

# Vector Functions (1A)

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- Vector Functions
- Motion
- Curvature

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# Vector Valued Functions

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Set of points  $(x, y, z)$

Parametric functions  $x = f(t)$      $y = g(t)$      $x = h(t)$

$$(x, y, z) \rightarrow (f(t), g(t), h(t))$$

Vector Valued Function  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$

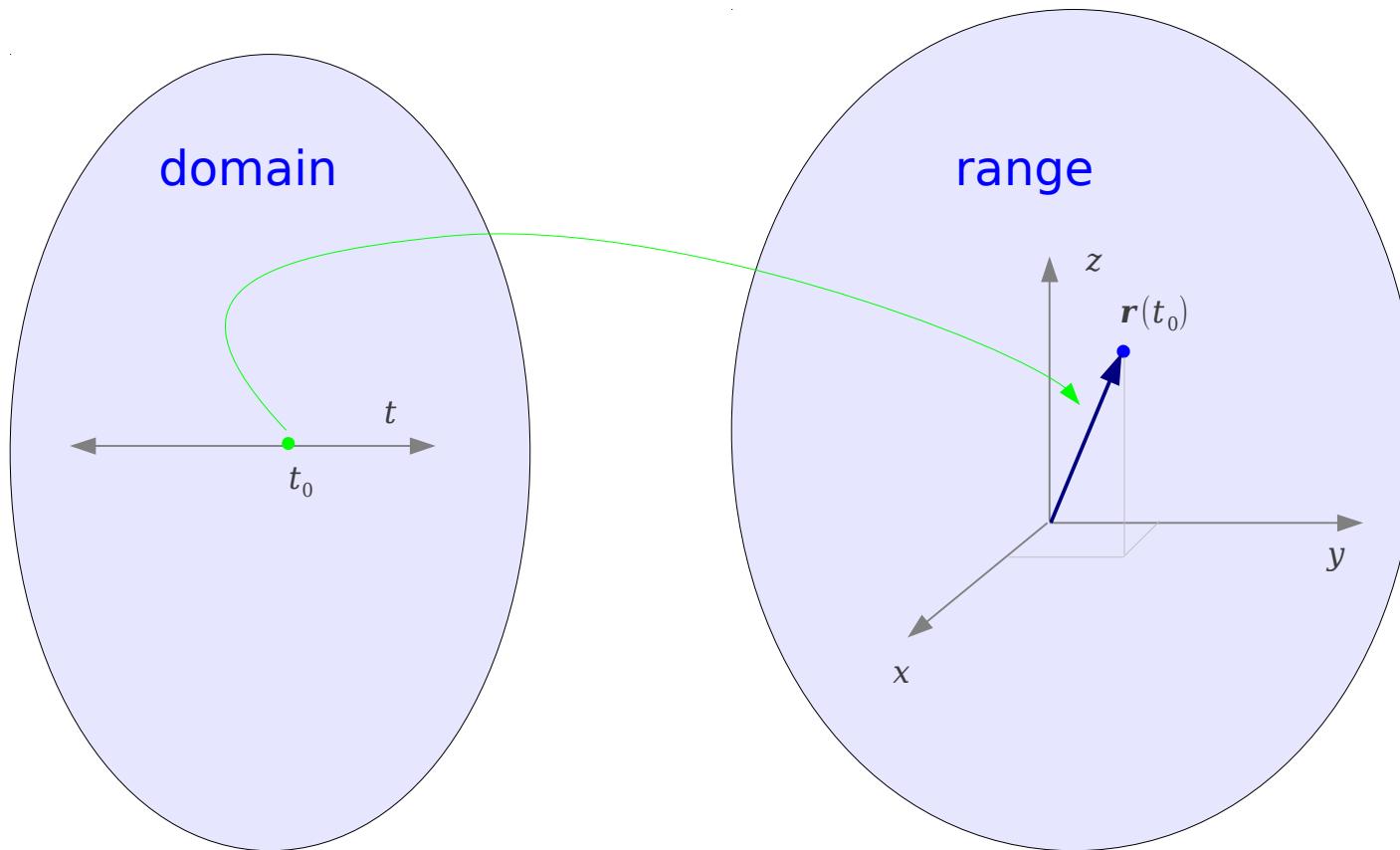
$$= f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

