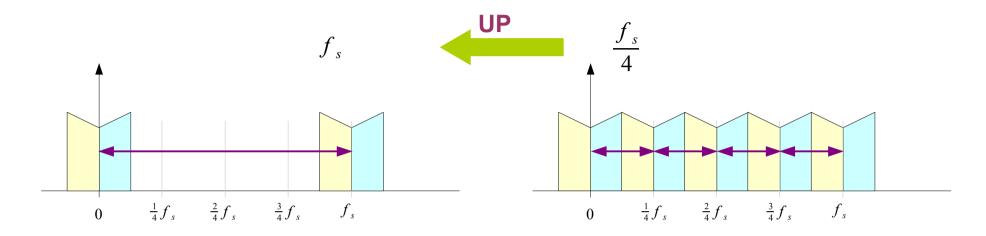
Up-Sampling (5B)

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Band-limited Signal



Sampling Frequency

 f_{s}

Sampling Time

$$T = \frac{1}{f_s}$$

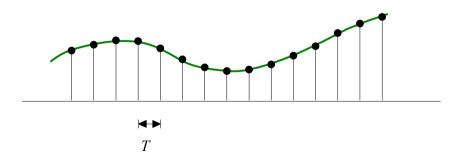


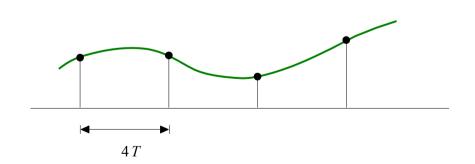
Sampling Frequency

$$f'_{s} = \frac{1}{4}f_{s}$$

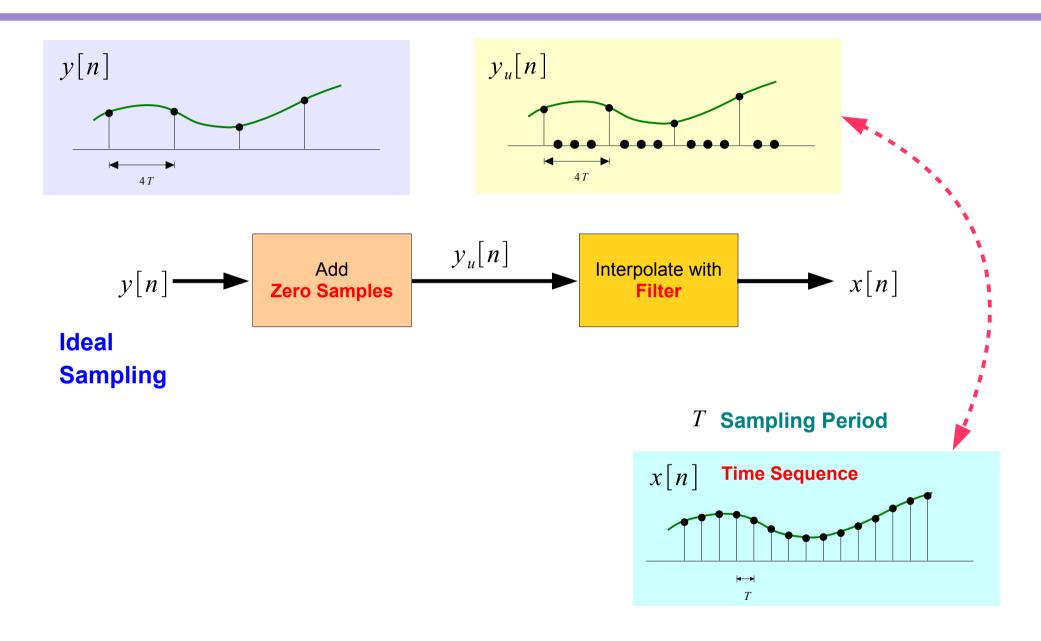
Sampling Time

$$T' = \frac{4}{f_s}$$

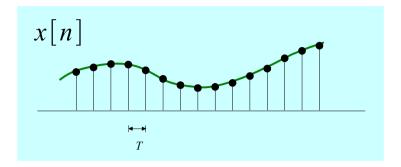




Time Sequence



Normalized Radian Frequency



$$\hat{\omega} = \omega \cdot T_s = \frac{\omega}{1/T_s}$$

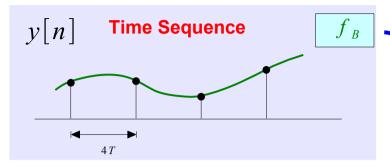
$$\hat{\omega} = \frac{\omega}{f_s} = 2\pi \frac{f}{f_s}$$





