

**LINEAR
DATABOOK**

**NATIONAL
SEMICONDUCTOR**



1980

LINEAR

DATABOOK

National Semiconductor

LINEAR DATABOOK

Voltage Regulators

1

Voltage References

2

Operational Amplifiers/Buffers

3

Instrumentation Amplifiers

4

Voltage Comparators

5

Analog Switches

6

Sample and Hold

7

A to D, D to A

8

**Industrial/Automotive/Functional Blocks/
Telecommunications**

9

Audio, Radio and TV Circuits

10

Transistor/Diode Arrays

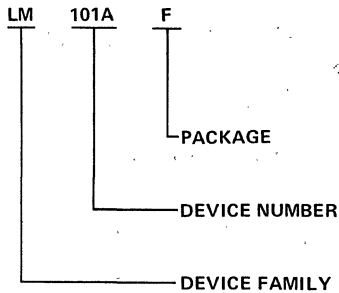
11

Appendices/Physical Dimensions

12



Ordering Information



PACKAGE

- D – Glass/Metal Dual-In-Line Package
- F – Glass/Metal Flat Pack
- H – TO-5 (TO-99, TO-100, TO-46)
- J – Low Temperature Glass Dual-In-Line Package
- K – TO-3 (Steel)
- KC – TO-3 (Aluminum)
- N – Plastic Dual-In-Line Package
- P – TO-202 (D-40, Durawatt)
- S – “SGS” Type Power Dual-In-Line Package
- T – TO-220
- W – Low Temperature Glass Flat-Pack
- Z – TO-92

DEVICE NUMBER

- 3, 4, or 5 Digit Number Suffix Indicators:
- A – Improved Electrical Specification
 - C – Commercial Temperature Range

DEVICE FAMILY

- AD – Analog to Digital
- AH – Analog Hybrid
- AM – Analog Monolithic
- CD – CMOS Digital
- DA – Digital to Analog
- DM – Digital Monolithic
- LF – Linear FET
- LH – Linear Hybrid
- LM – Linear Monolithic
- LX – Transducer
- MM – MOS Monolithic
- TBA – Linear Monolithic

Devices are listed in the table of contents alpha-numerically by device family (LH, LM, LX, etc.) and then by device number. With most of National's proprietary linear circuits, a 1-2-3 numbering system is employed. The 1 denotes a Military temperature range device (-55°C to $+125^{\circ}\text{C}$), the 2 denotes an Industrial temperature range device (-25°C to $+85^{\circ}\text{C}$), and the 3 denotes a Commercial temperature range device (0°C to $+70^{\circ}\text{C}$), i.e. LM101/LM201/LM301.

Exceptions to this are the LM1800 series of consumer circuits which are specified for the commercial temperature range; some hybrid circuits which employ a “C” suffix to denote the commercial temperature range; and second-source products which follow the original manufacturers numbering system, i.e. LM741/LM741C or LM1414/LM1514.

Parts are generally listed in the table of contents by military part number first, i.e. LM139/LM239/LM339. Where a separate data sheet exists for a different temperature range, the device will be listed separately, i.e. LM119/LM219 and listed separately LM319. Where only one temperature range exists, the part will be listed in its proper order, i.e. LM340.

Table of Contents

| | |
|-----------------------------------|---|
| Edge Index by Product Family..... | 1 |
| Ordering Information..... | 2 |
| Alpha-Numerical Index..... | 9 |

Section 1—Voltage Regulators†

| | |
|--|--------|
| Voltage Regulator Guide..... | 1-iii |
| Precision Regulator Guide..... | 1-vii |
| Definition of Terms..... | 1-viii |
| Fixed or Adjustable Voltage Regulators..... | 1-1 |
| LM104/LM204/LM304 Negative Regulator..... | 1-2 |
| LM105/LM205/LM305/LM305A, LM376 Voltage Regulators..... | 1-5 |
| LM109/LM209/LM309 5-Volt Regulator..... | 1-10 |
| LM117/LM217/LM317 3-Terminal Adjustable Regulator..... | 1-15 |
| LM117HV/LM217HV/LM317HV High Voltage 3-Terminal Adjustable Regulator..... | 1-23 |
| LM120 Series 3-Terminal Negative Regulators..... | 1-31 |
| LM123/LM223/LM323 3 Amp, 5 Volt Positive Regulator..... | 1-39 |
| LM125/LM325/LM325A, LM126/LM326 Voltage Regulators..... | 1-43 |
| LM130/LM330 3-Terminal Positive Regulators..... | 1-50 |
| LM137/LM237/LM337 3-Terminal Adjustable Negative Regulators..... | 1-56 |
| LM137HV/LM237HV/LM337HV 3-Terminal Adjustable Negative Regulators (High Voltage)..... | 1-61 |
| LM138/LM238/LM338 5 Amp Adjustable Power Regulators..... | 1-66 |
| LM140A/LM140/LM340A/LM340 Series 3-Terminal Positive Regulators..... | 1-74 |
| LM140L/LM340L Series 3-Terminal Positive Regulators..... | 1-82 |
| LM145/LM245/LM345 Negative Three Amp Regulator..... | 1-85 |
| LM150/LM250/LM350 3 Amp Adjustable Power Regulators..... | 1-89 |
| LM320L/LM320ML Series 3-Terminal Negative Regulators..... | 1-97 |
| LM341 Series 3-Terminal Positive Regulators..... | 1-103 |
| LM342 Series 3-Terminal Positive Regulators..... | 1-106 |
| LM723/LM723C Voltage Regulator..... | 1-110 |
| LM1524/LM2524/LM3524 Regulating Pulse Width Modulator..... | 1-115 |
| LM2930 3-Terminal Positive Regulator..... | 1-130 |
| LM78XX Series Voltage Regulators..... | 1-136 |
| LM78LXX Series 3-Terminal Positive Regulators..... | 1-139 |
| LM78MXX Series 3-Terminal Positive Regulators..... | 1-145 |
| LM79XX Series 3-Terminal Negative Regulators..... | 1-148 |
| LM79LXXAC Series 3-Terminal Negative Regulators..... | 1-153 |
| LM79MXX Series 3-Terminal Negative Regulators..... | 1-157 |

†For additional information, see National Semiconductor's Voltage Regulator Handbook.

Section 2—Voltage References

| | |
|--|-------|
| Voltage Reference Guide..... | 2-iii |
| Voltage Reference and Precision Reference Guides..... | 2-iv |
| LH0070 Series Precision BCD Buffered Reference..... | 2-1 |
| LH0071 Series Precision Binary Buffered Reference..... | 2-1 |
| LH0075 Positive Precision Programmable Regulator..... | 2-5 |
| LH0076 Negative Precision Programmable Regulator..... | 2-10 |
| LM103 Reference Diode..... | 2-15 |
| LM113/LM313 Reference Diode..... | 2-18 |
| LM129/LM329 Precision Reference..... | 2-21 |
| LM136/LM236/LM336 2.5V Reference Diode..... | 2-26 |
| LM185/LM285/LM385 Voltage Reference Diode..... | 2-32 |
| LM199/LM299/LM399 Precision Reference..... | 2-38 |
| LM199A/LM299A/LM399A Precision Reference..... | 2-44 |
| LM3999 Precision Reference..... | 2-47 |

Table of Contents (Continued)

Section 3—Operational Amplifiers/Buffers†

| | |
|---|--------|
| BI-FET™/BI-FET II™ Op Amp Selection Guide..... | 3-v |
| Military Op Amp Selection Guide..... | 3-vii |
| Industrial Op Amp Selection Guide..... | 3-ix |
| Commercial Op Amp Selection Guide..... | 3-x |
| Special Function Operational and Special Function Buffer Amplifier Guides..... | 3-xii |
| Definition of Terms..... | 3-xiii |
| LF155/LF156/LF157 Series Monolithic JFET Input Operational Amplifiers..... | 3-1 |
| LF347 Wide Bandwidth Quad JFET Input Operational Amplifier..... | 3-14 |
| LF351 Wide Bandwidth JFET Input Operational Amplifier..... | 3-22 |
| LF353 Wide Bandwidth Dual JFET Input Operational Amplifier..... | 3-29 |
| LF13741 Monolithic JFET Input Operational Amplifier..... | 3-38 |
| LM10/LM10B(L)/LM10C(L) Op Amp and Voltage Reference..... | 3-49 |
| LM101A/LM201A/LM301A Operational Amplifiers..... | 3-65 |
| LH2101A/LH2201A/LH2301A Dual High Performance Op Amp..... | 3-72 |
| LM102/LM202/LM302 Voltage Followers..... | 3-74 |
| LM107/LM207/LM307 Operational Amplifiers..... | 3-79 |
| LM108/LM208/LM308 Operational Amplifiers..... | 3-83 |
| LM108A/LM208A/LM308A, LM308A-1, LM308A-2 Operational Amplifiers..... | 3-88 |
| LH2108/LH2208/LH2308, LH2108A/LH2208A/LH2308A Dual Super Beta Op Amp..... | 3-93 |
| LM110/LM210/LM310 Voltage Follower..... | 3-95 |
| LM112/LM212/LM312 Operational Amplifiers..... | 3-102 |
| LM118/LM218/LM318 Operational Amplifiers..... | 3-106 |
| LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902 Low Power Quad Operational Amplifiers..... | 3-113 |
| LM143/LM343 High Voltage Operational Amplifier..... | 3-122 |
| LM144/LM344 High Voltage, High Slew Rate Operational Amplifier..... | 3-129 |
| LM146/LM246/LM346 Programmable Quad Operational Amplifiers..... | 3-135 |
| LM148, LM149 Series Quad 741 Op Amps..... | 3-147 |
| LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904 Low Power Dual Operational Amplifiers..... | 3-157 |
| LM159/LM359 Dual, High Speed, Programmable, Current Mode (Norton) Amplifiers..... | 3-167 |
| LM192/LM292/LM392, LM2924 Low Power Operational Amplifier/Voltage Comparator..... | 3-183 |
| LM216/LM316, LM216A/LM316A Operational Amplifiers..... | 3-187 |
| LM709/LM709A/LM709C Operational Amplifier..... | 3-190 |
| LM725/LM725A/LM725C (Instrumentation) Operational Amplifier..... | 3-194 |
| LM733/LM733C Differential Video Amp..... | 3-198 |
| LM741/LM741A/LM741C/LM741E Operational Amplifier..... | 3-202 |
| LM747/LM747A/LM747C/LM747E Dual Operational Amplifiers..... | 3-205 |
| LM748/LM748C Operational Amplifier..... | 3-210 |
| LM1558/LM1458 Dual Operational Amplifier..... | 3-213 |
| LM2900/LM3900, LM3301, LM3401 Quad Amplifiers..... | 3-215 |
| LM4250/LM4250C Programmable Operational Amplifier..... | 3-224 |
| LH24250/LH24250C Dual Programmable Micropower Op Amp..... | 3-229 |
| LM13080 Programmable Power Op Amp..... | 3-231 |
| LH0002/LH0002C Current Amplifier..... | 3-238 |
| LH0021/LH0021C 1.0 Amp Power Operational Amplifier..... | 3-241 |
| LH0041/LH0041C 0.2 Amp Power Operational Amplifier..... | 3-241 |
| LH0022/LH0022C High Performance FET Op Amp..... | 3-248 |
| LH0042/LH0042C Low Cost FET Op Amp..... | 3-248 |
| LH0052/LH0052C Precision FET Op Amp..... | 3-248 |

†For additional information, see National Semiconductor's Special Functions Databook.

Table of Contents (Continued)

Section 3—Operational Amplifiers/Buffers[†] (Continued)

| | |
|--|-------|
| LH0024/LH0024C High Slew Rate Operational Amplifier..... | 3-255 |
| LH0032/LH0032C Ultra Fast FET Operational Amplifier..... | 3-258 |
| LH0033/LH0033C, LH0063/LH0063C Fast and Damn Fast Buffer Amplifiers..... | 3-263 |
| LH0044 Series Precision Low Noise Operational Amplifiers..... | 3-274 |
| LH0045/LH0045C Two Wire Transmitter..... | 3-280 |
| LH0061/LH0061C 0.5 Amp Wide Band Operational Amplifier..... | 3-291 |
| LH0062/LH0062C High Speed FET Operational Amplifier..... | 3-294 |
| LH2110/LH2210/LH2310 Dual Voltage Follower..... | 3-300 |

[†]For additional information, see National Semiconductor's Special Functions Databook.

Section 4—Instrumentation Amplifiers[†]

| | |
|---|-------|
| Special Function Instrumentation Amplifier Guide..... | 4-iii |
| Definition of Terms..... | 4-iv |
| LF152/LF352 FET Input Instrumentation Amplifier..... | 4-1 |
| LM121/LM221/LM321, LM121A/LM221A/LM321A Precision Preamplifiers..... | 4-11 |
| LH0036/LH0036C Instrumentation Amplifier..... | 4-19 |
| LH0038/LH0038C True Instrumentation Amplifier..... | 4-27 |
| LH0084/LH0084C Digitally Programmable Gain Instrumentation Amplifier..... | 4-38 |

[†]For additional information, see National Semiconductor's Special Functions Databook.

Section 5—Voltage Comparators

| | |
|---|-------|
| Voltage Comparator Guide..... | 5-iii |
| Definition of Terms..... | 5-iv |
| LF111/LF211/LF311 Voltage Comparators..... | 5-1 |
| LH2111/LH2211/LH2311 Dual Voltage Comparator..... | 5-7 |
| LM106/LM206/LM306 Voltage Comparator..... | 5-9 |
| LM111/LM211 Voltage Comparator..... | 5-12 |
| LM119/LM219/LM319 High Speed Dual Comparator..... | 5-18 |
| LM139/LM239/LM339, LM139A/LM239A/LM339A, LM2901, LM3302 Low Power Low Offset Voltage Quad Comparators..... | 5-23 |
| LM160/LM260/LM360 High Speed Differential Comparator..... | 5-31 |
| LM161/LM261/LM361 High Speed Differential Comparators..... | 5-34 |
| LM193/LM293/LM393, LM193A/LM293A/LM393A, LM2903 Low Power Low Offset Voltage Dual Comparators..... | 5-37 |
| LM311 Voltage Comparator..... | 5-44 |
| LM710/LM710C Voltage Comparator..... | 5-52 |
| LM711/LM711C Dual Comparator..... | 5-55 |
| LM1514/LM1414 Dual Differential Voltage Comparator..... | 5-58 |

Section 6—Analog Switches[†]

| | |
|--|-------|
| Analog Switches/Multiplexers Selection Guide..... | 6-iii |
| Hybrid Analog Switch Selection Guide..... | 6-iv |
| Definition of Terms..... | 6-iv |
| LF11331/LF13331 4 Normally Open Switches With Disable..... | 6-1 |
| LF11332/LF13332 4 Normally Closed Switches With Disable..... | 6-1 |
| LF11333/LF13333 2 Normally Closed Switches and 2 Normally Open Switches With Disable..... | 6-1 |
| LF11201/LF13201 4 Normally Closed Switches..... | 6-1 |
| LF11202/LF13202 4 Normally Open Switches..... | 6-1 |
| LF11508/LF13508 8-Channel Analog Multiplexer..... | 6-11 |
| LF11509/LF13509 4-Channel Differential Analog Multiplexer..... | 6-11 |

[†]For additional information, see National Semiconductor's Special Functions Databook and FET Databook.

Table of Contents (Continued)

Section 7—Sample and Hold†

| | |
|---|-------|
| Sample and Hold Amplifier Guide..... | 7-iii |
| Definition of Terms..... | 7-iv |
| LF198/LF298/LF398, LF198A/LF398A Monolithic Sample and Hold Circuits..... | 7-1 |

†For additional information, see National Semiconductor's Special Functions Databook.

Section 8—A to D, D to A†

| | |
|--|-------|
| A/D Converter/DVM Selection Guide..... | 8-iii |
| D/A Converter Selection Guide..... | 8-iv |
| General Data Acquisition System Block Diagram/Part Numbering System..... | 8-v |
| Definition of Terms..... | 8-vi |
| AD7520/AD7530/AD7533 10-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7521/AD7531 12-Bit Binary Multiplying D/A Converter..... | 8-1 |
| ADB1200 (MM5863) 12-Bit Binary A/D Building Block..... | 8-3 |
| ADC0800 (MM4357B/MM5357B) 8-Bit A/D Converter..... | 8-10 |
| ADC0801, ADC0802, ADC0803, ADC0804 8-Bit μ P Compatible A/D Converters..... | 8-21 |
| ADC0808, ADC0809 8-Bit μ P Compatible A/D Converters with 8-Channel Multiplexer..... | 8-45 |
| ADC0816, ADC0817 8-Bit μ P Compatible A/D Converters with 16-Channel Multiplexer..... | 8-56 |
| ADC1210, ADC1211 12-Bit CMOS A/D Converters..... | 8-67 |
| DAC0800 (LMDAC08) 8-Bit Digital-to-Analog Converter..... | 8-77 |
| DAC0808, DAC0807, DAC0806 8-Bit D/A Converters..... | 8-85 |
| DAC1000 thru DAC1008 10-Bit, μ P Compatible, Double-Buffered D to A Converters..... | 8-92 |
| DAC1020 10-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1200/DAC1201 12-Bit (Binary) Digital-to-Analog Converters..... | 8-124 |
| DAC1202/DAC1203 3-Digit (BCD) Digital-to-Analog Converters..... | 8-124 |
| DAC1220 12-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1280, DAC1285 12-Bit (Binary) Digital-to-Analog Converters..... | 8-131 |
| DAC1286, DAC1287 3-Digit (BCD) Digital-to-Analog Converters..... | 8-131 |
| DM2502, DM2503, DM2504 Successive Approximation Registers..... | 8-139 |
| LF13300 Integrating A/D Analog Building Block..... | 8-144 |
| LM131A/LM131, LM231A/LM231, LM331A/LM331 Precision Voltage-to-Frequency Converters..... | 8-162 |
| LM1508/LM1408 8-Bit D/A Converter..... | 8-173 |
| MM54C905/MM74C905 12-Bit Successive Approximation Register..... | 8-175 |
| TP3000 CODEC System (TP3001 μ -Law, TP3002 A-Law)..... | 8-180 |
| LH0091 True RMS to DC Converter..... | 8-193 |
| LH0094 Multifunction Converter..... | 8-198 |

†For additional information, see National Semiconductor's Data Acquisition Handbook.

Section 9—Industrial/Automotive/Functional Blocks/ Telecommunications

| | |
|---|------|
| Definition of Terms..... | 9-iv |
| LM122/LM222/LM322, LM2905/LM3905 Precision Timers..... | 9-1 |
| LM134/LM234/LM334 3-Terminal Adjustable Current Sources..... | 9-13 |
| LM135/LM235/LM335, LM135A/LM235A/LM335A Precision Temperature Sensors..... | 9-21 |
| LM555/LM555C Timer..... | 9-29 |
| LM556/LM556C Dual Timer..... | 9-35 |
| LM565/LM565C Phase Locked Loop..... | 9-38 |
| LM566/LM566C Voltage Controlled Oscillator..... | 9-43 |

Table of Contents (Continued)

Section 9—Industrial/Automotive/Functional Blocks/ Telecommunications (Continued)

| | |
|--|-------|
| LM567/LM567C Tone Decoder..... | 9-46 |
| LM1014/LM1014A Motor Speed Regulator..... | 9-50 |
| LM1801 Smoke Detector..... | 9-54 |
| LM1812 Ultrasonic Transceiver..... | 9-58 |
| LM1815 Adaptive Sense Amplifier..... | 9-64 |
| LM1830 Fluid Detector..... | 9-67 |
| LM2877 Dual 4-Watt Power Audio Amplifier..... | 9-73 |
| LM2907, LM2917 Frequency to Voltage Converter..... | 9-79 |
| LM3080/LM3080A Operational Transconductance Amplifier..... | 9-92 |
| LM3909 LED Flasher/Oscillator..... | 9-96 |
| LM3911 Temperature Controller..... | 9-100 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| LM3915 Dot/Bar Display Driver..... | 9-120 |
| LM13600/LM13600A/LM11600A Dual Operational Transconductance Amplifiers With Linearizing Diodes and Buffers..... | 9-136 |

Section 10—Audio, Radio and TV Circuits

| | |
|--|---------|
| Audio Selection Guide..... | 10-iv |
| Definition of Terms..... | 10-viii |
| LM377 Dual 2 Watt Audio Amplifier..... | 10-1 |
| LM378 Dual 4 Watt Audio Amplifier..... | 10-6 |
| LM379 Dual 6 Watt Audio Amplifier..... | 10-10 |
| LM380 Audio Power Amplifier..... | 10-14 |
| LM381/LM381A Low Noise Dual Preamplifier..... | 10-18 |
| LM382 Low Noise Dual Preamplifier..... | 10-21 |
| LM383/LM383A 8 Watt Audio Power Amplifier..... | 10-24 |
| LM384 5 Watt Audio Power Amplifier..... | 10-28 |
| LM386 Low Voltage Audio Power Amplifier..... | 10-32 |
| LM387/LM387A Low Noise Dual Preamplifier..... | 10-36 |
| LM388 1.5 Watt Audio Power Amplifier..... | 10-39 |
| LM389 Low Voltage Audio Power Amplifier With NPN Transistor Array..... | 10-44 |
| LM390 1 Watt Battery Operated Audio Power Amplifier..... | 10-51 |
| LM391 Audio Power Driver..... | 10-56 |
| LM1011, LM1011A Dolby B-Type Noise Reduction Processor..... | 10-67 |
| LM1017 4-Bit Binary 7-Segment Decoder/Driver..... | 10-70 |
| LM1019N Digital Tuning Station Detector..... | 10-74 |
| LM1303 Stereo Preamplifier..... | 10-77 |
| LM1310 Phase-Locked Loop FM Stereo Demodulator..... | 10-79 |
| LM1391 Phase-Locked Loop Block..... | 10-81 |
| LM1596/LM1496 Balanced Modulator-Demodulator..... | 10-84 |
| LM1800 Phase-Locked Loop FM Stereo Demodulator..... | 10-88 |
| LM1818 Electronically Switched Audio Tape System..... | 10-90 |
| LM1828, LM1848 Color Television Chroma Demodulator..... | 10-99 |
| LM1870 Stereo Demodulator With Band..... | 10-102 |
| LM1877 Dual Power Audio Amplifier..... | 10-108 |
| LM1880 No-Holds Vertical/Horizontal..... | 10-113 |
| LM1886 TV Video Matrix D to A..... | 10-120 |
| LM1889 TV Video Modulator..... | 10-125 |
| LM1896/LM2896 Dual Power Audio Amplifier..... | 10-134 |
| LM2000 Audio Driver..... | 10-141 |
| LM2001 Low Voltage Audio Driver..... | 10-147 |

Table of Contents (Continued)

Section 10—Audio, Radio and TV Circuits (Continued)

| | |
|--|--------|
| LM2002/LM2002A 8 Watt Audio Power Amplifier..... | 10-152 |
| LM2808 Monolithic TV Sound System..... | 10-156 |
| LM3011 Wide Band Amplifier..... | 10-160 |
| LM3064 Television Automatic Fine Tuning..... | 10-162 |
| LM3075 FM Detector/Limiter and Audio Preamplifier..... | 10-164 |
| LM3089 FM Receiver IF System..... | 10-166 |
| LM3189 FM Receiver IF System..... | 10-170 |
| LM3820 AM Radio System..... | 10-176 |
| LM4500A High Fidelity FM Stereo Blend Demodulator..... | 10-180 |
| TBA120S IF Amplifier and Detector..... | 10-181 |
| TBA120U/TBA120T IF Amplifier and Detector..... | 10-184 |
| TBA440C Monolithic Video IF Amplifier..... | 10-188 |
| TBA510 Chrominance Combination..... | 10-190 |
| TBA530 RGB Matrix Preamplifier..... | 10-194 |
| TBA540 Reference Combination..... | 10-197 |
| TBA560C Luminance and Chrominance Control Combination..... | 10-201 |
| TBA920/TBA920S Line Oscillator Combination..... | 10-205 |
| TBA950-2 Television Signal Processing Circuit..... | 10-208 |
| TBA970 Television Video Amplifier..... | 10-212 |
| TBA990 Color Demodulator..... | 10-215 |
| TDA440 Video IF Amplifier..... | 10-217 |
| TDA2522 Color Demodulation Combination..... | 10-221 |
| TDA2530, TDA2531 R-G-B Matrix Preamplifiers With Clamps..... | 10-223 |
| TDA2560 Luminance and Chrominance Control Combination..... | 10-226 |
| TDA2590 Line Oscillator Combination..... | 10-229 |

Section 11—Transistor/Diode Arrays

| | |
|---|--------|
| Transistor/Diode Arrays Selection Guide..... | 11-iii |
| LM194/LM394 Supermatch Pair..... | 11-1 |
| LM195/LM295/LM395 Ultra Reliable Power Transistors..... | 11-7 |
| LM3045, LM3046, LM3086 Transistor Arrays..... | 11-15 |
| LM3146 High Voltage Transistor Array..... | 11-20 |

Section 12—Appendices/Physical Dimensions

| | |
|---|-------|
| National A+ and B+ Extended Quality and Reliability Programs for Linear Circuits..... | 12-1 |
| MIL-STD-883/MIL-M-38510..... | 12-6 |
| Linear Cross Reference Guide..... | 12-7 |
| Industry Package Cross Reference Guide..... | 12-11 |
| Physical Dimensions..... | 12-13 |

For additional information on Linear Products, see National Semiconductor's Linear Applications Handbook.

Alpha-Numerical Index

| | |
|---|-------|
| AD7520 10-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7521 12-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7530 10-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7531 12-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7533 10-Bit Binary Multiplying D/A Converter..... | 8-1 |
| ADB1200 (MM5863) 12-Bit Binary A/D Building Block..... | 8-3 |
| ADC0800 (MM4357B/MM5357B) 8-Bit A/D Converter..... | 8-10 |
| ADC0801 8-Bit μ P Compatible A/D Converter..... | 8-21 |
| ADC0802 8-Bit μ P Compatible A/D Converter..... | 8-21 |
| ADC0803 8-Bit μ P Compatible A/D Converter..... | 8-21 |
| ADC0804 8-Bit μ P Compatible A/D Converter..... | 8-21 |
| ADC0808 8-Bit μ P Compatible A/D Converter with 8-Channel Multiplexer..... | 8-45 |
| ADC0809 8-Bit μ P Compatible A/D Converter with 8-Channel Multiplexer..... | 8-45 |
| ADC0816 8-Bit μ P Compatible A/D Converter with 16-Channel Multiplexer..... | 8-56 |
| ADC0817 8-Bit μ P Compatible A/D Converter with 16-Channel Multiplexer..... | 8-56 |
| ADC1210 12-Bit CMOS A/D Converter..... | 8-67 |
| ADC1211 12-Bit CMOS A/D Converter..... | 8-67 |
| DAC0800 (LMDAC08) 8-Bit Digital-to-Analog Converter..... | 8-77 |
| DAC0806 8-Bit D/A Converter..... | 8-85 |
| DAC0807 8-Bit D/A Converter..... | 8-85 |
| DAC0808 8-Bit D/A Converter..... | 8-85 |
| DAC1000 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1001 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1002 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1003 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1004 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1005 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1006 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1007 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1008 10-Bit, μ P Compatible, Double-Buffered D to A Converter..... | 8-92 |
| DAC1020 10-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1200 12-Bit (Binary) Digital-to-Analog Converter..... | 8-124 |
| DAC1201 12-Bit (Binary) Digital-to-Analog Converter..... | 8-124 |
| DAC1202 3-Digit (BCD) Digital-to-Analog Converter..... | 8-124 |
| DAC1203 3-Digit (BCD) Digital-to-Analog Converter..... | 8-124 |
| DAC1220 12-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1280 12-Bit (Binary) Digital-to-Analog Converter..... | 8-131 |
| DAC1285 12-Bit (Binary) Digital-to-Analog Converter..... | 8-131 |
| DAC1286 3-Digit (BCD) Digital-to-Analog Converter..... | 8-131 |
| DAC1287 3-Digit (BCD) Digital-to-Analog Converter..... | 8-131 |
| DM2502 Successive Approximation Register..... | 8-139 |
| DM2503 Successive Approximation Register..... | 8-139 |
| DM2504 Successive Approximation Register..... | 8-139 |
| LF111 Voltage Comparators..... | 5-1 |
| LF152 FET Input Instrumentation Amplifier..... | 4-1 |
| LF155 Series Monolithic JFET Input Operational Amplifiers..... | 3-1 |
| LF156 Series Monolithic JFET Input Operational Amplifiers..... | 3-1 |
| LF157 Series Monolithic JFET Input Operational Amplifiers..... | 3-1 |
| LF198 Monolithic Sample and Hold Circuit..... | 7-1 |
| LF198A Monolithic Sample and Hold Circuit..... | 7-1 |
| LF211 Voltage Comparator..... | 5-1 |
| LF298 Monolithic Sample and Hold Circuit..... | 7-1 |
| LF311 Voltage Comparator..... | 5-1 |
| LF347 Wide Bandwidth Quad JFET Input Operational Amplifier..... | 3-14 |

Alpha-Numerical Index (Continued)

| | |
|---|-------|
| LF351 Wide Bandwidth JFET Input Operational Amplifier..... | 3-22 |
| LF352 FET Input Instrumentation Amplifier..... | 4-1 |
| LF353 Wide Bandwidth Dual JFET Input Operational Amplifier..... | 3-29 |
| LF398 Monolithic Sample and Hold Circuit..... | 7-1 |
| LF398A Monolithic Sample and Hold Circuit..... | 7-1 |
| LF11201 4 Normally Closed Switches..... | 6-1 |
| LF11202 4 Normally Open Switches..... | 6-1 |
| LF11331 4 Normally Open Switches With Disable..... | 6-1 |
| LF11332 4 Normally Closed Switches With Disable..... | 6-1 |
| LF11333 2 Normally Closed Switches and 2 Normally Open Switches With Disable..... | 6-1 |
| LF11508 8-Channel Analog Multiplexer..... | 6-11 |
| LF11509 4-Channel Differential Analog Multiplexer..... | 6-11 |
| LF13201 4 Normally Closed Switches..... | 6-1 |
| LF13202 4 Normally Open Switches..... | 6-1 |
| LF13300 Integrating A/D Analog Building Block..... | 8-144 |
| LF13331 4 Normally Open Switches With Disable..... | 6-1 |
| LF13332 4 Normally Closed Switches With Disable..... | 6-1 |
| LF13333 2 Normally Closed Switches and 2 Normally Open Switches With Disable..... | 6-1 |
| LF13741 Monolithic JFET Input Operational Amplifier..... | 3-38 |
| LH0002 Current Amplifier..... | 3-238 |
| LH0002C Current Amplifier..... | 3-238 |
| LH0021 1.0 Amp Power Operational Amplifier..... | 3-241 |
| LH0021C 1.0 Amp Power Operational Amplifier..... | 3-241 |
| LH0022 High Performance FET Op Amp..... | 3-248 |
| LH0022C High Performance FET Op Amp..... | 3-248 |
| LH0024 High Slew Rate Operational Amplifier..... | 3-255 |
| LH0024C High Slew Rate Operational Amplifier..... | 3-255 |
| LH0032 Ultra Fast FET Operational Amplifier..... | 3-258 |
| LH0032C Ultra Fast FET Operational Amplifier..... | 3-258 |
| LH0033 Fast and Damn Fast Buffer Amplifier..... | 3-263 |
| LH0033C Fast and Damn Fast Buffer Amplifier..... | 3-263 |
| LH0036 Instrumentation Amplifier..... | 4-19 |
| LH0036C Instrumentation Amplifier..... | 4-19 |
| LH0038 True Instrumentation Amplifier..... | 4-27 |
| LH0038C True Instrumentation Amplifier..... | 4-27 |
| LH0041 0.2 Amp Power Operational Amplifier..... | 3-241 |
| LH0041C 0.2 Amp Power Operational Amplifier..... | 3-241 |
| LH0042 Low Cost FET Op Amp..... | 3-248 |
| LH0042C Low Cost FET Op Amp..... | 3-248 |
| LH0044 Series Precision Low Noise Operational Amplifiers..... | 3-274 |
| LH0045 Two Wire Transmitter..... | 3-280 |
| LH0045C Two Wire Transmitter..... | 3-280 |
| LH0052 Precision FET Op Amp..... | 3-248 |
| LH0052C Precision FET Op Amp..... | 3-248 |
| LH0061 0.5 Amp Wide Band Operational Amplifier..... | 3-291 |
| LH0061C 0.5 Amp Wide Band Operational Amplifier..... | 3-291 |
| LH0062 High Speed FET Operational Amplifier..... | 3-294 |
| LH0062C High Speed FET Operational Amplifier..... | 3-294 |
| LH0063 Fast and Damn Fast Buffer Amplifier..... | 3-263 |
| LH0063C Fast and Damn Fast Buffer Amplifier..... | 3-263 |
| LH0070 Series Precision BCD Buffered Reference..... | 2-1 |
| LH0071 Series Precision Binary Buffered Reference..... | 2-1 |
| LH0075 Positive Precision Programmable Regulator..... | 2-5 |
| LH0076 Negative Precision Programmable Regulator..... | 2-10 |
| LH0084 Digitally Programmable Gain Instrumentation Amplifier..... | 4-38 |

Alpha-Numerical Index (Continued)

| | |
|--|-------|
| LH0084C Digitally Programmable Gain Instrumentation Amplifier..... | 4-38 |
| LH0091 True RMS to DC Converter..... | 8-193 |
| LH0094 Multifunction Converter..... | 8-198 |
| LH2101A Dual High Performance Op Amp..... | 3-72 |
| LH2108 Dual Super Beta Op Amp..... | 3-93 |
| LH2108A Dual Super Beta Op Amp..... | 3-93 |
| LH2110 Dual Voltage Follower..... | 3-300 |
| LH2111 Dual Voltage Comparator..... | 5-7 |
| LH2201A Dual High Performance Op Amp..... | 3-72 |
| LH2208 Dual Super Beta Op Amp..... | 3-93 |
| LH2208A Dual Super Beta Op Amp..... | 3-93 |
| LH2210 Dual Voltage Follower..... | 3-300 |
| LH2211 Dual Voltage Comparator..... | 5-7 |
| LH2301A Dual High Performance Op Amp..... | 3-72 |
| LH2308 Dual Super Beta Op Amp..... | 3-93 |
| LH2308A Dual Super Beta Op Amp..... | 3-93 |
| LH2310 Dual Voltage Follower..... | 3-300 |
| LH2311 Dual Voltage Comparator..... | 5-7 |
| LH24250 Dual Programmable Micropower Op Amp..... | 3-229 |
| LH24250C Dual Programmable Micropower Op Amp..... | 3-229 |
| LM10 Op Amp and Voltage Reference..... | 3-49 |
| LM10B(L) Op Amp and Voltage Reference..... | 3-49 |
| LM10C(L) Op Amp and Voltage Reference..... | 3-49 |
| LM101A Operational Amplifier..... | 3-65 |
| LM102 Voltage Follower..... | 3-74 |
| LM103 Reference Diode..... | 2-15 |
| LM104 Negative Regulator..... | 1-2 |
| LM105 Voltage Regulator..... | 1-5 |
| LM106 Voltage Comparator..... | 5-9 |
| LM107 Operational Amplifier..... | 3-79 |
| LM108 Operational Amplifier..... | 3-83 |
| LM108A Operational Amplifier..... | 3-88 |
| LM109 5-Volt Regulator..... | 1-10 |
| LM110 Voltage Follower..... | 3-95 |
| LM111 Voltage Comparator..... | 5-12 |
| LM112 Operational Amplifier..... | 3-102 |
| LM113 Reference Diode..... | 2-18 |
| LM117 3-Terminal Adjustable Regulator..... | 1-15 |
| LM117HV High Voltage 3-Terminal Adjustable Regulator..... | 1-23 |
| LM118 Operational Amplifier..... | 3-106 |
| LM119 High Speed Dual Comparator..... | 5-18 |
| LM120 Series 3-Terminal Negative Regulators..... | 1-31 |
| LM121 Precision Preamplifier..... | 4-11 |
| LM121A Precision Preamplifier..... | 4-11 |
| LM122 Precision Timer..... | 9-1 |
| LM123 3 Amp, 5 Volt Positive Regulator..... | 1-39 |
| LM124 Low Power Quad Operational Amplifier..... | 3-113 |
| LM124A Low Power Quad Operational Amplifier..... | 3-113 |
| LM125 Voltage Regulator..... | 1-43 |
| LM126 Voltage Regulator..... | 1-43 |
| LM129 Precision Reference..... | 2-21 |
| LM130 3-Terminal Positive Regulator..... | 1-50 |
| LM131 Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM131A Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM134 3-Terminal Adjustable Current Source..... | 9-13 |

Alpha-Numerical Index (Continued)

| | |
|---|-------|
| LM135 Precision Temperature Sensor..... | 9-21 |
| LM135A Precision Temperature Sensor..... | 9-21 |
| LM136 2.5V Reference Diode..... | 2-26 |
| LM137 3-Terminal Adjustable Negative Regulators..... | 1-56 |
| LM137HV 3-Terminal Adjustable Negative Regulator (High Voltage)..... | 1-61 |
| LM138 5 Amp Adjustable Power Regulators..... | 1-66 |
| LM139 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM139A Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM140 Series 3-Terminal Positive Regulators..... | 1-74 |
| LM140A Series 3-Terminal Positive Regulators..... | 1-74 |
| LM140L Series 3-Terminal Positive Regulators..... | 1-82 |
| LM143 High Voltage Operational Amplifier..... | 3-122 |
| LM144 High Voltage, High Slew Rate Operational Amplifier..... | 3-129 |
| LM145 Negative Three Amp Regulator..... | 1-85 |
| LM146 Programmable Quad Operational Amplifier..... | 3-135 |
| LM148 Series Quad 741 Op Amps..... | 3-147 |
| LM149 Series Quad 741 Op Amps..... | 3-147 |
| LM150 3 Amp Adjustable Power Regulator..... | 1-89 |
| LM158 Low Power Dual Operational Amplifier..... | 3-157 |
| LM158A Low Power Dual Operational Amplifier..... | 3-157 |
| LM159 Dual, High Speed, Programmable Current Mode (Norton) Amplifier..... | 3-167 |
| LM160 High Speed Differential Comparator..... | 5-31 |
| LM161 High Speed Differential Comparator..... | 5-34 |
| LM185 Voltage Reference Diode..... | 2-32 |
| LM192 Low Power Operational Amplifier/Voltage Comparator..... | 3-183 |
| LM193 Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM193A Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM194 Supermatch Pair..... | 11-1 |
| LM195 Ultra Reliable Power Transistor..... | 11-7 |
| LM199 Precision Reference..... | 2-38 |
| LM199A Precision Reference..... | 2-44 |
| LM201A Operational Amplifier..... | 3-65 |
| LM202 Voltage Follower..... | 3-74 |
| LM204 Negative Regulator..... | 1-2 |
| LM205 Voltage Regulator..... | 1-5 |
| LM206 Voltage Comparator..... | 5-9 |
| LM207 Operational Amplifier..... | 3-79 |
| LM208 Operational Amplifier..... | 3-83 |
| LM208A Operational Amplifier..... | 3-88 |
| LM209 5-Volt Regulator..... | 1-10 |
| LM210 Voltage Follower..... | 3-95 |
| LM211 Voltage Comparator..... | 5-12 |
| LM212 Operational Amplifier..... | 3-102 |
| LM216 Operational Amplifier..... | 3-187 |
| LM216A Operational Amplifier..... | 3-187 |
| LM217 3-Terminal Adjustable Regulator..... | 1-15 |
| LM217HV High Voltage 3-Terminal Adjustable Regulator..... | 1-23 |
| LM218 Operational Amplifier..... | 3-106 |
| LM219 High Speed Dual Comparator..... | 5-18 |
| LM221 Precision Preamplifier..... | 4-11 |
| LM221A Precision Preamplifier..... | 4-11 |
| LM222 Precision Timer..... | 9-1 |
| LM223 3 Amp, 5 Volt Positive Regulator..... | 1-39 |
| LM224 Low Power Quad Operational Amplifier..... | 3-113 |
| LM224A Low Power Quad Operational Amplifier..... | 3-113 |

Alpha-Numerical Index (Continued)

| | |
|--|-------|
| LM231 Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM231A Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM234 3-Terminal Adjustable Current Source..... | 9-13 |
| LM235 Precision Temperature Sensor..... | 9-21 |
| LM235A Precision Temperature Sensor..... | 9-21 |
| LM236 2.5V Reference Diode..... | 2-26 |
| LM237 3-Terminal Adjustable Negative Regulator..... | 1-56 |
| LM237HV 3-Terminal Adjustable Negative Regulator (High Voltage)..... | 1-61 |
| LM238 5 Amp Adjustable Power Regulator..... | 1-66 |
| LM239 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM239A Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM245 Negative Three Amp Regulator..... | 1-85 |
| LM246 Programmable Quad Operational Amplifier..... | 3-135 |
| LM250 3 Amp Adjustable Power Regulator..... | 1-89 |
| LM258 Low Power Dual Operational Amplifier..... | 3-157 |
| LM258A Low Power Dual Operational Amplifier..... | 3-157 |
| LM260 High Speed Differential Comparator..... | 5-31 |
| LM261 High Speed Differential Comparator..... | 5-34 |
| LM285 Voltage Reference Diode..... | 2-32 |
| LM292 Low Power Operational Amplifier/Voltage Comparator..... | 3-183 |
| LM293 Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM293A Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM295 Ultra Reliable Power Transistor..... | 11-7 |
| LM299 Precision Reference..... | 2-38 |
| LM299A Precision Reference..... | 2-44 |
| LM301A Operational Amplifier..... | 3-65 |
| LM302 Voltage Follower..... | 3-74 |
| LM304 Negative Regulator..... | 1-2 |
| LM305 Voltage Regulator..... | 1-5 |
| LM305A Voltage Regulator..... | 1-5 |
| LM306 Voltage Comparator..... | 5-9 |
| LM307 Operational Amplifier..... | 3-79 |
| LM308 Operational Amplifier..... | 3-83 |
| LM308A Operational Amplifier..... | 3-88 |
| LM308A-1 Operational Amplifier..... | 3-88 |
| LM308A-2 Operational Amplifier..... | 3-88 |
| LM309 5-Volt Regulator..... | 1-10 |
| LM310 Voltage Follower..... | 3-95 |
| LM311 Voltage Comparator..... | 5-44 |
| LM312 Operational Amplifier..... | 3-102 |
| LM313 Reference Diode..... | 2-18 |
| LM316 Operational Amplifier..... | 3-187 |
| LM316A Operational Amplifier..... | 3-187 |
| LM317 3-Terminal Adjustable Regulator..... | 1-15 |
| LM317HV High Voltage 3-Terminal Adjustable Regulator..... | 1-23 |
| LM318 Operational Amplifier..... | 3-106 |
| LM319 High Speed Dual Comparator..... | 5-18 |
| LM320L Series 3-Terminal Negative Regulators..... | 1-97 |
| LM320ML Series 3-Terminal Negative Regulators..... | 1-97 |
| LM321 Precision Preamplifier..... | 4-11 |
| LM321A Precision Preamplifier..... | 4-11 |
| LM322 Precision Timer..... | 9-1 |
| LM323 3 Amp, 5 Volt Positive Regulator..... | 1-39 |
| LM324 Low Power Quad Operational Amplifier..... | 3-113 |
| LM324A Low Power Quad Operational Amplifier..... | 3-113 |

Alpha-Numerical Index (Continued)

| | |
|---|-------|
| LM325 Voltage Regulator..... | 1-43 |
| LM325A Voltage Regulator..... | 1-43 |
| LM326 Voltage Regulator..... | 1-43 |
| LM329 Precision Reference..... | 2-21 |
| LM330 3-Terminal Positive Regulator..... | 1-50 |
| LM331 Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM331A Precision Voltage-to-Frequency Converter..... | 8-162 |
| LM334 3-Terminal Adjustable Current Source..... | 9-13 |
| LM335 Precision Temperature Sensor..... | 9-21 |
| LM335A Precision Temperature Sensor..... | 9-21 |
| LM336 2.5V Reference Diode..... | 2-26 |
| LM337 3-Terminal Adjustable Negative Regulator..... | 1-56 |
| LM337HV 3-Terminal Adjustable Negative Regulator (High Voltage)..... | 1-61 |
| LM338 5 Amp Adjustable Power Regulator..... | 1-66 |
| LM339 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM339A Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM340 Series 3-Terminal Positive Regulators..... | 1-74 |
| LM340A Series 3-Terminal Positive Regulators..... | 1-74 |
| LM340L Series 3-Terminal Positive Regulators..... | 1-82 |
| LM341 Series 3-Terminal Positive Regulators..... | 1-103 |
| LM342 Series 3-Terminal Positive Regulators..... | 1-106 |
| LM343 High Voltage Operational Amplifier..... | 3-122 |
| LM344 High Voltage, High Slew Rate Operational Amplifier..... | 3-129 |
| LM345 Negative Three Amp Regulator..... | 1-85 |
| LM346 Programmable Quad Operational Amplifier..... | 3-135 |
| LM350 3 Amp Adjustable Power Regulator..... | 1-89 |
| LM358 Low Power Dual Operational Amplifier..... | 3-157 |
| LM358A Low Power Dual Operational Amplifier..... | 3-157 |
| LM359 Dual, High Speed, Programmable Current Mode (Norton) Amplifiers..... | 3-167 |
| LM360 High Speed Differential Comparator..... | 5-31 |
| LM361 High Speed Differential Comparator..... | 5-34 |
| LM376 Voltage Regulator..... | 1-5 |
| LM377 Dual 2 Watt Audio Amplifier..... | 10-1 |
| LM378 Dual 4 Watt Audio Amplifier..... | 10-6 |
| LM379 Dual 6 Watt Audio Amplifier..... | 10-10 |
| LM380 Audio Power Amplifier..... | 10-14 |
| LM381 Low Noise Dual Preamplifier..... | 10-18 |
| LM381A Low Noise Dual Preamplifier..... | 10-18 |
| LM382 Low Noise Dual Preamplifier..... | 10-21 |
| LM383 8 Watt Audio Power Amplifier..... | 10-24 |
| LM383A 8 Watt Audio Power Amplifier..... | 10-24 |
| LM384 5 Watt Audio Power Amplifier..... | 10-28 |
| LM385 Voltage Reference Diode..... | 2-32 |
| LM386 Low Voltage Audio Power Amplifier..... | 10-32 |
| LM387 Low Noise Dual Preamplifier..... | 10-36 |
| LM387A Low Noise Dual Preamplifier..... | 10-36 |
| LM388 1.5 Watt Audio Power Amplifier..... | 10-39 |
| LM389 Low Voltage Audio Power Amplifier With NPN Transistor Array..... | 10-44 |
| LM390 1 Watt Battery Operated Audio Power Amplifier..... | 10-51 |
| LM391 Audio Power Driver..... | 10-56 |
| LM392 Low Power Operational Amplifier/Voltage Comparator..... | 3-183 |
| LM393 Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM393A Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM394 Supermatch Pair..... | 11-1 |

Alpha-Numerical Index (Continued)

| | |
|--|-------|
| LM395 Ultra Reliable Power Transistor..... | 11-7 |
| LM399 Precision Reference..... | 2-38 |
| LM399A Precision Reference..... | 2-44 |
| LM555 Timer..... | 9-29 |
| LM555C Timer..... | 9-29 |
| LM556 Dual Timer..... | 9-35 |
| LM556C Dual Timer..... | 9-35 |
| LM565 Phase Locked Loop..... | 9-38 |
| LM565C Phase Locked Loop..... | 9-38 |
| LM566 Voltage Controlled Oscillator..... | 9-43 |
| LM566C Voltage Controlled Oscillator..... | 9-43 |
| LM567 Tone Decoder..... | 9-46 |
| LM567C Tone Decoder..... | 9-46 |
| LM709 Operational Amplifier..... | 3-190 |
| LM709A Operational Amplifier..... | 3-190 |
| LM709C Operational Amplifier..... | 3-190 |
| LM710 Voltage Comparator..... | 5-52 |
| LM710C Voltage Comparator..... | 5-52 |
| LM711 Dual Comparator..... | 5-55 |
| LM711C Dual Comparator..... | 5-55 |
| LM723 Voltage Regulator..... | 1-110 |
| LM723C Voltage Regulator..... | 1-110 |
| LM725 (Instrumentation) Operational Amplifier..... | 3-194 |
| LM725A (Instrumentation) Operational Amplifier..... | 3-194 |
| LM725C (Instrumentation) Operational Amplifier..... | 3-194 |
| LM733 Differential Video Amp..... | 3-198 |
| LM733C Differential Video Amp..... | 3-198 |
| LM741 Operational Amplifier..... | 3-202 |
| LM741A Operational Amplifier..... | 3-202 |
| LM741C Operational Amplifier..... | 3-202 |
| LM741E Operational Amplifier..... | 3-202 |
| LM747 Dual Operational Amplifier..... | 3-205 |
| LM747A Dual Operational Amplifier..... | 3-205 |
| LM747C Dual Operational Amplifier..... | 3-205 |
| LM747E Dual Operational Amplifier..... | 3-205 |
| LM748 Operational Amplifier..... | 3-210 |
| LM748A Operational Amplifier..... | 3-210 |
| LM78XX Series Voltage Regulators..... | 1-136 |
| LM78LXX Series 3-Terminal Positive Regulators..... | 1-139 |
| LM78MXX Series 3-Terminal Positive Regulators..... | 1-145 |
| LM79XX Series 3-Terminal Negative Regulators..... | 1-148 |
| LM79LXXAC Series 3-Terminal Negative Regulators..... | 1-153 |
| LM79MXX Series 3-Terminal Negative Regulators..... | 1-157 |
| LM1011 Dolby B-Type Noise Reduction Processor..... | 10-67 |
| LM1011A Dolby B-Type Noise Reduction Processor..... | 10-67 |
| LM1014 Motor Speed Regulator..... | 9-50 |
| LM1014A Motor Speed Regulator..... | 9-50 |
| LM1017 4-Bit Binary 7-Segment Decoder/Driver..... | 10-70 |
| LM1019N Digital Tuning Station Detector..... | 10-74 |
| LM1303 Stereo Preamplifier..... | 10-77 |
| LM1310 Phase Locked Loop FM Stereo Demodulator..... | 10-79 |
| LM1391 Phase Locked Loop Block..... | 10-81 |
| LM1408 8-Bit D/A Converter..... | 8-173 |
| LM1414 Dual Differential Voltage Comparator..... | 5-58 |
| LM1458 Dual Operational Amplifier..... | 3-213 |

Alpha-Numerical Index (Continued)

| | |
|--|--------|
| LM1496 Balanced Modulator-Demodulator..... | 10-84 |
| LM1508 8-Bit D/A Converter..... | 8-173 |
| LM1514 Dual Differential Voltage Comparator..... | 5-58 |
| LM1524 Regulating Pulse Width Modulator..... | 1-115 |
| LM1558 Dual Operational Amplifier..... | 3-213 |
| LM1596 Balanced Modulator-Demodulator..... | 10-84 |
| LM1800 Phase Locked Loop FM Stereo Demodulator..... | 10-88 |
| LM1801 Smoke Detector..... | 9-54 |
| LM1812 Ultrasonic Transceiver..... | 9-58 |
| LM1815 Adaptive Sense Amplifier..... | 9-64 |
| LM1818 Electronically Switched Audio Tape System..... | 10-90 |
| LM1828 Color Television Chroma Demodulator..... | 10-99 |
| LM1830 Fluid Detector..... | 9-67 |
| LM1848 Color Television Chroma Demodulator..... | 10-99 |
| LM1870 Stereo Demodulator with Blend..... | 10-102 |
| LM1877 Dual Power Audio Amplifier..... | 10-108 |
| LM1880 No-Holds Vertical/Horizontal..... | 10-113 |
| LM1886 TV Video Matrix D to A..... | 10-120 |
| LM1889 TV Video Modulator..... | 10-125 |
| LM1896/LM2896 Dual Power Audio Amplifier..... | 10-134 |
| LM2000 Low Voltage Audio Driver..... | 10-141 |
| LM2001 Low Voltage Audio Driver..... | 10-147 |
| LM2002 8-Watt Audio Power Amplifier..... | 10-152 |
| LM2002A 8-Watt Audio Power Amplifier..... | 10-152 |
| LM2524 Regulating Pulse Width Modulator..... | 1-115 |
| LM2808 Monolithic TV Sound System..... | 10-156 |
| LM2877 Dual 4-Watt Power Audio Amplifier..... | 9-73 |
| LM2900 Quad Amplifier..... | 3-215 |
| LM2901 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM2902 Low Power Quad Operational Amplifier..... | 3-113 |
| LM2903 Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM2904 Low Power Dual Operational Amplifier..... | 3-157 |
| LM2905 Precision Timer..... | 9-1 |
| LM2907 Frequency to Voltage Converter..... | 9-79 |
| LM2917 Frequency to Voltage Converter..... | 9-79 |
| LM2924 Low Power Operational Amplifier/Voltage Comparator..... | 3-183 |
| LM2930 3-Terminal Positive Regulator..... | 1-130 |
| LM3011 Wide Band Amplifier..... | 10-160 |
| LM3045 Transistor Array..... | 11-15 |
| LM3046 Transistor Array..... | 11-15 |
| LM3064 Television Automatic Fine Tuning..... | 10-162 |
| LM3075 FM Detector/Limiter and Audio Preamplifier..... | 10-164 |
| LM3080 Operational Transconductance Amplifier..... | 9-92 |
| LM3080A Operational Transconductance Amplifier..... | 9-92 |
| LM3086 Transistor Array..... | 11-15 |
| LM3089 FM Receiver IF System..... | 10-166 |
| LM3146 High Voltage Transistor Array..... | 11-20 |
| LM3189 FM Receiver IF System..... | 10-170 |
| LM3301 Quad Amplifier..... | 3-215 |
| LM3302 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM3401 Quad Amplifier..... | 3-215 |
| LM3524 Regulating Pulse Width Modulator..... | 1-115 |
| LM3820 AM Radio System..... | 10-176 |
| LM3900 Quad Amplifier..... | 3-215 |
| LM3905 Precision Timer..... | 9-1 |

Alpha-Numerical Index (Continued)

| | |
|--|--------|
| LM3909 LED Flasher/Oscillator..... | 9-96 |
| LM3911 Temperature Controller..... | 9-100 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| LM3915 Dot/Bar Display Driver..... | 9-120 |
| LM3999 Precision Reference..... | 2-47 |
| LM4250 Programmable Operational Amplifier..... | 3-224 |
| LM4250C Programmable Operational Amplifier..... | 3-224 |
| LM4500A High Fidelity FM Stereo Blend Demodulator..... | 10-180 |
| LM11600A Dual Operational Transconductance Amplifier With Linearizing Diodes and Buffers..... | 9-136 |
| LM13080 Programmable Power Op Amp..... | 3-231 |
| LM13600 Dual Operational Transconductance Amplifier With Linearizing Diodes and Buffers..... | 9-136 |
| LM13600A Dual Operational Transconductance Amplifier With Linearizing Diodes and Buffers..... | 9-136 |
| MM54C905 12-Bit Successive Approximation Register..... | 8-175 |
| MM74C905 12-Bit Successive Approximation Register..... | 8-175 |
| TBA120S IF Amplifier and Detector..... | 10-181 |
| TBA120T IF Amplifier and Detector..... | 10-184 |
| TBA120U IF Amplifier and Detector..... | 10-184 |
| TBA440C Monolithic Video IF Amplifier..... | 10-188 |
| TBA510 Chrominance Combination..... | 10-190 |
| TBA530 RGB Matrix Preamplifier..... | 10-194 |
| TBA540 Reference Combination..... | 10-197 |
| TBA560C Luminance and Chrominance Control Combination..... | 10-201 |
| TBA920 Line Oscillator Combination..... | 10-205 |
| TBA920S Line Oscillator Combination..... | 10-205 |
| TBA950-2 Television Signal Processing Circuit..... | 10-208 |
| TBA970 Television Video Amplifier..... | 10-212 |
| TBA990 Color Demodulator..... | 10-215 |
| TDA440 Video IF Amplifier..... | 10-217 |
| TDA2522 Color Demodulation Combination..... | 10-221 |
| TDA2530 R-G-B Matrix Preamplifier With Clamps..... | 10-223 |
| TDA2531 R-G-B Matrix Preamplifier With Clamps..... | 10-223 |
| TDA2560 Luminance and Chrominance Control Combination..... | 10-226 |
| TDA2590 Line Oscillator Combination..... | 10-229 |
| TP3000 CODEC System..... | 8-180 |
| TP3001 μ -Law..... | 8-180 |
| TP3002 A-Law..... | 8-180 |



Section 1

Voltage Regulators

1



Section Contents

| | |
|--|--------|
| Voltage Regulator Guide..... | 1-iii |
| Precision Regulator Guide..... | 1-vii |
| Definition of Terms..... | 1-viii |
| Fixed or Adjustable Voltage Regulators..... | 1-1 |
| Positive 3-Terminal Fixed | |
| LM109/LM209/LM309 5-Volt Regulator..... | 1-10 |
| LM123/LM223/LM323 3 Amp, 5 Volt Positive Regulator..... | 1-39 |
| LM130/LM330 3-Terminal Positive Regulators..... | 1-50 |
| LM140A/LM140/LM340A/LM340 Series 3-Terminal Positive Regulators..... | 1-74 |
| LM140L/LM340L Series 3-Terminal Positive Regulators..... | 1-82 |
| LM341 Series 3-Terminal Positive Regulators..... | 1-103 |
| LM342 Series 3-Terminal Positive Regulators..... | 1-106 |
| LM2930 3-Terminal Positive Regulator..... | 1-130 |
| LM78XX Series Voltage Regulators..... | 1-136 |
| LM78LXX Series 3-Terminal Positive Regulators..... | 1-139 |
| *LM78MXX Series 3-Terminal Positive Regulators..... | 1-145 |
| Positive 3-Terminal Adjustable | |
| LM117/LM217/LM317 3-Terminal Adjustable Regulator..... | 1-15 |
| LM117HV/LM217HV/LM317HV High Voltage 3-Terminal Adjustable Regulator..... | 1-23 |
| LM138/LM238/LM338 5 Amp Adjustable Power Regulators..... | 1-66 |
| LM150/LM250/LM350 3 Amp Adjustable Power Regulators..... | 1-89 |
| Positive Multi-Terminal Adjustable | |
| LM105/LM205/LM305/LM305A, LM376 Voltage Regulators..... | 1-5 |
| LM723/LM723C Voltage Regulator..... | 1-110 |
| Negative 3-Terminal Fixed | |
| LM120 Series 3-Terminal Negative Regulators..... | 1-31 |
| LM145/LM245/LM345 Negative Three Amp Regulator..... | 1-85 |
| LM320L/LM320ML Series 3-Terminal Negative Regulators..... | 1-97 |
| LM79XX Series 3-Terminal Negative Regulators..... | 1-148 |
| LM79LXXAC Series 3-Terminal Negative Regulators..... | 1-153 |
| LM79MXX Series 3-Terminal Negative Regulators..... | 1-157 |
| Negative 3-Terminal Adjustable | |
| LM137/LM237/LM337 3-Terminal Adjustable Negative Regulators..... | 1-56 |
| LM137HV/LM237HV/LM337HV 3-Terminal Adjustable Negative Regulators (High Voltage)..... | 1-61 |
| Negative Multi-Terminal Adjustable | |
| LM104/LM204/LM304 Negative Regulator..... | 1-2 |
| LM723/LM723C Voltage Regulator..... | 1-110 |
| Dual Tracking | |
| LM125/LM325/LM325A Voltage Regulators..... | 1-43 |
| LM126/LM326 Voltage Regulators..... | 1-43 |
| Switching | |
| LM104/LM204/LM304 Negative Regulator..... | 1-2 |
| LM723/LM723C Voltage Regulator..... | 1-110 |
| LM1524/LM2524/LM3524 Regulating Pulse Width Modulator..... | 1-115 |

† For more information See National Semiconductor's Voltage Regulator Handbook.

3-TERMINAL POSITIVE VOLTAGE REGULATORS

| Output Current (A) | Device | Available V _{OUT} (V) | V _{OUT} Tol. (±%) | Regulation | | V _{IN} (V) Max | Ripple Rejection (dB) | |
|--------------------|------------------|--------------------------------|----------------------------|--|--|-------------------------|-----------------------|----|
| | | | | Line (Note 1) % V _{OUT} /V _{IN} | Load (Note 2) % V _{OUT} /V _{IN} | | | |
| 5 | LM138, LM238 | 1.2 to 32 (Adjustable) | N/A | 0.005 | 0.1 | 35 | 86 | |
| | LM338 | 1.2 to 32 (Adjustable) | N/A | 0.005 | 0.1 | 35 | 86 | |
| 3 | LM150, LM250 | 1.2 to 32 (Adjustable) | N/A | 0.005 | 0.1 | 35 | 86 | |
| | LM350 | 1.2 to 32 (Adjustable) | N/A | 0.005 | 0.1 | 35 | 86 | |
| | LM123K, LM223K | 5 | 6 | 0.01 | 0.5 | 20 | 75 | |
| | LM323K | 5 | 4 | 0.01 | 0.5 | 20 | 75 | |
| 1.5 | LM117, LM217 | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 | |
| | LM317 | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 | |
| | LM117HV, LM217HV | 1.2 to 57 (Adjustable) | N/A | 0.01 | 0.1 | 60 | 80 | |
| | LM317HV | 1.2 to 57 (Adjustable) | N/A | 0.01 | 0.1 | 60 | 80 | |
| | LM109K, LM209K | 5 | 6 | 0.004 | 1.0 | 35 | 80 | |
| | LM309K | 5 | 4 | 0.004 | 1.0 | 35 | 80 | |
| | LM140K | 5, 12, 15 | 4 | 0.02 | 0.5 | 35 | 66-80 | |
| | LM140AK | 5, 12, 15 | 2 | 0.002 | 0.1 | 35 | 66-80 | |
| | LM340 | 5, 12, 15 | 4 | 0.02 | 0.5 | 35 | 66-80 | |
| | LM340A | 5, 12, 15 | 2 | 0.002 | 0.1 | 35 | 66-80 | |
| | LM78XXC | 5, 12, 15 | 4 | 0.03 | 0.5 | 35 | 66-80 | |
| | 0.5 | LM117H, LM217H | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 |
| | | LM317H | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 |
| LM117HVH, LM217HVH | | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 | |
| LM317HVH | | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 | |
| LM317M | | 1.2 to 37 (Adjustable) | N/A | 0.01 | 0.1 | 40 | 80 | |
| LM341 | | 5, 12, 15 | 4 | 0.02 | 0.5 | 35 | 80 | |
| LM78MXX | | 5, 12, 15 | 4 | 0.03 | 0.5 | 35 | 80 | |
| 0.25 | LM342 | 5, 12, 15 | 4 | 0.03 | 0.5 | 35 | 53-64 | |
| 0.20 | LM109H, LM209H | 5 | 6 | 0.004 | 0.4 | 35 | 80 | |
| | LM309H | 5 | 4 | 0.004 | 0.4 | 35 | 80 | |
| | LM2930P | 5, 8 | ±10 | | | 26V | 56 | |
| | LM130H | 5 | ±5 | | | 30V | 56 | |
| | LM330H | 5 | ±6 | | | 26V | 56 | |
| | LM330P | 5 | ±6 | | | 26V | 56 | |
| 0.10 | LM140L, LM240L | 5, 12, 15 | 2 | 0.02 | 0.25 | 35 | 48-62 | |
| | LM340L | 5, 12, 15 | 2 | 0.02 | 0.25 | 35 | 48-62 | |
| | LM78LXXA | 5, 12, 15 | 4 | 0.03 | 0.25 | 35 | 45-60 | |

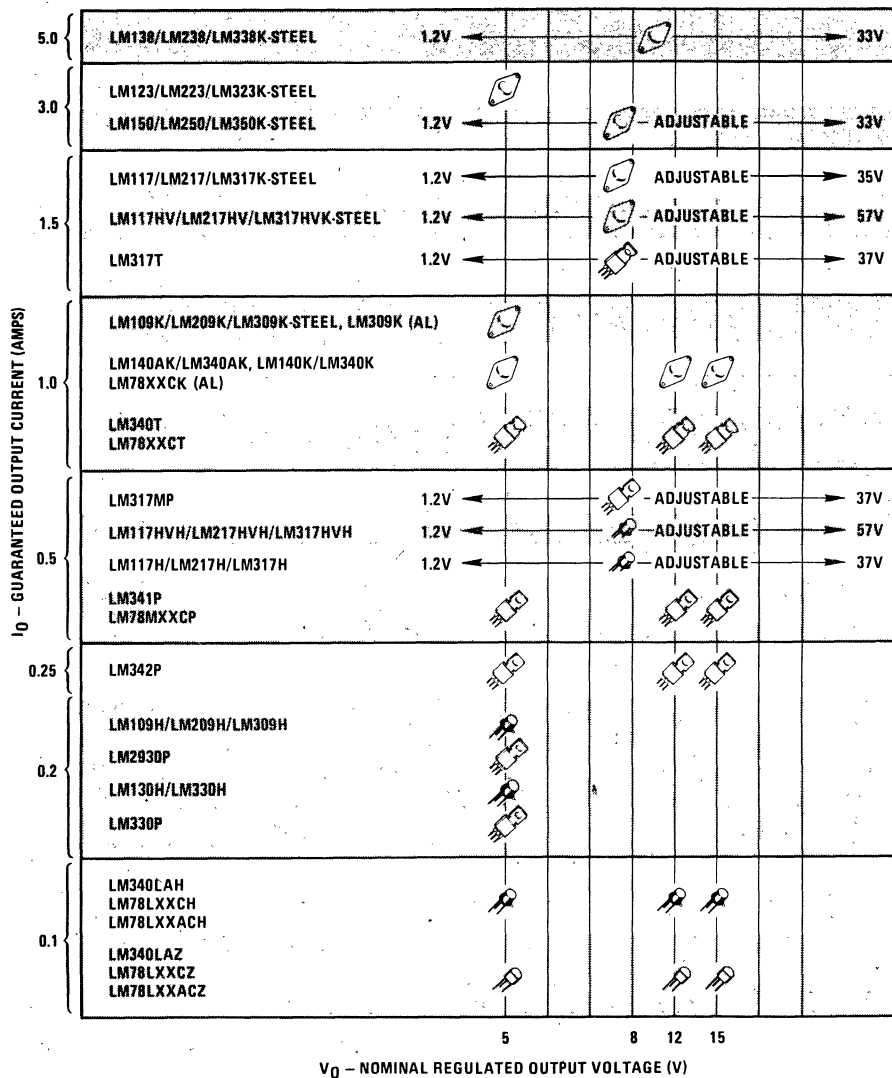
Note 1: Line regulation is the change in output voltage for a change in input voltage.

Note 2: Load regulation is the change in output voltage due to a change in load current from no load to full load.



Voltage Regulator Guide

1-14



| | PACKAGE DESIGNATOR | PACKAGE TYPE |
|--|--------------------|-------------------------|
| | K KC K STEEL | TO-3* HERMETIC |
| | T | TO-220 PLASTIC |
| | P | TO-202 PLASTIC |
| | H | TO-5, TO-39 HERMETIC |
| | Z | TO-92 PLASTIC |

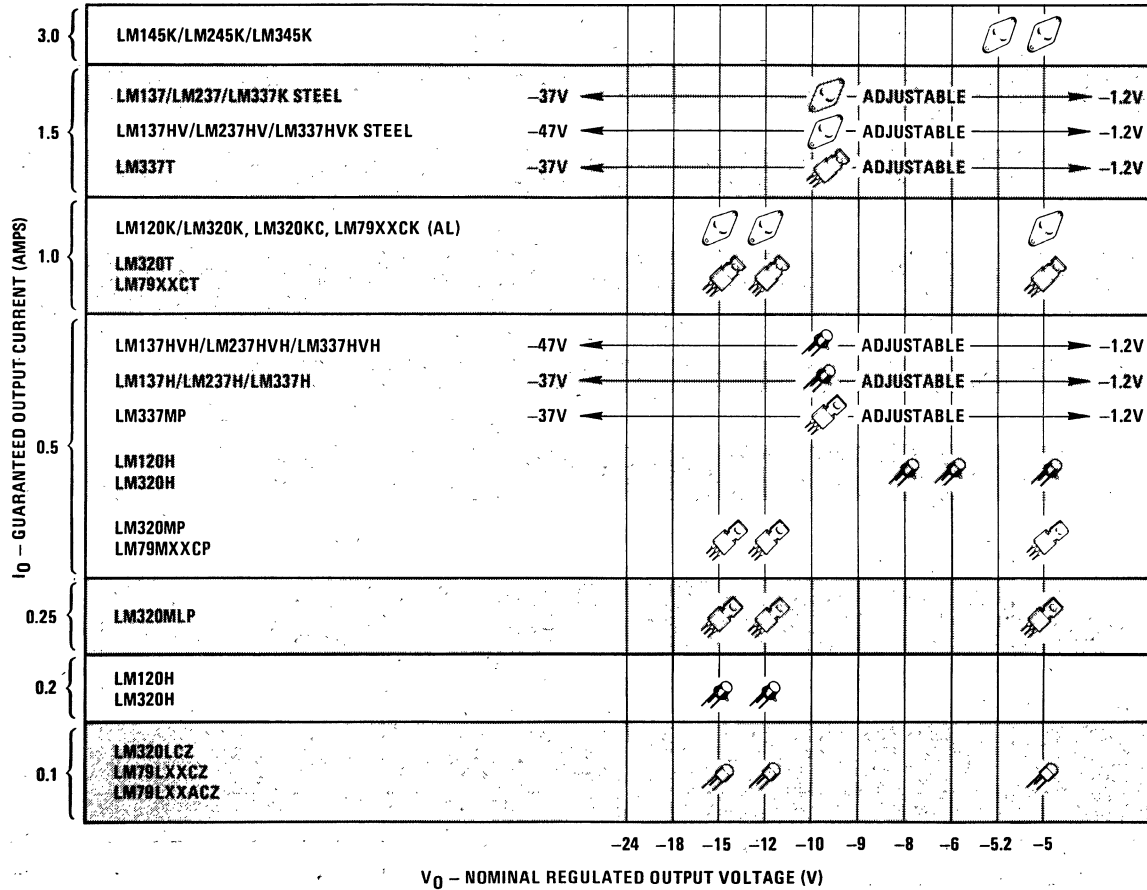
*All devices with TO-3 package designators (K or K STEEL) are supplied in steel TO-3 packages unless otherwise designated as (AL) aluminum TO-3 package. All KC designated devices are supplied in aluminum TO-3.

3-TERMINAL NEGATIVE VOLTAGE REGULATORS

| Output Current (A) | Device | Available V _{OUT} (V) | V _{OUT} Tol. (±%) | Regulation | | V _{IN} (V) Max | Ripple Rejection (dB) |
|--------------------|--|---|--|---|---|-------------------------|-----------------------|
| | | | | Line (Note 1) % V _{OUT} /V _{IN} | Load (Note 2) % V _{OUT} /V _{IN} | | |
| 3 | LM145K, LM245K LM345K | -5.0, -5.2 -5.0, -5.2 | 2 | 0.008 | 0.6 | 20 | 68 |
| | | | 4 | 0.008 | 0.6 | 20 | 68 |
| 1.5 | LM137, LM237 LM337 LM137HV, LM237HV LM337HV LM120K | -1.2 to -37 (Adjustable) -1.2 to -37 (Adjustable) -1.2 to -47 (Adjustable) -1.2 to -47 (Adjustable) -5 -12, -15, | N/A | 0.006 | 0.3 | 40 | 77 |
| | | | N/A | 0.007 | 0.3 | 40 | 77 |
| | | | N/A | 0.006 | 0.3 | 50 | 77 |
| | | | N/A | 0.007 | 0.3 | 50 | 77 |
| | | | 2 | 0.02 | 0.3 | 25 | 64 |
| | | | | | | 35 (12V) 40 (15V) | 80 75 70 |
| | LM320K | -5 -12, -15 | 4 | 0.02 | 0.3 | 25 | 64 |
| | | | | | | 35 (12V) 40 (15V) | 80 75 70 |
| | | | | | | | |
| | LM320T | -5 -12, -15 | 4 | 0.02 | 0.3 | 25 35 (12V, 15V) | 64 75-80 70 |
| | LM79XXC | -5 -12, -15 | 4 | 0.03 | 0.4 | 35 | 66-70 |
| | 0.5 | LM137H, LM237H LM337H LM137HVH, LM237HVH LM337HVH LM337M LM120H LM320H LM320M LM79MXX | -1.2 to -37 (Adjustable) -1.2 to -37 (Adjustable) -1.2 to -47 (Adjustable) -1.2 to -47 (Adjustable) -1.2 to -37 (Adjustable) -5.0 -5.0 -5 -12, -15 -5, -12, -15 | N/A | 0.006 | 0.3 | 40 |
| N/A | | | | 0.007 | 0.3 | 40 | 77 |
| N/A | | | | 0.006 | 0.3 | 50 | 77 |
| N/A | | | | 0.007 | 0.3 | 50 | 77 |
| N/A | | | | 0.007 | 0.3 | 40 | 77 |
| 2 | | | | 0.02 | 0.6 | 25 | 64 |
| 4 | | | | 0.02 | 0.6 | 25 | 64 |
| 4 | | | | 0.02 | 0.6 | 25 | 60-64 |
| 4 | | | | | | 35 (12V, 15V) | 70-80 |
| | | | | | | | |
| | | | | | | | |
| 0.25 | | | | LM320ML | -5 -12, -15 | 4 | 0.01 |
| 0.20 | LM120H LM320H | -12 -15 | 2 | 0.02 | 0.1 | 35 (12V) | 70-80 |
| | | | 4 | 0.02 | 0.1 | 40 (15V) | |
| 0.10 | LM320L LM79LXXA | -5 -12, -15 -5, -12, -15 | 4 | 0.01 | 0.5 | 35 | 60-65 |
| | | | 4 | 0.02 | 0.6 | 35 | 50-55 |

1-1

Voltage Regulator Guide



| | PACKAGE DESIGNATOR | PACKAGE TYPE |
|--|--------------------|-------------------------|
| | K KC K STEEL | TO-3* HERMETIC |
| | T | TO-220 PLASTIC |
| | P | TO-202 PLASTIC |
| | H | TO-5, TO-39 HERMETIC |
| | Z | TO-92 PLASTIC |

*All devices with TO-3 package designators (K or K STEEL) are supplied in steel TO-3 packages unless otherwise designated as (AL) aluminum TO-3 package. All KC designated devices are supplied in aluminum TO-3.

| Function | Features | Line Reg | Load Reg | I _{OUT} (mA) | V _{OUT} Toler. (@ 25°C (Max)) | Drift (Max) | Part Number | | * Page Number |
|---|---|----------|----------|-----------------------|--|-------------|----------------|---------------|---------------|
| | | | | | | | -55°C to 125°C | -25°C to 85°C | |
| Positive Programmable Voltage Regulator | Internal programming resistors, adjustable current limit, V _{OUT} = 5, 6, 8, 10, 12, 15, 18V | 0.008% | 0.055% | 0.1-200 | 0.5% | | LH0075 | LH0075C | 7-8 |
| Negative Programmable Voltage Regulator | | | | | 0.5% | | LH0076 | LH0075C | 7-13 |

*Refers to Special Functions Databook, 1979 edition



Definition of Terms

Current-Limit Sense Voltage: The voltage across the current limit terminals required to cause the regulator to current-limit with a short circuited output. This voltage is used to determine the value of the external current-limit resistor when external booster transistors are used.

Dropout Voltage: The input-output voltage differential at which the circuit ceases to regulate against further reductions in input voltage.

Feedback Sense Voltage: The voltage, referred to ground, on the feedback terminal of the regulator while it is operating in regulation.

Input Voltage Range: The range of dc input-voltages over which the regulator will operate within specifications.

Line Regulation: The change in output voltage for a change in the input voltage. The measurement is made under conditions of low dissipation or by using pulse techniques such that the average chip temperature is not significantly affected.

Load Regulation: The change in output voltage for a change in load current at constant chip temperature.

Long Term Stability: Output voltage stability under accelerated life-test conditions at 125°C with maximum rated voltages and power dissipation for 1000 hours.

Maximum Power Dissipation: The maximum total device dissipation for which the regulator will operate within specifications.

Output-Input Voltage Differential: The voltage difference between the unregulated input voltage and the regulated output voltage for which the regulator will operate within specifications.

Output Noise Voltage: The RMS ac voltage at the output with constant load and no input ripple, measured over a specified frequency range.

Output Voltage Range: The range of regulated output voltages over which the specifications apply.

Output Voltage Scale Factor: The output voltage obtained for a unit value of resistance between the adjustment terminal and ground.

Quiescent Current: That part of input current to the regulator that is not delivered to the load.

Ripple Rejection: The line regulation for ac input signals at or above a given frequency with a specified value of bypass capacitor on the reference bypass terminal.

Standby Current Drain: That part of the operating current of the regulator which does not contribute to the load current.

Temperature Stability: The percentage change in output voltage for a thermal variation from room temperature to either temperature extreme.

Thermal Regulation: Percentage change in output voltage for a given change in power dissipation over a specified time period.



**National
Semiconductor**

Fixed or Adjustable Voltage Regulators

At National we see the trend moving toward the use of more adjustable regulators and we are broadening the adjustable line to satisfy this demand.

As you browse through this Voltage Regulator section you will notice many changes. We've expanded the adjustable regulator line and many voltage options on fixed regulators have been deleted.

The fixed voltage regulators, like the 7800 and 7900 series, resulted in customers having to stock and hold in inventory quantities of each voltage in order to always have on hand a specific device for a particular system. This proved to be very costly especially when production was stopped due to shortage of a particular voltage.

Adjustables combine versatility, performance and reliability, leading to increased popularity.

Versatility

- Satisfy output voltage requirements from 1.2V up to 47V
- Simplify inventory and purchasing since a single device satisfies many voltage requirements
- Allows precision application

Performance

- Improves system performance by having line and load regulation a factor of 10 better
- Has improved overload protection thus allowing greater output current over operating temperature range

Reliability

- Improves system reliability with each device being subjected to 100% thermal limit burn-in

As more and more applications use adjustable regulators, we believe that they will become the most popular regulators in the industry.



Voltage Regulators

LM104/LM204/LM304 Negative Regulator

General Description

The LM104 series are precision voltage regulators which can be programmed by a single external resistor to supply any voltage from 40V down to zero while operating from a single unregulated supply. They can also provide 0.01-percent regulation in circuits using a separate, floating bias supply, where the output voltage is limited only by the breakdown of external pass transistors. Although designed primarily as linear, series regulators, the circuits can be used as switching regulators, current regulators or in a number of other control applications. Typical performance characteristics are:

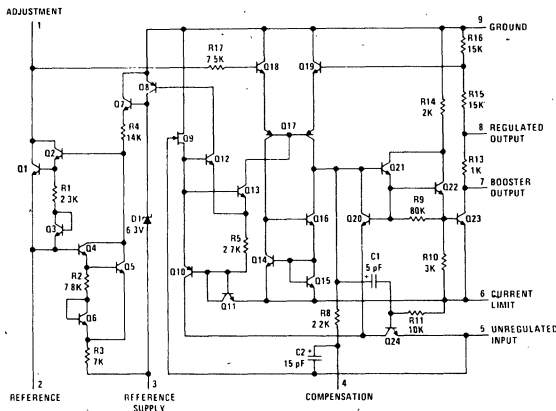
- Subsurface zener reference
- 1 mV regulation no load to full load
- 0.01%/V line regulation
- 0.2 mV/V ripple rejection

- 0.3% temperature stability over military temperature range

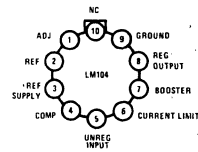
The LM104 series are complements of the LM100 and LM105 positive regulators, intended for systems requiring regulated negative voltages which have a common ground with the unregulated supply. By themselves, they can deliver output currents to 25 mA, but external transistors can be added to get any desired current. The output voltage is set by external resistors, and either constant or foldback current limiting is made available.

The LM104 is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LM204 is specified for operation over the -25°C to $+85^{\circ}\text{C}$ temperature range. The LM304 is specified for operation from 0°C to $+70^{\circ}\text{C}$.

Schematic and Connection Diagrams



Metal Can Package



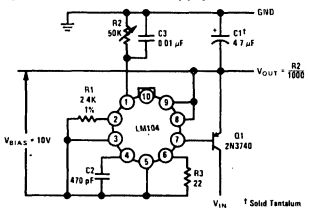
Note: Pin 5 connected to case.

TOP VIEW

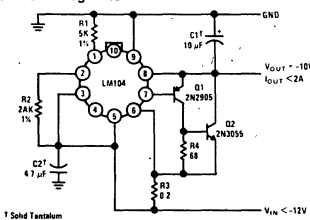
Order Number LM104H, LM204H or LM304H
See NS Package H10C

Typical Applications

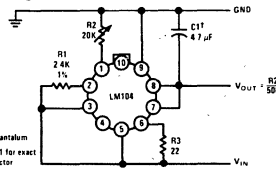
Operating with Separate Bias Supply



High Current Regulator

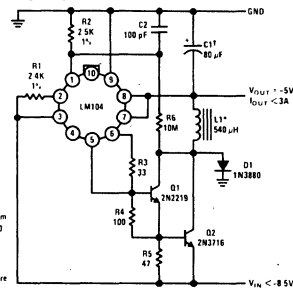


Basic Regulator Circuit



† Solid Tantalum
‡ Trim R1 for exact scale factor

Switching Regulator



† Solid Tantalum
‡ 60 Turns #20 on Arnold Engineering AD9253 Z Molybdenum Permalloy Core

Absolute Maximum Ratings

| | LM104/LM204 | LM304 |
|--------------------------------------|----------------|-----------------|
| Input Voltage | 50V | 40V |
| Input-Output Voltage Differential | 50V | 40V |
| Power Dissipation (Note 1) | 500 mW | 500 mW |
| Operating Temperature Range | | |
| LM104 | -55°C to 125°C | |
| LM204 | -25°C to 85°C | |
| LM304 | | 0°C to +70°C |
| Storage Temperature Range | -65°C to 150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C | 300°C |

Electrical Characteristics

| PARAMETER | CONDITIONS | LM104/LM204 | | | LM304 | | | UNITS |
|--|---|-------------|-------|--------|-------|-------|--------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Voltage Range | | -50 | | -8 | -40 | | -8 | V |
| Output Voltage Range | | -40 | | -0.015 | -30 | | -0.035 | V |
| Output-Input Voltage Differential (Note 3) | $I_O = 20 \text{ mA}$ | 2.0 | | 50 | 2.0 | | 40 | V |
| | $I_O = 5 \text{ mA}$ | 0.5 | | 50 | 0.5 | | 40 | V |
| Load Regulation (Note 4) | $0 \leq I_O \leq 20 \text{ mA}$ $R_{SC} = 15\Omega$ | | 1 | 5 | | 1 | .5 | mV |
| Line Regulation (Note 5) | $V_{OUT} \leq -5V$ $\Delta V_{IN} = 0.1 V_{IN}$ | | 0.056 | 0.1 | | 0.056 | 0.1 | % |
| Ripple Rejection | $C_{19} = 10 \mu F, f = 120 \text{ Hz}$ $V_{IN} < -15V$ $-7V \geq V_{IN} \geq -15V$ | | 0.2 | 0.5 | | 0.2 | 0.5 | mV/V |
| | | | 0.5 | 1.0 | | 0.5 | 1.0 | mV/V |
| Output Voltage Scale Factor | $R_{23} = 2.4k$ | 1.8 | 2.0 | 2.2 | 1.8 | 2.0 | 2.2 | V/kΩ |
| Temperature Stability | $V_O \leq -1V$ | | 0.3 | 1.0 | | 0.3 | 1.0 | % |
| Output Noise Voltage | $10 \text{ Hz} \leq f \leq 10 \text{ kHz}$ $V_O \leq -5V, C_{19} = 0$ $C_{19} = 10 \mu F$ | | 0.007 | | | 0.007 | | % |
| | | | 15 | | | 15 | | μV |
| Standby Current Drain | $I_L = 5 \text{ mA}, V_O = 0$ $V_O = -30V$ $V_O = -40V$ | | 1.7 | 2.5 | | 1.7 | 2.5 | mA |
| | | | 3.6 | 5.0 | | 3.6 | 5.0 | mA |
| Long Term Stability | $V_O \leq -1V$ | | 0.01 | 1.0 | | 0.01 | 1.0 | % |

Note 1: The maximum junction temperature of the LM104 is 150°C, while that of the LM204 is 125°C and LM304 is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case.

Note 2: These specifications apply for junction temperatures between -55°C and 150°C (between -25°C and 100°C for the LM204 and 0°C to +85°C for the LM304) and for input and output voltages within the ranges given, unless otherwise specified. The load and line regulation specifications are for constant junction temperature. Temperature drift effects must be taken into account separately when the unit is operating under conditions of high dissipation.

Note 3: When external booster transistors are used, the minimum output-input voltage differential is increased, in the worst case, by approximately 1V.

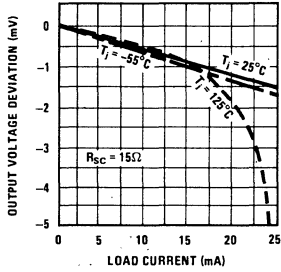
Note 4: The output currents given, as well as the load regulation, can be increased by the addition of external transistors. The improvement factor will be roughly equal to the composite current gain of the added transistors.

Note 5: With zero output, the dc line regulation is determined from the ripple rejection. Hence, with output voltages between 0V and -5V, a dc output variation, determined from the ripple rejection, must be added to find the worst-case line regulation.

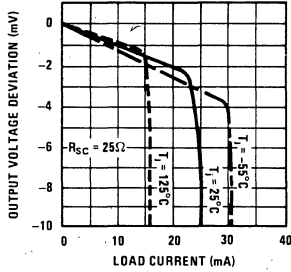


Typical Performance Characteristics

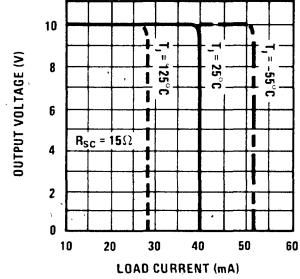
Load Regulation



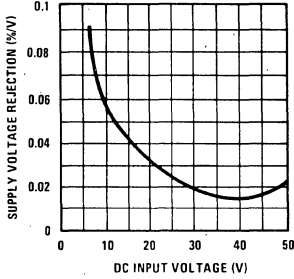
Load Regulation



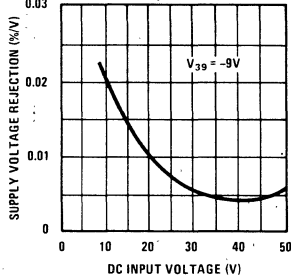
Current Limiting



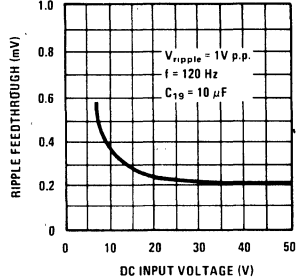
Supply Voltage Rejection



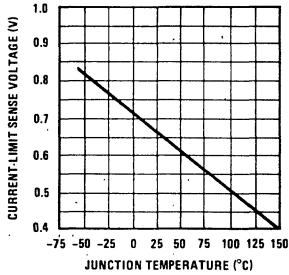
Supply Voltage Rejection With Preregulated Reference Supply



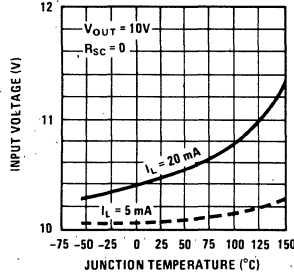
Ripple Rejection



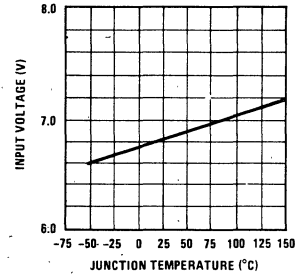
Current Limit Sense Voltage



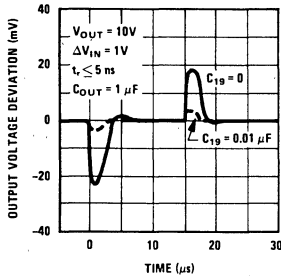
Regulator Dropout Voltage



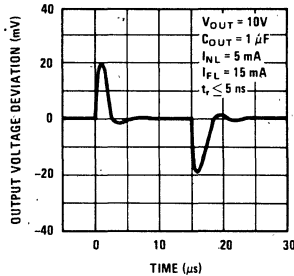
Minimum Input Voltage



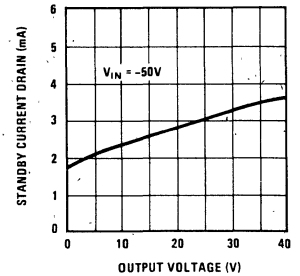
Line Transient Response



Load Transient Response



Standby Current Drain



LM105/LM205/LM305/LM305A, LM376 Voltage Regulators

General Description

The LM105 series are positive voltage regulators similar to the LM100, except that an extra gain stage has been added for improved regulation. A redesign of the biasing circuitry removes any minimum load current requirement and at the same time reduces standby current drain, permitting higher voltage operation. They are direct, plug-in replacements for the LM100 in both linear and switching regulator circuits with output voltages greater than 4.5V. Important characteristics of the circuits are:

- Output voltage adjustable from 4.5V to 40V
- Output currents in excess of 10A possible by adding external transistors
- Load regulation better than 0.1%, full load with current limiting
- DC line regulation guaranteed at 0.03%/V

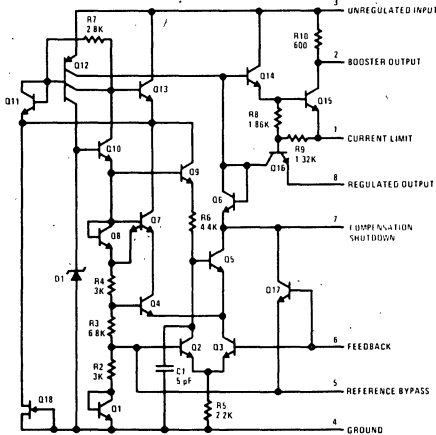
- Ripple rejection of 0.01%/V
- 45 mA output current without external pass transistor (LM305A)

Like the LM100, they also feature fast response to both load and line transients, freedom from oscillations with varying resistive and reactive loads and the ability to start reliably on any load within rating. The circuits are built on a single silicon chip and are supplied in either an 8-lead, TO-5 header or a 1/4" x 1/4" metal flat package.

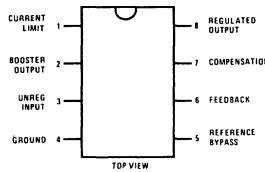
The LM105 is specified for operation for $-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$, the LM205 is specified for $-25^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$, and the LM305/LM305A, LM376 is specified for $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$.

1

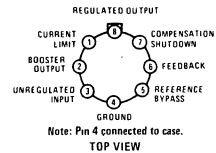
Schematic and Connection Diagrams



Dual-In-Line Package



Metal Can Package



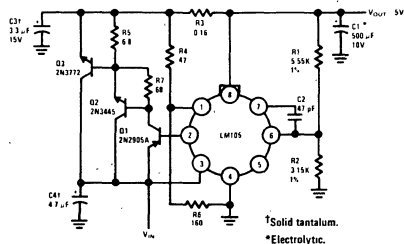
Order Number LM376N
See NS Package N08B

Order Number LM105H,
LM205H, LM305H or LM305AH
See NS Package H08C

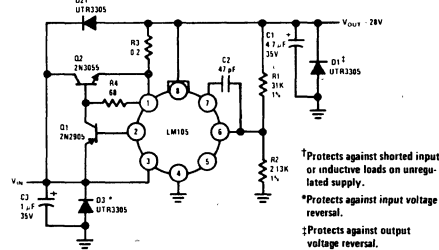
Pin connections shown are for metal can.

Typical Applications

10A Regulator with Foldback Current Limiting



1.0A Regulator with Protective Diodes



LM105/LM205/ LM305/LM305A, LM376

Absolute Maximum Ratings

| | LM105 | LM205 | LM305 | LM305A | LM376 |
|--|-----------------|-----------------|-----------------|-----------------|-----------------|
| Input Voltage | 50V | 50V | 40V | 50V | 40V |
| Input-Output Differential | 40V | 40V | 40V | 40V | 40V |
| Power Dissipation (Note 1) | 800 mW | 800 mW | 800 mW | 800 mW | 400 mW |
| Operating Temperature Range | -55°C to +125°C | -25°C to +85°C | 0°C to +70°C | 0°C to +70°C | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | 300°C | 300°C | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LM105 | | | LM205 | | | LM305 | | | LM305A | | | LM376 | | | UNITS | |
|---|---|-------|-------|------|-------|-------|------|-------|-------|------|--------|----------------------------|------|-------|----------------------------|------|-------|---|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| Input Voltage Range | | 8.5 | | 50 | 8.5 | | 50 | 8.5 | | 40 | 8.5 | | 50 | 9.0 | | 40 | V | |
| Output Voltage Range | | 4.5 | | 40 | 4.5 | | 40 | 4.5 | | 30 | 4.5 | | 40 | 5.0 | | 37 | V | |
| Input-Output Voltage Differential | | 3.0 | | 30 | 3.0 | | 30 | 3.0 | | 30 | 3.0 | | 30 | 3.0 | | 30 | V | |
| Load Regulation (Note 3) | R _{SC} = 10Ω, T _A = 25°C | | 0.02 | 0.05 | | 0.02 | 0.05 | | 0.02 | 0.05 | | | | | | | % | |
| | R _{SC} = 10Ω, T _A = T _A (MAX) | | 0.03 | 0.1 | | 0.03 | 0.1 | | 0.03 | 0.1 | | | | | | | % | |
| | R _{SC} = 10Ω, T _A = T _A (MIN) | | 0.03 | 0.1 | | 0.03 | 0.1 | | 0.03 | 0.1 | | | | | | | % | |
| | 0 ≤ I _O ≤ 12 mA | | | | | | | | | | | | | | | | | % |
| | R _{SC} = 0Ω, T _A = 25°C | | | | | | | | | | | | 0.02 | 0.2 | | | 0.2 | % |
| R _{SC} = 0Ω, T _A = 70°C | | | | | | | | | | | | 0.03 | 0.4 | | | 0.5 | % | |
| R _{SC} = 0Ω, T _A = 0°C | | | | | | | | | | | | 0.03 | 0.4 | | | 0.5 | % | |
| | | | | | | | | | | | | 0 ≤ I _O ≤ 45 mA | | | 0 ≤ I _O ≤ 25 mA | | | |
| Line Regulation | T _A = 25°C | | | | | | | | | | | | | | | 0.03 | %/V | |
| | 0°C ≤ T _A ≤ +70°C | | | | | | | | | | | | | | | 0.1 | %/V | |
| | V _{IN} - V _{OUT} ≤ 5V, T _A = 25°C | | 0.025 | 0.06 | | 0.025 | 0.06 | | 0.025 | 0.06 | | 0.025 | 0.06 | | | | %/V | |
| | V _{IN} - V _{OUT} ≥ 5V, T _A = 25°C | | 0.015 | 0.03 | | 0.015 | 0.03 | | 0.015 | 0.03 | | 0.015 | 0.03 | | | | %/V | |
| Temperature Stability | T _A (MIN) ≤ T _A ≤ T _A (MAX) | | 0.3 | 1.0 | | 0.3 | 1.0 | | 0.3 | 1.0 | | 0.3 | 1.0 | | | | % | |
| Feedback Sense Voltage | | 1.63 | 1.7 | 1.81 | 1.63 | 1.7 | 1.81 | 1.63 | 1.7 | 1.81 | 1.55 | 1.7 | 1.85 | 1.60 | 1.72 | 1.80 | V | |
| Output Noise Voltage | 10 Hz ≤ f ≤ 10 kHz | | | | | | | | | | | | | | | | | |
| | C _{REF} = 0 | | 0.005 | | | 0.005 | | | 0.005 | | | 0.005 | | | | | % | |
| | C _{REF} = 0.1μF | | 0.002 | | | 0.002 | | | 0.002 | | | 0.002 | | | | | % | |
| Standby Current Drain | V _{IN} = 30V, T _A = 25°C | | | | | | | | | | | | | | | 2.5 | mA | |
| | V _{IN} = 40V | | | | | | | | 0.8 | 2.0 | | | | | | | mA | |
| | V _{IN} = 50V | | 0.8 | 2.0 | | 0.8 | 2.0 | | | | | 0.8 | 2.0 | | | | mA | |
| Current Limit Sense Voltage | T _A = 25°C, R _{SC} = 10Ω, V _{OUT} = 0V, (Note 4) | 225 | 300 | 375 | 225 | 300 | 375 | 225 | 300 | 375 | 225 | 300 | 375 | | 300 | | mV | |
| Long Term Stability | | | 0.1 | 1.0 | | 0.1 | 1.0 | | 0.1 | 1.0 | | 0.1 | 1.0 | | | | % | |
| Ripple Rejection | C _{REF} = 10μF, f = 120 Hz | | 0.003 | 0.01 | | 0.003 | 0.01 | | 0.003 | 0.01 | | 0.003 | | | | 0.1 | %/V | |

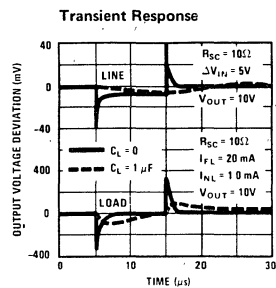
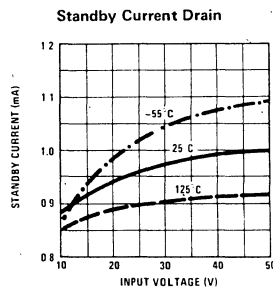
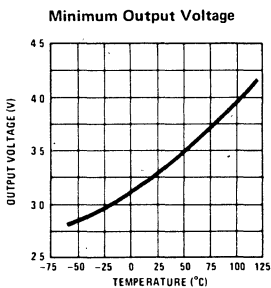
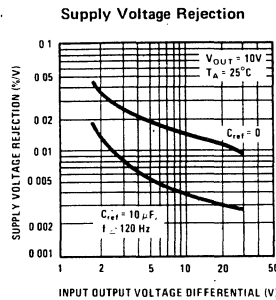
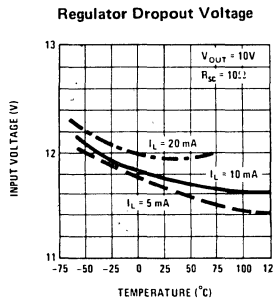
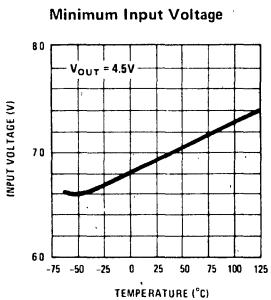
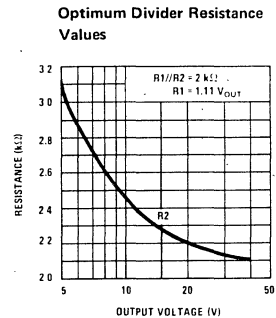
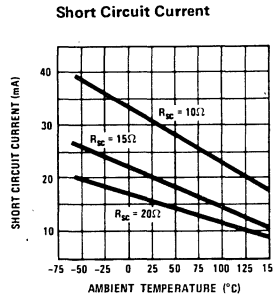
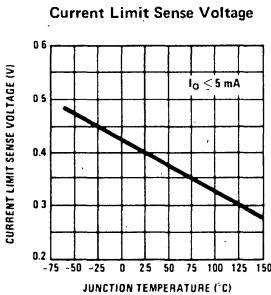
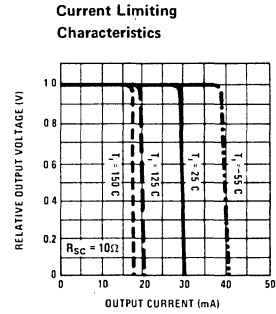
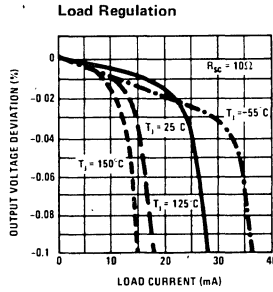
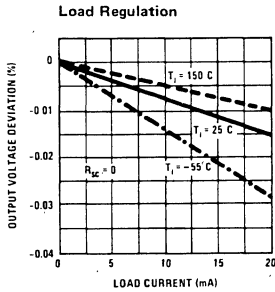
Note 1: The maximum junction temperature of the LM105 and LM305A is 150°C, the LM205 and LM376 is 100°C, and the LM305 is 85°C. For operation at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W junction to ambient, or 45°C/W junction to case. For the epoxy dual-in-line package, derating is based on a thermal resistance of 187°C/W junction to ambient. Peak dissipations to 1W are allowable providing the dissipation rating is not exceeded with the power averaged over a five second interval for the LM105 and LM205, and averaged over a two second interval for the LM305.

Note 2: Unless otherwise specified, these specifications apply for temperatures within the operating temperature range, for input and output voltages within the range given, and for a divider impedance seen by the feedback terminal of 2 kΩ. Load and line regulation specifications are for a constant junction temperature. Temperature drift effects must be taken into account separately when the unit is operating under conditions of high dissipation.

Note 3: The output currents given, as well as the load regulation, can be increased by the addition of external transistors. The improvement factor will be roughly equal to the composite current gain of the added transistors.

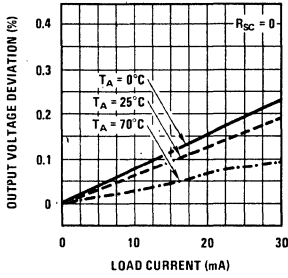
Note 4: With no external pass transistor.

Typical Performance Characteristics LM105/LM205/LM305/LM305A

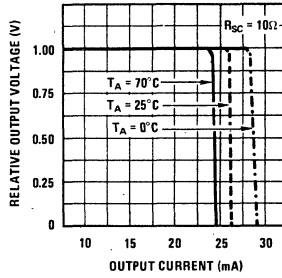


Typical Performance Characteristics LM376

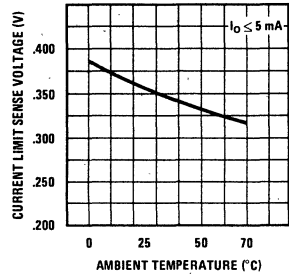
Load Regulation



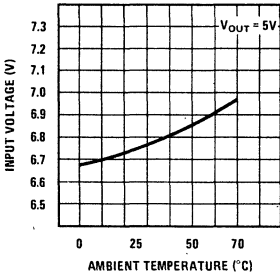
Current Limiting Characteristics



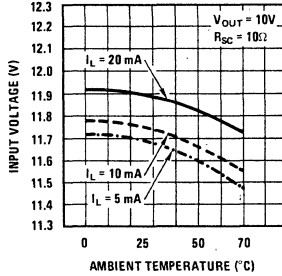
Current Limit Sense Voltage



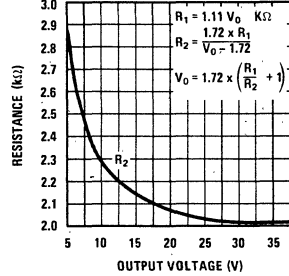
Minimum Input Voltage



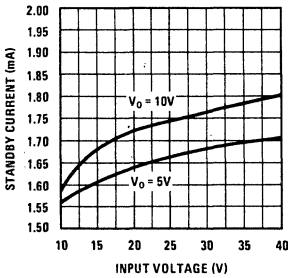
Regulator Dropout Voltage



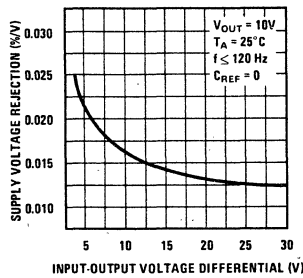
Optimum Divider Resistance



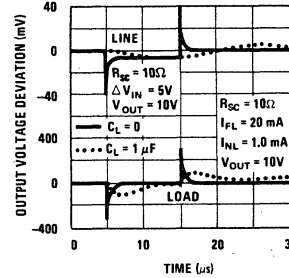
Standby Current Drain
TA = 25°C



Supply Voltage Rejection

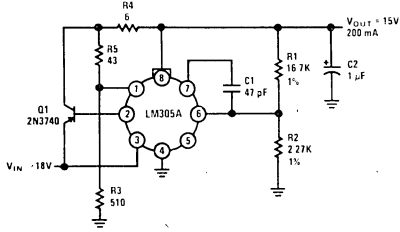


Transient Response

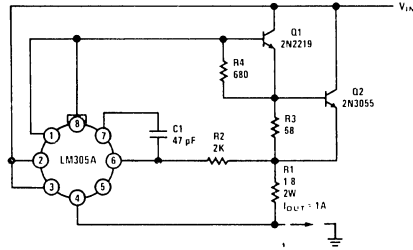


Typical Applications (Continued)

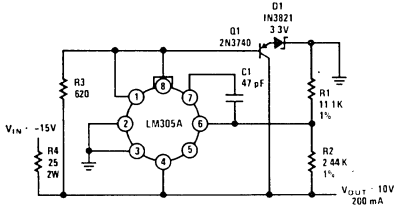
Linear Regulator with Foldback Current Limiting



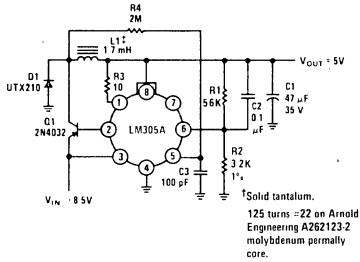
Current Regulator



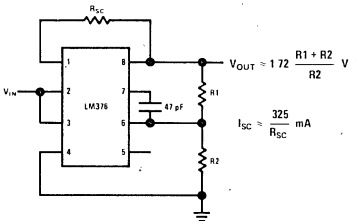
Shunt Regulator



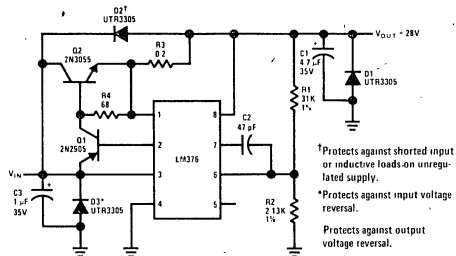
Switching Regulator



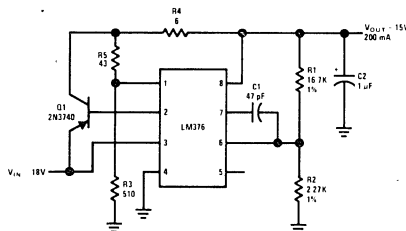
Basic Positive Regulator with Current Limiting



1.0A Regulator with Protective Diodes



Linear Regulator with Foldback Current Limiting





Voltage Regulators

LM109/LM209/LM309 5-Volt Regulator

General Description

The LM109 series are complete 5 V regulators fabricated on a single silicon chip. They are designed for local regulation on digital logic cards, eliminating the distribution problems associated with single-point regulation. The devices are available in two standard transistor packages. In the solid-kovar TO-5 header, it can deliver output currents in excess of 200 mA, if adequate heat sinking is provided. With the TO-3 power package, the available output current is greater than 1 A.

The regulators are essentially blowout proof. Current limiting is included to limit the peak output current to a safe value. In addition, thermal shutdown is provided to keep the IC from overheating. If internal dissipation becomes too great, the regulator will shut down to prevent excessive heating.

Considerable effort was expended to make these devices easy to use and to minimize the number of external components. It is not necessary to bypass the output, although this does improve transient response somewhat. Input bypassing is needed, however, if the regulator is

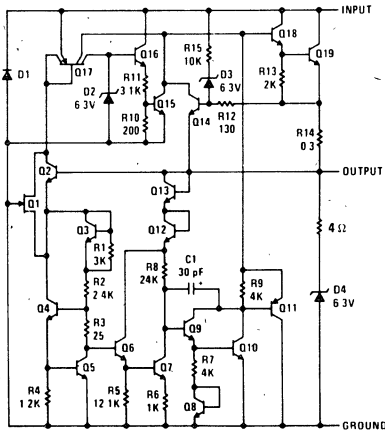
located very far from the filter capacitor of the power supply. Stability is also achieved by methods that provide very good rejection of load or line transients as are usually seen with TTL logic.

Although designed primarily as a fixed-voltage regulator, the output of the LM109 series can be set to voltages above 5 V, as shown below. It is also possible to use the circuits as the control element in precision regulators, taking advantage of the good current-handling capability and the thermal overload protection.

Features

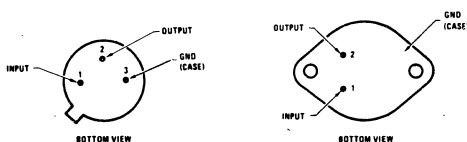
- Specified to be compatible, worst case, with TTL and DTL
- Output current in excess of 1 A
- Internal thermal overload protection
- No external components required

Schematic Diagram



Connection Diagrams

Metal Can Packages

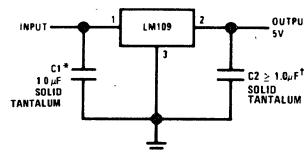


Order Number LM109H, LM209H or LM309H
See Package H03A

Order Number LM109K STEEL, LM209K STEEL, LM309K STEEL or LM309K (Aluminum)
See Package K02A

Typical Application

Fixed 5V Regulator

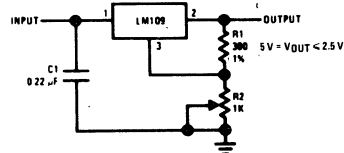


*Required if regulator is located more than 4" from power supply filter capacitor.

†Although no output capacitor is needed for stability, it does improve transient response. C2 should be used whenever long wires are used to connect to the load, or when transient response is critical.

NOTE: Pin 3 electrically connected to case.

Adjustable Output Regulator



Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage | 35 V |
| Power Dissipation | Internally Limited |
| Operating Junction Temperature Range | |
| LM109 | -55°C to +150°C |
| LM209 | -25°C to +150°C |
| LM309 | 0°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

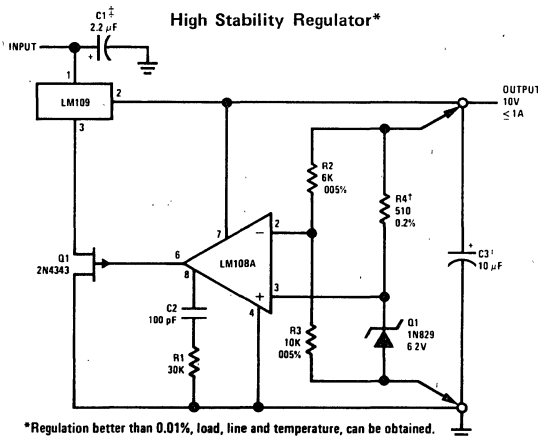
Electrical Characteristics

| PARAMETER | CONDITIONS | LM109/LM209 | | | LM309 | | | UNITS |
|---|--|-------------|------|-----|-------|------|------|---------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Output Voltage | $T_j = 25^\circ\text{C}$ | 4.7 | 5.05 | 5.3 | 4.8 | 5.05 | 5.2 | V |
| Line Regulation | $T_j = 25^\circ\text{C}$, $7\text{V} \leq V_{\text{IN}} \leq 25\text{V}$ | | 4.0 | 50 | | 4.0 | 50 | mV |
| Load Regulation | $T_j = 25^\circ\text{C}$ | | | | | | | |
| TO-5 Package | $5\text{mA} \leq I_{\text{OUT}} \leq 0.5\text{A}$ | | 15 | 50 | | 15 | 50 | mV |
| TO-3 Package | $5\text{mA} \leq I_{\text{OUT}} \leq 1.5\text{A}$ | | 15 | 100 | | 15 | 100 | mV |
| Output Voltage | $7\text{V} \leq V_{\text{IN}} \leq 25\text{V}$, $5\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$, $P < P_{\text{MAX}}$ | 4.6 | | 5.4 | 4.75 | | 5.25 | V |
| Quiescent Current | $7\text{V} \leq V_{\text{IN}} \leq 25\text{V}$ | | 5.2 | 10 | | 5.2 | 10 | mA |
| Quiescent Current Change | $7\text{V} \leq V_{\text{IN}} \leq 25\text{V}$ | | | 0.5 | | | 0.5 | mA |
| | $5\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$ | | | 0.8 | | | 0.8 | mA |
| Output Noise Voltage | $T_A = 25^\circ\text{C}$ $10\text{Hz} \leq f \leq 100\text{kHz}$ | | 40 | | | 40 | | μV |
| Long Term Stability | | | | 10 | | | 20 | mV |
| Ripple Rejection | $T_j = 25^\circ\text{C}$ | 50 | | | 50 | | | dB |
| Thermal Resistance, Junction to Case | (Note 2) | | | | | | | |
| TO-5 Package | | | 15 | | | 15 | | $^\circ\text{C}/\text{W}$ |
| TO-3 Package | | | 2.5 | | | 2.5 | | $^\circ\text{C}/\text{W}$ |

Note 1: Unless otherwise specified, these specifications apply for $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM109, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM209, and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM309; $V_{\text{IN}} = 10\text{V}$ and $I_{\text{OUT}} = 0.1\text{A}$ for the TO-5 package or $I_{\text{OUT}} = 0.5\text{A}$ for the TO-3 package. For the TO-5 package, $I_{\text{MAX}} = 0.2\text{A}$ and $P_{\text{MAX}} = 2.0\text{W}$. For the TO-3 package, $I_{\text{MAX}} = 1.0\text{A}$ and $P_{\text{MAX}} = 20\text{W}$.

Note 2: Without a heat sink, the thermal resistance of the TO-5 package is about $150^\circ\text{C}/\text{W}$, while that of the TO-3 package is approximately $35^\circ\text{C}/\text{W}$. With a heat sink, the effective thermal resistance can only approach the values specified, depending on the efficiency of the sink.

Typical Applications (Continued)

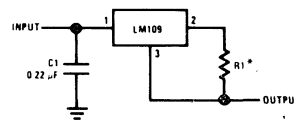


*Regulation better than 0.01%, load, line and temperature, can be obtained.

†Determines zener current. May be adjusted to minimize thermal drift.

‡Solid tantalum.

Current Regulator



*Determines output current. If wirewound resistor is used, bypass with $0.1\mu\text{F}$.

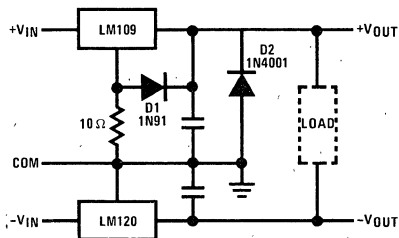
Application Hints

- Bypass the input of the LM109 to ground with $\geq 0.2 \mu\text{F}$ ceramic or solid tantalum capacitor if main filter capacitor is more than 4 inches away.
- Use steel package instead of aluminum if more than 5,000 thermal cycles are expected. ($\Delta T \geq 50^\circ\text{C}$)
- Avoid insertion of regulator into "live" socket if input voltage is greater than 10 V. The output will rise to within 2 V of the unregulated input if the ground pin does not make contact, possibly damaging the load. The LM109 may also be damaged if a large output capacitor is charged up, then discharged through the internal clamp zener when the ground pin makes contact.
- The output clamp zener is designed to absorb transients only. It will not clamp the output effectively if a failure occurs in the internal power transistor structure. Zener dynamic impedance is $\approx 4 \Omega$. Continuous RMS current into the zener should not exceed 0.5 A.
- Paralleling of LM109s for higher output current is not recommended. Current sharing will be almost nonexistent, leading to a current limit mode operation for devices with the highest initial output voltage. The current limit devices may also heat up to the

thermal shutdown point ($\approx 175^\circ\text{C}$). Long term reliability cannot be guaranteed under these conditions.

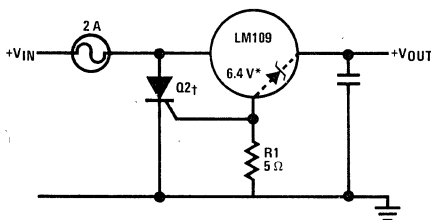
- Preventing latchoff for loads connected to negative voltage:

If the output of the LM109 is pulled negative by a high current supply so that the output pin is more than 0.5 V negative with respect to the ground pin, the LM109 can latch off. This can be prevented by clamping the ground pin to the output pin with a germanium or Schottky diode as shown. A silicon diode (1N4001) at the output is also needed to keep the positive output from being pulled too far negative. The 10Ω resistor will raise $+V_{\text{OUT}}$ by $\approx 0.05 \text{ V}$.

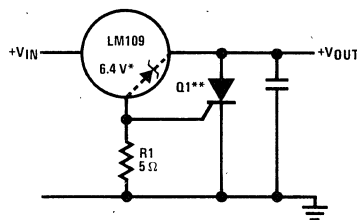


Crowbar Overvoltage Protection

INPUT CROWBAR



OUTPUT CROWBAR



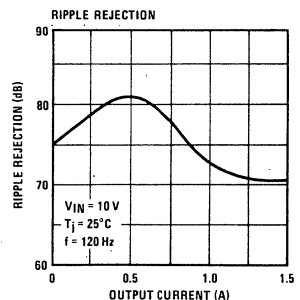
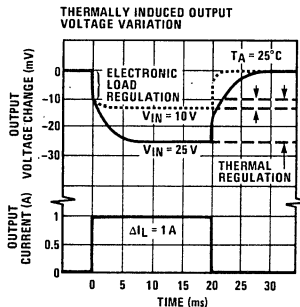
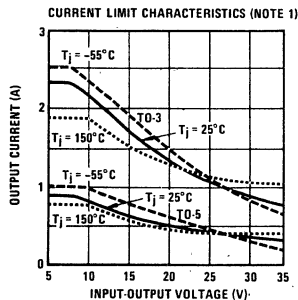
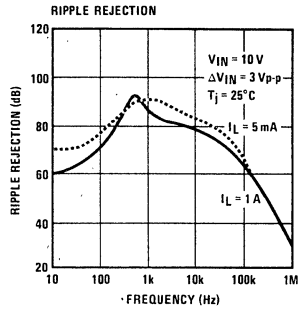
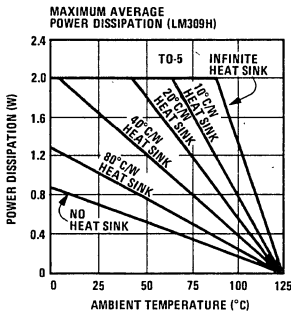
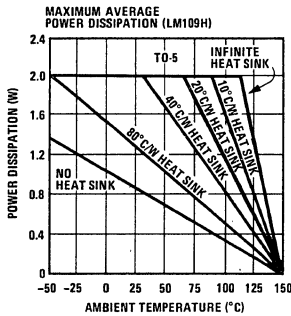
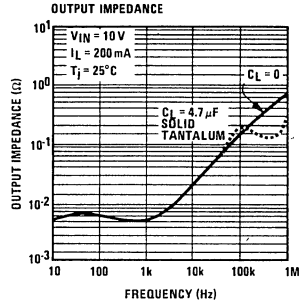
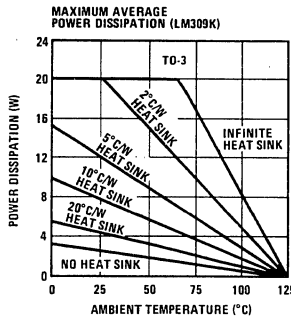
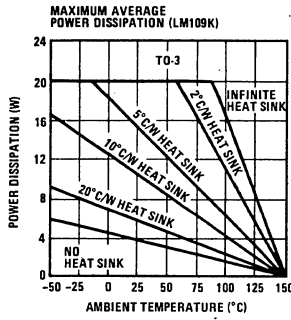
*Zener is internal to LM109.

**Q1 must be able to withstand 7 A continuous current if fusing is not used at regulator input. LM109 bond wires will fuse at currents above 7 A.

†Q2 is selected for surge capability. Consideration must be given to filter capacitor size, transformer impedance, and fuse blowing time.

††Trip point is $\approx 7.5 \text{ V}$.

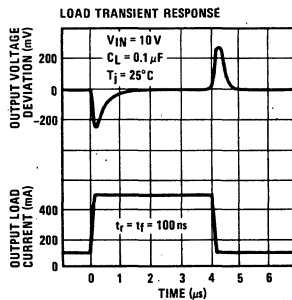
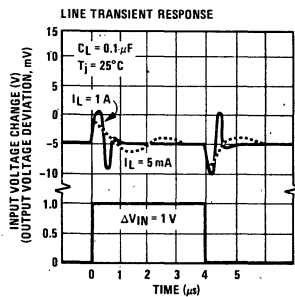
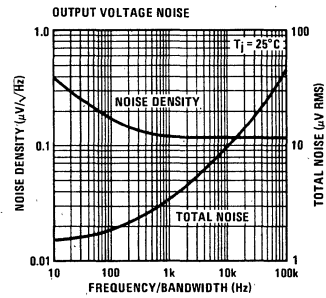
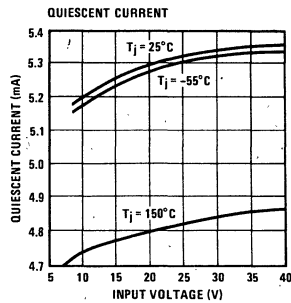
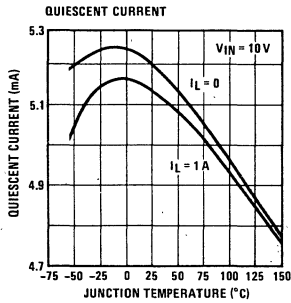
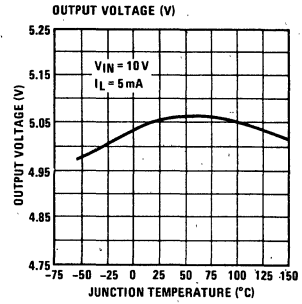
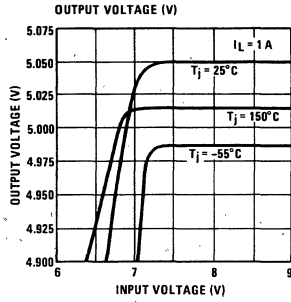
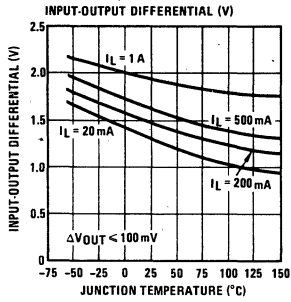
Typical Performance Characteristics



Note 1: Current limiting foldback characteristics are determined by input-output differential, not by output voltage.



Typical Performance Characteristics (Continued)



LM117/LM217/LM317 3-Terminal Adjustable Regulator

General Description

The LM117/LM217/LM317 are adjustable 3-terminal positive voltage regulators capable of supplying in excess of 1.5A over a 1.2V to 37V output range. They are exceptionally easy to use and require only two external resistors to set the output voltage. Further, both line and load regulation are better than standard fixed regulators. Also, the LM117 is packaged in standard transistor packages which are easily mounted and handled.

In addition to higher performance than fixed regulators, the LM117 series offers full overload protection available only in IC's. Included on the chip are current limit, thermal overload protection and safe area protection. All overload protection circuitry remains fully functional even if the adjustment terminal is disconnected.

Features

- Adjustable output down to 1.2V
- Guaranteed 1.5A output current
- Line regulation typically 0.01%/V
- Load regulation typically 0.1%
- Current limit constant with temperature
- **100% electrical burn-in**
- Eliminates the need to stock many voltages
- Standard 3-lead transistor package
- 80 dB ripple rejection

Normally, no capacitors are needed unless the device is situated far from the input filter capacitors in which case an input bypass is needed. An optional output capacitor can be added to improve transient response. The adjustment terminal can be bypassed to achieve very high ripple rejections ratios which are difficult to achieve with standard 3-terminal regulators.

Besides replacing fixed regulators, the LM117 is useful in a wide variety of other applications. Since the regulator is "floating" and sees only the input-to-output differential voltage, supplies of several hundred volts can be regulated as long as the maximum input to output differential is not exceeded.

Also, it makes an especially simple adjustable switching regulator, a programmable output regulator, or by connecting a fixed resistor between the adjustment and output, the LM117 can be used as a precision current regulator. Supplies with electronic shutdown can be achieved by clamping the adjustment terminal to ground which programs the output to 1.2V where most loads draw little current.

The LM117K, LM217K and LM317K are packaged in standard TO-3 transistor packages while the LM117H, LM217H and LM317H are packaged in a solid Kovar base TO-5 transistor package. The LM117 is rated for operation from -55°C to $+150^{\circ}\text{C}$, the LM217 from -25°C to $+150^{\circ}\text{C}$ and the LM317 from 0°C to $+125^{\circ}\text{C}$. The LM317T and LM317MP, rated for operation over a 0°C to $+125^{\circ}\text{C}$ range, are available in a TO-220 plastic package and a TO-202 package, respectively.

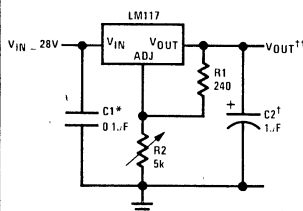
For applications requiring greater output current in excess of 3A and 5A, see LM150 series and LM138 series data sheets, respectively. For the negative complement, see LM137 series data sheet.

LM117 Series Packages and Power Capability

| DEVICE | PACKAGE | RATED POWER DISSIPATION | DESIGN LOAD CURRENT |
|--------|---------|-------------------------|---------------------|
| LM117 | TO-3 | 20W | 1.5A |
| LM217 | TO-39 | 2W | 0.5A |
| LM317 | | | |
| LM317T | TO-220 | 15W | 1.5A |
| LM317M | TO-202 | 7.5W | 0.5A |

Typical Applications

1.2V-25V Adjustable Regulator

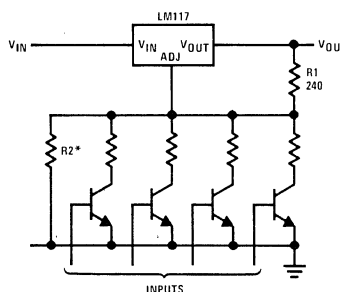


†Optional—improves transient response

*Needed if device is far from filter capacitors

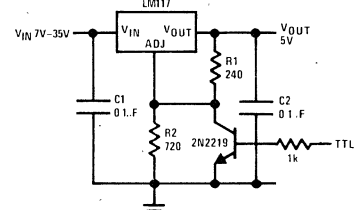
$$\dagger\dagger V_{OUT} = 1.25V \left(1 + \frac{R2}{R1} \right)$$

Digitally Selected Outputs



*Sets maximum V_{OUT}

5V Logic Regulator with Electronic Shutdown*



*Min output $\approx 1.2V$

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input–Output Voltage Differential | 40V |
| Operating Junction Temperature Range | |
| LM117 | –55°C to +150°C |
| LM217 | –25°C to +150°C |
| LM317 | 0°C to +125°C |
| Storage Temperature | –65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Preconditioning

Burn-In in Thermal Limit 100% All Devices

Electrical Characteristics (Note 1)

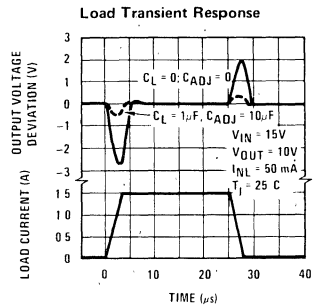
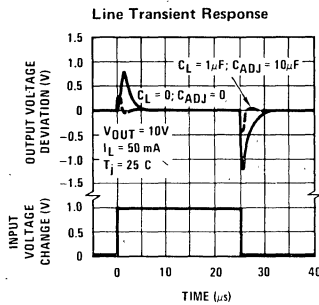
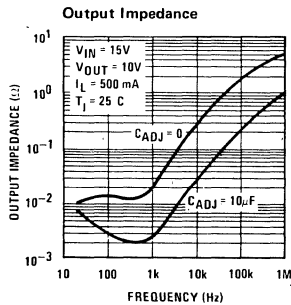
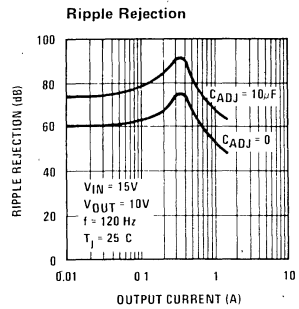
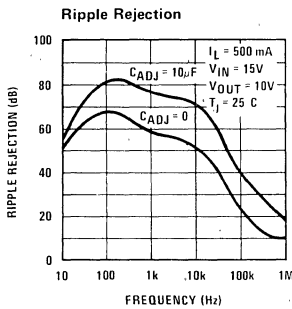
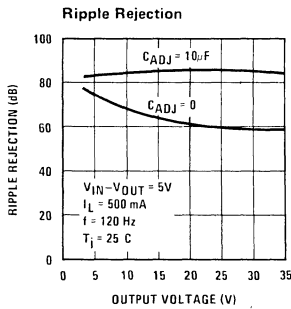
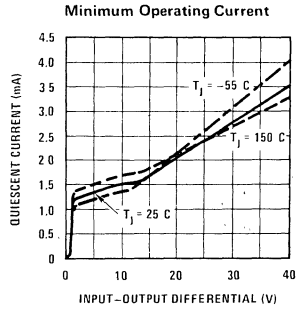
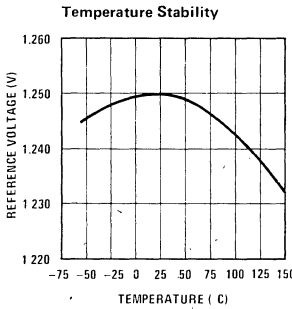
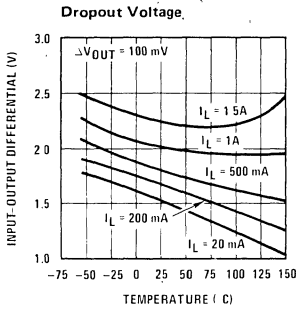
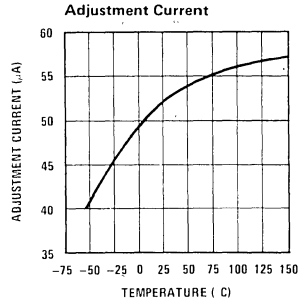
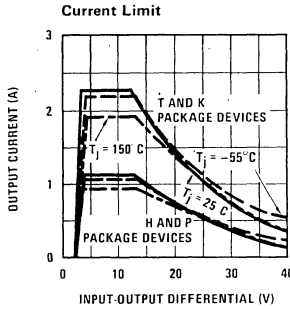
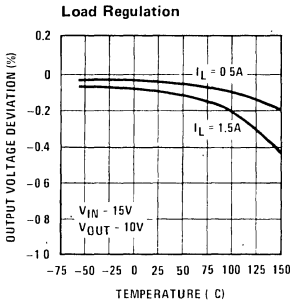
| PARAMETER | CONDITIONS | LM117/217 | | | LM317 | | | UNITS |
|---|--|-----------|------|-------|-------|-------|-------|--------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{\text{IN}} - V_{\text{OUT}} \leq 40\text{V}$ (Note 2) | | 0.01 | 0.02 | | 0.01 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$ $V_{\text{OUT}} \leq 5\text{V}$, (Note 2) $V_{\text{OUT}} \geq 5\text{V}$, (Note 2) | | 5 | 15 | | 5 | 25 | mV |
| | | | 0.1 | 0.3 | | 0.1 | 0.5 | % |
| Thermal Regulation | $T_A = 25^\circ\text{C}$, 20 ms Pulse | | 0.03 | 0.07 | | 0.04 | 0.07 | %/W |
| Adjustment Pin Current | | | 50 | 100 | | 50 | 100 | μA |
| Adjustment Pin Current Change | $10\text{mA} \leq I_L \leq I_{\text{MAX}}$ $2.5\text{V} \leq (V_{\text{IN}} - V_{\text{OUT}}) \leq 40\text{V}$ | | 0.2 | 5 | | 0.2 | 5 | μA |
| Reference Voltage | $3 \leq (V_{\text{IN}} - V_{\text{OUT}}) \leq 40\text{V}$, (Note 3) $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$, $P \leq P_{\text{MAX}}$ | 1.20 | 1.25 | 1.30 | 1.20 | 1.25 | 1.30 | V |
| Line Regulation | $3\text{V} \leq V_{\text{IN}} - V_{\text{OUT}} \leq 40\text{V}$, (Note 2) | | 0.02 | 0.05 | | 0.02 | 0.07 | %/V |
| Load Regulation | $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$, (Note 2) $V_{\text{OUT}} \leq 5\text{V}$ $V_{\text{OUT}} \geq 5\text{V}$ | | 20 | 50 | | 20 | 70 | mV |
| | | | 0.3 | 1 | | 0.3 | 1.5 | % |
| Temperature Stability | $T_{\text{MIN}} \leq T_j \leq T_{\text{MAX}}$ | | 1 | | | 1 | | % |
| Minimum Load Current | $V_{\text{IN}} - V_{\text{OUT}} = 40\text{V}$ | | 3.5 | 5 | | 3.5 | 10 | mA |
| Current Limit | $V_{\text{IN}} - V_{\text{OUT}} \leq 15\text{V}$ K and T Package H and P Package | | 1.5 | 2.2 | | 1.5 | 2.2 | A |
| | | | 0.5 | 0.8 | | 0.5 | 0.8 | A |
| | $V_{\text{IN}} - V_{\text{OUT}} = 40\text{V}$, $T_j = +25^\circ\text{C}$ K and T Package H and P Package | | 0.30 | 0.4 | | 0.15 | 0.4 | A |
| | | | 0.15 | 0.20 | | 0.075 | 0.20 | A |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{Hz} \leq f \leq 10\text{kHz}$ | | | 0.003 | | | 0.003 | % |
| Ripple Rejection Ratio | $V_{\text{OUT}} = 10\text{V}$, $f = 120\text{Hz}$ $C_{\text{ADJ}} = 10\mu\text{F}$ | | | 65 | | | 65 | dB |
| | | | 66 | 80 | | 66 | 80 | dB |
| Long-Term Stability | $T_A = 125^\circ\text{C}$ | | 0.3 | 1 | | 0.3 | 1 | % |
| Thermal Resistance, Junction to Case | H Package | | 12 | 15 | | 12 | 15 | $^\circ\text{C/W}$ |
| | K Package | | 2.3 | 3 | | 2.3 | 3 | $^\circ\text{C/W}$ |
| | T Package | | | | | 4 | | $^\circ\text{C/W}$ |
| | P Package | | | | | 12 | | $^\circ\text{C/W}$ |

Note 1: Unless otherwise specified, these specifications apply: $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM117, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM217 and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM317; $V_{\text{IN}} - V_{\text{OUT}} = 5\text{V}$ and $I_{\text{OUT}} = 0.1\text{A}$ for the TO-5 and TO-202 packages and $I_{\text{OUT}} = 0.5\text{A}$ for the TO-3 package and TO-220 package. Although power dissipation is internally limited, these specifications are applicable for power dissipations of 2W for the TO-5 and TO-202 and 20W for the TO-3 and TO-220. I_{MAX} is 1.5A for the TO-3 and TO-220 package and 0.5A for the TO-5 and TO-202 package.

Note 2: Regulation is measured at constant junction temperature, using pulse testing with a low duty cycle. Changes in output voltage due to heating effects are covered under the specification for thermal regulation.

Note 3: Selected devices with tightend tolerance reference voltage available.

Typical Performance Characteristics (K and T Packages)



Application Hints

In operation, the LM117 develops a nominal 1.25V reference voltage, V_{REF} , between the output and adjustment terminal. The reference voltage is impressed across program resistor R1 and, since the voltage is constant, a constant current I_1 then flows through the output set resistor R2, giving an output voltage of

$$V_{OUT} = V_{REF} \left(1 + \frac{R_2}{R_1} \right) + I_{ADJ} R_2$$

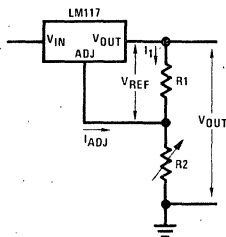


FIGURE 1.

Since the $100\mu\text{A}$ current from the adjustment terminal represents an error term, the LM117 was designed to minimize I_{ADJ} and make it very constant with line and load changes. To do this, all quiescent operating current is returned to the output establishing a minimum load current requirement. If there is insufficient load on the output, the output will rise.

External Capacitors

An input bypass capacitor is recommended. A $0.1\mu\text{F}$ disc or $1\mu\text{F}$ solid tantalum on the input is suitable input bypassing for almost all applications. The device is more sensitive to the absence of input bypassing when adjustment or output capacitors are used but the above values will eliminate the possibility of problems.

The adjustment terminal can be bypassed to ground on the LM117 to improve ripple rejection. This bypass capacitor prevents ripple from being amplified as the output voltage is increased. With a $10\mu\text{F}$ bypass capacitor 80 dB ripple rejection is obtainable at any output level. Increases over $10\mu\text{F}$ do not appreciably improve the ripple rejection at frequencies above 120 Hz. If the bypass capacitor is used, it is sometimes necessary to include protection diodes to prevent the capacitor from discharging through internal low current paths and damaging the device.

In general, the best type of capacitors to use are solid tantalum. Solid tantalum capacitors have low impedance even at high frequencies. Depending upon capacitor construction, it takes about $25\mu\text{F}$ in aluminum electrolytic to equal $1\mu\text{F}$ solid tantalum at high frequencies. Ceramic capacitors are also good at high frequencies; but some types have a large decrease in capacitance at frequencies around 0.5 MHz. For this reason, $0.01\mu\text{F}$ disc may seem to work better than a $0.1\mu\text{F}$ disc as a bypass.

Although the LM117 is stable with no output capacitors, like any feedback circuit, certain values of external capacitance can cause excessive ringing. This occurs with values between 500 pF and 5000 pF . A $1\mu\text{F}$ solid tantalum (or $25\mu\text{F}$ aluminum electrolytic) on the output swamps this effect and insures stability.

Load Regulation

The LM117 is capable of providing extremely good load regulation but a few precautions are needed to obtain maximum performance. The current set resistor connected between the adjustment terminal and the output terminal (usually 240Ω) should be tied directly to the output of the regulator rather than near the load. This eliminates line drops from appearing effectively in series with the reference and degrading regulation. For example, a 15V regulator with 0.05Ω resistance between the regulator and load will have a load regulation due to line resistance of $0.05\Omega \times I_L$. If the set resistor is connected near the load the effective line resistance will be $0.05\Omega (1 + R_2/R_1)$ or in this case, 11.5 times worse.

Figure 2 shows the effect of resistance between the regulator and 240Ω set resistor.

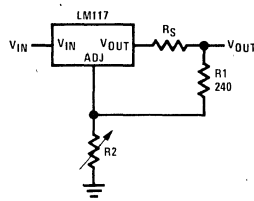


FIGURE 2. Regulator with Line Resistance in Output Lead

With the TO-3 package, it is easy to minimize the resistance from the case to the set resistor, by using two separate leads to the case. However, with the TO-5 package, care should be taken to minimize the wire length of the output lead. The ground of R2 can be returned near the ground of the load to provide remote ground sensing and improve load regulation.

Protection Diodes

When external capacitors are used with any IC regulator it is sometimes necessary to add protection diodes to prevent the capacitors from discharging through low current points into the regulator. Most $10\mu\text{F}$ capacitors have low enough internal series resistance to deliver 20A spikes when shorted. Although the surge is short, there is enough energy to damage parts of the IC.

When an output capacitor is connected to a regulator and the input is shorted, the output capacitor will discharge into the output of the regulator. The discharge



Application Hints (Continued)

current depends on the value of the capacitor, the output voltage of the regulator, and the rate of decrease of V_{IN} . In the LM117, this discharge path is through a large junction that is able to sustain 15A surge with no problem. This is not true of other types of positive regulators. For output capacitors of 25 μ F or less, there is no need to use diodes.

The bypass capacitor on the adjustment terminal can discharge through a low current junction. Discharge

occurs when *either* the input or output is shorted. Internal to the LM117 is a 50 Ω resistor which limits the peak discharge current. No protection is needed for output voltages of 25V or less and 10 μ F capacitance. *Figure 3* shows an LM117 with protection diodes included for use with outputs greater than 25V and high values of output capacitance.

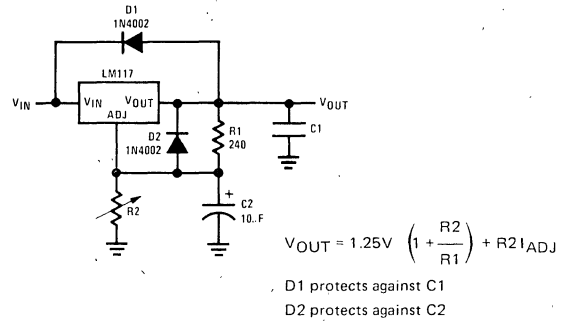
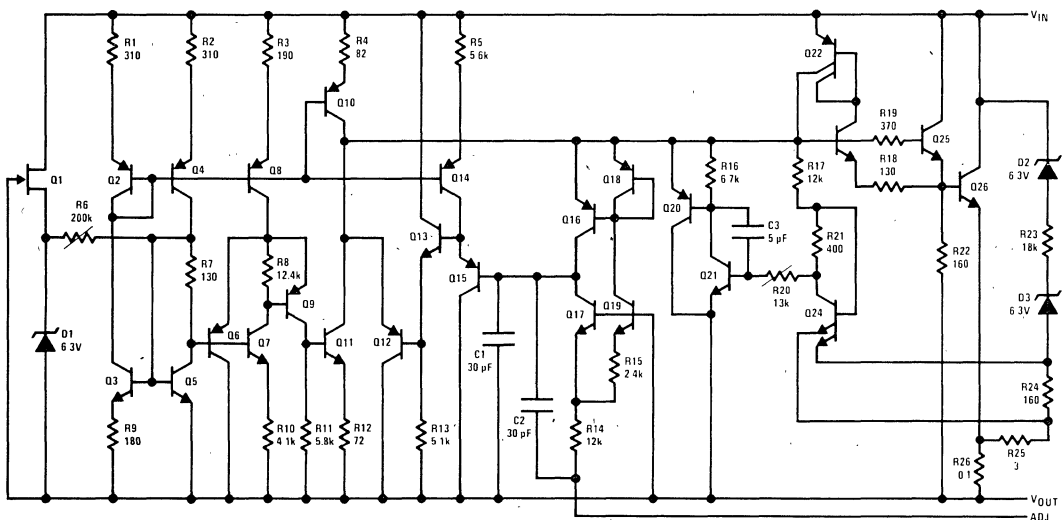


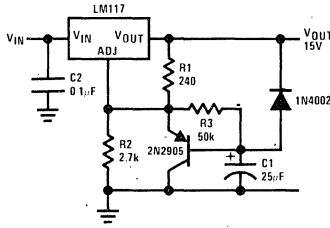
FIGURE 3. Regulator with Protection Diodes

Schematic Diagram

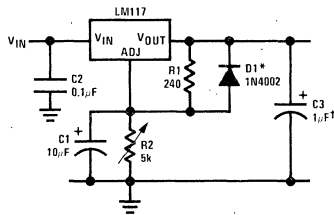


Typical Applications (Continued)

Slow Turn-On 15V Regulator

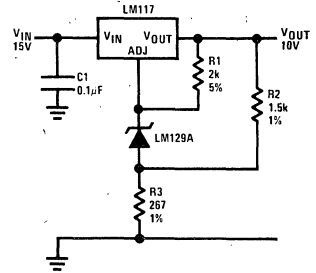


Adjustable Regulator with Improved Ripple Rejection

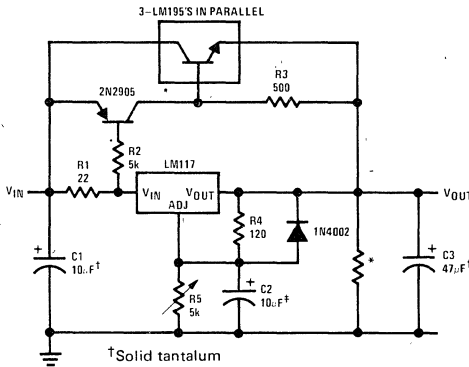


† Solid tantalum
* Discharges C1 if output is shorted to ground

High Stability 10V Regulator

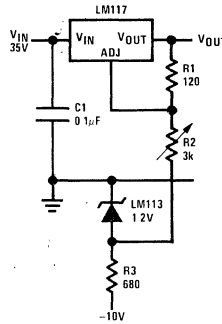


High Current Adjustable Regulator

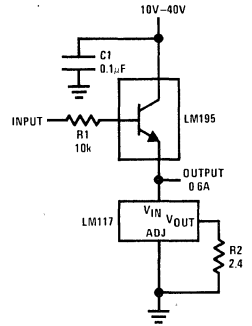


† Solid tantalum
* Minimum load current = 30 mA
‡ Optional—improves ripple rejection

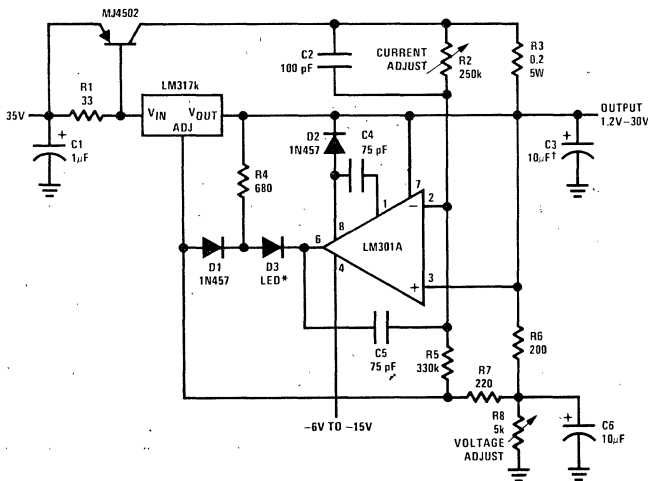
0 to 30V Regulator



Power Follower

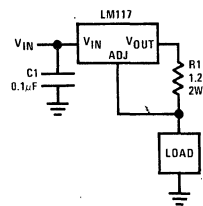


5A Constant Voltage/Constant Current Regulator

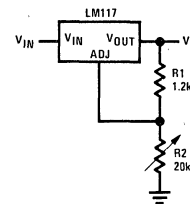


† Solid tantalum
* Lights in constant current mode

1A Current Regulator



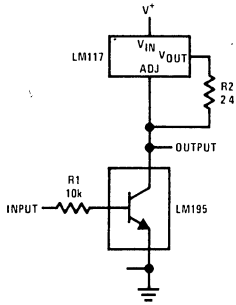
1.2V-20V Regulator with Minimum Program Current



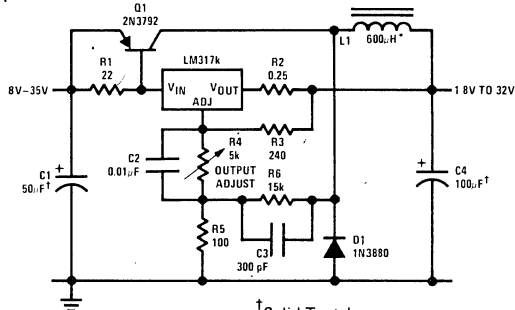
* Minimum load current ≈ 4 mA

Typical Applications (Continued)

High Gain Amplifier

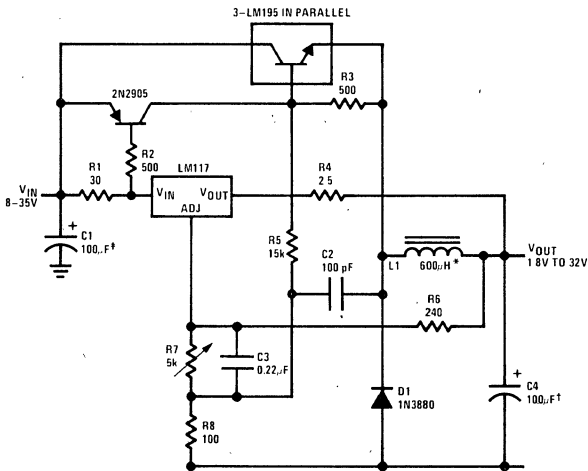


Low Cost 3A Switching Regulator



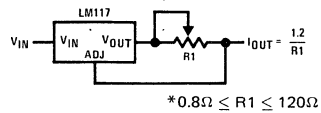
† Solid Tantalum
* Core—Arnold A-254168-2 60 turns

4A Switching Regulator with Overload Protection



† Solid Tantalum
* Core Arnold A-254168-2 60 turns

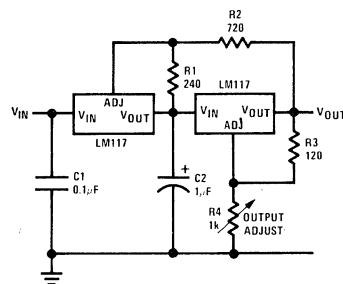
Precision Current Limiter



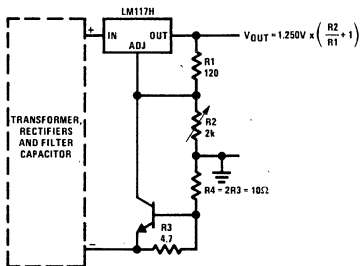
$$I_{OUT} = \frac{1.2}{R1}$$

* $0.8\Omega \leq R1 \leq 120\Omega$

Tracking Preregulator

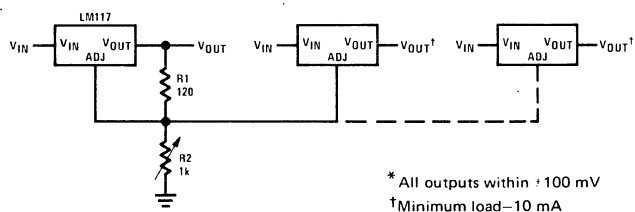


Adjustable Regulator with Current Limiter



Short circuit current is approximately 600 mV/R3, or 120 mA (compared to LM117H's 1 ampere current limit)
At 50 mA output only 3/4V of drop occurs in R3 and R4

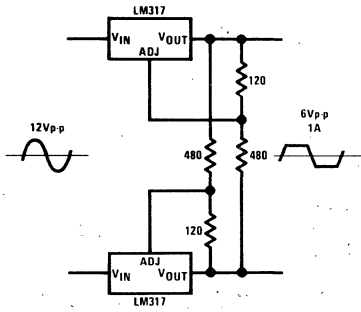
Adjusting Multiple On-Card Regulators with Single Control*



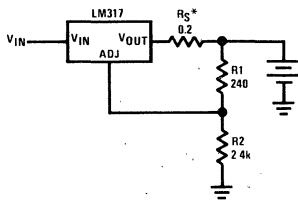
* All outputs within ±100 mV
† Minimum load—10 mA

Typical Applications (Continued)

AC Voltage Regulator

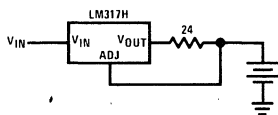


12V Battery Charger

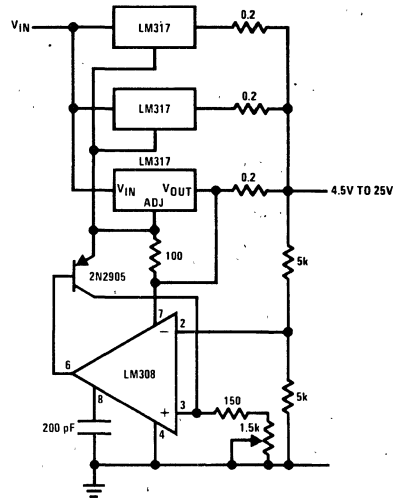


* R_S —sets output impedance of charger $Z_{OUT} = R_S \left(1 + \frac{R_2}{R_1} \right)$
Use of R_S allows low charging rates with fully charged battery.

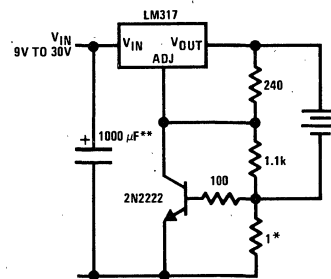
50 mA Constant Current Battery Charger



Adjustable 4A Regulator



Current Limited 6V Charger

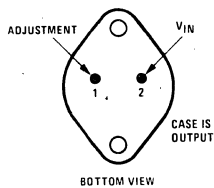


*Sets peak current (0.6A for 1Ω)

**1000 μF is recommended to filter out any input transients.

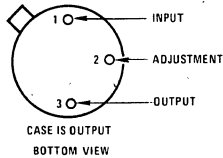
Connection Diagrams

**(TO-3 Steel)
Metal Can Package**



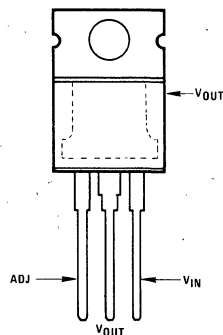
Order Number:
LM117K STEEL
LM217K STEEL
LM317K STEEL
See NS Package K02A

**(TO-39)
Metal Can Package**



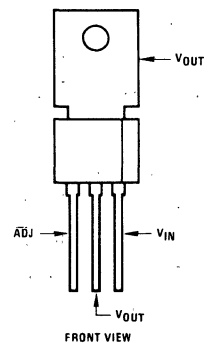
Order Number:
LM117H
LM217H
LM317H
See NS Package H03A

**(TO-220)
Plastic Package**



Order Number:
LM317T
See NS Package T03B

**(TO-202)
Plastic Package**



Order Number:
LM317MP
See NS Package P03A
TAB Formed Devices
LM317MP TB
See NS Package P03E

LM117HV/LM217HV/LM317HV High Voltage 3-Terminal Adjustable Regulator

General Description

The LM117HV/LM217HV/LM317HV are adjustable 3-terminal positive voltage regulators capable of supplying in excess of 1.5A over a 1.2V to 57V output range. They are exceptionally easy to use and require only two external resistors to set the output voltage. Further, both line and load regulation are better than standard fixed regulators. Also, the LM117HV is packaged in standard transistor packages which are easily mounted and handled.

In addition to higher performance than fixed regulators, the LM117HV series offers full overload protection available only in IC's. Included on the chip are current limit, thermal overload protection and safe area protection. All overload protection circuitry remains fully functional even if the adjustment terminal is disconnected.

Features

- Adjustable output down to 1.2V
- Guaranteed 1.5A output current
- Line regulation typically 0.01%/V
- Load regulation typically 0.1%
- Current limit constant with temperature
- 100% electrical burn-in
- Eliminates the need to stock many voltages
- Standard 3-lead transistor package
- 80 dB ripple rejection

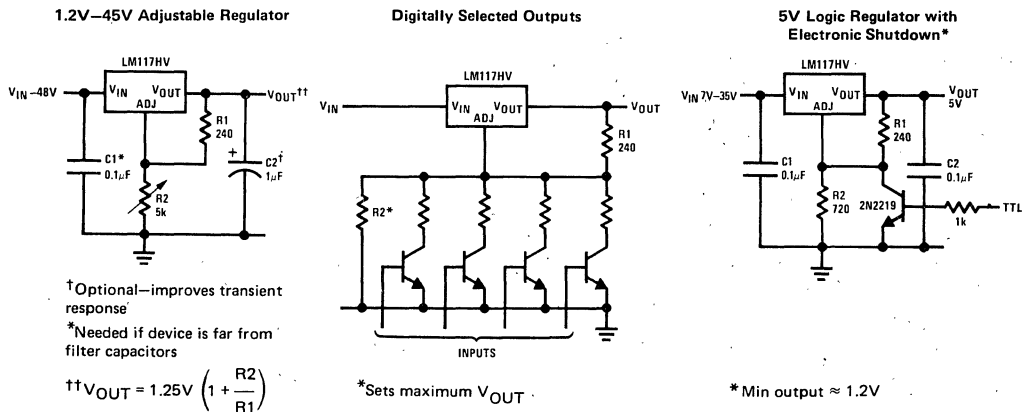
Normally, no capacitors are needed unless the device is situated far from the input filter capacitors in which case an input bypass is needed. An optional output capacitor can be added to improve transient response. The adjustment terminal can be bypassed to achieve very high ripple rejections ratios which are difficult to achieve with standard 3-terminal regulators.

Besides replacing fixed regulators, the LM117HV is useful in a wide variety of other applications. Since the regulator is "floating" and sees only the input-to-output differential voltage, supplies of several hundred volts can be regulated as long as the maximum input to output differential is not exceeded.

Also, it makes an especially simple adjustable switching regulator, a programmable output regulator, or by connecting a fixed resistor between the adjustment and output, the LM117HV can be used as a precision current regulator. Supplies with electronic shutdown can be achieved by clamping the adjustment terminal to ground which programs the output to 1.2V where most loads draw little current.

The LM117HVK STEEL, LM217HVK STEEL, and LM317HVK STEEL are packaged in standard TO-3 transistor packages while the LM117HVH, LM217HVH and LM317HVH are packaged in a solid Kovar base TO-5 transistor package. The LM117HV is rated for operation from -55°C to +150°C, the LM217HV from -25°C to +150°C and the LM317HV from 0°C to +125°C.

Typical Applications



Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input–Output Voltage Differential | 60V |
| Operating Junction Temperature Range | |
| LM117HV | –55°C to +150°C |
| LM217HV | –25°C to +150°C |
| LM317HV | 0°C to +125°C |
| Storage Temperature | –65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM117HV/217HV | | | LM317HV | | | UNITS |
|---|--|---------------|-------|------|---------|-------|------|--------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{\text{IN}} - V_{\text{OUT}} \leq 60\text{V}$ (Note 2) | | 0.01 | 0.02 | | 0.01 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$ $V_{\text{OUT}} \leq 5\text{V}$, (Note 2) $V_{\text{OUT}} \geq 5\text{V}$, (Note 2) | | 5 | 15 | | 5 | 25 | mV |
| | | | 0.1 | 0.3 | | 0.1 | 0.5 | % |
| Thermal Regulation | $T = 10\text{ns}$ | | | | | | | %/W |
| Adjustment Pin Current | | | 50 | 100 | | 50 | 100 | μA |
| Adjustment Pin Current Change | $10\text{mA} \leq I_L \leq I_{\text{MAX}}$ $3.0\text{V} \leq (V_{\text{IN}} - V_{\text{OUT}}) \leq 60\text{V}$ | | 0.2 | 5 | | 0.2 | 5 | μA |
| Reference Voltage | $3 \leq (V_{\text{IN}} - V_{\text{OUT}}) \leq 60\text{V}$, (Note 3) $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$, $P \leq P_{\text{MAX}}$ | 1.20 | 1.25 | 1.30 | 1.20 | 1.25 | 1.30 | V |
| Line Regulation | $3\text{V} \leq V_{\text{IN}} - V_{\text{OUT}} \leq 60\text{V}$, (Note 2) | | 0.02 | 0.05 | | 0.02 | 0.07 | %/V |
| Load Regulation | $10\text{mA} \leq I_{\text{OUT}} \leq I_{\text{MAX}}$, (Note 2) $V_{\text{OUT}} \leq 5\text{V}$ $V_{\text{OUT}} \geq 5\text{V}$ | | 20 | 50 | | 20 | 70 | mV |
| | | | 0.3 | 1 | | 0.3 | 1.5 | % |
| Temperature Stability | $T_{\text{MIN}} \leq T_j \leq T_{\text{MAX}}$ | | 1 | | | 1 | | % |
| Minimum Load Current | $V_{\text{IN}} - V_{\text{OUT}} = 60\text{V}$ | | 3.5 | 7 | | 3.5 | 12 | mA |
| Current Limit | $V_{\text{IN}} - V_{\text{OUT}} \leq 15\text{V}$ K Package H Package | | 1.5 | 2.2 | | 1.5 | 2.2 | A |
| | | | 0.5 | 0.8 | | 0.5 | 0.8 | A |
| | $V_{\text{IN}} - V_{\text{OUT}} = 60\text{V}$ K Package H Package | | | 0.1 | | | 0.1 | A |
| | | | | 0.03 | | | 0.03 | A |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{Hz} \leq f \leq 10\text{kHz}$ | | 0.003 | | | 0.003 | | % |
| Ripple Rejection Ratio | $V_{\text{OUT}} = 10\text{V}$, $f = 120\text{Hz}$ $\text{CADJ} = 10\mu\text{F}$ | | 65 | | | 65 | | dB |
| | | 66 | 80 | | 66 | 80 | | dB |
| Long-Term Stability | $T_A = 125^\circ\text{C}$ | | 0.3 | 1 | | 0.3 | 1 | % |
| Thermal Resistance, Junction to Case | H Package | | 12 | 15 | | 12 | 15 | $^\circ\text{C/W}$ |
| | K Package | | 2.3 | 3 | | 2.3 | 3 | $^\circ\text{C/W}$ |

Note 1: Unless otherwise specified, these specifications apply $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM117HV, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM217HV and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM317HV; $V_{\text{IN}} - V_{\text{OUT}} = 5\text{V}$ and $I_{\text{OUT}} = 0.1\text{A}$ for the TO-5 package and $I_{\text{OUT}} = 0.5\text{A}$ for the TO-3 package. Although power dissipation is internally limited, these specifications are applicable for power dissipations of 2W for the TO-5 and 20W for the TO-3. I_{MAX} is 1.5A for the TO-3 and 0.5A for the TO-5 package.

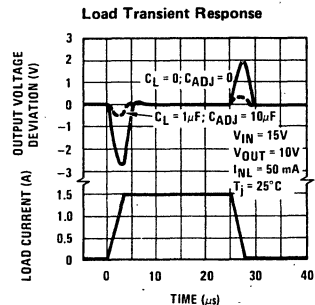
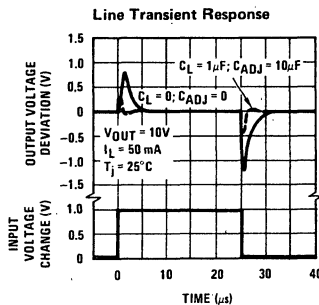
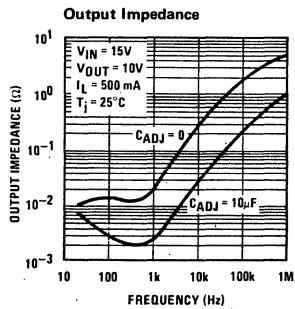
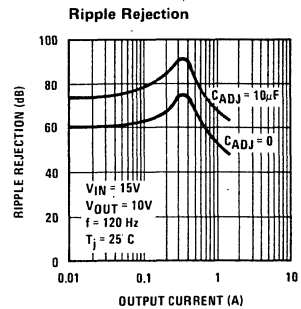
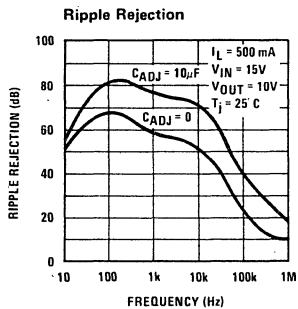
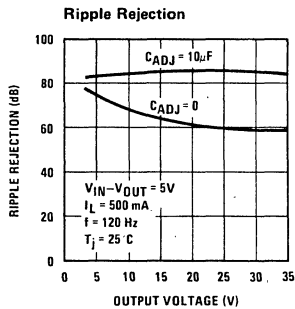
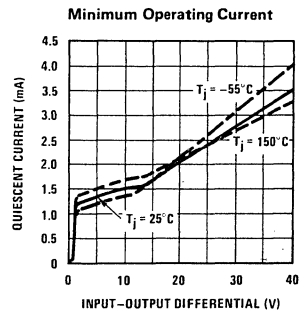
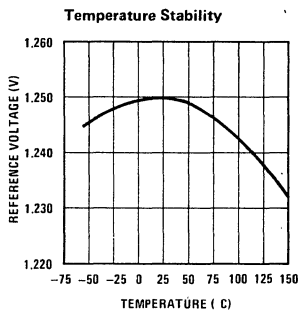
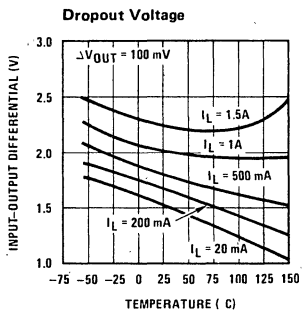
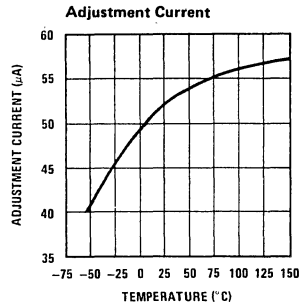
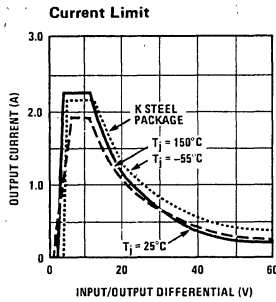
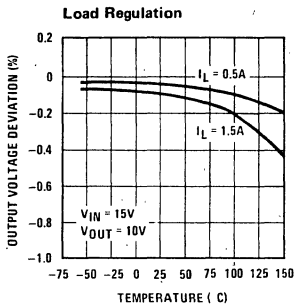
Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. Pulse testing with low duty cycle is used.

Note 3: Selected devices with tightened tolerance reference voltage available.

Typical Performance Characteristics (K and T Packages)

LM117HV/LM217HV/LM317HV

1



Application Hints

In operation, the LM117HV develops a nominal 1.25V reference voltage, V_{REF} , between the output and adjustment terminal. The reference voltage is impressed across program resistor $R1$ and, since the voltage is constant, a constant current I_1 then flows through the output set resistor $R2$, giving an output voltage of

$$V_{OUT} = V_{REF} \left(1 + \frac{R2}{R1} \right) + I_{ADJ} R2$$

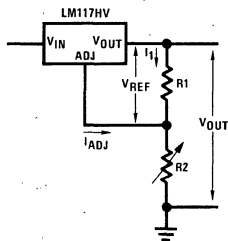


FIGURE 1.

Since the 100 μ A current from the adjustment terminal represents an error term, the LM117HV was designed to minimize I_{ADJ} and make it very constant with line and load changes. To do this, all quiescent operating current is returned to the output establishing a minimum load current requirement. If there is insufficient load on the output, the output will rise.

External Capacitors

An input bypass capacitor is recommended. A 0.1 μ F disc or 1 μ F solid tantalum on the input is suitable input bypassing for almost all applications. The device is more sensitive to the absence of input bypassing when adjustment or output capacitors are used but the above values will eliminate the possibility of problems.

The adjustment terminal can be bypassed to ground on the LM117HV to improve ripple rejection. This bypass capacitor prevents ripple from being amplified as the output voltage is increased. With a 10 μ F bypass capacitor 80 dB ripple rejection is obtainable at any output level. Increases over 10 μ F do not appreciably improve the ripple rejection at frequencies above 120 Hz. If the bypass capacitor is used, it is sometimes necessary to include protection diodes to prevent the capacitor from discharging through internal low current paths and damaging the device.

In general, the best type of capacitors to use are solid tantalum. Solid tantalum capacitors have low impedance even at high frequencies. Depending upon capacitor construction, it takes about 25 μ F in aluminum electrolytic to equal 1 μ F solid tantalum at high frequencies. Ceramic capacitors are also good at high frequencies; but some types have a large decrease in capacitance at frequencies around 0.5 MHz. For this reason, 0.01 μ F disc may seem to work better than a 0.1 μ F disc as a bypass.

Although the LM117HV is stable with no output capacitors, like any feedback circuit, certain values of external capacitance can cause excessive ringing. This occurs with values between 500 pF and 5000 pF. A 1 μ F solid tantalum (or 25 μ F aluminum electrolytic) on the output swamps this effect and insures stability.

Load Regulation

The LM117HV is capable of providing extremely good load regulation but a few precautions are needed to obtain maximum performance. The current set resistor connected between the adjustment terminal and the output terminal (usually 240 Ω) should be tied directly to the output of the regulator rather than near the load. This eliminates line drops from appearing effectively in series with the reference and degrading regulation. For example, a 15V regulator with 0.05 Ω resistance between the regulator and load will have a load regulation due to line resistance of 0.05 Ω x I_L . If the set resistor is connected near the load the effective line resistance will be 0.05 Ω (1 + R2/R1) or in this case, 11.5 times worse.

Figure 2 shows the effect of resistance between the regulator and 240 Ω set resistor.

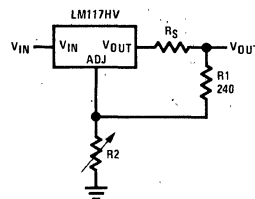


FIGURE 2. Regulator with Line Resistance in Output Lead

With the TO-3 package, it is easy to minimize the resistance from the case to the set resistor, by using two separate leads to the case. However, with the TO-5 package, care should be taken to minimize the wire length of the output lead. The ground of $R2$ can be returned near the ground of the load to provide remote ground sensing and improve load regulation.

Protection Diodes

When external capacitors are used with any IC regulator it is sometimes necessary to add protection diodes to prevent the capacitors from discharging through low current points into the regulator. Most 10 μ F capacitors have low enough internal series resistance to deliver 20A spikes when shorted. Although the surge is short, there is enough energy to damage parts of the IC.

When an output capacitor is connected to a regulator and the input is shorted, the output capacitor will discharge into the output of the regulator. The discharge

Application Hints (Continued)

current depends on the value of the capacitor, the output voltage of the regulator, and the rate of decrease of V_{IN} . In the LM117HV, this discharge path is through a large junction that is able to sustain 15A surge with no problem. This is not true of other types of positive regulators. For output capacitors of $25\mu\text{F}$ or less, there is no need to use diodes.

The bypass capacitor on the adjustment terminal can discharge through a low current junction. Discharge

occurs when *either* the input or output is shorted. Internal to the LM117HV is a 50Ω resistor which limits the peak discharge current. No protection is needed for output voltages of 25V or less and $10\mu\text{F}$ capacitance. *Figure 3* shows an LM117HV with protection diodes included for use with outputs greater than 25V and high values of output capacitance.

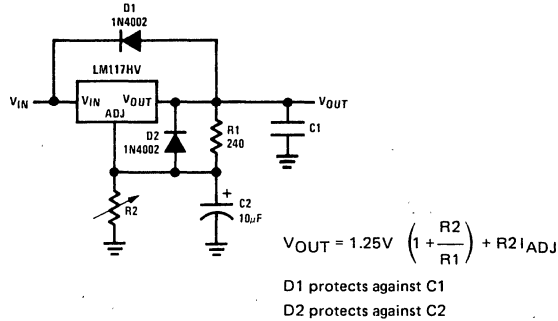
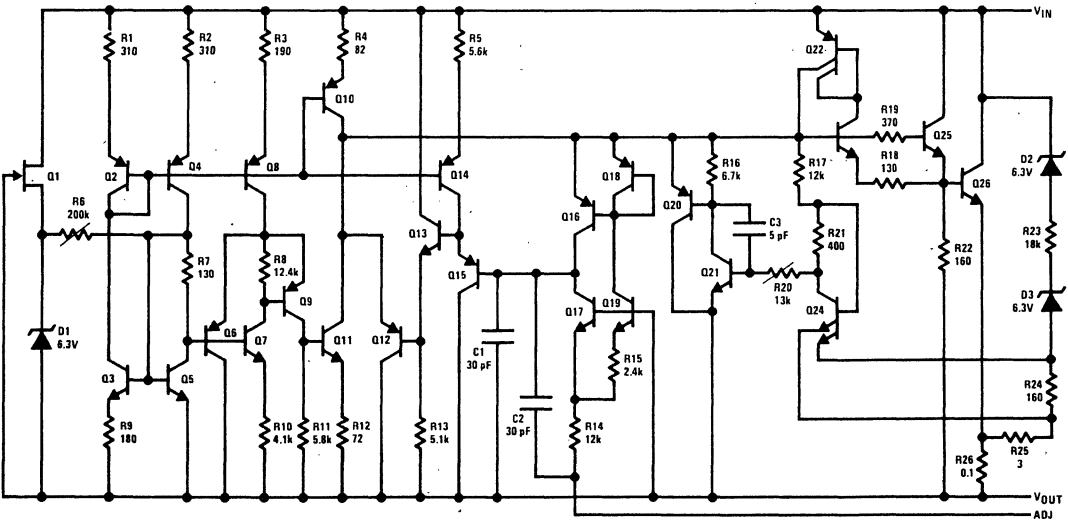


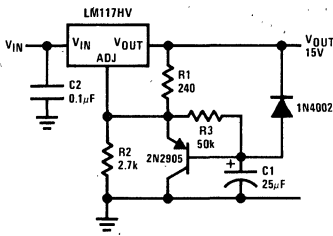
FIGURE 3. Regulator with Protection Diodes

Schematic Diagram

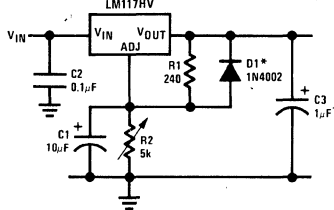


Typical Applications (Continued)

Slow Turn-On 15V Regulator

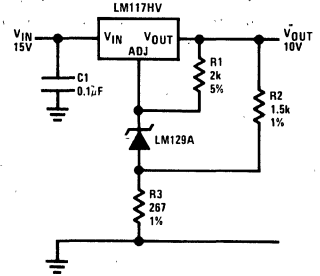


Adjustable Regulator with Improved Ripple Rejection

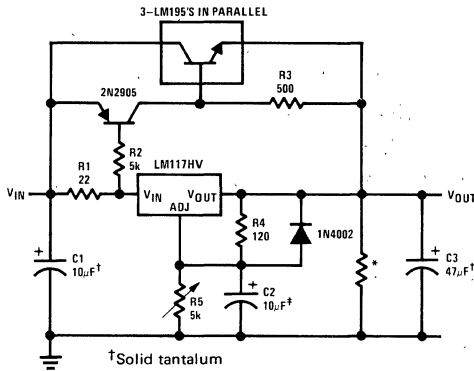


†Solid tantalum
*Discharges C1 if output is shorted to ground

High Stability 10V Regulator

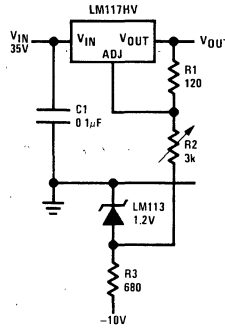


High Current Adjustable Regulator

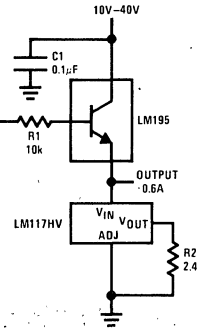


†Solid tantalum
*Minimum load current = 30 mA
‡Optional—improves ripple rejection

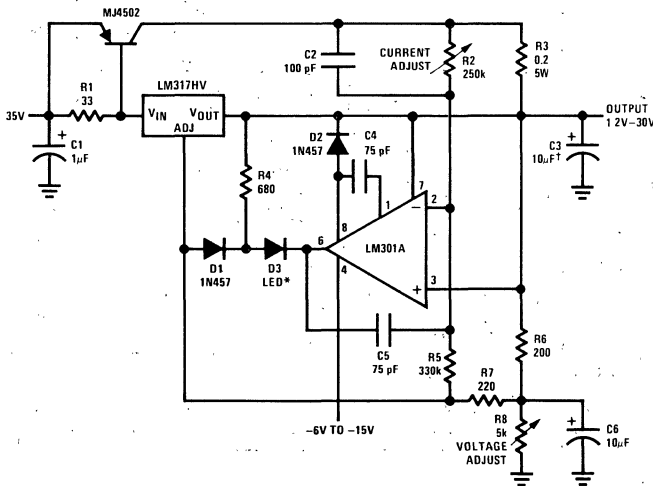
0 to 30V Regulator



Power Follower

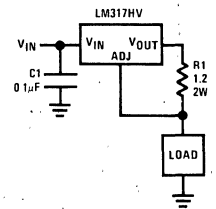


5A Constant Voltage/Constant Current Regulator

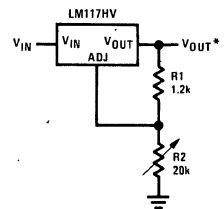


†Solid tantalum
*Lights in constant current mode

1A Current Regulator



1.2V-20V Regulator with Minimum Program Current



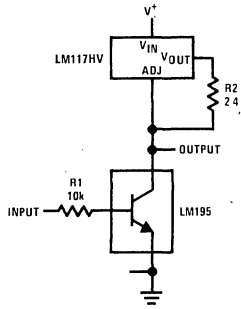
*Minimum load current ≈ 4 mA

Typical Applications (Continued)

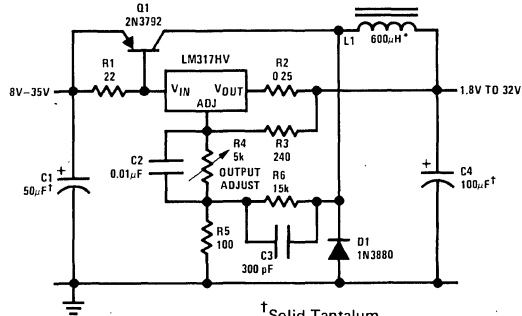
LM117HV/LM217HV/LM317HV

1

High Gain Amplifier



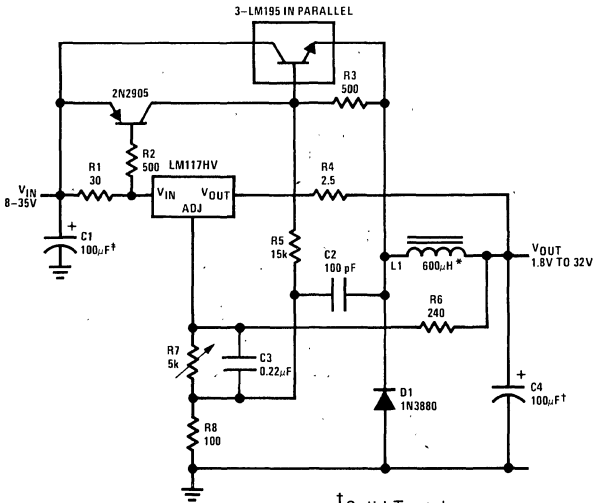
Low Cost 3A Switching Regulator



† Solid Tantalum

*Core—Arnold A-254168-2 60 turns

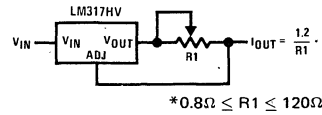
4A Switching Regulator with Overload Protection



† Solid Tantalum

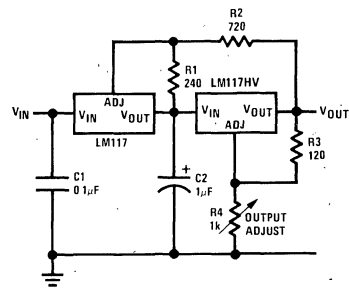
*Core Arnold A-254168-2 60 turns

Precision Current Limiter

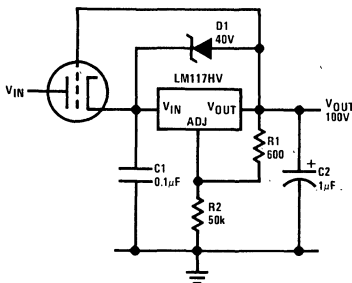


* $0.8\Omega \leq R1 \leq 120\Omega$

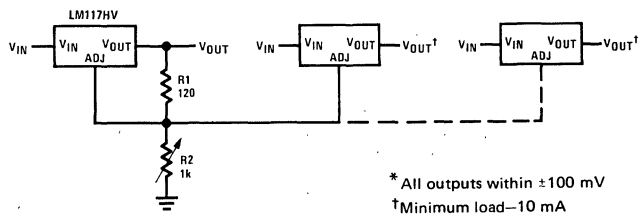
Tracking Preregulator



High Voltage Regulator



Adjusting Multiple On-Card Regulators with Single Control*

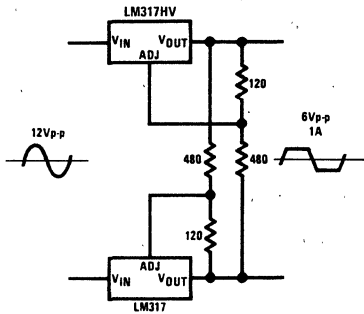


* All outputs within ± 100 mV

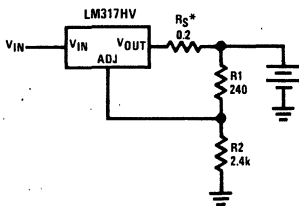
† Minimum load—10 mA

Typical Applications (Continued)

AC Voltage Regulator

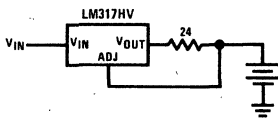


12V Battery Charger

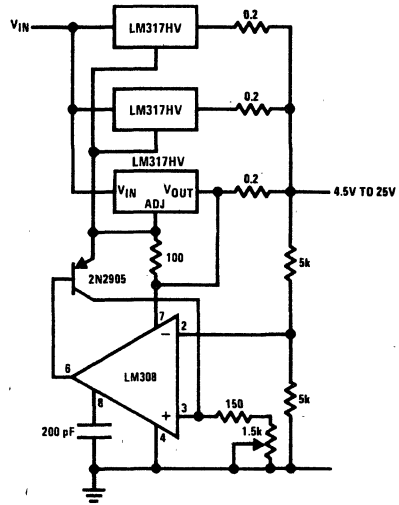


* R_S —sets output impedance of charger $Z_{OUT} = R_S \left(1 + \frac{R_2}{R_1}\right)$
 Use of R_S allows low charging rates with fully charged battery.

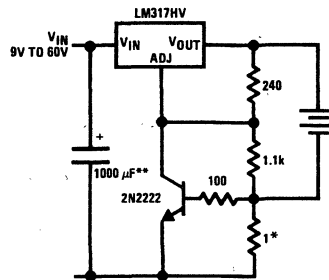
50 mA Constant Current Battery Charger



Adjustable 4A Regulator



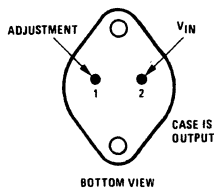
Current Limited 6V Charger



*Sets peak current (0.6A for 1Ω)
 **1000 μF is recommended to filter out any input transients.

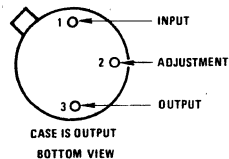
Connection Diagrams

(TO-3 Steel)
 Metal Can Package



Order Number LM117HVK STEEL,
 LM217HVK STEEL, or
 LM317HVK STEEL
 See Package K02A

(TO-39)
 Metal Can Package



Order Number LM117HVH,
 LM217HVH, or LM317HVH
 See Package H03A

LM120 Series 3-Terminal Negative Regulators

General Description

The LM120 Series are three-terminal negative regulators with a fixed output voltage of $-5V$, $-12V$, and $-15V$, and up to 1.5A load current capability. These devices need only one external component—a compensation capacitor at the output, making them easy to apply. Worst case guarantees on output voltage deviation due to any combination of line, load or temperature variation assure satisfactory system operation. Where other voltages are required, the LM137 Series provides an output voltage range of $-1.2V$ to $-47V$.

Exceptional effort has been made to make the LM120 Series immune to overload conditions. The regulators have current limiting which is independent of temperature, combined with thermal overload protection. Internal current limiting protects against momentary faults while thermal shutdown prevents junction temperatures from exceeding safe limits during prolonged overloads.

Although primarily intended for fixed output voltage applications, the LM120 Series may be programmed for higher output voltages with a simple resistive divider. The low quiescent drain current of the devices allows this technique to be used with good regulation.

Features

- Preset output voltage error less than $\pm 3\%$
- Preset current limit
- Internal thermal shutdown
- Operates with input-output voltage differential down to 1V
- Excellent ripple rejection
- Low temperature drift
- Easily adjustable to higher output voltage

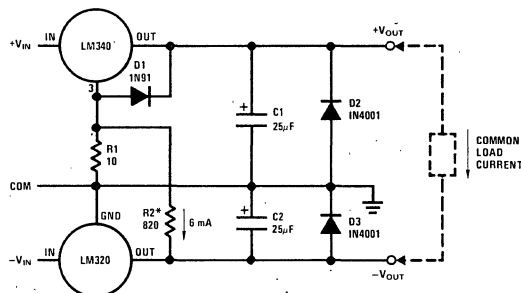
LM120 Series Packages and Power Capability

| DEVICE | PACKAGE | RATED POWER DISSIPATION | DESIGN LOAD CURRENT |
|----------------|---------|-------------------------|---------------------|
| LM120 LM320 | TO-3 | 20W | 1.5A |
| | TO-5 | 2W | 0.5A |
| LM320T | TO-220 | 15W | 1.5A |
| LM320M | TO-202 | 7.5W | 0.5A |
| LM320ML* | TO-202 | 7.5W | 0.25A |
| LM320L* | TO-92 | 1.2W | 0.1A |

*Electrical specifications shown on separate data sheet

Typical Applications

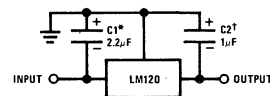
Preventing Positive Regulator Latch-Up



R1 & D1 allow the positive regulator to "start-up" when V_{IN} is delayed relative to V_{OUT} and a heavy load is drawn between the outputs. Without R1 & D1, most three-terminal regulators will not start with heavy (0.1A-1A) load current flowing to the negative regulator, even though the positive output is clamped by D2

*R2 is optional. Ground pin current from the positive regulator flowing through R1 will increase $+V_{OUT} \approx 60\text{ mV}$ if R2 is omitted.

Fixed Regulator

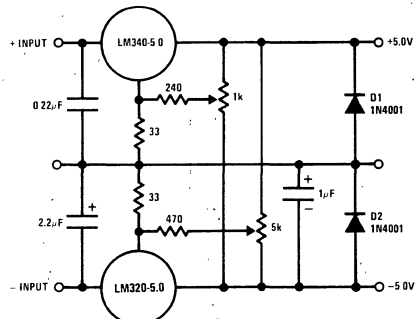


*Required if regulator is separated from filter capacitor by more than 3". For value given, capacitor must be solid tantalum. 25µF aluminum electrolytic may be substituted.

†Required for stability. For value given, capacitor must be solid tantalum. 25µF aluminum electrolytic may be substituted.

For output capacitance in excess of 100µF, a high current diode from input to output (1N4001, etc.) will protect the regulator from momentary input shorts.

Dual Trimmed Supply



- 5 VOLT REGULATORS (Note 3)

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally Limited |
| Input Voltage | -25V |
| Input-Output Voltage Differential | 25V |
| Junction Temperatures | See Note 1 |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

| ORDER NUMBERS | | METAL CAN PACKAGE | | | | | | | | | POWER PLASTIC PACKAGE | | | | | | UNITS | | | | | | | |
|---|---|-------------------|-----|-------|-------------|-----|-------|------------|------|-------|-----------------------|------|-------|-------------|------|-------|--------------|-------------|------|-------|------|------|-------|---|
| | | LM120K-5.0 | | | LM320K-5.0 | | | LM120H-5.0 | | | LM320H-5.0 | | | LM320T-5.0 | | | | LM320MP-5.0 | | | | | | |
| | | (TO-3) | | | (TO-3) | | | (TO-5) | | | (TO-5) | | | (TO-220) | | | | (TO-202) | | | | | | |
| DESIGN OUTPUT CURRENT (I _D) DEVICE DISSIPATION (P _D) | | 1.5A 20W | | | 1.5A 20W | | | 0.5A 2W | | | 0.5A 2W | | | 1.5A 15W | | | 0.5A 7.5W | | | | | | | |
| PARAMETER | CONDITIONS (NOTE 1) | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | | | | |
| Output Voltage | T _J = 25°C, V _{IN} = 10V, I _{LOAD} = 5 mA | -5.1 | -5 | -4.9 | -5.2 | -5 | -4.8 | -5.1 | -5.0 | -4.9 | -5.2 | -5.0 | -4.8 | -5.2 | -5.0 | -4.8 | -5.2 | -5.0 | -4.8 | V | | | | |
| Line Regulation | T _J = 25°C, I _{LOAD} = 5 mA, V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 10 | 25 | | 10 | 40 | | 10 | 25 | | 10 | 40 | | 10 | 40 | | 10 | 40 | mV | | | | |
| Input Voltage | | -25 | | -7 | -25 | | -7 | -25 | | -7 | -25 | | -7 | -25 | | -7.5 | -25 | | -7.5 | V | | | | |
| Ripple Rejection | f = 120 Hz | 54 | 64 | | 54 | 64 | | 54 | 64 | | 54 | 64 | | 54 | 64 | | 54 | 64 | | 54 | 64 | dB | | |
| Load Regulation, (Note 2) | T _J = 25°C, V _{IN} = 10V, 5 mA ≤ I _{LOAD} ≤ I _D | | 50 | 75 | | 50 | 100 | | 30 | 50 | | 30 | 50 | | 50 | 100 | | 40 | 100 | | 40 | 100 | mV | |
| Output Voltage, (Note 1) | -7.5V ≤ V _{IN} ≤ V _{MAX} , 5 mA ≤ I _{LOAD} ≤ I _D , P ≤ P _D | -5.20 | | -4.80 | -5.25 | | -4.75 | -5.20 | | -4.80 | -5.25 | | -4.75 | -5.25 | | -4.75 | -5.25 | | -5.0 | -4.75 | | -5.0 | -4.75 | V |
| Quiescent Current | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | mA | |
| Quiescent Current Change | T _J = 25°C V _{MIN} ≤ V _{IN} ≤ V _{MAX} 5 mA ≤ I _{LOAD} ≤ I _D | | 0.1 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.4 | | 0.05 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.3 | | 0.05 | 0.3 | mA | |
| Output Noise Voltage | T _A = 25°C, C _L = 1μF, I _L = 5 mA, V _{IN} = 10V, 10 Hz ≤ f ≤ 100 kHz | | 150 | | | 150 | | | 150 | | | 150 | | | 150 | | | | 150 | | | 150 | μV | |
| Long Term Stability | | | 5 | 50 | | 5 | 50 | | 5 | 50 | | 5 | 50 | | 10 | | | 10 | | | 10 | | mV | |
| Thermal Resistance | | | | | | | | | | | | | | | | | | | | | | | | |
| Junction to Case | | | | 3 | | | 3 | | | 15 | | | 15 | | 4 | | | 12 | | | | | °C/W | |
| Junction to Ambient | | | | 35 | | | 35 | | | 150 | | | 150 | | 50 | | | 70 | | | | | °C/W | |

Note 1: This specification applies over -55°C ≤ T_J ≤ +150°C for the LM120, and 0°C ≤ T_J ≤ +125°C for the LM320.

Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. To ensure constant junction temperature, low duty cycle, pulse testing is used. The LM120/LM320 series does have low thermal feedback, improving line and load regulation. On all other tests, even though power dissipation is internally limited, electrical specifications apply only up to P_D.

Note 3: For -5V 3 amp regulators, see LM145 data sheet.

- 12 VOLT REGULATORS

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally Limited |
| Input Voltage | -35V |
| Input-Output Voltage Differential | 30V |
| Junction Temperatures | See Note 1 |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

| ORDER NUMBERS | | METAL CAN PACKAGE | | | | | | | | | | | | POWER PLASTIC PACKAGE | | | | | | UNITS | |
|---|---|---------------------|-----|-------|---------------------|-----|-------|---------------------|------|-------|---------------------|------|-------|-----------------------|-----|-------|------------------------|------|-------|-------|----|
| | | LM120K-12 (TO-3) | | | LM320K-12 (TO-3) | | | LM120H-12 (TO-5) | | | LM320H-12 (TO-5) | | | LM320T-12 (TO-220) | | | LM320MP-12 (TO-202) | | | | |
| DESIGN OUTPUT CURRENT (I _D) DEVICE DISSIPATION (P _D) | | 1A 20W | | | 1A 20W | | | 0.2A 2W | | | 0.2A 2W | | | 1A 15W | | | 0.5A 7.5W | | | | |
| PARAMETER | CONDITIONS (NOTE 1) | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| Output Voltage | T _J = 25°C, V _{IN} = 17V, I _{LOAD} = 5 mA | -12.3 | -12 | -11.7 | -12.4 | -12 | -11.6 | -12.3 | -12 | -11.7 | -12.4 | -12 | -11.6 | -12.4 | -12 | -11.6 | -12.5 | -12 | -11.5 | V | |
| Line Regulation | T _J = 25°C, I _{LOAD} = 5 mA, V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 4 | 10 | | 4 | 20 | | 4 | 10 | | 4 | 20 | | 4 | 20 | | 4 | 24 | mV | |
| Input Voltage | | -32 | | -14 | -32 | | -14 | -32 | | -14 | -32 | | -14 | -32 | | -14.5 | -32 | | -14.5 | V | |
| Ripple Rejection | f = 120 Hz | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | | 100 | dB |
| Load Regulation, (Note 2) | T _J = 25°C, V _{IN} = 17V, 5 mA ≤ I _{LOAD} ≤ I _D | | 30 | 80 | | 30 | 80 | | 10 | 25 | | 10 | 40 | | 30 | 80 | | 40 | 100 | mV | |
| Output Voltage, (Note 1) | 14.5V ≤ V _{IN} ≤ V _{MAX} , 5 mA ≤ I _{LOAD} ≤ I _D , P ≤ P _D | -12.5 | | -11.5 | -12.6 | | -11.4 | -12.5 | | -11.5 | -12.6 | | -11.4 | -12.6 | | -11.4 | -12.6 | | -11.4 | V | |
| Quiescent Current | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 | mA | |
| Quiescent Current Change | T _J = 25°C V _{MIN} ≤ V _{IN} ≤ V _{MAX} 5 mA ≤ I _{LOAD} ≤ I _D | | 0.1 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.4 | | 0.05 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.3 | mA | |
| Output Noise Voltage | T _A = 25°C, C _L = 1μF, I _L = 5 mA, V _{IN} = 17V, 10 Hz ≤ f ≤ 100 kHz | | 400 | | 400 | | | | 400 | | 400 | | | | 400 | | 400 | | | μV | |
| Long Term Stability | | | 12 | 120 | | 12 | 120 | | 12 | 120 | | 12 | 120 | | 24 | | 24 | | 24 | mV | |
| Thermal Resistance | | | | | | | | | | | | | | | | | | | | | |
| Junction to Case | | | | 3 | | | 3 | | | 15 | | | 15 | | 4 | | | | 12 | °C/W | |
| Junction to Ambient | | | | 35 | | | 35 | | | 150 | | | 150 | | 50 | | | | 70 | °C/W | |

Note 1: This specification applies over -55°C ≤ T_J ≤ +150°C for the LM120, and 0°C ≤ T_J ≤ +125°C for the LM320.

Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. To ensure constant junction temperature, low duty cycle, pulse testing is used. The LM120/LM320 series does have low thermal feedback, improving line and load regulation. On all other tests, even though power dissipation is internally limited, electrical specifications apply only up to P_D.

- 15 VOLT REGULATORS

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally Limited |
| Input Voltage | |
| LM120/LM320 | -40V |
| LM320T/LM320MP | -35V |
| Input-Output Voltage Differential | 30V |
| Junction Temperatures | See Note 1 |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

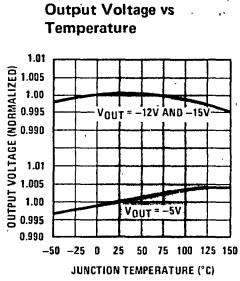
Electrical Characteristics

| ORDER NUMBERS | | METAL CAN PACKAGE | | | | | | | | | POWER PLASTIC PACKAGE | | | | | | UNITS | | |
|---|---|-------------------|-----|-------|-----------|-----|-------|------------|------|-------|-----------------------|------|-------|-----------|-----|-------|--------------|------------|-------|
| | | LM120K-15 | | | LM320K-15 | | | LM120H-15 | | | LM320H-15 | | | LM320T-15 | | | | LM320MP-15 | |
| DESIGN OUTPUT CURRENT (I _D) DEVICE DISSIPATION (P _D) | | 1A 20W | | | 1A 20W | | | 0.2A 2W | | | 0.2A 2W | | | 1A 15W | | | 0.5A 7.5W | | |
| PARAMETER | CONDITIONS (NOTE 1) | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |
| Output Voltage | T _J = 25°C, V _{IN} = 20V, I _{LOAD} = 5 mA | -15.3 | -15 | -14.7 | -15.4 | -15 | -14.6 | -15.3 | -15 | -14.7 | -15.4 | -15 | -14.6 | -15.5 | -15 | -14.5 | -15.6 | -15 | -14.4 |
| Line Regulation | T _J = 25°C, I _{LOAD} = 5 mA, V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 5 | 10 | | 5 | 20 | | 5 | 10 | | 5 | 20 | | 5 | 20 | | 5 | 30 |
| Input Voltage | | -35 | | -17 | -35 | | -17 | -35 | | -17 | -35 | | -17 | -35 | | -17.5 | -35 | | -17.5 |
| Ripple Rejection | f = 120 Hz | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | | 56 | 80 | |
| Load Regulation, (Note 2) | T _J = 25°C, V _{IN} = 20V, 5 mA ≤ I _{LOAD} ≤ I _D | | 30 | 80 | | 30 | 80 | | 10 | 25 | | 10 | 40 | | 30 | 80 | | 40 | 100 |
| Output Voltage, (Note 1) | 17.5V ≤ V _{IN} ≤ V _{MAX} , 5 mA ≤ I _{LOAD} ≤ I _D , P ≤ P _D | -15.5 | | -14.5 | -15.6 | | -14.4 | -15.5 | | -14.5 | -15.6 | | -14.4 | -15.7 | | -14.3 | -15.7 | | -14.3 |
| Quiescent Current | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 | | 2 | 4 |
| Quiescent Current Change | T _J = 25°C | | | | | | | | | | | | | | | | | | |
| | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | 0.1 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.4 | | 0.05 | 0.4 | | 0.1 | 0.4 | | 0.05 | 0.3 |
| | 5 mA ≤ I _{LOAD} ≤ I _D | | 0.1 | 0.4 | | 0.1 | 0.4 | | 0.03 | 0.4 | | 0.03 | 0.4 | | 0.1 | 0.4 | | 0.04 | 0.25 |
| Output Noise Voltage | T _A = 25°C, C _L = 1μF, I _L = 5 mA, V _{IN} = 20V, 10 Hz ≤ f ≤ 100 kHz | | 400 | | 400 | | | 400 | | | 400 | | | 400 | | | 400 | | |
| Long Term Stability | | | 15 | 150 | | 15 | 150 | | 15 | 150 | | 15 | 150 | | 30 | | 30 | | 30 |
| Thermal Resistance | | | | | | | | | | | | | | | | | | | |
| Junction to Case | | | | 3 | | | 3 | | | 15 | | | 15 | | 4 | | | 12 | °C/W |
| Junction to Ambient | | | | 35 | | | 35 | | | 150 | | | 150 | | 50 | | | 70 | °C/W |

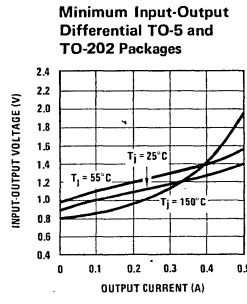
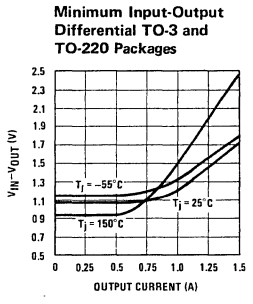
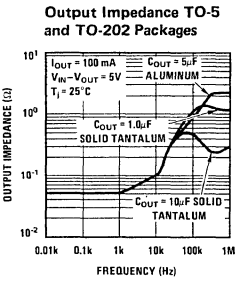
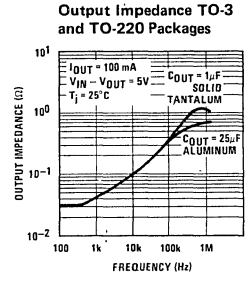
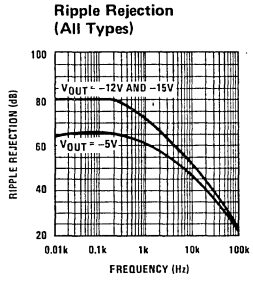
Note 1: This specification applies over -55°C ≤ T_J ≤ +150°C for the LM120, and 0°C ≤ T_J ≤ +125°C for the LM320.

Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. To ensure constant junction temperature, low duty cycle, pulse testing is used. The LM120/LM320 series does have low thermal feedback, improving line and load regulation. On all other tests, even though power dissipation is internally limited, electrical specifications apply only up to P_D.

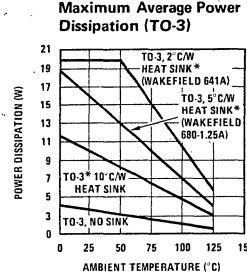
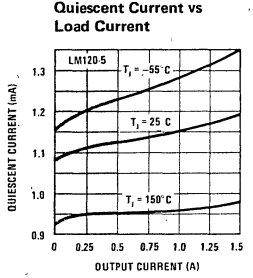
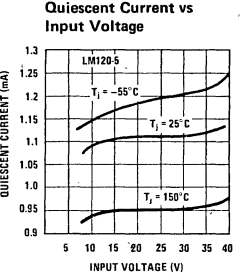
Typical Performance Characteristics



Note: Shaded portion refers to LM320 series regulators.

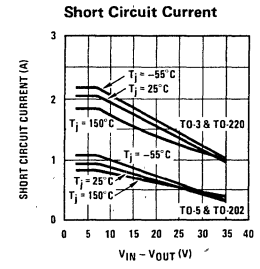
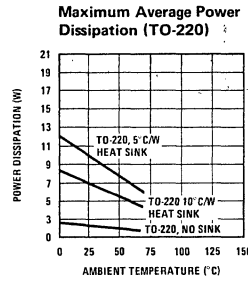
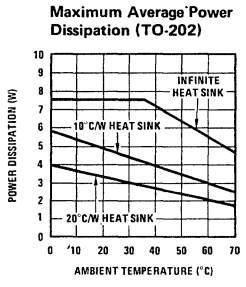
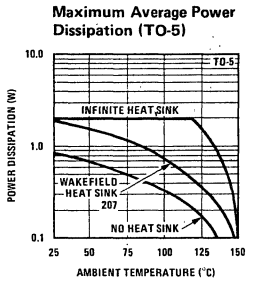


1



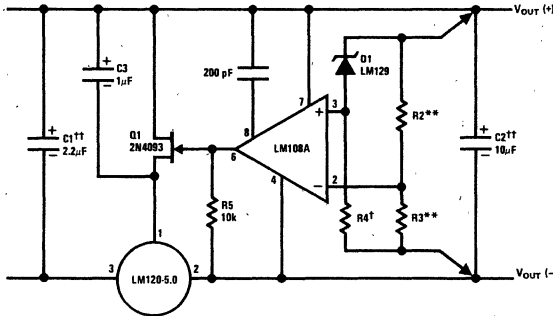
Note: Shaded area shows operating range of TO-5 and TO-202 packages.

*These curves for LM120 and LM220. Derate 25°C further for LM320.



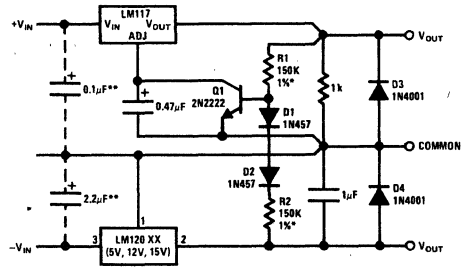
Typical Applications (Continued)

High Stability 1 Amp Regulator



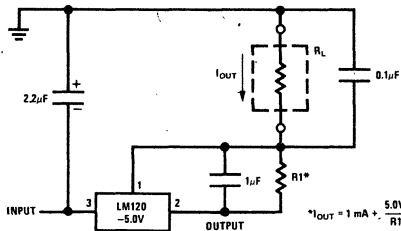
Load and line regulation <math><0.01\%</math> temperature stability <math><0.2\%</math>
 †Determines Zener current.
 ††Solid tantalum.
 An LM120-12 or LM120-15 may be used to permit higher input voltages, but the regulated output voltage must be at least -15V when using the LM120-12 and -18V for the LM120-15.
 **Select resistors to set output voltage. 2 ppm/C tracking suggested.

Wide Range Tracking Regulator



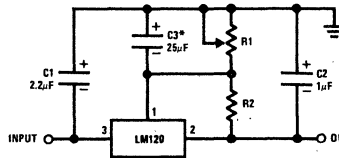
*Resistor tolerance of R1 and R2 determine matching of (+) and (-) inputs.
 **Necessary only if raw supply capacitors are more than 3" from regulators
 An LM308N array may substitute for Q1, D1 and D2 for better stability and tracking. In the array diode, transistors Q3 and Q4 (in parallel) make up Q2; similarly, Q1 and Q2 become D1 and Q3 replaces the 2N2222.

Current Source



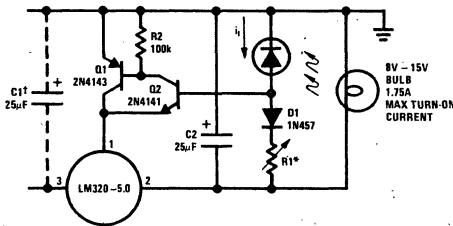
$I_{OUT} = 1 \text{ mA} \cdot \frac{5.0V}{R1}$

Variable Output

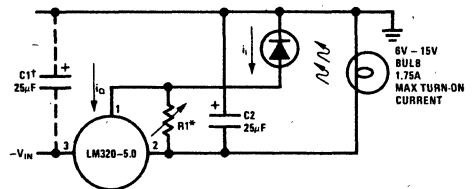


*Optional. Improves transient response and ripple rejection.
 $V_{OUT} = V_{SET} \cdot \frac{R1 + R2}{R2}$
 SELECT R2 AS FOLLOWS
 LM120-5 - 300Ω
 LM120-12 - 750Ω
 LM120-15 - 1K

Light Controllers Using Silicon Photo Cells



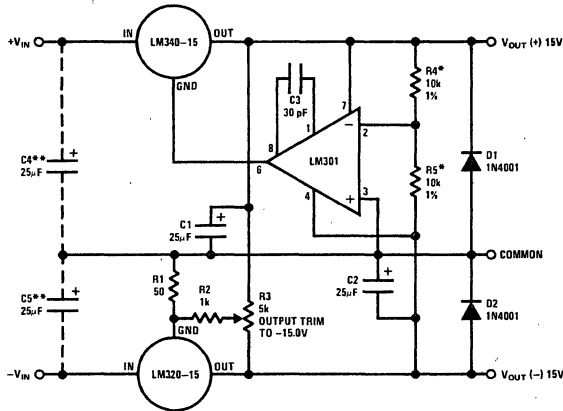
*Lamp brightness increases until $i_i = 5V/R1$ (i_i can be set as low as 1μA).
 †Necessary only if raw supply filter capacitor is more than 2" from LM320MP.



*Lamp brightness increases until $i_i = i_Q (\approx 1 \text{ mA}) + 5V/R1$.
 †Necessary only if raw supply filter capacitor is more than 2" from LM320.

Typical Applications (Continued)

±15V, 1 Amp Tracking Regulators



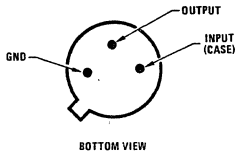
Performance (Typical)

| | | |
|---|----------------|----------------|
| Load Regulation at $\Delta I_L = 1A$ | 10 mV | 1 mV |
| Output Ripple, $C_{IN} = 3000\mu F, I_L = 1A$ | 100 μ Vrms | 100 μ Vrms |
| Temperature Stability | +50 mV | +50 mV |
| Output Noise 10 Hz $\leq f \leq$ 10 kHz | 150 μ Vrms | 150 μ Vrms |

*Resistor tolerance of R4 and R5 determine matching of (+) and (-) outputs.
 **Necessary only if raw supply filter capacitors are more than 2" from regulators.

Connection Diagrams

Metal Can Package (TO-39) (H)

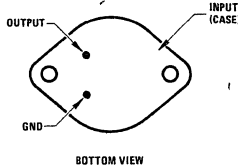


Order Numbers:

- LM120H-5.0
- LM320H-5.0
- LM120H-12
- LM320H-12
- LM120H-15
- LM320H-15

See NS Package H03A

Steel Metal Can Package TO-3 (K)

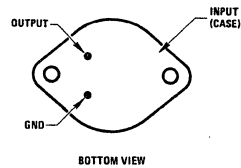


Order Numbers:

- LM120K-5.0
- LM220K-5.0
- LM320K-5.0
- LM120K-12
- LM220K-12
- LM320K-12
- LM120K-15
- LM320K-15

See NS Package K02A

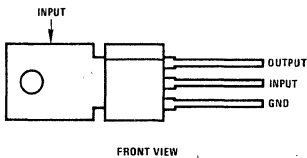
Aluminum Metal Can Package TO-3 (KC)



Order Numbers:

- LM320KC-5.0
 - LM320KC-12
 - LM320KC-15
- See NS Package KC02A

Power Package TO-202 (P)

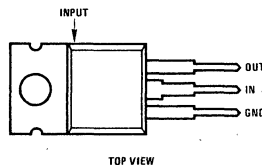


Order Numbers:

- LM320MP-5.0
- LM320MP-12
- LM320MP-15

See NS Package P03A
 For Tab Formed TO-202
 Order Numbers:
 LM320MP-5.0 TB
 LM320MP-12 TB
 LM320MP-15 TB
 See NS Package P03E

Power Package TO-220 (T)

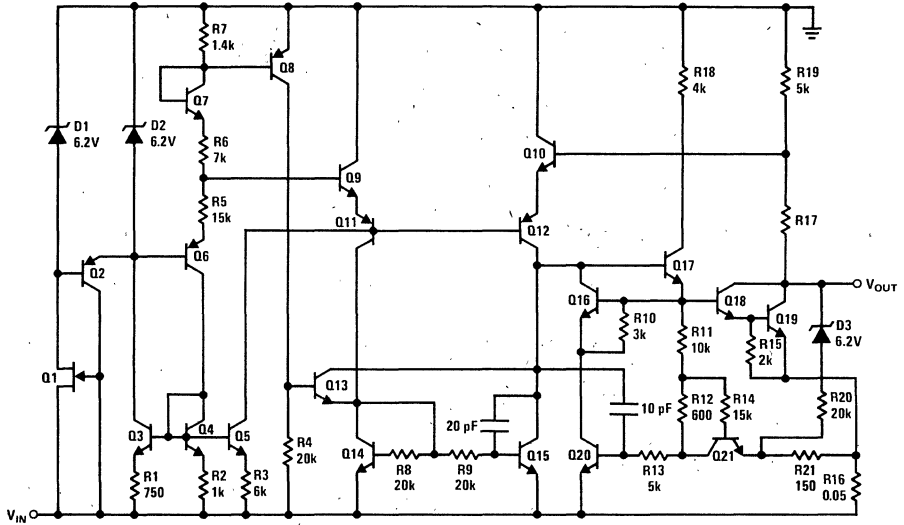


Order Numbers:

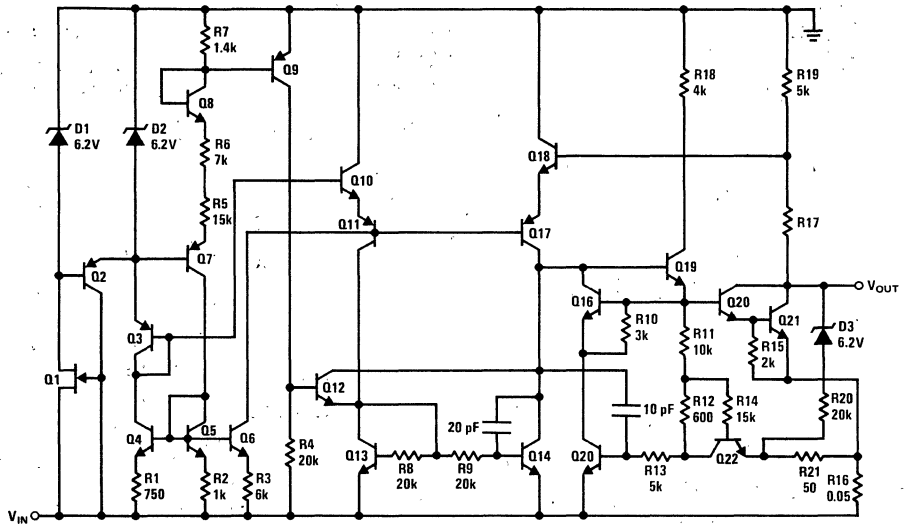
- LM320T-5.0
 - LM320T-12
 - LM320T-15
- See NS Package T03B

Schematic Diagrams

-5V



-12V and -15V



LM123/LM223/LM323 3 Amp, 5 Volt Positive Regulator
General Description

The LM123 is a three-terminal positive regulator with a preset 5V output and a load driving capability of 3 amps. New circuit design and processing techniques are used to provide the high output current without sacrificing the regulation characteristics of lower current devices.

The 3 amp regulator is virtually blowout proof. Current limiting, power limiting, and thermal shutdown provide the same high level of reliability obtained with these techniques in the LM109 1 amp regulator.

No external components are required for operation of the LM123. If the device is more than 4 inches from the filter capacitor, however, a 1 μ F solid tantalum capacitor should be used on the input. A 0.1 μ F or larger capacitor may be used on the output to reduce load transient spikes created by fast switching digital logic, or to swamp out stray load capacitance.

An overall worst case specification for the combined effects of input voltage, load currents, ambient

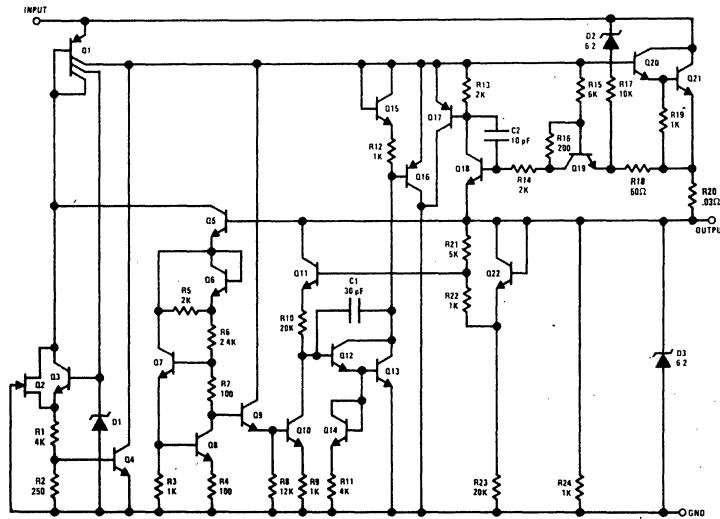
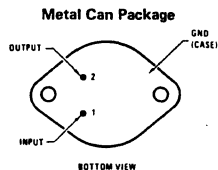
temperature, and power dissipation ensure that the LM123 will perform satisfactorily as a system element.

For applications requiring other voltages, see LM150 series data sheet.

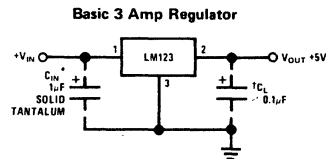
Operation is guaranteed over the junction temperature range -55°C to $+150^{\circ}\text{C}$. An electrically identical LM223 operates from -25°C to $+150^{\circ}\text{C}$ and the LM323 is specified from 0°C to $+125^{\circ}\text{C}$ junction temperature. A hermetic TO-3 package is used for high reliability and low thermal resistance.

Features

- 3 amp output current
- Internal current and thermal limiting
- 0.01 Ω typical output impedance
- 7.5 minimum input voltage
- 30W power dissipation
- 100% electrical burn-in

Schematic Diagram

Connection Diagram


Order Number LM123K STEEL,
LM223K STEEL or LM323K STEEL
See NS Package K02A

Typical Applications


*Required if LM123 is more than 4" from filter capacitor.

†Regulator is stable with no load capacitor into resistive loads.

Absolute Maximum Ratings

| | |
|--------------------------------------|--------------------|
| Input Voltage | 20V |
| Power Dissipation | Internally Limited |
| Operating Junction Temperature Range | |
| LM123 | -55°C to +150°C |
| LM223 | -25°C to +150°C |
| LM323 | 0°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Preconditioning

| | |
|--------------------------|------------------|
| Burn-In in Thermal Limit | 100% All Devices |
|--------------------------|------------------|

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM123/LM223 | | | LM323 | | | UNITS |
|--|---|-------------|--------|----------|-------|--------|----------|--------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Output Voltage | $T_J = 25^\circ\text{C}$ $V_{IN} = 7.5\text{V}, I_{OUT} = 0$ | 4.7 | 5 | 5.3 | 4.8 | 5 | 5.2 | V |
| Output Voltage | $7.5\text{V} \leq V_{IN} \leq 15\text{V}$ $0 \leq I_{OUT} \leq 3\text{A}, P \leq 30\text{W}$ | 4.6 | | 5.4 | 4.75 | | 5.25 | V |
| Line Regulation (Note 3) | $T_J = 25^\circ\text{C}$ $7.5\text{V} \leq V_{IN} \leq 15\text{V}$ | | 5 | 25 | | 5 | 25 | mV |
| Load Regulation (Note 3) | $T_J = 25^\circ\text{C}, V_{IN} = 7.5\text{V},$ $0 \leq I_{OUT} \leq 3\text{A}$ | | 25 | 100 | | 25 | 100 | mV |
| Quiescent Current | $7.5\text{V} \leq V_{IN} \leq 15\text{V},$ $0 \leq I_{OUT} \leq 3\text{A}$ | | 12 | 20 | | 12 | 20 | mA |
| Output Noise Voltage | $T_J = 25^\circ\text{C}$ $10\text{ Hz} \leq f \leq 100\text{ kHz}$ | | 40 | | | 40 | | μVrms |
| Short Circuit Current Limit | $T_J = 25^\circ\text{C}$ $V_{IN} = 15\text{V}$ $V_{IN} = 7.5\text{V}$ | | 3 4 | 4.5 5 | | 3 4 | 4.5 5 | A A |
| Long Term Stability | | | | 35 | | | 35 | mV |
| Thermal Resistance Junction to Case (Note 2) | | | 2 | | | 2 | | $^\circ\text{C/W}$ |

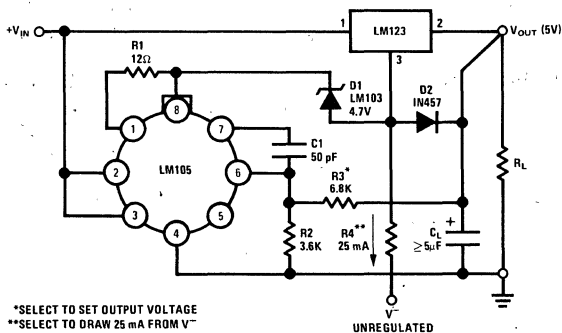
Note 1: Unless otherwise noted, specifications apply for $-55^\circ\text{C} \leq T_J \leq +150^\circ\text{C}$ for the LM123, $-25^\circ\text{C} \leq T_J \leq +150^\circ\text{C}$ for the LM223, and $0^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$ for the LM323. Although power dissipation is internally limited, specifications apply only for $P \leq 30\text{W}$.

Note 2: Without a heat sink, the thermal resistance of the TO-3 package is about 35°C/W . With a heat sink, the effective thermal resistance can only approach the specified values of 2°C/W , depending on the efficiency of the heat sink.

Note 3: Load and line regulation are specified at constant junction temperature. Pulse testing is required with a pulse width $\leq 1\text{ ms}$ and a duty cycle $\leq 5\%$.

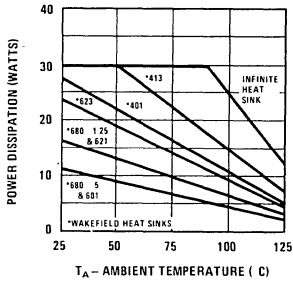
Typical Applications (Continued)

Adjustable Output 5V – 10V 0.1% Regulation

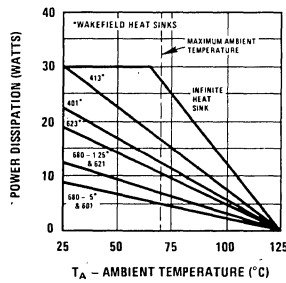


Typical Performance Characteristics

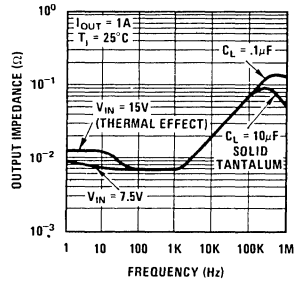
Maximum Average Power Dissipation For LM123; LM223



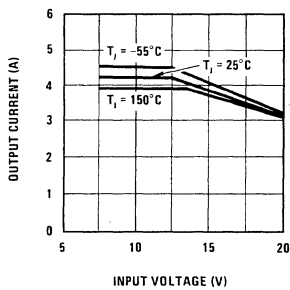
Maximum Average Power Dissipation For LM323



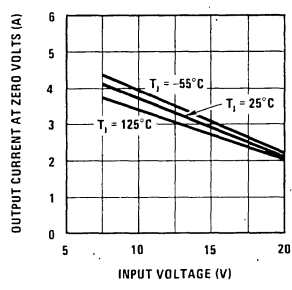
Output Impedance



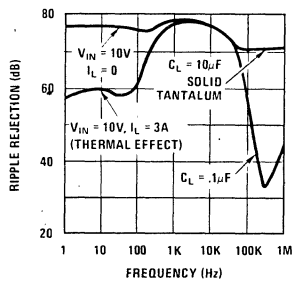
Peak Available Output Current



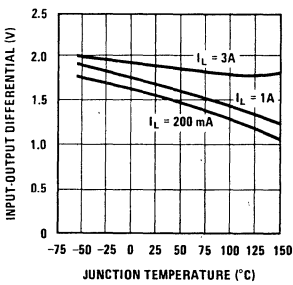
Short Circuit Current



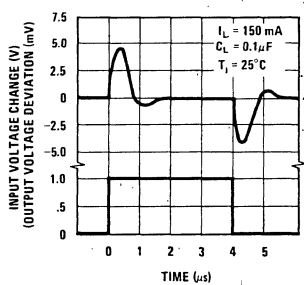
Ripple Rejection



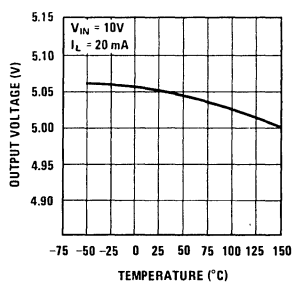
Dropout Voltage



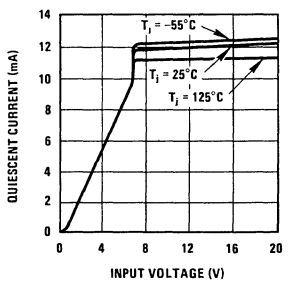
Line Transient Response



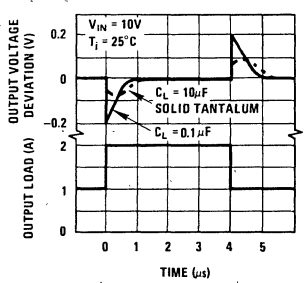
Output Voltage



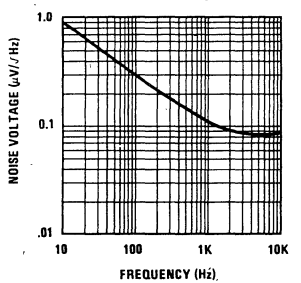
Quiescent Current



Load Transient Response



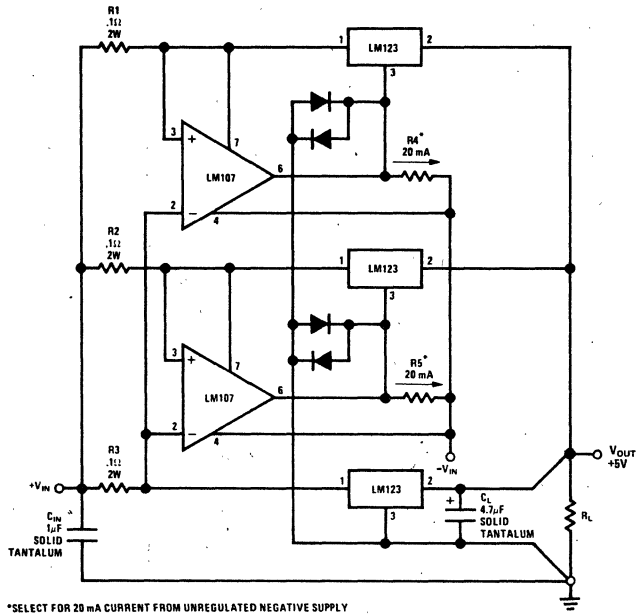
Output Noise Voltage



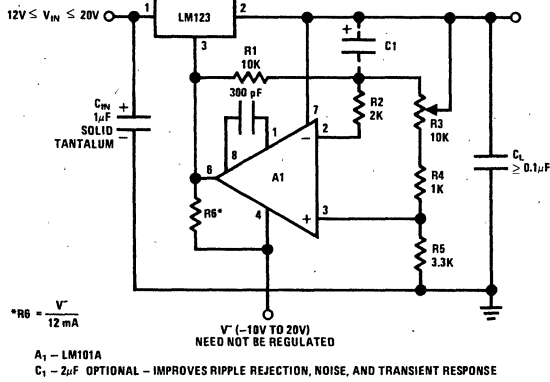
1

Typical Applications (Continued)

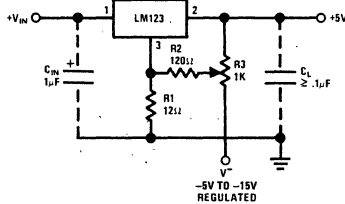
10 Amp Regulator With Complete Overload Protection



Adjustable Regulator 0-10V @ 3A



Trimming Output to 5V



LM125/LM325/LM325A, LM126/LM326 Voltage Regulators

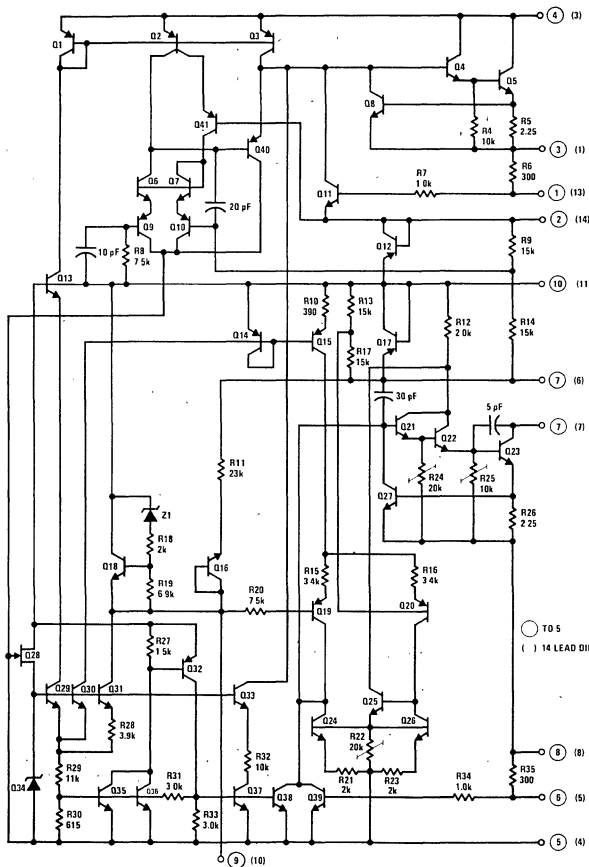
General Description

These are dual polarity tracking regulators designed to provide balanced positive and negative output voltages at current up to 100 mA, the devices are set for ± 15 V, ± 12 V and ± 5 , -12 V outputs respectively. Input voltages up to ± 30 V can be used and there is provision for adjustable current limiting. These devices are available in three package types to accommodate various power requirements and temperature ranges.

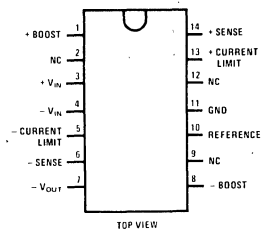
Features

- ± 15 V and ± 12 V tracking outputs
- Output currents to 100 mA
- Output voltages balanced to within 1% (LM125, LM126, LM325A)
- Line and load regulation of 0.06%
- Internal thermal overload protection
- Standby current drain of 3 mA
- Externally adjustable current limit
- Internal current limit

Schematic and Connection Diagrams

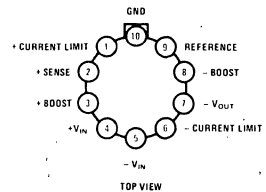


Dual-In-Line Package



Order Number **LM325AN, LM325N,**
or LM326N
See NS Package N14A

Metal Can Package



Order Number **LM125H,**
LM325H, LM126H or
LM326H
See NS Package H10C

Absolute Maximum Ratings

| | |
|--|------------|
| Input Voltage | ±30V |
| Forced V_{O+} (min) (Note 1) | -0.5V |
| Forced V_{O-} (max) (Note 1) | +0.5V |
| Power Dissipation (Note 2) | P_{MAX} |
| Output Short-Circuit Duration (Note 3) | Indefinite |

Operating Conditions

| | |
|--|-----------------|
| Operating Temperature Range | |
| LM125 | -55°C to +125°C |
| LM325, LM325A | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics LM125/LM325/LM325A (Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-------|------|-------|--------------------|
| Output Voltage LM125, LM325A LM325 | $T_j = 25^\circ\text{C}$ | 14.8 | 15 | 15.2 | V |
| | | 14.5 | 15 | 15.5 | V |
| Input-Output Differential | | 2.0 | | | V |
| Line Regulation | $V_{IN} = 18\text{V to }30\text{V}$, $I_L = 20\text{ mA}$, $T_j = 25^\circ\text{C}$ | | 2.0 | 10 | mV |
| Line Regulation Over Temperature Range | $V_{IN} = 18\text{V to }30\text{V}$, $I_L = 20\text{ mA}$ | | 2.0 | 20 | mV |
| Load Regulation V_{O+} V_{O-} | $I_L = 0\text{ to }50\text{ mA}$, $V_{IN} = \pm 30\text{V}$, $T_j = 25^\circ\text{C}$ | | 3.0 | 10 | mV |
| | | | 5.0 | 10 | mV |
| Load Regulation Over Temperature Range V_{O+} V_{O-} | $I_L = 0\text{ to }50\text{ mA}$, $V_{IN} = \pm 30\text{V}$ | | 4.0 | 20 | mV |
| | | | 7.0 | 20 | mV |
| Output Voltage Balance LM125/LM325A LM325 | $T_j = 25^\circ\text{C}$ | | | ±150 | mV |
| | | | | ±300 | mV |
| Output Voltage Over Temperature Range LM125/LM325A LM325 | $P \leq P_{MAX}$, $0 \leq I_O \leq 50\text{ mA}$, $18\text{V} \leq V_{IN} \leq 30$ | 14.65 | | 15.35 | V |
| | | 14.27 | | 15.73 | V |
| Temperature Stability of V_O | | | ±0.3 | | % |
| Short Circuit Current Limit | $T_j = 25^\circ\text{C}$ | | 260 | | mA |
| Output Noise Voltage | $T_j = 25^\circ\text{C}$, BW = 100 - 10 kHz | | 150 | | μVrms |
| Positive Standby Current | $T_j = 25^\circ\text{C}$ | | 1.75 | 3.0 | mA |
| Negative Standby Current | $T_j = 25^\circ\text{C}$ | | 3.1 | 5.0 | mA |
| Long Term Stability | | | 0.2 | | %/kHr |
| Thermal Resistance Junction to Case (Note 4) LM125H, LM325H | | | 45 | | $^\circ\text{C/W}$ |
| | | | | | |
| Junction to Ambient LM325AN, LM325N | | | 150 | | $^\circ\text{C/W}$ |

Note 1: That voltage to which the output may be forced without damage to the device.

Note 2: Unless otherwise specified, these specifications apply for $T_j = -55^\circ\text{C}$ to $+150^\circ\text{C}$ on LM125, $T_j = 0^\circ\text{C}$ to $+125^\circ\text{C}$ on LM325 and LM325A, $V_{IN} = \pm 20\text{V}$, $I_L = 0\text{ mA}$, $I_{MAX} = 100\text{ mA}$, $P_{MAX} = 2.0\text{W}$ for the TO-5 H package. $I_{MAX} = 100\text{ mA}$, $P_{MAX} = 1.0\text{W}$ for the DIP N package.

Note 3: If the junction temperature exceeds 150°C the output short circuit duration is 60 seconds.

Note 4: Without a heat sink, the thermal resistance junction to ambient of the TO-5 Package is about 150°C/W . With a heat sink, the effective thermal resistance can only approach the junction to case values specified, depending on the efficiency of the sink.

Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage | ±30V |
| Forced V_{O^+} (Min) (Note 1) | -0.5V |
| Forced V_{O^-} (Max) (Note 1) | +0.5V |
| Power Dissipation (Note 2) | Internally Limited |
| Output Short-Circuit Duration (Note 3) | Indefinite |
| Operating Temperature Range | |
| LM126 | -55°C to +125°C |
| LM326 | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics LM126/LM326 (Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-------|------|-------|---------------------|
| Output Voltage | $T_J = 25^\circ\text{C}$ | | | | |
| LM126 | | 11.8 | 12 | 12.2 | V |
| LM326 | | 11.5 | | 12.5 | V |
| Input-Output Differential | | 2.0 | | | V |
| Line Regulation | $V_{IN} = 15\text{V to }30\text{V}$ $I_L = 20\text{ mA}, T_J = 25^\circ\text{C}$ | | 2.0 | 10 | mV |
| Line Regulation Over Temperature Range | $V_{IN} = 15\text{V to }30\text{V}, I_L = 20\text{ mA}$ | | 2.0 | 20 | mV |
| Load Regulation | $I_L = 0\text{ to }50\text{ mA}, V_{IN} = \pm 30\text{V},$ $T_J = 25^\circ\text{C}$ | | 3.0 | 10 | mV |
| V_{O^+} | | | 5.0 | 10 | mV |
| V_{O^-} | | | | | |
| Load Regulation Over Temperature Range | $I_L = 0\text{ to }50\text{ mA}, V_{IN} = \pm 30\text{V}$ | | 4.0 | 20 | mV |
| V_{O^+} | | | 7.0 | 20 | mV |
| V_{O^-} | | | | | |
| Output Voltage Balance | $T_J = 25^\circ\text{C}$ | | | | |
| LM126 | | | | ±125 | mV |
| LM326 | | | | ±250 | mV |
| Output Voltage Over Temperature Range | $P \leq P_{MAX}, 0 \leq I_O \leq 50\text{ mA}$ $15\text{V} \leq V_{IN} \leq 30\text{V}$ | 11.68 | | 12.32 | V |
| LM126 | | 11.32 | | 12.68 | V |
| LM326 | | | | | |
| Temperature Stability of V_{O^+} | | | ±0.3 | | % |
| Short Circuit Current Limit | $T_J = 25^\circ\text{C}$ | | 260 | | mA |
| Output Noise Voltage | $T_J = 25^\circ\text{C}, \text{BW} = 100 - 10\text{ kHz}$ | | 100 | | μV_{rms} |
| Positive Standby Current | $T_J = 25^\circ\text{C}, I_L = 0$ | | 1.75 | 3.0 | mA |
| Negative Standby Current | $T_J = 25^\circ\text{C}, I_L = 0$ | | 3.1 | 5.0 | mA |
| Long Term Stability | | | 0.2 | | %/kHr |
| Thermal Resistance Junction to Case (Note 4) | | | 45 | | $^\circ\text{C/W}$ |
| LM126H/LM326H | | | | | |
| Junction to Ambient LM326N | | | 150 | | $^\circ\text{C/W}$ |

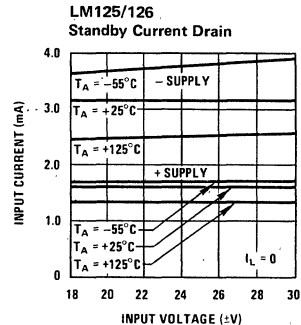
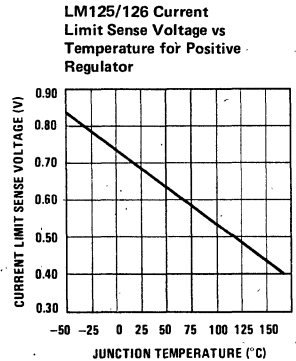
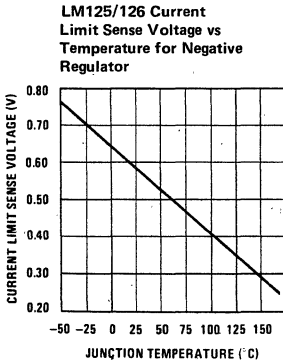
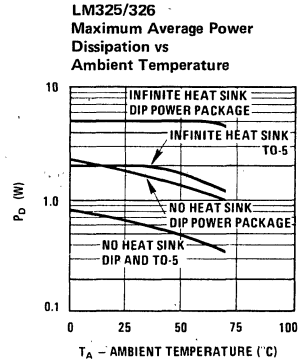
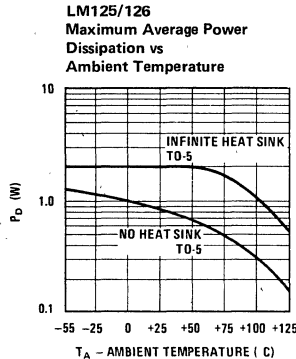
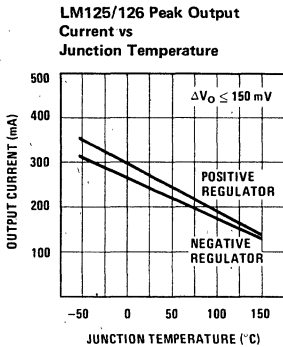
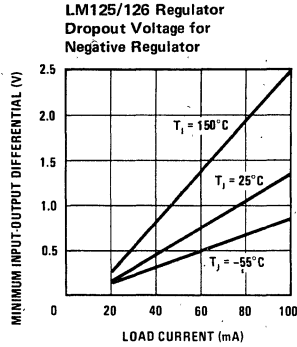
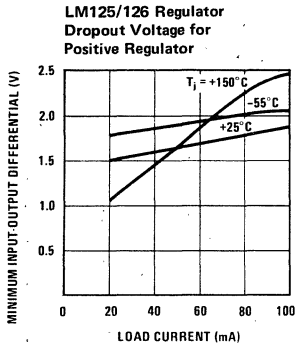
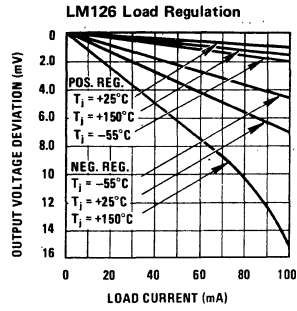
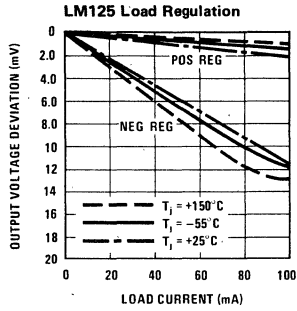
Note 1: That voltage to which the output may be forced without damage to the device.

Note 2: Unless otherwise specified, these specifications apply for $T_J = -55^\circ\text{C}$ to $+150^\circ\text{C}$ on LM126, $T_J = 0^\circ\text{C}$ to $+125^\circ\text{C}$ on LM326, $V_{IN} = \pm 20\text{V}$, $I_L = 0\text{ mA}$, $I_{MAX} = 100\text{ mA}$, $P_{MAX} = 2.0\text{W}$ for the TO-5 H Package, $I_{MAX} = 100\text{ mA}$, $P_{MAX} = 1.0\text{W}$ for the DIP N Package.

Note 3: If the junction temperature exceeds 150°C the output short circuit duration is 60 seconds.

Note 4: Without a heat sink, the thermal resistance junction to ambient of the TO-5 Package is about 150°C/W . With a heat sink, the effective thermal resistance can only approach the junction to case values specified, depending on the efficiency of the sink.

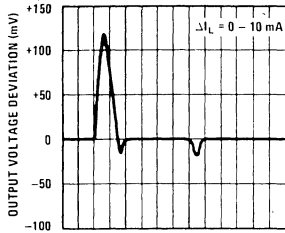
Typical Performance Characteristics ($V_{IN} = \pm 20V$, $I_L = 0$ mA, $T_J = 25^\circ C$, unless otherwise noted.)





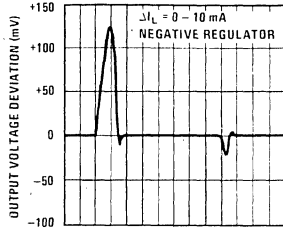
Typical Performance Characteristics (Continued)

LM125
Load Transient Response
for Negative Regulator



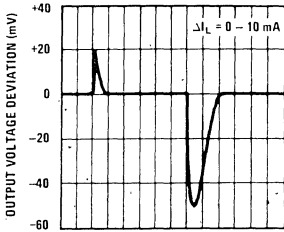
TIME (1µs/DIV)

LM126
Load Transient Response



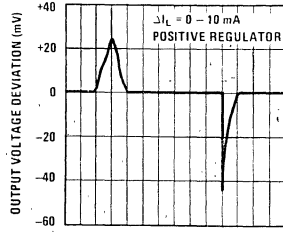
TIME (1µs/DIV)

LM125
Load Transient Response
for Positive Regulator



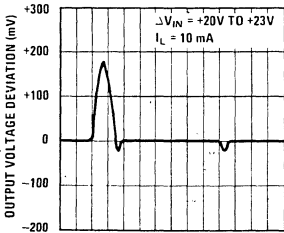
TIME (1µs/DIV)

LM126
Load Transient Response



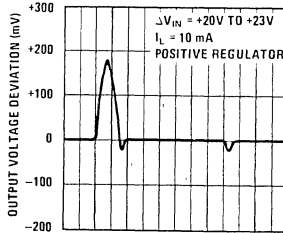
TIME (2µs/DIV)

LM125
Line Transient Response
for Positive Regulator



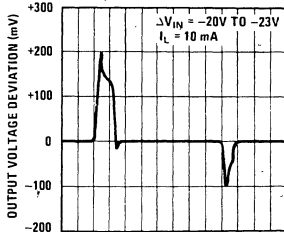
TIME (2µs/DIV)

LM126
Line Transient Response



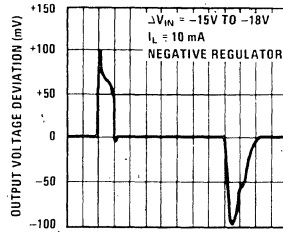
TIME (2µs/DIV)

LM125
Line Transient Response
for Negative Regulator



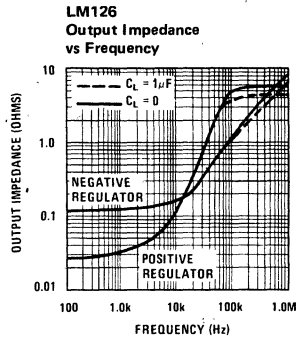
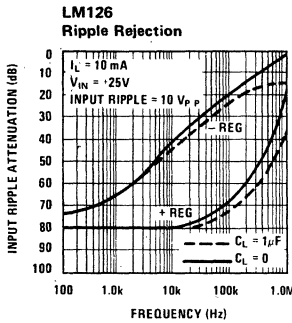
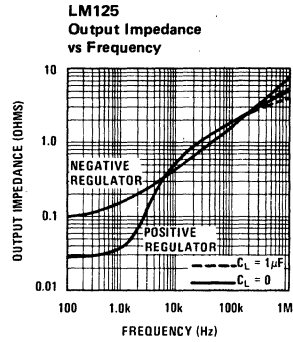
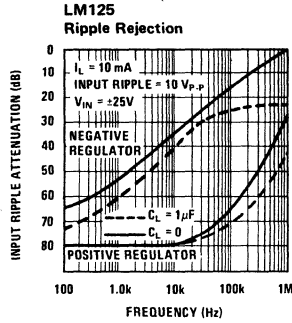
TIME (10µs/DIV)

LM126
Line Transient Response



TIME (15µs/DIV)

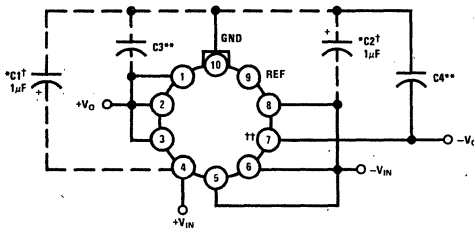
Typical Performance Characteristics (Continued)



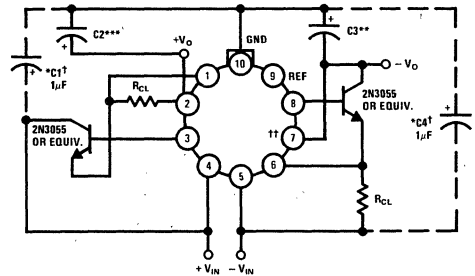
Typical Applications

Note. Metal can (H) packages shown.

Basic Regulator^{†††}



2.0 Amp Boosted Regulator With Current Limit



I_{CL} = CURRENT LIMIT SENSE VOLTAGE (SEE CURVE)
R_{CL}

[†]SOLID TANTALUM

^{††}SHORT PINS 6 AND 7 ON DIP.

^{†††}R_{CL} CAN BE ADDED TO THE BASIC REGULATOR BETWEEN PINS 6 AND 5, 1 AND 2 TO REDUCE CURRENT LIMIT.

*REQUIRED IF REGULATOR IS LOCATED AN APPRECIABLE DISTANCE FROM POWER SUPPLY FILTER.

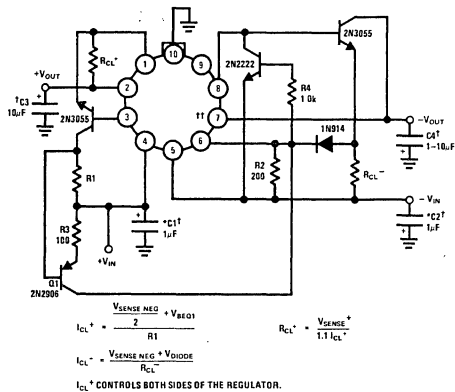
**ALTHOUGH NO CAPACITOR IS NEEDED FOR STABILITY, IT DOES HELP TRANSIENT RESPONSE. (IF NEEDED USE 1µF ELECTROLYTIC).

***ALTHOUGH NO CAPACITOR IS NEEDED FOR STABILITY, IT DOES HELP TRANSIENT RESPONSE. (IF NEEDED USE 10µF ELECTROLYTIC).

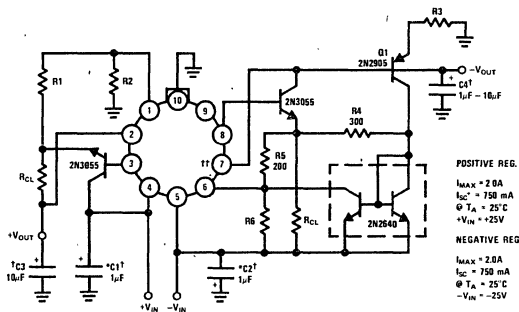
Typical Applications (Continued)

LM125/LM325/LM325A,
LM126/LM326

Positive Current Dependent Simultaneous Current Limiting



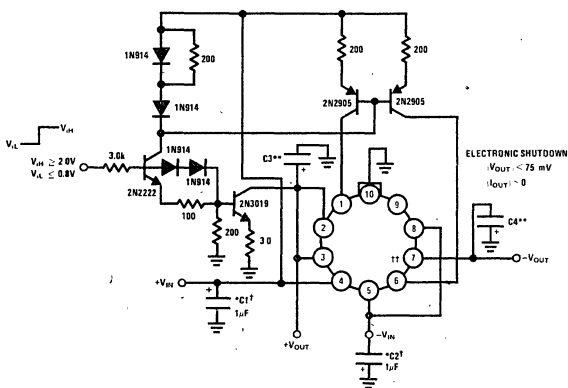
Boosted Regulator With Foldback Current Limit



Resistor Values

| | LM125 | LM126 |
|-----|-------|-------|
| R1 | 18 | 20 |
| R2 | 310 | 180 |
| R3 | 2.4k | 1.35k |
| R6 | 300 | 290 |
| RCL | 0.7 | 0.9 |

Electric Shutdown



¹SOLID TANTALUM
²SHORT PINS 6 AND 7 ON DIP
³REQUIRED IF REGULATOR IS LOCATED AN APPRECIABLE DISTANCE FROM POWER SUPPLY FILTER.
⁴ALTHOUGH NO CAPACITOR IS NEEDED FOR STABILITY, IT DOES HELP TRANSIENT RESPONSE. (IF NEEDED USE 1μF ELECTROLYTIC.)

LM130/LM330 3-Terminal Positive Regulators

General Description

The LM130 series of 3-terminal positive voltage regulators feature an ability to source full output current with an input-output differential of 0.5V or less. Familiar regulator features such as current limit and thermal overload protection are also provided.

The low in-out differential voltage makes the LM130 useful for certain battery applications since this feature allows a longer battery discharge before the output falls out of regulation. For example, a 9V battery supplying the regulator input voltage discharges to below 5½ V before any change is noted in the output. Supporting this feature, the LM130 protects both itself and regulated systems from negative voltage inputs resulting from reverse installations of batteries.

Other protection features include line transient protection up to 50V, when the output actually shuts down to avoid damaging internal and external circuits. Also, the LM330 regulator in the TO-202 package cannot be harmed by a temporary mirror-image insertion.

A fixed output of 5V is available in the 3-lead hermetic metal can and the plastic TO-202 power package (LM330 only).

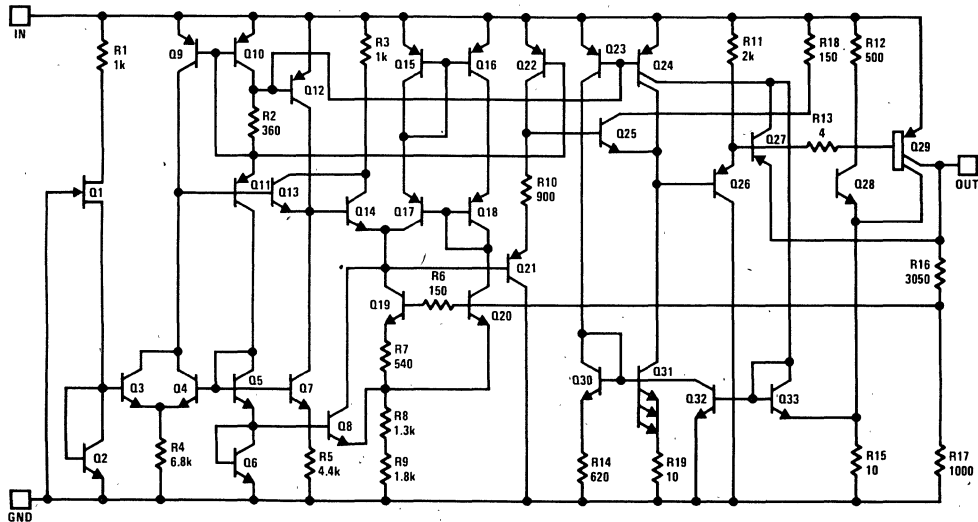
Features

- Input-output differential less than 0.5V
- Output current of 150mA
- Reverse battery protection
- Line transient protection
- Internal short circuit current limit
- Internal thermal overload protection
- Mirror-image insertion protection
- Available in plastic TO-202 (LM330)

Voltage Range

| | |
|------------|----|
| LM130H-5.0 | 5V |
| LM330H-5.0 | 5V |
| LM330P-5.0 | 5V |

Schematic



Absolute Maximum Ratings

| | LM130 | LM330 |
|--|--------------------|--------------------|
| Input Voltage | | |
| Operating Range | 30V | 26V |
| Line Transient Protection (1000 ms) | 50V | 26V |
| Internal Power Dissipation | Internally Limited | Internally Limited |
| Operating Temperature Range | -55°C to +125°C | 0°C to +70°C |
| Maximum Junction Temperature | +150°C | +125°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | +300°C | +300°C |

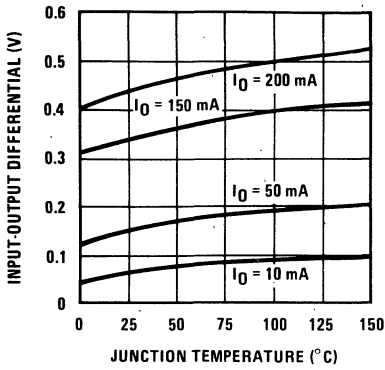
Electrical Characteristics (Note 1)

| Parameter | | Conditions | LM130 | | | LM330 | | | Units |
|-----------------|---------------------------------|--|------------|----------------|--------------|------------|----------------|--------------|-------|
| | | | Min | Typ | Max | Min | Typ | Max | |
| V _o | Output Voltage | T _J = 25°C | 4.8 | 5 | 5.2 | 4.8 | 5 | 5.2 | V |
| | Output Voltage Over Temp | 5 < I _o < 150mA 6 < V _{IN} < 26V | 4.75 | | 5.25 | 4.75 | | 5.25 | |
| ΔV _o | Line Regulation | 9 < V _{IN} < 16V, I _o = 5mA 6 < V _{IN} < 26V, I _o = 5mA | | 7 30 | 15 45 | | 7 30 | 25 60 | mV |
| | Load Regulation | 5 < I _o < 150mA | | 14 | 25 | | 14 | 50 | |
| | Long Term Stability | | | 20 | | 20 | | mV/1000 hrs | |
| I _Q | Quiescent Current | I _o = 10 mA I _o = 50 mA I _o = 150 mA | | 3.5 5 18 | 5 7 30 | | 3.5 5 18 | 7 9 40 | mA |
| | Line Transient Reverse Polarity | V _{IN} = 40V, R _L = 100Ω, 1 sec V _{IN} = -6V, R _L = 100Ω | | 25 -80 | 40 | | 25 -80 | | |
| ΔI _Q | Quiescent Current Change | 6 < V _{IN} < 26V | | 10 | | | 10 | % | |
| V _{IN} | Max Operational Input Voltage | | 30 | 35 | | 26 | 35 | V | |
| | Max Line Transient | 100 ms V _o ≤ 5.5V 1 sec V _o ≤ 5.5V | 50 40 | 60 50 | | 60 50 | | | |
| | Reverse Polarity Input Voltage | 100 ms V _o > -0.3V, R _L = 100Ω DC V _o > -0.3V, R _L = 100Ω | -30 -12 | -15 -6 | | -30 -12 | | | |
| | Output Noise Voltage | 10 Hz-100 kHz | | 50 | | 50 | | μV | |
| | Output Impedance | I _o = 100 mADC + 10 mArms | | 200 | | 200 | | mΩ | |
| | Ripple Rejection | | | 56 | | 56 | | dB | |
| | Current Limit | | 150 | 400 | 700 | 150 | 400 | 700 | mA |
| | Dropout Voltage | I _o = 150 mA | | 0.4 | 0.5 | | 0.4 | 0.6 | V |
| | Thermal Resistance | Junction to Case | | | | | | | °C/W |
| | | TO-39 | | 40 | | | 40 | | |
| | | TO-202 | | — | | | 12 | | |
| | | Junction to Ambient | | | | | | | |
| | TO-39 | | 140 | | | 140 | | | |
| | TO-202 | | — | | | 70 | | | |

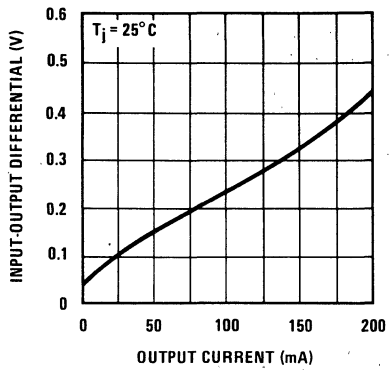
Note 1: Unless otherwise specified: V_{IN} = 14V, I_o = 200 mA, T_J = 25°C, C1 = 0.1 μF, C2 = 10 μF. All characteristics except noise voltage and ripple rejection are measured using pulse techniques (t_w < 10 ms, duty cycle < 5%). Output voltage changes due to changes in internal temperature must be taken into account separately.

Typical Performance Characteristics

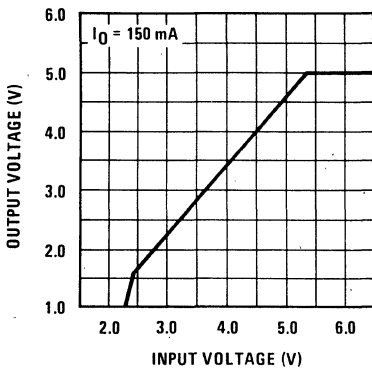
Dropout Voltage



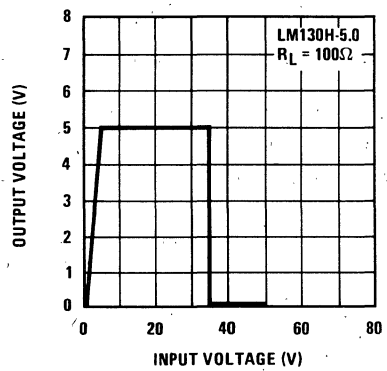
Dropout Voltage



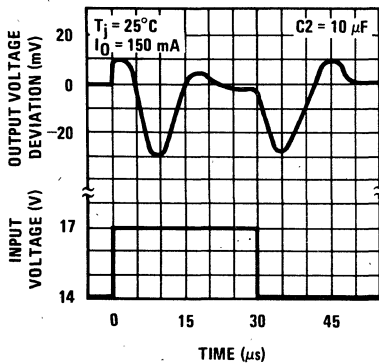
Low Voltage Behavior



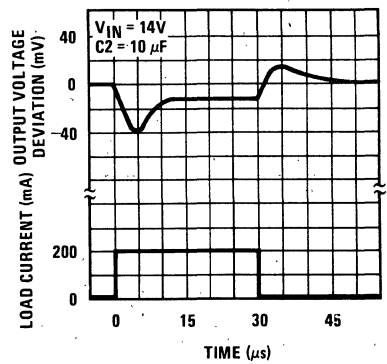
High Voltage Behavior



Line Transient Response

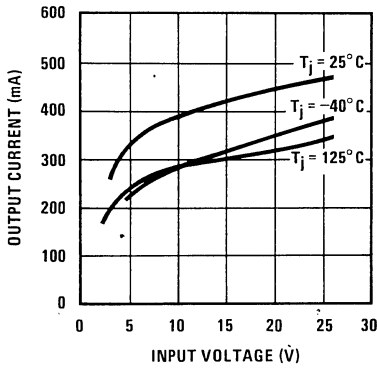


Load Transient Response

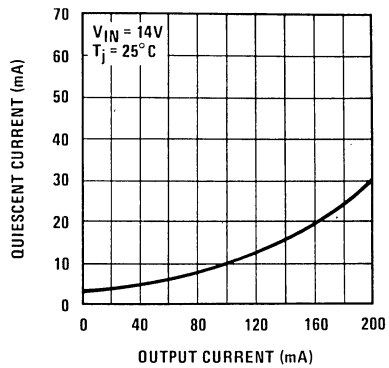


Typical Performance Characteristics (Continued)

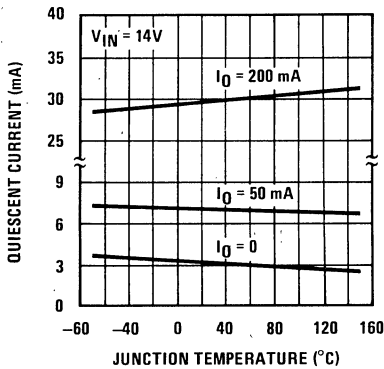
Peak Output Current



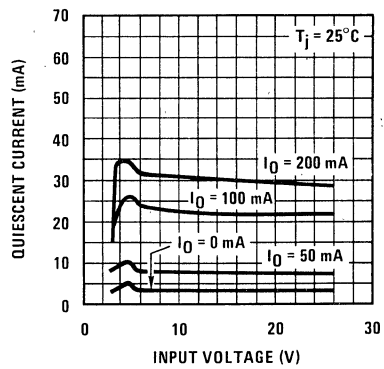
Quiescent Current



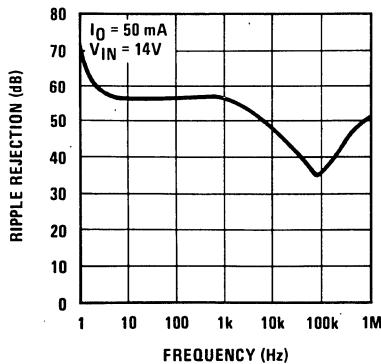
Quiescent Current



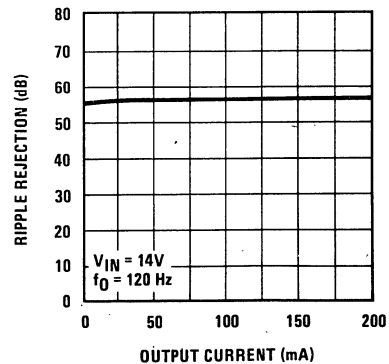
Quiescent Current



Ripple Rejection

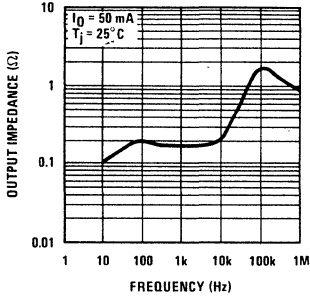


Ripple Rejection

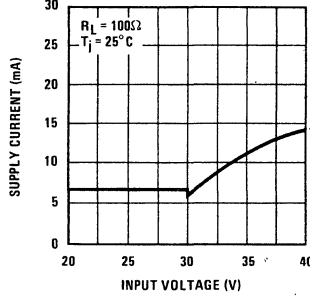


Typical Performance Characteristics (Continued)

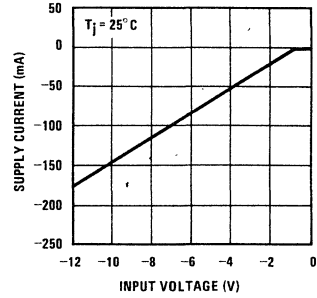
Output Impedance



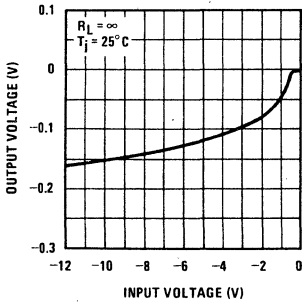
Overtolerance Supply Current



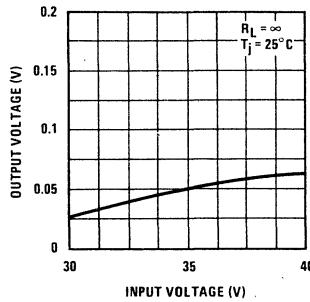
Reverse Supply Current



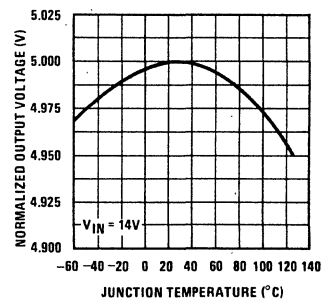
Output at Reverse Supply



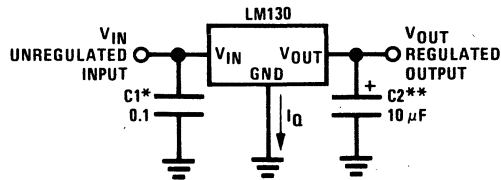
Output at Overtolerance



Output Voltage (Normalized to 5V at T_J = 25°C)



Typical Application



* Required if regulator is located far from power supply filter
 ** C2 must be at least 10 μF to maintain stability. May be increased without bound. Locate as close as possible to regulator.

Definition of Terms

Dropout Voltage: The input-output voltage differential at which the circuit ceases to regulate against further reduction in input voltage. Measured when the output voltage has dropped 100 mV from the nominal value obtained at 14V input, dropout voltage is dependent upon load current and junction temperature.

Input Voltage: The DC voltage applied to the input terminals with respect to ground.

Input-Output Differential: The voltage difference between the unregulated input voltage and the regulated output voltage for which the regulator will operate.

Line Regulation: The change in output voltage for a change in the input voltage. The measurement is made under conditions of low dissipation or by using pulse techniques such that the average chip temperature is not significantly affected.

Load Regulation: The change in output voltage for a change in load current at constant chip temperature.

Long Term Stability: Output voltage stability under accelerated life-test conditions after 1000 hours with maximum rated voltage and junction temperature.

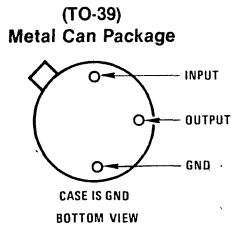
Output Noise Voltage: The rms AC voltage at the output, with constant load and no input ripple, measured over a specified frequency range.

Quiescent Current: That part of the positive input current that does not contribute to the positive load current. The regulator ground lead current.

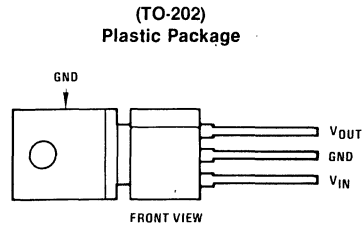
Ripple Rejection: The ratio of the peak-to-peak input ripple voltage to the peak-to-peak output ripple voltage.

Temperature Stability of V_O : The percentage change in output voltage for a thermal variation from room temperature to either temperature extreme.

Connection Diagrams



Order Number
LM130H-5.0
LM330H-5.0
See Package H03B



Order Number
LM330P-5.0 TB
See Package P03E



LM137/LM237/LM337 3-Terminal Adjustable Negative Regulators

General Description

The LM137/LM237/LM337 are adjustable 3-terminal negative voltage regulators capable of supplying in excess of $-1.5A$ over an output voltage range of $-1.2V$ to $-37V$. These regulators are exceptionally easy to apply, requiring only 2 external resistors to set the output voltage and 1 output capacitor for frequency compensation. The circuit design has been optimized for excellent regulation and low thermal transients. Further, the LM137 series features internal current limiting, thermal shutdown and safe-area compensation, making them virtually blowout-proof against overloads.

The LM137/LM237/LM337 serve a wide variety of applications including local on-card regulation, programmable-output voltage regulation or precision current regulation. The LM137/LM237/LM337 are ideal complements to the LM117/LM217/LM317 adjustable positive regulators.

Features

- Output voltage adjustable from $-1.2V$ to $-37V$
- $1.5A$ output current guaranteed, $-55^{\circ}C$ to $+150^{\circ}C$

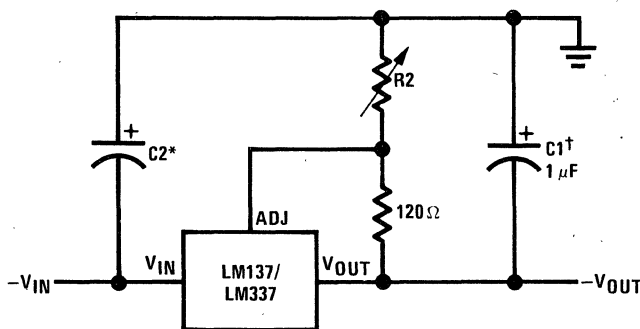
- Line regulation typically $0.01\%/V$
- Load regulation typically 0.3%
- Excellent thermal regulation, $0.002\%/W$
- 77 dB ripple rejection
- Excellent rejection of thermal transients
- 50 ppm/ $^{\circ}C$ temperature coefficient
- Temperature-independent current limit
- Internal thermal overload protection
- 100% electrical burn-in
- Standard 3-lead transistor package

LM137 Series Packages and Power Capability

| DEVICE | PACKAGE | RATED POWER DISSIPATION | DESIGN LOAD CURRENT |
|----------------|---------|-------------------------|---------------------|
| LM137 | TO-3 | 20W | 1.5A |
| LM237 LM337 | TO-39 | 2W | 0.5A |
| LM337T | TO-220 | 15W | 1.5A |
| LM337M | TO-202 | 7.5W | 0.5A |

Typical Applications

Adjustable Negative Voltage Regulator



$$-V_{OUT} = -1.25V \left(1 + \frac{R2}{120\Omega} \right)$$

†C1 = $1 \mu F$ solid tantalum or $10 \mu F$ aluminum electrolytic required for stability

*C2 = $1 \mu F$ solid tantalum is required only if regulator is more than 4" from power-supply filter capacitor

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input–Output Voltage Differential | 40V |
| Operating Junction Temperature Range | |
| LM137 | –55°C to +150°C |
| LM237 | –25°C to +150°C |
| LM337 | 0°C to +125°C |
| Storage Temperature | –65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Preconditioning

Burn-In in Thermal Limit 100% All Devices

Electrical Characteristics (Note 1)

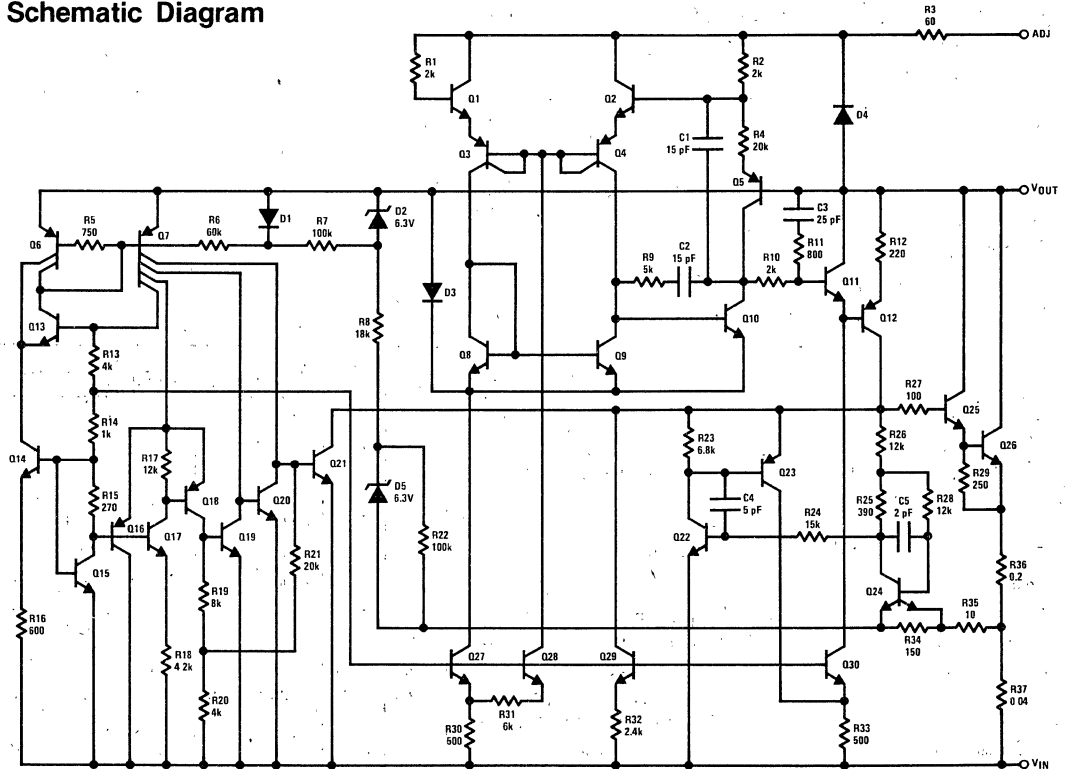
| PARAMETER | CONDITIONS | LM137/LM237 | | | LM337 | | | UNITS |
|--------------------------------------|---|-------------|--------|--------|--------|--------|--------|---------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{IN} - V_{OUT} \leq 40\text{V}$ (Note 2) | | 0.01 | 0.02 | | 0.01 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{mA} \leq I_{OUT} \leq I_{MAX}$ $ V_{OUT} \leq 5\text{V}$, (Note 2) $ V_{OUT} \geq 5\text{V}$, (Note 2) | | 15 | 25 | | 15 | 50 | mV |
| | | | 0.3 | 0.5 | | 0.3 | 1.0 | % |
| | | | 0.002 | 0.02 | | 0.003 | 0.04 | %/W |
| Thermal Regulation | $T_A = 25^\circ\text{C}$, 10 ms Pulse | | 0.002 | 0.02 | | 0.003 | 0.04 | %/W |
| Adjustment Pin Current | | | 65 | 100 | | 65 | 100 | μA |
| Adjustment Pin Current Change | $10\text{mA} \leq I_L \leq I_{MAX}$ $2.5\text{V} \leq V_{IN} - V_{OUT} \leq 40\text{V}$, $T_A = 25^\circ\text{C}$ | | 2 | 5 | | 2 | 5 | μA |
| Reference Voltage | $T_A = 25^\circ\text{C}$ (Note 3) $3 \leq V_{IN} - V_{OUT} \leq 40\text{V}$, (Note 3) $10\text{mA} \leq I_{OUT} \leq I_{MAX}$, $P \leq P_{MAX}$ | –1.225 | –1.250 | –1.275 | –1.213 | –1.250 | –1.287 | V |
| | | –1.200 | –1.250 | –1.300 | –1.200 | –1.250 | –1.300 | V |
| Line Regulation | $3\text{V} \leq V_{IN} - V_{OUT} \leq 40\text{V}$, (Note 2) | | 0.02 | 0.05 | | 0.02 | 0.07 | %/V |
| Load Regulation | $10\text{mA} \leq I_{OUT} \leq I_{MAX}$, (Note 2) $ V_{OUT} \leq 5\text{V}$ $ V_{OUT} \geq 5\text{V}$ | | 20 | 50 | | 20 | 70 | mV |
| | | | 0.3 | 1 | | 0.3 | 1.5 | % |
| | | | 0.6 | | | 0.6 | | % |
| Temperature Stability | $T_{MIN} \leq T_j \leq T_{MAX}$ | | 0.6 | | | 0.6 | | % |
| Minimum Load Current | $ V_{IN} - V_{OUT} \leq 40\text{V}$ $ V_{IN} - V_{OUT} \leq 10\text{V}$ | | 2.5 | 5 | | 2.5 | 10 | mA |
| | | | 1.2 | 3 | | 1.5 | 6 | mA |
| Current Limit | $ V_{IN} - V_{OUT} \leq 15\text{V}$ K and T Package H and P Package $ V_{IN} - V_{OUT} = 40\text{V}$, $T_j = +25^\circ\text{C}$ | 1.5 | 2.2 | | 1.5 | 2.2 | | A |
| | | 0.5 | 0.8 | | 0.5 | 0.8 | | A |
| | | 0.24 | 0.4 | | 0.15 | 0.4 | | A |
| | H and P Package | 0.15 | 0.20 | | 0.10 | 0.20 | | A |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{Hz} \leq f \leq 10\text{kHz}$ | | 0.003 | | | 0.003 | | % |
| Ripple Rejection Ratio | $V_{OUT} = -10\text{V}$, $f = 120\text{Hz}$ $C_{ADJ} = 10\mu\text{F}$ | | 60 | | | 60 | | dB |
| | | 66 | 77 | | 66 | 77 | | dB |
| Long-Term Stability | $T_A = 125^\circ\text{C}$, 1000 Hours | | 0.3 | 1 | | 0.3 | 1 | % |
| Thermal Resistance, Junction to Case | H Package | | 12 | 15 | | 12 | 15 | $^\circ\text{C}/\text{W}$ |
| | K Package | | 2.3 | 3 | | 2.3 | 3 | $^\circ\text{C}/\text{W}$ |
| | T Package | | | | | 4 | | $^\circ\text{C}/\text{W}$ |
| | P Package | | | | | 12 | | $^\circ\text{C}/\text{W}$ |

Note 1: Unless otherwise specified, these specifications apply $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM137, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM237 and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM337; $V_{IN} - V_{OUT} = 5\text{V}$; and $I_{OUT} = 0.1\text{A}$ for the TO-5 package and TO-202 package and $I_{OUT} = 0.5\text{A}$ for the TO-3 package and TO-220 package. Although power dissipation is internally limited, these specifications are applicable for power dissipations of 2W for the TO-5 and TO-202 and 20W for the TO-3 and TO-220. I_{MAX} is 1.5A for the TO-3 and TO-220 package and 0.5A for the TO-202 package, and 0.2A for the TO-39 package.

Note 2: Regulation is measured at constant junction temperature, using pulse testing with a low duty cycle. Changes in output voltage due to heating effects are covered under the specification for thermal regulation. Load regulation is measured on the output pin at a point 1/8" below the base of the TO-3 and TO-39 packages.

Note 3: Selected devices with tightened tolerance reference voltage available.

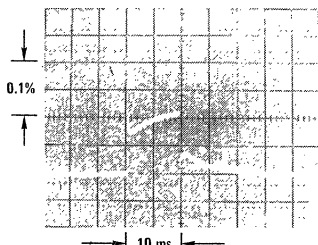
Schematic Diagram



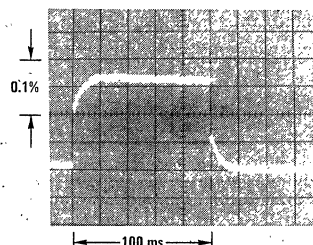
Thermal Regulation

When power is dissipated in an IC, a temperature gradient occurs across the IC chip affecting the individual IC circuit components. With an IC regulator, this gradient can be especially severe since power dissipation is large. Thermal regulation is the effect of these temperature gradients on output voltage (in percentage output change) per Watt of power change in a specified time. Thermal regulation error is independent of electrical regulation or temperature coefficient, and occurs within 5 ms to 50 ms after a change in power dissipation. Thermal regulation depends on IC layout as well as electrical design. The thermal regulation of a voltage regulator is defined as the percentage change of V_{OUT} , per Watt, within the first 10 ms after a step of power is applied. The LM137's specification is 0.02%/W, max.

In Figure 1, a typical LM137's output drifts only 3 mV (or 0.03% of $V_{OUT} = -10V$) when a 10W pulse is applied for 10 ms. This performance is thus well inside the specification limit of $0.02\%/W \times 10W = 0.2\%$ max. When the 10W pulse is ended, the thermal regulation again shows a 3 mV step as the LM137 chip cools off. Note that the load regulation error of about 8 mV (0.08%) is additional to the thermal regulation error. In Figure 2, when the 10W pulse is applied for 100 ms, the output drifts only slightly beyond the drift in the first 10 ms, and the thermal error stays well within 0.1% (10 mV).



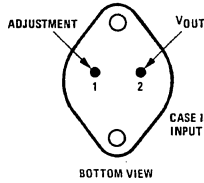
LM137, $V_{OUT} = -10V$
 $V_{IN} - V_{OUT} = -40V$
 $I_L = 0A \rightarrow 0.25A \rightarrow 0A$
 Vertical sensitivity, 5 mV/div
FIGURE 1



LM137, $V_{OUT} = -10V$
 $V_{IN} - V_{OUT} = -40V$
 $I_L = 0A \rightarrow 0.25A \rightarrow 0A$
 Horizontal sensitivity, 20 ms/div
FIGURE 2

Connection Diagrams

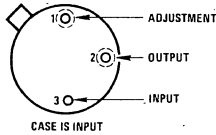
TO-3 Metal Can Package



BOTTOM VIEW

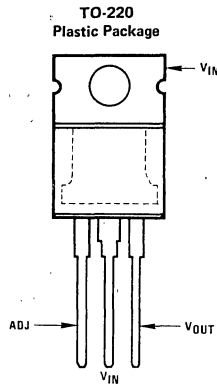
Order Number:
LM137K STEEL
LM237K STEEL
LM337K STEEL
See NS Package K02A

TO-39 Metal Can Package



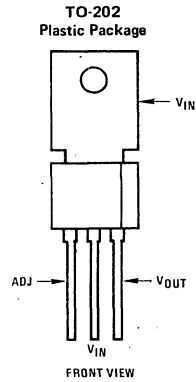
BOTTOM VIEW

Order Number:
LM137H
LM237H
LM337H
See NS Package H03A



FRONT VIEW

Order Number:
LM337T
See NS Package T03B

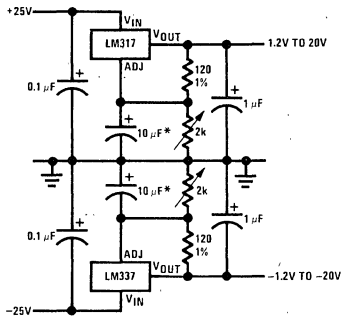


FRONT VIEW

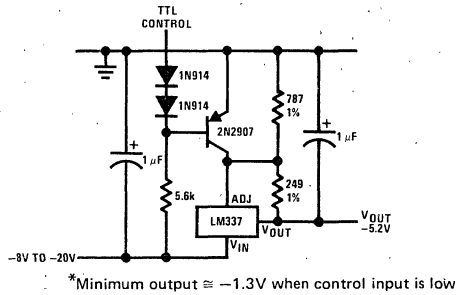
Order Number:
LM337MP
See NS Package P03A
For Tab Bend TO-202 Order Number:
LM337MP TB
See NS Package P03E

Typical Applications (Continued)

Adjustable Lab Voltage Regulator



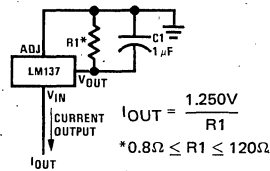
-5.2V Regulator with Electronic Shutdown*



*Minimum output $\approx -1.3V$ when control input is low

*The 10 μF capacitors are optional to improve ripple rejection

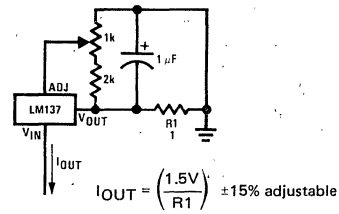
Current Regulator



$$I_{OUT} = \frac{1.250V}{R1}$$

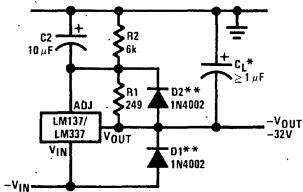
* $0.8\Omega \leq R1 \leq 120\Omega$

Adjustable Current Regulator



$$I_{OUT} = \left(\frac{1.5V}{R1} \right) \pm 15\% \text{ adjustable}$$

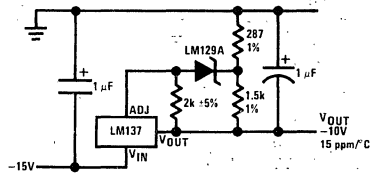
Negative Regulator with Protection Diodes



*When C_L is larger than 20 μF , D1 protects the LM137 in case the input supply is shorted

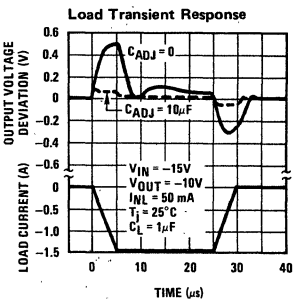
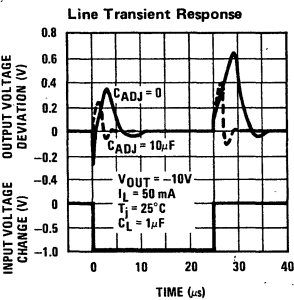
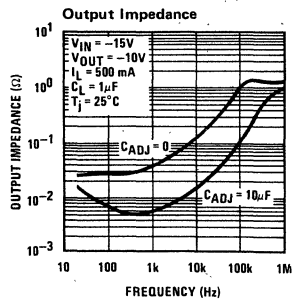
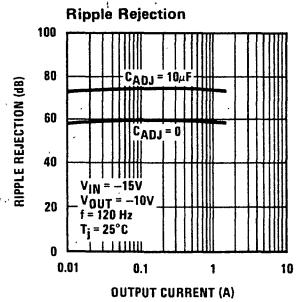
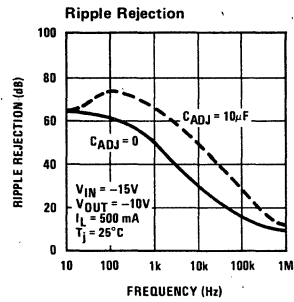
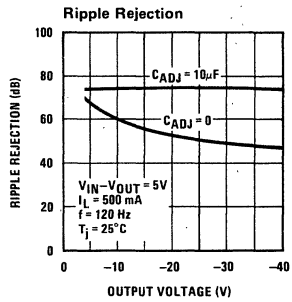
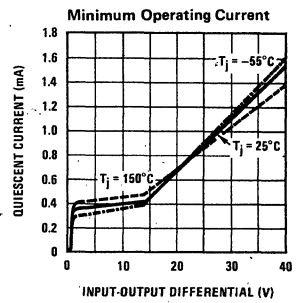
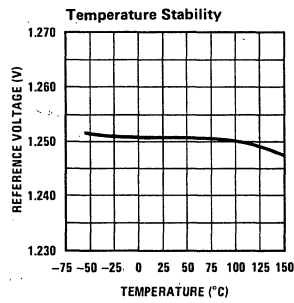
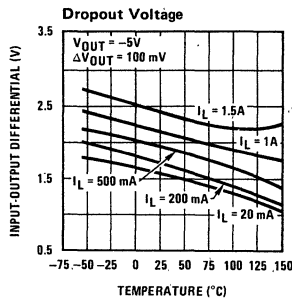
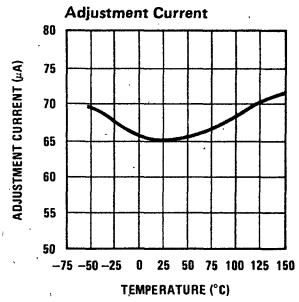
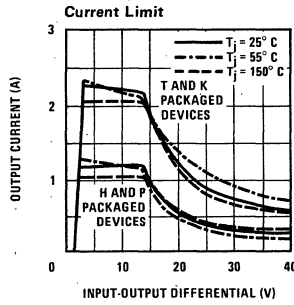
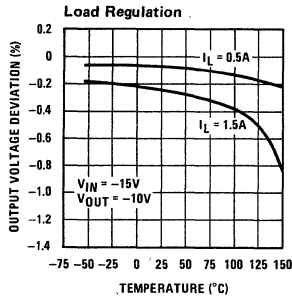
**When $C2$ is larger than 10 μF and $-V_{OUT}$ is larger than $-25V$, D2 protects the LM137 in case the output is shorted

High Stability -10V Regulator



$V_{OUT} = -10V$
15 ppm/°C

Typical Performance Characteristics (K Steel, KC and T Packages)



LM137HV/LM237HV/LM337HV 3-Terminal Adjustable Negative Regulators (High Voltage)

General Description

The LM137HV/LM237HV/LM337HV are adjustable 3-terminal negative voltage regulators capable of supplying in excess of $-1.5A$ over an output voltage range of $-1.2V$ to $-47V$. These regulators are exceptionally easy to apply, requiring only 2 external resistors to set the output voltage and 1 output capacitor for frequency compensation. The circuit design has been optimized for excellent regulation and low thermal transients. Further, the LM137HV series features internal current limiting, thermal shutdown and safe-area compensation, making them virtually blowout-proof against overloads.

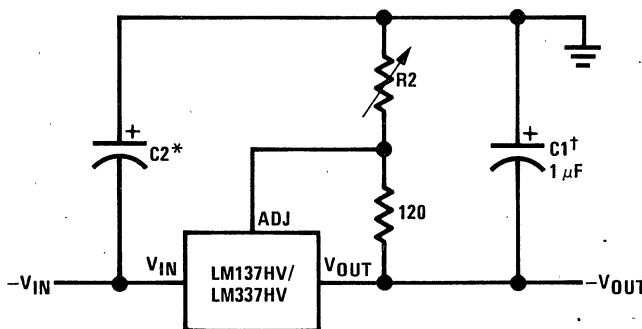
The LM137HV/LM237HV/LM337HV serve a wide variety of applications including local on-card regulation, programmable-output voltage regulation or precision current regulation. The LM137HV/LM237HV/LM337HV are ideal complements to the LM117HV/LM217HV/LM317HV adjustable positive regulators.

Features

- Output voltage adjustable from $-1.2V$ to $-47V$
- $1.5A$ output current guaranteed, $-55^{\circ}C$ to $+150^{\circ}C$
- Line regulation typically $0.01\%/V$
- Load regulation typically 0.3%
- Excellent thermal regulation, $0.002\%/W$
- 77 dB ripple rejection
- Excellent rejection of thermal transients
- $50\text{ ppm}/^{\circ}C$ temperature coefficient
- Temperature-independent current limit
- Internal thermal overload protection
- 100% electrical burn-in
- Standard 3-lead transistor package

Typical Applications

Adjustable Negative Voltage Regulator



$$-V_{OUT} = -1.25V \left(1 + \frac{R2}{120\Omega} \right)$$

† $C1 = 1\ \mu F$ solid tantalum or $10\ \mu F$ aluminum electrolytic required for stability

* $C2 = 1\ \mu F$ solid tantalum is required only if regulator is more than 4" from power-supply filter capacitor

Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input–Output Voltage Differential | 50V |
| Operating Junction Temperature Range | |
| LM137HV | –55°C to +150°C |
| LM237HV | –25°C to +150°C |
| LM337HV | 0°C to +125°C |
| Storage Temperature | –65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Preconditioning

| | |
|--------------------------|------------------|
| Burn-In in Thermal Limit | 100% All Devices |
|--------------------------|------------------|

Electrical Characteristics (Note 1)

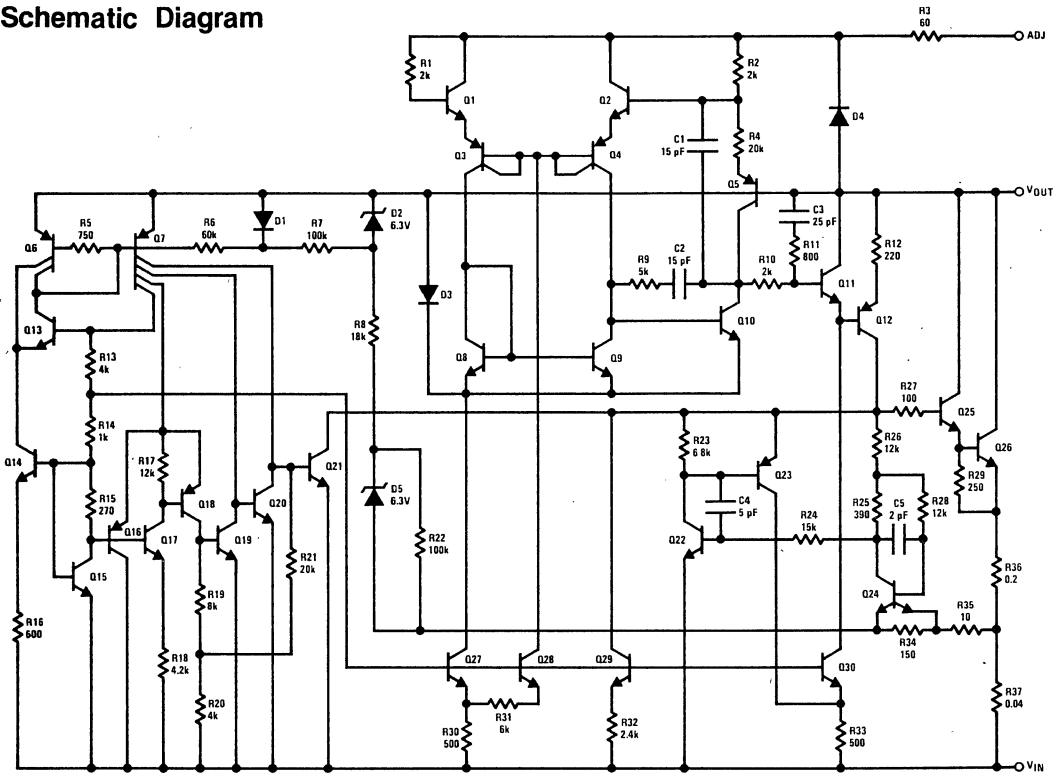
| PARAMETER | CONDITIONS | LM137HV/LM237HV | | | LM337HV | | | UNITS |
|--------------------------------------|---|-----------------|--------|--------|---------|--------|--------|---------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{IN} - V_{OUT} \leq 50\text{V}$, (Note 2) | | 0.01 | 0.02 | | 0.01 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{mA} \leq I_{OUT} \leq I_{MAX}$ $ V_{OUT} \leq 5\text{V}$, (Note 2) $ V_{OUT} \geq 5\text{V}$, (Note 2) | | 15 | 25 | | 15 | 50 | mV |
| | | | 0.3 | 0.5 | | 0.3 | 1.0 | % |
| | | | | | | | | |
| Thermal Regulation | $T_A = 25^\circ\text{C}$, 10 ms Pulse | | 0.002 | 0.02 | | 0.003 | 0.04 | %/W |
| Adjustment Pin Current | | | 65 | 100 | | 65 | 100 | μA |
| Adjustment Pin Current Change | $10\text{mA} \leq I_L \leq I_{MAX}$ $2.5\text{V} \leq V_{IN} - V_{OUT} \leq 50\text{V}$, $T_A = 25^\circ\text{C}$ | | 2 | 5 | | 2 | 5 | μA |
| | | | 3 | 6 | | 3 | 6 | μA |
| Reference Voltage | $T_A = 25^\circ\text{C}$, (Note 3) $3 \leq V_{IN} - V_{OUT} \leq 50\text{V}$, (Note 3) $10\text{mA} \leq I_{OUT} \leq I_{MAX}$, $P \leq P_{MAX}$ | –1.225 | –1.250 | –1.275 | –1.213 | –1.250 | –1.287 | V |
| | | –1.200 | –1.250 | –1.300 | –1.200 | –1.250 | –1.300 | V |
| Line Regulation | $3\text{V} \leq V_{IN} - V_{OUT} \leq 50\text{V}$, (Note 2) | | 0.02 | 0.05 | | 0.02 | 0.07 | %/V |
| Load Regulation | $10\text{mA} \leq I_{OUT} \leq I_{MAX}$, (Note 2) $ V_{OUT} \leq 5\text{V}$ $ V_{OUT} \geq 5\text{V}$ | | 20 | 50 | | 20 | 70 | mV |
| | | | 0.3 | 1 | | 0.3 | 1.5 | % |
| | | | | | | | | |
| Temperature Stability | $T_{MIN} \leq T_j \leq T_{MAX}$ | | 0.6 | | | 0.6 | | % |
| Minimum Load Current | $ V_{IN} - V_{OUT} \leq 50\text{V}$ $ V_{IN} - V_{OUT} \leq 10\text{V}$ | | 2.5 | 5 | | 2.5 | 10 | mA |
| | | | 1.2 | 3 | | 1.5 | 6 | mA |
| Current Limit | $ V_{IN} - V_{OUT} \leq 13\text{V}$ K Package H Package $ V_{IN} - V_{OUT} = 50\text{V}$, $T_A = +25^\circ\text{C}$ K Package H Package | 1.5 | 2.2 | 3.2 | 1.5 | 2.2 | 3.5 | A |
| | | 0.5 | 0.8 | 1.6 | 0.5 | 0.8 | 1.8 | A |
| | | 0.2 | 0.4 | 0.8 | 0.1 | 0.4 | 0.8 | A |
| | | 0.1 | 0.17 | 0.5 | 0.050 | 0.17 | 0.5 | A |
| | | | | | | | | |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{Hz} \leq f \leq 10\text{kHz}$ | | 0.003 | | | 0.003 | | % |
| Ripple Rejection Ratio | $V_{OUT} = -10\text{V}$, $f = 120\text{Hz}$ $C_{ADJ} = 10\mu\text{F}$ | | 60 | | | 60 | | dB |
| | | 66 | 77 | | 66 | 77 | | dB |
| Long-Term Stability | $T_A = 125^\circ\text{C}$, 1000 Hours | | 0.3 | 1 | | 0.3 | 1 | % |
| Thermal Resistance, Junction to Case | H Package K Package | | 12 | 15 | | 12 | 15 | $^\circ\text{C}/\text{W}$ |
| | | | 2.3 | 3 | | 2.3 | 3 | $^\circ\text{C}/\text{W}$ |

Note 1: Unless otherwise specified, these specifications apply $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM137HV, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM237HV and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM337HV; $V_{IN} - V_{OUT} = 5\text{V}$; and $I_{OUT} = 0.1\text{A}$ for the TO-5 package and $I_{OUT} = 0.5\text{A}$ for the TO-3 package. Although power dissipation is internally limited, these specifications are applicable for power dissipations of 2W for the TO-5 and 20W for the TO-3. I_{MAX} is 1.5A for the TO-3 package and 0.2A for the TO-5 package.

Note 2: Regulation is measured at constant junction temperature, using pulse testing with a low duty cycle. Changes in output voltage due to heating effects are covered under the specification for thermal regulation. Load regulation is measured on the output pin at a point 1/8" below the base of the TO-3 and TO-5 packages.

Note 3: Selected devices with tightened tolerance reference voltage available.

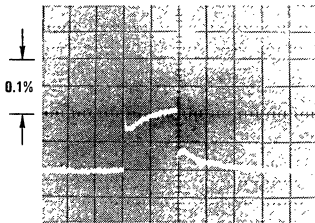
Schematic Diagram



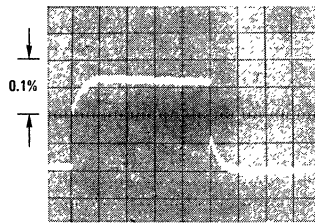
Thermal Regulation

When power is dissipated in an IC, a temperature gradient occurs across the IC chip affecting the individual IC circuit components. With an IC regulator, this gradient can be especially severe since power dissipation is large. Thermal regulation is the effect of these temperature gradients on output voltage (in percentage output change) per Watt of power change in a specified time. Thermal regulation error is independent of electrical regulation or temperature coefficient, and occurs within 5 ms to 50 ms after a change in power dissipation. Thermal regulation depends on IC layout as well as electrical design. The thermal regulation of a voltage regulator is defined as the percentage change of V_{OUT} , per Watt, within the first 10 ms after a step of power is applied. The LM137HV's specification is 0.02%/W, max.

In Figure 1, a typical LM137HV's output drifts only 3 mV (or 0.03% of $V_{OUT} = -10V$) when a 10W pulse is applied for 10 ms. This performance is thus well inside the specification limit of $0.02\%/W \times 10W = 0.2\%$ max. When the 10W pulse is ended, the thermal regulation again shows a 3 mV step as the LM137HV chip cools off. Note that the load regulation error of about 8 mV (0.08%) is additional to the thermal regulation error. In Figure 2, when the 10W pulse is applied for 100 ms, the output drifts only slightly beyond the drift in the first 10 ms, and the thermal error stays well within 0.1% (10 mV).



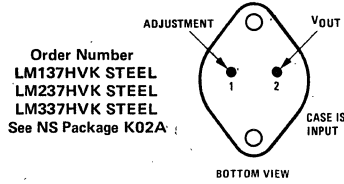
LM137HV, $V_{OUT} = -10V$
 $V_{IN} - V_{OUT} = -40V$
 $I_L = 0A \rightarrow 0.25A \rightarrow 0A$
 Vertical sensitivity, 5 mV/div
FIGURE 1



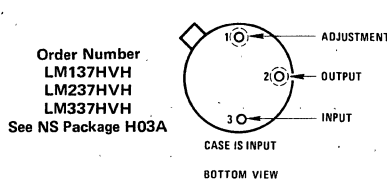
LM137HV, $V_{OUT} = -10V$
 $V_{IN} - V_{OUT} = -40V$
 $I_L = 0A \rightarrow 0.25A \rightarrow 0A$
 Horizontal sensitivity, 20 ms/div
FIGURE 2

Connection Diagrams

**TO-3
Metal Can Package**

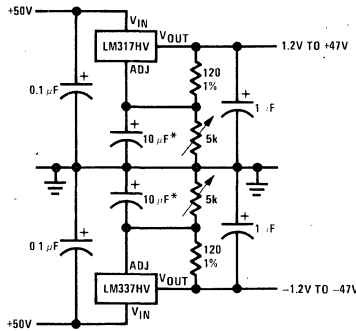


**TO-39
Metal Can Package**



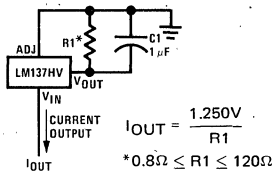
Typical Applications (Continued)

Adjustable High Voltage Regulator

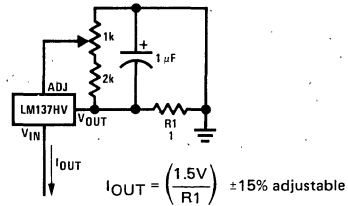


*The 10 μF capacitors are optional to improve ripple-rejection

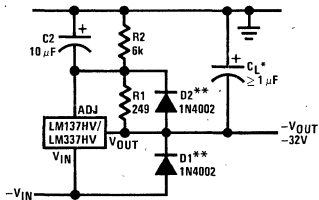
Current Regulator



Adjustable Current Regulator



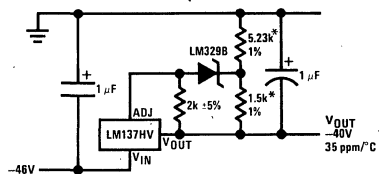
Negative Regulator with Protection Diodes



*When C_L is larger than 20 μF , D1 protects the LM137HV is case the input supply is shorted

**When $C2$ is larger than 10 μF and $-V_{OUT}$ is larger than $-25V$, D2 protects the LM137HV in case the output is shorted

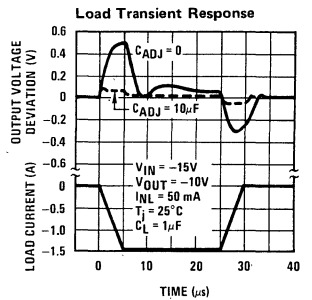
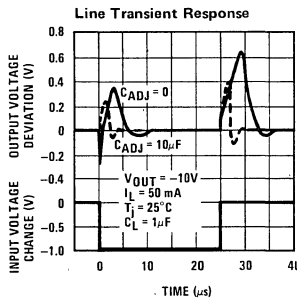
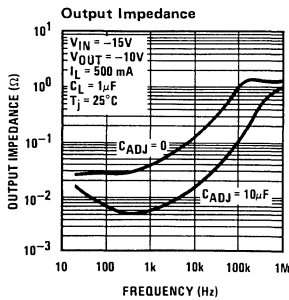
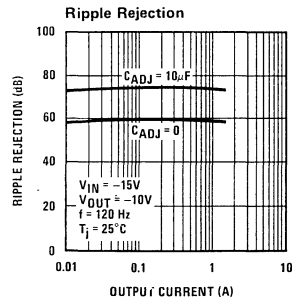
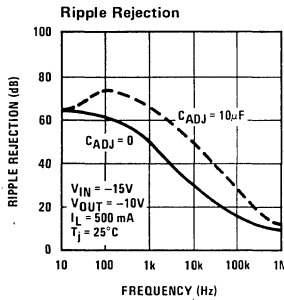
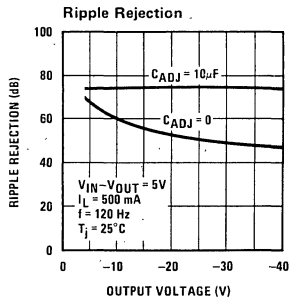
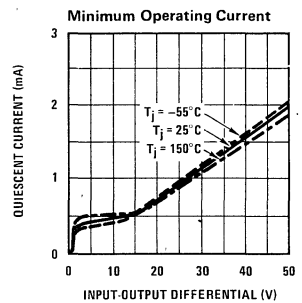
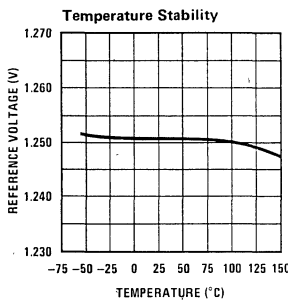
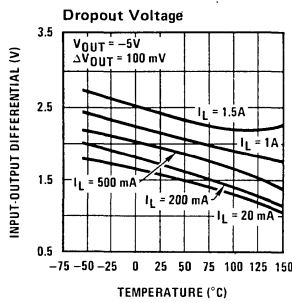
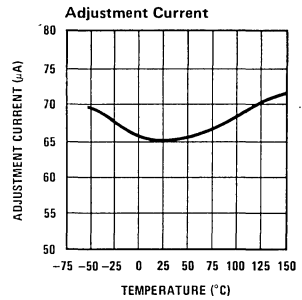
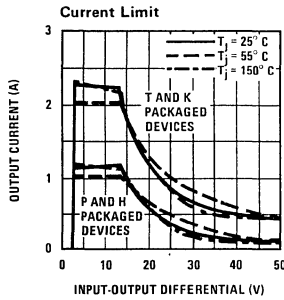
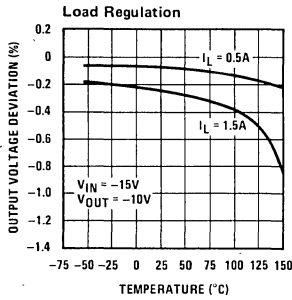
High Stability -40V Regulator



*Use resistors with good tracking TC < 25 ppm/ $^{\circ}C$

Typical Performance Characteristics (H and K STEEL Package)

LM137HV/LM237HV/LM337HV





Voltage Regulators

LM138/LM238/LM338 5 Amp Adjustable Power Regulators

General Description

The LM138/LM238/LM338 are adjustable 3-terminal positive voltage regulators capable of supplying in excess of 5A over a 1.2V to 32V output range. They are exceptionally easy to use and require only 2 resistors to set the output voltage. Careful circuit design has resulted in outstanding load and line regulation — comparable to many commercial power supplies. The LM138 family is supplied in a standard 3-lead transistor package.

A unique feature of the LM138 family is time-dependent current limiting. The current limit circuitry allows peak currents of up to 12A to be drawn from the regulator for short periods of time. This allows the LM138 to be used with heavy transient loads and speeds start-up under full-load conditions. Under sustained loading conditions, the current limit decreases to a safe value protecting the regulator. Also included on the chip are thermal overload protection and safe area protection for the power transistor. Overload protection remains functional even if the adjustment pin is accidentally disconnected.

Normally, no capacitors are needed unless the device is situated far from the input filter capacitors in which case an input bypass is needed. An optional output capacitor can be added to improve transient response. The adjustment terminal can be bypassed to achieve

very high ripple rejections ratios which are difficult to achieve with standard 3-terminal regulators.

Besides replacing fixed regulators or discrete designs, the LM138 is useful in a wide variety of other applications. Since the regulator is "floating" and sees only the input-to-output differential voltage, supplies of several hundred volts can be regulated as long as the maximum input to output differential is not exceeded.

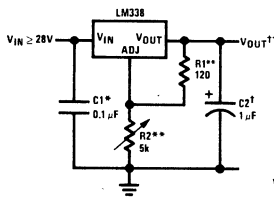
The LM138/LM238/LM338 are packaged in standard steel TO-3 transistor packages. The LM138 is rated for operation from -55°C to +150°C, the LM238 from -25°C to +150°C and the LM338 from 0°C to +125°C.

Features

- Guaranteed 7A peak output current
- Guaranteed 5A output current
- Adjustable output down to 1.2V
- Line regulation typically 0.005%/V
- Load regulation typically 0.1%
- Guaranteed thermal regulation
- Current limit constant with temperature
- 100% electrical burn-in in thermal limit
- Standard 3-lead transistor package

Typical Applications

1.2V–25V Adjustable Regulator

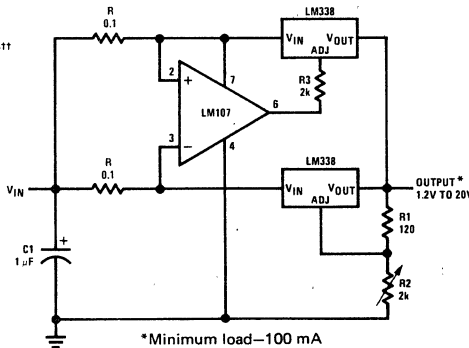


† Optional—improves transient response
 * Needed if device is far from filter capacitors

$$\dagger\dagger V_{OUT} = 1.25V \cdot \left(1 + \frac{R_2}{R_1}\right)$$

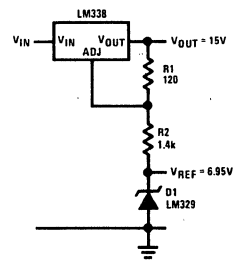
*R1 = 240Ω for LM138 and LM238
 **R1, R2 as an assembly can be ordered from Bourns.
 MIL part no. 7105A-AT2-502
 COMM part no. 7105A-AT7-502

10A Regulator



*Minimum load—100 mA

Regulator and Voltage Reference



Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input-Output Voltage Differential | 35V |
| LM138 | 55 C to +150 C |
| LM238 | 25 C to +150 C |
| LM338 | 0 C to +125°C |
| Storage Temperature | 65 C to +150 C |
| Lead Temperature (Soldering, 10 seconds) | 300 C |

Preconditioning

Burn-In in Thermal Limit

All Devices 100%

Electrical Characteristics (Note 1)

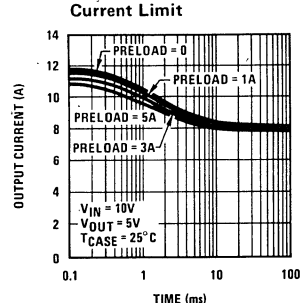
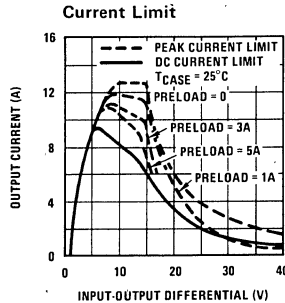
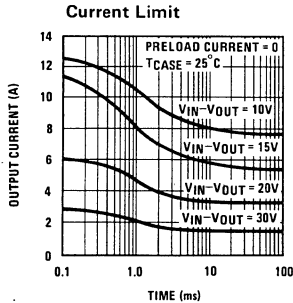
| PARAMETER | CONDITIONS | LM138/LM238 | | | LM338 | | | UNITS |
|--------------------------------------|---|-------------|-------|-------|-------|-------|---------------------------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{IN} - V_{OUT} \leq 35\text{V}$, (Note 2) | | 0.005 | 0.01 | | 0.005 | 0.03 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{ mA} \leq I_{OUT} \leq 5\text{A}$ $V_{OUT} \leq 5\text{V}$, (Note 2) $V_{OUT} \geq 5\text{V}$, (Note 2) | | 5 | 15 | 5 | 25 | mV | |
| | | | 0.1 | 0.3 | 0.1 | 0.5 | % | |
| | | | | | | | | |
| Thermal Regulation | Pulse = 20 ms | | 0.002 | 0.01 | 0.002 | 0.02 | %/W | |
| Adjustment Pin Current | | | 45 | 100 | 45 | 100 | μA | |
| Adjustment Pin Current Change | $10\text{ mA} \leq I_L \leq 5\text{A}$ $3\text{V} \leq (V_{IN} - V_{OUT}) \leq 35\text{V}$ | | 0.2 | 5 | 0.2 | 5 | μA | |
| Reference Voltage | $3 \leq (V_{IN} - V_{OUT}) \leq 35\text{V}$, (Note 3) $10\text{ mA} \leq I_{OUT} \leq 5\text{A}$, $P \leq 50\text{W}$ | 1.19 | 1.24 | 1.29 | 1.19 | 1.24 | 1.29 | V |
| Line Regulation | $3\text{V} \leq V_{IN} - V_{OUT} \leq 35\text{V}$, (Note 2) | | 0.02 | 0.04 | 0.02 | 0.06 | %/V | |
| Load Regulation | $10\text{ mA} \leq I_{OUT} \leq 5\text{A}$, (Note 2) $V_{OUT} \leq 5\text{V}$ $V_{OUT} \geq 5\text{V}$ | | 20 | 30 | 20 | 50 | mV | |
| | | | 0.3 | 0.6 | 0.3 | 1.0 | % | |
| | | | | | | | | |
| Temperature Stability | $T_{MIN} \leq T_J \leq T_{MAX}$ | | 1 | | 1 | | % | |
| Minimum Load Current | $V_{IN} - V_{OUT} = 35\text{V}$ | | 3.5 | 5 | 3.5 | 10 | mA | |
| Current Limit | $V_{IN} - V_{OUT} \leq 10\text{V}$ DC 0.5 ms Peak $V_{IN} - V_{OUT} = 30\text{V}$ | 5.0 | 8 | | 5.0 | 8 | A | |
| | | 7 | 12 | | 7 | 12 | A | |
| | | | 1 | | | 1 | A | |
| | | | | | | | | |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{ Hz} \leq f \leq 10\text{ kHz}$ | | | 0.003 | | 0.003 | % | |
| Ripple Rejection Ratio | $V_{OUT} = 10\text{V}$, $f = 120\text{ Hz}$ $C_{ADJ} = 10\text{ }\mu\text{F}$ | | 60 | | 60 | | dB | |
| | | 60 | 75 | | 60 | 75 | dB | |
| Long Term Stability | $T_A = 125^\circ\text{C}$ | | 0.3 | 1 | 0.3 | 1 | % | |
| Thermal Resistance, Junction to Case | K Package | | | 1.0 | | 1.0 | $^\circ\text{C}/\text{W}$ | |

Note 1: Unless otherwise specified, these specifications apply $-55^\circ\text{C} \leq T_J \leq +150^\circ\text{C}$ for the LM138, $-25^\circ\text{C} \leq T_J \leq +150^\circ\text{C}$ for the LM238 and $0^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$ for the LM338, $V_{IN} - V_{OUT} = 5\text{V}$ and $I_{OUT} = 2.5\text{A}$. Although power dissipation is internally limited, these specifications are applicable for power dissipations up to 50W.

Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects are taken into account separately by thermal regulation.

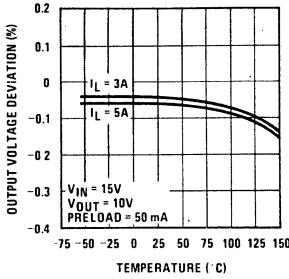
Note 3: Selected devices with tightened tolerance reference voltage available.

Typical Performance Characteristics

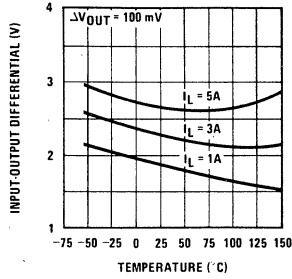


Typical Performance Characteristics (Continued)

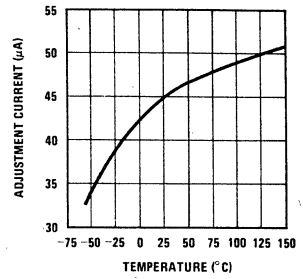
Load Regulation



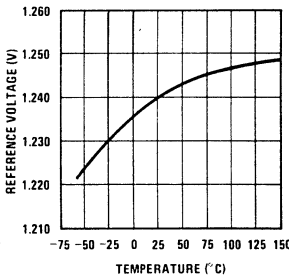
Dropout Voltage



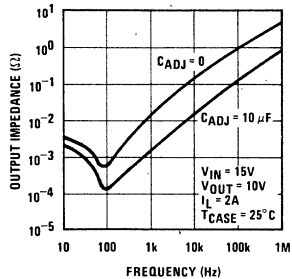
Adjustment Current



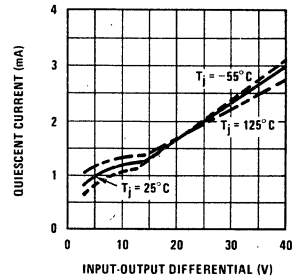
Temperature Stability



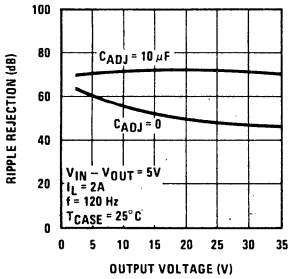
Output Impedance



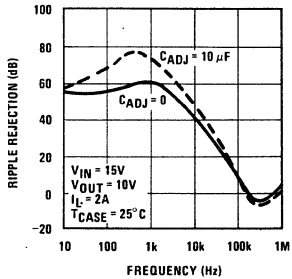
Minimum Operating Current



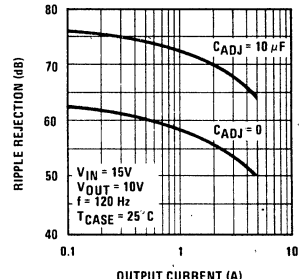
Ripple Rejection



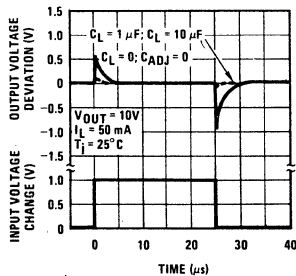
Ripple Rejection



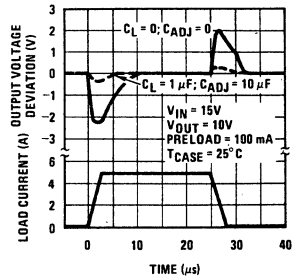
Ripple Rejection



Line Transient Response



Load Transient Response



Application Hints

In operation, the LM138 develops a nominal 1.25V reference voltage, V_{REF} , between the output and adjustment terminal. The reference voltage is impressed across program resistor R_1 and, since the voltage is constant, a constant current I_1 then flows through the output set resistor R_2 , giving an output voltage of

$$V_{OUT} = V_{REF} \left(1 + \frac{R_2}{R_1} \right) + I_{ADJ} R_2.$$

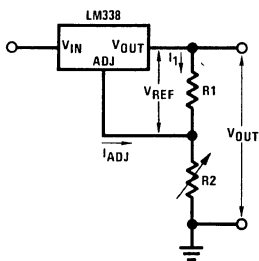


FIGURE 1

Since the 50 μ A current from the adjustment terminal represents an error term, the LM138 was designed to minimize I_{ADJ} and make it very constant with line and load changes. To do this, all quiescent operating current is returned to the output establishing a minimum load current requirement. If there is insufficient load on the output, the output will rise.

External Capacitors

An input bypass capacitor is recommended. A 0.1 μ F disc or 1 μ F solid tantalum on the input is suitable input bypassing for almost all applications. The device is more sensitive to the absence of input bypassing when adjustment or output capacitors are used but the above values will eliminate the possibility of problems.

The adjustment terminal can be bypassed to ground on the LM138 to improve ripple rejection. This bypass capacitor prevents ripple from being amplified as the output voltage is increased. With a 10 μ F bypass capacitor 75 dB ripple rejection is obtainable at any output level. Increases over 20 μ F do not appreciably improve the ripple rejection at frequencies above 120 Hz. If the bypass capacitor is used, it is sometimes necessary to include protection diodes to prevent the capacitor from discharging through internal low current paths and damaging the device.

In general, the best type of capacitors to use are solid tantalum. Solid tantalum capacitors have low impedance even at high frequencies. Depending upon capacitor construction, it takes about 25 μ F in aluminum electrolytic to equal 1 μ F solid tantalum at high frequencies. Ceramic capacitors are also good at high frequencies, but some types have a large decrease in capacitance at frequencies around 0.5 MHz. For this reason, 0.01 μ F disc may seem to work better than a 0.1 μ F disc as a bypass.

Although the LM138 is stable with no output capacitors, like any feedback circuit, certain values of external capacitance can cause excessive ringing. This occurs with values between 500 pF and 5000 pF. A 1 μ F solid tantalum (or 25 μ F aluminum electrolytic) on the output swamps this effect and insures stability.

Load Regulation

The LM138 is capable of providing extremely good load regulation but a few precautions are needed to obtain maximum performance. The current set resistor connected between the adjustment terminal and the output terminal (usually 240 Ω) should be tied directly to the output of the regulator rather than near the load. This eliminates line drops from appearing effectively in series with the reference and degrading regulation. For example, a 15V regulator with 0.05 Ω resistance between the regulator and load will have a load regulation due to line resistance of 0.05 Ω \times I_L . If the set resistor is connected near the load the effective line resistance will be 0.05 Ω (1 + R_2/R_1) or in this case, 11.5 times worse.

Figure 2 shows the effect of resistance between the regulator and 240 Ω set resistor.

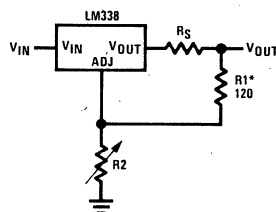


FIGURE 2. Regulator with Line Resistance in Output Lead

With the TO-3 package, it is easy to minimize the resistance from the case to the set resistor, by using 2 separate leads to the case. The ground of R_2 can be returned near the ground of the load to provide remote ground sensing and improve load regulation.

Protection Diodes

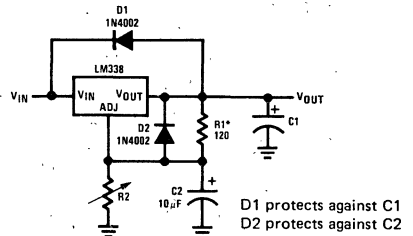
When external capacitors are used with any IC regulator it is sometimes necessary to add protection diodes to prevent the capacitors from discharging through low current points into the regulator. Most 20 μ F capacitors have low enough internal series resistance to deliver 20A spikes when shorted. Although the surge is short, there is enough energy to damage parts of the IC.

When an output capacitor is connected to a regulator and the input is shorted, the output capacitor will discharge into the output of the regulator. The discharge current depends on the value of the capacitor, the output voltage of the regulator, and the rate of decrease of V_{IN} . In the LM138 this discharge path is through a large junction that is able to sustain 25A surge with no problem. This is not true of other types of positive

Application Hints (Continued)

regulators. For output capacitors of 100 μ F or less at output of 15V or less, there is no need to use diodes.

The bypass capacitor on the adjustment terminal can discharge through a low current junction. Discharge occurs when *either* the input or output is shorted. Internal to the LM138 is a 50 Ω resistor which limits the peak discharge current. No protection is needed for output voltages of 25V or less and 10 μ F capacitance. *Figure 3* shows an LM138 with protection diodes included for use with outputs greater than 25V and high values of output capacitance.

