Correlation (1A)

•

Copyright (c) 2011 Young W. Lim.
Permission is granted to copy, distribute and/or modify this document under the terms of the GNU Free Documentation License, Version 1.2 or any later version published by the Free Software Foundation; with no Invariant Sections, no Front-Cover Texts, and no Back-Cover Texts. A copy of the license is included in the section entitled "GNU Free Documentation License".
Please send corrections (or suggestions) to youngwlim@hotmail.com.
This document was produced by using OpenOffice and Octave.

Probability Density Function

Probability Density Function
$$f(x; t) = \frac{\partial}{\partial x} F(x; t)$$

$$P[a \leq X(t) \leq b] = \int_a^b f(x; t) dx$$

$$F(x; t) = \int_{-\infty}^{x} f(x; t) dx$$

Cumulative Distribution Function
$$F(x; t) = \int_{-\infty}^{x} f(x; t) dx$$

$$P[X(t) \leq b] = \int_{-\infty}^{b} f(x; t) dx = F(b; t)$$

$$\begin{array}{c}
X(t) \\
f(x;t)
\end{array}$$

X(t) random variable X(t) at a given time t

f(x, t) The probability density function of random variable X(t)

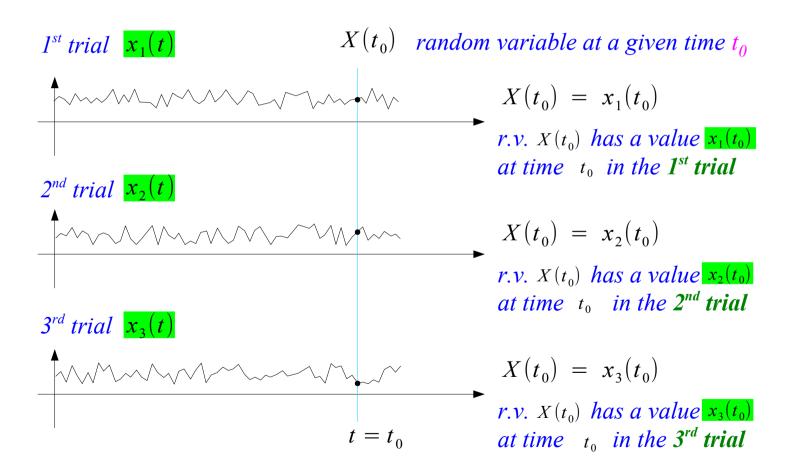
$$P[x \le X(t) \le x + dt] = f(x; t) dx$$
$$P[X(t) = x] \Rightarrow f(x; t)$$

$$\begin{array}{c|cccc}
r.v. & X(t_0) \\
 & b \\
 & a \\
\hline
 & t = t_0
\end{array}$$

Probability Density Function

$$X(t)$$
 random variable $X(t)$ at a given time t
 $f(x;t)$ The probability density function of random variable $X(t)$

$$P[x \le X(t) \le x + dt] = f(x; t) dx$$
$$P[X(t) = x] \Rightarrow f(x; t)$$



Joint Probability Density Function

Joint Probability Density Function
$$f(x_1, x_2; t_1, t_2) = \frac{\partial^2}{\partial x_1 \partial x_2} F(x_1, x_2; t_1, t_2)$$

$$P[\{a \le X(t_1) \le b\} \cap \{c \le X(t_2) \le d\}] = \int_a^b \int_c^d f(x_1, x_2; t_1, t_2) dx_1 dx_2$$

Joint Cumulative Distribution Function
$$F(x_1, x_2; t_1, t_2) = \int_{-\infty}^{x_1} \int_{-\infty}^{x_2} f(x_1, x_2; t_1, t_2) dx_1 dx_2$$

$$P\big[\left\{X(t_1) \leq b\right\} \ \cap \ \left\{X(t_2) \leq d\right\}\big] \ = \ \int_{-\infty}^{b} \int_{-\infty}^{d} f(x_1, x_2; \ t_1, t_2) \ dx_1 \ dx_2 \ = \ F(b, d; \ t_1, t_2)$$

