Object Libraries

Visualization
User's Guide

NOTICE FOR USERS:

This User Guide is a general instruction for Open CASCADE Technology study. It may be incomplete and even contain occasional mistakes, particularly in examples, samples, etc.

OPEN CASCADE S.A.S. bears no responsibility for such mistakes. If you find any mistakes or imperfections in this document, or if you have suggestions for improving this document, please, contact us and contribute your share to the development of Open CASCADE Technology: bugmaster@opencascade.com

http://www.opencascade.com/contact/

TABLE OF CONTENTS

1. Introduction

This manual explains how to use Open CASCADE Technology Visualization. It provides basic documentation on setting up and using Visualization. For advanced information on Visualization and its applications, see our offerings on our web site (Training and E-Learning) at http://www.opencascade.org/support/training/

Visualization in Open CASCADE Technology is based on the separation of:

- on the one hand - the data which stores the geometry and topology of the entities you want to display and select, and
- on the other hand - its *presentation* (what you see when an object is displayed in a scene) and *selection* (possibility to choose the whole object or its sub-parts interactively in order to apply some application-defined operations to the selected entities).

1.1. Open CASCADE Technology Visualization and the Organization of this guide

Presentations are managed through the Presentation component, and selection through the Selection component.

To make management of these functionalities in 3D more intuitive and consequently, more transparent, **Application Interactive Services** have been created. **AIS** use the notion of the *interactive object*, a displayable and selectable entity, which represents an element from the application data. As a result, in 3D, you, the user, have no need to be familiar with any functions underlying AIS unless you want to create your own interactive objects or selection filters.

If, however, you require types of interactive objects and filters other than those provided, you will need to know the mechanics of presentable and selectable objects, specifically how to implement their virtual functions. To do this requires familiarity with such fundamental concepts as the sensitive primitive and the presentable object.

The packages used to display 3D objects are the following:

- AIS
- StdPrs
- Prs3d
- PrsMgr
- V3d
- Graphic3d

If you are concerned with 2D visualization, you must familiarize yourself with the fundamental concepts of presentation as outlined in the section on this subject in chapter 1, Fundamental Concepts. In brief, the packages used to display 3D objects are applicable for visualization of 2D objects too.

Figure 1 below presents a schematic overview of the relations between the key concepts and packages in visualization. Naturally, "Geometry & Topology" is just an example of application data that can be handled by AIS, and application-specific interactive objects can deal with any kind of data.
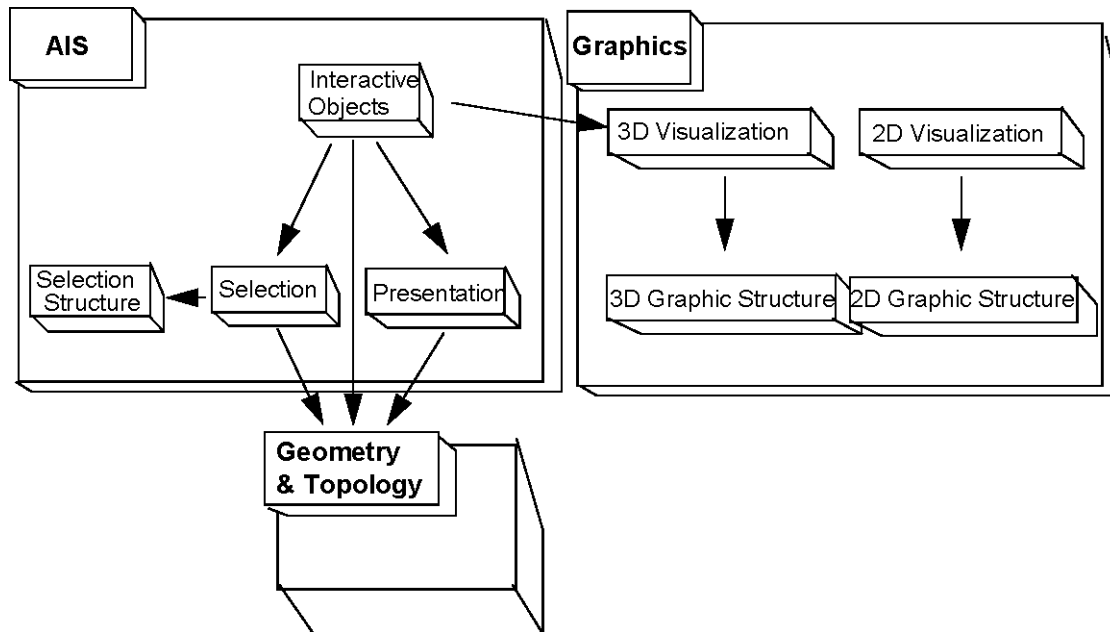
Figure 1. Key concepts and packages in visualization

To answer different needs of CASCADE users, this user's guide offers the following three paths in reading it.

- If the 3D services proposed in AIS meet your requirements, you need only read chapter 3, *AIS: Application Interactive Services*.

- If the services provided do not satisfy your requirements - if for example, you need a selection filter on another type of entity - you should read chapter 2 *Fundamental Concepts*, chapter 3 *AIS: Application Interactive Services*, and possibly chapters 4 and 5 *3D Presentations* and *3D Resources*. You may want to begin with the chapter presenting AIS.

- If your display will be in 2D, you should read chapter 1 *Fundamental Concepts*, chapter 6 *2D Presentations* and chapter 7 *2D Resources*.

2. Fundamental Concepts

2. 1 Presentation

In Open CASCADE Technology, presentation services are separated from the data, which they represent, which is generated by applicative algorithms. This division allows you to modify a geometric or topological algorithm and its resulting objects without modifying the visualization services.

2. 1. 1 Key difference in implementation of 2D and 3D visualization

Current implementation of 3D visualization services is based on OpenGL.

2D visualization packages use native window system API (Win32 GDI API on Windows, Xlib API on Unix and Linux).

2. 1. 2 Structure of the Presentation

Displaying an object on the screen involves three kinds of entity:

- a presentable object, the *AIS_InteractiveObject*
- a viewer
- an interactive context, the *AIS_InteractiveContext*.

The presentable object

The purpose of a presentable object is to provide the graphical representation of an object in the form of Graphic3d structure. On the first display request, it creates this structure by calling the appropriate algorithm and retaining this framework for further display.

Standard presentation algorithms are provided in the StdPrs and Prs3d packages. You can, however, write specific presentation algorithms of your own, provided that they create presentations made of structures from the Graphic3d packages. You can also create several presentations of a single presentable object: one for each visualization mode supported by your application.

Each object to be presented individually must be presentable or associated with a presentable object.

The viewer

The viewer allows you to interactively manipulate views of the object. When you zoom, translate or rotate a view, the viewer operates on the graphic structure created by the presentable object and not on the data model of the application. Creating Graphic3d structures in your presentation algorithms allows you to use the 3D viewers provided in Open CASCADE Technology for 2D and 3D visualisation.

The Interactive Context

(see chapter 2, AIS: Application Interactive Services) The interactive context controls the entire presentation process from a common high-level API. When the application requests the display of an object, the interactive context requests the graphic structure from the presentable object and sends it to the viewer for displaying.

Presentation packages

Presentation involves at least the AIS, PrsMgr, StdPrs and V3d packages. Additional packages such as Prs3d and Graphic3d may be used if you need to implement your own presentation algorithms.

AIS

See chapter 2, **AIS: Application Interactive Services** The *AIS* package provides all classes to implement interactive objects (presentable and selectable 2D or 3D entities).

PrsMgr

The *PrsMgr* package provides all the classes needed to implement the presentation process: the *Presentation* and *PresentableObject* abstract classes and the *PresentationManager2d* and *PresentationManager3d* concrete classes.

StdPrs

The *StdPrs* package provides ready-to-use standard presentation algorithms of points, curves and shapes of the geometry and topology toolkits.

V3d

The *V3d* package provides the services supported by the 3D viewer.

Prs3d

The *Prs3d* package provides some generic presentation algorithms such as wireframe, shading and hidden line removal associated with a Drawer class which controls the attributes of the presentation to be created in terms of color, line type, thickness, and so on.

Graphic3d

The *Graphic3d* package provides resources to create 2D and 3D graphic structures (please refer to chapters on 3D Resources and 2D Resources for more information).

2. 1. 3 A Basic Example: How to display a 3D object

Example

```
Void Standard_Real dx  = ...;  //Parameters
Void Standard_Real dy  = ...;  //to build a wedge
Void Standard_Real dz  = ...;
Void Standard_Real ltx = ...;


Handle(V3d_Viewer)aViewer = ...;
Handle(AIS_InteractiveContext)aContext;
aContext = new AIS_InteractiveContext(aViewer);


BRepPrimAPI_MakeWedge w(dx, dy, dz, ltx);
TopoDS_Solid & = w.Solid();
Handle(AIS_Shape) anAis = new AIS_Shape(S);
//creation of the presentable object
aContext -> Display(anAis);
//Display the presentable object in the 3d viewer.
```

The shape is created using the *BRepPrimAPI_MakeWedge* command. An AIS_Shape is then created from the shape. When calling the *Display* command, the interactive context calls the Compute method of the presentable object to calculate the presentation data and transfer it to the viewer. See Figure 2 below.

Class PresentationManager3d

calls Compute() method of AIS_InteractiveObject to obtain Graphics3d structure

**calls
Compute()**

deals with

Deferred class
AIS_InteractiveObject

Declares Compute() method

Object's presentation

inherits

Creation of AIS_Shape

Class AIS_Shape

Compute()

uses algorithms of Prs3d and StdPrs packages to create Graphics3d structure

uses

StdPrs and Prs3d packages

Contains various algorithms to transform object structures into a Graphics3d structures

Creation of topological object

Topological object

Figure 2. Processes involved in displaying a presentable shape

2. 2 Selection

This chapter deals with the process used for selecting entities, which are displayed in the 2D space of the selection view.

2. 2. 1 The Selection Principle

Objects that may be selected graphically, are displayed as sets of sensitive primitives, which provide sensitive zones in 2D graphic space. These zones are sorted according to their position on the screen when starting the selection process.

The position of the mouse is also associated with a sensitive zone. When moving within the window where objects are displayed, the areas touched by the zone of the mouse are analyzed. The owners of these areas are then highlighted or signaled by other means such as the name of the object highlighted in a list. That way, you are informed of the identity of the element detected.
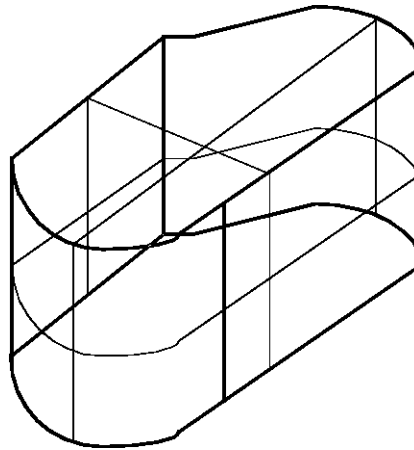
Figure 3. A model
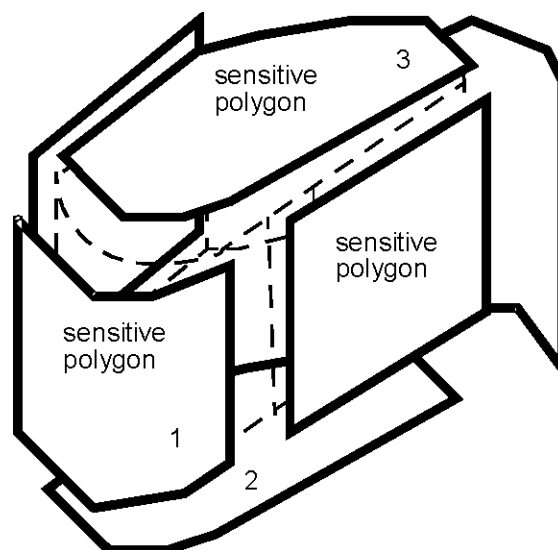
Figure 4. Modeling faces with sensitive primitives
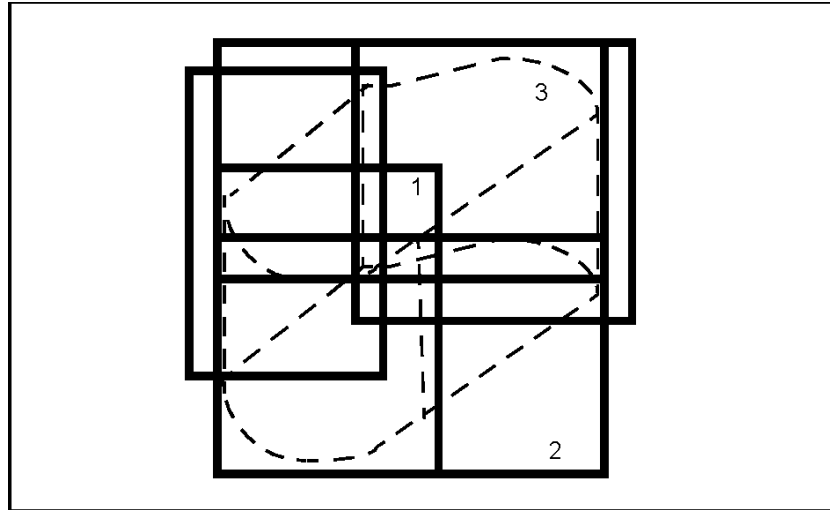
Figure 5. In a dynamic selection, each sensitive polygon is represented by its bounding rectangle

position of the mouse

selected rectangle

Mouse position inside the sensitive polygon

The owner is detected and stored
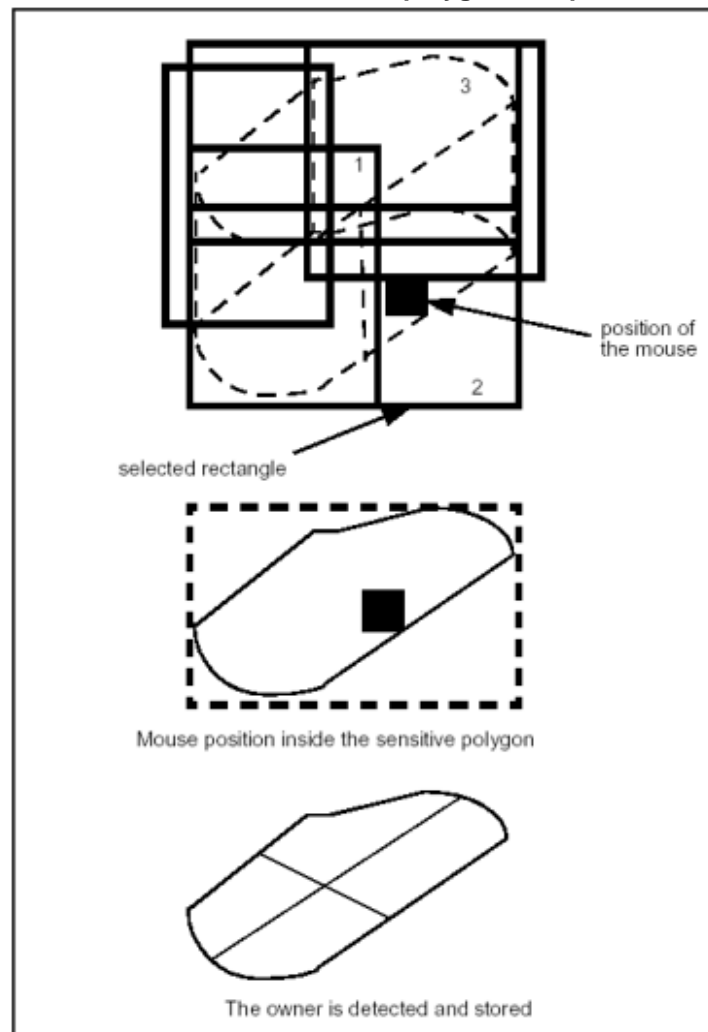
Figure 6. Reference to the sensitive primitive, then to the owner

2. 2. 2 The Sensitive Primitive

The sensitive primitive - along with the entity owner - allow you to define what can be made selectable, and in so doing, provide the link between the applicative object and the sensitive zones defined by the 2D bounding boxes. For an object to be dynamically selectable, it has to be represented either as a sensitive primitive or a set of them. These give 2D boxes that will be included in a sorting algorithm.

The use of 2D boxes allows a pre-selection of the detected entities. After pre-selection, the algorithm checks which sensitive primitives are actually detected. When detected, the primitives provide their owners' identity.

Example

The sensitive line segment below proposes a bounding box to the selector. During selection, positions 1 and 2 of the mouse detect the box but after sorting, only position 2 retains the line segment as selected by the algorithm.
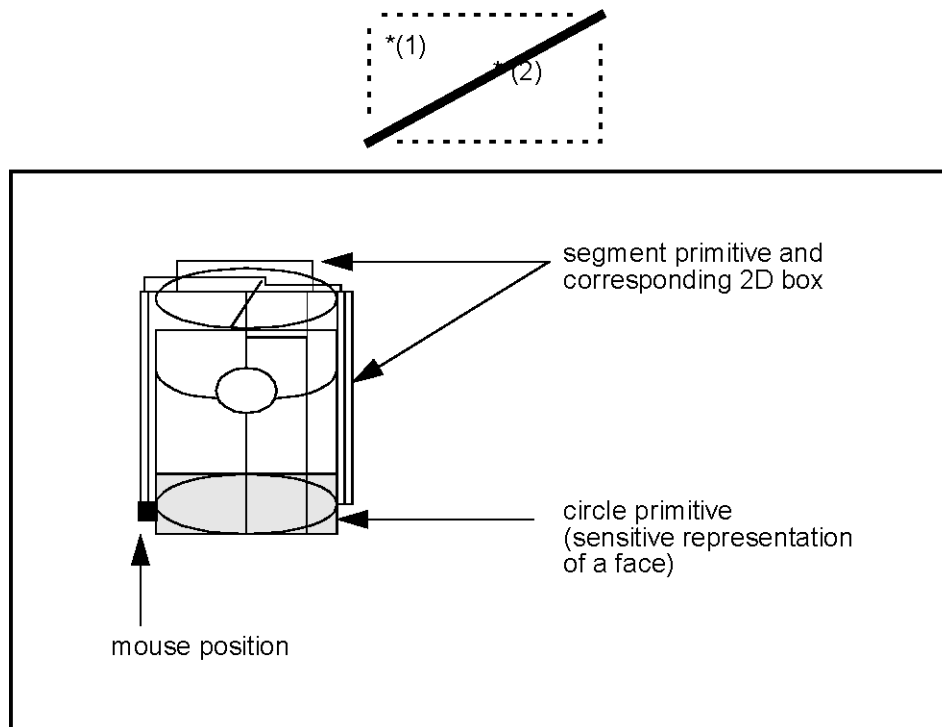
Figure 7. Example of sensitive primitives

When the 2D box associated with the position of the mouse intersects the 2D box of a sensitive primitive, the owner of the sensitive primitive is called and its presentation is highlighted.

