

CORDIC Background (4A)

•
•

Copyright (c) 2011 Young W. Lim.

Permission is granted to copy, distribute and/or modify this document under the terms of the GNU Free Documentation License, Version 1.2 or any later version published by the Free Software Foundation; with no Invariant Sections, no Front-Cover Texts, and no Back-Cover Texts. A copy of the license is included in the section entitled "GNU Free Documentation License".

Please send corrections (or suggestions) to youngwlim@hotmail.com.

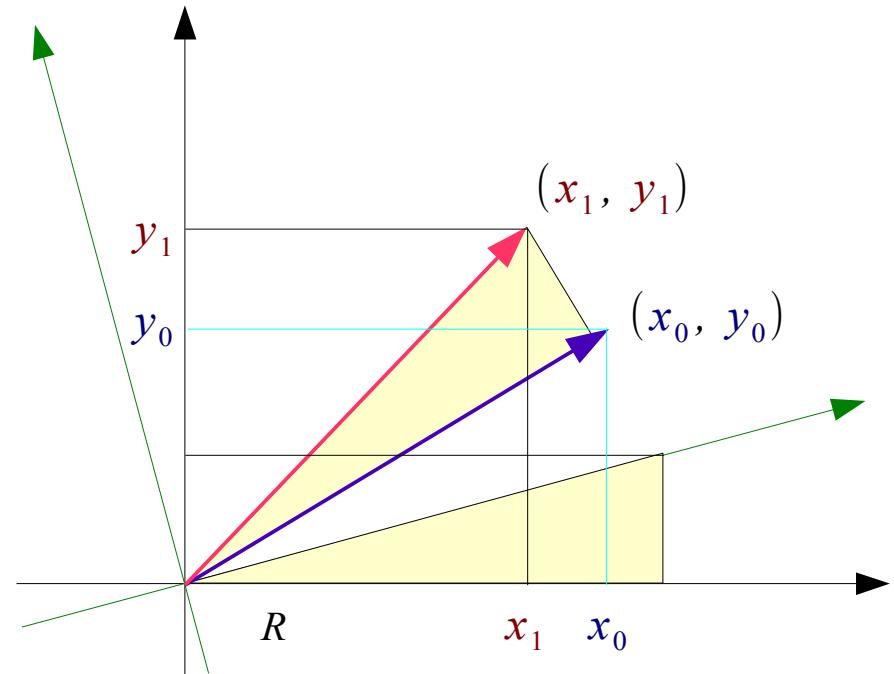
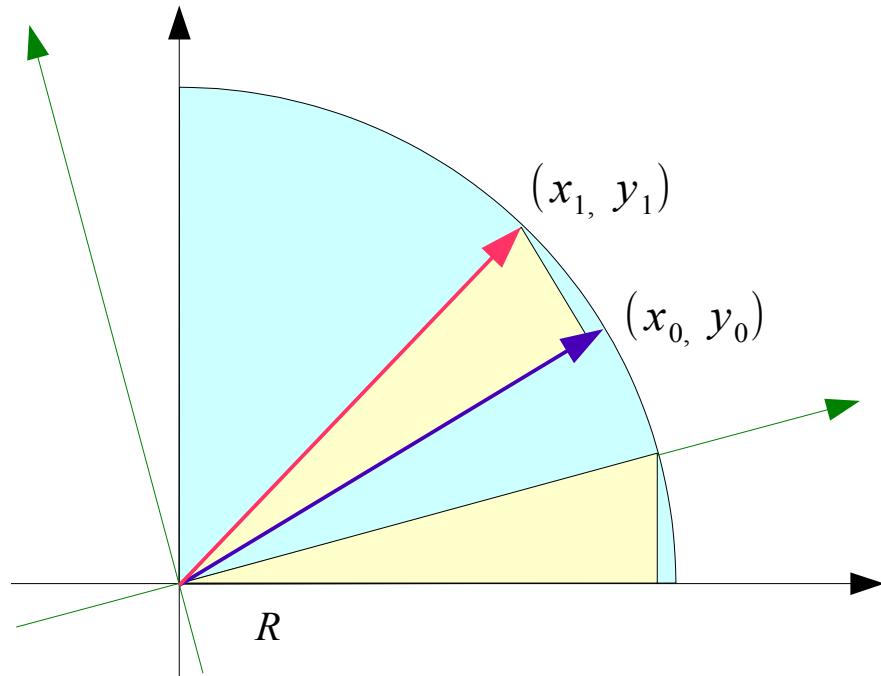
This document was produced by using OpenOffice and Octave.

