

Group Delay and Phase Delay (1A)

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Beat Signal

Very similar frequency signals

$$1.1 \text{ Hz} \quad \cos(2\pi * 1.1 * t)$$

$$0.9 \text{ Hz} \quad \cos(2\pi * 0.9 * t)$$

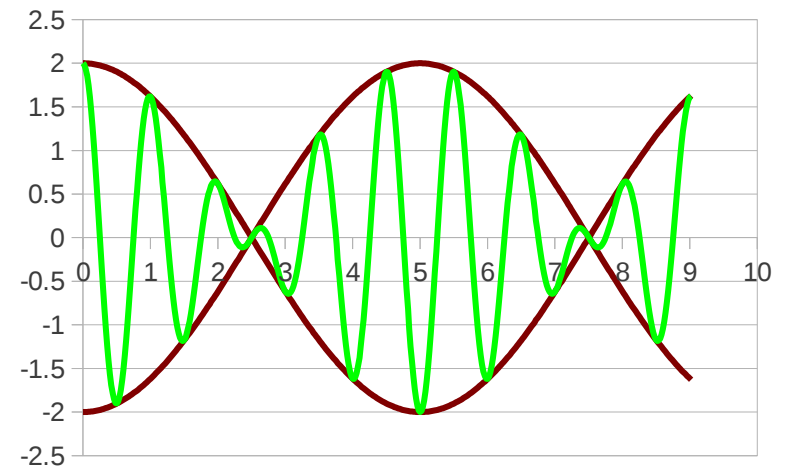
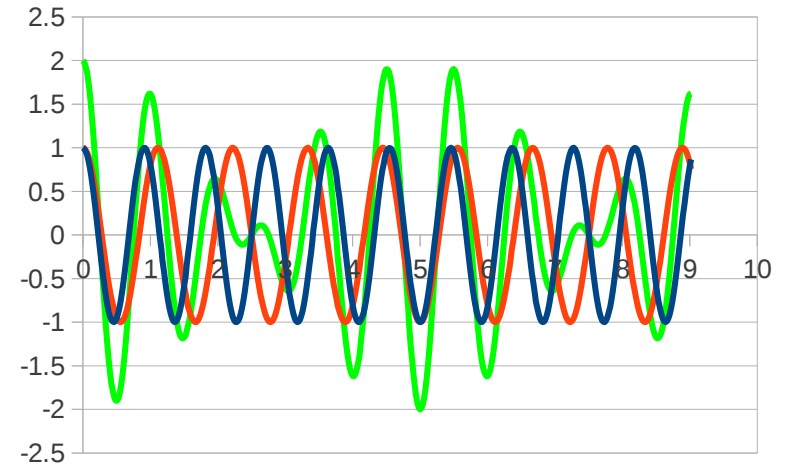
$$\cos(2\pi * 1.1 * t) + \cos(2\pi * 0.9 * t)$$

$$= \cos\left(2\pi * \frac{(1.1-0.9)}{2} * t\right) \cdot \cos\left(2\pi * \frac{(1.1+0.9)}{2} * t\right)$$

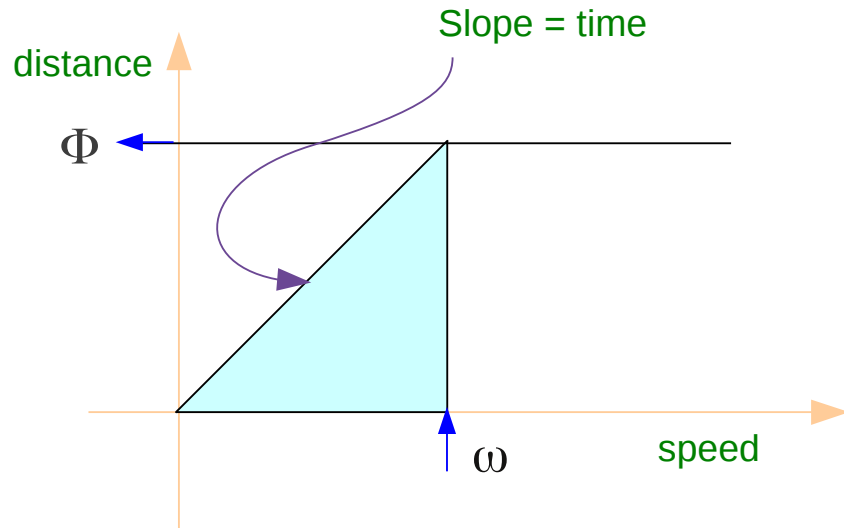
$$= \cos(2\pi * 0.1 * t) \cdot \cos(2\pi * 1.0 * t)$$

