



Special relativity and steps towards general relativity: SR

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- SR: spacetime = w:Minkowski space





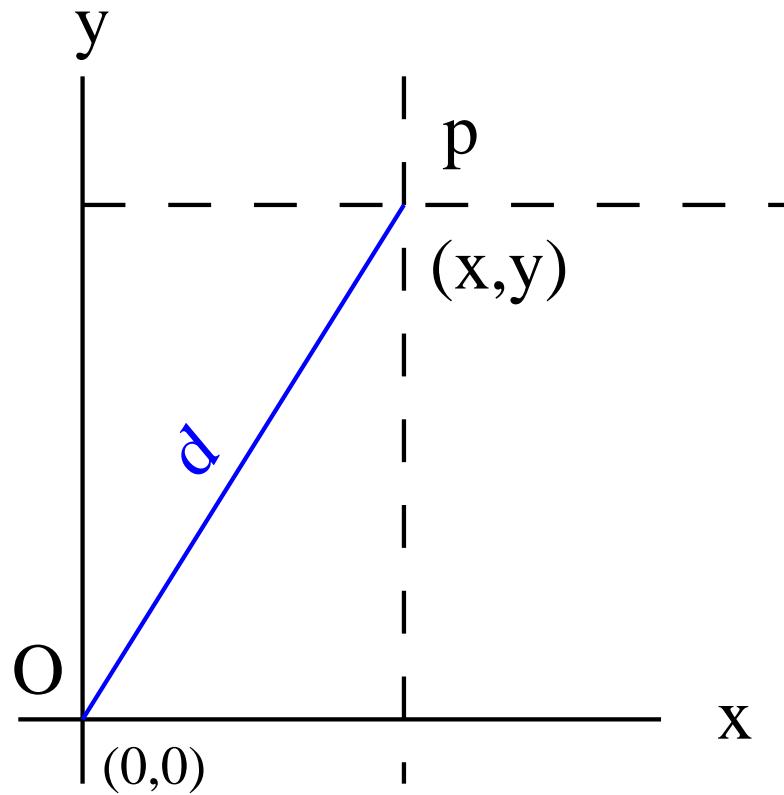
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- SR: spacetime = [w:Minkowski space](#)
- GR: spacetime = a solution of the
[w:Einstein field equations](#)





SR: Minkowski spacetime

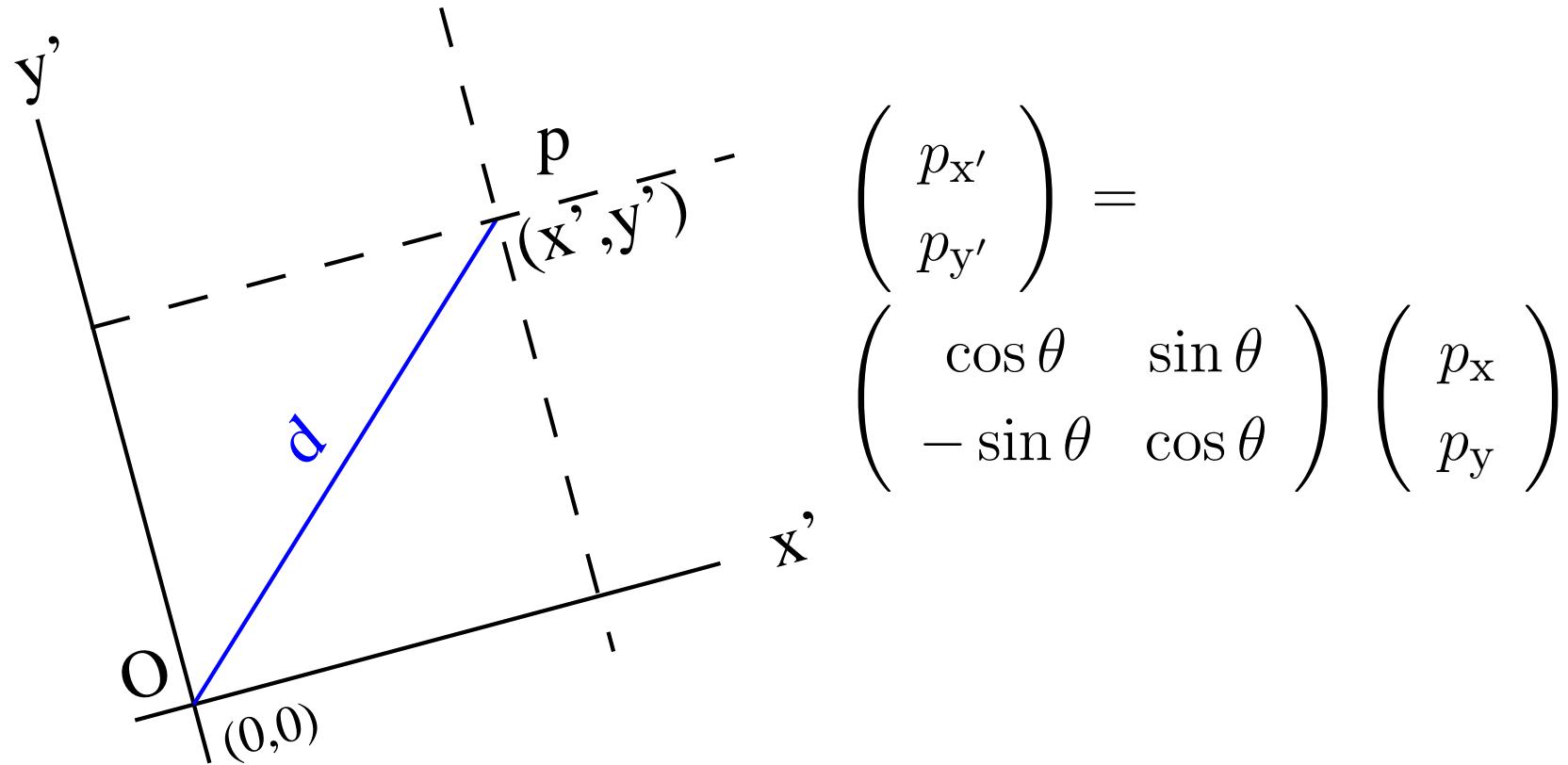


p at (x, y) , distance from observer at O is d





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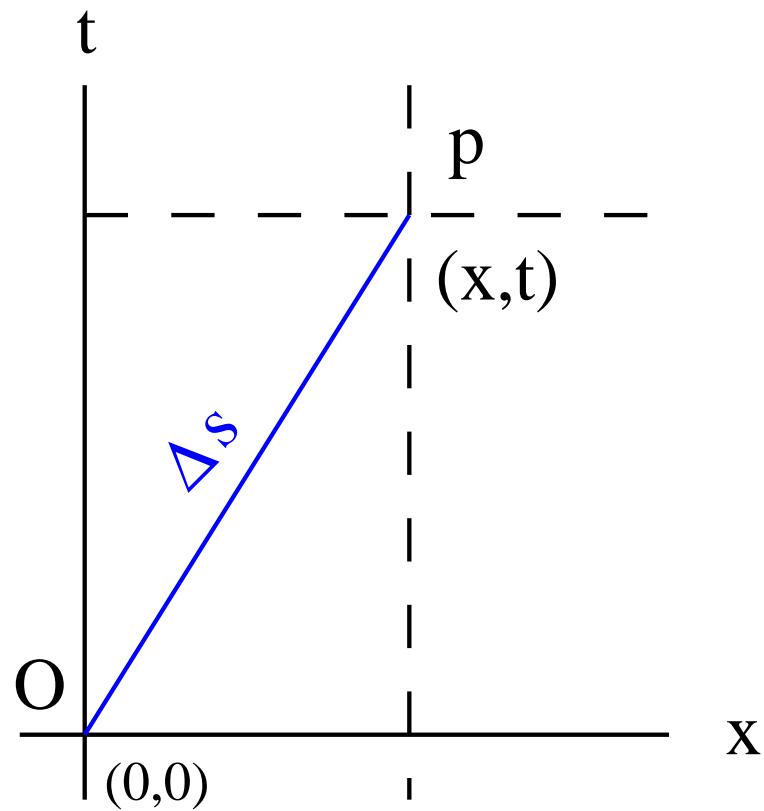


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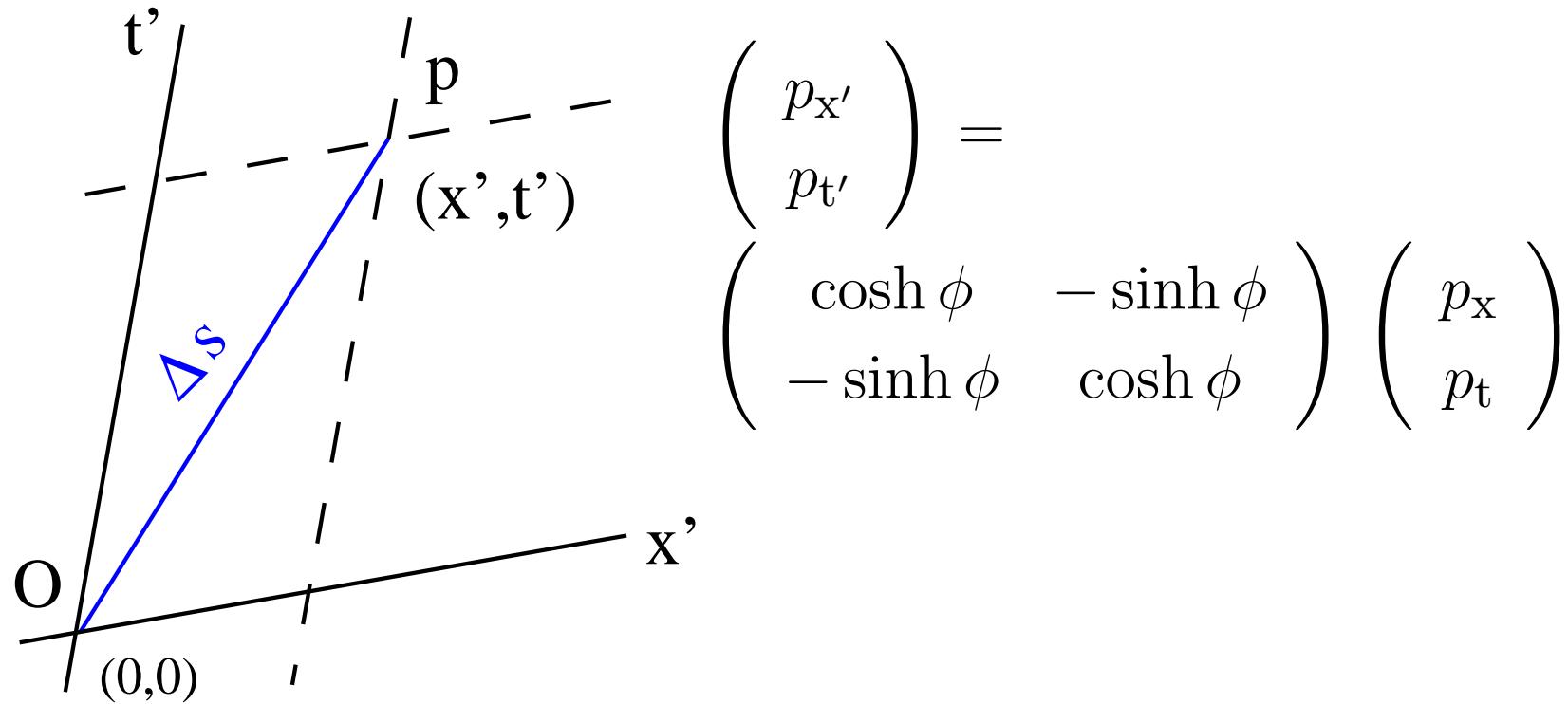


p at (x, t) , w:invariant interval from observer at O is Δs
where $(\Delta s)^2 = -(\Delta t)^2 + (\Delta x)^2$





SR: Minkowski spacetime



p at (x', t') , invariant interval from observer at O is $\Delta s = (\Delta s)^2 = -(\Delta t')^2 + (\Delta x')^2 = \text{unchanged}$





SR: Lorentz transformation

$$\Lambda(\phi) := \begin{pmatrix} \cosh \phi & -\sinh \phi \\ -\sinh \phi & \cosh \phi \end{pmatrix}$$

$$\cosh \phi := \frac{e^\phi + e^{-\phi}}{2}$$

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w:hyperbolic function





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L = $\frac{1 \text{ s}}{1 \text{ s}} = 1$ (dimensionless)



SR: rapidity ϕ vs velocity β

What is ϕ ?





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What is ϕ ?

observer A has worldline $(x, t) = (0, t)$





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observer B has worldline $(x', t') = (0, t')$





SR: rapidity ϕ vs velocity β

What is ϕ ?

observer B has worldline $(x', t') = (0, t')$

in A's coordinate system, B's worldline is:

$$\begin{pmatrix} 0 \\ t' \end{pmatrix} = \Lambda \begin{pmatrix} x \\ t \end{pmatrix}$$





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What is ϕ ?

observer B has worldline $(x', t') = (0, t')$

in A's coordinate system, B's worldline is:

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where velocity $\beta := v/c \equiv v = \tanh \phi$





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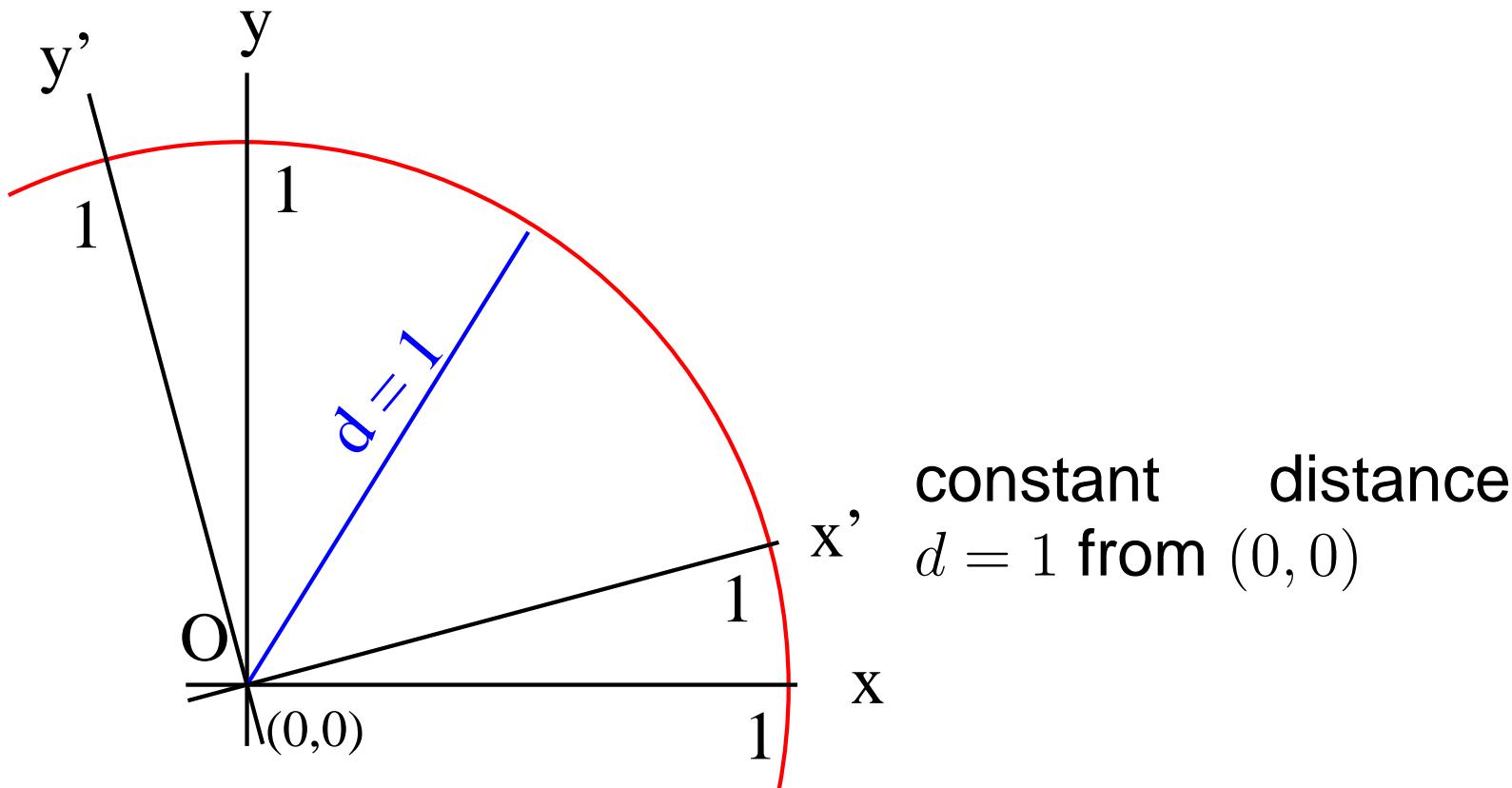




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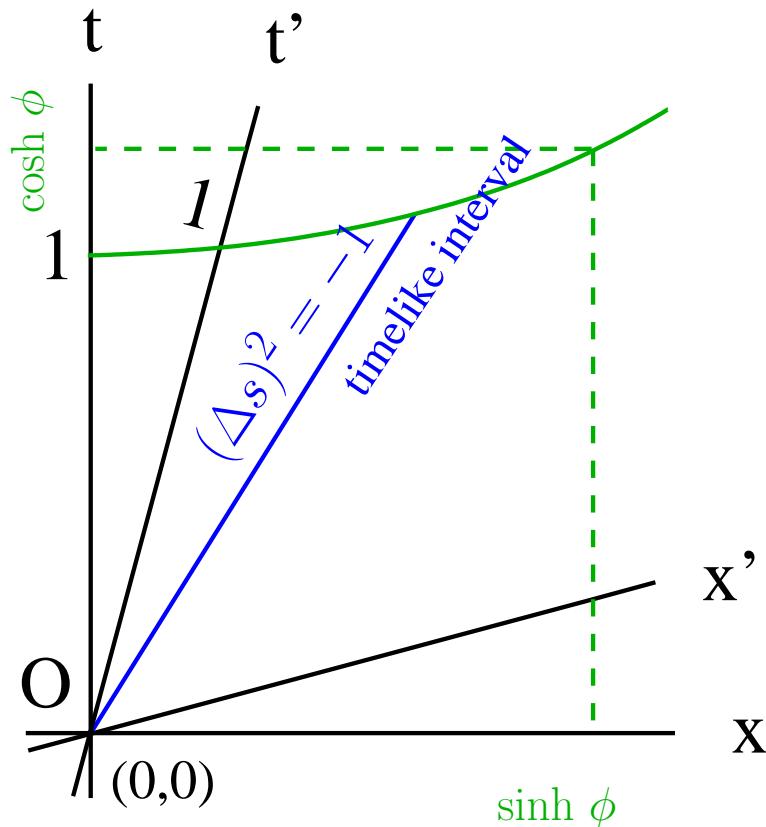




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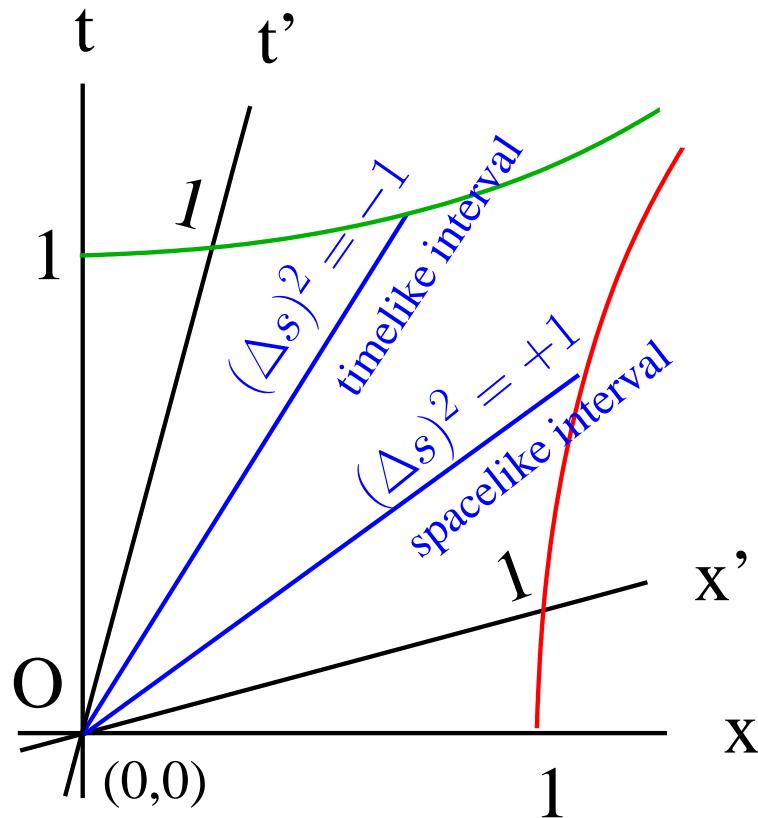




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Can high ϕ push the t' axis close to the x axis?



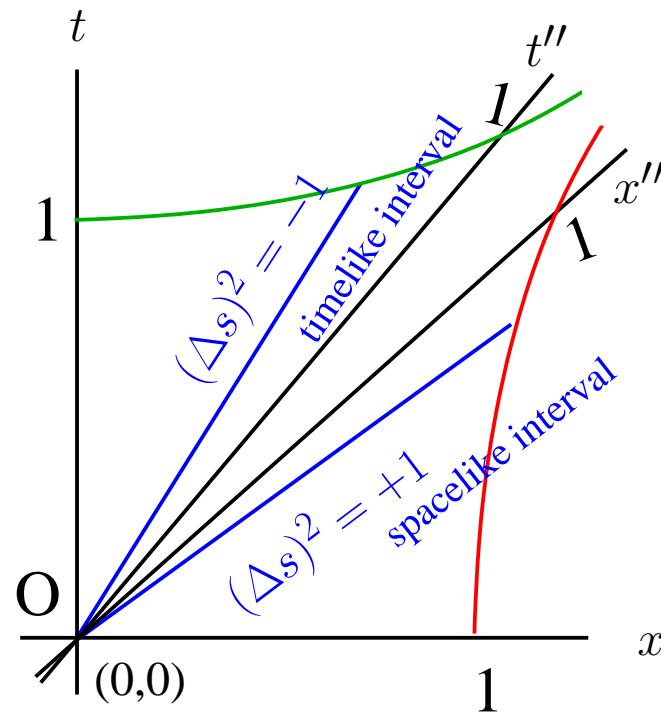


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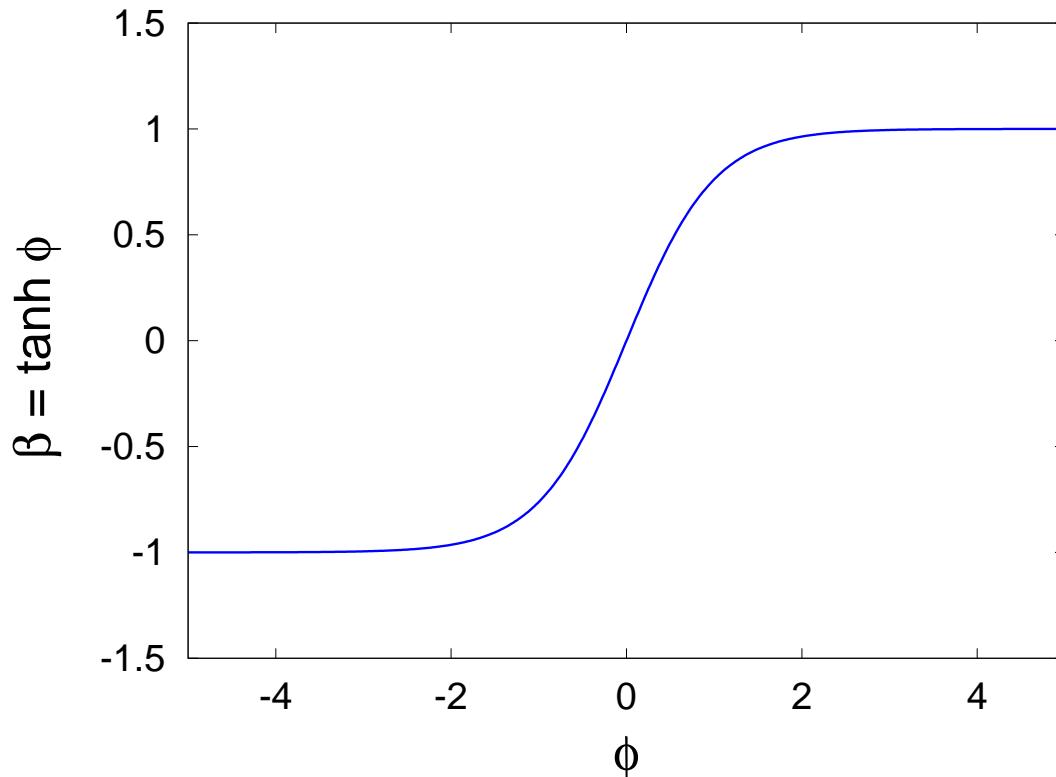


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- w:[Michelson-Morley experiment \(1887\)](#)





SR: adding velocities

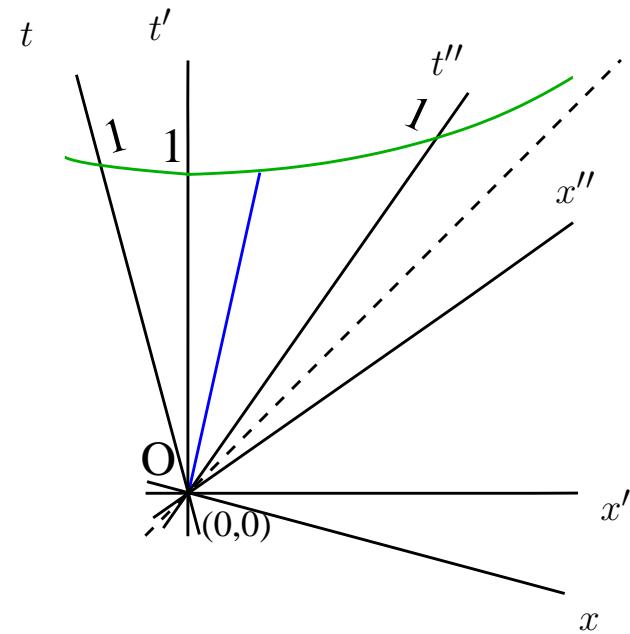
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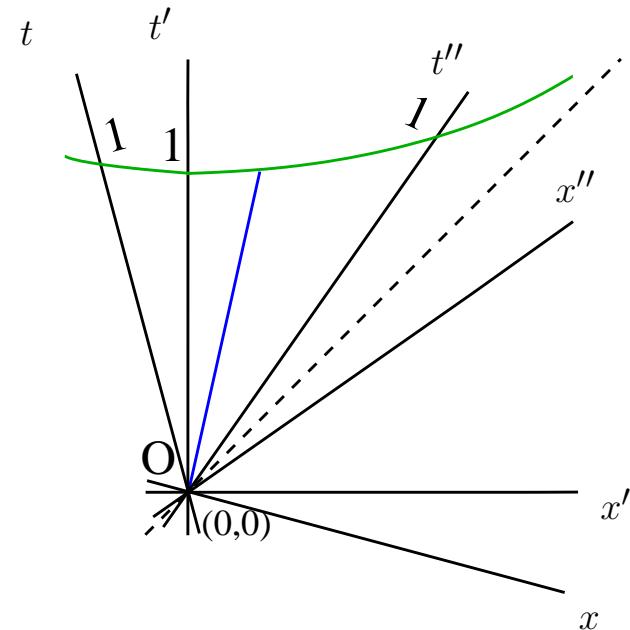
where $\tanh \phi_1 = \beta_1 = 0.1$