The notion of sensitive primitive is important for the developer when defining his own classes of sensitive primitives for the chosen selection modes. The classes must

contain *Areas* and *Matches* functions. The former provides the list of 2D sensitive boxes representing the sensitive primitive at pre-selection and the latter determines if the detection of the primitive by the 2D boxes is valid.

2. 2. 3 The Principles of Dynamic Selection

Dynamic selection causes objects in a view to be automatically highlighted as the mouse cursor moves over them. This allows the user to be certain that the picked object is the correct one. Dynamic Selection is based on the following two concepts:

- a Selectable Object (see *AIS_InteractiveObject*)

- an Interactive Context

Selectable Object

A selectable object presents a given number of selection modes which can be redefined, and which will be activated or deactivated in the selection manager's selectors.

NOTE

The term, selection mode of a selectable object, can refer to the selection mode of the object itself or to that of one of its parts.

For each selection mode, a *SelectMgr_Selection* object class is included in the selectable object. (Each selection mode establishes a priority of selection for each class of selectable object defined.)

The notion of SELECTION is comparable to the notion of DISPLAY. Just as a display contains a set of graphic primitives that allow display of the entity in a specific display mode, a SELECTION contains a set of sensitive primitives, which allow detection of the entities they are associated with.

Interactive Context

See chapter 2, AIS: Application Interactive Services, Section 2.4

The interactive context is used to manage both selectable objects and selection processes.

Selection modes may be activated or de-activated for given selectable objects. Information is then provided about the status of activated/de-activated selection modes for a given object in a given selector.

Example

Let's consider the 3D selectable shape object, which corresponds to a topological shape.

For this class, seven selection modes can be defined:

> mode 0 - selection of the shape itself
>
> mode 1 - selection of vertices
>
> mode 2 - selection of edges
>
> mode 3 - selection of wires
>
> mode 4 - selection of faces
>
> mode 5 - selection of shells
>
> mode 6 - selection of solids
>
> mode 7 - selection of compsolids
>
> mode 8 - selection of compounds

Selection 2 includes the sensitive primitives that model all the edges of the shape. Each of these primitives contains a reference to the edge it represents.

The selections may be calculated before any activation and are graph independent as long as they are not activated in a given selector. Activation of selection mode 3 in a selector associated with a view V leads to the projection of the 3D sensitive primitives contained in the selection; then the 2D areas which represent the 2D bounding boxes of these primitives are provided to the sorting process of the selector containing all the detectable areas.

To deactivate selection mode 3 remove all those 2D areas.

Selection Packages

The selection packages are the following: *SelectBasics*, *SelectMgr*, *Select3D*, *StdSelect*.

SelectBasics

The *SelectBasics* package contains the basic classes of the selection:

- the main definition of a sensitive primitive: *SensitiveEntity*
- the definition of a sensitive primitive owner: *EntityOwner*
- the algorithm used for sorting sensitive boxes: *SortAlgo*

EntityOwner is used to establish a link from *SensitiveEntity* to application-level objects. For example, *SelectMgr_EntityOwner* (see below) class holds a pointer to corresponding *SelectableObject*.

SelectMgr

The *SelectMgr* package is used to manage the whole dynamic selection process. It contains the *SelectableObject, Entity Owner containing a link to its SelectableObject, Selection*, *SelectionManager*, and *ViewSelector* classes.

There are also implementations of *ViewerSelector* interface for 3D selection in *StdSelect* package: *ViewerSelector3d,*.

Select3D

The *Select3D* package contains all 3D standard sensitive primitives such as point, curve and face. All these classes inherit from 3D *SensitiveEntry* from *SelectBasics* with an additional method, which allows recovery of the bounding boxes in the 2D graphic selection space, if required. This package also includes the 3D-2D projector.

StdSelect

The *StdSelect* package provides standard uses of the classes described above and main tools used to prevent the developer from redefining the selection objects. In particular, *StdSelect* includes standard means for selection of topological objects (shapes).

2. 2. 4 Methodology

Several operations must be performed prior to using dynamic selection:

1. Implement specific sensitive primitives if those defined in Select3D are not sufficient. These primitives must inherit from *SensitiveEntity* from *SelectBasics* or from a suitable Select3D sensitive entity class when a projection from 3D to 2D is necessary.

2. Define all the owner types, which will be used, and the classes of selectable objects, i.e. the number of possible selection modes for these objects and the calculation of the decomposition of the object into sensitive primitives of all the primitives describing this mode. It is possible to define only one default selection mode for a selectable object if this object is to be selectable in a unique way.

3. Install the process, which provides the user with the identity of the owner of the detected entities in the selection loop.

When all these steps have been carried out, follow the procedure below:

1. Create an interactive context.

2. Create the selectable objects and calculate their various possible selections.

3. Load these selectable objects in the interactive context. The objects may be common to all the selectors, i.e. they will be seen by all the selectors in the selection manager, or local to one selector or more.

4. Activate or deactivate the objects' selection modes in the selector(s). When activating a selection mode in a selector for a given object, the manager sends the order to make the sensitive primitives in this selector selectable. If the primitives are to projected from 3D to 2D, the selector calls the specific method used to carry out this projection.

At this stage, the selection of selectable entities in the selectors is available.

The selection loop informs constantly the selectors with the position of the mouse and questions them about the detected entities.

2. 2. 5 Example of Use

Let's suppose you are creating an application that displays houses in a viewer of the V3d package and you want to select houses or parts of these houses (windows, doors, etc.) in the graphic window.

You define a selectable object called *House* and propose four possible selection modes for this object:

1 - selection of the house itself

2 - selection of the rooms

3 - selection of the walls

4 - selection of the doors.

You have to write the method, which calculates the four selections above, i.e. the sensitive primitives which are activated when the mode is.

You must define the class *Owner* specific to your application. This class will contain the reference to the house element it represents: wall, door or room. It inherits from *EntityOwner* from *SelectMgr*.

For example, let's consider a house with the following representation:
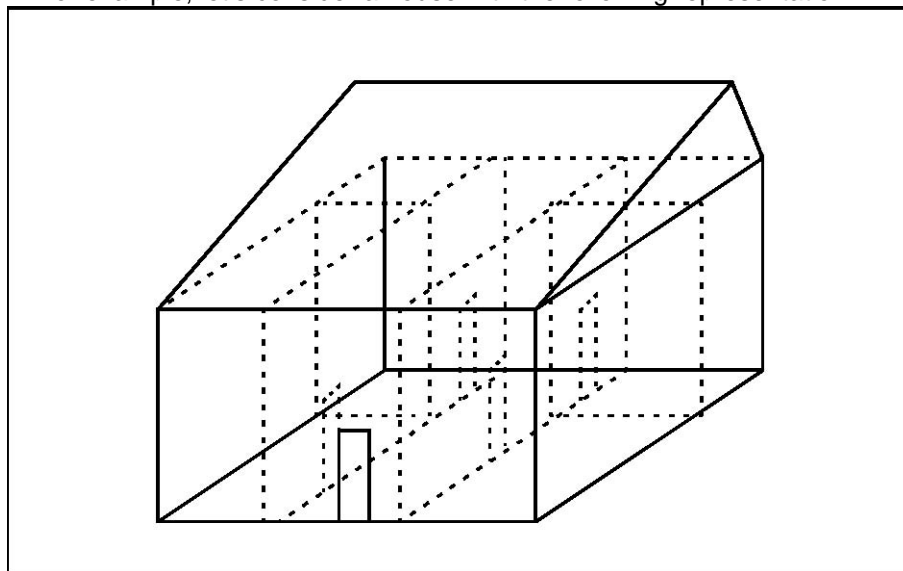
Figure 8. Selection of the rooms of a house

To build the selection, which corresponds to the mode "selection of the rooms" (selection 2 in the list of selection modes) use the following procedure:

Example

```
Void House::ComputeSelection
      (Const Handle(SelectMgr_Selection)& Sel,
       const Standard_Integer mode {
            switch(mode){
            case 0: //Selection of the rooms
            {
            for(Standard_Integer i = 1; i <= myNbRooms;
          i++)
             { //for every room, create an instance of the
          owner

               //along with the given room and its name.
            Handle(RoomOwner) aRoomOwner = new RoomOwner
            (Room(i), NameRoom(i)); //Room() returns a room
            and NameRoom() returns its name.
Handle(Select3d_SensitiveBox) aSensitiveBox;
aSensitiveBox = new Select3d_SensitiveBox
      (aRoomOwner, Xmin, Ymin, Zmin, Xmax, Ymax, Zmax);
            Sel -> Add(aSensitiveBox);
            }
            break;
            Case 1: ... //Selection of the doors
            } //Switch

   ) // ComputeSelection
```


View 1

Before selection
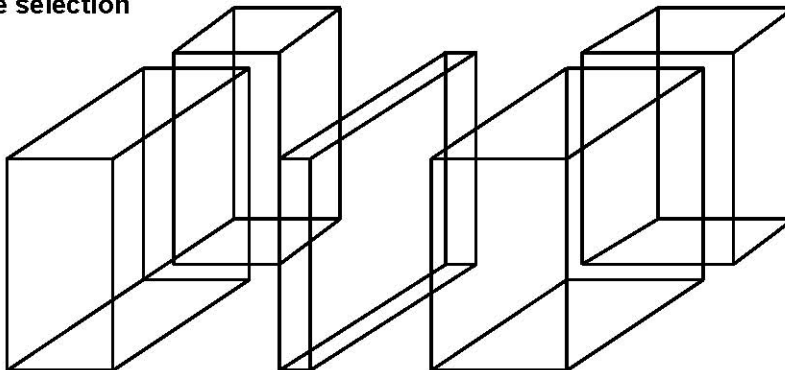
Figure 9. Activated sensitive boxes corresponding to selection mode 0 (selection of the rooms)
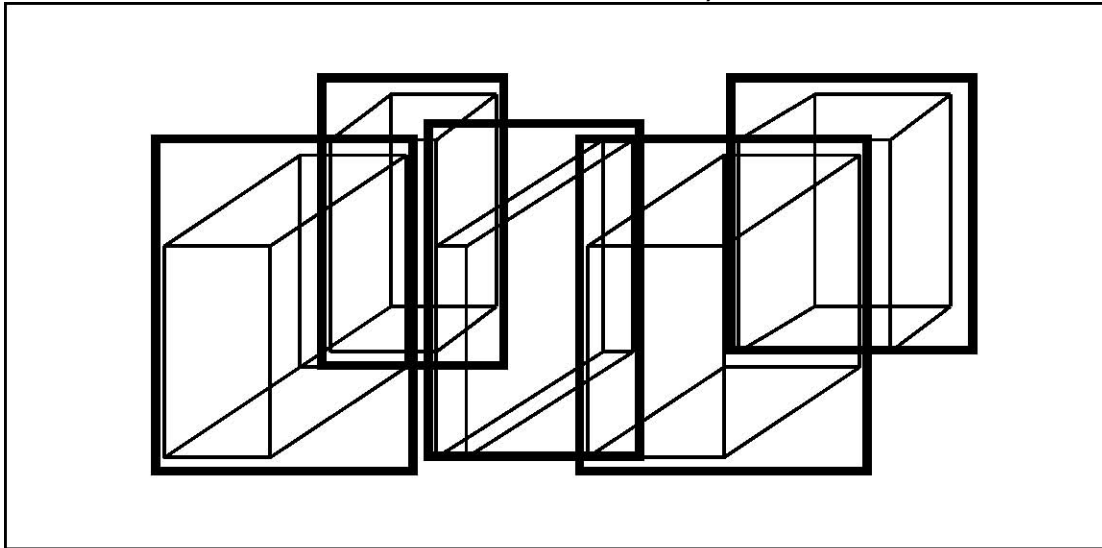
Figure 10. Activated sensitive rectangles in the selector during dynamic selection in view 1

(
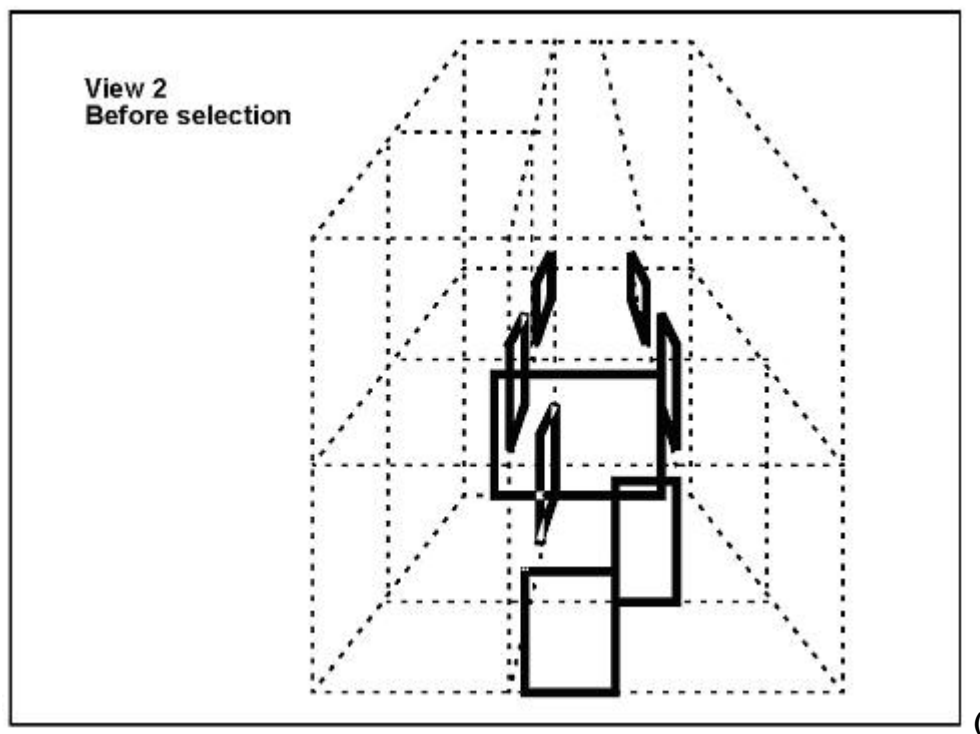
Figure 11. Activated sensitive polygons corresponding to selection mode 1. (selection of the doors)
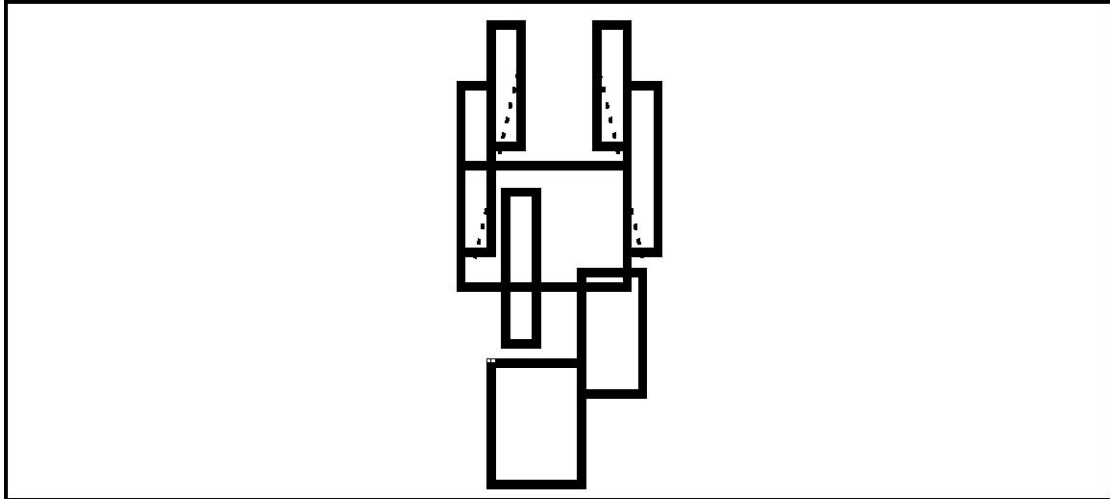
Figure 12. Sensitive rectangles in the selector during dynamic selection in view 2

3. AIS: Application Interactive Services

Application Interactive Services (**AIS**) offers a set of general services beyond those offered by basic Selection and Presentation packages such as **PrsMgr**, **SelectMgr** and **StdSelect**. These allow you to manage presentations and dynamic selection in a viewer simply and transparently. To use these services optimally, you should know various rules and conventions. Section I provides an overview of the important classes which you need to manipulate AIS well. Sections 2 and 3 explain in detail how to use them and how to implement them, as well as the rules and conventions to respect. The annexes offer various standard Interactive Objects in AIS, an example of an implementation of AIS and a reminder of how to manage presentation and selection.

3. 1 Overview

3. 1. 1 Interactive Context/Local Context

AIS_InteractiveContext

The central entity, which pilots visualizations and selections, is the Interactive Context. It is linked to a main viewer (and if need be, a trash bin viewer.) It has two operating modes: the Neutral Point and the local visualization and selection context. The neutral point, which is the default mode, allows you to easily visualize and select interactive objects, which have been loaded into the context. Opening Local Contexts allows you to prepare and use a temporary selection environment without disturbing the neutral point. A set of functions allows you to choose the interactive objects, which you want to act on, the selection modes, which you want to activate, and the temporary visualizations, which you will execute. When the operation is finished, you close the current local context and return to the state in which you were before opening it (neutral point or previous local context).

3. 1. 2 The Interactive Object

AIS_InteractiveObject

Entities, which are visualized and selected, are Interactive Objects. You can use classes of standard interactive objects for which all necessary functions have already been programmed, or you can implement your own classes of interactive objects, by respecting a certain number of rules and conventions described below.

3. 1. 3 Graphic Attributes Manager or "Drawer"
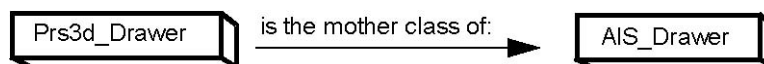
An Interactive Object can have a certain number of graphic attributes specific to it (such as visualization mode, color and material) By the same token, the Interactive Context has a drawer which is valid by default for the objects it controls. When an interactive object is visualized, the required graphic attributes are first taken from its

own Drawer if it has the ones required, or from the context drawer if it does not have them.

3. 1. 4 Selection Filters
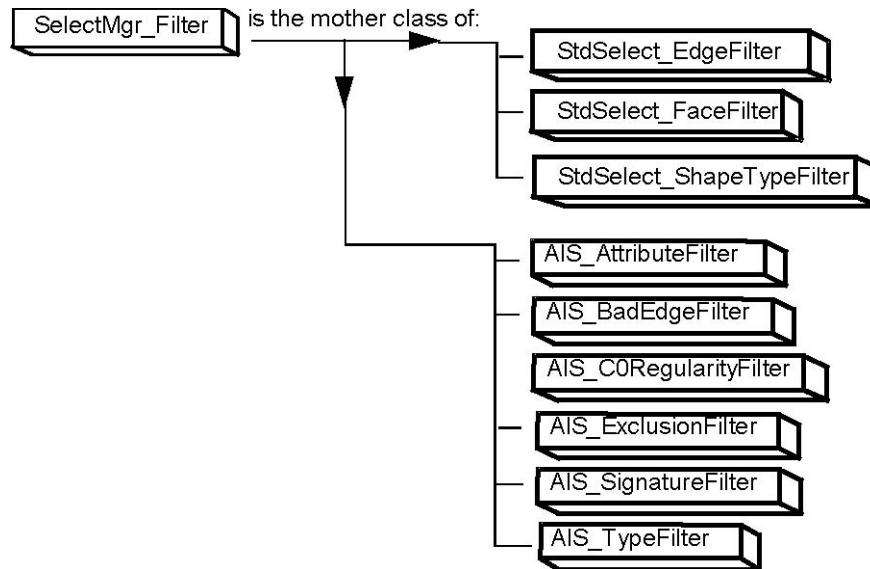
An important need in selection is the filtering of entities, which you want to select. Consequently there are FILTER entities, which allow you to refine the dynamic detection context, which you want to put into effect. Some of these filters can be used at the Neutral Point, others only in an open local context. A user will be able to program his own filters and load them into the interactive context.