CORDIC Background

J. P. Deschamps, G. A. Bioul, G.D. Sutter, Synthesis of Arithmetic Circuits

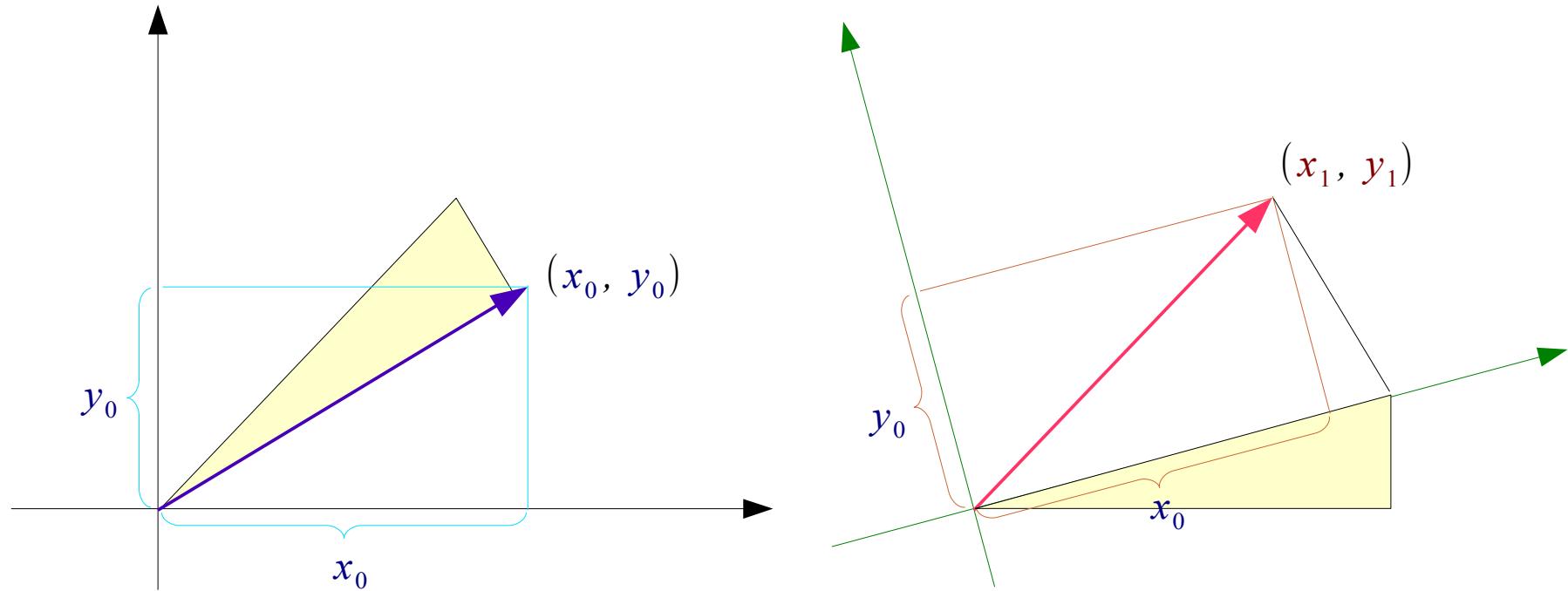
Vector Rotation (1)

