```
\mathbf{U} \cdot \mathbf{I} \cdot \mathbf{\eta} = \mathbf{F}_{\mathbf{wheel}} \cdot \mathbf{V}_{\mathbf{A/B}}
T_{wheel} = 8.55 \cdot 70\% \cdot I \cdot 10^{-3} \cdot n
                                                        (n is the gear ratio)
\mathbf{T}_{\text{wheel}} = \mathbf{F}_{\text{wheel}} \cdot \mathbf{R}_{\text{wheel}}
S = \frac{1}{2} \mathbf{a} \cdot \mathbf{t}^2 = \frac{1}{2} \mathbf{V}_{A/B} \cdot \mathbf{t}_{A/B}
                                                  (S = 6 \text{ m, at point A/B})
F \cdot t = m \cdot \Delta V \rightarrow (F_{wheel} - F_{rolling}) \cdot t_{A/B} = m \cdot V_{A/B}
eq1 := 7 \cdot 0.7 = Fwheel \cdot Vab
                                                        4.9 = Fwheel Vab
eq2 := Twheel = 5.985 \cdot 0.001 \cdot n \cdot 0.93
                                                     Twheel = 0.00556605 n
eq5 := Twheel = Fwheel \cdot 0.04
                                                      Twheel = 0.04 Fwheel
eq3 := 6 = \frac{1}{2} \cdot Vab \cdot t
                                                           6 = \frac{1}{2} Vab t
eq4 := (Fwheel - 0.1104) \cdot t = 0.75 \cdot Vab
                                               (Fwheel - 0.1104) t = 0.75 Vab
simplify(solve(\{eq1, eq2, eq3, eq4, eq5\}, [Vab, n, t, Fwheel, Twheel]))
                       [Vab = 4.142427119, n = 8.500688297, t = 2.896852414, Fwheel]
                             = 1.182881402, Twheel = 0.04731525609], [Vab = -2.071213560]
                             -3.825725660 \text{ I}, n = -3.853653497 + 7.118059363 \text{ I}, t =
                             -1.313242534 + 2.425682101 \text{ I}, Fwheel = -0.5362407012
                             + 0.9904868579 I, Twheel = -0.02144962805
                             +0.03961947432I], [Vab = -2.071213560 + 3.825725660I, n =
                             -3.853653497 - 7.118059363  I, t = -1.313242534
                             -2.425682101 \text{ I}, Fwheel = -0.5362407012 - 0.9904868579 \text{ I},
                            Twheel = -0.02144962805 - 0.03961947432I
```

So Vab = 4.142427119, *n* = 8.500688297, *t* = 2.896852414, *Fwheel*

= 1.182881402, Twheel = 0.04731525609