# Vector Valued Functions (1)

Vector Valued Function

$$\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$$

$$= f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

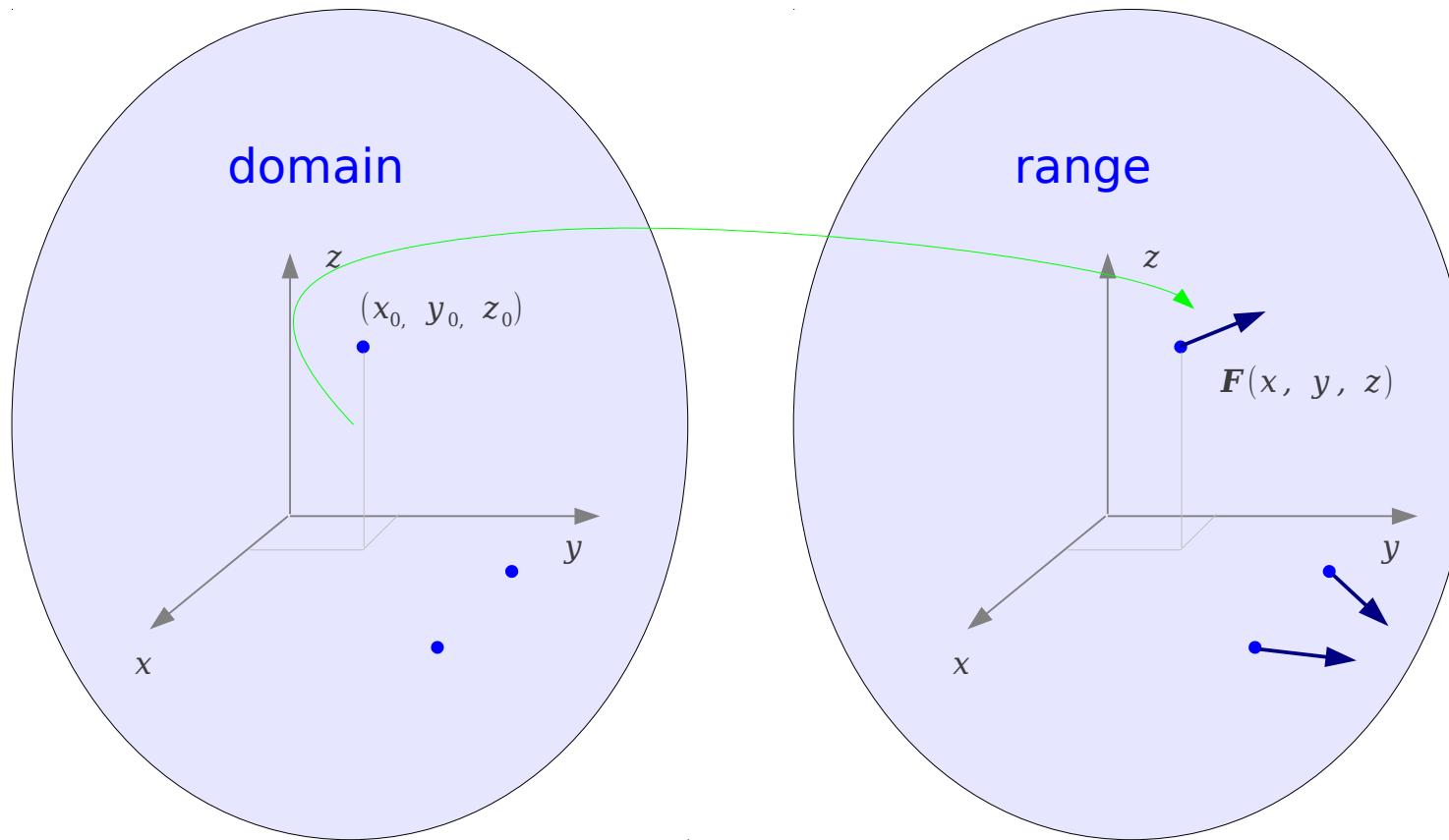


# Vector Valued Functions (2)

Vector Field

$(x, y, z)$

$\mathbf{F}(x, y, z)$



# Limit of a Vector Function

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Vector Valued Function       $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$

Limit of a Vector Valued Function

$$\lim_{t \rightarrow a} \mathbf{r}(t) = \left\langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \right\rangle$$