$$y_1 = x_0 \sin \alpha + y_0 \cos \alpha$$

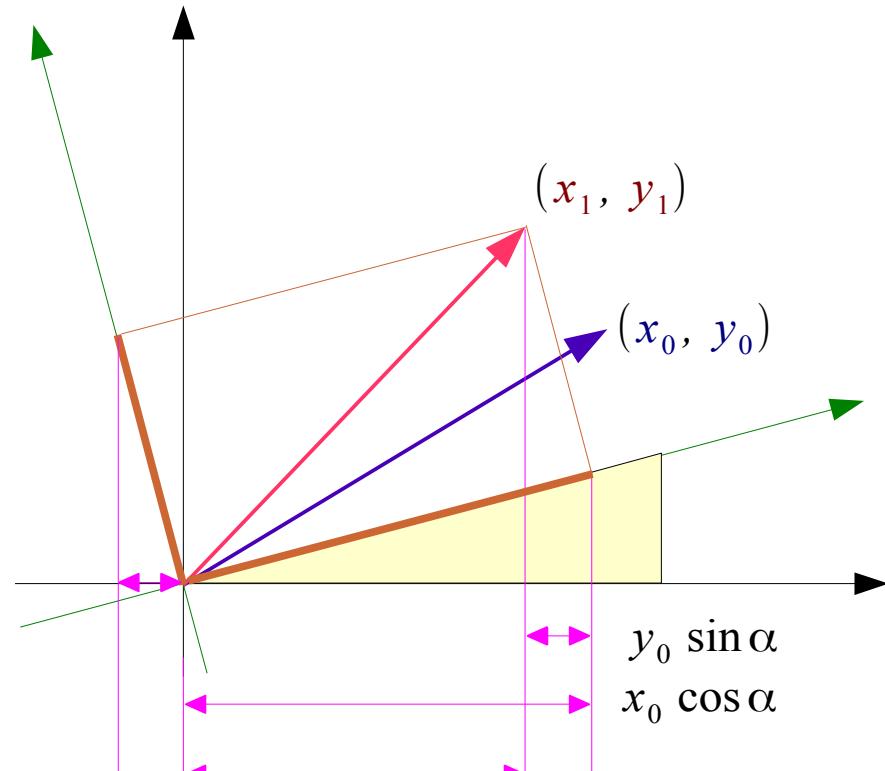


$$x_1 = x_0 \cos \alpha - y_0 \sin \alpha$$

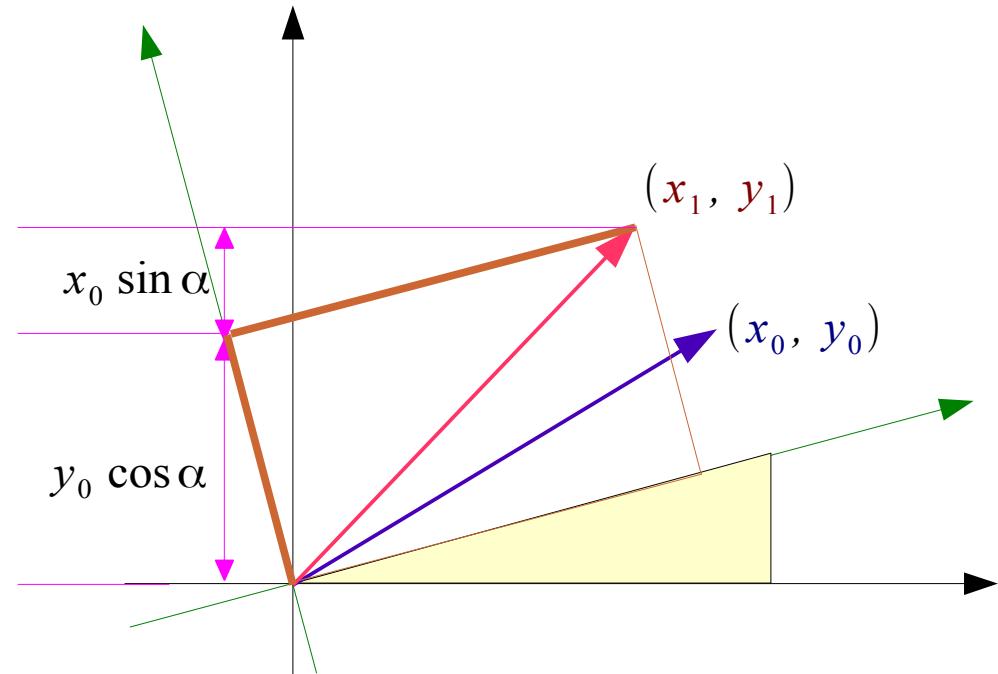
Vector Rotation (2)



Vector Rotation (3)