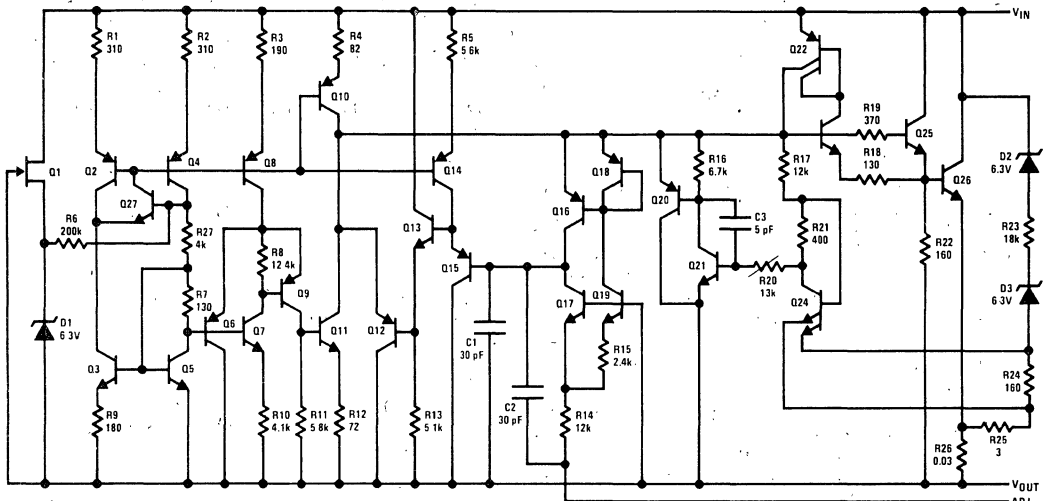


$$V_{OUT} = 1.25V \left(1 + \frac{R_2}{R_1} \right) + R_2 I_{ADJ}$$

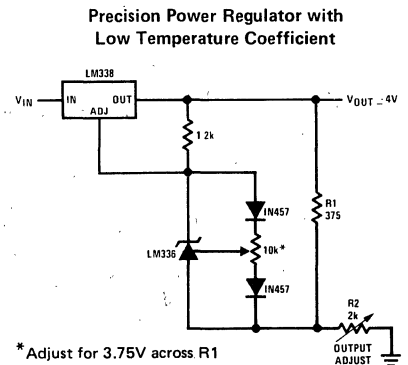
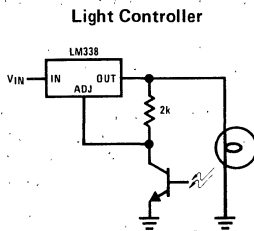
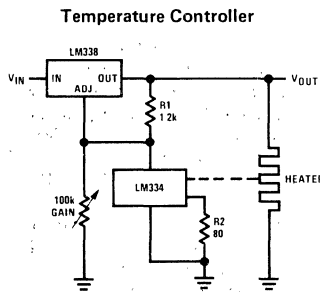
*R1 = 240 Ω for LM138 and LM238

FIGURE 3. Regulator with Protection Diodes

Schematic Diagram

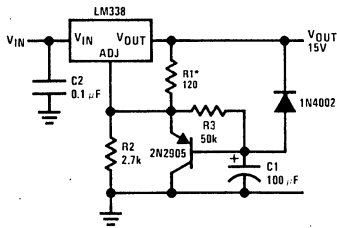


Typical Applications (Continued)



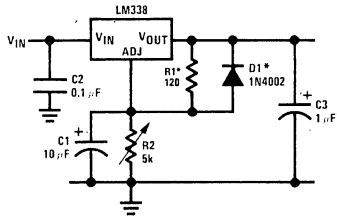
Typical Applications (Continued)

Slow Turn-ON 15V Regulator



*R1 = 240Ω for LM138 and LM238

Adjustable Regulator with Improved Ripple Rejection

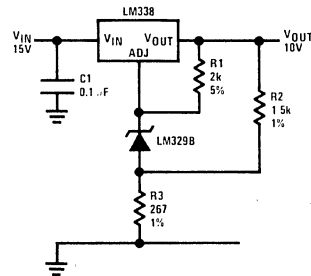


†Solid tantalum

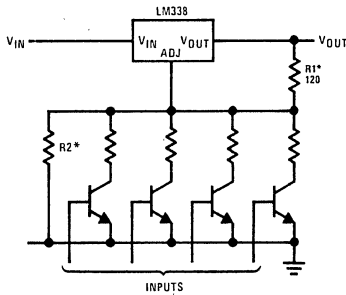
*Discharges C1 if output is shorted to ground

**R1 = 240Ω for LM138 and LM238

High Stability 10V Regulator



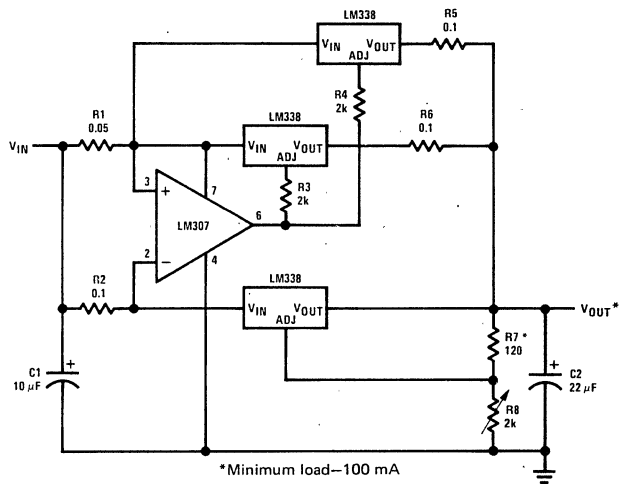
Digitally Selected Outputs



*Sets maximum V_{OUT}

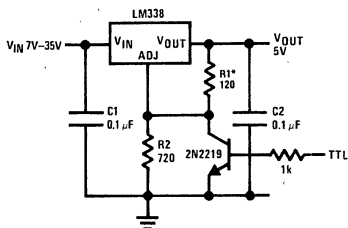
**R1 = 240Ω for LM138 and LM238

15A Regulator



*Minimum load—100 mA

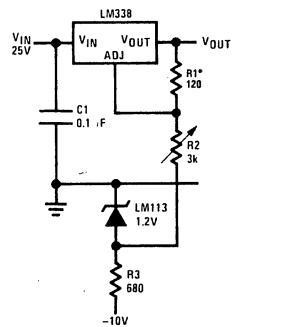
5V Logic Regulator with Electronic Shutdown**



*R1 = 240Ω for LM138 or LM238

**Minimum output ≈ 1.2V

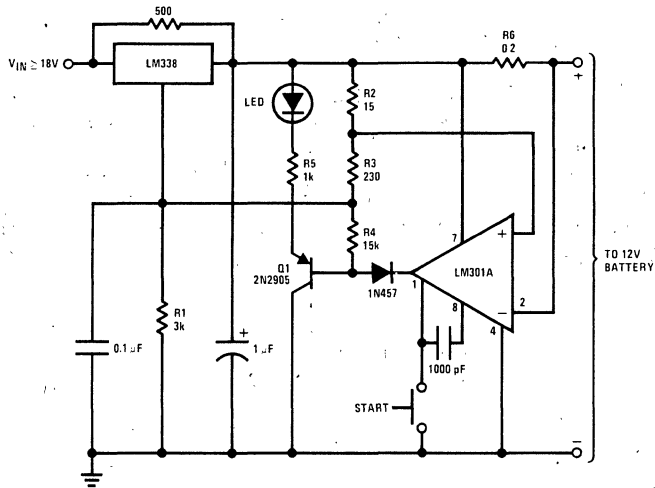
0 to 22V Regulator



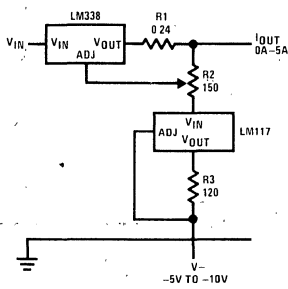
*R1=240Ω for LM138 and LM238

Typical Applications (Continued)

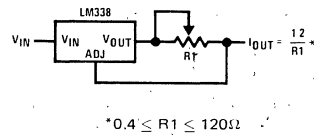
12V Battery Charger



Adjustable Current Regulator

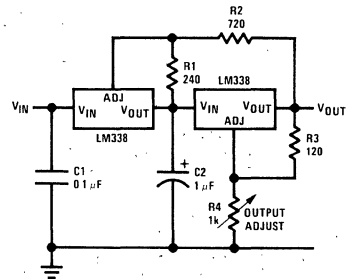


Precision Current Limiter

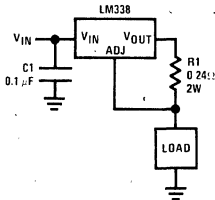
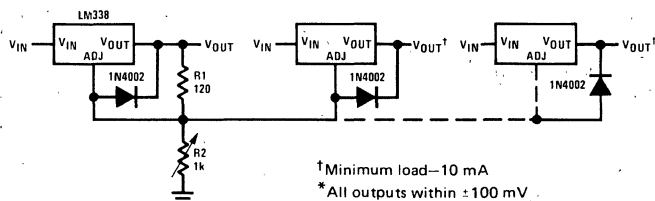


$$*0.4 \leq R1 \leq 120\Omega$$

Tracking Preregulator



5A Current Regulator

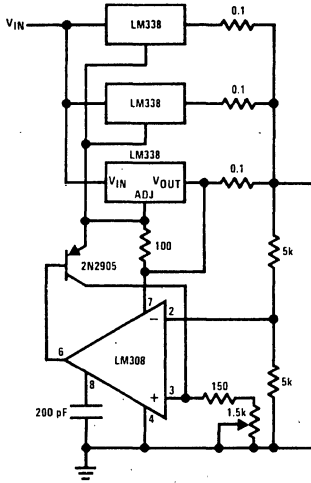
Adjusting Multiple On-Card Regulators
with Single Control*

†Minimum load—10 mA

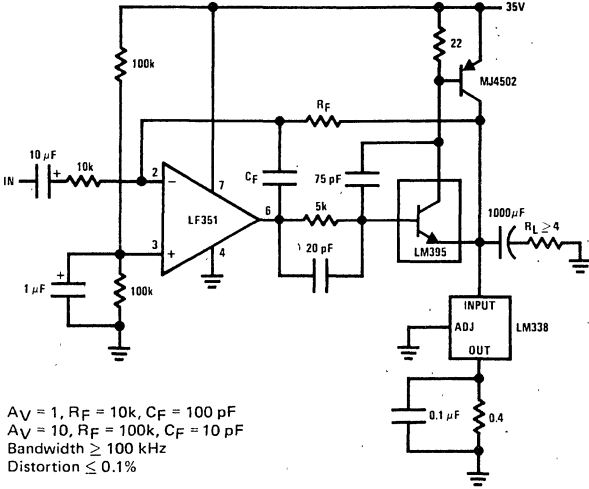
*All outputs within ± 100 mV.

Typical Applications (Continued)

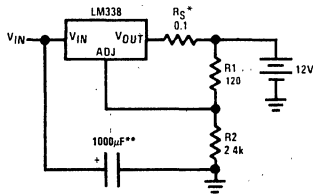
Adjustable 15A Regulator



Power Amplifier



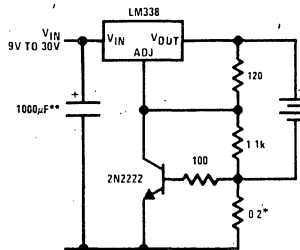
Simple 12V Battery Charger



*RS—sets output impedance of charger $Z_{OUT} = R_S \left(1 + \frac{R_2}{R_1} \right)$
 Use of RS allows low charging rates with fully charged battery.

**1000 μF is recommended to filter out any input transients.

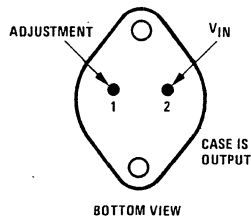
Current Limited 6V Charger



*Sets max charge current to 3A
 **1000 μF is recommended to filter out any input transients.

Connection Diagram

Metal Can Package



Order Number LM138K STEEL,
 LM238K STEEL or LM338K STEEL
 See NS Package K02A



Voltage Regulators

LM140A/LM140/LM340A/LM340 Series 3-Terminal Positive Regulators

General Description

The LM140A/LM140/LM340A/LM340 series of positive 3-terminal voltage regulators are designed to provide superior performance as compared to the previously available 78XX series regulator. Computer programs were used to optimize the electrical and thermal performance of the packaged IC which results in outstanding ripple rejection, superior line and load regulation in high power applications (over 15W).

With these advances in design, the LM340 is now guaranteed to have line and load regulation that is a factor of 2 better than previously available devices. Also, all parameters are guaranteed at 1A vs 0.5A output current. The LM140A/LM340A provide tighter output voltage tolerance, $\pm 2\%$ along with $0.01\%/V$ line regulation and $0.3\%/A$ load regulation.

Current limiting is included to limit peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high for the heat sinking provided, the thermal shutdown circuit takes over limiting die temperature.

Considerable effort was expended to make the LM140-XX series of regulators easy to use and minimize the number of external components. It is not necessary to bypass the output, although this does improve transient response. Input bypassing is needed only if the regulator is located far from the filter capacitor of the power supply.

Although designed primarily as fixed voltage regulators, these devices can be used with external components to obtain adjustable voltages and currents.

The entire LM140A/LM140/LM340A/LM340 series of regulators is available in the metal TO-3 power package

and the LM340A/LM340 series is also available in the TO-220 plastic power package. Where other voltages are required, the LM117 series provides +1.2V to +57V.

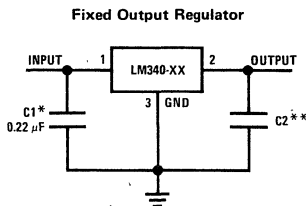
Features

- Complete specifications at 1A load
- Output voltage tolerances of $\pm 2\%$ at $T_j = 25^\circ\text{C}$ and $\pm 4\%$ over the temperature range (LM140A/LM340A)
- Fixed output voltages available 5, 12, 15V
- Line regulation of 0.01% of $V_{OUT}/V \Delta V_{IN}$ at 1A load (LM140A/LM340A)
- Load regulation of 0.3% of $V_{OUT}/A \Delta I_{LOAD}$ (LM140A/LM340A)
- Internal thermal overload protection
- Internal short-circuit current limit
- Output transistor safe area protection
- 100% thermal limit burn-in
- Special circuitry allows start-up even if output is pulled to negative voltage (\pm supplies)

LM140 Series Package and Power Capability

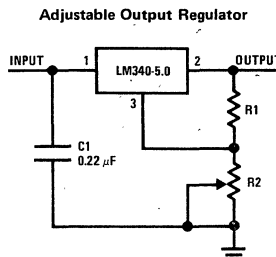
| DEVICE | PACKAGE | RATED POWER DISSIPATION | DESIGN LOAD CURRENT |
|------------------|---------|-------------------------|---------------------|
| LM140 LM340 | TO-3 | 20W | 1.5A |
| LM340T | TO-220 | 15W | 1.5A |
| LM341 | TO-202 | 7.5W | 0.5A |
| LM342 | TO-202 | 7.5W | 0.25A |
| LM140L LM340L | TO-39 | 2W | 0.1A |
| LM340L | TO-92 | 1.2W | 0.1A |

Typical Applications



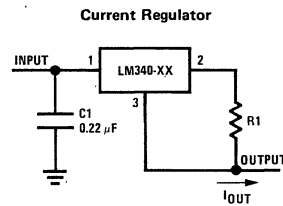
*Required if the regulator is located far from the power supply filter

** Although no output capacitor is needed for stability, it does help transient response. (If needed, use 0.1 μF , ceramic disc)



$$V_{OUT} = 5V + (5V/R1 + I_Q) R2$$

$$5V/R1 > 3 I_Q, \text{ load regulation } (L_r) \approx [(R1 + R2)/R1] (L_r \text{ of LM340-5})$$



$$I_{OUT} = \frac{V_{2-3}}{R1} + I_Q$$

$$\Delta I_Q = 1.3 \text{ mA over line and load changes}$$

Absolute Maximum Ratings

| | |
|---|--------------------|
| Input Voltage ($V_O = 5V, 12V, 15V$) | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range (T_A) | |
| LM140A/LM140 | -55°C to +125°C |
| LM340A/LM340 | 0°C to +70°C |
| Maximum Junction Temperature (TO-3 Package K, KC) | 150°C |
| (TO-220 Package T) | 125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | |
| TO-3 Package K, KC | 300°C |
| TO-220 Package T | 230°C |

Electrical Characteristics LM140A/LM340A (Note 2)

$I_{OUT} = 1A$, -55°C ≤ T_j ≤ +150°C (LM140A), or 0°C ≤ T_j ≤ +125°C (LM340A) unless otherwise specified.

| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS |
|---|---|-----------------------|-----|----------------------|------------------------|-----|----------------------|--------------------------|-----|------|-------|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_j = 25^\circ\text{C}$ | 4.9 | 5 | 5.1 | 11.75 | 12 | 12.25 | 14.7 | 15 | 15.3 | V |
| | $P_D \leq 15W$, $5\text{ mA} \leq I_O \leq 1A$ | 4.8 | | 5.2 | 11.5 | | 12.5 | 14.4 | | 15.6 | V |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | (7.5 ≤ V_{IN} ≤ 20) | | | (14.8 ≤ V_{IN} ≤ 27) | | | (17.9 ≤ V_{IN} ≤ 30) | | | V |
| ΔV_O Line Regulation | $I_O = 500\text{ mA}$ | 10 | | | 18 | | | 22 | | | mV |
| | ΔV_{IN} | (7.5 ≤ V_{IN} ≤ 20) | | | (14.8 ≤ V_{IN} ≤ 27) | | | (17.9 ≤ V_{IN} ≤ 30) | | | V |
| | $T_j = 25^\circ\text{C}$ | 3 | | | 4 | | | 4 | | | mV |
| | ΔV_{IN} | (7.3 ≤ V_{IN} ≤ 20) | | | (14.5 ≤ V_{IN} ≤ 27) | | | (17.5 ≤ V_{IN} ≤ 30) | | | V |
| | $T_j = 25^\circ\text{C}$ Over Temperature | 4 | | | 9 | | | 10 | | | mV |
| ΔV_{IN} | (8 ≤ V_{IN} ≤ 12) | | | (16 ≤ V_{IN} ≤ 22) | | | (20 ≤ V_{IN} ≤ 26) | | | V | |
| ΔV_O Load Regulation | $T_j = 25^\circ\text{C}$ | 10 | | | 12 | | | 12 | | | mV |
| | $5\text{ mA} \leq I_O \leq 1.5A$ | 15 | | | 19 | | | 21 | | | mV |
| | $250\text{ mA} \leq I_O \leq 750\text{ mA}$ Over Temperature, $5\text{ mA} \leq I_O \leq 1A$ | 25 | | | 60 | | | 75 | | | mV |
| I_Q Quiescent Current | $T_j = 25^\circ\text{C}$ | 6 | | | 6 | | | 6 | | | mA |
| | Over Temperature | 6.5 | | | 6.5 | | | 6.5 | | | mA |
| ΔI_Q Quiescent Current Change | $5\text{ mA} \leq I_O \leq 1A$ | 0.5 | | | 0.5 | | | 0.5 | | | mA |
| | $I_O = 500\text{ mA}$ | 0.8 | | | 0.8 | | | 0.8 | | | mA |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | (8 ≤ V_{IN} ≤ 25) | | | (15 ≤ V_{IN} ≤ 30) | | | (17.9 ≤ V_{IN} ≤ 30) | | | V |
| | $T_j = 25^\circ\text{C}$, $I_O = 1A$ $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | 0.8 | | | 0.8 | | | 0.8 | | | mA |
| V_N Output Noise Voltage | $T_A = 25^\circ\text{C}$, $10\text{ Hz} \leq f \leq 100\text{ kHz}$ | 40 | | | 75 | | | 90 | | | μV |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $T_j = 25^\circ\text{C}$, $f = 120\text{ Hz}$, $I_O = 1A$ | 68 | 80 | | 61 | 72 | | 60 | 70 | | dB |
| | $f = 120\text{ Hz}$, $I_O = 500\text{ mA}$, Over Temperature, or $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | 68 | | | 61 | | | 60 | | | dB |
| | | (8 ≤ V_{IN} ≤ 18) | | | (15 ≤ V_{IN} ≤ 25) | | | (18.5 ≤ V_{IN} ≤ 28.5) | | | V |
| R_O Dropout Voltage Output Resistance Short-Circuit Current Peak Output Current Average TC of V_O | $T_j = 25^\circ\text{C}$, $I_O = 1A$ | 2.0 | | | 2.0 | | | 2.0 | | | V |
| | $f = 1\text{ kHz}$ | 8 | | | 18 | | | 19 | | | mΩ |
| | $T_j = 25^\circ\text{C}$ | 2.1 | | | 1.5 | | | 1.2 | | | A |
| | $T_j = 25^\circ\text{C}$ | 2.4 | | | 2.4 | | | 2.4 | | | A |
| | Min, $T_j = 0^\circ\text{C}$, $I_O = 5\text{ mA}$ | -0.6 | | | -1.5 | | | -1.8 | | | mV/°C |
| V_{IN} Input Voltage Required to Maintain Line Regulation | $T_j = 25^\circ\text{C}$ | 7.3 | | | 14.5 | | | 17.5 | | | V |

Note 1: Thermal resistance of the TO-3 package (K, KC) is typically 4°C/W junction to case and 35°C/W case to ambient. Thermal resistance of the TO-220 package (T) is typically 4°C/W junction to case and 50°C/W case to ambient.

Note 2: All characteristics are measured with a capacitor across the input of 0.22 μF and a capacitor across the output of 0.1 μF. All characteristics except noise voltage and ripple rejection ratio are measured using pulse techniques ($t_W \leq 10\text{ ms}$, duty cycle ≤ 5%). Output voltage changes due to changes in internal temperature must be taken into account separately.

Electrical Characteristics LM140 (Note 2)

-55°C ≤ T_j ≤ +150°C unless otherwise noted.

| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS | | | |
|--|--|--|---|------------------------------|----------------------------|-----|-------------------------------|-------------------------------|-----|---------------------------------|-------------------------------|-----|-------|----|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | | | |
| V _O | Output Voltage | T _j = 25°C, 5 mA ≤ I _O ≤ 1A | | | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V |
| | | P _D ≤ 15W, 5 mA ≤ I _O ≤ 1A | | | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V |
| | | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | | (8 ≤ V _{IN} ≤ 20) | | | (15.5 ≤ V _{IN} ≤ 27) | | | (18.5 ≤ V _{IN} ≤ 30) | | | V |
| ΔV _O | Line Regulation | I _O = 500 mA | T _j = 25°C | | 3 | 50 | | 4 | 120 | | 4 | 150 | mV | |
| | | | ΔV _{IN} | | (7 ≤ V _{IN} ≤ 25) | | | (14.5 ≤ V _{IN} ≤ 30) | | | (17.5 ≤ V _{IN} ≤ 30) | | | V |
| | | | -55°C ≤ T _j ≤ +150°C | | | | | 120 | | | 150 | | | mV |
| | I _O ≤ 1A | T _j = 25°C | | 50 | | | 120 | | | 150 | | | mV | |
| | | ΔV _{IN} | | (7.3 ≤ V _{IN} ≤ 20) | | | (14.6 ≤ V _{IN} ≤ 27) | | | (17.7 ≤ V _{IN} ≤ 30) | | | V | |
| | | -55°C ≤ T _j ≤ +150°C | | 25 | | | 60 | | | 75 | | | mV | |
| ΔV _O | Load Regulation | T _j = 25°C | 5 mA ≤ I _O ≤ 1.5A | | 10 | 50 | | 12 | 120 | | 12 | 150 | mV | |
| | | | 250 mA ≤ I _O ≤ 750 mA | | 25 | | | 60 | | | 75 | | | mV |
| | | | -55°C ≤ T _j ≤ +150°C, 5 mA ≤ I _O ≤ 1A | | 50 | | | 120 | | | 150 | | | mV |
| I _Q | Quiescent Current | I _O ≤ 1A | T _j = 25°C | | 6 | | | 6 | | | 6 | | | mA |
| | | | -55°C ≤ T _j ≤ +150°C | | 7 | | | 7 | | | 7 | | | mA |
| ΔI _Q | Quiescent Current Change | 5 mA ≤ I _O ≤ 1A | | 0.5 | | | 0.5 | | | 0.5 | | | mA | |
| | | T _j = 25°C, I _O ≤ 1A | | 0.8 | | | 0.8 | | | 0.8 | | | mA | |
| | | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | (8 ≤ V _{IN} ≤ 20) | | | (15 ≤ V _{IN} ≤ 27) | | | (18.5 ≤ V _{IN} ≤ 30) | | | V | |
| | | I _O ≤ 500 mA, -55°C ≤ T _j ≤ +150°C | | 0.8 | | | 0.8 | | | 0.8 | | | mA | |
| V _N | Output Noise Voltage | T _A = 25°C, 10 Hz ≤ f ≤ 100 kHz | | 40 | | | 75 | | | 90 | | | μV | |
| | | f = 120 Hz | | 68 | | | 61 | | | 60 | | | dB | |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ | Ripple Rejection | I _O ≤ 1A, T _j = 25°C or I _O ≤ 500 mA, -55°C ≤ T _j ≤ +150°C | | 80 | | | 72 | | | 70 | | | dB | |
| | | V _{MIN} ≤ V _{IN} ≤ V _{MAX} | | (8 ≤ V _{IN} ≤ 18) | | | (15 ≤ V _{IN} ≤ 25) | | | (18.5 ≤ V _{IN} ≤ 28.5) | | | V | |
| | | I _O ≤ 500 mA, -55°C ≤ T _j ≤ +150°C | | 68 | | | 61 | | | 60 | | | dB | |
| R _O | Dropout Voltage | T _j = 25°C, I _{OUT} = 1A | | 2.0 | | | 2.0 | | | 2.0 | | | V | |
| | Output Resistance | f = 1 kHz | | 8 | | | 18 | | | 19 | | | mΩ | |
| | Short-Circuit Current | T _j = 25°C | | 2.1 | | | 1.5 | | | 1.2 | | | A | |
| | Peak Output Current | T _j = 25°C | | 2.4 | | | 2.4 | | | 2.4 | | | A | |
| | Average TC of V _{OUT} | 0°C ≤ T _j ≤ +150°C, I _O = 5 mA | | -0.6 | | | -1.5 | | | -1.8 | | | mV/°C | |
| V _{IN} | Input Voltage Required to Maintain Line Regulation | T _j = 25°C, I _O ≤ 1A | | 7.3 | | | 14.6 | | | 17.7 | | | V | |

Note 2: All characteristics are measured with a capacitor across the input of 0.22 μF and a capacitor across the output of 0.1 μF. All characteristics except noise voltage and ripple rejection ratio are measured using pulse techniques (t_W ≤ 10 ms, duty cycle ≤ 5%). Output voltage changes due to changes in internal temperature must be taken into account separately.

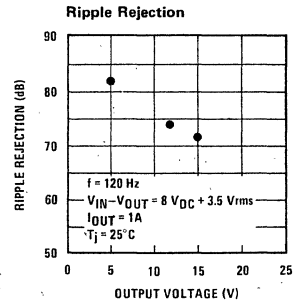
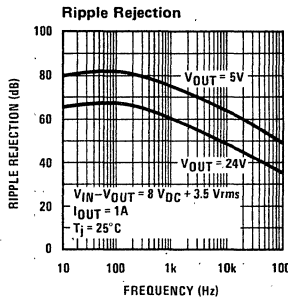
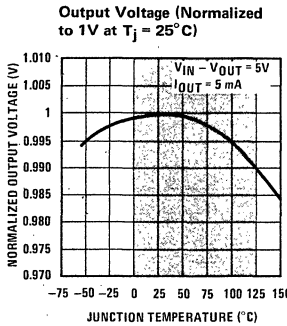
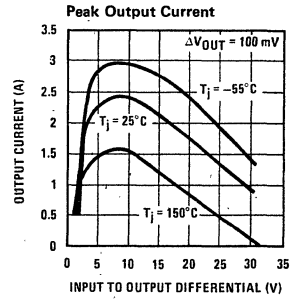
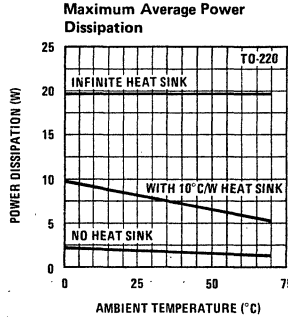
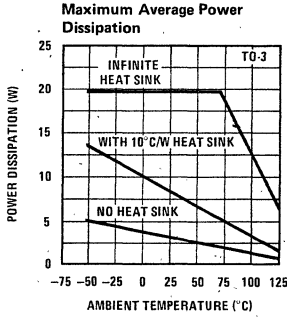
Electrical Characteristics LM340 (Note 2)

$0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ unless otherwise noted.

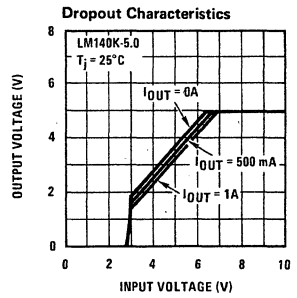
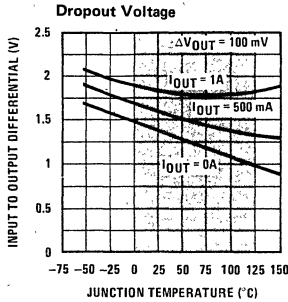
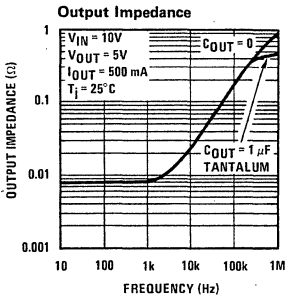
| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS | | | | | |
|--|--|--|--|---|-----|--------------------------------------|--------------------------------------|-----|--------------------------------------|--|-------|-------|--------------------------------------|-----|-----|----|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | | | | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | | | | | |
| V_O | Output Voltage | $T_j = 25^{\circ}\text{C}, 5\text{ mA} \leq I_O \leq 1\text{ A}$ | | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V | | | |
| | | $P_D \leq 15\text{ W}, 5\text{ mA} \leq I_O \leq 1\text{ A}$ | | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V | | | |
| | | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | (7 $\leq V_{\text{IN}} \leq 20$) | | | (14.5 $\leq V_{\text{IN}} \leq 27$) | | | (17.5 $\leq V_{\text{IN}} \leq 30$) | | | V | | | |
| ΔV_O | Line Regulation | $I_O = 500\text{ mA}$ | $T_j = 25^{\circ}\text{C}$ | 3 | 50 | 4 | 120 | 4 | 150 | | | mV | | | | |
| | | | ΔV_{IN} | (7 $\leq V_{\text{IN}} \leq 25$) | | | (14.5 $\leq V_{\text{IN}} \leq 30$) | | | (17.5 $\leq V_{\text{IN}} \leq 30$) | | | V | | | |
| | | | $0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ | | | | 50 | | | 120 | | | 150 | mV | | |
| | $I_O \leq 1\text{ A}$ | ΔV_{IN} | (8 $\leq V_{\text{IN}} \leq 20$) | | | (15 $\leq V_{\text{IN}} \leq 27$) | | | (18.5 $\leq V_{\text{IN}} \leq 30$) | | | V | | | | |
| | | $T_j = 25^{\circ}\text{C}$ | | | | 50 | | | 120 | | | 150 | mV | | | |
| | | ΔV_{IN} | (7.3 $\leq V_{\text{IN}} \leq 20$) | | | (14.6 $\leq V_{\text{IN}} \leq 27$) | | | (17.7 $\leq V_{\text{IN}} \leq 30$) | | | V | | | | |
| ΔV_O | Load Regulation | $T_j = 25^{\circ}\text{C}$ | $5\text{ mA} \leq I_O \leq 1.5\text{ A}$ | 10 | 50 | 12 | 120 | 12 | 150 | | | mV | | | | |
| | | | $250\text{ mA} \leq I_O \leq 750\text{ mA}$ | | | | 25 | | | 60 | | | 75 | mV | | |
| | | | $5\text{ mA} \leq I_O \leq 1\text{ A}, 0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ | | | | 50 | | | 120 | | | 150 | mV | | |
| I_Q | Quiescent Current | $I_O \leq 1\text{ A}$ | $T_j = 25^{\circ}\text{C}$ | | | | 8 | | | 8 | | | 8 | mA | | |
| | | | $0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ | | | | | | | | | | 8.5 | 8.5 | 8.5 | mA |
| ΔI_Q | Quiescent Current Change | $5\text{ mA} \leq I_O \leq 1\text{ A}$ | | | | | 0.5 | | | 0.5 | | | 0.5 | mA | | |
| | | $T_j = 25^{\circ}\text{C}, I_O \leq 1\text{ A}$ | | | | | 1.0 | | | 1.0 | | | 1.0 | mA | | |
| | | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | | | | (7.5 $\leq V_{\text{IN}} \leq 20$) | | | (14.8 $\leq V_{\text{IN}} \leq 27$) | | | (17.9 $\leq V_{\text{IN}} \leq 30$) | | | V |
| | | $I_O \leq 500\text{ mA}, 0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ | | | | | 1.0 | | | 1.0 | | | 1.0 | mA | | |
| V_N | Output Noise Voltage | $T_A = 25^{\circ}\text{C}, 10\text{ Hz} \leq f \leq 100\text{ kHz}$ | | 40 | | | 75 | | | 90 | | | μV | | | |
| | | $f = 120\text{ Hz}$ | $I_O \leq 1\text{ A}, T_j = 25^{\circ}\text{C}$ or $I_O \leq 500\text{ mA}, 0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$ | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | 62 | 80 | 55 | 72 | 54 | 70 | | | dB | | |
| | | | | | | 62 | | 55 | | 54 | | | dB | | | |
| $\frac{\Delta V_{\text{IN}}}{\Delta V_{\text{OUT}}}$ | Ripple Rejection | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | (8 $\leq V_{\text{IN}} \leq 18$) | | | (15 $\leq V_{\text{IN}} \leq 25$) | | | (18.5 $\leq V_{\text{IN}} \leq 28.5$) | | | V | | | |
| | | | | | | | | | | | | | | | | |
| R_O | Dropout Voltage | $T_j = 25^{\circ}\text{C}, I_{\text{OUT}} = 1\text{ A}$ | | 2.0 | | | 2.0 | | | 2.0 | | | V | | | |
| | Output Resistance | $f = 1\text{ kHz}$ | | 8 | | | 18 | | | 19 | | | $\text{m}\Omega$ | | | |
| | Short-Circuit Current | $T_j = 25^{\circ}\text{C}$ | | 2.1 | | | 1.5 | | | 1.2 | | | A | | | |
| | Peak Output Current | $T_j = 25^{\circ}\text{C}$ | | 2.4 | | | 2.4 | | | 2.4 | | | A | | | |
| | Average TC of V_{OUT} | $0^{\circ}\text{C} \leq T_j \leq +150^{\circ}\text{C}, I_O = 5\text{ mA}$ | | -0.6 | | | -1.5 | | | -1.8 | | | $\text{mV}/^{\circ}\text{C}$ | | | |
| V_{IN} | Input Voltage Required to Maintain Line Regulation | $T_j = 25^{\circ}\text{C}, I_O \leq 1\text{ A}$ | | 7.3 | | | 14.6 | | | 17.7 | | | V | | | |

Note 2: All characteristics are measured with a capacitor across the input of $0.22\ \mu\text{F}$ and a capacitor across the output of $0.1\ \mu\text{F}$. All characteristics except noise voltage and ripple rejection ratio are measured using pulse techniques ($t_W \leq 10\text{ ms}$, duty cycle $\leq 5\%$). Output voltage changes due to changes in internal temperature must be taken into account separately.

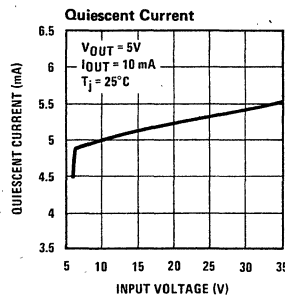
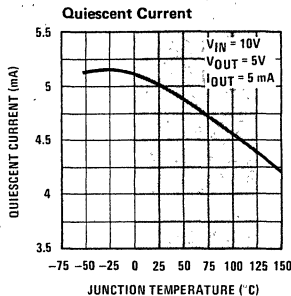
Typical Performance Characteristics



Note. Shaded area refers to LM340A/LM340



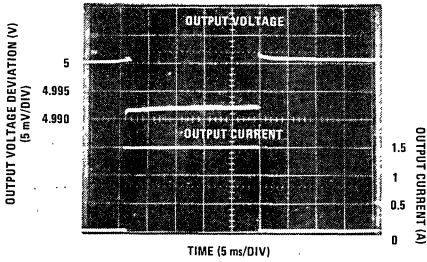
Note. Shaded area refers to LM340A/LM340



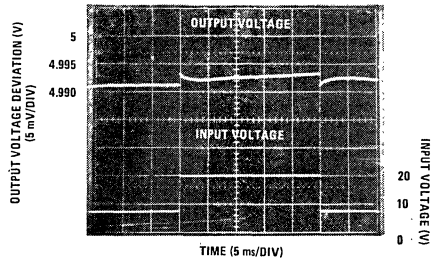
Note. Shaded area refers to LM340A/LM340

Typical Performance Characteristics (Continued)

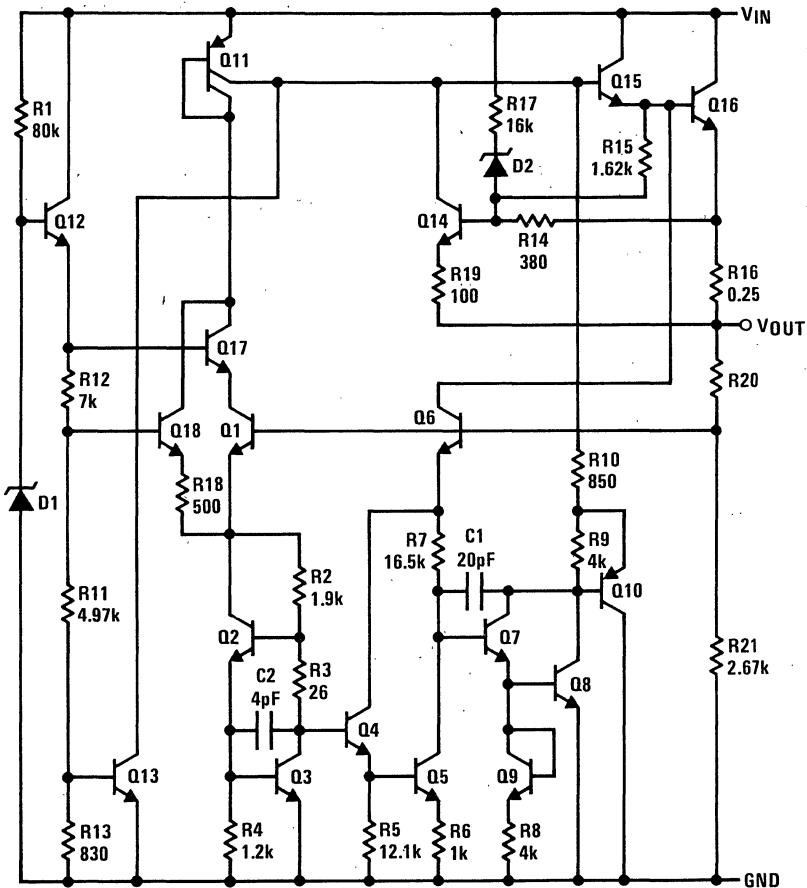
Load Regulation
140AK-5.0, $V_{IN} = 10V$, $T_A = 25^\circ C$



Line Regulation
140AK-5.0, $I_{OUT} = 1A$, $T_A = 25^\circ C$



Equivalent Schematic



Application Hints

The LM340 is designed with thermal protection, output short-circuit protection and output transistor safe area protection. However, as with *any* IC regulator, it becomes necessary to take precautions to assure that the regulator is not inadvertently damaged. The following describes possible misapplications and methods to prevent damage to the regulator.

Shorting the Regulator Input: When using large capacitors at the output of these regulators that have V_{OUT} greater than 6V, a protection diode connected input to output (Figure 1) may be required if the input is shorted to ground. Without the protection diode, an input short will cause the input to rapidly approach ground potential, while the output remains near the initial V_{OUT} because of the stored charge in the large output capacitor. The capacitor will then discharge through reverse biased emitter-base junction of the pass device, Q16, which breaks down at 6.5V and forward biases the base-collector junction. If the energy released by the capacitor into the emitter-base junction is large enough, the junction and the regulator will be destroyed. The fast diode in Figure 1 will shunt the capacitor's discharge current around the regulator.

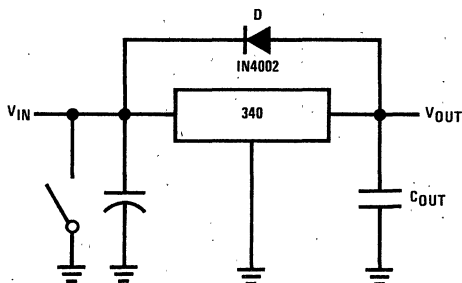


FIGURE 1. Input Short

Raising the Output Voltage above the Input Voltage: Since the output of the LM340 does not sink current, forcing the output high can cause damage to internal low current paths in a manner similar to that just described in the "Shorting the Regulator Input" section.

Regulator Floating Ground (Figure 2): When the ground pin alone becomes disconnected, the output approaches the unregulated input, causing possible damage to other circuits connected to V_{OUT} . If ground is reconnected with power "ON", damage may also occur to the regulator. This fault is most likely to occur when plugging in regulators or modules with on card regulators into powered up sockets. Power should be turned off first, thermal limit ceases operating, or ground should be connected first if power must be left on.

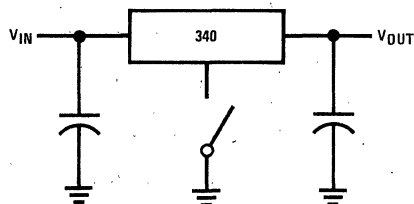


FIGURE 2. Regulator Floating Ground

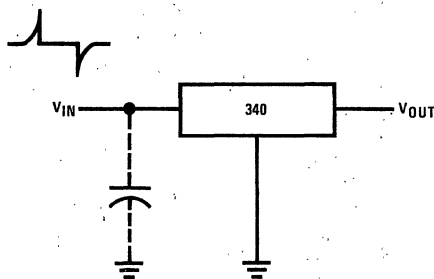
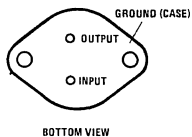


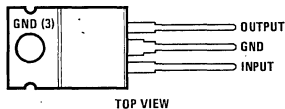
FIGURE 3. Transients

Connection Diagrams

TO-3 Metal Can Package (K and KC)



TO-220 Power Package (T)



Steel Package Order Numbers:

| | | | |
|-------------|------------|-------------|------------|
| LM140AK-5.0 | LM140K-5.0 | LM340AK-5.0 | LM340K-5.0 |
| LM140AK-12 | LM140K-12 | LM340AK-12 | LM340K-12 |
| LM140AK-15 | LM140K-15 | LM340AK-15 | LM340K-15 |

See NS Package K02A

Plastic Package Order Numbers:

| | |
|-------------|------------|
| LM340AT-5.0 | LM340T-5.0 |
| LM340AT-12 | LM340T-12 |
| LM340AT-15 | LM340T-15 |

See NS Package T03B

Aluminum Package Order Numbers:

LM340KC-5.0
LM340KC-12
LM340KC-15
See NS Package KC02A



LM140L/LM340L Series 3-Terminal Positive Regulators

Voltage Regulators

General Description

The LM140L series of three terminal positive regulators is available with several fixed output voltages making them useful in a wide range of applications. The LM140LA is an improved version of the LM78LXX series with a tighter output voltage tolerance (specified over the full military temperature range), higher ripple rejection, better regulation and lower quiescent current. The LM140LA regulators have $\pm 2\%$ V_{OUT} specification, 0.04%/V line regulation, and 0.01%/mA load regulation. When used as a zener diode/resistor combination replacement, the LM140LA usually results in an effective output impedance improvement of two orders of magnitude, and lower quiescent current. These regulators can provide local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow the LM140LA to be used in logic systems, instrumentation, Hi-Fi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators, these devices can be used with external components to obtain adjustable voltages and currents.

The LM140LA/LM340LA are available in the low profile metal three lead TO-39 (H) and the LM340LA is also available in the plastic TO-92 (Z). With adequate heat sinking the regulator can deliver 100 mA output current. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes

too high for the heat sinking provided, the thermal shutdown circuit takes over, preventing the IC from overheating.

For applications requiring other voltages, see LM117 data sheet.

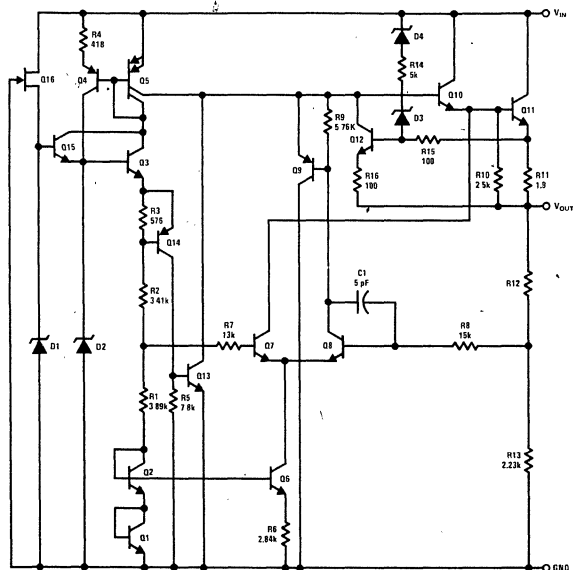
Features

- Line regulation of 0.04%/V
- Load regulation of 0.01%/mA
- Output voltage tolerances of $\pm 2\%$ at $T_J = 25^\circ\text{C}$ and $\pm 4\%$ over the temperature range (LM140LA) $\pm 3\%$ over the temperature range (LM340LA)
- Output current of 100 mA
- Internal thermal overload protection
- Output transistor safe area protection
- Internal short circuit current limit
- Available in metal TO-39 low profile package (LM140LA/LM340LA) and plastic TO-92 (LM340LA)

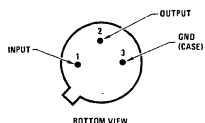
Output Voltage Options

| | |
|-------------|-----|
| LM140LA-5.0 | 5V |
| LM140LA-12 | 12V |
| LM140LA-15 | 15V |
| LM340LA-5.0 | 5V |
| LM340LA-12 | 12V |
| LM340LA-15 | 15V |

Equivalent Circuit

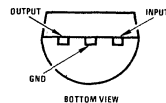


Connection Diagrams



Order Number:

- | | |
|--------------|--------------|
| LM140LAH-5.0 | LM340LAH-5.0 |
| LM140LAH-12 | LM340LAH-12 |
| LM140LAH-15 | LM340LAH-15 |
- See NS Package H03A



Order Number:

- | |
|--------------|
| LM340LAZ-5.0 |
| LM340LAZ-12 |
| LM340LAZ-15 |
- See NS Package Z03A

Absolute Maximum Ratings

| | | | |
|-------------------------------------|--------------------|--|-----------------|
| Input Voltage 5.0V, 12V and 15V | 35V | Maximum Junction Temperature | +150°C |
| Internal Power Dissipation (Note 1) | Internally Limited | Storage Temperature Range | |
| Operating Temperature Range | | Metal Can (H package) | -65°C to +150°C |
| LM140LA | -55°C to +125°C | Molded TO-92 | -55°C to +150°C |
| LM340LA | 0°C to +70°C | Lead Temperature (Soldering, 10 seconds) | +300°C |

Electrical Characteristics (Note 2)

Test conditions unless otherwise specified

$T_A = -55^\circ\text{C}$ to $+125^\circ\text{C}$ (LM140LA)

$T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$ (LM340LA)

$I_O = 40\text{ mA}$

$C_{IN} = 0.33\mu\text{F}$, $C_O = 0.01\mu\text{F}$

| OUTPUT VOLTAGE OPTION | | | | 5.0V | | | 12V | | | 15V | | | UNITS | | |
|--|---|--------|---|---|-----|------------|------------|------|-------------|-------------|------|---------------|---------------|----|----------------|
| INPUT VOLTAGE (unless otherwise noted) | | | | 10V | | | 19V | | | 23V | | | | | |
| PARAMETER | | ρ | CONDITIONS | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | V | | |
| V_O | Output Voltage | | $T_J = 25^\circ\text{C}$ | 4.9 | 5 | 5.1 | 11.75 | 12 | 12.25 | 14.7 | 15 | 15.3 | | V | |
| | Output Voltage Over Temp. (Note 4) | | LM140LA | $I_O = 1\text{-}100\text{ mA}$ or $I_O = 1\text{-}40\text{ mA}$ and $V_{IN} = ()\text{ V}$ | 4.8 | | 5.2 | 11.5 | | 12.5 | 14.4 | | 15.6 | | |
| | | | LM340LA | $I_O = 1\text{-}100\text{ mA}$ or $I_O = 1\text{-}40\text{ mA}$ and $V_{IN} = ()\text{ V}$ | | | (7.2 - 20) | | | (14.5 - 27) | | | (17.6 - 30) | | |
| | | | | 4.85 | | 5.15 | 11.65 | | 12.35 | 14.55 | | 15.45 | | | |
| ΔV_O | Line Regulation | | $T_J = 25^\circ\text{C}$ | $I_O = 40\text{ mA}$ | 18 | 30 | | | 30 | 65 | | | 37 | 70 | mV |
| | | | | $V_{IN} = ()\text{ V}$ | | | (7 - 25) | | | (14.2 - 30) | | | (17.3 - 30) | | |
| | | | | $I_O = 100\text{ mA}$ | 18 | 30 | | | 30 | 65 | | | 37 | 70 | |
| | | | | | | | (7.5 - 25) | | | (14.5 - 30) | | | (17.5 - 30) | | |
| | Load Regulation | | $T_J = 25^\circ\text{C}$ | $I_O = 1\text{-}40\text{ mA}$ $I_O = 1\text{-}100\text{ mA}$ | 5 | 20 | | | 10 | 40 | | | 12 | 50 | mV 1000 hrs |
| | | | | 20 | 40 | | | 30 | 80 | | | 35 | 100 | | |
| Long Term Stability | | | | | 12 | | | | 24 | | | 30 | | | |
| I_O | Quiescent Current | | $T_J = 25^\circ\text{C}$ | 3 | 4.5 | | | 3 | 4.5 | | | 3.1 | 4.5 | mA | |
| | | | $T_J = 125^\circ\text{C}$ | | | 4.2 | | | 4.2 | | | 4.2 | | | |
| ΔI_O | Quiescent Current Change | | $T_J = 25^\circ\text{C}$ | $\Delta\text{Load } I_O = 1\text{-}40\text{ mA}$ | | | 0.1 | | | 0.1 | | | 0.1 | mA | |
| | | | | ΔLine | | | 0.5 | | | 0.5 | | 0.5 | | | |
| | | | | $V_{IN} = ()\text{ V}$ | | | (7.5 - 25) | | | (14.3 - 30) | | | (17.5 - 30) | | |
| V_N | Output Noise Voltage | | $T_J = 25^\circ\text{C}$ (Note 3) $f = 10\text{ Hz} - 10\text{ kHz}$ | | 40 | | | | 80 | | | 90 | μV | | |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ | Ripple Rejection | | $f = 120\text{ Hz}$, $V_{IN} = ()\text{ V}$ | 55 | 62 | | | 47 | 54 | | | 45 | 52 | dB | |
| | | | | | | (7.5 - 18) | | | (14.5 - 25) | | | (17.5 - 28.5) | | | |
| | Input Voltage Required to Maintain Line Regulation | | $T_J = 25^\circ\text{C}$, $I_O = 40\text{ mA}$ | 7 | | | | | 14.2 | | | 17.3 | V | | |

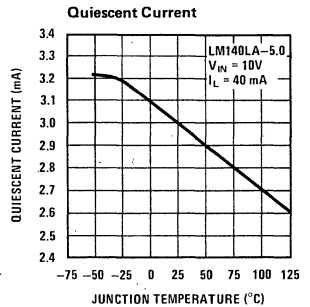
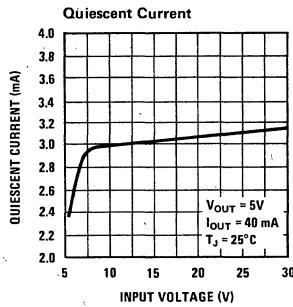
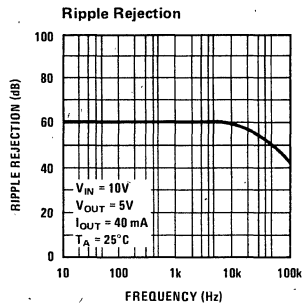
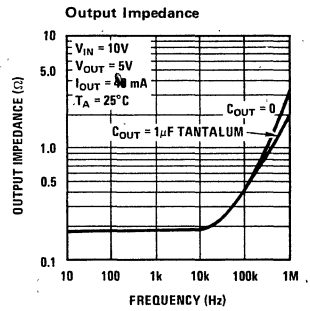
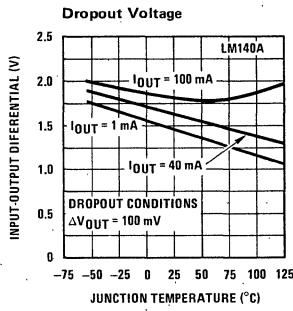
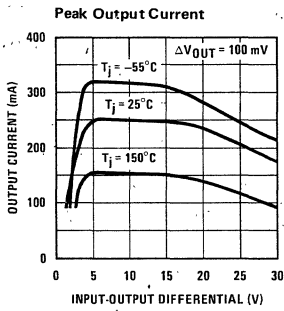
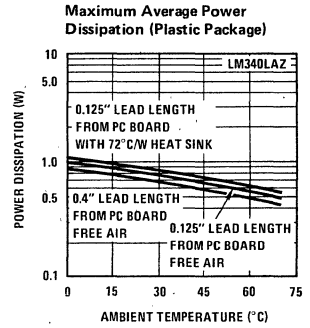
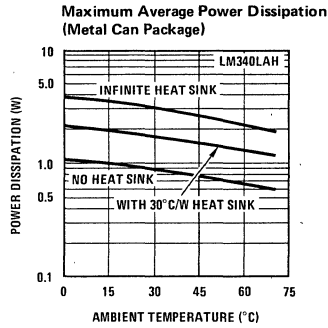
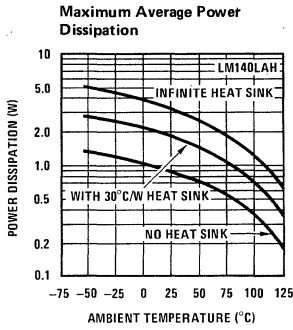
Note 1: Thermal resistance of the Metal Can Package (H) without a heat sink is 40°C/W junction to case and 140°C/W junction to ambient. Thermal resistance of the TO-92 package is 180°C/W junction to ambient with 0.4 inch leads from a PC board and 160°C/W junction to ambient with 0.125 inch lead length to a PC board.

Note 2: The maximum steady state usable output current and input voltage are very dependent on the heat sinking and/or lead length of the package. The data above represent pulse test conditions with junction temperatures as indicated at the initiation of tests.

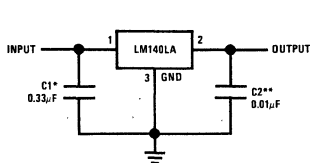
Note 3: It is recommended that a minimum load capacitor of $0.01\mu\text{F}$ be used to limit the high frequency noise bandwidth.

Note 4: The temperature coefficient of V_{OUT} is typically within $0.01\%V_O/^\circ\text{C}$.

Typical Performance Characteristics

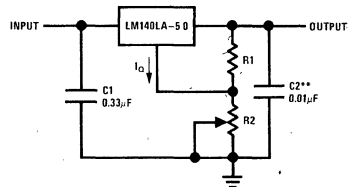


Typical Applications



*Required if the regulator is located far from the power supply filter.
 **See note 3 in the electrical characteristics table.

Fixed Output Regulator



$V_{OUT} = 5V + (5V/R1 + I_Q) R2$
 $5V/R1 > 3 I_Q$ load regulation (L_L) = $[(R1 + R2)/R1] (I_L \text{ of LM140LA-5.0})$

Adjustable Output Regulator

LM145/LM245/LM345 Negative Three Amp Regulator
General Description

The LM145 is a three-terminal negative regulator with a fixed output voltage of $-5V$ or $-5.2V$, and up to 3A load current capability. This device needs only one external component—a compensation capacitor at the output, making it easy to apply. Worst case guarantees on output voltage deviation due to any combination of line, load or temperature variation assure satisfactory system operation.

Exceptional effort has been made to make the LM145 immune to overload conditions. The regulator has current limiting which is independent of temperature, combined with thermal overload protection. Internal current limiting protects against momentary faults while thermal shutdown prevents junction temperatures from exceeding safe limits during prolonged overloads.

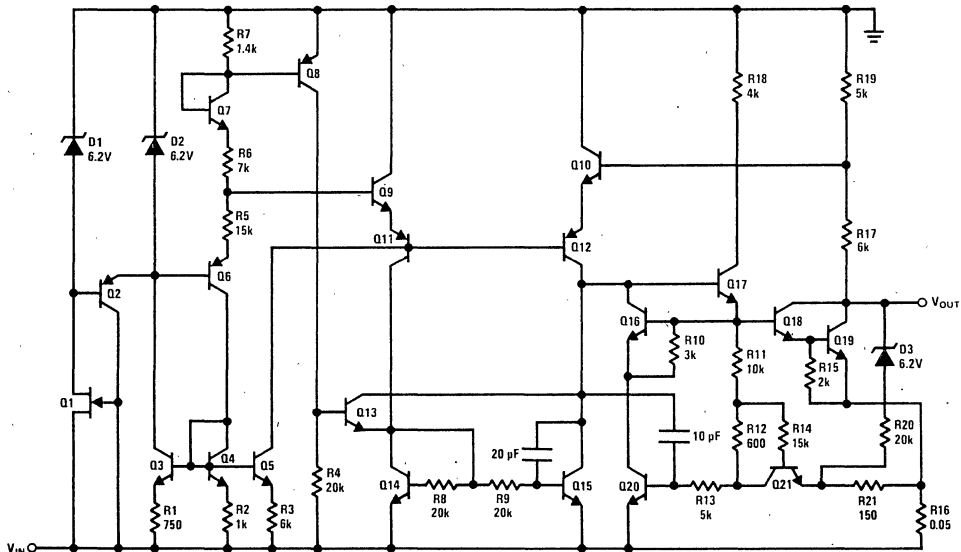
Although primarily intended for fixed output voltage applications, the LM145 may be programmed for higher

output voltages with a simple resistive divider. The low quiescent drain current of the device allows this technique to be used with good regulation.

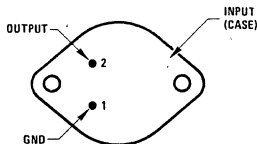
The LM145 comes in a hermetic TO-3 package rated at 25W. Two reduced temperature range parts, LM245 and LM345, are also available.

Features

- Output voltage accurate to better than $\pm 2\%$
- Current limit constant with temperature
- Internal thermal shutdown protection
- Operates with input-output voltage differential of 2.8V at full rated load over full temperature range
- Regulation guaranteed with 25W power dissipation
- 3A output current guaranteed
- Only one external component needed
- 100% electrical burn-in

Schematic Diagram

Connection Diagram

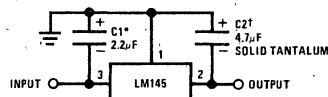
Metal Can Package



BOTTOM VIEW

Order Number LM145K-5.0, LM245K-5.0
LM345K-5.0, LM145K-5.2, LM245K-5.2,
or LM345K-5.2

See NS Package K02A

Typical Applications


† Required for stability. For value given, capacitor must be solid tantalum. 50µF aluminum electrolytic may be substituted. Values given may be increased without limit.

* Required if regulator is separated from filter capacitor. For value given, capacitor must be solid tantalum. 50µF aluminum electrolytic may be substituted.

Fixed Regulator

Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage | 20V |
| Input-Output Differential | 20V |
| Power Dissipation | Internally Limited |
| Operating Junction Temperature Range | |
| LM145 | -55°C to +150°C |
| LM245 | -25°C to +150°C |
| LM345 | 0°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (-5V & -5.2V) (Note 1)

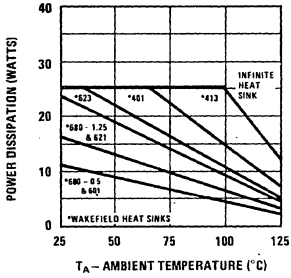
| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|--|---|-------------|------|-------|-------|------|-------|--------------------|
| | | LM145/LM245 | | | LM345 | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Output Voltage | $T_j = 25^\circ\text{C}$, $I_{\text{OUT}} = 5\text{ mA}$, $V_{\text{IN}} = -7.5$ | -5.1 | -5.0 | -4.9 | -5.2 | -5.0 | -4.8 | V |
| 5.0V | | -5.3 | -5.2 | -5.1 | -5.4 | -5.2 | -5.0 | V |
| 5.2V | | | | | | | | V |
| Line Regulation (Note 2) | $T_j = 25^\circ\text{C}$ $-20\text{V} \leq V_{\text{IN}} \leq -7.5\text{V}$ | | 5 | 15 | | 5 | 25 | mV |
| Load Regulation (Note 2) | $T_j = 25^\circ\text{C}$, $V_{\text{IN}} = -7.5\text{V}$ $5\text{ mA} \leq I_{\text{OUT}} \leq 3\text{ A}$ | | 30 | 75 | | 30 | 100 | mV |
| Output Voltage | $-20\text{V} \leq V_{\text{IN}} \leq -7.8\text{V}$ $5\text{ mA} \leq I_{\text{OUT}} \leq 3\text{ A}$ $P \leq 25\text{W}$ $T_{\text{MIN}} \leq T_j \leq T_{\text{MAX}}$ | -5.20 | | -4.80 | -5.25 | | -4.75 | V |
| 5.0V | | -5.40 | | -5.00 | -5.45 | | -4.95 | V |
| 5.2V | | | | | | | | V |
| Quiescent Current | $-20\text{V} \leq V_{\text{IN}} \leq -7.5\text{V}$ $5\text{ mA} \leq I_{\text{OUT}} \leq 3\text{ A}$ | | 1.0 | 3.0 | | 1.0 | 3.0 | mA |
| Short Circuit Current | $V_{\text{IN}} = -7.5\text{V}$, $T_j = +25^\circ\text{C}$ $V_{\text{IN}} = -20\text{V}$, $T_j = +25^\circ\text{C}$ | | 4 | 5.0 | | 4 | 5.0 | A |
| | | | | 2 | 3.5 | | 2 | 3.5 |
| Output Noise Voltage | $T_A = 25^\circ\text{C}$, $C_L = 4.7\mu\text{F}$ $10\text{ Hz} \leq f \leq 100\text{ kHz}$ | | 150 | | | 150 | | μV |
| Long Term Stability | | | 5 | 50 | | 5 | 50 | mV |
| Thermal Resistance Junction to Case | | | 2 | | | 2 | | $^\circ\text{C/W}$ |

Note 1: Unless otherwise specified, these specifications apply: $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM145; $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM245 and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM345. $V_{\text{IN}} = -7.5\text{V}$ and $I_{\text{OUT}} = 5\text{ mA}$. Although power dissipation is internally limited, electrical specifications apply only for power levels up to 25W. For calculations of junction temperature rise due to power dissipation, use a thermal resistance of 35°C/W for the TO-3 with no heat sink. With a heat sink, use 2°C/W for junction to case thermal resistance.

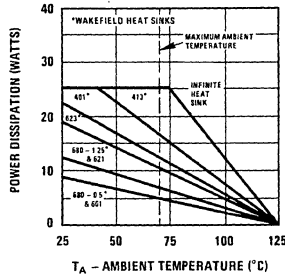
Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. To ensure constant junction temperature, pulse testing with a low duty cycle is used.

Typical Performance Characteristics

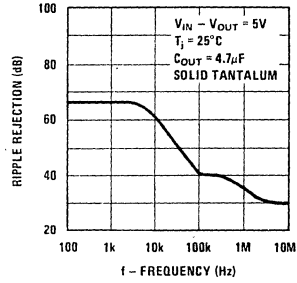
Maximum Average Power Dissipation for LM145, LM245



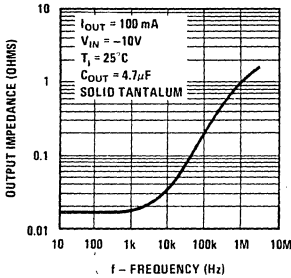
Maximum Average Power Dissipation for LM345



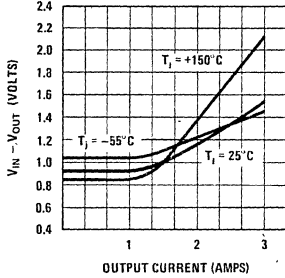
Ripple Rejection



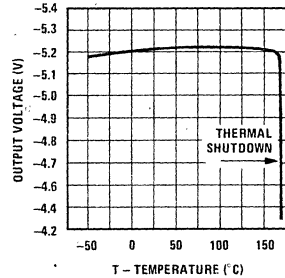
Output Impedance



Minimum Input-Output Voltage Differential

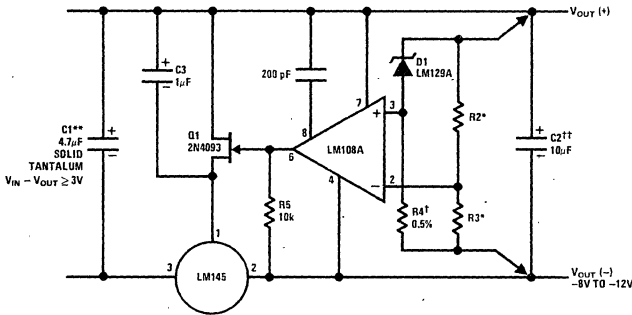


Output Voltage vs Temperature



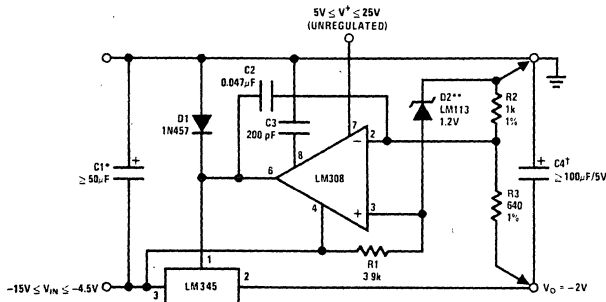
1

Typical Applications (Continued)



High Stability Regulator

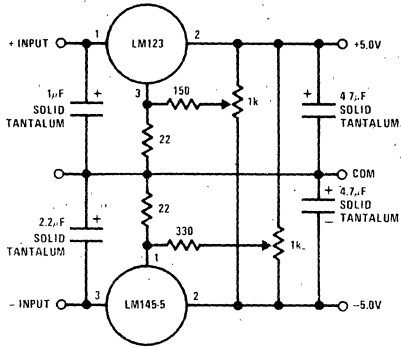
- *Select resistors to set output voltage. 1 ppm/°C tracking suggested.
- **C1 is not needed if power supply filter capacitor is within 3" of regulator.
- †Determines zener current. May be adjusted to minimize temperature drift.
- ††Solid tantalum.
- Load and line regulation < 0.01%
- Temperature drift < 0.001%/°C



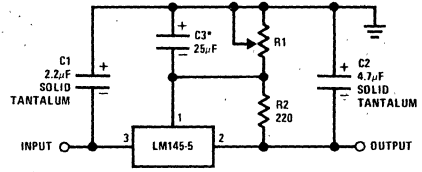
-2V ECL Termination Regulator

- **C1 is not needed if power supply filter capacitor is within 3" of regulator.
- †Keep C4 within 2" of LM345. There is no upper limit on C4 and unlimited capacitance can be added at extended distances from the regulator.
- **D2 sets initial output voltage accuracy. The LM113 is available in .5, .2, and .1% tolerance.

Typical Applications (Continued)



Dual 3 Amp Trimmed Supply



*Optional. Improves transient response and ripple rejection.

$$V_{OUT} = -5V \left(\frac{R1 + R2}{R2} \right)$$

Variable Output (-5.0V to -15V)

LM150/LM250/LM350 3 Amp Adjustable Power Regulators

General Description

The LM150/LM250/LM350 are adjustable 3-terminal positive voltage regulators capable of supplying in excess of 3A over a 1.2V to 33V output range. They are exceptionally easy to use and require only 2 external resistors to set the output voltage. Further, both line and load regulation are comparable to discrete designs. Also, the LM150 is packaged in standard transistor packages which are easily mounted and handled.

In addition to higher performance than fixed regulators, the LM150 series offers full overload protection available only in IC's. Included on the chip are current limit, thermal overload protection and safe area protection. All overload protection circuitry remains fully functional even if the adjustment terminal is accidentally disconnected.

Features

- Adjustable output down to 1.2V
- Guaranteed 3A output current
- Line regulation typically 0.005%/V
- Load regulation typically 0.1%
- Guaranteed thermal regulation
- Current limit constant with temperature
- 100% electrical burn-in in thermal limit
- Eliminates the need to stock many voltages
- Standard 3-lead transistor package
- 86 dB ripple rejection

Normally, no capacitors are needed unless the device is situated far from the input filter capacitors in which case an input bypass is needed. An optional output capacitor can be added to improve transient response. The adjustment terminal can be bypassed to achieve very high ripple rejections ratios which are difficult to achieve with standard 3-terminal regulators.

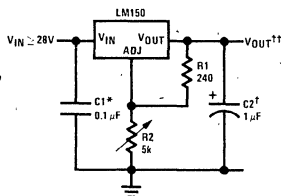
Besides replacing fixed regulators or discrete designs, the LM150 is useful in a wide variety of other applications. Since the regulator is "floating" and sees only the input-to-output differential voltage, supplies of several hundred volts can be regulated as long as the maximum input to output differential is not exceeded.

Also, it makes an especially simple adjustable switching regulator, a programmable output regulator, or by connecting a fixed resistor between the adjustment and output, the LM150 can be used as a precision current regulator. Supplies with electronic shutdown can be achieved by clamping the adjustment terminal to ground which programs the output to 1.2V where most loads draw little current.

The LM150/LM250/LM350 are packaged in standard steel TO-3 transistor packages. The LM150 is rated for operation from -55°C to $+150^{\circ}\text{C}$, the LM250 from -25°C to $+150^{\circ}\text{C}$ and the LM350 from 0°C to $+125^{\circ}\text{C}$.

Typical Applications

1.2V–25V Adjustable Regulator



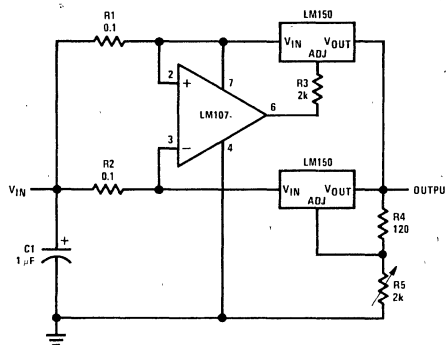
†Optional—improves transient response

*Needed if device is far from filter capacitors

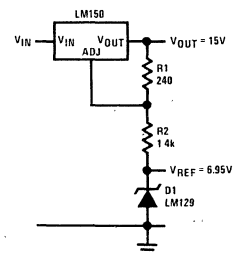
$$\dagger\dagger V_{\text{OUT}} = 1.25V \left(1 + \frac{R2}{R1} \right)$$

Note. Usually $R1 = 240\Omega$ for LM150 and LM250 and $R1 = 120\Omega$ for LM350.

6A Regulator



Regulator and Voltage Reference



Absolute Maximum Ratings

| | |
|--|--------------------|
| Power Dissipation | Internally limited |
| Input—Output Voltage Differential | 35V |
| LM150 | -55°C to +150°C |
| LM250 | -25°C to +150°C |
| LM350 | 0°C to +125°C |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Preconditioning

Burn-In in Thermal Limit All Devices 100%

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM150/LM250 | | | LM350 | | | UNITS |
|--------------------------------------|--|-------------|-------|------|-------|-------|------|--------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$, $3\text{V} \leq V_{IN} - V_{OUT} \leq 35\text{V}$, (Note 2) | | 0.005 | 0.01 | | 0.005 | 0.03 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $10\text{mA} \leq I_{OUT} \leq 3\text{A}$ $V_{OUT} \leq 5\text{V}$, (Note 2) $V_{OUT} \geq 5\text{V}$, (Note 2) | | 5 | 15 | | 5 | 25 | mV |
| | | | 0.1 | 0.3 | | 0.1 | 0.5 | % |
| | | | | | | | | |
| Thermal Regulation | Pulse = 20 ms | | 0.002 | 0.01 | | 0.002 | 0.03 | %/W |
| Adjustment Pin Current | | | 50 | 100 | | 50 | 100 | μA |
| Adjustment Pin Current Change | $10\text{mA} \leq I_L \leq 3\text{A}$ $3\text{V} \leq (V_{IN} - V_{OUT}) \leq 35\text{V}$ | | 0.2 | 5 | | 0.2 | 5 | μA |
| Reference Voltage | $3 \leq (V_{IN} - V_{OUT}) \leq 35\text{V}$, (Note 3) $10\text{mA} \leq I_{OUT} \leq 3\text{A}$, $P \leq 30\text{W}$ | 1.20 | 1.25 | 1.30 | 1.20 | 1.25 | 1.30 | V |
| Line Regulation | $3\text{V} \leq V_{IN} - V_{OUT} \leq 35\text{V}$, (Note 2) | | 0.02 | 0.05 | | 0.02 | 0.07 | %/V |
| Load Regulation | $10\text{mA} \leq I_{OUT} \leq 3\text{A}$, (Note 2) $V_{OUT} \leq 5\text{V}$ $V_{OUT} \geq 5\text{V}$ | | 20 | 50 | | 20 | 70 | mV |
| | | | 0.3 | 1 | | 0.3 | 1.5 | % |
| | | | | | | | | |
| Temperature Stability | $T_{MIN} \leq T_j \leq T_{MAX}$ | | 1 | | | 1 | | % |
| Minimum Load Current | $V_{IN} - V_{OUT} = 35\text{V}$ | | 3.5 | 5 | | 3.5 | 10 | mA |
| Current Limit | $V_{IN} - V_{OUT} \leq 10\text{V}$ | 3.0 | 4.5 | | 3.0 | 4.5 | | A |
| | $V_{IN} - V_{OUT} = 30\text{V}$, $T_j = +25^\circ\text{C}$ | 0.3 | 1 | | 0.25 | 1 | | A |
| RMS Output Noise, % of V_{OUT} | $T_A = 25^\circ\text{C}$, $10\text{Hz} \leq f \leq 10\text{kHz}$ | | 0.003 | | | 0.003 | | % |
| Ripple Rejection Ratio | $V_{OUT} = 10\text{V}$, $f = 120\text{Hz}$ | | 65 | | | 65 | | dB |
| | $C_{ADJ} = 10\mu\text{F}$ | 66 | 86 | | 66 | 86 | | dB |
| Long Term Stability | $T_A = 125^\circ\text{C}$ | | 0.3 | 1 | | 0.3 | 1 | % |
| Thermal Resistance, Junction to Case | K Package | | | 1.5 | | | 1.5 | $^\circ\text{C/W}$ |

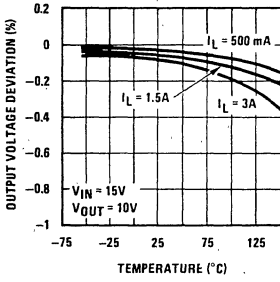
Note 1: Unless otherwise specified, these specifications apply $-55^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM150, $-25^\circ\text{C} \leq T_j \leq +150^\circ\text{C}$ for the LM250 and $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ for the LM350, $V_{IN} - V_{OUT} = 5\text{V}$ and $I_{OUT} = 1.5\text{A}$. Although power dissipation is internally limited, these specifications are applicable for power dissipations up to 30W.

Note 2: Regulation is measured at constant junction temperature. Changes in output voltage due to heating effects must be taken into account separately. Pulse testing with low duty cycle is used.

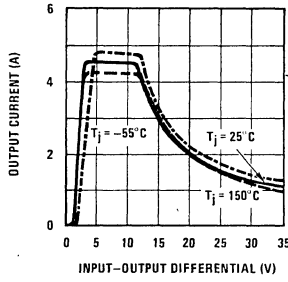
Note 3: Selected devices with tightened tolerance reference voltage available.

Typical Performance Characteristics

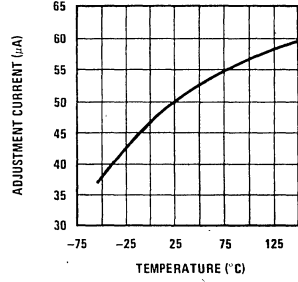
Load Regulation



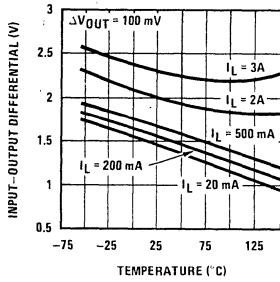
Current Limit



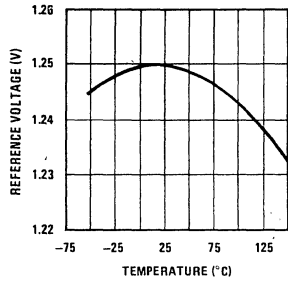
Adjustment Current



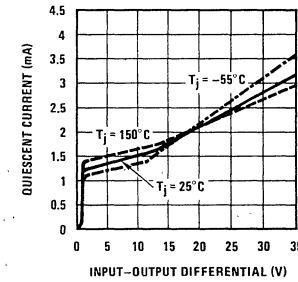
Dropout Voltage



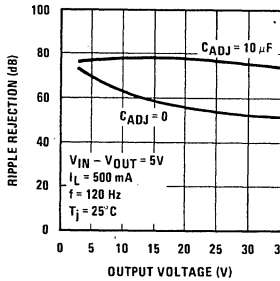
Temperature Stability



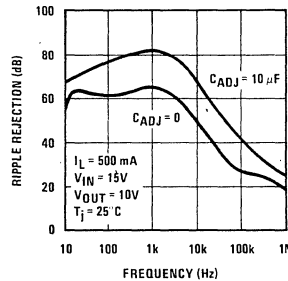
Minimum Operating Current



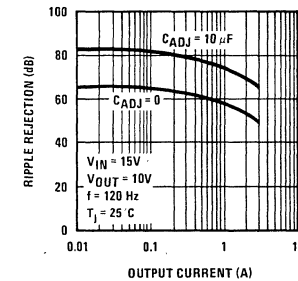
Ripple Rejection



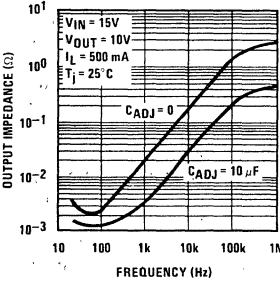
Ripple Rejection



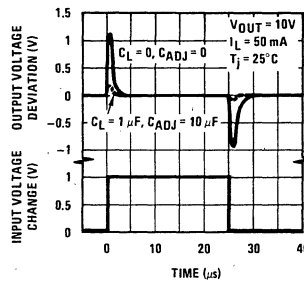
Ripple Rejection



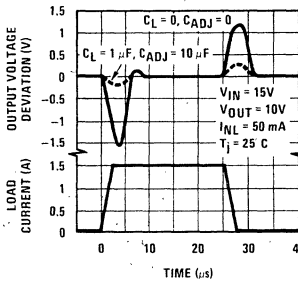
Output Impedance



Line Transient Response



Load Transient Response



Application Hints

In operation, the LM150 develops a nominal 1.25V reference voltage, V_{REF} , between the output and adjustment terminal. The reference voltage is impressed across program resistor $R1$ and, since the voltage is constant, a constant current I_1 then flows through the output set resistor $R2$, giving an output voltage of

$$V_{OUT} = V_{REF} \left(1 + \frac{R2}{R1} \right) + I_{ADJ} R2.$$

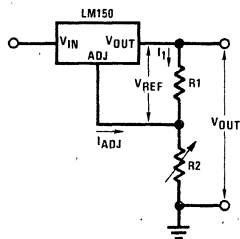


FIGURE 1

Since the 50 μ A current from the adjustment terminal represents an error term, the LM150 was designed to minimize I_{ADJ} and make it very constant with line and load changes. To do this, all quiescent operating current is returned to the output establishing a minimum load current requirement. If there is insufficient load on the output, the output will rise.

External Capacitors

An input bypass capacitor is recommended. A 0.1 μ F disc or 1 μ F solid tantalum on the input is suitable input bypassing for almost all applications. The device is more sensitive to the absence of input bypassing when adjustment or output capacitors are used but the above values will eliminate the possibility of problems.

The adjustment terminal can be bypassed to ground on the LM150 to improve ripple rejection. This bypass capacitor prevents ripple from being amplified as the output voltage is increased. With a 10 μ F bypass capacitor 86 dB ripple rejection is obtainable at any output level. Increases over 10 μ F do not appreciably improve the ripple rejection at frequencies above 120 Hz. If the bypass capacitor is used, it is sometimes necessary to include protection diodes to prevent the capacitor from discharging through internal low current paths and damaging the device.

In general, the best type of capacitors to use are solid tantalum. Solid tantalum capacitors have low impedance even at high frequencies. Depending upon capacitor construction, it takes about 25 μ F in aluminum electrolytic to equal 1 μ F solid tantalum at high frequencies. Ceramic capacitors are also good at high frequencies, but some types have a large decrease in capacitance at frequencies around 0.5 MHz. For this reason, 0.01 μ F disc may seem to work better than a 0.1 μ F disc as a bypass.

Although the LM150 is stable with no output capacitors, like any feedback circuit, certain values of external capacitance can cause excessive ringing. This occurs with values between 500 pF and 5000 pF. A 1 μ F solid tantalum (or 25 μ F aluminum electrolytic) on the output swamps this effect and insures stability.

Load Regulation

The LM150 is capable of providing extremely good load regulation but a few precautions are needed to obtain maximum performance. The current set resistor connected between the adjustment terminal and the output terminal (usually 240 Ω) should be tied directly to the output of the regulator rather than near the load. This eliminates line drops from appearing effectively in series with the reference and degrading regulation. For example, a 15V regulator with 0.05 Ω resistance between the regulator and load will have a load regulation due to line resistance of 0.05 Ω \times I_L . If the set resistor is connected near the load the effective line resistance will be 0.05 Ω (1 + R2/R1) or in this case, 11.5 times worse.

Figure 2 shows the effect of resistance between the regulator and 240 Ω set resistor.

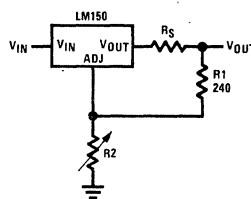


FIGURE 2. Regulator with Line Resistance in Output Lead

With the TO-3 package, it is easy to minimize the resistance from the case to the set resistor, by using 2 separate leads to the case. The ground of R2 can be returned near the ground of the load to provide remote ground sensing and improve load regulation.

Protection Diodes

When external capacitors are used with any IC regulator it is sometimes necessary to add protection diodes to prevent the capacitors from discharging through low current points into the regulator. Most 10 μ F capacitors have low enough internal series resistance to deliver 20A spikes when shorted. Although the surge is short, there is enough energy to damage parts of the IC.

When an output capacitor is connected to a regulator and the input is shorted, the output capacitor will discharge into the output of the regulator. The discharge current depends on the value of the capacitor, the output voltage of the regulator, and the rate of decrease of V_{IN} . In the LM150, this discharge path is through a large junction that is able to sustain 25A surge with no problem. This is not true of other types of positive

Application Hints (Continued)

regulators. For output capacitors of 25 μF or less, there is no need to use diodes.

The bypass capacitor on the adjustment terminal can discharge through a low current junction. Discharge occurs when *either* the input or output is shorted. Internal to the LM150 is a 50 Ω resistor which limits the peak discharge current. No protection is needed for output voltages of 25V or less and 10 μF capacitance. *Figure 3* shows an LM150 with protection diodes included for use with outputs greater than 25V and high values of output capacitance.

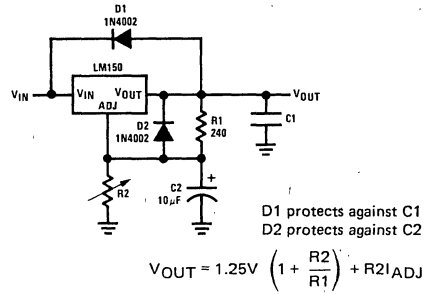
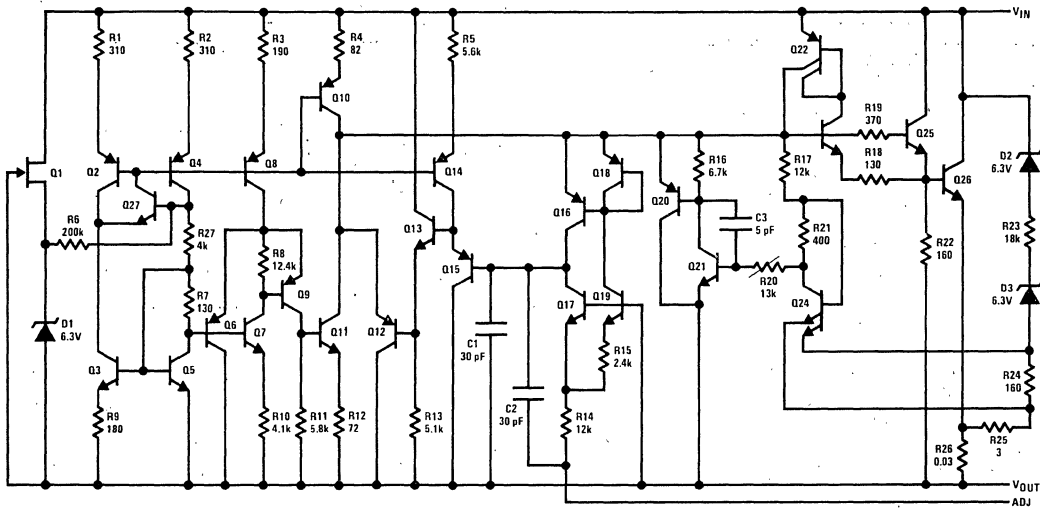


FIGURE 3. Regulator with Protection Diodes

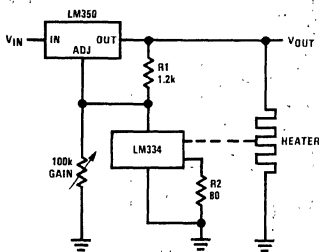
Schematic Diagram



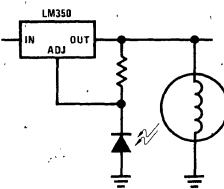
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Typical Applications (Continued)

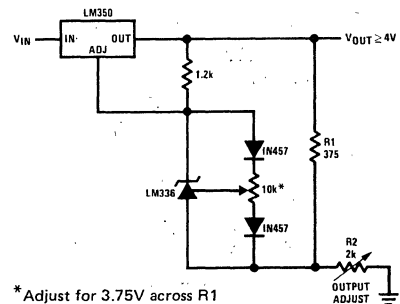
Temperature Controller



Light Controller



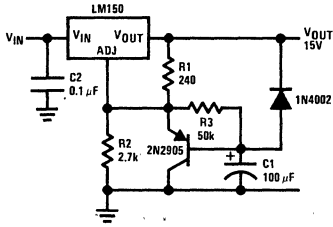
Precision Power Regulator with Low Temperature Coefficient



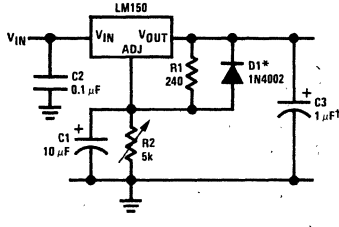
* Adjust for 3.75V across R1

Typical Applications (Continued)

Slow Turn-ON 15V Regulator

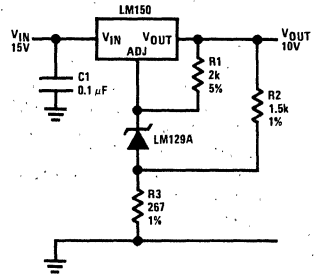


Adjustable Regulator with Improved Ripple Rejection

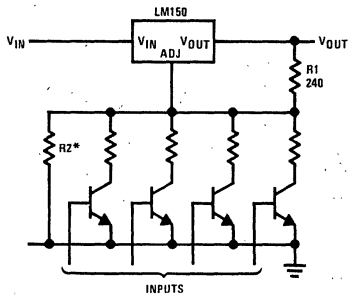


†Solid tantalum
* Discharges C1 if output is shorted to ground

High Stability 10V Regulator

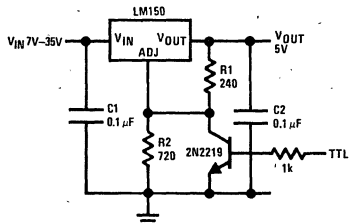


Digitally Selected Outputs



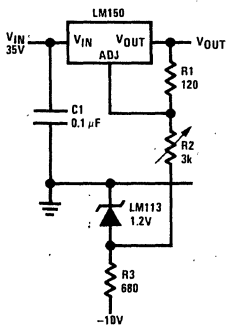
*Sets maximum V_{OUT}

5V Logic Regulator with Electronic Shutdown*

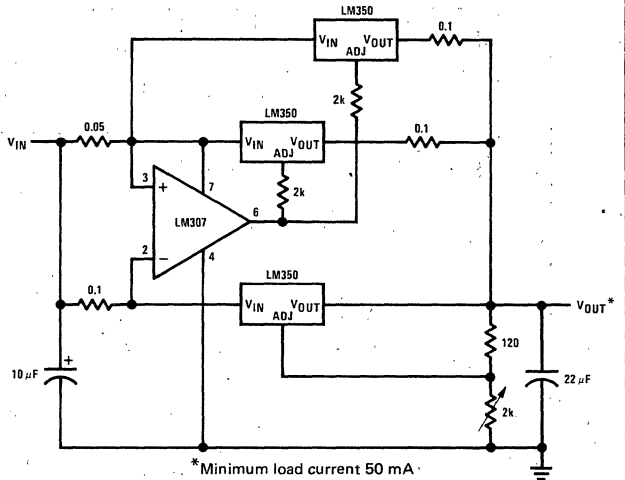


*Min output ≈ 1.2V

0 to 30V Regulator

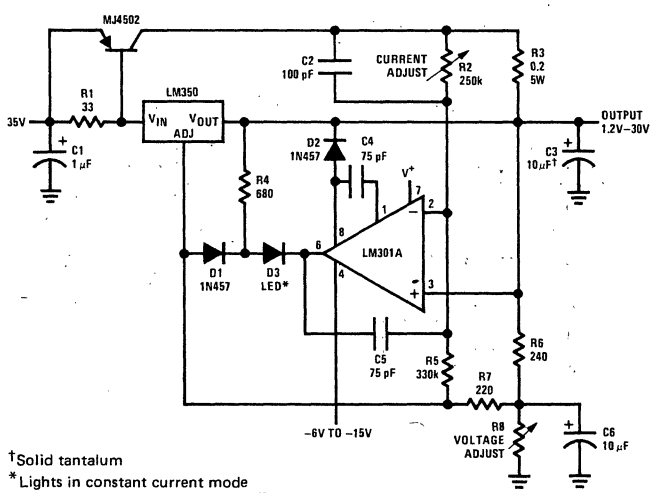


10A Regulator



*Minimum load current 50 mA

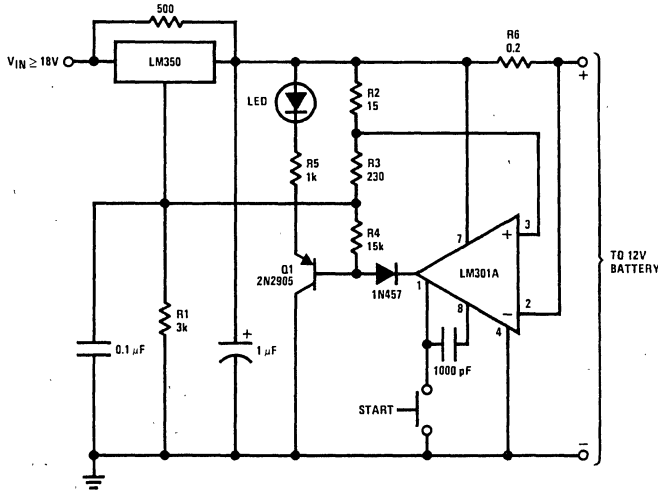
5A Constant Voltage/Constant Current Regulator



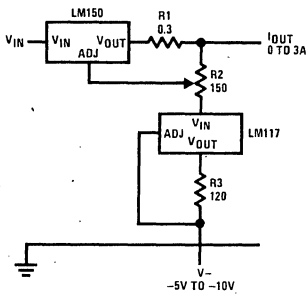
†Solid tantalum
*Lights in constant current mode

Typical Applications (Continued)

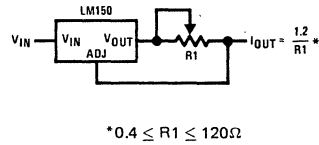
12V Battery Charger



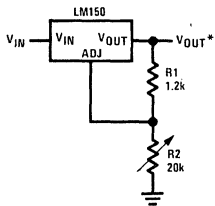
Adjustable Current Regulator



Precision Current Limiter

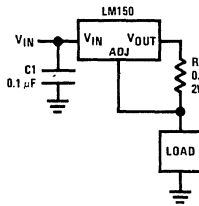


1.2V - 20V Regulator with Minimum Program Current

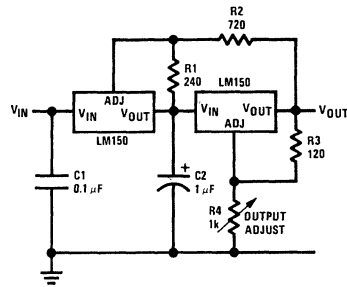


*Minimum load current ≈ 4 mA

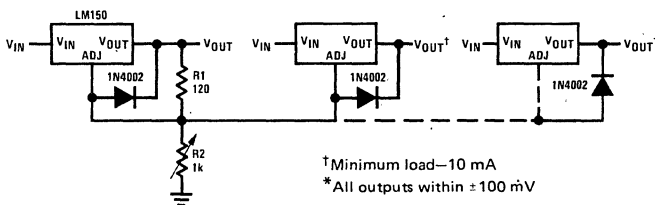
3A Current Regulator



Tracking Preregulator

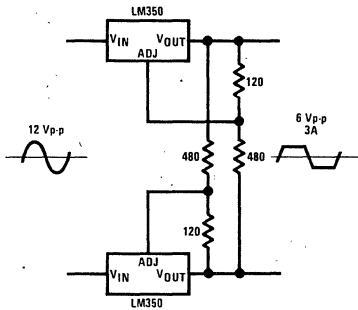


Adjusting Multiple On-Card Regulators with Single Control*

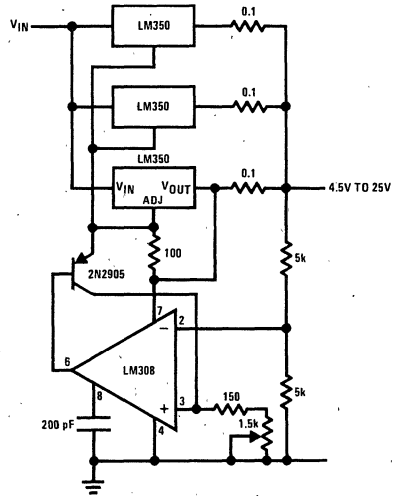


Typical Applications (Continued)

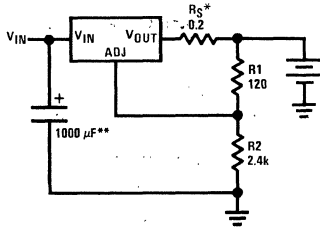
AC Voltage Regulator



Adjustable 10A Regulator



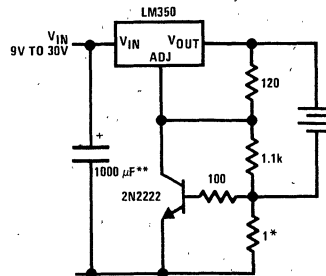
Simple 12V Battery Charger



*R_S—sets output impedance of charger $Z_{OUT} = R_S \left(1 + \frac{R_2}{R_1} \right)$
 Use of R_S allows low charging rates with fully charged battery.

**1000 μF is recommended to filter out any input transients.

Current Limited 6V Charger

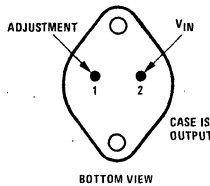


*Sets peak current (2A for 0.3Ω)

**1000 μF is recommended to filter out any input transients.

Connection Diagram

Metal Can Package



Order Number LM150K STEEL, LM250K STEEL
 or LM350K STEEL
 See NS Package K02A

LM320L/LM320ML Series 3-Terminal Negative Regulators

General Description

The LM320L/LM320ML series of 3-terminal negative voltage regulators features fixed output voltages of $-5V$, $-12V$ and $-15V$, with output current capabilities in excess of 100 mA, for the LM320L series, and 250 mA for the LM320ML series. These devices were designed using the latest computer techniques for optimizing the packaged IC thermal/electrical performance. The LM320L/LM320ML series, even when combined with a minimum output compensation capacitor of $0.1 \mu F$, exhibits an excellent transient response, a maximum line regulation of $0.07\% V_O/V$, and a maximum load regulation of $0.01\% V_O/mA$.

The LM320L/LM320ML series also includes, as self-protection circuitry: safe operating area circuitry for output transistor power dissipation limiting, a temperature independent short circuit current limit for peak output current limiting, and a thermal shutdown circuit to prevent excessive junction temperature. Although designed primarily as fixed voltage regulators, these devices may be combined with simple external circuitry for boosted and/or adjustable voltages and currents. The LM320L series is available in the 3-lead TO-92 package, and the LM320ML series is available in the 3-lead TO-202 package.

For applications requiring other voltages, see LM137 data sheet.

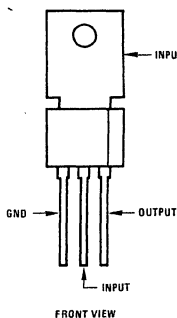
Features

- Preset output voltage error is less than $\pm 5\%$ over load, line and temperature
- LM320L is specified at an output current of 100 mA
- LM320ML is specified at an output current of 250 mA
- Internal short-circuit, thermal and safe operating area protection
- Easily adjustable to higher output voltages
- Maximum line regulation less than $0.07\% V_{OUT}/V$
- Maximum load regulation less than $0.01\% V_{OUT}/mA$
- Easily compensated with a small $0.1 \mu F$ output capacitor

| DEVICE | PACKAGE | RATED POWER DISSIPATION | DESIGN OUTPUT CURRENT |
|---------|---------|-------------------------|-----------------------|
| LM320ML | TO-202 | 7.5W | 0.25A |
| LM320L | TO-92 | 0.6W | 0.1A |

Connection Diagrams

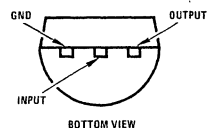
TO-202 Power Package (P)



Order Numbers:
 LM320MLP-5.0
 LM320MLP-12
 LM320MLP-15
 See NS Package P03A

For Tab Formed TO-202 Order Numbers:
 LM320MLP-5.0 TB
 LM320MLP-12 TB
 LM320MLP-15 TB
 See NS Package P03E

TO-92 Plastic Package (Z)



Order Numbers:
 LM320LZ-5.0
 LM320LZ-12
 LM320LZ-15
 See NS Package Z03A

Absolute Maximum Ratings

| | |
|--|--|
| Input Voltage | |
| $V_{OUT} = -5V, -12V, \text{ and } -15V$ | -35V |
| Internal Power Dissipation (Notes 1 and 3) | Internally Limited |
| Operating Temperature Range | $0^{\circ}\text{C to } +70^{\circ}\text{C}$ |
| Maximum Junction Temperature | $+125^{\circ}\text{C}$ |
| Storage Temperature Range | |
| Molded TO-92 | $-55^{\circ}\text{C to } +150^{\circ}\text{C}$ |
| Molded TO-202 | $-65^{\circ}\text{C to } +150^{\circ}\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics LM320ML (Note 2) $T_A = 0^{\circ}\text{C to } +70^{\circ}\text{C}$ unless otherwise noted.

| OUTPUT VOLTAGE | | -5V | | | -12V | | | -15V | | | UNITS |
|---|---|-------|-----|---------------------------------|-------|-----|----------------------------------|--------|-----|----------------------------------|---------------|
| INPUT VOLTAGE (unless otherwise noted) | | -10V | | | -17V | | | -20V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_j = 25^{\circ}\text{C}, I_O = 250\text{ mA}$ | -5.2 | -5 | -4.8 | -12.5 | -12 | -11.5 | -15.6 | -15 | -14.4 | V |
| | $1\text{ mA} \leq I_O \leq 250\text{ mA}$ ($V_{MIN} \leq V_{IN} \leq V_{MAX}$) | -5.25 | | -4.75 | -12.6 | | -11.4 | -15.75 | | -14.25 | |
| ΔV_O Line Regulation | $T_j = 25^{\circ}\text{C}, I_O = 250\text{ mA}$ | | | 50 | | | 40 | | | 40 | mV |
| | ($V_{MIN} \leq V_{IN} \leq V_{MAX}$) | | | ($-25 \leq V_{IN} \leq -7.3$) | | | ($-30 \leq V_{IN} \leq -14.6$) | | | ($-30 \leq V_{IN} \leq -17.7$) | V |
| ΔV_O Load Regulation | $T_j = 25^{\circ}\text{C}$ $1\text{ mA} \leq I_O \leq 250\text{ mA}$ | | | 50 | | | 120 | | | 150 | mV |
| ΔV_O Long Term Stability | $I_O = 250\text{ mA}$ | | 20 | | | 48 | | | 60 | | mV/1000 hr |
| I_Q Quiescent Current | $I_O = 250\text{ mA}$ | | 2 | 6 | | 2 | 6 | | 2 | 6 | mA |
| ΔI_Q Quiescent Current Change | $1\text{ mA} \leq I_O \leq 250\text{ mA}$ | | | 0.3 | | | 0.3 | | | 0.3 | mA |
| | $I_O = 250\text{ mA}$ | | | 0.25 | | | 0.25 | | | 0.25 | |
| | ($V_{MIN} \leq V_{IN} \leq V_{MAX}$) | | | ($-20 \leq V_{IN} \leq -7.5$) | | | ($-27 \leq V_{IN} \leq -14.8$) | | | ($-30 \leq V_{IN} \leq -18$) | |
| V_n Output Noise Voltage | $T_j = 25^{\circ}\text{C}, I_O = 250\text{ mA}$ $f = 10\text{ Hz} - 10\text{ kHz}$ | | | 40 | | | 100 | | | 120 | μV |
| $\frac{\Delta V_{IN}}{\Delta V_O}$ Ripple Rejection | $T_j = 25^{\circ}\text{C}, I_O = 250\text{ mA}$ $f = 120\text{ Hz}$ | 54 | | | 56 | | | 54 | | | dB |
| Input Voltage Required to Maintain Line Regulation | $T_j = 25^{\circ}\text{C}$ $I_O = 250\text{ mA}$ | | | -7.3 | | | -14.6 | | | -17.7 | V |

Note 1: Thermal resistance of the TO-202 Package (P) without a heat sink is 12°C/W junction to case and 70°C/W case to ambient.

Note 2: To ensure constant junction temperature, low duty cycle pulse testing is used.

Electrical Characteristics LM320L (Note 4) $T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$ unless otherwise noted.

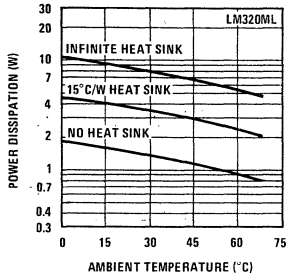
| OUTPUT VOLTAGE | | | -5V | | | -12V | | | -15V | | | UNITS |
|---|---|--|--------------------------------------|-------|---------------------------------------|---------------------------------------|-------|---------------------------------------|--------------------------------------|---------------|-------|-------|
| INPUT VOLTAGE (unless otherwise noted) | | | -10V | | | -17V | | | -20V | | | |
| PARAMETER* | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| V_O | Output Voltage (Note 3) | $T_J = 25^\circ\text{C}, I_O = 100\text{ mA}$ | -5.2 | -5 | -4.8 | -12.5 | -12 | -11.5 | -15.6 | -15 | -14.4 | |
| | $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | -5.25 | | -4.75 | -12.6 | | -11.4 | -15.75 | | -14.25 | V | |
| | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | $(-20 \leq V_{\text{IN}} \leq -7.5)$ | | | $(-27 \leq V_{\text{IN}} \leq -14.8)$ | | | $(-30 \leq V_{\text{IN}} \leq -18)$ | | | | |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | -5.25 | | -4.75 | -12.6 | | -11.4 | -15.7 | | -14.25 | | |
| | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | $(-20 \leq V_{\text{IN}} \leq -7)$ | | | $(-27 \leq V_{\text{IN}} \leq -14.5)$ | | | $(-30 \leq V_{\text{IN}} \leq -17.5)$ | | | | |
| ΔV_O | Line Regulation | $T_J = 25^\circ\text{C}, I_O = 100\text{ mA}$ | | 60 | | 45 | | 45 | | 45 | mV | |
| | | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | $(-20 \leq V_{\text{IN}} \leq -7.3)$ | | | $(-27 \leq V_{\text{IN}} \leq -14.6)$ | | | $(-30 \leq V_{\text{IN}} \leq 17.7)$ | | | V |
| | $T_J = 25^\circ\text{C}, I_O = 40\text{ mA}$ | | 60 | | 45 | | 45 | | 45 | mV | | |
| | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | $(-20 \leq V_{\text{IN}} \leq -7)$ | | | $(-27 \leq V_{\text{IN}} \leq -14.5)$ | | | $(-30 \leq V_{\text{IN}} \leq 17.5)$ | | | V | |
| ΔV_O | Load Regulation | $T_J = 25^\circ\text{C},$ $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | | 50 | | 100 | | 125 | | mV | | |
| ΔV_O | Long Term Stability | $I_O = 100\text{ mA}$ | | 20 | | 48 | | 60 | | mV/1000 hr | | |
| I_Q | Quiescent Current | $T_J = 25^\circ\text{C}, I_O = 100\text{ mA}$ | | 2 | 6 | | 2 | 6 | | 2 | 6 | mA |
| ΔI_Q | Quiescent Current Change | $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | | | 0.3 | | | 0.3 | | | 0.3 | mA |
| | | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | | 0.1 | | | 0.1 | | | 0.1 | mA |
| | | $I_O = 100\text{ mA}$ | | | 0.25 | | | 0.25 | | | 0.25 | mA |
| | | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | $(-20 \leq V_{\text{IN}} \leq -7.5)$ | | | $(-27 \leq V_{\text{IN}} \leq -14.8)$ | | | $(-30 \leq V_{\text{IN}} \leq -18)$ | | | V |
| V_n | Output Noise Voltage | $T_J = 25^\circ\text{C}, I_O = 100\text{ mA},$ $f = 10\text{ Hz} - 20\text{ kHz}$ | | 40 | | 96 | | 120 | | μV | | |
| $\frac{\Delta V_{\text{IN}}}{\Delta V_O}$ | Ripple Rejection | $T_J = 25^\circ\text{C}, I_O = 100\text{ mA},$ $f = 120\text{ Hz}$ | | 50 | | 52 | | 50 | | dB | | |
| | Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ\text{C}$ $I_O = 100\text{ mA}$ $I_O = 40\text{ mA}$ | | | -7.3 | | | -14.6 | | -17.7 | V | |
| | | | | | -7.0 | | | -14.5 | | -17.5 | | |

Note 3: Thermal resistance, junction to ambient, of the TO-92 (Z) Package is 180°C/W when mounted with 0.40 inch leads on a PC board, and 160°C/W when mounted with 0.25 inch leads on a PC board.

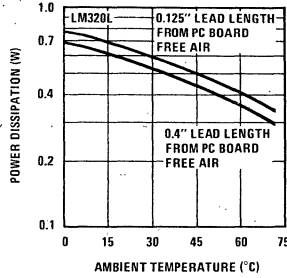
Note 4: To ensure constant junction temperature, low duty cycle pulse testing is used.

Typical Performance Characteristics

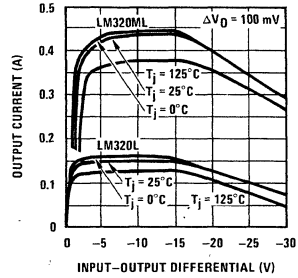
Maximum Average Power Dissipation (TO-202)



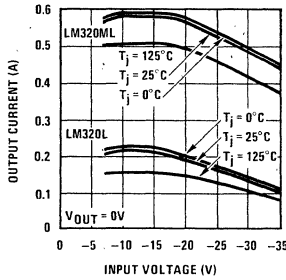
Maximum Average Power Dissipation (TO-92)



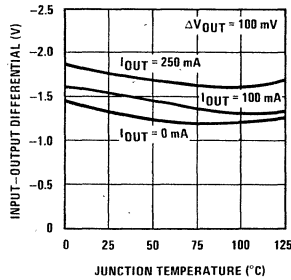
Peak Output Current



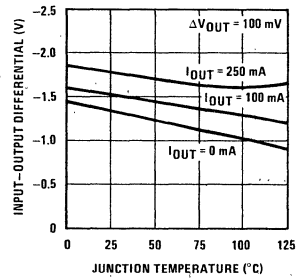
Short-Circuit Output Current



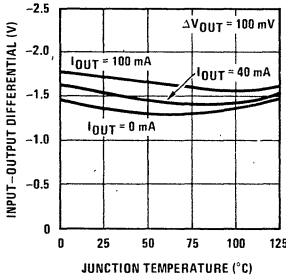
Dropout Voltage, LM320ML, -5V



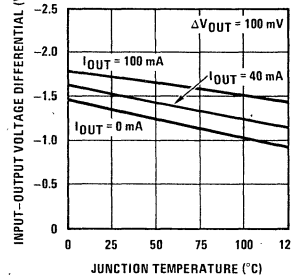
Dropout Voltage, LM320ML, -12V and -15V



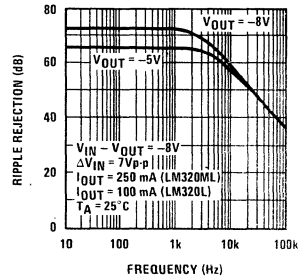
Dropout Voltage, LM320L -5V



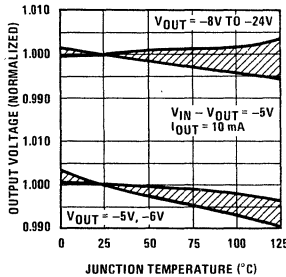
Dropout Voltage, LM320L -12V and -15V



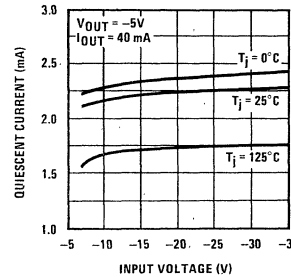
Ripple Rejection



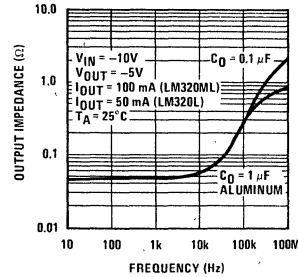
Output Voltage vs. Temperature (Normalized to 1V at $T_j = 25^\circ\text{C}$)



Quiescent Current

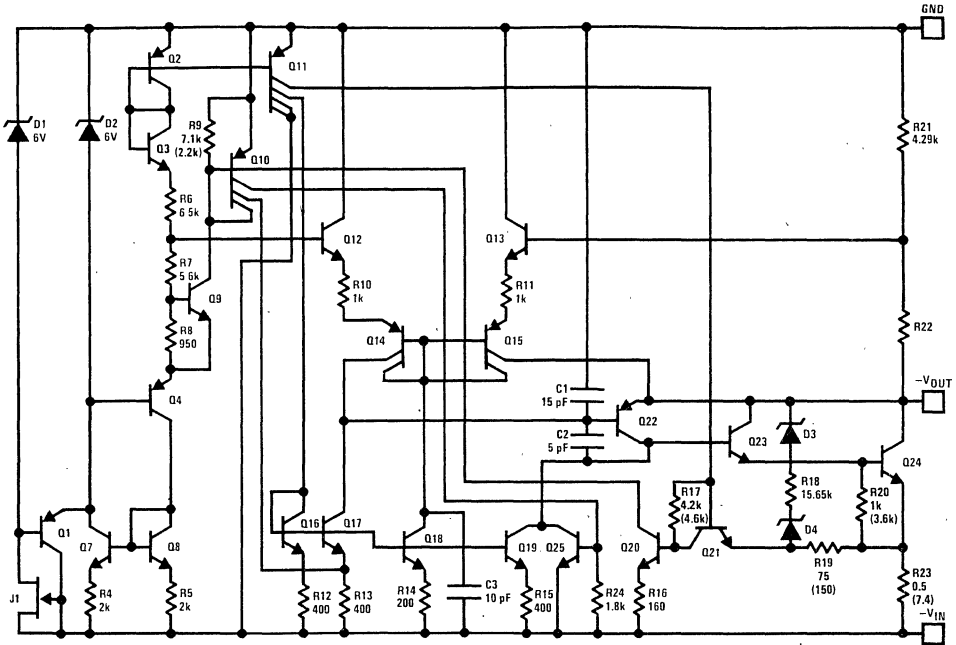


Output Impedance

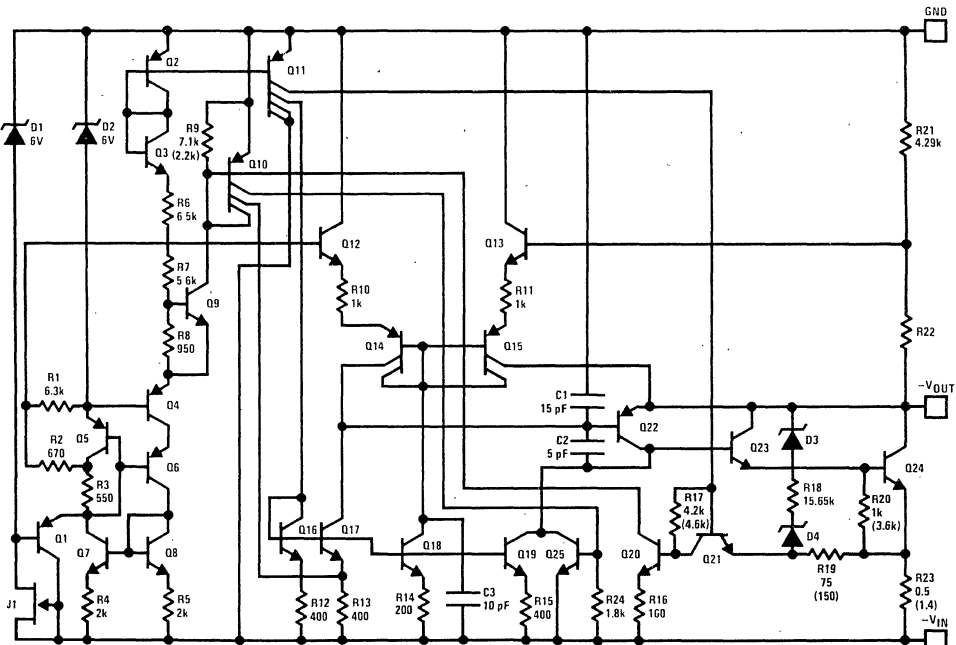


Schematic Diagrams

-5V
LM320ML (LM320L)

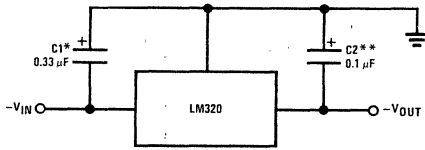


-12V and -15V
LM320ML (LM320L)



Typical Applications

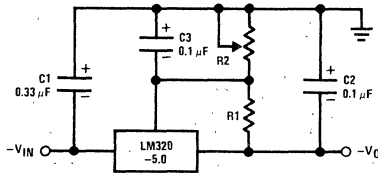
Fixed Output Regulator



*Required if the regulator is located far from the power supply filter. A 1 μF aluminum electrolytic may be substituted.

**Required for stability. A 1 μF aluminum electrolytic may be substituted.

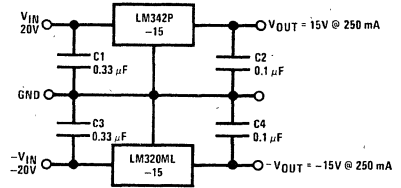
Adjustable Output Regulator



$$-V_0 = -5V - (5V/R1 + I_Q) \cdot R2,$$

$$5V/R1 > 3 I_Q$$

±15V, 250 mA Dual Power Supply





LM341 Series 3-Terminal Positive Regulators

General Description

The LM341-XX series of three terminal regulators is available with several fixed output voltages making them useful in a wide range of applications. One of these is local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow these regulators to be used in logic systems, instrumentation, HiFi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators these devices can be used with external components to obtain adjustable voltages and currents.

The LM341-XX series is available in the plastic TO-202 package. This package allows these regulators to deliver over 0.5A if adequate heat sinking is provided. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high for the heat sinking provided, the thermal shutdown circuit takes over preventing the IC from overheating.

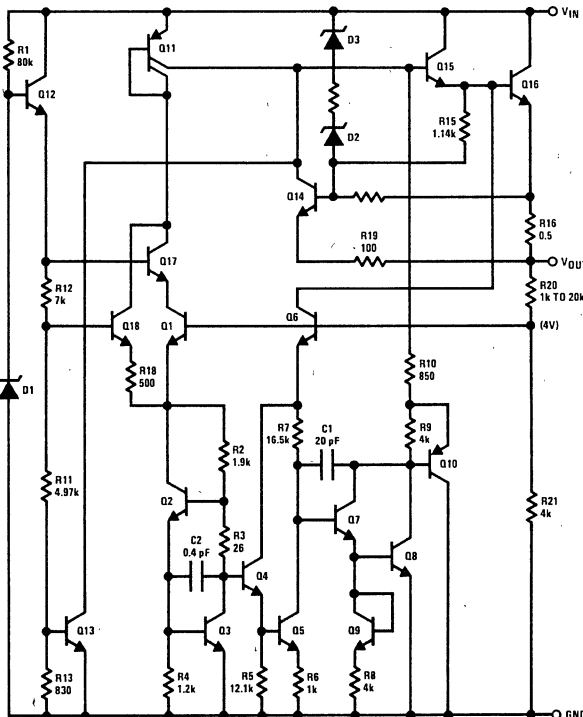
Considerable effort was expended to make the LM341-XX series of regulators easy to use and minimize the number of external components. It is not necessary to bypass the output, although this does improve transient response. Input bypassing is needed only if the regulator is located far from the filter capacitor of the power supply.

For applications requiring other voltages, see LM117 data sheet.

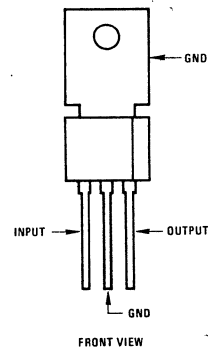
Features

- Output current in excess of 0.5A
- Internal thermal overload protection
- No external components required
- Output transistor safe area protection
- Internal short circuit current limit
- Available in plastic TO-202 package
- Special circuitry allows start-up even if output is pulled to negative voltage (\pm supplies)

Schematic and Connection Diagrams



Plastic Package



| | |
|---------------------|---------------------|
| Order Number: | For Tab Bend TO-202 |
| LM341P-5.0 | Order Number: |
| LM341P-12 | LM341P-5.0 TB |
| LM341P-15 | LM341P-12 TB |
| See NS Package P03A | LM341P-15 TB |
| | See NS Package P03E |

Absolute Maximum Ratings

| | |
|--|---|
| Input Voltage ($V_O = 5V, 12V$ and $15V$) | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range | 0°C to $+70^\circ\text{C}$ |
| Maximum Junction Temperature | $+125^\circ\text{C}$ |
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | $+230^\circ\text{C}$ |

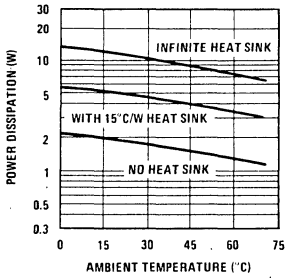
Electrical Characteristics $T_A = 0^\circ\text{C}$ to 70°C , $I_O = 500\text{ mA}$, unless otherwise noted.

| OUTPUT VOLTAGE | | | 5V | | | 12V | | | 15V | | | UNITS |
|---|---|--|-----------------------------|-----|------|------------------------------|-----|------|------------------------------|-----|-------|---------------|
| INPUT VOLTAGE (unless otherwise noted) | | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_J = 25^\circ\text{C}$ | | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V |
| | $P_D \leq 7.5W$, $5\text{ mA} \leq I_O \leq 500\text{ mA}$ and $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V |
| | | | $(7.5 \leq V_{IN} \leq 20)$ | | | $(14.8 \leq V_{IN} \leq 27)$ | | | $(18 \leq V_{IN} \leq 30)$ | | | V |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$, $I_O = 100\text{ mA}$ | | | | 50 | | | 120 | | | 150 | mV |
| | $T_J = 25^\circ\text{C}$, $I_O = 500\text{ mA}$ | | | | 100 | | | 240 | | | 300 | mV |
| | | | $(7.2 \leq V_{IN} \leq 25)$ | | | $(14.5 \leq V_{IN} \leq 30)$ | | | $(17.6 \leq V_{IN} \leq 30)$ | | | V |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, $5\text{ mA} \leq I_O \leq 500\text{ mA}$ | | | | -100 | | | 240 | | | 300 | mV |
| ΔV_O Long Term Stability | | | | | 20 | | | 48 | | | 60 | mV/1000 hrs |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | 4 | | 10 | 4 | | 10 | 4 | | 10 | mA |
| ΔI_Q Quiescent Current Change | $T_J = 25^\circ\text{C}$ | | | | 0.5 | | | 0.5 | | | 0.5 | mA |
| | $T_J = 25^\circ\text{C}$ | | | | 1 | | | 1 | | | 1 | mA |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | $(7.5 \leq V_{IN} \leq 25)$ | | | $(14.8 \leq V_{IN} \leq 30)$ | | | $(18 \leq V_{IN} \leq 30)$ | | | V |
| V_n Output Noise Voltage | $T_J = 25^\circ\text{C}$, $f = 10\text{ Hz} - 100\text{ kHz}$ | | 40 | | | 75 | | | 90 | | | μV |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $f = 120\text{ Hz}$ | | 78 | | | 71 | | | 69 | | | V |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ\text{C}$, $I_O = 500\text{ mA}$ | | 7.2 | | | 14.5 | | | 17.6 | | | V |

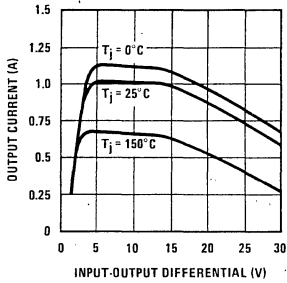
Note 1: Thermal resistance without a heat sink for junction to case temperature is 12°C/W for the TO-202 package. Thermal resistance for case to ambient temperature is 70°C/W for the TO-202 package.

Typical Performance Characteristics

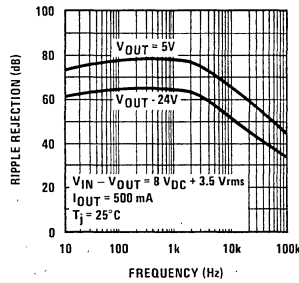
Maximum Average Power Dissipation



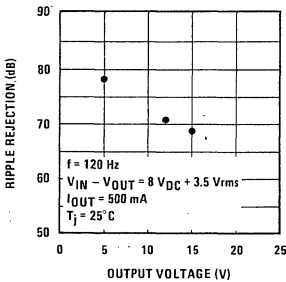
Peak Output Current



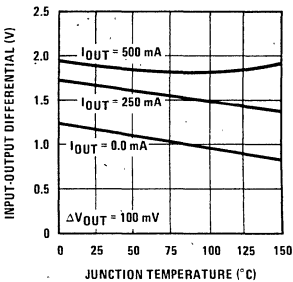
Ripple Rejection



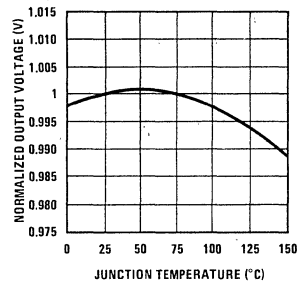
Ripple Rejection



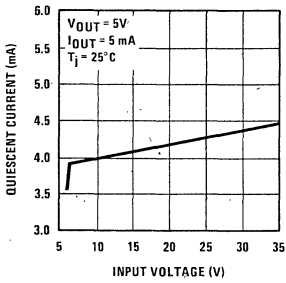
Dropout Voltage



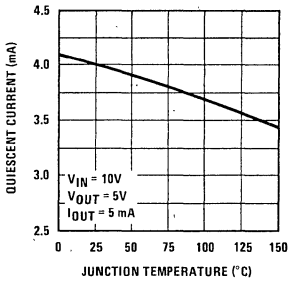
Output Voltage (Normalized to 1V at $T_J = 25^\circ\text{C}$)



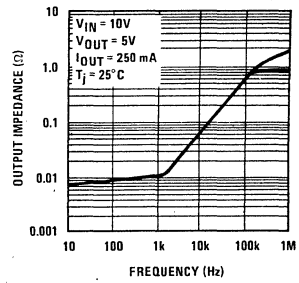
Quiescent Current



Quiescent Current



Output Impedance





LM342 Series 3-Terminal Positive Regulators

General Description

The LM342-XX series of three terminal regulators is available with several fixed output voltages making them useful in a wide range of applications. One of these is local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow these regulators to be used in logic systems, instrumentation, HiFi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators these devices can be used with external components to obtain adjustable voltages and currents.

The LM342-XX series is available in the plastic TO-202 package. This package allows these regulators to deliver over 0.25A if adequate heat sinking is provided. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high for the heat sinking provided, the thermal shutdown circuit takes over preventing the IC from overheating.

Considerable effort was expended to make the LM342-XX series of regulators easy to use and minimize the number of external components. It is not necessary to bypass the output, although this does improve transient response.

Input bypassing is needed only if the regulator is located far from the filter capacitor of the power supply.

For applications requiring other voltages, see LM117 data sheet.

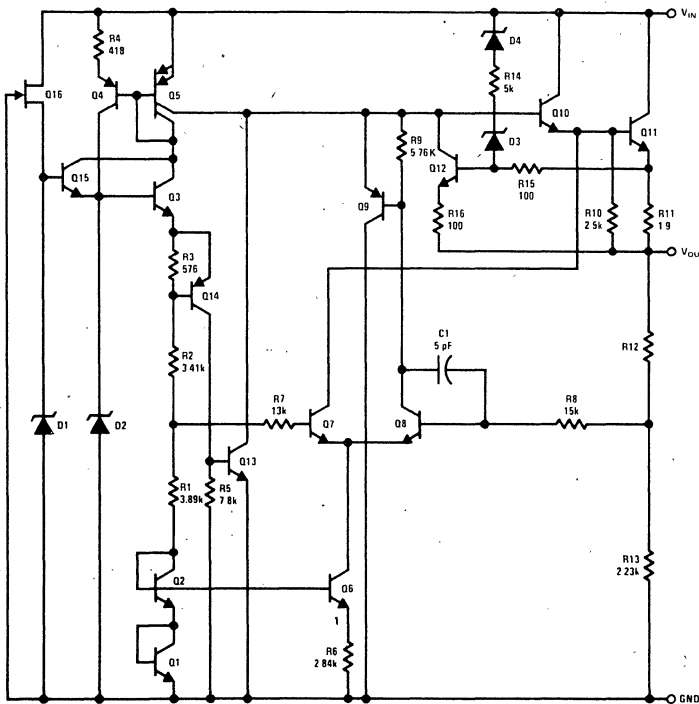
Features

- Output current in excess of 0.25A
- Internal thermal overload protection
- No external components required
- Output transistor safe area protection
- Internal short circuit current limit
- Available in plastic TO-202 package
- Special circuitry allows start-up even if output is pulled to negative voltage (\pm supplies)

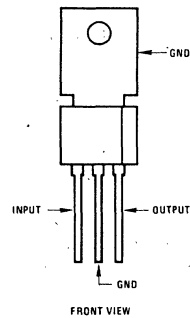
Voltage Range

| | |
|-----------|-----|
| LM342-5.0 | 5V |
| LM342-12 | 12V |
| LM342-15 | 15V |

Schematic and Connection Diagrams



Plastic Package



Order Numbers:
 LM342P-5.0
 LM342P-12
 LM342P-15
 See NS Package P03A

For Tab Bend TO-202
 Order Numbers:
 LM342P-5.0 TB
 LM342P-12 TB
 LM342P-15 TB
 See NS Package P03E

Absolute Maximum Ratings

| | |
|--|-----------------------------------|
| Input Voltage | |
| $V_O = 5V$ | 30V |
| $V_O = 12V$ and $15V$ | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range | $0^{\circ}C$ to $+70^{\circ}C$ |
| Maximum Junction Temperature | $125^{\circ}C$ |
| Storage Temperature Range | $-65^{\circ}C$ to $+150^{\circ}C$ |
| Lead Temperature (Soldering, 10 seconds) | $300^{\circ}C$ |

Electrical Characteristics

$T_A = 0^{\circ}C$ to $+70^{\circ}C$, $I_O = 250$ mA (Note 2) unless noted.

| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS |
|--|---|------------------------------------|-----|------|--------------------------------------|-----|------|--------------------------------------|-----|-------|-------------|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage (Note 3) | $T_J = 25^{\circ}C$ | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V |
| | $1\text{ mA} \leq I_O \leq 250\text{ mA}$ and $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V |
| | | (8 $\leq V_{IN} \leq 20$) | | | (15 $\leq V_{IN} \leq 27$) | | | (18 $\leq V_{IN} \leq 30$) | | | V |
| ΔV_O Line Regulation | $T_J = 25^{\circ}C$, $I_O = 250\text{ mA}$ | 55 (7.3 $\leq V_{IN} \leq 25$) | | | 100 (14.6 $\leq V_{IN} \leq 30$) | | | 100 (17.7 $\leq V_{IN} \leq 30$) | | | mV V |
| ΔV_O Load Regulation | $T_J = 25^{\circ}C$, $1\text{ mA} \leq I_O \leq 250\text{ mA}$ | 50 | | | 120 | | | 150 | | | mV |
| ΔV_O Long Term Stability | | 20 | | | 48 | | | 60 | | | mV/1000 hrs |
| I_Q Quiescent Current | $T_J = 25^{\circ}C$ | 6 | | | 6 | | | 6 | | | mA |
| ΔI_Q Quiescent Current Change | $T_J = 25^{\circ}C$, $1\text{ mA} \leq I_O \leq 250\text{ mA}$ | 0.5 | | | 0.5 | | | 0.5 | | | mA |
| | $T_J = 25^{\circ}C$, $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | 1.5 | | | 1.5 | | | 1.5 | | | mA |
| | | (7.3 $\leq V_{IN} \leq 25$) | | | (14.6 $\leq V_{IN} \leq 30$) | | | (17.7 $\leq V_{IN} \leq 30$) | | | V |
| V_n Output Noise Voltage | $T_J = 25^{\circ}C$, $f = 10\text{ Hz} - 10\text{ kHz}$ | 40 | | | 96 | | | 120 | | | μV |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $f = 120\text{ Hz}$ | 50 | 64 | | 44 | 58 | | 42 | 56 | | dB |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^{\circ}C$, $I_O = 250\text{ mA}$ | 7.3 | | | 14.6 | | | 17.7 | | | V |

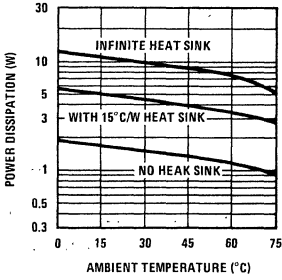
Note 1: Thermal resistance of the TO-202 package (P) without a heat sink is $12^{\circ}C/W$ junction to case and $80^{\circ}C/W$ junction to ambient.

Note 2: The electrical characteristics data represent pulse test conditions with junction temperatures as shown at the initiation of tests.

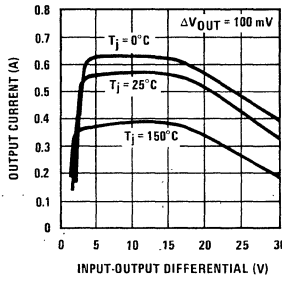
Note 3: The temperature coefficient of V_{OUT} is typically within 0.01% $V_O/^{\circ}C$.

Typical Performance Characteristics

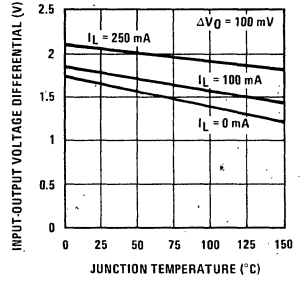
Maximum Average Power Dissipation (TO-202 Package)



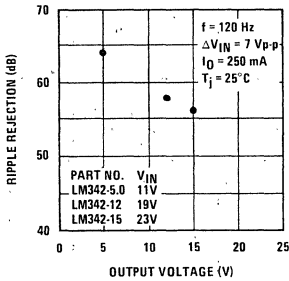
Peak Output Current



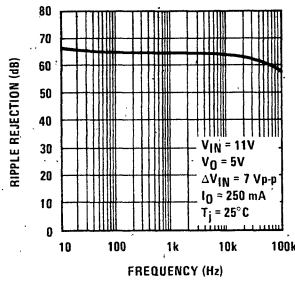
Dropout Voltage



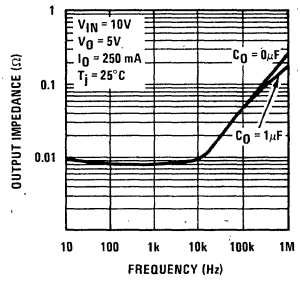
Ripple Rejection



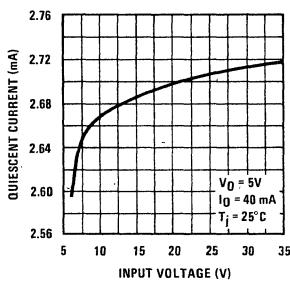
Ripple Rejection



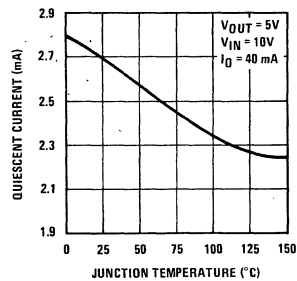
Output Impedance



Quiescent Current

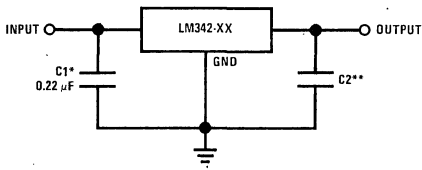


Quiescent Current



Typical Applications

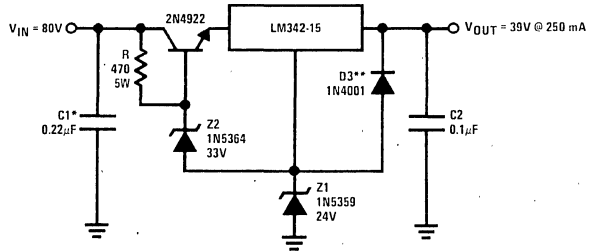
Fixed Output Regulator



*Required if the regulator is located far from power supply filter

**Although not required, C2 does improve transient response. (If needed, use 0.1 μF ceramic disc.)

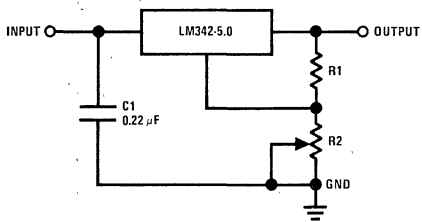
High Output Voltage Regulator



*Necessary if regulator is located far from the power supply filter

**D3 aids in full load start-up and protects the regulator during short circuits from high input to output voltage differentials

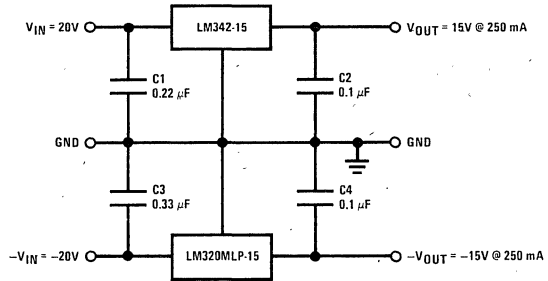
Adjustable Output Regulator



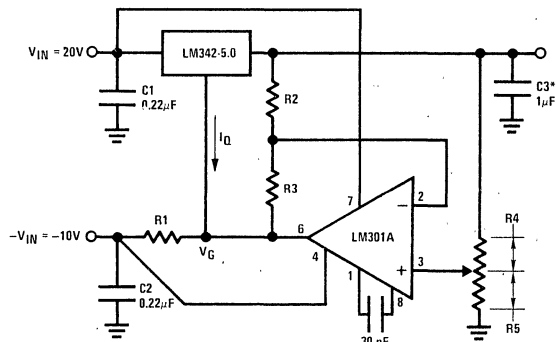
$$V_o = 5V + (5V/R1 + I_Q) R2$$

$$\frac{5V/R1 > 3I_Q}{(R1 + R2)/R1} \cdot (L_r \text{ of LM342-05})$$

±15V, 250 mA Dual Power Supply



Variable Output Regulator 0.5V – 18V



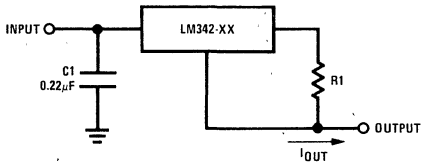
$$V_{OUT} = V_G + 5V, R1 = (-V_{IN}/I_Q \text{ LM342})$$

$$V_{OUT} = 5V(R2/R4) \text{ for } (R2 + R3) = (R4 + R5)$$

A 0.5V output will correspond to $(R2/R4) = 0.1, (R3/R4) = 0.9$

*Solid tantalum

Current Regulator



$$I_{OUT} = V^2 - 3/R1 + I_Q$$

$\Delta I_Q \leq 1.5 \text{ mA}$ over line and load changes

LM723/LM723C Voltage Regulator

General Description

The LM723/LM723C is a voltage regulator designed primarily for series regulator applications. By itself, it will supply output currents up to 150 mA; but external transistors can be added to provide any desired load current. The circuit features extremely low standby current drain, and provision is made for either linear or foldback current limiting. Important characteristics are:

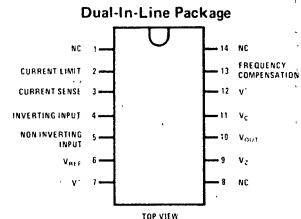
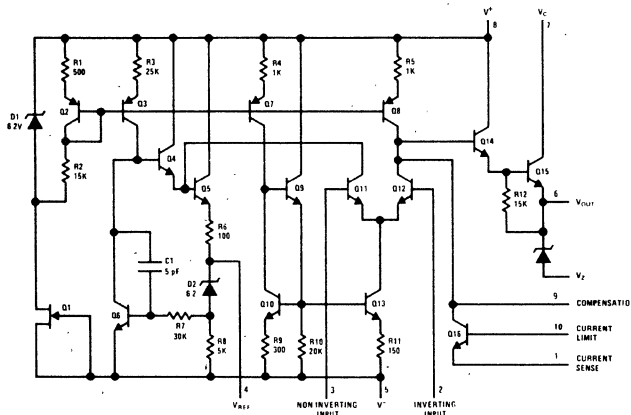
- 150 mA output current without external pass transistor
- Output currents in excess of 10A possible by adding external transistors

- Input voltage 40V max
- Output voltage adjustable from 2V to 37V
- Can be used as either a linear or a switching regulator.

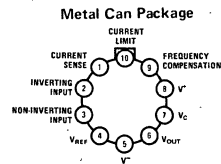
The LM723/LM723C is also useful in a wide range of other applications such as a shunt regulator, a current regulator or a temperature controller.

The LM723C is identical to the LM723 except that the LM723C has its performance guaranteed over a 0°C to 70°C temperature range, instead of -55°C to +125°C.

Schematic and Connection Diagrams *

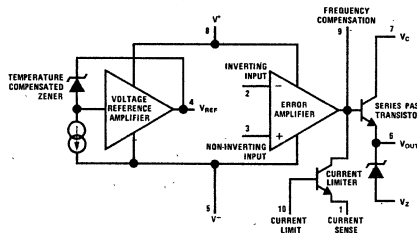


Order Number LM723CN
See NS Package N14A
Order Number LM723J or LM723CJ
See NS Package J14A



Note: Pin 5 connected to c.s.s.
TOP VIEW
Order Number LM723H or LM723CH
See NS Package H10C

Equivalent Circuit *



*Pin numbers refer to metal can package.

Absolute Maximum Ratings

| | |
|--|-----------------|
| Pulse Voltage from V^+ to V^- (50 ms) | 50V |
| Continuous Voltage from V^+ to V^- | 40V |
| Input-Output Voltage Differential | 40V |
| Maximum Amplifier Input Voltage (Either Input) | 7.5V |
| Maximum Amplifier Input Voltage (Differential) | 5V |
| Current from V_Z | 25 mA |
| Current from V_{REF} | 15 mA |
| Internal Power Dissipation Metal Can (Note 1) | 800 mW |
| Cavity DIP (Note 1) | 900 mW |
| Molded DIP (Note 1) | 660 mW |
| Operating Temperature Range LM723 | -55°C to +125°C |
| LM723C | 0°C to +70°C |
| Storage Temperature Range Metal Can | -65°C to +150°C |
| DIP | -55°C to +125°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LM723 | | | LM723C | | | UNITS |
|-----------------------------------|---|-------|------|------|--------|------|------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $V_{IN} = 12V$ to $V_{IN} = 15V$ -55°C ≤ T_A ≤ +125°C 0°C ≤ T_A ≤ +70°C $V_{IN} = 12V$ to $V_{IN} = 40V$ | | .01 | 0.1 | | .01 | 0.1 | % V_{OUT} |
| | | | | | | | 0.3 | % V_{OUT} |
| | | | | | | | 0.3 | % V_{OUT} |
| | | | .02 | 0.2 | | 0.1 | 0.5 | % V_{OUT} |
| Load Regulation | $I_L = 1$ mA to $I_L = 50$ mA -55°C ≤ T_A ≤ +125°C 0°C ≤ T_A ≤ +70°C | | .03 | 0.15 | | .03 | 0.2 | % V_{OUT} |
| | | | | 0.6 | | | | % V_{OUT} |
| | | | | | | | 0.6 | % V_{OUT} |
| Ripple Rejection | $f = 50$ Hz to 10 kHz, $C_{REF} = 0$ $f = 50$ Hz to 10 kHz, $C_{REF} = 5 \mu F$ | | 74 | | | 74 | | dB |
| | | | 86 | | | 86 | | dB |
| Average Temperature | -55°C ≤ T_A ≤ +125°C | | .002 | .015 | | | | %/°C |
| Coefficient of Output Voltage | 0°C ≤ T_A ≤ +70°C | | | | | .003 | .015 | %/°C |
| Short Circuit Current Limit | $R_{SC} = 10\Omega$, $V_{OUT} = 0$ | | 65 | | | 65 | | mA |
| Reference Voltage | | 6.95 | 7.15 | 7.35 | 6.80 | 7.15 | 7.50 | V |
| Output Noise Voltage | $BW = 100$ Hz to 10 kHz, $C_{REF} = 0$ $BW = 100$ Hz to 10 kHz, $C_{REF} = 5 \mu F$ | | 20 | | | 20 | | μV_{rms} |
| | | | 2.5 | | | 2.5 | | μV_{rms} |
| Long Term Stability | | | 0.1 | | | 0.1 | | %/1000 hrs |
| Standby Current Drain | $I_L = 0$, $V_{IN} = 30V$ | | 1.3 | 3.5 | | 1.3 | 4.0 | mA |
| Input Voltage Range | | 9.5 | | 40 | 9.5 | | 40 | V |
| Output Voltage Range | | 2.0 | | 37 | 2.0 | | 37 | V |
| Input-Output Voltage Differential | | 3.0 | | 38 | 3.0 | | 38 | V |

Note 1: See derating curves for maximum power rating above 25°C.

Note 2: Unless otherwise specified, $T_A = 25^\circ C$, $V_{IN} = V^+ = V_C = 12V$, $V^- = 0$, $V_{OUT} = 5V$, $I_L = 1$ mA, $R_{SC} = 0$, $C_1 = 100$ pF, $C_{REF} = 0$ and divider impedance as seen by error amplifier ≤ 10 kΩ connected as shown in Figure 1. Line and load regulation specifications are given for the condition of constant chip temperature. Temperature drifts must be taken into account separately for high dissipation conditions.

Note 3: L_1 is 40 turns of No. 20 enameled copper wire wound on Ferroxcube P36/22-3B7 pot core or equivalent with 0.009 in. air gap.

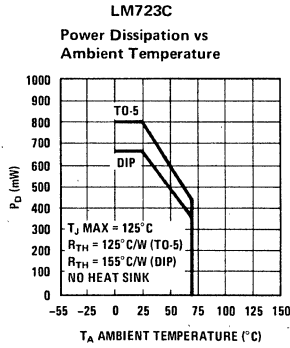
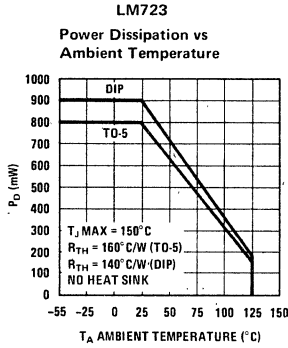
Note 4: Figures in parentheses may be used if R1/R2 divider is placed on opposite input of error amp.

Note 5: Replace R1/R2 in figures with divider shown in Figure 13.

Note 6: V^+ must be connected to a +3V or greater supply.

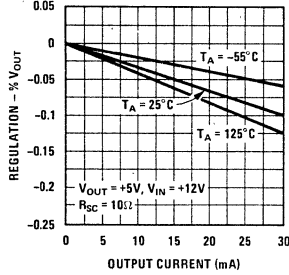
Note 7: For metal can applications where V_Z is required, an external 6.2 volt zener diode should be connected in series with V_{OUT} .

Maximum Power Ratings

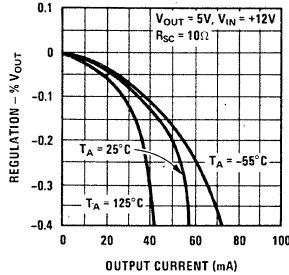


Typical Performance Characteristics

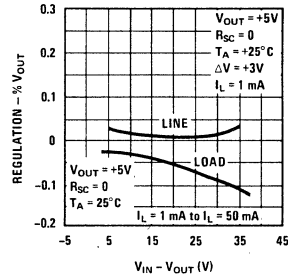
Load Regulation Characteristics with Current Limiting



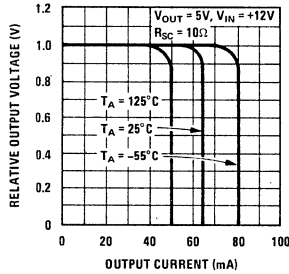
Load Regulation Characteristics with Current Limiting



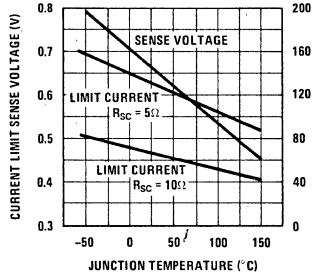
Load & Line Regulation vs Input-Output Voltage Differential



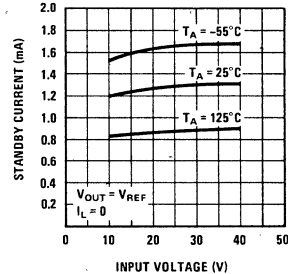
Current Limiting Characteristics



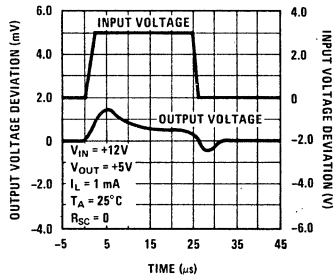
Current Limiting Characteristics vs Junction Temperature



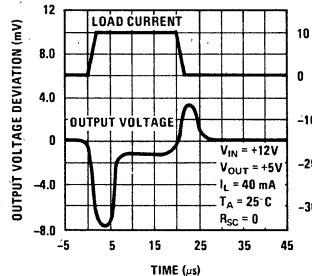
Standby Current Drain vs Input Voltage



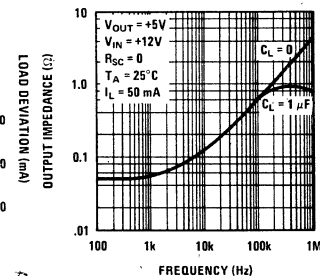
Line Transient Response



Load Transient Response



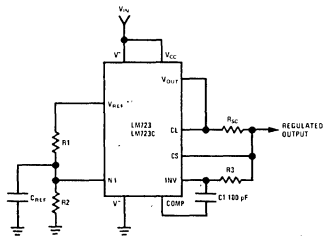
Output Impedance vs Frequency



| POSITIVE OUTPUT VOLTAGE | APPLICABLE FIGURES | FIXED OUTPUT ±5% | | OUTPUT ADJUSTABLE ±10% (Note 5) | | | NEGATIVE OUTPUT VOLTAGE | APPLICABLE FIGURES | FIXED OUTPUT ±5% | | 5% OUTPUT ADJUSTABLE ±10% | | |
|-------------------------|---------------------|------------------|------|---------------------------------|-----|-----|-------------------------|--------------------|------------------|------|---------------------------|-----|-----|
| | | R1 | R2 | R1 | P1 | R2 | | | R1 | R2 | R1 | P1 | R2 |
| +3.0 | 1, 5, 6, 9, 12 (4) | 4.12 | 3.01 | 1.8 | 0.5 | 1.2 | +100 | 7 | 3.57 | 102 | 2.2 | 10 | 91 |
| +3.6 | 1, 5, 6, 9, 12 (4) | 3.57 | 3.65 | 1.5 | 0.5 | 1.5 | +250 | 7 | 3.57 | 255 | 2.2 | 10 | 240 |
| +5.0 | 1, 5, 6, 9, 12 (4) | 2.15 | 4.99 | .75 | 0.5 | 2.2 | -6 (Note 6) | 3, (10) | 3.57 | 2.43 | 1.2 | 0.5 | .75 |
| +6.0 | 1, 5, 6, 9, 12 (4) | 1.15 | 6.04 | 0.5 | 0.5 | 2.7 | -9 | 3, 10 | 3.48 | 5.36 | 1.2 | 0.5 | 2.0 |
| +9.0 | 2, 4, (5, 6, 12, 9) | 1.87 | 7.15 | .75 | 1.0 | 2.7 | -12 | 3, 10 | 3.57 | 8.45 | 1.2 | 0.5 | 3.3 |
| +12 | 2, 4, (5, 6, 9, 12) | 4.87 | 7.15 | 2.0 | 1.0 | 3.0 | -15 | 3, 10 | 3.65 | 11.5 | 1.2 | 0.5 | 4.3 |
| +15 | 2, 4, (5, 6, 9, 12) | 7.87 | 7.15 | 3.3 | 1.0 | 3.0 | -28 | 3, 10 | 3.57 | 24.3 | 1.2 | 0.5 | 10 |
| +28 | 2, 4, (5, 6, 9, 12) | 21.0 | 7.15 | 5.6 | 1.0 | 2.0 | -45 | 8 | 3.57 | 41.2 | 2.2 | 10 | 33 |
| +45 | 7 | 3.57 | 48.7 | 2.2 | 10 | 39 | -100 | 8 | 3.57 | 97.6 | 2.2 | 10 | 91 |
| +75 | 7 | 3.57 | 78.7 | 2.2 | 10 | 68 | -250 | 8 | 3.57 | 249 | 2.2 | 10 | 240 |

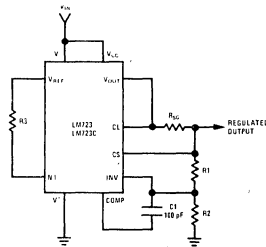
| | | |
|---|--|--|
| Outputs from +2 to +7 volts [Figures 1, 5, 6, 9, 12, (4)] $V_{OUT} = [V_{REF} \times \frac{R2}{R1 + R2}]$ | Outputs from +4 to +250 volts [Figure 7] $V_{OUT} = [\frac{V_{REF}}{2} \times \frac{R2 - R1}{R1}], R3 = R4$ | Current Limiting $I_{LIMIT} = \frac{V_{SENSE}}{R_{SC}}$ |
| Outputs from +7 to +37 volts [Figures 2, 4, (5, 6, 9, 12)] $V_{OUT} = [V_{REF} \times \frac{R1 + R2}{R2}]$ | Outputs from -6 to -250 volts [Figures 3, 8, 10] $V_{OUT} = [\frac{V_{REF}}{2} \times \frac{R1 + R2}{R1}], R3 = R4$ | Foldback Current Limiting $I_{KNEE} = [\frac{V_{OUT} R3}{R_{SC} R4} + \frac{V_{SENSE} (R3 + R4)}{R_{SC} R4}]$ $I_{SHORT\ CKT} = [\frac{V_{SENSE}}{R_{SC}} \times \frac{R3 + R4}{R4}]$ |

Typical Applications



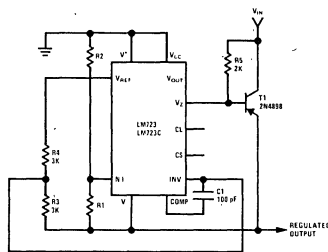
TYPICAL PERFORMANCE
 Note: $R3 = \frac{R1 R2}{R1 + R2}$ for minimum temperature drift.
 Regulated Output Voltage: 5V
 Line Regulation ($\Delta V_{IN} = 3V$): 0.5 mV
 Load Regulation ($\Delta I_L = 50\text{ mA}$): 1.5 mV

FIGURE 1. Basic Low Voltage Regulator (V_{OUT} = 2 to 7 Volts)



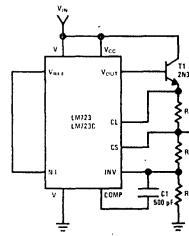
TYPICAL PERFORMANCE
 Note: $R3 = \frac{R1 R2}{R1 + R2}$ for minimum temperature drift.
 Regulated Output Voltage: 15V
 Line Regulation ($\Delta V_{IN} = 3V$): 1.5 mV
 Load Regulation ($\Delta I_L = 50\text{ mA}$): 4.5 mV
 R3 may be eliminated for minimum component count.

FIGURE 2. Basic High Voltage Regulator (V_{OUT} = 7 to 37 Volts)



TYPICAL PERFORMANCE
 Regulated Output Voltage: -15V
 Line Regulation ($\Delta V_{IN} = 3V$): 1 mV
 Load Regulation ($\Delta I_L = 100\text{ mA}$): 2 mV

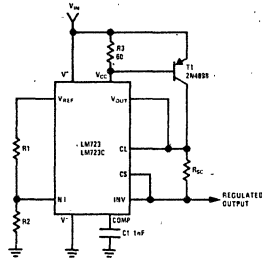
FIGURE 3. Negative Voltage Regulator



TYPICAL PERFORMANCE
 Regulated Output Voltage: +15V
 Line Regulation ($\Delta V_{IN} = 3V$): 1.5 mV
 Load Regulation ($\Delta I_L = 1A$): 15 mV

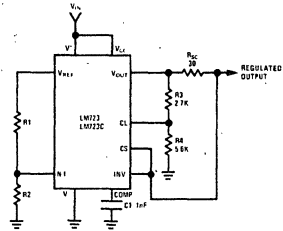
FIGURE 4. Positive Voltage Regulator (External NPN Pass Transistor)

Typical Applications (Continued)



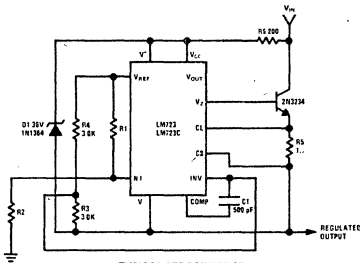
TYPICAL PERFORMANCE
 Regulated Output Voltage +5V
 Line Regulation ($\Delta V_{IN} = 3V$) 0.5 mV
 Load Regulation ($\Delta I_L = 1A$) 5 mV

FIGURE 5. Positive Voltage Regulator (External PNP Pass Transistor)



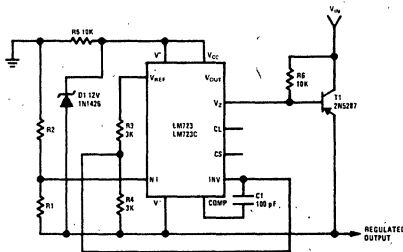
TYPICAL PERFORMANCE
 Regulated Output Voltage +5V
 Line Regulation ($\Delta V_{IN} = 3V$) 0.5 mV
 Load Regulation ($\Delta I_L = 10 mA$) 1 mV
 Short Circuit Current 20 mA

FIGURE 6. Foldback Current Limiting



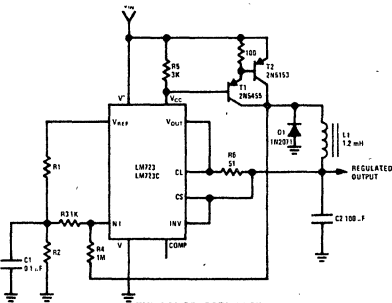
TYPICAL PERFORMANCE
 Regulated Output Voltage +50V
 Line Regulation ($\Delta V_{IN} = 20V$) 15 mV
 Load Regulation ($\Delta I_L = 50 mA$) 20 mV

FIGURE 7. Positive Floating Regulator



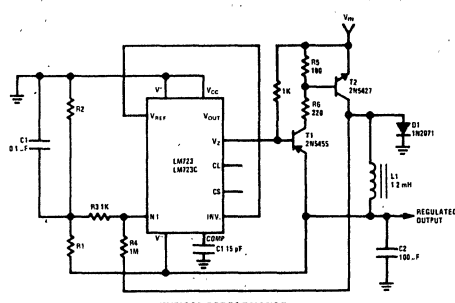
TYPICAL PERFORMANCE
 Regulated Output Voltage -100V
 Line Regulation ($\Delta V_{IN} = 20V$) 30 mV
 Load Regulation ($\Delta I_L = 100 mA$) 20 mV

FIGURE 8. Negative Floating Regulator



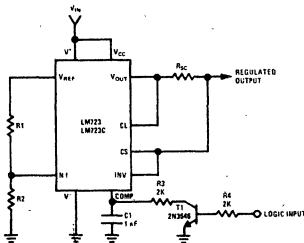
TYPICAL PERFORMANCE
 Regulated Output Voltage +5V
 Line Regulation ($\Delta V_{IN} = 30V$) 18 mV
 Load Regulation ($\Delta I_L = 2A$) 80 mV

FIGURE 9. Positive Switching Regulator



TYPICAL PERFORMANCE
 Regulated Output Voltage -15V
 Line Regulation ($\Delta V_{IN} = 20V$) 8 mV
 Load Regulation ($\Delta I_L = 2A$) 6 mV

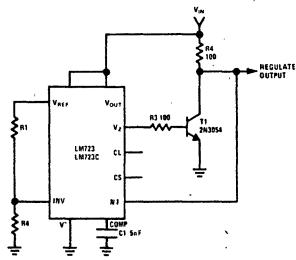
FIGURE 10. Negative Switching Regulator



TYPICAL PERFORMANCE
 Regulated Output Voltage +5V
 Line Regulation ($\Delta V_{IN} = 3V$) 0.5 mV
 Load Regulation ($\Delta I_L = 50 mA$) 1.5 mV

Note: Current limit transistor may be used for shutdown if current limiting is not required.

FIGURE 11. Remote Shutdown Regulator with Current Limiting



TYPICAL PERFORMANCE
 Regulated Output Voltage +5V
 Line Regulation ($\Delta V_{IN} = 10V$) 0.5 mV
 Load Regulation ($\Delta I_L = 100 mA$) 1.5 mV

FIGURE 12. Shunt Regulator

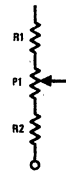


FIGURE 13. Output Voltage Adjust (See Note 5)

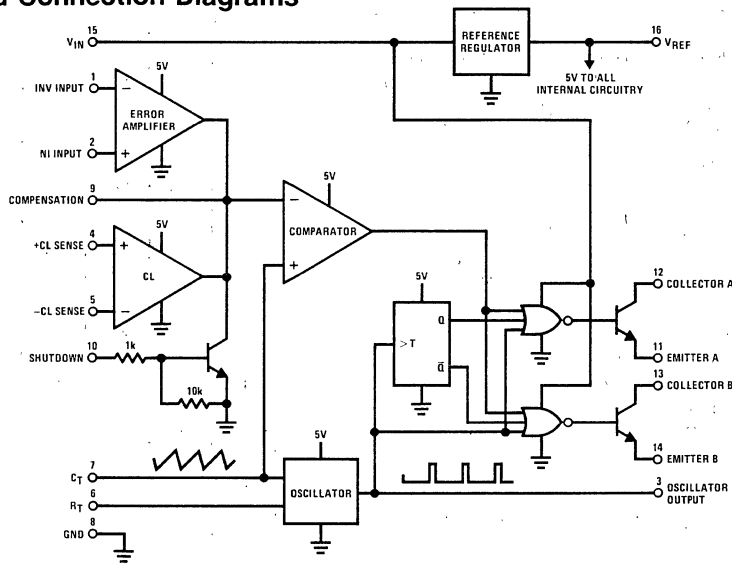
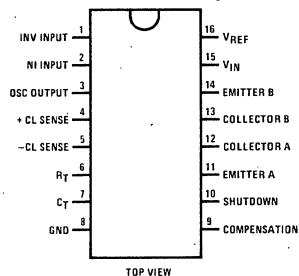
**LM1524/LM2524/LM3524
Regulating Pulse Width Modulator**
General Description

The LM1524 series of regulating pulse width modulators contains all of the control circuitry necessary to implement switching regulators of either polarity, transformer coupled DC to DC converters, transformerless polarity converters and voltage doublers, as well as other power control applications. This device includes a 5V voltage regulator capable of supplying up to 50 mA to external circuitry, a control amplifier, an oscillator, a pulse width modulator, a phase splitting flip-flop, dual alternating output switch transistors, and current limiting and shutdown circuitry. Both the regulator output transistor and each output switch are internally current limited and, to limit junction temperature, an internal thermal shutdown circuit is employed. The LM1524 is rated for operation from -55°C to $+125^{\circ}\text{C}$ and is packaged in a hermetic 16-lead DIP (J). The LM2524 and LM3524 are rated for operation from 0°C to $+70^{\circ}\text{C}$ and are

packaged in either a hermetic 16-lead DIP (J) or a 16-lead molded DIP (N).

Features

- Complete PWM power control circuitry.
- Frequency adjustable to greater than 100 kHz
- 2% frequency stability with temperature
- Total quiescent current less than 10 mA
- Dual alternating output switches for both push-pull or single-ended applications
- Current limit amplifier provides external component protection
- On-chip protection against excessive junction temperature and output current
- 5V, 50 mA linear regulator output available to user

Block and Connection Diagrams

Dual-In-Line Package


Order Number LM1524J, LM2524J
or LM3524J
See NS Package J16A

Order Number LM2524N
or LM3524N
See NS Package N16A

Absolute Maximum Ratings

| | | | |
|--|-----------------|--|-----------------|
| Input Voltage | 40V | Maximum Junction Temperature | |
| Reference Voltage, Forced | 6V | (J Package) | 150°C |
| Reference Output Current | 50 mA | (N Package) | 125°C |
| Output Current (Each Output) | 100 mA | Storage Temperature Range | -65°C to +150°C |
| Oscillator Charging Current (Pin 6 or 7) | 5 mA | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Internal Power Dissipation (Note 1) | 1W | | |
| Operating Temperature Range | | | |
| LM1524 | -55°C to +125°C | | |
| LM2524/LM3524 | 0°C to +70°C | | |

Electrical Characteristics

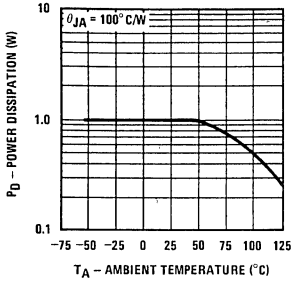
Unless otherwise stated, these specifications apply for $T_A = -55^\circ\text{C}$ to $+125^\circ\text{C}$ for the LM1524 and 0°C to $+70^\circ\text{C}$ for the LM2524 and LM3524, $V_{IN} = 20\text{V}$, and $f = 20\text{ kHz}$. Typical values other than temperature coefficients, are at $T_A = 25^\circ\text{C}$.

| PARAMETER | CONDITIONS | LM1524/ LM2524 | | | LM3524 | | | UNITS |
|-------------------------------------|--|-------------------|-----|-----|--------|-----|-----|----------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Reference Section | | | | | | | | |
| Output Voltage | | 4.8 | 5.0 | 5.2 | 4.6 | 5.0 | 5.4 | V |
| Line Regulation | $V_{IN} = 8-40\text{V}$ | | 10 | 20 | | 10 | 30 | mV |
| Load Regulation | $I_L = 0-20\text{ mA}$ | | 20 | 50 | | 20 | 50 | mV |
| Ripple Rejection | $f = 120\text{ Hz}, T_A = 25^\circ\text{C}$ | | 66 | | | 66 | | dB |
| Short-Circuit Output Current | $V_{REF} = 0, T_A = 25^\circ\text{C}$ | | 100 | | | 100 | | mA |
| Temperature Stability | Over Operating Temperature Range | | 0.3 | 1 | | 0.3 | 1 | % |
| Long Term Stability | $T_A = 25^\circ\text{C}$ | | 20 | | | 20 | | mV/khr |
| Oscillator Section | | | | | | | | |
| Maximum Frequency | $C_T = 0.001\ \mu\text{F}, R_T = 2\ \text{k}\Omega$ | | 350 | | | 350 | | kHz |
| Initial Accuracy | R_T and C_T constant | | 5 | | | 5 | | % |
| Frequency Change with Voltage | $V_{IN} = 8-40\text{V}, T_A = 25^\circ\text{C}$ | | | 1 | | | 1 | % |
| Frequency Change with Temperature | Over Operating Temperature Range | | | 2 | | | 2 | % |
| Output Amplitude (Pin 3) | $T_A = 25^\circ\text{C}$ | | 3.5 | | | 3.5 | | V |
| Output Pulse Width (Pin 3) | $C_T = 0.01\ \mu\text{F}, T_A = 25^\circ\text{C}$ | | 0.5 | | | 0.5 | | μs |
| Error Amplifier Section | | | | | | | | |
| Input Offset Voltage | $V_{CM} = 2.5\text{V}$ | | 0.5 | 5 | | 2 | 10 | mV |
| Input Bias Current | $V_{CM} = 2.5\text{V}$ | | 2 | 10 | | 2 | 10 | μA |
| Open Loop Voltage Gain | | 72 | 80 | | 60 | 80 | | dB |
| Common-Mode Input Voltage Range | $T_A = 25^\circ\text{C}$ | 1.8 | | 3.4 | 1.8 | | 3.4 | V |
| Common-Mode Rejection Ratio | $T_A = 25^\circ\text{C}$ | | 70 | | | 70 | | dB |
| Small Signal Bandwidth | $A_V = 0\ \text{dB}, T_A = 25^\circ\text{C}$ | | 3 | | | 3 | | MHz |
| Output Voltage Swing | $T_A = 25^\circ\text{C}$ | 0.5 | | 3.8 | 0.5 | | 3.8 | V |
| Comparator Section | | | | | | | | |
| Maximum Duty Cycle | % Each Output ON | 45 | | | 45 | | | % |
| Input Threshold (Pin 9) | Zero Duty Cycle | | 1 | | | 1 | | V |
| Input Threshold (Pin 9) | Maximum Duty Cycle | | 3.5 | | | 3.5 | | V |
| Input Bias Current | | | -1 | | | -1 | | μA |
| Current Limiting Section | | | | | | | | |
| Sense Voltage | $V(\text{Pin } 2) - V(\text{Pin } 1) \geq 50\text{ mV},$ $\text{Pin } 9 = 2\text{V}, T_A = 25^\circ\text{C}$ | 190 | 200 | 210 | 180 | 200 | 220 | mV |
| Sense Voltage T.C. | | | 0.2 | | | 0.2 | | $\text{mV}/^\circ\text{C}$ |
| Common-Mode Voltage | | -0.7 | | 1 | -0.7 | | 1 | V |
| Output Section (Each Output) | | | | | | | | |
| Collector-Emitter Voltage | | 40 | | | 40 | | | V |
| Collector Leakage Current | $V_{CE} = 40\text{V}$ | | 0.1 | 50 | | 0.1 | 50 | μA |
| Saturation Voltage | $I_C = 50\text{ mA}$ | | 1 | 2 | | 1 | 2 | V |
| Emitter Output Voltage | $V_{IN} = 20\text{V}, I_E = -250\ \mu\text{A}$ | 17 | 18 | | 17 | 18 | | V |
| Rise Time (10% to 90%) | $R_C = 2\ \text{k}\Omega, T_A = 25^\circ\text{C}$ | | 0.2 | | | 0.2 | | μs |
| Fall Time (90% to 10%) | $R_C = 2\ \text{k}\Omega, T_A = 25^\circ\text{C}$ | | 0.1 | | | 0.1 | | μs |
| Total Standby Current | $V_{IN} = 40\text{V}$, Pins 1, 4, 7, 8, 11 and 14 are grounded, Pin 2 = 2V, All Other Inputs and Outputs Open | | 5 | 10 | | 5 | 10 | mA |

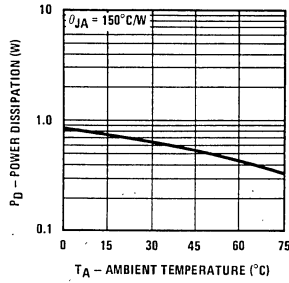
Note 1: For operation at elevated temperatures, devices in the J package must be derated based on a thermal resistance of $100^\circ\text{C}/\text{W}$, junction to ambient, and devices in the N package must be derated based on a thermal resistance of $150^\circ\text{C}/\text{W}$ junction to ambient.

Typical Performance Characteristics

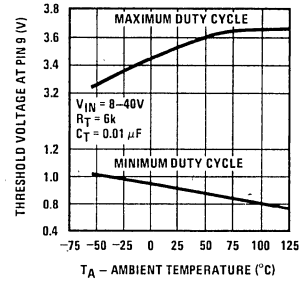
Maximum Average Power Dissipation (J Package)



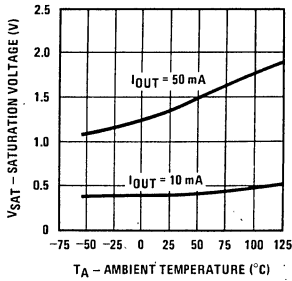
Maximum Average Power Dissipation (N Package)



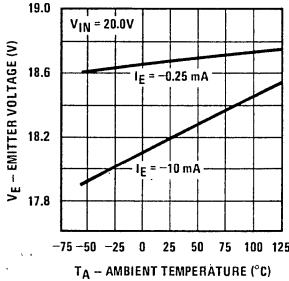
Maximum and Minimum Duty Cycle Threshold Voltage



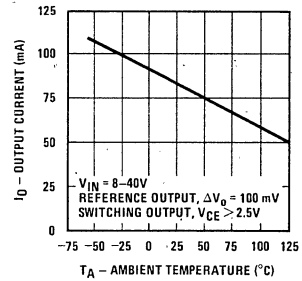
Output Transistor Saturation Voltage



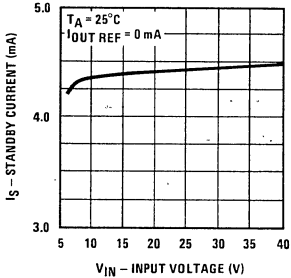
Output Transistor Emitter Voltage



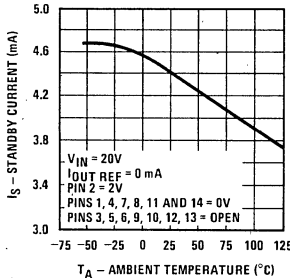
Reference and Switching Transistor Peak Output Current



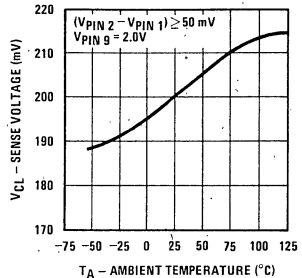
Standby Current



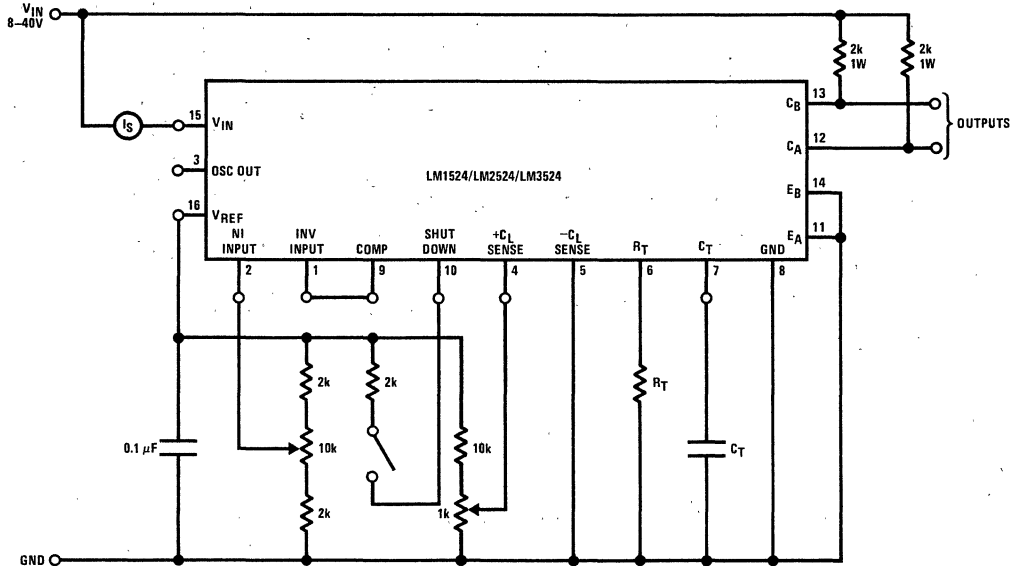
Standby Current



Current Limit Sense Voltage (VPin 4 - VPin 5)



Test Circuit

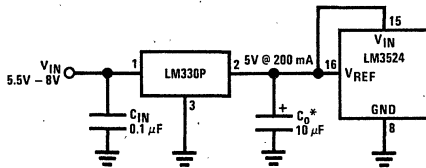


Functional Description

INTERNAL VOLTAGE REGULATOR

The LM3524 has on chip a 5V, 50 mA, short circuit protected voltage regulator. This voltage regulator provides a supply for all internal circuitry of the device and can be used as an external reference.

For input voltages of less than 8V the 5V output should be shorted to pin 15, V_{IN}, which disables the 5V regulator. With these pins shorted the input voltage must be limited to a maximum of 6V. If input voltages of 6-8V are to be used, a pre-regulator, as shown in Figure 1, must be added.



* Minimum C_O of 10 μF required for stability.

FIGURE 1

OSCILLATOR

The LM3524 provides a stable on-board oscillator. Its frequency is set by an external resistor, R_T and capacitor, C_T. A graph of R_T, C_T vs oscillator frequency is shown in Figure 2. The oscillator's output provides the signals for triggering an internal flip-flop, which directs the PWM information to the outputs, and a blanking pulse to turn off both outputs during transitions to ensure that cross conduction does not occur. The width of the blanking pulse, or dead time, is controlled by the value of C_T, as shown in Figure 3. The recommended

values of R_T are 1.8 kΩ to 100 kΩ, and for C_T, 0.001 μF to 0.1 μF.

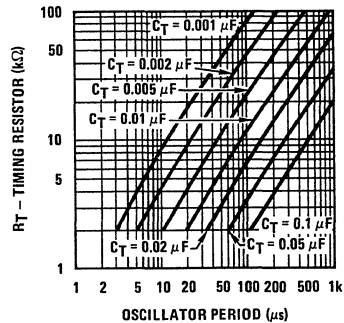


FIGURE 2

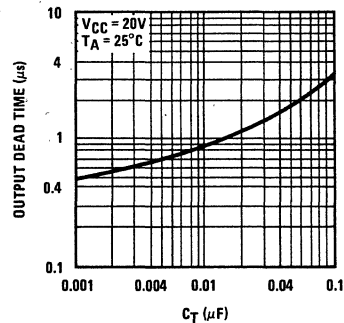


FIGURE 3

Functional Description (Continued)

ERROR AMPLIFIER

The error amplifier is a differential input, transconductance amplifier. Its gain, nominally 80 dB, is set by either feedback or output loading. This output loading can be done with either purely resistive or a combination of resistive and reactive components. A graph of the amplifier's gain vs output load resistance is shown in Figure 4.

The output of the amplifier, or input to the pulse width modulator, can be overridden easily as its output impedance is very high ($Z_o \approx 5 \text{ M}\Omega$). For this reason a DC voltage can be applied to pin 9 which will override the error amplifier and force a particular duty cycle to the outputs. An example of this could be a non-regulating motor speed control where a variable voltage was applied to pin 9 to control motor speed. A graph of the output duty cycle vs the voltage on pin 9 is shown in Figure 5.

The amplifier's inputs have a common-mode input range of 1.8V–3.4V. The on board regulator is useful for biasing the inputs to within this range.

CURRENT LIMITING

The function of the current limit amplifier is to override the error amplifier's output and take control of the pulse width. The output duty cycle drops to about 25% when a current limit sense voltage of 200 mV is applied between the $+C_L$ and $-C_L$ terminals. Increasing the sense voltage approximately 5% results in a 0% output duty cycle. Care should be taken to ensure the -0.7V to $+1.0\text{V}$ input common-mode range is not exceeded.

OUTPUT STAGES

The outputs of the LM3524 are NPN transistors, capable of a maximum current of 100 mA. These transistors are driven 180° out of phase and have non-committed open collectors and emitters as shown in Figure 6.

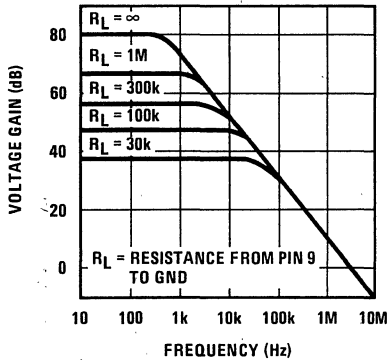


FIGURE 4

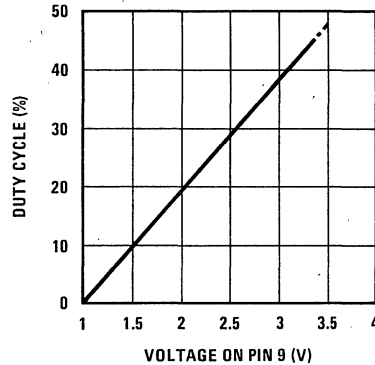


FIGURE 5

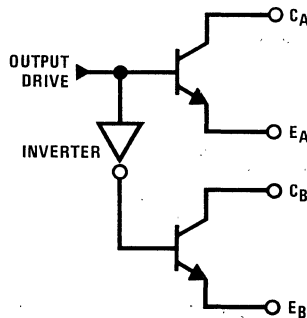


FIGURE 6

Typical Applications

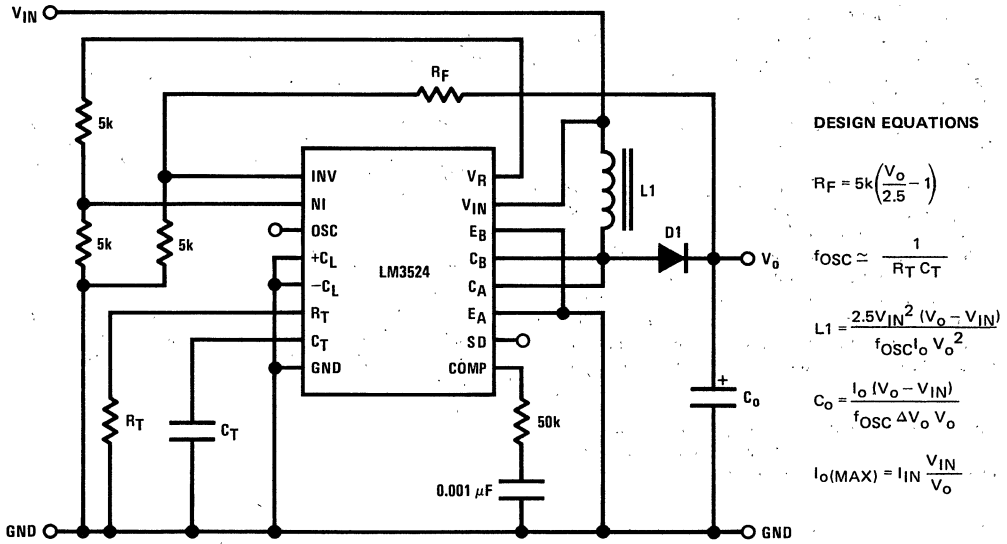


FIGURE 7. Positive Regulator, Step-Up Basic Configuration ($I_{IN(MAX)} = 80 \text{ mA}$)

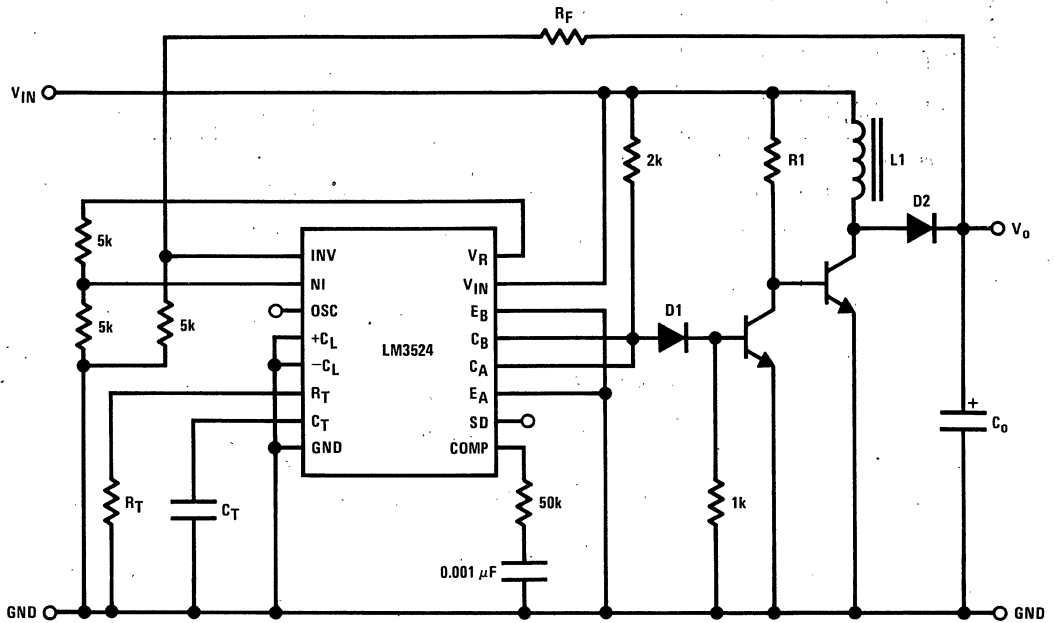


FIGURE 8. Positive Regulator, Step-Up Boosted Current Configuration

Typical Applications (Continued)

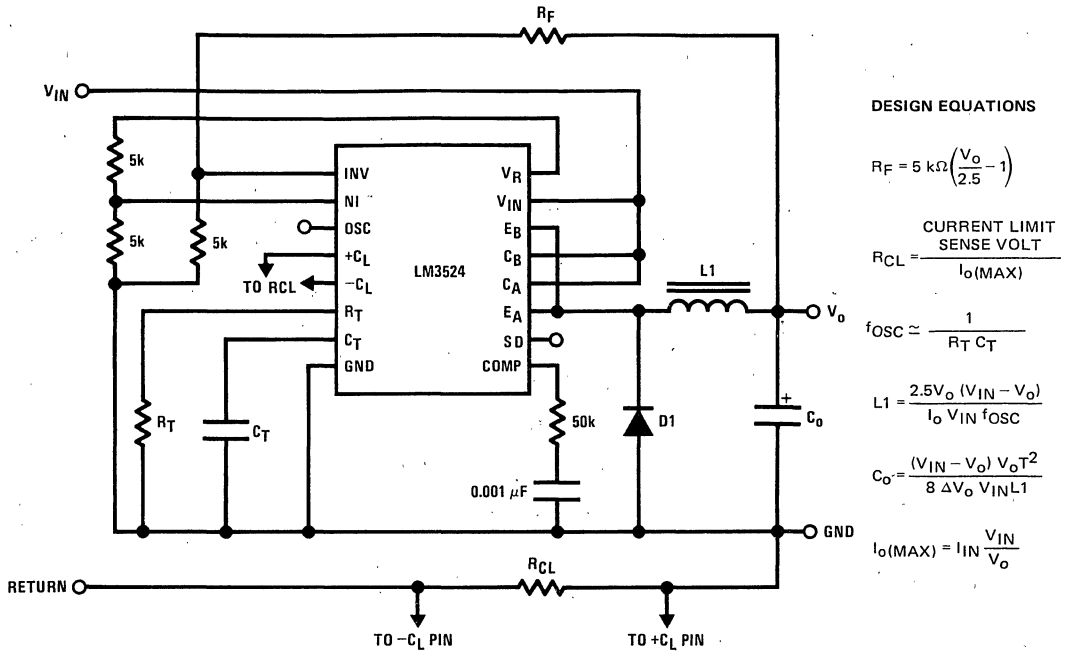


FIGURE 9. Positive Regulator, Step-Down Basic Configuration ($I_{IN}(\text{MAX}) = 80 \text{ mA}$)

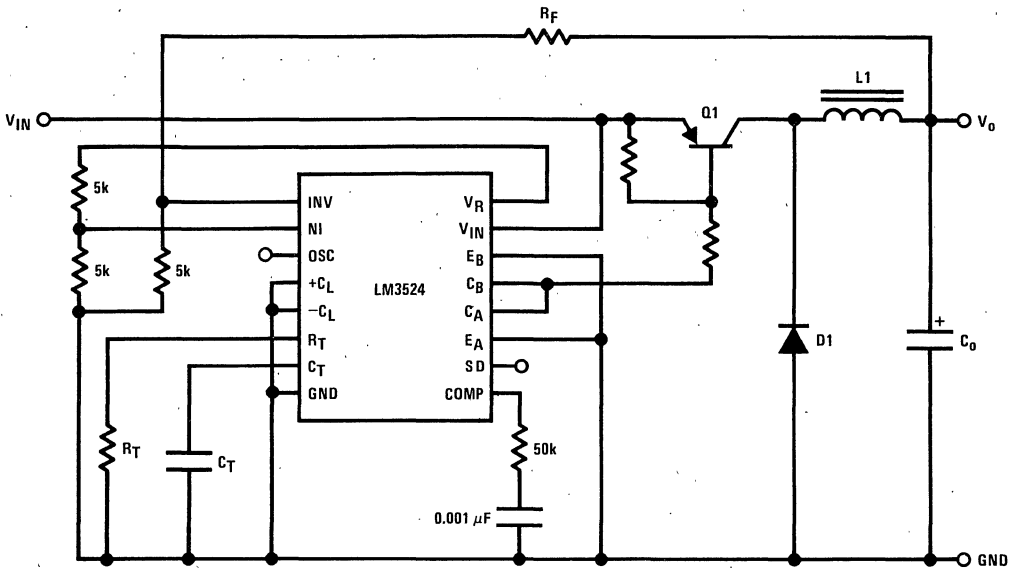
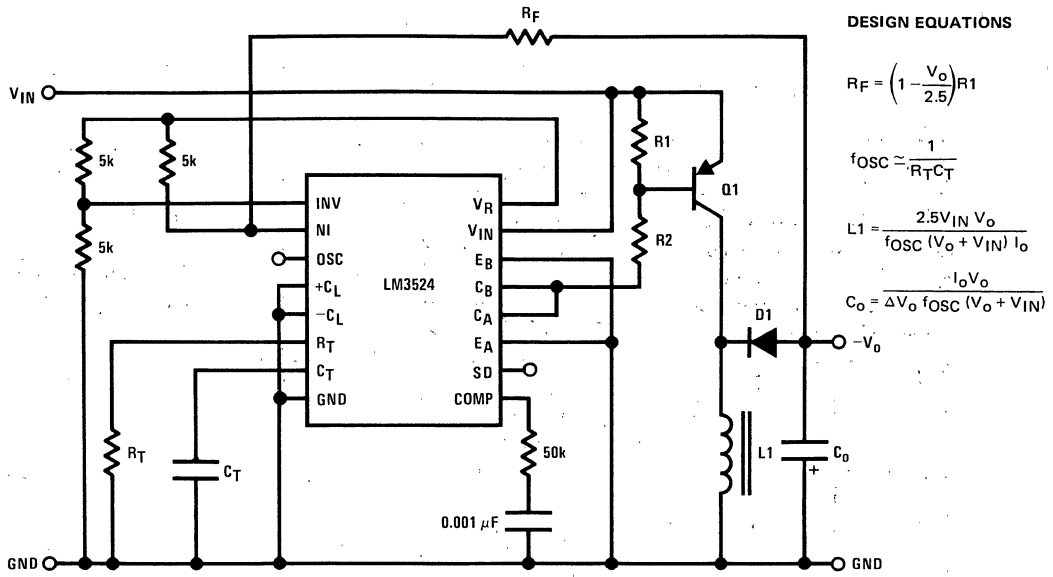


FIGURE 10. Positive Regulator, Step-Down Boosted Current Configuration

Typical Applications (Continued)



DESIGN EQUATIONS

$$R_F = \left(1 - \frac{V_o}{2.5V}\right) R_1$$

$$f_{OSC} \approx \frac{1}{R_T C_T}$$

$$L_1 = \frac{2.5V_{IN} V_o}{f_{OSC} (V_o + V_{IN}) I_o}$$

$$C_o = \frac{I_o V_o}{\Delta V_o f_{OSC} (V_o + V_{IN})}$$

FIGURE 11. Boosted Current Polarity Inverter

BASIC SWITCHING REGULATOR THEORY AND APPLICATIONS

The basic circuit of a step-down switching regulator circuit is shown in Figure 12, along with a practical circuit design using the LM3524 in Figure 15.

The circuit works as follows: Q1 is used as a switch, which has ON and OFF times controlled by the pulse width modulator. When Q1 is ON, power is drawn from VIN and supplied to the load through L1; VA is at approximately VIN, D1 is reverse biased, and Co is

charging. When Q1 turns OFF the inductor L1 will force VA negative to keep the current flowing in it, D1 will start conducting and the load current will flow through D1 and L1. The voltage at VA is smoothed by the L1, Co filter giving a clean DC output. The current flowing through L1 is equal to the nominal DC load current plus some ΔIL which is due to the changing voltage across it. A good rule of thumb is to set ΔILp-p ≈ 40% · Io.

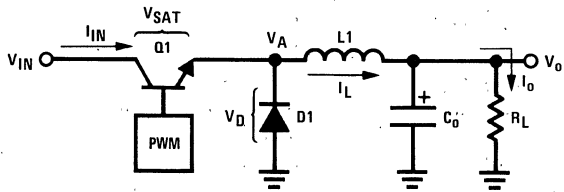


FIGURE 12. Basic Step-Down Switching Regulator

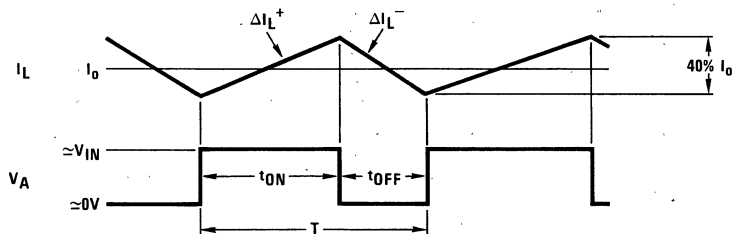


FIGURE 13

Typical Applications (Continued)

From the relation $V_L = L \frac{di}{dt}$, $\Delta I_L \approx \frac{V_L T}{L1}$

$$\Delta I_L^+ = \frac{(V_{IN} - V_o) t_{ON}}{L1}; \Delta I_L^- = \frac{V_o t_{OFF}}{L1}$$

Neglecting V_{SAT} , V_D , and setting $\Delta I_L^+ = \Delta I_L^-$;

$$V_o \approx V_{IN} \left(\frac{t_{ON}}{t_{OFF} + t_{ON}} \right) = V_{IN} \left(\frac{t_{ON}}{T} \right);$$

where $T =$ Total Period

The above shows the relation between V_{IN} , V_o and duty cycle.

$$I_{IN}(DC) = I_{OUT}(DC) \left(\frac{t_{ON}}{t_{ON} + t_{OFF}} \right);$$

as Q1 only conducts during t_{ON} .

$$P_{IN} = I_{IN}(DC) V_{IN} = (I_o(DC)) \left(\frac{t_{ON}}{t_{ON} + t_{OFF}} \right) V_{IN}$$

$$P_o = I_o V_o$$

The efficiency, η , of the circuit is:

$$\eta_{MAX} = \frac{P_o}{P_{IN}} = \frac{I_o V_o}{I_o \left(\frac{t_{ON}}{t_{ON} + t_{OFF}} \right) V_{IN} + \frac{V_{SAT} t_{ON} + V_D t_{OFF}}{T} I_o}$$

$$= \frac{V_o}{V_o + 1} \text{ for } V_{SAT} = V_D = 1V.$$

η_{MAX} will be further decreased due to switching losses in Q1. For this reason Q1 should be selected to have the maximum possible f_T , which implies very fast rise and fall times.

CALCULATING INDUCTOR L1

$$t_{ON} \approx \frac{(\Delta I_L^+) \cdot L1}{(V_{IN} - V_o)}, t_{OFF} = \frac{(\Delta I_L^-) \cdot L1}{V_o}$$

$$t_{ON} + t_{OFF} = T = \frac{(\Delta I_L^+) \cdot L1}{(V_{IN} - V_o)} + \frac{(\Delta I_L^-) \cdot L1}{V_o}$$

$$= \frac{0.4 I_o L1}{(V_{IN} - V_o)} + \frac{0.4 I_o L1}{V_o}$$

Since $\Delta I_L^+ = \Delta I_L^- = 0.4 I_o$

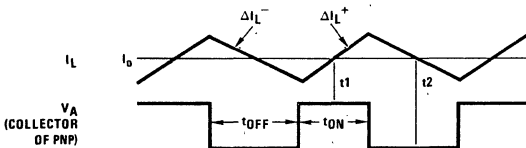


FIGURE 14

Solving the above for L1

$$L1 = \frac{2.5 V_o (V_{IN} - V_o)}{I_o V_{IN} f}$$

where L1 is in Henrys
f is switching frequency in Hz

CALCULATING OUTPUT FILTER CAPACITOR C_o:

Figure 14 shows L1's current with respect to Q1's t_{ON} and t_{OFF} times. This current must flow to the load and C_o . C_o 's current will then be the difference between I_L and I_o .

$$I_{C_o} = I_L - I_o$$

From Figure 14 it can be seen that current will be flowing into C_o for the second half of t_{ON} through the first half of t_{OFF} , or a time, $t_{ON}/2 + t_{OFF}/2$. The current flowing for this time is $\Delta I_L/4$. The resulting ΔV_c or ΔV_o is described by:

$$\Delta V_{op-p} = \frac{1}{C} \cdot \frac{\Delta I_L}{4} \cdot \left(\frac{t_{ON}}{2} + \frac{t_{OFF}}{2} \right)$$

$$= \frac{\Delta I_L}{4C} \left(\frac{t_{ON} + t_{OFF}}{2} \right)$$

Since $\Delta I_L = \frac{V_o(T - t_{ON})}{L1}$ and $t_{ON} = \frac{V_o T}{V_{IN}}$

$$\Delta V_{op-p} = \frac{V_o \left(T - \frac{V_o T}{V_{IN}} \right) \left(\frac{T}{2} \right)}{4C L1} = \frac{(V_{IN} - V_o) V_o T^2}{8V_{IN} C_o L1} \text{ or}$$

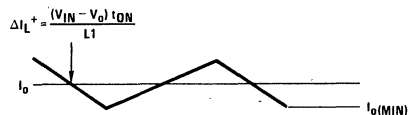
$$C_o = \frac{(V_{IN} - V_o) V_o T^2}{8 \Delta V_o V_{IN} L1}$$

where: C is in farads, T is $\frac{1}{\text{switching frequency}}$

ΔV_o is p-p output ripple

The inductor's current cannot be allowed to fall to zero, as this would cause the inductor to saturate. For this reason some minimum I_o is required as shown below:

$$I_o(MIN) = \frac{(V_{IN} - V_o) t_{ON}}{2L1} = \frac{(V_{IN} - V_o) V_o}{2f V_{IN} L1}$$



Typical Applications (Continued)

A complete step-down switching regulator schematic, using the LM3524, is illustrated in *Figure 15*. Transistors Q1 and Q2 have been added to boost the output to 1A. The 5V regulator of the LM3524 has been divided in half to bias the error amplifier's non-inverting input to within its common-mode range. Since each output transistor is on for half the period, actually 45%, they have been paralleled to allow longer possible duty cycles, up to 90%. This makes a lower possible input voltage. The output voltage is set by:

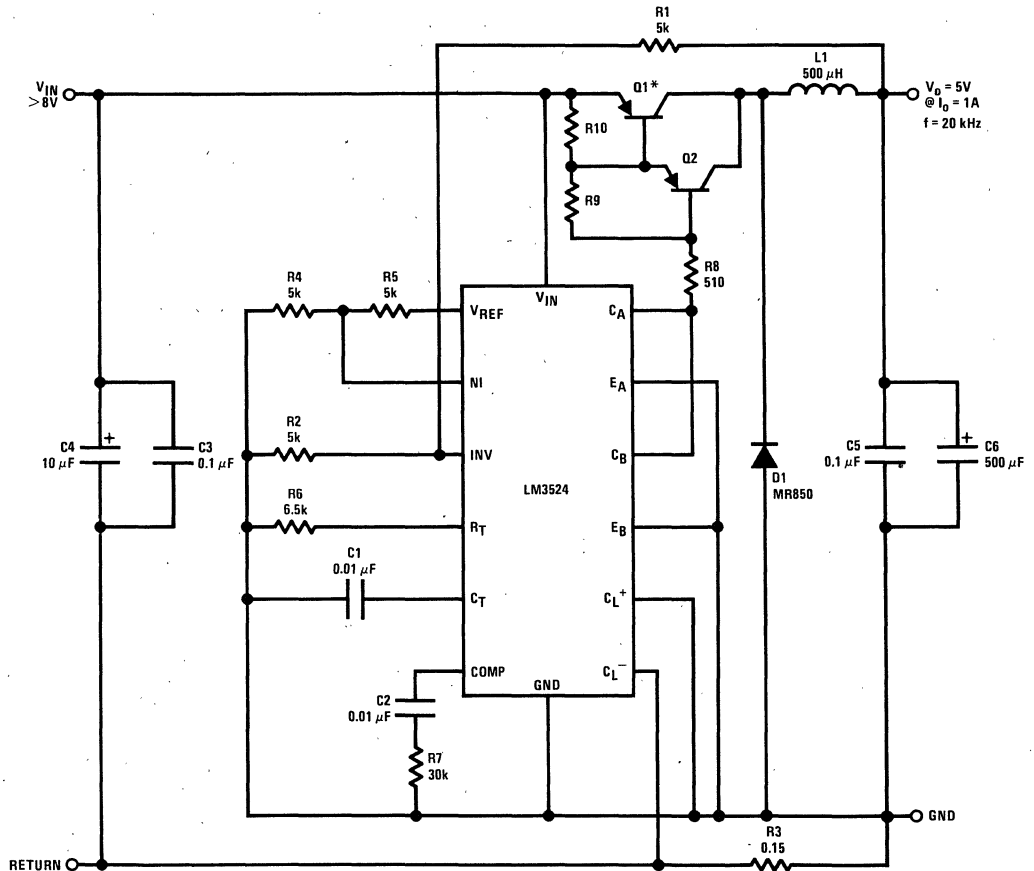
$$V_o = V_{NI} \left(1 + \frac{R_1}{R_2} \right)$$

where V_{NI} is the voltage at the error amplifier's non-inverting input.

Resistor R3 sets the current limit to:

$$\frac{200 \text{ mV}}{R_3} = \frac{200 \text{ mV}}{0.15} = 1.3 \text{ A.}$$

Figure 16 and *17* show a PC board layout and stuffing diagram for the 5V, 1A regulator of *Figure 15*. The regulator's performance is listed in *Table 1*.



* Mounted to Staver Heatsink No. V5-1.

Q1 = BD344, MJE171

Q2 = 2N5023

L1 = >40 turns No. 22 wire on Ferroxcube No. K300502 Torroid core.

FIGURE 15. 5V, 1 Amp Step-Down Switching Regulator

Typical Applications (Continued)

TABLE I

| PARAMETER | CONDITIONS | TYPICAL CHARACTERISTICS |
|-----------------------------|--------------------------------------|-------------------------|
| Output Voltage | $V_{IN} = 10V, I_o = 1A$ | 5V |
| Switching Frequency | $V_{IN} = 10V, I_o = 1A$ | 20 kHz |
| Short Circuit Current Limit | $V_{IN} = 10V$ | 1.3A |
| Load Regulation | $V_{IN} = 10V, I_o = 0.2 - 1A$ | 3 mV |
| Line Regulation | $\Delta V_{IN} = 10 - 20V, I_o = 1A$ | 6 mV |
| Efficiency | $V_{IN} = 10V, I_o = 1A$ | 80% |
| Output Ripple | $V_{IN} = 10V, I_o = 1A$ | 10 mVp-p |

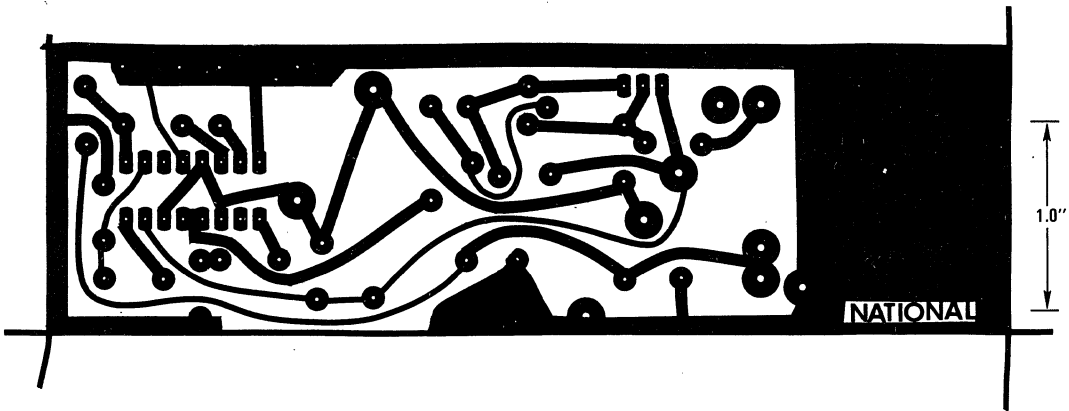


FIGURE 16. 5V, 1 Amp Switching Regulator, Foil Side

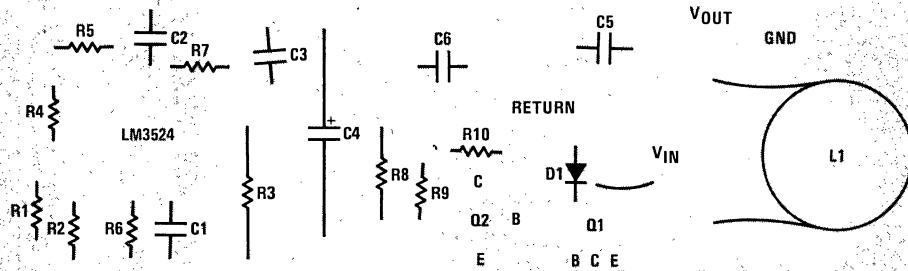


FIGURE 17. Stuffing Diagram, Component Side.

Typical Applications (Continued)

THE STEP-UP SWITCHING REGULATOR

Figure 18 shows the basic circuit for a step-up switching regulator. In this circuit Q1 is used as a switch to alternately apply V_{IN} across inductor L1. During the time, t_{ON} , Q1 is ON and energy is drawn from V_{IN} and stored in L1; D1 is reverse biased and I_O is supplied from the charge stored in C_O . When Q1 opens, t_{OFF} , voltage V1 will rise positively to the point where D1 turns

ON. The output current is now supplied through L1, D1 to the load and any charge lost from C_O during t_{ON} is replenished. Here also, as in the step-down regulator, the current through L1 has a DC component plus some ΔI_L . ΔI_L is again selected to be approximately 40% of I_L . Figure 19 shows the inductor's current in relation to Q1's ON and OFF times.

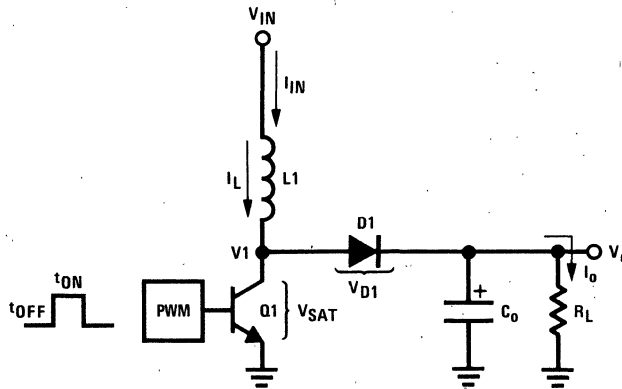


FIGURE 18. Basic Step-Up Switching Regulator

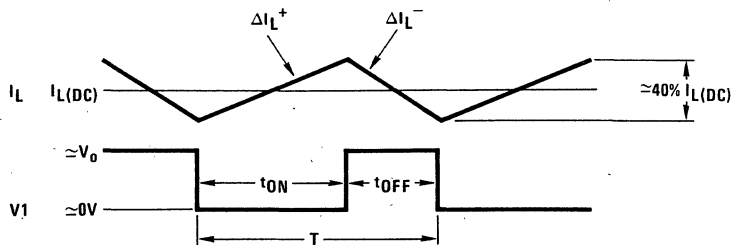


FIGURE 19

Typical Applications (Continued)

$$\text{From } \Delta I_L = \frac{V_L T}{L}, \quad \Delta I_L^+ \approx \frac{V_{IN} t_{ON}}{L1}$$

$$\text{and } \Delta I_L^- \approx \frac{(V_o - V_{IN}) t_{OFF}}{L1}$$

$$\text{Since } \Delta I_L^+ = \Delta I_L^-, \quad V_{IN} t_{ON} = V_o t_{OFF} - V_{IN} t_{OFF},$$

and neglecting V_{SAT} and V_{D1}

$$V_o \approx V_{IN} \left(1 + \frac{t_{ON}}{t_{OFF}} \right)$$

The above equation shows the relationship between V_{IN} , V_o and duty cycle.

In calculating input current $I_{IN(DC)}$, which equals the inductor's DC current, assume first 100% efficiency:

$$P_{IN} = I_{IN(DC)} V_{IN}$$

$$P_{OUT} = I_o V_o = I_o V_{IN} \left(1 + \frac{t_{ON}}{t_{OFF}} \right)$$

for $\eta = 100\%$, $P_{OUT} = P_{IN}$

$$I_o V_{IN} \left(1 + \frac{t_{ON}}{t_{OFF}} \right) = I_{IN(DC)} V_{IN}$$

$$I_{IN(DC)} = I_o \left(1 + \frac{t_{ON}}{t_{OFF}} \right)$$

This equation shows that the input, or inductor, current is larger than the output current by the factor $(1 + t_{ON}/t_{OFF})$. Since this factor is the same as the relation between V_o and V_{IN} , $I_{IN(DC)}$ can also be expressed as:

$$I_{IN(DC)} = I_o \left(\frac{V_o}{V_{IN}} \right)$$

So far it is assumed $\eta = 100\%$, where the actual efficiency or η_{MAX} will be somewhat less due to the saturation voltage of Q1 and forward voltage of D1. The internal power loss due to these voltages is the average I_L current flowing, or I_{IN} , through either V_{SAT} or V_{D1} . For $V_{SAT} = V_{D1} = 1V$ this power loss becomes $I_{IN(DC)} (1V)$. η_{MAX} is then:

$$\eta_{MAX} = \frac{P_o}{P_{IN}} = \frac{V_o I_o}{V_o I_o + I_{IN} (1V)} = \frac{V_o I_o}{V_o I_o + I_o \left(1 + \frac{t_{ON}}{t_{OFF}} \right)}$$

$$\text{From } V_o = V_{IN} \left(1 + \frac{t_{ON}}{t_{OFF}} \right),$$

$$\eta_{max} = \frac{V_{IN}}{V_{IN} + 1}$$

This equation assumes only DC losses, however η_{MAX} is further decreased because of the switching time of Q1 and D1.

In calculating the output capacitor C_o it can be seen that C_o supplies I_o during t_{ON} . The voltage change on C_o during this time will be some $\Delta V_c = \Delta V_o$ or the output ripple of the regulator. Calculation of C_o is:

$$\Delta V_o = \frac{I_o t_{ON}}{C_o} \text{ or } C_o = \frac{I_o t_{ON}}{\Delta V_o}$$

$$\text{From } V_o = V_{IN} \left(\frac{T}{t_{OFF}} \right); \quad t_{OFF} = \frac{V_{IN}}{V_o} T$$

$$\text{where } T = t_{ON} + t_{OFF} = \frac{1}{f}$$

$$t_{ON} = T - \frac{V_{IN}}{V_o} T = T \left(\frac{V_o - V_{IN}}{V_o} \right) \text{ therefore:}$$

$$C_o = \frac{I_o T \left(\frac{V_o - V_{IN}}{V_o} \right)}{\Delta V_o} = \frac{I_o (V_o - V_{IN})}{f \Delta V_o V_o}$$

where: C_o is in farads, f is the switching frequency, ΔV_o is the p-p output ripple

Calculation of inductor L1 is as follows:

$$L1 = \frac{V_{IN} t_{ON}}{\Delta I_L^+}, \text{ since during } t_{ON},$$

V_{IN} is applied across L1

$$\Delta I_{Lp-p} = 0.4 I_L = 0.4 I_{IN} = 0.4 I_o \left(\frac{V_o}{V_{IN}} \right), \text{ therefore:}$$

$$L1 = \frac{V_{IN} t_{ON}}{0.4 I_o \left(\frac{V_o}{V_{IN}} \right)} \text{ and since } t_{ON} = \frac{T(V_o - V_{IN})}{V_o}$$

$$L1 = \frac{2.5 V_{IN}^2 (V_o - V_{IN})}{f I_o V_o^2}$$

where : L1 is in henrys, f is the switching frequency in Hz

Typical Applications (Continued)

To apply the above theory, a complete step-up switching regulator is shown in *Figure 20*. Since V_{IN} is 5V, V_{REF} is tied to V_{IN} . The input voltage is divided by 2 to bias the error amplifier's inverting input. The output voltage is:

$$V_{OUT} = \left(1 + \frac{R_2}{R_1}\right) \cdot V_{INV} = 2.5 \cdot \left(1 + \frac{R_2}{R_1}\right)$$

The network D1, C1 forms a slow start circuit.

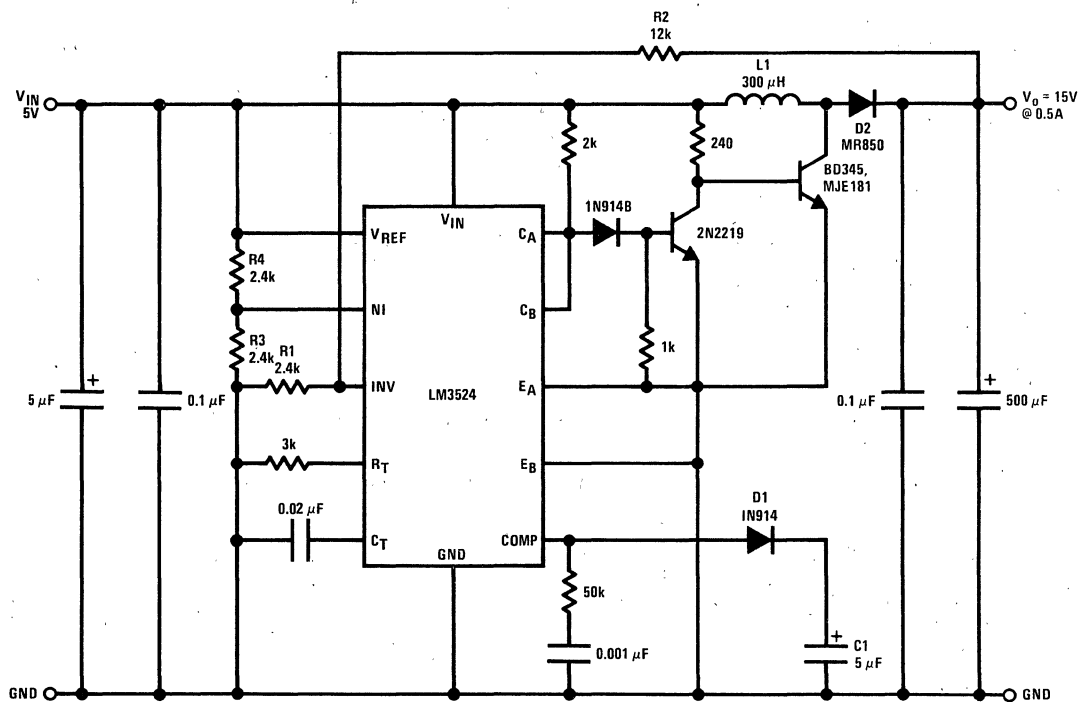
This holds the output of the error amplifier initially low thus reducing the duty-cycle to a minimum. Without the slow start circuit the inductor may saturate at turn-on because it has to supply high peak currents to charge the output capacitor from 0V. It should

also be noted that this circuit has no supply rejection. By adding a reference voltage at the non-inverting input to the error amplifier, see *Figure 21*, the input voltage variations are rejected.

The LM3524 can also be used in inductorless switching regulators. *Figure 22* shows a polarity inverter which if connected to *Figure 20* provides a -15V unregulated output.

MOTOR SPEED CONTROL

Figure 23 shows a regulating series DC motor speed control circuit using the LM3524 for the control and drive for the motor and the LM2907 as a speed sensor for the feedback network.



L1 = > 25 turns No. 24 wire on Ferroxcube No. K300502 Torroid core.

FIGURE 20. 15V, 0.5A Step-Up Switching Regulator

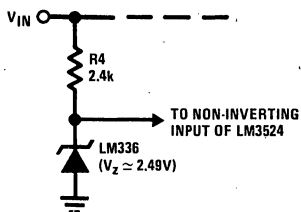


FIGURE 21

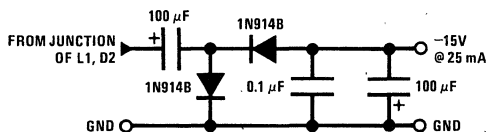


FIGURE 22

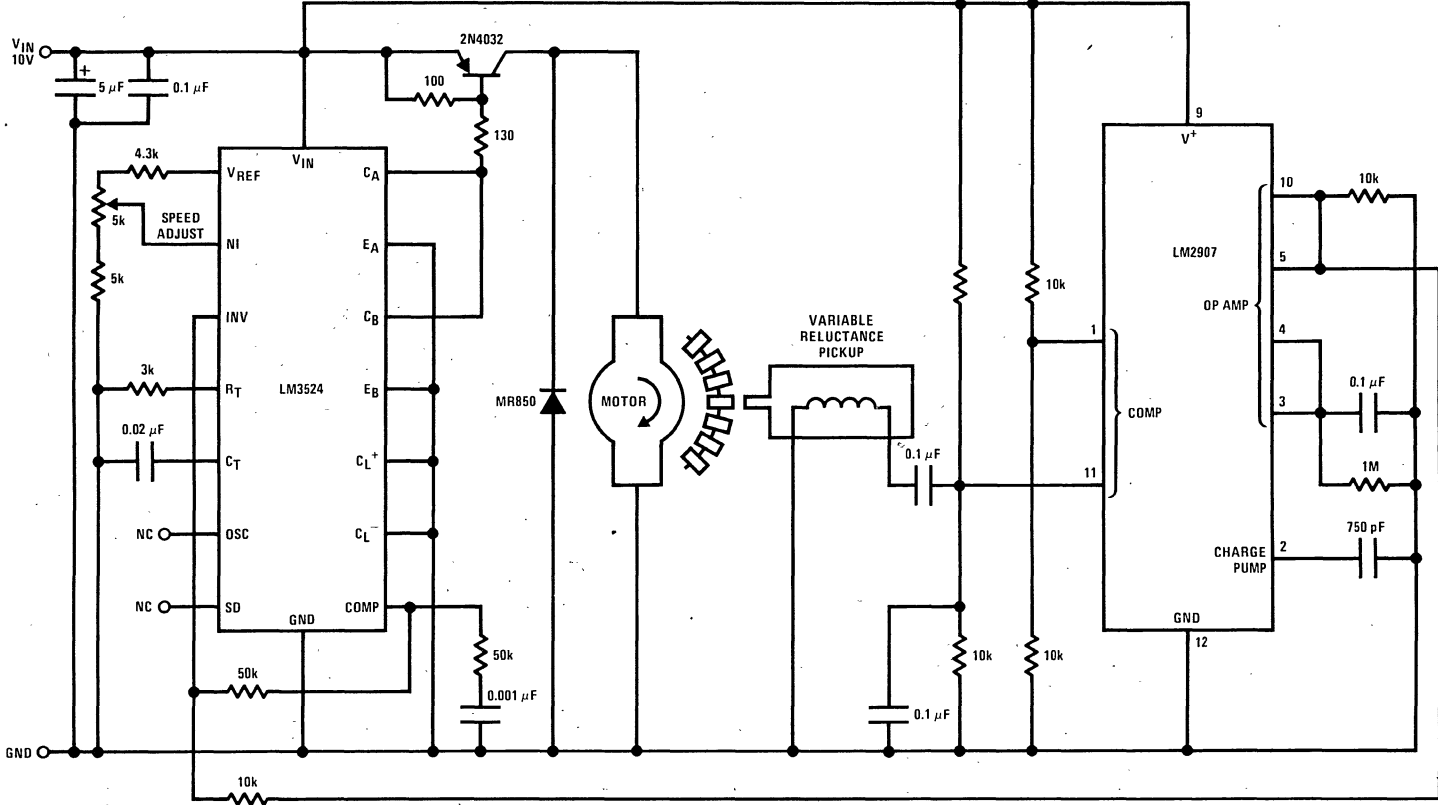


FIGURE 23. Motor Speed Control

LM2930 3-Terminal Positive Regulator

General Description

The LM2930 3-terminal positive voltage regulator features an ability to source 150mA of output current with an input-output differential of 0.6V or less. Efficient use of low input voltages obtained, for example, from an automotive battery during cold crank conditions, allows 5V circuitry to be properly powered with supply voltages as low as 5.6V. Familiar regulator features such as current limit and thermal overload protection are also provided.

Designed primarily for automotive applications, the LM2930 and all regulated circuitry are protected from reverse battery installations or 2 battery jumps. During line transients, such as a load dump (40V) when the input voltage to the regulator can momentarily exceed the specified maximum operating voltage, the regulator will automatically shut down to protect both internal circuits and the load. The LM2930 cannot be harmed by temporary mirror-image insertion.

Fixed outputs of 5V and 8V are available in the plastic TO-202 power package.

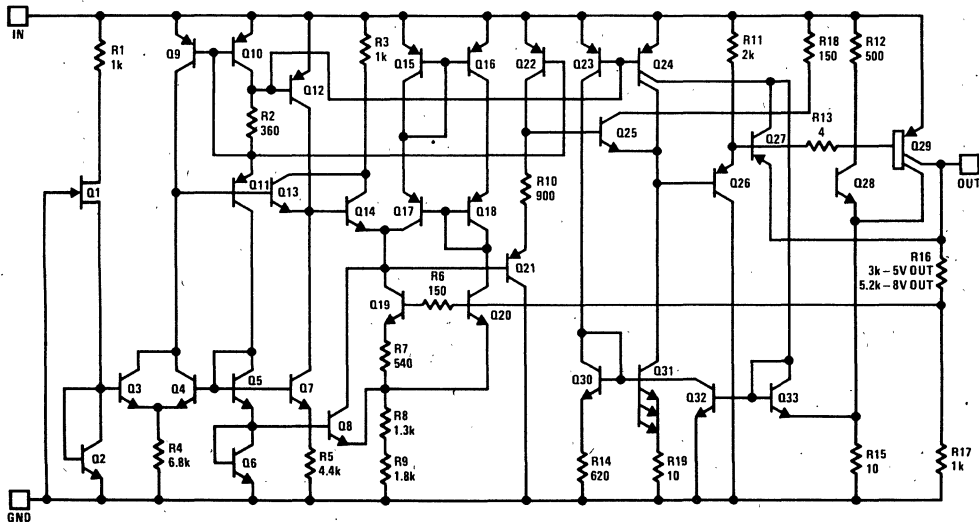
Features

- Input-output differential less than 0.6V
- Output current in excess of 150mA
- Reverse battery protection
- 40V load dump protection
- Internal short circuit current limit
- Internal thermal overload protection
- Mirror-image insertion protection

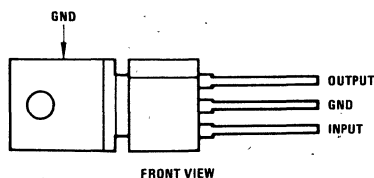
Voltage Range

| | |
|---------------|----|
| LM2930P-5.0TB | 5V |
| LM2930P-8.0TB | 8V |

Schematic and Connection Diagrams



Order Number
 LM2930-5.0 TB
 LM2930-8.0 TB
 See Package P03E



Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage | |
| Operating Range | 26V |
| Overvoltage Protection | 40V |
| Reverse Voltage (100 ms) | -12V |
| Reverse Voltage (DC) | -6V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range | -40 °C to +85 °C |
| Maximum Junction Temperature | 125 °C |
| Storage Temperature Range | -65 °C to +150 °C |
| Lead Temperature (Soldering, 10 seconds) | 230 °C |

Electrical Characteristics (Note 2)

LM2930P-5.0TB ($V_{IN} = 14V$, $I_O = 150\text{ mA}$, $T_J = 25^\circ\text{C}$, $C_2 = 10\ \mu\text{F}$, unless otherwise specified)

| Parameter | Conditions | Min | Typ | Max | Units |
|---|--|-----|------|-----|------------------|
| Output Voltage | $6V \leq V_{IN} \leq 26V$, $5\text{ mA} \leq I_O \leq 150\text{ mA}$, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$ | 4.5 | 5 | 5.5 | V |
| Line Regulation | $9V \leq V_{IN} \leq 16V$ $I_O = 5\text{ mA}$ | | 7 | 25 | mV |
| | $6V \leq V_{IN} \leq 26V$ $I_O = 5\text{ mA}$ | | 30 | 80 | mV |
| Load Regulation | $5\text{ mA} \leq I_O \leq 150\text{ mA}$ | | 14 | 50 | mV |
| Output Impedance | 100 mA_{DC} & 10 mA rms , 100 Hz-10 kHz | | 200 | | m Ω |
| Quiescent Current | $I_O = 10\text{ mA}$ | | 4 | 7 | mA |
| | $I_O = 150\text{ mA}$ | | 30 | 40 | mA |
| Output Noise Voltage | 10 Hz-100 kHz | | 140 | | μVrms |
| Long Term Stability | | | 20 | | mV/1000 hr |
| Ripple Rejection | $f_O = 120\text{ Hz}$ | | 56 | | dB |
| Dropout Voltage | $I_O = 150\text{ mA}$ | | 0.3 | 0.6 | V |
| Output Voltage Under Transient Conditions | $-12V \leq V_{IN} \leq 40V$, $R_L = 100\Omega$ | | -0.3 | 5.5 | V |

Electrical Characteristics (Note 2)

LM2930P-8.0TB ($V_{IN} = 14V$, $I_O = 150\text{ mA}$, $T_J = 25^\circ\text{C}$, $C_2 = 10\ \mu\text{F}$, unless otherwise specified)

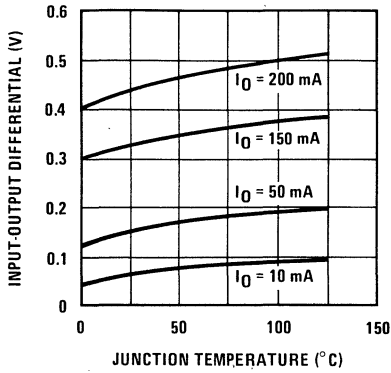
| Parameter | Conditions | Min | Typ | Max | Units |
|---|--|-----|------|-----|------------------|
| Output Voltage | $9.4V \leq V_{IN} \leq 26V$, $5\text{ mA} \leq I_O \leq 150\text{ mA}$, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$ | 7.2 | 8 | 8.8 | V |
| Line Regulation | $9.4V \leq V_{IN} \leq 16V$ $I_O = 5\text{ mA}$ | | 12 | 50 | mV |
| | $9.4V \leq V_{IN} \leq 26V$ $I_O = 5\text{ mA}$ | | 50 | 100 | mV |
| Load Regulation | $5\text{ mA} \leq I_O \leq 150\text{ mA}$ | | 25 | 50 | mV |
| Output Impedance | 100 mA_{DC} & 10 mA rms , 100 Hz-10 kHz | | 300 | | m Ω |
| Quiescent Current | $I_O = 10\text{ mA}$ | | 4 | 7 | mA |
| | $I_O = 150\text{ mA}$ | | 30 | 40 | mA |
| Output Noise Voltage | 10 Hz-100 kHz | | 170 | | μVrms |
| Long Term Stability | | | 30 | | mV/1000 hr |
| Ripple Rejection | $f_O = 120\text{ Hz}$ | | 52 | | dB |
| Dropout Voltage | $I_O = 150\text{ mA}$ | | 0.3 | 0.6 | V |
| Output Voltage Under Transient Conditions | $-12V \leq V_{IN} \leq 40V$, $R_L = 100\Omega$ | | -0.3 | 8.8 | V |

Note 1: Thermal resistance without a heat sink for junction to case temperature is 12 °C/W and for case to ambient temperature is 70 °C/W.

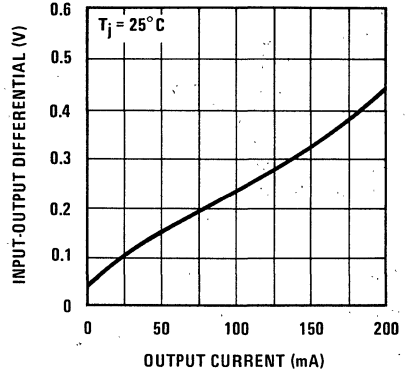
Note 2: All characteristics are measured with a capacitor across the input of 0.1 μF and a capacitor across the output of 10 μF . All characteristics except noise voltage and ripple rejection ratio are measured using pulse techniques ($t_W \leq 10\text{ ms}$, duty cycle $\leq 5\%$). Output voltage changes due to changes in internal temperature must be taken into account separately.

Typical Performance Characteristics

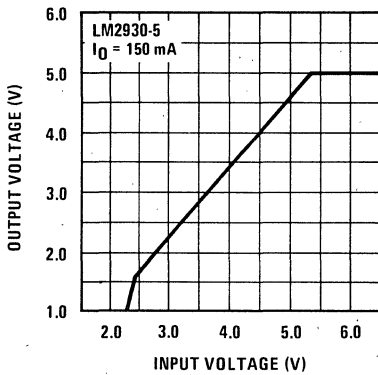
Dropout Voltage



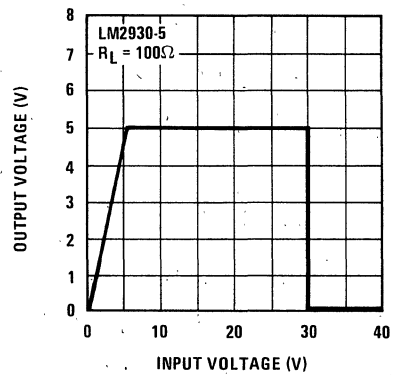
Dropout Voltage



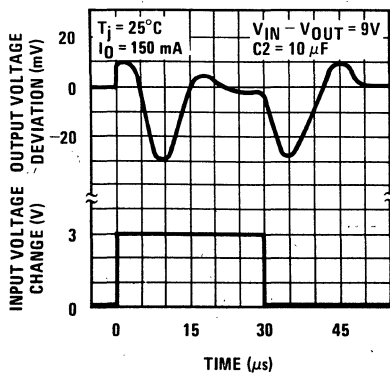
Low Voltage Behavior



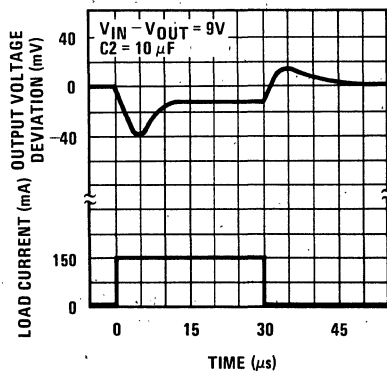
High Voltage Behavior



Line Transient Response

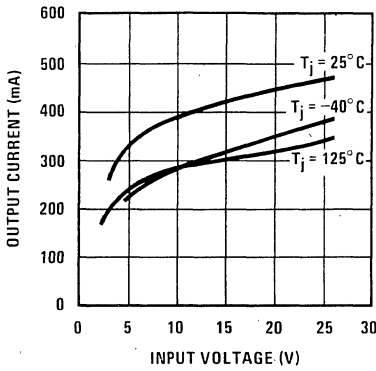


Load Transient Response

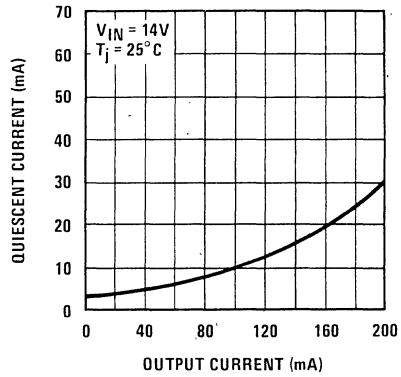


Typical Performance Characteristics (Continued)

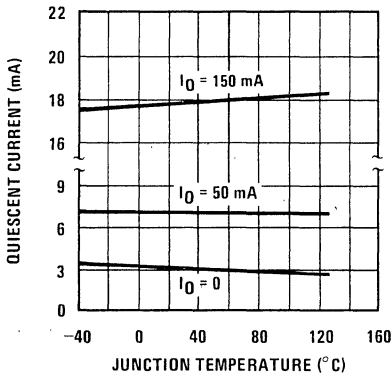
Peak Output Current



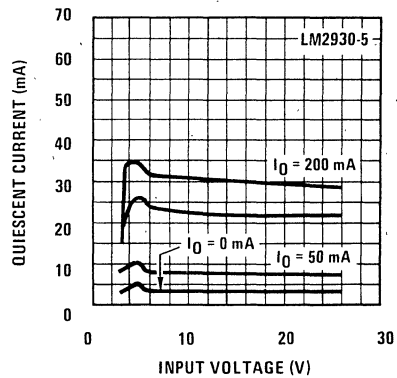
Quiescent Current



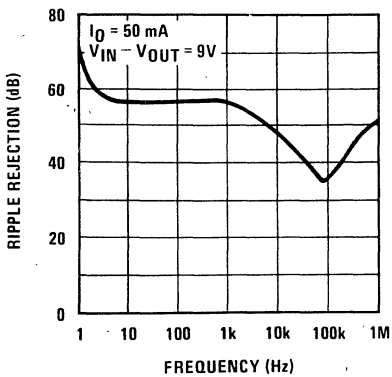
Quiescent Current



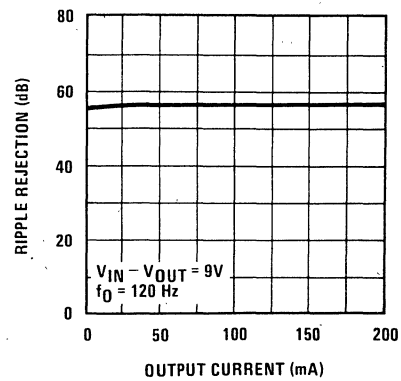
Quiescent Current



Ripple Rejection

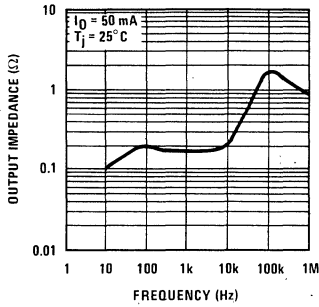


Ripple Rejection

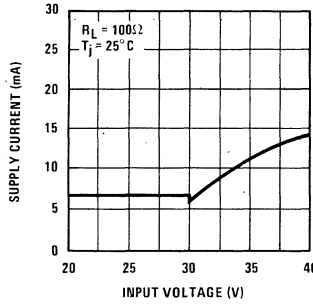


Typical Performance Characteristics (Continued)

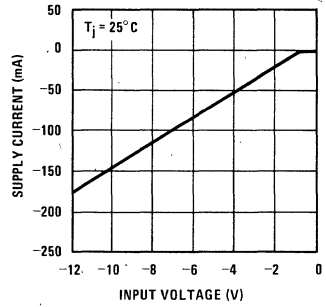
Output Impedance



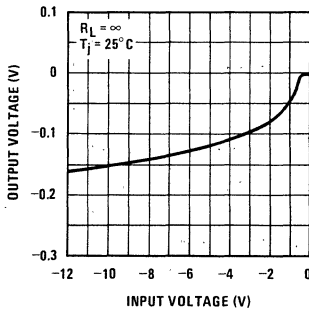
Overvoltage Supply Current



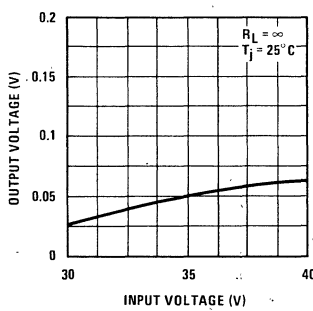
Reverse Supply Current



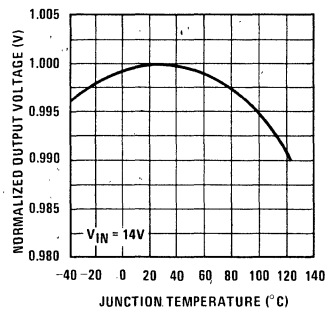
Output at Reverse Supply



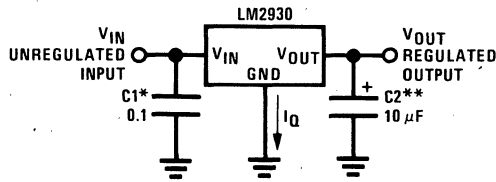
Output at Overvoltage



Output Voltage (Normalized to 1V at T_J = 25°C)



Typical Application



* Required if regulator is located far from power supply filter.
 ** C2 must be at least 10 μF to maintain stability. May be increased without bound. Locate as close as possible to regulator.

Definition of Terms

Dropout Voltage: The input-output voltage differential at which the circuit ceases to regulate against further reduction in input voltage. Measured when the output voltage has dropped 100 mV from the nominal value obtained at 14V input, dropout voltage is dependent upon load current and junction temperature.

Input Voltage: The DC voltage applied to the input terminals with respect to ground.

Input-Output Differential: The voltage difference between the unregulated input voltage and the regulated output voltage for which the regulator will operate.

Line Regulation: The change in output voltage for a change in the input voltage. The measurement is made under conditions of low dissipation or by using pulse techniques such that the average chip temperature is not significantly affected.

Load Regulation: The change in output voltage for a change in load current at constant chip temperature.

Long Term Stability: Output voltage stability under accelerated life-test conditions after 1000 hours with maximum rated voltage and junction temperature.

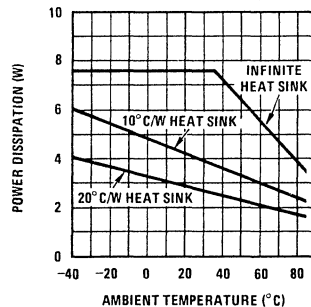
Output Noise Voltage: The rms AC voltage at the output, with constant load and no input ripple, measured over a specified frequency range.

Quiescent Current: That part of the positive input current that does not contribute to the positive load current. The regulator ground lead current.

Ripple Rejection: The ratio of the peak-to-peak input ripple voltage to the peak-to-peak output ripple voltage.

Temperature Stability of V_O : The percentage change in output voltage for a thermal variation from room temperature to either temperature extreme.

Maximum Power Dissipation





Voltage Regulators

LM78XX Series Voltage Regulators

General Description

The LM78XX series of three terminal regulators is available with several fixed output voltages making them useful in a wide range of applications. One of these is local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow these regulators to be used in logic systems, instrumentation, HiFi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators these devices can be used with external components to obtain adjustable voltages and currents.

The LM78XX series is available in an aluminum TO-3 package which will allow over 1.0A load current if adequate heat sinking is provided. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high for the heat sinking provided, the thermal shutdown circuit takes over preventing the IC from overheating.

Considerable effort was expended to make the LM78XX series of regulators easy to use and minimize the number

of external components. It is not necessary to bypass the output, although this does improve transient response. Input bypassing is needed only if the regulator is located far from the filter capacitor of the power supply.

For applications requiring other voltages, see LM117 data sheet.

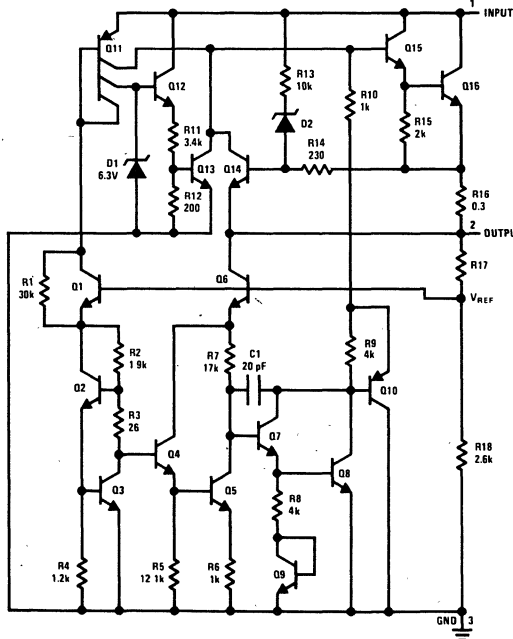
Features

- Output current in excess of 1A
- Internal thermal overload protection
- No external components required
- Output transistor safe area protection
- Internal short circuit current limit
- Available in the aluminum TO-3 package

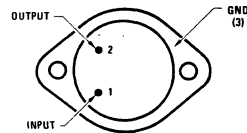
Voltage Range

| | |
|---------|-----|
| LM7805C | 5V |
| LM7812C | 12V |
| LM7815C | 15V |

Schematic and Connection Diagrams



**Metal Can Package
TO-3 (K)
Aluminum**



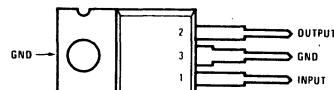
BOTTOM VIEW

Order Numbers:

- LM7805CK
- LM7812CK
- LM7815CK

See NS Package KC02A

**Plastic Package
TO-220 (T)**



TOP VIEW

Order Numbers:

- LM7805CT
- LM7812CT
- LM7815CT

See NS Package T03B

Absolute Maximum Ratings

| | |
|---|---|
| Input Voltage ($V_O = 5V, 12V$ and $15V$) | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range (T_A) | 0°C to $+70^\circ\text{C}$ |
| Maximum Junction Temperature | |
| (K Package) | 150°C |
| (T Package) | 125°C |
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | |
| TO-3 Package K | 300°C |
| TO-220 Package T | 230°C |

Electrical Characteristics LM78XXC (Note 2) $0^\circ\text{C} \leq T_j \leq 125^\circ\text{C}$ unless otherwise noted.

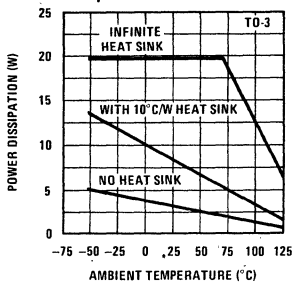
| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS | |
|---|--|---|-----|--------------------------------------|------------------------------------|---------------------------------------|---------------------------------------|---------------------------------------|---|---------------------------------------|----------------------------|----|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| V_O Output Voltage | $T_j = 25^\circ\text{C}, 5\text{ mA} \leq I_O \leq 1\text{ A}$ | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V | |
| | $P_D \leq 15\text{ W}, 5\text{ mA} \leq I_O \leq 1\text{ A}$ | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V | |
| | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | | ($7 \leq V_{\text{IN}} \leq 20$) | | | ($14.5 \leq V_{\text{IN}} \leq 27$) | | | ($17.5 \leq V_{\text{IN}} \leq 30$) | V | |
| ΔV_O Line Regulation | $I_O = 500\text{ mA}$ | $T_j = 25^\circ\text{C}$ | | 3 | 50 | | 4 | 120 | | 4 | 150 | mV |
| | | ΔV_{IN} | | ($7 \leq V_{\text{IN}} \leq 20$) | | ($14.5 \leq V_{\text{IN}} \leq 25$) | | ($17.5 \leq V_{\text{IN}} \leq 30$) | | | V | |
| | | $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ | | | 50 | | 120 | | 150 | | mV | |
| | $I_O \leq 1\text{ A}$ | ΔV_{IN} | | ($8 \leq V_{\text{IN}} \leq 20$) | | ($15 \leq V_{\text{IN}} \leq 27$) | | ($18.5 \leq V_{\text{IN}} \leq 30$) | | | V | |
| | | $T_j = 25^\circ\text{C}$ | | | 50 | | 120 | | 150 | | mV | |
| | | ΔV_{IN} | | ($7.3 \leq V_{\text{IN}} \leq 20$) | | ($14.6 \leq V_{\text{IN}} \leq 27$) | | ($17.7 \leq V_{\text{IN}} \leq 30$) | | | V | |
| ΔV_O Load Regulation | $T_j = 25^\circ\text{C}$ | $5\text{ mA} \leq I_O \leq 1.5\text{ A}$ | | 10 | 50 | | 12 | 120 | | 12 | 150 | mV |
| | | $250\text{ mA} \leq I_O \leq 750\text{ mA}$ | | | 25 | | 60 | | 75 | | mV | |
| | $5\text{ mA} \leq I_O \leq 1\text{ A}, 0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ | | | 50 | | 120 | | 150 | | mV | | |
| I_Q Quiescent Current | $I_O \leq 1\text{ A}$ | $T_j = 25^\circ\text{C}$ | | 8 | | 8 | | 8 | | 8 | mA | |
| | | $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ | | | 8.5 | | 8.5 | | 8.5 | | mA | |
| ΔI_Q Quiescent Current Change | $5\text{ mA} \leq I_O \leq 1\text{ A}$ | | | 0.5 | | 0.5 | | 0.5 | | 0.5 | mA | |
| | $T_j = 25^\circ\text{C}, I_O \leq 1\text{ A}$ | | | 1.0 | | 1.0 | | 1.0 | | 1.0 | mA | |
| | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | | ($7.5 \leq V_{\text{IN}} \leq 20$) | | ($14.8 \leq V_{\text{IN}} \leq 27$) | | ($17.9 \leq V_{\text{IN}} \leq 30$) | | | V | |
| | $I_O \leq 500\text{ mA}, 0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ | | | 1.0 | | 1.0 | | 1.0 | | 1.0 | mA | |
| V_N Output Noise Voltage | $T_A = 25^\circ\text{C}, 10\text{ Hz} \leq f \leq 100\text{ kHz}$ | | | 40 | | 75 | | 90 | | | μV | |
| | | | | 62 | 80 | 55 | 72 | 54 | 70 | | dB | |
| $\frac{\Delta V_{\text{IN}}}{\Delta V_{\text{OUT}}}$ Ripple Rejection | $f = 120\text{ Hz}$ | $I_O \leq 1\text{ A}, T_j = 25^\circ\text{C}$ or $I_O \leq 500\text{ mA}$ | | 62 | 80 | 55 | 72 | 54 | 70 | | dB | |
| | | $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}$ | | | | | | | | | dB | |
| | | $V_{\text{MIN}} \leq V_{\text{IN}} \leq V_{\text{MAX}}$ | | | ($8 \leq V_{\text{IN}} \leq 18$) | | ($15 \leq V_{\text{IN}} \leq 25$) | | ($18.5 \leq V_{\text{IN}} \leq 28.5$) | | V | |
| R_O | Dropout Voltage | $T_j = 25^\circ\text{C}, I_{\text{OUT}} = 1\text{ A}$ | | 2.0 | | 2.0 | | 2.0 | | | V | |
| | Output Resistance | $f = 1\text{ kHz}$ | | 8 | | 18 | | 19 | | | $\text{m}\Omega$ | |
| | Short-Circuit Current | $T_j = 25^\circ\text{C}$ | | 2.1 | | 1.5 | | 1.2 | | | A | |
| | Peak Output Current | $T_j = 25^\circ\text{C}$ | | 2.4 | | 2.4 | | 2.4 | | | A | |
| | Average TC of V_{OUT} | $0^\circ\text{C} \leq T_j \leq +125^\circ\text{C}, I_O = 5\text{ mA}$ | | 0.6 | | 1.5 | | 1.8 | | | $\text{mV}/^\circ\text{C}$ | |
| V_{IN} Input Voltage Required to Maintain Line Regulation | $T_j = 25^\circ\text{C}, I_O \leq 1\text{ A}$ | | 7.3 | | 14.6 | | 17.7 | | | V | | |

Note 1: Thermal resistance of the TO-3 package (K, KC) is typically $4^\circ\text{C}/\text{W}$ junction to case and $35^\circ\text{C}/\text{W}$ case to ambient. Thermal resistance of the TO-220 package (T) is typically $4^\circ\text{C}/\text{W}$ junction to case and $50^\circ\text{C}/\text{W}$ case to ambient.

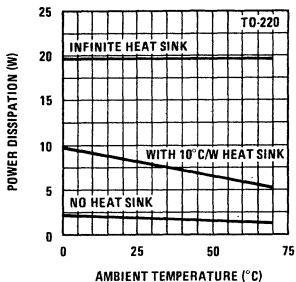
Note 2: All characteristics are measured with capacitor across the input of $0.22\ \mu\text{F}$, and a capacitor across the output of $0.1\ \mu\text{F}$. All characteristics except noise voltage and ripple rejection ratio are measured using pulse techniques ($t_W \leq 10\text{ ms}$, duty cycle $\leq 5\%$). Output voltage changes due to changes in internal temperature must be taken into account separately.

Typical Performance Characteristics

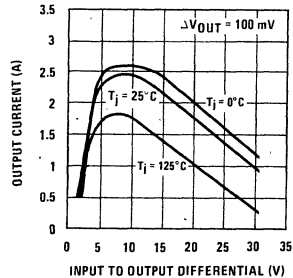
Maximum Average Power Dissipation



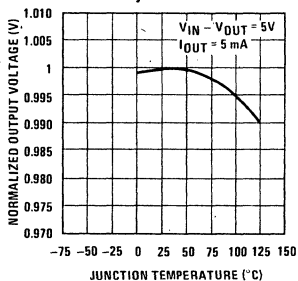
Maximum Average Power Dissipation



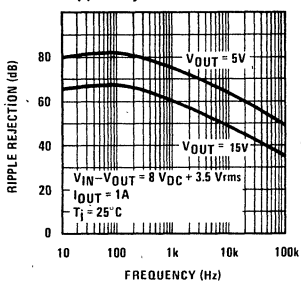
Peak Output Current



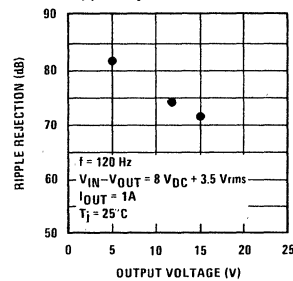
Output Voltage (Normalized to 1V at T_J = 25°C)



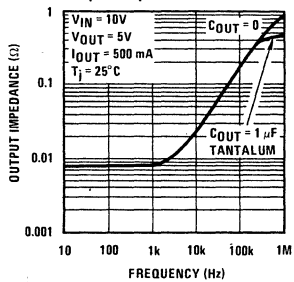
Ripple Rejection



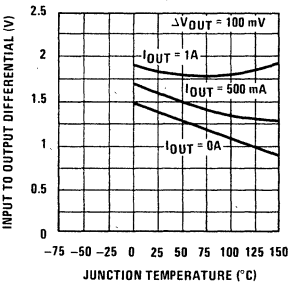
Ripple Rejection



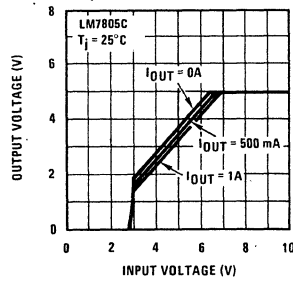
Output Impedance



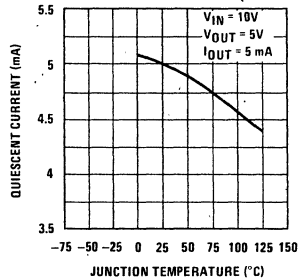
Dropout Voltage



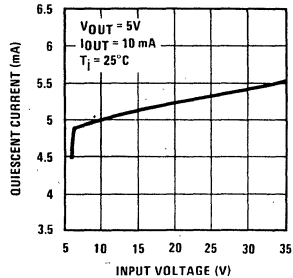
Dropout Characteristics



Quiescent Current



Quiescent Current



LM78LXX Series 3-Terminal Positive Regulators

General Description

The LM78LXX series of three terminal positive regulators is available with several fixed output voltages making them useful in a wide range of applications. When used as a zener diode/resistor combination replacement, the LM78LXX usually results in an effective output impedance improvement of two orders of magnitude, and lower quiescent current. These regulators can provide local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow the LM78LXX to be used in logic systems, instrumentation, HiFi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators these devices can be used with external components to obtain adjustable voltages and currents.

The LM78LXX is available in the metal three lead TO-39 (H) and the plastic TO-92 (Z). With adequate heat sinking the regulator can deliver 100 mA output current. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high, for the heat sinking provided, the thermal shutdown circuit takes over preventing the IC from overheating.

For applications requiring other voltages, see LM117 data sheet.

Features

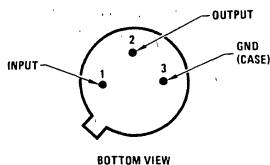
- Output voltage tolerances of $\pm 5\%$ (LM78LXXAC) and $\pm 10\%$ (LM78LXXC) over the temperature range
- Output current of 100 mA
- Internal thermal overload protection
- Output transistor safe area protection
- Internal short circuit current limit
- Available in plastic TO-92 and metal TO-39 low profile packages

Voltage Range

| | |
|---------|-----|
| LM78L05 | 5V |
| LM78L12 | 12V |
| LM78L15 | 15V |

Connection Diagrams

Metal Can Package

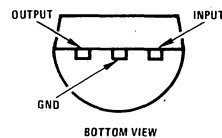


Order Numbers:

| | |
|------------|-----------|
| LM78L05ACH | LM78L05CH |
| LM78L12ACH | LM78L12CH |
| LM78L15ACH | LM78L15CH |

See NS Package H03A

Plastic Package



Order Numbers:

| | |
|------------|-----------|
| LM78L05ACZ | LM78L05CZ |
| LM78L12ACZ | LM78L12CZ |
| LM78L15ACZ | LM78L15CZ |

See NS Package Z03A

Absolute Maximum Ratings

| | | |
|--|-----------------------|--------------------|
| Input Voltage | $V_O = 5V$ | 30V |
| | $V_O = 12V$ and $15V$ | 35V |
| Internal Power Dissipation (Note 1) | | Internally Limited |
| Operating Temperature Range | | 0°C to +70°C |
| Maximum Junction Temperature | | 125°C |
| Storage Temperature Range | | |
| Metal Can (H Package) | | -65°C to +150°C |
| Molded TO-92 (Z Package) | | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | | 300°C |

LM78LXXAC Electrical Characteristics (Note 2)

$T_J = 0^\circ\text{C}$ to $+125^\circ\text{C}$, $I_O = 40\text{ mA}$, $C_{IN} = 0.33\mu\text{F}$, $C_O = 0.1\mu\text{F}$ (unless noted)

| LM78LXXAC OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS |
|--|--|------|---------------------|---------------------|------------------------|----------------------|------------------------|------------------------|------|-------------|------------------------|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage (Note 4) | $T_J = 25^\circ\text{C}$ | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V |
| | $1\text{ mA} \leq I_O \leq 70\text{ mA}$ | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | .V |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ and $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V |
| | | | | | (7 ≤ V_{IN} ≤ 20) | | | (14.5 ≤ V_{IN} ≤ 27) | | | (17.5 ≤ V_{IN} ≤ 30) |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$ | | 10 | 54 | | 20 | 110 | | 25 | 140 | mV |
| | | | (8 ≤ V_{IN} ≤ 20) | | (16 ≤ V_{IN} ≤ 27) | | (20 ≤ V_{IN} ≤ 30) | | | | V |
| | | | 18 | 75 | | 30 | 180 | | 37 | 250 | mV |
| | | | (7 ≤ V_{IN} ≤ 20) | | (14.5 ≤ V_{IN} ≤ 27) | | (17.5 ≤ V_{IN} ≤ 30) | | | V | |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | 5 | 30 | | 10 | 50 | | 12 | 75 | mV | |
| | $T_J = 25^\circ\text{C}$, $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | 20 | 60 | | 30 | 100 | | 35 | 150 | mV | |
| ΔV_O Long Term Stability | | | 12 | | | 24 | | | 30 | mV/1000 hrs | |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | 3 | 5 | | 3 | 5 | | 3.1 | 5 | mA |
| | $T_J = 125^\circ\text{C}$ | | | 4.7 | | | 4.7 | | | 4.7 | |
| ΔI_Q Quiescent Current Change | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | | 0.1 | | | 0.1 | | | 0.1 | mA |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | | 1.0 | | | 1.0 | | | 1.0 | mA |
| | | | | (8 ≤ V_{IN} ≤ 20) | | (16 ≤ V_{IN} ≤ 27) | | (20 ≤ V_{IN} ≤ 30) | | | V |
| V_n Output Noise Voltage | $T_J = 25^\circ\text{C}$, (Note 3) $f = 10\text{ Hz} - 10\text{ kHz}$ | | 40 | | | 80 | | | 90 | μV | |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $f = 120\text{ Hz}$ | 47 | 62 | | 40 | 54 | | 37 | 51 | | dB |
| | | | (8 ≤ V_{IN} ≤ 16) | | (15 ≤ V_{IN} ≤ 25) | | (20 ≤ V_{IN} ≤ 28.5) | | | | V |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ\text{C}$ | | 7 | | | 14.5 | | | 17.5 | | V |

Note 1: Thermal resistance of the Metal Can Package (H) without a heat sink is 15°C/W junction to case and 140°C/W junction to ambient. Thermal resistance of the TO-92 package is 180°C/W junction to ambient with 0.4" leads from a PC board and 160°C/W junction to ambient with 0.125" lead length to a PC board.

Note 2: The maximum steady state usable output current and input voltage are very dependent on the heat sinking and/or lead length of the package. The data above represent pulse test conditions with junction temperatures as indicated at the initiation of test.

Note 3: Recommended minimum load capacitance of 0.01μF to limit high frequency noise bandwidth.

Note 4: The temperature coefficient of V_{OUT} is typically within ±0.01% $V_O/^\circ\text{C}$.

Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage $V_O = 5V$ | 30V |
| $V_O = 12V$ and $15V$ | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range | 0°C to +70°C |
| Maximum Junction Temperature | 125°C |
| Storage Temperature Range | |
| Metal Can (H Package) | -65°C to +150°C |
| Molded TO-92 | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

LM78LXX Electrical Characteristics (Note 2)

$T_J = 0^\circ\text{C}$ to $+125^\circ\text{C}$, $I_O = 40\text{ mA}$, $C_{IN} = 0.33\mu\text{F}$, $C_O = 0.1\mu\text{F}$ (unless noted)

| LM78LXX OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS |
|---|---|---------------------|--|------------------------|----------------------|------------------------|--------------------------|------|----------------------|------|---------------|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage (Note 4) | $T_J = 25^\circ\text{C}$ | 4.6 | 5 | 5.4 | 11.1 | 12 | 12.9 | 13.8 | 15 | 16.2 | V |
| | $1\text{ mA} \leq I_O \leq 70\text{ mA}$ or | 4.5 | | 5.5 | 10.8 | | 13.2 | 13.5 | | 16.5 | V |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ and ΔV_{IN} | (7 ≤ V_{IN} ≤ 20) | | | | (14.5 ≤ V_{IN} ≤ 27) | | | (18 ≤ V_{IN} ≤ 30) | | V |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$ | | 10 | 150 | | 20 | 200 | | 25 | 250 | mV |
| | | | (8 ≤ V_{IN} ≤ 20) | | (16 ≤ V_{IN} ≤ 27) | | (20 ≤ V_{IN} ≤ 30) | | | | V |
| | | | 18 | 200 | | 30 | 250 | | 30 | 300 | mV |
| | | (7 ≤ V_{IN} ≤ 20) | | (14.5 ≤ V_{IN} ≤ 27) | | (18 ≤ V_{IN} ≤ 30) | | | | V | |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | 5 | 30 | | 10 | 50 | | 12 | 75 | mV |
| | | | $T_J = 25^\circ\text{C}$, $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | | 20 | 60 | | 30 | 100 | | 35 |
| ΔV_O Long Term Stability | | | 12 | | | 24 | | | 30 | | mV/1000 hrs |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | 3 | 6 | | 3 | 6.5 | | 3.1 | 6.5 | mA |
| | $T_J = 125^\circ\text{C}$ | | | 5.5 | | | 6 | | | 6 | |
| ΔI_Q Quiescent Current Change | $T_J = 25^\circ\text{C}$, $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | | 0.2 | | 0.2 | | | 0.2 | | mA |
| | | | | 1.5 | | 1.5 | | 1.5 | | 1.5 | mA |
| | $T_J = 25^\circ\text{C}$ | | (8 ≤ V_{IN} ≤ 20) | | | (16 ≤ V_{IN} ≤ 27) | | | (20 ≤ V_{IN} ≤ 30) | | V |
| \dot{V}_n Output Noise Voltage | $T_J = 25^\circ\text{C}$, (Note 3) $f = 10\text{ Hz} - 10\text{ kHz}$ | | 40 | | | 80 | | | 90 | | μV |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $f = 125\text{ Hz}$ | | 40 | 60 | | 36 | 52 | | 33 | 49 | dB |
| | | | (8 ≤ V_{IN} ≤ 18) | | (15 ≤ V_{IN} ≤ 25) | | (18.5 ≤ V_{IN} ≤ 28.5) | | | | V |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ\text{C}$ | | 7 | | | 14.5 | | | 18 | | V |

Note 1: Thermal resistance of the Metal Can Package (H) without a heat sink is 15°C/W junction to case and 140°C/W junction to ambient. Thermal resistance of the TO-92 package is 180°C/W junction to ambient with 0.4" leads from a PC board and 160°C/W junction to ambient with 0.125" lead length to a PC board.

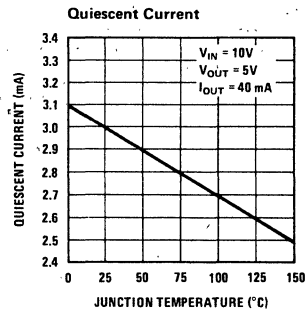
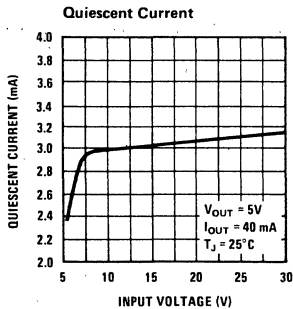
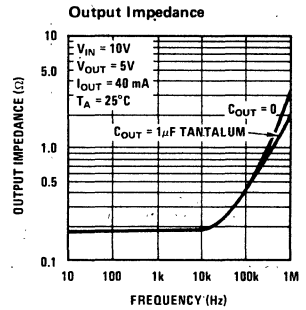
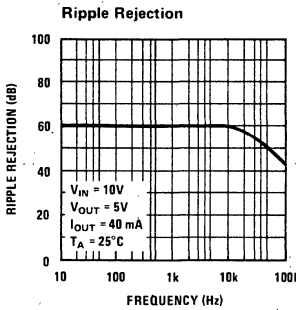
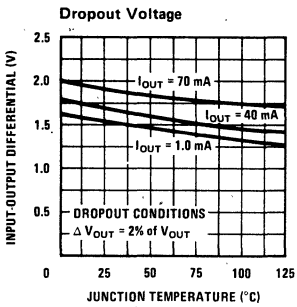
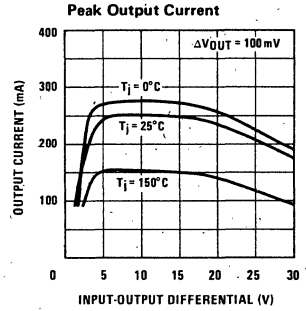
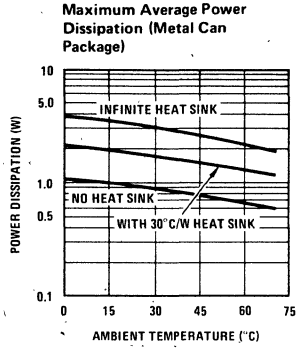
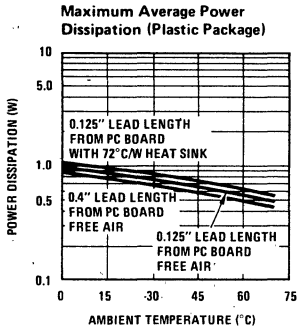
Note 2: The maximum steady state usable output current and input voltage are very dependent on the heat sinking and/or lead length of the package. The data above represent pulse test conditions with junction temperatures as indicated at the initiation of test.

Note 3: Recommended minimum load capacitance of 0.01μF to limit high frequency noise bandwidth.

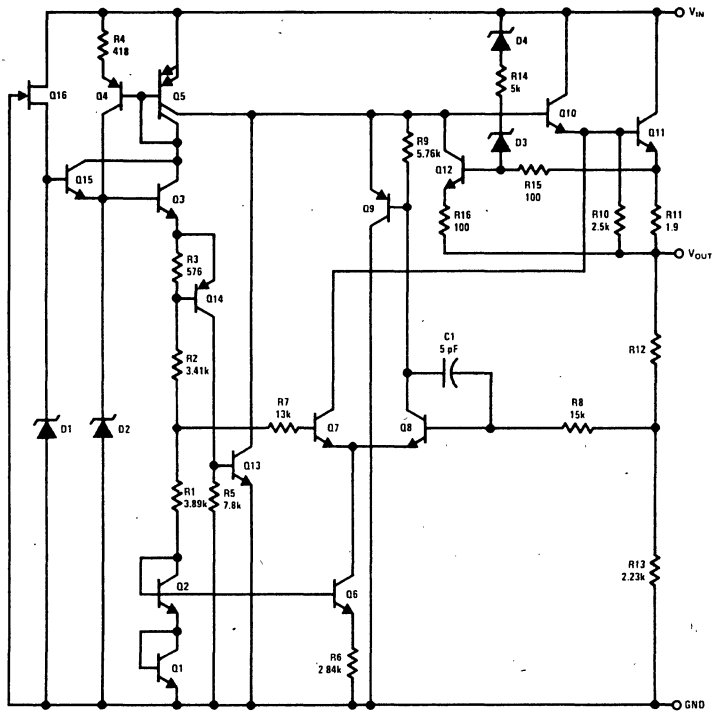
Note 4: The temperature coefficient of V_{OUT} is typically within ±0.01% $V_O/^\circ\text{C}$.

1

Typical Performance Characteristics

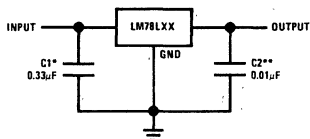


Equivalent Circuit



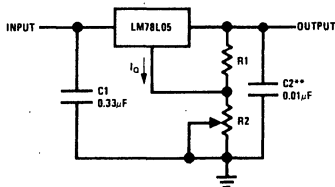
LM78LXX

Typical Applications



*Required if the regulator is located far from the power supply filter.
 **See Note 3 in the electrical characteristics table.

Fixed Output Regulator

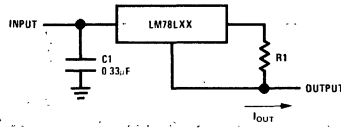


$$V_{OUT} = 5V + (5V/R1 + I_Q) R2$$

$$5V/R1 > 3 I_Q, \text{ load regulation } (L_L) \approx [(R1 + R2)/R1] (L_L \text{ of LM78L05})$$

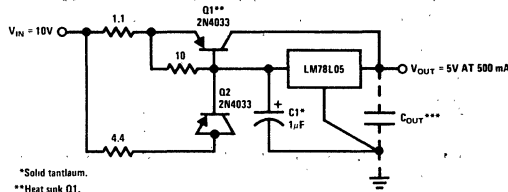
Adjustable Output Regulator

Typical Applications (Continued)



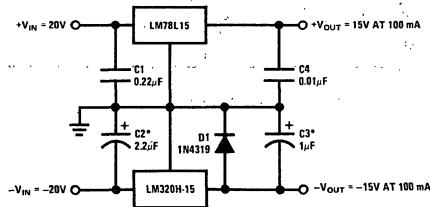
$I_{OUT} \approx (V_{IN}/R1) + I_Q$
 $\Delta I_Q = 1.5 \text{ mA over line and load changes}$

Current Regulator

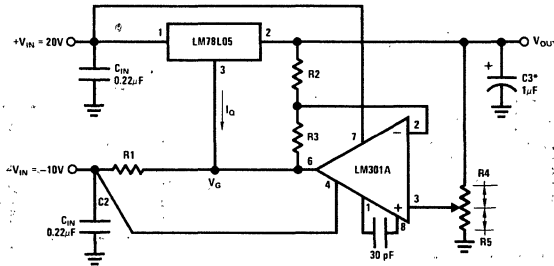


*Solid tantalum.
 **Heat sink Q1.
 ***Optional: Improves ripple rejection and transient response.
 Load Regulation: $0.6\% \leq I_L \leq 250 \text{ mA}$ pulsed with $t_{ON} = 50 \text{ ms}$.

5V, 500 mA Regulator with Short Circuit Protection



*Solid tantalum.
 $\pm 15\text{V}, 100 \text{ mA Dual Power Supply}$



*Solid tantalum.
 $V_{OUT} = V_G + 5V, R1 = (-V_{IN}/I_Q \text{ LM78L05})$
 $V_{OUT} = 5V (R2/R4) \text{ for } (R2 + R3) = (R4 + R5)$
 A 0.5V output will correspond to $(R2/R4) = 0.1, (R3/R4) = 0.9$

Variable Output Regulator 0.5V – 18V

LM78MXX Series 3-Terminal Positive Regulators
General Description

The LM78MXX series of three terminal regulators is available with several fixed output voltages making them useful in a wide range of applications. One of these is local on card regulation, eliminating the distribution problems associated with single point regulation. The voltages available allow these regulators to be used in logic systems, instrumentation, HiFi, and other solid state electronic equipment. Although designed primarily as fixed voltage regulators these devices can be used with external components to obtain adjustable voltages and currents.

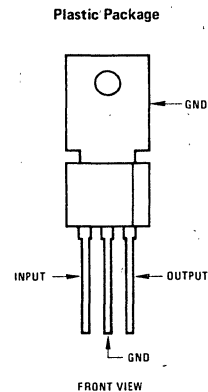
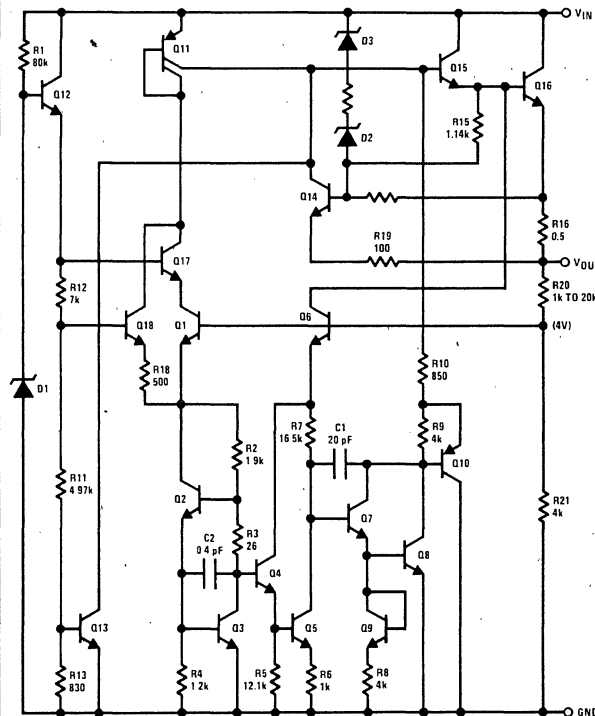
The LM78MXX series is available in the plastic TO-202 package. This package allows these regulators to deliver over 0.5A if adequate heat sinking is provided. Current limiting is included to limit the peak output current to a safe value. Safe area protection for the output transistor is provided to limit internal power dissipation. If internal power dissipation becomes too high for the heat sinking provided, the thermal shutdown circuit takes over preventing the IC from overheating.

Considerable effort was expended to make the LM78MXX series of regulators easy to use and minimize the number of external components. It is not necessary to bypass the output, although this does improve transient response. Input bypassing is needed only if the regulator is located far from the filter capacitor of the power supply.

For applications requiring other voltages, see LM117 data sheet.

Features

- Output current in excess of 0.5A
- Internal thermal overload protection
- No external components required
- Output transistor safe area protection
- Internal short circuit current limit
- Available in plastic TO-202 package
- Special circuitry allows start-up even if output is pulled to negative voltage (\pm supplies)

Schematic and Connection Diagrams

Order Numbers:

LM78M05CP
LM78M12CP
LM78M15CP
See NS Package P03A

For Tab Bend TO-202

Order Numbers:
LM78M05CP TB
LM78M12CP TB
LM78M15CP TB
See NS Package P03E

Absolute Maximum Ratings

| | |
|--|---|
| Input Voltage ($V_O = 5V, 12V$ and $15V$) | 35V |
| Internal Power Dissipation (Note 1) | Internally Limited |
| Operating Temperature Range | 0°C to $+70^\circ\text{C}$ |
| Maximum Junction Temperature | $+125^\circ\text{C}$ |
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | $+230^\circ\text{C}$ |

Electrical Characteristics

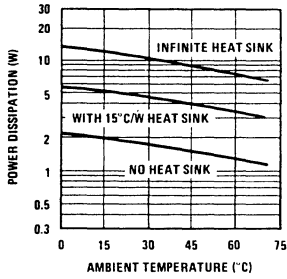
$T_A = 0^\circ\text{C}$ to 70°C , $I_O = 500\text{ mA}$, unless otherwise noted.

| OUTPUT VOLTAGE | | 5V | | | 12V | | | 15V | | | UNITS |
|---|--|------------------------------|-----|------|-------------------------------|-----|------|-------------------------------|-----|-------|---------------|
| INPUT VOLTAGE (unless otherwise noted) | | 10V | | | 19V | | | 23V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_J = 25^\circ\text{C}$ | 4.8 | 5 | 5.2 | 11.5 | 12 | 12.5 | 14.4 | 15 | 15.6 | V |
| | $P_D \leq 7.5W$, $5\text{ mA} \leq I_O \leq 500\text{ mA}$ | 4.75 | | 5.25 | 11.4 | | 12.6 | 14.25 | | 15.75 | V |
| | and $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | (7.5 $\leq V_{IN} \leq 20$) | | | (14.8 $\leq V_{IN} \leq 27$) | | | (18 $\leq V_{IN} \leq 30$) | | | V |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$, $I_O = 100\text{ mA}$ | | | 50 | | | 120 | | | 150 | mV |
| | $T_J = 25^\circ\text{C}$, $I_O = 500\text{ mA}$ | | | 100 | | | 240 | | | 300 | mV |
| | | (7.2 $\leq V_{IN} \leq 25$) | | | (14.5 $\leq V_{IN} \leq 30$) | | | (17.6 $\leq V_{IN} \leq 30$) | | | V |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, $5\text{ mA} \leq I_O \leq 500\text{ mA}$ | | | 100 | | | 240 | | | 300 | mV |
| ΔV_O Long Term Stability | | | | 20 | | | 48 | | | 60 | mV/1000 hrs |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | 4 | 10 | | 4 | 10 | | 4 | 10 | mA |
| ΔI_Q Quiescent Current Change | $T_J = 25^\circ\text{C}$ | | | 0.5 | | | 0.5 | | | 0.5 | mA |
| | $T_J = 25^\circ\text{C}$ | | | 1 | | | 1 | | | 1 | mA |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | (7.5 $\leq V_{IN} \leq 25$) | | | (14.8 $\leq V_{IN} \leq 30$) | | | (18 $\leq V_{IN} \leq 30$) | | | V |
| V_n Output Noise Voltage | $T_J = 25^\circ\text{C}$, $f = 10\text{ Hz} - 100\text{ kHz}$ | | | 40 | | | 75 | | | 90 | μV |
| $\frac{\Delta V_{IN}}{\Delta V_{OUT}}$ Ripple Rejection | $f = 120\text{ Hz}$ | | | 78 | | | 71 | | | 69 | dB |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ\text{C}$, $I_O = 500\text{ mA}$ | | | 7.2 | | | 14.5 | | | 17.6 | V |

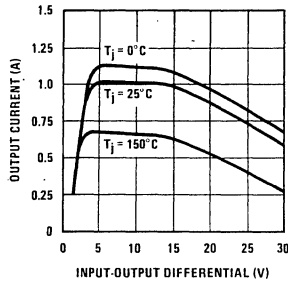
Note 1: Thermal resistance without a heat sink for junction to case temperature is 12°C/W for the TO-202 package. Thermal resistance for case to ambient temperature is 70°C/W for the TO-202 package.

Typical Performance Characteristics

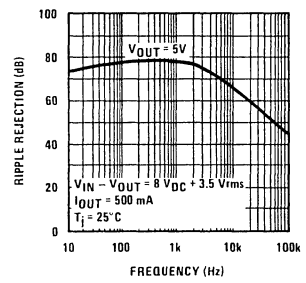
Maximum Average Power Dissipation



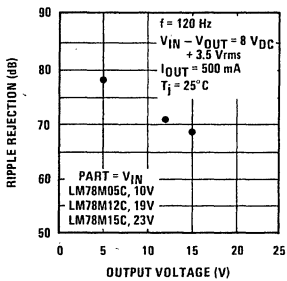
Peak Output Current



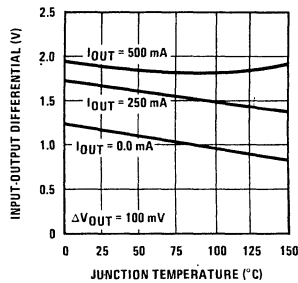
Ripple Rejection



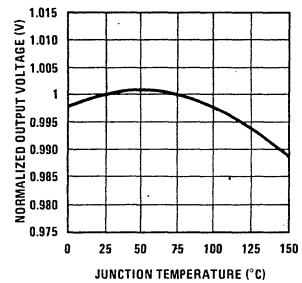
Ripple Rejection



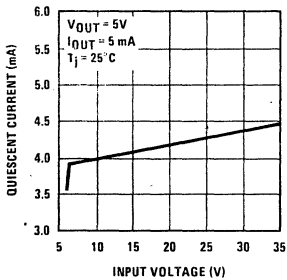
Dropout Voltage



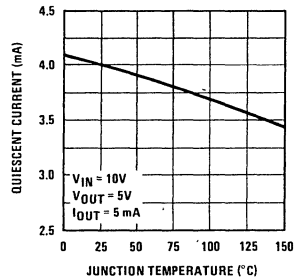
Output Voltage (Normalized to 1V at $T_J = 25^\circ\text{C}$)



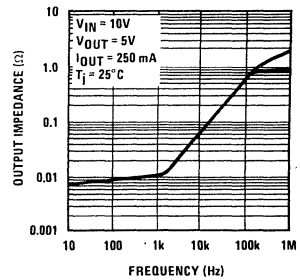
Quiescent Current



Quiescent Current



Output Impedance





LM79XX Series 3-Terminal Negative Regulators

General Description

The LM79XX series of 3-terminal regulators is available with fixed output voltages of $-5V$, $-12V$, and $-15V$. These devices need only one external component—a compensation capacitor at the output. The LM79XX series is packaged in the TO-220 power package and is capable of supplying 1.5A of output current.

These regulators employ internal current limiting safe area protection and thermal shutdown for protection against virtually all overload conditions.

Low ground pin current of the LM79XX series allows output voltage to be easily boosted above the preset value with a resistor divider. The low quiescent current

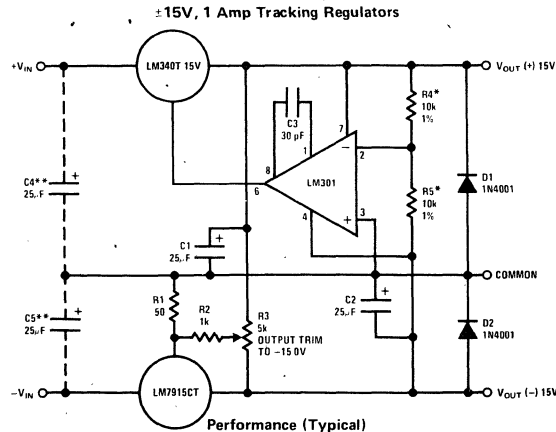
drawn of these devices with a specified maximum change with line and load ensures good regulation in the voltage boosted mode.

For applications requiring other voltages, see LM137 data sheet.

Features

- Thermal, short circuit and safe area protection
- High ripple rejection
- 1.5A output current
- 4% preset output voltage

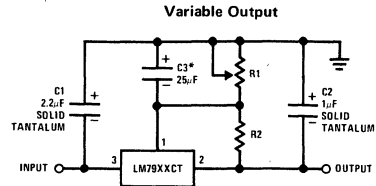
Typical Applications



Performance (Typical)

| | (-15) | (+15) |
|--|------------------|------------------|
| Load Regulation at $\Delta I_L = 1A$ | 40 mV | 2 mV |
| Output Ripple, $C_{IN} = 3000\mu F$, $I_L = 1A$ | $100\mu V_{rms}$ | $100\mu V_{rms}$ |
| Temperature Stability | 50 mV | 50 mV |
| Output Noise $10 Hz \leq f \leq 10 kHz$ | $150\mu V_{rms}$ | $150\mu V_{rms}$ |

* Resistor tolerance of R4 and R5 determine matching of (+) and (-) outputs
 ** Necessary only if raw supply filter capacitors are more than 3" from regulators

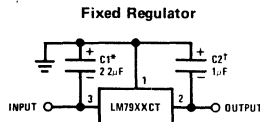


* Improves transient response and ripple rejection. Do not increase beyond $50\mu F$.

$$V_{OUT} = V_{SET} \left(\frac{R1 + R2}{R2} \right)$$

Select R2 as follows

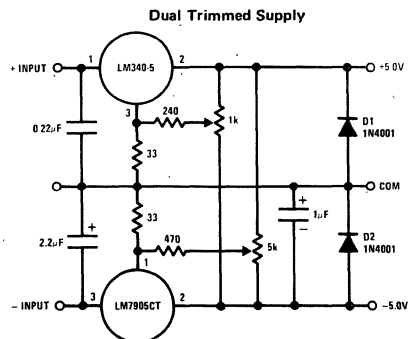
| | |
|----------|------|
| LM7905CT | 300Ω |
| LM7912CT | 750Ω |
| LM7915CT | 1k |



* Required if regulator is separated from filter capacitor by more than 3". For value given, capacitor must be solid tantalum. $25\mu F$ aluminum electrolytic may be substituted.

† Required for stability. For value given, capacitor must be solid tantalum. $25\mu F$ aluminum electrolytic may be substituted. Values given may be increased without limit.

For output capacitance in excess of $100\mu F$, a high current diode from input to output (1N4001, etc.) will protect the regulator from momentary input shorts.



Absolute Maximum Ratings

| | |
|--|--------------------|
| Input Voltage | |
| ($V_O = 5V$) | -35V |
| ($V_O = 12V$ and $15V$) | -40V |
| Input-Output Differential | |
| ($V_O = 5V$) | 25V |
| ($V_O = 12V$ and $15V$) | 30V |
| Power Dissipation | Internally Limited |
| Operating Junction Temperature Range | 0°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 230°C |

Electrical Characteristics Conditions unless otherwise noted: $I_{OUT} = 500\text{ mA}$, $C_{IN} = 2.2\mu\text{F}$, $C_{OUT} = 1\mu\text{F}$, $0^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$, Power Dissipation $\leq 15\text{W}$.

| PART NUMBER | | LM7905C | | | UNITS |
|---|--|------------------------------|------|-------|----------------------------|
| OUTPUT VOLTAGE | | 5V | | | |
| INPUT VOLTAGE (unless otherwise specified) | | -10V | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | |
| V_O Output Voltage | $T_J = 25^\circ\text{C}$ $5\text{ mA} \leq I_{OUT} \leq 1\text{ A}$, $P \leq 15\text{ W}$ | -4.8 | -5.0 | -5.2 | V |
| | | -4.75 | | -5.25 | V |
| | | (-20 $\leq V_{IN} \leq -7$) | | | V |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$, (Note 2) | | 8 | 50 | mV |
| | | (-25 $\leq V_{IN} \leq -7$) | | | V |
| | | | 2 | 15 | mV |
| (-12 $\leq V_{IN} \leq -8$) | | | | V | |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, (Note 2) $5\text{ mA} \leq I_{OUT} \leq 1.5\text{ A}$ $250\text{ mA} \leq I_{OUT} \leq 750\text{ mA}$ | | | | mV |
| | | | 15 | 100 | mV |
| | | | 5 | 50 | mV |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | 1 | 2 | mA |
| ΔI_Q Quiescent Current Change | With Line | | | 0.5 | mA |
| | With Load, $5\text{ mA} \leq I_{OUT} \leq 1\text{ A}$ | | | 0.5 | mA |
| V_n Output Noise Voltage | $T_A = 25^\circ\text{C}$, $10\text{ Hz} \leq f \leq 100\text{ Hz}$ | | 125 | | μV |
| Ripple Rejection | $f = 120\text{ Hz}$ | 54 | 66 | | dB |
| (-18 $\leq V_{IN} \leq -8$) | | | | | V |
| Dropout Voltage | $T_J = 25^\circ\text{C}$, $I_{OUT} = 1\text{ A}$ | | 1.1 | | V |
| I_{OMAX} Peak Output Current | $T_J = 25^\circ\text{C}$ | | 2.2 | | A |
| Average Temperature Coefficient of Output Voltage | $I_{OUT} = 5\text{ mA}$, $0^\circ\text{C} \leq T_J \leq 100^\circ\text{C}$ | | 0.4 | | $\text{mV}/^\circ\text{C}$ |

1

Electrical Characteristics (Continued) Conditions unless otherwise noted: $I_{OUT} = 500\text{ mA}$, $C_{IN} = 2.2\mu\text{F}$, $C_{OUT} = 1\mu\text{F}$, $0^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$, Power Dissipation = 1.5W.

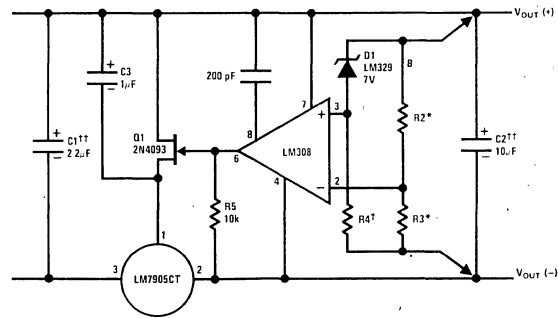
| PART NUMBER | | | LM7912C | | | LM7915C | | | UNITS | |
|---|---|--|--------------------------------|--------------------------------|-------|--------------------------------|--------------------------------|--------|----------------------------|----|
| OUTPUT VOLTAGE | | | 12V | | | 15V | | | | |
| INPUT VOLTAGE (unless otherwise specified) | | | -19V | | | -23V | | | | |
| PARAMETER | CONDITIONS | | MIN | TYP | MAX | MIN | TYP | MAX | | |
| V_O Output Voltage | $T_J = 25^\circ\text{C}$ | | -11.5 | -12.0 | -12.5 | -14.4 | -15.0 | -15.6 | V | |
| | $5\text{ mA} \leq I_{OUT} \leq 1\text{A}$, $P \leq 15\text{W}$ | | -11.4 | | -12.6 | -14.25 | | -15.75 | V | |
| | | | $(-27 \leq V_{IN} \leq -14.5)$ | | | $(-30 \leq V_{IN} \leq -17.5)$ | | | V | |
| ΔV_O Line Regulation | $T_J = 25^\circ\text{C}$, (Note 2) | | | 5 | 80 | | 5 | 100 | mV | |
| | | | | $(-30 \leq V_{IN} \leq -14.5)$ | | | $(-30 \leq V_{IN} \leq -17.5)$ | | | V |
| | | | | | 3 | 30 | | 3 | 50 | mV |
| | | | | $(-22 \leq V_{IN} \leq -16)$ | | | $(-26 \leq V_{IN} \leq -20)$ | | | V |
| ΔV_O Load Regulation | $T_J = 25^\circ\text{C}$, (Note 2) $5\text{ mA} \leq I_{OUT} \leq 1.5\text{A}$ $250\text{ mA} \leq I_{OUT} \leq 750\text{ mA}$ | | | 15 | 200 | | 15 | 200 | mV | |
| | | | | 15 | 200 | | 15 | 200 | mV | |
| | | | | 5 | 75 | | 5 | 75 | mV | |
| I_Q Quiescent Current | $T_J = 25^\circ\text{C}$ | | | 1.5 | 3 | | 1.5 | 3 | mA | |
| ΔI_Q Quiescent Current Change | With Line With Load, $5\text{ mA} \leq I_{OUT} \leq 1\text{A}$ | | | | 0.5 | | | 0.5 | mA | |
| | | | | $(-30 \leq V_{IN} \leq -14.5)$ | | | $(-30 \leq V_{IN} \leq -17.5)$ | | | V |
| | | | | | | 0.5 | | | 0.5 | mA |
| V_n Output Noise Voltage | $T_A = 25^\circ\text{C}$, $10\text{ Hz} \leq f \leq 100\text{ Hz}$ | | | 300 | | | 375 | | μV | |
| Ripple Rejection | $f = 120\text{ Hz}$ | | 54 | 70 | | 54 | 70 | | dB | |
| | | | $(-25 \leq V_{IN} \leq -15)$ | | | $(-30 \leq V_{IN} \leq -17.5)$ | | | V | |
| Dropout Voltage | $T_J = 25^\circ\text{C}$, $I_{OUT} = 1\text{A}$ | | | 1.1 | | | 1.1 | | V | |
| I_{OMAX} Peak Output Current | $T_J = 25^\circ\text{C}$ | | | 2.2 | | | 2.2 | | A | |
| Average Temperature Coefficient of Output Voltage | $I_{OUT} = 5\text{ mA}$, $0^\circ\text{C} \leq T_J \leq 100^\circ\text{C}$ | | | -0.8 | | | -1.0 | | $\text{mV}/^\circ\text{C}$ | |

Note 1: For calculations of junction temperature rise due to power dissipation, thermal resistance junction to ambient (θ_{JA}) is $50^\circ\text{C}/\text{W}$ (no heat sink) and $5^\circ\text{C}/\text{W}$ (infinite heat sink).

Note 2: Regulation is measured at a constant junction temperature by pulse testing with a low duty cycle. Changes in output voltage due to heating effects must be taken into account.

Typical Applications (Continued)

High Stability 1 Amp Regulator



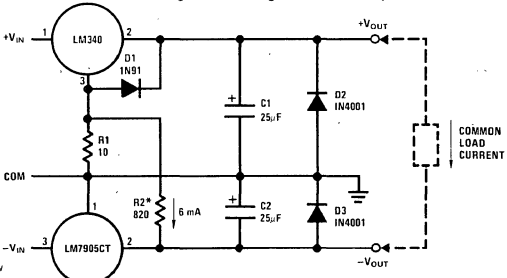
Load and line regulation < 0.01% temperature stability ≤ 0.2%

† Determines Zener current

†† Solid tantalum

* Select resistors to set output voltage. 2 ppm/°C tracking suggested

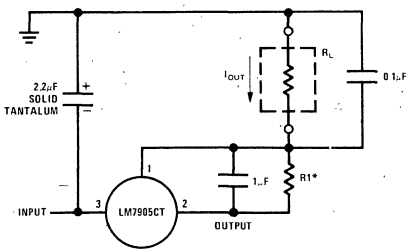
Preventing Positive Regulator Latch-Up



R1 and D1 allow the positive regulator to "start-up" when +VIN is delayed relative to -VIN and a heavy load is drawn between the outputs. Without R1 and D1, most three-terminal regulators will not start with heavy (0.1A-1A) load current flowing to the negative regulator, even though the positive output is clamped by D2.

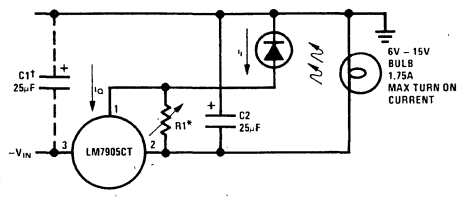
* R2 is optional. Ground pin current from the positive regulator flowing through R1 will increase +VOUT ≈ 60 mV if R2 is omitted.

Current Source



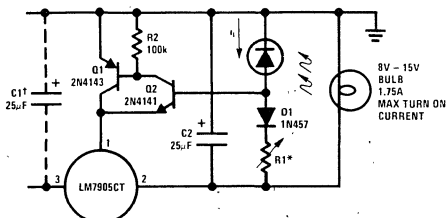
$$*I_{OUT} = 1 \text{ mA} + \frac{5V}{R1}$$

Light Controllers Using Silicon Photo Cells



* Lamp brightness increases until $i_l = i_Q (\approx 1 \text{ mA}) + 5V/R1$.

† Necessary only if raw supply filter capacitor is more than 2" from LM7905CT

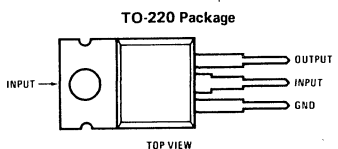
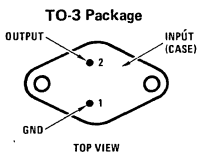


* Lamp brightness increases until $i_l = 5V/R1$ (i_l can be set as low as 1µA)

† Necessary only if raw supply filter capacitor is more than 2" from LM7905CT

Connection Diagrams

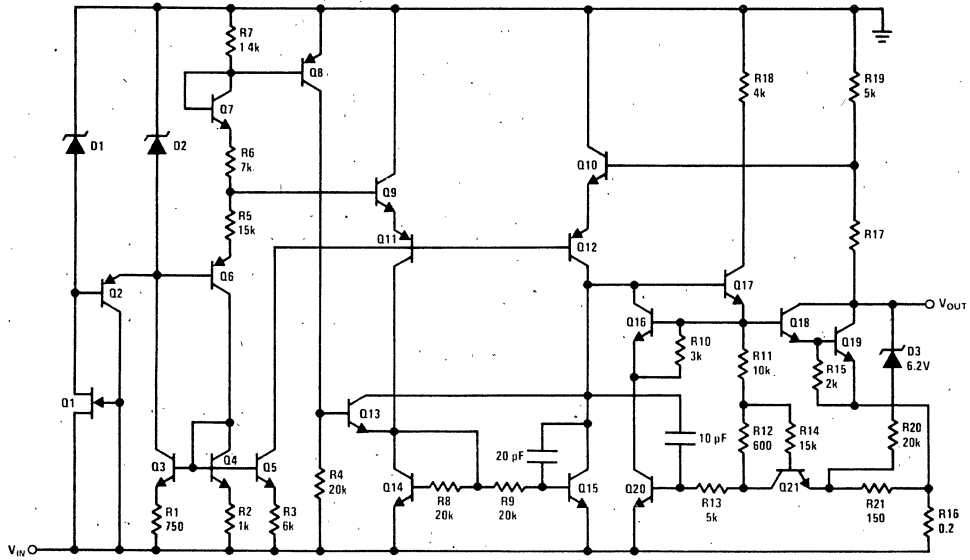
Order Numbers:
LM7905CK
LM7912CK
LM7915CK
See NS Package KC02A



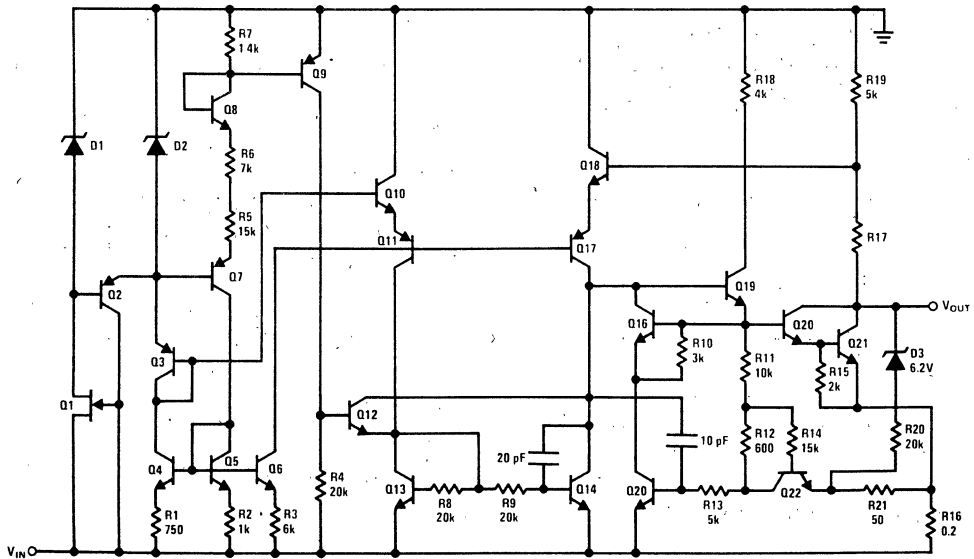
Order Numbers:
LM7905CT
LM7912CT
LM7915CT
See NS Package T03B

Schematic Diagrams

-5V



-12V and -15V



LM79LXXAC Series 3-Terminal Negative Regulators

General Description

The LM79LXXAC series of 3-terminal negative voltage regulators features fixed output voltages of $-5V$, $-12V$, and $-15V$, with output current capabilities in excess of 100 mA. These devices were designed using the latest computer techniques for optimizing the packaged IC thermal/electrical performance. The LM79LXXAC series, even when combined with a minimum output compensation capacitor of $0.1 \mu F$, exhibits an excellent transient response, a maximum line regulation of $0.07\% V_O/V$, and a maximum load regulation of $0.01\% V_O/mA$.

The LM79LXXAC series also includes, as self-protection circuitry: safe operating area circuitry for output transistor power dissipation limiting, a temperature independent short circuit current limit for peak output current limiting, and a thermal shutdown circuit to prevent excessive junction temperature. Although designed primarily as fixed voltage regulators, these devices may be combined with simple external circuitry for boosted and/

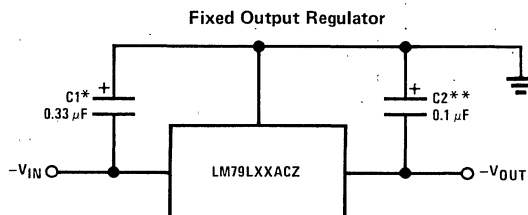
or adjustable voltages and currents. The LM79LXXAC series is available in the 3-lead TO-92 package.

For applications requiring other voltages, see LM137 data sheet.

Features

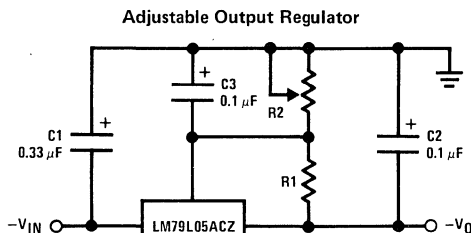
- Preset output voltage error is less than $\pm 5\%$ over load, line and temperature
- Specified at an output current of 100 mA
- Easily compensated with a small $0.1 \mu F$ output capacitor
- Internal short-circuit, thermal and safe operating area protection
- Easily adjustable to higher output voltages
- Maximum line regulation less than $0.07\% V_{OUT}/V$
- Maximum load regulation less than $0.01\% V_{OUT}/mA$
- TO-92 package

Typical Applications



*Required if the regulator is located far from the power supply filter. A $1 \mu F$ aluminum electrolytic may be substituted.

**Required for stability. A $1 \mu F$ aluminum electrolytic may be substituted.

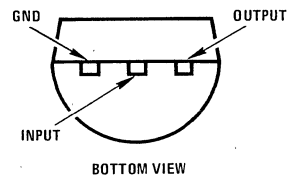


$$-V_O = -5V - (5V/R_1 + I_Q) \cdot R_2$$

$$5V/R_1 > 3 I_Q$$

Connection Diagram

TO-92 Plastic Package (Z)



Order Numbers

LM79L05ACZ

LM79L12ACZ

LM79L15ACZ

See NS Package Z03A

Absolute Maximum Ratings

| | | |
|--|------------------------------|---------------------------------|
| Input Voltage | $V_O = -5V, -12V$ and $-15V$ | $-35V$ |
| Internal Power Dissipation (Note 1) | | Internally Limited |
| Operating Temperature Range | | $0^\circ C$ to $+70^\circ C$ |
| Maximum Junction Temperature | | $+125^\circ C$ |
| Storage Temperature Range | | $-55^\circ C$ to $+150^\circ C$ |
| Lead Temperature (Soldering, 10 seconds) | | $300^\circ C$ |

Electrical Characteristics (Note 2) $T_J = 0^\circ C$ to $+125^\circ C$ unless otherwise noted.

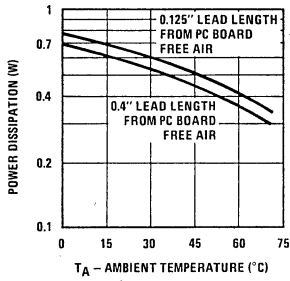
| OUTPUT VOLTAGE | | $-5V$ | | | $-12V$ | | | $-15V$ | | | |
|---|--|--------|-----|-------|--------|-----|-------|--------|-----|--------|------------|
| INPUT VOLTAGE (unless otherwise noted) | | $-10V$ | | | $-17V$ | | | $-20V$ | | | UNITS |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_J = 25^\circ C, I_O = 100\text{ mA}$ | -5.2 | -5 | -4.8 | -12.5 | -12 | -11.5 | -15.6 | -15 | -14.4 | V |
| | $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | -5.25 | | -4.75 | -12.6 | | -11.4 | -15.7 | | -14.25 | |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | | | | | | | | | |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | -5.25 | | -4.75 | -12.6 | | -11.4 | -15.75 | | -14.25 | |
| ΔV_O Line Regulation | $T_J = 25^\circ C, I_O = 100\text{ mA}$ | | | 60 | | | 45 | | | 45 | mV |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | | | | | | | | | V |
| | $T_J = 25^\circ C, I_O = 40\text{ mA}$ | | | 60 | | | 45 | | | 45 | mV |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | | | | | | | | | V |
| ΔV_O Load Regulation | $T_J = 25^\circ C,$ $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | | | 50 | | | 100 | | | 125 | mV |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | | 30 | | | 50 | | | 75 | mV |
| | | | | | | | | | | | |
| ΔV_O Long Term Stability | $I_O = 100\text{ mA}$ | | 20 | | | 48 | | | 60 | | mV/1000 hr |
| I_Q Quiescent Current | $I_O = 100\text{ mA}$ | | 2 | 6 | | 2 | 6 | | 2 | 6 | mA |
| | $T_J = 125^\circ C, I_O = 40\text{ mA}$ | | | 5.5 | | | 5.5 | | | 5.5 | mA |
| ΔI_Q Quiescent Current Change | $1\text{ mA} \leq I_O \leq 100\text{ mA}$ | | | 0.3 | | | 0.3 | | | 0.3 | mA |
| | $1\text{ mA} \leq I_O \leq 40\text{ mA}$ | | | 0.1 | | | 0.1 | | | 0.1 | |
| | $I_O = 100\text{ mA}$ | | | 0.25 | | | 0.25 | | | 0.25 | |
| | $V_{MIN} \leq V_{IN} \leq V_{MAX}$ | | | | | | | | | | |
| V_n Output Noise Voltage | $T_J = 25^\circ C, I_O = 100\text{ mA},$ $f = 10\text{ Hz} - 10\text{ kHz}$ | | | 40 | | | 96 | | | 120 | μV |
| | | | | | | | | | | | |
| $\frac{\Delta V_{IN}}{\Delta V_O}$ Ripple Rejection | $T_J = 25^\circ C, I_O = 100\text{ mA},$ $f = 120\text{ Hz}$ | | 50 | | | 52 | | | 50 | | dB |
| Input Voltage Required to Maintain Line Regulation | $T_J = 25^\circ C$ | | | | | | | | | | V |
| | $I_O = 100\text{ mA}$ | | | -7.3 | | | -14.6 | | | -17.7 | |
| | $I_O = 40\text{ mA}$ | | | -7.0 | | | -14.5 | | | -17.5 | |

Note 1: Thermal resistance, junction to ambient, of the TO-92 (Z) package is $180^\circ C/W$ when mounted with 0.40 inch leads on a PC board, and $160^\circ C/W$ when mounted with 0.25 inch leads on a PC board.

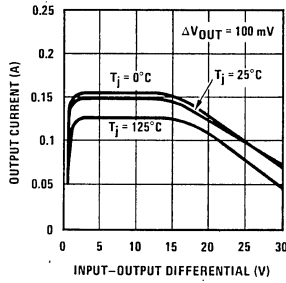
Note 2: To ensure constant junction temperature, low duty cycle pulse testing is used.

Typical Performance Characteristics

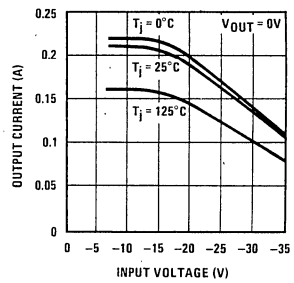
Maximum Average Power Dissipation (TO-92)



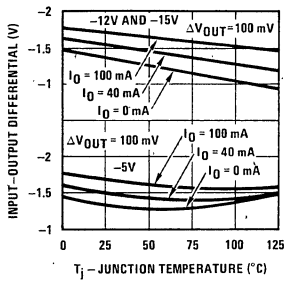
Peak Output Current



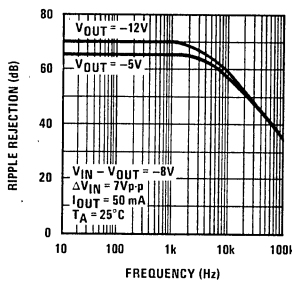
Short Circuit Output Current



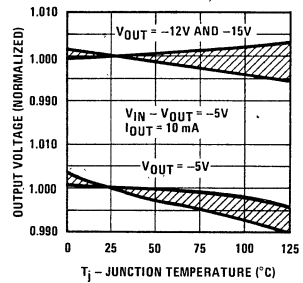
Dropout Voltage



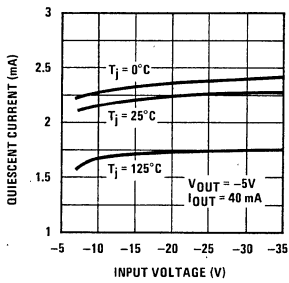
Ripple Rejection



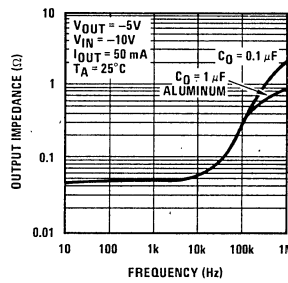
Output Voltage vs. Temperature (Normalized to 1V @ 25°C)



Quiescent Current

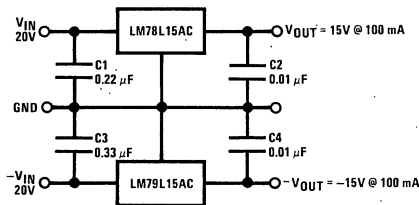


Output Impedance



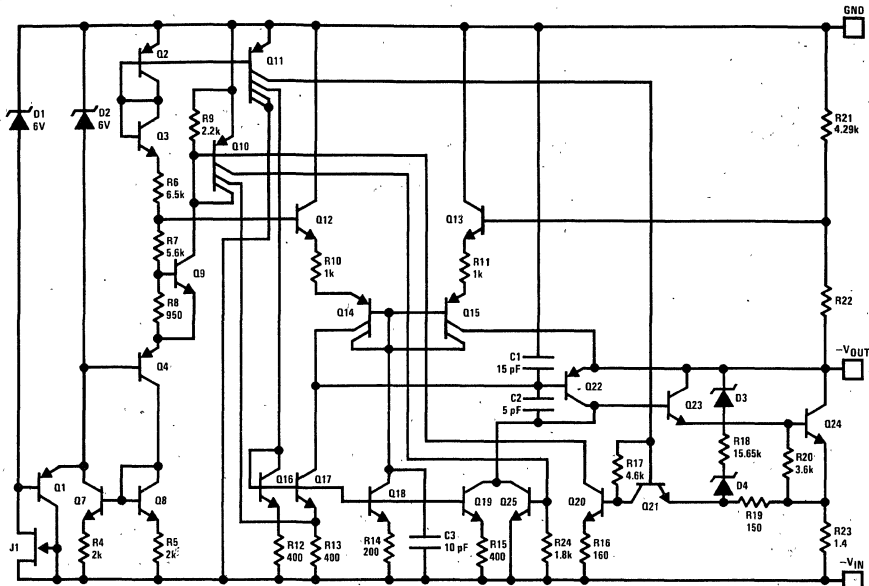
Typical Applications (Continued)

±15V, 100 mA Dual Power Supply

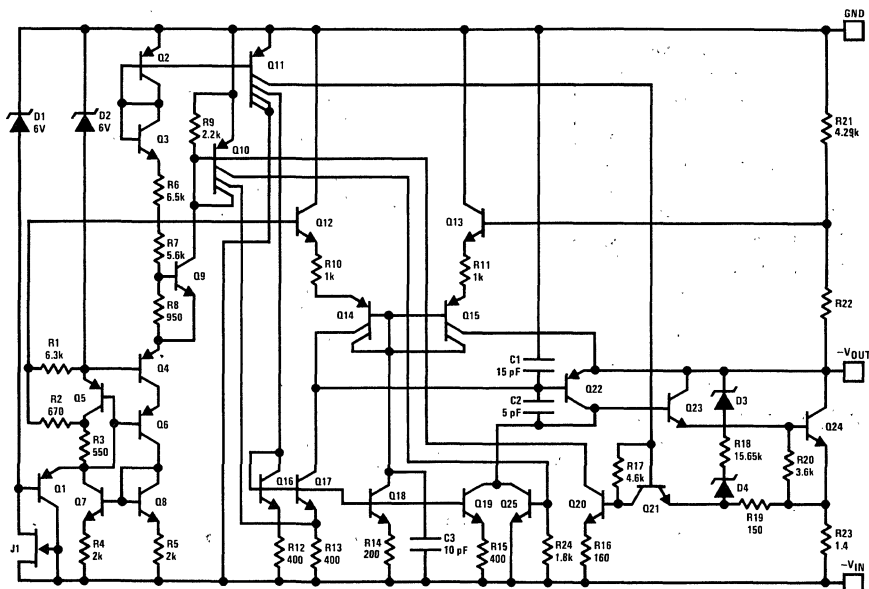


Schematic Diagrams

-5V



-12V and -15V



LM79MXX Series 3-Terminal Negative Regulators

General Description

The LM79MXX series of 3-terminal regulators is available with fixed output voltages of $-5V$, $-12V$, and $-15V$. These devices need only one external component—a compensation capacitor at the output. The LM79MXX series is packaged in the TO-202 power package and TO-5 metal can and is capable of supplying 0.5A of output current.

These regulators employ internal current limiting safe area protection and thermal shutdown for protection against virtually all overload conditions.

Low ground pin current of the LM79MXX series allows output voltage to be easily boosted above the preset value with a resistor divider. The low quiescent current

drawn of these devices with a specified maximum change with line and load ensures good regulation in the voltage boosted mode.

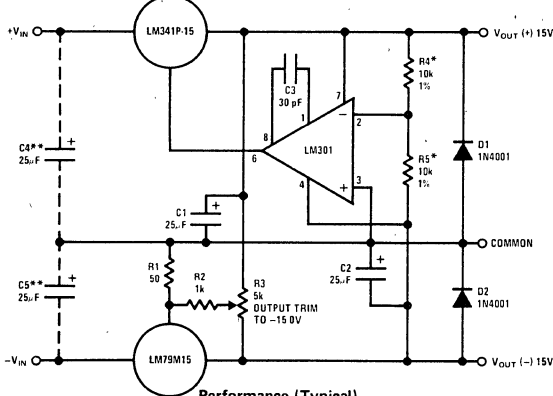
For applications requiring other voltages, see LM137 data sheet.

Features

- Thermal, short circuit and safe area protection
- High ripple rejection
- 0.5A output current
- 4% preset output voltage

Typical Applications

±15V, 1 Amp Tracking Regulators

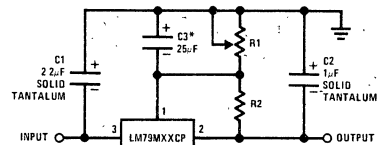


Performance (Typical)

| | (-15) | (+15) |
|--|-------------------|-------------------|
| Load Regulation at 0.5A | 40 mV | 2 mV |
| Output Ripple, $C_{1N} = 3000\mu F$, $I_L = 0.5A$ | 100 μV_{rms} | 100 μV_{rms} |
| Temperature Stability | 50 mV | 50 mV |
| Output Noise 10 Hz $\leq f \leq$ 10 kHz | 150 μV_{rms} | 150 μV_{rms} |

*Resistor tolerance of R4 and R5 determine matching of (+) and (-) outputs
 **Necessary only if raw supply filter capacitors are more than 3" from regulators

Variable Output



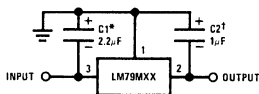
*Improves transient response and ripple rejection. Do not increase beyond 50 μF .

$$V_{OUT} = V_{SET} \left(\frac{R1 + R2}{R2} \right)$$

Select R2 as follows:

| | |
|-----------|--------------|
| LM79M05CP | 300 Ω |
| LM79M12CP | 750 Ω |
| LM79M15CP | 1k |

Fixed Regulator

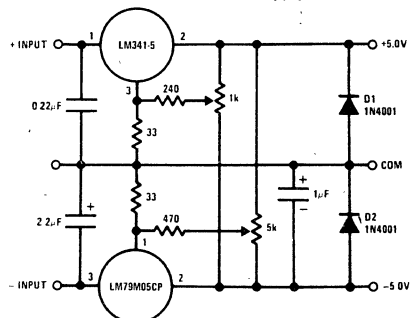


*Required if regulator is separated from filter capacitor by more than 3". For value given, capacitor must be solid tantalum. 25 μF aluminum electrolytic may be substituted.

†Required for stability. For value given, capacitor must be solid tantalum. 25 μF aluminum electrolytic may be substituted. Values given may be increased without limit.

For output capacitance in excess of 100 μF , a high current diode from input to output (1N4001, etc.) will protect the regulator from momentary input shorts.

Dual Trimmed Supply



Absolute Maximum Ratings

| | | |
|--|---------------------------------|------|
| Input Voltage | | 25V |
| ($V_O = 5V$) | | |
| ($V_O = 12V$ and $15V$) | | -35V |
| Input/Output Differential | | 25V |
| ($V_O = 5V$ to $8V$) | | |
| ($V_O = 12V$ and $15V$) | | 30V |
| Power Dissipation | Internally Limited | |
| Operating Junction Temperature Range | $0^\circ C$ to $+125^\circ C$ | |
| Storage Temperature Range | $-65^\circ C$ to $+150^\circ C$ | |
| Lead Temperature (Soldering, 10 seconds) | $230^\circ C$ | |

Electrical Characteristics

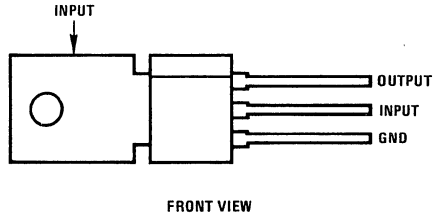
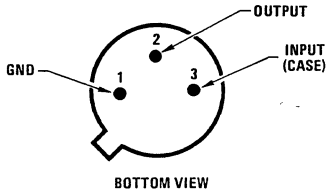
Conditions unless otherwise noted: $I_{OUT} = 350\text{ mA}$, $C_{IN} = 2.2\mu\text{F}$, $C_{OUT} = 1\mu\text{F}$, $0^\circ C \leq T_j \leq +125^\circ C$

| PART NUMBER | | LM79M05C | LM79M12C | LM79M15C | UNITS | | | | | | |
|---|---|-----------------------------|-----------------------------|----------|-------|--------------------------------|-------|--------------------------------|--------------------------------|--------|----------------------|
| OUTPUT VOLTAGE | | -5V | -12V | -15V | | | | | | | |
| INPUT VOLTAGE (unless otherwise specified) | | -10V | -19V | -23V | | | | | | | |
| PARAMETER | CONDITIONS | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_O Output Voltage | $T_j = 25^\circ C$ | -4.8 | -5.0 | -5.2 | -11.5 | -12.0 | -12.5 | -14.4 | -15.0 | -15.6 | V |
| | $5\text{ mA} \leq I_{OUT} \leq 350\text{ mA}$ | -4.75 | | -5.25 | -11.4 | | -12.6 | -14.25 | | -15.75 | V |
| | | $(-25 \leq V_{IN} \leq -7)$ | | | | $(-27 \leq V_{IN} \leq -14.5)$ | | | $(-30 \leq V_{IN} \leq -17.5)$ | | V |
| ΔV_O Line Regulation | $T_j = 25^\circ C$, (Note 2) | | 8 | 50 | | 5 | 80 | | 5 | 80 | mV |
| | | | $(-25 \leq V_{IN} \leq -7)$ | | | $(-30 \leq V_{IN} \leq -14.5)$ | | | $(- \leq V_{IN} \leq -17.5)$ | | V |
| | | | 2 | 30 | | 3 | 30 | | 3 | 50 | mV |
| | | | $(-18 \leq V_{IN} \leq -8)$ | | | $(-25 \leq V_{IN} \leq -15)$ | | | $(-28 \leq V_{IN} \leq -18)$ | | V |
| ΔV_O Load Regulation | $T_j = 25^\circ C$, (Note 2) $5\text{ mA} \leq I_{OUT} \leq 0.5A$ | | 30 | 100 | | 30 | 240 | | 30 | 240 | mV |
| I_Q Quiescent Current | $T_j = 25^\circ C$ | | 1 | 2 | | 1.5 | 3 | | 1.5 | 3 | mA |
| ΔI_Q Quiescent Current Change | With Line | | | 0.4 | | | 0.4 | | | 0.4 | mA |
| | With Load, $5\text{ mA} \leq I_{OUT} \leq 350\text{ mA}$ | | | | | $(-30 \leq V_{IN} \leq -14.5)$ | | $(-30 \leq V_{IN} \leq -27)$ | | | V |
| | | | | 0.4 | | | 0.4 | | | 0.4 | mA |
| V_N Output Noise Voltage | $T_A = 25^\circ C$, $10\text{ Hz} \leq f \leq 100\text{ Hz}$ | | 750 | | | 400 | | | 400 | | μV |
| Ripple Rejection | $f = 120\text{ Hz}$ | 54 | 66 | | 54 | 70 | | 54 | 70 | | dB |
| | | | $(-18 \leq V_{IN} \leq -8)$ | | | $(-25 \leq V_{IN} \leq -15)$ | | $(-30 \leq V_{IN} \leq -17.5)$ | | | V |
| Dropout Voltage | $T_j = 25^\circ C$, $I_{OUT} = 0.5A$ | | 1.1 | | | 1.1 | | | 1.1 | | V |
| I_{OMAX} Peak Output Current | $T_j = 25^\circ C$ | | 800 | | | 800 | | | 800 | | A |
| Average Temperature Coefficient of Output Voltage | $I_{OUT} = 5\text{ mA}$, $0^\circ C \leq T_j \leq 100^\circ C$ | | 0.4 | | | -0.8 | | | -1.0 | | $\text{mV}/^\circ C$ |

Note 1: For calculations of junction temperature rise due to power dissipation, thermal resistance junction to ambient (θ_{JA}) is $70^\circ C/W$ (no heat sink) and $12^\circ C/W$ (infinite heat sink).

Note 2: Regulation is measured at a constant junction temperature by pulse testing with a low duty cycle. Changes in output voltage due to heating effects must be taken into account.

Connection Diagrams



Metal Can Package TO-39 (H)
Order Number:
LM79M05CH
LM79M12CH
LM79M15CH
See NS Package H03A

Power Package TO-202 (P)
Order Number:
LM79M05CP
LM79M12CP
LM79M15CP
See NS Package P03A

For Tab Band TO-202
Order Number:
LM79M05CP TB
LM79M12CP TB
LM79M15CP TB
See NS Package P03E



Section 2

Voltage References

2



Section Contents

| | |
|--|-------|
| Voltage Reference Guide..... | 2-iii |
| Voltage Reference and Precision Reference Guides..... | 2-iv |
| LH0070 Series Precision BCD Buffered Reference..... | 2-1 |
| LH0071 Series Precision Binary Buffered Reference..... | 2-1 |
| LM103 Reference Diode..... | 2-15 |
| LM113/LM313 Reference Diode..... | 2-18 |
| LM129/LM329 Precision Reference..... | 2-21 |
| LM136/LM236/LM336 2.5V Reference Diode..... | 2-26 |
| LM185/LM285/LM385 Voltage Reference Diode..... | 2-32 |
| LM199/LM299/LM399 Precision Reference..... | 2-38 |
| LM199A/LM299A/LM399A Precision Reference..... | 2-44 |
| LM3999 Precision Reference..... | 2-47 |

| REVERSE BREAKDOWN VOLTAGE V_R at I_R | DEVICE | VOLTAGE TOLERANCE MAX, $T_A = 25^\circ\text{C}$ | VOLTAGE TEMPERATURE DRIFT – ppm/ $^\circ\text{C}$ MAX or mV MAX CHANGE OVER TEMPERATURE RANGE | | CURRENT RANGE, I_R | DYNAMIC IMPEDANCE |
|---|------------|--|--|---|----------------------------|----------------------|
| | | | DRIFT (MAX) | TEMPERATURE RANGE | | |
| 1.22 | LM113 | ±5% | 100 (typ) | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 500 μA to 20 mA | 0.3 Ω |
| 1.22 | LM313 | ±5% | 100 (typ) | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 500 μA to 20 mA | 0.3 Ω |
| 1.22 | LM113-1 | ±1% | 50 (typ) | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 500 μA to 20 mA | 0.3 Ω |
| 1.22 | LM113-2 | ±2% | 50 (typ) | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 500 μA to 20 mA | 0.3 Ω |
| 2.49 | LM136 | ±2% | 18 mV | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 2.49 | LM136A | ±1% | 18 mV | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 2.49 | LM236 | ±2% | 9 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 2.49 | LM236A | ±1% | 9 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 2.49 | LM336 | ±4% | 6 mV | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 2.49 | LM336B | ±2% | 6 mV | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM136-5.0 | ±2% | 36 mV | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM136A-5.0 | ±1% | 36 mV | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM236-5.0 | ±2% | 18 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM236A-5.0 | ±1% | 18 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM336-5.0 | ±4% | 12 mV | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 5.0 | LM336B-5.0 | ±2% | 12 mV | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 400 μA to 10 mA | 0.2 Ω |
| 6.90 | LM129A | +3%, –2% | 10 | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.6 Ω |
| 6.90 | LM129B | +3%, –2% | 20 | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.6 Ω |
| 6.90 | LM129C | +3%, –2% | 50 | –55 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.6 Ω |
| 6.90 | LM329B | ±5% | 20 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.8 Ω |
| 6.90 | LM329C | ±5% | 50 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.8 Ω |
| 6.90 | LM329D | ±5% | 100 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.6 mA to 15 mA | 0.8 Ω |
| 6.95 | LM199A | +1%, –2% | 0.5 | –55 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM199A | +1%, –2% | 10 | 85 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM199 | +1%, –2% | 1 | –55 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM199 | +1%, –2% | 15 | 85 $^\circ\text{C}$ to +125 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM299A | +1%, –2% | 0.5 | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM299 | +1%, –2% | 1 | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM399A | ±5% | 1 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM399 | ±5% | 2 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.5 mA to 10 mA | 0.5 Ω |
| 6.95 | LM3999 | ±5% | 5 | 0 $^\circ\text{C}$ to +70 $^\circ\text{C}$ | 0.6 mA to 10 mA | 0.6 Ω |
| 10.00 | LH0070-0 | 0.1% | 20 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |
| 10.00 | LH0070-1 | 0.1% | 10 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |
| 10.00 | LH0070-2 | 0.05% | 4 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |
| 10.24 | LH0071-0 | 0.1% | 20 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |
| 10.24 | LH0071-1 | 0.1% | 10 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |
| 10.24 | LH0071-2 | 0.05% | 4 mV | –25 $^\circ\text{C}$ to +85 $^\circ\text{C}$ | 0 mA to 20 mA | 0.2 Ω |

Voltage Reference and Precision Reference Guides

VOLTAGE REFERENCES

| REVERSE BREAKDOWN VOLTAGE V_R at I_R | DEVICE | VOLTAGE TOLERANCE MAX, $T_A = 25^\circ\text{C}$ | VOLTAGE TEMPERATURE DRIFT – ppm/ $^\circ\text{C}$ MAX or mV MAX CHANGE OVER TEMPERATURE RANGE | | CURRENT RANGE, I_R | DYNAMIC IMPEDANCE |
|---|--------|--|--|---|-------------------------------------|-------------------|
| | | | DRIFT (MAX) | TEMPERATURE RANGE | | |
| LOW CURRENT ZENER DIODES | | | | | | |
| 1.8 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 2.0 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 2.2 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 2.4 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 2.7 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 3.0 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 3.3 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 3.6 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 3.9 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 4.3 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 4.7 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 5.1 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |
| 5.6 | LM103 | $\pm 10\%$ | $-5 \text{ mV}/^\circ\text{C}$ (typ) | -55°C to $+125^\circ\text{C}$ | $10 \mu\text{A}$ to 10 mA | 15Ω |

PRECISION REFERENCES

| Function | Features | Line Reg | Load Reg | I_{OUT} (mA) | V_{OUT} Toler. @ 25°C (Max) | Drift (Max) | Part Number | | ** |
|--|--|----------|----------|----------------|---|---------------|--|---|-------------|
| | | | | | | | -55°C to 125°C | -25°C to 85°C | Page Number |
| 10.000V Precision BCD Reference | Three-terminal buffered zener reference, 0.1Ω output, 12.5 to 40V input, $100\mu\text{V}$ p-p noise | 0.02% | 0.01% | 0-5 | 0.1% | 20 mV* | LH0070-0 | | 7-4 |
| | | 0.02% | 0.02% | | 0.1% | 10 mV | LH0070-1 | | |
| | | 0.02% | 0.02% | | 0.05% | 4 mV | LH0070-2 | | |
| 10.024V Precision Binary Reference | | 0.02% | 0.01% | 0-5 | 0.1% | 20 mV* | LH0071-0 | | 7-4 |
| | | 0.02% | 0.02% | | 0.1% | 10 mV | LH0071-1 | | |
| | | 0.02% | 0.02% | | 0.05% | 4 mV | LH0071-2 | | |
| 6.95V Temperature Stabilized Reference | Thermostated two-terminal zener, 0.5Ω low noise | | 0.1% | 0.5-10 | +1%, -2% | 15 mV 1 mV | LM199A LM299A | | 7-23 |
| 6.9V Reference | Low noise subsurface zener 0.8Ω | | | 6-15 | 5% | 7 to 35 mV | LM129 | | 7-18 |

*These specifications apply for -25°C to $+85^\circ\text{C}$.

**Refers to Special Functions Databook, 1979 edition

LH0070 Series Precision BCD Buffered Reference LH0071 Series Precision Binary Buffered Reference

General Description

The LH0070 and LH0071 are precision, three terminal, voltage references consisting of a temperature compensated zener diode driven by a current regulator and a buffer amplifier. The devices provide an accurate reference that is virtually independent of input voltage, load current, temperature and time. The LH0070 has a 10.000V nominal output to provide equal step sizes in BCD applications. The LH0071 has a 10.240V nominal output to provide equal step sizes in binary applications.

The output voltage is established by trimming ultra-stable, low temperature drift, thin film resistors under actual operating circuit conditions. The devices are short-circuit proof in both the current sourcing and sinking directions.

The LH0070 and LH0071 series combine excellent long term stability, ease of application, and low cost,

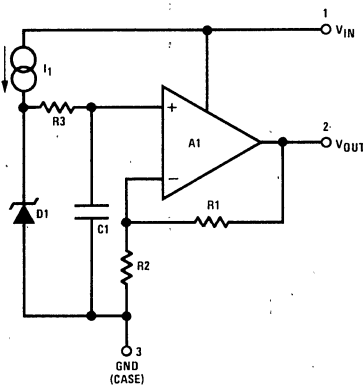
making them ideal choices as reference voltages in precision D to A and A to D systems.

Features

- Accurate output voltage

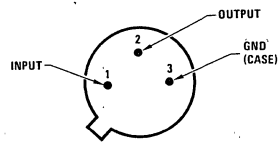
| | |
|--------|---------------|
| LH0070 | 10V ±0.01% |
| LH0071 | 10.24V ±0.01% |
- Single supply operation 12.5V to 40V
- Low output impedance 0.1Ω
- Excellent line regulation 0.1 mV/V
- Low zener noise 100 μVp-p
- 3-lead TO-5 (pin compatible with the LM109)
- Short circuit proof
- Low standby current 3 mA

Equivalent Schematic



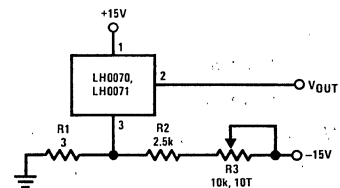
Connection Diagram

TO-39 Metal Can Package



BOTTOM VIEW

Order Number LH0070-1H, LH0071-1H,
LH0070-2H or LH0071-2H
See NS Package H03A

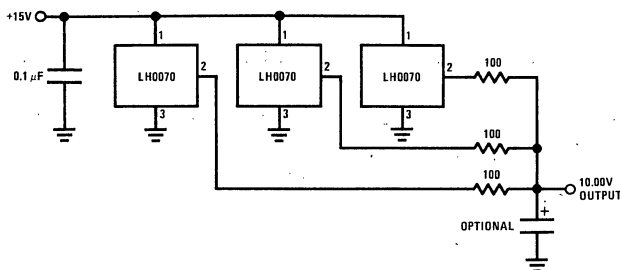


*Note. The output of the LH0070 and LH0071 may be adjusted to a precise voltage by using the above circuit since the supply current of the devices is relatively small and constant with temperature and input voltage. For the circuit shown, supply sensitivities are degraded slightly to 0.01%/V change in V_{OUT} for changes in V_{IN} and V_- .

An additional temperature drift of 0.0001%/°C is added due to the variation of supply current with temperature of the LH0070 and LH0071. Sensitivity to the value of R1, R2 and R3 is less than 0.001%/°.

*Output Voltage Fine Adjustment

Typical Applications



Statistical Voltage Standard

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 40V |
| Power Dissipation (See Curve) | 600 mW |
| Short Circuit Duration | Continuous |
| Output Current | ±20 mA |
| Operating Temperature Range | -55°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

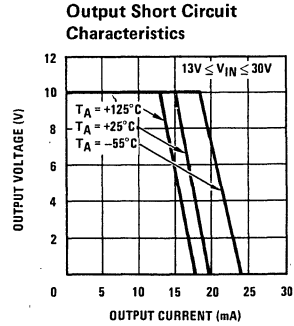
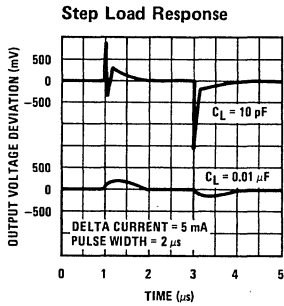
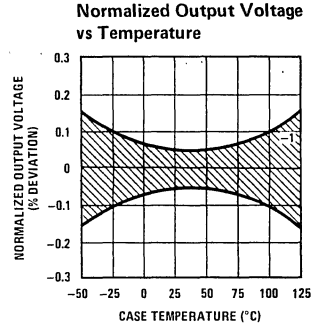
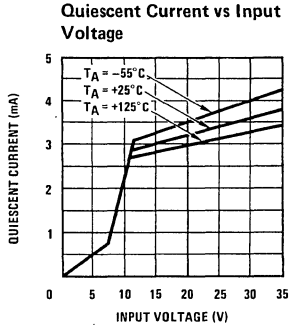
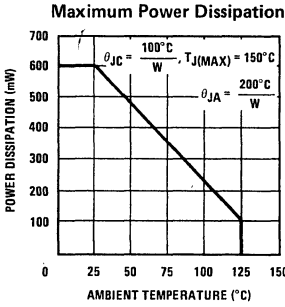
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|------|--------|-------|---------------------|
| Output Voltage | $T_A = 25^\circ\text{C}$ | | | | |
| LH0070 | | | 10.000 | | V |
| LH0071 | | | 10.240 | | V |
| Output Accuracy | $T_A = 25^\circ\text{C}$ | | | | |
| -0, -1 | | | ±0.03 | ±0.1 | % |
| -2 | | | ±0.02 | ±0.05 | % |
| Output Accuracy | | | | | |
| -0, -1 | | | | ±0.3 | % |
| -2 | | | | ±0.2 | % |
| Output Voltage Change With Temperature | (Note 2) | | | | |
| -0 | | | | ± 0.2 | % |
| -1 | | | ±0.02 | ± 0.1 | % |
| -2 | | | ±0.01 | ±0.04 | % |
| Line Regulation | $13\text{V} \leq V_{IN} \leq 33\text{V}, T_C = 25^\circ\text{C}$ | | | | |
| -0, -1 | | | 0.02 | 0.1 | % |
| -2 | | | 0.01 | 0.03 | % |
| Input Voltage Range | | 12.5 | | 40 | V |
| Load Regulation | $0\text{ mA} \leq I_{OUT} \leq 5\text{ mA}$ | | 0.01 | 0.03 | % |
| Quiescent Current | $13\text{V} \leq V_{IN} \leq 33\text{V}, I_{OUT} = 0\text{ mA}$ | 2 | 3 | 5 | mA |
| Change In Quiescent Current | $\Delta V_{IN} = 20\text{V}$ From 13V To 33V | | 0.75 | 1.5 | mA |
| Output Noise Voltage | $\text{BW} = 0.1\text{ Hz To } 10\text{ Hz}, T_A = 25^\circ\text{C}$ | | 20 | | μV_{p-p} |
| Ripple Rejection | $f = 120\text{ Hz}$ | | 0.01 | | $\%/V_{p-p}$ |
| Output Resistance | | | 0.2 | 1 | Ω |
| Long Term Stability | $T_A = 25^\circ\text{C}, (\text{Note } 3)$ | | | | |
| -0, -1 | | | | ±0.2 | %/yr. |
| -2 | | | | ±0.05 | %/yr. |

Note 1: Unless otherwise specified, these specifications apply for $V_{IN} = 15.0\text{V}$, $R_L = 10\text{ k}\Omega$, and over the temperature range of $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$.