3. 2 Rules and Conventions Governing Interactive Objects

An interactive object is a "virtual" entity, which can be presented and selected. It can also have its own visualization aspects such as color, material, and mode of visualization. In order to create and manipulate the interactive objects with ease, you must know the rules and conventions, which have been established. Several "virtual" functions must be implemented for these objects to have the behavior expected of them. A certain number of standard interactive objects, which respect the rules and conventions described below, have been implemented in AIS. The current list of them can be found in ANNEX I. The services that concern manipulation of presentations, selection and graphic attributes will be treated separately.

3. 2. 1 Presentations:
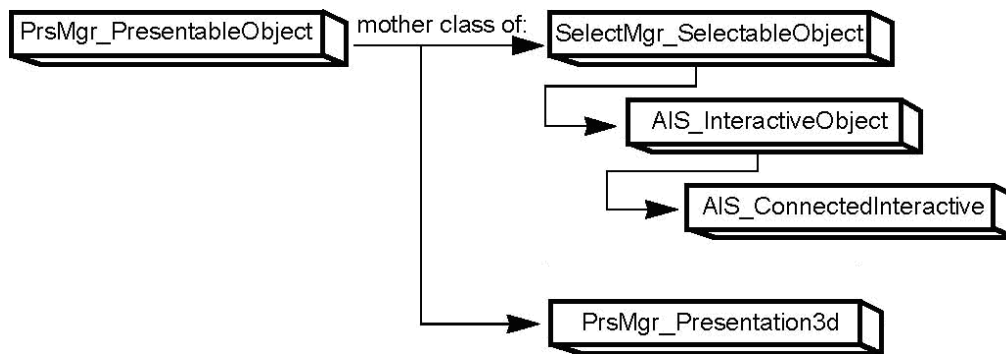
Conventions

- Either in 2D or in 3D, an interactive object can have as many presentations as its creator wants to give it.
- 3D presentations are managed by PresentationManager3D. As this is transparent in AIS, the user does not have to worry about it.
- A presentation is identified by an index and by the reference to the Presentation Manager which it depends on.
- By convention, the default mode of representation for the Interactive Object has index 0.

Virtual functions

Calculation of different presentations of an interactive object is done in the *Compute* functions inheriting from *PrsMgr_ PresentableObject::Compute* functions. They are automatically called by *PresentationManager* at a visualization or an update request.

If you are creating your own type of interactive object, you must implement the Compute function in one of the following ways:

- **For 3D:**

Example

```
void PackageName_ClassName::Compute
      (const Handle(PrsMgr_PresentationManager3d)&
                              aPresentationManager,
       const Handle(Prs3d_Presentation)& aPresentation,
       const Standard_Integer aMode = 0);
```

- **For hidden line removal (HLR) mode in 3D (*):**

Example

```
void PackageName_ClassName::Compute
      (const Handle(Prs3d_Projector)& aProjector,
       const Handle(Prs3d_Presentation)& aPresentation);
```

WARNING (*)

As its call is automatically ordered by a view, this function requires explanation; the view has two states: normal mode and computed mode (Hidden Line Removal, or HLR mode). When the latter is active, the view looks for all presentations displayed in normal mode, which have been signaled as accepting HLR mode. An internal mechanism allows us to call the interactive object's own *Compute*, that is, projector, function. How do you declare that such and such a presentation will accept an "equivalent" in HLR mode? By convention, it is the Interactive Object, which accepts or rejects the representation of HLR mode. You can make this declaration in one of two ways, either initially by using one of the values of the enumeration PrsMgr_TypeOfPresentation:

- PrsMgr_TOP_AllView,
- PrsMgr_TOP_ProjectorDependant

or later on, by using the function:

- • PrsMgr_PresentableObject::SetTypeOfPresentation

AIS_Shape class is an example of an interactive object that supports HLR representation. It supports two types of the HLR algorithm:

1) the polygonal algorithm based on the shape's triangulation;
2) the exact algorithm that works with the shape's real geometry.

The type of the HLR algorithm is stored in AIS_Drawer of the shape. It is a value of the Prs3d_TypeOfHLR enumeration and can be set to:

1) Prs3d_TOH_PolyAlgo for polygonal algorithm

2) Prs3d_TOH_Algo for exact algoritm

3) Prs3d_TOH_NotSet if the type of algorithm is not set for the given interactive object instance (see the explanation below).

The type of the HLR algorithm used for AIS_Shape can be changed by calling the AIS_Shape::SetTypeOfHLR () method. To get the current HLR algorithm type AIS_Shape::TypeOfHLR () is to be used. These methods get the value from the drawer of AIS_Shape. If the HLR algorithm type in the AIS_Drawer is set to Prs3d_TOH_NotSet, the AIS_Drawer gets the value from the default drawer of AIS_InteractiveContext. In this manner it is possible to change the default HLR algorithm to be used by all newly dsplayed interactive objects. The value of the HLR algorithm type stored in the context drawer can be Prs3d_TOH_Algo or Prs3d_TOH_PolyAlgo. The polygonal algorithm is the default one.

3. 2. 2 Important Specifics of AIS:

There are four types of interactive object in AIS:

- the "construction element" or Datum,
- the Relation (dimensions and constraints)
- the Object
- the None type (when the object is of an unknown type).

Inside these categories, additional characterization is available by means of a signature (an index.) By default, the interactive object has a NONE type and a signature of 0 (equivalent to NONE.) If you want to give a particular type and signature to your interactive object, you must redefine two virtual functions:

- `AIS_InteractiveObject::Type`
- `AIS_InteractiveObject::Signature.`

WARNING

Some signatures have already been used by "standard" objects delivered in AIS. (see the list of standard objects, Annex I.)

As will be seen below, the interactive context can have a default mode of representation for the set of interactive objects. This mode may not be accepted by a given class of objects. Consequently, a virtual function allowing you to get information about this class must be implemented:

- `AIS_InteractiveObject::AcceptDisplayMode.`

Services You Should Know

Display Mode: An object can have its own display mode, which is different from that proposed by the interactive context. The functions to use are:

- `AIS_InteractiveContext::SetDisplayMode`
- `AIS_InteractiveContext::UnsetDisplayMode.`

Hilight Mode: At dynamic detection, the presentation echoed by the Interactive Context, is by default the presentation already on the screen. You can always specify the display mode used for highlighting purposes (so called highlight mode), which is valid no matter what the active representation of the object. It makes no difference whether this choice is temporary or definitive. To do this, you use the following functions:

- `AIS_InteractiveObject::SetHilightMode`
- `AIS_InteractiveObject::UnSetHilightMode`

Note that the same presentation (and consequently the same highlight mode) is used for highlighting *detected* objects and for highlighting *selected* objects, the latter being drawn with a special *selection color* (refer to the section related to *Interactive Context* services).

An example: For a shape - whether it is visualized in wireframe presentation or with shading - you want to systematically highlight the wireframe presentation. Consequently, you set the highlight mode to *0* in the constructor of the interactive object. You mustn't forget to effect the implementation of this representation mode in the *Compute* functions.

Infinite Status: If you don't want an object to be affected by a FitAll view, you must declare it infinite; you can cancel its "infinite" status in the same way.

- AIS_InteractiveObject::SetInfiniteState
- AIS_InteractiveObject::IsInfinite

Example

Let's take the case of a class called IShape, representing an interactive object
```
myPk_IShape::myPK_IShape
      (const TopoDS_Shape& SH, PrsMgr_TypeOfPresentation
aType):

      AIS_InteractiveObject(aType),
      myShape(SH),
      myDrwr(new AIS_Drawer())
{
      SetHilightMode(0);
}
void myPk_IShape::Compute
      (const Handle(PrsMgr_PresentationManager3d) & PM,
       const Handle(Prs3d_Presentation)& P,
       const Standard_Integer TheMode)
{
      switch (TheMode){
```

```
               case 0:
                      StdPrs_WFDeflectionShape::Add
               (P,myShape,myDrwr);
                      //algo for calculation of wireframe
               presentation break;

               case 1:
                      StdPrs_ShadedShape::Add (P,myShape,myDrwr);
                      //algo for calculation of shading presentation.
                      break;
               }
       }
       void myPk_IsShape::Compute
               (const Handle(Prs3d_Projector)& Prj,
               const Handle(Prs3d_Presentation) P)
       {

               StdPrs_HLRPolyShape::Add(P,myShape,myDrwr);
               //Cas-cade hidden line mode calculation algorithm
       }
```

3. 3 Selections

3. 3. 1 Conventions

An interactive object can have an indefinite number of modes of selection, each representing a "decomposition" into sensitive primitives; each primitive has an Owner (*SelectMgr_EntityOwner*) which allows us to identify the exact entity which has been detected (see ANNEX II).

The set of sensitive primitives, which correspond to a given mode, is stocked in a SELECTION (*SelectMgr_Selection*).

Each Selection mode is identified by an index. By Convention, the default selection mode that allows us to grasp the Interactive object in its entirety is mode *0*.

3. 3. 2 Virtual functions

The calculation of Selection primitives (or sensitive primitives) is done by the intermediary of a virtual function, *ComputeSelection*. This should be implemented for each type of interactive object on which you want to make different type selections using the following function:

- AIS_ConnectedInteractive::ComputeSelection

A detailed explanation of the mechanism and the manner of implementing this function has been given in ANNEX II.

Moreover, just as the most frequently manipulated entity is TopoDS_Shape, the most used Interactive Object is AIS_Shape. You will see below that activation functions for standard selection modes are proposed in the Interactive context (selection by vertex, by edges etc.). To create new classes of interactive object with the same behavior as AIS_Shape - such as vertices and edges - you must redefine the virtual function:

- AIS_ConnectedInteractive::AcceptShapeDecomposition.

3. 3. 3 Other Services

You can change the default selection mode index of an Interactive Object. For instance, you can:

- check to see if there is a selection mode
- check the current selection mode
- set a selection mode
- unset a selection mode.

The following functions are concerned:

- AIS_InteractiveObject::HasSelectionMode
- AIS_InteractiveObject::SelectionMode
- AIS_InteractiveContext::SetSelectionMode
- AIS_InteractiveContext::UnsetSelectionMode

These functions are only of interest if you decide that the *0* mode adopted by convention will not do. In the same way, you can temporarily change the priority of certain interactive objects for selection of 0 mode. You could do this to make it easier to detect them graphically. You can:

- check to see if there is a selection priority setting for the owner
- check the current priority
- set a priority
- unset the priority.

To do this, you use the following functions:

- AIS_InteractiveObject::HasSelectionPriority
- AIS_InteractiveObject::SelectionPriority
- AIS_InteractiveObject::SetSelectionPriority
- AIS_InteractiveObject::UnsetSelectionPriority

3. 4 Graphic attributes of an interactive object

Keep in mind the following points concerning graphic attributes:

- Each interactive object can have its own visualization attributes.
- The set of graphic attributes of an interactive object is stocked in an *AIS_Drawer*, which is only a *Prs3d_Drawer* with the possibility of a link to another drawer
- By default, the interactive object takes the graphic attributes of the context in which it is visualized (visualization mode, deflection values for the calculation of presentations, number of isoparameters, color, type of line, material, etc.)
- In the *AIS_InteractiveObject* abstract class, several standard attributes have been privileged. These include: color, thickness of line, material, and transparency. Consequently, a certain number of virtual functions, which allow us to act on these attributes, have been proposed. Each new class of interactive object can redefine these functions in order to bring about the changes it should produce in the behavior of the class.

Change: | AISPoint::SetColor | - define: | AIS_Drawer::PointAspect |

Figure 13. Redefinition of virtual functions for changes in AIS_Point

Change: | AIS_Shape::SetColor | - redefine:
- | AIS_Drawer::FreeBoundaryAspect |
- | AIS_Drawer::UnFreeBoundaryAspect |
- | AIS_Drawer::UIsoAspect |
- | AIS_Drawer::VIsoAspect |
- | AIS_Drawer::ShadingAspect |
- | AIS_Drawer::SeenLineAspect |
- | AIS_Drawer::HiddenLineAspect |
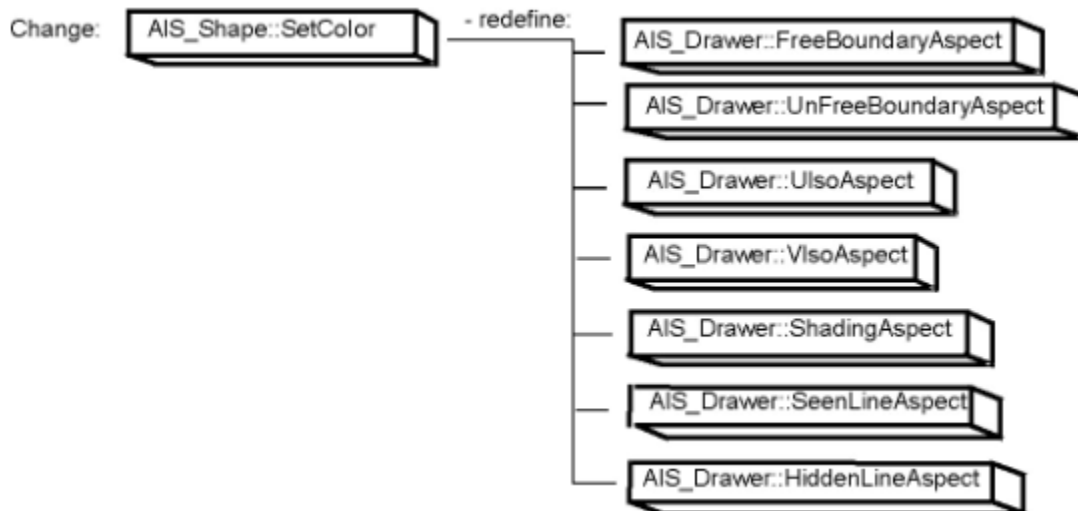
Figure 14. Redefinition of virtual functions for changes in AIS_Shape.

The virtual functions concerned here allow you to provide settings for:

- color
- width
- material

- transparency

The functions concerned are the following:

- `AIS_InteractiveObject::UnsetColor`
- `AIS_InteractiveObject::SetWidth`
- `AIS_InteractiveObject::UnsetWidth`
- `AIS_InteractiveObject::SetMaterial`
  `(const Graphic3d_NameOfPhysicalMaterial & aName)`
- `AIS_InteractiveObject::SetMaterial`
  `(const Graphic3d_MaterialAspect & aMat)`
- `AIS_InteractiveObject::UnsetMaterial`
- `AIS_InteractiveObject::SetTransparency`
- `AIS_InteractiveObject::UnsetTransparency`

For other types of attribute, it is appropriate to change the Drawer of the object directly using:

- `AIS_InteractiveObject::SetAttributes`
- `AIS_InteractiveObject::UnsetAttributes`

3. 4. 1 Manipulation of Attributes

Some of these functions may imply the recalculation of presentations of the object. It is important to know which ones. If an interactive object's presentation mode is to be updated, a flag from *PrsMgr_PresentableObject* indicates this. The mode should be updated using the functions *Display* and *Redisplay* in *AIS_InteractiveContext*.

3. 5 Complementary Services - Precautions

3. 5. 1 Changing an interactive object's location

When using complementary services for interactive objects, pay special attention to the following cases:

Functions allowing us to temporarily "move" the representation and selection of Interactive Objects in a view without recalculation.

- `AIS_InteractiveContext::SetLocation`
- `AIS_InteractiveContext::ResetLocation`
- `AIS_InteractiveContext::HasLocation`
- `AIS_InteractiveContext::Location`

How you link applicative entities to interactive objects.

3. 5. 2 Connecting an interactive object to an applicative entity

Each Interactive Object has functions that allow us to attribute it an Owner in the form of a Transient.

- `AIS_InteractiveObject::SetOwner`
- `AIS_InteractiveObject::HasOwner`
- `AIS_InteractiveObject::Owner`

An interactive object can therefore be associated with an applicative entity or not, without this affecting its behavior.

3. 5. 3 Resolving coincident topology

Due to the fact that the accuracy of three-dimensional graphics coordinates has a finite resolution the elements of topological objects can coincide producing the effect of "popping" some elements one over another.

To avoid such kind of a problem when the elements of two or more InteractiveObjects are coincident you can apply the polygon offset. It is a sort of graphics computational offset, or depth buffer offset, that allows you to arrange elements (by modifying their depth value) without changing their coordinates. The graphical elements that accept this kind of offsets are solid polygons or displayed as boundary lines and points. The polygons could be displayed as lines or points by setting the appropriate interior style.

The following method allows you to set up the polygon offsets:

- `void AIS_InteractiveObject::SetPolygonOffsets`
    `(const Standard_Integer aMode,`
     `const Standard_Real aFactor,`
     `const Standard_Real aUnits)`

    The parameter aMode can contain various combinations of Aspect_PolygonOffsetMode enumeration elements. The enumeration has the following elements:

    - `Aspect_POM_None`
    - `Aspect_POM_Off`
    - `Aspect_POM_Fill`
    - `Aspect_POM_Line`
    - `Aspect_POM_Point`
    - `Aspect_POM_All`

The combination of these elements defines the polygon display modes that will use the given offsets. You can switch off the polygon offsets by passing the Aspect_POM_Off. Passing Aspect_POM_None allows you to change the aFactor and aUnits values without changing the mode. If aMode is different from Aspect_POM_Off, the aFactor and aUnits arguments are used by the graphics renderer to calculate the depth offset value:

offset = aFactor * m + aUnits * r,

where m – maximum depth slope for the polygons currently being displayed, r – minimum depth resolution (implementation-specific)

Negative offset values move polygons closer to the viewer while positive values shift polygons away.

WARNING

This method has a side effect – it creates its own shading aspect if not yet created, so it is better to set up the object shading aspect first.