Normalized to f_s

Normalized Radian Frequency



$$\frac{f}{f_s} = \frac{f_B}{1/4T} = f_B \cdot 4T$$

The Same

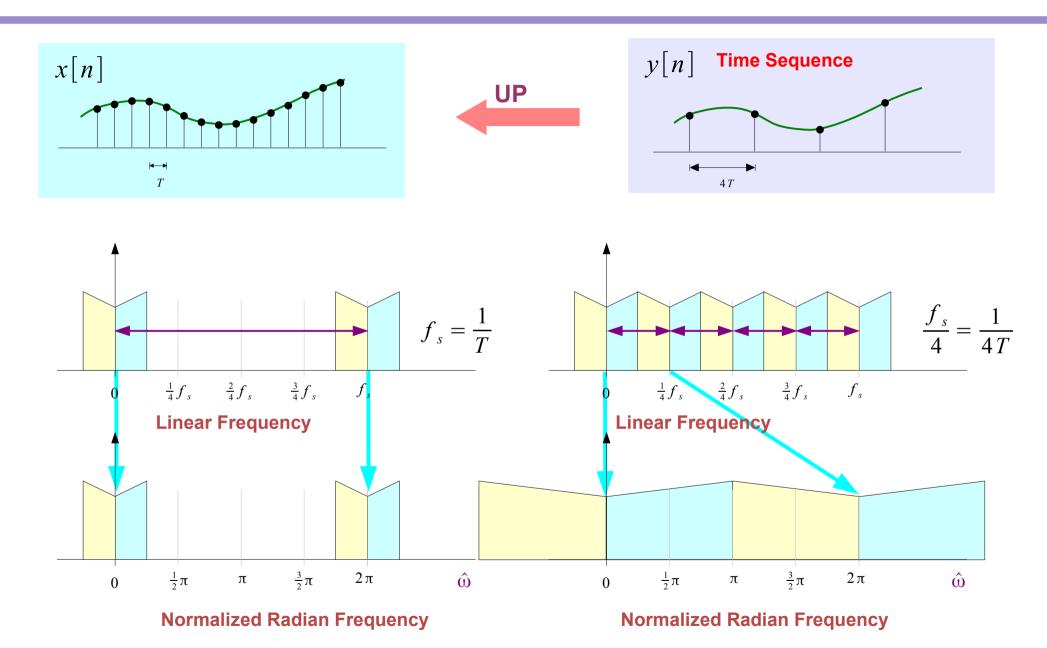
- Time Sequence
- Normalized Radian Frequency