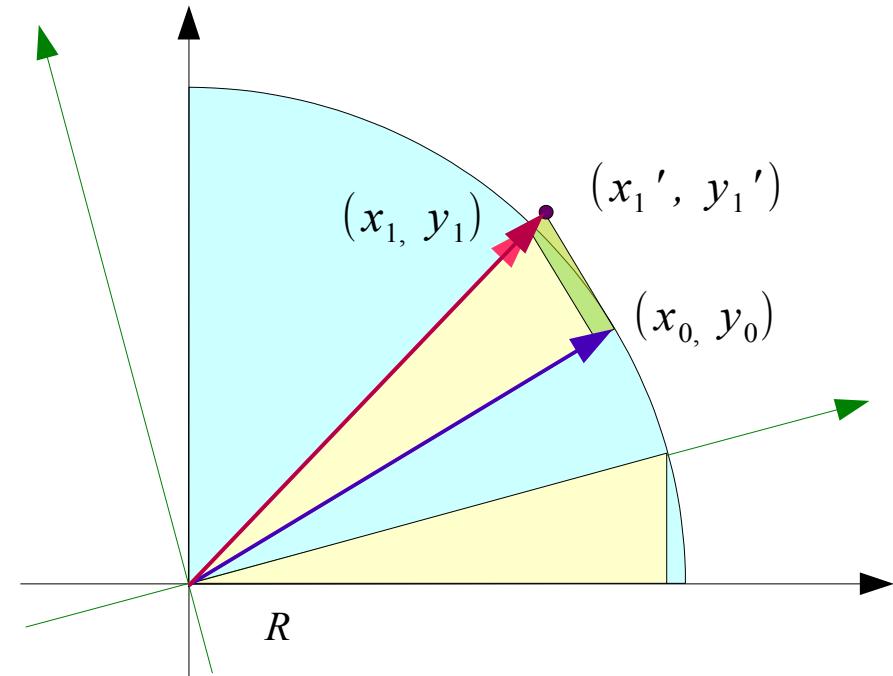
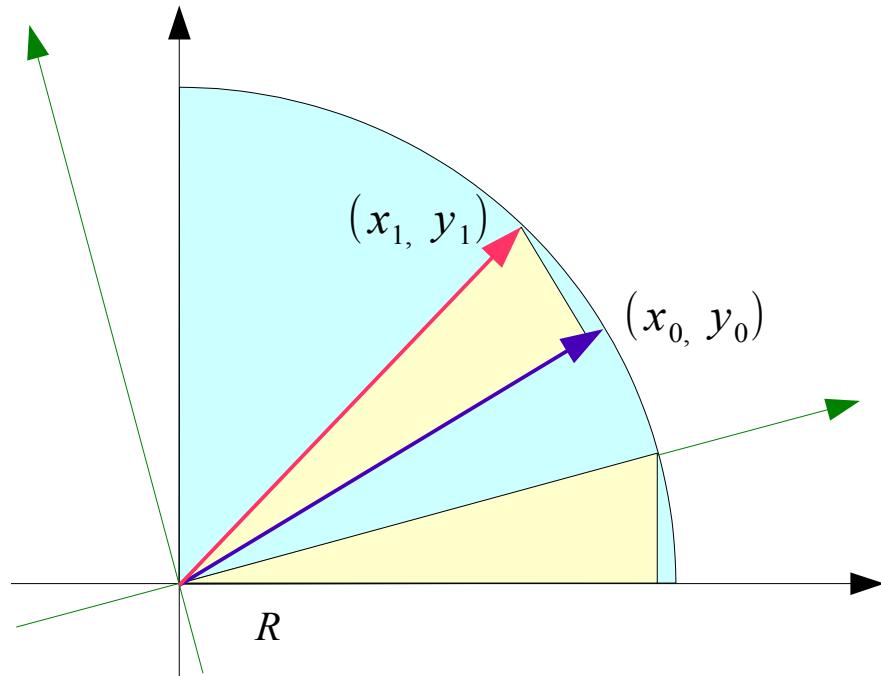