Slow
moving
envelop

Fast
moving
carrier

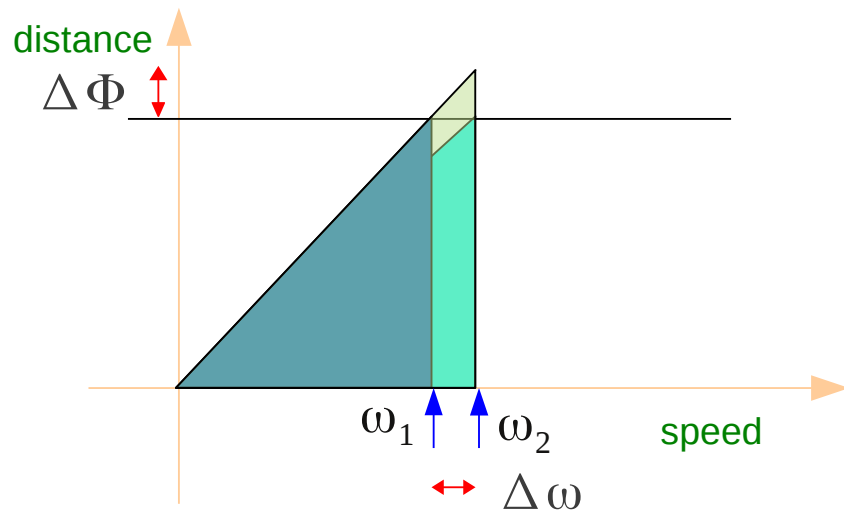


Angle and Angular Speed



$$\Phi = \omega \cdot t$$

$$t = \frac{\Phi}{\omega}$$



$$\Delta\Phi = \Delta\omega \cdot \Delta t$$

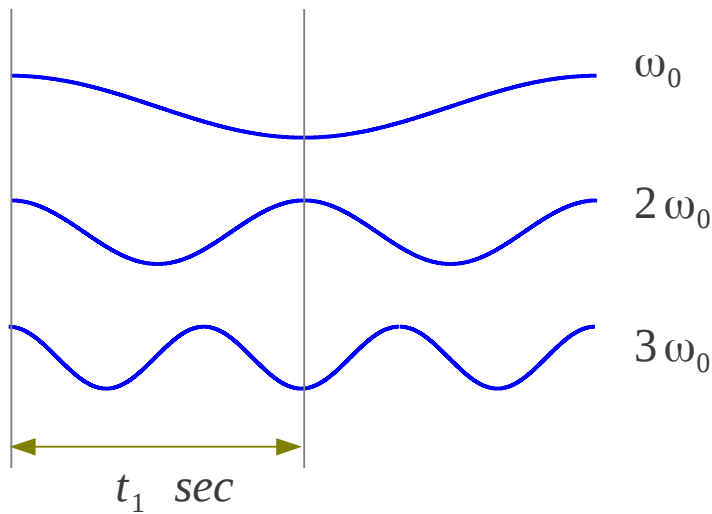
$$\Delta t = \frac{\Delta\Phi}{\Delta\omega}$$

Phase Shift and Time Shift

measure phase shift not in second
But *in portions* of a cosine wave cycle
within phase change in one cycle

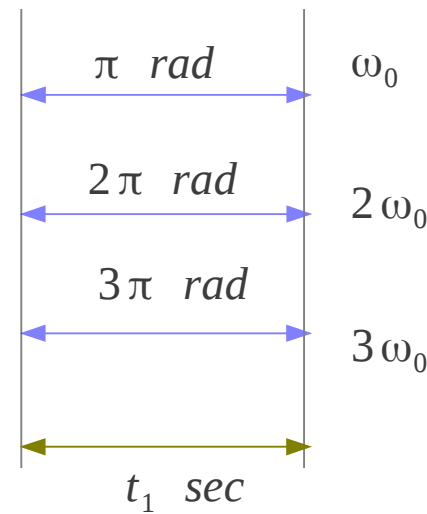
Phase Shift \longrightarrow in radians, degrees
Delay \longrightarrow in seconds (time)