 $X(t_1)$, $X(t_2)$ random variables at time t_1 and t_2

 $f(x_1, x_2; t_1, t_2)$ joint probability density function

$$P[\{X(t_1) = x_1\} \cap \{X(t_2) = x_2\}]$$

$$\Rightarrow f(x_1, x_2; t_1, t_2)$$

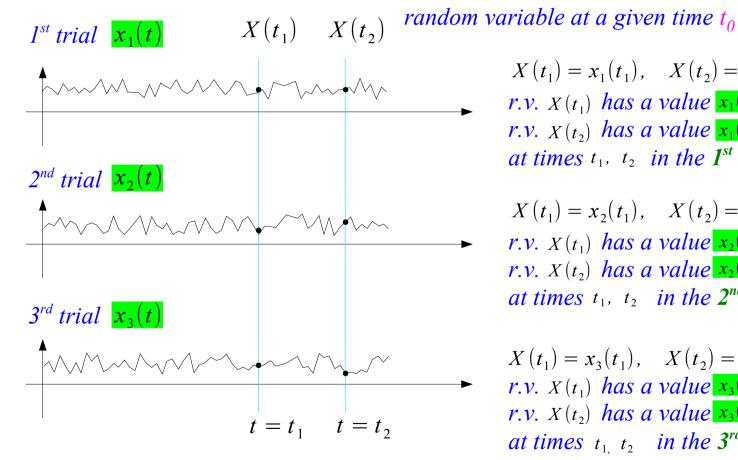
Probability Density Function

$$X(t_1)$$
, $X(t_2)$ random variables at time t_1 and t_2

$$f(x_1, x_2; t_1, t_2)$$
 joint probability density function

$$P[\{X(t_1) = x_1\} \cap \{X(t_2) = x_2\}]$$

$$\Rightarrow f(x_1, x_2; t_1, t_2)$$



$$X(t_1) = x_1(t_1), \quad X(t_2) = x_1(t_2)$$

$$r.v. \ X(t_1) \ has \ a \ value \ \frac{x_1(t_1)}{x_1(t_2)}$$

$$r.v. \ X(t_2) \ has \ a \ value \ \frac{x_1(t_2)}{x_1(t_2)}$$

$$at \ times \ t_1, \ t_2 \ in \ the \ 1^{st} \ trial$$

$$X(t_1) = x_2(t_1)$$
, $X(t_2) = x_2(t_2)$
 $r.v. \ X(t_1)$ has a value $x_2(t_1)$
 $r.v. \ X(t_2)$ has a value $x_2(t_2)$
at times t_1 , t_2 in the 2^{nd} trial

$$X(t_1) = x_3(t_1)$$
, $X(t_2) = x_3(t_2)$
 $r.v. \ X(t_1)$ has a value $x_3(t_1)$
 $r.v. \ X(t_2)$ has a value $x_3(t_2)$
at times t_1 , t_2 in the 3^{rd} trial

Moments of a Random Process

The n-th Moment

$$E[X^{n}(t)] = \int_{-\infty}^{+\infty} x^{n} f(x;t) dx$$

1st Moment

$$E[X(t)] = \int_{-\infty}^{+\infty} x f(x;t) dx$$
$$= \mu(t)$$

2nd Moment

$$E[X^{2}(t)] = \int_{-\infty}^{+\infty} x^{2} f(x; t) dx$$

The n-th Central Moment

$$E[(X(t) - \mu(t))^n] = \int_{-\infty}^{+\infty} (x - \mu(t))^n f(x; t) dx$$

1st <u>Central</u> Moment

$$E[(X(t) - \mu(t))] = \int_{-\infty}^{+\infty} (x - \mu(t)) f(x; t) dx$$

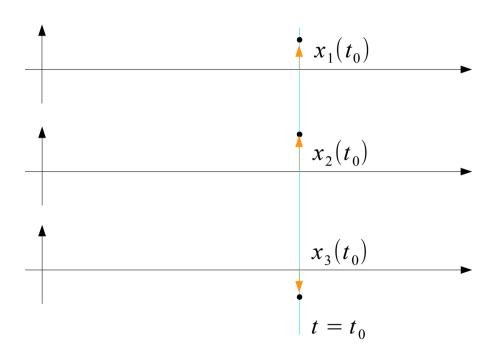
2nd Central Moment

$$E[(X(t) - \mu(t))^{2}] = \int_{-\infty}^{+\infty} (x - \mu(t))^{2} f(x; t) dx$$
$$= \sigma^{2}(t)$$