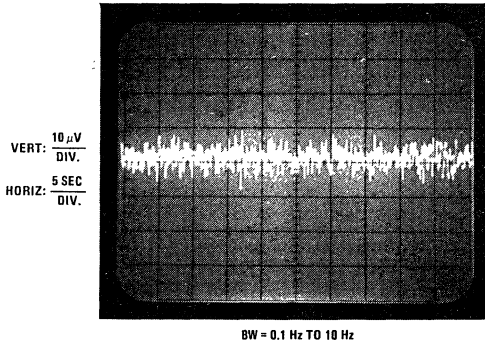
Note 2: This specification is the difference in output voltage measured at $T_A = 85^\circ\text{C}$ and $T_A = 25^\circ\text{C}$ or $T_A = 25^\circ\text{C}$ and $T_A = -25^\circ\text{C}$ with readings taken after test chamber and device-under-test stabilization at temperature using a suitable precision voltmeter.

Note 3: This parameter is guaranteed by design and not tested.

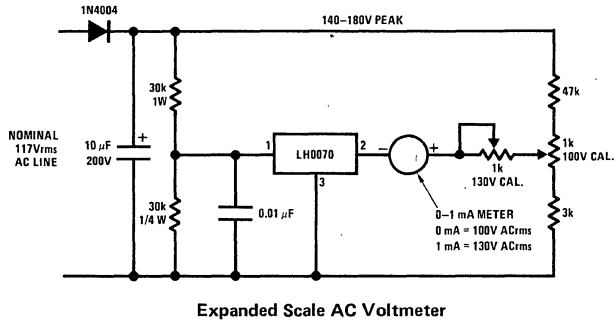
Typical Performance Characteristics



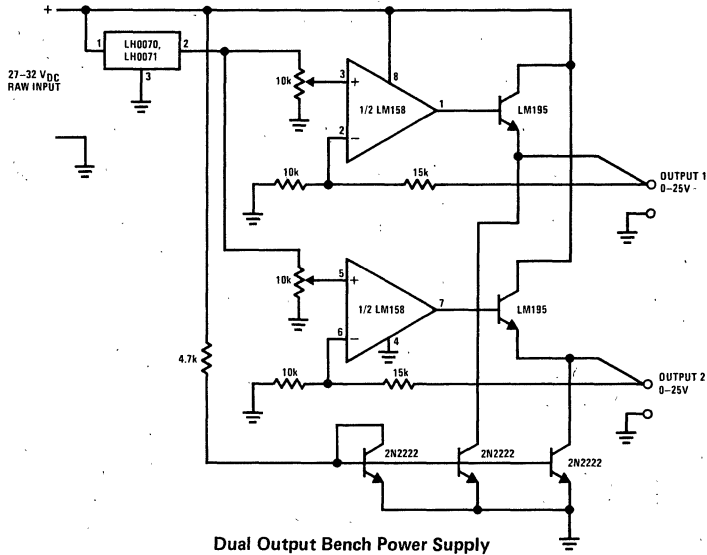
Noise Voltage



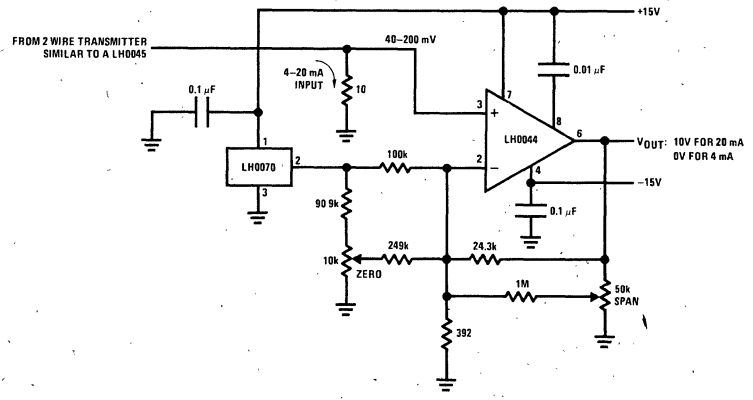
Typical Applications (Continued)



Typical Applications (Continued)



Dual Output Bench Power Supply



Precision Process Control Interface

LH0075 Positive Precision Programmable Regulator

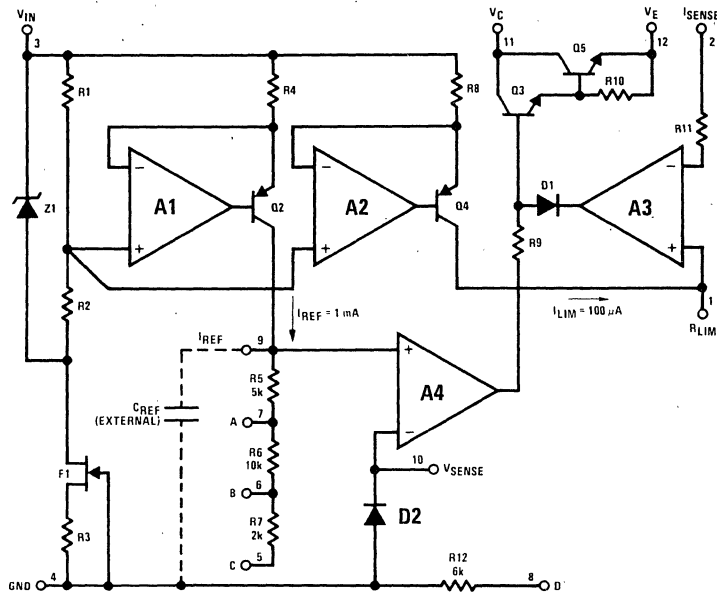
General Description

The LH0075 is a precision programmable regulator for positive voltages. Regulated output voltages from 0 to 27V may be obtained using one external resistor. Also available without any external components are several fixed regulated voltages with accuracies to 0.1% (5V, 6V, 10V, 12V and 15V). The output current limit is adjustable from 0 to 200 mA using two external resistors. These features provide an inventory of precision regulated values in one package.

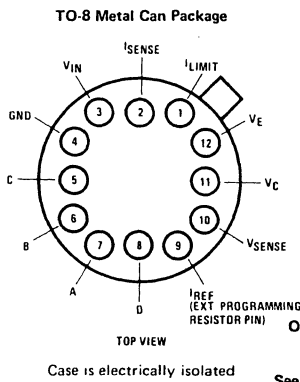
Features

- Output adjustable to 0V
- Line regulation typically 0.008%/V
- Load regulation typically 0.075%
- Remote voltage sensing
- Ripple rejection of 80 dB
- Adjustable precision current limit
- Output currents to 200 mA
- Popular voltages available without external resistors

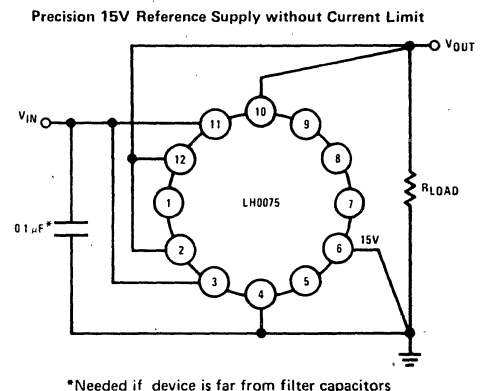
Schematic Diagram



Connection Diagram



Typical Applications



2

Absolute Maximum Ratings

| | |
|--|---------------------|
| Input Voltage | 32V |
| Output Voltage | 27V |
| Output Current | 200 mA |
| Power Dissipation | See Curve |
| Operating Temperature Range | T_{MIN} T_{MAX} |
| LH0075 | -55°C to +125°C |
| LH0075C | 0°C to +70°C |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

Unless otherwise specified conditions are for $T_{MIN} \leq T_A \leq T_{MAX}$

| PARAMETER | CONDITIONS | LH0075 | | | LH0075C | | | UNITS |
|--|---|--------|---------|-------|---------|---------|-------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$ | | 0.008 | 0.02 | | 0.008 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}$, $1\text{ mA} < I_{LOAD} < 200\text{ mA}$ $V_{OUT} \leq 5\text{V}$ $V_{OUT} \geq 5\text{V}$ | | 2.5 | 7.5 | | 2.5 | 15 | mV |
| | | | 0.055 | 0.15 | | 0.055 | 0.3 | % |
| | | | | | | | | |
| Reference Current (I_{REF}) | $T_A = 25^\circ\text{C}$, $V_{IN} = 15\text{V}$ | 0.998 | 1.000 | 1.002 | 0.995 | 1.00 | 1.005 | mA |
| Load Regulation | $1\text{ mA} < I_{LOAD} < 200\text{ mA}$ $V_{OUT} \leq 5\text{V}$ $V_{OUT} \geq 5\text{V}$ | | 4 | 15 | | 4 | 25 | mV |
| | | | 0.075 | 0.3 | | 0.075 | 0.5 | % |
| | | | | | | | | |
| Reference Current Drift ($\Delta I_{REF}/\Delta\text{Temp}$) | $V_{IN} = 15\text{V}$ | | -0.0065 | | | -0.0065 | | %/°C |
| Minimum Load Current (I_{LIM}) | (Note 1) | 98 | 100 | 102 | 95 | 100 | 105 | μA |
| Output Voltage Range | | 0 | | 27 | 0 | | 27 | V |
| Minimum Input Voltage | | 8 | | | 8 | | | V |
| Input-Output Differential Voltage | $T_A = 25^\circ\text{C}$, $1\text{ mA} < I_{LOAD} < 200\text{ mA}$ | | 3.0 | 3.2 | | 3.0 | 3.5 | V |
| Quiescent Supply Current | | | 6 | 6.5 | | 6.5 | 8 | mA |
| Ripple Rejection | $V_{OUT} = 5\text{V}$, $f = 120\text{ Hz}$ $C_{REF} = 2.2\ \mu\text{F}$ | | 65 | | | 65 | | dB |
| | | | 80 | | | 80 | | dB |
| Initial Output Voltage Tolerance | (Note 2) | | ±0.1 | ±0.5 | | ±0.1 | ±1.0 | % |
| Output Voltage Change with Temperature ($\Delta V_{OUT}/\Delta\text{Temp}$) | (Note 3) | | 0.003 | | | 0.003 | | %/°C |

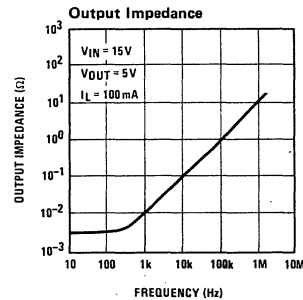
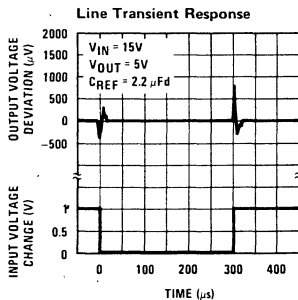
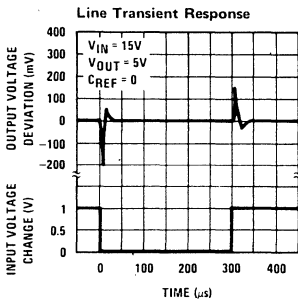
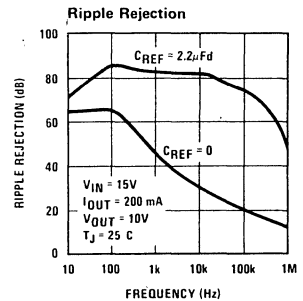
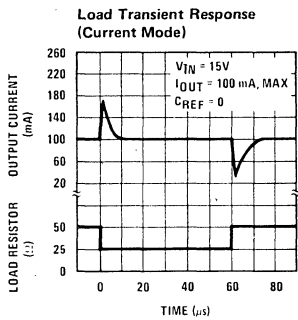
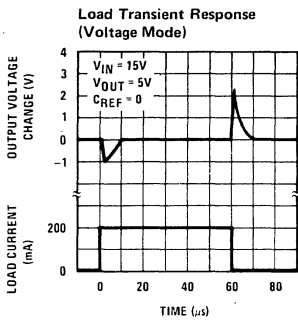
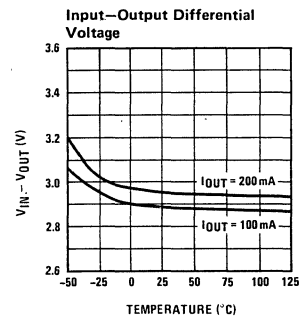
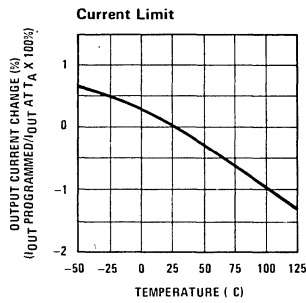
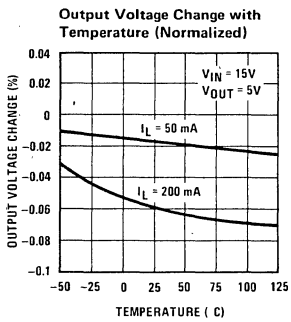
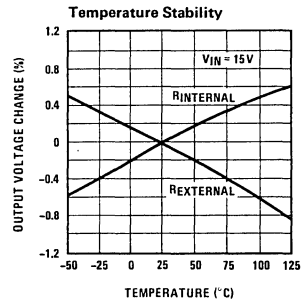
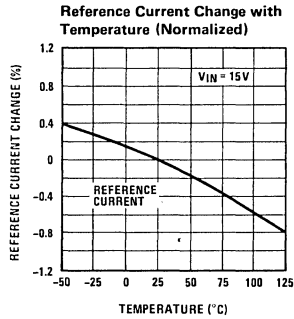
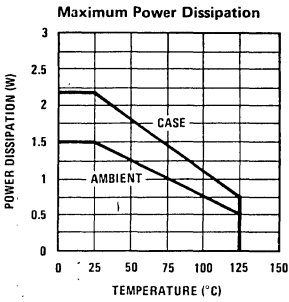
Note 1: Minimum load current is established by I_{LIM} , the current from Q4. (See schematic). I_{LIM} goes directly to the output if the current limit feature is used.

Note 2: For $V_{IN} = 15\text{V}$ and V_{OUT} obtained by using R5, R6, R7 and R12 individually.

Note 3: Total change over specified temperature range.

Typical Performance Characteristics

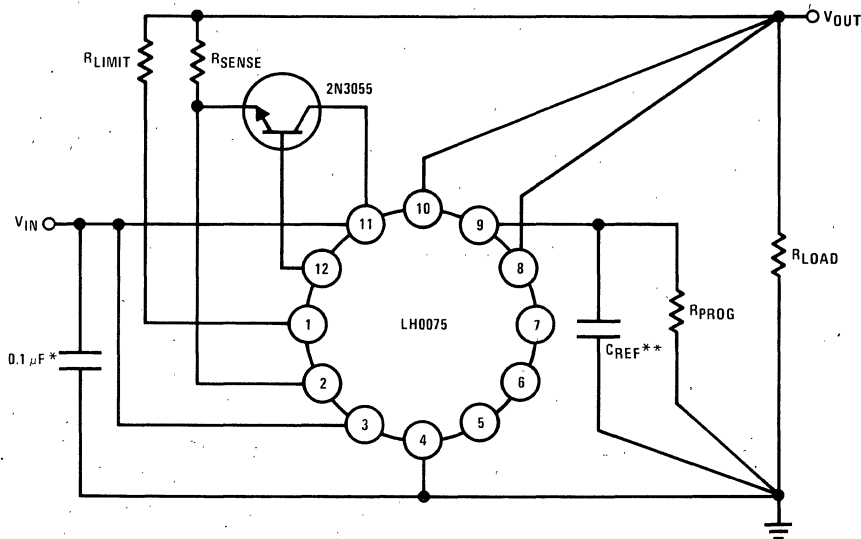
LH0075



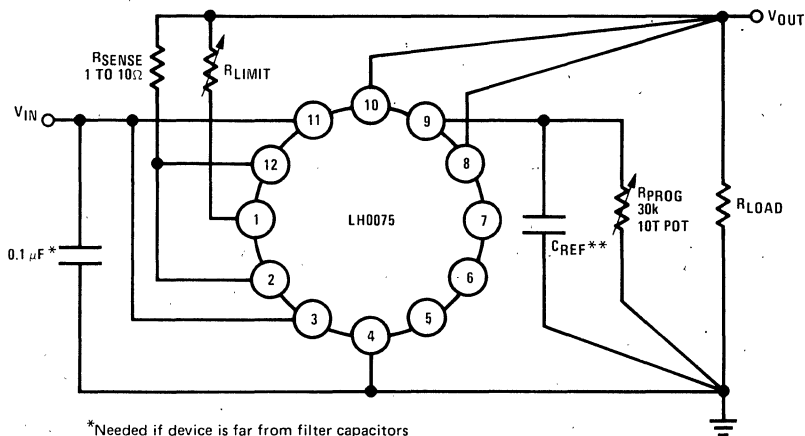
2

Typical Applications (Continued)

2A Regulator with Current Limit



Variable Voltage Reference with Current Limit



*Needed if device is far from filter capacitors

**Optional—improves transient response

$$R_{PROG} = \frac{V_{OUT \text{ Desired}}}{1 \text{ mA}}$$

$$I_{OUT(MAX)} = \left[\frac{R_{LIMIT}}{R_{SENSE}} + 1 \right] \times 100 \mu A$$

$$I_{OUT} \leq 200 \text{ mA}$$

Applications Information

The LH0075 does not require capacitors for stable operation, but an input bypass is recommended if device

is far from filter capacitors. A 0.1 μF for input bypassing should be adequate for almost all applications.

Applications Information (Continued)

DESCRIPTION OF OPTIONS

Ripple Rejection Compensation. (Increases Ripple Rejection Typically to 80 dB)

The ripple rejection may be improved by connecting an external capacitor between pin 9 and ground. (The typical performance curves show the rejection with a capacitance of 2.2 μ Fd.)

Internal Voltage Programming

The LH0075 provides various precision output voltages simply by using one or more of the internal resistors. A particular voltage may be obtained by external connections as shown in Table I.

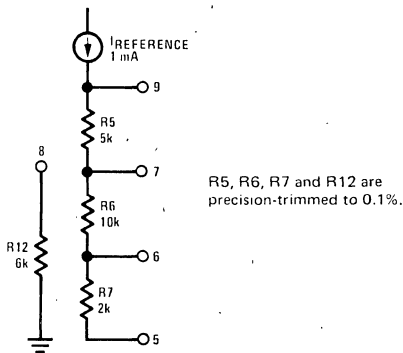


FIGURE 1

External Voltage Programming

An external resistance can be connected between pin 9 and ground to obtain any voltage from 0 to 27V using the following equation:

$$R_{EXT} = \frac{V_{OUT \text{ Desired}}}{1 \text{ mA}}$$

The reference current (I_{REF}) has a typical temperature coefficient of $-65 \text{ ppm}/^\circ\text{C}$. Choosing a resistive material with a temperature coefficient of $65 \text{ ppm}/^\circ\text{C}$ will compensate the negative temperature coefficient, resulting in an output voltage with minimal change over the operating temperature range. Example of a good resistive material is Nichrome, which has a typical temperature coefficient of $80 \text{ ppm}/^\circ\text{C}$.

Since a current source is used as a reference, this makes remote voltage programming possible.

Current Limit Programming

The maximum current output of the device may be limited by adding two external resistors as shown below. The resistor values are easily calculated with the following equation:

$$I_{OUT(MAX)} = \left[\frac{R_{LIMIT}}{R_{SENSE}} + 1 \right] \times 100 \mu\text{A}$$

where $R_{SENSE} = 1$ to 10Ω

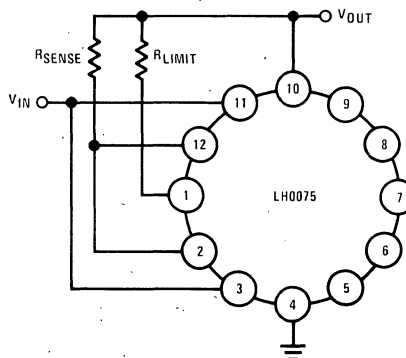


FIGURE 2. Current Limit Programming

This programmable current limit feature can be extended to make the LH0075 a programmable constant current source. This can be done by leaving pin 9 open and setting R_{LIMIT} and R_{SENSE} as desired.

For applications where the current limit is used, a minimum load current of $100 \mu\text{A}$ is established at the output. This arises from the fact that the constant current used in setting maximum output current is $100 \mu\text{A}$, and it goes directly to the output of the LH0075. If the total current drawn from the output is less than the minimum, the output will rise.

As in the remote voltage adjustment application, remote current sensing can be applied similarly. R_{SENSE} must be placed as close to the output of the LH0075 as possible, but R_{LIMIT} can be a fixed resistor or potentiometer located remotely from the device.

TABLE I. Connection Scheme for Internal Available Output Voltages

| OUTPUT VOLTAGE (V) | PIN 5 | PIN 6 | PIN 7 | PIN 8 | PIN 9 |
|--------------------|--------|-------|--------|--------|--------|
| 5 | | | Gnd | | |
| 6 | | | | -----● | -----● |
| 8 | -----● | | | -----● | -----● |
| 10 | | Gnd | -----● | -----● | -----● |
| 12 | Gnd | | -----● | -----● | -----● |
| 15 | | Gnd | | | |
| 18 | -----● | | -----● | -----● | -----● |

LH0076 Negative Precision Programmable Regulator

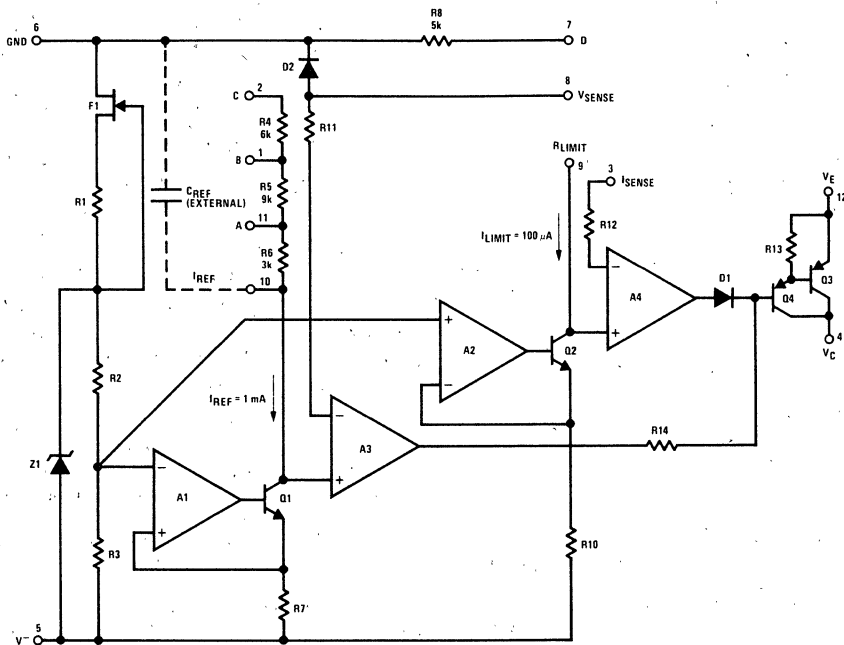
General Description

The LH0076 is a precision programmable regulator for negative voltages. Regulated output voltages from 0 to -27V may be obtained by using 1 external resistor. Also available without any external components are several fixed regulated voltages with accuracies to 0.1% (-3V, -5V, -6V, -8V, -9V, -12V, -15V and -18V). The output current limit is adjustable from 0 to 200 mA using 2 external resistors. These features provide an inventory of precision regulated values in 1 package.

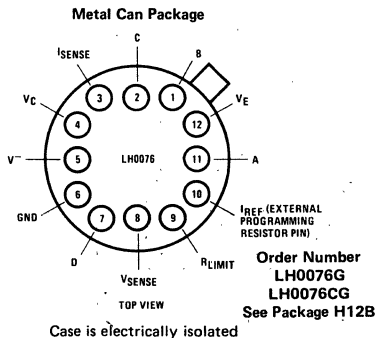
Features

- Line regulation typically 0.005%/V
- Load regulation typically 0.02%
- Remote voltage sensing
- Ripple rejection -70 dB
- Output Adjustable to 0V
- Adjustable precision current limit
- Output current to 200 mA

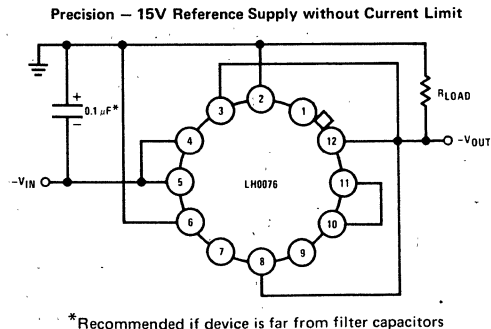
Schematic Diagram



Connection Diagram



Typical Application



Absolute Maximum Ratings

| | |
|--|-----------------|
| Input Voltage | -32V |
| Output Voltage | -27V |
| Output Current | 200 mA |
| Power Dissipation | See Curve |
| Operating Temperature | |
| LH0076 | -55°C to +125°C |
| LH0076C | -25°C to +85°C |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

Conditions are for $T_{MIN} \leq T_A \leq T_{MAX}$ unless otherwise specified.

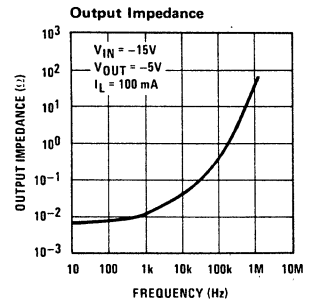
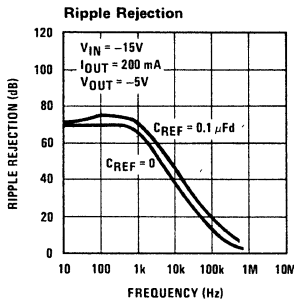
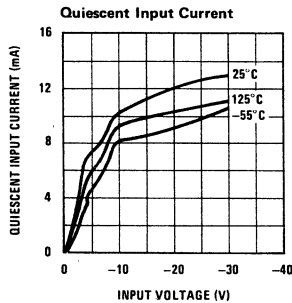
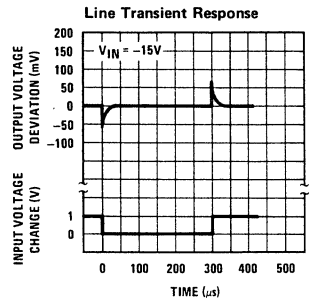
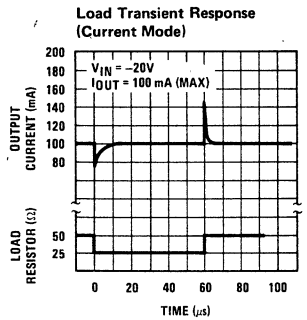
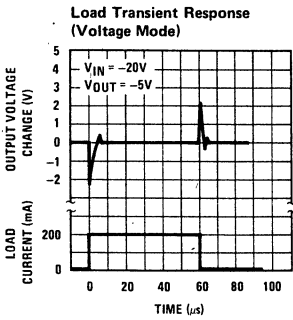
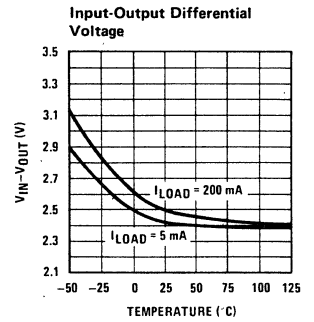
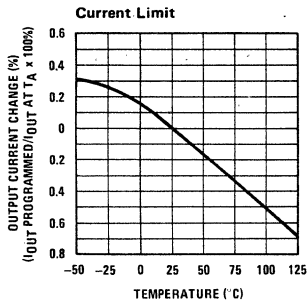
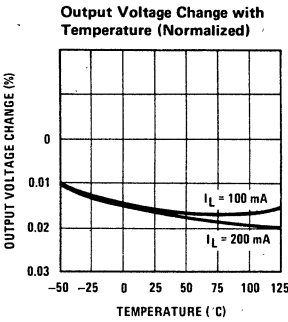
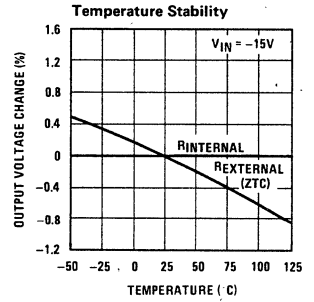
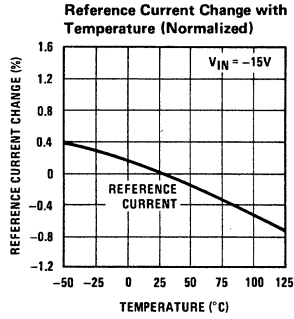
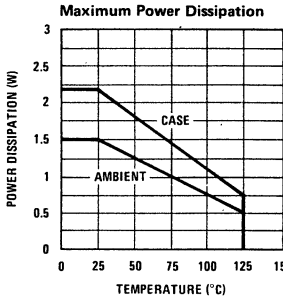
| PARAMETER | CONDITIONS | LH0076 | | | LH0076C | | | UNITS |
|--|--|--------|---------|-----------|---------|-----------|-----------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Line Regulation | $T_A = 25^\circ\text{C}$ | | 0.005 | 0.02 | | 0.005 | 0.04 | %/V |
| Load Regulation | $T_A = 25^\circ\text{C}, 1\text{ mA} < I_{LOAD} < 200\text{ mA}$ $V_{OUT} \geq -5\text{V}$ $V_{OUT} \leq -5\text{V}$ | | | 7.5 | | | 15 | mV |
| | | | 0.02 | 0.15 | | 0.02 | 0.3 | % |
| Reference Current (I_{REF}) | $T_A = 25^\circ\text{C}, V_{IN} = -15\text{V}$ | 0.998 | 1.000 | 1.002 | 0.995 | 1.000 | 1.005 | mA |
| Reference Current Drift ($\Delta I_{REF} / \Delta\text{Temp}$) | $V_{IN} = -15\text{V}$ | | -0.0065 | | | -0.0065 | | %/°C |
| Minimum Load Current (I_{LIM}) | (Note 1) | 98 | 100 | 102 | 95 | 100 | 105 | μA |
| Output Voltage Range | | 0 | | -27 | 0 | | -27 | V |
| Minimum Input Voltage | | -8 | | | -8 | | | V |
| Input-Output Differential Voltage | $T_A = 25^\circ\text{C}, 1\text{ mA} < I_{LOAD} < 200\text{ mA}$ | | 2.7 | 3.2 | | 2.7 | 3.5 | V |
| Quiescent Supply Current | | | 9 | 10 | | 9 | 11 | mA |
| Ripple Rejection | $V_{OUT} = -5\text{V}, f = 120\text{ Hz}$ | | 70 | | | 70 | | dB |
| Initial Output Voltage Tolerance | $T_A = 25^\circ\text{C}$, (Note 2) | | +0.1 | ± 0.5 | | ± 0.1 | ± 1.0 | % |
| Output Voltage Change with Temperature | (Note 3) | | 0.003 | | | 0.003 | | %/°C |

Note 1: Minimum load current is established by I_{LIM} , the current to Q2 (see schematic). I_{LIM} draws directly from the output if current limit feature is used.

Note 2: For $V_{IN} = -15\text{V}$ and V_{OUT} obtained by using R4, R5, R6 and R8 individually.

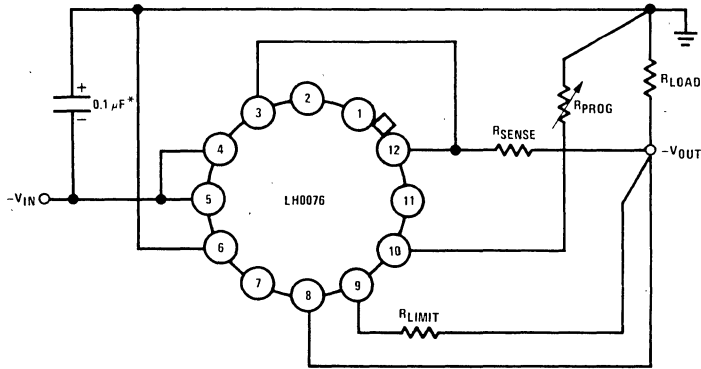
Note 3: Total change over specified temperature range.

Typical Performance Characteristics

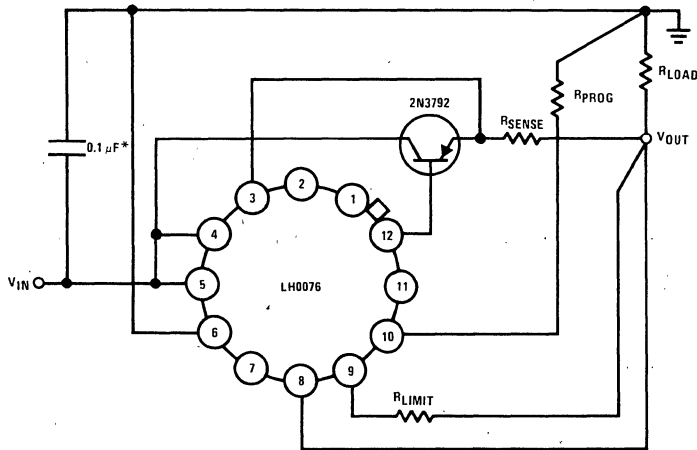


Typical Application (Continued)

Variable Voltage Reference with Current Limit



2-Amp Regulator with Current Limit



*Recommended if device is far from filter capacitors

Application Information

The LH0076 does not require external capacitors for stable operation. However, an input bypass is recommended if the device is far from filter capacitors. A 0.1 μF for input bypassing should be adequate for most applications.

DESCRIPTION OF OPTIONS

External Voltage Programming

An external resistance can be connected between pin 10 and ground to obtain any voltage from 0 to -27V using the following equation:

$$R_{EXT} = \frac{V_{OUT \text{ desired}}}{-1 \text{ mA}}$$

The reference current (I_{REF}) has a typical temperature coefficient of -60 ppm/°C. Choosing a resistive material with a temperature coefficient of 60 ppm/°C will compensate the negative tempco of the reference current, resulting in an output voltage with minimal change over the operating temperature range. Example of a good resistive material is nichrome, which has a typical tempco of 80 ppm/°C. Nichrome is the resistive material used in the LH0076, resulting in output voltage drift of 20 ppm/°C typically.

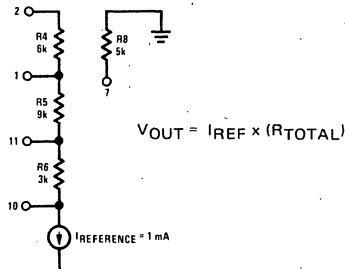
Application Information (Continued)

Because a current source is used as a reference, remote voltage programming is possible.

Internal Voltage Programming

The LH0076 provides various precision output voltages simply by using 1 or more of the internal programming resistors. These voltages may be obtained by using the connections as shown in Table I.

R_{TOTAL} is the total resistance between pin 10 and ground



R4, R5, R6 and R8 are precision trimmed to 0.1%

FIGURE 1

Current Limit Programming

The maximum current output of the device may be limited by adding 2 external resistors as shown in Figure 2. The resistor values are calculated using the following equation:

$$I_{OUT(MAX)} = \left[\frac{R_{LIMIT}}{R_{SENSE}} + 1 \right] \times 100 \mu A$$

where $R_{SENSE} = 1$ to 10Ω

This programming current limit feature can be extended to make the LH0076 a programmable current sink. This can be done by leaving pin 10 open and setting R_{LIMIT} and R_{SENSE} as desired. (See Figure 3).

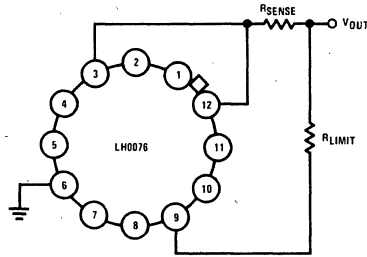


FIGURE 2. Current Limit Programming

For applications where the current limit is used, a minimum load current of $100 \mu A$ is established at the output. This arises from the fact that the constant current used in setting maximum output current is $100 \mu A$, and it comes directly from the output of the LH0076. If the total load current is less than this minimum current, the output will drop.

As in the remote voltage adjustment application, remote current sensing can be applied similarly. R_{SENSE} should be placed as close to the output of the LH0076 as possible, but R_{LIMIT} can be a resistor or potentiometer located remotely from the device.

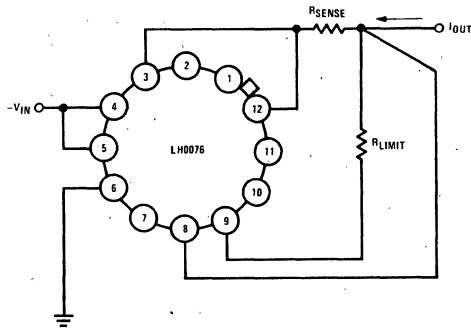


FIGURE 3. Precision Current Sink

TABLE I. Connection Scheme for Internally Available Output Voltages

| OUTPUT VOLTAGE (V) | PIN 1 | PIN 2 | PIN 7 | PIN 10 | PIN 11 |
|--------------------|-------|-------|-------|--------|--------|
| -3 | | | | | Gnd |
| -5 | | | ————— | ————— | |
| -6 | ————— | Gnd | ————— | ————— | |
| -8 | | | ————— | ————— | ————— |
| -9 | Gnd | | | ————— | ————— |
| -12 | Gnd | | | | |
| -15 | | Gnd | | ————— | ————— |
| -18 | | Gnd | | | |

LM103 Reference Diode**

General Description

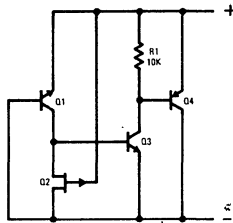
The LM103 is a two-terminal monolithic reference diode electrically equivalent to a breakdown diode. The device makes use of the reverse punch-through of double-diffused transistors, combined with active circuitry, to produce a breakdown characteristic which is ten times sharper than single-junction zener diodes at low voltages. Breakdown voltages from 1.8V to 5.6V are available; and, although the design is optimized for operation between 100 μ A and 1 mA, it is completely specified from 10 μ A to 10 mA. Noteworthy features of the device are:

- Exceptionally sharp breakdown
- Low dynamic impedance from 10 μ A to 10 mA

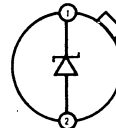
- Performance guaranteed over full military temperature range
- Planar, passivated junctions for stable operation
- Low capacitance.

The LM103, packaged in a hermetically sealed, modified TO-46 header is useful in a wide range of circuit applications from level shifting to simple voltage regulation. It can also be employed with operational amplifiers in producing breakpoints to generate nonlinear transfer functions. Finally, its unique characteristics recommend it as a reference element in low voltage power supplies with input voltages down to 4V.

Schematic and Connection Diagrams



Metal Can Package

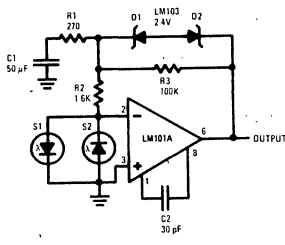


Note: Pin 2 connected to case.
TOP VIEW

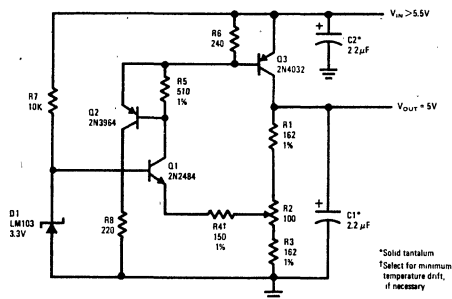
Order Number LM103H
See NS Package H02A

Typical Applications

Saturating Servo Preampifier
with Rate Feedback



200 mA Positive Regulator



*Solid tantalum
†Select for minimum
temperature drift,
if necessary

**Covered by U.S. Patent Number 3,571,630

Absolute Maximum Ratings

| | |
|--------------------------------------|----------------|
| Power Dissipation (note 1) | 250 mW |
| Reverse Current | 20 mA |
| Forward Current | 100 mA |
| Operating Temperature Range | -55°C to 125°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (soldering, 60 sec) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|--|---|-----|------|-----|----------------------------|
| Reverse Breakdown Voltage Change | $10 \mu\text{A} \leq I_R \leq 100 \mu\text{A}$ | | 60 | 120 | mV |
| | $100 \mu\text{A} \leq I_R \leq 1 \text{ mA}$ | | 15 | 50 | mV |
| | $1 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | | 50 | 150 | mV |
| Reverse Dynamic Impedance (Note 3) | $I_R = 3 \text{ mA}$ | | 5 | 25 | Ω |
| | $I_R = 0.3 \text{ mA}$ | | 15 | 60 | Ω |
| Reverse Leakage Current | $V_R = V_Z - 0.2\text{V}$ | | 2 | 5 | μA |
| Forward Voltage Drop | $I_F = 10 \text{ mA}$ | 0.7 | 0.8 | 1.0 | V |
| Peak-to-Peak Broadband Noise Voltage | $10 \text{ Hz} \leq f \leq 100 \text{ kHz}, I_R = 1 \text{ mA}$ | | 300 | | μV |
| Reverse Breakdown Voltage Change with Current (Note 4) | $10 \mu\text{A} \leq I_R \leq 100 \mu\text{A}$ | | | 200 | mV |
| | $100 \mu\text{A} \leq I_R \leq 1 \text{ mA}$ | | | 60 | mV |
| | $1 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | | | 200 | mV |
| Breakdown Voltage Temperature Coefficient (Note 4) | $100 \mu\text{A} \leq I_R \leq 1 \text{ mA}$ | | -5.0 | | $\text{mV}/^\circ\text{C}$ |

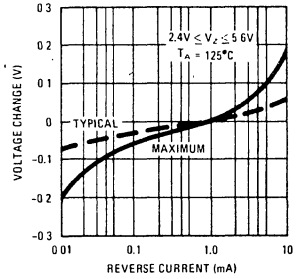
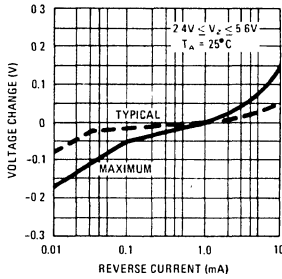
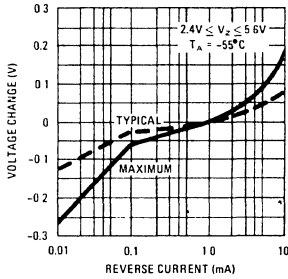
Note 1: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 80°C/W junction to case or 440°C/W junction to ambient (see curve).

Note 2: These specifications apply for $T_A = 25^\circ\text{C}$ and $1.8\text{V} < V_Z < 5.6\text{V}$ unless stated otherwise. The diode should not be operated with shunt capacitances between 100 pF and 0.01 μF , unless isolated by at least a 300 Ω resistor, as it may oscillate at some currents.

Note 3: Measured with the peak-to-peak change of reverse current equal to 10% of the DC reverse current.

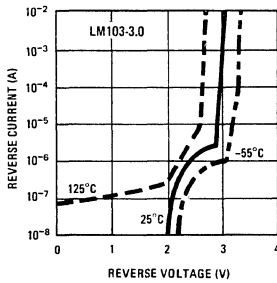
Note 4: These specifications apply for $-55^\circ\text{C} < T_A < +125^\circ\text{C}$.

Guaranteed Reverse Characteristics

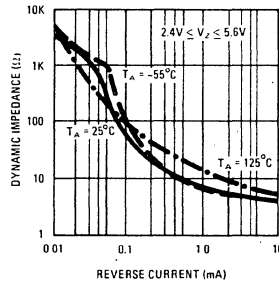


Typical Performance Characteristics

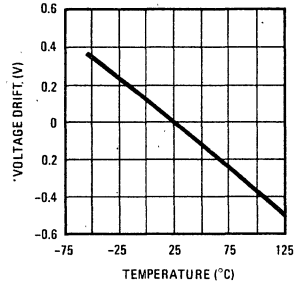
Reverse Characteristics



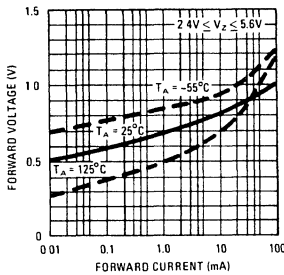
Reverse Dynamic Impedance



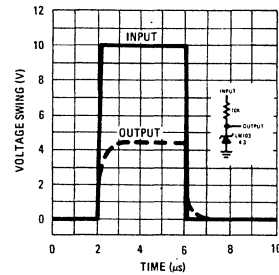
Temperature Drift



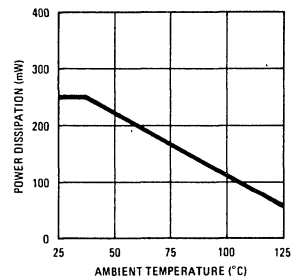
Forward Characteristics



Response Time



Maximum Power Dissipation



BREAKDOWN VOLTAGE*

- 1.8
- 2.0
- 2.2
- 2.4
- 2.7
- 3.0
- 3.3
- 3.6
- 3.9
- 4.3
- 4.7
- 5.1
- 5.6

PART NUMBER

- LM103H-1.8
- LM103H-2.0
- LM103H-2.2
- LM103H-2.4
- LM103H-2.7
- LM103H-3.0
- LM103H-3.3
- LM103H-3.6
- LM103H-3.9
- LM103H-4.3
- LM103H-4.7
- LM103H-5.1
- LM103H-5.6

*Measured at I_R = 1 mA.
Standard tolerance is ±10%.

LM113/LM313 Reference Diode

General Description

The LM113/LM313 are temperature compensated, low voltage reference diodes. They feature extremely-tight regulation over a wide range of operating currents in addition to an unusually-low breakdown voltage and good temperature stability.

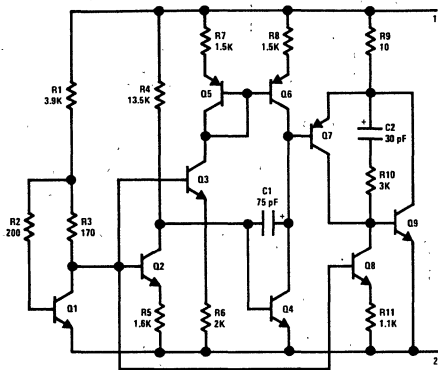
The diodes are synthesized using transistors and resistors in a monolithic integrated circuit. As such, they have the same low noise and long term stability as modern IC op amps. Further, output voltage of the reference depends only on highly-predictable properties of components in the IC; so they can be manufactured and supplied to tight tolerances. Outstanding features include:

- Low breakdown voltage: 1.220V

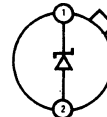
- Dynamic impedance of 0.3Ω from $500\mu\text{A}$ to 20mA
- Temperature stability typically 1% over -55°C to 125°C range (LM113), 0°C to 70°C (LM313)
- Tight tolerance: $\pm 5\%$ standard; $\pm 2\%$ and $\pm 1\%$ on special order.

The characteristics of this reference recommend it for use in bias-regulation circuitry, in low-voltage power supplies or in battery powered equipment. The fact that the breakdown voltage is equal to a physical property of silicon—the energy-band-gap voltage—makes it useful for many temperature-compensation and temperature-measurement functions.

Schematic and Connection Diagrams



Metal Can Package

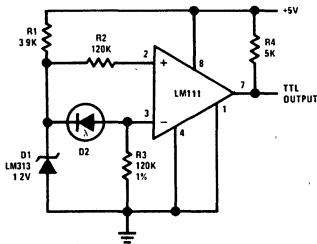


Note: Pin 2 connected to case...
TOP VIEW

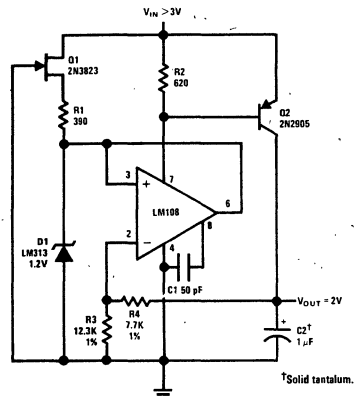
Order Number LM113H or LM313H
See NS Package H02A

Typical Applications

Level Detector for Photodiode



Low Voltage Regulator



Absolute Maximum Ratings

Operating Conditions

| | | | MIN | MAX | UNITS |
|--|-----------------|-------------------------------|-----|------|-------|
| Power Dissipation (Note 1) | 100 mW | Temperature (T _A) | | | |
| Reverse Current | 50 mA | LM113 | -55 | +125 | °C |
| Forward Current | 50 mA | LM313 | 0 | 70 | °C |
| Storage Temperature Range | -65°C to +150°C | | | | |
| Lead Temperature (Soldering, 10 seconds) | 300°C | | | | |

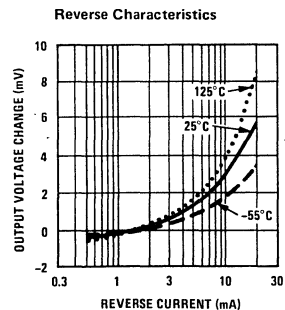
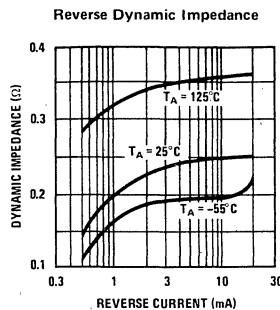
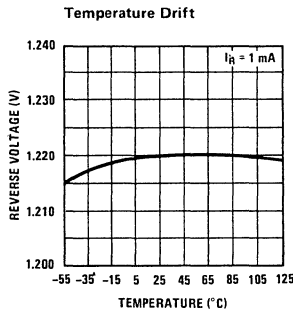
Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|-------|-------|-------|-------|
| Reverse Breakdown Voltage LM113/LM313 LM113-1 LM113-2 | I _R = 1 mA | 1.160 | 1.220 | 1.280 | V |
| | | 1.210 | 1.22 | 1.232 | V |
| | | 1.195 | 1.22 | 1.245 | V |
| Reverse Breakdown Voltage Change | 0.5 mA ≤ I _R ≤ 20 mA | | 6.0 | 15 | mV |
| Reverse Dynamic Impedance | I _R = 1 mA I _R = 10 mA | | 0.2 | 1.0 | Ω |
| | | | 0.25 | 0.8 | Ω |
| Forward Voltage Drop | I _F = 1.0 mA | | 0.67 | 1.0 | V |
| RMS Noise Voltage | 10 Hz ≤ f ≤ 10 kHz I _R = 1 mA | | 5 | | μV |
| Reverse Breakdown Voltage Change with Current | 0.5 mA ≤ I _R ≤ 10 mA T _{MIN} ≤ T _A ≤ T _{MAX} | | | 15 | mV |
| Breakdown Voltage Temperature Coefficient | 1.0 mA ≤ I _R ≤ 10 mA T _{MIN} ≤ T _A ≤ T _{MAX} | | 0.01 | | %/°C |

Note 1: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction and a thermal resistance of 80°C/W junction to case or 440°C/W junction to ambient.

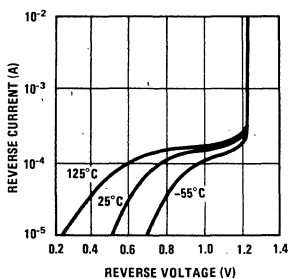
Note 2: These specifications apply for T_A = 25°C, unless stated otherwise. At high currents, breakdown voltage should be measured with lead lengths less than 1/4 inch. Kelvin contact sockets are also recommended. The diode should not be operated with shunt capacitances between 200 pF and 0.1 μF, unless isolated by at least a 100 Ω resistor, as it may oscillate at some currents.

Typical Performance Characteristics

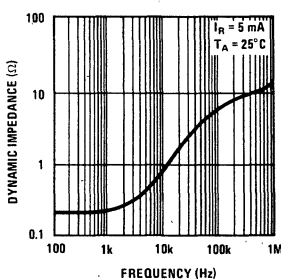


Typical Performance Characteristics (Continued)

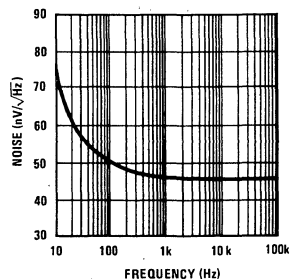
Reverse Characteristics



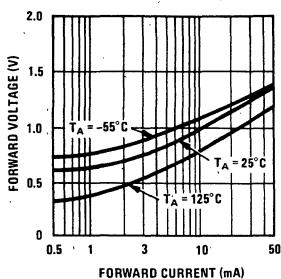
Reverse Dynamic Impedance



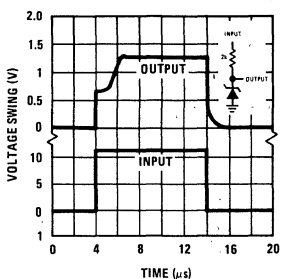
Noise Voltage



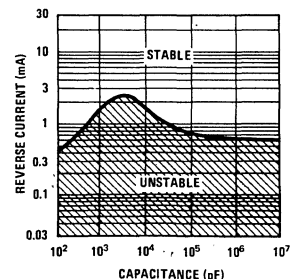
Forward Characteristics



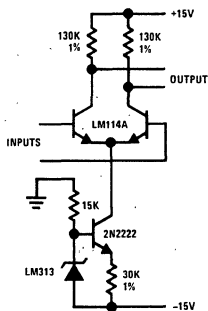
Response Time



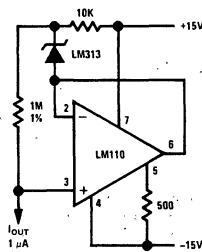
Maximum Shunt Capacitance



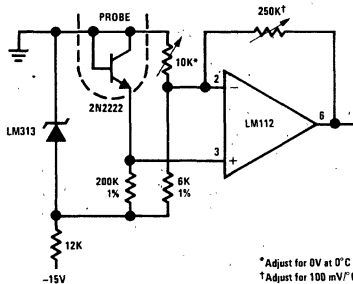
Typical Applications (Continued)



Amplifier Biasing for Constant Gain with Temperature



Constant Current Source



* Adjust for 0V at 0°C
 † Adjust for 100 mV/°C

Thermometer

LM129/LM329 Precision Reference

General Description

The LM129 and LM329 family are precision multi-current temperature compensated 6.9V zener references with dynamic impedances a factor of 10 to 100 less than discrete diodes. Constructed in a single silicon chip, the LM129 uses active circuitry to buffer the internal zener allowing the device to operate over a 0.5 mA to 15 mA range with virtually no change in performance. The LM129 and LM329 are available with selected temperature coefficients of 0.001, 0.002, 0.005 and 0.01%/°C. These new references also have excellent long term stability and low noise.

A new subsurface breakdown zener used in the LM129 gives lower noise and better long term stability than conventional IC zeners. Further the zener and temperature compensating transistor are made by a planar process so they are immune to problems that plague ordinary zeners. For example, there is virtually no voltage shifts in zener voltage due to temperature cycling and the device is insensitive to stress on the leads.

The LM129 can be used in place of conventional zeners with improved performance. The low dynamic impedance

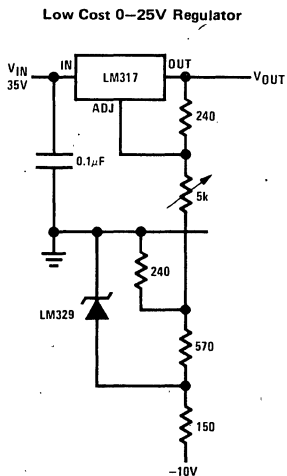
simplifies biasing and the wide operating current allows the replacement of many zener types.

The LM129 is packaged in a 2-lead TO-46 package and is rated for operation over a -55°C to $+125^{\circ}\text{C}$ temperature range. The LM329 for operation over $0-70^{\circ}\text{C}$ is available in both a hermetic TO-46 package and a TO-92 epoxy package.

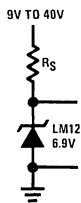
Features

- 0.6 mA to 15 mA operating current
- 0.6Ω dynamic impedance at any current
- Available with temperature coefficients of 0.001%/°C
- $7\mu\text{V}$ wideband noise
- 5% initial tolerance
- 0.002% long term stability
- Low cost
- Subsurface zener

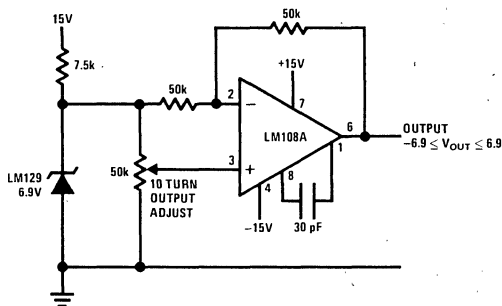
Typical Applications



Simple Reference



Adjustable Bipolar Output Reference



Absolute Maximum Ratings

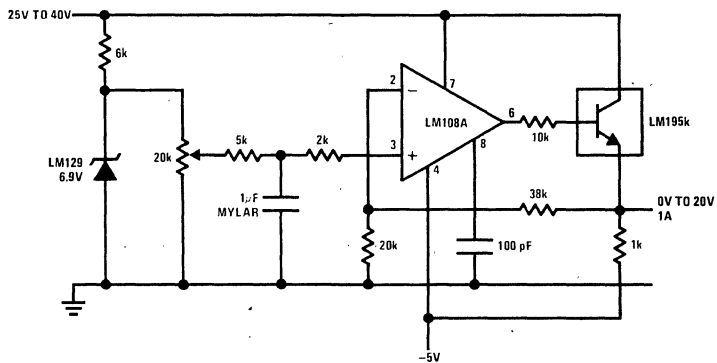
| | |
|--|-----------------|
| Reverse Breakdown Current | 30 mA |
| Forward Current | 2 mA |
| Operating Temperature Range | |
| LM129 | -55°C to +125°C |
| LM329 | 0°C to +70°C |
| Storage Temperature Range | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM129A, B, C | | | LM329B, C, D | | | UNITS |
|---|---|--------------|-----|-----|--------------|-----|------|-----------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Reverse Breakdown Voltage | $T_A = 25^\circ\text{C}$, $0.6\text{ mA} \leq I_R \leq 15\text{ mA}$ | 6.7 | 6.9 | 7.2 | 6.6 | 6.9 | 7.25 | V |
| Reverse Breakdown Change with Current | $T_A = 25^\circ\text{C}$, $0.6\text{ mA} \leq I_R \leq 15\text{ mA}$ | | 9 | 14 | | 9 | 20 | mV |
| Reverse Dynamic Impedance | $T_A = 25^\circ\text{C}$, $I_R = 1\text{ mA}$ | | 0.6 | 1 | | 0.8 | 2 | Ω |
| RMS Noise | $T_A = 25^\circ\text{C}$, $10\text{ Hz} \leq F \leq 10\text{ kHz}$ | | 7 | 20 | | 7 | 100 | μV |
| Long Term Stability | $T_A = 45^\circ\text{C} \pm 0.1^\circ\text{C}$, $I_R = 1\text{ mA} \pm 0.3\%$ | | 20 | | | 20 | | ppm |
| Temperature Coefficient | $I_R = 1\text{ mA}$ | | | | | | | |
| LM129A, LM329A | | | 6 | 10 | | 6 | 10 | ppm/ $^\circ\text{C}$ |
| LM129B, LM329B | | | 15 | 20 | | 15 | 20 | ppm/ $^\circ\text{C}$ |
| LM129C, LM329C | | | 30 | 50 | | 30 | 50 | ppm/ $^\circ\text{C}$ |
| LM329D | | | | | | 50 | 100 | ppm/ $^\circ\text{C}$ |
| Change In Reverse Breakdown Temperature Coefficient | $1\text{ mA} \leq I_R \leq 15\text{ mA}$ | | 1 | | | 1 | | ppm/ $^\circ\text{C}$ |
| Reverse Breakdown Change with Current | $1\text{ mA} \leq I_R \leq 15\text{ mA}$ | | 12 | | | 12 | | mV |
| Reverse Dynamic Impedance | $1\text{ mA} \leq I_R \leq 15\text{ mA}$ | | 0.8 | | | 1 | | Ω |

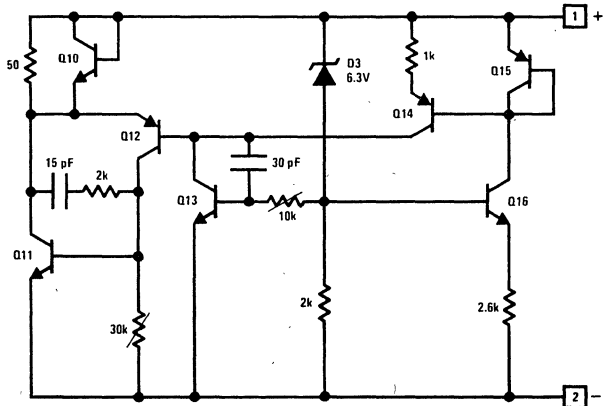
Note 1: These specifications apply for $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LM129 and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ for the LM329 unless otherwise specified. The maximum junction temperature for an LM129 is 150°C and LM329 is 100°C . For operating at elevated temperature, devices in TO-46 package must be derated based on a thermal resistance of 440°C/W junction to ambient or 80°C/W junction to case. For the TO-92 package, the derating is based on 180°C/W junction to ambient with 0.4" leads from a PC board and 160°C/W junction to ambient with 0.125" lead length to a PC board.

0V to 20V Power Reference

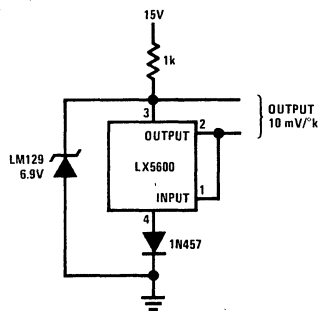


2

Reference

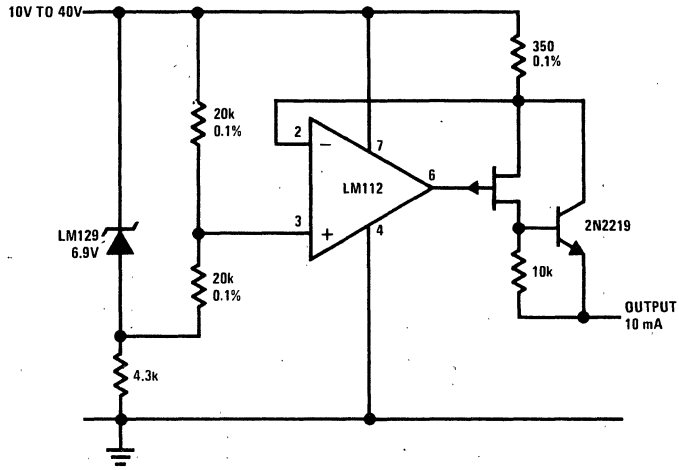


External Reference for Temperature Transducer

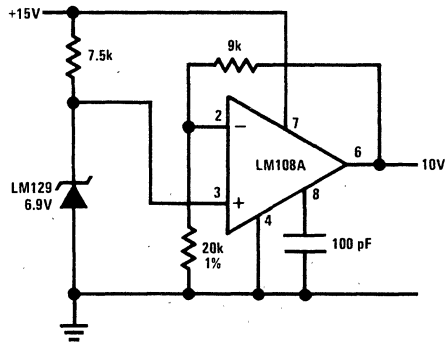


Typical Applications (Continued)

Positive Current Source

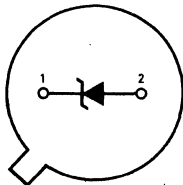


Buffered Reference with Single Supply



Connection Diagrams

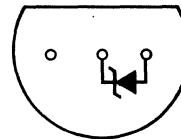
Metal Can Package



BOTTOM VIEW

Order Number LM129AH, LM129BH
LM129CH, LM329AH, LM329BH, LM329CH
or LM329DH
See NS Package H02A

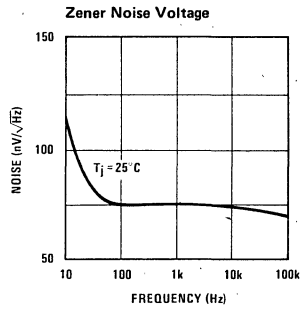
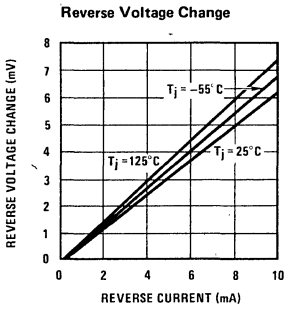
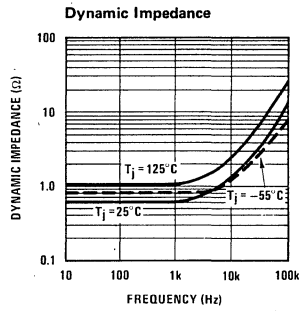
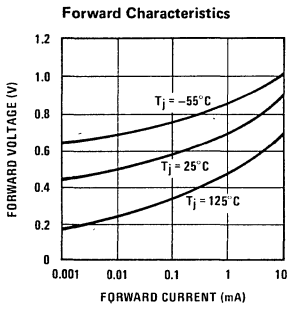
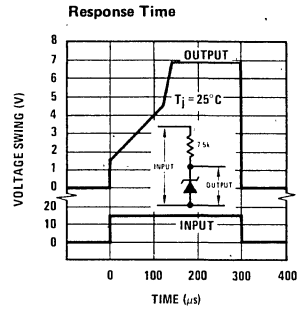
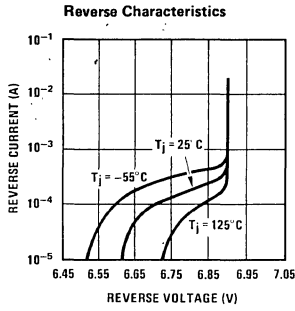
Plastic Package



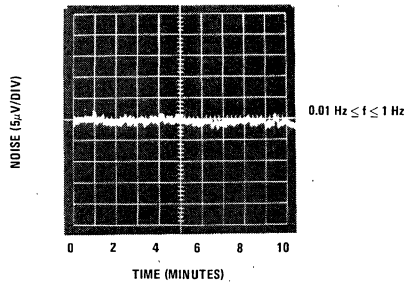
BOTTOM VIEW

Order Number LM329BZ, LM329CZ
or LM329DZ
See NS Package Z03A

Typical Performance Characteristics



Low Frequency Noise Voltage





LM136/LM236/LM336 2.5V Reference Diode

General Description

The LM136/LM236 and LM336 integrated circuits are precision 2.5V shunt regulator diodes. These monolithic IC voltage references operate as a low temperature coefficient 2.5V zener with 0.2Ω dynamic impedance. A third terminal on the LM136 allows the reference voltage and temperature coefficient to be trimmed easily.

The LM136 series is useful as a precision 2.5V low voltage reference for digital voltmeters, power supplies or op amp circuitry. The 2.5V make it convenient to obtain a stable reference from 5V logic supplies. Further, since the LM136 operates as a shunt regulator, it can be used as either a positive or negative voltage reference.

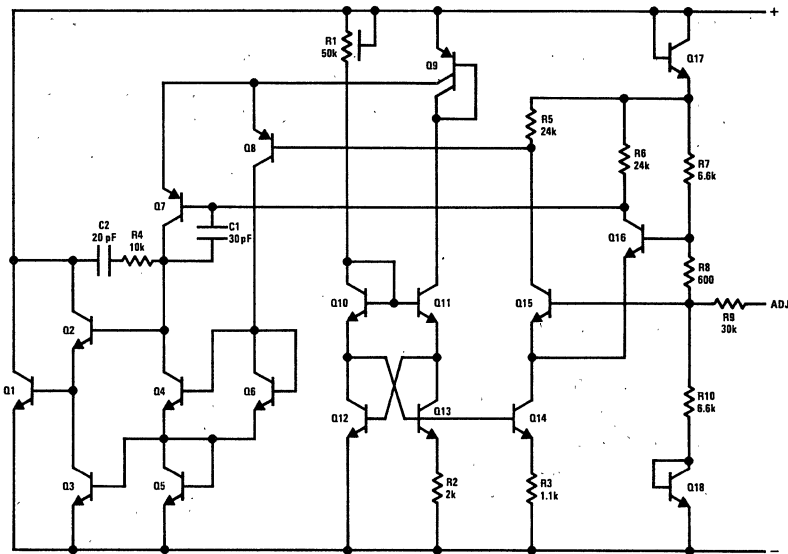
The LM136 is rated for operation over -55°C to $+125^\circ\text{C}$ while the LM236 is rated over a -25°C to $+85^\circ\text{C}$

temperature range. Both are packaged in a TO-46 package. The LM336 is rated for operation over a 0°C to $+70^\circ\text{C}$ temperature range and is available in either a three lead TO-46 package or a TO-92 plastic package.

Features

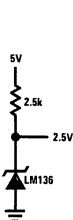
- Low temperature coefficient
- Wide operating current of $300\ \mu\text{A}$ to $10\ \text{mA}$
- 0.2Ω dynamic impedance
- $\pm 1\%$ initial tolerance available
- Guaranteed temperature stability
- Easily trimmed for minimum temperature drift
- Fast turn-on
- Three lead transistor package
- 5.0V device also available—LM336—5.0

Schematic Diagram

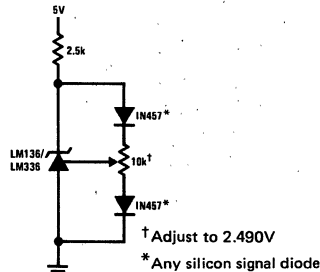


Typical Applications

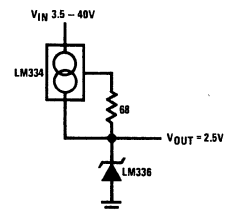
2.5V Reference



2.5V Reference with Minimum Temperature Coefficient



Wide Input Range Reference



Absolute Maximum Ratings

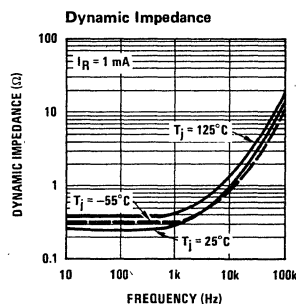
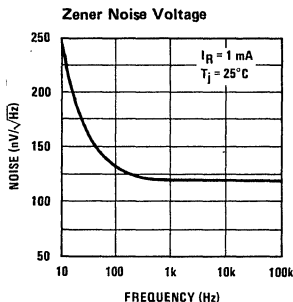
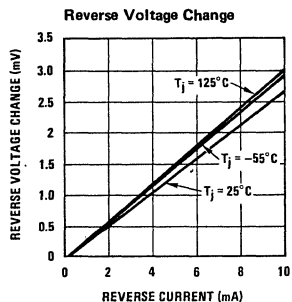
| | |
|--|-----------------|
| Reverse Current | 15 mA |
| Forward Current | 10 mA |
| Storage Temperature | -60°C to +150°C |
| Operating Temperature | |
| LM136 | -55°C to +150°C |
| LM236 | -25°C to +85°C |
| LM336 | 0°C to +70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

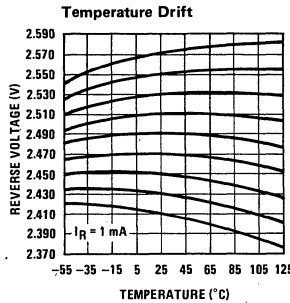
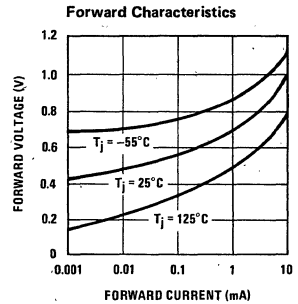
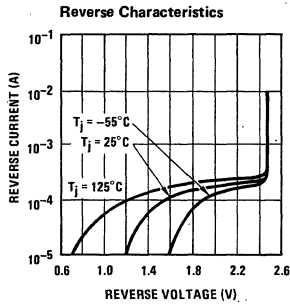
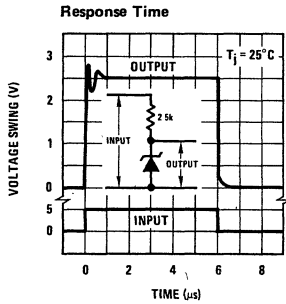
| PARAMETER | CONDITIONS | LM136A/LM236A LM136/LM236 | | | LM336B LM336 | | | UNITS |
|---------------------------------------|---|------------------------------|-------|-------|-----------------|-------|-------|----------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Reverse Breakdown Voltage | $T_A = 25^\circ\text{C}$, $I_R = 1\text{ mA}$ LM136/LM236/LM336 | 2.440 | 2.490 | 2.540 | 2.390 | 2.490 | 2.590 | V |
| | LM136A/LM236A, LM336B | 2.465 | 2.490 | 2.515 | 2.440 | 2.490 | 2.540 | V |
| Reverse Breakdown Change With Current | $T_A = 25^\circ\text{C}$, $400\ \mu\text{A} \leq I_R \leq 10\text{ mA}$ | | 2.6 | 6 | | 2.6 | 10 | mV |
| Reverse Dynamic Impedance | $T_A = 25^\circ\text{C}$, $I_R = 1\text{ mA}$ | | 0.2 | 0.6 | | 0.2 | 1 | Ω |
| Temperature Stability | V_R Adjusted to 2.490V $I_R = 1\text{ mA}$, (Figure 2) | | | | | | | |
| | $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ (LM336) | | | | 1.8 | 6 | | mV |
| | $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ (LM236) | | 3.5 | 9 | | | | mV |
| | $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ (LM136) | | 12 | 18 | | | | mV |
| Reverse Breakdown Change With Current | $400\ \mu\text{A} \leq I_R \leq 10\text{ mA}$ | | 3 | 10 | | 3 | 12 | mV |
| Reverse Dynamic Impedance | $I_R = 1\text{ mA}$ | | 0.4 | 1 | | 0.4 | 1.4 | Ω |
| Long Term Stability | $T_A = 25^\circ\text{C} \pm 0.1^\circ\text{C}$, $I_R = 1\text{ mA}$ | | 20 | | | 20 | | ppm |

Note 1: Unless otherwise specified, the LM136 is specified from $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, the LM236 from $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ and the LM336 from $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$. The maximum junction temperature of the LM136 is 150°C , LM236 is 125°C and the LM336 is 100°C . For elevated junction temperature, devices in the TO-46 package should be derated based on a thermal resistance of 440°C/W junction to ambient or 80°C/W junction to case. For the TO-92 package, the derating is based on 180°C/W junction to ambient with $0.4''$ leads from a PC board and 160°C/W junction to ambient with $0.125''$ lead length to a PC board.

Typical Performance Characteristics



Typical Performance Characteristics (Continued)



Application Hints

The LM136 series voltage references are much easier to use than ordinary zener diodes. Their low impedance and wide operating current range simplify biasing in almost any circuit. Further, either the breakdown voltage or the temperature coefficient can be adjusted to optimize circuit performance.

Figure 1 shows an LM136 with a 10k potentiometer for adjusting the reverse breakdown voltage. With the addition of R1 the breakdown voltage can be adjusted without affecting the temperature coefficient of the device. The adjustment range is usually sufficient to

adjust for both the initial device tolerance and inaccuracies in buffer circuitry.

If minimum temperature coefficient is desired, two diodes can be added in series with the adjustment potentiometer as shown in Figure 2. When the device is adjusted to 2.490V the temperature coefficient is minimized. Almost any silicon signal diode can be used for this purpose such as a 1N914, 1N4148 or a 1N457. For proper temperature compensation the diodes should be in the same thermal environment as the LM136. It is usually sufficient to mount the diodes near the LM136 on the printed circuit board. The absolute resistance of R1 is not critical and any value from 2k to 20k will work.

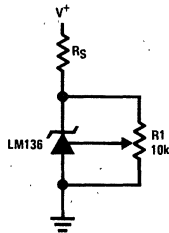


FIGURE 1. LM136 With Pot for Adjustment of Breakdown Voltage

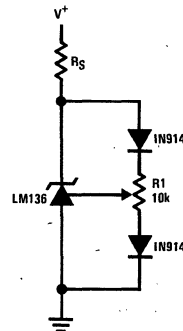
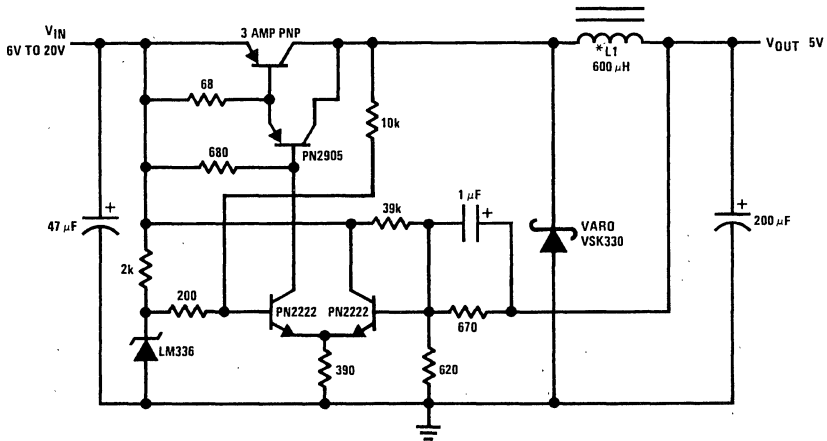


FIGURE 2. Temperature Coefficient Adjustment

Typical Applications (Continued)

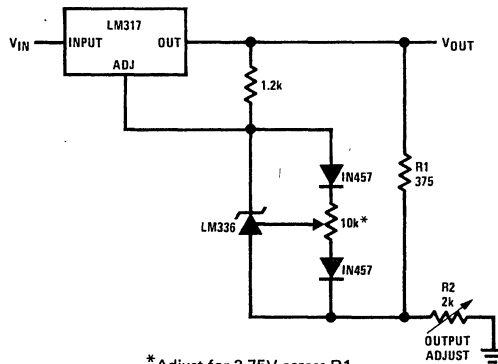
Low Cost 2 Amp Switching Regulator†



*L1 60 turns #16 wire on Arnold Core A-254168-2

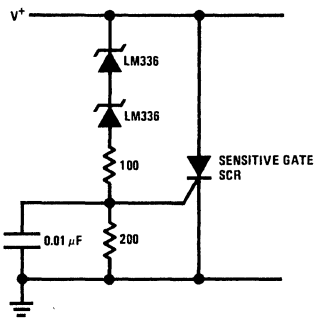
†Efficiency ≈ 80%

Precision Power Regulator with Low Temperature Coefficient

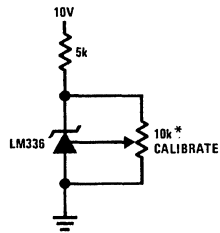


* Adjust for 3.75V across R1

5V Crowbar



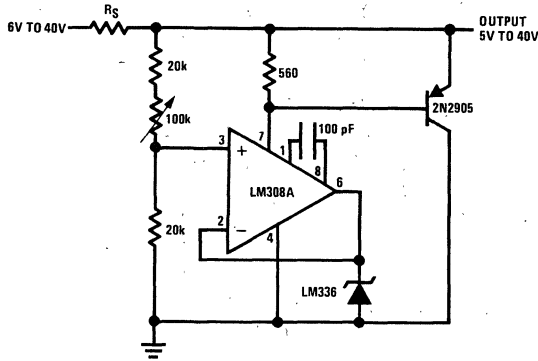
Trimmed 2.5V Reference with Temperature Coefficient Independent of Breakdown Voltage



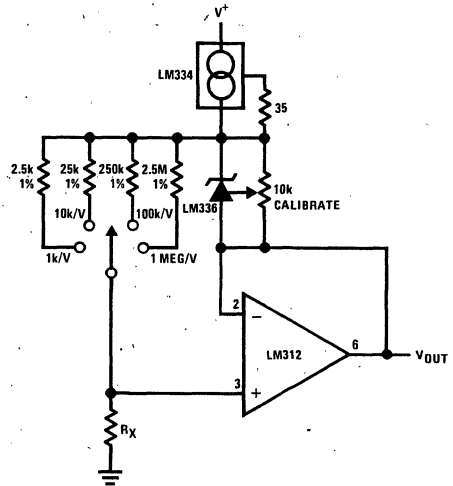
*Does not affect temperature coefficient

Typical Applications (Continued)

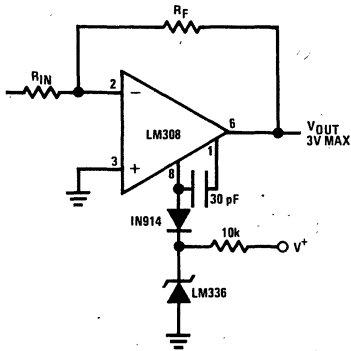
Adjustable Shunt Regulator



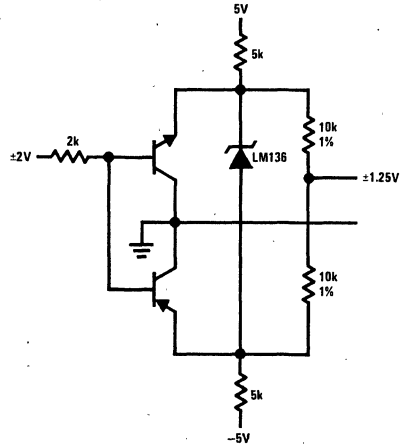
Linear Ohmmeter



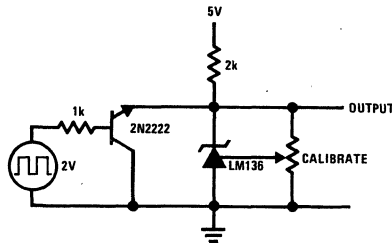
Op Amp with Output Clamped



Bipolar Output Reference

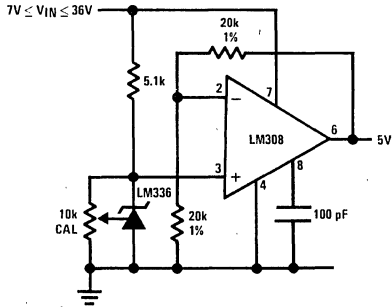


2.5V Square Wave Calibrator

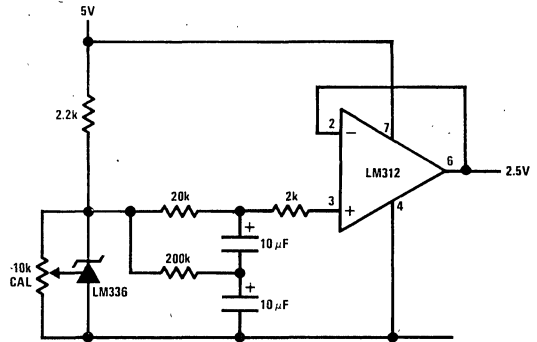


Typical Applications (Continued)

5V Buffered Reference

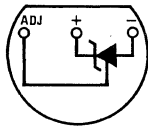


Low Noise Buffered Reference



Connection Diagrams

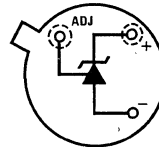
TO-92
Plastic Package



BOTTOM VIEW

Order Number
LM336Z or LM336BZ
See NS Package Z03A

TO-46
Metal Can Package



BOTTOM VIEW

Order Number
LM136H, LM236H, LM336H, LM136AH,
LM236AH or LM336BH
See NS Package H03H

LM185/LM285/LM385 Voltage Reference Diode

General Description

The LM185/LM285/LM385 are micropower 2-terminal band-gap voltage regulator diodes. Operating over a 10 μ A to 20 mA current range, they feature exceptionally low dynamic impedance and good temperature stability. On-chip trimming is used to provide tight voltage tolerance. Since the LM185 band-gap reference uses only transistors and resistors, low noise and good long term stability result.

Careful design of the LM185 has made the device exceptionally tolerant of capacitive loading, making it easy to use in almost any reference application. The wide dynamic operating range allows its use with widely varying supplies with excellent regulation. Some outstanding features are:

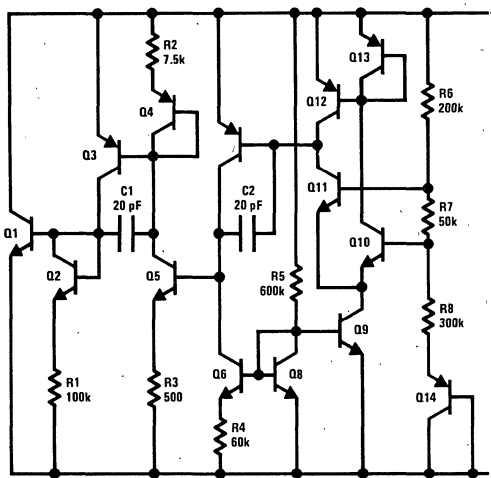
- Operating current of 10 μ A to 20 mA
- 1% and 2% initial tolerance
- 1 Ω dynamic impedance

- Low temperature coefficient
- Low voltage reference—1.235V

The extremely low power drain of the LM185 makes it useful for micropower circuitry. This voltage reference can be used to make portable meters, regulators or general purpose analog circuitry with battery life approaching shelf life. Further, the wide operating current allows it to replace older references with a tighter tolerance part.

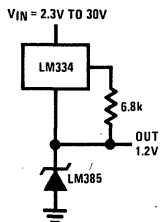
The LM185 is rated for operation over a -55°C to 125°C temperature range while the LM285 is rated -25°C to 85°C and the LM385 0°C to 70°C . The LM185/LM285/LM385 are available in a hermetic TO-46 package and the LM385 is also available in a low-cost TO-92 molded package.

Schematic Diagram

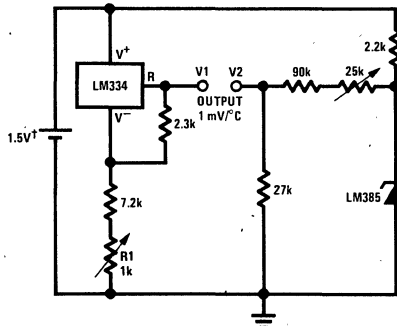


Applications

Wide Input Range Reference



Centigrade Thermometer



Calibration

1. Adjust R1 so that $V_1 = \text{temp at } 1 \text{ mV}/^{\circ}\text{C}$
 2. Adjust V2 to 273.2 mV
- I_Q for 1.3V to 1.6V battery voltage = 50 μ A to 150 μ A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Reverse Current | 30 mA |
| Forward Current | 10 mA |
| Operating Temperature Range | |
| LM185 | -55°C to +125°C |
| LM285 | -25°C to +85°C |
| LM385 | 0°C to 70°C |
| Storage Temperature | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

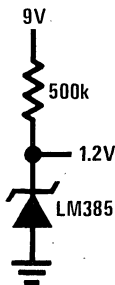
| Parameter | Conditions | LM185/LM285/LM385B | | | LM385 | | | Units |
|---|---|--------------------|-------|-------|-------|-------|-------|-----------------------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Reverse Breakdown Voltage | $T_A = 25^\circ\text{C}$ $I_{\text{MIN}} \leq I_R \leq 20 \text{ mA}$ LM185/LM285/LM385B | 1.223 | 1.235 | 1.247 | 1.223 | 1.235 | 1.247 | V |
| | | | | | 1.205 | 1.235 | 1.260 | V |
| Minimum Operating Current | | | 8 | 10 | | 8 | 15 | μA |
| Reverse Breakdown Voltage Change with Current | $I_{\text{MIN}} \leq I_R \leq 1 \text{ mA}$ $1 \text{ mA} \leq I_R \leq 20 \text{ mA}$ | | | 1 | | | 1 | mV |
| | | | | 1.5 | | | 1.5 | mV |
| | | | | 10 | | | 20 | mV |
| | | | | 20 | | | 25 | mV |
| Reverse Dynamic Impedance | $I_R = 100 \mu\text{A}$ | | 0.2 | 0.6 | | 0.4 | 1 | Ω |
| | | | | 1.5 | | | 1.5 | Ω |
| Average Temperature Coefficient | $10 \mu\text{A} \leq I_R \leq 20 \text{ mA}$ (Note 2) | | 20 | | | 20 | | ppm/ $^\circ\text{C}$ |
| Wide Band Noise (RMS) | $I_R = 100 \mu\text{A}$ $10 \text{ Hz} \leq f \leq 10 \text{ kHz}$ | | 60 | | | 60 | | μV |
| Long Term Stability | $I_R = 100 \mu\text{A}$ $T_A = 25^\circ\text{C} \pm 0.1^\circ\text{C}$ | | 20 | | | 20 | | ppm/kHR |

Note 1: Boldface type applies over the operating temperature range. Thermal resistance of the TO-46 package is 440°C/W junction to ambient or 80°C/W junction to case. Thermal resistance of the TO-92 package is 180°C/W junction to ambient.

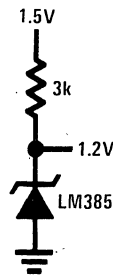
Note 2: Guaranteed maximum average temperature coefficient available as special order.

Applications (Continued)

Micropower Reference from 9V Battery

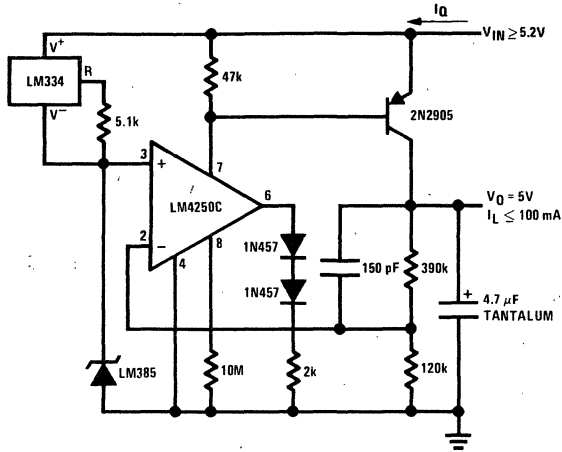


Reference from 1.5V Battery



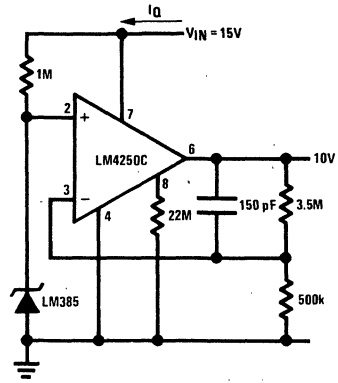
LM385 Applications

Micropower* 5V Regulator



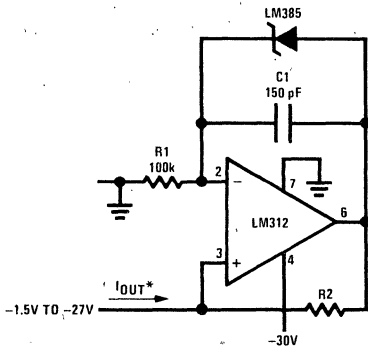
* $I_Q \approx 30 \mu A$

Micropower* 10V Reference

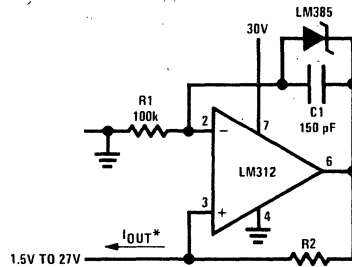


* $I_Q \approx 20 \mu A$ standby current

Precision 1 μA to 1 mA Current Sources



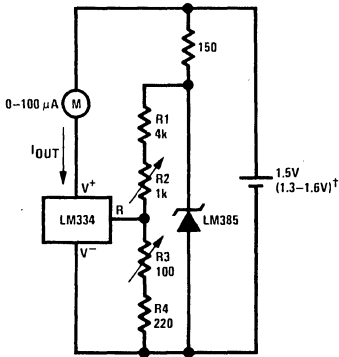
$$I_{OUT}^* = \frac{1.23V}{R_2}$$



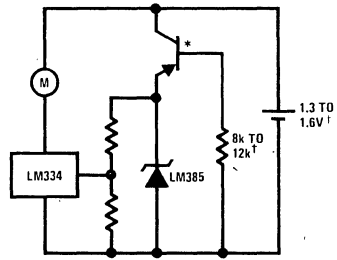
LM385 Applications (Continued)

METER THERMOMETERS

0°C–100°C Thermometer



Lower Power Thermometer

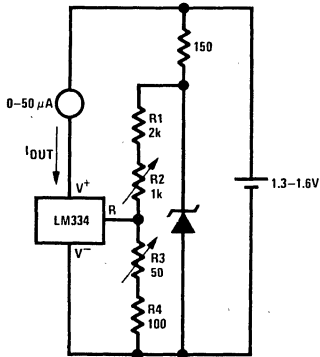


* 2N3638 or 2N2907 select for inverse $H_{FE} \approx 5$
 † Select for operation at 1.3V
 ‡ $I_Q \approx 600 \mu A$ to $900 \mu A$

Calibration

1. Short LM385, adjust R3 for $I_{OUT} = \text{temp}$ at $1 \mu A/^{\circ}K$
 2. Remove short, adjust R2 for correct reading in centigrade
- † I_Q at 1.3V $\approx 500 \mu A$
 I_Q at 1.6V $\approx 2.4 \text{ mA}$

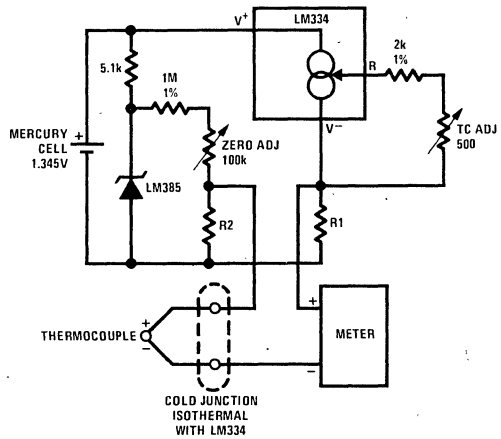
0°F–50°F Thermometer



Calibration

1. Short LM385, adjust R3 for $I_{OUT} = \text{temp}$ at $1.8 \mu A/^{\circ}K$
2. Remove short, adjust R2 for correct reading in $^{\circ}F$

Micropower Thermocouple Cold Junction Compensator



Adjustment Procedure

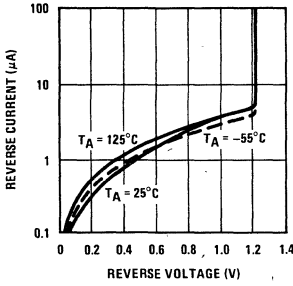
1. Adjust TC ADJ pot until voltage across R1 equals kelvin temperature multiplied by the thermocouple seebeck coefficient.
2. Adjust zero ADJ pot until voltage across R2 equals the thermocouple seebeck coefficient multiplied by 273.2.

| Thermocouple Type | Seebeck Coefficient ($\mu V/^{\circ}C$) | R1 (Ω) | R2 (Ω) | Voltage Across R1 @ 25°C (mV) | Voltage Across R2 (mV) |
|-------------------|---|-----------------|-----------------|-------------------------------|------------------------|
| J | 52.3 | 523 | 1.24k | 15.60 | 14.32 |
| T | 42.8 | 432 | 1k | 12.77 | 11.78 |
| K | 40.8 | 412 | 953 Ω | 12.17 | 11.17 |
| S | 6.4 | 63.4 | 150 Ω | 1.908 | 1.766 |

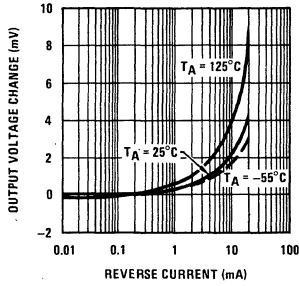
Typical supply current 50 μA

Typical Performance Characteristics

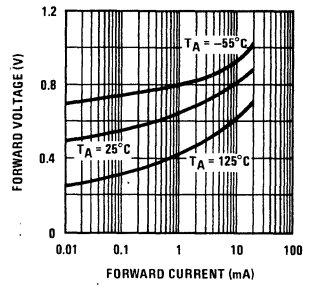
Reverse Characteristics



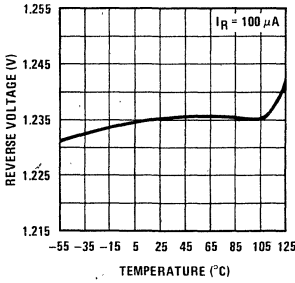
Reverse Characteristics



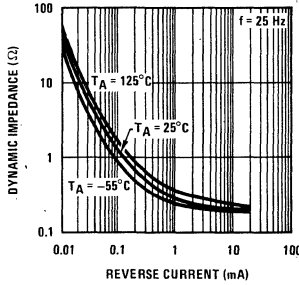
Forward Characteristics



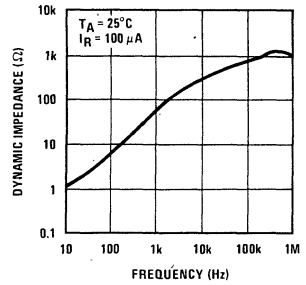
Temperature Drift



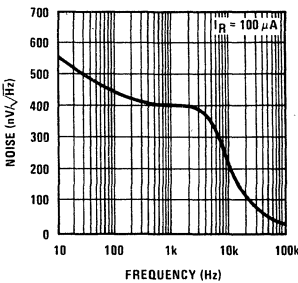
Reverse Dynamic Impedance



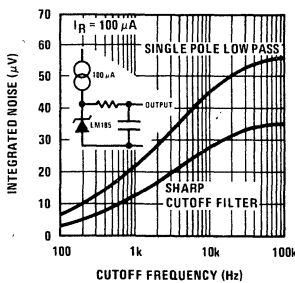
Reverse Dynamic Impedance



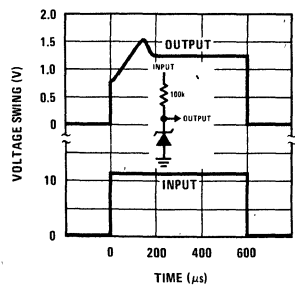
Noise Voltage



Filtered Output Noise

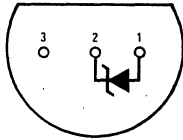


Response Time



Connection Diagrams

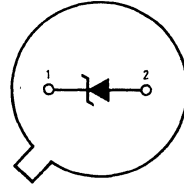
TO-92
Plastic Package



BOTTOM VIEW

Order Number LM385Z or LM385BZ
See NS Package Z03D

TO-46
Metal Can Package



BOTTOM VIEW

Order Number LM185H, LM285H,
LM385H or LM385BH
See NS Package H02A

LM199/LM299/LM399 Precision Reference

General Description

The LM199/LM299/LM399 are precision, temperature-stabilized monolithic zeners offering temperature coefficients a factor of ten better than high quality reference zeners. Constructed on a single monolithic chip is a temperature stabilizer circuit and an active reference zener. The active circuitry reduces the dynamic impedance of the zener to about 0.5Ω and allows the zener to operate over 0.5 mA to 10 mA current range with essentially no change in voltage or temperature coefficient. Further, a new subsurface zener structure gives low noise and excellent long term stability compared to ordinary monolithic zeners. The package is supplied with a thermal shield to minimize heater power and improve temperature regulation.

The LM199 series references are exceptionally easy to use and free of the problems that are often experienced with ordinary zeners. There is virtually no hysteresis in reference voltage with temperature cycling. Also, the LM199 is free of voltage shifts due to stress on the leads. Finally, since the unit is temperature stabilized, warm-up time is fast.

The LM199 can be used in almost any application in place of ordinary zeners with improved performance. Some ideal applications are analog to digital converters,

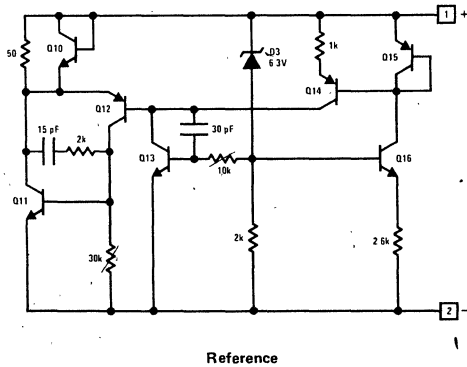
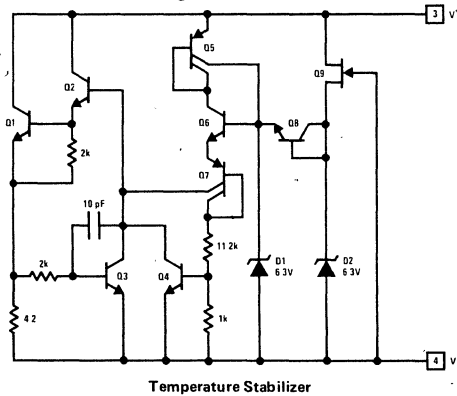
calibration standards, precision voltage or current sources or precision power supplies. Further in many cases the LM199 can replace references in existing equipment with a minimum of wiring changes.

The LM199 series devices are packaged in a standard hermetic TO-46 package inside a thermal shield. The LM199 is rated for operation from -55°C to $+125^{\circ}\text{C}$ while the LM299 is rated for operation from -25°C to $+85^{\circ}\text{C}$ and the LM399 is rated from 0°C to $+70^{\circ}\text{C}$.

Features

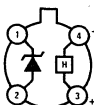
- Guaranteed $0.0001\%/^{\circ}\text{C}$ temperature coefficient
- Low dynamic impedance — 0.5Ω
- Initial tolerance on breakdown voltage — 2%
- Sharp breakdown at $400\mu\text{A}$
- Wide operating current — $500\mu\text{A}$ to 10 mA
- Wide supply range for temperature stabilizer
- Guaranteed low noise
- Low power for stabilization — 300 mW at 25°C
- Long term stability — 20 ppm

Schematic Diagrams



Connection Diagram

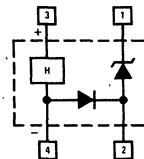
Metal Can Package



TOP VIEW

Order Number LM199H, LM299H
or LM399H
See NS Package H04D

Functional Block Diagram



Absolute Maximum Ratings

| | |
|--|-----------------|
| Temperature Stabilizer Voltage | 40V |
| Reverse Breakdown Current | 20 mA |
| Forward Current | 1 mA |
| Reference to Substrate Voltage $V_{(RS)}$ (Note 1) | 40V -0.1V |
| Operating Temperature Range | |
| LM199 | -55°C to +125°C |
| LM299 | -25°C to +85°C |
| LM399 | 0°C to +70°C |
| Storage Temperature Range | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 2)

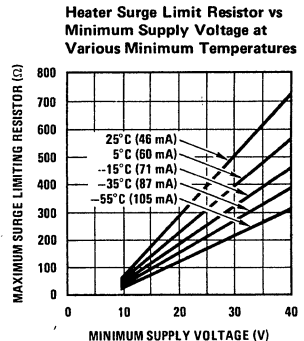
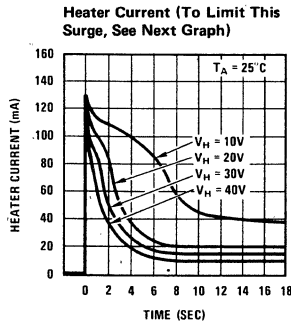
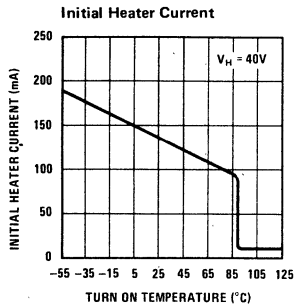
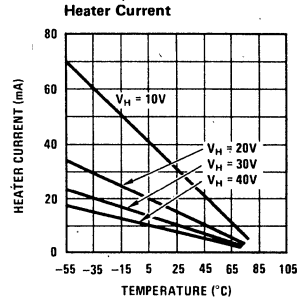
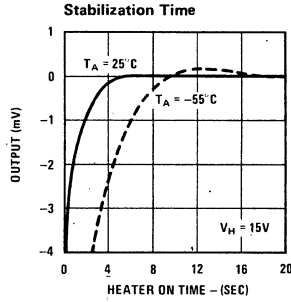
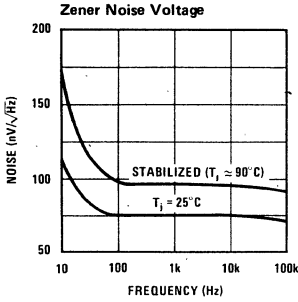
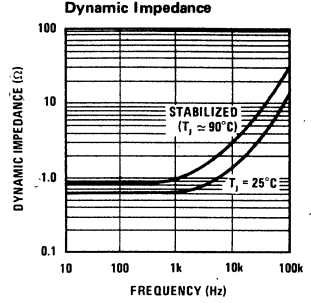
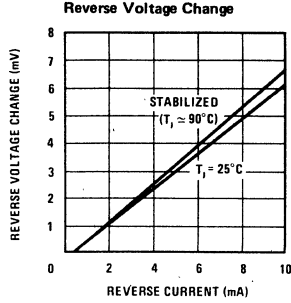
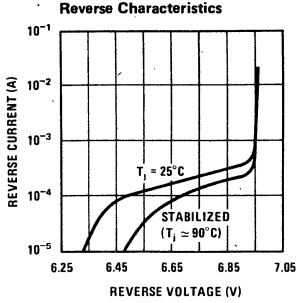
| PARAMETER | CONDITIONS | LM199/LM299 | | | LM399 | | | UNITS |
|--|---|-------------|---------|--------|-------|---------|--------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Reverse Breakdown Voltage | $0.5 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | 6.8 | 6.95 | 7.1 | 6.6 | 6.95 | 7.3 | V |
| Reverse Breakdown Voltage Change With Current | $0.5 \text{ mA} \leq I \leq 10 \text{ mA}$ | | 6 | 9 | | 6 | 12 | mV |
| Reverse Dynamic Impedance | $I_R = 1 \text{ mA}$ | | 0.5 | 1 | | 0.5 | 1.5 | Ω |
| Reverse Breakdown Temperature Coefficient | $-55^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ $85^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ | | 0.00003 | 0.0001 | | | | %/°C |
| | $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ | | 0.00005 | 0.0015 | | | | %/°C |
| | | | 0.00003 | 0.0001 | | 0.00003 | 0.0002 | %/°C |
| RMS Noise | $10 \text{ Hz} \leq f \leq 10 \text{ kHz}$ | | 7 | 20 | | 7 | 50 | μV |
| Long Term Stability | Stabilized, $22^\circ\text{C} \leq T_A \leq 28^\circ\text{C}$, 1000 Hours, $I_R = 1 \text{ mA} \pm 0.1\%$ | | 20 | | | 20 | | ppm |
| Temperature Stabilizer Supply Current | $T_A = 25^\circ\text{C}$, Still Air, $V_S = 30\text{V}$ $T_A = -55^\circ\text{C}$ | | 8.5 | 14 | | 8.5 | 15 | mA |
| Temperature Stabilizer Supply Voltage | (Note 3) | 9 | | 40 | 9 | | 40 | V |
| Warm-Up Time to 0.05% | $V_S = 30\text{V}$, $T_A = 25^\circ\text{C}$ | | 3 | | | 3 | | Seconds |
| Initial Turn-on Current | $9 \leq V_S \leq 40$, $T_A = 25^\circ\text{C}$, (Note 3) | | 140 | 200 | | 140 | 200 | mA |

Note 1: The substrate is electrically connected to the negative terminal of the temperature stabilizer. The voltage that can be applied to either terminal of the reference is 40V more positive or 0.1V more negative than the substrate.

Note 2: These specifications apply for 30V applied to the temperature stabilizer and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LM199; $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ for the LM299 and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ for the LM399.

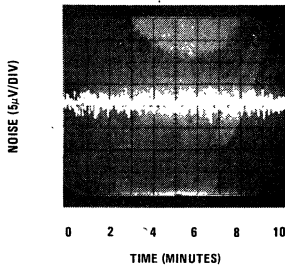
Note 3: This initial current can be reduced by adding an appropriate resistor and capacitor to the heater circuit. See the performance characteristic graphs to determine values.

Typical Performance Characteristics

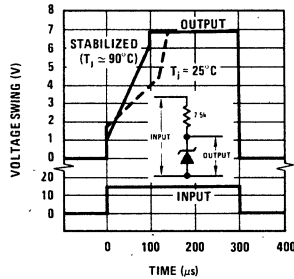


*Heater must be bypassed with a 2 μF or larger tantalum capacitor if maximum value resistors are used. Otherwise, 30% to 50% smaller values must be used. If heater oscillates, resistor value may be too small.

Low Frequency Noise Voltage

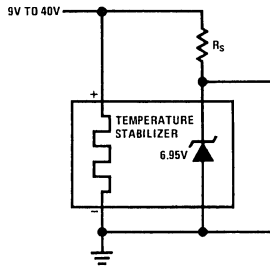


Response Time

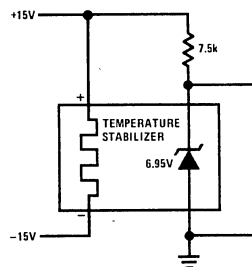


Typical Applications

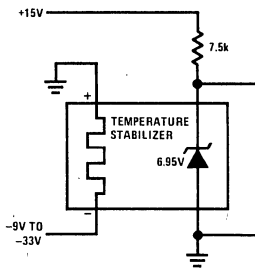
Single Supply Operation



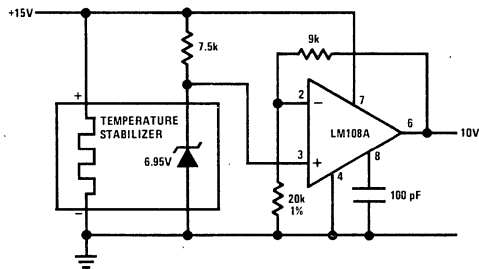
Split Supply Operation



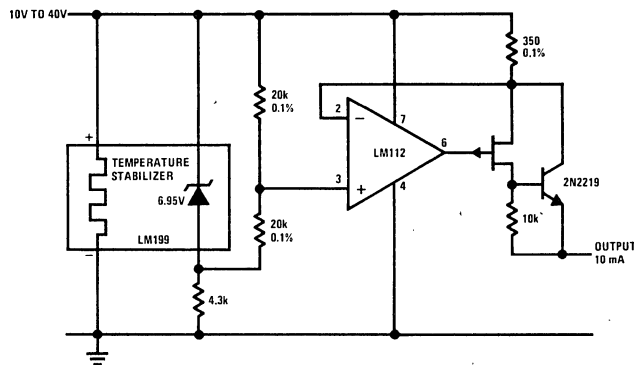
Negative Heater Supply with Positive Reference



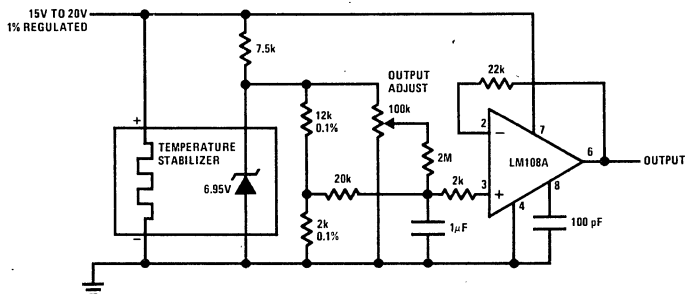
Buffered Reference With Single Supply



Positive Current Source

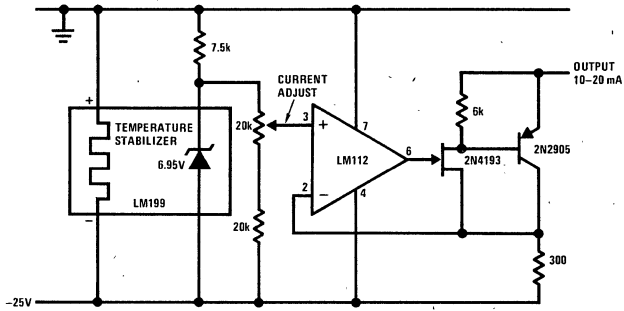


Standard Cell Replacement

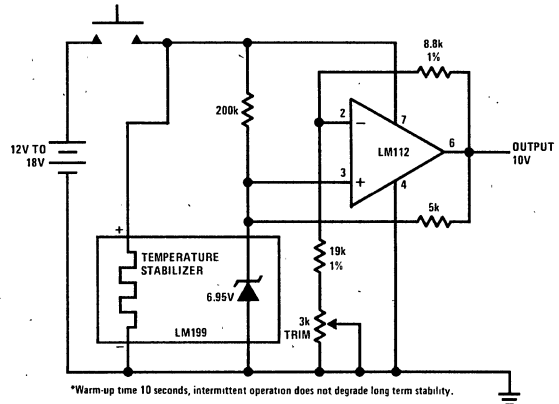


Typical Applications (Continued)

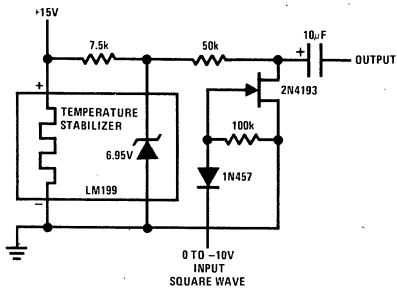
Negative Current Source



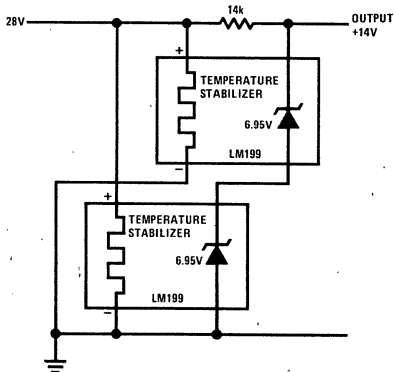
Portable Calibrator*



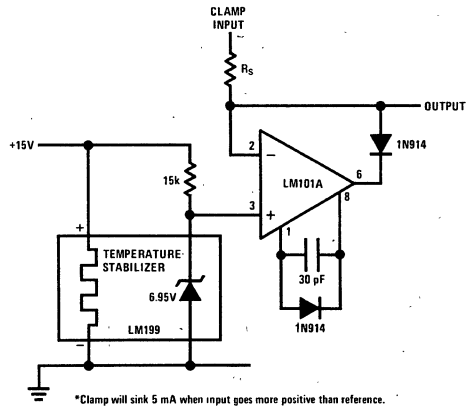
Square Wave Voltage Reference



14V Reference

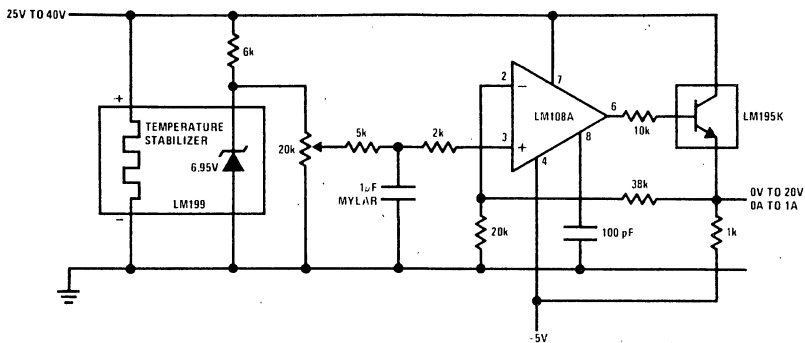


Precision Clamp*

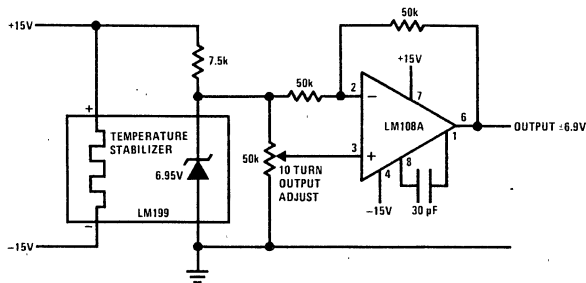


Typical Applications (Continued)

0V to 20V Power Reference



Bipolar Output Reference





LM199A/LM299A/LM399A Precision Reference

General Description

The LM199A/LM299A/LM399A are precision, temperature-stabilized monolithic zeners offering temperature coefficients a factor of ten better than high quality reference zeners. Constructed on a single monolithic chip is a temperature stabilizer circuit and an active reference zener. The active circuitry reduces the dynamic impedance of the zener to about 0.5Ω and allows the zener to operate over 0.5 mA to 10 mA current range with essentially no change in voltage or temperature coefficient. Further, a new subsurface zener structure gives low noise and excellent long term stability compared to ordinary monolithic zeners. The package is supplied with a thermal shield to minimize heater power and improve temperature regulation.

The LM199A series references are exceptionally easy to use and free of the problems that are often experienced with ordinary zeners. There is virtually no hysteresis in reference voltage with temperature cycling. Also, the LM199A is free of voltage shifts due to stress on the leads. Finally, since the unit is temperature stabilized, warm up time is fast.

The LM199A can be used in almost any application in place of ordinary zeners with improved performance. Some ideal applications are analog to digital converters, calibration standards, precision voltage or current sources or precision power supplies. Further in many cases the LM199A can replace references in existing equipment with a minimum of wiring changes.

Voltage References

The LM199A series devices are packaged in a standard hermetic TO-46 package inside a thermal shield. The LM199 is rated for operation from -55°C to $+125^{\circ}\text{C}$ while the LM299A is rated for operation from -25°C to $+85^{\circ}\text{C}$ and the LM399A is rated from 0°C to $+70^{\circ}\text{C}$.

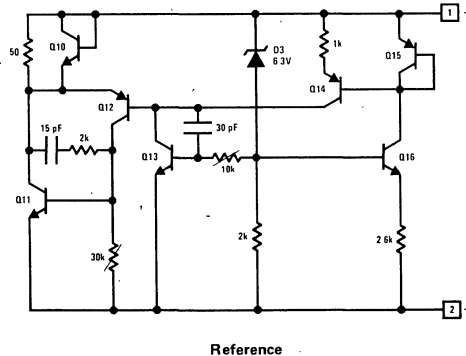
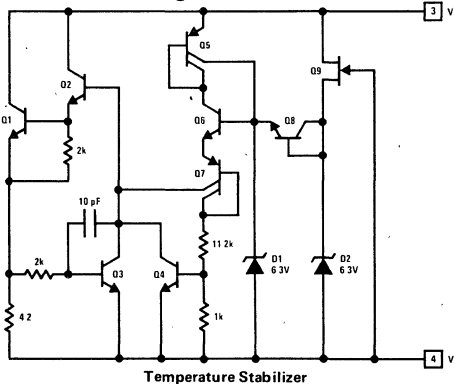
Certified Long Term Stability Devices

All devices are tested for 1000 hours minimum at 25°C ambient temperature with temperature stabilizer operating. All devices shipped with long term data which certifies a maximum drift for the 1000 hours of 20 ppm or 50 ppm.

Features

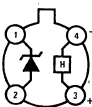
- Guaranteed $0.00005\%/^{\circ}\text{C}$ temperature coefficient
- Low dynamic impedance — 0.5Ω
- Initial tolerance on breakdown voltage — 2%
- Sharp breakdown at $400\mu\text{A}$
- Wide operating current — $500\mu\text{A}$ to 10 mA
- Wide supply range for temperature stabilizer
- Guaranteed low noise
- Low power for stabilization — 300 mW at 25°C
- Long term stability — 20 ppm
- Certified long term stability available

Schematic Diagrams



Connection Diagram

Metal Can Package

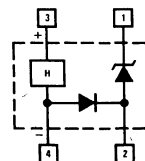


Order Number LM199AH, LM299AH
or LM399AH
See NS Package H04D

Certified Long Term Stability Device

| CERTIFIED LONG TERM STABILITY ppm MAX | ORDERING NUMBERS |
|---------------------------------------|------------------|
| 20 | LM199AH-20 |
| 20 | LM299AH-20 |
| 50 | LM399AH-50 |

Functional Block Diagram



Absolute Maximum Ratings

| | |
|--|-----------------|
| Temperature Stabilizer Voltage | 40V |
| Reverse Breakdown Current | 20 mA |
| Forward Current | 1 mA |
| Reference to Substrate Voltage $V_{(RS)}$ (Note 1) | +40V -0.1V |
| Operating Temperature Range | |
| LM199A | -55°C to +125°C |
| LM299A | -25°C to +85°C |
| LM399A | 0°C to +70°C |
| Storage Temperature Range | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LM199A, LM299A | | | LM399A | | | UNITS |
|--|--|----------------|---------|---------|--------|---------|--------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Reverse Breakdown Voltage | $0.5 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | 6.8 | 6.95 | 7.1 | 6.6 | 6.95 | 7.3 | V |
| Reverse Breakdown Voltage Change With Current | $0.5 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | | 6 | 9 | | 6 | 12 | mV |
| Reverse Dynamic Impedance | $I_R = 1 \text{ mA}$ | | 0.5 | 1 | | 0.5 | 1.5 | Ω |
| Reverse Breakdown Temperature Coefficient | $-55^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ $85^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ | | 0.00002 | 0.00005 | | | | %/°C |
| | $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ LM299A $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ LM399A | | 0.00005 | 0.0010 | | | | %/°C |
| | | | 0.00002 | 0.00005 | | | | %/°C |
| | | | | | | 0.00003 | 0.0001 | %/°C |
| RMS Noise | $10 \text{ Hz} \leq f \leq 10 \text{ kHz}$ | | 7 | 20 | | 7 | 50 | μV |
| Long Term Stability | Stabilized, $22^\circ\text{C} \leq T_A \leq 28^\circ\text{C}$, 1000 Hours, $I_R = 1 \text{ mA} \pm 0.1\%$ | | 20 | | | 20 | | ppm |
| Temperature Stabilizer Supply Current | $T_A = 25^\circ\text{C}$, Still Air, $V_S = 30\text{V}$, $T_A = -55^\circ\text{C}$ | | 8.5 | 14 | | 8.5 | 15 | mA |
| Temperature Stabilizer Supply Voltage (Note 3) | | 9 | | 40 | 9 | | 40 | V |
| Warm-Up Time to 0.05% | $V_S = 30\text{V}$, $T_A = 25^\circ\text{C}$ | | 3 | | | 3 | | Seconds |
| Initial Turn-on Current | $9 \leq V_S \leq 40$, $T_A = 25^\circ\text{C}$, (Note 3) | | 140 | 200 | | 140 | 200 | mA |

Note 1: The substrate is electrically connected to the negative terminal of the temperature stabilizer. The voltage that can be applied to either terminal of the reference is 40V more positive or 0.1V more negative than the substrate.

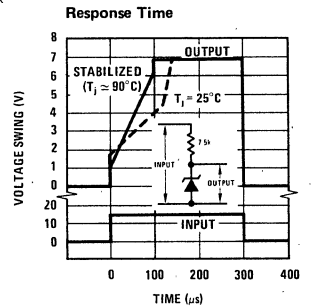
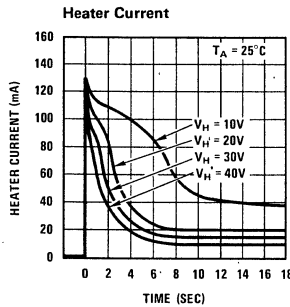
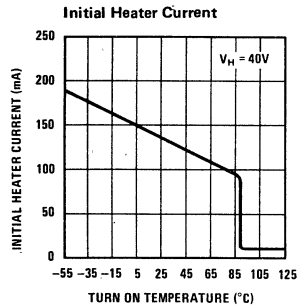
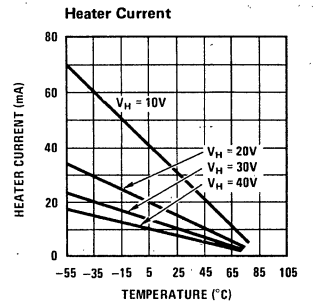
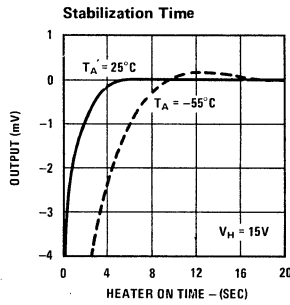
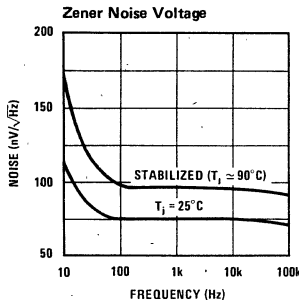
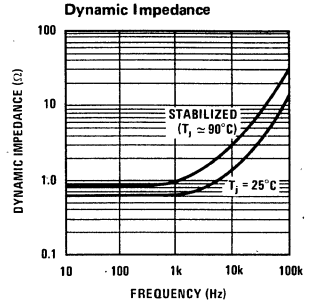
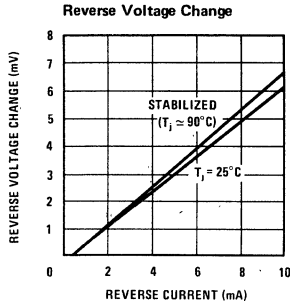
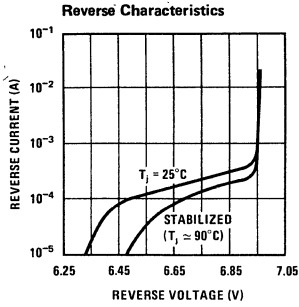
Note 2: These specifications apply for 30V applied to the temperature stabilizer and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LM199A; $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ for the LM299A and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ for the LM399A.

Note 3: This initial current can be reduced by adding an appropriate resistor and capacitor to the heater circuit. See the performance characteristic graphs to determine values.

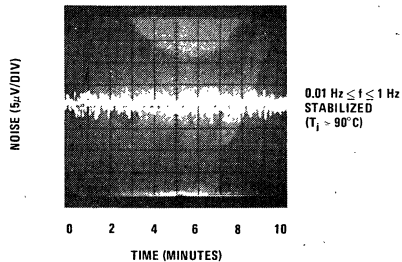
Typical Applications

For typical applications, see LM199 data sheet on preceding pages.

Typical Performance Characteristics



Low Frequency Noise Voltage



LM3999 Precision Reference

General Description

The LM3999 is a precision, temperature-stabilized monolithic zener offering temperature coefficients a factor of ten better than high quality reference zeners. Constructed on a single monolithic chip is a temperature stabilizer circuit and an active reference zener. The active circuitry reduces the dynamic impedance of the zener to about 0.5Ω and allows the zener to operate over 0.5 mA to 10 mA current range with essentially no change in voltage or temperature coefficient. Further, a new subsurface zener structure gives low noise and excellent long term stability compared to ordinary monolithic zeners.

The LM3999 reference is exceptionally easy to use and free of the problems that are often experienced with ordinary zeners. There is virtually no hysteresis in reference voltage with temperature cycling. Also, the LM3999 is free of voltage shifts due to stress on the leads. Finally, since the unit is temperature stabilized, warm up time is fast.

The LM3999 can be used in almost any application in place of ordinary zeners with improved performance.

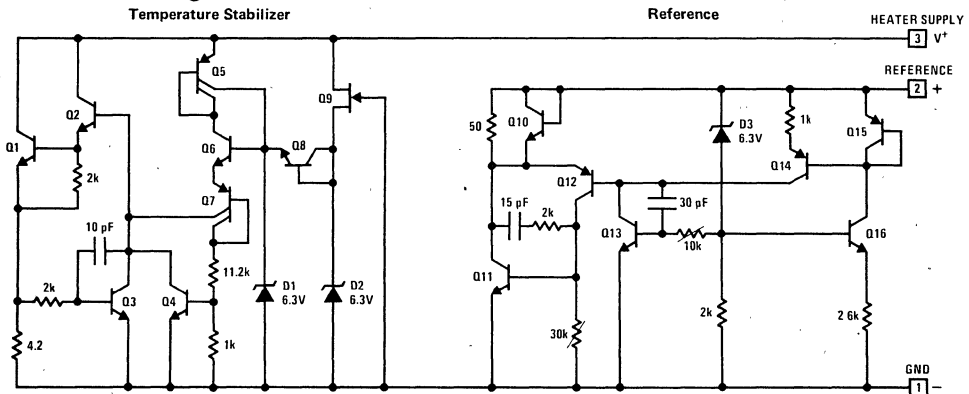
Some ideal applications are analog to digital converters, precision voltage or current sources or precision power supplies. Further, in many cases, the LM3999 can replace references in existing equipment with a minimum of wiring changes.

The LM3999 is packaged in a standard TO-92 package and is rated from 0°C to $+70^{\circ}\text{C}$.

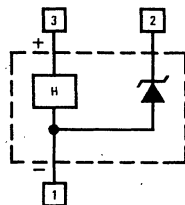
Features

- Guaranteed $0.0005\%/^{\circ}\text{C}$ temperature coefficient
- Low dynamic impedance – 0.5Ω
- Initial tolerance on breakdown voltage – 5%
- Sharp breakdown at $400\mu\text{A}$
- Wide operating current – $500\mu\text{A}$ to 10 mA
- Wide supply range for temperature stabilizer
- Low power for stabilization – 400 mW at 25°C
- Long term stability – 20 ppm

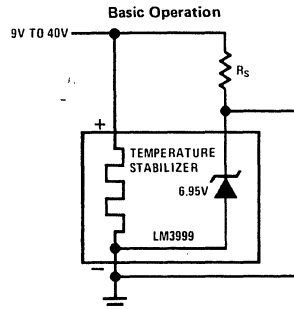
Schematic Diagram



Functional Block Diagram



Typical Applications



Absolute Maximum Ratings

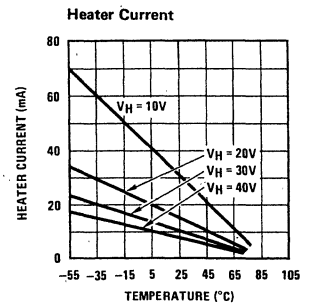
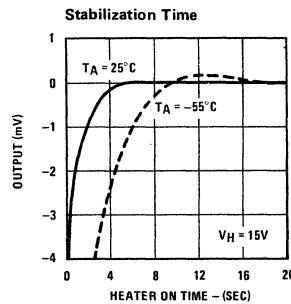
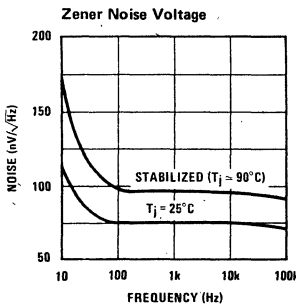
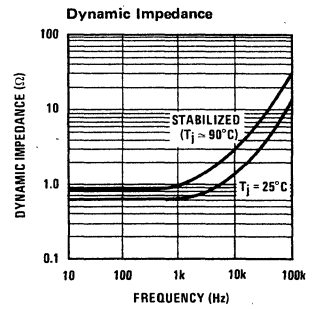
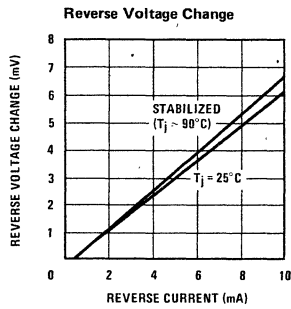
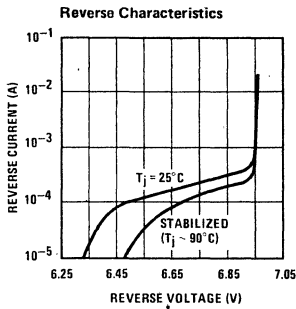
| | |
|--|-----------------|
| Temperature Stabilizer Voltage | 36V |
| Reverse Breakdown Current | 20 mA |
| Forward Current | 0.1 mA |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -55°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

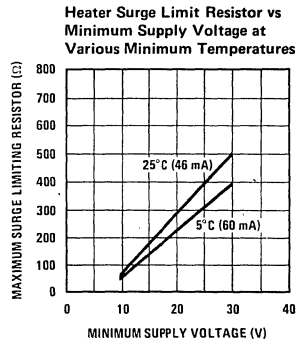
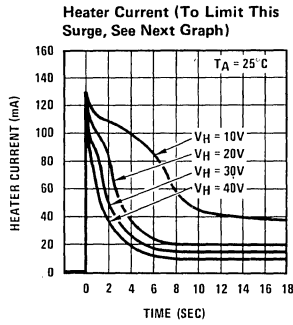
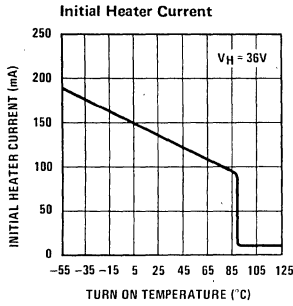
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|--------|--------|---------------|
| Reverse Breakdown Voltage | $0.6 \text{ mA} \leq I_R \leq 10 \text{ mA}$ | 6.6 | 6.95 | 7.3 | V |
| Reverse Breakdown Voltage Change With Current | $0.6 \text{ mA} \leq I \leq 10 \text{ mA}$ | | 6 | 20 | mV |
| Reverse Dynamic Impedance | $I_R = 1 \text{ mA}$ | | 0.6 | 2.2 | Ω |
| Reverse Breakdown Temperature Coefficient | $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ | | 0.0002 | 0.0005 | %/°C |
| RMS Noise | $10 \text{ Hz} \leq f \leq 10 \text{ kHz}$ | | 7 | | μV |
| Long Term Stability | Stabilized, $22^\circ\text{C} \leq T_A \leq 28^\circ\text{C}$, 1000 Hours, $I_R = 1 \text{ mA} \pm 0.1\%$ | | 20 | | ppm |
| Temperature Stabilizer | $T_A = 25^\circ\text{C}$, Still Air, $V_S = 30\text{V}$ | | 12 | 18 | mA |
| Temperature Stabilizer Supply Voltage | | | | 36 | V |
| Warm-Up Time to 0.05% | $V_S = 30\text{V}$, $T_A = 25^\circ\text{C}$ | | 5 | | Seconds |
| Initial Turn-on Current | $9 \leq V_S \leq 40$, $T_A = 25^\circ\text{C}$ | | 140 | 200 | mA |

Note 1: These specifications apply for 30V applied to the temperature stabilizer and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$.

Typical Performance Characteristics

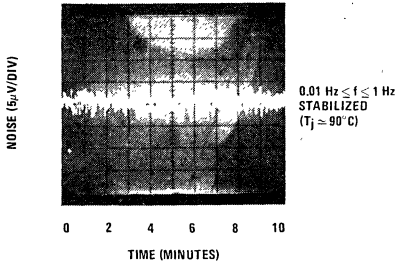


Typical Performance Characteristics (Continued)

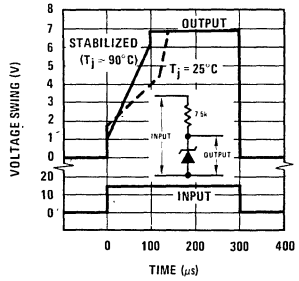


* Heater must be bypassed with a $2 \mu F$ tantalum capacitor if maximum value resistors are used. Otherwise 30% to 50% smaller values must be used. If heater voltage oscillates under any condition, temperature is not at control point.

Low Frequency Noise Voltage

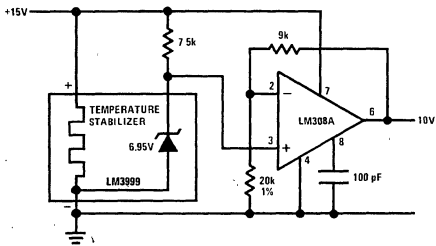


Response Time

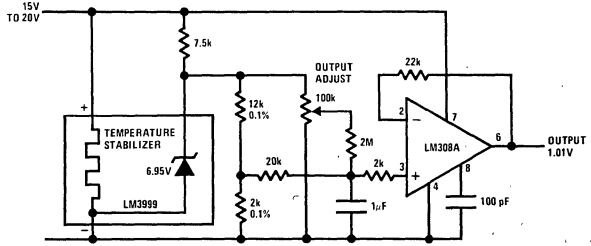


Typical Applications (Continued)

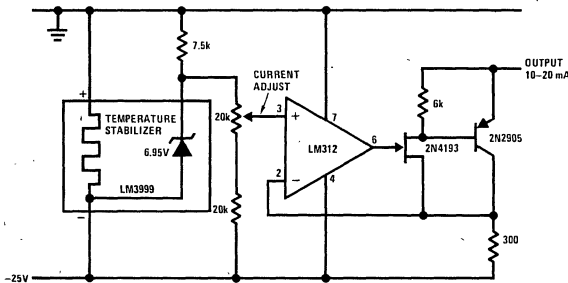
Buffered Reference With Single Supply



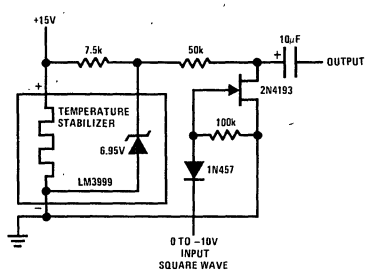
Voltage Reference



Negative Current Source

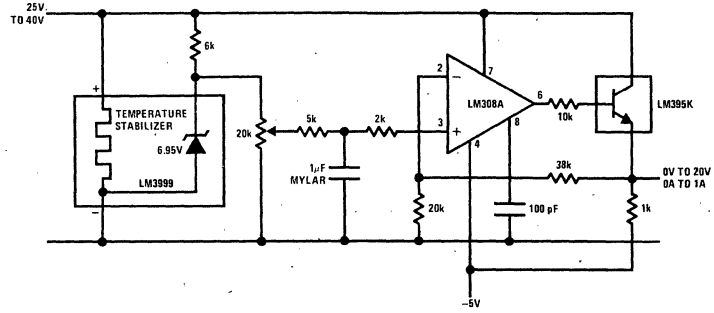


Square Wave Voltage Reference

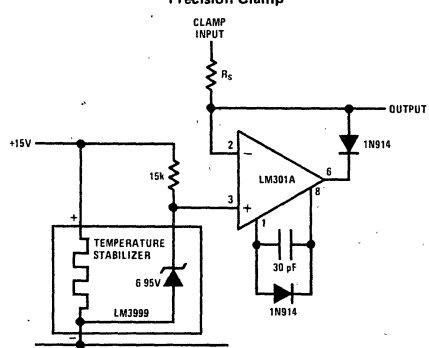


Typical Applications (Continued)

0V to 20V Power Reference

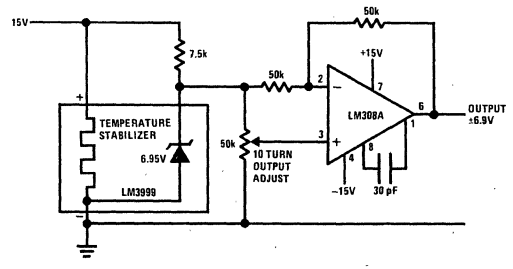


Precision Clamp*

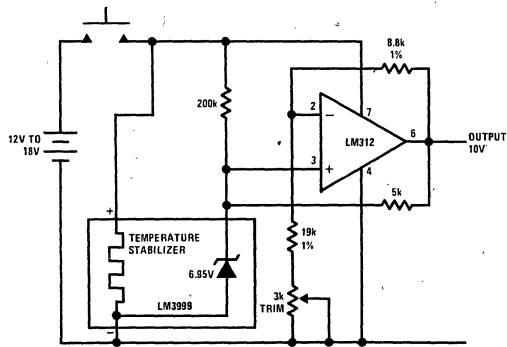


*Clamp will sink 5 mA when input goes more positive than reference.

Bipolar Output Reference



Portable Calibrator*



*Warm-up time 10 seconds; intermittent operation does not degrade long term stability.

Connection Diagram

Plastic Package



BOTTOM VIEW

Order Number LM3999Z
See NS Package Z03A



Section 3
**Operational
Amplifiers/Buffers**

3



Section Contents

| | |
|---|--------|
| BI-FET™/BI-FET II™ Op Amp Selection Guide..... | 3-v |
| Military Op Amp Selection Guide..... | 3-vii |
| Industrial Op Amp Selection Guide..... | 3-ix |
| Commercial Op Amp Selection Guide..... | 3-x |
| Special Function Operational Amplifier and Special Function Buffer Amplifier Guides..... | 3-xii |
| Definition of Terms..... | 3-xiii |
| High Input Impedance ($I_B < 25$ nA) | |
| LF155/LF255/LF355 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF155A/LF355A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156/LF256/LF356 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156A/LF356A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157/LF257/LF357 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157A/LF357A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF347 Wide Bandwidth Quad JFET Input Operational Amplifier..... | 3-14 |
| LF351 Wide Bandwidth JFET Input Operational Amplifier..... | 3-22 |
| LF353 Wide Bandwidth Dual JFET Input Operational Amplifier..... | 3-29 |
| LF13741 Monolithic JFET Input Operational Amplifier..... | 3-38 |
| LM108/LM208/LM308 Operational Amplifiers..... | 3-83 |
| LM108A/LM208A/LM308A, LM308A-1, LM308A-2 Operational Amplifiers..... | 3-88 |
| LM110/LM210/LM310 Voltage Follower..... | 3-95 |
| LM112/LM212/LM312 Operational Amplifiers..... | 3-102 |
| LM121/LM221/LM321, LM121A/LM221A/LM321A Precision Preamplifiers..... | 4-11 |
| LM216/LM316, LM216A/LM316A Operational Amplifiers..... | 3-187 |
| Low Drift ($\Delta V_{OS}/Temp < 10$ μV/°C) | |
| LF155/LF255/LM355 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF155A/LF355A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156/LF256/LF356 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156A/LF356A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157/LF257/LF357 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157A/LF357A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LM108A/LM208A/LM308A, LM308A-1, LM308A-2 Operational Amplifiers..... | 3-88 |
| LM725/LM725A/LM725C (Instrumentation) Operational Amplifier..... | 3-194 |
| High Slew Rate ($S_R > 10$ V/μs) | |
| LF156/LF256/LF356 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156A/LF356A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157/LF257/LF357 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF347 Wide Bandwidth Quad JFET Input Operational Amplifier..... | 3-14 |
| LF351 Wide Bandwidth JFET Input Operational Amplifier..... | 3-22 |
| LF353 Wide Bandwidth Dual JFET Input Operational Amplifier..... | 3-29 |
| LM102/LM202/LM302 Voltage Followers..... | 3-74 |
| LM110/LM210/LM310 Voltage Follower..... | 3-95 |
| LM118/LM218/LM318 Operational Amplifiers..... | 3-106 |

Section Contents (Continued)

Low Power Consumption

| | |
|---|-------|
| LM10/LM10B(L)/LM10C(L) Op Amp and Voltage Reference..... | 3-49 |
| LM108A/LM208A/LM308A, LM308A-1, LM308A-2 Operational Amplifier..... | 3-88 |
| LM112/LM212/LM312 Operational Amplifiers..... | 3-102 |
| LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902 Low Power Quad Operational Amplifiers..... | 3-113 |
| LM146/LM246/LM346 Programmable Quad Operational Amplifiers..... | 3-135 |
| LM4250/LM4250C Programmable Operational Amplifier..... | 3-224 |

Single Supply

| | |
|---|-------|
| LM10/LM10B(L)/LM10C(L) Op Amp and Voltage Reference..... | 3-49 |
| LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902 Low Power Quad Operational Amplifiers..... | 3-113 |
| LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904 Low Power Dual Operational Amplifiers..... | 3-157 |
| LM2900/LM3900, LM3301, LM3401 Quad Amplifiers..... | 3-215 |

High Voltage ($V_{CC} > \pm 25V$)

| | |
|---|-------|
| LM143/LM343 High Voltage Operational Amplifier..... | 3-122 |
| LM144/LM344 High Voltage, High Slew Rate Operational Amplifier..... | 3-129 |

Buffer

| | |
|--|-------|
| LM102/LM202/LM302 Voltage Followers..... | 3-74 |
| LM110/LM210/LM310 Voltage Follower..... | 3-95 |
| LM733/LM733C Differential Video Amp..... | 3-198 |

Programmable

| | |
|---|-------|
| LM146/LM246/LM346 Programmable Quad Operational Amplifiers..... | 3-135 |
| LM4250/LM4250C Programmable Operational Amplifier..... | 3-224 |
| LM13080 Programmable Power Op Amp..... | 3-231 |

High Output Current ($I_O \geq 200 \text{ mA}$)

| | |
|--|-------|
| LM13080 Programmable Power Op Amp..... | 3-231 |
|--|-------|

General Purpose, Compensated

| | |
|---|-------|
| LF155/LF255/LM355 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF155A/LF355A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156/LF256/LF356 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF156A/LF356A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157/LF257/LF357 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157A/LF357A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF347 Wide Bandwidth Quad JFET Input Operational Amplifier..... | 3-14 |
| LF351 Wide Bandwidth JFET Input Operational Amplifier..... | 3-22 |
| LF353 Wide Bandwidth Dual JFET Input Operational Amplifier..... | 3-29 |
| LF13741 Monolithic JFET Input Operational Amplifier..... | 3-38 |
| LM10/LM10B(L)/LM10C(L) Op Amp and Voltage Reference..... | 3-49 |
| LM107/LM207/LM307 Operational Amplifiers..... | 3-79 |
| LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902 Low Power Quad Operational Amplifiers..... | 3-113 |
| LM148, LM149 Series Quad 741 Op Amps..... | 3-147 |
| LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904 Low Power Dual Operational Amplifiers..... | 3-157 |
| LM159/LM359 Dual, High Speed, Programmable, Current Mode (Norton) Amplifiers..... | 3-167 |
| LM741/LM741A/LM741C/LM741E Operational Amplifier..... | 3-202 |
| LM747/LM747A/LM747C/LM747E Dual Operational Amplifiers..... | 3-205 |

Section Contents (Continued)

General Purpose, Compensated (Continued)

| | |
|---|-------|
| LM1558/LM1458 Dual Operational Amplifier..... | 3-213 |
| LM2900/LM3900, LM3301, LM3401 Quad Amplifier..... | 3-215 |
| LM13080 Programmable Power Op Amp..... | 3-231 |

General Purpose, Uncompensated

| | |
|--|-------|
| LF157/LF257/LF357 Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LF157A/LF357A Monolithic JFET Input Operational Amplifier..... | 3-1 |
| LM101A/LM201A/LM301A Operational Amplifiers..... | 3-65 |
| LM709/LM709A/LM709C Operational Amplifier..... | 3-190 |
| LM748/LM748C Operational Amplifier..... | 3-210 |

Op Amp—Comparator

| | |
|--|-------|
| LM192/LM292/LM392, LM2924 Low Power Operational Amplifier/Voltage Comparator.... | 3-183 |
|--|-------|

Note. For additional information on operational amplifiers, see National Semiconductor's Special Functions Databook.

| DC ELECTRICAL CHARACTERISTICS | | | | | | | AC ELECTRICAL CHARACTERISTICS | |
|---|--|---|---|--|-----------------------|--|-------------------------------|--|
| PART NUMBER | V _{OS} – MAX OFFSET VOLTAGE (mV) (T _A = 25°C) | ΔV _{OS} /ΔT – T.C. OF V _{OS} (μV/°C) TYP | I _B – MAX BIAS CURRENT (pA) (T _J = 25°C) | AVOL LARGE SIGNAL VOLTAGE GAIN (V/mV) MIN (T _A = 25°C) | SR – SLEW RATE (V/μs) | e _n – EQUIV. INPUT NOISE VOLTAGE (nV/√Hz) (Note 2) | | |
| MILITARY BI-FET OP AMP (Note 1) | | | | | | | | |
| LF155 | 5 | 5 | 100 | 50 | 5 | 20 | | |
| LF155A | 2 | 5 (max) | 50 | 50 | 5 | 20 | | |
| LF156 | 5 | 5 | 100 | 50 | 12 | 12 | | |
| LF156A | 2 | 5 (max) | 50 | 50 | 12 | 12 | | |
| LF157 | 5 | 5 | 100 | 50 | 50 | 12 | | |
| LF157A | 2 | 5 (max) | 50 | 50 | 50 | 12 | | |
| INDUSTRIAL BI-FET OP AMP (Note 1) | | | | | | | | |
| LF255 | 5 | 5 | 100 | 50 | 5 | 20 | | |
| LF256 | 5 | 5 | 100 | 50 | 12 | 12 | | |
| LF257 | 5 | 5 | 100 | 50 | 50 | 12 | | |
| COMMERCIAL BI-FET AND BI-FET II OP AMP (Note 3) | | | | | | | | |
| LF351 | 10 | 10 | 200 | 25 | 13 | 16 | | |
| LF351A | 2 | 10 | 100 | 25 | 13 | 16 | | |
| LF351B | 5 | 10 | 200 | 25 | 13 | 16 | | |
| LF355 | 10 | 5 | 200 | 25 | 5 | 25 | | |
| LF355A | 2 | 5 (max) | 50 | 25 | 5 | 25 | | |
| LF356 | 10 | 5 | 200 | 25 | 12 | 15 | | |
| LF356A | 2 | 5 (max) | 50 | 25 | 12 | 15 | | |
| LF357 | 10 | 5 | 200 | 25 | 50 | 15 | | |
| LF357A | 2 | 5 (max) | 50 | 25 | 50 | 15 | | |
| LF13741 | 15 | 10 | 200 | 25 | 0.5 | 37 | | |
| BI-FET II DUAL OP AMPS (Characteristics for Each Amplifier) (Note 3) | | | | | | | | |
| LF353 | 10 | 10 | 200 | 25 | 13 | 16 | | |
| LF353A | 2 | 10 | 100 | 25 | 13 | 16 | | |
| LF353B | 5 | 10 | 200 | 25 | 13 | 16 | | |
| BI-FET II QUAD OP AMPS (Characteristics for Each Amplifier) (Note 3) | | | | | | | | |
| LF347 | 10 | 10 | 200 | 25 | 13 | 16 | | |
| LF347A | 2 | 10 | 100 | 25 | 13 | 16 | | |
| LF347B | 5 | 10 | 200 | 25 | 13 | 16 | | |

A-3

BI-FET™/BI-FET II™ Op Amp Selection Guide

| SELECTION BY DESIGN PARAMETER | | | | | ADDITIONAL NS PRODUCTS USING BI-FET TECHNOLOGY | |
|--|---|--|---|---|---|--|
| Max Input Offset Voltage (T _A = 25°C) | <u>2 mV</u> LF155A/LF355A LF156A/LF356A LF357A LF351A LF353A LF347A | <u>5 mV</u> LF351B LF347B LF353B LF155/LF156/LF157 LF255/LF256/LF257 | <u>10 mV</u> LF355/LF356/LF357 LF351 LF353 LF347 | <u>15 mV</u> LF13741 | <ul style="list-style-type: none"> • LF111 Comparator • LF198 Sample and Hold • LF11201 Series of Analog Switches • LF11331 Series of Analog Switches • LF11508 Series of Analog Multiplexers • LF152 Instrumentation Amplifier • LF13300 Integrating A/D Building Block | |
| Max Input Bias Current (T _J = 25°C) | <u>50 pA</u> LF155A/LF156A/LF157A LF355A/LF356A/LF357A | <u>100 pA</u> LF155/LF156/LF157 LF255/LF256/LF257 LF351A LF353A LF347A | <u>200 pA</u> LF355/LF356/LF357 LF351/LF351B LF347/LF347B LF353/LF353B LF13741 | | | |
| Typ Equivalent Input Noise Voltage per $\sqrt{\text{Hz}}$, f = 1000 Hz, R _S = 100Ω | <u>12 nV or Less</u> LF156/LF156A LF157/LF157A LF256/LF257 | <u>15 nV To 20 nV</u> LF356 LF351 LF155 LF356A LF351A LF155A LF357 LF351B LFT155 LF357A LF347 LF255 LF347A LF347B LF353 LF353A LF353B | | <u>25 nV To 37 nV</u> LF355 LF13741 LF355A | | |
| Typ Slew Rate | <u>0.5 V/μs</u> LF13741 | <u>5 V/μs</u> LF155/LF155A LF255 LF355/LF355A | <u>12 V/μs</u> LF156 LF156A LF256 LF356 LF356A | <u>13 V/μs</u> LF351 LF351A LF351B LF353 LF353A LF353B LF347 LF347A LF347B | | <u>50 V/μs</u> LF157 LF157A LF357 LF357A |

MILITARY TEMPERATURE RANGE: $-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$

| Device | Input Offset Voltage Max (mV) | Input Offset Voltage Drift Max ($\mu\text{V}/^{\circ}\text{C}$) | Input Offset Current Max (nA) | Input Bias Current Max (nA) | Voltage Gain Min (Volts/V) | Bandwidth $A_V = 1$ Typ (MHz) | Slew Rate $A_V = 1$ Typ (V/ μs) | Output Current Min @ $R_L = 2\text{k}(\text{mA})$ | Supply Voltage Min (V) | Supply Voltage Max (V) | Common Mode Range (V) | Differential Input Voltage (V) | Supply Current $T_A = 25^{\circ}\text{C}$ Max (mA) | Compensation Components Per Amplifier | Package Types |
|-----------------------------------|-------------------------------|---|-------------------------------|-----------------------------|----------------------------|-------------------------------|---|---|------------------------|------------------------|-----------------------|--------------------------------|--|---------------------------------------|---------------|
| SINGLE OP AMPS | | | | | | | | | | | | | | | |
| LH101 | 6 | 6 typ | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 0 | TO-5 F.P. |
| LM101A | 3 | 15 | 20 | 100 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 1 | TO-5 DIP F.P. |
| LM101 | 6 | 6 typ | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 1 | TO-5 F.P. |
| LM102 | 7.5 | 6 typ | * | 100 | 0.999 | 10 | 10 | 1 | ± 12 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 |
| | | | | | | | | ($R_L = 8\text{k}\Omega$) | | | | | | | |
| LM107 | 3 | 15 | 20 | 100 | 25k | 1 | 0.5 | 7.5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 0 | TO-5 DIP F.P. |
| LM108A | 1 | 5 | 0.4 | 3 | 40k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 1 | TO-5 DIP F.P. |
| LM108 | 3 | 15 | 0.4 | 3 | 25k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 1 | TO-5 DIP F.P. |
| LM110 | 6 | 12 | * | 10 | 0.999 | 20 | 30 | 1 | ± 5 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 DIP |
| | | | | | | | | ($R_L = 8\text{k}\Omega$) | | | | | | | |
| LM112 | 3 | 15 | 0.4 | 3 | 25k | 1 | 0.2 | 1.3 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 0 | TO-5 DIP F.P. |
| | | | | | | | | ($R_L = 10\text{k}\Omega$) | | | | | | | |
| LM118 | 4 | * | 50 | 250 | 20k | 15 | 50 min | 6 | ± 5 | ± 18 | ± 11.5 | (Note 1) | 8 | 0 | TO-5 DIP F.P. |
| LM121A ($R_{SET}=70\text{k}$) | 0.65 | 0.2 | 1 | 30 | 16k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 1.5 | 1 | TO-5 DIP F.P. |
| LM121 ($R_{SET}=70\text{k}$) | 1 | 1 | 3 | 30 | 16k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 1.5 | 1 | TO-5 DIP F.P. |
| LM143 | 6 | * | 7 | 35 | 50k | 1 | 2.5 | 4.4 | ± 4 | ± 40 | ± 38 | ± 40 | 4 | 0 | TO-5 DIP F.P. |
| | | | | | | | | ($R_L \geq 5\text{k}$) | | | | | | | |
| LM144 | 6 | * | 7 | 35 | 50k | 2 | 30 | 4.4 | ± 4 | ± 40 | ± 38 | ± 40 | 4 | 1 | TO-5 DIP F.P. |
| | | | | | | | ($A_V > 10$) | ($R_L \geq 5\text{k}$) | | | | | | | |
| LF155A | 2.5 | 10 | 25 | 0.05 | 25k | 2.5 | 5 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 4 | 0 | TO-5 |
| LF155 | 7 | 20 | 50 | 0.1 | 25k | 2.5 | 5 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 4 | 0 | TO-5 |
| LF156A | 2.5 | 10 | 25 | 0.05 | 25k | 5 | 15 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| LF156 | 7 | 20 | 50 | 0.1 | 25k | 5 | 15 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| LF157A ($A_V \geq 5$) | 2.5 | 10 | 25 | 0.05 | 25k | 25 | 75 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| LF157 ($A_V \geq 5$) | 7 | 20 | 50 | 0.1 | 25k | 25 | 75 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| LM709A | 3 | 15 | 250 | 600 | 25k | 1 | 0.3 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 3.6 | 3 | TO-5 |
| LM709 | 6 | 6 typ | 500 | 1500 | 25k | 1 | 0.3 | 5 | ± 9 | ± 18 | ± 8 | ± 5 | 5.5 | 3 | TO-5 DIP |
| LM725A | 0.7 | 2 | 18 | 180 | 1000 | 0.5 | 0.005 | 5 | ± 3 | ± 22 | ± 13.5 | ± 5 | 3.5 | 4 | TO-5 DIP |
| LM725 | 1.5 | 5 | 40 | 200 | 1000 | 0.5 | 0.005 | 5 | ± 3 | ± 22 | ± 13.5 | ± 5 | 3.5 | 4 | TO-5 F.P. |
| LM741A | 4 | 15 | 70 | 210 | 32k | 1 | 0.5 | 7.5 | ± 3 | ± 22 | ± 12 | ± 30 | 4.0 | 0 | TO-5 DIP F.P. |
| LM741 | 6 | 15 typ | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 2.8 | 0 | TO-5 DIP F.P. |
| LM748 | 6 | * | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 2.8 | 1 | TO-5 |
| LM4250 ($V_S = \pm 15\text{V}$) | 4 | * | 3 | 7.5 | 50k | 0.1 | 0.03 | 0.12 | ± 1 | ± 18 | ± 12 | ± 15 | 0.011 set | 0 | TO-5 DIP |
| | | | | | | | | ($R_L \geq 100\text{k}$) | | | | | | | |

Note 1: Inputs have shunt-diode protection; current must be limited. *Not specified

Military Op Amp Selection Guide

MILITARY TEMPERATURE RANGE: $-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$

| Device | Input Offset Voltage Max (mV) | Input Offset Voltage Drift Max ($\mu\text{V}/^{\circ}\text{C}$) | Input Offset Current Max (nA) | Input Bias Current Max (nA) | Voltage Gain Min (Volts/V) | Bandwidth $A_V = 1$ Typ (MHz) | Slew Rate $A_V = 1$ Typ ($\text{V}/\mu\text{s}$) | Output Current Min @ $R_L = 2\text{k}$ (mA) | Supply Voltage Min (V) | Supply Voltage Max (V) | Common Mode Range (V) | Differential Input Voltage (V) | Supply Current $T_A = 25^{\circ}\text{C}$ Max (mA) (Note 2) | Compensation Components Per Amplifier | Package Types |
|--------------------------------------|-------------------------------|---|-------------------------------|-----------------------------|----------------------------|-------------------------------|--|---|------------------------|------------------------|--------------------------|--------------------------------|---|---------------------------------------|---------------|
| DUAL OP AMPS | | | | | | | | | | | | | | | |
| LM158 | 5 | * | 30 | 150 | 25k | 1 | * | 0.8 | ± 1.5 | ± 16 | $V^+ - 1.5$ | V^+ | 1.2 | 0 | TO-5 DIP |
| LM1558 | 6 | * | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 5.0 | 0 | TO-5 |
| LM747A | 4 | 15 | 70 | 210 | 32k | 1 | 0.5 | 7.5 | ± 3 | ± 22 | ± 12 | ± 30 | 5.6 | 0 | DIP |
| LM747 | 6 | * | 500 | 1500 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 5.6 | 0 | DIP |
| QUAD OP AMPS | | | | | | | | | | | | | | | |
| LM124 | 7 | 7 typ | ± 30 | 150 | 50 | 1.0 | * | 10 | -16 | +16 | 0 to $V^+ - 1.5\text{V}$ | V_{DC}^+ | 3 | 0 | D, F, J |
| LM146 ($I_{SET} = 10 \mu\text{A}$) | 5 | 5 typ | 20 | 100 | 100k | 1.2 | 0.4 | 1.2 | ± 2 | ± 22 | ± 0.7 | ± 30 | 2 | 0 | DIP |
| LM148 | 6 | 15 typ | 75 | 325 | 25k | 1 | 0.6 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3.6 | 0 | DIP F.P. |
| LM149 ($A_V \geq 5$) | 6 | 15 typ | 75 | 325 | 25k | 4 | 3 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3.6 | 0 | DIP F.P. |
| LM1900 | * | * | * | 150 | 0.8k | 2.5 | * | 10 source 1 sink | ± 4 | ± 36 | * | * | 12 | 0 | DIP |

Note 2: Supply current for all channels of amplifier in the package.

INDUSTRIAL TEMPERATURE RANGE: $-25^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$

| Device | Input Offset Voltage Max (mV) | Input Offset Current Max ($\mu\text{V}/^{\circ}\text{C}$) | Input Offset Current Max (nA) | Input Bias Current Max (nA) | Voltage Gain Min (Volts/V) | Bandwidth $A_V = 1$ Typ (MHz) | Slew Rate $A_V = 1$ Typ (V/ μs) | Output Current Min @ $R_L = 2 \text{ k}\Omega$ (mA) | Supply Min (V) | Voltage Max (V) | Common Mode Range (V) | Differential Input Voltage (V) | Supply Current $T_A = 25^{\circ}\text{C}$ Max (mA) (Note 2) | Compensation Components Per Amplifier | Package Types |
|--------------------------------------|-------------------------------|---|--|---------------------------------------|----------------------------|-------------------------------|---|---|--------------------------|------------------------|-------------------------------------|--------------------------------|---|---------------------------------------|---------------|
| SINGLE OP AMPS | | | | | | | | | | | | | | | |
| LM201A | 3 | 15 | 20 | 100 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 1 | TO-5 DIP F.P. |
| LM202 | 10 | 15 typ | * | 15 | 0.999 | 10 | 10 | 1 | ± 12 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 |
| LM207 | 2 | 20 | 20 | 100 | 25k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 0 | TO-5 DIP F.P. |
| LM208A | 1.0 | 5 | 0.4 | 3 | 40k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 1 | TO-5 DIP F.P. |
| LM208 | 3 | 15 | 0.4 | 3 | 25k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 1 | TO-5 DIP F.P. |
| LM210 | 4 | * | * | 3 | 0.999 | 20 | 30 | 1 | ± 5 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 DIP F.P. |
| LM212 | 2 | 15 | 0.2 | 2 | 25k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.6 | 0 | TO-5 DIP F.P. |
| LM216A | 3 | * | 0.015 | 0.05 | 20k | 1 | 0.3 | 1 | ± 5 | ± 20 | ± 13 | (Note 1) | 0.6 | 0 | TO-5 DIP F.P. |
| LM216 | 10 | * | 0.05 | 0.15 | 10k | 1 | 0.3 | 1 | ± 5 | ± 20 | ± 13 | (Note 1) | 0.8 | 0 | TO-5 DIP F.P. |
| LM218 | 4 | * | 50 | 500 | 25k | 15 | 50 min | 5 | ± 5 | ± 18 | ± 11.5 | (Note 1) | 8 | 0 | TO-5 DIP F.P. |
| LM221A ($R_{SET} = 70\text{k}$) | 0.65 | 0.2 | 1 | 30 | 16k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 1.5 | 1 | TO-5 DIP F.P. |
| LM221 ($R_{SET} = 70\text{k}$) | 1 | 1 | 3 | 30 | 16k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 1.5 | 1 | TO-5 DIP F.P. |
| LF255 | 6.5 | 5 typ | 20 | 50 | 25k | 2.5 | 5 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 4 | 0 | TO-5 |
| LF256 | 6.5 | 5 typ | 20 | 50 | 25k | 5 | 15 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| LF257 ($A_V \geq 5$) | 6.5 | 5 typ | 20 | 50 | 25k | 25 | 75 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 7 | 0 | TO-5 |
| DUAL OP AMPS | | | | | | | | | | | | | | | |
| LM258 | 7.5 | 7 typ | 150 | 500 | 15k | 1 | 0.5 | 10-source 5-sink | 3 (± 1.5) | 32 (± 16) | V^+ -1.5 | 32 | 1.2 | 0 | TO-5 DIP |
| QUAD OP AMPS | | | | | | | | | | | | | | | |
| LM224 | 9 | 7 typ | 150 | 500 | 15k | 1 | * | 10 | 3 | 32 | $V^+ - 1.5$ | 32 | 2 | 0 | DIP F.P. |
| LM246 | 6 | 7 typ | 100 | 250 | 50k | 0.5 | 0.4 | 1.2 | ± 2 | ± 18 | ± 1.5 | ± 30 | 2.5 | 0 | DIP |
| LM248 | 7.5 | 15 typ | 125 | 500 | 15k | 1 | 0.5 | 5 | ± 5 | ± 18 | ± 18 | ± 36 | 4.5 | 0 | DIP |
| LM249 | 7.5 | 15 typ | 125 | 500 | 15k | 4 | 2 | 5 | ± 5 | ± 18 | ± 18 | ± 36 | 4.5 | 0 | DIP |
| LM2900 | * | * | * | 200 | 1.2k | 2.5 | * | 3-source 0.5-sink | +4 | +36 | * | * | 10 | 0 | DIP |
| LM2902 | 10 ($T_A = 25^{\circ}$) | * | ± 50 ($T_A = 25^{\circ}\text{C}$) | 500 ($T_A = 25^{\circ}\text{C}$) | 100k typ | 1 | * | 20-source 8-sink | 3.0 ± 1.5 dual | 26 ± 13 dual | -0.3 V_{DC} to $+26 V_{DC}$ | 26 V_{DC} | 2 | 0 | DIP |

Note 1: Inputs have shunt-diode protection; current must be limited.

Note 2: Supply current for all channels of amplifier in the package.

*Not specified

Commercial Op Amp Selection Guide

COMMERCIAL TEMPERATURE RANGE: $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$

| Device | Input Offset | Input Offset | Input Offset | Input Bias | Voltage | Bandwidth | Slew Rate | Output | Supply | Common | Differential | Supply | Compensation | Package Types | |
|----------------------------|--------------|------------------------------------|--------------|------------|-----------|-----------|---------------------|---------------------------|----------|----------|--------------|----------|--------------|---------------|----------------|
| | Max | Max | Max | Max | Gain | $A_V = 1$ | $A_V = 1$ | Voltage | Voltage | Mode | Input | Current | | | |
| | (mV) | ($\mu\text{V}/^{\circ}\text{C}$) | (nA) | (nA) | (Volts/V) | Typ | Typ | Swing | Min | Max | Rejection | Max | Components | | |
| | | | | | | (MHz) | (V/ μs) | $R_L = 10\text{ k}\Omega$ | | (V) | (dB) | (mA) | | | |
| | | | | | | | | (V) | | (V) | Min | (Note 2) | | | |
| SINGLE OP AMPS | | | | | | | | | | | | | | | |
| LM201 | 10 | 10 typ | 750 | 200 | 15k | 1 | 0.5 | 5 | ± 3 | ± 22 | ± 12 | ± 30 | 3 | 1 | TO-5 F. P. |
| LM301A | 10 | 30 | 70 | 300 | 15k | 1 | 0.5 | 5 | ± 3 | ± 18 | ± 12 | ± 30 | 3 | 1 | TO-5 DIP |
| LM302 | 20 | 20 typ | * | 30 | 0.9985 | 10 | 10 | 1 | ± 12 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 |
| LM307 | 10 | 30 | 50 | 250 | 15k | 1 | 0.5 | 5 | ± 3 | ± 18 | ± 12 | ± 30 | 3 | 0 | TO-5 DIP F.P. |
| LM308A | 0.73 | 5 | 1.5 | 10 | 60k | 1 | 0.3 | 1 | ± 2 | ± 20 | ± 14 | (Note 1) | 0.8 | 1 | TO-5 DIP F.P. |
| LM308 | 10 | 30 | 1.5 | 10 | 15k | 1 | 0.3 | 1 | ± 2 | ± 18 | ± 14 | (Note 1) | 0.8 | 1 | TO-5 DIP F.P. |
| LM310 | 10 | 10 typ | * | 10 | 0.999 | 20 | 30 | 1 | ± 5 | ± 18 | ± 10 | * | 5.5 | 0 | TO-5 DIP F.P. |
| LM312 | 10 | 30 | 1.5 | 10 | 15k | 1 | 0.3 | 1 | ± 2 | ± 18 | ± 14 | (Note 1) | 0.8 | 0 | TO-5 DIP F.P. |
| LM316A | 6 | * | 0.03 | 0.1 | 30k | 1 | 0.3 | 1 | ± 5 | ± 20 | ± 13 | (Note 1) | 0.6 | 0 | TO-5 DIP F.P. |
| LM316 | 15 | * | 0.1 | 0.25 | 15k | 1 | 0.3 | 1 | ± 5 | ± 20 | ± 13 | (Note 1) | 0.8 | 0 | TO-5 DIP F.P. |
| LM318 | 15 | * | 300 | 750 | 20k | 15 | 50 | 5 | ± 5 | ± 18 | ± 11.5 | (Note 1) | 10 | 0 | TO-5 DIP |
| LM321A | 0.65 | 0.2 | 1 | 25 | 12k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 2.2 | 1 | TO-5 DIP F.P. |
| ($R_{SET} = 70\text{k}$) | | | | | | | | | | | | | | | |
| LM321 | 2.5 | 1 | 4 | 28 | 12k | 0.5 | * | * | ± 5 | ± 20 | ± 15 | ± 15 | 2.2 | 1 | TO-5 DIP F.P. |
| ($R_{SET} = 70\text{k}$) | | | | | | | | | | | | | | | |
| LM343 | 10 | * | 14 | 55 | 50k | 1 | 2.5 | 4 | ± 4 | ± 34 | ± 34 | ± 34 | 5.0 | 0 | TO-5 DIP F.P. |
| | | | | | | | | ($R_L \geq 5\text{k}$) | | | | | | | |
| LM344 | 10 | * | 14 | 55 | 50k | 2 | 30 | 4 | ± 4 | ± 34 | ± 34 | ± 34 | 5.0 | 1 | TO-5 DIP F.P. |
| | | | | | | | | ($R_L \geq 5\text{k}$) | | | | | | | |
| LF351 | 10 | 10 typ | 0.1 | 0.2 | 25k | 4 | 13 | ± 12 | -18 | 18 | 70 | ± 30 | 3.4 | 0 | H, N |
| LF351A | 2 | 10 typ | 0.05 | 0.2 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | H, N |
| LF351B | 5 | 10 typ | 0.1 | 0.1 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | H, N |
| LF355A | 2.3 | 5 | 1 | 5 | 25k | 2.5 | 5 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 4 | 0 | TO-5, Mini-DIP |
| LF355 | 13 | 5 typ | 2 | 8 | 15k | 2.5 | 5 | 5 | ± 5 | ± 18 | ± 16 | ± 30 | 4 | 0 | TO-5, Mini-DIP |
| LF356A | 2.3 | 5 | 1 | 5 | 25k | 5 | 15 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 10 | 0 | TO-5, Mini-DIP |
| LF356 | 13 | 5 typ | 2 | 8 | 15k | 5 | 15 | 5 | ± 5 | ± 18 | ± 16 | ± 30 | 10 | 0 | TO-5, Mini-DIP |
| LF357A | 2.3 | 5 | 1 | 5 | 25k | 25 | 75 | 5 | ± 5 | ± 22 | ± 20 | ± 40 | 10 | 0 | TO-5, Mini-DIP |
| ($A_V \geq 5$) | | | | | | | | | | | | | | | |
| LF357 | 13 | 5 typ | 2 | 8 | 15k | 25 | 75 | 5 | ± 5 | ± 18 | ± 16 | ± 30 | 10 | 0 | TO-5, Mini-DIP |
| ($A_V \geq 5$) | | | | | | | | | | | | | | | |
| LF13741 | 20 | 10 typ | 2 | 8 | 15k | 1 | 0.5 | 5 | ± 4 | ± 18 | ± 16 | ± 30 | 4 | 0 | TO-5, Mini-DIP |

Note 1: Inputs have shunt-diode protection; current must be limited.

*Not specified

COMMERCIAL TEMPERATURE RANGE $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$

| Device | Input Offset | Input Offset | Input Offset | Input Bias | Voltage Gain | Bandwidth | Slew Rate | Output Voltage | Supply Voltage | | Common Mode Rejection Ratio | Differential Input Voltage | Supply Current | Compensation Components | Package Types |
|-----------------------------------|--------------|------------------------------------|--------------|------------|--------------|-----------|---------------------|----------------------------|----------------|--------------|-----------------------------|----------------------------|----------------|-------------------------|---------------|
| | Max | Max | Max | Max | | | | | Min | Max | | | | | |
| | (mV) | ($\mu\text{V}/^{\circ}\text{C}$) | (nA) | (nA) | (Volts/V) | (MHz) | (V/ μs) | (V) | (V) | (V) | (dB) | (V) | (mA) | | |
| SINGLE OP AMPS (Continued) | | | | | | | | | | | | | | | |
| LM709C | 10 | 12 typ | 500 | 1500 | 15k | 1 | 0.3 | 5 | ± 9 | ± 18 | ± 8 | ± 5 | 6.6 | 3 | TO-5 DIP |
| LM725C | 3.5 | 2 typ | 50 | 250 | 125k | 0.5 | 0.005 | 5 | ± 3 | ± 22 | ± 13.5 | ± 5 | 5 | 4 | TO-5 DIP |
| LM741C | 7.5 | 15 typ | 300 | 800 | 15k | 1 | 0.5 | 5 | ± 3 | ± 18 | ± 12 | ± 30 | 2.8 | 0 | TO-5 DIP F.P. |
| LM741E | 4 | 15 | 70 | 210 | 32k | 1 | 0.5 | 7.5 | ± 3 | ± 18 | ± 12 | ± 30 | 3.75 | 0 | TO-5 DIP F.P. |
| LM748C | 6 | 6 | 0.5 | 1.5 | 25k | 1 | 0.5 | 5 | ± 3 | ± 18 | ± 12 | ± 30 | 2.8 | 1 | TO-5 DIP |
| LM4250C | 6 | * | 8 | 10 | 50k | 0.1 | 0.03 | 0.12 | ± 1 | ± 18 | ± 12 | ± 15 | 0.011 | 0 | TO-5 DIP |
| | | | | | | | ($A_V > 10$) | ($R_L \geq 100\text{k}$) | | | | | (Set) | | |
| DUAL OP AMPS | | | | | | | | | | | | | | | |
| LF353 | 10 | 10 typ | 0.1 | 0.2 | 25k | 4 | 13 | ± 12 | -18 | 18 | 70 | ± 30 | 3.4 | 0 | N, H |
| LF353A | 2 | 10 typ | 0.05 | 0.2 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | N, H |
| LF353B | 5 | 10 typ | 0.1 | 0.1 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | N, H |
| LM358 | 7.5 | 7 typ | 150 | 500 | 15k | 1 | * | 8 | ± 1.5 | ± 15 | $V^+ - 1.5$ | V^+ | 1.2 | 0 | TO-5 DIP |
| LM1458 | 6 | * | 300 | 800 | 15k | 1 | 0.2 | 5 | ± 3 | ± 18 | ± 15 | ± 30 | 5.6 | 0 | TO-5 DIP |
| LM747C | 6 | * | 300 | 800 | 15k | 1 | 0.5 | 5 | ± 3 | ± 18 | ± 12 | ± 30 | 5.6 | 0 | DIP |
| LM747E | 4 | 15 | 70 | 210 | 32k | 1 | 0.5 | 7.5 | ± 3 | ± 18 | ± 12 | ± 30 | 5.6 | 0 | DIP |
| QUAD OP AMPS | | | | | | | | | | | | | | | |
| LF347 | 10 | 10 typ | 0.01 | 0.2 | 25k | 4 | 13 | ± 12 | -18 | 18 | 70 | ± 30 | 3.4 | 0 | N, J |
| LF347A | 2 | 10 typ | 0.05 | 0.2 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | N, J |
| LF347B | 5 | 10 typ | 0.1 | 0.1 | 50k | 4 | 13 | ± 12 | -18 | 18 | 80 | ± 30 | 2.8 | 0 | N, J |
| LM324 | 9 | 7 typ | 150 | 500 | 15k | 1 | * | 10-source 5-sink | 3 | 32 | $V^+ - 1.5$ | 32 | 2 | 0 | DIP F. P. |
| LM346 | 5 | 10 typ | 100 | 250 | 100k | 0.8 | 0.4 | ± 12 | -18 | 18 | 70 | ± 30 | 0.62 | 0 | N, J |
| LM348 | 7.5 | 15 typ | 100 | 400 | 15k | 1 | * | 5 | ± 5 | ± 18 | ± 18 | ± 36 | 4.5 | 0 | DIP F. P. |
| LM349 | 7.5 | 15 typ | 100 | 400 | 15k | 4 | 3 | 5 | ± 5 | ± 18 | ± 18 | ± 36 | 4.5 | 0 | DIP F. P. |
| ($A_V \geq 5$) | | | | | | | | | | | | | | | |
| LM3900 | * | * | * | 200 | 2.8k | 2.5 | 20 | 10 | 4 | 36 | * | * | 10 | 0 | DIP |
| | | | | | | | | | (± 2) | (± 18) | | | | | |

Note 2: Supply current for all channels of amplifier in the package

SPECIAL FUNCTION OPERATIONAL AMPLIFIERS

| Features | Input Offset Voltage Max (mV) | Input Offset Voltage Drift Typ ($\mu\text{V}/^\circ\text{C}$) | Input Offset Current Max (nA) | Input Bias Current Max (nA) | Voltage Gain Min (Volts/mV) | Bandwidth $A_v = 1$ Typ (MHz) | Slew Rate $A_v = 1$ Typ (V/ μs) | Output Current (mA) | Supply Voltage | | Temperature Range | | | * Page Number |
|---------------------------|-------------------------------|---|-------------------------------|-----------------------------|-----------------------------|-------------------------------|---|---------------------|----------------|----------|-------------------|---------------|-------------|---------------|
| | | | | | | | | | Min (V) | Max (V) | -55°C to 125°C | -25°C to 85°C | 0°C to 70°C | |
| | | | | | | | | | | | | | | |
| Micropower Low Drift | 1 | 4 | 20 | 100 | 25 | 1 | 0.25 | ± 5 | ± 5 | ± 20 | LH0001 | | 1-4 | |
| | 2.5 | 3 | 20 | 100 | 25 | 1 | 0.25 | ± 5 | ± 5 | ± 20 | LH0001A | | 1-7 | |
| | 5 | 3 | 60 | 200 | 25 | 1 | 0.25 | ± 5 | ± 5 | ± 20 | LH0001AC | | 1-7 | |
| Wideband | 3 | 4 | 200 | 2000 | 15 | 30 | 30 | ± 100 | ± 5 | ± 20 | LH0003 | LH0003C | | 1-10 |
| High Voltage | 1 | 4 | 20 | 100 | 30 | 1 | 0.25 | ± 15 | ± 5 | ± 45 | LH0004 | | 1-12 | |
| | 1.5 | 4 | 45 | 120 | | | 0.25 | ± 15 | ± 5 | ± 45 | LH0004C | | 1-12 | |
| Wideband | 3 | 10 | 5 | 25 | 4 | 30 (1) | 20 (1) | ± 50 | ± 9 | ± 20 | LH0005A | | 1-15 | |
| | 10 | 20 | 20 | 50 | 2 | 30 (1) | 20 (1) | ± 50 | ± 9 | ± 20 | LH0005 | | 1-15 | |
| | 10 | 25 | 25 | 100 | 2 | 30 (1) | 20 (1) | ± 50 | ± 9 | ± 20 | LH0005C | | 1-18 | |
| High Gain Medium Power | 2.5 | 10 | 50 | 250 | 100 | 1 | 0.25 | ± 40 | ± 5 | ± 22 | LH0020 | | 1-20 | |
| | 6 | 10 | 200 | 500 | 50 | 1 | 0.25 | ± 40 | ± 5 | ± 22 | LH0020C | | 1-20 | |
| High Power | 3 | 3 | 100 | 300 | 100 | 1 | 3 | ± 1000 | ± 5 | ± 18 | LH0021 | | 1-22 | |
| | 6 | 5 | 200 | 500 | 100 | 1 | 3 | ± 1000 | ± 5 | ± 18 | | LH0021C | | 1-22 |
| | 3 | 3 | 100 | 300 | 100 | 1 | 3 | ± 200 | ± 5 | ± 18 | LH0041 | | 1-22 | |
| | 6 | 5 | 200 | 500 | 100 | 1 | 3 | ± 200 | ± 5 | ± 18 | | LH0041C | | 1-22 |
| | 4 | 5 | 100 | 300 | 50 | 15 | 70 | ± 500 | ± 5 | ± 18 | LH0061 | | 1-61 | |
| | 10 | 5 | 200 | 500 | 25 | 15 | 70 | ± 500 | ± 5 | ± 18 | | LH0061C | | 1-61 |
| General Purpose FET Input | 4 | 5 | 0.002 | 0.01 | 100 | 1 | 3 | ± 10 | ± 5 | ± 22 | LH0022 | | 1-29 | |
| | 6 | 5 | 0.005 | 0.025 | 75 | 1 | 3 | ± 10 | ± 5 | ± 22 | | LH0022C | | 1-29 |
| | 20 | 5 | 0.005 | 0.025 | 50 | 1 | 3 | ± 10 | ± 5 | ± 22 | LH0042 | | 1-29 | |
| | 20 | 10 | 0.01 | 0.05 | 25 | 1 | 3 | ± 10 | ± 5 | ± 22 | | LH0042C | | 1-29 |
| | 0.5 | 2 | 0.0005 | 0.0025 | 100 | 1 | 3 | ± 10 | ± 5 | ± 22 | LH0052 | | 1-29 | |
| | 1 | 5 | 0.001 | 0.005 | 75 | 1 | 3 | ± 10 | ± 5 | ± 22 | | LH0052C | | 1-29 |
| Wideband High Slew Rate | 4 | 20 | 5,000 | 30,000 | 4 | 50 | 500 | ± 10 | ± 9 | ± 18 | LH0024 | | 1-36 | |
| | 8 | 25 | 15,000 | 40,000 | 3 | 50 | 400 | ± 10 | ± 9 | ± 18 | | LH0024C | | 1-36 |
| Wideband FET Input | 5 | 25 | 0.025 | 0.1 | 1 | 70 | 500 | ± 10 | ± 5 | ± 18 | LH0032 | | 1-39 | |
| | 15 | 25 | 0.05 | 0.2 | 1 | 70 | 500 | ± 10 | ± 5 | ± 18 | | LH0032C | | 1-39 |
| Precision FET Input | 0.05 | 0.2 | 5 | 30 | 500 | 0.4 | 0.06 | ± 1.3 | ± 3 | ± 20 | LH0044 | | 1-44 | |
| | 0.1 | 0.2 | 5 | 30 | 500 | 0.4 | 0.06 | ± 1.3 | ± 3 | ± 20 | | LH0044C | | 1-44 |
| | 0.025 | 0.1 | 2.5 | 15 | 1,000 | 0.4 | 0.06 | ± 1.3 | ± 3 | ± 20 | LH0044A | | 1-44 | |
| | 0.025 | 0.1 | 2.5 | 15 | 1,000 | 0.4 | 0.06 | ± 1.3 | ± 3 | ± 20 | | LH0044AC | | 1-44 |
| | 0.05 | 0.2 | 5 | 30 | 500 | 0.4 | 0.06 | ± 1.3 | ± 3 | ± 20 | | LH0044B | | 1-44 |
| Medium Speed. FET Input | 5 | 5 | 0.002 | 0.01 | 50 | 15 | 70 | ± 6 | ± 5 | ± 20 | LH0062 | | 1-64 | |
| | 15 | 10 | 0.005 | 0.065 | 25 | 15 | 70 | ± 6 | ± 5 | ± 20 | | LH0062C | | 1-64 |
| Dual Precision | 2 | 15 | 10 | 75 | 50 | 1 | 0.5 | ± 5 | ± 3 | ± 22 | LH2101A | | 1-72 | |
| | 2 | 15 | 10 | 75 | 50 | 1 | 0.5 | ± 5 | ± 3 | ± 22 | | LH2201A | LH2301A | 1-72 |
| | 7.5 | 30 | 50 | 250 | 25 | 1 | 0.5 | ± 5 | ± 3 | ± 22 | | LH2108A | | 1-74 |
| | 0.5 | 5 | 0.2 | 2 | 80 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | LH2208A | LH2308A | 1-74 |
| | 0.5 | 5 | 0.2 | 2 | 80 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | LH2108 | | 1-74 |
| | 0.5 | 5 | 1.0 | 7 | 80 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | LH2208 | LH2308 | 1-74 |
| | 2 | 15 | 0.2 | 2 | 50 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | | | 1-74 |
| | 2 | 15 | 0.2 | 2 | 50 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | | | 1-74 |
| | 7.5 | 30 | 1.0 | 7 | 50 | 1 | 0.3 | ± 1 | ± 2 | ± 20 | | | | 1-74 |
| Dual Low Power | 3 | — | 5 | 15 | 100 | 0.25 | 0.16 | ± 0.75 | ± 1 | ± 18 | LH24250 | | 1-76 | |
| | 6 | — | 10 | 30 | 75 | 0.25 | 0.16 | ± 0.75 | ± 1 | ± 18 | | LH24250C | | 1-76 |

Note: For information on monolithic operational amplifiers, consult the Linear Databook.

Note 1: Specified for $A_v = -10$.

*Refers to Special Functions Databook, 1979 edition

SPECIAL FUNCTION BUFFER AMPLIFIERS

| Features | Voltage Gain (min) | Output Current | Slew Rate | Input Impedance | Part Number | | * Page Number |
|-----------------------------|--------------------|----------------|-----------------------|--------------------|----------------|----------------------|---------------|
| | | | | | -55°C to 125°C | -25°C to 85°C | |
| Bipolar Input, medium speed | 0.95 | ± 100 mA | 200 V/ μs | 180 K Ω | LH0002H | LH0002CH LH0002CN | 2-4 2-4 |
| FET Input, high speed | 0.97 | ± 100 mA | 1000 V/ μs | 10^{10} Ω | LH0033G | LH0033CG LH0033CJ | 2-7 2-7 |
| FET Input, very high speed | 0.95 | ± 250 mA | 2000 V/ μs | 10^{10} Ω | LH0063K | LH0063CK | 2-7 |

*Refers to Special Functions Databook, 1979 edition

Definition of Terms

Bandwidth: That frequency at which the voltage gain is reduced to $1/\sqrt{2}$ times the low frequency value.

Common-Mode Rejection Ratio: The ratio of the input common-mode voltage range to the peak-to-peak change in input offset voltage over this range.

Harmonic Distortion: That percentage of harmonic distortion being defined as one-hundred times the ratio of the root-mean-square (rms) sum of the harmonics to the fundamental. % harmonic distortion =

$$\frac{(V_2^2 + V_3^2 + V_4^2 + \dots)^{1/2}}{V_1} (100\%)$$

where V_1 is the rms amplitude of the fundamental and V_2, V_3, V_4, \dots are the rms amplitudes of the individual harmonics.

Input Bias Current: The average of the two input currents.

Input Common-Mode Voltage Range: The range of voltages on the input terminals for which the amplifier is operational. Note that the specifications are not guaranteed over the full common-mode voltage range unless specifically stated.

Input Impedance: The ratio of input voltage to input current under the stated conditions for source resistance (R_S) and load resistance (R_L).

Input Offset Current: The difference in the currents into the two input terminals when the output is at zero.

Input Offset Voltage: That voltage which must be applied between the input terminals through two equal resistances to obtain zero output voltage.

Input Resistance: The ratio of the change in input voltage to the change in input current on either input with the other grounded.

Input Voltage Range: The range of voltages on the input terminals for which the amplifier operates within specifications.

Large-Signal Voltage Gain: The ratio of the output voltage swing to the change in input voltage required to drive the output from zero to this voltage.

Output Impedance: The ratio of output voltage to output current under the stated conditions for source resistance (R_S) and load resistance (R_L).

Output Resistance: The small signal resistance seen at the output with the output voltage near zero.

Output Voltage Swing: The peak output voltage swing, referred to zero, that can be obtained without clipping.

Offset Voltage Temperature Drift: The average drift rate of offset voltage for a thermal variation from room temperature to the indicated temperature extreme.

Power Supply Rejection: The ratio of the change in input offset voltage to the change in power supply voltages producing it.

Settling Time: The time between the initiation of the input step function and the time when the output voltage has settled to within a specified error band of the final output voltage.

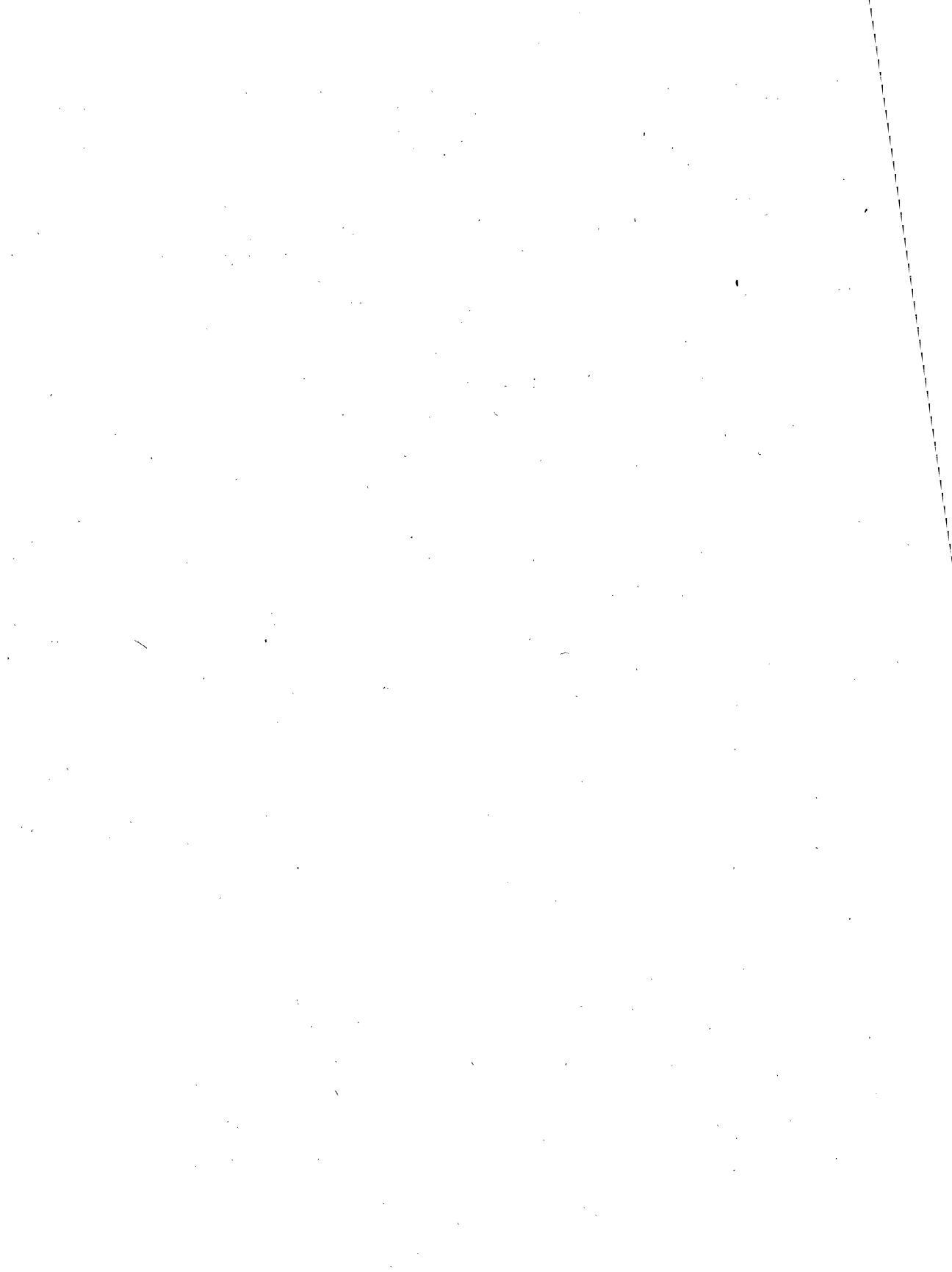
Slew Rate: The internally-limited rate of change in output voltage with a large-amplitude step function applied to the input.

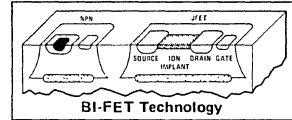
Supply Current: The current required from the power supply to operate the amplifier with no load and the output midway between the supplies.

Transient Response: The closed-loop step-function response of the amplifier under small-signal conditions.

Unity Gain Bandwidth: The frequency range from dc to the frequency where the amplifier open loop gain rolls off to one.

Voltage Gain: The ratio of output voltage to input voltage under the stated conditions for source resistance (R_S) and load resistance (R_L).





LF155/LF156/LF157 Series Monolithic JFET Input Operational Amplifiers

LF155, LF155A, LF255, LF355, LF355A, LF355B low supply current
 LF156, LF156A, LF256, LF356, LF356A, LF356B wide band
 LF157, LF157A, LF257, LF357, LF357A, LF357B wide band decompensated ($A_{V_{MIN}} = 5$)

General Description

These are the first monolithic JFET input operational amplifiers to incorporate well matched, high voltage JFETs on the same chip with standard bipolar transistors (BI-FET Technology). These amplifiers feature low input bias and offset currents, low offset voltage and offset voltage drift, coupled with offset adjust which does not degrade drift or common-mode rejection. The devices are also designed for high slew rate, wide bandwidth, extremely fast settling time, low voltage and current noise and a low 1/f noise corner.

Advantages

- Replace expensive hybrid and module FET op amps
- Rugged JFETs allow blow-out free handling compared with MOSFET input devices
- Excellent for low noise applications using either high or low source impedance—very low 1/f corner
- Offset adjust does not degrade drift or common-mode rejection as in most monolithic amplifiers
- New output stage allows use of large capacitive loads (10,000 pF) without stability problems
- Internal compensation and large differential input voltage capability

Applications

- Precision high speed integrators
- Fast D/A and A/D converters
- High impedance buffers
- Wideband, low noise, low drift amplifiers
- Logarithmic amplifiers

- Photocell amplifiers
- Sample and Hold circuits

Common Features

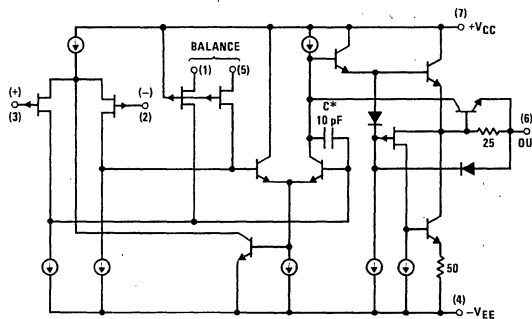
(LF155A, LF156A, LF157A)

- Low input bias current 30 pA
- Low Input Offset Current 3 pA
- High input impedance $10^{12}\Omega$
- Low input offset voltage 1 mV
- Low input offset voltage temperature drift $3\mu V/^{\circ}C$
- Low input noise current $0.01 \text{ pA}/\sqrt{\text{Hz}}$
- High common-mode rejection ratio 100 dB
- Large dc voltage gain 106 dB

Uncommon Features

| | LF155A | LF156A | LF157A ($A_V = 5$)* | UNITS |
|---|--------|--------|--------------------------|------------------------------|
| ■ Extremely fast settling time to 0.01% | 4 | 1.5 | 1.5 | μs |
| ■ Fast slew rate | 5 | 12 | 50 | $\text{V}/\mu\text{s}$ |
| ■ Wide gain bandwidth | 2.5 | 5 | 20 | MHz |
| ■ Low input noise voltage | 20 | 12 | 12 | $\text{nV}/\sqrt{\text{Hz}}$ |

Simplified Schematic



* $C = 2 \text{ pF}$ on LF157

Absolute Maximum Ratings

| | LF155A/6A/7A | LF155/6/7 | LF355B/6B/7B LF255/6/7 LF355B/6B/7B | LF355A/6A/7A LF355/6/7 |
|---|-----------------|-----------------|---|---------------------------|
| Supply Voltage | ±22V | ±22V | ±22V | ±18V |
| Power Dissipation (P_D at 25°C) and Thermal Resistance (θ_{JA}) (Note 1) | | | | |
| T_{jMAX} | | | | |
| (H and J Package) | 150°C | 150°C | 115°C | 115°C |
| (N Package) | | | 100°C | 100°C |
| (H Package) P_D | 670 mW | 670 mW | 570 mW | 570 mW |
| θ_{JA} | 150°C/W | 150°C/W | 150°C/W | 150°C/W |
| (J Package) P_D | 670 mW | 670 mW | 570 mW | 570 mW |
| θ_{JA} | 140°C/W | 140°C/W | 140°C/W | 140°C/W |
| (N Package) P_D | | | 500 mW | 500 mW |
| θ_{JA} | | | 155°C/W | 155°C/W |
| Differential Input Voltage | ±40V | ±40V | ±40V | ±30V |
| Input Voltage Range (Note 2) | ±20V | ±20V | ±20V | ±16V |
| Output Short Circuit Duration | Continuous | Continuous | Continuous | Continuous |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | 300°C | 300°C |

DC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | LF155A/6A/7A | | | LF355A/6A/7A | | | UNITS |
|---------------------------|---|---|--------------|------------------|-----|--------------|------------------|-----|----------------------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| V_{OS} | Input Offset Voltage | $R_S = 50\Omega, T_A = 25^\circ C$ | | 1 | 2 | | 1 | 2 | mV |
| | | Over Temperature | | | 2.5 | | | 2.3 | mV |
| $\Delta V_{OS}/\Delta T$ | Average TC of Input Offset Voltage | $R_S = 50\Omega$ | | 3 | 5 | | 3 | 5 | $\mu V/^\circ C$ |
| $\Delta TC/\Delta V_{OS}$ | Change in Average TC with V_{OS} Adjust | $R_S = 50\Omega, (Note\ 4)$ | | 0.5 | | | 0.5 | | $\mu V/^\circ C$ per mV |
| I_{OS} | Input Offset Current | $T_j = 25^\circ C, (Notes\ 3,\ 5)$ | | 3 | 10 | | 3 | 10 | pA |
| | | $T_j \leq T_{HIGH}$ | | | 10 | | | 1 | nA |
| I_B | Input Bias Current | $T_j = 25^\circ C, (Notes\ 3,\ 5)$ | | 30 | 50 | | 30 | 50 | pA |
| | | $T_j \leq T_{HIGH}$ | | | 25 | | | 5 | nA |
| R_{IN} | Input Resistance | $T_j = 25^\circ C$ | | 10 ¹² | | | 10 ¹² | | Ω |
| A_{VOL} | Large Signal Voltage Gain | $V_S = \pm 15V, T_A = 25^\circ C$ | 50 | 200 | | 50 | 200 | | V/mV |
| | | $V_O = \pm 10V, R_L = 2k$ Over Temperature | | 25 | | | 25 | | |
| V_O | Output Voltage Swing | $V_S = \pm 15V, R_L = 10k$ | ±12 | ±13 | | ±12 | ±13 | | V |
| | | $V_S = \pm 15V, R_L = 2k$ | ±10 | ±12 | | ±10 | ±12 | | V |
| V_{CM} | Input Common-Mode Voltage Range | $V_S = \pm 15V$ | ±11 | +15.1 | | ±11 | +15.1 | | V |
| | | | | -12 | | | -12 | | V |
| CMRR | Common-Mode Rejection Ratio | | 85 | 100 | | 85 | 100 | | dB |
| PSRR | Supply Voltage Rejection Ratio | (Note 6) | 85 | 100 | | 85 | 100 | | dB |

AC Electrical Characteristics $T_A = 25^\circ C, V_S = \pm 15V$

| SYMBOL | PARAMETER | CONDITIONS | LF155A/355A | | | LF156A/356A | | | LF157A/357A | | | UNITS |
|----------|--------------------------------|-----------------------|-------------|------|-----|-------------|------|-----|-------------|------|-----|----------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| SR | Slew Rate | LF155A/6A; $A_V = 1,$ | 3 | 5 | | 10 | 12 | | | | | V/ μs |
| | | LF157A; $A_V = 5$ | | | | | | | 40 | 50 | | V/ μs |
| GBW | Gain Bandwidth Product | | | 2.5 | | 4 | 4.5 | | 15 | 20 | | MHz |
| t_s | Settling Time to 0.01% | (Note 7) | | 4 | | | 1.5 | | | 1.5 | | μs |
| e_n | Equivalent Input Noise Voltage | $R_S = 100\Omega$ | | | | | | | | 15 | | nV/\sqrt{Hz} |
| | | $f = 100\ Hz$ | | 25 | | | 15 | | | 15 | | nV/\sqrt{Hz} |
| | | $f = 1000\ Hz$ | | 25 | | | 12 | | | 12 | | nV/\sqrt{Hz} |
| i_n | Equivalent Input Noise Current | $f = 100\ Hz$ | | 0.01 | | | 0.01 | | | 0.01 | | pA/\sqrt{Hz} |
| | | $f = 1000\ Hz$ | | 0.01 | | | 0.01 | | | 0.01 | | pA/\sqrt{Hz} |
| C_{IN} | Input Capacitance | | | 3 | | | 3 | | | 3 | | pF |

DC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | LF155/6/7 | | | LF255/6/7 LF355B/6B/7B | | | LF355/6/7 | | | UNITS |
|----------------------|--|--|-----------|------------------|-----|---------------------------|------------------|-----|------------------|--------------|--------------|-------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V _{OS} | Input Offset Voltage | R _S = 50Ω, T _A = 25°C Over Temperature | | 3 | 5 | | 3 | 5 | 3 | 10 | mV | |
| ΔV _{OS} /ΔT | Average TC of Input Offset Voltage | R _S = 50Ω | | 5 | 7 | | 5 | 6.5 | 5 | 13 | μV/°C | |
| ΔTC/ΔV _{OS} | Change in Average TC with V _{OS} Adjust | R _S = 50Ω, (Note 4) | | 0.5 | | | 0.5 | | 0.5 | | μV/°C per mV | |
| I _{OS} | Input Offset Current | T _J = 25°C, (Notes 3, 5) T _J ≤ T _{HIGH} | | 3 | 20 | | 3 | 20 | 3 | 50 | pA | |
| I _B | Input Bias Current | T _J = 25°C, (Notes 3, 5) T _J ≤ T _{HIGH} | | 30 | 100 | | 30 | 100 | 30 | 200 | pA | |
| R _{IN} | Input Resistance | T _J = 25°C | | 10 ¹² | | | 10 ¹² | | 10 ¹² | | Ω | |
| AV _{OL} | Large Signal Voltage Gain | V _S = ±15V, T _A = 25°C V _O = ±10V, R _L = 2k Over Temperature | 50 | 200 | | 50 | 200 | | 25 | 200 | V/mV | |
| V _O | Output Voltage Swing | V _S = ±15V, R _L = 10k V _S = ±15V, R _L = 2k | ±12 | ±13 | | ±12 | ±13 | | ±12 | ±13 | V | |
| V _{CM} | Input Common-Mode Voltage Range | V _S = ±15V | ±11 | +15.1 -12 | | ±11 | +15.1 -12 | | ±10 | +15.1 -12 | V | |
| CMRR | Common-Mode Rejection Ratio | | 85 | 100 | | 85 | 100 | | 80 | 100 | dB | |
| PSRR | Supply Voltage Rejection Ratio | (Note 6) | 85 | 100 | | 85 | 100 | | 80 | 100 | dB | |

DC Electrical Characteristics T_A = 25°C, V_S = ±15V

| PARAMETER | LF155A/155, LF255, LF355A/355B | | LF355 | | LF156A/156, LF256/356B | | LF356A/356 | | LF157A/157 LF257/357B | | LF357A/357 | | UNITS |
|----------------|--------------------------------------|-----|-------|-----|---------------------------|-----|------------|-----|--------------------------|-----|------------|-----|-------|
| | TYP | MAX | TYP | MAX | TYP | MAX | TYP | MAX | TYP | MAX | TYP | MAX | |
| Supply Current | 2 | 4 | 2 | 4 | 5 | 7 | 5 | 10 | 5 | 7 | 5 | 10 | mA |

AC Electrical Characteristics T_A = 25°C, V_S = ±15V

| SYMBOL | PARAMETER | CONDITIONS | LF155/255/ 355/355B | LF156/256, LF356B | LF156/256/ 356/356B | LF157/257, LF357B | LF157/257/ 357/357B | UNITS |
|-----------------|--------------------------------|---|------------------------|----------------------|------------------------|----------------------|------------------------|------------------|
| | | | TYP | MIN | TYP | MIN | TYP | |
| SR | Slew Rate | LF155/6: A _V = 1, LF157: A _V = 5 | 5 | 7.5 | 12 | 30 | 50 | V/μs |
| GBW | Gain Bandwidth Product | | 2.5 | | 5 | | 20 | MHz |
| t _s | Settling Time to 0.01% | (Note 7) | 4 | | 1.5 | | 1.5 | μs |
| e _n | Equivalent Input Noise Voltage | R _S = 100Ω f = 100 Hz f = 1000 Hz | 25 20 | | 15 12 | | 15 12 | nV/√Hz nV/√Hz |
| i _n | Equivalent Input Current Noise | f = 100 Hz f = 1000 Hz | 0.01 0.01 | | 0.01 0.01 | | 0.01 0.01 | pA/√Hz pA/√Hz |
| C _{IN} | Input Capacitance | | 3 | | 3 | | 3 | pF |

Notes for Electrical Characteristics

Note 1: The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{jMAX} , θ_{jA} , and the ambient temperature, T_A . The maximum available power dissipation at any temperature is $P_D = (T_{jMAX} - T_A)/\theta_{jA}$ or the 25°C P_{DMAX} , whichever is less.

Note 2: Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

Note 3: Unless otherwise stated, these test conditions apply:

| | LF155A/6A/7A LF155/6/7 | LF255/6/7 | LF355A/6A/7A | LF355B/6B/7B | LF355/6/7 |
|-----------------------|--|---|---------------------------------------|---------------------------------------|---------------------------------------|
| Supply Voltage, V_S | $\pm 15V \leq V_S \leq \pm 20V$ | $\pm 15V \leq V_S \leq \pm 20V$ | $\pm 15V \leq V_S \leq \pm 18V$ | $\pm 15V \leq V_S \leq \pm 20V$ | $V_S = \pm 15V$ |
| T_A | $-55^\circ C \leq T_A \leq +125^\circ C$ | $-25^\circ C \leq T_A \leq +85^\circ C$ | $0^\circ C \leq T_A \leq +70^\circ C$ | $0^\circ C \leq T_A \leq +70^\circ C$ | $0^\circ C \leq T_A \leq +70^\circ C$ |
| THIGH | +125°C | +85°C | +70°C | +70°C | +70°C |

and V_{OS} , I_B and I_{QS} are measured at $V_{CM} = 0$.

Note 4: The Temperature Coefficient of the adjusted input offset voltage changes only a small amount ($0.5\mu V/^\circ C$ typically) for each mV of adjustment from its original unadjusted value. Common-mode rejection and open loop voltage gain are also unaffected by offset adjustment.

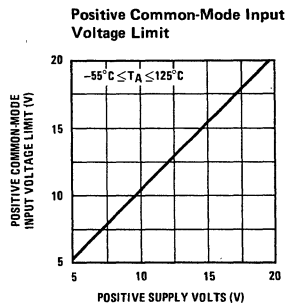
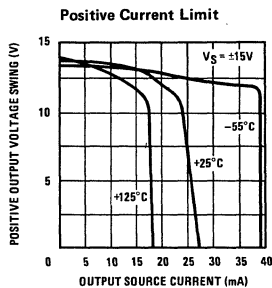
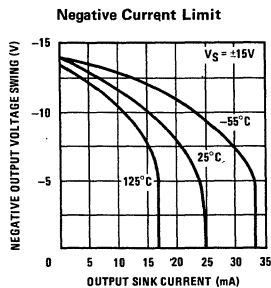
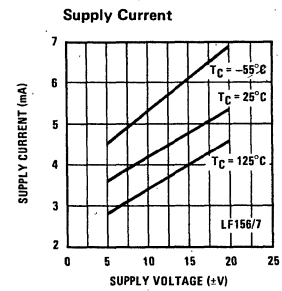
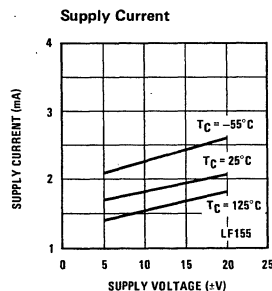
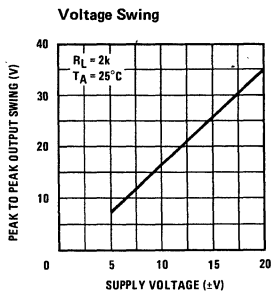
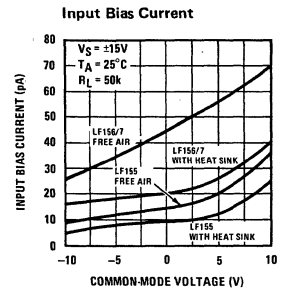
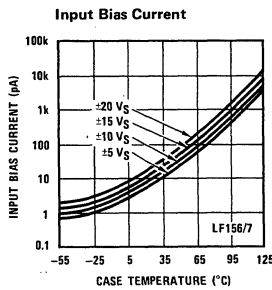
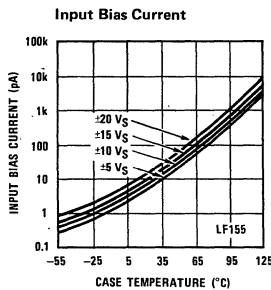
Note 5: The input bias currents are junction leakage currents which approximately double for every $10^\circ C$ increase in the junction temperature, T_j . Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_d . $T_j = T_A + \theta_{jA} P_d$ where θ_{jA} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

Note 6: Supply Voltage Rejection is measured for both supply magnitudes increasing or decreasing simultaneously, in accordance with common practice.

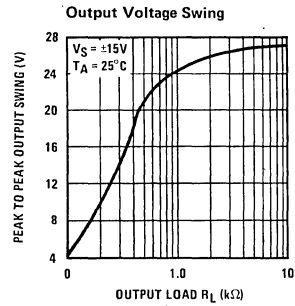
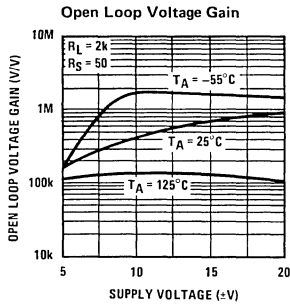
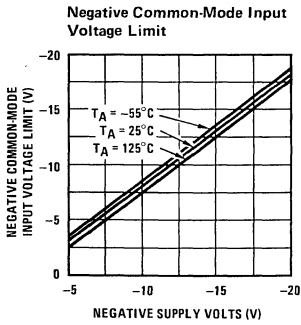
Note 7: Settling time is defined here, for a unity gain inverter connection using 2 k Ω resistors for the LF155/6. It is the time required for the error voltage (the voltage at the inverting input pin on the amplifier) to settle to within 0.01% of its final value from the time a 10V step input is applied to the inverter. For the LF157, $A_V = -5$, the feedback resistor from output to input is 2 k Ω and the output step is 10V (See Settling Time Test Circuit, page 3-9).

Typical DC Performance Characteristics

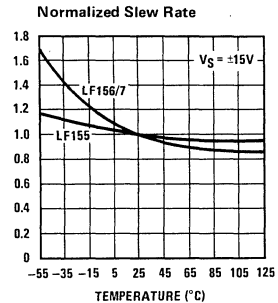
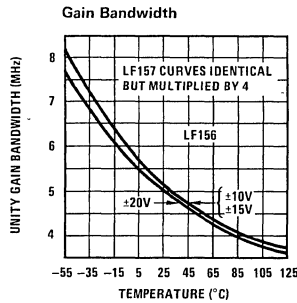
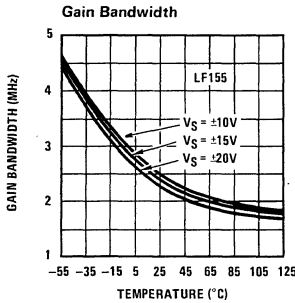
Curves are for LF155, LF156 and LF157 unless otherwise specified.



Typical DC Performance Characteristics (Continued)

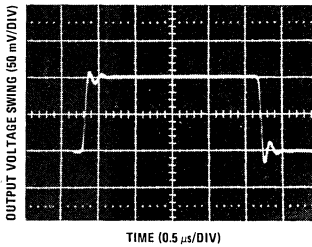


Typical AC Performance Characteristics

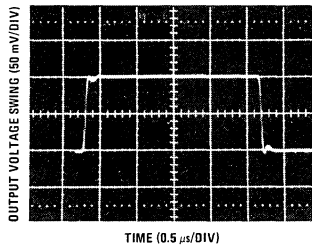


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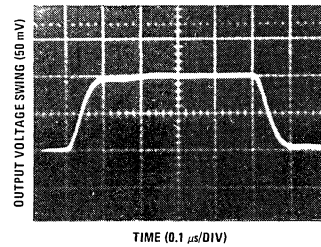
LF155 Small Signal Pulse Response, $A_V = +1$



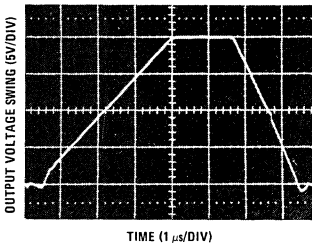
LF156 Small Signal Pulse Response, $A_V = +1$



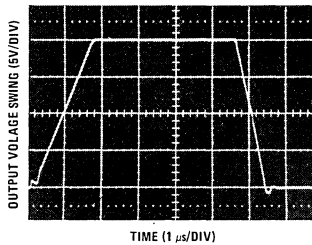
LF157 Small Signal Pulse Response, $A_V = +5$



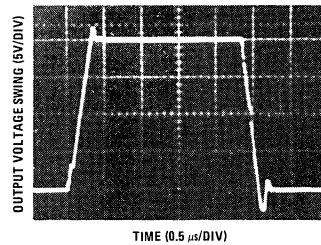
LF155 Large Signal Pulse Response, $A_V = +1$



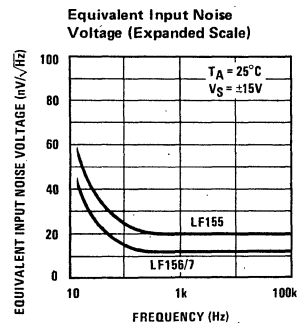
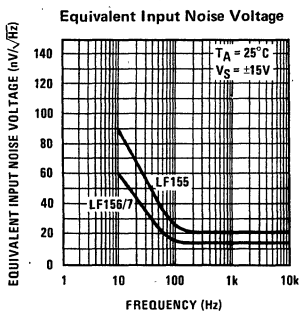
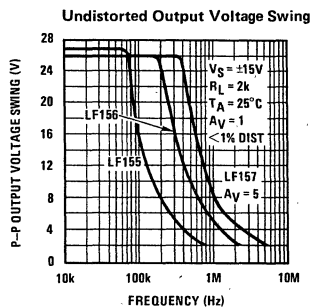
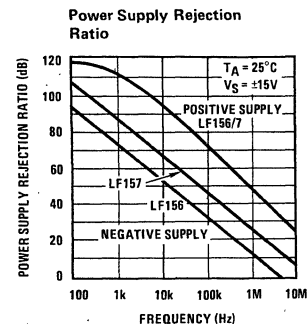
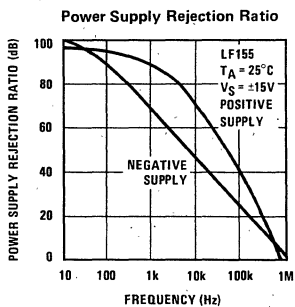
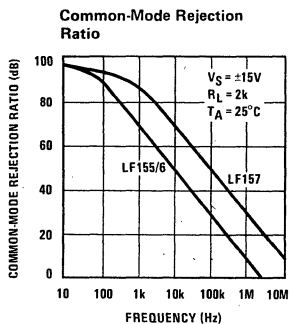
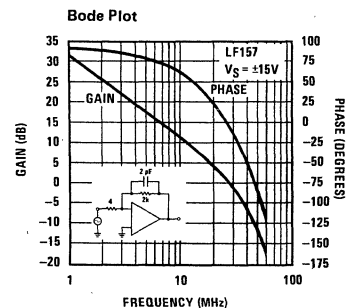
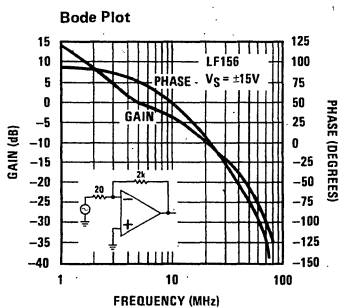
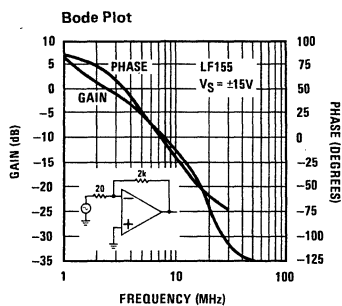
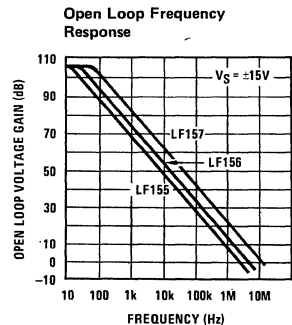
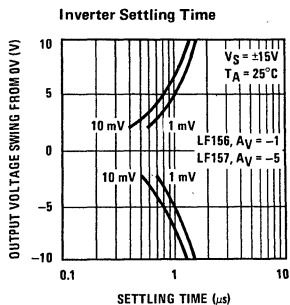
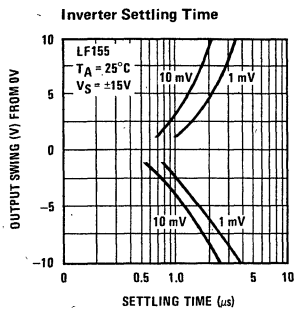
LF156 Large Signal Pulse Response, $A_V = +1$



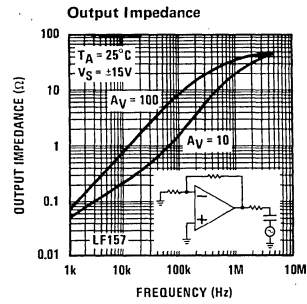
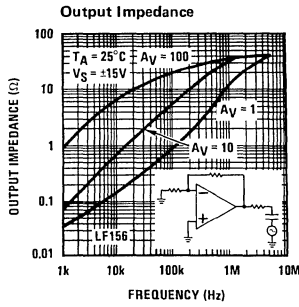
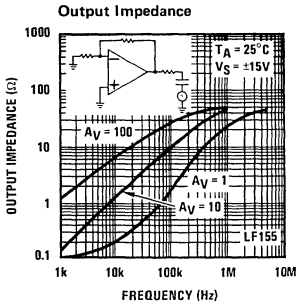
LF157 Large Signal Pulse Response, $A_V = +5$



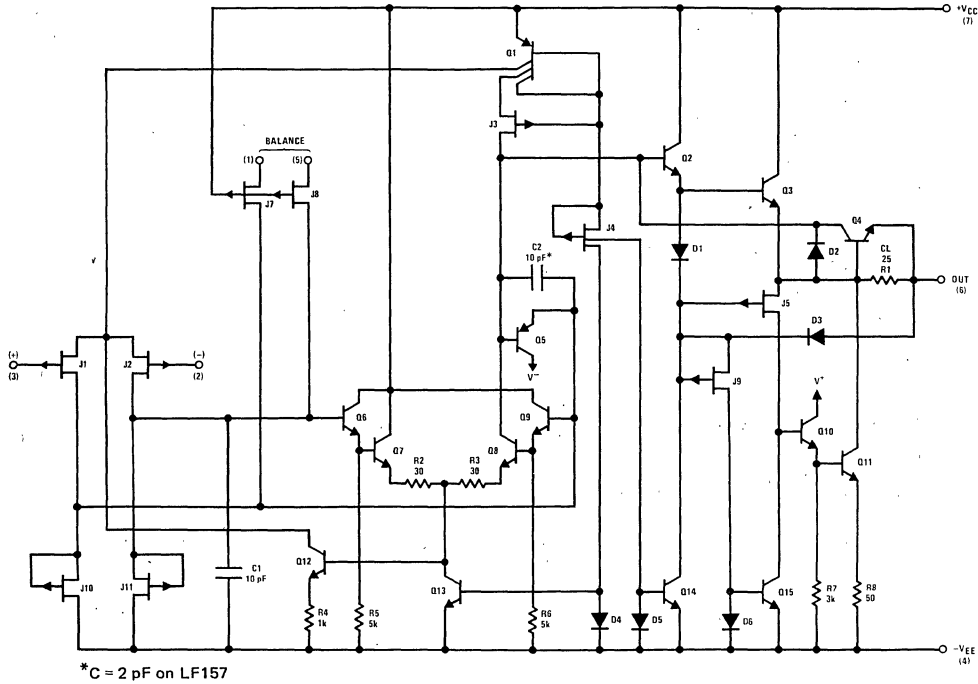
Typical AC Performance Characteristics (Continued)



Typical AC Performance Characteristics (Continued)



Detailed Schematic

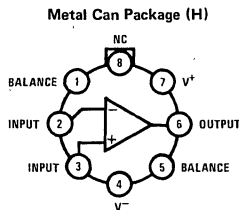


Connection Diagrams (Top Views)

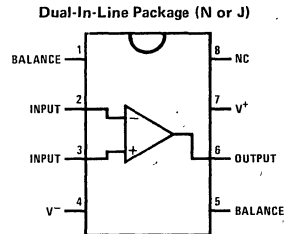
Order Number

| | | |
|---------|---------|---------|
| LF155AH | LF156AH | LF157AH |
| LF155H | LF156H | LF157H |
| LF255H | LF256H | LF257H |
| LF355AH | LF356AH | LF357AH |
| LF355H | LF356H | LF357H |

See NS Package H08C



Note 4: Pin 4 connected to case.



Order Number LF355N, LF356N
or LF357N
See NS Package N08B

Application Hints

The LF155/6/7 series are op amps with JFET input devices. These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

Exceeding the negative common-mode limit on either input will cause a reversal of the phase to the output and force the amplifier output to the corresponding high or low state. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

Exceeding the positive common-mode limit on a single input will not change the phase of the output however, if both inputs exceed the limit, the output of the amplifier will be forced to a high state.

These amplifiers will operate with the common-mode input voltage equal to the positive supply. In fact, the common-mode voltage can exceed the positive supply by approximately 100 mV independent of supply voltage and over the full operating temperature range. The positive supply can therefore be used as a reference on an input as, for example, in a supply current monitor and/or limiter.

Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed

in polarity or that the unit is not inadvertently installed backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Because these amplifiers are JFET rather than MOSFET input op amps they do not require special handling.

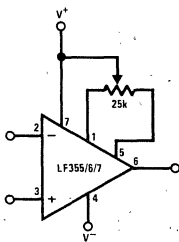
All of the bias currents in these amplifiers are set by FET current sources. The drain currents for the amplifiers are therefore essentially independent of supply voltage.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize "pickup" and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to ac ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately six times the expected 3 dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

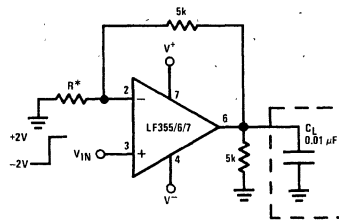
Typical Circuit Connections

V_{OS} Adjustment



- V_{OS} is adjusted with a 25k potentiometer
- The potentiometer wiper is connected to V⁺
- For potentiometers with temperature coefficient of 100 ppm/°C or less the additional drift with adjust is ≈ 0.5 μV/°C/mV of adjustment
- Typical overall drift: 5 μV/°C ± (0.5 μV/°C/mV of adj.)

Driving Capacitive Loads



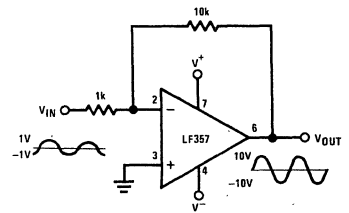
- * LF155/6 R = 5k
- LF157 R = 1.25k

Due to a unique output stage design, these amplifiers have the ability to drive large capacitive loads and still maintain stability. C_L(MAX) ≈ 0.01 μF.

Overshoot ≤ 20%

Settling time (t_s) ≈ 5 μs

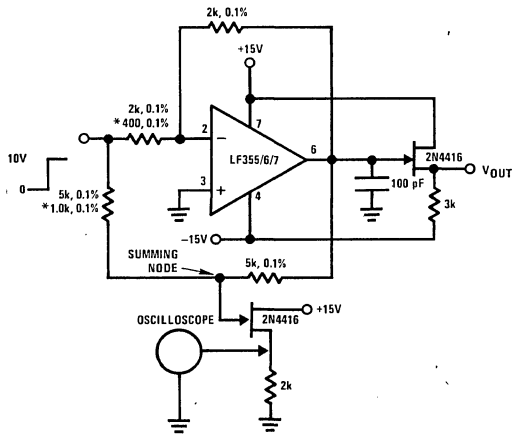
LF157. A Large Power BW Amplifier



For distortion ≤ 1% and a 20 V_{p-p} V_{OUT} swing, power bandwidth is: 500 kHz.

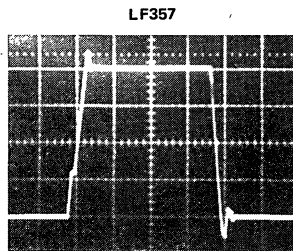
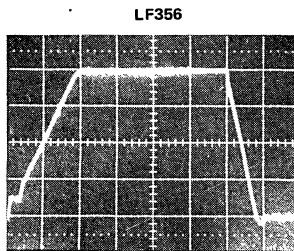
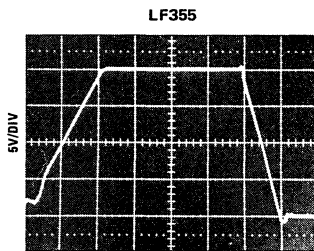
Typical Applications

Settling Time Test Circuit



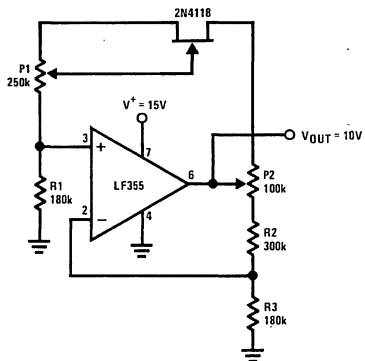
- Settling time is tested with the LF155/6 connected as unity gain inverter and LF157 connected for $A_V = -5$
- FET used to isolate the probe capacitance
- Output = 10V step
- $A_V = -5$ for LF157

Large Signal Inverter Output, V_{OUT} (from Settling Time Circuit)



3

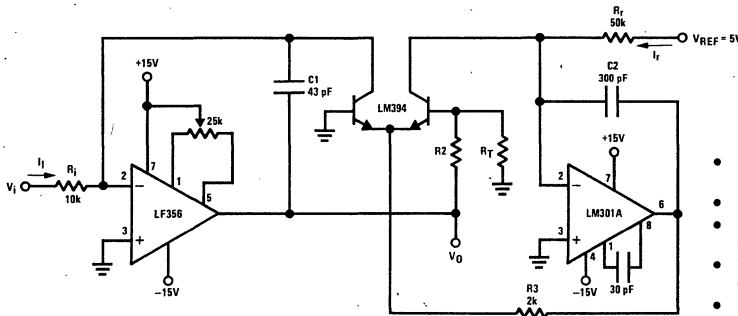
Low Drift Adjustable Voltage Reference



- $\Delta V_{OUT}/\Delta T = \pm 0.002\%/^{\circ}C$
- All resistors and potentiometers should be wire-wound
- P1: drift adjust
- P2: V_{OUT} adjust
- Use LF155 for
 - ▲ Low I_B
 - ▲ Low drift
 - ▲ Low supply current

Typical Applications (Continued)

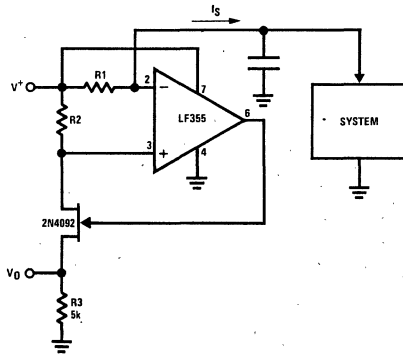
Fast Logarithmic Converter



- Dynamic range: $100 \mu\text{A} \leq I_i \leq 1 \text{ mA}$ (5 decades), $|V_O| = 1\text{V/decade}$
- Transient response: $3 \mu\text{s}$ for $\Delta I_i = 1$ decade
- C1, C2, R2, R3: added dynamic compensation
- V_{OS} adjust the LF156 to minimize quiescent error
- R_T : Tel Labs type Q81 + 0.3%/°C

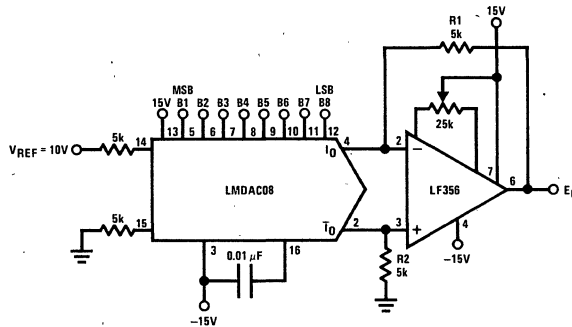
$$|V_{OUT}| = \left[1 + \frac{R_2}{R_T} \right] \frac{kT}{q} \ln V_i \left[\frac{R_r}{V_{REF} R_i} \right] = \log V_i \frac{1}{R_i I_r} \quad R_2 = 15.7\text{k}, R_T = 1\text{k}, 0.3\%/^\circ\text{C (for temperature compensation)}$$

Precision Current Monitor



- $V_O = 5 R_1/R_2$ (V/mA of I_S)
- R1, R2, R3: 0.1% resistors
- Use LF155 for
 - ▲ Common-mode range to supply range
 - ▲ Low I_B
 - ▲ Low V_{OS}
 - ▲ Low supply current

8-Bit D/A Converter with Symmetrical Offset Binary Operation

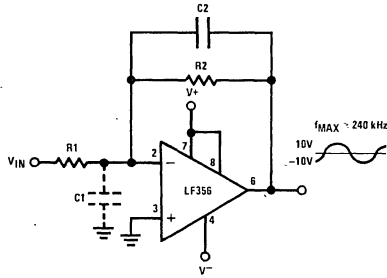


- R1, R2 should be matched within $\pm 0.05\%$
- Full-scale response time: $3 \mu\text{s}$

| E_O | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B8 | COMMENTS |
|--------|----|----|----|----|----|----|----|----|---------------------|
| +9.920 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Positive Full-Scale |
| +0.040 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | (+) Zero-Scale |
| -0.040 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | (-) Zero-Scale |
| -9.920 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Negative Full-Scale |

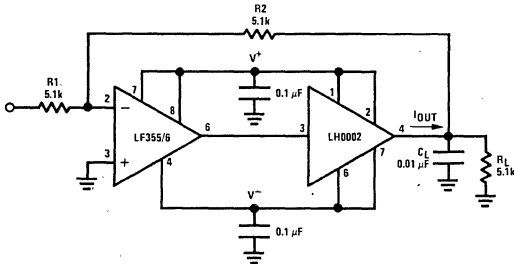
Typical Applications (Continued)

Wide BW Low Noise, Low Drift Amplifier



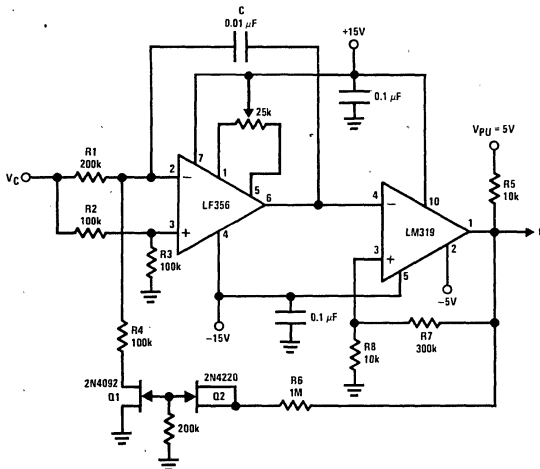
- Power BW: $f_{MAX} = \frac{S_f}{2\pi V_p} \approx 240 \text{ kHz}$
- Parasitic input capacitance $C_1 \approx (3 \text{ pF for LF155, LF156 and LF157 plus any additional layout capacitance})$ interacts with feedback elements and creates undesirable high frequency pole. To compensate add C_2 such that: $R_2 C_2 \approx R_1 C_1$.

Boosting the LF156 with a Current Amplifier



- $I_{OUT(MAX)} \approx 150 \text{ mA}$ (will drive $R_L \geq 100\Omega$)
- $\frac{\Delta V_{OUT}}{\Delta T} = \frac{0.15}{10^{-2}} \text{ V}/\mu\text{s}$ (with C_L shown)
- No additional phase shift added by the current amplifier

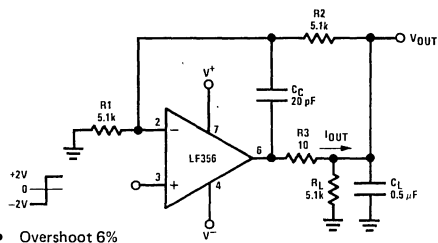
3 Decades VCO



$$f = \frac{V_C (R_8 + R_7)}{[8 V_{PU} R_8 R_1] C}, \quad 0 \leq V_C \leq 30V, \quad 10 \text{ Hz} \leq f \leq 10 \text{ kHz}$$

R_1, R_4 matched. Linearity 0.1% over 2 decades.

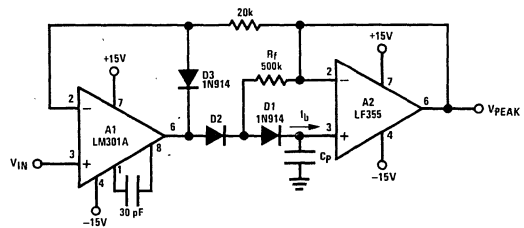
Isolating Large Capacitive Loads



- Overshoot 6%
- $t_s \approx 10 \mu\text{s}$
- When driving large C_L , the V_{OUT} slew rate determined by C_L and $I_{OUT(MAX)}$:

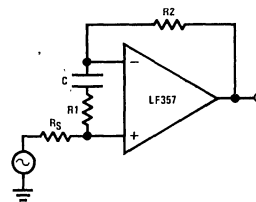
$$\frac{\Delta V_{OUT}}{\Delta T} = \frac{I_{OUT}}{C_L} \approx \frac{0.02}{0.5} \text{ V}/\mu\text{s} = 0.04 \text{ V}/\mu\text{s} \text{ (with } C_L \text{ shown)}$$

Low Drift Peak Detector



- By adding D_1 and R_f , $V_{D1} = 0$ during hold mode. Leakage of D_2 provided by feedback path through R_f .
- Leakage of circuit is essentially I_b (LF155, LF156) plus capacitor leakage of C_p .
- Diode D_3 clamps V_{OUT} (A1) to $V_{IN} - V_{D3}$ to improve speed and to limit reverse bias of D_2 .
- Maximum input frequency should be $\ll 1/2\pi R_f C_{D2}$ where C_{D2} is the shunt capacitance of D_2 .

Non-Inverting Unity Gain Operation for LF157



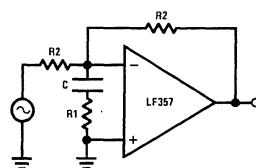
$$R_1 C \geq \frac{1}{(2\pi) (5 \text{ MHz})}$$

$$R_1 = \frac{R_2 + R_3}{4}$$

$$A_V(DC) = 1$$

$$f_{-3 \text{ dB}} \approx 5 \text{ MHz}$$

Inverting Unity Gain for LF157



$$R_1 C \geq \frac{1}{(2\pi) (5 \text{ MHz})}$$

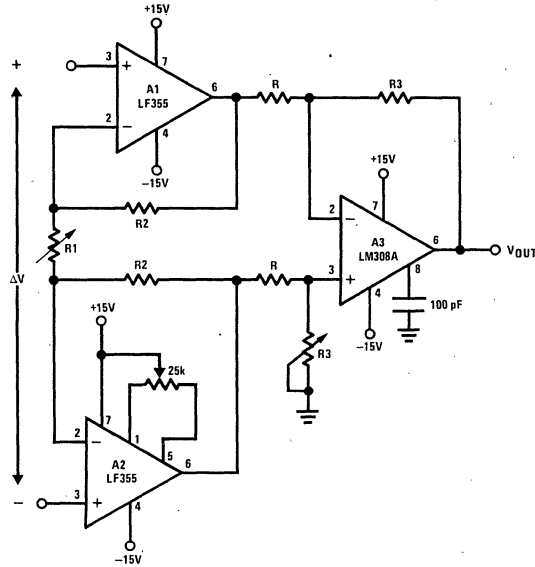
$$R_1 = \frac{R_2}{4}$$

$$A_V(DC) = -1$$

$$f_{-3 \text{ dB}} \approx 5 \text{ MHz}$$

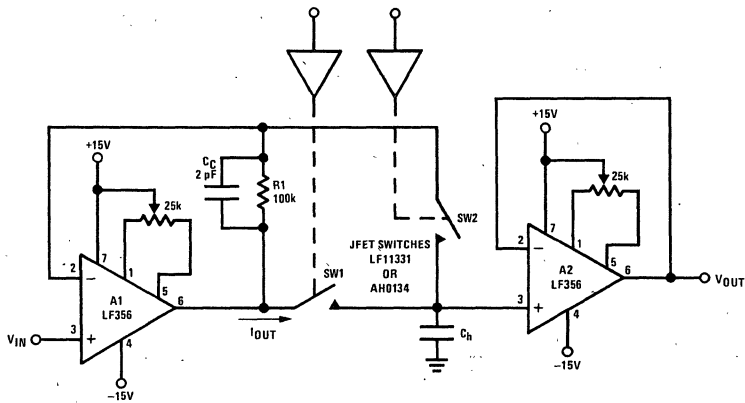
Typical Applications (Continued)

High Impedance, Low Drift Instrumentation Amplifier



- $V_{OUT} = \frac{R3}{R} \left[\frac{2R2}{R1} + 1 \right] \Delta V, V^- + 2V \leq V_{IN} \text{ common-mode} \leq V^+$
- System V_{OS} adjusted via A2 V_{OS} adjust
- Trim R3 to boost up CMRR to 120 dB. Instrumentation amplifier Resistor array RA201 (National Semiconductor) recommended

Fast Sample and Hold



- Both amplifiers (A1, A2) have feedback loops individually closed with stable responses (overshoot negligible)
- Acquisition time T_A , estimated by:

$$T_A \approx \left[\frac{2R_{ON} \cdot V_{IN} \cdot C_h}{S_r} \right]^{1/2} \text{ provided that:}$$

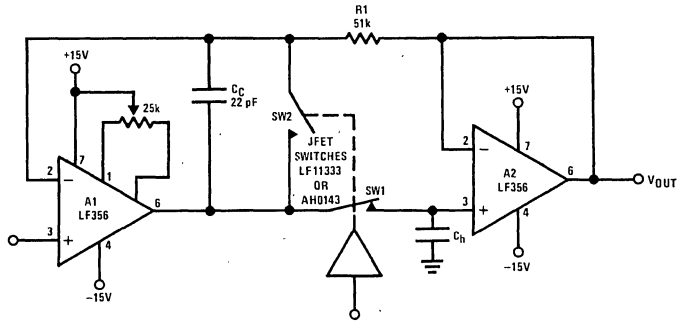
$$V_{IN} < 2\pi S_r R_{ON} C_h \text{ and } T_A > \frac{V_{IN} C_h}{I_{OUT(MAX)}} \text{, } R_{ON} \text{ is of SW1}$$

$$\text{If inequality not satisfied: } T_A \approx \frac{V_{IN} C_h}{20 \text{ mA}}$$

- LF156 develops full S_r output capability for $V_{IN} \geq 1V$
- Addition of SW2 improves accuracy by putting the voltage drop across SW1 inside the feedback loop
- Overall accuracy of system determined by the accuracy of both amplifiers, A1 and A2

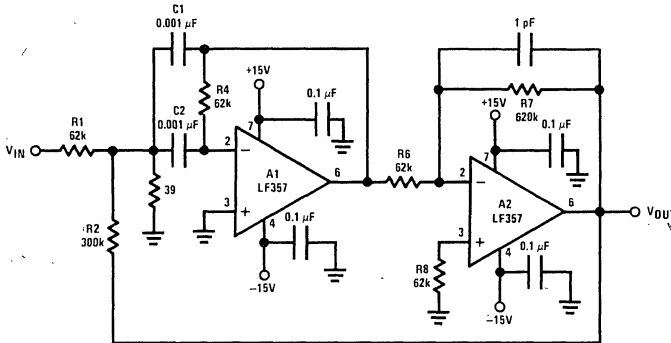
Typical Applications (Continued)

High Accuracy Sample and Hold



- By closing the loop through A2, the V_{OUT} accuracy will be determined uniquely by A1. No V_{OS} adjust required for A2.
- T_A can be estimated by same considerations as previously but, because of the added propagation delay in the feedback loop (A2) the overshoot is not negligible.
- Overall system slower than fast sample and hold
- R1, C_C : additional compensation
- Use LF156 for
 - ▲ Fast settling time
 - ▲ Low V_{OS}

High Q Band Pass Filter

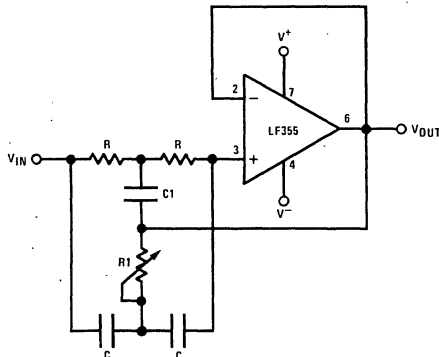


- By adding positive feedback (R2) Q increases to 40
- $f_{BP} = 100$ kHz

$$\frac{V_{OUT}}{V_{IN}} = 10\sqrt{Q}$$

- Clean layout recommended
- Response to a 1 Vp-p tone burst: 300 μ s

High Q Notch Filter

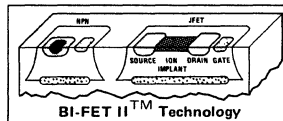


- $2R1 = R = 10$ M Ω
- $2C = C1 = 300$ pF
- Capacitors should be matched to obtain high Q
- $f_{NOTCH} = 120$ Hz, notch = -55 dB, $Q > 100$
- Use LF155 for
 - ▲ Low I_B
 - ▲ Low supply current



Operational Amplifiers/Buffers

LF347 Wide Bandwidth Quad JFET Input Operational Amplifier



General Description

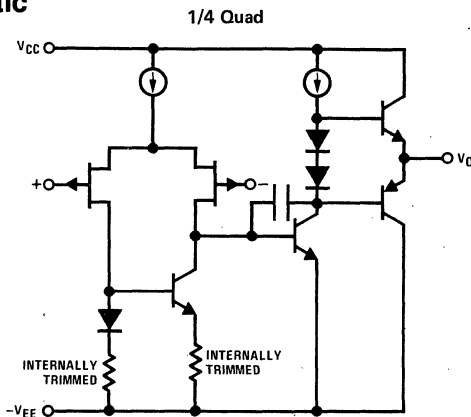
The LF347 is a low cost, high speed quad JFET input operational amplifier with an internally trimmed input offset voltage (BI-FET IITM technology). The device requires a low supply current and yet maintains a large gain bandwidth product and a fast slew rate. In addition, well matched high voltage JFET input devices provide very low input bias and offset currents. The LF347 is pin compatible with the standard LM348. This feature allows designers to immediately upgrade the overall performance of existing LM348 and LM324 designs.

The LF347 may be used in applications such as high speed integrators, fast D/A converters, sample-and-hold circuits and many other circuits requiring low input offset voltage, low input bias current, high input impedance, high slew rate and wide bandwidth. The device has low noise and offset voltage drift.

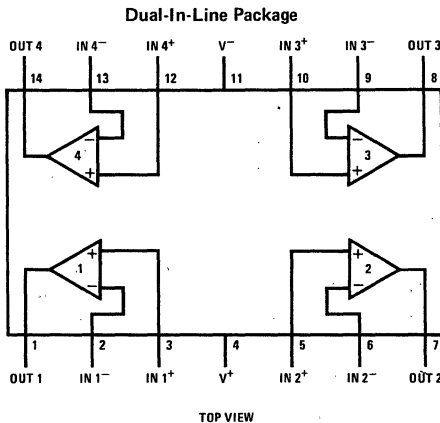
Features

- Internally trimmed offset voltage 2 mV
- Low input bias current 50 pA
- Low input noise voltage 16 nV/√Hz
- Low input noise current 0.01 pA/√Hz
- Wide gain bandwidth 4 MHz
- High slew rate 13 V/μs
- Low supply current 7.2 mA
- High input impedance 10¹²Ω
- Low total harmonic distortion $A_V = 10$, $R_L = 10k$, $V_O = 20$ Vp-p, BW = 20 Hz–20 kHz < 0.02%
- Low 1/f noise corner 50 Hz
- Fast settling time to 0.01% 2 μs

Simplified Schematic



Connection Diagram



Order Number LF347N, LF347AN
or LF347BN
See NS Package N14A

Order Number LF347J, LF347AJ
or LF347BJ
See NS Package J14A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Operating Temperature Range | 0°C to +70°C |
| T _j (MAX) | 115°C |
| Differential Input Voltage | ±30V |
| Input Voltage Range (Note 2) | ±15V |
| Output Short Circuit Duration (Note 3) | Continuous |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (Note 4)

| SYMBOL | PARAMETER | CONDITIONS | LF347A | | | LF347B | | | LF347 | | | UNITS |
|----------------------|------------------------------------|--|--------|------------------|----------|--------|------------------|----------|-------|------------------|----------|--------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V _{OS} | Input Offset Voltage | R _S = 10 kΩ, T _A = 25°C Over Temperature | | 1 4 | 2 4 | | 3 7 | 5 7 | | 5 10 13 | | mV mV |
| ΔV _{OS} /ΔT | Average TC of Input Offset Voltage | R _S = 10 kΩ | | 10 | | | 10 | | | 10 | | μV/°C |
| I _{OS} | Input Offset Current | T _j = 25°C, (Notes 4, 5) T _j ≤ 70°C | | 25 2 | 100 2 | | 25 4 | 100 7 | | 25 4 | 100 4 | pA nA |
| I _B | Input Bias Current | T _j = 25°C, (Notes 4, 5) T _j ≤ 70°C | | 50 4 | 200 4 | | 50 8 | 200 8 | | 50 8 | 200 8 | pA nA |
| R _{IN} | Input Resistance | T _j = 25°C | | 10 ¹² | | | 10 ¹² | | | 10 ¹² | | Ω |
| AVOL | Large Signal Voltage Gain | V _S = ±15V, T _A = 25°C V _O = ±10V, R _L = 2 kΩ Over Temperature | 50 | 100 | | 50 | 100 | | 25 | 100 | | V/mV V/mV |
| V _O | Output Voltage Swing | V _S = ±15V, R _L = 10 kΩ | ±12 | ±13.5 | | ±12 | ±13.5 | | ±12 | ±13.5 | | V |
| V _{CM} | Input Common-Mode Voltage Range | V _S = ±15V | ±11 | +15 -12 | | ±11 | +15 -12 | | ±11 | +15 -12 | | V V |
| CMRR | Common-Mode Rejection Ratio | R _S ≤ 10 kΩ | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| PSRR | Supply Voltage Rejection Ratio | (Note 6) | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| I _S | Supply Current | | | 7.2 | 11 | | 7.2 | 11 | | 7.2 | 11 | mA |

AC Electrical Characteristics (Note 4)

| SYMBOL | PARAMETER | CONDITIONS | LF347A | | | LF347B | | | LF347 | | | UNITS |
|----------------|---------------------------------|---|--------|------|-----|--------|------|-----|-------|------|-----|--------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| | Amplifier to Amplifier Coupling | T _A = 25°C, f = 1 Hz–20 kHz (Input Referred) | | -120 | | | -120 | | | -120 | | dB |
| SR | Slew Rate | V _S = ±15V, T _A = 25°C | | 13 | | | 13 | | | 13 | | V/μs |
| GBW | Gain-Bandwidth Product | V _S = ±15V, T _A = 25°C | | 4 | | | 4 | | | 4 | | MHz |
| e _n | Equivalent Input Noise Voltage | T _A = 25°C, R _S = 100Ω, f = 1000 Hz | | 16 | | | 16 | | | 16 | | nV/√Hz |
| i _n | Equivalent Input Noise Current | T _j = 25°C, f = 1000 Hz | | 0.01 | | | 0.01 | | | 0.01 | | pA/√Hz |

Note 1: For operating at elevated temperature, the device must be derated based on a thermal resistance of 125°C/W junction to ambient or 95°C/W junction to case.

Note 2: Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

Note 3: P_D max rating cannot be exceeded.

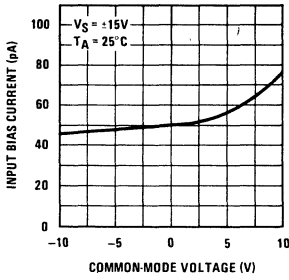
Note 4: These specifications apply for V_S = ±15V and 0°C ≤ T_A ≤ +70°C. V_{OS}, I_B and I_{OS} are measured at V_{CM} = 0.

Note 5: The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_j. Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_D. T_j = T_A + θ_{jA} P_D where θ_{jA} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

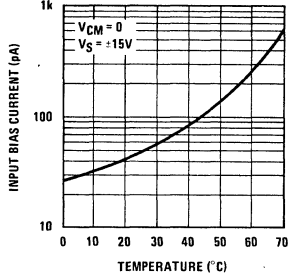
Note 6: Supply voltage rejection ratio is measured for both supply magnitudes increasing or decreasing simultaneously in accordance with common practice.

Typical Performance Characteristics

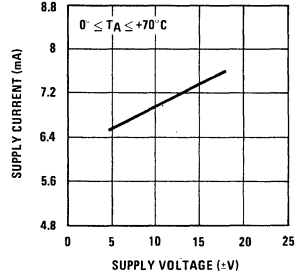
Input Bias Current



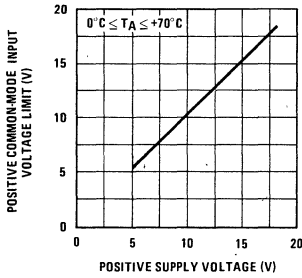
Input Bias Current



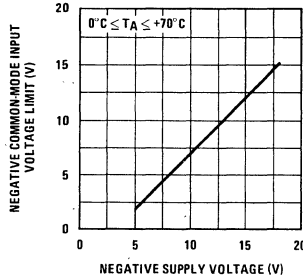
Supply Current



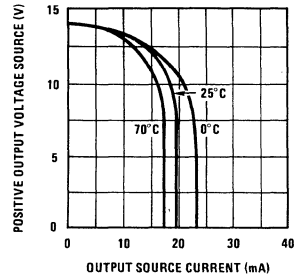
Positive Common-Mode Input Voltage Limit



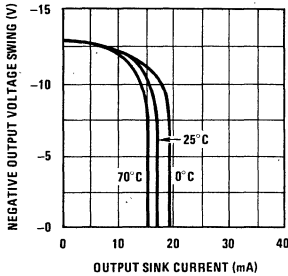
Negative Common-Mode Input Voltage Limit



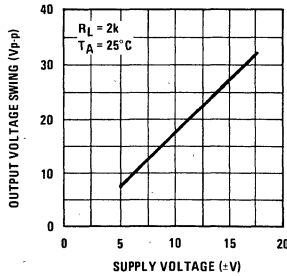
Positive Current Limit



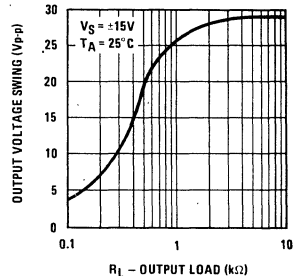
Negative Current Limit



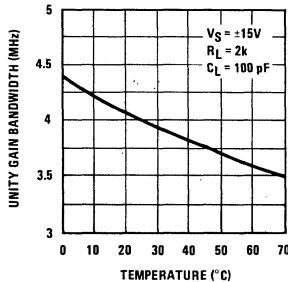
Voltage Swing



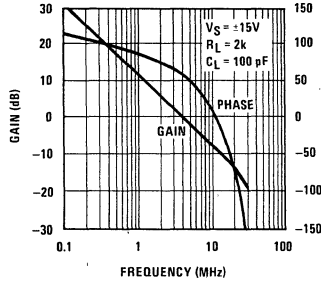
Output Voltage Swing



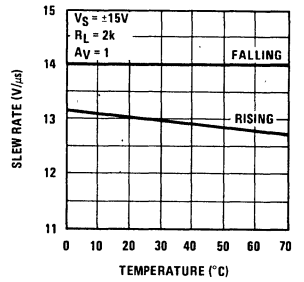
Gain Bandwidth



Bode Plot

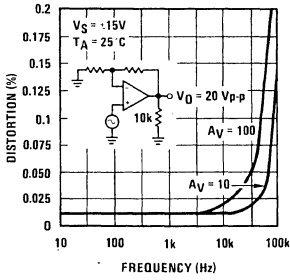


Slew Rate

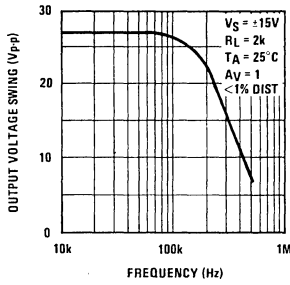


Typical Performance Characteristics (Continued)

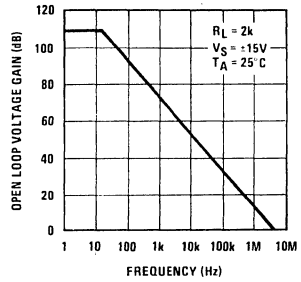
Distortion vs Frequency



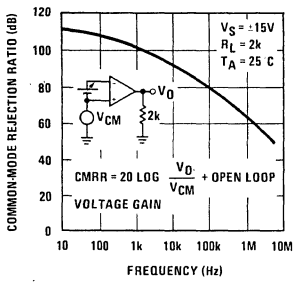
Undistorted Output Voltage Swing



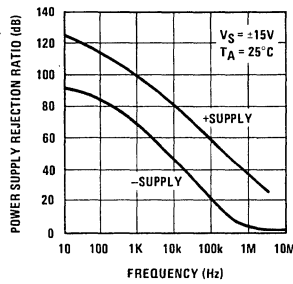
Open Loop Frequency Response



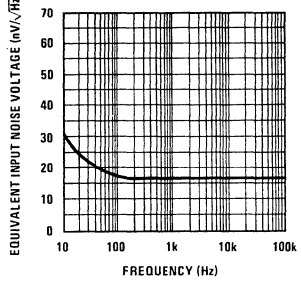
Common-Mode Rejection Ratio



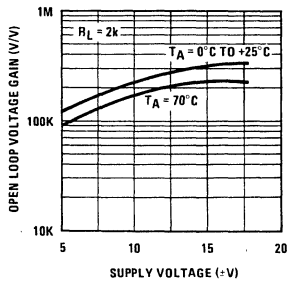
Power Supply Rejection Ratio



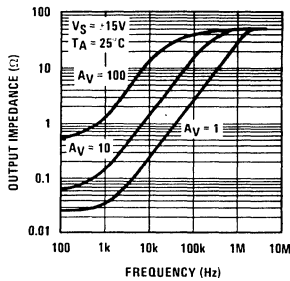
Equivalent Input Noise Voltage



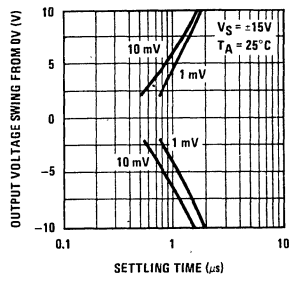
Open Loop Voltage Gain (V/V)



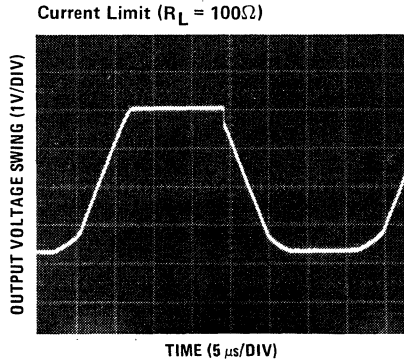
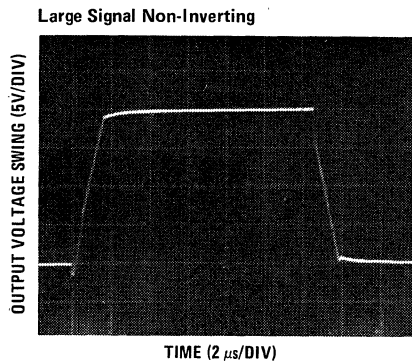
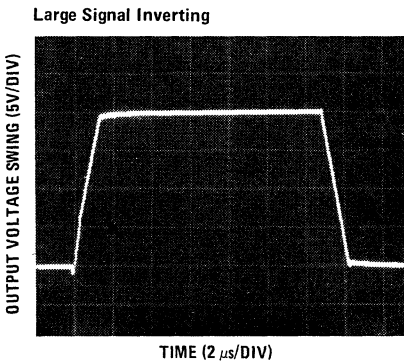
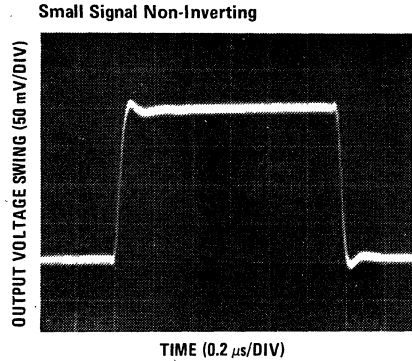
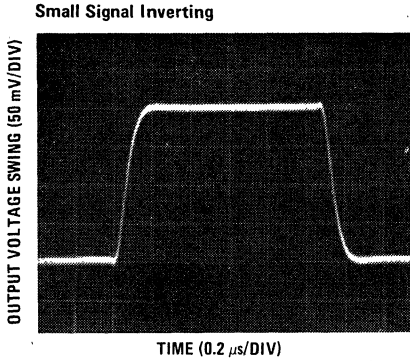
Output Impedance



Inverter Settling Time



Pulse Response



Application Hints

The LF347 is an op amp with an internally trimmed input offset voltage and JFET input devices (BI-FET II™). These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore, large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be

allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

Exceeding the negative common-mode limit on either input will cause a reversal of the phase to the output and force the amplifier output to the corresponding high or low state. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a

Application Hints (Continued)

high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

Exceeding the positive common-mode limit on a single input will not change the phase of the output; however, if both inputs exceed the limit, the output of the amplifier will be forced to a high state.

The amplifiers will operate with a common-mode input voltage equal to the positive supply; however, the gain bandwidth and slew rate may be decreased in this condition. When the negative common-mode voltage swings to within 3V of the negative supply, an increase in input offset voltage may occur.

Each amplifier is individually biased by a zener reference which allows normal circuit operation on $\pm 4V$ power supplies. Supply voltages less than these may result in lower gain bandwidth and slew rate.

The LF347 will drive a 2 k Ω load resistance to $\pm 10V$ over the full temperature range of 0°C to +70°C. If the amplifier is forced to drive heavier load currents, however, an increase in input offset voltage may occur on the negative voltage swing and finally reach an active current limit on both positive and negative swings.

Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed

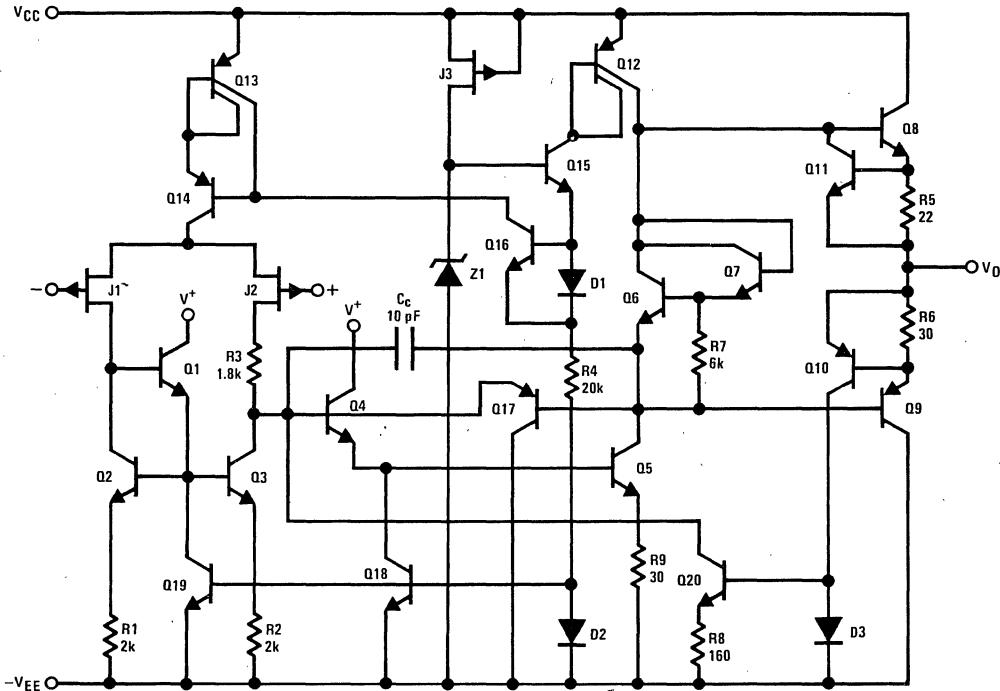
backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Because these amplifiers are JFET rather than MOSFET input op amps they do not require special handling.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize "pick-up" and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

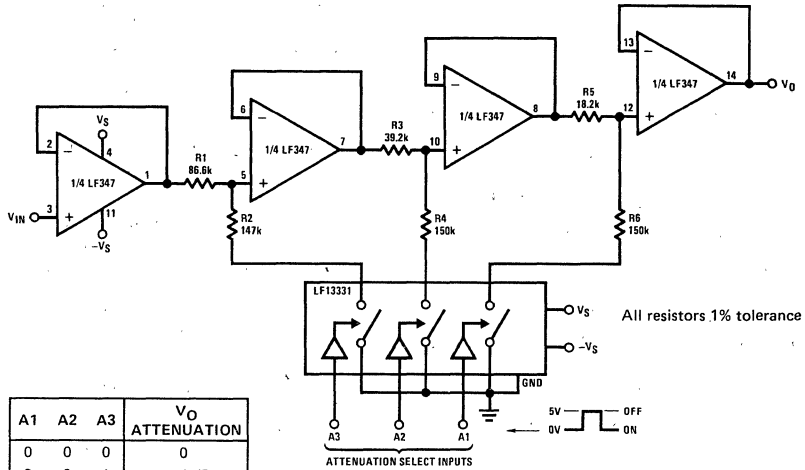
A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to AC ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately 6 times the expected 3 dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

Detailed Schematic



Typical Applications

Digitally Selectable Precision Attenuator

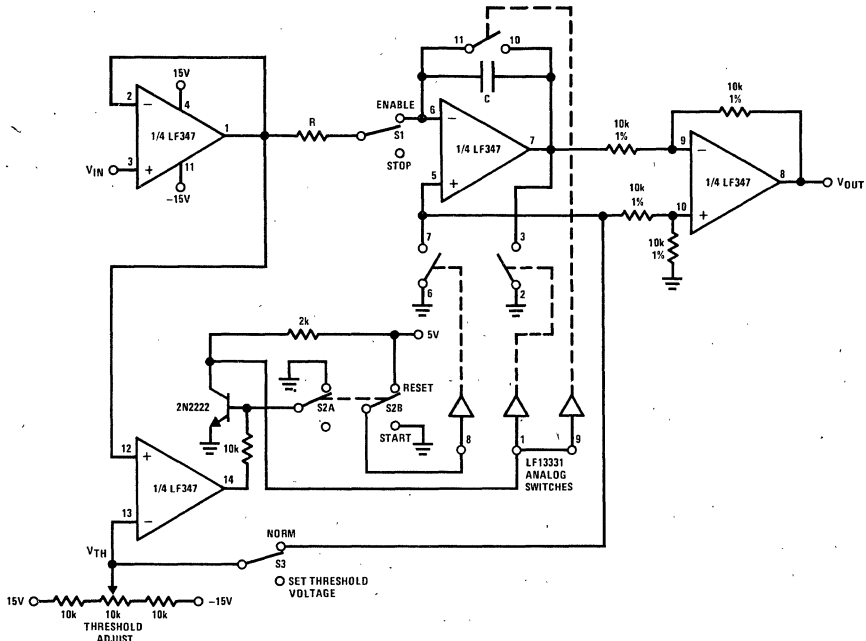


All resistors 1% tolerance

| A1 | A2 | A3 | V _O ATTENUATION |
|----|----|----|----------------------------|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | -1 dB |
| 0 | 1 | 0 | -2 dB |
| 0 | 1 | 1 | -3 dB |
| 1 | 0 | 0 | -4 dB |
| 1 | 0 | 1 | -5 dB |
| 1 | 1 | 0 | -6 dB |
| 1 | 1 | 1 | -7 dB |

- Accuracy of better than 0.4% with standard 1% value resistors
- No offset adjustment necessary
- Expandable to any number of stages
- Very high input impedance

Long Time Integrator with Reset, Hold and Starting Threshold Adjustment



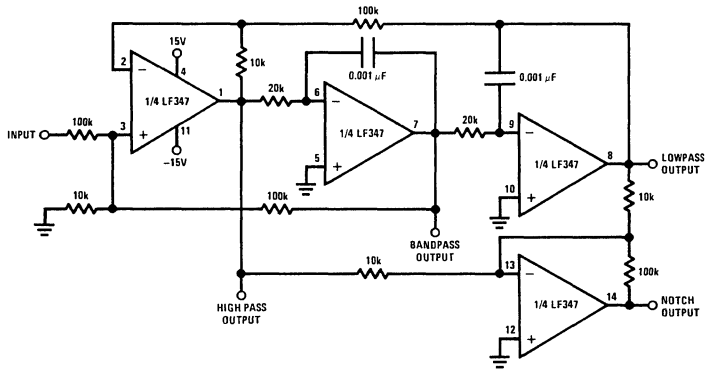
- V_{OUT} starts from zero and is equal to the integral of the input voltage with respect to the threshold voltage:

$$V_{OUT} = \frac{1}{RC} \int_0^t (V_{IN} - V_{TH}) dt$$

- Output starts when V_{IN} ≥ V_{TH}
- Switch S1 permits stopping and holding any output value
- Switch S2 resets system to zero

Typical Applications (Continued)

Universal State Variable Filter



For circuit shown:
 $f_o = 3 \text{ kHz}$, $f_{\text{NOTCH}} = 9.5 \text{ kHz}$
 $Q = 3.4$
 Passband gain:
 Highpass — 0.1
 Bandpass — 1
 Lowpass — 1
 Notch — 10

- $f_o \times Q \leq 200 \text{ kHz}$
- 10V peak sinusoidal output swing without slew limiting to 200 kHz
- See LM348 data sheet for design equations



Operational Amplifiers/Buffers

LF351 Wide Bandwidth JFET Input Operational Amplifier

General Description

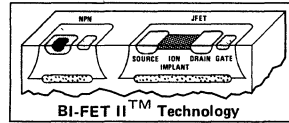
The LF351 is a low cost high speed JFET input operational amplifier with an internally trimmed input offset voltage (BI-FET II™ technology). The device requires a low supply current and yet maintains a large gain bandwidth product and a fast slew rate. In addition, well matched high voltage JFET input devices provide very low input bias and offset currents. The LF351 is pin compatible with the standard LM741 and uses the same offset voltage adjustment circuitry. This feature allows designers to immediately upgrade the overall performance of existing LM741 designs.

The LF351 may be used in applications such as high speed integrators, fast D/A converters, sample-and-hold circuits and many other circuits requiring low input offset voltage, low input bias current, high input impedance, high slew rate and wide bandwidth. The device has low noise and offset voltage drift, but for applica-

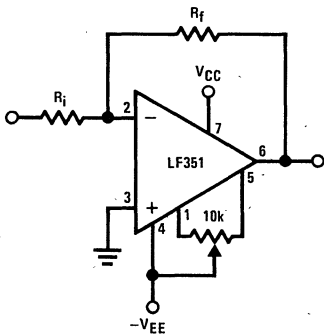
tions where these requirements are critical, the LF356 is recommended. If maximum supply current is important, however, the LF351 is the better choice.

Features

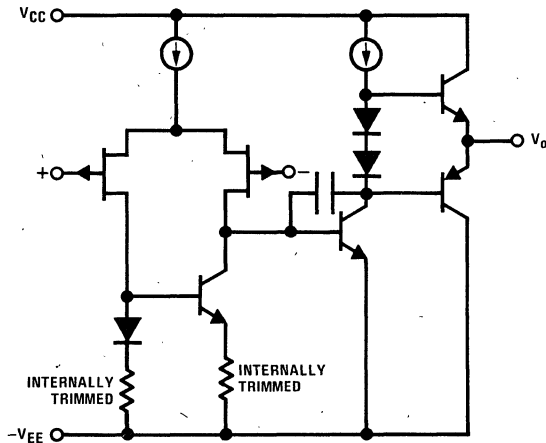
- Internally trimmed offset voltage 2 mV
- Low input bias current 50 pA
- Low input noise voltage 16 nV/√Hz
- Low input noise current 0.01 pA/√Hz
- Wide gain bandwidth 4 MHz
- High slew rate 13 V/μs
- Low supply current 1.8 mA
- High input impedance 1012Ω
- Low total harmonic distortion $A_V = 10$, $R_L = 10k$, $V_O = 20$ Vp-p, BW = 20 Hz–20 kHz <0.02%
- Low 1/f noise corner 50 Hz
- Fast settling time to 0.01% 2 μs



Typical Connection

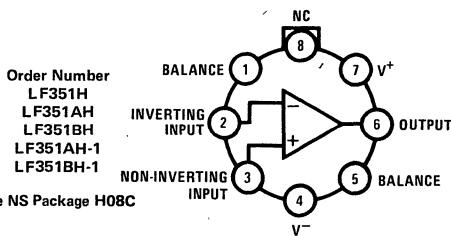


Simplified Schematic



Connection Diagrams (Top Views)

Metal Can Package

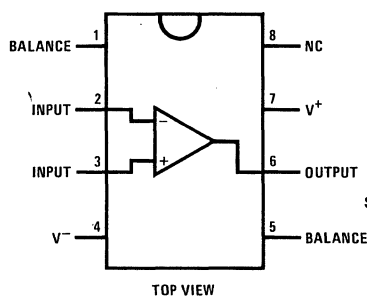


Order Number
LF351H
LF351AH
LF351BH
LF351AH-1
LF351BH-1

See NS Package H08C

Note. Pin 4 connected to case.

Dual-In-Line Package



Order Number
LF351N
LF351AN
LF351BN
LF351AN-1
LF351BN-1

See NS Package N08B

TOP VIEW

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Operating Temperature Range | 0°C to +70°C |
| T _j (MAX) | 115°C |
| Differential Input Voltage | ±30V |
| Input Voltage Range (Note 2) | ±15V |
| Output Short Circuit Duration | Continuous |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | LF351A | | | LF351B | | | LF351 | | | UNITS |
|----------------------|------------------------------------|--|--------|------------|----------|--------|------------|----------|-------|------------|----------|--------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V _{OS} | Input Offset Voltage | R _S = 10 kΩ, T _A = 25°C Over Temperature | | 1 | 2 4 | | 3 | 5 7 | | 5 | 10 13 | mV mV |
| ΔV _{OS} /ΔT | Average TC of Input Offset Voltage | R _S = 10 kΩ LF351A-1, LF351B-1 | | 10 | 20 | | 10 | 30 | | 10 | | μV/°C |
| I _{OS} | Input Offset Current | T _j = 25°C, (Notes 3, 4) T _j ≤ 70°C | | 25 | 100 2 | | 25 | 100 4 | | 25 | 100 4 | pA nA |
| I _B | Input Bias Current | T _j = 25°C, (Notes 3, 4) T _j ≤ 70°C | | 50 | 200 4 | | 50 | 200 8 | | 50 | 200 8 | pA nA |
| R _{IN} | Input Resistance | T _j = 25°C | | 1012 | | | 1012 | | | 1012 | | Ω |
| AVOL | Large Signal Voltage Gain | V _S = ±15V, T _A = 25°C V _O = ±10V, R _L = 2 kΩ Over Temperature | 50 | 100 | | 50 | 100 | | 25 | 100 | | V/mV V/mV |
| V _O | Output Voltage Swing | V _S = ±15V, R _L = 10 kΩ | ±12 | ±13.5 | | ±12 | ±13.5 | | ±12 | ±13.5 | | V |
| V _{CM} | Input Common-Mode Voltage Range | V _S = ±15V | ±11 | +15 -12 | | ±11 | +15 -12 | | ±11 | +15 -12 | | V V |
| CMRR | Common-Mode Rejection Ratio | R _S ≤ 10 kΩ | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| PSRR | Supply Voltage Rejection Ratio | (Note 5) | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| I _S | Supply Current | | | 1.8 | 2.8 | | 1.8 | 2.8 | | 1.8 | 3.4 | mA |

AC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | LF351A | | | LF351B | | | LF351 | | | UNITS |
|----------------|--------------------------------|--|--------|------|-----|--------|------|-----|-------|------|-----|-------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| SR | Slew Rate | V _S = ±15V, T _A = 25°C | 10 | 13 | | | 13 | | | 13 | | V/μs |
| GBW | Gain Bandwidth Product | V _S = ±15V, T _A = 25°C | 3 | 4 | | | 4 | | | 4 | | MHz |
| e _n | Equivalent Input Noise Voltage | T _A = 25°C, R _S = 100Ω, f = 1000 Hz | | 16 | | | 16 | | | 16 | | nV√Hz |
| i _n | Equivalent Input Noise Current | T _j = 25°C, f = 1000 Hz | | 0.01 | | | 0.01 | | | 0.01 | | pA√Hz |

Note 1: For operating at elevated temperature, the device must be derated based on a thermal resistance of 150°C/W junction to ambient or 45°C/W junction to case.

Note 2: Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

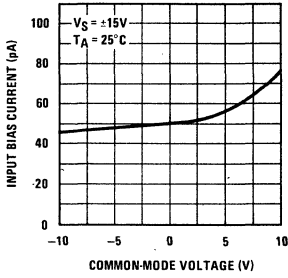
Note 3: These specifications apply for V_S = ±15V and 0°C ≤ T_A ≤ +70°C. V_{OS}, I_B and I_{OS} are measured at V_{CM} = 0.

Note 4: The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_j. Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_D. T_j = T_A + Θ_{J A} P_D where Θ_{J A} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

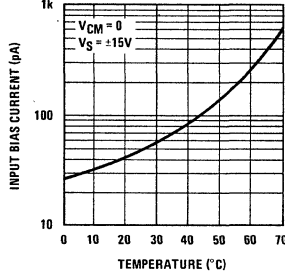
Note 5: Supply voltage rejection ratio is measured for both supply magnitudes increasing or decreasing simultaneously in accordance with common practice.

Typical Performance Characteristics

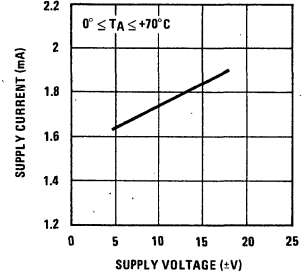
Input Bias Current



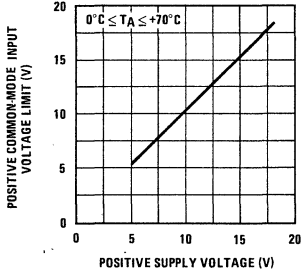
Input Bias Current



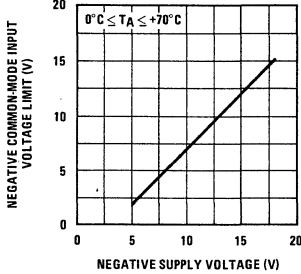
Supply Current



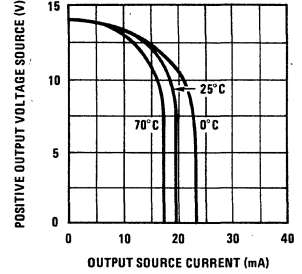
Positive Common-Mode Input Voltage Limit



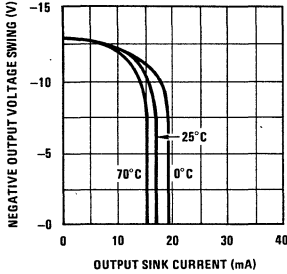
Negative Common-Mode Input Voltage Limit



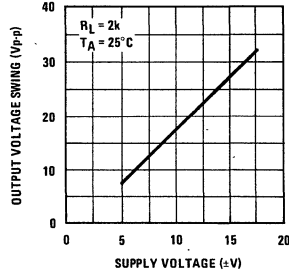
Positive Current Limit



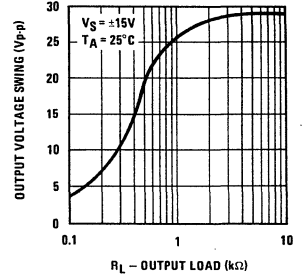
Negative Current Limit



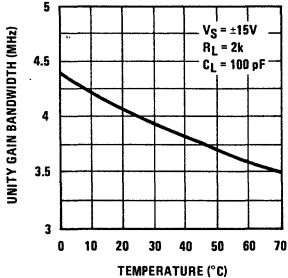
Voltage Swing



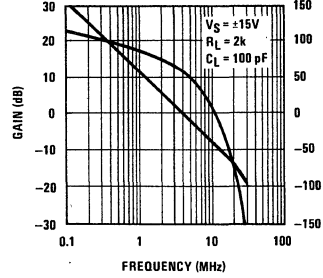
Output Voltage Swing



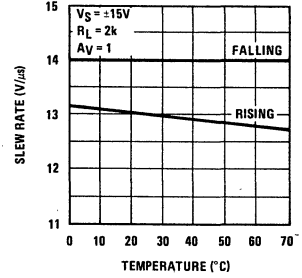
Gain Bandwidth



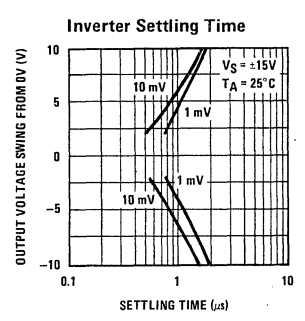
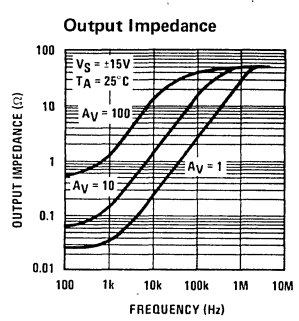
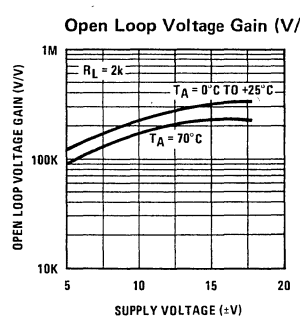
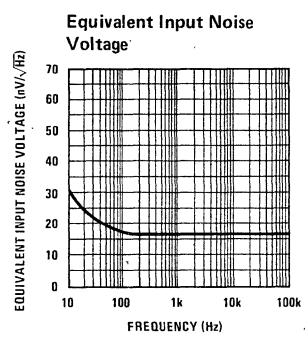
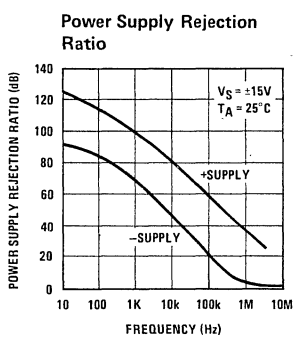
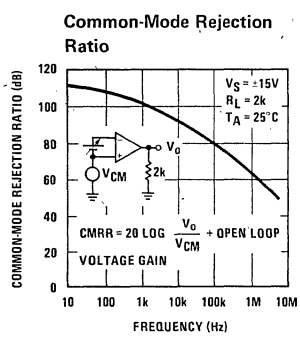
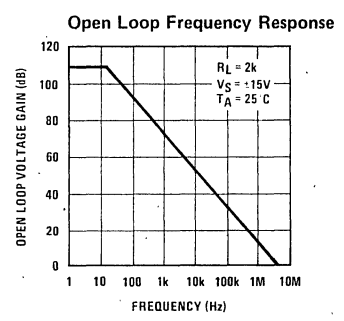
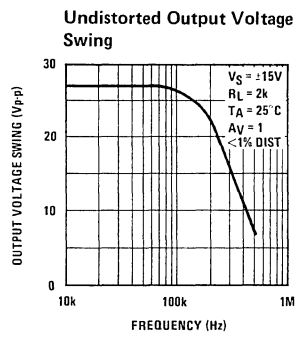
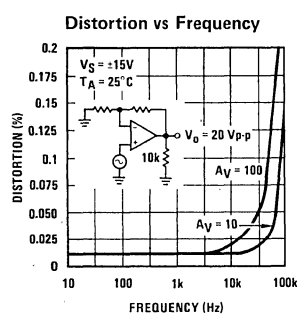
Bode Plot



Slew Rate

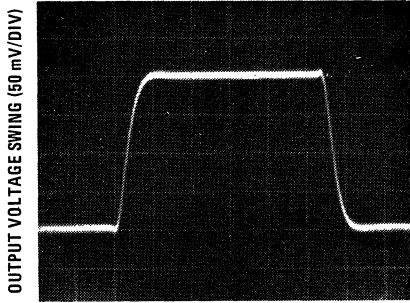


Typical Performance Characteristics (Continued)



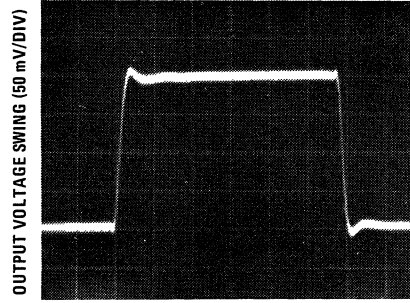
Pulse Response

Small Signal Inverting



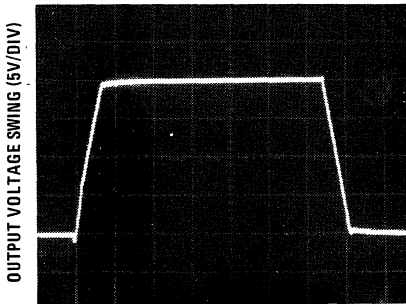
TIME (0.2 μ s/DIV)

Small Signal Non-Inverting



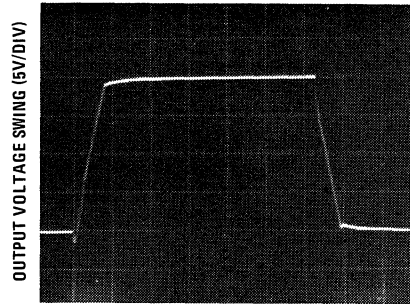
TIME (0.2 μ s/DIV)

Large Signal Inverting



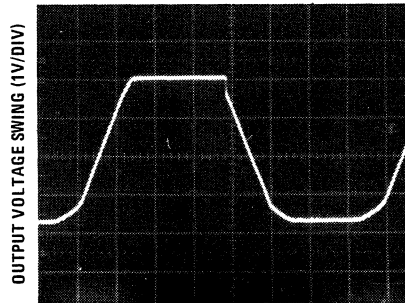
TIME (2 μ s/DIV)

Large Signal Non-Inverting



TIME (2 μ s/DIV)

Current Limit ($R_L = 100\Omega$)



TIME (5 μ s/DIV)

Application Hints

The LF351 is an op amp with an internally trimmed input offset voltage and JFET input devices (BI-FET II™). These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore, large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be

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Exceeding the negative common-mode limit on either input will cause a reversal of the phase to the output and force the amplifier output to the corresponding high or low state. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a

Application Hints (Continued)

high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

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Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed

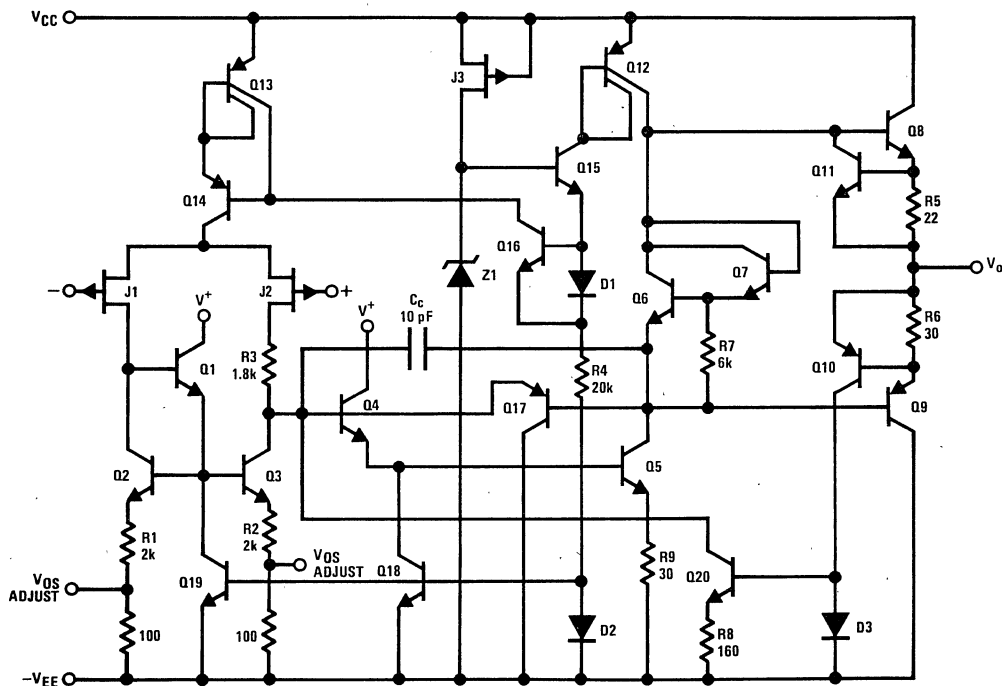
backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Because these amplifiers are JFET rather than MOSFET input op amps they do not require special handling.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize "pick-up" and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

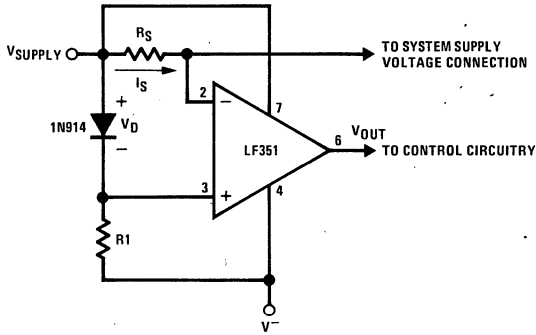
A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to AC ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately 6 times the expected 3 dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

Detailed Schematic



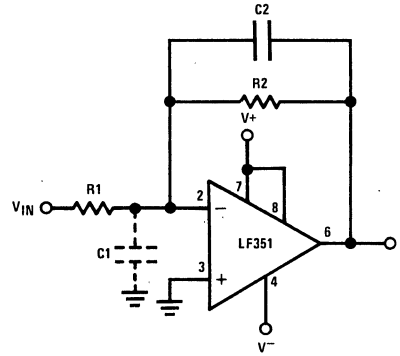
Typical Applications

Supply Current Indicator/Limiter



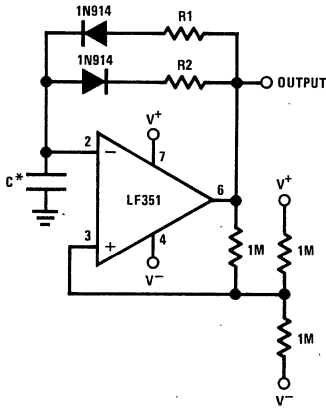
- V_{OUT} switches high when $R_S I_S > V_D$

Hi- Z_{IN} Inverting Amplifier



Parasitic input capacitance $C1 \approx (3 \text{ pF for LF351 plus any additional layout capacitance})$ interacts with feedback elements and creates undesirable high frequency pole. To compensate, add $C2$ such that: $R2C2 \approx R1C1$.

Ultra-Low (or High) Duty Cycle Pulse Generator

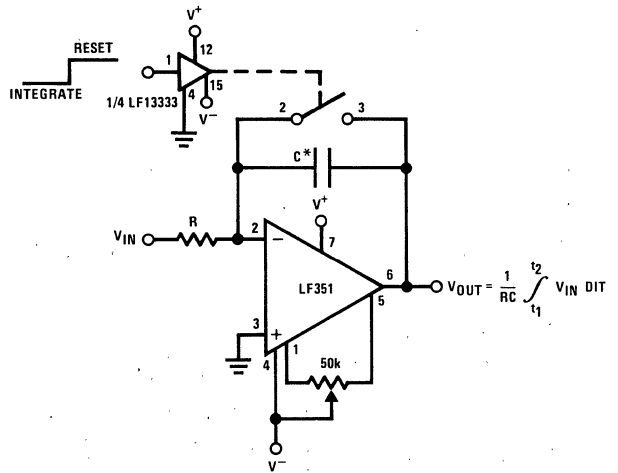


- $t_{OUTPUT \text{ HIGH}} \approx R1C \ln \frac{4.8 - 2V_S}{4.8 - V_S}$
- $t_{OUTPUT \text{ LOW}} \approx R2C \ln \frac{2V_S - 7.8}{V_S - 7.8}$

where $V_S = V^+ + |V^-|$

* low leakage capacitor

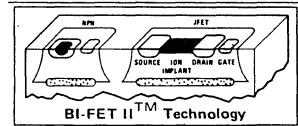
Long Time Integrator



* Low leakage capacitor

- 50k pot used for less sensitive V_{OS} adjust

LF353 Wide Bandwidth Dual JFET Input Operational Amplifier



General Description

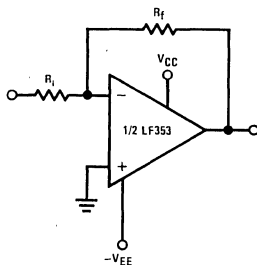
These devices are low cost, high speed, dual JFET input operational amplifiers with an internally trimmed input offset voltage (BI-FET II™ technology). They require low supply current yet maintain a large gain bandwidth product and fast slew rate. In addition, well matched high voltage JFET input devices provide very low input bias and offset currents. The LF353 is pin compatible with the standard LM1558 allowing designers to immediately upgrade the overall performance of existing LM1558 and LM358 designs.

These amplifiers may be used in applications such as high speed integrators, fast D/A converters, sample and hold circuits and many other circuits requiring low input offset voltage, low input bias current, high input impedance, high slew rate and wide bandwidth. The devices also exhibit low noise and offset voltage drift.

Features

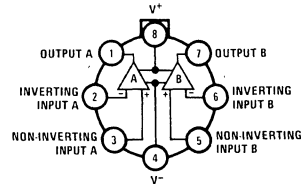
- Internally trimmed offset voltage 2 mV
- Low input bias current 50 pA
- Low input noise voltage 16 nV/√Hz
- Low input noise current 0.01 pA/√Hz
- Wide gain bandwidth 4 MHz
- High slew rate 13 V/μs
- Low supply current 3.6 mA
- High input impedance 10¹²Ω
- Low total harmonic distortion $A_V = 10$, $R_L = 10k$, $V_O = 20$ Vp-p, $BW = 20$ Hz–20 kHz < 0.02%
- Low 1/f noise corner 50 Hz
- Fast settling time to 0.01% 2 μs

Typical Connection



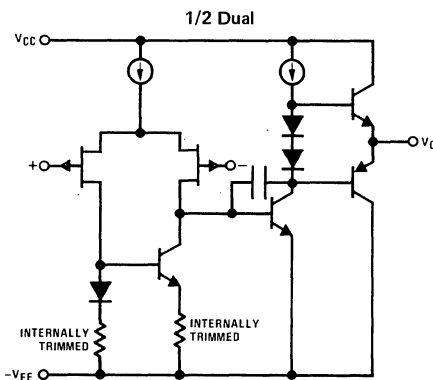
Connection Diagrams

LF353H Metal Can Package (Top View)

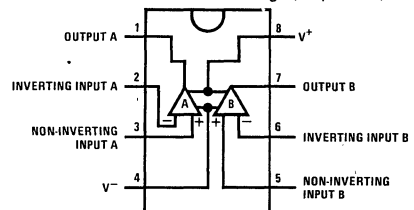


Order Number LF353AH or LF353BH
See NS Package H08C

Simplified Schematic



LF353N Dual-In-Line Package (Top View)



Order Number LF353AN, LF353BN or LF353N
See NS Package N08A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Operating Temperature Range | 0°C to +70°C |
| T _J (MAX) | 115°C |
| Differential Input Voltage | ±30V |
| Input Voltage Range (Note 2) | ±15V |
| Output Short Circuit Duration (Note 3) | Continuous |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (Note 4)

| SYMBOL | PARAMETER | CONDITIONS | LF353A | | | LF353B | | | LF353 | | | UNITS |
|----------------------|------------------------------------|--|--------|------------------|----------|--------|------------------|----------|-------|------------------|----------|--------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| V _{OS} | Input Offset Voltage | R _S = 10 kΩ, T _A = 25°C Over Temperature | | 1 | 2 4 | | 3 | 5 7 | | 5 | 10 13 | mV mV |
| ΔV _{OS} /ΔT | Average TC of Input Offset Voltage | R _S = 10 kΩ | | 10 | 20 | | 10 | 30 | | 10 | | μV/°C |
| I _{OS} | Input Offset Current | T _J = 25°C, (Notes 4, 5) T _J ≤ 70°C | | 25 | 100 2 | | 25 | 100 4 | | 25 | 100 4 | pA nA |
| I _B | Input Bias Current | T _J = 25°C, (Notes 4, 5) T _J ≤ 70°C | | 50 | 4 | | 50 | 200 8 | | 50 | 200 8 | pA nA |
| R _{IN} | Input Resistance | T _J = 25°C | | 10 ¹² | | | 10 ¹² | | | 10 ¹² | | Ω |
| A _{VOL} | Large Signal Voltage Gain | V _S = ±15V, T _A = 25°C V _O = ±10V, R _L = 2 kΩ Over Temperature | 50 | 100 | | 50 | 100 | | 25 | 100 | | V/mV V/mV |
| V _O | Output Voltage Swing | V _S = ±15V, R _L = 10 kΩ | ±12 | ±13.5 | | ±12 | ±13.5 | | ±12 | ±13.5 | | V |
| V _{CM} | Input Common-Mode Voltage Range | V _S = ±15V | ±11 | +15 -12 | | ±11 | +15 -12 | | ±11 | +15 -12 | | V V |
| CMRR | Common-Mode Rejection Ratio | R _S ≤ 10 kΩ | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| PSRR | Supply Voltage Rejection Ratio | (Note 6) | 80 | 100 | | 80 | 100 | | 70 | 100 | | dB |
| I _S | Supply Current | | | 3.6 | 5.6 | | 3.6 | 5.6 | | 3.6 | 6.5 | mA |

AC Electrical Characteristics (Note 4)

| SYMBOL | PARAMETER | CONDITIONS | LF353A | | | LF353B | | | LF353 | | | UNITS |
|----------------|---------------------------------|--|--------|------|-----|--------|------|-----|-------|------|-----|--------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| | Amplifier to Amplifier Coupling | T _A = 25°C, f = 1 Hz– 20 kHz (Input Referred) | | -120 | | | -120 | | | -120 | | dB |
| SR | Slew Rate | V _S = ±15V, T _A = 25°C | 10 | 13 | | | 13 | | | 13 | | V/μs |
| GBW | Gain-Bandwidth Product | V _S = ±15V, T _A = 25°C | 3 | 4 | | | 4 | | | 4 | | MHz |
| e _n | Equivalent Input Noise Voltage | T _A = 25°C, R _S = 100Ω, f = 1000 Hz | | 16 | | | 16 | | | 16 | | nV/√Hz |
| i _n | Equivalent Input Noise Current | T _J = 25°C, f = 1000 Hz | | 0.01 | | | 0.01 | | | 0.01 | | pA/√Hz |

Note 1: For operating at elevated temperature, the device must be derated based on a thermal resistance of 160°C/W junction to ambient for the N package, and 150°C/W junction to ambient for the H package.

Note 2: Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

Note 3: The power dissipation limit, however, cannot be exceeded.

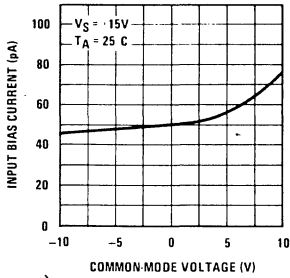
Note 4: These specifications apply for V_S = ±15V and 0°C ≤ T_A ≤ +70°C. V_{OS}, I_B and I_{OS} are measured at V_{CM} = 0.

Note 5: The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_J. Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_D. T_J = T_A + Θ_{JA} P_D where Θ_{JA} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

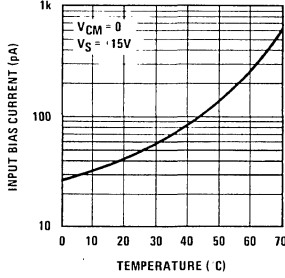
Note 6: Supply voltage rejection ratio is measured for both supply magnitudes increasing or decreasing simultaneously in accordance with common practice.

Typical Performance Characteristics

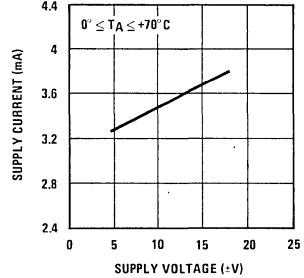
Input Bias Current



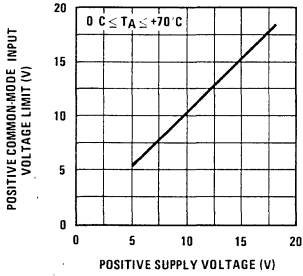
Input Bias Current



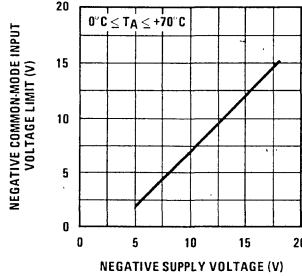
Supply Current



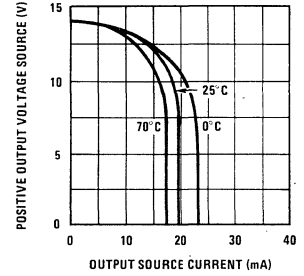
Positive Common-Mode Input Voltage Limit



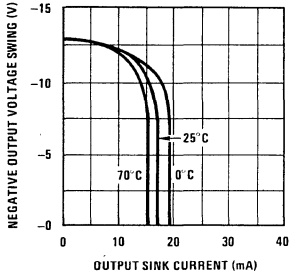
Negative Common-Mode Input Voltage Limit



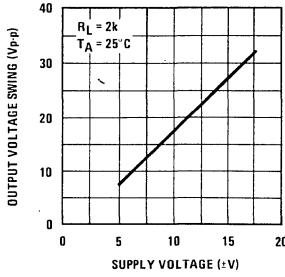
Positive Current Limit



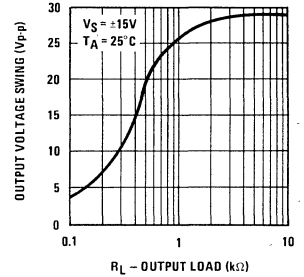
Negative Current Limit



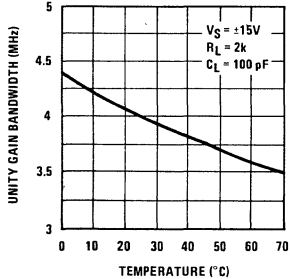
Voltage Swing



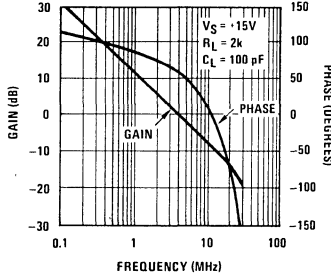
Output Voltage Swing



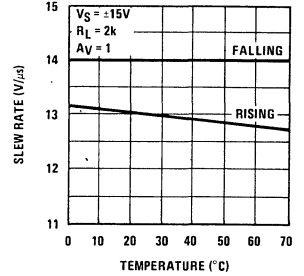
Gain Bandwidth



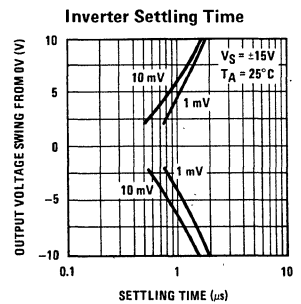
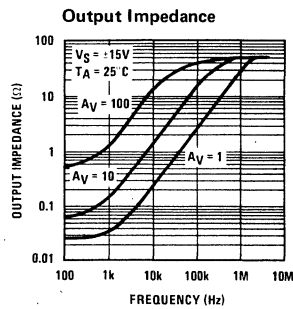
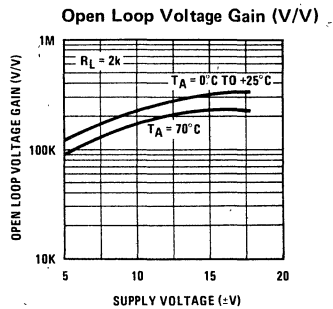
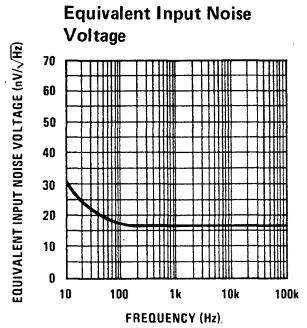
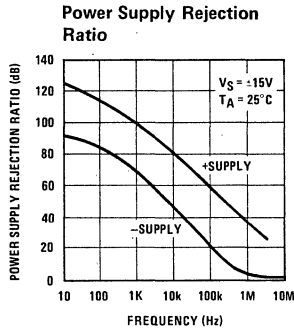
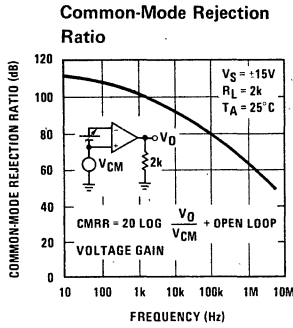
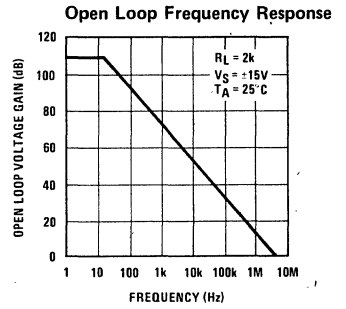
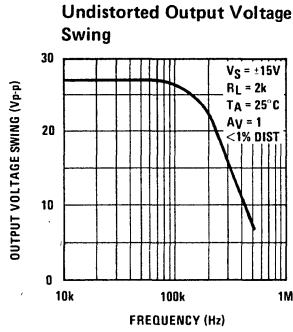
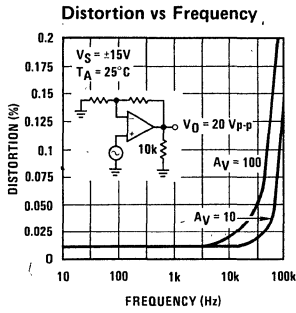
Bode Plot



Slew Rate

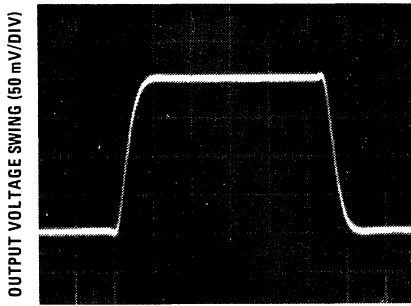


Typical Performance Characteristics (Continued)



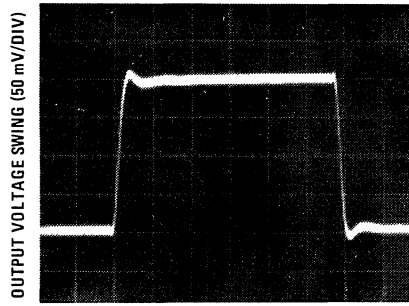
Pulse Response

Small Signal Inverting



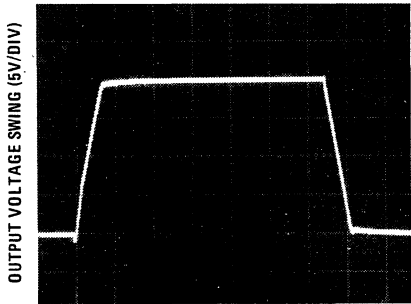
TIME (0.2 μ s/DIV)

Small Signal Non-Inverting



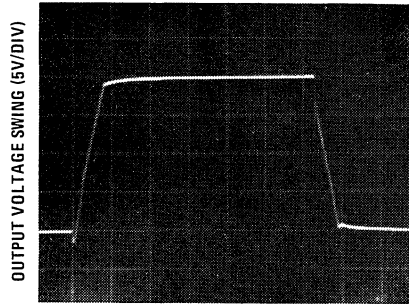
TIME (0.2 μ s/DIV)

Large Signal Inverting



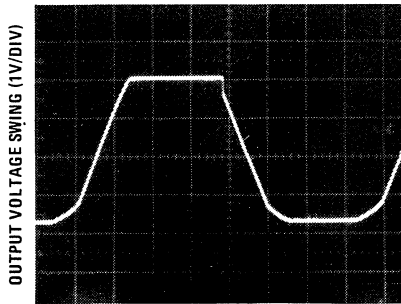
TIME (2 μ s/DIV)

Large Signal Non-Inverting



TIME (2 μ s/DIV)

Current Limit ($R_L = 100\Omega$)



TIME (5 μ s/DIV)

3

Application Hints

These devices are op amps with an internally trimmed input offset voltage and JFET input devices (BI-FET II). These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore, large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be

allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

Exceeding the negative common-mode limit on either input will cause a reversal of the phase to the output and force the amplifier output to the corresponding high or low state. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a

Application Hints (Continued)

high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

Exceeding the positive common-mode limit on a single input will not change the phase of the output; however, if both inputs exceed the limit, the output of the amplifier will be forced to a high state.

The amplifiers will operate with a common-mode input voltage equal to the positive supply; however, the gain bandwidth and slew rate may be decreased in this condition. When the negative common-mode voltage swings to within 3V of the negative supply, an increase in input offset voltage may occur.

Each amplifier is individually biased by a zener reference which allows normal circuit operation on $\pm 4V$ power supplies. Supply voltages less than these may result in lower gain bandwidth and slew rate.

The amplifiers will drive a 2 k Ω load resistance to $\pm 10V$ over the full temperature range of 0°C to +70°C. If the amplifier is forced to drive heavier load currents, however, an increase in input offset voltage may occur on the negative voltage swing and finally reach an active current limit on both positive and negative swings.

Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed

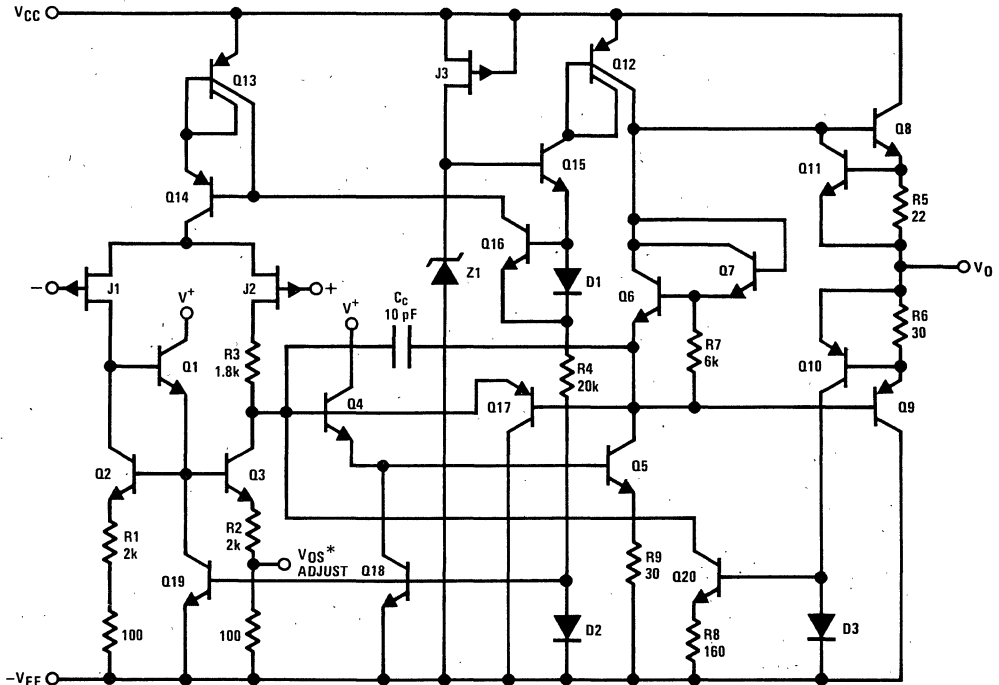
backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Because these amplifiers are JFET rather than MOSFET input op amps they do not require special handling.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize "pick-up" and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

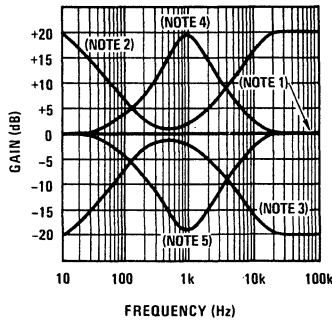
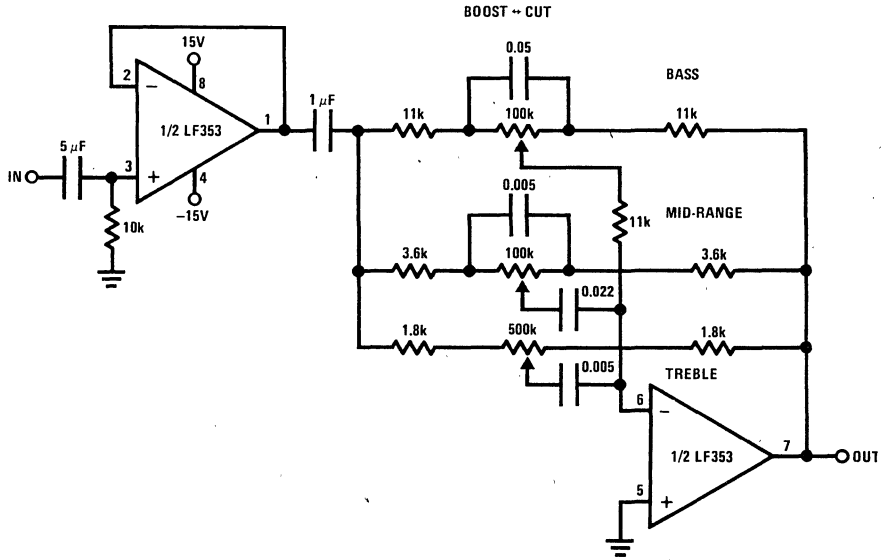
A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to AC ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately 6 times the expected 3 dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

Detailed Schematic



Typical Applications

Three-Band Active Tone Control

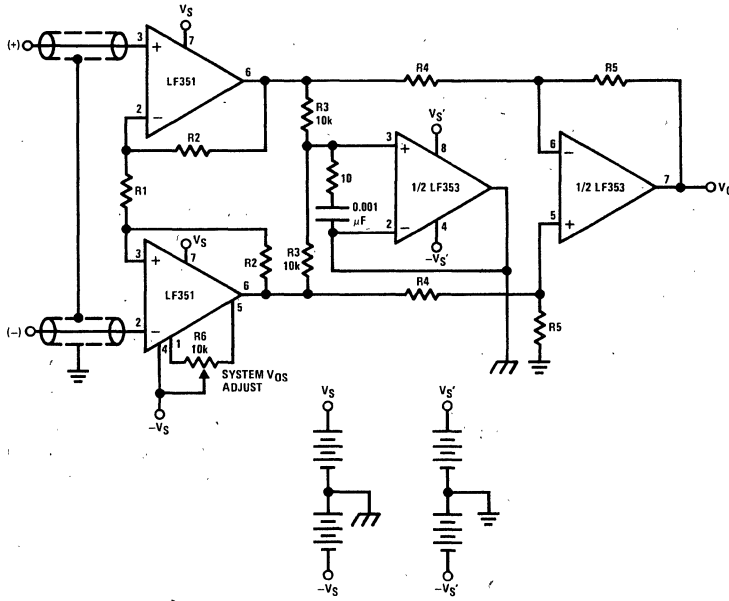


- Note 1: All controls flat.
- Note 2: Bass and treble boost, mid flat.
- Note 3: Bass and treble cut, mid flat.
- Note 4: Mid boost, bass and treble flat.
- Note 5: Mid cut, bass and treble flat.

- All potentiometers are linear taper
- Use the LF347 Quad for stereo applications

Typical Applications (Continued)

Improved CMRR Instrumentation Amplifier



SEPARATE

$$A_V = \left(\frac{2R_2}{R_1} + 1 \right) \frac{R_5}{R_4}$$

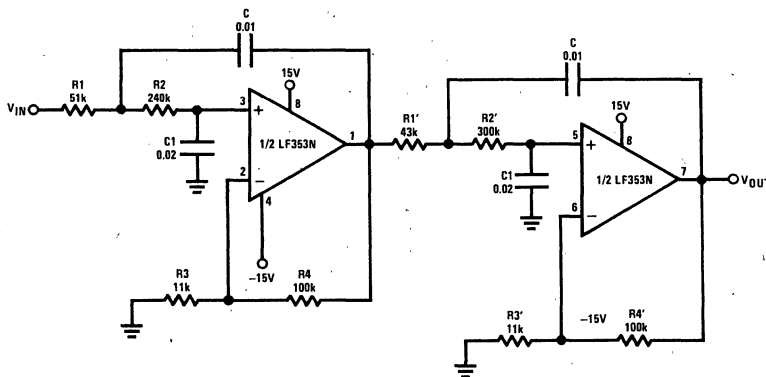
⏏ and ⏏ are separate isolated grounds

Matching of R2's, R4's and R5's control CMRR

With $A_{VT} = 1400$, resistor matching = 0.01%: CMRR = 136 dB

- Very high input impedance
- Super high CMRR

Fourth Order Low Pass Butterworth Filter

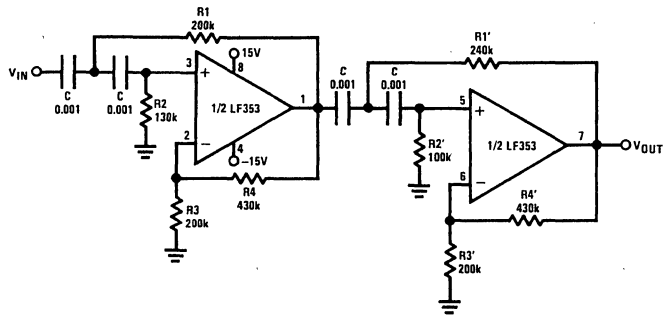


$$\bullet \text{ Corner frequency } (f_c) = \sqrt{\frac{1}{R_1 R_2 C C_1}} \cdot \frac{1}{2\pi} = \sqrt{\frac{1}{R_1' R_2' C C_1}} \cdot \frac{1}{2\pi}$$

- Passband gain (H_0) = $(1 + R_4/R_3) (1 + R_4'/R_3')$
- First stage Q = 1.31
- Second stage Q = 0.541
- Circuit shown uses nearest 5% tolerance resistor values for a filter with a corner frequency of 100 Hz and a passband gain of 100
- Offset nulling necessary for accurate DC performance

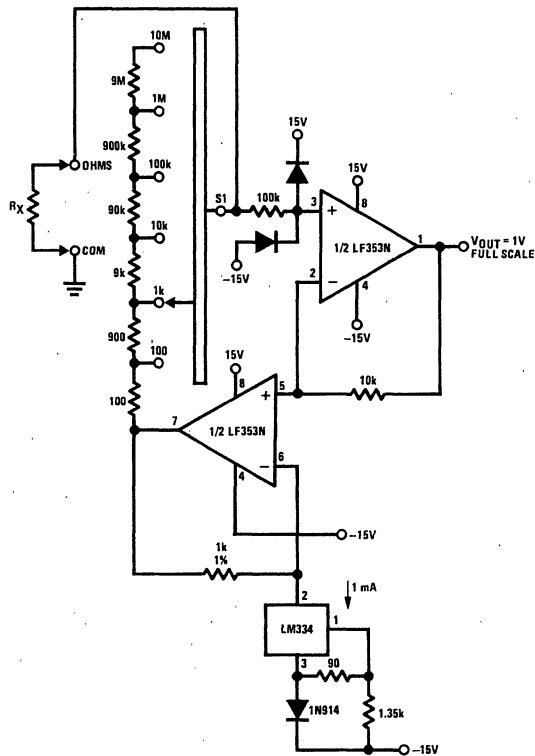
Typical Applications (Continued)

Fourth Order High Pass Butterworth Filter



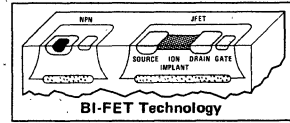
- Corner frequency (f_c) = $\sqrt{\frac{1}{R1R2C^2}} \cdot \frac{1}{2\pi} = \sqrt{\frac{1}{R1'R2'C^2}} \cdot \frac{1}{2\pi}$
- Passband gain (H_0) = $(1 + R4/R3)(1 + R4'/R3')$
- First stage $Q = 1.31$
- Second stage $Q = 0.541$
- Circuit shown uses closest 5% tolerance resistor values for a filter with a corner frequency of 1 kHz and a passband gain of 10

Ohms to Volts Converter



$$V_O = \frac{1V}{R_{LADDER}} \times R_X$$

Where R_{LADDER} is the resistance from switch S1 pole to pin 10 of the LF354.



LF13741 Monolithic JFET Input Operational Amplifier

General Description

The LF13741 is a 741 with BI-FET input followers on the same die. Familiar operating characteristics — those of a 741 — with the added advantage of low input bias current make the LF13741 easy to use. Monolithic fabrication makes this “drop-in-replacement” operational amplifier very economical.

Applications in which the LF13741 excels are those which require low bias current, moderate speed and low cost. A few examples include high impedance transducer amplifiers, photocell amplifiers, buffers for high impedance, slow to moderate speed sources and buffers in sample-and-hold type systems where leakage from the hold capacitor node must be kept to a minimum.

Systems designers can take full advantage of their knowledge of the 741 when designing with the LF13741 to achieve extremely rapid “design times.” The LF13741 can also be used in existing sockets to make the “error budget” for input bias and/or offset currents negligible and in many cases eliminate trimming. For higher speed and lower noise use the LF155, LF156, LF157 series of BI-FET operational amplifiers.

Features

- Low input bias current 50 pA
- Input common-mode range to positive supply voltage
- Low input noise current 0.01 pA/√Hz
- High input impedance 5 x 10¹¹Ω
- Familiar operating characteristics

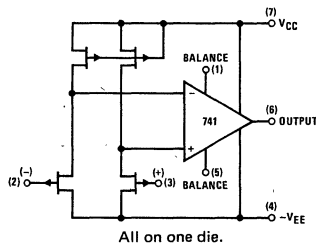
Advantages

- FET inputs — 741 operating characteristics
- Low cost
- Ease of use
- Standard supplies
- Standard pin outs
- Non-rectifying input for RF environment
- Rapid “design time”

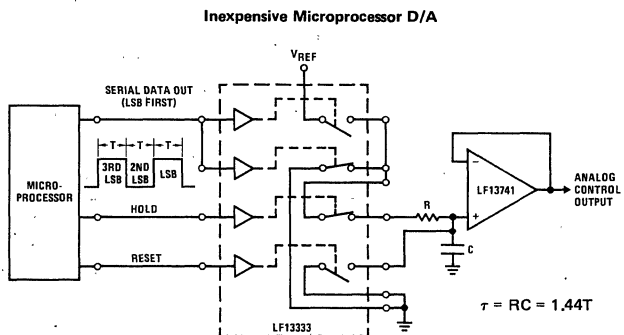
Applications

- Smoke detectors
- I to V converters
- High impedance buffers
- Low drift sample and hold circuits
- High input impedance, slow comparators
- Long time timers
- Low drift peak detectors
- Supply current monitors
- Low error budget systems

Simplified Schematic



Typical Applications



Absolute Maximum Ratings

| | | | |
|-----------------------------|--------------|--|-----------------|
| Supply Voltage | ±18V | Input Voltage Range (Note 2) | ±16V |
| Power Dissipation (Note 1) | 500 mW | Output Short Circuit Duration | Continuous |
| Operating Temperature Range | 0°C to +70°C | Storage Temperature Range | -65°C to +150°C |
| T _j (MAX) | 100°C | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Differential Input Voltage | ±30V | | |

DC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------------|------------------------------------|--|-----|----------------------|----------|--------------|
| V _{OS} | Input Offset Voltage | R _S = 10 kΩ, T _A = 25°C Over Temperature | | 5 | 15 20 | mV mV |
| ΔV _{OS} /ΔT | Average TC of Input Offset Voltage | R _S = 10 kΩ | | 10 | | μV/°C |
| I _{OS} | Input Offset Current | T _j = 25°C, (Notes 3, 4) T _j ≤ 70°C | | 10 | 50 2 | pA nA |
| I _B | Input Bias Current | T _j = 25°C, (Notes 3, 4) T _j ≤ 70°C | | 50 1.6 | 200 8 | pA nA |
| R _{IN} | Input Resistance | T _j = 25°C | | 5 x 10 ¹¹ | | Ω |
| A _{VOL} | Large Signal Voltage Gain | V _S = ±15V, T _A = 25°C V _O = ±10V, R _L = 2 kΩ Over Temperature | 25 | 100 | | V/mV V/mV |
| V _O | Output Voltage Swing | V _S = ±15V, R _L = 10 kΩ | ±12 | ±13 | | V |
| V _{CM} | Input Common-Mode Voltage Range | V _S = ±15V | ±11 | +15.1 -12 | | V V |
| CMRR | Common-Mode Rejection Ratio | R _S ≤ 10 kΩ | 70 | 90 | | dB |
| PSRR | Supply Voltage Rejection Ratio | (Note 5) | 77 | 96 | | dB |
| I _S | Supply Current | | | 2 | 4 | mA |

AC Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------|--------------------------------|--|-----|--------------|-----|----------------|
| SR | Slew Rate | V _S = ±15V, T _A = 25°C | | 0.5 | | V/μs |
| GBW | Gain-Bandwidth Product | V _S = ±15V, T _A = 25°C | | 1.0 | | MHz |
| e _n | Equivalent Input Noise Voltage | T _A = 25°C, R _S = 100 Ω f = 100 Hz f = 1000 Hz | | 50 37 | | nV√Hz nV√Hz |
| i _n | Equivalent Input Noise Current | T _j = 25°C f = 100 Hz f = 1000 Hz | | 0.01 0.01 | | pA√Hz pA√Hz |

Note 1: For operating at elevated temperature, the device must be derated based on a thermal resistance of 150°C/W junction to ambient or 45°C/W junction to case.

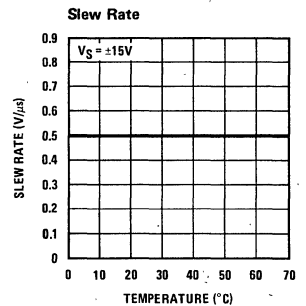
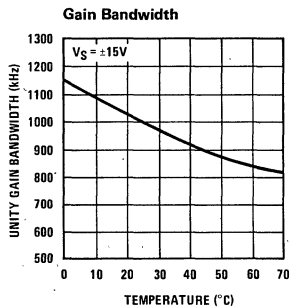
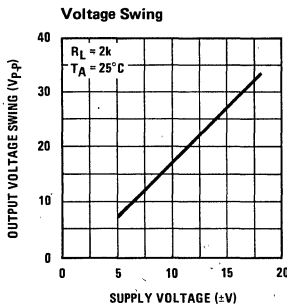
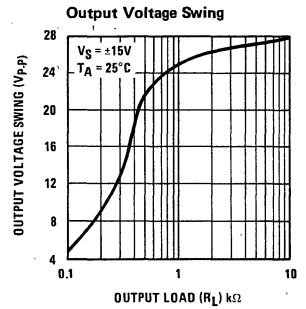
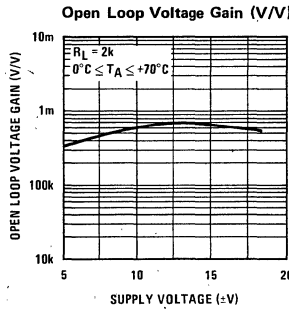
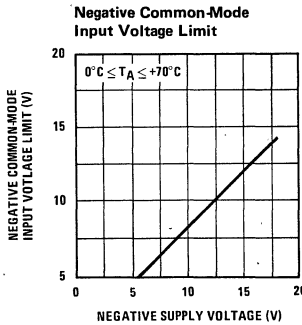
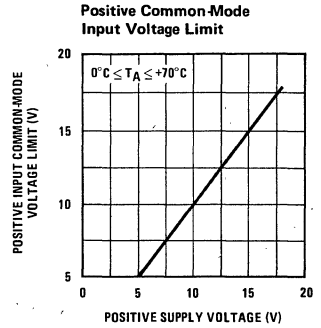
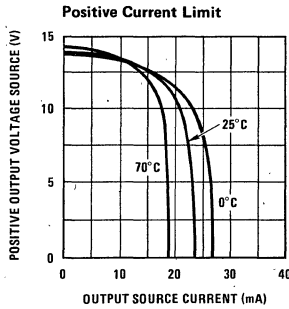
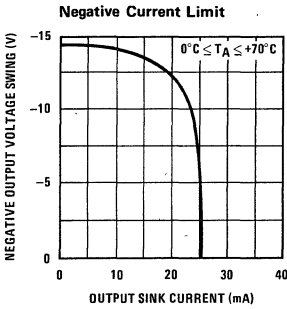
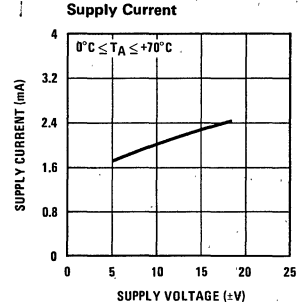
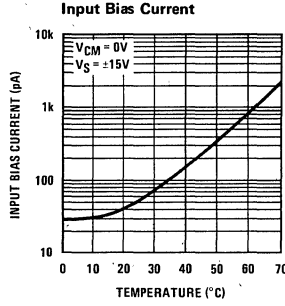
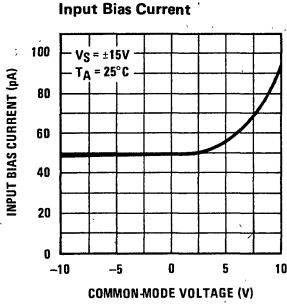
Note 2: Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

Note 3: These specifications apply for V_S = ±15V and 0°C ≤ T_A ≤ +70°C. V_{OS}, I_B, and I_{OS} are measured at V_{CM} = 0.