$$x_1 = x_0 \cos \alpha - y_0 \sin \alpha$$



$$y_1 = x_0 \sin \alpha + y_0 \cos \alpha$$

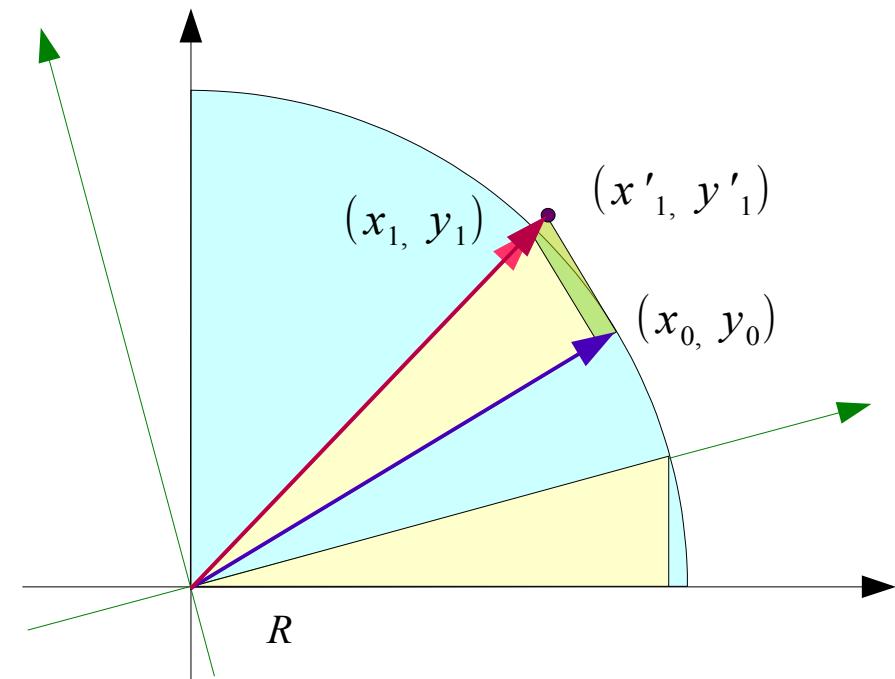
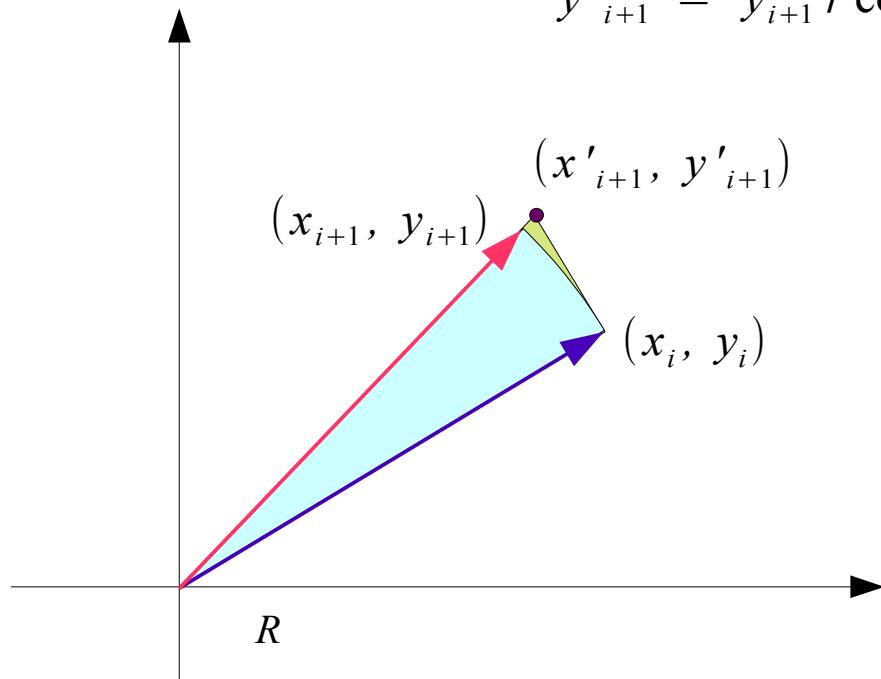
Pseudo-rotation (4)



Pseudo-rotation

$$x'_{i+1} = x_{i+1} / \cos \alpha_i$$

$$y'_{i+1} = y_{i+1} / \cos \alpha_i$$



Unified CORDIC Iteration Eq

References

- [1] <http://en.wikipedia.org/>
- [2] CORDIC FAQ, www.dspguru.com
- [3] R. Andraka, A survey of CORDIC algorithms for FPGA based computers
- [4] J. S. Walther, A Unified Algorithm for Elementary Functions
- [5] J. P. Deschamps, G. A. Bioul, G.D. Sutter, Synthesis of Arithmetic Circuits