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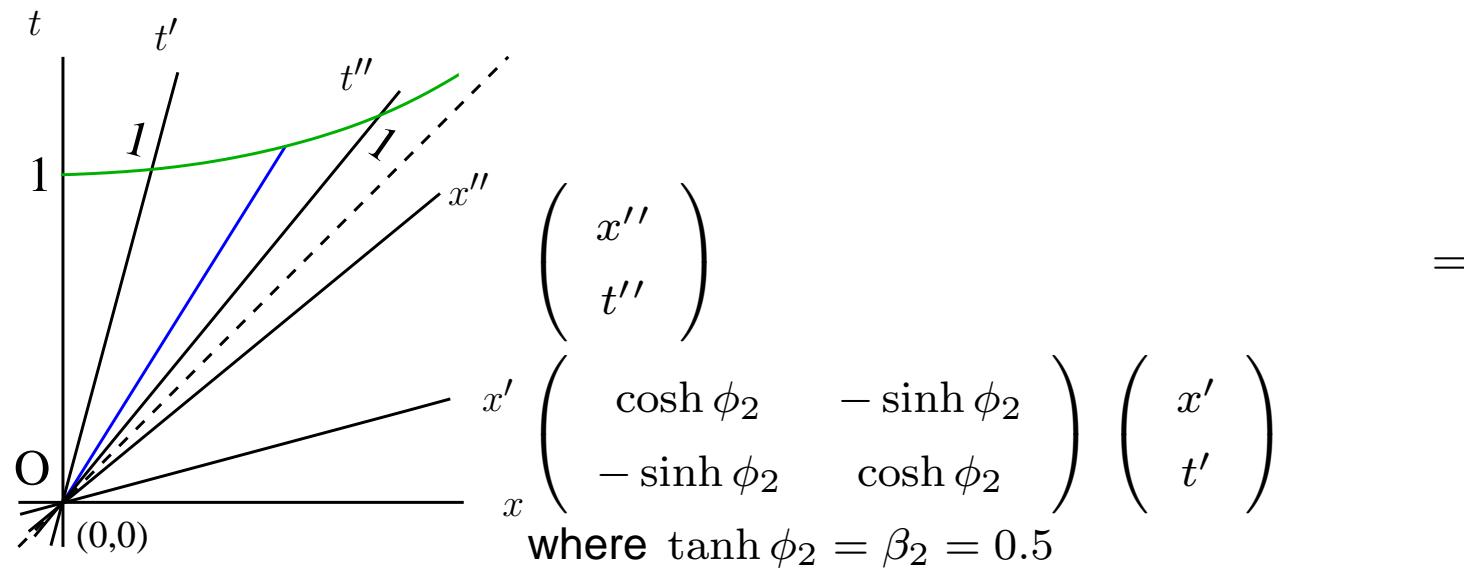
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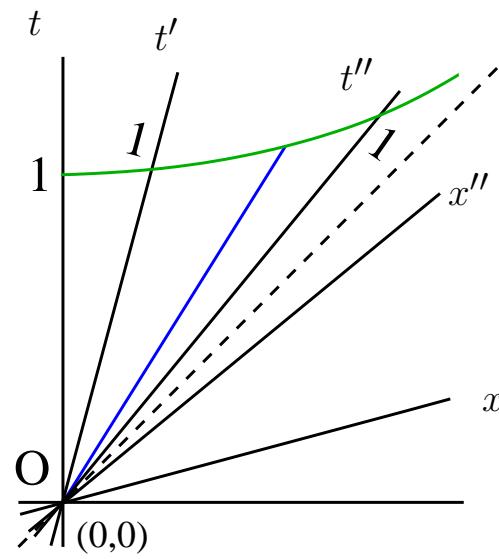
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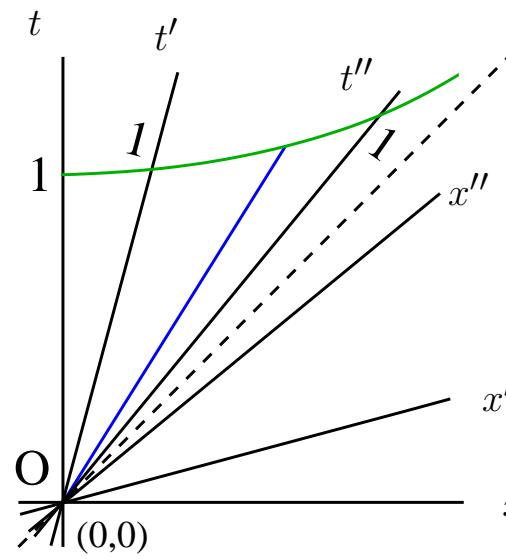
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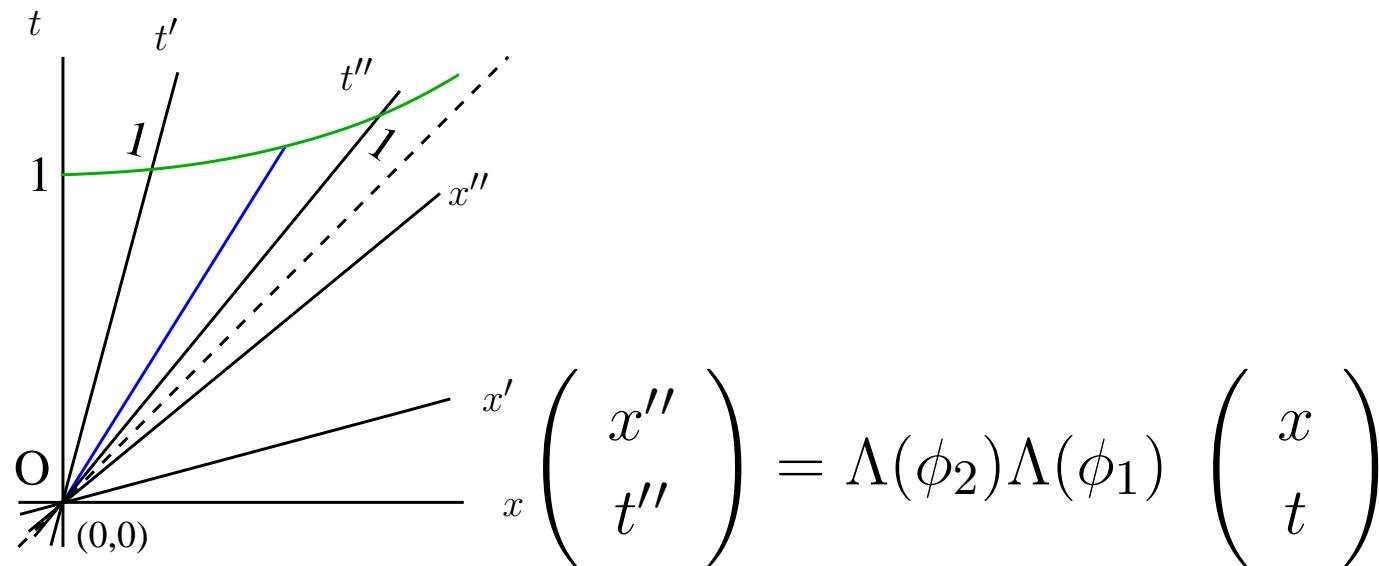
but $\Lambda(\phi_2)\Lambda(\phi_1) = \Lambda(\phi_1 + \phi_2)$





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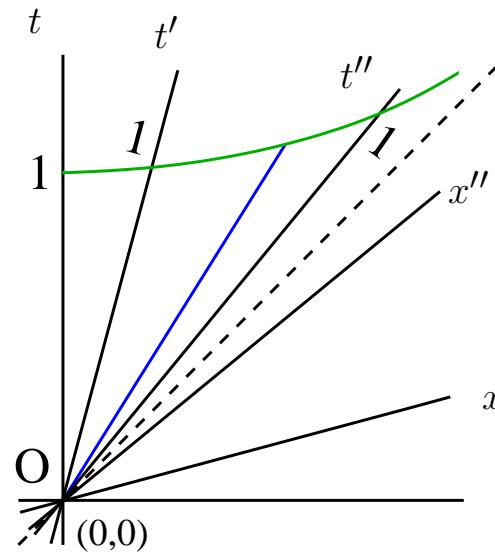
cf. rotation θ_1 "plus" rotation θ_2 = rotation $\theta_1 + \theta_2$





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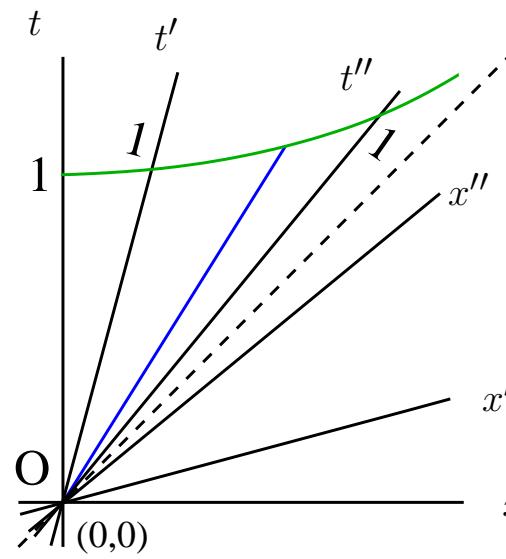
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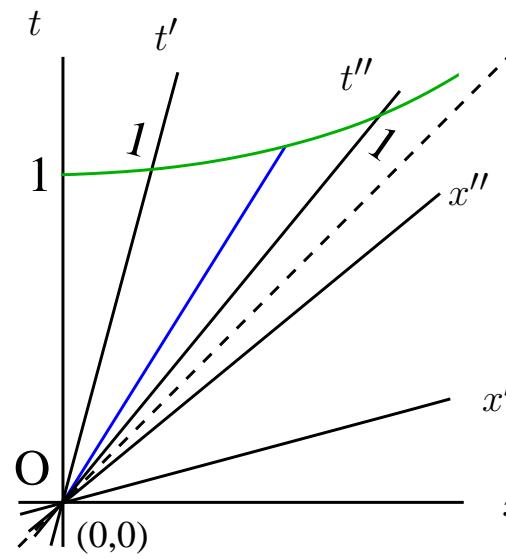
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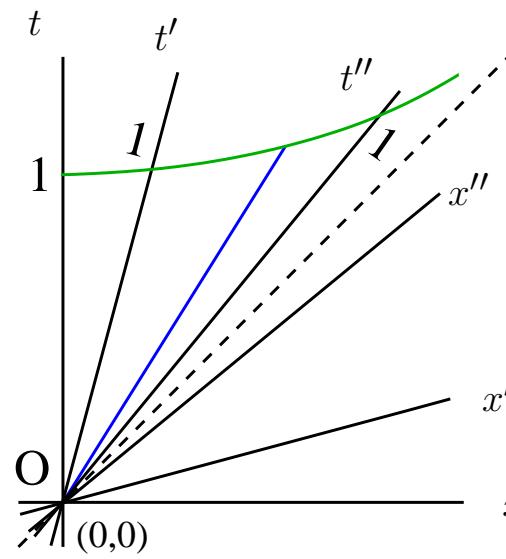
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$$x \begin{pmatrix} x'' \\ t'' \end{pmatrix} = \Lambda(\phi_2)\Lambda(\phi_1) \begin{pmatrix} x \\ t \end{pmatrix}$$

but $\Lambda(\phi_2)\Lambda(\phi_1) = \Lambda(\phi_1 + \phi_2)$

$$\text{so } \beta_3 = \tanh(\phi_1 + \phi_2) = \frac{\beta_1 + \beta_2}{1 + \beta_1 \beta_2} = \frac{0.1 + 0.5}{1 + 0.1 \times 0.5} \approx 0.57$$





SR: Lorentz factor

Λ : alternative to hyperbolic trig functions





SR: Lorentz factor

Λ : alternative to hyperbolic trig functions

$$\Lambda(\phi) := \begin{pmatrix} \cosh \phi & -\sinh \phi \\ -\sinh \phi & \cosh \phi \end{pmatrix}$$

$$\cosh \phi := \frac{e^\phi + e^{-\phi}}{2}$$

$$\sinh \phi := \frac{e^\phi - e^{-\phi}}{2}$$

w:**hyperbolic function**





SR: Lorentz factor

Λ : alternative to hyperbolic trig functions

$$\Lambda(\beta) := \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix}$$

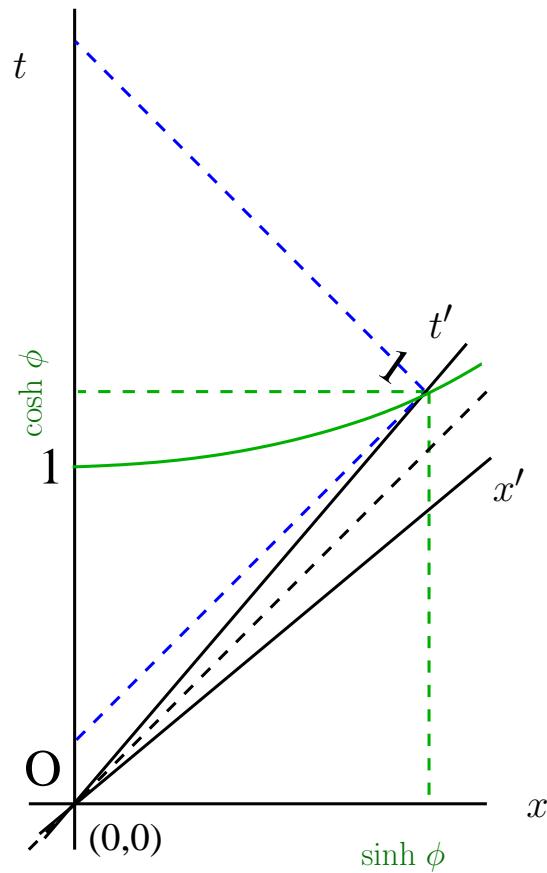
$$\begin{aligned}\beta &= \tanh \phi \\ \gamma &:= (1 - \beta^2)^{-1/2} = \\ &\text{Lorentz factor}\end{aligned}$$

$$\begin{aligned}\gamma &= \cosh \phi \\ \beta\gamma &= \sinh \phi\end{aligned}$$



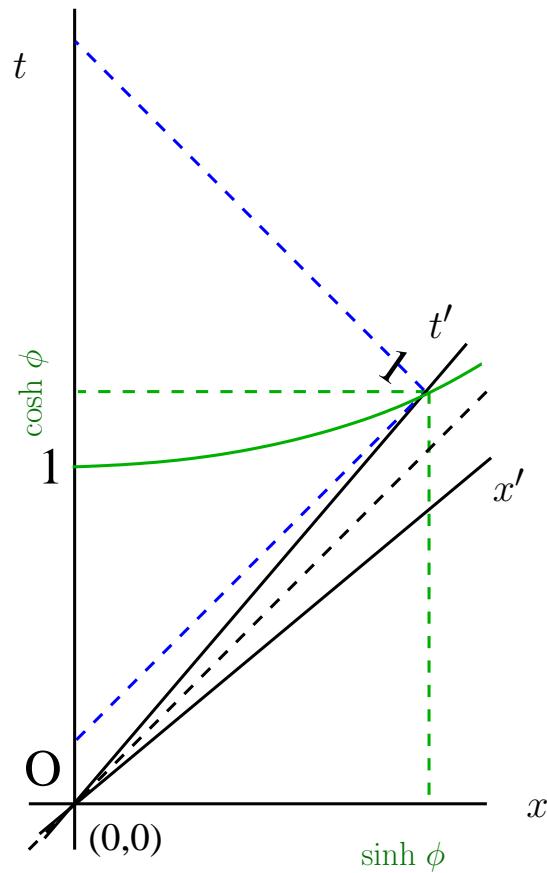


SR: worldline time dilation





SR: worldline time dilation

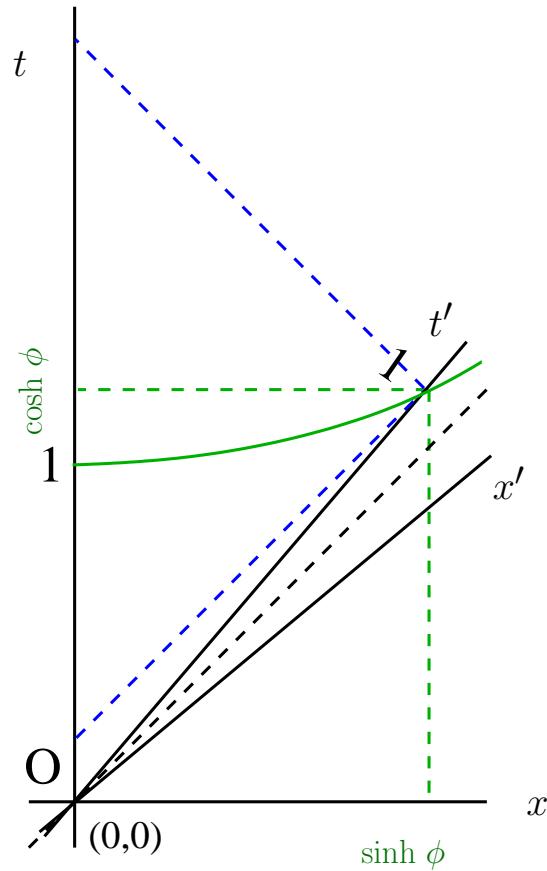


$$\cosh \phi \equiv \gamma$$





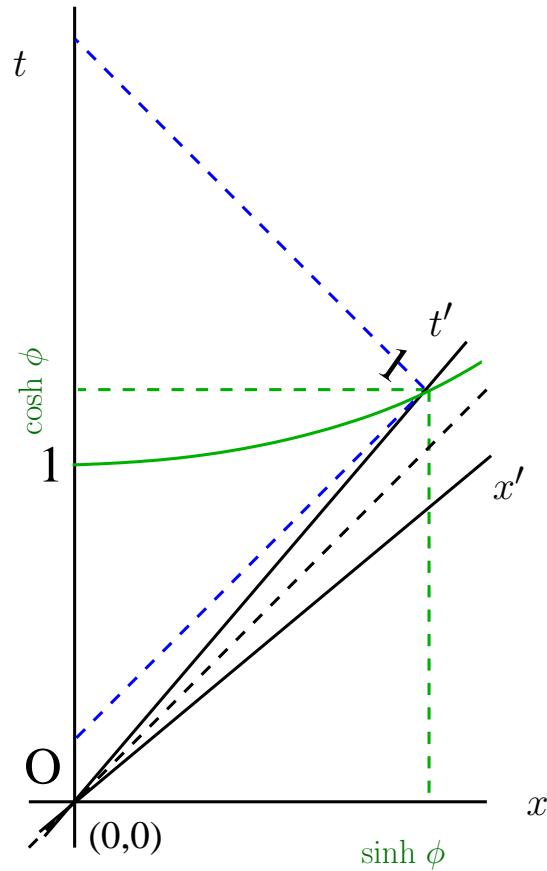
SR: worldline time dilation



$$\cosh \phi \equiv \gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$$



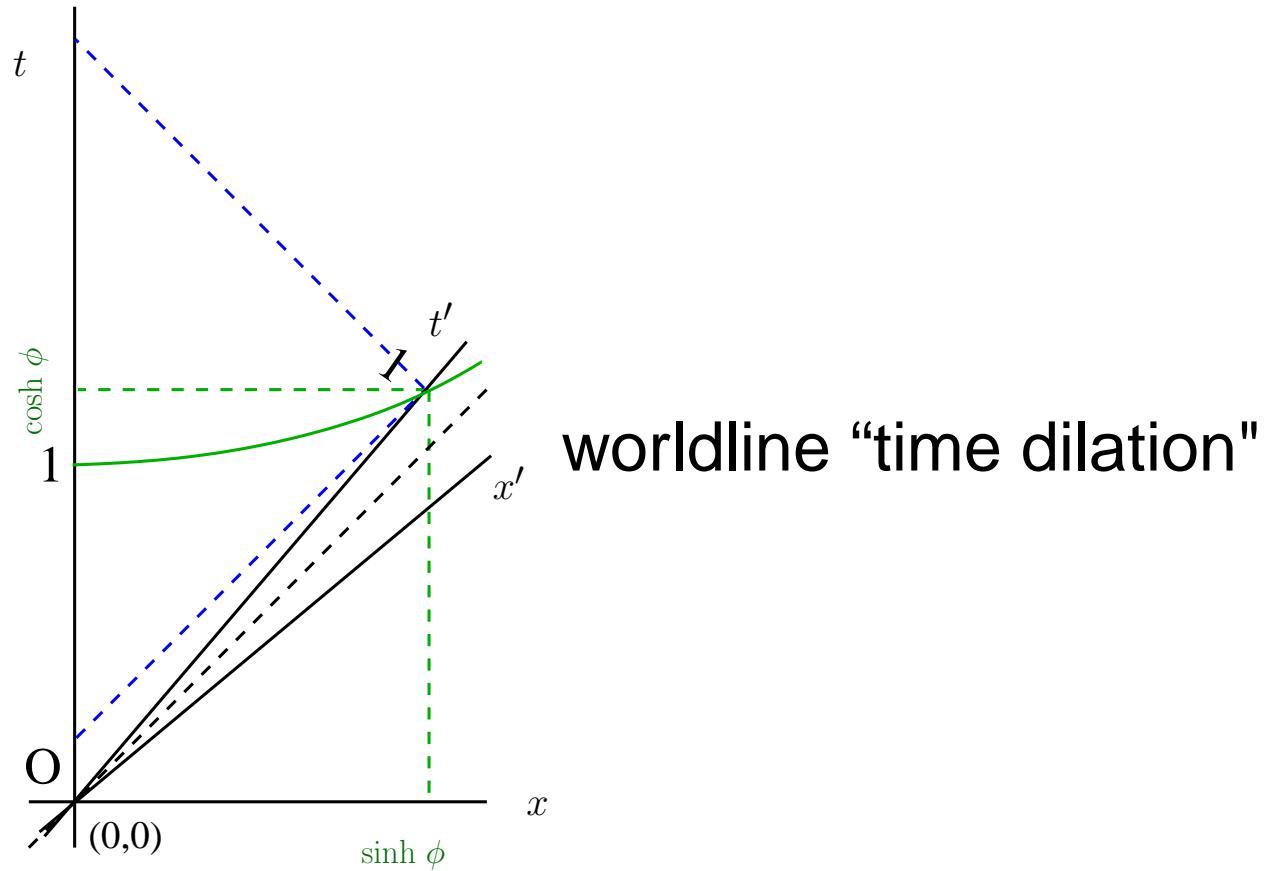
SR: worldline time dilation



$$\cosh \phi \equiv \gamma \equiv \frac{1}{\sqrt{1-\beta^2}} > 1$$



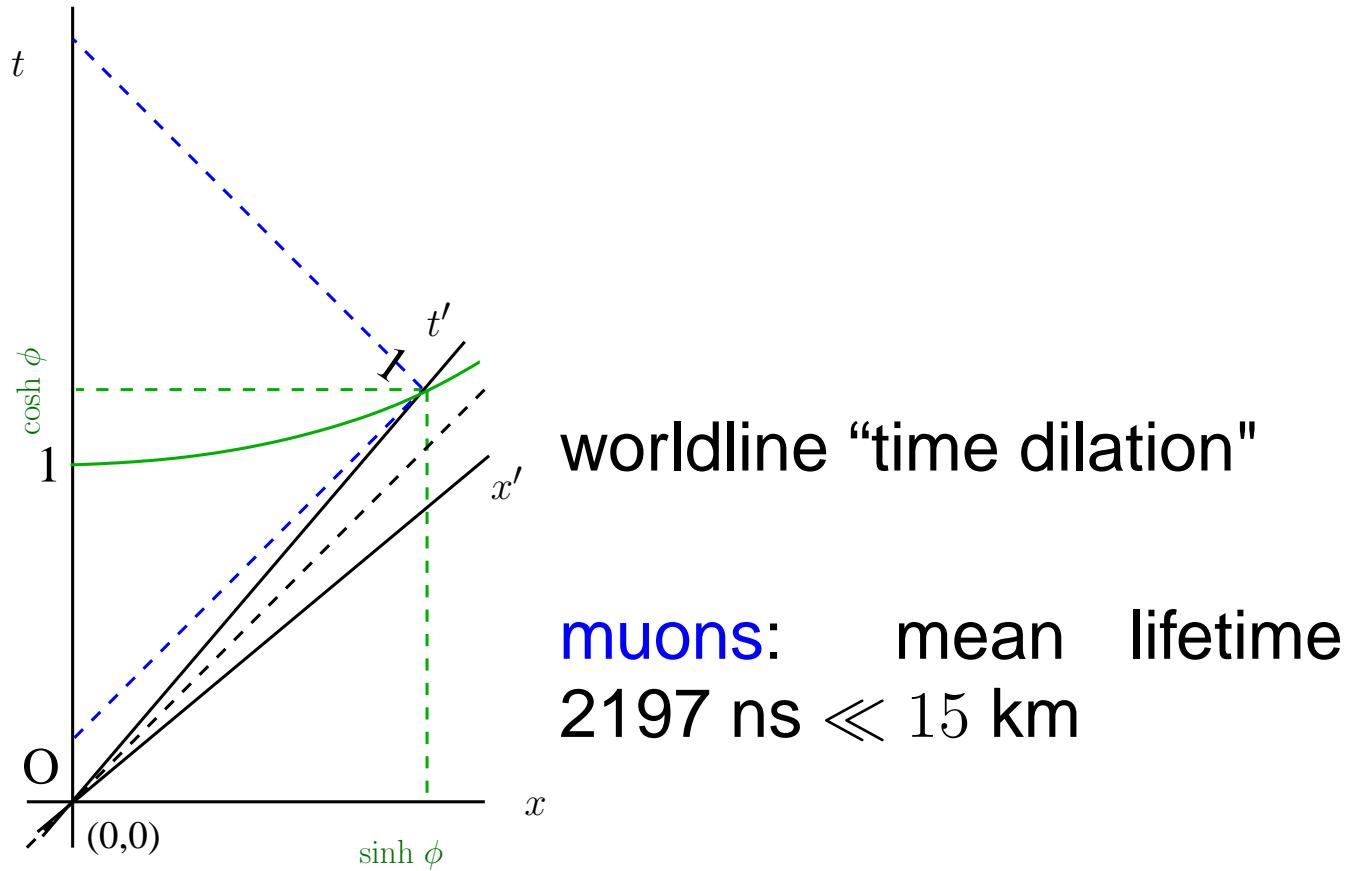
SR: worldline time dilation



$$\cosh \phi \equiv \gamma \equiv \frac{1}{\sqrt{1-\beta^2}} > 1$$

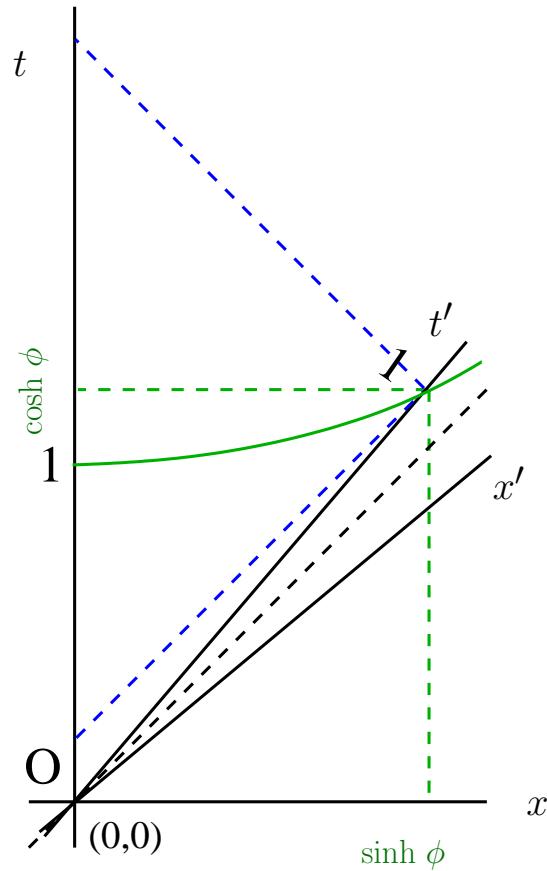


SR: worldline time dilation



$$\cosh \phi \equiv \gamma \equiv \frac{1}{\sqrt{1-\beta^2}} > 1$$

SR: worldline time dilation



worldline “time dilation”

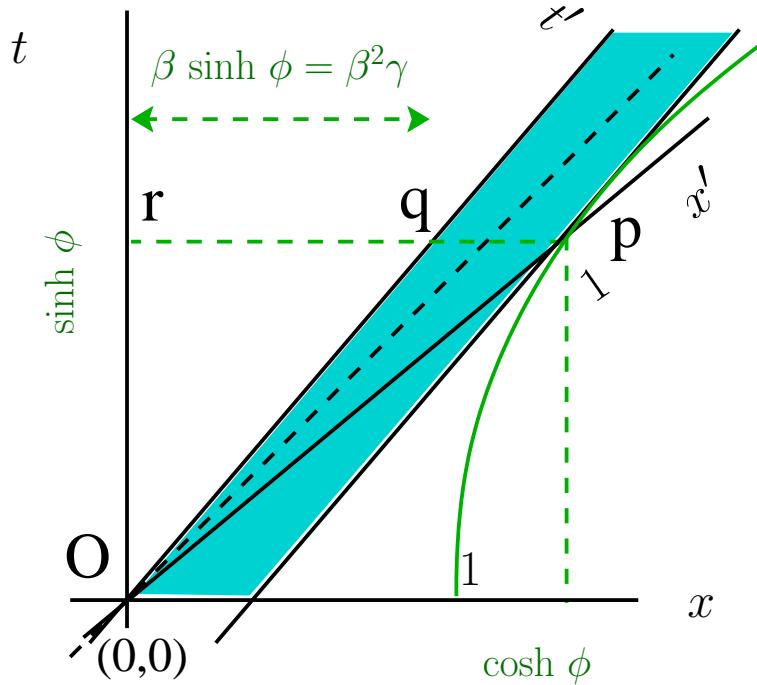
muons: mean lifetime
 $2197 \text{ ns} \ll 15 \text{ km}$

time dilation \Rightarrow muons
 can hit the ground

$$\cosh \phi \equiv \gamma \equiv \frac{1}{\sqrt{1-\beta^2}} > 1$$

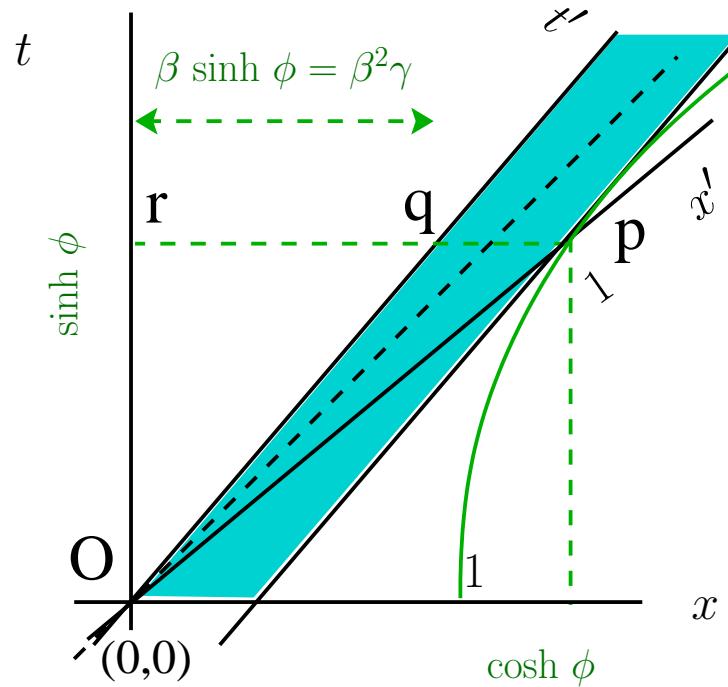


SR: worldsheet space contraction





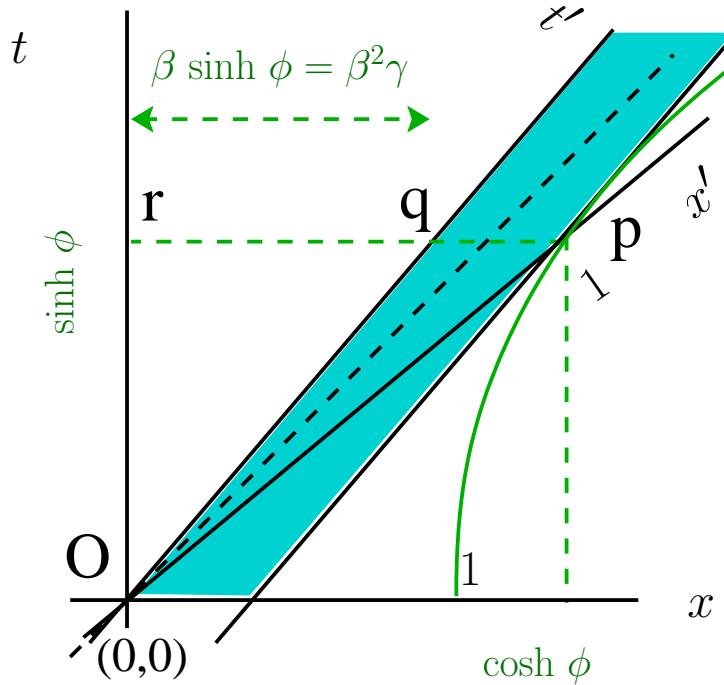
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} =$$