$$\frac{f}{f_s} = \frac{4 f_B}{1/T} = f_B \cdot 4T$$

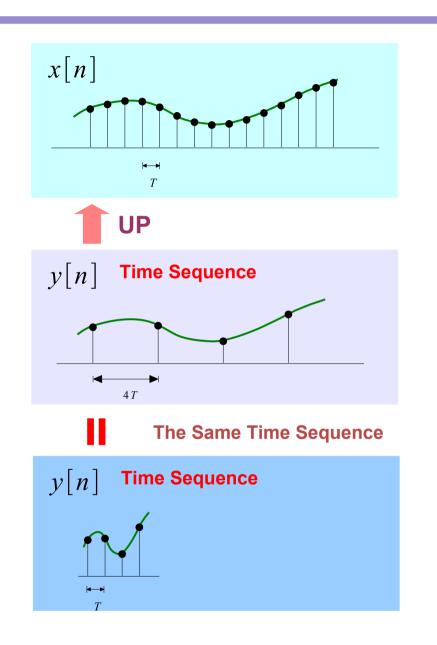
y'[n] Time Sequence

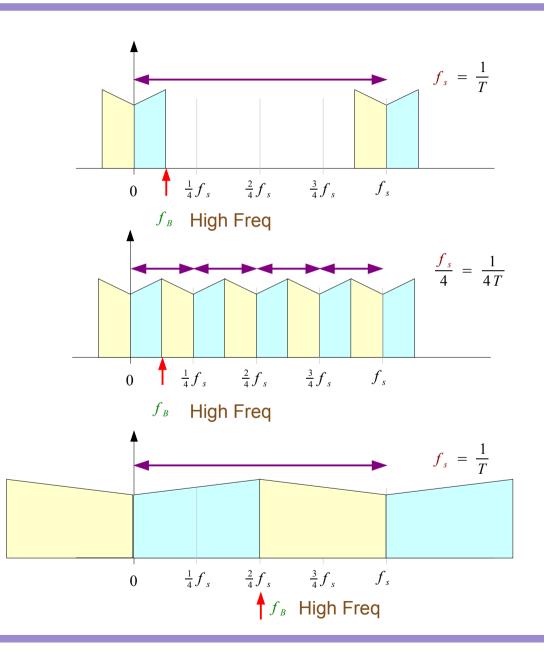
 $4f_B$

Time Sequence & Sampling Frequency

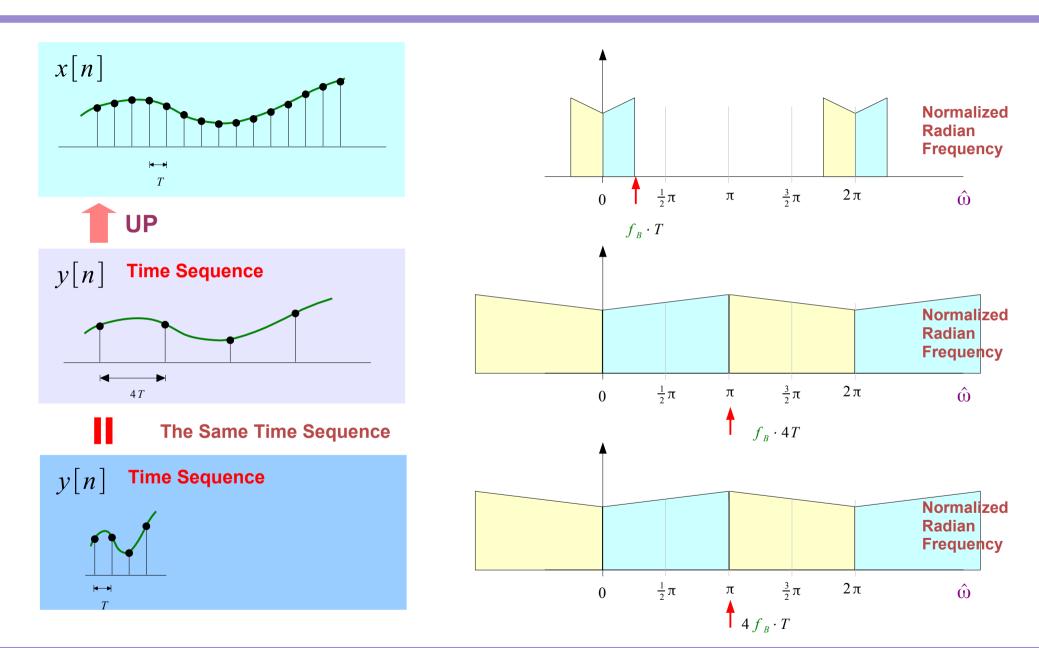


Spectrum in a Linear Frequency

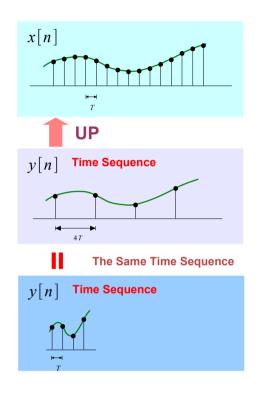


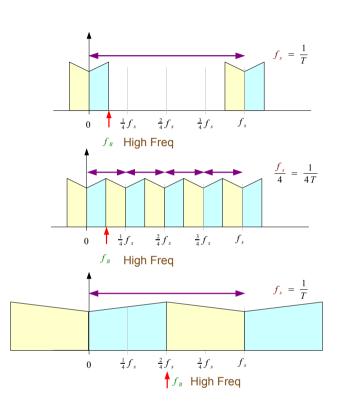


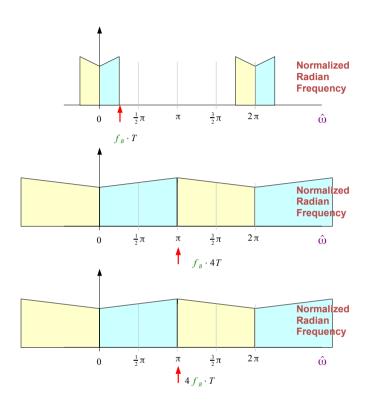
Spectrum in a Normalized Frequency



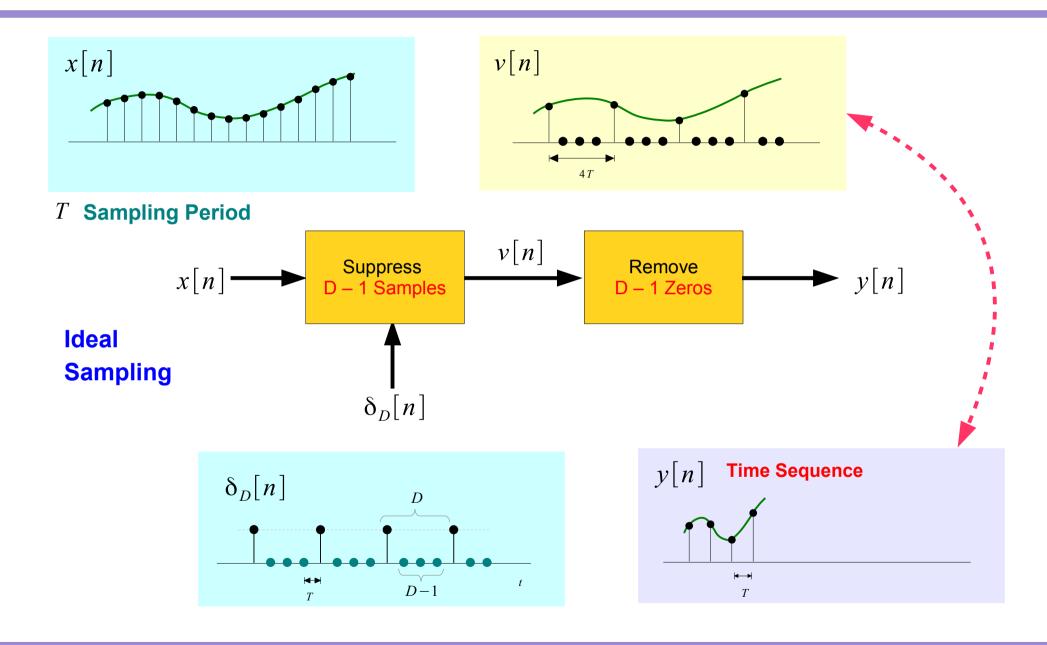
Time Sequence Spectrum



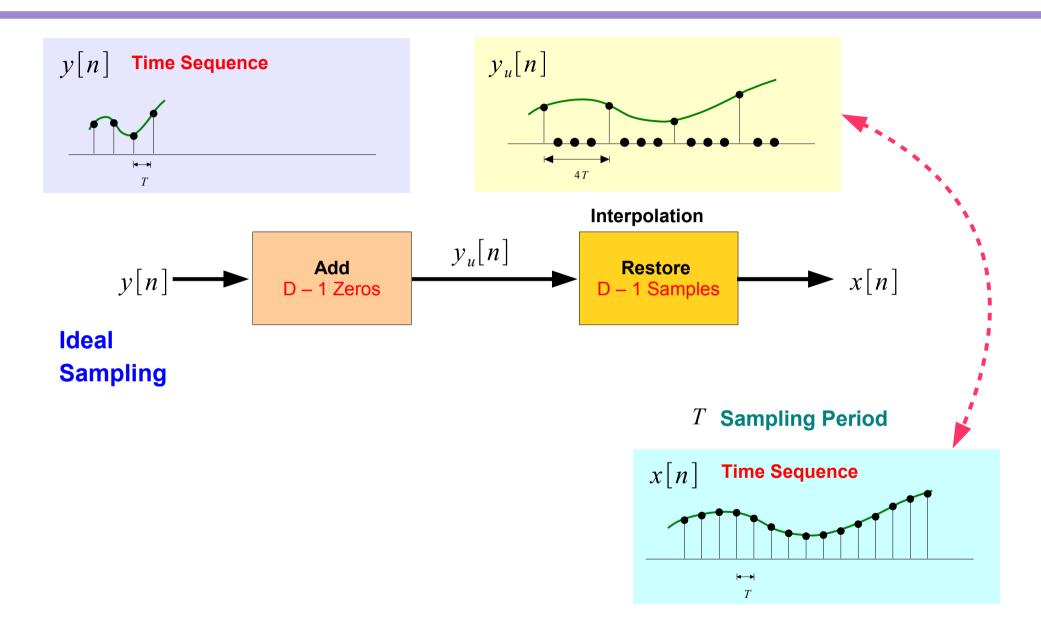




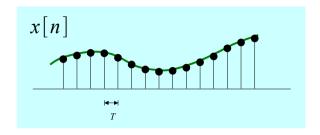
Z-Transform and Down Sampling



Z-Transform and Up Sampling

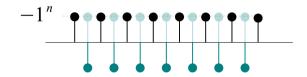


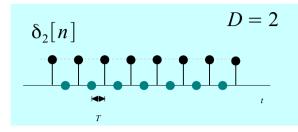
Example When D=2(1)



$$x[n] = e^{j\omega n}$$



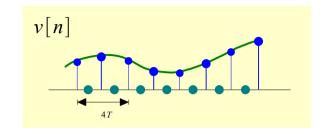