You can use the following functions to obtain the current settings for polygon offsets:

- `void AIS_InteractiveObject::PolygonOffsets`
    `(Standard_Integer &aMode,`
     `Standard_Real &aFactor,`
     `Standard_Real &aUnits)`

- `Standard_Boolean`
    `AIS_InteractiveObject::HasPolygonOffsets()`

The same operation could be performed for the interactive object known by the AIS_InteractiveContext with the following methods:

- `void AIS_InteractiveContext::SetPolygonOffsets`
    `(const Handle(AIS_InteractiveObject) &anObj,`
     `const Standard_Integer aMode,`
     `const Standard_Real aFactor,`
     `const Standard_Real aUnits)`

- `void AIS_InteractiveContext::PolygonOffsets`
    `(const Handle(AIS_InteractiveObject) &anObj,`
     `Standard_Integer &aMode,`
     `Standard_Real &aFactor,`
     `Standard_Real &aUnits)`

- `Standard_Boolean`
    `AIS_InteractiveContext::HasPolygonOffsets`
    `(const Handle(AIS_InteractiveObject) &anObj)`

3. 6 The Interactive Context

3. 6. 1 Preliminary Rules

The Interactive Context allows us to manage in a transparent way, the graphic and "selectable" behavior of interactive objects in one or more viewers. Most functions which allow us to modify the attributes of interactive objects, and which were presented in the preceding chapter, will be looked at again here.

There is one essential rule to follow: the modification of an interactive object, which is already known by the Context, must be done using Context functions. You can only directly call the functions available for an interactive object if it has not been loaded into an Interactive Context.

Example

```
Handle (AIS_Shape) TheAISShape = new AIS_Shape (ashape);
myIntContext->Display(TheAISShape);
myIntContext->SetDisplayMode(TheAISShape , 1);
myIntContext->SetColor(TheAISShape, Quantity_NOC_RED);
```

//but you can write

```
Handle (AIS_Shape) TheAISShape = new AIS_Shape (ashape);
TheAISShape->SetColor(Quantity_NOC_RED);
TheAISShape->SetDisplayMode(1);
myIntContext->Display(TheAISShape);
```

3. 6. 2 Groups of functions

You must distinguish two states in the Interactive Context:

- No Open Local Context; which will be referred to as Neutral Point.
- One or several open local contexts, each representing a temporary state of selection and presentation.

Some functions can only be used in open Local Context; others in closed local context; others do not have the same behavior in one state as in the other.

The Interactive Context is composed of a great many functions, which can be conveniently grouped according to theme:

- management proper to the context
- management in the local context

- presentations and selection in open/closed context
- selection strictly speaking

3. 6. 3 Management proper to the Interactive Context

The Interactive Context is made up of a Principal Viewer and, optionally, a trash bin or "Collector" Viewer. It also has a group of adjustable settings allowing you to personalize the behavior of presentations and selections:

- Default Drawer, containing all the color and line attributes which can be used by interactive objects, which do not have their own attributes.
- Default Visualization Mode for interactive objects

    Default: mode 0
- Highlight color of entities detected by mouse movement

    Default: Quantity_NOC_CYAN1
- Preselection color

    Default: Quantity_NOC_GREEN
- Selection color (when you click on a detected object)

    Default: Quantity_NOC_GRAY80
- Sub-Intensity color

    Default: Quantity_NOC_GRAY40

All of these settings can be modified by functions proper to the Context.

When you change a graphic attribute pertaining to the Context (visualization mode, for example), all interactive objects, which do not have the corresponding appropriate attribute, are updated.

Example

```
//obj1, obj2: 2 interactive objects.

TheCtx->Display(obj1,Standard_False); // False = no update
of viewer.
TheCtx->Display(obj2,Standard_True); // True = Update of
Viewer
TheCtx->SetDisplayMode(obj1,3,Standard_False);
TheCtx->SetDisplayMode(2);
// obj2 is visualised in mode 2 (if it accepts this mode)
// obj1 stays visualised in its mode 3.
```

To the main Viewer, are associated a *PresentationManager3D* and a *Selector3D* which manage the presentation and selection of present interactive objects. The

same is true of the optional Collector. As we shall see, this management is completely transparent for the user.

3. 7 Management of Local Context

3. 7. 1 Rules and Conventions

- Opening a local context allows you to prepare an environment for temporary presentations and selections, which will disappear once the local context is closed.
- It is possible to open several local contexts, but only the last one will be active.
- When you close a local context, the one before, which is still on the stack, reactivates. If none is left, you return to Neutral Point.
- Each local context has an index created when the context opens. You should close the local context, which you have opened.

3. 7. 2 Important functionality

The interactive object, which is used the most by applications, is *AIS_Shape*. Consequently, standard functions are available which allow you to easily prepare selection operations on the constituent elements of shapes (selection of vertices, edges, faces etc) in an open local context. The selection modes specific to "Shape" type objects are called **Standard Activation Mode**. These modes are only taken into account in open local context and only act on interactive objects which have redefined the virtual function *AcceptShapeDecomposition()* so that it returns *TRUE*.

- Objects, which are temporarily in a local context, are not recognized by other local contexts a priori. Only objects visualized in Neutral Point are recognized by all local contexts.

- The state of a temporary interactive object in a local context can only be modified while another local context is open (except for one special case - see III.4.2)

WARNING

The specific modes of selection only concern the interactive objects, which are present in the Main Viewer. In the Collector, you can only locate interactive objects, which answer positively to the positioned filters when a local context is open. Under no circumstances are they decomposed in standard mode etc.

3. 7. 3 Use

Opening and closing a local context are easy to put into operation:

- `AIS_InteractiveContext::OpenLocalContext`

The options available allow you to control what you want to do:

- *UseDisplayedObjects*: allows you to load or not load the interactive objects visualized at Neutral Point in the local context, which you open. If *FALSE*, the local context is empty after being opened. If *TRUE*, the objects at Neutral Point are modified by their default selection mode.
- *AllowShapeDecomposition*: AIS_Shape allows or prevents decomposition in standard shape location mode of objects at Neutral Point, which are type-"privileged" (see selection chapter). This Flag is only taken into account when *UseDisplayedObjects* is *TRUE*.
- *AcceptEraseOfObjects*: authorises other local contexts to erase the interactive objects present in this context. This option is rarely used. The last option has no current use.

This function returns the index of the created local context. It should be kept and used when the context is closed.

To load objects visualized at Neutral Point into a local context or remove them from one:
- `AIS_InteractiveContext::UseDisplayedObjects`
- `AIS_InteractiveContext::NotUseDisplayedObjects`

Closing Local Contexts is done by:
- `AIS_InteractiveContext::CloseLocalContext`
- `AIS_InteractiveContext::CloseAllContexts`

WARNING

When the index isn't specified in the first function, the current Context is closed. This option can be dangerous, as other Interactive Functions can open local contexts without necessarily warning the user. For greater security, you have to close the context with the index given on opening.

To get the index of the current context, use the following function:

- `AIS_InteractiveContext::IndexOfCurrentLocal`

The second function allows you to close all open local contexts at one go. In this case, you find yourself directly at Neutral Point.

When you close a local context, all temporary interactive objects are erased (deleted), all selection modes concerning the context are cancelled, and all content filters are emptied.

3. 7. 4 Management of Presentations and Selections

You must distinguish between the Neutral Point and the Open Local Context states. Although the majority of visualization functions can be used in both situations, their behavior is different:

3. 7. 5 Presentation in Neutral Point

Neutral Point should be used to visualize the interactive objects, which represent and select an applicative entity. Visualization and Erasing orders are straightforward:

- ```
  AIS_InteractiveContext::Display
          (const Handle(AIS_InteractiveObject)& anIobj,
           const Standard_Boolean
  updateviewer=Standard_True);
  ```

- ```
  AIS_InteractiveContext::Display
          (const Handle(AIS_InteractiveObject)& anIobj,
           const Standard_Integer amode,
           const Standard_Integer aSelectionMode,
           const Standard_Boolean
  updateviewer = Standard_True,
           const Standard_Boolean
  allowdecomposition = Standard_True);
  ```

- `AIS_InteractiveContext::Erase`
- `AIS_InteractiveContext::EraseMode`
- `AIS_InteractiveContext::ClearPrs`
- `AIS_InteractiveContext::Redisplay`
- `AIS_InteractiveContext::Remove`
- `AIS_InteractiveContext::EraseAll`
- `AIS_InteractiveContext::Hilight`
- `AIS_InteractiveContext::HilightWithColor`

3. 7. 6 Important Remarks:

Bear in mind the following points:

- It is recommended to display and erase interactive objects when no local context is opened, and open a local context for local selection only.
- The first **Display** function among the two ones available in *InteractiveContext* visualizes the object in its default mode (set with help of SetDisplayMode() method of InteractiveObject prior to Display() call), or in the default context mode, if applicable. If it has neither, the function displays it in 0 presentation mode. The object's default selection mode is automatically activated (0 mode by convention).
- Activating the displayed object by default can be turned off with help of **SetAutoActivateSelection**() method. This might be efficient if you are not interested in selection immediately after displaying an object.
- The second **Display** function should only be used in Neutral Point to visualize a supplementary mode for the object, which you can erase by EraseMode (...). You activate the selection mode. This is passed as an argument. By convention, if you do not want to activate a selection mode,

you must set the *SelectionMode* argument to the value of -1. This function is especially interesting in open local context, as we will see below.

- In Neutral Point, it is unadvisable to activate other selection modes than the default selection one. It is preferable to open a local context in order to activate particular selection modes.

- When you call **Erase** (Interactive object) function, the *PutIncollector* argument, which is FALSE by default, allows you to visualize the object directly in the Collector and makes it selectable (by activation of 0 mode). You can nonetheless block its passage through the Collector by changing the value of this option. In this case, the object is present in the Interactive Context, but is not seen anywhere.

- **Erase**() with *putInCollector* **= Standard_True** might be slow as it re-computes the objects presentation in the Collector. Set putInCollector to Standard_False if you simply want to hide the object's presentation temporarily.

- Modifications of visualization attributes and graphic behavior is effected through a set of functions similar to those which are available for the interactive object (color, thickness of line, material, transparency, locations etc.) The context then manages immediate and deferred updates.

- Call **Remove**() method of *InteractiveContext* as soon as the interactive object is no longer needed and you want to destroy it.. Otherwise, references to *InteractiveObject* are kept by *InteractiveContext*, and the *Object* is not destroyed that results in memory leaks. In general, if some interactive object's presentation can be computed quickly, it is recommended to **Remove**() it instead of **Erase**()-ing.

3. 7. 7 Presentation in Local Context

In open local context, the Display functions presented above apply as well.

WARNING

The function, AIS_InteractiveObject::Display, automatically activates the object's default selection mode. When you only want to visualize an Interactive Object in open Context, you must call the second function:

```
AIS_InteractiveContext::Display.
```

You can activate or deactivate specific selection modes in local open context in several different ways:

Use the Display functions with the appropriate modes

Activate standard mode:

- ```AIS_InteractiveContext::ActivateStandardMode```
  only if a local Context is opened

- ```AIS_InteractiveContext::DeactivateStandardMode```

- ```AIS_InteractiveContext::ActivatedStandardModes```

- AIS_InteractiveContext::SetShapeDecomposition

This has the effect of activating the corresponding selection mode for all objects in Local Context, which accept decomposition into sub-shapes. Every new Object which has been loaded into the interactive context and which answers these decomposition criteria is automatically activated according to these modes.

WARNING

If you have opened a local context by loading an object with the default options (AllowShapeDecomposition = Standard_True), all objects of the "Shape" type are also activated with the same modes. You can act on the state of these "Standard" objects by using SetShapeDecomposition(Status).

Load an interactive object by the following function:

- AIS_InteractiveContext::Load.

This function allows you to load an Interactive Object whether it is visualized or not with a given selection mode, and/or with the desired decomposition option. If *AllowDecomp=TRUE* and obviously, if the interactive object is of the "Shape" type, these "standard" selection modes will be automatically activated as a function of the modes present in the Local Context.

Directly activate/deactivate selection modes on an object:

- AIS_InteractiveContext::Activate
- AIS_InteractiveContext::Deactivate.

3. 7. 8 Use of Filters

When Interactive objects have been "prepared" in local context, you can add rejection filters. The root class of objects is *SelectMgr_Filter*. The principle behind it is straightforward: a filter tests to see whether the owners (*SelectMgr_EntityOwner*) detected in mouse position by the Local context selector answer *OK*. If so, it is kept; if not, it is rejected.

You can therefore create your own class of filter objects by implementing the deferred function *IsOk()*:

Example

```
class MyFilter : public SelectMgr_Filter {
};
```

```
virtual Standard_Boolean MyFilter::IsOk
      (const Handle(SelectMgr_EntityOwner)& anObj) const =
0;
```

In *SelectMgr*, there are also Composition filters (AND Filters, OR Filters), which allow you to combine several filters. In InteractiveContext , all filters that you add are stocked in an OR filter (which answers *OK* if at least one filter answers *OK*).

There are Standard filters, which have already been implemented in several packages:

- `StdSelect_EdgeFilter`

      Filters acting on edges such as lines and circles
- `StdSelect_FaceFilter`

      Filters acting on faces such as planes, cylinders and spheres
- `StdSelect_ShapeTypeFilter`

      Filters shape types such as compounds, solids, shells and wires
- `AIS_TypeFilter`

      Acts on types of interactive objects
- `AIS_SignatureFilter`

      Acts on types and signatures of interactive objects
- `AIS_AttributeFilter`

      Acts on attributes of Interactive Objects such as color and width

Because there are specific behaviors on shapes, each new Filter class must, if necessary, redefine a function, which allows a Local Context to know if it acts on specific types of sub-shapes:

- `AIS_LocalContext::ActsOn`.

By default, this function answers *FALSE*.

WARNING
Only type filters are activated in Neutral Point. This is to make it possible to identify a specific type of visualized object. For filters to come into play, one or more object selection modes must be activated.

There are several functions to manipulate filters:

- `AIS_InteractiveContext::AddFilter`

to add a filter passed as an argument.

- `AIS_InteractiveContext::RemoveFilter`

to remove a filter passed as an argument.

- AIS_InteractiveContext::RemoveFilters

to remove all filters present.

- AIS_InteractiveContext::Filters

to get the list of filters active in a local context.

Example

```
myContext->OpenLocalContext(Standard_False);
// no object in neutral point is loaded

myContext->ActivateStandardMode(TopAbs_Face);
//activates decomposition of shapes into faces.
Handle (AIS_Shape) myAIShape = new AIS_Shape ( ATopoShape);

myContext->Display(myAIShape, 1, -
1, Standard_True, Standard_True);   //shading visualization mode, no
```
specific mode, authorization for //decomposition into sub-shapes. At this Stage,
myAIShape is decomposed into faces...

```
Handle(StdSelect_FaceFilter) Fil1= new
      StdSelect_FaceFilter(StdSelect_Revol);
Handle(StdSelect_FaceFilter) Fil2= new
      StdSelect_FaceFilter(StdSelect_Plane);

myContext->AddFilter(Fil1);
myContext->AddFilter(Fil2);
```
//only faces of revolution or planar faces will be selected

```
***

myContext->MoveTo( xpix, ypix, Vue);
```
// detects of mouse position

---

3. 7. 9 Selection Strictly Speaking.

Dynamic detection and selection are put into effect in a straightforward way. There are only a few conventions and functions to be familiar with. The functions are the same in neutral point and in open local context:

- AIS_InteractiveContext::MoveTo

    passes mouse position to Interactive Context selectors

- AIS_InteractiveContext::Select

  stocks what has been detected on the last MoveTo. Replaces the previously selected object. Empties the stack if nothing has been detected at the last move

- AIS_InteractiveContext::ShiftSelect

  if the object detected at the last move was not already selected , it is added to the list of those selected. If not, it is withdrawn. Nothing happens if you click on an empty area.

- AIS_InteractiveContext::Select

  selects everything found in the surrounding area

- AIS_InteractiveContext::ShiftSelect

  selects what was not previously in the list of selected, deselects those already present.

Highlighting of detected and selected entities is automatically managed by the Interactive Context, whether you are in neutral point or Local Context. The Highlight colors are those dealt with above. You can nonetheless disconnect this automatic mode if you want to manage this part yourself:

- `AIS_InteractiveContext::SetAutomaticHilight`
- `AIS_InteractiveContext::AutomaticHilight`

If there is no open local context, the objects selected are called CURRENT OBJECTS; SELECTED OBJECTS if there is one. Iterators allow entities to be recovered in either case. A set of functions allows you to manipulate the objects, which have been placed in these different lists.

WARNING

When a Local Context is open, you can select entities other than interactive objects (vertices, edges etc.) from decompositions in standard modes, or from activation in specific modes on specific interactive objects. Only interactive objects are stocked in the list of selected objects. You can question the Interactive context by moving the mouse. The following functions will allow you to:

- tell whether something has been detected
- tell whether it is a shape
- get the shape if the detected entity is one
- get the interactive object if the detected entity is one.

The following functions are concerned:
- `AIS_InteractiveContext::HasDetected`
- `AIS_InteractiveContext::HasDetectedShape`
- `AIS_InteractiveContext::DetectedShape`
- `AIS_InteractiveContext::DetectedInteractive`

After using the Select and ShiftSelect functions in Neutral Point, you can explore the list of selections, referred to as current objects in this context. You can:

- initiate a scan of this list
- extend the scan
- resume the scan
- get the name of the current object detected in the scan.

The following functions are concerned:
- `AIS_InteractiveContext::InitCurrent`
- `AIS_InteractiveContext::MoreCurrent`
- `AIS_InteractiveContext::NextCurrent`
- `AIS_InteractiveContext::Current`

You can:

- get the first current interactive object
- highlight current objects
- remove highlight from current objects
- empty the list of current objects in order to update it
- find the current object.

The following functions are concerned:
- `AIS_InteractiveContext::FirstCurrentObject`
- `AIS_InteractiveContext::HilightCurrents`
- `AIS_InteractiveContext::UnhilightCurrents`
- `AIS_InteractiveContext::ClearCurrents`
- `AIS_InteractiveContext::IsCurrent`.

In Local Context, you can explore the list of selected objects available. You can:
- initiate,
- extend,
- resume a scan, and then
- get the name of the selected object.

The following functions are concerned:

- `AIS_InteractiveContext::InitSelected`
- `AIS_InteractiveContext::MoreSelected`
- `AIS_InteractiveContext::NextSelected`
- `AIS_InteractiveContext::SelectedShape`.

You can:

- check to see if you have a selected shape, and if not,
- get the picked interactive object,
- check to see if the applicative object has an owner from Interactive attributed to it
- get the owner of the detected applicative entity
- get the name of the selected object.

The following functions are concerned:

- AIS_InteractiveContext::HasSelectedShape
- AIS_InteractiveContext::Interactive
- AIS_InteractiveContext::HasApplicative
- AIS_InteractiveContext::Applicative
- AIS_InteractiveContext::IsSelected.

Example