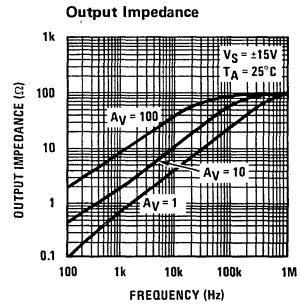
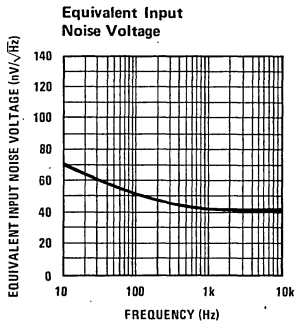
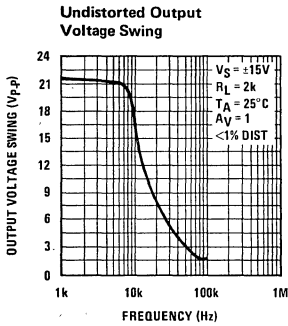
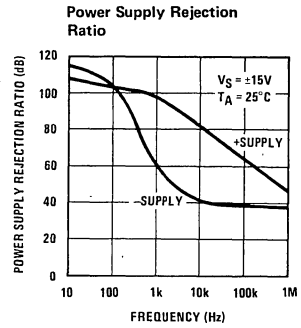
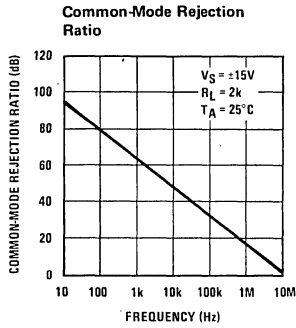
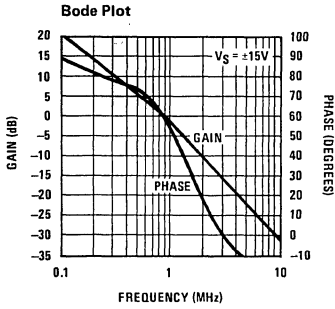
Note 4: The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_j. Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_D. T_j = T_A + θ_{JA} P_D where θ_{JA} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

Note 5: Supply Voltage Rejection Ratio is measured for both supply magnitudes increasing or decreasing simultaneously in accordance with common practice.

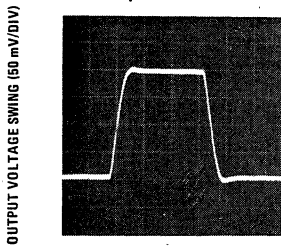
Typical Performance Characteristics



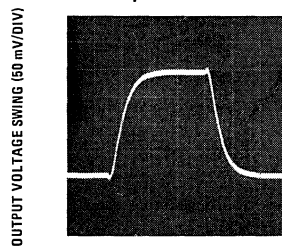
Typical Performance Characteristics (Continued)



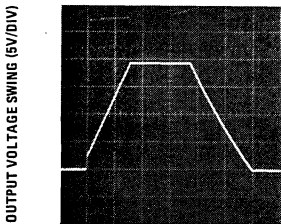
Small Signal Non-Inverting Pulse Response



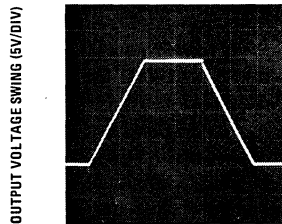
Small Signal Inverting Pulse Response



Large Signal Non-Inverting Pulse Response



Large Signal Inverting Pulse Response



Application Hints

GENERAL CHARACTERISTICS

The LF13741 makes the job of converting from a bipolar to a FET input op amp easy. As a systems designer you are probably very familiar with the operating characteristics of a 741 op amp. In fact, many of you have used 741s with FET input followers—that's just what the LF13741 is, but it's all on a single die.

When you need a low cost, reliable, well known op amp with low input currents and moderate speed, use an LF13741.

DIFFERENTIAL INPUTS

You don't have to use clamps across the inputs for differential input voltages of less than 40V. The input JFET's of the LF13741, in addition to being well matched, have large reverse breakdown voltages from gate to source and drain.

POSITIVE INPUT COMMON-MODE VOLTAGE LIMIT

With the LF13741 (unlike the normal 741) you can take both inputs above the positive supply voltage by more than 0.1V before the amplifier ceases to function. This feature enables you to use the LF13741 to monitor and/or limit the current from the same supply used to power it (see typical applications).

If you exceed the positive common-mode voltage limit on only one input the output phase will remain correct. When you exceed the limit on both inputs, the output phase is unpredictable.

NEGATIVE INPUT COMMON-MODE VOLTAGE LIMIT

There are two negative input voltage ranges of interest:

1. The range between the negative common-mode voltage limit and the negative supply voltage.
2. Voltages which are more negative than the negative supply voltage.

If you take only one of the inputs of the LF13741 into the first range, the output phase will remain correct. When you take both inputs into this range the output will go toward the positive supply voltage.

If you force either or both of the inputs into the second range, an internal diode will be turned "ON." Unless you externally limit the diode current to about 1 mA, the device will be destroyed. In either case, limited or unlimited input current, you cannot predict the output.

HANDLING

You do not have to take any special precautions in handling the LF13741. It has JFET, as opposed to fragile MOSFET, inputs.

APPLYING POWER

You should never: reverse the power supplies to the LF13741; plug a part in backwards in a powered socket

or board; make the negative supply voltage more positive than an input voltage.

Any one of these supply conditions will forward bias an internal diode. If you have not externally limited the resulting current, the device will be destroyed.

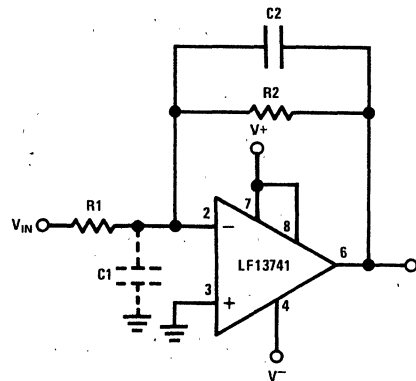
LAYOUT

To ensure stability of response you should take care with lead dress, component placement and power supply decoupling. For example, the body of feedback resistors (from output to input pins) should be placed close to the inverting input pin. Noise "pickup" and capacitance to ground from the input pin will be minimized—effects which are usually desirable.

Because of the very low input bias currents of the LF13741, special care should be taken in printed circuit board layouts to prevent unnecessary leakage from the input nodes, (see typical applications).

FEEDBACK POLE

You create a feedback pole when you place resistive feedback around an amplifier. The parallel resistance and capacitance from the input of the device (usually the inverting input) to ac ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and there is negligible effect on stability margin. However, if the feedback pole is less than approximately six times the expected 3 dB frequency, (a distinct possibility when using FET op amps) you should place a lead capacitor from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant (Figure 1).

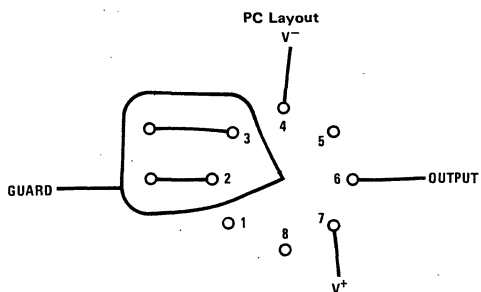
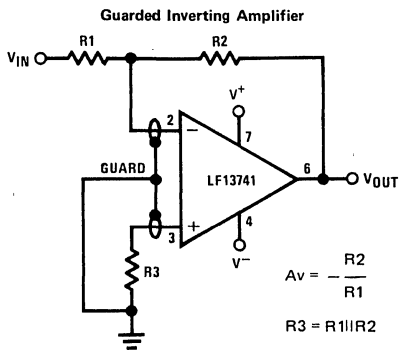
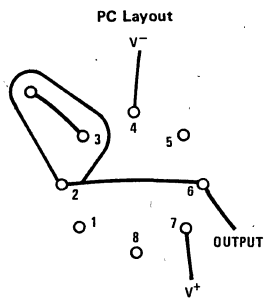
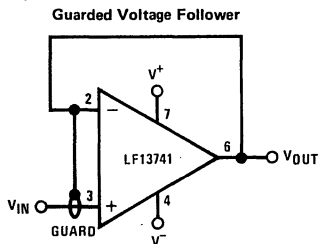


Parasitic input capacitance $C1 \cong (3 \text{ pF for LF13741 plus any additional layout capacitance})$ interacts with feedback elements and creates undesirable high frequency pole. To compensate, add $C2$ such that: $R2C2 \cong R1C1$.

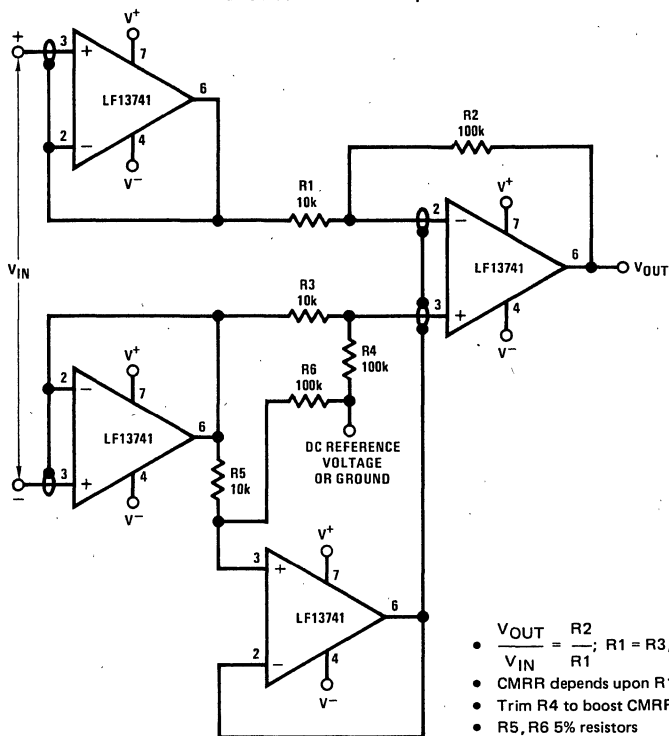
FIGURE 1

Typical Applications (Continued)

Circuits Using Guard Rings to Prevent Leakage Currents Between Inputs and V⁻

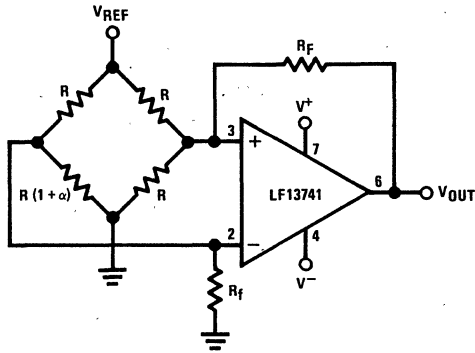


Guarded Instrumentation Amplifier



Typical Applications (Continued)

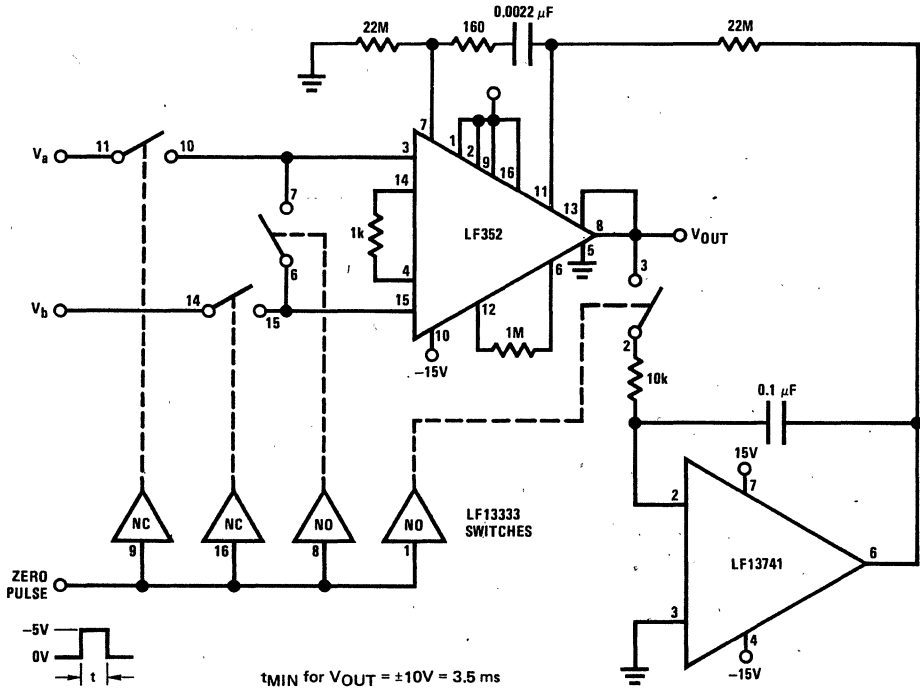
Bridge Amplifier



For $R_f \gg R$

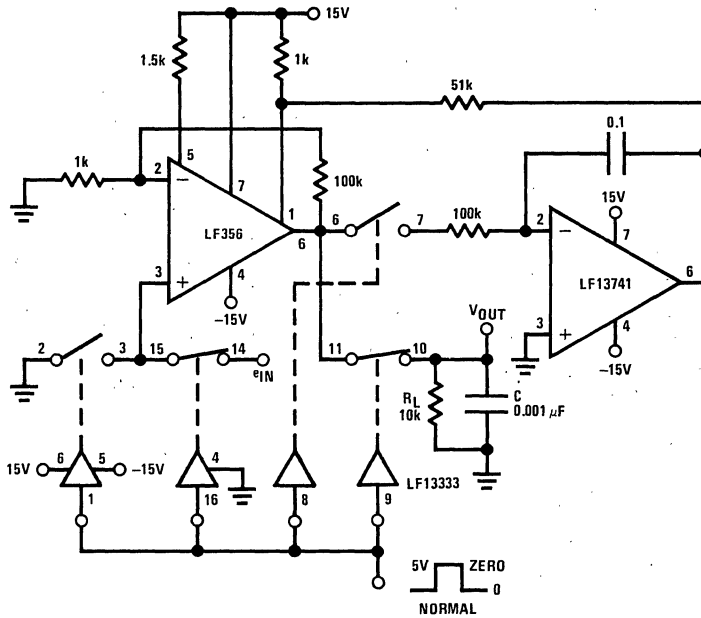
$$V_O = \frac{V_{REF}}{2} \left(\frac{R_f}{R} \right) \left(\frac{\alpha}{1 + \alpha} \right)$$

Automatic V_{ios} Adjust ($R_G/R_G \geq 100$) For Instrumentation Amplifier



Typical Applications (Continued)

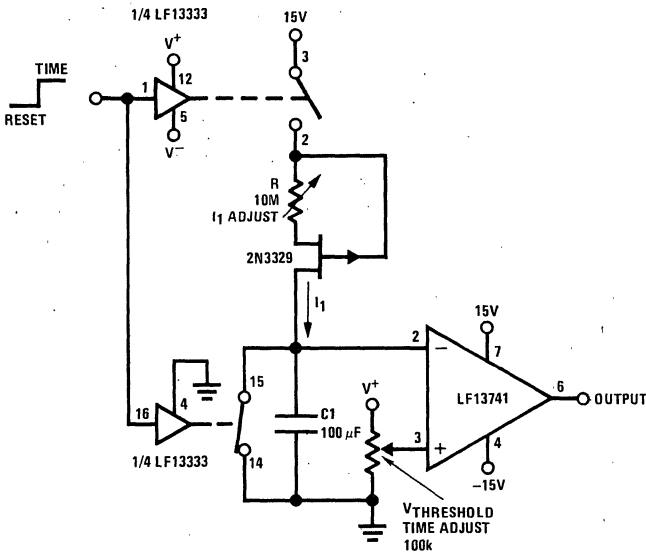
Auto Zero Circuit for LF356



- With the output having a 10k load resistor minimum pulse width to zero $\approx 800 \mu s$
- The capacitor on the output reduces the output switch glitch

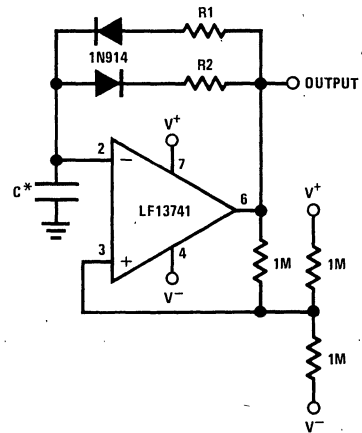
3

Long Time Timer



- $Time = \frac{C1}{I1} V_{THRESHOLD}$
- Output goes high on time out
- Reverse op amp inputs for output low on time out
- C1 low leakage capacitor

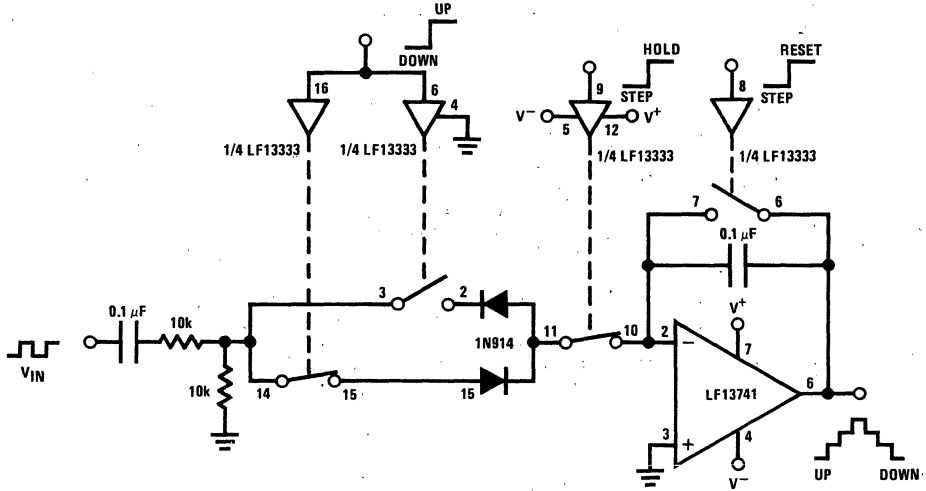
Ultra-Low (Or High) Duty Cycle Pulse Generator



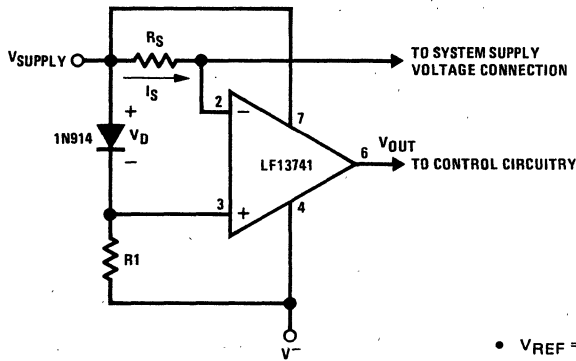
- $t_{OUTPUT HIGH} \approx R1C \ln \frac{4.8 - 2V_S}{4.8 - V_S}$
 - $t_{OUTPUT LOW} \approx R2C \ln \frac{2V_S - 7.8}{V_S - 7.8}$
- where $V_S = V^+ + |V^-|$
 *low leakage capacitor

Typical Applications (Continued)

Up/Down Staircase Generator/Step and Hold

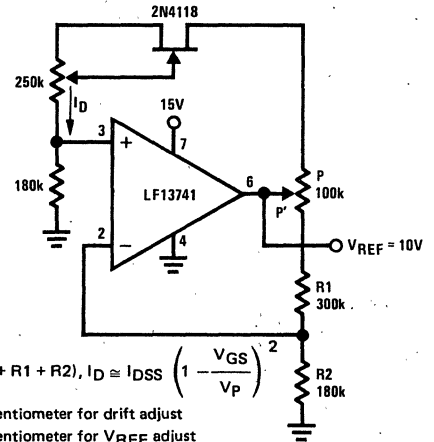


Supply Current Indicator/Limiter



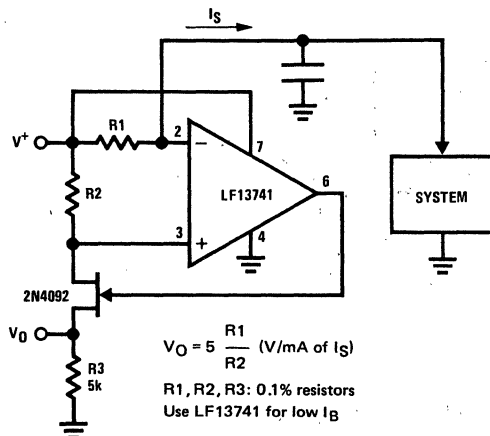
- V_{OUT} switches high when $R_S I_S > V_D$

Low Drift Adjustable Voltage Reference



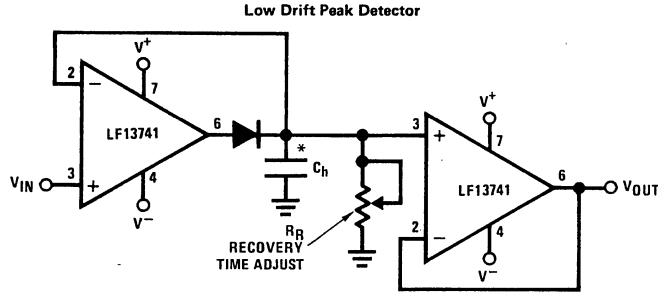
- $V_{REF} = I_D (P' + R1 + R2)$, $I_D \approx I_{DSS} \left(1 - \frac{V_{GS}}{V_P}\right)^2$
- Trim 250k potentiometer for drift adjust
- Trim 100k potentiometer for V_{REF} adjust

Supply Current Monitor

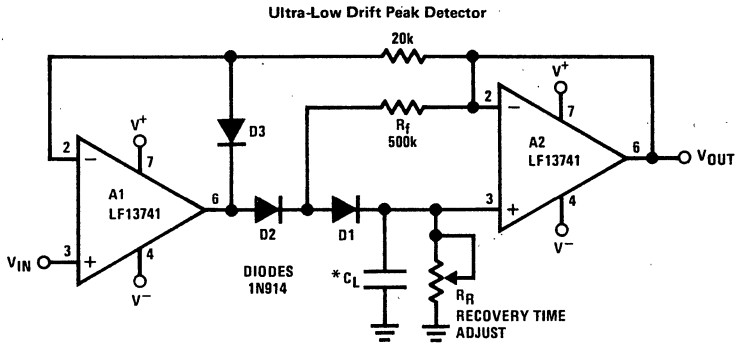


- $V_O = 5 \frac{R1}{R2} (V/mA \text{ of } I_S)$
- $R1, R2, R3: 0.1\% \text{ resistors}$
- Use LF13741 for low I_B

Typical Applications (Continued)



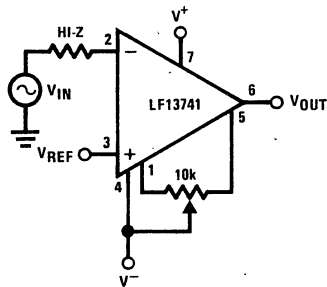
*Low leakage capacitor



- By adding D1 and Rf, $V_{D1} = 0$ during hold mode. Leakage of D2 provided by feedback path through Rf.
- Leakage of circuit is I_B plus leakage of C_h .
- D3 clamps V_{OUT} A1 to $V_{IN} - V_{D3}$ to improve speed and to limit the reverse bias of D2.
- Maximum input frequency should be $\ll 1/2\pi R_f C_{D2}$, where C_{D2} is the shunt capacitance of D2.

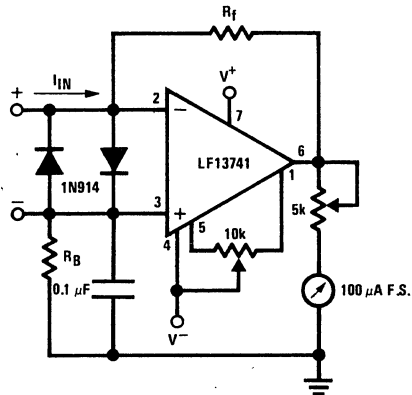
*Low leakage capacitor

Comparator with Offset Adjust for Hi-Z Inputs



$$V^- + 3V \leq V_{IN} \leq V^+ + 0.1V$$

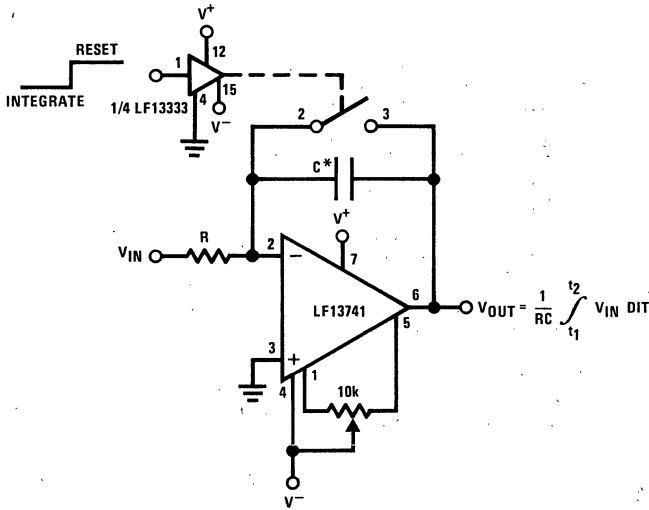
Low Current Ammeter



| I _{FULL SCALE} | R _F | R _B |
|-------------------------|----------------|----------------|
| 100 nA | 1.5M | 1.5M |
| 500 nA | 300k | 300k |
| 1 μA | 300k | 0 |
| 5 μA | 60k | 0 |
| 10 μA | 30k | 0 |
| 50 μA | 6k | 0 |
| 100 μA | 3k | 0 |

Typical Applications (Continued)

Long Time Integrator



*Low leakage capacitor

Precision Current Sink

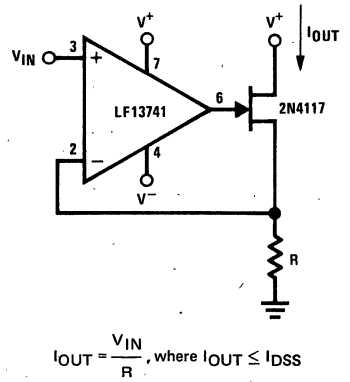
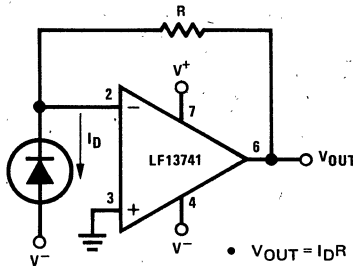
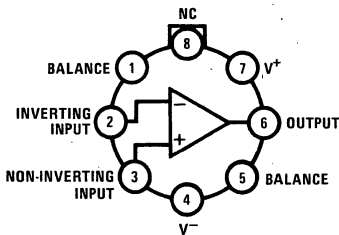


Photo Cell Amplifier (I to V Converter)



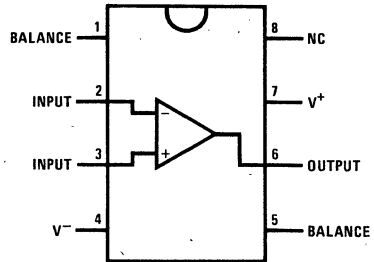
Connection Diagrams (Top Views)

TO-99 Metal Can Package



Order Number LF13741H
See NS Package H08C

Dual-In-Line Package



Order Number LF13741N
See NS Package NO8B

Note: Pin 4 connected to case.

LM10/LM10B(L)/LM10C(L) Op Amp and Voltage Reference

General Description

The LM10 series are monolithic linear ICs consisting of a precision reference, an adjustable reference buffer and an independent, high quality op amp.

The unit can operate from a total supply voltage as low as 1.1V or as high as 40V, drawing only 270 μ A. A complementary output stage swings within 15 mV of the supply terminals or will deliver ± 20 mA output current with ± 0.4 V saturation. Reference output can be as low as 200 mV. Some other characteristics of the LM10 are

| | |
|------------------------|-------------------------|
| ■ input-offset voltage | 2.0 mV (max) |
| ■ input-offset current | 0.7 nA (max) |
| ■ input-bias current | 20 nA (max) |
| ■ reference regulation | 0.1% (max) |
| ■ offset-voltage drift | 2 μ V/ $^{\circ}$ C |
| ■ reference drift | 0.002%/ $^{\circ}$ C |

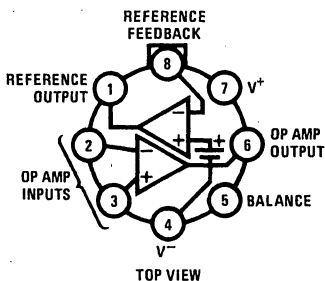
The circuit is recommended for portable equipment and is completely specified for operation from a single power cell. In contrast, high output-drive capability, both voltage and current, along with thermal overload protection, suggest it in demanding general-purpose applications.

The device is capable of operating in a floating mode, independent of fixed supplies. It can function as a remote comparator, signal conditioner, SCR controller or transmitter for analog signals, delivering the processed signal on the same line used to supply power. It is also suited for operation in a wide range of voltage- and current-regulator applications, from low voltages to several hundred volts, providing greater precision than existing ICs.

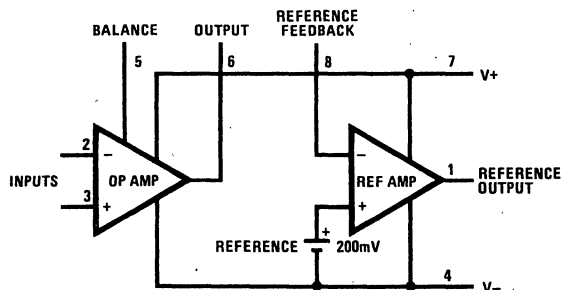
This series is available in the three standard temperature ranges, with the commercial part having relaxed limits. In addition, a low-voltage specification (suffix "L") is available in the limited temperature ranges at a cost savings.

Connection and Functional Diagrams

Metal Can Package (H)



Order Number LM10H, LM10BH, LM10CH,
LM10BLH or LM10CLH
See NS Package HO8A



Absolute Maximum Ratings

| | LM10/LM10B/LM10C | LM10BL/LM10CL |
|--|--------------------|---------------|
| Total supply voltage | 45V | 7V |
| Differential input voltage (note 1) | ±40V | ±7V |
| Power dissipation (note 2) | internally limited | |
| Output short-circuit duration (note 3) | indefinite | |
| Storage-temperature range | -55°C to +150°C | |
| Lead temperature (soldering, 10s) | 300°C | |

Electrical Characteristics (T_J = 25°C, T_{MIN} ≤ T_J ≤ T_{MAX}, note 4)

(Boldface type refers to limits over temperature range.)

| PARAMETER | CONDITIONS | LM10/LM10B | | | LM10C | | | UNITS |
|-------------------------------|---|------------|-------|--------------|-------------|-------|-------------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input offset voltage | | | 0.3 | 2.0 | | 0.5 | 4.0 | mV |
| | | | | 3.0 | | | 5.0 | mV |
| Input offset current (note 5) | | | 0.25 | 0.7 | | 0.4 | 2.0 | nA |
| | | | | 1.5 | | | 3.0 | nA |
| Input bias current | | | 10 | 20 | | 12 | 30 | nA |
| | | | | 30 | | | 40 | nA |
| Input resistance | | 250 | 500 | | 150 | 400 | kΩ | |
| | | 150 | | | 115 | | | kΩ |
| Large signal voltage gain | V _S = ±20V, I _{OUT} = 0 | 120 | 400 | | 80 | 400 | V/mV | |
| | V _{OUT} = ±19.95V | 80 | | | 50 | | V/mV | |
| | V _S = ±20V, V _{OUT} = ±19.4V | 50 | 130 | | 25 | 130 | V/mV | |
| | I _{OUT} = ±20 mA (±15 mA) | 20 | | | 15 | | V/mV | |
| Shunt gain (note 6) | V _S = ±0.6V (0.65V), I _{OUT} = ±2 mA | 1.5 | 3.0 | | 1.0 | 3.0 | V/mV | |
| | V _{OUT} = ±0.4V (±0.3V), V _{CM} = -0.4V | 0.5 | | | 0.75 | | V/mV | |
| | 1.2V (1.3V) ≤ V _{OUT} ≤ 40V, R _L = 1.1 kΩ | 14 | 33 | | 10 | 33 | V/mV | |
| | 0.1 mA ≤ I _{OUT} ≤ 5 mA | 6 | | | 6 | | V/mV | |
| Common-mode rejection | 1.5V ≤ V ⁺ ≤ 40V, R _L = 250Ω | 8 | 25 | | 6 | 25 | V/mV | |
| | 0.1 mA ≤ I _{OUT} ≤ 20 mA | 4 | | | 4 | | V/mV | |
| | -20V ≤ V _{CM} ≤ 19.15V (19V) | 93 | 102 | | 90 | 102 | dB | |
| Supply-voltage rejection | V _S = ±20V | 87 | | | 87 | | dB | |
| | -0.2V ≥ V ⁻ ≥ -39V | 90 | 96 | | 87 | 96 | dB | |
| Offset voltage drift | V ⁺ = 1.0V (1.1V) | 84 | | | 84 | | dB | |
| | 1.0V (1.1V) ≤ V ⁺ ≤ 39.8V | 96 | 106 | | 93 | 106 | dB | |
| Offset current drift | V ⁻ = -0.2V | 90 | | | 90 | | dB | |
| | | | 2.0 | | | 5.0 | μV/°C | |
| Bias current drift | | | 2.0 | | | 5.0 | pA/°C | |
| | T _C < 100°C | | 60 | | | 90 | pA/°C | |
| Line regulation | 1.2V (1.3V) ≤ V _S ≤ 40V | | 0.001 | 0.003 | | 0.001 | 0.008 | %/V |
| | 0 ≤ I _{REF} ≤ 1.0 mA, V _{REF} = 200 mV | | | 0.006 | | | 0.01 | %/V |
| Load regulation | 0 ≤ I _{REF} ≤ 1.0 mA | | 0.01 | 0.1 | | 0.01 | 0.15 | % |
| | V ⁺ - V _{REF} ≥ 1.0V (1.1V) | | | 0.15 | | | 0.2 | % |
| Amplifier gain | 0.2V ≤ V _{REF} ≤ 35V | 50 | 75 | | 25 | 70 | V/mV | |
| | | 23 | | | 15 | | V/mV | |
| Feedback sense voltage | | 195 | 200 | 205 | 190 | 200 | 210 | mV |
| | | 194 | | 206 | 189 | | 211 | mV |
| Feedback current | | | 20 | 50 | | 22 | 75 | nA |
| | | | | 65 | | | 90 | nA |
| Reference drift | | | 0.002 | | | 0.003 | %/°C | |
| Supply current | | | 270 | 400 | | 300 | 500 | μA |
| | | | | 500 | | | 570 | μA |
| Supply current change | 1.2V (1.3V) ≤ V _S ≤ 40V | | 15 | 75 | | 15 | 75 | μA |

Electrical Characteristics ($T_J = 25^\circ\text{C}$, $T_{\text{MIN}} \leq T_J \leq T_{\text{MAX}}$, note 4)

(Boldface type refers to limits over temperature range.)

| PARAMETER | CONDITIONS | LM10BL | | | LM10CL | | | UNITS |
|----------------------------------|--|--------|-------|------|--------|-------|------|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input offset voltage | | | 0.3 | 2.0 | | 0.5 | 4.0 | mV |
| | | | | 3.0 | | | 5.0 | mV |
| Input offset current (note 5) | | | 0.1 | 0.7 | | 0.2 | 2.0 | nA |
| | | | | 1.5 | | | 3.0 | nA |
| Input bias current | | | 10 | 20 | | 12 | 30 | nA |
| | | | | 30 | | | 40 | nA |
| Input resistance | | 250 | 500 | | 150 | 400 | | k Ω |
| | | 150 | | | 115 | | | k Ω |
| Large signal voltage gain | $V_S = \pm 3.25\text{V}$, $I_{\text{OUT}} = 0$ | 60 | 300 | | 40 | 300 | | V/mV |
| | $V_{\text{OUT}} = \pm 3.2\text{V}$ | 40 | | | 25 | | | V/mV |
| | $V_S = \pm 3.25\text{V}$, $I_{\text{OUT}} = 10\text{ mA}$ | 10 | 25 | | 5 | 25 | | V/mV |
| | $V_{\text{OUT}} = \pm 2.75\text{V}$ | 4 | | | 3 | | | V/mV |
| Shunt gain (note 6) | $V_S = \pm 0.6\text{V}$ (0.65V), $I_{\text{OUT}} = \pm 2\text{ mA}$ | 1.5 | 3.0 | | 1.0 | 3.0 | | V/mV |
| | $V_{\text{OUT}} = \pm 0.4\text{V}$ ($\pm 0.3\text{V}$), $V_{\text{CM}} = -0.4\text{V}$ | 0.5 | | | 0.75 | | | V/mV |
| | $1.5\text{V} \leq V^+ \leq 6.5\text{V}$, $R_L = 500\Omega$ | 8 | 30 | | 6 | 30 | | V/mV |
| | $0.1\text{ mA} \leq I_{\text{OUT}} \leq 10\text{ mA}$ | 4 | | | 4 | | | V/mV |
| Common-mode rejection | $-3.25\text{V} \leq V_{\text{CM}} \leq 2.4\text{V}$ (2.25V) | 89 | 102 | | 80 | 102 | | dB |
| | $V_S = \pm 3.25\text{V}$ | 83 | | | | | | dB |
| Supply-voltage rejection | $-0.2\text{V} \geq V^- \geq -5.4\text{V}$ | 86 | 96 | | 80 | 96 | | dB |
| | $V^+ = 1.0\text{V}$ (1.2V) | 80 | | | | | | dB |
| | 1.0V (1.1V) $\leq V^+ \leq 6.3\text{V}$ | 94 | 106 | | 80 | 106 | | dB |
| | $V^- = 0.2\text{V}$ | 88 | | | | | | dB |
| Offset voltage drift | | | 2.0 | | | 5.0 | | $\mu\text{V}/^\circ\text{C}$ |
| Offset current drift | | | 2.0 | | | 5.0 | | $\text{pA}/^\circ\text{C}$ |
| Bias current drift | | | 60 | | | 90 | | $\text{pA}/^\circ\text{C}$ |
| Line regulation | 1.2V (1.3V) $\leq V_S \leq 6.5\text{V}$ | | 0.001 | 0.01 | | 0.001 | 0.02 | %/V |
| | $0 \leq I_{\text{REF}} \leq 0.5\text{ mA}$, $V_{\text{REF}} = 200\text{ mV}$ | | | 0.02 | | | 0.03 | %/V |
| Load regulation | $0 \leq I_{\text{REF}} \leq 0.5\text{ mA}$ | | 0.01 | 0.1 | | 0.01 | 0.15 | % |
| | $V^+ - V_{\text{REF}} \geq 1.0\text{V}$ (1.1V) | | | 0.15 | | | 0.2 | % |
| Amplifier gain | $0.2\text{V} \leq V_{\text{REF}} \leq 5.5\text{V}$ | 30 | 70 | | 20 | 70 | | V/mV |
| | | 20 | | | 15 | | | V/mV |
| Feedback sense voltage | | 195 | 200 | 205 | 190 | 200 | 210 | mV |
| | | 194 | | 206 | 189 | | 211 | mV |
| Feedback current | | | 20 | 50 | | 22 | 75 | nA |
| | | | | 65 | | | 90 | nA |
| Reference drift | | | 0.002 | | | 0.003 | | $\%/^\circ\text{C}$ |
| Supply current | | | 260 | 400 | | 280 | 500 | μA |
| | | | | 500 | | | 570 | μA |

Note 1: The input voltage can exceed the supply voltages provided that the voltage from the input to any other terminal does not exceed the maximum differential input voltage and excess dissipation is accounted for when $V_{\text{IN}} < V^-$.

Note 2: The maximum, operating-junction temperature is 150°C for the LM10, 100°C for the LM10B(L) and 85°C for the LM10C(L). At elevated temperatures, devices must be derated based on package thermal resistance.

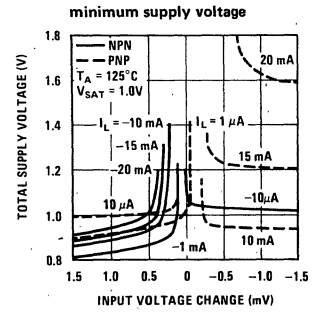
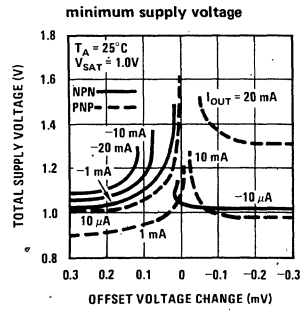
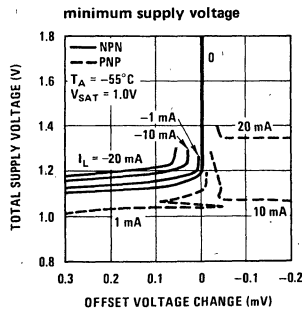
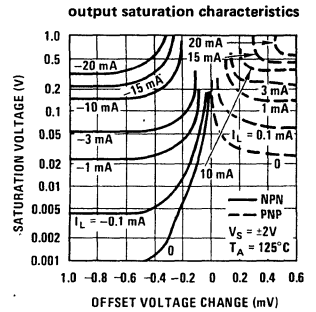
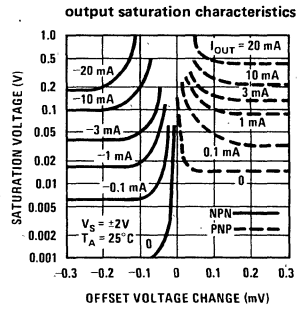
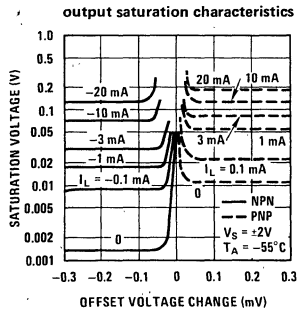
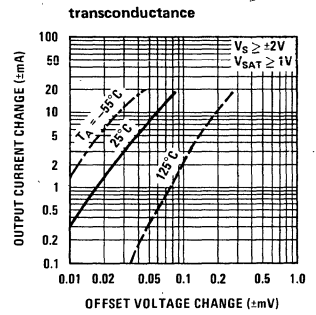
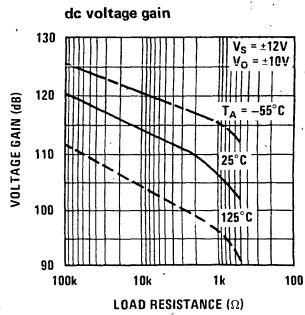
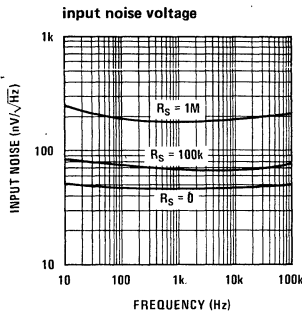
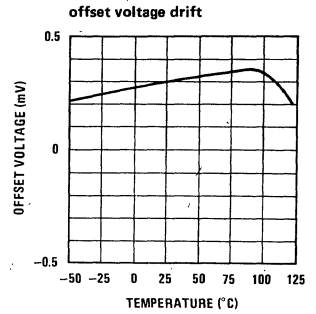
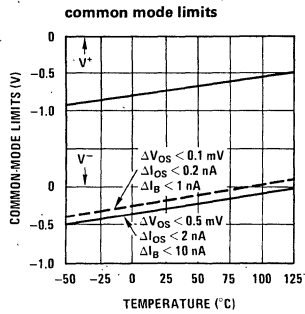
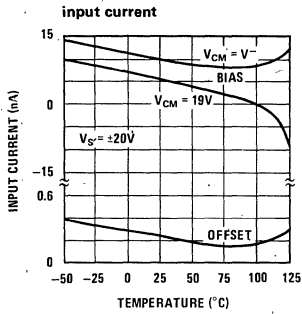
Note 3: Internal thermal limiting prevents excessive heating that could result in sudden failure, but the IC can be subjected to accelerated stress with a shorted output and worst-case conditions.

Note 4: These specifications apply for $V^- \leq V_{\text{CM}} \leq V^+ - 0.85\text{V}$ (1.0V), 1.2V (1.3V) $< V_S \leq V_{\text{MAX}}$, $V_{\text{REF}} = 0.2\text{V}$ and $0 \leq I_{\text{REF}} \leq 1.0\text{ mA}$, unless otherwise specified: $V_{\text{MAX}} = 40\text{V}$ for the standard part and 6.5V for the low voltage part. Normal typeface indicates 25°C limits. **Boldface type indicates limits and altered test conditions for full-temperature-range operation**; this is -55°C to 125°C for the LM10, -25°C to 85°C for the LM10B(L) and 0°C to 70°C for the LM10C(L). The specifications do not include the effects of thermal gradients ($\tau_1 \approx 20\text{ ms}$), die heating ($\tau_2 \approx 0.2\text{ s}$) or package heating. Gradient effects are small and tend to offset the electrical error (see curves).

Note 5: For $T_J > 90^\circ\text{C}$, I_{OS} may exceed 1.5 nA for $V_{\text{CM}} = V^-$. With $T_J = 125^\circ\text{C}$ and $V^- \leq V_{\text{CM}} \leq V^- + 0.1\text{V}$, $I_{\text{OS}} \leq 5\text{ nA}$.

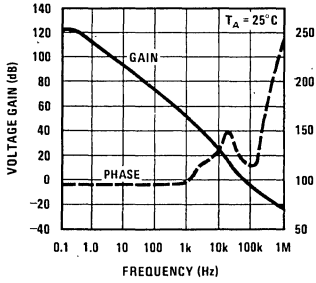
Note 6: This defines operation in floating applications such as the bootstrapped regulator or two-wire transmitter. Output is connected to the V^+ terminal of the IC and input common mode is referred to V^- (see typical applications). Effect of larger output-voltage swings with higher load resistance can be accounted for by adding the positive-supply rejection error.

Typical Performance Characteristics (Op Amp)

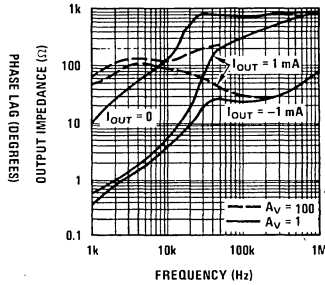


Typical Performance Characteristics (Op Amp)

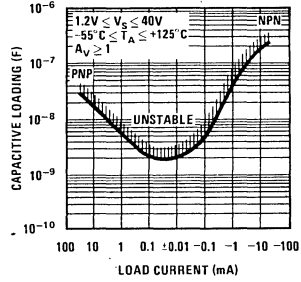
frequency response



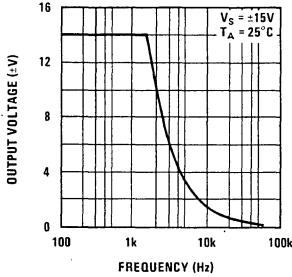
output impedance



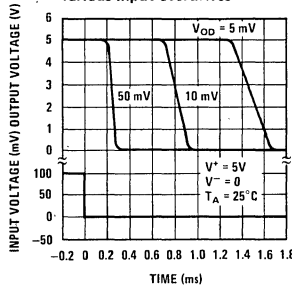
typical stability range



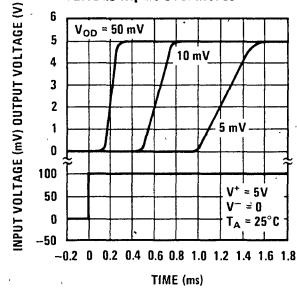
large signal response



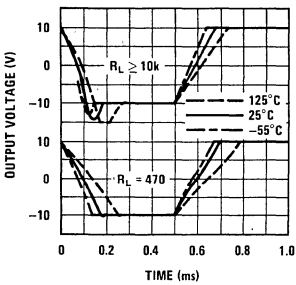
comparator response time for various input overdrives



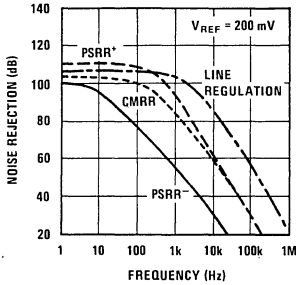
comparator response time for various input overdrives



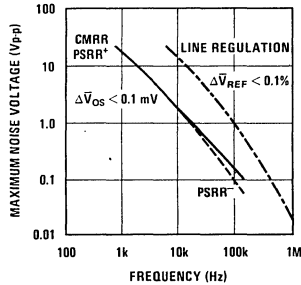
follower pulse response



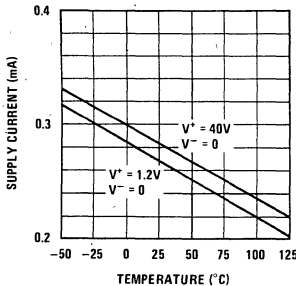
noise rejection



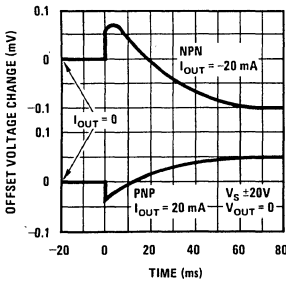
rejection slew limiting



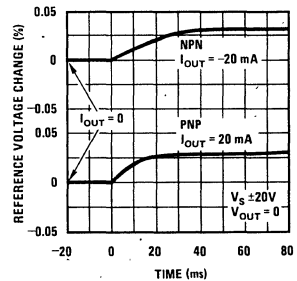
supply current



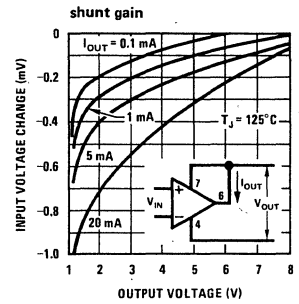
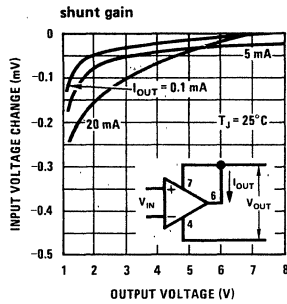
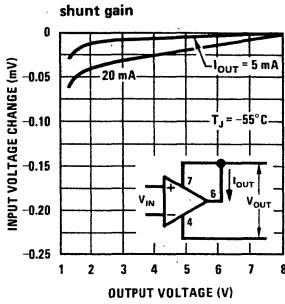
thermal gradient feedback



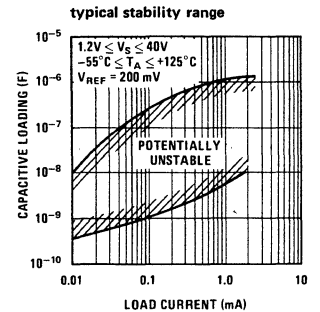
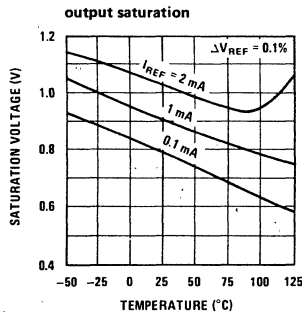
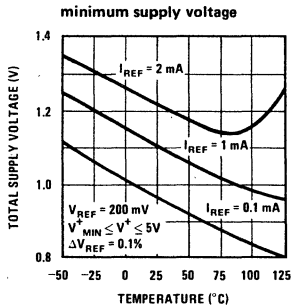
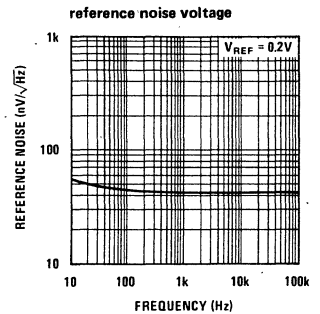
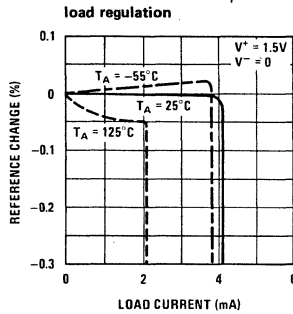
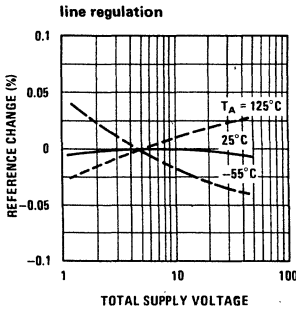
thermal gradient cross-coupling



Typical Performance Characteristics (Op Amp)



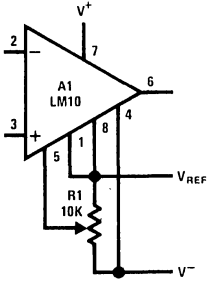
Typical Performance Characteristics (Reference)



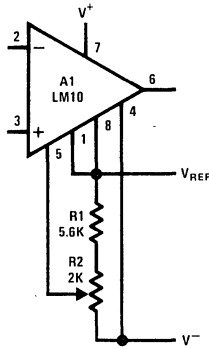
Typical Applications^{††}

op amp offset adjustment

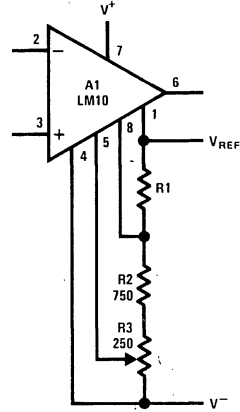
standard



limited range

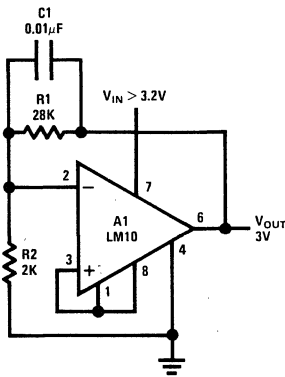


limited range with boosted reference

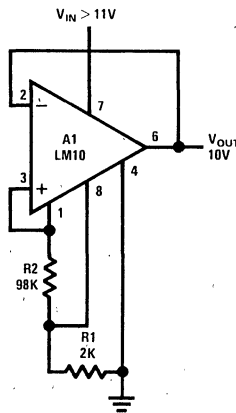


positive regulators[†]

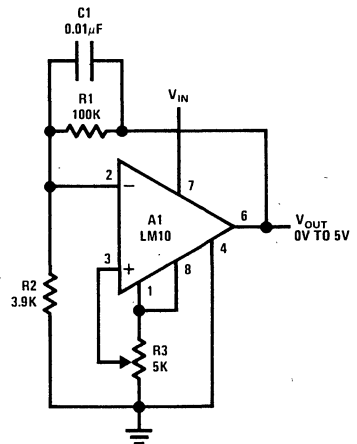
low voltage



best regulation



zero output

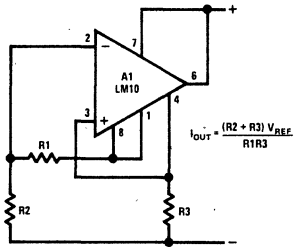


[†]Use only electrolytic output capacitors.

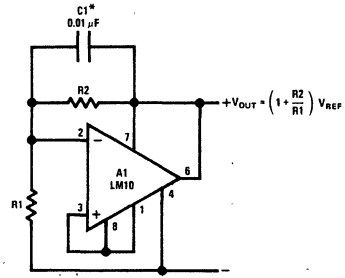
^{††}Circuit descriptions available in application note AN-211.

Typical Applications ††

current regulator

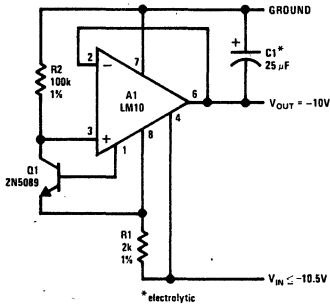


shunt regulator



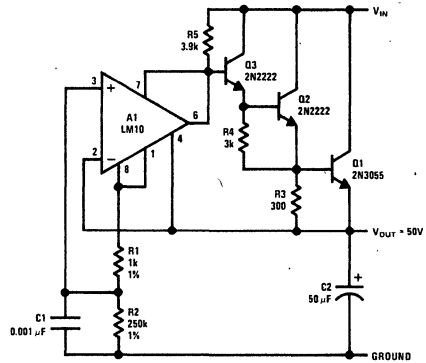
* required for capacitive loading

negative regulator

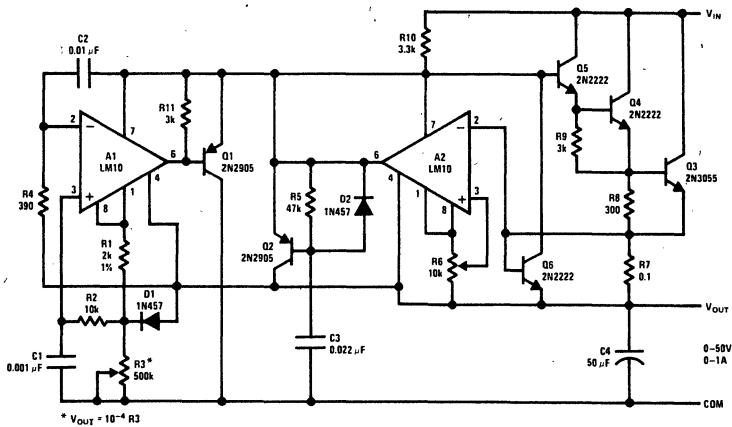


* electrolytic

precision regulator



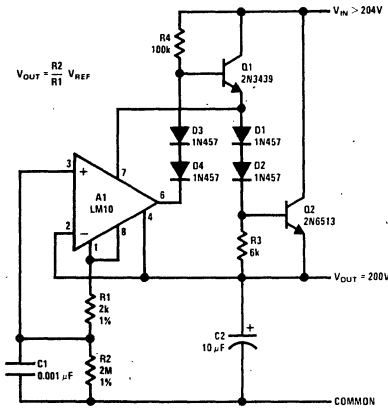
laboratory power supply



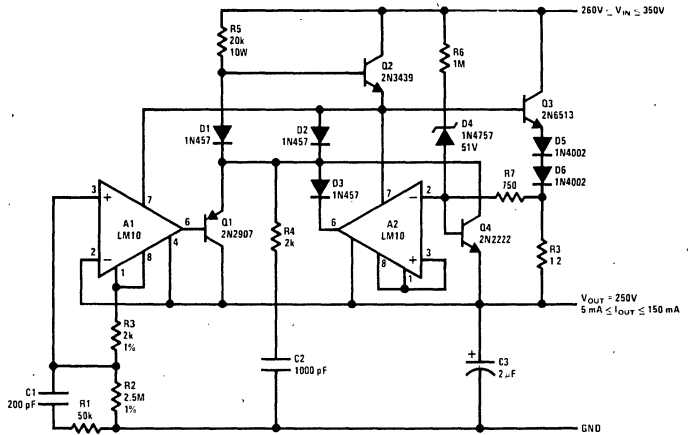
†† Circuit descriptions available in application note AN-211.

Typical Applications ††

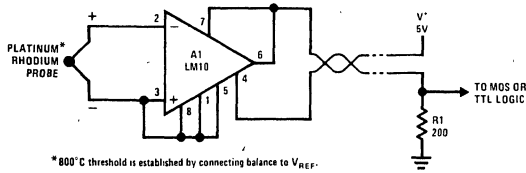
hv regulator



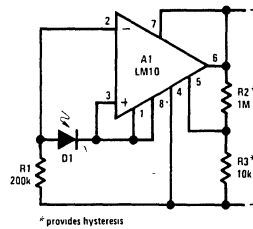
protected hv regulator



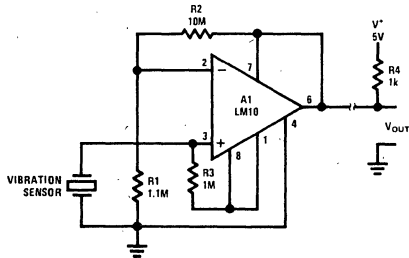
flame detector



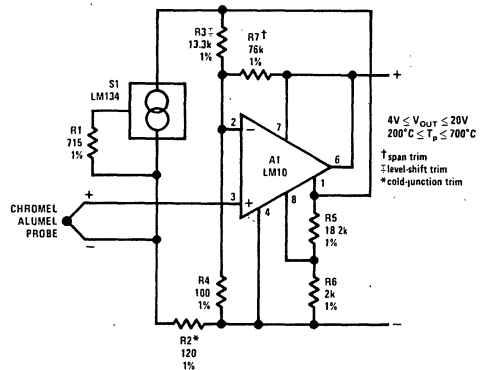
light level sensor



remote amplifier



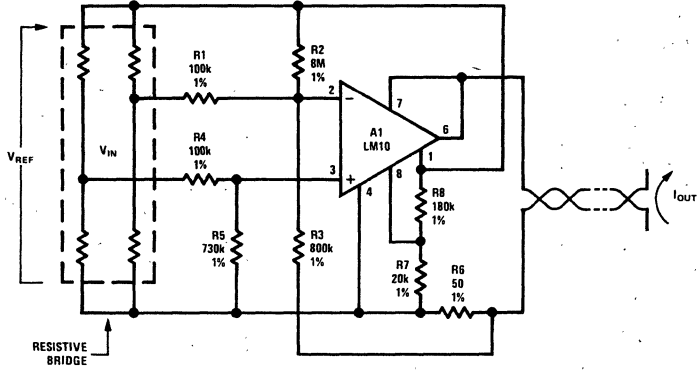
remote thermocouple amplifier



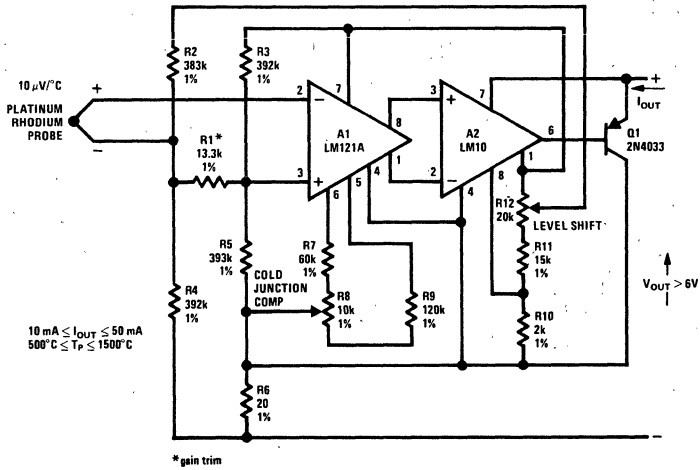
†† Circuit descriptions available in application note AN-211.

Typical Applications ††

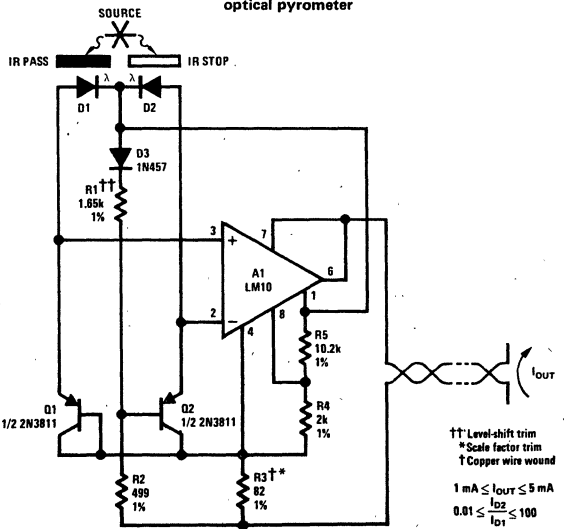
transmitter for bridge sensor



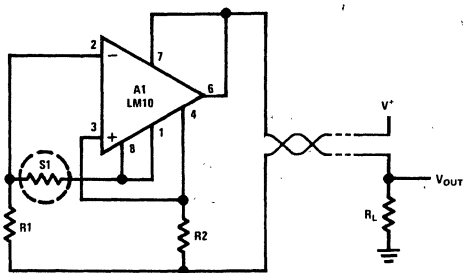
precision thermocouple transmitter



optical pyrometer



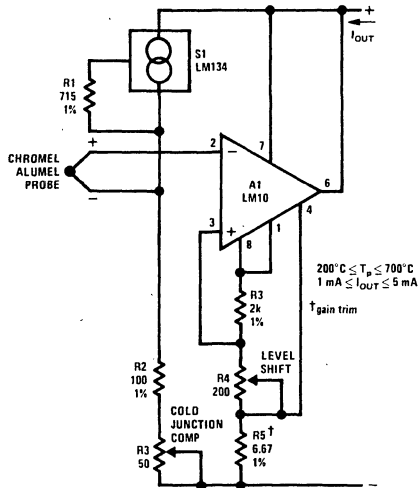
resistance thermometer transmitter



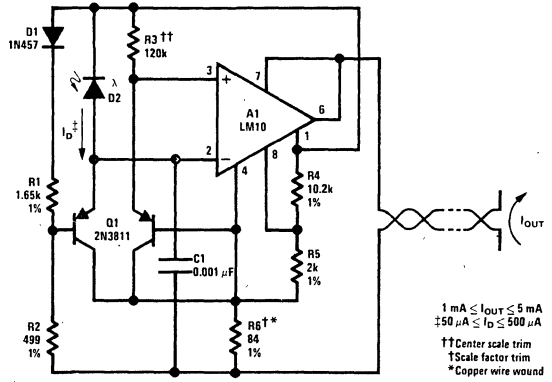
†† Circuit descriptions available in application note AN-211.

Typical Applications ^{††}

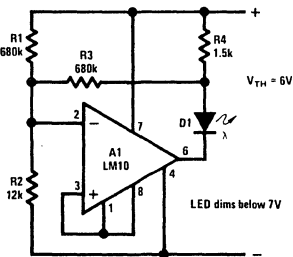
thermocouple transmitter



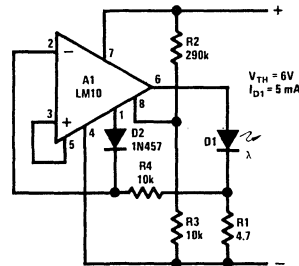
logarithmic light sensor



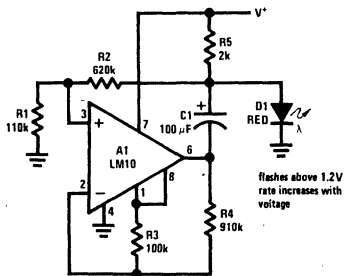
battery-level indicator



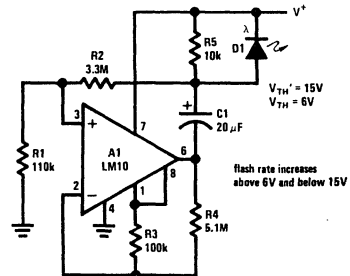
battery-threshold indicator



single-cell voltage monitor



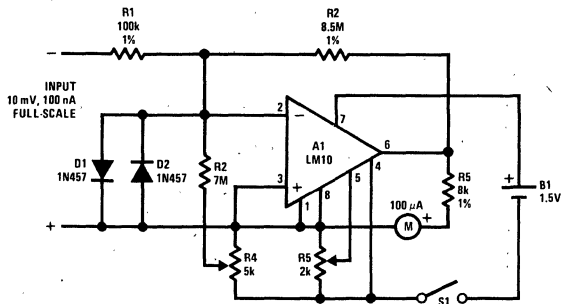
double-ended voltage monitor



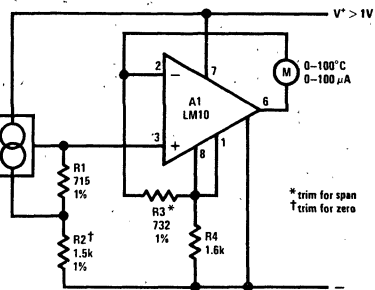
^{††}Circuit descriptions available in application note AN-211.

Typical Applications ^{††}

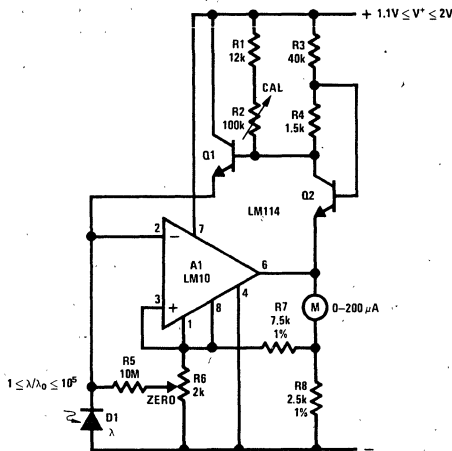
meter amplifier



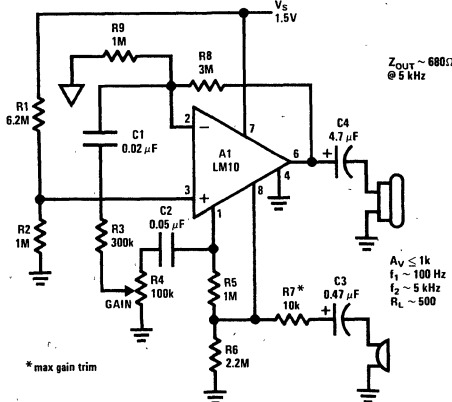
thermometer



light meter



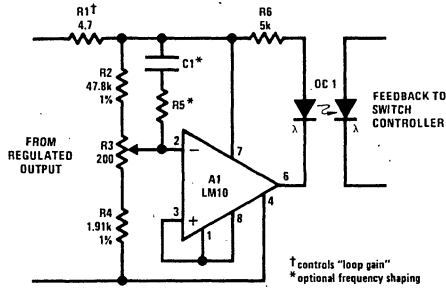
microphone amplifier



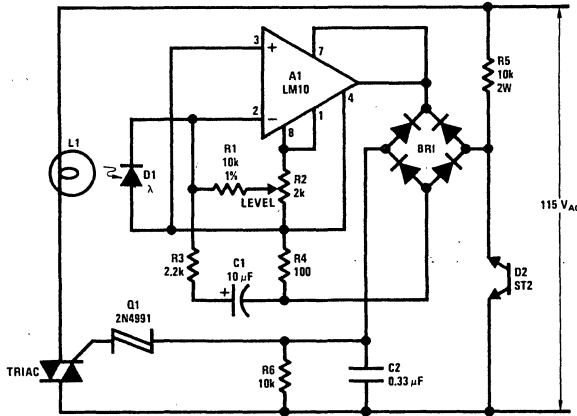
^{††}Circuit descriptions available in application note AN-211.

Typical Applications ^{††}

isolated voltage sensor



light-level controller

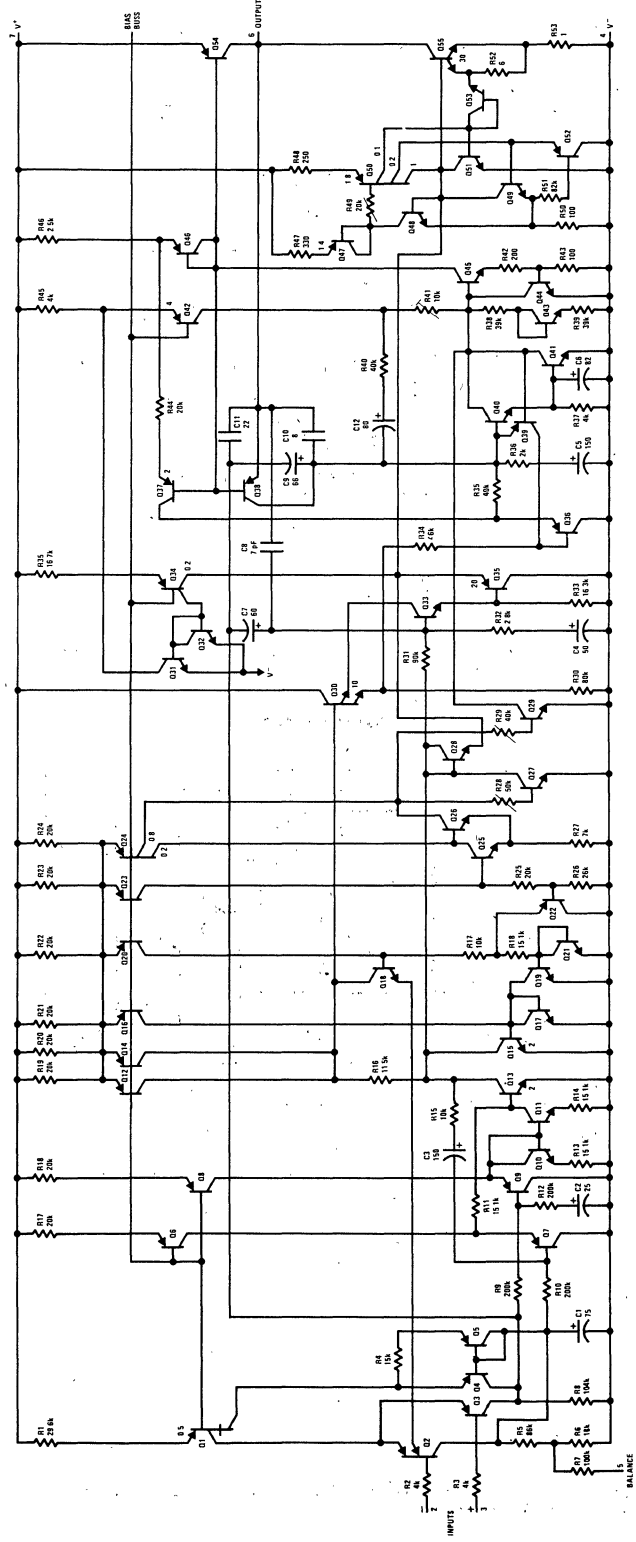


^{††}Circuit descriptions available in application note AN-211.

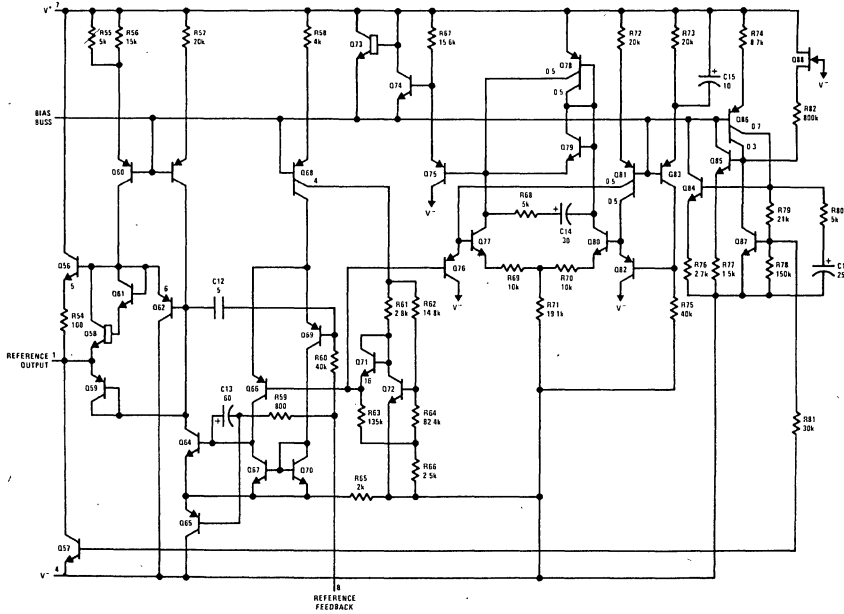
Application Hints

With heavy amplifier loading to V^- , resistance drops in the V^- lead can adversely affect reference regulation. Lead resistance can approach 1Ω . Therefore, the common to the reference circuitry should be connected as close as possible to the package.

Operational Amplifier Schematic



Reference and Internal Regulator



LM10/LM10B(L)/LM10C(L)

3

Definition of Terms

Input offset voltage: That voltage which must be applied between the input terminals to bias the unloaded output in the linear region.

Input offset current: The difference in the currents at the input terminals when the output is unloaded in the linear region.

Input bias current: The absolute value of the average of the two input currents.

Input resistance: The ratio of the change in input voltage to the change in input current on either input with the other grounded.

Large signal voltage gain: The ratio of the specified output voltage swing to the change in differential input voltage required to produce it.

Shunt gain: The ratio of the specified output voltage swing to the change in differential input voltage required to produce it with the output tied to the V^+ terminal of the IC. The load and power source are connected between the V^+ and V^- terminals, and input common-mode is referred to the V^- terminal.

Common-mode rejection: The ratio of the input voltage range to the change in offset voltage between the extremes.

Supply-voltage rejection: The ratio of the specified supply-voltage change to the change in offset voltage between the extremes.

Line regulation: The average change in reference output voltage over the specified supply voltage range.

Load regulation: The change in reference output voltage from no load to that load specified.

Feedback sense voltage: The voltage, referred to V^- , on the reference feedback terminal while operating in regulation.

Reference amplifier gain: The ratio of the specified reference output change to the change in feedback sense voltage required to produce it.

Feedback current: The absolute value of the current at the feedback terminal when operating in regulation.

Supply current: The current required from the power source to operate the amplifier and reference with their outputs unloaded and operating in the linear range.

LM101A/LM201A/LM301A Operational Amplifiers

General Description

The LM101A series are general purpose operational amplifiers which feature improved performance over industry standards like the LM709. Advanced processing techniques make possible an order of magnitude reduction in input currents, and a redesign of the biasing circuitry reduces the temperature drift of input current. Improved specifications include:

- Offset voltage 3 mV maximum over temperature (LM101A/LM201A)
- Input current 100 nA maximum over temperature (LM101A/LM201A)
- Offset current 20 nA maximum over temperature (LM101A/LM201A)
- Guaranteed drift characteristics
- Offsets guaranteed over entire common mode and supply voltage ranges
- Slew rate of 10V/μs as a summing amplifier

This amplifier offers many features which make its application nearly foolproof: overload protection on the input and output, no latch-up when the common mode range is exceeded, freedom from oscillations and compensation with a single 30 pF

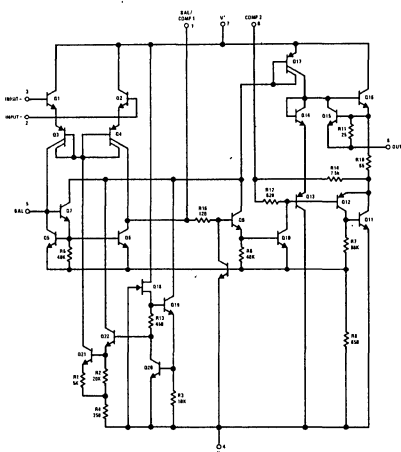
capacitor. It has advantages over internally compensated amplifiers in that the frequency compensation can be tailored to the particular application. For example, in low frequency circuits it can be overcompensated for increased stability margin. Or the compensation can be optimized to give more than a factor of ten improvement in high frequency performance for most applications.

In addition, the device provides better accuracy and lower noise in high impedance circuitry. The low input currents also make it particularly well suited for long interval integrators or timers, sample and hold circuits and low frequency waveform generators. Further, replacing circuits where matched transistor pairs buffer the inputs of conventional IC op amps, it can give lower offset voltage and drift at a lower cost.

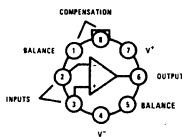
The LM101A is guaranteed over a temperature range of -55°C to +125°C, the LM201A from -25°C to +85°C, and the LM301A from 0°C to 70°C.

3

Schematic ** and Connection Diagrams (Top Views)



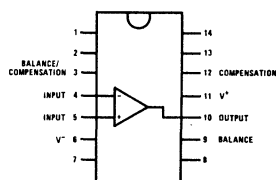
Metal Can Package



Note: Pin 4 connected to case.

Order Number LM101AH,
LM201AH or LM301AH
See NS Package H08C

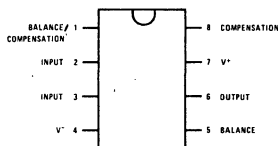
Dual-In-Line Package



Note: Pin 6 connected to bottom of package.

Order Number LM101AJ-14,
LM201AJ-14 or LM301AJ
See NS Package J14A

Dual-In-Line Package



Order Number
LM301AJ

See NS Package J08A
Order Number LM301AN
See NS Package N08A

**Pin connections shown are for metal can.

Absolute Maximum Ratings

| | LM101A/LM201A | LM301A |
|--|---|-----------------|
| Supply Voltage | ±22V | ±18V |
| Power Dissipation (Note 1) | 500 mW | 500 mW |
| Differential Input Voltage | ±30V | ±30V |
| Input Voltage (Note 2) | ±15V | ±15V |
| Output Short Circuit Duration (Note 3) | Indefinite | Indefinite |
| Operating Temperature Range | -55°C to +125°C (LM101A) -25°C to +85°C (LM201A) | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM101A/LM201A | | | LM301A | | | UNITS |
|---|---|---------------|------|-----|--------|-----|-----|--|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage LM101A, LM201A, LM301A | $T_A = 25^\circ\text{C}$ $R_S \leq 50\text{ k}\Omega$ | | 0.7 | 2.0 | 2.0 | 7.5 | | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 1.5 | 10 | 3.0 | 50 | | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 30 | 75 | 70 | 250 | | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 1.5 | 4.0 | | 0.5 | 2.0 | | M Ω |
| Supply Current | $T_A = 25^\circ\text{C}$ $V_S = \pm 20\text{V}$ $V_S = \pm 15\text{V}$ | | 1.8 | 3.0 | | 1.8 | 3.0 | mA mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L \geq 2\text{ k}\Omega$ | 50 | 160 | | 25 | 160 | | V/mV |
| Input Offset Voltage | $R_S \leq 50\text{ k}\Omega$ $R_S \leq 10\text{ k}\Omega$ | | | 3.0 | | 10 | | mV mV |
| Average Temperature Coefficient of Input Offset Voltage | $R_S \leq 50\text{ k}\Omega$ $R_S \leq 10\text{ k}\Omega$ | | 3.0 | 15 | 6.0 | 30 | | $\mu\text{V}/^\circ\text{C}$ $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | $T_A = T_{MAX}$ $T_A = T_{MIN}$ | | | 20 | | 70 | | nA nA nA |
| Average Temperature Coefficient of Input Offset Current | $25^\circ\text{C} \leq T_A \leq T_{MAX}$ $T_{MIN} \leq T_A \leq 25^\circ\text{C}$ | | 0.01 | 0.1 | 0.01 | 0.3 | | $\text{nA}/^\circ\text{C}$ $\text{nA}/^\circ\text{C}$ |
| Input Bias Current | | | | 0.1 | | 0.3 | | μA |
| Supply Current | $T_A = T_{MAX}$, $V_S = \pm 20\text{V}$ | | 1.2 | 2.5 | | | | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L \geq 2\text{ k}\Omega$ | 25 | | | 15 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$ $R_L = 10\text{ k}\Omega$ $R_L = 2\text{ k}\Omega$ | ±12 | ±14 | | ±12 | ±14 | | V V V |
| Input Voltage Range | $V_S = \pm 20\text{V}$ $V_S = \pm 15\text{V}$ | ±15 | | | | | | V V |
| Common-Mode Rejection Ratio | $R_S \leq 50\text{ k}\Omega$ $R_S \leq 10\text{ k}\Omega$ | 80 | 96 | | 70 | 90 | | dB dB |
| Supply Voltage Rejection Ratio | $R_S \leq 50\text{ k}\Omega$ $R_S \leq 10\text{ k}\Omega$ | 80 | 96 | | 70 | 96 | | dB dB |

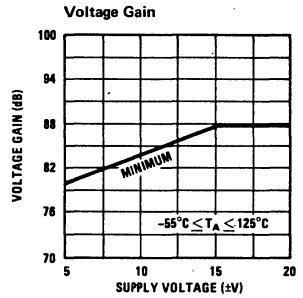
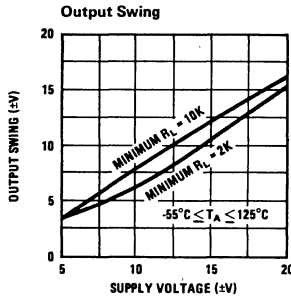
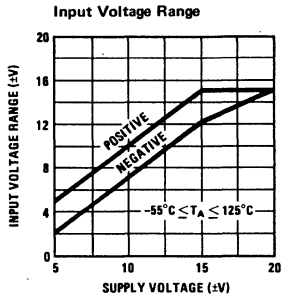
Note 1: The maximum junction temperature of the LM101A is 150°C, and that of the LM201A/LM301A is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 187°C/W, junction to ambient.

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

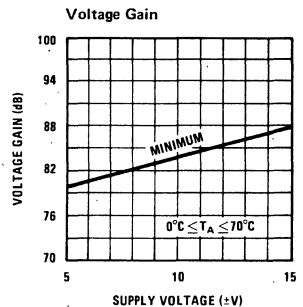
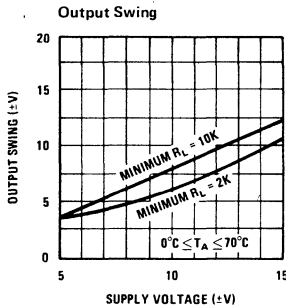
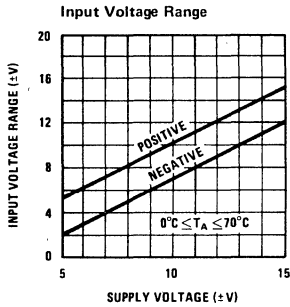
Note 3: Continuous short circuit is allowed for case temperatures to 125°C and ambient temperatures to 75°C for LM101A/LM201A, and 70°C and 55°C respectively for LM301A.

Note 4: Unless otherwise specified, these specifications apply for $C_1 = 30\text{ pF}$, $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ (LM101A), $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ (LM201A), $\pm 5\text{V} \leq V_S \leq \pm 15\text{V}$ and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ (LM301A).

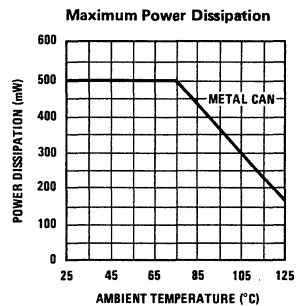
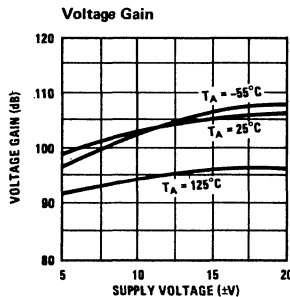
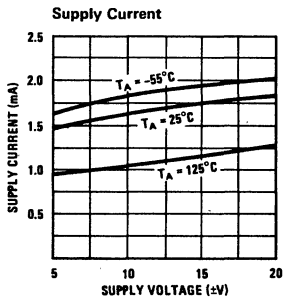
Guaranteed Performance Characteristics LM101A/LM201A



Guaranteed Performance Characteristics LM301A

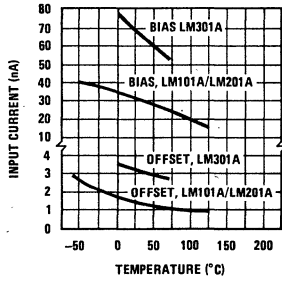


Typical Performance Characteristics

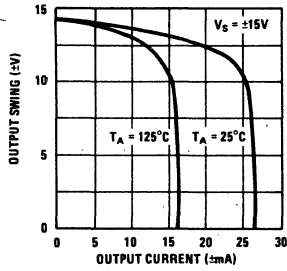


Typical Performance Characteristics (Continued)

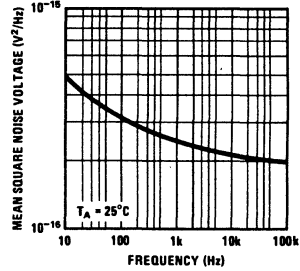
Input Current, LM101A/
LM201A/LM301A



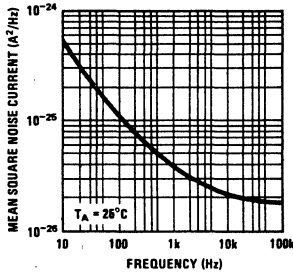
Current Limiting



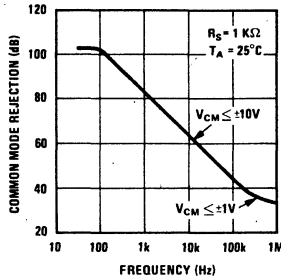
Input Noise Voltage



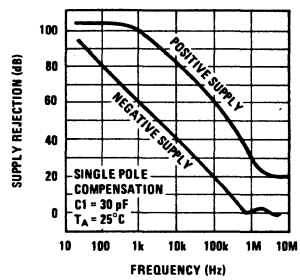
Input Noise Current



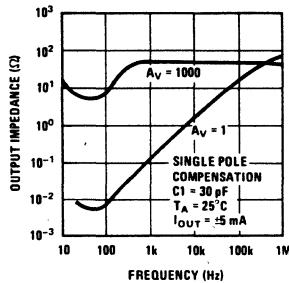
Common Mode Rejection



Power Supply Rejection

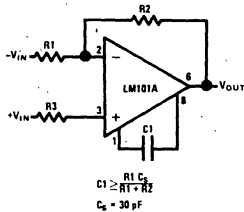


Closed Loop Output Impedance

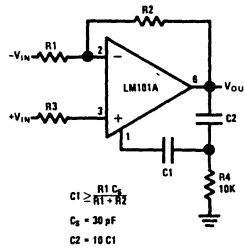


Typical Performance Characteristics for Various Compensation Circuits**

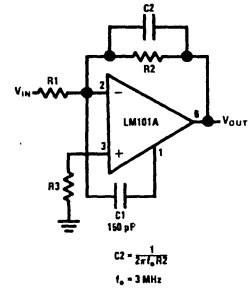
Single Pole Compensation



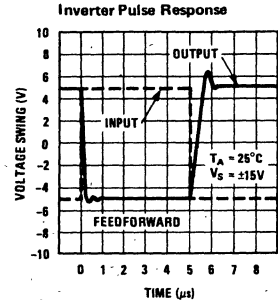
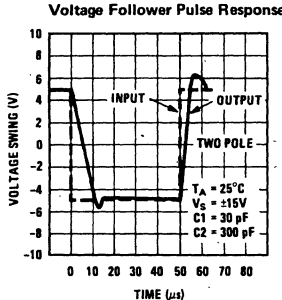
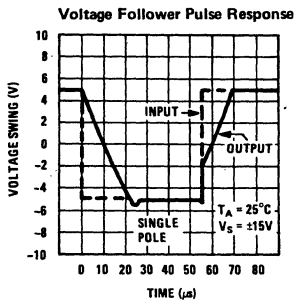
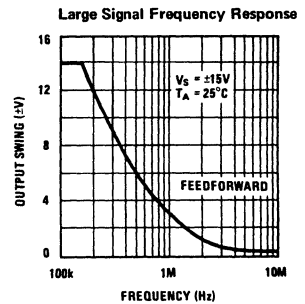
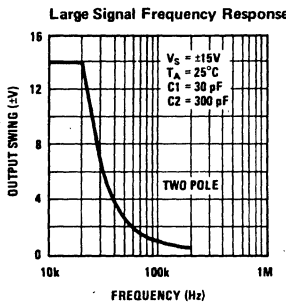
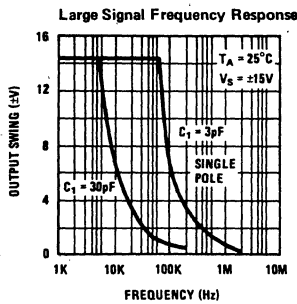
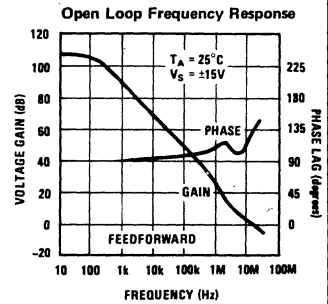
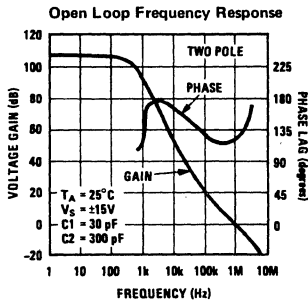
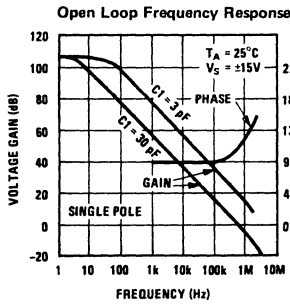
Two Pole Compensation



Feedforward Compensation

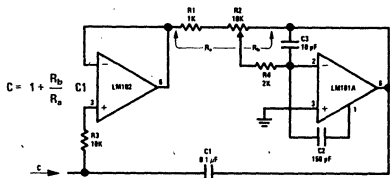


**Pin connections shown are for metal can.

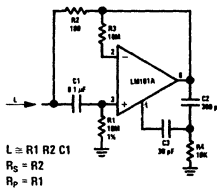


Typical Applications **

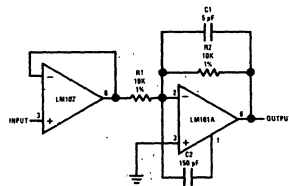
Variable Capacitance Multiplier



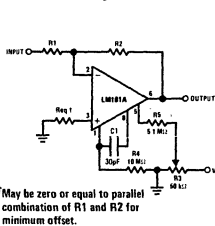
Simulated Inductor



Fast Inverting Amplifier With High Input Impedance

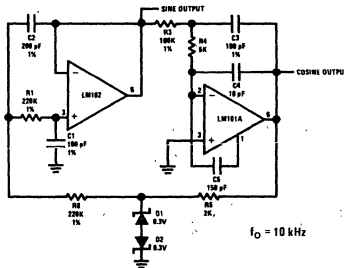


Inverting Amplifier with Balancing Circuit



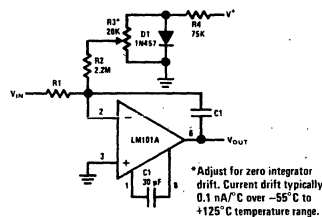
*May be zero or equal to parallel combination of R1 and R2 for minimum offset.

Sine Wave Oscillator



f₀ = 10 kHz

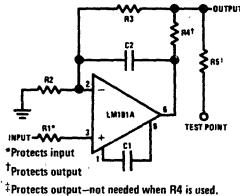
Integrator with Bias Current Compensation



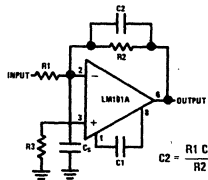
*Adjust for zero integrator drift. Current drift typically 0.1 nA/°C over -55°C to +125°C temperature range.

Application Hints **

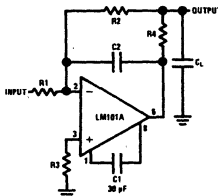
Protecting Against Gross Fault Conditions



Compensating For Stray Input Capacitances Or Large Feedback Resistor



Isolating Large Capacitive Loads



Although the LM101A is designed for trouble free operation, experience has indicated that it is wise to observe certain precautions given below to protect the devices from abnormal operating conditions. It might be pointed out that the advice given here is applicable to practically any IC op amp, although the exact reason why may differ with different devices.

When driving either input from a low-impedance source, a limiting resistor should be placed in series with the input lead to limit the peak instantaneous output current of the source to something less than 100 mA. This is especially important when the inputs go outside a piece of equipment where they could accidentally be connected to high voltage sources. Large capacitors on the input (greater than 0.1 μF) should be treated as a low source impedance and isolated with a resistor. Low impedance sources do not cause a problem unless their output voltage exceeds the supply voltage. However, the supplies go to zero when they are turned off, so the isolation is usually needed.

The output circuitry is protected against damage from shorts to ground. However, when the amplifier output is connected to a test point, it should be isolated by a limiting resistor, as test points frequently get shorted to bad places. Further, when the amplifier drives a load external to the equipment, it is also advisable to use some sort of limiting resistance to preclude mishaps.

Precautions should be taken to insure that the power supplies for the integrated circuit never become reversed—even under transient conditions. With reverse voltages greater than 1V, the IC will conduct excessive current, fusing internal aluminum interconnects. If there is a possibility of this happening, clamp diodes with a high peak current rating should be installed on the supply lines. Reversals of the voltage between V⁺ and V⁻ will always cause a problem, although reversals with respect to ground may also give difficulties in many circuits.

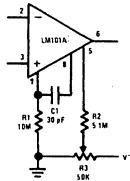
The minimum values given for the frequency compensation capacitor are stable only for source resistances less than 10 kΩ, stray capacitances on the summing junction less than 5 pF and capacitive loads smaller than 100 pF. If any of these conditions are not met, it becomes necessary to overcompensate the amplifier with a larger compensation capacitor. Alternately, lead capacitors can be used in the feedback network to negate the effect of stray capacitance and large feedback resistors or an RC network can be added to isolate capacitive loads.

Although the LM101A is relatively unaffected by supply bypassing, this cannot be ignored altogether. Generally it is necessary to bypass the supplies to ground at least once on every circuit card, and more bypass points may be required if more than five amplifiers are used. When feed-forward compensation is employed, however, it is advisable to bypass the supply leads of each amplifier with low inductance capacitors because of the higher frequencies involved.

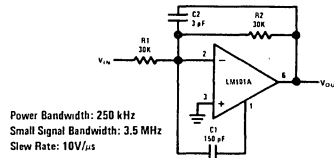
**Pin connections shown are for metal can.

Typical Applications** (Continued)

Standard Compensation and Offset Balancing Circuit

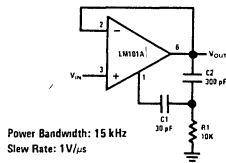


Fast Summing Amplifier



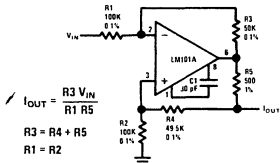
Power Bandwidth: 250 kHz
Small Signal Bandwidth: 3.5 MHz
Slew Rate: 10V/μs

Fast Voltage Follower



Power Bandwidth: 15 kHz
Slew Rate: 1V/μs

Bilateral Current Source

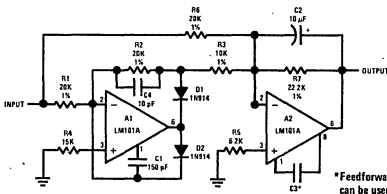


$$I_{OUT} = \frac{R3 V_{IN}}{R1 R5}$$

$$R3 = R4 + R5$$

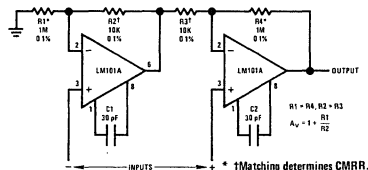
$$R1 = R2$$

Fast AC/DC Converter*



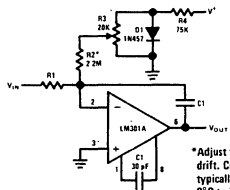
*Feedforward compensation can be used to make a fast full wave rectifier without a filter.

Instrumentation Amplifier



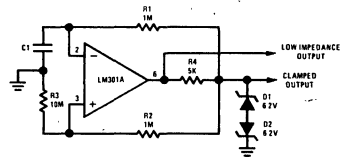
*1 Matching determines CMRR.

Integrator with Bias Current Compensation

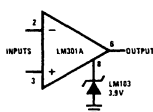


*Adjust for zero integrator drift. Current drift typically 0.1 nA/°C over 0°C to 70°C temperature range.

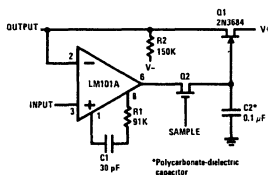
Low Frequency Square Wave Generator



Voltage Comparator for Driving RTL Logic or High Current Driver

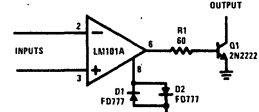


Low Drift Sample and Hold



*Polycarbonate-dielectric capacitor

Voltage Comparator for Driving DTL or TTL Integrated Circuits



**Pin connections shown are for metal can.



National Semiconductor

Operational Amplifiers/Buffers

LH2101A/LH2201A/LH2301A Dual High Performance Op Amp

general description

The LH2101A series of dual operational amplifiers are two LM101A type op amps in a single hermetic package. Featuring all the same performance characteristics of the single, these duals offer in addition closer thermal tracking, lower weight, reduced insertion cost, and smaller size than two singles. For additional information, see the LM101A data sheet and National's Linear Application Handbook.

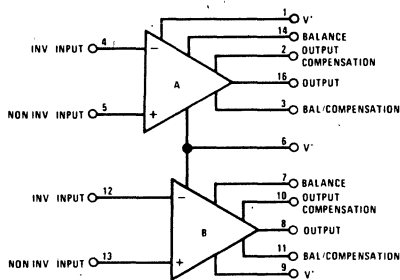
The LH2101A is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LH2201A is specified for operation over the

-25°C to $+85^{\circ}\text{C}$ temperature range. The LH2301A is specified for operation over the 0°C to $+70^{\circ}\text{C}$ temperature range.

features

- Low offset voltage
- Low offset current
- Guaranteed drift characteristics
- Offsets guaranteed over entire common mode and supply voltage ranges
- Slew rate of $10\text{V}/\mu\text{s}$ as a summing amplifier

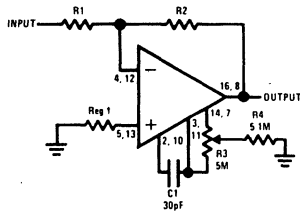
connection diagram



Order Number LH2101AD or
LH2201AD or LH2301AD
See Package D16C

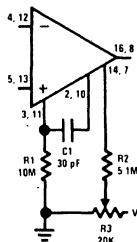
auxiliary circuits

Inverting Amplifier with Balancing Circuit

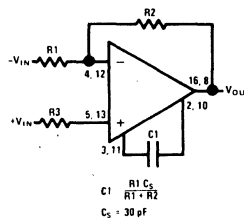


*May be zero or equal to parallel combination of R1 and R2 for minimum offset

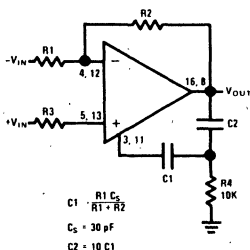
Alternate Balancing Circuit



Single Pole Compensation

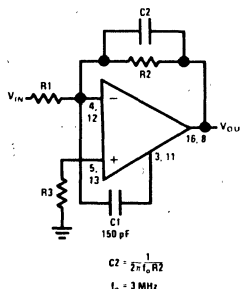


Two Pole Compensation



$R1 C1 = R2 C2$
 $C1 = R1 C2$
 $C2 = 10 \text{ pF}$

Feedforward Compensation



$C2 = \frac{1}{2\pi f_c R2}$
 $f_c = 3 \text{ MHz}$

absolute maximum ratings

| | |
|-------------------------------|------------|
| Supply Voltage | ±22V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Voltage | ±30V |
| Input Voltage (Note 2) | ±15V |
| Output Short Circuit Duration | Continuous |

| | | |
|--------------------------------------|---------|----------------|
| Operating Temperature Range | LH2101A | -55°C to 125°C |
| | LH2201A | -25°C to 85°C |
| | LH2301A | 0°C to 70°C |
| Storage Temperature Range | | -65°C to 150°C |
| Lead Temperature (Soldering, 10 sec) | | 300°C |

electrical characteristics each side (Note 3)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---|---|------------|------------|------------|--|
| | | LH2101A | LH2201A | LH2301A | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}, R_S \leq 50\text{ k}\Omega$ | 2.0 | 2.0 | 7.5 | mV Max |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | 10 | 10 | 50 | nA Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 75 | 75 | 250 | nA Max |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 1.5 | 1.5 | 0.5 | M Ω Min |
| Supply Current | $T_A = 25^\circ\text{C}, V_S = \pm 20\text{V}$ | 3.0 | 3.3 | 3.0 | mA Max |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}, R_L \geq 2\text{ k}\Omega$ | 50 | 50 | 25 | V/mV Min |
| Input Offset Voltage | $R_S \leq 50\text{ k}\Omega$ | 3.0 | 3.0 | 10 | mV Max |
| Average Temperature Coefficient of Input Offset Voltage | | 15 | 15 | 30 | $\mu\text{V}/^\circ\text{C}$ Max |
| Input Offset Current | | 20 | 20 | 70 | nA Max |
| Average Temperature Coefficient of Input Offset Current | $25^\circ\text{C} < T_A < 125^\circ\text{C}$ $-55^\circ\text{C} \leq T_A \leq 25^\circ\text{C}$ | 0.1 | 0.1 | 0.3 | nA/ $^\circ\text{C}$ Max nA/ $^\circ\text{C}$ Max |
| Input Bias Current | | 100 | 100 | 300 | nA Max |
| Supply Current | $T_A = +125^\circ\text{C}, V_S = \pm 20\text{V}$ | 2.5 | 2.5 | | mA Max |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, V_{OUT} = \pm 10\text{V}$ $R_L > 2\text{ k}\Omega$ | 25 | 25 | 15 | V/mV Min |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 10\text{ k}\Omega$ $R_L = 2\text{ k}\Omega$ | ±12 ±10 | ±12 ±10 | ±12 ±10 | V Min V Min |
| Input Voltage Range | $V_S = \pm 20\text{V}$ | ±15 | ±15 | ±12 | V Min |
| Common Mode Rejection Ratio | $R_S < 50\text{ k}\Omega$ | 80 | 80 | 70 | dB Min |
| Supply Voltage Rejection Ratio | $R_S < 50\text{ k}\Omega$ | 80 | 80 | 70 | dB Min |

Note 1: The maximum junction temperature of the LH2101A is 150°C, while that of the LH2201A is 100°C. For operating temperatures of devices in the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with 0.03-inch-wide, 2-ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LH2201A, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$. For the LH2301A these specifications apply for $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$, and $\pm 5\text{V} \leq V_S \leq \pm 15\text{V}$. Supply current and input voltage range are specified as $V_S = \pm 15\text{V}$ for the LH2301A. $C_1 = 30\text{ pF}$ unless otherwise specified.

LM102/LM202/LM302 Voltage Followers

General Description

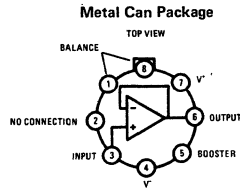
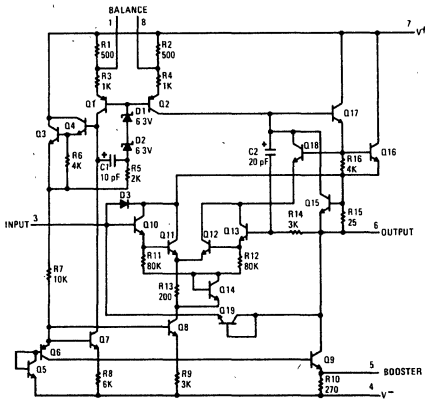
The LM102 series are high-gain operational amplifiers designed specifically for unity-gain voltage follower applications. Built on a single silicon chip, the devices incorporate advanced processing techniques to obtain very low input current and high input impedance. Further, the input transistors are operated at zero collector-base voltage to virtually eliminate high temperature leakage currents. It can therefore be operated in a temperature stabilized component oven to get extremely low input currents and low offset voltage drift. Other outstanding characteristics of the device include:

- Fast slewing – 10V/μs
- Low input current – 10 nA (max)

- High input resistance – 10,000 MΩ
- No external frequency compensation required
- Simple offset balancing with optional 1K potentiometer
- Plug-in replacement for both the LM101 and LM709 in voltage follower applications.

The LM102, which is designed to operate with supply voltages between ±12V and ±15V, also features low input capacitance as well as excellent small signal and large signal frequency response – all of which minimize high frequency gain error. Because of the low wiring capacitances inherent in monolithic construction, this fast operation can be realized without increasing power consumption.

Schematic** and Connection Diagrams

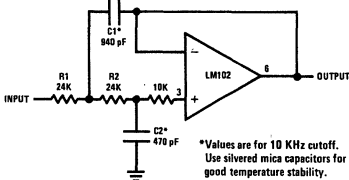


Note: Pin 4 connected to case.

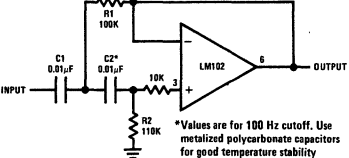
Order Number LM102H, LM202H or LM302H
See NS Package H08C

Typical Applications**

Low Pass Active Filter

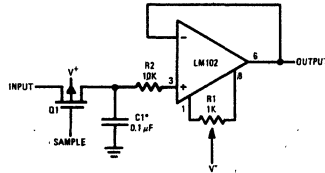


High Pass Active Filter

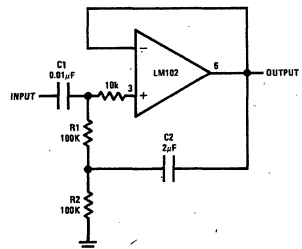


**Pin connections shown are for metal can.

Sample and Hold With Offset Adjustment



High Input Impedance AC Amplifier



Absolute Maximum Ratings

| | |
|--|----------------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Input Voltage (Note 2) | ±15V |
| Output Short Circuit Duration (Note 3) | Indefinite |
| Operating Temperature Range | LM102 -55°C to 125°C |
| | LM202 -25°C to 85°C |
| | LM302 0°C to 70°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM102 | | LM202 | | LM302 | | UNITS | | |
|----------------------------------|--|-----------|-----------|-----------|-----------|--------|-----------|------------------------------|-----|-----|
| | | MIN | TYP | MAX | MIN | TYP | MAX | | | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | 2 | 5 | 3 | 10 | 5 | 15 | mV | | |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 3 | 10 | 7 | 15 | 10 | 30 | nA | | |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 10^{10} | 10^{12} | 10^{10} | 10^{12} | 10^9 | 10^{12} | Ω | | |
| Input Capacitance | | | 3.0 | 3.0 | | 3.0 | | pF | | |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L = 8\text{ k}\Omega$ | 0.999 | 0.9996 | 0.999 | 0.9995 | 1.0 | 0.9985 | 0.9995 | 1.0 | V/V |
| Output Resistance | $T_A = 25^\circ\text{C}$ | 0.8 | 2.5 | 0.8 | 2.5 | 0.8 | 2.5 | Ω | | |
| Supply Current | $T_A = 25^\circ\text{C}$ | 3.5 | 5.5 | 3.5 | 5.5 | 3.5 | 5.5 | mA | | |
| Input Offset Voltage | | | 7.5 | | 15 | | 20 | mV | | |
| Offset Voltage Temperature Drift | | 6 | | 15 | | 20 | | $\mu\text{V}/^\circ\text{C}$ | | |
| Input Bias Current | $T_A = T_{A\text{MAX}}$ | 3 | 10 | 1.5 | 5.0 | 3.0 | 15 | nA | | |
| | $T_A = T_{A\text{MIN}}$ | 30 | 100 | 30 | 50 | 20 | 50 | nA | | |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L = 10\text{ k}\Omega$ | 0.999 | | | | | | | | |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$, (Note 5) | ±10 | | ±10 | | ±10 | | V | | |
| Supply Current | $T_A = 125^\circ\text{C}$ | 2.6 | 4.0 | | | | | mA | | |
| Supply Voltage Rejection Ratio | $\pm 12\text{V} \leq V_S \leq \pm 15\text{V}$ | 60 | | 60 | | 60 | | dB | | |

Note 1: The maximum junction temperature of the LM102 is 150°C, while that of the LM202 is 100°C and that of the LM302 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16 inch thick epoxy glass board with ten, 0.03 inch wide, 2 ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

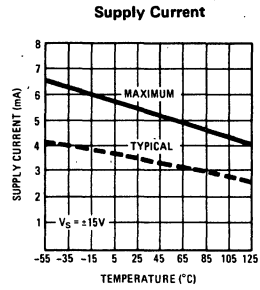
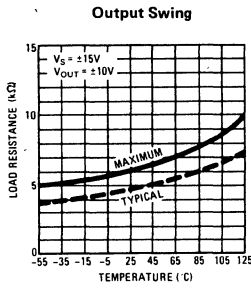
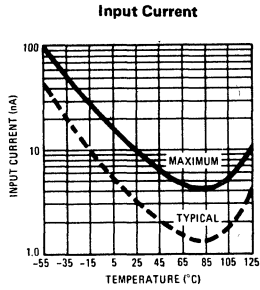
Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: Continuous short circuit for the LM102 and LM202 is allowed for case temperatures to 125°C and ambient temperatures to 70°C. For the LM302, continuous short circuit is allowed for 70°C case or 55°C ambient temperature. It is necessary to insert a resistor greater than 2 k Ω in series with the input when the amplifier is driven from low impedance sources to prevent damage when the output is shorted.

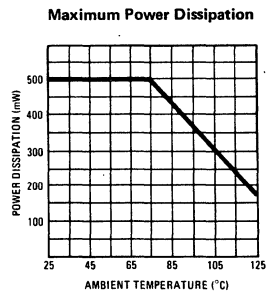
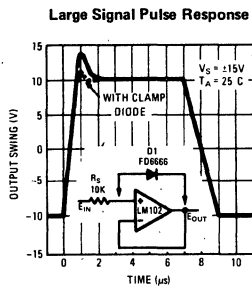
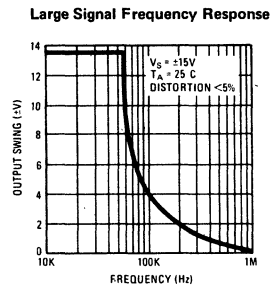
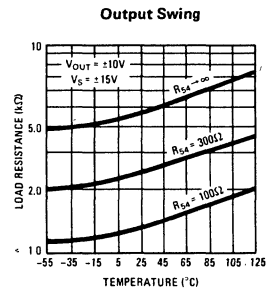
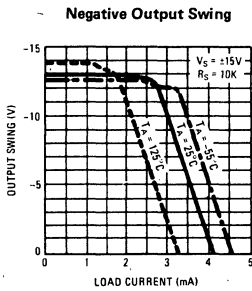
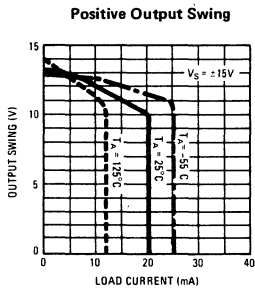
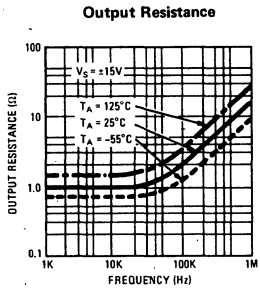
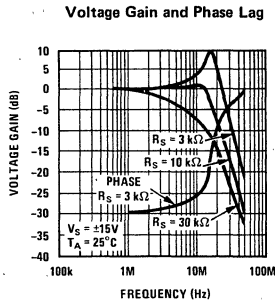
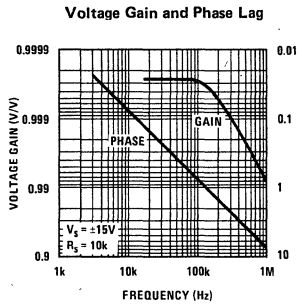
Note 4: These specifications apply for $\pm 12\text{V} \leq V_S \leq \pm 15\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ for the LM102, $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ for the LM202, and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ for the LM302 unless otherwise specified.

Note 5: Increased output swing under load can be obtained by connecting an external resistor between the booster and V^- terminals. See curve.

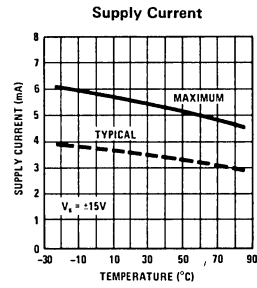
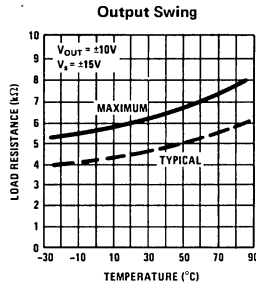
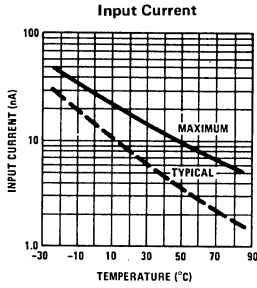
Guaranteed Performance Characteristics LM102



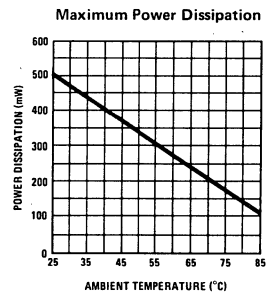
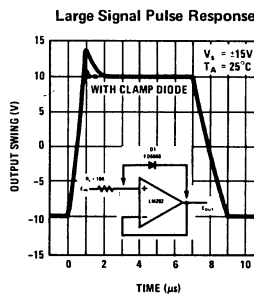
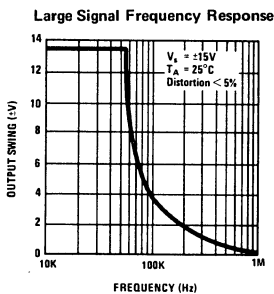
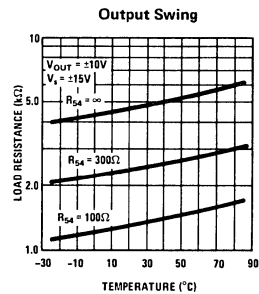
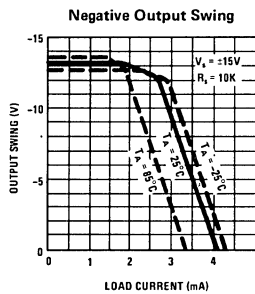
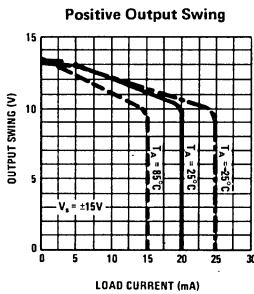
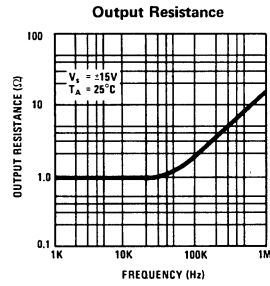
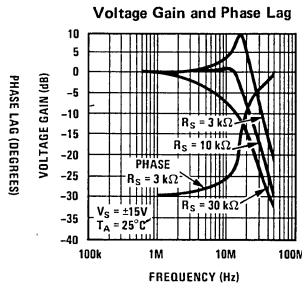
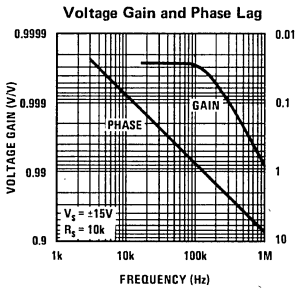
Typical Performance Characteristics LM102



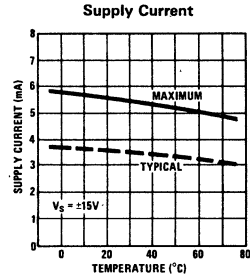
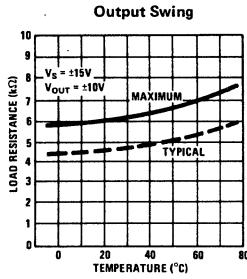
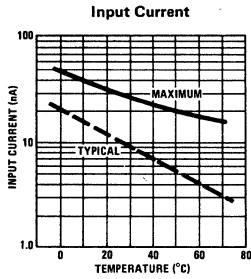
Guaranteed Performance Characteristics LM202



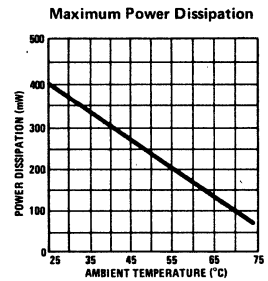
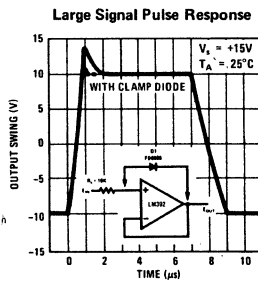
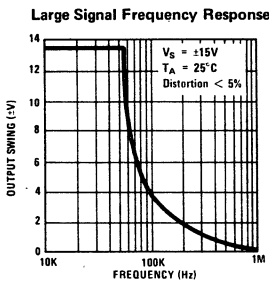
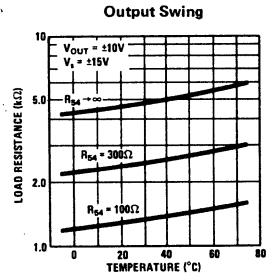
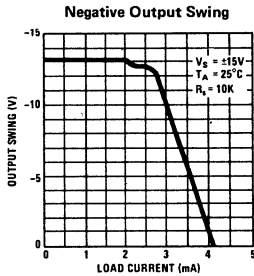
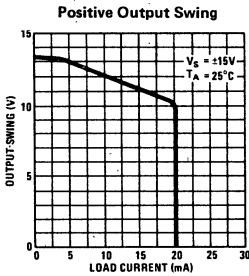
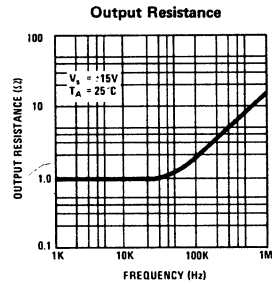
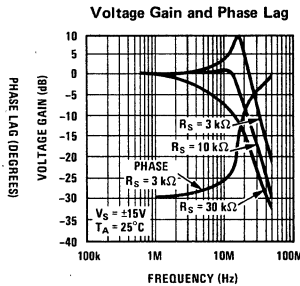
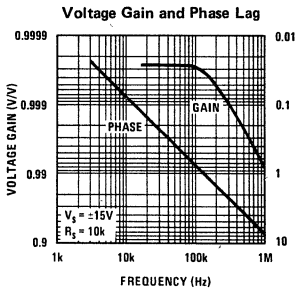
Typical Performance Characteristics LM202



Guaranteed Performance Characteristics LM302



Typical Performance Characteristics LM302



LM107/LM207/LM307 Operational Amplifiers

General Description

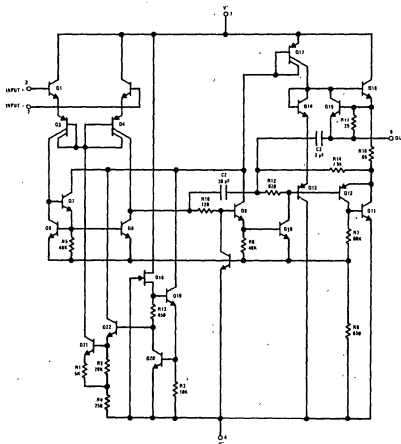
The LM107 series are complete, general purpose operational amplifiers, with the necessary frequency compensation built into the chip. Advanced processing techniques make the input currents a factor of ten lower than industry standards like the 709. Yet, they are a direct, plug-in replacement for the 709, LM101, LM101A and 741.

- Offset voltage 3 mV maximum over temperature
- Input current 100 nA maximum over temperature
- Offset current 20 nA maximum over temperature
- Guaranteed drift characteristics

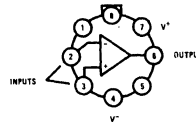
The LM107 series offers the features of the LM101, which makes its application nearly fool-proof. In addition, the device provides better accuracy and lower noise in high impedance circuitry. The low input currents also make it particularly well suited for long interval integrators or timers, sample and hold circuits and low frequency waveform generators. Further, replacing circuits where matched transistor pairs buffer the inputs of conventional IC op amps, it can give lower offset voltage and drift at a lower cost.

The LM107 is guaranteed over a -55°C to $+125^{\circ}\text{C}$ temperature range, the LM207 from -25°C to $+85^{\circ}\text{C}$ and the LM307 from 0°C to $+70^{\circ}\text{C}$.

Schematic ** and Connection Diagrams



Metal Can Package

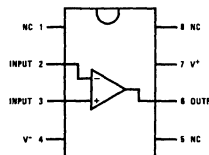


Note: Pin 4 connected to case.

TOP VIEW

Order Number **LM107H, LM207H**
or **LM307H**
See NS Package H08C

Dual-In-Line Package

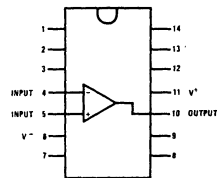


Note: Pin 4 connected to bottom of package.

TOP VIEW

Order Number **LM107J,**
LM207J or **LM307J**
See NS Package J08A
Order Number **LM307N**
See NS Package N08A

Dual-In-Line Package



Note: Pin 6 connected to bottom of package.

TOP VIEW

Order Number **LM107J-14,**
LM207J-14 or **LM307J-14**
See NS Package J14A

**Pin connections shown are for metal can.

Absolute Maximum Ratings

| | LM107/LM207 | LM307 | | T _{MIN} | T _{MAX} |
|--|---|-----------------|-------|------------------|------------------|
| Supply Voltage | ±22V | ±18V | | | |
| Power Dissipation (Note 1) | 500 mW | 500 mW | | | |
| Differential Input Voltage | ±30V | ±30V | LM107 | -55°C | +125°C |
| Input Voltage (Note 2) | ±15V | ±15V | LM207 | -25°C | +85°C |
| Output Short-Circuit Duration | Indefinite | Indefinite | LM307 | 0°C | +70°C |
| Operating Temperature Range | (LM107) -55°C to +125°C (LM207) -25°C to +85°C | 0°C to +70°C | | | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | | | |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | | | |

Electrical Characteristics (Note 3)

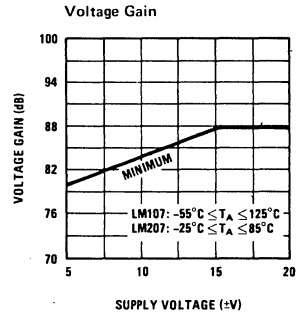
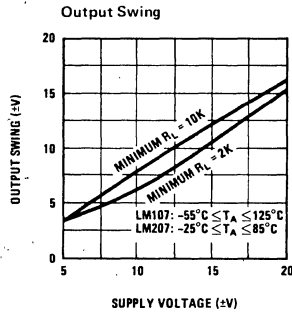
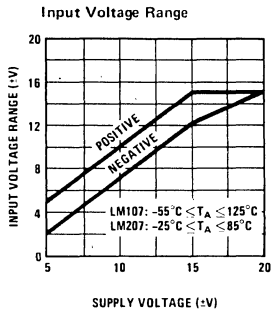
| PARAMETER | CONDITIONS | LM107/LM207 | | | LM307 | | | UNITS |
|---|--|-------------|------|-----|-------|-----|-----|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | T _A = 25°C, R _S ≤ 50 kΩ | | 0.7 | 2.0 | | 2.0 | 7.5 | mV |
| Input Offset Current | T _A = 25°C | | 1.5 | 10 | | 3.0 | 50 | nA |
| Input Bias Current | T _A = 25°C | | 30 | 75 | | 70 | 250 | nA |
| Input Resistance | T _A = 25°C | 1.5 | 4.0 | | 0.5 | 2.0 | | MΩ |
| Supply Current | T _A = 25°C | | | | | | | |
| | V _S = ±20V | | 1.8 | 3.0 | | | | mA |
| | V _S = ±15V | | | | 1.8 | 3.0 | | mA |
| Large Signal Voltage Gain | T _A = 25°C, V _S = ±15V V _{OUT} = ±10V, R _L ≥ 2 kΩ | 50 | 160 | | 25 | 160 | | V/mV |
| Input Offset Voltage | R _S ≤ 50 kΩ | | | 3.0 | | | 10 | mV |
| Average Temperature Coefficient of Input Offset Voltage | | | 3.0 | 15 | 6.0 | 30 | | μV/°C |
| Input Offset Current | | | | 20 | | | 70 | nA |
| Average Temperature Coefficient of Input Offset Current | 25°C ≤ T _A ≤ T _{MAX} T _{MIN} ≤ T _A ≤ 25°C | | 0.01 | 0.1 | 0.01 | 0.3 | | nA/°C |
| | | | 0.02 | 0.2 | 0.02 | 0.6 | | nA/°C |
| Input Bias Current | | | | 100 | | | 300 | nA |
| Supply Current | T _A = +125°C, V _S = ±20V | | 1.2 | 2.5 | | | | mA |
| Large Signal Voltage Gain | V _S = ±15V, V _{OUT} = ±10V R _L ≥ 2 kΩ | 25 | | | 15 | | | V/mV |
| Output Voltage Swing | V _S = ±15V | | | | | | | |
| | R _L = 10 kΩ | ±12 | ±14 | | ±12 | ±14 | | V |
| | R _L = 2 kΩ | ±10 | ±13 | | ±10 | ±13 | | V |
| Input Voltage Range | V _S = ±20V | ±15 | | | | | | V |
| | V _S = ±15V | | | | ±12 | | | V |
| Common Mode Rejection Ratio | R _S ≤ 50 kΩ | 80 | 96 | | 70 | 90 | | dB |
| Supply Voltage Rejection Ratio | R _S ≤ 50 kΩ | 80 | 96 | | 70 | 96 | | dB |

Note 1: The maximum junction temperature of the LM107 is 150°C, and the LM207/LM307 is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

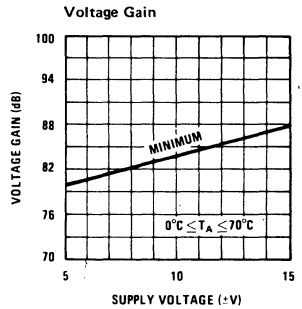
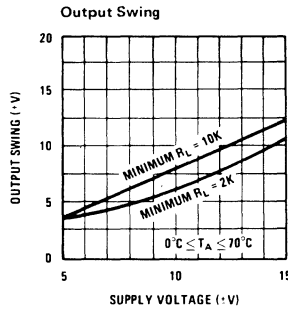
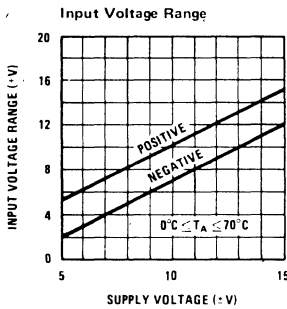
Note 2: For supply voltages less than -15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for ±5V ≤ V_S ≤ +20V and -55°C ≤ T_A ≤ +125°C for the LM107 or -25°C ≤ T_A ≤ +85°C for the LM207, and 0°C ≤ T_A ≤ +70°C and ±5V ≤ V_S ≤ ±15V for the LM307 unless otherwise specified.

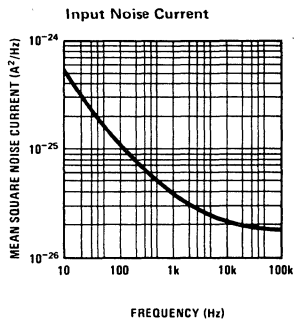
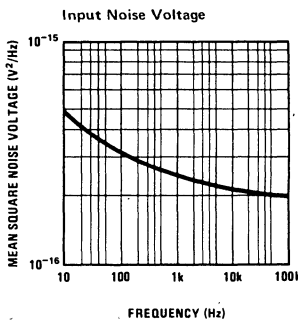
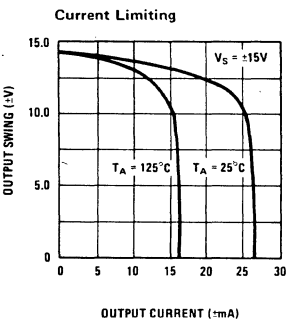
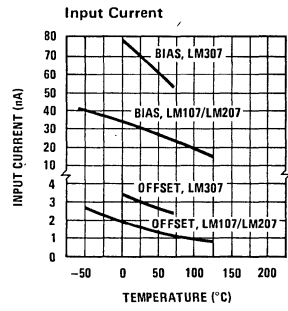
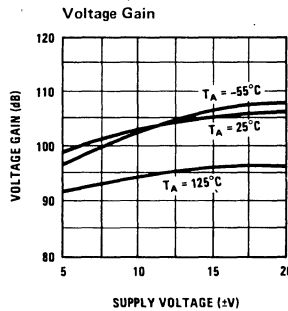
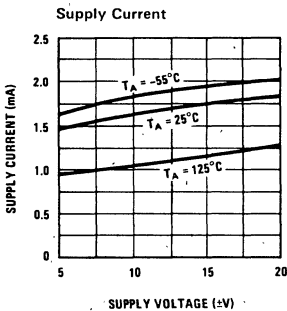
Guaranteed Performance Characteristics LM107/LM207



Guaranteed Performance Characteristics LM307

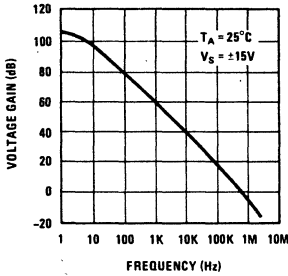


Typical Performance Characteristics

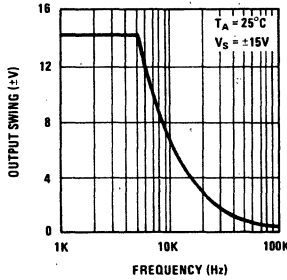


Typical Performance Characteristics (Continued)

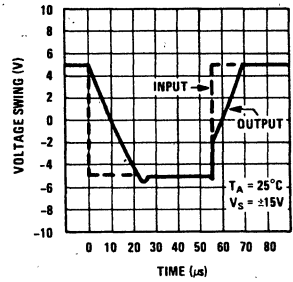
Open Loop Frequency Response



Large Signal Frequency Response

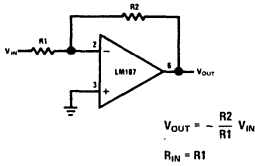


Voltage Follower Pulse Response

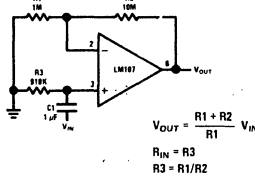


Typical Applications**

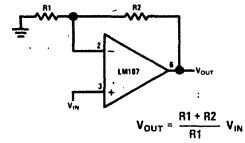
Inverting Amplifier



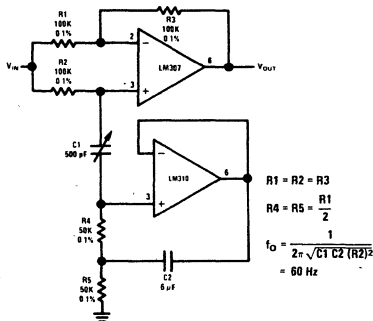
Non-Inverting AC Amplifier



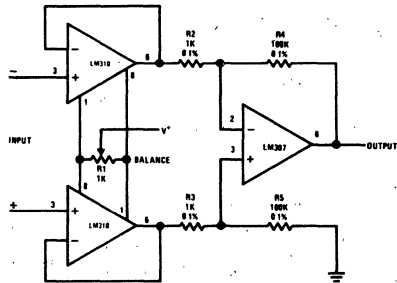
Non-Inverting Amplifier



Tunable Notch Filter



Differential Input Instrumentation Amplifier



**Pin connections shown are for metal can.

LM108/LM208/LM308 Operational Amplifiers

General Description

The LM108 series are precision operational amplifiers having specifications a factor of ten better than FET amplifiers over a -55°C to $+125^{\circ}\text{C}$ temperature range. Selected units are available with offset voltages less than 1.0 mV and drifts less than $5\mu\text{V}/^{\circ}\text{C}$, again over the military temperature range. This makes it possible to eliminate offset adjustments, in most cases, and obtain performance approaching chopper stabilized amplifiers.

The devices operate with supply voltages from $\pm 2\text{V}$ to $\pm 20\text{V}$ and have sufficient supply rejection to use unregulated supplies. Although the circuit is interchangeable with and uses the same compensation as the LM101A, an alternate compensation scheme can be used to make it particularly insensitive to power supply noise and to make supply bypass capacitors unnecessary. Outstanding characteristics include:

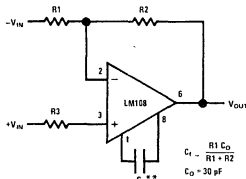
- Maximum input bias current of 3.0 nA over temperature
- Offset current less than 400 pA over temperature
- Supply current of only 300 μA , even in saturation
- Guaranteed drift characteristics

The low current error of the LM108 series makes possible many designs that are not practical with conventional amplifiers. In fact, it operates from $10\text{M}\Omega$ source resistances, introducing less error than devices like the 709 with $10\text{k}\Omega$ sources. Integrators with drifts less than $500\mu\text{V}/\text{sec}$ and analog time delays in excess of one hour can be made using capacitors no larger than $1\mu\text{F}$.

The LM108 is guaranteed from -55°C to $+125^{\circ}\text{C}$, the LM208 from -25°C to $+85^{\circ}\text{C}$, and the LM308 from 0°C to $+70^{\circ}\text{C}$.

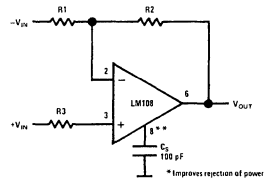
Compensation Circuits

Standard Compensation Circuit



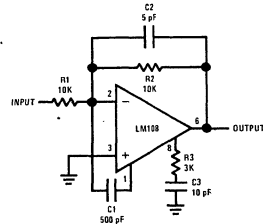
** Bandwidth and slew rate are proportional to $1/C_0$ or $1/C_0^2$.

Alternate* Frequency Compensation



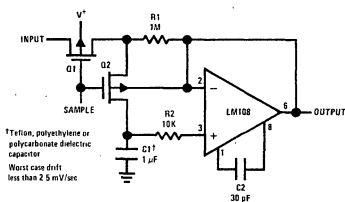
** Bandwidth and slew rate are proportional to $1/C_0$ or $1/C_0^2$.

Feedforward Compensation

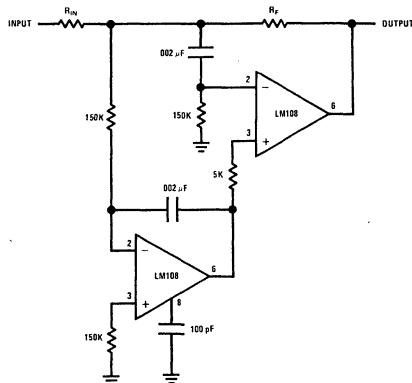


Typical Applications

Sample and Hold



High Speed Amplifier with Low Drift and Low Input Current



Absolute Maximum Ratings

| | LM108/LM208 | LM308 |
|--|-----------------|-----------------|
| Supply Voltage | ±20V | ±18V |
| Power Dissipation (Note 1) | 500 mW | 500 mW |
| Differential Input Current (Note 2) | ±10 mA | ±10 mA |
| Input Voltage (Note 3) | ±15V | ±15V |
| Output Short-Circuit Duration | Indefinite | Indefinite |
| Operating Temperature Range (LM108) | -55°C to +125°C | 0°C to +70°C |
| (LM208) | -25°C to +85°C | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM108/LM208 | | | LM308 | | | UNITS |
|---|--|-------------|------|-----|-------|-----|-----|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 0.7 | 2.0 | | 2.0 | 7.5 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 0.05 | 0.2 | | 0.2 | 1 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 0.8 | 2.0 | | 1.5 | 7 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 30 | 70 | | 10 | 40 | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 0.3 | 0.6 | | 0.3 | 0.8 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L \geq 10\text{ k}\Omega$ | 50 | 300 | | 25 | 300 | | V/mV |
| Input Offset Voltage | | | | 3.0 | | | 10 | mV |
| Average Temperature Coefficient of Input Offset Voltage | | | 3.0 | 15 | | 6.0 | 30 | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | | | | 0.4 | | | 1.5 | nA |
| Average Temperature Coefficient of Input Offset Current | | | 0.5 | 2.5 | | 2.0 | 10 | $\text{pA}/^\circ\text{C}$ |
| Input Bias Current | | | | 3.0 | | | 10 | nA |
| Supply Current | $T_A = 125^\circ\text{C}$ | | 0.15 | 0.4 | | | | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L \geq 10\text{ k}\Omega$ | 25 | | | 15 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ | ±13 | ±14 | | ±13 | ±14 | | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±13.5 | | | ±14 | | | V |
| Common-Mode Rejection Ratio | | 85 | 100 | | 80 | 100 | | dB |
| Supply Voltage Rejection Ratio | | 80 | 96 | | 80 | 96 | | dB |

Note 1: The maximum junction temperature of the LM108 is 150°C, for the LM208, 100°C and for the LM308, 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

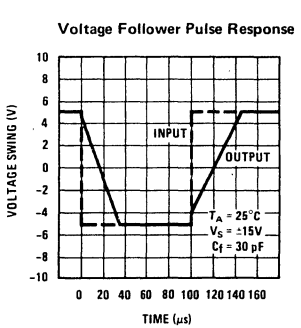
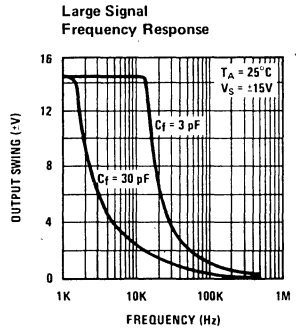
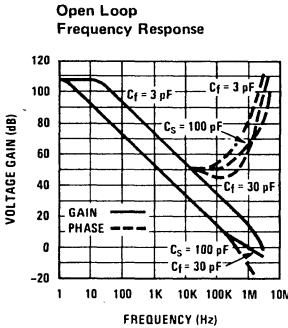
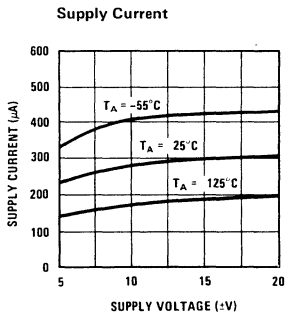
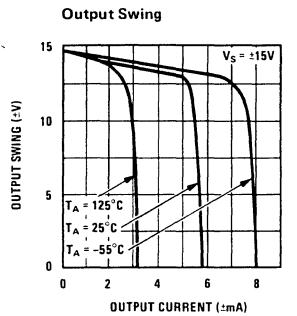
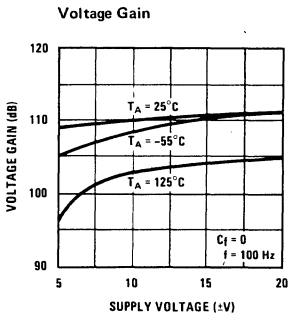
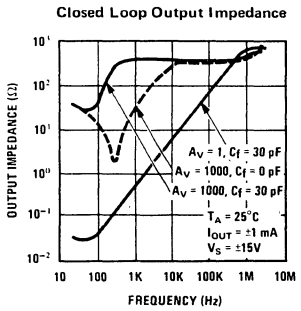
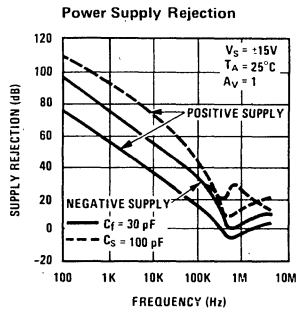
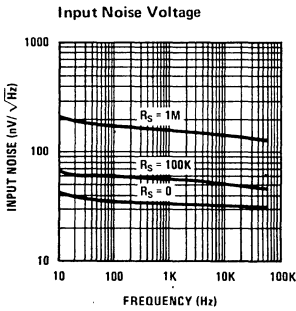
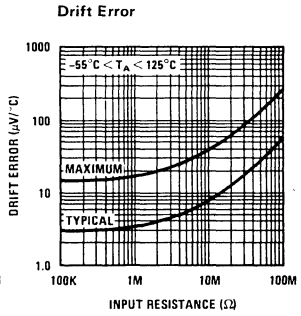
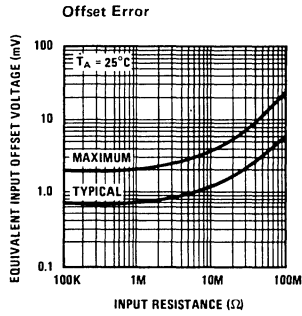
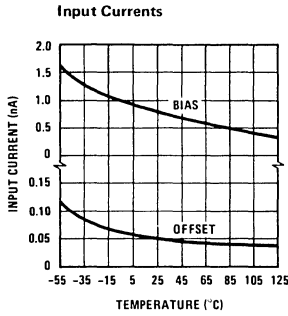
Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LM208, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$, and for the LM308 they are limited to $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$.

Typical Performance Characteristics LM108/LM208

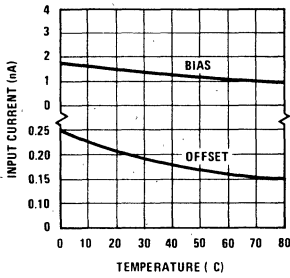
LM108/LM208/LM308



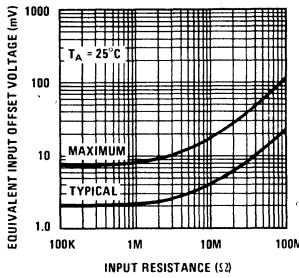
3

Typical Performance Characteristics LM308

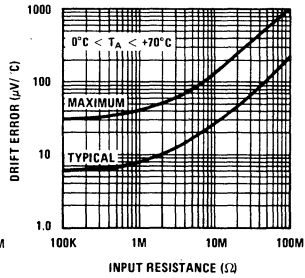
Input Currents



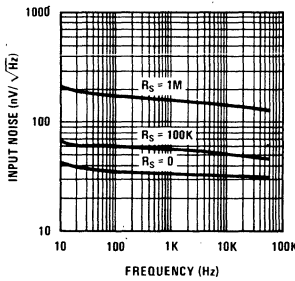
Offset Error



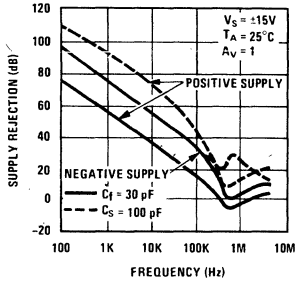
Drift Error



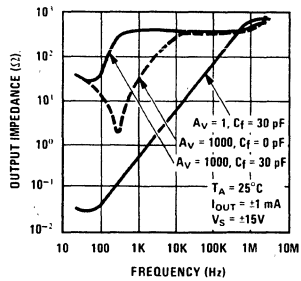
Input Noise Voltage



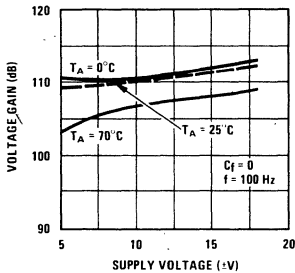
Power Supply Rejection



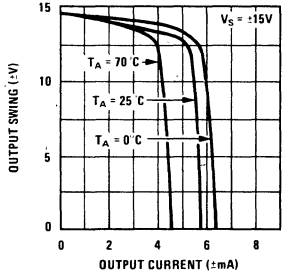
Closed Loop Output Impedance



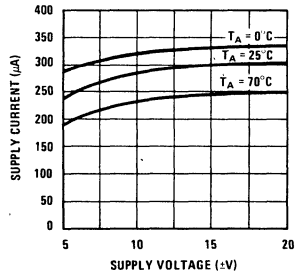
Voltage Gain



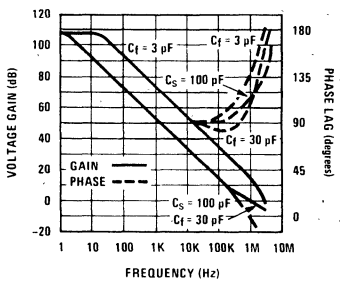
Output Swing



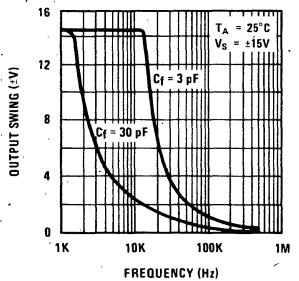
Supply Current



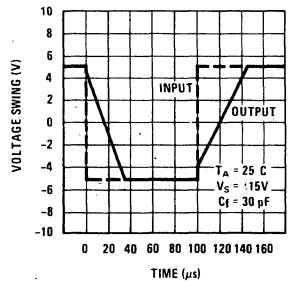
Open Loop Frequency Response



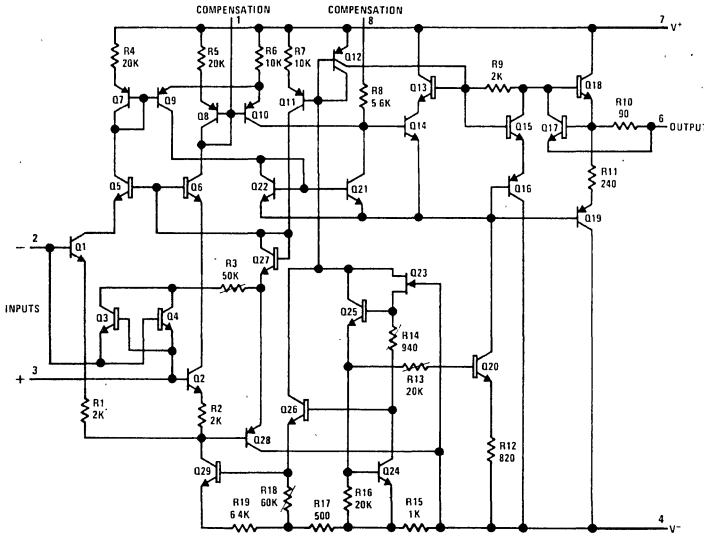
Large Signal Frequency Response



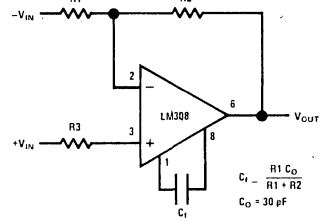
Voltage Follower Pulse Response



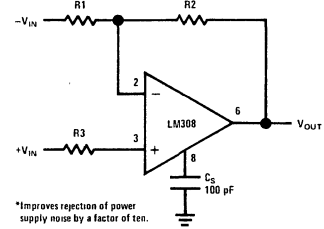
Schematic Diagram and Compensation Circuits



Standard Compensation Circuit



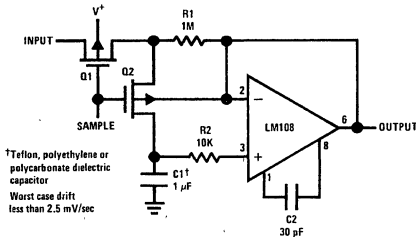
Alternate* Frequency Compensation



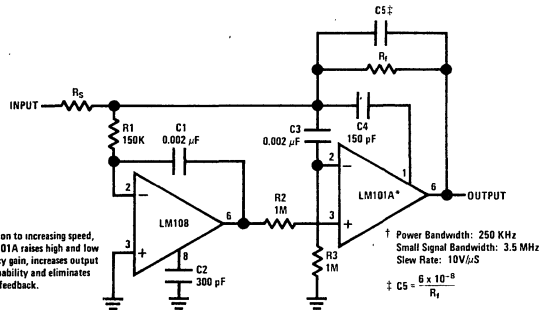
*Improves rejection of power supply noise by a factor of ten.

Typical Applications (Continued)

Sample and Hold

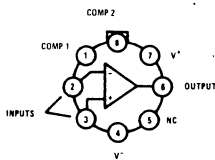


Fast† Summing Amplifier



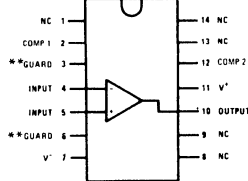
Connection Diagrams

Metal Can Package



Note: Pin 4 connected to case.

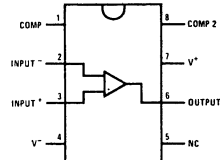
Dual-In-Line Package



Note: Pin 7 connected to bottom of package.

TOP VIEW

Dual-In-Line Package



TOP VIEW

Order Number LM108H
LM208H or LM308H
See NS Package H08C

Order Number LM108J,
LM208J or LM308J
See NS Package J14A

Order Number LM108J-8,
LM208J-8 or LM308J-8
See NS Package J08A
Order Number LM308N
See NS Package N08B

*Pin connections shown on schematic diagram are for TO-5 package.
**Unused pin (no internal connection) to allow for input anti-leakage guard ring on printed circuit board layout.



National Semiconductor

Operational Amplifiers/Buffers

LM108A/LM208A/LM308A, LM308A-1, LM308A-2 Operational Amplifiers

General Description

The LM108/LM108A series are precision operational amplifiers having specifications about a factor of ten better than FET amplifiers over their operating temperature range. In addition to low input currents, these devices have extremely low offset voltage, making it possible to eliminate offset adjustments, in most cases, and obtain performance approaching chopper stabilized amplifiers.

The devices operate with supply voltages from $\pm 2V$ to $\pm 18V$ and have sufficient supply rejection to use unregulated supplies. Although the circuit is interchangeable with and uses the same compensation as the LM101A, an alternate compensation scheme can be used to make it particularly insensitive to power supply noise and to make supply bypass capacitors unnecessary. Outstanding characteristics include:

- Offset voltage guaranteed less than 0.5 mV
- Maximum input bias current of 3.0 nA over temperature

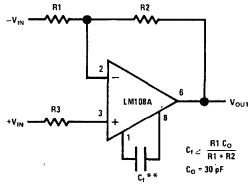
- Offset current less than 400 pA over temperature
- Supply current of only 300 μA , even in saturation
- Guaranteed 5 $\mu V/^\circ C$ drift.
- Guaranteed 1 $\mu V/^\circ C$ for LM308A-1

The low current error of the LM108A series makes possible many designs that are not practical with conventional amplifiers. In fact, it operates from 10 M Ω source resistances, introducing less error than devices like the 709 with 10 k Ω sources. Integrators with drifts less than 500 $\mu V/sec$ and analog time delays in excess of one hour can be made using capacitors no larger than 1 μF .

The LM208A is identical to the LM108A, except that the LM208A has its performance guaranteed over a $-25^\circ C$ to $85^\circ C$ temperature range, instead of $-55^\circ C$ to $125^\circ C$. The LM308A devices have slightly-relaxed specifications and performance guaranteed over a $0^\circ C$ to $70^\circ C$ temperature range.

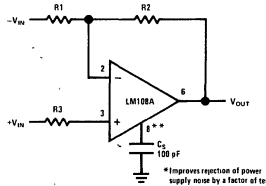
Compensation Circuits

Standard Compensation Circuit



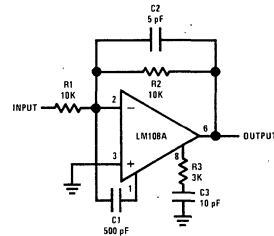
** Bandwidth and slew rate are proportional to $1/C_1$ or $1/C_2$

Alternate* Frequency Compensation



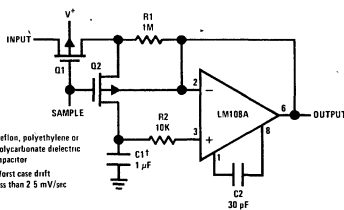
** Bandwidth and slew rate are proportional to $1/C_1$ or $1/C_2$

Feedforward Compensation

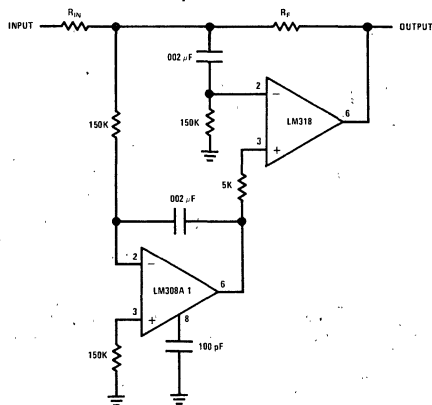


Typical Applications

Sample and Hold



High Speed Amplifier with Low Drift and Low Input Current



LM108A/LM208A Absolute Maximum Ratings

| | | |
|--------------------------------------|--------|----------------|
| Supply Voltage | | ±20V |
| Power Dissipation (Note 1) | | 500 mW |
| Differential Input Current (Note 2) | | ±10 mA |
| Input Voltage (Note 3) | | ±15V |
| Output Short-Circuit Duration | | Indefinite |
| Operating Temperature Range | LM108A | -55°C to 125°C |
| | LM208A | -25°C to 85°C |
| Storage Temperature Range | | -65°C to 150°C |
| Lead Temperature (Soldering, 10 sec) | | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|-------|------|-----|------------------------------|
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 0.3 | 0.5 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 0.05 | 0.2 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 0.8 | 2.0 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 30 | 70 | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 0.3 | 0.6 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}, R_L \geq 10\text{ k}\Omega$ | 80 | 300 | | V/mV |
| Input Offset Voltage | | | | 1.0 | mV |
| Average Temperature Coefficient of Input Offset Voltage | | | 1.0 | 5.0 | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | | | | 0.4 | nA |
| Average Temperature Coefficient of Input Offset Current | | | 0.5 | 2.5 | $\text{pA}/^\circ\text{C}$ |
| Input Bias Current | | | | 3.0 | nA |
| Supply Current | $T_A = +125^\circ\text{C}$ | | 0.15 | 0.4 | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, V_{OUT} = \pm 10\text{V}$ $R_L \geq 10\text{ k}\Omega$ | 40 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 10\text{ k}\Omega$ | ±13 | ±14 | | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±13.5 | | | V |
| Common Mode Rejection Ratio | | 96 | 110 | | dB |
| Supply Voltage Rejection Ratio | | 96 | 110 | | dB |

Note 1: The maximum junction temperature of the LM108A is 150°C, while that of the LM208A is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LM208A, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$.



LM308A, LM308A-1, LM308A-2

Absolute Maximum Ratings

| | |
|--------------------------------------|----------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Current (Note 2) | ±10 mA |
| Input Voltage (Note 3) | ±15V |
| Output Short-Circuit Duration | Indefinite |
| Operating Temperature Range | 0°C to 70°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|-----|------|------------------------------|
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 0.3 | 0.5 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 0.2 | 1 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 1.5 | 7 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 10 | 40 | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ | | 0.3 | 0.8 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V},$ $V_{OUT} = \pm 10\text{V}, R_L \geq 10\text{ k}\Omega$ | 80 | 300 | | V/mV |
| Input Offset Voltage | $V_S = \pm 15\text{V}, R_S = 100\Omega$ | | | | |
| LM308A | | | | 0.73 | mV |
| LM308A-1 | | | | 0.54 | mV |
| LM308A-2 | | | | 0.59 | mV |
| Average Temperature Coefficient of Input Offset Voltage | $V_S = \pm 15\text{V}, R_S = 100\Omega$ | | | | |
| LM308A | | | 2.0 | 5.0 | $\mu\text{V}/^\circ\text{C}$ |
| LM308A-1 | | | 0.6 | 1.0 | $\mu\text{V}/^\circ\text{C}$ |
| LM308A-2 | | | 1.3 | 2.0 | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | | | | 1.5 | nA |
| Average Temperature Coefficient of Input Offset Current | | | 2.0 | 10 | $\text{pA}/^\circ\text{C}$ |
| Input Bias Current | | | | 10 | nA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, V_{OUT} = \pm 10\text{V}$ $R_L \geq 10\text{ k}\Omega$ | 60 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 10\text{ k}\Omega$ | ±13 | ±14 | | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±14 | | | V |
| Common-Mode Rejection Ratio | | 96 | 110 | | dB |
| Supply Voltage Rejection Ratio | | 96 | 110 | | dB |

Note 1: The maximum junction temperature of the LM308A, LM308-1 and LM308-2 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 15\text{V}$ and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$, unless otherwise specified.

Application Hints

A very low drift amplifier poses some uncommon application and testing problems. Many sources of error can cause the apparent circuit drift to be much higher than would be predicted.

Thermocouple effects caused by temperature gradient across dissimilar metals are perhaps the worst offenders. Only a few degrees gradient can cause hundreds of microvolts of error. The two places this shows up, generally, are the package-to printed circuit board interface and temperature gradients across resistors. Keeping package leads short and the two input leads close together help greatly.

Resistor choice as well as physical placement is important for minimizing thermocouple effects. Carbon, oxide film and some metal film resistors can cause large thermocouple errors. Wirewound resistors of evenohm or manganin are best since they only generate about $2 \mu\text{V}/^\circ\text{C}$ referenced to copper. Of course, keeping the resistor ends at the same temperature is important. Generally, shielding a low drift stage electrically and thermally will yield good results.

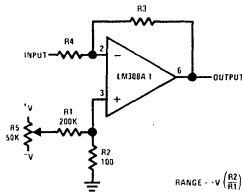
Resistors can cause other errors besides gradient generated voltages. If the gain setting resistors do not track with temperature a gain error will result. For example a gain of 1000 amplifier with a con-

stant 10 mV input will have a 10V output. If the resistors mismatch by 0.5% over the operating temperature range, the error at the output is 50 mV. Referred to input, this is a $50 \mu\text{V}$ error. All of the gain fixing resistor should be the same material.

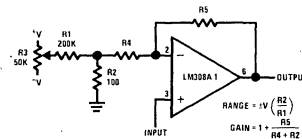
Offset balancing the LM308A-1 can be a problem since there is no easy offset adjustment incorporated into the circuit. These devices are selected for low drift with no offset adjustment to the internal circuitry, so any change of the internal currents will change the drift — probably for the worse. Offset adjustment must be done at the input. The three most commonly needed circuits are shown here.

Testing low drift amplifiers is also difficult. Standard drift testing technique such as heating the device in an oven and having the leads available through a connector, thermoprobe, or the soldering iron method — do not work: Thermal gradients cause much greater errors than the amplifier drift. Coupling microvolt signal through connectors is especially bad since the temperature difference across the connector can be 50°C or more. The device under test along with the gain setting resistor should be isothermal. The following circuit will yield good results if well constructed.

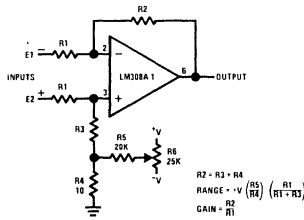
Offset Adjustment for Inverting Amplifiers



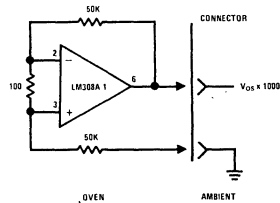
Offset Adjustment for Non-Inverting Amplifiers



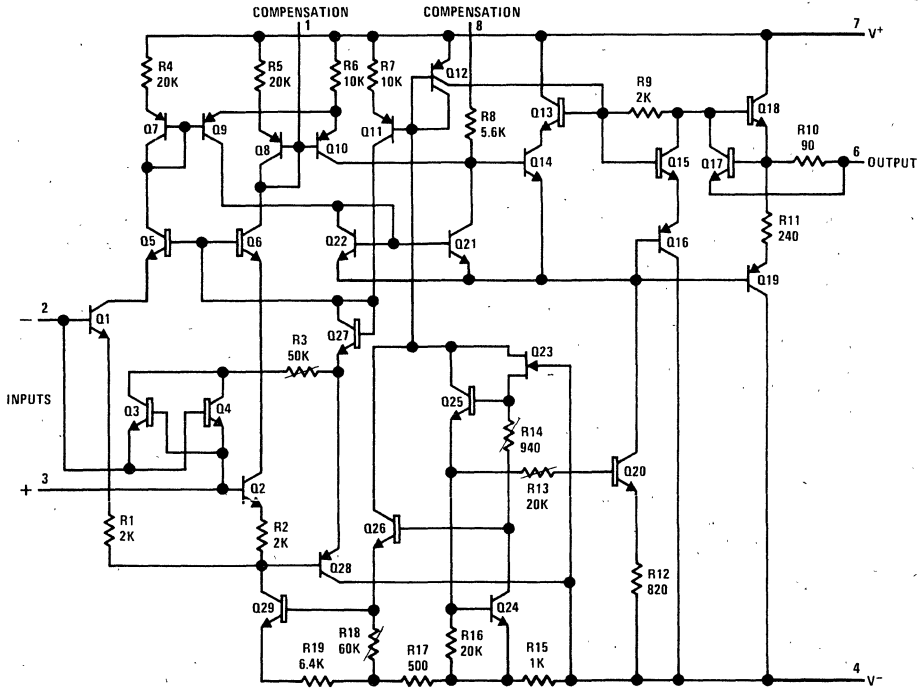
Offset Adjustment for Differential Amplifiers



Drift Measurement Circuit



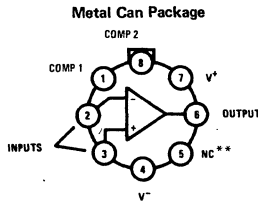
Schematic Diagram*



*Pin connections shown on schematic diagram refer to TO-5 package.

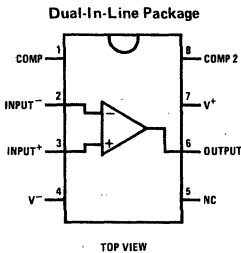
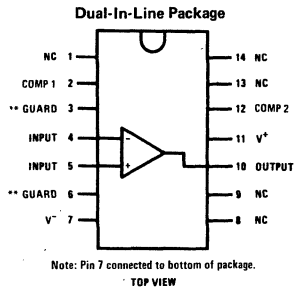
Connection Diagrams

Order Number LM108AH, LM208AH,
LM308AH, LM308AH-1 or LM308AH-2
See NS Package H08C



**Unused pin (no internal connection) to allow for input anti-leakage guard ring on printed circuit board layout.

Order Number LM108AJ, LM208AJ,
or LM308AJ
See NS Package J14A



Order Number LM108AJ-8,
LM208AJ-8 or LM308AJ-8
See NS Package J08A
Order Number LM208AN
or LM308AN
See NS Package N08B

**LH2108/LH2208/LH2308,
LH2108A/LH2208A/LH2308A Dual Super Beta
Op Amp**

general description

The LH2108A/LH2208A/LH2308A and LH2108/LH2208/LH2308 series of dual operational amplifiers are two LM108A or LM108 type op amps in a single hermetic package. Featuring all the same performance characteristics of the single device, these duals also offer closer thermal tracking, lower weight, reduced insertion cost, and smaller size than two single devices. For additional information see the LM108A or LM108 data sheet and National's Linear Application Handbook.

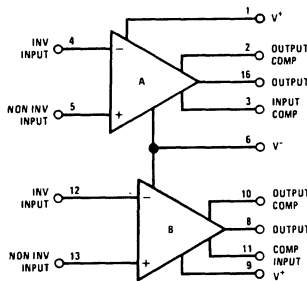
The LH2108A/LH2108 is specified for operation over the -55°C to +125°C military temperature range. The LH2208A/LH2208 is specified for operation over the -25°C to +85°C temperature

range. The LH2308A/LH2308 is specified for operation over the 0°C to +70°C temperature range.

features

- Low offset current 50 pA
- Low offset voltage 0.7 mV
- Low offset voltage LH2108A 0.3 mV
LH2108 0.7 mV
- Wide input voltage range ±15V
- Wide operating supply range ±3V to ±20V

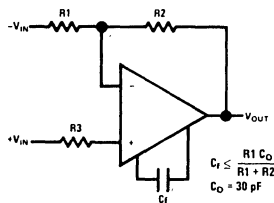
connection diagram



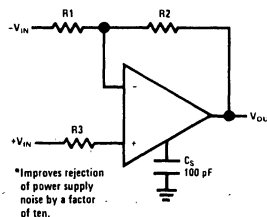
Order Number LH2108AD, LH2208AD,
LH2308AD, LH2108D, LH2208D,
or LH2308D
See Package D16C

auxiliary circuits

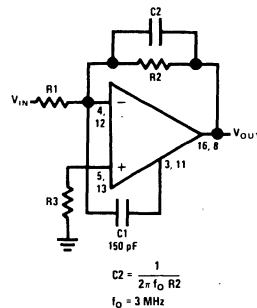
Standard Compensation Circuit



Alternate * Frequency Compensation



Feedforward Compensation



absolute maximum ratings

| | | | |
|-------------------------------------|------------|--------------------------------------|-----------------|
| Supply Voltage | ±20V | Operating Temperature Range | -55°C to +125°C |
| Power Dissipation (Note 1) | 500 mW | LH2108A/LH2108 | -25°C to +85°C |
| Differential Input Current (Note 2) | ±10 mA | LH2208A/LH2208 | 0°C to +70°C |
| Input Voltage (Note 3) | ±15V | LH2308A/LH2308 | -65°C to +150°C |
| Output Short Circuit Duration | Continuous | Storage Temperature Range | 300°C |
| | | Lead Temperature (Soldering, 10 sec) | |

electrical characteristics each side (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---|--|--------|--------|--------|----------------------------------|
| | | LH2108 | LH2208 | LH2308 | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | 2.0 | 2.0 | 7.5 | mV Max |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | 0.2 | 0.2 | 1.0 | nA Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 2.0 | 2.0 | 7.0 | nA Max |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 30 | 30 | 10 | M Ω Min |
| Supply Current | $T_A = 25^\circ\text{C}$ | 0.6 | 0.6 | 0.8 | mA Max |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = +15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L > 10\text{ k}\Omega$ | 50 | 50 | 25 | V/mV Min |
| Input Offset Voltage | | 3.0 | 3.0 | 10 | mV Max |
| Average Temperature Coefficient of Input Offset Voltage | | 15 | 15 | 30 | $\mu\text{V}/^\circ\text{C}$ Max |
| Input Offset Current | | 0.4 | 0.4 | 1.5 | nA Max |
| Average Temperature Coefficient of Input Offset Current | | 2.5 | 2.5 | 10 | $\text{pA}/^\circ\text{C}$ Max |
| Input Bias Current | | 3.0 | 3.0 | 10 | nA Max |
| Supply Current | $T_A = +125^\circ\text{C}$ | 0.4 | 0.4 | - | mA Max |
| Large Signal Voltage Gain | $V_S = +15\text{V}$, $V_{OUT} = +10\text{V}$ $R_L > 10\text{ k}\Omega$ | 25 | 25 | 15 | V/mV Min |
| Output Voltage Swing | $V_S = +15\text{V}$, $R_L = 10\text{ k}\Omega$ | ±13 | ±13 | ±13 | V Min |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±13.5 | ±13.5 | ±14 | V Min |
| Common Mode Rejection Ratio | | 85 | 85 | 80 | dB Min |
| Supply Voltage Rejection Ratio | | 80 | 80 | 80 | dB Min |

electrical characteristics each side (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---|--|---------|---------|---------|----------------------------------|
| | | LH2108A | LH2208A | LH2308A | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | 0.5 | 0.5 | 0.5 | mV Max |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | 0.2 | 0.2 | 1.0 | nA Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 2.0 | 2.0 | 7.0 | nA Max |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 30 | 30 | 10 | M Ω Min |
| Supply Current | $T_A = 25^\circ\text{C}$ | 0.6 | 0.6 | 0.8 | mA Max |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = +15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L > 10\text{ k}\Omega$ | 80 | 80 | 80 | V/mV Min |
| Input Offset Voltage | | 1.0 | 1.0 | 0.73 | mV Max |
| Average Temperature Coefficient of Input Offset Voltage | | 5 | 5 | 5 | $\mu\text{V}/^\circ\text{C}$ Max |
| Input Offset Current | | 0.4 | 0.4 | 1.5 | nA Max |
| Average Temperature Coefficient of Input Offset Current | | 2.5 | 2.5 | 10 | $\text{pA}/^\circ\text{C}$ Max |
| Input Bias Current | | 3.0 | 3.0 | 10 | nA Max |
| Supply Current | $T_A = +125^\circ\text{C}$ | 0.4 | 0.4 | - | mA Max |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = +10\text{V}$ $R_L > 10\text{ k}\Omega$ | 40 | 40 | 60 | V/mV Min |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ | ±13 | ±13 | ±13 | V Min |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±13.5 | ±13.5 | ±14 | V Min |
| Common Mode Rejection Ratio | | 96 | 96 | 96 | dB Min |
| Supply Voltage Rejection Ratio | | 96 | 96 | 96 | dB Min |

Note 1: The maximum junction temperature of the LH2108A/LH2108 is 150°C, while that of the LH2208A/LH2208 is 100°C and that of the LH2308A/LH2308 is 85°C. For operating devices in the flat package at elevated temperatures, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with 0.03-inch-wide, 2-ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} < V_S < \pm 20\text{V}$ and $-55^\circ\text{C} < T_A < 125^\circ\text{C}$, unless otherwise specified. With the LH2208A/LH2208, however, all temperature specifications are limited to $-25^\circ\text{C} < T_A < 85^\circ\text{C}$ and with the LH2308A/LH2308 for $\pm 5\text{V} < V_S < 15\text{V}$ and $0^\circ\text{C} < T_A < 70^\circ\text{C}$.

LM110/LM210/LM310 Voltage Follower

General Description

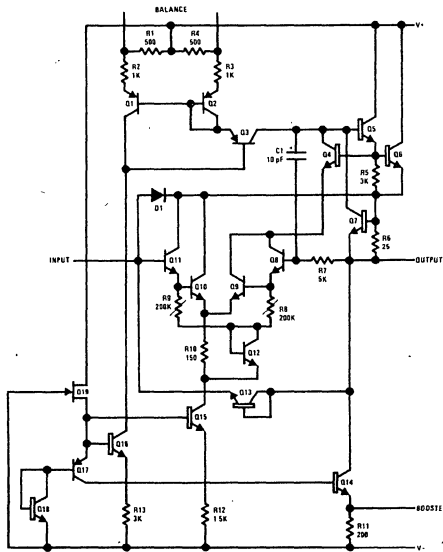
The LM110 series are monolithic operational amplifiers internally connected as unity-gain non-inverting amplifiers. They use super-gain transistors in the input stage to get low bias current without sacrificing speed. Directly interchangeable with 101, 741 and 709 in voltage follower applications, these devices have internal frequency compensation and provision for offset balancing. Outstanding characteristics include:

- Input current: 10 nA max. over temperature
- Small signal bandwidth: 20 MHz
- Slew rate: 30V/ μ s
- Supply voltage range: $\pm 5V$ to $\pm 18V$

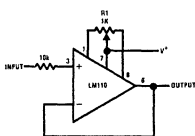
The LM110 series are useful in fast sample and hold circuits, active filters, or as general-purpose buffers. Further, the frequency response is enough better than standard IC amplifiers that the followers can be included in the feedback loop without introducing instability. They are plug-in replacements for the LM102 series voltage followers, offering lower offset voltage, drift, bias current and noise in addition to higher speed and wider operating voltage range.

The LM110 is specified over a temperature range $-55^{\circ}C \leq T_A \leq +125^{\circ}C$, the LM210 from $-25^{\circ}C \leq T_A \leq +85^{\circ}C$ and the LM310 from $0^{\circ}C \leq T_A \leq +70^{\circ}C$.

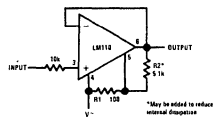
Schematic Diagram



Auxiliary Circuits

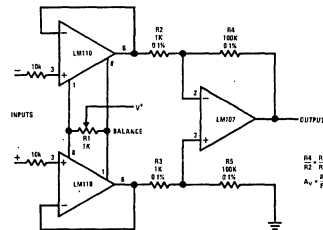


Offset Balancing Circuit

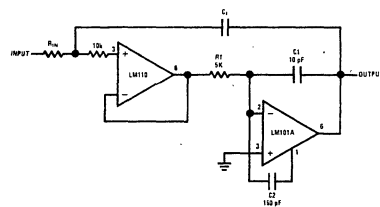


Increasing Negative Swing Under Load

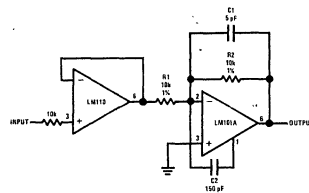
Typical Applications



Differential Input Instrumentation Amplifier



Fast Integrator with Low Input Current



Fast Inverting Amplifier with High Input Impedance

Absolute Maximum Ratings

| | |
|--|----------------------|
| Supply Voltage | ±18V |
| Power Dissipation (Note 1) | 500 mW |
| Input Voltage (Note 2) | ±15V |
| Output Short Circuit Duration (Note 3) | Indefinite |
| Operating Temperature Range | LM110 -55°C to 125°C |
| | LM210 -25°C to 85°C |
| | LM310 0°C to +70°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM110 | | | LM210 | | | LM310 | | | UNITS |
|--------------------------------|--|-----------|-----------|-----|-----------|-----------|-----------|-----------|-----|------------------------------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 1.5 | 4.0 | 1.5 | 4.0 | 2.5 | 7.5 | | mV | |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 1.0 | 3.0 | 1.0 | 3.0 | 2.0 | 7.0 | | nA | |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 10^{10} | 10^{12} | | 10^{10} | 10^{12} | 10^{10} | 10^{12} | | Ω | |
| Input Capacitance | | | 1.5 | | 1.5 | | 1.5 | | | pF | |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L = 8\text{ k}\Omega$ | 0.999 | 0.9999 | | 0.999 | 0.9999 | 0.999 | 0.9999 | | V/V | |
| Output Resistance | $T_A = 25^\circ\text{C}$ | | 0.75 | 2.5 | 0.75 | 2.5 | 0.75 | 2.5 | | Ω | |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 3.9 | 5.5 | 3.9 | 5.5 | 3.9 | 5.5 | | mA | |
| Input Offset Voltage | | | | 6.0 | | 6.0 | | 10 | | mV | |
| Offset Voltage | $-55^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ | | 6 | | 6 | | | | | $\mu\text{V}/^\circ\text{C}$ | |
| Temperature Drift | $T_A = 125^\circ\text{C}$ | | 12 | | 12 | | | | | $\mu\text{V}/^\circ\text{C}$ | |
| | $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ | | | | | | 10 | | | $\mu\text{V}/^\circ\text{C}$ | |
| Input Bias Current | | | | 10 | | 10 | | 10 | | nA | |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$ $R_L = 10\text{ k}\Omega$ | 0.999 | | | 0.999 | | 0.999 | | | V/V | |
| Output Voltage Swing (Note 5) | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ | ± 10 | | | ± 10 | | ± 10 | | | V | |
| Supply Current | $T_A = 125^\circ\text{C}$ | | 2.0 | 4.0 | 2.0 | 4.0 | | | | mA | |
| Supply Voltage Rejection Ratio | $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$ | 70 | 80 | | 70 | 80 | 70 | 80 | | dB | |

Note 1: The maximum junction temperature of the LM110 is 150°C, of the LM210 is 100°C, and of the LM310 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

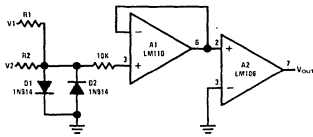
Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: Continuous short circuit for the LM110 and LM210 is allowed for case temperatures to 125°C and ambient temperatures to 70°C, and for the LM310, 70°C case temperature or 55°C ambient temperature. It is necessary to insert a resistor greater than 2k Ω in series with the input when the amplifier is driven from low impedance sources to prevent damage when the output is shorted.

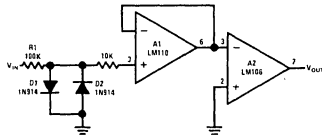
Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ for the LM110, $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ for the LM210, and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ for the LM310 unless otherwise specified.

Note 5: Increased output swing under load can be obtained by connecting an external resistor between the booster and V^- terminals. See curve.

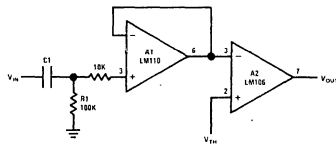
Typical Applications



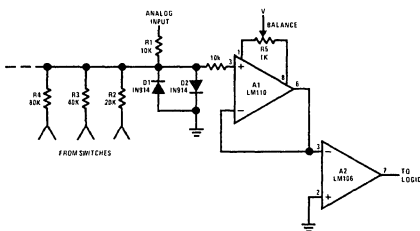
Comparator for Signals of Opposite Polarity



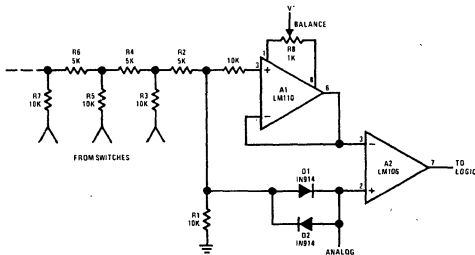
Zero Crossing Detector



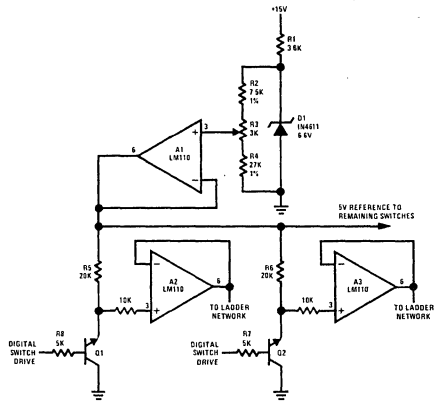
Comparator for AC Coupled Signals



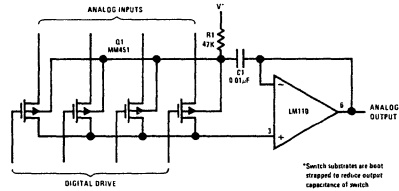
Comparator for A/D Converter Using a Binary-Weighted Network



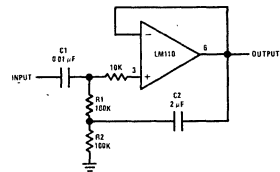
Comparator for A/D Converter Using a Ladder Network



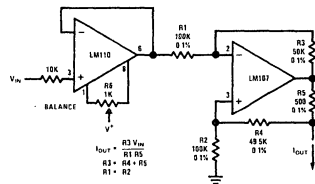
Driver for A/D Ladder Network



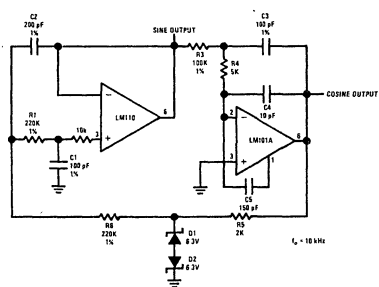
Buffer for Analog Switch*



High Input Impedance AC Amplifier

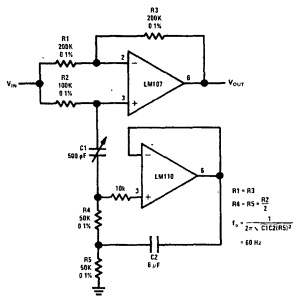


Bilateral Current Source

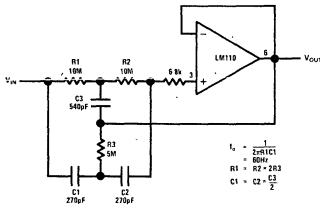


Sine Wave Oscillator

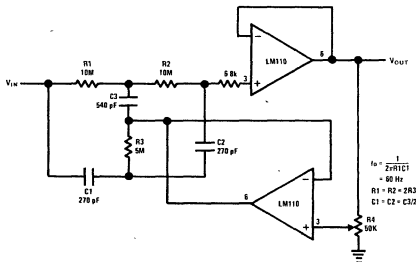
Typical Applications (Continued)



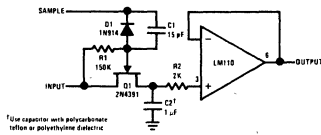
Tunable Notch Filter



High Q Notch Filter

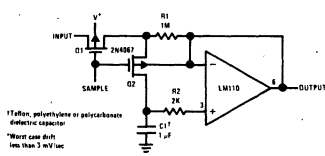


Adjustable Q Notch Filter



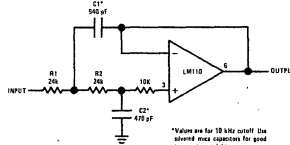
*Use capacitors with polycarbonate or polyethylene dielectric

Sample and Hold



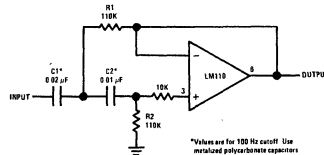
*FETs, polyethylene or polycarbonate dielectric capacitor
 *Input bias current less than 3 nV/dec

Low Drift Sample and Hold*



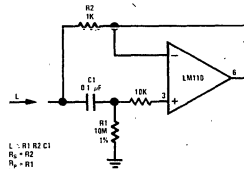
*Values are for 10 kHz cutoff. Use matched mica capacitors for good temperature stability

Low Pass Active Filter

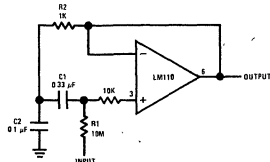


*Values are for 100 Hz cutoff. Use matched polycarbonate capacitors for good temperature stability

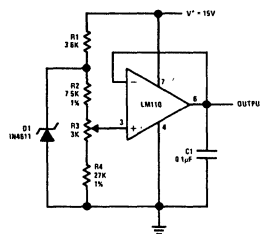
High Pass Active Filter



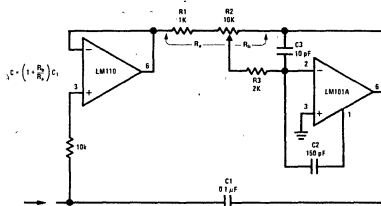
Simulated Inductor



Bandpass Filter

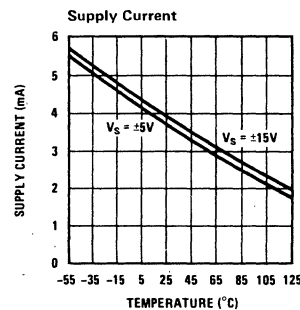
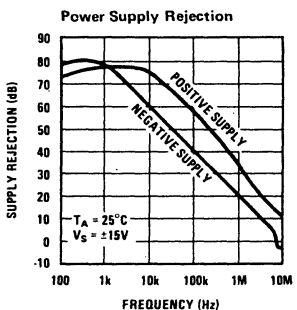
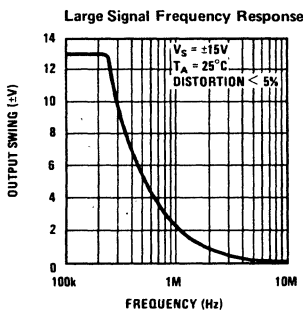
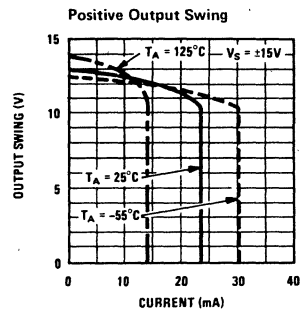
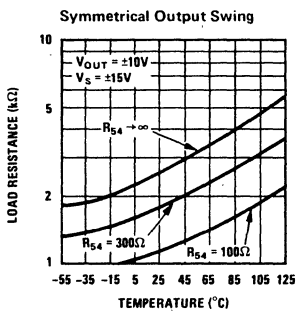
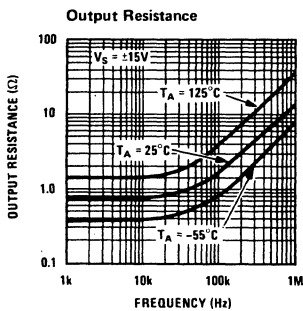
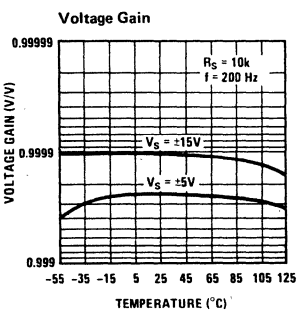
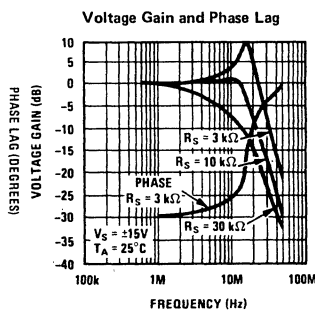
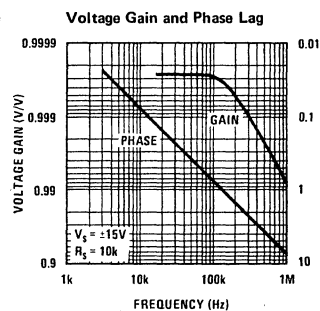
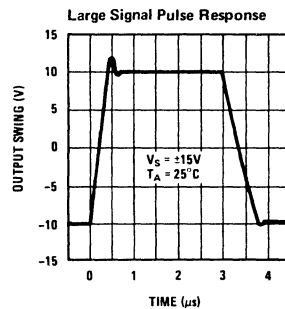
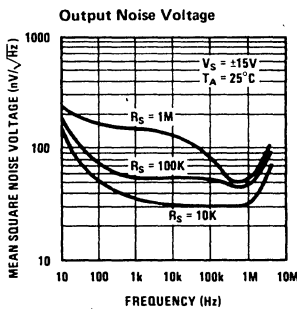
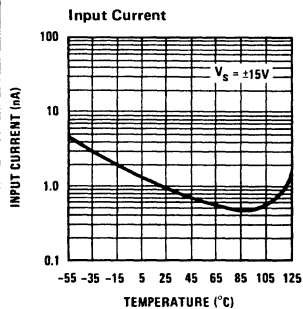


Buffered Reference Source

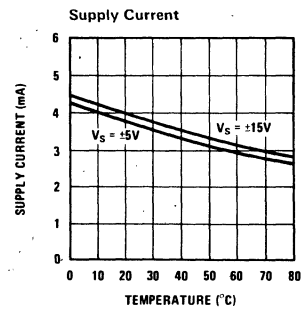
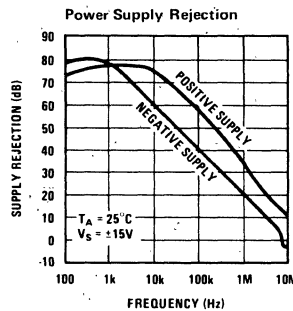
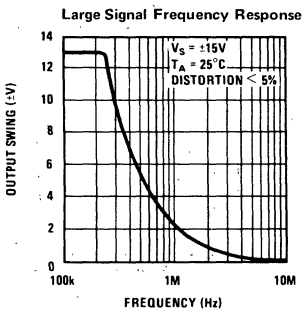
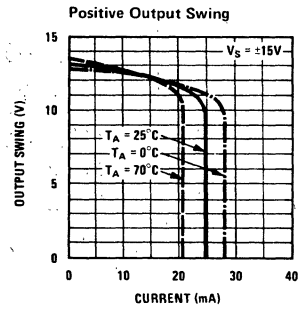
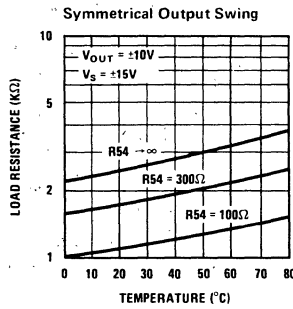
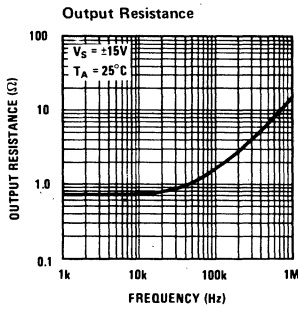
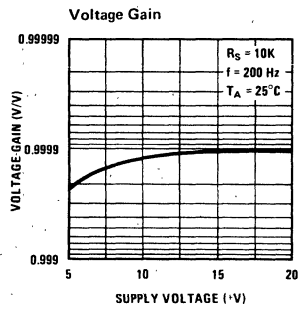
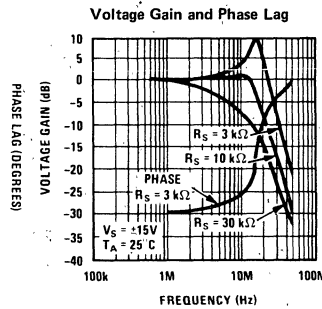
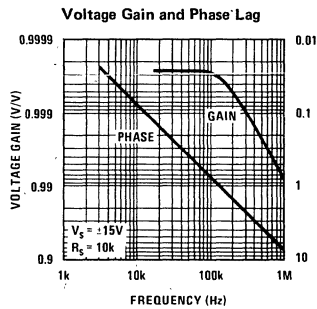
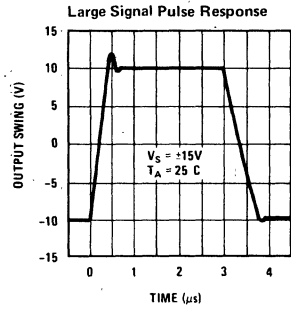
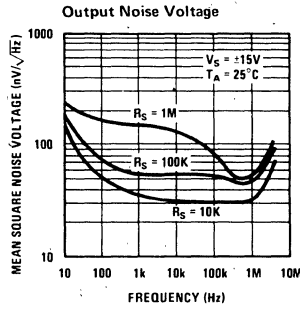
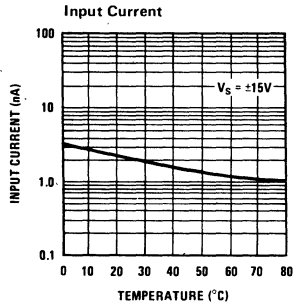


Variable Capacitance Multiplier

Typical Performance Characteristics (LM110/LM210)

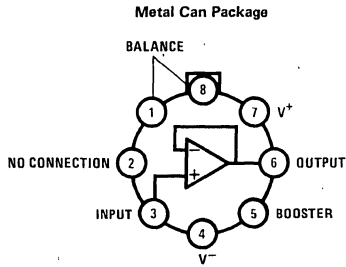


Typical Performance Characteristics (LM310)



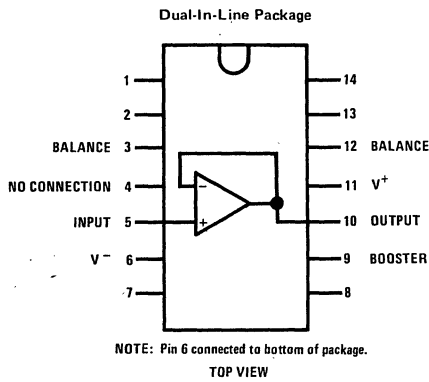
Connection Diagrams

LM110/LM210/LM310

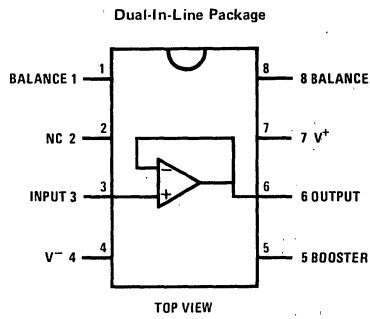


NOTE: Pin 4 connected to case.
TOP VIEW

Order Number LM110H, LM210H
or LM310H
See NS Package H08C



Order Number LM110J, LM210J
or LM310J
See NS Package J14A



Order Number LM310N
See NS Package N08B

Order Number LM310J-8
See NS Package J08A

3



**National
Semiconductor**

Operational Amplifiers/Buffers

LM112/LM212/LM312 Operational Amplifiers

General Description

The LM112 series are micropower operational amplifiers with very low offset-voltage and input-current errors—at least a factor of ten better than FET amplifiers over a -55°C to $+125^{\circ}\text{C}$ temperature range. Similar to the LM108 series, that also use supergain transistors, they differ in that they include internal frequency compensation and have provisions for offset adjustment with a single potentiometer.

These amplifiers will operate on supply voltages of $\pm 2\text{V}$ to $\pm 20\text{V}$, drawing a quiescent current of only $300\ \mu\text{A}$. Performance is not appreciably affected over this range of voltages, so operation from unregulated power sources is easily accomplished. They can also be run from a single supply like the 5V used for digital circuits. Some noteworthy features are:

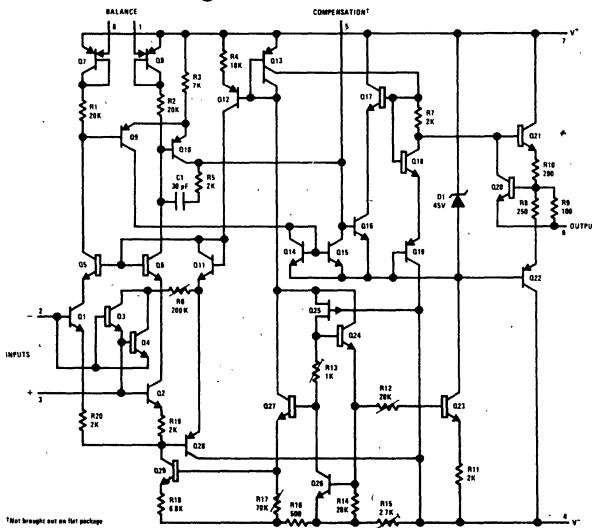
- Maximum input bias current of 3 nA over temperature

- Offset current less than 400 pA over temperature
- Low noise
- Guaranteed drift specifications

The LM112 series are the first IC amplifiers to improve reliability by including overvoltage protection for the MOS compensation capacitor. Without this feature, IC's have been known to suffer catastrophic failure caused by short-duration overvoltage spikes on the supplies. Unlike other internally-compensated IC amplifiers, it is possible to overcompensate with an external capacitor to increase stability margin.

The LM212 is identical to the LM112, except that the LM212 has its performance guaranteed over a -25°C to 85°C temperature range instead of -55°C to 125°C . The LM312 is guaranteed over a 0°C to 70°C temperature range.

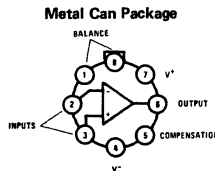
Schematic Diagram **



**Not brought out on flat package

**Pin connections shown are for metal can.

Connection Diagram



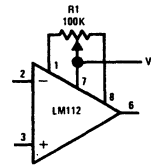
Note: Pin 4 connected to case.

TOP VIEW

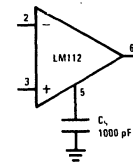
Order Number LM112H, LM212H,
or LM312H
See NS Package H08C

Auxiliary Circuits **

Offset Balancing



Overcompensation for Greater Stability Margin



Absolute Maximum Ratings

| | LM112/LM212 | LM312 |
|--|-----------------|-----------------|
| Supply Voltage | ±20V | ±18V |
| Power Dissipation (Note 1) | 500 mW | 500 mW |
| Differential Input Current (Note 2) | ±10 mA | ±10 mA |
| Input Voltage (Note 3) | ±15V | ±15V |
| Output Short-Circuit Duration | Indefinite | Indefinite |
| Operating Temperature Range | | 0°C to +70°C |
| LM112 | -55°C to +125°C | |
| LM212 | -25°C to +85°C | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM112/LM212 | | | LM312 | | | UNITS |
|---|--|-------------|------|-----|-------|-----|-----|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 0.7 | 2.0 | | 2.0 | 7.5 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 0.05 | 0.2 | | 0.2 | 1 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 0.8 | 2.0 | | 1.5 | 7 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 30 | 70 | | 10 | 40 | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 0.3 | 0.6 | | 0.3 | 0.8 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L \geq 10\text{ k}\Omega$ | 50 | 300 | | 25 | 300 | | V/mV |
| Input Offset Voltage | | | | 3.0 | | | 10 | mV |
| Average Temperature Coefficient of Input Offset Voltage | | | 3.0 | 15 | | 6.0 | 30 | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | | | | 0.4 | | | 1.5 | nA |
| Average Temperature Coefficient of Input Offset Current | | | 0.5 | 2.5 | | 2.0 | 10 | $\text{pA}/^\circ\text{C}$ |
| Input Bias Current | | | | 3.0 | | | 10 | nA |
| Supply Current | $T_A = 125^\circ\text{C}$ | | 0.15 | 0.4 | | | | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$ $R_L \geq 10\text{ k}\Omega$ | 25 | | | 15 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ | ±13 | ±14 | | ±13 | ±14 | | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±13.5 | | | ±14 | | | V |
| Common-Mode Rejection Ratio | | 85 | 100 | | 80 | 100 | | dB |
| Supply Voltage Rejection Ratio | | 80 | 96 | | 80 | 96 | | dB |

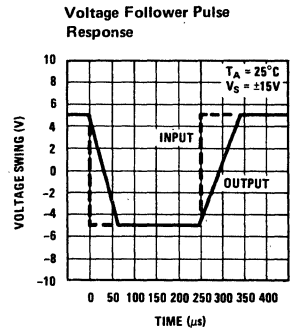
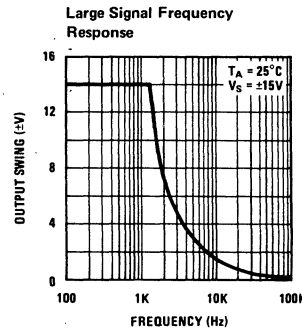
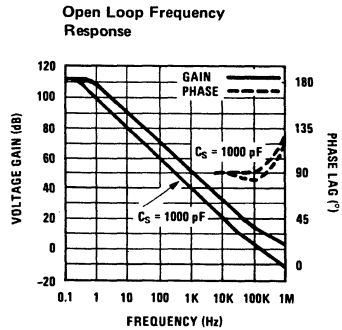
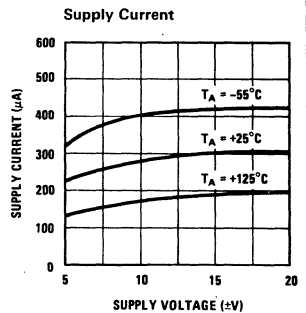
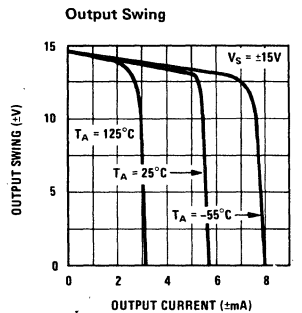
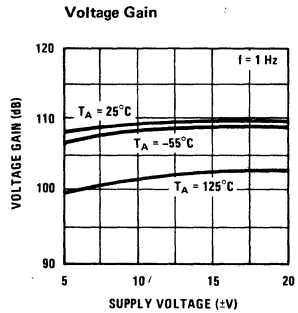
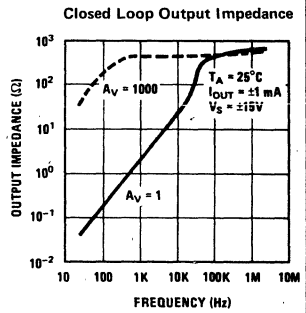
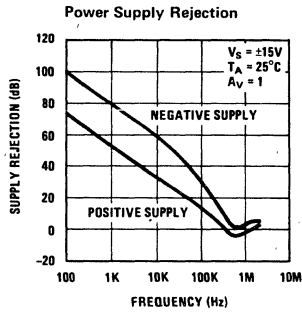
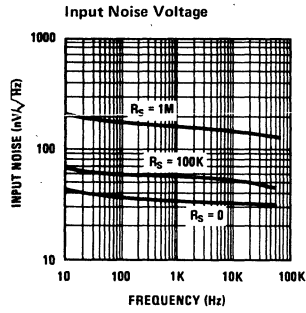
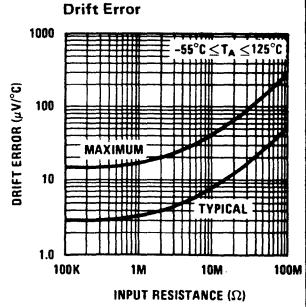
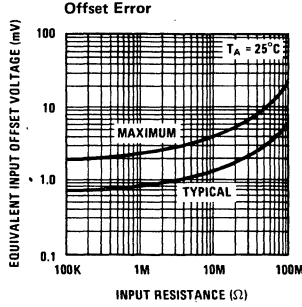
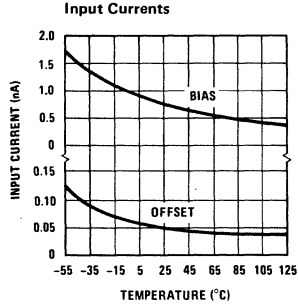
Note 1: The maximum junction temperature of the LM112 is 150°C, LM212 is 100°C and LM312 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: The inputs are shunted with shunt diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

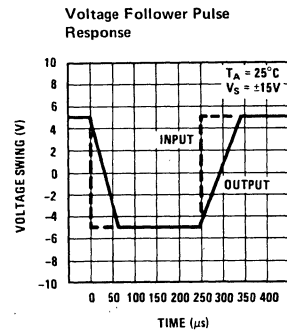
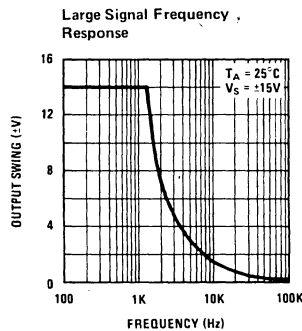
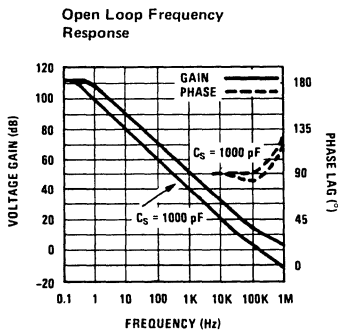
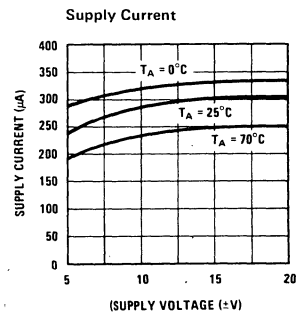
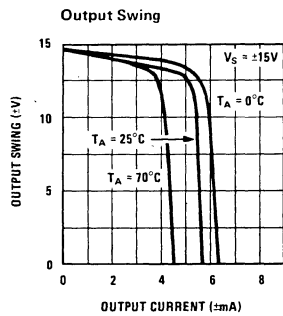
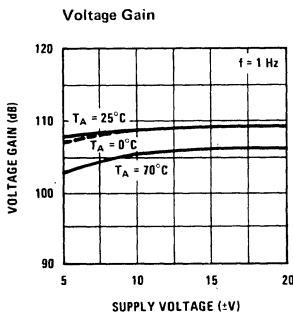
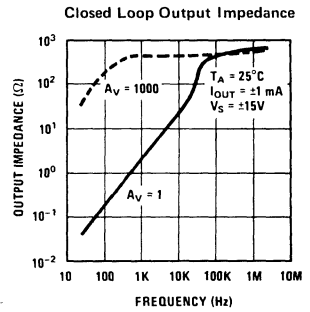
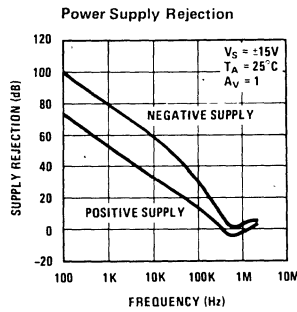
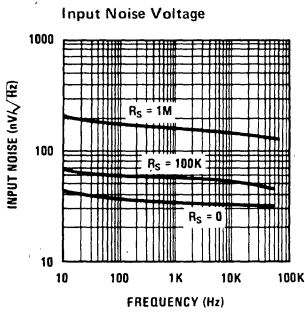
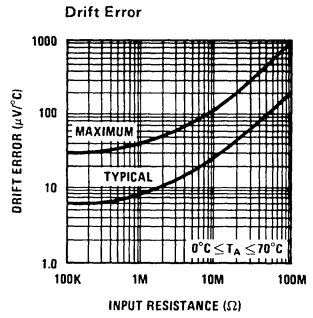
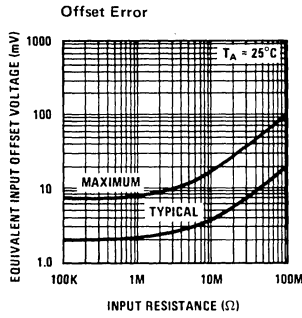
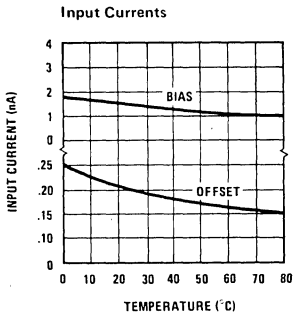
Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ (LM112), $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ (LM212), $\pm 5\text{V} \leq V_S \leq \pm 15\text{V}$ and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ (LM312) unless otherwise noted.

Typical Performance Characteristics LM112/LM212



Typical Performance Characteristics LM312





Operational Amplifiers/Buffers

LM118/LM218/LM318 Operational Amplifiers

General Description

The LM118 series are precision high speed operational amplifiers designed for applications requiring wide bandwidth and high slew rate. They feature a factor of ten increase in speed over general purpose devices without sacrificing DC performance.

Features

- 15 MHz small signal bandwidth
- Guaranteed 50V/ μ s slew rate
- Maximum bias current of 250 nA
- Operates from supplies of ± 5 V to ± 20 V
- Internal frequency compensation
- Input and output overload protected
- Pin compatible with general purpose op amps

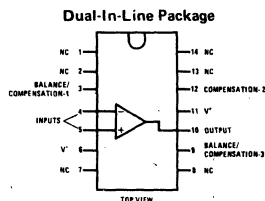
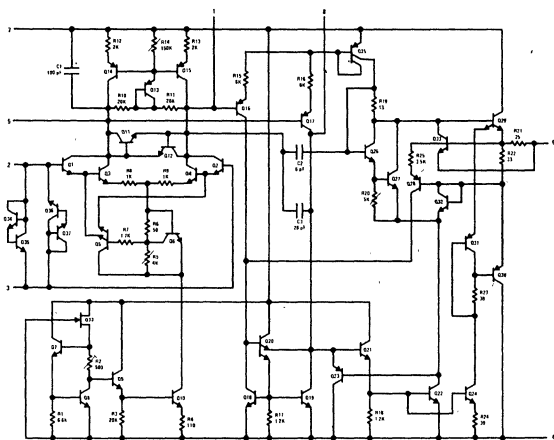
The LM118 series has internal unity gain frequency compensation. This considerably simplifies its application since no external components are necessary for operation. However, unlike most internally

compensated amplifiers, external frequency compensation may be added for optimum performance. For inverting applications, feedforward compensation will boost the slew rate to over 150V/ μ s and almost double the bandwidth. Overcompensation can be used with the amplifier for greater stability when maximum bandwidth is not needed. Further, a single capacitor can be added to reduce the 0.1% settling time to under 1 μ s.

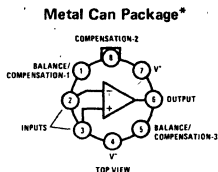
The high speed and fast settling time of these op amps make them useful in A/D converters, oscillators, active filters, sample and hold circuits, or general purpose amplifiers. These devices are easy to apply and offer an order of magnitude better AC performance than industry standards such as the LM709.

The LM218 is identical to the LM118 except that the LM218 has its performance specified over a -25°C to $+85^{\circ}\text{C}$ temperature range. The LM318 is specified from 0°C to $+70^{\circ}\text{C}$.

Schematic and Connection Diagrams

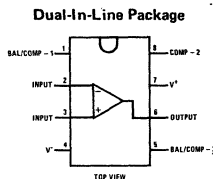


Order Number LM118J, LM218J
or LM318J
See NS Package J14A



*Pin connections shown on schematic diagram and typical applications are for TO-5 package.

Order Number LM118H, LM218H
or LM318H
See NS Package H08C



Order Number LM118J-8,
LM218J-8 or LM318J-8
See NS Package J08A
Order Number LM318N
See NS Package N08B

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±20V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Current (Note 2) | ±10 mA |
| Input Voltage (Note 3) | ±15V |
| Output Short-Circuit Duration | Indefinite |
| Operating Temperature Range | |
| LM118 | -55°C to +125°C |
| LM218 | -25°C to +85°C |
| LM318 | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM118/LM218 | | | LM318 | | | UNITS |
|--------------------------------|---|-------------|-----|-----|-------|-----|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 2 | 4 | | 4 | 10 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 6 | 50 | | 30 | 200 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 120 | 250 | | 150 | 500 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 1 | 3 | | 0.5 | 3 | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 5 | 8 | | 5 | 10 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}, R_L \geq 2\text{ k}\Omega$ | 50 | 200 | | 25 | 200 | | V/mV |
| Slew Rate | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}, A_V = 1$ | 50 | 70 | | 50 | 70 | | V/ μs |
| Small Signal Bandwidth | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ | | 15 | | | 15 | | MHz |
| Input Offset Voltage | | | | 6 | | | 15 | mV |
| Input Offset Current | | | | 100 | | | 300 | nA |
| Input Bias Current | | | | 500 | | | 750 | nA |
| Supply Current | $T_A = 125^\circ\text{C}$ | | 4.5 | 7 | | | | |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, V_{OUT} = \pm 10\text{V}$ $R_L \geq 2\text{ k}\Omega$ | 25 | | | 20 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 2\text{ k}\Omega$ | ±12 | ±13 | | ±12 | ±13 | | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±11.5 | | | ±11.5 | | | V |
| Common-Mode Rejection Ratio | | 80 | 100 | | 70 | 100 | | dB |
| Supply Voltage Rejection Ratio | | 70 | 80 | | 65 | 80 | | dB |

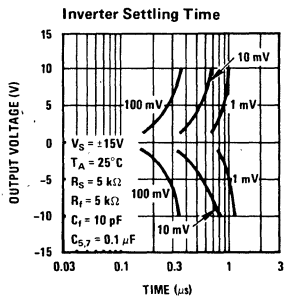
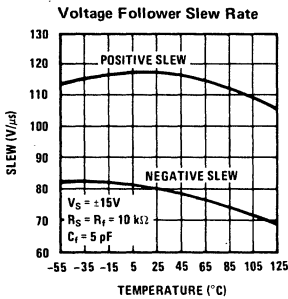
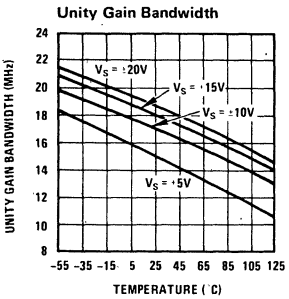
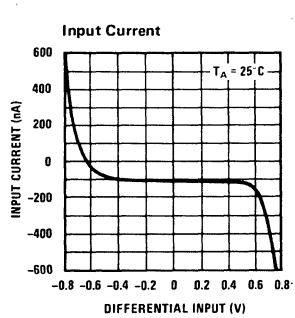
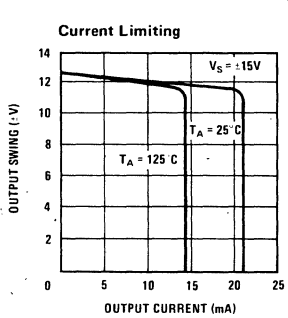
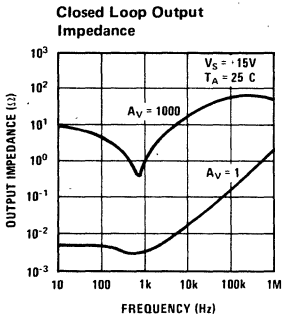
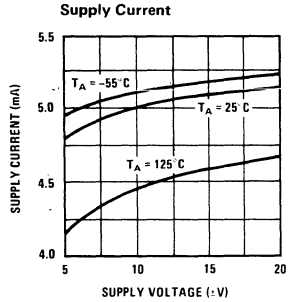
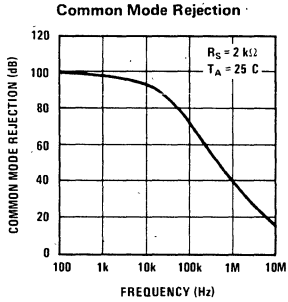
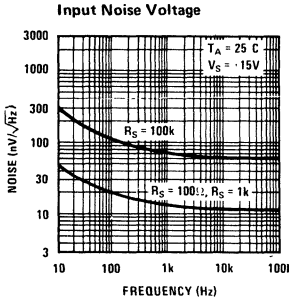
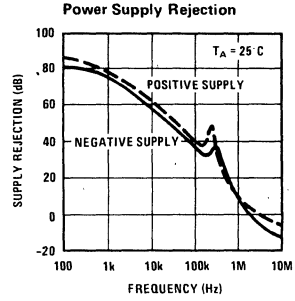
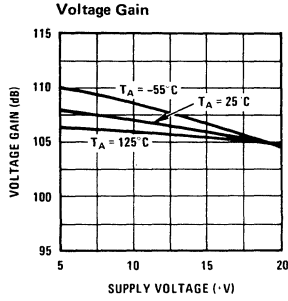
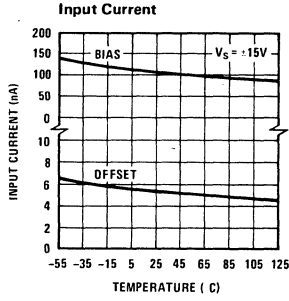
Note 1: The maximum junction temperature of the LM118 is 150°C, the LM218 is 110°C, and the LM318 is 110°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

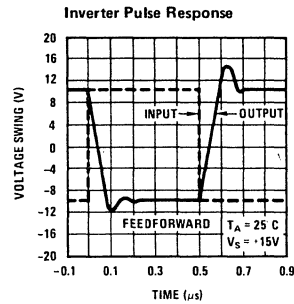
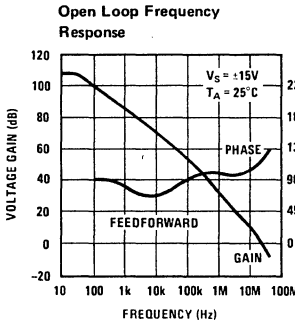
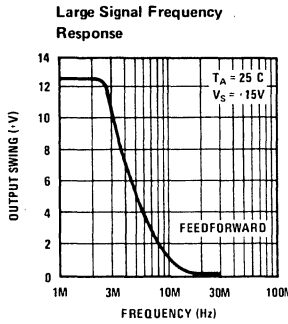
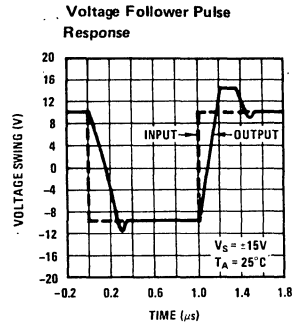
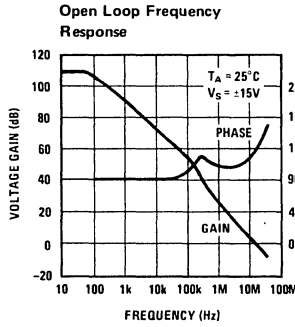
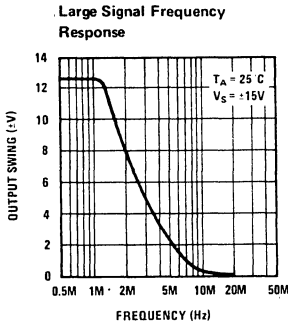
Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, (LM118), $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ (LM218), and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ (LM318). Also, power supplies must be bypassed with 0.1 μF disc capacitors.

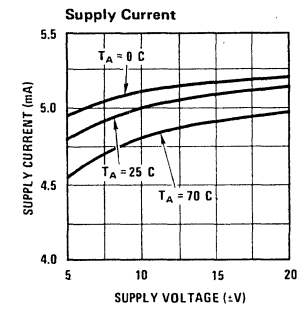
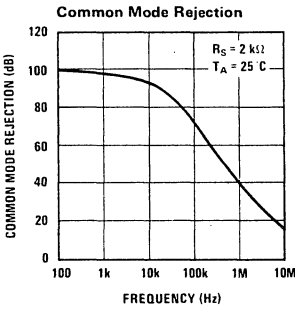
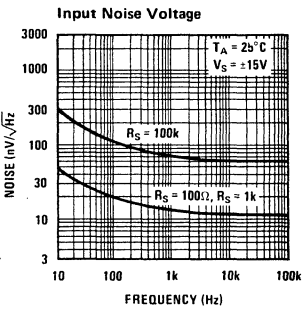
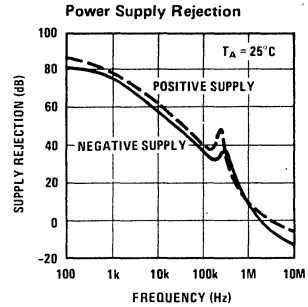
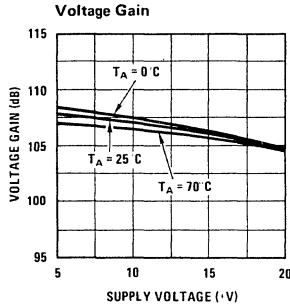
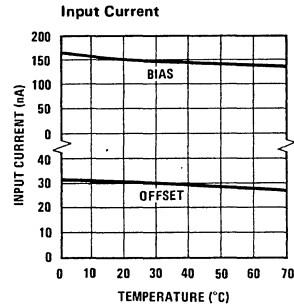
Typical Performance Characteristics LM118, LM218



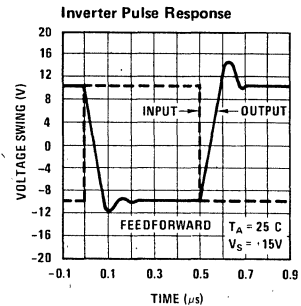
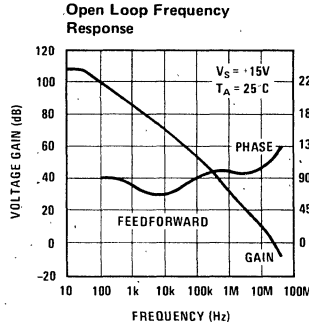
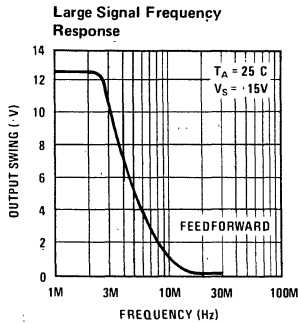
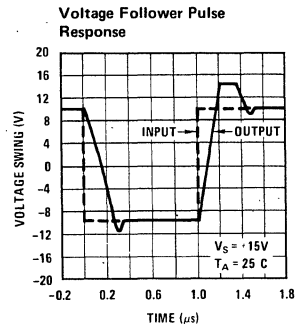
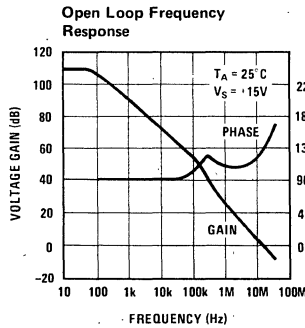
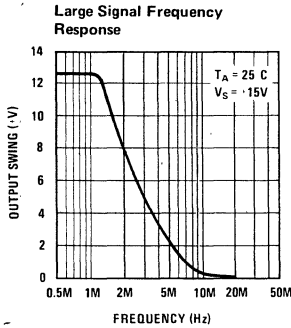
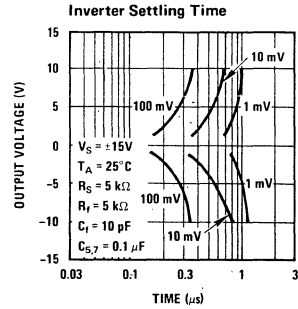
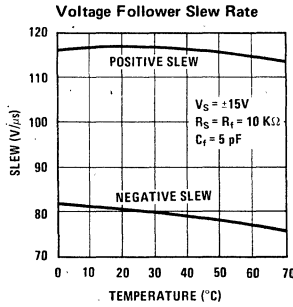
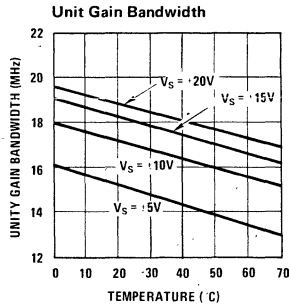
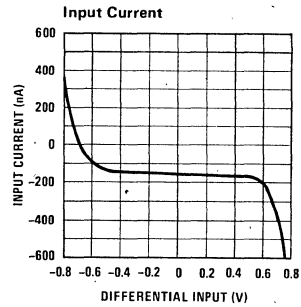
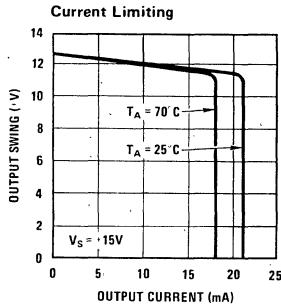
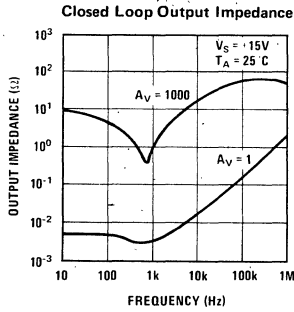
Typical Performance Characteristics LM118, LM218 (Continued)



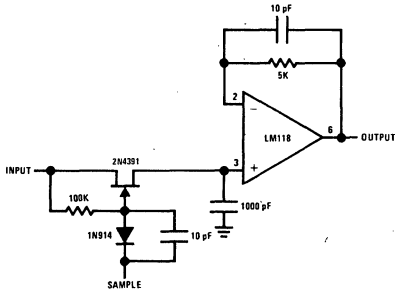
Typical Performance Characteristics LM318



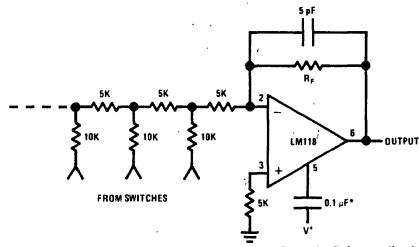
Typical Performance Characteristics LM318 (Continued)



Typical Applications (Continued)

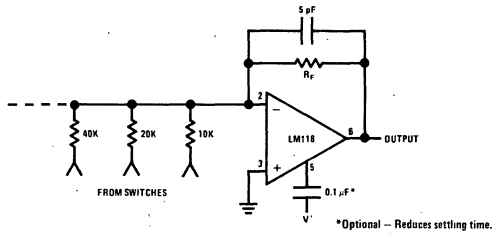


Fast Sample and Hold



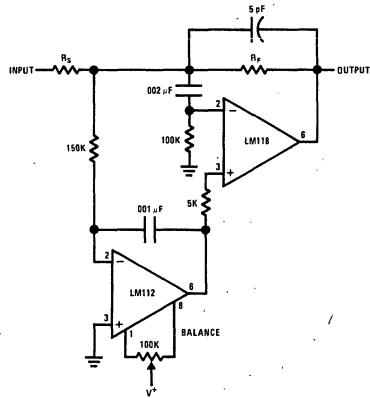
*Optional - Reduces settling time.

D/A Converter Using Ladder Network

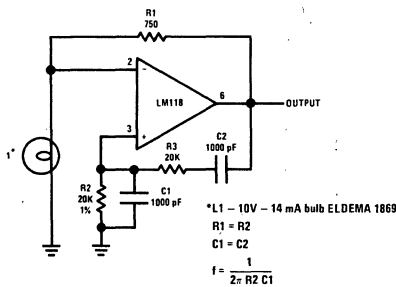


*Optional - Reduces settling time.

D/A Converter Using Binary Weighted Network

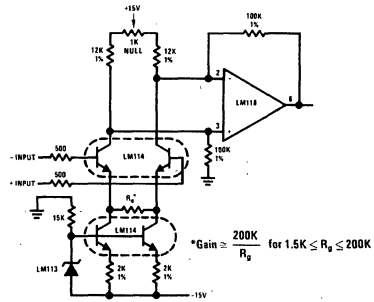


Fast Summing Amplifier with Low Input Current



*L1 - 10V - 14 mA bulb ELDEMA 1869
 $R_1 = R_2$
 $C_1 = C_2$
 $f = \frac{1}{2\pi R_2 C_1}$

Wein Bridge Sine Wave Oscillator



*Gain $\geq \frac{200K}{R_0}$ for $1.5K \leq R_0 \leq 200K$

Instrumentation Amplifier

LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902
Low Power Quad Operational Amplifiers
General Description

The LM124 series consists of four independent, high gain, internally frequency compensated operational amplifiers which were designed specifically to operate from a single power supply over a wide range of voltages. Operation from split power supplies is also possible and the low power supply current drain is independent of the magnitude of the power supply voltage.

Application areas include transducer amplifiers, dc gain blocks and all the conventional op amp circuits which now can be more easily implemented in single power supply systems. For example, the LM124 series can be directly operated off of the standard +5 V_{DC} power supply voltage which is used in digital systems and will easily provide the required interface electronics without requiring the additional ±15 V_{DC} power supplies.

Unique Characteristics

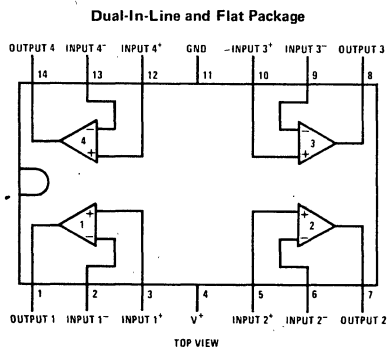
- In the linear mode the input common-mode voltage range includes ground and the output voltage can also swing to ground, even though operated from only a single power supply voltage.
- The unity gain cross frequency is temperature compensated.
- The input bias current is also temperature compensated.

Advantages

- Eliminates need for dual supplies
- Four internally compensated op amps in a single package
- Allows directly sensing near GND and V_{OUT} also goes to GND
- Compatible with all forms of logic
- Power drain suitable for battery operation

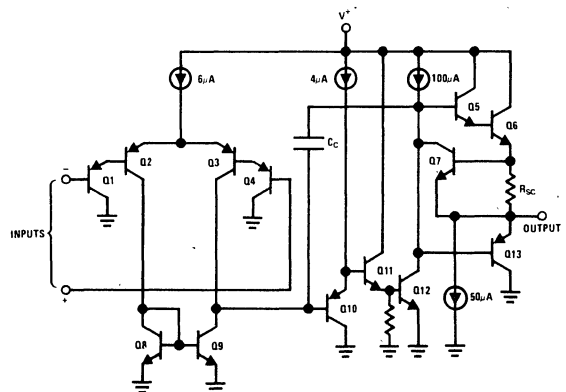
Features

- Internally frequency compensated for unity gain
- Large dc voltage gain 100 dB
- Wide bandwidth (unity gain) 1 MHz (temperature compensated)
- Wide power supply range:
 - Single supply 3 V_{DC} to 30 V_{DC}
 - or dual supplies ±1.5 V_{DC} to ±15 V_{DC}
- Very low supply current drain (800μA) — essentially independent of supply voltage (1 mW/op amp at +5 V_{DC})
- Low input biasing current 45 nA_{DC} (temperature compensated)
- Low input offset voltage and offset current 2 mV_{DC} 5 nA_{DC}
- Input common-mode voltage range includes ground
- Differential input voltage range equal to the power supply voltage
- Large output voltage swing 0 V_{DC} to V⁺ - 1.5 V_{DC}

Connection Diagram


Order Number LM124J, LM124AJ,
LM224J, LM224AJ, LM324J,
LM324AJ or LM2902J
See NS Package J14A

Order Number LM324N, LM324AN
or LM2902N
See NS Package N14A

Schematic Diagram (Each Amplifier)


LM124/LM224/LM324, LM124A/LM224A/LM324A, LM2902

Absolute Maximum Ratings

| | LM124/LM224/LM324 LM124A/LM224A/LM324A | LM2902 | LM124/LM224/LM324 LM124A/LM224A/LM324A | LM2902 |
|--|---|---|---|-----------------|
| Supply Voltage, V^+ | 32 V _{DC} or ±16 V _{DC} | 26 V _{DC} or ±13 V _{DC} | 50 mA | 50 mA |
| Differential Input Voltage | 32 V _{DC} | 26 V _{DC} | Operating Temperature Range | -40°C to +85°C |
| Input Voltage | -0.3 V _{DC} to +26 V _{DC} | -0.3 V _{DC} to +26 V _{DC} | LM324/LM324A | 0°C to +70°C |
| Power Dissipation (Note 1) | | | LM224/LM224A | -25°C to +85°C |
| Molded DIP | 570 mW | 570 mW | LM124/LM124A | -55°C to +125°C |
| Cavity DIP | 900 mW | | Storage Temperature Range | -65°C to +150°C |
| Flat Pack | 800 mW | | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Output Short-Circuit to GND (One Amplifier) (Note 2) | Continuous | Continuous | | |
| $V^+ \leq 15$ V _{DC} and $T_A = 25^\circ\text{C}$ | | | | |

Electrical Characteristics ($V^+ = +5.0$ V_{DC}, Note 4)

| PARAMETER | CONDITIONS | LM124A | | | LM224A | | | LM324A | | | LM124/LM224 | | | LM324 | | | LM2902 | | | UNITS |
|--|--|--------|-------------|-----|--------|-------------|-----|--------|-------------|-----|-------------|-------------|-----|-------|-------------|-----|--------|-------------|-----|-----------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, (Note 5) | 1 | 2 | | 1 | 3 | | 2 | 3 | | ±2 | ±5 | | ±2 | ±7 | | ±2 | ±7 | | mV _{DC} |
| Input Bias Current (Note 6) | $I_{IN(+)}$ or $I_{IN(-)}$, $T_A = 25^\circ\text{C}$ | 20 | 50 | | 40 | 80 | | 45 | 100 | | 45 | 150 | | 45 | 250 | | 45 | 250 | | nA _{DC} |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$, $T_A = 25^\circ\text{C}$ | 2 | 10 | | 2 | 15 | | 5 | 30 | | ±3 | ±30 | | ±5 | ±50 | | ±5 | ±50 | | nA _{DC} |
| Input Common-Mode Voltage Range (Note 7) | $V^+ = 30$ V _{DC} , $T_A = 25^\circ\text{C}$ | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | V _{DC} |
| Supply Current | $R_L = \infty$, $V_{CC} = 30\text{V}$, (LM2902 $V_{CC} = 26\text{V}$) $R_L = \infty$ On All Op Amps Over Full Temperature Range | 1.5 | 3 | | 1.5 | 3 | | 1.5 | 3 | | 1.5 | 3 | | 1.5 | 3 | | 1.5 | 3 | | mA _{DC} |
| | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | mA _{DC} |
| Large Signal Voltage Gain | $V^+ = 15$ V _{DC} (For Large V_O Swing) $R_L \geq 2$ k Ω , $T_A = 25^\circ\text{C}$ | 50 | 100 | | 50 | 100 | | 25 | 100 | | 50 | 100 | | 25 | 100 | | 100 | | | V/mV |
| Output Voltage Swing | $R_L = 2$ k Ω , $T_A = 25^\circ\text{C}$ (LM2902 $R_L \geq 10$ k Ω) | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | V _{DC} |
| Common-Mode Rejection Ratio | DC, $T_A = 25^\circ\text{C}$ | 70 | 85 | | 70 | 85 | | 65 | 85 | | 70 | 85 | | 65 | 70 | | 50 | 70 | | dB |
| Power Supply Rejection Ratio | DC, $T_A = 25^\circ\text{C}$ | 65 | 100 | | 65 | 100 | | 65 | 100 | | 65 | 100 | | 65 | 100 | | 50 | 100 | | dB |
| Amplifier-to-Amplifier Coupling (Note 8) | $f = 1$ kHz to 20 kHz, $T_A = 25^\circ\text{C}$ (Input Referred) | -120 | | | -120 | | | -120 | | | -120 | | | -120 | | | -120 | | | dB |
| Output Current Source | $V_{IN}^+ = 1$ V _{DC} , $V_{IN}^- = 0$ V _{DC} , $V^+ = 15$ V _{DC} , $T_A = 25^\circ\text{C}$ | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | | mA _{DC} |
| Sink | $V_{IN}^- = 1$ V _{DC} , $V_{IN}^+ = 0$ V _{DC} , $V^+ = 15$ V _{DC} , $T_A = 25^\circ\text{C}$ | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | mA _{DC} |
| | $V_{IN}^- = 1$ V _{DC} , $V_{IN}^+ = 0$ V _{DC} , $T_A = 25^\circ\text{C}$, $V_O = 200$ mV _{DC} | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | μ A _{DC} |
| Short Circuit to Ground | $T_A = 25^\circ\text{C}$, (Note 2) | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | | mA _{DC} |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM124A | | | LM224A | | | LM324A | | | LM124/LM224 | | | LM324 | | | LM2902 | | | UNITS |
|--|--|----------------|-------------------|-----|----------------|-------------------|-----|----------------|-------------------|-----|----------------|-------------------|-----|----------------|-------------------|-----|----------------|-------------------|-----|----------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | (Note 5) | 4 | | | 4 | | | 5 | | | ±7 | | | ±9 | | | ±10 | | | mV _{DC} |
| Input Offset Voltage Drift | R _S = 0Ω | 7 | 20 | | 7 | 20 | | 7 | 30 | | 7 | | 7 | | 7 | | 7 | | 7 | μV/°C |
| Input Offset Current | I _{IN(+)} - I _{IN(-)} | 30 | | | 30 | | | 75 | | | ±100 | | | ±150 | | | 45 ±200 | | | nA _{DC} |
| Input Offset Current Drift | | 10 | 200 | | 10 | 200 | | 10 | 300 | | 10 | | 10 | | 10 | | 10 | | 10 | pA _{DC} /°C |
| Input Bias Current | I _{IN(+)} or I _{IN(-)} | 40 | 100 | | 40 | 100 | | 40 | 200 | | 40 | 300 | | 40 | 500 | | 40 | 500 | | nA _{DC} |
| Input Common-Mode Voltage Range (Note 7) | V ⁺ = 30 V _{DC} | 0 | V ⁺ -2 | | 0 | V ⁺ -2 | | 0 | V ⁺ -2 | | 0 | V ⁺ -2 | | 0 | V ⁺ -2 | | 0 | V ⁺ -2 | | V _{DC} |
| Large Signal Voltage Gain | V ⁺ = +15 V _{DC} (For Large V _O Swing) R _L ≥ 2 kΩ | 25 | | | 25 | | | 15 | | | 25 | | | 15 | | | 15 | | | V/mV |
| Output Voltage Swing | | | | | | | | | | | | | | | | | | | | |
| V _{OH} | V ⁺ = +30 V _{DC} , R _L = 2 kΩ R _L ≥ 10 kΩ | 26 | | | 26 | | | 26 | | | 26 | | | 26 | | | 22 | | | V _{DC} |
| V _{OL} | V ⁺ = 5 V _{DC} , R _L ≤ 10 kΩ | 27 | 28 | | 27 | 28 | | 27 | 28 | | 27 | 28 | | 27 | 28 | | 23 | 24 | | V _{DC} |
| Output Current | | | | | | | | | | | | | | | | | | | | |
| Source | V _{IN} ⁺ = +1 V _{DC} , V _{IN} ⁻ = 0 V _{DC} , V ⁺ = 15 V _{DC} | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | mA _{DC} |
| Sink | V _{IN} ⁻ = +1 V _{DC} , V _{IN} ⁺ = 0 V _{DC} , V ⁺ = 15 V _{DC} | 10 | 15 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | mA _{DC} |
| Differential Input Voltage | (Note 7) | V ⁺ | | | V ⁺ | | | V ⁺ | | | V ⁺ | | | V ⁺ | | | V ⁺ | | | V _{DC} |

Note 1: For operating at high temperatures, the LM324/LM324A, LM2902 must be derated based on a +125°C maximum junction temperature and a thermal resistance of 175°C/W which applies for the device soldered in a printed circuit board, operating in a still air ambient. The LM224/LM224A and LM124/LM124A can be derated based on a +150°C maximum junction temperature. The dissipation is the total of all four amplifiers—use external resistors, where possible, to allow the amplifier to saturate or to reduce the power which is dissipated in the integrated circuit.

Note 2: Short circuits from the output to V⁺ can cause excessive heating and eventual destruction. The maximum output current is approximately 40 mA independent of the magnitude of V⁺. At values of supply voltage in excess of +15 V_{DC}, continuous short-circuits can exceed the power dissipation ratings and cause eventual destruction. Destructive dissipation can result from simultaneous shorts on all amplifiers.

Note 3: This input current will only exist when the voltage at any of the input leads is driven negative. It is due to the collector-base junction of the input PNP transistors becoming forward biased and thereby acting as input diode clamps. In addition to this diode action, there is also lateral NPN parasitic transistor action on the IC chip. This transistor action can cause the output voltages of the op amps to go to the V⁺ voltage level (or to ground for a large overdrive) for the time duration that an input is driven negative. This is not destructive and normal output states will re-establish when the input voltage, which was negative, again returns to a value greater than -0.3 V_{DC}.

Note 4: These specifications apply for V⁺ = +5 V_{DC} and -55°C ≤ T_A ≤ +125°C, unless otherwise stated. With the LM224/LM224A, all temperature specifications are limited to -25°C ≤ T_A ≤ +85°C, the LM324/LM324A temperature specifications are limited to 0°C ≤ T_A ≤ +70°C, and the LM2902 specifications are limited to -40°C ≤ T_A ≤ +85°C.

Note 5: V_O ≈ 1.4 V_{DC}, R_S = 0Ω with V⁺ from 5 V_{DC} to 30 V_{DC}; and over the full input common-mode range (0 V_{DC} to V⁺ - 1.5 V_{DC}).

Note 6: The direction of the input current is out of the IC due to the PNP input stage. This current is essentially constant, independent of the state of the output so no loading change exists on the input lines.

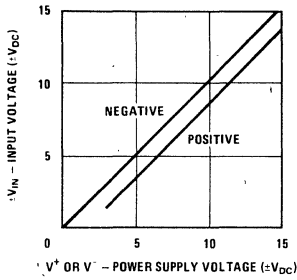
Note 7: The input common-mode voltage or either input signal voltage should not be allowed to go negative by more than 0.3V. The upper end of the common-mode voltage range is V⁺ - 1.5V, but either or both inputs can go to +32 V_{DC} without damage (+26 V_{DC} for LM2902).

Note 8: Due to proximity of external components, insure that coupling is not originating via stray capacitance between these external parts. This typically can be detected as this type of capacitive increases at higher frequencies.

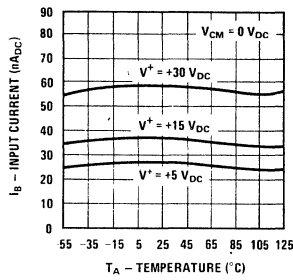
Typical Performance Characteristics

LM124/LM224/LM324,
LM124A/LM224A/LM324A, LM2902

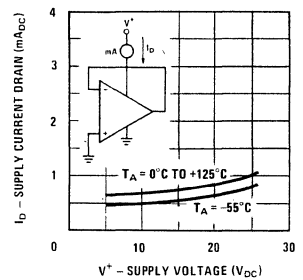
Input Voltage Range



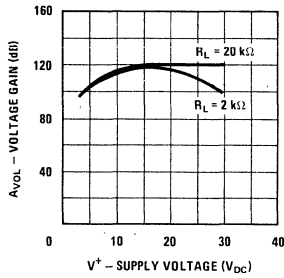
Input Current



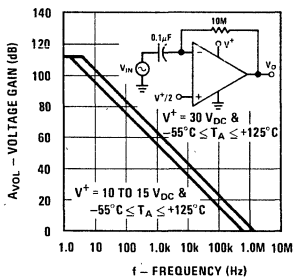
Supply Current



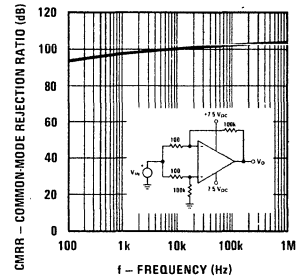
Voltage Gain



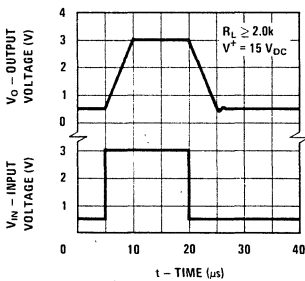
Open Loop Frequency Response



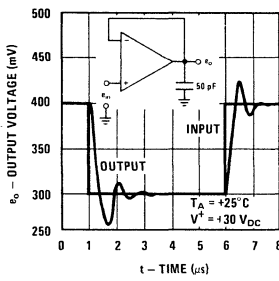
Common Mode Rejection Ratio



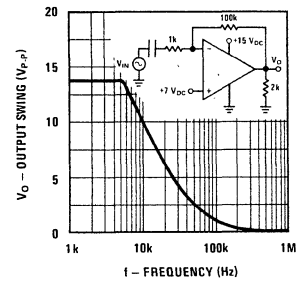
Voltage Follower Pulse Response



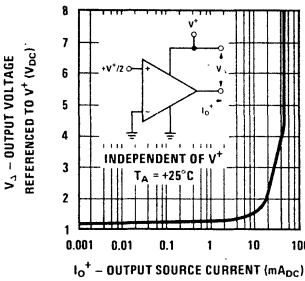
Voltage Follower Pulse Response (Small Signal)



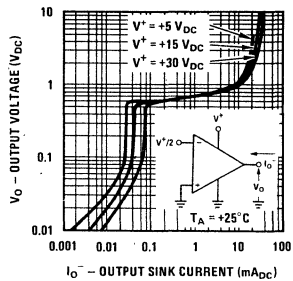
Large Signal Frequency Response



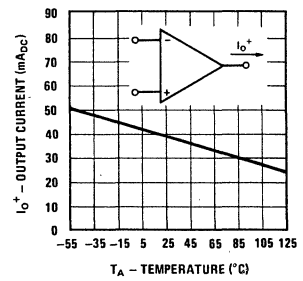
Output Characteristics Current Sourcing



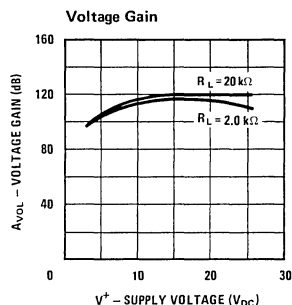
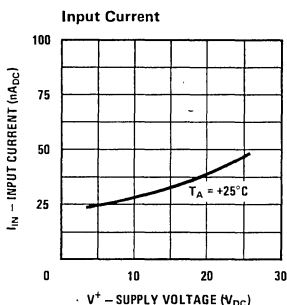
Output Characteristics Current Sinking



Current Limiting



Typical Performance Characteristics (LM2902 only)



Application Hints

The LM124 series are op amps which operate with only a single power supply voltage, have true-differential inputs, and remain in the linear mode with an input common-mode voltage of 0 V_{DC}. These amplifiers operate over a wide range of power supply voltage with little change in performance characteristics. At 25°C amplifier operation is possible down to a minimum supply voltage of 2.3 V_{DC}.

The pinouts of the package have been designed to simplify PC board layouts. Inverting inputs are adjacent to outputs for all of the amplifiers and the outputs have also been placed at the corners of the package (pins 1, 7, 8, and 14).

Precautions should be taken to insure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a test socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Large differential input voltages can be easily accommodated and, as input differential voltage protection diodes are not needed, no large input currents result from large differential input voltages. The differential input voltage may be larger than V⁺ without damaging the device. Protection should be provided to prevent the input voltages from going negative more than -0.3 V_{DC} (at 25°C). An input clamp diode with a resistor to the IC input terminal can be used.

To reduce the power supply current drain, the amplifiers have a class A output stage for small signal levels which converts to class B in a large signal mode. This allows the amplifiers to both source and sink large output currents. Therefore both NPN and PNP external current boost transistors can be used to extend the power capability of the basic amplifiers. The output voltage needs to raise approximately 1 diode drop above ground to bias the on-chip vertical PNP transistor for output current sinking applications.

For ac applications, where the load is capacitively coupled to the output of the amplifier, a resistor should

be used, from the output of the amplifier to ground to increase the class A bias current and prevent crossover distortion. Where the load is directly coupled, as in dc applications, there is no crossover distortion.

Capacitive loads which are applied directly to the output of the amplifier reduce the loop stability margin. Values of 50 pF can be accommodated using the worst-case non-inverting unity gain connection. Large closed loop gains or resistive isolation should be used if larger load capacitance must be driven by the amplifier.

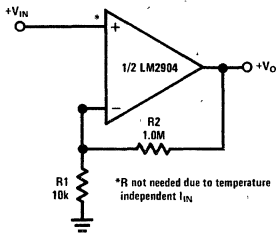
The bias network of the LM124 establishes a drain current which is independent of the magnitude of the power supply voltage over the range of from 3 V_{DC} to 30 V_{DC}.

Output short circuits either to ground or to the positive power supply should be of short time duration. Units can be destroyed, not as a result of the short circuit current causing metal fusing, but rather due to the large increase in IC chip dissipation which will cause eventual failure due to excessive junction temperatures. Putting direct short-circuits on more than one amplifier at a time will increase the total IC power dissipation to destructive levels, if not properly protected with external dissipation limiting resistors in series with the output leads of the amplifiers. The larger value of output source current which is available at 25°C provides a larger output current capability at elevated temperatures (see typical performance characteristics) than a standard IC op amp.

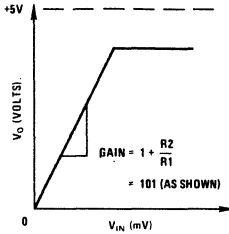
The circuits presented in the section on typical applications emphasize operation on only a single power supply voltage. If complementary power supplies are available, all of the standard op amp circuits can be used. In general, introducing a pseudo-ground (a bias voltage reference of V⁺/2) will allow operation above and below this value in single power supply systems. Many application circuits are shown which take advantage of the wide input common-mode voltage range which includes ground. In most cases, input biasing is not required and input voltages which range to ground can easily be accommodated.

Typical Single-Supply Applications ($V^+ = 5.0 V_{DC}$)

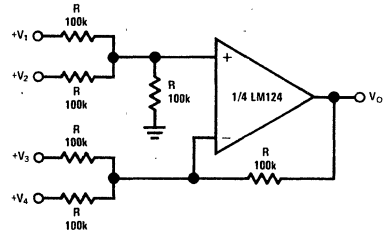
Non-Inverting DC Gain (0V Input = 0V Output)



*R not needed due to temperature independent I_{IN}

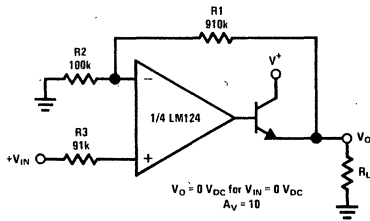


DC Summing Amplifier
 ($V_{IN}'S \geq 0 V_{DC}$ AND $V_O \geq 0 V_{DC}$)



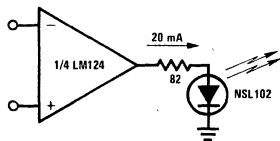
Where: $V_O = V_1 + V_2 + V_3 + V_4$
 $(V_1 + V_2) \geq (V_3 + V_4)$ to keep $V_O > 0 V_{DC}$

Power Amplifier



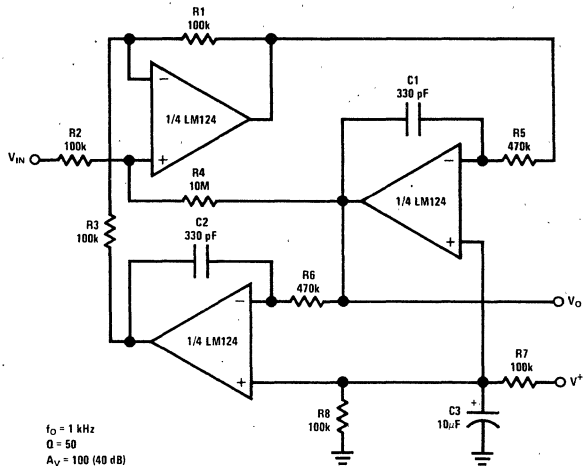
$V_O = 0 V_{DC}$ for $V_{IN} = 0 V_{DC}$
 $A_V = 10$

LED Driver



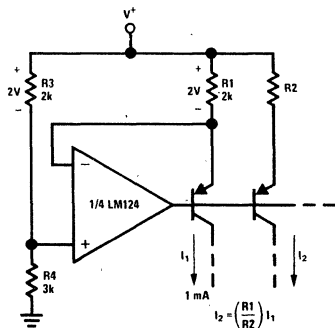
NSL102

"BI-QUAD" RC Active Bandpass Filter

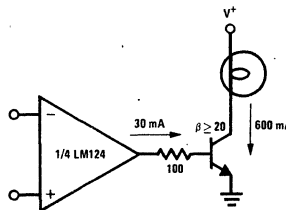


$f_o = 1 \text{ kHz}$
 $Q = 50$
 $A_V = 100 \text{ (40 dB)}$

Fixed Current Sources

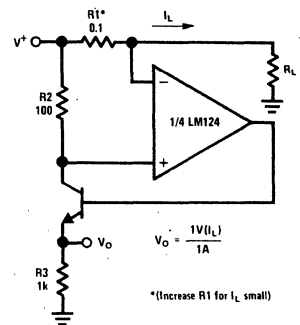


Lamp Driver



$\beta \geq 20$
 600 mA

Current Monitor

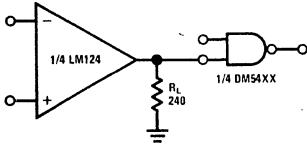


$$V_O = \frac{1V(I_L)}{1A}$$

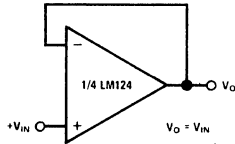
*(Increase R1 for I_L small)

Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

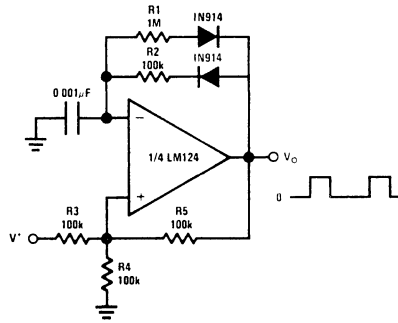
Driving TTL



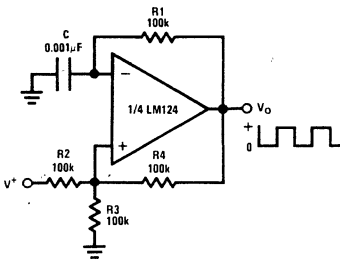
Voltage Follower



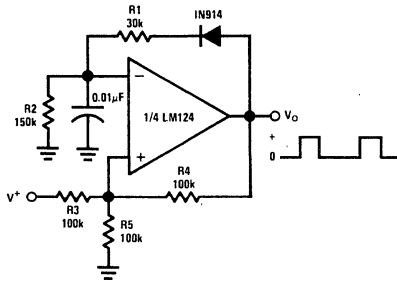
Pulse Generator



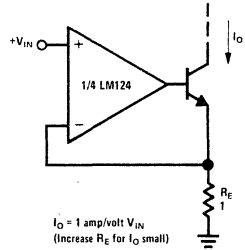
Squarewave Oscillator



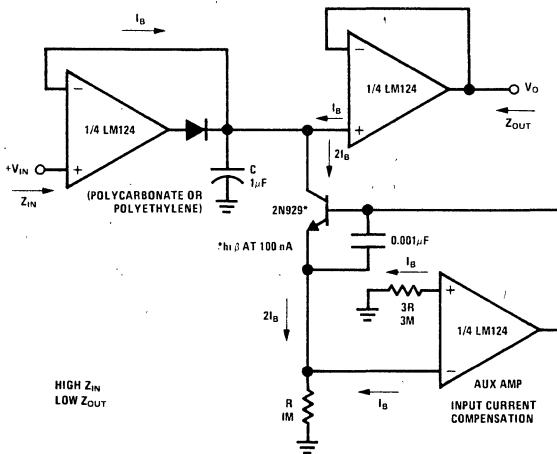
Pulse Generator



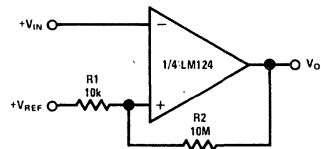
High Compliance Current Sink



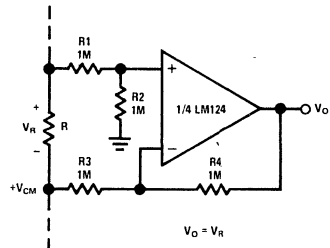
Low Drift Peak Detector



Comparator with Hysteresis



Ground Referencing A Differential Input Signal



Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

Voltage Controlled Oscillator Circuit

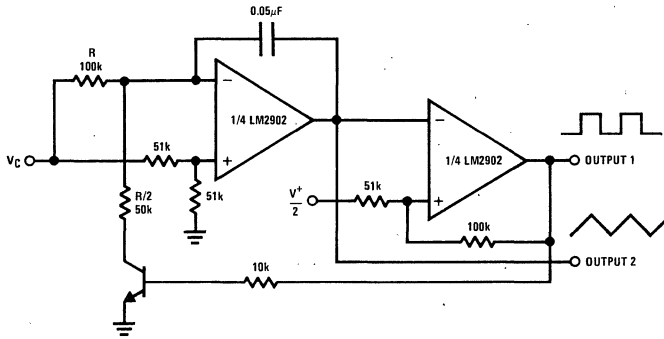
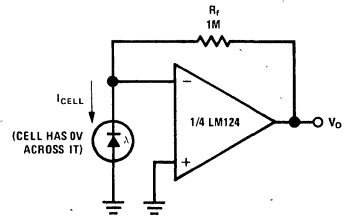
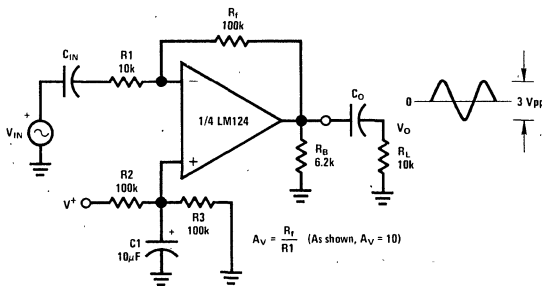


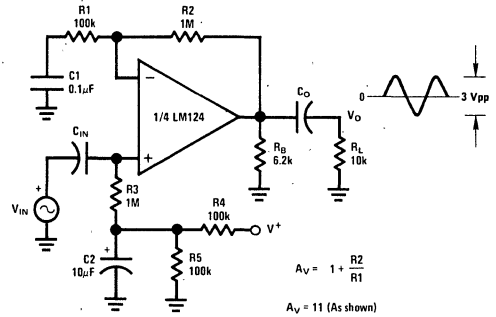
Photo Voltaic-Cell Amplifier



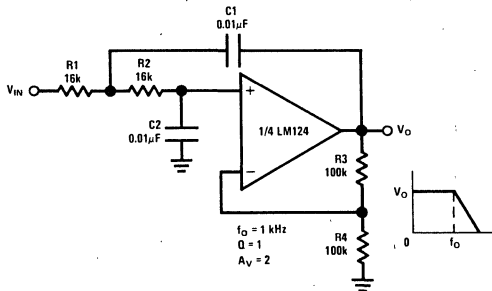
AC Coupled Inverting Amplifier



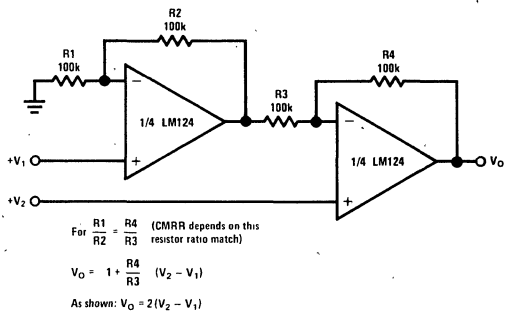
AC Coupled Non-Inverting Amplifier



DC Coupled Low-Pass RC Active Filter

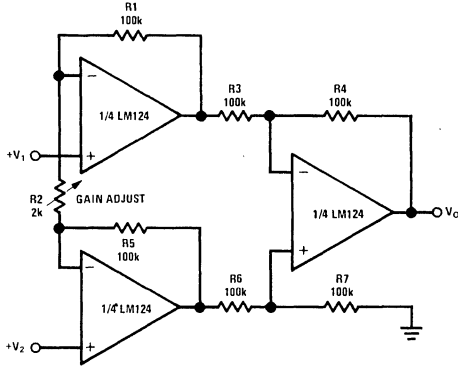


High Input Z, DC Differential Amplifier



Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

High Input Z Adjustable-Gain DC Instrumentation Amplifier

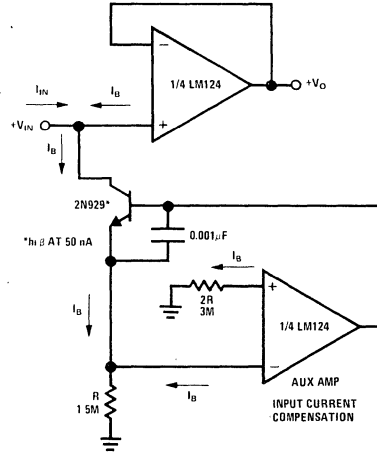


If $R1 = R5$ & $R3 = R4 = R6 = R7$ (CMRR depends on match)

$$V_O = 1 + \frac{2R1}{R2} (V_2 - V_1)$$

As shown $V_O = 101 (V_2 - V_1)$

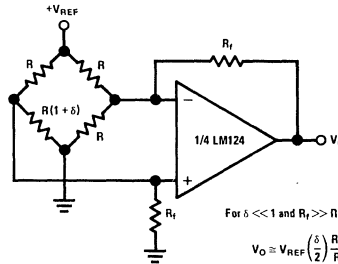
Using Symmetrical Amplifiers to Reduce Input Current (General Concept)



* I_{IN} AT 50 nA

AUX AMP
INPUT CURRENT
COMPENSATION

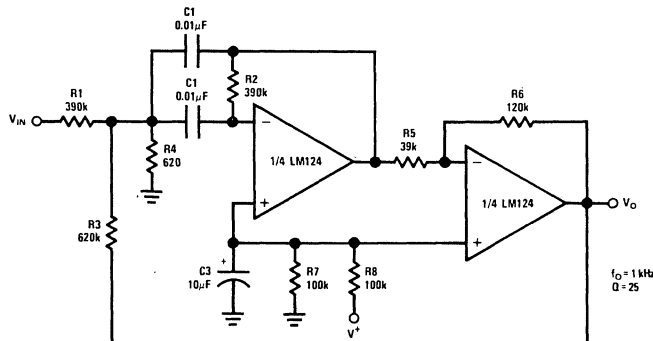
Bridge Current Amplifier



For $\delta \ll 1$ and $R_f \gg R_i$

$$V_O \approx V_{REF} \left(\frac{\delta}{2} \right) \frac{R_f}{R}$$

Bandpass Active Filter



$f_0 = 1 \text{ kHz}$
 $Q = 25$

LM143/LM343 High Voltage Operational Amplifier

General Description

The LM143 is a general purpose high voltage operational amplifier featuring operation to $\pm 40V$, complete input overvoltage protection up to $\pm 40V$ and input currents comparable to those of other super- β op amps. Increased slew rate, together with higher common-mode and supply rejection, insure improved performance at high supply voltages. Operating characteristics, in particular supply current, slew rate and gain, are virtually independent of supply voltage and temperature. Furthermore, gain is unaffected by output loading at high supply voltages due to thermal symmetry on the die. The LM143 is pin compatible with general purpose op amps and has offset null capability.

Application areas include those of general purpose op amps, but can be extended to higher voltages and higher output power when externally boosted. For example, when used in audio power applications, the LM143 provides a power bandwidth that covers the entire audio spectrum. In addition, the LM143 can be reliably operated in environments with large overvoltage spikes on the power supplies, where other internally-compensated op amps would suffer catastrophic failure.

The LM343 is similar to the LM143 for applications in less severe supply voltage and temperature environments.

Features

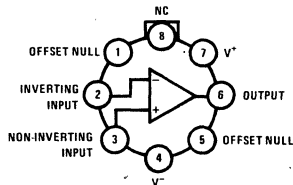
- Wide supply voltage range $\pm 4.0V$ to $\pm 40V$
- Large output voltage swing $\pm 37V$
- Wide input common-mode range $\pm 38V$
- Input overvoltage protection Full $\pm 40V$
- Supply current is virtually independent of supply voltage and temperature

Unique Characteristics

- Low input bias current 8.0 nA
- Low input offset current 1.0 nA
- High slew rate—essentially independent of temperature and supply voltage $2.5V/\mu s$
- High voltage gain—virtually independent of resistive loading, temperature, and supply voltage 100k min
- Internally compensated for unity gain
- Output short circuit protection
- Pin compatible with general purpose op amps

Connection Diagrams

Metal Can Package

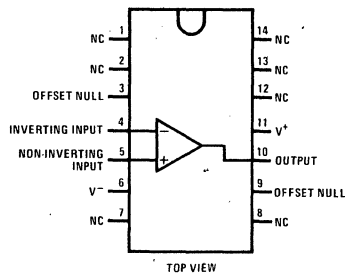


NOTE: Pin 4 connected to case.

TOP VIEW

Order Number LM143H
or LM343H
See NS Package H08C

Dual-In-Line Package



TOP VIEW

Order Number LM143D
or LM343D
See NS Package D14E

Absolute Maximum Ratings (Note 1)

| | LM143 | LM343 |
|--|-----------------|-----------------|
| Supply Voltage | ±40V | ±34V |
| Power Dissipation (Note 1) | 680 mW | 680 mW |
| Differential Input Voltage (Note 2) | 80V | 68V |
| Input Voltage (Note 2) | ±40V | ±34V |
| Operating Temperature Range | -55°C to +125°C | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Output Short Circuit Duration | 5 seconds | 5 seconds |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 3)

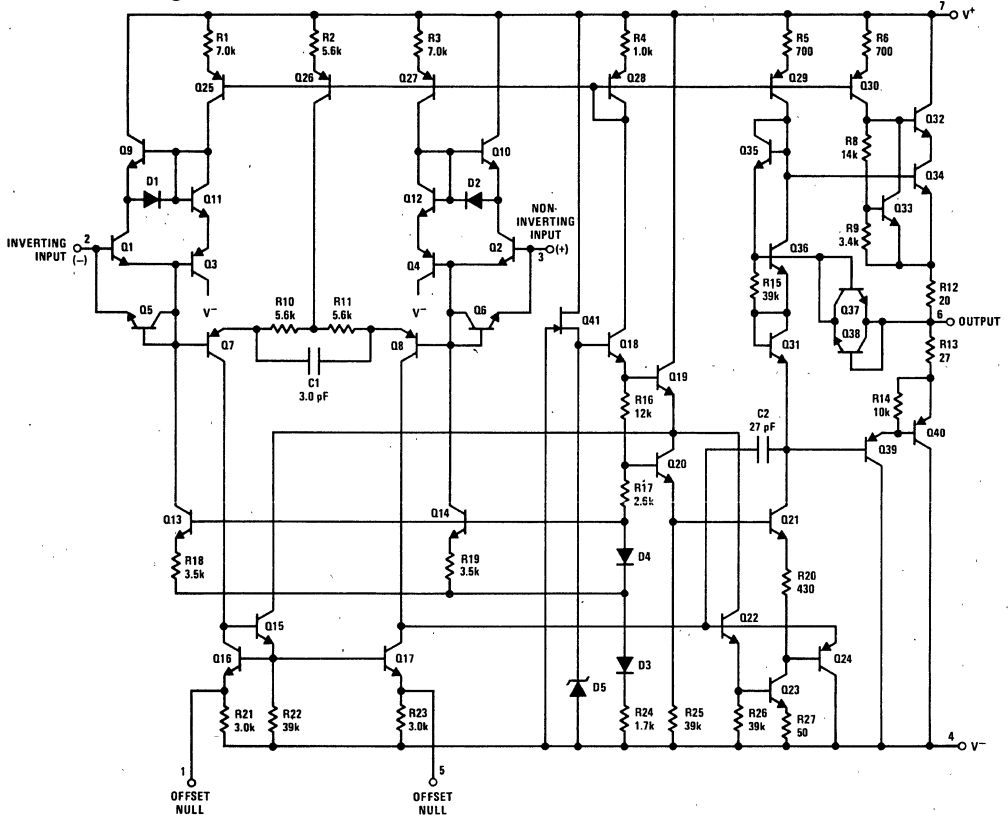
| PARAMETER | CONDITIONS | LM143 | | | LM343 | | | UNITS |
|--------------------------------|--|------------|--------------|------------|------------|--------------|----------|------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 2.0 | 5.0 | | 2.0 | 8.0 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 1.0 | 3.0 | | 1.0 | 10 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 8.0 | 20 | | 8.0 | 40 | nA |
| Supply Voltage Rejection Ratio | $T_A = 25^\circ\text{C}$ | | 10 | 100 | | 10 | 200 | $\mu\text{V/V}$ |
| Output Voltage Swing | $T_A = 25^\circ\text{C}$, $R_L \geq 5\text{ k}\Omega$ | 22 | 25 | | 20 | 25 | | V |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_{\text{OUT}} = \pm 10\text{V}$, $R_L \geq 100\text{ k}\Omega$ | 100k | 180k | | 70k | 180k | | V/V |
| Common-Mode Rejection Ratio | $T_A = 25^\circ\text{C}$ | 80 | 90 | | 70 | 90 | | dB |
| Input Voltage Range | $T_A = 25^\circ\text{C}$ | 24 | 26 | | 22 | 26 | | V |
| Supply Current (Note 4) | $T_A = 25^\circ\text{C}$ | | 2.0 | 4.0 | | 2.0 | 5.0 | mA |
| Short Circuit Current | $T_A = 25^\circ\text{C}$ | | 20 | | | 20 | | mA |
| Slew Rate | $T_A = 25^\circ\text{C}$, $A_V = 1$ | | 2.5 | | | 2.5 | | $\text{V}/\mu\text{s}$ |
| Power Bandwidth | $T_A = 25^\circ\text{C}$, $V_{\text{OUT}} = 40\text{ V}_{\text{P-P}}$, $R_L = 5\text{ k}\Omega$, $\text{THD} \leq 1\%$ | | 20k | | | 20k | | Hz |
| Unity Gain Frequency | $T_A = 25^\circ\text{C}$ | | 1.0M | | | 1.0M | | Hz |
| Input Offset Voltage | $T_A = \text{Max}$ $T_A = \text{Min}$ | | | 6.0 6.0 | | | 10 10 | mV mV |
| Input Offset Current | $T_A = \text{Max}$ $T_A = \text{Min}$ | | 0.8 1.8 | 4.5 7.0 | | 0.8 1.8 | 14 14 | nA nA |
| Input Bias Current | $T_A = \text{Max}$ $T_A = \text{Min}$ | | 5.0 16 | 35 35 | | 5.0 16 | 55 55 | nA nA |
| Large Signal Voltage Gain | $R_L \geq 100\text{ k}\Omega$, $T_A = \text{Max}$ $R_L \geq 100\text{ k}\Omega$, $T_A = \text{Min}$ | 50k 50k | 150k 220k | | 50k 50k | 150k 220k | | V/V V/V |
| Output Voltage Swing | $R_L \geq 5.0\text{ k}\Omega$, $T_A = \text{Max}$ $R_L \geq 5.0\text{ k}\Omega$, $T_A = \text{Min}$ | 22 22 | 26 25 | | 20 20 | 26 25 | | V V |

Note 1: Absolute maximum ratings are not necessarily concurrent, and care must be taken not to exceed the maximum junction temperature of the LM143 (150°C) or the LM343 (100°C). For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

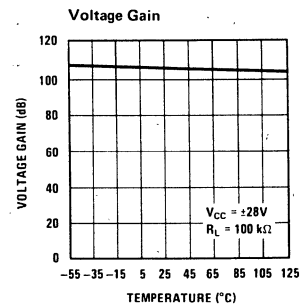
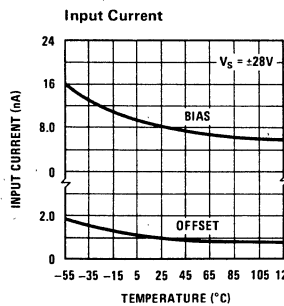
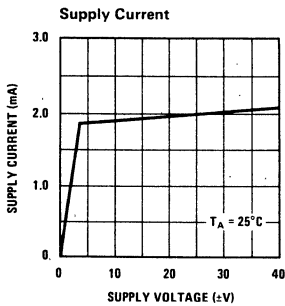
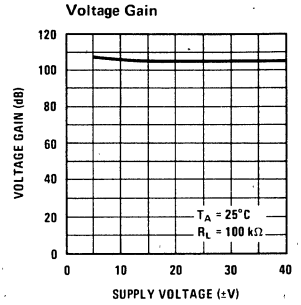
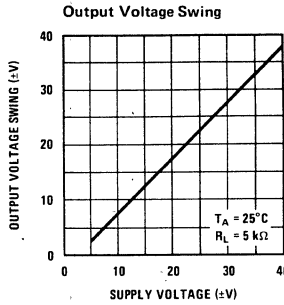
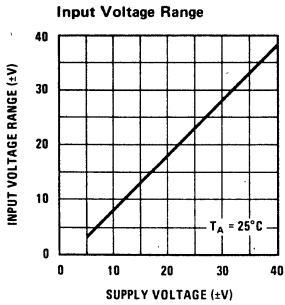
Note 2: For supply voltage less than ±40V for the LM143 and less than ±34V for the LM343, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for $V_S = \pm 28\text{V}$. For LM143, $T_A = \text{max} = 125^\circ\text{C}$ and $T_A = \text{min} = -55^\circ\text{C}$. For LM343, $T_A = \text{max} = 70^\circ\text{C}$ and $T_A = \text{min} = 0^\circ\text{C}$.

Schematic Diagram

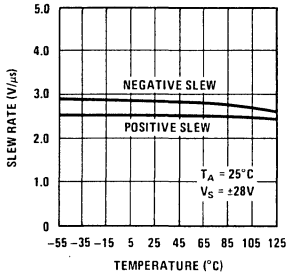


Typical Performance Characteristics

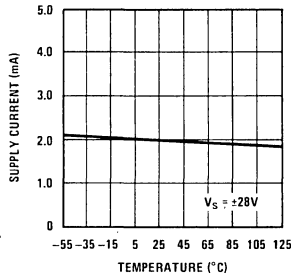


Typical Performance Characteristics (Continued)

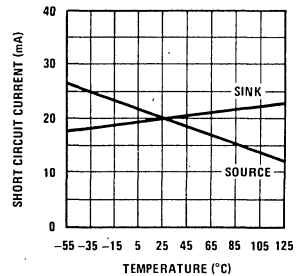
Voltage Follower Slew Rate



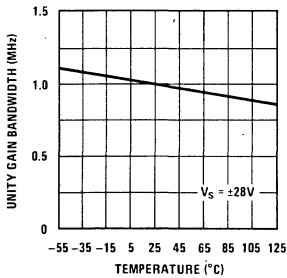
Supply Current



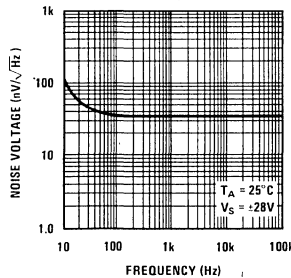
Short Circuit Current



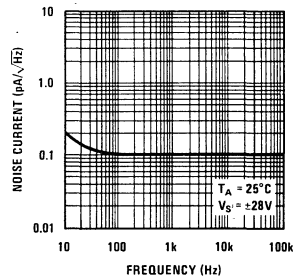
Unity Gain Bandwidth



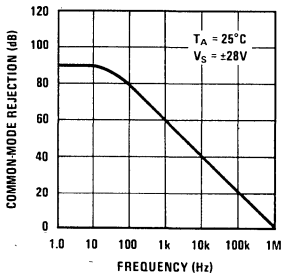
Input Noise Voltage



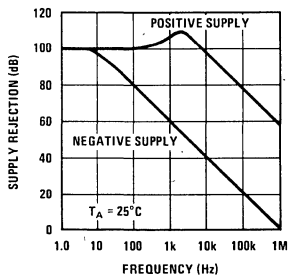
Input Noise Current



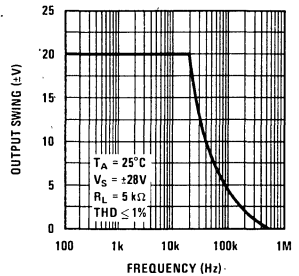
Common-Mode Rejection



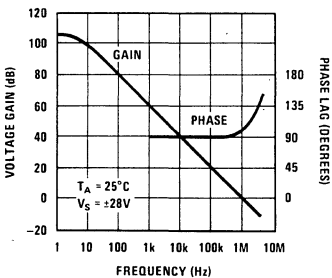
Power Supply Rejection



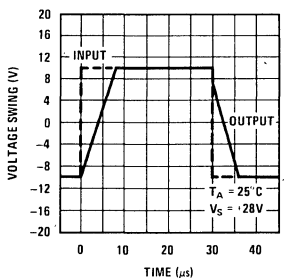
Large Signal Frequency Response



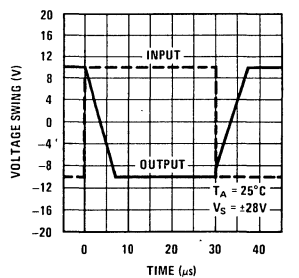
Open Loop Frequency Response



Voltage Follower Pulse Response



Inverter Pulse Response



Application Hints (See AN-127)

The LM143 is designed for trouble free operation at any supply voltage up to and including the guaranteed maximum of $\pm 40V$. Input overvoltage protection, both common-mode and differential, is 100% tested and guaranteed at the maximum supply voltage. Furthermore, all possible high voltage destructive modes during supply voltage turn-on have been eliminated by design. As with most IC op amps, however, certain precautions should be observed to insure that the LM143 remains virtually blow-out proof.

Although output short circuits to ground or either supply can be sustained indefinitely at lower supply voltages, these short circuits should be of limited duration when operating at higher supply voltages. Units can be destroyed by any combination of high ambient temperature, high supply voltages, and high power dissipation which results in excessive die temperature. This is also true when driving low impedance or reactive loads or loads that can revert to low impedance; for example, the LM143 can drive most general purpose op amps outside of the maximum input voltage range, causing heavy current to flow and possibly destroying both devices.

Precautions should be taken to insure that the power supplies never become reversed in polarity—even under transient conditions. With reverse voltage, the IC will conduct excessive current, fusing the internal aluminum interconnects. Voltage reversal between the power supplies will almost always result in a destroyed unit.

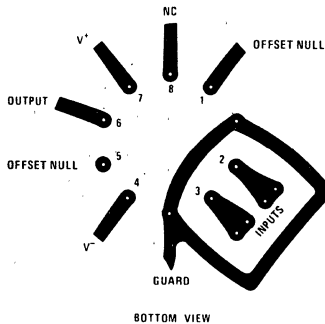


FIGURE 1. Printed Circuit Layout for Input Guarding with TO-5 Package

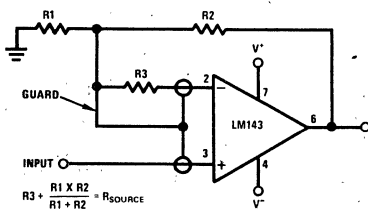


FIGURE 3. Guarded Non-Inverting Amplifier

In high voltage applications which are sensitive to very low input currents, special precautions should be exercised. For example, with high source resistances, care should be taken to prevent the magnitude of the PC board leakage currents, although quite small, from approaching those of the op amp input currents. These leakage currents become larger at $125^{\circ}C$ and are made worse by high supply voltages. To prevent this, PC boards should be properly cleaned and coated to prevent contamination and to provide protection from condensed water vapor when operating below $0^{\circ}C$. A guard ring is also recommended to significantly reduce leakage currents from the op amp input pins to the adjacent high voltage pins in the standard op amp pin connection as shown in Figure 1. Figures 2, 3 and 4 show how the guard ring is connected for the three most common op amp configurations.

Finally, caution should be exercised in high voltage applications as electrical shock hazards are present. Since the negative supply is connected to the case, users may inadvertently contact voltages equal to those across the power supplies.

The LM143 can be used as a plug-in replacement in most general purpose op amp applications. The circuits presented in the following section emphasize those applications which take advantage of the unique high voltage capabilities of the LM143.

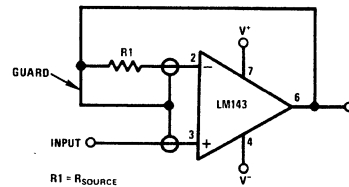


FIGURE 2. Guarded Voltage Follower

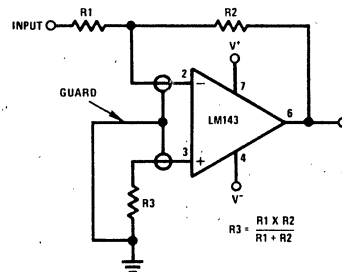
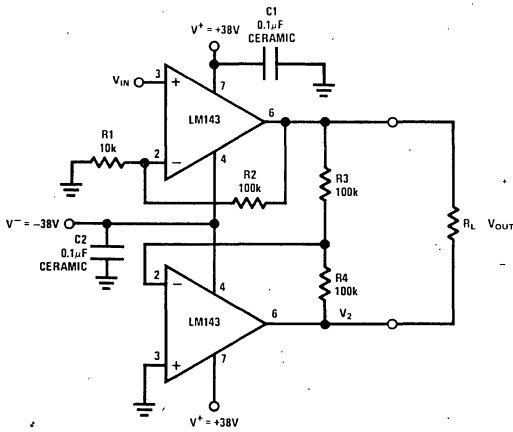
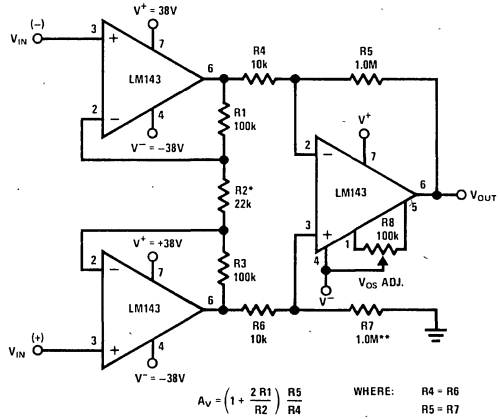


FIGURE 4. Guarded Inverting Amplifier

Typical Applications ‡ (For more detail see AN-127)



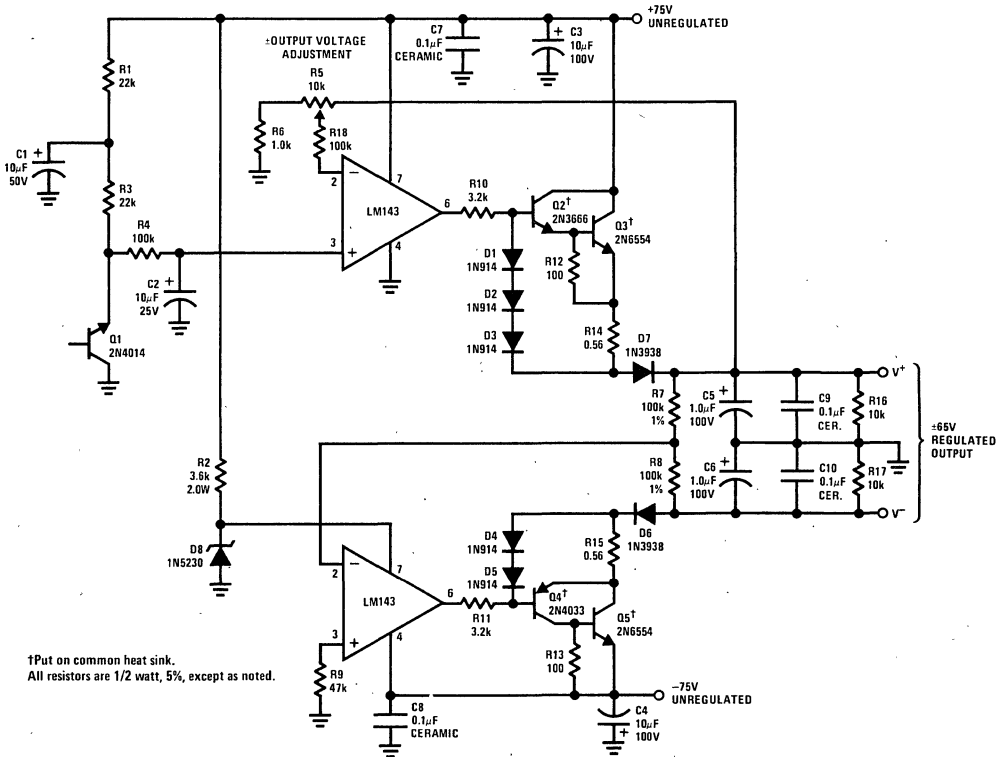
130 V_{p,p} Drive Across a Floating Load



$A_v = \left(1 + \frac{2R_1}{R_2}\right) \frac{R_5}{R_4}$ WHERE: $R_4 = R_6$
 $R_5 = R_7$

*R2 may be adjustable to trim the gain.
 **R7 may be adjusted to compensate for the resistance tolerance of R4 - R7 for best CMR.

±34V Common-Mode Instrumentation Amplifier

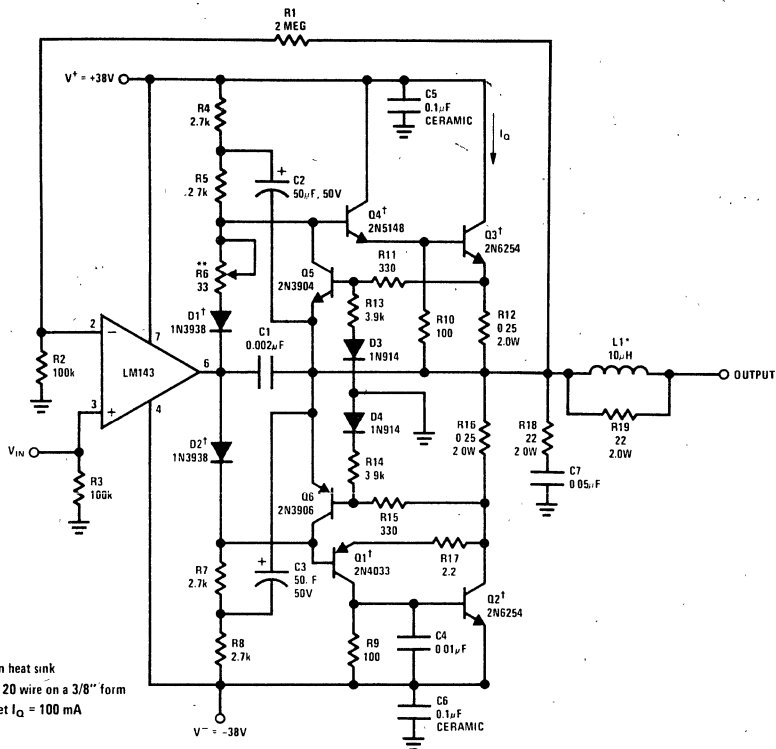


†Put on common heat sink.
 All resistors are 1/2 watt, 5%, except as noted.

Tracking ±65V, 1 Amp Power Supply with Short Circuit Protection

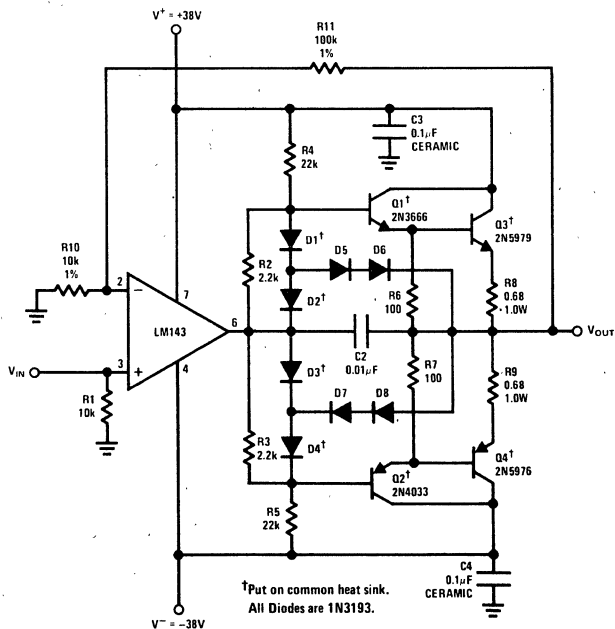
‡The 38V supplies allow for a 5% voltage tolerance. All resistors are 1/2 watt, except as noted.

Typical Applications (Continued) (For more detail see AN-127)



- †Put on common heat sink
- *34 turns of no. 20 wire on a 3/8" form
- **Adjust R6 to set $I_Q = 100$ mA

90W Audio Power Amplifier with Safe Area Protection



- †Put on common heat sink.
- All Diodes are 1N3193.

1 Amp Power Amplifier with Short Circuit Protection

‡The 38V supplies allow for a 5% voltage tolerance. All resistors are 1/2 watt, except as noted.

LM144/LM344 High Voltage, High Slew Rate Operational Amplifier

General Description

The LM144 is a general purpose high voltage, uncompensated operational amplifier featuring operation to $\pm 36V$, complete input overvoltage protection up to the supply voltages and input currents comparable to those of other super- β op amps. Increased slew rate, together with high common-mode and supply rejection, insure excellent performance at high supply voltages. Operating characteristics, in particular supply current, slew rate and gain, are virtually independent of supply voltage and temperature. Furthermore, due to thermal symmetry on the die, gain is unaffected by output loading at high supply voltages.

With the unique advantages of low input current, high gain, and high slew rate, the LM144 can increase accuracy and useful frequency range in many existing applications. For example, the LM144 is a plug-in replacement for the LM101A, as well as other general purpose op amps.

The LM144 can be compensated with a single capacitor, thus giving the user the ability to optimize ac parameters to suit the application. For example, in applications such as audio power amplifiers, the LM144 with a gain of 10 can provide a $\pm 30V$ output swing, a slew rate of approximately $30V/\mu s$, and a 120 kHz full power

bandwidth. In applications where capacitive loads or cables must be driven, the LM144 can be overcompensated for increased stability.

The LM344 is similar to the LM144 for applications in less severe supply voltage and temperature environments.

Features

- External compensation provides large power bandwidth ($A_V \geq 10$) 120 kHz
- Wide operating voltage range $\pm 4.0V$ to $\pm 36V$
- Large output voltage swing $\pm 30V$
- Wide input common-mode range
- Input overvoltage protection
- Electrical characteristics independent of supply voltage and temperature

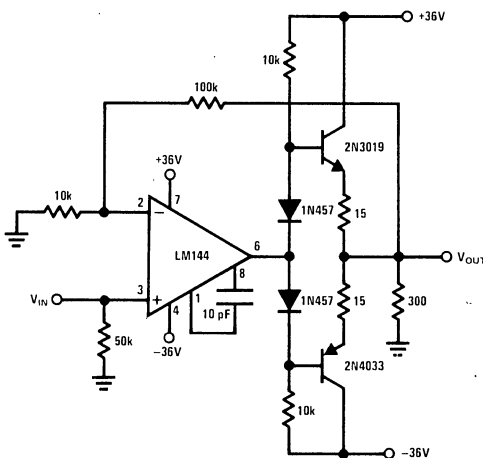
Unique Characteristics

- Low input bias current 8.0 nA
- Low input offset current 1.0 nA
- High slew rate ($A_V \geq 10$) $30V/\mu s$
- High voltage gain 100k min
- Offset voltage null capability

3

Typical Application

Large Power Bandwidth, Current Boosted Audio Line Driver



Absolute Maximum Ratings (These ratings are not concurrent)

| | LM144 | LM344 |
|--|-----------------|-----------------|
| Supply Voltage | ±40V | ±34V |
| Power Dissipation (Note 1) | 680 mW | 680 mW |
| Differential Input Voltage (Note 2) | 80V | 68V |
| Input Voltage (Note 2) | ±40V | ±34V |
| Operating Temperature Range | -55°C to +125°C | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Output Short Circuit Duration | 5 seconds | 5 seconds |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 3)

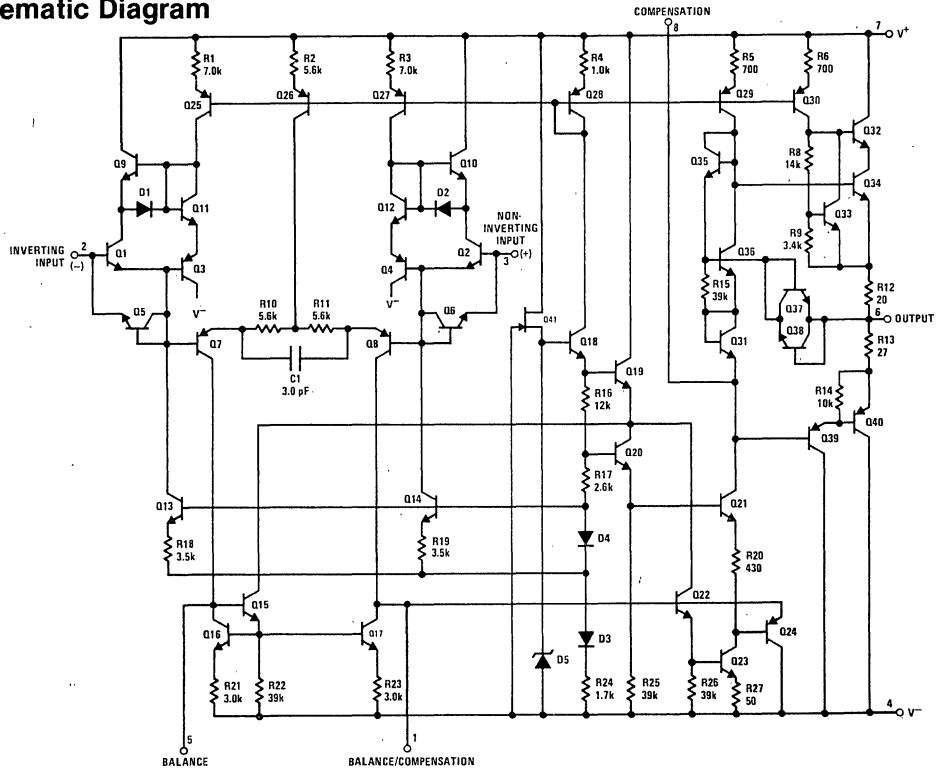
| PARAMETER | CONDITIONS | LM144 | | | LM344 | | | UNITS |
|--------------------------------|---|-------|------|-----|-------|------|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | 2.0 | 5.0 | | 2.0 | 8.0 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 1.0 | 3.0 | | 1.0 | 10 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 8.0 | 20 | | 8.0 | 40 | nA |
| Supply Voltage Rejection Ratio | $T_A = 25^\circ\text{C}$ | | 10 | 100 | | 10 | 200 | $\mu\text{V/V}$ |
| Output Voltage Swing | $T_A = 25^\circ\text{C}$, $R_L \geq 5\text{ k}\Omega$ | 22 | 25 | | 20 | 25 | | V |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_{\text{OUT}} = \pm 10\text{V}$, $R_L \geq 100\text{ k}\Omega$ | 100k | 180k | | 70k | 180k | | V/V |
| Common-Mode Rejection Ratio | $T_A = 25^\circ\text{C}$ | 80 | 90 | | 70 | 90 | | dB |
| Input Voltage Range | $T_A = 25^\circ\text{C}$ | 24 | 26 | | 22 | 26 | | V |
| Supply Current | $T_A = 25^\circ\text{C}$ | | 2.0 | 4.0 | | 2.0 | 5.0 | mA |
| Short Circuit Current | $T_A = 25^\circ\text{C}$ | | 20 | | | 20 | | mA |
| Slew Rate | $T_A = 25^\circ\text{C}$, $A_V = 1$ | | 2.5 | | | 2.5 | | V/ μs |
| | $T_A = 25^\circ\text{C}$, $A_V = 10$, $C_1 = 3\text{ pF}$ | | 30 | | | 30 | | V/ μs |
| Power Bandwidth | $T_A = 25^\circ\text{C}$, $V_{\text{OUT}} = 40\text{ V}_{\text{P-P}}$, $R_L \geq 5\text{ k}\Omega$, $\text{THD} \leq 1\%$, $A_V = 1$ | | 20k | | | 20k | | Hz |
| Unity Gain Frequency | $T_A = 25^\circ\text{C}$ | | 1.0M | | | 1.0M | | Hz |
| Input Offset Voltage | $T_A = \text{Max}$ | | | 6.0 | | | 10 | mV |
| | $T_A = \text{Min}$ | | | 6.0 | | | 10 | mV |
| Input Offset Current | $T_A = \text{Max}$ | | 0.8 | 4.5 | | 0.8 | 14 | nA |
| | $T_A = \text{Min}$ | | 1.8 | 7.0 | | 1.8 | 14 | nA |
| Input Bias Current | $T_A = \text{Max}$ | | 5.0 | 35 | | 5.0 | 55 | nA |
| | $T_A = \text{Min}$ | | 16 | 35 | | 16 | 55 | nA |
| Large Signal Voltage Gain | $R_L \geq 100\text{ k}\Omega$, $T_A = \text{Max}$ | 50k | 150k | | 50k | 150k | | V/V |
| | $R_L \geq 100\text{ k}\Omega$, $T_A = \text{Min}$ | 50k | 220k | | 50k | 220k | | V/V |
| Output Voltage Swing | $R_L \geq 5.0\text{ k}\Omega$, $T_A = \text{Max}$ | 22 | 26 | | 20 | 26 | | V |
| | $R_L \geq 5.0\text{ k}\Omega$, $T_A = \text{Min}$ | 22 | 25 | | 20 | 25 | | V |

Note 1: The maximum junction temperature of the LM144 is 150°C, while that of the LM344 is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: For supply voltage less than ±40V for the LM144 and less than ±34V for the LM344, the absolute maximum input voltage is equal to the supply voltage.

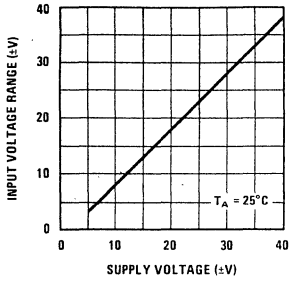
Note 3: These specifications apply for $V_S = \pm 28\text{V}$. For the LM144, $T_A = \text{max} = 125^\circ\text{C}$ and $T_A = \text{min} = -55^\circ\text{C}$. For the LM344, $T_A = \text{max} = 70^\circ\text{C}$ and $T_A = \text{min} = 0^\circ\text{C}$.

Schematic Diagram

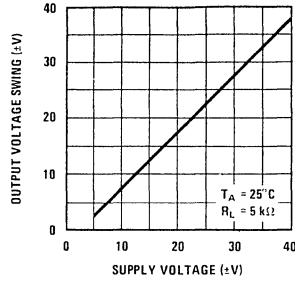


Typical Performance Characteristics

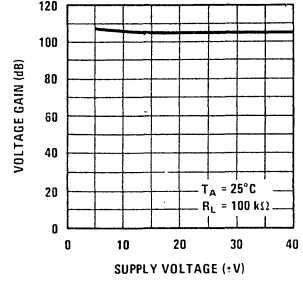
Input Voltage Range



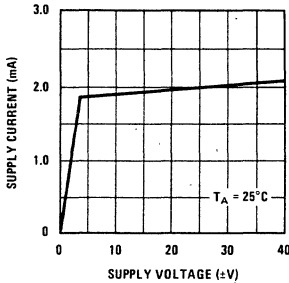
Output Voltage Swing



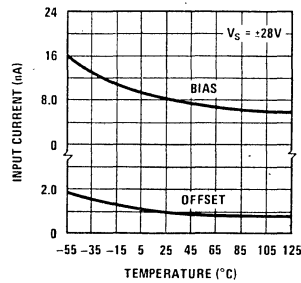
Voltage Gain



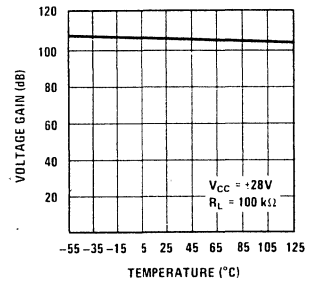
Supply Current



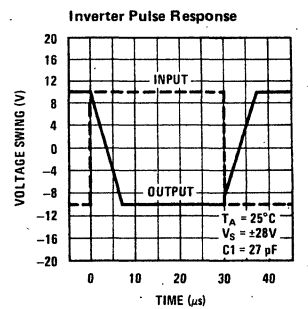
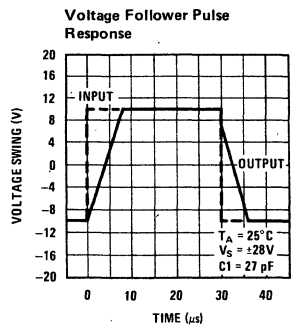
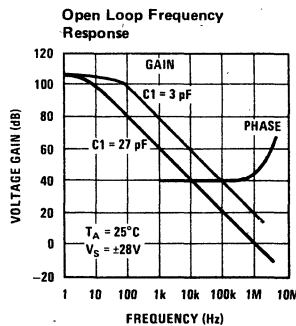
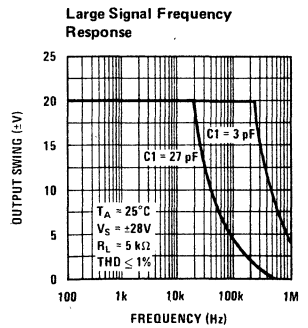
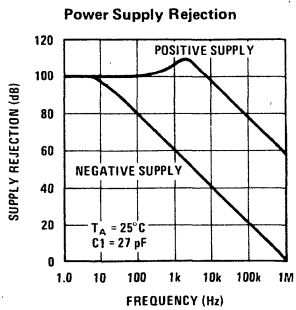
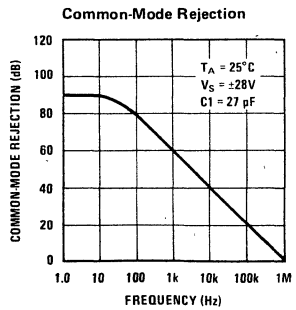
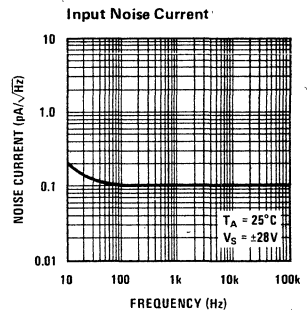
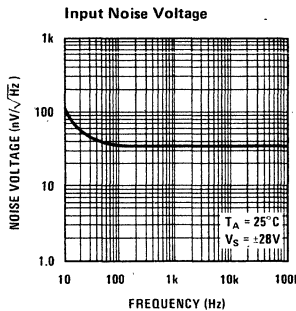
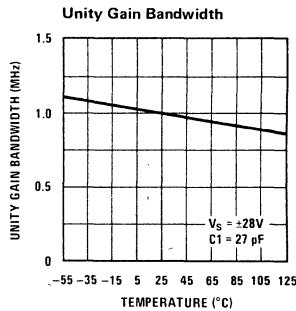
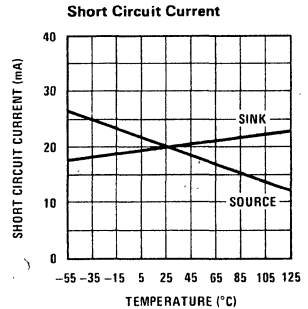
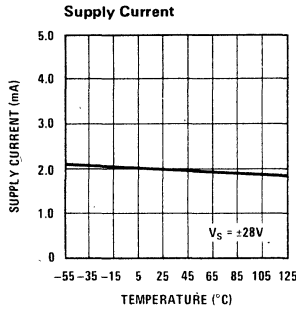
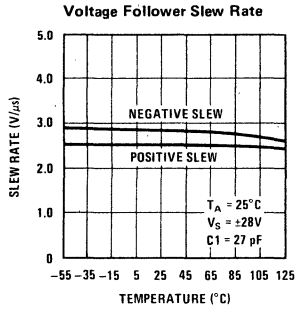
Input Current



Voltage Gain



Typical Performance Characteristics (Continued)



Application Hints (See Also AN-127)

The LM144 is designed for trouble-free operation at any supply voltage up to a maximum of $\pm 40V$. Input over-voltage protection, both common-mode and differential, is 100% tested and guaranteed at the maximum supply voltage. Furthermore, all possible high voltage destructive modes during supply voltage turn-on have been eliminated by design. As with most IC op amps, however, certain precautions should be observed to insure that the LM144 remains virtually blow-out proof.

Although output short circuits to ground or either supply can be sustained indefinitely for supply voltages, below $\pm 18V$, these short circuits should be of limited duration when operating at higher supply voltages. Units can be destroyed by any combination of high ambient temperature, high supply voltages, and high power dissipation which results in excessive die temperature. This is also true when driving low impedance or reactive loads or loads that can revert to low impedance; for example, the LM144 can drive most general purpose op amps outside of their maximum input voltage range, causing heavy current to flow and possibly destroying both devices.

Precautions should be taken to insure that the power supplies never become reversed in polarity—even under transient conditions. With reverse voltage, the IC will conduct excessive current, fusing the internal aluminum interconnects. Voltage reversal between the power supplies will almost always result in a destroyed unit.

In high voltage applications which are sensitive to very low input currents, special precautions should be exer-

cised. For example, with high source resistances, care should be taken to prevent the magnitude of the PC board leakage currents, although quite small, from approaching those of the op amp input currents. These leakage currents become larger at $125^{\circ}C$ and are made worse by high supply voltages. To prevent this, PC boards should be properly cleaned and coated to prevent contamination and to provide protection from condensed water vapor when operation below $0^{\circ}C$. A guard ring is also recommended to significantly reduce leakage currents from the op amp input pins to the adjacent high voltage pins in the standard op amp pin connection as shown in Figure 1. Figures 2, 3 and 4 show how the guard ring is connected for the three most common op amp configurations.

The minimum values given for the frequency compensation capacitor are stable only for source resistances less than $10\text{ k}\Omega$, stray capacitances on the summing junction less than 5 pF and capacitive loads smaller than 100 pF . If any of these conditions are not met, it becomes necessary to overcompensate the amplifier with a larger compensation capacitor. Alternately, lead capacitors can be used in the feedback network to negate the effect of stray capacitance and large feedback resistors or an RC network can be added to isolate capacitive loads. See Figures 5, 6 and 7.

Finally, caution should be exercised in high voltage applications as electrical shock hazards are present. Since the negative supply is connected to the case, users may inadvertently contact voltages equal to those across the power supplies.

3

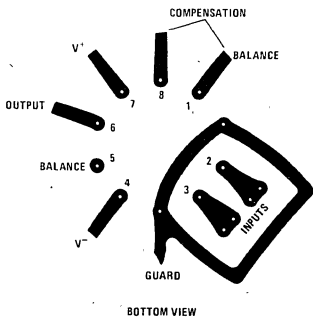


FIGURE 1. Printed Circuit Layout for Input Guarding with TO-5 Package

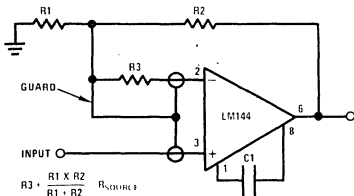


FIGURE 3. Guarded Non-Inverting Amplifier

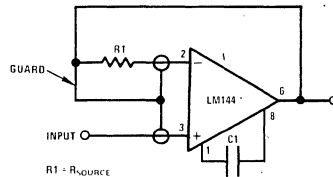


FIGURE 2. Guarded Voltage Follower

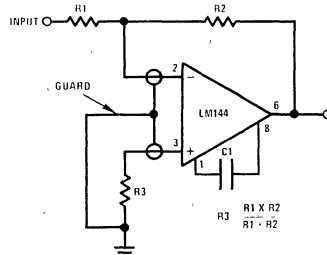


FIGURE 4. Guarded Inverting Amplifier

Application Hints (Continued)

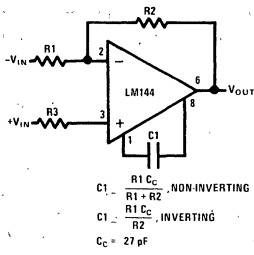


FIGURE 5. Single Pole Compensation

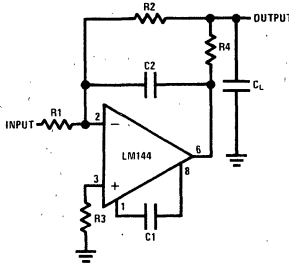


FIGURE 6. Isolating Large Capacitive Loads

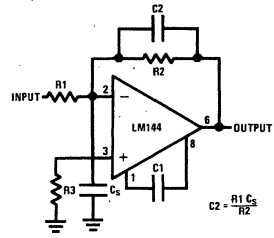


FIGURE 7. Compensating For Stray Input Capacitances or Large Feedback Resistor

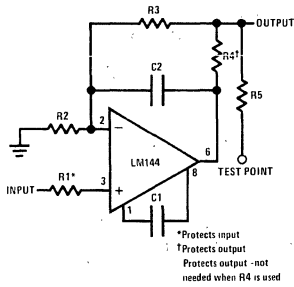


FIGURE 8. Protecting Against Gross Fault Conditions

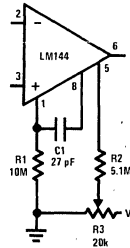
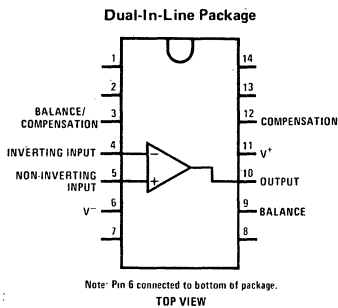
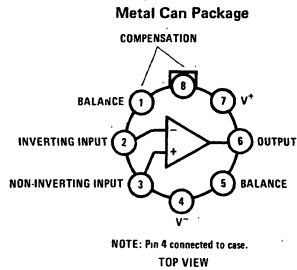


FIGURE 9. Balancing Circuit

Connection Diagrams



Order Number LM144D
or LM344D
See NS Package D14E



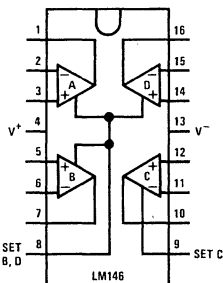
Order Number LM144H
or LM344H
See NS Package H08C

LM146/LM246/LM346 Programmable Quad Operational Amplifiers
General Description

The LM146 series of quad op amps consists of four independent, high gain, internally compensated, low power, programmable amplifiers. Two external resistors (R_{SET}) allow the user to program the gain bandwidth product, slew rate, supply current, input bias current, input offset current and input noise. For example, the user can trade-off supply current for bandwidth or optimize noise figure for a given source resistance. In a similar way, other amplifier characteristics can be tailored to the application. Except for the two programming pins at the end of the package, the LM146 pin-out is the same as the LM124 and LM148.

Features ($I_{SET} = 10 \mu A$)

- Programmable electrical characteristics
- Battery-powered operation
- Low supply current 350 μA amplifier
- Guaranteed gain bandwidth product 0.8 MHz min
- Large DC voltage gain 120 dB
- Low noise voltage 28 nV/\sqrt{Hz}
- Wide power supply range $\pm 1.5V$ to $\pm 22V$
- Class AB output stage—no crossover distortion
- Ideal pin out for Biquad active filters
- Input bias currents are temperature compensated

Connection Diagrams (Dual-In-Line Packages, Top Views)


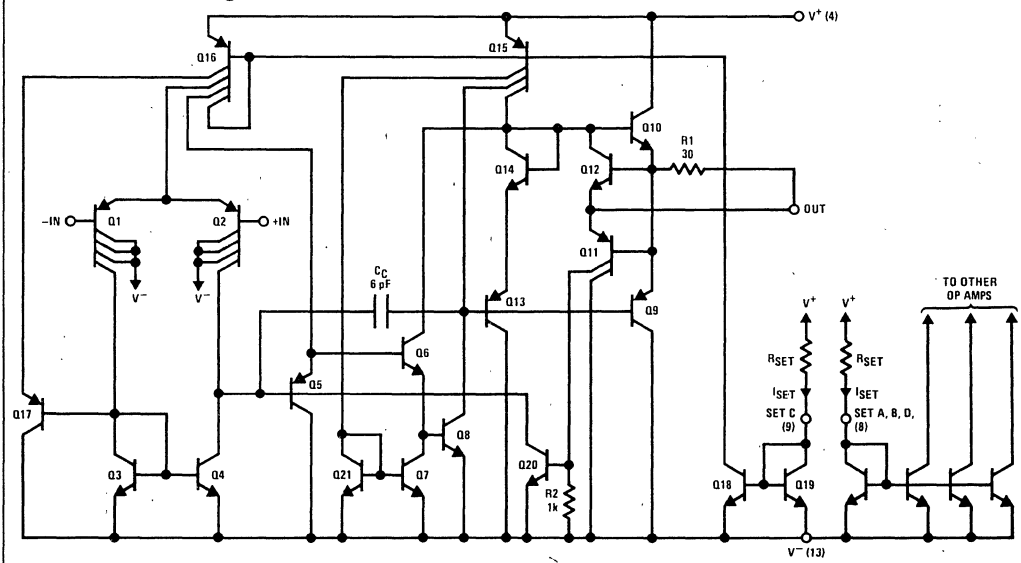
Order Number LM146J, LM246J or LM346J
See NS Package J16A

Order Number LM246N or LM346N
See NS Package N16A

PROGRAMMING EQUATIONS

Total Supply Current = 1.4 mA ($I_{SET}/10 \mu A$)
 Gain Bandwidth Product = 1 MHz ($I_{SET}/10 \mu A$)
 Slew Rate = 0.4V/ μs ($I_{SET}/10 \mu A$)
 Input Bias Current ≈ 50 nA ($I_{SET}/10 \mu A$)
 I_{SET} = Current into pin 8, pin 9 (see schematic-diagram)

$$I_{SET} = \frac{V^+ - V^- - 0.6V}{R_{SET}}$$

Schematic Diagram


Absolute Maximum Ratings (Note 1)

| | LM146 | LM246 | LM346 |
|--|-----------------|-----------------|-----------------|
| Supply Voltage | ±22V | ±18V | ±18V |
| Differential Input Voltage (Note 1) | ±30V | ±30V | ±30V |
| CM Input Voltage (Note 1) | ±15V | ±15V | ±15V |
| Power Dissipation (Note 2) | 900 mW | 500 mW | 500 mW |
| Output Short-Circuit Duration (Note 3) | Indefinite | Indefinite | Indefinite |
| Operating Temperature Range | -55°C to +125°C | -25°C to +85°C | 0°C to +70°C |
| Maximum Junction Temperature | 150°C | 110°C | 100°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | 300°C |
| Thermal Resistance (θ_{jA}), (Note 2) | | | |
| Cavity DIP (D) (J) | P_d | 900 mW | 900 mW |
| | θ_{jA} | 90°C/W | 90°C/W |
| Molded DIP (N) | P_d | 900 mW | 500 mW |
| | θ_{jA} | 90°C/W | 140°C/W |

DC Electrical Characteristics ($V_S = \pm 15V$, $I_{SET} = 10 \mu A$, Note 4)

| PARAMETER | CONDITIONS | LM146 | | | LM246/LM346 | | | UNITS |
|------------------------------|---|-------|------|-----|-------------|------|-----|-----------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $V_{CM} = 0V$, $R_S \leq 50 \Omega$, $T_A = 25^\circ C$ | | 0.5 | 5 | | 0.5 | 6 | mV |
| Input Offset Current | $V_{CM} = 0V$, $T_A = 25^\circ C$ | | 2 | 20 | | 2 | 100 | nA |
| Input Bias Current | $V_{CM} = 0V$, $T_A = 25^\circ C$ | | 50 | 100 | | 50 | 250 | nA |
| Supply Current (4 Op Amps) | $T_A = 25^\circ C$ | | 1.4 | 2.0 | | 1.4 | 2.5 | mA |
| Large Signal Voltage Gain | $R_L = 10 k\Omega$, $\Delta V_{OUT} = \pm 10V$, $T_A = 25^\circ C$ | 100 | 1000 | | 50 | 1000 | | V/mV |
| Input CM Range | $T_A = 25^\circ C$ | ±13.5 | ±14 | | ±13.5 | ±14 | | V |
| CM Rejection Ratio | $R_S \leq 10 k\Omega$, $T_A = 25^\circ C$ | 80 | 100 | | 70 | 100 | | dB |
| Power Supply Rejection Ratio | $R_S \leq 10 k\Omega$, $T_A = 25^\circ C$ | 80 | 100 | | 74 | 100 | | dB |
| Output Voltage Swing | $R_L \geq 10 k\Omega$, $T_A = 25^\circ C$ | ±12 | ±14 | | ±12 | ±14 | | V |
| Short-Circuit Current | $T_A = 25^\circ C$ | 5 | 20 | 30 | 5 | 20 | 30 | mA |
| Gain Bandwidth Product | $T_A = 25^\circ C$ | 0.8 | 1.2 | | 0.5 | 1.2 | | MHz |
| Phase Margin | $T_A = 25^\circ C$ | | 60 | | | 60 | | Deg |
| Slew Rate | $T_A = 25^\circ C$ | | 0.4 | | | 0.4 | | V/ μs |
| Input Noise Voltage | $f = 1 kHz$, $T_A = 25^\circ C$ | | 28 | | | 28 | | nV/ \sqrt{Hz} |
| Channel Separation | $R_L = 10 k\Omega$, $\Delta V_{OUT} = 0V$ to $\pm 12V$, $T_A = 25^\circ C$ | | 120 | | | 120 | | dB |
| Input Resistance | $T_A = 25^\circ C$ | | 1.0 | | | 1.0 | | M Ω |
| Input Capacitance | $T_A = 25^\circ C$ | | 2.0 | | | 2.0 | | pF |
| Input Offset Voltage | $V_{CM} = 0V$, $R_S \leq 50 \Omega$ | | 0.5 | 6 | | 0.5 | 7.5 | mV |
| Input Offset Current | $V_{CM} = 0V$ | | 2 | 25 | | 2 | 100 | nA |
| Input Bias Current | $V_{CM} = 0V$ | | 50 | 100 | | 50 | 250 | nA |
| Supply Current (4 Op Amps) | | | 1.5 | 2.0 | | 1.5 | 2.5 | mA |
| Large Signal Voltage Gain | $R_L = 10 k\Omega$, $\Delta V_{OUT} = \pm 10V$ | 50 | 1000 | | 25 | 1000 | | V/mV |
| Input CM Range | | ±13.5 | ±14 | | ±13.5 | ±14 | | V |
| CM Rejection Ratio | $R_S \leq 50 \Omega$ | 70 | 100 | | 70 | 100 | | dB |
| Power Supply Rejection Ratio | $R_S \leq 50 \Omega$ | 76 | 100 | | 74 | 100 | | dB |
| Output Voltage Swing | $R_L \geq 10 k\Omega$ | ±12 | ±14 | | ±12 | ±14 | | V |

DC Electrical Characteristics (V_S = ±15V, I_{SET} = 1 μA)

| PARAMETER | CONDITIONS | LM146 | | | LM246/LM346 | | | UNITS |
|----------------------------|--|-------|-----|-----|-------------|-----|-----|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | V _{CM} = 0V, R _S ≤ 50 Ω, T _A = 25°C | | 0.5 | 5 | | 0.5 | 7 | mV |
| Input Bias Current | V _{CM} = 0V, T _A = 25°C | | 7.5 | 20 | | 7.5 | 100 | nA |
| Supply Current (4 Op Amps) | T _A = 25°C | | 140 | 250 | | 140 | 300 | μA |
| Gain Bandwidth Product | T _A = 25°C | 80 | 100 | | 50 | 100 | | kHz |

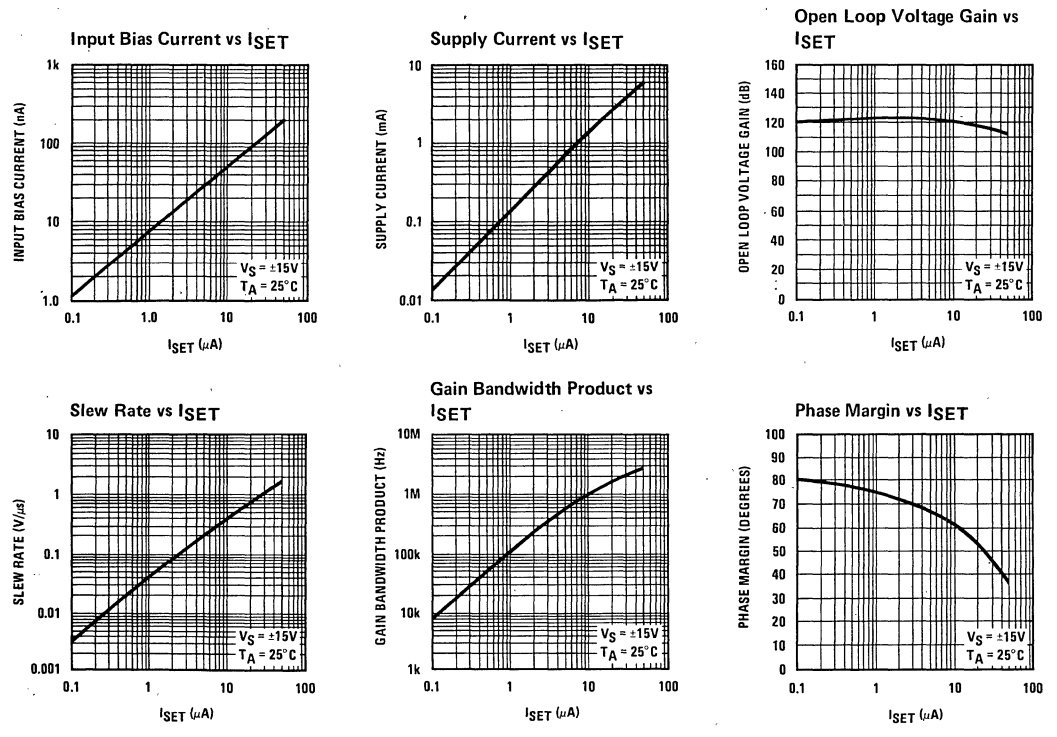
DC Electrical Characteristics (V_S = ±1.5V, I_{SET} = 10 μA)

| PARAMETER | CONDITIONS | LM146 | | | LM246/LM346 | | | UNITS |
|----------------------|--|-------|-----|-----|-------------|-----|-----|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | V _{CM} = 0V, R _S ≤ 50 Ω, T _A = 25°C | | 0.5 | 5 | | 0.5 | 7 | mV |
| Input CM Range | T _A = 25°C | ±0.7 | | | ±0.7 | | | V |
| CM Rejection Ratio | R _S ≤ 50 Ω, T _A = 25°C | | 80 | | | 80 | | dB |
| Output Voltage Swing | R _L ≥ 10 kΩ, T _A = 25°C | ±0.6 | | | ±0.6 | | | V |

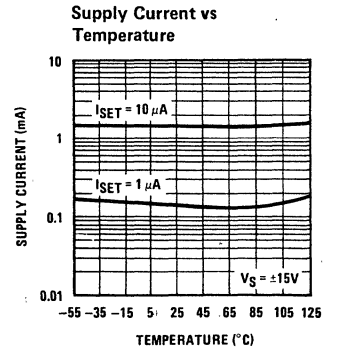
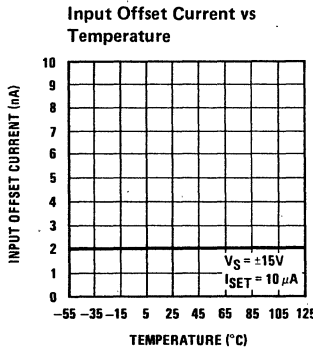
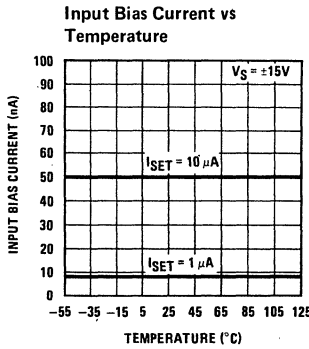
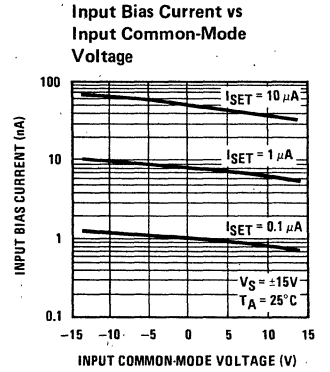
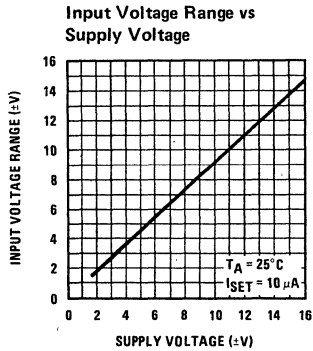
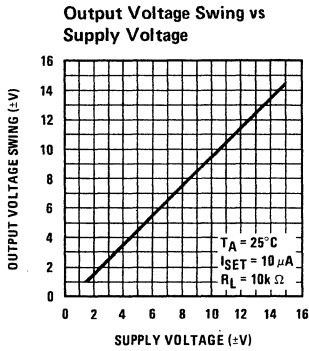
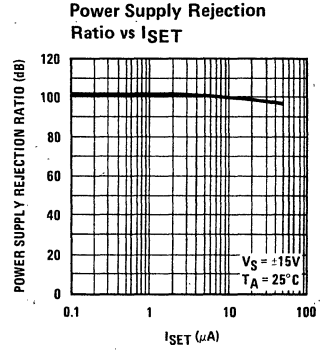
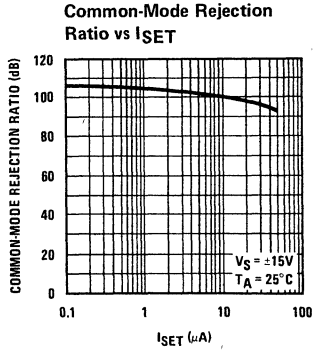
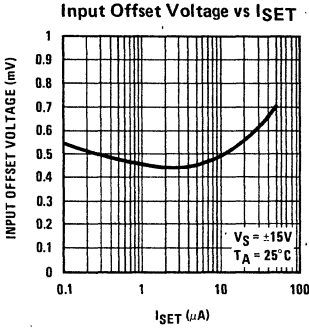
- Note 1:** For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.
- Note 2:** The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX}, θ_{J A}, and the ambient temperature, T_A. The maximum available power dissipation at any temperature is P_D = (T_{JMAX} - T_A)/θ_{J A} or the 25°C P_{DMAX}, whichever is less.
- Note 3:** Any of the amplifier outputs can be shorted to ground indefinitely; however, more than one should not be simultaneously shorted as the maximum junction temperature will be exceeded.
- Note 4:** These specifications apply over the absolute maximum operating temperature range unless otherwise noted.