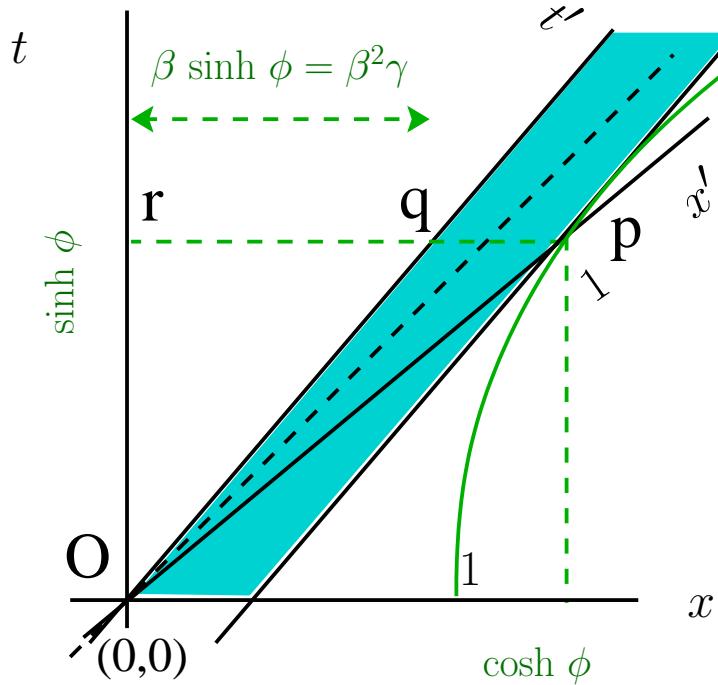
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = \cosh \phi - \beta \sinh \phi$$



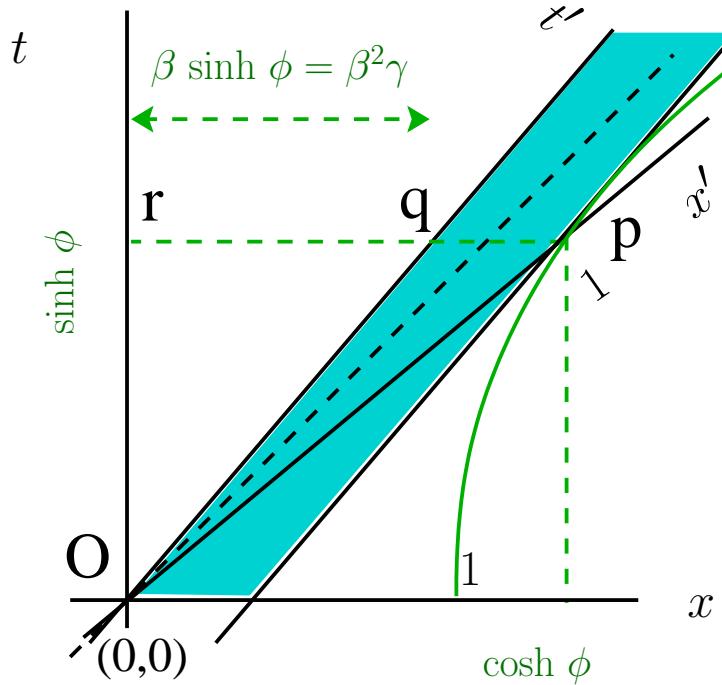
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = \gamma - \beta \beta \gamma$$



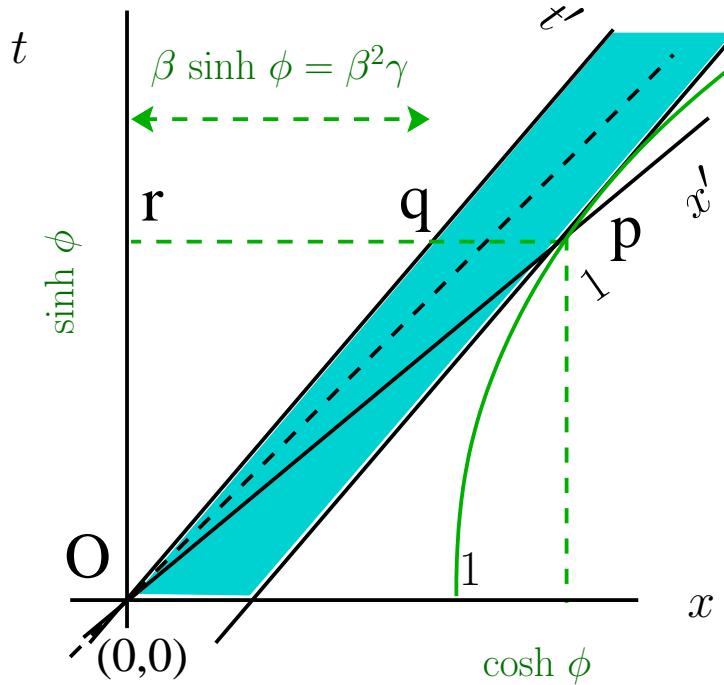
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = (1 - \beta^2)\gamma$$



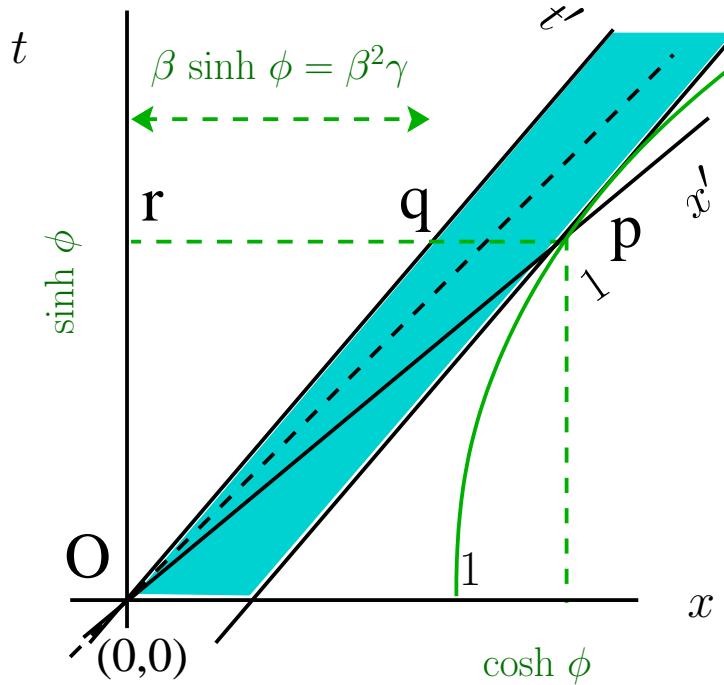
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = (1 - \beta^2)^{1+(-1/2)}$$



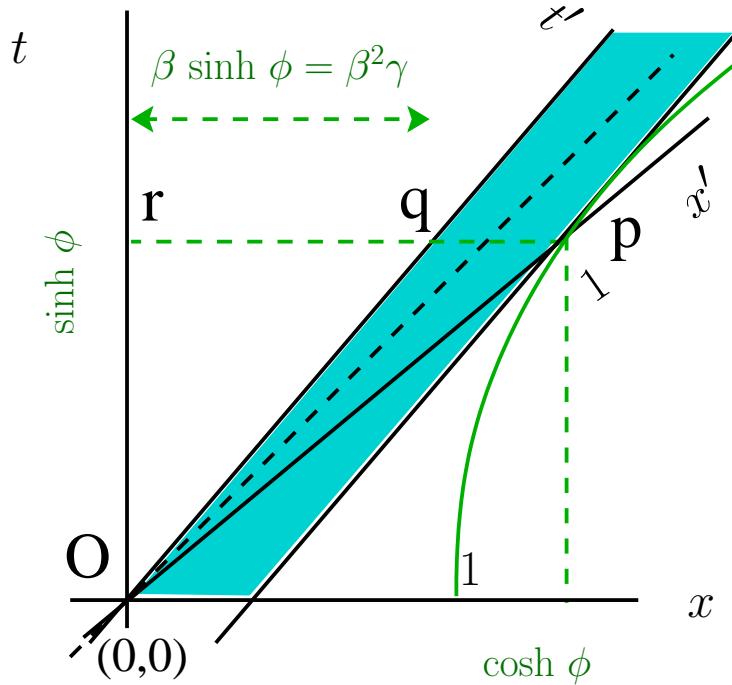
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = (1 - \beta^2)^{1/2}$$



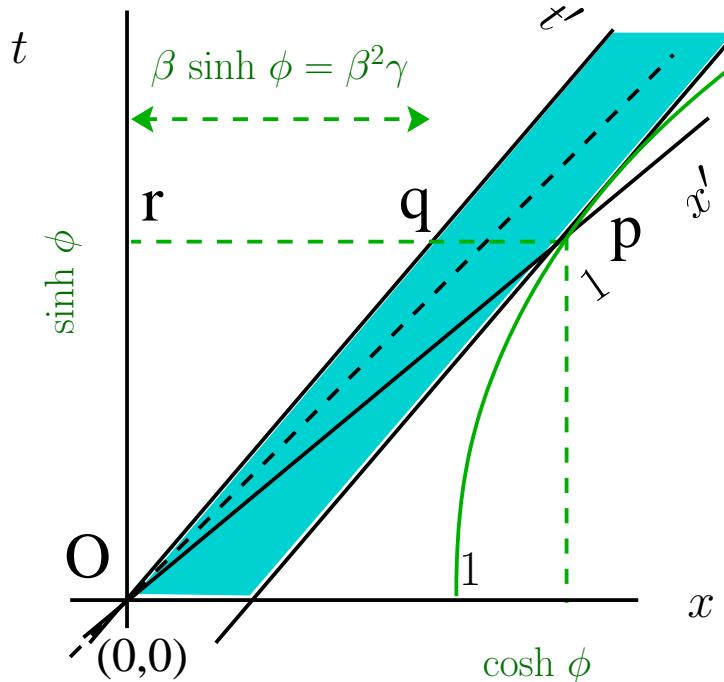
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = \gamma^{-1} < 1$$

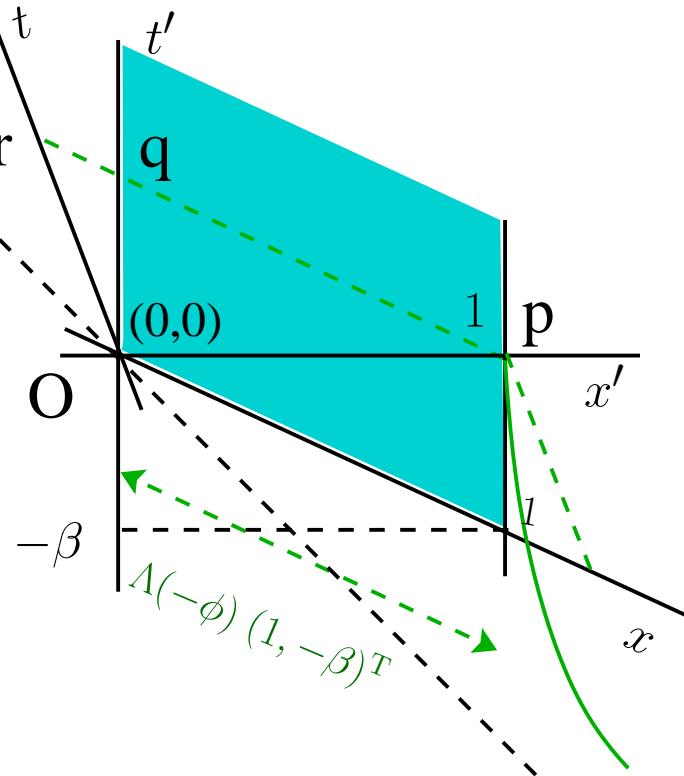


SR: worldsheet space contraction

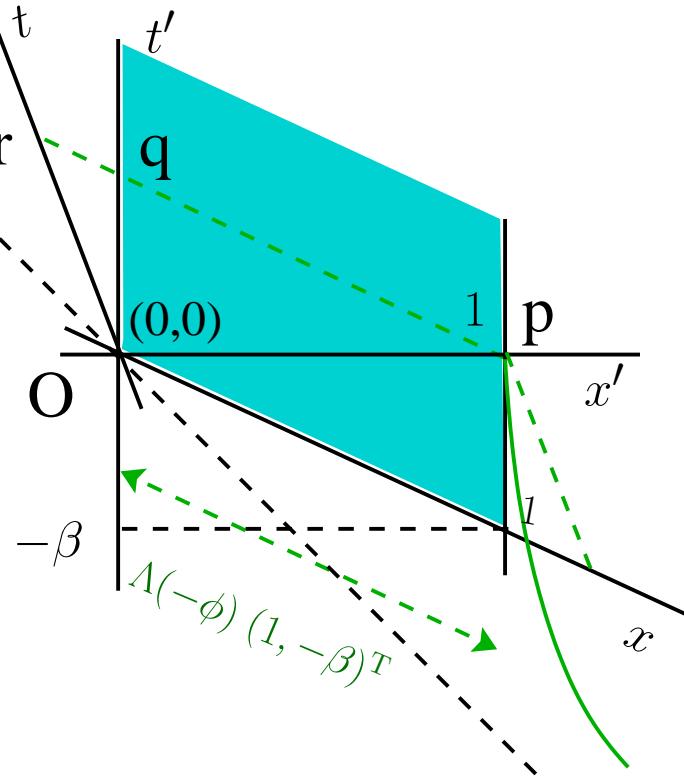


$$\sqrt{\Delta s^2(q, p)} = \gamma^{-1} < 1 \quad \text{worldsheet "space contraction"}$$

SR: worldsheet space contraction



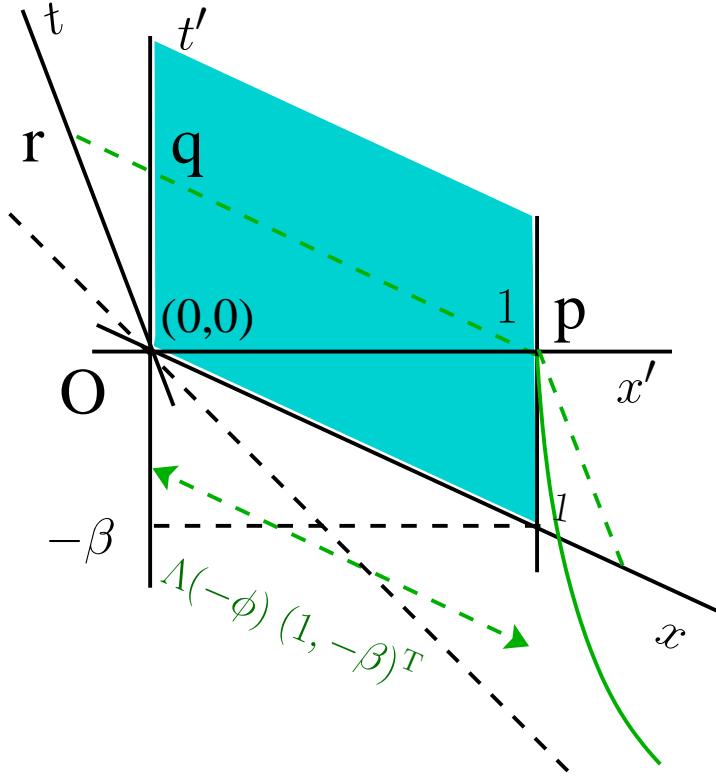
SR: worldsheet space contraction



$$\Lambda^{-1} \begin{pmatrix} 1 \\ -\beta \end{pmatrix} = \begin{pmatrix} \cosh \phi - \beta \sinh \phi \\ \sinh \phi - \beta \cosh \phi \end{pmatrix}$$

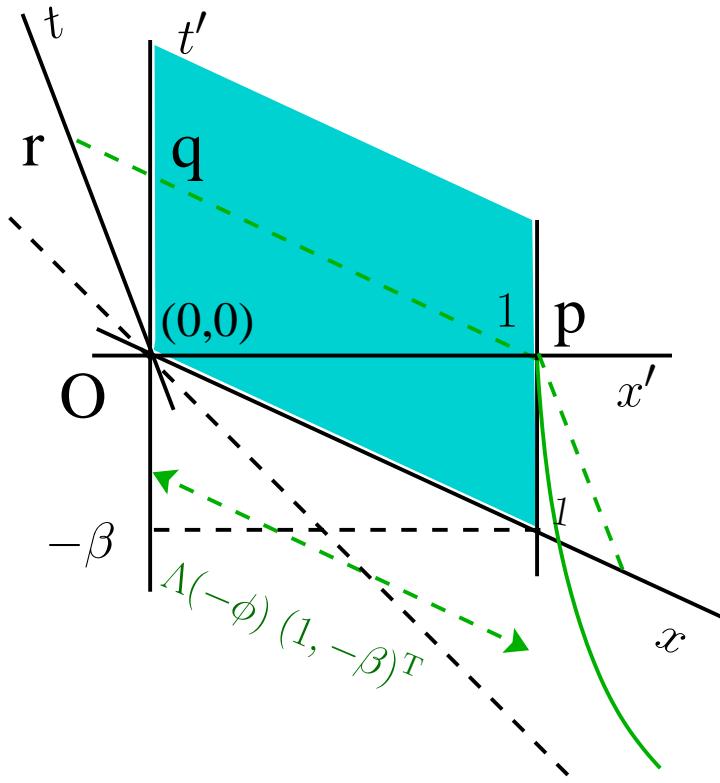


SR: worldsheet space contraction



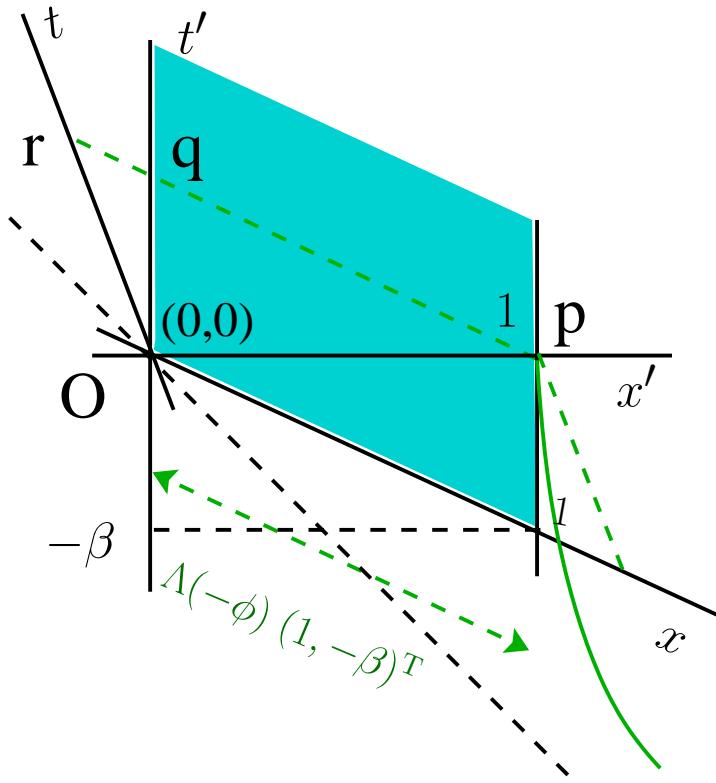
$$\Lambda^{-1} \begin{pmatrix} 1 \\ -\beta \end{pmatrix} = \begin{pmatrix} \cosh \phi (1 - \beta^2) \\ \cosh \phi (\tanh \phi - \tanh \phi) \end{pmatrix}$$

SR: worldsheet space contraction



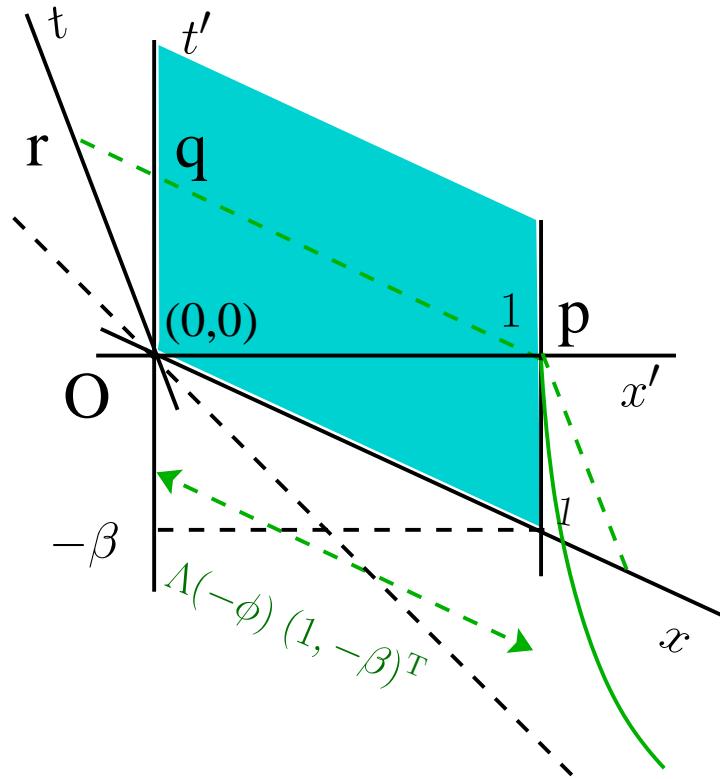
$$\Lambda^{-1} \begin{pmatrix} 1 \\ -\beta \end{pmatrix} = \begin{pmatrix} \gamma(1 - \beta^2) \\ 0 \end{pmatrix}$$

SR: worldsheet space contraction



$$\Lambda^{-1} \begin{pmatrix} 1 \\ -\beta \end{pmatrix} = \begin{pmatrix} \gamma^{-1} \\ 0 \end{pmatrix}$$

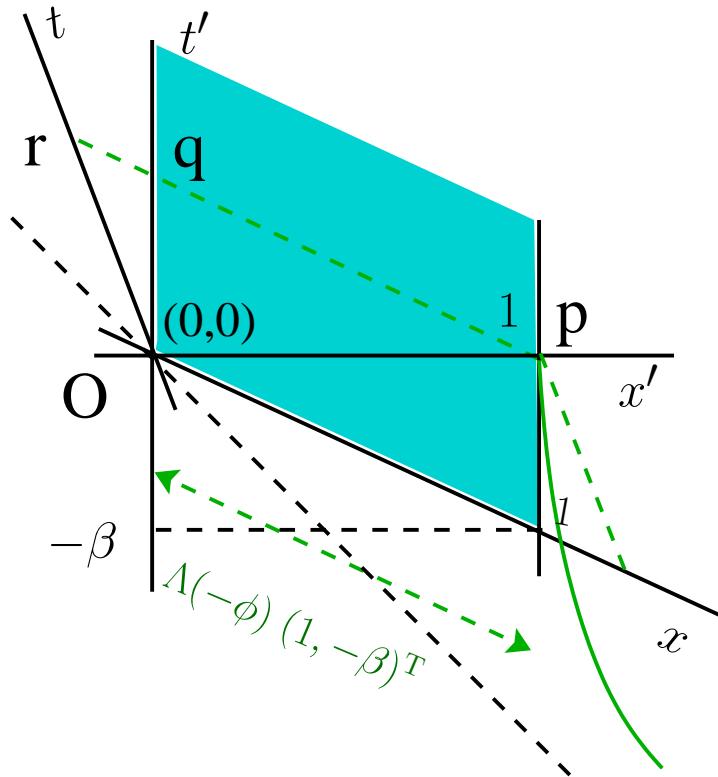
SR: worldsheet space contraction



$$\sqrt{\Delta s^2(q, p)} = \gamma^{-1} < 1$$



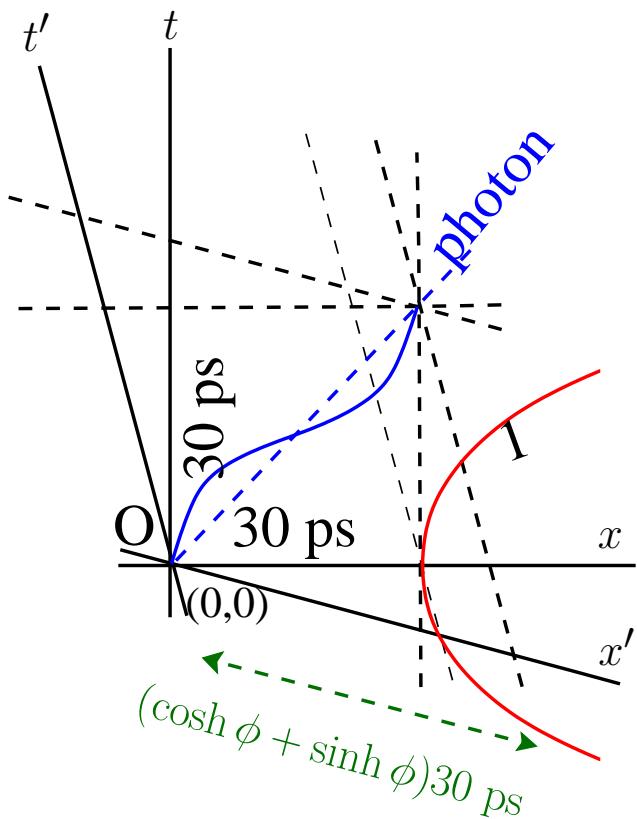
SR: worldsheet space contraction



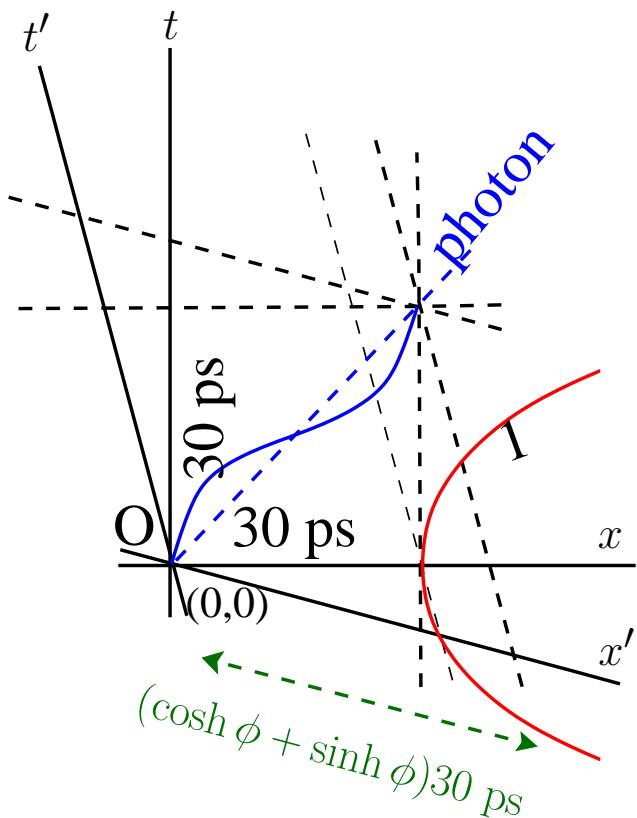
$$\sqrt{\Delta s^2(q, p)} = \gamma^{-1} < 1 \quad \text{worldsheet "space contraction"}$$