Moments of a Random Process

- X(t) Random Variable at a given time t
- $x_i(t)$ outcome of ith realization at a given time t

Ensemble



$$E[X(t_0)] = \int_{-\infty}^{+\infty} x f(x; t_0) dx = \mu(t_0)$$

Ensemble Average

$$\bar{x}(t) = \frac{1}{N} \sum_{n=1}^{N} x_n(t)$$

$$N \to \infty$$

$$E[X(t)] = \int_{-\infty}^{+\infty} x f(x;t) dx$$

$$= \mu(t)$$

Stationarity

First-Order Stationary Process

$$f(x_1; t_1) = f(x_1; t_1+k) \qquad \forall k$$
$$f(x; t) \Rightarrow f(x)$$

Second-Order Stationary Process

$$\begin{split} f\left(x_{1}\;,x_{2}\;;\;\;t_{1}\;,t_{2}\right) &=\; f\left(x_{1}\;,x_{2}\;;\;\;t_{1}\!+\!k\;,t_{2}\!+\!k\right) \qquad \forall\, k \\ \\ f\left(x_{1}\;,x_{2}\;;\;\;t_{1}\;,t_{2}\right) &=\; f\left(x_{1}\;,x_{2}\;;\;\;0,\;t_{2}\!-\!t_{1}\right) \qquad k = -t_{1} \\ \\ f\left(x_{1}\;,x_{2}\;;\;\;t_{1}\;,t_{2}\right) &\Rightarrow\; f\left(x_{1}\;,x_{2}\;;\;\;t_{2}\!-\!t_{1}\right) \end{split}$$

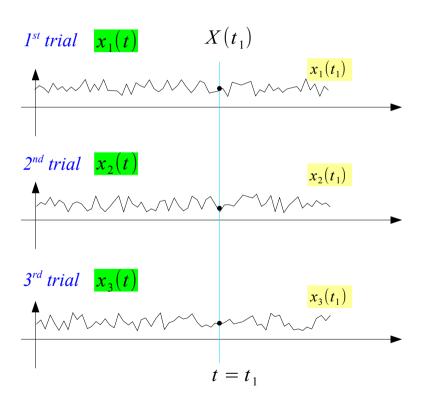
Nth-Order Stationary Process

$$f(x_1, x_2, \dots, x_n; t_1, t_2, \dots, t_n) = f(x_1, x_2, \dots, x_n; t_1+k, t_2+k, \dots, t_n+k) \quad \forall k$$

Mean Function

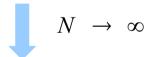
Mean Function

$$\mu_{x}(t) = E[X(t)]$$



Ensemble Average

$$\overline{x(t)} = \frac{1}{N} \sum_{n=1}^{N} x_n(t)$$



$$E[X(t)] = \int_{-\infty}^{+\infty} x f(x;t) dx$$
$$= \mu(t)$$

First Order Stationary Process

The n-th Moment

The n-th Central Moment

$$E[X^{n}(t)] = \int_{-\infty}^{+\infty} x^{n} f(x;t) dx$$

$$E\left[X^{n}(t)\right] = \int_{-\infty}^{+\infty} x^{n} f(x;t) dx \qquad E\left[\left(X(t) - \mu(t)\right)^{n}\right] = \int_{-\infty}^{+\infty} (x - \mu(t))^{n} f(x;t) dx$$