3

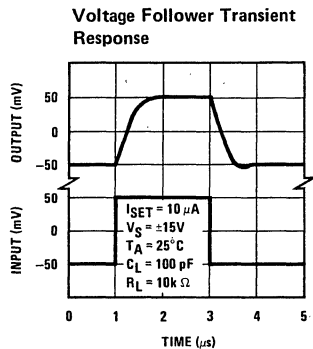
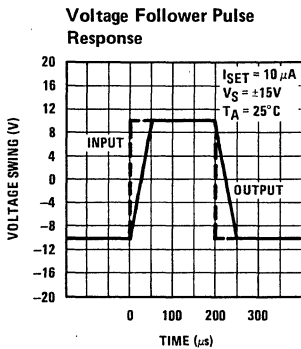
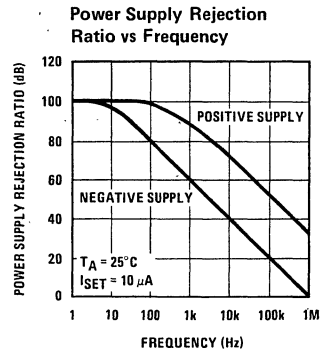
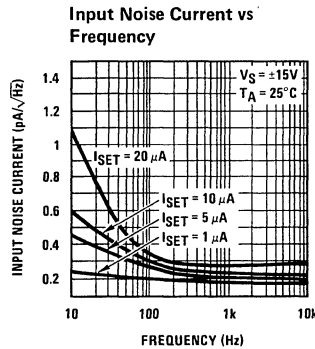
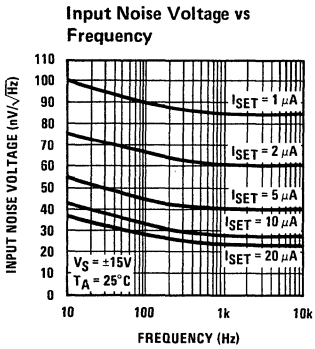
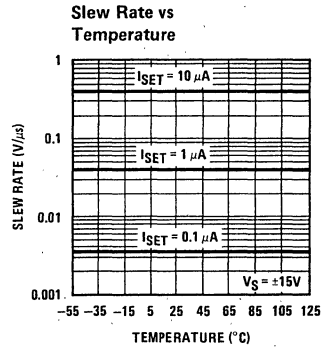
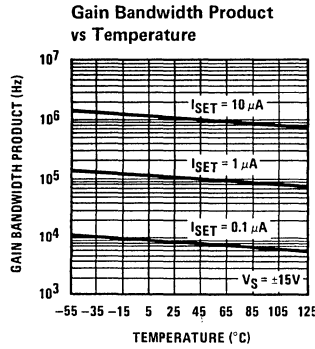
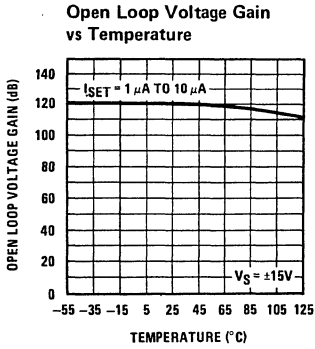
Typical Performance Characteristics



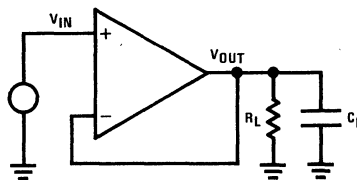
Typical Performance Characteristics (Continued)



Typical Performance Characteristics (Continued)



Transient Response Test Circuit



Application Hints

Avoid reversing the power supply polarity, the device will fail.

Common-Mode Input Voltage: The negative common-mode voltage limit is one diode drop above the negative supply voltage. Exceeding this limit on either input will result in an output phase reversal. The positive common-mode limit is typically 1V below the positive supply voltage. No output phase reversal will occur if this limit is exceeded by either input.

Output Voltage Swing vs I_{SET}: For a desired output voltage swing the value of the minimum load depends on the positive and negative output current capability of the op amp. The maximum available positive output current, (I_{CL+}), of the device increases with I_{SET} whereas the negative output current (I_{CL-}) is independent of I_{SET}. Figure 1 illustrates the above.

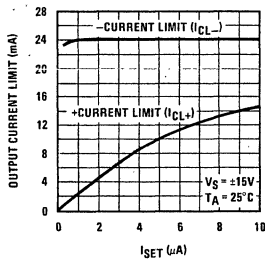


FIGURE 1. Output Current Limit vs I_{SET}

Input Capacitance: The input capacitance, C_{IN}, of the LM146 is approximately 2 pF; any stray capacitance, C_S, (due to external circuit circuit layout) will add to C_{IN}. When resistive or active feedback is applied, an additional pole is added to the open loop frequency response of the device. For instance with resistive feedback (Figure 2), this pole occurs at 1/2π (R₁||R₂) (C_{IN} + C_S). Make sure that this pole occurs at least 2 octaves beyond the expected -3 dB frequency corner of the closed loop gain of the amplifier; if not, place a lead capacitor in the feedback such that the time constant of this capacitor and the resistance it parallels is equal to the R₁(C_S + C_{IN}), where R₁ is the input resistance of the circuit.

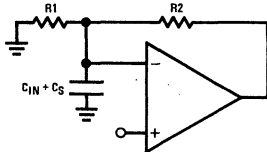


FIGURE 2

Temperature Effect on the GBW: The GBW (gain bandwidth product), of the LM146 is directly proportional to I_{SET} and inversely proportional to the absolute temperature. When using resistors to set the bias current, I_{SET}, of the device, the GBW product will decrease with increasing temperature. Compensation can be provided by creating an I_{SET} current directly proportional to temperature (see typical applications).

Isolation Between Amplifiers: The LM146 die is isothermally laid out such that crosstalk between all 4 amplifiers is in excess of -105 dB (DC). Optimum isolation (better than -110 dB) occurs between amplifiers A and D, B and C; that is, if amplifier A dissipates power on its output stage, amplifier D is the one which will be affected the least, and vice versa. Same argument holds for amplifiers B and C.

LM146 Typical Performance Summary: The LM146 typical behavior is shown in Figure 3. The device is fully predictable. As the set current, I_{SET}, increases, the speed, the bias current, and the supply current increase while the noise power decreases proportionally and the V_{OS} remains constant. The usable GBW range of the op amp is 10 kHz to 3.5-4 MHz.

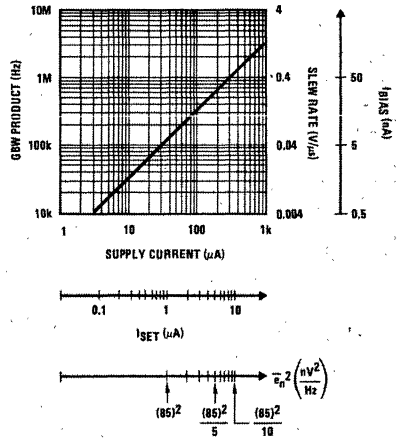


FIGURE 3. LM146 Typical Characteristics

Low Power Supply Operation: The quad op amp operates down to ±1.3V supply. Also, since the internal circuitry is biased through programmable current sources, no degradation of the device speed will occur.

Speed vs Power Consumption: LM146 vs LM4250 (single programmable). Through Figure 4, we observe that the LM146's power consumption has been optimized for GBW products above 200 kHz, whereas the LM4250 will reach a GBW of no more than 300 kHz, for GBW products below 200 kHz, the LM4250 will consume less.

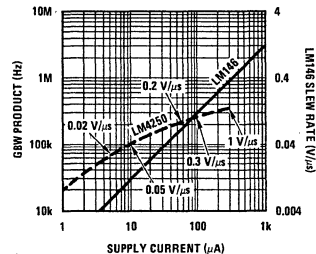
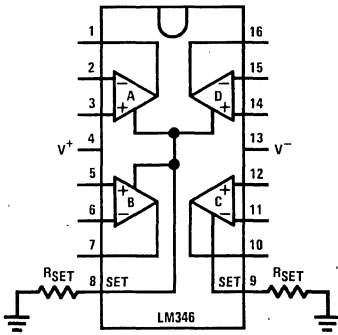


FIGURE 4. LM146 vs LM4250

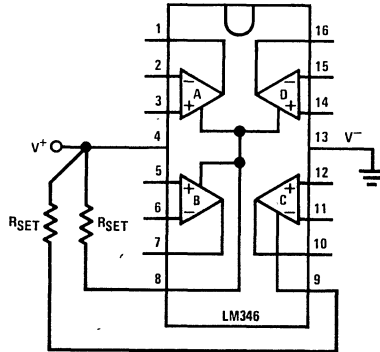
Typical Applications

Dual Supply or Negative Supply Biasing



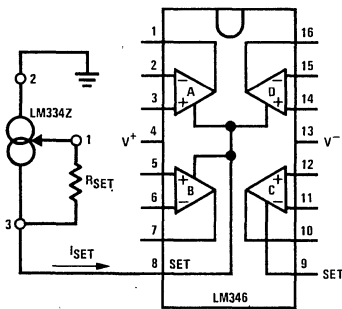
$$I_{SET} \approx \frac{|V^-| - 0.6V}{R_{SET}}$$

Single (Positive) Supply Biasing



$$I_{SET} \approx \frac{V^+ - 0.6V}{R_{SET}}$$

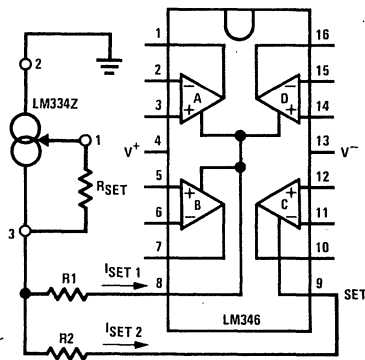
Current Source Biasing with Temperature Compensation



$$I_{SET} = \frac{67.7 \text{ mV}}{R_{SET}}$$

- The LM334 provides an I_{SET} directly proportional to absolute temperature. This cancels the slight GBW product temperature coefficient of the LM346.

Biasing all 4 Amplifiers with Single Current Source

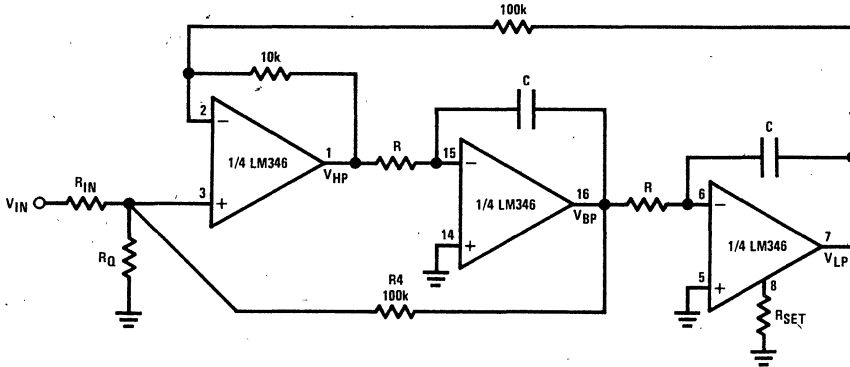


$$\frac{I_{SET1}}{I_{SET2}} = \frac{R2}{R1}, I_{SET1} + I_{SET2} = \frac{67.7 \text{ mV}}{R_{SET}}$$

- For $I_{SET1} \approx I_{SET2}$ resistors R1 and R2 are not required if a slight error between the 2 set currents can be tolerated. If not, then use $R1 = R2$ to create a 100 mV drop across these resistors.

Active Filters Applications

Basic (Non-Inverting "State Variable") Active Filter Building Block



- The LM146 quad programmable op amp is especially suited for active filters because of their adequate GBW product and low power consumption.

Circuit synthesis equations (for circuit analysis equations, consult with the AF100 and LM148 data sheet).

Need to know desired:
 f_o = center frequency measured at the BP output
 Q_o = quality factor measured at the BP output
 H_o = gain at the output of interest (BP or HP or LP or all of them)

- Relation between different gains: $H_o(BP) = 0.316 \times Q_o \times H_o(LP)$; $H_o(LP) = 10 \times H_o(HP)$

$R \times C = \frac{5.033 \times 10^{-2}}{f_o}$ (sec)

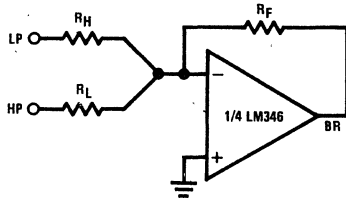
For BP output: $R_Q = \left(\frac{3.478 Q_o - H_o(BP)}{10^5} - \frac{H_o(BP)}{10^5 \times 3.478 \times Q_o} \right)^{-1}$; $R_{IN} = \frac{(3.478 Q_o - 1)}{\frac{1}{R_Q} + 10^{-5}}$

For HP output: $R_Q = \frac{1.1 \times 10^5}{3.478 Q_o (1.1 - H_o(HP)) - H_o(HP)}$; $R_{IN} = \frac{1.1}{\frac{H_o(HP)}{1} + 10^{-5}} - 1$

Note. All resistor values are given in ohms.

For LP output: $R_Q = \frac{11 \times 10^5}{3.478 Q_o (11 - H_o(LP)) - H_o(LP)}$; $R_{IN} = \frac{11}{\frac{H_o(LP)}{1} + 10^{-5}} - 1$

- For BR (notch) output: Use the 4th amplifier of the LM146 to sum the LP and HP outputs of the basic filter.



$$\sqrt{\frac{R_H}{R_L}} = 0.316 \frac{f_{notch}}{f_o}$$

Determine R_F according to the desired gains: $H_o(BR) |_{f \ll f_{notch}} = \frac{R_F}{R_L} H_o(LP)$, $H_o(BR) |_{f \gg f_{notch}} = \frac{R_F}{R_H} H_o(HP)$

- Where to use amplifier C: Examine the above gain relations and determine the dynamics of the filter. Do not allow slew rate limiting in any output (V_{HP} , V_{BP} , V_{LP}), that is:

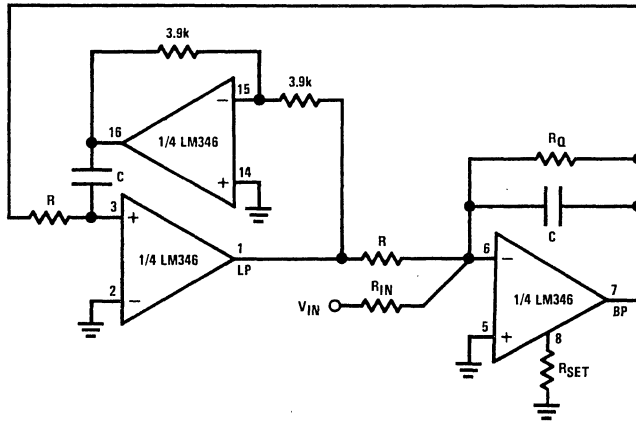
$$V_{IN(peak)} < 63.66 \times 10^3 \times \frac{I_{SET}}{10 \mu A} \times \frac{1}{f_o \times H_o}$$
 (Volts)

If necessary, use amplifier C, biased at higher I_{SET} , where you get the largest output swing.

Deviation from Theoretical Predictions: Due to the finite GBW products of the op amps the f_o , Q_o will be slightly different from the theoretical predictions.

$$f_{real} \approx \frac{f_o}{1 + \frac{2 f_o}{GBW}}, \quad Q_{real} \approx \frac{Q_o}{1 - \frac{3.2 f_o \times Q_o}{GBW}}$$

A Simple-to-Design BP, LP Filter Building Block



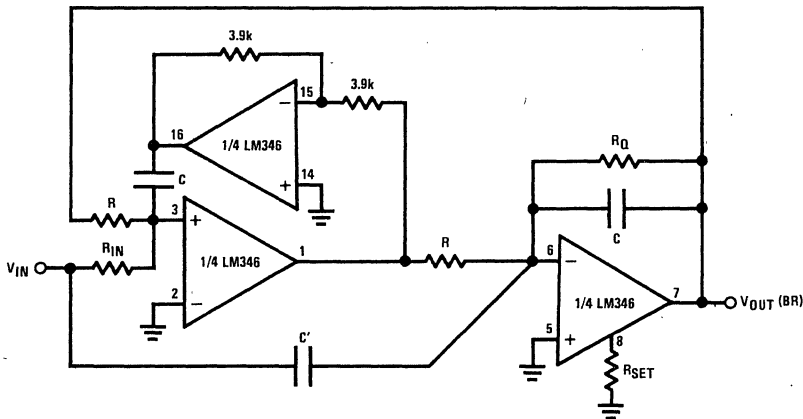
- If resistive biasing is used to set the LM346 performance, the Q_o of this filter building block is nearly insensitive to the op amp's GBW product; temperature drift; it has also better noise performance than the state variable filter.

Circuit Synthesis Equations

$$H_o(BP) = Q_o H_o(LP); R \times C = \frac{0.159}{f_o}; R_Q = Q_o \times R; R_{IN} = \frac{R_Q}{H_o(BP)} = \frac{R}{H_o(LP)}$$

- For the eventual use of amplifier C, see comments on the previous page.

A 3-Amplifier Notch Filter (or Elliptic Filter Building Block)



Circuit Synthesis Equations

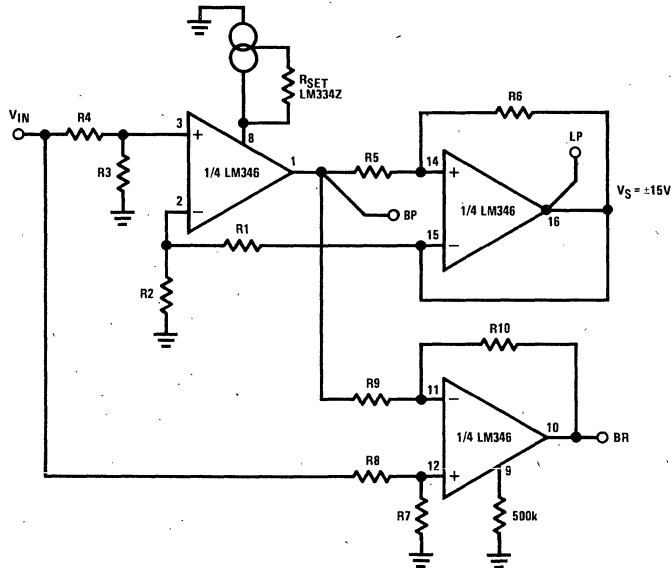
$$R \times C = \frac{0.159}{f_o}; R_Q = Q_o \times R; R_{IN} = \frac{0.159 \times f_o}{C' \times f_{notch}^2}$$

$$H_o(BR) \Big|_{f \ll f_{notch}} = \frac{R}{R_{IN}} H_o(BR) \Big|_{f \gg f_{notch}} = \frac{C'}{C}$$

- For nothing but a notch output: $R_{IN} = R, C' = C$.

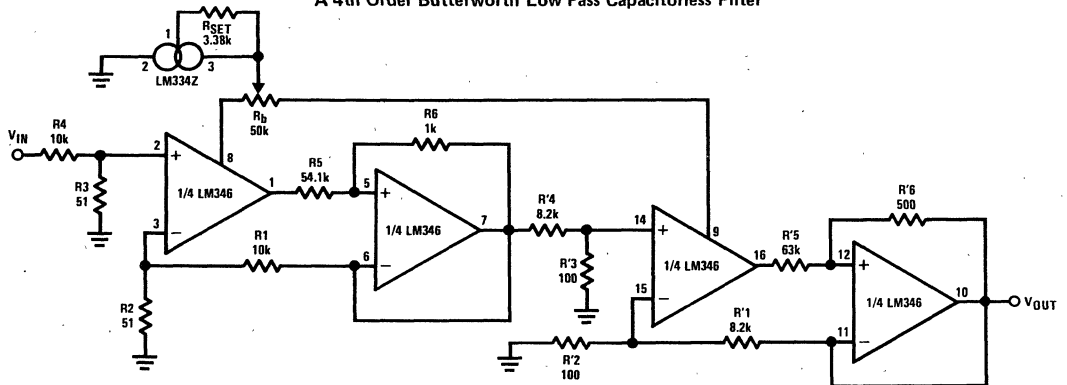
Active Filters Applications (Continued)

Capacitorless Active Filters (Basic Circuit)



- This is a BP, LP, BR filter. The filter characteristics are created by using the tunable frequency response of the LM346.
- **Limitations:** $Q_0 < 10$, $f_o \times Q_0 < 1.5$ MHz, output voltage should not exceed $V_{peak(out)} \leq \frac{63.66 \times 10^3}{f_o} \times \frac{I_{SET} (\mu A)}{10 \mu A}$ (V)
- Design equations: $a = \frac{R6 + R5}{R6}$, $b = \frac{R2}{R1 + R2}$, $c = \frac{R3}{R3 + R4}$, $d = \frac{R7}{R8 + R7}$, $e = \frac{R10}{R9 + R10}$, $f_o(BP) = f_u \sqrt{\frac{b}{a}}$, $H_o(BP) = a \times c$
 $H_o(LP) = \frac{c}{b}$, $Q_o = \sqrt{a \times b}$
 $f_o(BR) = f_o(BP) \left(1 - \frac{c}{b}\right) \approx f_o(BP)$ ($C \ll 1$) provided that $d = H_o(BP) \times e$, $H_o(BR) = \frac{R10}{R9}$.
- Advantage: f_o , Q_o , H_o can be independently adjusted; that is, the filter is extremely easy to tune.
- Tuning procedure (ex. BP tuning)
 1. Pick up a convenient value for b ; ($b < 1$)
 2. Adjust Q_o through $R5$
 3. Adjust $H_o(BP)$ through $R4$
 4. Adjust f_o through R_{SET}

A 4th Order Butterworth Low Pass Capacitorless Filter

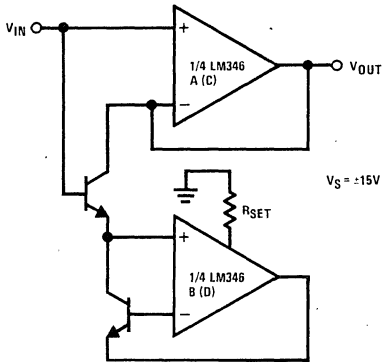


Ex: $f_c = 20$ kHz, H_o (gain of the filter) = 1, $Q_{o1} = 0.541$, $Q_{o2} = 1.306$.

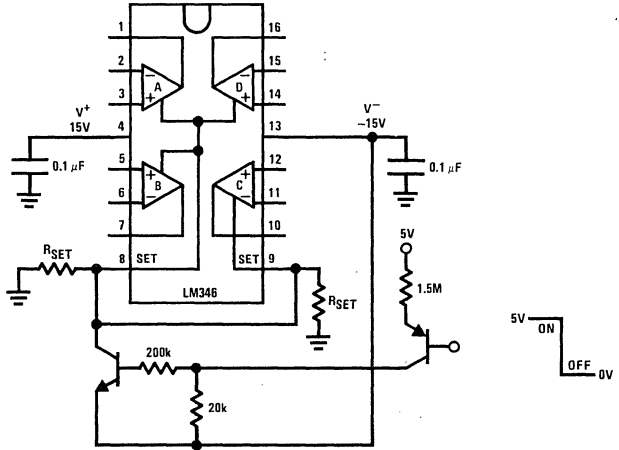
- Since for this filter the GBW product of all 4 amplifiers has been designed to be the same (~ 1 MHz) only one current source can be used to bias the circuit. Fine tuning can be further accomplished through R_b .

Miscellaneous Applications

A Unity Gain Follower with Bias Current Reduction



Circuit Shutdown

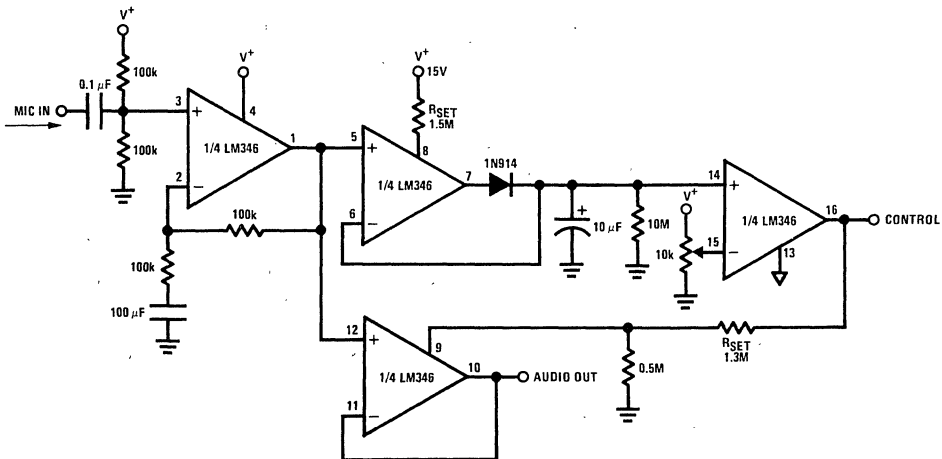


- For better performance, use a matched NPN pair.

- By pulling the SET pin(s) to V^- the op amp(s) shuts down and its output goes to a high impedance state. According to this property, the LM346 can be used as a very low speed analog switch.

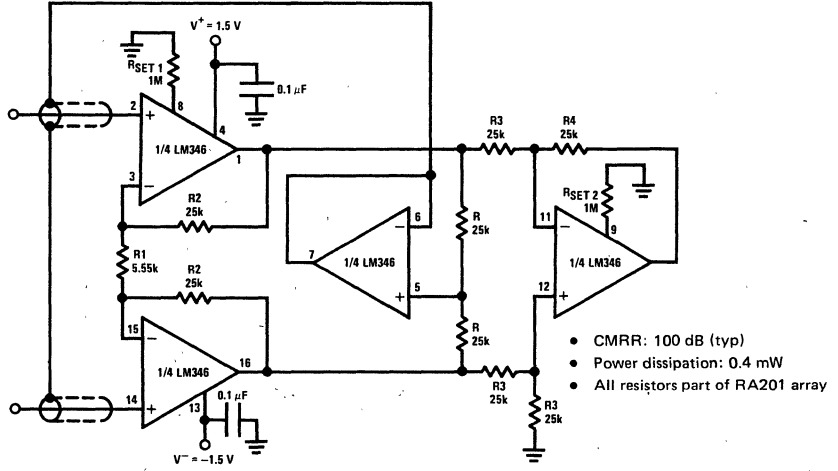
3

Voice Activated Switch and Amplifier



Miscellaneous Applications (Continued)

X10 Micropower Instrumentation Amplifier with Buffered Input Guarding



LM148, LM149 Series Quad 741 Op Amps

LM148/LM248/LM348 quad 741 op amps

LM149/LM249/LM349 wide band decompensated ($A_{V(MIN)} = 5$)

General Description

The LM148 series is a true quad 741. It consists of four independent, high gain, internally compensated, low power operational amplifiers which have been designed to provide functional characteristics identical to those of the familiar 741 operational amplifier. In addition the total supply current for all four amplifiers is comparable to the supply current of a single 741 type op amp. Other features include input offset currents and input bias current which are much less than those of a standard 741. Also, excellent isolation between amplifiers has been achieved by independently biasing each amplifier and using layout techniques which minimize thermal coupling. The LM149 series has the same features as the LM148 plus a gain bandwidth product of 4 MHz at a gain of 5 or greater.

The LM148 can be used anywhere multiple 741 or 1558 type amplifiers are being used and in applications where amplifier matching or high packing density is required.

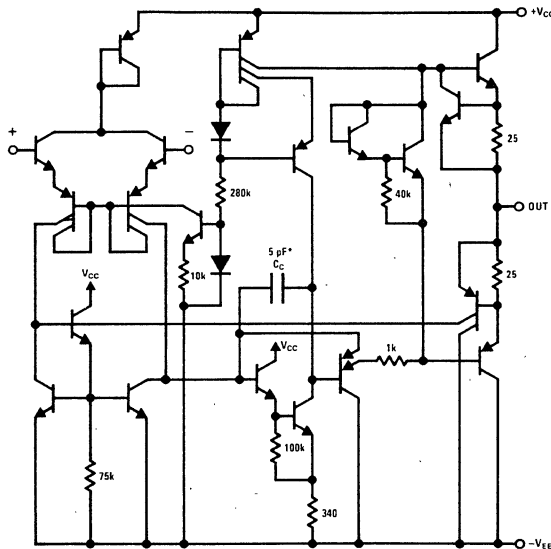
Features

- 741 op amp operating characteristics
- Low supply current drain 0.6 mA/Amplifier
- Class AB output stage—no crossover distortion
- Pin compatible with the LM124
- Low input offset voltage 1 mV
- Low input offset current 4 nA
- Low input bias current 30 nA
- Gain bandwidth product

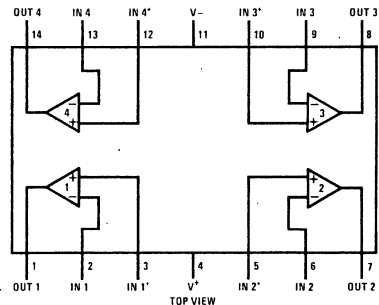
| | |
|------------------------|---------|
| LM148 (unity gain) | 1.0 MHz |
| LM149 ($A_V \geq 5$) | 4 MHz |
- High degree of isolation between amplifiers 120 dB
- Overload protection for inputs and outputs

3

Schematic and Connection Diagrams



Dual-In-Line Package



Order Number LM148J, LM248J, LM348J,
LM149J, LM249J or LM349J
See NS Package J14A
Order Number LM348N or LM349N
See NS Package N14A

Absolute Maximum Ratings

| | LM148/LM149 | LM248/LM249 | LM348/LM349 |
|---|---------------------------------------|-----------------------|---------------------|
| Supply Voltage | ±22V | ±18V | ±18V |
| Differential Input Voltage | ±44V | ±36V | ±36V |
| Input Voltage | ±22V | ±18V | ±18V |
| Output Short Circuit Duration (Note 1) | Continuous | Continuous | Continuous |
| Power Dissipation (P_d at 25°C) and Thermal Resistance (θ_{JA}), (Note 2) | | | |
| Molded DIP (N) | P_d — θ_{JA} — | — — | 500 mW 150°C/W |
| Cavity DIP (J) | P_d 900 mW θ_{JA} 100°C/W | 900 mW 100°C/W | 900 mW 100°C/W |
| Maximum Junction Temperature (T_{JMAX}) | 150°C | 110°C | 100°C |
| Operating Temperature Range | -55°C ≤ T_A ≤ +125°C | -25°C ≤ T_A ≤ +85°C | 0°C ≤ T_A ≤ +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 60 seconds) | 300°C | 300°C | 300°C |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LM148/LM149 | | | LM248/LM249 | | | LM348/LM349 | | | UNITS |
|---------------------------------|---|-------------|------------|-----|-------------|------------|-----|-------------|------------|-----|--------------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $R_S \leq 10\text{ k}\Omega$ | | 1.0 | 5.0 | | 1.0 | 6.0 | | 1.0 | 6.0 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 4 | 25 | | 4 | 50 | | 4 | 50 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 30 | 100 | | 30 | 200 | | 30 | 200 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 0.8 | 2.5 | | 0.8 | 2.5 | | 0.8 | 2.5 | | MΩ |
| Supply Current All Amplifiers | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 2.4 | 3.6 | | 2.4 | 4.5 | | 2.4 | 4.5 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L \geq 2\text{ k}\Omega$ | 50 | 160 | | 25 | 160 | | 25 | 160 | | V/mV |
| Amplifier to Amplifier Coupling | $T_A = 25^\circ\text{C}$, $f = 1\text{ Hz to } 20\text{ kHz}$ (Input Referred) See Crosstalk Test Circuit | | -120 | | | -120 | | | -120 | | dB |
| Small Signal Bandwidth | $T_A = 25^\circ\text{C}$ LM148 series LM149 series | | 1.0 4.0 | | | 1.0 4.0 | | | 1.0 4.0 | | MHz MHz |
| Phase Margin | $T_A = 25^\circ\text{C}$ LM148 series ($A_V = 1$) LM149 series ($A_V = 5$) | | 60 60 | | | 60 60 | | | 60 60 | | degrees degrees |
| Slew Rate | $T_A = 25^\circ\text{C}$ LM148 series ($A_V = 1$) LM149 series ($A_V = 5$) | | 0.5 2.0 | | | 0.5 2.0 | | | 0.5 2.0 | | V/ μs V/ μs |
| Output Short Circuit Current | $T_A = 25^\circ\text{C}$ | | 25 | | | 25 | | | 25 | | mA |
| Input Offset Voltage | $R_S \leq 10\text{ k}\Omega$ | | | 6.0 | | | 7.5 | | | 7.5 | mV |
| Input Offset Current | | | | 75 | | | 125 | | | 100 | nA |
| Input Bias Current | | | | 325 | | | 500 | | | 400 | nA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L > 2\text{ k}\Omega$ | 25 | | | 15 | | | 15 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$, $R_L = 2\text{ k}\Omega$ | ±12 ±10 | ±13 ±12 | | ±12 ±10 | ±13 ±12 | | ±12 ±10 | ±13 ±12 | | V V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±12 | | | ±12 | | | ±12 | | | V |
| Common-Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | 70 | 90 | | 70 | 90 | | 70 | 90 | | dB |
| Supply Voltage Rejection | $R_S \leq 10\text{ k}\Omega$ | 77 | 96 | | 77 | 96 | | 77 | 96 | | dB |

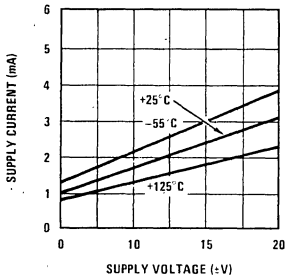
Note 1: Any of the amplifier outputs can be shorted to ground indefinitely; however, more than one should not be simultaneously shorted as the maximum junction temperature will be exceeded.

Note 2: The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX} , θ_{JA} , and the ambient temperature, T_A . The maximum available power dissipation at any temperature is $P_d = (T_{JMAX} - T_A)/\theta_{JA}$ or the 25°C P_{dMAX} , whichever is less.

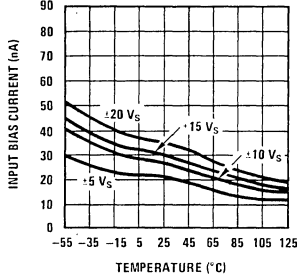
Note 3: These specifications apply for $V_S = \pm 15\text{V}$ and over the absolute maximum operating temperature range ($T_L \leq T_A \leq T_H$) unless otherwise noted.

Typical Performance Characteristics

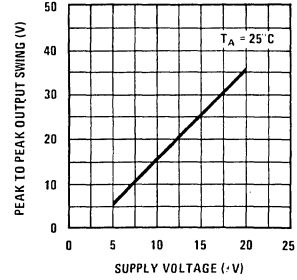
Supply Current



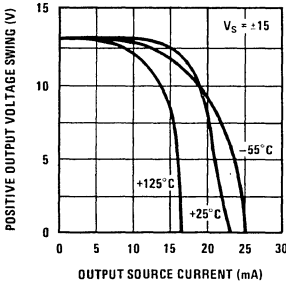
Input Bias Current



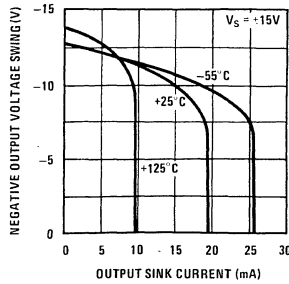
Voltage Swing



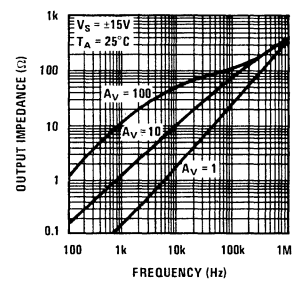
Positive Current Limit



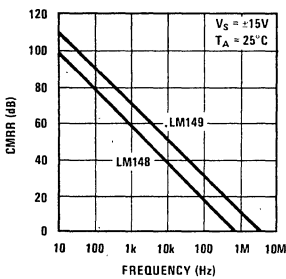
Negative Current Limit



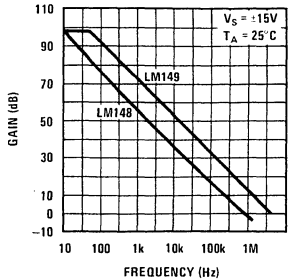
Output Impedance



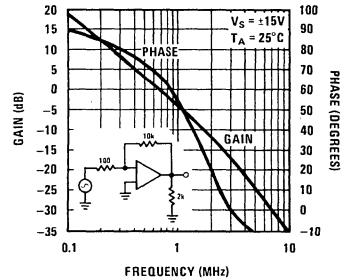
Common-Mode Rejection Ratio



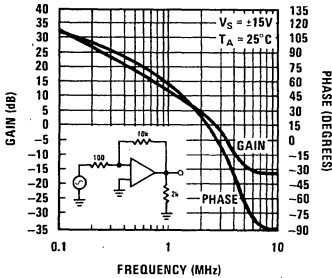
Open Loop Frequency Response



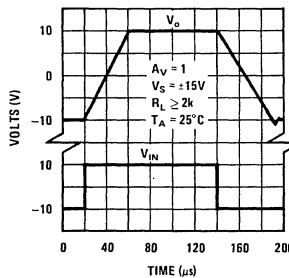
Bode Plot LM148



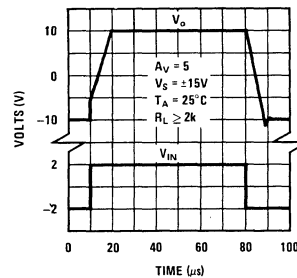
Bode Plot LM149



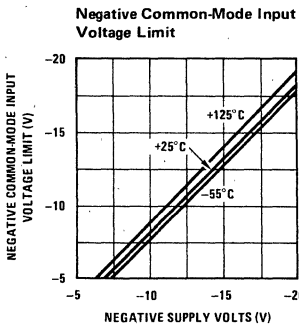
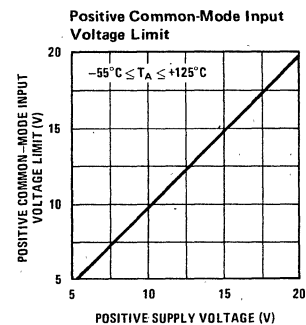
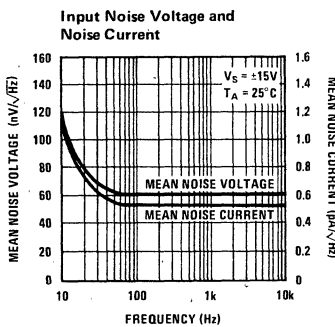
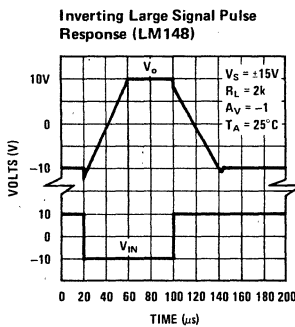
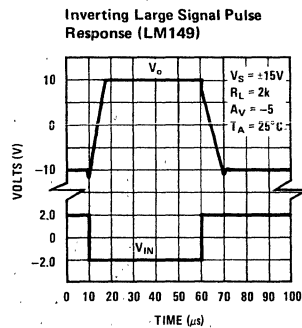
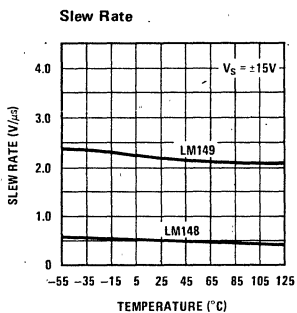
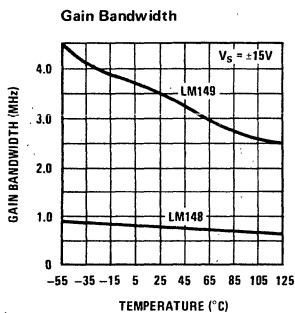
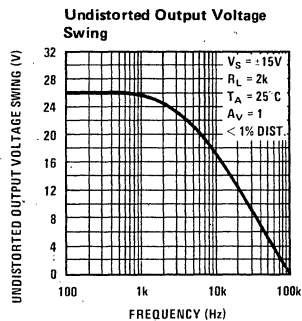
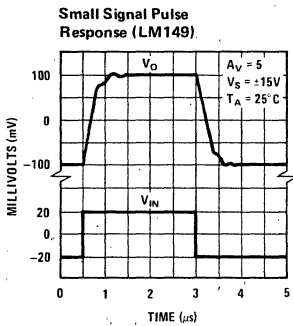
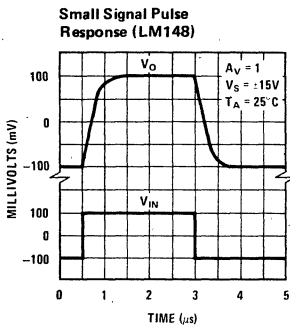
Large Signal Pulse Response (LM148)



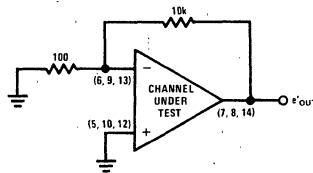
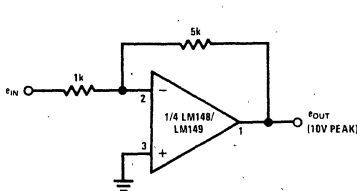
Large Signal Pulse Response (LM149)



Typical Performance Characteristics (Continued)



Cross Talk Test Circuits



$$\text{Crosstalk} = -20 \log \frac{e'_{OUT}}{101 \times e_{OUT}} \text{ (dB)}$$

$V_S = \pm 15V$

Application Hints

The LM148 series are quad low power 741 op amps. In the proliferation of quad op amps, these are the first to offer the convenience of familiar, easy to use operating characteristics of the 741 op amp. In those applications where 741 op amps have been employed, the LM148 series op amps can be employed directly with no change in circuit performance.

The LM149 series has the same characteristics as the LM148 except it has been decompensated to provide a wider bandwidth. As a result the part requires a minimum gain of 5.

The package pin-outs are such that the inverting input of each amplifier is adjacent to its output. In addition, the amplifier outputs are located in the corners of the package which simplifies PC board layout and minimizes package related capacitive coupling between amplifiers.

The input characteristics of these amplifiers allow differential input voltages which can exceed the supply voltages. In addition, if either of the input voltages is within the operating common-mode range, the phase of the output remains correct. If the negative limit of the operating common-mode range is exceeded at both inputs, the output voltage will be positive. For input voltages which greatly exceed the maximum supply voltages, either differentially or common-mode, resistors should be placed in series with the inputs to limit the current.

Like the LM741, these amplifiers can easily drive a 100 pF capacitive load throughout the entire dynamic output voltage and current range. However, if very large capacitive loads must be driven by a non-inverting unity gain amplifier, a resistor should be placed between

the output (and feedback connection) and the capacitance to reduce the phase shift resulting from the capacitive loading.

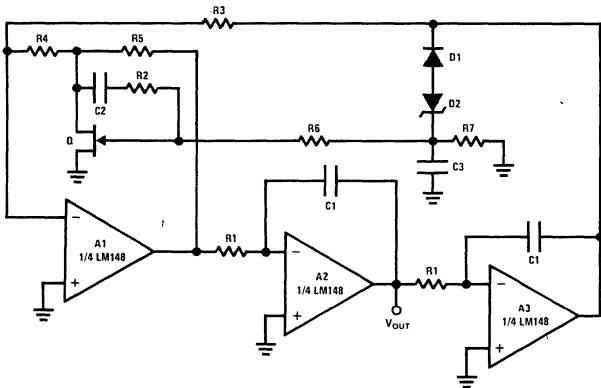
The output current of each amplifier in the package is limited. Short circuits from an output to either ground or the power supplies will not destroy the unit. However, if multiple output shorts occur simultaneously, the time duration should be short to prevent the unit from being destroyed as a result of excessive power dissipation in the IC chip.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize "pickup" and maximize the frequency of the feedback pole which capacitance from the input to ground creates.

A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to ac ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3 dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately six times the expected 3 dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

Typical Applications — LM148

One Decade Low Distortion Sinewave Generator



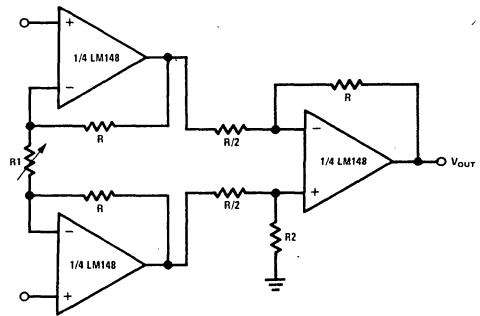
$$f = \frac{1}{2\pi R_1 C_1} \times \sqrt{K}, \quad K = \frac{R_4 R_5}{R_3} \left(\frac{1}{r_{DS}} + \frac{1}{R_4} + \frac{1}{R_5} \right), \quad r_{DS} \cong \frac{R_{ON}}{\left(1 - \frac{V_{GS}}{V_P} \right)^{1/2}}$$

$$f_{MAX} = 5 \text{ kHz}, \quad THD \leq 0.03\%$$

$R_1 = 100k \text{ pot.}$, $C_1 = 0.0047\mu F$, $C_2 = 0.01\mu F$, $C_3 = 0.1\mu F$, $R_2 = R_6 = R_7 = 1M$, $R_3 = 5.1k$, $R_4 = 12\Omega$, $R_5 = 240\Omega$, $Q = NS5102$, $D_1 = 1N914$, $D_2 = 3.6V \text{ avalanche diode (ex. LM103)}$, $V_{GS} = \pm 15V$

A simpler version with some distortion degradation at high frequencies can be made by using A1 as a simple inverting amplifier, and by putting back-to-back zeners in the feedback loop of A3.

Low Cost Instrumentation Amplifier



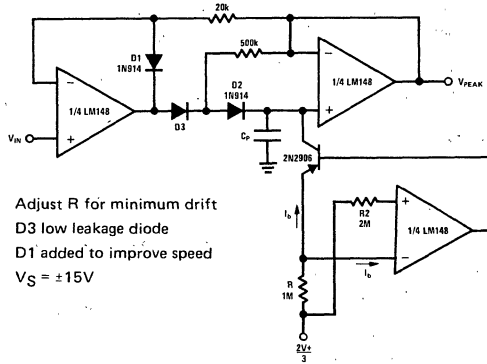
$$V_{OUT} = 2 \left(\frac{2R}{R_1} + 1 \right), \quad V_S - 3V \leq V_{IN CM} \leq V_S^+ - 3V,$$

$$V_S = \pm 15V$$

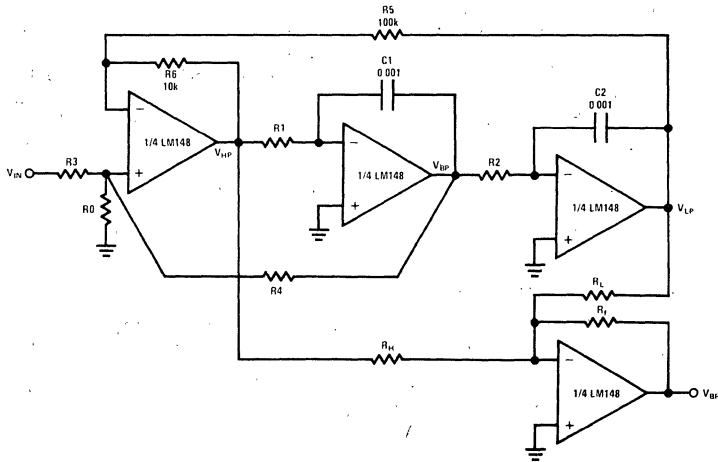
$$R = R_2, \text{ trim } R_2 \text{ to boost CMRR}$$

Typical Applications — LM148 (Continued)

Low Drift Peak Detector with Bias Current Compensation



Universal State-Space Filter



Tune Q through R0.
 For predictable results: $f_0 Q \leq 4 \times 10^4$
 Use Band Pass output to tune for Q

$$\frac{V(s)}{V_{IN}(s)} = \frac{N(s)}{D(s)}, \quad D(s) = s^2 + \frac{s\omega_0}{Q} + \omega_0^2$$

$$N_{HP}(s) = s^2 H_{OHP}, \quad N_{BP}(s) = \frac{-s\omega_0 H_{OHP}}{Q}, \quad N_{LP} = \omega_0^2 H_{OLP}$$

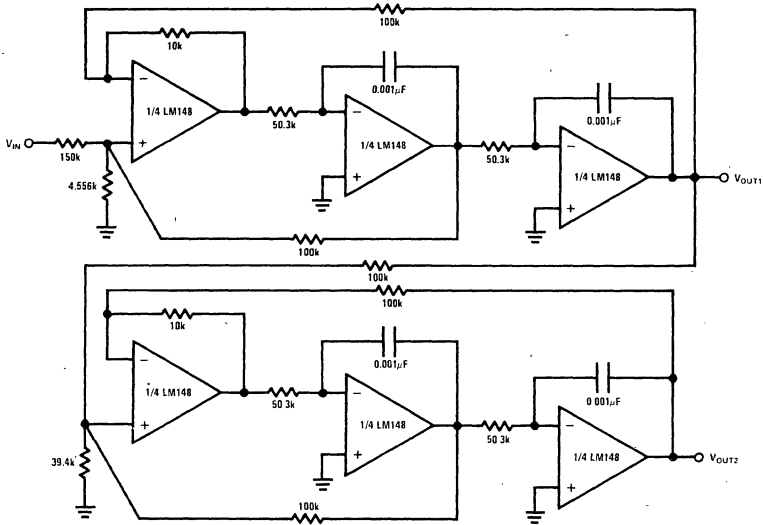
$$f_0 = \frac{1}{2\pi} \sqrt{\frac{R_6}{R_5}} \sqrt{\frac{1}{t_1 t_2}}, \quad t_i = R_i C_i, \quad Q = \left(\frac{1 + R_4 I R_3 + R_4 I R_0}{1 + R_6 I R_5} \right) \left(\frac{R_6}{R_5} \frac{t_1}{t_2} \right)^{1/2}$$

$$f_{NOTCH} = \frac{1}{2\pi} \left(\frac{R_H}{R_L t_1 t_2} \right)^{1/2}, \quad H_{OHP} = \frac{1 + R_6 I R_5}{1 + R_3 I R_0 + R_3 I R_4}, \quad H_{OHP} = \frac{1 + R_4 I R_3 + R_4 I R_0}{1 + R_3 I R_0 + R_3 I R_4}$$

$$H_{OLP} = \frac{1 + R_5 I R_6}{1 + R_3 I R_0 + R_3 I R_4}$$

Typical Applications — LM148 (Continued)

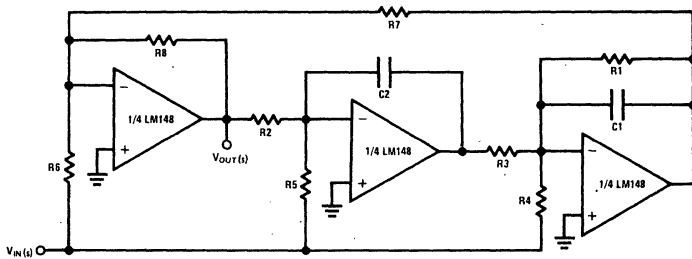
A 1 kHz 4 Pole Butterworth



Use general equations, and tune each section separately
 $Q_{1st\text{SECTION}} = 0.541, Q_{2nd\text{SECTION}} = 1.306$
 The response should have 0 dB peaking

3

A 3 Amplifier Bi-Quad Notch Filter



$$Q = \sqrt{\frac{R8}{R7}} \times \frac{R1C1}{\sqrt{R3C2R2C1}}, \quad f_o = \frac{1}{2\pi} \sqrt{\frac{R8}{R7}} \times \frac{1}{\sqrt{R2R3C1C2}}, \quad f_{\text{NOTCH}} = \frac{1}{2\pi} \sqrt{\frac{R6}{R3R5R7C1C2}}$$

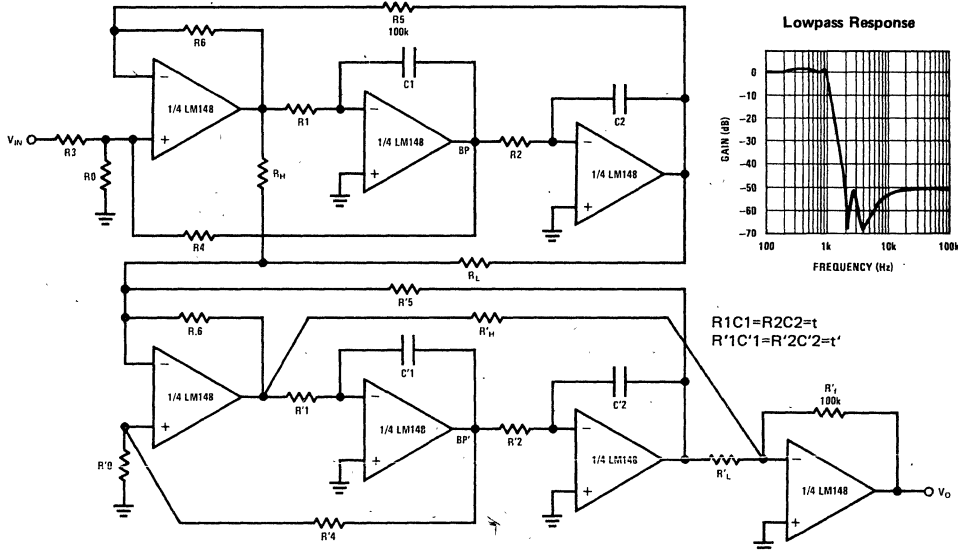
Necessary condition for notch: $\frac{1}{R6} = \frac{R1}{R4R7}$

Ex: $f_{\text{NOTCH}} = 3 \text{ kHz}, Q = 5, R1 = 270\text{k}, R2 = R3 = 20\text{k}, R4 = 27\text{k}, R5 = 20\text{k}, R6 = R8 = 10\text{k}, R7 = 100\text{k}, C1 = C2 = 0.001\mu\text{F}$

Better noise performance than the state-space approach

Typical Applications — LM148 (Continued)

A 4th Order 1 kHz Elliptic Filter (4 Poles, 4 Zeros)



$$R1C1=R2C2=t$$

$$R'1C'1=R'2C'2=t'$$

$f_c = 1 \text{ kHz}$, $f_s = 2 \text{ kHz}$, $f_p = 0.543$, $f_z = 2.14$, $Q = 0.841$, $f'_p = 0.987$, $f'_z = 4.92$, $Q' = 4.403$, normalized to ripple BW

$$f_p = \frac{1}{2\pi} \sqrt{\frac{R6}{R5}} \times \frac{1}{t}, f_z = \frac{1}{2\pi} \sqrt{\frac{R_H}{R_L}} \times \frac{1}{t}, Q = \left(\frac{1 + R4R3 + R4R0}{1 + R6R5} \right) \times \sqrt{\frac{R6}{R5}}, Q' = \sqrt{\frac{R'6}{R'5} \frac{1 + R'4R'0}{1 + R'6R'5 + R'6R_p}}$$

$$R_p = \frac{R_H R_L}{R_H + R_L}$$

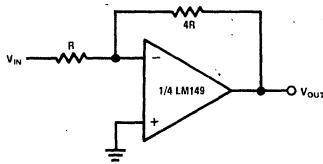
Use the BP outputs to tune Q, Q', tune the 2 sections separately

$R1 = R2 = 92.6k$, $R3 = R4 = R5 = 100k$, $R6 = 10k$, $R0 = 107.8k$, $R_L = 100k$, $R_H = 155.1k$,

$R'1 = R'2 = 50.9k$, $R'4 = R'5 = 100k$, $R'6 = 10k$, $R'0 = 5.78k$, $R'_L = 100k$, $R'_H = 248.12k$, $R'_f = 100k$. All capacitors are $0.001\mu F$.

Typical Applications — LM149

Minimum Gain to Insure LM149 Stability



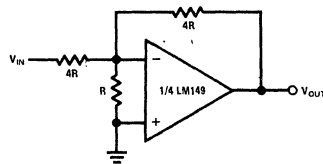
$$ACL(s) = \frac{V_{OUT}}{V_{IN}} = \frac{-4}{\left(1 + \frac{5}{A_{OL}(s)}\right)} \approx -4$$

$$V_O \Big|_{V_{IN}=0} \approx \pm 5 V_{OS}$$

Power BW = 40 kHz

Small Signal BW = G BW/5

The LM149 as a Unity Gain Inverter



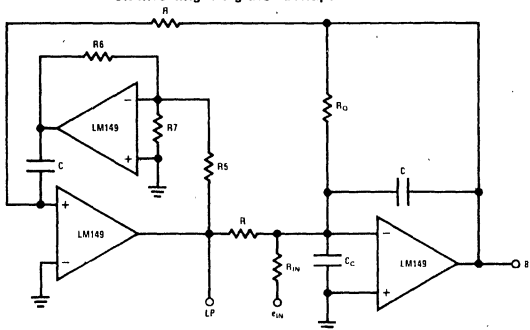
$$ACL(s) = \frac{V_{OUT}}{V_{IN}} = \left(\frac{-1}{1 + \frac{6}{A_{OL}(s)}} \right) \approx -1$$

$$V_O \Big|_{V_{IN}=0} \approx \pm 5 V_{OS}$$

Small signal BW = GBW/5

Typical Applications — LM149 (Continued)

Non-inverting-Integrator Bandpass Filter



For stability purposes: $R7 = R6/4$, $10R6 = R5$, $C_C = 10C$

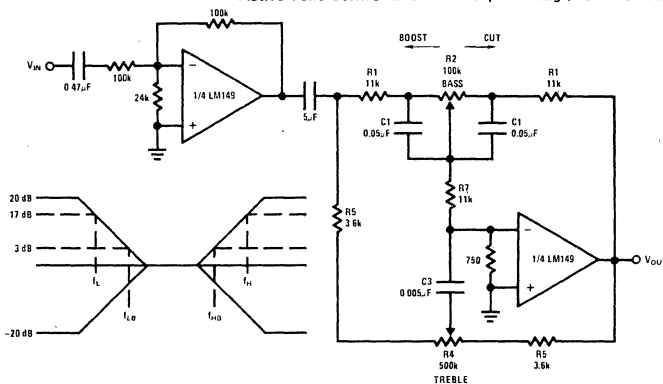
$$f_0 = \frac{1}{2\pi} \sqrt{\frac{R5}{R6}} \times \frac{1}{RC}, \quad Q = \frac{RQ}{R} \sqrt{\frac{R5}{R6}}, \quad Ho_{BP} = \frac{RQ}{R_{IN}}$$

$(f_{O(MAX)}, Q_{MAX}) = 20 \text{ kHz}, 10$

Better Q sensitivity with respect to open loop gain variations than the state variable filter.

$R7, C_C$ added for compensation

Active Tone Control with Full Output Swing (No Slew Limiting at 20 kHz)



$V_S = \pm 15V, V_{OUT(MAX)} = 9.1 V_{RMS}$
 $f_{MAX} = 20 \text{ kHz}, THD \leq 1\%$
 Duplicate the above circuit for stereo

$$f_L = \frac{1}{2\pi R2 C1}, \quad f_{LB} = \frac{1}{2\pi R1 C1}$$

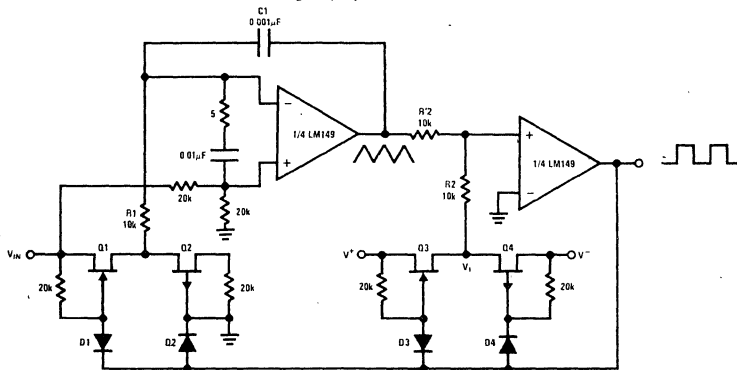
$$f_H = \frac{1}{2\pi R5 C3}, \quad f_{HB} = \frac{1}{2\pi (R1 + 2R7) C3}$$

Max Bass Gain $\approx (R1 + R2)/R1$

Max Treble Gain $\approx (R1 + 2R7)/R5$

as shown: $f_L \approx 32 \text{ Hz}, f_{LB} \approx 320 \text{ Hz}$
 $f_H \approx 11 \text{ kHz}, f_{HB} \approx 1.1 \text{ Hz}$

Triangular, Squarewave Generator



$$f = \frac{K \times V_{IN}}{8V^+ C1 R1}, \quad K = R2/R2', \quad \frac{2V_I}{K} \leq 25V, \quad V^+ = V^-, \quad V_S = \pm 15V$$

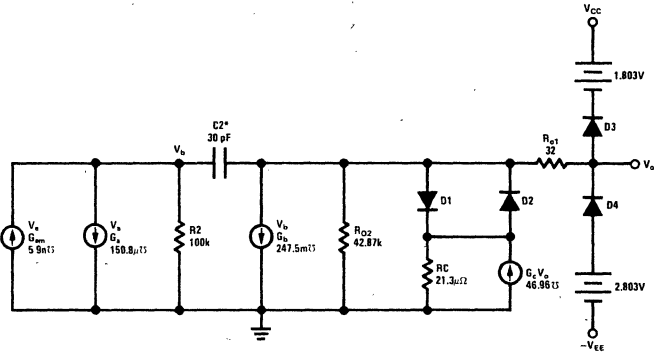
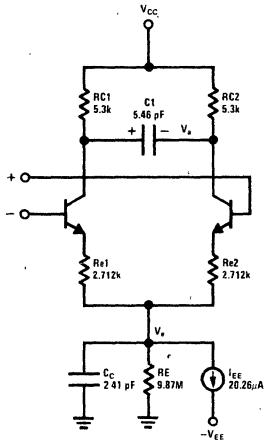
Use LM125 for $\pm 15V$ supply

The circuit can be used as a low frequency V/F for process control.

Q1, Q3: KE4393, Q2, Q4: P1087E, D1-D4 = 1N914

Typical Simulation

LM148, LM149, LM741 Macromodel for Computer Simulation



$\beta_{O1} = 112$ $I_S = 8 \cdot 10^{-16}$
 $\beta_{O2} = 144$ *C2 = 6 pF for LM149

-For more details, see IEEE Journal of Solid-State Circuits, Vol. SC-9, No. 6, December 1974

LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904

Low Power Dual Operational Amplifiers

General Description

The LM158 series consists of two independent, high gain, internally frequency compensated operational amplifiers which were designed specifically to operate from a single power supply over a wide range of voltages. Operation from split power supplies is also possible and the low power supply current drain is independent of the magnitude of the power supply voltage.

Application areas include transducer amplifiers, dc gain blocks and all the conventional op amp circuits which now can be more easily implemented in single power supply systems. For example, the LM158 series can be directly operated off of the standard +5 V_{DC} power supply voltage which is used in digital systems and will easily provide the required interface electronics without requiring the additional ±15 V_{DC} power supplies.

Unique Characteristics

- In the linear mode the input common-mode voltage range includes ground and the output voltage can also swing to ground, even though operated from only a single power supply voltage.
- The unity gain cross frequency is temperature compensated.
- The input bias current is also temperature compensated.

Advantages

- Eliminates need for dual supplies
- Two internally compensated op amps in a single package

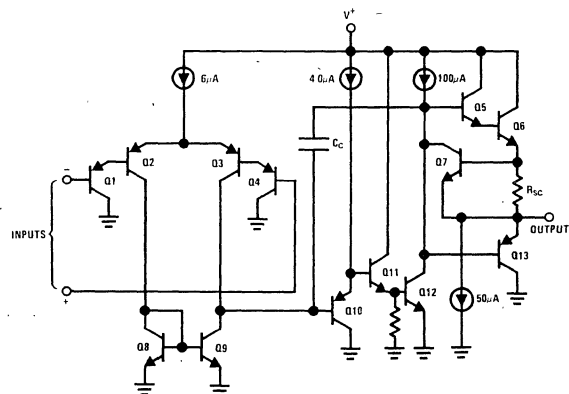
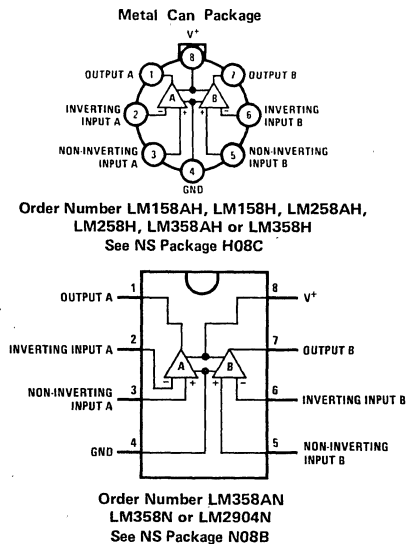
- Allows directly sensing near GND and V_{OUT} also goes to GND
- Compatible with all forms of logic
- Power drain suitable for battery operation
- Pin-out same as LM1558/LM1458 dual operational amplifier

Features

- Internally frequency compensated for unity gain
- Large dc voltage gain 100 dB
- Wide bandwidth (unity gain) 1 MHz (temperature compensated)
- Wide power supply range:
 - Single supply 3 V_{DC} to 30 V_{DC}
 - or dual supplies ±1.5 V_{DC} to ±15 V_{DC}
- Very low supply current drain (500μA) – essentially independent of supply voltage (1 mW/op amp at +5 V_{DC})
- Low input biasing current 45 nA_{DC} (temperature compensated)
- Low input offset voltage 2 mV_{DC} and offset current 5 nA_{DC}
- Input common-mode voltage range includes ground
- Differential input voltage range equal to the power supply voltage
- Large output voltage 0 V_{DC} to V⁺ – 1.5 V_{DC} swing

3
**LM158/LM258/LM358,
LM158A/LM258A/LM358A, LM2904**

Connection Diagrams (Top Views) Schematic Diagram (Each Amplifier)



LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904

Absolute Maximum Ratings

| | LM158/LM258/LM358 LM158A/LM258A/LM358A | LM2904 |
|--|---|---|
| Supply Voltage, V^+ | 32 V _{DC} or ±16 V _{DC} | 26 V _{DC} or ±13 V _{DC} |
| Differential Input Voltage | 32 V _{DC} | 26 V _{DC} |
| Input Voltage | -0.3 V _{DC} to +32 V _{DC} | -0.3 V _{DC} to +26 V _{DC} |
| Power Dissipation (Note 1) | | |
| Molded DIP (LM358N) | 570 mW | 570 mW |
| Metal Can (LM158H/LM258H/LM358H) | 830 mW | |
| Output Short-Circuit to GND (One Amplifier) (Note 2) | Continuous | Continuous |
| $V^+ \leq 15$ V _{DC} and $T_A = 25^\circ\text{C}$ | | |
| Input Current ($V_{IN} < -0.3$ V _{DC}) (Note 3) | 50 mA | 50 mA |
| Operating Temperature Range | | |
| LM358 | 0°C to +70°C | -40°C to +85°C |
| LM258 | -25°C to +85°C | |
| LM158 | -55°C to +125°C | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics ($V^+ = +5.0$ V_{DC}, Note 4)

| PARAMETER | CONDITIONS | LM158A | | | LM258A | | | LM358A | | | LM158/LM258 | | | LM358 | | | LM2904 | | | UNITS |
|---------------------------------|--|--------|-------------|-----|--------|-------------|-----|--------|-------------|-----|-------------|-------------|-----|-------|-------------|-----|--------|-------------|------------------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, (Note 5) | 1 | 2 | | 1 | 3 | | 2 | 3 | | ±2 | ±5 | | ±2 | ±7 | | ±2 | ±7 | mV _{DC} | |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$, $T_A = 25^\circ\text{C}$, (Note 6) | 20 | 50 | | 40 | 80 | | 45 | 100 | | 45 | 150 | | 45 | 250 | | 45 | 250 | nA _{DC} | |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$, $T_A = 25^\circ\text{C}$ | 2 | 10 | | 2 | 15 | | 5 | 30 | | ±3 | ±30 | | ±5 | ±50 | | ±5 | ±50 | nA _{DC} | |
| Input Common-Mode Voltage Range | $V^+ = 30$ V _{DC} , $T_A = 25^\circ\text{C}$ (Note 7) | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | V _{DC} | |
| Supply Current | $R_L = \infty$, $V_{CC} = 30$ V (LM2904 $V_{CC} = 26$ V) $R_L = \infty$ On All Op Amps Over Full Temperature Range | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | | 1 | 2 | mA _{DC} | |
| | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | | 0.7 | 1.2 | mA _{DC} | |
| Large Signal Voltage Gain | $V^+ = 15$ V _{DC} (For Large V_O Swing) $R_L \geq 2$ k Ω , $T_A = 25^\circ\text{C}$ | 50 | 100 | | 50 | 100 | | 25 | 100 | | 50 | 100 | | 25 | 100 | | 100 | | V/mV | |
| Output Voltage Swing | $R_L = 2$ k Ω , $T_A = 25^\circ\text{C}$ (LM2904 $R_L \geq 10$ k Ω) | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | | 0 | $V^+ - 1.5$ | V _{DC} | |
| Common-Mode Rejection Ratio | DC, $T_A = 25^\circ\text{C}$ | 70 | 85 | | 70 | 85 | | 65 | 85 | | 70 | 85 | | 65 | 70 | | 50 | 70 | dB | |
| Power Supply Rejection Ratio | DC, $T_A = 25^\circ\text{C}$ | 65 | 100 | | 65 | 100 | | 65 | 100 | | 65 | 100 | | 65 | 100 | | 50 | 100 | dB | |
| Amplifier-to-Amplifier Coupling | $f = 1$ kHz to 20 kHz, $T_A = 25^\circ\text{C}$ (Input Referred), (Note 8) | | -120 | | | -120 | | | -120 | | | -120 | | | -120 | | | -120 | dB | |
| Output Current Source | $V_{IN}^+ = 1$ V _{DC} , $V_{IN}^- = 0$ V _{DC} , $V^+ = 15$ V _{DC} , $T_A = 25^\circ\text{C}$ | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | | 20 | 40 | mA _{DC} | |

Electrical Characteristics (Continued) ($V^+ = +5.0 V_{DC}$, Note 4)

| PARAMETER | CONDITIONS | LM158A | | | LM258A | | | LM358A | | | LM158/LM258 | | | LM358 | | | LM2904 | | | UNITS | |
|----------------------------------|---|--------|-----|-----------|--------|-----|-----------|--------|-----|-----------|-------------|-----|-----------|-------|-----|-----------|--------|-----|-----------|--------------------|------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| Sink | $V_{IN}^- = 1 V_{DC}$, $V_{IN}^+ = 0 V_{DC}$, $V^+ = 15 V_{DC}$, $T_A = 25^\circ C$ | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | mADC | |
| | $V_{IN}^- = 1 V_{DC}$, $V_{IN}^+ = 0 V_{DC}$, $T_A = 25^\circ C$, $V_O = 200 mV_{DC}$ | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | 12 | 50 | | μADC | |
| Short Circuit to Ground | $T_A = 25^\circ C$, (Note 2) | | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | | 40 | 60 | mADC | |
| Input Offset Voltage | (Note 5) | | | 4 | | | 4 | | | 5 | | | ± 7 | | | ± 9 | | | ± 10 | mV _{DC} | |
| Input Offset Voltage Drift | $R_S = 0\Omega$ | | 7 | 15 | | 7 | 15 | | 7 | 20 | | 7 | | 7 | | 7 | | 7 | | $\mu V/^\circ C$ | |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$ | | | 30 | | | 30 | | | 75 | | | ± 100 | | | ± 150 | | | 45 | ± 200 | nADC |
| Input Offset Current Drift | | | 10 | 200 | | 10 | 200 | | 10 | 300 | | 10 | | 10 | | 10 | | 10 | | $\mu ADC/^\circ C$ | |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$ | | 40 | 100 | | 40 | 100 | | 40 | 200 | | 40 | 300 | | 40 | 500 | | 40 | 500 | nADC | |
| Input Common-Mode Voltage Range | $V^+ = 30 V_{DC}$, (Note 7) | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | V _{DC} | |
| Large Signal Voltage Gain | $V^+ = +15 V_{DC}$ (For Large V_O Swing) $R_L \geq 2 k\Omega$ | 25 | | | 25 | | | 15 | | | 25 | | | 15 | | | 15 | | | V/mV | |
| Output Voltage Swing V_{OH} | $V^+ = +30 V_{DC}$, $R_L = 2 k\Omega$ $R_L \geq 10 k\Omega$ | 26 | | | 26 | | | 26 | | | 26 | | | 26 | | | 22 | | | V _{DC} | |
| | $V^+ = 5 V_{DC}$, $R_L \leq 10 k\Omega$ | 27 | 28 | | 27 | 28 | | 27 | 28 | | 27 | 28 | | 27 | 28 | | 23 | 24 | | V _{DC} | |
| V_{OL} | $V^+ = 5 V_{DC}$, $R_L \leq 10 k\Omega$ | | 5 | 20 | | 5 | 20 | | 5 | 20 | | 5 | 20 | | 5 | 20 | | 5 | 100 | mV _{DC} | |
| Output Current Source | $V_{IN}^+ = +1 V_{DC}$, $V_{IN}^- = 0 V_{DC}$, $V^+ = -15 V_{DC}$ | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | 10 | 20 | | mADC | |
| | Sink $V_{IN}^- = +1 V_{DC}$, $V_{IN}^+ = 0 V_{DC}$, $V^+ = 15 V_{DC}$ | 10 | 15 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | 5 | 8 | | mADC | |
| Differential Input Voltage | (Note 7) | | | V^+ | | | V^+ | | | V^+ | | | V^+ | | | V^+ | | | V^+ | V _{DC} | |

Note 1: For operating at high temperatures, the LM358/LM358A, LM2904 must be derated based on a $+125^\circ C$ maximum junction temperature and a thermal resistance of $175^\circ C/W$ which applies for the device soldered in a printed circuit board, operating in a still air ambient. The LM258/LM258A and LM158/LM158A can be derated based on a $+150^\circ C$ maximum junction temperature. The dissipation is the total of all four amplifiers—use external resistors, where possible, to allow the amplifier to saturate or to reduce the power which is dissipated in the integrated circuit.

Note 2: Short circuits from the output to V^+ can cause excessive heating and eventual destruction. The maximum output current is approximately 40 mA independent of the magnitude of V^+ . At values of supply voltage in excess of $+15 V_{DC}$, continuous short-circuits can exceed the power dissipation ratings and cause eventual destruction. Destructive dissipation can result from simultaneous shorts on all amplifiers.

Note 3: This input current will only exist when the voltage at any of the input leads is driven negative. It is due to the collector-base junction of the input PNP transistors becoming forward biased and thereby acting as input diode clamps. In addition to this diode action, there is also lateral NPN parasitic transistor action on the IC chip. This transistor action can cause the output voltages of the op amps to go to the V^+ voltage level (or to ground for a large overdrive) for the time duration that an input is driven negative. This is not destructive and normal output states will re-establish when the input voltage, which was negative, again returns to a value greater than $-0.3 V_{DC}$.

Note 4: These specifications apply for $V^+ = +5 V_{DC}$ and $-55^\circ C \leq T_A \leq +125^\circ C$, unless otherwise stated. With the LM258/LM258A, all temperature specifications are limited to $-25^\circ C \leq T_A \leq +85^\circ C$, the LM358/LM358A temperature specifications are limited to $0^\circ C \leq T_A \leq +70^\circ C$, and the LM2904 specifications are limited to $-40^\circ C \leq T_A \leq +85^\circ C$.

Note 5: $V_O \approx 1.4 V_{DC}$, $R_S = 0\Omega$ with V^+ from $5 V_{DC}$ to $30 V_{DC}$; and over the full input common-mode range ($0 V_{DC}$ to $V^+ - 1.5 V_{DC}$).

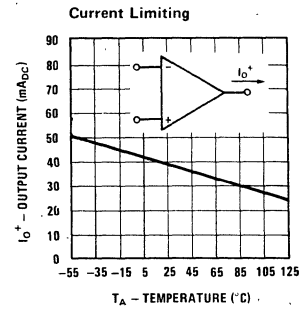
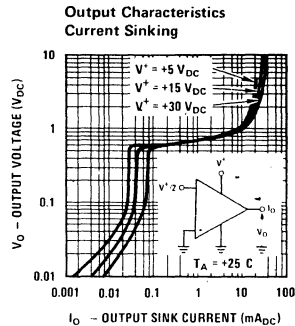
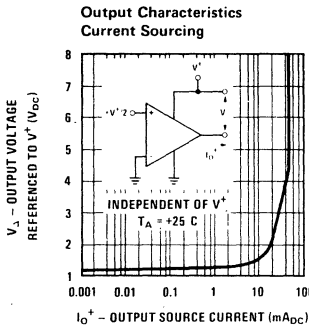
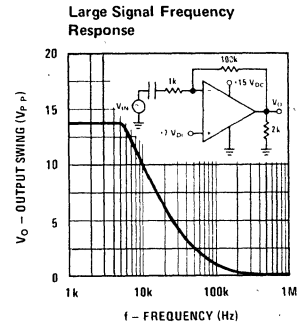
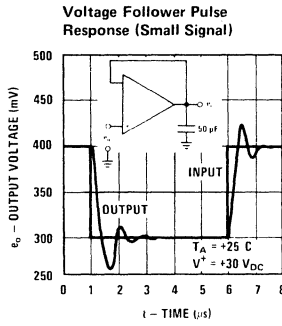
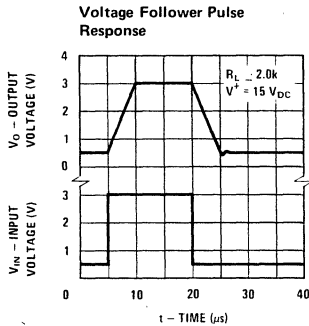
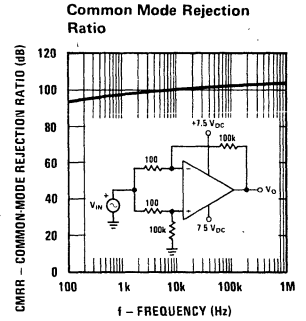
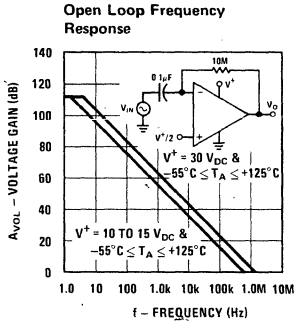
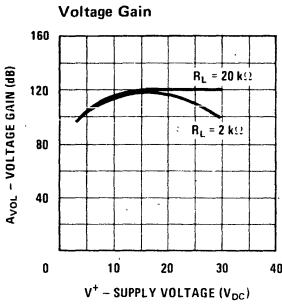
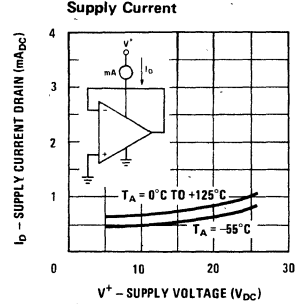
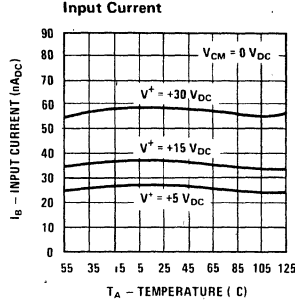
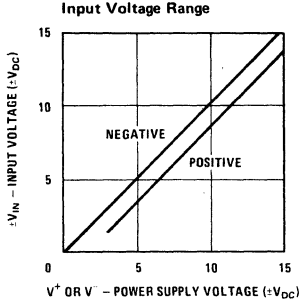
Note 6: The direction of the input current is out of the IC due to the PNP input stage. This current is essentially constant, independent of the state of the output so no loading change exists on the input lines.

Note 7: The input common-mode voltage or either input signal voltage should not be allowed to go negative by more than 0.3V. The upper end of the common-mode voltage range is $V^+ - 1.5V$, but either or both inputs can go to $+32 V_{DC}$ without damage ($+26 V_{DC}$ for LM2904).

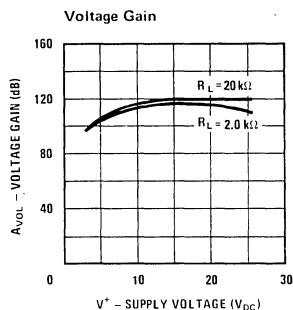
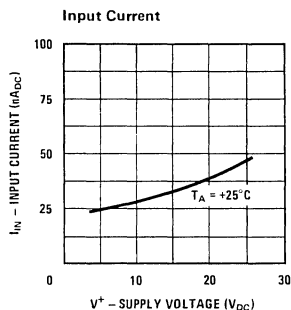
Note 8: Due to proximity of external components, insure that coupling is not originating via stray capacitance between these external parts. This typically can be detected as this type of capacitive increases at higher frequencies.



Typical Performance Characteristics



Typical Performance Characteristics (Continued) (LM2902 only)



Application Hints

The LM158 series are op amps which operate with only a single power supply voltage, have true-differential inputs, and remain in the linear mode with an input common-mode voltage of 0 V_{DC}. These amplifiers operate over a wide range of power supply voltage with little change in performance characteristics. At 25°C amplifier operation is possible down to a minimum supply voltage of 2.3 V_{DC}.

Precautions should be taken to insure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a test socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Large differential input voltages can be easily accommodated and, as input differential voltage protection diodes are not needed, no large input currents result from large differential input voltages. The differential input voltage may be larger than V⁺ without damaging the device. Protection should be provided to prevent the input voltages from going negative more than -0.3 V_{DC} (at 25°C). An input clamp diode with a resistor to the IC input terminal can be used.

To reduce the power supply current drain, the amplifiers have a class A output stage for small signal levels which converts to class B in a large signal mode. This allows the amplifiers to both source and sink large output currents. Therefore both NPN and PNP external current boost transistors can be used to extend the power capability of the basic amplifiers. The output voltage needs to raise approximately 1 diode drop above ground to bias the on-chip vertical PNP transistor for output current sinking applications.

For ac applications, where the load is capacitively coupled to the output of the amplifier, a resistor should be used, from the output of the amplifier to ground to increase the class A bias current and prevent crossover

distortion. Where the load is directly coupled, as in dc applications, there is no crossover distortion.

Capacitive loads which are applied directly to the output of the amplifier reduce the loop stability margin. Values of 50 pF can be accommodated using the worst-case non-inverting unity gain connection. Large closed loop gains or resistive isolation should be used if larger load capacitance must be driven by the amplifier.

The bias network of the LM158 establishes a drain current which is independent of the magnitude of the power supply voltage over the range of from 3 V_{DC} to 30 V_{DC}.

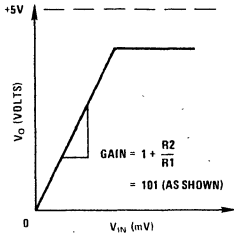
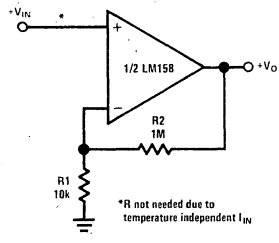
Output short circuits either to ground or to the positive power supply should be of short time duration. Units can be destroyed, not as a result of the short circuit current causing metal fusing, but rather due to the large increase in IC chip dissipation which will cause eventual failure due to excessive junction temperatures. Putting direct short-circuits on more than one amplifier at a time will increase the total IC power dissipation to destructive levels, if not properly protected with external dissipation limiting resistors in series with the output leads of the amplifiers. The larger value of output source current which is available at 25°C provides a larger output current capability at elevated temperatures (see typical performance characteristics) than a standard IC op amp.

The circuits presented in the section on typical applications emphasize operation on only a single power supply voltage. If complementary power supplies are available, all of the standard op amp circuits can be used. In general, introducing a pseudo-ground (a bias voltage reference of V⁺/2) will allow operation above and below this value in single power supply systems. Many application circuits are shown which take advantage of the wide input common-mode voltage range which includes ground. In most cases, input biasing is not required and input voltages which range to ground can easily be accommodated.

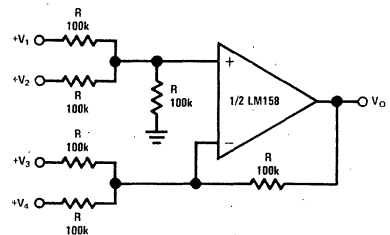
Typical Single-Supply Applications ($V^+ = 5.0 V_{DC}$)

LM158/LM258/LM358, LM158A/LM258A/LM358A, LM2904

Non-Inverting DC Gain (0V Input = 0V Output)

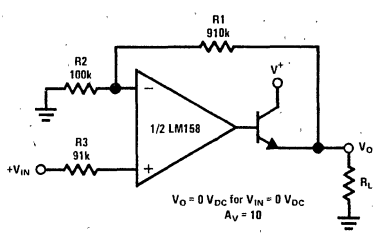


DC Summing Amplifier ($V_{IN}'S \ge 0 V_{DC}$ AND $V_O \ge 0 V_{DC}$)

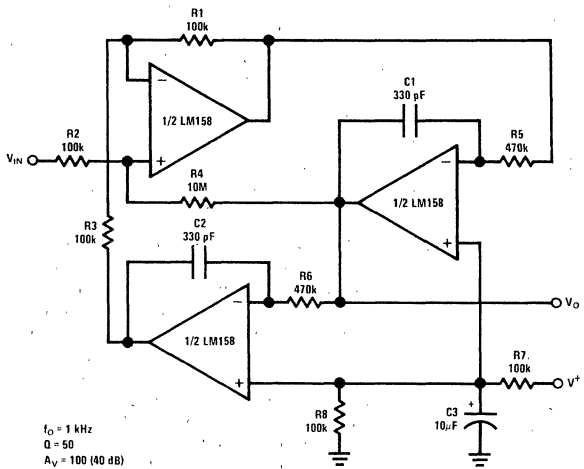


Where: $V_O = V_1 + V_2 - V_3 - V_4$
 $(V_1 + V_2) \ge (V_3 + V_4)$ to keep $V_O > 0 V_{DC}$

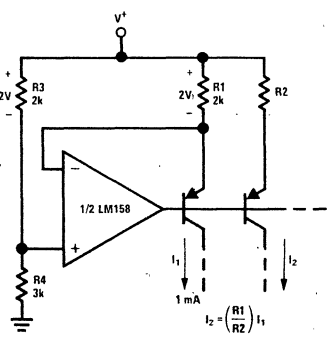
Power Amplifier



"BI-QUAD" RC Active Bandpass Filter



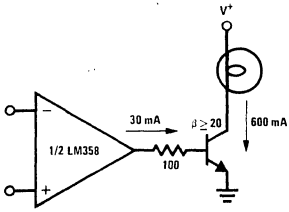
Fixed Current Sources



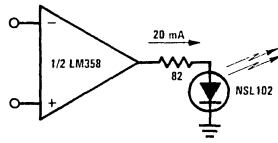
Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

LM158/LM258/LM358,
LM158A/LM258A/LM358A, LM2904

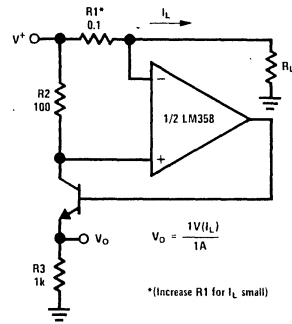
Lamp Driver



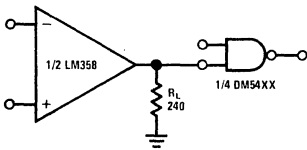
LED Driver



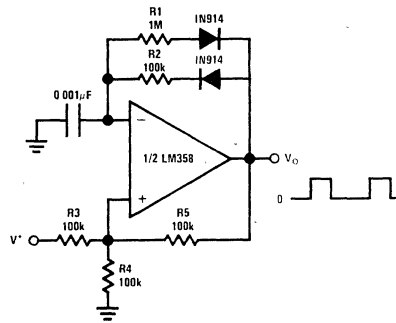
Current Monitor



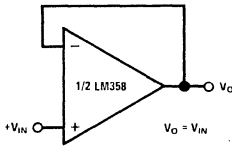
Driving TTL



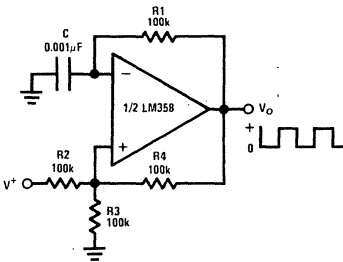
Pulse Generator



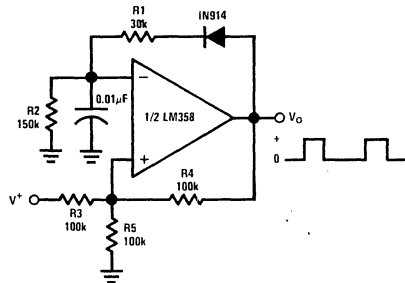
Voltage Follower



Squarewave Oscillator

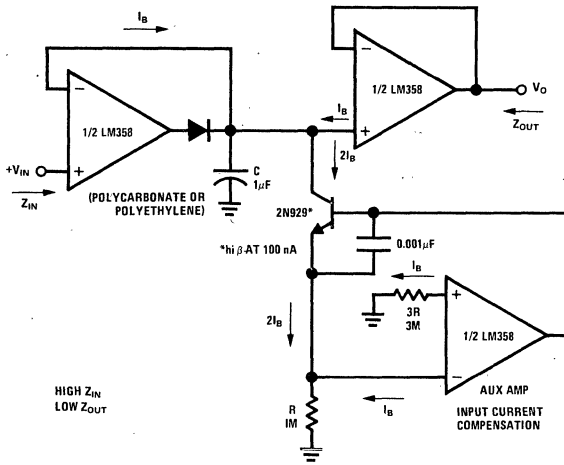


Pulse Generator

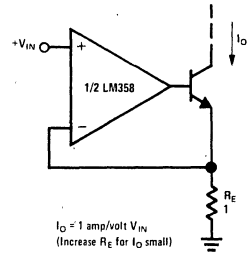


Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

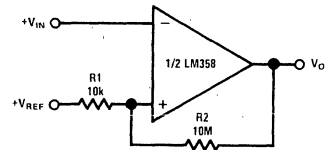
Low Drift Peak Detector



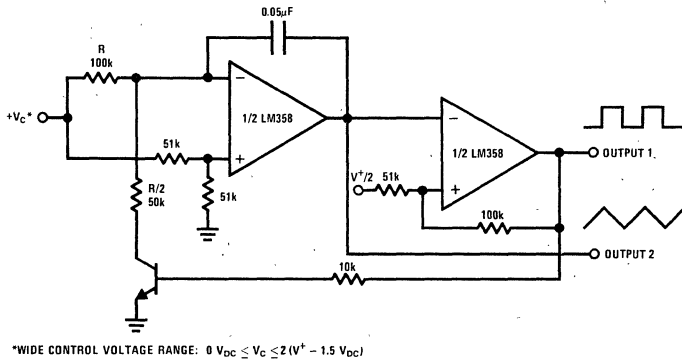
High Compliance Current Sink



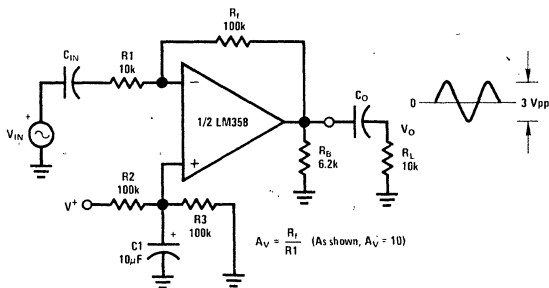
Comparator with Hysteresis



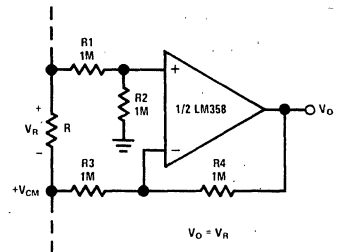
Voltage Controlled Oscillator (VCO)



AC Coupled Inverting Amplifier

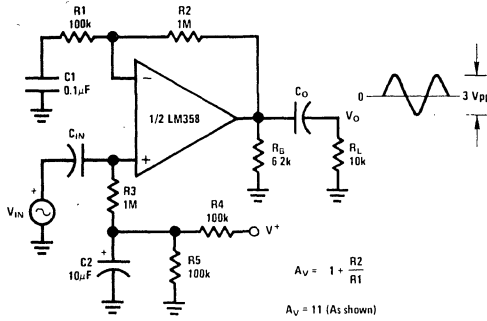


Ground Referencing A Differential Input Signal

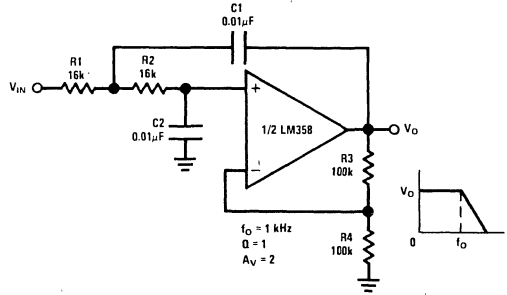


Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

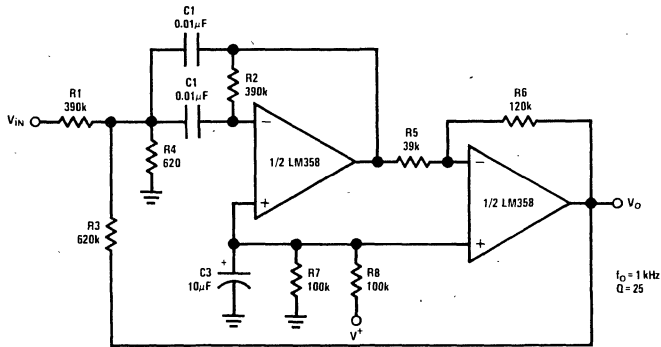
AC Coupled Non-Inverting Amplifier



DC Coupled Low-Pass RC Active Filter



Bandpass Active Filter



High Input Z, DC Differential Amplifier

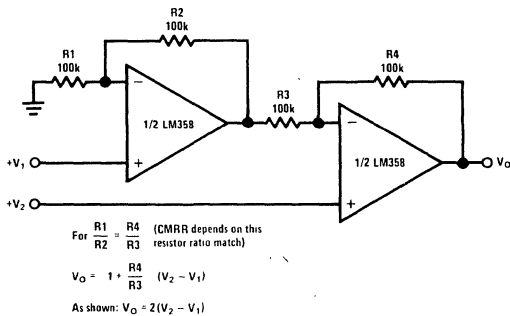
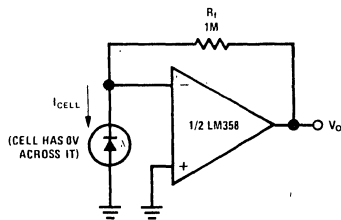


Photo Voltaic-Cell Amplifier

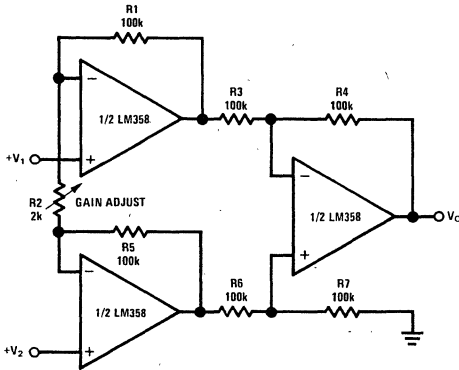


LM158/LM258/LM358,
LM158A/LM258A/LM358A, LM2904

3

Typical Single-Supply Applications (Continued) ($V^+ = 5.0 V_{DC}$)

High Input Z Adjustable-Gain DC Instrumentation Amplifier

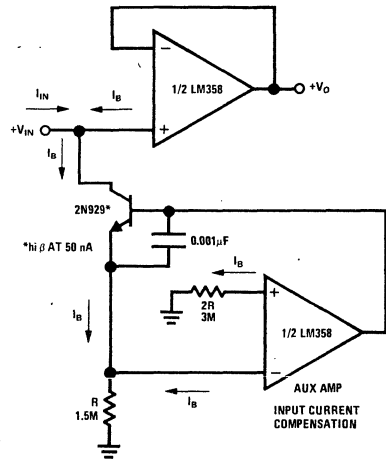


If $R1 = R5$ & $R3 = R4 = R6 = R7$ (CMRR depends on match)

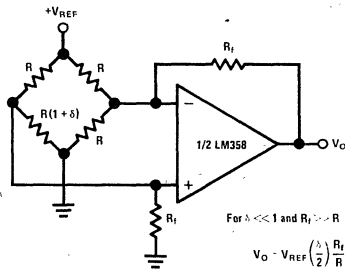
$$V_O = 1 + \frac{2R1}{R2} (V_2 - V_1)$$

As shown $V_O = 101 (V_2 - V_1)$

Using Symmetrical Amplifiers to Reduce Input Current (General Concept)



Bridge Current Amplifier



For $\Delta \ll 1$ and $R_f \gg R$

$$V_O = V_{REF} \left(\frac{1}{2} \right) \frac{R_f}{R}$$

LM159/LM359 Dual, High Speed, Programmable, Current Mode (Norton) Amplifiers

General Description

The LM159/LM359 consists of two current differencing (Norton) input amplifiers. Design emphasis has been placed on obtaining high frequency performance and providing user programmable amplifier operating characteristics. Each amplifier is broadbanded to provide a high gain bandwidth product, fast slew rate and stable operation for an inverting closed loop gain of 10 or greater. Pins for additional external frequency compensation are provided. The amplifiers are designed to operate from a single supply and can accommodate input common-mode voltages greater than the supply.

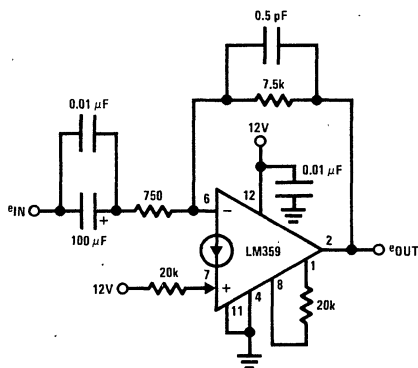
Applications

- General purpose video amplifiers
- High frequency, high Q active filters
- Photo-diode amplifiers
- Wide frequency range waveform generation circuits
- All LM3900 AC applications work to much higher frequencies

Features

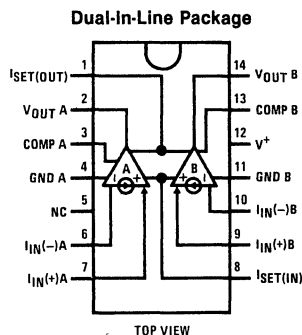
- User programmable gain bandwidth product, slew rate, input bias current, output stage biasing current and total device power dissipation
- High gain bandwidth product ($I_{SET} = 0.5 \text{ mA}$)
 - 400 MHz for $A_V = 10$ to 100
 - 30 MHz for $A_V = 1$
- High slew rate ($I_{SET} = 0.5 \text{ mA}$)
 - 60 $V/\mu\text{s}$ for $A_V = 10$ to 100
 - 30 $V/\mu\text{s}$ for $A_V = 1$
- Current differencing inputs allow high common-mode input voltages
- Operates from a single 5V to 22V supply
- Large inverting amplifier output swing, 2 mV to $V_{CC} - 2V$
- Low spot noise, 6 $nV/\sqrt{\text{Hz}}$, for $f > 1 \text{ kHz}$

Typical Application



- $A_V = 20 \text{ dB}$
- $-3 \text{ dB bandwidth} = 2.5 \text{ Hz to } 25 \text{ MHz}$
- Differential phase error $< 1^\circ$ at 3.58 MHz
- Differential gain error $< 0.5\%$ at 3.58 MHz

Connection Diagram



Order Number LM159J or LM359J
See NS Package J14A
Order Number LM359N
See NS Package N14A

Absolute Maximum Ratings

| | | | |
|----------------------------|---|---|---|
| Supply Voltage | 22 V _{DC} ±11 V _{DC} | Input Currents, I _{IN} (+) or I _{IN} (-) Set Currents, I _{SET} (IN) or I _{SET} (OUT) | 10 mA _{DC} 2 mA _{DC} |
| Power Dissipation (Note 1) | | Operating Temperature Range | |
| J Package | 1W | LM159 | -55°C to +125°C |
| N Package | 750 mW | LM359 | 0°C to 70°C |
| Maximum T _J | | Storage Temperature Range | -65°C to +150°C |
| J Package | 150°C | Lead Temperature (Soldering, 10 seconds) | 300°C |
| N Package | 125°C | | |
| θ _{JA} | | | |
| J Package | 100°C/W | | |
| N Package | 160°C/W | | |

Electrical Characteristics

I_{SET}(IN) = I_{SET}(OUT) = 0.5 mA, V_{supply} = 12V, T_A = 25°C unless otherwise noted.

| Parameter | Conditions | LM159 | | | LM359 | | | Units |
|-------------------------------------|--|-------|------|------|-------|------|-----|-------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Open Loop Voltage Gain | V _{supply} = 12V, R _L = 1k, f = 100 Hz T _A = 125°C | 66 | 72 | | 62 | 72 | | dB |
| Bandwidth | | 62 | 68 | | 68 | | | dB |
| Unity Gain | R _{IN} = 1 kΩ, C _{comp} = 10 pF | 20 | 30 | | 15 | 30 | | MHz |
| Gain Bandwidth Product | R _{IN} = 50Ω to 200Ω | 300 | 400 | | 200 | 400 | | MHz |
| Gain of 10 to 100 | | | | | | | | |
| Slew Rate | | | | | | | | |
| Unity Gain | R _{IN} = 1 kΩ, C _{comp} = 10 pF | | 30 | | | 30 | | V/μs |
| Gain of 10 to 100 | R _{IN} < 200Ω | | 60 | | | 60 | | V/μs |
| Amplifier to Amplifier Coupling | f = 100 Hz to 100 kHz, R _L = 1k | | -80 | | | -80 | | dB |
| Mirror Gain (Note 2) | @ 2 mA I _{IN} (+), I _{SET} = 5 μA, T _A = 25°C @ 0.2 mA I _{IN} (+), I _{SET} = 5 μA Over Temp | 0.95 | 1.0 | 1.05 | 0.9 | 1.0 | 1.1 | μA/μA |
| | @ 20 μA I _{IN} (+), I _{SET} = 5 μA Over Temp | 0.95 | 1.0 | 1.05 | 0.9 | 1.0 | 1.1 | μA/μA |
| ΔMirror Gain (Note 2) | @ 20 μA to 0.2 mA I _{IN} (+) Over Temp, I _{SET} = 5 μA | | 1 | 5 | | 3 | 5 | % |
| Input Bias Current | Inverting Input, T _A = 25°C Over Temp | | 8 | 15 | | 8 | 15 | μA |
| | | | | 30 | | | 30 | μA |
| Input Resistance (β _{re}) | Inverting Input | | 2.5 | | | 2.5 | | kΩ |
| Output Resistance | I _{OUT} = 15 mA rms, f = 1 MHz | | 3.5 | | | 3.5 | | Ω |
| Output Voltage Swing | R _L = 600Ω | | | | | | | |
| V _{OUT} High | I _{IN} (-) & I _{IN} (+) Grounded | 9.5 | 10.3 | | 9.5 | 10.3 | | V |
| V _{OUT} Low | I _{IN} (-) = 100 μA, I _{IN} (+) = 0 | | 2 | 50 | | 2 | 50 | mV |
| Output Currents | | | | | | | | |
| Source | I _{IN} (-) & I _{IN} (+) Grounded, R _L = 100Ω | 20 | 40 | | 16 | 40 | | mA |
| Sink (Linear Region) | V _{comp} - 0.5V = V _{OUT} = 1V, I _{IN} (+) = 0 | | 4.7 | | | 4.7 | | mA |
| Sink (Overdriven) | I _{IN} (-) = 100 μA, I _{IN} (+) = 0, V _{OUT} Force = 1V | 2 | 3 | | 1.5 | 3 | | mA |
| Supply Current | Non-Inverting Input Grounded, R _L = ∞ | | 18.5 | 20 | | 18.5 | 22 | mA |
| Power Supply Rejection (Note 3) | f = 120 Hz, I _{IN} (+) Grounded | 40 | 50 | | 40 | 50 | | dB |

Note 1: See Maximum Power Dissipation graph.

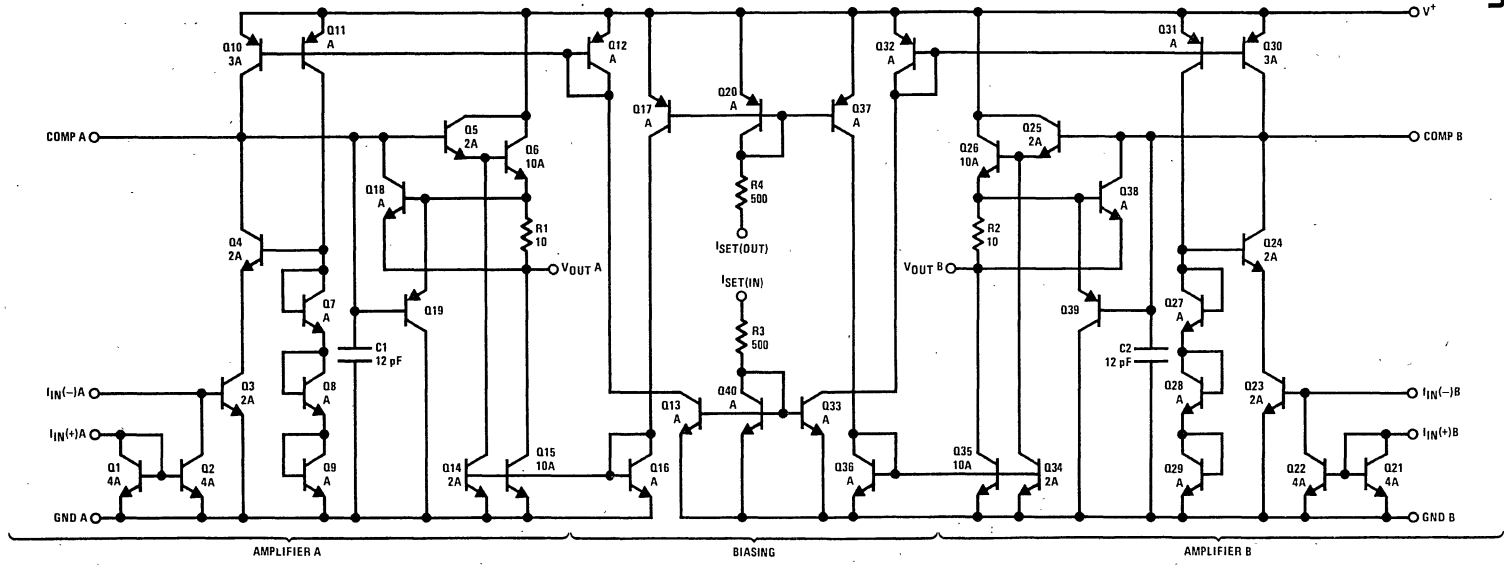
Note 2: Mirror gain is the current gain of the current mirror which is used as the non-inverting input.

Gain is the % change in A₁ for two different mirror currents at any given temperature.

Note 3: See Supply Rejection graphs.

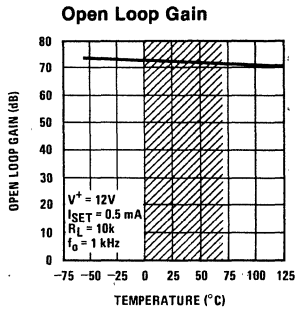
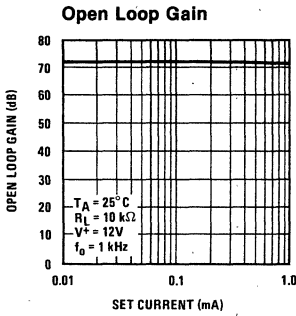
$$\left(A_1 = \frac{I_{IN}(-)}{I_{IN}(+)} \right) \Delta \text{Mirror}$$

Schematic Diagram

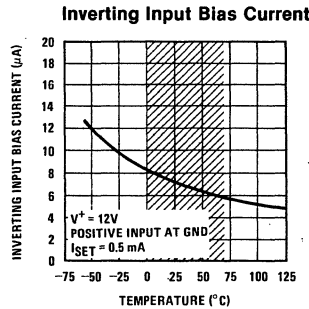
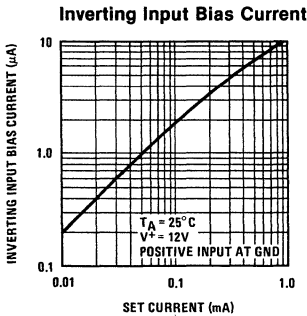
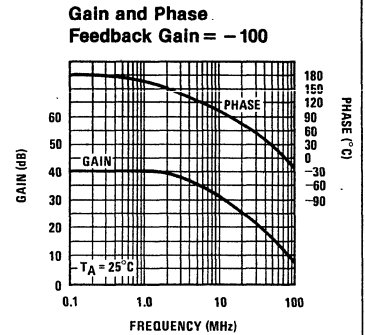
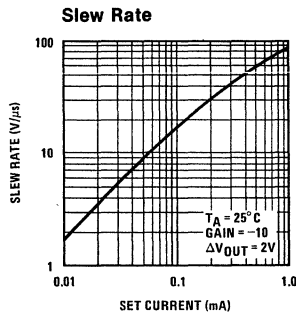
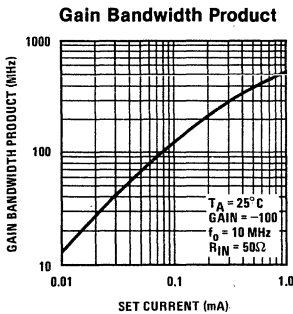
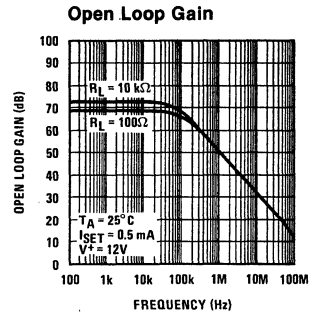


3-169

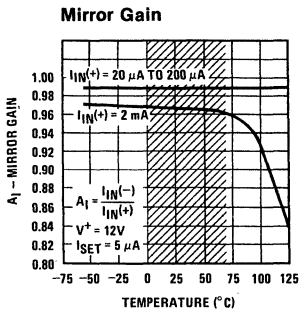
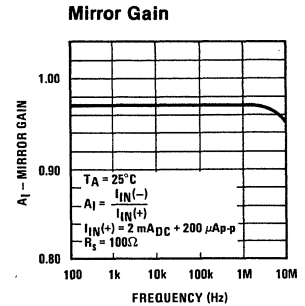
Typical Performance Characteristics



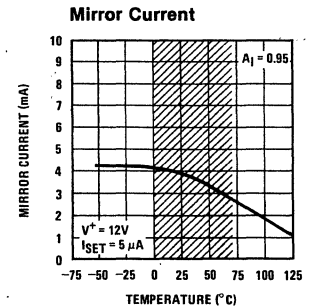
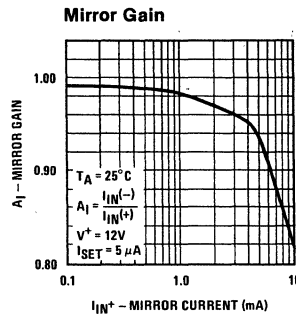
Note: Shaded area refers to LM359J/LM359N



Note: Shaded area refers to LM359J/LM359N

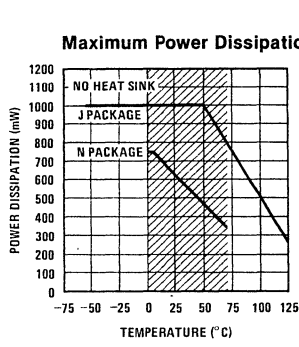
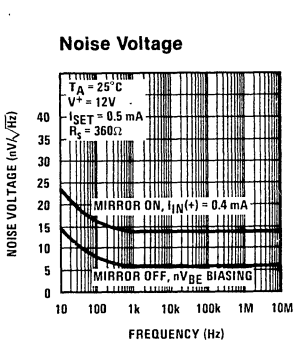
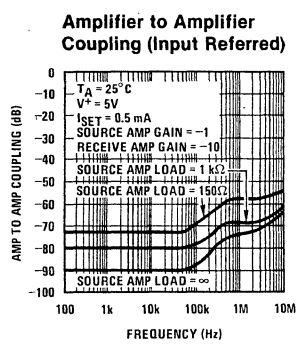
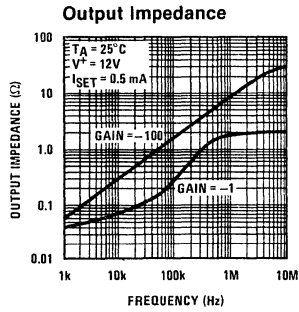
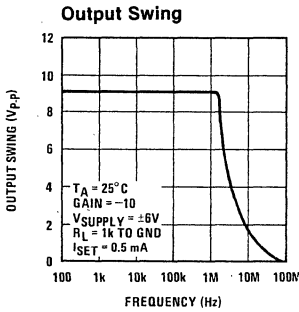
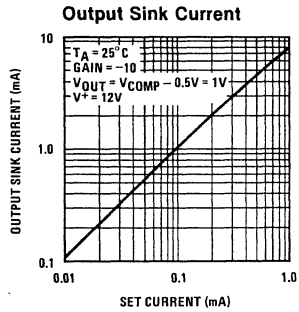
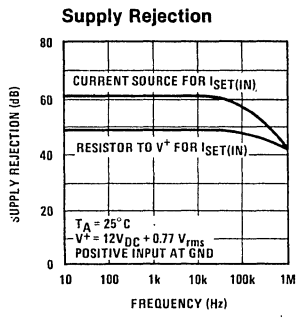
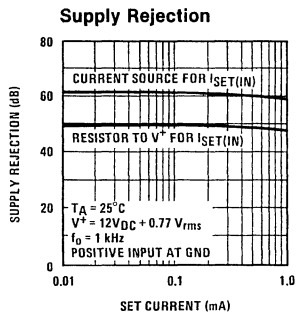
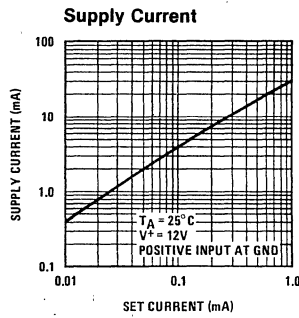


Note: Shaded area refers to LM359J/LM359N



Note: Shaded area refers to LM359J/LM359N

Typical Performance Characteristics (Continued)



Application Hints

The LM159/LM359 consists of two wide bandwidth, decompensated current differencing (Norton) amplifiers. Although similar in operation to the original LM3900, design emphasis for these amplifiers has been placed on obtaining much higher frequency performance as illustrated in Figure 1.

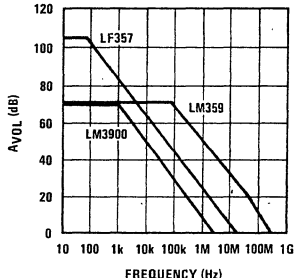


FIGURE 1

Note: Shaded area refers to LM359J/LM359N

This significant improvement in frequency response is the result of using a common-emitter/common-base (cascode) gain stage which is typical in many discrete and integrated video and RF circuit designs. Another versatile aspect of these amplifiers is the ability to externally program many internal amplifier parameters to suit the requirements of a wide variety of applications in which this type of amplifier can be used.

DC BIASING

The LM359 is intended for single supply voltage operation which requires DC biasing of the output. The current mirror circuitry which provides the non-inverting input for the amplifier also facilitates DC biasing the output. The basic operation of this current mirror is that the current (both AC and DC) flowing into the non-inverting input will force an equal amount of current to flow into the inverting input. The mirror gain (A_1) specification is the measure of how closely these two currents match. For more details see National Application Note AN-72.

Application Hints (Continued)

DC biasing of the output is accomplished by establishing a reference DC current into the (+) input, $I_{IN}(+)$, and requiring the output to provide the (-) input current. This forces the output DC level to be whatever value necessary (within the output voltage swing of the amplifier) to provide this DC reference current, *Figure 2*.

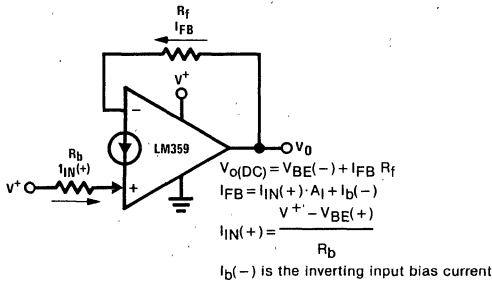


FIGURE 2

The DC input voltage at each input is a transistor V_{BE} ($\cong 0.6 V_{DC}$) and must be considered for DC biasing. For most applications, the supply voltage, V^+ , is suitable and convenient for establishing $I_{IN}(+)$. The inverting input bias current, $I_b(-)$, is a direct function of the programmable input stage current (see current programmability section) and to obtain predictable output DC biasing set $I_{IN}(+) \geq 10I_b(-)$.

The following figures illustrate typical biasing schemes for AC amplifiers using the LM359:

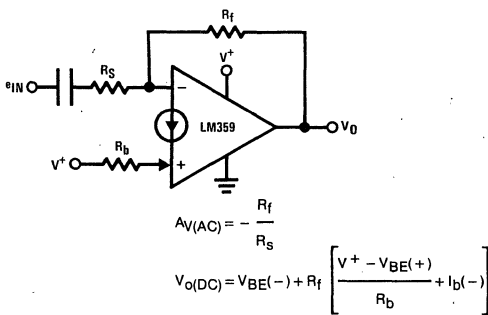


FIGURE 3. Biasing an Inverting AC Amplifier

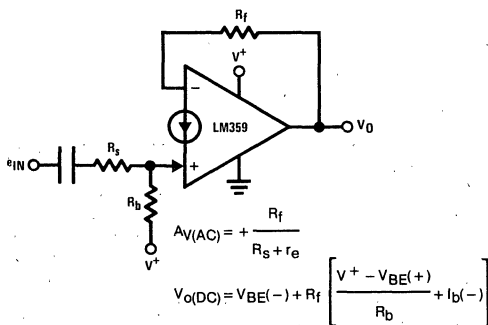


FIGURE 4. Biasing a Non-Inverting AC Amplifier

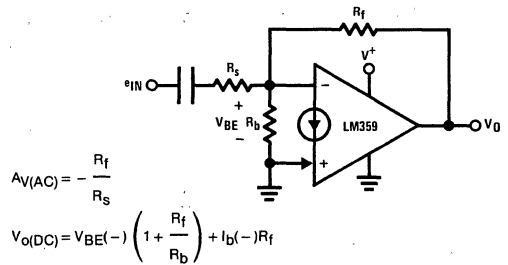


FIGURE 5. nV_{BE} Biasing

The nV_{BE} biasing configuration is most useful for low noise applications where a reduced input impedance can be accommodated (see typical applications section).

OPERATING CURRENT PROGRAMMABILITY (I_{SET})

The input bias current, slew rate, gain bandwidth product, output drive capability and total device power consumption of both amplifiers can be simultaneously controlled and optimized via the two programming pins $I_{SET(OUT)}$ and $I_{SET(IN)}$.

$I_{SET(OUT)}$

The output set current ($I_{SET(OUT)}$) is equal to the amount of current sourced from pin 1 and establishes the class A biasing current for the Darlington emitter follower output stage. Using a single resistor from pin 1 to ground, as shown in *Figure 6*, this current is equal to:

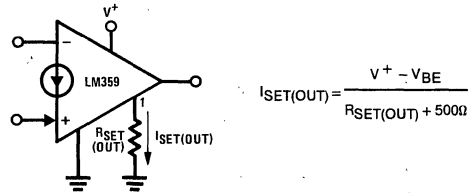


FIGURE 6. Establishing the Output Set Current

The output set current can be adjusted to optimize the amount of current the output of the amplifier can sink to drive load capacitance and for loads connected to V^+ . *The maximum output sinking current is approximately 10 times $I_{SET(OUT)}$.* This set current is best used to reduce the total device supply current if the amplifiers are not required to drive small load impedances.

$I_{SET(IN)}$

The input set current $I_{SET(IN)}$ is equal to the current flowing into pin 8. A resistor from pin 8 to V^+ sets this current to be:

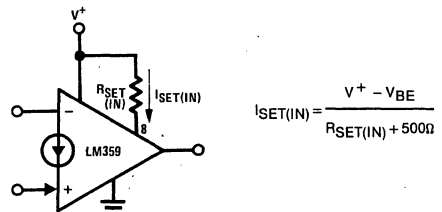


FIGURE 7. Establishing the Input Set Current

Application Hints (Continued)

$I_{SET(IN)}$ is most significant in controlling the AC characteristics of the LM359 as it directly sets the total input stage current of the amplifiers which determines the maximum slew rate, the frequency of the open loop dominant pole, the input resistance of the (-) input and the biasing current $I_b(-)$. All of these parameters are significant in wide band amplifier design. The input stage current is approximately 3 times $I_{SET(IN)}$ and by using this relationship the following first order approximations for these AC parameters are:

$$S_{r(MAX)} = \text{max slew rate} \cong \frac{3I_{SET(IN)}(10^{-6})}{C_{comp}} \quad (V/\mu s)$$

$$\text{frequency of dominant pole} \cong \frac{3I_{SET(IN)}}{2\pi C_{comp} A_{VOL} (0.026 V)} \quad (\text{Hz})$$

$$\text{input resistance} = \beta r_e \cong \frac{150 (0.026 V)}{3I_{SET(IN)}} \quad (\Omega)$$

where C_{comp} is the total capacitance from the compensation pin (pin 3 or pin 13) to ground, A_{VOL} is the low frequency open loop voltage gain in V/V and an ambient temperature of 25°C is assumed ($KT/q = 26 \text{ mV}$ and $\beta_{typ} = 150$). $I_{SET(IN)}$ also controls the DC input bias current by the expression:

$$I_b(-) = \frac{3I_{SET}}{\beta} \cong \frac{I_{SET}}{50} \quad \text{for NPN } \beta = 150$$

which is important for DC biasing considerations.

The total device supply current (for both amplifiers) is also a direct function of the set currents and can be approximated by:

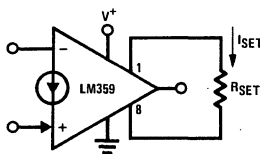
$$I_{supply} \cong 27 \times I_{SET(OUT)} + 11 \times I_{SET(IN)}$$

with each set current programmed by individual resistors.

PROGRAMMING WITH A SINGLE RESISTOR

Operating current programming may also be accomplished using only one resistor by letting $I_{SET(IN)}$ equal $I_{SET(OUT)}$. The programming current is now referred to as I_{SET} and it is created by connecting a resistor from pin 1 to pin 8 (Figure 8).

$$I_{SET} = \frac{V^+ - 2V_{BE}}{R_{SET} + 1 \text{ k}\Omega} \quad \text{where } V_{BE} \cong 0.6V$$



$$I_{SET(IN)} = I_{SET(OUT)} = I_{SET}$$

FIGURE 8. Single Resistor Programming of I_{SET}

This configuration does not affect any of the internal set current dependent parameters differently than previously discussed except the total supply current which is now equal to:

$$I_{supply} \cong 37 \times I_{SET}$$

Care must be taken when using resistors to program the set current to prevent significantly increasing the supply voltage above the value used to determine the set current. This would cause an increase in total supply current due to the resulting increase in set current and the maximum device power dissipation could be exceeded. The set resistor value(s) should be adjusted for the new supply voltage.

One method to avoid this is to use an adjustable current source which has voltage compliance to generate the set current as shown in Figure 9.

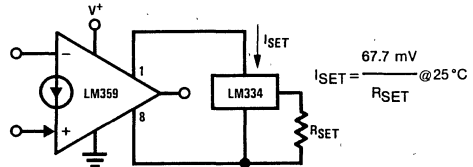


FIGURE 9. Current Source Programming of I_{SET}

This circuit allows I_{SET} to remain constant over the entire supply voltage range of the LM359 which also improves power supply ripple rejection as illustrated in the Typical Performance Characteristics. It should be noted, however, that the current through the LM334 as shown will change linearly with temperature but this can be compensated for (see LM334 data sheet).

Pin 1 must never be shorted to ground or pin 8 never shorted to V^+ without limiting the current to 2 mA or less to prevent catastrophic device failure.

CONSIDERATIONS FOR HIGH FREQUENCY OPERATION

The LM359 is intended for use in relatively high frequency applications and many factors external to the amplifier itself must be considered. Minimization of stray capacitances and their effect on circuit operation are the primary requirements. The following list contains some general guidelines to help accomplish this end:

1. Keep the leads of all external components as short as possible.
2. Place components conducting signal current from the output of an amplifier away from that amplifier's non-inverting input.
3. Use reasonably low value resistances for gain setting and biasing.
4. Use of a ground plane is helpful in providing a shielding effect between the inputs and from input to output. Avoid using vector boards.
5. Use a single-point ground and single-point supply distribution to minimize crosstalk. Always connect the two grounds (one from each amplifier) together.

Application Hints (Continued)

- Avoid use of long wires (> 2") but if necessary, use shielded wire.
- Bypass the supply close to the device with a low inductance, low value capacitor (typically a .01 μF ceramic) to create a good high frequency ground. If long supply leads are unavoidable, a small resistor ($\sim 10\Omega$) in series with the bypass capacitor may be needed and using shielded wire for the supply leads is also recommended.

COMPENSATION

The LM359 is internally compensated for stability with closed loop inverting gains of 10 or more. For an inverting gain of less than 10 and all non-inverting amplifiers (the amplifier always has 100% negative current feedback regardless of the gain in the non-inverting configuration) some external frequency compensation is required because the stray capacitance to ground from the (-) input and the feedback resistor add additional lagging phase within the feedback loop. The value of the input capacitance will typically be in the range of 6 pF to 10 pF for a reasonably constructed circuit board. When using a feedback resistance of 30 k Ω or less, the best method of compensation, without sacrificing slew rate, is to add a lead capacitor in parallel with the feedback resistor with a value on the order of 1 pF to 5 pF as shown in Figure 10.

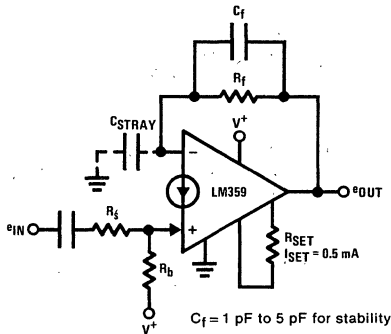


FIGURE 10. Best Method of Compensation

Another method of compensation is to increase the effective value of the internal compensation capacitor by adding capacitance from the COMP pin of an amplifier to ground. An external 20 pF capacitor will generally compensate for all gain settings but will also reduce the gain bandwidth product and the slew rate. These same results can also be obtained by reducing $I_{SET(IN)}$ if the full capabilities of the amplifier are not required. This method is termed over-compensation.

Another area of concern from a stability standpoint is that of capacitive loading. The amplifier will generally drive capacitive loads up to 100 pF without oscillation problems. Any larger C loads can be isolated from the output as shown in Figure 11. Over-compensation of the amplifier can also be used if the corresponding reduction of the GBW product can be afforded.

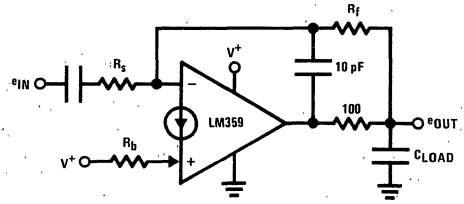


FIGURE 11. Isolating Large Capacitive Loads

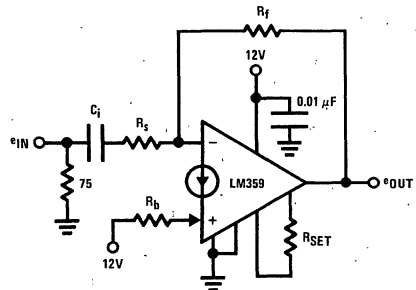
In most applications using the LM359, the input signal will be AC coupled so as not to affect the DC biasing of the amplifier. This gives rise to another subtlety of high frequency circuits which is the effective series inductance (ESL) of the coupling capacitor which creates an increase in the impedance of the capacitor at high frequencies and can cause an unexpected gain reduction. Low ESL capacitors like solid tantalum for large values of C and ceramic for smaller values are recommended. A parallel combination of the two types is even better for gain accuracy over a wide frequency range.

AMPLIFIER DESIGN EXAMPLES

The ability of the LM359 to provide gain at frequencies higher than most monolithic amplifiers can provide makes it most useful as a basic broadband amplification stage. The design of standard inverting and non-inverting amplifiers, though different than standard op amp design due to the current differencing inputs, also entail subtle design differences between the two types of amplifiers. These differences will be best illustrated by design examples. For these examples a practical video amplifier with a passband of 8 Hz to 10 MHz and a gain of 20 dB will be used. It will be assumed that the input will come from a 75 Ω source and proper signal termination will be considered. The supply voltage is 12 V_{DC} and single resistor programming of the operating current, I_{SET} , will be used for simplicity.

AN INVERTING VIDEO AMPLIFIER

- Basic circuit configuration:



- Determine the required I_{SET} from the characteristic curves for gain bandwidth product.

$$GBW_{MIN} = 10 \times 10 \text{ MHz} = 100 \text{ MHz}$$

For a flat response to 10 MHz a closed loop response to two octaves above 10 MHz (40 MHz) will be sufficient.

Application Hints (Continued)

Actual GBW = 10 × 40 MHz = 400 MHz

I_{SET} required = 0.5 mA

$$R_{SET} = \frac{V^+ - 2V_{BE}}{I_{SET}} - 1 \text{ k}\Omega = \frac{10.8\text{V}}{0.5 \text{ mA}} - 1 \text{ k}\Omega = 20.6 \text{ k}\Omega$$

3. Determine maximum value for R_f to provide stable DC biasing

$$I_{f(MIN)} \geq 10 \times \frac{3I_{SET}}{\beta} = 100 \text{ }\mu\text{A} \text{ minimum DC feedback current}$$

Optimum output DC level for maximum symmetrical swing without clipping is:

$$V_{oDC(opt)} = \frac{V_{o(MAX)} - V_{o(MIN)}}{2} + V_{o(MIN)}$$

$$\approx \frac{(V^+ - 3V_{BE}) - 2 \text{ mV}}{2}$$

$$V_{oDC(opt)} \approx \frac{12 - 1.8\text{V}}{2} = \frac{10.2\text{V}}{2} = 5.1 \text{ V}_{DC}$$

$R_{f(MAX)}$ can now be found:

$$R_{f(MAX)} = \frac{V_{oDC(opt)} - V_{BE}(-)}{I_{f(MIN)}} = \frac{5.1\text{V} - 0.6}{100 \text{ }\mu\text{A}} = 45 \text{ k}\Omega$$

This value should not be exceeded for predictable DC biasing.

4. Select R_s to be large enough so as not to appreciably load the input termination resistance:

$$R_s \geq 750 \Omega \text{ Let } R_s = 750 \Omega$$

5. Select R_f for appropriate gain:

$$A_v = -\frac{R_f}{R_s} \text{ so; } R_f = 10R_s = 7.5 \text{ k}\Omega$$

7.5 k Ω is less than the calculated $R_{f(MAX)}$ so DC predictability is insured.

6. Since $R_f = 7.5\text{k}$, for the output to be biased to 5.1 V_{DC} , the reference current $I_{IN}(+)$ must be:

$$I_{IN}(+) = \frac{5.1\text{V} - V_{BE}(-)}{R_f} = \frac{5.1\text{V} - 0.6}{7.5 \text{ k}\Omega} = 600 \text{ }\mu\text{A}$$

Now R_b can be found by:

$$R_b = \frac{V^+ - V_{BE}(+)}{I_{IN}(+)} = \frac{12 - 0.6}{600 \text{ }\mu\text{A}} = 19 \text{ k}\Omega$$

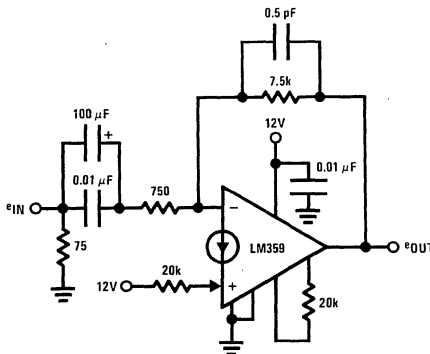
7. Select C_f to provide the proper gain for the 8 Hz minimum input frequency:

$$C_f \geq \frac{1}{2\pi R_s (f_{low})} = \frac{1}{2\pi (750 \Omega) (8 \text{ Hz})} = 26 \text{ }\mu\text{F}$$

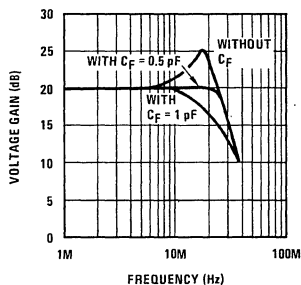
A larger value of C_f will allow a flat frequency response down to 8 Hz and a 0.01 μF ceramic capacitor in parallel with C_f will maintain high frequency gain accuracy.

8. Test for peaking of the frequency response and add a feedback "lead" capacitor to compensate if necessary.

Final Circuit Using Standard 5% Tolerance Resistor Values:



Circuit Performance:



$V_{o(DC)} = 5.1\text{V}$

Differential phase error $< 1^\circ$ for 3.58 MHz f_{IN}

Differential gain error $< 0.5\%$ for 3.58 MHz f_{IN}

$f_{-3 \text{ dB low}} = 2.5 \text{ Hz}$

A NON-INVERTING VIDEO AMPLIFIER

For this case several design considerations must be dealt with.

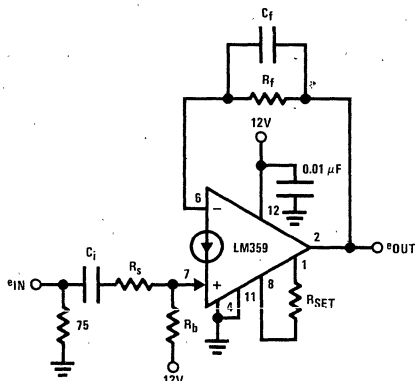
- The output voltage (AC and DC) is strictly a function of the size of the feedback resistor and the sum of AC and DC "mirror current" flowing into the (+) input.
- The amplifier always has 100% current feedback so external compensation is required. Add a small (1 pF-5 pF) feedback capacitance to leave the amplifier's open loop response and slew rate unaffected.
- To prevent saturating the mirror stage the total AC and DC current flowing into the amplifier's (+) input should be less than 2 mA.
- The output's maximum negative swing is one diode above ground due to the V_{BE} diode clamp at the (-) input.

Application Hints (Continued)

DESIGN EXAMPLE:

$e_{IN} = 50$ mV (MAX), $f_{IN} = 10$ MHz (MAX), desired circuit BW = 20 MHz, $A_V = 20$ dB, driving source impedance = 75Ω , $V^+ = 12$ V.

1. Basic circuit configuration:



2. Select I_{SET} to provide adequate amplifier bandwidth so that the closed loop bandwidth will be determined by R_f and C_f . To do this, the set current should program an amplifier open loop gain of at least 20 dB at the desired closed loop bandwidth of the circuit. For this example, an I_{SET} of 0.5 mA will provide 26 dB of open loop gain at 20 MHz which will be sufficient. Using single resistor programming for I_{SET} :

$$R_{SET} = \frac{V^+ - 2V_{BE}}{I_{SET}} - 1 \text{ k}\Omega = 20.6 \text{ k}\Omega$$

3. Since the closed loop bandwidth will be determined

by R_f and C_f $\left(f_{-3 \text{ dB}} = \frac{1}{2\pi R_f C_f} \right)$ to obtain a 20 MHz

bandwidth, both R_f and C_f should be kept small. It can be assumed that C_f can be in the range of 1 pF to 5 pF for carefully constructed circuit boards to insure stability and allow a flat frequency response. This will limit the value of R_f to be within the range of:

$$\frac{1}{2\pi \cdot 5 \text{ pF} \cdot 20 \text{ MHz}} \leq R_f \leq \frac{1}{2\pi \cdot 1 \text{ pF} \cdot 20 \text{ MHz}}$$

$$\text{or } 1.6 \text{ k}\Omega \leq R_f \leq 7.96 \text{ k}\Omega$$

Also, for a closed loop gain of +10, R_f must be 10 times $R_s + r_e$ where r_e is the mirror diode resistance.

4. So as not to appreciably load the 75Ω input termination resistance the value of $(R_s + r_e)$ is set to 750Ω .
5. For $A_V = 10$; R_f is set to $7.5 \text{ k}\Omega$.

6. The optimum output DC level for symmetrical AC swing is:

$$V_{oDC(\text{opt})} = \frac{V_{o(\text{MAX})} - V_{o(\text{MIN})}}{2} + V_{o(\text{MIN})}$$

$$= \frac{(12 - 1.8)\text{V} - 0.6\text{V}}{2} + 0.6\text{V} = 5.4\text{V}_{DC}$$

7. The DC feedback current must be:

$$I_{FB} = \frac{V_{oDC(\text{opt})} - V_{BE(-)}}{R_f} = \frac{5.4\text{V} - 0.6\text{V}}{7.5\text{k}}$$

$$= 640 \mu\text{A} = I_{IN(+)}$$

DC biasing predictability will be insured because $640 \mu\text{A}$ is greater than the minimum of $I_{SET}/5$ or $100 \mu\text{A}$.

For gain accuracy the total AC and DC mirror current should be less than 2 mA. For this example the maximum AC mirror current will be;

$$\frac{\pm e_{in \text{ peak}}}{R_s + r_e} = \frac{\pm 50 \text{ mV}}{750\Omega} = \pm 66 \mu\text{A}$$

therefore the total mirror current range will be $574 \mu\text{A}$ to $706 \mu\text{A}$ which will insure gain accuracy.

8. R_b can now be found:

$$R_b = \frac{V^+ - V_{BE(+)}}{I_{IN(+)}} = \frac{12 - 0.6}{640 \mu\text{A}} = 17.8 \text{ k}\Omega$$

9. Since $R_s + r_e$ will be 750Ω and r_e is fixed by the DC mirror current to be:

$$r_e = \frac{KT}{q I_{IN(+)}} = \frac{26 \text{ mV}}{640 \mu\text{A}} \cong 40\Omega \text{ at } 25^\circ\text{C}$$

R_s must be $750\Omega - 40\Omega$ or 710Ω which can be a 680Ω resistor in series with a 30Ω resistor which are standard 5% tolerance resistor values.

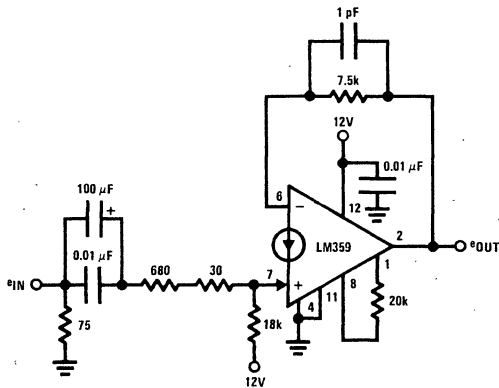
10. As a final design step, C_f must be selected to pass the lower passband frequency corner of 8 Hz for this example.

$$C_f = \frac{1}{2\pi (R_s + r_e) f_{low}} = \frac{1}{2\pi (750\Omega) (8 \text{ Hz})} = 26.5 \mu\text{F}$$

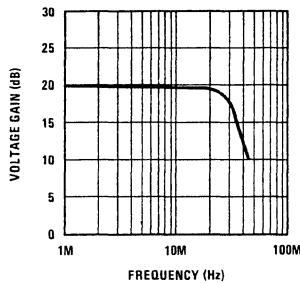
A larger value may be used and a $0.01 \mu\text{F}$ ceramic capacitor in parallel with C_f will maintain high frequency gain accuracy.

Application Hints (Continued)

Final Circuit Using Standard 5% Tolerance Resistor Values:



Circuit Performance:



$V_{O(DC)} = 5.4V$
 Differential phase error $< 0.5^\circ$
 Differential gain error $< 2\%$
 $f_{-3dB\ low} = 2.5\ Hz$

GENERAL PRECAUTIONS

The LM359 is designed primarily for single supply operation but split supplies may be used if the negative supply voltage is well regulated as the amplifiers have no negative supply rejection.

The total device power dissipation must always be kept in mind when selecting an operating supply voltage, the programming current, I_{SET} , and the load resistance, particularly, when DC coupling the output to a succeeding stage. To prevent damaging the current mirror input diode, the mirror current should always be limited to 10

mA, or less, which is important if the input is susceptible to high voltage transients. The voltage at any of the inputs must not be forced more negative than $-0.7V$ without limiting the current to 10 mA.

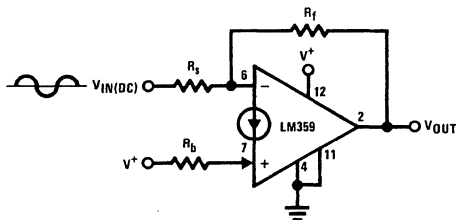
The supply voltage must never be reversed to the device; however, plugging the device into a socket backwards would then connect the positive supply voltage to the pin that has no internal connection (pin 5) which may prevent inadvertent device failure!

3

Typical Applications

DC Coupled Inputs

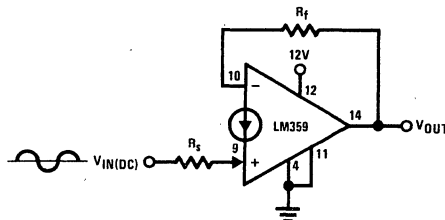
Inverting



$$V_{O(DC)} = \left[\frac{V + -V_{BE(+)} - \frac{V_{IN(DC)} - V_{BE(-)}}{R_S}}{R_b} \right] R_f + V_{BE(-)}$$

$$A_{V(AC)} = - \frac{R_f}{R_S}$$

Non-Inverting



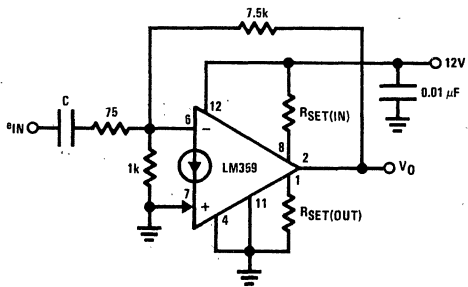
$$V_{O(DC)} = V_{BE(-)} + \frac{(V_{IN(DC)} - V_{BE(+)} R_f)}{R_S}$$

$$A_{V(AC)} = + \frac{R_f}{R_S + r_{e(+)}}$$

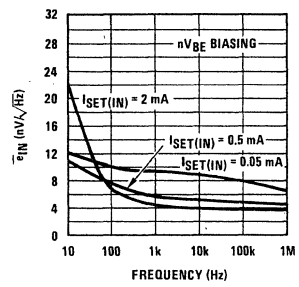
- Eliminates the need for an input coupling capacitor
- input DC level must be stable and can exceed the supply voltage of the LM359 provided that maximum input currents are not exceeded.

Application Hints (Continued)

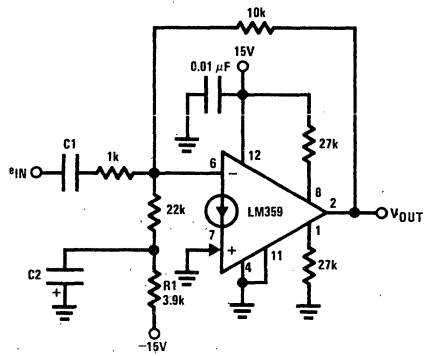
Noise Reduction using nV_{BE} Biasing



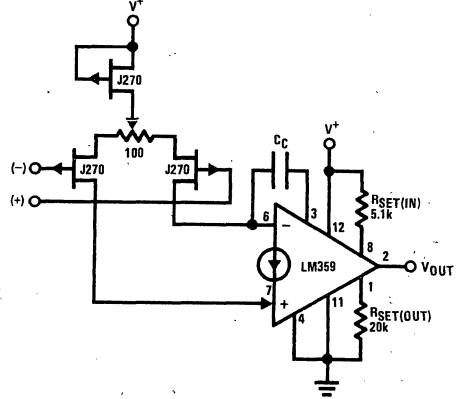
Typical Input Referred Noise Performance



nV_{BE} Biasing with a Negative Supply



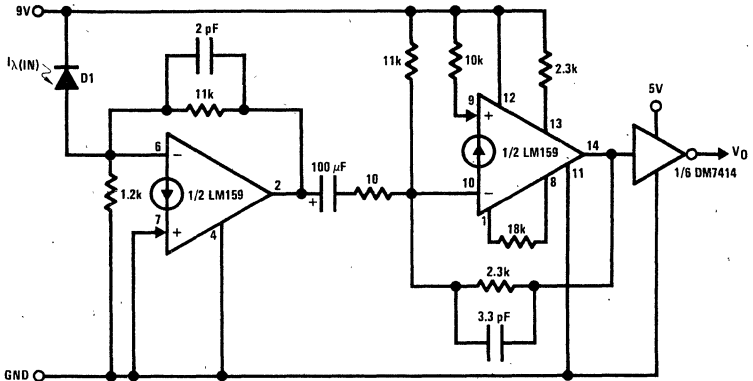
Adding a JFET Input Stage



- R1 and C2 provide additional filtering of the negative biasing supply

- FET input voltage mode op amp
- For $A_V = +1$; BW = 40 MHz, $S_r = 60$ V/μs; $C_C = 51$ pF
- For $A_V = +11$; BW = 24 MHz, $S_r = 130$ V/μs; $C_C = 5$ pF
- For $A_V = +100$; BW = 4.5 MHz, $S_r = 150$ V/μs; $C_C = 2$ pF
- V_{OS} is typically < 25 mV; 100Ω potentiometer allows a V_{OS} adjust range of $\approx \pm 200$ mV
- Inputs must be DC biased for single supply operation

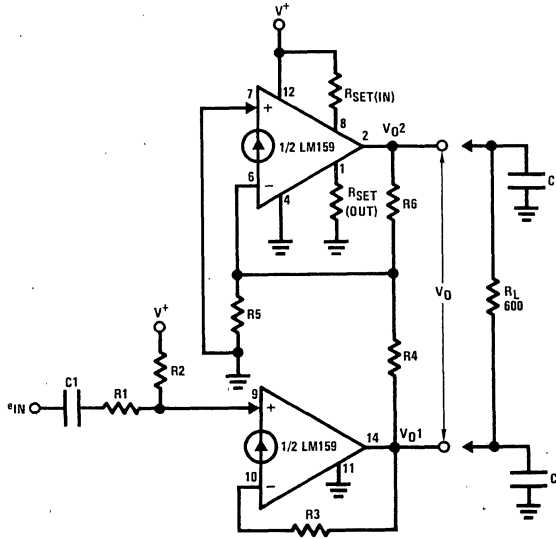
Photo Diode Amplifier



- D1~RCA N-Type Silicon P-I-N Photodiode
- Frequency response of greater than 10 MHz
- If slow rise and fall times can be tolerated the gate on the output can be removed. In this case the rise and the fall time of the LM359 is 40 ns.
- $T_{PDL} = 45$ ns, $T_{PDH} = 50$ ns—T²L output

Typical Applications (Continued)

Balanced Line Driver

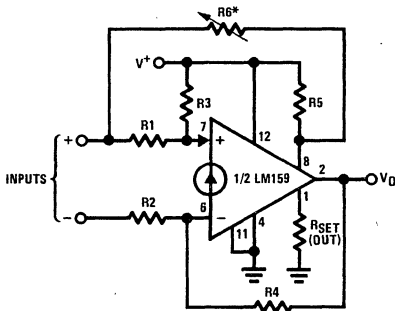


$$\text{For } V_{O1} = V_{O2} = \frac{V^+}{2}, \quad \frac{R_3}{R_2} = \frac{V^+ - \phi}{2(V^+ - \phi)}, \quad \frac{R_6}{R_5} = \frac{V^+ - \phi}{\phi} \quad \text{where } \phi = 0.6V$$

$$A_v = -\frac{R_3}{R_1} \left(\frac{R_6}{R_4} + 1 \right)$$

- 1 MHz—3 dB bandwidth with gain of 10 and 0 dbm into 600Ω
- 0.3% distortion at full bandwidth; reduced to 0.05% with bandwidth of 10 kHz
- Will drive $C_L = 1500$ pF with no additional compensation, ± 0.01 μF with $C_{comp} = 180$ pF
- 70 dB signal to noise ratio at 0 dbm into 600Ω, 10 kHz bandwidth

Difference Amplifier



$$V_{O(DC)} = \frac{R_4}{R_3} (V^+ - \phi) \quad \text{where } \phi = 0.6V$$

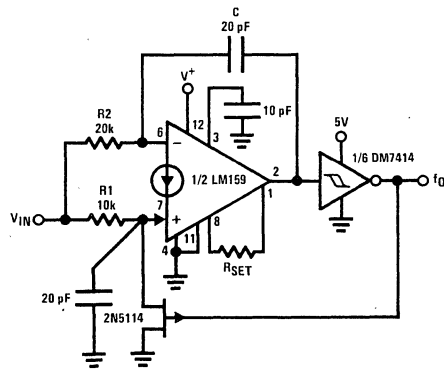
$$A_v = \frac{R_4}{R_1} \quad \text{for } R_1 = R_2$$

*CMRR is adjusted for max at expected CM input signal

$$R_6 \approx \frac{R_5}{5}, \quad \text{for } R_5 = 100 \text{ k}\Omega$$

- Wide bandwidth
- 70 dB CMRR typ
- Wide CM input voltage range

Voltage Controlled Oscillator



$$f_o = \frac{V_{IN} - \phi}{4C\Delta V R_1}$$

where: $R_2 = 2R_1$

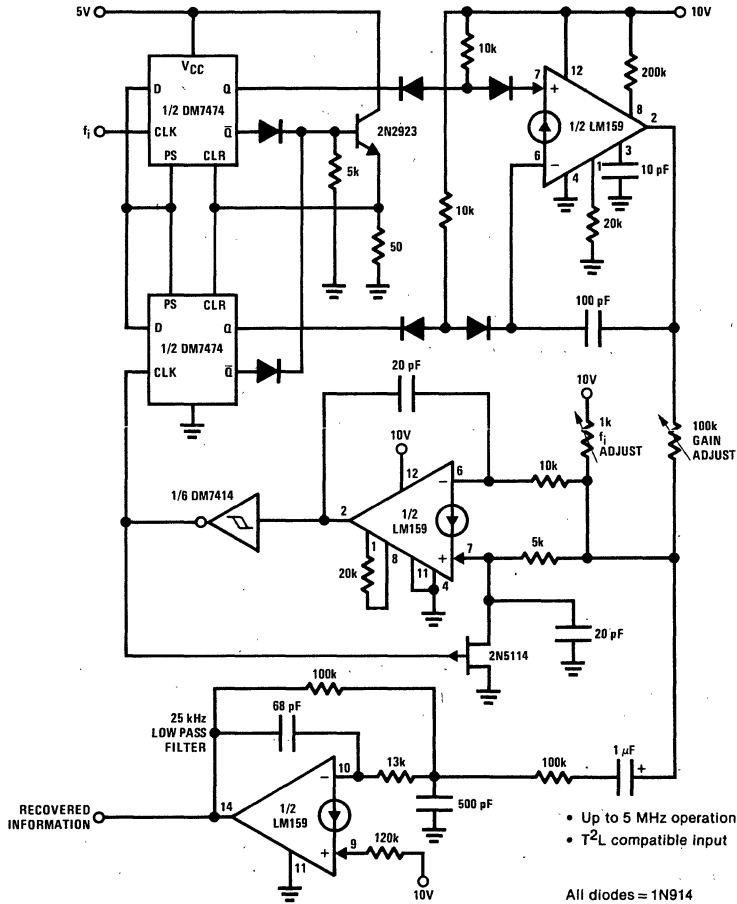
ϕ = amplifier input voltage = 0.6V

$\Delta V = \text{DM7414 hysteresis, typ } 1V$

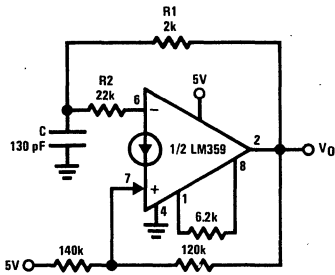
- 5 MHz operation
- T²L output

Typical Applications (Continued)

Phase Locked Loop



Squarewave Generator

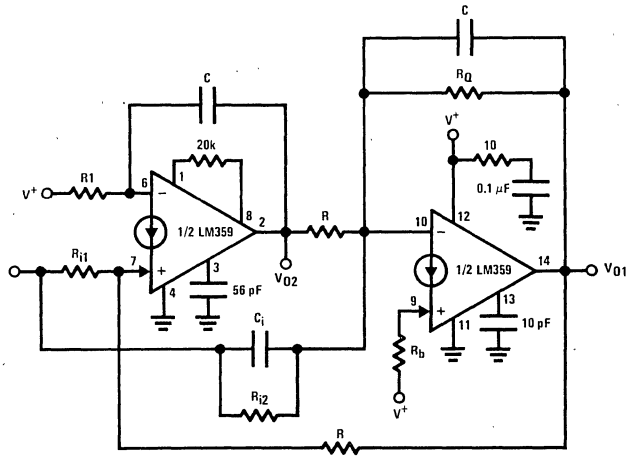


$f = 1 \text{ MHz}$
 Output is TTL compatible
 Frequency is adjusted by R1 & C ($R1 \ll R2$)

Typical Applications

LM159/LM359

High Performance 2 Amplifier Biquad Filter(s)



- The high speed of the LM359 allows the center frequency Q_0 product of the filter to be : $f_0 \times Q_0 \leq 5$ MHz
- The above filter(s) maintains performance over wide temperature range
- One half of LM359 acts as a true non-inverting Integrator so only 2 amplifiers (instead of 3 or 4) are needed for the biquad filter structure

3

DC BIASING EQUATIONS FOR $V_{O1(DC)} \cong V_{O2(DC)} \cong V^+ / 2$

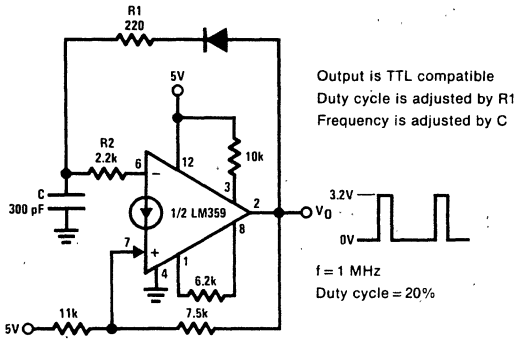
| | |
|----------|--|
| Type I | $\frac{2 V_{IN(DC)}}{V^+ (R_{i2})} + \frac{1}{R} + \frac{1}{R_Q} = \frac{2}{R_b} ; R_1 = 2R$ |
| Type II | $\frac{1}{R} + \frac{1}{R_Q} = \frac{2}{R_b} ; R_1 = 2R$ |
| Type III | $\frac{1}{R} + \frac{1}{R_Q} = \frac{2}{R_b} ; \frac{1}{R_1} = \frac{V_{IN(DC)}}{V^+ (R_{i1})} + \frac{1}{2R}$ |

ANALYSIS AND DESIGN EQUATIONS

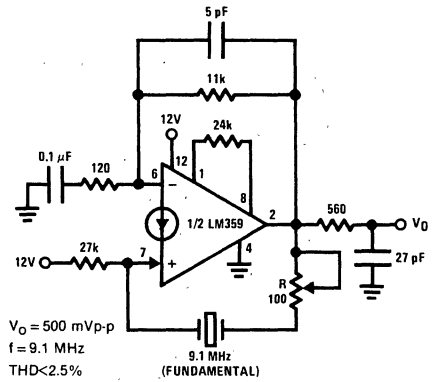
| Type | V_{O1} | V_{O2} | C_i | R_{i2} | R_{i1} | f_0 | Q_0 | f_z (notch) | $H_{o(LP)}$ | $H_{o(BP)}$ | $H_{o(HP)}$ | $H_{o(BR)}$ |
|------|--------------|----------|-------|----------|----------|----------------------|---------|-------------------------------------|-------------|----------------|-------------|---|
| I | BP | LP | O | R_{i2} | ∞ | $\frac{1}{2} \pi RC$ | R_Q/R | — | R/R_{i2} | R_Q/R_{i2} | — | — |
| II | HP | BP | C_i | ∞ | ∞ | $\frac{1}{2} \pi RC$ | R_Q/R | — | — | $R_Q C_i / RC$ | C_i / C | — |
| III | Notch/ BR | — | C_i | ∞ | R_{i1} | $\frac{1}{2} \pi RC$ | R_Q/R | $\frac{1}{2} \pi \sqrt{RR_i C C_i}$ | — | — | — | $H_o \Big _{f \rightarrow \infty} = C_i / C$ $H_o \Big _{f \rightarrow 0} = R / R_i$ |

Typical Applications (Continued)

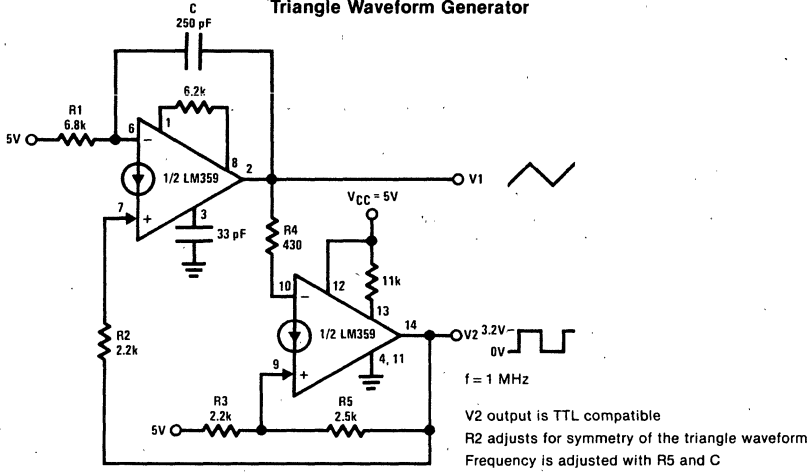
Pulse Generator



Crystal Controlled Sinewave Oscillator



Triangle Waveform Generator



LM192/LM292/LM392, LM2924 Low Power Operational Amplifier/Voltage Comparator

General Description

The LM192 series consists of 2 independent building block circuits. One is a high gain, internally frequency compensated operational amplifier, and the other is a precision voltage comparator. Both the operational amplifier and the voltage comparator have been specifically designed to operate from a single power supply over a wide range of voltages. Both circuits have input stages which will common-mode input down to ground when operating from a single power supply. Operation from split power supplies is also possible and the low power supply current is independent of the magnitude of the supply voltage.

Application areas include transducer amplifier with pulse shaper, DC gain block with level detector, VCO, as well as all conventional operational amplifier or voltage comparator circuits. Both circuits can be operated directly from the standard 5 V_{DC} power supply voltage used in digital systems, and the output of the comparator will interface directly with either TTL or CMOS logic. In addition, the low power drain makes the LM192 extremely useful in the design of portable equipment.

Advantages

- Eliminates need for dual power supplies
- An internally compensated op amp and a precision comparator in the same package
- Allows sensing at or near ground
- Power drain suitable for battery operation
- Pin-out is the same as both the LM158 dual op amp and the LM193 dual comparator

Features

- Wide power supply voltage range
 - Single supply 3V to 32V
 - Dual supply ±1.5V to ±16V
- Low supply current drain—essentially independent of supply voltage 600 μA
- Low input biasing current 50 nA
- Low input offset voltage 2 mV
- Low input offset current 5 nA
- Input common-mode voltage range includes ground
- Differential input voltage range equal to the power supply voltage

ADDITIONAL OP AMP FEATURES

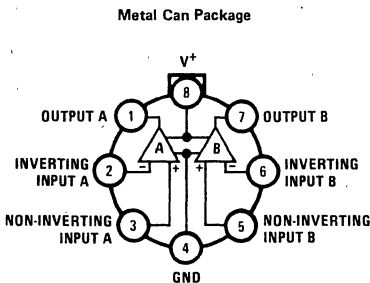
- Internally frequency compensated for unity gain
- Large DC voltage gain 100 dB
- Wide bandwidth (unity gain) 1 MHz
- Large output voltage swing 0V to V⁺ - 1.5V

ADDITIONAL COMPARATOR FEATURES

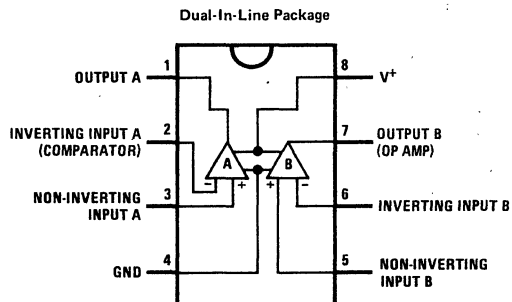
- Low output saturation voltage 250 mV at 4 mA
- Output voltage compatible with all types of logic systems

Connection Diagrams (Top Views)

(Amplifier A = Comparator)
(Amplifier B = Operational Amplifier)



Order Number LM192H, LM292H or LM392H
See NS Package H08C



Order Number LM192J, LM292J, LM392J or LM2924J
See NS Package J08A

Order Number LM392N or LM2924N
See NS Package N08B



Absolute Maximum Ratings

| | LM192/LM292/LM392 | LM2924 |
|---|-------------------|------------------|
| Supply Voltage, V^+ | 32V or $\pm 16V$ | 26V or $\pm 13V$ |
| Differential Input Voltage | 32V | 26V |
| Input Voltage | -0.3V to +32V | -0.3V to +26V |
| Power Dissipation (Note 1) | | |
| Molded DIP (LM392N, LM2924N) | 570 mW | 570 mW |
| Metal Can (LM192H/LM292H/LM392H) | 830 mW | |
| Output Short-Circuit to Ground (Note 2) | Continuous | Continuous |
| Input Current ($V_{IN} < -0.3 V_{DC}$) (Note 3) | 50 mA | 50 mA |
| Operating Temperature Range | | |
| LM392 | 0°C to +70°C | -40°C to +85°C |
| LM292 | -25°C to +85°C | |
| LM192 | -55°C to +125°C | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics ($V^+ = 5 V_{DC}$; specifications apply to both amplifiers unless otherwise stated) (Note 4)

| PARAMETER | CONDITIONS | LM192 | | | LM292/LM392 | | | LM2924 | | | UNITS |
|---------------------------------|---|-------|---------|-------------|-------------|---------|-------------|--------|---------|-------------|---------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ C$, (Note 5) | | ± 2 | ± 5 | | ± 2 | ± 5 | | ± 2 | ± 7 | mV |
| Input Bias Current | IN(+) or IN(-), $T_A = 25^\circ C$, (Note 6) | | 50 | 150 | | 50 | 250 | | 50 | 250 | nA |
| Input Offset Current | IN(+) - IN(-), $T_A = 25^\circ C$ | | ± 3 | ± 25 | | ± 5 | ± 50 | | ± 5 | ± 50 | nA |
| Input Common-Mode Voltage Range | $V^+ = 30 V_{DC}$, $T_A = 25^\circ C$, (Note 7) | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | V |
| Supply Current | $R_L = \infty$, $V_{CC} = 30V$, (LM2924, $V_{CC} = 26V$) | | 1 | 2 | | 1 | 2 | | 1 | 2 | mA |
| Supply Current | $R_L = \infty$, $V_{CC} = 5V$ | | 0.5 | 1 | | 0.5 | 1 | | 0.5 | 1 | mA |
| Amplifier-to-Amplifier Coupling | $f = 1 \text{ kHz to } 20 \text{ kHz}$, $T_A = 25^\circ C$, Input Referred, (Note 8) | | -100 | | | -100 | | | -100 | | dB |
| Input Offset Voltage | (Note 5) | | | ± 7 | | | ± 7 | | | ± 10 | mV |
| Input Bias Current | IN(+) or IN(-) | | | 300 | | | 400 | | | 500 | nA |
| Input Offset Current | IN(+) - IN(-) | | | 100 | | | 150 | | | 200 | nA |
| Input Common-Mode Voltage Range | $V^+ = 30 V_{DC}$, (Note 7) | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | 0 | | $V^+ - 2$ | V |
| Differential Input Voltage | Keep All $V_{IN}'s \geq 0 V_{DC}$ (or V^- , if Used), (Note 9) | | | V^+ | | | V^+ | | | V^+ | V |
| OP AMP ONLY | | | | | | | | | | | |
| Large Signal Voltage Gain | $V^+ = 15 V_{DC}$ (For Large V_O Swing), $R_L = 2 \text{ k}\Omega$, $T_A = 25^\circ C$ | 50 | 100 | | 25 | 100 | | | 100 | | V/mV |
| Output Voltage Swing | $R_L = 2 \text{ k}\Omega$, $T_A = 25^\circ C$, (LM2924, $R_L \geq 10 \text{ k}\Omega$) | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | V |
| Common-Mode Rejection Ratio | DC, $T_A = 25^\circ C$ | 70 | 85 | | 65 | 70 | | 50 | 70 | | dB |
| Power Supply Rejection Ratio | DC, $T_A = 25^\circ C$ | 65 | 100 | | 65 | 100 | | 50 | 100 | | dB |
| Output Current Source | $V_{IN}(+) = 1 V_{DC}$, $V_{IN}(-) = 0 V_{DC}$, $V^+ = 15 V_{DC}$, $T_A = 25^\circ C$ | 20 | 40 | | 20 | 40 | | 20 | 40 | | mA |
| Output Current Sink | $V_{IN}(-) = 1 V_{DC}$, $V_{IN}(+) = 0 V_{DC}$, $V^+ = 15 V_{DC}$, $V_O \geq 1 V_{DC}$, $T_A = 25^\circ C$ | 10 | 20 | | 10 | 20 | | 10 | 20 | | mA |
| | $V_{IN}(-) = 1 V_{DC}$, $V_{IN}(+) = 0 V_{DC}$, $V^+ = 15 V_{DC}$, $V_O = 200 \text{ mV}$, $T_A = 25^\circ C$ | 12 | 50 | | 12 | 50 | | 12 | 50 | | μA |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM192 | | | LM292/LM392 | | | LM2924 | | | UNITS |
|----------------------------|--|-------|-----|-----|-------------|-----|-----|--------|-----|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage Drift | $R_S = 0\Omega$ | | 7 | | | 7 | | | 7 | | $\mu V/^\circ C$ |
| Input Offset Current Drift | $R_S = 0\Omega$ | | 10 | | | 10 | | | 10 | | $pA/^\circ C$ |
| COMPARATOR ONLY | | | | | | | | | | | |
| Voltage Gain | $R_L \geq 15 k\Omega$, $V^+ = 15 V_{DC}$, $T_A = 25^\circ C$ | 50 | 200 | | 50 | 200 | | 25 | 100 | | $V/\mu V$ |
| Large Signal Response Time | $V_{IN} = TTL$ Logic Swing, $V_{REF} = 1.4 V_{DC}$, $V_{RL} = 5 V_{DC}$, $R_L = 5.1 k\Omega$, $T_A = 25^\circ C$ | | 300 | | | 300 | | | 300 | | ns |
| Response Time | $V_{RL} = 5 V_{DC}$, $R_L = 5.1 k\Omega$, $T_A = 25^\circ C$, (Note 10) | | 1.3 | | | 1.3 | | | 1.5 | | μs |
| Output Sink Current | $V_{IN(-)} = 1 V_{DC}$, $V_{IN(+)} = 0 V_{DC}$, $V_O \leq 1.5 V_{DC}$, $T_A = 25^\circ C$ | 6 | 16 | | 6 | 16 | | 6 | 16 | | mA |
| Saturation Voltage | $V_{IN(-)} \geq 1 V_{DC}$, $V_{IN(+)} = 0$, $I_{SINK} \leq 4 mA$, $T_A = 25^\circ C$ | | 250 | 400 | | 250 | 400 | | | 400 | mV |
| | $V_{IN(-)} \geq 1 V_{DC}$, $V_{IN(+)} = 0$, $I_{SINK} \leq 4 mA$ | | | 700 | | | 700 | | | 700 | mV |
| Output Leakage Current | $V_{IN(-)} = 0$, $V_{IN(+)} \geq 1 V_{DC}$, $V_O = 5 V_{DC}$, $T_A = 25^\circ C$ | | 0.1 | | | 0.1 | | | 0.1 | | nA |
| | $V_{IN(-)} = 0$, $V_{IN(+)} \geq 1 V_{DC}$, $T_A = 25^\circ C$ | | | 1.0 | | | 1.0 | | | 1.0 | μA |
| | $V_{IN(+)} \geq 1 V_{DC}$, $V_O = 30 V_{DC}$ | | | | | | | | | | |

Note 1: For operating at temperatures above $25^\circ C$, the LM392N and the LM2924N must be derated based on a $125^\circ C$ maximum junction temperature and a thermal resistance of $175^\circ C/W$ which applies for the device soldered in a printed circuit board, operating in still air ambient. The LM192H/LM292H/LM392H must be derated based on a $150^\circ C$ maximum junction temperature and a thermal resistance of $150^\circ C/W$. The dissipation is the total of both amplifiers—use external resistors, where possible, to allow the amplifier to saturate or to reduce the power which is dissipated in the integrated circuit.

Note 2: Short circuits from the output to V^+ can cause excessive heating and eventual destruction. The maximum output current is approximately 40 mA for the op amp and 30 mA for the comparator independent of the magnitude of V^+ . At values of supply voltage in excess of 15V, continuous short circuits can exceed the power dissipation ratings and cause eventual destruction.

Note 3: This input current will only exist when the voltage at any of the input leads is driven negative. It is due to the collector-base junction of the input PNP transistors becoming forward biased and thereby acting as input diode clamps. In addition to this diode action, there is also lateral NPN parasitic transistor action on the IC chip. This transistor action can cause the output voltages of the amplifiers to go to the V^+ voltage level (or to ground for a large overdrive) for the time duration that an input is driven negative. This is not destructive and normal output states will re-establish when the input voltage, which was negative, again returns to a value greater than $-0.3V$.

Note 4: These specifications apply for $V^+ = 5V$ and $-55^\circ C \leq T_A \leq +125^\circ C$, unless otherwise stated. For the LM292, all temperature specifications are limited to $-25^\circ C \leq T_A \leq +85^\circ C$, the LM392 temperature specifications are limited to $0^\circ C \leq T_A \leq +70^\circ C$ and the LM2924 temperature specifications are limited to $-40^\circ C \leq T_A \leq +85^\circ C$.

Note 5: At output switch point, $V_O \cong 1.4V$, $R_S = 0\Omega$ with V^+ from 5V to 30V; and over the full input common-mode range (0V to $V^+ - 1.5V$).

Note 6: The direction of the input current is out of the IC due to the PNP input stage. This current is essentially constant, independent of the state of the output so no loading change exists on the input lines.

Note 7: The input common-mode voltage or either input signal voltage should not be allowed to go negative by more than 0.3V. The upper end of the common-mode voltage range is $V^+ - 1.5V$, but either or both inputs can go to 32V without damage (26V for LM2924).

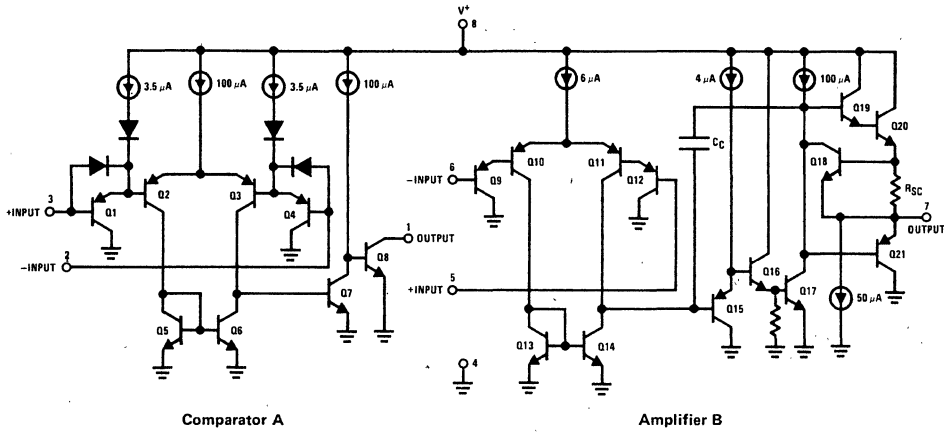
Note 8: Due to proximity of external components, insure that coupling is not originating via the stray capacitance between these external parts. This typically can be detected as this type of capacitive increases at higher frequencies.

Note 9: Positive excursions of input voltage may exceed the power supply level. As long as the other input voltage remains within the common-mode range, the comparator will provide a proper output state. The input voltage to the op amp should not exceed the power supply level. The input voltage state must not be less than $-0.3V$ (or 0.3V below the magnitude of the negative power supply, if used) on either amplifier.

Note 10: The response time specified is for a 100 mV input step with 5 mV overdrive. For larger overdrive signals 300 ns can be obtained.

Note 11: For input signals that exceed V_{CC} , only the overdrive amplifier is affected. With a 5V supply, V_{IN} should be limited to 25V max, and a limiting resistor should be used on all inputs that might exceed the positive supply.

Schematic Diagram



Application Hints

Please refer to the application hints section of the LM193 and the LM158 data sheets.

LM216/LM316, LM216A/LM316A Operational Amplifiers

General Description

These devices are precision, high input impedance operational amplifiers designed for applications requiring extremely low input-current errors. They use supergain transistors in a Darlington input stage to get input bias currents that are equal to high-quality FET amplifiers—even in limited temperature range operation. The low input current is, however, obtained with some sacrifice to offset voltage, offset voltage drift and noise when compared to the non-Darlington LM112 series. Note-worthy specifications include:

- Guaranteed bias currents as low as 50 pA
- Maximum offset currents down to 15 pA
- Operates from supplies of $\pm 3V$ to $\pm 20V$
- Supply current only 300 μA at $\pm 20V$

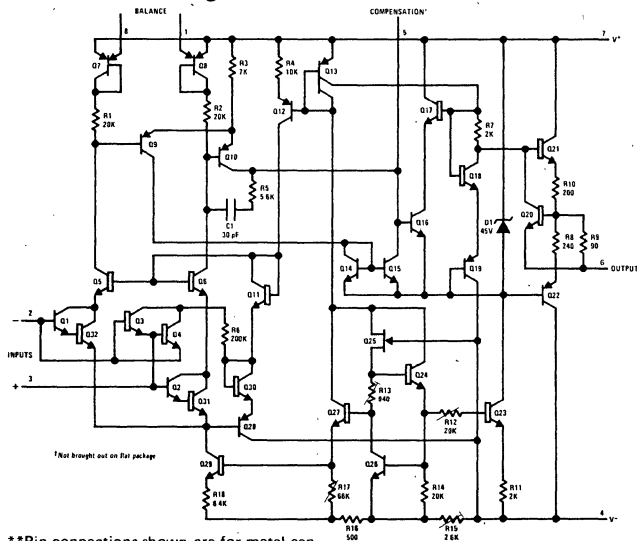
These operational amplifiers are internally frequency compensated and have provisions for offset balancing with a single external potentiometer.

Further, unlike most other internally compensated amplifiers, the MOS compensation capacitor is protected to prevent catastrophic failure from overvoltage spikes on the supplies.

The low current error of these amplifiers make possible many designs that were previously impractical with monolithic amplifiers. They will operate from 100 M Ω source resistances, introducing less error than general purpose amplifiers with 10 k Ω sources. Integrators with worst case drifts less than 10 $\mu V/sec$ and analog time delays in excess of one day can also be made using capacitors no larger than 1 μF .

The LM216A and LM316A are high performance versions of the LM216 and LM316. The LM216 and LM216A are specified for operation from $-25^{\circ}C$ to $85^{\circ}C$, while the LM316 and LM316A are specified from $0^{\circ}C$ to $55^{\circ}C$.

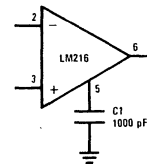
Schematic Diagram **



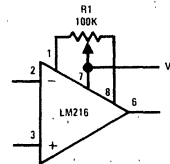
**Pin connections shown are for metal can.

Auxiliary Circuits **

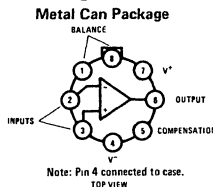
Overcompensation for Greater Stability Margin



Offset Balancing

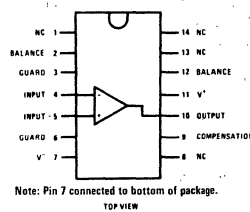


Connection Diagrams



Order Number LM216H or LM216AH or LM316H or LM316AH
See NS Package H08C

Dual-In-Line Package



Order Number LM216D or LM216AD or LM316D or LM316AD
See NS Package D14E



Absolute Maximum Ratings

| | | |
|--------------------------------------|----------------|---------------|
| Supply Voltage | ±20V | |
| Power Dissipation (Note 1) | 500 mW | |
| Differential Input Current (Note 2) | ±10 mA | |
| Input Voltage (Note 3) | ±15V | |
| Output Short-Circuit Duration | Indefinite | |
| Operating Temperature Range | LM216/LM216A | -25°C to 85°C |
| | LM316/LM316A | 0°C to 70°C |
| Storage Temperature Range | -65°C to 150°C | |
| Lead Temperature (Soldering, 10 sec) | 300°C | |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | LM216A | LM216 | LM316A | LM316 | UNITS |
|--------------------------------|---|--------|-------|--------|-------|-------|
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, Max | 3 | 10 | 3 | 10 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$, Max | 15 | 50 | 15 | 50 | pA |
| Input Bias Current | $T_A = 25^\circ\text{C}$, Max | 50 | 150 | 50 | 150 | pA |
| Input Resistance | $T_A = 25^\circ\text{C}$, Min | 5 | 1 | 5 | 1 | GΩ |
| Supply Current | $T_A = 25^\circ\text{C}$, Max | 0.6 | 0.8 | 0.6 | 0.8 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L \geq 10\text{ k}\Omega$, Min | 40 | 20 | 40 | 20 | V/mV |
| Input Offset Voltage | Max | 6 | 15 | 6 | 15 | mV |
| Input Offset Current | Max | 30 | 100 | 30 | 100 | pA |
| Input Bias Current | Max | 100 | 250 | 100 | 250 | pA |
| Supply Current | $T_A = T_{MAX}$, Max | 0.5 | | 0.5 | | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$, $R_L > 10\text{ k}\Omega$, Min | 20 | 10 | 30 | 15 | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$, Min | ±13 | ±13 | ±13 | ±13 | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$, Min | ±13 | ±13 | ±13 | ±13 | V |
| Common-Mode Rejection Ratio | Min | 80 | 80 | 80 | 80 | dB |
| Supply Voltage Rejection Ratio | Min | 80 | 80 | 80 | 80 | dB |

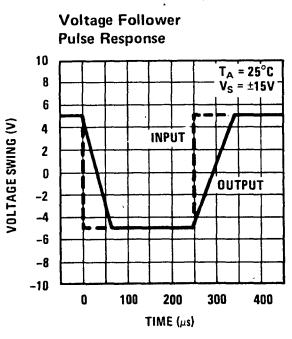
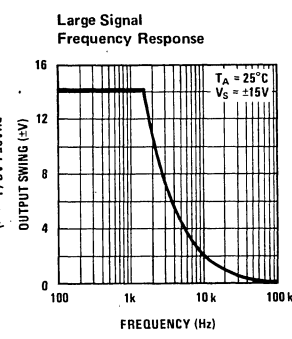
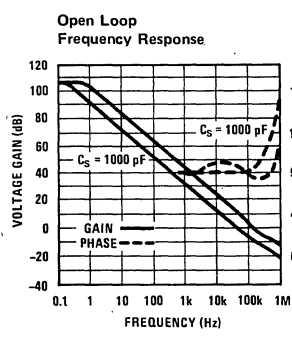
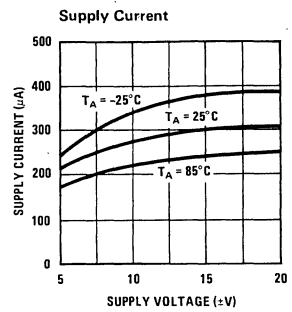
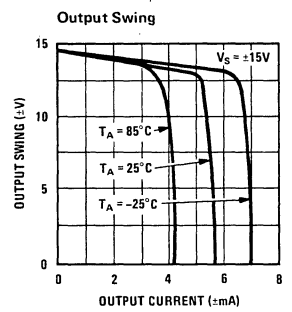
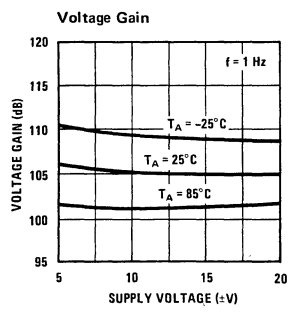
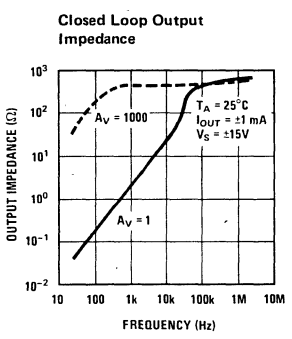
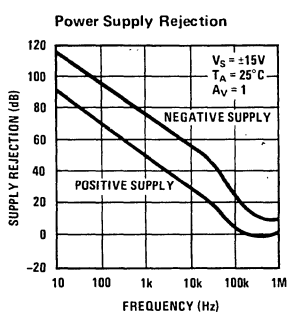
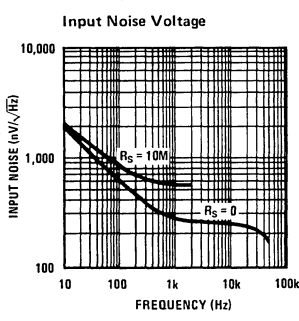
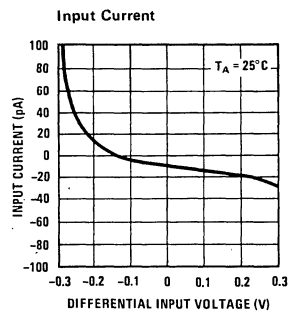
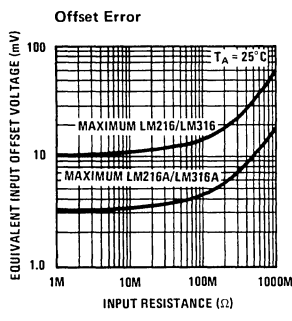
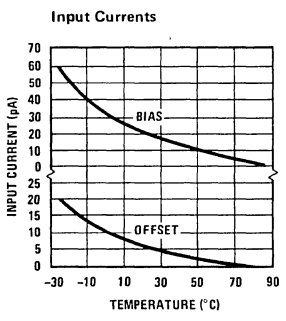
Note 1: The maximum junction temperature of the LM216 and LM216A is 100°C, while that of the LM316 and LM316A is 70°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with ten, 0.03-inch-wide, 2-ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs unless some limiting resistance is used.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$, unless otherwise specified. With the LM316 and LM316A however, all temperature specifications are limited to $0^\circ\text{C} \leq T_A \leq 55^\circ\text{C}$.

Typical Performance Characteristics





Operational Amplifiers/Buffers

LM709/LM709A/LM709C Operational Amplifier

General Description

The LM709 series are a monolithic operational amplifier intended for general-purpose applications. Operation is completely specified over the range of voltages commonly used for these devices. The design, in addition to providing high gain, minimizes both offset voltage and bias currents. Further, the class-B output stage gives a large output capability with minimum power drain.

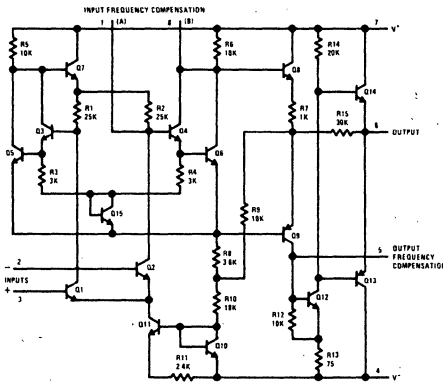
External components are used to frequency compensate the amplifier. Although the unity-gain compensation network specified will make the amplifier unconditionally stable in all feedback

configurations, compensation can be tailored to optimize high-frequency performance for any gain setting.

The fact that the amplifier is built on a single silicon chip provides low offset and temperature drift at minimum cost. It also ensures negligible drift due to temperature gradients in the vicinity of the amplifier.

The LM709C is commercial-industrial version of the LM709. It is identical to the LM709/LM709A except that it is specified for operation from 0°C to +70°C.

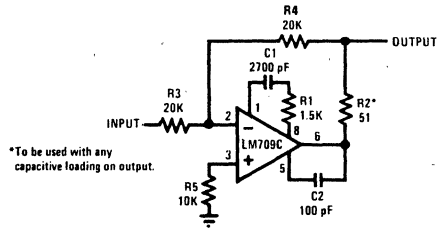
Schematic Diagram **



**Pin connections shown are for metal can package.

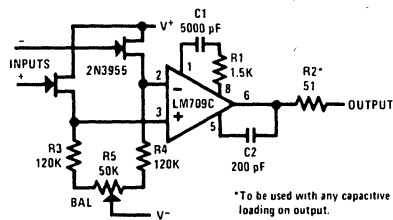
Typical Applications **

Unity Gain Inverting Amplifier



*To be used with any capacitive loading on output.

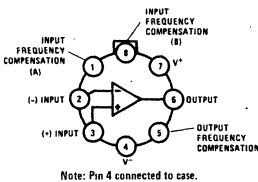
FET Operational Amplifier



*To be used with any capacitive loading on output.

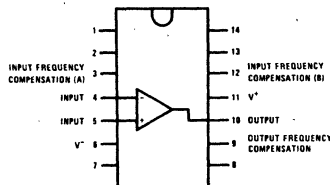
Connection Diagrams

Metal Can Package



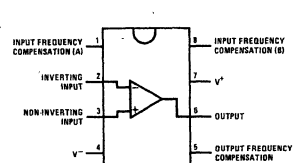
Order Number LM709H or LM709CH
See NS Package H08C

Dual-In-Line Package



Order Number LM709CN
See NS Package N14A

Dual-In-Line Package



Order Number LM709CN-8
See NS Package N08A

Absolute Maximum Ratings

| | LM709/LM709A | LM709C |
|--|--|--|
| Supply Voltage | ±18V | ±18V |
| Power Dissipation (Note 1) | 300 mW | 250 mW |
| Differential Input Voltage | ±5V | ±5V |
| Input Voltage | ±10V | ±10V |
| Output Short-Circuit Duration ($T_A = 25^\circ\text{C}$) | 5 seconds | 5 seconds |
| Storage Temperature Range | $T_{\text{MIN}} \quad T_{\text{MAX}}$ -65°C to +150°C | $T_{\text{MIN}} \quad T_{\text{MAX}}$ -65°C to +150°C |
| Operating Temperature Range | -55°C to +125°C | 0°C to +70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 2)

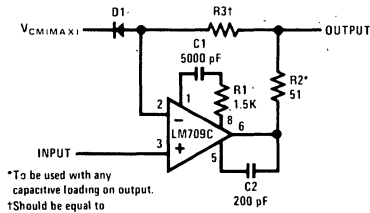
| PARAMETER | CONDITIONS | LM709A | | LM709 | | LM709C | | UNITS |
|---|---|--------|---------|-------|---------|--------|---------|------------------------------|
| | | MIN | TYP MAX | MIN | TYP MAX | MIN | TYP MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}, R_S \leq 10 \text{ k}\Omega$ | 0.6 | 2.0 | 1.0 | 5.0 | 2.0 | 7.5 | mV |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 100 | 200 | 200 | 500 | 300 | 1500 | nA |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | 10 | 50 | 50 | 200 | 100 | 500 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 350 | 700 | 150 | 400 | 50 | 250 | k Ω |
| Output Resistance | $T_A = 25^\circ\text{C}$ | 150 | | 150 | | 150 | | Ω |
| Supply Current | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ | 2.5 | 3.6 | 2.6 | 5.5 | 2.6 | 6.6 | mA |
| Transient Response | $V_{\text{IN}} = 20 \text{ mV}, C_L \leq 100 \text{ pF}$ | | | | | | | |
| Risettime | $T_A = 25^\circ\text{C}$ | | 1.5 | 0.3 | 1.0 | 0.3 | 1.0 | μs |
| Overshoot | | | 30 | 10 | 30 | 10 | 30 | % |
| Slew Rate | $T_A = 25^\circ\text{C}$ | 0.25 | | 0.25 | | 0.25 | | V/ μs |
| Input Offset Voltage | $R_S \leq 10 \text{ k}\Omega$ | | 3.0 | | 6.0 | | 10 | mV |
| Average Temperature Coefficient of Input Offset Voltage | $R_S = 50 \Omega$ $T_A = 25^\circ\text{C}$ to T_{MAX} | 1.8 | 10 | 3.0 | | 6.0 | | $\mu\text{V}/^\circ\text{C}$ |
| | $T_A = 25^\circ\text{C}$ to T_{MIN} | 1.8 | 10 | 6.0 | | 12 | | $\mu\text{V}/^\circ\text{C}$ |
| | $R_S = 10 \text{ k}\Omega$ $T_A = 25^\circ\text{C}$ to T_{MAX} | 2.0 | 15 | | | | | |
| | $T_A = 25^\circ\text{C}$ to T_{MIN} | 4.8 | 25 | | | | | |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, R_L \geq 2 \text{ k}\Omega$ $V_{\text{OUT}} = \pm 10\text{V}$ | 25 | 70 | 25 | 45 70 | 15 | 45 | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 10 \text{ k}\Omega$ | ±12 | ±14 | ±12 | ±14 | ±12 | ±14 | V |
| | $V_S = \pm 15\text{V}, R_L = 2 \text{ k}\Omega$ | ±10 | ±13 | ±10 | ±13 | ±10 | ±13 | V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±8.0 | | ±8.0 | ±10.0 | ±8.0 | ±10 | V |
| Common-Mode Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$ | 80 | 110 | 70 | 90 | 65 | 90 | dB |
| Supply Voltage Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$ | 40 | 100 | 25 | 150 | 25 | 200 | $\mu\text{V}/\text{V}$ |
| Input Offset Current | $T_A = T_{\text{MAX}}$ | 3.5 | 50 | 20 | 200 | 75 | 400 | nA |
| | $T_A = T_{\text{MIN}}$ | 40 | 250 | 100 | 500 | 125 | 750 | nA |
| Input Bias Current | $T_A = T_{\text{MIN}}$ | 0.3 | 0.6 | 0.5 | 1.5 | 0.36 | 2.0 | μA |
| Input Resistance | $T_A = T_{\text{MIN}}$ | 85 | 170 | 40 | 100 | 50 | 250 | k Ω |

Note 1: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction temperature for LM709/LM709A and 100°C maximum for LM709C and a thermal resistance of 150°C/W junction to ambient or 45°C/W, junction to case for the metal can package. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick, epoxy glass board with ten, 0.03-inch-thick, 2-ounce copper conductors (see curve).

Note 2: These specifications apply for $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for LM709/LM709A and $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ for LM709C with the following conditions: $\pm 9\text{V} \leq V_S \leq \pm 15\text{V}$, $C_1 = 5000 \text{ pF}$, $R_1 = 1.5\text{k}\Omega$, $C_2 = 200 \text{ pF}$ and $R_2 = 51 \Omega$.

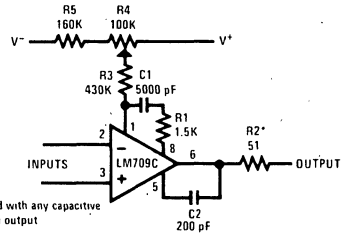
Typical Applications (Continued)

Voltage Follower



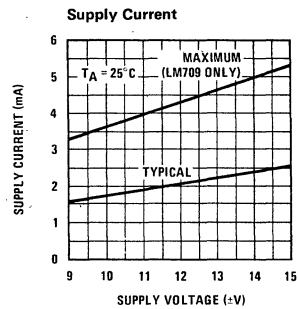
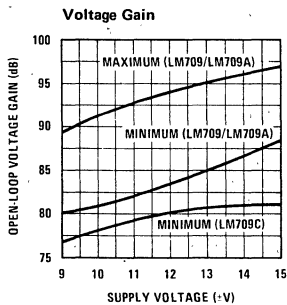
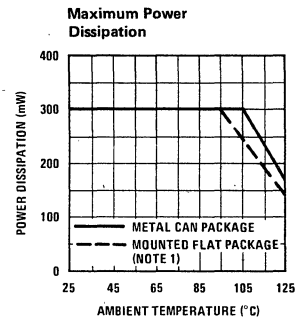
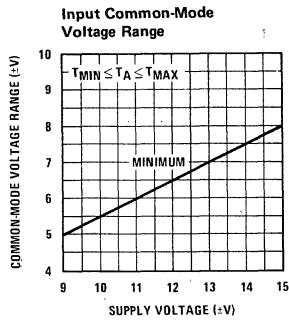
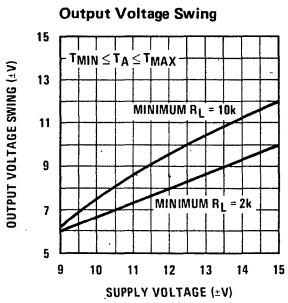
*To be used with any capacitive loading on output.
†Should be equal to dc source resistance on input

Offset Balancing Circuit

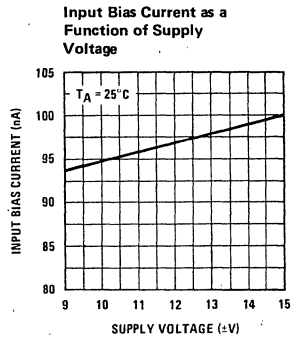
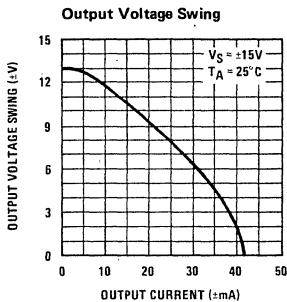
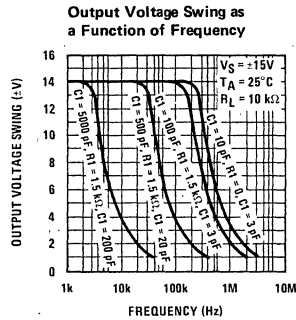
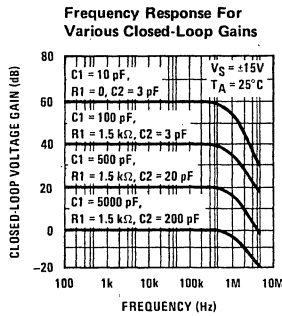
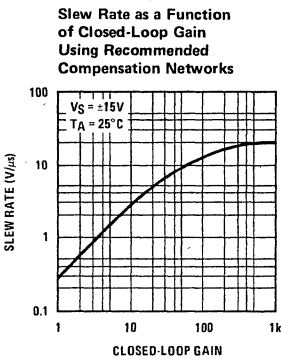
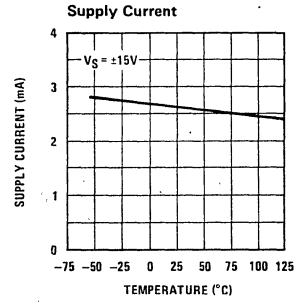
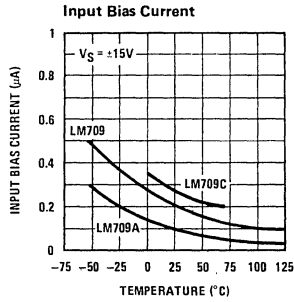
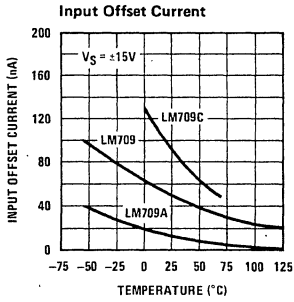


*To be used with any capacitive loading on output

Guaranteed Performance Characteristics



Typical Performance Characteristics





Operational Amplifiers/Buffers

LM725/LM725A/LM725C (Instrumentation) Operational Amplifier

General Description

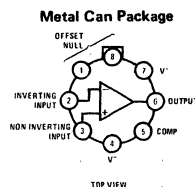
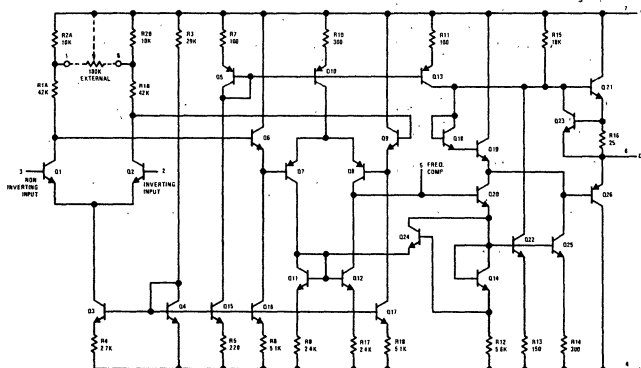
The LM725/LM725A/LM725C are operational amplifiers featuring superior performance in applications where low noise, low drift, and accurate closed-loop gain are required. With high common mode rejection and offset null capability, it is especially suited for low level instrumentation applications over a wide supply voltage range.

The LM725A has tightened electrical performance with higher input accuracy and like the LM725, is guaranteed over a -55°C to $+125^{\circ}\text{C}$ temperature range. The LM725C has slightly relaxed specifications and has its performance guaranteed over a 0°C to 70°C temperature range.

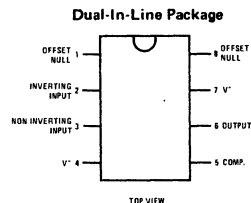
Features

- High open loop gain 3,000,000
- Low input voltage drift $0.6 \mu\text{V}/^{\circ}\text{C}$
- High common mode rejection 120 dB
- Low input noise current $0.15 \text{ pA}/\sqrt{\text{Hz}}$
- Low input offset current 2 nA
- High input voltage range $\pm 14\text{V}$
- Wide power supply range $\pm 3\text{V}$ to $\pm 22\text{V}$
- Offset null capability
- Output short circuit protection

Schematic and Connection Diagrams



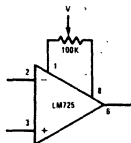
Order Number LM725H or LM725AH or LM725CH
See NS Package H08C



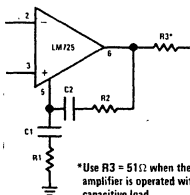
Order Number LM725CN
See NS Package N08B

Auxiliary Circuits

Voltage Offset Null Circuit



Frequency Compensation Circuit



*Use R3 = 51Ω when the amplifier is operated with capacitive load.

Compensation Component Values

| A_{VCL} | R1 (Ω) | C1 (μF) | R2 (Ω) | C2 (μF) |
|-----------|--------|---------|--------|---------|
| 10,000 | 10K | 50 pF | — | — |
| 1,000 | 470 | .001 | — | — |
| 100 | 47 | .01 | — | — |
| 10 | 27 | .05 | 270 | .0015 |
| 1 | 10 | .05 | 39 | .02 |

Absolute Maximum Ratings

| | | | | |
|--------------------------------------|-----------------|-----------------------------|----------------------|----------------------|
| Supply Voltage | ±22V | Operating Temperature Range | T _A (MIN) | T _A (MAX) |
| Internal Power Dissipation (Note 1) | 500 mW | LM725 | -55°C | to +125°C |
| Differential Input Voltage | ±5V | LM725A | -55°C | to +125°C |
| Input Voltage (Note 2) | ±22V | LM725C | 0°C | to +70°C |
| Storage Temperature Range | -65°C to +150°C | | | |
| Lead Temperature (Soldering, 10 sec) | 300°C | | | |

Electrical Characteristics (Note 3)

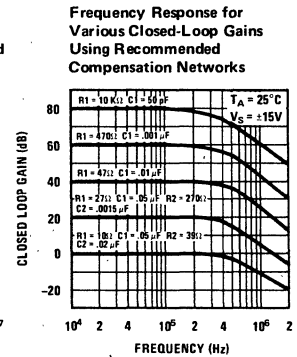
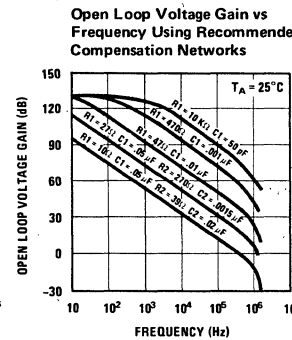
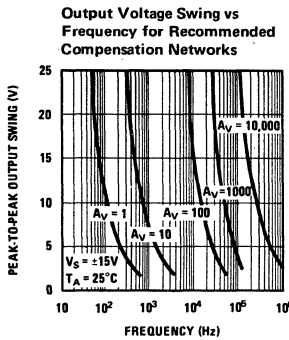
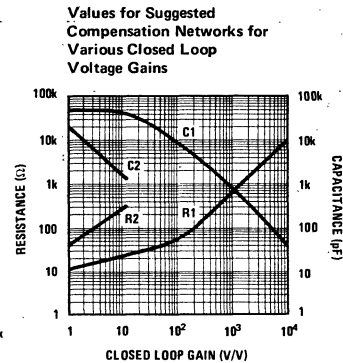
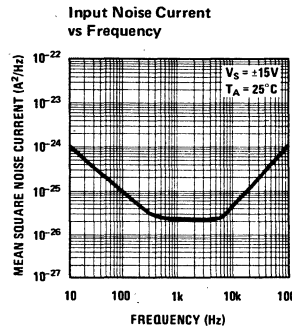
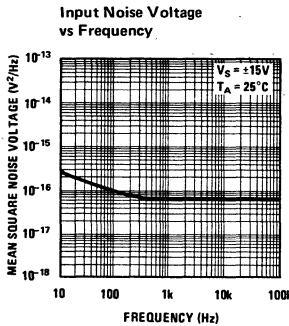
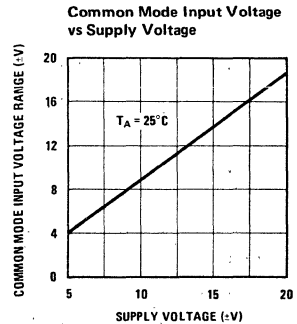
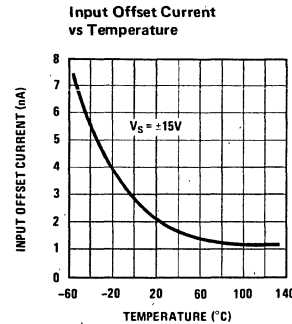
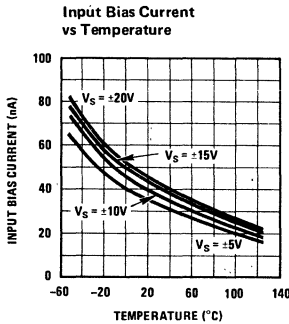
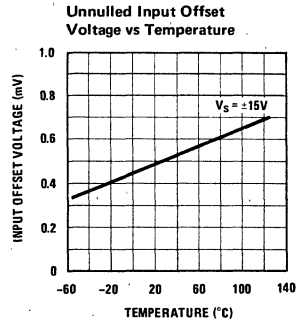
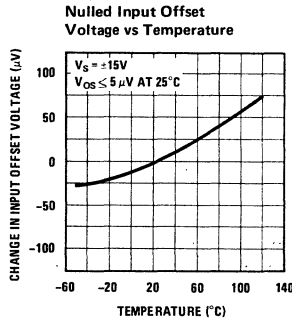
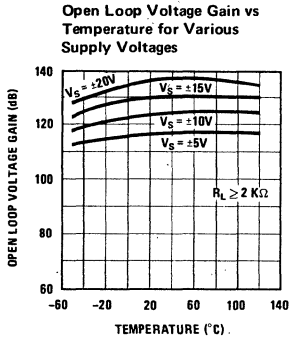
| PARAMETER | CONDITIONS | LM725A | | | LM725 | | | LM725C | | | UNITS |
|--|---|-----------|-------|------|-----------|-------|------|---------|-------|------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage (Without External Trim) | T _A = 25°C, R _S ≤ 10 kΩ | | | 0.5 | | 0.5 | 1.0 | | 0.5 | 2.5 | mV |
| Input Offset Current | T _A = 25°C | | 2.0 | 5.0 | | 2.0 | 20 | | 2.0 | 35 | nA |
| Input Bias Current | T _A = 25°C | | 42 | 80 | | 42 | 100 | | 42 | 125 | nA |
| Input Noise Voltage | T _A = 25°C | | | | | | | | | | |
| | f _o = 10 Hz | | | 15 | | | 15 | | | 15 | nV/√Hz |
| | f _o = 100 Hz | | | 9.0 | | | 9.0 | | | 9.0 | nV/√Hz |
| | f _o = 1 kHz | | | 8.0 | | | 8.0 | | | 8.0 | nV/√Hz |
| Input Noise Current | T _A = 25°C | | | | | | | | | | |
| | f _o = 10 Hz | | | 1.0 | | | 1.0 | | | 1.0 | pA/√Hz |
| | f _o = 100 Hz | | | 0.3 | | | 0.3 | | | 0.3 | pA/√Hz |
| | f _o = 1 kHz | | | 0.15 | | | 0.15 | | | 0.15 | pA/√Hz |
| Input Resistance | T _A = 25°C | | | 1.5 | | | 1.5 | | | 1.5 | MΩ |
| Input Voltage Range | T _A = 25°C | ±13.5 | ±14 | | ±13.5 | ±14 | | ±13.5 | ±14 | | V |
| Large Signal Voltage Gain | T _A = 25°C, R _L ≥ 2 kΩ, V _{OUT} = ±10V | 1000 | 3000 | | 1000 | 3000 | | 250 | 3000 | | V/mV |
| Common-Mode Rejection Ratio | T _A = 25°C, R _S ≤ 10 kΩ | 120 | | | 110 | 120 | | 94 | 120 | | dB |
| Power Supply Rejection Ratio | T _A = 25°C, R _S ≤ 10 kΩ | | 2.0 | 5.0 | | 2.0 | 10 | | 2.0 | 35 | μV/V |
| Output Voltage Swing | T _A = 25°C, R _L ≥ 10 kΩ | ±12.5 | ±13.5 | | ±12 | ±13.5 | | ±12 | ±13.5 | | V |
| | R _L ≥ 2 kΩ | ±12.0 | ±13.5 | | ±10 | ±13.5 | | ±10 | ±13.5 | | V |
| Power Consumption | T _A = 25°C | | 80 | 105 | | 80 | 105 | | 80 | 150 | mW |
| Input Offset Voltage (Without External Trim) | R _S ≤ 10 kΩ | | | 0.7 | | | 1.5 | | | 3.5 | mV |
| Average Input Offset Voltage Drift (Without External Trim) | R _S = 50Ω | | | 2.0 | | 2.0 | 5.0 | | 2.0 | | μV/°C |
| Average Input Offset Voltage Drift (With External Trim) | R _S = 50Ω | | 0.6 | 1.0 | | 0.6 | | | 0.6 | | μV/°C |
| Input Offset Current | T _A = T _{MAX} | | 1.2 | 4.0 | | 1.2 | 20 | | 1.2 | 35 | nA |
| | T _A = T _{MIN} | | 7.5 | 18.0 | | 7.5 | 40 | | 4.0 | 50 | nA |
| Average Input Offset Current Drift | | | 35 | 90 | | 35 | 150 | | 10 | | pA/°C |
| Input Bias Current | T _A = T _{MAX} | | 20 | 70 | | 20 | 100 | | | 125 | nA |
| | T _A = T _{MIN} | | 80 | 180 | | 80 | 200 | | | 250 | nA |
| Large Signal Voltage Gain | R _L ≥ 2 kΩ, T _A = T _{MAX} | 1,000,000 | | | 1,000,000 | | | 125,000 | | | V/V |
| | R _L ≥ 2 kΩ, T _A = T _{MIN} | 500,000 | | | 250,000 | | | 125,000 | | | V/V |
| Common-Mode Rejection Ratio | R _S ≤ 10 kΩ | 110 | | | 100 | | | 115 | | | dB |
| Power Supply Rejection Ratio | R _S ≤ 10 kΩ | | | 8.0 | | | 20 | | 20 | | μV/V |
| Output Voltage Swing | R _L ≥ 2 kΩ | ±12 | | | ±10 | | | ±10 | | | V |

Note 1: Derate at 150°C/W for operation at ambient temperatures above 75°C.

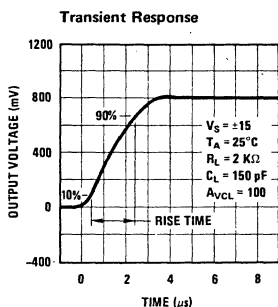
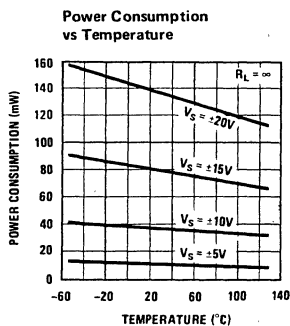
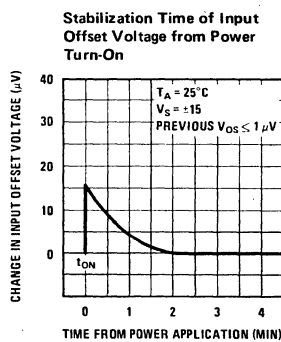
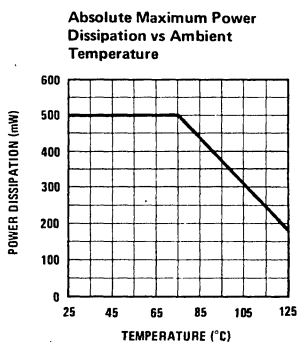
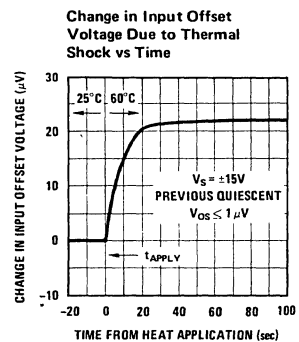
Note 2: For supply voltages less than ±22V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for V_S = ±15V unless otherwise specified.

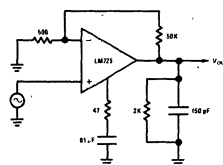
Typical Performance Characteristics



Typical Performance Characteristics (Continued)



Transient Response Test Circuit



LM733/LM733C Differential Video Amp

General Description

The LM733/LM733C is a two-stage, differential input, differential output, wide-band video amplifier. The use of internal series-shunt feedback gives wide bandwidth with low phase distortion and high gain stability. Emitter-follower outputs provide a high current drive, low impedance capability. It's 120 MHz bandwidth and selectable gains of 10, 100, and 400, without need for frequency compensation, make it a very useful circuit for memory element drivers, pulse amplifiers, and wide band linear gain stages.

The LM733 is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LM733C is specified for operation over the 0°C to $+70^{\circ}\text{C}$ temperature range.

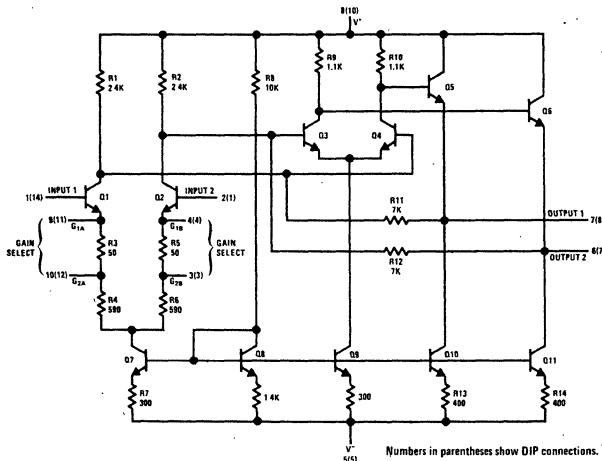
Features

- 120 MHz bandwidth
- 250 k Ω input resistance
- Selectable gains of 10, 100, 400
- No frequency compensation
- High common mode rejection ratio at high frequencies.

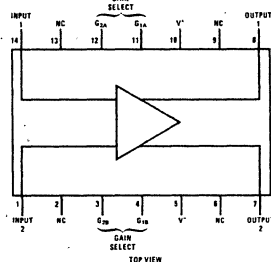
Applications

- Magnetic tape systems
- Disk file memories
- Thin and thick film memories
- Woven and plated wire memories
- Wide band video amplifiers.

Schematic and Connection Diagrams

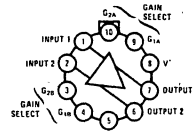


Dual-In-Line Package



Order Number LM733CN
See NS Package N14A

Metal Can Package

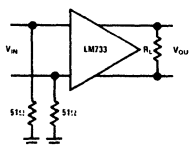


Note: Pin 5 connected to case.

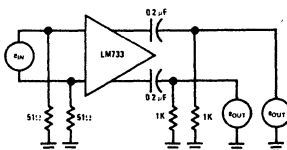
Order Number LM733H or LM733CH
See NS Package H10D

Test Circuits

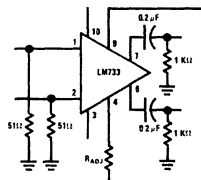
Test Circuit 1



Test Circuit 2



Voltage Gain Adjust Circuit



$V_{CC} = 6\text{V}$, $T_A = 25^{\circ}\text{C}$
(Pin numbers apply to TO-5 package)

Absolute Maximum Ratings

| | |
|--------------------------------------|-----------------|
| Differential Input Voltage | ±5V |
| Common Mode Input Voltage | ±6V |
| V_{CC} | ±8V |
| Output Current | 10 mA |
| Power Dissipation (Note 1) | 500 mW |
| Junction Temperature | +150°C |
| Storage Temperature Range | -65°C to +150°C |
| Operating Temperature Range LM733 | -55°C to +125°C |
| LM733C | 0°C to +70°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics ($T_A = 25^\circ\text{C}$, unless otherwise specified, see test circuits, $V_S = \pm 6.0\text{V}$)

| CHARACTERISTICS | TEST CIRCUIT | TEST CONDITIONS | LM733 | | | LM733C | | | UNITS |
|--------------------------------|--------------|--|-------|------|------|--------|------|------|------------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Differential Voltage Gain | | | | | | | | | |
| Gain 1 (Note 2) | 1 | $R_L = 2\text{ k}\Omega$ $V_{OUT} = 3 V_{PP}$ | 300 | 400 | 500 | 250 | 400 | 600 | |
| Gain 2 (Note 3) | | | 90 | 100 | 110 | 80 | 100 | 120 | |
| Gain 3 (Note 4) | | | 9.0 | 10 | 11 | 8.0 | 10 | 12 | |
| Bandwidth | | | | | | | | | |
| Gain 1 | 2 | | | 40 | | | 40 | | MHz |
| Gain 2 | | | | 90 | | | 90 | | MHz |
| Gain 3 | | | | 120 | | | 120 | | MHz |
| Rise Time | | | | | | | | | |
| Gain 1 | 2 | $V_{OUT} = 1 V_{PP}$ | | 10.5 | | | 10.5 | | ns |
| Gain 2 | | | | 4.5 | 10 | | 4.5 | 12 | ns |
| Gain 3 | | | | 2.5 | | | 2.5 | | ns |
| Propagation Delay | | | | | | | | | |
| Gain 1 | 2 | $V_{OUT} = 1 V_{PP}$ | | 7.5 | | | 7.5 | | ns |
| Gain 2 | | | | 6.0 | 10 | | 6.0 | 10 | ns |
| Gain 3 | | | | 3.6 | | | 3.6 | | ns |
| Input Resistance | | | | | | | | | |
| Gain 1 | | | | 4.0 | | | 4.0 | | k Ω |
| Gain 2 | | | | 20 | 30 | 10 | 30 | | k Ω |
| Gain 3 | | | | | 250 | | | 250 | |
| Input Capacitance | | Gain 2 | | 2.0 | | | 2.0 | | pF |
| Input Offset Current | | | | 0.4 | 3.0 | | 0.4 | 5.0 | μA |
| Input Bias Current | | | | 9.0 | 20 | | 9.0 | 30 | μA |
| Input Noise Voltage | | BW = 1 kHz to 10 MHz | | 12 | | | 12 | | μVrms |
| Input Voltage Range | 1 | | ±1.0 | | | ±1.0 | | | V |
| Common Mode Rejection Ratio | | | | | | | | | |
| Gain 2 | 1 | $V_{CM} = \pm 1\text{V}$ $f \leq 100\text{ kHz}$ | 60 | 86 | | 60 | 86 | | dB |
| Gain 2 | | | | 60 | 60 | | 60 | | dB |
| Supply Voltage Rejection Ratio | | | | | | | | | |
| Gain 2 | 1 | $\Delta V_S = \pm 0.5\text{V}$ | 50 | 70 | | 50 | 70 | | dB |
| Output Offset Voltage | | | | | | | | | |
| Gain 1 | 1 | $R_L = \infty$ | | 0.6 | 1.5 | | 0.6 | 1.5 | V |
| Gain 2 and 3 | | | | | 0.35 | 1.0 | | 0.35 | 1.5 |
| Output Common Mode Voltage | 1 | $R_L = \infty$ | 2.4 | 2.9 | 3.4 | 2.4 | 2.9 | 3.4 | V |
| Output Voltage Swing | 1 | $R_L = 2\text{k}$ | 3.0 | 4.0 | | 3.0 | 4.0 | | V |
| Output Sink Current | | | 2.5 | 3.6 | | 2.5 | 3.6 | | mA |
| Output Resistance | | | | 20 | | | 20 | | Ω |
| Power Supply Current | 1 | $R_L = \infty$ | | 18 | 24 | | 18 | 24 | mA |

Electrical Characteristics (Continued)

(The following specifications apply for $-55^{\circ}\text{C} < T_A < 125^{\circ}\text{C}$ for the LM733 and $0^{\circ}\text{C} < T_A < 70^{\circ}\text{C}$ for the LM733C, $V_S = \pm 6.0\text{V}$)

| CHARACTERISTICS | TEST CIRCUIT | TEST CONDITIONS | LM733 | | | LM733C | | | UNITS |
|--------------------------------|--------------|---|---------|-----|------|---------|-----|------------------|-------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Differential Voltage Gain | | | | | | | | | |
| Gain 1 | | | 200 | | 600 | 250 | | 600 | |
| Gain 2 | 1 | $R_L = 2\text{ k}\Omega, V_{OUT} = 3 V_{PP}$ | 80 | | 120 | 80 | | 120 | |
| Gain 3 | | | 8.0 | | 12.0 | 8.0 | | 12.0 | |
| Input Resistance Gain 2 | | | 8 | | | 8 | | $\text{k}\Omega$ | |
| Input Offset Current | | | | | 5 | | | μA | |
| Input Bias Current | | | | | 40 | | | μA | |
| Input Voltage Range | 1 | | ± 1 | | | ± 1 | | V | |
| Common Mode Rejection Ratio | | | | | | | | | |
| Gain 2 | 1 | $V_{CM} = \pm 1\text{V}, f \leq 100\text{ kHz}$ | 50 | | | 50 | | dB | |
| Supply Voltage Rejection Ratio | | | | | | | | | |
| Gain 2 | 1 | $\Delta V_S = \pm 0.5\text{V}$ | 50 | | | 50 | | dB | |
| Output Offset Voltage | | | | | | | | | |
| Gain 1 | 1 | $R_L = \infty$ | | | 1.5 | | | 1.5 | |
| Gain 2 and 3 | | | | | 1.2 | | | 1.5 | |
| Output Voltage Swing | 1 | $R_L = 2\text{k}$ | 2.5 | | | 2.8 | | V_{PP} | |
| Output Sink Current | | | 2.2 | | | 2.5 | | mA | |
| Power Supply Current | 1 | $R_L = \infty$ | | | 27 | | | 27 | |

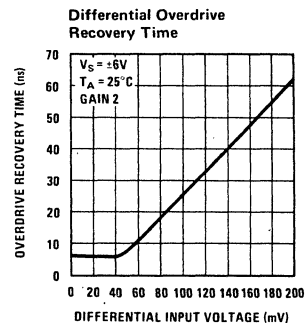
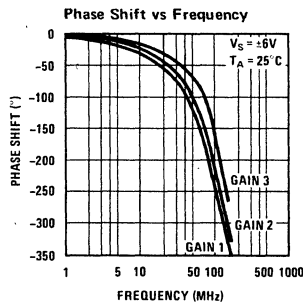
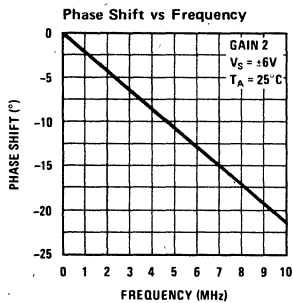
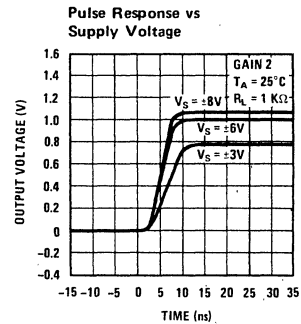
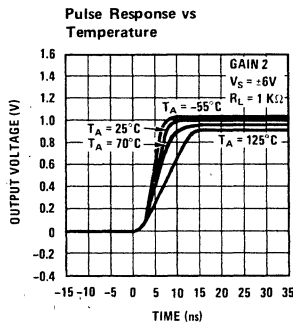
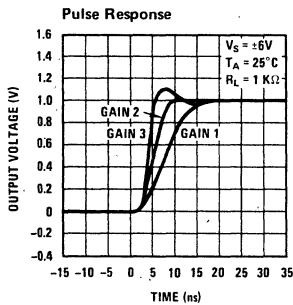
Note 1: The maximum junction temperature of the LM733 is 150°C , while that of the LM733C is 100°C . For operation at elevated temperatures devices in the TO-100 package must be derated based on a thermal resistance of $150^{\circ}\text{C}/\text{W}$ junction to ambient or $45^{\circ}\text{C}/\text{W}$ junction to case. Thermal resistance of the dual-in-line package is $100^{\circ}\text{C}/\text{W}$.

Note 2: Pins G1A and G1B connected together.

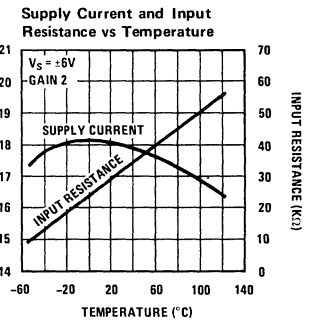
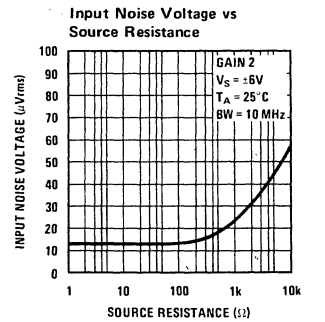
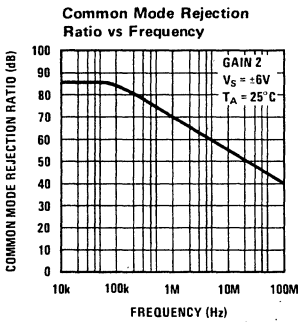
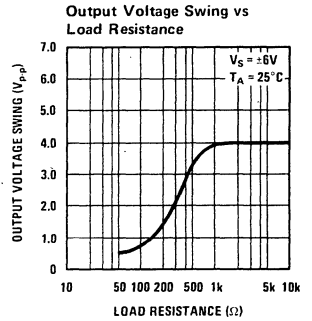
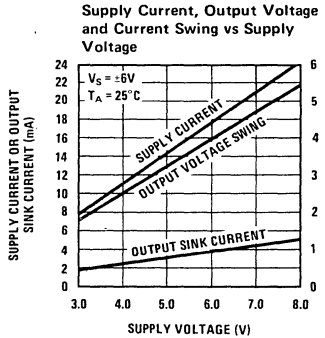
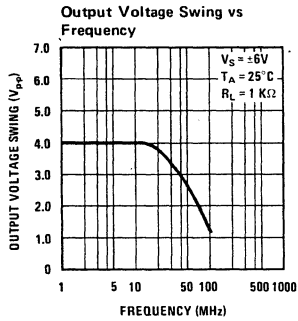
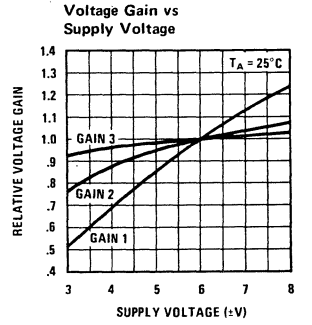
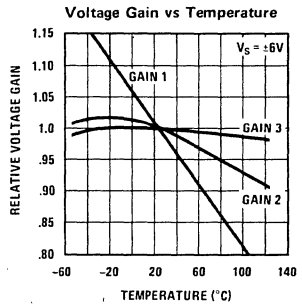
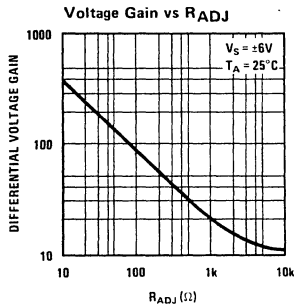
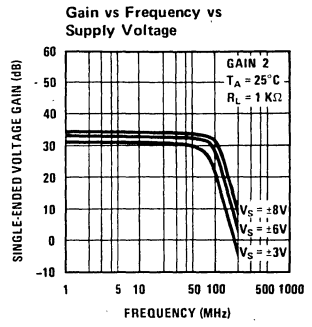
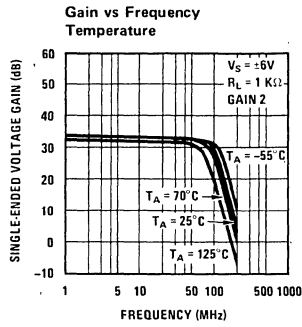
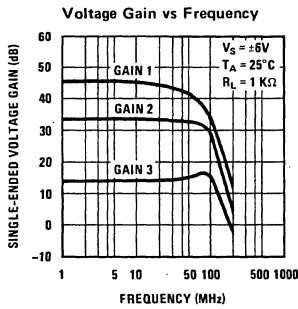
Note 3: Pins G2A and G2B connected together.

Note 4: Gain select pins open.

Typical Performance Characteristics



Typical Performance Characteristics (Continued)





Operational Amplifiers/Buffers

LM741/LM741A/LM741C/LM741E Operational Amplifier

General Description

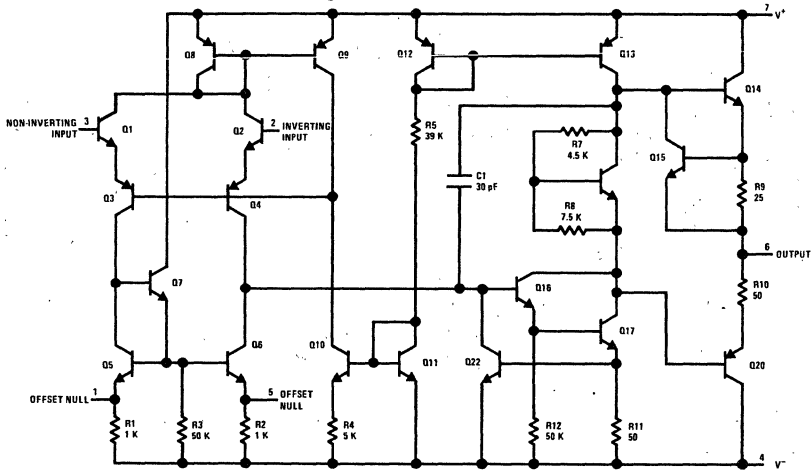
The LM741 series are general purpose operational amplifiers which feature improved performance over industry standards like the LM709. They are direct, plug-in replacements for the 709C, LM201, MC1439 and 748 in most applications.

The amplifiers offer many features which make their application nearly foolproof: overload protection on the input and output, no latch-up when the common mode range is exceeded, as well as freedom from oscillations.

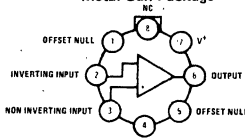
The LM741C/LM741E are identical to the LM741/LM741A except that the LM741C/LM741E have their performance guaranteed over a 0°C to +70°C temperature range, instead of -55°C to +125°C.

The amplifiers offer many features which make their application nearly foolproof: overload protection on the input and output, no latch-up when the common mode range is exceeded, as well as freedom from oscillations.

Schematic and Connection Diagrams (Top Views)



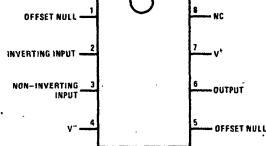
Metal Can Package



Note: Pin 4 connected to case.

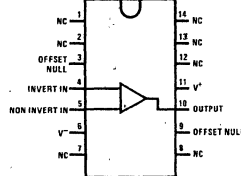
Order Number LM741H, LM741AH,
LM741CH or LM741EH
See NS Package H08C

Dual-In-Line Package



Order Number LM741CN or LM741EN
See NS Package N08B
Order Number LM741CJ
See NS Package J08A

Dual-In-Line Package



Order Number LM741CN-14
See NS Package N14A
Order Number LM741J-14, LM741AJ-14
or LM741CJ-14
See NS Package J14A

Absolute Maximum Ratings

| | LM741A | LM741E | LM741 | LM741C |
|---|-----------------|-----------------|-----------------|-----------------|
| Supply Voltage | ±22V | ±22V | ±22V | ±18V |
| Power Dissipation (Note 1) | 500 mW | 500 mW | 500 mW | 500 mW |
| Differential Input Voltage | ±30V | ±30V | ±30V | ±30V |
| Input Voltage (Note 2) | ±15V | ±15V | ±15V | ±15V |
| Output Short Circuit Duration | Indefinite | Indefinite | Indefinite | Indefinite |
| Operating Temperature Range | -55°C to +125°C | 0°C to +70°C | -55°C to +125°C | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | 300°C | 300°C |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LM741A/LM741E | | | LM741 | | | LM741C | | | UNITS |
|---------------------------------------|---|---------------|-----|-------|-------|-----|-----|--------|-----|-----|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | | | | | | | | | |
| | $R_S \leq 10\text{ k}\Omega$ | | | | 1.0 | 5.0 | | 2.0 | 6.0 | | mV |
| | $R_S \leq 50\Omega$ | | 0.8 | 3.0 | | | | | | | mV |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | | | | | | | | |
| Average Input Offset Voltage Drift | $R_S \leq 50\Omega$ | | | 4.0 | | | | | | | mV |
| | $R_S \leq 10\text{ k}\Omega$ | | | | | 6.0 | | | 7.5 | | mV |
| Average Input Offset Current Drift | | | 15 | | | | | | | | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Voltage Adjustment Range | $T_A = 25^\circ\text{C}, V_S = \pm 20\text{V}$ | ±10 | | | ±15 | | | ±15 | | | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 3.0 | 30 | 20 | 200 | | 20 | 200 | | nA |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | 70 | 85 | 500 | | 300 | | | nA |
| Average Input Offset Current Drift | | | 0.5 | | | | | | | | $\text{nA}/^\circ\text{C}$ |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 30 | 80 | 80 | 500 | | 80 | 500 | | nA |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | 0.210 | | 1.5 | | | 0.8 | | μA |
| Input Resistance | $T_A = 25^\circ\text{C}, V_S = \pm 20\text{V}$ | 1.0 | 6.0 | | 0.3 | 2.0 | | 0.3 | 2.0 | | M Ω |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}, V_S = \pm 20\text{V}$ | 0.5 | | | | | | | | | M Ω |
| Input Voltage Range | $T_A = 25^\circ\text{C}$ | | | | | | | ±12 | ±13 | | V |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | | ±12 | ±13 | | | | | V |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, R_L \geq 2\text{ k}\Omega$ | | | | | | | | | | |
| | $V_S = \pm 20\text{V}, V_O = \pm 15\text{V}$ | 50 | | | | | | | | | V/mV |
| | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ | | | | 50 | 200 | | 20 | 200 | | V/mV |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}, R_L \geq 2\text{ k}\Omega,$ | | | | | | | | | | |
| Output Voltage Swing | $V_S = \pm 20\text{V}, V_O = \pm 15\text{V}$ | 32 | | | | | | | | | V/mV |
| | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ | | | | 25 | | | 15 | | | V/mV |
| | $V_S = \pm 5\text{V}, V_O = \pm 2\text{V}$ | 10 | | | | | | | | | V/mV |
| | $V_S = \pm 20\text{V}, R_L \geq 10\text{ k}\Omega$ | ±16 | | | | | | | | | V |
| Output Short Circuit Current | $R_L \geq 2\text{ k}\Omega$ | ±15 | | | | | | | | | V |
| | $V_S = \pm 15\text{V}, R_L \geq 10\text{ k}\Omega$ | | | | ±12 | ±14 | | ±12 | ±14 | | V |
| | $R_L \geq 2\text{ k}\Omega$ | | | | ±10 | ±13 | | ±10 | ±13 | | V |
| | $T_A = 25^\circ\text{C}$ | 10 | 25 | 35 | 25 | | | 25 | | | mA |
| Common-Mode Rejection Ratio | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | 10 | | 40 | | | | | | | dB |
| Common-Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega, V_{CM} = \pm 12\text{V}$ | | | | 70 | 90 | | 70 | 90 | | dB |
| | $R_S \leq 50\text{ k}\Omega, V_{CM} = \pm 12\text{V}$ | 80 | 95 | | | | | | | | dB |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM741A/LM741E | | | LM741 | | | LM741C | | | UNITS |
|--------------------------------|---|---------------|------|-----|-------|-----|-----|--------|-----|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage Rejection Ratio | $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$ $V_S = \pm 20\text{V}$ to $V_S = \pm 5\text{V}$ $R_S \leq 50\Omega$ $R_S \leq 10\text{ k}\Omega$ | 86 | 96 | | 77 | 96 | | 77 | 96 | | dB |
| | | | | | | | | | | | dB |
| Transient Response | $T_A = 25^\circ\text{C}$, Unity Gain | | | | | | | | | | |
| | | | | | | | | | | | |
| Rise Time | | | 0.25 | 0.8 | | 0.3 | | | 0.3 | | μs |
| Overshoot | | | 6.0 | 20 | | 5 | | 5 | | | % |
| Bandwidth (Note 4) | $T_A = 25^\circ\text{C}$ | 0.437 | 1.5 | | | | | | | | MHz |
| Slew Rate | $T_A = 25^\circ\text{C}$, Unity Gain | 0.3 | 0.7 | | | 0.5 | | | 0.5 | | V/ μs |
| Supply Current | $T_A = 25^\circ\text{C}$ | | | | | 1.7 | 2.8 | | 1.7 | 2.8 | mA |
| Power Consumption | $T_A = 25^\circ\text{C}$ $V_S = \pm 20\text{V}$ $V_S = \pm 15\text{V}$ $V_S = \pm 20\text{V}$ | | 80 | 150 | | 50 | 85 | | 50 | 85 | mW |
| | | | | | | | | | | | mW |
| LM741A | $T_A = T_{A\text{MIN}}$ | | | 165 | | | | | | | mW |
| | $T_A = T_{A\text{MAX}}$ | | | 135 | | | | | | | mW |
| LM741E | $V_S = \pm 20\text{V}$ | | | 150 | | | | | | | mW |
| | $T_A = T_{A\text{MIN}}$ | | | 150 | | | | | | | mW |
| | $T_A = T_{A\text{MAX}}$ | | | 150 | | | | | | | mW |
| LM741 | $V_S = \pm 15\text{V}$ | | | | | | | | | | |
| | $T_A = T_{A\text{MIN}}$ | | | | 60 | 100 | | | | | mW |
| | $T_A = T_{A\text{MAX}}$ | | | | 45 | 75 | | | | | mW |

Note 1: The maximum junction temperature of the LM741/LM741A is 150°C , while that of the LM741C/LM741E is 100°C . For operation at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of $150^\circ\text{C}/\text{W}$ junction to ambient, or $45^\circ\text{C}/\text{W}$ junction to case. The thermal resistance of the dual-in-line package is $100^\circ\text{C}/\text{W}$ junction to ambient.

Note 2: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.

Note 3: Unless otherwise specified, these specifications apply for $V_S = \pm 15\text{V}$, $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ (LM741/LM741A). For the LM741C/LM741E, these specifications are limited to $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$.

Note 4: Calculated value from: $\text{BW (MHz)} = 0.35/\text{Rise Time}(\mu\text{s})$.

LM747/LM747A/LM747C/LM747E Dual Operational Amplifiers

General Description

The LM747 series are general purpose dual operational amplifiers. The two amplifiers share a common bias network and power supply leads. Otherwise, their operation is completely independent.

- Low-power consumption
- No latch-up
- Balanced offset null

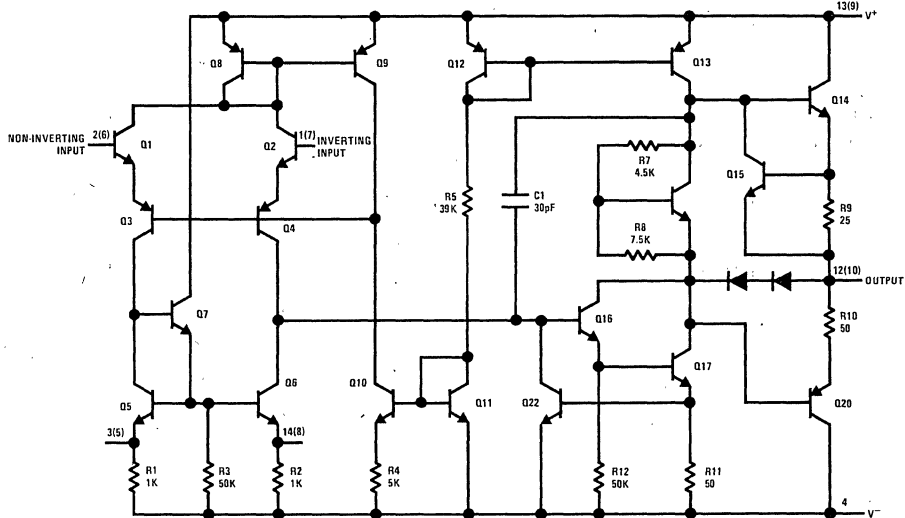
Additional features of the LM747 and LM747C are: no latch-up when input common mode range is exceeded, freedom from oscillations, and package flexibility.

Features

- No frequency compensation required
- Short-circuit protection
- Wide common-mode and differential voltage ranges

The LM747C/LM747E is identical to the LM747/LM747A except that the LM747C/LM747E has its specifications guaranteed over the temperature range from 0°C to +70°C instead of -55°C to +125°C.

Schematic Diagram (each amplifier)



Note: Numbers in parentheses are pin numbers for amplifier B, DIP only.

Absolute Maximum Ratings

| | | |
|--|---------------|-----------------|
| Supply Voltage | LM747/LM747A | ±22V |
| | LM747C/LM747E | ±18V |
| Power Dissipation (Note 1) | | 800 mW |
| Differential Input Voltage | | ±30V |
| Input Voltage (Note 2) | | ±15V |
| Output Short-Circuit Duration | | Indefinite |
| Operating Temperature Range | | |
| | LM747/LM747A | -55°C to +125°C |
| | LM747C/LM747E | 0°C to +70°C |
| Storage Temperature Range | | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | | 300°C |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LM747A/LM747E | | | LM747 | | | LM747C | | | UNITS |
|---------------------------------------|--|---------------|-----|-------|-------|-----|-----|--------|-----|-----|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | | | | | | | | | | |
| | $R_S \leq 10\text{ k}\Omega$ | | | | | 1.0 | 5.0 | | 2.0 | 6.0 | mV |
| | $R_S \leq 50\Omega$ | | 0.8 | 3.0 | | | | | | | mV |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | 4.0 | | | | | | | mV |
| Average Input Offset Voltage Drift | $R_S \leq 50\Omega$ | | | | | | 6.0 | | | 7.5 | mV |
| | $R_S \leq 10\text{ k}\Omega$ | | | 15 | | | | | | | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Voltage Adjustment Range | $T_A = 25^\circ\text{C}, V_S = \pm 20\text{V}$ | ±10 | | | | ±15 | | | ±15 | | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 3.0 | 30 | | 20 | 200 | | 20 | 200 | nA |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | 70 | | 85 | 500 | | | 300 | nA |
| Average Input Offset Current Drift | | | | 0.5 | | | | | | | $\text{nA}/^\circ\text{C}$ |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 30 | 80 | | 80 | 500 | | 80 | 500 | nA |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | 0.210 | | | 1.5 | | | 0.8 | μA |
| Input Resistance | $T_A = 25^\circ\text{C}, V_S = \pm 20\text{V}$ | 1.0 | 6.0 | | 0.3 | 2.0 | | 0.3 | 2.0 | | $\text{M}\Omega$ |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}, V_S = \pm 20\text{V}$ | 0.5 | | | | | | | | | $\text{M}\Omega$ |
| Input Voltage Range | $T_A = 25^\circ\text{C}$ | | | | | | | ±12 | ±13 | | V |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | | ±12 | ±13 | | | | | V |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, R_L \geq 2\text{ k}\Omega$ | | | | | | | | | | V/mV |
| | $V_S = \pm 20\text{V}, V_O = \pm 15\text{V}$ | 50 | | | | | | | | | V/mV |
| | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ | | | | 50 | 200 | | 20 | 200 | | |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}, R_L \geq 2\text{ k}\Omega$ | | | | | | | | | | V/mV |
| Output Voltage Swing | $V_S = \pm 20\text{V}, V_O = \pm 15\text{V}$ | | | | | | | | | | V/mV |
| | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ | | | | 25 | | | 15 | | | V/mV |
| | $V_S = \pm 5\text{V}, V_O = \pm 2\text{V}$ | | | | 10 | | | | | | V/mV |
| | $V_S = \pm 20\text{V}, R_L \geq 10\text{ k}\Omega$ | ±16 | | | | | | | | | V |
| Output Short Circuit Current | $R_L \geq 2\text{ k}\Omega$ | ±15 | | | | | | | | | V |
| | $V_S = \pm 15\text{V}$ | | | | | | | | | | V |
| | $R_L \geq 10\text{ k}\Omega$ | | | | ±12 | ±14 | | ±12 | ±14 | | V |
| | $R_L \geq 2\text{ k}\Omega$ | | | | ±10 | ±13 | | ±10 | ±13 | | V |
| Common-Mode Rejection Ratio | $T_A = 25^\circ\text{C}$ | 10 | 25 | 35 | | 25 | | | 25 | | dB |
| | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | 10 | | 40 | | | | | | | dB |
| Common-Mode Rejection Ratio | $T_{AMIN} \leq T_A \leq T_{AMAX}$ | | | | | | | | | | dB |
| | $R_S \leq 10\text{ k}\Omega, V_{CM} = \pm 12\text{V}$ | | | | 70 | 90 | | 70 | 90 | | dB |
| Common-Mode Rejection Ratio | $R_S \leq 50\text{ k}\Omega, V_{CM} = \pm 12\text{V}$ | | | | 80 | 95 | | | | | dB |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM747A/LM747E | | | LM747 | | | LM747C | | | UNITS |
|--------------------------------|---|---------------|------|-----|-------|-----|-----|--------|-----|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage Rejection Ratio | $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$ $V_S = \pm 20\text{V}$ to $V_S = \pm 5\text{V}$ $R_S \leq 50\Omega$ $R_L \leq 10\text{ k}\Omega$ | 86 | 96 | | 77 | 96 | | 77 | 96 | | dB |
| | | | | | | | | | | | |
| Transient Response | $T_A = 25^\circ\text{C}$, Unity Gain | | | | | | | | | | |
| Rise Time | | | 0.25 | 0.8 | | 0.3 | | | 0.3 | | μs |
| Overshoot | | | 6.0 | 20 | | 5 | | | 5 | | % |
| Bandwidth (Note 4) | $T_A = 25^\circ\text{C}$ | 0.437 | 1.5 | | | | | | | | MHz |
| Slew Rate | $T_A = 25^\circ\text{C}$, Unity Gain | 0.3 | 0.7 | | | 0.5 | | | 0.5 | | V/ μs |
| Supply Current | $T_A = 25^\circ\text{C}$ | | | | | 1.7 | 2.8 | | 1.7 | 2.8 | mA |
| Power Consumption | $T_A = 25^\circ\text{C}$ | | | | | | | | | | |
| | $V_S = \pm 20\text{V}$ | | 80 | 150 | | | | | | | mW |
| LM747A | $V_S = \pm 15\text{V}$ | | | | 50 | 85 | | 50 | 85 | | mW |
| | $V_S = \pm 20\text{V}$ | | | | | | | | | | mW |
| LM747E | $T_A = T_{A\text{MIN}}$ | | | 165 | | | | | | | mW |
| | $T_A = T_{A\text{MAX}}$ | | | 135 | | | | | | | mW |
| LM747 | $V_S = \pm 20\text{V}$ | | | 150 | | | | | | | mW |
| | $T_A = T_{A\text{MIN}}$ | | | 150 | | | | | | | mW |
| LM747 | $T_A = T_{A\text{MAX}}$ | | | 150 | | | | | | | mW |
| | $V_S = \pm 15\text{V}$ | | | | | | | | | | mW |
| LM747 | $T_A = T_{A\text{MIN}}$ | | | | 60 | 100 | | | | | mW |
| | $T_A = T_{A\text{MAX}}$ | | | | 45 | 75 | | | | | mW |

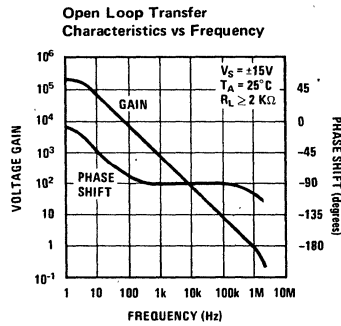
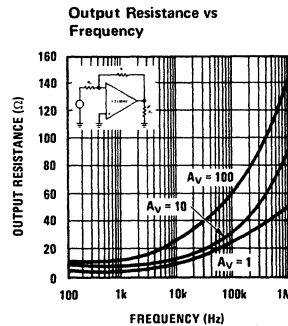
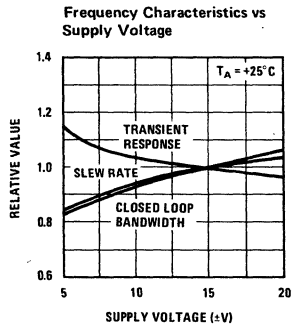
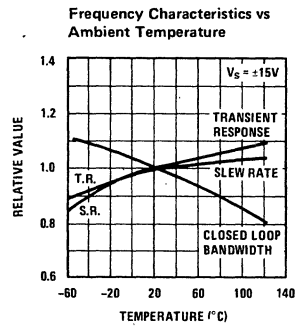
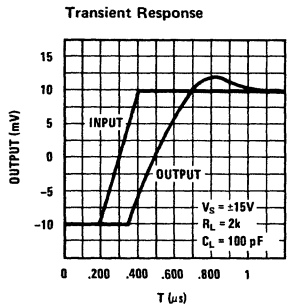
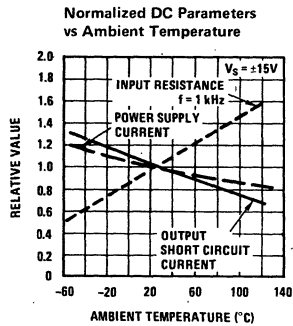
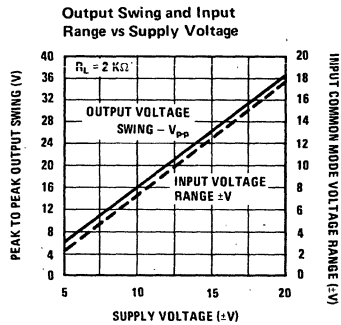
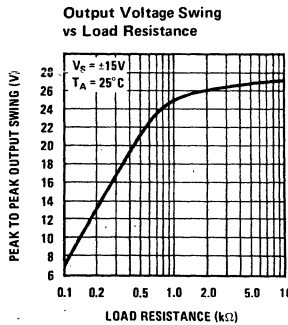
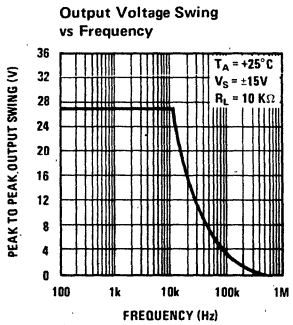
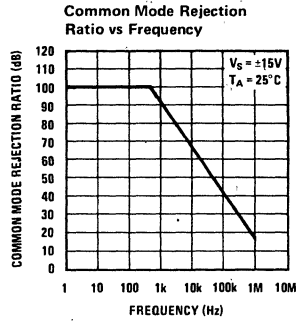
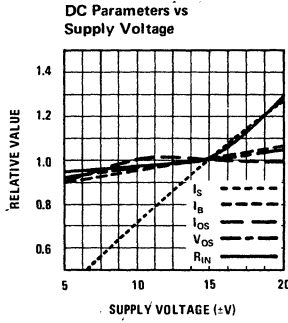
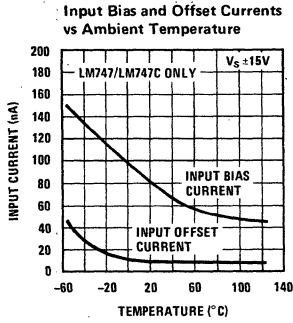
Note 1: The maximum junction temperature of the LM747/LM747A is 150°C , while that of the LM747C/LM747E is 100°C . For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W , junction to ambient, or 45°C/W , junction to case. The thermal resistance of the dual-in-line package is 100°C/W , junction to ambient.

Note 2: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ for the LM747A and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ for the LM747E unless otherwise specified. The LM741 and LM741C are specified for $V_S = \pm 15\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$, respectively, unless otherwise specified.

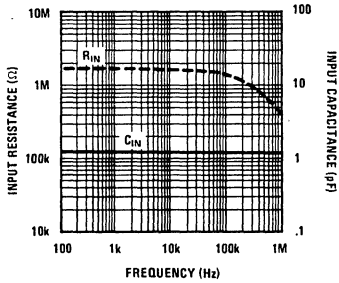
Note 4: Calculated value from: $0.35/\text{Rise Time}$ (μs).

Typical Performance Characteristics

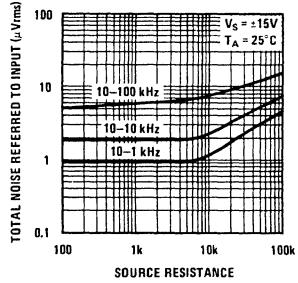


Typical Performance Characteristics (Continued)

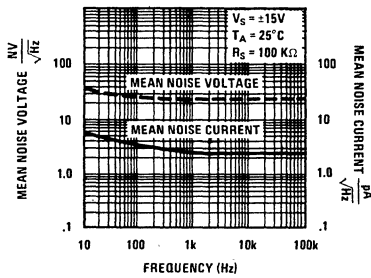
Input Resistance and Input Capacitance vs Frequency



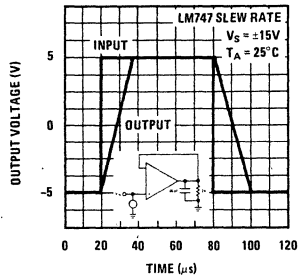
Broadband Noise for Various Bandwidths



Input Noise Voltage and Current vs Frequency

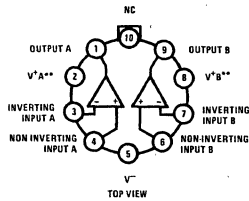


Voltage Follower Large Signal Pulse Response



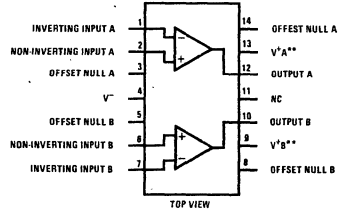
Connection Diagrams

Metal Can Package



Order Number LM747AH, LM747H, LM747EH or LM747CH
See NS Package H10C

Dual-In-Line Package



Order Number LM747AJ, LM747J, LM747EJ or LM747CJ
See NS Package J14A
Order Number LM747EN or LM747CN
See NS Package N14A

** V^+A and V^+B are internally connected for LM747AJ, LM747CJ etc.

LM748/LM748C Operational Amplifier

General Description

The LM748/LM748C is a general purpose operational amplifier built on a single silicon chip. The resulting close match and tight thermal coupling gives low offsets and temperature drift as well as fast recovery from thermal transients. In addition, the device features:

- Frequency compensation with a single 30 pF capacitor
- Operation from $\pm 5V$ to $\pm 20V$
- Low current drain: 1.8 mA at $\pm 20V$.
- Continuous short-circuit protection
- Operation as a comparator with differential inputs as high as $\pm 30V$

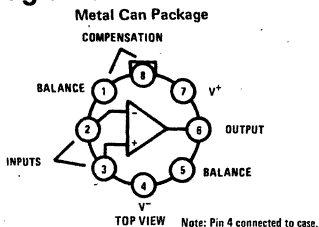
- No latch-up when common mode range is exceeded.

- Same pin configuration as the LM101.

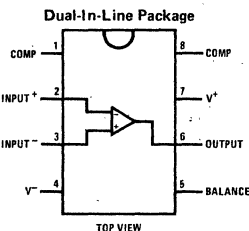
The unity-gain compensation specified makes the circuit stable for all feedback configurations, even with capacitive loads. However, it is possible to optimize compensation for best high frequency performance at any gain. As a comparator, the output can be clamped at any desired level to make it compatible with logic circuits.

The LM748 is specified for operation over the $-55^{\circ}C$ to $+125^{\circ}C$ military temperature range. The LM748C is specified for operation over the $0^{\circ}C$ to $+70^{\circ}C$ temperature range.

Connection Diagrams



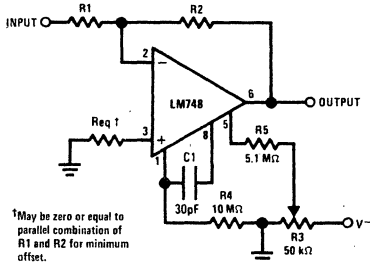
Order Number LM748H or LM748CH
See NS Package H08C



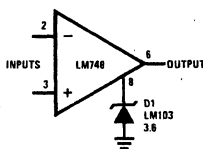
Order Number LM748CN
See NS Package N08B
Order Number LM748J or LM748CJ
See NS Package J08A

Typical Applications

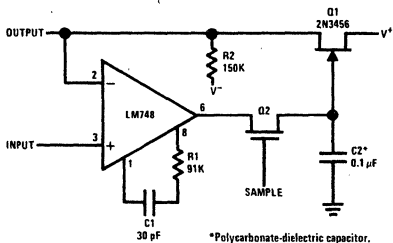
Inverting Amplifier with Balancing Circuit



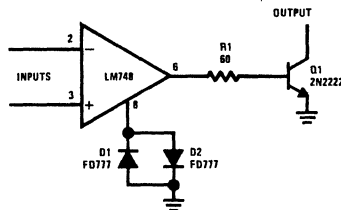
Voltage Comparator for Driving DTL or TTL Integrated Circuits



Low Drift Sample and Hold



Voltage Comparator for Driving RTL Logic or High Current Driver



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±22V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Voltage | ±30V |
| Input Voltage (Note 2) | ±15V |
| Output Short-Circuit Duration (Note 3) | Indefinite |
| Operating Temperature Range: LM748 | -55°C to +125°C |
| LM748C | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 4)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|----------------------|----------------------|-------------|--------------------------------|
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $R_S \leq 10\text{ k}\Omega$ | | 1.0 | 5.0 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 40 | 200 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 120 | 500 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 300 | 800 | | k Ω |
| Supply Current | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 1.8 | 2.8 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L \geq 2\text{ k}\Omega$ | 50 | 160 | | V/mV |
| Input Offset Voltage | $R_S \leq 10\text{ k}\Omega$ | | | 6.0 | mV |
| Average Temperature Coefficient of Input Offset Voltage | $R_S \leq 50\Omega$ | | 3.0 | | $\mu\text{V}/^\circ\text{C}$ |
| | $R_S \leq 10\text{ k}\Omega$ | | 6.0 | | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | $T_A = 0^\circ\text{C}$ to 70°C $T_A = -55^\circ\text{C}$ to 125°C | | | 300 500 | nA nA |
| Input Bias Current | $T_A = 0^\circ\text{C}$ to 70°C $T_A = -55^\circ\text{C}$ to 125°C | | | 0.8 1.5 | μA μA |
| Supply Current | $T_A = +125^\circ\text{C}$, $V_S = \pm 15\text{V}$ $T_A = -55^\circ\text{C}$ to 125°C | | 1.2 1.9 | 2.25 3.3 | mA mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$ $R_L \geq 2\text{ k}\Omega$ | 25 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\Omega$ $R_L = 2\text{ k}\Omega$ | ± 12 ± 10 | ± 14 ± 13 | | V V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ± 12 | | | V |
| Common Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | 70 | 90 | | dB |
| Supply Voltage Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | 77 | 90 | | dB |

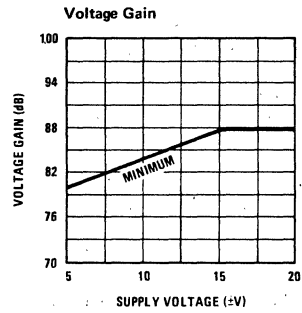
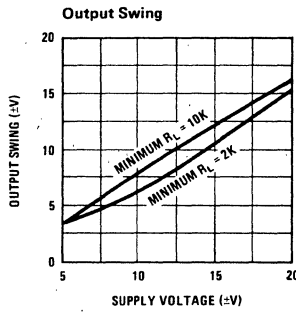
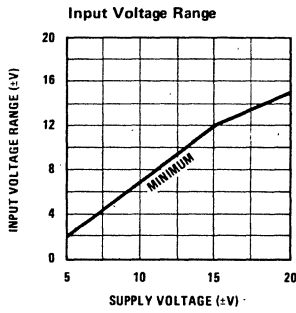
Note 1: For operating at elevated temperatures the devices must be derated based on a maximum junction to case thermal resistance of 45°C per watt, or 150°C per watt junction to ambient. (See Curves).

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

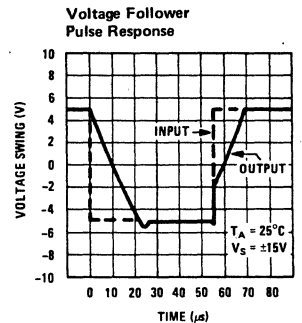
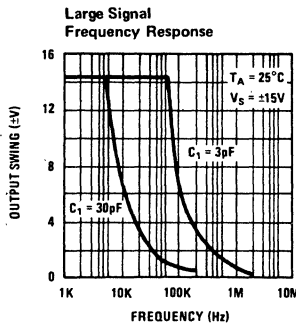
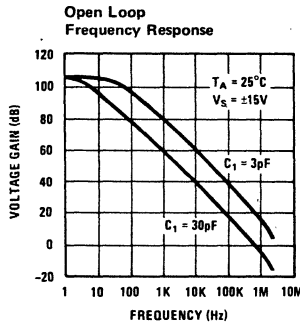
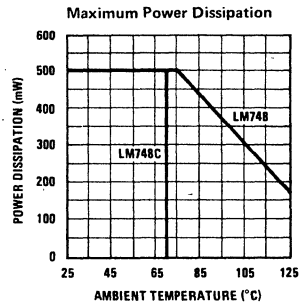
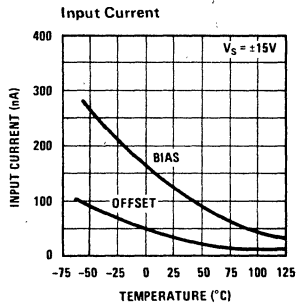
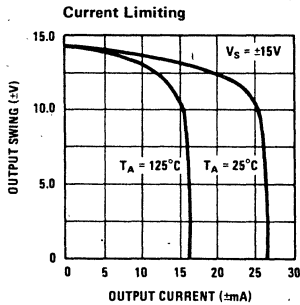
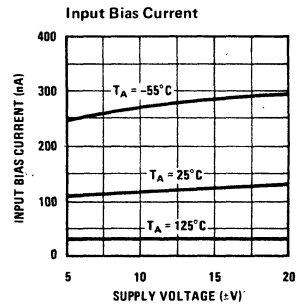
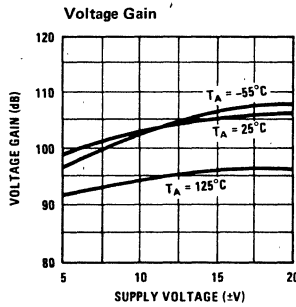
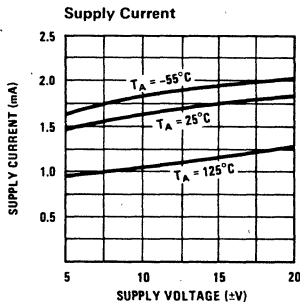
Note 3: Continuous short circuit is allowed for case temperatures to +125°C and ambient temperatures to +70°C.

Note 4: These specifications apply for $+5\text{V} \leq V_S \leq +15\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LM748C, however, all temperature specifications are limited to $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$.

Guaranteed Performance Characteristics (Note 4)



Typical Performance Characteristics



LM1558/LM1458 Dual Operational Amplifier

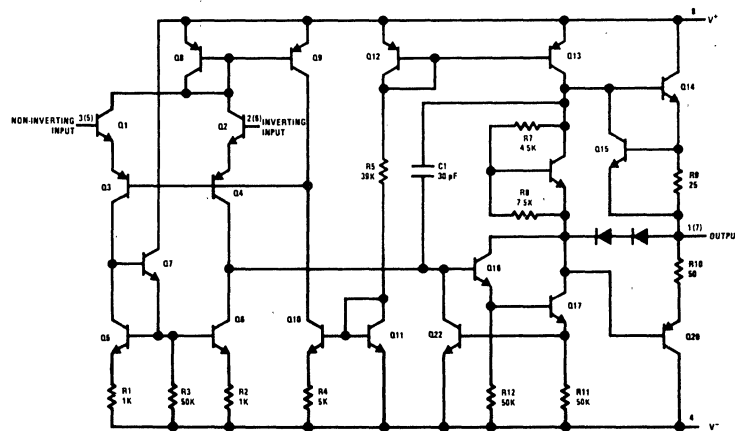
General Description

The LM1558 and the LM1458 are general purpose dual operational amplifiers. The two amplifiers share a common bias network and power supply leads. Otherwise, their operation is completely independent. Features include:

- No frequency compensation required
- Short-circuit protection
- Wide common-mode and differential voltage ranges
- Low-power consumption
- 8-lead TO-5 and 8-lead mini DIP
- No latch up when input common mode range is exceeded

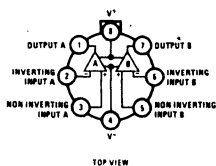
The LM1458 is identical to the LM1558 except that the LM1458 has its specifications guaranteed over the temperature range from 0°C to 70°C instead of -55°C to +125°C.

Schematic and Connection Diagrams



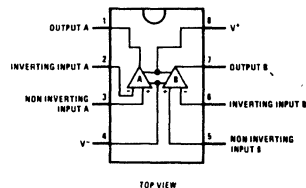
Note: Numbers in parentheses are pin numbers for amplifier B.

Metal Can Package



Order Number **LM1558H**
or **LM1458H**
See NS Package H08C

Dual-In-Line Package



Order Number **LM1558J** or **LM1458J**
See NS Package J08A

Order Number **LM1458N**
See NS Package N08B

Absolute Maximum Ratings

| | | | |
|--|--------|--------------------------------------|----------------|
| Supply Voltage LM1558 | ±22V | Output Short-Circuit Duration | Indefinite |
| LM1458 | ±18V | Operating Temperature Range LM1558 | -55°C to 125°C |
| Power Dissipation (Note 1) LM1558H/LM1458H | 500 mW | LM1458 | 0°C to 70°C |
| LM1458N | 400 mW | Storage Temperature Range | -65°C to 150°C |
| Differential Input Voltage | ±30V | Lead Temperature (Soldering, 10 sec) | 300°C |
| Input Voltage (Note 2) | ±15V | | |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LM1558 | | | LM1458 | | | UNITS |
|--------------------------------|--|------------|------------|-----|------------|------------|-----|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $R_S \leq 10\text{ k}\Omega$ | | 1.0 | 5.0 | | 1.0 | 6.0 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 80 | 200 | | 80 | 200 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 200 | 500 | | 200 | 500 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 0.3 | 1.0 | | 0.3 | 1.0 | | M Ω |
| Supply Current Both Amplifiers | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 3.0 | 5.0 | | 3.0 | 5.6 | mA |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{\text{OUT}} = \pm 10\text{V}$, $R_L \geq 2\text{ k}\Omega$ | 50 | 160 | | 20 | 160 | | V/mV |
| Input Offset Voltage | $R_S \leq 10\text{ k}\Omega$ | | | 6.0 | | | 7.5 | mV |
| Input Offset Current | | | | 500 | | | 300 | nA |
| Input Bias Current | | | | 1.5 | | | 0.8 | μA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{\text{OUT}} = \pm 10\text{V}$ $R_L \geq 2\text{ k}\Omega$ | 25 | | | 15 | | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ $R_L = 2\text{ k}\Omega$ | ±12 ±10 | ±14 ±13 | | ±12 ±10 | ±14 ±13 | | V V |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±12 | | | ±12 | | | V |
| Common Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | 70 | 90 | | 70 | 90 | | dB |
| Supply Voltage Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | 77 | 96 | | 77 | 96 | | dB |

Note 1: The maximum junction temperature of the LM1558 is 150°C, while that of the LM1458 is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient or 45°C/W, junction to case. For the DIP the device must be derated based on a thermal resistance of 187°C/W, junction to ambient.

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LM1458, however, all specifications are limited to $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ and $V_S = \pm 15\text{V}$.

LM2900/LM3900, LM3301, LM3401 Quad Amplifiers

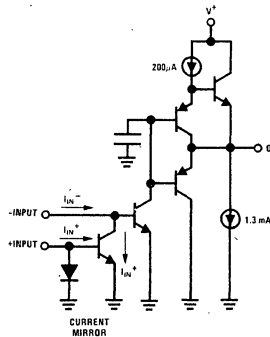
General Description

The LM2900 series consists of four independent, dual input, internally compensated amplifiers which were designed specifically to operate off of a single power supply voltage and to provide a large output voltage swing. These amplifiers make use of a current mirror to achieve the non-inverting input function. Application areas include: ac amplifiers, RC active filters, low frequency triangle, squarewave and pulse waveform generation circuits, tachometers and low speed, high voltage digital logic gates.

Features

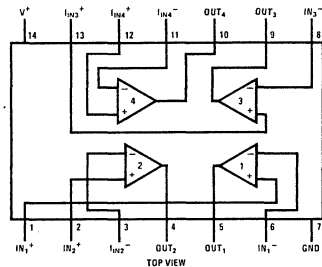
- Wide single supply voltage range or dual supplies $4 V_{DC}$ to $36 V_{DC}$
 $\pm 2 V_{DC}$ to $\pm 18 V_{DC}$
- Supply current drain independent of supply voltage
- Low input biasing current 30 nA
- High open-loop gain 70 dB
- Wide bandwidth 2.5 MHz (Unity Gain)
- Large output voltage swing $(V^+ - 1) V_{p-p}$
- Internally frequency compensated for unity gain
- Output short-circuit protection

Schematic and Connection Diagrams

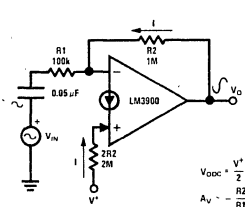


Order Number LM2900J
See NS Package J14A
Order Number LM2900N,
LM3900N, LM3301N
or LM3401N
See NS Package N14A

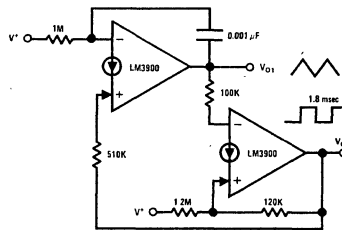
Dual-In-Line and Flat Package



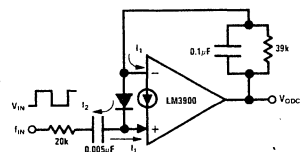
Typical Applications ($V^+ = 15 V_{DC}$)



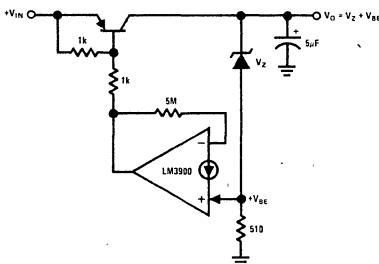
Inverting Amplifier



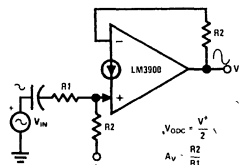
Triangle/Square Generator



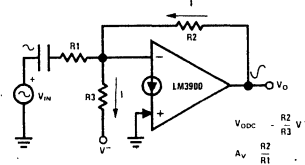
Frequency-Doubling Tachometer



Low $V_{IN} - V_{OUT}$ Voltage Regulator



Non-Inverting Amplifier



Negative Supply Biasing

Absolute Maximum Ratings

| | LM2900/LM3900 | LM3301 | LM3401 |
|--|---------------------|---------------------|---------------------|
| Supply Voltage | 32 VDC ±16 VDC | 28 VDC ±14 VDC | 18 VDC ±9 VDC |
| Power Dissipation (T _A = 25°C) (Note 1) | | | |
| Cavity DIP | 900 mW | | |
| Flat Pack | 800 mW | | |
| Molded DIP | 570 mW | 570 mW | 570 mW |
| Input Currents, I _{IN} ⁺ or I _{IN} ⁻ | 20 mA _{DC} | 20 mA _{DC} | 20 mA _{DC} |
| Output Short-Circuit Duration – One Amplifier | Continuous | Continuous | Continuous |
| T _A = 25°C (See Application Hints) | | | |
| Operating Temperature Range | | -40°C to +85°C | 0°C to +75°C |
| LM2900 | -40°C to +85°C | | |
| LM3900 | 0°C to +70°C | | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C | 300°C |

Electrical Characteristics (Note 6)

| PARAMETER | CONDITIONS | LM2900 | | | LM3900 | | | LM3301 | | | LM3401 | | | UNITS |
|---------------------------|---|--------|------|-----|--------|------|-----|--------|------|-----|--------|------|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Open Loop | | | | | | | | | | | | | | |
| Voltage Gain | | | | | | | | | | | | | | V/mV |
| Voltage Gain | T _A = 25°C, f = 100 Hz | 1.2 | 2.8 | | 1.2 | 2.8 | | 1.2 | 2.8 | | 1.2 | 2.8 | | V/mV |
| Input Resistance | T _A = 25°C, Inverting Input | | 1 | | | 1 | | | 1 | | 0.1 | 1 | | MΩ |
| Output Resistance | | | 8 | | | 8 | | | 8 | | | 8 | | kΩ |
| Unity Gain Bandwidth | T _A = 25°C, Inverting Input | | 2.5 | | | 2.5 | | | 2.5 | | | 2.5 | | MHz |
| Input Bias Current | T _A = 25°C, Inverting Input Inverting Input | | 30 | 200 | | 30 | 200 | | 30 | 300 | | 30 | 300 | nA nA |
| Slew Rate | T _A = 25°C, Positive Output Swing T _A = 25°C, Negative Output Swing | | 0.5 | | | 0.5 | | | 0.5 | | | 0.5 | | V/μs V/μs |
| Supply Current | T _A = 25°C, R _L = ∞ On All Amplifiers | | 6.2 | 10 | | 6.2 | 10 | | 6.2 | 10 | | 6.2 | 10 | mA _{DC} |
| Output Voltage Swing | T _A = 25°C, R _L = 2k, V _{CC} = 15.0 VDC | | | | | | | | | | | | | |
| V _{OUT} High | I _{IN} ⁻ = 0, I _{IN} ⁺ = 0 | | 13.5 | | | 13.5 | | | 13.5 | | | 13.5 | | VDC |
| V _{OUT} Low | I _{IN} ⁻ = 10μA, I _{IN} ⁺ = 0 | | 0.09 | 0.2 | | 0.09 | 0.2 | | 0.09 | 0.2 | | 0.09 | 0.2 | VDC |
| V _{OUT} High | I _{IN} ⁻ = 0, I _{IN} ⁺ = 0 R _L = ∞, V _{CC} = 30 VDC | | 29.5 | | | 29.5 | | | 29.5 | | | 29.5 | | VDC |
| Output Current Capability | T _A = 25°C | | | | | | | | | | | | | |
| Source | | | 6 | 18 | | 6 | 10 | | 5 | 18 | | 5 | 10 | mA _{DC} |
| Sink | (Note 2) | | 0.5 | 1.3 | | 0.5 | 1.3 | | 0.5 | 1.3 | | 0.5 | 1.3 | mA _{DC} |
| I _{SINK} | V _{OL} = 1V, I _{IN} = 5μA | | 5 | | | 5 | | | 5 | | | 5 | | mA _{DC} |

Electrical Characteristics (Continued) (Note 6)

| PARAMETER | CONDITIONS | LM2900 | | | LM3900 | | | LM3301 | | | LM3401 | | | UNITS |
|------------------------|--|--------|-----|-----|--------|-----|-----|--------|-----|------|--------|-----|------|---------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Power Supply Rejection | $T_A = 25^\circ\text{C}$, $f = 100\text{ Hz}$ | 70 | | | 70 | | | 70 | | | 70 | | | dB |
| Mirror Gain | @ $20\mu\text{A}$ (Note 3) | 0.90 | 1.0 | 1.1 | 0.90 | 1.0 | 1.1 | 0.90 | 1 | 1.10 | 0.90 | 1 | 1.10 | $\mu\text{A}/\mu\text{A}$ |
| | @ $200\mu\text{A}$ (Note 3) | 0.90 | 1.0 | 1.1 | 0.90 | 1.0 | 1.1 | 0.90 | 1 | 1.10 | 0.90 | 1 | 1.10 | $\mu\text{A}/\mu\text{A}$ |
| Δ Mirror Gain | @ $20\mu\text{A}$ To $200\mu\text{A}$ (Note 3) | 2 5 | | | 2 5 | | | 2 5 | | | 2 5 | | | % |
| Mirror Current | (Note 4) | 10 500 | | | 10 500 | | | 10 500 | | | 10 500 | | | μA_{DC} |
| Negative Input Current | $T_A = 25^\circ\text{C}$ (Note 5) | 1.0 | | | 1.0 | | | 1.0 | | | 1.0 | | | mA_{DC} |
| Voltage Gain | $f = 100\text{ Hz}$ | | | | | | | | | | | | | V/mV |
| Input Bias Current | Inverting Input | | | | | | | | | | | | | nA |

Note 1: For operating at high temperatures, the device must be derated based on a 125°C maximum junction temperature and a thermal resistance of 175°C/W which applies for the device soldered in a printed circuit board, operating in a still air ambient.

Note 2: The output current sink capability can be increased for large signal conditions by overdriving the inverting input. This is shown in the section on Typical Characteristics.

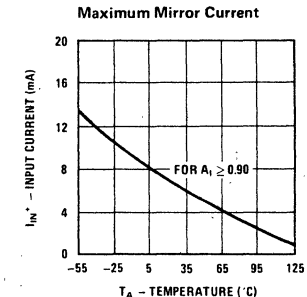
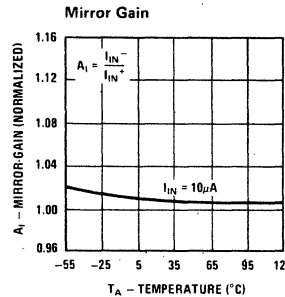
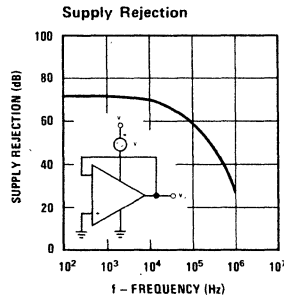
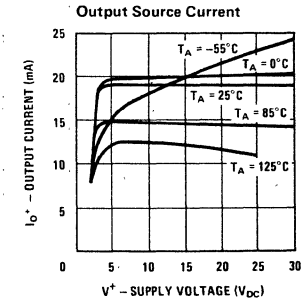
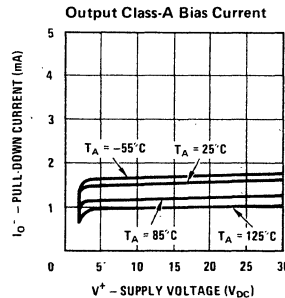
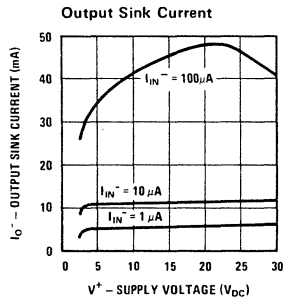
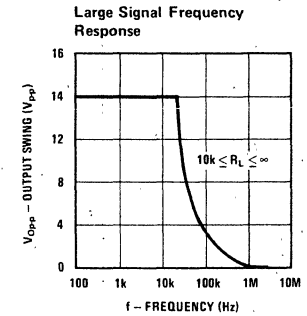
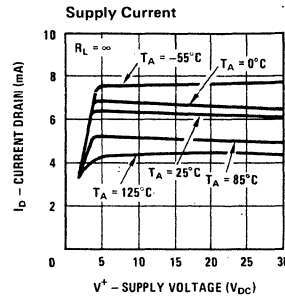
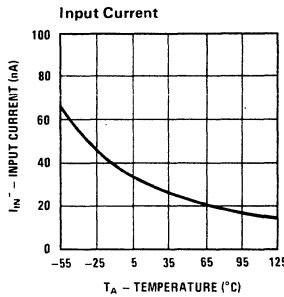
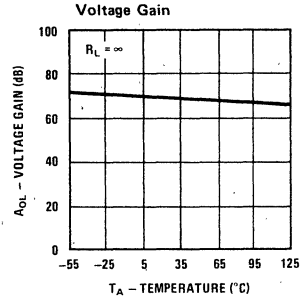
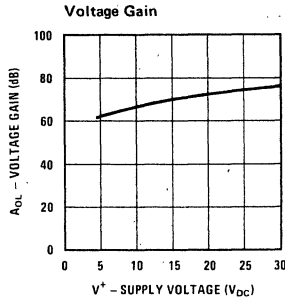
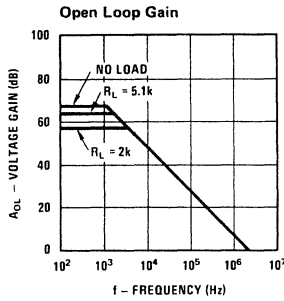
Note 3: This spec indicates the current gain of the current mirror which is used as the non-inverting input.

Note 4: Input V_{BE} match between the non-inverting and the inverting inputs occurs for a mirror current (non-inverting input current) of approximately $10\mu\text{A}$. This is therefore a typical design center for many of the application circuits.

Note 5: Clamp transistors are included on the IC to prevent the input voltages from swinging below ground more than approximately $-0.3 V_{\text{DS}}$. The negative input currents which may result from large signal overdrive with capacitance input coupling need to be externally limited to values of approximately 1 mA. Negative input currents in excess of 4 mA will cause the output voltage to drop to a low voltage. This maximum current applies to any one of the input terminals. If more than one of the input terminals are simultaneously driven negative smaller maximum currents are allowed. Common-mode current biasing can be used to prevent negative input voltages; see for example, the "Differentiator Circuit" in the applications section.

Note 6: These specs apply for $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, unless otherwise stated.

Typical Performance Characteristics



Application Hints

When driving either input from a low-impedance source, a limiting resistor should be placed in series with the input lead to limit the peak input current. Currents as large as 20 mA will not damage the device, but the current mirror on the non-inverting input will saturate and cause a loss of mirror gain at mA current levels—especially at high operating temperatures.

Precautions should be taken to insure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a test socket as an unlimited current surge through the resulting forward diode within the IC could cause fuzing of the internal conductors and result in a destroyed unit.

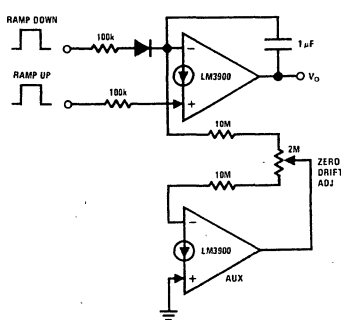
Output short circuits either to ground or to the positive power supply should be of short time duration. Units can be destroyed, not as a result of the short circuit current causing metal fuzing, but rather due to the large increase in IC chip dissipation which will cause eventual failure due to excessive junction temperatures. For example, when operating from a well-regulated +5 V_{DC} power supply at T_A = 25°C with a 100 kΩ shunt-feedback resistor (from the output to the inverting input) a short directly to the power supply will not cause catastrophic failure but the current magnitude will be approximately 50 mA and the junction temperature will be above T_J max. Larger feedback resistors will reduce the current, 11 MΩ provides approximately 30 mA, an open circuit provides 1.3 mA, and a direct connection from the output to the non-inverting input will result in catastrophic failure when the output is shorted to V⁺ as this then places the base-emitter junction of the input transistor directly across the power supply. Short-circuits to ground will have magnitudes of approximately 30 mA and will not cause catastrophic failure at T_A = 25°C.

Unintentional signal coupling from the output to the non-inverting input can cause oscillations. This is likely only in breadboard hook-ups with long component leads and can be prevented by a more careful lead dress or by locating the non-inverting input biasing resistor close to the IC. A quick check of this condition is to bypass the non-inverting input to ground with a capacitor. High impedance biasing resistors used in the non-inverting input circuit make this input lead highly susceptible to unintentional ac signal pickup.

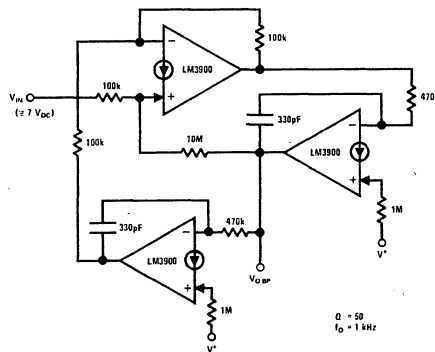
Operation of this amplifier can be best understood by noticing that input currents are differenced at the inverting-input terminal and this difference current then flows through the external feedback resistor to produce the output voltage. Common-mode current biasing is generally useful to allow operating with signal levels near ground or even negative as this maintains the inputs biased at +V_{BE}. Internal clamp transistors (see note 5) catch negative input voltages at approximately -0.3 V_{DC} but the magnitude of current flow has to be limited by the external input network. For operation at high temperature, this limit should be approximately 100μA.

This new "Norton" current-differencing amplifier can be used in most of the applications of a standard IC op amp. Performance as a dc amplifier using only a single supply is not as precise as a standard IC op amp operating with split supplies but is adequate in many less critical applications. New functions are made possible with this amplifier which are useful in single power supply systems. For example, biasing can be designed separately from the ac gain as was shown in the "inverting amplifier," the "difference integrator" allows controlling the charging and the discharging of the integrating capacitor both with positive voltages, and the "frequency doubling tachometer" provides a simple circuit which reduces the ripple voltage on a tachometer output dc voltage.

Typical Applications (Continued)

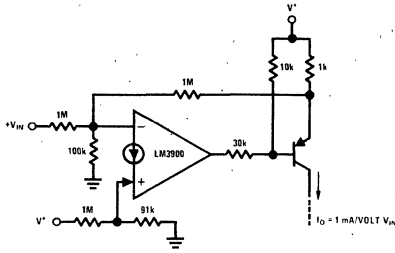


Low-Drift Ramp and Hold Circuit

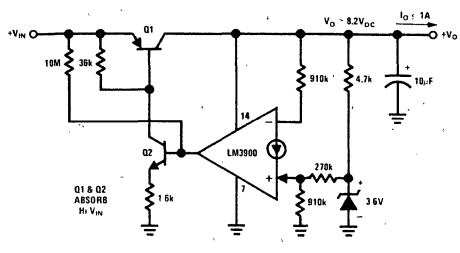


Bi-Quad Active Filter
(2nd Degree State-Variable Network)

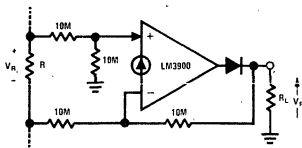
Typical Applications (Continued)



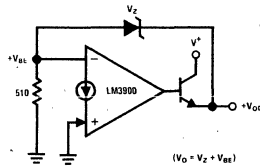
Voltage-Controlled Current Source (Transconductance Amplifier)



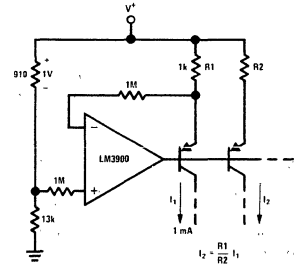
Hi V_{IN} , Lo ($V_{IN} - V_O$) Self-Regulator



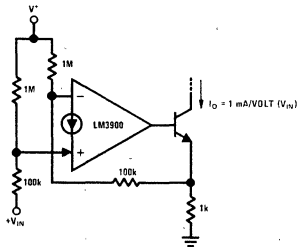
Ground-Referencing a Differential Input Signal



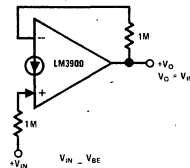
Voltage Regulator



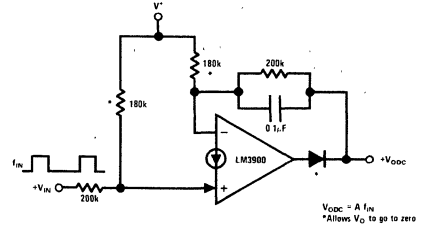
Fixed Current Sources



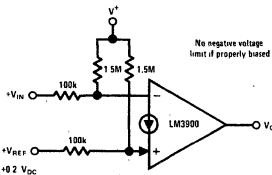
Voltage-Controlled Current Sink (Transconductance Amplifier)



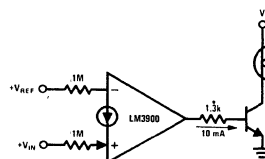
Buffer Amplifier



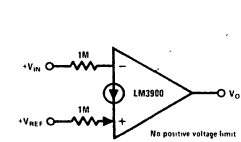
Tachometer



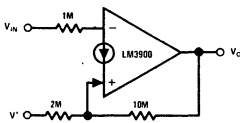
Low-Voltage Comparator



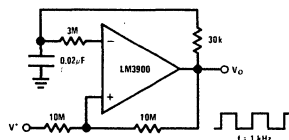
Power Comparator



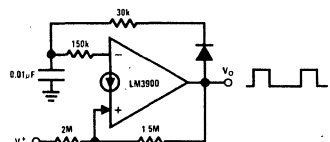
Comparator



Schmitt-Trigger



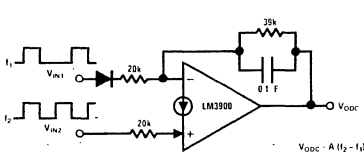
Square-Wave Oscillator



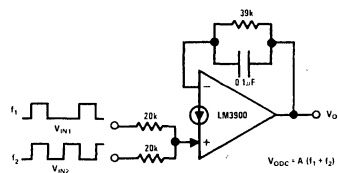
Pulse Generator

Typical Applications (Continued)

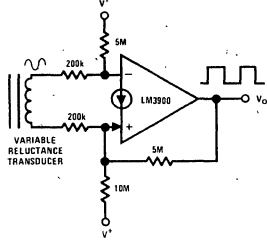
LM2900/LM3900, LM3301, LM3401



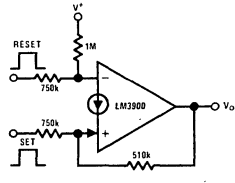
Frequency Differencing Tachometer



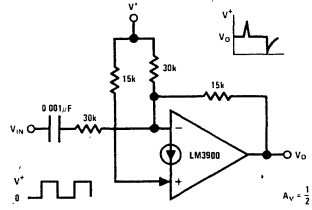
Frequency Averaging Tachometer



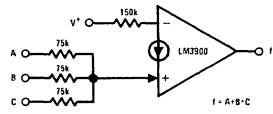
Squaring Amplifier (W/Hysteresis)



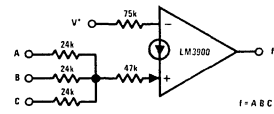
Bi-Stable Multivibrator



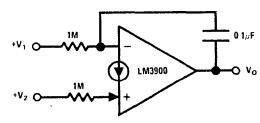
Differentiator (Common-Mode Biasing Keeps Input at +V_{BE})



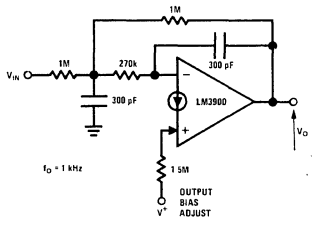
"OR" Gate



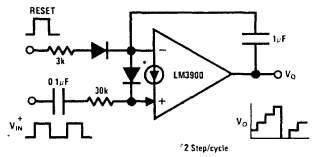
"AND" Gate



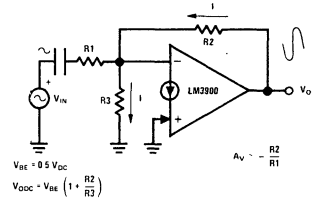
Difference Integrator



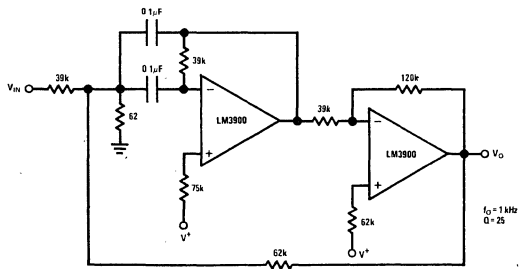
Low Pass Active Filter



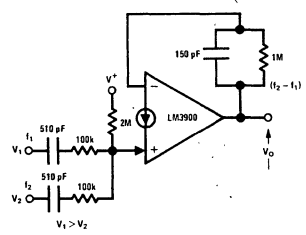
Staircase Generator



V_{BE} Biasing



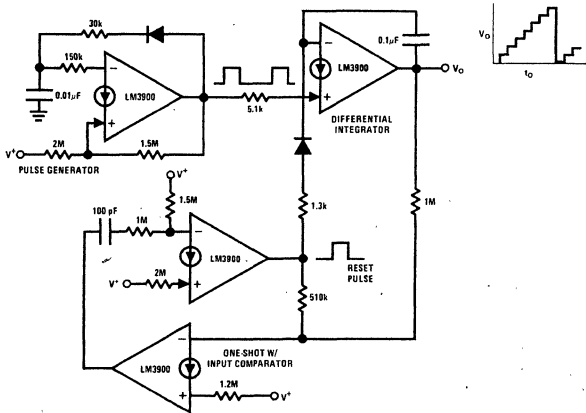
Bandpass Active Filter



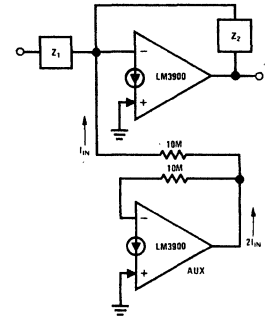
Low-Frequency Mixer

3

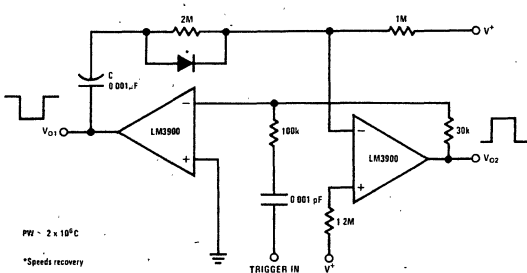
Typical Applications (Continued)



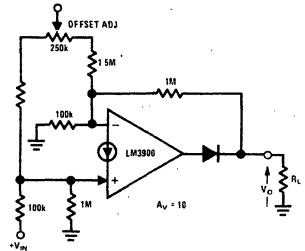
Free-Running Staircase Generator/Pulse Counter



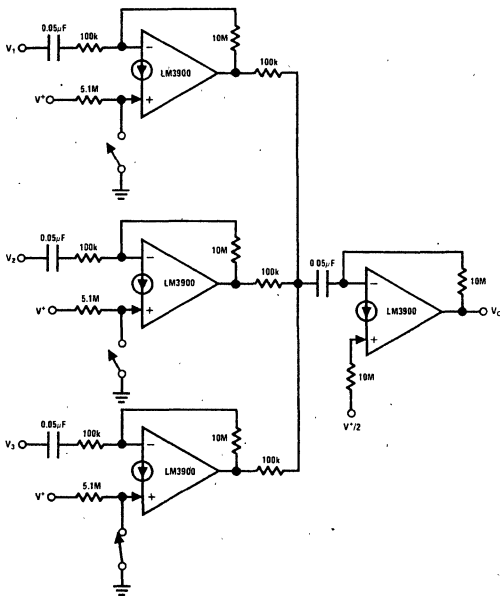
Supplying I_{IN} with Aux. Amp (to Allow Hi-Z Feedback Networks)



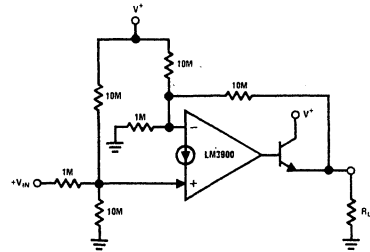
One-Shot Multivibrator



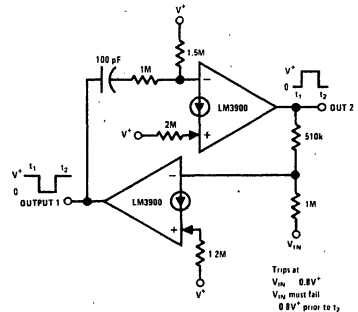
Non-Inverting DC Gain to (0,0)



Channel Selection by DC Control (or Audio Mixer)



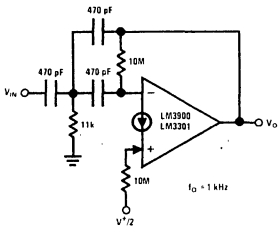
Power Amplifier



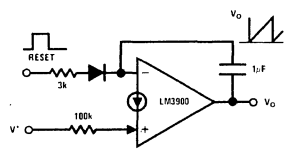
One-Shot with DC Input Comparator

Trips at $V_{IN} = 0.8V^+$
 V_{IN} must fall $0.8V^+$ prior to t_2

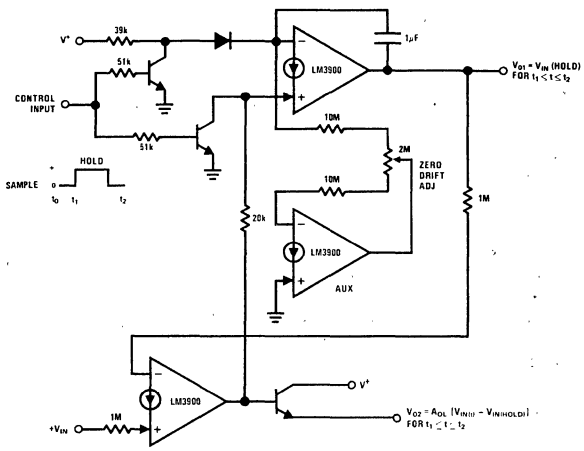
Typical Applications (Continued)



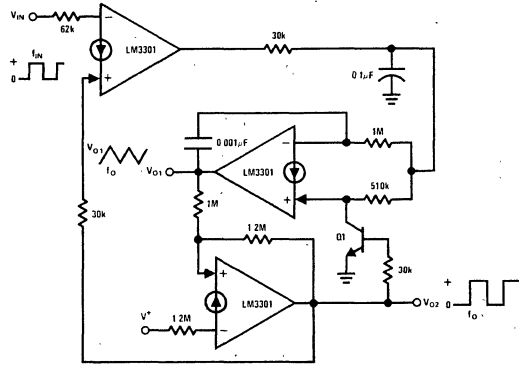
High Pass Active Filter



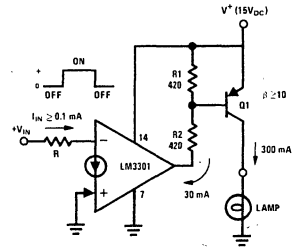
Sawtooth Generator



Sample-Hold and Compare with New +V_{IN}

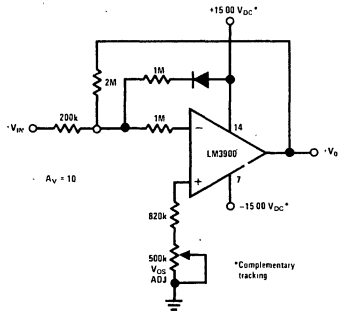


Phase-locked Loop

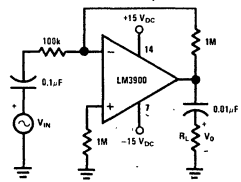


Boosting to 300 mA Loads

Split-Supply Applications ($V^+ = +15 V_{DC}$ & $V^- = -15 V_{DC}$)



Non-Inverting DC Gain



AC Amplifier

LM4250/LM4250C Programmable Operational Amplifier

General Description

The LM4250 and LM4250C are extremely versatile programmable monolithic operational amplifiers. A single external master bias current setting resistor programs the input bias current, input offset current, quiescent power consumption, slew rate, input noise, and the gain-bandwidth product. The device is a truly general purpose operational amplifier.

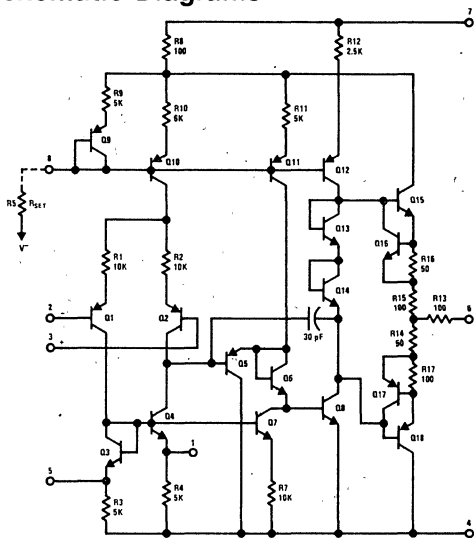
- Standby power consumption as low as 500 nW
- No frequency compensation required
- Programmable electrical characteristics
- Offset Voltage nulling capability
- Can be powered by two flashlight batteries
- Short circuit protection

Features

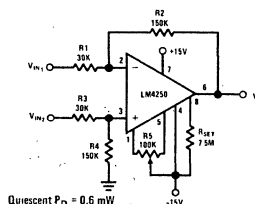
- $\pm 1V$ to $\pm 18V$ power supply operation
- 3 nA input offset current

The LM4250C is identical to the LM4250 except that the LM4250C has its performance guaranteed over a $0^{\circ}C$ to $70^{\circ}C$ temperature range instead of the $-55^{\circ}C$ to $+125^{\circ}C$ temperature range of the LM4250.

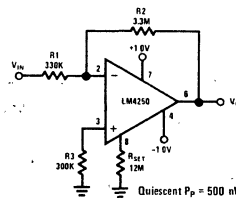
Schematic Diagrams



Typical Applications



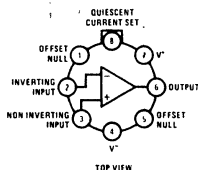
X5 Difference Amplifier



500 Nano-Watt X10 Amplifier

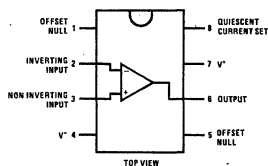
Connection Diagrams

Metal Can Package



Order Number LM4250H or LM4250CH
See NS Package H08C

Dual-In-Line Package



Order Number LM4250CN
See NS Package N08B
Order Number LM4250J
or LM4250CJ
See NS Package J08A

Absolute Maximum Ratings

| | | | |
|----------------------------|--------|--------------------------------------|---------------------------------------|
| Supply Voltage | ±18V | Output Short-Circuit Duration | Indefinite |
| Power Dissipation (Note 1) | 500 mW | Operating Temperature Range | LM4250 -55°C ≤ T _A ≤ 125°C |
| Differential Input Voltage | ±30V | | LM4250C 0°C ≤ T _A ≤ 70°C |
| Input Voltage (Note 2) | ±15V | Storage Temperature Range | -65°C to 150°C |
| I _{SET} Current | 150 μA | Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics LM4250 (-55°C ≤ T_A ≤ 125°C unless otherwise specified)

| PARAMETERS | CONDITIONS | V _S = ±1.5V | | | |
|--------------------------------|--|-------------------------|--------|--------------------------|--------|
| | | I _{SET} = 1 μA | | I _{SET} = 10 μA | |
| | | MIN | MAX | MIN | MAX |
| V _{OS} | T _A = 25° R _S ≤ 100 kΩ | | 3 mV | | 5 mV |
| I _{OS} | T _A = 25° | | 3 nA | | 10 nA |
| I _{bias} | T _A = 25° | | 7.5 nA | | 50 nA |
| Large Signal Voltage Gain | T _A = 25° R _L = 100 kΩ | 40k | | | |
| | V _O = ±0.6, R _L = 10 kΩ | | | 50k | |
| Supply Current | T _A = 25°C | | 7.5 μA | | 80 μA |
| Power Consumption | T _A = 25°C | | 23 μW | | 240 μW |
| V _{OS} | R _S ≤ 100 kΩ | | 4 mV | | 6 mV |
| I _{OS} | T _A = 125°C | | 5 nA | | 10 nA |
| I _{bias} | T _A = -55°C | | 3 nA | | 10 nA |
| I _{bias} | | | 7.5 nA | | 50 nA |
| Input Voltage Range | | ±0.7V | | ±0.7V | |
| Large Signal Voltage Gain | V _O = ±0.6V R _L = 100 kΩ | 30k | | | |
| | R _L = 10 kΩ | | | 30k | |
| Output Voltage Swing | R _L = 100 kΩ | ±0.6V | | | |
| | R _L = 10 kΩ | | | ±0.6V | |
| Common Mode Rejection Ratio | R _S ≤ 10 kΩ | 70 dB | | 70 dB | |
| Supply Voltage Rejection Ratio | R _S ≤ 10 kΩ | 76 dB | | 76 dB | |
| Supply Current | | | 8 μA | | 90 μA |
| Power Consumption | | | 24 μW | | 270 μW |

| PARAMETERS | CONDITIONS | V _S = ±15V | | | |
|--------------------------------|---|-------------------------|--------|--------------------------|--------|
| | | I _{SET} = 1 μA | | I _{SET} = 10 μA | |
| | | MIN | MAX | MIN | MAX |
| V _{OS} | T _A = 25°C R _S ≤ 100 kΩ | | 3 mV | | 5 mV |
| I _{OS} | T _A = 25°C | | 3 nA | | 10 nA |
| I _{bias} | T _A = 25°C | | 7.5 nA | | 50 nA |
| Large Signal Voltage Gain | T _A = 25°C R _L = 100 kΩ | 100k | | | |
| | V _O = ±10V R _L = 10 kΩ | | | 100k | |
| Supply Current | T _A = 25°C | | 10 μA | | 90 μA |
| Power Consumption | T _A = 25°C | | 300 μW | | 2.7 mW |
| V _{OS} | R _S ≤ 100 kΩ | | 4 mV | | 6 mV |
| I _{OS} | T _A = 125°C | | 25 nA | | 25 nA |
| I _{bias} | T _A = -55°C | | 3 nA | | 10 nA |
| I _{bias} | | | 7.5 nA | | 50 nA |
| Input Voltage Range | | ±13.5V | | ±13.5V | |
| Large Signal Voltage Gain | V _O = ±10V R _L = 100 kΩ | 50k | | | |
| | R _L = 10 kΩ | | | 50k | |
| Output Voltage Swing | R _L = 100 kΩ | ±12V | | | |
| | R _L = 10 kΩ | | | ±12V | |
| Common Mode Rejection Ratio | R _S ≤ 10 kΩ | 70 dB | | 70 dB | |
| Supply Voltage Rejection Ratio | R _S ≤ 10 kΩ | 76 dB | | 76 dB | |
| Supply Current | | | 11 μA | | 100 μA |
| Power Consumption | | | 330 μW | | 3 mW |

Note 1: The maximum junction temperature of the LM4250 is 150°C, while that of the LM4250C is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W junction to ambient, or 45°C/W junction to case. The thermal resistance of the dual-in-line package is 125°C/W.

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Electrical Characteristics LM4250C ($0^{\circ}\text{C} \leq T_A \leq 70^{\circ}\text{C}$ unless otherwise specified)

| PARAMETERS | CONDITIONS | $V_S = \pm 1.5\text{V}$ | | | |
|--------------------------------|--|----------------------------|------------------|-----------------------------|-------------------|
| | | $I_{SET} = 1\ \mu\text{A}$ | | $I_{SET} = 10\ \mu\text{A}$ | |
| | | MIN | MAX | MIN | MAX |
| V_{OS} | $T_A = 25^{\circ}\text{C}$ $R_S \leq 100\ \text{k}\Omega$ | | 5 mV | | 6 mV |
| I_{OS} | $T_A = 25^{\circ}\text{C}$ | | 6 nA | | 20 nA |
| I_{bias} | $T_A = 25^{\circ}\text{C}$ | | 10 nA | | 75 nA |
| Large Signal Voltage Gain | $T_A = 25^{\circ}\text{C}$ $R_L = 100\ \text{k}\Omega$ $V_O = \pm 0.6\text{V}$ $R_L = 10\ \text{k}\Omega$ | 25k | | 25k | |
| Supply Current | $T_A = 25^{\circ}\text{C}$ | | 8 μA | | 90 μA |
| Power Consumption | $T_A = 25^{\circ}\text{C}$ | | 24 μW | | 270 μW |
| V_{OS} | $R_S \leq 10\ \text{k}\Omega$ | | 6.5 mV | | 7.5 mV |
| I_{OS} | | | 8 nA | | 25 nA |
| I_{bias} | | | 10 nA | | 80 nA |
| Input Voltage Range | | $\pm 0.6\text{V}$ | | $\pm 0.6\text{V}$ | |
| Large Signal Voltage Gain | $V_O = \pm 0.6\text{V}$ $R_L = 100\ \text{k}\Omega$ $R_L = 10\ \text{k}\Omega$ | 25k | | 25k | |
| Output Voltage Swing | $R_L = 100\ \text{k}\Omega$ $R_L = 10\ \text{k}\Omega$ | $\pm 0.6\text{V}$ | | $\pm 0.6\text{V}$ | |
| Common Mode Rejection Ratio | $R_S \leq 10\ \text{k}\Omega$ | 70 dB | | 70 dB | |
| Supply Voltage Rejection Ratio | $R_S \leq 10\ \text{k}\Omega$ | 74 dB | | 74 dB | |
| Supply Current | | | 8 μA | | 90 μA |
| Power Consumption | | | 24 μW | | 270 μW |

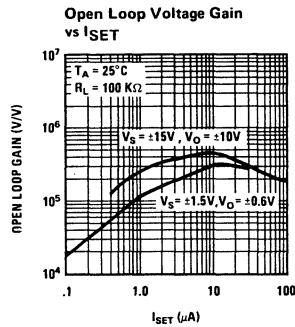
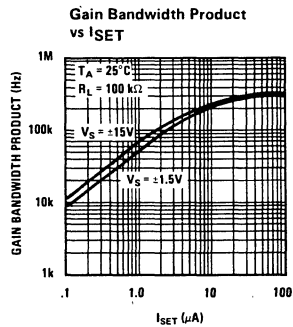
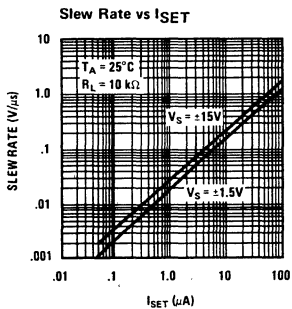
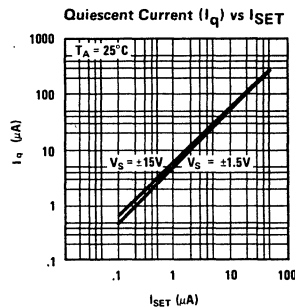
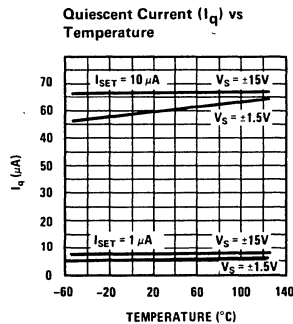
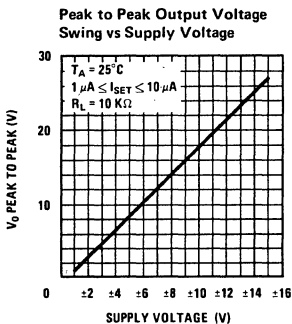
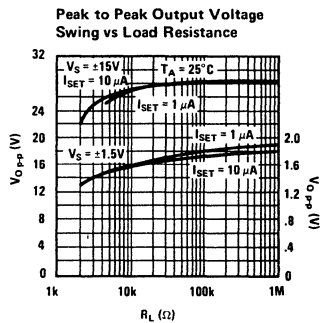
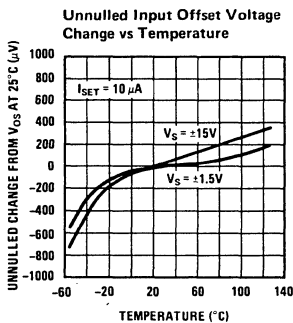
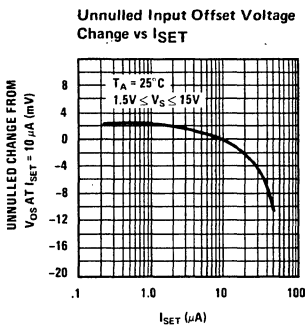
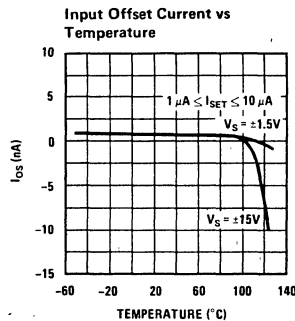
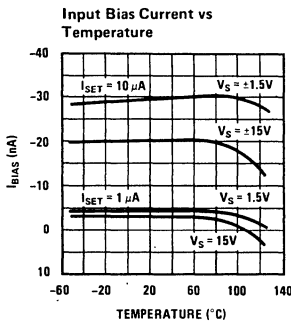
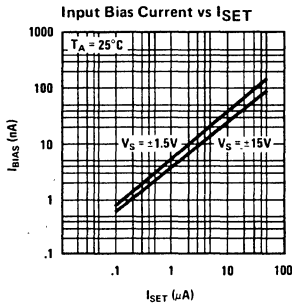
| PARAMETERS | CONDITIONS | $V_S = \pm 15\text{V}$ | | | |
|--------------------------------|---|----------------------------|-------------------|-----------------------------|-------------------|
| | | $I_{SET} = 1\ \mu\text{A}$ | | $I_{SET} = 10\ \mu\text{A}$ | |
| | | MIN | MAX | MIN | MAX |
| V_{OS} | $T_A = 25^{\circ}\text{C}$ $R_S \leq 100\ \text{k}\Omega$ | | 5 mV | | 6 mV |
| I_{OS} | $T_A = 25^{\circ}\text{C}$ | | 6 nA | | 20 nA |
| I_{bias} | $T_A = 25^{\circ}\text{C}$ | | 10 nA | | 75 nA |
| Large Signal Voltage Gain | $T_A = 25^{\circ}\text{C}$ $R_L = 100\ \text{k}\Omega$ $V_O = \pm 10\text{V}$ $R_L = 10\ \text{k}\Omega$ | 60k | | 60k | |
| Supply Current | $T_A = 25^{\circ}\text{C}$ | | 11 μA | | 100 μA |
| Power Consumption | $T_A = 25^{\circ}\text{C}$ | | 330 μW | | 3 mW |
| V_{OS} | $R_S \leq 10\ \text{k}\Omega$ | | 6.5 mV | | 7.5 mV |
| I_{OS} | | | 8 nA | | 25 nA |
| I_{bias} | | | 10 nA | | 80 nA |
| Input Voltage Range | | $\pm 13.5\text{V}$ | | $\pm 13.5\text{V}$ | |
| Large Signal Voltage Gain | $V_O = \pm 10\text{V}$ $R_L = 100\ \text{k}\Omega$ $R_L = 10\ \text{k}\Omega$ | 50k | | 50k | |
| Output Voltage Swing | $R_L = 100\ \text{k}\Omega$ $R_L = 10\ \text{k}\Omega$ | $\pm 12\text{V}$ | | $\pm 12\text{V}$ | |
| Common Mode Rejection Ratio | $R_S \leq 10\ \text{k}\Omega$ | 70 dB | | 70 dB | |
| Supply Voltage Rejection Ratio | $R_S \leq 10\ \text{k}\Omega$ | 74 dB | | 74 dB | |
| Supply Current | | | 11 μA | | 100 μA |
| Power Consumption | | | 300 μW | | 3 mW |

Resistor Biasing

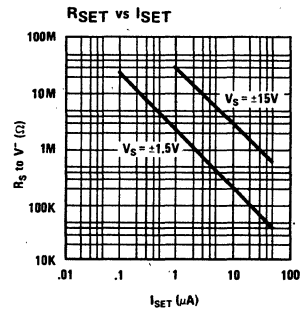
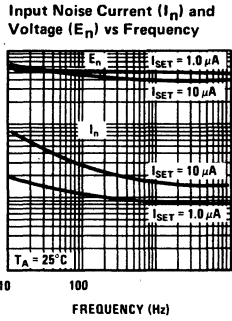
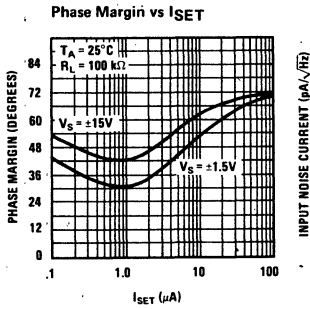
Set Current Setting Resistor to V^-

| V_S | I_{SET} | | | | |
|--------------------|-------------------|-------------------|-------------------|-----------------|------------------|
| | 0.1 μA | 0.5 μA | 1.0 μA | 5 μA | 10 μA |
| $\pm 1.5\text{V}$ | 25.6 M Ω | 5.04 M Ω | 2.5 M Ω | 492 k Ω | 244 k Ω |
| $\pm 3.0\text{V}$ | 55.6 M Ω | 11.0 M Ω | 5.5 M Ω | 1.09 M Ω | 544 k Ω |
| $\pm 6.0\text{V}$ | 116 M Ω | 23.0 M Ω | 11.5 M Ω | 2.29 M Ω | 1.14 M Ω |
| $\pm 9.0\text{V}$ | 176 M Ω | 35.0 M Ω | 17.5 M Ω | 3.49 M Ω | 1.74 M Ω |
| $\pm 12.0\text{V}$ | 236 M Ω | 47.0 M Ω | 23.5 M Ω | 4.69 M Ω | 2.34 M Ω |
| $\pm 15.0\text{V}$ | 296 M Ω | 59.0 M Ω | 29.5 M Ω | 5.89 M Ω | 2.94 M Ω |

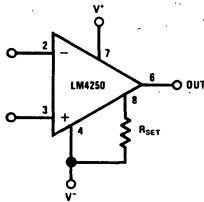
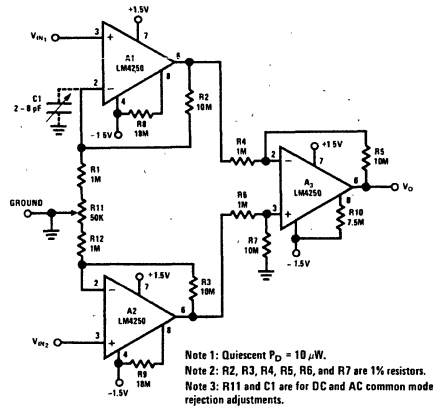
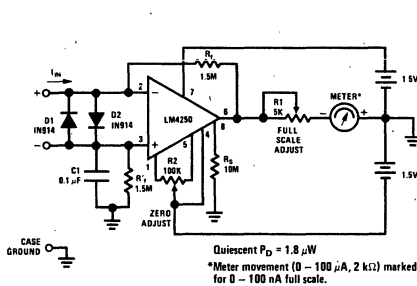
Typical Performance Characteristics



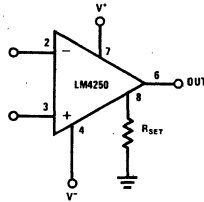
Typical Performance Characteristics (Continued)



Typical Applications (Continued)



RSET Connected to V^-

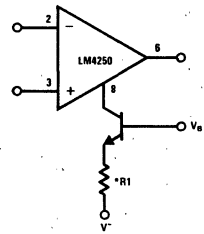


RSET Connected to Ground

I_{SET} EQUATIONS:

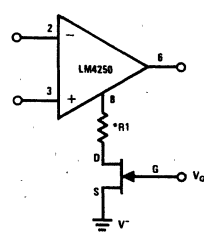
$$I_{SET} = \frac{V^- + V^- - 0.5}{R_{SET}} \quad \text{where } R_{SET} \text{ is connected to } V^-.$$

$$I_{SET} = \frac{V^- - 0.5}{R_{SET}} \quad \text{where } R_{SET} \text{ is connected to ground.}$$

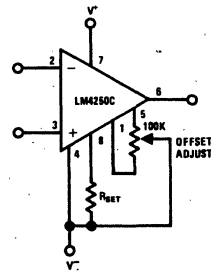


Transistor Current Source Biasing

*R1 limits I_{SET} maximum



FET Current Source Biasing



Offset Null Circuit

LH24250/LH24250C Dual Programmable Micropower Op Amp

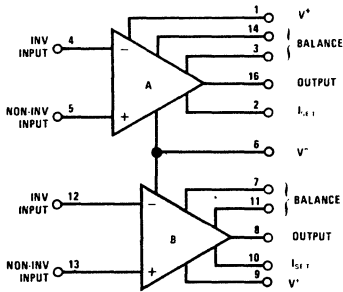
general description

The LH24250/LH24250C series of dual programmable micropower operational amplifiers are two LM4250 type op amps in a single hermetic package. Featuring all the same performance characteristics of the LM4250, the LH24250/LH24250C duals also offer closer thermal tracking, lower weight, reduced insertion cost and smaller size than two single devices. For additional information, see the LM4250 data sheet and National's Linear Application Handbook.

features

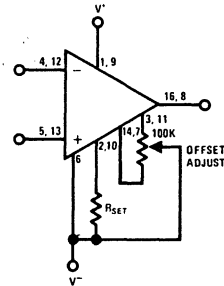
- ±1V to ±18V power supply operation
- Standby power consumption as low as 20 μW
- Offset current programmable from less than 0.5 nA to 30 nA
- Programmable slew rate
- May be shut-down using standard open collector TTL
- Internally compensated and short circuit proof

connection diagram and auxiliary circuit



Order Number LH24250D or LH24250CD
See Package D16C

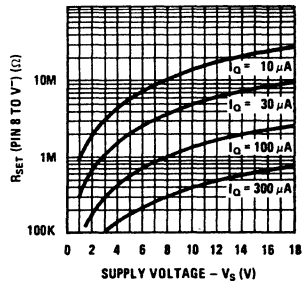
Offset Null Circuit



typical quiescent current setting resistor

(Pin 8 to V₋)

| V _S | 10 μA | 30 μA | 100 μA | 300 μA |
|----------------|--------|--------|--------|--------|
| ±1.5 | 1.5 MΩ | 470 kΩ | 150 kΩ | |
| ±3 | 3.3 MΩ | 1.1 MΩ | 330 kΩ | 100 kΩ |
| ±6 | 7.5 MΩ | 2.7 MΩ | 750 kΩ | 220 kΩ |
| ±9 | 13 MΩ | 4 MΩ | 1.3 MΩ | 350 kΩ |
| ±12 | 18 MΩ | 5.6 MΩ | 1.5 MΩ | 510 kΩ |
| ±15 | 22 MΩ | 7.5 MΩ | 2.2 MΩ | 620 kΩ |



absolute maximum ratings

| | | | |
|-------------------------------------|------------|--------------------------------------|-----------------|
| Supply Voltage | +18V | Operating Temperature Range | -55°C to +125°C |
| Power Dissipation (Note 1) | 500 mW | LH24250 | 0°C to +70°C |
| Differential Input Voltage (Note 2) | +15V | LH24250C | -65°C to +150°C |
| Input Voltage (Note 3) | +15V | Storage Temperature Range | 300°C |
| Output Short Circuit Duration | Continuous | Lead Temperature (Soldering, 10 sec) | |

electrical characteristics – each side (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | UNITS |
|--------------------------------|---|---------|----------|-------------------|
| | | LH24250 | LH24250C | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}, R_S < 100\text{ k}\Omega$ | 3.0 | 6.0 | mV Max |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | 5 | 10 | nA Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 15 | 30 | nA Max |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 3 | 3 | M Ω Min |
| Power Consumption | $T_A = 25^\circ\text{C}, V_O = 0, R_{SET} = 2.7\text{ M}\Omega$ | 480 | 600 | μW Max |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}, R_L > 10\text{ k}\Omega$ | 100 | 75 | V/mV Min |
| Input Offset Voltage | $R_S > 10\text{ k}\Omega$ | 4.0 | 7.5 | mV Max |
| Input Offset Current | | 5 | 15 | nA Max |
| Input Bias Current | | 15 | 50 | nA Max |
| Large Signal Voltage Gain | $R_L > 10\text{ k}\Omega$ | 50 | 50 | V/mV Min |
| Output Voltage Swing | $R_L > 10\text{ k}\Omega, V_S = \pm 15\text{V}$ | ±10 | ±10 | V Min |
| Input Voltage Range | $T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}$ | ±12 | ±12 | V Min |
| Common Mode Rejection Ratio | $T_A = 25^\circ\text{C}, R_S < 10\text{ k}\Omega$ | 70 | 70 | dB Min |
| Supply Voltage Rejection Ratio | $T_A = 25^\circ\text{C}, R_S < 10\text{ k}\Omega$ | 76 | 76 | dB Min |

- Note 1:** Derate linearly 2 mW/°C case temperature above 25°C.
- Note 2:** This rating applies to maximum voltage differential between input terminals. The maximum input voltage on either input terminal is limited to +V_S up to +15V.
- Note 3:** This rating limited to ± supply voltage to a maximum of ±15V.
- Note 4:** These specifications apply for V_S = ±6V, I_Q = 30 μA , and -55°C < T_A < +125°C unless otherwise specified. With the LH24250C, however, all temperature specifications are limited to 0°C < T_A < 70°C.

LM13080 Programmable Power Op Amp

General Description

The LM13080 is an internally compensated medium power operational amplifier designed for use in those applications requiring load currents of several hundred milliamperes. This amplifier has the added advantage of having an input stage programmed with an external resistor. The user is able to optimize the amplifier performance for each individual application with this feature. Applications include servo amplifiers and drivers, high input impedance audio amplifiers, DC-to-DC converters, precision power comparators which can either sink or source current and motor speed controls.

current boost transistors to the output of a standard operational amplifier.

By selecting the proper input stage bias resistor it is possible to tailor the performance of the input stage to meet the needs of any particular system. Trade-offs between input offset voltage, input bias current and gain bandwidth are easily made.

An unusual feature of the LM13080 is an electronic shut-down capability.

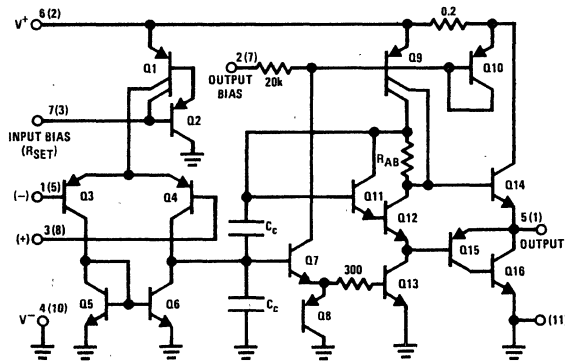
The LM13080 may be powered from either single or dual power supplies, and will operate from as little as 3V.

As a power operational amplifier, the LM13080 is capable of delivering 0.25A to a load. This feature allows the system designer to fulfill his medium power circuit requirements without having to add external

Features

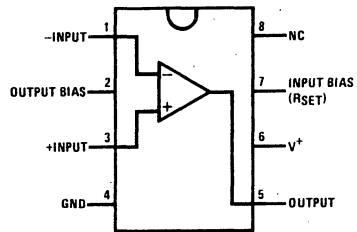
- High output current—250 mA
- Externally programmable input stage
- Low power supply operation—3V
- Electronic shut-down capability
- Internally compensated for unity gain
- Low input bias current

Schematic and Connection Diagrams



Numbers in parentheses show LM13080P connections

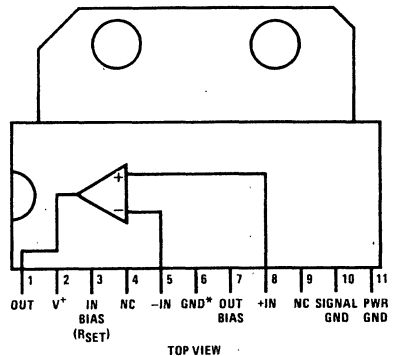
Dual-In-Line Package (LM13080N)



TOP VIEW

Order Number LM13080N
See NS Package N08B

Single-In-Line Package (LM13080P)



TOP VIEW

*Pin 6 can be connected to pin 10, if not, pin 6 must be left with no connection.

Order Number LM13080P
See NS Package P11A

Absolute Maximum Ratings

| | | | |
|--|--------------------------------|---|-----------------|
| Supply Voltage Operation Range | 3V to 15V or ±1.5V to ±7.5V | Input Voltage Range, (Note 3) | -0.3V to +15V |
| Power Dissipation, (Note 1) | | Input Current ($V_{IN} \leq -0.3V$), (Note 4) | 20 mA |
| Molded Dual-In-Line Package (LM13080N) | 1000 mW | Operating Temperature Range | 0°C to +70°C |
| Differential Input Voltage, (Note 2) | 15V | Storage Temperature Range | -65°C to +150°C |
| | | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

($V_S = 12V$, $R_{SET} = 680k$, unless otherwise specified)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|---|------|-----|--------------|------------------|
| Input Offset Voltage | $T_A = 25^\circ C$, (Note 5) | | ±3 | ±7 | mV |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$, $T_A = 25^\circ C$ | | 100 | 400 | nA |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$, $T_A = 25^\circ C$ | | ±30 | ±75 | nA |
| Supply Current | $R_L = \infty$, $T_A = 25^\circ C$, (Note 6) | | 3 | 6 | mA |
| Output Voltage Swing | $V_S = \pm 6V$, $T_A = 25^\circ C$, (Note 1) | | | | |
| V_{OH} | $R_L = 50\Omega$ | 4.5 | 5 | | V |
| | $R_L = 8\Omega$ | 2 | | | V |
| V_{OL} | $R_L = 50\Omega$ | | -5 | -4.5 | V |
| | $R_L = 8\Omega$ | | | -2 | V |
| Large Signal Voltage Gain | $V_S = \pm 6V$, $R_L = 50\Omega$, $f = 100$ Hz, $T_A = 25^\circ C$ | 3 | 10 | | V/mV |
| Input Common-Mode Voltage Range | $V_S \leq 15V$, $T_A = 25^\circ C$, (Note 3) | 1 | | $V_S - 1.5$ | V |
| Input Offset Voltage | (Note 5) | | | ±10 | mV |
| Input Offset Voltage Drift | | | 5 | | $\mu V/^\circ C$ |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$ | | | 600 | nA |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$ | | | ±150 | nA |
| Input Offset Current Drift | | | 50 | | $pA/^\circ C$ |
| Supply Current | $R_L = \infty$, (Note 6) | | | 8 | mA |
| Output Voltage Swing | $V_S = \pm 6V$, (Note 1) | | | | |
| V_{OH} | $R_L = 50\Omega$ | | | 4 | V |
| | $R_L = 8\Omega$ | | | 1.6 | V |
| V_{OL} | $R_L = 50\Omega$ | -4 | | | V |
| | $R_L = 8\Omega$ | -1.6 | | | V |
| Large Signal Voltage Gain | $V_S = \pm 6V$, $R_L = 50\Omega$, $f = 100$ Hz | 1 | | | V/mV |
| Input Common-Mode Voltage Range | $V_S \leq 15V$, (Note 3) | 1.25 | | $V_S - 1.75$ | V |
| Common-Mode Rejection Ratio | | 63 | 85 | | dB |
| Total Harmonic Distortion | $R_L = 8\Omega$, $V_O = 2 V_{rms}$, $f = 1$ kHz | | 0.5 | 5 | % |

Note 1: For operation at high temperatures the LM13080 must be derated based on a maximum junction temperature of 150°C and a thermal resistance of 120°C/W. The thermal resistance value is for a package soldered into a printed circuit board and operating in a still air ambient.