Limit of a Vector Valued Function

$\mathbf{r}(a)$  is defined

$\lim_{t \rightarrow a} \mathbf{r}(t)$  exists

$$\mathbf{r}(a) = \lim_{t \rightarrow a} \mathbf{r}(t)$$

# Derivative of a Vector Function

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Vector Valued Function

$$\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$$

Derivative of a Vector Valued Function

$$\mathbf{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t}$$

$$\mathbf{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

# Arc Length (1)

Vector Valued Function

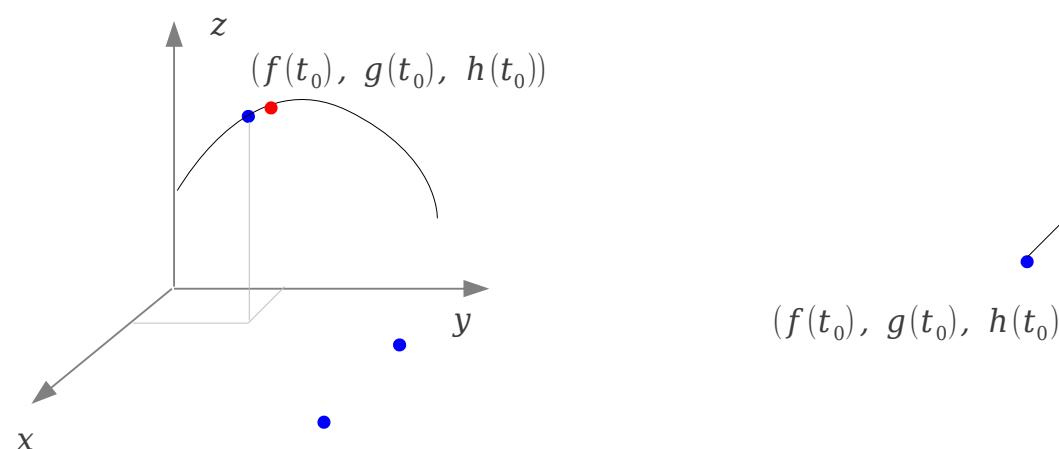
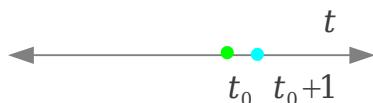
$$\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$$

Derivative of a Vector Valued Function

$$\mathbf{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t}$$

$$\mathbf{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

$$(f(t_0+1), g(t_0+1), h(t_0+1))$$



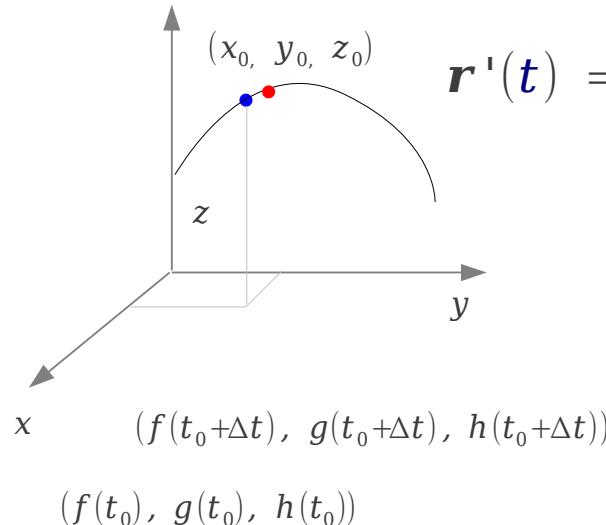
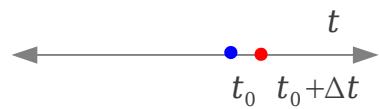
# Arc Length (2)