Given time shift (delay)



The same delay
applied to all frequencies

The actual phase shift is different
According to the frequency

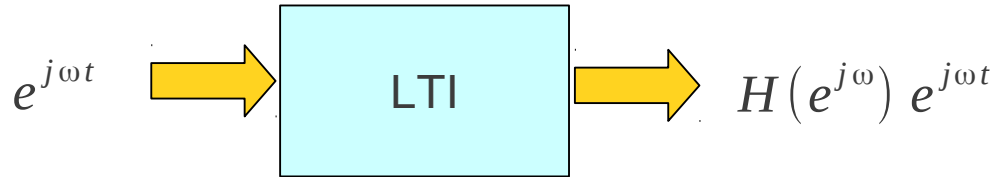


The different phase shift
to the different frequency



Frequency Response

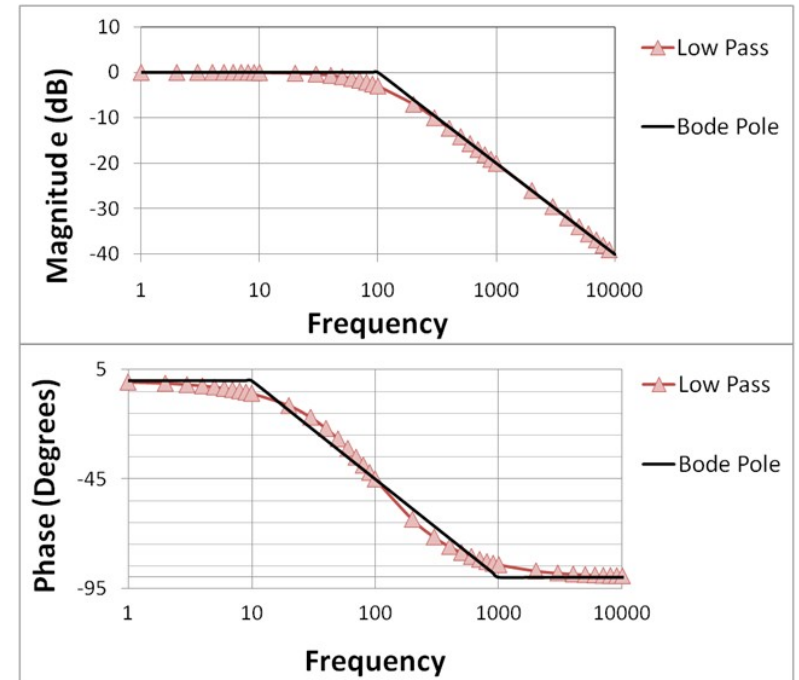
Frequency Response $H(e^{j\omega})$



$|H(e^{j\omega})|$ Magnitude Response

$\angle H(e^{j\omega})$ Phase Response

LPF example



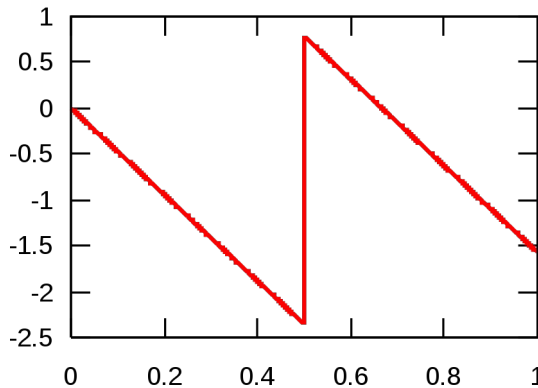
Linear Phase System

Linear Phase System

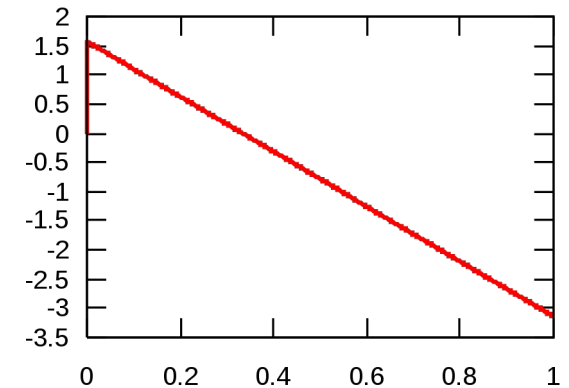
Phase Shift \propto Frequency

$$\angle H(e^{j\omega}) \propto \omega$$

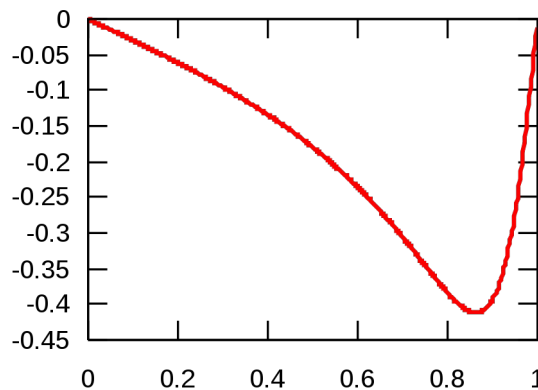
a) FIR Filter (Type II) having Linear Phase



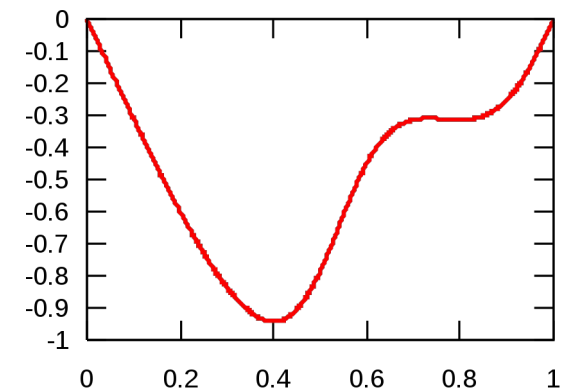
b) FIR Filter (Type IV) having Linear Phase



