# Magnetic Sensor (3A)

Magnetic Sensor TypeMagnetic Sensor Characteristics

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### Magnetic Sensor Type – Physical Effect

| Physical Effect                                  | Magnetic Sensor Type  |  |
|--|---|--|
| Hall Effect                                      | Hall Effect Sensor  |  |
| Magnetoresistance (MR)<br>(MR)                   | MR sensor   |  |
|  | AMR (Anisotropic MR) sensor                                   |  |
|  | GMR (Giant MR) sensor   |  |
| Josephson Effect +<br>Magnetic Flux Quantization | Superconducting Quantum Interference<br>Device (SQUID) sensor |  |

### Magnetic Sensor Type – Magnetic Field

| Magnetic Field        | Characteristics        | Туре                          |
|-----------------------|------------------------|-------------------------------|
| Low<br>(~1µG)         | Medical, Military      | SQUID, search coil            |
| Medium<br>(1µG ~ 10G) | Earth's field sensor   | Fluxgate, MI, AMR             |
| High<br>(10G~)        | Using permanent magnet | Reed switch, MR, GMR,<br>Hall |

The transport of electrons through an electrical device is affected by the presence of an external magnetic field. (deflected electrons)

#### Hall Effect:

• A charge build-up → voltage difference

#### **Magneto-resistance Effect:**

• Increasing current path length → increasing resistance

### **Josephson Effect:**

- DC Josephson: no voltage drop (I < I), resistive mode (I > I)
- AC Josephson: frequency is controlled by the voltage

### Magnetic Sensor

## Principles of Operation (2)

#### **MR (Magneto-Resistance) Effect:**

- Current path becomes longer and narrower
- Increasing resistance

### AMR (Anisotropic Magneto-Resistance) Effect:

• Electrical resistance depends on the <u>angle</u> between the direction of <u>electrical current</u> and the orientation of <u>magnetic field</u>

### **GMR (Giant Magneto-Resistance) Effect:**

- Alternating layers of ferromagnetic and nonmagnetic materials
- An external magnetic field changes magnetic moments: anti-parallel (high resistance) → parallel (low resistance)

| Material | Output<br>Voltage | Temp<br>Range | Temp<br>Ratio | Driving<br>Source | Magnet<br>Field   | Cost      |
|----------|-------------------|---------------|---------------|-------------------|-------------------|-----------|
| InSb     | Large             | Small         | Large         | Voltage           | Saturate          | Cheap     |
| InAs     |                   | Small         | Medium        |                   | Offset<br>change  |           |
| GaAs     | Small             | Large         | Small         | Current           | Wide<br>range     |           |
| Ge       |                   | Small         | Small         | Current           | Good<br>linearity | Expensive |

### Hall Sensor Types – Driving Source

| Material            | Linearity | Temp Char | Offset<br>Voltage | Circuit<br>Complexity |
|---------------------|-----------|-----------|-------------------|-----------------------|
| Constant<br>Current | Good      | Good      | Large             | Complex               |
| Constant<br>Voltage | Bad       | Bad       | Small             | Simple                |

### Hall IC

One Chip

- → Hall Sensor
- + Amplification Circuit
- + Temperature Correction Cirucuit
  - Linear Hall IC

output voltage is

linearly proportional to magnetic field strength

• Digital Hall IC

Schmitt Trigger

#### References

- [1] http://en.wikipedia.org/[2] Nam Ki Min, Sensor Electronics, Dong-il Press