$$\delta_{2}[n] = \frac{1}{2}(1 + (-1)^{n})$$

$$= \frac{1}{2}(1 + e^{-j\pi n})$$

$$(e^{-j\pi} = -1)$$



$$v[n] = \frac{1}{2}x[n] + \frac{1}{2}e^{-j\pi n}x[n]$$

$$= \frac{1}{2}e^{j\omega n} + \frac{1}{2}e^{-j\pi n}e^{j\omega n}$$

$$= \frac{1}{2}e^{j\omega n} + \frac{1}{2}e^{+j(\omega-\pi)n}$$

$$V(z) = \frac{1}{2} \sum_{n=-\infty}^{+\infty} \left(x[n] z^{-n} + x[n] (-z)^{-n} \right) = \frac{1}{2} X(z) + \frac{1}{2} X(-z)$$

$$V(e^{j\hat{\omega}}) = \frac{1}{2} X(e^{j\hat{\omega}}) + \frac{1}{2} X(e^{-j\pi} e^{j\hat{\omega}})$$

$$V(\hat{\omega}) = \frac{1}{2} X(\hat{\omega}) + \frac{1}{2} X(\hat{\omega} - \pi)$$

Z-Transform Analysis

$$\delta_D[n] = \begin{cases} 1 & \text{if } n/D \text{ is an integer} \\ 0 & \text{otherwise} \end{cases}$$

$$v[n] = \delta_D[n]x[n]$$