SR: Doppler shift

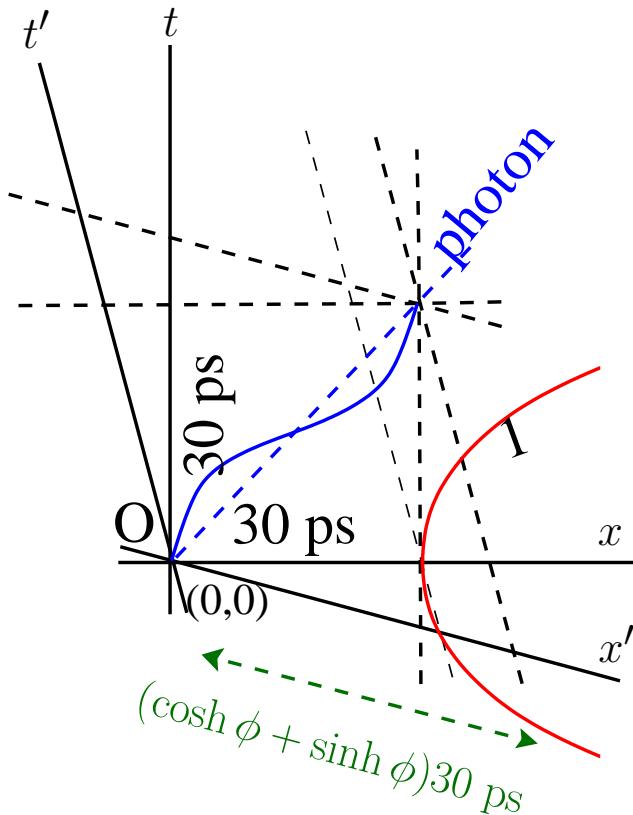


SR: Doppler shift



see photon worldline calculation

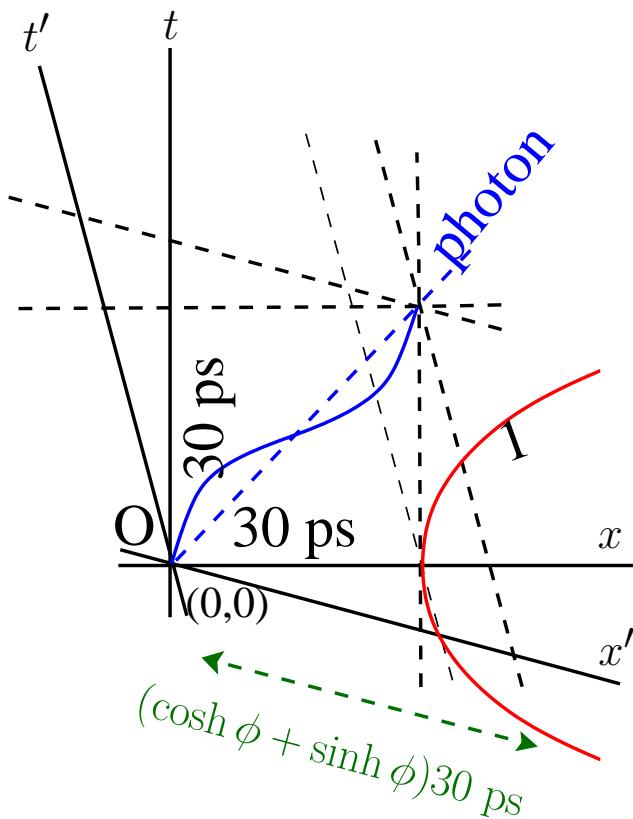
SR: Doppler shift



see photon worldline calculation

$$x' = (\cosh \phi + \sinh \phi)t$$

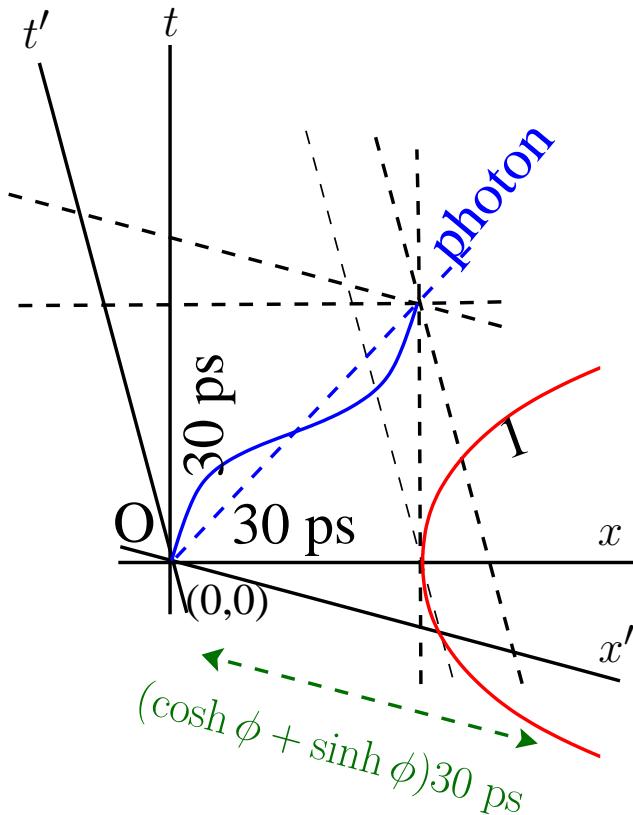
SR: Doppler shift



see photon worldline calculation

$$x' = (\cosh \phi + \sinh \phi)x$$

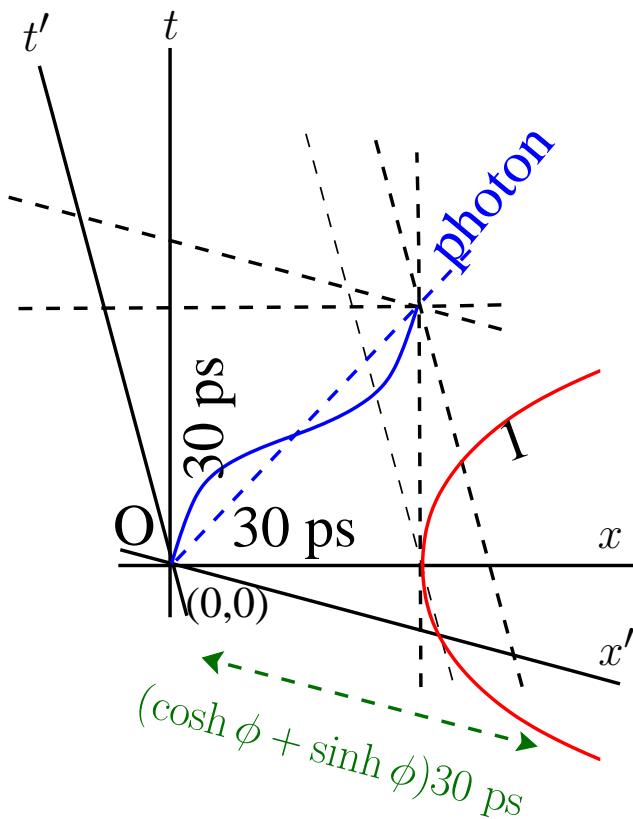
SR: Doppler shift



see photon worldline calculation

$$x'/x = \cosh \phi + \sinh \phi$$

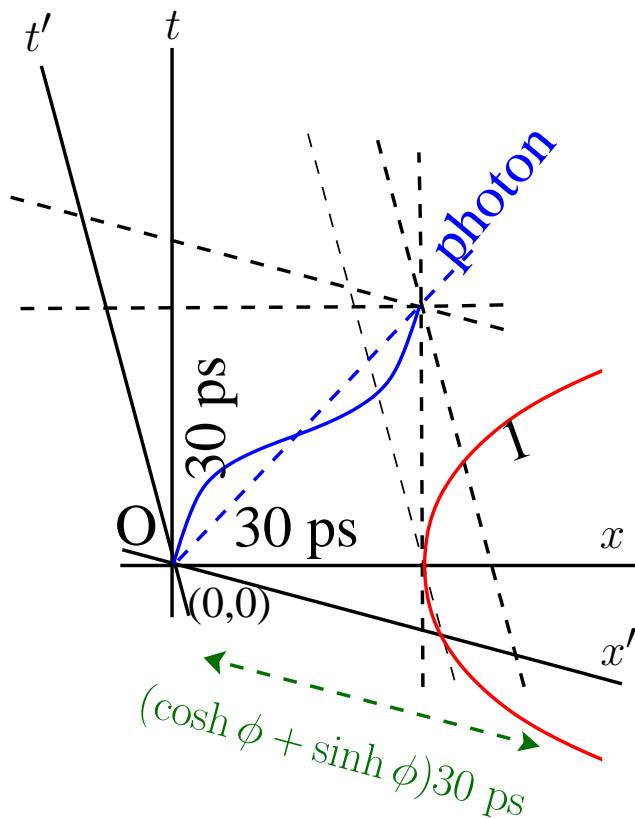
SR: Doppler shift



see photon worldline calculation

$$x'/x = \gamma + \beta\gamma$$

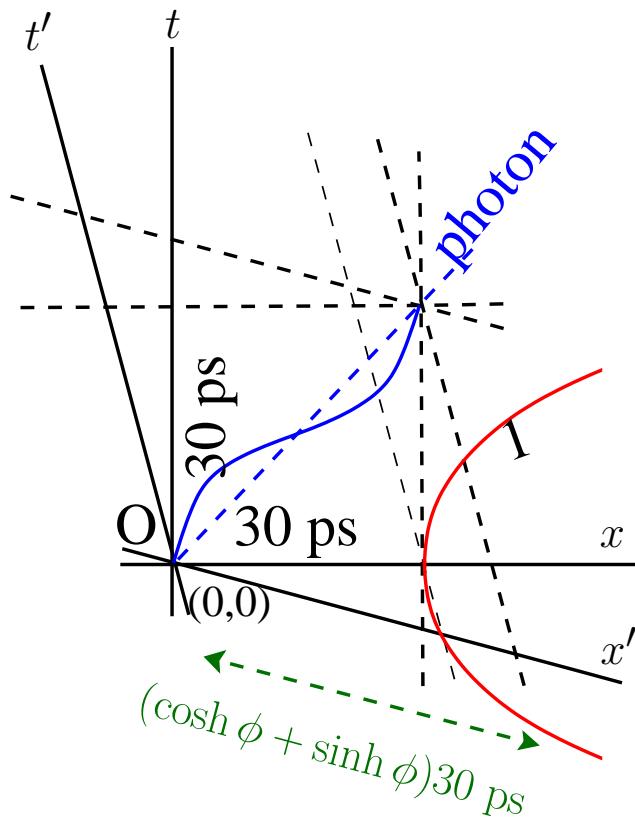
SR: Doppler shift



see photon worldline calculation

$$x'/x = \gamma(1 + \beta)$$

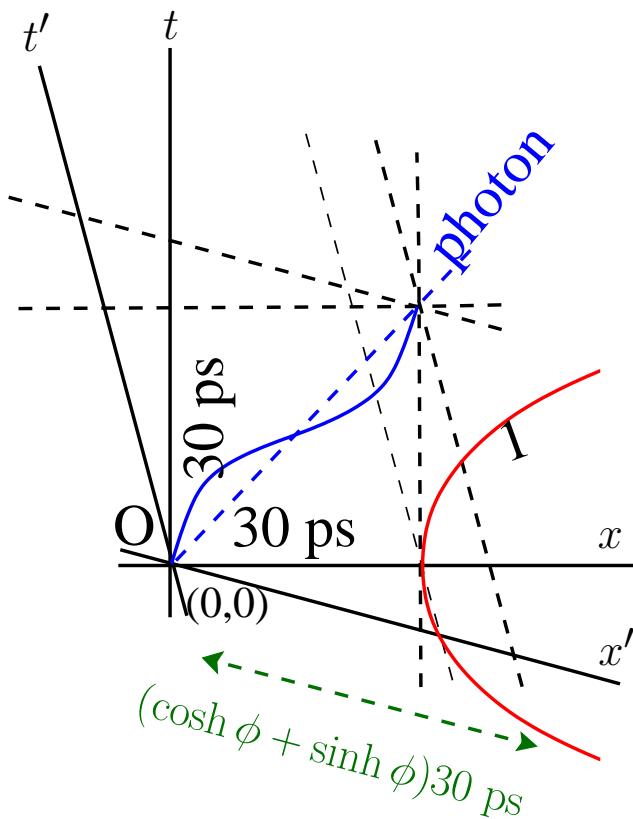
SR: Doppler shift



see photon worldline calculation

$$x'/x = \gamma(1 + \beta) = \frac{1+\beta}{\sqrt{1-\beta^2}}$$

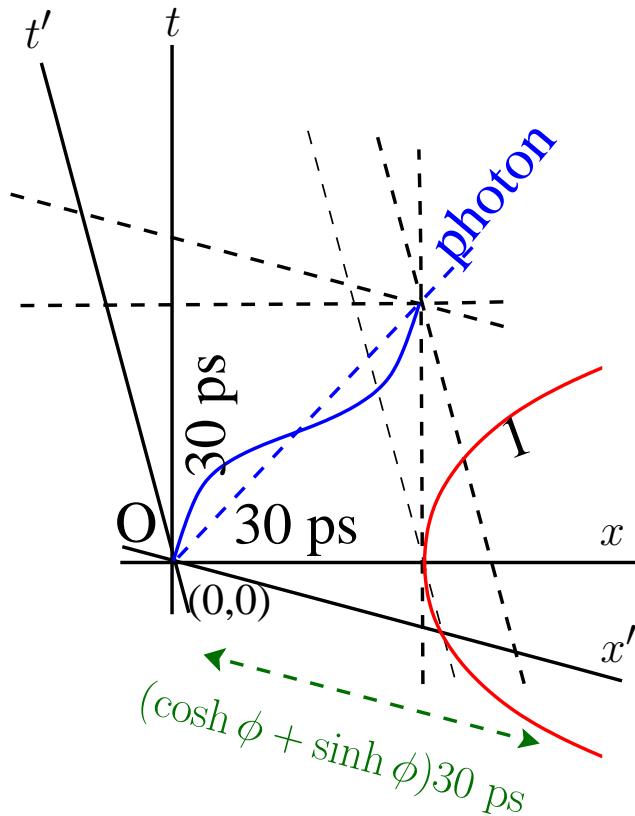
SR: Doppler shift



see photon worldline calculation

$$x'/x = \gamma(1 + \beta) = \frac{\sqrt{(1+\beta)^2}}{\sqrt{(1-\beta)(1+\beta)}}$$

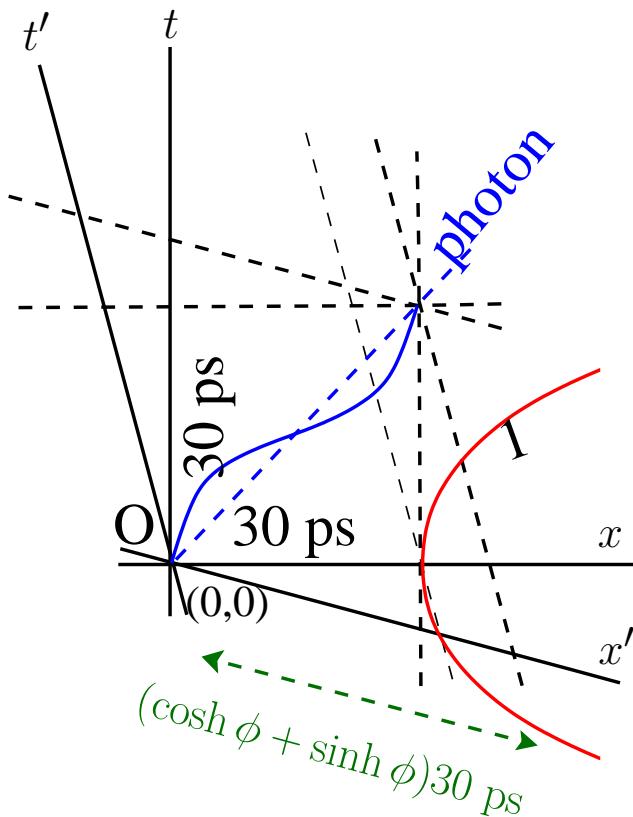
SR: Doppler shift



see photon worldline calculation

$$x'/x = \gamma(1 + \beta) = \sqrt{\frac{1+\beta}{1-\beta}}$$

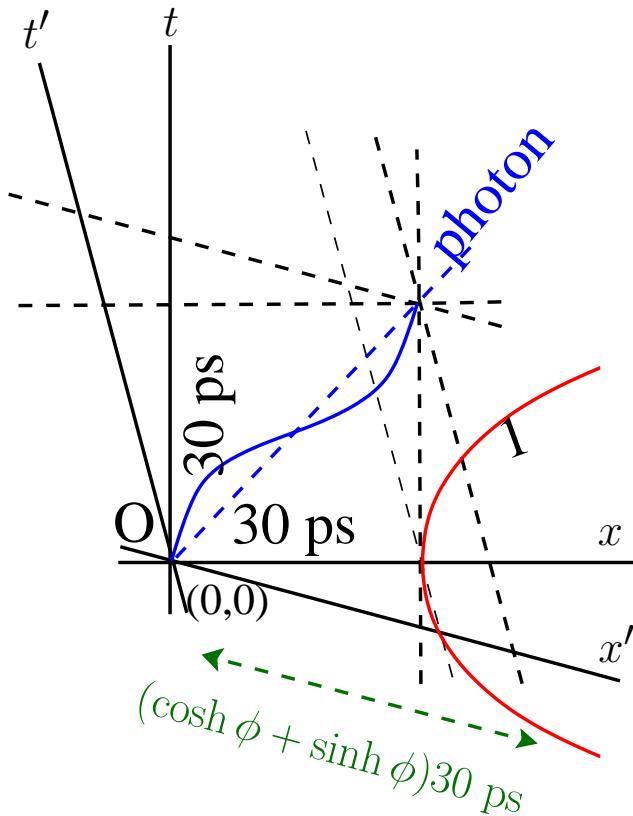
SR: Doppler shift



see photon worldline calculation

$$1 + z := \lambda'/\lambda = \gamma(1 + \beta) \equiv \sqrt{\frac{1+\beta}{1-\beta}}$$
redshift

SR: Doppler shift



see photon worldline calculation

$$1 + z := \lambda'/\lambda = \gamma(1 + \beta) \equiv \sqrt{\frac{1+\beta}{1-\beta}}$$

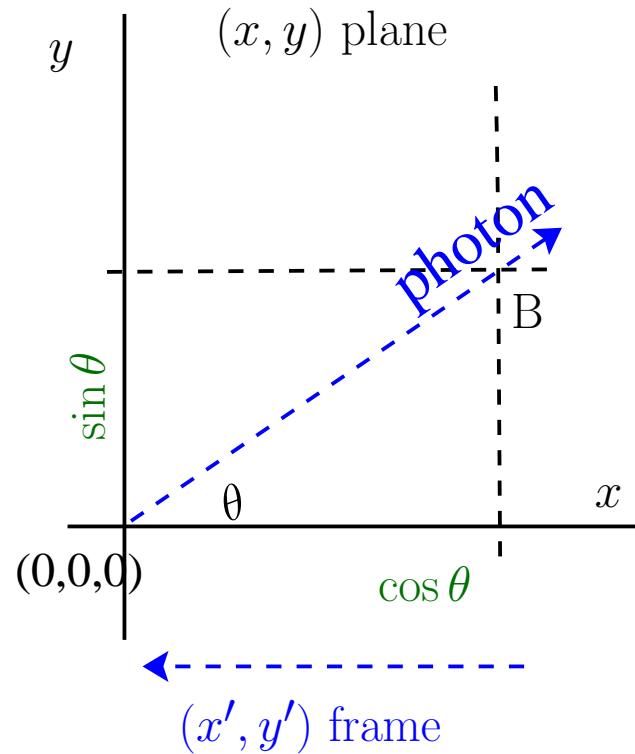
redshift

$$\Rightarrow \text{when } \beta \ll 1, z \approx \beta$$



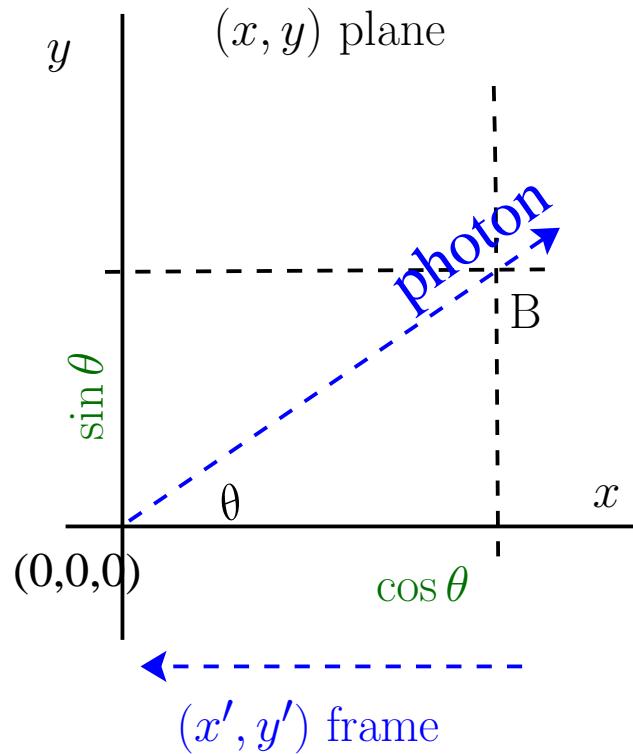


SR: relativistic aberration





SR: relativistic aberration



event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$





SR: relativistic aberration

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SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$

$$\Lambda^{-1} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 1 \end{pmatrix}$$





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$

$$\Lambda^{-1} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 1 \end{pmatrix} = \begin{pmatrix} \gamma & 0 & \beta\gamma \\ 0 & 1 & 0 \\ \beta\gamma & 0 & \gamma \end{pmatrix} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 1 \end{pmatrix}$$





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$

$$\Lambda^{-1} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 1 \end{pmatrix} = \begin{pmatrix} \gamma \cos \theta + \beta \gamma \\ \sin \theta \\ \beta \gamma \cos \theta + \gamma \end{pmatrix}$$





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$

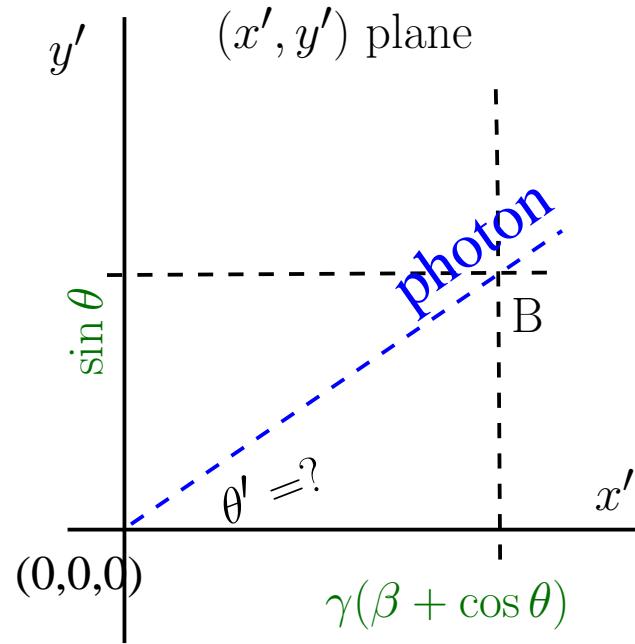
$$\Lambda^{-1} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 1 \end{pmatrix} = \begin{pmatrix} \gamma(\cos \theta + \beta) \\ \sin \theta \\ \gamma(1 + \beta \cos \theta) \end{pmatrix}$$





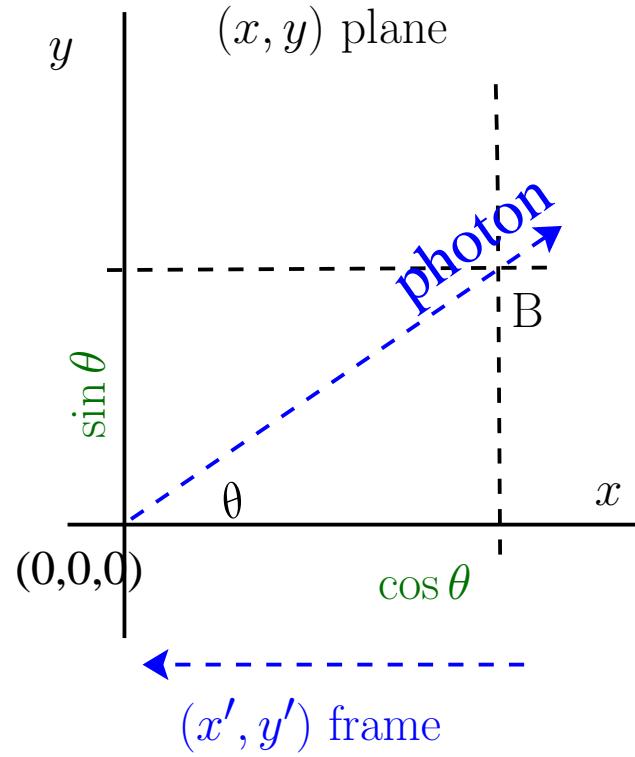
SR: relativistic aberration

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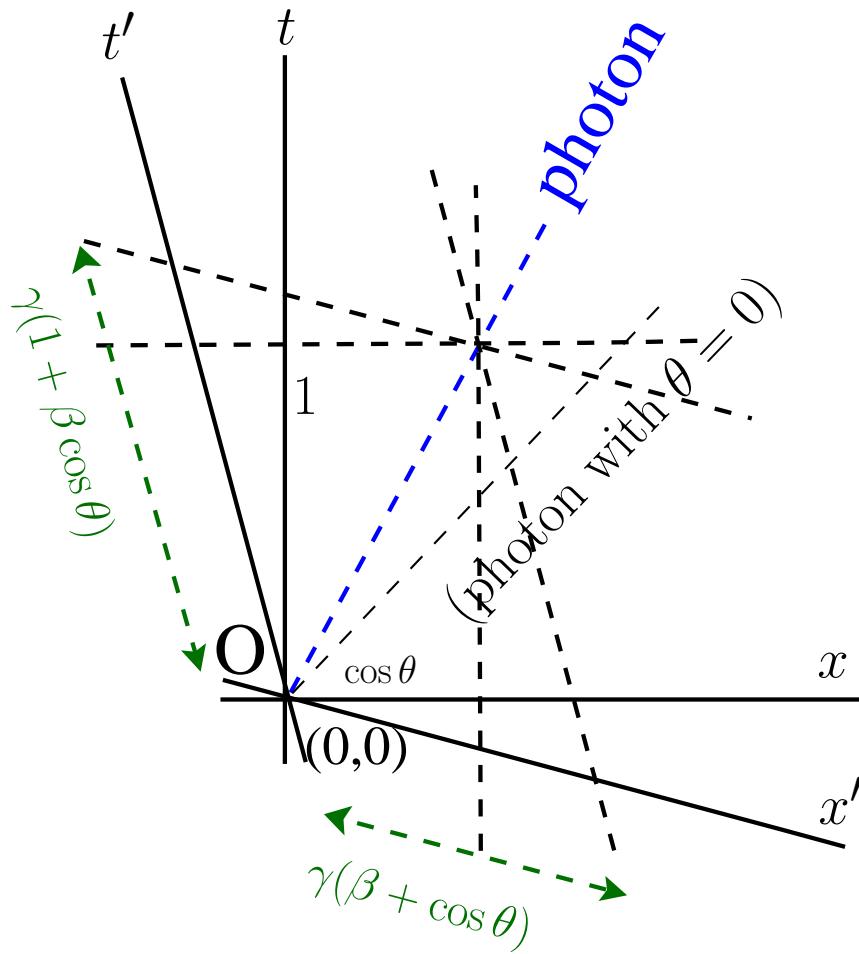
SR: relativistic aberration

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SR: relativistic aberration

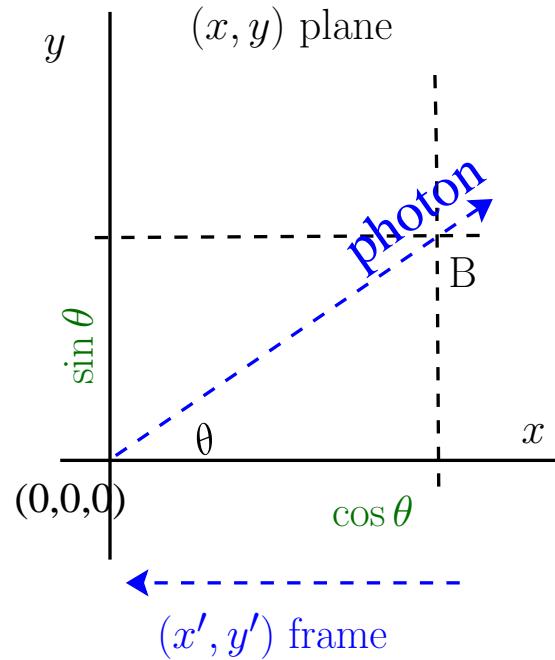
event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$



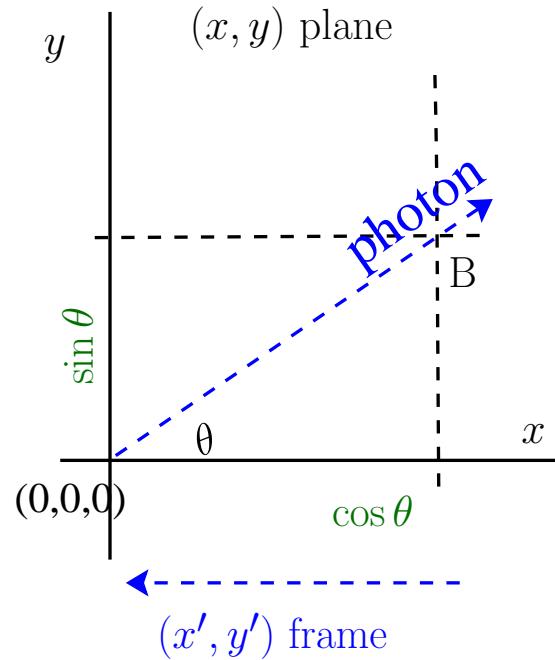
$$\tan \theta' = \frac{\sin \theta}{\gamma(\beta + \cos \theta)}$$





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$



$$\tan \theta' = \frac{\sin \theta}{\gamma(\beta + \cos \theta)} < \tan \theta \text{ if } 0 < \beta < 1$$

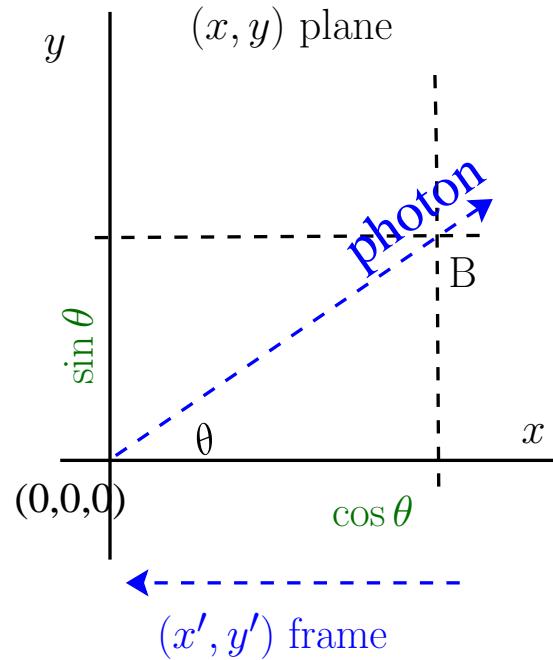
w:Relativistic aberration





SR: relativistic aberration

event B: $(x, y, t) = (\cos \theta, \sin \theta, 1)$



$$\tan \theta' = \frac{\sin \theta}{\gamma(\beta + \cos \theta)} < \tan \theta \text{ if } 0 < \beta < 1$$