c) IIR Filter having Non-Linear Phase

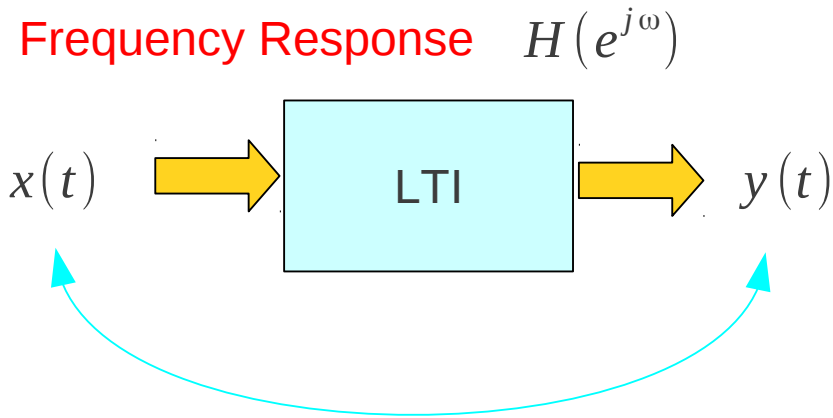


d) FIR Filter having Non-Linear Phase

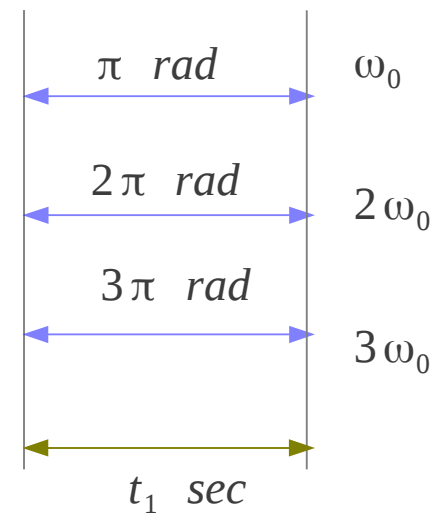
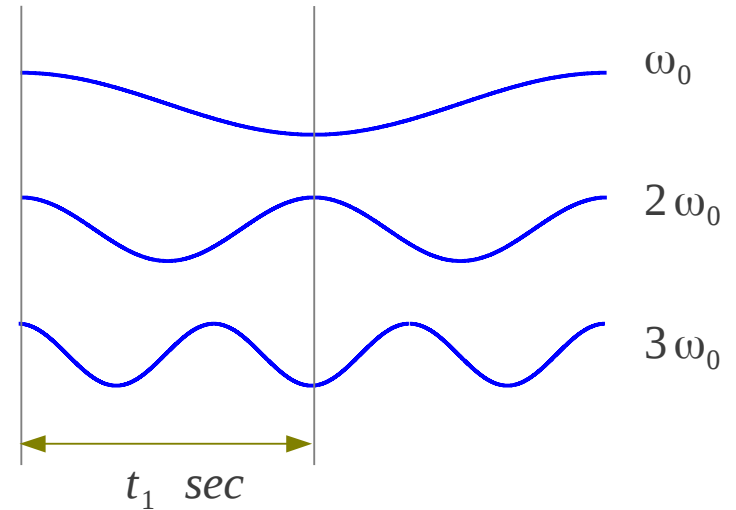
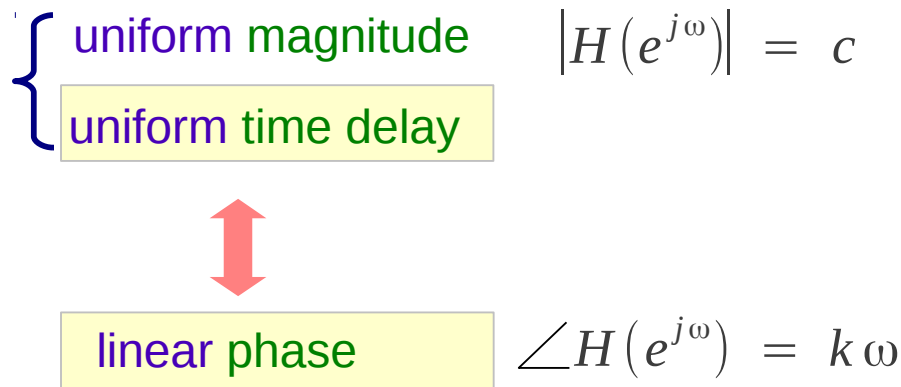


Non-Linear Phase System

Uniform Time Delay (1)