$$V[z] = \cdots + v[0]z^{0} + v[D]z^{-D} + v[2D]z^{-2D} + \cdots$$
 $y[n]$

$$V[z] = \sum_{n=-\infty}^{+\infty} v[n]z^{-n} = \sum_{m=-\infty}^{+\infty} v[mD]z^{-mD} = F(z^{D})$$

T Sampling Period

Z-Transform Analysis

$$\delta_2[n] = \frac{1}{2}(1 + (-1)^n) = \frac{1}{2}(1 + e^{-j\pi n}) = \begin{cases} 1 & \text{if } n/2 \text{ is an integer (even)} \\ 0 & \text{otherwise} \end{cases}$$

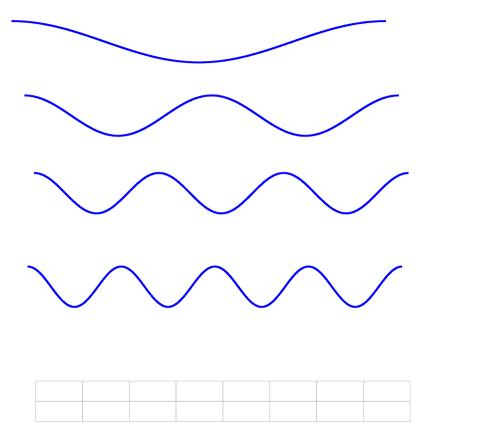
$$v[n] = \frac{1}{2}x[n] + \frac{1}{2}e^{-j\pi n}x[n]$$
 $x[n] = e^{j\omega n}$

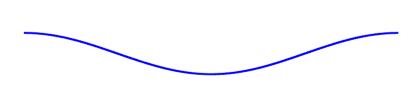
$$v[n] = \frac{1}{2}e^{j\omega n} + \frac{1}{2}e^{-j\pi n}e^{j\omega n} = \frac{1}{2}e^{j\omega n} + \frac{1}{2}e^{+j(\omega-\pi)n}$$

$$V(z) = \frac{1}{2} \sum_{n=-\infty}^{+\infty} \left(x[n] z^{-n} + x[n] (-z)^{-n} \right) = \frac{1}{2} X(z) + \frac{1}{2} X(-z)$$