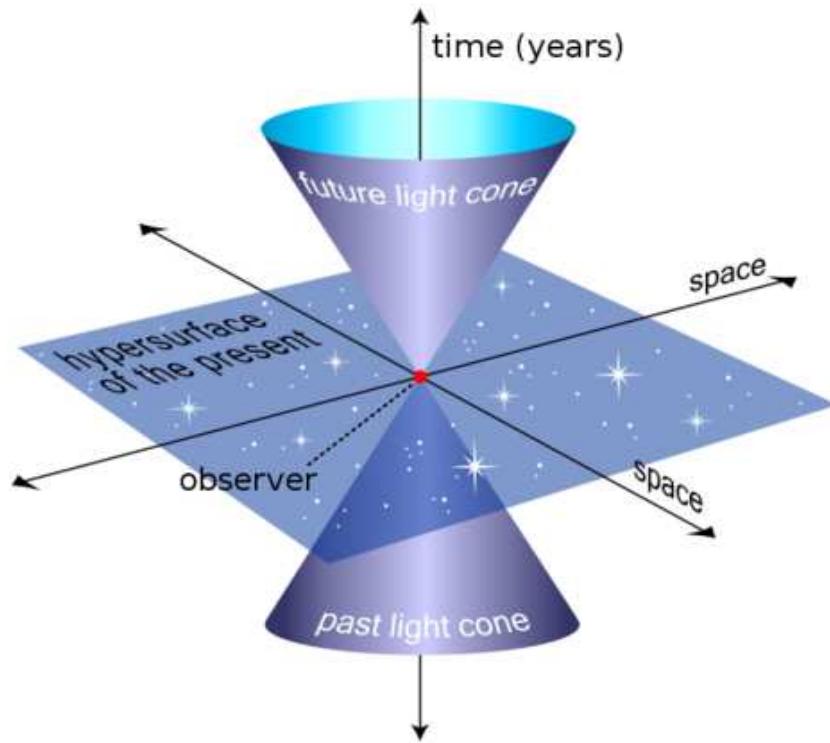
w:Relativistic aberration

⇒ relativistic beaming, e.g. AGN jets

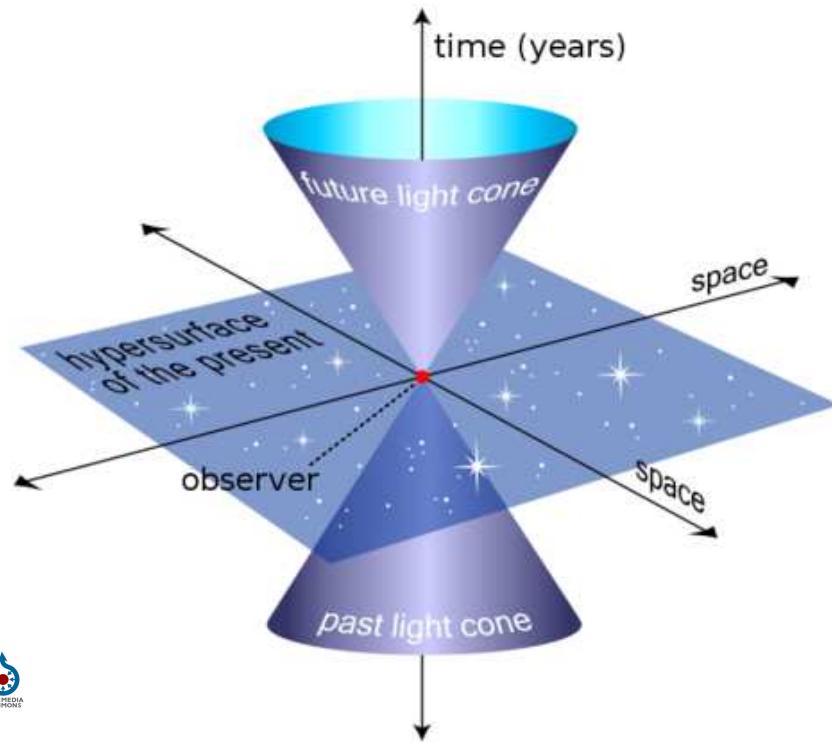




SR: world line



SR: world line

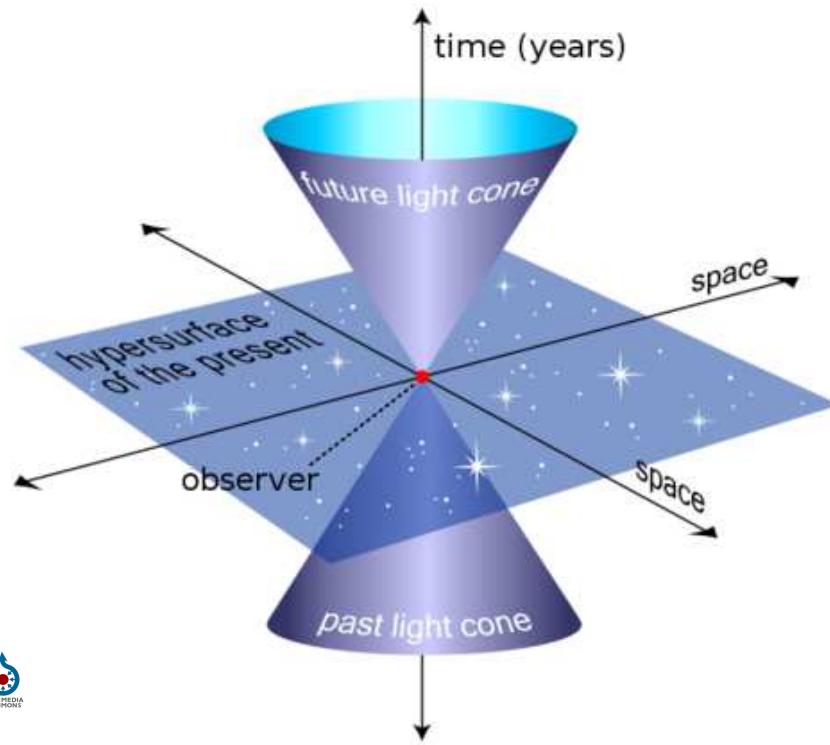


lightlike interval = null interval: $(\Delta s)^2 = 0$

spacetime =



SR: world line



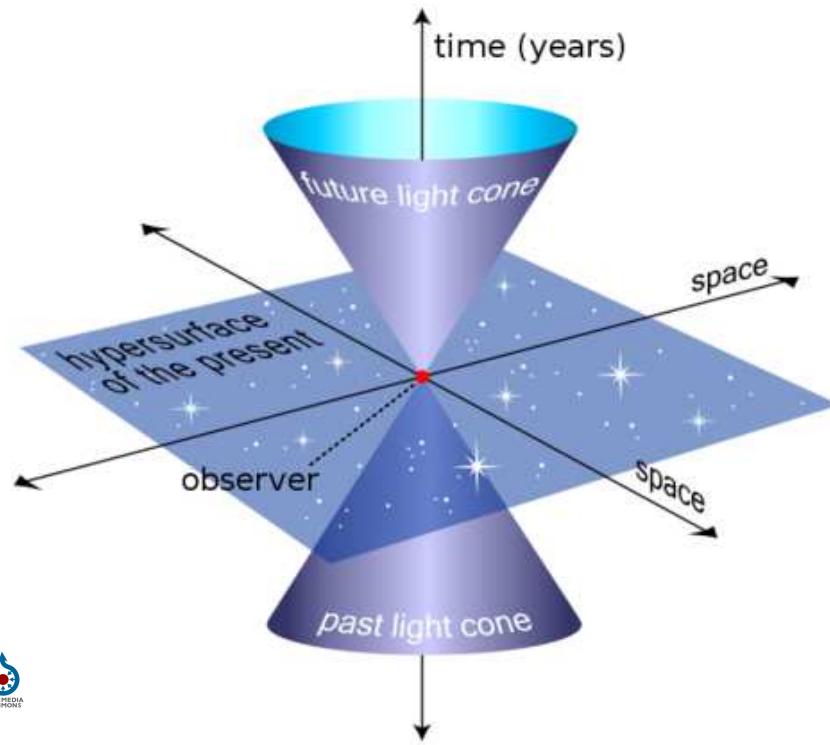
lightlike interval = null interval: $(\Delta s)^2 = 0$

spacetime = on past w:**light cone** + inside past light cone





SR: world line



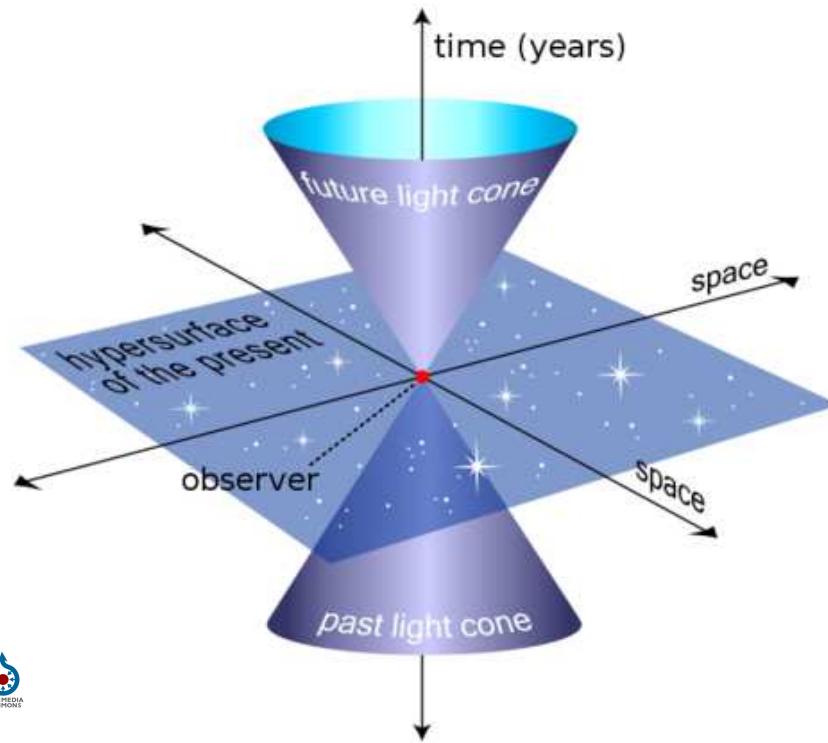
lightlike interval = null interval: $(\Delta s)^2 = 0$

spacetime = on past w:light cone + inside past light cone
+ on future light cone + inside future light cone





SR: world line



lightlike interval = null interval: $(\Delta s)^2 = 0$

spacetime = on past w:light cone + inside past light cone
+ on future light cone + inside future light cone
+ elsewhere





SR: world line

Lorentz transform of world line





SR: world line

Lorentz transform of world line





SR: world line

Lorentz transform of world line



- coordinate time in spacetime model \neq time in your brain (thinking)





SR: world line

Lorentz transform of world line



- coordinate time in spacetime model \neq time in your brain (thinking)
- $\frac{dt}{dt_{\text{thinking}}}$ can be positive or negative





SR: world line

Lorentz transform of world line



- coordinate time in spacetime model \neq time in your brain (thinking)
- $\frac{dt}{d\lambda}$ can be positive or negative, λ arbitrary real parameter





SR: world line

Lorentz transform of world line



- coordinate time in spacetime model \neq time in your brain (thinking)
- $\frac{dt}{d\lambda}$ can be positive or negative, λ arbitrary real parameter
- “elsewhere” spacetime events can change from past to future even though $\frac{dt}{d\lambda} > 0$





SR: world line

Lorentz transform of world line



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- w:proper time $\tau :=$ time along a worldline measured by clock following that worldline





SR: world line

Lorentz transform of world line

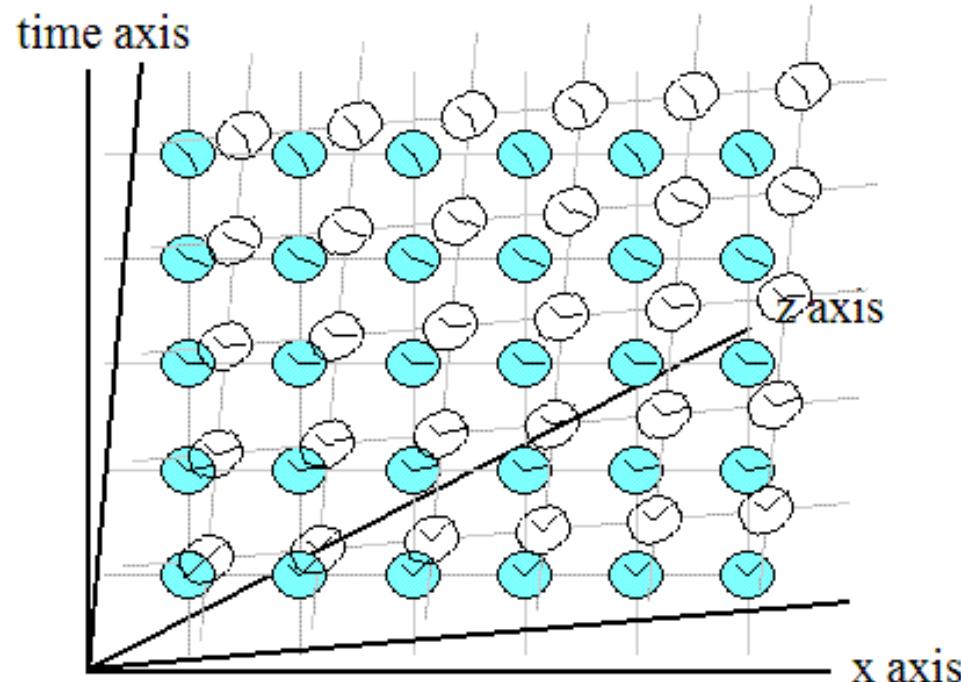


- coordinate time in spacetime model \neq time in your brain (thinking)
- $\frac{dt}{d\lambda}$ can be positive or negative, λ arbitrary real parameter
- “elsewhere” spacetime events can change from past to future even though $\frac{dt}{d\lambda} > 0$
- w:proper time $\tau :=$ time along a worldline measured by clock following that worldline
- often $d\tau$ is useful for integrating





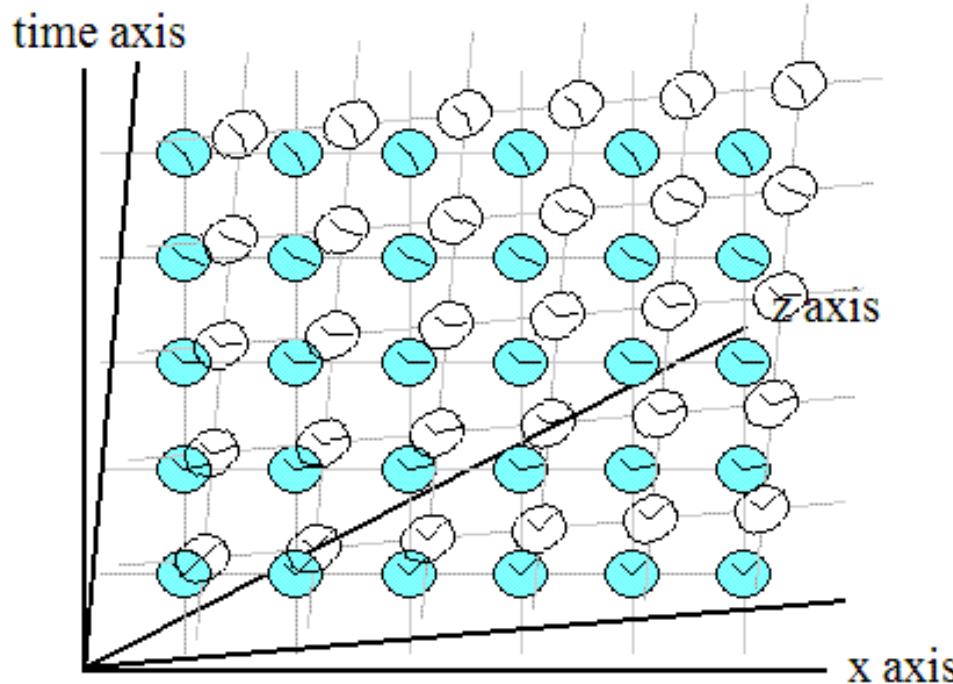
SR: Rietdijk–Putnam–Penrose p.



Relativity shows that the inertial frames of reference of relatively moving objects do not overlap each other.



SR: Rietdijk–Putnam–Penrose p.



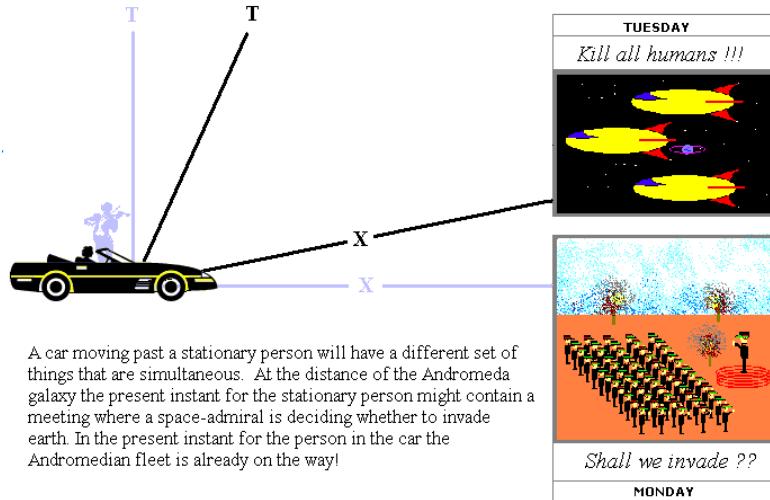
Relativity shows that the inertial frames of reference of relatively moving objects do not overlap each other.

b:Inertialoverlay.GIF

- each observer can synchronise clocks + rods

SR: Rietdijk–Putnam–Penrose p.

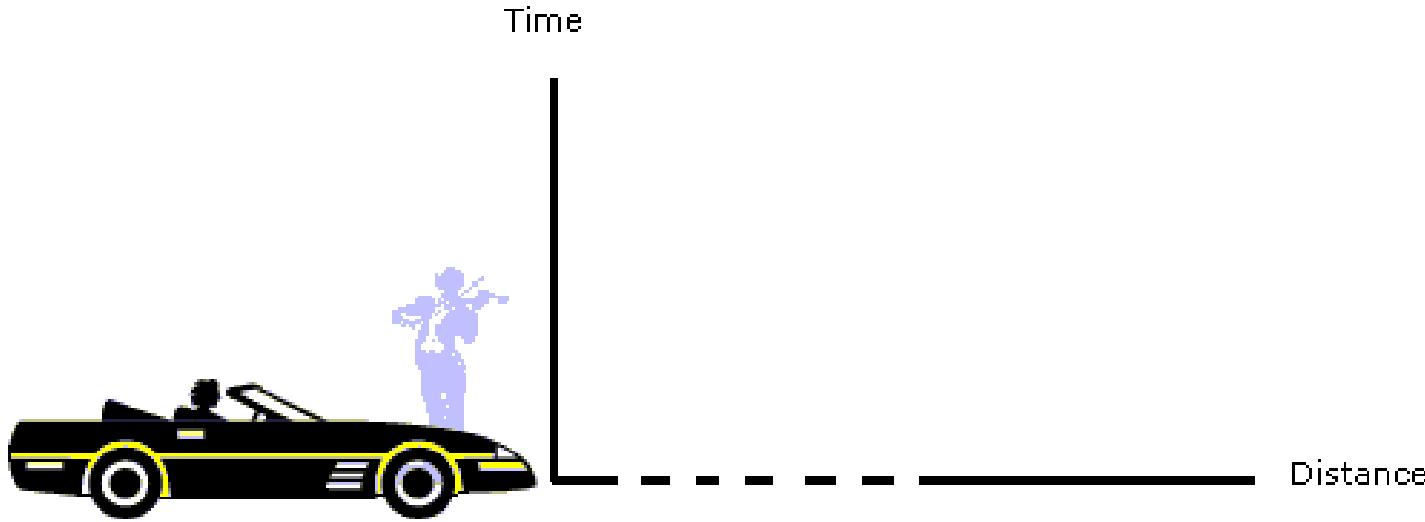
The Andromeda Paradox



w:Rietdijk-Putnam argument b:Rel2.gif



SR: Rietdijk–Putnam–Penrose p.

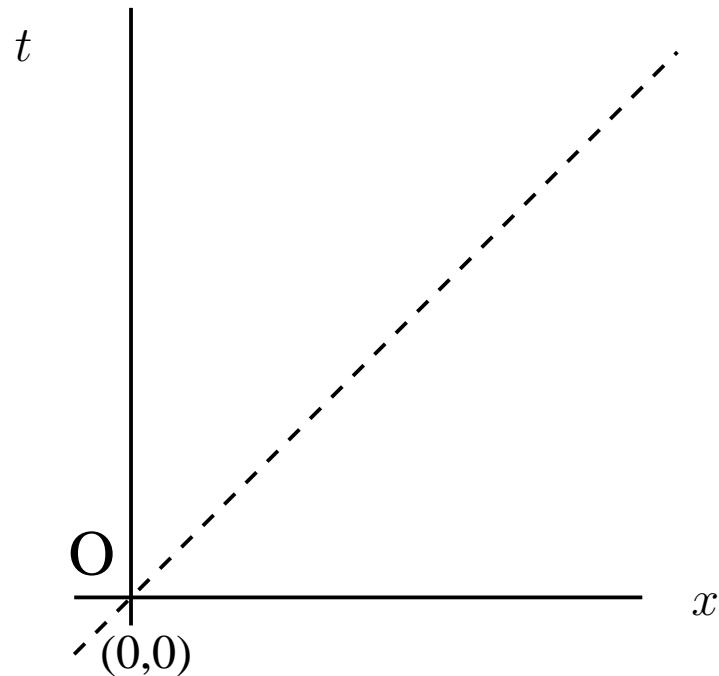


[w:Rietdijk–Putnam argument](#) [b:Rel3.gif](#)





SR: tachyons and causality

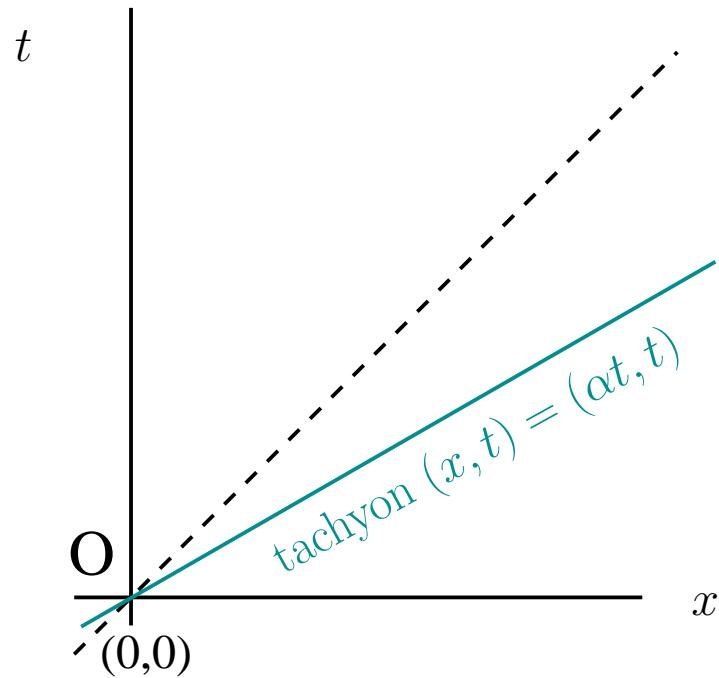


observer “at rest”





SR: tachyons and causality

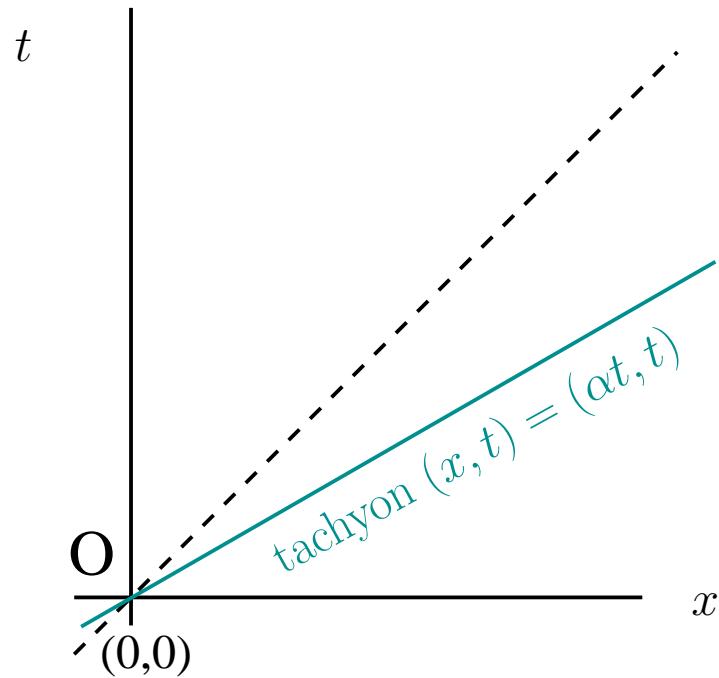


add a tachyon with speed $\alpha > 1$





SR: tachyons and causality



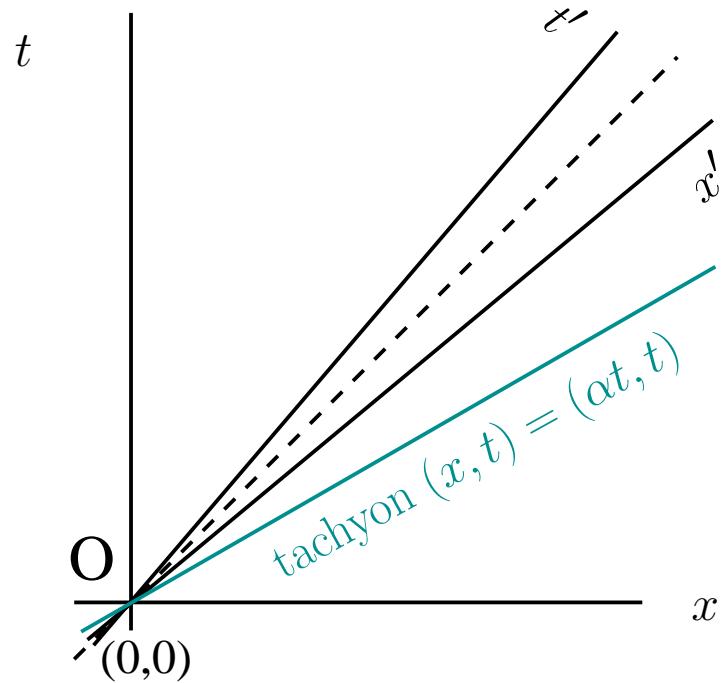
add a tachyon with speed $\alpha > 1$

choose rocket at speed β with $1/\alpha < \beta < 1$





SR: tachyons and causality



add a tachyon with speed $\alpha > 1$

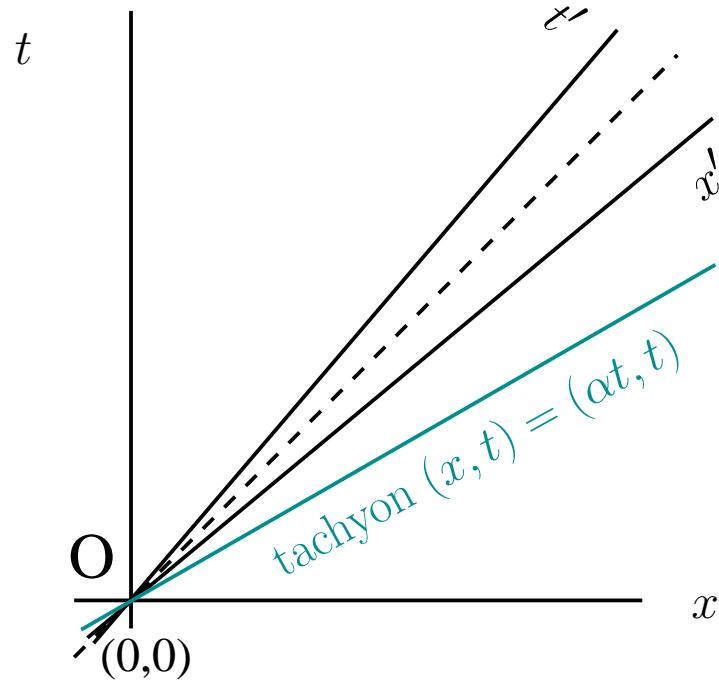
choose rocket at speed β with $1/\alpha < \beta < 1$

add axes x', t' for the rocket





SR: tachyons and causality



add a tachyon with speed $\alpha > 1$

choose rocket at speed β with $1/\alpha < \beta < 1$

add axes x', t' for the rocket

rocket frame: $(\alpha t, t)$ becomes Λ $(\alpha t, t)^T$





SR: tachyons and causality

$$\begin{pmatrix} x' \\ t' \end{pmatrix} = \Lambda \begin{pmatrix} \alpha t \\ t \end{pmatrix} =$$





SR: tachyons and causality

$$\begin{pmatrix} x' \\ t' \end{pmatrix} = \Lambda \begin{pmatrix} \alpha t \\ t \end{pmatrix} = \begin{pmatrix} \gamma\alpha t - \beta\gamma t \\ -\alpha\beta\gamma t + \gamma t \end{pmatrix}$$





SR: tachyons and causality

$$\begin{pmatrix} x' \\ t' \end{pmatrix} = \Lambda \begin{pmatrix} \alpha t \\ t \end{pmatrix} = \gamma t \begin{pmatrix} \alpha - \beta \\ -\alpha\beta + 1 \end{pmatrix}$$





SR: tachyons and causality

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$x' = \gamma t(\alpha - \beta) > 0$ since $\alpha > 1 > \beta$





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$dt'/dt < 0$

same sequence of spacetime events = tachyon worldline:

t increases for observer “at rest”,

t' decreases for rocket observer (with $\beta > 1/\alpha$)





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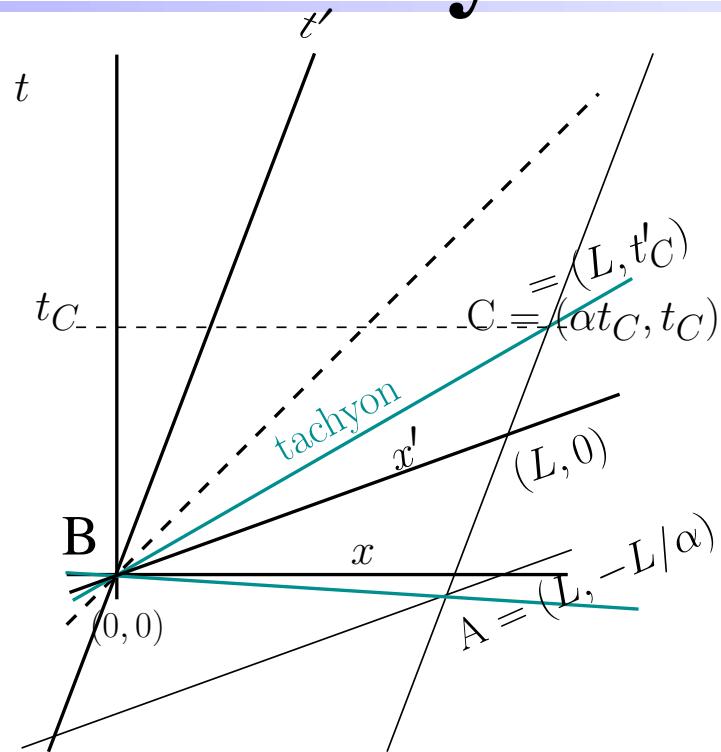
t' decreases for rocket observer (with $\beta > 1/\alpha$)

