# MPI

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### The Butterfly Swap Operations

Communicators and Groups defines collection of processes that may communicate with each other.

Need to specify a communicator as an argument.

MPI\_COMM\_WORLD - predefined communicator that includes all of your MPI processes.

Within a communicator, every process has its own unique, integer identifier, called rank or "task ID".

Used to specify the source and destination. Also can be used in conditional statements.

### MPI\_Alltoall

MPI\_Alltoall - Sends data from all to all processes

int MPI\_Alltoall( void \*sendbuf, int sendcount, MPI\_Datatype sendtype, void \*recvbuf, int recvcnt, MPI\_Datatype recvtype, MPI\_Comm comm )

INPUT PARAMETERS sendbuf - starting address of send buffer (choice) sendcounts - integer array equal to the group size specifying the number of elements to send to each processor sendtype - data type of send buffer elements (handle) recvcounts - integer array equal to the group size specifying the maximum number of elements that can be received from each processor recvtype - data type of receive buffer elements (handle) comm - communicator (handle)

OUTPUT PARAMETERS recvbuf - address of receive buffer (choice) MPI\_Alltoallv - Sends data from all to all processes, with a displacement

int MPI\_Alltoallv (void \*sendbuf, int \*sendcnts, int \*sdispls, MPI\_Datatype sendtype, void \*recvbuf, int \*recvcnts, int \*rdispls, MPI\_Datatype recvtype, MPI\_Comm comm )

INPUT PARAMETERS sendbuf - starting address of send buffer (choice) sendcounts - integer array equal to the group size specifying the number of elements to send to each processor sdispls - integer array (of length group size). Entry j specifies the displacement (relative to sendbuf from which to take the outgoing data destined for process j sendtype - data type of send buffer elements (handle) recvcounts - integer array equal to the group size specifying the maximum number of elements that can be received from each processor rdispls - integer array (of length group size). Entry i specifies the displacement (relative to recvbuf at which to place the incoming data from process recvtype - data type of receive buffer elements (handle) comm - communicator (handle)

OUTPUT PARAMETERS

recvbuf - address of receive buffer (choice)

Alltoallv flexibility in that the location of send data is specified by sdispls and the location of the placement of receive data is specified by rdispls.

The **jth block** sent from **process i** is received by **process j** and is placed in the **ith block**.

Need not be all the same size block

sendcount[j], sendtype at process i
recvcount[i], recvtype at process j.

The amount of data sent must be equal to the amount of data received, pairwise between every pair of processes.

Distinct type maps between sender and receiver are still allowed.

ALLTOALLW in MPI-2.

Can specify separately count, displacement, and datatype.

The displacement of blocks is specified in bytes.

Can be seen as a generalization several MPI functions depending on the input arguments.

For short messages

The message itself + supplementary info may be sent and stored at the receiver side In some buffer space without receiver's intervention

message envelope - length, sender, tag, etc

A matching receiver operation may not be needed But message must be copied from the intermediate buffer to the receive buffer

+Synchronization overhead is reduced

- May require large amount of preallocated buffer space
- Flooding a process with many eager messages may overflow  $\rightarrow$  contention

For large messages

Buffering the data makes no sense

The envelope is immediately stored at the receiver The actual message transfer blocks until the user's receive buffer is available

Extra data copy could be avoided, improving effective bandwidth, but sender and receiver must synchronize.

### **Communication Modes**

#### **Blocking**

#### Immediate

- Standard
- Buffered
- Synchronous
- Ready

- Standard
- Buffered
- Synchronous
- Ready

### Blocking

does not return until the message data and envelope have been safely stored away so that the sender is free to access and overwrite the send buffer.

The message might be copied directly into the matching receive buffer, or it might be copied into a temporary system buffer.

Message buffering decouples the send and receive operations.

A blocking send can complete as soon as the message was buffered, even if no matching receive has been executed by the receiver.

On the other hand, message buffering can be expensive, as it entails additional memory-to-memory copying, and it requires the allocation of memory for buffering.

MPI offers the choice of several communication modes that allow one to control the choice of the communication protocol.

#### **Standard Communication Mode**

It is up to MPI to decide whether outgoing messages will be buffered.

1) MPI may buffer outgoing messages.

 $\rightarrow$  the send call may complete before a matching receive is invoked.

2) Buffer space may be unavailable, or

MPI may choose not to buffer outgoing messages, for performance reasons.

 $\rightarrow$  the send call will not complete until a matching receive has been posted, and the data has been moved to the receiver.

Thus, a send in standard mode can be started whether or not a matching receive has been posted. It may complete before a matching receive is posted.

The standard mode send is non-local: successful completion of the send operation may depend on the occurrence of a matching receive.

### **Buffered Communication Mode**

A buffered mode send operation can be started whether or not a matching receive has been posted.

It may complete before a matching receive is posted.

However, unlike the standard send, this operation is **local**, and its completion does not depend on the occurrence of a matching receive.