```
myAISCtx->InitSelected();
while (myAISCtx->MoreSelected())
      {
      if (myAISCtx->HasSelectedShape)
            {
            TopoDS_Shape ashape = myAISCtx-
      >SelectedShape();
            // to be able to use the picked shape
            }
      else
            {
            Handle_AIS_InteractiveObject aniobj = myAISCtx-
      >Interactive();
            // to be able to use the picked interactive object
            }
myAISCtx->NextSelected();
}
```

3. 7. 10 Remarks:

In Local Context and in the iteration loop, which allows you to recover selected entities, you have to ask whether you have selected a shape or an interactive object before you can recover the entity. If you have selected a Shape from TopoDS on decomposition in standard mode, the *Interactive ()* function returns the interactive object, which provided the selected shape. Other functions allow you to manipulate the content of Selected or Current Objects:

- erase selected objects
- display them,
- put them in the list of selections

The following functions are concerned:

- AIS_InteractiveContext::EraseSelected
- AIS_InteractiveContext::DisplaySelected
- AIS_InteractiveContext::SetSelected

You can also:

- take the list of selected objects from a local context and put it into the list of current objects in Neutral Point,
- add or remove an object from the list of selected entities,
- highlight and
- remove highlighting from a selected object
- empty the list of selected objects.

The following functions are concerned:

- AIS_InteractiveContext::SetSelectedCurrent
- AIS_InteractiveContext::AddOrRemoveSelected
- AIS_InteractiveContext::HilightSelected
- AIS_InteractiveContext::UnhilightSelected
- AIS_InteractiveContext::ClearSelected

You can highlight and remove highlighting from a current object, and empty the list of current objects.

- AIS_InteractiveContext::HilightCurrents
- AIS_InteractiveContext::UnhilightCurrents
- AIS_InteractiveContext::ClearCurrents

When you are in open Local Context, you may be lead to keep "temporary" interactive objects. This is possible using the following functions:

- AIS_InteractiveContext::KeepTemporary
- AIS_InteractiveContext::SetSelectedCurrent

The first function transfers the characteristics of the interactive object seen in its local context (visualization mode etc.) to the neutral point. When the local context is closed, the object does not disappear. The second allows the selected object to become the current object when you close the local context.

You can also want to modify in a general way the state of the local context before continuing a selection (emptying objects, removing filters, standard activation modes). To do that, you must use the following function:

- AIS_InteractiveContext::ClearLocalContext

3. 7. 11 Advice on Using Local Contexts

The possiblities of use for local contexts are numerous depending on the type of operation that you want to perform:

- working on all visualized interactive objects,
- working on only a few objects,
- working on a single object.

1. When you want to work on one type of entity, you should open a local context with the option UseDisplayedObjects set to FALSE. Some functions which allow you to recover the visualized interactive objects, which have a given Type, and Signature from the "Neutral Point" are:

```
AIS_InteractiveContext::DisplayedObjects
(AIS_ListOfInteractive& aListOfIO) const;

AIS_InteractiveContext::DisplayedObjects
(const AIS_KindOfInteractive WhichKind,
 const Standard_Integer WhichSignature,
   AIS_ListOfInteractive& aListOfIO) const;
```

At this stage, you only have to load the functions Load, Activate, and so on.

2. When you open a Local Context with default options, you must keep the following points in mind:

The Interactive Objects visualized at Neutral Point are activated with their default selection mode. You must deactivate those, which you do not want to use.

The Shape Type Interactive Objects are automatically decomposed into sub-shapes when standard activation modes are launched.

The "temporary" Interactive Objects present in the Local Contexts are not automatically taken into account. You have to load them manually if you want to use them.

The stages could be the following:
1. Open a Local Context with the right options;
2. Load/Visualize the required complementary objects with the desired activation modes.
3. Activate Standard modes if necessary
4. Create its filters and add them to the Local Context
5. Detect/Select/recover the desired entities
6. Close the Local Context with the adequate index.

It is useful to create an INTERACTIVE EDITOR, to which you pass the Interactive Context. This will take care of setting up the different contexts of selection/presentation according to the operation, which you want to perform.

Example

You have visualized several types of interactive objects: *AIS_Points*, *AIS_Axes*, *AIS_Trihedrons*, and *AIS_Shapes*.

For your applicative function, you need an axis to create a revolved object. You could obtain this axis by identifying:

- an axis which is already visualized,

- 2 points,

- a rectilinear edge on the shapes which are present,

- a cylindrical face on the shapes (You will take the axis of this face)

```
myIHMEditor::myIHMEditor
      (const Handle(AIS_InteractiveContext)& Ctx,
       ....) :
       myCtx(Ctx),
      ...


{
}

myIHMEditor::PrepareContext()
{
myIndex =myCtx->OpenLocalContext();

//the filters

Handle(AIS_SignatureFilter) F1 = new
       AIS_SignatureFilter(AIS_KOI_Datum, AIS_SD_Point);
//filter on the points

Handle(AIS_SignatureFilter) F2 = new
      AIS_SignatureFilter(AIS_KOI_Datum, AIS_SD_Axis);
//filters on the axes.

Handle(StdSelect_FaceFilter) F3 = new
       StdSelect_FaceFilter(AIS_Cylinder);
//cylindrical face filters

//...

// activation of standard modes on the shapes..
myCtx->ActivateStandardMode(TopAbs_FACE);
myCtx->ActivateStandardMode(TopAbs_VERTEX);
```

```
myCTX->Add(F1);
myCTX->Add(F2);
myCTX->Add(F3);


// at this point, you can call the selection/detection function
}


void myIHMEditor::MoveTo(xpix, ypix, Vue)


{
myCTX->MoveTo(xpix, ypix, vue);
// the highlight of what is detected is automatic.
}

Standard_Boolean myIHMEditor::Select()
{
// returns true if you should continue the selection

        myCTX->Select();
        myCTX->InitSelected();
        if(myCTX->MoreSelected())
                {
                 if(myCTX->HasSelectedShape())

            { const TopoDS_Shape& sh = myCTX-
        >SelectedShape();
            if( vertex){
                    if(myFirstV...)
                    {
                    //if it's the first vertex, you stock it, then you deactivate
            the faces and only keep the filter on the points:
                    mypoint1 = ....;
                    myCtx->RemoveFilters();
                    myCTX-
            >DeactivateStandardMode(TopAbs_FACE);
                    myCtx->Add(F1);
                    // the filter on the AIS_Points
                    myFirstV = Standard_False;
                    return Standard_True;
                     }
                    else
                     {
                    mypoint2 =...;
                    // construction of the axis return Standard_False;
                    }
                }
             else
              {
            //it is a cylindrical face : you recover the axis; visualize it; and
            stock it.
                return Standard_False;
```

```
                        }
                          }
                        // it is not a shape but is no doubt a point.
                else
                {
                Handle(AIS_InteractiveObject)
                    SelObj = myCTX->SelectedInteractive();
                    if(SelObj->Type()==AIS_KOI_Datum)
                    {
                            if(SelObj->Signature()==1)
                            {
                                    if (firstPoint)
                                    {
                                    mypoint1 =...
                                            return Standard_True;
                                    }
                                    else
                                    {
                                    mypoint2 = ...;
                                    //construction of the axis, visualization, stocking
                                    return Standard_False;
                                    }
                            }

                            else
                            {
                            // you have selected an axis; stock the axis
                            return Standard_False;
                            }
                            }
                            }
                            }
                            }
void myIHMEditor::Terminate()
{
myCtx->CloseLocalContext(myIndex);
...
}
```

ANNEX I: Standard Interactive Object Classes in AIS DATUMS:

AIS_Point
AIS_Axis
AIS_Line
AIS_Circle
AIS_Plane
AIS_Trihedron : 4 selection modes

- mode 0 : selection of a trihedron
- mode 1 : selection of the origin of the trihedron
- mode 2 : selection of the axes
- mode 3 : selection of the planes XOY, YOZ, XOZ

when you activate one of modes 1 2 3 4 , you pick AIS objects of type:

- AIS_Point
- AIS_Axis (and information on the type of axis)
- AIS_Plane (and information on the type of plane).

AIS_PlaneTrihedron offers 3 selection modes:

- mode 0 : selection of the whole trihedron
- mode 1 : selection of the origin of the trihedron
- mode 2 : selection of the axes - same remarks as for the Trihedron.

Warning

For the presentation of planes and trihedra, the default unit of length is millimeter, and the default value for the representation of axes is 100. If you modify these dimensions, you must temporarily recover the object DRAWER. From inside it, take the Aspects in which the values for length are stocked (PlaneAspect for the plane, FirstAxisAspect for trihedra), and change these values inside these Aspects. Finally, recalculate the presentation.

OBJECTS

AIS_Shape : 3 visualization modes :

- mode 0 : Line (default mode)
- mode 1 : Shading (depending on the type of shape)
- mode 2 : Bounding Box

7 maximum selection modes, depending on the complexity of the shape :

- mode 0 : selection of the AIS_Shape
- mode 1 : selection of the vertices
- mode 2 : selection of the edges
- mode 3 : selection of the wires
- mode 4 : selection of the faces

- mode 5 : selection of the shells
- mode 6 : selection of the constituent solids.

AIS_Triangulation: Simple interactive object for displaying triangular mesh contained in Poly_Triangulation container.

AIS_ConnectedInteractive: Interactive Object connecting to another interactive object reference, and located elsewhere in the viewer makes it possible not to calculate presentation and selection, but to deduce them from your object reference.

AIS_ConnectedShape: Object connected to interactive objects having a shape; this class has the same decompositions as AIS_Shape. What's more, it allows a presentation of hidden parts, which are calculated automatically from the shape of its reference.

AIS_MultipleConnectedInteractive: Object connected to a list of interactive objects (which can also be Connected objects. It does not require memory hungry calculations of presentation)

AIS_MultipleConnectedShape: Interactive Object connected to a list of interactive objects having a Shape (AIS_Shape, AIS_ConnectedShape, AIS_MultipleConnectedShape). The presentation of hidden parts is calculated automatically.

AIS_TexturedShape: Interactive Object that supports texture mapping. It is constructed as a usual AIS_Shape, but has additional methods that allow to map a texture on it.

MeshVS_Mesh: Interactive Object that represents meshes, it has a data source that provides geometrical information (nodes, elements) and can be built up from the source data with a custom presentation builder.

RELATIONS

The list is not exhaustive.

AIS_ConcentricRelation

AIS_FixRelation

AIS_IdenticRelation

AIS_ParallelRelation

AIS_PerpendicularRelation

AIS_Relation

AIS_SymmetricRelation

AIS_TangentRelation

DIMENSIONS

AIS_AngleDimension

AIS_Chamf2dDimension

AIS_Chamf3dDimension

AIS_DiameterDimension

AIS_DimensionOwner

AIS_LengthDimension

AIS_OffsetDimension

AIS_RadiusDimension

MeshVS_Mesh

MeshVS_Mesh is an Interactive Object that represents meshes.

This object differs from the AIS_Shape as its geometrical data is supported by the data source (*MeshVS_DataSource*) that describes nodes and elements of the object. As a result, you can provide your own data source.

However, the *DataSource* does not provide any information on attributes, for example nodal colors, but you can apply them in a special way – by choosing the appropriate presentation builder.

The presentations of MeshVS_Mesh are built with the presentation builders (*MeshVS_PrsBuilder*). You can choose between the builders to represent the object in a different way. Moreover, you can redefine the base builder class and provide your own presentation builder.

You can add/remove builders using the following methods:

- `MeshVS_Mesh::AddBuilder`
  `(const Handle (MeshVS_PrsBuilder) &Builder,`
  `Standard_Boolean TreatAsHilighter)`
- `MeshVS_Mesh::RemoveBuilder (const Standard_Integer Index)`
- `MeshVS_Mesh::RemoveBuilderById`
  `(const Standard_Integer Id)`

There is a set of reserved display and highlighting mode flags for MeshVS_Mesh. Mode value is a number of bits that allows you to select additional display parameters and combine the following mode flags:

- `MeshVS_DMF_WireFrame`
- `MeshVS_DMF_Shading`
- `MeshVS_DMF_Shrink`

  base modes: display mesh in wireframe, shading, shrink modes.

- `MeshVS_DMF_VectorDataPrs`
- `MeshVS_DMF_NodalColorDataPrs`
- `MeshVS_DMF_ElementalColorDataPrs`
- `MeshVS_DMF_TextDataPrs`
- `MeshVS_DMF_EntitiesWithData`

  represent different kinds of data

- MeshVS_DMF_DeformedPrsWireFrame
- MeshVS_DMF_DeformedPrsShading
- MeshVS_DMF_DeformedPrsShrink
  display deformed mesh in wireframe, shading or shrink modes

- MeshVS_DMF_SelectionPrs
- MeshVS_DMF_HilightPrs
  selection and hilighting

- MeshVS_DMF_User
  user-defined mode

These values will be used by the presentation builder.

There is also a set of selection modes flags that can be grouped in a combination of bits:

- MeshVS_SMF_0D
- MeshVS_SMF_Link
- MeshVS_SMF_Face
- MeshVS_SMF_Volume
- MeshVS_SMF_Element
  Element: 0D, Link, Face and Volume grouped as a bit mask

- MeshVS_SMF_Node
- MeshVS_SMF_All
  All: Element and Node grouped as a bit mask

- MeshVS_SMF_Mesh
- MeshVS_SMF_Group

Such an object, for example, can be used for displaying the object, stored in the STL file format:

Example

```
// read the data and create a data source
Handle (StlMesh_Mesh) aSTLMesh = RWStl::ReadFile (aFileName);
Handle (XSDRAWSTLVRML_DataSource) aDataSource =
                    new XSDRAWSTLVRML_DataSource (aSTLMesh);

// create mesh
Handle (MeshVS_Mesh) aMesh = new MeshVS();
aMesh->SetDataSource (aDataSource);
```

```
// use default presentation builder
Handle (MeshVS_MeshPrsBuilder) aBuilder =
        new MeshVS_MeshPrsBuilder (aMesh);
aMesh->AddBuilder (aBuilder, Standard_True);
```

MeshVS_NodalColorPrsBuilder allows you to represent a mesh with a color scaled texture mapped on it. To do this you should define a color map for the color scale, pass this map to the presentation builder, and define an appropriate value in the range of 0.0 – 1.0 for every node.

The following example demonstrates how you can do this (**please check,** if the view has been set up to display textures):

Example

```
// assign nodal builder to the mesh
Handle (MeshVS_NodalColorPrsBuilder) aBuilder =
  new MeshVS_NodalColorPrsBuilder
    (aMesh, MeshVS_DMF_NodalColorDataPrs | MeshVS_DMF_OCCMask);
aBuilder->UseTexture (Standard_True);

// prepare color map
Aspect_SequenceOfColor aColorMap;
aColorMap.Append ((Quantity_NameOfColor) Quantity_NOC_RED);
aColorMap.Append ((Quantity_NameOfColor) Quantity_NOC_BLUE1);

// assign color scale map values (0..1) to nodes
TColStd_DataMapOfIntegerReal aScaleMap;
…
  // iterate through the nodes and add an node id and an appropriate
  // value to the map
  aScaleMap.Bind (anId, aValue);

// pass color map and color scale values to the builder
aBuilder->SetColorMap (aColorMap);
aBuilder->SetInvalidColor (Quantity_NOC_BLACK);
aBuilder->SetTextureCoords (aScaleMap);
aMesh->AddBuilder (aBuilder, Standard_True);
```

ANNEX II : Principles of Dynamic Selection

The idea of dynamic selection is to represent the entities, which you want to select by a bounding box in the actual 2D space of the selection view. The set of these zones is ordered by a powerful sorting algorithm. To then find the applicative entities actually detected at this position, all you have to do is read which rectangles are touched at mouse position (X,Y) of the view, and judiciously reject some of the entities which have provided these rectangles.

How to go from the objects to 2D boxes

An intermediary stage consists in representing what you can make selectable by means of sensitive primitives and owners, entities of a high enough level to be known by the selector mechanisms.

The sensitive primitive is capable of:

- giving a 2D bounding box to the selector.

- answering the rejection criteria positively or negatively by a "Matches" function.

- being projected from 3D in the 2D space of the view if need be.

- returning the owner which it will represent in terms of selection.

A set of standard sensitive primitives exists in Select3D packages for 3D primitives.

The owner is the entity, which makes it possible to link the sensitive primitives and the objects that you really wanted to detect. It stocks the diverse information, which makes it possible to find objects. An owner has a priority (*5* by default), which you can modulate, so as to make one entity more selectable than another.
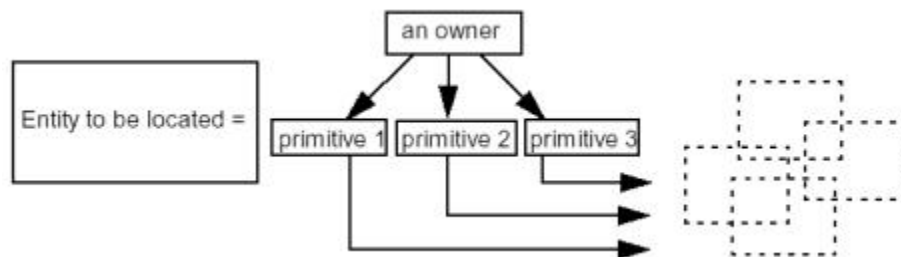
Implementation in an interactive/selectable object

1. Define the number of selection modes possible, i.e. what you want to identify by activating each of the selection modes. Example: for an interactive object representing a topological shape,

mode 0: selection of the interactive object itself

mode 1: selection of the vertices

mode 2: selection of the edges

mode 3: selection of the wires

mode 4: selection of the faces detectable

2. For each selection mode of an interactive object, "model" the set of entities, which you want to locate by these primitives and these owners.

3. There exists an "owner" root class, *SelectMgr_EntityOwne*r, containing a reference to a selectable object, which has created it. If you want to stock its information, you have to create classes derived from this root class. Example: for shapes, there is the *StdSelect_BRepOwner* class, which can save a TopoDS shape as a field as well as the Interactive Object.

4. The set of sensitive primitives which has been calculated for a given mode is stocked in *SelectMgr_Selection*.

5. For an Interactive object, the modeling is done in the *ComputeSelection* virtual function.

Example

Let an interactive object represent a box.
We are interested in having 2 location modes:

   • mode 0: location of the whole box.

   • mode 1: location of the edges on the box.

For the first mode, all sensitive primitives will have the same owner, which will represent the interactive object. In the second case, we have to create an owner for each edge, and this owner will have to contain the index for the edge, which it represents. You will create a class of owner, which derives from *SelectMgr_EntityOwner*.

The *ComputeSelection* function for the interactive box can have the following form:

```
void InteractiveBox::ComputeSelection
      (const Handle(SelectMgr_Selection)& Sel,
       const Standard_Integer Mode)
{
      switch(Mode)
            {
            case 0:
            //locating the whole box by making its faces sensitive...
            {
      Handle(SelectMgr_EntityOwner) Ownr = new
            SelectMgr_EntityOwner(this,5);
      for(Standard_Integer I=1;I<=Nbfaces;I++)
```

```
      {
      //Array is a TColgp_Array1OfPnt: which represents the array of vertices.
    Sensitivity is
Select3D_TypeOfSensitivity value
      Sel->Add(new
Select3D_SensitiveFace(Ownr, Array, Sensitivity));
      }
      break;
    }
  case 1:
      // locates the edges
      {
        for(Standard_Integer i=1; i<=12; i++)
            {
            // 1 owner per edge...
            Handle(mypk_EdgeOwner) Ownr =
                new mypk_EdgeOwner(this, i, 6);
                //6->priority
                Sel->Add(new Select3D_SensitiveSegment
                    (Ownr, firstpt(i), lastpt(i)));
            }
            break;
        }
    }
}
```

How It Works Concretely

Selectable objects are loaded in the selection manager, which has one or more
selectors; in general, we suggest assigning one selector per viewer. All you have to
do afterwards is to activate or deactivate the different selection modes for selectable
objects. The *SelectionManager* looks after the call to the *ComputeSelection*
functions for different objects. NOTE: This procedure is completely hidden if you use
the interactive contexts of AIS (see section 3.3, Contexts)

Example

//We have several " interactive boxes " box1, box2, box3;

```
  Handle(SelectMgr_SelectionManager) SM = new
  SelectMgr_SelectionManager();
  Handle(StdSelect_ViewerSelector3d) VS = new
  StdSelect_ViewerSelector3d();

      SM->Add(VS);
      SM->Load(box1); SM->Load(box2); SM->Load(box3);
```

```
                    // box load.
                    SM->Activate(box1, 0, VS);
                    // activates mode 0 of box 1 in the selector VS
                    SM->Activate(box1, 1, VS);
                    M->Activate(box3, 1, VS);

VS->Pick(xpix, ypix, vue3d)
// detection of primitives by mouse position.