- observer at rest: tachyon emitted at origin
- rocket: tachyon absorbed at origin



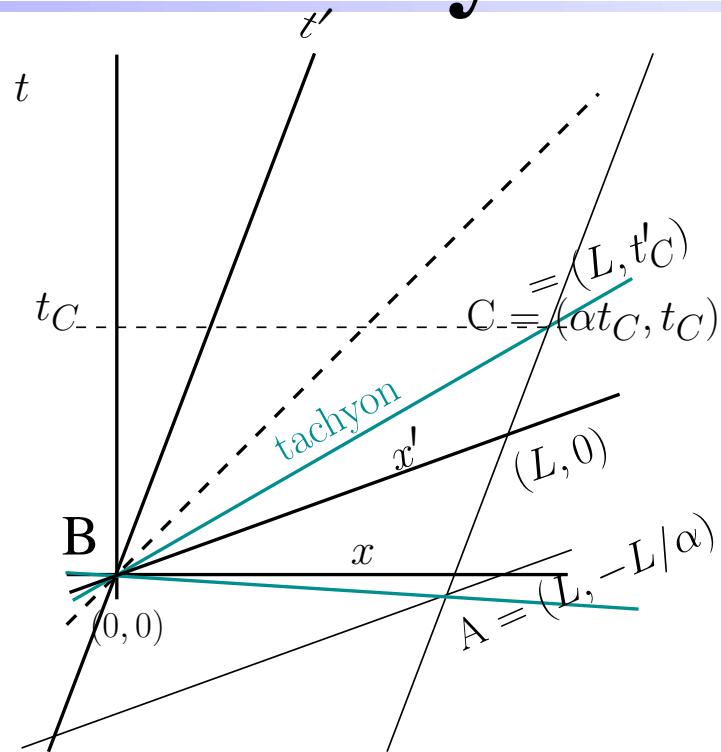


SR: tachyonic antitelephone





SR: tachyonic antitelephone

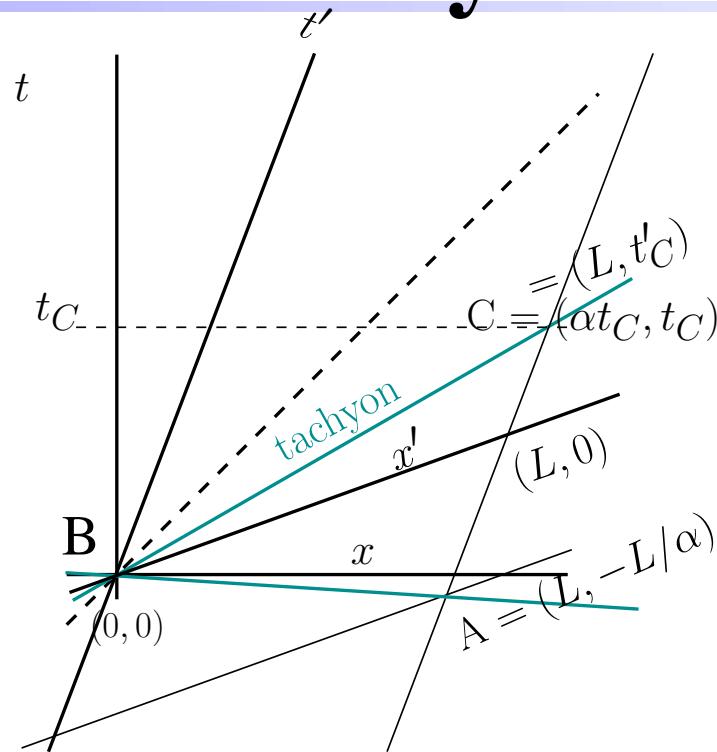


B stationary: (x, t)
frame





SR: tachyonic antitelephone



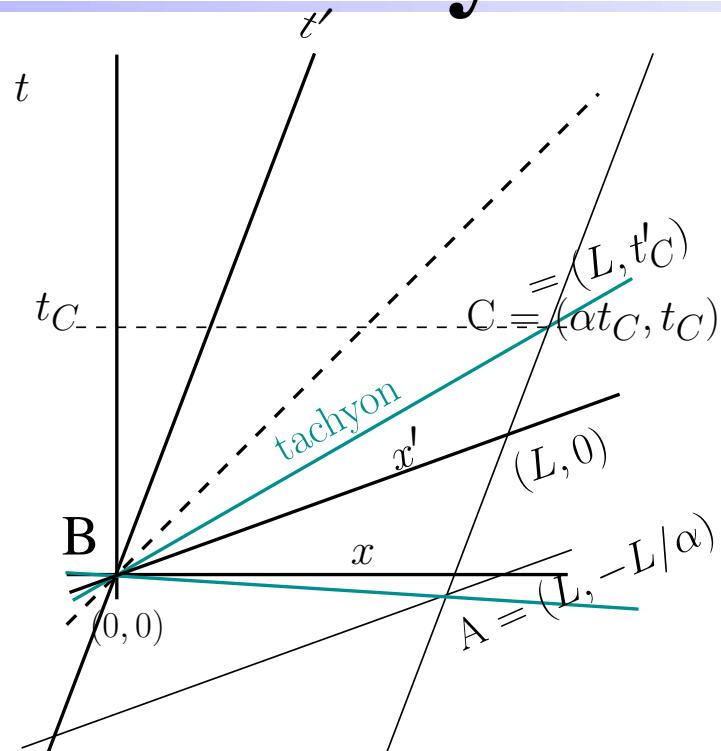
B stationary: (x, t)
frame

A moving at speed β :
 (x', t') frame





SR: tachyonic antitelephone



A: tachyon at $\alpha > 1$ to B

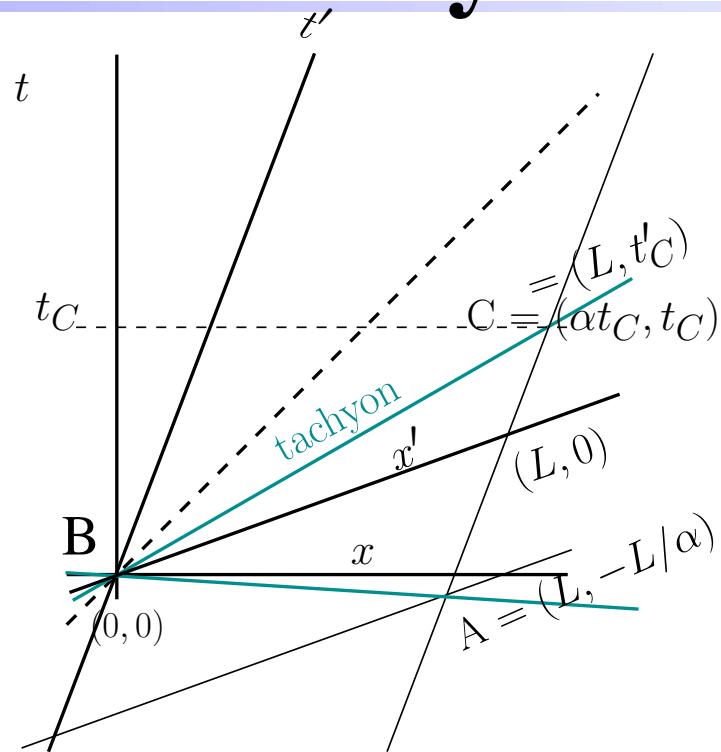
B stationary: (x, t)
frame

A moving at speed β :
 (x', t') frame





SR: tachyonic antitelephone



B: tachyon at $\alpha > 1$ to C

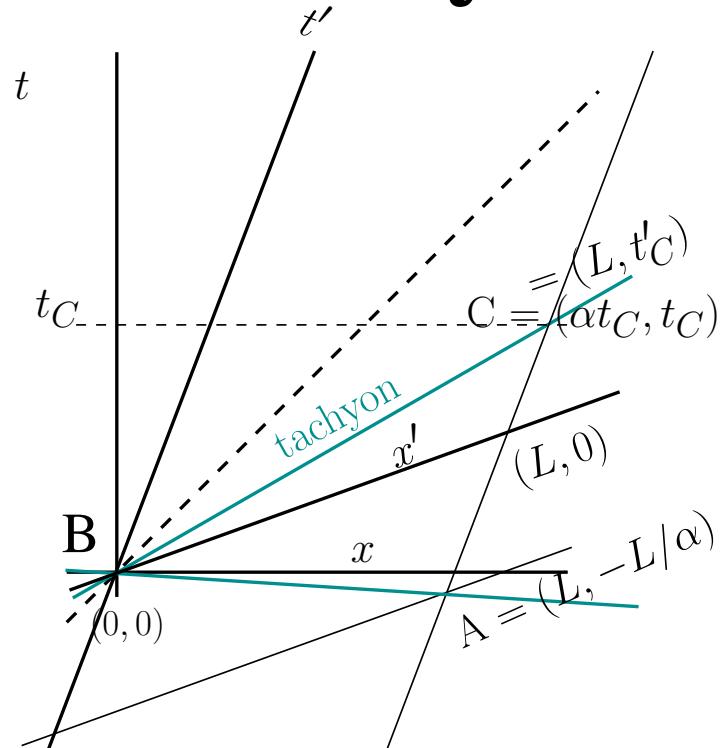
B stationary: (x, t)
frame

A moving at speed β :
 (x', t') frame





SR: tachyonic antitelephone



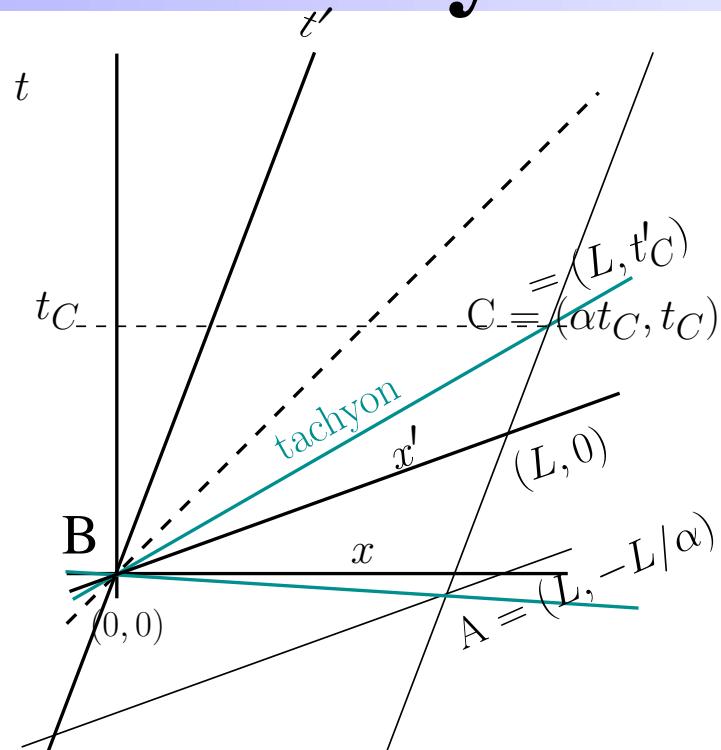
$$C: \begin{pmatrix} L \\ t'_C \end{pmatrix} = \Lambda \begin{pmatrix} \alpha t_C \\ t_C \end{pmatrix}$$

B stationary: (x, t)
frame
A moving at speed β :
 (x', t') frame





SR: tachyonic antitelephone



$$\begin{pmatrix} L \\ t'_C \end{pmatrix} = \gamma t_C \begin{pmatrix} \alpha - \beta \\ -\alpha\beta + 1 \end{pmatrix}$$

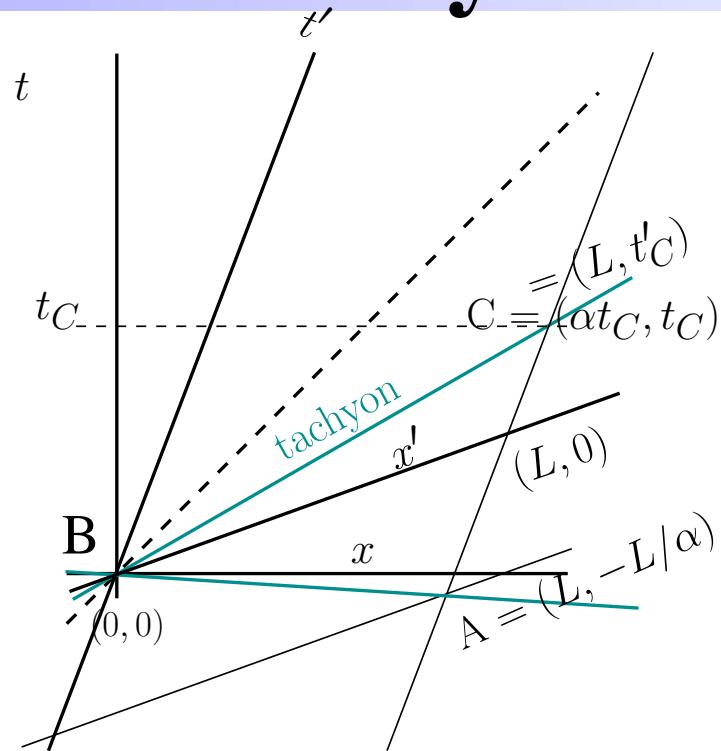
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SR: tachyonic antitelephone



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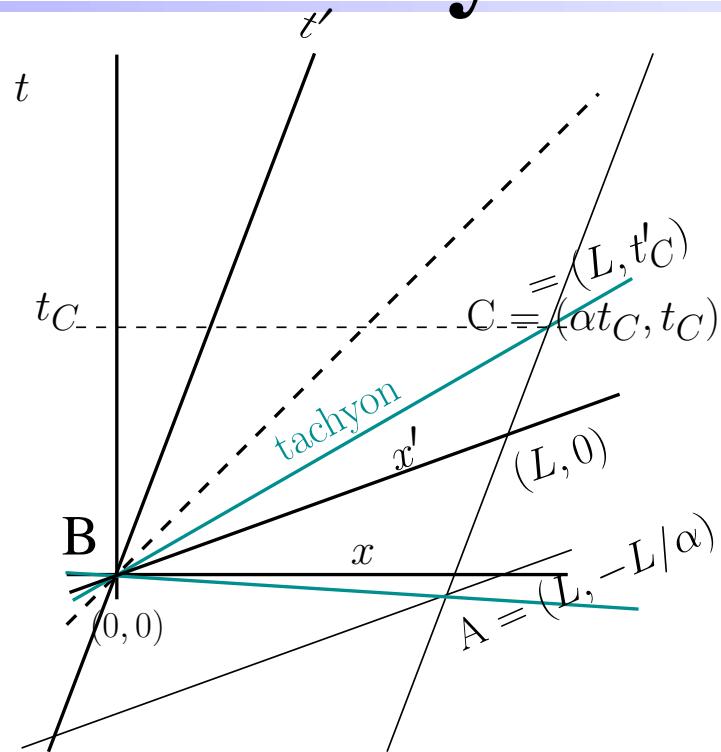
$$t'_C = \gamma t_C (1 - \alpha\beta)$$

B stationary: (x, t)
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 A moving at speed β :
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SR: tachyonic antitelephone



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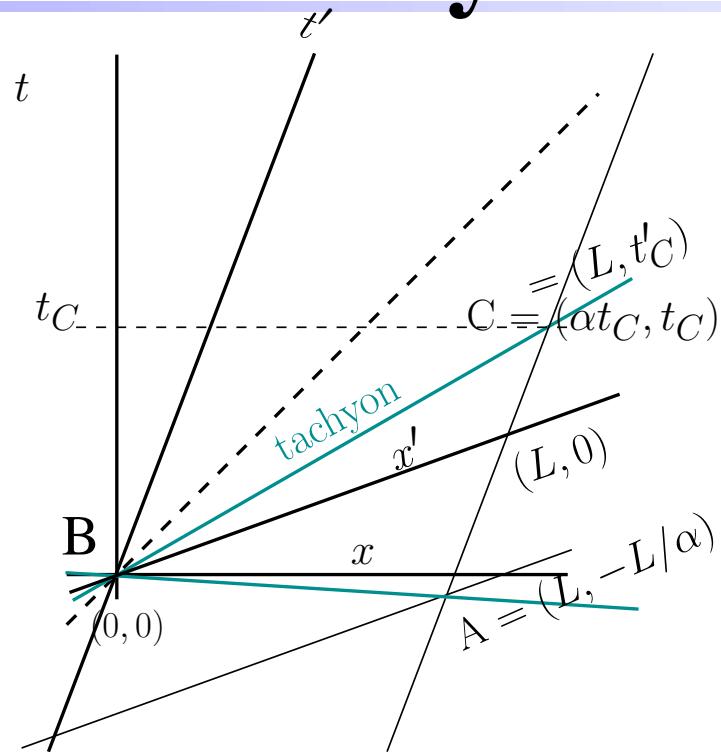
$$t'_C = \gamma \frac{L}{\gamma(\alpha-\beta)}(1 - \alpha\beta)$$

B stationary: (x, t)
 frame
 A moving at speed β :
 (x', t') frame





SR: tachyonic antitelephone



$$\begin{pmatrix} L \\ t'_C \end{pmatrix} = \gamma t_C \begin{pmatrix} \alpha - \beta \\ -\alpha\beta + 1 \end{pmatrix}$$

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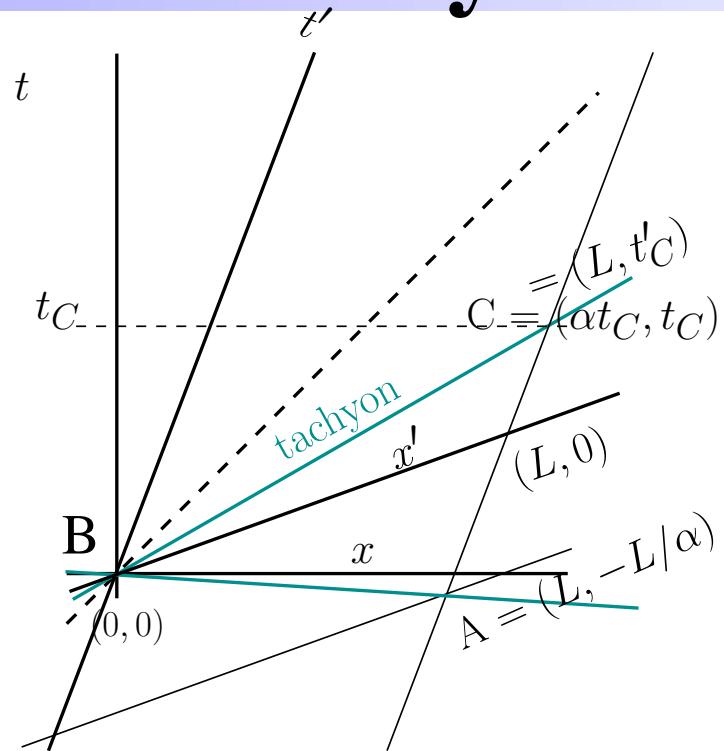
B stationary: (x, t)
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A moving at speed β :
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SR: tachyonic antitelephone



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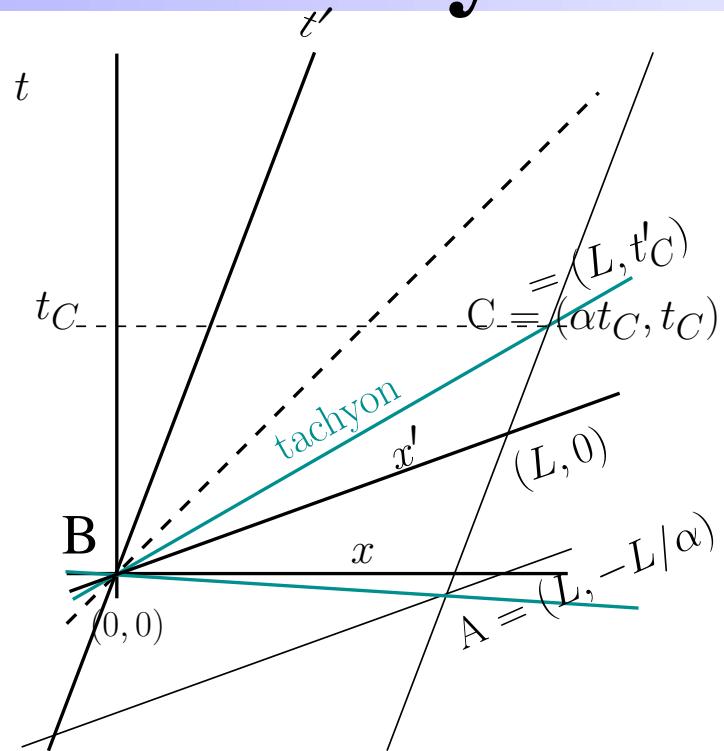
$$t'_C = L \frac{1 - \alpha\beta}{\alpha - \beta}$$

$$t'_C - t'_A = L \left(\frac{1 - \alpha\beta}{\alpha - \beta} + \frac{1}{\alpha} \right)$$





SR: tachyonic antitelephone



B stationary: (x, t)
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A moving at speed β :
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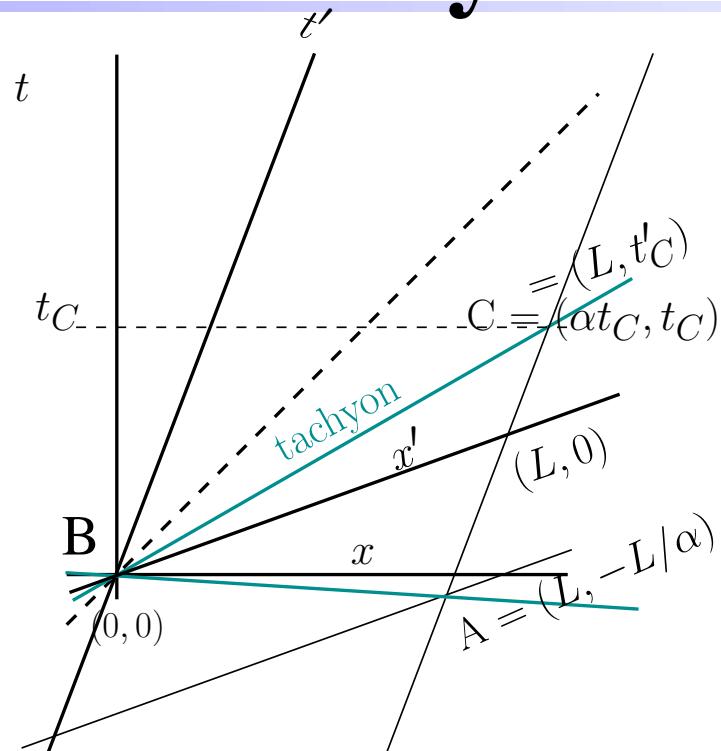
$$t'_C = L \frac{1 - \alpha\beta}{\alpha - \beta}$$

$$t'_C - t'_A = L \frac{\alpha - \alpha^2\beta + \alpha - \beta}{\alpha(\alpha - \beta)}$$





SR: tachyonic antitelephone



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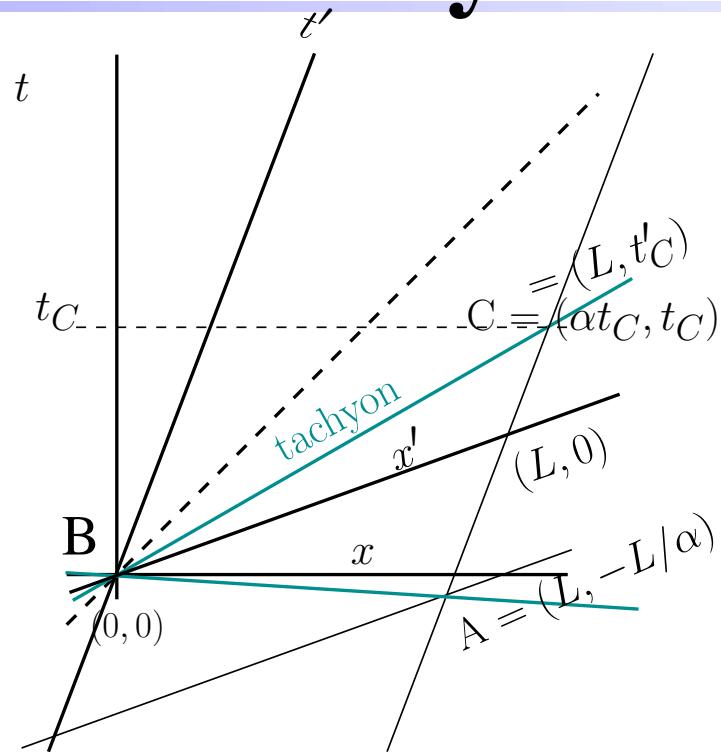
$$t'_C - t'_A = L \frac{2\alpha - (\alpha^2 + 1)\beta}{\alpha(\alpha - \beta)}$$

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A moving at speed β :
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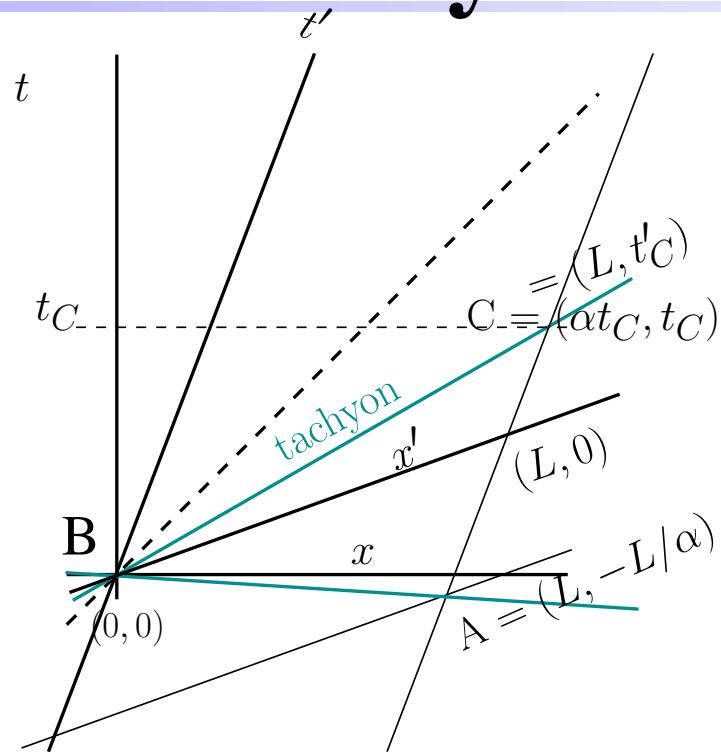
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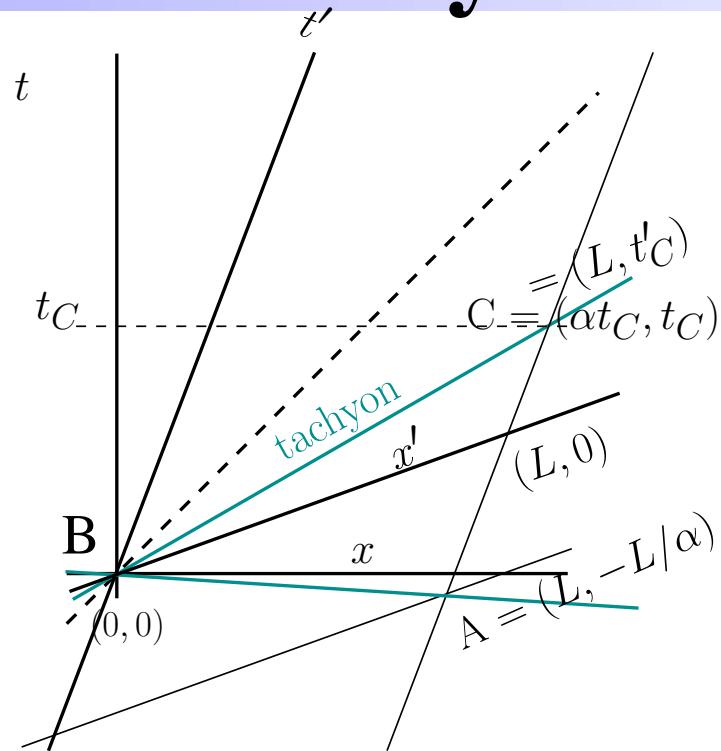
$$< 0 \text{ if } \beta > \frac{2\alpha}{\alpha^2 + 1}$$

A receives tachyonic response at C before sending it





SR: tachyonic antitelephone



B stationary: (x, t)
frame
A moving at speed β :
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$$\begin{pmatrix} L \\ t'_C \end{pmatrix} = \gamma t_C \begin{pmatrix} \alpha - \beta \\ -\alpha\beta + 1 \end{pmatrix}$$

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$$t'_C - t'_A = L \frac{2\alpha - (\alpha^2 + 1)\beta}{\alpha(\alpha - \beta)}$$

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A receives tachyonic response at C before sending it

w:tachyonic antitelephone



SR: pole-barn/ladder paradox





SR: pole-barn/ladder paradox



- ladder of length 29.9γ ns, garage length 30 ns





SR: pole-barn/ladder paradox



- ladder of length 29.9γ ns, garage length 30 ns
- instantaneously close front + back doors





SR: pole-barn/ladder paradox

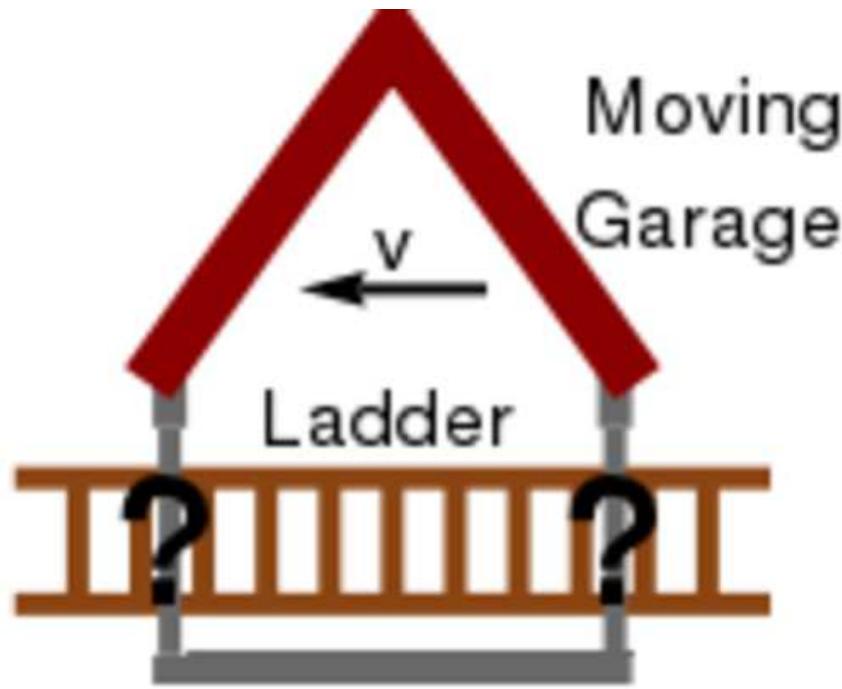


- ladder of length 29.9γ ns, garage length 30 ns
- instantaneously close front + back doors
- 29.9γ ns / $\gamma < 30$ ns \Rightarrow OK





SR: pole-barn/ladder paradox



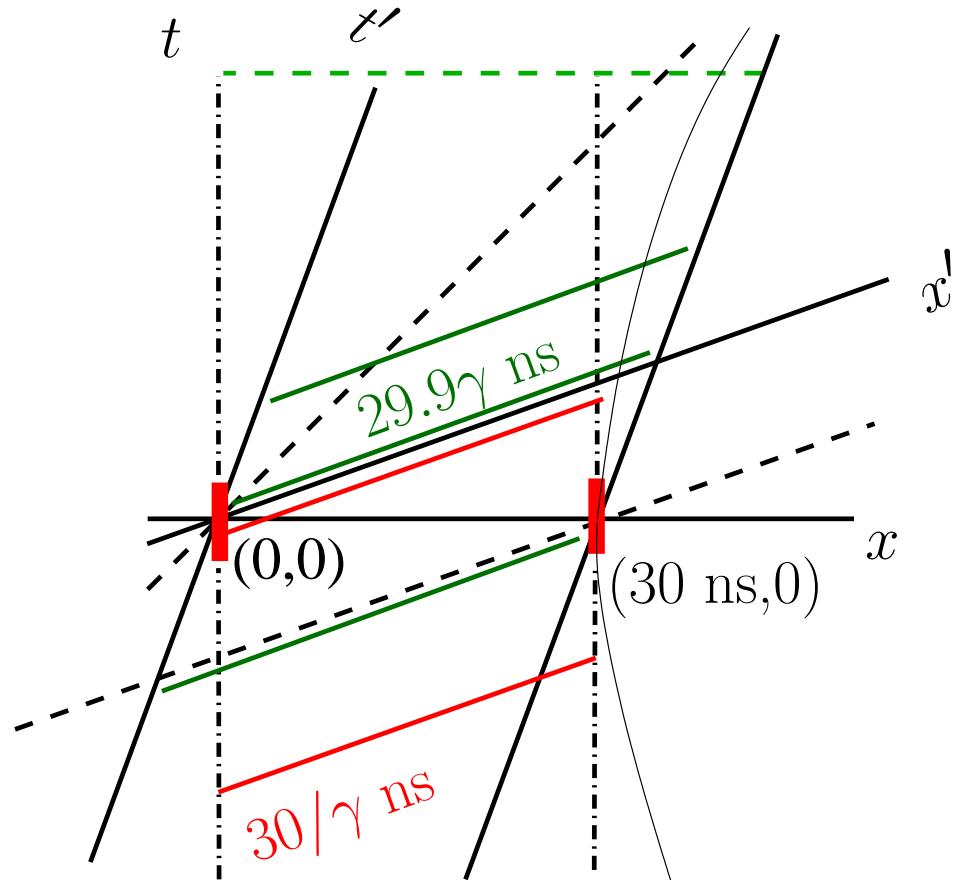
- ladder of length 29.9γ ns, garage length 30 ns
- instantaneously close front + back doors
- ladder frame: garage $30/\gamma$ ns long $\ll 29.9\gamma$ ns!!