The waveform shape can be preserved.

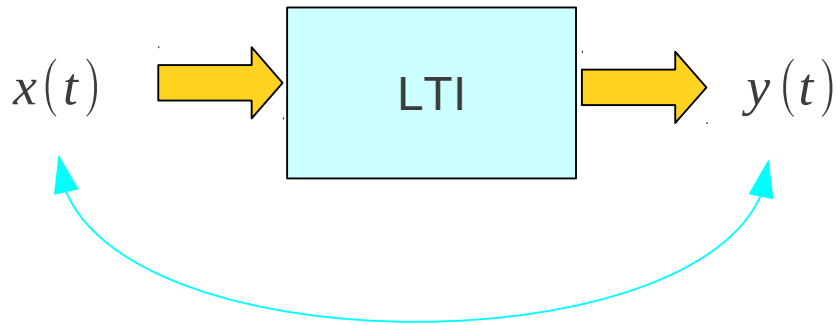


Uniform Time Delay

Group Delay & Phase Delay \rightarrow Could remove delay from the phase response

Uniform Time Delay (2)

Frequency Response $H(e^{j\omega})$



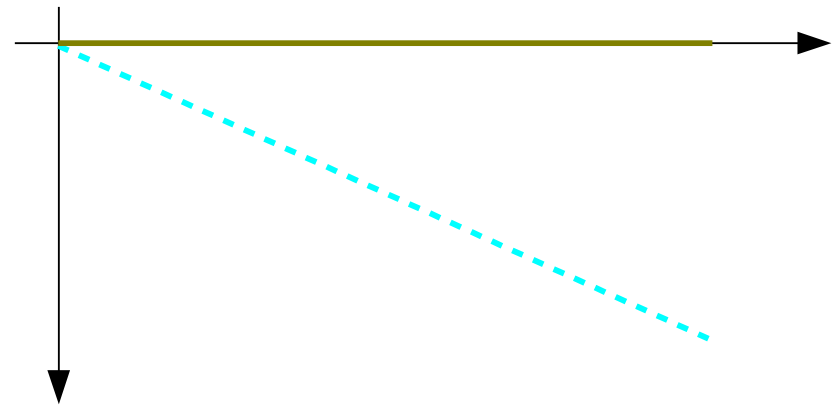
The waveform shape can be preserved.