Vector Valued Function

$$\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$$

Derivative of a Vector Valued Function

$$\mathbf{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

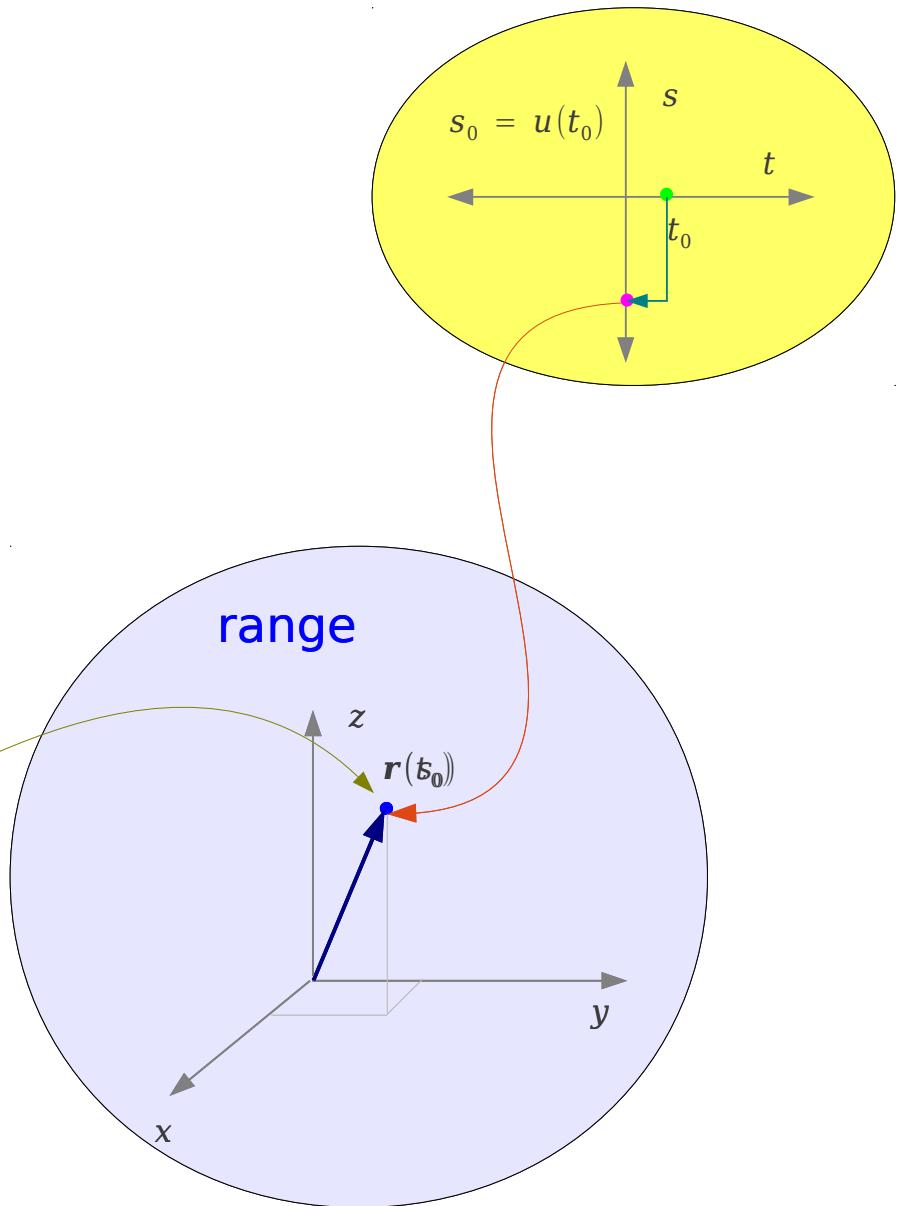
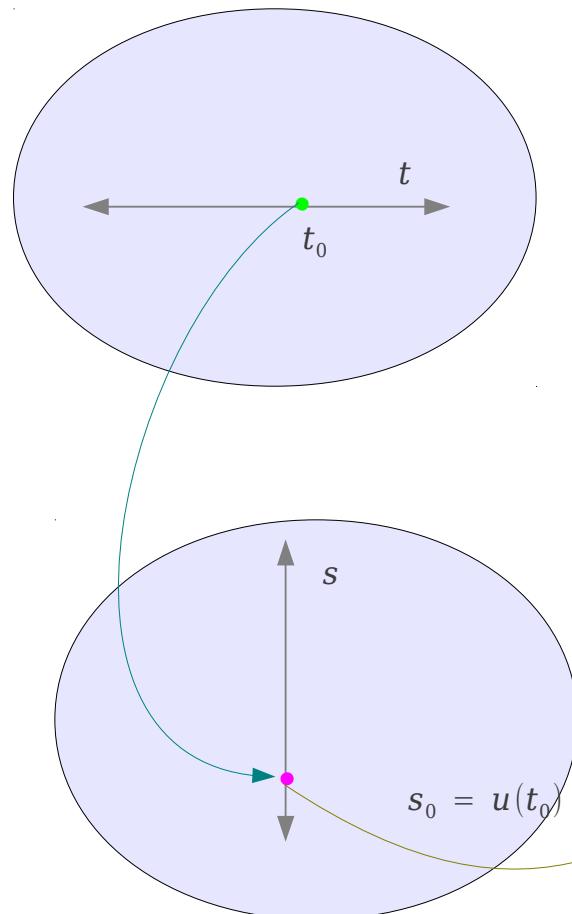