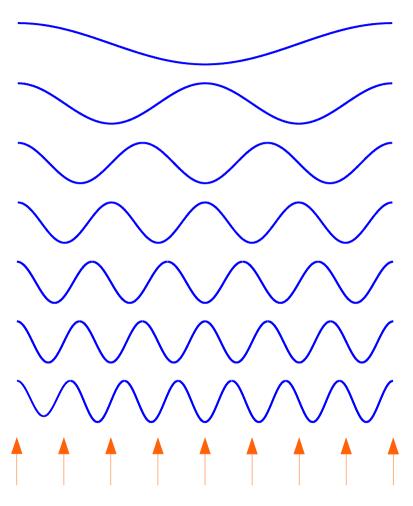
$$V(\omega) = V(e^{j\omega}) = \frac{1}{2}X(e^{j\omega}) + \frac{1}{2}X(e^{-j\pi}e^{j\omega}) = \frac{1}{2}X(\omega) + \frac{1}{2}X(\omega - \pi)$$

Measuring Rotation Rate





Signals with Harmonic Frequencies (1)



1 cvcle / sec

2 Hz

2 cycles / sec

3 Hz

3 cycles / sec

4 Hz

4 cycles / sec

5 Hz

5 cycles / sec

6 Hz

6 cycles / sec

7 Hz

7 cycles / sec

$$\cos (1.2 \pi t) = \frac{e^{+j(1.2\pi)t} + e^{-j(1.2\pi)t}}{2}$$

$$\cos (2 \cdot 2\pi t) = \frac{e^{+j(2 \cdot 2\pi)t} + e^{-j(2 \cdot 2\pi)t}}{2}$$

$$\cos (3 \cdot 2\pi t) = \frac{e^{+j(3 \cdot 2\pi)t} + e^{-j(3 \cdot 2\pi)t}}{2}$$

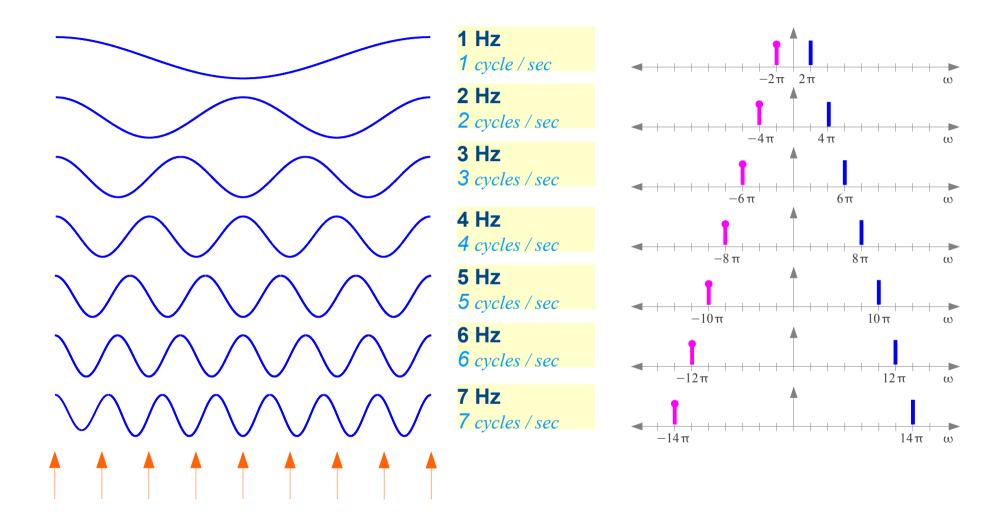
$$\cos (4 \cdot 2 \pi t) = \frac{e^{+j(4 \cdot 2\pi)t} + e^{-j(4 \cdot 2\pi)t}}{2}$$

