```
::::::::::::::
cordic.scfix.cpp
::::::::::::::
//*****************************************************************************
//  Test of SystemC Fixpoint CORDIC
//
//  Licensing:
//    This code is distributed under GNU LGPL license.
//
//  Modified:
//    2012.07.05
//
//  Author:
//    Based on SCLive 3.0 and www.asic-world.com example codes
//
//    Modifications by Young W. Lim
//
//
//*****************************************************************************


#define SC_INCLUDE_FX

#include <systemc.h>
#include <iostream>
#include <iomanip>

#include "cordic.hpp"

int sc_main(int argc, char * argv[]) {

  double pi = 3.141592653589793;
  double K = 1.646760258121;
  int nIter = 10;

  double x, y, z;


  //-----------------------------------------------------------------------------
  // printf ("\nGrinding on [K, 0, 0]\n");
  // Circular (X0C, 0L, 0L);
  //-----------------------------------------------------------------------------
  x = 1 / K;
  y = 0.0;
  z = 0.0;
  cout << "-----------------------------------------------\n"
       << "xi=" << x << " yi=" << y << " zi=" << z << "\n";

  cordic(&x, &y, &z, nIter);

  cout  << "xo=" << x << " yo=" << y << " zo=" << z << "\n";


  //-----------------------------------------------------------------------------
  // printf ("\nGrinding on [K, 0, pi/6] -> [0.86602540, 0.50000000, 0]\n");
  // Circular (X0C, 0L, HalfPi / 3L);
  //-----------------------------------------------------------------------------
  x = 1 / K;
  y = 0.0;
  z = pi / 6.0;
  cout << "-----------------------------------------------\n"
       << "xi=" << x << " yi=" << y << " zi=" << z << "\n";

  cordic(&x, &y, &z, nIter);

  cout  << "xo=" << x << " yo=" << y << " zo=" << z << "\n";



  //-----------------------------------------------------------------------------
```

```
  // printf ("\nGrinding on [K, 0, pi/4] -> [0.70710678, 0.70710678, 0]\n");
  // Circular (X0C, 0L, HalfPi / 2L);
  //-----------------------------------------------------------------------------
  x = 1 / K;
  y = 0.0;
  z = pi / 4.0;
  cout << "-----------------------------------------------\n"
       << "xi=" << x << " yi=" << y << " zi=" << z << "\n";

  cordic(&x, &y, &z, nIter);

  cout  << "xo=" << x << " yo=" << y << " zo=" << z << "\n";



  //-----------------------------------------------------------------------------
  // printf ("\nGrinding on [K, 0, pi/3] -> [0.50000000, 0.86602540, 0]\n");
  // Circular (X0C, 0L, 2L * (HalfPi / 3L));
  //-----------------------------------------------------------------------------
  x = 1 / K;
  y = 0.0;
  z = pi / 3.0;
  cout << "-----------------------------------------------\n"
       << "xi=" << x << " yi=" << y << " zi=" << z << "\n";

  cordic(&x, &y, &z, nIter);

  cout  << "xo=" << x << " yo=" << y << " zo=" << z << "\n";







  return (0);



}
::::::::::::::
cordic.cpp
::::::::::::::
# include <cstdlib>
# include <iostream>
# include <iomanip>
# include <cmath>
# include <ctime>

using namespace std;

# include "cordic.hpp"

#define SC_INCLUDE_FX

#include <systemc.h>


#define FIXPT


//****************************************************************************80

void cordic ( double *x, double *y, double *z, int n )

//****************************************************************************80
//  CORDIC returns the sine and cosine using the CORDIC method.
//
//  Licensing:
```

```
//
//    This code is distributed under the GNU LGPL license.
//
//  Modified:
//
//    2012.04.17
//
//  Author:
//
//    Based on MATLAB code in a Wikipedia article.
//
//    Modifications by John Burkardt
//
//    Further modified by Young W. Lim
//
//  Parameters:
//
//    Input:
//      *x: x coord of an init vector
//      *y: y coord of an init vector
//      *z: angle (-90 <= angle <= +90)
//       n: number of iteration
//         A value of 10 is low.  Good accuracy is achieved
//         with 20 or more iterations.
//
//    Output:
//      *xo: x coord of a final vector
//      *yo: y coord of a final vector
//      *zo: angle residue
//
//  Local Parameters:
//
//    Local, real ANGLES(60) = arctan ( (1/2)^(0:59) );
//
//    Local, real KPROD(33), KPROD(j) = product ( 0 <= i <= j ) K(i),
//    K(i) = 1 / sqrt ( 1 + (1/2)^(2i) ).
//
//
{
# define ANGLES_LENGTH 60
# define KPROD_LENGTH 33

#ifdef FIXPT
  double angle;
  double angles[ANGLES_LENGTH] = {
#else
  sc_fixed<32, 3> angle;
  sc_fixed<32, 3> angles[ANGLES_LENGTH] = {
#endif
    7.8539816339744830962E-01,
    4.6364760900080611621E-01,
    2.4497866312686415417E-01,
    1.2435499454676143503E-01,
    6.2418809995957348474E-02,
    3.1239833430268276254E-02,
    1.5623728620476830803E-02,
    7.8123410601011112965E-03,
    3.9062301319669718276E-03,
    1.9531225164788186851E-03,
    9.7656218955931943040E-04,
    4.8828121119489827547E-04,
    2.4414062014936176402E-04,
    1.2207031189367020424E-04,
    6.1035156174208775022E-05,
    3.0517578115526096862E-05,
    1.5258789061315762107E-05,
    7.6293945311019702634E-06,
    3.8146972656064962829E-06,
    1.9073486328101870354E-06,
    9.5367431640596087942E-07,
```