$$\mathbf{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t}$$

Arc Length

$$\begin{aligned}s &= \int_a^b \sqrt{[f'(t)]^2 + [g'(t)]^2 + [h'(t)]^2} dt \\&= \int_a^b \|\mathbf{r}'(t)\| dt\end{aligned}$$

# Composite Function



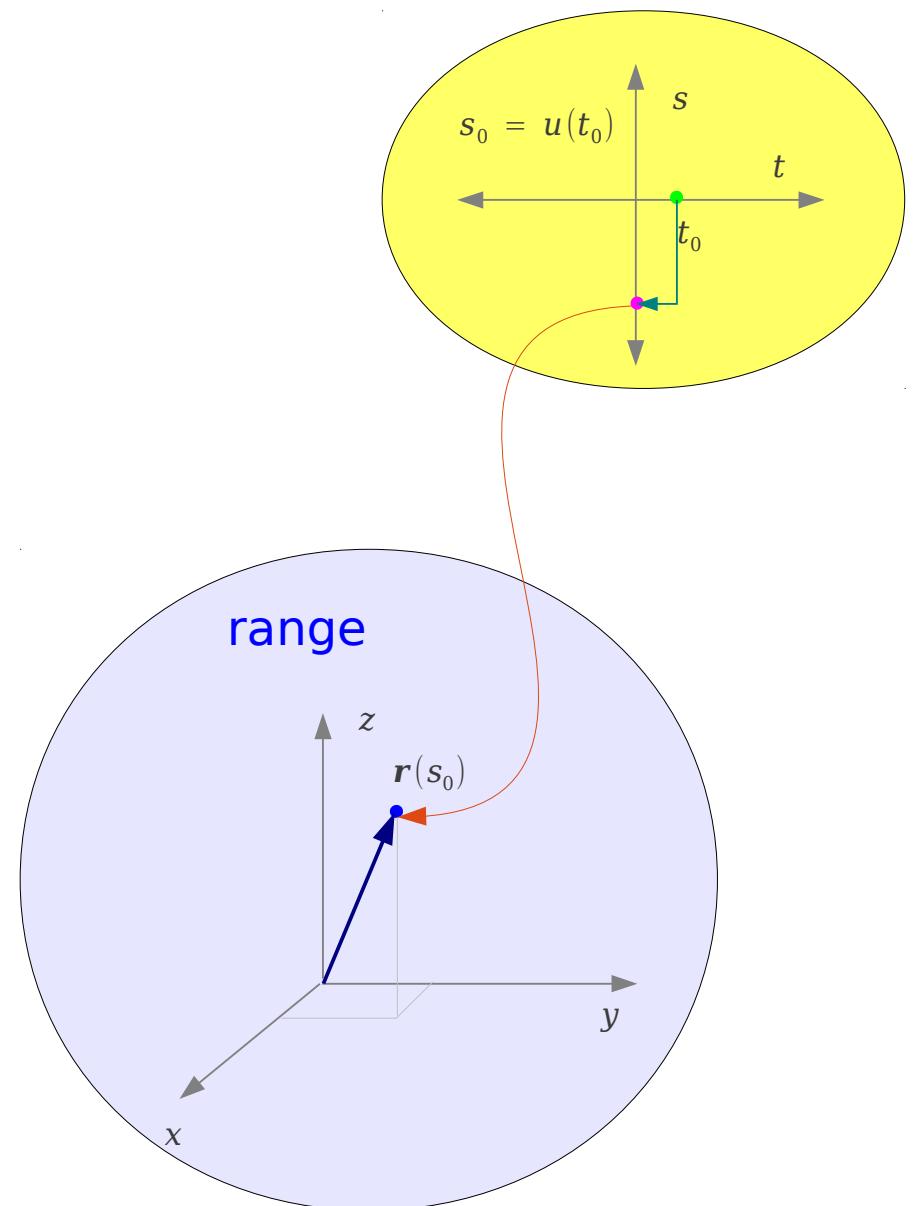
# Chain Rule of a Vector Function (1)