Note 2: Differential input voltages up to the magnitude of the power supply voltage will not damage the input circuitry. However, input voltages outside the input common-mode voltage range will not be able to properly control the output of the amplifier.

Note 3: The input voltage applied to either input should not be allowed to go more than 0.3V below the potential applied to pin 4; however, either input can be taken as high as 15V without causing damage to the circuit. Input voltages below the minimum common-mode voltage range may cause a phase reversal in the output.

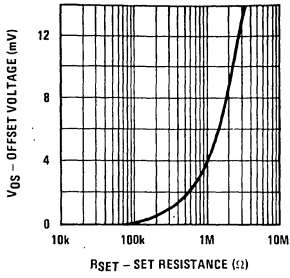
Note 4: This input current will exist only when the voltage at either input lead is driven negative. It is due to the base-isolation junction of the PNP transistor tub becoming forward biased and thereby acting as an input diode clamp. In addition to this diode action, there is also lateral NPN parasitic action on the IC chip. This transistor action can cause the output to take an undefined state for the time duration that an input is driven negative.

Note 5: $V_O = 6V$, $R_S = 0\Omega$, and over the full input common-mode voltage range.

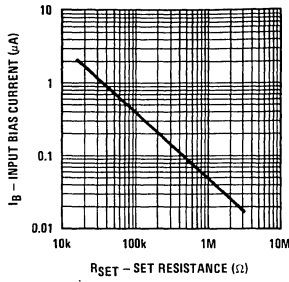
Note 6: Supply current is measured with the amplifier connected in a unity gain follower configuration and the positive input set to one-half of the supply voltage.

Typical Performance Characteristics

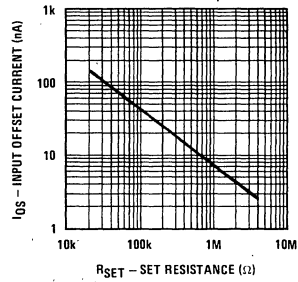
Offset Voltage



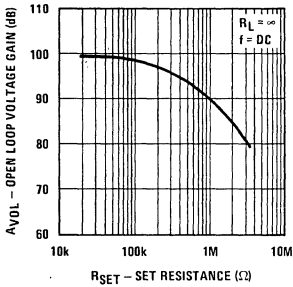
Input Bias Current



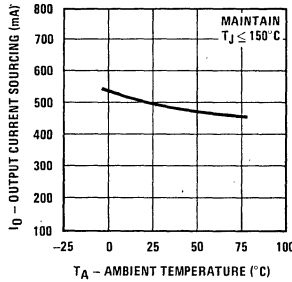
Offset Current



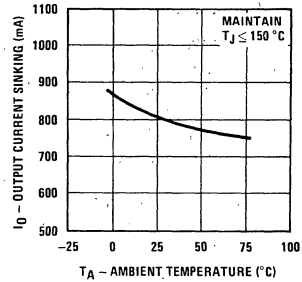
Voltage Gain as a Function of RSET



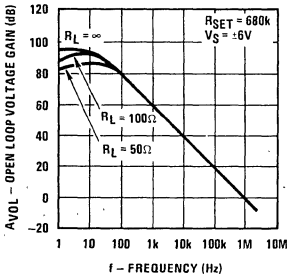
Output Current Sourcing



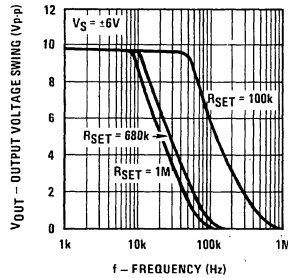
Output Current Sinking



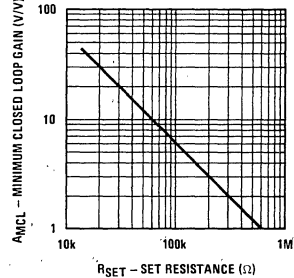
Open Loop Frequency Response



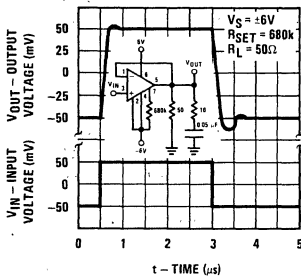
Large Signal Frequency Response



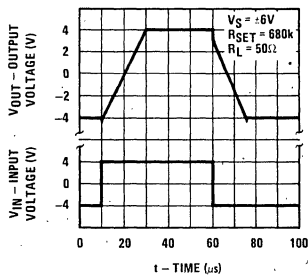
Minimum Stable Closed Loop Gain



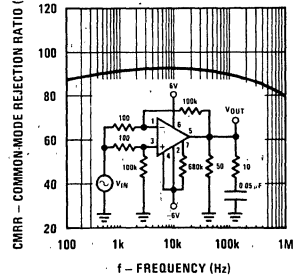
Voltage Follower Pulse Response (Small Signal)



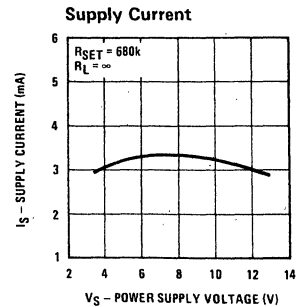
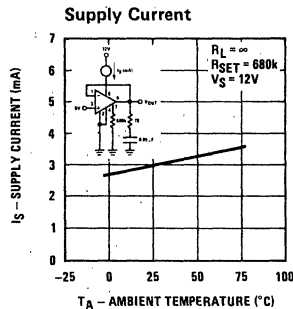
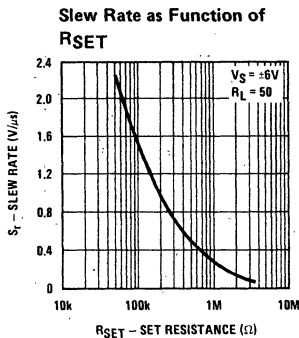
Voltage Follower Pulse Response (Large Signal)



Common-Mode Rejection Ratio



Typical Performance Characteristics (Continued)



Application Hints

The LM13080 is a power op amp capable of sourcing or sinking more than 250 mA which does not include internal current limit or thermal shut-down. Therefore, the user must make sure that his application will not exceed the power dissipation ratings of the package. The LM13080 is rated at a maximum power dissipation of 1000 mW, but this rating is for an ambient temperature of 25°C. For operation at temperatures above 25°C, the maximum dissipation must be derated using the equation:

$$P_D = \frac{T_J - T_A}{\Theta_{JA}} \quad (1)$$

where P_D is the maximum allowable power dissipation, T_J is the maximum junction temperature (150°C), T_A is the ambient temperature and Θ_{JA} is the thermal resistance of the package operated in a still air environment (120°C/W). If the LM13080 is to be used in a 70°C ambient then the maximum power that can be dissipated is:

$$P_D = \frac{150^\circ\text{C} - 70^\circ\text{C}}{120^\circ\text{C/W}} = 665 \text{ mW.}$$

The LM13080 derives its ability to sink current through the use of a composite NPN/PNP output configuration. This local loop must be compensated by the series connection of a 0.05 μF capacitor and a 10Ω resistor between the output of the op amp (pin 5) and the negative power supply (pin 4). The RC does not just filter out the oscillation from the output waveform but actually stabilizes the loop.

If the inputs of the LM13080 are driven below the input common-mode voltage range, it is possible that the output will experience a phase reversal. This is particularly true for the non-inverting input ($V_{IN(+)}$). If either input is driven to a voltage level 0.3V below the substrate (pin 4) a parasitic NPN transistor will be turned ON. The emitter of this parasitic transistor is the normal input transistor epi (N-type, base) region, the base is the substrate (P-type) and the collector is every other epi region on the die. Circuit operation in this mode is unpredictable. If an input is forced below the substrate, the current flowing out of that input should be limited to 20 mA to insure that the amplifier will not be destroyed.

Programming the LM13080 is accomplished by selecting the value of R_{SET} , the input stage bias resistor, to optimize the amplifier for each particular application. An example would be an application with low source resistance which requires a low offset voltage to make a precise DC measurement. By selecting an R_{SET} of 100 kΩ, the normal offset voltage would be reduced to approximately one-fourth the value, it would be if a 680k resistor was used. By studying the curves, it can be seen that the bias current will increase but an increase here has very little effect due to the small source impedance. It should also be noted that with a 100k input set resistor the gain bandwidth product will also increase, and in fact, the amplifier must be operated with a closed loop voltage gain of 6 to assure stability.

The effect of R_{SET} on the total quiescent supply current will be very small ($\Delta I_S < 5\% I_S$) as long as R_{SET} is 100k or greater.

To employ electronic shut-down the output bias pin, pin 2, and the negative end of the input bias resistor, R_{SET} , are connected to the negative power supply (or ground in a single power system) through a saturated NPN transistor (or other electronic switch). When the transistor is turned OFF, all of the bias currents inside the op amp are turned OFF and all input and output terminals will float. When first turned ON, the output will take about 5 μs to reach the correct level. To insure that the LM13080 is OFF, leakage in the control device must be below the level that will allow pins 2 and 7 to rise to within 0.4V of V^+ .

Power supply rejection is a function of the change in voltage across the input bias resistor, R_{SET} . To improve the PSRR of the LM13080, the user must be careful to bypass pin 7 to pin 6 or to establish a floating voltage referenced to the positive power supply to serve as a connection point for R_{SET} . In applications where PSRR is important, it is imperative that a supply bypass capacitor(s) be used.

Because the LM13080 is a power op amp, some amount of die heating should be expected. The curve of open loop frequency response shows the effect of thermal feedback on low frequency signals as the output load is increased.

Typical Applications

LINE DRIVER

The line driver circuit in *Figure 1* is able to accept an unbalanced, high impedance input and convert it to a balanced output suitable for driving a low impedance line. This is particularly useful in an environment where magnetically induced hum or noise pickup is a problem. The outputs of the 2 LM13080's are of opposite polarity; therefore, terminating the line with a balanced load (i.e., a differential amplifier or a transformer) will cause common-mode interference pickup to be cancelled.

This circuit will drive a 20 Vp-p signal into a 50Ω load for frequencies up to 10 kHz. Above 10 kHz the output signal is slow rate limited, but the line driver will still supply a 13 Vp-p signal at 20 kHz. The voltage gain of the network is 2, and the low frequency roll-off is determined by:

$$f_L = \frac{1}{2\pi RC}$$

It can be seen that if the load is connected directly between the outputs of the amplifiers, the line driver

becomes a simple bridge amplifier capable of delivering 2W into a 16Ω load.

PIEZOELECTRIC ALARM

The piezoelectric alarm shown in *Figure 2* uses a 3-terminal transducer (Gulton 101FB or equivalent) to produce an 80 dB SPL alarm.

The transducer has a feedback terminal which is connected to the non-inverting input of the LM13080, causing oscillation at the resonant frequency of the piezoelectric crystal. The alarm can be controlled through the use of the electronic shut-down feature of the amplifier. The 100k resistor and 0.1 μF capacitor are used to provide a reference voltage at the inverting input and to keep the duty cycle of the crystal oscillation close to 50%. The RC time constant of this feedback network should be much greater than the time constant of the transducer.

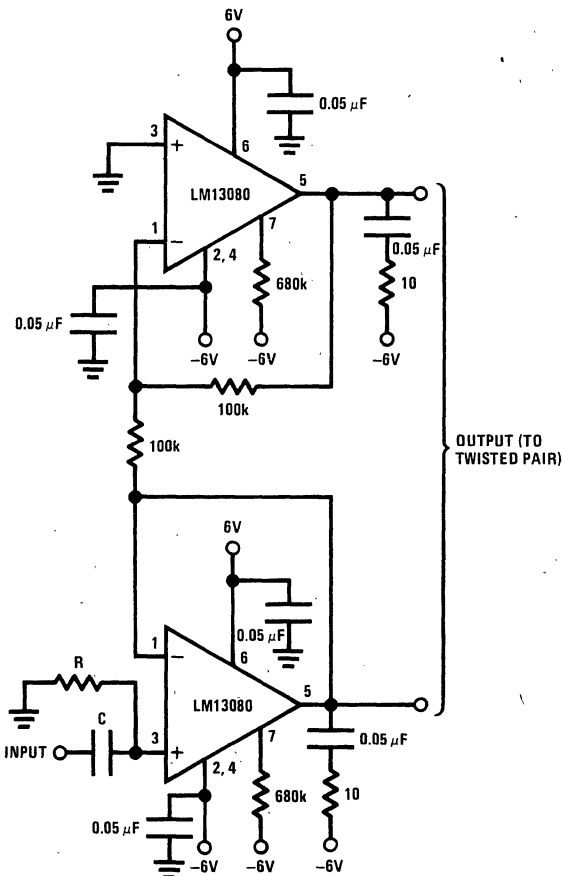


FIGURE 1. Line Driver — Unbalanced Input to Balanced Output

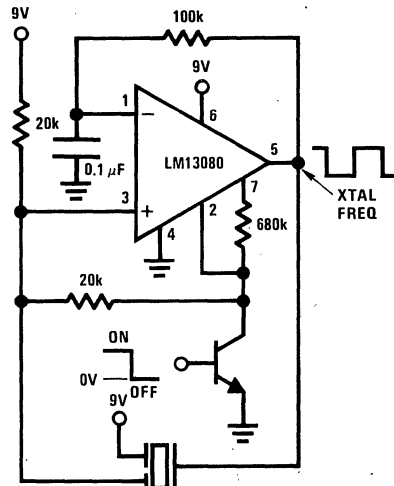


FIGURE 2. Piezoelectric Alarm

Typical Applications (Continued)

SIRENS

Two separate circuits for sirens are shown. The first, *Figure 3*, is a 2-state or ON-OFF type siren where the LM13080 oscillates at an audio frequency and drives an 8Ω speaker and the LM339 acts as a switch which controls the audio burst rate. The second siren, *Figure 4*, provides a constant audio output but alternates between 2 separate tones. The LM13080 is set to oscillate at one basic frequency and this frequency is changed by adding a 200 kΩ charging resistor in parallel with the feedback resistor, R2.

LAMP FLASHER – RELAY DRIVER

The LM13080 is easily adaptable to such applications as low frequency warning devices. The output of the oscillator is a squarewave that is used to drive lamps or small relays. As shown in *Figure 5*, the circuit alternately flashes 2 incandescent lamps.

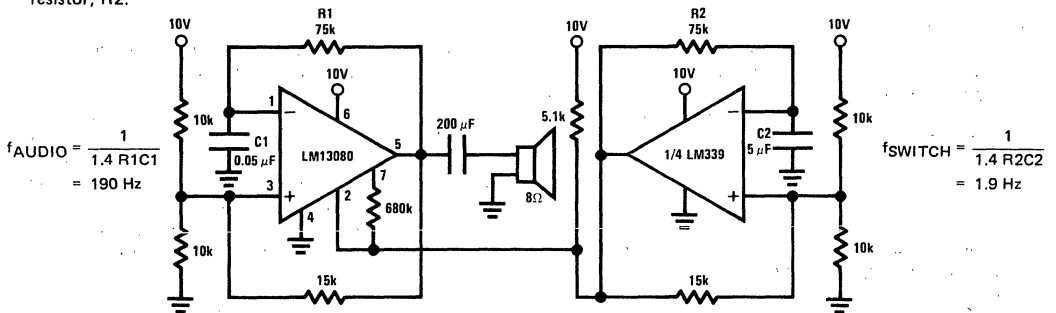


FIGURE 3. 2-State Siren

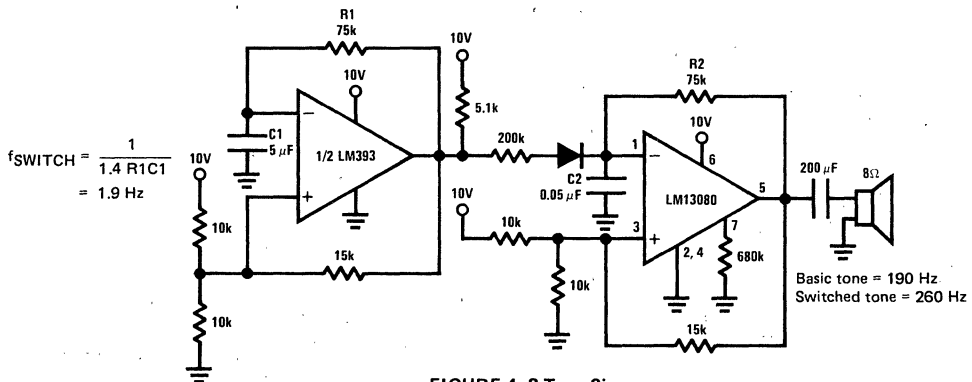


FIGURE 4. 2-Tone Siren

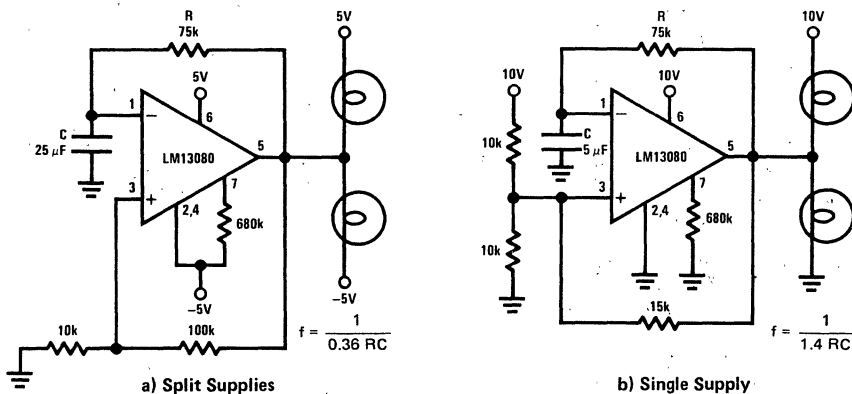


FIGURE 5. Low Frequency Lamp Flasher/Relay Driver

Typical Applications (Continued)

MOTOR SPEED CONTROL

The LM13080 can be used to construct a very simple speed control for small motors requiring less than 0.5A start current. This circuit operates by impressing the multiple of a reference voltage across the motor, and then varying the reference by means of quasi-positive feedback to change the voltage across the motor any time the load on the motor changes.

To understand the circuit operation, it is easiest to let the voltage at the cathode of diode D1, Figure 6, be the input voltage, V_{IN} , to the system. Diode D1 is actually a level shift diode to bring V_{IN} into the common-mode range of the amplifier. A reference voltage is established by the combined voltage drop through the 10Ω potentiometer, R3 and the reference diode, D2 and is applied to the non-inverting input of the LM13080. Resistor R4 is a bias resistor used to keep D2 active. The $10k$ speed adjust potentiometer is 2 resistors in 1, where section R1 is the input resistance and section R2 is the negative feedback resistance. It can be seen that the voltage impressed across the motor is equal to:

$$V_{MOTOR} = \frac{(V_{BE2} + I_3 R_3) R_2}{R_1} + V_{BE}$$

The positive feedback is developed as a change in the voltage across R3 due to the change in the motor current caused by a variation in the motor's load. Resistor R3 is shown as a potentiometer so that the amount of positive feedback can be adjusted for smooth operation of the motor. Capacitor C1 and resistor R5 serve as a filter for the reference voltage at the non-inverting input of the amplifier.

VOLTAGE REGULATORS

In normal, positive or negative regulator application such as those shown in Figure 7 and Figure 8, the LM13080 has 2 major advantages over standard operational amplifiers. The LM13080 has its own on-chip pass device and in addition can either sink or source 250 mA of load current.

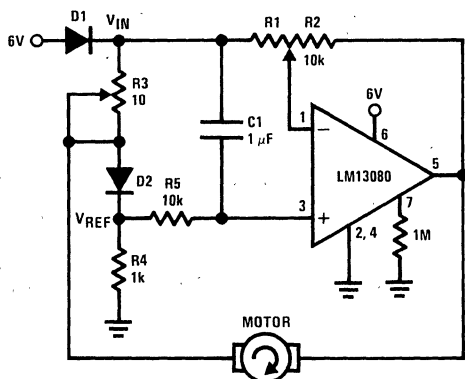
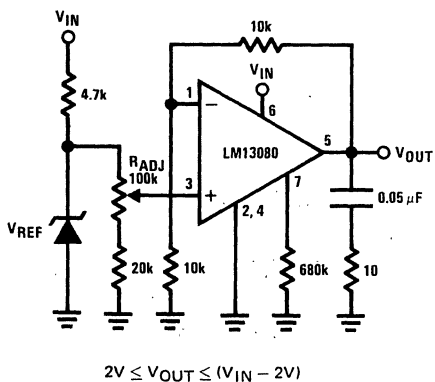
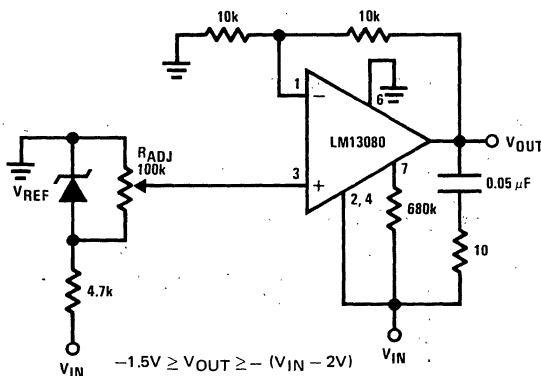


FIGURE 6. Motor Speed Control



$$2V \leq V_{OUT} \leq (V_{IN} - 2V)$$

FIGURE 7. Positive Variable Voltage Regulator



$$-1.5V \geq V_{OUT} \geq -(V_{IN} - 2V)$$

FIGURE 8. Negative Variable Voltage Regulator

LH0002/LH0002C Current Amplifier

general description

The LH0002/LH0002C is a general purpose thick film hybrid current amplifier that is built on a single substrate. The circuit features:

- High Input Impedance 400 k Ω
- Low Output Impedance 6 Ω
- High Power Efficiency
- Low Harmonic Distortion
- DC to 30 MHz Bandwidth
- Output Voltage Swing that Approaches Supply Voltage
- 400 mA Pulsed Output Current
- Slew rate is typically 200V/ μ s
- Operation from $\pm 5V$ to $\pm 20V$

These features make it ideal to integrate with an operational amplifier inside a closed loop configuration to increase current output. The symmetrical

output portion of the circuit also provides a low output impedance for both the positive and negative slopes of output pulses.

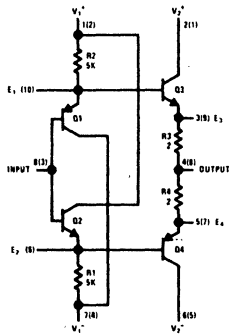
The LH0002 is available in an 8-lead low-profile TO-5 header; the LH0002C is also available in an 8-lead TO-5, and a 10-pin molded dual-in-line package.

The LH0002 is specified for operation over the $-55^{\circ}C$ to $+125^{\circ}C$ military temperature range. The LH0002C is specified for operation over the $0^{\circ}C$ to $+85^{\circ}C$ temperature range.

applications

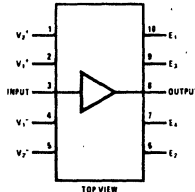
- Line driver
- 30 MHz buffer
- High speed D/A conversion
- Instrumentation buffer
- Precision current source

schematic and connection diagrams



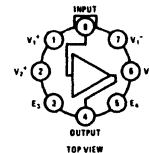
Pin numbers in parentheses denote pin connections for dual-in-line package.

Dual-In-Line Package



Order Number LH0002CN
See Package N10B

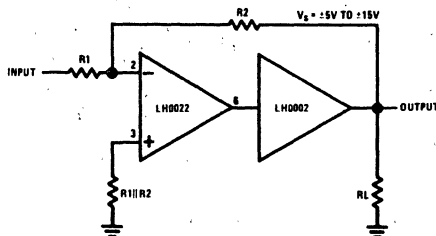
Metal Can Package



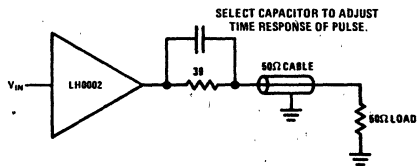
Order Number LH0002H or LH0002CH
See Package H08A

typical applications

High Current Operational Amplifier



Line Driver



*Previously called NH0002/NH0002C

absolute maximum ratings

| | | |
|---|---------|-----------------|
| Supply Voltage | | ±22V |
| Power Dissipation Ambient | | 600 mW |
| Input Voltage (Equal to Power Supply Voltage) | | |
| Storage Temperature Range | | -65°C to +150°C |
| Operating Temperature Range | LH0002 | -55°C to +125°C |
| | LH0002C | 0°C to +85°C |
| Steady State Output Current | | ±100 mA |
| Pulsed Output Current (50 ms On/1 sec Off) | | ±400 mA |

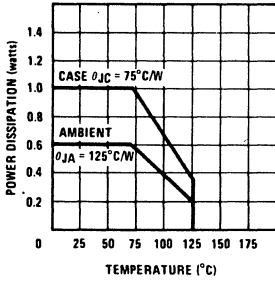
electrical characteristics (Note 1)

| PARAMETERS | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------|---|-------|------|-------|---------------|
| Voltage Gain | $R_S = 10\text{ k}\Omega$, $R_L = 1.0\text{ k}\Omega$ $V_{IN} = 3.0\text{ V}_{PP}$, $f = 1.0\text{ kHz}$ $T_A = -55^\circ\text{C}$ to 125°C | .95 | .97 | | |
| AC Current Gain | $V_{IN} = 1.0\text{ V}_{rms}$ $f = 1.0\text{ kHz}$ | | 40 | | A/mA |
| Input Impedance | $R_S = 200\text{ k}\Omega$, $V_{IN} = 1.0\text{ V}_{rms}$, $f = 1.0\text{ kHz}$, $R_L = 1.0\text{ k}\Omega$ | 180 | 400 | — | k Ω |
| Output Impedance | $V_{IN} = 1.0\text{ V}_{rms}$, $f = 1.0\text{ kHz}$ $R_L = 50\Omega$, $R_S = 10\text{ k}\Omega$ | — | 6 | 10 | Ω |
| Output Voltage Swing | $R_L = 1.0\text{ k}\Omega$, $f = 1.0\text{ kHz}$ | ±10 | ±11 | — | V |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $V_{IN} = \pm 10\text{V}$, $R_S \leq 50\Omega$ $R_L = 100\Omega$, $T_A = 25^\circ\text{C}$ | ±9.5V | | | |
| DC Output Offset Voltage | $R_S = 300\Omega$, $R_L = 1.0\text{ k}\Omega$ $T_A = -55^\circ\text{C}$ to 125°C | — | ±10 | ±30 | mV |
| DC Input Offset Current | $R_S = 10\text{ k}\Omega$, $R_L = 1.0\text{ k}\Omega$ $T_A = -55^\circ\text{C}$ to 125°C | — | ±6.0 | ±10 | μA |
| Harmonic Distortion | $V_{IN} = 5.0\text{ V}_{rms}$, $f = 1.0\text{ kHz}$ $R_L = 1\text{ k}$ | — | 0.1 | — | % |
| Rise Time | $R_L = 50\Omega$, $\Delta V_{IN} = 100\text{mV}$ | | 7 | 12 | ns |
| Positive Supply Current | $R_S = 10\text{ k}\Omega$, $R_L = 1\text{ k}\Omega$ | — | +6.0 | +10.0 | mA |
| Negative Supply Current | $R_S = 10\text{ k}\Omega$, $R_L = 1\text{ k}\Omega$ | — | -6.0 | -10.0 | mA |

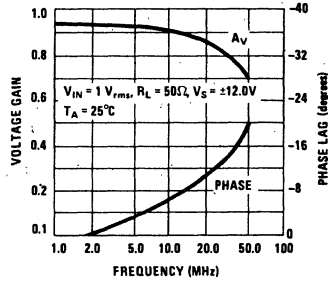
Note 1: Specification applies for $T_A = 25^\circ\text{C}$ with +12V on Pins 1 and 2; -12V on Pins 6 and 7 for the metal can package and +12V on Pins 1 and 2; -12V on Pins 4 and 5 for the dual-in-line package unless otherwise specified. The parameter guarantees for LH0002C apply over the temperature range of 0°C to +85°C, while parameters for the LH0002 are guaranteed over the temperature range -55°C to 125°C.

typical performance

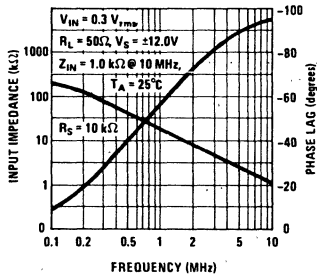
Maximum Power Dissipation



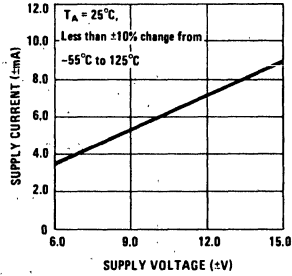
Frequency Response



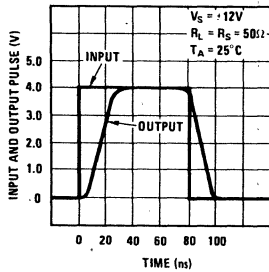
Input Impedance (Magnitude & Phase)



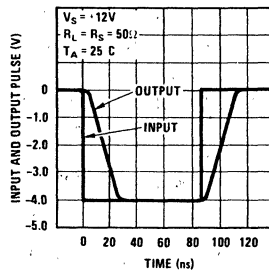
Supply Current



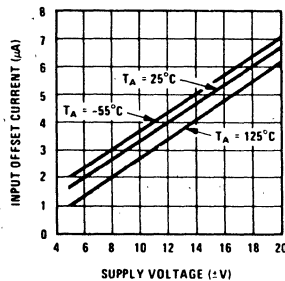
Positive Pulse



Negative Pulse



Input Offset Current



absolute maximum ratings

| | |
|--|--------------------------------|
| Supply Voltage | ±18V |
| Power Dissipation | See curves |
| Differential Input Voltage | ±30V |
| Input Voltage (Note 1) | ±15V |
| Peak Output Current (Note 2) | LH0021/LH0021C 2.0 Amps |
| | LH0041/LH0041C 0.5 Amps |
| Output Short Circuit Duration (Note 3) | Continuous |
| Operating Temperature Range | LH0021/LH0041 -55°C to +125°C |
| | LH0021C/LH0041C -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

dc electrical characteristics for LH0021/LH0021C (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---|---|----------------|-----------|------------|------------|------------|------------|------------------------------|
| | | LH0021 | | | LH0021C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S < 100\Omega, T_C = 25^\circ\text{C}$ $R_S < 100\Omega$ | | 1.0 | 3.0 5.0 | | 3.0 | 6.0 7.5 | mV mV |
| Voltage Drift with Temperature | $R_S < 100\Omega$ | | 3 | 25 | | 5 | 30 | $\mu\text{V}/^\circ\text{C}$ |
| Offset Voltage Drift with Time | | | 5 | | | 5 | | $\mu\text{V}/\text{week}$ |
| Offset Voltage Change with Output Power | | | 5 | 15 | | 5 | 20 | $\mu\text{V}/\text{watt}$ |
| Input Offset Current | $T_C = 25^\circ\text{C}$ | | 30 | 100 300 | | 50 | 200 500 | nA nA |
| Offset Current Drift with Temperature | | | 0.1 | 1.0 | | 0.2 | 1.0 | $\text{nA}/^\circ\text{C}$ |
| Offset Current Drift with Time | | | 2 | | | 2 | | nA/week |
| Input Bias Current | $T_C = 25^\circ\text{C}$ | | 100 | 300 1.0 | | 200 | 500 1.0 | nA μA |
| Input Resistance | $T_C = 25^\circ\text{C}$ | 0.3 | 1.0 | | 0.3 | 1.0 | | M Ω |
| Input Capacitance | | | 3 | | | 3 | | pF |
| Common Mode Rejection Ratio | $R_S < 100\Omega, \Delta V_{CM} = \pm 10\text{V}$ | 70 | 90 | | 70 | 90 | | dB |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±12 | | | ±12 | | | V |
| Power Supply Rejection Ratio | $R_S < 100\Omega, \Delta V_S = \pm 10\text{V}$ | 80 | 96 | | 70 | 90 | | dB |
| Voltage Gain | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ $R_L = 1\text{ k}\Omega, T_C = 25^\circ\text{C}$ $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ $R_L = 100\Omega$ | 100 | 200 | | 100 | 200 | | V/mV V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 100\Omega$ $V_S = \pm 15\text{V}, R_L = 10\Omega, T_C = 25^\circ\text{C}$ | ±13.5 ±11.0 | 14 ±12 | | ±13 ±10 | ±14 ±12 | | V V |
| Output Short Circuit Current | $V_S = \pm 15\text{V}, T_C = 25^\circ\text{C}, R_{SC} = 0.5\Omega$ | 0.8 | 1.2 | 1.6 | 0.8 | 1.2 | 1.6 | Amps |
| Power Supply Current | $V_S = \pm 15\text{V}, V_{OUT} = 0$ | | 2.5 | 3.5 | | 3.0 | 4.0 | mA |
| Power Consumption | $V_S = \pm 15\text{V}, V_{OUT} = 0$ | | 75 | 105 | | 90 | 120 | mW |

ac electrical characteristics for LH0021/LH0021C ($T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}, C_C = 3000\text{ pF}$)

| | | | | | | | | |
|---------------------------------|--|-----|------|-----|-----|------|-----|-------------------|
| Slew Rate | $A_V = +1, R_L = 100\Omega$ | 0.8 | 3.0 | | 1.0 | 3.0 | | V/ μs |
| Power Bandwidth | $R_L = 100\Omega$ | | 20 | | | 20 | | kHz |
| Small Signal Transient Response | | 0.3 | | 1.0 | | 0.3 | 1.5 | μs |
| Small Signal Overshoot | | 5 | | 20 | | 10 | 30 | % |
| Settling Time (0.1%) | $\Delta V_{IN} = 10\text{V}, A_V = +1$ | 4 | | | | 4 | | μs |
| Overload Recovery Time | | 3 | | | | 3 | | μs |
| Harmonic Distortion | $f = 1\text{ kHz}, P_O = 0.5\text{W}$ | | 0.2 | | | 0.2 | | % |
| Input Noise Voltage | $R_C = 50\Omega, \text{B.W.} = 10\text{ Hz to } 10\text{ kHz}$ | | 5 | | | 5 | | $\mu\text{V rms}$ |
| Input Noise Current | $\text{B.W.} = 10\text{ Hz to } 10\text{ kHz}$ | | 0.05 | | | 0.05 | | nA rms |

dc electrical characteristics for LH0041/LH0041C (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---|---|------------|------|------------|------------|------------|------------|------------------------------|
| | | LH0041 | | | LH0041C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S \leq 100\Omega, T_A = 25^\circ\text{C}$ $R_S \leq 100\Omega$ | | 1.0 | 3.0 5.0 | | 3.0 | 6.0 7.5 | mV mV |
| Voltage Drift with Temperature | $R_S \leq 100\Omega$ | | 3 | | | 5 | | $\mu\text{V}/^\circ\text{C}$ |
| Offset Voltage Drift with Time | | | 5 | | | 5 | | $\mu\text{V}/\text{week}$ |
| Offset Voltage Change with Output Power | | | 15 | | | 15 | | $\mu\text{V}/\text{watt}$ |
| Offset Voltage Adjustment Range | (Note 5) | | 20 | | | 20 | | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 30 | 100 300 | | 50 | 200 500 | nA nA |
| Offset Current Drift with Temperature | | | 0.1 | 1.0 | | 0.2 | 1.0 | $\text{nA}/^\circ\text{C}$ |
| Offset Current Drift with Time | | | 2 | | | 2 | | nA/week |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 100 | 300 1.0 | | 200 | 500 1.0 | nA μA |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 0.3 | 1.0 | | 0.3 | 1.0 | | M Ω |
| Input Capacitance | | | 3 | | | 3 | | pF |
| Common Mode Rejection Ratio | $R_S \leq 100\Omega, \Delta V_{CM} = \pm 10\text{V}$ | 70 | 90 | | 70 | 90 | | dB |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ± 12 | | | ± 12 | | | V |
| Power Supply Rejection Ratio | $R_S \leq 100\Omega, \Delta V_S = \pm 10\text{V}$ | 80 | 96 | | 70 | 90 | | dB |
| Voltage Gain | $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ $R_L = 1\text{ k}\Omega, T_A = 25^\circ\text{C}$ $V_S = \pm 15\text{V}, V_O = \pm 10\text{V}$ $R_L = 100\Omega$ | 100 | 200 | | 100 | 200 | | V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 100\Omega$ | ± 13.0 | 14.0 | | ± 13.0 | ± 14.0 | | V |
| Output Short Circuit Current | $V_S = \pm 15\text{V}, T_A = 25^\circ\text{C}$ (Note 6) | | 200 | 300 | | 200 | 300 | mA |
| Power Supply Current | $V_S = \pm 15\text{V}, V_{OUT} = 0$ | | 2.5 | 3.5 | | 3.0 | 4.0 | mA |
| Power Consumption | $V_S = \pm 15\text{V}, V_{OUT} = 0$ | | 75 | 105 | | 90 | 120 | mW |

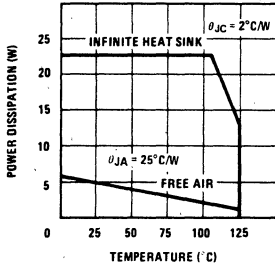
ac electrical characteristics for LH0041/LH0041C ($T_A = 25^\circ\text{C}, V_S = \pm 15\text{V}, C_C = 3000\text{ pF}$)

| | | | | | | | | |
|---------------------------------|--|-----|------|-----|-----|------|-----|--------------------------|
| Slew Rate | $A_V = +1, R_L = 100\Omega$ | 1.5 | 3.0 | | 1.0 | 3.0 | | V/ μs |
| Power Bandwidth | $R_L = 100\Omega$ | | 20 | | | 20 | | kHz |
| Small Signal Transient Response | | | 0.3 | 1.0 | | 0.3 | 1.5 | μs |
| Small Signal Overshoot | | | 5 | 20 | | 10 | 30 | % |
| Settling Time (0.1%) | $\Delta V_{IN} = 10\text{V}, A_V = +1$ | | 4 | | | 4 | | μs |
| Overload Recovery Time | | | 3 | | | 3 | | μs |
| Harmonic Distortion | $f = 1\text{ kHz}, P_O = 0.5\text{W}$ | | 0.2 | | | 0.2 | | % |
| Input Noise Voltage | $R_S = 50\Omega, \text{B.W.} = 10\text{ Hz to } 10\text{ kHz}$ | | 5 | | | 5 | | $\mu\text{V}/\text{rms}$ |
| Input Noise Current | $\text{B.W.} = 10\text{ Hz to } 10\text{ kHz}$ | | 0.05 | | | 0.05 | | nA/rms |

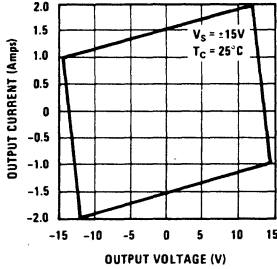
- Note 1:** Rating applies for supply voltages above $\pm 15\text{V}$. For supplies less than $\pm 15\text{V}$, rating is equal to supply voltage.
- Note 2:** Rating applies for LH0041G and LH0021K with $R_{SC} = 0\Omega$.
- Note 3:** Rating applies as long as package power rating is not exceeded.
- Note 4:** Specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$, and $-55^\circ\text{C} \leq T_C \leq 125^\circ\text{C}$ for LH0021K and LH0041G, and $-25^\circ\text{C} \leq T_C \leq +85^\circ\text{C}$ for LH0021CK, LH0041CG and LH0041CJ unless otherwise specified. Typical values are for 25°C only.
- Note 5:** TO-8 "G" packages only.
- Note 6:** Rating applies for "J" DIP package and for TO-8 "G" package with $R_{SC} = 3.3\text{ ohms}$.

typical performance characteristics

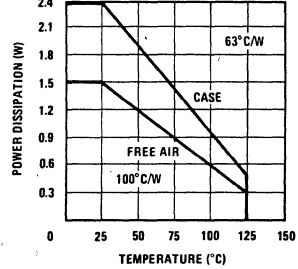
Power Derating-LH0021



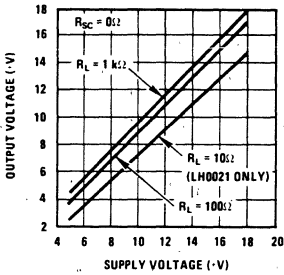
Safe Operating Area - LH0021



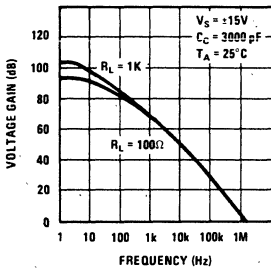
Package Power Dissipation LH0041/LH0041C



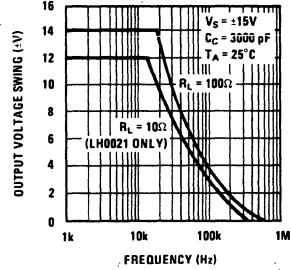
Output Voltage Swing



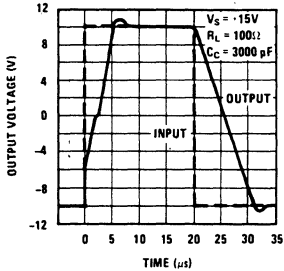
Open Loop Frequency Response



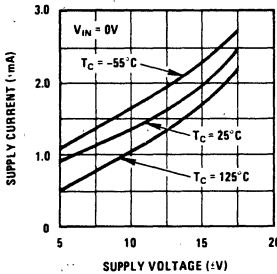
Large Signal Frequency Response



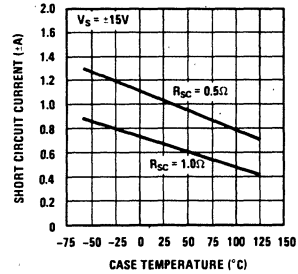
Voltage Follower Pulse Response



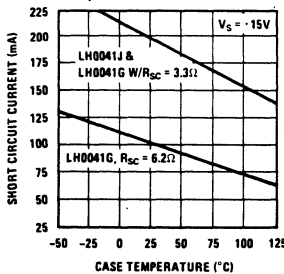
No Load Supply Current



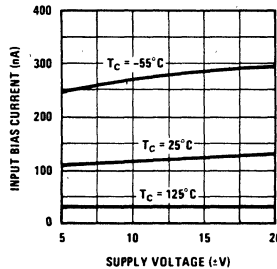
Short Circuit Current vs Temperature LH0021/LH0021C



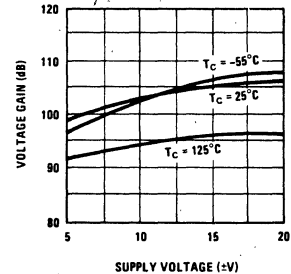
Short Circuit Current vs Temperature LH0041/LH0041C



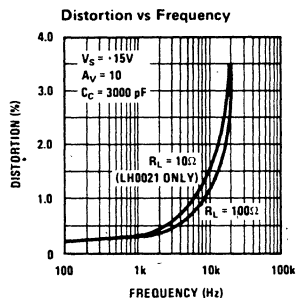
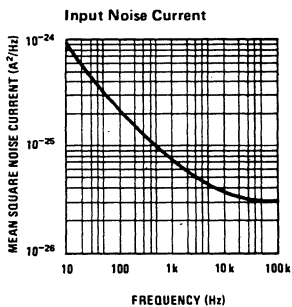
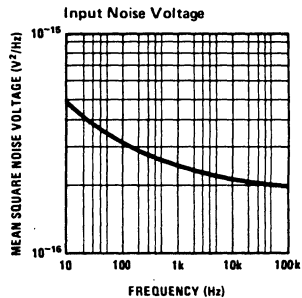
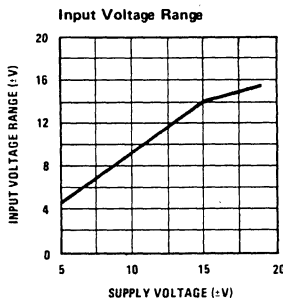
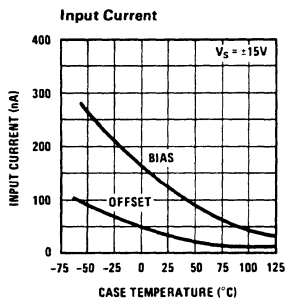
Input Bias Current



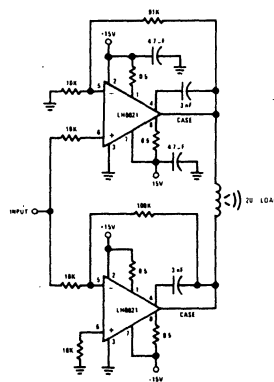
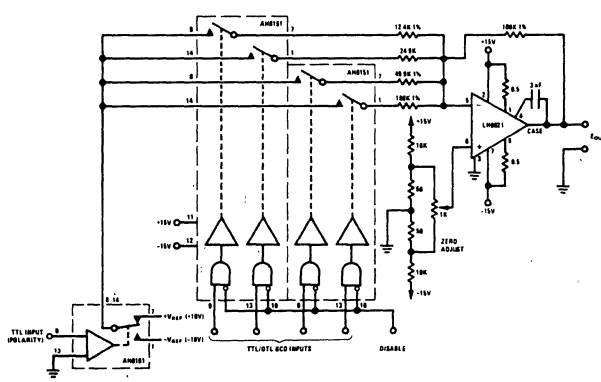
Voltage Gain



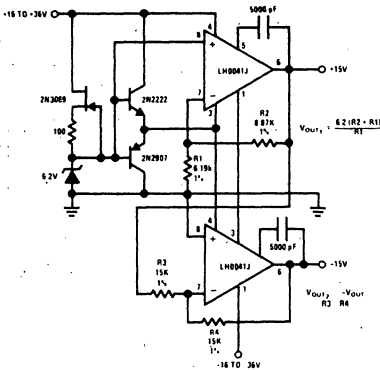
typical performance characteristics (con't)



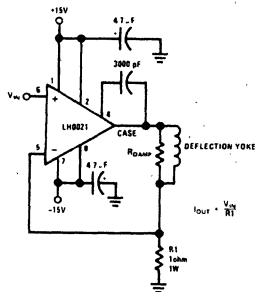
typical applications



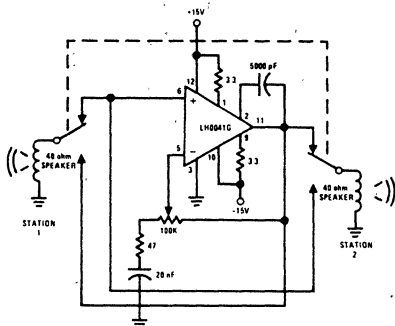
typical applications (con't)



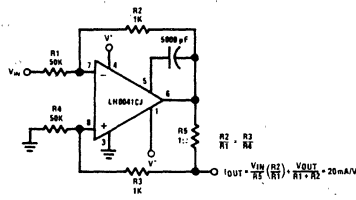
Dual Tracking One Amp Power Supply



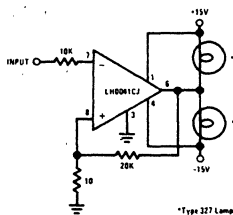
CRT Deflection Yoke Driver



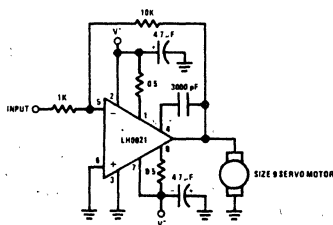
Two Way Intercom



Programmable High Current Source/Sink

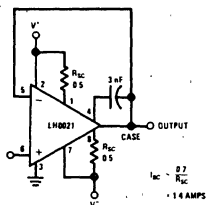


Power Comparator

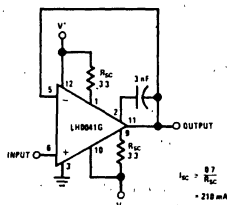


DC Servo Amplifier

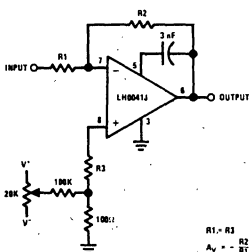
auxiliary circuits



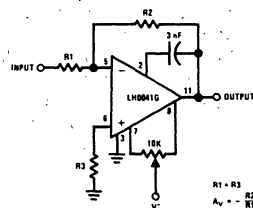
LH0021 Unity Gain Circuit with Short Circuit Limiting



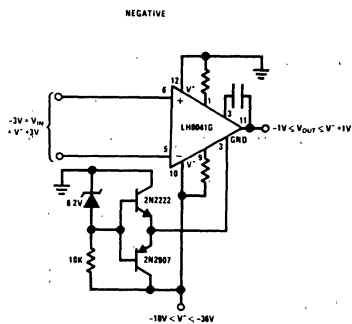
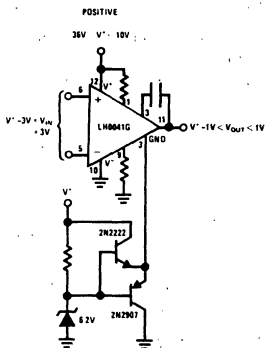
LH0041G Unity Gain with Short Circuit Limiting



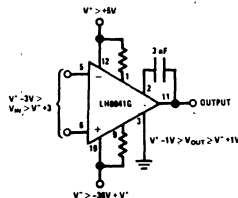
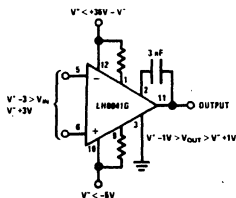
LH0041/LH0021 Offset Voltage Null Circuit (LH0041CJ Pin Connections Shown)*



LH0041G Offset Voltage Null Circuit*



Operation from Single Supplies



Operation from Non-Symmetrical Supplies

*For additional offset null circuit techniques see National Linear Applications Handbook.

LH0022/LH0022C,
LH0042/LH0042C, LH0052/LH0052C



Operational Amplifiers/Buffers

LH0022/LH0022C High Performance FET Op Amp LH0042/LH0042C Low Cost FET Op Amp LH0052/LH0052C Precision FET Op Amp

general description

The LH0022/LH0042/LH0052 are a family of FET input operational amplifiers with very closely matched input characteristics, very high input impedance, and ultra-low input currents with no compromise in noise, common mode rejection ratio, open loop gain, or slew rate. The internally laser nulled LH0052 offers 500 microvolts maximum offset and $5 \mu\text{V}/^\circ\text{C}$ offset drift. Input offset current is less than 500 femtoamps at room temperature and 100 pA maximum at 125°C . The LH0022 and LH0042 are not internally nulled but offer comparable matching characteristics. All devices in the family are internally compensated and are free of latch-up and unusual oscillation problems. The devices may be offset nulled with a single 10k trimpot with negligible effect in CMRR.

The LH0022, LH0042 and LH0052 are specified for operation over the -55°C to $+125^\circ\text{C}$ military temperature range. The LH0022C, LH0042C and LH0052C are specified for operation over the -25°C to $+85^\circ\text{C}$ temperature range.

features

- Low input offset current—500 femtoamps max. (LH0052)

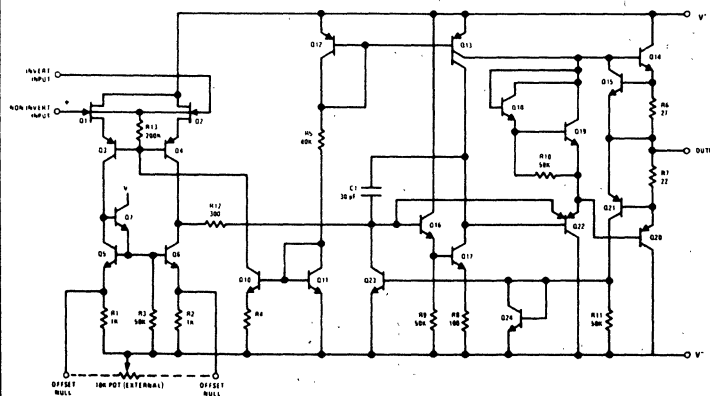
- Low input offset drift— $5 \mu\text{V}/^\circ\text{C}$ max (LH0052)
- Low input offset voltage—100 microvolts-typ.
- High open loop gain—100 dB typ.
- Excellent slew rate— $3.0 \text{ V}/\mu\text{s}$ typ.
- Internal 6 dB/octave frequency compensation
- Pin compatible with standard IC op amps (TO-5 package)

The LH0022/LH0042/LH0052 family of IC op amps are intended to fulfill a wide variety of applications for process control, medical instrumentation, and other systems requiring very low input currents and tightly matched input offsets. The LH0052 is particularly suited for long term high accuracy integrators and high accuracy sample and hold buffer amplifiers. The LH0022 and LH0042 provide low cost high performance for such applications as electrometer and photocell amplification, pico-ammeters, and high input impedance buffers.

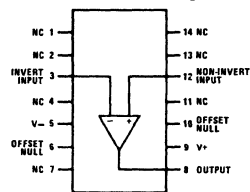
Special electrical parameter selection and custom built circuits are available on special request.

For additional application information and information on other National operational amplifiers, see *Available Linear Applications Literature*.

schematic and connection diagrams

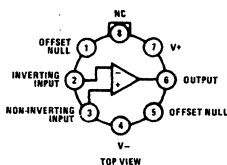


Dual-In-Line Package



Order Number LH0022D,
LH0022CD, LH0042D, LH0042CD,
LH0052D or LH0052CD
See Package D14E

Metal Can Package



Order Number LH0022H, LH0022CH,
LH0042H, LH0042CH,
LH0052H or LH0052CH
See Package H08A

*Previously Called NH0022/NH0022C

absolute maximum ratings

| | |
|--|-----------------|
| Supply Voltage | ±22V |
| Power Dissipation (see graph) | 500 mW |
| Input Voltage (Note 1) | ±15V |
| Differential Input Voltage (Note 2) | ±30V |
| Voltage Between Offset Null and V ⁻ | ±0.5V |
| Short Circuit Duration | Continuous |
| Operating Temperature Range | |
| LH0022, LH0042, LH0052 | -55°C to +125°C |
| LH0022C, LH0042C, LH0052C | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

dc electrical characteristics For LH0022/LH0022C (Note 3)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS | |
|---|---|--------|--------------------|------------------|---------|--------------------|------------------|---------|--|
| | | LH0022 | | | LH0022C | | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | | |
| Input Offset Voltage | R _S ≤ 100 kΩ; T _A = 25°C, V _S = ±15V | | 2.0 | 4.0 | | 3.5 | 6.0 | mV | |
| | R _S ≤ 100 kΩ, V _S = ±15V | | | 5.0 | | | 7.0 | mV | |
| Temperature Coefficient of Input Offset Voltage | R _S ≤ 100 kΩ | | 5 | 10 | | 5 | 15 | μV/°C | |
| Offset Voltage Drift with Time | | | 3 | | | 4 | | μV/week | |
| Input Offset Current | (Note 4) | | 0.2 | 2.0 | | 1.0 | 5.0 | pA | |
| | | | | 2.0 | | | 0.5 | nA | |
| Temperature Coefficient of Input Offset Current | | | Doubles every 10°C | | | Doubles every 10°C | | | |
| Offset Current Drift with Time | | | 0.1 | | | 0.1 | | pA/week | |
| Input Bias Current | (Note 4) | | 5 | 10 | | 10 | 25 | pA | |
| | | | | 10 | | | 2.5 | nA | |
| Temperature Coefficient of Input Bias Current | | | Doubles every 10°C | | | Doubles every 10°C | | | |
| Differential Input Resistance | | | | 10 ¹² | | | 10 ¹² | Ω | |
| Common Mode Input Resistance | | | | 10 ¹² | | | 10 ¹² | Ω | |
| Input Capacitance | | | | 4.0 | | | 4.0 | pF | |
| Input Voltage Range | V _S = ±15V | ±12 | ±13.5 | | ±12 | ±13.5 | | V | |
| Common Mode Rejection Ratio | R _S ≤ 10 kΩ, V _{IN} = ±10V | 80 | 90 | | 70 | 90 | | dB | |
| Supply Voltage Rejection Ratio | R _S ≤ 10 kΩ, ±5V ≤ V _S ≤ ±15V | 80 | 90 | | 70 | 90 | | dB | |
| Large Signal Voltage Gain | R _L = 2 kΩ, V _{OUT} = ±10V, T _A = 25°C, V _S = ±15V | 100 | 200 | | 75 | 160 | | V/mV | |
| | R _L = 2 kΩ, V _{OUT} = ±10V, V _S = ±15V | | 50 | | 50 | | | V/mV | |
| Output Voltage Swing | R _L = 1 kΩ, T _A = 25°C, V _S = ±15V | ±10 | ±12.5 | | ±10 | ±12 | | V | |
| | R _L = 2 kΩ, V _S = ±15V | ±10 | | | ±10 | | | V | |
| Output Current Swing | V _{OUT} = ±10V, T _A = 25°C | ±10 | ±15 | | ±10 | ±15 | | mA | |
| Output Resistance | | | 75 | | | 75 | | Ω | |
| Output Short Circuit Current | | | 25 | | | 25 | | mA | |
| Supply Current | V _S = ±15V | | 2.0 | 2.5 | | 2.4 | 2.8 | mA | |
| Power Consumption | V _S = ±15V | | | 75 | | | 85 | mW | |

dc electrical characteristics for LH0042/LH0042C (Note 3)

($V_S = \pm 15V$, unless otherwise specified)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS | | |
|---|--|----------|----------------------------------|-----|---------|----------------------------------|------------|------------------------------|----------|------|
| | | LH0042 | | | LH0042C | | | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | | | |
| Input Offset Voltage | $R_S \leq 100\text{ k}\Omega$ | | 5.0 | 20 | | 6.0 | 20 | mV | | |
| Temperature Coefficient of Input Offset Voltage | $R_S \leq 100\text{ k}\Omega$ | | 5 | | | 10 | | $\mu\text{V}/^\circ\text{C}$ | | |
| Offset Voltage Drift with Time | | | 7 | | | 10 | | $\mu\text{V}/\text{week}$ | | |
| Input Offset Current | (Note 4) | | 1 | 5 | | 2 | 10 | pA | | |
| Temperature Coefficient of Input Offset Current | | | Doubles every 10°C | | | Doubles every 10°C | | | | |
| Offset Current Drift with Time | | | 0.1 | | | 0.1 | | pA/week | | |
| Input Bias Current | (Note 4) | | 10 | 25 | | 15 | 50 | pA | | |
| Temperature Coefficient of Input Bias Current | | | Doubles every 10°C | | | Doubles every 10°C | | | | |
| Differential Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω | |
| Common Mode Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω | |
| Input Capacitance | | | 4.0 | | | 4.0 | | | pF | |
| Input Voltage Range | | ± 12 | ± 13.5 | | | ± 12 | ± 13.5 | | | V |
| Common Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega, V_{IN} = \pm 10V$ | 70 | 86 | | | 70 | 80 | | | dB |
| Supply Voltage Rejection Ratio | $R_S \leq 10\text{ k}\Omega, \pm 5V \leq V_S \leq \pm 15V$ | 70 | 86 | | | 70 | 80 | | | dB |
| Large Signal Voltage Gain | $R_L = 1\text{ k}\Omega, V_{OUT} = \pm 10V$ | 50 | 150 | | | 25 | 100 | | | V/mV |
| Output Voltage Swing | $R_L = 1\text{ k}\Omega$ | ± 10 | ± 12.5 | | | ± 10 | ± 12 | | | V |
| Output Current Swing | $V_{OUT} = \pm 10V$ | ± 10 | ± 15 | | | ± 10 | ± 15 | | | mA |
| Output Resistance | | | 75 | | | 75 | | | Ω | |
| Output Short Circuit Current | | | 20 | | | 20 | | | mA | |
| Supply Current | | | 2.5 | | | 2.8 | | | 4.0 | mA |
| Power Consumption | | | 105 | | | 120 | | | mW | |

dc electrical characteristics For LH0052/LH0052C (Note 3)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS | | |
|---|--|----------|----------------------------------|-----|---------|----------------------------------|------------|------------------------------|----------|------|
| | | LH0052 | | | LH0052C | | | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | | | |
| Input Offset Voltage | $R_S \leq 100\text{ k}\Omega, V_S = \pm 15V, T_A = 25^\circ\text{C}$ | | 0.1 | 0.5 | | 0.2 | 1.0 | mV | | |
| Temperature Coefficient of Input Offset Voltage | $R_S \leq 100\text{ k}\Omega, V_S = \pm 15V$ | | | 1.0 | | | 1.5 | mV | | |
| Offset Voltage Drift with Time | $R_S \leq 100\text{ k}\Omega, V_S = \pm 15V$ | | 2 | 5 | | 5 | 10 | $\mu\text{V}/^\circ\text{C}$ | | |
| Input Offset Current | (Note 4) | | 0.01 | 0.5 | | 0.02 | 1.0 | pA | | |
| Temperature Coefficient of Input Offset Current | | | Doubles every 10°C | | | Doubles every 10°C | | | | |
| Offset Current Drift with Time | | | < 0.1 | | | < 0.1 | | | pA/week | |
| Input Bias Current | (Note 4) | | 0.5 | 2.5 | | 1.0 | 5.0 | pA | | |
| Temperature Coefficient of Input Bias Current | | | Doubles every 10°C | | | Doubles every 10°C | | | | |
| Differential Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω | |
| Common Mode Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω | |
| Input Capacitance | | | 4.0 | | | 4.0 | | | pF | |
| Input Voltage Range | $V_S = \pm 15V$ | ± 12 | ± 13.5 | | | ± 12 | ± 13.5 | | | V |
| Common Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega, V_{IN} = \pm 10V$ | 74 | 90 | | | 70 | 90 | | | dB |
| Supply Voltage Rejection Ratio | $R_S \leq 10\text{ k}\Omega, \pm 5V \leq V_S \leq \pm 15V$ | 74 | 90 | | | 70 | 90 | | | dB |
| Large Signal Voltage Gain | $R_L = 2\text{ k}\Omega, V_{OUT} = \pm 10V, V_S = \pm 15V, T_A = 25^\circ\text{C}$ | 100 | 200 | | | 75 | 160 | | | V/mV |
| Output Voltage Swing | $R_L = 2\text{ k}\Omega, V_{OUT} = \pm 10V, V_S = \pm 15V$ | 50 | | | | 50 | | | | V/mV |
| Output Current Swing | $R_L = 1\text{ k}\Omega, T_A = 25^\circ\text{C}, V_S = \pm 15V$ | ± 10 | ± 12.5 | | | ± 10 | ± 12 | | | V |
| Output Resistance | $R_L = 2\text{ k}\Omega, V_S = \pm 15V$ | ± 10 | ± 15 | | | ± 10 | ± 15 | | | mA |
| Output Short Circuit Current | $V_{OUT} = \pm 10V, T_A = 25^\circ\text{C}$ | ± 10 | ± 15 | | | ± 10 | ± 15 | | | mA |
| Supply Current | $V_S = \pm 15V$ | | 3.0 | | | 3.0 | | | 3.8 | mA |
| Power Consumption | $V_S = \pm 15V$ | | 105 | | | 114 | | | mW | |

ac electrical characteristics For all amplifiers ($T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|------------------------|--|--------------|-----|-----|-----------------|-----|-----|------------------------------|
| | | LH0022/42/52 | | | LH0022C/42C/52C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Slew Rate | Voltage Follower | 1.5 | 3.0 | | 1.0 | 3.0 | | $\text{V}/\mu\text{s}$ |
| Large Signal Bandwidth | Voltage Follower | | 40 | | | 40 | | kHz |
| Small Signal Bandwidth | | | 1.0 | | | 1.0 | | MHz |
| Rise Time | | | 0.3 | 1.5 | | 0.3 | 1.5 | μs |
| Overshoot | | | 10 | 30 | | 15 | 40 | % |
| Settling Time (0.1%) | $\Delta V_{IN} = 10\text{V}$ | | 4.5 | | | 4.5 | | μs |
| Overload Recovery | | | 4.0 | | | 4.0 | | μs |
| Input Noise Voltage | $R_S = 10\text{ k}\Omega$, $f_o = 10\text{ Hz}$ | | 150 | | | 150 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10\text{ k}\Omega$, $f_o = 100\text{ Hz}$ | | 55 | | | 55 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10\text{ k}\Omega$, $f_o = 1\text{ kHz}$ | | 35 | | | 35 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10\text{ k}\Omega$, $f_o = 10\text{ kHz}$ | | 30 | | | 30 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $\text{BW} = 10\text{ Hz to } 10\text{ kHz}$, $R_S = 10\text{ k}\Omega$ | | 12 | | | 12 | | μVrms |
| Input Noise Current | $\text{BW} = 10\text{ Hz to } 10\text{ kHz}$ | | <.1 | | | <.1 | | pArms |

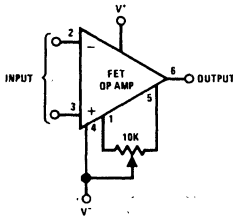
Note 1: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.

Note 2: Rating applies for minimum source resistance of $10\text{ k}\Omega$, for source resistances less than $10\text{ k}\Omega$, maximum differential input voltage is $\pm 5\text{V}$.

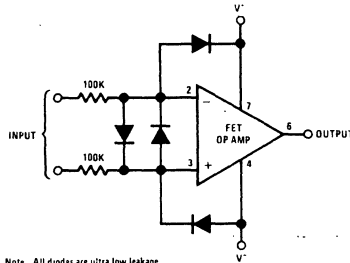
Note 3: Unless otherwise specified, these specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ for the LH0022 and LH0052 and $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ for the LH0022C and LH0052C. Typical values are given for $T_A = 25^\circ\text{C}$.

Note 4: Input currents are a strong function of temperature. Due to high speed testing they are specified at a junction temperature $T_j = 25^\circ\text{C}$, self heating will cause an increase in current in manual tests.

auxiliary circuits (shown for TO-5 pin out)

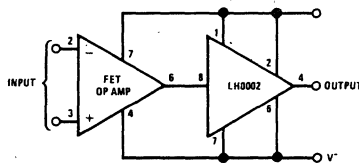


Offset Null



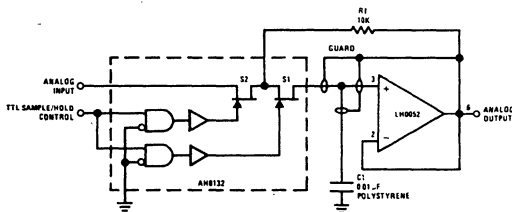
Note: All diodes are ultra low leakage

Protecting Inputs From $\pm 150\text{V}$ Transients

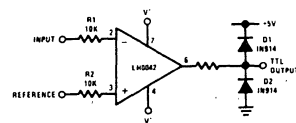


Boosting Output Drive to $\pm 100\text{ mA}$

typical applications

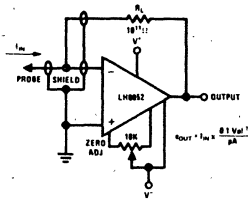


Low Drift Sample and Hold

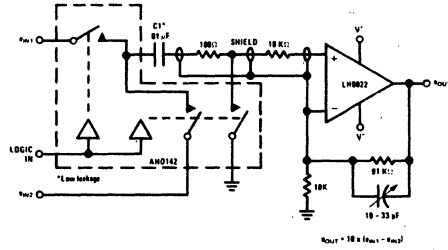


Precision Voltage Comparator

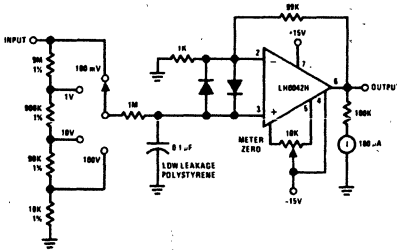
typical applications (con't)



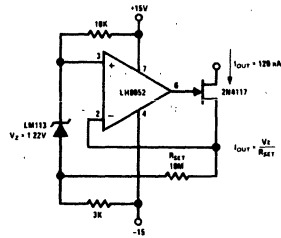
Picoamp Amplifier for pH Meters and Radiation Detectors



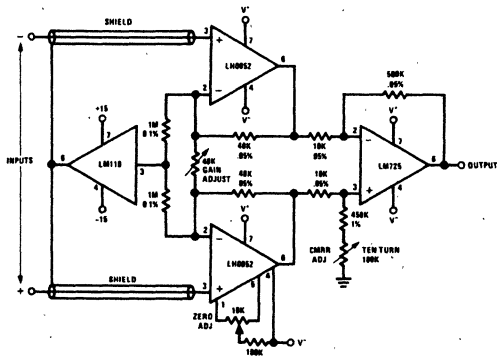
Precision Subtractor for Automatic Test Gear



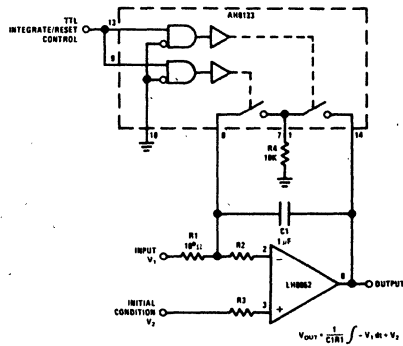
Sensitive Low Cost "VTVM"



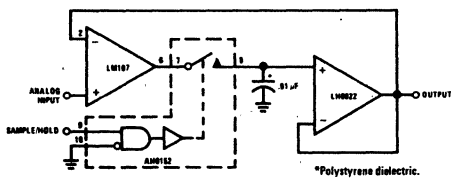
Ultra Low Level Current Source



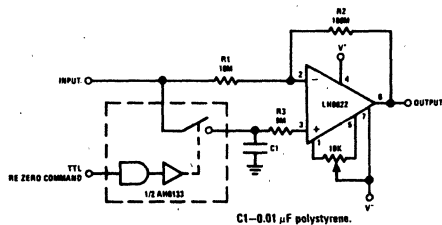
True Instrumentation Amplifier



Precision Integrator

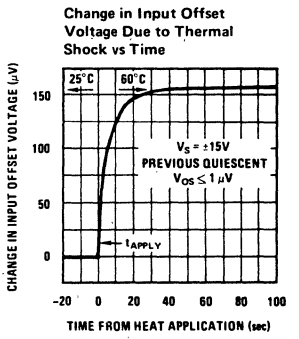
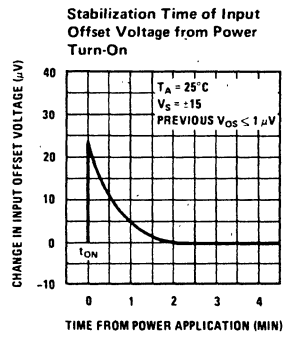
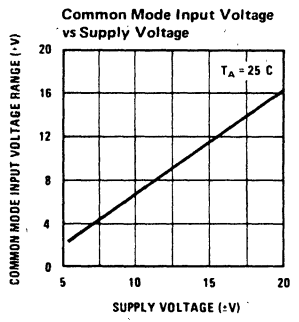
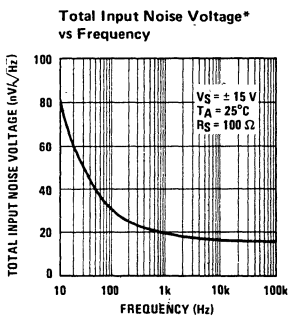
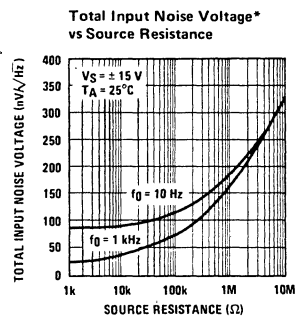
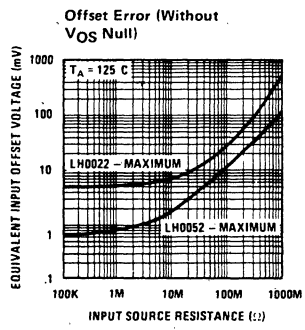
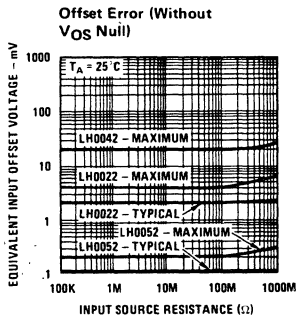
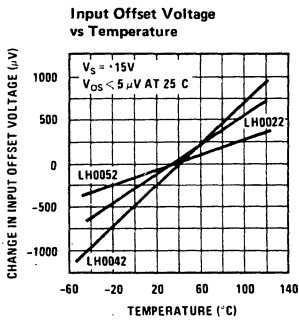
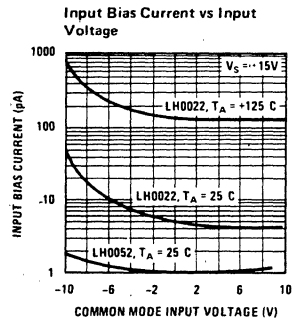
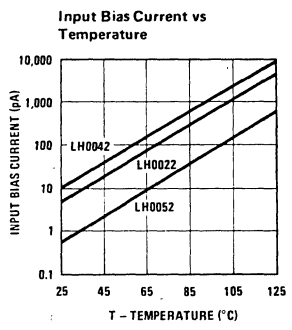
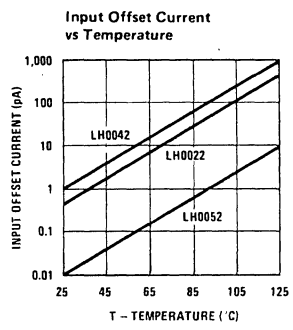
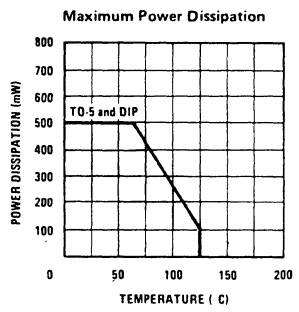


Precision Sample and Hold



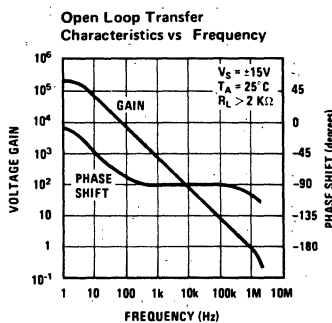
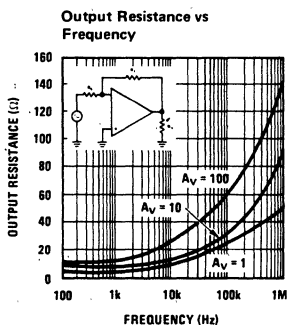
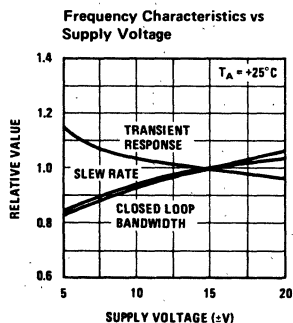
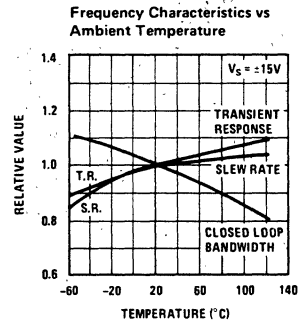
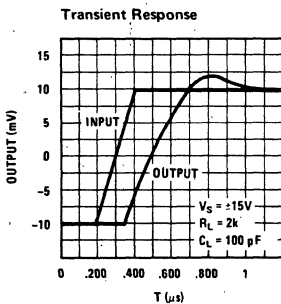
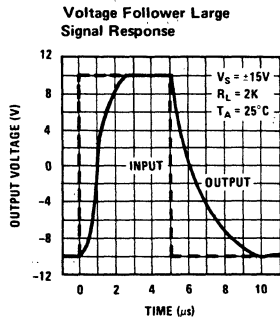
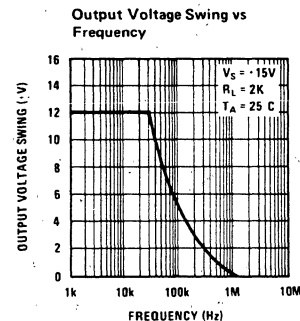
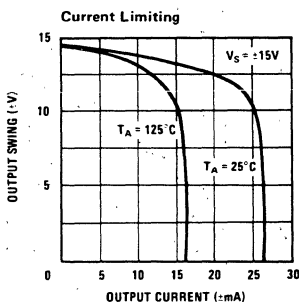
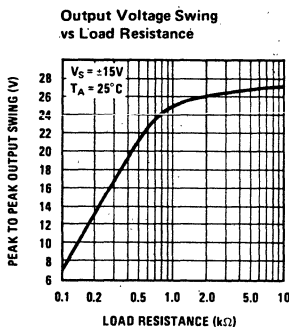
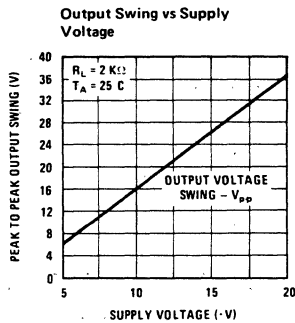
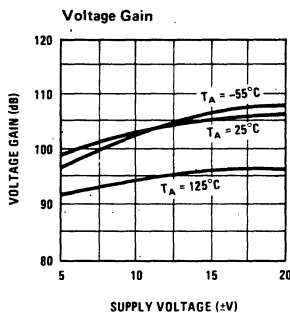
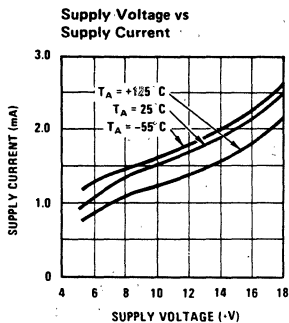
Re-Zeroing Amplifier

typical performance characteristics



*Noise Voltage Includes Contribution from Source Resistance

typical performance characteristics (con't)



LH0024/LH0024C High Slew Rate Operational Amplifier

general description

The LH0024/LH0024C is a very wide bandwidth, high slew rate operational amplifier intended to fulfill a wide variety of high speed applications such as buffers to A to D and D to A converters and high speed comparators. The device exhibits useful gain in excess of 50 MHz making it possible to use in video applications requiring higher gain accuracy than is usually associated with such amplifiers.

- Offset null with single pot
- Low input offset – 2 mV
- Pin compatible with standard IC op amps

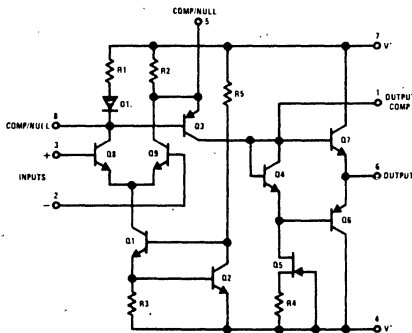
The LH0024/LH0024C's combination of wide bandwidth and high slew rate make it an ideal choice for a variety of high speed applications including active filters, oscillators, and comparators as well as many high speed general purpose applications.

features

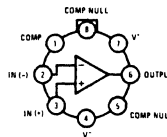
- Very high slew rate – 500 V/ μ s at $A_v = +1$
- Wide small signal bandwidth – 70 MHz
- Wide large signal bandwidth – 15 MHz
- High output swing – $\pm 12V$ into 1K

The LH0024 is guaranteed over the temperature range $-55^{\circ}C$ to $+125^{\circ}C$, whereas the LH0024C is guaranteed $-25^{\circ}C$ to $+85^{\circ}C$.

schematic and connection diagrams



Metal Can Package

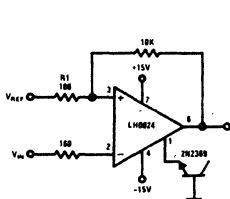


TOP VIEW
Note: For heat sink use
Thermalloy 2230-5 series.

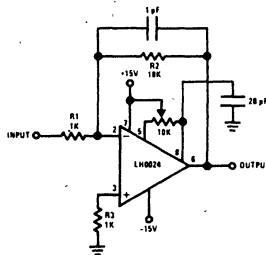
Order Number LH0024H or LH0024CH
See Package H08B

typical applications

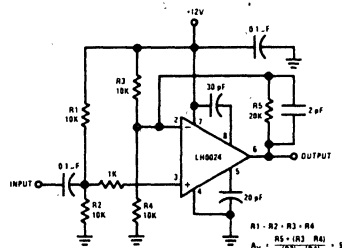
TTL Compatible Comparator



Offset Null



Video Amplifier



R1 - R2 - R3 - R4
R5 - R3 R4
A_v = "TRJ" "TRJ" - 5

absolute maximum ratings

| | | |
|--------------------------------------|---------|-----------------|
| Supply Voltage | | ±18V |
| Input Voltage | | Equal to Supply |
| Differential Input Voltage | | ±5V |
| Power Dissipation | | 600 mW |
| Operating Temperature Range | LH0024 | -55°C to +125°C |
| | LH0024C | -25°C to +85°C |
| Storage Temperature Range | | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | | 300°C |

dc electrical characteristics (Note 1)

| PARAMETER | CONDITIONS | LH0024 | | | LH0024C | | | UNITS |
|---|--|--------|------|------|---------|------|------|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S = 50\Omega, T_A = 25^\circ\text{C}$ | | 2.0 | 4.0 | | 5.0 | 8.0 | mV |
| | $R_S = 50\Omega$ | | | 6.0 | | | 10.0 | mV |
| Average Temperature Coefficient of Input Offset Voltage | $V_S = \pm 15\text{V}, R_S = 50\Omega$ -55°C to 125°C | | -20 | | | -25 | | $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 2.0 | 5.0 | | 4.0 | 15.0 | μA |
| | | | | 10.0 | | | 20.0 | μA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 15 | 30 | | 18 | 40 | μA |
| | | | | 40 | | | 50 | μA |
| Supply Current | | | 12.5 | 15 | | 12.5 | 15 | mA |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}, R_L = 1\text{k}, T_A = 25^\circ\text{C}$ $V_S = \pm 15\text{V}, R_L = 1\text{k}$ | 4 | 5 | | 3 | 4 | | V/mV |
| | | 3 | | | 2.5 | | | V/mV |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ±12 | ±13 | | ±12 | ±13 | | V |
| Output Voltage Swing | $V_S = \pm 15\text{V}, R_L = 1\text{k}, T_A = 25^\circ\text{C}$ $V_S = \pm 15\text{V}, R_L = 1\text{k}$ | ±12 | ±13 | | ±10 | ±13 | | V |
| | | ±10 | | | ±10 | | | V |
| Slew Rate | $V_S = \pm 15\text{V}, R_L = 1\text{k},$ $C_1 = C_2 = 30\text{ pF}$ $A_V = +1, T_A = 25^\circ\text{C}$ | 400 | 500 | | 250 | 400 | | V/ μs |
| Common Mode Rejection Ratio | $V_S = \pm 15\text{V}, \Delta V_{IN} = \pm 10\text{V}$ $R_S = 50\Omega$ | | 60 | | | 60 | | dB |
| Power Supply Rejection Ratio | $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$ $R_S = 50\Omega$ | | 60 | | | 60 | | dB |

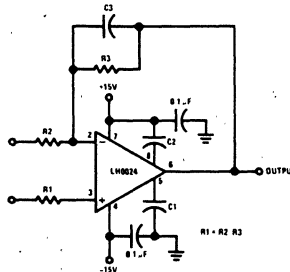
Note 1: These specifications apply for $V_S = \pm 15\text{V}$ and -55°C to $+125^\circ\text{C}$ for the LH0024 and -25°C to $+85^\circ\text{C}$ for the LH0024C.

frequency compensation

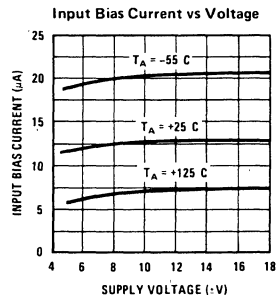
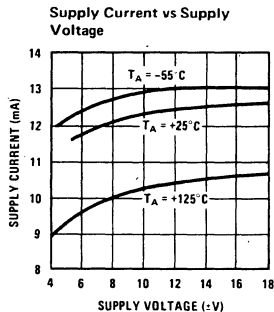
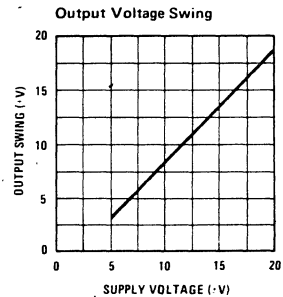
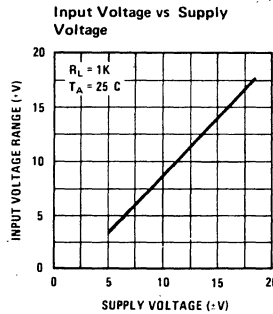
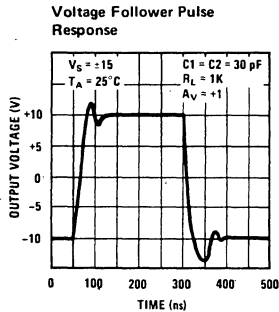
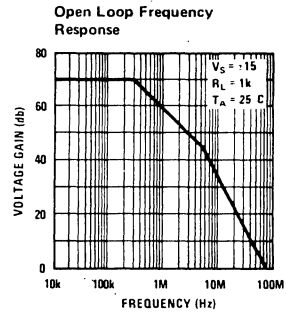
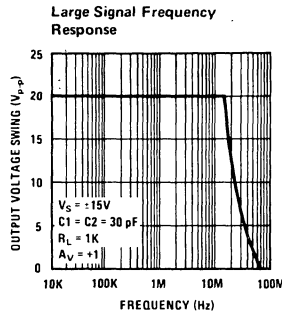
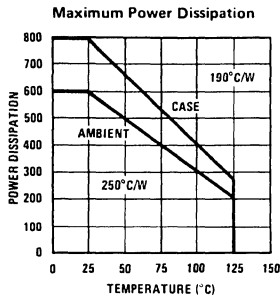
TABLE I

| CLOSED LOOP GAIN | C_1 | C_2 | C_3 |
|------------------|-------|-------|-------|
| 100 | 0 | 0 | 0 |
| 20 | 0 | 0 | 0 |
| 10 | 0 | 20 pF | 1 pF |
| 1 | 30 pF | 30 pF | 3 pF |

Frequency Compensation Circuit



typical performance characteristics



applications information

1. Layout Considerations

The LH0024/LH0024C, like most high speed circuitry, is sensitive to layout and stray capacitance. Power supplies should be by-passed as near the device as is practicable with at least .01 μF disc type capacitors. Compensating capacitors should also be placed as close to device as possible.

2. Compensation Recommendations

Compensation schemes recommended in Table 1 work well under typical conditions. However, poor layout and long lead lengths can degrade the performance of the LH0024 or cause the device to oscillate. Slight adjustments in the values for C1, C2, and C3 may be necessary for a given layout. In particular, when operating at a gain of

-1, C3 may require adjustment in order to perfectly cancel the input capacitance of the device.

When operating the LH0024/LH0024C at a gain of +1, the value of R1 should be at least 1K ohm.

The case of the LH0024 is electrically isolated from the circuit; hence, it may be advantageous to drive the case in order to minimize stray capacitances.

3. Heat Sinking

The LH0024/LH0024C is specified for operation without the use of an explicit heat sink. However, internal power dissipation does cause a significant temperature rise. Improved offset voltage drift can be obtained by limiting the temperature rise with a clip-on heat sink such as the Thermalloy 2228B or equivalent.



Operational Amplifiers/Buffers

LH0032/LH0032C Ultra Fast FET Operational Amplifier

general description

The LH0032/LH0032C is a high slew rate, high input impedance differential operational amplifier suitable for diverse application in fast signal handling. The high allowable differential input voltage, ease of output clamping, and high output drive capability particularly suit it for comparator applications. It may be used in applications normally reserved for video amplifiers allowing the use of operational gain setting and frequency response shaping into the megahertz region.

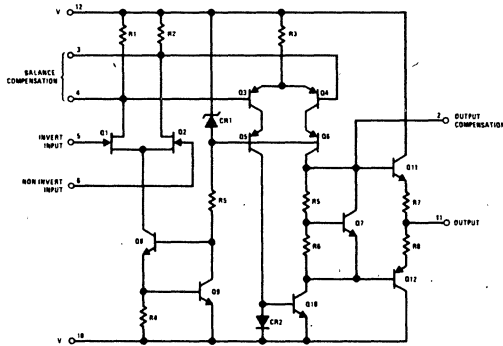
- Low input bias current 20 pA max
- Offset null with single pot
- Low input offset voltage 2 mV max
- No compensation for gains above 50

The LH0032's wide bandwidth, high input impedance and high output capacity make it an ideal choice for applications such as summing amplifiers in high speed D to A's, buffers in data acquisition systems, and sample and hold circuits. Additional applications include high speed integrators and video amplifiers. The LH0032 is guaranteed over the temperature range -55°C to +125°C and the LH0032C is guaranteed from -25°C to +85°C.

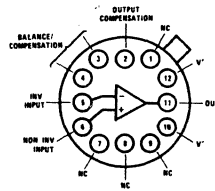
features

- High slew rate 500 V/μs
- High bandwidth 70 MHz
- High input impedance 10¹²Ω

schematic and connection diagrams



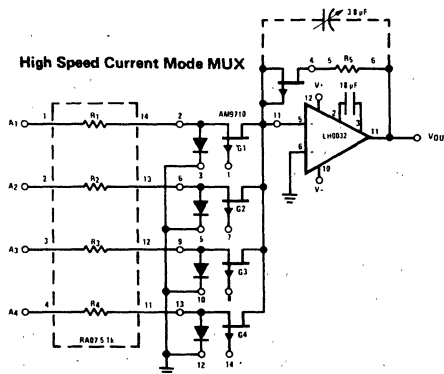
Metal Can Package



TOP VIEW

Note: For best sink use thermally 2248 series or Watfield 215-XX series.

Order Number LH0036G or LH0036CG
See NS Package H12B



absolute maximum ratings

| | |
|--------------------------------------|-----------------|
| Supply Voltage | ±18V |
| Input Voltage | ±V _S |
| Differential Input Voltage | ±30V |
| Power Dissipation | See curve |
| Operating Temperature Range LH0032 | -55°C to +125°C |
| LH0032C | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

dc electrical characteristics (Note 1)

| PARAMETER | CONDITIONS | LH0032 | | | LH0032C | | | UNITS |
|------------------------------|--|--------|-------|-----|---------|-----|------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | T _J = 25°C (Note 3) | | 2 | 5 | | 5 | 15 | mV |
| Average Offset Voltage Drift | | | 25 | 10 | | 25 | 20 | mV |
| Input Bias Current | T _J = 25°C (Note 3) | | 10 | 100 | | 25 | 200 | pA |
| | | | | 50 | | | 15.0 | nA |
| Input Offset Current | T _J = 25°C (Note 3) | | 5 | 25 | | 10 | 50 | pA |
| | | | | 25 | | | 5 | nA |
| Large Signal Voltage Gain | V _{OUT} = ±10V, f = 1 kHz, R _L = 1 kΩ, T _J = 25°C | 60 | 70 | | 60 | 70 | | dB |
| | V _{OUT} = ±10V, f = 1 kHz, R _L = 1 kΩ | 57 | | | 57 | | | dB |
| Input Voltage Range | | ±10 | ±12 | | ±10 | ±12 | | V |
| Output Voltage Swing | R _L = 1 kΩ | ±10 | ±13.5 | | ±10 | ±13 | | V |
| Power Supply Rejection Ratio | ΔV _S = ±10V | 50 | 60 | | 50 | 60 | | dB |
| Common Mode Rejection Ratio | ΔV _{IN} = 10V | 50 | 60 | | 50 | 60 | | dB |
| Supply Current | T _J = 25°C | | 18 | 20 | | 20 | 22 | mA |

3

ac electrical characteristics (Note 2)

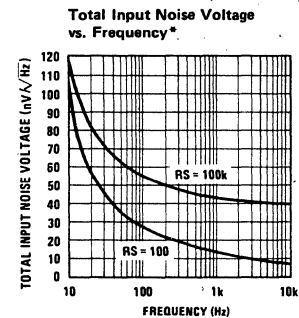
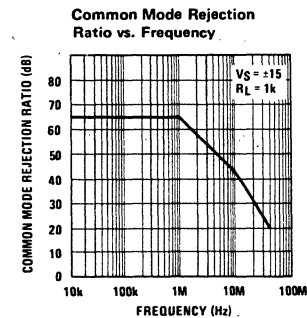
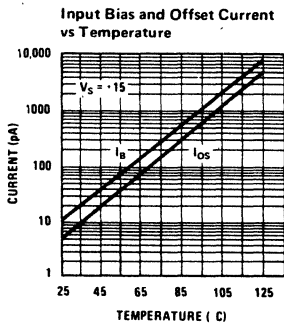
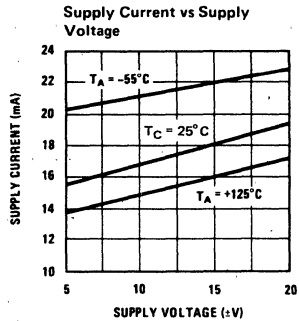
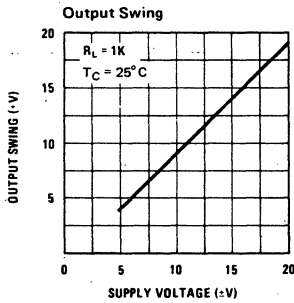
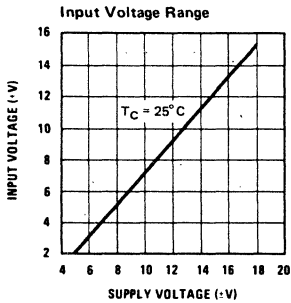
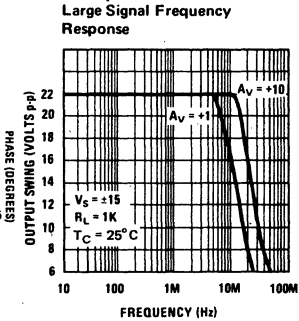
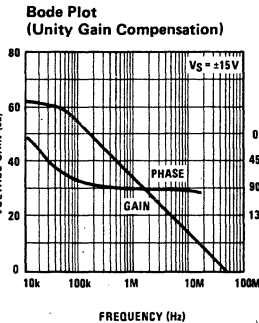
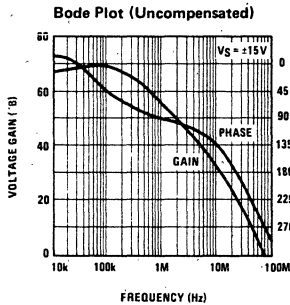
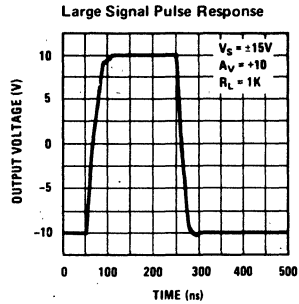
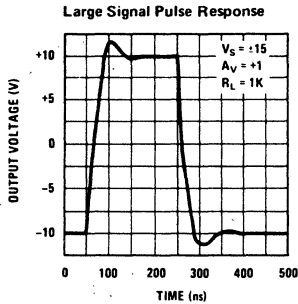
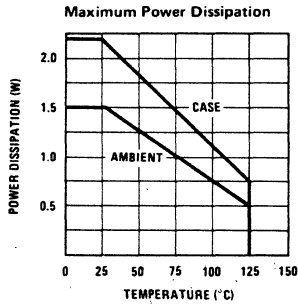
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------------|---|-----|-----|-----|-------|
| Slew Rate | A _V = +1, ΔV _{IN} = 20V | 350 | 500 | | V/μs |
| Settling Time to 1% of Final Value | A _V = -1, ΔV _{IN} = 20V | | 100 | | ns |
| Settling Time to 0.1% of Final Value | A _V = -1, ΔV _{IN} = 20V | | 300 | | ns |
| Small Signal Rise Time | A _V = +1, ΔV _{IN} = 1V | | 8 | 20 | ns |
| Small Signal Delay Time | A _V = +1, ΔV _{IN} = 1V | | 10 | 25 | ns |

Note 1: These specifications apply at V_S = ±15V and over -55°C to +125°C for the LH0032 and -25°C to +85°C for the LH0032C, unless otherwise specified.

Note 2: These specifications apply for V_S = ±15V, R_L = 1 kΩ and T_J = 25°C

Note 3: Due to high speed automatic testing, these parameters are correlated to junction temperature.

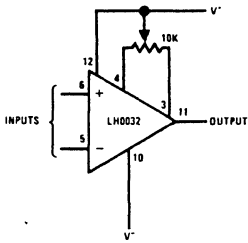
typical performance characteristics (con't)



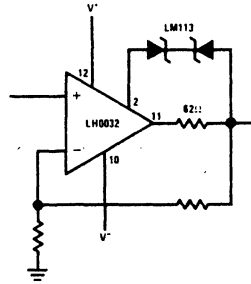
* Noise voltage includes contribution from source resistance.

auxiliary circuits

Offset Null

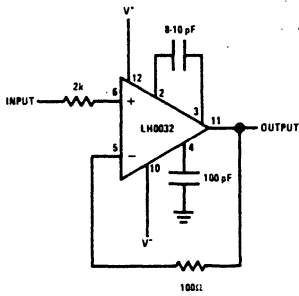


Output Short Circuit Protection

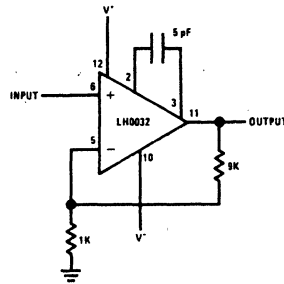


typical applications (con't)

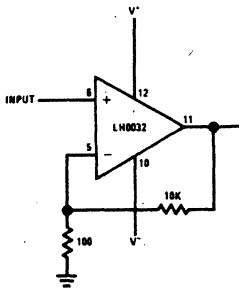
Unity Gain Amplifier



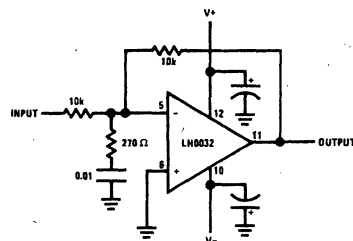
10X Buffer Amplifier



100X Buffer Amplifier

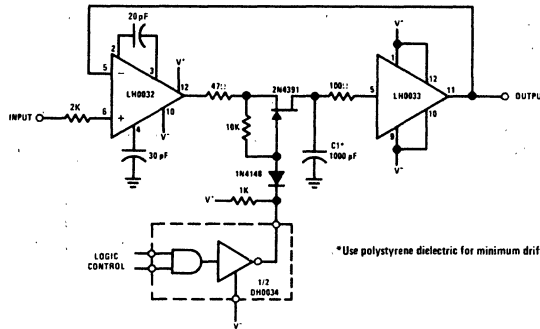


Non-Compensated Unity Gain Inverter

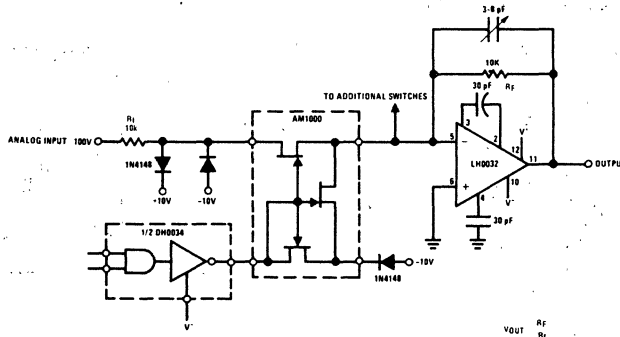


typical applications (con't)

High Speed Sample and Hold



Current Mode Multiplexer



applications information

Power Supply Decoupling

The LH0032/LH0032C like most high speed circuits is sensitive to layout and stray capacitance. Power supplies should be by-passed as near to Pins 10 and 12 as practicable with low inductance capacitors such as 0.01 μF disc ceramics. Compensation components should also be located close to the appropriate pins to minimize stray reactances.

Input Capacitance

The input capacitance to the LH0032/LH0032C is typically 5 pF and thus may form a significant time constant with high value resistors. For optimum performance, the input capacitance to the inverting input should be compensated by a small capacitor across the feedback resistor. The value is strongly dependent on layout and closed loop gain, but will typically be in the neighborhood of several picofarads.

In the non-inverting configuration, it may be advantageous to bootstrap the case and/or a guard conductor to the inverting input. This serves both to divert leakage currents away from the non-inverting input and to reduce the effective input capacitance. A unity gain follower so treated will have an input capacitance under a picofarad.

Heat Sinking

While the LH0032/LH0032C is specified for operation without any explicit heat sink, internal power dissipation does cause a significant temperature rise. Improved bias current performance can thus be obtained by limiting this temperature rise with a small head sink such as the Thermalloy No. 2241 or equivalent. The case of the device has no internal connection, so it may be electrically connected to the sink if this is advantageous. Be aware, however, that this will affect the stray capacitances to all pins and may thus require adjustment of circuit compensation values.

LH0033/LH0033C, LH0063/LH0063C Fast and Damn Fast Buffer Amplifiers

general description

The LH0033/LH0033C and LH0063/LH0063C are high speed, FET input, voltage follower/buffers designed to provide high current drive at frequencies from DC to over 100 MHz. The LH0033/LH0033C will provide ± 10 mA into 1 k Ω loads (± 100 mA peak) at slew rates of 1500V/ μ s. The LH0063/LH0063C will provide ± 250 mA into 50 Ω loads (± 500 mA peak) at slew rates of up to 6000V/ μ s. In addition, both exhibit excellent phase linearity up to 20 MHz.

Both are intended to fulfill a wide range of buffer applications such as high speed line drivers, video impedance transformation, nuclear instrumentation amplifiers, op amp isolation buffer for driving reactive loads and high impedance input buffers for high speed A to D's and comparators. In addition, the LH0063/LH0063C can continuously drive 50 Ω coaxial cables or be used as a diddle yoke driver for high resolution CRT displays. For additional applications information, see AN-48.

advantages

- Only +10V supply needed for 5 V_{P-P} video out
- Speed does not degrade system performance
- Wide data rate range for phase encoded systems

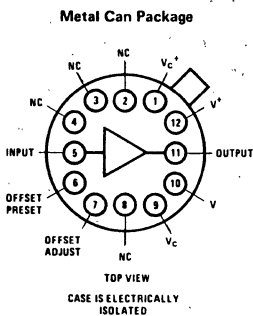
- Output drive adequate for most loads
- Single pre-calibrated package

features

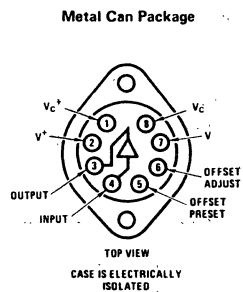
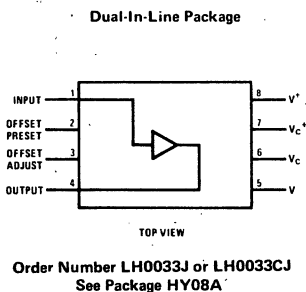
- Damn fast (LH0063) 6000V/ μ s
- Wide range single or dual supply operation
- Wide power bandwidth DC to 100 MHz
- High output drive ± 10 V with 50 Ω load
- Low phase non-linearity 2 degrees
- Fast rise times 2 ns
- High current gain 120 dB
- High input resistance 10^{10} Ω

These devices are constructed using specially selected junction FET's and active laser trimming to achieve guaranteed performance specifications. The LH0033 and LH0063 are specified for operation from -55°C to $+125^{\circ}\text{C}$; whereas, the LH0033C and LH0063C are specified from -25°C to $+85^{\circ}\text{C}$. The LH0033/LH0033C is available in a 1.5W metal TO-8 package and a special 1/2 x 1 inch 8 pin ceramic dual-in-line package while the LH0063/LH0063C is available in a 5W 8-pin TO-3 package.

connection diagrams



Order Number LH0033G or LH0033C
See Package H12B



Order Number LH0063K or LH0063CK
See Package K08A

absolute maximum ratings

| | | | | |
|--|----------------------------------|---------------------|--------------------------------------|--|
| Supply Voltage (V^+ , V^-) | 40V | Peak Output Current | LH0063/LH0063C LH0033/LH0033C | ±500 mA ±250 mA |
| Maximum Power Dissipation (See Curves) | LH0063/LH0063C LH0033/LH0033C | 5W 1.5W | Operating Temperature Range | LH0033 and LH0063 LH0033C and LH0063C |
| Maximum Junction Temperature | 175°C | | Storage Temperature Range | -55°C to +125°C -25°C to +85°C |
| Input Voltage | Equal to Supplies | | Lead Temperature (Soldering, 10 sec) | -65°C to +150°C 300°C |
| Continuous Output Current | LH0063/LH0063C LH0033/LH0033C | ±250 mA ±100 mA | | |

dc electrical characteristics LH0033/LH0033C: (Note 1)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---|--|-----------|------------|----------|-----------|------------|--------------------|------------------------------|
| | | LH0033 | | | LH0033C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Output Offset Voltage | $R_S = 100\text{ k}\Omega$, $T_C = 25^\circ\text{C}$ $R_S = 100\text{ k}\Omega$ | | 5 | 10 15 | | 12 | 20 25 | mV mV |
| Average Temperature Coefficient of Offset Voltage | $R_S = 100\text{ k}\Omega$, $-55^\circ\text{C} \leq T_C \leq 125^\circ\text{C}$ | | 50 | | | 50 | | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current | $T_C = 25^\circ\text{C}$ | | .05 | .1 10 | | .05 | .15 5 | nA nA |
| Voltage Gain | $V_{IN} = 1\text{V}_{rms}$, $f = 1\text{ kHz}$, $R_L = 1\text{ k}\Omega$, $R_S = 100\text{ k}\Omega$ | .97 | .98 | 1 | .96 | .98 | 1 | V/V |
| Input Impedance | $R_L = 1\text{ k}\Omega$ | 10^{10} | 10^{11} | | 10^{10} | 10^{11} | | Ω |
| Output Impedance | $V_{IN} = 1\text{V}_{rms}$, $f = 1\text{ kHz}$, $R_S = 100\text{ k}\Omega$, $R_L = 1\text{ k}\Omega$ | | 6 | 10 | | 6 | 10 | Ω |
| Output Voltage Swing | $R_L = 1\text{ k}\Omega$, $R_L = 100\Omega$, $T_C = 25^\circ\text{C}$ $V_S = \pm 5\text{V}$, $R_L = 1\text{ k}\Omega$ | ±12 ±9 | ±13 6 | | ±12 ±9 | ±13 6 | V V V_{PP} | |
| Supply Current | $V_{IN} = 0\text{V}$, $V_S = \pm 15\text{V}$ $V_S = \pm 5\text{V}$ | | 20 18 | 22 | | 21 18 | 24 | mA mA |
| Power Consumption | $V_{IN} = 0\text{V}$, $V_S = \pm 15\text{V}$ $V_S = \pm 5\text{V}$ | | 600 180 | 660 | | 630 180 | 720 | mW mW |

ac electrical characteristics

LH0033/LH0033C ($T_C = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $R_S = 50\Omega$, $R_L = 1\text{ k}\Omega$)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---------------------|-------------------------------|--------|------|-----|---------|------|-----|------------------|
| | | LH0033 | | | LH0033C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Slew Rate | $V_{IN} = \pm 10\text{V}$ | 1000 | 1500 | | 1000 | 1400 | | V/ μs |
| Bandwidth | $V_{IN} = 1\text{V}_{rms}$ | | 100 | | | 100 | | MHz |
| Phase Non-Linearity | $BW = 1$ to 20 MHz | | 2 | | | 2 | | degrees |
| Rise Time | $\Delta V_{IN} = 0.5\text{V}$ | | 2.9 | | | 3.2 | | ns |
| Propagation Delay | $\Delta V_{IN} = 0.5\text{V}$ | | 1.2 | | | 1.5 | | ns |
| Harmonic Distortion | $f > 1\text{ kHz}$ | | <0.1 | | | <0.1 | | % |

Note 1: Unless otherwise specified, these specifications apply for +15V applied to pins 1 and 12, -15V applied to pins 9 and 10, and pin 6 shorted to pin 7 for the LH0033/LH0033C. For the LH0063/LH0063C, specifications apply for +15V applied to pins 1 and 2, -15V applied to pins 7 and 8, and pin 5 shorted to pin 6. Unless otherwise noted, specifications apply over a temperature range of $-55^\circ\text{C} \leq T_C \leq +125^\circ\text{C}$ for the LH0033 and LH0063; and $-25^\circ\text{C} \leq T_C \leq +85^\circ\text{C}$ for the LH0033C and LH0063C. Typical values shown are for $T_C = 25^\circ\text{C}$.

dc electrical characteristics LH0063/LH0063C (Note 1)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|--|--|-----------|-----------|------|-----------|-----------|------|------------------------------|
| | | LH0063 | | | LH0063C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Output Offset Voltage | $R_S \leq 100\text{ k}\Omega$, $T_C = 25^\circ\text{C}$ $R_S \leq 100\text{ k}\Omega$ | | 10 | 25 | | 10 | 50 | mV mV |
| Average Temperature Coefficient of Output Offset Voltage | $R_S \leq 100\text{ k}\Omega$ | | 300 | | | 300 | | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current | $T_J = 25^\circ\text{C}$ | | .1 | -5 | | .1 | -5 | nA nA |
| Voltage Gain | $V_{IN} = \pm 10\text{V}$, $R_S \leq 100\text{ k}\Omega$, $R_L = 1\text{ k}\Omega$ | .94 | .96 | 1 | .94 | .96 | 1 | V/V |
| Voltage Gain | $V_{IN} = \pm 10\text{V}$, $R_S \leq 100\text{ k}\Omega$, $R_L = 50\Omega$, $T_C = 25^\circ\text{C}$ | .92 | .93 | .98 | .91 | .93 | .98 | V/V |
| Input Resistance | | 10^{10} | 10^{11} | | 10^{10} | 10^{11} | | Ω |
| Input Capacitance | Case Shorted to Output | | 8 | | | 8 | | pF |
| Output Impedance | $V_{OUT} = \pm 10\text{V}$, $R_S = 100\text{ k}\Omega$, $R_L = 50\Omega$ | | 1 | 4 | | 1 | 4 | Ω |
| Output Current Swing | $V_{IN} = \pm 10\text{V}$, $R_S \leq 100\text{ k}\Omega$ | .2 | .25 | | .2 | .25 | | Amps |
| Output Voltage Swing | $R_L = 50\Omega$ | ± 10 | ± 13 | | ± 10 | ± 13 | | V |
| Output Voltage Swing | $V_S = \pm 5\text{V}$, $R_L = 50\Omega$, $T_C = 25^\circ\text{C}$ | 5 | 7 | | 5 | 7 | | $V_{p,p}$ |
| Supply Current | $T_C = 25^\circ\text{C}$, $R_L = \infty$, $V_S = \pm 15\text{V}$ | | 35 | 65 | | 35 | 65 | mA |
| Supply Current | $V_S = \pm 5\text{V}$ | | 50 | | | 50 | | mA |
| Power Consumption | $T_C = 25^\circ\text{C}$, $R_L = \infty$, $V_S = \pm 15\text{V}$ | | 1.05 | 1.95 | | 1.05 | 1.95 | W |
| Power Consumption | $V_S = \pm 5\text{V}$ | | 500 | | | 500 | | mW |

ac electrical characteristics

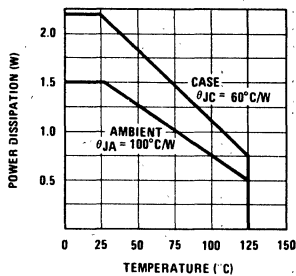
LH0063/LH0063C: ($T_C = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $R_S = 50\Omega$, $R_L = 50\Omega$)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---------------------|--|--------|------|-----|---------|------|-----|------------------|
| | | LH0063 | | | LH0063C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Slew Rate | $R_L = 1\text{ k}\Omega$, $V_{IN} = \pm 10\text{V}$ | | 6000 | | | 6000 | | V/ μs |
| Slew Rate | $R_L = 50\Omega$, $V_{IN} = \pm 10\text{V}$, $T_C = 25^\circ\text{C}$ | 2000 | 2400 | | 2000 | 2400 | | V/ μs |
| Bandwidth | $V_{IN} = 1\text{ V}_{rms}$ | | 200 | | | 200 | | MHz |
| Phase Non-Linearity | BW = 1 to 20 MHz | | 2 | | | 2 | | degrees |
| Rise Time | $\Delta V_{IN} = .5\text{V}$ | | 1.6 | | | 1.9 | | ns |
| Propagation Delay | $\Delta V_{IN} = .5\text{V}$ | | 1.9 | | | 2.1 | | ns |
| Harmonic Distortion | | | <0.1 | | | <0.1 | | % |

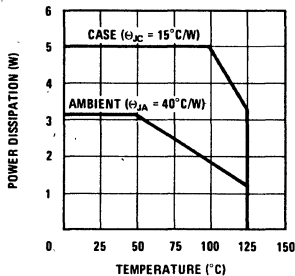
Note 1: Unless otherwise specified, these specifications apply for +15V applied to pins 1 and 12, -15V applied to pins 9 and 10, and pin 6 shorted to pin 7 for the LH0033/LH0033C. For the LH0063/LH0063C, specifications apply for +15V applied to pins 1 and 2, -15V applied to pins 7 and 8, and pin 5 shorted to pin 6. Unless otherwise noted, specifications apply over a temperature range of $-55^\circ\text{C} \leq T_C \leq +125^\circ\text{C}$ for the LH0033 and LH0063; and $-25^\circ\text{C} \leq T_C \leq +85^\circ\text{C}$ for the LH0033C and LH0063C. Typical values shown are for $T_C = 25^\circ\text{C}$.

typical performance characteristics

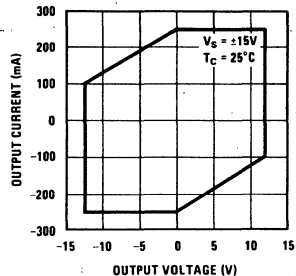
LH0033 Power Dissipation



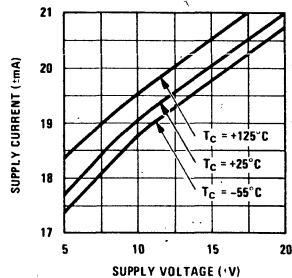
LH0063 Power Dissipation



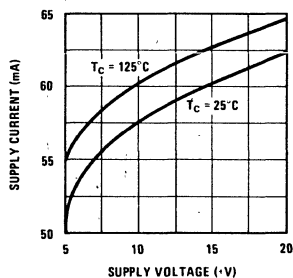
LH0063 DC Safe Operating Area



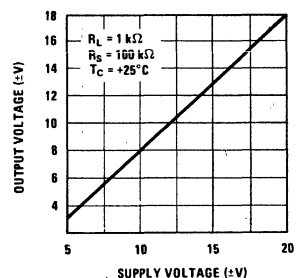
LH0033 Supply Current vs Supply Voltage



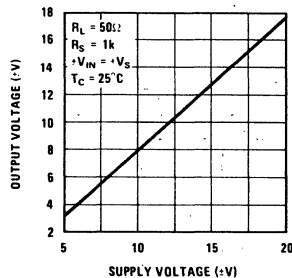
LH0063 Supply Current vs Supply Voltage



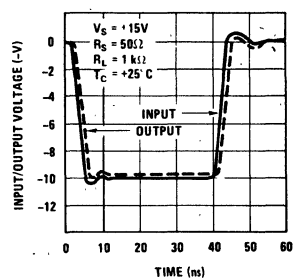
LH0033 Output Voltage vs Supply Voltage



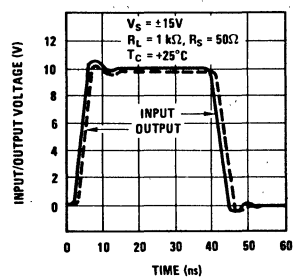
LH0063 Output Voltage vs Supply Voltage



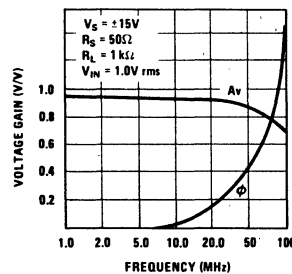
LH0033 Negative Pulse Response



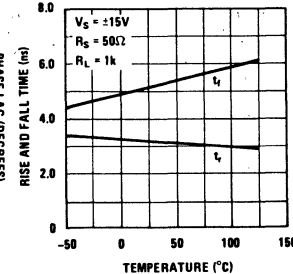
LH0033 Positive Pulse Response



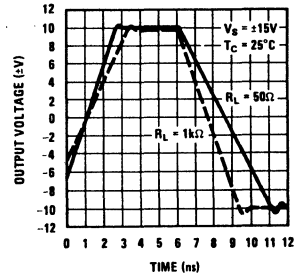
LH0033 Frequency Response



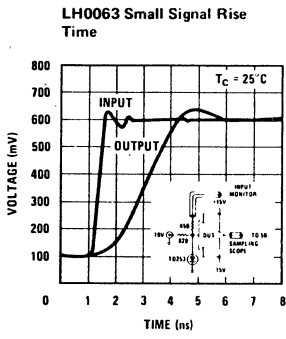
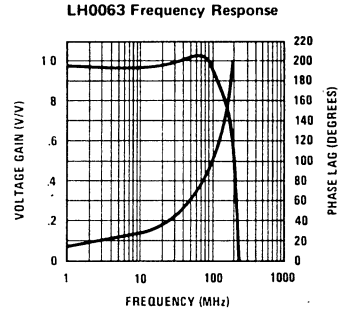
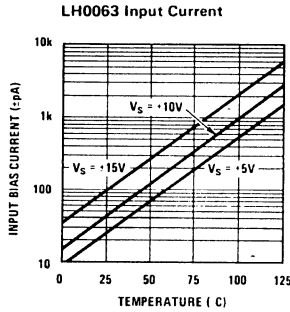
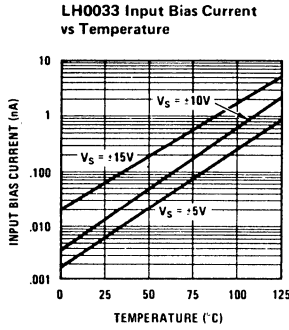
LH0033 Rise and Fall Time vs Temperature



LH0063 Large Signal Pulse Response



typical performance characteristics (con't)



application hints

Recommended Layout Precautions: RF/video printed circuit board layout rules should be followed when using the LH0033 and LH0063 since they will provide power gain to frequencies over 100 MHz. Ground planes are recommended and power supplies should be decoupled at each device with low inductance capacitors. In addition, ground plane shielding may be extended to the metal case of the device since it is electrically isolated from internal circuitry. Alternatively the case should be connected to the output to minimize input capacitance.

Offset Voltage Adjustment: Both the LH0033's and LH0063's offset voltages have been actively trimmed by laser to meet-guaranteed specifications when the offset preset pin is shorted to the offset adjust pin. This pre-calibration allows the devices to be used in most DC or AC applications without individually offset nulling each device. If offset null is desirable, it is simply obtained by leaving the offset preset pin open and connecting a trim pot of 100Ω for the LH0033 or 1 kΩ for the LH0063 between the offset adjust pin and V⁻ as illustrated in Figures 1 and 2.

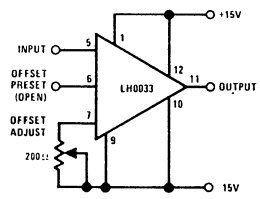


FIGURE 1. Offset Zero Adjust for LH0033 (Pin nos. shown for TO-8)

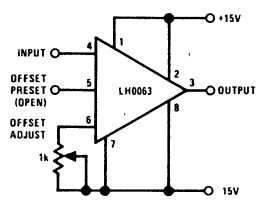


FIGURE 2. Offset Zero Adjust for LH0063

application hints (con't)

Operation from Single or Asymmetrical Power Supplies: Both device types may be readily used in applications where symmetrical supplies are unavailable or not desirable. A typical application might be an interface to a MOS shift register where $V^+ = +5V$ and $V^- = -12V$. In this case, an apparent output offset occurs due to the device's voltage gain of less than unity. This additional output offset error may be predicted by:

$$\Delta V_O \cong (1 - A_V) \frac{(V^+ - V^-)}{2} = .005 (V^+ - V^-)$$

where:

A_V = No load voltage gain, typically .99

V^+ = Positive supply voltage

V^- = Negative supply voltage

For the above example, ΔV_O would be -35 mV. This may be adjusted to zero as described in Section 2. For AC coupled applications, no additional offset occurs if the DC input is properly biased as illustrated in the "typical applications" section.

Short Circuit Protection: In order to optimize transient response and output swing, output current limit has been omitted from the LH0033 and LH0063. Short circuit protection may be added by inserting appropriate value resistors between V^+ and V_C^+ pins and V^- and V_C^- pins

as illustrated in Figures 3 and 4. Resistor values may be predicted by:

$$R_{LIM} \cong \frac{V^+}{I_{SC}} = \frac{V^-}{I_{SC}}$$

where: $I_{SC} \leq 100$ mA for LH0033

$I_{SC} \leq 250$ mA for LH0063

The inclusion of limiting resistors in the collectors of the output transistors reduces output voltage swing. Decoupling V_C^+ and V_C^- pins with capacitors to ground will retain full output swing for transient pulses. Alternate active current limit techniques that retain full DC output swing are shown in Figures 5, 6 and 7. In Figures 5 and 6, the current sources are saturated during normal operation thus apply full supply voltage to the V_C pins. Under fault conditions, the voltage decreases as required by the overload. For Figure 5:

$$R_{LIM} = \frac{V_{BE}}{I_{SC}} = \frac{.6V}{60 \text{ mA}} = 10\Omega$$

In Figure 6, quad transistor arrays are used to minimize can count and:

$$R_{LIM} = \frac{V_{BE}}{1/3 (I_{SC})} = \frac{.6V}{1/3 (200 \text{ mA})} = 8.2\Omega$$

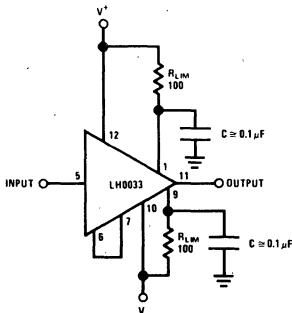


FIGURE 3. LH0033 Using Resistor Current Limiting

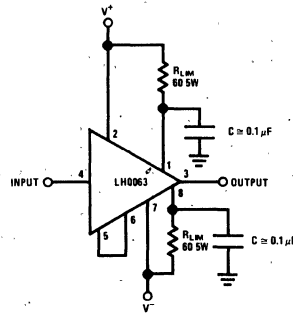


FIGURE 4. LH0063 Using Resistor Current Limiting

application hints (con't)

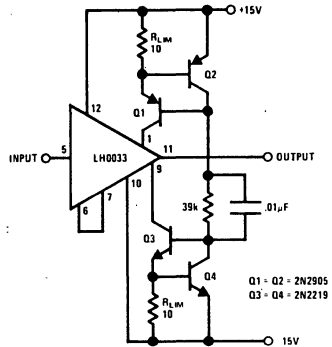


FIGURE 5. LH0033 Current Limiting Using Current Sources

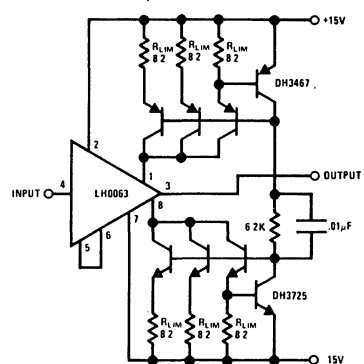


FIGURE 6. LH0063 Current Limiting Using Current Sources

Capacitive Loading: Both the LH0033 and LH0063 are designed to drive capacitive loads such as coaxial cables in excess of several thousand picofarads without susceptibility to oscillation. However, peak current resulting from $(C \times dV/dt)$ should be limited below absolute maximum peak current ratings for the devices.

Thus for the LH0033:

$$\left(\frac{\Delta V_{IN}}{\Delta t}\right) \times C_L \leq I_{OUT} \leq \pm 250 \text{ mA}$$

and for the LH0063:

$$\left(\frac{\Delta V_{IN}}{\Delta t}\right) \times C_L \leq I_{OUT} \leq \pm 500 \text{ mA}$$



application hints (con't)

In addition, power dissipation resulting from driving capacitive loads plus standby power should be kept below total package power rating:

$$P_{diss\ pkg} \geq P_{DC} + P_{AC}$$

$$P_{diss\ pkg} \geq (V^+ - V^-) \times I_S + P_{AC}$$

$$P_{AC} \cong (V_{P-P})^2 \times f \times C_L$$

where V_{P-P} = Peak-to-peak output voltage swing
 f = frequency
 C_L = Load Capacitance

Operation Within an Op Amp Loop: Both devices may be used as a current booster or isolation buffer within a closed loop with op amps such as LH0032, LH0062, or LM118. An isolation

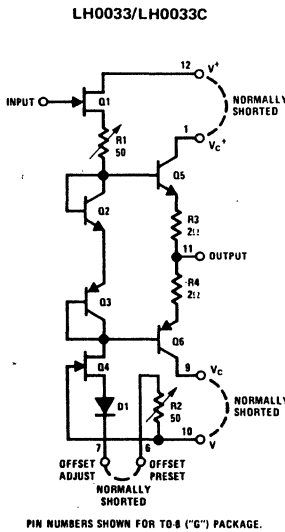
resistor of 47Ω should be used between the op amp output and the input of LH0033. The wide bandwidths and high slew rates of the LH0033 and LH0063 assure that the loop has the characteristics of the op amp and that additional rolloff is not required.

Hardware: In order to utilize the full drive capabilities of both devices, each should be mounted with a heat sink particularly for extended temperature operation. The cases of both are isolated from the circuit and may be connected to system chassis.

ACHTUNG!

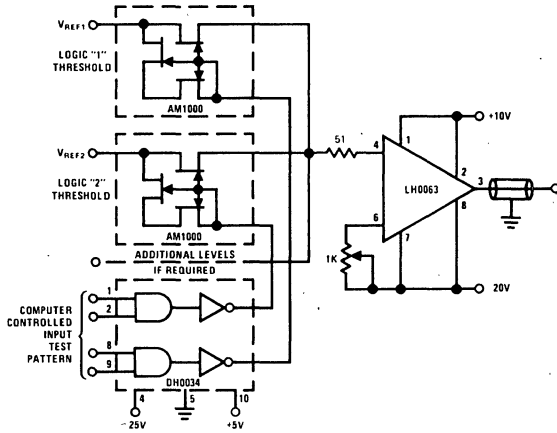
Power supply bypassing is necessary to prevent oscillation with both the LH0033 and LH0063 in all circuits. Low inductance ceramic disc capacitors with the shortest practical lead lengths must be connected from each supply lead (within < ¼ to ½" of the device package) to a ground plane. Capacitors should be one or two 0.1µF in parallel for the LH0033; adding a 4.7µF solid tantalum capacitor will help in troublesome instances. For the LH0063, two 0.1µF ceramic and one 4.7µF solid tantalum capacitors in parallel will be necessary on each supply lead.

schematic diagrams

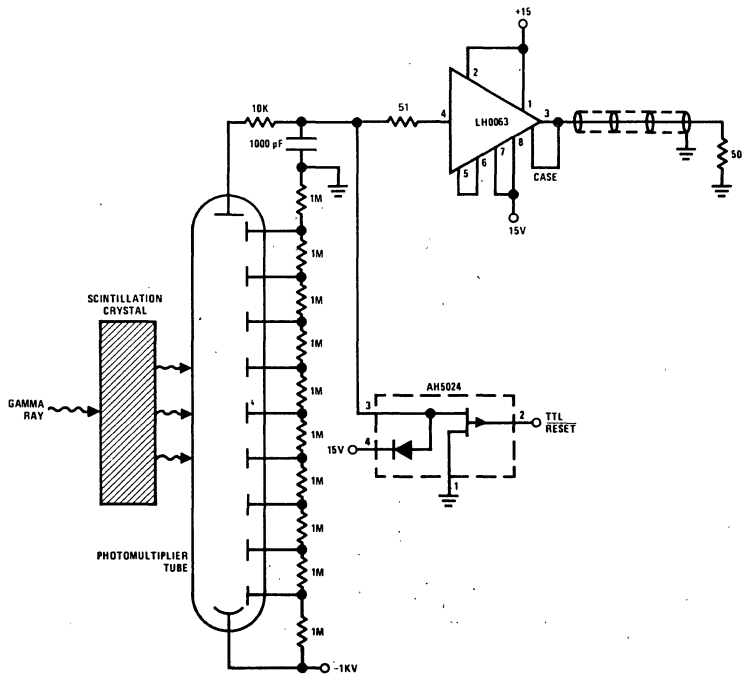


typical applications

High Speed Automatic Test Equipment
Forcing Function Generator



Gamma Ray Pulse Integrator

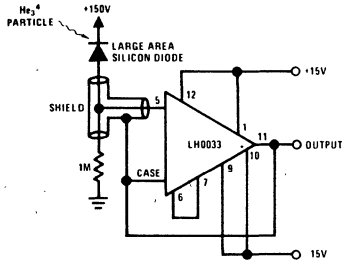


LH0033/LH0033C, LH0063/LH0063C

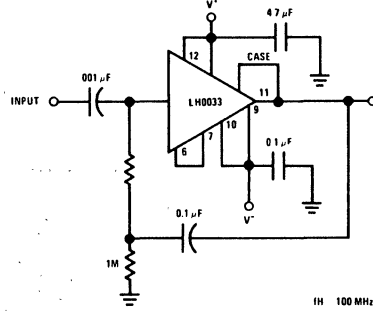
3

typical applications (con't)

Nuclear Particle Detector

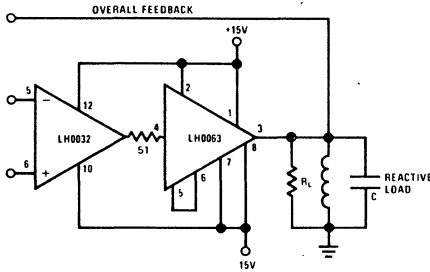


High Input Impedance AC Coupled Amplifier

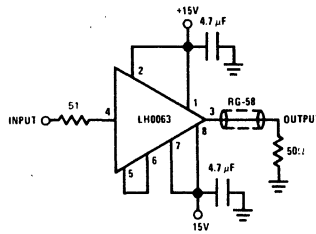


IH 100 MHz

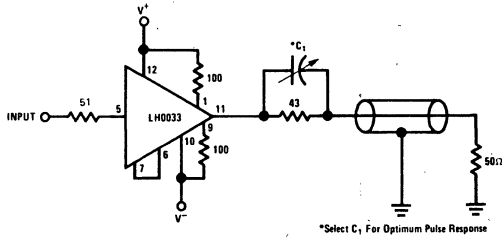
Isolation Buffer



Coaxial Cable Driver

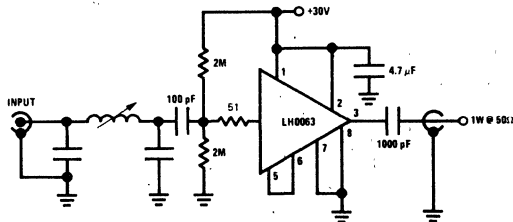


Coaxial Cable Driver



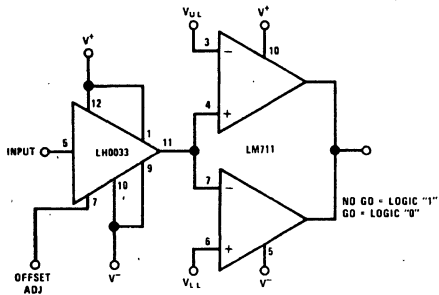
*Select C₁ For Optimum Pulse Response

1W CW Final Amplifier

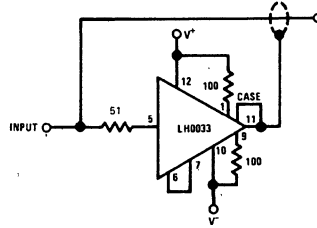


typical applications (con't)

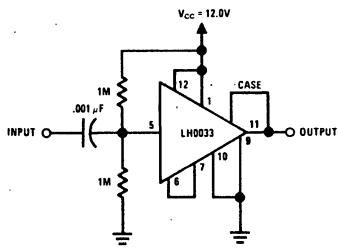
High Input Impedance Comparator
With Offset Adjust



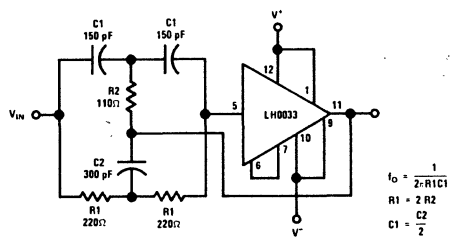
Instrumentation Shield/Line Driver



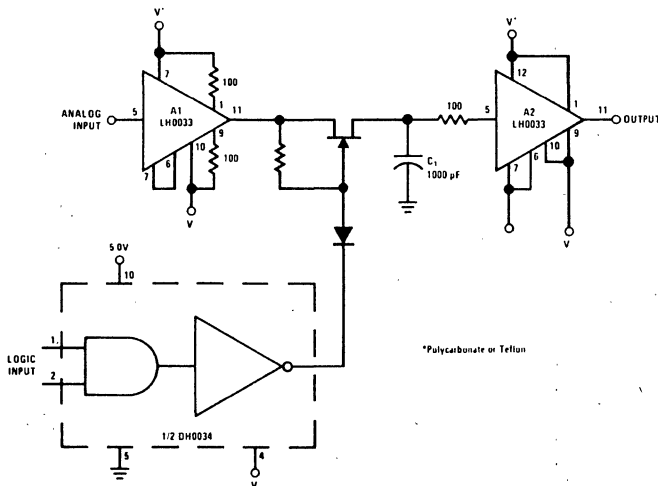
Single Supply AC Amplifier



4.5 MHz Notch Filter



High Speed Sample & Hold





LH0044 Series Precision Low Noise Operational Amplifiers

General Description

The LH0044 Series is a low noise, ultra-stable, high gain, precision operational amplifier family intended to replace either chopper-stabilized monolithic or modular amplifiers. The devices are particularly suited for differential mode, inverting, and non-inverting mode applications requiring very low initial offset, low offset drift, very high gain, high CMRR, and high PSRR. In addition, the LH0044 Series' low initial offset and offset drift eliminate costly and time consuming null adjustments at the systems level. The superior performance afforded by the LH0044 Series is made possible by advanced processing and testing techniques, as well as active laser trim of critical metal film resistors to minimize offset voltage and drift. Unique construction eliminates thermal feedback effects.

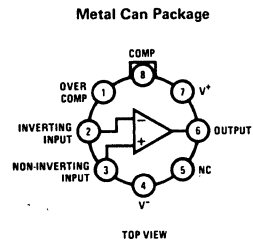
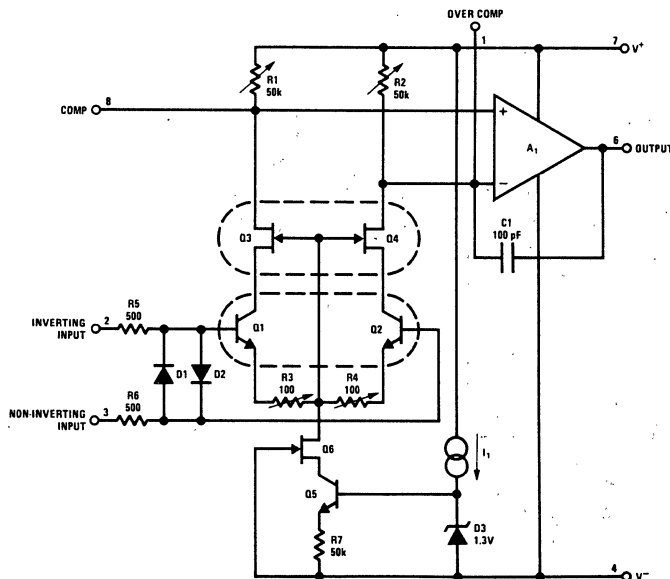
The LH0044 Series is an excellent choice for a wide range of precision applications including strain gauge bridges, thermocouple amplifiers, and ultrastable reference amplifiers. The LH0044 and LH0044A are

guaranteed over the temperature range of -55°C to $+125^{\circ}\text{C}$, and the LH0044AC, LH0044B, and LH0044C are guaranteed from -25°C to $+85^{\circ}\text{C}$. The device is available in standard TO-5 op amp pin out and is compatible with LM108A, LM725, and LM741 type amplifiers.

Features

- Low input offset voltage 25 μV max
- Excellent long-term stability $\pm 1\mu\text{V}/\text{month}$ max
- Low offset drift 0.5 $\mu\text{V}/^{\circ}\text{C}$ max
- Very low noise 0.7 $\mu\text{Vp-p}$ max 0.1 Hz to 10 Hz
- High CMRR and PSRR 120 dB min
- High open loop gain 120 dB min
- Wide common-mode range $\pm 13\text{V}$ min
- Wide supply voltage range $\pm 2\text{V}$ to $\pm 20\text{V}$

Equivalent Circuit and Connection Diagram



Case is electrically isolated
 Note: Compensation is not normally required. However, for maximum stability, a 0.01 μF capacitor should be placed between pins 7 and 8 when device is used below closed loop gains of 10.

Order Number LH0044H,
 LH0044AH, LH0044CH, LH0044ACH,
 LH0044BH
 See Package H08B

Absolute Maximum Ratings

| | | | |
|-------------------------------------|------------|--|-----------------|
| Supply Voltage | ±20V | Operating Temperature Range | -55°C to +125°C |
| Power Dissipation | 600 mW | LH0044, LH0044A | -25°C to +85°C |
| Differential Input Voltage (Note 4) | ±1V | LH0044AC, LH0044B, LH0044C | -65°C to +150°C |
| Input Voltage (Note 5) | ±15V | Storage Temperature Range | -65°C to +150°C |
| Output Short-Circuit Duration | Continuous | Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|------------------------------------|---|------------------|--------------------|-----|------------------------|--------------------|-----|--|
| | | LH0044A/LH0044AC | | | LH0044/LH0044B/LH0044C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $R_S = 50\Omega$, $V_{CM} = 0\text{V}$ LH0044C Only | | 8 | 25 | | 12 | 50 | μV μV |
| Input Offset Voltage | $R_S = 50\Omega$, $V_{CM} = 0\text{V}$ LH0044A and LH0044B Only | | | 50 | | | 150 | μV μV |
| Average Input Offset Voltage Drift | $T_{MIN} \leq T_A \leq T_{MAX}$ LH0044B Only | | 0.1 | 0.5 | | 0.2 | 1.3 | $\mu\text{V}/^\circ\text{C}$ $\mu\text{V}/^\circ\text{C}$ |
| Long-Term Stability | (Note 2) | | 0.2 | 1 | | 0.3 | 2 | $\mu\text{V}/\text{month}$ |
| Input Noise Voltage (Note 3) | $\text{BW} = 0.1 \text{ Hz to } 10 \text{ Hz}$, $R_S = 50\Omega$ $R_S = 10 \text{ k}\Omega$ Imbalance | | 0.35 | 0.7 | | 0.35 | 0.8 | μV_{p-p} μV_{p-p} |
| Thermal Feedback Coefficient | | | 0.005 | | | 0.005 | | $\mu\text{V}/\text{mW}$ |
| Open Loop Voltage Gain | $R_L = 10 \text{ k}\Omega$ | 120 | 145 | | 114 | 140 | | dB |
| Common-Mode Rejection Ratio | $-10\text{V} \leq V_{CM} \leq +10\text{V}$ | 120 | 145 | | 114 | 140 | | dB |
| Power Supply Rejection Ratio | $\pm 3\text{V} \leq V_S \leq \pm 18\text{V}$ | 120 | 145 | | 114 | 140 | | dB |
| Input Voltage Range | | ±13 | ±13.8 | | ±12 | ±13.5 | | V |
| Output Voltage Swing | $R_L = 10 \text{ k}\Omega$ | ±13 | ±13.7 | | ±12 | ±13.5 | | V |
| Input Offset Current | $25^\circ\text{C} \leq T_A \leq T_{MAX}$ $T_{MIN} \leq T_A < 25^\circ\text{C}$ | | 1.0 | 2.5 | | 1.5 | 5.0 | nA nA |
| Average Input Offset Current Drift | | | 5 | 40 | | .15 | 80 | $\text{pA}/^\circ\text{C}$ |
| Input Bias Current | $25^\circ\text{C} \leq T_A \leq T_{MAX}$ $T_{MIN} \leq T_A < 25^\circ\text{C}$ | | 8.5 | 15 | | 10 | 30 | nA nA |
| Average Input Bias Current Drift | | | 50 | 300 | | 100 | 600 | $\text{pA}/^\circ\text{C}$ |
| Differential Input Impedance | | 5 | 10 | | 2.5 | 8 | | M Ω |
| Common-Mode Input Impedance | | | 2×10^{11} | | | 2×10^{11} | | Ω |
| Supply Current | $I_L = 0$ | | 0.9 | 3.0 | | 1.0 | 4.0 | mA |
| Power Dissipation | | | 27 | 90 | | 30 | 120 | mW |

AC Electrical Characteristics $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$

| PARAMETER | CONDITIONS | TYP | UNITS |
|------------------------|--|---------|--|
| Input Noise Voltage | $R_S = 1 \text{ k}\Omega$, $f_O = 10 \text{ Hz}$ $R_S = 1 \text{ k}\Omega$, $f_O = 1 \text{ kHz}$ | 11 9 | $\text{nV}/\sqrt{\text{Hz}}$ $\text{nV}/\sqrt{\text{Hz}}$ |
| Slew Rate | $A_V = +1$, $R_L = 10 \text{ k}\Omega$, $V_{IN} = \pm 10\text{V}$ | 0.06 | V/ μs |
| Large Signal Bandwidth | $A_V = +1$, $R_L = 10 \text{ k}\Omega$, $V_{IN} = \pm 10\text{V}$ | 1 | kHz |
| Overload Recovery Time | $A_V = +100$, $V_{IN} = -100 \text{ mV}$, $\Delta V_{IN} = 200 \text{ mV}$ | 5 | μs |
| Small Signal Bandwidth | $A_V = +1$, $R_L = 10 \text{ k}\Omega$ | 400 | kHz |
| Small Signal Rise Time | $A_V = +1$, $R_L = 10 \text{ k}\Omega$, $V_{IN} = 10 \text{ mV}$ | 2.5 | μs |
| Overshoot | $A_V = +1$, $R_L = 10 \text{ k}\Omega$, $V_{IN} = 10 \text{ mV}$, $C_L = 100 \text{ pF}$ | 10 | % |

Note 1: All specifications apply for all device grades, at $V_S = \pm 15\text{V}$, and from T_{MIN} to T_{MAX} unless otherwise specified. T_{MIN} is -55°C and T_{MAX} is $+125^\circ\text{C}$ for the LH0044A and LH0044. T_{MIN} is -25°C and T_{MAX} is $+85^\circ\text{C}$ for the LH0044AC, LH0044B and LH0044C. Typical values are given for $T_A = 25^\circ\text{C}$.

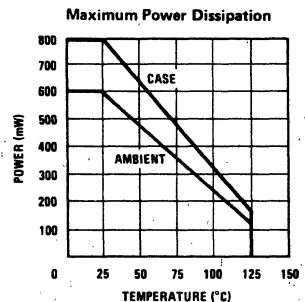
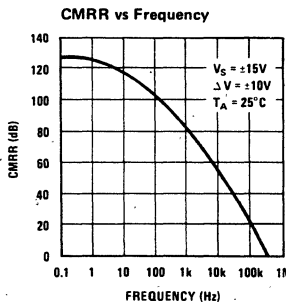
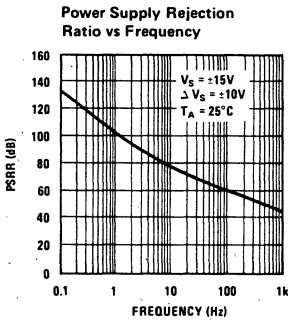
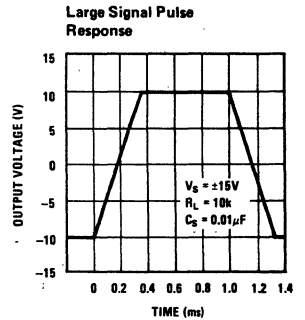
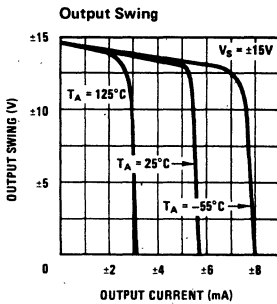
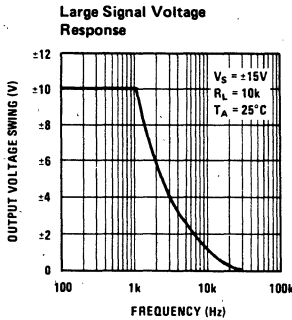
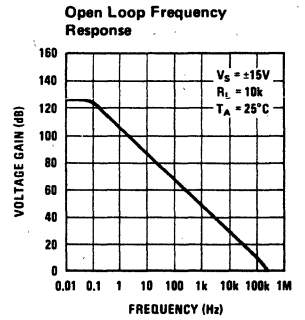
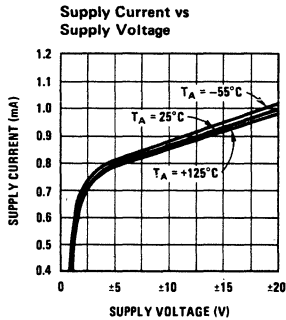
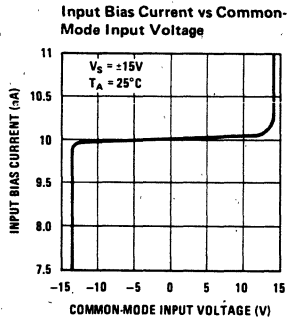
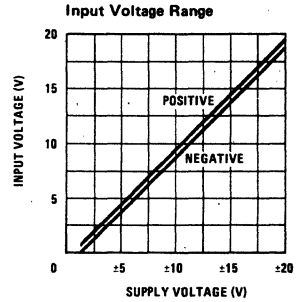
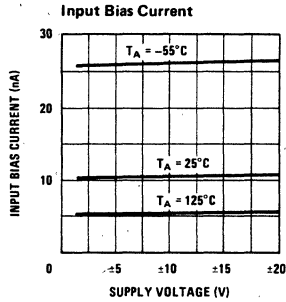
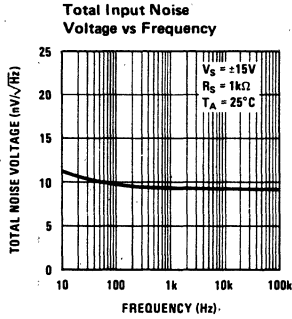
Note 2: This parameter is not 100% tested; however, 90% of the devices are guaranteed to meet this specification after one month of operation and after initial turn-on stabilization.

Note 3: Noise is 100% tested on the LH0044A, LH0044AC and LH0044B only. 90% of the LH0044 and LH0044C devices are guaranteed to meet this specification.

Note 4: The inputs are shunted by back-to-back diodes for over-voltage protection. Excessive current will flow for differential input voltages in excess of 1V. Input current should be limited to less than 1 mA.

Note 5: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.

Typical Performance Characteristics



Applications Information

LOW DRIFT CONSIDERATIONS

Achieving ultra-low drift in practical applications requires strict attention to board layout, thermocouple effects, and input guarding. For specific recommendations refer to AN-63 and AN-79.

A point worth stressing with regard to low drift specifications is testing of the LH0044. Simply stated—it is virtually impossible to test the device using a thermoprobe or other form of local heating. A one degree centigrade temperature gradient can account for tens of microvolts of virtual offset (or drift). The test circuit of *Figure 1* is recommended for use in a stabilized oven or continuously stirred oil bath with the entire circuit inside the oven or bath. Isothermal layout of the resistors is advised in order to minimize thermocouple induced EMF's.

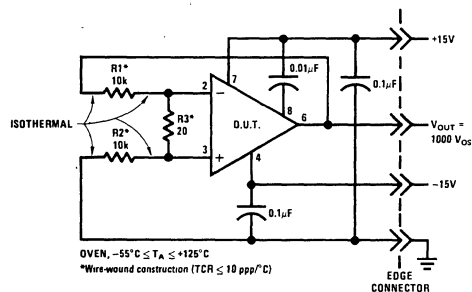


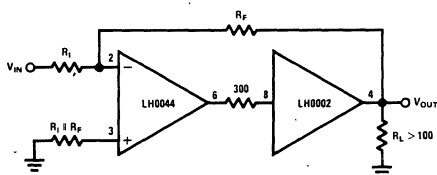
FIGURE 1. LH0044 Temperature Test Circuit

OVER COMPENSATION

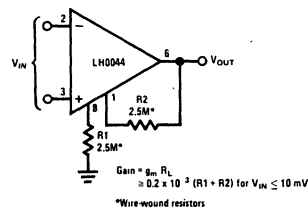
The LH0044 may be overcompensated in order to minimize noise bandwidth by paralleling the internal 100 pF capacitor with an external capacitor connected between pins 1 and 6. Unity gain frequency may be predicted by:

$$f = \frac{4 \times 10^{-5}}{100 \text{ pF} + C_{\text{ext}} \text{ pF}} \text{ (Hz)}$$

Typical Applications



Buffered Output for Heavy Loads



X1000 Instrumentation Amp

COMPENSATION

For closed loop gains in excess of 10, no external components are required for frequency stability. However, for gains of 10 or less, a 0.01µF disc capacitor is recommended between pin 7 (V⁺) and pin 8 (Comp). An improvement in ac PSRR will also be realized by use of the 0.01µF capacitor.

OFFSET NULL

In general, further nulling of LH0044 is neither necessary nor recommended. For most applications the specified initial offset is sufficient.

However, for those applications requiring additional null, an obvious temptation might be to place a pot between pins 1 and 8 with the wiper returned to V⁺. This technique will usually result in reduced gain and increased offset drift due to mismatch in the TCR of the pot and R1 and R2. The technique is, therefore, not generally recommended.

The recommended technique for offset nulling the LH0044 is shown in *Figure 2*. Null is accomplished in A₂ and all errors are divided by the closed loop gain of the LH0044. Additional offset and drift incurred due to use of A₂ is less than 1µV/V for V⁺ and V⁻ changes and 0.01µV/°C drift for the values shown in *Figure 2*.

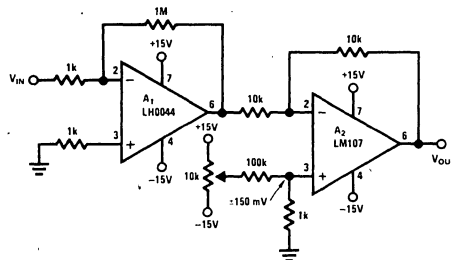
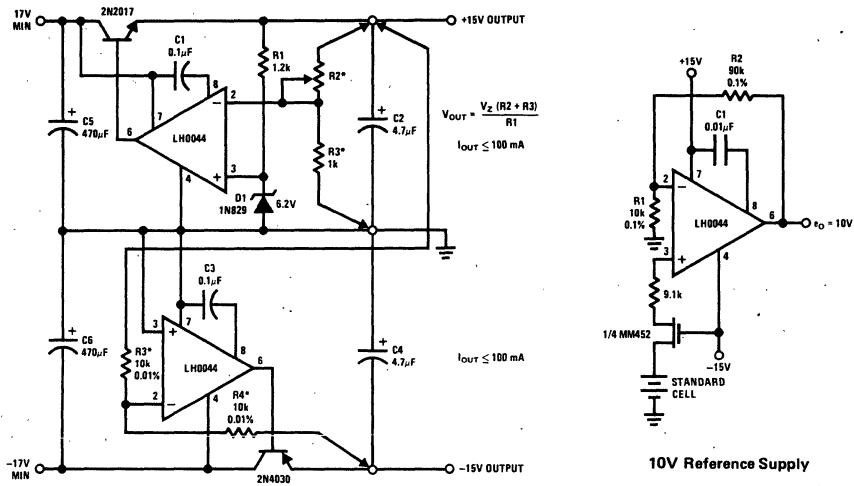


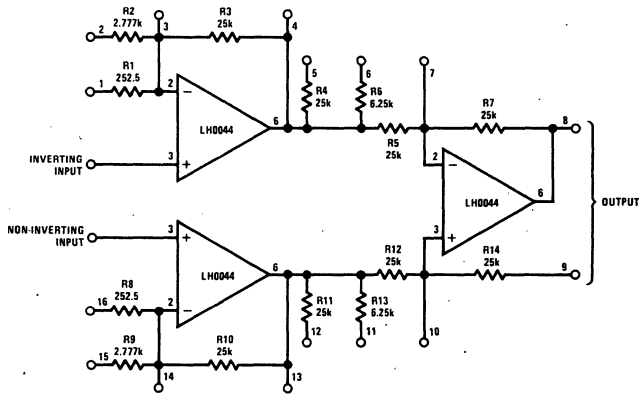
FIGURE 2. LH0044 Null Technique

Typical Applications (Continued)



*Wire-wound for minimum drift.
 Line and load regulation $\leq 0.005\%$

Precision Dual Tracking Regulator

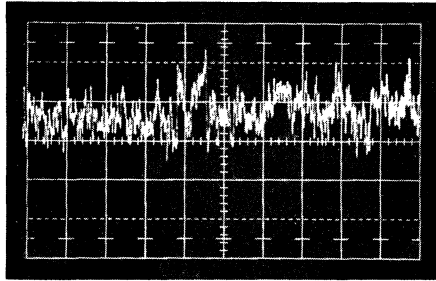
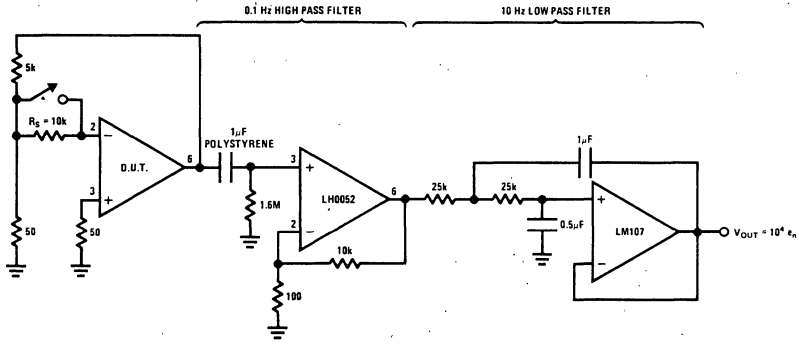


All resistors are part of National's RA201 resistor array.

| OVERALL GAIN | INPUT STAGE GAIN | OUTPUT STAGE GAIN | JUMPER PINS ON RA201 |
|--------------|------------------|-------------------|---------------------------|
| X1 | X1 | X1 | — |
| X2 | X1 | X2 | 5 to 7, 12 to 10 |
| X5 | X1 | X5 | 6 to 7, 11 to 10 |
| X10 | X10 | X1 | 2 to 15 |
| X20 | X10 | X2 | 2 to 15, 5 to 7, 12 to 10 |
| X50 | X10 | X5 | 2 to 15, 6 to 7, 11 to 10 |
| X100 | X100 | X1 | 1 to 16 |
| X200 | X100 | X2 | 1 to 16, 5 to 7, 12 to 10 |
| X500 | X100 | X5 | 1 to 16, 6 to 7, 11 to 10 |
| X995 | X199 | X5 | 1 to 14, 6 to 7, 11 to 10 |

Precision Instrumentation Amplifier

Noise Test Circuit



VERT: 200 nV/DIV
HORIZ: 5 SEC/DIV

LH0045/LH0045C Two Wire Transmitter

general description

The LH0045/LH0045C Two Wire Transmitters are linear integrated circuits designed to convert the voltage from a sensor to a current, and send it through to a receiver, utilizing the same simple twisted pair as the supply voltage.

The LH0045 and LH0045C contain an internal reference designed to power the sensor bridge, a sensitive input amplifier, and an output current source. The output current scale can be adjusted to match the industry standards of 4.0 mA to 20 mA or 10 mA to 50 mA.

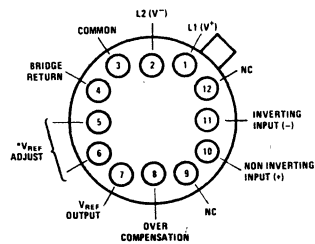
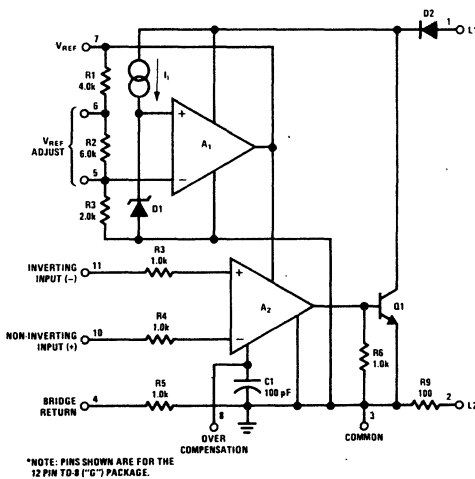
Designed for use with various sensors, the LH0045/LH0045C will interface with thermocouples, strain gauges, or thermistors. The use of the power supply leads as the signal output eliminates two or three extra wires in remote signal applications. Also, current output minimizes susceptibility to voltage noise spikes and eliminates line drop problems.

features

- High sensitivity > 10 μ A/ μ V
- Low input offset voltage 1.0 mV
- Low input bias current 2.0 nA
- Single supply operation 10V to 50V
- Programmable bridge reference 5.0V to 30V (LH0045G)
- Non-interactive span and null adjust
- Over compensation capability
- Supply reversal protection

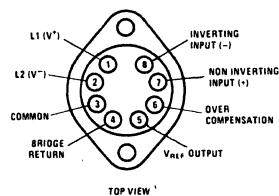
The LH0045/LH0045C is intended to fulfill a wide variety of process control, instrumentation, and data acquisition applications. The LH0045 is guaranteed over the temperature range of -55°C to $+125^{\circ}\text{C}$; whereas the LH0045C is guaranteed from -25°C to $+85^{\circ}\text{C}$.

equivalent schematic and connection diagrams



Order Number LH0045G or LH0045CG
See Package H12B

TO-3



Order Number LH0045K or LH0045CK
See Package K08A

absolute maximum ratings

| | |
|--|-----------------|
| Supply Voltage (L1 to common) | +50V |
| Input Current | ±20 mA |
| Input Voltage (Either Input to Common) | 0V to V_{REF} |
| Differential Input Voltage | ±20 V |
| Output Current (Either L1 or L2) | 50 mA |
| Reference Output Current | 5.0 mA |
| Power Dissipation | |
| LH0045G | 1.5W |
| LH0045K | 3.0W |
| Operating Temperature Range | |
| LH0045 | -55°C to +125°C |
| LH0045C | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

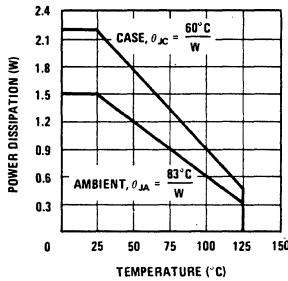
electrical characteristics (Note 1)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---|--|---------------------------|---------------------------|------|---------------------------|---------------------------|------|--------------------------------|
| | | LH0045 | | | LH0045C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage (V_{OS}) | $I_S = 4.0 \text{ mA}, T_A = 25^\circ\text{C}$ $I_S = 4.0 \text{ mA}$ | | 0.7 | 2.0 | | 2.0 | 7.5 | mV |
| | | | | 3.0 | | | 10 | mV |
| Offset Voltage Temperature Coefficient ($\Delta V_{OS}/\Delta T$) | $I_S = 4.0 \text{ mA}$ | | 3.0 | | | 6.0 | | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current (I_B) | $T_A = 25^\circ\text{C}$ | | 0.8 | 2.0 | | 1.5 | 7.0 | nA |
| | | | | 3.0 | | | 10. | nA |
| Input Offset Current (I_{OS}) | $T_A = 25^\circ\text{C}$ | | 0.05 | 0.2 | | 0.2 | 1.0 | nA |
| | | | | 0.4 | | | 1.5 | nA |
| Open Loop Transconductance (g_{MOL}) | $\Delta I_S = 4.0 \text{ mA to } 20 \text{ mA}$ $\Delta I_S = 10 \text{ mA to } 50 \text{ mA}$ | 10^6 2×10^6 | 10^7 2×10^7 | | 10^6 2×10^6 | 10^7 2×10^7 | | μS μS |
| Supply Voltage Range (V_S) | LH0045G pins 5 and 6 open | 9.0 | | 50 | 9.0 | | 50 | V |
| | | 15 | | 50 | 15 | | 50 | V |
| Input Voltage Range (V_{IN}) | LH0045G pins 5 and 6 open | 1.0 | | 3.3 | 1.0 | | 3.3 | V |
| | | 1.0 | | 7.6 | 1.0 | | 7.6 | V |
| Open Loop Output Impedance (R_{OUT}) | $V_S = 10\text{V to } 45\text{V}, I_S = 4.0 \text{ mA}, T_A = 25^\circ\text{C}$ | | 1.0 | | | 1.0 | | M Ω |
| Common Mode Rejection Ratio (CMRR) | $\Delta V_{IN} = 1.0\text{V to } 3.3\text{V}, I_S = 12 \text{ mA}$ | 0.1 | 0.05 | | 0.1 | 0.05 | | mV/V |
| Power Supply Rejection Ratio (PSRR) | $\Delta V_S = 10\text{V to } 45\text{V}, I_S = 12 \text{ mA}$ | 0.1 | 0.01 | | 0.1 | 0.01 | | mV/V |
| Open Loop Supply Current (I_{SOL}) | $V_S = 50\text{V}$ | | 2.0 | 3.0 | | 2.0 | 3.0 | mA |
| Reference Voltage Load Regulation ($\Delta V_{REF}/\Delta I_{REF}$) | $\Delta I_{REF} = 0 \text{ mA to } 2.0 \text{ mA}, T_A = 25^\circ\text{C}$ | | 0.05 | 0.2 | | 0.05 | 0.2 | % |
| Reference Voltage Line Regulation ($\Delta V_{REF}/\Delta V_S$) | $\Delta V_S = 10\text{V to } 45\text{V}, T_A = 25^\circ\text{C}$ | | 0.3 | 0.5 | | 0.3 | 0.7 | mV/V |
| Reference Voltage Temperature Coefficient ($\Delta V_{REF}/\Delta T$) | $I_{REF} = 2.0 \text{ mA}$ | | 0.004 | | | 0.004 | | $\%/^\circ\text{C}$ |
| Reference Voltage (V_{REF}) | $I_{REF} = 2.0 \text{ mA}, T_A = 25^\circ\text{C}$ $I_{REF} = 2.0 \text{ mA}, T_A = 25^\circ\text{C},$ LH0045G pins 5 and 6 open | 4.3 | 5.1 | 5.9 | 4.3 | 5.1 | 5.9 | V |
| | | 8.6 | 10.3 | 12 | 8.6 | 10.3 | 12 | V |
| Resistor R9 | $I_S = 12 \text{ mA}, T_A = 25^\circ\text{C}$ | 95 | 100 | 105 | 95 | 100 | 105 | Ω |
| Average Temperature Coefficient of R9 (TCR_9) | $I_S = 12 \text{ mA}$ | | 50 | 300 | | 50 | 300 | PPM/ $^\circ\text{C}$ |
| Resistor R5 | $I_S = 1.0 \text{ mA}, T_A = 25^\circ\text{C}$ | 950 | 1000 | 1050 | 950 | 1000 | 1050 | Ω |
| Average Temperature Coefficient of R5 (TCR_5) | $I_S = 1.0 \text{ mA}$ | | 50 | 300 | | 50 | 300 | PPM/ $^\circ\text{C}$ |
| Input Resistance (R_{IN}) | $T_A = 25^\circ\text{C}$ | | 50 | | | 50 | | M Ω |

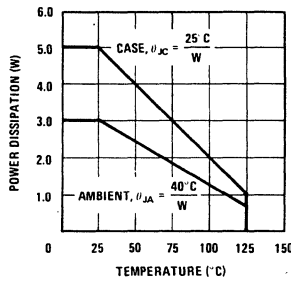
Note 1: Unless otherwise specified, these specifications apply for $+10\text{V} \leq V_S \leq +50\text{V}$, pin 5 shorted to pin 6 on the LH0045G, over the temperature range -55°C to $+125^\circ\text{C}$ for the LH0045 and -25°C to $+85^\circ\text{C}$ for the LH0045C.

typical performance characteristics

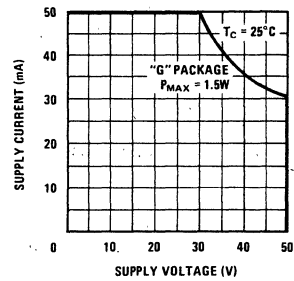
LH0045G Maximum Power Dissipation



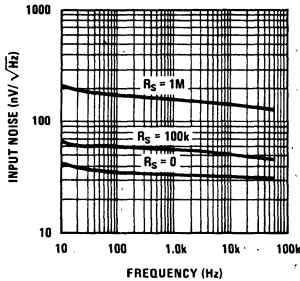
LH0045K Maximum Power Dissipation



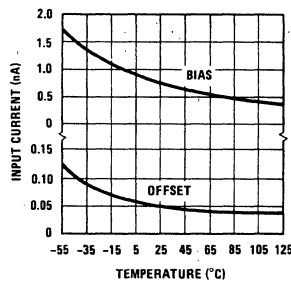
Safe Operating Area



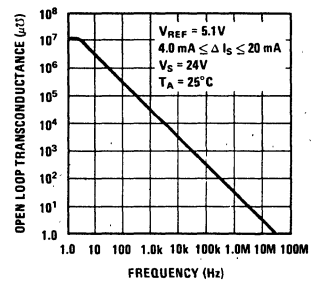
Input Noise Voltage



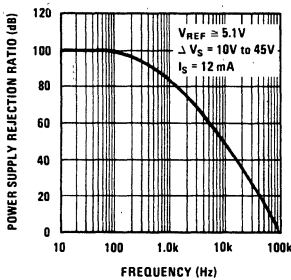
Input Currents



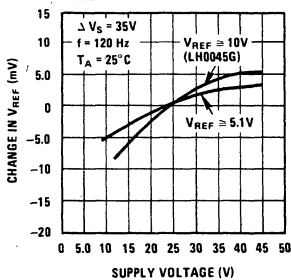
Open Loop Transconductance vs Frequency



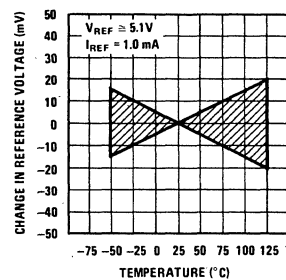
Power Supply Rejection Ratio vs Frequency



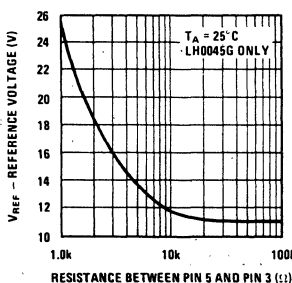
VREF Line Regulation



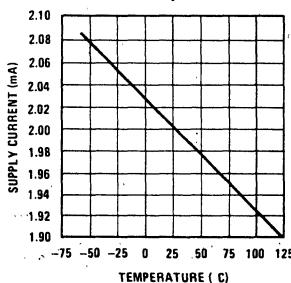
Variation of VREF With Temperature Normalized to 25°C



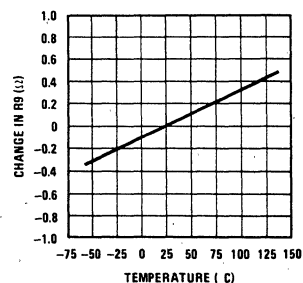
VREF vs Resistance Between Pin 5 and Pin 3



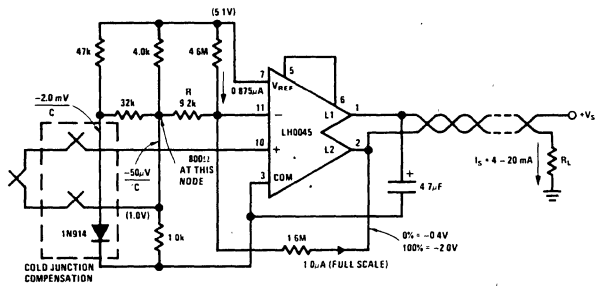
Open Loop Supply Current vs Temperature



Change in R9 With Temperature Normalized to 25°C

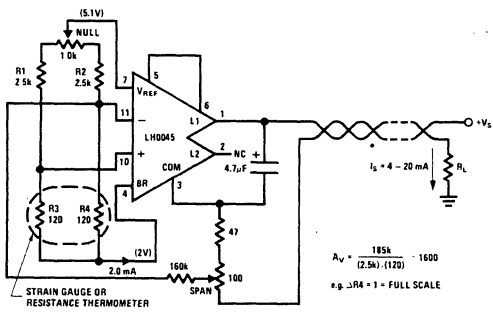


typical applications*



FOR 1.0 A FULL SCALE, $R_{in} = V_{in}/I_{in} = \text{SOURCE IMPEDANCE @ PIN 11}$
 e.g. V_{in} (FULL SCALE) = 10 mV, $R_{in} = 10k$
 BRIDGE IMPEDANCE = 0.8k, $R = 10k - 0.8k = 9.2k$

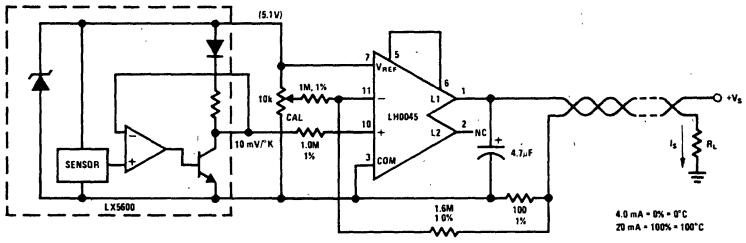
Thermocouple Input Transmitter



$$A_v = \frac{185k}{(2.5k)(120)} = 1600$$

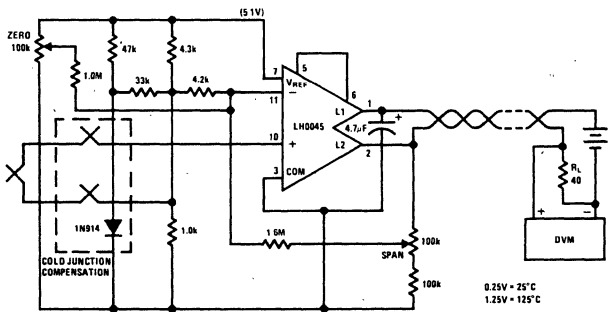
e.g. $\Delta R = 1 = \text{FULL SCALE}$

Resistance Bridge Input Transmitter



4.0 mA = 0% = 0°C
 20 mA = 100% = 100°C

Electronic Temperature Sensor

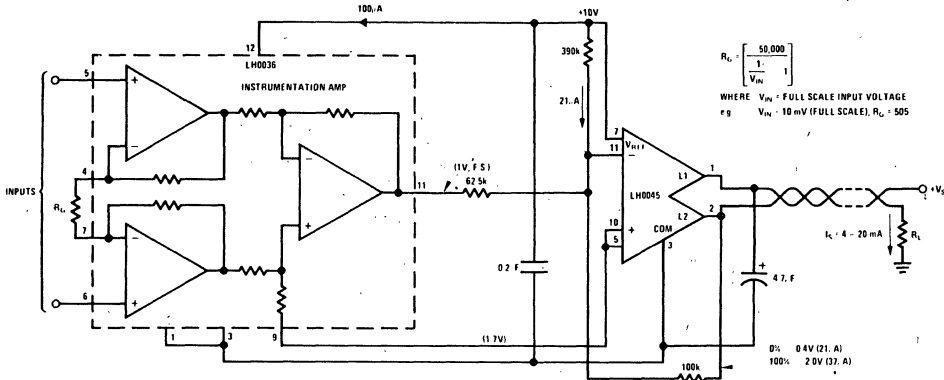


0.25V = 25°C
 1.25V = 125°C

Remote Sensing Digital Thermometer

*Pin numbers refer to 'G' package. All voltages indicated by () are measured with respect to common, pin 3.

typical applications* (con't)



*Pin numbers refer to 'G' package. All voltages indicated by () are measured with respect to common, pin 3.

Instrumentation Amplifier Transmitter

applications information

CIRCUIT DESCRIPTION AND OPERATION

A simplified schematic of the LH0045/LH0045C is shown in Figure 1. Differential amplifier, A₂ converts very low level signals to an output current via transistor Q1. Reference voltage diode D1 is used to supply voltage for operation of A₂ and to bias an external bridge. Current source I₁ minimizes fluctuation in the bridge reference voltage due to changes in V_S.

In normal operation, the LH0045/LH0045C is used in conjunction with an external bridge comprised of R_{B1} through R_{B4}. The bridge resistors in conjunction with bridge return resistor, R₅, bias A₂ in its linear region and sense the input signal; e.g. R_{B4} might be a strain sensitive resistor in a strain gauge bridge. R_T is adjusted to purposely unbalance the bridge for 4.0 mA output (null) for zero signal input. This is accomplished by forcing 2.5μA more through R_{B3} than R_{B4}.

The 2.5μA imbalance causes a voltage rise of (2.5μA) x (100Ω) or 250μV at the top of R_{B3}. Terminal L2 may be viewed as the output of an op amp whose closed loop gain is approximately R_F/R_{B3} = 1600.

The 250μV rise at the top of R_{B3} causes a voltage drop of (1600) x (250μV) or -0.4V across R₉. An output current, I_S, equal to 0.4V/R₉ or 4.0 mA is thus established in Q1. If R_{B4} is now decreased by 1.0Ω (due to application of a strain force), a -1.0 mV change in input voltage will result. This causes L2 to drop to -2.0V. The output current would then be 2.0V/100Ω or 20 mA (Full Scale). If R_{B3} is a resistor of the same material as R_{B4} but not subjected to the strain, temperature drift effects will be equal in the two legs and will cancel.

In actual practice the loading effects of R_{B2} on the gain (span) and R_F on output current must be taken into account.

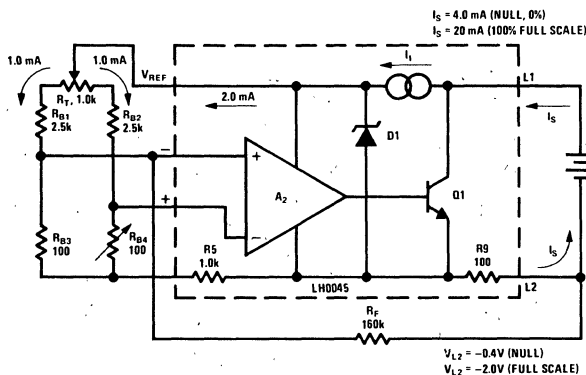


FIGURE 1. LH0045 Simplified Schematic

applications information (con't)

THERMAL CONSIDERATIONS

The power output transistor of the LH0045 is thermally isolated from the signal amplifier, A_2 . Nevertheless, a change in the power dissipation will cause a change in the temperature of the package and thus may cause amplifier drift. These temperature excursions may be minimized by careful heat sinking to hold the case temperature equal to the ambient. With the TO-8 (G) package this is best accomplished by a clip-on heat sink such as the Thermalloy #2240A or the Wakefield #215-CB. The 8 lead TO-3 is particularly convenient for heat sinking, in that it may be bolted directly to many commercial aluminum heat sink extrusions, or to the chassis. In both packages the case is electrically isolated from the circuit.

In addition, the power change can be minimized by operating the device from relatively high supply voltages in series with a relatively high load resistance. When the signal forces the supply current higher, the voltage across the device will be reduced and the internal power dissipation kept nearly equal to the low current, high voltage condition.

For example, take the case of a 4.0 mA to 20 mA transmitter with a 24V supply and a 100 Ω load resistance. The power at 4.0 mA is (23.6V) x (4.0 mA) = 94.4 mW while at full scale the power is (22V) x (20 mA) = 440 mW. The net change in power is 345 mW. This change in power will cause a change in temperature and thus a change in offset voltage of A_2 .

If the optimum load resistance of 800 Ω (from Figure 2) is used, the power at null is [24V - (4.0 mA) x (800 Ω)] (4.0 mA) = 83 mW. The power at full scale is [24V - (20 mA) x (800 Ω)] (20 mA) = 160 mW. The net change is 77 mW. This change is significantly less than without the resistor.

If the supply voltage is increased to 48V and the load resistance chosen to be the optimum value from Figure 2 (1.95k), then the power at null is [48V - (4.0 mA) x (1.95k)] (4.0 mA) = 160.8

mW and the power at full scale is [48 - (20) x (1.95k)] (20 mA) = 180 mW for a net change of 19.2 mW.

Note that the optimized load resistance is actually the sum of the line resistance, receiver resistances and added external load resistance. However, in many applications the line resistance and receiver resistances are negligible compared to the added external load resistance and thus may be omitted in calculations.

AUXILIARY PINS

The LH0045 has several auxiliary pins designed to provide the user with enhanced flexibility and performance. The following is a discussion of possible uses for these pins.

Programmable V_{REF} - Pins 5 and 6 (LH0045G Only)

The LH0045G provides pins 5 and 6 to allow the user to program the value of the reference voltage. The factory trimmed 10V value is obtained by leaving 5 and 6 open. A short between 5 and 6 will program the reference to a nominal 5.1V (equivalent to the fixed value used in the LH0045K).

A resistor or pot may be placed between pin 5 and common (pin 3) to obtain reference voltages between 10V and 30V or between pin 5 and pin 7 for reference voltages below 10V. Increased reference voltage might be useful to extend the positive common mode range or to accommodate transducers requiring higher supply voltage. A plot of resistance between pin 5 and pin 3 versus V_{REF} is given in the typical electrical characteristics section. V_{REF} may be adjusted about its nominal value by arranging a pot from V_{REF} to common and feeding a resistor from the wiper into pin 5 so that it may either inject or extract current. Lastly, pin 5 may be used as a nominal 1.7V reference point, if care is taken not to unduly load it with either dc current or capacitance. Obviously, higher supply voltages must be used to obtain the higher reference values. The minimum supply voltage to reference voltage differential is about 4.0V.

Bridge Return

An applications resistor is provided in the LH0045 with a nominal value of 1.0 k Ω . The primary application for the resistor is to maintain the minimum common mode input voltage (1.0V) required by the signal amplifier, A_2 . A typical input application might utilize a strain gauge or thermistor bridge where the resistance of the sensor is 100 Ω . Since only 1.0 mA may be drawn from V_{REF} , the 1.0 k Ω bridge return resistor is used to bias A_2 in its linear region as shown in Figure 3.

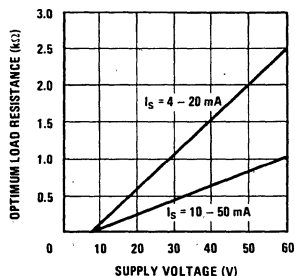


FIGURE 2. Optimum Load Resistance vs Supply Voltage

applications information (con't)

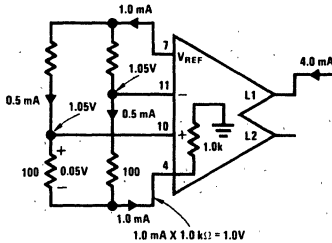


FIGURE 3. Use of Bridge Return

Over Compensation – Pin 8 (LH0045G), Pin 6 (LH0045K)

Over compensation of the signal amplifier, A₂ may be desirable in dc applications where the noise-bandwidth must be minimized. A capacitor should be placed between pin 8 (pin 6 on the LH0045K) and pin 3, common.

Typically,

$$f_{3db} = \frac{1}{2\pi R(C_1 + C_{EXT})}$$

where:

$$R = 400\text{ M}\Omega$$

$$C_1 = \text{Internal Compensation Capacitor} = 100\text{ pF}$$

$$C_{EXT} = \text{External (over-compensation) Capacitor}$$

Input Guard – Pins 9 and 12 (LH0045G)

Pins 9 and 12 have no internal connection whatever and thus need not be used. In some critical low current applications there may be an advantage to running a guard conductor between the inputs and the adjacent pins to intercept stray leakage currents. Pins 9 and 12 may be connected to this guard to simplify the PC board layout and allow the guard to continue under the device. (See AN-63 for further discussion of guarding techniques.)

NULL AND SPAN ADJUSTMENTS

Most applications of the LH0045 will require potentiometers to trim the initial tolerances of the sensor, the external resistors and the LH0045 itself. The preferred adjustment procedure is to stimulate the sensor, alternating between two known values, such as zero and full scale. The span and null are adjusted by monitoring the output current on a chart recorder, meter, or oscilloscope. A full scale stimulus is applied to the sensor and the span potentiometer adjusted for the desired full scale. Then, to adjust the null, apply a zero percent signal to the sensor and adjust the null potentiometer for the desired zero percent current indication.

If it is impractical to cycle the sensor during the calibration procedure, the signal may be simulated electrically with two cautions: 1) the calibration

signal must be floating and 2) the calibration thus achieved does not account for sensor inaccuracies and/or errors in the signal generator.

SENSOR SELECTION

Generally it is easiest to use an insulated sensor. If it is necessary to use a grounded sensor, the power supply must be isolated from chassis ground to avoid extraneous circulating currents.

DESIGN EXAMPLE

There are numerous circuit configurations that may be utilized with the LH0045. The following is intended as a general design example which may be extended to specific cases.

Circuit Requirements

Output Characteristics

- a. 0% = 4.0 mA (NULL)
- b. 100% = 20 mA (SPAN = 16 mA)
- c. Supply Voltage = 24V

Input (Sensor) Characteristics

- a. V_{IN} = 100 mV (Full Scale)
- b. V_{IN} = 0 mV (Zero Scale)
- c. Source Impedance ≤ 1.0Ω

General Characteristics

- a. 0°C ≤ T_A ≤ +75°C
- b. Overall Accuracy ≤ 0.5%

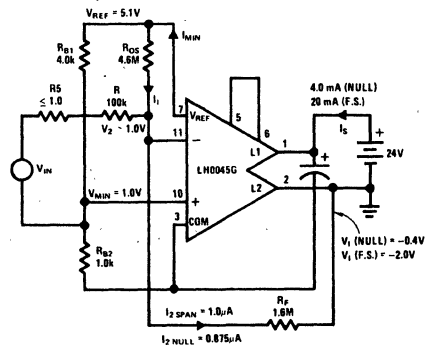


FIGURE 4. Design Example Circuit

Selection of R_F

Input bias current to the LH0045C is guaranteed less than 10 nA. Furthermore, the change in I_B over the temperature range of interest is typically under 1.0 nA. If I_{2 SPAN} is selected to be 1.0μA (1000 Δ I_B) errors due to Δ I_B/Δ T will be less than 0.1%. For SPAN = 16 mA.

$$V_{SPAN} = \Delta V_1 = -(16\text{mA})(R_9) = -1.6V$$

applications information (con't)

where R_9 = Internal Current Set Resistor = 100Ω
For $I_2 \text{ SPAN} = 1.0\mu\text{A}$,

$$R_F = \frac{V_{\text{SPAN}}}{I_2 \text{ SPAN}} = \frac{-1.6\text{V}}{1.0\mu\text{A}} = 1.6\text{M}$$

$$R_F = 1.6\text{M}\Omega$$

Selection of R_{B1} and R_{B2}

The minimum input common mode voltage, V_{MIN} required at the pin 10 input of A_2 is 1.0V. Furthermore, the maximum open loop supply current (I_{SOL}) drawn by the LH0045 is 3.0 mA. That leaves $I_{\text{MIN}} = 4.0\text{ mA} - 3.0\text{ mA} = 1.0\text{ mA}$ left to bias the bridge at null. Hence:

$$R_{B2} \geq \frac{V_{\text{MIN}}}{I_{\text{MIN}}} = \frac{1.0\text{V}}{1.0\text{ mA}} = 1.0\text{ k}\Omega$$

And,

$$\frac{V_{\text{REF}} R_{B2}}{R_{B1} + R_{B2}} = 1.0\text{V}$$

$$R_{B1} = R_{B2} \frac{V_{\text{REF}} - 1.0\text{V}}{1.0\text{V}}$$

$$= 1.0\text{k} (5.1 - 1.0)$$

$$R_{B1} \cong 4.0\text{ k}\Omega$$

Alternatively, an LM113, 1.22V reference diode, or an op amp such as the LM108 may be used to bias the signal amplifier, A_2 as shown in Figure 5. These techniques have the advantage of lowering the impedance seen at pin 10.

Selection of R_{OS}

R_{OS} is selected to provide the null current of 4.0 mA, $V_1 \text{ NULL} = 4.0\text{ mA} \times 100\Omega = 0.4\text{V}$. From previous calculations we know that $V_{\text{MIN}} = 1.0\text{V}$. The voltage pin 11, V_2 is:

$$V_2 = V_{\text{MIN}} + V_{\text{OS}} \cong V_{\text{MIN}}$$

for $V_{\text{IN}} = 0\text{V}$

Hence, the current required to generate the null voltage, $I_2 \text{ NULL}$ is:

$$I_2 \text{ NULL} = \frac{V_{\text{MIN}} - V_1 \text{ NULL}}{R_F}$$

$$= \frac{1.0\text{V} - (-0.4\text{V})}{1.6\text{ M}\Omega} = 0.875\mu\text{A}$$

This current must be provided by R_{OS} from V_{REF} ; hence:

$$R_{OS} = \frac{V_{\text{REF}} - V_{\text{MIN}}}{I_2 \text{ NULL}}$$

The nominal value for V_{REF} is 5.1V, therefore the nominal value for R_{OS} is:

$$\frac{5.1\text{V} - 1.0\text{V}}{0.875\mu\text{A}} \quad \text{or}$$

$$R_{OS} = 4.6\text{ M}\Omega$$

It should be noted however, that the variation of V_{REF} may be as high as 5.9V or as low as 4.3V. Furthermore, the tolerances of R_9 (100Ω), R_{B1} , R_{B2} , and the input V_{OS} of A_2 would predict values for R_{OS} as low as 3.98M and as high as 5.43M. The implication is that in the specific case, R_{OS} should be implemented with a pot, of appropriate value, in order to accommodate the tolerances of V_{REF} , R_9 , V_{OS} , R_{B1} , R_{B2} , etc.

Selection of R

SPAN is required to be 16 mA. From feedback theory and the gain equation we know:

$$I_{\text{SPAN}} = V_{\text{IN}} \frac{R_F}{R} \times \frac{1}{R_9}$$

where:

R = total impedance in signal path between pin 10 and pin 11

R_9 = Current setting resistor = 100Ω

V_{IN} = Full scale input voltage = 100 mV

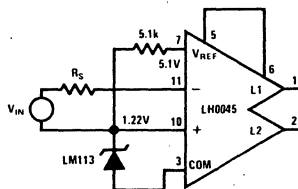
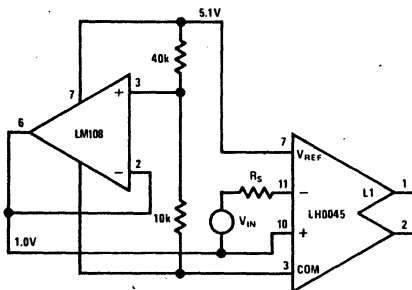


FIGURE 5. Alternate Biasing Techniques

applications information (con't)

$$\therefore R = \frac{(V_{IN})(R_F)}{(I_{SPAN})(R_9)}$$

$$R = \frac{(100 \text{ mV})(1.6 \text{ M}\Omega)}{(16 \text{ mA})(100\Omega)}$$

$$R = 100 \text{ k}\Omega$$

As before, uncertainties in device parameters might dictate that R_F be made a pot of appropriate value.

Summary of the Steps to Determine External Resistor Values

1. Select $I_{FULL \text{ SCALE}} = I_{NULL} + I_{SPAN}$ for the desired application. (I_{NULL} is frequently 4.0 mA and $I_{FULL \text{ SCALE}}$ is frequently 20 mA.)
2. Select $I_2 \text{ SPAN}$ so that it is large compared to ΔI_B . $1000 \Delta I_B$ is a good value.
3. Determine $V_{SPAN} = \Delta V_2 = (I_{SPAN})(R_9)$.
4. Determine $R_F = (V_{SPAN}/I_2 \text{ SPAN})$
5. Select

$$R_{B2} \geq \frac{V_{MIN}}{I_{MIN}}$$

$$R_{B2} \geq \frac{1 \text{ VOLT}}{I_{NULL} - I_{SOL}}$$

Where:

V_{MIN} = minimum common mode input voltage

I_{MIN} = minimum available bridge current

I_{SOL} = maximum open loop supply current

6. Determine

$$R_{B1} = R_{B2} \frac{V_{REF} - V_{MIN}}{V_{MIN}}$$

7. Determine $V_2 \text{ NULL} = I_{NULL} R_9$

8. Determine

$$I_2 \text{ NULL} = \frac{V_{MIN} - V_2 \text{ NULL}}{R_F}$$

9. Determine

$$R_{OS} = \frac{V_{REF} - V_{MIN}}{I_2 \text{ NULL}}$$

10. Determine

$$R = \frac{(V_{IN})(R_F)}{(I_{SPAN})(R_9)}$$

Where:

V_{IN} = Sensor full scale output voltage

ERROR BUDGET ANALYSIS

Errors Due to Change in V_{REF} (ΔV_{REF})

There are several factors which could cause a change in V_{REF} . First, as the ambient temperature changes, a V_{REF} drift of $\pm 0.2 \text{ mV}/^\circ\text{C}$ might be expected. Secondly, supply voltage variations could cause a $0.5 \text{ mV}/\text{V}$ change in V_{REF} . Lastly, self-heating due to power dissipation variations can cause drift of the reference.

An overall expression for change in V_{REF} is:

$$\Delta V_{REF} = \underbrace{[(\theta)(\Delta P_{DISS}) + \Delta T_A]}_{\text{Thermal Effects}} \frac{\Delta V_{REF}}{\Delta T} + \underbrace{\frac{\Delta V_{REF}}{\Delta V_S} (\Delta V_S)}_{\text{Supply Voltage Effects}}$$

Where:

θ = Thermal resistance, either junction-to-ambient to junction to case

ΔP_{DISS} = Change in avg. power dissipation

ΔT_A = Change in ambient temperature

$\frac{\Delta V_{REF}}{\Delta T}$ = Reference voltage drift (in $\text{mV}/^\circ\text{C}$)

$\frac{\Delta V_{REF}}{\Delta V_S}$ = Line regulation of V_{REF}

Several steps may be taken to minimize the bracketed terms in the equation above. For example, operating the LH0045G with a heat-sink reduces the thermal resistance from $\theta_{JA} = 83^\circ\text{C}/\text{W}$ to $\theta_{JC} = 60^\circ\text{C}/\text{W}$. For the LH0045K (TO-3) $\theta_{JA} = 40^\circ\text{C}/\text{W}$ may be reduced to $\theta_{JC} = 25^\circ\text{C}/\text{W}$ by using a heat sink. The ΔP_{DISS} term may be significantly reduced using the power minimization technique described under "Thermal Considerations." For the design example, ΔP_{DISS} is reduced from 384 mW to 77 mW ($R_L = 800\Omega$.) Evaluating the LH0045G with a heat-sink and $R_L = 800\Omega$ yields:

$$\Delta V_{REF} = \left(\frac{60^\circ\text{C}}{\text{W}} (0.077\text{W}) + 75^\circ\text{C} \right) \left(\frac{0.2 \text{ mV}}{^\circ\text{C}} \right) + \frac{0.5 \text{ mV}}{\text{V}} (16\text{V})$$

$$\Delta V_{REF} = 24 \text{ mV}$$

The LH0045K (TO-3) under the same operating conditions would exhibit a $\Delta V_{REF} \cong 23 \text{ mV}$.

applications information (con't)

An expression for error in the output current due to ΔV_{REF} is:

$$\frac{\Delta I_S}{I_{SPAN}} (\%) = 100 \frac{(K)(R_{OS})(\Delta V_{REF}) - (1-K)(\Delta V_{REF})(R_F)}{(R_9)(R_{OS})(I_{SPAN})}$$

Where:

ΔV_{REF} = Total change in V_{REF}

$$K = \frac{R_{B2}}{R_{B1} + R_{B2}}$$

R9 = Current set resistor

I_{SPAN} = Change in output current from 0% to 100%

For example, $\Delta V_{REF} = 24$ mV, $K = 0.2$, $R_9 = 100\Omega$, $I_{SPAN} = 16$ mA. Hence, a 0.12% worst case error might be expected in output currents due to ΔV_{REF} effects.

Error Due to V_{OS} Drift

One of the primary causes of error in I_S is caused by V_{OS} drift. Drift may be induced either by self heating of the device or ambient temperature changes. The input offset voltage drift, $\Delta V_{OS}/\Delta T$, is nominally $3.3\mu V/^\circ C$ per millivolt of initial offset. An expression for the total temperature dependent drift is:

$$\Delta V_{OS} = [(\theta)(\Delta P_{DISS}) + \Delta T_A] \frac{\Delta V_{OS}}{\Delta T}$$

Where:

θ = Thermal resistance either junction-to-ambient or junction-to-case

ΔP_{DISS} = Change in average power dissipation

ΔT_A = Change in ambient temperature

The bracketed term may be minimized by heat sinking and using the power minimization technique described under "Thermal Considerations." For the LH0045G design example, $\Delta V_{OS} = 0.352$ mV under ambient conditions and 0.263 mV using a heat-sink and $R_L = 800\Omega$. Comparable V_{OS} for the LH0045K would be 0.254 mV.

The error in output current due to ΔV_{OS} is:

$$\begin{aligned} \frac{\Delta I_S}{I_{SPAN}} (\text{in } \%) &= 100 \times \frac{\Delta V_{OS}}{V_{IN} (\text{FULL SCALE})} \\ &= 100 \times \frac{R_F}{(R)(R_9)(I_{SPAN})} \end{aligned}$$

For the design example, $\Delta V_{OS} = 0.263$ mV, V_{IN} (Full Scale) = 100 mV. Hence, $0.26 \text{ mV} \div 100 \text{ mV}$ or 0.26% worst case error could be expected in output current effects.

Errors Due to Changes in R9

The temperature coefficient of R9 (TCR) will produce errors in the output current. Changes in R9 may be caused by self-heating of the device or by ambient temperature changes.

$$\frac{\Delta I_S}{I_{SPAN}} (\text{in } \%) = 100 \frac{\Delta R_9}{\Delta T} (\theta P_{DISS} + \Delta T_A)$$

Where:

θ = Thermal resistance either from junction-to-ambient or junction-to-case

ΔP_{DISS} = Change in average power dissipation

ΔT_A = Change in ambient temperature

$$\frac{\Delta R_9}{\Delta T} = \text{TCR of } R_9$$

Using the LH0045G design example, $\Delta R_9/\Delta T = 0.03\%/^\circ C$, hence a 3.2% worst case error in output current might be expected for operation without a heat sink over the temperature range.

Heat sinking the device and using $R_L = 800\Omega$, reduces $\Delta I_S/I_{SPAN}$ to 2.3%. Comparable error for the LH0045K would also be about 2.3%.

The error analysis indicates that the internal current set resistor, R9 is inadequate to satisfy high accuracy design criterion. In these instances, an external 100Ω resistor should be substituted for R9.

Obviously, the TCR of the resistor should be low. Metal film or wire-wound resistors are the best choice offering TCR's less than $10 \text{ ppm}/^\circ C$ versus $50 \text{ ppm}/^\circ C$ typical drift for R9.

External Causes of Error

The components external to the LH0045 are also critical in determining errors. Specifically, the composition of resistors R_{B1} , R_{OS} , R_F , R , etc. in the design example will influence both drift and long term stability.

In particular, resistors and potentiometers of wire wound construction are recommended. Also, metal-film resistors with low TCR ($\leq 10 \text{ ppm}/^\circ C$) may be used for fixed resistor applications.

applications information (con't)

Error Analysis Summary

The overall errors attributable to the LH0045 may be minimized using heat sinking, and utilization of an external load resistor. Although R_L reduces the compliance of the circuit, its use is generally advisable in precision applications. External components should be selected for low TCR and long-term stability.

The design example errors, using an external 100Ω wire wound resistor for R_9 equal:

$$\frac{\Delta I_S}{I_{SPAN}} = \underbrace{0.12\%}_{\Delta V_{REF}} + \underbrace{0.26\%}_{\Delta V_{OS}} + \underbrace{0.08\%}_{\Delta R_9} = 0.46\%$$

definition of terms

Input Offset Voltage, V_{OS} : The voltage which must be applied between the input terminals through equal resistances to obtain 4.0 mA of supply (output) current.

Input Bias Current, I_B : The average of the two input currents.

Input Offset Current, I_{OS} : The difference in the current into the two input terminals when the supply (output) current is 4.0 mA.

Input Resistance, R_{IN} : The ratio of the change in input voltage to the change in input current at either input with the other input connected to 1.0 Vdc.

Open Loop Transconductance, g_{MOL} : The ratio of the supply (output) current SPAN to the input voltage required to produce that SPAN.

Open Loop Output Resistance, R_{OUT} : The ratio of a specified supply (output) voltage change to the resulting change in supply (output) current at the specified current level.

SOCKETS AND HEAT SINKS

Mounting sockets, test sockets, and heat sinks are available for the G package and K package.

The following or their equivalents are recommended:

Sockets:

G - 12 lead TO-8: Barnes Corp. #MGX-12
Textool #212-100-323

K - 8 lead TO-3: Keystone Elec. (N.Y.) #4626
or #4627

Heat Sinks

G - 12 lead TO-8: Thermalloy #2240A
Wakefield #215-CB

K - 8 lead TO-3: IERC #LAIC 3B4V

Common Mode Rejection Ratio, CMRR: The ratio of the change in input offset voltage to the peak-to-peak input voltage range.

Power Supply Rejection Ratio, PSRR: The ratio of the change in input offset voltage to the change in supply (output) voltage producing it.

Input Voltage Range, V_{IN} : The range of voltages on the input terminals for which the device operates within specifications.

Open Loop Supply Current, I_S : The supply current required with the signal amplifier A_2 biased off (inverting input positive, non-inverting input negative) and no load on the V_{REF} terminal.

This represents a measure of the minimum low end signal current.

Reference Voltage Line Regulation, $\Delta V_{REF}/\Delta V_S$: The ratio of the change in V_{REF} to the peak-to-peak change in supply (output) voltage producing it.

Reference Voltage Load Regulation, $\Delta V_{REF}/\Delta I_{REF}$: The change in V_{REF} for a stipulated change in I_{REF} .

LH0061/LH0061C 0.5 Amp Wide Band Operational Amplifier

general description

The LH0061/LH0061C is a wide band, high speed, operational amplifier capable of supplying currents in excess of 0.5 ampere at voltage levels of $\pm 12V$. Output short circuit protection is set by external resistors, and compensation is accomplished with a single external capacitor. With a suitable heat sink the device is rated at 20 Watts.

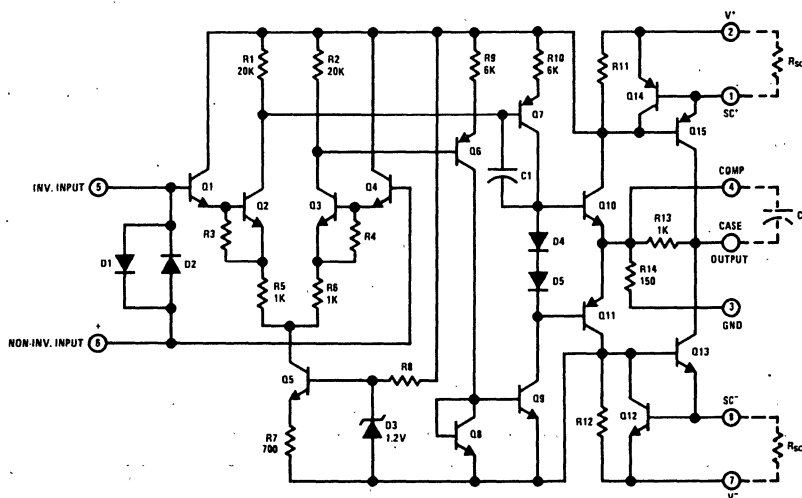
The wide bandwidth and high output power capabilities of the LH0061/LH0061C make it ideal for such applications as AC servos, deflection yoke drivers, capstan drivers, and audio amplifiers. The

LH0061 is guaranteed over the temperature range $-55^{\circ}C$ to $+125^{\circ}C$; whereas, the LH0061C is guaranteed from $-25^{\circ}C$ to $+85^{\circ}C$.

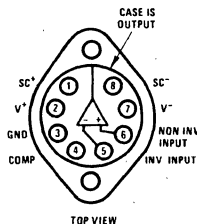
features

- | | |
|-------------------------------|--------------|
| ■ Output current | 0.5 Amp |
| ■ Wide large signal bandwidth | 1 MHz |
| ■ High slew rate | 70V/ μ s |
| ■ Low standby power | 240 mW |
| ■ Low input current | 300 nA Max |

schematic and connection diagrams



TO-3 Package



Order Numbers:

LH0061K ($-55^{\circ}C$ to $+125^{\circ}C$)

LH0061CK ($-25^{\circ}C$ to $+85^{\circ}C$)

See Package KOBA

absolute maximum ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation | See Curve |
| Differential Input Current (Note 2) | ±10 mA |
| Input Voltage (Note 3) | ±15V |
| Peak Output Current | 2A |
| Output Short Circuit Duration (Note 4) | Continuous |
| Operating Temperature Range LH0061 | -55°C to +125°C |
| LH0061C | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

dc electrical characteristics (Note 1)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|---|--|--------|----------|------------|---------|-----------|------------|------------------------------|
| | | LH0061 | | | LH0061C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S \leq 10 \text{ k}\Omega$, $T_C = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $R_S \leq 10 \text{ k}\Omega$, $V_S = \pm 15\text{V}$ | | 1.0 | 4.0 6.0 | | 3.0 10 | 15 | mV mV |
| Voltage Drift with Temperature | $R_S \leq 10 \text{ k}\Omega$ | | 5 | | | 5 | | $\mu\text{V}/^\circ\text{C}$ |
| Offset Voltage Change with Output Power | | | 5 | | | 5 | | $\mu\text{V}/\text{watt}$ |
| Input Offset Current | $T_C = 25^\circ\text{C}$ | | 30 | 100 300 | | 50 | 200 500 | nA nA |
| Offset Current Drift with Temperature | | | 1 | | | 1 | | nA/ $^\circ\text{C}$ |
| Input Bias Current | $T_C = 25^\circ\text{C}$ | | 100 | 300 1.0 | | 200 | 500 1.0 | nA μA |
| Input Resistance | $T_C = 25^\circ\text{C}$ | | 0.3 | 1.0 | | 0.3 | 1.0 | M Ω |
| Input Capacitance | | | | 3 | | | 3 | pF |
| Common Mode Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$, $\Delta V_{\text{CM}} = \pm 10\text{V}$ | | 70 | 90 | | 60 | 80 | dB |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | | ± 11 | | | ± 11 | | V |
| Power Supply Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$, $\Delta V_S = \pm 10\text{V}$ | | 70 | 80 | | 50 | 70 | dB |
| Voltage Gain | $V_S = \pm 15\text{V}$, $V_O = \pm 10\text{V}$ $R_L = 1 \text{ k}\Omega$, $T_C = 25^\circ\text{C}$ $V_S = \pm 15\text{V}$, $V_O = \pm 10\text{V}$ $R_L = 20\Omega$ | | 50 | 100 | | 25 | 50 | V/mV V/mV |
| Output Voltage Swing | $V_S = \pm 15\text{V}$, $R_L = 20\Omega$ | | ± 10 | ± 12 | | ± 10 | ± 12 | V |
| Output Short Circuit Current | $V_S = \pm 15\text{V}$, $T_C = 25^\circ\text{C}$, $R_{\text{SC}} = 1.0\Omega$ | | 600 | | | 600 | | mA |
| Power Supply Current | $V_S = \pm 15\text{V}$, $V_{\text{OUT}} = 0$ | | 7 | 10 | | 10 | 15 | mA |
| Power Consumption | $V_S = \pm 15\text{V}$, $V_{\text{OUT}} = 0$ | | 210 | 300 | | 300 | 450 | mW |

ac electrical characteristics ($T_C = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$, $C_C = 3000 \text{ pF}$)

| | | | | | | | | |
|---------------------------------|--|----|-----|----|----|-----|----|------------------|
| Slew Rate | $A_V = +1$, $R_L = 100\Omega$ | 25 | 70 | | 25 | 70 | | V/ μs |
| Power Bandwidth | $R_L = 100\Omega$ | | 1 | | | 1 | | MHz |
| Small Signal Transient Response | | | 30 | | | 30 | | ns |
| Small Signal Overshoot | | | 5 | 20 | | 10 | 30 | % |
| Settling Time (0.1%) | $\Delta V_{\text{IN}} = 10\text{V}$, $A_V = +1$ | | 0.8 | | | 0.8 | | μs |
| Overload Recovery Time | | | 1 | | | 1 | | μs |
| Harmonic Distortion | $f = 1 \text{ kHz}$, $P_O = 0.5\text{W}$ | | 0.2 | | | 0.2 | | % |

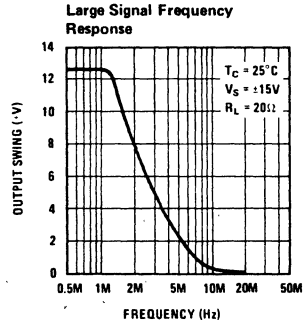
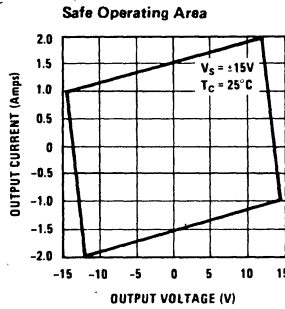
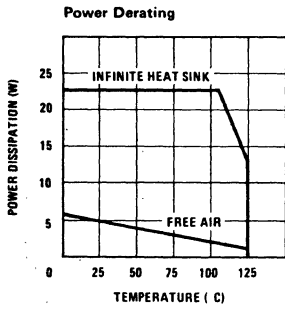
Note 1: Specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$, $C_C = 3000 \text{ pF}$, and $-55^\circ\text{C} \leq T_C \leq +125^\circ\text{C}$ for the LH0061K and $-25^\circ\text{C} \leq T_C \leq +85^\circ\text{C}$ for the LH0061CK. Typical values are for $T_C = 25^\circ\text{C}$.

Note 2: The inputs are shunted with back-to-back diodes for overvoltage protection. Excessive current will flow if a differential voltage in excess of 1V is applied between the inputs without limiting resistors.

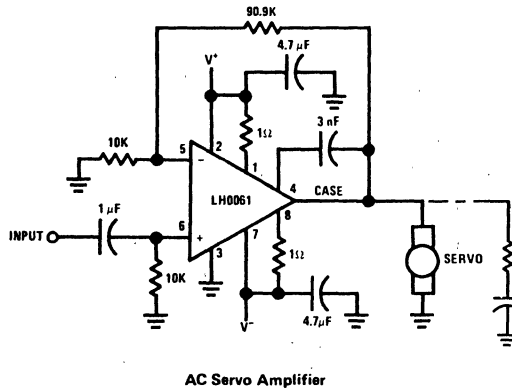
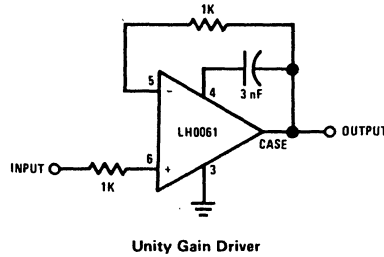
Note 3: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.

Note 4: Rating applies as long as package power rating is not exceeded.

typical performance characteristics



typical applications



LH0062/LH0062C High Speed FET Operational Amplifier

general description

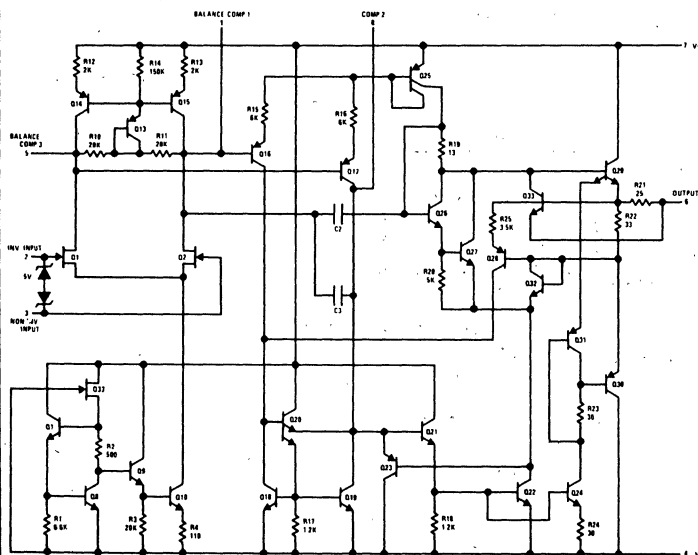
The LH0062/LH0062C is a precision, high speed FET input operational amplifier with more than an order of magnitude improvement in slew rate and bandwidth over conventional FET IC op amps. In addition it features very closely matched input characteristics, very high input impedance, and ultra low input currents with no compromise in noise, common mode rejection ratio or open loop gain. The device has internal unity gain frequency compensation, thus assuring stability in all normal applications. This considerably simplifies its application, since no external components are necessary for operation. However, unlike most internally compensated amplifiers, external frequency compensation may be added for optimum performance. For inverting applications, feed-forward compensation will boost the slew rate to over 120 V/ μ s and almost double the bandwidth. (See LB-2, LB-14, and LB-17 for discussions of the application of feed-forward techniques). Over-compensation can be used with the amplifier for greater stability when maximum bandwidth is not needed. Further, a single capacitor can be added to reduce the 0.1% settling time to under 1 μ s. In addition it is free of latch-up and may be simply offset nulled with negligible effect on offset drift or CMRR.

The LH0062 is designed for applications requiring wide bandwidth, high slew rate and fast settling time while at the same time demanding the high input impedance and low input currents characteristic of FET inputs. Thus it is particularly suited for such applications as video amplifiers, sample/hold circuits, high speed integrators, and buffers for A/D conversion and multiplex system. The LH0062 is specified for the full military temperature range of -55° to $+125^{\circ}$ C while the LH0062C is specified to operate over a -25° C to $+85^{\circ}$ C temperature range.

features

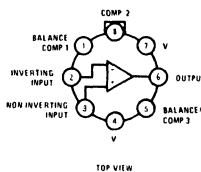
- High slew rate 70 V/ μ s
- Wide bandwidth 15 MHz
- Settling time (0.1%) 1 μ s
- Low input offset voltage 2 mV
- Low input offset current 1 pA
- Wide supply range ± 5 V to ± 20 V
- Internal 6 dB/octave frequency compensation
- Pin compatible with std IC op amps (TO-5 pkg)

schematic and connection diagrams*



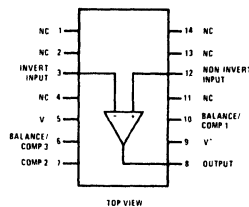
*Pin Numbers Shown for TO-5 Package

Metal Can Package



Order Number
LH0062H or LH0062CH
See Package H08A

Dual-In-Line Package



Order Number
LH0062D or LH0062CD
See Package D14E

absolute maximum ratings

| | | | |
|-------------------------------------|------------|--------------------------------------|-----------------|
| Supply Voltage | ±20V | Operating Temperature | |
| Power Dissipation (see graph) | 500 mW | LH0062, | -55°C to +125°C |
| Input Voltage (Note 1) | ±5V | LH0062C, | -25°C to +85°C |
| Differential Input Voltage (Note 2) | ±30V | Storage Temperature Range | -65°C to +150°C |
| Short Circuit Duration | Continuous | Lead Temperature (Soldering, 10 sec) | 300°C |

dc electrical characteristics (Note 3)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS | |
|---|--|----------|----------------------------------|-----|----------|----------------------------------|-----|------------------------------|----------|
| | | LH0062 | | | LH0062C | | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | | |
| Input Offset Voltage | $R_S \leq 100 \text{ k}\Omega$; $T_A = 25^\circ\text{C}$ | | 2 | 5 | | 10 | 15 | mV | |
| | $R_S \leq 100 \text{ k}\Omega$ | | | 7 | | | 20 | mV | |
| Temperature Coefficient of Input Offset Voltage | $R_S \leq 100 \text{ k}\Omega$ | | 5 | 25 | | 10 | 35 | $\mu\text{V}/^\circ\text{C}$ | |
| Offset Voltage Drift with Time | | | 4 | | | 5 | | $\mu\text{V}/\text{week}$ | |
| Input Offset Current | $T_A = 25^\circ\text{C}$ | | 0.2 | 2 | | 1 | 5 | pA | |
| | | | | 2 | | | 0.2 | nA | |
| Temperature Coefficient of Input Offset Current | | | Doubles every 10°C | | | Doubles every 10°C | | | |
| Offset Current Drift with Time | | | 0.1 | | | 0.1 | | pA/week | |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 5 | 10 | | 10 | 65 | pA | |
| | | | | 10 | | | 2 | nA | |
| Temperature Coefficient of Input Bias Current | | | Doubles every 10°C | | | Doubles every 10°C | | | |
| Differential Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω |
| Common Mode Input Resistance | | | 10^{12} | | | 10^{12} | | | Ω |
| Input Capacitance | | | 4 | | | 4 | | | pF |
| Input Voltage Range | $V_S = \pm 15\text{V}$ | ± 10 | ± 12 | | ± 10 | ± 12 | | V | |
| Common Mode Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$, $V_{IN} = \pm 10\text{V}$ | 80 | 90 | | 70 | 90 | | dB | |
| Supply Voltage Rejection Ratio | $R_S \leq 10 \text{ k}\Omega$, $\pm 5\text{V} \leq V_S \leq \pm 15\text{V}$ | 80 | 90 | | 70 | 90 | | dB | |
| Large Signal Voltage Gain | $R_L = 2 \text{ k}\Omega$, $V_{OUT} = \pm 10\text{V}$, $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | 50 | 200 | | 25 | 160 | | V/mV | |
| | $R_L = 2 \text{ k}\Omega$, $V_{OUT} = \pm 10\text{V}$, $V_S = \pm 15\text{V}$ | | 25 | | 25 | | | V/mV | |
| Output Voltage Swing | $R_L = 2 \text{ k}\Omega$, $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | ± 12 | ± 13 | | ± 12 | ± 13 | | V | |
| | $R_L = 2 \text{ k}\Omega$, $V_S = \pm 15\text{V}$ | ± 10 | | | ± 10 | | | V | |
| Output Current Swing | $V_{OUT} = \pm 10\text{V}$, $T_A = 25^\circ\text{C}$ | ± 10 | ± 15 | | ± 10 | ± 15 | | mA | |
| Output Resistance | | | 75 | | 75 | | | Ω | |
| Output Short Circuit Current | $T_A = 25^\circ\text{C}$ | | 25 | | 25 | | | mA | |
| Supply Current | $V_S = \pm 15\text{V}$ | | 5 | 8 | | 7 | 12 | mA | |
| Power Consumption | $V_S = \pm 15\text{V}$ | | | 240 | | | 360 | mW | |

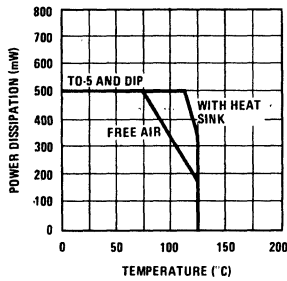
ac electrical characteristics ($T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|------------------------|---|--------|-----|-----|---------|-----|-----|------------------------------|
| | | LH0062 | | | LH0062C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Slew Rate | Voltage Follower | 50 | 70 | | 50 | 70 | | V/ μs |
| Large Signal Bandwidth | Voltage Follower | | 2 | | | 2 | | MHz |
| Small Signal Bandwidth | | | 15 | | | 15 | | MHz |
| Rise Time | | | 25 | | | 25 | | ns |
| Overshoot | | | 10 | | | 15 | | % |
| Settling Time (0.1%) | $\Delta V_{IN} = 10\text{V}$ | | 1 | | | 1 | | μs |
| Overload Recovery | | | 0.9 | | | 0.9 | | μs |
| Input Noise Voltage | $R_S = 10 \text{ k}\Omega$, $f_o = 10 \text{ Hz}$ | | 150 | | | 150 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10 \text{ k}\Omega$, $f_o = 100 \text{ Hz}$ | | 55 | | | 55 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10 \text{ k}\Omega$, $f_o = 1 \text{ kHz}$ | | 35 | | | 35 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $R_S = 10 \text{ k}\Omega$, $f_o = 10 \text{ kHz}$ | | 30 | | | 30 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| Input Noise Voltage | $\text{BW} = 10 \text{ Hz to } 10 \text{ kHz}$, $R_S = 10 \text{ k}\Omega$ | | 12 | | | 12 | | μVrms |
| Input Noise Current | $\text{BW} = 10 \text{ Hz to } 10 \text{ kHz}$ | | <.1 | | | <.1 | | pArms |

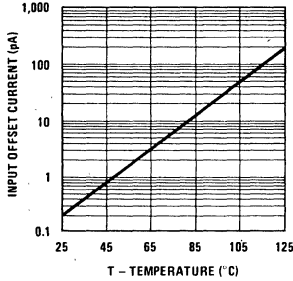
Note 1: For supply voltages less than $\pm 15\text{V}$, the absolute maximum input voltage is equal to the supply voltage.
Note 2: Inputs are protected from excessive voltages by back-to-back diodes. Input currents should be limited to 1 mA.
Note 3: Unless otherwise specified, these specifications apply for $\pm 5\text{V} \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LH0062 and $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ for LH0062C. Typical values are given for $T_A = 25^\circ\text{C}$. Power supplies should be bypassed with 0.1 μF ceramic capacitors.

typical performance characteristics

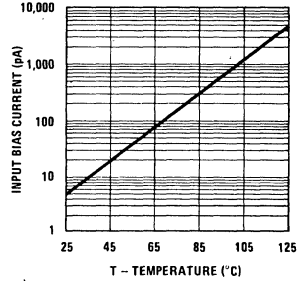
Maximum Power Dissipation



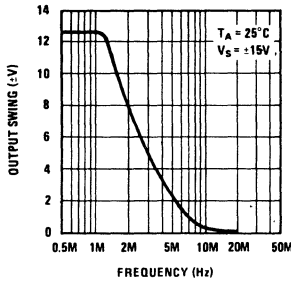
Input Offset Current vs Temperature



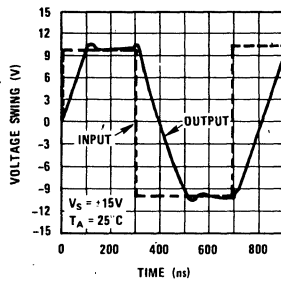
Input Bias Current vs Temperature



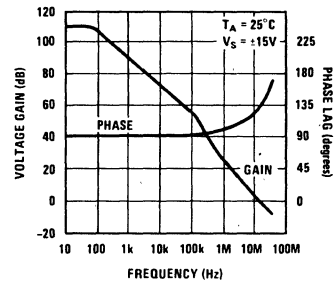
Large Signal Frequency Response



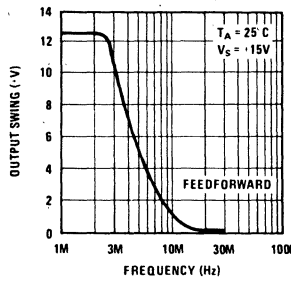
Voltage Follower Pulse Response



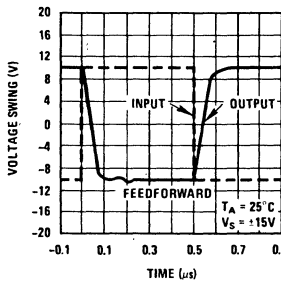
Open Loop Frequency Response



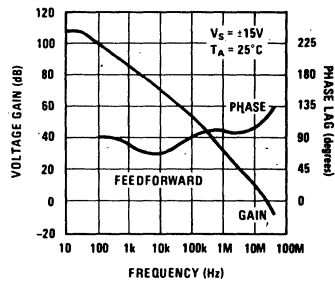
Large Signal Frequency Response



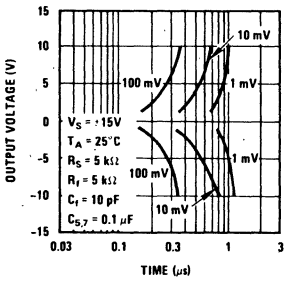
Inverter Pulse Response



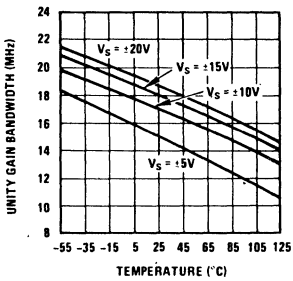
Open Loop Frequency Response



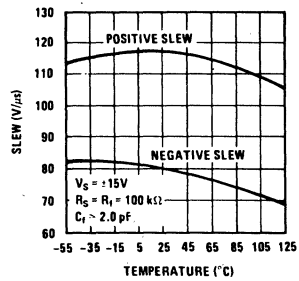
Inverter Settling Time



Unity Gain Bandwidth

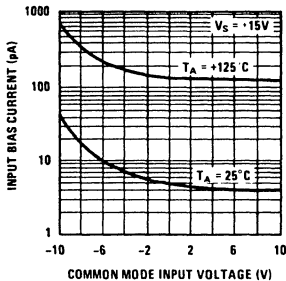


Voltage Follower Slew Rate

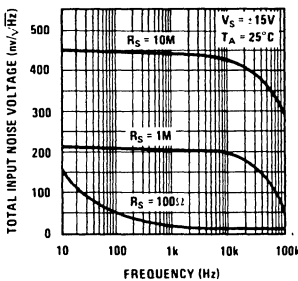


typical performance characteristics (con't)

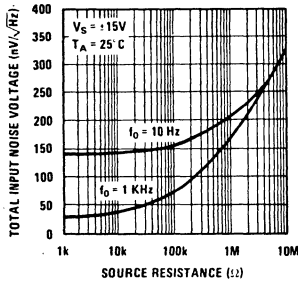
Input Bias Current vs Input Voltage



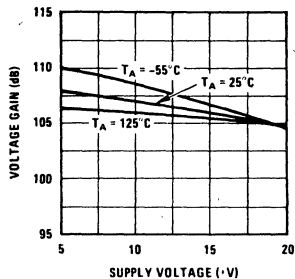
Total Input Noise Voltage* vs Frequency



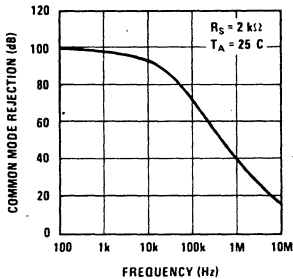
Total Input Noise Voltage* vs Source Resistance



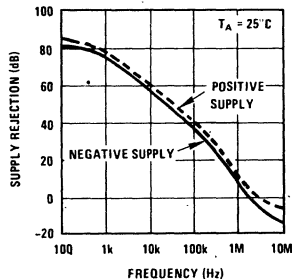
Voltage Gain



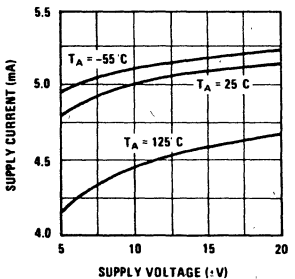
Common Mode Rejection



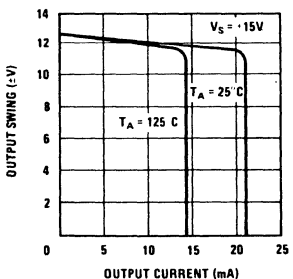
Power Supply Rejection



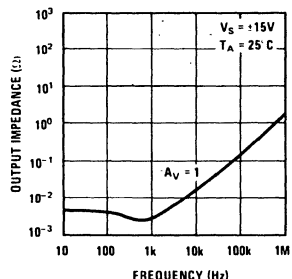
Supply Current



Current Limiting



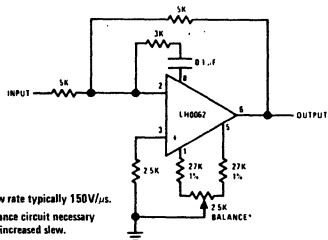
Closed Loop Output Impedance



*Noise Voltage Includes Contribution from Source Resistance

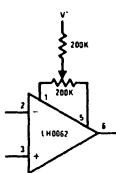
auxiliary circuits

Feedforward Compensation for Greater Inverting Slew Rate†

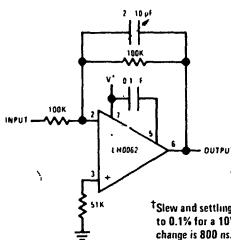


†Slew rate typically 150V/μs.
*Balance circuit necessary for increased slew.

Offset Balancing



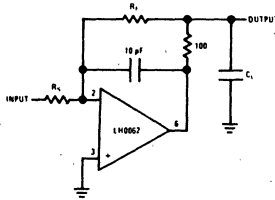
Compensation for Minimum Settling† Time



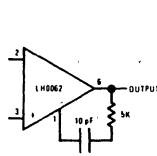
†Slow and settling time to 0.1% for a 10V step change is 800 ns.

auxiliary circuits (con't)

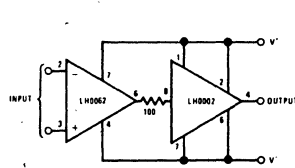
Isolating Large Capacitive Loads



Overcompensation

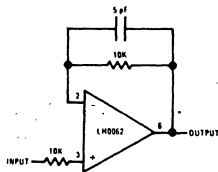


Boosting Output Drive to +100 mA

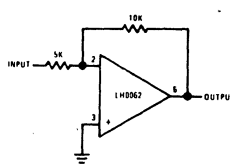


typical applications*

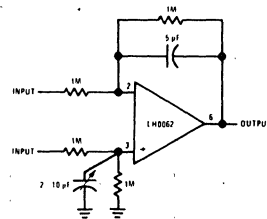
Fast Voltage Follower



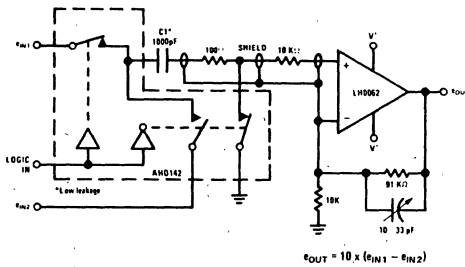
Fast Summing Amplifier



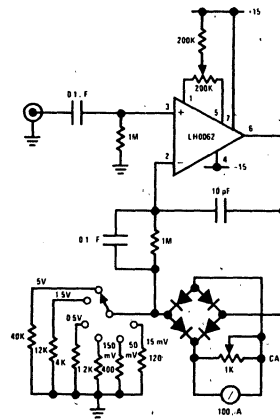
Differential Amplifier



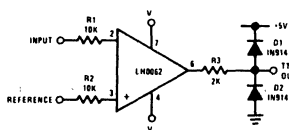
High Speed Subtractor



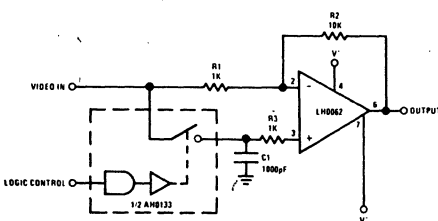
Wide Range AC Voltmeter



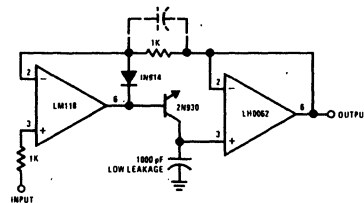
Fast Precision Voltage Comparator



Video DC Restoring Amplifier



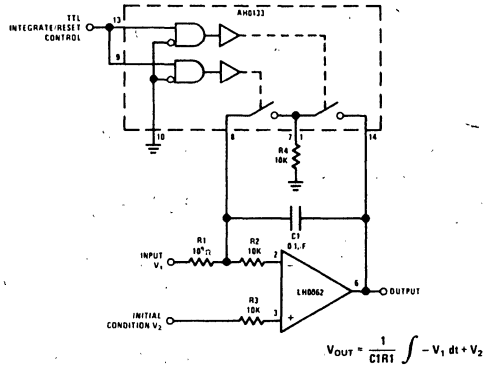
High Speed Positive Peak Detector



*Pin numbers shown for TO-5 package

typical applications* (con't)

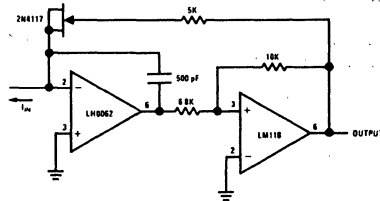
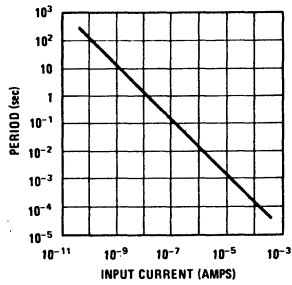
Precision Integrator



*Pin numbers shown for TO-5 package

3

Precision Wide Range Current to Period Converter



LH2110/LH2210/LH2310 Dual Voltage Follower

general description

The LH2110 series of dual voltage followers are two LM110 type followers in a single hermetic package. Featuring all the same performance characteristics of the single, these duals offer in addition closer thermal tracking, lower weight, reduced insertion cost and smaller size than two singles. For additional information, see the LM110 data sheet and National's Linear Application Notebook.

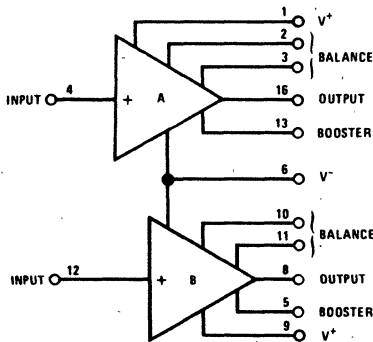
The LH2110 is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LH2210 is specified for operation over the -25°C to $+85^{\circ}\text{C}$ temperature range. The LH2310 is speci-

fied for operation over the 0°C to $+70^{\circ}\text{C}$ temperature range.

features

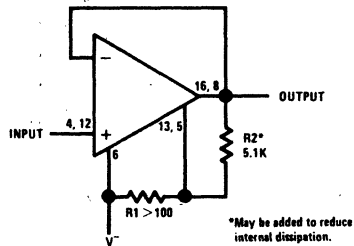
- Low input current 1 nA
- High input resistance 10^{10} ohms
- High slew rate $30\text{V}/\mu\text{s}$
- Wide bandwidth 20 MHz
- Wide operating supply range $\pm 5\text{V}$ to $\pm 18\text{V}$
- Output short circuit proof

connection diagram

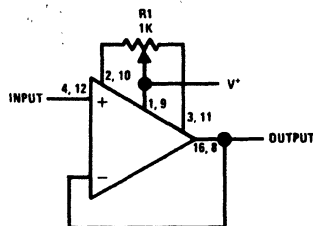


Order Number LH2110D or LH2210D or LH2310D
See Package D16C

auxiliary circuits



Increasing Negative Swing Under Load



Offset Balancing Circuit

absolute maximum ratings

| | | | | |
|--|------------|--------------------------------------|--------|----------------|
| Supply Voltage | ±18V | Operating Temperature Range | LH2110 | -55°C to 125°C |
| Power Dissipation (Note 1) | 500 mW | | LH2210 | -25°C to 85°C |
| Input Voltage (Note 2) | ±15V | | LH2310 | 0°C to 70°C |
| Output Short Circuit Duration (Note 3) | Continuous | Storage Temperature Range | | -65°C to 150°C |
| | | Lead Temperature (Soldering, 10 sec) | | 300°C |

electrical characteristics Each side (Note 4)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---------------------------------|--|-----------|-----------|-----------|----------------------------------|
| | | LH2110 | LH2210 | LH2310 | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$ | 4.0 | 4.0 | 7.5 | mV Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 3.0 | 3.0 | 7.0 | nA Max |
| Input Resistance | $T_A = 25^\circ\text{C}$ | 10^{10} | 10^{10} | 10^{10} | Ω Min |
| Input Capacitance | | 1.5 | 1.5 | 1.5 | pF Typ |
| Large Signal Voltage Gain | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ $V_{OUT} = \pm 10\text{V}$, $R_L = 8\text{ k}\Omega$ | .999 | .999 | .999 | V/V Min |
| Output Resistance | $T_A = 25^\circ\text{C}$ | 2.5 | 2.5 | 2.5 | Ω Max |
| Supply Current (Each Amplifier) | $T_A = 25^\circ\text{C}$ | 5.5 | 5.5 | 5.5 | mA Max |
| Input Offset Voltage | | 6.0 | 6.0 | 10 | mV Max |
| Offset Voltage | $-55^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ | 6 | 6 | 10 | $\mu\text{V}/^\circ\text{C}$ Typ |
| Temperature Drift | $T_A = 125^\circ\text{C}$ | 12 | 12 | — | $\mu\text{V}/^\circ\text{C}$ Typ |
| Input Bias Current | | 10 | 10 | 10 | nA Max |
| Large Signal Voltage Gain | $V_S = \pm 15\text{V}$, $V_{OUT} = \pm 10\text{V}$ $R_L = 10\text{ k}\Omega$ | .999 | .999 | .999 | V/V Min |
| Output Voltage Swing (Note 5) | $V_S = \pm 15\text{V}$, $R_L = 10\text{ k}\Omega$ | ±10 | ±10 | ±10 | V Min |
| Supply Current (Each Amplifier) | $T_A = 125^\circ\text{C}$ | 4.0 | 4.0 | — | mA Max |
| Supply Voltage Rejection Ratio | $\pm 5\text{V} \leq V_S \leq \pm 18\text{V}$ | 70 | 70 | 70 | dB Min |

Note 1: The maximum junction temperature of the LH2110 is 150°C, while that of the LH2210 is 100°C and that of the LH2310 is 85°C. For operating devices in the flat package at elevated temperatures, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with 0.03-inch-wide, 2-ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 2: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 3: Continuous short circuit is allowed for case temperatures to 125°C and ambient temperatures to 70°C. It is necessary to insert a resistor greater than 2 k Ω in series with the input when the amplifier is driven from low impedance sources to prevent damage when the output is shorted.

Note 4: These specifications apply for $\pm 5\text{V} < V_S \leq \pm 18\text{V}$ and $-55^\circ\text{C} < T_A \leq 125^\circ\text{C}$, unless otherwise specified. With the LM210, however, all temperature specifications are limited to $-25^\circ\text{C} < T_A \leq 85^\circ\text{C}$, and for the LH2310, all temperature specifications are limited to $0^\circ\text{C} \leq T_A < 70^\circ\text{C}$.

Note 5: Increased output swing under load can be obtained by connecting an external resistor between the booster and V^- terminals.



Section 4
**Instrumentation
Amplifiers**

4



Section Contents

| | |
|--|-------|
| Special Function Instrumentation Amplifier Guide..... | 4-iii |
| Definition of Terms..... | 4-iv |
| LF152/LF352 FET Input Instrumentation Amplifier..... | 4-1 |
| LM121/LM221/LM321, LM121A/LM221A/LM321A Precision Preamplifiers..... | 4-11 |

Note. For additional information on instrumentation amplifiers, see National Semiconductor's Special Functions Databook.

All of the amplifiers in this guide are true differential input instrumentation amplifiers with very high common mode rejection and adjustable gain.

| Features | I _B Max | V _{OSin} Max | Characteristics | | Gain Tempco | Gain Error | Part Number | | ** Page Number |
|---|--------------------|-----------------------|----------------------------------|----------------|----------------------|------------------|---------------|----------------|-------------------|
| | | | $\frac{\Delta V_{OS}}{\Delta T}$ | Gain Lin. | | | -25°C to 85°C | -55°C to 125°C | |
| 90μW dissipation, wide supply range, one external gain set resistor | 125 nA 100 nA | 2 mV 1 mV | 10 μV/°C 10 μV/°C | 0.03% 0.03% | * | 3% max 1% max | LH0036C | LH0036 | 3-4 |
| Low cost, one external gain set resistor | 500 nA | 2 mV 1 mV | 10 μV/°C 10 μV/°C | 0.03% 0.03% | * * | 1% 0.3% | LH0037C | LH0037 | 3-12 |
| Ultra low drift, all gain set resistors internal, very low noise, very linear, guard drive amplifier included | 100 nA | 150 μV 100 μV | 1 μV/°C max 0.25 μV/°C max | 1 ppm 1 ppm | 7 ppm/°C 7 ppm/°C | 0.1% 0.1% | LH0038C | LH0038 | 3-15 |

*Dependent upon external resistors.

**Refers to Special Functions Databook, 1979 edition



Definition of Terms

Bandwidth: That frequency at which the voltage gain is reduced to $1/\sqrt{2}$ times the low frequency value.

Common-Mode Rejection Ratio: The ratio of the input common-mode voltage range to the peak-to-peak change in input offset voltage over this range.

Harmonic Distortion: That percentage of harmonic distortion being defined as one-hundred times the ratio of the root-mean-square (rms) sum of the harmonics to the fundamental. % harmonic distortion =

$$\frac{(V_2^2 + V_3^2 + V_4^2 + \dots)^{1/2}}{V_1} (100\%)$$

where V_1 is the rms amplitude of the fundamental and V_2, V_3, V_4, \dots are the rms amplitudes of the individual harmonics.

Input Bias Current: The average of the two input currents.

Input Common-Mode Voltage Range: The range of voltages on the input terminals for which the amplifier is operational. Note that the specifications are not guaranteed over the full common-mode voltage range unless specifically stated.

Input Impedance: The ratio of input voltage to input current under the stated conditions for source resistance (R_S) and load resistance (R_L).

Input Offset Current: The difference in the currents into the two input terminals when the output is at zero.

Input Offset Voltage: That voltage which must be applied between the input terminals through two equal resistances to obtain zero output voltage.

Input Resistance: The ratio of the change in input voltage to the change in input current on either input with the other grounded.

Input Voltage Range: The range of voltages on the input terminals for which the amplifier operates within specifications.

Large-Signal Voltage Gain: The ratio of the output voltage swing to the change in input voltage required to drive the output from zero to this voltage.

Output Impedance: The ratio of output voltage to output current under the stated conditions for source resistance (R_S) and load resistance (R_L).

Output Resistance: The small signal resistance seen at the output with the output voltage near zero.

Output Voltage Swing: The peak output voltage swing, referred to zero, that can be obtained without clipping.

Offset Voltage Temperature Drift: The average drift rate of offset voltage for a thermal variation from room temperature to the indicated temperature extreme.

Power Supply Rejection: The ratio of the change in input offset voltage to the change in power supply voltages producing it.

Settling Time: The time between the initiation of the input step function and the time when the output voltage has settled to within a specified error band of the final output voltage.

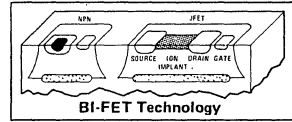
Slew Rate: The internally-limited rate of change in output voltage with a large-amplitude step function applied to the input.

Supply Current: The current required from the power supply to operate the amplifier with no load and the output midway between the supplies.

Transient Response: The closed-loop step-function response of the amplifier under small-signal conditions.

Unity Gain Bandwidth: The frequency range from dc to the frequency where the amplifier open loop gain rolls off to one.

Voltage Gain: The ratio of output voltage to input voltage under the stated conditions for source resistance (R_S) and load resistance (R_L).



LF152/LF352 FET Input Instrumentation Amplifier

General Description

The LF152 series is the first monolithic JFET input instrumentation amplifier. The well-matched high voltage JFET input devices provide very high input impedance and extremely low bias currents, making the LF152 ideal in applications where high source impedances are encountered.

The LF152 very accurately amplifies a differential input signal and rejects common-mode signal and noise. It is not an op amp, but operates with an internal closed loop gain connection which allows good linearity with no external feedback. The LF152 eliminates the need for extremely precise resistor matching to obtain high common-mode rejection (CMR) and provides high input impedance as compared to the use of conventional op amps connected as a difference amplifier.

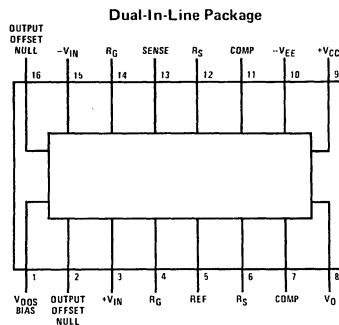
The LF152 utilizes internal differential current feedback eliminating the need for precision external feedback components. The amplifier gain can be easily adjusted from 1 to 1000 by changing the value of a single resistor. The transfer function for the LF152 is highly

accurate because it has a very low initial gain error and non-linearity. The bandwidth and slew rate are externally controlled and the sense input and device output are pinned out separately for added versatility.

Features

- JFET inputs
- High input impedance $2 \times 10^{12} \Omega$
- Low bias currents 3 pA
- Low noise currents 0.01 pA rms
- Low gain nonlinearity 0.02%
- High common-mode rejection ratio 110 dB min (G = 100)
- Single resistor gain adjust
- External compensation for extended gain and frequency ranges
- Both input and output offset adjust capability to allow a change of gain without rezeroing
- Low supply current 1 mA

Connection Diagram



Order Number LF152D
or LF352D
See NS Package D16C

Simplified Schematic

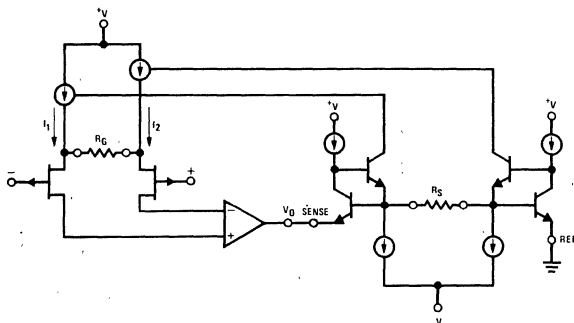


FIGURE 1

Typical Circuit

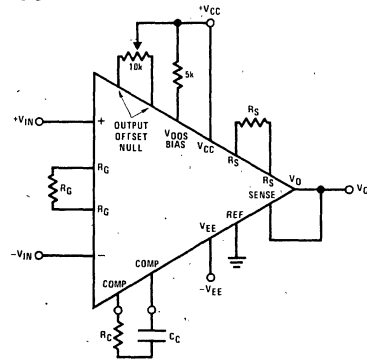


FIGURE 2

Absolute Maximum Ratings

| | LF152 | LF352 |
|--|---------------------------------|---------------------------------|
| Supply Voltage | ±22V | ±18V |
| Differential Input Voltage | ±44V | ±36V |
| Input Voltage Range | ±22V | ±18V |
| Output Short Circuit Duration | Continuous | Continuous |
| Power Dissipation and Thermal Resistance (Note 1) | | |
| Cavity DIP (D) P_D (25°C) | 900 mW | 900 mW |
| θ_{jA} | 100°C/W | 100°C/W |
| Maximum Junction Temperature | +150°C | +100°C |
| Operating Temperature Range | -55°C ≤ T _A ≤ +125°C | 0°C ≤ T _A ≤ +70°C |
| Storage Temperature Range | -65°C ≤ T _A ≤ +150°C | -65°C ≤ T _A ≤ +150°C |
| Lead Temperature (Soldering, 60 seconds) | 300°C | 300°C |

DC Electrical Characteristics (Notes 2 and 3)

| PARAMETER | CONDITIONS | LF152 | | | LF352 | | | UNITS | |
|------------------------------------|---|--|-----|-----|--------------------|------|------|--------|----|
| | | MIN | TYP | MAX | MIN | TYP | MAX | | |
| G _R | Gain Range | R _C = 160Ω, C _C = 0.002μF | | | 1 | | | | |
| G | Gain Equation | G = R _S /R _G | | | | | | | |
| G _E | Error From Gain Equation | T _A = 25°C, G = 1-100, R _L = 10k | | | 0.05 | 0.1 | 0.05 | 0.2 | % |
| G _{NL} | Gain Nonlinearity | T _A = 25°C, G = 1-100, R _L = 10k | | | 0.02 | 0.05 | 0.02 | 0.1 | % |
| ΔG/ΔT | Gain Temperature Coefficient | | | | 3 | | | ppm/°C | |
| V _O | Output Voltage Range | R _L = 2k | | | ±9 | | | V | |
| R _O | Output Resistance | T _A = 25°C, G = 1 | | | 1.2 | | | Ω | |
| V _{IN} | Input Voltage Range | | | | ±10 | | | V | |
| I _B | Input Bias Current | T _A = 25°C | | | 3 | 20 | 3 | 40 | pA |
| I _{IO} | Input Offset Current | T _A = 25°C | | | 3 | 20 | 0.2 | 3 | nA |
| | | | | | 0.5 | 10 | 0.5 | 20 | pA |
| | | | | | 0.3 | 2.0 | 0.05 | 0.6 | nA |
| R _{IN} | Input Resistance | T _A = 25°C | | | | | | | |
| | Differential | | | | 2x10 ¹² | | | Ω | |
| | Common-Mode | | | | 2x10 ¹² | | | Ω | |
| C _{IN} | Input Capacitance | T _A = 25°C | | | | | | | |
| | Differential | | | | 2.5 | | | pF | |
| | Common-Mode | | | | 5.0 | | | pF | |
| CMRR | Common-Mode Rejection (RTI) (Note 4) | G = 1 | | | 75 | 85 | 65 | 80 | dB |
| | | G = 10 | | | 95 | 105 | 85 | 100 | dB |
| | | G = 100 | | | 110 | 125 | 100 | 120 | dB |
| | | G = 1000 | | | 115 | 125 | 105 | 120 | dB |
| V _{IOS} | Input Offset Voltage | T _A = 25°C | | | 8 | 15 | 15 | 30 | mV |
| ΔV _{IOS} /ΔT | Temperature Coefficient | | | | 10 | | | μV/°C | |
| ΔV _{IOS} /ΔV _S | Supply Sensitivity | | | | 100 | | | μV/V | |
| V _{OOS} | Output Offset Voltage | T _A = 25°C | | | | | | | |
| ΔV _{OOS} /ΔT | Temperature Coefficient | | | | 600 | | | μV/°C | |
| ΔV _{OOS} /ΔV _S | Supply Sensitivity | | | | 400 | | | μV/V | |
| I _{REF} | Reference Current | | | | 15 | | | μA | |
| R _{REF} | Reference Input Resistance | | | | 500 | | | MΩ | |
| I _S | Supply Current | T _A = 25°C | | | 0.7 | 2.2 | 1.2 | 2.2 | mA |

AC Electrical Characteristics (Notes 2 and 3)

| PARAMETER | CONDITIONS | LF152 | | | LF352 | | | UNITS |
|-----------|------------------------------|--|-----|-----|-------|---------------|-----|---------------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| e_n | Noise Voltage (RTI) (Note 5) | $T_A = 25^\circ\text{C}$ 0.1 Hz – 10 Hz 10 Hz – 10 kHz | | | 1.3 | 670/G | | $\mu\text{V/p-p}$ μVrms |
| i_n | Noise Current (RTI) (Note 5) | $T_A = 25^\circ\text{C}$, 10 Hz – 10 kHz | | | 0.01 | | | pArms |
| GBW | Small Signal Bandwidth | $T_A = 25^\circ\text{C}$, ± 3 dB | | | | | | |
| | | G = 1 | | | 140 | | | kHz |
| | | G = 10 | | | 50 | | | kHz |
| | | G = 100 | | | 30 | | | kHz |
| | | G = 1000 | | | 7 | | | kHz |
| | | $T_A = 25^\circ\text{C}$, $\pm 1\%$ Flatness | | | | | | |
| | | G = 1 | | | 5 | | | kHz |
| | | G = 10 | | | 4 | | | kHz |
| PBW | Full-Power Bandwidth | | | | 25 | | | kHz |
| | | G = 100 | | | 2 | | | kHz |
| | | G = 1000 | | | 1.5 | | | kHz |
| | | | | | 200 | | | μs |
| SR | Slew Rate | | | | 1 | | | V/ μs |
| t_s | Settling Time 0.1% | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | G = 1 | | | 15 | | | μs |
| | | G = 10 | | | 15 | | | μs |
| | | G = 100 | | | 40 | | | μs |
| G = 1000 | | | 200 | | | μs | | |

Note 1: The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by $T_j \text{ MAX}$, θ_{jA} , and the ambient temperature, T_A . The maximum available power dissipation at any temperature is $P_D = (T_j \text{ MAX} - T_A)/\theta_{jA}$ or the 25°C $P_D \text{ MAX}$, whichever is less.

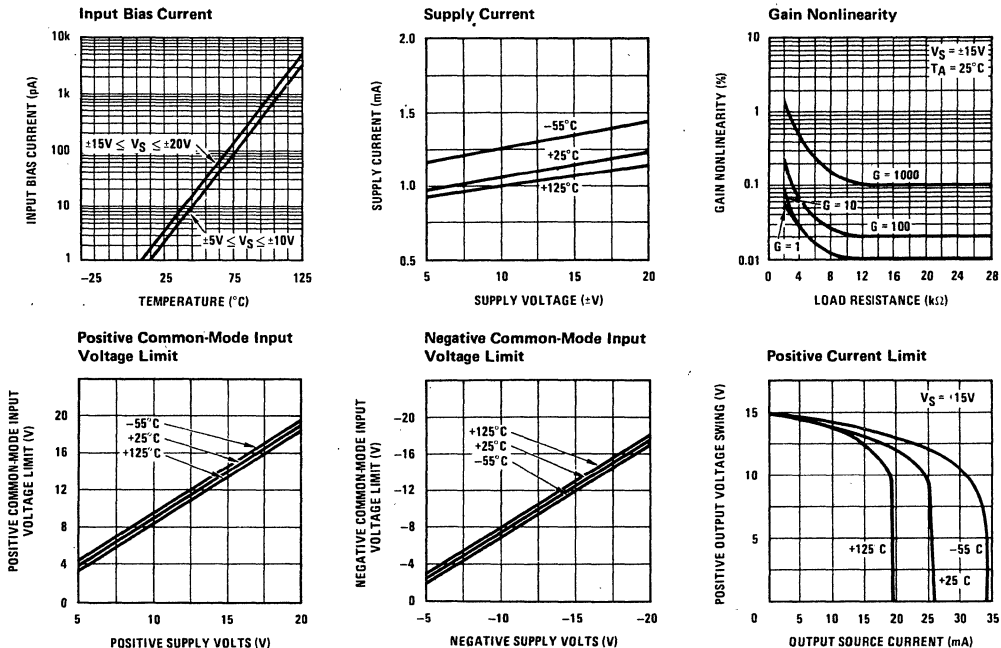
Note 2: These specifications apply for $V_S = \pm 15\text{V}$ and over the absolute maximum operating temperature range ($T_L \leq T_A \leq T_H$) unless otherwise noted. Parameters are specified for $R_C = 160\Omega$, $C_C = 0.002\mu\text{F}$, and a proper layout such as the PC board in Figure 7, which is laid out for Figure 2 and Figure 4.

Note 3: If VOOS adjust is not used, pins 1, 2 and 16 MUST be shorted to V_{CC} .

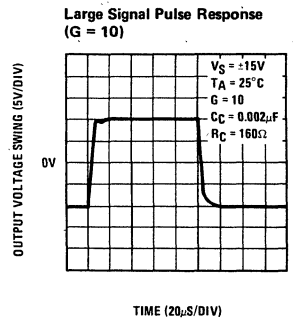
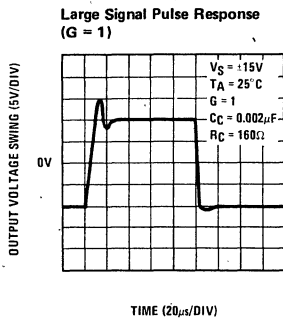
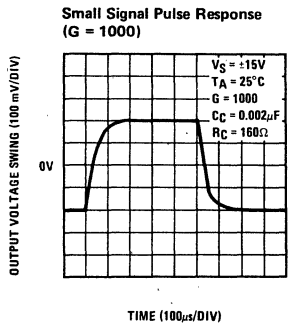
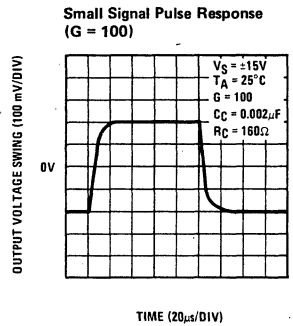
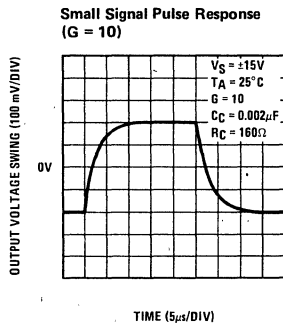
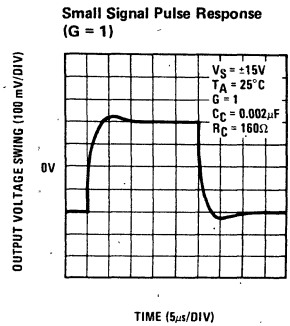
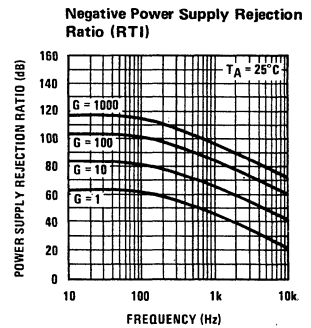
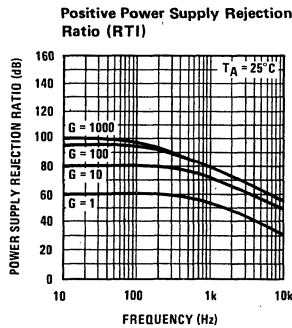
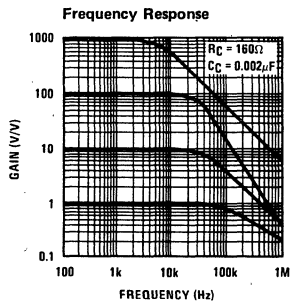
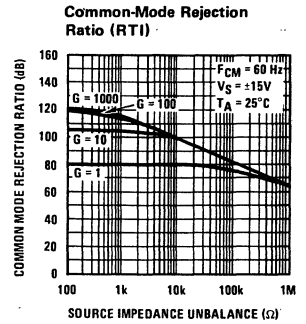
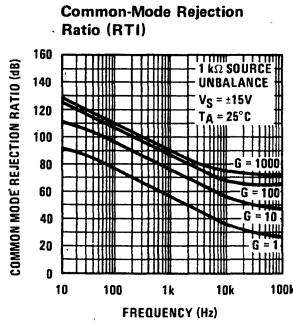
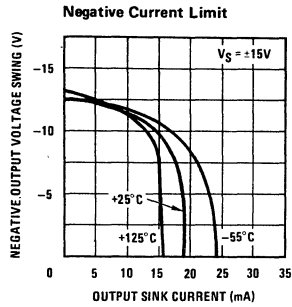
Note 4: Referred to input (RTI). May be referred to output by subtracting gain in dB.

Note 5: Referred to input (RTI). May be referred to output by multiplying by gain G.

Typical Performance Characteristics

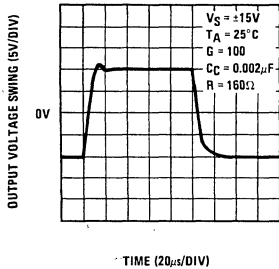


Typical Performance Characteristics (Continued)

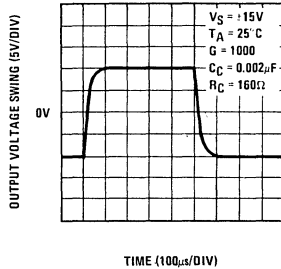


Typical Performance Characteristics (Continued)

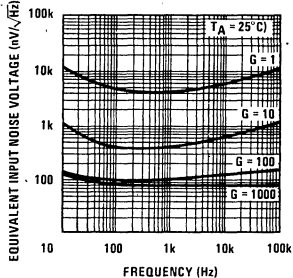
Large Signal Pulse Response
(G = 100)



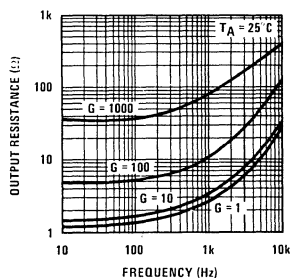
Large Signal Pulse Response
(G = 1000)



Equivalent Input Noise Voltage



Output Resistance



Application Hints

BASIC OPERATION

The LF152 is a monolithic JFET input differential current feedback instrumentation amplifier. The BIFET process used to fabricate the LF152 makes it possible to take advantage of JFETs throughout the design. In the simplified schematic of *Figure 1*, the differential input voltage is impressed across resistor R_G via the input JFETs, while the difference between the sense and reference voltages is impressed across the resistor R_S . The gain of the amplifier is determined by the ratio of resistor R_S to resistor R_G ($G = R_S/R_G$). (For clarity let's follow a signal through the amplifier:)

In *Figure 1*, let $R_G = R_S = 1 \text{ M}\Omega$, the (-) input be grounded, and the (+) input be 1V; the output should be 1V. The 1V signal applied develops $1\mu\text{A}$ through R_G from right to left and unbalances the current drive to the second stage amplifier. The additional current driven into the (+) input of the second stage amplifier causes the output to increase. As V_O increases, the sense input voltage increases and the left side of R_S also increases. When the sense input has risen 1V, $1\mu\text{A}$ will flow through R_S from left to right and, thus, subtract $1\mu\text{A}$ from I_1 . An opposite action simultaneously occurs in I_2 which brings the currents into the second stage and thus the system back into balance.

The LF152 series is designed to optimize key parameters in instrumentation amplifiers. The device has very high

common-mode rejection, low gain non-linearity, extremely low bias currents and very high input impedance.

INPUTS

The P-channel JFET input devices of the LF152 series provide very low bias currents and very high input impedances.

The maximum differential input voltage is independent of the supply voltages, however, neither of the input voltages should be allowed to exceed the negative supply, as this will cause large currents to flow, which can result in a destroyed unit.

Exceeding the negative voltage range on either input will cause a reversal of phase to the output and force the amplifier output to the corresponding high or low state. Exceeding the negative input voltage range on both inputs will force the amplifier output to a high state. Exceeding the positive input voltage range on a single input will not change the phase of the output; however, gain linearity will degrade. If both inputs exceed the positive input voltage range, the output of the amplifier will be forced to a high state.

The common-mode slew rate of the inputs should be limited to $5\text{V}/\mu\text{s}$ to insure low input bias currents.

Application Hints (Continued)

USING THE SENSE, REFERENCE, AND OUTPUT PINS

The sense input and the output of the device are pinned out separately to allow increased flexibility in system designs (see applications). The reference input allows biasing of the output voltage, from +10V to -10V. The ac input resistance of both the sense and reference inputs is unusually high because their input currents are forced to be constant with voltage (typically 20µA).

The maximum linear output swing is determined by the magnitude of resistor R_S:

$$|V_{O\ MAX}| = 10\mu A (R_S)$$

If the output of the amplifier is to be abruptly changed more than 6V, a PNP transistor should be connected, as shown in Figure 3, to prevent the slew rate of the output from exceeding the slew rate of the sense stage. If this precaution is not taken, the base-emitter junction of the input transistor in the sense stage will transiently break down and its β will degrade, resulting in a permanent negative shift in output offset voltage.

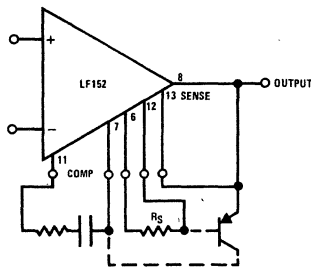


FIGURE 3. Large Signal Transient Suppression

OFFSET VOLTAGE

Because of the two stage design of the instrumentation amplifier, there are two independent contributors to offset voltage (V_OS). The output offset (V_OO_S) is

independent of gain while the input offset (V_IO_S) is multiplied by the gain of the amplifier to the output.

$$V_{O\ S} = V_{I\ O\ S} (G) + V_{O\ O\ S}$$

The output offset of the LF152 can be adjusted as shown in Figure 2. In addition, the LF152 features input offset adjust which is not common to monolithic instrumentation amplifiers and is normally available only on expensive modules. The simple adjust scheme shown in Figure 5 has only a slight increase in non-linearity compared to that of Figure 4 and is recommended for most applications. Nulling both input and output offset makes the overall offset zero, independent of gain.

The output offset is affected by adjustment of the input offset. For every mV of input offset adjust, the output offset will change by approximately 32 mV. Adjustment of the output offset has no effect on the input offset, so it should always be done last.

Offset adjustment changes the temperature coefficient of the V_OS drift. The typical input offset drift of the unadjusted device is -10µV/°C. If the input offset is adjusted, the V_IO_S drift increases by approximately

$$V_{I\ O\ S\ drift} \approx -10\mu V/^{\circ}C + 2\mu V/^{\circ}C / (mV\ of\ adjustment)$$

The V_OO_S drift will be improved by output offset adjust because the magnitudes of the current sources adjusted become less sensitive to V_{BE} variations. If V_OO_S adjust is not used, pins 1, 2 and 16 must be shorted to the positive supply for circuit operation.

OFFSET VOLTAGE ADJUSTMENT PROCEDURE

For gains less than 100, only output offset adjustment is needed. For gains greater than 100, input offset adjust is usually necessary since the input offset voltage amplified to the output may be out of the range of the output offset adjust. Input offset adjust is also needed if zero overall offset is desired while varying the amplifier gain.

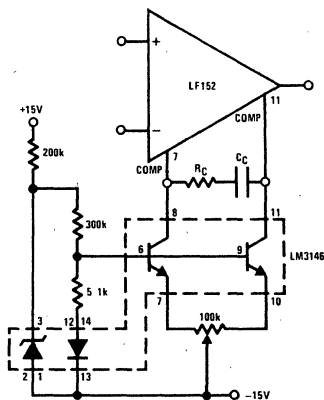


FIGURE 4. Input Offset Adjust

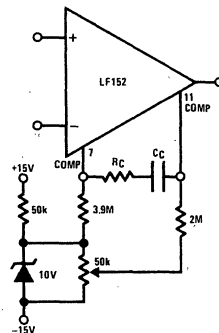


FIGURE 5. Simple Input Offset Adjust

Application Hints (Continued)

To adjust the input offset, the following procedure should be used:

The effective input offset voltage appears directly across R_G when both inputs are connected to ground, and can be measured by a voltmeter referenced to ground. This offset error across R_G can be zeroed by the input offset adjustment circuit shown in *Figure 4* or *5*. The remaining error at the output is strictly due to the output offset voltage which can then be nulled out with the circuit shown in *Figure 2*. The amplifier is now offset nulled independent of gain.

COMPENSATION

The variable bandwidth and slew rate of the LF152 are controlled by an RC network between the compensation pins of the amplifier as shown in *Figure 2*. R_C and C_C may be varied for optimum operating characteristics in a particular application.

Layout of accompanying circuitry may influence the value of this RC network. The lead lengths to resistors

R_S and R_G should be minimized and the capacitance from these nodes should also be minimized for optimum frequency response. If $R_C = 160\Omega$ and $C_C = 0.002\mu F$ in the printed circuit board of *Figure 7*, the amplifier will be compensated for all gains from 1 to 1000. Gains from 0.1 to 10,000 may be obtained with different compensation.

GAIN ERROR AND NONLINEARITY

Gain error of the LF152 is the error between the average slope of the transfer function compared to the slope of R_S/R_G . In the LF152, the small gain error is essentially constant with gain and may be nulled out by trimming R_S .

Of the existing monolithic instrumentation amplifiers, the LF152 is among the lowest in gain nonlinearity error. Gain nonlinearity is the curvature of the transfer function from the theoretically perfect function as shown in *Figure 6*.

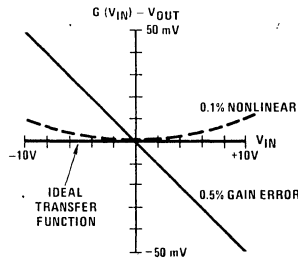


FIGURE 6. Gain Error and Nonlinearity

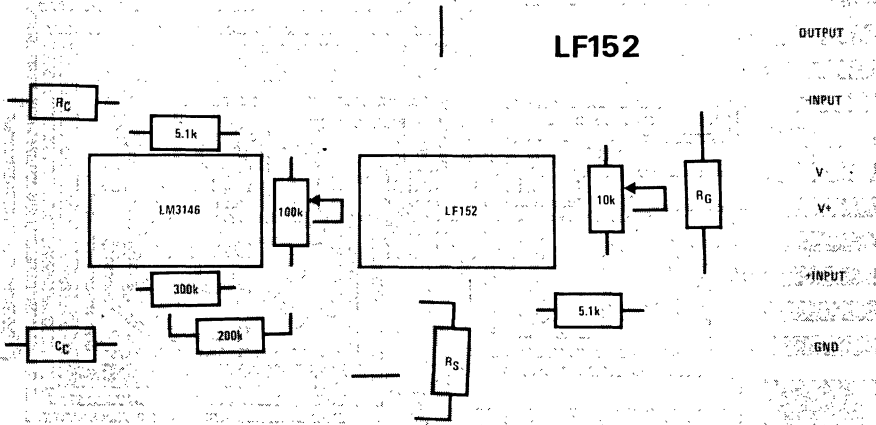
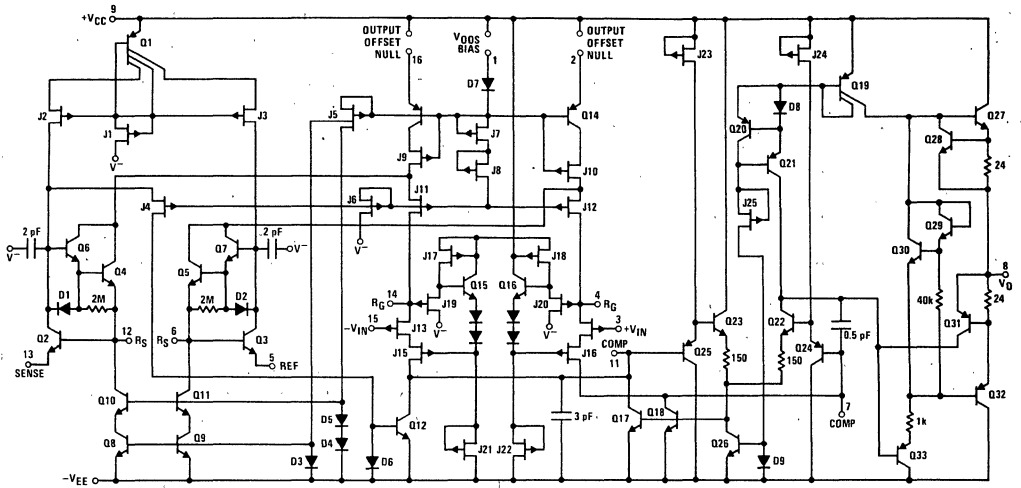


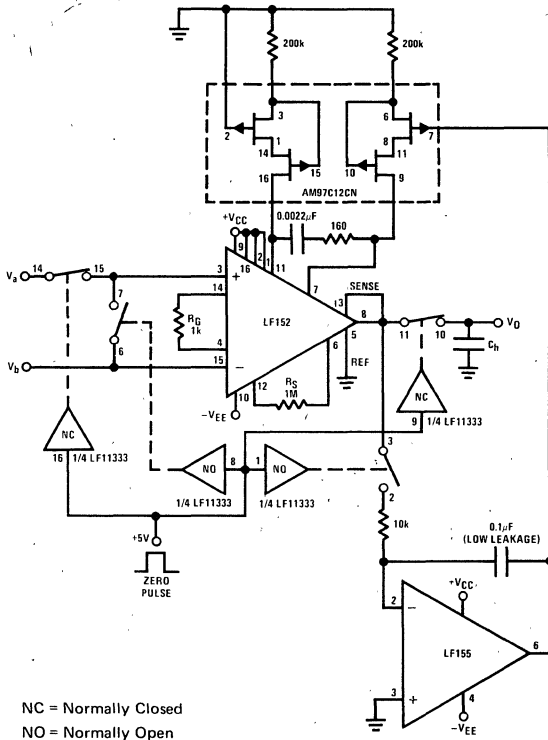
FIGURE 7. PC Layout (Bottom View)

Detailed Schematic



Typical Applications

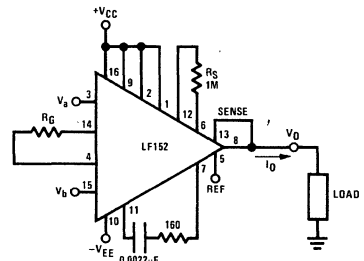
Automatic V_{IOS} Adjust ($G \geq 100$)



NC = Normally Closed
NO = Normally Open

Minimum pulse width to drive V_O to zero is 400 μ s.

General Purpose Instrumentation Amplifier



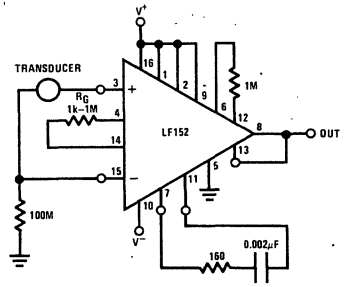
$$V_O = (V_a - V_b) \frac{R_S}{R_G} + V_{REF}$$

For $\frac{R_S}{R_G} = 1$,

$$V_O = V_a + V_{REF} - V_b$$

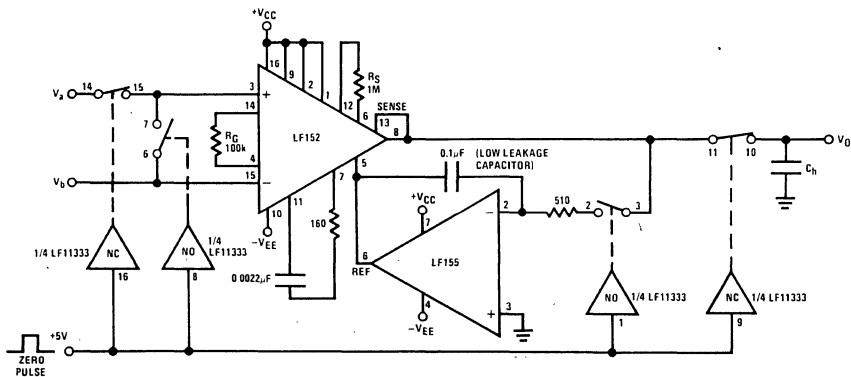
I_O SOURCE OR SINK ≤ 5 mA

Isolated Sensor



Typical Applications (Continued)

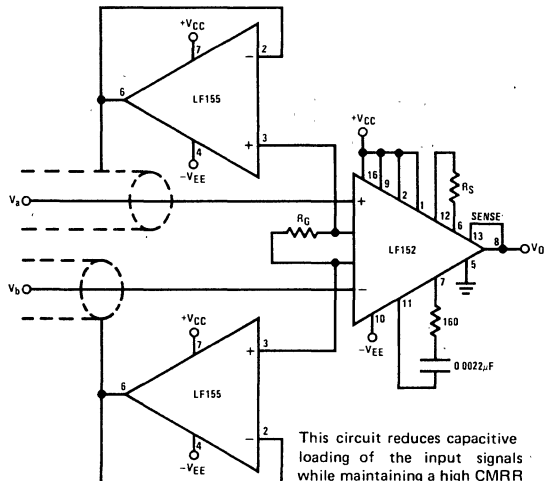
Automatic VOOS Adjust (For $G \leq 100$)



Minimum pulse width to drive V_0 to zero is $450\mu s$

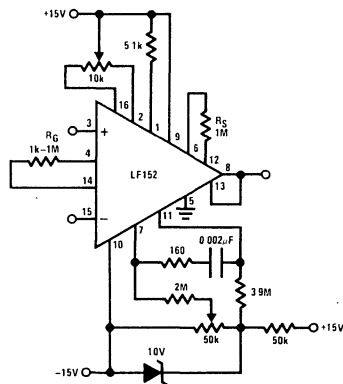
NC = Normally Closed
NO = Normally Open

AC Active Guard Drive

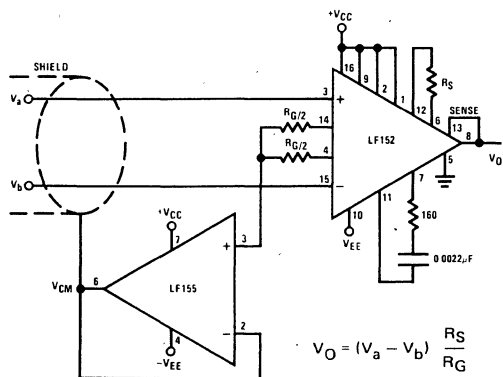


This circuit reduces capacitive loading of the input signals while maintaining a high CMRR

Typical Circuit with Full Offset Adjust



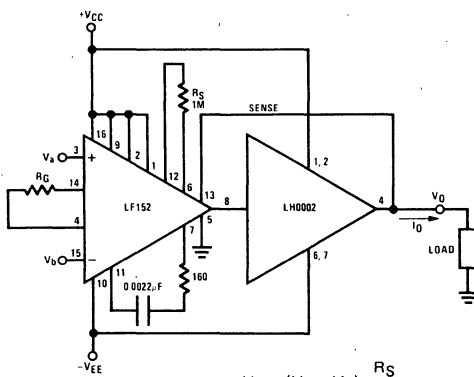
Active Guard Drive



$$V_0 = (V_a - V_b) \frac{R_S}{R_G}$$

(This circuit reduces the degradation of CMRR caused by the capacitance of shielded cable.)

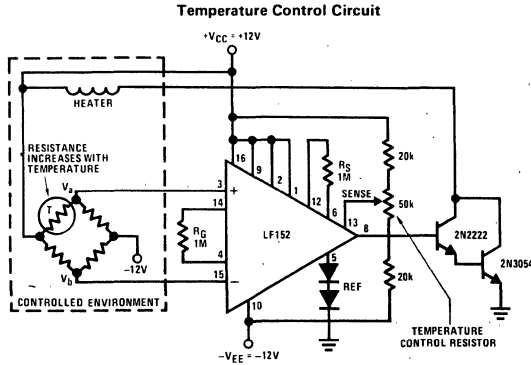
Output Current Boost



$$V_0 = (V_a - V_b) \frac{R_S}{R_G}$$

I_0 SOURCE OR SINK ≤ 95 mA

Typical Applications (Continued)

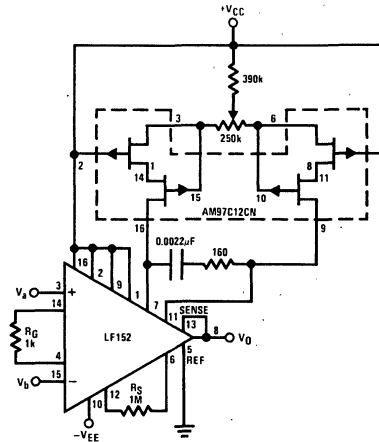


Under balanced conditions, $V_{SENSE} - V_{REF}$ appears across R_S . $V_a - V_b$ appears across R_G and $I_{RG} = I_{RS}$.

$$\frac{V_a - V_b}{R_G} = \frac{V_{SENSE}}{R_S} \text{ or } V_a - V_b = V_{SENSE} \frac{R_G}{R_S}$$

V_{SENSE} is fixed by the temperature control resistor and R_G/R_S is constant. The LF152 is used as a comparator with a feedback loop closed through the heater and the temperature dependent resistor. If $V_a - V_b > V_{SENSE} R_G/R_S$. The output goes high turning "ON" the heater. If $V_a - V_b < V_{SENSE} R_G/R_S$. The output goes low turning "OFF" the heater.

Alternate Input Offset (V_{IOS}) Adjust Scheme



Definition of Terms

G Closed loop gain. $G = R_S/R_G$

G_E Gain error. A rotational error of the transfer function about the origin.

G_{NL} Gain nonlinearity. Curvature of the transfer function.

V_{OS} Offset voltage. Voltage offset of the transfer function at the origin $V_{OS} = V_{IOS}(G) + V_{OOS}$

LM121/LM221/LM321, LM121A/LM221A/LM321A Precision Preamplifiers

General Description

The LM121 series are precision preamplifiers designed to operate with general purpose operational amplifiers to drastically decrease dc errors. Drift, bias current, common mode and supply rejection are more than a factor of 50 better than standard op amps alone. Further, the added dc gain of the LM121 decreases the closed loop gain error.

The LM121 series operates with supply voltages from $\pm 3V$ to $\pm 20V$ and has sufficient supply rejection to operate from unregulated supplies. The operating current is programmable from $5\mu A$ to $200\mu A$ so bias current, offset current, gain and noise can be optimized for the particular application while still realizing very low drift. Super-gain transistors are used for the input stage so input error currents are lower than conventional amplifiers at the same operating current. Further, the initial offset voltage is easily nulled to zero.

Features

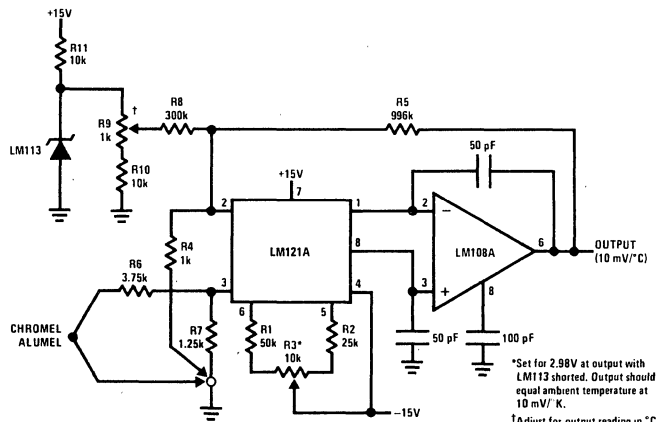
- Guaranteed drift of LM121A series — $0.2\mu V/^{\circ}C$
- Guaranteed drift of LM121 series — $1\mu V/^{\circ}C$

- Offset voltage less than 0.4 mV
- Bias current less than 10 nA at $10\mu A$ operating current
- CMRR 126 dB minimum
- 120 dB supply rejection
- Easily nulled offset voltage

The extremely low drift of the LM121 will improve accuracy on almost any precision dc circuit. For example, instrumentation amplifier, strain gauge amplifiers and thermocouple amplifiers now using chopper amplifiers can be made with the LM121. The full differential input and high common-mode rejection are another advantage over choppers. For applications where low bias current is more important than drift, the operating current can be reduced to low values. High operating currents can be used for low voltage noise with low source resistance. The programmable operating current of the LM121 allows tailoring the input characteristics to match those of specialized op amps.

The LM121 is specified over a $-55^{\circ}C$ to $+125^{\circ}C$ temperature range, the LM221 over a $-25^{\circ}C$ to $+85^{\circ}C$ range and the LM321 over a $0^{\circ}C$ to $+70^{\circ}C$ temperature range.

Typical Applications



Thermocouple Amplifier with Cold Junction Compensation

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±20V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Voltage (Notes 2 and 3) | ±15V |
| Input Voltage (Note 3) | ±15V |
| Operating Temperature Range | |
| LM121 | -55°C to +125°C |
| LM221 | -25°C to +85°C |
| LM321 | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 4) LM121, LM221, LM321

| PARAMETER | CONDITIONS | LM121, LM221 | | | LM321 | | | UNITS |
|---|---|--------------|-----|-----|---------|-----|-----|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ | | | 0.7 | | | 1.5 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | | 1 | | | 2 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | | 10 | | | 20 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | | 10 | | | 18 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | | 100 | | | 180 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | 4 | | | 2 | | | MΩ |
| | $R_{\text{SET}} = 6.4\text{k}$ | 0.4 | | | 0.2 | | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | | 1.5 | | | 2.2 | mA |
| Input Offset Voltage | $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ | | | 1.0 | | | 2.5 | mV |
| Input Bias Current | $R_{\text{SET}} = 70\text{k}$ | | | 30 | | | 28 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | | 300 | | | 280 | nA |
| Input Offset Current | $R_{\text{SET}} = 70\text{k}$ | | | 3 | | | 4 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | | 30 | | | 40 | nA |
| Input Offset Current Drift | $R_{\text{SET}} = 70\text{k}$ | | 3 | | | 3 | | pA/°C |
| Average Temperature Coefficient of Input Offset Voltage | $R_S \leq 200\Omega$, $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ Offset Voltage Nulled | | | 1 | | | 1 | μV/°C |
| Long Term Stability | | | 5 | | | 5 | | μV/yr |
| Supply Current | | | | 2.5 | | | 3.5 | mA |
| Input Voltage Range | $V_S = \pm 15\text{V}$, (Note 5) $R_{\text{SET}} = 70\text{k}$ | ±13 | | | ±13 | | | V |
| | $R_{\text{SET}} = 6.4\text{k}$ | +7, -13 | | | +7, -13 | | | V |
| Common-Mode Rejection Ratio | $R_{\text{SET}} = 70\text{k}$ | | 120 | | | 114 | | dB |
| | $R_{\text{SET}} = 6.4\text{k}$ | | 114 | | | 114 | | dB |
| Supply Voltage Rejection Ratio | $R_{\text{SET}} = 70\text{k}$ | | 120 | | | 114 | | dB |
| | $R_{\text{SET}} = 6.4\text{k}$ | | 114 | | | 114 | | dB |
| Voltage Gain | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$, $R_L > 3\text{M}\Omega$ | | 16 | | | 12 | | V/V |
| Noise | $R_{\text{SET}} = 70\text{k}$, $R_{\text{SOURCE}} = 0$ | | 8 | | | 8 | | nV/√Hz |

Note 1: The maximum junction temperature of the LM121 is 150°C, while that of the LM221 is 100°C. The maximum junction temperature of the LM321 is 85°C. For operating at elevated temperature, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/6 inch thick epoxy glass board with ten, 0.03 inch wide, 2 ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes in series with a 500Ω resistor for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5 \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, unless otherwise specified. With the LM221, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$, and for the LM321 the specifications apply over a 0°C to $+70^\circ\text{C}$ temperature range.

Note 5: External precision resistor - 0.1% - can be placed from pins 1 and 8 to 7 to increase positive common-mode range.

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±20V |
| Power Dissipation (Note 1) | 500 mW |
| Differential Input Voltage (Notes 2 and 3) | ±15V |
| Input Voltage (Note 3) | ±15V |
| Operating Temperature Range | |
| LM121A | -55°C to +125°C |
| LM221A | -25°C to +85°C |
| LM321A | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 4) LM121A, LM221A, LM321A

| PARAMETER | CONDITIONS | LM121A, LM221A | | | LM321A | | | UNITS |
|---|---|----------------|------|------|---------|------|------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ | | 0.2 | 0.4 | | 0.2 | 0.4 | mV |
| Input Offset Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | 0.3 | 0.5 | | 0.3 | 0.5 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | | 5 | | | 5 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | 5 | 10 | | 5 | 15 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | 50 | 100 | | 50 | 150 | nA |
| Input Resistance | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | 4 | 8 | | 2 | 8 | | MΩ |
| | $R_{\text{SET}} = 6.4\text{k}$ | 0.4 | | | 0.2 | | | MΩ |
| Supply Current | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$ | | 0.8 | 1.5 | | 0.8 | 2.2 | mA |
| Input Offset Voltage | $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ | | 0.5 | 0.65 | | 0.5 | 0.65 | mV |
| Input Bias Current | $R_{\text{SET}} = 70\text{k}$ | | 15 | 30 | | 15 | 25 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | 150 | 300 | | 150 | 250 | nA |
| Input Offset Current | $R_{\text{SET}} = 70\text{k}$ | | 0.5 | 1 | | 0.5 | 1 | nA |
| | $R_{\text{SET}} = 6.4\text{k}$ | | 5 | 10 | | 5 | 10 | nA |
| Input Offset Current Drift | $R_{\text{SET}} = 70\text{k}$ | | 3 | | | 3 | | pA/°C |
| Average Temperature Coefficient of Input Offset Voltage | $R_S \leq 200\Omega$, $6.4\text{k} \leq R_{\text{SET}} \leq 70\text{k}$ Offset Voltage Nulled | | 0.07 | 0.2 | | 0.07 | 0.2 | μV/°C |
| Long Term Stability | | | 3 | | | 3 | | μV/yr |
| Supply Current | | | 1 | 2.5 | | 1 | 3.5 | mA |
| Input Voltage Range | $V_S = \pm 15\text{V}$, (Note 5) | | | | | | | |
| | $R_{\text{SET}} = 70\text{k}$ | ±13 | | | ±13 | | | V |
| | $R_{\text{SET}} = 6.4\text{k}$ | +7, -13 | | | +7, -13 | | | V |
| Common-Mode Rejection Ratio | $R_{\text{SET}} = 70\text{k}$ | 126 | 140 | | 126 | 140 | | dB |
| | $R_{\text{SET}} = 6.4\text{k}$ | 120 | 130 | | 120 | 130 | | dB |
| Supply Voltage Rejection Ratio | $R_{\text{SET}} = 70\text{k}$ | 120 | 126 | | 118 | 126 | | dB |
| | $R_{\text{SET}} = 6.4\text{k}$ | 114 | 120 | | 114 | 120 | | dB |
| Voltage Gain | $T_A = 25^\circ\text{C}$, $R_{\text{SET}} = 70\text{k}$, $R_L > 3\text{M}\Omega$ | 16 | 20 | | 12 | 20 | | V/V |
| Noise | $R_{\text{SET}} = 70\text{k}$, $R_{\text{SOURCE}} = 0$ | | 8 | | | 8 | | nV/√Hz |

Note 1: The maximum junction temperature of the LM121A is 150°C, while that of the LM221A is 100°C. The maximum junction temperature of the LM321A is 85°C. For operating at elevated temperature, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W junction to case. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/6 inch thick epoxy glass board with ten, 0.03 inch wide, 2 ounce copper conductors. The thermal resistance of the dual-in-line package is 100°C/W junction to ambient.

Note 2: The inputs are shunted with back-to-back diodes in series with a 500Ω resistor for overvoltage protection. Therefore, excessive current will flow if a differential input voltage in excess of 1V is applied between the inputs.

Note 3: For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.

Note 4: These specifications apply for $\pm 5 \leq V_S \leq \pm 20\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, unless otherwise specified. With the LM221A, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$, and for the LM321A the specifications apply over a 0°C to $+70^\circ\text{C}$ temperature range.

Note 5: External precision resistor – 0.1% – can be placed from pins 1 and 8 to 7 to increase positive common-mode range.

Frequency Compensation

UNIVERSAL COMPENSATION

The additional gain of the LM121 preamplifier when used with an operational amplifier usually necessitates additional frequency compensation. When the closed loop gain of the op amp with the LM121 is less than the gain of the LM121 alone, more compensation is needed. The worst case situation is when there is 100% feedback—such as a voltage follower or integrator—and the gain of the LM121 is high. When high closed loop gains are used—for example $A_V = 1000$ —and only an addition gain of 200 is inserted by the LM121, the frequency compensation of the op amp will usually suffice.

The frequency compensation shown here is designed to operate with any unity-gain stable op amp. *Figure 1* shows the basic configuration of frequency stabilizing network. In operation the output of the LM121 is rendered single ended by a $0.01\mu\text{F}$ bypass capacitor to ground. Overall frequency compensation then is achieved by an integrating capacitor around the op amp.

$$\text{Bandwidth at unity-gain} \cong \frac{12}{2\pi R_{\text{SET}} C}$$

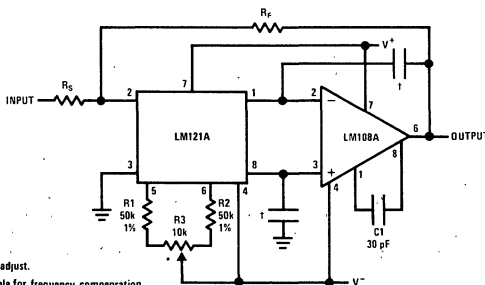
$$\text{for } 0.5 \text{ MHz bandwidth } C = \frac{4}{10^6 R_{\text{SET}}}$$

For use with higher frequency op amps such as the LM118 the bandwidth may be increased to about 2 MHz.

If the closed loop gain is greater than unity, "C" may be decreased to:

$$C = \frac{4}{10^6 A_{\text{CL}} R_{\text{SET}}}$$

Typical Applications



*Offset adjust.

†See table for frequency compensation.

FIGURE 1. Low Drift Op Amp Using the LM121A as a Preamp

ALTERNATE COMPENSATION

The two compensation capacitors can be made equal for improved power supply rejection. In this case the formula for the compensation capacitor is:

$$C = \frac{8}{10^6 A_{\text{CL}} R_{\text{SET}}}$$

Table I shows typical values for the two compensating capacitors for various gains and operating currents.

TABLE I

| CLOSED LOOP GAIN | CURRENT SET RESISTOR | | | | |
|------------------|----------------------|-------|-------|-------|------|
| | 120 kΩ | 60 kΩ | 30 kΩ | 12 kΩ | 6 kΩ |
| $A_V = 1$ | 68 | 130 | 270 | 680 | 1300 |
| $A_V = 5$ | 15 | 27 | 56 | 130 | 270 |
| $A_V = 10$ | 10 | 15 | 27 | 68 | 130 |
| $A_V = 50$ | 1 | 3 | 5 | 15 | 27 |
| $A_V = 100$ | — | 1 | 3 | 5 | 10 |
| $A_V = 500$ | — | — | 1 | 1 | 3 |
| $A_V = 1000$ | — | — | — | — | — |

This table applies for the LM108, LM101A, LM741, LM118. Capacitance is in pF.

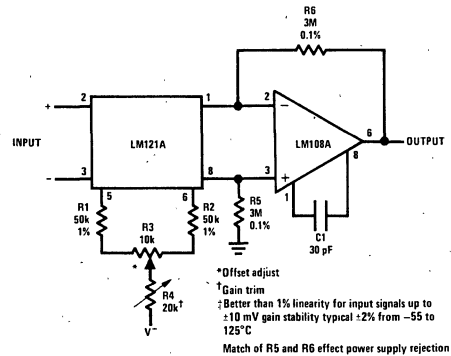
DESIGN EQUATIONS FOR THE LM121 SERIES

$$\text{Gain } A_V \approx \frac{1.2 \times 10^6}{R_{\text{SET}}}$$

Null Pot Value should be 10% of R_{SET}

$$\text{Operating Current} \approx \frac{2 \times 0.65\text{V}}{R_{\text{SET}}}$$

$$\text{Positive Common-Mode Limit} \approx V^+ - \left[0.6 - \frac{0.65\text{V} \times 50\text{k}}{R_{\text{SET}}} \right]$$



*Offset adjust

†Gain trim

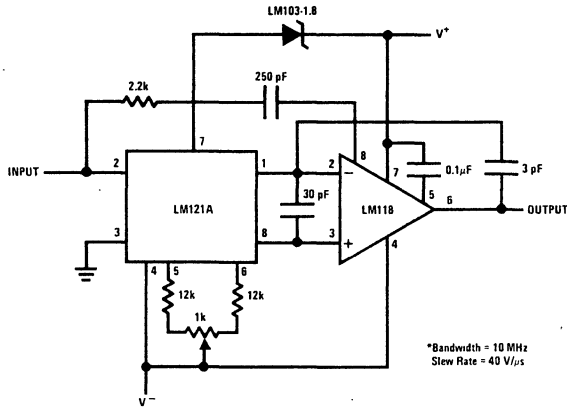
‡Better than 1% linearity for input signals up to $\pm 10 \text{ mV}$ gain stability typical $\pm 2\%$ from -55 to 125°C

Match of R5 and R6 effect power supply rejection

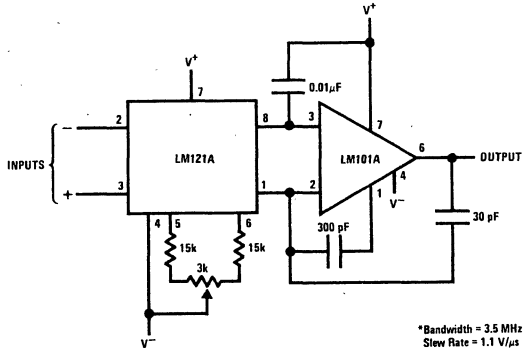
Gain of 1000 Instrumentation Amplifier†

Typical Applications (Continued)

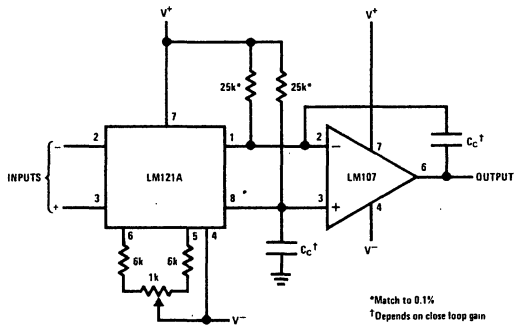
LM121/LM221/LM321,
LM121A/LM221A/LM321A



High Speed* Inverting Amplifier with Low Drift



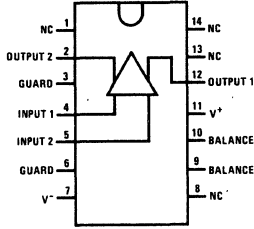
Medium Speed* General Purpose Amplifier



Increased Common-Mode Range at High Operating Currents

Connection Diagrams

Dual-In-Line Package

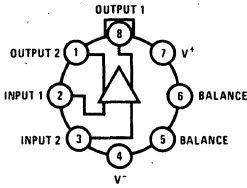


NOTE: Pin 7 connected to bottom of package.

TOP VIEW

Order Number LM121D,
 LM221D, LM221AD
 or LM321AD
 See NS Package D14E

Metal Can Package

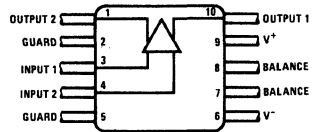


Note: Pin 4 connected to case.

TOP VIEW

Order Number LM121H,
 LM221H, LM321H, LM121AH,
 LM221AH or LM321AH
 See NS Package H08C

Flat Package



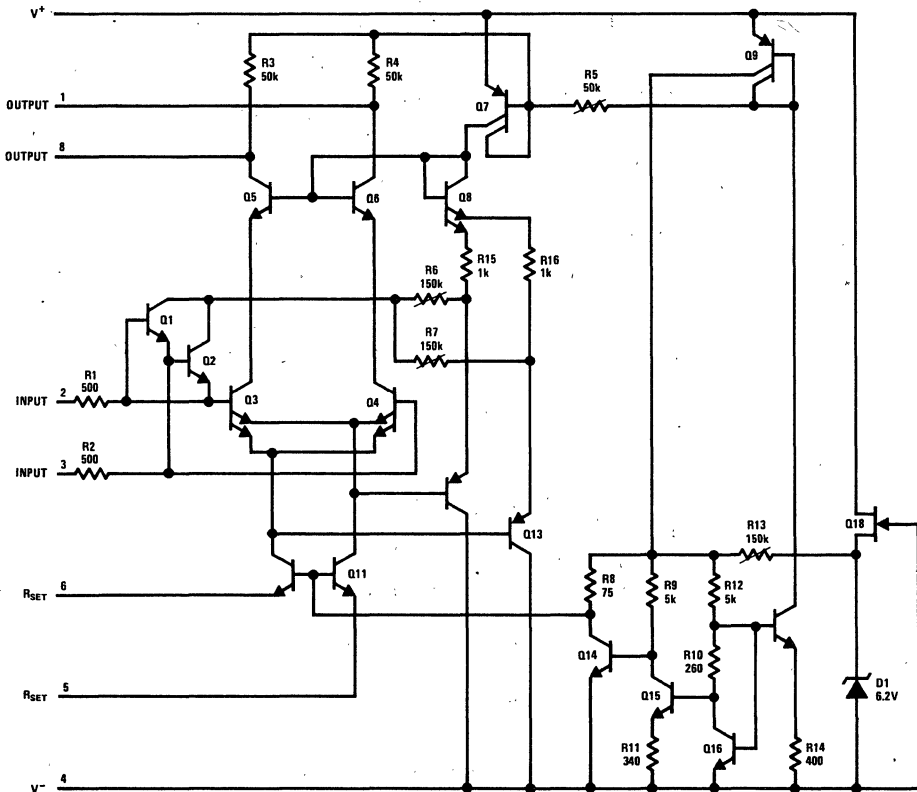
NOTE: Pin 6 connected to bottom of package.

TOP VIEW

Order Number LM221F,
 LM321F, LM221AF
 or LM321AF
 See NS Package F10A

Note: Outputs are inverting from
 the input of the same number.

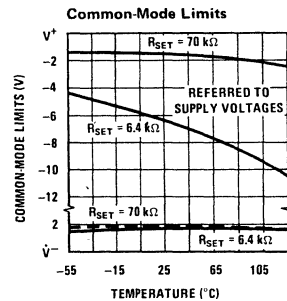
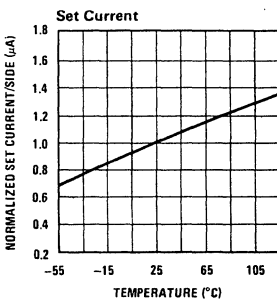
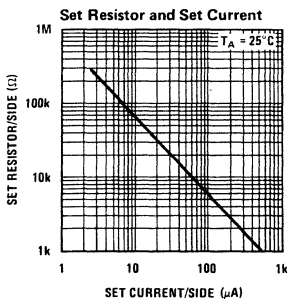
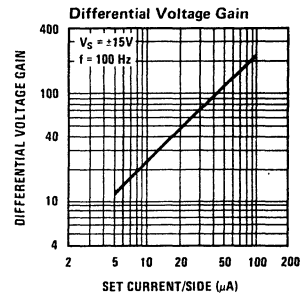
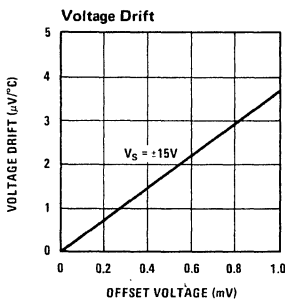
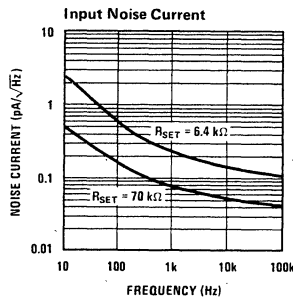
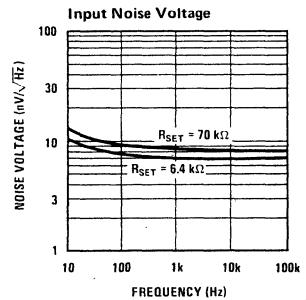
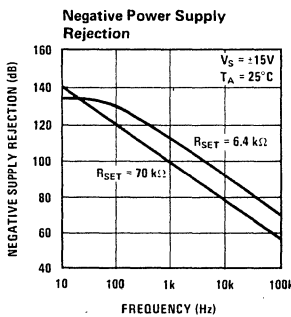
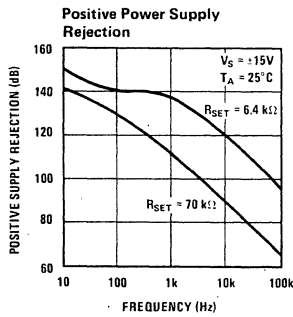
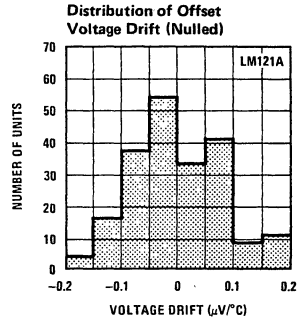
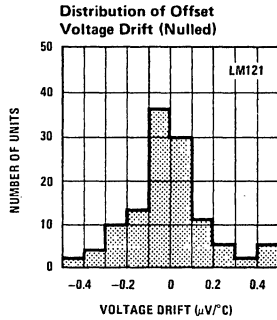
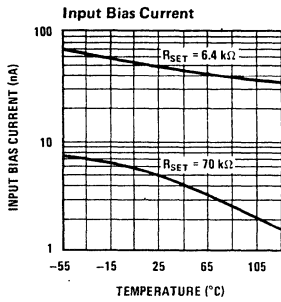
Schematic Diagram*



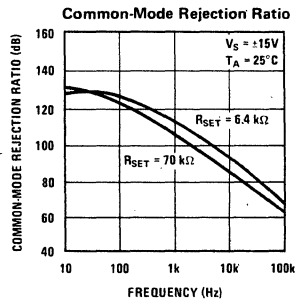
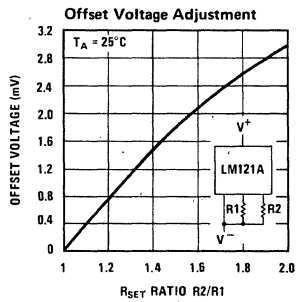
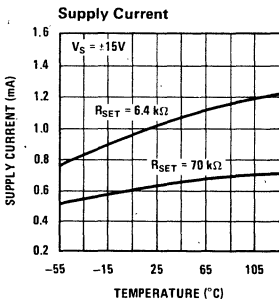
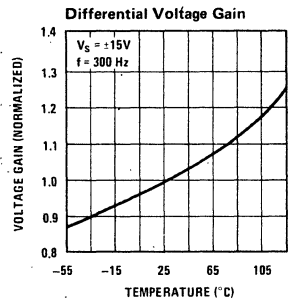
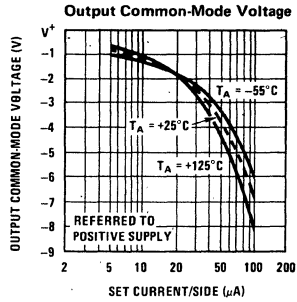
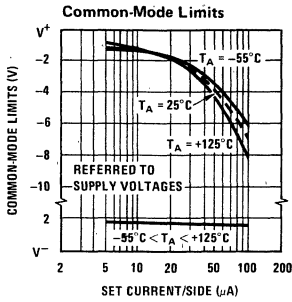
*Pin connections shown on schematic diagram and typical applications are for TO-5 package.

Typical Performance Characteristics

LM121/LM221/LM321,
LM121A/LM221A/LM321A



Typical Performance Characteristics (Continued)



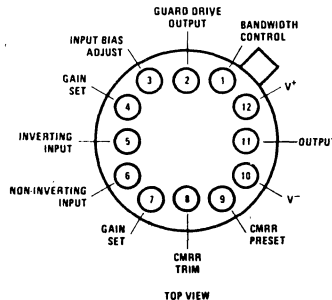
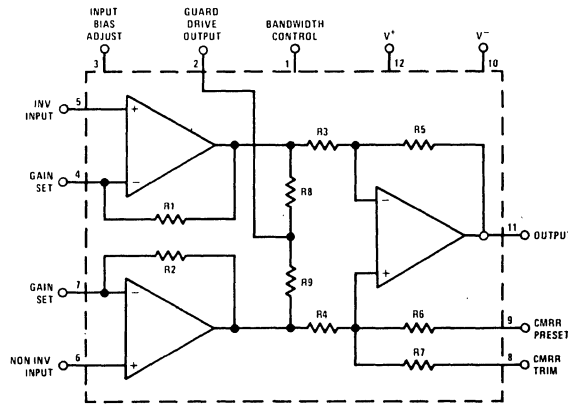
LH0036/LH0036C Instrumentation Amplifier
general description

The LH0036/LH0036C is a true micro power instrumentation amplifier designed for precision differential signal processing. Extremely high accuracy can be obtained due to the 300 M Ω input impedance and excellent 100 dB common mode rejection ratio. It is packaged in a hermetic TO-8 package. Gain is programmable with one external resistor from 1 to 1000. Power supply operating range is between $\pm 1V$ and $\pm 18V$. Input bias current and output bandwidth are both externally adjustable or can be set by internally set values. The LH0036 is specified for operation over the $-55^{\circ}C$ to $+125^{\circ}C$ temperature range and the

LH0036C is specified for operation over the $-25^{\circ}C$ to $+85^{\circ}C$ temperature range.

features

- High input impedance 300 M Ω
- High CMRR 100 dB
- Single resistor gain adjust 1 to 1000
- Low power 90 μ W
- Wide supply range $\pm 1V$ to $\pm 18V$
- Adjustable input bias current
- Adjustable output bandwidth
- Guard drive output

equivalent circuit and connection diagrams


Order Number LH0036G or LH0036CG
See NS Package H12B

absolute maximum ratings

| | | | |
|----------------------------|-----------------|--|-----------------|
| Supply Voltage | ±18V | Short Circuit Duration | Continuous |
| Differential Input Voltage | ±30V | Operating Temperature Range | -55°C to +125°C |
| Input Voltage Range | ±V _S | LH0036 | -25°C to +85°C |
| Shield Drive Voltage | ±V _S | LH0036C | -55°C to +150°C |
| CMRR Preset Voltage | ±V _S | Storage Temperature Range | 65°C to +150°C |
| CMRR Trim Voltage | ±V _S | Lead Temperature, Soldering 10 seconds | 300°C |
| Power Dissipation (Note 3) | 1.5W | | |

electrical characteristics (Notes 1 and 2)

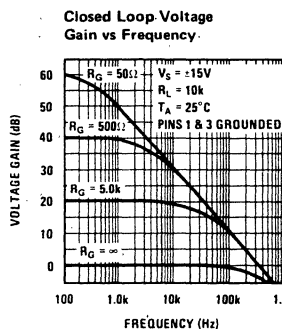
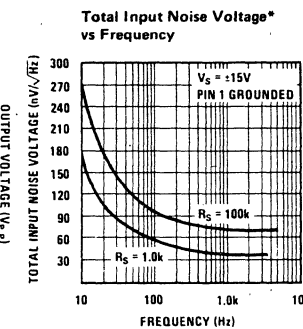
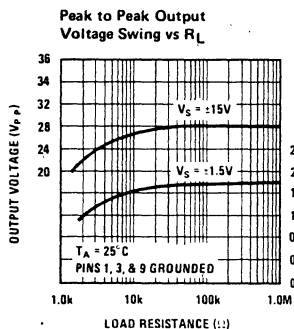
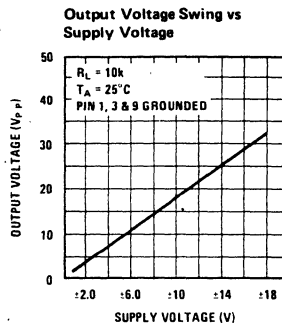
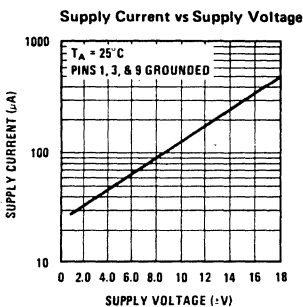
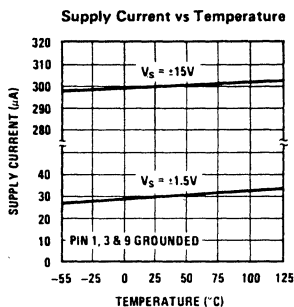
| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|--|--|-----------------------|-------|------|---------|-------|------|--------|
| | | LH0036 | | | LH0036C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage (V _{IOS}) | R _S = 1.0kΩ, T _A = 25°C | | 0.5 | 1.0 | | 1.0 | 2.0 | mV |
| | | | | 2.0 | | | 3.0 | mV |
| Output Offset Voltage (V _{OOS}) | R _S = 1.0kΩ, T _A = 25°C | | 2.0 | 5.0 | | 5.0 | 10 | mV |
| | | | | 6.0 | | | 12 | mV |
| Input Offset Voltage Tempco (ΔV _{IOS} /ΔT) | R _S ≤ 1.0kΩ | | 10 | | | 10 | | μV/°C |
| Output Offset Voltage Tempco (ΔV _{OOS} /ΔT) | | | 15 | | | 15 | | μV/°C |
| Overall Offset Referred to Input (V _{OS}) | A _V = 1.0 | | 2.5 | | | 6.0 | | mV |
| | | A _V = 10 | 0.7 | | | 1.5 | | mV |
| | | A _V = 100 | 0.52 | | | 1.05 | | mV |
| | | A _V = 1000 | 0.502 | | | 1.005 | | mV |
| Input Bias Current (I _B) | T _A = 25°C | | 40 | 100 | | 50 | 125 | nA |
| | | | | 150 | | | 200 | nA |
| Input Offset Current (I _{OS}) | T _A = 25°C | | 10 | 40 | | 20 | 50 | nA |
| | | | | 80 | | | 100 | nA |
| Small Signal Bandwidth | A _V = 1.0, R _L = 10kΩ | | 350 | | | 350 | | kHz |
| | | | 35 | | | 35 | | kHz |
| | | | 3.5 | | | 3.5 | | kHz |
| | | | 350 | | | 350 | | Hz |
| Full Power Bandwidth | V _{IN} = ±10V, R _L = 10k, A _V = 1 | | 5.0 | | | 5.0 | | kHz |
| Input Voltage Range | Differential | ±10 | ±12 | | ±10 | ±12 | | V |
| | Common Mode | ±10 | ±12 | | ±10 | ±12 | | V |
| Gain Nonlinearity | | | 0.03 | | | 0.03 | | % |
| Deviation From Gain Equation Formula | A _V = 1 to 1000 | | ±0.3 | ±1.0 | | ±1.0 | ±3.0 | % |
| PSRR | ±5.0V ≤ V _S ≤ ±15V, A _V = 1.0 | | 1.0 | 2.5 | | 1.0 | 5.0 | mV/V |
| | ±5.0V ≤ V _S ≤ ±15V, A _V = 100 | | 0.05 | 0.25 | | 0.10 | 0.50 | mV/V |
| CMRR | A _V = 1.0 DC to | | 1.0 | 2.5 | | 2.5 | 5.0 | mV/V |
| | A _V = 10 100 Hz | | 0.1 | 0.25 | | 0.25 | 0.50 | mV/V |
| | A _V = 100 ΔR _S = 1.0k | | 50 | 100 | | 50 | 100 | μV/V |
| Output Voltage | V _S = ±15V, R _L = 10kΩ | ±10 | ±13.5 | | ±10 | ±13.5 | | V |
| | V _S = ±1.5V, R _L = 100kΩ | ±0.6 | ±0.8 | | ±0.6 | ±0.8 | | V |
| Output Resistance | | | 0.5 | | | 0.5 | | Ω |
| Supply Current | | | 300 | 400 | | 400 | 600 | μA |
| Equivalent Input Noise Voltage | 0.1 Hz < f < 10 kHz, R _S < 50Ω | | 20 | | | 20 | | μV/p-p |
| Slew Rate | ΔV _{IN} = ±10V, R _L = 10kΩ, A _V = 1.0 | | 0.3 | | | 0.3 | | V/μs |
| Settling Time | To ±10 mV, R _L = 10kΩ, ΔV _{OUT} = 1.0V | | | | | | | |
| | | A _V = 1.0 | | 3.8 | | 3.8 | | μs |
| | | A _V = 100 | | 180 | | 180 | | μs |

Note 1: Unless otherwise specified, all specifications apply for V_S = ±15V, Pins 1, 3, and 9 grounded, -25°C to +85°C for the LH0036C and -55°C to +125°C for the LH0036.

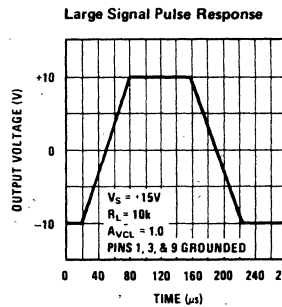
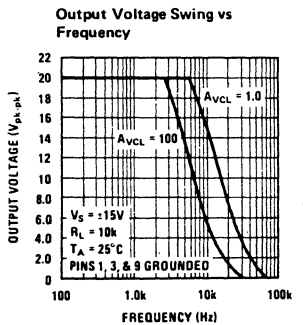
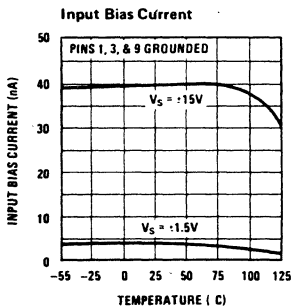
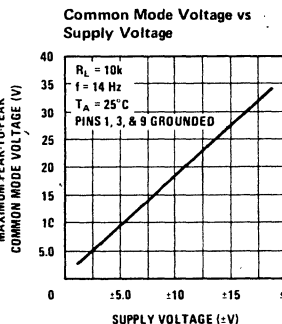
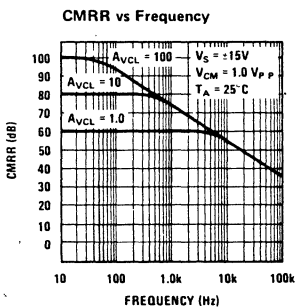
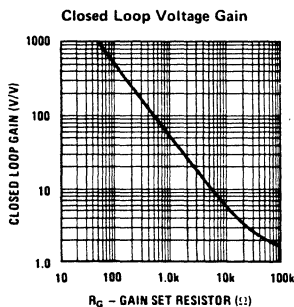
Note 2: All typical values are for T_A = 25°C.

Note 3: The maximum junction temperature is 150°C. For operation at elevated temperature derate the G package on a thermal resistance of 90°C/W, above 25°C.

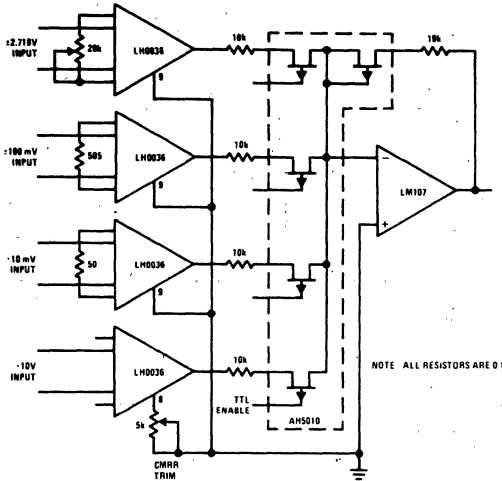
typical performance characteristics



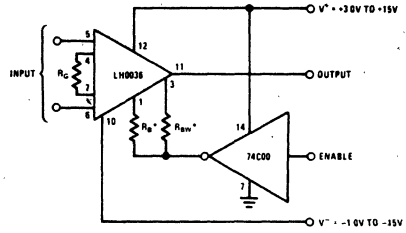
*Noise voltage includes contribution from source resistance



typical applications

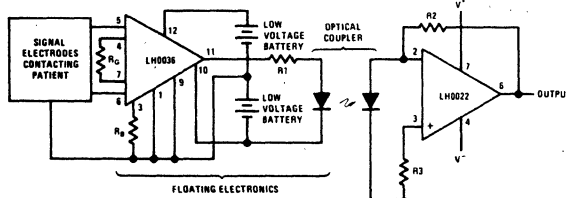


Pre MUX Signal Conditioning

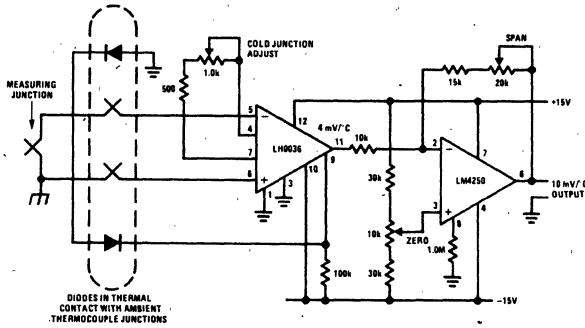


* R_{1in} AND R_2 ARE OPTIONAL BANDWIDTH AND INPUT BIAS CURRENT CONTROLLING RESISTORS

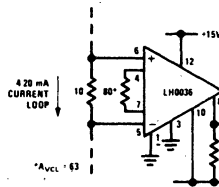
Instrumentation Amplifier with Logic Controlled Shut-Down



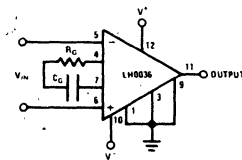
Isolation Amplifier for Medical Telemetry



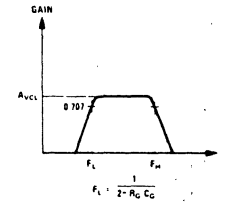
Thermocouple Amplifier with Cold Junction Compensation



Process Control Interface



High Pass Filter



applications information

THEORY OF OPERATION

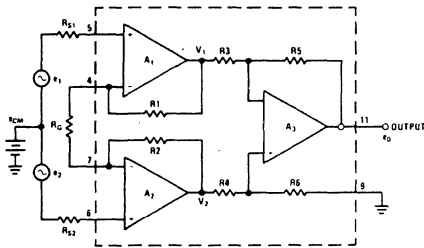


FIGURE 1. Simplified LH0036

The LH0036 is a 2 stage amplifier with a high input impedance gain stage comprised of A₁ and A₂ and a differential to single-ended unity gain stage, A₃. Operational amplifier, A₁, receives differential input signal, e₁, and amplifies it by a factor equal to (R₁ + R_G)/R_G.

A₁ also receives input e₂ via A₂ and R₂. e₂ is seen as an inverting signal with a gain of R₁/R_G. A₁ also receives the common mode signal e_{CM} and processes it with a gain of +1.

Hence:

$$V_1 = \frac{R_1 + R_G}{R_G} e_1 - \frac{R_1}{R_G} e_2 + e_{CM} \quad (1)$$

By similar analysis V₂ is seen to be:

$$V_2 = \frac{R_2 + R_G}{R_G} e_2 - \frac{R_2}{R_G} e_1 + e_{CM} \quad (2)$$

For R₁ = R₂:

$$V_2 - V_1 = \left[\left(\frac{2R_1}{R_G} + 1 \right) \right] (e_2 - e_1) \quad (3)$$

Also, for R₃ = R₅ = R₄ = R₆, the gain of A₃ = 1, and:

$$e_0 = (1)(V_2 - V_1) = (e_2 - e_1) \left[1 + \left(\frac{2R_1}{R_G} \right) \right] \quad (4)$$

As can be seen for identically matched resistors, e_{CM} is cancelled out, and the differential gain is dictated by equation (4).

For the LH0036, equation (4) reduces to:

$$A_{VCL} = \frac{e_0}{e_2 - e_1} = 1 + \frac{50k}{R_G} \quad (5a)$$

The closed loop gain may be set to any value from 1 (R_G = ∞) to 1000 (R_G ≅ 50Ω). Equation (5a) re-arranged in more convenient form may be used to select R_G for a desired gain:

$$R_G = \frac{50k}{A_{VCL} - 1} \quad (5b)$$

USE OF BANDWIDTH CONTROL (pin 1)

In the standard configuration, pin 1 of the LH0036 is simply grounded. The amplifier's slew rate in this configuration is typically 0.3V/μs and small

signal bandwidth 350 kHz for A_{VCL} = 1. In some applications, particularly at low frequency, it may be desirable to limit bandwidth in order to minimize the overall noise bandwidth of the device. A resistor R_{BW} may be placed between pin 1 and ground to accomplish this purpose. Figure 2 shows typical small signal bandwidth versus R_{BW}.

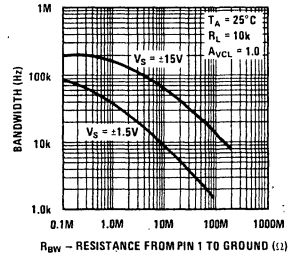


FIGURE 2. Bandwidth vs R_{BW}

It also should be noted that large signal bandwidth and slew rate may be adjusted down by use of R_{BW}. Figure 3 is plot of slew rate versus R_{BW}.

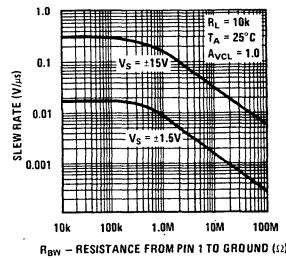


FIGURE 3. Output Slew Rate vs R_{BW}

CMRR CONSIDERATIONS

Use of Pin 9, CMRR Preset

Pin 9 should be grounded for nominal operation. An internal factory trimmed resistor, R₆, will yield a CMRR in excess of 80 dB (for A_{VCL} = 100). Should a higher CMRR be desired, pin 9 should be left open and the procedure, in this section followed.

DC Off-set Voltage and Common Mode Rejection Adjustments

Off-set may be nulled using the circuit shown in Figure 4.

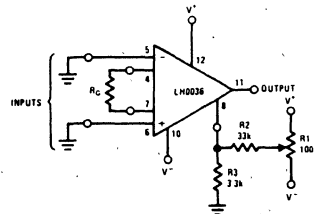


FIGURE 4. V_Os Adjustment Circuit

Pin 8 is also used to improve the common mode rejection ratio as shown in Figure 5. Null is

applications information (con't)

achieved by alternately applying $\pm 10V$ (for V^+ & $V^- = 15V$) to the inputs and adjusting R1 for minimum change at the output.

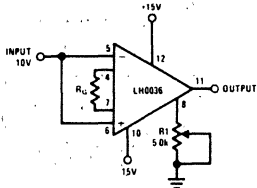


FIGURE 5. CMRR Adjustment Circuit

The circuits of Figure 4 and 5 may be combined as shown in Figure 6 to accomplish both V_{OS} and CMRR null. However, the V_{OS} and CMRR adjustment are interactive and several iterations are required. The procedure for null should start with the inputs grounded.

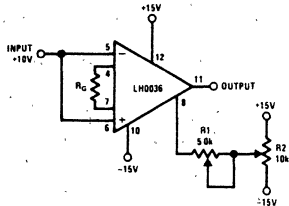
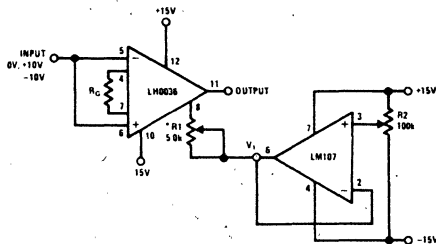


FIGURE 6. Combined CMRR, V_{OS} Adjustment Circuit

R_2 is adjusted for V_{OS} null. An input of $+10V$ is then applied and R_1 is adjusted for CMRR null. The procedure is then repeated until the optimum is achieved.

A circuit which overcomes adjustment interaction is shown in Figure 7. In this case, R_2 is adjusted first for output null of the LH0036. R_1 is then adjusted for output null with $+10V$ input. It is always a good idea to check CMRR null with a $-10V$ input. The optimum null achievable will yield the highest CMRR over the amplifiers common mode range.



* NOTE: NOMINAL VALUE R_1 TO ACHIEVE OPTIMUM CMRR IS 30 K Ω .

FIGURE 7. Improved V_{OS} , CMRR Nulling Circuit

AC CMRR Considerations

The ac CMRR may be improved using the circuit of Figure 8.

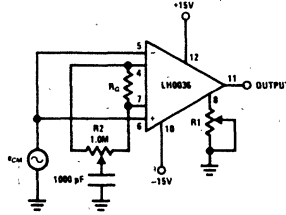


FIGURE 8. Improved AC CMRR Circuit

After adjusting R_1 for best dc CMRR as before, R_2 should be adjusted for minimum peak-to-peak voltage at the output while applying an ac common mode signal of the maximum amplitude and frequency of interest.

INPUT BIAS CURRENT CONTROL

Under nominal operating conditions (pin 3 grounded), the LH0036 requires input currents of 40 nA. The input current may be reduced by inserting a resistor (R_B) between 3 and ground or, alternatively, between 3 and V^- . For R_B returned to ground, the input bias current may be predicted by:

$$I_{BIAS} \cong \frac{V^+ - 0.5}{4 \times 10^8 + 800 R_B} \quad (6a)$$

or

$$R_B = \frac{V^+ - 0.5 - (4 \times 10^8) (I_{BIAS})}{800 I_{BIAS}} \quad (6b)$$

Where:

I_{BIAS} = Input Bias Current (nA)

R_B = External Resistor connected between pin 3 and ground (Ohms)

V^+ = Positive Supply Voltage (Volts)

Figure 9 is a plot of input bias current versus R_B .

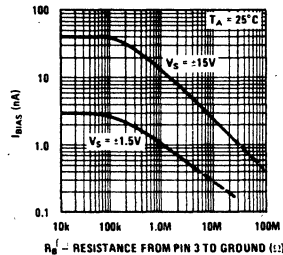


FIGURE 9. Input Bias Current as a Function of R_B

As indicated above, R_B may be returned to the negative supply voltage. Input bias current may then be predicted by:

$$I_{BIAS} \cong \frac{(V^+ - V^-) - 0.5}{4 \times 10^8 + 800 R_B}$$

applications information (con't)

or

$$R_B \cong \frac{(V^+ - V^-) - 0.5 - (4 \times 10^8)(I_{BIAS})}{800 I_{BIAS}} \quad (8)$$

Where:

- I_{BIAS} = Input Bias Current (nA)
- R_B = External resistor connected between pin 3 and V^- (Ohms)
- V^+ = Positive Supply Voltage (Volts)
- V^- = Negative Supply Voltage (Volts)

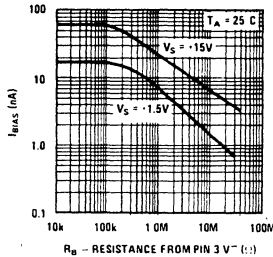


FIGURE 10. Input Bias Current as a Function of R_B

Figure 10 is a plot of input bias current versus R_B returned to V^- it should be noted that bandwidth is affected by changes in R_B . Figure 11 is a plot of bandwidth versus R_B .

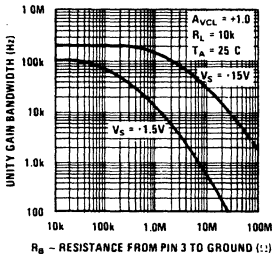


FIGURE 11. Unity Gain Bandwidth as a Function of R_B

BIAS CURRENT RETURN PATH CONSIDERATIONS

The LH0036 exhibits input bias currents typically in the 40 nA region in each input. This current must flow through R_{ISO} as shown in Figure 12.