$$\cos (5.2 \pi t) = \frac{e^{+j(5.2\pi)t} + e^{-j(5.2\pi)t}}{2}$$

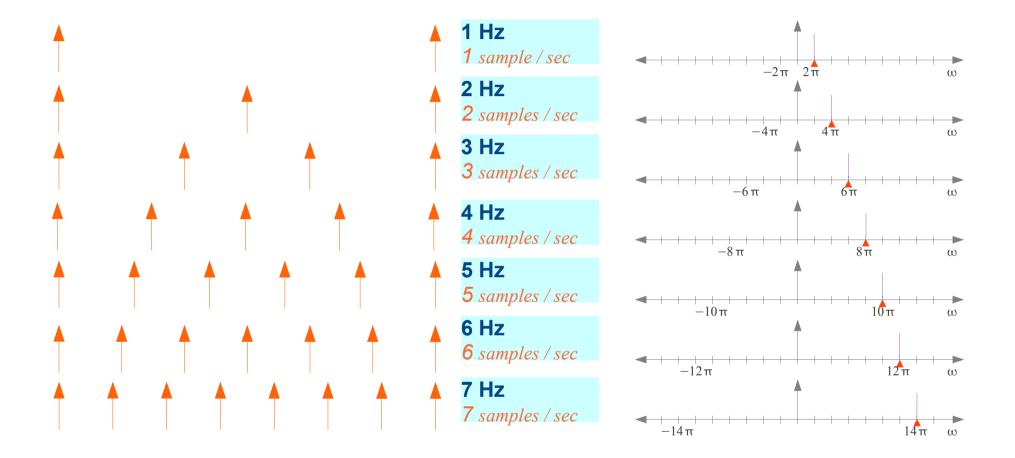
$$\cos (6.2\pi t) = \frac{e^{+j(6.2\pi)t} + e^{-j(6.2\pi)t}}{2}$$

$$\cos (7.2 \pi t) = \frac{e^{+j(7.2\pi)t} + e^{-j(7.2\pi)t}}{2}$$

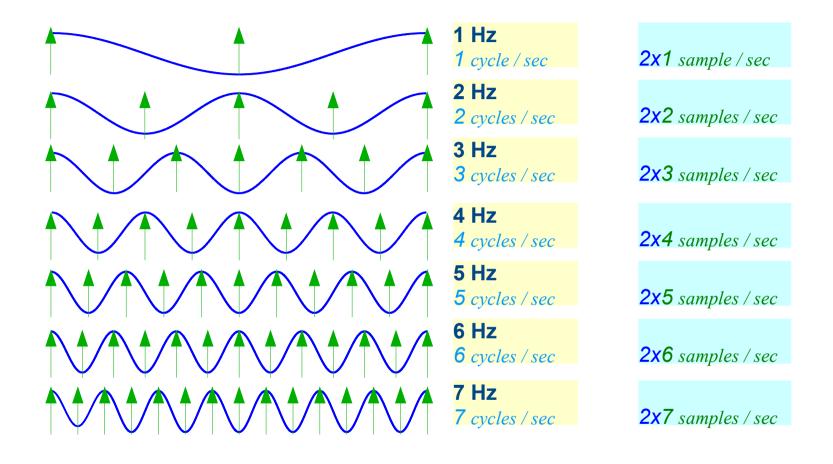
Signals with Harmonic Frequencies (2)