Is this possible or not? Make a spacetime diagram.



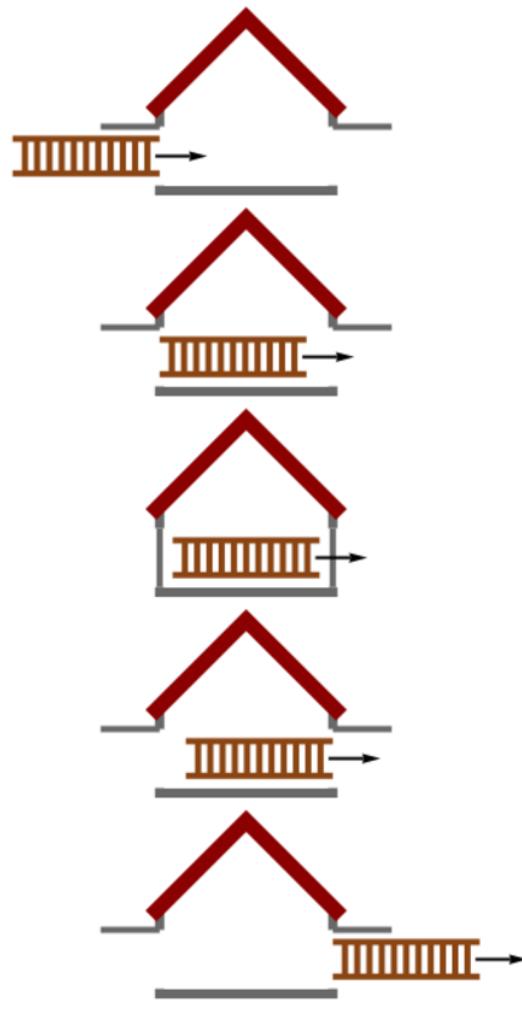


SR: pole-barn/ladder paradox



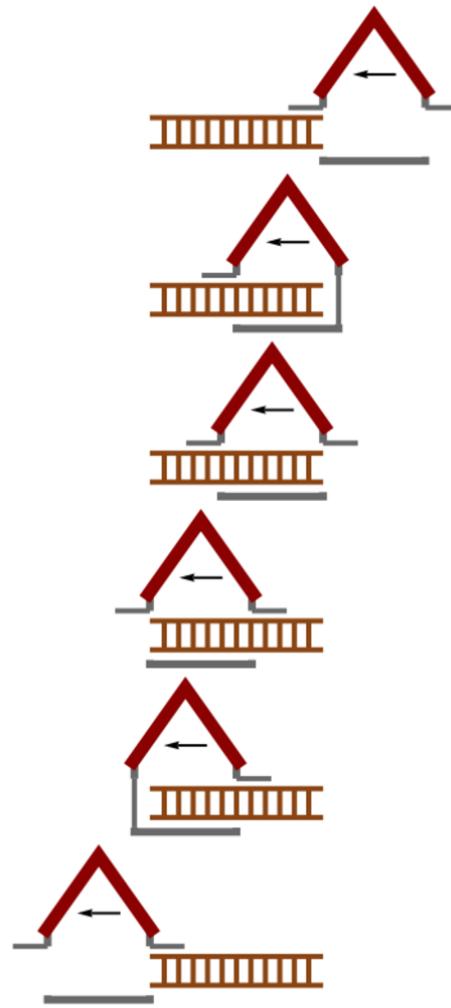


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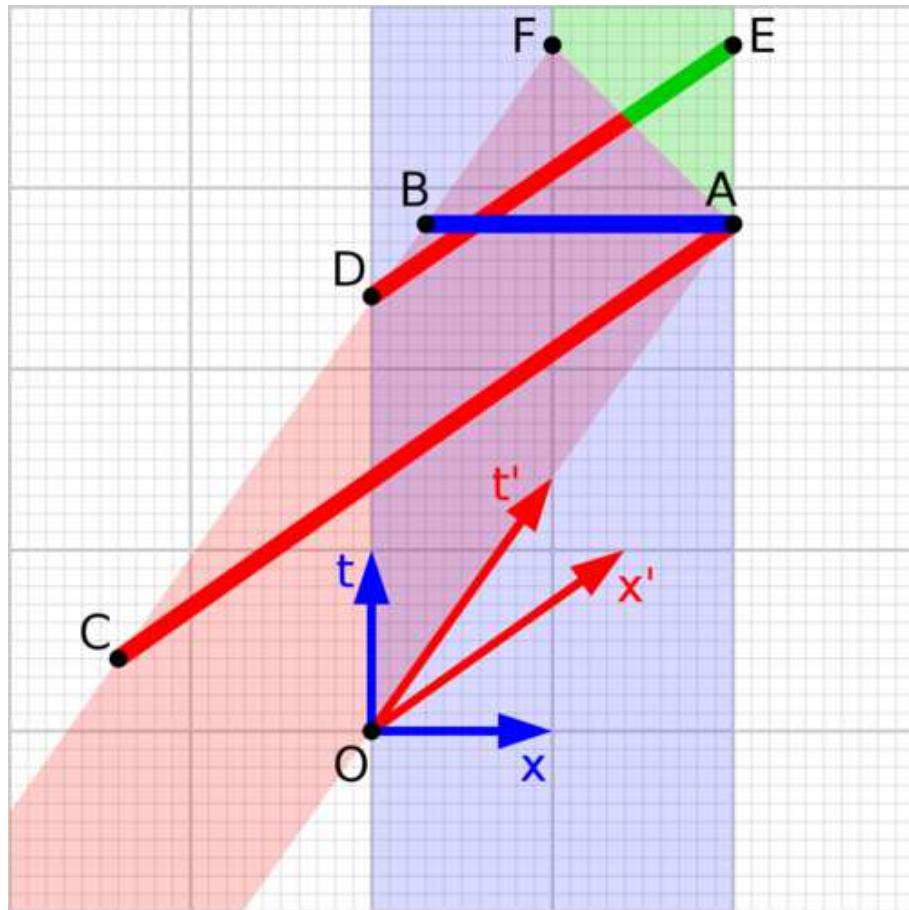


SR: pole-barn/ladder paradox





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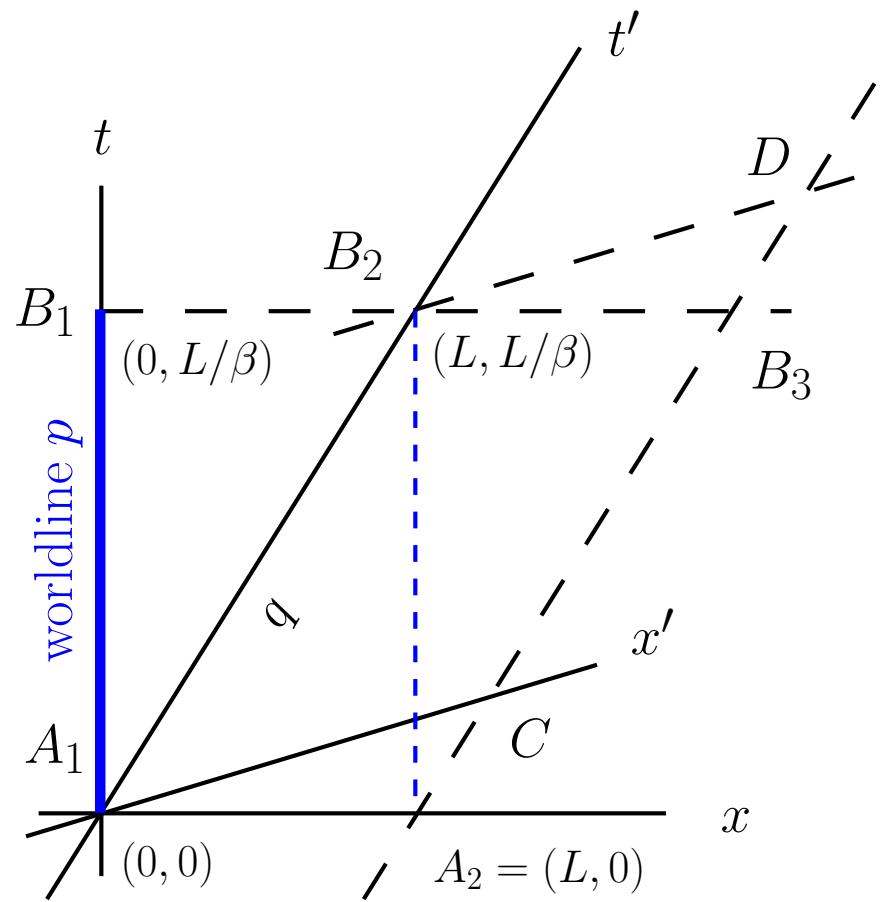


[w:Ladder paradox](#)





SR: twins paradox

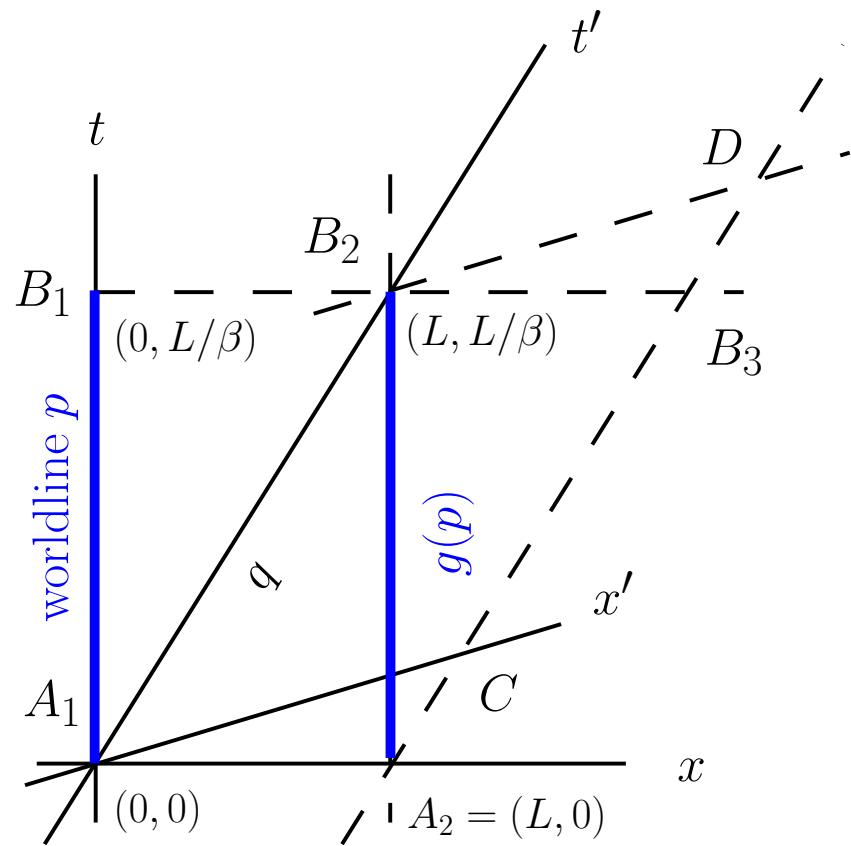


simply connected Minkowski





SR: twins paradox

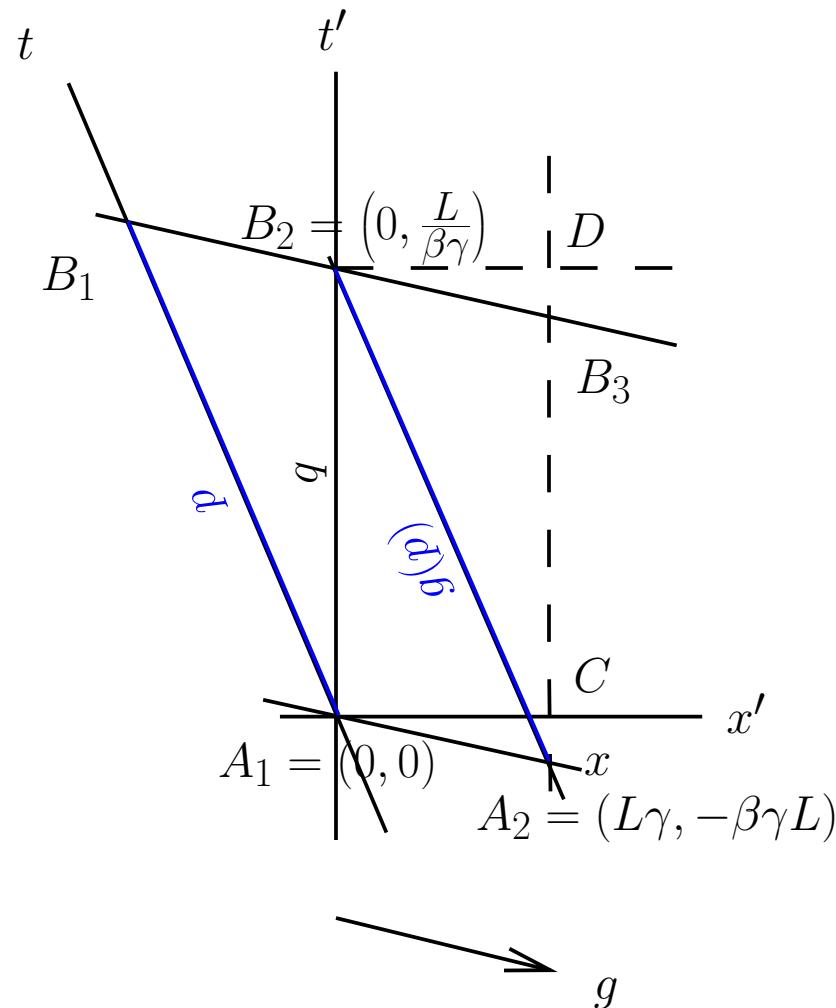


holonomy \overrightarrow{g}
identify spacetime events

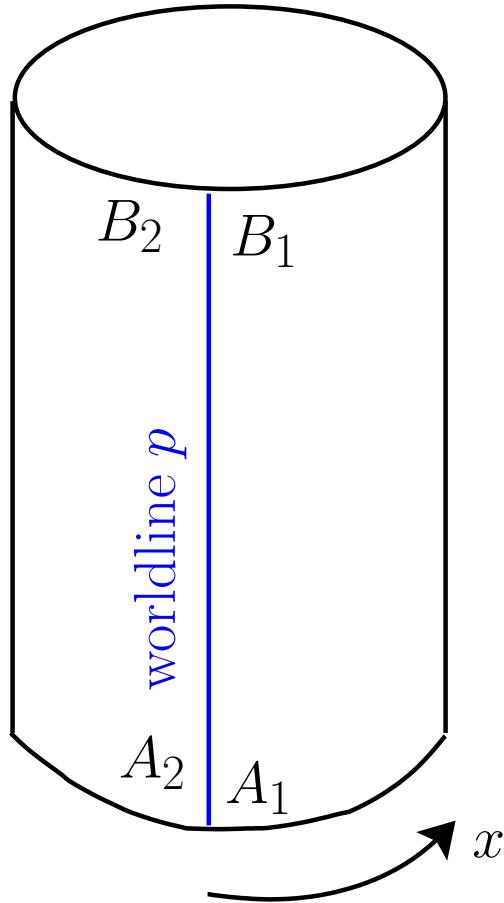




SR: twins paradox

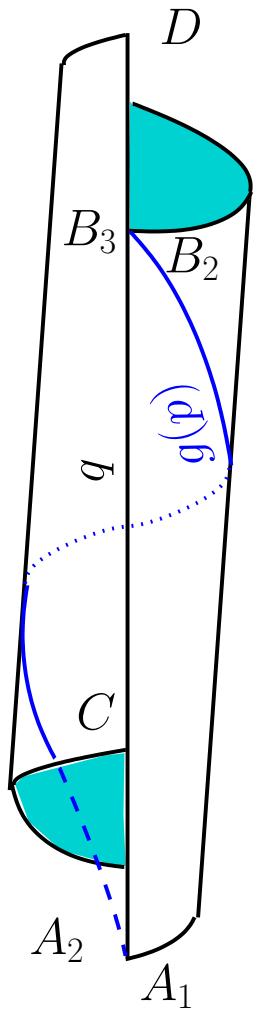


SR: twins paradox

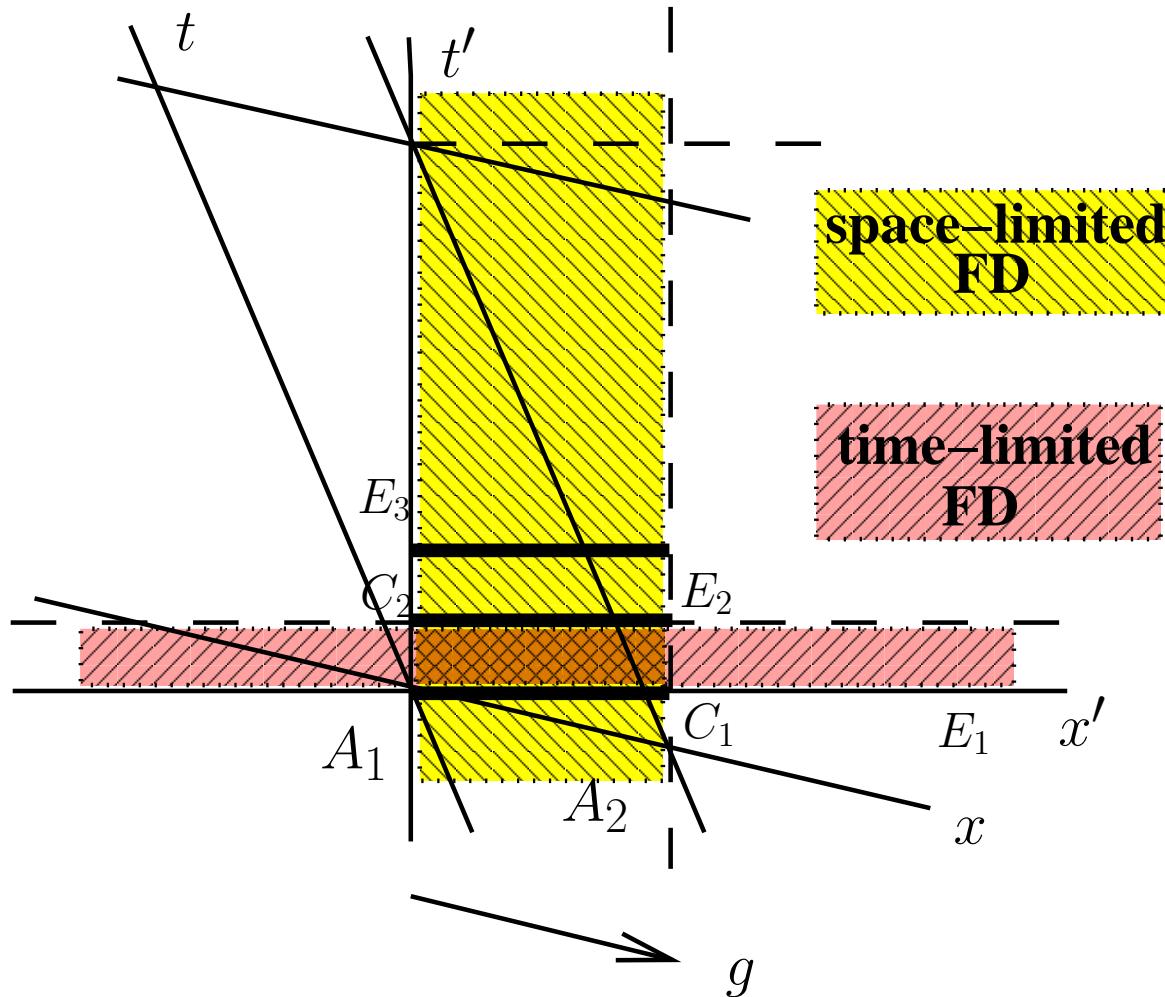




SR: twins paradox

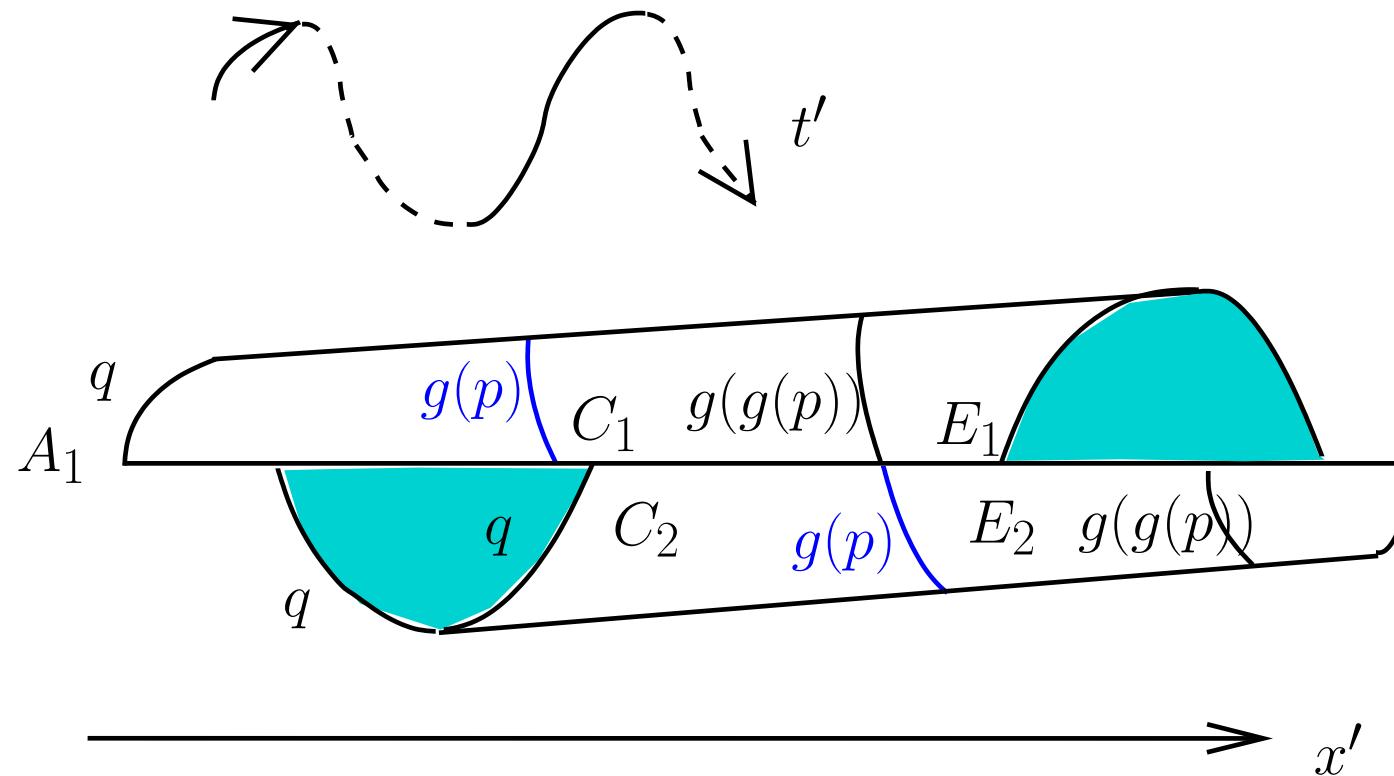


SR: twins paradox





SR: twins paradox



Roukema & Bajtlik 2008, MNRAS, 390, 655
[arXiv:astro-ph/0612155](https://arxiv.org/abs/astro-ph/0612155)

- helps understand w:Ehrenfest paradox



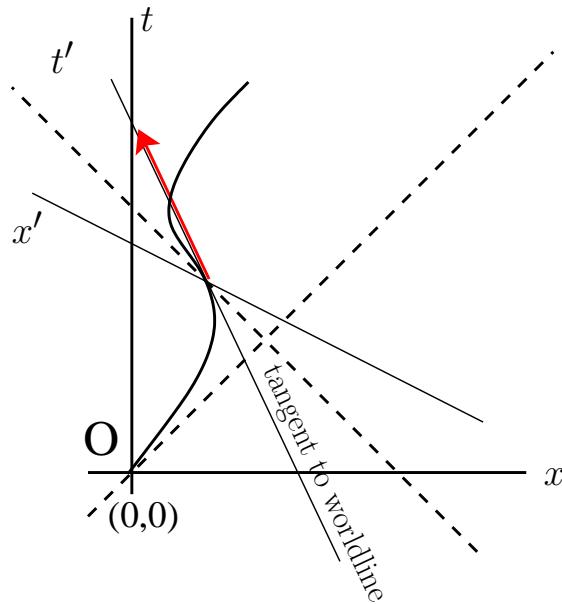
SR: four-velocity, four-momentum

choose x axis so that 3-velocity $u_{\text{Galilean}} = (\beta, 0, 0)^T$ for observer with $(t, x, y, z)^T$ coord system



SR: four-velocity, four-momentum

choose x axis so that 3-velocity $u_{\text{Galilean}} = (\beta, 0, 0)^T$ for observer with (t, x, y, z) coord system