Handle(EntityOwner) POwnr = VS->OnePicked();
// picking of the "best" owner detected

for(VS->Init();VS->More();VS->Next())
   {
   VS->Picked();
   // picking of all owners detected
     }
   SM->Deactivate(box1);
   // deactivate all active modes of box1
```

Sensitive primitive segments

Projections of sensitive primitives
+ sorting of boxes in view

owner

owner

Ok -> back to owner, then to
selected edge

Detection of a zone, back
to the primitive, rejection tests
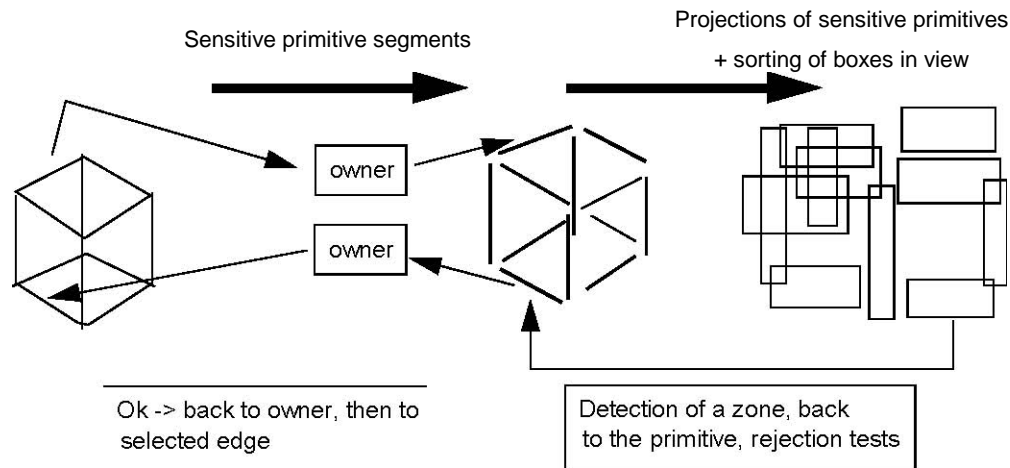
1st activation of the box's mode 1: calculation of sensitive primitives + 3D/2D projection + sorting

deactivation of mode: only updated by sorting

rotation of the view: only projection + sorting of active primitives

modification of the box -> Recalculation of the active selection, recalculation flag on the inactive ones + 3D/2D projection + sorting

4. 3D Presentations

4. 1 Glossary of 3D terms

4. 1. 1 From Graphic3d

Primitive	A primitive is a drawable element. It has a definition in 3D space. Primitives can either be lines, faces, text, or markers. Once displayed markers and text remain the same size. Lines and faces can be modified e.g. zoomed. Primitives must be stored in a group.
Group	A set of primitives and attributes on those primitives. Primitives and attributes may be added to a group but cannot be removed from a group, except by erasing them globally. A group can have a pick identity.
Structure	Manages a set of groups. The groups are mutually exclusive. A structure can be edited, adding or removing groups. A structure can reference other structures to form a hierarchy. It has a default (identity) transformation and other transformations may be applied to it (rotation, translation, scale, etc). It has no default attributes for the primitive lines, faces, markers, and text. Attributes may be set in a structure but they are overridden by the attributes in each group. Each structure has a display priority associated with it, which rules the order in which it is redrawn in a 3D viewer. If the visualization mode is incompatible with the view it is not displayed in that view, e.g. a shading-only object is not visualized in a wireframe view.

4. 1. 2 From V3d

View	A view is defined by a view orientation, a view mapping, and a context view.
Viewer	Manages a set of views.
View orientation	Defines the manner in which the observer looks at the scene in terms of View Reference Coordinates.
View mapping	Defines the transformation from View Reference Coordinates to the Normalized Projection Coordinates. This follows the Phigs scheme.

Light	There are five kinds of light source - ambient, headlight, directional, positional and spot. The light is only activated in a shading context in a view.
Depth-cueing	Reduces the color intensity for the portion of an object further away from the eye to give the impression of depth. This is used for wireframe objects. Shaded objects do not require this.
Z-Buffering	This is a form of hidden surface removal in shading mode only. This is always active for a view in the shading mode. It cannot be suppressed.
Anti-aliasing	This mode attempts to improve the screen resolution by drawing lines and curves in a mixture of colors so that to the human eye the line or curve is smooth. The quality of the result is linked to the quality of the algorithm used by the workstation hardware.

4. 2 Creating a 3D scene

To create 3D graphic objects and display them on the screen, follow the procedure below:

1. Create attributes.

2. Create a 3D viewer..

3. Create a view.

4. Create an interactive context.

5. Create interactive objects.

6. Create primitives in the interactive object

7. Display the interactive object.

4. 2. 1 Create attributes

Create colors.

Example

```
Quantity_Color Black (Quantity_NOC_BLACK);
Quantity_Color Blue (Quantity_NOC_MATRABLUE);
Quantity_Color Brown (Quantity_NOC_BROWN4);
Quantity_Color Firebrick (Quantity_NOC_FIREBRICK);
Quantity_Color Forest (Quantity_NOC_FORESTGREEN);
Quantity_Color Gray (Quantity_NOC_GRAY70);
Quantity_Color
```

```
      MyColor (0.99, 0.65, 0.31, Quantity_TOC_RGB);
Quantity_Color Beet (Quantity_NOC_BEET);
Quantity_Color White (Quantity_NOC_WHITE);
```

Create line attributes.

Example

```
Handle(Graphic3d_AspectLine3d) CTXLBROWN =
      new Graphic3d_AspectLine3d ();
Handle(Graphic3d_AspectLine3d) CTXLBLUE =
      new Graphic3d_AspectLine3d ();
Handle(Graphic3d_AspectLine3d) CTXLWHITE =
      new Graphic3d_AspectLine3d();
CTXLBROWN->SetColor (Brown);
CTXLBLUE->SetColor (Blue);
CTXLWHITE->SetColor (White);
```

Create marker attributes.

Example

```
Handle(Graphic3d_AspectMarker3d) CTXMFIREBRICK =
      new Graphic3d_AspectMarker3d();
CTXMFIREBRICK->SetColor (Firebrick);
CTXMFIREBRICK->SetScale (1.0);
CTXMFIREBRICK->SetType (Aspect_TOM_BALL);
```

Create facet attributes.

Example

```
Handle(Graphic3d_AspectFillArea3d) CTXF =
      new Graphic3d_AspectFillArea3d ();
Graphic3d_MaterialAspect BrassMaterial
(Graphic3d_NOM_BRASS);
Graphic3d_MaterialAspect GoldMaterial
(Graphic3d_NOM_GOLD);
CTXF->SetInteriorStyle (Aspect_IS_SOLID);
```

```
CTXF->SetInteriorColor (MyColor);
CTXF->SetDistinguishOn ();
CTXF->SetFrontMaterial (GoldMaterial);
CTXF->SetBackMaterial (BrassMaterial);
CTXF->SetEdgeOn ();
```

Create text attributes.

Example

```
Handle(Graphic3d_AspectText3d) CTXT =
     new Graphic3d_AspectText3d
     (Forest, Graphic3d_NOF_ASCII_MONO, 1., 0.);
```

4. 2. 2 Create a 3D Viewer (a Windows example)

Example
```
Handle(Aspect_DisplayConnection) aDisplayConnection;
Handle(Graphic3d_GraphicDriver) aGraphicDriver =
     Graphic3d::InitGraphicDriver (aDisplayConnection);
TCollection_ExtendedString aName("3DV");
myViewer =
     new V3d_Viewer (aGraphicDriver, aName.ToExtString (),
     "");
myViewer -> SetDefaultLights ();
myViewer -> SetLightOn ();
```

4. 2. 3 Create a 3D view (a Windows example)

It is assumed that a valid Windows window may already be accessed via the method GetSafeHwnd().

Example

Handle (WNT_Window) aWNTWindow;
aWNTWindow = new WNT_Window (GetSafeHwnd());
myView = myViewer -> CreateView();
myView -> SetWindow (a WNTWindow);

4. 2. 4 Create an interactive context

Example

```
myAISContext = new AIS_InteractiveContext (myViewer);
```

You are now able to display interactive objects such as an AIS_Shape.

Example

```
TopoDS_Shape aShape = BRepAPI_MakeBox(10, 20, 30)_Solid();
Handle (AIS_Shape) aAISShape = new AIS_Shape(aShape);
myAISContext -> Display (aAISShape);
```

4. 2. 5 Create your own interactive object

Follow the procedure below to compute the presentable object:

1. Build a presentable object inheriting from AIS_InteractiveObject (refer to the Chapter on Presentable Objects).

2. Reuse the Prs3d_Presentation provided as an argument of the compute methods.

NOTE

There are two compute methods: one for a 'standard representation, and the other for a 'degenerated representation, i.e. in hidden line removal and wireframe modes.

Example of the compute methods

```
Void
myPresentableObject::Compute
      (const Handle(PrsMgr_PresentationManager3d)&
            aPresentationManager,
            const Handle(Prs3d_Presentation)& aPrs,
            const Standard_Integer aMode)
```

```
(
//...
)



void
myPresentableObject::Compute
              (const Handle(Prs3d_Projector)&,
        const Handle(Prs3d_Presentation)& aPrs)
(
//...
)
```

4. 2. 6 Create primitives in the interactive object

Get the group used in Prs3d_Presentation.

Example

```
Handle(Graphic3d_Group) TheGroup =
Prs3d_Root::CurrentGroup(aPrs);
```

Update the group attributes.

Example

```
TheGroup -> SetPrimitivesAspect(CTXLBLUE);
```

Create two triangles in group TheGroup.

Example

```
Standard_Integer aNbTria = 2;
Handle(Graphic3d_ArrayOfTriangles) aTriangles = new
Graphic3d_ArrayOfTriangles(3 * aNbTria, 0, Standard_True);
Standard_Integer anIndex;
```

```
for (anIndex = 1; anIndex <= aNbTria; nt++)
{
  aTriangles->AddVertex(anIndex * 5., 0., 0., 1., 1., 1.);
  aTriangles->AddVertex(anIndex * 5 + 5, 0., 0., 1., 1.,
1.);
  aTriangles->AddVertex(anIndex * 5 + 2.5, 5., 0., 1., 1.,
1.);
}
TheGroup->BeginPrimitives ();
mygroup->AddPrimitiveArray(aTriangles);
TheGroup->EndPrimitives ();
```

The BeginPrimitives () and EndPrimitives () methods are used when creating a set
of various primitives in the same group.

Use the polyline function to create a boundary box for the Struct structure in group
TheGroup.

Example

```
Standard_Real Xm, Ym, Zm, XM, YM, ZM;
Struct->MinMaxValues (Xm, Ym, Zm, XM, YM, ZM);

Handle(Graphic3d_ArrayOfPolylines)    aPolylines    =    new
Graphic3d_ArrayOfPolylines(16, 4);
aPolylines->AddBound (4);
aPolylines->AddVertex (Xm, Ym, Zm);
aPolylines->AddVertex (Xm, Ym, ZM);
aPolylines->AddVertex (Xm, YM, ZM);
aPolylines->AddVertex (Xm, YM, Zm);
aPolylines->AddBound (4);
aPolylines->AddVertex (Xm, Ym, Zm);
aPolylines->AddVertex (XM, Ym, Zm);
aPolylines->AddVertex (XM, Ym, ZM);
aPolylines->AddVertex (XM, YM, ZM);
aPolylines->AddBound (4);
aPolylines->AddVertex (XM, YM, Zm);
aPolylines->AddVertex (XM, Ym, Zm);
aPolylines->AddVertex (XM, YM, Zm);
aPolylines->AddVertex (Xm, YM, Zm);
aPolylines->AddBound (4);
aPolylines->AddVertex (Xm, YM, ZM);
aPolylines->AddVertex (XM, YM, ZM);
aPolylines->AddVertex (XM, Ym, ZM);
aPolylines->AddVertex (Xm, Ym, ZM);

TheGroup->BeginPrimitives ();
```

```
TheGroup->AddPrimitiveArray(aPolylines);
TheGroup->EndPrimitives ();
```

Create text and markers in group TheGroup.

Example

```
static char *texte[3] = {  "Application title",
              "My company",
              "My company address." };
Graphic3d_Array10fVertex Tpts8 (0, 1);
Tpts8(0).SetCoord (-40.0, -40.0, -40.0);
Tpts8(1).SetCoord (40.0, 40.0, 40.0);
TheGroup->MarkerSet (Tpts8);
Graphic3d_Vertex Marker (0.0, 0.0, 0.0);

for (i=0; i<=2; i++) {
  Marker.SetCoord (-(Standard_Real)i*4 + 30,
                    (Standard_Real)i*4,
                   -(Standard_Real)i*4);
  TheGroup->Text (texte[i], Marker, 20.);
}
```

5. 3D Resources

The 3D resources include the Graphic3d and V3d packages.

5. 1 Graphic3D

5. 1. 1 Overview

The **Graphic3d** package is used to create 3D graphic objects in a 3D viewer. These objects called **structures** are made up of groups of primitives and attributes. A group is the smallest editable element of a structure. A transformation can be applied to a structure. Structures can be connected to form a tree of structures, composed by transformations. Structures are globally manipulated by the viewer.

5. 1. 2 Provided services

Graphic structures can be:
- Displayed,
- Highlighted,
- Erased,
- Transformed,
- Connected to form a tree.

There are classes for:
- Visual attributes for lines, faces, markers, text, materials,
- Vectors and vertices,
- Graphic objects, groups, and structures.

5. 1. 3 About the primitives

Markers
- Have one or more vertices,
- Have a type, a scale factor, and a color,
- Have a size, shape, and orientation independent of transformations.

Polygons
- Have one closed boundary,
- Have at least three vertices,
- Are planar and have a normal,
- Have interior attributes - style, color, front and back material, texture and reflection ratio,
- Have a boundary with the following attributes - type, width scale factor, color. The boundary is only drawn when the interior style is hollow.

Polygons with holes

- Have multiple closed boundaries, each one with at least three vertices,
- Are planar and have a normal,
- Have interior attributes - style, color, front and back material,
- Have a boundary with the following attributes - type, width scale factor, color. The boundary is only drawn when the interior style is hollow.

Polylines

- Have two or more vertices,
- Have the following attributes - type, width scale factor, color.

Text

- Has geometric and non-geometric attributes,
- Geometric attributes - character height, character up vector, text path, horizontal and vertical alignment, orientation, three-dimensional position, zoomable flag
- Non-geometric attributes - text font, character spacing, character expansion factor, color.

5. 1. 4 Primitive arrays

Primitive arrays are a more efficient approach to describe and display the primitives from the aspects of memory usage and graphical performance. The key feature of the primitive arrays is that the primitive data is not duplicated. For example, two polygons could share the same vertices, so it is more efficient to keep the vertices in a single array and specify the polygon vertices with indices of this array. In addition to such kind of memory savings, the OpenGl graphics driver provides the Vertex Buffer Objects (VBO). VBO is a sort of video memory storage that can be allocated to hold the primitive arrays, thus making the display operations more efficient and releasing the RAM memory.

The Vertex Buffer Objects are enabled by default, but VBOs availability depends on the implementation of OpenGl. If the VBOs are unavailable or there is not enough video memory to store the primitive arrays, the RAM memory will be used to store the arrays.

The Vertex Buffer Objects can be disabled at the application level. You can use the following method to enable/disable VBOs:

- `void Graphic3d_GraphicDriver::EnableVBO`
     `(const Standard_Boolean status)`

The following example shows how to disable the VBO support:

Example

```
// get the graphic driver
Handle (Graphic3d_GraphicDriver) aDriver =
  myAISContext->CurrentViewer()->Driver();

// disable VBO support
aDriver->EnableVBO (Standard_False);
```

Please note that the use of Vertex Buffer Objects requires the application level primitive data provided by the Graphic3d_ArrayOfPrimitives to be transferred to the video memory. TKOpenGl transfers the data and releases the Graphic3d_ArrayOfPrimitives internal pointers to the primitive data. Thus it might be necessary to pay attention to such kind of behaviour, as the pointers could be modified (nullified) by the TKOpenGl.

The different types of primitives could be presented with the following primitive arrays:
- Graphic3d_ArrayOfPoints,
- Graphic3d_ArrayOfPolygons,
- Graphic3d_ArrayOfPolylines,
- Graphic3d_ArrayOfQuadrangles,
- Graphic3d_ArrayOfQuadrangleStrips,
- Graphic3d_ArrayOfSegments,
- Graphic3d_ArrayOfTriangleFans,
- Graphic3d_ArrayOfTriangles,
- Graphic3d_ArrayOfTriangleStrips.

The Graphic3d_ArrayOfPrimitives is a base class for these primitive arrays.

There is a set of similar methods to add vertices to the primitive array:
- Standard_Integer Graphic3d_ArrayOfPrimitives::AddVertex

These methods take vertex coordinates as an argument and allow you to define the color, the normal and the texture coordinates assigned to the vertex. The return value is the actual number of vertices in the array.

You can also modify the values assigned to the vertex or query these values by the vertex index:
- void Graphic3d_ArrayOfPrimitives::SetVertice
- void Graphic3d_ArrayOfPrimitives::SetVertexColor
- void Graphic3d_ArrayOfPrimitives::SetVertexNormal
- void Graphic3d_ArrayOfPrimitives::SetVertexTexel

- gp_Pnt Graphic3d_ArrayOfPrimitives::Verticie
- gp_Dir Graphic3d_ArrayOfPrimitives::VertexNormal
- gp_Pnt2d Graphic3d_ArrayOfPrimitives::VertexTexel
- Quantity_Color Graphic3d_ArrayOfPrimitives::VertexColor
- void Graphic3d_ArrayOfPrimitives::Verticie
- void Graphic3d_ArrayOfPrimitives::VertexNormal
- void Graphic3d_ArrayOfPrimitives::VertexTexel
- void Graphic3d_ArrayOfPrimitives::VertexColor

The following example shows how to define an array of points:

Example

// create an array
```
Handle (Graphic3d_ArrayOfPoints) anArray =
          new Graphic3d_ArrayOfPoints (aVerticiesMaxCount);
```

// add vertices to the array
```
anArray->AddVertex (10.0, 10.0, 10.0);
anArray->AddVertex (0.0, 10.0, 10.0);
```

// add the array to the structure
```
Handle (Graphic3d_Group) aGroup =
                         Prs3d_Root::CurrentGroup (aPrs);
aGroup->BeginPrimitives ();
aGroup->AddPrimitiveArray (anArray);
aGroup->EndPrimitives ();
```

If the primitives share the same vertices (polygons, triangles, etc) then you can define them as indices of the vertices array. The following method allows you to define the primitives by the indices:

- Standard_Integer Graphic3d_ArrayOfPrimitives::AddEdge

This method adds an "edge" in the range [1, VertexNumber()] in the array.
It is also possible to query the vertex defined by an edge:

- Standard_Integer Graphic3d_ArrayOfPrimitives::Edge

The following example shows how to define an array of triangles:

Example

// create an array
```
Standard_Boolean IsNormals     = Standard_False;
Standard_Boolean IsColors      = Standard_False;
```