$$f(x,t) \Rightarrow f(x)$$

 $f(x,t) \Rightarrow f(x)$ if **f** does not change with time



$$E[X^n(t)] \Rightarrow E[X^n]$$

$$E[(X(t) - \mu(t))^n] \Rightarrow E[(X - \mu)^n]$$

First Order Stationary Process



$$E[X(t)] \Rightarrow E[X] = \mu$$

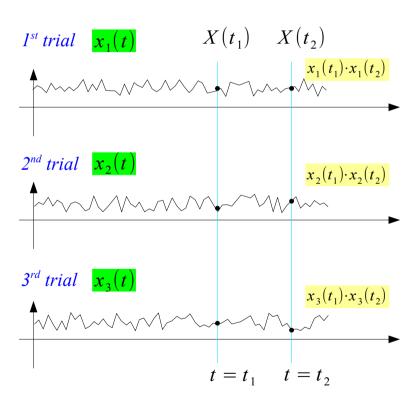


$$E[(X(t) - \mu(t))^2] \Rightarrow E[(X - \mu)^2] = \sigma^2$$

AutoCorrelation Functions

Auto-correlation Function

$$R_{xx}(t_1, t_2) = E[\underline{X(t_1)} \underline{X(t_2)}]$$



Ensemble Average

$$\overline{x(t_1)x(t_2)} = \frac{1}{N} \sum_{n=1}^{N} x_n(t_1) \cdot x_n(t_2)$$

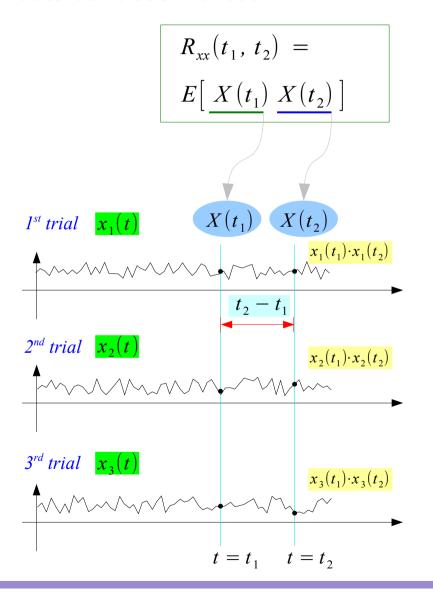
$$N \to \infty$$

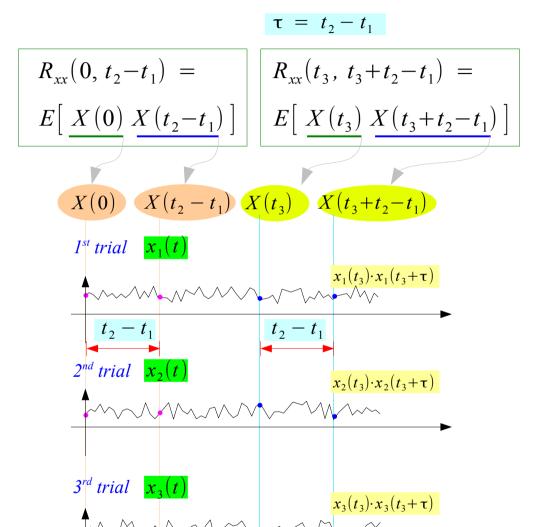
$$E[X(t_1)X(t_2)] = R_{xx}(t_1, t_2)$$

$$= \int_{-\infty}^{+\infty} x_1 x_2 f(x_1, x_2; t_1, t_2) dx_1 dx_2$$

AutoCorrelation Function Examples

auto-correlation function





 $t = t_2 - t_1$ $t = t_3$ $t = t_3 + t_2 - t_1$

Second Order Stationary Process

auto-correlation function

$$R_{xx}(t_1, t_2) = E\left[\underline{X(t_1)} \underline{X(t_2)}\right]$$



2nd Order Stationary Process

$$f(x_1, x_2; t_1, t_2) \Rightarrow f(x_1, x_2; t_2 - t_1)$$

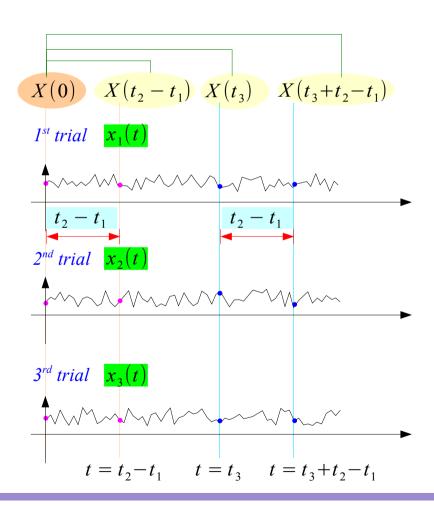
$$\begin{split} R_{xx}(t_1, t_2) &= R_{xx}(0, t_2 - t_1) = R_{xx}(t_3, t_3 + t_2 - t_1) = \\ E\big[\, \underline{X(t_1)} \, \, \underline{X(t_2)} \, \big] = E\big[\, \underline{X(0)} \, \, \underline{X(t_2 - t_1)} \, \big] = \\ E\big[\, \underline{X(t_3)} \, \, \underline{X(t_3 + t_2 - t_1)} \, \big] \\ \Rightarrow R_{xx}(t_1 - t_2) = R_{xx}(\tau) \qquad \tau = t_2 - t_1 \end{split}$$