Derivative of a Vector Valued Function

$$s = u(t)$$

$$\frac{ds}{dt} = \frac{du(t)}{dt} \quad \rightarrow \quad u'(t)$$

$$\frac{dr}{dt} = \frac{dr}{ds} \frac{ds}{dt} = r'(s)u'(t)$$



# Chain Rule of a Vector Function (2)

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Vector Valued Function

$$\mathbf{r}(s) = \langle f(s), g(s), h(s) \rangle$$

Scalar Function

$$s = u(t)$$

$$\mathbf{r}(u(t)) = \langle f(u(t)), g(u(t)), h(u(t)) \rangle$$

Derivative of a Vector Valued Function

$$s = u(t)$$

$$\frac{ds}{dt} = \frac{du(t)}{dt} \quad \rightarrow \quad u'(t)$$

$$\frac{d\mathbf{r}}{dt} = \frac{d\mathbf{r}}{ds} \frac{ds}{dt} = \mathbf{r}'(s)u'(t)$$

# Integration of a Vector Function

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Vector Valued Function

$$\mathbf{r}(\mathbf{t}) = \langle f(\mathbf{t}), g(\mathbf{t}), h(\mathbf{t}) \rangle$$

$$= f(\mathbf{t})\mathbf{i} + g(\mathbf{t})\mathbf{j} + h(\mathbf{t})\mathbf{k}$$

Limit of a Vector Valued Function

$$\int \mathbf{r}(\mathbf{t}) dt = \left\langle \int f(\mathbf{t}) dt, \int g(\mathbf{t}) dt, \int h(\mathbf{t}) dt \right\rangle$$

$$= \int f(\mathbf{t}) dt \mathbf{i} + \int g(\mathbf{t}) dt \mathbf{j} + \int h(\mathbf{t}) dt \mathbf{k}$$

# Integration of a Vector Function

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Vector Valued Function

$$\mathbf{r}(\mathbf{t}) = f(\mathbf{t})\mathbf{i} + g(\mathbf{t})\mathbf{j} + h(\mathbf{t})\mathbf{k}$$

Displacement

$$\mathbf{v}(\mathbf{t}) = \mathbf{r}'(\mathbf{t}) = f'(\mathbf{t})\mathbf{i} + g'(\mathbf{t})\mathbf{j} + h'(\mathbf{t})\mathbf{k}$$

acceleration

$$\mathbf{a}(\mathbf{t}) = \mathbf{v}'(\mathbf{t}) = \mathbf{r}''(\mathbf{t}) = f''(\mathbf{t})\mathbf{i} + g''(\mathbf{t})\mathbf{j} + h''(\mathbf{t})\mathbf{k}$$

Speed

$$\|\mathbf{v}(\mathbf{t})\| = \left\| \frac{\mathbf{r}(\mathbf{t})}{d\mathbf{t}} \right\| = \|f'(\mathbf{t})\mathbf{i} + g'(\mathbf{t})\mathbf{j} + h'(\mathbf{t})\mathbf{k}\|$$

$$= \sqrt{(f'(\mathbf{t}))^2 + (g'(\mathbf{t}))^2 + (h'(\mathbf{t}))^2}$$

$$= \sqrt{\left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2 + \left( \frac{dz}{dt} \right)^2}$$

# Unit Tangent of a Vector Function

Vector Valued Function

$$\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

Displacement

$$\mathbf{v}(t) = \mathbf{r}'(t) = f'(t)\mathbf{i} + g'(t)\mathbf{j} + h'(t)\mathbf{k}$$