```
Standard_Boolean IsTextureCrds = Standard_False;
Handle (Graphic3d_ArrayOfTriangles) anArray =
          new Graphic3d_ArrayOfTriangles (aVerticesMaxCount,
                                          aEdgesMaxCount,
                                          IsNormals,
                                          IsColors,
                                          IsTextureCrds);
```
// add vertices to the array
```
anArray->AddVertex (-1.0,  0.0,  0.0);    // vertex 1
anArray->AddVertex ( 1.0,  0.0,  0.0);    // vertex 2
anArray->AddVertex ( 0.0,  1.0,  0.0);    // vertex 3
anArray->AddVertex ( 0.0, -1.0,  0.0);    // vertex 4
```

// add edges to the array
```
anArray->AddEdge (1);   // first triangle
anArray->AddEdge (2);
anArray->AddEdge (3);
anArray->AddEdge (1);   // second triangle
anArray->AddEdge (2);
anArray->AddEdge (4);
```

// add the array to the structure
```
Handle (Graphic3d_Group) aGroup =
                         Prs3d_Root::CurrentGroup (aPrs);
aGroup->BeginPrimitives ();
aGroup->AddPrimitiveArray (anArray);
aGroup->EndPrimitives ();
```

If the primitive array presents primitives built from sequential sets of vertices, for example polygons, then you can specify the bounds, or the number of vertices for each primitive. You can use the following method to define the bounds and the color for each bound:

- `Standard_Integer Graphic3d_ArrayOfPrimitives::AddBound`

This method returns the actual number of bounds.

It is also possible to set the color and query the number of edges in the bound and bound color:

- `Standard_Integer Graphic3d_ArrayOfPrimitives::Bound`
- `Quantity_Color Graphic3d_ArrayOfPrimitives::BoundColor`
- `void Graphic3d_ArrayOfPrimitives::BoundColor`

The following example shows how to define an array of polygons:

Example

// create an array
```
Standard_Boolean IsNormals     = Standard_False;
Standard_Boolean IsVertexColors = Standard_False;
Standard_Boolean IsFaceColors   = Standard_False;
Standard_Boolean IsTextureCrds  = Standard_False;
Handle (Graphic3d_ArrayOfPolygons) anArray =
          new Graphic3d_ArrayOfPolygons (aVerticesMaxCount,
                                         aBoundsMaxCount,
                                         aEdgesMaxCount,
                                         IsNormals,
                                         IsVertexColors,
                                         IsFaceColors,
                                         IsTextureCrds);
```

// add bounds to the array, first polygon
```
anArray->AddBound (3);
anArray->AddVertex (-1.0,  0.0,  0.0);
anArray->AddVertex ( 1.0,  0.0,  0.0);
anArray->AddVertex ( 0.0,  1.0,  0.0);
```

// add bounds to the array, second polygon
```
anArray->AddBound (4);
anArray->AddVertex (-1.0,  0.0,  0.0);
anArray->AddVertex ( 1.0,  0.0,  0.0);
anArray->AddVertex ( 1.0, -1.0,  0.0);
anArray->AddVertex (-1.0, -1.0,  0.0);
```

// add the array to the structure
```
Handle (Graphic3d_Group) aGroup =
                          Prs3d_Root::CurrentGroup (aPrs);
aGroup->BeginPrimitives ();
aGroup->AddPrimitiveArray (anArray);
aGroup->EndPrimitives ();
```

There are also several helper methods. You can get the type of the primitive array:

- `Graphic3d_TypeOfPrimitiveArray`
                `Graphic3d_ArrayOfPrimitives::Type`
- `Standard_CString Graphic3d_ArrayOfPrimitives::StringType`

and check if the primitive array provides normals, vertex colors, vertex texels (texture coordinates):

- `Standard_Boolean`
        `Graphic3d_ArrayOfPrimitives::HasVertexNormals`

- `Standard_Boolean`
  `Graphic3d_ArrayOfPrimitives::HasVertexColors`
- `Standard_Boolean`
  `Graphic3d_ArrayOfPrimitives::HasVertexTexels`

or get the number of vertices, edges and bounds:
- `Standard_Integer`
  `Graphic3d_ArrayOfPrimitives::VertexNumber`
- `Standard_Integer`
  `Graphic3d_ArrayOfPrimitives::EdgeNumber`
- `Standard_Integer`
  `Graphic3d_ArrayOfPrimitives::BoundNumber`

5. 1. 5 About materials

A **material** is defined by coefficients of:
- Transparency,
- Diffuse reflection,
- Ambient reflection,
- Specular reflection.

Two properties define a given material:
- Transparency
- Reflection properties - its absorption and reflection of light.

Diffuse reflection is seen as a component of the color of the object.

Specular reflection is seen as a component of the color of the light source.

The following items are required to determine the three colors of reflection:
- Color,
- Coefficient of diffuse reflection,
- Coefficient of ambient reflection,
- Coefficient of specular reflection.

5. 1. 6 About textures

A **texture** is defined by a name.
Three types of texture are available:
- 1D,
- 2D,
- Environment mapping.

5. 1. 7 Graphic3d text

The OpenGl graphics driver uses advanced text rendering powered by FTGL library. This library provides vector text rendering, as a result the text can be rotated and zoomed without quality loss.

Graphic3d text primitives have the following features:

- fixed size (non-zoomable) or zoomable,
- can be rotated to any angle in the view plane,
- support unicode charset.

The text attributes for the group could be defined with the Graphic3d_AspectText3d attributes group.

To add any text to the graphic structure you can use the following methods:

- `void Graphic3d_Group::Text`

  `(const Standard_CString AText,`

  `const Graphic3d_Vertex& APoint,`

  `const Standard_Real AHeight,`

  `const Quantity_PlaneAngle AAngle,`

  `const Graphic3d_TextPath ATp,`

  `const Graphic3d_HorizontalTextAlignment AHta,`

  `const Graphic3d_VerticalTextAlignment AVta,`

  `const Standard_Boolean EvalMinMax),`

  AText parameter is the text string, APoint is the three-dimensional position of the text, AHeight is the text height, AAngle is the orientation of the text (at the moment, this parameter has no effect, but you can specify the text orientation through the Graphic3d_AspectText3d attributes).

  ATp parameter defines the text path, AHta is the horizontal alignment of the text, AVta is the vertical alignment of the text.

  You can pass Standard_False as EvalMinMax if you don't want the graphic3d structure boundaries to be affected by the text position.

  Please note that the text orientation angle can be defined by Graphic3d_AspectText3d attributes.

- `void Graphic3d_Group::Text`

  `(const Standard_CString AText,`

  `const Graphic3d_Vertex& APoint,`

  `const Standard_Real AHeight,`

  `const Standard_Boolean EvalMinMax)`

- `void Graphic3d_Group::Text`

  `(const TCcollection_ExtendedString &AText,`

  `const Graphic3d_Vertex& APoint,`

```
                        const  Standard_Real  AHeight,
                        const  Quantity_PlaneAngle AAngle,
                        const  Graphic3d_TextPath  ATp,
                        const  Graphic3d_HorizontalTextAlignment  AHta,
                        const  Graphic3d_VerticalTextAlignment  AVta,
                        const  Standard_Boolean EvalMinMax)
```

- void Graphic3d_Group::Text
    ```
    (const  TCcollection_ExtendedString &AText,
     const  Graphic3d_Vertex& APoint,
     const  Standard_Real  AHeight,
     const  Standard_Boolean EvalMinMax)
    ```

Example

// get the group
```
Handle (Graphic3d_Group)  aGroup =
                          Prs3d_Root::CurrentGroup (aPrs);
```

// change the text aspect
```
Handle(Graphic3d_AspectText3d)  aTextAspect =
                          new Graphic3d_AspectText3d ();
aTextAspect->SetTextZoomable (Standard_True);
aTextAspect->SetTextAngle (45.0);
aGroup->SetPrimitivesAspect (aTextAspect);
```

// add a text primitive to the structure
```
Graphic3d_Vertex aPoint (1, 1, 1);
aGroup->Text (Standard_CString ("Text"), aPoint, 16.0);
```

---

5. 1. 8 Display priorities

Structure display priorities control the order in which structures are drawn. When you display a structure you specify its priority. The lower the value, the lower the display priority. When the display is regenerated the structures with the lowest priority are drawn first. For structures with the same display priority the order in which they were displayed determines the drawing order. CAS.CADE supports eleven structure display priorities.

5. 1. 9 About structure hierarchies

The root is the top of a structure hierarchy or structure network. The attributes of a parent structure are passed to its descendants. The attributes of the descendant structures do not affect the parent. Recursive structure networks are not supported.

5. 2 V3d

5. 2. 1 Overview

The **V3d** package provides the resources to define a 3D viewer and the views attached to this viewer (orthographic, perspective). This package provides the commands to manipulate the graphic scene of any 3D object visualized in a view on screen.

A set of high-level commands allows the separate manipulation of parameters and the result of a projection (Rotations, Zoom, Panning, etc.) as well as the visualization attributes (Mode, Lighting, Clipping, Depth-cueing, etc) in any particular view.

5. 2. 2 Provided services

The V3d package is basically a set of tools directed by commands from the viewer front-end. This tool set contains methods for creating and editing classes of the viewer such as:

- Default parameters of the viewer,
- Views (orthographic, perspective),
- Lighting (positional, directional, ambient, spot, headlight),
- Clipping planes (note that only Z-clipping planes can work with the Phigs interface),
- Instantiated sequences of views, planes, light sources, graphic structures, and picks,
- Various package methods.

5. 2. 3 A programming example

Example

This sample TEST program for the V3d Package uses primary packages Xw and Graphic3d and secondary packages Visual3d, Aspect, Quantity, Phigs, math.

```
//Create a default display connection
Handle(Aspect_DisplayConnection) aDisplayConnection =
    new Aspect_DisplayConnection();



//Create a Graphic Driver from the default Aspect_DisplayConnection
Handle(Graphic3d_GraphicDriver) GD =
        Graphic3d::InitGraphicDriver (aDisplayConnection);

// Create a Viewer to this Driver
Handle(V3d_Viewer) VM = new V3d_Viewer(GD, 400.,
```

```
    // Space size
    V3d_Xpos, // Default projection Quantity_NOC_DARKVIOLET,
    // Default background
    V3d_ZBUFFER,
    // Type of visualization
    V3d_GOURAUD,
    // Shading model
    V3d_WAIT) ;
    // Update mode
```

// Create a structure in this Viewer
```
Handle(Graphic3d_Structure) S =
      new Graphic3d_Structure(VM->Viewer()) ;
```

// Type of structure
```
S->SetVisual (Graphic3d_TOS_SHADING);
```

// Create a group of primitives in this structure
```
Handle(Graphic3d_Group) G = new Graphic3d_Group(S) ;
```

// Fill this group with one polygon of size 100
```
Graphic3d_Array1OfVertex Points(0, 3) ;
Points(0).SetCoord(-100./2.,-100./2.,-100./2.) ;
Points(1).SetCoord(-100./2., 100./2.,-100./2.) ;
Points(2).SetCoord( 100./2., 100./2.,-100./2.) ;
Points(3).SetCoord( 100./2.,-100./2.,-100./2.) ;
Normal.SetCoord(0.,0.,1.) ;
G->Polygon(Points, Normal) ;
```

// Create Ambient and Infinite Lights in this Viewer
```
Handle(V3d_AmbientLight) L1 = new V3d_AmbientLight
      (VM, Quantity_NOC_GRAY50) ;
Handle(V3d_DirectionalLight) L2 = new V3d_DirectionalLight
      (VM, V3d_XnegYnegZneg, Quantity_NOC_WHITE) ;
```

// Create a 3D quality Window with the same DisplayConnection
```
Handle(Xw_Window) W =
      new Xw_Window(aDisplayConnection, "Test
V3d", 0.5, 0.5, 0.5, 0.5) ;
```

// Map this Window to this screen
```
 W->Map() ;
```

// Create a Perspective View in this Viewer
```
Handle(V3d_PerspectiveView) V =
      new V3d_PerspectiveView(VM);
```

// Set the Eye position
```
V->SetEye(100., 100., 100.) ;
```

```
// Associate this View with the Window
V->SetWindow(W) ;

// Activate ALL defined Lights in this View
V->SetLightOn() ;

// Display ALL structures in this View
(VM->Viewer())->Display() ;

// Finally update the Visualization in this View
V->Update() ;
```

5. 2. 4 Glossary of view transformations

The following terms are used to define view orientation, i.e. transformation from World Coordinates (WC) to the View Reference Coordinates system (VRC)

View Reference Point (VRP)	Defines the origin of View Reference Coordinates.
View Reference Plane Normal (VPN)	Defines the normal of projection plane of the view.
View Reference Up Vector (VUP)	Defines the vertical of observer of the view.

The following terms are used to define view mapping, i.e. transformation from View Reference Coordinates (VRC) to the Normalized Projection Coordinates (NPC)

Projection type	Orthographic or perspective.
Projection Reference Point (PRP)	Defines the observer position.
Front Plane Distance (FPD)	Defines the position of the front clipping plane in View Reference Coordinates system.
Back Plane Distance (BPD)	Defines the position of the back clipping plane in View Reference Coordinates system.
View Plane Distance (VPD)	Defines the position of the view projection plane in View Reference Coordinates system. View plane must be located between front and back clipping planes.
Window Limits	Defines the visible part of the view projection plane (left, right, top and bottom boundaries: Umin, Umax, Vmax and Vmin respectively) in View Reference Coordinates.

The V3d_View API uses the following terms to define view orientation and mapping

At	Position of View Reference Point (VRP) in World

	Coordinates
Eye	Position of the observer (projection reference point) in World Coordinates. Influences to the view projection vector and depth value.
Proj	View projection vector (VPN)
Up	Position of the high point / view up vector (VUP)
Depth	Distance between Eye and At point
ZSize	Distance between front and back clipping planes
Size	Window size in View Reference Coordinates
Focal Reference point	Position of Projection Reference Point (PRP) in World Coordinates
Focale	Distance between Projection Reference Point (PRP) and View projection plane

5. 2. 5 Management of perspective projection

The perspective projection allows definition of viewing volume as a truncated pyramid (frustum) with apex at the Projection Reference Point. In the View Reference Coordinate system it can be presented by the following picture:
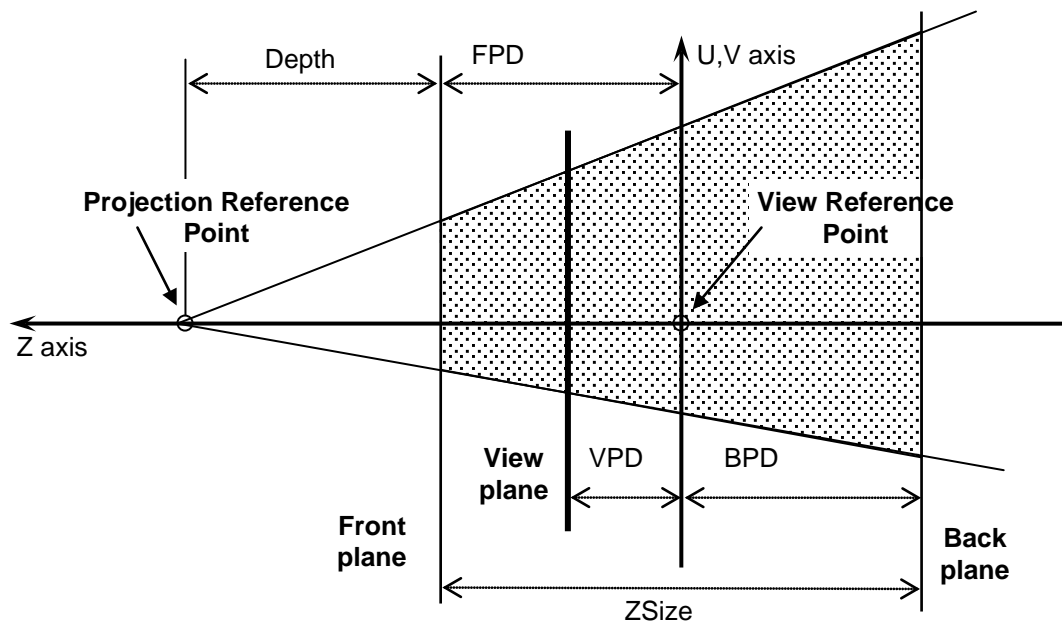

Figure 1 View Reference Coordinate System, perspective viewing volume and view mapping parameters

During panning, window limits are changed, as if a sort of "frame" through which the user sees a portion of the view plane was moved over the view. The perspective frustum itself remains unchanged.

The perspective projection is defined by two parameters:

- **Depth** value defines distance between Projection Reference Point and the nearest (front) clipping plane.
- **ZSize** defines distance between Front and Back clipping planes. The influence of this parameter is caused by the OCCT specific to center viewing volume around View Reference Point so the front and back plane distances were the same: FPD = BPD = ZSize / 2.

Note that the closer the displayed object to the Projection Reference Point the more visible its perspective distortion. Thus, in order to get a good perspective it is recommended to set ZSize value comparable with the expected model size and small Depth value.

However, very small Depth values might lead to inaccuracy of "fit all" operation and to non-realistic perspective distortion.

Example

```
// Create a Perspective View in Viewer VM
Handle(V3d_PerspectiveView) V =
        new V3d_PerspectiveView(VM);

// Set the ZSize
V->SetZSize(2000.) ;

// Set the Depth value
V->SetDepth(20.) ;

// Set the current mapping as default
// to be used by Reset() operation
V->SetViewMappingDefault() ;
```

As an alternative to manual setting of perspective parameters the *V3d_View::DepthFitAll* function can be used.

Example

```
// Display shape in Viewer VM
Handle(AIS_InteractiveContext) aContext =
        new AIS_InteractiveContext(VM);
aContext->Display(shape);