Thus, if a send is executed and no matching receive is posted, then MPI must buffer the outgoing message, so as to allow the send call to complete.

An error will occur if there is insufficient buffer space. The amount of available buffer space is controlled by the user.

Buffer allocation by the user may be required for the buffered mode to be effective.

### Synchronous Communication Mode

A send that uses the synchronous mode can be started whether or not a matching receive was posted.

However, the send will complete successfully only if a matching receive is posted, and the receive operation has started to receive the message sent by the synchronous send.

Thus, the completion of a synchronous send not only indicates that the send buffer can be reused, but also indicates that the receiver has reached a certain point in its execution, namely that it has started executing the matching receive.

If both sends and receives are blocking operations then the use of the synchronous mode provides synchronous communication semantics: a communication does not complete at either end before both processes rendezvous at the communication.

A send executed in this mode is non-local.

### Ready Communication Mode

A send that uses the ready communication mode may be started only if the matching receive is already posted. Otherwise, the operation is erroneous and its outcome is undefined.

On some systems, this allows the removal of a hand-shake operation that is otherwise required and results in improved performance.

The completion of the send operation does not depend on the status of a matching receive, and merely indicates that the send buffer can be reused.

A send operation that uses the ready mode has the same semantics as a standard send operation, or a synchronous send operation;

it is merely that the sender provides additional information to the system (namely that a matching receive is already posted), that can save some overhead.

In a correct program, therefore, a ready send could be replaced by a standard send with no effect on the behavior of the program other than performance.

### NonBlocking Communication (1)

overlapping communication and computation light-weight threads vs nonblocking communication.

A nonblocking send (receive) start call initiates the send (receive) operation, but does not complete it.

The send (receive) start call will return before the message was copied out of (into) the send (receiver) buffer.

A separate send (receive) complete call is needed to complete the communication, i.e., to verify that the data has been copied out of the send buffer (received into the receive buffer).

With suitable hardware, the transfer of data out of the sender (receiver) memory may proceed concurrently with computations done at the sender (receiver) after the send (receive) was initiated and before it completed.

The use of nonblocking receives may also avoid system buffering and memory-to-memory copying, as information is provided early on the location of the receive buffer.

### NonBlocking Communication (2)

Nonblocking send start calls can use the same four modes as blocking sends: standard, buffered, synchronous and ready.

Sends of all modes, ready excepted, can be started whether or not a matching receive has been posted ;

a nonblocking ready send can be started only if a matching receive is posted.

In all cases, the send start call is local: it returns immediately, irrespective of the status of other processes.

If the call causes some system resource to be exhausted, then it will fail and return an error code. Quality implementations of MPI should ensure that this happens only in ``pathological'' cases. That is, an MPI implementation should be able to support a large number of pending nonblocking operations.

The send-complete call returns when data has been copied out of the send buffer. It may carry additional meaning, depending on the send mode.

If the send mode is **synchronous**, then the send can complete only if a matching receive has started. That is, a receive has been posted, and has been matched with the send. In this case, the send-complete call is non-local. Note that a synchronous, nonblocking send may complete, if matched by a nonblocking receive, before the receive complete call occurs. (It can complete as soon as the sender ``knows" the transfer will complete, but before the receiver ``knows" the transfer will complete.)

If the send mode is **buffered** then the message must be buffered if there is no pending receive. In this case, the send-complete call is local, and must succeed irrespective of the status of a matching receive.

If the send mode is **standard** then the send-complete call may return before a matching receive occurred, if the message is buffered. On the other hand, the send-complete may not complete until a matching receive occurred, and the message was copied into the receive buffer.

Nonblocking sends can be matched with blocking receives, and vice-versa.

## Send Modes (1)

#### **MPI\_Send**

MPI\_Send will not return until you can use the send buffer. It may or may not block (it is allowed to buffer, either on the sender or receiver side, or to wait for the matching receive).

#### **MPI\_Bsend**

May buffer; returns immediately and you can use the send buffer. A late add-on to the MPI specification. Should be used only when absolutely necessary.

#### MPI\_Ssend will not return until <u>matching receive</u> posted

MPI\_Rsend May be used ONLY if matching receive already posted. User responsible for writing a correct program.

# Send Modes (2)

#### **MPI\_Isend**

Nonblocking send. But not necessarily asynchronous.

You can NOT reuse the send buffer until either a successful, wait/test or you KNOW that the message has been received (see MPI\_Request\_free).

Note also that while the I refers to immediate, there is no performance requirement on MPI\_Isend. An immediate send must return to the user without requiring a matching receive at the destination. An implementation is free to send the data to the destination before returning, as long as the send call does not block waiting for a matching receive. Different strategies of when to send the data offer different performance advantages and disadvantages that will depend on the application.

#### MPI\_Ibsend

buffered nonblocking

#### **MPI\_Issend**

Synchronous nonblocking. Note that a Wait/Test will complete only when the matching receive is posted.

#### **MPI\_Irsend**

As with MPI\_Rsend, but nonblocking.

#### References

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