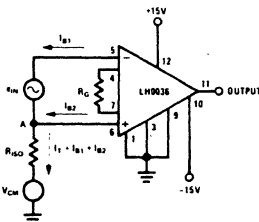


FIGURE 12. Bias Current Return Path

In a typical application, $V_S = \pm 15V$, $I_{B1} \cong I_{B2} \cong 40$ nA, the total current, I_T , would flow through R_{ISO} causing a voltage rise at point A. For values of $R_{ISO} \geq 150$ M Ω , the voltage at point A exceeds the +12V common range of the device. Clearly, for $R_{ISO} = \infty$, the LH0036 would be driven to positive saturation.

The implication is that a finite impedance must be supplied between the input and power supply ground. The value of the resistor is dictated by the maximum input bias current, and the common mode voltage. Under worst case conditions:

$$R_{ISO} \leq \frac{V_{CMR} - V_{CM}}{I_T} \quad (9)$$

Where:

V_{CMR} = Common Mode Range (10V for the LH0036)

V_{CM} = Common Mode Voltage

$$I_T = I_{B1} + I_{B2}$$

In applications in which the signal source is floating, such as a thermocouple, one end of the source may be grounded directly or through a resistor.

GUARD OUTPUT

Pin 2 of the LH0036 is provided as a guard drive pin in those stringent applications which require very low leakage and minimum input capacitance. Pin 2 will always be biased at the input common mode voltage. The source impedance looking into pin 2 is approximately 15 k Ω . Proper use of the guard/shield pin is shown in Figure 13.

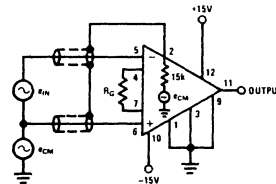


FIGURE 13. Use of Guard

For applications requiring a lower source impedance than 15 k Ω , a unity gain buffer, such as the LH0002 may be inserted between pin 2 and the input shields as shown in Figure 14.

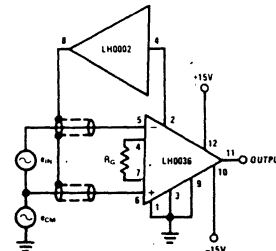


FIGURE 14. Guard Pin With Buffer

definition of terms

Bandwidth: The frequency at which the voltage gain is reduced to 0.707 of the low frequency (dc) value.

Closed Loop Gain, A_{VCL} : The ratio of the output voltage swing to the input voltage swing determined by $A_{VCL} = 1 + (50k/R_G)$. Where: R_G = Gain Set Resistor.

Common Mode Rejection Ratio: The ratio of input voltage range to the peak-to-peak change in offset voltage over this range.

Gain Equation Accuracy: The deviation of the actual closed loop gain from the predicted closed loop gain, $A_{VCL} = 1 + (50k/R_G)$ for the specified closed loop gain.

Input Bias Current: The current flowing at pin 5 and 6 under the specified operating conditions.

Input Offset Current: The difference between the input bias current at pins 5 and 6; i.e. $I_{OS} = |I_5 - I_6|$.

Input Stage Offset Voltage, V_{IOS} : The voltage which must be applied to the input pins to force the output to zero volts for $A_{VCL} = 100$.

Output Stage Offset Voltage, V_{OOS} : The voltage which must be applied to the input of the output stage to produce zero output voltage. It can be measured by measuring the overall offset at unity gain and subtracting V_{IOS} .

$$V_{OOS} = \left[V_{OS} \Big|_{A_{VCL} = 1} \right] - \left[V_{OS} \Big|_{A_{VCL} = 1000} \right]$$

Overall Offset Voltage:

$$V_{OS} = V_{IOS} + \frac{V_{OOS}}{A_{VCL}}$$

Power Supply Rejection Ratio: The ratio of the change in offset voltage, V_{OS} , to the change in supply voltage producing it.

Resistor, R_B : An optional resistor placed between pin 3 of the LH0036 and ground (or V^-) to reduce the input bias current.

Resistor, R_{BW} : An optional resistor placed between pin 1 of the LH0036 and ground (or V^-) to reduce the bandwidth of the output stage.

Resistor, R_G : A gain setting resistor connected between pins 4 and 7 of the LH0036 in order to program the gain from 1 to 1000.

Settling Time: The time between the initiation of an input step function and the time when the output voltage has settled to within a specified error band of the final output voltage.

LH0038/LH0038C True Instrumentation Amplifier

General Description

The LH0038/LH0038C is a precision true instrumentation amplifier (TIA) capable of amplifying very low level signals, such as thermocouple and low impedance strain gauge outputs. Precision thin film gain setting resistors are included in the package to allow the user to set the closed-loop gain from 100 to 2000. Since the resistors are of a homogeneous single chip construction, they track almost perfectly so that temperature variations of closed loop gain are virtually eliminated.

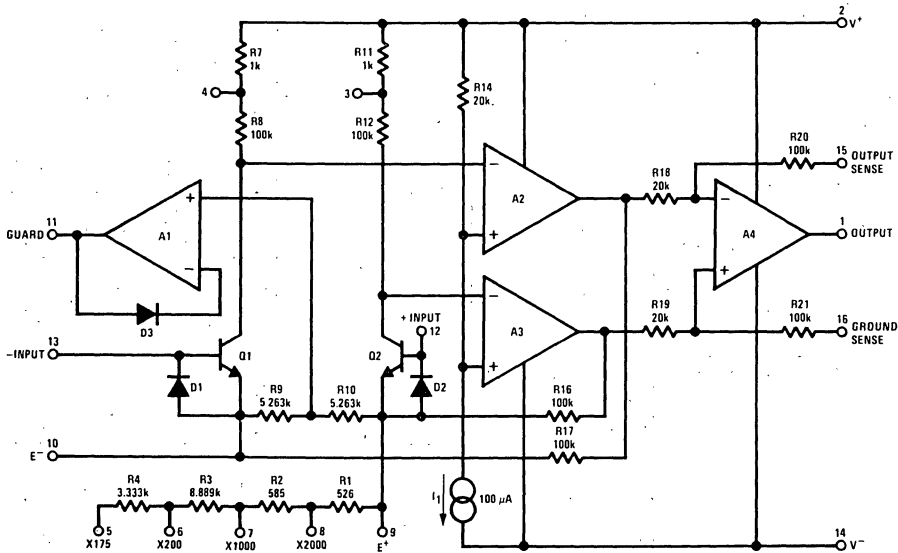
LH0038 exhibits excellent CMRR, PSRR, gain linearity, as well as extremely low input offset voltage, offset voltage drift and input noise voltage.

The devices are provided in a hermetically sealed 16-lead DIP. The LH0038 is guaranteed from -55°C to $+125^{\circ}\text{C}$; whereas the LH0038C is guaranteed from -25°C to $+85^{\circ}\text{C}$.

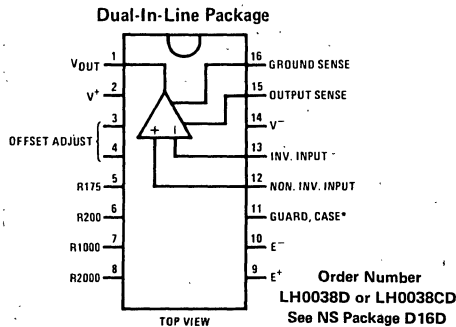
Features

- Ultralow offset voltage $25\ \mu\text{V}$ typ., $100\ \mu\text{V}$ max
- Ultralow offset drift $0.25\ \mu\text{V}/\text{C}$ max
- Ultralow input noise $0.2\ \mu\text{Vp-p}$
- Pin strap gain options 100, 200, 400, 500, 1k, 2k
- Excellent PSRR and CMRR 120 dB

Simplified Schematic Diagram



Connection Diagram



* Guard output is connected to the case.

Order Number
LH0038D or LH0038CD
See NS Package D16D

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Differential Input Voltage (Note 1) | ±1V |
| Input Voltage | ±V _S |
| Power Dissipation (See Curve) | 500 mW |
| Short Circuit Duration | Continuous |
| Operating Temperature Range | |
| LH0038 | -55°C to +125°C |
| LH0038C | -25°C to +85°C |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 20 seconds) | 300°C |

DC Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LH0038 | | | LH0038C | | | UNITS |
|--|--|-----------------------|------|------|---------|-----|--------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| V _{IOS} Input Offset Voltage | R _S = 50Ω V _{CM} = 0V | T _A = 25°C | 25 | 100 | 30 | 150 | μV | |
| ΔV _{IOS} /ΔT Input Offset Voltage Tempco | | | 0.1 | 0.25 | 0.2 | 1.0 | | μV/°C |
| V _{OOS} Output Offset Voltage | V _{CM} = 0V | T _A = 25°C | 3 | 10 | 5 | 25 | mV | |
| ΔV _{OOS} /ΔT Output Offset Voltage Tempco | | | 25 | | 25 | | | μV/°C |
| I _B Input Bias Current | V _{CM} = 0V | T _A = 25°C | 50 | 100 | 50 | 100 | nA | |
| I _{OS} Input Offset Current | | | 2 | 5 | 7 | 10 | | |
| ΔI _B /ΔT Input Bias Current Tempco | | | | 500 | | 500 | | ppA/°C |
| AV _{CL} Closed Loop Gain | Gain Pins Jumpered | | | | | | V/V | |
| | None | | 100 | | 100 | | | |
| | 6-10 | | 200 | | 200 | | | |
| | 6-9, 10-5 | | 400 | | 400 | | | |
| | 6-10, 5-9 | | 500 | | 500 | | | |
| | 7-10 | | 1000 | | 1000 | | | |
| | 8-10 | | 2000 | | 2000 | | | |
| Closed Loop Gain Error | AV _{CL} = 100, 200 | | 0.1 | 0.3 | 0.1 | 0.4 | % | |
| | AV _{CL} = 400, 500 | | 0.2 | 0.3 | 0.2 | 0.6 | | |
| | AV _{CL} = 1000 | | 0.3 | 0.5 | 0.5 | 1.0 | | |
| | AV _{CL} = 2000 | | 1.0 | 2.0 | 1.5 | 3.0 | | |
| Gain Temperature Coefficient | AV _{CL} = 1k | | 7 | | 7 | | ppm/°C | |
| Gain Nonlinearity | 100 ≤ AV _{CL} ≤ 2k | | 1 | | 1 | | ppm | |
| V _{INCM} Common-Mode Input Voltage Range | | ±10 | ±12 | | ±10 | ±12 | V | |
| V _O Output Voltage | R _L ≥ 10 kΩ | ±10 | ±12 | | ±10 | ±12 | | |
| V _S Supply Voltage Range | | ±5 | | ±18 | ±5 | ±18 | | |
| Guard Voltage Error | -10V < V _{CM} < +10V | | ±10 | ±100 | | ±10 | ±100 | mV |

DC Electrical Characteristics (Note 2) (Continued)

| PARAMETER | | CONDITIONS | | LH0038 | | | LH0038C | | | UNITS |
|----------------------|------------------------------|---------------------------------------|------------------|---------|---------|----------|---------|---------|----------|------------|
| | | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| CMRR | Common-Mode Rejection Ratio | $V_{IN} = \pm 10V$ | $AV_{CL} = 100$ | 94 | 110 | | 86 | 110 | | dB |
| | | | $AV_{CL} = 1000$ | 114 | 120 | | 106 | 110 | | |
| PSRR | Power Supply Rejection Ratio | $\pm 5V \leq \Delta V_S \leq \pm 15V$ | $AV_{CL} = 100$ | 94 | 110 | | 94 | 110 | | dB |
| | | | $AV_{CL} = 1000$ | 110 | 120 | | 100 | 110 | | |
| I _{OSC} | Output Short Circuit Current | $T_A = 25^\circ C$ | | ± 2 | ± 5 | ± 10 | ± 2 | ± 5 | ± 10 | mA |
| I _S | Supply Current | $T_A = 25^\circ C$ | | | 1.6 | 2.0 | | 1.6 | 3.0 | |
| R _{IN DIFF} | Input Resistance | $AV_{CL} = 1000, T_A = 25^\circ C$ | | | 5 | | | 5 | | M Ω |
| R _{IN CM} | Common-Mode Input Resistance | | | | 1 | | | 1 | | G Ω |
| R _{OUT} | Output Resistance | | | | 1 | | | 1 | | m Ω |

AC Electrical Characteristics $V_S = \pm 15V, T_A = 25^\circ C$

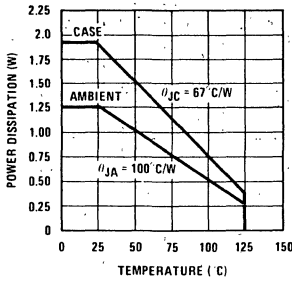
| PARAMETER | | COMMENT | CONDITIONS | | TYP | UNITS |
|----------------|-------------------------------------|-----------|-----------------------------|------------------|-----|-----------------|
| e _n | Equivalent Input Noise Voltage | Figure 1 | $R_S = 0, f = 0.1$ to 10 Hz | | 0.2 | μV_{p-p} |
| \bar{e}_n | Equivalent Input Spot Noise Voltage | Figure 1 | $R_S = 100\Omega$ | f = 10 Hz | 6.5 | nV/ \sqrt{Hz} |
| | | | | f = 100 Hz | 6.0 | |
| | | | | f = 1 kHz | 6.0 | |
| | | | | f = 10 kHz | 6.0 | |
| BW | Large Signal Bandwidth | | $V_{OUT} = \pm 10V$ | | 1.6 | kHz |
| S _r | Slew Rate | | $V_{OUT} = \pm 10V$ | | 0.3 | V/ μs |
| t _s | Settling Time to 0.01% | Figure 13 | | 20V Step | 120 | μs |
| | | | | -10V Step | 80 | |
| | | | | +10V Step | 60 | |
| t _r | Rise Time | | $\Delta V_{OUT} = 100$ mV | $AV_{CL} = 100$ | 6 | μs |
| | | | | $AV_{CL} = 1000$ | 13 | |
| \bar{i}_n | Equivalent Input Spot Noise Current | | $R_S = 100$ M Ω | f = 10 Hz | 0.1 | pA/ \sqrt{Hz} |

Note 1: The inputs are protected by diodes for overvoltage protection. Excessive currents will flow for differential voltages in excess of $\pm 1V$. Input current should be limited to less than 10 mA.

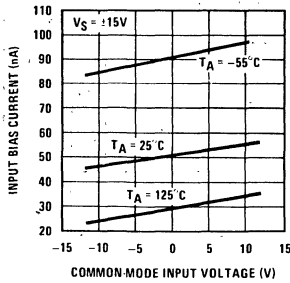
Note 2: Unless otherwise noted these specifications apply for $V_S = \pm 15.0V$, pin 15 connected to pin 1, pin 16 connected to ground, over the temperature range $-55^\circ C$ to $+125^\circ C$ for the LH0038 and $-25^\circ C$ to $+85^\circ C$ for LH0038C.

Typical Performance Characteristics

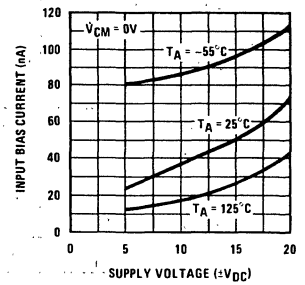
Power Dissipation



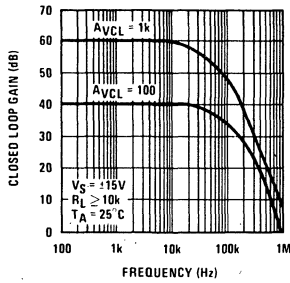
Input Bias Current



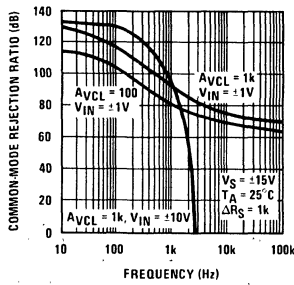
Input Bias Current



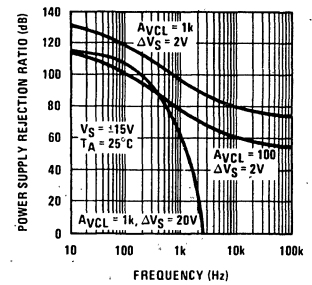
Closed Loop Frequency Response



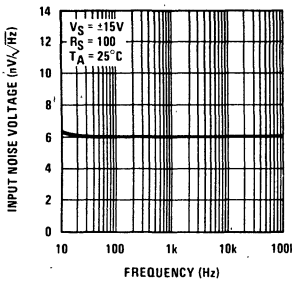
Common-Mode Rejection



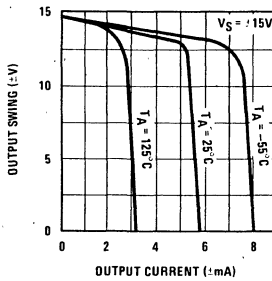
Power Supply Rejection



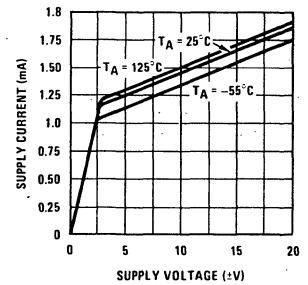
Input Noise Voltage (Includes Source Impedance)



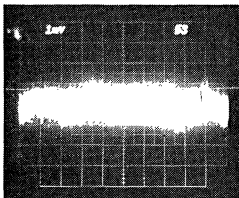
Output Swing



Supply Current

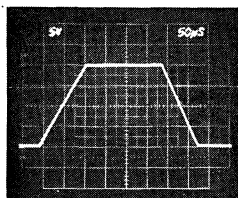


Wide Band Noise



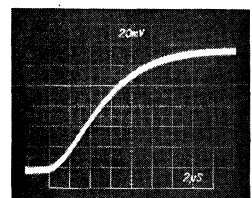
VS = ±15V, RS = 1kΩ, AV = 10k, DUT = 1k
 Vertical sensitivity: 0.1 μV/CM
 Horizontal sensitivity: 5 sec/CM
 Bandwidth: 0.1 Hz to 10 Hz

Pulse Response



VS = ±15V
 RL ≥ 10kΩ
 AVCL = 1k

Rise Time



VS = ±15V
 RL ≥ 10kΩ
 AVCL = 1k

Noise Test Circuit

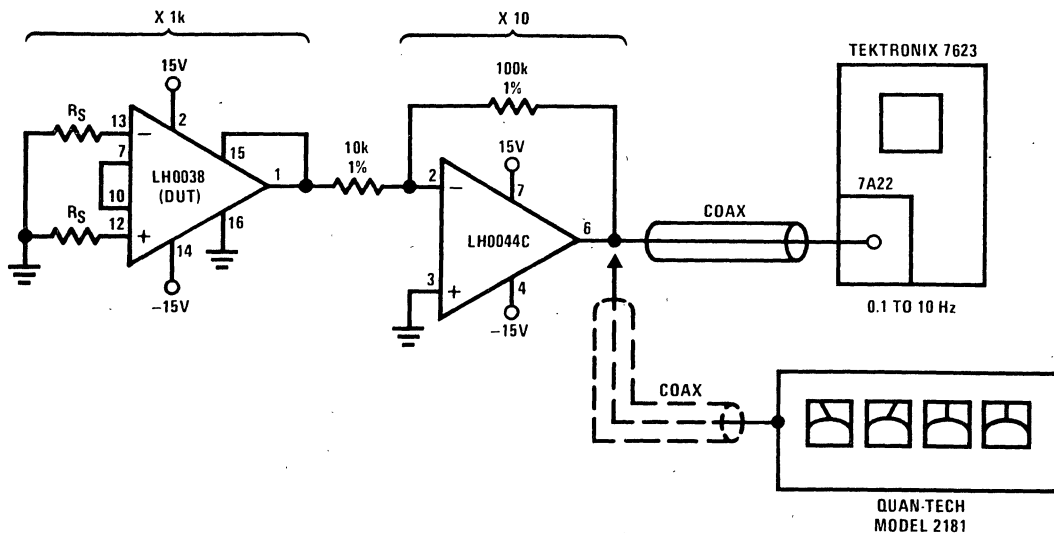


FIGURE 1.

Typical Application

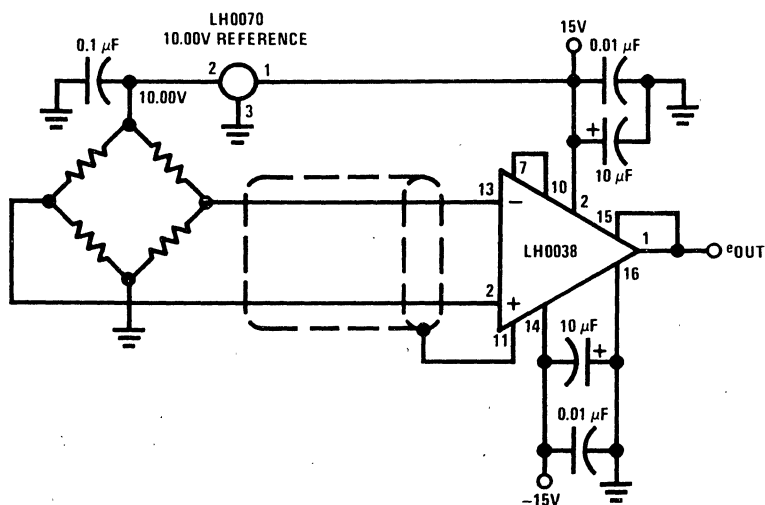


FIGURE 2. X1000 Bridge Amplifier

Applications Information

THEORY OF OPERATION

The LH0038 is a 3-stage, true instrumentation amplifier composed of a well matched transistor differential pair, Q1 and Q2, a common-mode loop amplifier, A2 and A3, and a differential to single ended amplifier, A4. A simplified schematic is shown in Figure 3.

Current source, I_A , establishes a voltage across R14 of approximately 2V, which results in a 2V drop across R8 and R12. This constant voltage forces the first stage

current to be 20 μA per side. The action of A2 and A3 is such that 20 μA is maintained constant despite the presence of common-mode signals. The differential outputs of A2 and A3 are applied to differential amplifier, A4, which converts the signal to a single-ended output and provides a gain of 5. The total gain of the amplifier is, therefore, the fixed gain of 5 multiplied by the gain of the composite input stage.

Applications Information (Continued)

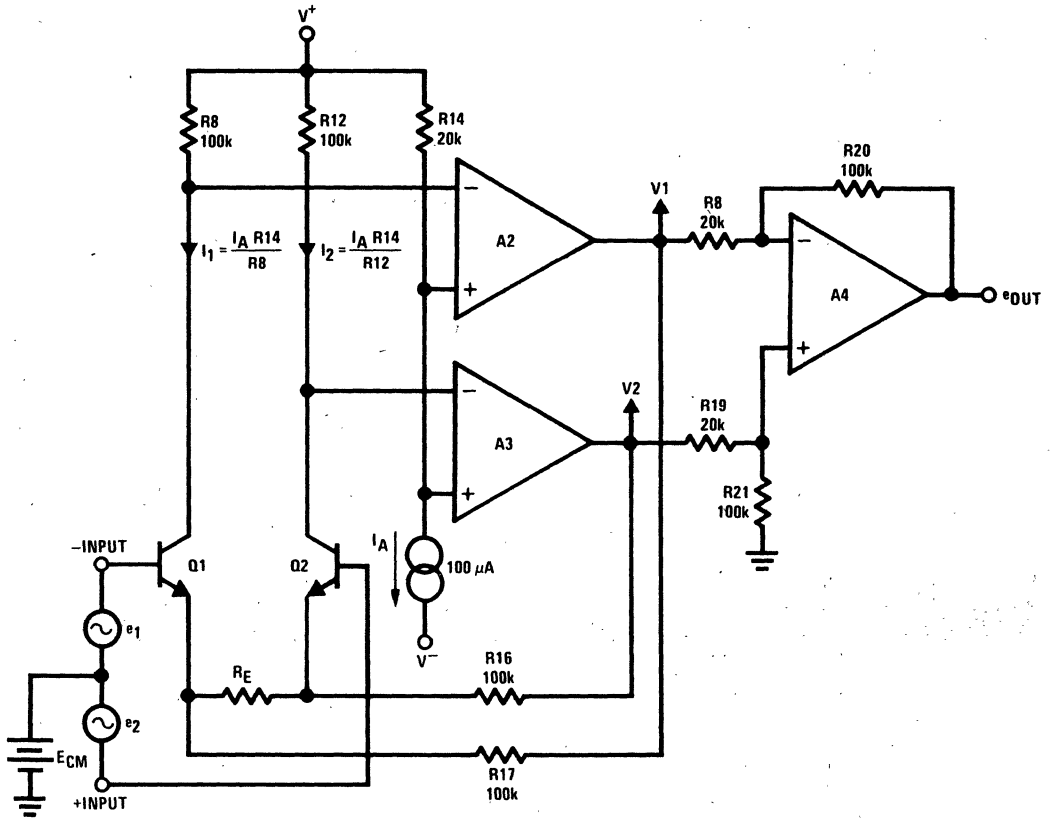


FIGURE 3. LH0038 Simplified Schematic

The closed loop gain of the composite amplifier may be better understood by referring to Figure 3. The Q1-A2 loop may be viewed as differential amplifier with the inverting input at the base and non-inverting input at the emitter. Combining small signal AC and large signal DC analysis =

$$v_1 = e_1 \left(\frac{R_{17} + R_E}{R_E} \right) - e_2 \left(\frac{R_{17}}{R_E} \right) \quad (1)$$

$$+ E_{CM} - V_{BE1} - I_1 R_{17}$$

By similar analysis:

$$v_2 = e_2 \left(\frac{R_{16} + R_E}{R_E} \right) - e_1 \left(\frac{R_{16}}{R_E} \right) \quad (2)$$

$$+ E_{CM} - V_{BE2} - I_2 R_{16}$$

For $I_1 \equiv I_2$, $R_{17} \equiv R_{16}$, $V_{BE1} \equiv V_{BE2}$, subtracting equation (1) from (2) results in:

$$v_2 - v_1 = (e_2 - e_1) \left(\frac{R_{16} + R_E}{R_E} \right) + (e_2 - e_1) \left(\frac{R_{16}}{R_E} \right) \quad (3)$$

$$+ (e_2 - e_1) \left(\frac{R_{16}}{R_E} \right)$$

$$\frac{v_2 - v_1}{e_2 - e_1} = \frac{2 R_{16}}{R_E} + 1 \quad (4)$$

Applications Information (Continued)

The differential input voltage ($v_2 - v_1$) is amplified by the closed loop gain of A4:

$$e_{OUT} = (AV_{CL4})(e_2 - e_1) \quad (5)$$

where:

$$AV_{CL4} = \frac{R_{20}}{R_8} = 5.00$$

$$AV_{CL} = 5 \left(\frac{2R_{16}}{R_E} + 1 \right) \quad (6)$$

As an example, with all gain pins open, $R_E = 10.526 \text{ k}\Omega$, and:

$$AV_{CL} = 5 \left(\frac{(2)(100k)}{10.526k} + 1 \right) = 100.0 \quad (7)$$

All other closed loop gain configurations place a precision resistor in parallel with $R_E (R_9 + R_{10})$. For example, for a gain of 200, pin 6 is connected to pin 10 and the gain is predicted by:

$$AV_{CL} = 5.00 \left[\frac{(2)(100k)}{(10.526k) \parallel (10.000k)} + 1 \right] = (5.00)(40) = 200 \quad (8)$$

CLOSED LOOP GAIN CONSIDERATIONS USING INTERNAL RESISTORS

Table I summarizes the primary gain configurations available with the LH0038. Obviously, other gains are possible. Using the internally supplied resistors has the advantage that R_{16} , R_{17} , and R_E all track thermally, minimizing the device's gain error as a function of temperature.

Gain adjustment by paralleling or series padding internally supplied resistors is generally discouraged since external resistors will generally not thermally track. It is recommended that the gain adjustment be done in a subsequent stage as shown in *Figure 4*.

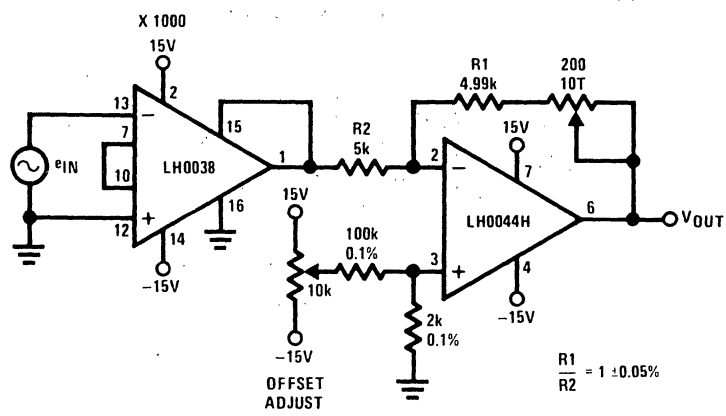


FIGURE 4. Recommended Gain Adjust Circuit

TABLE I. LH0038 INTERNAL GAIN CONFIGURATIONS

| OVERALL GAIN | FIRST STAGE GAIN | PIN CONNECTIONS | EFFECTIVE R_E |
|--------------|------------------|---------------------------------|--------------------|
| 100 | 20 | All Gain Pins Open | 10.5260 k Ω |
| 200 | 40 | Pin 6 to Pin 10 | 5.1281 k Ω |
| 400 | 80 | Pin 6 to Pin 9, Pin 10 to Pin 5 | 2.5316 k Ω |
| 500 | 100 | Pin 6 to Pin 10, Pin 9 to Pin 5 | 2.0202 k Ω |
| 1000 | 200 | Pin 7 to Pin 10 | 1.0050 k Ω |
| 2000 | 400 | Pin 8 to Pin 10 | 0.5013 k Ω |

Applications Information (Continued)

GUARD DRIVE

The LH0038 is provided with a guard drive output, which will always be at the input common-mode voltage. The guard drive amplifier is short-circuit proof and is capable of driving several thousand pF without danger of latch-up or oscillation.

The guard drive tied to a shielded input cable will greatly reduce noise pick-up, and also improve AC CMRR by maintaining the shield at the common-mode voltage. *Figure 5* illustrates the proper use of the guard drive.

The guard drive output is also connected to the case to provide electrostatic shielding to the system.

REMOTE OUTPUT SENSE

The feedback network of the LH0038 may be closed directly at the load in order to eliminate errors due to lead resistance. Also, a unity gain buffer; e.g. LH0002, may be included within the feedback loop to increase output current capability as shown in *Figure 7*.

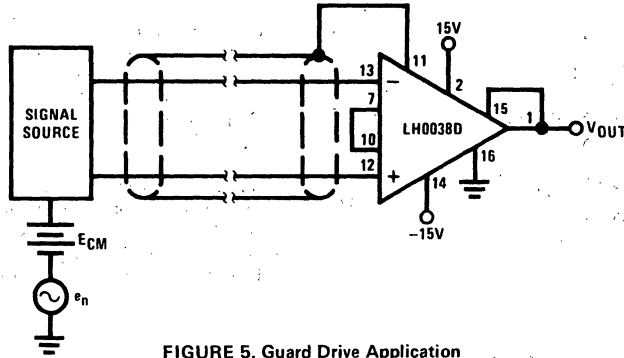


FIGURE 5. Guard Drive Application

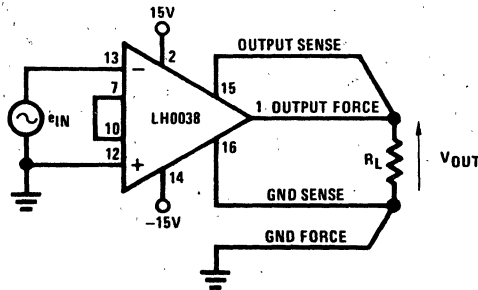


FIGURE 6. Remote Sense Connection

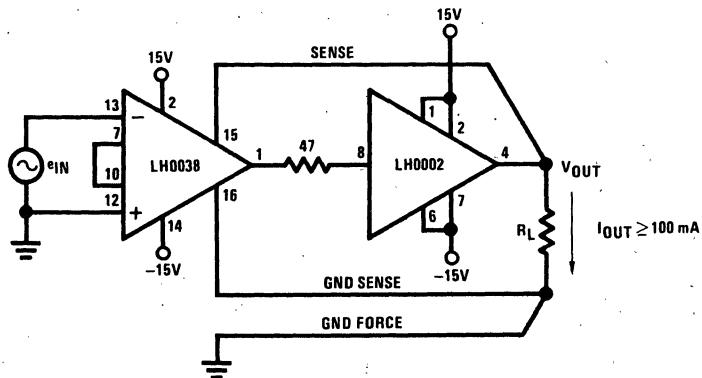


FIGURE 7. Output Buffer Connection

Applications Information (Continued)

OFFSET NULL

Offset of the LH0038 is trimmed by the factory to a very low value. The offset may be further trimmed using a 10 kΩ, 10 turn, 100 ppm/°C potentiometer as shown in Figure 8. However, a drift increase of 0.3 μV/°C will be caused for each 100 μV of offset adjusted. The recommended offset null is shown in Figure 4 and is accomplished in the following stage.

BIAS CURRENT CONSIDERATIONS

The LH0038 exhibits bias current of approximately 50 nA per side, and requires a path to ground or supply. The practical limitation to the maximum resistance between the inputs and ground is dictated by negative common-mode range as shown in Figure 9. For example, for V_{CM} = -10V, R_{CM} ≤ 20 MΩ.

The LH0038 input stage bias was optimized for minimum voltage noise so the input bias currents are higher than might otherwise be expected. Note, however, that the input currents are very well matched, resulting in an offset current value much lower than one might infer from the bias current. In order to take advantage of this low offset current, the source impedances at both inputs should be matched to minimize DC drift. Further, bias current is relatively constant with temperature (as opposed to an FET stage), so one can consider bias current compensation schemes such as shown in Figure 10. The danger with such techniques is that the offset current and noise contributed by the bias current compensator will dominate the system noise.

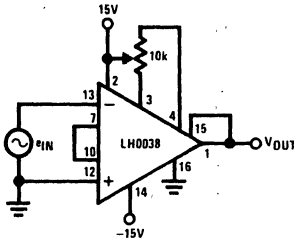


FIGURE 8. Offset Adjust Circuit
(See also Figure 4)

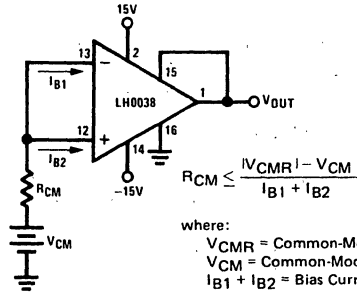


FIGURE 9. Bias Current Return

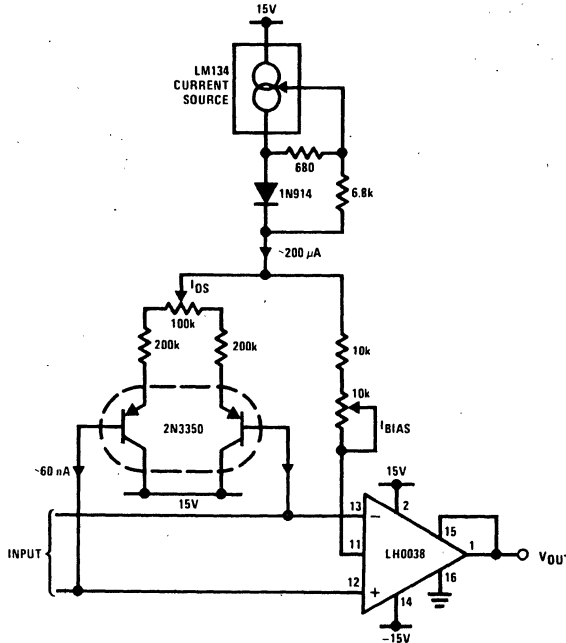


FIGURE 10. Bias Current Compensation

Applications Information (Continued)

SETTLING TIME

The LH0038 has been purposely over-compensated, and is therefore remarkably free from any undesirable transient response. Small signal settling time is governed by gain-bandwidth product; large signal settling time is dominated by slew rate.

Figure 11 shows an input voltage step of +10V to -10V applied, through a 1000 to 1 voltage divider, to the device configured for an inverting gain of 1000. The output of the device will therefore be equal to the negative of the input after the device is completely settled. By resistively subtracting the input before the divider from the device output, a pseudo summing junction is generated. The voltage at this pseudo summing junction goes "off screen" on the photos, since in the first small time increment the input goes instantaneously to -10 mV and the output is still at +10V. About 130 μ s after the input has gone negative, the output slews back in range and begins an exponential approach to the final value. Figure 12 is the same set-up for a -10V to +10V input pulse. Note that there is no overshoot in either case. The test circuit is shown in Figure 13.

HIGH FREQUENCY CMRR

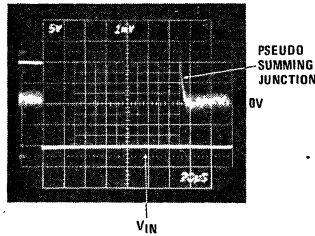
The LH0038 resistor ratios are carefully trimmed for optimum CMRR at DC through 60 Hz. Inevitably, this rejection will degrade at higher frequencies due to 2 separate effects: stray capacitance mismatch and slew rate limiting in the input stage. In most discrete instru-

mentation amplifier realizations, the stray capacitance mismatch dominates simply because the stray capacitances are relatively large (this can be trimmed out in a discrete amplifier). In a hybrid circuit such as the LH0038, stray capacitance is minimized, so the effects of mismatch are also minimized.

The response to a pulse or noise spike applied as a common-mode signal may be dominated by the slow characteristics of the input stage. Whenever the common-mode input slew rate exceeds 0.2 V/ μ s, the 2 input amplifiers will apply identical ramp signals to the final stage and cause its output to go to near 0V. Note that the amplifier is not really active under these conditions as normal mode signal variations will *not* be coupled to the output. Some time may be required for the amplifier to settle after a transient of this kind before the output can be considered representative of the input. Slew rate limiting will not normally be the limiting factor for sine wave common-mode signals as 0.2 V/ μ s corresponds to about 2 kHz (20 Vp-p).

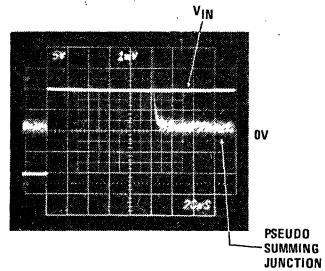
POWER SUPPLY DECOUPLING

Although the LH0038 exhibits in excess of 120 dB PSRR at DC, the figure degrades to 100 dB at 120 Hz. It is recommended that both V^+ and V^- leads be bypassed with 1 μ F electrolytic in shunt with 0.01 μ F ceramic disc no further than 1 inch from the device.



$t_s, A_V = 100, V_{IN} = 20V$

FIGURE 11. Settling Time



$t_s, A_V = 100, V_{IN} = 20V$

FIGURE 12. Settling Time

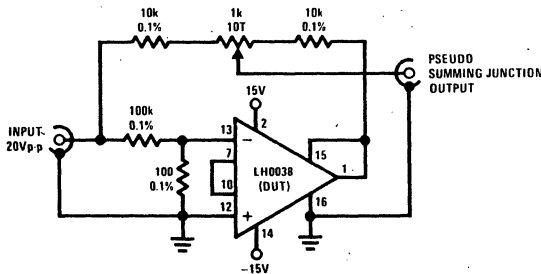


FIGURE 13. Settling Time Test Circuit

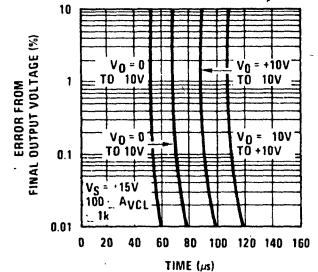


FIGURE 14. Settling Time

Definition of Terms

Bandwidth: That frequency at which the voltage gain is reduced to 3 dB below the low frequency value.

Common-Mode Rejection Ratio, CMRR: The ratio of the input common-mode voltage range to the peak-to-peak change in input offset voltage over this range.

Input Offset Voltage, V_{IOS} : The voltage which must be applied to the inputs to force the outputs of the input stage to 0V. V_{IOS} can be calculated by measuring V_{OS} at closed loop gains of 100 and 2000 and using the following equation:

$$V_{IOS} = \frac{(V_{OS})_{2k} - (V_{OS})_{100}}{1900}$$

Where:

$(V_{OS})_{2k}$ = overall offset voltage for $A_{VCL} = 2k$.

$(V_{OS})_{100}$ = overall offset voltage for $A_{VCL} = 100$.

Gain Non-Linearity: The deviation of the gain from a straight line drawn through the end points expressed as a percent of full-scale (10V for operations on $\pm 15V$ supply). Note that this is a more stringent specification than deviation from the best straight line and is double the number that would be specified if the percentage were based on a 20V ($\pm 10V$) range.

Guard Voltage Error: The voltage difference between the guard drive output and the average of the 2 input voltages.

Input Bias Current, I_B : The average of the 2 input currents.

Input Common-Mode Voltage Range, V_{INCM} : The range of voltages on the input terminals for which the amplifier is operational. Note that the specifications are not guaranteed over the full common-mode voltage range unless specifically stated.

Input Offset Current, I_{OS} : The difference in the currents into the 2 input terminals when the output is at zero.

Input Resistance: The ratio of the change in input voltage to the change in input current on either input with the other grounded.

Overall Offset Voltage, V_{OS} : The output voltage when both inputs are connected to 0V. V_{OS} is composed of input amplifier offset voltage effects, V_{IOS} , and output amplifier effects, V_{OOS} . It is given by:

$$V_{OS} = (A_{VCL}) (V_{IOS}) - V_{OOS}$$

Where:

A_{VCL} = closed loop gain = 100 to 2k

V_{IOS} = input stage offset voltage

V_{OOS} = output stage offset voltage

Output Offset Voltage, V_{OOS} : The output voltage when the outputs of the input stage are forced to 0V. V_{OOS} may be calculated by measuring V_{OS} at closed loop gains of 100 and 2000 and using the following equation:

$$V_{OOS} = \frac{(V_{OS})_{100} - (V_{OS})_{2k}}{19}$$

Where:

$(V_{OS})_{100}$ = overall offset voltage for $A_{VCL} = 100$

$(V_{OS})_{2k}$ = overall offset voltage for A_{VCL}

Output Voltage, V_O : The peak output voltage swing, referred to zero.

Offset Voltage Temperature Drift, $\Delta V_{IOS}/\Delta T$: The average drift rate of offset voltage for a thermal variation from room temperature to the indicated temperature extreme.

Power Supply Rejection Ratio, PSRR: The ratio of the change in input offset voltage to the change in power supply voltages producing it.

Settling Times, t_s : The time between the initiation of the input step function and the time when the output voltage has settled to within a specified error band of the final output voltage.

Slew Rate, S_r : The internally-limited rate of change in output voltage with a large-amplitude step function applied to the input.

Supply Current, $\pm I_S$: The current required from the power supply to operate the amplifier with no load and the output midway between the supplies.

Supply Voltage Range: The range of voltages on the supply terminals for which the device is operational. Note that the specifications are not guaranteed over the full supply voltage range unless specifically stated.

Transient Response, t_r : The closed-loop step-function response of the amplifier under small-signal conditions.

Unity Gain Bandwidth: The frequency range from DC to the frequency where the amplifier open loop gain rolls off to 1.

Closed Loop Gain, A_{VCL} : The ratio of output voltage to input voltage under the stated conditions of source resistance (R_S) and load resistance (R_L).

Voltage Gain Error: The deviation in percent between the ideal voltage gain and the value obtained when the device is configured for that gain.

LH0084/LH0084C Digitally Programmable Gain Instrumentation Amplifier

General Description

The LH0084/LH0084C is a self-contained, high speed, high accuracy, digitally programmable gain instrumentation amplifier. It consists of a FET input, variable gain voltage follower input stage followed by a differential output stage. The input stage is programmable to accurate gain steps of 1, 2, 5, or 10 controlled by the logic levels of a 2-bit TTL-compatible digital input word. For additional flexibility, the output stage is pin-strappable to fixed gains of 1, 4, or 10 for an overall gain range of 1 to 100.

Applications include increased dynamic range A-to-D converters, test systems, and post multiplexer amplifier for data acquisition systems where its short settling time speeds channel sampling.

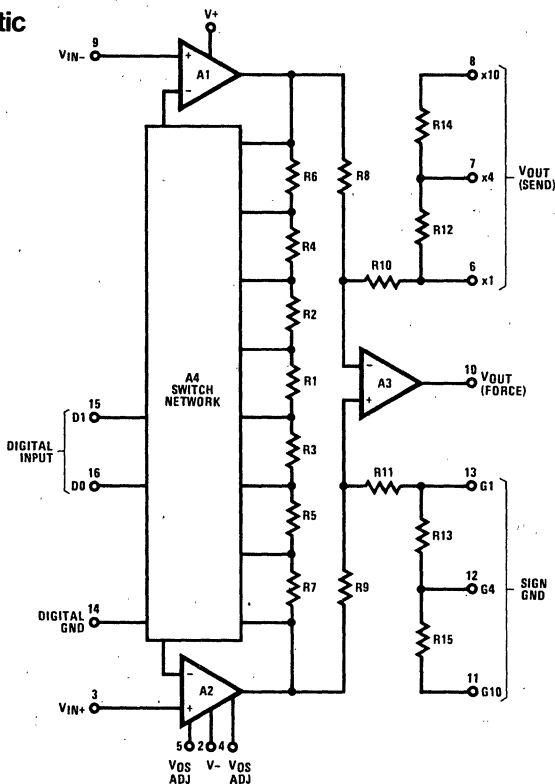
The device exhibits high input impedance, low offset voltage, high CMRR and PSRR, high speed, and excellent gain accuracy and gain non-linearity.

The LH0084 is guaranteed for operation from -55°C to $+125^{\circ}\text{C}$, whereas the LH0084C is guaranteed from -25°C to $+85^{\circ}\text{C}$. Both devices are provided in a hermetically sealed 16-lead dual-in-line metal package.

Features

- Excellent gain accuracy and gain non-linearity 0.002% typ
- Extremely low gain drift 1 ppm/ $^{\circ}\text{C}$
- High input impedance 10 Ω typ
- High CMRR and PSRR 76 dB min
- TTL-compatible digital inputs
- High speed, settling to 0.1% 5 μs max

Simplified Schematic





Section 5

Voltage Comparators





Section Contents

| | |
|---|-------|
| Voltage Comparator Guide..... | 5-iii |
| Definition of Terms..... | 5-iv |
| LF111/LF211/LF311 Voltage Comparators..... | 5-1 |
| LM106/LM206/LM306 Voltage Comparators..... | 5-9 |
| LM111/LM211 Voltage Comparator..... | 5-12 |
| LM119/LM219/LM319 High Speed Dual Comparator..... | 5-18 |
| LM139/LM239/LM339, LM139A/LM239A/LM339A, LM2901, LM3302 Low Power Low Offset Voltage Quad Comparators..... | 5-23 |
| LM160/LM260/LM360 High Speed Differential Comparator..... | 5-31 |
| LM161/LM261/LM361 High Speed Differential Comparators..... | 5-34 |
| LM193/LM293/LM393, LM193A/LM293A/LM393A, LM2903 Low Power Low Offset Voltage Dual Comparators..... | 5-37 |
| LM311 Voltage Comparator..... | 5-44 |
| LM710/LM710C Voltage Comparator..... | 5-52 |
| LM711/LM711C Dual Comparator..... | 5-55 |
| LM1514/LM1414 Dual Differential Voltage Comparator..... | 5-58 |

| Device | Temperature Range* | DTL/TTL Fanout | Supply Voltage Typ (V) | Input Bias Current (25°C) Max (μA) | Input Offset Current (25°C) Max (μA) | Input Offset Voltage (25°C) Max (mV) | Response Time ¹ Typ (ns) | Voltage Gain Typ | Package Type | Comments |
|----------------------|--------------------|----------------|------------------------|------------------------------------|--------------------------------------|--------------------------------------|-------------------------------------|------------------|---------------|---|
| LM106 | Military | 10 | $V^+ = 12$ | 20 | 3 | 2 | 40 max | 40k | TO-5 F.P. | Single comparator with strobe, high speed and sensitivity, large fanout |
| LM206 | Industrial | 10 | $V^- = -3$ | 20 | 3 | 2 | 40 max | 40k | TO-5 F.P. | |
| LM306 | Commercial | 10 | To -12 | 25 | 5 | 5 | 40 max | 40k | TO-5 F.P. | |
| LF111 | Military | 2 | 36 | 0.05 | 0.00025 | 4 | 200 | 200k | TO-5 DIP F.P. | FET front-end inputs |
| LF211 | Industrial | 2 | 36 | 0.05 | 0.00025 | 4 | 200 | 200k | TO-5 DIP F.P. | |
| LF311 | Commercial | 2 | 36 | 0.15 | 0.00075 | 10 | 200 | 200k | TO-5 DIP F.P. | |
| LM111 | Military | 5 | ±15 | 0.1 | 0.04 | 0.7 | 200 | 200k | TO-5 DIP F.P. | Single, with strobe, will work from single supply, low bias current |
| LH2111 Dual (Note 1) | Military | 5 | ±15 | 0.1 | 0.04 | 0.7 | 200 | 200k | TO-5 DIP F.P. | |
| LM211 | Industrial | 5 | To 5 | 0.1 | 0.04 | 0.7 | 200 | 200k | TO-5 DIP F.P. | |
| LH2211 Dual (Note 1) | Industrial | 5 | To 5 | 0.1 | 0.04 | 0.7 | 200 | 200k | TO-5 DIP F.P. | |
| LM311 | Commercial | 5 | And GND | 0.25 | 0.06 | 2 | 200 | 200k | TO-5 DIP F.P. | |
| LH2311 Dual (Note 1) | Commercial | 5 | And GND | 0.25 | 0.06 | 2 | 200 | 200k | TO-5 DIP F.P. | |
| LM119 | Military | 2 (Each Side) | ±15 | 0.5 | 0.075 | 4 | 80 | 40k | TO-5 DIP F.P. | |
| LM219 | Industrial | 2 (Each Side) | To 5 | 0.5 | 0.075 | 4 | 80 | 40k | TO-5 DIP F.P. | |
| LM319 | Commercial | 2 (Each Side) | And GND | 1 | 0.2 | 8 | 80 | 40k | TO-5 DIP | |
| LM139 Quad | Military | 1 | ±1 | 0.1 | 0.025 | 5 | 1.3μs | 200k | DIP F.P. | Quad comparator designed for single supply operation, input common mode range includes ground |
| LM239 Quad | Industrial | 1 | To ±18 | 0.25 | 0.050 | 5 | 1.3μs | 200k | DIP | |
| LM339 Quad | Commercial | 1 | Or From | 0.25 | 0.050 | 5 | 1.3μs | 200k | DIP | |
| LM139A Quad | Military | 1 | 2 | 0.1 | 0.025 | 2 | 1.3μs | 200k | DIP F.P. | |
| LM239A Quad | Industrial | 1 | To 36 | 0.25 | 0.050 | 2 | 1.3μs | 200k | DIP | |
| LM339A Quad | Commercial | 1 | And GND | 0.25 | 0.050 | 2 | 1.3μs | 200k | DIP | |
| LM160 | Military | 2 | ±4.5 | 10 | 2 | 2 | 16 | 3k | TO-5 DIP F.P. | |
| LM260 | Industrial | 2 | To 10 | 10 | 2 | 2 | 16 | 3k | TO-5 DIP | |
| LM360 | Commercial | 2 | ±6.5 | 15 | 4 | 4 | 16 | 3k | TO-5 DIP | |
| LM161 (LM529) | Military | 2 | ±5 | 10 | 2 | 2 | 12 | 3k | TO-5 DIP F.P. | Very high speed, with individual strobes, DTL/TTL compatible |
| LM261 | Industrial | 2 | To ±15 | 10 | 2 | 2 | 12 | 3k | TO-5 DIP | |
| LM361 (LM529C) | Commercial | 2 | And 5 | 15 | 4 | 4 | 12 | 3k | TO-5 DIP | |
| LM193 | Military | 1 | ±1 | 0.1 | 0.025 | 5 | 1.3μs | 200k | TO-5 | Dual comparator designed for single supply operation; input common-mode range includes ground |
| LM293 | Industrial | 1 | To ±18 | 0.25 | 0.050 | 5 | 1.3μs | 200k | TO-5 | |
| LM393 | Commercial | 1 | Or From | 0.25 | 0.050 | 5 | 1.3μs | 200k | TO-5, DIP | |
| LM193A | Military | 1 | 2 | 0.1 | 0.025 | 2 | 1.3μs | 200k | TO-5 | |
| LM293A | Industrial | 1 | To 36 | 0.25 | 0.050 | 2 | 1.3μs | 200k | TO-5 | |
| LM393A | Commercial | 1 | And Gnd | 0.25 | 0.050 | 2 | 1.3μs | 200k | TO-5, DIP | |
| LM710 | Military | 1 | $V^+ = 12$ | 20 | 3 | 2 | 40 | 1750 | TO-5 | |
| LM710C | Commercial | 1 | $V^- = -6$ | 25 | 5 | 5 | 40 | 1500 | TO-5 DIP | |
| LM711 Dual | Military | 1 | $V^+ = 12$ | 75 | 10 | 3.5 | 40 | 1500 | TO-5 | |
| LM711C Dual | Commercial | 1 | $V^- = -6$ | 100 | 15 | 5 | 40 | 1500 | TO-5 DIP | Dual differential, common output, individual strobes |
| LM1514 Dual | Military | 1 | $V^+ = 14$ | 20 | 3 | 3 | 30 | 1250 | DIP | Dual LM710 with separate strobes, individual outputs |
| LM1414 Dual | Commercial | 1 | $V^- = -7$ | 25 | 5 | 4 | 30 | 1000 | DIP | |
| LM2901 Quad | Industrial | 1 | ±1 (2V) to ±18 (36) | 0.25 | 0.05 | 7 | 1.3 | 200k | DIP | Quad comparator designed for single supply operation, input common-mode range includes ground |
| LM2903 | Automotive | 1 | ±1 (2V) to ±18 (36) | 0.25 | 0.050 | 7 | 1.3μs | 200k | DIP | Dual comparator designed for single supply operation; input common-mode range includes ground |

Note 1: Dual version of device. ¹Response time is specified for 100 mV step input with 5 mV overdrive.

*Military: -55°C to +125°C; Industrial: -25°C to +85°C; Commercial: 0°C to +70°C; Automotive: -40°C to +85°C





Definition of Terms

Input Bias Current: The average of the two input currents.

Input Offset Current: The absolute value of the difference between the two input currents for which the output will be driven higher than or lower than specified voltages.

Input Offset Voltage: The absolute value of the voltage between the input terminals required to make the output voltage greater than or less than specified voltages.

Input Voltage Range: The range of voltage on the input terminals (common-mode) over which the offset specifications apply.

Logic Threshold Voltage: The voltage at the output of the comparator at which the loading logic circuitry changes its digital state.

Negative Output Level: The negative dc output voltage with the comparator saturated by a differential input equal to or greater than a specified voltage.

Output Leakage Current: The current into the output terminal with the output voltage within a given range and the input drive equal to or greater than a given value.

Output Resistance: The resistance seen looking into the output terminal with the dc output level at the logic threshold voltage.

Output Sink Current: The maximum negative current that can be delivered by the comparator.

Positive Output Level: The high output voltage level with a given load and the input drive equal to or greater than a specified value.

Power Consumption: The power required to operate the comparator with no output load. The power will vary with signal level, but is specified as a maximum for the entire range of input signal conditions.

Response Time: The interval between the application of an input step function and the time when the output crosses the logic threshold voltage. The input step drives the comparator from some initial, saturated input voltage to an input level just barely in excess of that required to bring the output from saturation to the logic threshold voltage. This excess is referred to as the voltage overdrive.

Saturation Voltage: The low-output voltage level with the input drive equal to or greater than a specified value.

Strobe Current: The current out of the strobe terminal when it is at the zero logic level.

Strobed Output Level: The dc output voltage, independent of input conditions, with the voltage on the strobe terminal equal to or less than the specified low state.

Strobe "ON" Voltage: The maximum voltage on either strobe terminal required to force the output to the specified high state independent of the input voltage.

Strobe "OFF" Voltage: The minimum voltage on the strobe terminal that will guarantee that it does not interfere with the operation of the comparator.

Strobe Release Time: The time required for the output to rise to the logic threshold voltage after the strobe terminal has been driven from zero to the one logic level.

Supply Current: The current required from the positive or negative supply to operate the comparator with no output load. The power will vary with input voltage, but is specified as a maximum for the entire range of input voltage conditions.

Voltage Gain: The ratio of the change in output voltage to the change in voltage between the input terminals producing it.

LF111/LF211/LF311 Voltage Comparators

General Description

The LF111, LF211 and LF311 are FET input voltage comparators that virtually eliminate input current errors. Designed to operate over a 5.0V to $\pm 15V$ range the LF111 can be used in the most critical applications.

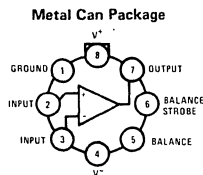
The extremely low input currents of the LF111 allows the use of a simple comparator in applications usually requiring input current buffering. Leakage testing, long time delay circuits, charge measurements, and high source impedance voltage comparisons are easily done.

Further, the LF111 can be used in place of the LM111 eliminating errors due to input currents. See the "application hints" of the LM311 for application help.

Advantages

- Eliminates input current errors
- Interchangeable with LM111
- No need for input current buffering

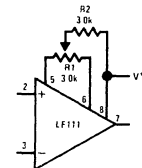
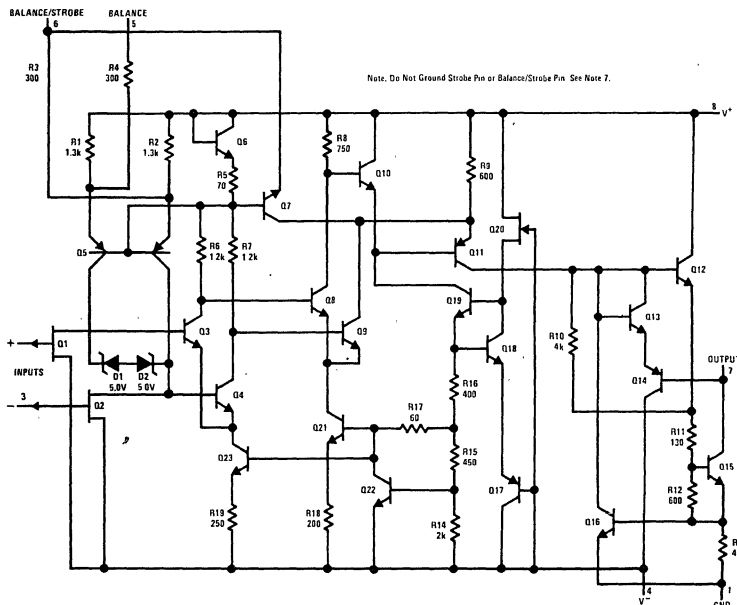
Connection Diagram*



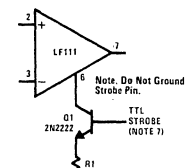
NOTE: Pin 4 connected to case
TOP VIEW

Order Number LF111H, LF211H
or LF311H
See NS Package H08C

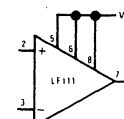
Schematic Diagram and Auxiliary Circuits



Offset Balancing



Strobing



*Increases typical common mode slew from 7.0V/ μ s to 18V/ μ s

Increasing Input Stage Current*

Absolute Maximum Ratings

| | LF111/LF211 | LF311 |
|--|-----------------|-----------------|
| Total Supply Voltage (V_{B4}) | 36V | 36V |
| Output to Negative Supply Voltage (V_{74}) | 50V | 40V |
| Ground to Negative Supply Voltage (V_{14}) | 30V | 30V |
| Differential Input Voltage | ±30V | ±30V |
| Input Voltage (Note 1) | ±15V | ±15V |
| Power Dissipation (Note 2) | 500 mW | 500 mW |
| Output Short Circuit Duration | 10 seconds | 10 seconds |
| Operating Temperature Range | | |
| LF111 | -55°C to +125°C | |
| LF211 | -25°C to +85°C | |
| LF311 | | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics (LF111/LF211) (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|--|-------|------|------|-------|
| Input Offset Voltage (Note 4) | $T_A = 25^\circ\text{C}$, R_S | | 0.7 | 4.0 | mV |
| Input Offset Current (Note 4) | $T_A = 25^\circ\text{C}$, $V_{CM} = 0$ (Note 6) | | 5.0 | 25 | pA |
| Input Bias Current | $T_A = 25^\circ\text{C}$, $V_{CM} = 0$ (Note 6) | | 20 | 50 | pA |
| Voltage Gain | $T_A = 25^\circ\text{C}$ | 40 | 200 | | V/mV |
| Response Time (Note 5) | $T_A = 25^\circ\text{C}$ | | 200 | | ns |
| Saturation Voltage | $V_{IN} \leq -5.0\text{ mV}$, $I_{OUT} = 50\text{ mA}$, $T_A = 25^\circ\text{C}$ | | 0.75 | 1.5 | V |
| Strobe On Current | $T_A = 25^\circ\text{C}$ | | 3.0 | | mA |
| Output Leakage Current | $V_{IN} \geq 5.0\text{ mV}$, $V_{OUT} = 35\text{V}$, $T_A = 25^\circ\text{C}$ | | 0.2 | 10 | nA |
| Input Offset Voltage (Note 4) | | | | 6.0 | mV |
| Input Offset Current (Note 4) | $V_S = \pm 15\text{V}$, $V_{CM} = 0$ (Note 6) | | 2.0 | 3.0 | nA |
| Input Bias Current | $V_S = \pm 15\text{V}$, $V_{CM} = 0$ (Note 6) | | 5.0 | 7.0 | nA |
| Input Voltage Range | | -13.5 | ±14 | 13.0 | V |
| Saturation Voltage | $V^+ \geq 4.5\text{V}$, $V^- = 0$ $V_{IN} \leq -6.0\text{ mV}$, $I_{SINK} \leq 8.0\text{ mA}$ | | 0.23 | 0.4 | V |
| Output Leakage Current | $V_{IN} \geq 5.0\text{ mV}$, $V_{OUT} = 35\text{V}$ | | 0.1 | 0.5 | μA |
| Positive Supply Current | $T_A = 25^\circ\text{C}$ | | 5.1 | 6.0 | mA |
| Negative Supply Current | $T_A = 25^\circ\text{C}$ | | 4.1 | 5.0 | mA |

Note 1: This rating applies for ±15V supplies. The positive input voltage limit is 30V above the negative supply. The negative input voltage limit is equal to the negative supply voltage or 30V below the positive supply, whichever is less.

Note 2: The maximum junction temperature of the LF111 is +150°C, the LF211 is +110°C and the LF311 is +85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of +150°C/W, junction to ambient, or +45°C/W, junction to case.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$, and the Ground pin at ground, and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LF111, unless otherwise stated. With the LF211, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ and for the LF311 $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5.0V supply up to ±15V supplies.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1.0 mA load. Thus, these parameters define an error band and take into account the worst case effects of voltage gain and input impedance.

Note 5: The response time specified (see definitions) is for a 100 mV input step with 5.0 mV overdrive.

Note 6: For input voltages greater than 15V above the negative supply the bias and offset currents will increase—see typical performance curves.

Note 7: Do not short the strobe pin to ground; it should be current driven at 3 to 5 mA.

Electrical Characteristics (LF311) (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|---|-----|--------------|-----|--------|
| Input Offset Voltage (Note 4) | $T_A = 25^\circ\text{C}$, $R_S \leq 50\text{k}$ | | 2.0 | 10 | mV |
| Input Offset Current (Note 4) | $T_A = 25^\circ\text{C}$, $V_{CM} = 0$ (Note 6) | | 5.0 | 75 | pA |
| Input Bias Current | $T_A = 25^\circ\text{C}$, $V_{CM} = 0$ (Note 6) | | 25 | 150 | pA |
| Voltage Gain | $T_A = 25^\circ\text{C}$ | | 200 | | V/mV |
| Response Time (Note 5) | $T_A = 25^\circ\text{C}$ | | 200 | | ns |
| Saturation Voltage | $V_{IN} \leq -10\text{ mV}$, $I_{OUT} = 50\text{ mA}$, $T_A = 25^\circ\text{C}$ | | 0.75 | 1.5 | V |
| Strobe On Current | $T_A = 25^\circ\text{C}$ | | 3.0 | | mA |
| Output Leakage Current | $V_{IN} \geq 10\text{ mV}$, $V_{OUT} = 35\text{V}$, $T_A = 25^\circ\text{C}$ | | 0.2 | 10 | nA |
| Input Offset Voltage (Note 4) | $R_S \leq 50\text{k}$ | | | 15 | mV |
| Input Offset Current (Note 4) | $V_S = \pm 15\text{V}$, $V_{CM} = 0$ (Note 6) | | 1.0 | | nA |
| Input Bias Current | $V_S = \pm 15\text{V}$, $V_{CM} = 0$ (Note 6) | | 3.0 | | nA |
| Input Voltage Range | | | +14 -13.5 | | V V |
| Saturation Voltage | $V^+ \geq 4.5\text{V}$, $V^- = 0$ $V_{IN} \leq -10\text{ mV}$, $I_{SINK} \leq 8.0\text{ mA}$ | | 0.23 | 0.4 | V |
| Positive Supply Current | $T_A = 25^\circ\text{C}$ | | 5.1 | 7.5 | mA |
| Negative Supply Current | $T_A = 25^\circ\text{C}$ | | 4.1 | 5.0 | mA |

Note 1: This rating applies for $\pm 15\text{V}$ supplies. The positive input voltage limit is 30V above the negative supply. The negative input voltage limit is equal to the negative supply voltage or 30V below the positive supply, whichever is less.

Note 2: The maximum junction temperature of the LF111 is $+150^\circ\text{C}$, the LF211 is $+110^\circ\text{C}$ and the LF311 is $+85^\circ\text{C}$. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of $+150^\circ\text{C/W}$, junction to ambient, or $+45^\circ\text{C/W}$, junction to case.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$ and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LF111, unless otherwise stated. With the LF211, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ and for the LF311 $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5.0 mV supply up to $\pm 15\text{V}$ supplies.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1.0 mA load. Thus, these parameters define an error band and take into account the worst case effects of voltage gain and input impedance.

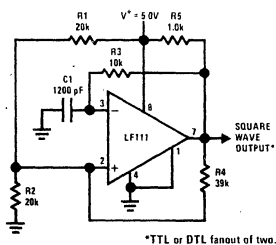
Note 5: The response time specified (see definitions) is for a 100 mV input step with 5.0 mV overdrive.

Note 6: For input voltages greater than 15V above the negative supply the bias and offset currents will increase—see typical performance curves.

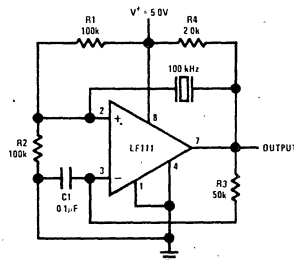
Note 7: Do not short the strobe pin to ground; it should be current driven at 3 to 5 mA.

5

Typical Applications

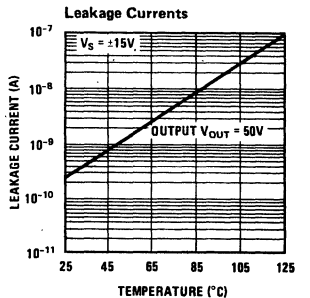
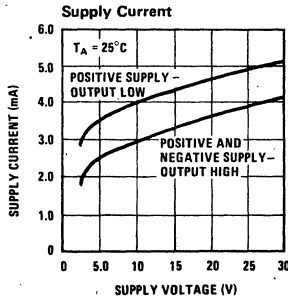
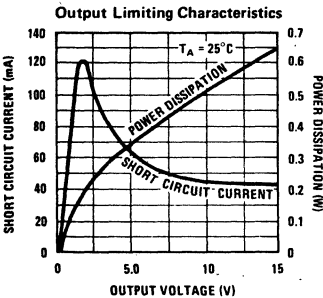
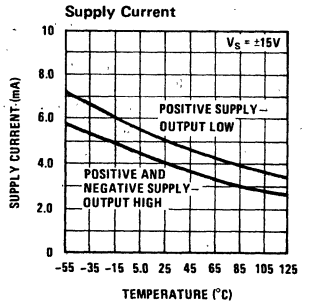
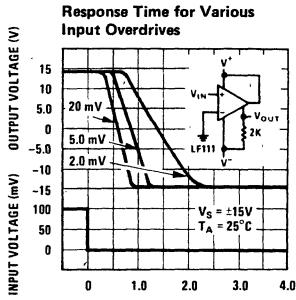
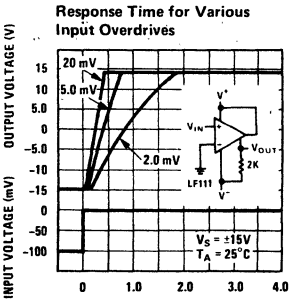
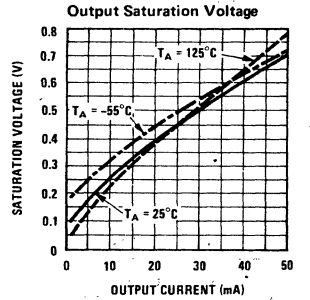
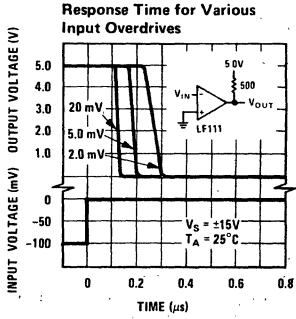
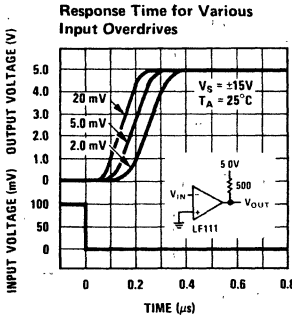
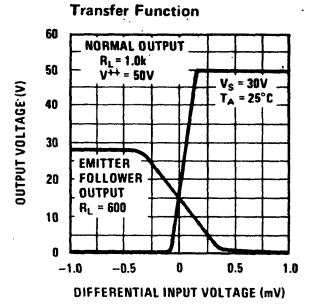
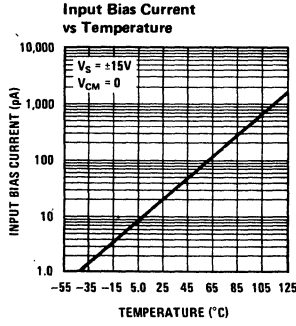
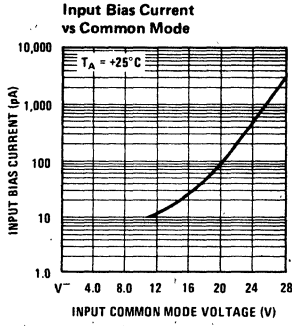


100 kHz Free Running Multivibrator



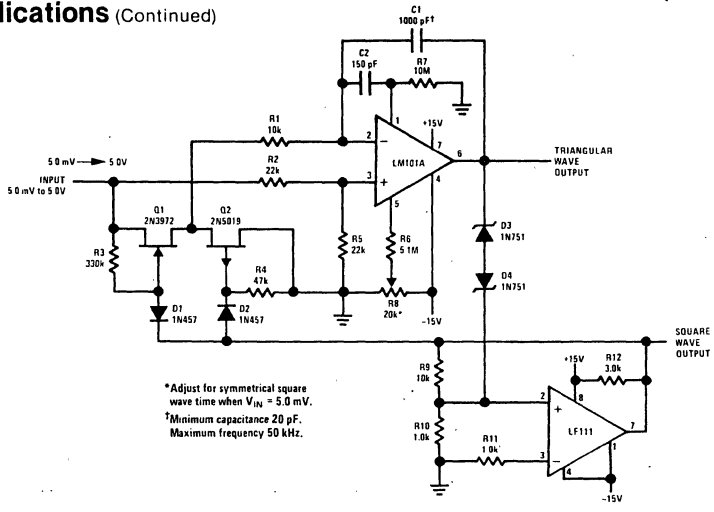
Crystal Oscillator

Typical Performance

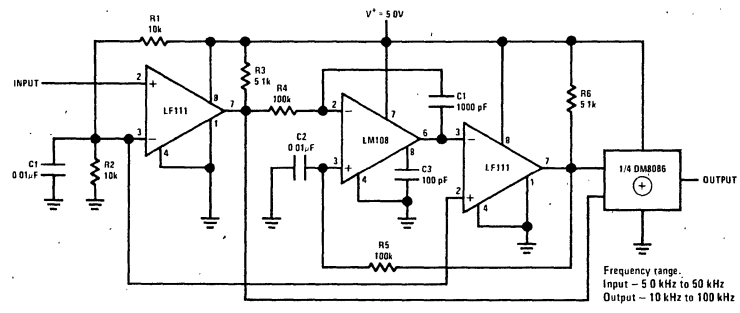


Typical Applications (Continued)

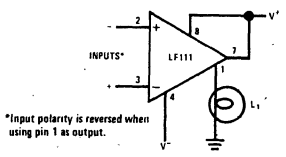
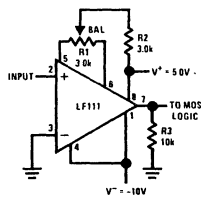
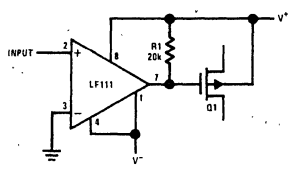
LF111/LF211/LF311



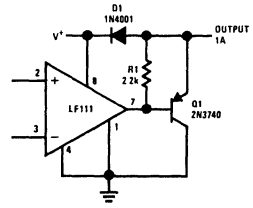
*Adjust for symmetrical square wave time when $V_{IN} = 5.0$ mV.
 †Minimum capacitance 20 pF.
 ‡Maximum frequency 50 kHz.



Frequency range:
 Input - 50 kHz to 50 kHz
 Output - 10 kHz to 100 kHz

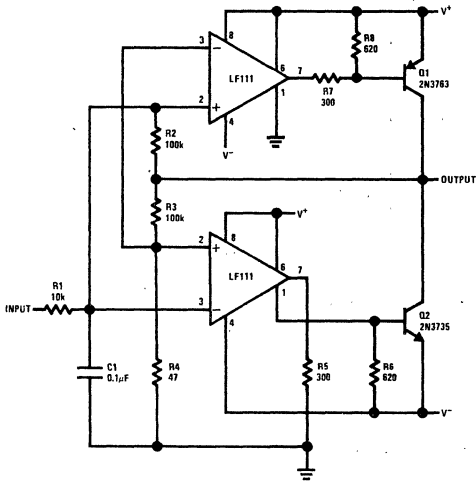


*Input polarity is reversed when using pin 1 as output.

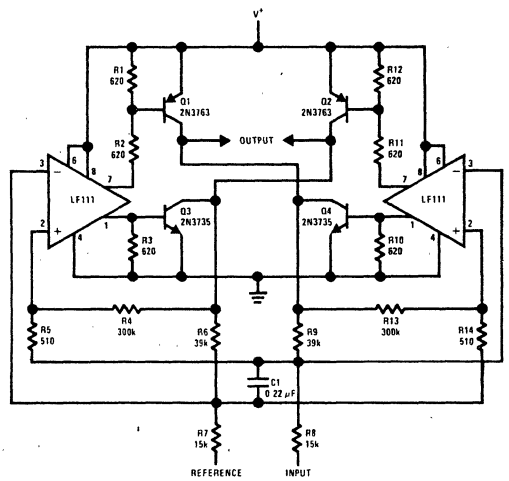


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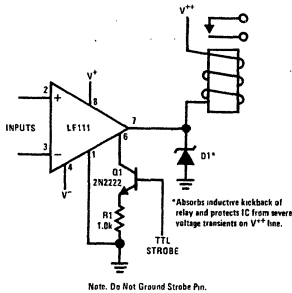
Typical Applications (Continued)



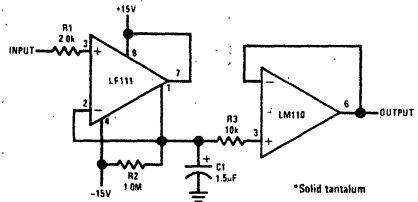
Switching Power Amplifier



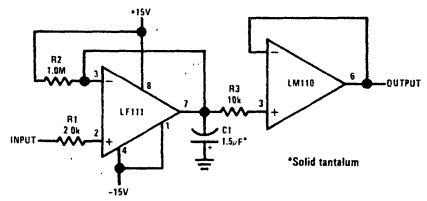
Switching Power Amplifier



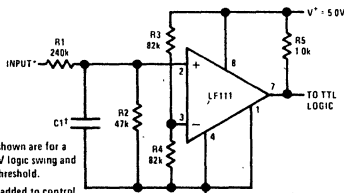
Relay Driver with Strobe



Positive Peak Detector

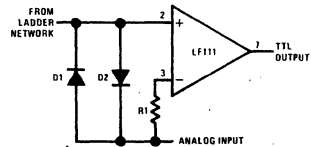


Negative Peak Detector



TTL Interface with High Level Logic

*Values shown are for a 0 to 30V logic swing and a 15V threshold.
†May be added to control speed and reduce susceptibility to noise spikes.



Using Clamp Diodes to Improve Response

LH2111/LH2211/LH2311 Dual Voltage Comparator

general description

The LH2111 series of dual voltage comparators are two LM111 type comparators in a single hermetic package. Featuring all the same performance characteristics of the single, these duals offer in addition closer thermal tracking, lower weight, reduced insertion cost and smaller size than two singles. For additional information see the LM111 data sheet and National's Linear Application Handbook.

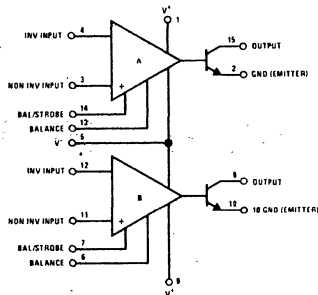
The LH2111 is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LH2211 is specified for operation over the -25°C to $+85^{\circ}\text{C}$ temperature range. The LH2311 is speci-

fied for operation over the 0°C to 70°C temperature range.

features

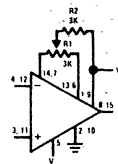
- Wide operating supply range $\pm 15\text{V}$ to a single $+5\text{V}$
- Low input currents 6 nA
- High sensitivity $10\ \mu\text{V}$
- Wide differential input range $\pm 30\text{V}$
- High output drive $50\text{ mA}, 50\text{V}$

connection diagram

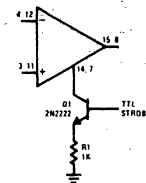


Order Number LH2111D or
or LH2211D or LH2311D
See Package D16C

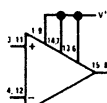
auxiliary circuits



Offset Balancing

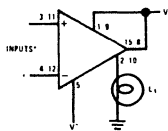


Strobing

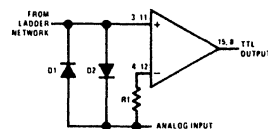


*Increases typical common mode
slew from $7.0\text{V}/\mu\text{s}$ to $18\text{V}/\mu\text{s}$.

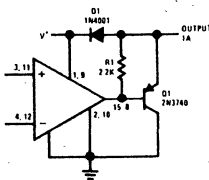
Increasing Input Stage Current*



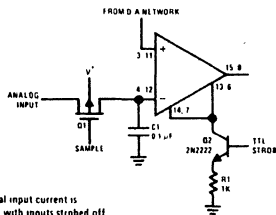
Driving Ground-Referred Load



Using Clamp Diodes to Improve Responses

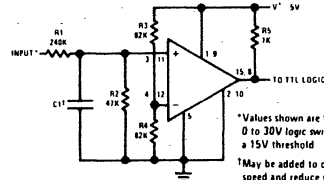


Comparator and Solenoid Driver



*Typical input current is
 50 pA with inputs strobed off

Strobing off Both Input*
and Output Stages



*Values shown are for a
 0 to 30V logic swing and
a 15V threshold

†May be added to control
speed and reduce susceptibility
to noise spikes

TTL Interface with High Level Logic

absolute maximum ratings

| | | | |
|---|--------|--------------------------------------|-----------------------|
| Total Supply Voltage ($V^+ - V^-$) | 36V | Output Short Circuit Duration | 10 sec |
| Output to Negative Supply Voltage ($V_{OUT} - V^-$) | 50V | Operating Temperature Range | LH2111 -55°C to 125°C |
| Ground to Negative Supply Voltage (GND - V^-) | 30V | | LH2211 -25°C to 85°C |
| Differential Input Voltage | ±30V | | LH2311 0°C to 70°C |
| Input Voltage (Note 1) | ±15V | Storage Temperature Range | -65°C to 150°C |
| Power Dissipation (Note 2) | 500 mW | Lead Temperature (Soldering, 10 sec) | 300°C |

electrical characteristics — each side (Note 3)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|-------------------------------|---|--------|--------|--------|----------|
| | | LH2111 | LH2211 | LH2311 | |
| Input Offset Voltage (Note 4) | $T_A = 25^\circ\text{C}, R_S \leq 50\text{k}$ | 3.0 | 3.0 | 7.5 | mV Max |
| Input Offset Current (Note 4) | $T_A = 25^\circ\text{C}$ | 10 | 10 | 50 | nA Max |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | 100 | 100 | 250 | nA Max |
| Voltage Gain | $T_A = 25^\circ\text{C}$ | 200 | 200 | 200 | V/mV Typ |
| Response Time (Note 5) | $T_A = 25^\circ\text{C}$ | 200 | 200 | 200 | ns Typ |
| Saturation Voltage | $V_{IN} \leq -5\text{ mV}, I_{OUT} = 50\text{ mA}$ $T_A = 25^\circ\text{C}$ | 1.5 | 1.5 | 1.5 | V Max |
| Strobe On Current | $T_A = 25^\circ\text{C}$ | 3.0 | 3.0 | 3.0 | mA Typ |
| Output Leakage Current | $V_{IN} \geq 5\text{ mV}, V_{OUT} = 35\text{V}$ $T_A = 25^\circ\text{C}$ | 10 | 10 | 50 | nA Max |
| Input Offset Voltage (Note 4) | $R_S \leq 50\text{k}$ | 4.0 | 4.0 | 10 | mV Max |
| Input Offset Current (Note 4) | | 20 | 20 | 70 | nA Max |
| Input Bias Current | | 150 | 150 | 300 | nA Max |
| Input Voltage Range | | ±14 | ±14 | ±14 | V Typ |
| Saturation Voltage | $V^+ \geq 4.5\text{V}, V^- = 0$ $V_{IN} \leq -5\text{ mV}, I_{SINK} < 8\text{ mA}$ | 0.4 | 0.4 | 0.4 | V Max |
| Positive Supply Current | $T_A = 25^\circ\text{C}$ | 6.0 | 6.0 | 7.5 | mA Max |
| Negative Supply Current | $T_A = 25^\circ\text{C}$ | 5.0 | 5.0 | 5.0 | mA Max |

Note 1: This rating applies for ±15V supplies. The positive input voltage limit is 30V above the negative supply. The negative input voltage limit is equal to the negative supply voltage or 30V below the positive supply, whichever is less.

Note 2: The maximum junction temperature is 150°C. For operating at elevated temperatures, devices in the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with 0.03-inch-wide, 2 ounce copper conductor. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$ and $-55^\circ\text{C} < T_A < 125^\circ\text{C}$ for the LH2111, $-25^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ for the LH2211, and $0^\circ\text{C} < T_A < 70^\circ\text{C}$ for the LH2311, unless otherwise stated. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5V supply up to ±15V supplies. For the LH2311, $V_{IN} = \pm 10\text{ mV}$.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1 mA load. Thus, these parameters define an error band and take into account the worst case effects of voltage gain and input impedance.

Note 5: The response time specified is for a 100 mV input step with 5 mV overdrive.

LM106/LM206/LM306 Voltage Comparator

General Description

The LM106 series are high-speed voltage comparators designed to accurately detect low-level analog signals and drive a digital load. They are equivalent to an LM710, combined with a two input NAND gate and an output buffer. The circuits can drive RTL, DTL or TTL integrated circuits directly. Furthermore, their outputs can switch voltages up to 24V at currents as high as 100 mA.

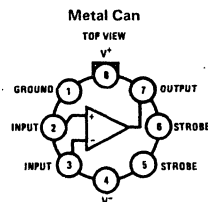
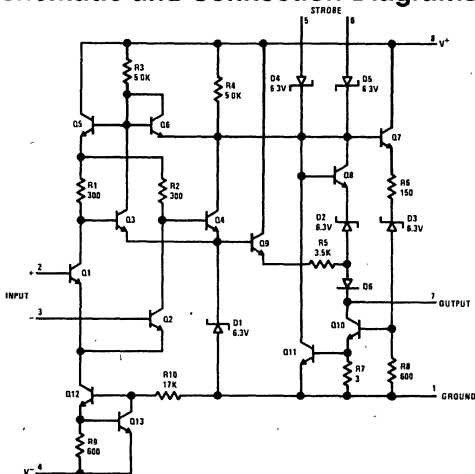
Features

- Improved accuracy
- Fan-out of 10 with DTL or TTL
- Added logic or strobe capability
- Useful as a relay or lamp driver
- Plug-in replacement for the LM710
- 40 ns maximum response time

The devices have short-circuit protection which limits the inrush current when it is used to drive incandescent lamps, in addition to preventing damage from accidental shorts to the positive supply. The speed is equivalent to that of an LM710. However, they are even faster where buffers and additional logic circuitry can be eliminated by the increased flexibility of the LM106 series. They can also be operated from any negative supply voltage between -3V and -12V with little effect on performance.

The LM106 is specified for operation over the -55°C to +125°C military temperature range. The LM206 is specified for operation over the -25°C to +85°C temperature range. The LM306 is specified for operation over 0°C to +70°C temperature range.

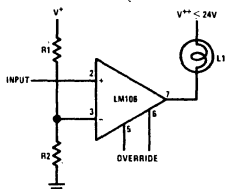
Schematic and Connection Diagrams **



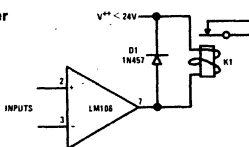
Order Number LM106H, LM206H or LM306H
See NS Package H08C

Typical Applications **

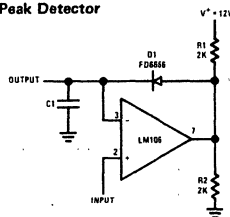
Level Detector and Lamp Driver



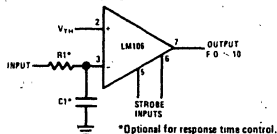
Relay Driver



Fast Response Peak Detector



Adjustable Threshold Line Receiver



Absolute Maximum Ratings

| | | | |
|-----------------------------------|------|--|---------------------|
| Positive Supply Voltage | 15V | Power Dissipation (Note 1) | 600 mW |
| Negative Supply Voltage | -15V | Output Short Circuit Duration | 10 seconds |
| Output Voltage | 24V | Operating Temperature Range | T_{MIN} T_{MAX} |
| Output to Negative Supply Voltage | 30V | LM106 | -55°C to +125°C |
| Differential Input Voltage | ±5V | LM206 | -25°C to +85°C |
| Input Voltage | ±7V | LM306 | 0°C to +70°C |
| | | Storage Temperature Range | -65°C to +150°C |
| | | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LM106/LM206 | | | LM306 | | | UNITS |
|------------------------|--|-------------|------|-----|-------|------|-----|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | (Note 3) | | 0.5 | 2.0 | | 1.6 | 5.0 | mV |
| Input Offset Current | (Note 3) | | 0.7 | 3.0 | | 1.8 | 5.0 | μA |
| Input Bias Current | | | 10 | 20 | | 16 | 25 | μA |
| Response Time | $R_L = 390\Omega$ to 5V $C_L = 15$ pF, (Note 4) | | 28 | 40 | | 28 | 40 | ns |
| Saturation Voltage | $V_{IN} \leq -5$ mV, $I_{OUT} = 100$ mA | | 1.0 | 1.5 | | | | V |
| | $V_{IN} \leq -7$ mV, $I_{OUT} = 100$ mA | | | | | 0.8 | 2.0 | V |
| Output Leakage Current | $V_{IN} \geq 5$ mV, $8V \leq V_{OUT} \leq 24V$ | | 0.02 | 1.0 | | | | μA |
| | $V_{IN} \geq 7$ mV, $8V \leq V_{OUT} \leq 24V$ | | | | | 0.02 | 2.0 | μA |

The following specifications apply for $T_{MIN} \leq T_A \leq T_{MAX}$ (Note 5)

| | | | | | | | | |
|---|---|------|------|-----|------|------|-----|-------|
| Input Offset Voltage | (Note 3) | | | 3.0 | | 6.5 | | mV |
| Average Temperature Coefficient of Input Offset Voltage | | | 3.0 | 10 | | 5 | 20 | μV/°C |
| Input Offset Current | $T_L \leq T_A \leq 25^\circ\text{C}$, (Note 3) | | 1.8 | 7.0 | | 2.4 | 7.5 | μA |
| | $25^\circ\text{C} \leq T_A \leq T_H$ | | 0.25 | 3.0 | | | 5.0 | μA |
| Average Temperature Coefficient of Input Offset Current | $25^\circ\text{C} \leq T_A \leq T_H$ | | 5.0 | 25 | | 15 | 50 | nA/°C |
| | $T_L \leq T_A \leq 25^\circ\text{C}$ | | 15 | 75 | | 24 | 100 | nA/°C |
| Input Bias Current | $T_L \leq T_A \leq 25^\circ\text{C}$ | | | 45 | | 25 | 40 | μA |
| | $25^\circ\text{C} \leq T_A \leq T_H$ | | | 20 | | | 25 | μA |
| Input Voltage Range | $-7V \leq V^- \leq -12V$ | ±5.0 | | | | ±5.0 | | V |
| Differential Input Voltage Range | | ±5.0 | | | | ±5.0 | | V |
| Saturation Voltage | $V_{IN} \leq -5$ mV, $I_{OUT} = 50$ mA | | | 1.0 | | | 1.0 | V |
| | $V_{IN} \leq -8$ mV For LM306 | | | | | | | |
| Saturation Voltage | $V_{IN} \leq -5$ mV, $I_{OUT} = 16$ mA | | | 0.4 | | | 0.4 | V |
| | $V_{IN} \leq -8$ mV For LM306 | | | | | | | |
| Positive Output Level | $V_{IN} \geq 5$ mV, $I_{OUT} = -400\mu\text{A}$ | 2.5 | | 5.5 | 2.5 | | 5.5 | V |
| | $V_{IN} \geq 8$ mV For LM306 | | | | | | | |
| Output Leakage Current | $V_{IN} \geq 5$ mV, $8V \leq V_{OUT} \leq 24V$ | | | 1.0 | | | 2.0 | μA |
| | $V_{IN} \geq 8$ mV For LM306 | | | | | | | |
| | $T_L \leq T_A \leq 25^\circ\text{C}$ | | | | | | | |
| | $25^\circ\text{C} < T_A \leq T_H$ | | | 100 | | | 100 | μA |
| Strobe Current | $V_{STROBE} = 0.4V$ | -1.7 | -3.2 | | -1.7 | -3.2 | | mA |
| Strobe "ON" Voltage | | 0.9 | 1.4 | | 0.9 | 1.4 | | V |
| Strobe "OFF" Voltage | $I_{SINK} \leq 16$ mA | | 1.4 | 2.2 | | 1.4 | 2.2 | V |
| Positive Supply Current | $V_{IN} = -5$ mV | | 5.5 | 10 | | 5.5 | 10 | mA |
| | $V_{IN} = -8$ mV For LM306 | | | | | | | |
| Negative Supply Current | | -1.5 | -3.6 | | -1.5 | -3.6 | | mA |

Note 1: The maximum junction temperature of LM106 is 150°C, LM206 is 110°C, LM306 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. For the flat package, the derating is based on a thermal resistance of 185°C/W when mounted on a 1/16-inch-thick epoxy glass board with ten, 0.03-inch-wide, 2-ounce copper conductors.

Note 2: These specifications apply for $-3V \geq V^- \geq -12V$, $V^+ = 12V$ and $T_A = 25^\circ\text{C}$ unless otherwise specified. All currents into device pins are considered positive.

Note 3: The offset voltages and offset currents given are the maximum values required to drive the output down to 0.5V or up to 4.4V (0.5V or up to 4.8V for the LM306). Thus, these parameters actually define an error band and take into account the worst-case effects of voltage gain, specified supply voltage variations, and common mode voltage variations.

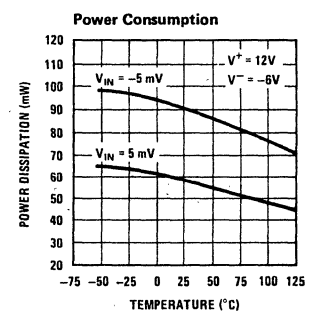
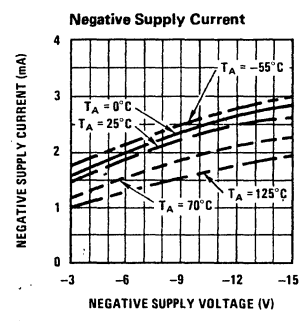
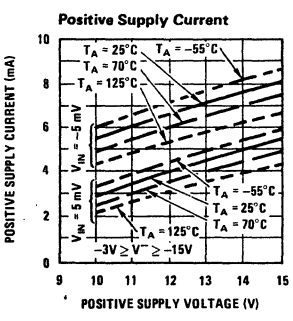
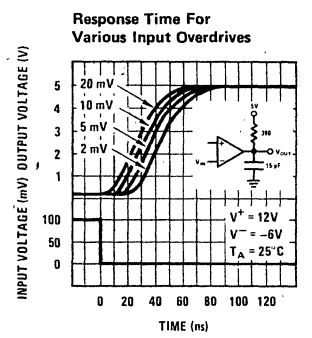
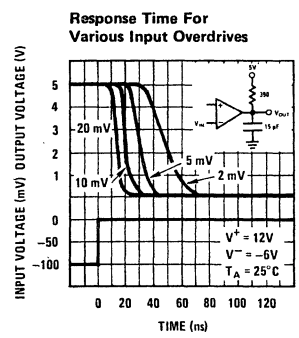
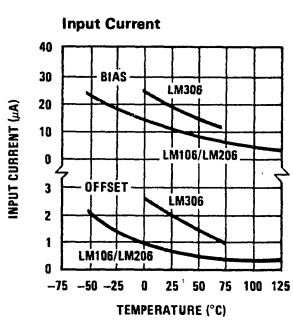
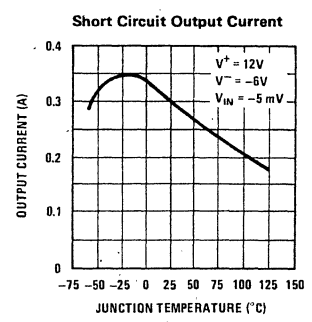
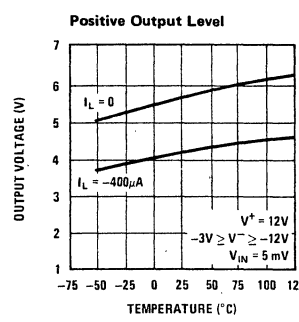
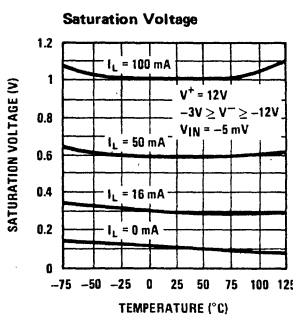
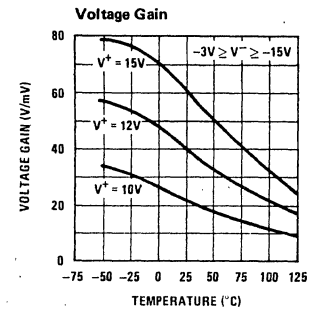
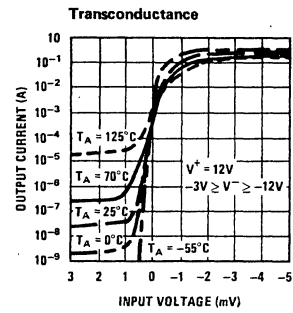
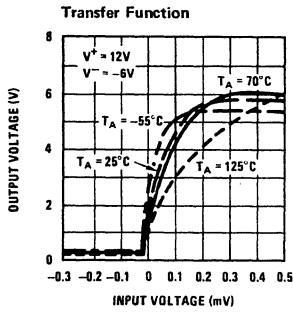
Note 4: The response time specified (see definitions) is for a 100 mV input step with 5 mV overdrive.

Note 5: All currents into device pins are considered positive.

Typical Performance Characteristics

LM106/LM206/LM306

5



National Semiconductor

LM111/LM211 Voltage Comparator[†]

Voltage Comparators

General Description

The LM111 and LM211 are voltage comparators that have input currents nearly a thousand times lower than devices like the LM106 or LM710. They are also designed to operate over a wider range of supply voltages: from standard $\pm 15V$ op amp supplies down to the single 5V supply used for IC logic. Their output is compatible with RTL, DTL and TTL as well as MOS circuits. Further, they can drive lamps or relays, switching voltages up to 50V at currents as high as 50 mA. Outstanding characteristics include:

- Operates from single 5V supply
- Input current: 150 nA max. over temperature
- Offset current: 20 nA max. over temperature

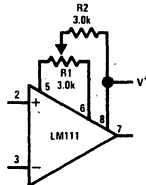
- Differential input voltage range: $\pm 30V$
- Power consumption: 135 mW at $\pm 15V$

Both the inputs and the outputs of the LM111 or the LM211 can be isolated from system ground, and the output can drive loads referred to ground, the positive supply or the negative supply. Offset balancing and strobe capability are provided and outputs can be wire OR'ed. Although slower than the LM106 and LM710 (200 ns response time vs 40 ns) the devices are also much less prone to spurious oscillations. The LM111 has the same pin configuration as the LM106 and LM710.

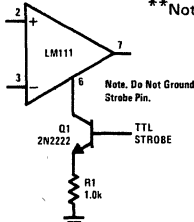
The LM211 is identical to the LM111, except that its performance is specified over a $-25^{\circ}C$ to $85^{\circ}C$ temperature range instead of $-55^{\circ}C$ to $125^{\circ}C$.

[†]See application hints LM311

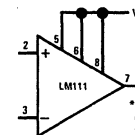
Auxiliary Circuits**



Offset Balancing



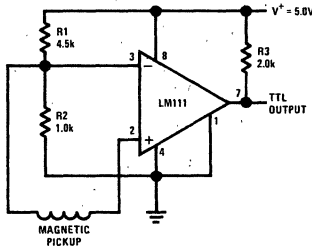
Strobing



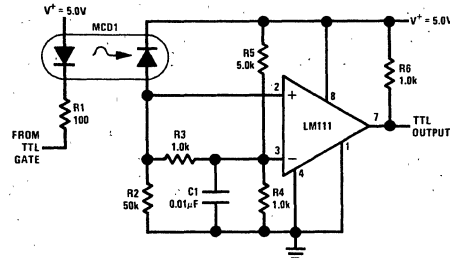
Increasing Input Stage Current*

** Note: Pin connections shown on schematic diagram and typical applications are for TO-5 package.

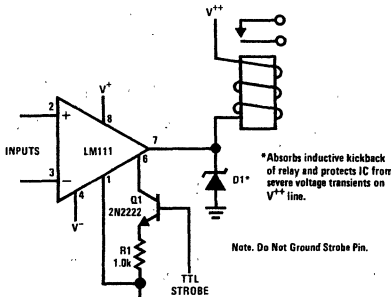
Typical Applications**



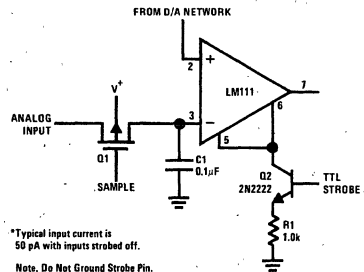
Detector for Magnetic Transducer



Digital Transmission Isolator



Relay Driver with Strobe*



Strobing off Both Input* and Output Stages

*Typical input current is 50 μA with inputs strobed off.
Note: Do Not Ground Strobe Pin.

*Absorbs inductive kickback of relay and protects IC from severe voltage transients on V^{+} line.
Note: Do Not Ground Strobe Pin.

Absolute Maximum Ratings

| | |
|--|--|
| Total Supply Voltage (V_{84}) | 36V |
| Output to Negative Supply Voltage (V_{74}) | 50V |
| Ground to Negative Supply Voltage (V_{14}) | 30V |
| Differential Input Voltage | $\pm 30V$ |
| Input Voltage (Note 1) | $\pm 15V$ |
| Power Dissipation (Note 2) | 500 mW |
| Output Short Circuit Duration | 10 sec |
| Operating Temperature Range LM111 | -55°C to 125°C |
| LM211 | -25°C to 85°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (soldering, 10 sec) | 300°C |
| Voltage at Strobe Pin | $V^+ - 5V$ |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|--|-------|------------|------|---------------|
| Input Offset Voltage (Note 4) | $T_A = 25^{\circ}\text{C}$, $R_S \leq 50k$ | | 0.7 | 3.0 | mV |
| Input Offset Current (Note 4) | $T_A = 25^{\circ}\text{C}$ | | 4.0 | 10 | nA |
| Input Bias Current | $T_A = 25^{\circ}\text{C}$ | | 60 | 100 | nA |
| Voltage Gain | $T_A = 25^{\circ}\text{C}$ | 40 | 200 | | V/mV |
| Response Time (Note 5) | $T_A = 25^{\circ}\text{C}$ | | 200 | | ns |
| Saturation Voltage | $V_{IN} \leq -5\text{ mV}$, $I_{OUT} = 50\text{ mA}$ $T_A = 25^{\circ}\text{C}$ | | 0.75 | 1.5 | V |
| Strobe ON Current (Note 6) | $T_A = 25^{\circ}\text{C}$ | | 3.0 | | mA |
| Output Leakage Current | $V_{IN} \geq 5\text{ mV}$, $V_{OUT} = 35V$ $T_A = 25^{\circ}\text{C}$, $I_{STROBE} = 3\text{ mA}$ | | 0.2 | 10 | nA |
| Input Offset Voltage (Note 4) | $R_S \leq 50k$ | | | 4.0 | mV |
| Input Offset Current (Note 4) | | | | 20 | nA |
| Input Bias Current | | | | 150 | nA |
| Input Voltage Range | $V^+ = 15V$, $V^- = -15V$, Pin 7 Pull-Up May Go To 5V | -14.5 | 13.8,-14.7 | 13.0 | V |
| Saturation Voltage | $V^+ \geq 4.5V$, $V^- = 0$ $V_{IN} \leq -6\text{ mV}$, $I_{SINK} \leq 8\text{ mA}$ | | 0.23 | 0.4 | V |
| Output Leakage Current | $V_{IN} \geq 5\text{ mV}$, $V_{OUT} = 35V$ | | 0.1 | 0.5 | μA |
| Positive Supply Current | $T_A = 25^{\circ}\text{C}$ | | 5.1 | 6.0 | mA |
| Negative Supply Current | $T_A = 25^{\circ}\text{C}$ | | 4.1 | 5.0 | mA |

Note 1: This rating applies for $\pm 15V$ supplies. The positive input voltage limit is 30V above the negative supply. The negative input voltage limit is equal to the negative supply voltage or 30V below the positive supply, whichever is less.

Note 2: The maximum junction temperature of the LM111 is 150°C , while that of the LM211 is 110°C . For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of $150^{\circ}\text{C}/\text{W}$, junction to ambient, or $45^{\circ}\text{C}/\text{W}$, junction to case. The thermal resistance of the dual-in-line package is $100^{\circ}\text{C}/\text{W}$, junction to ambient.

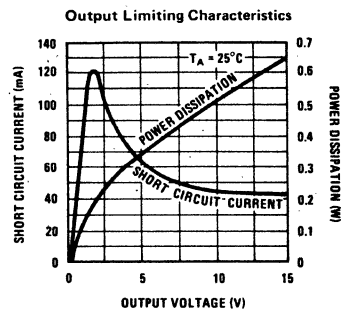
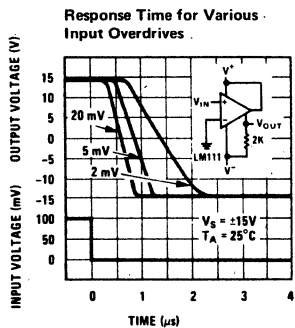
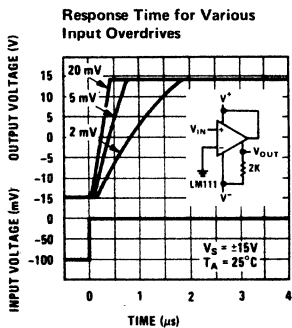
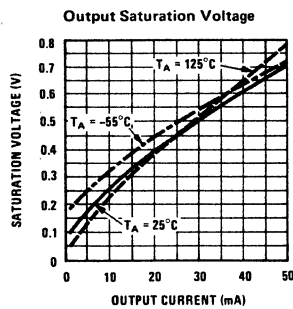
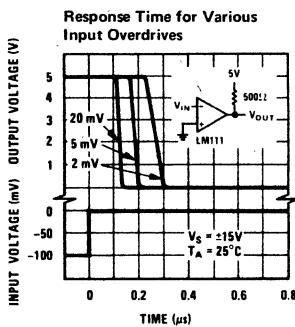
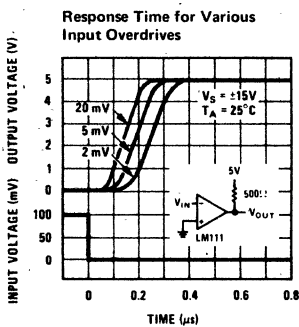
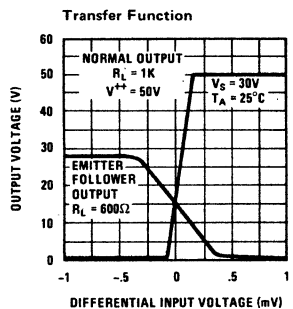
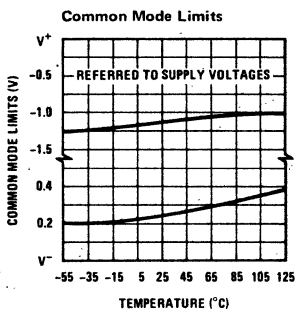
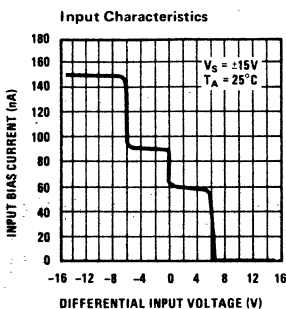
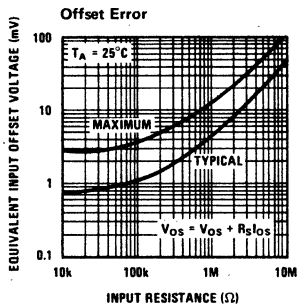
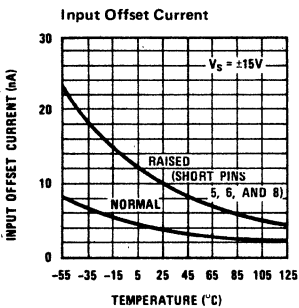
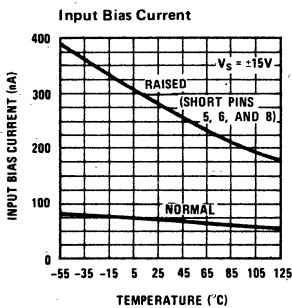
Note 3: These specifications apply for $V_S = \pm 15V$ and Ground pin at ground, and $-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$, unless otherwise stated. With the LM211, however, all temperature specifications are limited to $-25^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5V supply up to $\pm 15V$ supplies.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1 mA load. Thus, these parameters define an error band and take into account the worst-case effects of voltage gain and input impedance.

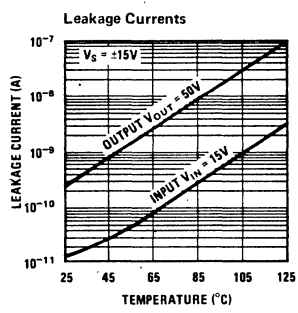
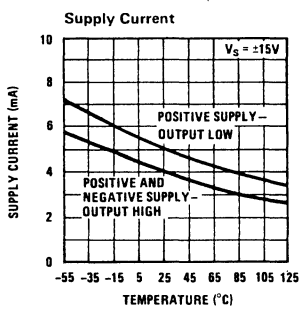
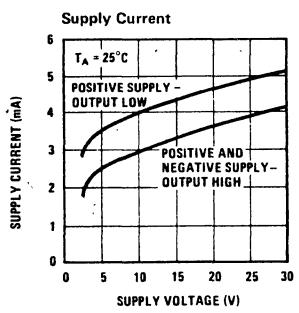
Note 5: The response time specified (see definitions) is for a 100 mV input step with 5 mV overdrive.

Note 6: Do not short the strobe pin to ground; it should be current driven at 3 to 5 mA.

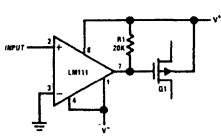
Typical Performance Characteristics



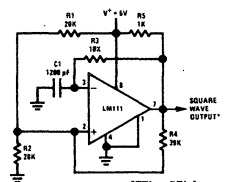
Typical Performance Characteristics (Continued)



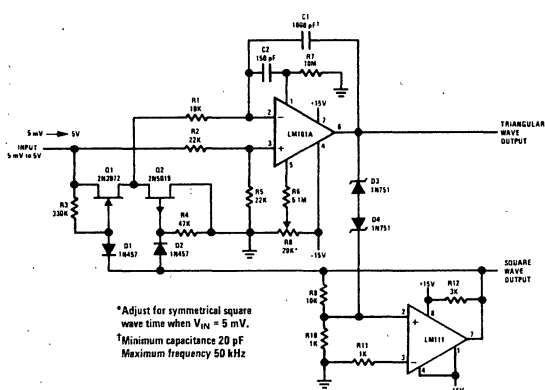
Typical Applications (Continued)



Zero Crossing Detector Driving MOS Switch

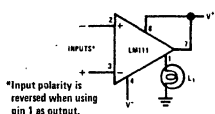


100 kHz Free Running Multivibrator

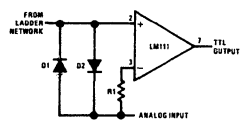


*Adjust for symmetrical square wave time when $V_{IN} = 5\text{ mV}$.
 *Minimum capacitance 20 pF
 *Maximum frequency 50 kHz

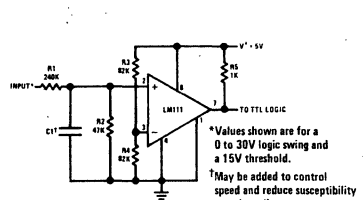
10 Hz to 10 kHz Voltage Controlled Oscillator



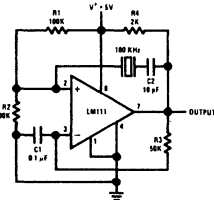
Driving Ground-Referenced Load



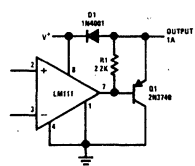
Using Clamp Diodes to Improve Response



TTL Interface with High Level Logic

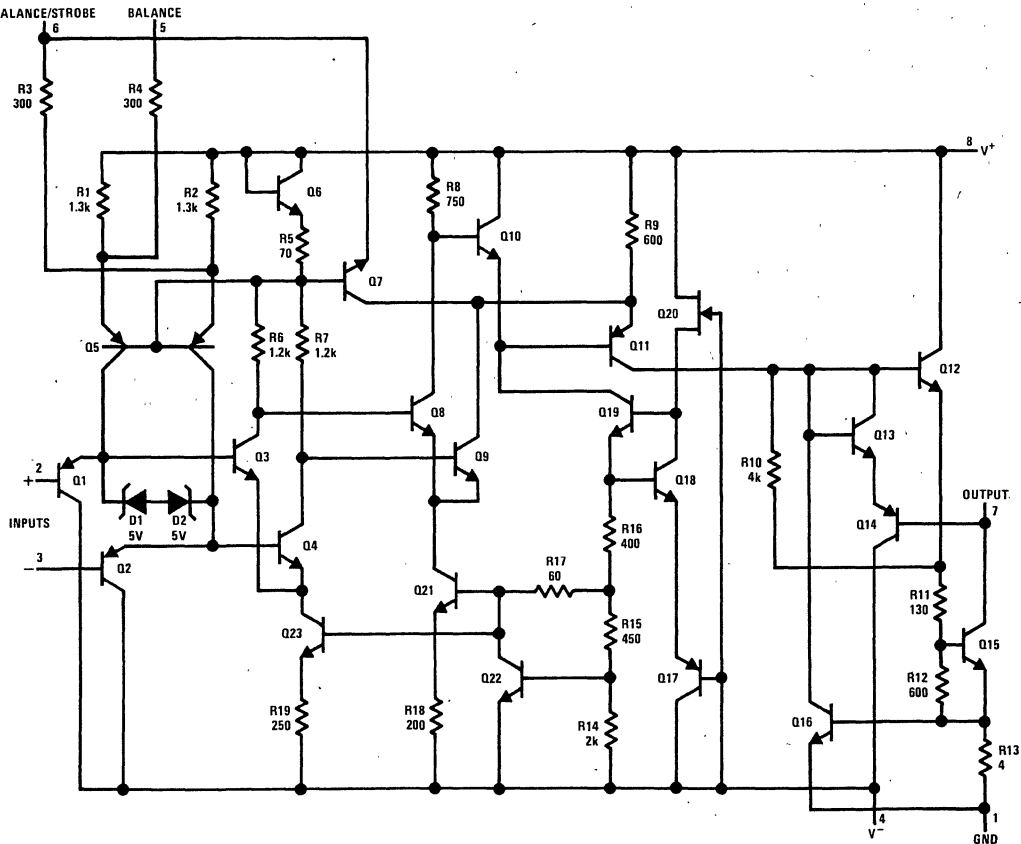


Crystal Oscillator



Comparator and Solenoid Driver

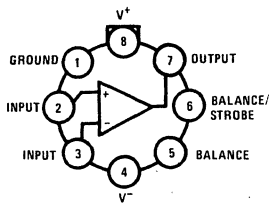
Schematic Diagram



5

Connection Diagrams *

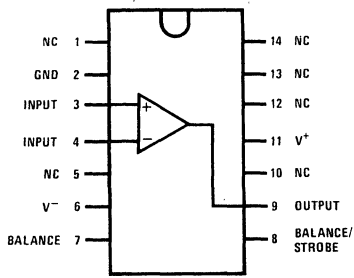
Metal Can Package



NOTE: Pin 4 connected to case.
TOP VIEW

Order Number LM111H or LM211H
See NS Package H08C

Dual-In-Line Package



Note: Pin 6 connected to bottom of package.

TOP VIEW

Order Number LM111J or LM211J
See NS Package J14A

*Pin connections shown are for metal can.



Voltage Comparators

LM119/LM219/LM319 High Speed Dual Comparator

General Description

The LM119 series are precision high speed dual comparators fabricated on a single monolithic chip. They are designed to operate over a wide range of supply voltages down to a single 5V logic supply and ground. Further, they have higher gain and lower input currents than devices like the LM710. The uncommitted collector of the output stage makes the LM119 compatible with RTL, DTL and TTL as well as capable of driving lamps and relays at currents up to 25 mA. Outstanding features include:

- Maximum input current of 1 μ A over temperature
- Inputs and outputs can be isolated from system ground
- High common mode slew rate

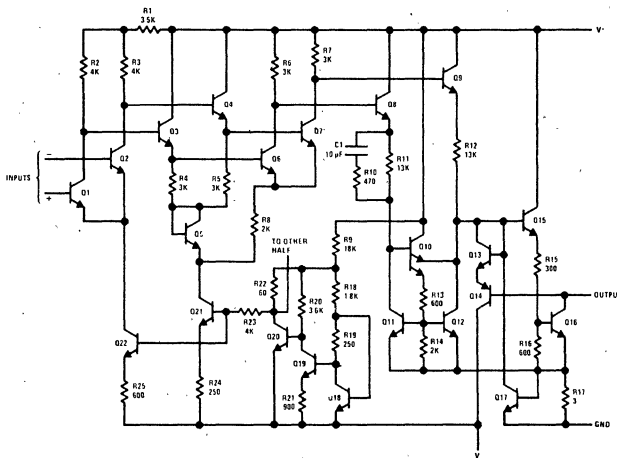
Although designed primarily for applications requiring operation from digital logic supplies, the LM119 series are fully specified for power supplies up to ± 15 V. It features faster response than the LM111 at the expense of higher power dissipation. However, the high speed, wide operating voltage range and low package count make the LM119 much more versatile than older devices like the LM711.

The LM119 is specified from -55°C to $+125^{\circ}\text{C}$, the LM219 is specified from -25°C to $+85^{\circ}\text{C}$, and the LM319 is specified from 0°C to $+70^{\circ}\text{C}$.

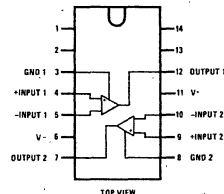
Features

- Two independent comparators
- Operates from a single 5V supply
- Typically 80 ns response time at ± 15 V
- Minimum fan-out of 2 each side

Schematic and Connection Diagrams



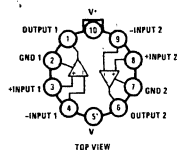
Dual-In-Line-Package



Order Number LM319N
See NS Package N14A

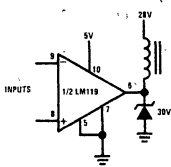
Order Number LM119J, LM219J
or LM319J
See NS Package J14A

Metal Can Package

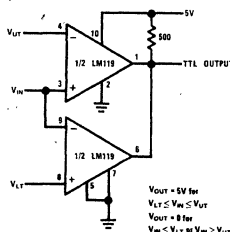


Order Number LM119H, LM219H
or LM319H
See NS Package H10C

Typical Applications



Relay Driver



Window Detector

$V_{OUT} = 5V$ for
 $V_{IN} \leq V_{IN} \leq V_{UT}$
 $V_{OUT} = 0$ for
 $V_{IN} \leq V_{LT} \text{ or } V_{IN} \geq V_{UT}$

Absolute Maximum Ratings LM119/LM219

| | | | |
|-----------------------------------|------|--------------------------------------|----------------|
| Total Supply Voltage | 36V | Power Dissipation (Note 2) | 500 mW |
| Output to Negative Supply Voltage | 36V | Output Short Circuit Duration | 10 sec |
| Ground to Negative Supply Voltage | 25V | Operating Temperature Range LM119 | -55°C to 125°C |
| Ground to Positive Supply Voltage | 18V | LM219 | -25°C to 85°C |
| Differential Input Voltage | ±5V | Storage Temperature Range | -65°C to 150°C |
| Input Voltage (Note 1) | ±15V | Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|--|-----|------|------------|---------------|
| Input Offset Voltage (Note 4) | $T_A = 25^\circ\text{C}$, $R_S \leq 5k$ | | 0.7 | 4.0 | mV |
| Input Offset Current (Note 4) | $T_A = 25^\circ\text{C}$ | | 30 | 75 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 150 | 500 | nA |
| Voltage Gain | $T_A = 25^\circ\text{C}$ | 10 | 40 | | V/mV |
| Response Time (Note 5) | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 80 | | ns |
| Saturation Voltage | $V_{IN} \leq -5\text{ mV}$, $I_{OUT} = 25\text{ mA}$ $T_A = 25^\circ\text{C}$ | | 0.75 | 1.5 | V |
| Output Leakage Current | $V_{IN} \geq 5\text{ mV}$, $V_{OUT} = 35\text{V}$ $T_A = 25^\circ\text{C}$ | | 0.2 | 2 | μA |
| Input Offset Voltage (Note 4) | $R_S \leq 5k$ | | | 7 | mV |
| Input Offset Current (Note 4) | | | | 100 | nA |
| Input Bias Current | | | | 1000 | nA |
| Input Voltage Range | $V_S = \pm 15\text{V}$ $V^+ = 5\text{V}$, $V^- = 0$ | 1 | ±13 | 3 | V |
| Saturation Voltage | $V^+ \geq 4.5\text{V}$, $V^- = 0$ $V_{IN} \leq -6\text{ mV}$, $I_{SINK} \leq 3.2\text{ mA}$ $T_A \geq 0^\circ\text{C}$ $T_A \leq 0^\circ\text{C}$ | | 0.23 | 0.4 0.6 | V V |
| Output Leakage Current | $V_{IN} \geq 5\text{ mV}$, $V_{OUT} = 35\text{V}$ | | 1 | 10 | μA |
| Differential Input Voltage | | | | ±5 | V |
| Positive Supply Current | $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = 0$ | | 4.3 | | mA |
| Positive Supply Current | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 8 | 11.5 | mA |
| Negative Supply Current | $T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{V}$ | | 3 | 4.5 | mA |

Note 1: For supply voltages less than $\pm 15\text{V}$ the absolute maximum input voltage is equal to the supply voltage.

Note 2: The maximum junction temperature of the LM119 is 150°C , while that of the LM219 is 110°C . For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W , junction to ambient, or 45°C/W , junction to case. The thermal resistance of the dual-in-line package is 100°C/W , junction to ambient.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$, and the Ground pin at ground, and $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$, unless otherwise stated. With the LM219, however, all temperature specifications are limited to $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5V supply up to $\pm 15\text{V}$ supplies.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1 mA load. Thus, these parameters define an error band and take into account the worst case effects of voltage gain and input impedance.

Note 5: The response time specified (see definitions) is for a 100 mV input step with 5 mV overdrive.

Absolute Maximum Ratings LM319

| | | | |
|-----------------------------------|------|--------------------------------------|----------------|
| Total Supply Voltage | 36V | Power Dissipation (Note 2) | 500 mW |
| Output to Negative Supply Voltage | 36V | Output Short Circuit Duration | 10 sec |
| Ground to Negative Supply Voltage | 25V | Operating Temperature Range LM319 | 0°C to 70°C |
| Ground to Positive Supply Voltage | 18V | Storage Temperature Range | -65°C to 150°C |
| Differential Input Voltage | ±5V | Lead Temperature (Soldering, 10 sec) | 300°C |
| Input Voltage (Note 1) | ±15V | | |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|---|-----|------|------|---------------|
| Input Offset Voltage (Note 4) | $T_A = 25^\circ\text{C}$, $R_S \leq 5k$ | | 2.0 | 8.0 | mV |
| Input Offset Current (Note 4) | $T_A = 25^\circ\text{C}$ | | 80 | 200 | nA |
| Input Bias Current | $T_A = 25^\circ\text{C}$ | | 250 | 1000 | nA |
| Voltage Gain | $T_A = 25^\circ\text{C}$ | 8 | 40 | | V/mV |
| Response Time (Note 5) | $T_A = 25^\circ\text{C}$ $V_S = \pm 15V$ | | 80 | | ns |
| Saturation Voltage | $V_{IN} \leq -10\text{ mV}$, $I_{OUT} = 25\text{ mA}$ $T_A = 25^\circ\text{C}$ | | 0.75 | 1.5 | V |
| Output Leakage Current | $V_{IN} \geq 10\text{ mV}$, $V_{OUT} = 35V$, $V^- = V_{GND} = 0V$, $T_A = 25^\circ\text{C}$ | | 0.2 | 10 | μA |
| Input Offset Voltage (Note 4) | $R_S \leq 5k$ | | | 10 | mV |
| Input Offset Current (Note 4) | | | | 300 | nA |
| Input Bias Current | | | | 1200 | nA |
| Input Voltage Range | $V_S = \pm 15V$ $V^+ = 5V$, $V^- = 0$ | 1 | ±13 | 3 | V |
| Saturation Voltage | $V^+ \geq 4.5V$, $V^- = 0$ $V_{IN} \leq -10\text{ mV}$, $I_{SINK} \leq 3.2\text{ mA}$ | | 0.3 | 0.4 | V |
| Differential Input Voltage | | | | ±5 | V |
| Positive Supply Current | $T_A = 25^\circ\text{C}$, $V^+ = 5V$, $V^- = 0$ | | 4.3 | | mA |
| Positive Supply Current | $T_A = 25^\circ\text{C}$ $V_S = \pm 15V$ | | 8 | 12.5 | mA |
| Negative Supply Current | $T_A = 25^\circ\text{C}$ $V_S = \pm 15V$ | | 3 | 5 | mA |

Note 1: For supply voltages less than ±15V the absolute maximum input voltage is equal to the supply voltage.

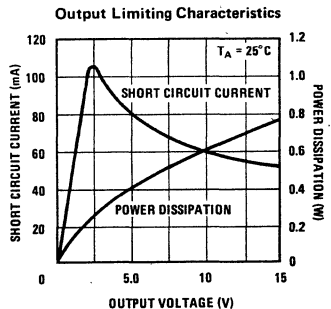
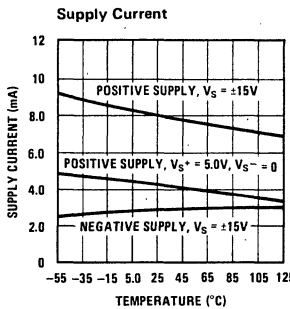
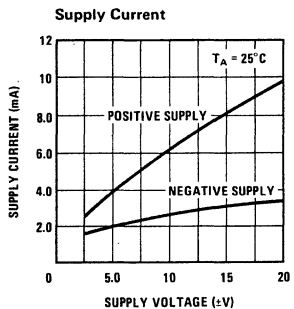
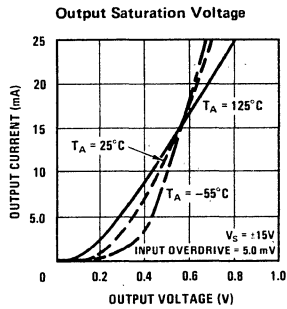
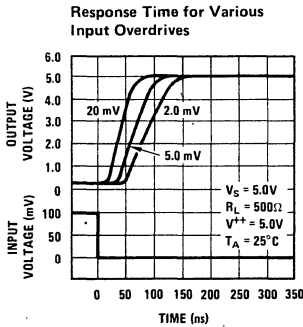
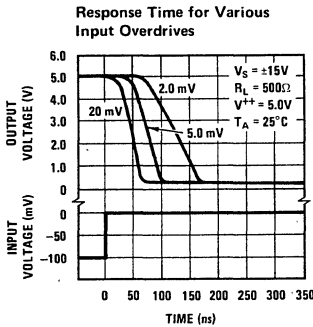
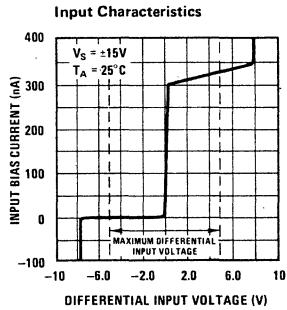
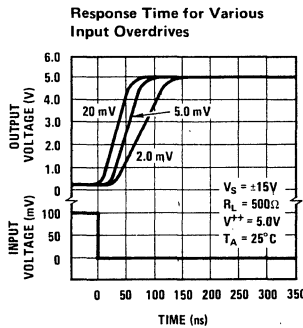
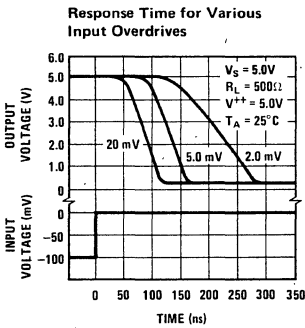
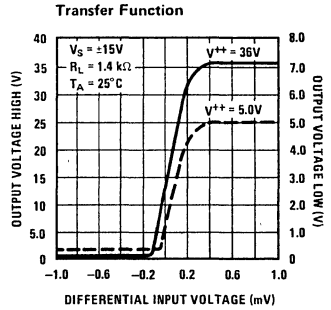
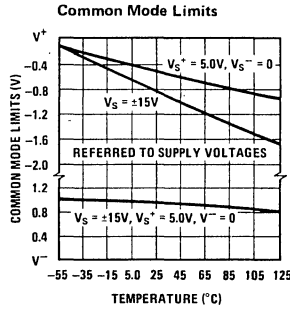
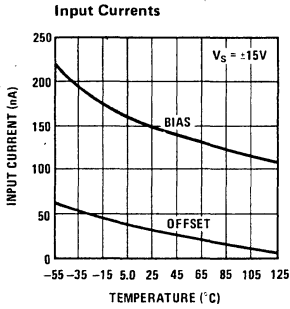
Note 2: The maximum junction temperature of the LM319 is 85°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient, or 45°C/W, junction to case. The thermal resistance of the dual-in-line package is 100°C/W, junction to ambient.

Note 3: These specifications apply for $V_S = \pm 15V$ and $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$, unless otherwise stated. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5V supply up to ±15V supplies.

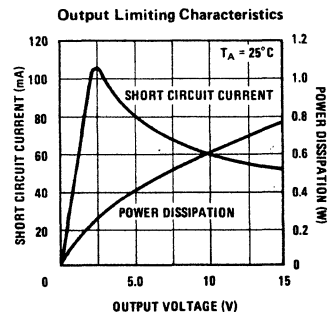
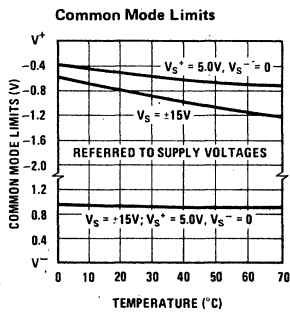
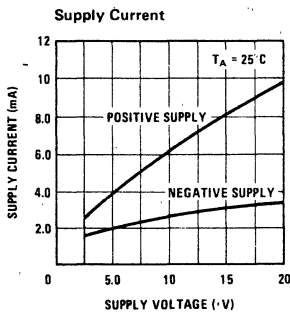
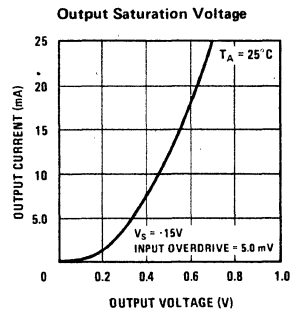
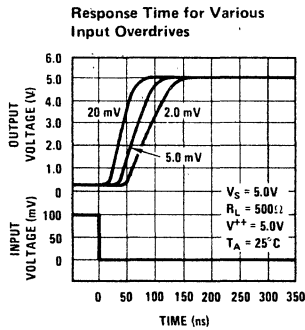
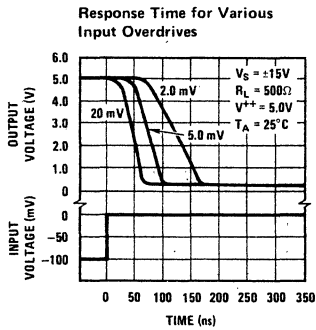
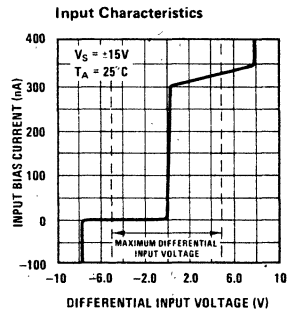
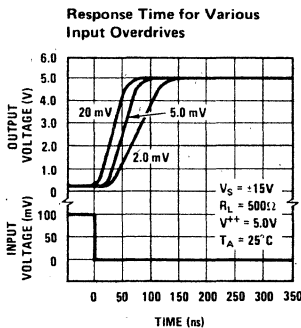
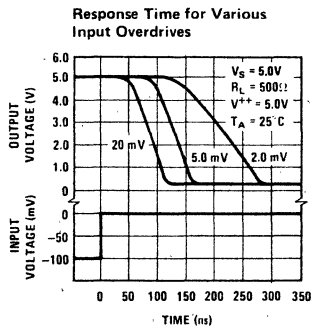
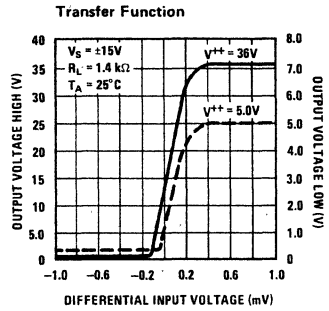
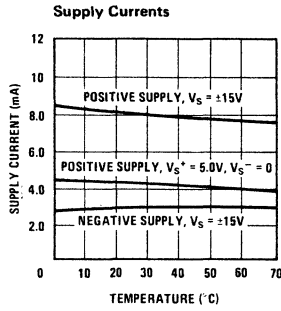
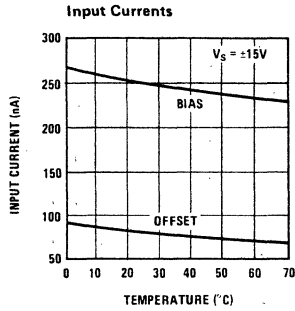
Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with a 1 mA load. Thus, these parameters define an error band and take into account the worst case effects of voltage gain and input impedance.

Note 5: The response time specified is for a 100 mV input step with 5 mV overdrive.

Typical Performance Characteristics LM119/LM219



Typical Performance Characteristics LM319





Voltage Comparators

LM139/ 239/ 339, LM139A/239A/339A, LM2901, LM3302 Low Power Low Offset Voltage Quad Comparators General Description

The LM139 series consists of four independent precision voltage comparators with an offset voltage specification as low as 2 mV max for all four comparators. These were designed specifically to operate from a single power supply over a wide range of voltages. Operation from split power supplies is also possible and the low power supply current drain is independent of the magnitude of the power supply voltage. These comparators also have a unique characteristic in that the input common-mode voltage range includes ground, even though operated from a single power supply voltage.

Application areas include limit comparators, simple analog to digital converters; pulse, squarewave and time delay generators; wide range VCO; MOS clock timers; multivibrators and high voltage digital logic gates. The LM139 series was designed to directly interface with TTL and CMOS. When operated from both plus and minus power supplies, they will directly interface with MOS logic— where the low power drain of the LM339 is a distinct advantage over standard comparators.

Advantages

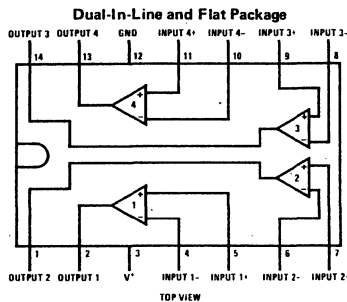
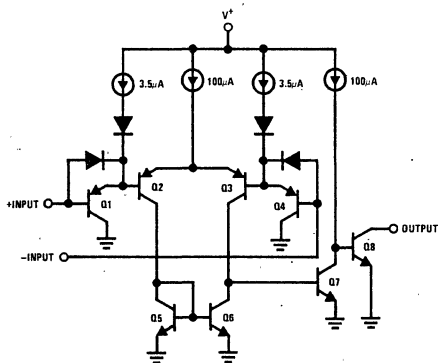
- High precision comparators
- Reduced V_{OS} drift over temperature

- Eliminates need for dual supplies
- Allows sensing near gnd
- Compatible with all forms of logic
- Power drain suitable for battery operation

Features

- Wide single supply voltage range or dual supplies
LM139 series, $2 V_{DC}$ to $36 V_{DC}$ or
LM139A series, LM2901 $\pm 1 V_{DC}$ to $\pm 18 V_{DC}$
LM3302 $2 V_{DC}$ to $28 V_{DC}$
or $\pm 1 V_{DC}$ to $\pm 14 V_{DC}$
- Very low supply current drain (0.8 mA) – independent of supply voltage (2 mW/comparator at $+5 V_{DC}$)
- Low input biasing current 25 nA
- Low input offset current ± 5 nA and offset voltage ± 3 mV
- Input common-mode voltage range includes gnd
- Differential input voltage range equal to the power supply voltage
- Low output 250 mV at 4 mA saturation voltage
- Output voltage compatible with TTL, DTL, ECL, MOS and CMOS logic systems

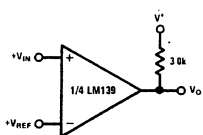
Schematic and Connection Diagrams



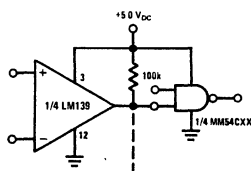
Order Number LM139J, LM139AJ, LM239J, LM239AJ, LM339J, LM339AJ, LM2901J or LM3302J
See NS Package J14A

Order Number LM339N, LM339AN, LM2901N or LM3302N
See NS Package N14A

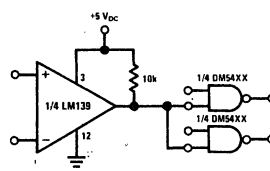
Typical Applications ($V^+ = 5.0 V_{DC}$)



Basic Comparator



Driving CMOS



Driving TTL

LM139/LM239/LM339, LM139A/LM239A/LM339A, LM2901, LM3302

5

LM139/LM239/LM339, LM139A/LM239A/LM339A, LM2901, LM3302

Absolute Maximum Ratings

| | LM139/LM239/LM339 LM139A/LM239A/LM339A LM2901 | LM3302 |
|---|---|---|
| Supply Voltage, V^+ | 36 V _{DC} or ±18 V _{DC} | 28 V _{DC} or ±14 V _{DC} |
| Differential Input Voltage | 36 V _{DC} | 28 V _{DC} |
| Input Voltage | -0.3 V _{DC} to +36 V _{DC} | -0.3 V _{DC} to +28 V _{DC} |
| Power Dissipation (Note 1) | | |
| Molded DIP | 570 mW | 570 mW |
| Cavity DIP | 900 mW | |
| Flat Pack | 800 mW | |
| Output Short-Circuit to GND, (Note 2) | Continuous | Continuous |
| Input Current ($V_{IN} < -0.3$ V _{DC}), (Note 3) | 50 mA | 50 mA |
| Operating Temperature Range | | |
| LM339A | 0°C to +70°C | -40°C to +85°C |
| LM239A | -25°C to +85°C | |
| LM2901 | -40°C to +85°C | |
| LM139A | -55°C to +125°C | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C | 300°C |

Electrical Characteristics ($V^+ = 5$ V_{DC}, Note 4)

| PARAMETER | CONDITIONS | LM139A | | | LM239A, LM339A | | | LM139 | | | LM239, LM339 | | | LM2901 | | | LM3302 | | | UNITS |
|---------------------------------|--|--------|------|-------------|----------------|------|-------------|-------|------|-------------|--------------|------|-------------|--------|------------------|-------------|-----------------|-----|-----|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, (Note 9) | | ±1.0 | ±2.0 | ±1.0 | ±2.0 | ±2.0 | ±5.0 | ±2.0 | ±5.0 | ±2.0 | ±7.0 | ±3 | ±20 | mV _{DC} | | | | | |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$ with Output in Linear Range, $T_A = 25^\circ\text{C}$, (Note 5) | | 25 | 100 | 25 | 250 | 25 | 100 | 25 | 250 | 25 | 250 | 25 | 500 | nADC | | | | | |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$, $T_A = 25^\circ\text{C}$ | | ±3.0 | ±25 | ±5.0 | ±50 | ±3.0 | ±25 | ±5.0 | ±50 | ±5 | ±50 | ±3 | ±100 | nADC | | | | | |
| Input Common-Mode Voltage Range | $T_A = 25^\circ\text{C}$, (Note 6) | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | V _{DC} | | | |
| Supply Current | $R_L = \infty$ on all Comparators, $T_A = 25^\circ\text{C}$ $R_L = \infty$, $V^+ = 30\text{V}$, $T_A = 25^\circ\text{C}$ | | 0.8 | 2.0 | 0.8 | 2.0 | 0.8 | 2.0 | 0.8 | 2.0 | 0.8 | 2.0 | 0.8 | 2 | mADC | | | | | |
| Voltage Gain | $R_L \geq 15$ k Ω , $V^+ = 15$ V _{DC} (To Support Large V_O Swing), $T_A = 25^\circ\text{C}$ | 50 | 200 | | 50 | 200 | 200 | | 200 | | 25 | 100 | 2 | 30 | V/mV | | | | | |
| Large Signal Response Time | $V_{IN} = \text{TTL Logic Swing}$, $V_{REF} = 1.4$ V _{DC} , $V_{RL} = 5$ V _{DC} , $R_L = 5.1$ k Ω , $T_A = 25^\circ\text{C}$ | | 300 | | 300 | | 300 | | 300 | | 300 | | 300 | | ns | | | | | |
| Response Time | $V_{RL} = 5$ V _{DC} , $R_L = 5.1$ k Ω , $T_A = 25^\circ\text{C}$, (Note 7) | | 1.3 | | 1.3 | | 1.3 | | 1.3 | | 1.3 | | 1.3 | | μs | | | | | |
| Output Sink Current | $V_{IN(-)} \geq 1$ V _{DC} , $V_{IN(+)} = 0$, $V_O \leq 1.5$ V _{DC} , $T_A = 25^\circ\text{C}$ | 6.0 | 16 | | 6.0 | 16 | 6.0 | 16 | 6.0 | 16 | 6.0 | 16 | 6.0 | 16 | mADC | | | | | |
| Saturation Voltage | $V_{IN(-)} \geq 1$ V _{DC} , $V_{IN(+)} = 0$, $I_{SINK} \leq 4$ mA, $T_A = 25^\circ\text{C}$ | | 250 | 400 | 250 | 400 | 250 | 400 | 250 | 400 | | 400 | 250 | 500 | mV _{DC} | | | | | |
| Output Leakage Current | $V_{IN(+)} \geq 1$ V _{DC} , $V_{IN(-)} = 0$, $V_O = 5$ V _{DC} , $T_A = 25^\circ\text{C}$ | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | nADC | | | | | |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM139A | | | LM239A, LM339A | | | LM139 | | | LM239, LM339 | | | LM2901 | | | LM3302 | | | UNITS |
|---------------------------------|---|--------|-----|-------------|----------------|-----|-------------|-------|-----|-------------|--------------|-----|-------------|--------|-----|-------------|--------|----------|------------------|-----------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | (Note 9) | | | 4.0 | | | 4.0 | | | 9.0 | | | 9.0 | 9 | 15 | | | 40 | mV _{DC} | |
| Input Offset Current | $I_{IN(+)} - I_{IN(-)}$ | | | ±100 | | | ±150 | | | ±100 | | | ±150 | 50 | 200 | | | 300 | nADC | |
| Input Bias Current | $I_{IN(+)}$ or $I_{IN(-)}$ with Output in Linear Range | | | 300 | | | 400 | | | 300 | | | 400 | 200 | 500 | | | 1000 | nADC | |
| Input Common-Mode Voltage Range | | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | V _{DC} |
| Saturation Voltage | $V_{IN(-)} \geq 1 V_{DC}$, $V_{IN(+)} = 0$, $I_{SINK} \leq 4$ mA | | | 700 | | | 700 | | | 700 | | | 700 | 400 | 700 | | | 700 | mV _{DC} | |
| Output Leakage Current | $V_{IN(+)} \geq 1 V_{DC}$, $V_{IN(-)} = 0$, $V_O = 30 V_{DC}$ | | | 1.0 | | | 1.0 | | | 1.0 | | | 1.0 | | | | | 1.0 | μADC | |
| Differential Input Voltage | Keep all $V_{IN}'s \geq 0 V_{DC}$ (or V^- , if used), (Note 8) | | | V^+ | | | V^+ | | | 36 | | | 36 | 0 | | V^+ | | V_{CC} | V _{DC} | |

Note 1: For operating at high temperatures, the LM339/LM339A, LM2901, LM3302 must be derated based on a 125°C maximum junction temperature and a thermal resistance of 175°C/W which applies for the device soldered in a printed circuit board, operating in a still air ambient. The LM239 and LM139 must be derated based on a 150°C maximum junction temperature. The low bias dissipation and the "ON-OFF" characteristic of the outputs keeps the chip dissipation very small ($P_D \leq 100$ mW), provided the output transistors are allowed to saturate.

Note 2: Short circuits from the output to V^+ can cause excessive heating and eventual destruction. The maximum output current is approximately 20 mA independent of the magnitude of V^+ .

Note 3: This input current will only exist when the voltage at any of the input leads is driven negative. It is due to the collector-base junction of the input PNP transistors becoming forward biased and thereby acting as input diode clamps. In addition to this diode action, there is also lateral NPN parasitic transistor action on the IC chip. This transistor action can cause the output voltages of the comparators to go to the V^+ voltage level (or to ground for a large overdrive) for the time duration that an input is driven negative. This is not destructive and normal output states will re-establish when the input voltage, which was negative, again returns to a value greater than $-0.3 V_{DC}$.

Note 4: These specifications apply for $V^+ = 5 V_{DC}$ and $-55^\circ C \leq T_A \leq +125^\circ C$, unless otherwise stated. With the LM239/LM239A, all temperature specifications are limited to $-25^\circ C \leq T_A \leq +85^\circ C$, the LM339/LM339A temperature specifications are limited to $0^\circ C \leq T_A \leq +70^\circ C$, and the LM2901, LM3302 temperature range is $-40^\circ C \leq T_A \leq +85^\circ C$.

Note 5: The direction of the input current is out of the IC due to the PNP input stage. This current is essentially constant, independent of the state of the output so no loading change exists on the reference or input lines.

Note 6: The input common-mode voltage or either input signal voltage should not be allowed to go negative by more than 0.3V. The upper end of the common-mode voltage range is $V^+ - 1.5V$, but either or both inputs can go to $+30 V_{DC}$ without damage.

Note 7: The response time specified is for a 100 mV input step with 5 mV overdrive. For larger overdrive signals 300 ns can be obtained, see typical performance characteristics section.

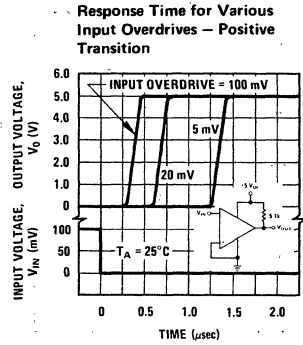
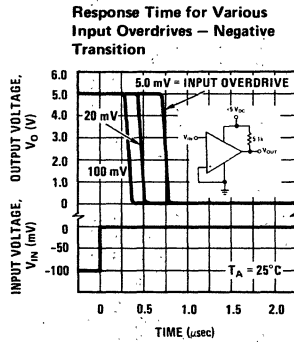
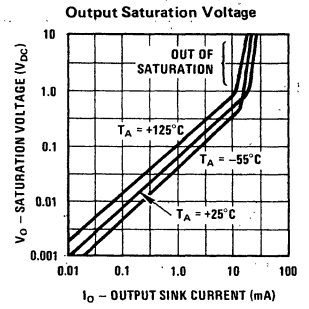
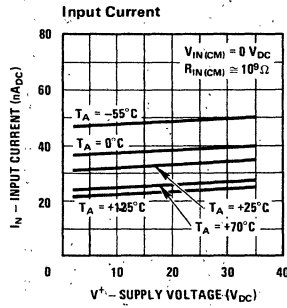
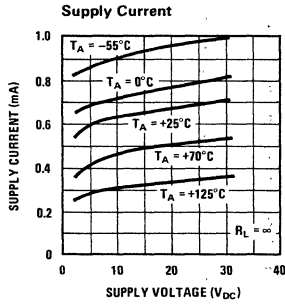
Note 8: Positive excursions of input voltage may exceed the power supply level. As long as the other voltage remains within the common-mode range, the comparator will provide a proper output state. The low input voltage state must not be less than $-0.3 V_{DC}$ (or $0.3 V_{DC}$ below the magnitude of the negative power supply, if used).

Note 9: At output switch point, $V_O \cong 1.4 V_{DC}$, $R_S = 0 \Omega$ with V^+ from $5 V_{DC}$; and over the full input common-mode range ($0 V_{DC}$ to $V^+ - 1.5 V_{DC}$).

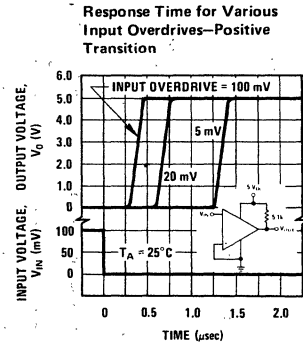
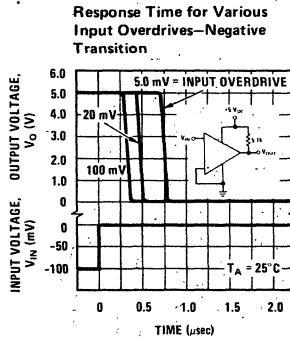
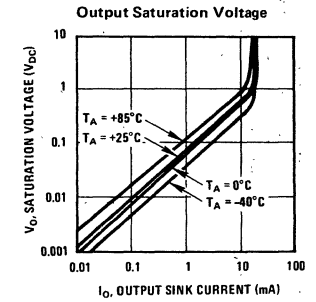
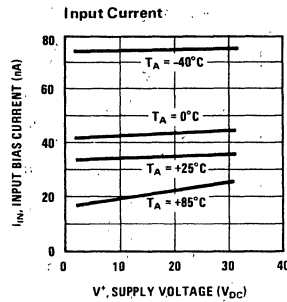
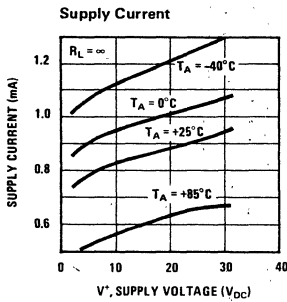
Note 10: For input signals that exceed V_{CC} , only the overdriven comparator is affected. With a 5V supply, V_{IN} should be limited to 25V max, and a limiting resistor should be used on all inputs that might exceed the positive supply.



Typical Performance Characteristics LM139/LM239/LM339, LM139A/LM239A/LM339A, LM3302



Typical Performance Characteristics LM2901



Application Hints

The LM139 series are high gain, wide bandwidth devices which, like most comparators, can easily oscillate if the output lead is inadvertently allowed to capacitively couple to the inputs via stray capacitance. This shows up only during the output voltage transition intervals as the comparator changes states. Power supply bypassing is not required to solve this problem. Standard PC board layout is helpful as it reduces stray input-output coupling. Reducing the input resistors to $< 10\text{ k}\Omega$ reduces the feedback signal levels and finally, adding even a small amount (1 to 10 mV) of positive feedback (hysteresis) causes such a rapid transition that oscillations due to stray feedback are not possible. Simply socketing the IC and attaching resistors to the pins will cause input-output oscillations during the small transition intervals unless hysteresis is used. If the input signal is a pulse waveform, with relatively fast rise and fall times, hysteresis is not required.

All pins of any unused comparators should be grounded.

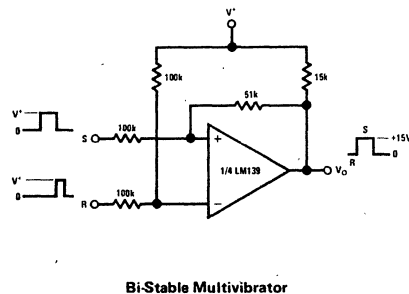
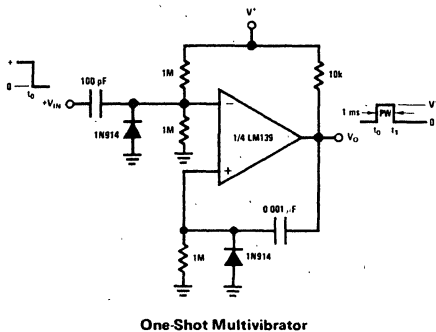
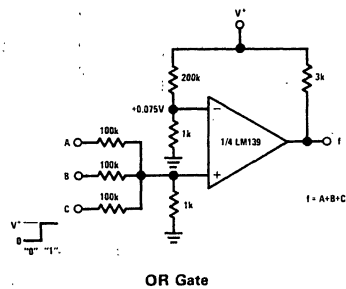
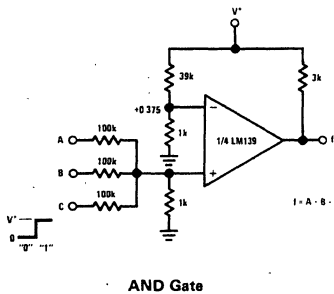
The bias network of the LM139 series establishes a drain current which is independent of the magnitude of the power supply voltage over the range of from 2 V_{DC} to 30 V_{DC} .

It is usually unnecessary to use a bypass capacitor across the power supply line.

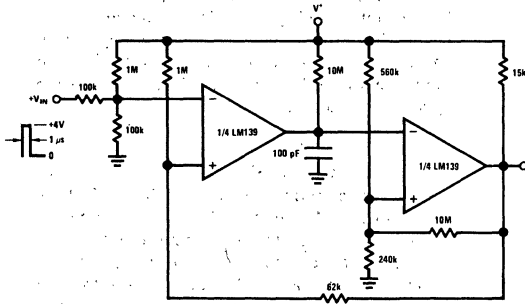
The differential input voltage may be larger than V^+ without damaging the device. Protection should be provided to prevent the input voltages from going negative more than $-0.3\text{ V}_{\text{DC}}$ (at 25°C). An input clamp diode can be used as shown in the applications section.

The output of the LM139 series is the uncommitted collector of a grounded-emitter NPN output transistor. Many collectors can be tied together to provide an output OR'ing function. An output pull-up resistor can be connected to any available power supply voltage within the permitted supply voltage range and there is no restriction on this voltage due to the magnitude of the voltage which is applied to the V^+ terminal of the LM139A package. The output can also be used as a simple SPST switch to ground (when a pull-up resistor is not used). The amount of current which the output device can sink is limited by the drive available (which is independent of V^+) and the β of this device. When the maximum current limit is reached (approximately 16 mA), the output transistor will come out of saturation and the output voltage will rise very rapidly. The output saturation voltage is limited by the approximately $60\Omega\ r_{\text{sat}}$ of the output transistor. The low offset voltage of the output transistor (1 mV) allows the output to clamp essentially to ground level for small load currents.

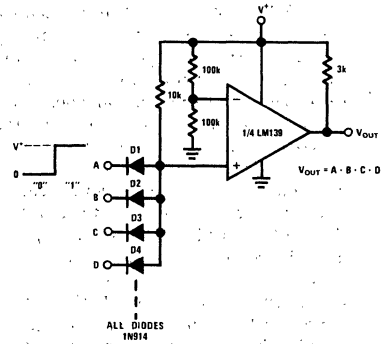
Typical Applications ($V^+ = 15\text{ V}_{\text{DC}}$)



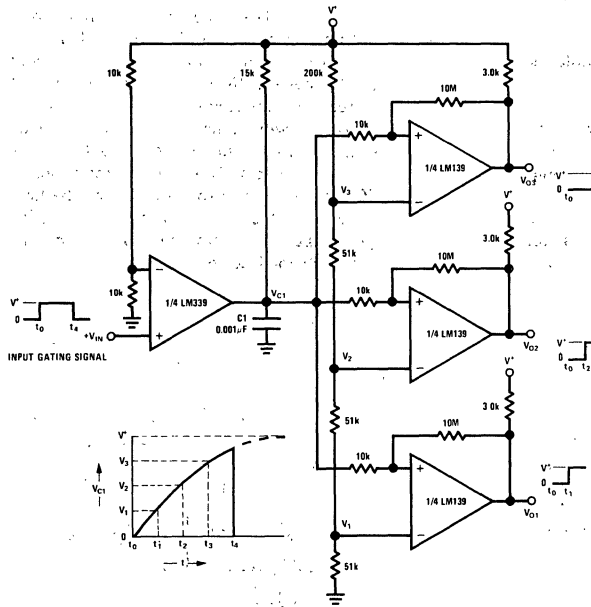
Typical Applications (Continued) ($V^+ = 15\text{ V}_{DC}$)



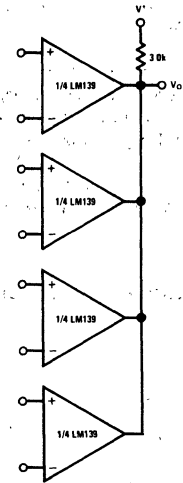
One-Shot Multivibrator with Input Lock Out



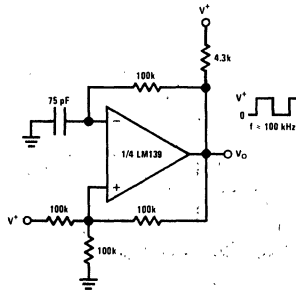
Large Fan-in AND Gate



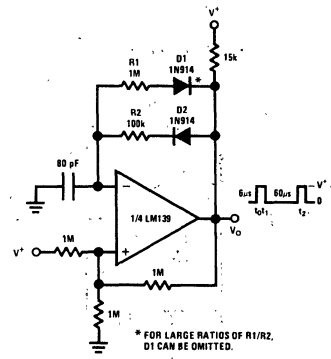
Time Delay Generator



Oring the Outputs



Squarwave Oscillator

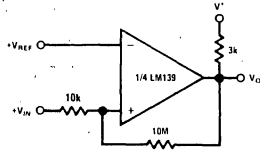


* FOR LARGE RATIOS OF R1/R2, D1 CAN BE OMITTED.

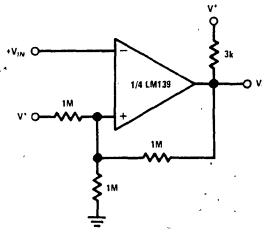
Pulse Generator

Typical Applications (Continued) ($V^+ = 5\text{ V}_{DC}$)

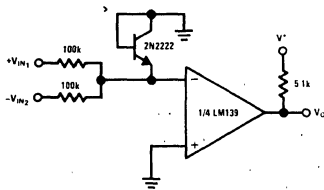
LM139/LM239/LM339,
LM139A/LM239A/LM339A, LM2901, LM3302



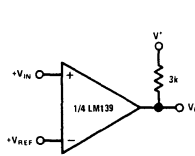
Non-Inverting Comparator with Hysteresis



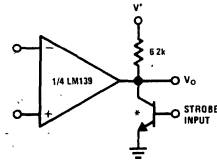
Inverting Comparator with Hysteresis



Comparing Input Voltages of Opposite Polarity

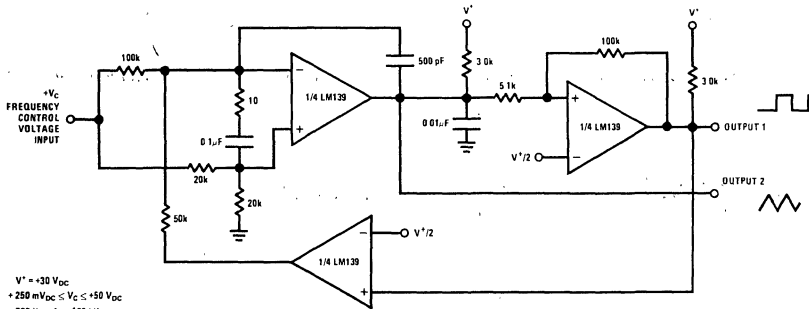


Basic Comparator



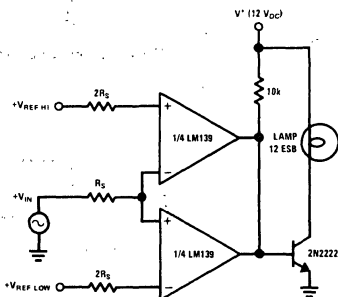
* OR LOGIC GATE WITHOUT PULL-UP RESISTOR

Output Strobing

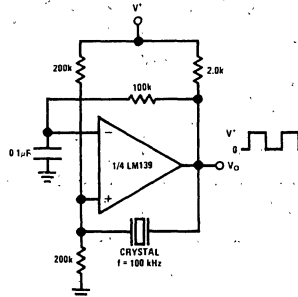


$V^+ = +30\text{ V}_{DC}$
 $+250\text{ mV}_{DC} \leq V_{O} \leq +50\text{ V}_{DC}$
 $700\text{ Hz} \leq f_o \leq 100\text{ kHz}$

Two-Decade High-Frequency VCO

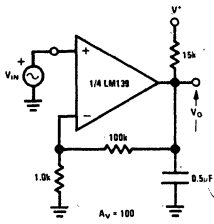


Limit Comparator

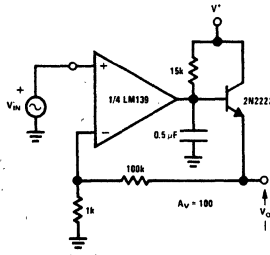


Crystal Controlled Oscillator

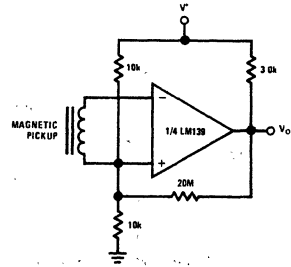
Typical Applications (Continued) ($V^+ = 5 V_{DC}$)



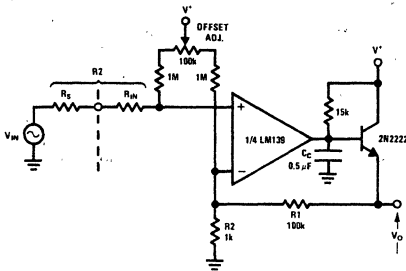
Low Frequency Op Amp



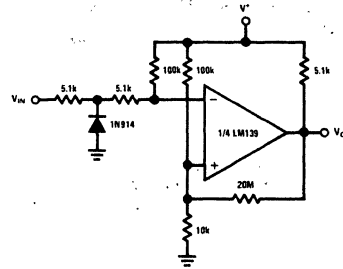
Low Frequency Op Amp
($V_O = 0V$ for $V_{IN} = 0V$)



Transducer Amplifier

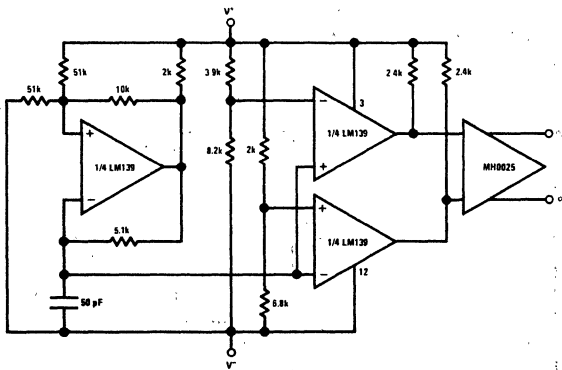


Low Frequency Op Amp with Offset Adjust

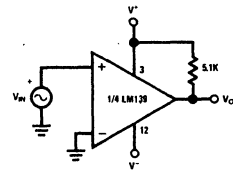


Zero Crossing Detector (Single Power Supply)

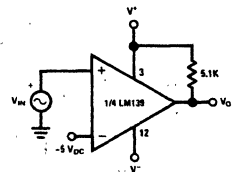
Split-Supply Applications ($V^+ = +15 V_{DC}$ and $V^- = -15 V_{DC}$)



MOS Clock Driver



Zero Crossing Detector



Comparator With a Negative Reference



**National
Semiconductor**

LM160/LM260/LM360 High Speed Differential Comparator

Voltage Comparators

General Description

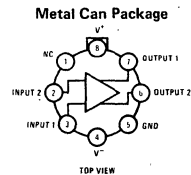
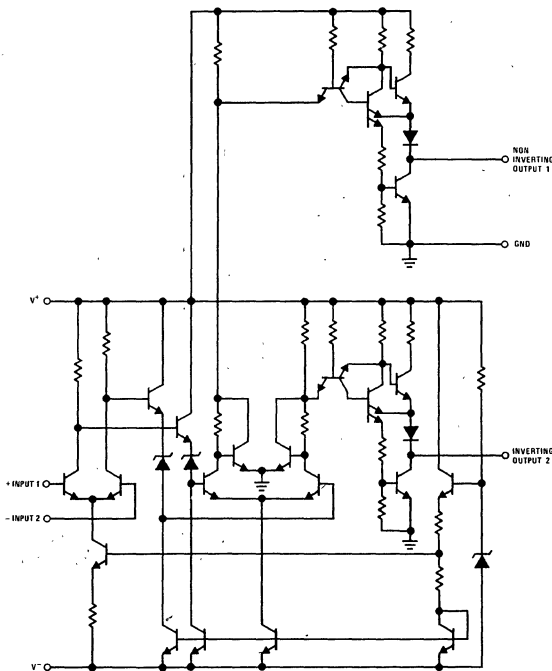
The LM160/LM260/LM360 is a very high speed differential input, complementary TTL output voltage comparator with improved characteristics over the $\mu A760/\mu A760C$, for which it is a pin-for-pin replacement. The device has been optimized for greater speed, input impedance and fan-out, and lower input offset voltage. Typically delay varies only 3 ns for overdrive variations of 5 mV to 500 mV.

Complementary outputs having minimum skew are provided. Applications involve high speed analog to digital converters and zero-crossing detectors in disc file systems.

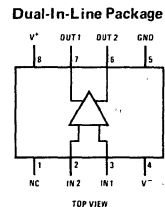
Features

- Guaranteed high speed 20 ns max
- Tight delay matching on both outputs
- Complementary TTL outputs
- High input impedance
- Low speed variation with overdrive variation
- Fan-out of 4
- Low input offset voltage
- Series 74 TTL compatible

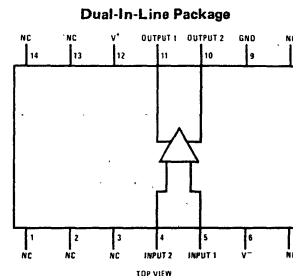
Schematic and Connection Diagrams



Order Number LM160H, LM260H or LM360H
See NS Package H08C



Order Number LM360N
See NS Package N08B



Order Number LM360N-14
See NS Package N14A
Order Number LM160J-14, LM260J-14
See NS Package J14A

LM160/LM260/LM360

5

Absolute Maximum Ratings

| | | | |
|----------------------------|----------------------|--------------------------------------|-----------------|
| Positive Supply Voltage | +8V | Operating Temperature Range | |
| Negative Supply Voltage | -8V | LM160 | -55°C to +125°C |
| Peak Output Current | 20 mA | LM260 | -25°C to +85°C |
| Differential Input Voltage | ±5V | LM360 | 0°C to +70°C |
| Input Voltage | $V^+ > V_{IN} > V^-$ | Storage Temperature Range | -65°C to +150°C |
| | | Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics ($T_{MIN} \leq T_A \leq T_{MAX}$)

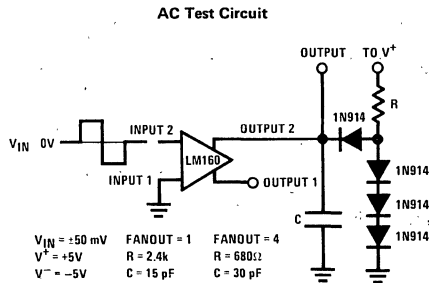
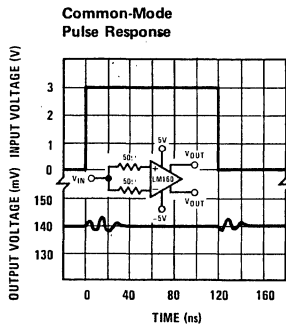
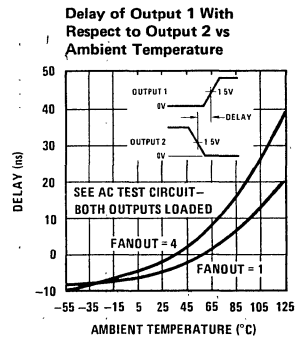
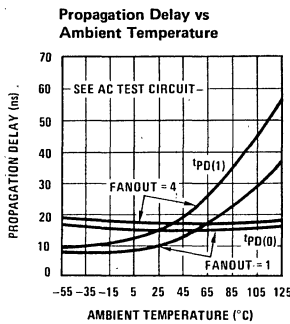
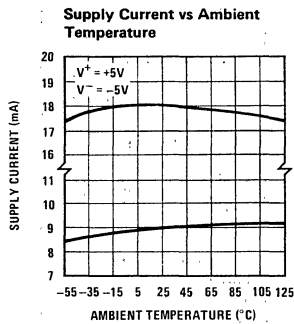
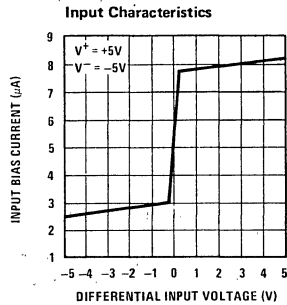
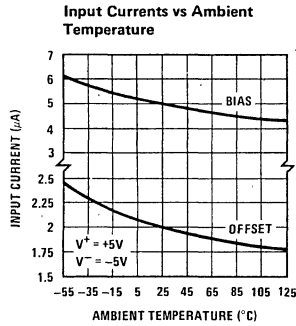
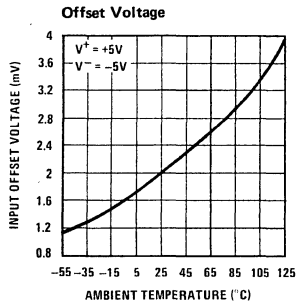
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|------|------|------|------------------------------|
| Operating Conditions | | | | | |
| Supply Voltage V_{CC}^+ | | 4.5 | 5 | 6.5 | V |
| Supply Voltage V_{CC}^- | | -4.5 | -5 | -6.5 | V |
| Input Offset Voltage | $R_S \leq 200\Omega$ | | 2 | 5 | mV |
| Input Offset Current | | | .5 | 3 | μ A |
| Input Bias Current | | | 5 | 20 | μ A |
| Output Resistance (Either Output) | $V_{OUT} = V_{OH}$ | | 100 | | Ω |
| Response Time | | | | | |
| | $T_A = 25^\circ\text{C}, V_S = \pm 5\text{V}$ (Note 1) | | 13 | 25 | ns |
| | $T_A = 25^\circ\text{C}, V_S = \pm 5\text{V}$ (Note 2) | | 12 | 20 | ns |
| | $T_A = 25^\circ\text{C}, V_S = \pm 5\text{V}$ (Note 3) | | 14 | | ns |
| Response Time Difference Between Outputs | | | | | |
| $(t_{pd} \text{ of } +V_{IN1}) - (t_{pd} \text{ of } -V_{IN2})$ | $T_A = 25^\circ\text{C}$, (Note 1) | | 2 | | ns |
| $(t_{pd} \text{ of } +V_{IN2}) - (t_{pd} \text{ of } -V_{IN1})$ | $T_A = 25^\circ\text{C}$, (Note 1) | | 2 | | ns |
| $(t_{pd} \text{ of } +V_{IN1}) - (t_{pd} \text{ of } +V_{IN2})$ | $T_A = 25^\circ\text{C}$, (Note 1) | | 2 | | ns |
| $(t_{pd} \text{ of } -V_{IN1}) - (t_{pd} \text{ of } -V_{IN2})$ | $T_A = 25^\circ\text{C}$, (Note 1) | | 2 | | ns |
| Input Resistance | $f = 1 \text{ MHz}$ | | 17 | | k Ω |
| Input Capacitance | $f = 1 \text{ MHz}$ | | 3 | | pF |
| Average Temperature Coefficient of Input Offset Voltage | $R_S = 50\Omega$ | | 8 | | $\mu\text{V}/^\circ\text{C}$ |
| Average Temperature Coefficient of Input Offset Current | | | 7 | | nA/ $^\circ\text{C}$ |
| Common Mode Input Voltage Range | $V_S = \pm 6.5\text{V}$ | ±4 | ±4.5 | | V |
| Differential Input Voltage Range | | ±5 | | | V |
| Output High Voltage (Either Output) | $I_{OUT} = -320\mu\text{A}, V_S = \pm 4.5\text{V}$ | 2.4 | 3 | | V |
| Output Low Voltage (Either Output) | $I_{SINK} = 6.4 \text{ mA}$ | | .25 | .4 | V |
| Positive Supply Current | $V_S = \pm 6.5\text{V}$ | | 18 | 32 | mA |
| Negative Supply Current | $V_S = \pm 6.5\text{V}$ | | -9 | -16 | mA |

Note 1: Response time measured from the 50% point of a 30 mVp-p 10 MHz sinusoidal input to the 50% point of the output.

Note 2: Response time measured from the 50% point of a 2 Vp-p 10 MHz sinusoidal input to the 50% point of the output.

Note 3: Response time measured from the start of a 100 mV input step with 5 mV overdrive to the time when the output crosses the logic threshold.

Typical Performance Characteristics





LM161/LM261/LM361 High Speed Differential Comparators

Voltage Comparators

General Description

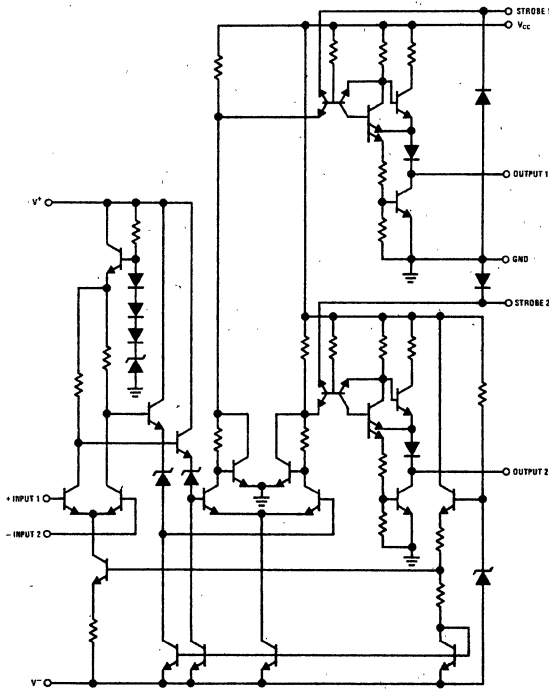
The LM161/LM261/LM361 is a very high speed differential input, complementary TTL output voltage comparator with improved characteristics over the SE529/NE529 for which it is a pin-for-pin replacement. The device has been optimized for greater speed performance and lower input offset voltage. Typically delay varies only 3 ns for over-drive variations of 5 mV to 500 mV. It may be operated from op amp supplies ($\pm 15V$).

Complementary outputs having minimum skew are provided. Applications involve high speed analog to digital converters and zero-crossing detectors in disc file systems.

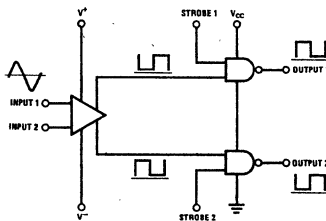
Features

- Independent strobes
- Guaranteed high speed 20 ns max
- Tight delay matching on both outputs
- Complementary TTL outputs
- Operates from op amp supplies $\pm 15V$
- Low speed variation with overdrive variation
- Low input offset voltage
- Versatile supply voltage range

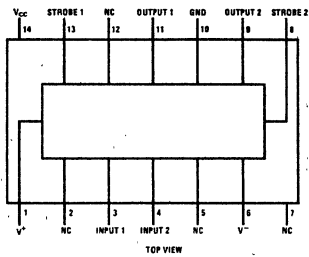
Schematic and Connection Diagrams



Logic Diagram

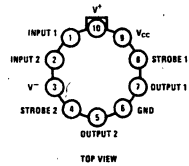


Dual-In-Line Package



Order Number LM161J, LM261J
or LM361J
See NS Package J14A
Order Number LM361N
See NS Package N14A

Metal Can Package



Order Number LM161H, LM261H
or LM361H
See NS Package H10C

Absolute Maximum Ratings

| | |
|--------------------------------------|---------------------|
| Positive Supply Voltage, V^+ | +16V |
| Negative Supply Voltage, V^- | -16V |
| Gate Supply Voltage, V_{CC} | +7V |
| Output Voltage | +7V |
| Differential Input Voltage | ±5V |
| Input Common Mode Voltage | ±6V |
| Power Dissipation | 600 mW |
| Storage Temperature Range | -65°C to +150°C |
| Operating Temperature Range | T_{MIN} T_{MAX} |
| LM161 | -55°C to +125°C |
| LM261 | -25°C to +85°C |
| LM361 | 0°C to +70°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

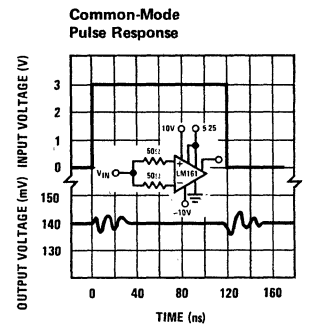
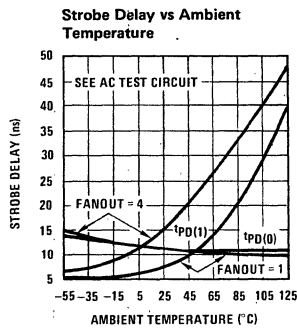
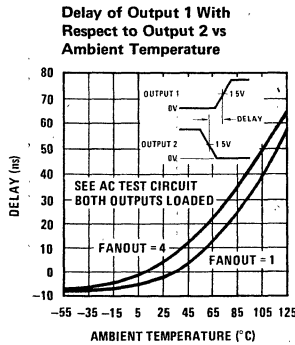
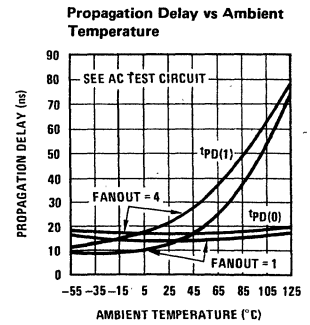
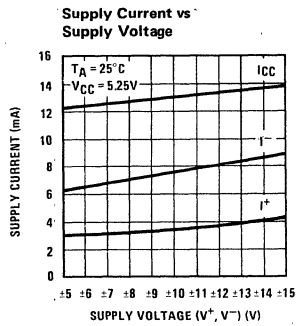
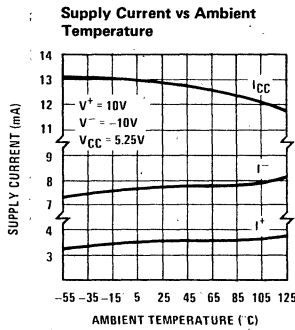
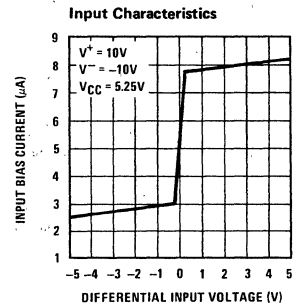
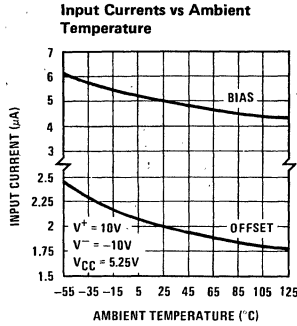
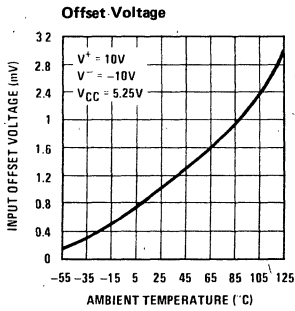
Operating Conditions

| | MIN | TYP | MAX |
|-------------------------|-------|-----|-------|
| Supply Voltage V^+ | | | |
| LM161/LM261 | 5V | | 15V |
| LM361 | 5V | | 15V |
| Supply Voltage V^- | | | |
| LM161/LM261 | -6V | | -15V |
| LM361 | -6V | | -15V |
| Supply Voltage V_{CC} | | | |
| LM161/LM261 | 4.5V | 5V | 5.5V |
| LM361 | 4.75V | 5V | 5.25V |

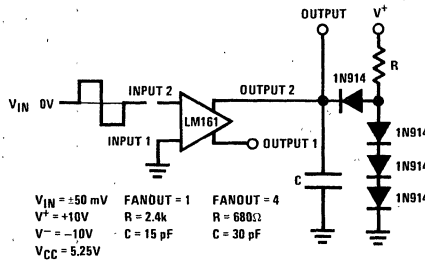
Electrical Characteristics ($V^+ = +10V, V_{CC} = +5V, V^- = -10V, T_{MIN} \leq T_A \leq T_{MAX}$, unless noted)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|--|--|------------------------------------|-----|------|-------|-----|------|------------|
| | | LM161/LM261 | | | LM361 | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | | | 1 | 3 | | 1 | 5 | mV |
| Input Bias Current | $T_A = 25^\circ C$ | | 5 | 20 | | 10 | 30 | μA |
| Input Offset Current | $T_A = 25^\circ C$ | | 2 | 3 | | 2 | 5 | μA |
| Voltage Gain | $T_A = 25^\circ C$ | | 3 | | | 3 | | V/mV |
| Input Resistance | $T_A = 25^\circ C, f = 1 \text{ kHz}$ | | 20 | | | 20 | | k Ω |
| Logical "1" Output Voltage | $V_{CC} = 4.75V, I_{SOURCE} = -5 \text{ mA}$ | 2.4 | 3.3 | | 2.4 | 3.3 | | V |
| Logical "0" Output Voltage | $V_{CC} = 4.75V, I_{SINK} = 6.4 \text{ mA}$ | | | .4 | | | .4 | V |
| Strobe Input "1" Current | $V_{CC} = 5.25V, V_{STROBE} = 2.4V$ | | | 200 | | | 200 | μA |
| Strobe Input "0" Current | $V_{CC} = 5.25V, V_{STROBE} = .4V$ | | | -1.6 | | | -1.6 | mA |
| Strobe Input "0" Voltage | $V_{CC} = 4.75V$ | | | .8 | | | .8 | V |
| Strobe Input "1" Voltage | $V_{CC} = 4.75V$ | 2 | | | 2 | | | V |
| Output Short Circuit Current | $V_{CC} = 5.25V, V_{OUT} = 0V$ | -18 | | 55 | -18 | | -55 | mA |
| Supply Current I^+ | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, -55^\circ C \leq T_A \leq 125^\circ C$ | | | 4.5 | | | | mA |
| Supply Current I^+ | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, 0^\circ C \leq T_A \leq 70^\circ C$ | | | | | | 5 | mA |
| Supply Current I^- | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, -55^\circ C \leq T_A \leq 125^\circ C$ | | | 10 | | | | mA |
| Supply Current I^- | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, 0^\circ C \leq T_A \leq 70^\circ C$ | | | | | | 10 | mA |
| Supply Current I_{CC} | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, -55^\circ C \leq T_A \leq 125^\circ C$ | | | 18 | | | | mA |
| Supply Current I_{CC} | $V^+ = 10V, V^- = -10V, V_{CC} = 5.25V, 0^\circ C \leq T_A \leq 70^\circ C$ | | | | | | 20 | mA |
| TRANSIENT RESPONSE | | $V_{IN} = 50 \text{ mV Overdrive}$ | | | | | | |
| Propagation Delay Time ($t_{pd(0)}$) | $T_A = 25^\circ C$ | | 14 | 20 | | 14 | 20 | ns |
| Propagation Delay Time ($t_{pd(1)}$) | $T_A = 25^\circ C$ | | 14 | 20 | | 14 | 20 | ns |
| Delay Between Output A and B | $T_A = 25^\circ C$ | | 2 | 5 | | 2 | 5 | ns |
| Strobe Delay Time ($t_{pd(0)}$) | $T_A = 25^\circ C$ | | 8 | | | 8 | | ns |
| Strobe Delay Time ($t_{pd(1)}$) | $T_A = 25^\circ C$ | | 8 | | | 8 | | ns |

Typical Performance Characteristics



AC Test Circuit



LM193/LM293/LM393, LM193A/LM293A/LM393A, LM2903

Low Power Low Offset Voltage Dual Comparators

General Description

The LM193 series consists of two independent precision voltage comparators with an offset voltage specification as low as 2.0 mV max for two comparators which were designed specifically to operate from a single power supply over a wide range of voltages. Operation from split power supplies is also possible and the low power supply current drain is independent of the magnitude of the power supply voltage. These comparators also have a unique characteristic in that the input common-mode voltage range includes ground, even though operated from a single power supply voltage.

Application areas include limit comparators, simple analog to digital converters; pulse, squarewave and time delay generators; wide range VCO; MOS clock timers; multivibrators and high voltage digital logic gates. The LM193 series was designed to directly interface with TTL and CMOS. When operated from both plus and minus power supplies, the LM193 series will directly interface with MOS logic—where their low power drain is a distinct advantage over standard comparators.

Advantages

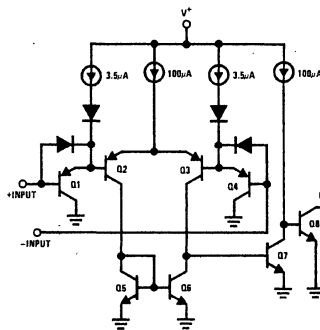
- High precision comparators
- Reduced V_{OS} drift over temperature

- Eliminates need for dual supplies
- Allows sensing near ground
- Compatible with all forms of logic
- Power drain suitable for battery operation

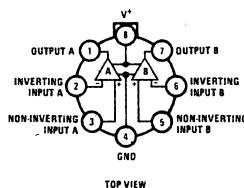
Features

- Wide single supply Voltage range
or dual supplies $2.0 V_{DC}$ to $36 V_{DC}$
 $\pm 1.0 V_{DC}$ to $\pm 18 V_{DC}$
- Very low supply current drain (0.8 mA)—independent of supply voltage (1.0 mW/comparator at $5.0 V_{DC}$)
- Low input biasing current 25 nA
- Low input offset current ± 5 nA
and maximum offset voltage ± 3 mV
- Input common-mode voltage range includes ground
- Differential input voltage range equal to the power supply voltage
- Low output saturation voltage 250 mV at 4 mA
- Output voltage compatible with TTL, DTL, ECL, MOS and CMOS logic systems

Schematic and Connection Diagrams

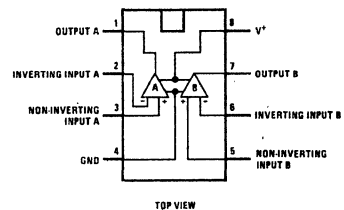


Metal Can Package



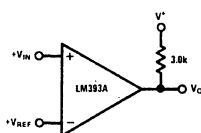
Order Number LM193H, LM193AH, LM293H, LM293AH, LM393H or LM393AH
See NS Package H08C

Dual-In-Line Package

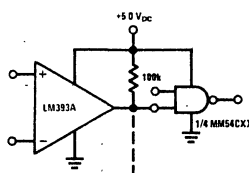


Order Number LM393N, LM393AN or LM2903N
See NS Package N08B

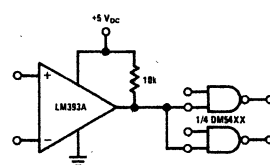
Typical Applications ($V^+ = 5.0 V_{DC}$)



Basic Comparator



Driving CMOS



Driving TTL

LM193/LM293/LM393, LM193A/LM293A/LM393A, LM2903

Absolute Maximum Ratings

| | |
|--|---|
| Supply Voltage, V^+ | 36 V _{DC} or ±18 V _{DC} |
| Differential Input Voltage | 36 V _{DC} |
| Input Voltage | -0.3 V _{DC} to +36 V _{DC} |
| Power Dissipation (Note 1) | |
| Molded DIP | 570 mW |
| Metal Can | 830 mW |
| Output Short-Circuit to Ground, (Note 2) | Continuous |
| Input Current ($V_{IN} < -0.3 V_{DC}$), (Note 3) | 50 mA |
| Operating Temperature Range | |
| LM393/LM393A | 0°C to +70°C |
| LM293/LM293A | -25°C to +85°C |
| LM193/LM193A | -55°C to +125°C |
| LM2903 | -40°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics ($V^+ = 5 V_{DC}$) (Note 4)

| PARAMETER | CONDITIONS | LM193A | | | LM293A, LM393A | | | LM193 | | | LM293, LM393 | | | LM2903 | | | UNITS |
|---------------------------------|--|--------|------|-------------|----------------|------|-------------|-------|------|-------------|--------------|------|-------------|--------|------|-------------|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $T_A = 25^\circ\text{C}$, (Note 9) | | ±1.0 | ±2.0 | | ±1.0 | ±2.0 | | ±1.0 | ±5.0 | | ±1.0 | ±5.0 | | ±2.0 | ±7.0 | mV _{DC} |
| Input Bias Current | I_{IN+} or I_{IN-} with Output In Linear Range, $T_A = 25^\circ\text{C}$, (Note 5) | | 25 | 100 | | 25 | 250 | | 25 | 100 | | 25 | 250 | | 25 | 250 | nADC |
| Input Offset Current | $I_{IN+} - I_{IN-}$, $T_A = 25^\circ\text{C}$ | | ±3.0 | ±25 | | ±5.0 | ±50 | | ±3.0 | ±25 | | ±5.0 | ±50 | | ±5.0 | ±50 | nADC |
| Input Common-Mode Voltage Range | $T_A = 25^\circ\text{C}$, (Note 6) | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | 0 | | $V^+ - 1.5$ | V _{DC} |
| Supply Current | $R_L = \infty$ on All Comparators, $T_A = 25^\circ\text{C}$ | | 0.4 | 1 | | 0.4 | 1 | | 0.4 | 1 | | 0.4 | 1 | | 0.4 | 1.0 | mADC |
| | $R_L = \infty$ on All Amps, $V^+ = 30 V_{DC}$ | | 1 | 2.5 | | 1 | 2.5 | | 2.5 | | | 2.5 | | 1 | 2.5 | | mADC |
| Voltage Gain | $R_L \geq 15 k\Omega$, $T_A = 25^\circ\text{C}$, $V^+ = 15 V_{DC}$ (To Support Large V_O Swing) | 50 | 200 | | 50 | 200 | | 50 | 200 | | 50 | 200 | | 25 | 100 | | V/ μ V |
| Large Signal Response Time | $V_{IN} = \text{TTL Logic Swing}$, $V_{REF} = 1.4 V_{DC}$ $V_{RL} = 5 V_{DC}$, $R_L = 5.1 k\Omega$, $T_A = 25^\circ\text{C}$ | | 300 | | 300 | | 300 | | 300 | | 300 | | 300 | | 300 | | ns |
| Response Time | $V_{RL} = 5 V_{DC}$, $R_L = 5.1 k\Omega$, $T_A = 25^\circ\text{C}$, (Note 7) | | 1.3 | | 1.3 | | 1.3 | | 1.3 | | 1.3 | | 1.5 | | 1.5 | | μ s |
| Output Sink Current | $V_{IN-} \geq 1 V_{DC}$, $V_{IN+} = 0$, $V_O \leq 1.5 V_{DC}$, $T_A = 25^\circ\text{C}$ | 6.0 | 16 | | 6.0 | 16 | | 6.0 | 16 | | 6.0 | 16 | | 6 | 16 | | mADC |
| Saturation Voltage | $V_{IN-} \geq 1 V_{DC}$, $V_{IN+} = 0$, $I_{SINK} \leq 4 \text{ mA}$, $T_A = 25^\circ\text{C}$ | | 250 | 400 | | 250 | 400 | | 250 | 400 | | 250 | 400 | | 400 | | mV _{DC} |
| Output Leakage Current | $V_{IN-} = 0$, $V_{IN+} \geq 1 V_{DC}$, $V_O = 5 V_{DC}$, $T_A = 25^\circ\text{C}$ | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | 0.1 | | nADC |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | LM193A | | | LM293A, LM393A | | | LM193 | | | LM293, LM393 | | | LM2903 | | UNITS |
|---------------------------------|---|--------|-----|-------------|----------------|-----|-------------|-------|-----|-------------|--------------|-----|-------------|--------|------------|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | |
| Input Offset Voltage | (Note 9) | | | 4.0 | | | 4.0 | | | 9 | | | 9 | 9 | 15 | mV _{DC} |
| Input Offset Current | $I_{IN+} - I_{IN-}$ | | | ±100 | | | ±150 | | | ±100 | | | ±150 | 50 | 200 | nA _{DC} |
| Input Bias Current | I_{IN+} or I_{IN-} with Output in Linear Range | | | 300 | | | 400 | | | 300 | | | 400 | 200 | 500 | nA _{DC} |
| Input Common-Mode Voltage Range | | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | | $V^+ - 2.0$ | 0 | $V^+ - 20$ | V _{DC} |
| Saturation Voltage | $V_{IN-} \geq 1 V_{DC}$, $V_{IN+} = 0$, $I_{SINK} \leq 4$ mA | | | 700 | | | 700 | | | 700 | | | 700 | 400 | 700 | mV _{DC} |
| Output Leakage Current | $V_{IN-} = 0$, $V_{IN+} \geq 1 V_{DC}$, $V_O = 30 V_{DC}$ | | | 1.0 | | | 1.0 | | | 1.0 | | | 1.0 | 1.0 | 1.0 | μA _{DC} |
| Differential Input Voltage | Keep All V_{IN} 's $\geq 0 V_{DC}$ (or V^- , if Used), (Note 8) | | | V^+ | | | V^+ | | | V^+ | | | V^+ | V^+ | V^+ | V _{DC} |

Note 1: For operating at high temperatures, the LM393/LM393A and LM2903 must be derated based on a 125°C maximum junction temperature and a thermal resistance of 175°C/W which applies for the device soldered in a printed circuit board, operating in a still air ambient. The LM193/LM193A/LM293/LM293A must be derated based on a 150°C maximum junction temperature. The low bias dissipation and the "ON-OFF" characteristic of the outputs keeps the chip dissipation very small ($P_D \leq 100$ mW), provided the output transistors are allowed to saturate.

Note 2: Short circuits from the output to V^+ can cause excessive heating and eventual destruction. The maximum output current is approximately 20 mA independent of the magnitude of V^+ .

Note 3: This input current will only exist when the voltage at any of the input leads is driven negative. It is due to the collector-base junction of the input PNP transistors becoming forward biased and thereby acting as input diode clamps. In addition to this diode action, there is also lateral NPN parasitic transistor action on the IC chip. This transistor action can cause the output voltages of the comparators to go to the V^+ voltage level (or to ground for a large overdrive) for the time duration that an input is driven negative. This is not destructive and normal output states will re-establish when the input voltage, which was negative, again returns to a value greater than $-0.3 V_{DC}$.

Note 4: These specifications apply for $V^+ = 5 V_{DC}$ and $-55^\circ C \leq T_A \leq +125^\circ C$, unless otherwise stated. With the LM293/LM293A all temperature specifications are limited to $-25^\circ C \leq T_A \leq +85^\circ C$ and the LM393/LM393A temperature specifications are limited to $0^\circ C \leq T_A \leq +70^\circ C$. The LM2903 is limited to $-40^\circ C \leq T_A \leq +85^\circ C$.

Note 5: The direction of the input current is out of the IC due to the PNP input stage. This current is essentially constant, independent of the state of the output so no loading change exists on the reference or input lines.

Note 6: The input common-mode voltage or either input signal voltage should not be allowed to go negative by more than 0.3V. The upper end of the common-mode voltage range is $V^+ - 1.5V$, but either or both inputs can go to $30 V_{DC}$ without damage.

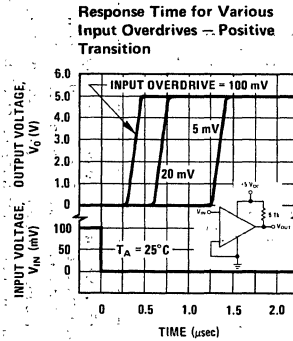
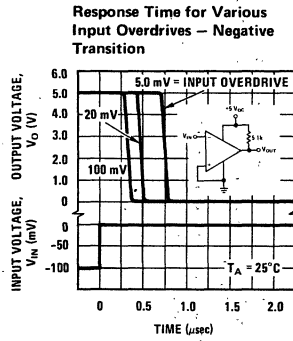
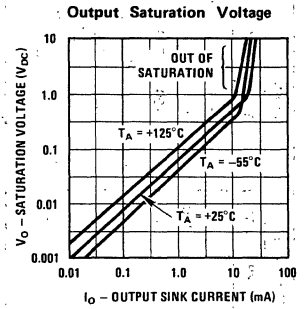
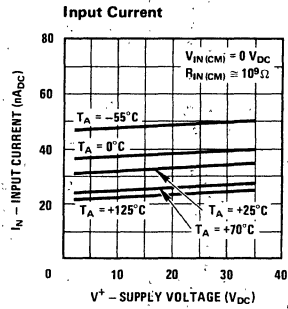
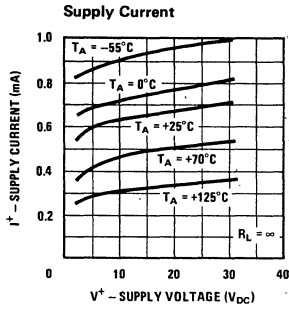
Note 7: The response time specified is for a 100 mV input step with 5 mV overdrive. For larger overdrive signals 300 ns can be obtained, see typical performance characteristics section.

Note 8: Positive excursions of input voltage may exceed the power supply level. As long as the other voltage remains within the common-mode range, the comparator will provide a proper output state. The low input voltage state must not be less than $-0.3 V_{DC}$ (or $0.3 V_{DC}$ below the magnitude of the negative power supply, if used).

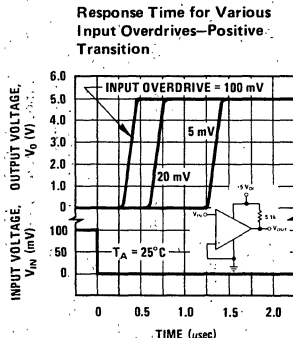
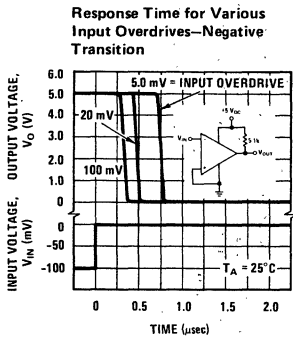
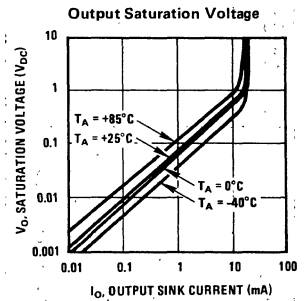
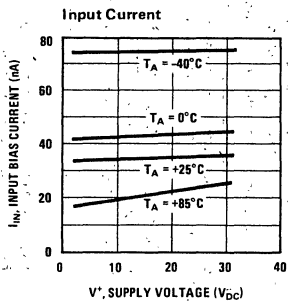
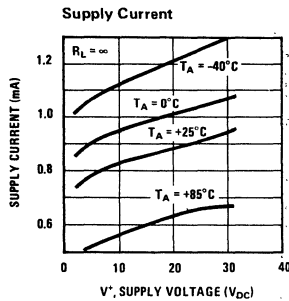
Note 9: At output switch point, $V_O \approx 1.4 V_{DC}$, $R_S = 0\Omega$ with V^+ from $5 V_{DC}$ to $30 V_{DC}$; and over the full input common-mode range ($0 V_{DC}$ to $V^+ - 1.5 V_{DC}$).

Note 10: For input signals that exceed V_{CC} , only the overdriven comparator is affected. With a 5V supply, V_{IN} should be limited to 25V max, and a limiting resistor should be used on all inputs that might exceed the positive supply.

Typical Performance Characteristics LM193/LM293/LM393, LM193A/LM293A/LM393A



Typical Performance Characteristics LM2903



Application Hints

The LM193 series are high gain, wide bandwidth devices which, like most comparators, can easily oscillate if the output lead is inadvertently allowed to capacitively couple to the inputs via stray capacitance. This shows up only during the output voltage transition intervals as the comparator changes states. Power supply bypassing is not required to solve this problem. Standard PC board layout is helpful as it reduces stray input-output coupling. Reducing the input resistors to $< 10 \text{ k}\Omega$ reduces the feedback signal levels and finally, adding even a small amount (1.0 to 10 mV) of positive feedback (hysteresis) causes such a rapid transition that oscillations due to stray feedback are not possible. Simply socketing the IC and attaching resistors to the pins will cause input-output oscillations during the small transition intervals unless hysteresis is used. If the input signal is a pulse waveform, with relatively fast rise and fall times, hysteresis is not required.

All pins of any unused comparators should be grounded.

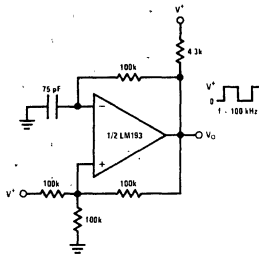
The bias network of the LM193 series establishes a drain current which is independent of the magnitude of the power supply voltage over the range of from $2.0 V_{DC}$ to $30 V_{DC}$.

It is usually unnecessary to use a bypass capacitor across the power supply line.

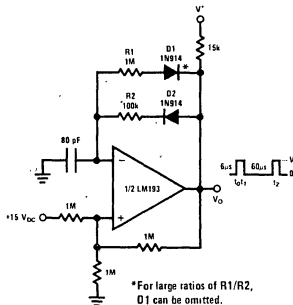
The differential input voltage may be larger than V^+ without damaging the device (see Note 8). Protection should be provided to prevent the input voltages from going negative more than $-0.3 V_{DC}$ (at 25°C). An input clamp diode can be used as shown in the applications section.

The output of the LM193 series is the uncommitted collector of a grounded-emitter NPN output transistor. Many collectors can be tied together to provide an output OR'ing function. An output pull-up resistor can be connected to any available power supply voltage within the permitted supply voltage range and there is no restriction on this voltage due to the magnitude of the voltage which is applied to the V^+ terminal of the LM193 package. The output can also be used as a simple SPST switch to ground (when a pull-up resistor is not used). The amount of current which the output device can sink is limited by the drive available (which is independent of V^+) and the β of this device. When the maximum current limit is reached (approximately 16 mA), the output transistor will come out of saturation and the output voltage will rise very rapidly. The output saturation voltage is limited by the approximately $60\Omega r_{SAT}$ of the output transistor. The low offset voltage of the output transistor (1.0 mV) allows the output to clamp essentially to ground level for small load currents.

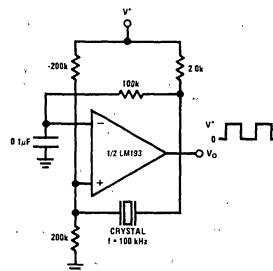
Typical Applications (Continued) ($V^+ = 15 V_{DC}$)



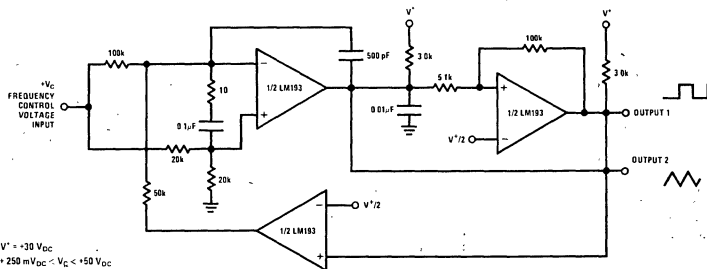
Squarewave Oscillator



Pulse Generator



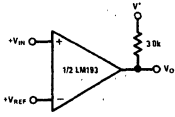
Crystal Controlled Oscillator



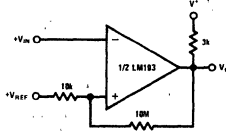
Two-Decade High-Frequency VCO

$V^+ = -30 V_{DC}$
 $+250 \text{ mV}_{DC} < V_C < +50 V_{DC}$
 $700 \text{ Hz} - f_0 < 100 \text{ kHz}$

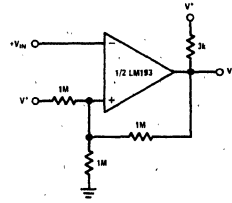
Typical Applications (Continued) ($V^+ = 15 V_{DC}$)



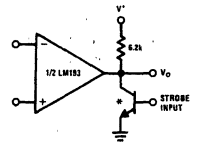
Basic Comparator



Non-Inverting Comparator with Hysteresis

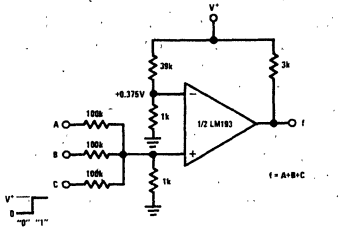


Inverting Comparator with Hysteresis

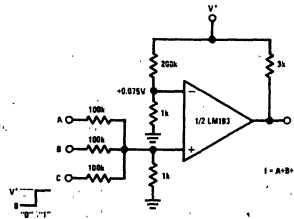


* OR LOGIC GATE WITHOUT PULL UP RESISTOR

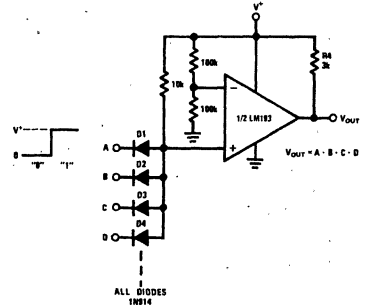
Output Strobe



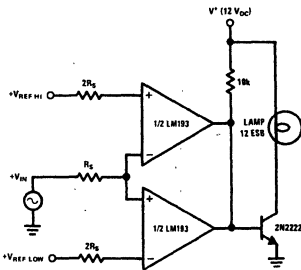
AND Gate



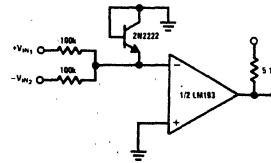
OR Gate



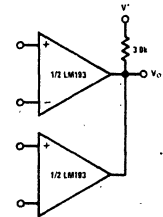
Large Fan-in AND Gate



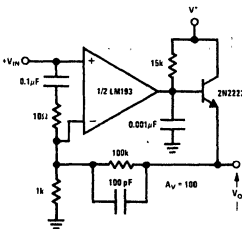
Limit Comparator



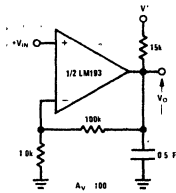
Comparing Input Voltages of Opposite Polarity



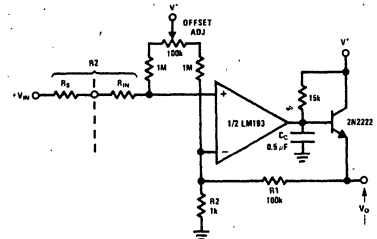
ORing the Outputs



Improved Op Amp



Low Frequency Op Amp

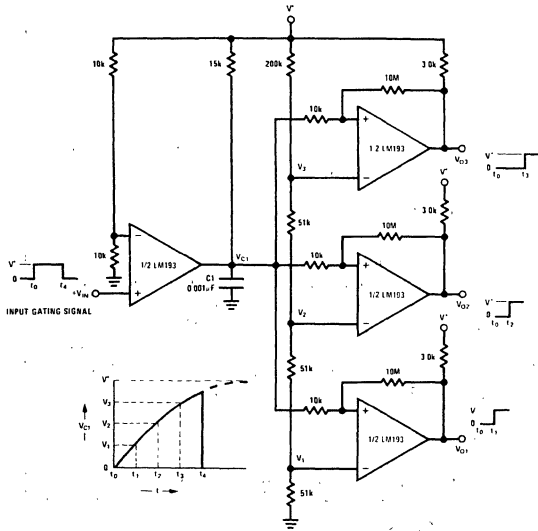


Low Frequency Op Amp with Offset Adjust

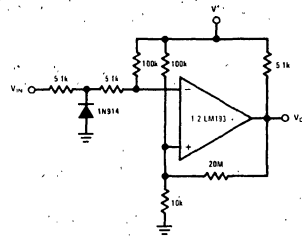
Typical Applications (Continued) ($V^+ = 15 V_{DC}$)

LM193/LM293/LM393,
LM193A/LM293A/LM393A, LM2903

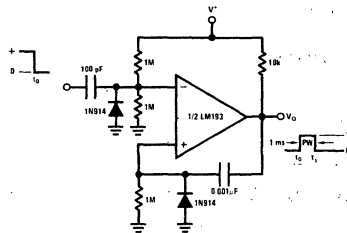
5



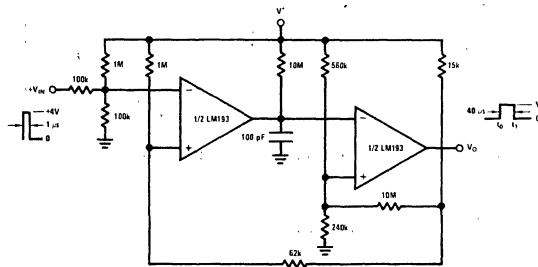
Time Delay Generator



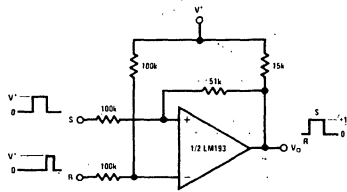
Zero Crossing Detector (Single Power Supply)



One-Shot Multivibrator

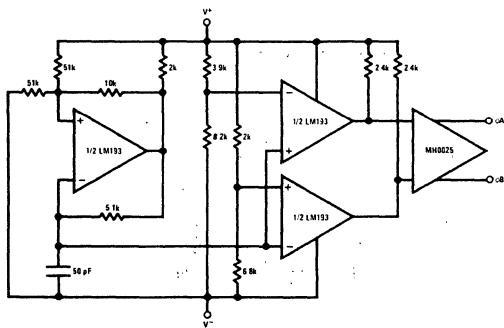


One-Shot Multivibrator with Input Lock Out

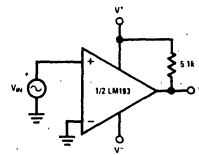


Bi-Stable Multivibrator

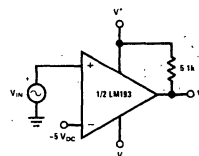
Split-Supply Applications ($V^+ = +15 V_{DC}$ and $V^- = -15 V_{DC}$)



MOS Clock Driver



Zero Crossing Detector



Comparator With a Negative Reference

LM311 Voltage Comparator

General Description

The LM311 is a voltage comparator that has input currents more than a hundred times lower than devices like the LM306 or LM710C. It is also designed to operate over a wider range of supply voltages: from standard $\pm 15V$ op amp supplies down to the single 5V supply used for IC logic. Its output is compatible with RTL, DTL and TTL as well as MOS circuits. Further, it can drive lamps or relays, switching voltages up to 40V at currents as high as 50 mA.

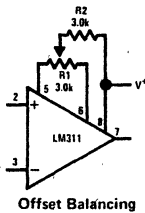
Features

- Operates from single 5V supply
- Maximum input current: 250 nA
- Maximum offset current: 50 nA

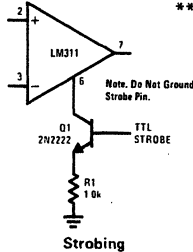
- Differential input voltage range: $\pm 30V$
- Power consumption: 135 mW at $\pm 15V$

Both the input and the output of the LM311 can be isolated from system ground, and the output can drive loads referred to ground, the positive supply or the negative supply. Offset balancing and strobe capability are provided and outputs can be wire OR'ed. Although slower than the LM306 and LM710C (200 ns response time vs 40 ns) the device is also much less prone to spurious oscillations. The LM311 has the same pin configuration as the LM306 and LM710C. See the "application hints" of the LM311 for application help.

Auxiliary Circuits **

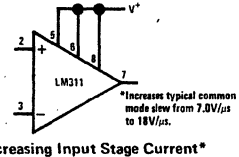


Offset Balancing



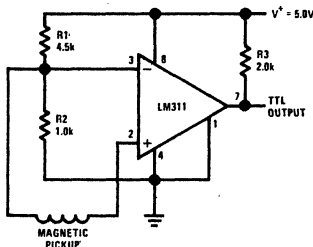
Strobing

** Note: Pin connections shown on schematic diagram and typical applications are for TO-5 package.

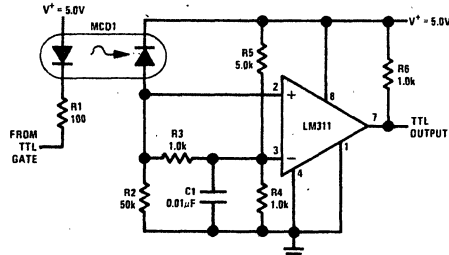


Increasing Input Stage Current*

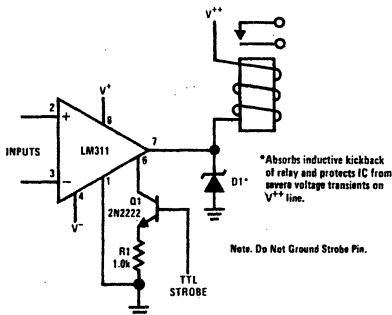
Typical Applications **



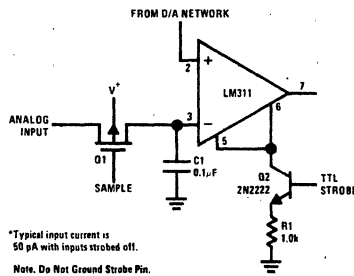
Detector for Magnetic Transducer



Digital Transmission Isolator



Relay Driver with Strobe



Strobing off Both Input* and Output Stages

Absolute Maximum Ratings

| | |
|--|----------------------------------|
| Total Supply Voltage (V_{84}) | 36V |
| Output to Negative Supply Voltage (V_{74}) | 40V |
| Ground to Negative Supply Voltage (V_{14}) | 30V |
| Differential Input Voltage | $\pm 30V$ |
| Input Voltage (Note 1) | $\pm 15V$ |
| Power Dissipation (Note 2) | 500 mW |
| Output Short Circuit Duration | 10 sec |
| Operating Temperature Range | $0^{\circ}C$ to $70^{\circ}C$ |
| Storage Temperature Range | $-65^{\circ}C$ to $150^{\circ}C$ |
| Lead Temperature (soldering, 10 sec) | $300^{\circ}C$ |
| Voltage at Strobe Pin | $V^{+}-5V$ |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|---|-------|------------|------|-------|
| Input Offset Voltage (Note 4) | $T_A = 25^{\circ}C$, $R_S \leq 50k$ | | 2.0 | 7.5 | mV |
| Input Offset Current (Note 4) | $T_A = 25^{\circ}C$ | | 6.0 | 50 | nA |
| Input Bias Current | $T_A = 25^{\circ}C$ | | 100 | 250 | nA |
| Voltage Gain | $T_A = 25^{\circ}C$ | 40 | 200 | | V/mV |
| Response Time (Note 5) | $T_A = 25^{\circ}C$ | | 200 | | ns |
| Saturation Voltage | $V_{IN} \leq -10$ mV, $I_{OUT} = 50$ mA $T_A = 25^{\circ}C$ | | 0.75 | 1.5 | V |
| Strobe ON Current | $T_A = 25^{\circ}C$ | | 3.0 | | mA |
| Output Leakage Current | $V_{IN} \geq 10$ mV, $V_{OUT} = 35V$ $T_A = 25^{\circ}C$, $I_{STROBE} = 3$ mA | | 0.2 | 50 | nA |
| Input Offset Voltage (Note 4) | $R_S \leq 50k$ | | | 10 | mV |
| Input Offset Current (Note 4) | | | | 70 | nA |
| Input Bias Current | | | | 300 | nA |
| Input Voltage Range | | -14.5 | 13.8,-14.7 | 13.0 | V |
| Saturation Voltage | $V^{+} \geq 4.5V$, $V^{-} = 0$ $V_{IN} \leq -10$ mV, $I_{SINK} \leq 8$ mA | | 0.23 | 0.4 | V |
| Positive Supply Current | $T_A = 25^{\circ}C$ | | 5.1 | 7.5 | mA |
| Negative Supply Current | $T_A = 25^{\circ}C$ | | 4.1 | 5.0 | mA |

Note 1: This rating applies for $\pm 15V$ supplies. The positive input voltage limit is 30V above the negative supply. The negative input voltage limit is equal to the negative supply voltage or 30V below the positive supply, whichever is less.

Note 2: The maximum junction temperature of the LM311 is $110^{\circ}C$. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of $150^{\circ}C/W$, junction to ambient, or $45^{\circ}C/W$, junction to case. The thermal resistance of the dual-in-line package is $100^{\circ}C/W$, junction to ambient.

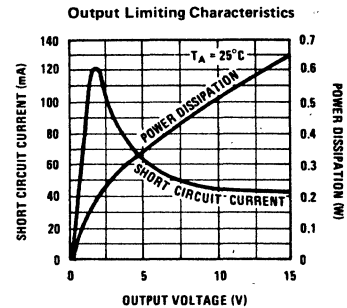
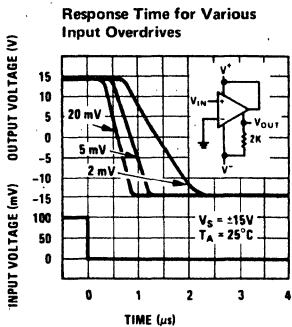
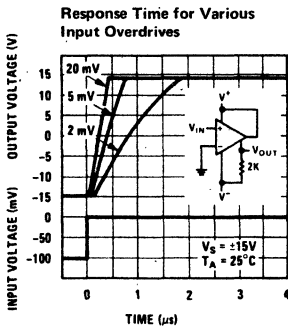
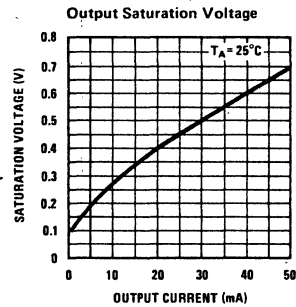
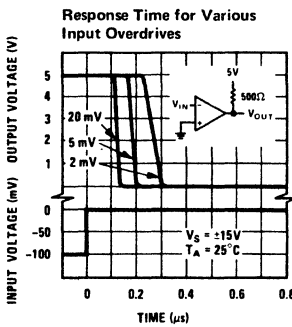
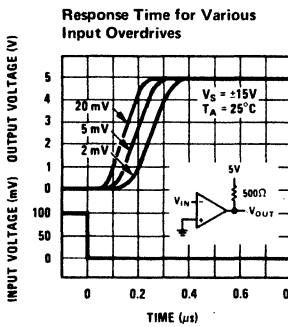
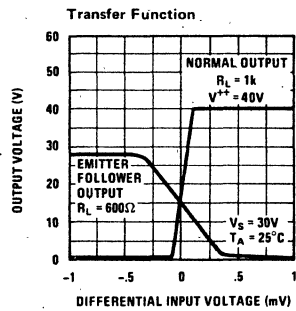
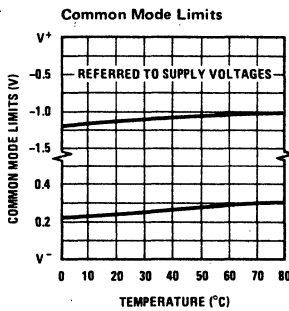
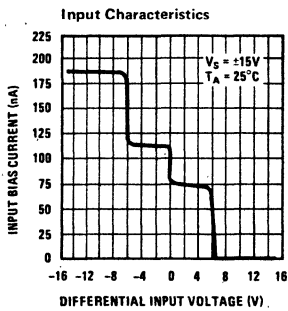
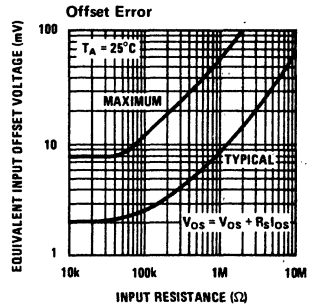
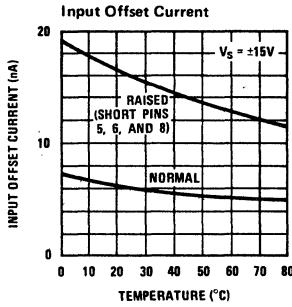
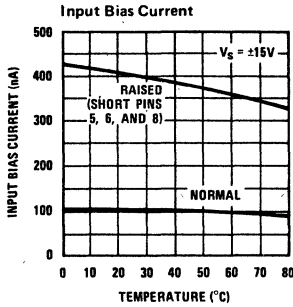
Note 3: These specifications apply for $V_S = \pm 15V$ and the Ground pin at ground, and $0^{\circ}C < T_A < +70^{\circ}C$, unless otherwise specified. The offset voltage, offset current and bias current specifications apply for any supply voltage from a single 5V supply up to $\pm 15V$ supplies.

Note 4: The offset voltages and offset currents given are the maximum values required to drive the output within a volt of either supply with 1 mA load. Thus, these parameters define an error band and take into account the worst-case effects of voltage gain and input impedance.

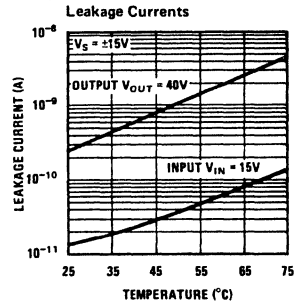
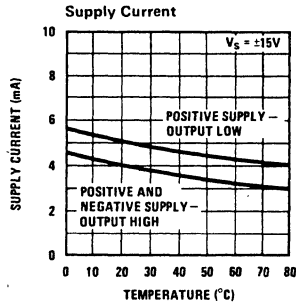
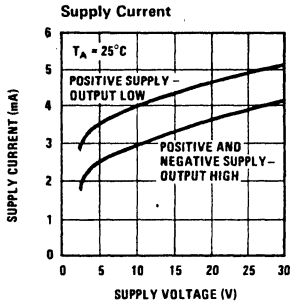
Note 5: The response time specified (see definitions) is for a 100 mV input step with 5 mV overdrive.

Note 6: Do not short the strobe pin to ground; it should be current driven at 3 to 5 mA.

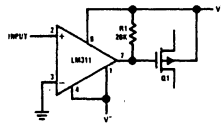
Typical Performance Characteristics



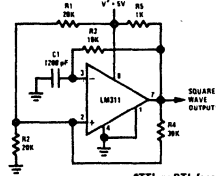
Typical Performance Characteristics (Continued)



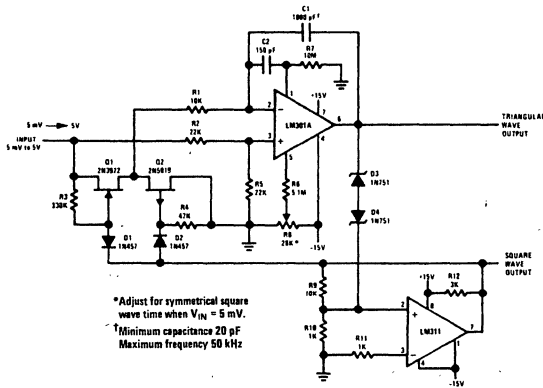
Typical Applications



Zero Crossing Detector
Driving MOS Switch

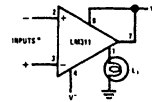


100 kHz Free Running Multivibrator
**TTL or DTL fanout of two.*



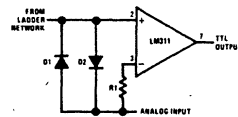
* Adjust for symmetrical square wave time when $V_{IN} = 5\text{ mV}$.
* Minimum capacitance 20 pF
* Maximum frequency 50 kHz

10 Hz to 10 kHz Voltage Controlled Oscillator

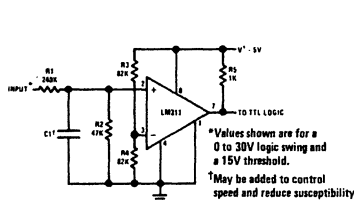


* Input polarity is reversed when using pin 1 as output.

Driving Ground-Referred Load

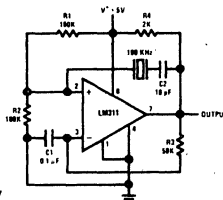


Using Clamp Diodes to Improve Response

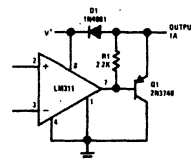


* Values shown are for a 0 to 30V logic swing and a 15V threshold.
* May be added to control speed and reduce susceptibility to noise spikes.

TTL Interface with High Level Logic

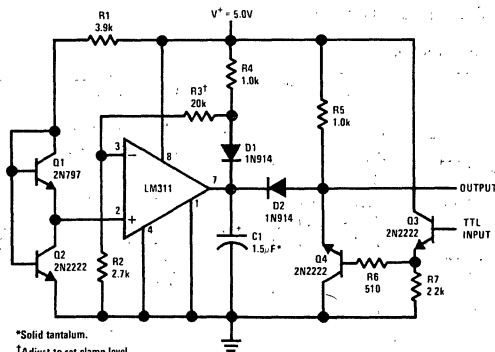


Crystal Oscillator



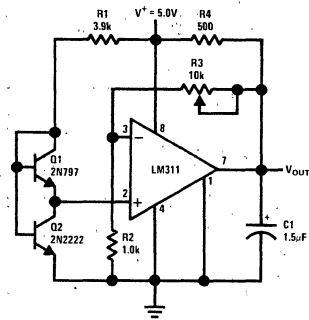
Comparator and Solenoid Driver

Typical Applications (Continued)

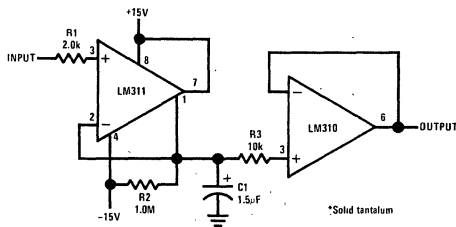


*Solid tantalum.
†Adjust to set clamp level.

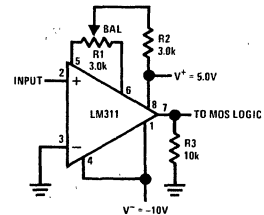
Precision Squarer



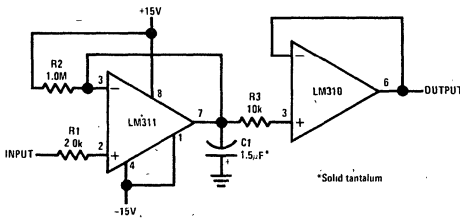
*Solid tantalum
Low Voltage Adjustable Reference Supply



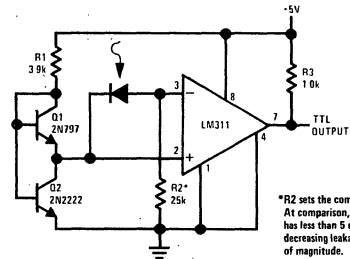
Positive Peak Detector



Zero Crossing Detector driving MOS logic

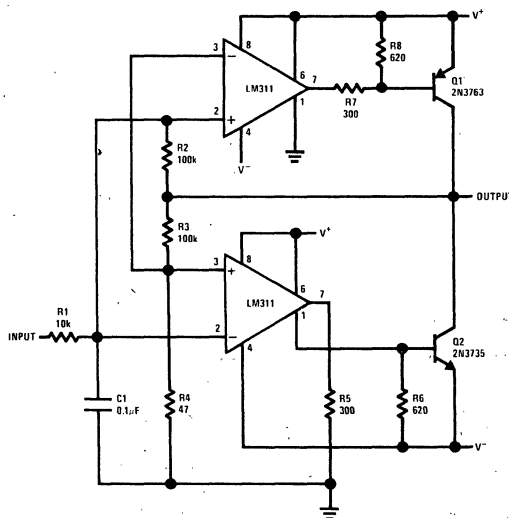


Negative Peak Detector

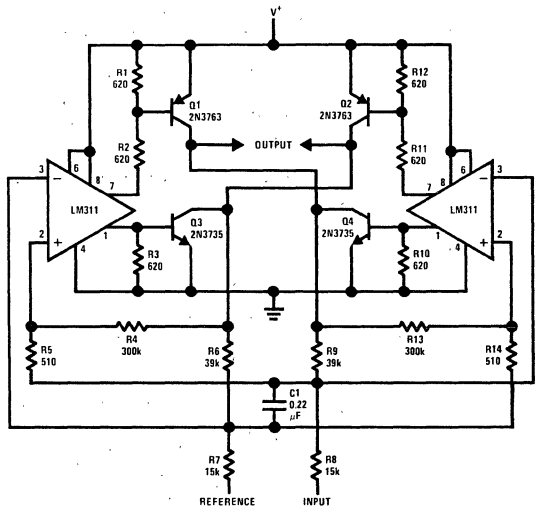


*R2 sets the comparison level. At comparison, the photodiode has less than 5 mV across it, decreasing leakages by an order of magnitude.

Precision Photodiode Comparator

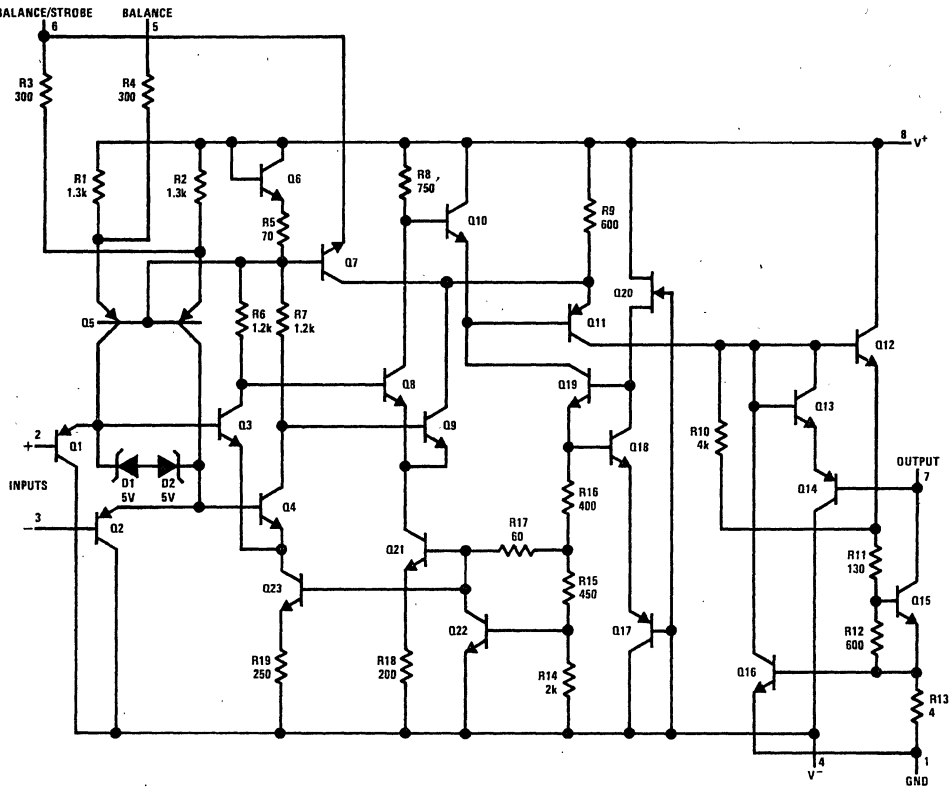


Switching Power Amplifier



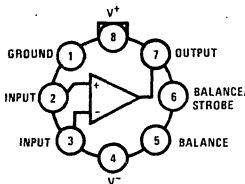
Switching Power Amplifier

Schematic Diagram



Connection Diagrams *

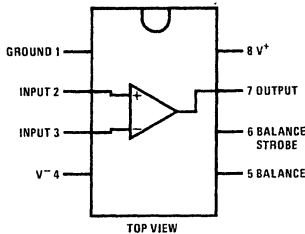
Metal Can Package



Order Number LM311H
See NS Package H08C

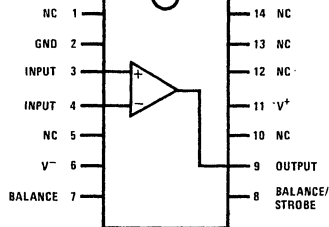
NOTE: Pin 4 connected to case.
TOP VIEW

Dual-In-Line Package



Order Number LM311N
See NS Package N08B
Order Number LM311J-8
See NS Package J08A

Dual-In-Line Package



Order Number LM311N-14
See NS Package N14A
Order Number LM311J
See NS Package J14A

Note: Pin 6 connected to bottom of package.

*Pin connections shown on schematic diagram and typical applications are for TO-5 package.

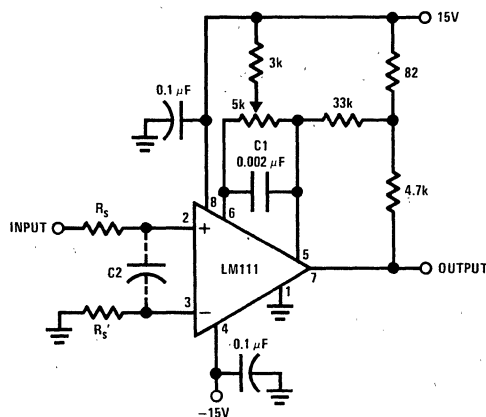
Application Hints

CIRCUIT TECHNIQUES FOR AVOIDING OSCILLATIONS IN COMPARATOR APPLICATIONS

When a high-speed comparator such as the LM111 is used with fast input signals and low source impedances, the output response will normally be fast and stable, assuming that the power supplies have been bypassed (with $0.1 \mu\text{F}$ disc capacitors), and that the output signal is routed well away from the inputs (pins 2 and 3) and also away from pins 5 and 6.

However, when the input signal is a voltage ramp or a slow sine wave, or if the signal source impedance is high ($1 \text{ k}\Omega$ to $100 \text{ k}\Omega$), the comparator may burst into oscillation near the crossing-point. This is due to the high gain and wide bandwidth of comparators like the LM111. To avoid oscillation or instability in such a usage, several precautions are recommended, as shown in *Figure 1* below.

1. The trim pins (pins 5 and 6) act as unwanted auxiliary inputs. If these pins are not connected to a trim-pot, they should be shorted together. If they are connected to a trim-pot, a $0.01 \mu\text{A}$ capacitor C1 between pins 5 and 6 will minimize the susceptibility to AC coupling. A smaller capacitor is used if pin 5 is used for positive feedback as in *Figure 1*.
2. Certain sources will produce a cleaner comparator output waveform if a 100 pF to 1000 pF capacitor C2 is connected directly across the input pins.
3. When the signal source is applied through a resistive network, R_s , it is usually advantageous to choose an R_s' of substantially the same value, both for DC and for dynamic (AC) considerations. Carbon, tin-oxide, and metal-film resistors have all been used successfully in comparator input circuitry. Inductive wirewound resistors are not suitable.
4. When comparator circuits use input resistors (eg. summing resistors), their value and placement are particularly important. In all cases the body of the resistor should be close to the device or socket. In other words there should be very little lead length or printed-circuit foil run between comparator and resistor to radiate or pick up signals. The same applies to capacitors, pots, etc. For example, if $R_s = 10 \text{ k}\Omega$, as little as 5 inches of lead between the resistors and the input pins can result in oscillations that are very hard to damp. Twisting these input leads tightly is the only (second best) alternative to placing resistors close to the comparator.
5. Since feedback to almost any pin of a comparator can result in oscillation, the printed-circuit layout should be engineered thoughtfully. Preferably there should be a groundplane under the LM111 circuitry, for example, one side of a double-layer circuit card. Ground foil (or, positive supply or negative supply foil) should extend between the output and the inputs, to act as a guard. The foil connections for the inputs should be as small and compact as possible, and should be essentially surrounded by ground foil on all sides, to guard against capacitive coupling from any high-level signals (such as the output). If pins 5 and 6 are not used, they should be shorted together. If they are connected to a trim-pot, the trim-pot should be located, at most, a few inches away from the LM111, and the $0.01 \mu\text{F}$ capacitor should be installed. If this capacitor cannot be used, a shielding printed-circuit foil may be advisable between pins 6 and 7. The power supply bypass capacitors should be located within a couple inches of the LM111. (Some other comparators require the power-supply bypass to be located immediately adjacent to the comparator.)



Pin connections shown are for LM111H in 8-lead TO-5 hermetic package

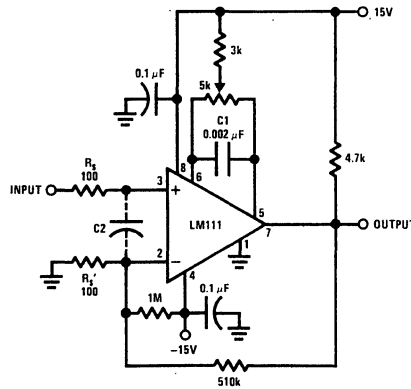
FIGURE 1. Improved Positive Feedback

Application Hints (Continued)

6. It is a standard procedure to use hysteresis (positive feedback) around a comparator, to prevent oscillation, and to avoid excessive noise on the output because the comparator is a good amplifier for its own noise. In the circuit of *Figure 2*, the feedback from the output to the positive input will cause about 3 mV of hysteresis. However, if R_S is larger than 100Ω , such as $50\text{ k}\Omega$, it would not be reasonable to simply increase the value of the positive feedback resistor above $510\text{ k}\Omega$. The circuit of *Figure 3* could be used, but it is rather awkward. See the notes in paragraph 7 below.
7. When both inputs of the LM111 are connected to active signals, or if a high-impedance signal is driving the positive input of the LM111 so that positive feedback would be disruptive, the circuit of *Figure 1* is

ideal. The positive feedback is to pin 5 (one of the offset adjustment pins). It is sufficient to cause 1 to 2 mV hysteresis and sharp transitions with input triangle waves from a few Hz to hundreds of kHz. The positive-feedback signal across the 82Ω resistor swings 240 mV below the positive supply. This signal is centered around the nominal voltage at pin 5, so this feedback does not add to the V_{OS} of the comparator. As much as 8 mV of V_{OS} can be trimmed out, using the $5\text{ k}\Omega$ pot and $3\text{ k}\Omega$ resistor as shown.

8. These application notes apply specifically to the LM111, LM211, LM311, and LF111 families of comparators, and are applicable to all high-speed comparators in general, (with the exception that not all comparators have trim pins).



Pin connections shown are for LM111H in 8-lead TO-5 hermetic package

FIGURE 2. Conventional Positive Feedback

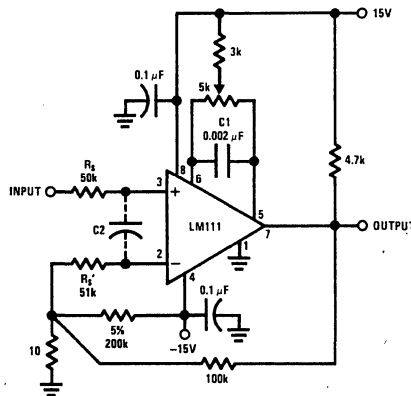


FIGURE 3. Positive Feedback With High Source Resistance



Voltage Comparators

LM710/LM710C Voltage Comparator

General Description

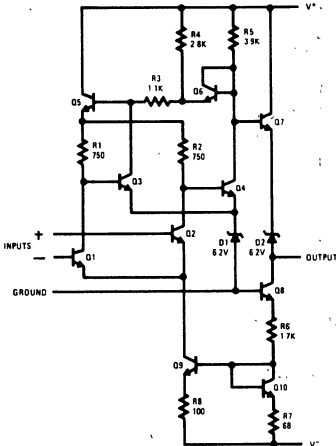
The LM710 series are a high-speed voltage comparators intended for use as an accurate, low-level digital level sensor or as a replacement for operational amplifiers in comparator applications where speed is of prime importance. The circuit has a differential input and a single-ended output, with saturated output levels compatible with practically all types of integrated logic.

The device is built on a single silicon chip which insures low offset and thermal drift. The use of a minimum number of stages along with minority-carrier lifetime control (gold doping) makes the circuit much faster than operational amplifiers in saturating comparator applications. In fact, the low

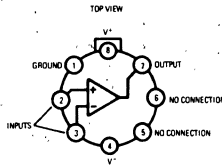
stray and wiring capacitances that can be realized with monolithic construction make the device difficult to duplicate with discrete components operating at equivalent power levels.

The LM710 series are useful as pulse height discriminators, voltage comparators in high-speed A/D converters or go, no-go detectors in automatic test equipment. They also have applications in digital systems as an adjustable-threshold line receiver or an interface between logic types. In addition, the low cost of the units suggests it for applications replacing relatively simple discrete component circuitry.

Schematic* and Connection Diagrams



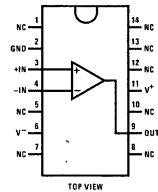
Metal Can Package



Note: Pin 4 connected to case.

Order Number LM710H
or LM710CH
See NS Package H08C

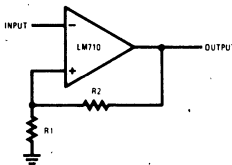
Dual-In-Line Package



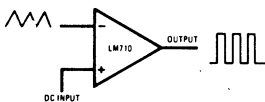
Order Number LM710N
or LM710CN
See NS Package N14A

Typical Applications*

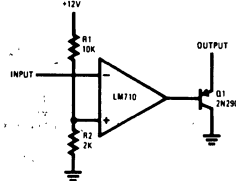
Schmitt Trigger



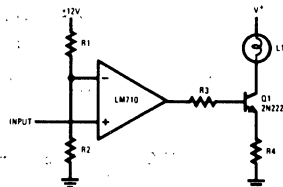
Pulse Width Modulator



Line Receive With Increased Output Sink Current



Level Detector With Lamp Driver



*Pin connections shown are for metal can.

Absolute Maximum Ratings

| | | | | |
|-------------------------------|------------|--|-----------|-----------|
| Positive Supply Voltage | +14V | Operating Temperature Range | T_{MIN} | T_{MAX} |
| Negative Supply Voltage | -7V | LM710 | -55°C | to +125°C |
| Peak Output Current | 10 mA | LM710C | 0°C | to +70°C |
| Output Short Circuit Duration | 10 seconds | Storage Temperature Range | -65°C | to +150°C |
| Differential Input Voltage | ±5V | Lead Temperature (Soldering, 60 seconds) | 300°C | |
| Input Voltage | ±7V | | | |
| Power Dissipation | | | | |
| TO-99, (Note 1) | 300 mW | | | |
| Flat Package, (Note 2) | 200 mW | | | |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LM710 | | | LM710C | | | UNITS |
|---|---|-------|------|-----|--------|------|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{CM} = 0V$, $T_A = 25^\circ C$ | | 0.6 | 2.0 | | 1.6 | 5.0 | mV |
| Input Offset Current | $V_{OUT} = 1.4V$, $T_A = 25^\circ C$ | | 0.75 | 3.0 | | 1.8 | 5.0 | μA |
| Input Bias Current | $T_A = 25^\circ C$ | | 13 | 20 | | 16 | 25 | μA |
| Voltage Gain | $T_A = 25^\circ C$ | 1250 | 1700 | | 1000 | 1500 | | |
| Output Resistance | $T_A = 25^\circ C$ | | 200 | | | 200 | | Ω |
| Output Sink Current | $V_{OUT} = 0$, $T_A = 25^\circ C$ | | | | | | | |
| | $\Delta V_{IN} \geq 5\text{ mV}$ | 2.0 | 2.5 | | | | | mA |
| | $\Delta V_{IN} \geq 10\text{ mV}$ | | | | 1.6 | 2.5 | | mA |
| Response Time | $T_A = 25^\circ C$, (Note 4) | | 40 | | | 40 | | ns |
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{CM} = 0V$ | | | 3.0 | | | 6.5 | mV |
| Average Temperature Coefficient of Input Offset Voltage | $T_{MIN} \leq T_A \leq T_{MAX}$ $R_S \leq 50\Omega$ | | 3.0 | 10 | | 5.0 | 20 | $\mu V/^\circ C$ |
| Input Offset Current | $T_A = T_{A\text{ MAX}}$ | | 0.25 | 3.0 | | | 7.5 | μA |
| | $T_A = T_{A\text{ MIN}}$ | | 1.8 | 7.0 | | | 7.5 | μA |
| Average Temperature Coefficient of Input Offset Current | $25^\circ C \leq T_A \leq T_{MAX}$ | | 5.0 | 25 | | 15 | 50 | $nA/^\circ C$ |
| | $T_{MIN} \leq T_A \leq 25^\circ C$ | | 15 | 75 | | 24 | 100 | $nA/^\circ C$ |
| Input Bias Current | $T_A = T_{MIN}$ | | 27 | 45 | | 25 | 40 | μA |
| Input Voltage Range | $V^- = -7V$ | ±5.0 | | | ±5.0 | | | V |
| Common-Mode Rejection Ratio | $R_S \leq 200\Omega$ | 80 | 100 | | 70 | 98 | | dB |
| Differential Input Voltage Range | | ±5.0 | | | ±5.0 | | | V |
| Voltage Gain | | 1000 | | | 800 | | | V/V |
| Positive Output Level | $-5\text{ mA} \leq I_{OUT} \leq 0$ $V_{IN} \geq 5\text{ mV}$ $V_{IN} \geq 10\text{ mV}$ | 2.5 | 3.2 | 4.0 | | | | V |
| | | | | | 2.5 | 3.2 | 4.0 | V |
| Negative Output Level | $V_{IN} \geq 5\text{ mV}$ $V_{IN} \geq 10\text{ mV}$ | -1.0 | -0.5 | 0 | | | | V |
| | | | | | -1.0 | -0.5 | 0 | V |
| Output Sink Current | $V_{IN} \geq 5\text{ mV}$, $V_{OUT} = 0$ $T_A = 125^\circ C$ $T_A = -55^\circ C$ | 0.5 | 1.7 | | | | | mA |
| | | 1.0 | 2.3 | | | | | mA |
| | $V_{IN} \geq 10\text{ mV}$, $V_{OUT} = 0$ $0^\circ C \leq T_A \leq +70^\circ C$ | | | | 0.5 | | | mA |
| Positive Supply Current | $V_{IN} \geq 5\text{ mV}$ $V_{IN} \geq 10\text{ mV}$ | | 5.2 | 9.0 | | | | mA |
| | | | | | 5.2 | 9.0 | | mA |
| Negative Supply Current | $V_{IN} \geq 5\text{ mV}$ $V_{IN} \geq 10\text{ mV}$ | | 4.6 | 7.0 | | | | mA |
| | | | | | 4.6 | 7.0 | | mA |
| Power Consumption | $I_{OUT} = 0$ $V_{IN} \geq 5\text{ mV}$ $V_{IN} \geq 10\text{ mV}$ | | 90 | 150 | | | | mW |
| | | | | | | | 150 | mW |

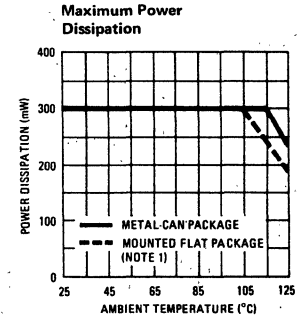
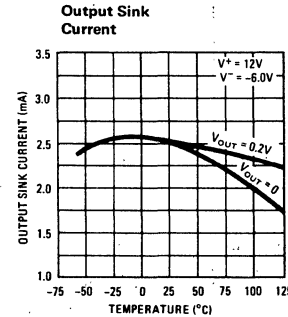
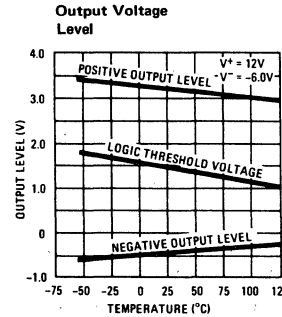
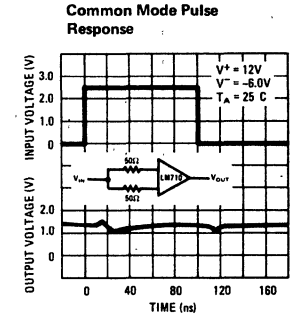
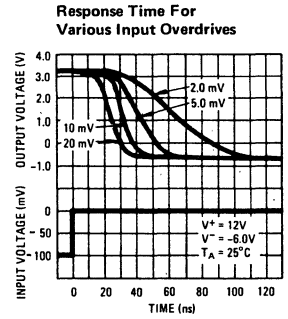
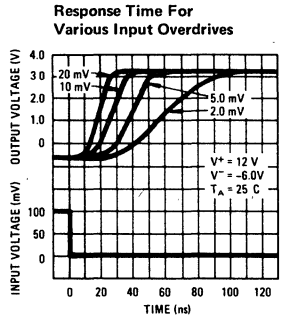
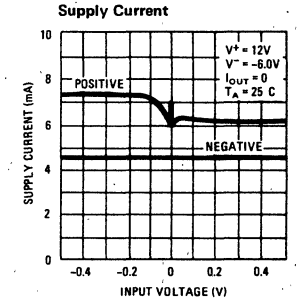
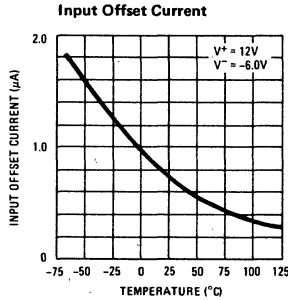
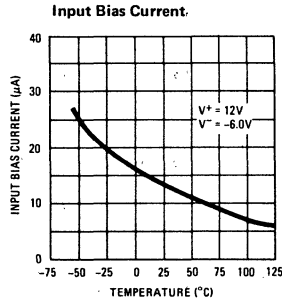
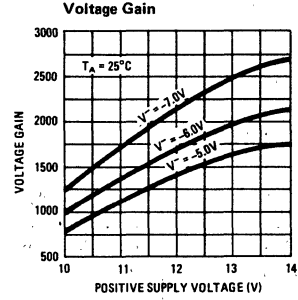
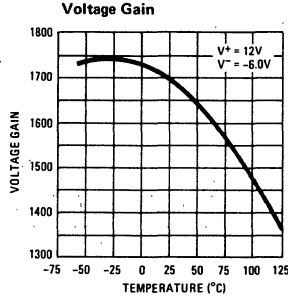
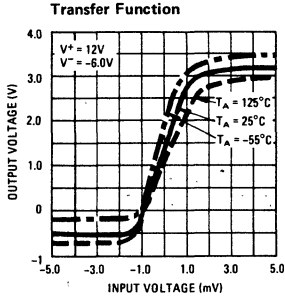
Note 1: Rating applies for case temperatures to 125°C for LM710 and to 70°C for LM710C; derate linearly at 5.6 mW/°C for ambient temperatures above 105°C.

Note 2: Derate linearly at 4.4 mW/°C for ambient temperatures above 100°C.

Note 3: These specifications apply for $V^+ = 12V$, $V^- = -6V$, $-55^\circ C \leq T_A \leq +125^\circ C$ for LM710 and $0^\circ C \leq T_A \leq +70^\circ C$ for LM710C unless otherwise specified. The input offset voltage and input offset current (see definitions) are specified for a logic threshold voltage of 1.8V at -55°C, 1.4V at 25°C, and 1V at 125°C for LM710 and 1.5V at 0°C, 1.4V at 25°C and 1.2V at 70°C for LM710C.

Note 4: The response time specified (see definitions) is a 100 mV input step with 5 mV overdrive (LM710) or a 10 mV overdrive (LM710C).

Typical Performance Characteristics



LM711/LM711C Dual Comparator

General Description

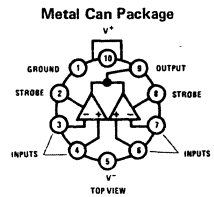
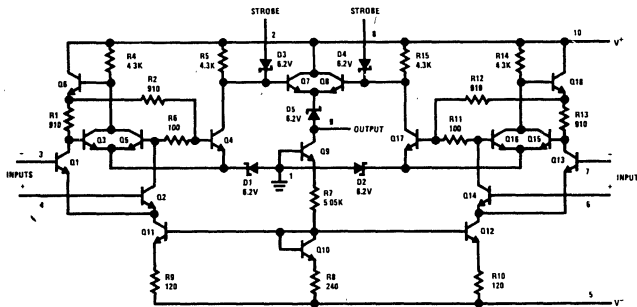
The LM711 series contains two voltage comparators with separate differential inputs, a common output and provision for strobing each side independently. Similar to the LM710, the device features low offset and thermal drift, a large input voltage range, low power consumption, fast recovery from large overloads and compatibility with most integrated logic circuits.

With the addition of an external resistor network, the LM711 series can be used as a sense amplifier for core memories. The input thresholding, combined with the high gain of the comparator, eliminates many of the inaccuracies encountered

with conventional sense amplifier designs. Further, it has the speed and accuracy needed for reliably detecting the outputs of cores as small as 20 mils.

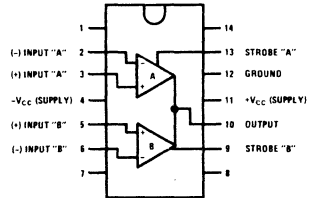
The LM711 series are also useful in other applications where a dual comparator with OR'ed outputs is required, such as a double-ended limit detector. By using common circuitry for both halves, the device can provide high speed with lower power dissipation than two single comparators. The LM711C is the commercial/industrial version of the LM711. With operation specified over a 0°C to +70°C temperature range.

Schematic ** and Connection Diagrams



Order Number LM711H or LM711CH
See NS Package H10C

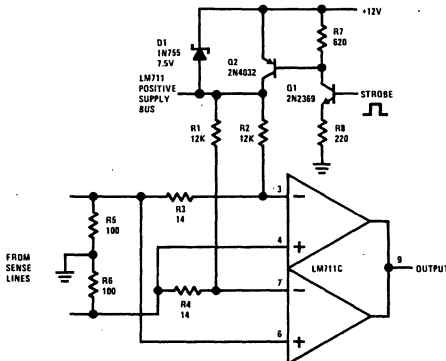
Dual-In-Line Package



Order Number LM711CN
See NS Package N14A

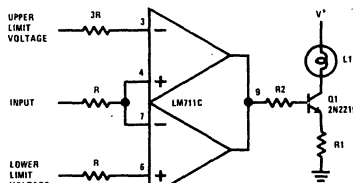
Typical Applications **

Sense Amplifier With Supply Strobing for Reduced Power Consumption*



*Standby dissipation is about 40 mW.

Double-Ended Limit Detector With Lamp Driver



**Pin connections shown are for metal can.

Absolute Maximum Ratings

| | | | |
|-------------------------------------|----------|--|---------------------|
| Positive Supply Voltage | +14V | Operating Temperature Range | T_{MIN} T_{MAX} |
| Negative Supply Voltage | -7V | LM711 | -55°C to +125°C |
| Peak Output Current | 25 mA | LM711C | 0°C to +70°C |
| Differential Input Voltage | ±5V | Storage Temperature Range | -65°C to +150°C |
| Input Voltage | ±7V | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Strobe Voltage | 0 to +6V | | |
| Internal Power Dissipation (Note 1) | 300 mW | | |

Electrical Characteristics (These specifications apply for $T_A = 25^\circ\text{C}$, $V^+ = 12\text{V}$, $V^- = -6\text{V}$)

| PARAMETER | CONDITIONS (Note 2) | LM711 | | | LM711C | | | UNITS |
|----------------------------------|---|-------|------|------|--------|------|-----|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{CM} = 0$ | | 1.0 | 3.5 | | 1.0 | 5.0 | mV |
| | $R_S \leq 200\Omega$, $-5\text{V} \leq V_{CM} \leq +5\text{V}$ | | 1.0 | 5.0 | | 1.0 | 7.5 | mV |
| Input Offset Current | | | 0.5 | 10.0 | | 0.5 | 15 | μA |
| Input Bias Current | | | 25 | 75 | | 25 | 100 | μA |
| Voltage Gain | | 750 | 1500 | | 700 | 1500 | | |
| Response Time (Note 3) | | | 40 | | | 40 | | ns |
| Strobe Release Time | | | 12 | | | 12 | | ns |
| Input Voltage Range | $V^- = 7\text{V}$ | ±5.0 | | | ±5.0 | | | V |
| Differential Input Voltage Range | | ±5.0 | | | ±5.0 | | | V |
| Output Resistance | | | 200 | | | 200 | | Ω |
| Positive Output Level | $V_{IN} \geq 10\text{ mV}$ | | 4.5 | 5.0 | | 4.5 | 5.0 | V |
| Loaded Positive Output Level | $V_{IN} \geq 10\text{ mV}$, $I_{OUT} = -5\text{ mA}$ | 2.5 | 3.5 | | 2.5 | 3.5 | | V |
| Negative Output Level | $V_{IN} \leq -10\text{ mV}$ | -1.0 | | 0 | -1.0 | -0.5 | 0 | V |
| Strobed Output Level | $V_{STROBE} \leq 0.3\text{V}$ | -1.0 | | 0 | -1.0 | | 0 | V |
| Output Sink Current | $V_{IN} \leq -10\text{ mV}$, $V_{OUT} \geq 0$ | 0.5 | 0.8 | | 0.5 | 0.8 | | mA |
| Strobe Current | $V_{STROBE} = 100\text{ mV}$ | | 1.2 | 2.5 | | 1.2 | 2.5 | mA |
| Positive Supply Current | $V_{IN} \leq -10\text{ mV}$ | | 8.6 | | | 8.6 | | mA |
| Negative Supply Current | | | 3.9 | | | 3.9 | | mA |
| Power Consumption | | | 130 | 200 | | 130 | 230 | mW |

The following specifications apply for $T_{MIN} \leq T_A \leq T_{MAX}$:

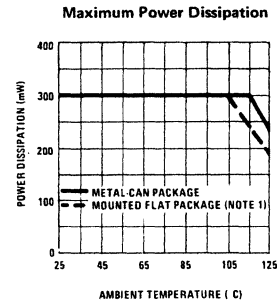
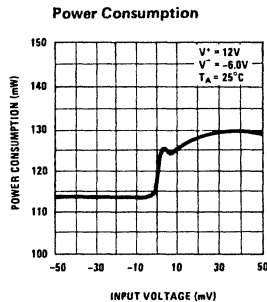
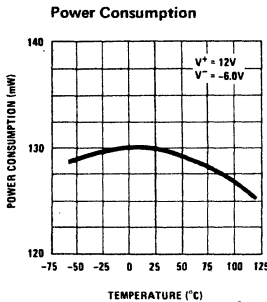
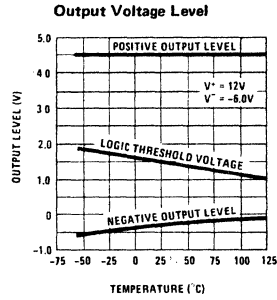
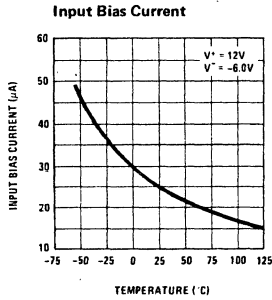
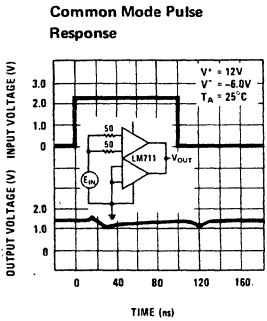
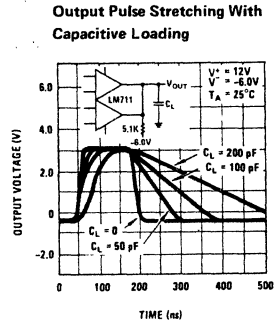
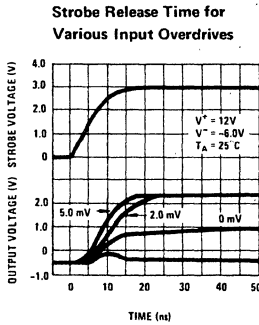
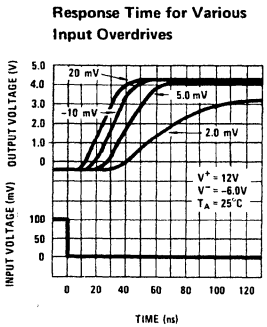
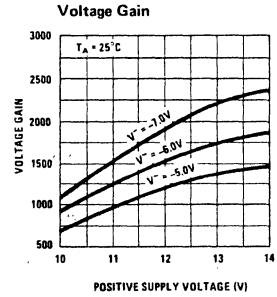
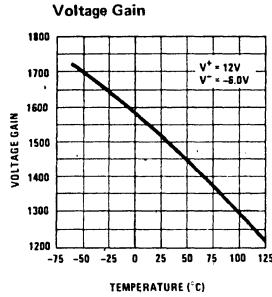
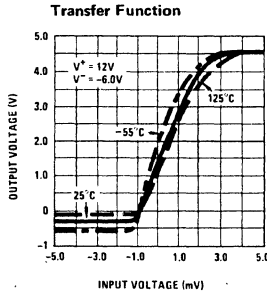
| | | | | | | |
|---|-------------------------------------|-----|-----|--|-----|------------------------------|
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{CM} = 0$ | | 4.5 | | 6.0 | mV |
| | $R_S \leq 200\Omega$ | | 6.0 | | 10 | mV |
| Input Offset Current | | | 20 | | 25 | μA |
| Input Bias Current | | | 150 | | 150 | μA |
| Average Temperature Coefficient of Input Offset Voltage | | | 5.0 | | 5.0 | $\mu\text{V}/^\circ\text{C}$ |
| Voltage Gain | | 500 | | | 500 | |

Note 1: Rating applies for case temperatures to 125°C; derate linearly at 5.6 mW/°C for ambient temperatures above 105°C.

Note 2: The input offset voltage and input offset current (see definitions) are specified for a logic threshold voltage of 1.8V at -55°C, 1.4V at 25°C, and 1V at 125°C.

Note 3: The response time specified is for a 100 mV input step with 5 mV overdrive (see definitions).

Typical Performance Characteristics



LM1514/LM1414 Dual Differential Voltage Comparator

General Description

The LM1514/LM1414 is a dual differential voltage comparator intended for applications requiring high accuracy and fast response times. The device is constructed on a single monolithic silicon chip.

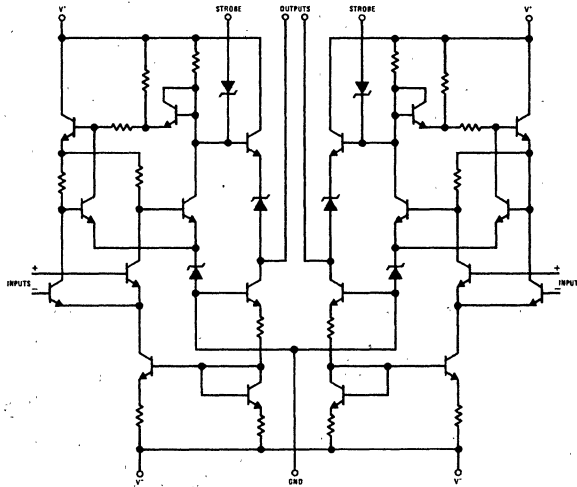
The LM1514/LM1414 is useful as a variable threshold Schmitt trigger, a pulse height discriminator, a voltage comparator in high-speed A-D converters, a memory sense amplifier or a high noise immunity line receiver. The output of the comparator is compatible with all integrated logic forms. The LM1514/LM1414 meet or exceed the specifications for the MC1514/MC1414 and are pin-for-pin replacements. The LM1514 is available in the ceramic dual-in-line package. The LM1414 is available in either the ceramic or molded dual-in-line package.

The LM1514 is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LM1414 is specified for operation over the 0°C to $+70^{\circ}\text{C}$ temperature range.

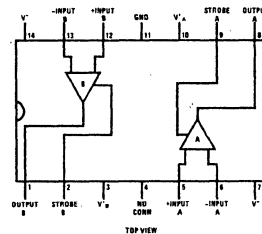
Features

- Two totally separate comparators per package
- Independent strobe capability
- High speed 30 ns typ
- Low input offset voltage and current
- High output sink current over temperature
- Output compatible with TTL/DTL logic
- Molded or ceramic dual-in-line package

Schematic and Connection Diagrams



Dual-In-Line Package



Order Number LM1414J or LM1514J
See NS Package J14A
Order Number LM1414N
See NS Package N14A

Absolute Maximum Ratings (Note 1)

| | |
|--|------------------------|
| Positive Supply Voltage | +14.0V |
| Negative Supply Voltage | -7.0V |
| Peak Output Current | 10 mA |
| Differential Input Voltage | ±5.0V |
| Input Voltage | ±7.0V |
| Power Dissipation (Note 2) | 600 mW |
| Operating Temperature Range | LM1514 -55°C to +125°C |
| | LM1414 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics for $T_A = 25^\circ\text{C}$, $V^+ = +12\text{V}$, $V^- = -6\text{V}$, unless otherwise specified

| PARAMETER | CONDITIONS | LM1514 | | | LM1414 | | | UNITS |
|----------------------------------|---|--------|------|------|--------|------|------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{CM} = 0\text{V}$, $V_{OUT} = 1.4\text{V}$ | | 0.6 | 2.0 | | 1.0 | 5.0 | mV |
| Input Offset Current | $V_{CM} = 0\text{V}$, $V_{OUT} = 1.4\text{V}$ | | 0.8 | 3.0 | | 1.2 | 5.0 | μA |
| Input Bias Current | | | | 20 | | | 25 | μA |
| Voltage Gain | | 1250 | | | 1000 | | | |
| Output Resistance | | | 200 | | | 200 | | Ω |
| Differential Input Voltage Range | | ±5.0 | | | ±5.0 | | | V |
| Input Voltage Range | $V^- = -7.0\text{V}$ | ±5.0 | | | ±5.0 | | | V |
| Common Mode Rejection Ratio | $R_S \leq 200\Omega$, $V^- = -7.0\text{V}$ | 80 | 100 | | 70 | 100 | | dB |
| Positive Output Voltage | $V_{IN} \geq 7.0\text{ mV}$, $0 \leq I_{OUT} \leq -5.0\text{ mA}$ | 2.5 | 3.2 | 4.0 | 2.5 | 3.2 | 4.0 | V |
| Negative Output Voltage | $V_{IN} \leq -7.0\text{ mV}$ | -1.0 | -0.5 | 0 | -1.0 | -0.5 | 0 | V |
| Strobed Output Voltage | $V_{STROBE} \leq 0.3\text{V}$ | -1.0 | -0.5 | 0 | -1.0 | -0.5 | 0 | V |
| Strobe "0" Current | $V_{STROBE} = 100\text{ mV}$ | | -1.2 | -2.5 | | -1.2 | -2.5 | mA |
| Positive Supply Current | $V_{IN} \leq -7\text{ mV}$ | | | 18 | | | 18 | mA |
| Negative Supply Current | $V_{IN} \leq -7\text{ mV}$ | | | -14 | | | -14 | mA |
| Power Consumption | | | 180 | 300 | | 180 | 300 | mW |
| Response Time | (Note 3) | | 30 | | | 30 | | ns |

LM1514/LM1414: The following apply for $T_L \leq T_A < T_H$ (Note 4) unless otherwise specified

| | | | | | | | | |
|--|--|------|-----|------------|-----|-----|------------|---|
| Input Offset Voltage | $R_S \leq 200\Omega$, $V_{OUT} = 1.8\text{V}$ for $T_A = T_L$ $V_{CM} = 0\text{V}$, $V_{OUT} = 1.0\text{V}$ for $T_A = T_H$ | | | 3.0 3.0 | | | 6.5 6.5 | mV mV |
| Input Bias Current Temperature Coefficient of Input Offset Voltage | | | 3.0 | 45 | | 5.0 | 40 | μA $\mu\text{V}/^\circ\text{C}$ |
| Input Offset Current | $V_{CM} = 0\text{V}$, $V_{OUT} = 1.8\text{V}$, $T_A = T_L$ $V_{CM} = 0\text{V}$, $V_{OUT} = 1.0\text{V}$, $T_A = T_H$ | | | 7.0 3.0 | | | 7.5 7.5 | μA μA |
| Voltage Gain | | 1000 | | | 800 | | | |
| Output Sink Current | $V_{IN} \leq -9.0\text{ mV}$, $V_{OUT} \geq 0\text{V}$ | 2.8 | 4.0 | | 1.6 | 2.5 | | mA |

Note 1: Voltage values are with respect to network ground terminal. Positive current is defined as current into the referenced pin.**Note 2:** LM1514 ceramic package: The maximum junction temperature is +150°C, for operating at elevated temperatures, devices must be derated linearly at 12.5 mW/°C. LM1414 ceramic package: The maximum junction temperature is +95°C for operating at elevated temperatures, devices must be derated linearly at 12.5 mW/°C. LM1414 molded package: The maximum junction temperature is +115°C, for operating at elevated temperatures, devices must be derated linearly at 6.7 mW/°C.**Note 3:** The response time specified (see definitions) for a 100 mV input step with 5 mV overdrive.**Note 4:** For LM1514, $T_L = -55^\circ\text{C}$, $T_H = +125^\circ\text{C}$. For LM1414, $T_L = 0^\circ\text{C}$, $T_H = +70^\circ\text{C}$.



Section 6

Analog Switches





Section Contents

| | |
|--|-------|
| Analog Switches/Multiplexers Selection Guide..... | 6-iii |
| Hybrid Analog Switch Selection Guide..... | 6-iv |
| Definition of Terms..... | 6-iv |
| LF11331/LF13331 4 Normally Open Switches With Disable..... | 6-1 |
| LF11332/LF13332 4 Normally Closed Switches With Disable..... | 6-1 |
| LF11333/LF13333 2 Normally Closed Switches and 2 Normally Open Switches With Disable..... | 6-1 |
| LF11201/LF13201 4 Normally Closed Switches..... | 6-1 |
| LF11202/LF13202 4 Normally Open Switches..... | 6-1 |
| LF11508/LF13508 8-Channel Analog Multiplexer..... | 6-11 |
| LF11509/LF13509 4-Channel Differential Analog Multiplexer..... | 6-11 |

Note. For additional information on analog switches, see National Semiconductor's Special Functions Databook and FET Databook.

| RON (Ω) | V _A /I (V) | PART NUMBER | LOGIC INPUT | V _S (V) TYP | t _{ON} /t _{OFF} TYP | RON (Ω) | V _A /I (V) | PART NUMBER | LOGIC INPUT | V _S (V) TYP | t _{ON} /t _{OFF} TYP | RON (Ω) | V _A /I (V) | PART NUMBER | LOGIC INPUT | V _S (V) TYP | t _{ON} /t _{OFF} TYP |
|---------------------|--------------------------|----------------|----------------|------------------------------|--|---------------------|--------------------------|----------------|----------------|------------------------------|--|-------------------------------|--------------------------|--------------------------|----------------|------------------------------|--|
| Dual SPST | | | | | | SPDT | | | | | | MULTIPLEXERS | | | | | |
| 10 | ±10 | AH0141/DG141 | TTL | -18, 12 | 0.8/1.1 μ s | 10 | ±10 | AH0146/DG146 | TTL | -18, 12 | 0.8/1.1 μ s | 3-Channel | | | | | |
| 30 | ±10 | AH0133/DG133 | TTL | -18, 12 | 0.5/0.9 μ s | 30 | ±10 | AH0144/DG144 | TTL | -18, 12 | 0.5/0.9 μ s | *100 | 15 mA | AH5013 | 15V TTL | 150/300 ns | |
| 80 | ±10 | AH0134/DG134 | TTL | -18, 12 | 0.5/0.9 μ s | 80 | ±10 | AH0143/DG143 | TTL | -18, 12 | 0.5/0.9 μ s | *150 | 5 mA | AH5014 | TTL | 150/300 ns | |
| 15 | ±7.5 | AH0151/DG151 | TTL | ±15 | 0.8/1.1 μ s | 15 | ±7.5 | AH0161/DG161 | TTL | ±15 | 0.8/1.1 μ s | 4-Channel | | | | | |
| 50 | ±7.5 | AH0152/DG152 | TTL | ±15 | 0.5/0.9 μ s | 50 | ±7.5 | AH0162/DG162 | TTL | ±15 | 0.5/0.9 μ s | *100 | 15 mA | AH5009/AM9709 | 15V TTL | 150/300 ns | |
| *30 | ±7.5 | AM181/DG181 | TTL | ±15, 5 | 180/150 ns | 100 | ±9 | AH2114 (Sw. 1) | 15V TTL | ±15 | 35/600 ns | *100 | 10 mA | AM97C09 | CMOS | 150/300 ns | |
| *75 | ±10 | AM182/DG182 | TTL | ±15, 5 | 300/150 ns | *30 | ±7.5 | AM187/DG187 | TTL | ±15, 5 | 180/150 ns | *150 | 5 mA | AH5010/AM9710 | TTL | 150/300 ns | |
| Triple SPST | | | | | | Dual SPDT | | | | | | 4-Channel Differential | | | | | |
| *100 | 15 mA | AH5015 | 15V TTL | | 150/300 ns | *30 | ±7.5 | AM190/DG190 | TTL | ±15, 5 | 180/150 ns | 280 | ±7.5 | CD4052 | CMOS | ±7.5 | 150/150 ns |
| *150 | 5 mA | AH5016 | TTL | | 150/300 ns | *75 | ±10 | AM188/DG188 | TTL | ±15, 5 | 300/150 ns | *350 | 12,-15 | LF11509 | TTL | ±15 | 1/0.2 μ s |
| Quad SPST | | | | | | Triple SPDT | | | | | | 270 | | | | | |
| 200-600 | ±10 | AH0015 | TTL | -20, 10, 5 | 100/400 ns | 280 | ±7.5 | CD4053 | CMOS | ±7.5 | 150/150 ns | 270 | | | | | |
| *200 | ±10 | LF11201 | TTL | ±15 | 90/500 ns | Dual DPST | | | | | | 6-Channel | | | | | |
| *200 | ±10 | LF11202 | TTL | ±15 | 90/500 ns | 10 | ±10 | AH0140/DG140 | TTL | -18, 12 | 0.8/1.1 μ s | 250-1500 | 50 mA | AM2009/MM4504/ MM5504 | TTL | -15, 5 | |
| *200 | ±10 | LF11331 | TTL | ±15 | 90/500 ns | 30 | ±10 | AH0129/DG129 | TTL | -18, 12 | 0.5/0.9 μ s | 8-Channel | | | | | |
| *200 | ±10 | LF11332 | TTL | ±15 | 90/500 ns | 80 | ±10 | AH0126/DG126 | TTL | -18, 12 | 0.5/0.9 μ s | 250-400 | ±5 | AM3705 | TTL | -15, 5 | 300/600 ns |
| *250 | ±10 | LF13201 | TTL | ±15 | 90/500 ns | 15 | ±7.5 | AH0153/DG153 | TTL | ±15 | 0.8/1.1 μ s | *350 | 12,-15 | LF11508 | TTL | ±15 | 1/0.2 μ s |
| *250 | ±10 | LF13202 | TTL | ±15 | 90/500 ns | 50 | ±7.5 | AH0154/DG154 | TTL | ±15 | 0.5/0.9 μ s | 270 | ±7.5 | CD4529B | CMOS | ±7.5 | 50/50 ns |
| *250 | ±10 | LF13331 | TTL | ±15 | 90/500 ns | 200-600 | ±10 | AH0019 | TTL | -20, 10, 5 | 100/400 ns | 280 | ±7.5 | CD4501 | CMOS | ±7.5 | 150/150 ns |
| *250 | ±10 | LF13332 | TTL | ±15 | 90/500 ns | *30 | ±7.5 | AM184/DG184 | TTL | ±15, 5 | 180/150 ns | Dual DPST | | | | | |
| *250 | ±10 | LF13333 | TTL | ±15 | 90/500 ns | *75 | ±10 | AM185/DG185 | TTL | ±15, 5 | 300/150 ns | 10 | ±10 | AH0145/DG145 | TTL | -18, 12 | 0.8/1.1 μ s |
| 280 | ±7.5 | CD4066 | CMOS | ±7.5 | | 8-Channel | | | | | | 30 | ±10 | AH0139/DG139 | TTL | -18, 12 | 0.5/0.9 μ s |
| 850 | ±7.5 | CD4016 | CMOS | ±7.5 | | 80 | ±10 | AH0142/DG142 | TTL | -18, 12 | 0.5/0.9 μ s | 15 | ±7.5 | AH0163/DG163 | TTL | ±15 | 0.8/1.1 μ s |
| *100 | 15 mA | AH5011/AM9711 | 15V TTL | | 150/300 ns | 50 | ±7.5 | AH0164/DG164 | TTL | ±15 | 0.5/0.9 μ s | 200-600 | ±10 | AH0014 | TTL | -20, 10, 5 | 350/400 ns |
| *100 | 10 mA | AM97C11 | CMOS | | 150/300 ns | 8-Channel | | | | | | 200-600 | ±10 | AH0014 | TTL | -20, 10, 5 | 350/400 ns |
| *150 | 5 mA | AH5012/AM9712 | TTL | | 150/300 ns | 8-Channel | | | | | | 8-Channel | | | | | |
| *150 | 3 mA | AM97C12 | CMOS | | 150/300 ns | 8-Channel | | | | | | 8-Channel | | | | | |
| *30 | ±7.5 | AM193 | TTL | ±15, 5 | 180/150 ns | 8-Channel | | | | | | 8-Channel | | | | | |
| *75 | ±10 | AM194 | TTL | ±15, 5 | 300/150 ns | 8-Channel | | | | | | 8-Channel | | | | | |

Notes:RON max @ T_A = 25°CV_A/I = maximum voltage or current to be safely switched

Part number = basic number/alternate number (i.e., AM181/DG181). May be ordered by either number.

*Preferred devices





HYBRID ANALOG SWITCHES

| Function | | Drain-Source "On" Resistance | Drain-Gate Leakage Current | t _{ON} | t _{OFF} | Part Number | | * Page Number |
|----------|-----------|------------------------------------|----------------------------------|-----------------|------------------|-------------------|------------------|---------------------|
| | | | | | | -55°C to 125°C | -25°C to 85°C | |
| Type | Style | | | | | | | |
| PMOS | DPDT | 200Ω | 200pA | 350ns | 600ns | AH0014 | AH0014C | 8-7 |
| PMOS | DPDT | 200Ω | 200pA | 100ns | 600ns | AH0015 | AH0015C | 8-7 |
| PMOS | Dual DPST | 200Ω | 200pA | 100ns | 600ns | AH0019 | AH0019C | 8-7 |
| NJFET | Dual SPDT | 10Ω | 10nA | 1.0μs | 2.5μs | AH0140 | AH0140C | 8-10 |
| NJFET | Dual SPDT | 15Ω | 10nA | 1.0μs | 2.5μs | AH0153 | AH0153C | 8-10 |
| NJFET | Dual SPDT | 30Ω | 1nA | 0.8μs | 1.0μs | AH0129 | AH0129C | 8-10 |
| NJFET | Dual SPDT | 50Ω | 1nA | 0.8μs | 1.0μs | AH0153 | AH0153C | 8-10 |
| NJFET | Dual SPDT | 80Ω | 1nA | 0.8μs | 1.0μs | AH0126 | AH0126C | 8-10 |
| NJFET | Dual SPDT | 10Ω | 10nA | 1.0μs | 2.5μs | AH0141 | AH0141C | 8-10 |
| NJFET | Dual SPST | 15Ω | 10nA | 1.0μs | 2.5μs | AH0151 | AH0151C | 8-10 |
| NJFET | Dual SPST | 30Ω | 1nA | 0.8μs | 1.0μs | AH0133 | AH0133C | 8-10 |
| NJFET | Dual SPST | 50Ω | 1nA | 0.8μs | 1.0μs | AH0152 | AH0152C | 8-10 |
| NJFET | Dual SPST | 80Ω | 1nA | 0.8μs | 1.0μs | AH0134 | AH0134C | 8-10 |
| NJFET | DPDT | 10Ω | 10nA | 1.0μs | 2.5μs | AH0145 | AH0145C | 8-10 |
| NJFET | DPDT | 15Ω | 10nA | 1.0μs | 2.5μs | AH0163 | AH0163C | 8-10 |
| NJFET | DPDT | 30Ω | 1nA | 0.8μs | 1.0μs | AH0139 | AH0139C | 8-10 |
| NJFET | DPDT | 50Ω | 1nA | 0.8μs | 1.0μs | AH0164 | AH0164C | 8-10 |
| NJFET | DPDT | 80Ω | 1nA | 0.8μs | 1.0μs | AH0142 | AH0142C | 8-10 |
| NJFET | SPDT | 10Ω | 10nA | 1.0μs | 2.5μs | AH0146 | AH0146C | 8-10 |
| NJFET | SPDT | 15Ω | 10nA | 1.0μs | 2.5μs | AH0161 | AH0161C | 8-10 |
| NJFET | SPDT | 30Ω | 1nA | 0.8μs | 1.0μs | AH0144 | AH0144C | 8-10 |
| NJFET | SPDT | 50Ω | 1nA | 0.8μs | 1.0μs | AH0162 | AH0162C | 8-10 |
| NJFET | SPDT | 80Ω | 1nA | 0.8μs | 1.0μs | AH0143 | AH0143C | 8-10 |
| NJFET | Dual SPST | 100Ω | 1nA | 1.5μs | 0.75μs | AH2114 | AH2114C | 8-17 |

*Refers to Special Functions Databook, 1979 edition

Definition of Terms

Driver Leakage Current: The sum of the currents into the source and drain switch terminals, with both held at the same specified voltage.

Switch Leakage Current: The current seen when a specified voltage is applied between drain and source of a channel that is logically turned off.

Logic "1" Input Voltage: The voltage level which is guaranteed to be interpreted by the device as a logical "true" signal.

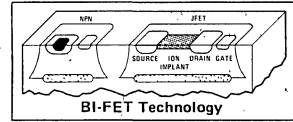
Switch "ON" Resistance: The equivalent resistance from source to drain, tested by forcing a specified current and measuring the resultant voltage drop.

Logic "0" Input Voltage: The voltage level which is guaranteed to be interpreted by the device as a logical "false" signal.

Switch Turn "OFF" Time: The interval between the time that the logic input passes through the threshold voltage and the time that the output goes to a specified voltage level in the test circuit.

Logic Input Slew Rate: The voltage difference between the logic "1" and logic "0" states divided by the transition time.

Switch Turn "ON" Time: The interval between the time that the logic input passes through the threshold voltage and the time that the output goes to 90% of its final value in the specified test circuit.



Quad SPST JFET Analog Switches

- LF11331/LF13331 4 Normally Open Switches with Disable
- LF11332/LF13332 4 Normally Closed Switches with Disable
- LF11333/LF13333 2 Normally Closed Switches and 2 Normally Open Switches with Disable
- LF11201/LF13201 4 Normally Closed Switches
- LF11202/LF13202 4 Normally Open Switches

General Description

These devices are a monolithic combination of bipolar and JFET technology producing the industry's first one chip quad JFET switch. A unique circuit technique is employed to maintain a constant resistance over the analog voltage range of $\pm 10V$. The input is designed to operate from minimum TTL levels, and switch operation also ensures a break-before-make action.

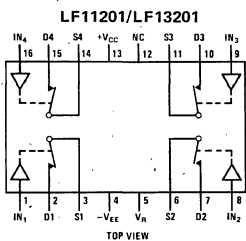
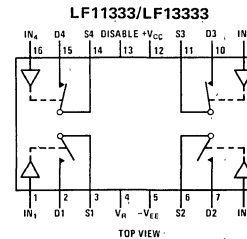
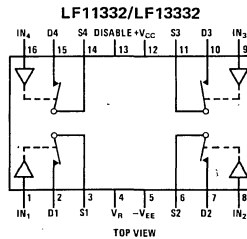
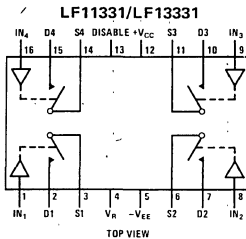
Features

- Analog signals are not loaded
- Constant "ON" resistance for signals up to $\pm 10V$ and 100 kHz
- Pin compatible with CMOS switches with the advantage of blow out free handling

- Small signal analog signals to 50 MHz
- Break-before-make action $t_{OFF} < t_{ON}$
- High open switch isolation at 1.0 MHz -50 dB
- Low leakage in "OFF" state < 1.0 nA
- TTL, DTL, RTL compatibility
- Single disable pin opens all switches in package on LF11331, LF11332, LF11333
- LF11201 is pin compatible with DG201

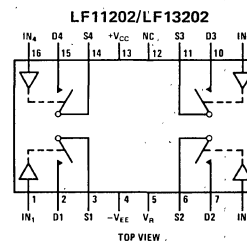
These devices operate from $\pm 15V$ supplies and swing a $\pm 10V$ analog signal. The JFET switches are designed for applications where a dc to medium frequency analog signal needs to be controlled.

Connection Diagrams (Dual-In-Line Packages) (All Switches Shown are For Logical "0")



Order Number LF11201D,
LF13201D, LF11202D,
LF13202D, LF11331D,
LF1331D, LF11332D,
LF1332D, LF11333D,
or LF1333D
See NS Package D16C

Order Number LF13201N,
LF13202N, LF13331N, LF13332N,
or LF13333N
See NS Package N16A



Test Circuit and Schematic Diagram

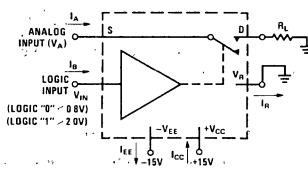


FIGURE 1. Typical Circuit for One Switch

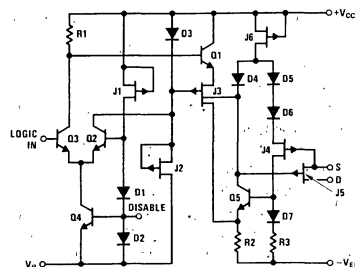


FIGURE 2. Schematic Diagram (Normally Open)

Absolute Maximum Ratings

| | |
|---|---|
| Positive Supply – Negative Supply ($V_{CC}-V_{EE}$) | 36V |
| Reference Voltage | $V_{EE} \leq V_R \leq V_{CC}$ |
| Logic Input Voltage | $V_R - 4.0V \leq V_{IN} \leq V_R + 6.0V$ |
| Analog Voltage | $V_{EE} \leq V_A \leq V_{CC} + 6V; V_A \leq V_{EE} + 36V$ |
| Analog Current | $ I_A < 20 \text{ mA}$ |
| Power Dissipation (Note 1) | |
| Molded DIP (N Suffix) | 500 mW |
| Cavity DIP (D Suffix) | 900 mW |

| | | |
|--|------------------------------|-----------------|
| Operating Temperature Range | LF11201, 2 and LF11331, 2, 3 | -55°C to +125°C |
| | LF13201, 2 and LF13331, 2, 3 | 0°C to +70°C |
| Storage Temperature | | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | | 300°C |

Electrical Characteristics (Notes 2, 7)

| SYMBOL | PARAMETER | CONDITIONS | LF11331/2/3 LF11201/2 | | | LF13331/2/3 LF13201/2 | | | UNITS |
|-------------------------|-------------------------------------|---|--------------------------|------------|------------|--------------------------|------------|-------------|------------------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| R_{ON} | "ON" Resistance | $V_A = 0, I_D = 1 \text{ mA}$ $T_A = 25^\circ\text{C}$ | | 150 200 | 200 300 | | 150 200 | 250 350 | Ω |
| R_{ON} Match | "ON" Resistance Matching | $T_A = 25^\circ\text{C}$ | | 5 | 20 | | 10 | 50 | Ω |
| V_A | Analog Range | | ± 10 | ± 11 | | ± 10 | ± 11 | | V |
| $I_{S(ON)} + I_{D(ON)}$ | Leakage Current in "ON" Condition | Switch "ON," $V_S = V_D = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 0.3 3 | 5 100 | | 0.3 3 | 10 30 | nA |
| $I_{S(OFF)}$ | Source Current in "OFF" Condition | Switch "OFF," $V_S = +10V, V_D = -10V$ $T_A = 25^\circ\text{C}$ | | 0.4 3 | 5 100 | | 0.4 3 | 10 30 | nA |
| $I_{D(OFF)}$ | Drain Current in "OFF" Condition | Switch "OFF," $V_S = +10V, V_D = -10V$ $T_A = 25^\circ\text{C}$ | | 0.1 3 | 5 100 | | 0.1 3 | 10 30 | nA |
| V_{INH} | Logical "1" Input Voltage | | 2.0 | | | 2.0 | | | V |
| V_{INL} | Logical "0" Input Voltage | | | | 0.8 | | | 0.8 | V |
| I_{INH} | Logical "1" Input Current | $V_{IN} = 5V$ $T_A = 25^\circ\text{C}$ | | 3.6 10 | 25 | | 3.6 10 | 40 100 | μA |
| I_{INL} | Logical "0" Input Current | $V_{IN} = 0.8$ $T_A = 25^\circ\text{C}$ | | | 0.1 1 | | | 0.1 1 | μA |
| t_{ON} | Delay Time "ON" | $V_S = \pm 10V, (Figure 3)$ $T_A = 25^\circ\text{C}$ | | 500 | | | 500 | | ns |
| t_{OFF} | Delay Time "OFF" | $V_S = \pm 10V, (Figure 3)$ $T_A = 25^\circ\text{C}$ | | 90 | | | 90 | | ns |
| $t_{ON} - t_{OFF}$ | Break-Before-Make | $V_S = \pm 10V, (Figure 3)$ $T_A = 25^\circ\text{C}$ | | 80 | | | 80 | | ns |
| $C_{S(OFF)}$ | Source Capacitance | Switch "OFF," $V_S = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 4.0 | | | 4.0 | | pF |
| $C_{D(OFF)}$ | Drain Capacitance | Switch "OFF," $V_D = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 3.0 | | | 3.0 | | pF |
| $C_{S(ON)} + C_{D(ON)}$ | Active Source and Drain Capacitance | Switch "ON," $V_S = V_D = 0V$ $T_A = 25^\circ\text{C}$ | | 5.0 | | | 5.0 | | pF |
| $I_{SO(OFF)}$ | "OFF" Isolation | (Figure 4), (Note 3) $T_A = 25^\circ\text{C}$ | | -50 | | | -50 | | dB |
| CT | Crosstalk | (Figure 4), (Note 3) $T_A = 25^\circ\text{C}$ | | -65 | | | -65 | | dB |
| SR | Analog Slew Rate | (Note 4) $T_A = 25^\circ\text{C}$ | | 50 | | | 50 | | V/ μs |
| I_{DIS} | Disable Current | (Figure 5), (Note 5) $T_A = 25^\circ\text{C}$ | | 0.4 0.6 | 1.0 1.5 | | 0.6 0.9 | 1.5 2.3 | mA |
| I_{EE} | Negative Supply Current | All Switches "OFF," $V_S = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 3.0 4.2 | 5.0 7.5 | | 4.3 6.0 | 7.0 10.5 | mA |
| I_R | Reference Supply Current | All Switches "OFF," $V_S = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 2.0 2.8 | 4.0 6.0 | | 2.7 3.8 | 5.0 7.5 | mA |
| I_{CC} | Positive Supply Current | All Switches "OFF," $V_S = \pm 10V$ $T_A = 25^\circ\text{C}$ | | 4.5 6.3 | 6.0 9.0 | | 7.0 9.8 | 9.0 13.5 | mA |

Note 1: For operating at high temperature the molded DIP products must be derated based on a +100°C maximum junction temperature and a thermal resistance of +150°C/W, devices in the cavity DIP are based on a +150°C maximum junction temperature and are derated at +100°C/W.

Note 2: Unless otherwise specified, $V_{CC} = +15V, V_{EE} = -15V, V_R = 0V$, and limits apply for $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ for the LF11331, 2, 3 and the LF11202, 2, $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ for the LF13331, 2, 3 and the LF13201, 2.

Note 3: These parameters are limited by the pin to pin capacitance of the package.

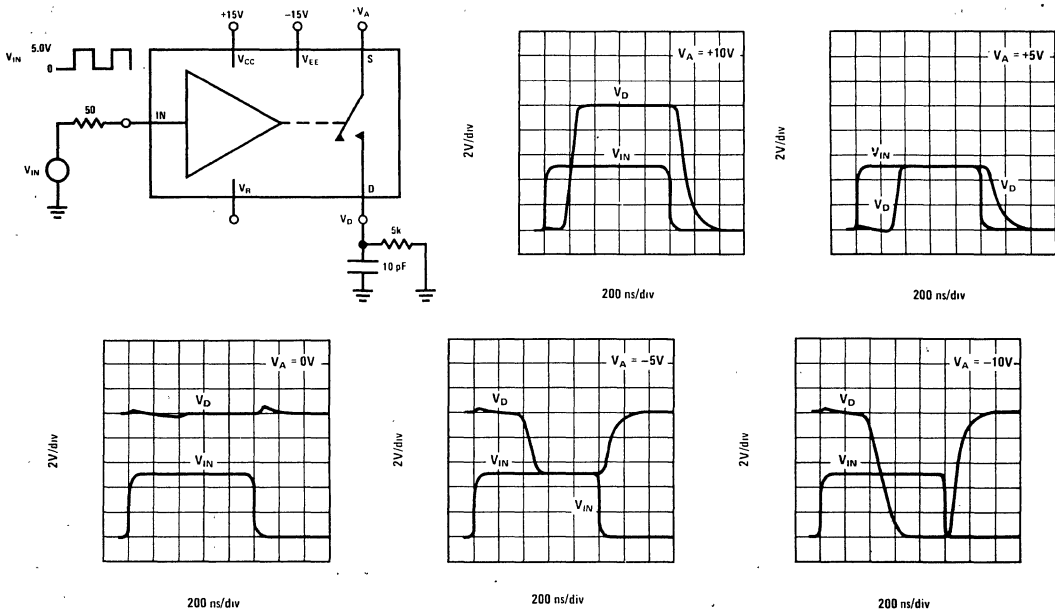
Note 4: This is the analog signal slew rate above which the signal is distorted as a result of finite internal slew rates.

Note 5: All switches in the device are turned "OFF" by saturating a transistor at the disable node as shown in Figure 5. The delay times will be approximately equal to the t_{ON} or t_{OFF} plus the delay introduced by the external transistor.

Note 6: This graph indicates the analog current at which 1% of the analog current is lost when the drain is positive with respect to the source.

Test Circuit and Typical Performance Curves

Delay Time, Rise Time, Settling Time, and Switching Transients



Additional Test Circuits

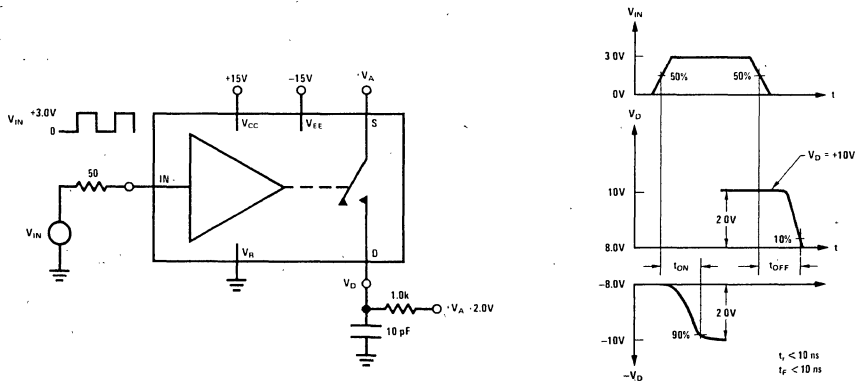


FIGURE 3. t_{ON} , t_{OFF} Test Circuit and Waveforms for a Normally Open Switch

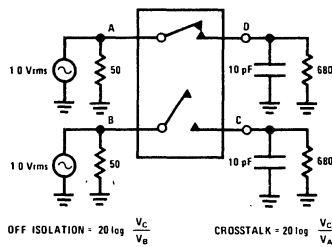
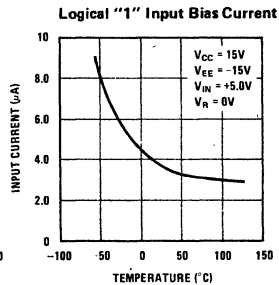
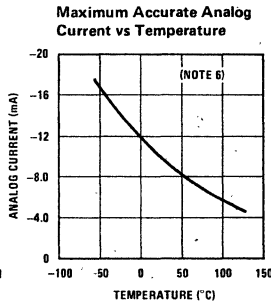
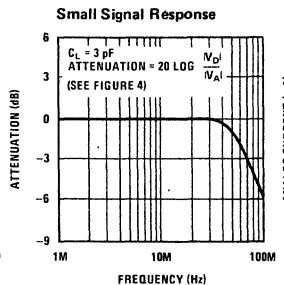
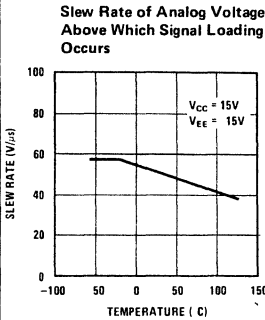
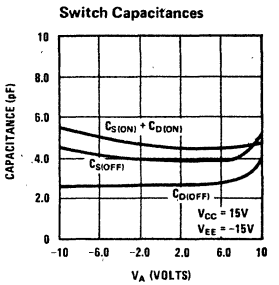
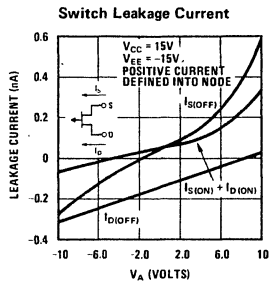
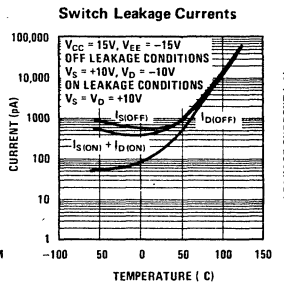
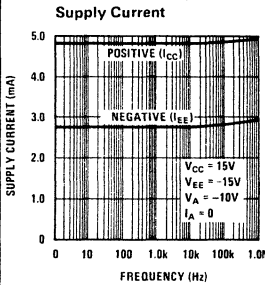
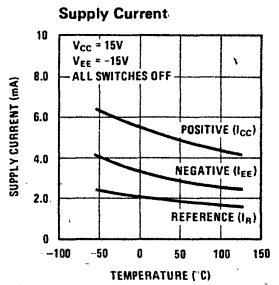
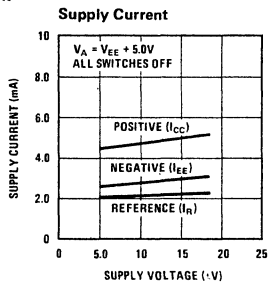
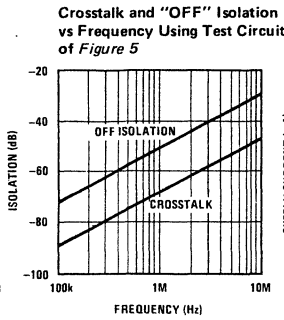
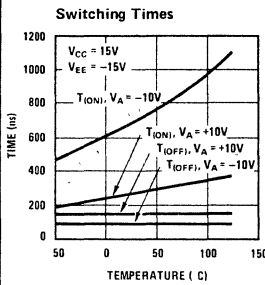
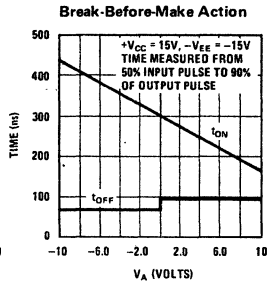
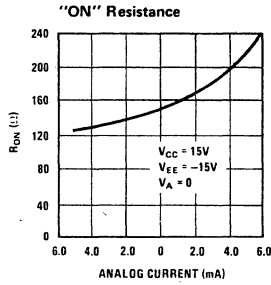
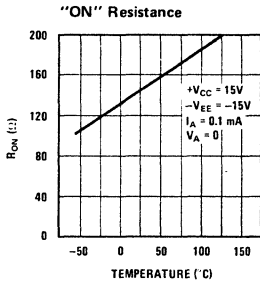
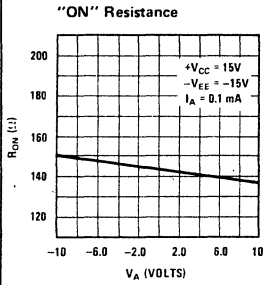


FIGURE 4. "OFF" Isolation, Crosstalk, Small Signal Response

LF11331, LF11332, LF11333, LF11201, LF11202 Series



Typical Performance Characteristics





Application Hints

GENERAL INFORMATION

These devices are monolithic quad JFET analog switches with "ON" resistances which are essentially independent of analog voltage or analog current. The leakage currents are typically less than 1 nA at 25°C in both the "OFF" and "ON" switch states and introduce negligible errors in most applications. Each switch is controlled by minimum TTL logic levels at its input and is designed to turn "OFF" faster than it will turn "ON." This prevents two analog sources from being transiently connected together during switching. The switches were designed for applications which require break-before-make action, no analog current loss, medium speed switching times and moderate analog currents.

Because these analog switches are JFET rather than CMOS, they do not require special handling.

LOGIC INPUTS

The logic input (IN), of each switch, is referenced to two forward diode drops (1.4V at 25°C) from the reference supply (V_R) which makes it compatible with DTL, RTL, and TTL logic families. For normal operation, the logic "0" voltage can range from 0.8V to -4.0V with respect to V_R and the logic "1" voltage can range from 2.0V to 6.0V with respect to V_R , provided V_{IN} is not greater than ($V_{CC} - 2.5V$). If the input voltage is greater than ($V_{CC} - 2.5V$), the input current will increase. If the input voltage exceeds 6.0V or -4.0V with respect to V_R , a resistor in series with the input should be used to limit the input current to less than 100 μ A.

ANALOG VOLTAGE AND CURRENT

Analog Voltage

Each switch has a constant "ON" resistance (R_{ON}) for analog voltages from ($V_{EE} + 5V$) to ($V_{CC} - 5V$). For analog voltages greater than ($V_{CC} - 5V$), the switch will remain ON independent of the logic input voltage. For analog voltages less than ($V_{EE} + 5V$), the ON resistance of the switch will increase. Although the switch will not operate normally when the analog voltage is out of the previously mentioned range, the source voltage can go to either ($V_{EE} + 36V$) or ($V_{CC} + 6V$), whichever is more positive, and can go as negative as V_{EE} without destruction. The drain (D) voltage can also go to either ($V_{EE} + 36V$) or ($V_{CC} + 6V$), whichever is more positive, and can go as negative as ($V_{CC} - 36V$) without destruction.

Analog Current

With the source (S) positive with respect to the drain (D), the R_{ON} is constant for low analog currents, but will increase at higher currents (>5 mA) when the FET enters the saturation region. However, if the drain is positive with respect to the source and a small analog current loss at high analog currents (Note 6) is tolerable, a low R_{ON} can be maintained for analog currents greater than 5 mA at 25°C.

LEAKAGE CURRENTS

The drain and source leakage currents, in both the ON and the OFF states of each switch, are typically less than 1 nA at 25°C and less than 100 nA at 125°C. As shown in the typical curves, these leakage currents are dependent on power supply voltages, analog voltage, analog current and the source to drain voltage.

DELAY TIMES

The delay time OFF (t_{OFF}) is essentially independent of both the analog voltage and temperature. The delay time ON (t_{ON}) will decrease as either ($V_{CC} - V_A$) decreases or the temperature decreases.

POWER SUPPLIES

The voltage between the positive supply (V_{CC}) and either the negative supply (V_{EE}) or the reference supply (V_R) can be as much as 36V. To accommodate variations in input logic reference voltages, V_R can range from V_{EE} to ($V_{CC} - 4.5V$). Care should be taken to ensure that the power supply leads for the device never become reversed in polarity or that the device is never inadvertently installed backwards in a test socket. If one of these conditions occurs, the supplies would zener an internal diode to an unlimited current; and result in a destroyed device.

SWITCHING TRANSIENTS

When a switch is turned OFF or ON, transients will appear at the load due to the internal transient voltage at the gate of the switch JFET being coupled to the drain and source by the junction capacitances of the JFET. The magnitude of these transients is dependent on the load. A lower value R_L produces a lower transient voltage. A negative transient occurs during the delay time ON, while a positive transient occurs during the delay time OFF. These transients are relatively small when compared to faster switch families.

DISABLE NODE

This node can be used, as shown in Figure 5, to turn all the switches in the unit off independent of logic inputs. Normally, the node floats freely at an internal diode drop ($\approx 0.7V$) above V_R . When the external transistor in Figure 5 is saturated, the node is pulled very close to V_R and the unit is disabled. Typically, the current from the node will be less than 1 mA. This feature is not available on the LF11201 or LF11202 series.

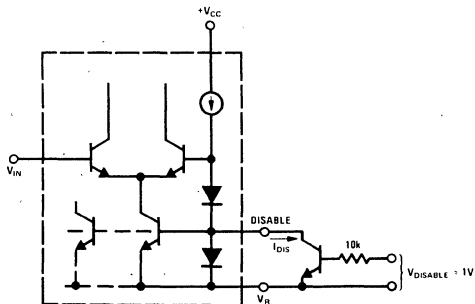
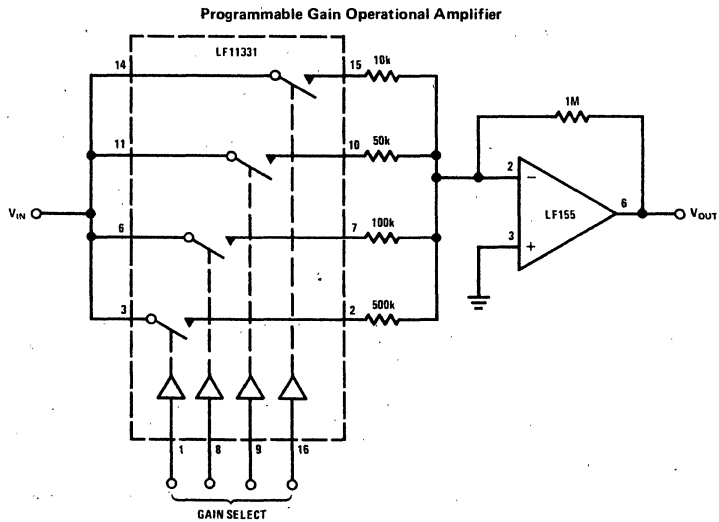
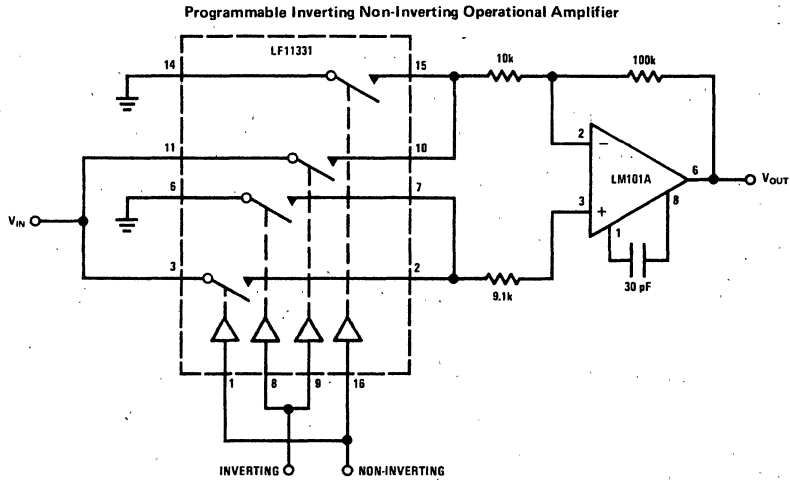
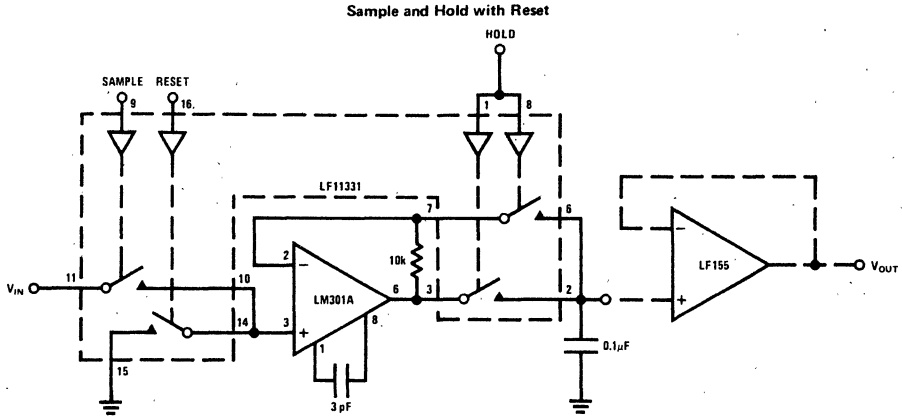
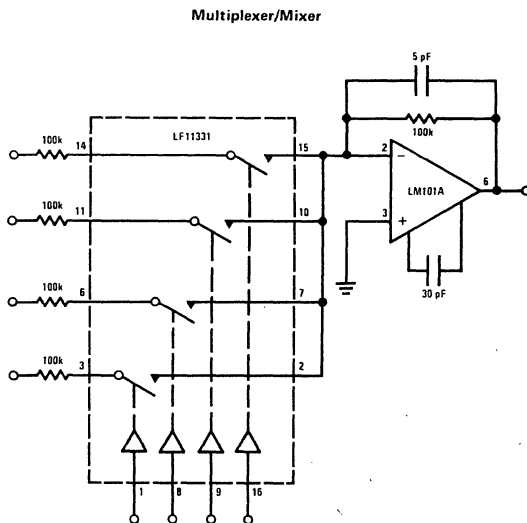
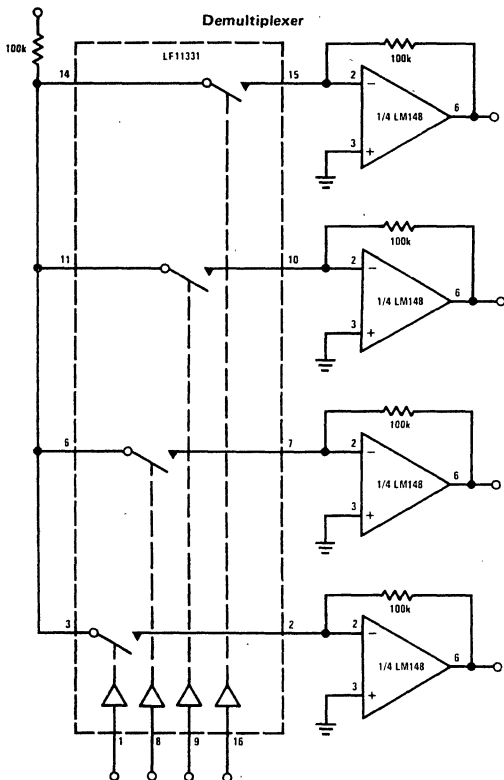


FIGURE 5. Disable Function

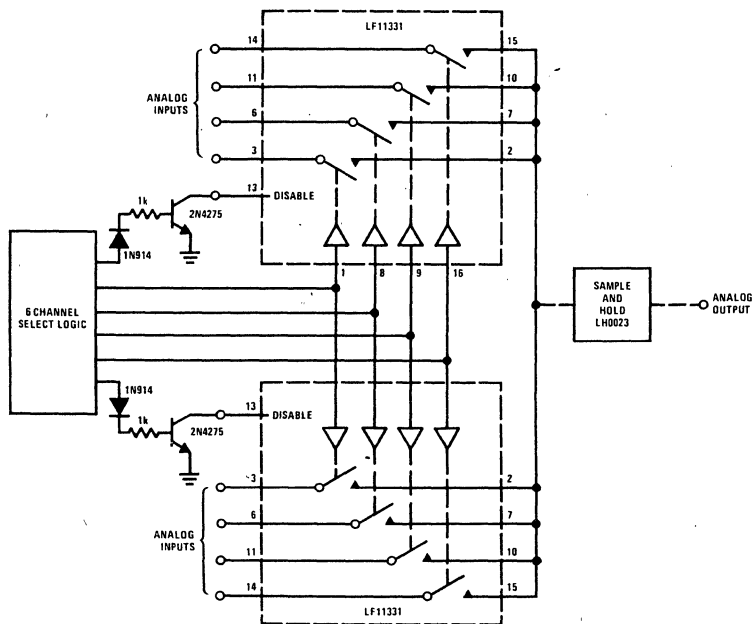
Typical Applications



Typical Applications (Continued)

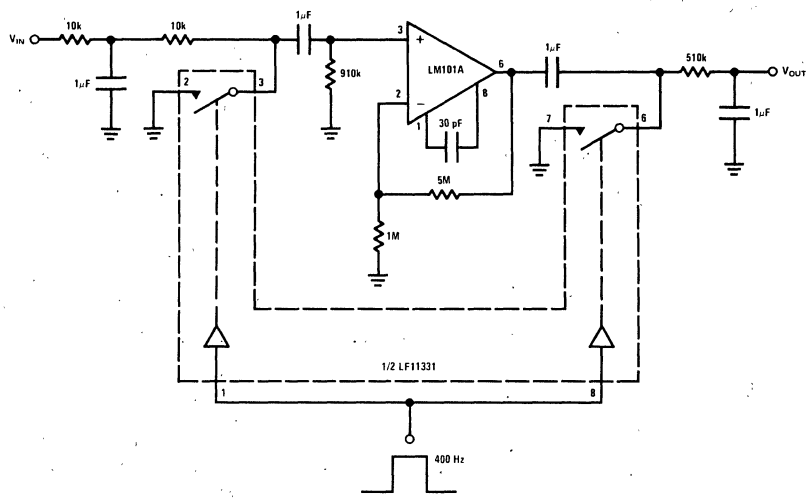


8-Channel Analog Commutator with 6-Channel Select Logic

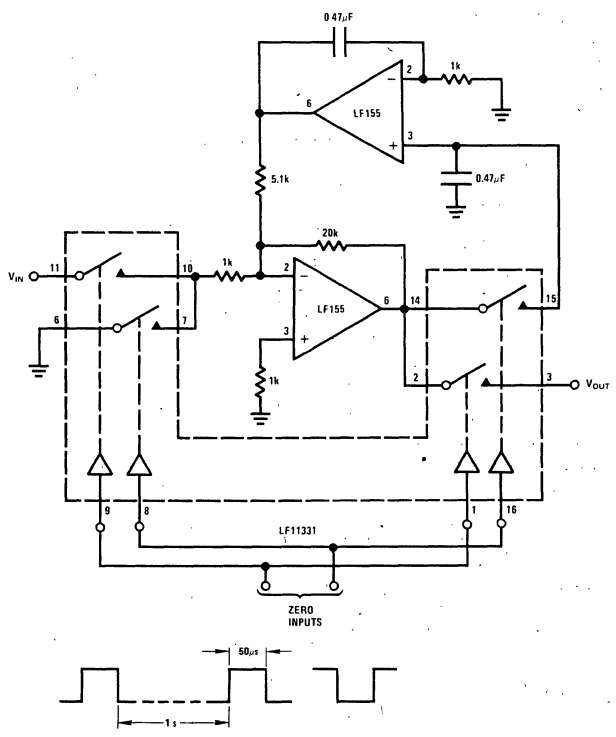


Typical Applications (Continued)

Chopper Channel Amplifier

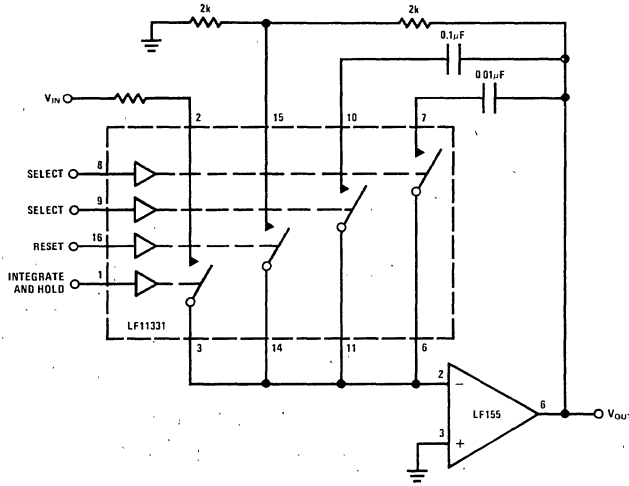


Self-Zeroing Operational Amplifier

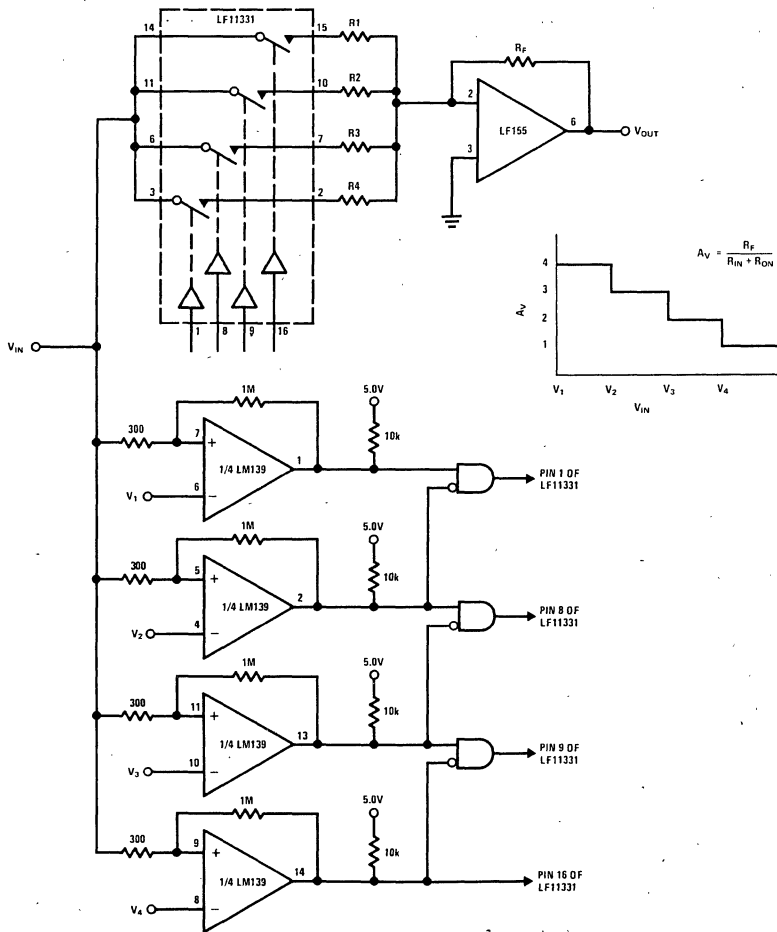


Typical Applications (Continued)

Programmable Integrator with Reset and Hold



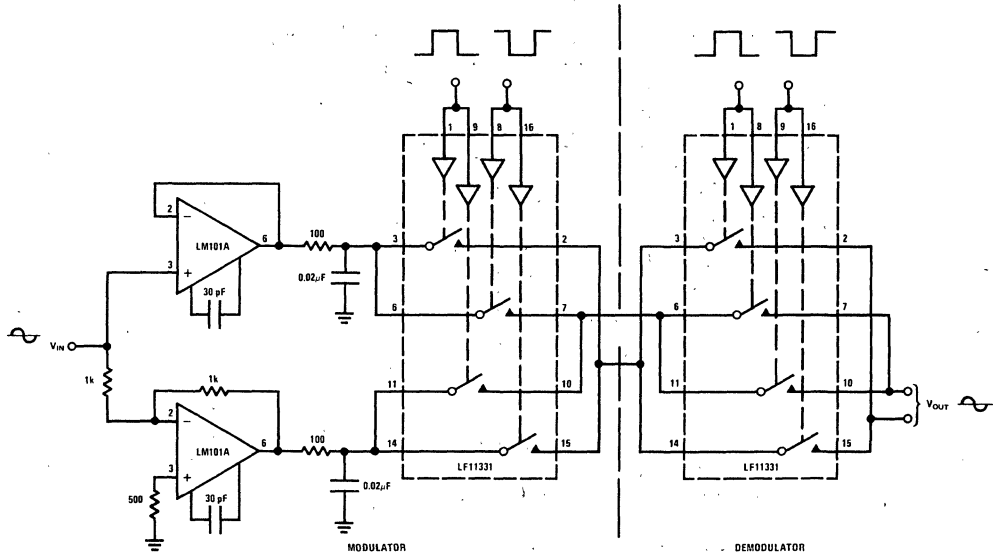
Staircase Transfer Function Operational Amplifier

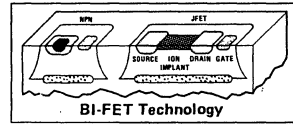


LF11331, LF11332, LF11333, LF11201, LF11202 Series

Typical Applications (Continued)

DSB Modulator-Demodulator





LF11508/LF13508 8-Channel Analog Multiplexer

LF11509/LF13509 4-Channel Differential Analog Multiplexer

General Description

The LF11508/LF13508 is an 8-channel analog multiplexer which connects the output to 1 of the 8 analog inputs depending on the state of a 3-bit binary address. An enable control allows disconnecting the output, thereby providing a package select function.

This device is fabricated with National's BI-FET technology which provides ion-implanted JFETs for the analog switch on the same chip as the bipolar decode and switch drive circuitry. This technology makes possible low constant "ON" resistance with analog input voltage variations. This device does not suffer from latch-up problems or static charge blow-out problems associated with similar CMOS parts. The digital inputs are designed to operate from both TTL and CMOS levels, while always providing a definite break-before-make action.

The LF11509/LF13509 is a 4-channel differential analog multiplexer. A 2-bit binary address will connect a pair

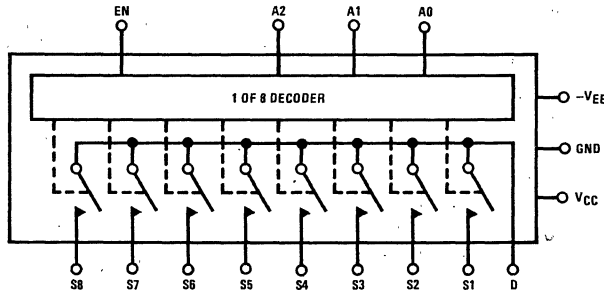
of independent analog inputs to one of any 4 pairs of independent analog outputs. The device has all the features of the LF11508 series and should be used whenever differential analog inputs are required.

Features

- JFET switches rather than CMOS
- No static discharge blow-out problem
- No SCR latch-up problems
- Analog signal range 11V, -15V
- Constant "ON" resistance for analog signals between -11V and 11V
- "ON" resistance 380 Ω typ
- Digital inputs compatible with TTL and CMOS
- Output enable control
- Break-before-make action: $t_{OFF} = 0.2 \mu s$; $t_{ON} = 2 \mu s$ typ
- Lower leakage devices available

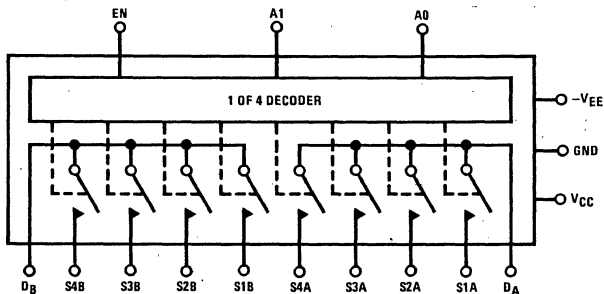
Functional Diagrams and Truth Tables

LF11508/LF13508



| EN | A2 | A1 | A0 | SWITCH ON |
|----|----|----|----|-----------|
| H | L | L | L | S1 |
| H | L | L | H | S2 |
| H | L | H | L | S3 |
| H | L | H | H | S4 |
| H | H | L | L | S5 |
| H | H | L | H | S6 |
| H | H | H | L | S7 |
| H | H | H | H | S8 |
| L | X | X | X | NONE |

LF11509/LF13509



| EN | A1 | A0 | SWITCH PAIR ON |
|----|----|----|----------------|
| L | X | X | None |
| H | L | L | S1 |
| H | L | H | S2 |
| H | H | L | S3 |
| H | H | H | S4 |

LF11508/LF13508, LF11509/LF13509


Absolute Maximum Ratings

| | LF11508, LF11509 | LF13508, LF13509 |
|---|--|---|
| Positive Supply — Negative Supply ($V_{CC} - V_{EE}$) | 36V | 36V |
| Positive Analog Input Voltage (Note 1) | V_{CC} | V_{CC} |
| Negative Analog Input Voltage (Note 1) | $-V_{EE}$ | $-V_{EE}$ |
| Positive Digital Input Voltage | V_{CC} | V_{CC} |
| Negative Digital Input Voltage | $-5V$ | $-5V$ |
| Analog Switch Current | $ I_S < 10\text{ mA}$ | $ I_S < 10\text{ mA}$ |
| Power Dissipation (P_D at 25°C) and Thermal Resistance (θ_{JA}), (Note 2) | | |
| Molded DIP (N) | P_D — θ_{JA} — | 500 mW 150°C/W |
| Cavity DIP (D) | P_D 900 mW θ_{JA} 100°C/W | 900 mW 100°C/W |
| Maximum Junction Temperature (T_{JMAX}) | 150°C | 100°C |
| Operating Temperature Range | $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ | $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ |
| Storage Temperature Range: | -65°C to $+150^\circ\text{C}$ | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 60 seconds) | 300°C | 300°C |

Electrical Characteristics (Note 3)

| SYMBOL | PARAMETER | CONDITIONS | LF11508, LF11509 | | | LF13508, LF13509 | | | UNITS |
|-----------------|---|---|--------------------------|------|-----|------------------|------|-----|----------|
| | | | MIN | TYP | MAX | MIN | TYP | MAX | |
| R_{ON} | "ON" Resistance | $V_{OUT} = 0V, I_S = 100\ \mu A$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 380 | 500 | | 380 | 650 | Ω |
| | | | | 600 | 750 | | 500 | 850 | Ω |
| ΔR_{ON} | ΔR_{ON} with Analog Voltage Swing | $-10V \leq V_{OUT} \leq +10V, I_S = 100\ \mu A$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 0.01 | 1 | | 0.01 | 1 | % |
| $R_{ON\ Match}$ | R_{ON} Match Between Switches | $V_{OUT} = 0V, I_S = 100\ \mu A$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 20 | 100 | | 20 | 150 | Ω |
| $I_S(OFF)$ | Source Current in "OFF" Condition | Switch "OFF", $V_S = 11, V_D = -11$, (Note 4) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 10 | 50 | | 0.09 | 50 | nA |
| $I_D(OFF)$ | Drain Current in "OFF" Condition | Switch "OFF", $V_S = 11, V_D = -11$, (Note 4) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 25 | 500 | | 0.6 | 500 | nA |
| $I_D(ON)$ | Leakage Current in "ON" Condition | Switch "ON" $V_D = 11V$, (Note 4) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 35 | 500 | | 1 | 500 | nA |
| V_{INH} | Digital "1" Input Voltage | | 2.0 | | | 2.0 | | | V |
| V_{INL} | Digital "0" Input Voltage | | | | 0.7 | | | 0.7 | V |
| I_{INL} | Digital "0" Input Current | $V_{IN} = 0.7V$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 1.5 | 20 | | 1.5 | 30 | μA |
| | | | | | 40 | | | 40 | μA |
| $I_{INL(EN)}$ | Digital "0" Enable Current | $V_{EN} = 0.7V$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 1.2 | 20 | | 1.2 | 30 | μA |
| | | | | | 40 | | | 40 | μA |
| t_{TRAN} | Switching Time of Multiplexer | (Figure 1), (Note 5) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 2.0 | 3 | | 1.8 | | μs |
| t_{OPEN} | Break-Before-Make | (Figure 3) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 1.6 | | | 1.6 | | μs |
| $t_{ON(EN)}$ | Enable Delay "ON" | (Figure 2) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 1.6 | | | 1.6 | | μs |
| $t_{OFF(EN)}$ | Enable Delay "OFF" | (Figure 2) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 0.2 | | | 0.2 | | μs |
| $I_{SO(OFF)}$ | "OFF" Isolation | (Note 6) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | -66 | | | -66 | | dB |
| CT | Crosstalk | LF11509 Series, (Note 6) | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | -66 | | | -66 | | dB |
| $C_S(OFF)$ | Source Capacitance ("OFF") | Switch "OFF", $V_{OUT} = 0V, V_S = 0V$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 2.2 | | | 2.2 | | pF |
| $C_D(OFF)$ | Drain Capacitance ("OFF") | Switch "OFF", $V_{OUT} = 0V, V_S = 0V$ | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 11.4 | | | 11.4 | | pF |
| I_{CC} | Positive Supply Current | All Digital Inputs Grounded | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 7.4 | 10 | | 7.4 | 12 | mA |
| | | | | 9.2 | 13 | | 7.9 | 15 | mA |
| I_{EE} | Negative Supply Current | All Digital Inputs Grounded | $T_A = 25^\circ\text{C}$ | | | | | | |
| | | | | 2.7 | 4.5 | | 2.7 | 5 | mA |
| | | | | 2.9 | 5.5 | | 2.8 | 6 | mA |

Notes

Note 1: If the analog input voltage exceeds this limit, the input current should be limited to less than 10 mA.