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    4.76837158203088859 93E-07,
    2.38418579101557982 49E-07,
    1.19209289550780685 31E-07,
    5.96046447753905544 14E-08,
    2.98023223876953036 77E-08,
    1.49011611938476551 47E-08,
    7.45058059692382798 71E-09,
    3.72529029846191404 53E-09,
    1.86264514923095702 91E-09,
    9.31322574615478515 36E-10,
    4.65661287307739257 78E-10,
    2.32830643653869628 90E-10,
    1.16415321826934814 45E-10,
    5.82076609134674072 26E-11,
    2.91038304567337036 13E-11,
    1.45519152283668518 07E-11,
    7.27595761418342590 33E-12,
    3.63797880709171295 17E-12,
    1.81898940354585647 58E-12,
    9.09494701772928237 92E-13,
    4.54747350886464118 96E-13,
    2.27373675443232059 48E-13,
    1.13686837721616029 74E-13,
    5.68434188608080148 70E-14,
    2.84217094304040074 35E-14,
    1.42108547152020037 17E-14,
    7.10542735760100185 87E-15,
    3.55271367880050092 94E-15,
    1.77635683940025046 47E-15,
    8.88178419700125232 34E-16,
    4.44089209850062616 17E-16,
    2.22044604925031308 08E-16,
    1.11022302462515654 04E-16,
    5.55111512312578270 21E-17,
    2.77555756156289135 11E-17,
    1.38777878078144567 55E-17,
    6.93889390390722837 76E-18,
    3.46944695195361418 88E-18,
    1.73472347597680709 44E-18 };

  int j;

#ifdef FIXPT
  double factor;
  double kprod[KPROD_LENGTH] = {
#else
  sc_fixed <32, 3> factor;
  sc_fixed <32, 3> kprod[KPROD_LENGTH] = {
#endif
    0.70710678118654752440,
    0.63245553203367586640,
    0.61357199107789634961,
    0.60883391251775242102,
    0.60764825625616820093,
    0.60735177014129595905,
    0.60727764409352599905,
    0.60725911229889273006,
    0.60725447933256232972,
    0.60725332108987516334,
    0.60725303152913433540,
    0.60725295913894481363,
    0.60725294104139716351,
    0.60725293651701023413,
    0.60725293538591350073,
    0.60725293510313931731,
    0.60725293503244577146,
    0.60725293501477238499,
    0.60725293501035403837,
    0.60725293500924945172,
    0.60725293500897330506,
```

```
    0.60725293500890426839,
    0.60725293500888700922,
    0.60725293500888269443,
    0.60725293500888161574,
    0.60725293500888134606,
    0.60725293500888127864,
    0.60725293500888126179,
    0.60725293500888125757,
    0.60725293500888125652,
    0.60725293500888125626,
    0.60725293500888125619,
    0.60725293500888125617 };

#ifdef FIXPT
  double pi = 3.141592653589793;
  double poweroftwo;
  double sigma;
  double sign_factor;
  double theta;

  double xn, yn;
#else
  sc_fixed<32, 3> pi = 3.141592653589793;
  sc_fixed<32, 3> poweroftwo;
  sc_fixed<32, 3> sigma;
  sc_fixed<32, 3> sign_factor;
  sc_fixed<32, 3> theta;

  sc_fixed<32, 3> xn, yn;

#endif

//
//  Initialize loop variables:
//
  theta = *z;

  xn = *x;
  yn = *y;

  poweroftwo = 1.0;
  angle = angles[0];

//
//  Iterations
//
  for ( j = 1; j <= n; j++ )
  {
    if ( theta < 0.0 )
    {
      sigma = -1.0;
    }
    else
    {
      sigma = 1.0;
    }

    factor = sigma * poweroftwo;

    *x =          xn - factor * yn;
    *y = factor * xn +          yn;

    xn = *x;
    yn = *y;


//
//  Update the remaining angle.
//
    theta = theta - sigma * angle;
```

```
    poweroftwo = poweroftwo / 2.0;
//
//  Update the angle from table, or eventually by just dividing by two.
//
    if ( ANGLES_LENGTH < j + 1 )
    {
      angle = angle / 2.0;
    }
    else
    {
      angle = angles[j];
    }

    *z = theta;
  }
//
//  Adjust length of output vector to be [cos(beta), sin(beta)]
//
//  KPROD is essentially constant after a certain point, so if N is
//  large, just take the last available value.
//
//   if ( 0 < n )
//   {
//     *c = *c * kprod [ i4_min ( n, KPROD_LENGTH ) - 1 ];
//     *s = *s * kprod [ i4_min ( n, KPROD_LENGTH ) - 1 ];
//   }
//
//  Adjust for possible sign change because angle was originally
//  not in quadrant 1 or 4.
//
//   *c = sign_factor * *c;
//   *s = sign_factor * *s;

  return;
# undef ANGLES_LENGTH
# undef KPROD_LENGTH
}
```