$$R_{xx}(\tau) = E[\underline{X(t)} \underline{X(t+\tau)}]$$

$$R_{xx}(t_3+t_2-t_1) = E[\underline{X(0)} \underline{X(t_3+t_2-t_1)}]$$

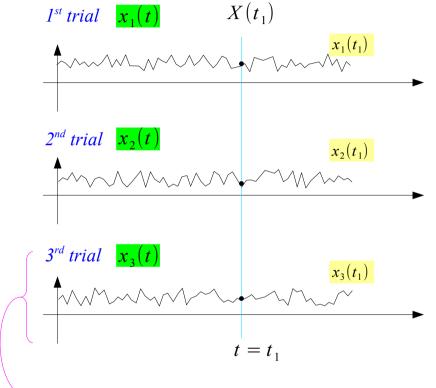
$$R_{xx}(t_3) = E[\underline{X(0)} \underline{X(t_3)}]$$

$$R_{xx}(t_2-t_1) = E[\underline{X(0)} X(t_2-t_1)]$$



Time Average & Mean

mean function



Time Average

$$\lim_{T\to\infty}\frac{1}{T}\int_{0}^{T}x(t)\,dt = \mu_{x}$$



Ensemble Average

$$\overline{x(t)} = \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} x_n(t)$$

$$E[X(t)] = \int_{-\infty}^{+\infty} x f(x;t) dx = \mu(t)$$

Stationary Process

$$\mu(t) = const$$

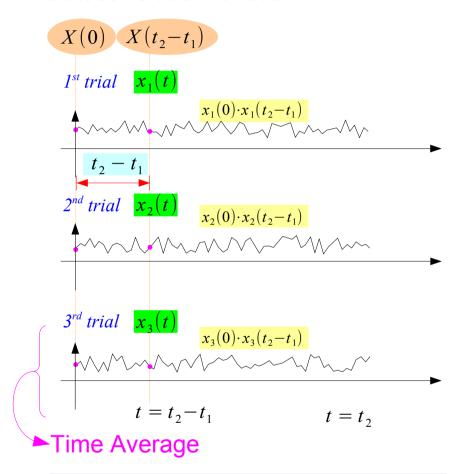


Ergodic Process

$$\mu(t) = \mu_x$$

Time Average & AutoCorrelation

autocorrelation function



$$\lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} x(t)x(t+t_{2}-t_{1}) dt$$

Ensemble Average

$$\overline{x(t_1)x(t_2)} = \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} x_n(t_1) \cdot x_n(t_2)$$

$$E[X(t_1)X(t_2)] = R_{xx}(t_1, t_2)$$

Stationary Process

$$E[X(t_1)X(t_2)] = R_{xx}(t_2-t_1)$$



Ergodic Process

$$R_{xx}(\tau) = \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} x(t)x(t+\tau) dt$$