// Create a Perspective View in Viewer VM
Handle(V3d_PerspectiveView) V =
        new V3d_PerspectiveView(VM);
```

// Set automatically the perspective parameters
```
V->DepthFitAll() ;
```

// Fit view to object size
```
V->FitAll();
```

// Set the current mapping as default
// to be used by Reset() operation
```
V->SetViewMappingDefault() ;
```

It is necessary to take into account that during rotation Z size of the view might be modified automatically to fit the model into the viewing volume.

Make sure the Eye point never gets between the Front and Back clipping planes.

In perspective view, changing Z size results in changed perspective effect. To avoid this, an application should specify the maximum expected Z size using V3d_View::SetZSize() method in advance.

V3d_View::FitAll() with FitZ = Standard_True and V3d_View::ZFitAll() also change the perspective effect and should therefore be used with precautions similar to those for rotation.

5. 2. 6 Underlay and overlay layers management

In addition to interactive 3d graphics displayed in the view you can display an underlying and overlying graphics: text, color scales, drawings.

All of the v3d view's graphical objects in the overlay are managed by the default layer manager (*V3d_LayerMgr*). The v3d view has a basic layer manager capable of displaying the color scale, but you can redefine this class to provide your own overlay and underlay graphics.

You can assign your own layer manager to the v3d view using the following method:

- `void V3d_View::SetLayerMgr`

   `(const Handle (V3d_LayerMgr)& aMgr)`

There are three virtual methods to prepare graphics in the manager for further drawing (set up layer dimensions, draw static graphics). These methods could be redefined:

- `void V3d_LayerMgr::Begin ()`

- `void V3d_LayerMgr::Redraw ()`

- `void V3d_LayerMgr::End ()`

The layer manager controls layers (*Visual3d_Layer*) and layer items (*Visual3d_LayerItem*). Both the overlay and underlay layers can be created by the layer manager.

The layer entity is presented by the *Visual3d_Layer* class. This entity provides drawing services in the layer, for example:

- `void Visual3d_Layer::DrawText`
- `void Visual3d_Layer::DrawRectangle`
- `void Visual3d_Layer::SetColor`
- `void Visual3d_Layer::SetViewport`

The following example demonstrates how to draw overlay graphics by the V3d_LayerMgr:

Example

// redefined method of V3d_LayerMgr
```
void MyLayerMgr::Redraw ()
{
  Quantity_Color aRed (Quantity_NOC_RED);
  myOverlayLayer->SetColor (aRed);
  myOverlayLayer->DrawRectangle (0, 0, 100, 100);
}
```

The layer contains layer items that will be displayed on view redraw. Such items are the Visual3d_LayerItem entities. To manipulate Visual3d_LayerItem entities assigned to the layer's internal list you can use the following methods:

- `void Visual3d_Layer::AddLayerItem`
  `(const Handle (Visual3d_LayerItem)& Item)`
- `void Visual3d_Layer::RemoveLayerItem`
  `(const Handle (Visual3d_LayerItem)& Item)`
- `void Visual3d_Layer::RemoveAllLayerItems ()`
- `const Visual3d_NListOfLayerItem&`
  `Visual3d_Layer::GetLayerItemList ()`

The layer's items are rendered when the following method is called by the graphical driver:

- `void Visual3d_Layer::RenderLayerItems ()`

The *Visual3d_LayerItem* has virtual methods that are used to render the item:

- `void Visual3d_LayerItem::RedrawLayerPrs ()`
- `void Visual3d_LayerItem::ComputeLayerPrs ()`

The item's presentation can be computed before drawing by the ComputeLayerPrs method to save time on redraw. It also has an additional flag that is used to tell that the presentation should be recomputed:

- `void Visual3d_LayerItem::SetNeedToRecompute`

     `(const Standard_Boolean NeedToRecompute)`

- `Standard_Boolean Visual3d_LayerItem::IsNeedToRecompute`

An example of Visual3d_LayerItem is *V3d_ColorScaleLayerItem* that represents the color scale entity as the layer's item.

The *V3d_ColorScaleLayerItem* sends render requests to the color scale entity represented by it. As this entity (*V3d_ColorScale*) is assigned to the *V3d_LayerMgr* it uses its overlay layer's services for drawing:

Example

```
// tell V3d_ColorScale to draw itself
void V3d_ColorScaleLayerItem::RedrawLayerPrs ()
{
  Visual3d_LayerItem::RedrawLayerPrs ()
  if (!MyColorScale.IsNull ())
    MyColorScale->DrawScale ();
}


// V3d_ColorScale has a reference to a LayerMgr
void V3d_ColorScale::DrawScale ()
{
  // calls V3d_ColorScale::PaintRect, V3d_ColorScale::PaintText, etc …
}


// PaintRect method uses overlay layer of LayerMgr to draw a rectangle
void V3d_ColorScale::PaintRect
        (const Standard_Integer X, const Standard_Integer Y,
         const Standard_Integer W, const Standard_Integer H,
         const Quantity_Color aColor,
         const Standard_Boolean aFilled)
{
  const Handle (Visual3d_Layer)& theLayer =
                                    myLayerMgr->Overlay ();
  …

  theLayer->SetColor (aColor);
  theLayer->DrawRectangle (X, Y, W, H);
  …
}
```

5. 2. 7 View background styles

There are three types of background styles available for V3d_view: solid color, gradient color and image.

To set solid color for the background you can use the following methods:

- `void V3d_View::SetBackgroundColor`

    `(const Quantity_TypeOfColor Type,`

    `const Quantity_Parameter V1,`

    `const Quantity_Parameter V2,`

    `const Quantity_Parameter V3)`

    This method allows you to specify the background color in RGB (red, green, blue) or HLS (hue, lightness, saturation) color spaces, so the appropriate values of the Type parameter are Quantity_TOC_RGB and Quantity_TOC_HLS. **Note** that the color value parameters V1,V2,V3 should be in the range between 0.0-1.0.

- `void V3d_View::SetBackgroundColor`

    `(const Quantity_Color &Color)`

- `void V3d_View::SetBackgroundColor`

    `(const Quantity_NameOfColor Name)`

The gradient background style could be set up with the following methods:

- `void V3d_View::SetBgGradientColors`

    `(const Quantity_Color& Color1,`

    `const Quantity_Color& Color2,`

    `const Aspect_GradientFillMethod FillStyle,`

    `const Standard_Boolean update)`

- `void V3d_View::SetBgGradientColors`

    `(const Quantity_NameOfColor Color1,`

    `const Quantity_NameOfColor Color2,`

    `const Aspect_GradientFillMethod FillStyle,`

    `const Standard_Boolean update)`

    The Color1 and Color2 parameters define the boundary colors of interpolation, the FillStyle parameter defines the direction of interpolation. You can pass Standard_True as the last parameter to update the view.

The fill style can be also set with the following method:

- `void V3d_View::SetBgGradientStyle`

    `(const Aspect_GradientFillMethod AMethod,`

    `const Standard_Boolean update)`

To get the current background color you can use the following methods:

- `void V3d_View::BackgroundColor`
  `(const Quantity_TypeOfColor Type,`
  `Quantity_Parameter &V1,`
  `Quantity_Parameter &V2,`
  `Quantity_Parameter &V3)`

- `Quantity_Color V3d_View::BackgroundColor()`

- `void V3d_View::GradientBackgroundColors`
  `(Quantity_Color& Color1,`
  `Quantity_Color& Color2)`

- `Aspect_GradientBackground GradientBackground()`

To set the image as a background and change the background image style you can use the following methods:

- `void V3d_View::SetBackgroundImage`
  `(const Standard_CString FileName,`
  `const Aspect_FillMethod FillStyle,`
  `const Standard_Boolean update)`

- `void V3d_View::SetBgImageStyle`
  `(const Aspect_FillMethod FillStyle,`
  `const Standard_Boolean update)`

The FileName parameter defines the image file name and the path to it, the FillStyle parameter defines the method of filling the background with the image. The methods are:

- `Aspect_FM_NONE`: draw the image in the default position

- `Aspect_FM_CENTERED`: draw the image at the center of the view

- `Aspect_FM_TILED`: tile the view with the image

- `Aspect_FM_STRETCH`: stretch the image over the view

5. 2. 8 User-defined clipping planes

The ability to define custom clipping planes could be very useful for some tasks. The v3d view provides such an opportunity.

The V3d_Plane class provides the services of clipping planes: it holds the plane equation coefficients and provides its graphical representation. To set and get plane equation coefficients you can use the following methods:

- `void V3d_Plane::SetPlane`
  `(const Quantity_Parameter A,`
  `const Quantity_Parameter B,`

```
                              const Quantity_Parameter C,
                              const Quantity_Parameter D)
```

- `void V3d_Plane::Plane`
  ```
              (Quantity_Parameter& A,
               Quantity_Parameter& B,
               Quantity_Parameter& C,
               Quantity_Parameter& D)
  ```

V3d_Plane also provides display services:

- `void V3d_Plane::Display`
  ```
              (const Handle(V3d_View)& aView,
               const Quantity_Color& aColor)
  ```

- `void V3d_Plane::Erase ()`

- `Standard_Boolean V3d_Plane::IsDisplayed ()`

  The Display method could be redefined to provide custom representation of the clipping plane.

The clipping planes could be activated with the following methods:

- `void V3d_View::SetPlaneOn`
  ```
              (const Handle(V3d_Plane)& MyPlane)
  ```

- `void V3d_View::SetPlaneOn ()`

  The first method appends the given V3d_Plane to the internal list of user-defined clipping planes of a view and activates it. If the plane is already in the list, it becomes activated. The second method activates all of the planes defined for the view.

The clipping planes could be deactivated with the similar methods:

- `void V3d_View::SetPlaneOff`
  ```
              (const Handle(V3d_Plane)& MyPlane)
  ```

- `void V3d_View::SetPlaneOff ()`

The only difference is that these methods remove the user-defined clipping planes from the internal list. Thus, the view retains only active clipping planes.

You can iterate through the active planes using the following methods:

- `void V3d_View::InitActivePlanes ()`

  sets the iterator to the beginning of the internal list of clipping planes

- `Standard_Boolean V3d_View::MoreActivePlanes ()`

  returns Standard_True if there are more active planes to return

- `void V3d_View::NextActivePlanes ()`

  sets the iterator to the next active plane in the list

- `Handle(V3d_Plane) V3d_View::ActivePlane ()`

  returns the active plane

or check if a certain clipping plane has been activated:

- `Standard_Boolean V3d_View::IsActivePlane`

  `(const Handle (V3d_Plane)& aPlane)` The number of clipping planes is limited. The following method allows you to check if it is possible to activate at least one more plane in the view or the limit has been reached:

- `Standard_Boolean V3d_View::IfMorePlanes ()`

Example

// try to use an existing clipping plane or create a new one
```
Handle(V3d_Plane) aCustomPlane;
myView->InitActivePlanes ();
if (myView->MoreActivePlanes ())
  aCustomPlane = myView->ActivePlane ();
else
  aCustomPlane = new V3d_Plane ();
```

// calculate new coefficients
```
Standard_Real a, b, c, d;
Standard_Real x = 0.0, y = 0.0, z = 10.0;
Standard_Real dx = 0.0, dy = 0.0, dz = 1.0;
gp_Pln aPln (gp_Pnt (x, y, z), gp_Dir (dx, dy, dz));
aPln.Coefficients (a, b, c, d);
```

// update plane
```
aCustomPlane->SetPlane (a, b, c, d);
myView->SetPlaneOn (aCustomPlane);
```

---

5. 2. 9 Dumping a 3D scene into an image file

The 3D scene displayed in the view could be dumped in high resolution into an image file. The high resolution (8192x8192 on some implementations) is achieved using the Frame Buffer Objects (FBO) provided by the graphic driver. Frame Buffer Objects enable off-screen rendering into a virtual view to produce images in the background mode (without displaying any graphics on the screen).

The V3d_View has the following methods for dumping the 3D scene:

- `Standard_Boolean V3d_View::Dump`

  `(const Standard_CString theFile,`

```
            const Image_TypeOfImage theBufferType)
```

- `Standard_Boolean V3d_View::Dump`

    ```
        (const Standard_CString theFile,
         const Aspect_FormatOfSheetPaper theFormat,
         const Image_TypeOfImage theBufferType)
    ```

These methods dump the 3D scene into an image file passed by its name and path as theFile.

The raster image data handling algorithm is based on the Image_PixMap class. The supported extensions are ".png", ".bmp", ".jpg", ".gif".

The first method dumps the scene into an image file with the view dimensions. The second method allows you to make the dimensions of the output image compatible to a certain format of printing paper passed by theFormat argument.

The value passed as theBufferType argument defines the type of the buffer for an output image (RGB, RGBA, floating-point, RGBF, RGBAF). Both methods return Standard_True if the scene has been successfully dumped.

Please note that dumping the image for a paper format with large dimensions is a memory consuming operation, it might be necessary to take care of preparing enough free memory to perform this operation.

- `Handle_Image_PixMap V3d_View::ToPixMap`

    ```
        (const Standard_Integer theWidth,
         const Standard_Integer theHeight,
         const Image_TypeOfImage theBufferType,
         const Standard_Boolean theForceCentered)
    ```

This method allows you to dump the displayed 3d scene into a pixmap with a width and height passed as theWidth and theHeight arguments.

The value passed as theBufferType argument defines the type of the buffer for a pixmap (RGB, RGBA, floating-point, RGBF, RGBAF).

The last parameter allows you to center the 3D scene on dumping.

All these methods assume that you have created a view and displayed a 3d scene in it. However, the window used for such a view could be virtual, so you can dump the 3d scene in the background mode without displaying it on the screen. To use such an opportunity you can perform the following steps:

1) Create display connection;
2) Initialize graphic driver;
3) Create a window;
4) Set up the window as virtual, Aspect_Window::SetVirtual ();
5) Create a view and an interactive context;
6) Assign the virtual window to the view;
7) Display a 3D scene;

8) Use one of the functions described above to dump the 3D scene.

The following example demonstrates this procedure for the WNT_Window:

Example

// create a dummy display connection
Handle(Aspect_DisplayConnection) aDisplayConnection;

// create a graphic driver
```
Handle (Graphic3d_GraphicDriver) aDriver =
  Graphic3d::InitGraphicDriver (aDisplayConnection);
```

// create a window
```
Standard_Integer aDefWidth  = 800;
Standard_Integer aDefHeight = 600;
Handle (WNT_WClass) aWClass =
            new WNT_WClass ("Virtual Class", DefWindowProc,
                            CS_VREDRAW | CS_HREDRAW, 0, 0,
                            ::LoadCursor (NULL, IDC_ARROW));
Handle (WNT_Window) aWindow =
            new WNT_Window ("VirtualWnd",  aWClass,
                            WS_OVERLAPPEDWINDOW, 0, 0,
                            aDefWidth, aDefHeight);
```

// set up the window as virtual
```
aWindow->SetVirtual (Standard_True);
```

// create a view and an interactive context
```
Handle (V3d_Viewer) aViewer =
            new V3d_Viewer (aDriver,
                            Standard_ExtString ("Virtual"));
Handle (AIS_InteractiveContext) aContext =
            new AIS_InteractiveContext (aViewer);
Handle (V3d_View) aView = aViewer->CreateView ();
```

// assign the virtual window to the view
```
aView->SetWindow (aWindow);
```

// display a 3D scene
```
Handle (AIS_Shape) aBox =
            new AIS_Shape (BRepPrimAPI_MakeBox (5, 5, 5));
aContext->Display (aBox);
aView->FitAll();
```

// dump the 3D scene into an image file

```
aView->Dump ("3dscene.png");
```

5. 2. 10 Printing a 3D scene

The contents of a view can be printed out. Moreover, the OpenGl graphic driver used by the v3d view supports printing in high resolution. The print method uses the OpenGl frame buffer (Frame Buffer Object) for rendering the view contents and advanced print algorithms that allow printing in, theoretically, any resolution.

The following method prints the view contents:

- ```
  void V3d_View::Print
       (const Aspect_Handle hPrnDC,
        const Standard_Boolean showDialog,
        const Standard_Boolean showBackground,
        const Standard_CString  filename,
        const Aspect_PrintAlgo   printAlgorithm)
  ```
  The hPrnDC is the printer device handle. You can pass your own printer handle or "NULL" to select the printer by the default dialog. In that case you can use the default dialog or pass "Standard_False" as the showDialog argument to select the default printer automatically.

  You can define the filename for the printer driver if you want to print out the result into a file.

  If you do not want to print the background, you can pass "Standard_False" as the showBackground argument.

  The printAlgorithm argument allows you to choose between two print algorithms that define how the 3d scene is mapped to the print area when the maximum dimensions of the frame buffer are smaller than the dimensions of the print area. You can pass the following values as the printAlgorithm argument:

  - ```
    Aspect_PA_STRETCH,
    ```
  - ```
    Aspect_PA_TILE
    ```

  The first value defines the stretch algorithm: the scene is drawn with the maximum possible frame buffer dimensions and then is stretched to the whole printing area. The second value defines TileSplit algorithm: covering the whole printing area by rendering multiple parts of the viewer.

Please note that at the moment printing is implemented only for Windows.

5. 2. 11 Vector image export

The 3D content of a view can be exported to the vector image file format. The vector image export is powered by the GL2PS library. You can export your 3D scenes into a file format supported by the GL2PS library: PostScript (PS), Encapsulated PostScript (EPS), Portable Document Format (PDF), Scalable Vector Graphics (SVG), LaTeX file format and Portable LaTeX Graphics (PGF).

The following method of Visual3d_View class allows you to export your 3D scene:

- `void Visual3d_View::Export`
  `(const Standard_CString FileName,`
  `const Graphic3d_ExportFormat Format,`
  `const Graphic3d_SortType aSortType,`
  `const Standard_Real  Precision,`
  `const Standard_Address ProgressBarFunc,`
  `const Standard_Address ProgressObject)`

  The FileName defines the output image file name and the Format argument defines the output file format:

  - `Graphic3d_EF_PostScript (PS),`
  - `Graphic3d_EF_EhnPostScript (EPS),`
  - `Graphic3d_EF_TEX (TEX),`
  - `Graphic3d_EF_PDF (PDF),`
  - `Graphic3d_EF_SVG (SVG),`
  - `Graphic3d_EF_PGF (PGF)`

  The aSortType parameter defines the GL2PS sorting algorithm for the primitives. The Precision, ProgressBarFunc and ProgressObject parameters are implemented for future uses and at the moment have no effect.

The Export method supports only basic 3d graphics and has several limitations:

- Rendering large scenes could be slow and can lead to large output files;
- Transparency is only supported for PDF and SVG output;
- Textures and some effects are not supported by the GL2PS library.

7. Graphic Attributes

7. 1 Aspect

7. 1. 1 Overview

The **Aspect** package provides classes for the graphic elements, which are common to all 2D and 3D viewers - screen background, windows, edges, groups of graphic attributes that can be used in describing 2D and 3D objects.

7. 1. 2 The services provided

The **Aspect** package provides classes to implement:

- Color maps,
- Pixels,
- Groups of graphic attributes,
- Edges, lines, background,
- Font classes,
- Width map classes,
- Marker map classes,
- Type of Line map classes,
- Window,
- Driver, PlotterDriver (inherited by PS_Driver), WindowDriver,
- Enumerations for many of the above,
- Array instantiations for edges,
- Array instantiations for map entries for color, type, font, width, and marker.