Unit Tangent

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$$

Arc length

$$s \rightarrow \frac{d\mathbf{r}}{dt} = \frac{d\mathbf{r}}{ds} \frac{ds}{dt}$$

velocity

- speed
- direction

Unit Tangent

$$\frac{d\mathbf{r}}{ds} = \frac{\frac{d\mathbf{r}}{dt}}{\frac{ds}{dt}} = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \mathbf{T}(t)$$

direction

speed

# Curvature of a Vector Function (1)

Vector Valued Function

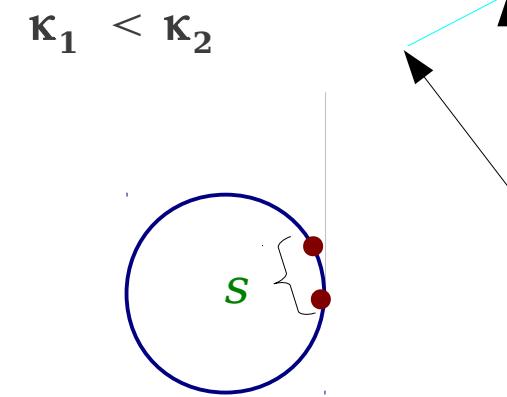
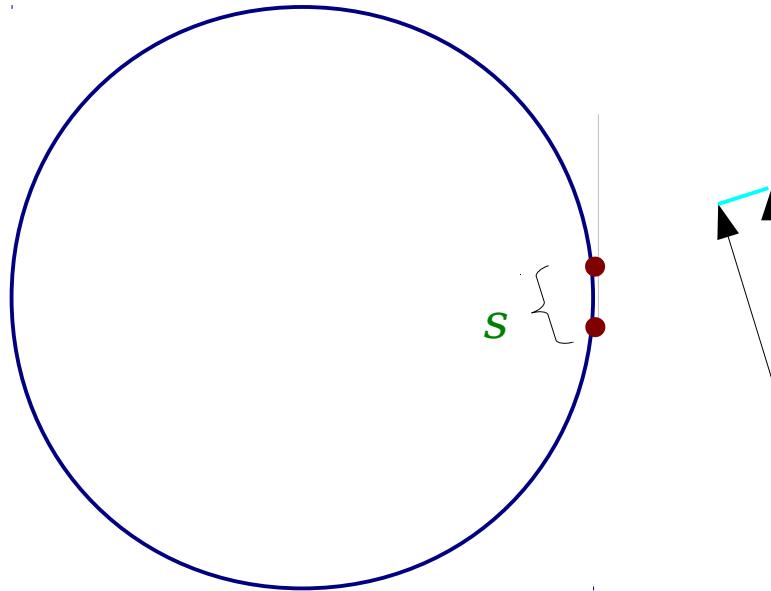
$$\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

Unit Tangent

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{d\mathbf{r}}{ds}$$

Curvature

$$\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\|$$



# Curvature of a Vector Function (2)

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Vector Valued Function

$$\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

Unit Tangent

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{d\mathbf{r}}{ds}$$

Curvature

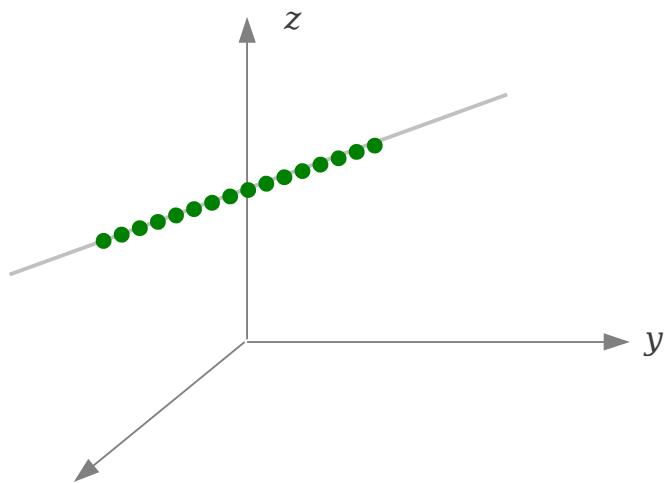
$$\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\|$$