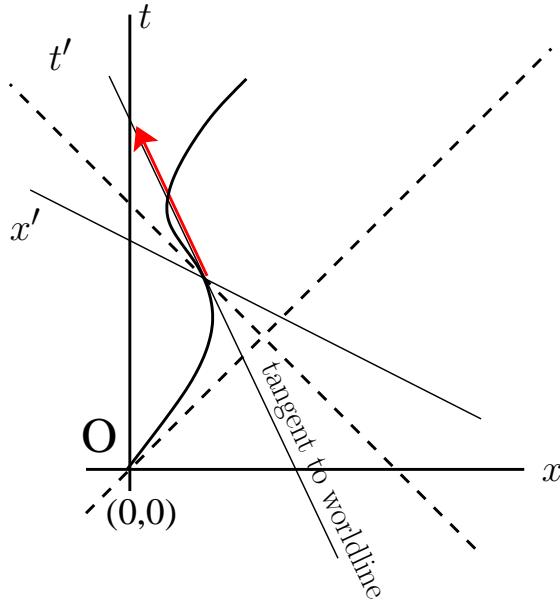
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$$(u^t, u^x) := \left(\frac{d}{d\tau} t(\tau), \frac{d}{d\tau} x(\tau) \right)$$

w:four-velocity



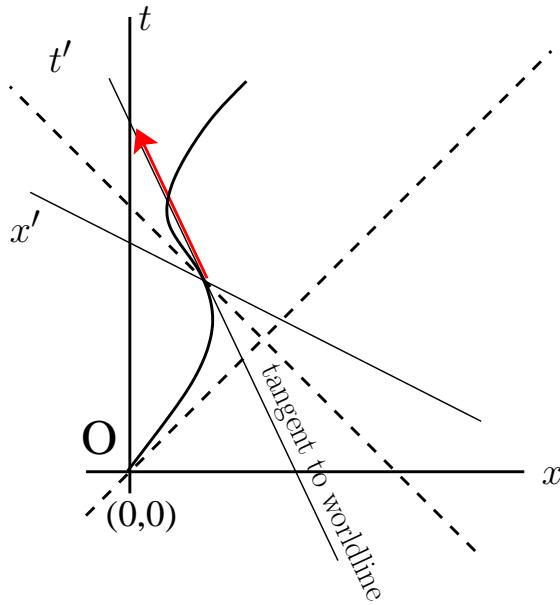
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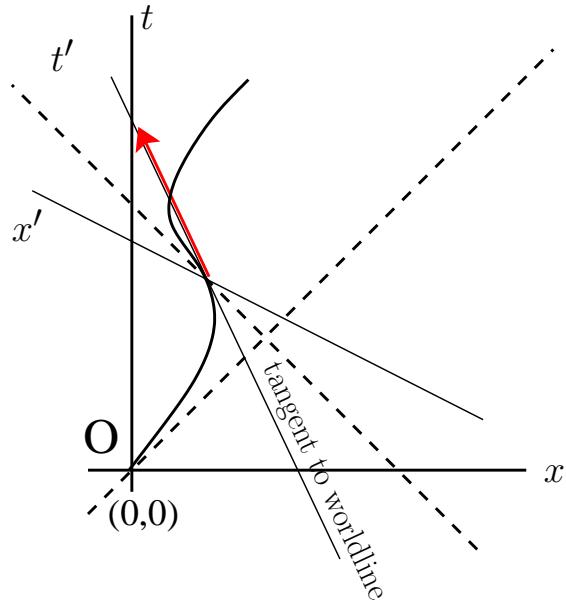
$$\text{similarly } (u^{t'}, u^{x'}) = \left(\frac{d}{d\tau} t'(\tau), \frac{d}{d\tau} x'(\tau) \right)$$



L in (t, x) spacetime
2-plane, extend from

SR: four-velocity, four-momentum

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w:four-velocity

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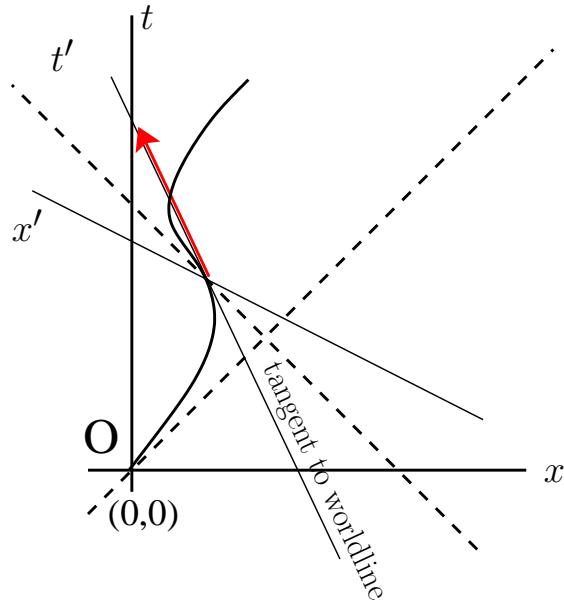
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want \vec{u} Lorentz invariant \Rightarrow
 $(u^t, u^x)^T = \Lambda^{-1}(1, 0)^T$

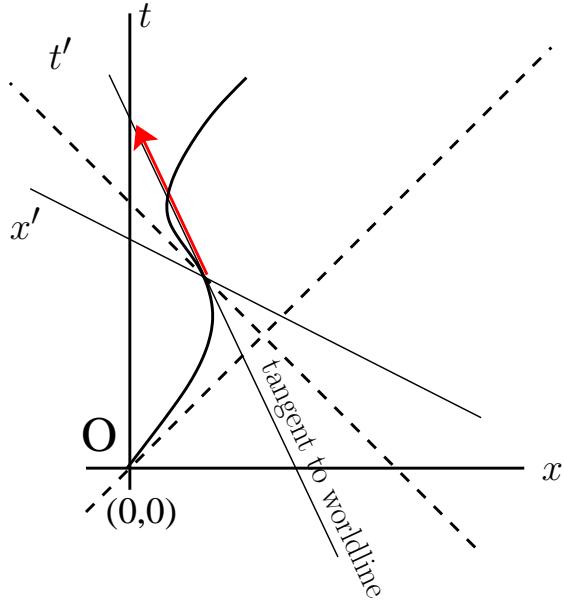
- in (t, x) spacetime

L²-plane, extend from

scalar speed β to
spacetime vector

SR: four-velocity, four-momentum

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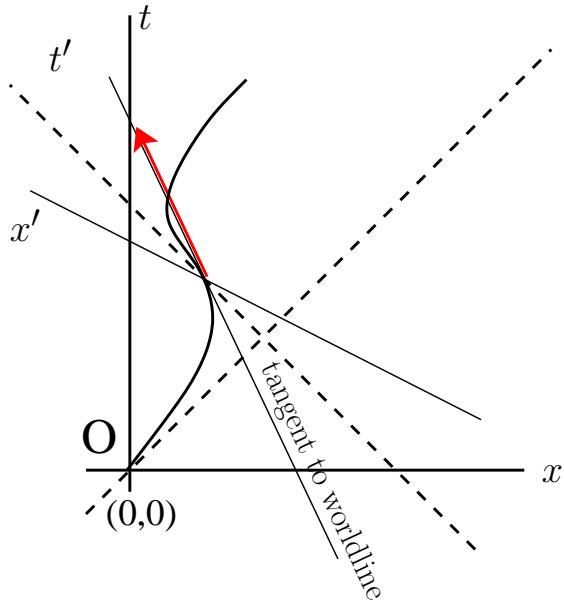
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 $\Rightarrow (u^t, u^x)^T = \Lambda^{-1}(1, 0)^T = \gamma(1, \beta)^T$

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want \vec{u} Lorentz invariant
 $\Rightarrow (u^t, u^x)^T = \Lambda^{-1}(1, 0)^T = \gamma(1, \beta)^T$

4D: $\vec{u} = \gamma(1, \beta^x, \beta^y, \beta^z)^T$

notation in this pdf:

\vec{u} = 4-vector, ${}^{(3)}\vec{u}$ = spatial component

SR: four-velocity, four-momentum

Is the 3-component (spatial component) of \vec{u} the same as the non-relativistic velocity?



SR: four-velocity, four-momentum

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SR: four-velocity, four-momentum



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$$(3) \vec{u} = \frac{d}{d\tau} (x, y, z)^T$$

$$= \gamma \frac{d}{dt} (x, y, z)^T$$



SR: four-velocity, four-momentum

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$$(3) \vec{u} = \frac{d}{d\tau}(x, y, z)^T$$

$$= \gamma \frac{d}{dt}(x, y, z)^T$$

$\neq \frac{d}{dt}(x, y, z)^T$ except if $\beta = 0 \Leftrightarrow \gamma = 1$



SR: four-velocity, four-momentum

momentum: $\vec{p} := m\vec{u} = m\gamma(1, \beta^x, \beta^y, \beta^z)^T$, where $m = \text{constant}$ w:invariant mass

^x ... = tensor-style component notation, not powers



SR: four-velocity, four-momentum

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momentum: $\vec{p} := m\vec{u} = m\gamma(1, \beta^x, \beta^y, \beta^z)^T$, where $m = \text{constant}$ [w:invariant mass](#)

What does the time component of momentum = $p^0 = m\gamma$ mean physically?

- first look at spatial component in a given ref. frame



SR: four-velocity, four-momentum

momentum: $\vec{p} := m\vec{u} = m\gamma(1, \beta^x, \beta^y, \beta^z)^T$, where $m = \text{constant}$ w:invariant mass

$$(3) \vec{p} = m \frac{d}{d\tau}(x, y, z)^T$$



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SR: four-velocity, four-momentum

let us define 4-acceleration, 4-force



SR: four-velocity, four-momentum

$$(u^t, u^x) := \left(\frac{d}{d\tau} t(\tau), \frac{d}{d\tau} x(\tau) \right)$$



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$$\vec{a} := \frac{d}{d\tau} \vec{u}$$



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$${}^{(3)}\vec{a} = \frac{d^2}{d\tau^2} {}^{(3)}\vec{x}$$



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$$\vec{a} := \frac{d}{d\tau} \vec{u}$$

$$^{(3)}\vec{a} = \frac{d^2}{d\tau^2}(x, y, z)^T$$



SR: four-velocity, four-momentum



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$${}^{(4)}\vec{f} := m \ {}^{(4)}\vec{a} \quad \text{defn } \underline{\text{w:four-force}}$$



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$$= m \frac{d}{d\tau} \vec{u}$$



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$$= \frac{d}{d\tau} \vec{p}$$



SR: invariance of ${}^{(4)}u$, ${}^{(4)}a$, ${}^{(4)}f$

Euclidean norm: $\|\vec{x}\|^2 = \sum_\mu (x^\mu)^2$



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w:Einstein summation sum is implicit





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Minkowski pseudo-norm: $\|\vec{x}\|^2 = -x^0x^0 + \delta_{ij}x^i x^j$

$\delta_{ij} = 1$ if $i = j$, otherwise = 0; $i, j \in 1, 2, 3$

invariance: $\|\vec{x}\|^2$ = same in all reference frames

sign convention: $(-, +, +, +)$ or $(+, -, -, -)$ are common



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similarly: $\|\vec{a}\|^2$, $\|\vec{f}\|^2$ invariant



SR: energy: varies with ref frame

Newtonian $K = (1/2)m\beta^2 = 0$ in rest frame



SR: energy: varies with ref frame



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4-force \vec{f} is invariant, but

3-force usually *defined* to be frame-dependent:

3-force := $\frac{d}{dt}^{(3)}\vec{p} \neq \frac{d}{d\tau}^{(3)}\vec{p}$



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$K = \text{work done}$



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$$\begin{aligned} &= \int_0^{\beta_2} \frac{(3)\vec{f}}{\gamma} \cdot d\vec{x} \\ &= \int_0^{\beta_2} \frac{d}{dt}(m\beta\gamma)dx \end{aligned}$$

(assume $(3)\vec{f}/\gamma \parallel \vec{x}$)



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$$\Rightarrow K + m = m\gamma \text{ drop "2"}$$



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so p^0 = kinetic energy + rest mass



SR: energy: varies with ref frame

Does small β limit agree with Newtonian K ?



SR: energy: varies with ref frame



Does small β limit agree with Newtonian K ?

momentum time component:

$$\begin{aligned} p^0 &= m\gamma = m(1 - \beta^2)^{-1/2} \\ &= m[1 - (1/2)(-\beta^2) + \mathcal{O}(\beta^4)] \text{ if } \beta \ll 1 \end{aligned}$$



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Yes.





SR: \vec{p} ...: invariant or not?

momentum: $\vec{p} = m\gamma(1, \beta^x, \beta^y, \beta^z)^T$

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m = w:invariant mass \equiv rest mass: invariant

AND conserved (in interactions): $\|\vec{p} + \vec{q}\|^2 = \|\vec{r}\|^2$





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WARNING: assume that 4-momentum vectors at different space-time positions can be parallel-transported; not the case in curved spacetime





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vector space $\Rightarrow p^i + q^i = r^i$ ($i = 1, 2, 3$)





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= conservation of (relativistic) 3-momentum (Newtonian: conserved)

but NOT invariant (Newtonian: not invariant)





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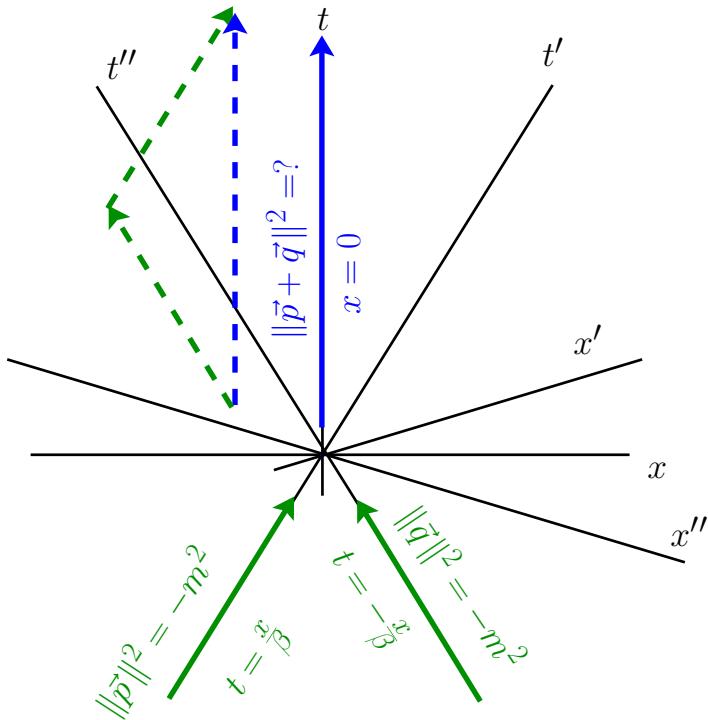
vector space $\Rightarrow p^0 + q^0 = r^0$

= conservation of (relativistic) “total energy” = $m + K$
(Newtonian: m conserved, K not conserved, $K+$ potential energy conserved)

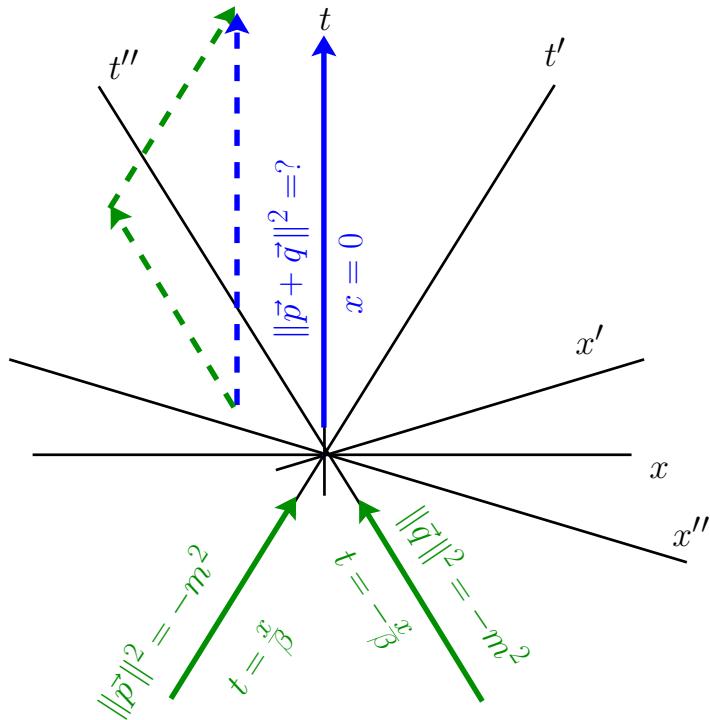
but NOT invariant (Newtonian: m invariant, K not invariant)



SR: $\vec{p} \dots$: invariant or not?



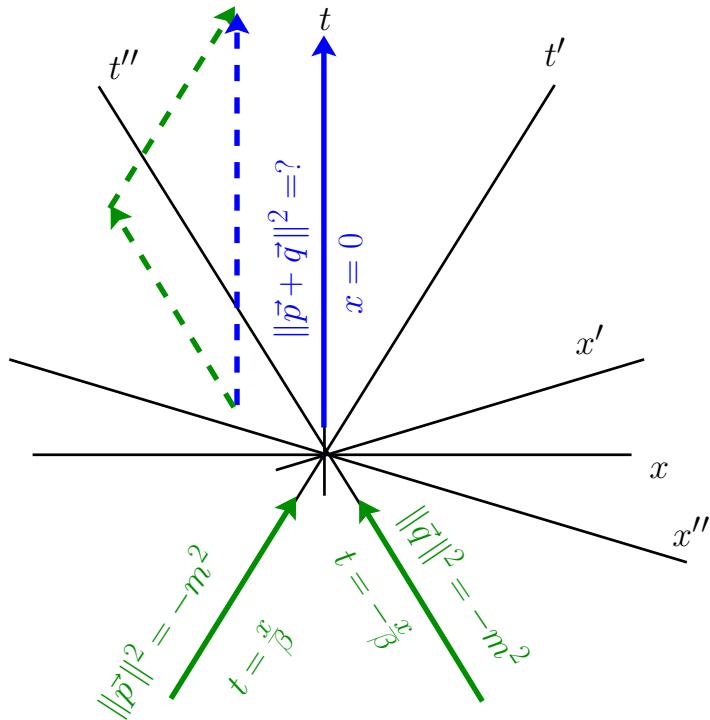
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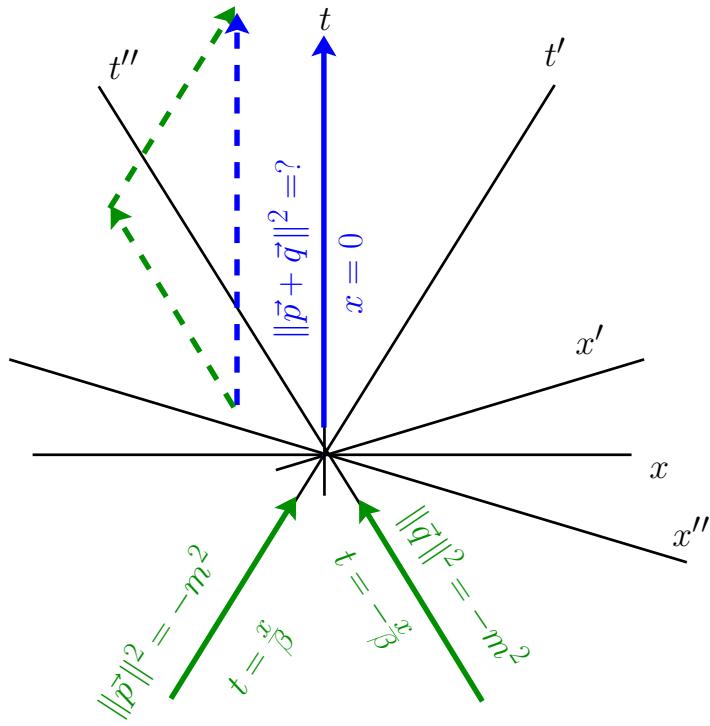


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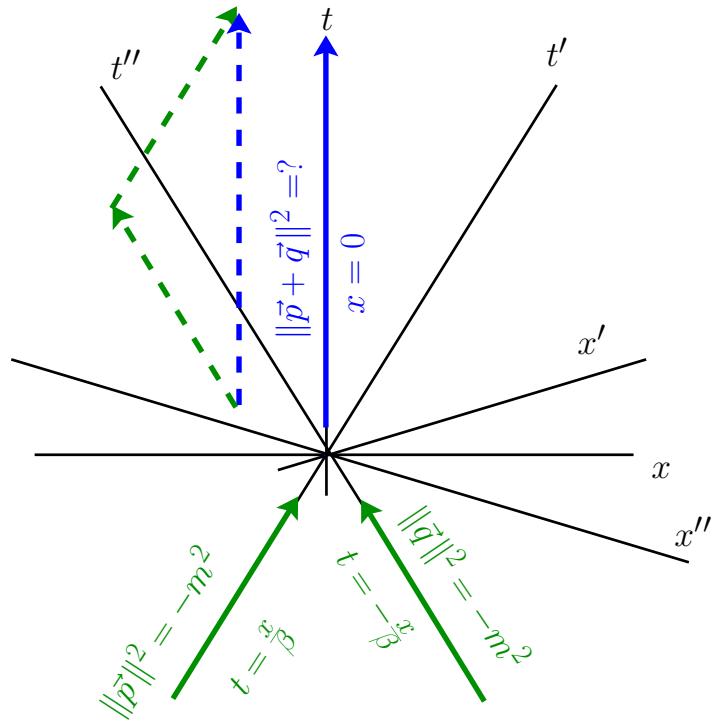
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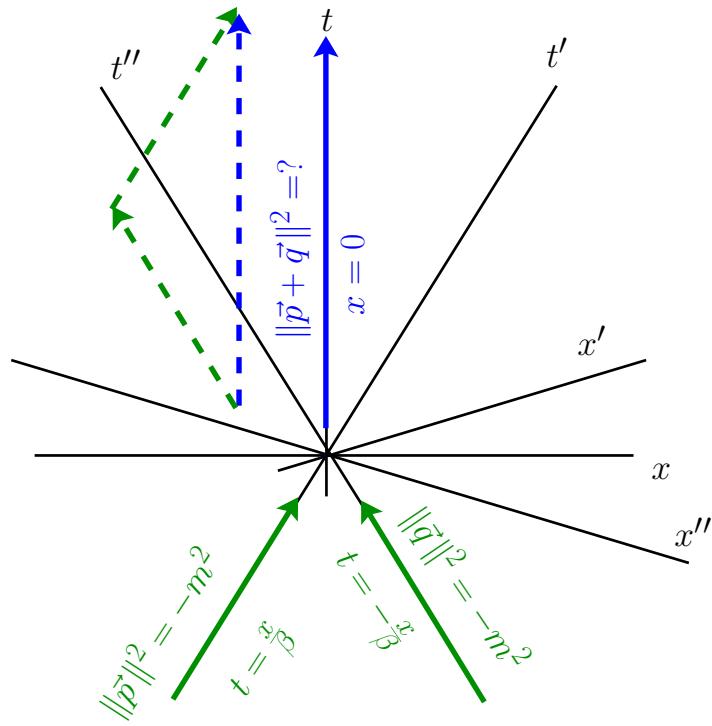
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$$L = m[2\gamma, (-\beta + \beta)\gamma, 0, 0]^T$$



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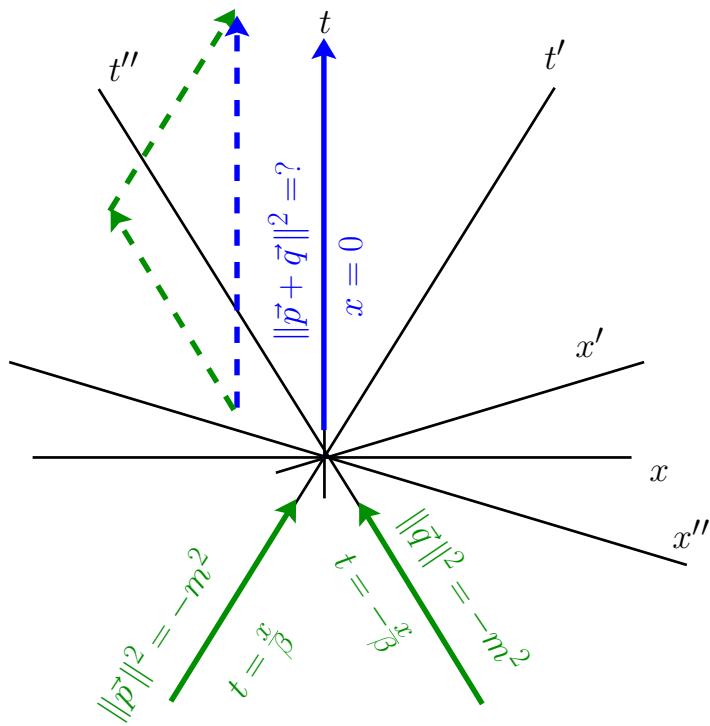
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$$\vec{r} = \vec{p} + \vec{q} = 2m\gamma(1, 0, 0, 0)^T$$





SR: \vec{p} ...: invariant or not?



system rest mass before and after: $2m\gamma$

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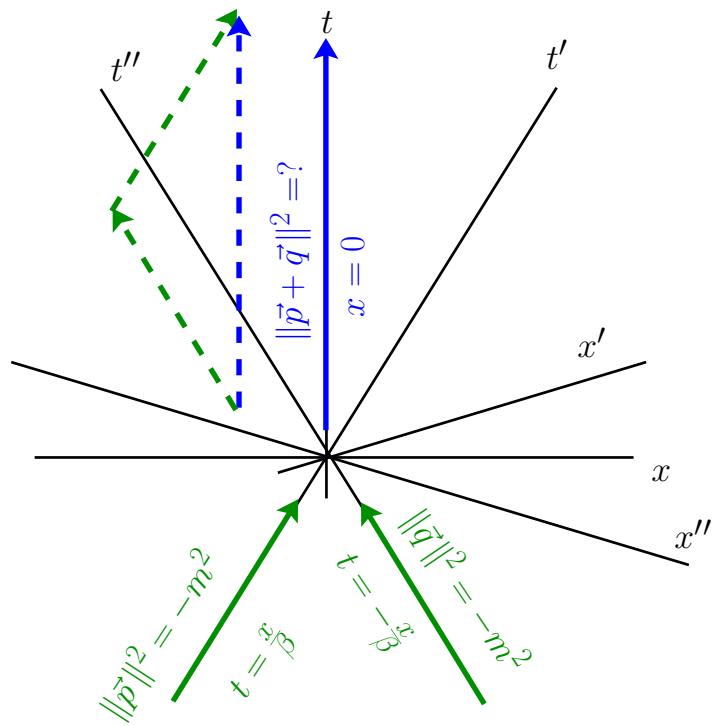
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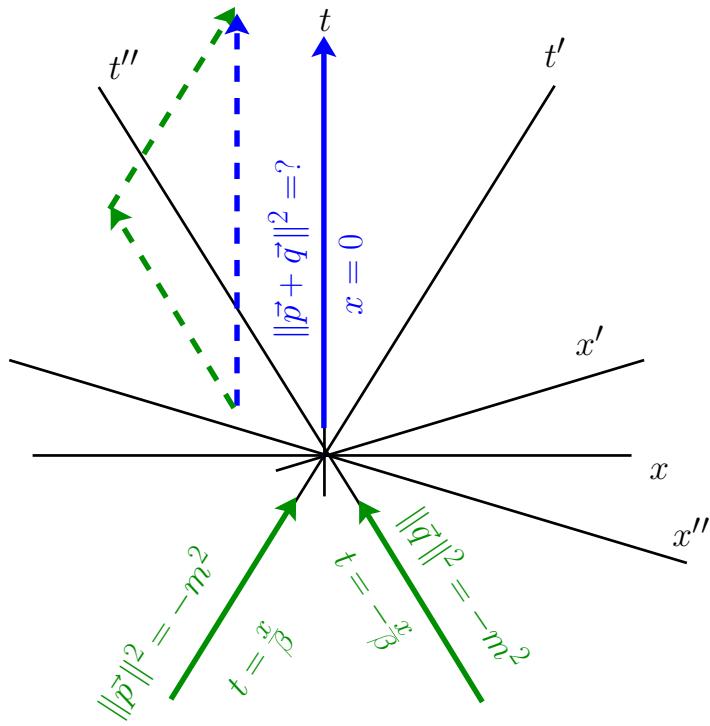
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$$\sqrt{-\|\vec{p}\|^2} + \sqrt{-\|\vec{q}\|^2} \neq \sqrt{-\|\vec{r}\|^2}$$

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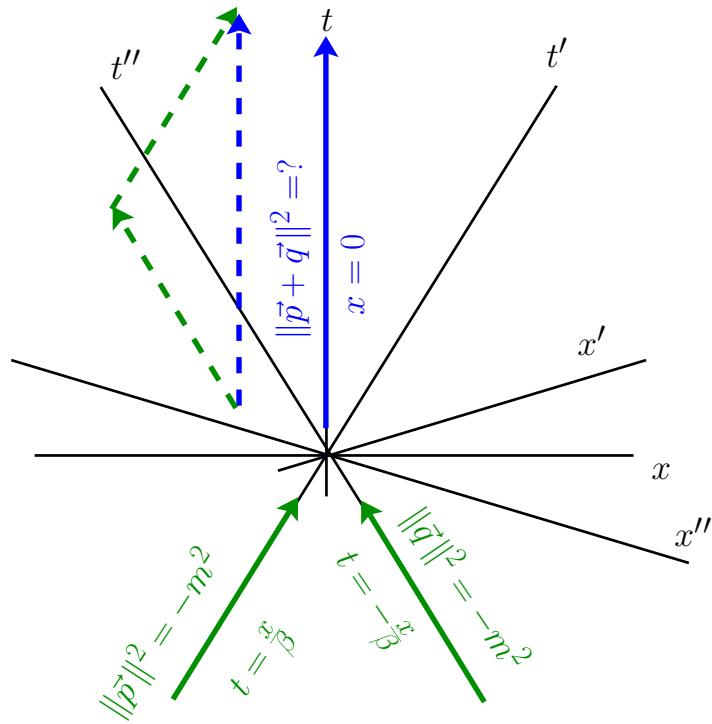
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rest masses in many different frames:

$$m + m \neq 2m\gamma \text{ if } \gamma \neq 1$$

$$\sqrt{-\|\vec{p}\|^2} + \sqrt{-\|\vec{q}\|^2} \neq \sqrt{-\|\vec{r}\|^2}$$

system mass is invariant, but can be divided into p^0 and $p^i, i \in \{1, 2, 3\}$ components in many different ways



SR: $\vec{p} \dots$: invariant or not?

interaction: momenta: $\vec{p} + \vec{q} \rightarrow \vec{r}$

moduli: $m, m, 2m\gamma$





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$E = m$ (the famous equation)





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moduli: $m, m, 2m\gamma$

total energy $E := p^0$

rest frame: $E := p^0 = t$ component of $m(1, 0, 0, 0)^T$

$E = m$ (the famous equation)

this means: in the rest frame, $K + m = m$ (trivial)

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refuse the assumption of absolute simultaneity (time)