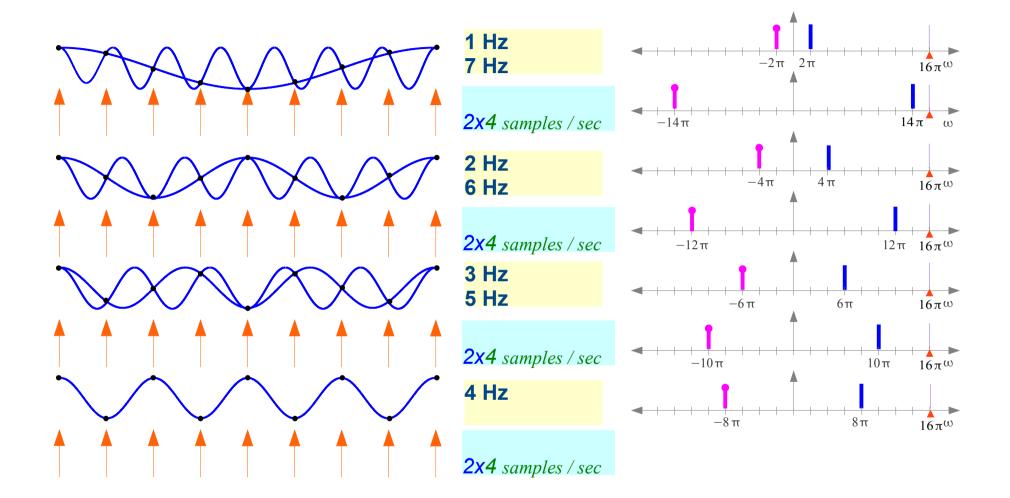
Sampling Frequency



Nyquist Frequency

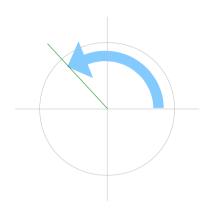


Aliasing



Sampling

$$\omega_s = 2\pi f_s (rad/sec)$$

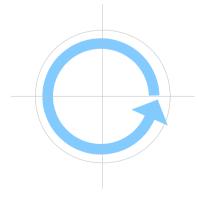


$$\omega_1 = 2\pi f_1$$

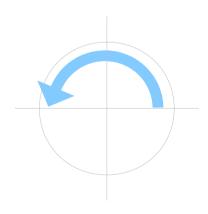
$$\omega_1 = \frac{\omega_s}{2} \ (rad/sec)$$

$$f_1 = \frac{f_s}{2} \ (rad \, lsec)$$

$$2\pi (rad) / T_s(sec)$$



$$\pi$$
 (rad) / T_s (sec)

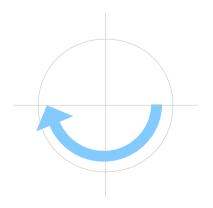


$$\omega_2 = 2\pi f_2$$

$$\omega_1 = \frac{\omega_s}{2} \ (rad/sec)$$
 $\omega_2 = -\frac{\omega_s}{2} \ (rad/sec)$

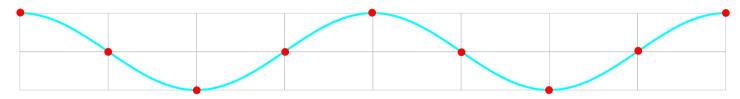
$$f_1 = \frac{f_s}{2} (rad/sec)$$
 $f_2 = -\frac{f_s}{2} (rad/sec)$

$$-\pi$$
 (rad) / T_s (sec)

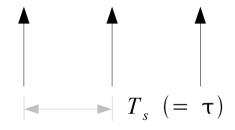


Sampling



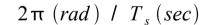


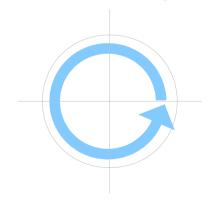
$$\omega_s = 2\pi f_s (rad/sec)$$

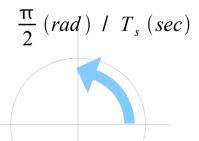


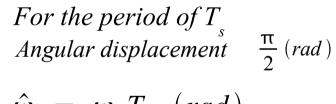












$$\hat{\omega} = \omega \cdot T_s \quad (rad)$$

$$= 2\pi f_1 \cdot T_s \quad (rad)$$

$$= 2\pi \frac{f_s}{4} \cdot T_s \quad (rad)$$

$$= \frac{\pi}{2} \quad (rad)$$

Angular Frequencies in Sampling

continuous-time signals

Signal Frequency

$$f_0 = \frac{1}{T_0}$$

Signal Angular Frequency

$$\omega_0 = 2\pi f_0 (rad/sec)$$

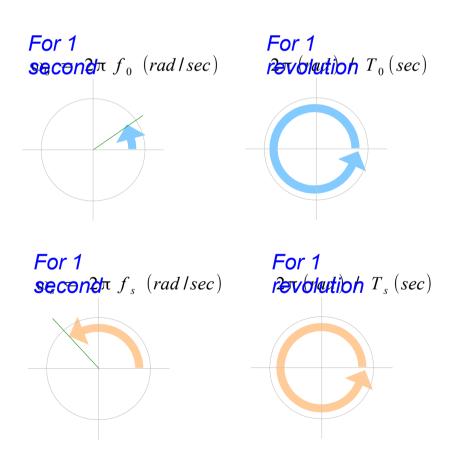
sampling sequence

Sampling Frequency

$$f_s = \frac{1}{T_s}$$

Sampling Angular Frequency

$$\omega_s = 2\pi f_s \ (rad \, lsec)$$



References

- [1] http://en.wikipedia.org/
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003
- [3] A "graphical interpretation" of the DFT and FFT, by Steve Mann
- [4] R. Cristi, "Modern Digital Signal Processing"