$\left\{ \begin{array}{l} \text{uniform magnitude} \\ \text{uniform time delay} \end{array} \right. \quad |H(e^{j\omega})| = c$

$\text{linear phase} \quad \angle H(e^{j\omega}) = k\omega$

Uniform Time Delay

Could remove delay from the phase response to achieve a horizontal line at zero degree (No delay)

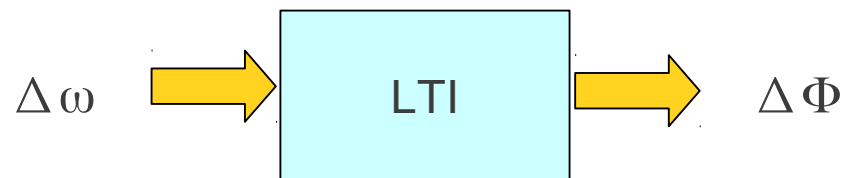


Group Delay

Consider the cosine components at *closely spaced frequencies* and *their phase shifts* in relation to each other

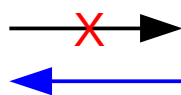


Group Delay:
The phase shift changes for *small changes in frequency*



A uniform, waveform preserving phase response → linear

Constant Group Delay



Uniform Time Delay (linear phase)

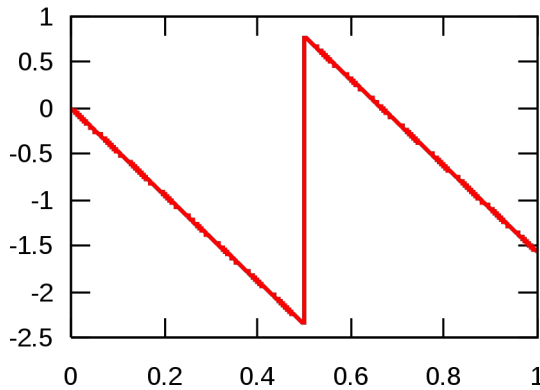
Group Delay (2)

Linear Phase System

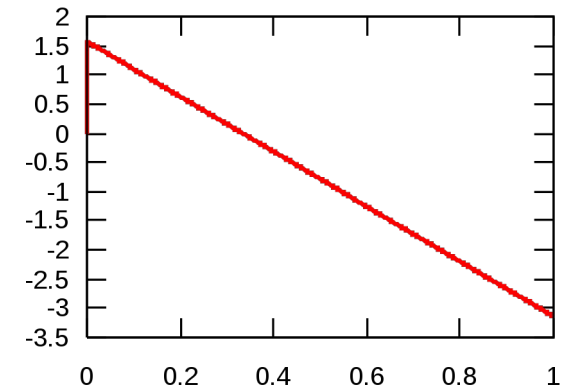
Phase Shift \propto Frequency

$$\angle H(e^{j\omega}) \propto \omega$$

a) FIR Filter (Type II) having Linear Phase

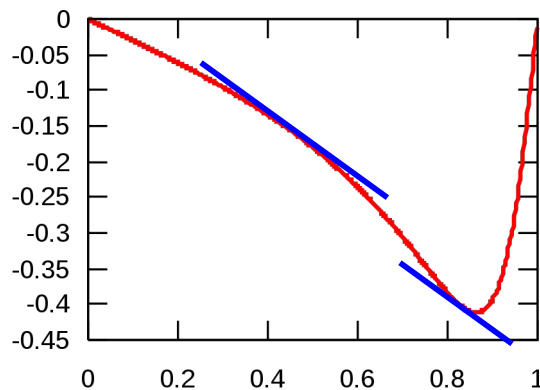


b) FIR Filter (Type IV) having Linear Phase

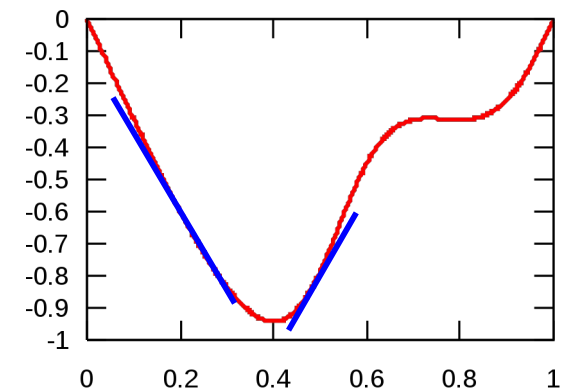


Non-Linear Phase System

c) IIR Filter having Non-Linear Phase



d) FIR Filter having Non-Linear Phase



Group Delay

References

- [1] <http://en.wikipedia.org/>
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003
- [3] <http://www.libinst.com/tpfd.htm>