Time Average & Ensemble Average

autocorrelation function

Ensemble Average

Time Average

Time Average & Ensemble Average

autocorrelation function

Ensemble Average

Moving Average Filter

Matched Filter

Correlation Functions (1)

auto-covariance function

$$C_{xx}(t_1, t_2) = E\left[\left(\underline{X(t_1) - \mu_x(t_1)}\right) \left(\underline{X(t_2) - \mu_x(t_2)}\right)\right]$$

$$C_{xx}(t_2 - t_1) = E[(X(t_1) - \mu_x(t_1)) (X(t_2) - \mu_x(t_2))]$$

$$C_{xx}(\tau) = E[(X(t) - \mu_x) (X(t+\tau) - \mu_x)]$$

auto-correlation function

$$R_{xx}(t_{1,} t_{2}) = E\left[\underline{X(t_{1})} \underline{X(t_{2})}\right]$$

$$R_{xx}(\tau) = E[X(t)X(t+\tau)]$$

Correlation Functions (2)

cross-covariance function

$$C_{xy}(t_1, t_2) = E[(X(t_1) - \mu_x(t_1)) (Y(t_2) - \mu_y(t_2))]$$

$$C_{xy}(\tau) = E[(X(t) - \mu_x) (Y(t+\tau) - \mu_y)]$$

cross-correlation function

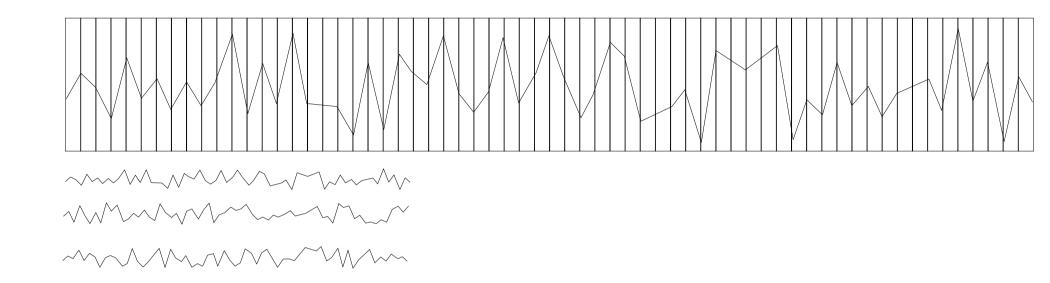
$$R_{xy}(t_{1,} t_{2}) = E\left[\underline{X(t_{1})} \underline{Y(t_{2})}\right]$$

$$R_{xy}(\tau) = E[X(t) Y(t+\tau)]$$

Ergodicity

$$\begin{split} \mu_{x} &= \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} x(t) \, dt \\ \hat{\mu}_{x} &= \frac{1}{T} \int_{0}^{T} x(t) \, dt = \bar{x} \\ \bar{\psi}_{x}^{2} &= \frac{1}{T} \int_{0}^{T} x^{2}(t) \, dt = \bar{x}^{2} \\ C_{xy}(\tau) &= E \big[\left(X(t) - \mu_{x} \right) \left(Y(t + \tau) - \mu_{y} \right) \big] \\ C_{xy}(\tau) &= \lim_{T \to 0} \frac{1}{T} \int_{0}^{T} \left(x(t) - \mu_{x} \right) \left(y(t + \tau) - \mu_{y} \right) \, dt \\ \hat{C}_{xy}(\tau) &= \frac{1}{T - \tau} \int_{0}^{T - \tau} \left(x(t) - \bar{x} \right) \left(y(t + \tau) - \bar{y} \right) \, dt \quad 0 \leq \tau < T \\ \hat{C}_{xy}(\tau) &= \frac{1}{T - |\tau|} \int_{0}^{T - |\tau|} \left(x(t) - \bar{x} \right) \left(y(t + \tau) - \bar{y} \right) \, dt \quad -T < \tau \leq 0 \end{split}$$

Time Average



Frequency Response

$$y(t) = h(t) * x(t) = \int_{-\infty}^{+\infty} h(\tau) x(t - \tau) d\tau$$

$$x(t) \qquad h(t) \qquad y(t)$$

$$\delta(t) \qquad h(t) \qquad h(t)$$

$$A e^{j\Phi} e^{j\omega t} \qquad h(t) \qquad H(j\omega) A e^{j\Phi} e^{j\omega t}$$

$$single frequency component : \omega \qquad component : \omega$$

$$H(j\omega) = \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega\tau} d\tau$$

References

- [1] http://en.wikipedia.org/
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003
- [3] K.H. Shin, J.K. Hammond, Fundamentals of Signal Processing for Sound and Vibration Engineers, Wiley, 2008