Arc length  $s$

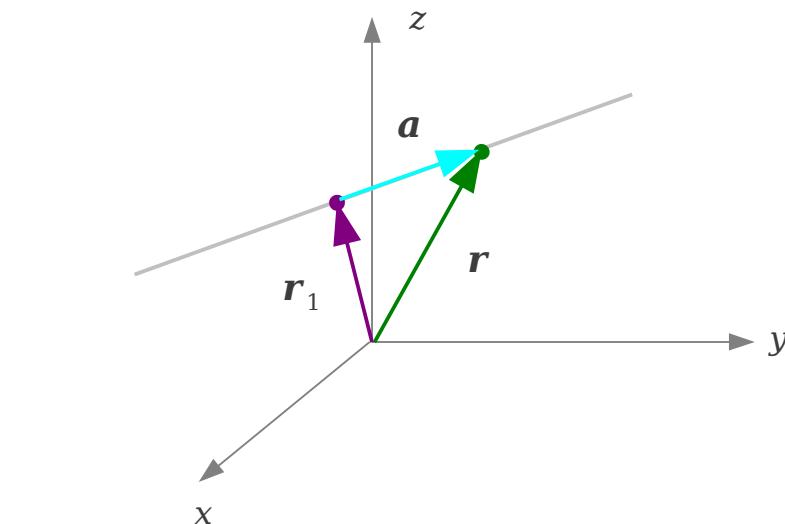
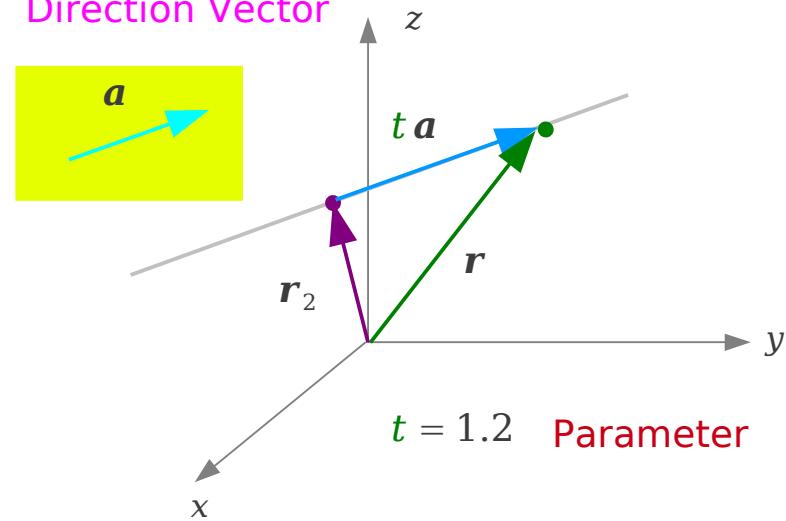
$$\frac{d\mathbf{T}}{dt} = \frac{d\mathbf{T}}{ds} \frac{ds}{dt}$$

$$\frac{d\mathbf{T}}{ds} = \frac{\frac{d\mathbf{T}}{dt}}{\frac{ds}{dt}} = \frac{\mathbf{T}'(t)}{\|\mathbf{r}'(t)\|} = \kappa(t)$$

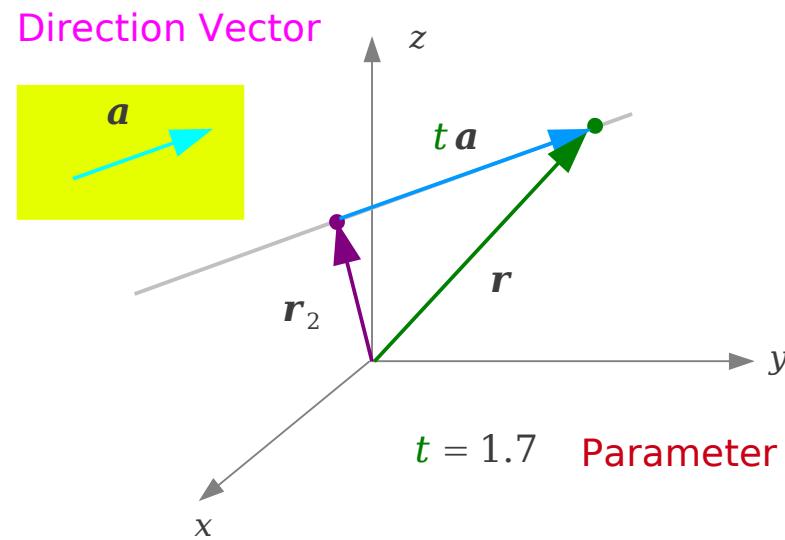
# Line Equations (2)



Direction Vector



Direction Vector



## References

- [1] <http://en.wikipedia.org/>
- [2] <http://planetmath.org/>
- [3] M.L. Boas, "Mathematical Methods in the Physical Sciences"
- [4] D.G. Zill, "Advanced Engineering Mathematics"