Note 2: The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{jMAX} , θ_{jA} , and the ambient temperature, T_A . The maximum available power dissipation at any temperature is $P_D = (T_{jMAX} - T_A) / \theta_{jA}$ or the $25^\circ\text{C } P_{DMAX}$, whichever is less.

Note 3: These specifications apply for $V_S = \pm 15\text{V}$ and over the absolute maximum operating temperature range ($T_L \leq T_A \leq T_H$) unless otherwise noted.

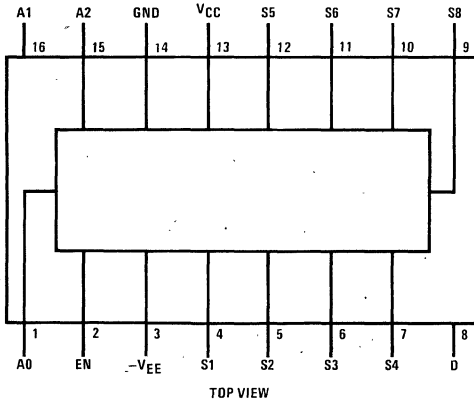
Note 4: Conditions applied to leakage tests insure worst case leakages. Exceeding 11V on the analog input may cause an "OFF" channel to turn "ON".

Note 5: Lots are sample tested to this parameter. The measurement conditions of *Figure 1* insure worst case transition time.

Note 6: "OFF" isolation is measured with all switches "OFF" and driving a source. Crosstalk is measured with a pair of switches "ON", driving channel A and measuring channel B. $R_L = 200$, $C_L = 7 \text{ pF}$, $V_S = 3 \text{ Vrms}$, $f = 500 \text{ kHz}$.

Connection Diagrams

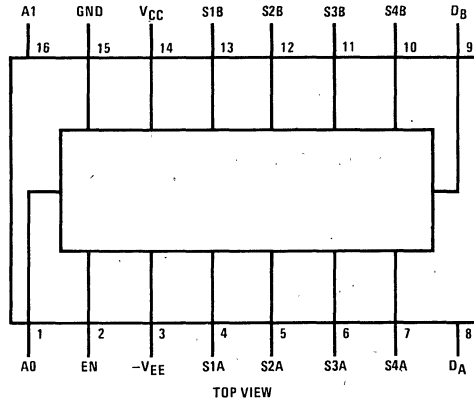
LF11508/LF13508
Dual-In-Line Package



Order Number LF11508D or LF13508D
See NS Package D16C

Order Number LF13508N
See NS Package N16A

LF11509/LF13509
Dual-In-Line Package



Order Number LF11509D or LF13509D
See NS Package D16C

Order Number LF13509N
See NS Package N16A

AC Test Circuits and Switching Time Waveforms

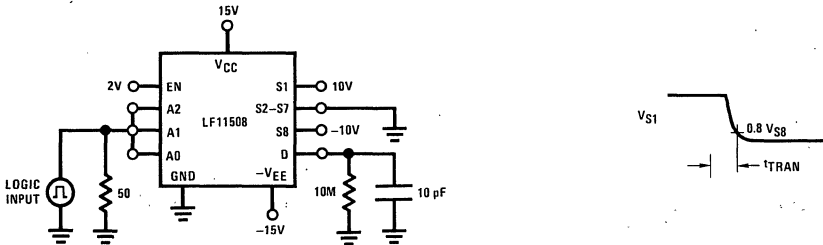


FIGURE 1. Transition Time

AC Test Circuit and Switching Time Waveforms (Continued)

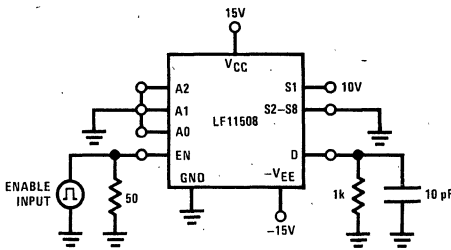


FIGURE 2. Enable Times

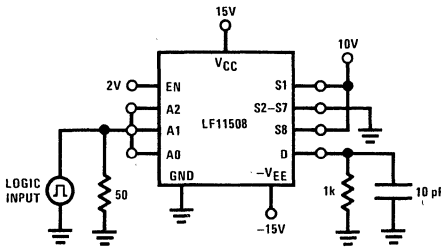
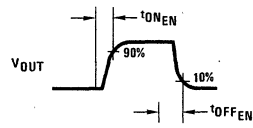
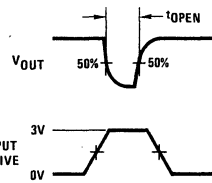
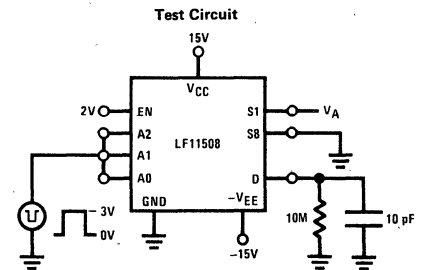
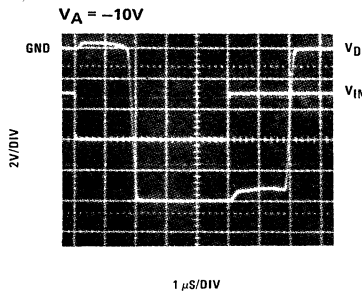
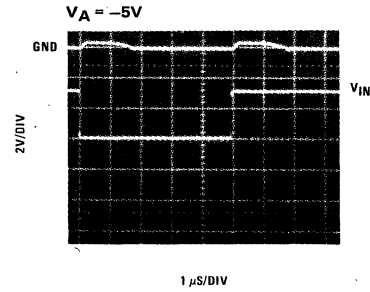
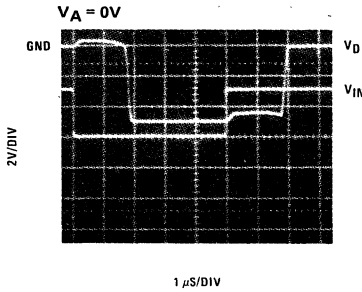
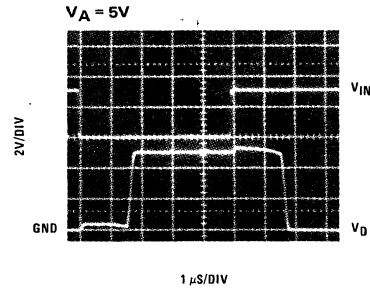
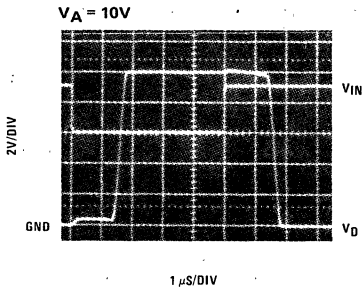


FIGURE 3. Break-Before-Make



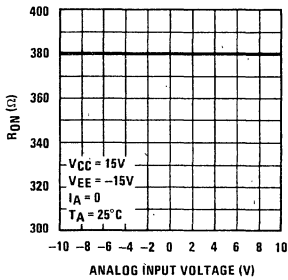
Transition Times and Transients



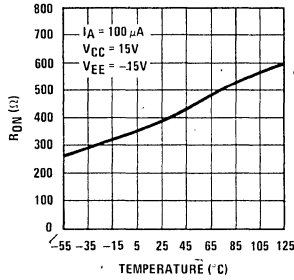
Typical Performance Characteristics

LF11508/LF13508, LF11509/LF13509

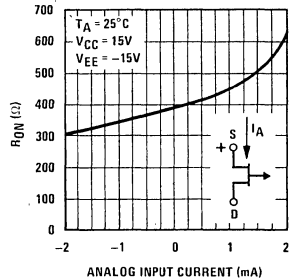
"ON" Resistance



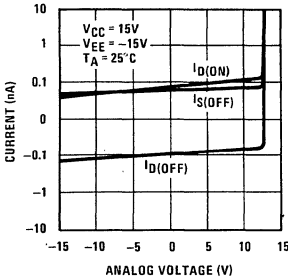
"ON" Resistance



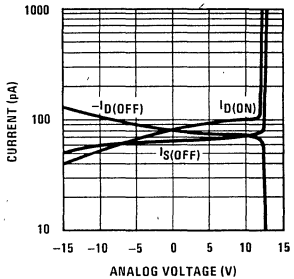
"ON" Resistance



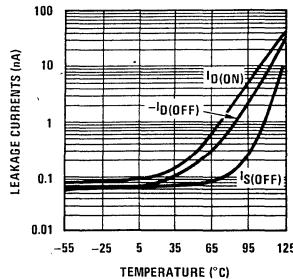
Switch Leakage Currents



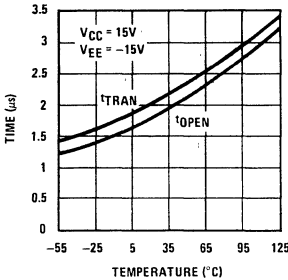
Switch Leakage Currents



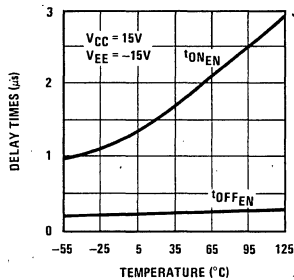
Switch Leakage Currents



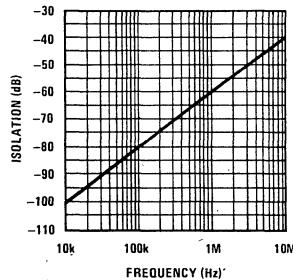
Switching Times (Figures 1 and 3)



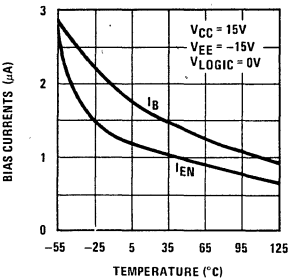
Enable Delay Times (Figure 2)



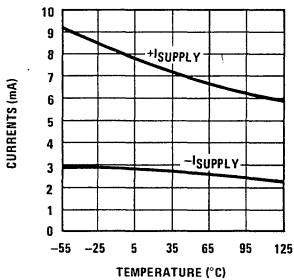
"OFF" Isolation and Crosstalk



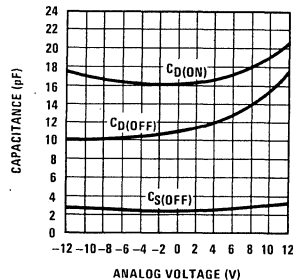
Bias Currents



Supply Currents



Switch Capacitances



Application Hints

The LF11508 series is an 8-channel analog multiplexer which allows the connection of a single load to 1 of 8 different analog inputs. These multiplexers incorporate JFETs in a switch configuration which insures a constant "ON" resistance over the analog voltage range of the device. Four TTL compatible inputs are provided; a 3-bit binary decode to select a particular channel and an enable input used as a package select. The switches operate with a break-before-make action preventing the temporary connection of 2 analog inputs during switching. Because these multiplexers are fabricated with the BI-FET process rather than CMOS, they do not require special handling.

The LF11509 series is a 4-channel differential multiplexer which allows two loads to be connected to 1 of 4 different pairs of analog inputs. The LF11509 series also has all the features of the LF11508.

ANALOG VOLTAGE AND CURRENT

The "ON" resistance, R_{ON} , of the analog switches is constant over a wide input range from positive (V_{CC}) supply to negative ($-V_{EE}$) supply.

The analog input should not exceed either positive or negative supply without limiting the current to less than 10 mA; otherwise the multiplexer may get damaged. For proper operation, however, the positive analog voltage should be kept equal to or less than $V_{CC} - 4V$ as this will increase the switch leakage in both "ON" and "OFF" state and it may also cause a false turn "ON" of a normally "OFF" switch. This limit applies over the full temperature range.

The maximum allowable switch "ON" voltage (the drop across the switch in the "ON" condition) is $\pm 0.4V$ over temperature. If this number is to exceed the input current should be limited to 10 mA.

The "ON" resistance of the multiplexing switches varies slightly with analog current because they are JFETs running at 0V gate to source. The JFET characteristics shown in Figure 4 indicates how R_{ON} tends to vary with current. A lower R_{ON} is possible when the source voltage is negative with respect to the drain voltage because the JFET becomes enhanced. Caution should be used when operating in this mode as this may forward-bias an internal transistor and cause high currents to flow in the switches. Thus, the drain voltage should never be greater than 0.4V positive with respect

to the source voltage without limiting the drain current to less than 10 mA.

LEAKAGE CURRENTS

Leakage currents will remain within the specified value as long as the drain and source remain within the specified analog voltage range. As the switch terminals exceed the positive analog voltage range "ON" and "OFF" leakage currents increase. The "ON" leakage increases due to an internal clamp required by the switch structure. The "OFF" leakage increases because the gate to source reverse bias has been decreased to the point where the switch becomes active. Leakage currents vary slightly with analog voltage and will approximately double for every $10^{\circ}C$ rise in temperature.

SWITCHING TIMES AND TRANSIENTS

These multiplexers operate with a break-before-make switch action. The turn off time is much faster than the turn on time to guarantee this feature over the full range of analog input voltage and temperature. Switching transients are introduced when a switch is turned "OFF". The amplitude of these transients may be reduced by increasing the load capacitance or decreasing the load resistance. The actual charge transfer in the transient may be reduced by operating on reduced power supplies. Examples of switching times and transients are shown in the typical characteristic curves. The enable function switching times are specified separately from switch-to-switch transition times and may be thought of as package-to-package transition times.

LOGIC INPUTS AND ENABLE INPUT

Switch selection in the LF11508 series is accomplished by using a 3-bit binary decode while the LF11509 series uses a 2-bit decode. These binary logic inputs are compatible with both TTL and CMOS logic voltage levels. The maximum positive voltage applied to these inputs may exceed V_{CC} but should not exceed $-V_{EE} + 36V$. The maximum negative voltage should not be less than $-4V$ below ground as this will cause an internal device to zener and all the switches will turn "ON".

As shown in the schematic diagram, the logic low bias current will flow until the PNP input is raised above the 3 diode reference ($\approx 2.1V$). Above this voltage the input device becomes reverse biased and the input current drops to the leakage of the reverse biased junction ($< 0.1 \mu A$).

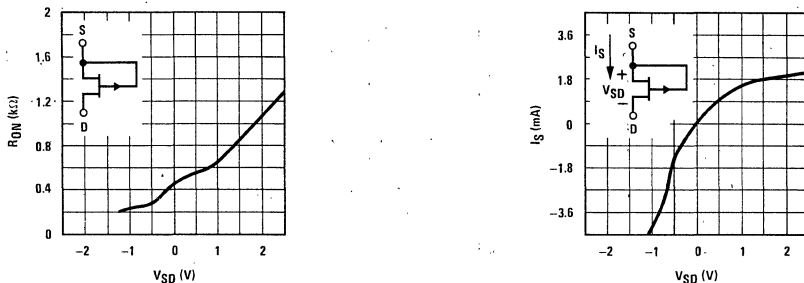


FIGURE 4. JFET Characteristics

Typical Applications

DATA ACQUISITION SYSTEM

A SIMPLIFIED SYSTEM DISCUSSION

Analog multiplexers (MUX) are usually used for multi-channel Data Acquisition Units (DAU). *Figure 5* shows a system in which 8 different analog inputs are sampled and converted into digital words for further processing. The sample and hold circuit is optional, depending on input speed requirements and on A/D converter speed.

Parameters characterizing the system are:

System Channels: The number of multiplexer channels.

Accuracy: The conversion accuracy of each individual sample with the system operating at the throughput rate.

Speed or Throughput Rate: Number of samples/second/channel the system can handle.

For a discussion on system structure, addressing mode and processor interfacing, see application note AN-159.

A. ACCURACY CONSIDERATIONS

1. Multiplexer's Influence on System Accuracy (*Figure 6*).

- a. The error, (E), caused by the finite "ON" resistance, R_{ON} , of the multiplexing switches is given by:

$$E(\%) = \frac{100}{1 + R_{IN}/(R_{ON} + R_S + \Delta R_{ON})} \text{ where:}$$

R_{IN} = following stage input impedance

ΔR_{ON} = "ON" resistance modulation which is negligible for JFET switches like the LF11508

Example: Let $R_{ON} = 450 \Omega$, $\Delta R_{ON} = 0$, $R_S = 0$, $T_A = 25^\circ C$ and allowable $E = 0.01\%$ which is equivalent to 1/2 LSB in a 12-bit system:

$$R_{IN} \Big|_{\min} = \frac{R_{ON} (100 - E)}{E} = 4.5 M\Omega$$

Note that if temperature effects are included, some gain (or full scale) drift will occur; but effects on linearity are small.

b. Multiplexer settling time (t_s):

$t_s(ON)$: is the time required for the MUX output to settle within a predetermined accuracy, as shown in Table I.

C_S (*Figure 6*): MUX output capacitance + following stage input capacitance + any stray capacitance at this node.

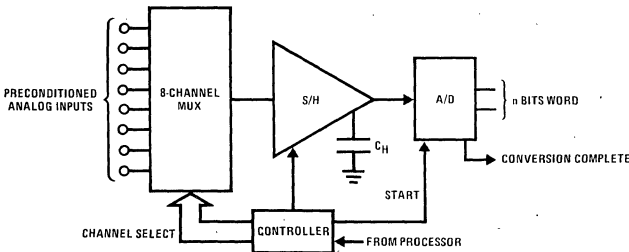


FIGURE 5. Random-Addressed, Multiplexed DAU

TABLE I.

| ERROR % | BITS | $t_s(ON)$ TO 1/2 LSB |
|---------|------|-------------------------|
| 0.2 | 8 | 6.2t |
| 0.05 | 10 | 7.6t |
| 0.01 | 12 | 9t |
| 0.0008 | 16 | 11.8t |

$$t = C_S (R_{ON} + R_S) \ln R_{IN}$$

$t_s(OFF)$: is the time it takes to discharge C_S within a tolerable error. The "OFF" settling time should be taken into account for bipolar inputs where its effects will appear as a worse case doubling of the $t_s(ON)$.

2. Sample and Hold Influence on System Accuracy

The sample and hold, if used, also introduces errors into the system accuracy due to:

- Offset voltage of sample and hold
- Droop rate in the Hold mode
- T_A : Aperture time or time delay between the time of a digital Hold command and the actual Hold occurrence
- T_{aq} : Acquisition time or time it takes to acquire an analog input and settle within a predetermined error band
- Hold step: Error created during the Sample to Hold mode caused by an undesirable charge injected into the Hold capacitor C_H .

For more details on sample and hold errors, see the LF198/LF298/LF398 data sheet.

3. A/D Converter Influence on System Accuracy

The "accuracy" of the A/D converter is the best possible system accuracy. In most data acquisition systems, the A/D converter is the most expensive single component, so its error will often dominate system error. Care should be taken that MUX, S/H and input source errors do not exceed system error requirements when added to A/D errors. For instance, if an 8-bit accuracy system is desired and an 8-bit A/D converter is used, the accuracy of the MUX and S/H should be far better than 8 bits.

For details on A/D converter specifications, see AN-156.

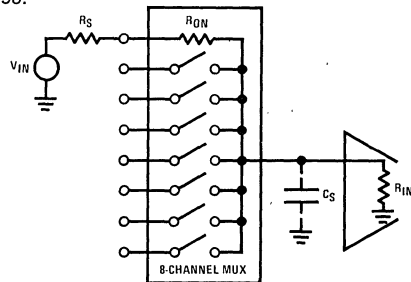


FIGURE 6. 8-Channel MUX

Typical Applications (Continued)

B. SPEED CONSIDERATIONS

In the system of *Figure 5* with the S/H omitted, if n-bit accuracy is desired, the change of the analog input voltage should be less than $\pm 1/2$ LSB over the A/D conversion time T_C . In other words, the analog input slew rate, (rate of change of input voltage), will cause a slew-induced error and its magnitude, with respect to the total system error, will depend on the particular application.

$$\left. \frac{\Delta V_{IN}}{\Delta t} \right|_{\max} < \frac{\pm 1/2 \text{ LSB}}{T_C} = \frac{V_{FS}}{2^n \times T_C}$$

where V_{FS} is the full scale voltage of the A/D. Note that slew induced errors are not affected by the MUX switch time since we can let the unit settle before starting conversion.

Example: Let $T_C = 40 \mu\text{s}$ (MM4357), $V_{FS} = 10\text{V}$ and $n = 8$.

$$\left. \frac{\Delta V_{IN}}{\Delta t} \right|_{\max} < \frac{1 \text{ mV}}{\mu\text{s}}$$

which is a very small number. A 10 Vp-p sine wave of a frequency greater than 32 Hz will have higher slew rate than this. The maximum throughput rate of the above 8-channel system would be calculated using both the A/D conversion time and the sum of MUX switch "ON" time and settling time, i.e.:

$$\text{Th. R} \Big|_{\max} = \frac{1}{8(T_C + T_{MUX})} = 3\text{k samples/sec/channel}$$

$$T_{MUX} = T_{ON} + T_S(\text{ON})$$

Also notice that Nyquist sampling criteria would allow each channel to have a signal bandwidth of 1.5 kHz max, while the slew limit dictates a maximum frequency of 32 Hz. If the input signal has a peak-to-peak voltage less than 10V, the allowable maximum input frequency can be calculated by:

$$f_{MAX} = \frac{(\text{Slew Rate})_{\max}}{\pi V_{p-p}}$$

On the other hand, if the input voltage is not band-limited a low pass filter with an attenuation of 30 dB or better at 1.5 kHz, should be connected in front of the MUX.

1. Improving System Speed with a Sample and Hold

The system speed can be improved by using the S/H shown in *Figure 5*. This allows a much greater rate of change of V_{IN} .

$$\left. \frac{\Delta V_{IN}}{\Delta t} \right|_{\max} < \frac{V_{FS}}{2^n \times T_A}$$

where T_A is the aperture time of the S/H. This represents an input slew rate improvement by a factor: T_C/T_A . Here again, the slew rate error is not affected by the acquisition time of the Sample and Hold since conversion will start after the S/H has settled. *An important thing to notice is that the sample and hold errors will add to the total system error budget; therefore, the inequality of the $\Delta V_{IN}/\Delta t$ expression should become more stringent.*

Example: $T_C = 40 \mu\text{s}$, $T_A = 0.5 \mu\text{s}$, $n = 8$: $T_C/T_A = 80$

So the use of a S/H allows a speed improvement by nearly two orders of magnitude.

The maximum throughput rate can be calculated by:

$$\text{Th. R} \Big|_{\max} = \frac{1}{8(T_A + T_{aq} + T_C)}$$

Notice that T_{MUX} does not affect the $\Delta V_{IN}/\Delta t$ expression *nor the throughput rate* of the system since it may be switched and settled while the Sample and Hold is in the Hold mode. This is true, provided that: $T_{MUX} < T_A + T_C$.

C. SYSTEM EXAMPLE (*Figure 7*)

The LF398 S/H with a 1000 pF hold capacitor, has an acquisition time of 4 μs to 0.1% (1/4 LSB error for 8 bits) and an aperture time of less than 200 μs . On the other hand, after the hold command, the output will settle to $\pm 0.05 \text{ mV}$ in 1 μs . This, together with the acquisition time, introduces approximately a $\pm 1/4$ LSB error. Allowing another 1/4 LSB error for hold step and gain non-linearity, the maximum slew error ($\Delta V_{IN}/\Delta t$) should not exceed 1/4 LSB or:

$$\frac{\Delta V_{IN}}{\Delta t} \leq \frac{1}{4} \times \frac{1}{256} \times \frac{1}{T_A} \approx 5 \text{ mV}/\mu\text{s}$$

(which is the maximum slew rate of a 5 V peak sine wave. Also notice that, due to the above input slew restrictions, the analog delay caused by the finite BW of the S/H and the digital delay caused by the response time of the controller will be negligible. The maximum throughput rate of the system is:

$$\text{Th. R} \Big|_{\max} = \frac{1}{8(5 + 40) 10^{-6}} = 2800 \text{ samples/sec/ch.}$$

If the system speed requirements are relaxed, but the A/D converter is still too slow, then an inexpensive S/H can be built by using just a capacitor and a low cost FET input op amp as shown in *Figure 8*.

Typical Applications (Continued)

LF11508/LF13508, LF11509/LF13509

6

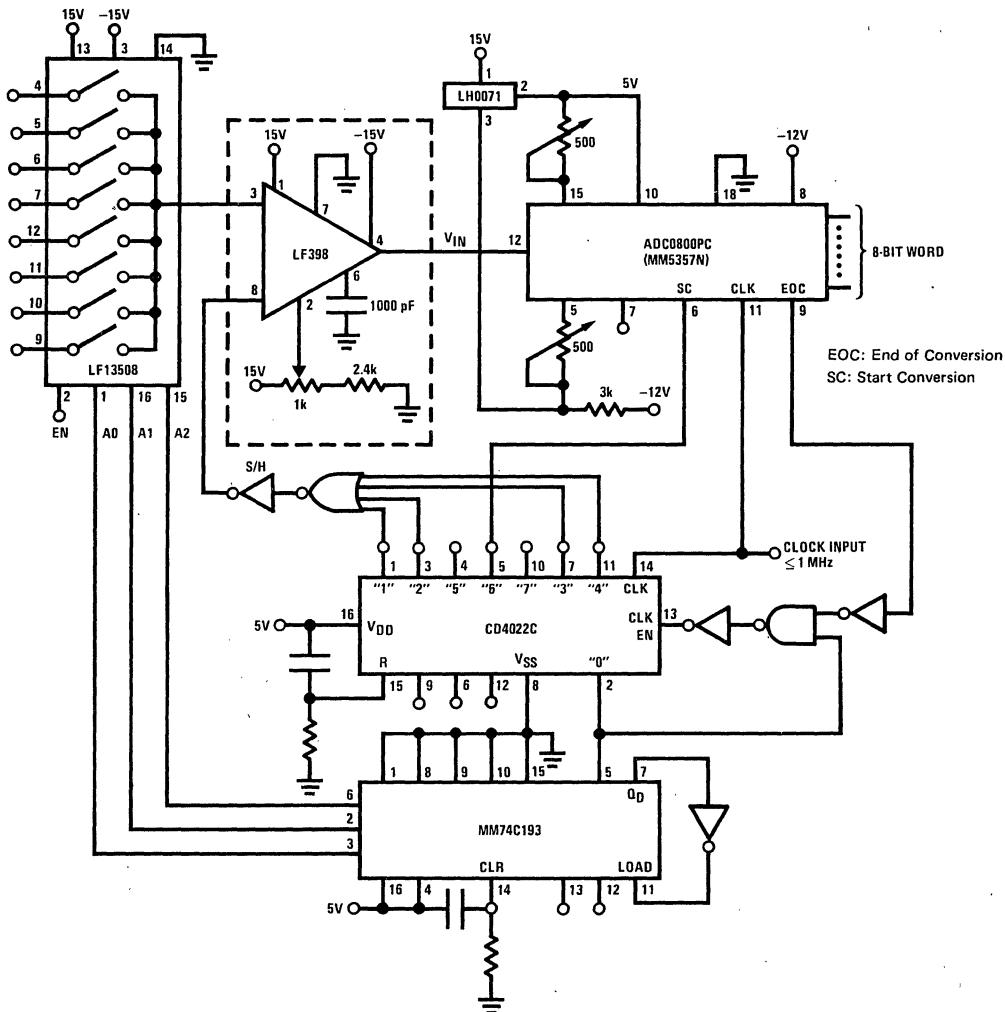


FIGURE 7a. Sequentially Multiplexed DAU with Sample and Hold

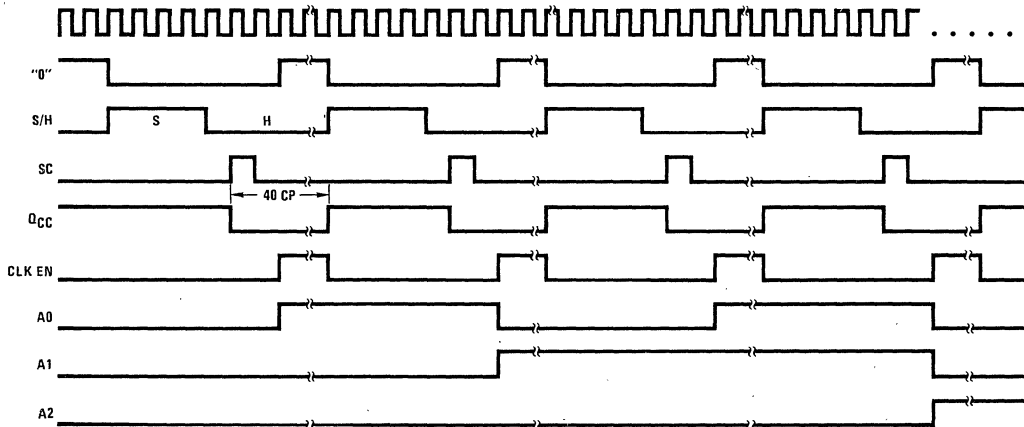


FIGURE 7b. Timing Diagram

Typical Applications (Continued)

D. DOUBLING THE SYSTEM CHANNEL CAPABILITY

This is done in two different ways. First, we can use second level multiplexing with speed benefits, as shown in *Figure 9*. A fast 2-channel multiplexer, made by the dual analog switch AM182, accepts the outputs of each 8-channel MUX, LF13508, and then feeds them sequentially into an 8-bit successive approximation A/D converter. With this technique, the throughput rate of the system can again be made independent of the the LF13508 speed. Looking at the timing diagram, when the A/D converter converts the analog value of an upper multiplexer channel, we switch channels in the lower multiplexer for the next conversion. This can be done provided that:

$$T_{MUX} \leq T_C + 1 CP.$$

The LF356 connected as unity gain buffers are used because of the low input impedance of the A/D; they are connected between multiplexers for speed optimization. With a maximum clock frequency of 4.5 MHz:

$$Th. R = \frac{10^6}{16 \times 2} = 31.25k \text{ samples/sec/channel}$$

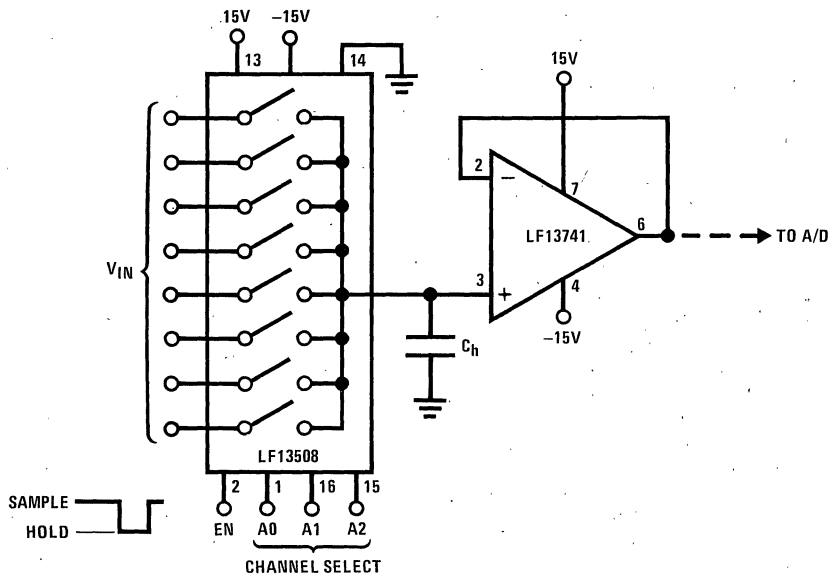
and

$$\left. \frac{\Delta V_{IN}}{\Delta t} \right|_{\max} < \frac{10}{256} \times \frac{1}{2 \mu s} = 19.5 \text{ mV}/\mu s \text{ for } 10V_{FS}$$

An alternate way to increase the system channel is shown in *Figure 10*, where the enable pins are used to disable one MUX while the other is sampling. With this method, many 8-channel multiplexers can be connected, but the parasitic capacitance at the common output node will keep increasing and will eventually degrade the settling time, $t_s(ON)$. Also, the MUX speed will now affect the system throughput. If, for instance, this method was used instead of second level multiplexing, the system of *Figure 9* will lose half of its speed. If, however, speed is not the prime system requirement, the approach of *Figure 10* is more cost effective.

E. DIFFERENTIAL INPUT SYSTEMS

Systems operating in industrial environments may require an instrumentation amplifier to separate the desired analog signal from any common-mode signal present. The LF11509 was designed to provide 4 pairs of differential input signals to the input of an instrumentation amplifier for further process. A 4-channel preconditioning circuit is shown in *Figure 11* and a complete system is shown in *Figure 12*.



- The acquisition time, T_A , of the Sample and Hold depends upon: R_{ON} , I_{DSS} of switches, Z_{OUT} of switches
- $I_{DSS} \approx 1.5 \text{ mA}$, $Z_{OUT} = 40 \text{ k}\Omega$
- $V_{IN} = 10V$, $C_h = 1000 \text{ pF}$, $T_A = 20 \mu s$ to 0.1%
- Error created by charge injection during Hold mode: $\Delta V_E \approx 10 \text{ pF} (14.5V - V_{IN})/C_h$

FIGURE 8. Inexpensive Sample and Hold

Typical Applications (Continued)

LF11508/LF13508, LF11509/LF13509

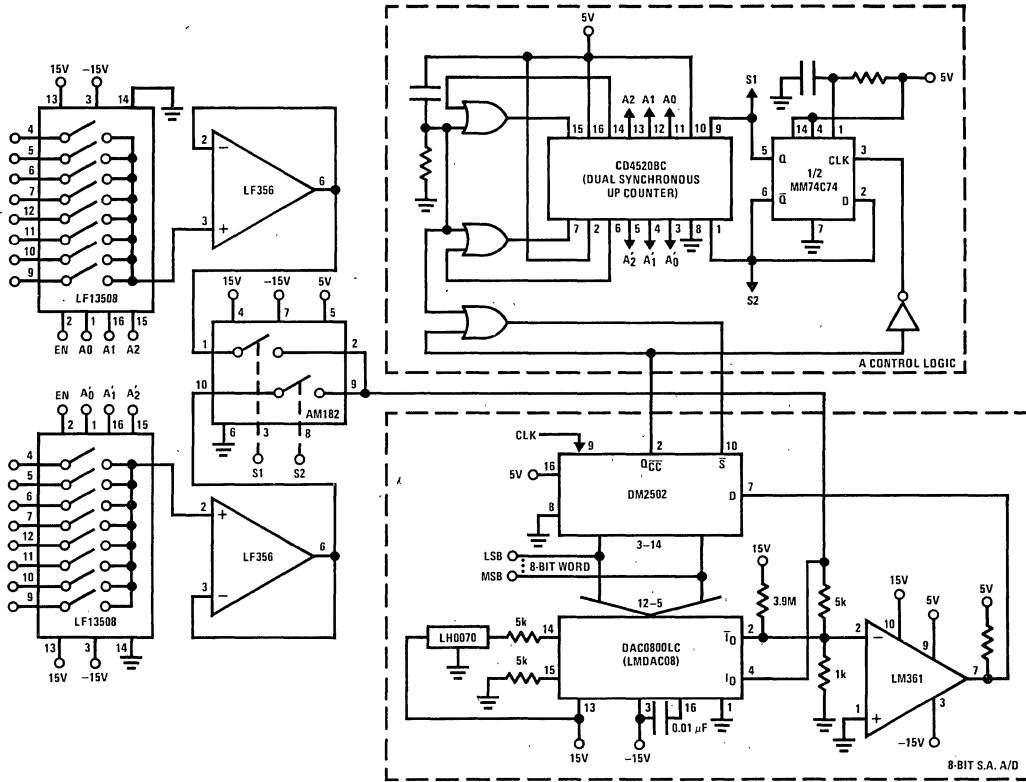


FIGURE 9a. A Fast 16-Channel DAU with Second Level Multiplexing

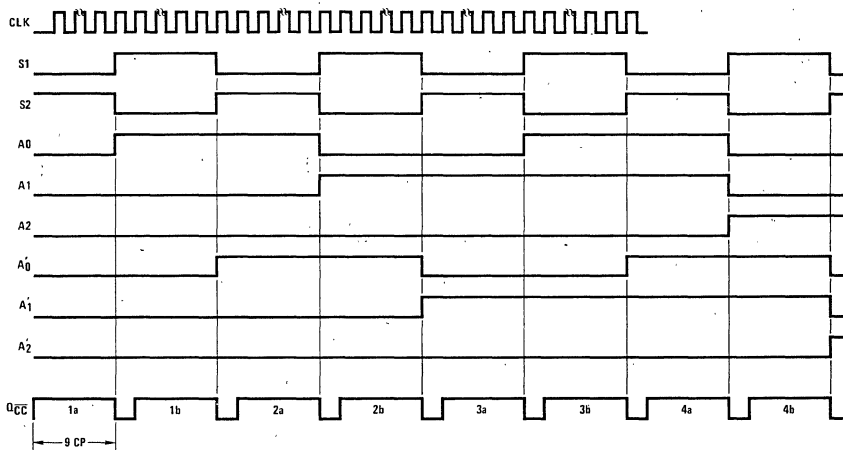


FIGURE 9b. Timing Diagram



Typical Applications (Continued)

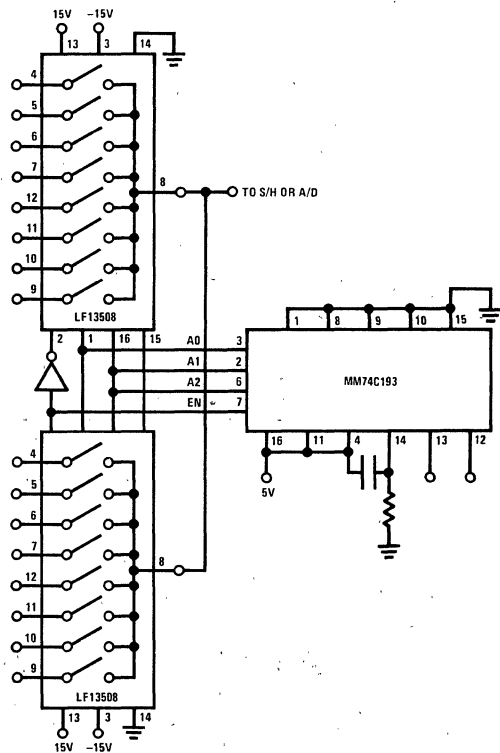
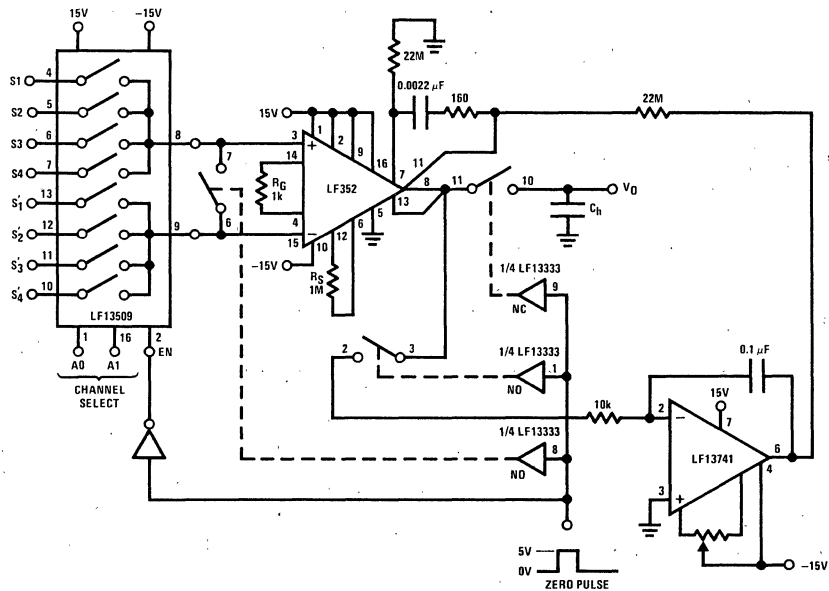


FIGURE 10. A 16-Channel Multiplexer with Sequential Multiplexing

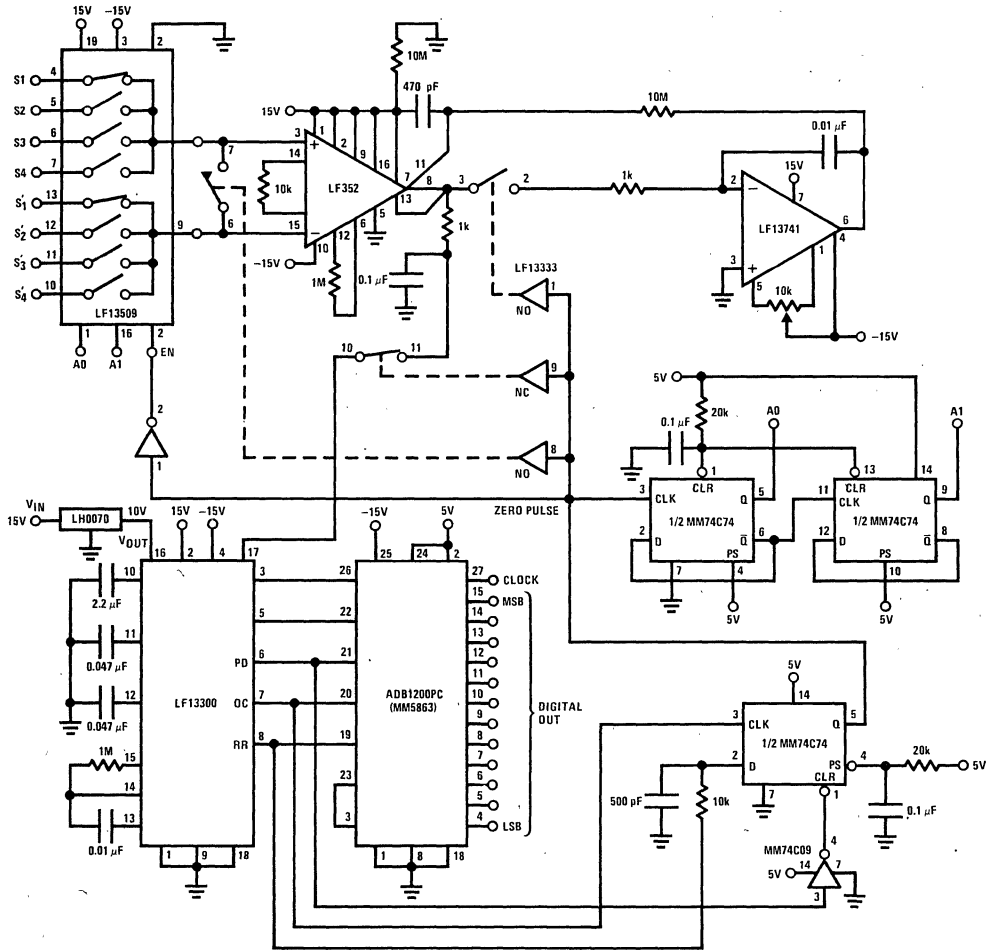


- Differential multiplexer disabled during auto zeroing
- Minimum zeroing pulse width will depend upon the integrator R1C
- This scheme provides input offset adjust especially useful with high gain connections. The device, LF352, provides pins for output offset adjust. For more details, see LF352 data sheet.

FIGURE 11. 4-Channel Differential Multiplexer with Auto Zeroed Instrumentation Amplifier

Typical Applications (Continued)

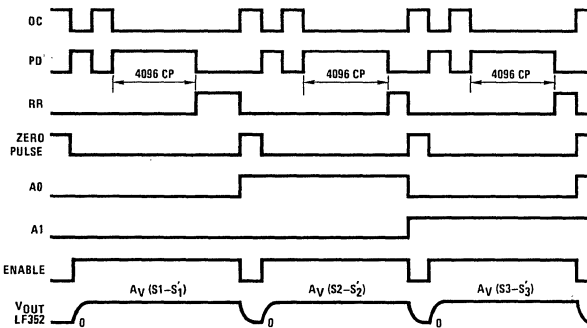
LF11508/LF13508, LF11509/LF13509



- $f_{CLOCK} \text{ max} = 200 \text{ kHz}$
- The LF352 instrumentation amplifier is auto zeroed during offset correction cycle of the LF13300 A/D
- The system accuracy will mostly depend on the instrumentation amplifier gain linearity

FIGURE 12a. 4-Channel Differential Multiplexer with Auto Zeroed Instrumentation Amplifier and 12-Bit A/D Converter

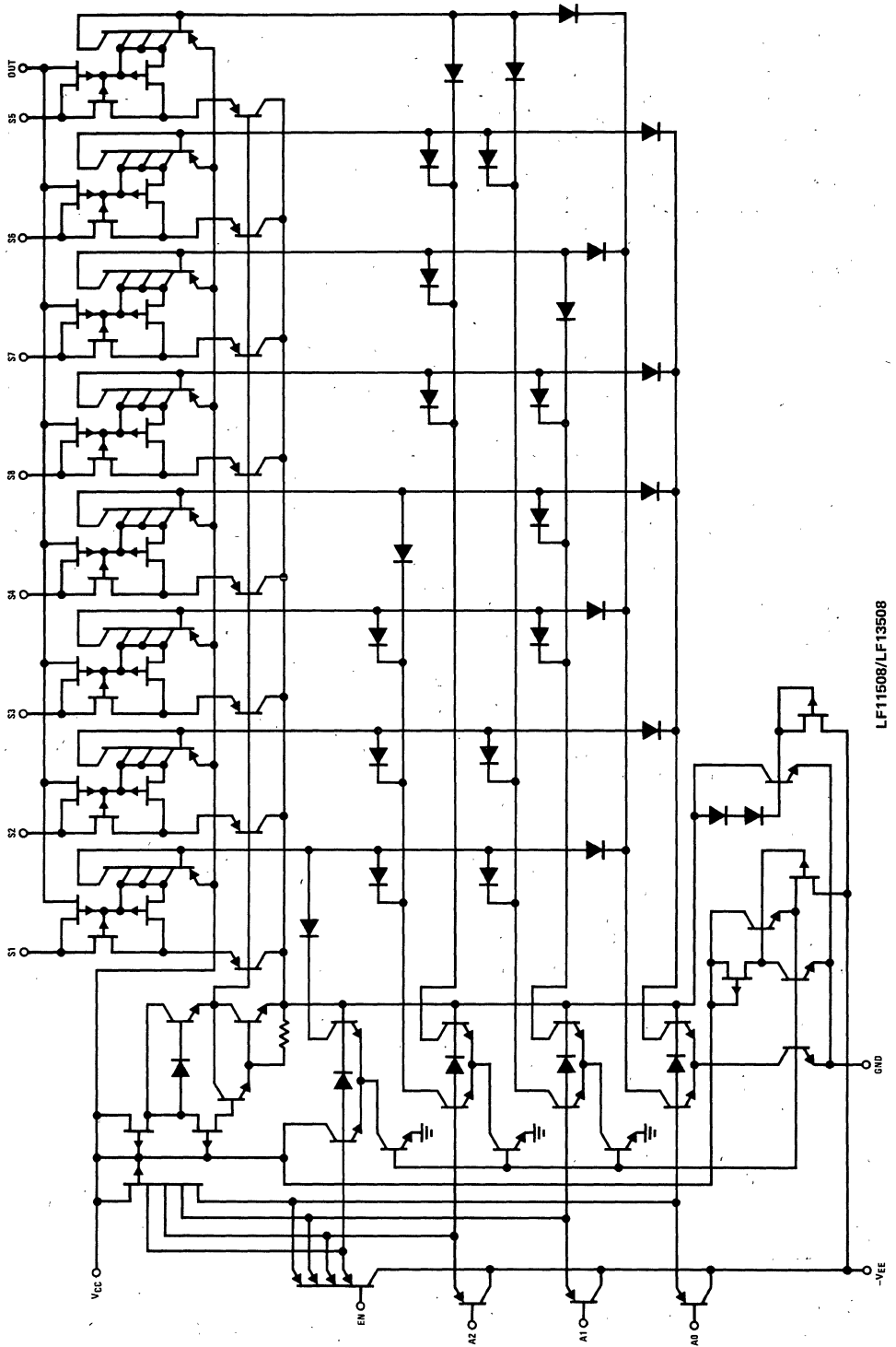
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PD: Polarity Detection
 OC: Offset Correction
 RR: Ramp Reference
 For more details, see LF13300 data sheet

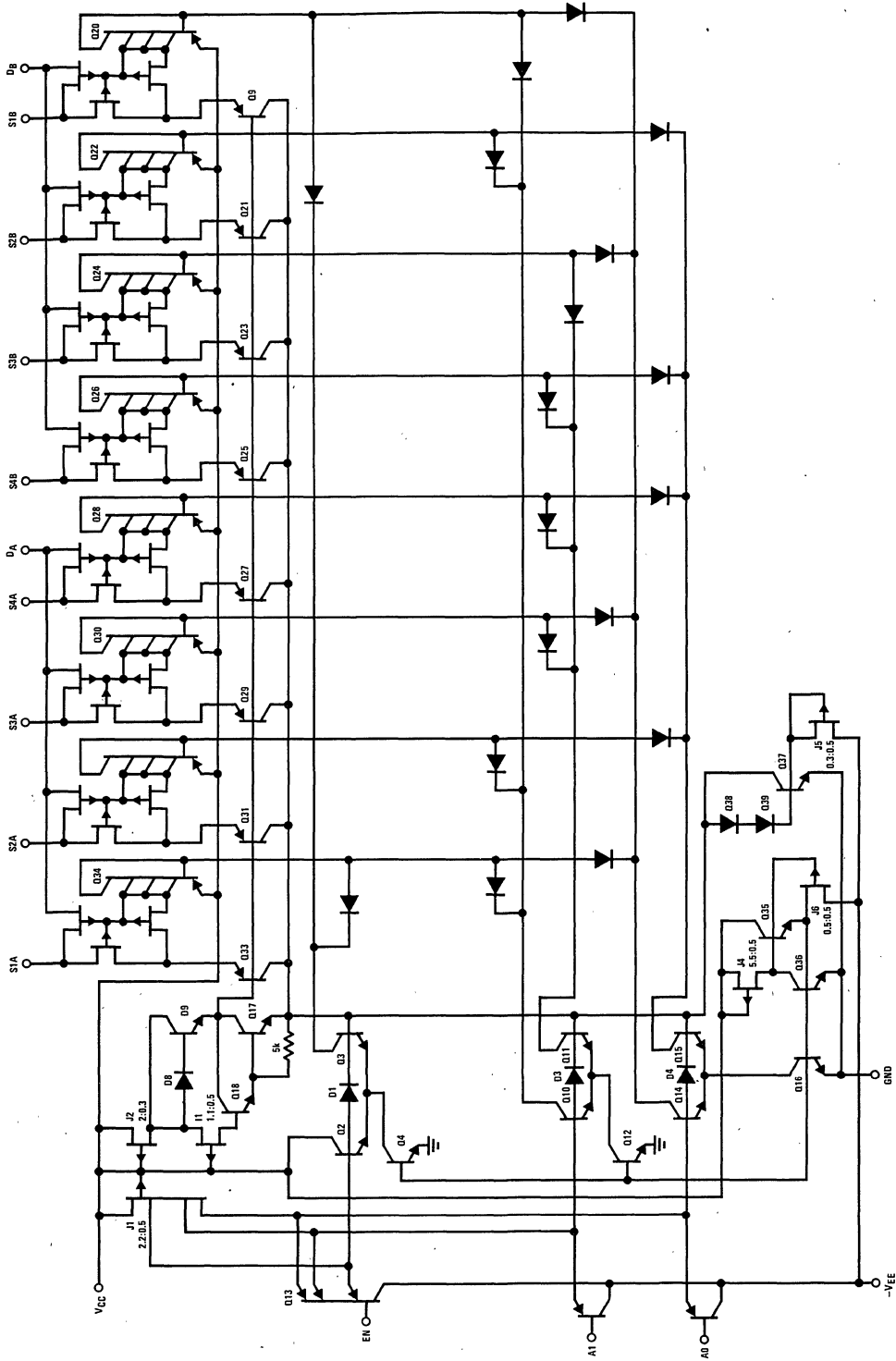
FIGURE 12b. System Timing Diagram for Differential MUX

Schematic Diagrams



LF11508/LF13508

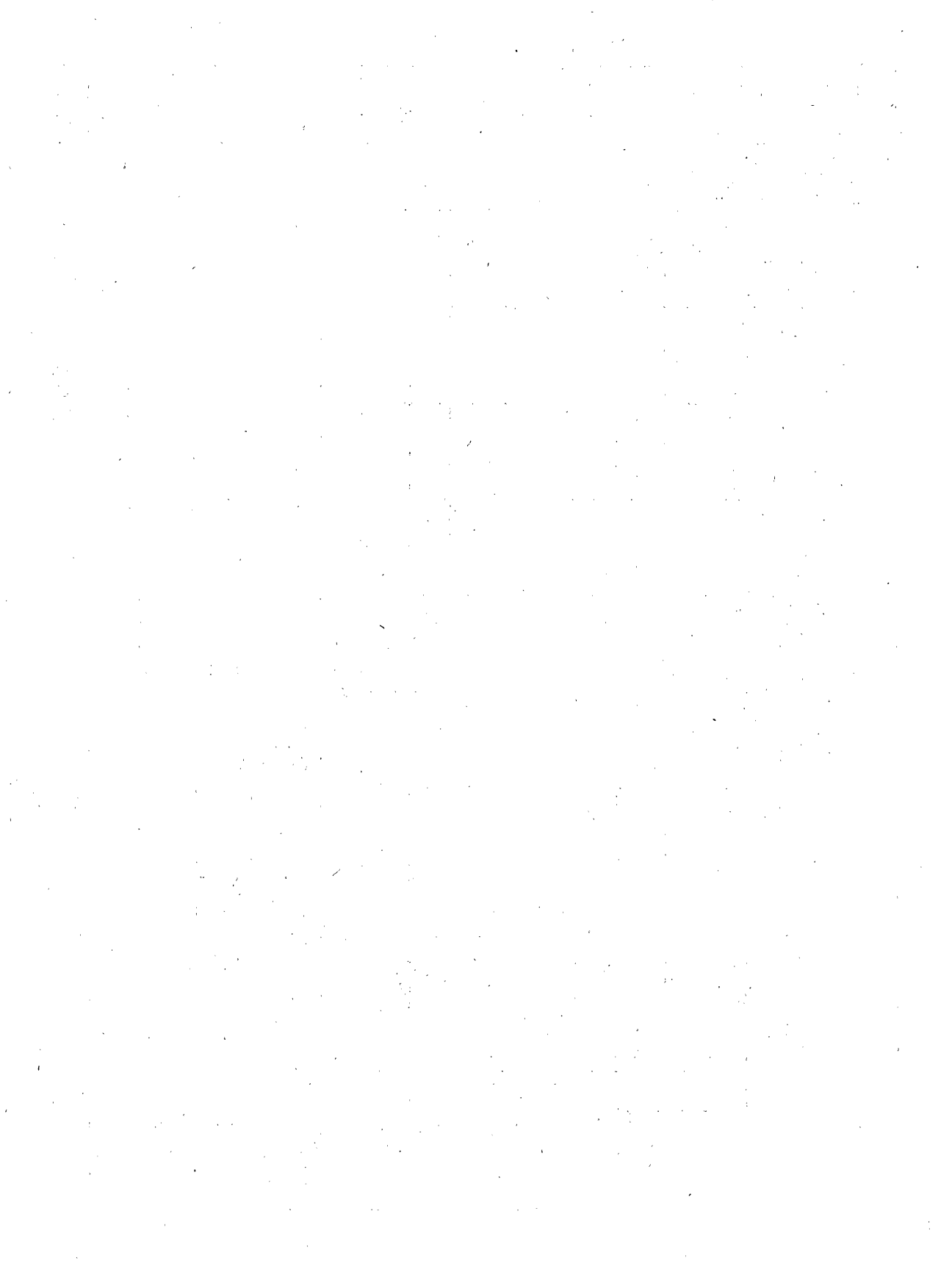
Schematic Diagrams (Continued)



LF1509/LF13509

LF1508/LF13508, LF1509/LF13509







Section 7



Sample and Hold



Section Contents

| | |
|---|-------|
| Sample and Hold Amplifier Guide..... | 7-iii |
| Definition of Terms..... | 7-iv |
| LF198/LF298/LF398, LF198A/LF398A Monolithic Sample and Hold Circuits..... | 7-1 |

Note. For additional information on sample and hold, see National Semiconductor's Special Functions Databook.

Each of these circuits includes input and output buffer amplifiers and analog switches for a complete sample and hold function.

| Features | Accuracy (Max) | Drift Rate ($T_A = 25^\circ\text{C}$) | Acquisition Time | Aperture Time | Part Number | | * Page Number |
|--------------|------------------------------|---|---|---------------|----------------|---------------|---------------|
| | | | | | -55°C to 125°C | -25°C to 85°C | |
| Monolithic | $\pm 0.02\%$ | 30 mV/s (Note 1) | 4 μs (Note 1) 20 μs (Note 2) | 25 ns | LF198 | LF298 | 7-1 |
| Low Drift | $\pm 0.01\%$ $\pm 0.02\%$ | 2 mV/s (Note 2) | 50 μs (Note 2) | 150 ns | LH0023G | LH0023CG | 4-4 |
| Medium Speed | $\pm 0.1\%$ $\pm 0.3\%$ | 25 mV/s (Note 1) | 10 μs (Note 1) | 20 ns | LH0043G | LH0043CG | 4-4 |
| High Speed | $\pm 0.2\%$ $\pm 0.3\%$ | 30 mV/s (Note 1) | 5 μs (Note 1) | 25 ns | LH0053G | LH0053CG | 4-12 |

Note 1: $C_S = 1000 \text{ pF}$.

Note 2: $C_S = 0.01 \mu\text{F}$.

*Refers to Special Functions Databook, 1979 edition

Definition of Terms

Acquisition Time: The time required to acquire a new analog input voltage with an output step of 10V. Note that acquisition time is not just the time required for the output to settle, but also includes the time required for all internal nodes to settle so that the output assumes the proper value when switched to the hold mode.

Aperture Time: The delay required between "Hold" command and an input analog transition, so that the transition does not affect the held output.

Dynamic Sampling Error: The error introduced into the held output due to a changing analog input at the time the hold command is given. Error is expressed in mV with a given hold capacitor value and input slew rate. Note that this error term occurs even for long sample times.

Gain Error: The ratio of output voltage swing to input voltage swing in the sample mode expressed as a percent difference.

Hold Settling Time: The time required for the output to settle within 1 mV of final value after the "hold" logic command.

Hold Step: The voltage step at the output of the sample and hold when switching from sample mode to hold mode with a steady (dc) analog input voltage. Logic swing is 5V.

LF198/LF298/LF398, LF198A/LF398A
Monolithic Sample and Hold Circuits
General Description

The LF198/LF298/LF398 are monolithic sample and hold circuits which utilize BI-FET technology to obtain ultra-high dc accuracy with fast acquisition of signal and low droop rate. Operating as a unity gain follower, dc gain accuracy is 0.002% typical and acquisition time is as low as 6 μ s to 0.01%. A bipolar input stage is used to achieve low offset voltage and wide bandwidth. Input offset adjust is accomplished with a single pin and does not degrade input offset drift. The wide bandwidth allows the LF198 to be included inside the feedback loop of 1 MHz op amps without having stability problems. Input impedance of 10¹⁰ Ω allows high source impedances to be used without degrading accuracy.

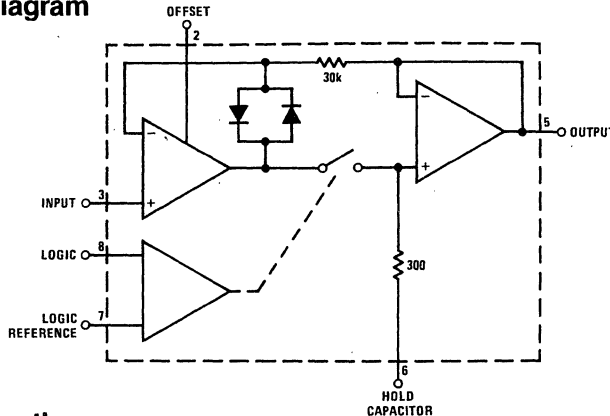
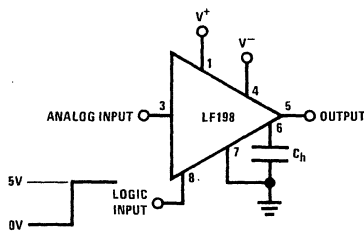
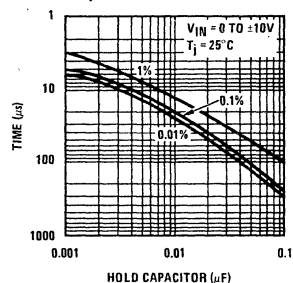
P-channel junction FET's are combined with bipolar devices in the output amplifier to give droop rates as low as 5 mV/min with a 1 μ F hold capacitor. The JFET's have much lower noise than MOS devices used in previous designs and do not exhibit high temperature instabilities. The overall design guarantees no feed-through from input to output in the hold mode even for input signals equal to the supply voltages.

Features

- Operates from $\pm 5V$ to $\pm 18V$ supplies
- Less than 10 μ s acquisition time
- TTL, PMOS, CMOS compatible logic input
- 0.5 mV typical hold step at $C_H = 0.01\mu F$
- Low input offset
- 0.002% gain accuracy
- Low output noise in hold mode
- Input characteristics do not change during hold mode
- High supply rejection ratio in sample or hold
- Wide bandwidth

Logic inputs on the LF198 are fully differential with low input current, allowing direct connection to TTL, PMOS, and CMOS. Differential threshold is 1.4V. The LF198 will operate from $\pm 5V$ to $\pm 18V$ supplies. It is available in an 8-lead TO-5 package.

An "A" version is available with tightened electrical specifications.

Functional Diagram

Typical Applications
Typical Connection

Acquisition Time


Absolute Maximum Ratings

| | |
|---|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation (Package Limitation) (Note 1) | 500 mW |
| Operating Ambient Temperature Range | |
| LF198/LF198A | -55°C to +125°C |
| LF298 | -25°C to +85°C |
| LF398/LF398A | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |

| | |
|--|-------------------------|
| Input Voltage | Equal to Supply Voltage |
| Logic To Logic Reference Differential Voltage (Note 2) | +7V, -30V |
| Output Short Circuit Duration | Indefinite |
| Hold Capacitor Short Circuit Duration | 10 sec |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 3)

| PARAMETER | CONDITIONS | LF198/LF298 | | | LF398 | | | UNITS |
|--|---|-------------|-----------|-------|-------|-----------|------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage, (Note 6) | $T_j = 25^\circ\text{C}$ | | 1 | 3 | | 2 | 7 | mV |
| | Full Temperature Range | | | 5 | | 10 | 10 | mV |
| Input Bias Current, (Note 6) | $T_j = 25^\circ\text{C}$ | | 5 | 25 | | 10 | 50 | nA |
| | Full Temperature Range | | | 75 | | | 100 | nA |
| Input Impedance | $T_j = 25^\circ\text{C}$ | | 10^{10} | | | 10^{10} | | Ω |
| Gain Error | $T_j = 25^\circ\text{C}, R_L = 10\text{k}$ | | 0.002 | 0.005 | | 0.004 | 0.01 | % |
| | Full Temperature Range | | | 0.02 | | | 0.02 | % |
| Feedthrough Attenuation Ratio at 1 kHz | $T_j = 25^\circ\text{C}, C_H = 0.01\mu\text{F}$ | 86 | 96 | | 80 | 90 | | dB |
| Output Impedance | $T_j = 25^\circ\text{C}$, "HOLD" mode | | 0.5 | 2 | | 0.5 | 4 | Ω |
| | Full Temperature Range | | | 4 | | | 6 | Ω |
| "HOLD" Step, (Note 4) | $T_j = 25^\circ\text{C}, C_H = 0.01\mu\text{F}, V_{\text{OUT}} = 0$ | | 0.5 | 2.0 | | 1.0 | 2.5 | mV |
| Supply Current, (Note 6) | $T_j \geq 25^\circ\text{C}$ | | 4.5 | 5.5 | | 4.5 | 6.5 | mA |
| Logic and Logic Reference Input Current | $T_j = 25^\circ\text{C}$ | | 2 | 10 | | 2 | 10 | μA |
| Leakage Current into Hold Capacitor (Note 6) | $T_j = 25^\circ\text{C}$, (Note 5) Hold Mode | | 30 | 100 | | 30 | 200 | pA |
| Acquisition Time to 0.1% | $\Delta V_{\text{OUT}} = 10\text{V}, C_H = 1000\text{ pF}$ | | 4 | | | 4 | | μs |
| | $C_H = 0.01\mu\text{F}$ | | 20 | | | 20 | | μs |
| Hold Capacitor Charging Current | $V_{\text{IN}} - V_{\text{OUT}} = 2\text{V}$ | | 5 | | | 5 | | mA |
| Supply Voltage Rejection Ratio | $V_{\text{OUT}} = 0$ | 80 | 110 | | 80 | 110 | | dB |
| Differential Logic Threshold | $T_j = 25^\circ\text{C}$ | 0.8 | 1.4 | 2.4 | 0.8 | 1.4 | 2.4 | V |

Electrical Characteristics (Continued) (Note 3)

| PARAMETER | CONDITIONS | LF198A | | | LF398A | | | UNITS |
|--|---|--------|------------------|-------|------------------|-------|---------------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Input Offset Voltage, (Note 6) | $T_j = 25^\circ\text{C}$ | | 1 | 1 | 2 | 2 | mV | |
| | Full Temperature Range | | | 2 | | 3 | mV | |
| Input Bias Current, (Note 6) | $T_j = 25^\circ\text{C}$ | | 5 | 25 | 10 | 25 | nA | |
| | Full Temperature Range | | | 75 | | 50 | nA | |
| Input Impedance | $T_j = 25^\circ\text{C}$ | | 10 ¹⁰ | | 10 ¹⁰ | | Ω | |
| Gain Error | $T_j = 25^\circ\text{C}, R_L = 10\text{k}$ | | 0.002 | 0.005 | 0.004 | 0.005 | % | |
| | Full Temperature Range | | | 0.01 | | 0.01 | % | |
| Feedthrough Attenuation Ratio at 1 kHz | $T_j = 25^\circ\text{C}, C_h = 0.01\mu\text{F}$ | 86 | 96 | | 86 | 90 | dB | |
| Output Impedance | $T_j = 25^\circ\text{C}$, "HOLD" mode | | 0.5 | 1 | 0.5 | 1 | Ω | |
| | Full Temperature Range | | | 4 | | 6 | Ω | |
| "HOLD" Step, (Note 4) | $T_j = 25^\circ\text{C}, C_h = 0.01\mu\text{F}, V_{\text{OUT}} = 0$ | | 0.5 | 1 | 1.0 | 1 | mV | |
| Supply Current, (Note 6) | $T_j \geq 25^\circ\text{C}$ | | 4.5 | 5.5 | 4.5 | 6.5 | mA | |
| Logic and Logic Reference Input Current | $T_j = 25^\circ\text{C}$ | | 2 | 10 | 2 | 10 | μA | |
| Leakage Current into Hold Capacitor (Note 6) | $T_j = 25^\circ\text{C}$, (Note 5) Hold Mode | | 30 | 100 | 30 | 100 | pA | |
| Acquisition Time to 0.1% | $\Delta V_{\text{OUT}} = 10\text{V}, C_h = 1000\text{pF}$ | | 4 | 6 | 4 | 6 | μs | |
| | $C_h = 0.01\mu\text{F}$ | | 20 | 25 | 20 | 25 | μs | |
| Hold Capacitor Charging Current | $V_{\text{IN}} - V_{\text{OUT}} = 2\text{V}$ | | 5 | | 5 | | mA | |
| Supply Voltage Rejection Ratio | $V_{\text{OUT}} = 0$ | 90 | 110 | | 90 | 110 | dB | |
| Differential Logic Threshold | $T_j = 25^\circ\text{C}$ | 0.8 | 1.4 | 2.4 | 0.8 | 1.4 | V | |

Note 1: The maximum junction temperature of the LF198/LF198A is 150°C , for the LF298, 115°C , and for the LF398/LF398A, 100°C . When operating at elevated ambient temperature, the power dissipation must be derated based on a thermal resistance (θ_{JA}) of 150°C/W .

Note 2: Although the differential voltage may not exceed the limits given, the common-mode voltage on the logic pins may be equal to the supply voltages without causing damage to the circuit. For proper logic operation, however, one of the logic pins must always be at least 2V below the positive supply and 3V above the negative supply.

Note 3: Unless otherwise specified, the following conditions apply. Unit is in "sample" mode, $V_S = \pm 15\text{V}$, $T_j = 25^\circ\text{C}$, $-11.5\text{V} \leq V_{\text{IN}} \leq +11.5\text{V}$, $C_h = 0.01\mu\text{F}$, and $R_L = 10\text{k}\Omega$. Logic reference voltage = 0V and logic voltage = 2.5V.

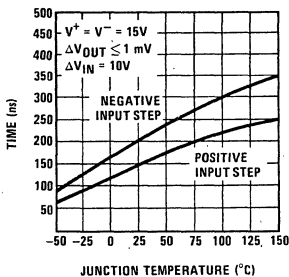
Note 4: Hold step is sensitive to stray capacitive coupling between input logic signals and the hold capacitor. 1 pF, for instance, will create an additional 0.5 mV step with a 5V logic swing and a $0.01\mu\text{F}$ hold capacitor. Magnitude of the hold step is inversely proportional to hold capacitor value.

Note 5: Leakage current is measured at a junction temperature of 25°C . The effects of junction temperature rise due to power dissipation or elevated ambient can be calculated by doubling the 25°C value for each 11°C increase in chip temperature. Leakage is guaranteed over full input signal range.

Note 6: These parameters guaranteed over a supply voltage range of ± 5 to $\pm 18\text{V}$.

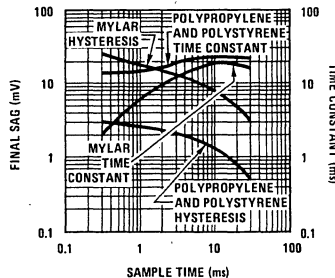
Typical Performance Characteristics

Aperture Time*

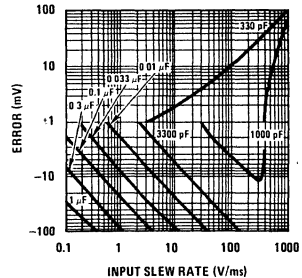


*See Definition of Terms

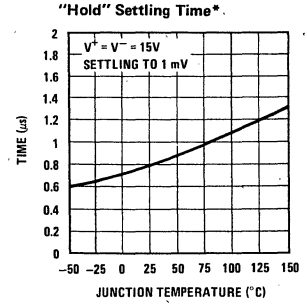
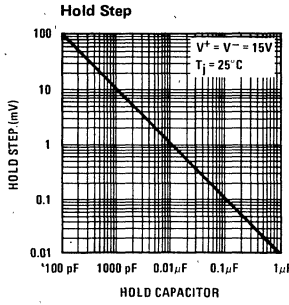
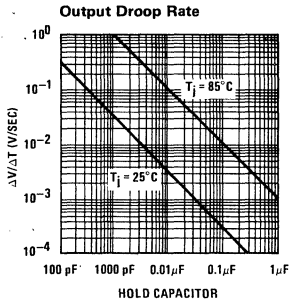
Capacitor Hysteresis



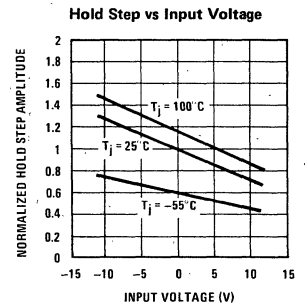
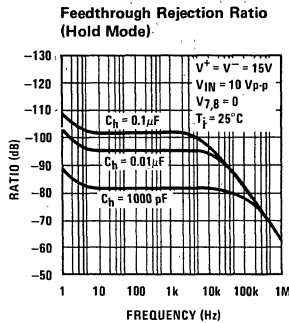
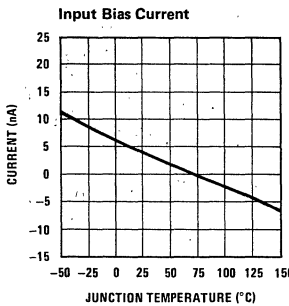
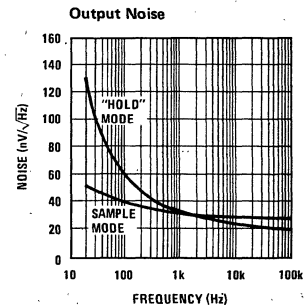
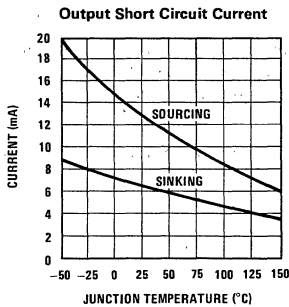
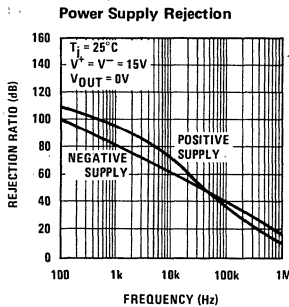
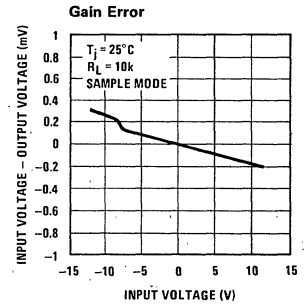
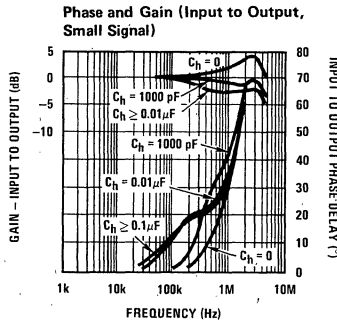
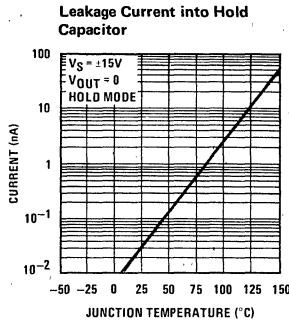
Dynamic Sampling Error



Typical Performance Characteristics (Continued)



*See definition



Application Hints

Hold Capacitor

Hold step, acquisition time, and droop rate are the major trade-offs in the selection of a hold capacitor value. Size and cost may also become important for larger values. Use of the curves included with this data sheet should be helpful in selecting a reasonable value of capacitance. Keep in mind that for fast repetition rates or tracking fast signals, the capacitor drive currents may cause a significant temperature rise in the LF198.

A significant source of error in an accurate sample and hold circuit is dielectric absorption in the hold capacitor. A mylar cap, for instance, may "sag back" up to 0.2% after a quick change in voltage. A long "soak" time is required before the circuit can be put back into the hold mode with this type of capacitor. Dielectrics with very low hysteresis are polystyrene, polypropylene, and Teflon. Other types such as mica and polycarbonate are not nearly as good. Ceramic is unusable with > 1% hysteresis. The advantage of polypropylene over polystyrene is that it extends the maximum ambient temperature from 85°C to 100°C. "NPO" or "COG" capacitors are now available for 125°C operation and also have low dielectric absorption. For more exact data, see the curve labeled dielectric absorption error vs sample time. The hysteresis numbers on the curve are final values, taken after full relaxation. The hysteresis error can be significantly reduced if the output of the LF198 is digitized quickly after the hold mode is initiated. The hysteresis relaxation time constant in polypropylene, for instance, is 10–50 ms. If A-to-D conversion can be made within 1 ms, hysteresis error will be reduced by a factor of ten.

DC and AC Zeroing

DC zeroing is accomplished by connecting the offset adjust pin to the wiper of a 1 kΩ potentiometer which has one end tied to V⁺ and the other end tied through a resistor to ground. The resistor should be selected to give ≈0.6 mA through the 1k potentiometer.

AC zeroing (hold step zeroing) can be obtained by adding an inverter with the adjustment pot tied input to output. A 10 pF capacitor from the wiper to the hold capacitor will give ±4 mV hold step adjustment with a 0.01μF hold capacitor and 5V logic supply. For larger logic swings, a smaller capacitor (< 10 pF) may be used.

Logic Rise Time

For proper operation, logic signals into the LF198 must have a minimum dV/dt of 1.0 V/μs. Slower signals will cause excessive hold step. If a R/C network is used in front of the logic input for signal delay, calculate the slope of the waveform at the threshold point to ensure that it is at least 1.0 V/μs.

Sampling Dynamic Signals

Sample error due to moving input signals probably causes more confusion among sample-and-hold users than any other parameter. The primary reason for this is that many users make the assumption that the sample and hold amplifier is truly locked on to the input signal while in the sample mode. In actuality, there are finite

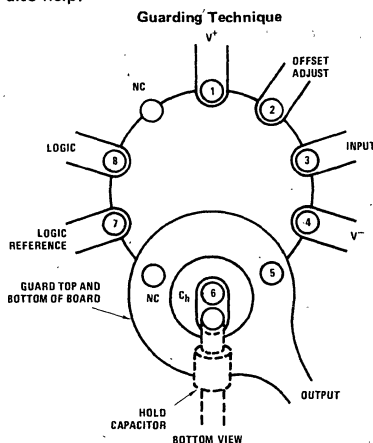
phase delays through the circuit creating an input-output differential for fast moving signals. In addition, although the output may have settled, the hold capacitor has an additional lag due to the 300Ω series resistor on the chip. This means that at the moment the "hold" command arrives, the hold capacitor voltage may be somewhat different than the actual analog input. The effect of these delays is opposite to the effect created by delays in the logic which switches the circuit from sample to hold. For example, consider an analog input of 20 Vp-p at 10 kHz. Maximum dV/dt is 0.6 V/μs. With no analog phase delay and 100 ns logic delay, one could expect up to (0.1μs)(0.6V/μs) = 60 mV error if the "hold" signal arrived near maximum dV/dt of the input. A positive-going input would give a +60 mV error. Now assume a 1 MHz (3 dB) bandwidth for the overall analog loop. This generates a phase delay of 160 ns. If the hold capacitor sees this exact delay, then error due to analog delay will be (0.16μs)(0.6 V/μs) = -96 mV. Total output error is +60 mV (digital) -96 mV (analog) for a total of -36 mV. To add to the confusion, analog delay is proportional to hold capacitor value while digital delay remains constant. A family of curves (dynamic sampling error) is included to help estimate errors.

A curve labeled Aperture Time has been included for sampling conditions where the input is steady during the sampling period, but may experience a sudden change nearly coincident with the "hold" command. This curve is based on a 1 mV error fed into the output.

A second curve, Hold Settling Time indicates the time required for the output to settle to 1 mV after the "hold" command.

Digital Feedthrough

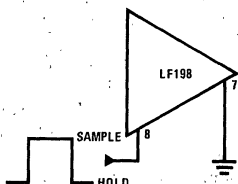
Fast rise time logic signals can cause hold errors by feeding externally into the analog input at the same time the amplifier is put into the hold mode. To minimize this problem, board layout should keep logic lines as far as possible from the analog input. Grounded guarding traces may also be used around the input line, especially if it is driven from a high impedance source. Reducing high amplitude logic signals to 2.5V will also help.



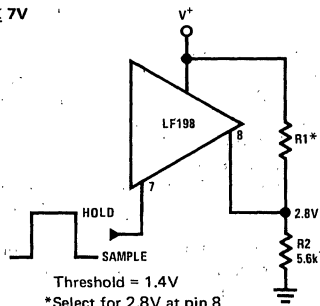
Use 10-pin layout. Guard around C_H is tied to output.

Logic Input Configurations

TTL & CMOS
 $3V \leq V_L \text{ (Hi State)} \leq 7V$

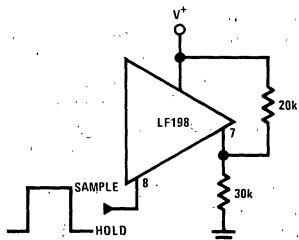


Threshold = 1.4V

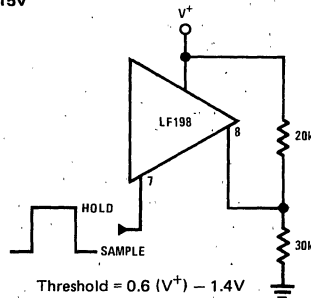


Threshold = 1.4V
 *Select for 2.8V at pin 8

CMOS
 $7V \leq V_L \text{ (Hi State)} \leq 15V$

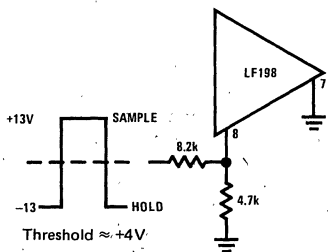


Threshold = $0.6 (V^+) + 1.4V$

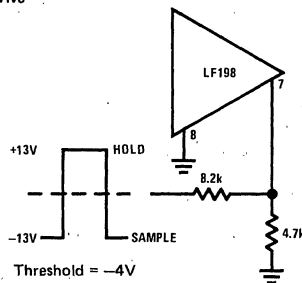


Threshold = $0.6 (V^+) - 1.4V$

Op Amp Drive



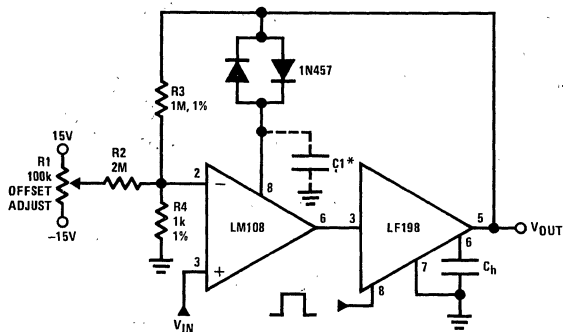
Threshold $\approx +4V$



Threshold = $-4V$

Typical Applications (Continued)

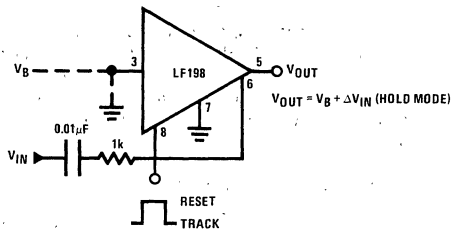
X1000 Sample & Hold



*For lower gains, the LM108 must be frequency compensated

Use $\approx \frac{100}{A_V}$ pF from comp 2 to ground

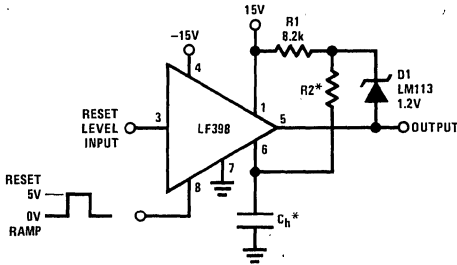
Sample and Difference Circuit (Output Follows Input in Hold Mode)



$V_{OUT} = V_B + \Delta V_{IN} \text{ (HOLD MODE)}$

Typical Applications (Continued)

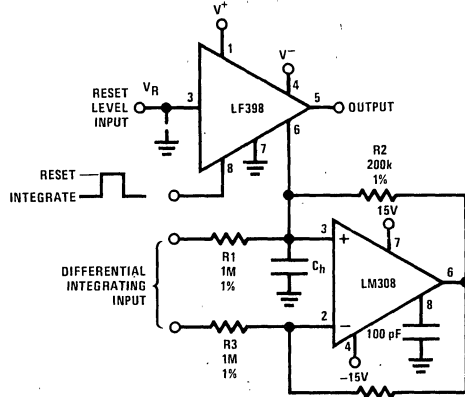
Ramp Generator with Variable Reset Level



*Select for ramp rate
 $R \geq 10k$

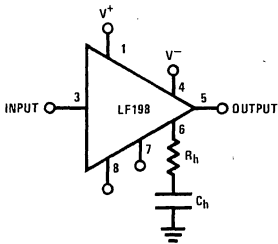
$$\frac{\Delta V}{\Delta T} = \frac{1.2V}{(R2)(Ch)}$$

Integrator with Programmable Reset Level



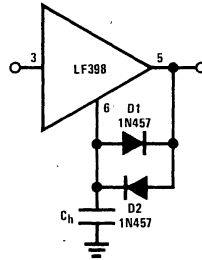
$$V_{OUT} \text{ (Hold Mode)} = \left[\frac{1}{(R1)(Ch)} \int_0^t V_{IN} dt \right] + \left[V_R \right]$$

Output Holds at Average of Sampled Input

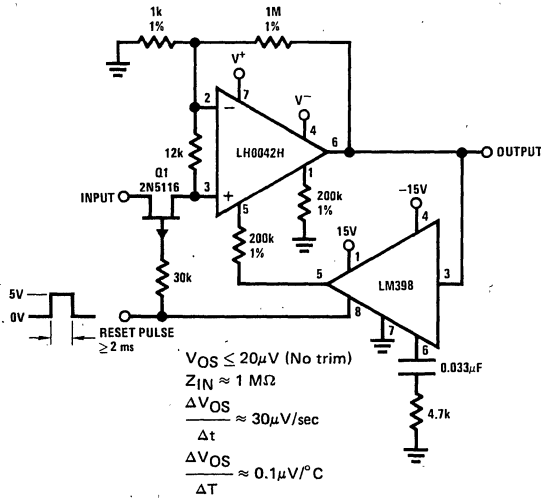


$$\text{Select } (R_h)(C_h) \gg \frac{1}{2\pi f_{IN} \text{ (Min)}}$$

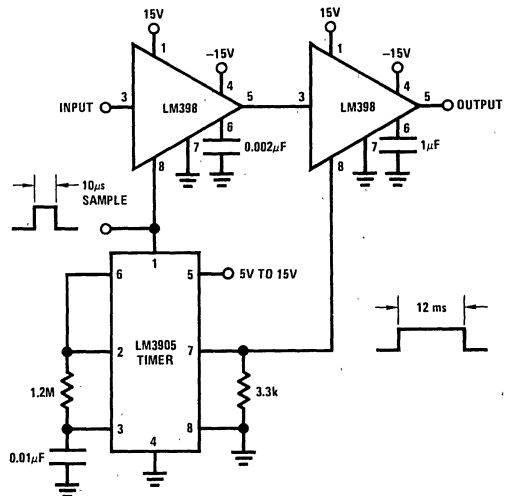
Increased Slew Current



Reset Stabilized Amplifier (Gain of 1000)

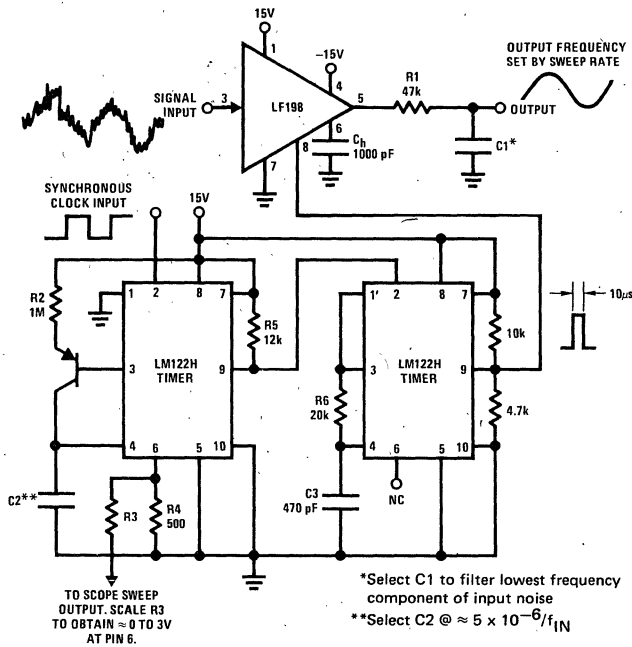


Fast Acquisition, Low Droop Sample & Hold

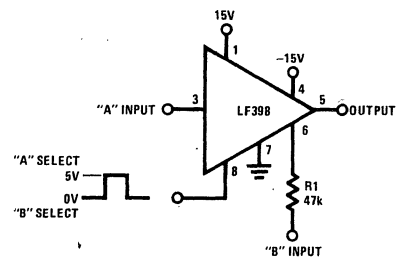


Typical Applications (Continued)

Synchronous Correlator for Recovering Signals Below Noise Level

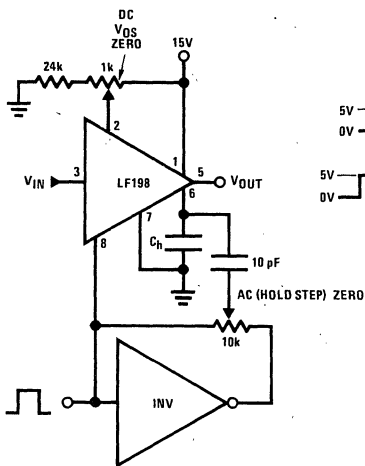


2-Channel Switch

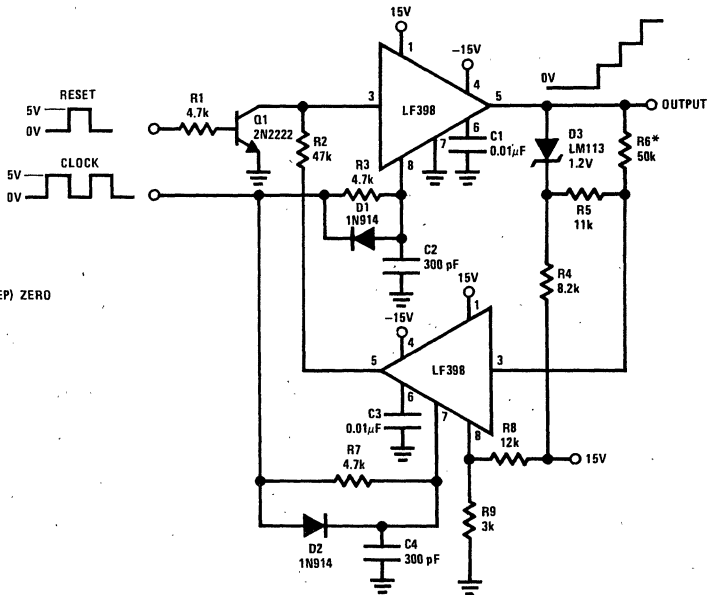


| | A | B |
|-------------------|------------------|-------------------|
| Gain | $1 \pm 0.02\%$ | $1 \pm 0.2\%$ |
| Z_{IN} | $10^{10} \Omega$ | 47 k Ω |
| BW | ≈ 1 MHz | ≈ 400 kHz |
| Crosstalk @ 1 kHz | -90 dB | -90 dB |
| Offset | ≤ 6 mV | ≤ 75 mV |

DC & AC Zeroing



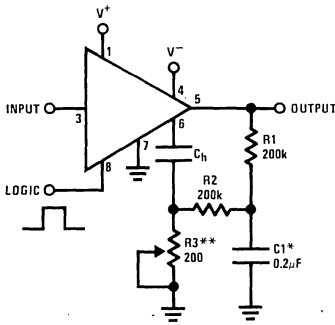
Staircase Generator



*Select for step height 50k $\rightarrow \approx 1$ V Step

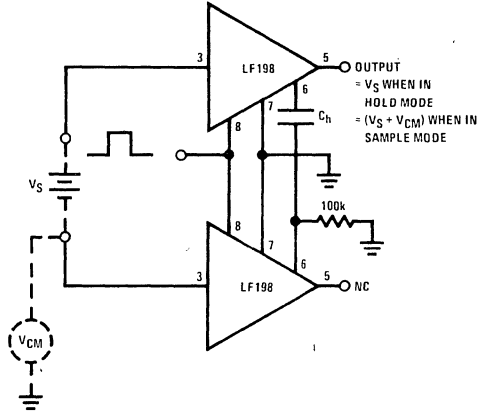
Typical Applications (Continued)

Capacitor Hysteresis Compensation



*Select for time constant $C1 = \frac{T}{100k}$
 **Adjust for amplitude

Differential Hold



Definition of Terms

Hold Step: The voltage step at the output of the sample and hold when switching from sample mode to hold mode with a steady (dc) analog input voltage. Logic swing is 5V.

Acquisition Time: The time required to acquire a new analog input voltage with an output step of 10V. Note that acquisition time is not just the time required for the output to settle, but also includes the time required for all internal nodes to settle so that the output assumes the proper value when switched to the hold mode.

Gain Error: The ratio of output voltage swing to input voltage swing in the sample mode expressed as a per cent difference.

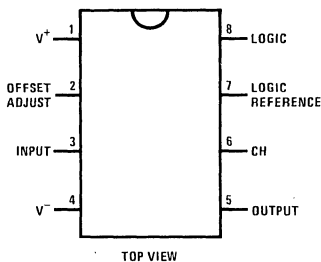
Hold Settling Time: The time required for the output to settle within 1 mV of final value after the "hold" logic command.

Dynamic Sampling Error: The error introduced into the held output due to a changing analog input at the time the hold command is given. Error is expressed in mV with a given hold capacitor value and input slew rate. Note that this error term occurs even for long sample times.

Aperture Time: The delay required between "Hold" command and an input analog transition, so that the transition does not affect the held output.

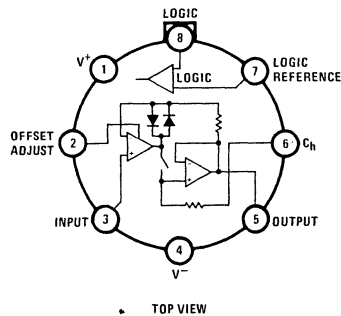
Connection Diagrams

Dual-In-Line Package



Order Number LF398N or LF398AN
 See NS Package N08A

Metal Can Package



Order Number LF198H, LF298H, LF398H,
 LF198AH or LF398AH
 See NS Package H08C



Section 8

A to D, D to A





Section Contents

| | |
|--|-------|
| A/D Converter/DVM Selection Guide..... | 8-iii |
| D/A Converter Selection Guide..... | 8-iv |
| General Data Acquisition System Block Diagram/Part Numbering System..... | 8-v |
| Definition of Terms..... | 8-vi |
| D/A Converters | |
| AD7520/AD7530/AD7533 10-Bit Binary Multiplying D/A Converter..... | 8-1 |
| AD7521/AD7531 12-Bit Binary Multiplying D/A Converter..... | 8-1 |
| DAC0800 (LMDAC08) 8-Bit Digital-to-Analog Converter..... | 8-77 |
| DAC0808, DAC0807, DAC0806 8-Bit D/A Converters..... | 8-85 |
| DAC1000 thru DAC1008 10-Bit, μ P Compatible, Double-Buffered D to A Converters..... | 8-92 |
| DAC1020 10-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1200/DAC1201 12-Bit (Binary) Digital-to-Analog Converters..... | 8-124 |
| DAC1202/DAC1203 3-Digit (BCD) Digital-to-Analog Converters..... | 8-124 |
| DAC1220 12-Bit Binary Multiplying D/A Converter..... | 8-114 |
| DAC1280, DAC1285 12-Bit (Binary) Digital-to-Analog Converters..... | 8-131 |
| DAC1286, DAC1287 3-Digit (BCD) Digital-to-Analog Converters..... | 8-131 |
| LM1508/LM1408 8-Bit D/A Converter..... | 8-173 |
| A/D Converters | |
| ADC0800 (MM4357B/MM5357B) 8-Bit A/D Converter..... | 8-10 |
| ADC0801, ADC0802, ADC0803, ADC0804 8-Bit μ P Compatible A/D Converters..... | 8-21 |
| ADC0808, ADC0809 8-Bit μ P Compatible A/D Converters with 8-Channel Multiplexer..... | 8-45 |
| ADC0816, ADC0817 8-Bit μ P Compatible A/D Converters with 16-Channel Multiplexer..... | 8-56 |
| ADC1210, ADC1211 12-Bit CMOS A/D Converters..... | 8-67 |
| Building Blocks | |
| ADB1200 (MM5863) 12-Bit Binary A/D Building Block..... | 8-3 |
| DM2502, DM2503, DM2504 Successive Approximation Registers..... | 8-139 |
| LF13300 Integrating A/D Analog Building Block..... | 8-144 |
| LM131A/LM131, LM231A/LM231, LM331A/LM331 Precision Voltage-to-Frequency Converters..... | 8-162 |
| MM54C905/MM74C905 12-Bit Successive Approximation Register..... | 8-175 |
| TP3000 CODEC System (TP3001 μ -Law, TP3002 A-Law)..... | 8-180 |

†For additional information, see National Semiconductor's Data Acquisition Handbook.

| Part No. | Resolution (Bits) | Absolute Accuracy (Max.) | Conversion Time (Typ.) | Input Voltage Range | Output Logic Levels | Supplies (V) | Temperature Range (Note 1) | | | Package | Comments |
|--------------------------|-------------------|--------------------------|------------------------|---------------------|---------------------|----------------|----------------------------|---|---|--------------------------|--|
| | | | | | | | M | I | C | | |
| A/D Converter | | | | | | | | | | | |
| ADC0800 | 8 | ±2 LSB | 35 μs | 10V | TTL, Tri-State* | +5, -12 | • | • | | 18-Pin DIP | |
| ADC0801 | 8 | ±¼ LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 20-Pin DIP | Differential Input |
| ADC0802 | 8 | ±½ LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 20-Pin DIP | Differential Input |
| ADC0803 | 8 | ±½ LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 20-Pin DIP | Differential Input |
| ADC0804 | 8 | ±1 LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 20-Pin DIP | Differential Input |
| ADC0808 | 8 | ±½ LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 28-Pin DIP | Includes 8-Channel MUX |
| ADC0809 | 8 | ±1 LSB | 100 μs | 5V | TTL, Tri-State | +5 | | • | • | 28-Pin DIP | Includes 8-Channel MUX |
| ADC0816 | 8 | ±½ LSB | 100 μs | 5V | TTL, Tri-State | +5 | • | • | • | 40-Pin DIP | Includes 16-Channel MUX |
| ADC0817 | 8 | ±1 LSB | 100 μs | 5V | TTL, Tri-State | +5 | | • | • | 40-Pin DIP | Includes 16-Channel MUX |
| ADB1200 LF13300 | 12 | ±1/2 LSB | 36 ms | ±11V | TTL, Tri-State | +5, -15 ±15 | | | • | 28-Pin DIP 18-Pin DIP | Dual Slope |
| ADC1210 | 12 | ±1/2 LSB | 100 μs | 10.2V | CMOS | +5 to ±15 | • | • | | 24-Pin DIP | 10-Bit Conversion in 30 μs |
| ADC1211 | 12 (10) | ±1 LSB | 100 μs | 10.2V | CMOS | +5 to ±15 | • | • | | 24-Pin DIP | |
| ADC3511 | 3½ Digit | .05% | 200 ms | 2V | TTL, Tri-State | +5 | | | • | 24-Pin DIP | Integrating μP Compatible |
| ADC3711 | 3¾ Digit | .05% | 400 ms | 2V | TTL, Tri-State | +5 | | | • | 24-Pin DIP | Integrating μP Compatible |
| LM131 | V-F | .01% | N/A | V _{CC} -2V | N/A | +5 to +40 | • | • | • | 8-Pin DIP or TO-99 Can | Voltage-to-Frequency Converter 100kHz Max |
| Digital Voltmeter | | | | | | | | | | | |
| ADD3501 | 3½ Digit | .05% | 200 ms | V _{CC} -2V | 7-Segment LED Drive | +5 | | | • | 28-Pin DIP | 3½ Digit LED DPM |
| ADD3701 | 3¾ Digit | .05% | 400 ms | V _{CC} -2V | 7-Segment LED Drive | +5 | | | • | 28-Pin DIP | 3¾ Digit LED DPM |

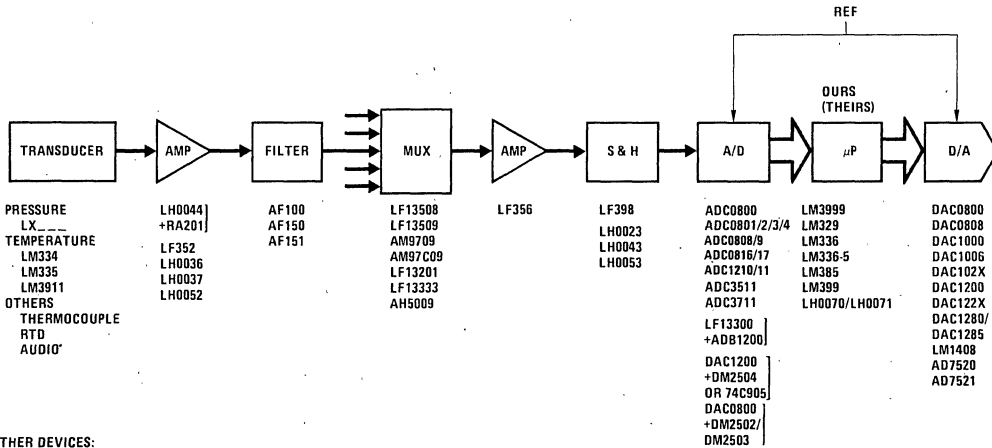
Note 1: Temperature ranges are: "M" is -55°C to +125°C ambient; "I" is -40°C to +85°C or -25°C to +85°C; "C" is 0°C to 70°C.

D/A Converter Selection Guide

| Part No. | Resolution (Bits) | Linearity @ 25°C (Max) | Internal Reference | Output Op Amp | Settling Time ($\pm 1/2$ LSB) | Supplies (V) | Temperature Range (Note 1) | | | Package | Comments |
|----------|-------------------|------------------------|--------------------|---------------|--------------------------------|---------------------|----------------------------|---|---|------------|------------------------------------|
| | | | | | | | M | I | C | | |
| DAC0800 | 8 | .19 | | | 135 ns | ± 5 to ± 15 | • | • | | 16-Pin DIP | High-Speed Multiplying |
| DAC0801 | 8 | .39 | | | 150 ns | ± 5 to ± 15 | • | • | | 16-Pin DIP | High-Speed Multiplying |
| DAC0802 | 8 | .1 | | | 135 ns | ± 5 to ± 15 | • | • | | 16-Pin DIP | High-Speed Multiplying |
| DAC0806 | 8 | .78 | | | 150 typ | ± 5 to ± 15 | | • | | 16-Pin DIP | Multiplying |
| DAC0807 | 8 | .39 | | | 150 typ | ± 5 to ± 15 | | • | | 16-Pin DIP | Multiplying |
| DAC0808 | 8 | .19 | | | 150 typ | ± 5 to ± 15 | • | • | | 16-Pin DIP | Multiplying |
| DAC1000 | 10 | .05 | | | 500 ns typ | 5 to 15 | • | • | • | 24-Pin DIP | μ P Compatible Double Buffered |
| DAC1001 | 10 | .1 | | | 500 ns typ | 5 to 15 | | • | • | 24-Pin DIP | μ P Compatible Double Buffered |
| DAC1002 | 10 | .2 | | | 500 ns typ | 5 to 15 | | • | • | 24-Pin DIP | μ P Compatible Double Buffered |
| DAC1006 | 10 | .05 | | | 500 ns typ | 5 to 15 | • | • | • | 20-Pin DIP | μ P Compatible Double Buffered |
| DAC1007 | 10 | .1 | | | 500 ns typ | 5 to 15 | | • | • | 20-Pin DIP | μ P Compatible Double Buffered |
| DAC1008 | 10 | .2 | | | 500 ns typ | 5 to 15 | | • | • | 20-Pin DIP | μ P Compatible Double Buffered |
| DAC1020 | 10 | .05 | | | 500 ns typ | 5 to 15 | • | • | • | 16-Pin DIP | 4-Quadrant Multiplying |
| DAC1021 | 10 | .1 | | | 500 ns typ | 5 to 15 | • | • | • | 16-Pin DIP | 4-Quadrant Multiplying |
| DAC1022 | 10 | .2 | | | 500 ns typ | 5 to 15 | • | • | • | 16-Pin DIP | 4-Quadrant Multiplying |
| DAC1200 | 12 | .012 | • | • | 1.5-2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | Current or Voltage Mode |
| DAC1201 | 12 | .049 | • | • | 1.5-2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | Current or Voltage Mode |
| DAC1202 | 3 Digit | .01 | • | • | 1.5-2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | BCD Current or Voltage Mode |
| DAC1203 | 3 Digit | .05 | • | • | 1.5-2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | BCD Current or Voltage Mode |
| DAC1220 | 12 | .05 | | | 500 ns typ | 5 to 15 | • | • | • | 18-Pin DIP | 4-Quadrant Multiplying |
| DAC1221 | 12 | .1 | | | 500 ns typ | 5 to 15 | • | • | • | 18-Pin DIP | 4-Quadrant Multiplying |
| DAC1222 | 12 | .2 | | | 500 ns typ | 5 to 15 | • | • | • | 18-Pin DIP | 4-Quadrant Multiplying |
| DAC1280 | 12 | .024 | • | • | 300 ns/2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | Current or Voltage Mode |
| DAC1285 | 12 | .012 | • | • | 300 ns/2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | Current or Voltage Mode |
| DAC1286 | 12 | .05 | • | • | 300 ns/2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | BCD Current or Voltage Mode |
| DAC1287 | 12 | .1 | • | • | 300 ns/2.5 μ s | ± 15 , 5 | • | • | | 24-Pin DIP | BCD Current or Voltage Mode |

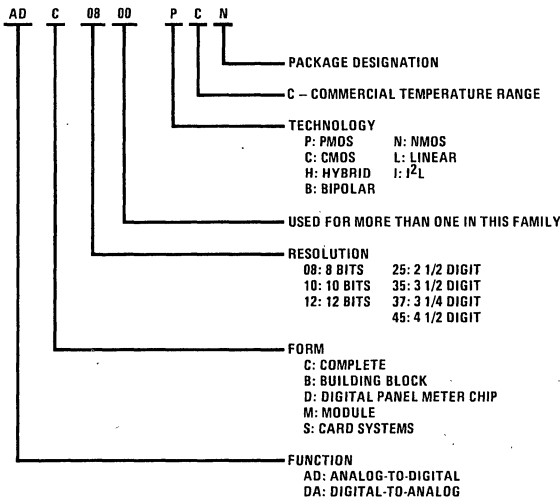
Note 1: Ambient temperature range for "M" is -55°C to $+125^{\circ}\text{C}$, "I" is -25°C to $+85^{\circ}\text{C}$, "C" is 0°C to $+70^{\circ}\text{C}$.

General Data Acquisition System Block Diagram



OTHER DEVICES:
 LM331 PRECISION VOLTAGE-TO-FREQUENCY CONVERTER
 ADS1216 16-CHANNEL 12-BIT DATA ACQUISITION SYSTEM WITH MEMORY

Converter Products Part Numbering System



Definition of Terms

Full-Scale Error: Full-scale error is a measure of the output error between an ideal D/A and the actual device output. Ideally for the DAC1200 full-scale is $V_{REF} - 1 \text{ LSB}$. For $V_{REF} = 10.240\text{V}$ and unipolar operation, $V_{FULLSCALE} = 10.240\text{V} - 2.5 \text{ mV} = 10.2375\text{V}$. Departures from this value include internal gain, scaling, and reference errors. Full-scale error is adjustable as discussed in the Applications section.

Linearity Error: Linearity error is the maximum deviation from a straight line passing through the endpoints of the D/A transfer characteristic. It is measured after calibrating for zero and full-scale. The linearity error of the DAC1200 series is guaranteed to be less than $\pm\frac{1}{2} \text{ LSB}$ or 0.0122% of F.S. for the DAC1200/DAC1200C and $\pm 0.0488\%$ of F.S. for the DAC1201/DAC1201C. Linearity error is a design parameter intrinsic to the device and cannot be externally adjusted.

Monotonicity: Monotonicity is a characteristic of the D/A which requires a non-negative output step for an increasing input digital code. Monotonicity, therefore, demands no back steps or sign changes of the D/A transfer characteristic slope.

Offset Voltage: Offset voltage is an output voltage other than zero volts for unipolar operation (and other than minus full-scale for bipolar operation) with all bits turned "OFF". In the DAC1200 series this error resides primarily in the output amplifier, A3. Offset voltage is adjustable to zero as discussed in the applications section.

Power Supply Sensitivity: Power supply sensitivity is a measure of the effect of power supply changes on the D/A full-scale output.

Resolution: Resolution is defined as the reciprocal of the number of discrete steps in the D/A output (as designed). It is directly related to the number of switches or bits within the D/A. For example, the DAC1200 has 2^{12} or 4096 steps. Resolution may therefore be expressed variously as 12 bits, as 1 part in 2^{12} , as 1 part in 4096, or as a percentage ($1/4096 \times 100 = 0.0244\%$). The DAC1202 has 1000 steps and 3 BCD digits. Resolution may be expressed as 0.1% or 3 BCD digits.

Settling Time: Two settling time parameters are specified for the DAC1200 series. Full-scale settling time requires a zero to full-scale or full-scale to zero output change. One LSB settling time requires one LSB output change. In both instances, settling time is the time required from a code transition until the D/A output reaches within $\pm\frac{1}{2} \text{ LSB}$ of final output value.

AD7520/AD7530/AD7533 10-Bit, AD7521/AD7531 12-Bit Binary Multiplying D/A Converters

General Description

The AD7520 and the AD7521 are, respectively, 10 and 12-bit binary multiplying digital-to-analog converters. A deposited thin film R-2R resistor ladder divides the reference current and provides the circuit with excellent temperature tracking characteristics (typically 0.0002%/°C linearity error temperature coefficient). The circuit uses CMOS current switches and drive circuitry to achieve low power consumption (30 mW max) and low leakages (200 nA max). The digital inputs are compatible with DTL/TTL logic levels as well as full CMOS logic level swings. This part, combined with an external amplifier and voltage reference, can be used as a standard D/A converter; however, it is also very attractive for multiplying applications (such as digitally controlled gain blocks) since its linearity error is essentially independent of the voltage reference.

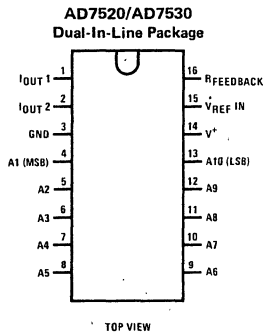
This part is available with 10-bit (0.05%), 9-bit (0.10%), and 8-bit (0.20%) non-linearity. The AD7520L, AD7520K, and AD7520J are direct replacements for

the 10-bit resolution AD7520 and AD7530 family, and equivalent to AD7533 family. The AD7521K, AD7521J and AD7521L are direct replacements for the 12-bit resolution AD7521 and AD7531 family. For more information, see DAC1020 data sheet.

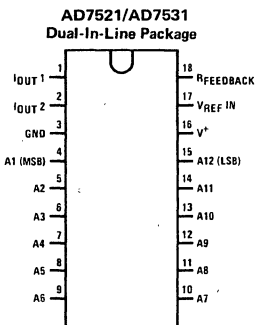
Features

- Linearity specified with zero and full-scale adjust only
- Integrated thin film on CMOS structure
- 10-bit or 12-bit resolution
- Low power dissipation 10 mW @ 15V typ
- Accepts variable or fixed reference $-25V \leq V_{REF} \leq +25V$
- 4-quadrant multiplying capability
- Interfaces directly with DTL, TTL and CMOS
- Fast settling time—600 ns typ
- Low feedthrough error—1/2 LSB @ 100 kHz typ

Connection Diagrams

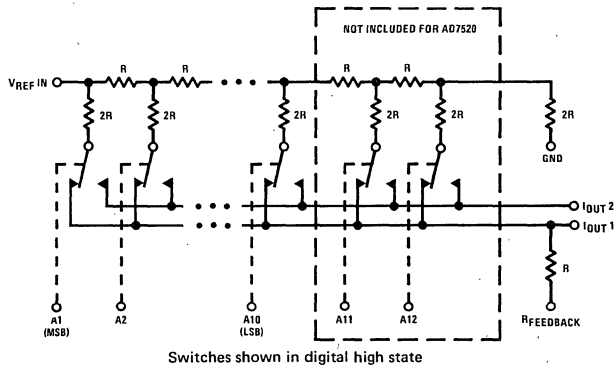


TOP VIEW



TOP VIEW

Equivalent Circuit



Switches shown in digital high state

Ordering Information*

10-BIT D/A CONVERTERS

| TEMPERATURE RANGE | | 0°C to 70°C | | -40°C to +85°C | -55°C to +125°C |
|-------------------|-----------------|-------------|----------|----------------|-----------------|
| | | 0.05% | AD7520LN | AD7530LN | AD7520LD |
| ACCURACY | 0.10% | AD7520KN | AD7530KN | AD7520KD | AD7530KD |
| | 0.20% | AD7520JN | AD7530JN | AD7520JD | AD7530JD |
| | PACKAGE OUTLINE | | N16A | | D16C |

12-BIT D/A CONVERTERS

| TEMPERATURE RANGE | | 0°C to 70°C | | -40°C to +85°C | -55°C to +125°C |
|-------------------|-----------------|-------------|----------|----------------|-----------------|
| | | 0.05% | AD7521LN | AD7531LN | AD7521LD |
| ACCURACY | 0.10% | AD7521KN | AD7531KN | AD7521KD | AD7531KD |
| | 0.20% | AD7521JN | AD7531JN | AD7521JD | AD7531JD |
| | PACKAGE OUTLINE | | N18A | | D18A |

*Note: Devices ordered using these P/N's will be marked with AD7520 series and DAC102X series numbers.

Absolute Maximum Ratings

| | |
|--|---------------------------|
| V ⁺ to Gnd | 17V |
| V _{REF} to Gnd | ±25V |
| Digital Input Voltage Range | V ⁺ to Gnd |
| DC Voltage at Pin 1 or Pin 2 (Note 3) | -100 mV to V ⁺ |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Temperature Range

| | MIN | MAX | UNITS |
|------------------------------|-----|------|-------|
| AD7520LN, AD7520KN, AD7520JN | 0 | +70 | °C |
| AD7521LN, AD7521KN, AD7521JN | 0 | +70 | °C |
| AD7530LN, AD7530KN, AD7530JN | 0 | +70 | °C |
| AD7531LN, AD7531KN, AD7531JN | 0 | +70 | °C |
| AD7520LD, AD7520KD, AD7520JD | -40 | +85 | °C |
| AD7521LD, AD7521KD, AD7521JD | -40 | +85 | °C |
| AD7530LD, AD7530KD, AD7530JD | -40 | +85 | °C |
| AD7531LD, AD7531KD, AD7531JD | -40 | +85 | °C |
| AD7520UD, AD7520TD, AD7520SD | -55 | +125 | °C |
| AD7521UD, AD7521TD, AD7521SD | -55 | +125 | °C |

Electrical Characteristics (V⁺ = 15V, V_{REF} = 10.000V, T_A = 25°C unless otherwise specified)

| PARAMETER | CONDITIONS | AD7520L, AD7520K, AD7520J | | | AD7521L, AD7521K, AD7521J | | | UNITS |
|-----------------------------------|---|---------------------------|--------|-------|---------------------------|--------|-------|---------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 10 | | | 12 | | | Bits |
| Linearity Error | T _{MIN} ≤ T _A ≤ T _{MAX} , -10V ≤ V _{REF} ≤ +10V, (Note 1) End Point Adjustment Only (See Linearity Error in Definition of Terms) | | | | | | | |
| 10-bit Parts | AD7520L, AD7520U, AD7521L, AD7521U, AD7530L, AD7531L | | | 0.05 | | | 0.05 | % FSR |
| 9-bit Parts | AD7520T, AD7520K, AD7521T, AD7521K, AD7530K, AD7531K | | | 0.10 | | | 0.10 | % FSR |
| 8-bit Parts | AD7520S, AD7520J, AD7521S, AD7521J, AD7530J, AD7531J | | | 0.20 | | | 0.20 | % FSR |
| Linearity Error Tempco | -10V ≤ V _{REF} ≤ +10V, (Notes 1 and 2) | | 0.0002 | | | 0.0002 | | % FS/°C |
| Full-Scale Error | -10V ≤ V _{REF} ≤ +10V, (Notes 1 and 2) | | 0.3 | | | 0.3 | | % FS |
| Full-Scale Error Tempco | T _{MIN} < T _A < T _{MAX} , (Note 2) | | | 0.001 | | | 0.001 | % FS/°C |
| Output Leakage Current | | | | | | | | |
| I _{OUT1} | All Digital Inputs Low, T _{MIN} ≤ T _A ≤ T _{MAX} | | | 200 | | | 200 | nA |
| I _{OUT2} | All Digital Inputs High, T _{MIN} ≤ T _A ≤ T _{MAX} | | | 200 | | | 200 | nA |
| Power Supply Sensitivity | All Digital Inputs High, 14V ≤ V ⁺ ≤ 16V (Figure 2 of DAC1020 data sheet) | | 0.005 | | | 0.005 | | % FS/V |
| V _{REF} Input Resistance | | 10 | 15 | 20 | 10 | 15 | 20 | kΩ |
| Full-Scale Current Settling Time | R _L = 100Ω from 0 to 99.95% FS All Digital Inputs Switched Simultaneously | | | 500 | | | 500 | ns |
| V _{REF} Feedthrough | All Digital Inputs Low, V _{REF} = 20 Vp-p @ 100 kHz D Package (Note 4) N Package | | | 10 | | | 10 | mVp-p |
| | | | 6 | 9 | | 6 | 9 | mVp-p |
| | | | 2 | 5 | | 2 | 5 | mVp-p |
| Output Capacitance | | | | | | | | |
| I _{OUT1} | All Digital Inputs Low | | 40 | | | 40 | | pF |
| | All Digital Inputs High | | 200 | | | 200 | | pF |
| I _{OUT2} | All Digital Inputs Low | | 200 | | | 200 | | pF |
| | All Digital Inputs High | | 40 | | | 40 | | pF |
| Digital Input | (Note 1) | | | | | | | |
| Low Threshold | T _{MIN} < T _A < T _{MAX} | | | 0.8 | | | 0.8 | V |
| High Threshold | T _{MIN} < T _A < T _{MAX} | 2.4 | | | 2.4 | | | V |
| Digital Input Current | T _{MIN} ≤ T _A ≤ T _{MAX} | | | | | | | |
| | Digital Input High | | 1 | 100 | | 1 | 100 | μA |
| | Digital Input Low | | -50 | -200 | | -50 | -200 | μA |
| Supply Current | All Digital Inputs High | | 0.2 | 1.6 | | 0.2 | 1.6 | mA |
| | All Digital Inputs Low | | 0.6 | 2 | | 0.6 | 2 | mA |
| Operating Power Supply Range | | 5 | | 15 | 5 | | 15 | V |

Note 1: V_{REF} = ±10V and V_{REF} = ±1V.

Note 2: Using internal feedback resistor.

Note 3: Both I_{OUT1} and I_{OUT2} must go to ground or the virtual ground of an operational amplifier. For every millivolt offset between I_{OUT1} or I_{OUT2}, 0.005% linearity error will be introduced.

Note 4: To achieve this low feedthrough in D package, the user must ground the metal lid.

ADB1200 (MM5863) 12-Bit Binary A/D Building Block

General Description

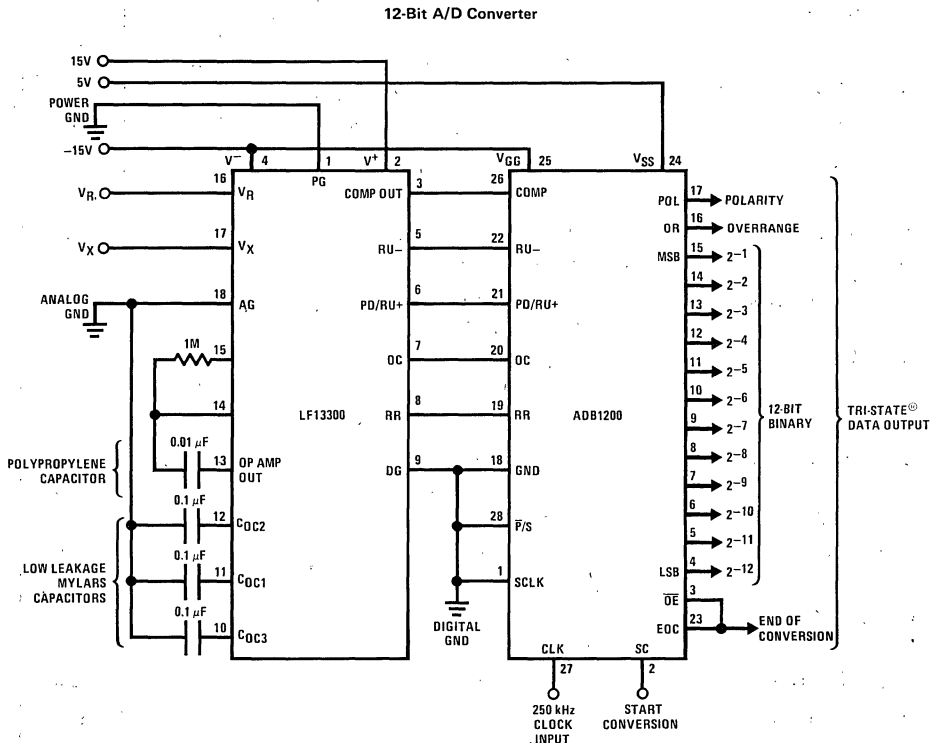
The ADB1200 is the digital controller for the LF13300D* analog building block. Together they form an integrating 12-bit A/D converter. The ADB1200 provides all the necessary control functions, plus features like auto zeroing, polarity and overrange indication, as well as continuous conversion. The 12-bit plus sign parallel and serial outputs are TRI-STATE® TTL level compatible. The device also includes output latches to simplify data bus interfacing.

*See LF13300D data sheet for more information

Features

- 12-bit binary output
- Parallel or serial output
- TRI-STATE output
- Polarity indication
- Overrange indication
- Continuous conversion capability
- 100% overrange capability
- 5V, -15V power requirements
- TTL compatible
- Clock frequency to 1 MHz

Circuit Diagram/Typical Applications



Absolute Maximum Ratings

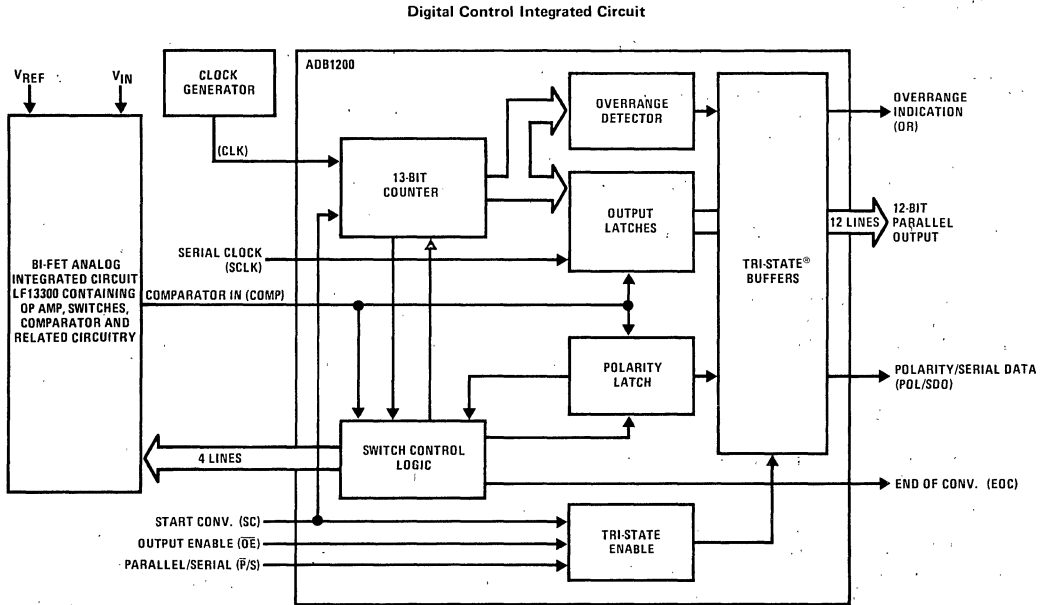
| | |
|--|-----------------|
| Supply Voltage (V _{SS}) | 5.25V |
| Supply Voltage (V _{GG}) | -16.5V |
| Voltage at Any Input | 5.25V |
| Operating Temperature | 0°C to +70°C |
| Storage Temperature | -40°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

V_{SS} = 5V, V_{GG} = -15V, 0°C to +70°C, unless otherwise specified.

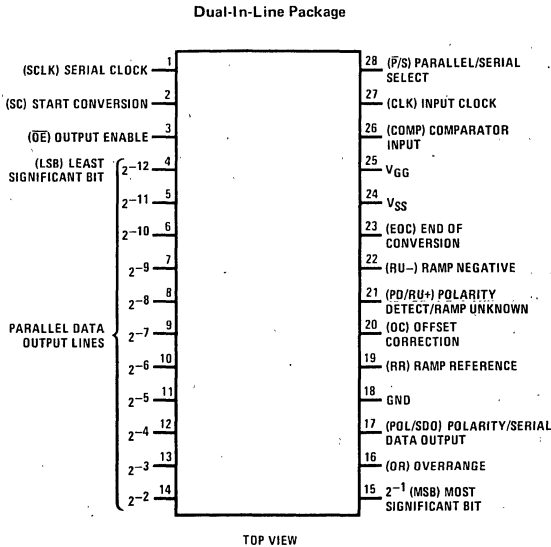
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|-------|--------|----------|-------|
| Power Supply Voltage (V _{SS}) | | 4.75 | 5.00 | 5.25 | V |
| Power Supply Voltage (V _{GG}) | | -13.5 | -15.00 | -16.5 | V |
| Power Supply Current (I _{SS}) | | | | 28 | mA |
| Power Supply Current (I _{GG}) | | | | 34 | mA |
| Logic "1" Input Voltage | | 3.4 | | | V |
| Logic "0" Input Voltage | | | | 0.8 | V |
| Logic "1" Output Voltage | V _{SS} = 4.75V, I _{OH} = 100 μA | 3.8 | | | V |
| Logic "0" Output Voltage | V _{SS} = 5.25V, I _{OL} = -1.6 mA | | | 0.4 | V |
| Width of EOC | Auto Cycle | 5/f | | | sec |
| Prop. Delay COMP to EOC | | 4/f | | 5/f+1 μs | sec |
| Output Enable Time | \overline{OE} to Any Data Output, SC = 1, $\overline{P/S}$ = 0 | | | 1.0 | μs |
| Output Disable Time | \overline{OE} to Any Data Output, SC = 1, $\overline{P/S}$ = 0 | | | 2.4 | μs |
| Output Enable Time | $\overline{P/S}$ to Any Data Output Except Polarity, SC = 1, \overline{OE} = 0 | | | 0.9 | μs |
| Output Disable Time | $\overline{P/S}$ to Any Data Output Except Polarity, SC = 1, \overline{OE} = 0 | | | 2.2 | μs |
| Output Enable Time | SC to Any Data Output, \overline{OE} = 0, $\overline{P/S}$ = 0 | | | 1.0 | μs |
| Output Disable Time | SC to Any Data Output, \overline{OE} = 0, $\overline{P/S}$ = 0 | | | 2.4 | μs |
| Prop. Delay Serial Clock | SCLK to POL/SDO | | | 0.6 | μs |
| Conversion Time | Full Scale | | | 8966/f | sec |
| Conversion Time | 100% Overrange | | | 13062/f | sec |
| Maximum Clock Frequency | CLK, Pin 27 | 500 | 1000 | | kHz |
| Maximum Serial Clock Frequency | SCLK, Pin 1 | 500 | 1000 | | kHz |

Block Diagram



ADB1200 (MM5863)

Connection Diagram



Order Number ADB1200PCN
See NS Package N28A

Functional Description

OPERATION

The ADB1200 is designed for use with the LF13300 analog front end. Four control signals are supplied to the LF13300 and 1 control signal is required from the LF13300. The conversion cycle is composed of 5 distinct phases. They are: Phase I — Offset Correct; Phase II — Polarity Detect; Phase III — Initialization; Phase IV — Ramp Unknown; Phase V — Ramp Reference.

Phase I — Offset Correct (256 Clock Periods)

This phase is initiated by taking the Start Conversion (SC) and the Output Enable (OE) lines to a logic "1". At this time, Offset Correct (OC) will be a logic "1". The LF13300 requires this phase to correct any intrinsic offset voltage errors prior to the polarity detect phase.

Phase II — Polarity Detect (256 Clock Periods)

This phase is used to determine polarity of the analog input. At the midpoint of this phase, COMP from the LF13300 is examined for polarity. If COMP = logic "1", then the input voltage is positive. If COMP = logic "0", then the input is negative. The Polarity Detect signal (PD/RU+) will be at a logic "1" during this entire phase. The above operation is also necessary to determine which integrator input (positive or negative) of the LF13300 should be used for proper A/D conversion (see LF13300 data sheet).

Phase III — Initialization (256 Clock Periods)

This phase is identical to Phase I and is used by the LF13300 to eliminate any offsets induced as a result of the Polarity Detect Phase. Offset Correct (OC) will be at a logic "1".

Phase IV — Ramp Unknown (4096 Clock Periods)

The unknown input voltage is integrated for a fixed time, 4096 clock periods, during this phase. The result of the Phase II Polarity Detect Cycle determines whether PD/RU+ or RU- will be at logic "1". If Phase II indicates a positive input, the PD/RU+ signal will be a logic "1". If phase II indicates a negative input, Ramp Negative

(RU-) will be a logic "1". These 2 signals will never be at logic "1" simultaneously.

Phase V — Ramp Reference

This phase is a variable length phase depending on the magnitude of the analog input voltage. During this time, Ramp Reference (RR) will be in the logic "1" state. When COMP goes to a logic "0" state, or when the internal counter reaches 100% of full scale (8192 clock periods), the Ramp Reference (RR) signal goes to the logic "0" state, the counter output is loaded into the output register, and the End of Conversion (EOC) signal goes to a logic "1". The Polarity Bit will reflect whatever value was determined during Phase II. The output register will hold the data until a new conversion is completed and new data is loaded into the register. The OE line must be low in the logic "0" state and SC must be high in the logic "1" state to enable the outputs.

DATA OUTPUTS

Both serial and parallel outputs are available. In either case, OE must be low and SC must be high to enable the outputs. For parallel output, the P/S line must be low in the logic "0" state. For serial outputs, the P/S line must be high. In the serial mode, the data is shifted out of the Polarity/Serial Output (POL/SDO) line and all other data outputs are in the high impedance state. Each Serial Clock (SCLK) will right shift the output register one bit. Thus, 13 clock pulses are required to fully shift out the data. The data will be shifted out in the following order: Polarity, Overrange, MSB, 2SB, 3SB, . . . , LSB. If OE and P/S are in the logic "0" state and SC in the logic "1" state, all outputs will momentarily go to the logic "1" state for 1 clock period immediately preceding EOC.

CONTINUOUS CONVERT MODE

In this mode, the End of Conversion (EOC) output is connected to the OE input. As long as SC is in the logic "1" state, then each EOC will initiate a new conversion. The data outputs will be disabled for the first 5 clock cycles after EOC goes high.

Truth Table

| INPUT | SC | OE | P/S | LSB | | | | | | | | | | | MSB | OVER-RANGE | POLARITY | |
|------------------|----|----|-----|-----|---|---|---|---|---|---|---|---|---|---|-----|------------|---------------|---|
| 100% Full Scale | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Full Scale | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | |
| Zero | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | |
| Zero | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| —Full Scale | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | |
| —100% Full Scale | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | |
| Any | 1 | 1 | X | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | |
| Any | 1 | 0 | 1 | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Serial Output | |
| Any | 0 | X | X | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | Z | |

1 = High
 0 = Low
 Z = High Impedance
 X = Don't Care

Timing Diagrams

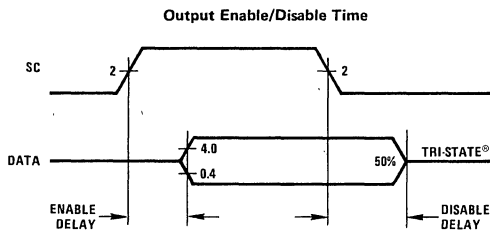
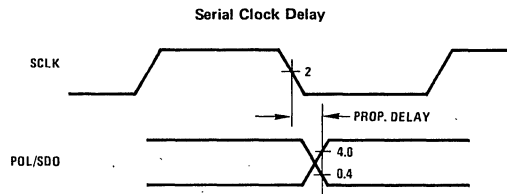
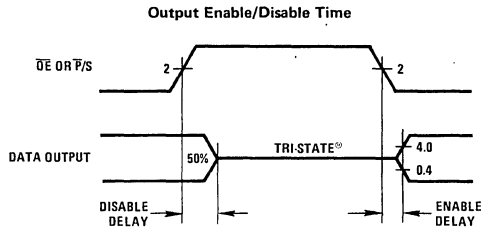


FIGURE 1. Parallel Data

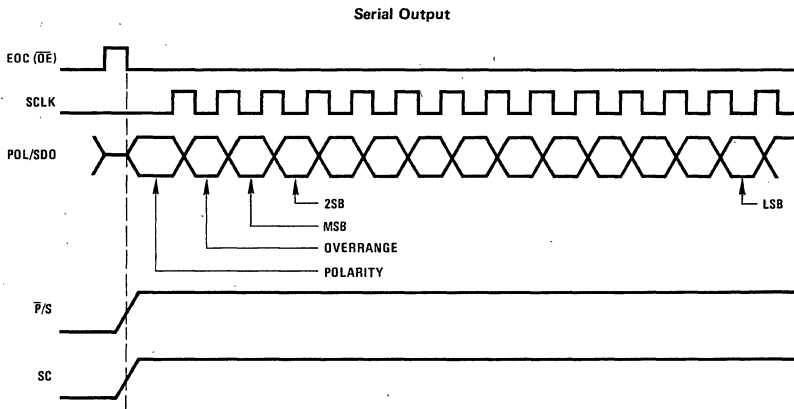


FIGURE 2. Serial Data

Timing Diagrams (Continued)

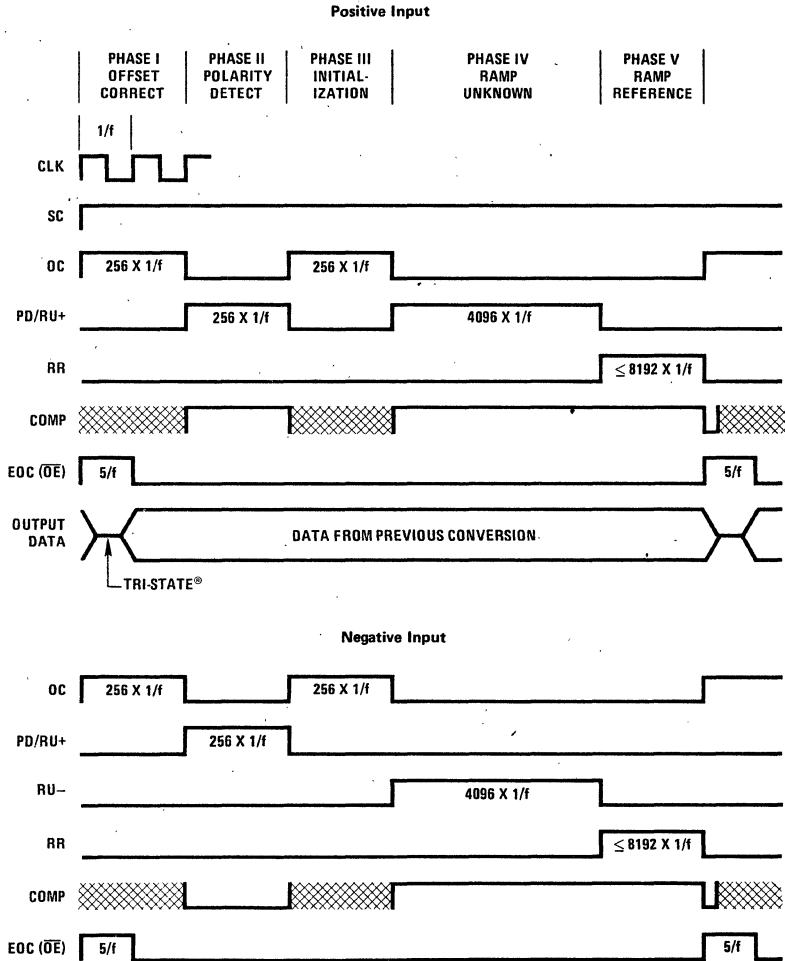


FIGURE 3. Continuous Conversion Mode

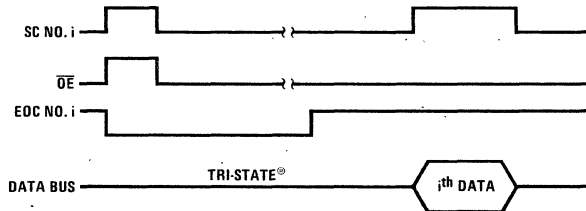
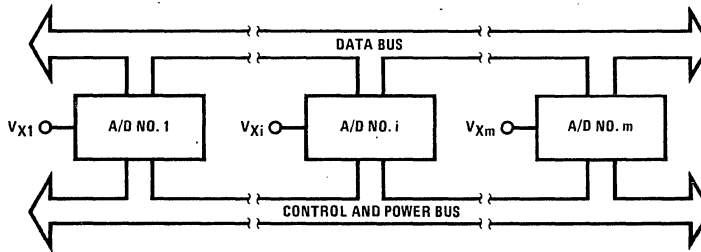


FIGURE 4. *i*th A/D Converter Data Retrieval Sequence

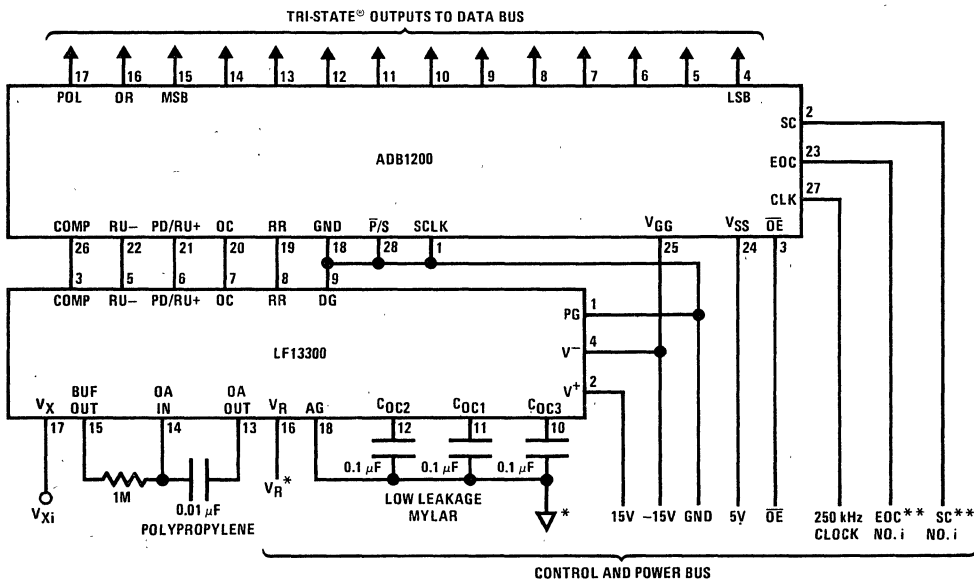
Typical Applications (Continued)

ADB1200 (MM5863)

Multi A/D Converter System on Common Bus



i^{th} A/D Converter



* May be common or separate. Care should be taken to avoid ground currents

** Direct or multiplexed access to the processor

Note. This application is related to Figure 4 of timing diagrams





**National
Semiconductor**

A to D, D to A

ADC0800 (MM4357B/MM5357B) 8-Bit A/D Converter

General Description

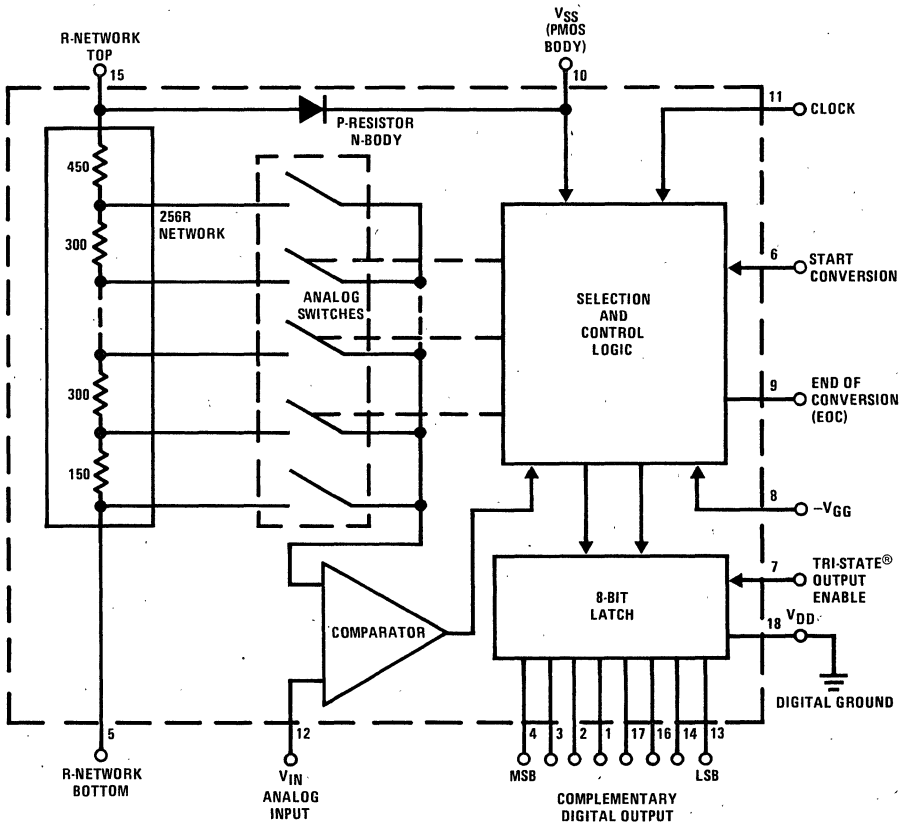
The ADC0800 is an 8-bit monolithic A/D converter using P-channel ion-implanted MOS technology. It contains a high input impedance comparator, 256 series resistors and analog switches, control logic and output latches. Conversion is performed using a successive approximation technique where the unknown analog voltage is compared to the resistor tie points using analog switches. When the appropriate tie point voltage matches the unknown voltage, conversion is complete and the digital outputs contain an 8-bit complementary binary word corresponding to the unknown. The binary output is TRI-STATE[®] to permit bussing on common data lines.

The ADC0800PD is specified over -55°C to $+125^{\circ}\text{C}$ and the ADC0800PCD is specified over 0°C to 70°C .

Features

- Low cost
- $\pm 5\text{V}$, 10V input ranges
- No missing codes
- Ratiometric conversion
- TRI-STATE outputs
- Fast
- Contains output latches
- TTL compatible
- Supply voltages 5V_{DC} and -12V_{DC}
- Resolution 8 bits
- Linearity $\pm 1\text{LSB}$
- Conversion speed 40 clock periods
- Clock range 50 to 800 kHz

Block Diagram



Absolute Maximum Ratings

| | |
|--|--|
| Supply Voltage (V _{DD}) | V _{SS} -22V |
| Supply Voltage (V _{GG}) | V _{SS} -22V |
| Voltage at Any Input | V _{SS} + 0.3V to V _{SS} -22V |
| Storage Temperature | 150°C |
| Operating Temperature | |
| ADC0800PD | -55°C to +125°C |
| ADC0800PCD | 0°C to +70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

These specifications apply for V_{SS} = 5.0 V_{DC}, V_{GG} = -12.0 V_{DC}, V_{DD} = 0 V_{DC}, a reference voltage of 10.000 V_{DC} across the on-chip R-network (V_{R-NETWORK TOP} = 5.000 V_{DC} and V_{R-NETWORK BOTTOM} = -5.000 V_{DC}), and a clock frequency of 800 kHz. For all tests, a 475Ω resistor is used from pin 5 to ground. Unless otherwise noted, these specifications apply over an ambient temperature range of -55°C to +125°C for the ADC0800PD and 0°C to +70°C for the ADC0800PCD.

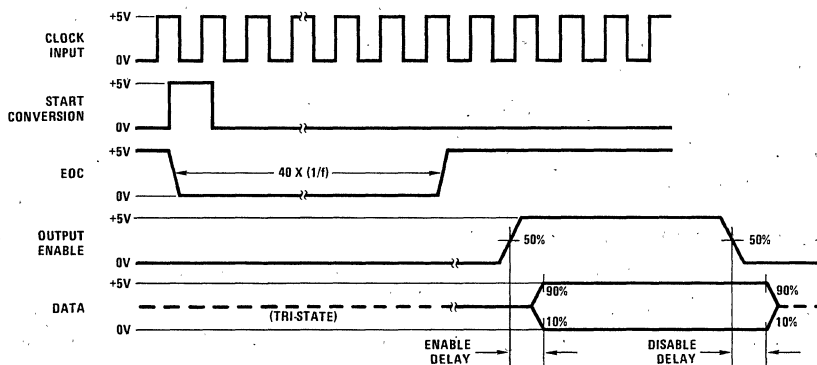
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|----------------------|-----|----------------------|---------------|
| Non-Linearity | T _A = 25°C, (Note 1) | | | ±1 | LSB |
| | Over Temperature, (Note 1) | | | ±2 | LSB |
| Differential Non-Linearity | | | | ±1/2 | LSB |
| Zero Error | | | | ±2 | LSB |
| Zero Error Temperature Coefficient | (Note 2) | | | 0.01 | %/°C |
| Full-Scale Error | | | | ±2 | LSB |
| Full-Scale Error Temperature Coefficient | (Note 2) | | | 0.01 | %/°C |
| Input Leakage | | | | 1 | μA |
| Logical "1" Input Voltage | All Inputs | V _{SS} -1.0 | | V _{SS} | V |
| Logical "0" Input Voltage | All Inputs | V _{GG} | | V _{SS} -4.2 | V |
| Logical Input Leakage | T _A = 25°C, All Inputs, V _{IL} = V _{SS} - 10V | | | 1 | μA |
| Logical "1" Output Voltage | All Outputs, I _{OH} = 100 μA | 2.4 | | | V |
| Logical "0" Output Voltage | All Outputs, I _{OL} = 1.6 mA | | | 0.4 | V |
| Disabled Output Leakage | T _A = 25°C, All Outputs, V _{OL} = V _{SS} @ 10V | | | 2 | μA |
| Clock Frequency | 0°C ≤ T _A ≤ +70°C | 50 | | 800 | kHz |
| | -55°C ≤ T _A ≤ +125°C | 100 | | 500 | kHz |
| Clock Pulse Duty Cycle | | 40 | | 60 | % |
| TRI-STATE Enable/Disable Time | | | | 1 | μs |
| Start Conversion Pulse | (Note 3) | 1 | | 3 1/2 | Clock Periods |
| Power Supply Current | T _A = 25°C | | | 15 | mA |

Note 1: Non-linearity specifications are based on best straight line.

Note 2: Guaranteed by design only.

Note 3: Start conversion pulse duration greater than 3 1/2 clock periods will cause conversion errors.

Timing Diagram



Data is complementary binary (full scale is all "0's" output).

Application Hints

OPERATION

The ADC0800 contains a network with 256-300Ω resistors in series. Analog switch taps are made at the junction of each resistor and at each end of the network. In operation, a reference (10.00V) is applied across this network of 256 resistors. An analog input (V_{IN}) is first compared to the center point of the ladder via the appropriate switch. If V_{IN} is larger than $V_{REF}/2$, the internal logic changes the switch points and now compares V_{IN} and $3/4 V_{REF}$. This process, known as successive approximation, continues until the best match of V_{IN} and V_{REF}/N is made. N now defines a specific tap on the resistor network. When the conversion is complete, the logic loads a binary word corresponding to this tap into the output latch and an end of conversion (EOC) logic level appears. The output latches hold this data valid until a new conversion is completed and new data is loaded into the latches. The data transfer occurs in about 200 ns so that valid data is present virtually all the time. Conversion requires 40 clock periods. The device may be operated in the free running mode by connecting the Start Conversion line to the End of Conversion line. However, to ensure start-up under all possible conditions, an external Start Conversion pulse is required during power up conditions.

REFERENCE

The reference applied across the 256 resistor network determines the analog input range. $V_{REF} = 10.00V$ with the top of the R-network connected to 5V and the bottom connected to $-5V$ gives a $\pm 5V$ range. The reference can be level shifted between V_{SS} and V_{GG} . However, the voltage, which is applied to the top of the R-network (pin 15), must not exceed V_{SS} to prevent forward biasing the on-chip parasitic silicon diode which exists between the P-diffused resistors (pin 15) and the N-type body (pin 10, V_{SS}). Use of a standard logic power supply for V_{SS} can cause problems, both due to initial voltage tolerance and changes over temperature. A solution is to power the V_{SS} line (15 mA max drain) from the output of the op amp which is used to bias the top of the R-network (pin 15). The analog input voltage and the voltage which is applied to the bottom of the R-network (pin 5) must be at

least 7V above the $-V_{DD}$ supply voltage to insure adequate voltage drive to the analog switches.

Other reference voltages may be used (such as 10.24V). If a 5V reference is used, the analog range will be 5V and accuracy will be reduced by a factor of 2. Thus, for maximum accuracy, it is desirable to operate with at least a 10V reference. For TTL logic levels, this requires 5V and $-5V$ for the R-network. CMOS can operate at the 10 V_{DC} V_{SS} level and a single 10 V_{DC} reference can be used. All digital voltage levels for both inputs and outputs will be from ground to V_{SS} .

ANALOG INPUT AND SOURCE RESISTANCE CONSIDERATIONS

The lead to the analog input (pin 12) should be kept as short as possible. Both noise and digital clock coupling to this input can cause conversion errors. To minimize any input errors, the following source resistance considerations should be noted:

- For $R_s \leq 5k$ No analog input bypass capacitor required, although a 0.1 μF input bypass capacitor will prevent pick-up due to unavoidable series lead inductance.
- For $5k < R_s \leq 20k$ A 0.1 μF capacitor from the input (pin 12) to ground should be used.
- For $R_s > 20k$ Input buffering is necessary.

If the overall converter system requires lowpass filtering of the analog input signal, use a 20 kΩ or less series resistor for a passive RC section or add an op amp RC active lowpass filter (with its inherent low output resistance) to insure accurate conversions.

CLOCK COUPLING

The clock lead should be kept away from the analog input line to reduce coupling.

LOGIC INPUTS

The logical "1" input voltage swing for the Clock, Start Conversion and Output Enable should be ($V_{SS} - 1.0V$).

Application Hints (Continued)

CMOS will satisfy this requirement but a pull-up resistor should be used for TTL logic inputs.

RE-START AND DATA VALID AFTER EOC

The EOC line (pin 9) will be in the low state for a maximum of 40 clock periods to indicate "busy". A START pulse which occurs while the A/D is BUSY will reset the SAR and start a new conversion with the EOC signal remaining in the low state until the end of this new conversion. When the conversion is complete, the EOC line will go to the high voltage state. An additional 4 clock periods must be allowed to elapse after EOC goes high, before a new conversion cycle is requested. Start Conversion pulses which occur during this last 4 clock period interval may be ignored (see *Figures 1 and 2* for high speed operation). This is only a problem for high conversion rates and keeping the number of conversions per second less than $(1/44) \times f_{CLOCK}$ automatically guarantees proper operation. For example, for an 800 kHz clock, 18,000 conversions per second are allowed. The transfer of the new digital data to the output is initiated when EOC goes to the high voltage state.

POWER SUPPLIES

Standard supplies are $V_{SS} = 5V$, $V_{GG} = -12V$ and $V_{DD} = 0V$. Device accuracy is dependent on stability of the reference voltage and has slight sensitivity to $V_{SS} - V_{GG}$. V_{DD} has no effect on accuracy. Noise spikes on the V_{SS} and V_{GG} supplies can cause improper conversion; therefore, filtering each supply with a 4.7 μF tantalum capacitor is recommended.

CONTINUOUS CONVERSIONS AND LOGIC CONTROL

Simply tying the EOC output to the Start Conversion input will allow continuous conversions, but an oscillation on this line will exist during the first 4 clock periods after EOC goes high. Adding a D flip-flop between EOC (D input) to Start Conversion (Q output) will prevent the oscillation and will allow a stop/continuous control via the "clear" input.

To prevent missing a start pulse which may occur after EOC goes high and prior to the required 4 clock period time interval, the circuit of *Figure 1* can be used. The RS latch can be set at any time and the 4-stage shift register delays the application of the start pulse to the A/D by 4 clock periods. The RS latch is reset 1 clock period after the A/D EOC signal goes to the low voltage state. This circuit also provides a Start Conversion pulse to the A/D which is 1 clock period wide.

A second control logic application circuit is shown in *Figure 2*. This allows an asynchronous start pulse of arbitrary length less than T_C , continuously converts for a fixed high level and provides a single clock period start pulse to the A/D. The binary counter is loaded with a count of 11 when the start pulse to the A/D appears. Counting is inhibited until the EOC signal from the A/D goes high. A carry pulse is then generated 4 clock periods after EOC goes high and is used to reset the input RS latch. This carry pulse can be used to indicate that the conversion is complete, the data has transferred to the output buffers and the system is ready for a new conversion cycle.

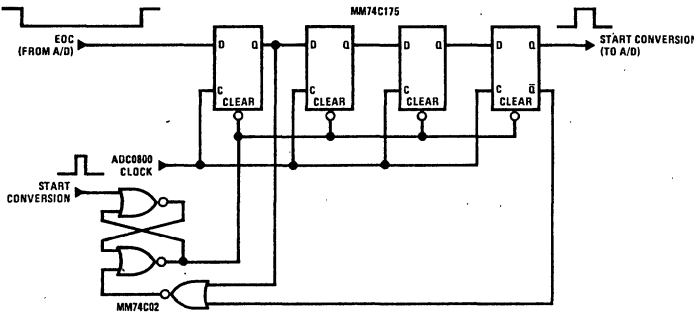


FIGURE 1. Delaying an Asynchronous Start Pulse

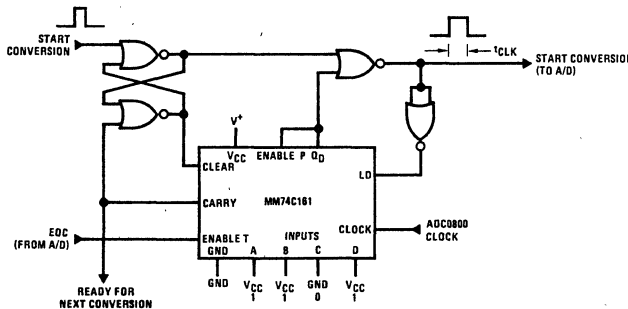


FIGURE 2. A/D Control Logic

Application Hints (Continued)

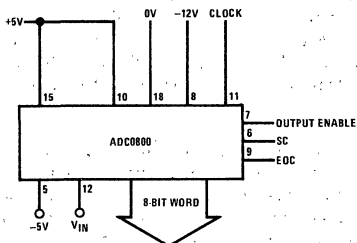
ZERO AND FULL-SCALE ADJUSTMENT

Zero Adjustment: This is the offset voltage required at the bottom of the R-network (pin 5) to make the 11111111 to 11111110 transition when the input voltage is 1/2 LSB (20 mV for a 10.24V scale). In most cases, this can be accomplished by having a 1 kΩ pot on pin 5. A resistor of 475Ω can be used as a non-adjustable best approximation from pin 5 to ground.

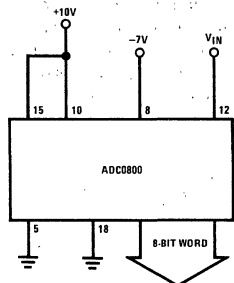
Full-Scale Adjustment: This is the offset voltage required at the top of the R-network (pin 15) to make the 00000001 to 00000000 transition when the input voltage is 1 1/2 LSB from full-scale (60 mV less than full-scale for a 10.24V scale). This voltage is guaranteed to be within 2 LSB for the ADC0800. In most cases, this can be accomplished by having a 1 kΩ pot on pin 15.

Typical Applications

General Connection

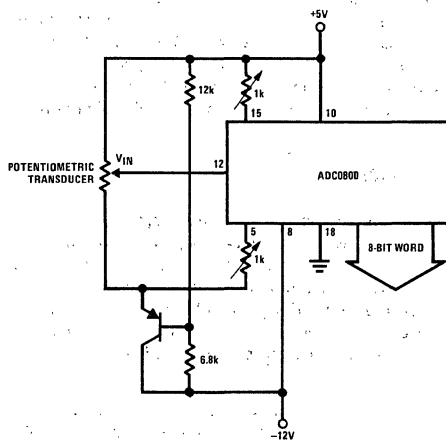


Hi-Voltage CMOS Output Levels



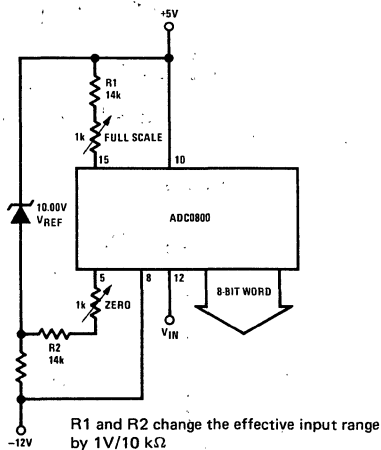
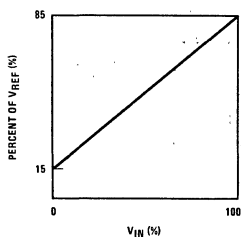
0V to 10V V_{IN} range
0V to 10V output levels

Ratiometric Input Signal with Tracking Reference



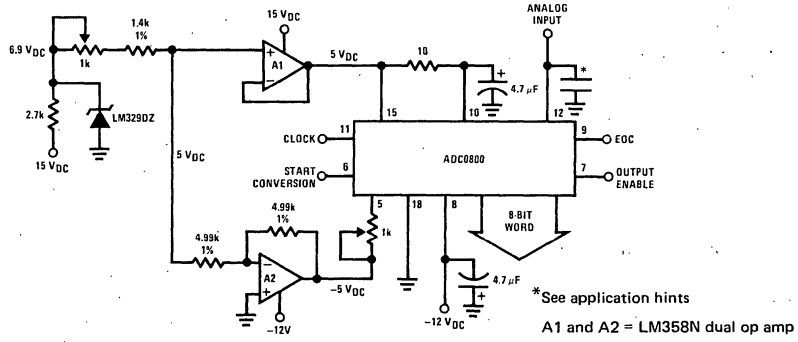
Level Shifted Zero and Full-Scale for Transducers

Level Shifted Input Signal Range

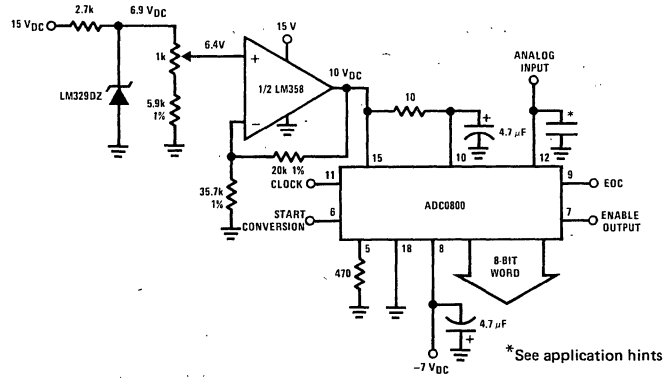


Typical Applications (Continued)

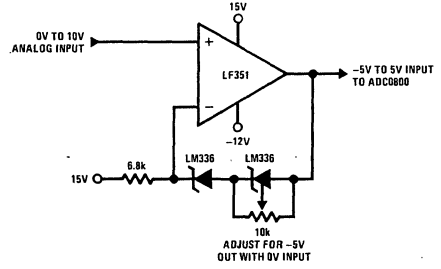
VREF = 10 VDC With TTL Logic Levels



VREF = 10 VDC With 10V CMOS Logic Levels



Input Level Shifting



- Permits TTL compatible outputs with 0V to 10V input range (0V to -10V input range achieved by reversing polarity of zener diodes and returning the 6.8k resistor to V⁻).

MICROPROCESSOR INTERFACE

Figure 3 and the following sample program are included to illustrate both hardware and software requirements to allow output data from the ADC0800 to be loaded into the memory of a microprocessor system. For this example, National's INS8060, SC/MP II, microprocessor has been used.

The sample program, as shown, will start the converter, load the converter's output data into the accumulator, keep track of the number of data bytes entered, complement the data and store this data into sequential memory locations. After 256 bytes have been entered, the control jumps to the user's program where proces-

Typical Applications (Continued)

sing of the data entered will be implemented. A more practical program whereby each data byte entered will be processed before another entry is made can easily be done by jumping back to the user's program at the end of the interrupt routine (where the data is loaded into the accumulator and stored in memory). The end of the user's program should provide a jump back to the INITIALIZE statement to start a new conversion and generate a new data entry.

The following arbitrarily chosen addresses and pointer assignments are used in this example:

Pointer 1 — WORD COUNT (ADDR:0100)

Also used to point to the A/D converter at address 0500 for this example when data is to be entered.

Pointer 2 — ENTERED DATA (ADDR's: 0200 → 02FF)
Data is stored in 2's complement binary form, i.e. 01111111 → +full-scale and 10000000 → - full-scale.

Pointer 3 — LOAD DATA SUBROUTINE (starts at ADDR:0300)

Executed when an EOC signal generates an interrupt request via sense A after an IEN (interrupt enable) instruction.

The address for the converter (0500) is unique for this particular sample program but may not be in a user's system so a different converter address must be used. Note that in *Figure 3* ADX and ADY for the address decode circuitry would be address bits ADB10 and ADB8 (pins 35 and 33 on the SC/MP II package) for converter address 0500.

SAMPLE PROGRAM TO LOAD DATA INTO MEMORY WITH SC/MP II.

```

0001 08      START:    NOP
0002 C4 01          LDIX'01
0004 35          XPAH 1
0005 C4 00          LDIX'00
0007 31          XPAL 1      ; P1 = 0100
0008 C4 02          LDIX'02
000A 36          XPAH 2
000B C4 00          LDIX'00
000D C9 00          ST(P1)      ; Zero word count (P1)
000F 32          XPAL 2      ; P2 = 0200
0010 C4 03          LDIX'03
0012 37          XPAH 3
0013 08      INITIALIZE:  NOP
0014 C4 00          LDIX'00
0016 33          XPAL 3      ; P3 = 0300
0017 C4 01          LDIX'01
0019 07          CAS          ; Starts converter via flag 0
001A C1 00          LD (P1)
001C F4 FF          XRIX'FF
001E 98 05          JZ DTA IN ; Test to see if word count is FF,
                                if so, jump to DTA IN
                                ; Enables INTERRUPT

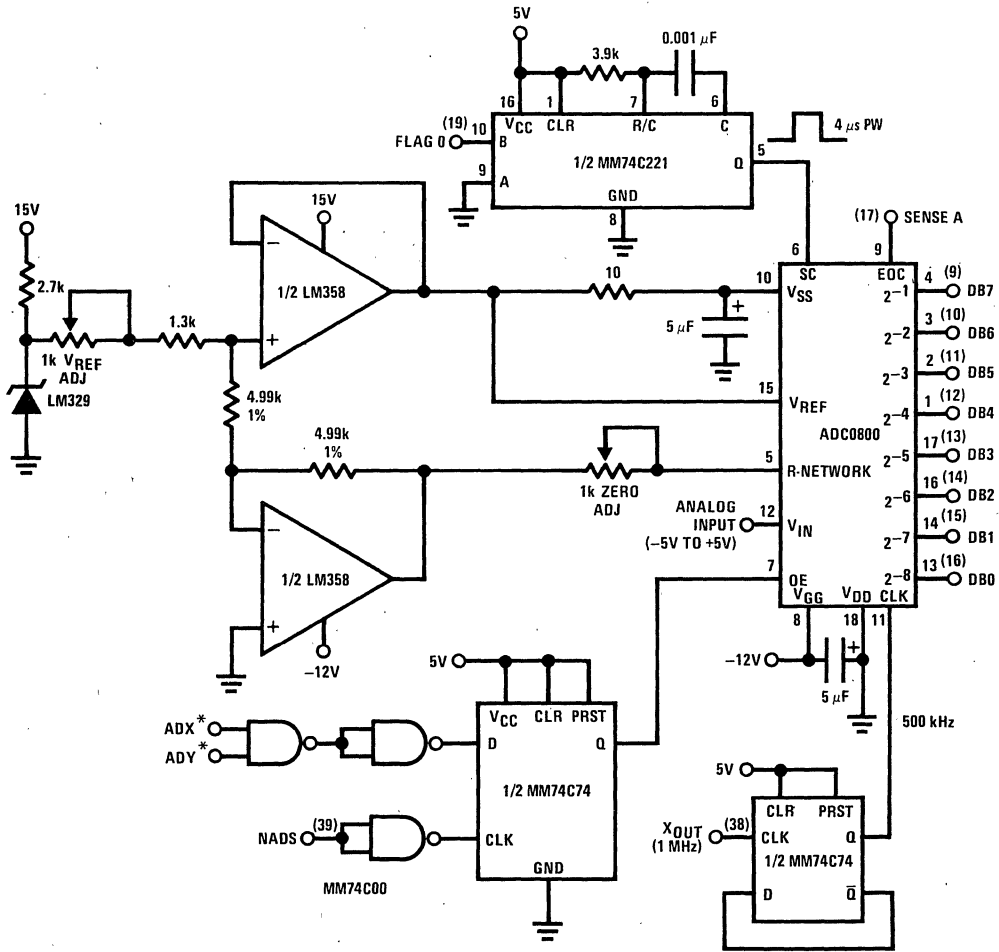
0020 05          IEN          ; Enables INTERRUPT
0021 08      LOOP:      NOP
0022 90 FE          JMP LOOP ; Loop until EOC
0024 08      DTA IN:    NOP

                                ; User program to process data
                                .
                                .
                                .

:DATA ENTRY SUBROUTINE
0300 08      DATA IN SR:  NOP
0301 A9 00          ILD (P1) ; Increment word count
0303 C4 05          LDIX'05
0305 35          XPAH 1      ; P1 will point to converter
0306 C1 00          LD (P1) ; Converter data loaded into
                                accumulator
0308 F4 7F          XRIX'7F ; Put data in 2's complement form
030A CE 01          ST @ 1(P2) ; Store data
030C C4 00          LDIX'00
030E 07          CAS          ; Resets flag 0
030F C4 01          LDIX'01
0311 35          XPAH 1      ; Resets P1 to point at word count
0312 C4 13          LDIX'13
0314 33          XPAL 3
0315 3F          XPPC 3      ; Return to INITIALIZE to start a
                                new conversion

```

Typical Applications (Continued)



- Setting flag 0 (FLG0 = 1) with software, starts conversion (FLG0 must be cleared before another conversion can be initiated)
- With interrupt enabled an EOC will force an interrupt. Interrupt subroutine should load converter data into the accumulator.
- Output data is in complementary offset binary form
- Numbers in parentheses denote pin numbers of SC/MP chip

*ADX and ADY can be any of the address lines but they must be high *only* at the time the converter output data is to be put on the data bus (i.e., the converter must have its own unique address)

FIGURE 3. Interfacing to the SC/MP II Microprocessor

Typical Applications (Continued)

TESTING THE A/D CONVERTER

There are many degrees of complexity associated with testing an A/D converter. One of the simplest tests is to apply a known analog input voltage to the converter and use LED's to display the resulting digital output code as shown in *Figure 4*. Note that the LED drivers invert the digital output of the A/D converter to provide a binary display. A lab DVM can be used if a precision voltage source is not available. After adjusting the zero and full-scale, any number of points can be checked, as desired.

For ease of testing, a 10.24 V_{DC} reference is recommended for the A/D converter. This provides an LSB of 40 mV (10.240/256). To adjust the zero of the A/D, an analog input voltage of 1/2 LSB or 20 mV should be

applied and the zero adjust potentiometer should be set to provide a flicker on the LSB LED readout with all the other display LEDs OFF.

To adjust the full-scale adjust potentiometer, an analog input which is 1 1/2 LSB less than the reference (10.240 - 0.060 or 10.180 V_{DC}) should be applied to the analog input and the full-scale adjusted for a flicker on the LSB LED, but this time with all the other LEDs ON.

A complete circuit for a simple A/D tester is shown in *Figure 5*. Note that the clock input voltage swing and the digital output voltage swings are from 0V to 10.24V. The MM74C901 provides a voltage translation to 5V operation and also the logic inversion so the readout LEDs are in binary.

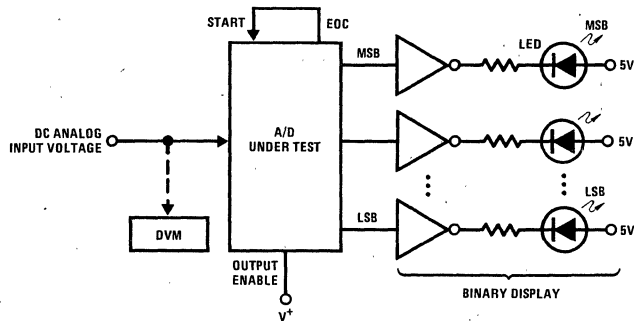


FIGURE 4. Basic A/D Tester

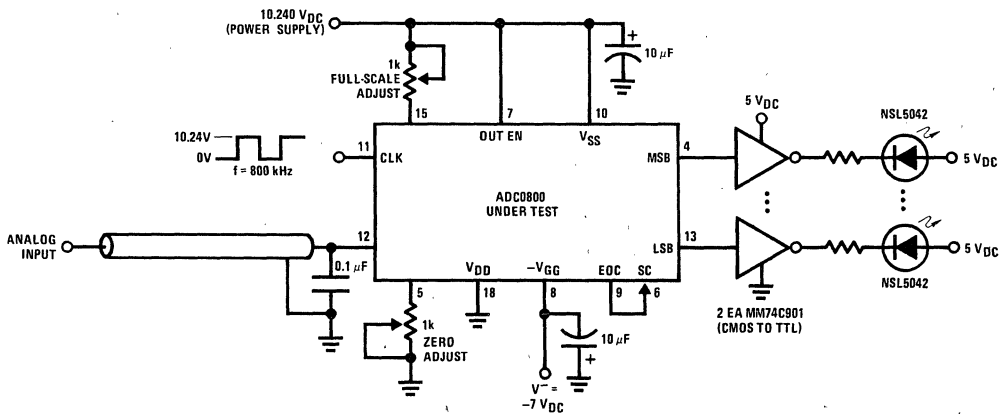


FIGURE 5. Complete Basic Tester Circuit

Typical Applications (Continued)

The digital output LED display can be decoded by dividing the 8 bits into the 4 most significant bits and 4 least significant bits. Table I shows the fractional binary equivalent of these two 8-bit groups. By adding the decoded voltages which are obtained from the column: "Input Voltage Value with a 10.240 V_{REF}" of both the MS and LS groups, the value of the digital display can be determined. For example, for an output LED display of "1011 0110" or "B6" (in hex) the voltage values from the table are 7.04 + 0.24 or

7.280 V_{DC}. These voltage values represent the center values of a perfect A/D converter. The input voltage has to change by $\pm 1/2$ LSB (± 20 mV), the "quantization uncertainty" of an A/D, to obtain an output digital code change. The effects of this quantization error have to be accounted for in the interpretation of the test results. A plot of this natural error source is shown in *Figure 6* where, for clarity, both the analog input voltage and the error voltage are normalized to LSBs.

TABLE I. DECODING THE DIGITAL OUTPUT LEDs

| HEX | BINARY | FRACTIONAL BINARY VALUE FOR | | INPUT VOLTAGE VALUE WITH 10.24 V _{REF} | |
|-----|---------|-----------------------------|----------|---|----------|
| | | MS GROUP | LS GROUP | MS GROUP | LS GROUP |
| F | 1 1 1 1 | 15/16 | 15/256 | 9.600 | 0.600 |
| E | 1 1 1 0 | 7/8 | 7/128 | 8.960 | 0.560 |
| D | 1 1 0 1 | 13/16 | 13/256 | 8.320 | 0.520 |
| C | 1 1 0 0 | 3/4 | 3/64 | 7.680 | 0.480 |
| B | 1 0 1 1 | 11/16 | 11/256 | 7.040 | 0.440 |
| A | 1 0 1 0 | 5/8 | 5/128 | 6.400 | 0.400 |
| 9 | 1 0 0 1 | 9/16 | 9/256 | 5.760 | 0.360 |
| 8 | 1 0 0 0 | 1/2 | 1/32 | 5.120 | 0.320 |
| 7 | 0 1 1 1 | 7/16 | 7/256 | 4.480 | 0.280 |
| 6 | 0 1 1 0 | 3/8 | 3/128 | 3.840 | 0.240 |
| 5 | 0 1 0 1 | 5/16 | 5/256 | 3.200 | 0.200 |
| 4 | 0 1 0 0 | 1/4 | 1/64 | 2.560 | 0.160 |
| 3 | 0 0 1 1 | 3/16 | 3/256 | 1.920 | 0.120 |
| 2 | 0 0 1 0 | 1/8 | 1/128 | 1.280 | 0.080 |
| 1 | 0 0 0 1 | 1/16 | 1/256 | 0.640 | 0.040 |
| 0 | 0 0 0 0 | | | 0 | 0 |

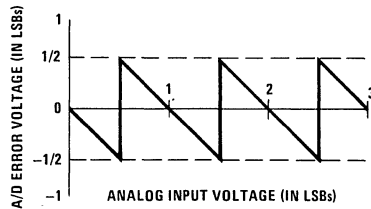


FIGURE 6. Error Plot of a Perfect A/D Showing Effects of Quantization Error

Typical Applications (Continued)

A low speed ramp generator can also be used to sweep the analog input voltage and the LED outputs will provide a binary counting sequence from zero to full-scale.

The techniques described so far are suitable for an engineering evaluation or a quick check on performance. For a higher speed test system, or to obtain plotted data, a digital-to-analog converter is needed for the test set-up. An accurate 10-bit DAC can serve as the precision voltage source for the A/D. Errors of the A/D under test can be provided as either analog voltages or differences in two digital words.

A basic A/D tester which uses a DAC and provides the error as an analog output voltage is shown in *Figure 7*. The 2 op amps can be eliminated if a lab DVM with a numerical subtraction feature is available to directly readout the difference voltage, "A-C". The analog

input voltage can be supplied by a low frequency ramp generator and an X-Y plotter can be used to provide analog error (Y axis) versus analog input (X axis). The construction details of a tester of this type are provided in the NSC application note AN-179, "Analog-to-Digital Converter Testing".

For operation with a microprocessor or a computer-based test system, it is more convenient to present the errors digitally. This can be done with the circuit of *Figure 8* where the output code transitions can be detected as the 10-bit DAC is incremented. This provides 1/4 LSB steps for the 8-bit A/D under test. If the results of this test are automatically plotted with the analog input on the X axis and the error (in LSB's) as the Y axis, a useful transfer function of the A/D under test results. For acceptance testing, the plot is not necessary and the testing speed can be increased by establishing internal limits on the allowed error for each code.

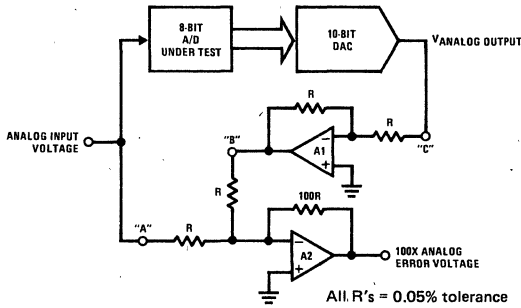


FIGURE 7. A/D Tester with Analog Error Output

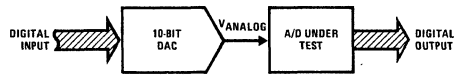
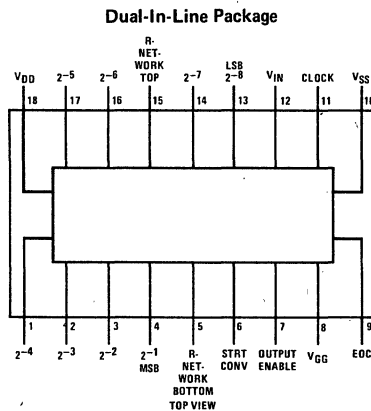


FIGURE 8. Basic "Digital" A/D Tester

Connection Diagram



Order Number ADC0800PD (-55°C to +125°C)
 or ADC0800PCD (0°C to +70°C)
 See NS Package D18A

ADC0801, ADC0802, ADC0803, ADC0804 8-Bit μ P Compatible A/D Converters

General Description

The ADC0801, ADC0802, ADC0803, ADC0804 are CMOS 8-bit, successive approximation A/D converters which use a modified potentiometric ladder—similar to the 256R products. They are designed to meet the NSC MICROBUS™ standard to allow operation with the 8080A control bus, and TRI-STATE® output latches directly drive the data bus. These A/Ds appear like memory locations or I/O ports to the microprocessor and no interfacing logic is needed.

A new differential analog voltage input allows increasing the common-mode rejection and offsetting the analog zero input voltage value. In addition, the voltage reference input can be adjusted to allow encoding any smaller analog voltage span to the full 8 bits of resolution.

Features

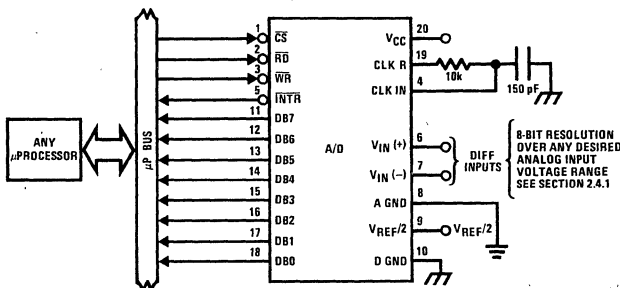
- MICROBUS (8080A) compatible—no interfacing logic needed
- Easy interface to all microprocessors, or operates "stand alone"

- Differential analog voltage inputs
- Logic inputs and outputs meet T²L voltage level specifications
- Works with 2.5V (LM336) voltage reference
- On-chip clock generator
- 0V to 5V analog input voltage range with single 5V supply
- No zero adjust required
- 0.3" standard width 20-pin DIP package

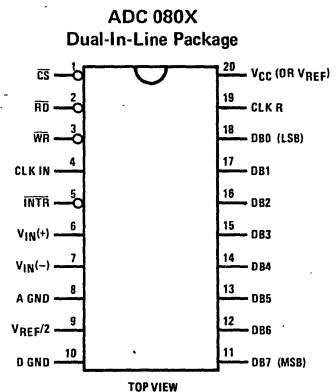
Key Specifications

- Resolution 8 bits
- Total error $\pm 1/4$ LSB, $\pm 1/2$ LSB and ± 1 LSB
- Conversion time 100 μ s
- Access time 135 ns
- Single supply 5 VDC
- Operates ratiometrically or with 5 VDC, 2.5 VDC, or analog span adjusted voltage reference

Typical Application



Connection Diagram



Absolute Maximum Ratings (Notes 1 and 2)

| | |
|---|------------------------------|
| Supply Voltage (V_{CC}) (Note 3) | 6.5V |
| Voltage at Any Input | -0.3V to ($V_{CC} + 0.3V$) |
| Storage Temperature Range | -65°C to +150°C |
| Package Dissipation at $T_A = 25^\circ\text{C}$ | 875 mW |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Ratings (Notes 1 and 2)

| | |
|----------------------------|--|
| Temperature Range (Note 1) | $T_{MIN} \leq T_A \leq T_{MAX}$ |
| ADC0801/02/03 LD | $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ |
| ADC0801/02/03/04 LCD | $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ |
| ADC0801/02/03/04 LCN | $0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}$ |
| Range of V_{CC} (Note 1) | 4.5 V_{DC} to 6.3 V_{DC} |

Electrical Characteristics

Converter Specifications:

$V_{CC} = 5 V_{DC}$, $V_{REF}/2 = 2.500 V_{DC}$, $T_{MIN} \leq T_A \leq T_{MAX}$ and $f_{CLK} = 640 \text{ kHz}$ unless otherwise stated.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|----------|------------|-----------------|-----------|
| ADC0801: Total Adjusted Error (Note 8) | With Full-Scale Adj. | | | $\pm 1/4$ | LSB |
| ADC0802: Total Unadjusted Error (Note 8) | Completely Unadjusted | | | $\pm 1/2$ | LSB |
| ADC0803: Total Adjusted Error (Note 8) | With Full-Scale Adj. | | | $\pm 1/2$ | LSB |
| ADC0804: Total Unadjusted Error (Note 8) | Completely Unadjusted | | | ± 1 | LSB |
| $V_{REF}/2$ Input Resistance | Input Resistance at Pin 9 | 1.0 | 1.3 | | $k\Omega$ |
| Analog Input Voltage Range | (Note 4) $V(+)$ or $V(-)$ | Gnd-0.05 | | $V_{CC} + 0.05$ | V_{DC} |
| DC Common-Mode Rejection | Over Analog Input Voltage Range | | $\pm 1/16$ | $\pm 1/8$ | LSB |
| Power Supply Sensitivity | $V_{CC} = 5 V_{DC} \pm 10\%$ Over Allowed $V_{IN}(+)$ and $V_{IN}(-)$ Voltage Range (Note 4) | | $\pm 1/16$ | $\pm 1/8$ | LSB |

Electrical Characteristics

Timing Specifications: $V_{CC} = 5 V_{DC}$ and $T_A = 25^\circ\text{C}$ unless otherwise noted.

| | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------|---|---|-----|-----|------|-------------|
| f_{CLK} | Clock Frequency | $V_{CC} = 6V$, (Note 5) | 100 | 640 | 1280 | kHz |
| | | $V_{CC} = 5V$ | 100 | 640 | 800 | kHz |
| T_c | Conversion Time | (Note 6) | 66 | | 73 | $1/f_{CLK}$ |
| CR | Conversion Rate In Free-Running Mode | \overline{INTR} tied to \overline{WR} with $\overline{CS} = 0 V_{DC}$, $f_{CLK} = 640 \text{ kHz}$ | | | 8770 | conv/s |
| $t_W(\overline{WR})_L$ | Width of \overline{WR} Input (Start Pulse Width) | $\overline{CS} = 0 V_{DC}$ (Note 7) | 100 | | | ns |
| t_{ACC} | Access Time (Delay from Falling Edge of \overline{RD} to Output Data Valid) | $C_L = 100 \text{ pF}$ (Use Bus Driver IC for Larger C_L) | | 135 | 200 | ns |
| t_{1H}, t_{0H} | TRI-STATE Control (Delay from Rising Edge of \overline{RD} to Hi-Z State) | $C_L = 10 \text{ pF}$, $R_L = 10k$ (See TRI-STATE Test Circuits) | | 125 | 250 | ns |
| t_{WI} | Delay from Falling Edge of \overline{WR} to Reset of \overline{INTR} | | | 300 | 450 | ns |
| C_{IN} | Input Capacitance of Logic Control Inputs | | | 5 | 7.5 | pF |
| C_{OUT} | TRI-STATE Output Capacitance (Data Buffers) | | | 5 | 7.5 | pF |

Electrical Characteristics

Digital Levels and DC Specifications:

$V_{CC} = 5 V_{DC}$ and $T_{MIN} \leq T_A \leq T_{MAX}$, unless otherwise noted.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|-----|--------|-----|-----------|
| CONTROL INPUTS [Note: CLK IN (pin 4) is the input of a Schmitt trigger circuit and is therefore specified separately] | | | | | |
| $V_{IN(1)}$ Logical "1" Input Voltage (Except Pin 4 CLK IN) | $V_{CC} = 5.25 V_{DC}$ | 2.0 | | 15 | V_{DC} |
| $V_{IN(0)}$ Logical "0" Input Voltage (Except Pin 4 CLK IN) | $V_{CC} = 4.75 V_{DC}$ | | | 0.8 | V_{DC} |
| V_{T+} CLK IN (Pin 4) Positive Going Threshold Voltage | | 2.7 | 3.1 | 3.5 | V_{DC} |
| V_{T-} CLK IN (Pin 4) Negative Going Threshold Voltage | | 1.5 | 1.8 | 2.1 | V_{DC} |
| V_H CLK IN (Pin 4) Hysteresis (V_{T+}) - (V_{T-}) | | 0.6 | 1.3 | 2.0 | V_{DC} |
| $I_{IN(1)}$ Logical "1" Input Current (All Inputs) | $V_{IN} = 5 V_{DC}$ | | 0.005 | 1 | μADC |
| $I_{IN(0)}$ Logical "0" Input Current (All Inputs) | $V_{IN} = 0 V_{DC}$ | -1 | -0.005 | | μADC |
| I_{CC} Supply Current (Includes Ladder Current) | $f_{CLK} = 640 \text{ kHz}$, $T_A = 25^\circ C$ and $\overline{CS} = "1"$ | | 1.3 | 2.5 | mA |

DATA OUTPUTS AND INTR

| | | | | | |
|---|--|-----|----|-----|------------------------|
| $V_{OUT(0)}$ Logical "0" Output Voltage | $I_O = 1.6 \text{ mA}$ $V_{CC} = 4.75 V_{DC}$ | | | 0.4 | V_{DC} |
| $V_{OUT(1)}$ Logical "1" Output Voltage | $I_O = -360 \mu A$ $V_{CC} = 4.75 V_{DC}$ | 2.4 | | | V_{DC} |
| I_{OUT} TRI-STATE Disabled Output Leakage (All Data Buffers) | $V_{OUT} = 0 V_{DC}$ $V_{OUT} = 5 V_{DC}$ | -3 | | 3 | μADC μADC |
| I_{SOURCE} Output Short Circuit Current | $T_A = 25^\circ C$ V_{OUT} Short to Gnd | 4.5 | 6 | | mADC |
| I_{SINK} | V_{OUT} Short to V_{CC} | 9.0 | 16 | | mADC |

Note 1: Absolute maximum ratings are those values beyond which the life of the device may be impaired.

Note 2: All voltages are measured with respect to Gnd, unless otherwise specified. The separate A Gnd point should always be wired to the D Gnd.

Note 3: A zener diode exists, internally, from V_{CC} to Gnd and has a typical breakdown voltage of $7 V_{DC}$.

Note 4: For $V_{IN(-)} \geq V_{IN(+)}$ the digital output code will be 0000 0000. Two on-chip diodes are tied to each analog input (see block diagram) which will forward conduct for analog input voltages one diode drop below ground or one diode drop greater than the V_{CC} supply. Be careful, during testing at low V_{CC} levels (4.5V), as high level analog inputs (5V) can cause this input diode to conduct—especially at elevated temperatures, and cause errors for analog inputs near full-scale. The spec allows 50 mV forward bias of either diode. This means that as long as the analog V_{IN} does not exceed the supply voltage by more than 50 mV, the output code will be correct. To achieve an absolute $0 V_{DC}$ to $5 V_{DC}$ input voltage range will therefore require a minimum supply voltage of $4.950 V_{DC}$ over temperature variations, initial tolerance and loading.

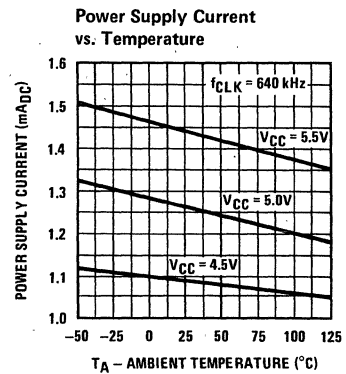
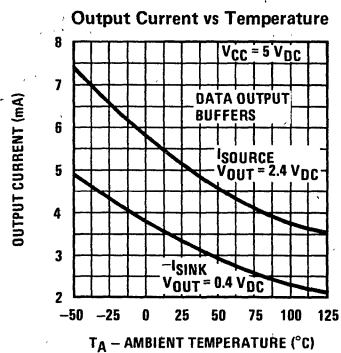
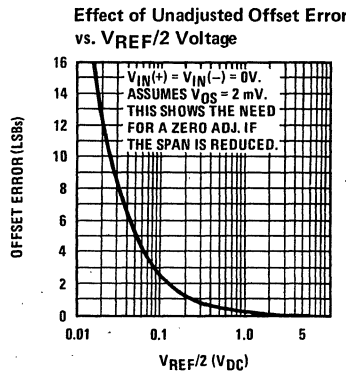
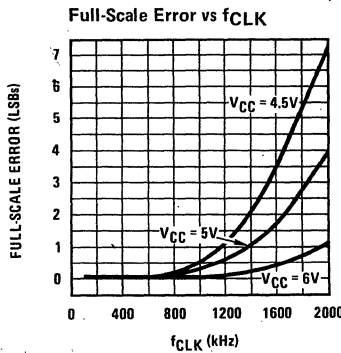
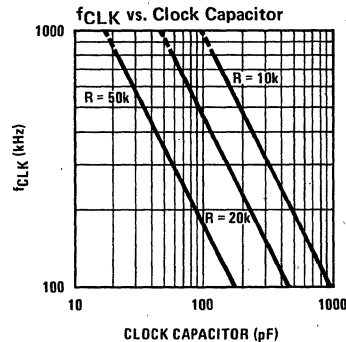
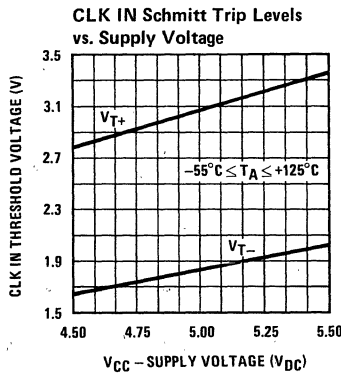
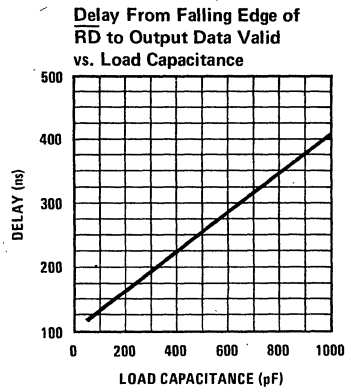
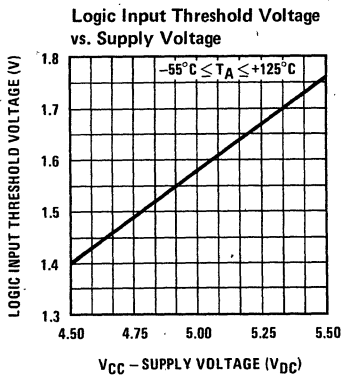
Note 5: With $V_{CC} = 6V$, the digital logic interfaces are no longer TTL compatible.

Note 6: With an asynchronous start pulse, up to 8 clock periods may be required before the internal clock phases are proper to start the conversion process.

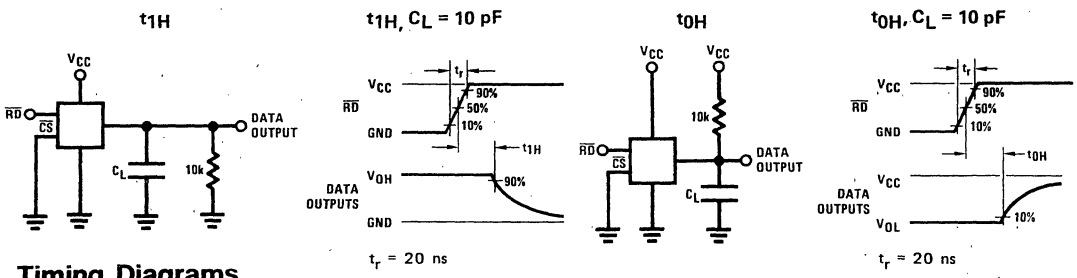
Note 7: The \overline{CS} input is assumed to bracket the \overline{WR} strobe input and therefore timing is dependent on the \overline{WR} pulse width. An arbitrarily wide pulse width will hold the converter in a reset mode and the start of conversion is initiated by the low to high transition of the \overline{WR} pulse (see timing diagrams).

Note 8: None of these A/Ds requires a zero adjust. However, if an all zero code is desired for an analog input other than 0.0V, or if a narrow full-scale span exists (for example: 0.5V to 4.0V full-scale) the $V_{IN(-)}$ input can be adjusted to achieve this. See section 2.5 and Figure 19.

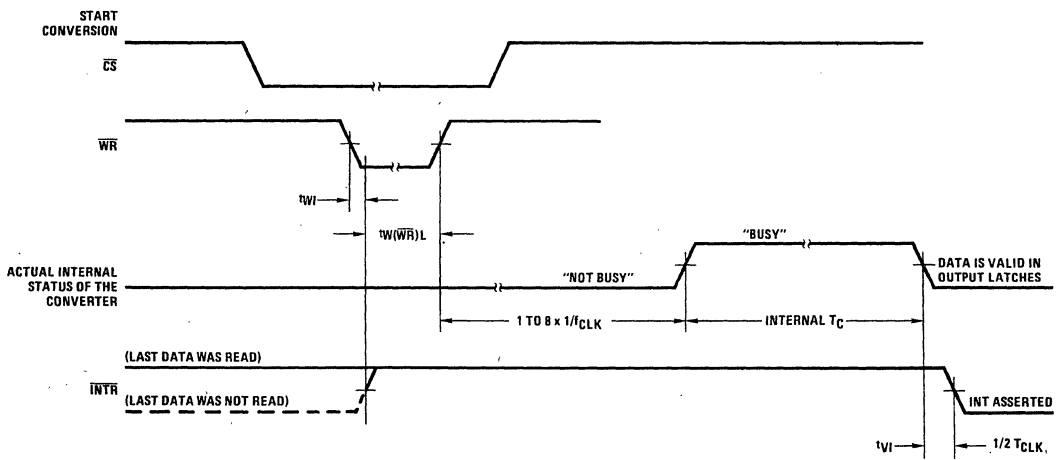
Typical Performance Characteristics



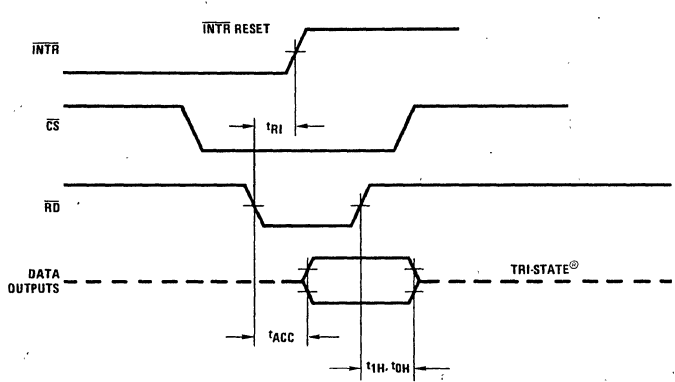
TRI-STATE® Test Circuits and Waveforms



Timing Diagrams



Output Enable and Reset INTR



Note: All timing is measured from the 50% voltage points.

1.0 UNDERSTANDING A/D ERROR SPECS

A perfect A/D transfer characteristic (staircase waveform) is shown in *Figure 1a*. The horizontal scale is analog input voltage and the particular points labeled are in steps of 1 LSB (19.53 mV with 2.5V tied to the VREF/2 pin). The digital output codes which correspond to these inputs are shown as D-1, D, and D+1. For the perfect A/D, not only will center-value (A-1, A, A+1, . . .) analog inputs produce the correct output

digital codes, but also each riser (the transitions between adjacent output codes) will be located ±1/2 LSB away from each center-value. As shown, the risers are ideal and have no width. Correct digital output codes will be provided for a range of analog input voltages which extend ±1/2 LSB from the ideal center-values. Each tread (the range of analog input voltage which provides the same digital output code) is therefore 1 LSB wide.

Figure 1b shows worst case error plot for ADC0801. All center-valued inputs are guaranteed to produce the correct output codes and the adjacent risers are guaranteed to be no closer to the center-value points than $\pm 1/4$ LSB. In other words, if we apply an analog input equal to the center-value $\pm 1/4$ LSB, we guarantee that the A/D will produce the correct digital code. The maximum range of the position of the code transition is indicated by the horizontal arrow and it is guaranteed to be no more than $1/2$ LSB.

The error curve of Figure 1c shows worst case error plot for ADC0802. Here we guarantee that if we apply an analog input equal to the LSB analog voltage center-value the A/D will produce the correct digital code.

Next to each transfer function is shown the corresponding error plot. Many people may be more familiar with error plots than transfer functions. The analog input voltage to the A/D is provided by either a linear ramp or by the discrete output steps of a high resolution DAC. Notice that the error is continuously displayed and includes the quantization uncertainty of the A/D. For example the error at point 1 of Figure 1a is $+1/2$ LSB because the digital code appeared $1/2$ LSB in advance of the center-value of the tread. The error plots always have a constant negative slope and the abrupt upside steps are always 1 LSB in magnitude.

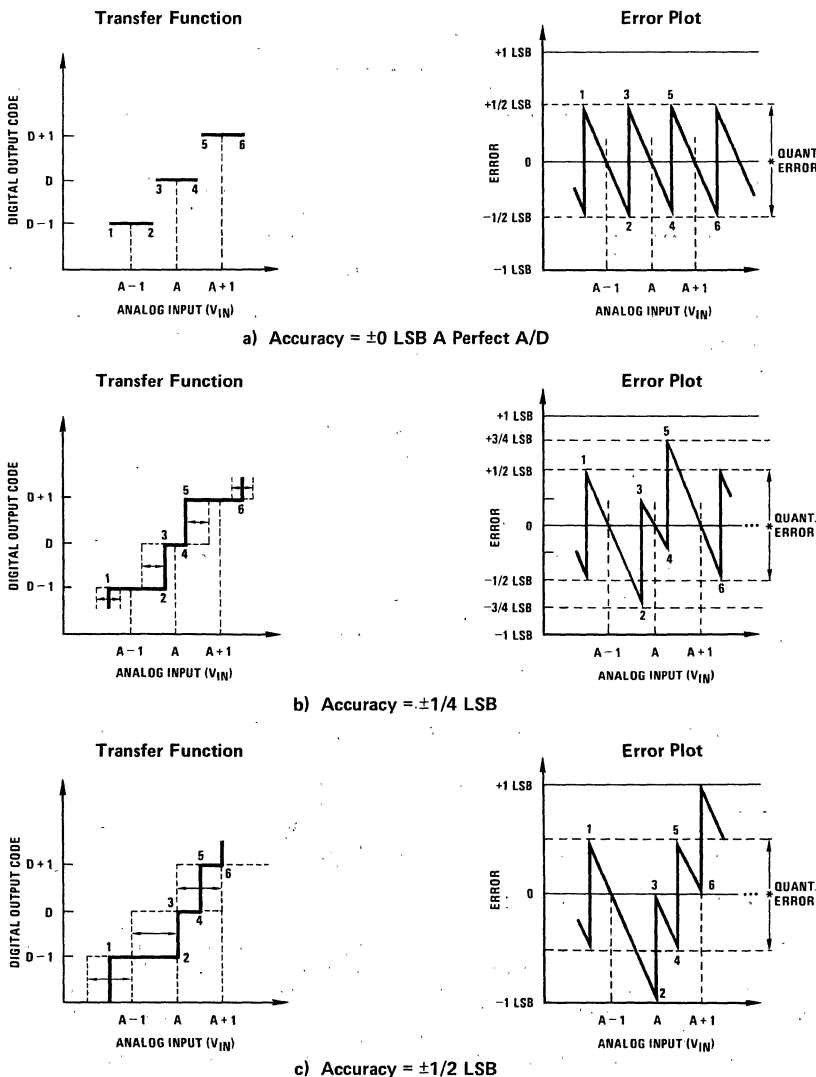


FIGURE 1. Clarifying the Error Specs of an A/D Converter

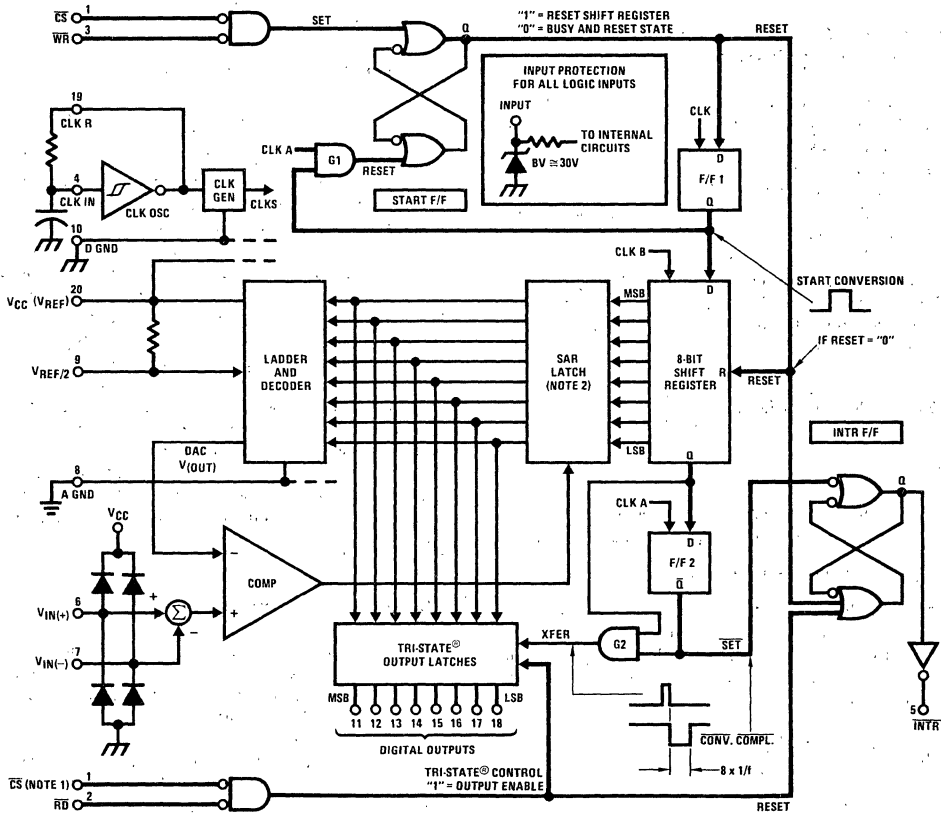
2.0 FUNCTIONAL DESCRIPTION

The ADC0801 series contains a circuit equivalent of the 256R network. Analog switches are sequenced by successive approximation logic to match the analog difference input voltage $[V_{IN(+)} - V_{IN(-)}]$ to a corresponding tap on the R network. The most significant bit is tested first and after 8 comparisons (64 clock cycles) a digital 8-bit binary code (1111 1111 = full-scale) is transferred to an output latch and then an interrupt is asserted (INTR makes a high-to-low transition). The device may be operated in the free-running mode by connecting INTR to the WR input with CS = 0. To insure start-up under all possible conditions, an external WR pulse is required during the first power-up cycle. A conversion in process can be interrupted by issuing a second start command.

On the high-to-low transition of the \overline{WR} input the internal SAR latches and the shift register stages are reset. As long as the CS input and WR input remain low, the A/D will remain in a reset state. Conversion will start from 1 to 8 clock periods after at least one of these inputs makes a low-to-high transition.

A functional diagram of the A/D converter is shown in Figure 2. All of the package pinouts are shown and the major logic control paths are drawn in heavier weight lines.

The converter is started by having \overline{CS} and \overline{WR} simultaneously low. This sets the start flip-flop (F/F) and the resulting "1" level resets the 8-bit shift register, resets the Interrupt (INTR) F/F and inputs a "1" to the D flop, F/F1, which is at the input end of the 8-bit shift register. Internal clock signals then transfer this "1" to the Q output of F/F1. The AND gate, G1, combines this "1" output with a clock signal to provide a reset signal to the start F/F. If the set signal is no longer present (either \overline{WR} or \overline{CS} is a "1") the start F/F is reset and the 8-bit shift register then can have the "1" clocked in, which starts the conversion process. If the set signal were to still be present, this reset pulse would have no effect (both outputs of the start F/F would momentarily be at a "1" level) and the 8-bit shift register would continue to be held in the reset mode. This logic therefore allows for wide CS and \overline{WR} signals and the converter will start after at least one of these signals returns high and the internal clocks again provide a reset signal for the start F/F.



Note 1: \overline{CS} shown twice for clarity.
 Note 2: SAR = Successive Approximation Register.

FIGURE 2. Block Diagram

After the "1" is clocked through the 8-bit shift register (which completes the SAR search) it appears as the input to the D flop, F/F 2. As soon as this "1" is output from the shift register, the AND gate, G2, causes the new digital word to transfer to the TRI-STATE output latches. When F/F 2 is subsequently clocked, the \overline{Q} output makes a high-to-low transition which causes the INTR F/F to set. An inverting buffer then supplies the INTR output signal.

When data is to be read, the combination of both CS and RD being low will cause the INTR F/F to be reset and the TRI-STATE output latches will be enabled to provide the 8-bit digital outputs.

2.1 Digital Control Inputs

The digital control inputs (\overline{CS} , \overline{RD} , and \overline{WR}) meet standard TTL logic voltage levels. These signals have been renamed when compared to the standard A/D Start and Output Enable labels. In addition, these inputs are active low to allow an easy interface to microprocessor control busses. For non-microprocessor based applications, the CS input (pin 1) can be grounded and the standard A/D Start function is obtained by an active low pulse applied at the WR input (pin 3) and the Output Enable function is caused by an active low pulse at the RD input (pin 2).

2.2 Analog Differential Voltage Inputs and Common-Mode Rejection

This A/D has additional applications flexibility due to the analog differential voltage input. The $V_{IN(-)}$ input (pin 7) can be used to automatically subtract a fixed voltage value from the input reading (tare correction). This is also useful in 4 mA–20 mA current loop conversion. In addition, common-mode noise can be reduced by use of the differential input.

The time interval between sampling $V_{IN(+)}$ and $V_{IN(-)}$ is 4-1/2 clock periods. The maximum error voltage due to this slight time difference between the input voltage samples is given by:

$$\Delta V_e(\text{MAX}) = (V_p) (2\pi f_{cm}) \left(\frac{4.5}{f_{CLK}} \right)$$

where:

ΔV_e is the error voltage due to sampling delay

V_p is the peak value of the common-mode voltage

f_{cm} is the common-mode frequency

As an example, to keep this error to 1/4 LSB (~5 mV) when operating with a 60 Hz common-mode frequency, f_{cm} , and using a 640 kHz A/D clock, f_{CLK} , would allow a peak value of the common-mode voltage, V_p , which is given by:

$$V_p = \frac{[\Delta V_e(\text{MAX}) (f_{CLK})]}{(2\pi f_{cm}) (4.5)}$$

or

$$V_p = \frac{(5 \times 10^{-3}) (640 \times 10^3)}{(6.28) (60) (4.5)}$$

which gives

$$V_p \approx 1.9V.$$

The allowed range of analog input voltages usually places more severe restrictions on input common-mode noise levels.

An analog input voltage with a reduced span and a relatively large zero offset can be easily handled by making use of the differential input (see section 2.4 Reference Voltage Flexibility).

2.3 Analog Inputs

2.3.1 Input Current

Due to the internal switching action, displacement currents will flow at the analog inputs. This is due to on-chip stray capacitance to ground. The voltage on this capacitance is switched and will result in currents entering the $V_{IN(+)}$ input and leaving the $V_{IN(-)}$ input which will depend on the analog differential input voltage levels. These current transients occur at the leading edge of the internal clocks. They rapidly decay and *do not cause errors* as the on-chip comparator is strobed at the end of the clock period.

2.3.2 Input Bypass Capacitors

Bypass capacitors at the inputs will average these charges and cause a DC current to flow through the output resistances of the analog signal sources. This charge pumping action is worse for continuous conversions with the $V_{IN(+)}$ input voltage at full-scale. For continuous conversions with a 640 kHz clock frequency with the $V_{IN(+)}$ input at 5V, this DC current is at a maximum of approximately 5 μ A. Therefore, *bypass capacitors should not be used at the analog inputs or the $V_{REF/2}$ pin* for high resistance sources (> 1 k Ω). If input bypass capacitors are necessary for noise filtering and high source resistance is desirable to minimize capacitor size, the detrimental effects of the voltage drop across this input resistance, which is due to the average value of the input current, can be eliminated with a full-scale adjustment while the given source resistor and input bypass capacitor are both in place. This is possible because the average value of the input current is a precise linear function of the differential input voltage.

2.3.3 Input Source Resistance

Large values of source resistance where an input bypass capacitor is not used, *will not cause errors* as the input currents settle out prior to the comparison time. If a low pass filter is required in the system, use a low valued series resistor (≤ 1 k Ω) for a passive RC section or add an op amp RC active low pass filter. For low source resistance applications, (≤ 1 k Ω), a 0.1 μ F bypass capacitor at the inputs will prevent pickup due to series lead inductance of a long wire. A 100 Ω series resistor can be used to isolate this capacitor—both the R and C are placed outside the feedback loop—from the output of an op amp, if used.

2.3.4 Noise

The leads to the analog inputs (pins 6 and 7) should be kept as short as possible to minimize input noise coupling. Both noise and undesired digital clock coupling to these inputs can cause system errors. The source resistance for these inputs should, in general, be kept below 5 k Ω . Larger values of source resistance can cause undesired system noise pickup. Input bypass capacitors, placed from the analog inputs to ground, will eliminate system noise pickup but can create analog scale errors as these capacitors will average the transient input switching currents of the A/D (see section 2.3.3). This scale error depends on both a large source resistance and the use of an input bypass capacitor. This error can be eliminated by doing a full-scale adjustment of the A/D (adjust $V_{REF}/2$ for a proper full-scale reading—see section 2.5.2 on Full-Scale Adjustment) with the source resistance and input bypass capacitor in place.

2.4 Reference Voltage

2.4.1 Span Adjust

For maximum applications flexibility, these A/Ds have been designed to accommodate a 5 V_{DC} , 2.5 V_{DC} or an adjusted voltage reference. This has been achieved in the design of the IC as shown in Figure 3.

Notice that the reference voltage for the IC is either 1/2 of the voltage which is applied to the V_{CC} supply pin, or is equal to the voltage which is externally forced at the $V_{REF}/2$ pin. This allows for a ratiometric voltage reference using the V_{CC} supply, a 5 V_{DC} reference voltage can be used for the V_{CC} supply or a voltage less than 2.5 V_{DC} can be applied to the $V_{REF}/2$ input for increased application flexibility. The internal gain to the $V_{REF}/2$ input is 2 to allow this factor of 2 reduction in the $V_{REF}/2$ voltage.

An example of the use of an adjusted reference voltage is to accommodate a reduced span—or dynamic voltage range of the analog input voltage. If the analog input voltage were to range from 0.5 V_{DC} to 3.5 V_{DC} , instead of 0V to 5 V_{DC} , the span would be 3V. With 0.5 V_{DC} applied to the $V_{IN}(-)$ pin to absorb the offset, the reference voltage can be made equal to 1/2 of the 3V span or 1.5 V_{DC} . The A/D now will encode the $V_{IN}(+)$ signal from 0.5V to 3.5V with the 0.5V input corresponding to zero and the 3.5 V_{DC} input corresponding to full-scale. The full 8 bits of resolution are therefore applied over this reduced analog input voltage range.

2.4.2 Reference Accuracy Requirements

The converter can be operated in a ratiometric mode or an absolute mode. In ratiometric converter applications, the magnitude of the reference voltage is a factor in both the output of the source transducer and the output of the A/D converter and therefore cancels out in the final digital output code. In absolute conversion applications, both the initial value and the temperature stability of the reference voltage are important accuracy factors in the operation of the A/D converter. For $V_{REF}/2$ voltages of 2.5 V_{DC} nominal value, initial errors of ± 10 m V_{DC} will cause conversion errors of ± 1 LSB due to the gain of 2 of the $V_{REF}/2$ input. In reduced span applications, the initial value and the stability of the $V_{REF}/2$ input

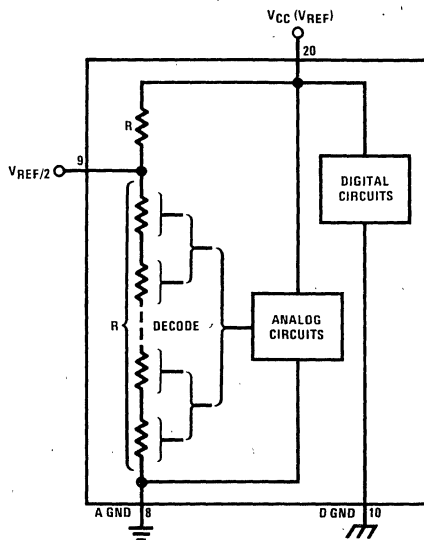


FIGURE 3. The $V_{REFERENCE}$ Design on the IC

voltage become even more important. For example, if the span is reduced to 2.5V, the analog input LSB voltage value is correspondingly reduced from 20 mV (5V span) to 10 mV and 1 LSB at the $V_{REF}/2$ input becomes 5 mV. As can be seen, this reduces the allowed initial tolerance of the reference voltage and requires correspondingly less absolute change with temperature variations. Note that spans smaller than 2.5V place even tighter requirements on the initial accuracy and stability of the reference source.

In general, the magnitude of the reference voltage will require an initial adjustment. Errors due to an improper value of reference voltage appear as full-scale errors in the A/D transfer function. IC voltage regulators may be used for references if the ambient temperature changes are not excessive. The LM336B 2.5V IC reference diode (from National Semiconductor) is available which operates with a 5V input voltage and has a temperature stability of 1.8 mV typ (6 mV max) over $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$. Other temperature range parts are also available.

2.5 Errors

2.5.1 Zero Error

The zero of the A/D does not require adjustment. If the minimum analog input voltage value, $V_{IN(MIN)}$, is not ground, a zero offset can be done. The converter can be made to output 0000 0000 digital code for this minimum input voltage by biasing the A/D $V_{IN}(-)$ input at this $V_{IN(MIN)}$ value (see Applications section). This utilizes the differential mode operation of the A/D.

The zero error of the A/D converter relates to the location of the first riser of the transfer function and can be measured by grounding the $V(-)$ input and applying a small magnitude positive voltage to the $V(+)$

input. Zero error is the difference between the actual DC input voltage which is necessary to just cause an output digital code transition from 0000 0000 to 0000 0001 and the ideal $1/2$ LSB value ($1/2$ LSB = 9.8 mV for $V_{REF}/2 = 2.500$ VDC).

2.5.2 Full-Scale

The full-scale adjustment can be made by applying a differential input voltage which is $1-1/2$ LSB down from the desired analog full-scale voltage range and then adjusting the magnitude of the $V_{REF}/2$ input (pin 9) for a digital output code which is just changing from 1111 1110 to 1111 1111. When offsetting the zero and using a span adjusted $V_{REF}/2$ voltage, the full-scale adjustment is made by inputting V_{MIN} to the $V_{IN}(-)$ input of the A/D and applying a voltage to the $V_{IN}(+)$ input which is given by:

$$V_{IN}(+) \text{ fs adj} = V_{MAX} - 1.5 \left[\frac{(V_{MAX} - V_{MIN})}{256} \right]$$

where:

V_{MAX} = The high end of the analog input range

and

V_{MIN} = the low end (the offset zero) of the analog range. (Both are ground referenced.)

2.6 Clocking Option

The clock for the A/D can be derived from the CPU clock or an external RC can be added to provide self-clocking. The CLK IN (pin 4) makes use of a Schmitt trigger as shown in Figure 4.

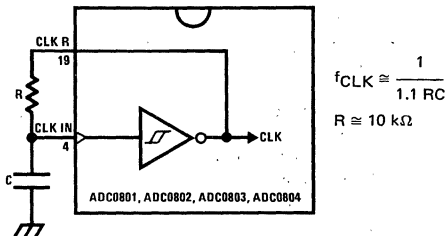


FIGURE 4. Self-Clocking the A/D

Heavy capacitive or DC loading of the clock R pin should be avoided as this will disturb normal converter operation. Loads less than 50 pF, such as driving up to 7 A/D converter clock inputs from a single clock R pin of 1 converter, are allowed. For larger clock line loading, a CMOS or low power T^2L buffer or PNP input logic should be used to minimize the loading on the clock R pin (do not use a standard T^2L buffer).

2.7 Restart During a Conversion

If the A/D is restarted (\overline{CS} and \overline{WR} go low and return high) during a conversion, the converter is reset and a new conversion is started. The output data latch is not

updated if the conversion in process is not allowed to be completed, therefore the data of the previous conversion remains in this latch.

2.8 Continuous Conversions

For operation in the free-running mode an initializing pulse should be used, following power-up, to insure circuit operation. In this application, the \overline{CS} input is grounded and the \overline{WR} input is tied to the \overline{INTR} output. This \overline{WR} and \overline{INTR} node should be momentarily forced to logic low following a power-up cycle to guarantee operation.

2.9 Driving the Data Bus

This MOS A/D, like MOS microprocessors and memories, will require a bus driver when the total capacitance of the data bus gets large. Other circuitry, which is tied to the data bus, will add to the total capacitive loading, even in TRI-STATE (high impedance mode). Backplane bussing also greatly adds to the stray capacitance of the data bus.

There are some alternatives available to the designer to handle this problem. Basically, the capacitive loading of the data bus slows down the response time, even though DC specifications are still met. For systems operating with a relatively slow CPU clock frequency, more time is available in which to establish proper logic levels on the bus and therefore higher capacitive loads can be driven (see typical characteristics curves).

At higher CPU clock frequencies time can be extended for I/O reads (and/or writes) by inserting wait states (8080) or using clock extending circuits (6800).

Finally, if time is short and capacitive loading is high, external bus drivers must be used. These can be TRI-STATE buffers (low power Schottky is recommended such as the DM74LS240 series) or special higher drive current products which are designed as bus drivers. High current bipolar bus drivers with PNP inputs are recommended.

2.10 Power Supplies

Noise spikes on the V_{CC} supply line can cause conversion errors as the comparator will respond to this noise. A low inductance tantalum filter capacitor should be used close to the converter V_{CC} pin and values of 1 μ F or greater are recommended. If an unregulated voltage is available in the system, a separate LM340LAZ-5.0, TO-92, 5V voltage regulator for the converter (and other analog circuitry) will greatly reduce digital noise on the V_{CC} supply.

2.11 Wiring and Hook-Up Precautions

Standard digital wire wrap sockets are not satisfactory for breadboarding this A/D converter. Sockets on PC boards can be used and all logic signal wires and leads should be grouped and kept as far away as possible from the analog signal leads. Exposed leads to the analog inputs can cause undesired digital noise and hum pickup, therefore shielded leads may be necessary in many applications.

A single point analog ground should be used which is separate from the logic ground points. The power supply bypass capacitor and the self-clocking capacitor (if used) should both be returned to digital ground. Any $V_{REF}/2$ bypass capacitors, analog input filter capacitors, or input signal shielding should be returned to the analog ground point. A test for proper grounding is to measure the zero error of the A/D converter. Zero errors in excess of 1/4 LSB can usually be traced to improper board layout and wiring (see section 2.5.1 for measuring the zero error).

3.0 TESTING THE A/D CONVERTER

There are many degrees of complexity associated with testing an A/D converter. One of the simplest tests is to apply a known analog input voltage to the converter and use LEDs to display the resulting digital output code as shown in Figure 5.

For ease of testing, the $V_{REF}/2$ (pin 9) should be supplied with 2.560 V_{DC} and a V_{CC} supply voltage of 5.12 V_{DC} should be used. This provides an LSB value of 20 mV.

If a full-scale adjustment is to be made, an analog input voltage of 5.090 V_{DC} (5.120 - 1/2 LSB) should be applied to the $V_{IN}(+)$ pin with the $V_{IN}(-)$ pin grounded. The value of the $V_{REF}/2$ input voltage should then be adjusted until the digital output code is just changing from 1111 1110 to 1111 1111. This value of $V_{REF}/2$ should then be used for all the tests.

The digital output LED display can be decoded by dividing the 8 bits into 2 hex characters, the 4 most significant (MS) and the 4 least significant (LS). Table I shows the fractional binary equivalent of these two 4-bit groups. By adding the decoded voltages which are obtained from the column: Input voltage value for a 2.560 $V_{REF}/2$ of both the MS and the LS groups, the value of

the digital display can be determined. For example, for an output LED display of 1011 0110 or B6 (in hex), the voltage values from the table are 3.520 + 0.120 or 3.640 V_{DC}. These voltage values represent the center-values of a perfect A/D converter. The effects of quantization error have to be accounted for in the interpretation of the test results.

For a higher speed test system, or to obtain plotted data, a digital-to-analog converter is needed for the test set-up. An accurate 10-bit DAC can serve as the precision voltage source for the A/D. Errors of the A/D under test can be provided as either analog voltages or differences in 2 digital words.

A basic A/D tester which uses a DAC and provides the error as an analog output voltage is shown in Figure 6. The 2 op amps can be eliminated if a lab DVM with a numerical subtraction feature is available to directly readout the difference voltage, "A-C". The analog input voltage can be supplied by a low frequency ramp generator and an X-Y plotter can be used to provide analog error (Y axis) versus analog input (X axis). The construction details of a tester of this type are provided in the NSC application note AN-179, "Analog-to-Digital Converter Testing".

For operation with a microprocessor or a computer-based test system, it is more convenient to present the errors digitally. This can be done with the circuit of Figure 7, where the output code transitions can be detected as the 10-bit DAC is incremented. This provides 1/4 LSB steps for the 8-bit A/D under test. If the results of this test are automatically plotted with the analog input on the X axis and the error (in LSB's) as the Y axis, a useful transfer function of the A/D under test results. For acceptance testing, the plot is not necessary and the testing speed can be increased by establishing internal limits on the allowed error for each code.

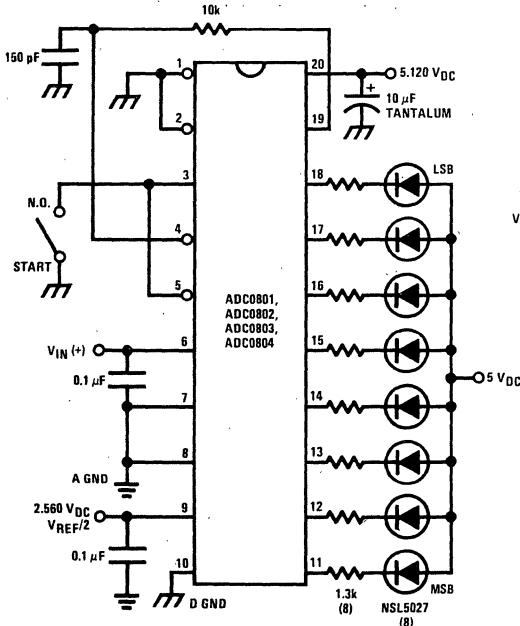


FIGURE 5. Basic A/D Tester

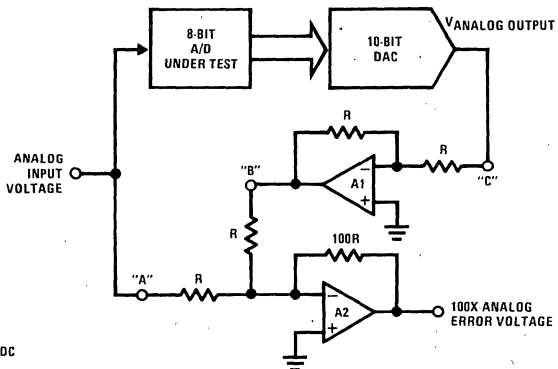


FIGURE 6. A/D Tester with Analog Error Output

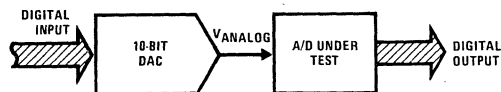


FIGURE 7. Basic "Digital" A/D Tester

TABLE I. DECODING THE DIGITAL OUTPUT LEDs

| HEX | BINARY | FRACTIONAL BINARY VALUE FOR | | OUTPUT VOLTAGE CENTER VALUES WITH $V_{REF/2} = 2.560 V_{DC}$ | |
|-----|---------|-----------------------------|----------|--|------------|
| | | MS GROUP | LS GROUP | VMS GROUP* | VLS GROUP* |
| F | 1 1 1 1 | 15/16 | 15/256 | 4.800 | 0.300 |
| E | 1 1 1 0 | 7/8 | 7/128 | 4.480 | 0.280 |
| D | 1 1 0 1 | 13/16 | 13/256 | 4.160 | 0.260 |
| C | 1 1 0 0 | 3/4 | 3/64 | 3.840 | 0.240 |
| B | 1 0 1 1 | 11/16 | 11/256 | 3.520 | 0.220 |
| A | 1 0 1 0 | 5/8 | 5/128 | 3.200 | 0.200 |
| 9 | 1 0 0 1 | 9/16 | 9/256 | 2.880 | 0.180 |
| 8 | 1 0 0 0 | 1/2 | 1/32 | 2.560 | 0.160 |
| 7 | 0 1 1 1 | 7/16 | 7/256 | 2.240 | 0.140 |
| 6 | 0 1 1 0 | 3/8 | 3/128 | 1.920 | 0.120 |
| 5 | 0 1 0 1 | 5/16 | 5/256 | 1.600 | 0.100 |
| 4 | 0 1 0 0 | 1/4 | 1/64 | 1.280 | 0.080 |
| 3 | 0 0 1 1 | 3/16 | 3/256 | 0.960 | 0.060 |
| 2 | 0 0 1 0 | 1/8 | 1/128 | 0.640 | 0.040 |
| 1 | 0 0 0 1 | 1/16 | 1/256 | 0.320 | 0.020 |
| 0 | 0 0 0 0 | | | 0 | 0 |

*V Display Output = VMS Group + VLS Group

4.0 MICROPROCESSOR INTERFACING

To discuss the interface with 8080A, 6800 and SC/MP-II microprocessors, a common sample subroutine structure is used. The microprocessor starts the A/D, reads and stores the results of 16 successive conversions, then returns to the user's program. The 16 data bytes are stored at location 0200 to 020F. All Data and Addresses will be given in hexadecimal form. Software and hardware details are provided separately for each type of microprocessor.

4.1 Interfacing 8080 Microprocessor Derivatives (8048, 8085)

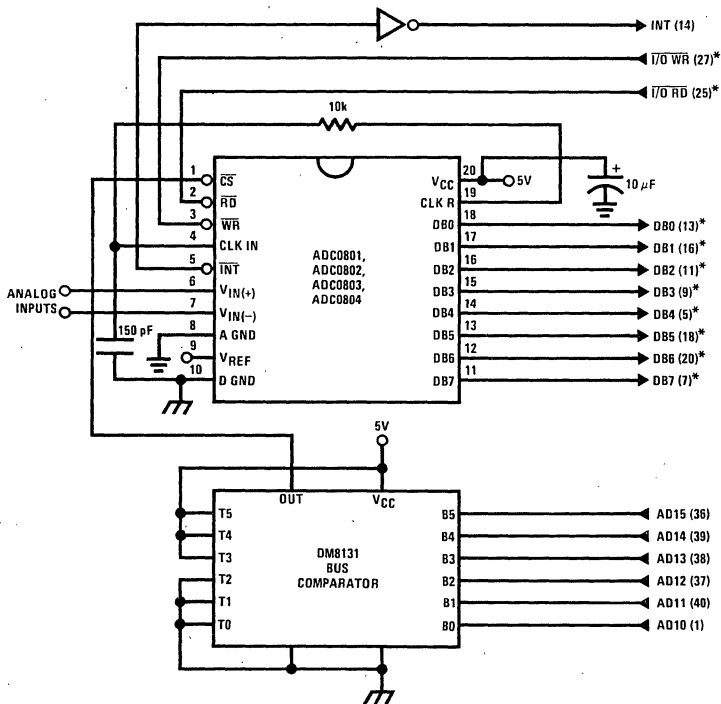
This converter has been designed to directly interface with an 8080A-2 microprocessor (MICROBUS class 2). The A/D can be mapped into memory space (using standard memory address decoding for CS and the MEMR and MEMW strobes) or it can be controlled as an I/O device by using the I/O R and I/O W strobes and decoding the address bits A0 → A7 (or address bits A8 → A15 as they will contain the same 8-bit address information) to obtain the CS input. Using the I/O space provides 256 additional addresses and may allow a simpler 8-bit address decoder but the data can only be input to the accumulator. To make use of the additional memory reference instructions, the A/D should be mapped into memory space. An example of an A/D in I/O space is shown in Figure 8.

The standard control bus signals of the 8080 (CS, RD and WR) can be directly wired to the digital control inputs of the A/D and the bus timing requirements are met to allow both starting the converter and outputting the data onto the data bus. A bus driver should be used for larger microprocessor systems where the data bus leaves the PC board and/or must drive capacitive loads larger than 100 pF.

4.1.1 Sample 8080A CPU Interfacing Circuitry and Program

The following sample program and associated hardware may be used to input data from the converter to the INS8080A CPU chip set (comprised of the INS8080A microprocessor, the INS8228 system controller and the INS8224 clock generator). For simplicity, the A/D is controlled as an I/O device, specifically an 8-bit bi-directional port located at an arbitrarily chosen port address, E0. The TRI-STATE output capability of the A/D eliminates the need for a peripheral interface device, however address decoding is still required to generate the appropriate CS for the converter.

It is important to note that in systems where the A/D converter is 1-of-8 or less I/O mapped devices, no address decoding circuitry is necessary. Each of the 8 address bits (A0 to A7) can be directly used as CS inputs—one for each I/O device.



Note 1: *Pin numbers for the INS8228 system controller, others are INS8080A.

Note 2: Pin 23 of the INS8228 must be tied to +12V through a 1 k Ω resistor to generate the RST 7 instruction when an interrupt is acknowledged as required by the accompanying sample program.

FIGURE 8. ADC0801-INS8080A CPU Interface

SAMPLE PROGRAM FOR FIGURE 8 ADC0801-INS8080A CPU INTERFACE

```

0038    C3 00 03    RST 7:          JMP     LD DATA
.
.
.
0100    21 00 02    START:          LXI H 0200H           ; HL pair will point to
.                                     ; data storage locations
0103    31 00 04    RETURN:         LXI SP 0400H        ; Initialize stack pointer (Note 1)
0106    7D          MOV A, L           ; Test # of bytes entered
0107    FE 0F      CPI OF H          ; If # = 16. JMP to
0109    CA 13 01   JZ CONT          ; user program
010C    D3 E0      OUT E0 H        ; Start A/D
010E    FB          EI           ; Enable interrupt
010F    00          NOP           ; Loop until end of
0110    C3 0F 01   JMP LOOP        ; conversion
0113    .          .
.
.          (User program to
.          process data)
.
.
0300    DB E0      LD DATA:      IN E0 H           ; Load data into accumulator
0302    77          MOV M, A          ; Store data
0303    23          INX H           ; Increment storage pointer
0304    C3 03 01   JMP RETURN

```

Note 1: The stack pointer must be dimensioned because a RST 7 instruction pushes the PC onto the stack.

Note 2: All addresses used were arbitrarily chosen.

4.2 Interfacing the Z-80

The Z-80 control bus is slightly different from that of the 8080. General RD and WR strobes are provided and separate memory request, MREQ, and I/O request, IORQ, signals are used which have to be combined with the generalized strobes to provide the equivalent 8080 signals. An advantage of operating the A/D in I/O space with the Z-80 is that the CPU will automatically insert one wait state (the RD and WR strobes are extended one clock period) to allow more time for the I/O devices to respond. Logic to map the A/D in I/O space is shown in Figure 9.

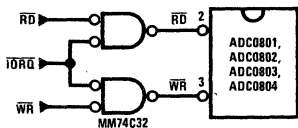


FIGURE 9. Mapping the A/D as an I/O device for use with the Z-80 CPU

Additional I/O advantages exist as software DMA routines are available and use can be made of the output data transfer which exists on the upper 8 address lines (A8 to A15) during I/O input instructions. For example, MUX channel selection for the A/D can be accomplished with this operating mode.

4.3 Interfacing 6800 Microprocessor Derivatives (6502, etc.)

The control bus for the 6800 microprocessor derivatives does not use the RD and WR strobe signals. Instead it employs a single R/W line and additional timing, if needed, can be derived from the $\phi 2$ clock. All I/O devices are memory mapped in the 6800 system, and a special signal, VMA, indicates that the current address is valid. Figure 10 shows an interface schematic where the A/D is memory mapped in the 6800 system. For simplicity, the CS decoding is shown using 1/2 DM8092. Note that in many 6800 systems, an already decoded $4/5$ line is brought out to the common bus at pin 21. This can be tied directly to the CS pin of the A/D, provided that no other devices are addressed at HEX ADDR: 4XXX or 5XXX.

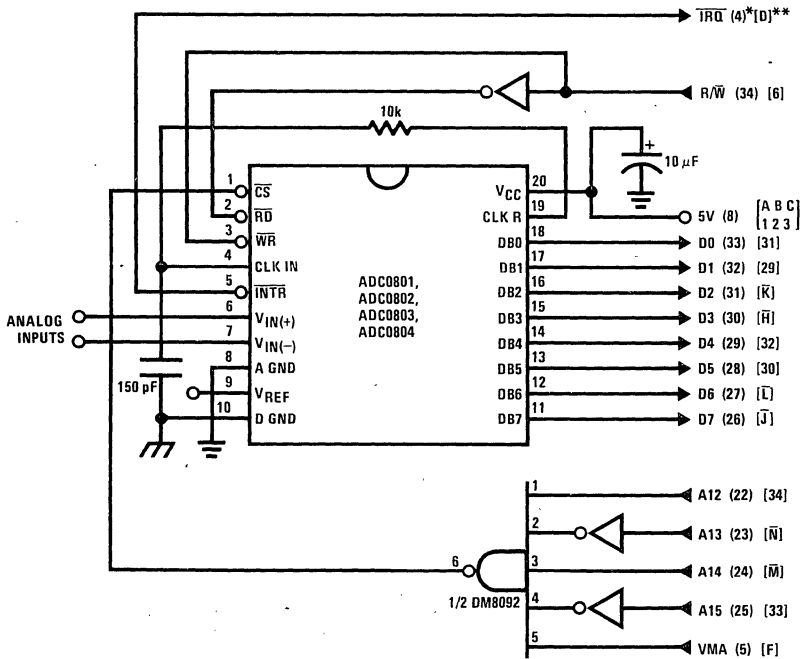
The following subroutine essentially performs the same function as in the case of the 8080A interface and it can be called from anywhere in the user's program.

In Figure 11 the ADC0801 series is interfaced to the M6800 microprocessor through (the arbitrarily chosen) Port B of the MC6820 or MC6821 Peripheral Interface Adapter, (PIA). Here the CS pin of the A/D is grounded since the PIA is already mapped in the M6800 system and no CS decoding is necessary. Also notice that the A/D output data lines are connected to the microprocessor bus under program control through the PIA and therefore the A/D RD pin can be grounded.

SAMPLE PROGRAM FOR FIGURE 10 ADC0801—MC6800 CPU INTERFACE

| | | | | | |
|------|----------|--------|------|----------|---|
| 0010 | DF 36 | DATIN | STX | TEMP2 | ; Save contents of X |
| 0012 | CE 00 2C | | LDX | #\$002C | ; Upon IRO low CPU |
| 0015 | FF FF F8 | | STX | \$\$\$F8 | ; jumps to 002C |
| 0018 | B7 50 00 | | STAA | \$5000 | ; Starts ADC0801 |
| 001B | 0E | | CLI | | |
| 001C | 3E | CONVRT | WAI | | ; Wait for interrupt |
| 001D | DE 34 | | LDX | TEMP1 | |
| 001F | 8C 02 0F | | CPX | #\$020F | ; Is final data stored? |
| 0022 | 27 14 | | BEQ | ENDP | |
| 0024 | B7 50 00 | | STAA | \$5000 | ; Restarts ADC0801 |
| 0027 | 08 | | INX | | |
| 0028 | DF 34 | | STX | TEMP1 | |
| 002A | 20 F0 | | BRA | CONVRT | |
| 002C | DE 34 | INTRPT | LDX | TEMP1 | |
| 002E | B6 50 00 | | LDAA | \$5000 | ; Read data |
| 0031 | A7 00 | | STAA | X | ; Store it at X |
| 0033 | 3B | | RTI | | |
| 0034 | 02 00 | TEMP1 | FDB | \$0200 | ; Starting address for ; data storage |
| 0036 | 00 00 | TEMP2 | FDB | \$0000 | |
| 0038 | CE 02 00 | ENDP | LDX | #\$0200 | ; Reinitialize TEMP1 |
| 003B | DF 34 | | STX | TEMP1 | |
| 003D | DE 36 | | LDX | TEMP2 | |
| 003F | 39 | | RTS | | ; Return from subroutine ; To user's program |

Note 1: In order for the microprocessor to service subroutines and interrupts, the stack pointer must be dimensioned in the user's program.



Note 1: Numbers in parentheses refer to MC6800 CPU pin out.

Note 2: Numbers or letters in brackets refer to standard M6800 system common bus code.

FIGURE 10. ADC0801 – MC6800 CPU Interface

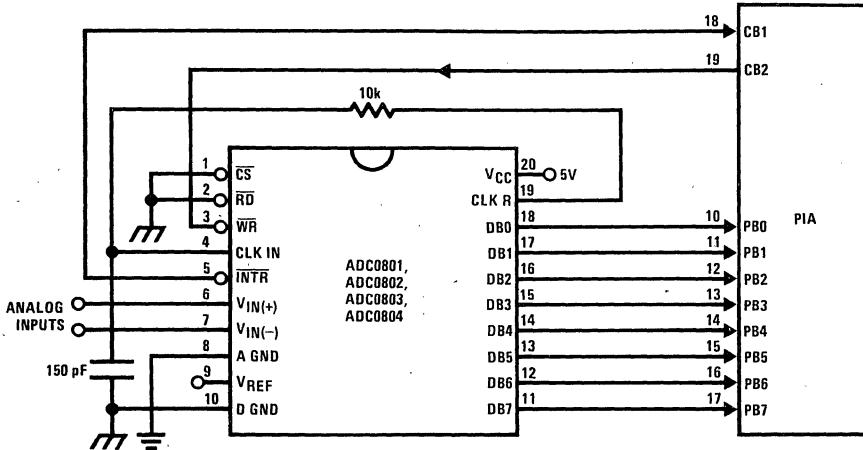


FIGURE 11. ADC0801-MC6820 PIA Interface

A sample interface program equivalent to the previous one, is shown below. The PIA Data and Control Registers of Port B are located at HEX addresses 8006 and 8007, respectively.

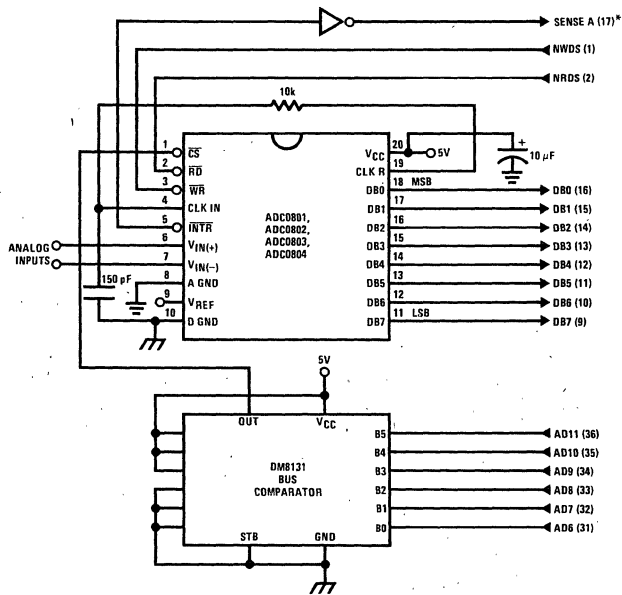
4.4 Interfacing the INS8060-SC/MP-II

The SC/MP-II interface technique with the ADC0801 series *Figure 12*, is similar to the 8080A CPU interface.

SAMPLE PROGRAM FOR FIGURE 11 ADC0801-MC6820 PIA INTERFACE

```

0010 CE 00 38    DATAIN  LDX    #S0038    ; Upon  $\overline{IRQ}$  low CPU
0013 FF FF F8    STX    $FFFF    ; jumps to 003B
0016 B6 80 06    LDAA   PIAORB    ; Clear possible  $\overline{IRQ}$  flags
0019 4F          CLRA
001A B7 80 07    STAA   PIACRB
001D B7 80 06    STAA   PIAORB    ; Set Port B as input
0020 0E          CLI
0021 C6 34          LDAB   #S34
0023 86 3D          LDAA   #S3D
0025 F7 80 07    CONVRT  STAB   PIACRB    ; Starts ADC0801
0028 B7 80 07    STAA   PIACRB
002B 3E          WAI          ; Wait for interrupt
002C DE 40          LDX    TEMP1
002E 8C 02 0F    CPX    #S020F    ; Is final data stored?
0031 27 0F          BEQ    ENDP
0033 08          INX
0034 DF 40          STX    TEMP1
0036 20 ED          BRA    CONVRT
0038 DE 40          INTRPT  LDX    TEMP1
003A B6 80 06    LDAA   PIAORB    ; Read data in
003D A7 00          STAA   X          ; Store it at X
003F 3B          RTI
0040 02 00          TEMP1  FDB    S0200    ; Starting address for
                                ; data storage
0042 CE 02 00    ENDP    LDX    #S0200    ; Reinitialize TEMP1
0045 DF 40          STX    TEMP1
0047 39          RTS          ; Return from subroutine
                                ; To user's program
                                PIAORB  EQU    S8006
                                PIACRB  EQU    S8007
    
```



*Pin numbers in parentheses are for the SC/MP CPU.

FIGURE 12. ADC0801 - SC/MP-II Microprocessor Interface

The A/D is treated as a peripheral and it is mapped into the memory space of the SC/MP-II system. An address, 0D00, is assigned to the A/D and the CS signal is shown to be decoded by a bus comparator, DM8131. The RD and WR pins of the A/D are tied directly to the Write Data Strobe, NWRS, and Read Data Strobe, NRDS, pins of the SC/MP-II CPU. Notice that the INTR signal should be inverted before being tied to the SENSE A pin of the SC/MP-II. A sample interface program is shown below.

5.0 GENERAL APPLICATIONS

The following applications show some interesting uses for the A/D. The fact that one particular microprocessor is used is not meant to be restrictive. Each of these appli-

cation circuits would have its counterpart using any microprocessor which is desired.

5.1 Multiple ADC0801 Series to MC6800 CPU Interface

To transfer analog data from several channels to a single microprocessor system, a multiple converter scheme presents several advantages over the conventional multiplexer single-converter approach. With the ADC0801 series, the differential inputs allow individual span adjustment for each channel. Furthermore, all analog input channels are sensed simultaneously, which essentially divides the microprocessor's total system servicing time by the number of channels, since all conversions occur simultaneously. This scheme is shown in *Figure 13*.

SAMPLE PROGRAM FOR FIGURE 12 ADC0801—SC/MP-II MICROPROCESSOR INTERFACE

```

0100      08          NOP
0101     C4 02      LD102
0103      35          XPAH(P1)
0104     C4 0D      LD10D
0106      36          XPAH(P2)
0107     C4 03      LD103
0109      37          XPAH(P3)
010A     C4 00      LD100
010C      31          XPAL(P1)      ; P1=0200, P1 points to 1st byte address
010D     C4 00      LD100
010F     C9 11      ST(P1+11)      ; Zero the byte count in address 0211
0112      32          XPAL(P2)      ; P2=0D00, P2 points to A/D
0113     CA 00      START: ST(P2)      ; START the A/D
0115     C4 00      LD100
0117      33          XPAL(P3)      ; P3=0300, P3 points to DATA in sub.
0118      05          IEN          ; starting address
0119      08          LOOP:  NOP
011A     90 FE      JMP(L00P)

                                User's Program
011C     USER      NOP
011D      NOP

                                .
                                .
0300     C2 00      DATA IN: LD(P2)      ; Load A/D data into accumulator
0302     CD 01      ST@1(P1)      ; Store A/D data and increment byte
                                ; address
0304     A9 11      1LD(P1+11)      ; Increment byte count
0306     C4 0F      LD10F
0308      03          SCL
0309     F9 11      CAD(P1+11)      ; 0F-(P1+11): Is byte count = 16?
030B     9B 03      JZ(USER)      ; If byte count = 16 jump to user's
                                ; program
030D     C4 13      LD113
030F      33          XPAL(P3)      ; P3=0113
0310     3F          XPPC(P3)      ; Go to START and do another conversion

```

The following schematic and sample subroutine (DATA IN) may be used to interface (up to) 8 ADC0801's directly to the MC6800 CPU. This scheme can easily be extended to allow the interface of more converters. In this configuration the converters are (arbitrarily) located at HEX address 5000 in the MC6800 memory space. To save components, the clock signal is derived from just one RC pair on the first converter. This output drives the other A/Ds.

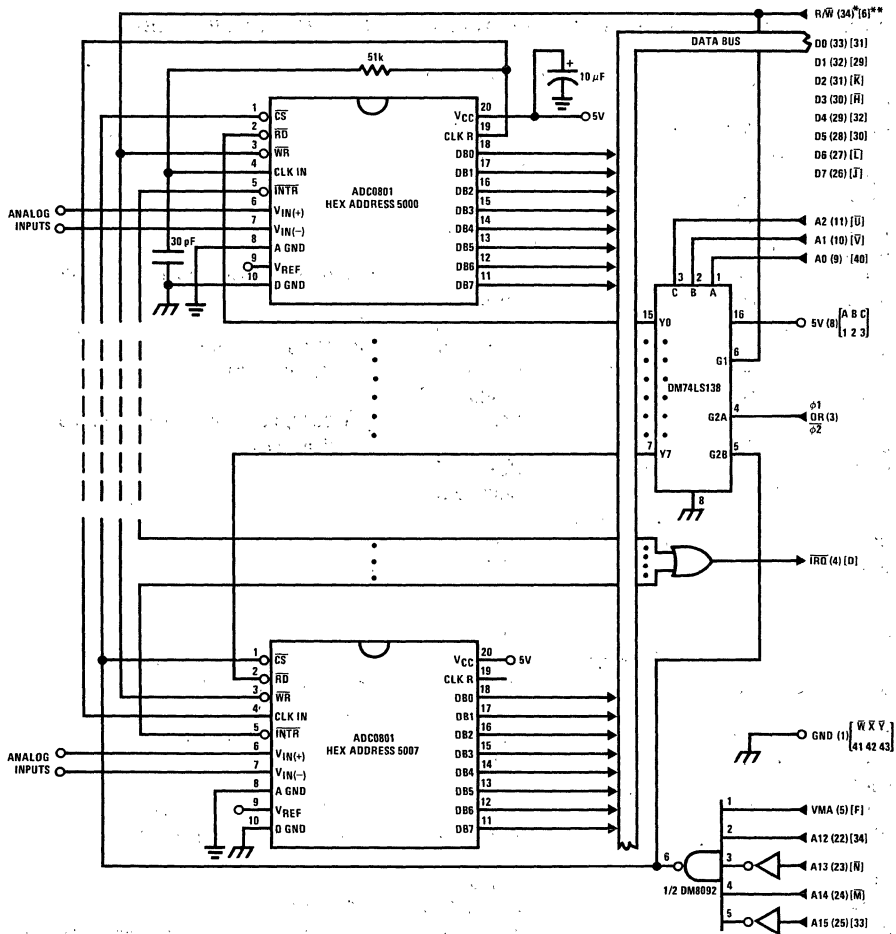
All the converters are started simultaneously with a STORE instruction at HEX address 5000. Note that any other HEX address of the form 5XXX will be decoded by the circuit, pulling all the CS inputs low. This can easily be avoided by using a more definitive address decoding scheme. All the interrupts are ORed together to insure that all A/Ds have completed their conversion before the microprocessor is interrupted.

The subroutine, DATA IN, may be called from anywhere in the user's program. Once called, this routine initializes

the CPU, starts all the converters simultaneously and waits for the interrupt signal. Upon receiving the interrupt, it reads the converters (from HEX addresses 5000 through 5007) and stores the data successively at (arbitrarily chosen) HEX addresses 0200 to 0207, before returning to the user's program. All CPU registers then recover the original data they had before servicing DATA IN.

5.2 Auto-Zeroed Differential Transducer Amplifier and A/D Converter

The differential inputs of the ADC0801 series eliminate the need to perform a differential to single ended conversion for a differential transducer. Thus, one op amp can be eliminated since the differential to single ended conversion is provided by the differential input of the ADC0801 series. In general, a transducer preamp is required to take advantage of the full A/D converter input dynamic range.



Note 1: Numbers in parentheses refer to MC6800 CPU pin out.

Note 2: Numbers or letters in brackets refer to standard M6800 system common bus code.

FIGURE 13. Interfacing Multiple A/Ds in a MC6800 System

PROGRAM FOR FIGURE 13 INTERFACING MULTIPLE A/Ds IN AN MC6800 SYSTEM

| ADDRESS | HEX CODE | MNEMONICS | COMMENTS |
|---------|----------|-------------------|-------------------------------------|
| 0010 | DF 44 | DATAIN STX TEMP | ; Save Contents of X |
| 0012 | CE 00 2A | LDX #002A | ; Upon IRO LOW CPU |
| 0015 | FF FF F8 | STX \$FFF8 | ; Jumps to 002A |
| 0018 | B7 50 00 | STAA \$5000 | ; Starts all A/D's |
| 001B | 0E | CLI | |
| 001C | 3E | WAI | ; Wait for interrupt |
| 001D | CE 50 00 | LDX #5000 | |
| 0020 | DF 40 | STX INDEX1 | ; Reset both INDEX |
| 0022 | CE 02 00 | LDX #0200 | ; 1 and 2 to starting |
| 0025 | DF 42 | STX INDEX2 | ; addresses |
| 0027 | DE 44 | LDX TEMP | |
| 0029 | 39 | RTS | ; Return from subroutine |
| 002A | DE 40 | INTRPT LDX INDEX1 | ; INDEX1 → X |
| 002C | A6 00 | LDAA X | ; Read data in from A/D at X |
| 002E | 08 | INX | ; Increment X by one |
| 002F | DF 40 | STX INDEX1 | ; X → INDEX1 |
| 0031 | DE 42 | LDX INDEX2 | ; INDEX2 → X |
| 0033 | A7 00 | STAA X | ; Store data at X |
| 0035 | 8C 02 07 | CPX #0207 | ; Have all A/D's been read? |
| 0038 | 27 05 | BEQ RETURN | ; Yes: branch to RETURN |
| 003A | 08 | INX | ; No: increment X by one |
| 003B | DF 42 | STX INDEX2 | ; X → INDEX2 |
| 003D | 20 EB | BRA INTRPT | ; Branch to 002A |
| 003F | 3B | RETURN RTI | |
| 0040 | 50 00 | INDEX1 FDB \$5000 | ; Starting address for A/D |
| 0042 | 02 00 | INDEX2 FDB \$0200 | ; Starting address for data storage |
| 0044 | 00 00 | TEMP FDB \$0000 | |

Note 1: In order for the microprocessor to service subroutines and interrupts, the stack pointer must be dimensioned in the user's program.

For amplification of DC input signals, a major system error is the input offset voltage of the amplifiers used for the preamp. Figure 14 is a gain of 100 differential preamp whose offset voltage errors will be cancelled by a zeroing subroutine which is performed by the INS8080A microprocessor system. The total allowable input offset voltage error for this preamp is only 50 μV for 1/4 LSB error. This would obviously require very precise amplifiers. The expression for the differential output voltage of the preamp is:

$$V_o = \underbrace{[V_{IN(+)} - V_{IN(-)}]}_{\text{SIGNAL}} \underbrace{\left[1 + \frac{2R_2}{R_1}\right]}_{\text{GAIN}} + \underbrace{(V_{os2} - V_{os1} - V_{os3} \pm I_x R_x)}_{\text{DC ERROR TERM}} \underbrace{\left(1 + \frac{2R_2}{R_1}\right)}_{\text{GAIN}}$$

where I_x is the current through resistor R_x . All of the offset error terms can be cancelled by making $\pm I_x R_x = V_{os1} + V_{os3} - V_{os2}$. This is the principle of this auto-zeroing scheme.

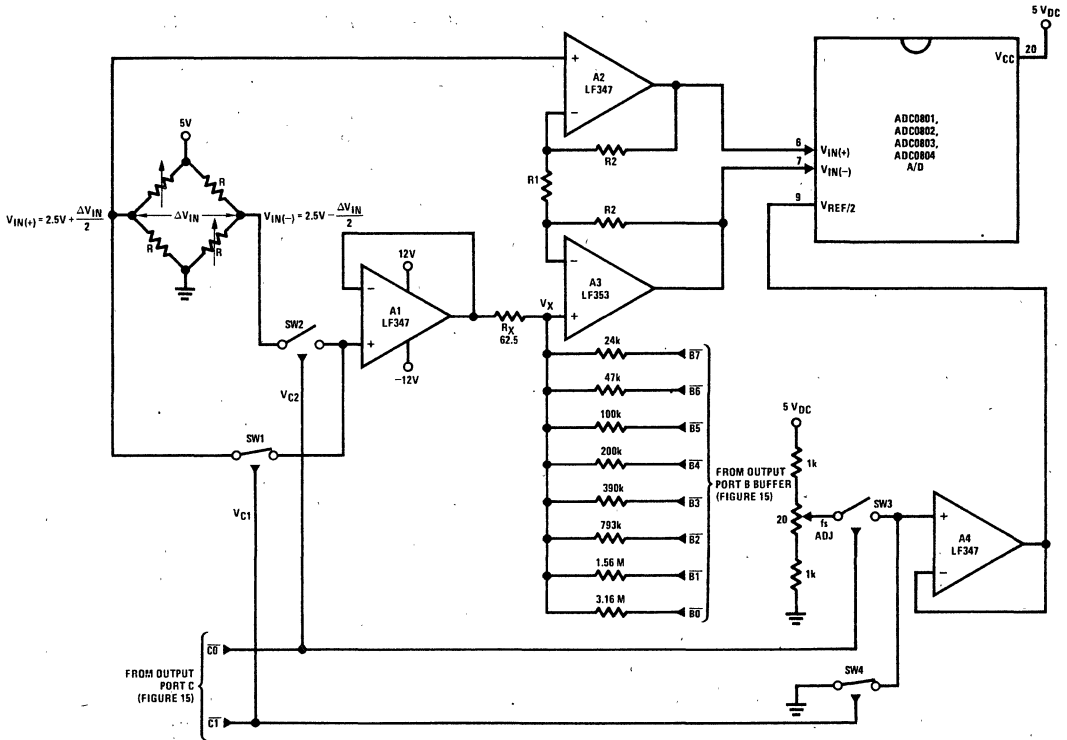
The INS8080A uses the 3 I/O ports of an INS8255 Programmable Peripheral Interface (PPI) to control the auto zeroing and input data from the ADC0801 as shown in Figure 15. The PPI is programmed for basic I/O operation (mode 0) with Port A being an input port and Ports B and C being output ports. Two bits of Port C are used to alternately open or close the 2 switches at the input

of the preamp. Switch SW1 is closed to force the preamp's differential input to be zero during the zeroing subroutine and then opened and SW2 is then closed for conversion of the actual differential input signal. Using 2 switches in this manner eliminates concern for the ON resistance of the switches as they must conduct only the input bias current of the input amplifiers.

Output Port B is used as a successive approximation register by the 8080 and the binary scaled resistors in series with each output bit create a D/A converter. During the zeroing subroutine, the voltage at V_x increases or decreases as required to make the differential output voltage equal to zero. This is accomplished by insuring that the voltage at the output of A1 is approximately 2.5V so that a logic "1" (5V) on any output of Port B will source current into node V_x thus raising the voltage at V_x and making the output differential more negative. Conversely, a logic "0" (0V) will pull current out of node V_x and decrease the voltage, causing the differential output to become more positive. For the resistor values shown, V_x can move ± 12 mV with a resolution of 50 μV which will null the offset error term to 1/4 LSB of full-scale for the ADC0801. It is important that the voltage levels which drive the auto-zero resistors be constant. Also, for symmetry, a logic swing of 0V to 5V is convenient. To achieve this, a CMOS buffer is used for the logic output signals of Port B and this CMOS package is powered with a stable 5V source. Buffer amplifier A1 is necessary so that it can source or sink the D/A output current.



ADC0801, ADC0802, ADC0803, ADC0804



- Note 1: $R2 = 49.5 R1$
- Note 2: Switches are CD4066BC CMOS analog switches.
- Note 3: The 9 resistors used in the auto-zero section can be $\pm 5\%$ tolerance.

FIGURE 14. Gain of 100 Differential Transducer Preamp

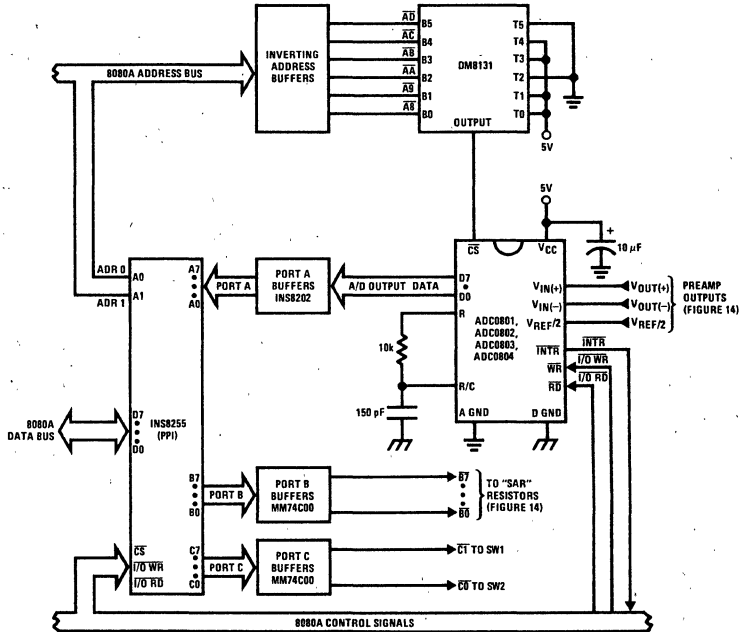


FIGURE 15. Microprocessor Interface Circuitry for Differential Preamp

A flow chart for the zeroing subroutine is shown in Figure 16. It must be noted that the ADC0801 series will output an all zero code when it converts a negative input [$V_{IN(-)} \geq V_{IN(+)}$]. Also, a logic inversion exists as all of the I/O ports are buffered with inverting gates.

Basically, if the data read is zero, the differential output voltage is negative, so a bit in Port B is cleared to pull V_x more negative which will make the output more positive for the next conversion. If the data read is not zero, the output voltage is positive so a bit in Port B is set to make V_x more positive and the output more negative. This continues for 8 approximations and the differential output eventually converges to within 5 mV of zero.

The actual program is given in Figure 17. All addresses used are compatible with the BLC 80/10 microcomputer system. In particular:

- Port A and the ADC0801 are at port address E4
- Port B is at port address E5
- Port C is at port address E6
- PPI control word port is at port address E7
- Program Counter automatically goes to ADDR:3C3D upon acknowledgement of an interrupt from the ADC0801

5-3 Multiple A/D Converters in a Z-80 Interrupt Driven Mode

In data acquisition systems where more than one A/D converter (or other peripheral device) will be interrupting program execution of a microprocessor, there is obviously a need for the CPU to determine which device requires servicing. Figure 18 and the accompanying software is a method of determining which of 7 ADC0801 converters has completed a conversion (INTR asserted) and is requesting an interrupt. This circuit allows starting the A/D converters in any sequence, but will input and store valid data from the converters with a priority sequence of A/D 1 being read first, A/D 2 second, etc., through A/D 7 which would have the lowest priority for data being read. Only the converters whose INT is asserted will be read.

The key to decoding circuitry is the MM74LS373, 8-bit D type flip-flop. When the Z-80 acknowledges the interrupt, the program is vectored to a data input Z-80 subroutine. This subroutine will read a peripheral status word from the MM74LS373 which contains the logic state of the INTR outputs of all the converters. Each converter which initiates an interrupt will place a logic "0" in a unique bit position in the status word and the subroutine will determine the identity of the converter and execute a data read. An identifier word (which indicates which A/D the data came from) is stored in the next sequential memory location above the location of the data so the program can keep track of the identity of the data entered.

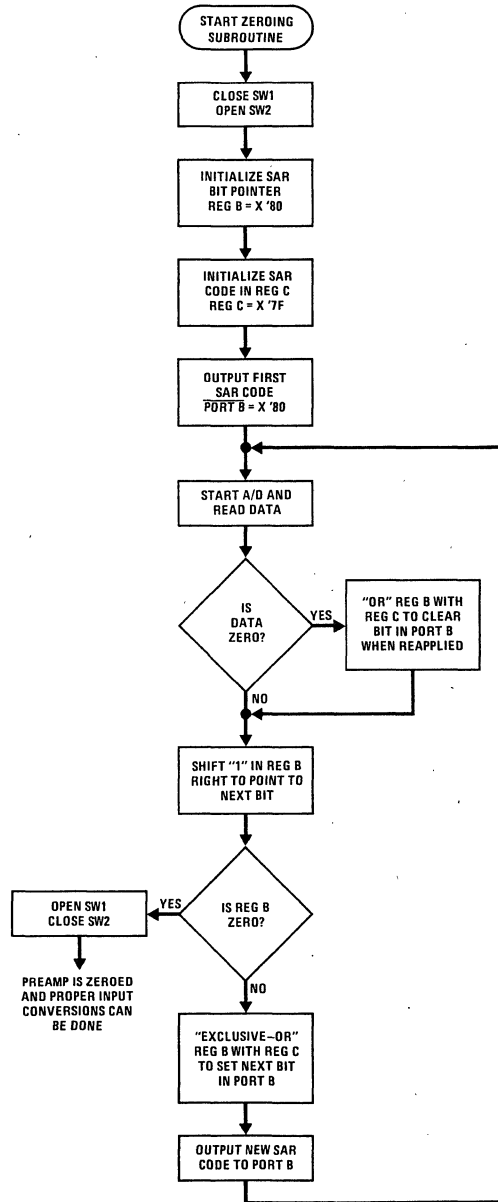


FIGURE 16. Flow Chart for Auto-Zero Routine

| | | | | |
|---|--------|------------------|----------------------|--|
| 3D00 | 3E90 | MVI 90 | | |
| 3D02 | D3E7 | Out Control Port | | ; Program PPI |
| 3D04 | 2601 | MVI H 01 | Auto-Zero Subroutine | |
| 3D06 | 7C | MOV A,H | | |
| 3D07 | D3E6 | OUT C | | ; Close SW1, open SW2 |
| 3D09 | 0680 | MVI B 80 | | ; Initialize SAR bit pointer |
| 3D0B | 3E7F | MVI A 7F | | ; Initialize SAR code |
| 3D0D | 4F | MOV C,A | Return | |
| 3D0E | D3E5 | OUT B | | ; Port B = SAR code |
| 3D10 | 31AA3D | LXI SP 3DAA | Start | ; Dimension stack pointer |
| 3D13 | D3E4 | OUT A | | ; Start A/D |
| 3D15 | FB | IE | | |
| 3D16 | 00 | NOP | Loop | ; Loop until \overline{INT} asserted |
| 3D17 | C3163D | JMP Loop | | |
| 3D1A | 7A | MOV A,D | Auto-Zero | |
| 3D1B | C600 | ADI 00 | | |
| 3D1D | CA2D3D | JZ Set C | | ; Test A/D output data for zero |
| 3D20 | 78 | MOV A,B | Shift B | |
| 3D21 | F600 | ORI 00 | | ; Clear carry |
| 3D23 | 1F | RAR | | ; Shift "1" in B right one place |
| 3D24 | FE00 | CPI 00 | | ; Is B zero? If yes last |
| 3D26 | CA373D | JZ Done | | ; approximation has been made |
| 3D29 | 47 | MOV B,A | | |
| 3D2A | C3333D | JMP New C | | |
| 3D2D | 79 | MOV A,C | Set C | |
| 3D2E | B0 | ORA B | | ; Set bit in C that is in same |
| 3D2F | 4F | MOV C,A | | ; position as "1" in B |
| 3D30 | C3203D | JMP Shift B | | |
| 3D33 | A9 | XRA C | New C | ; Clear bit in C that is in |
| 3D34 | C30D3D | JMP Return | | ; same position as "1" in B |
| 3D37 | 47 | MOV B,A | Done | ; then output new SAR code. |
| 3D38 | 7C | MOV A,H | | ; Open SW1, close SW2 then |
| 3D39 | EE03 | XRI 03 | | ; proceed with program. Preamp |
| 3D3B | D3E6 | OUT C | | ; is now zeroed. |
| 3D3D | | | Normal | |
| Program for processing proper data values | | | | |
| 3C3D | DBE4 | IN A | Read A/D Subroutine | ; Read A/D data |
| 3C3F | EEFF | XRI FF | | ; Invert data |
| 3C41 | 57 | MOV D,A | | |
| 3C42 | 78 | MOV A,B | | ; Is B Reg = 0? If not stay |
| 3C43 | E6FF | ANI FF | | ; in auto zero subroutine |
| 3C45 | C21A3D | JNZ Auto-Zero | | |
| 3C48 | C33D3D | JMP Normal | | |

Note: All numerical values are hexadecimal representations.

FIGURE 17. Software for Auto-Zeroed Differential A/D

5-3 Multiple A/D Converters in a Z-80 Interrupt Driven Mode (Continued)

The following notes apply:

- 1) It is assumed that the CPU automatically performs a RST 7 instruction when a valid interrupt is acknowledged (CPU is in interrupt mode 1). Hence, the subroutine starting address of X0038.
- 2) The address bus from the Z-80 and the data bus to the Z-80 are assumed to be inverted by bus drivers.
- 3) A/D data and identifying words will be stored in sequential memory locations starting at the arbitrarily chosen address X 3E00.
- 4) The stack pointer must be dimensioned in the main program as the RST 7 instruction automatically pushes the PC onto the stack and the subroutine uses an additional 6 stack addresses.

- 5) The peripherals of concern are mapped into I/O space with the following port assignments:

| HEX PORT ADDRESS | PERIPHERAL |
|------------------|--------------------------|
| 00 | MM74C374 8-bit flip-flop |
| 01 | A/D 1 |
| 02 | A/D 2 |
| 03 | A/D 3 |
| 04 | A/D 4 |
| 05 | A/D 5 |
| 06 | A/D 6 |
| 07 | A/D 7 |

This port address also serves as the A/D identifying word in the program.

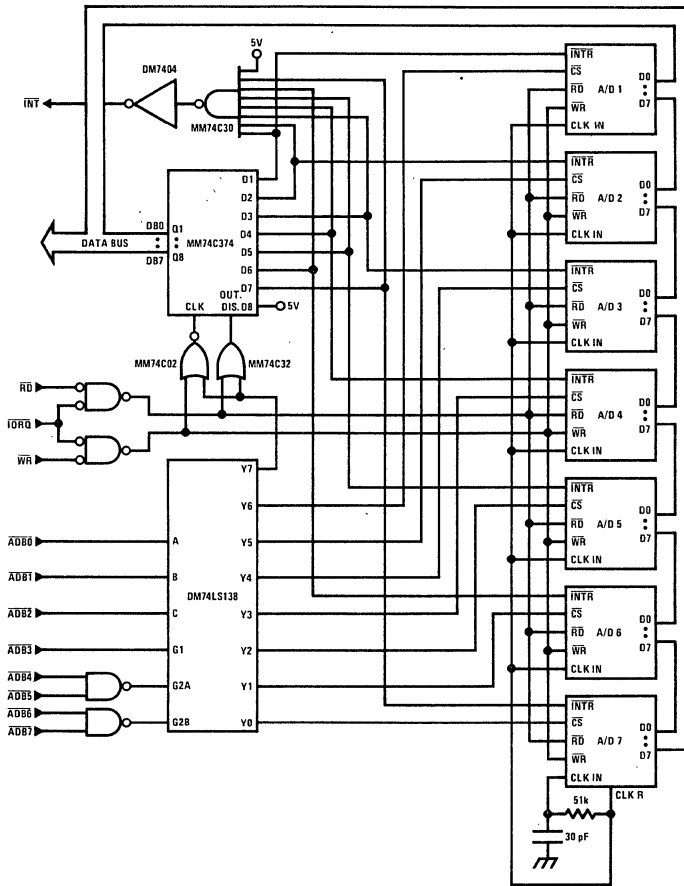


FIGURE 18. Multiple A/D's with Z-80 Type Microprocessor

INTERRUPT SERVICING SUBROUTINE

| LOC | OBJ CODE | SOURCE STATEMENT | COMMENT |
|------|----------|------------------|--|
| 0038 | E5 | PUSH HL | ; Save contents of all registers affected by |
| 0039 | C5 | PUSH BC | ; this subroutine. |
| 003A | F5 | PUSH AF | ; Assumed INT mode 1 earlier set. |
| 003B | 21 00 3E | LD (HL),X3E00 | ; Initialize memory pointer where data will be stored. |
| 003E | 0E 01 | LD C,X01 | ; C register will be port ADDR of A/D converters. |
| 0040 | D300 | OUT X00,A | ; Load peripheral status word into 8-bit latch. |
| 0042 | DB00 | IN A, X00 | ; Load status word into accumulator. |
| 0044 | 47 | LD B,A | ; Save the status word. |
| 0045 | 79 | LD A,C | ; Test to see if the status of all A/D's have |
| 0046 | FE 08 | CP, X08 | ; been checked. If so, exit subroutine. |
| 0048 | CA 60 00 | JPZ, DONE | |
| 004B | 78 | LD A,B | ; Test a single bit in status word by looking for |
| 004C | 1F | RRA | ; a "1" to be rotated into the CARRY (an INT |
| 004D | 47 | LD B,A | ; is loaded as a "1"). If CARRY is set then load |
| 004E | DA 5500 | JPC, LOAD | ; contents of A/D at port ADDR in C register. |
| 0051 | 0C | INC C | ; If CARRY is not set, increment C register to point |
| 0052 | C3 4500 | JP,TEST | ; to next A/D, then test next bit in status word. |
| 0055 | ED 78 | LOAD IN A, (C) | ; Read data from interrupting A/D and invert |
| 0057 | EE FF | XOR FF | ; the data. |
| 0059 | 77 | LD (HL),A | ; Store the data. |
| 005A | 2C | INC L | |
| 005B | 71 | LD (HL),C | ; Store A/D identifier (A/D port ADDR). |
| 005C | 2C | INC L | |
| 005D | C3 51 00 | JP,NEXT | ; Test next bit in status word. |
| 0060 | F1 | POP AF | ; Re-establish all registers as they were |
| 0061 | C1 | POP BC | ; before the interrupt. |
| 0062 | E1 | POP HL | |
| 0063 | C9 | RET | ; Return to original program. |

Typical Applications (Continued)

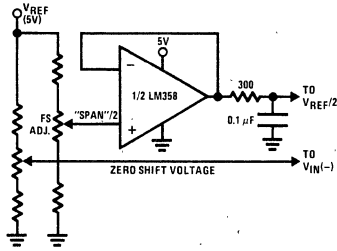


FIGURE 19. Offsetting the Zero of the ADC0801 and Performing an Input Range (Span) Adjustment

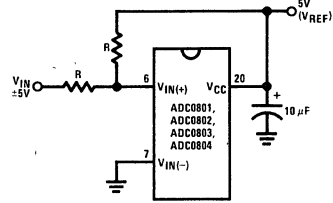


FIGURE 20. Handling ±5V Analog Input Range

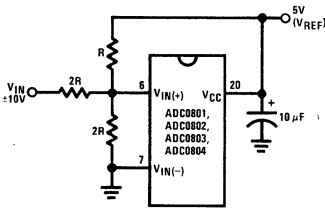


FIGURE 21. Handling ±10V Analog Input Range

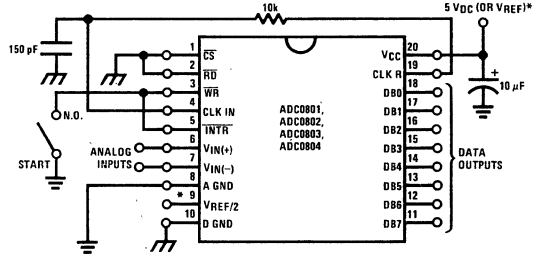


FIGURE 22. Free Running Connection

Ordering Information

| TEMPERATURE RANGE | | 0°C TO +70°C | -40°C TO +85°C | -55°C TO +125°C |
|-------------------|---------------------|-----------------|-----------------|-----------------|
| ERROR | ±1/4 Bit Adjusted | ADC0801LCN | ADC0801LCD | ADC0801LD |
| | ±1/2 Bit Unadjusted | ADC0802LCN | ADC0802LCD | ADC0802LD |
| | ±1/2 Bit Adjusted | ADC0803LCN | ADC0803LCD | ADC0803LD |
| | ±1 Bit Unadjusted | ADC0804LCN | ADC0804LCD | |
| PACKAGE OUTLINE | | N20A—MOLDED DIP | D20A—CAVITY DIP | D20A—CAVITY DIP |

ADC0808, ADC0809 8-Bit μ P Compatible A/D Converters With 8-Channel Multiplexer

General Description

The ADC0808, ADC0809 data acquisition component is a monolithic CMOS device with an 8-bit analog-to-digital converter, 8-channel multiplexer and microprocessor compatible control logic. The 8-bit A/D converter uses successive approximation as the conversion technique. The converter features a high impedance chopper stabilized comparator, a 256R voltage divider with analog switch tree and a successive approximation register. The 8-channel multiplexer can directly access any of 8 single-ended analog signals.

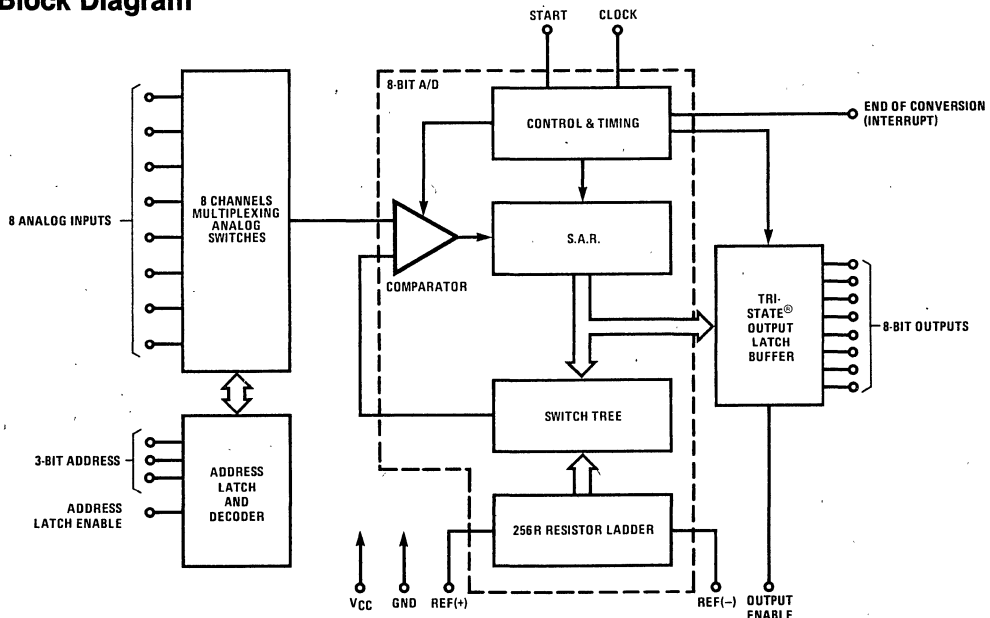
The device eliminates the need for external zero and full-scale adjustments. Easy interfacing to microprocessors is provided by the latched and decoded multiplexer address inputs and latched TTL TRI-STATE[®] outputs.

The design of the ADC0808, ADC0809 has been optimized by incorporating the most desirable aspects of several A/D conversion techniques. The ADC0808, ADC0809 offers high speed, high accuracy, minimal temperature dependence, excellent long-term accuracy and repeatability, and consumes minimal power. These features make this device ideally suited to applications from process and machine control to consumer and automotive applications. For 16-channel multiplexer with common output (sample/hold port) see ADC0816 data sheet.

Features

- Resolution — 8-bits
- Total unadjusted error — $\pm 1/2$ LSB and ± 1 LSB
- No missing codes
- Conversion time — 100 μ s
- Single supply — 5 V_{DC}
- Operates ratiometrically or with 5 V_{DC} or analog span adjusted voltage reference
- 8-channel multiplexer with latched control logic
- Easy interface to all microprocessors, or operates "stand alone"
- Outputs meet T²L voltage level specifications
- 0V to 5V analog input voltage range with single 5V supply
- No zero or full-scale adjust required
- Standard hermetic or molded 28-pin DIP package
- Temperature range -40°C to $+85^{\circ}\text{C}$ or -55°C to $+125^{\circ}\text{C}$
- Low power consumption — 15 mW
- Latched TRI-STATE[®] output

Block Diagram



Absolute Maximum Ratings (Notes 1 and 2)

| | |
|---|------------------------------|
| Supply Voltage (V_{CC}) (Note 3) | 6.5V |
| Voltage at Any Pin Except Control Inputs | -0.3V to ($V_{CC} + 0.3V$) |
| Voltage at Control Inputs (START, OE, CLOCK, ALE, ADD A, ADD B, ADD C) | -0.3V to +15V |
| Storage Temperature Range | -65°C to +150°C |
| Package Dissipation at $T_A = 25^\circ\text{C}$ | 875 mW |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Ratings (Notes 1 and 2)

| | |
|---|---|
| Temperature Range (Note 1) ADC0808CJ | $T_{MIN} \leq T_A \leq T_{MAX}$ -55°C $\leq T_A \leq$ +125°C |
| ADC0808CCJ, ADC0808CCN, ADC0809CCN | -40°C $\leq T_A \leq$ +85°C |
| Range of V_{CC} (Note 1) | 4.5 V_{DC} to 6.0 V_{DC} |

Electrical Characteristics

Converter Specifications: $V_{CC} = 5 V_{DC} = V_{REF(+)}$, $V_{REF(-)} = \text{GND}$, $T_{MIN} \leq T_A \leq T_{MAX}$ and $f_{CLK} = 640 \text{ kHz}$ unless otherwise stated.

| Parameter | Conditions | Min | Typ | Max | Units |
|--|---------------------------------------|------------------|------------|------------------------|---------------|
| ADC0808 Total Unadjusted Error (Note 5) | 25°C T_{MIN} to T_{MAX} | | | $\pm 1/2$ $\pm 3/4$ | LSB LSB |
| ADC0809 Total Unadjusted Error (Note 5) | 0°C to 70°C T_{MIN} to T_{MAX} | | | ± 1 $\pm 1 1/4$ | LSB LSB |
| Input Resistance | From Ref(+) to Ref(-) | 1.0 | 2.5 | | k Ω |
| Analog Input Voltage Range | (Note 4) V(+) or V(-) | GND-0.10 | | $V_{CC} + 0.10$ | V_{DC} |
| $V_{REF(+)}$ Voltage, Top of Ladder | Measured at Ref(+) | | V_{CC} | $V_{CC} + 0.1$ | V |
| $\frac{V_{REF(+)} + V_{REF(-)}}{2}$ Voltage, Center of Ladder | | $V_{CC}/2 - 0.1$ | $V_{CC}/2$ | $V_{CC}/2 + 0.1$ | V |
| $V_{REF(-)}$ Voltage, Bottom of Ladder | Measured at Ref(-) | -0.1 | 0 | | V |
| Comparator Input Current | $f_c = 640 \text{ kHz}$, (Note 6) | -2 | ± 0.5 | 2 | μA |

Electrical Characteristics

Digital Levels and DC Specifications: ADC0808CJ $4.5V \leq V_{CC} \leq 5.5V$, $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ unless otherwise noted
ADC0808CCJ, ADC0808CCN, and ADC0809CCN $4.75 \leq V_{CC} \leq 5.25V$, $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ unless otherwise noted

| Parameter | Conditions | Min | Typ | Max | Units |
|--|---|--------------|----------------|------------|---------------------|
| ANALOG MULTIPLEXER | | | | | |
| $I_{OFF(+)}$ OFF Channel Leakage Current | $V_{CC} = 5V$, $V_{IN} = 5V$, $T_A = 25^\circ\text{C}$ T_{MIN} to T_{MAX} | | 10 | 200 1.0 | nA μA |
| $I_{OFF(-)}$ OFF Channel Leakage Current | $V_{CC} = 5V$, $V_{IN} = 0$, $T_A = 25^\circ\text{C}$ T_{MIN} to T_{MAX} | -200 -1.0 | -10 | | nA μA |
| CONTROL INPUTS | | | | | |
| $V_{IN(1)}$ Logical "1" Input Voltage | | | $V_{CC} - 1.5$ | | V |
| $V_{IN(0)}$ Logical "0" Input Voltage | | | | 1.5 | V |
| $I_{IN(1)}$ Logical "1" Input Current (The Control Inputs) | $V_{IN} = 15V$ | | | 1.0 | μA |
| $I_{IN(0)}$ Logical "0" Input Current (The Control Inputs) | $V_{IN} = 0$ | -1.0 | | | μA |
| I_{CC} Supply Current | $f_{CLK} = 640 \text{ kHz}$ | | 0.3 | 3.0 | mA |

Electrical Characteristics (Continued)

Digital Levels and DC Specifications: ADC0808CJ $4.5V \leq V_{CC} \leq 5.5V$, $-55^{\circ}C \leq T_A \leq +125^{\circ}C$ unless otherwise noted
 ADC0808CCJ, ADC0808CCN, and ADC0809CCN $4.75 \leq V_{CC} \leq 5.25V$, $-40^{\circ}C \leq T_A \leq +85^{\circ}C$ unless otherwise noted

| Parameter | | Conditions | Min | Typ | Max | Units |
|---|--------------------------------|-------------------------|--------------|-----|------|--------------------|
| DATA OUTPUTS AND EOC (INTERRUPT) | | | | | | |
| $V_{OUT(1)}$ | Logical "1" Output Voltage | $I_O = -360 \mu A$ | $V_{CC}-0.4$ | | | V |
| $V_{OUT(0)}$ | Logical "0" Output Voltage | $I_O = 1.6 \text{ mA}$ | | | 0.45 | V |
| $V_{OUT(0)}$ | Logical "0" Output Voltage EOC | $I_O = 1.2 \text{ mA}$ | | | 0.45 | V |
| I_{OUT} | TRI-STATE Output Current | $V_O = 5V$ $V_O = 0$ | -3 | | 3 | μA μA |

Electrical Characteristics

Timing Specifications: $V_{CC} = V_{REF(+)} = 5V$, $V_{REF(-)} = \text{GND}$, $t_r = t_f = 20 \text{ ns}$ and $T_A = 25^{\circ}C$ unless otherwise noted.

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|------------------|-----------------------------------|--|-----|-----|---------------|------------------|
| t_{WS} | Minimum Start Pulse Width | (Figure 5) | | 100 | 200 | ns |
| t_{WALE} | Minimum ALE Pulse Width | (Figure 5) | | 100 | 200 | ns |
| t_s | Minimum Address Set-Up Time | (Figure 5) | | 25 | 50 | ns |
| t_H | Minimum Address Hold Time | (Figure 5) | | 25 | 50 | ns |
| t_D | Analog MUX Delay Time From ALE | $R_S = 0\Omega$ (Figure 5) | | 1 | 2.5 | μs |
| t_{H1}, t_{H0} | OE Control to Q Logic State | $C_L = 50 \text{ pF}$, $R_L = 10k$ (Figure 8) | | 125 | 250 | ns |
| t_{1H}, t_{0H} | OE Control to Hi-Z | $C_L = 10 \text{ pF}$, $R_L = 10k$ (Figure 8) | | 125 | 250 | ns |
| t_c | Conversion Time | $f_c = 640 \text{ kHz}$, (Figure 5) (Note 7) | 90 | 100 | 116 | μs |
| f_c | Clock Frequency | | 10 | 640 | 1280 | kHz |
| t_{EOC} | EOC Delay Time | (Figure 5) | 0 | | $8 + 2 \mu s$ | Clock Periods |
| C_{IN} | Input Capacitance | At Control Inputs | | 10 | 15 | pF |
| C_{OUT} | TRI-STATE® Output Capacitance | At TRI-STATE® Outputs, (Note 12) | | 10 | 15 | pF |

Note 1: Absolute maximum ratings are those values beyond which the life of the device may be impaired.

Note 2: All voltages are measured with respect to GND, unless otherwise specified.

Note 3: A zener diode exists, internally, from V_{CC} to GND and has a typical breakdown voltage of $7 V_{DC}$.

Note 4: Two on-chip diodes are tied to each analog input which will forward conduct for analog input voltages one diode drop below ground or one diode drop greater than the V_{CC} supply. The spec allows 100 mV forward bias of either diode. This means that as long as the analog V_{IN} does not exceed the supply voltage by more than 100 mV, the output code will be correct. To achieve an absolute $0 V_{DC}$ to $5 V_{DC}$ input voltage range will therefore require a minimum supply voltage of $4.900 V_{DC}$ over temperature variations, initial tolerance and loading.

Note 5: Total unadjusted error includes offset, full-scale, linearity, and multiplexer errors. See Figure 3. None of these A/Ds requires a zero or full-scale adjust. However, if an all zero code is desired for an analog input other than $0.0V$, or if a narrow full-scale span exists (for example: $0.5V$ to $4.5V$ full-scale) the reference voltages can be adjusted to achieve this. See Figure 13.

Note 6: Comparator input current is a bias current into or out of the chopper stabilized comparator. The bias current varies directly with clock frequency and has little temperature dependence (Figure 6). See paragraph 4.0.

Note 7: The outputs of the data register are updated one clock cycle before the rising edge of EOC.

Functional Description

Multiplexer: The device contains an 8-channel single-ended analog signal multiplexer. A particular input channel is selected by using the address decoder. Table I shows the input states for the address lines to select any channel. The address is latched into the decoder on the low-to-high transition of the address latch enable signal.

TABLE I

| SELECTED ANALOG CHANNEL | ADDRESS LINE | | |
|----------------------------|--------------|---|---|
| | C | B | A |
| IN0 | L | L | L |
| IN1 | L | L | H |
| IN2 | L | H | L |
| IN3 | L | H | H |
| IN4 | H | L | L |
| IN5 | H | L | H |
| IN6 | H | H | L |
| IN7 | H | H | H |

CONVERTER CHARACTERISTICS

The Converter

The heart of this single chip data acquisition system is its 8-bit analog-to-digital converter. The converter is designed

to give fast, accurate, and repeatable conversions over a wide range of temperatures. The converter is partitioned into 3 major sections: the 256R ladder network, the successive approximation register, and the comparator. The converter's digital outputs are positive true.

The 256R ladder network approach (*Figure 1*) was chosen over the conventional R/2R ladder because of its inherent monotonicity, which guarantees no missing digital codes. Monotonicity is particularly important in closed loop feedback control systems. A non-monotonic relationship can cause oscillations that will be catastrophic for the system. Additionally, the 256R network does not cause load variations on the reference voltage.

The bottom resistor and the top resistor of the ladder network in *Figure 1* are not the same value as the remainder of the network. The difference in these resistors causes the output characteristic to be symmetrical with the zero and full-scale points of the transfer curve. The first output transition occurs when the analog signal has reached +1/2 LSB and succeeding output transitions occur every 1 LSB later up to full-scale.

The successive approximation register (SAR) performs 8 iterations to approximate the input voltage. For any SAR type converter, n-iterations are required for an n-bit converter. *Figure 2* shows a typical example of a 3-bit converter. In the ADC0808, ADC0809, the approximation technique is extended to 8 bits using the 256R network.

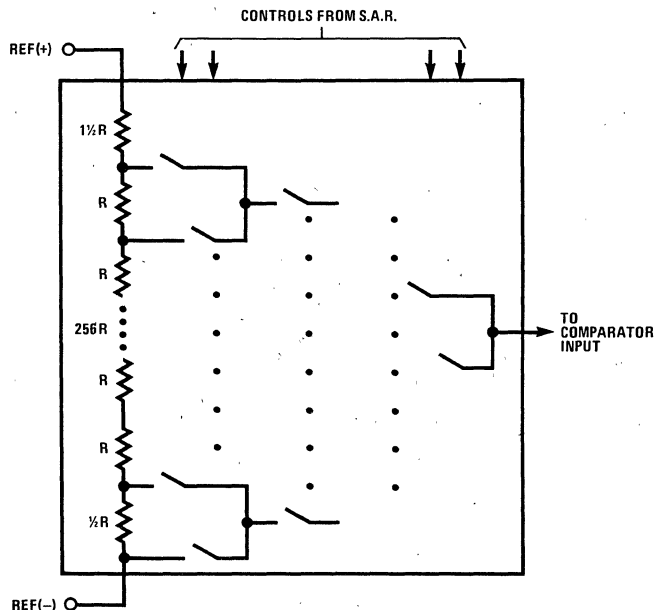


FIGURE 1. Resistor Ladder and Switch Tree

Functional Description (Continued)

The A/D converter's successive approximation register (SAR) is reset on the positive edge of the start conversion (SC) pulse. The conversion is begun on the falling edge of the start conversion pulse. A conversion in process will be interrupted by receipt of a new start conversion pulse. Continuous conversion may be accomplished by tying the end-of-conversion (EOC) output to the SC input. If used in this mode, an external start conversion pulse should be applied after power up. End-of-conversion will go low between 0 and 8 clock pulses after the rising edge of start conversion.

The most important section of the A/D converter is the comparator. It is this section which is responsible for the ultimate accuracy of the entire converter. It is also the

comparator drift which has the greatest influence on the repeatability of the device. A chopper-stabilized comparator provides the most effective method of satisfying all the converter requirements.

The chopper-stabilized comparator converts the DC input signal into an AC signal. This signal is then fed through a high gain AC amplifier and has the DC level restored. This technique limits the drift component of the amplifier since the drift is a DC component which is not passed by the AC amplifier. This makes the entire A/D converter extremely insensitive to temperature, long term drift and input offset errors.

Figure 4 shows a typical error curve for the ADC0808 as measured using the procedures outlined in AN-179.

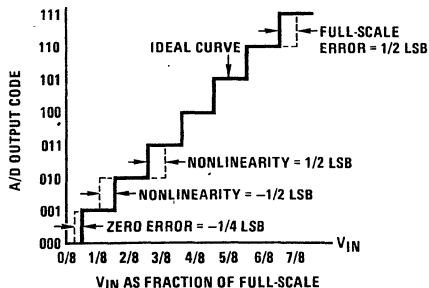


FIGURE 2. 3-Bit A/D Transfer Curve

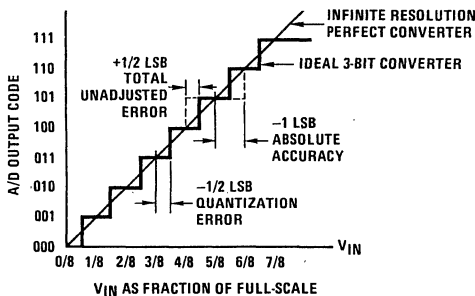


FIGURE 3. 3-Bit A/D Absolute Accuracy Curve

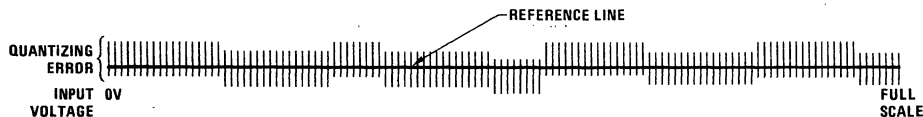
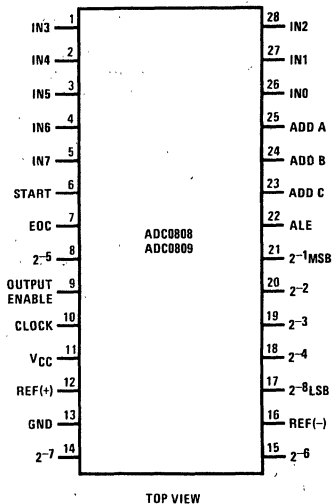


FIGURE 4. Typical Error Curve

Connection Diagram

Dual-In-Line Package



Timing Diagram

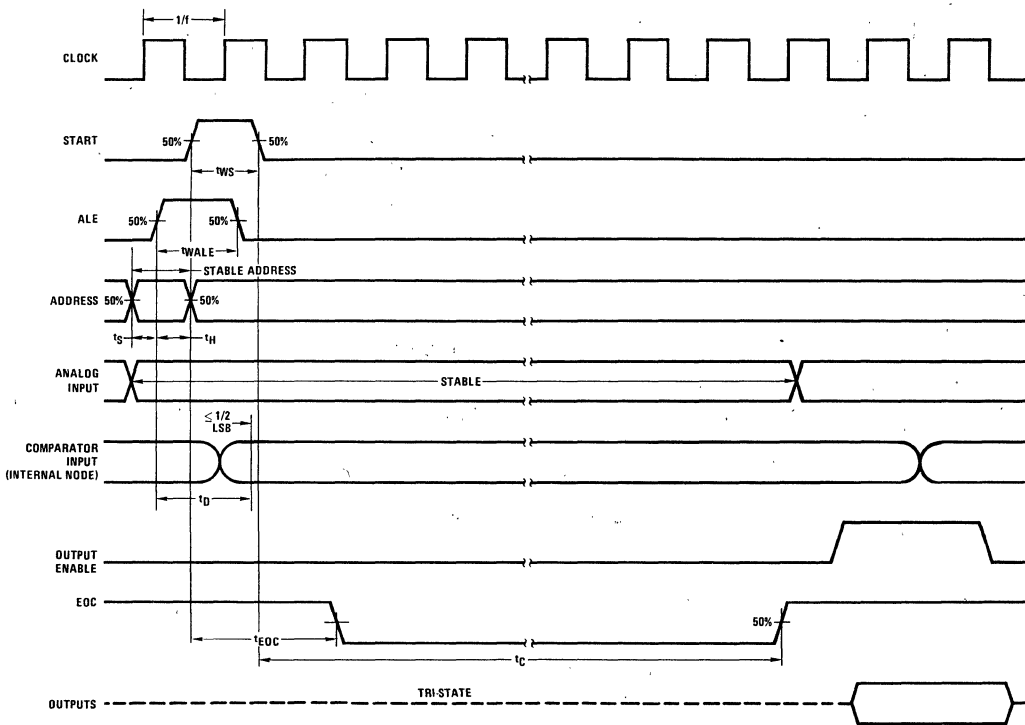


FIGURE 5

Typical Performance Characteristics

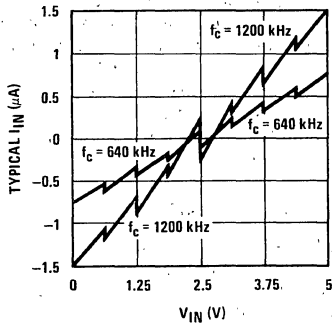


FIGURE 6. Comparator I_{IN} vs V_{IN}
($V_{CC} = V_{REF} = 5V$)

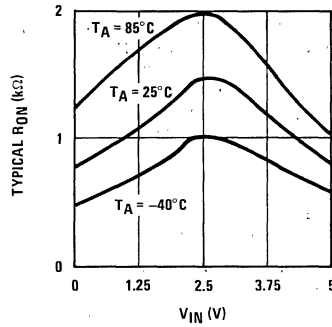


FIGURE 7. Multiplexer R_{ON} vs V_{IN}
($V_{CC} = V_{REF} = 5V$)

TRI-STATE® Test Circuits and Timing Diagrams

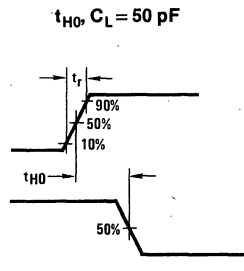
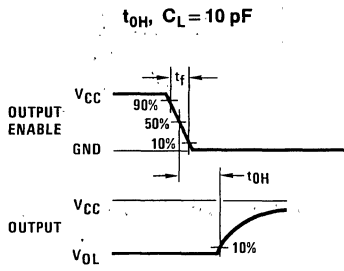
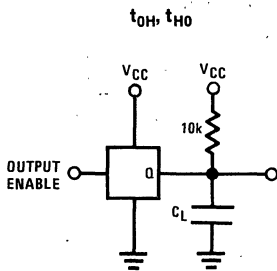
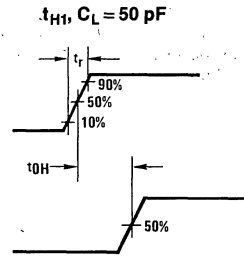
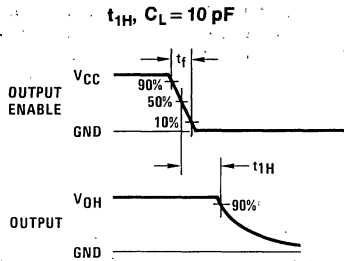
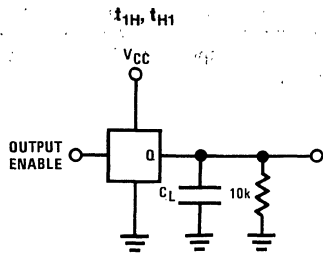


FIGURE 8

Applications Information

OPERATION

1.0 Ratiometric Conversion

The ADC0808, ADC0809 is designed as a complete Data Acquisition System (DAS) for ratiometric conversion systems. In ratiometric systems, the physical variable being measured is expressed as a percentage of full-scale which is not necessarily related to an absolute standard. The voltage input to the ADC0808 is expressed by the equation

$$\frac{V_{IN}}{V_{fs} - V_Z} = \frac{D_X}{D_{MAX} - D_{MIN}} \quad (1)$$

V_{IN} = Input voltage into the ADC0808

V_{fs} = Full-scale voltage

V_Z = Zero voltage

D_X = Data point being measured

D_{MAX} = Maximum data limit

D_{MIN} = Minimum data limit

A good example of a ratiometric transducer is a potentiometer used as a position sensor. The position of the wiper is directly proportional to the output voltage which is a ratio of the full-scale voltage across it. Since the data is represented as a proportion of full-scale, reference requirements are greatly reduced, eliminating a large source of error and cost for many applications. A major advantage of the ADC0808, ADC0809 is that the input voltage range is equal to the supply range so the transducers can be connected directly across the supply and their outputs connected directly into the multiplexer inputs, (Figure 9).

Ratiometric transducers such as potentiometers, strain gauges, thermistor bridges, pressure transducers, etc., are suitable for measuring proportional relationships; however, many types of measurements must be referred to an absolute standard such as voltage or current. This means a system reference must be used which relates the full-scale voltage to the standard volt. For example, if $V_{CC} = V_{REF} = 5.12V$, then the full-scale range is divided into 256 standard steps. The smallest standard step is 1 LSB which is then 20 mV.

2.0 Resistor Ladder Limitations

The voltages from the resistor ladder are compared to the selected Input 8 times in a conversion. These voltages are coupled to the comparator via an analog switch tree which is referenced to the supply. The voltages at the top, center and bottom of the ladder must be controlled to maintain proper operation.

The top of the ladder, Ref(+), should not be more positive than the supply, and the bottom of the ladder, Ref(-), should not be more negative than ground. The center of the ladder voltage must also be near the center of the supply because the analog switch tree changes from N-channel switches to P-channel switches. These limitations are automatically satisfied in ratiometric systems and can be easily met in ground referenced systems.

Figure 10 shows a ground referenced system with a separate supply and reference. In this system, the supply must be trimmed to match the reference voltage. For instance, if a 5.12V is used, the supply should be adjusted to the same voltage within 0.1V.

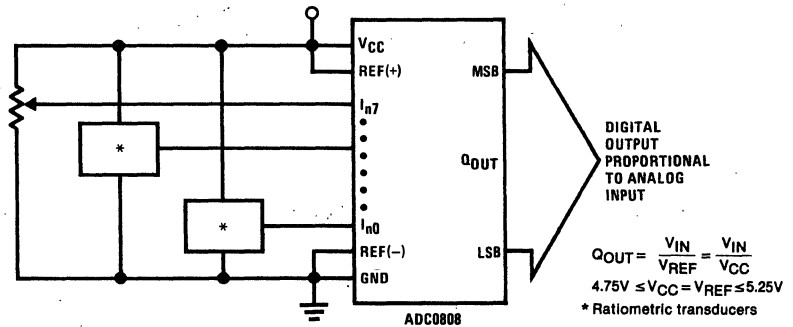


FIGURE 9. Ratiometric Conversion System

Applications Information (Continued)

The ADC0808 needs less than a milliamp of supply current so developing the supply from the reference is readily accomplished. In *Figure 11* a ground referenced system is shown which generates the supply from the reference. The buffer shown can be an op amp of sufficient drive to supply the milliamp of supply current and the desired bus drive, or if a capacitive bus is driven by the outputs a large capacitor will supply the transient supply current as seen in *Figure 12*. The LM301 is overcompensated to insure stability when loaded by the 10 μ F output capacitor.

The top and bottom ladder voltages cannot exceed V_{CC} and ground, respectively, but they can be symmetrically less than V_{CC} and greater than ground. The center of the ladder voltage should always be near the center of the supply. The sensitivity of the converter can be increased, (i.e., size of the LSB steps decreased) by using a symmetrical reference system. In *Figure 13*, a 2.5V reference is symmetrically centered about $V_{CC}/2$ since the same current flows in identical resistors. This system with a 2.5V reference allows the LSB bit to be half the size of a 5V reference system.

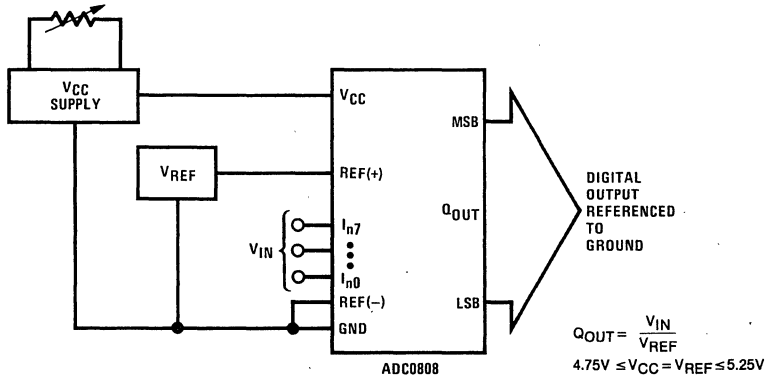


FIGURE 10. Ground Referenced Conversion System Using Trimmed Supply

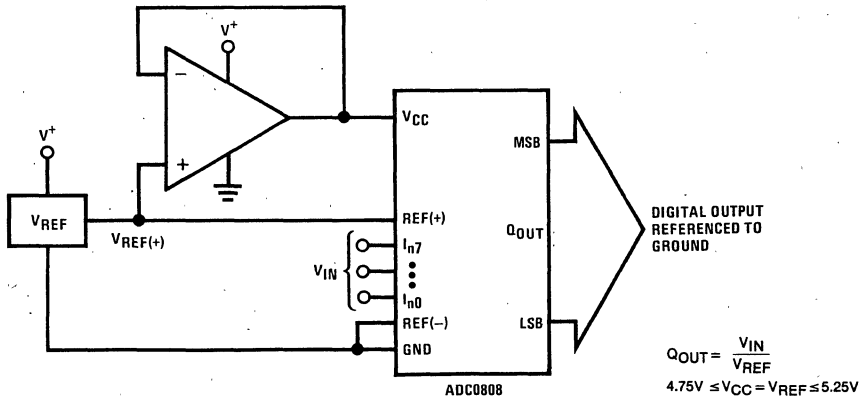


FIGURE 11. Ground Referenced Conversion System with Reference Generating V_{CC} Supply

Applications Information (Continued)

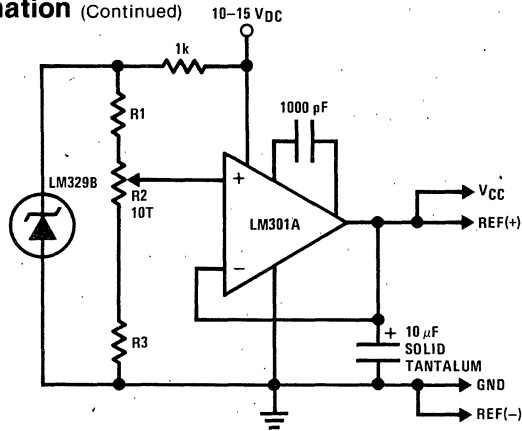


FIGURE 12. Typical Reference and Supply Circuit

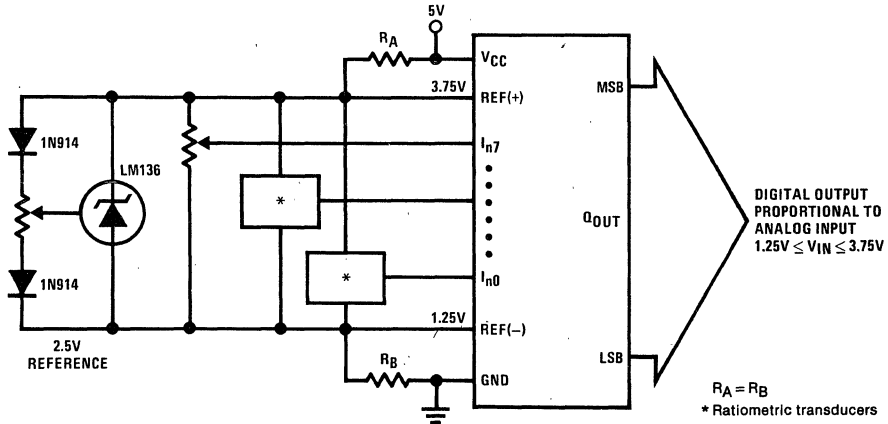


FIGURE 13. Symmetrically Centered Reference

3.0 Converter Equations

The transition between adjacent codes N and N + 1 is given by:

$$V_{IN} = \left\{ (V_{REF(+)} - V_{REF(-)}) \left[\frac{N}{256} + \frac{1}{512} \right] \pm V_{TUE} \right\} + V_{REF(-)} \quad (2)$$

The center of an output code N is given by:

$$V_{IN} = \left\{ (V_{REF(+)} - V_{REF(-)}) \left[\frac{N}{256} \right] \pm V_{TUE} \right\} + V_{REF(-)} \quad (3)$$

The output code N for an arbitrary input are the integers within the range:

$$N = \frac{V_{IN} - V_{REF(-)}}{V_{REF(+)} - V_{REF(-)}} \times 256 \pm \text{Absolute Accuracy} \quad (4)$$

- where: V_{IN} = Voltage at comparator input
- $V_{REF(+)}$ = Voltage at Ref(+)
- $V_{REF(-)}$ = Voltage at Ref(-)
- V_{TUE} = Total unadjusted error voltage (typically $V_{REF(+)} \div 512$)

4.0 Analog Comparator Inputs

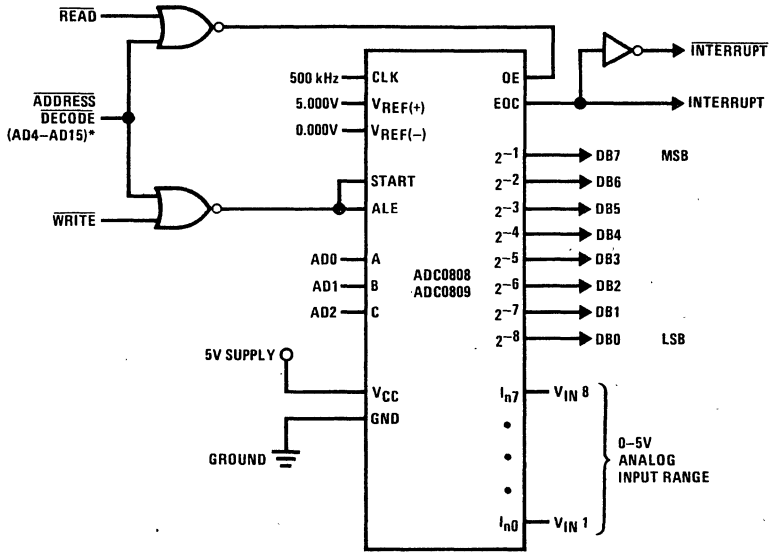
The dynamic comparator input current is caused by the periodic switching of on-chip stray capacitances. These are connected alternately to the output of the resistor ladder/switch tree network and to the comparator input as part of the operation of the chopper stabilized comparator.

The average value of the comparator input current varies directly with clock frequency and with V_{IN} as shown in Figure 6.

If no filter capacitors are used at the analog inputs and the signal source impedances are low, the comparator input current should not introduce converter errors, as the transient created by the capacitance discharge will die out before the comparator output is strobed.

If input filter capacitors are desired for noise reduction and signal conditioning they will tend to average out the dynamic comparator input current. It will then take on the characteristics of a DC bias current whose effect can be predicted conventionally.

Typical Application



* Address latches needed for 8085 and SC/MP Interfacing the ADC0808 to a microprocessor

MICROPROCESSOR INTERFACE TABLE

| PROCESSOR | READ | WRITE | INTERRUPT (COMMENT) |
|-----------|--------------------------|--------------------------|---|
| 8080 | $\overline{\text{MEMR}}$ | $\overline{\text{MEMW}}$ | INTR (Thru RST Circuit) |
| 8085 | $\overline{\text{RD}}$ | $\overline{\text{WR}}$ | INTR (Thru RST Circuit) |
| Z-80 | $\overline{\text{RD}}$ | $\overline{\text{WR}}$ | $\overline{\text{INT}}$ (Thru RST Circuit, Mode 0) |
| SC/MP | NRDS | NWDS | SA (Thru Sense A) |
| 6800 | VMA ϕ 2-R/W | VMA ϕ 2-R/W | $\overline{\text{IRQA}}$ or $\overline{\text{IRQB}}$ (Thru PIA) |

Ordering Information

| TEMPERATURE RANGE | | -40°C to +85°C | | -55°C to +125°C |
|-------------------|--------------------------|-----------------|-------------------|-------------------|
| Error | $\pm 1/2$ Bit Unadjusted | ADC0808CCN | ADC0808CCJ | ADC0808CJ |
| | ± 1 Bit Unadjusted | ADC0809CCN | | |
| Package Outline | | N28A Molded DIP | J28A Hermetic DIP | J28A Hermetic DIP |

ADC0816, ADC0817 8-Bit μ P Compatible A/D Converters with 16-Channel Multiplexer

General Description

The ADC0816, ADC0817 data acquisition component is a monolithic CMOS device with an 8-bit analog-to-digital converter, 16-channel multiplexer and microprocessor compatible control logic. The 8-bit A/D converter uses successive approximation as the conversion technique. The converter features a high impedance chopper stabilized comparator, a 256R voltage divider with analog switch tree and a successive approximation register. The 16-channel multiplexer can directly access any one of 16 single-ended analog signals, and provides the logic for additional channel expansion. Signal conditioning of any analog input signal is eased by direct access to the multiplexer output, and to the input of the 8-bit A/D converter.

The device eliminates the need for external zero and full-scale adjustments. Easy interfacing to microprocessors is provided by the latched and decoded multiplexer address inputs and latched TTL TRI-STATE[®] outputs.

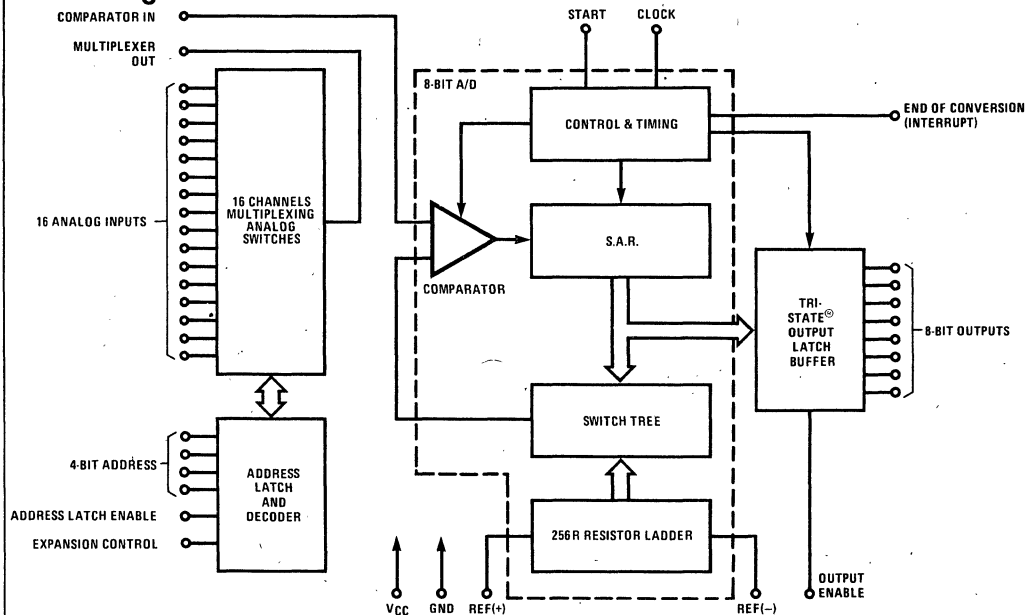
The design of the ADC0816, ADC0817 has been optimized by incorporating the most desirable aspects of several A/D conversion techniques. The ADC0816, ADC0817 offers high speed, high accuracy, minimal temperature dependence, excellent long-term accuracy and repeatability, and consumes minimal power. These features make this device ideally suited to applications from process and machine control to consumer and automotive applications. For similar performance in an 8-channel, 28-pin,

8-bit A/D converter, see the ADC0808, ADC0809 data sheet.

Features

- Resolution — 8-bits
- Total unadjusted error — $\pm 1/2$ LSB and ± 1 LSB
- No missing codes
- Conversion time — 100 μ s
- Single supply — $5 V_{DC}$
- Operates ratiometrically or with $5 V_{DC}$ or analog span adjusted voltage reference
- 16-channel multiplexer with latched control logic
- Easy interface to all microprocessors, or operates "stand alone"
- Outputs meet T²L voltage level specifications
- 0V to 5V analog input voltage range with single 5V supply
- No zero or full-scale adjust required
- Standard hermetic or molded 40-pin DIP package
- Temperature range -40°C to $+85^{\circ}\text{C}$ or -55°C to $+125^{\circ}\text{C}$
- Low power consumption — 15 mW
- Latched TRI-STATE[®] output
- Direct access to "comparator in" and "multiplexer out" for signal conditioning

Block Diagram



Absolute Maximum Ratings (Notes 1 and 2)

| | |
|--|------------------------------|
| Supply Voltage (V_{CC}) (Note 3) | 6.5V |
| Voltage at Any Pin Except Control Inputs | -0.3V to ($V_{CC} + 0.3V$) |
| Voltage at Control Inputs (START, OE, CLOCK, ALE, EXPANSION CONTROL, ADD A, ADD B, ADD C, ADD D) | -0.3V to 15V |
| Storage Temperature Range | -65°C to +150°C |
| Package Dissipation at $T_A = 25^\circ\text{C}$ | 875 mW |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Ratings (Notes 1 and 2)

| | |
|--|--|
| Temperature Range (Note 1) | $T_{MIN} \leq T_A \leq T_{MAX}$ -55°C $\leq T_A \leq$ +125°C -40°C $\leq T_A \leq$ +85°C |
| ADC0816CJ ADC0816CCJ, ADC0816CCN, ADC0817CCN | |
| Range of V_{CC} (Note 1) | 4.5 V_{DC} to 6.0 V_{DC} |
| Voltage at Any Pin Except Control Inputs | 0V to V_{CC} |
| Voltage at Control Inputs (START, OE, CLOCK, ALE, EXPANSION CONTROL, ADD A, ADD B, ADD C, ADD D) | 0V to 15V |

Electrical Characteristics

Converter Specifications: $V_{CC} = 5 V_{DC} = V_{REF(+)}$, $V_{REF(-)} = \text{GND}$, $V_{IN} = V_{\text{COMPARATOR IN}}$; $T_{MIN} \leq T_A \leq T_{MAX}$ and $f_{CLK} = 640 \text{ kHz}$ unless otherwise stated.

| Parameter | Conditions | Min | Typ | Max | Units |
|---|---------------------------------------|------------------|-------------|------------------------|---------------|
| ADC0816 Total Unadjusted Error (Note 5) | 25°C T_{MIN} to T_{MAX} | | | $\pm 1/2$ $\pm 3/4$ | LSB LSB |
| ADC0817 Total Unadjusted Error (Note 5) | 0°C to 70°C T_{MIN} to T_{MAX} | | | ± 1 $\pm 1 1/4$ | LSB LSB |
| Input Resistance | From Ref(+) to Ref(-) | 1.0 | 4.5 | | k Ω |
| Analog Input Voltage Range | (Note 4) $V(+)$ or $V(-)$ | GND-0.10 | | $V_{CC} + 0.10$ | V_{DC} |
| $V_{REF(+)}$ Voltage, Top of Ladder | Measured at Ref(+) | | V_{CC} | $V_{CC} + 0.1$ | V |
| $\frac{V_{REF(+)} + V_{REF(-)}}{2}$ Voltage, Center of Ladder | | $V_{CC}/2 - 0.1$ | $V_{CC}/2'$ | $V_{CC}/2 + 0.1$ | V |
| $V_{REF(-)}$ Voltage, Bottom of Ladder | Measured at Ref(-) | -0.1 | 0 | | V |
| Comparator Input Current | $f_c = 640 \text{ kHz}$, (Note 6) | -2 | ± 0.5 | 2 | μA |

Electrical Characteristics

Digital Levels and DC Specifications: ADC0816CJ 4.5V $\leq V_{CC} \leq$ 5.5V, -55°C $\leq T_A \leq$ +125°C unless otherwise noted.
ADC0816CCJ, ADC0816CCN, ADC0817CCN 4.75V $\leq V_{CC} \leq$ 5.25V, -40°C $\leq T_A \leq$ +85°C unless otherwise noted.

| Parameter | Conditions | Min | Typ | Max | Units |
|---------------------------|---|--|----------------|--------------------|--|
| ANALOG MULTIPLEXER | | | | | |
| R_{ON} | Analog Multiplexer ON Resistance | (Any Selected Channel) $T_A = 25^\circ\text{C}$, $R_L = 10\text{k}$ $T_A = 85^\circ\text{C}$ $T_A = 125^\circ\text{C}$ | | 1.5 3 6 9 | k Ω k Ω k Ω |
| ΔR_{ON} | Δ ON Resistance Between Any 2 Channels | (Any Selected Channel) $R_L = 10\text{k}$ | | 75 | Ω |
| $I_{OFF(+)}$ | OFF Channel Leakage Current | $V_{CC} = 5V$, $V_{IN} = 5V$, $T_A = 25^\circ\text{C}$ T_{MIN} to T_{MAX} | | 10 200 | nA μA |
| $I_{OFF(-)}$ | OFF Channel Leakage Current | $V_{CC} = 5V$, $V_{IN} = 0$, $T_A = 25^\circ\text{C}$ T_{MIN} to T_{MAX} | | -200 -1.0 | nA μA |
| CONTROL INPUTS | | | | | |
| $V_{IN(1)}$ | Logical "1" Input Voltage | | $V_{CC} - 1.5$ | | .V |
| $V_{IN(0)}$ | Logical "0" Input Voltage | | | 1.5 | V |
| $I_{IN(1)}$ | Logical "1" Input Current (The Control Inputs) | $V_{IN} = 15V$ | | 1.0 | μA |
| $I_{IN(0)}$ | Logical "0" Input Current (The Control Inputs) | $V_{IN} = 0$ | | -1.0 | μA |
| I_{CC} | Supply Current | $f_{CLK} = 640 \text{ kHz}$ | | 0.3 3.0 | mA |

Electrical Characteristics (Continued)

Digital Levels and DC Specifications: ADC0816CJ $4.5V \leq V_{CC} \leq 5.5V$, $-55^{\circ}C \leq T_A \leq +125^{\circ}C$ unless otherwise noted.
 ADC0816CCJ, ADC0816CCN, ADC0817CCN $4.75V \leq V_{CC} \leq 5.25V$, $-40^{\circ}C \leq T_A \leq +85^{\circ}C$ unless otherwise noted.

| Parameter | Conditions | Min | Typ | Max | Units |
|---|--------------------------------|-----------------------------|--------------|------|--------------------|
| DATA OUTPUTS AND EOC (INTERRUPT) | | | | | |
| $V_{OUT(1)}$ | Logical "1" Output Voltage | $I_O = -360 \mu A$ | $V_{CC}-0.4$ | | V |
| $V_{OUT(0)}$ | Logical "0" Output Voltage | $I_O = 1.6 \text{ mA}$ | | 0.45 | V |
| $V_{OUT(0)}$ | Logical "0" Output Voltage EOC | $I_O = 1.2 \text{ mA}$ | | 0.45 | V |
| I_{OUT} | TRI-STATE Output Current | $V_O = V_{CC}$ $V_O = 0$ | -3 | 3 | μA μA |

Electrical Characteristics

Timing Specifications: $V_{CC} = V_{REF(+)} = 5V$, $V_{REF(-)} = GND$, $t_r = t_f = 20 \text{ ns}$ and $T_A = 25^{\circ}C$ unless otherwise noted.

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|------------------|-----------------------------------|--|-----|-----|---------------|------------------|
| t_{WS} | Minimum Start Pulse Width | (Figure 5) | | 100 | 200 | ns |
| t_{WALE} | Minimum ALE Pulse Width | (Figure 5) | | 100 | 200 | ns |
| t_s | Minimum Address Set-Up Time | (Figure 5) | | 25 | 50 | ns |
| t_H | Minimum Address Hold Time | (Figure 5) | | 25 | 50 | ns |
| t_D | Analog MUX Delay Time From ALE | $R_S = 0\Omega$ (Figure 5) | | 1 | 2.5 | μs |
| t_{H1}, t_{H0} | OE Control to Q Logic State | $C_L = 50 \text{ pF}$, $R_L = 10k$ (Figure 8) | | 125 | 250 | ns |
| t_{1H}, t_{0H} | OE Control to Hi-Z | $C_L = 10 \text{ pF}$, $R_L = 10k$ (Figure 8) | | 125 | 250 | ns |
| t_c | Conversion Time | $f_c = 640 \text{ kHz}$, (Figure 5) (Note 7) | 90 | 100 | 116 | μs |
| f_c | Clock Frequency | | 10 | 640 | 1280 | kHz |
| t_{EOC} | EOC Delay Time | (Figure 5) | 0 | | $8 + 2 \mu s$ | Clock Periods |
| C_{IN} | Input Capacitance | At Control Inputs | | 10 | 15 | pF |
| C_{OUT} | TRI-STATE Output Capacitance | At TRI-STATE Outputs, (Note 7) | | 10 | 15 | pF |

Note 1: Absolute maximum ratings are those values beyond which the life of the device may be impaired.

Note 2: All voltages are measured with respect to GND, unless otherwise specified.

Note 3: A zener diode exists, internally, from V_{CC} to GND and has a typical breakdown voltage of $7 V_{DC}$.

Note 4: Two on-chip diodes are tied to each analog input which will forward conduct for analog input voltages one diode drop below ground or one diode drop greater than the V_{CC} supply. The spec allows 100 mV forward bias of either diode. This means that as long as the analog V_{IN} does not exceed the supply voltage by more than 100 mV, the output code will be correct. To achieve an absolute $0 V_{DC}$ to $5 V_{DC}$ input voltage range will therefore require a minimum supply voltage of $4.900 V_{DC}$ over temperature variations, initial tolerance and loading.

Note 5: Total unadjusted error includes offset, full-scale, and linearity errors. See Figure 3. None of these A/Ds requires a zero or full-scale adjust. However, if an all zero code is desired for an analog input other than 0.0V, or if a narrow full-scale span exists (for example: 0.5V to 4.5V full-scale) the reference voltages can be adjusted to achieve this. See Figure 13.

Note 6: Comparator input current is a bias current into or out of the chopper stabilized comparator. The bias current varies directly with clock frequency and has little temperature dependence (Figure 6). See paragraph 4.0.

Note 7: The outputs of the data register are updated one clock cycle before the rising edge of EOC.

Functional Description

Multiplexer: The device contains a 16-channel single-ended analog signal multiplexer. A particular input channel is selected by using the address decoder. Table 1 shows the input states for the address line and the expansion control line to select any channel. The address is latched into the decoder on the low-to-high transition of the address latch enable signal.

TABLE 1

| SELECTED ANALOG CHANNEL | ADDRESS LINE | | | | EXPANSION CONTROL |
|-------------------------|--------------|---|---|---|-------------------|
| | D | C | B | A | |
| IN0 | L | L | L | L | H |
| IN1 | L | L | L | H | H |
| IN2 | L | L | H | L | H |
| IN3 | L | L | H | H | H |
| IN4 | L | H | L | L | H |
| IN5 | L | H | L | H | H |
| IN6 | L | H | H | L | H |
| IN7 | L | H | H | H | H |
| IN8 | H | L | L | L | H |
| IN9 | H | L | L | H | H |
| IN10 | H | L | H | L | H |
| IN11 | H | L | H | H | H |
| IN12 | H | H | L | L | H |
| IN13 | H | H | L | H | H |
| IN14 | H | H | H | L | H |
| IN15 | H | H | H | H | H |
| All Channels OFF | X | X | X | X | L |

X = don't care

Additional single-ended analog signals can be multiplexed to the A/D converter by disabling all the multiplexer inputs using the expansion control. The additional external signals are connected to the comparator input and the device ground. Additional signal conditioning (i.e., prescaling, sample and hold, instrumentation amplification, etc.) may also be added between the analog input signal and the comparator input.

CONVERTER CHARACTERISTICS

The Converter

The heart of this single chip data acquisition system is its 8-bit analog-to-digital converter. The converter is designed to give fast, accurate, and repeatable conversions over a wide range of temperatures. The converter is partitioned into 3 major sections: the 256R ladder network, the successive approximation register, and the comparator. The converter's digital outputs are positive true.

The 256R ladder network approach (*Figure 1*) was chosen over the conventional R/2R ladder because of its inherent monotonicity, which guarantees no missing digital codes. Monotonicity is particularly important in closed loop feedback control systems. A non-monotonic relationship can cause oscillations that will be catastrophic for the system. Additionally, the 256R network does not cause load variations on the reference voltage.

The bottom resistor and the top resistor of the ladder network in *Figure 1* are not the same value as the remainder of the network. The difference in these resistors causes the output characteristic to be symmetrical with the zero and full-scale points of the transfer curve. The first output transition occurs when the analog signal has reached +1/2 LSB and succeeding output transitions occur every 1 LSB later up to full-scale.

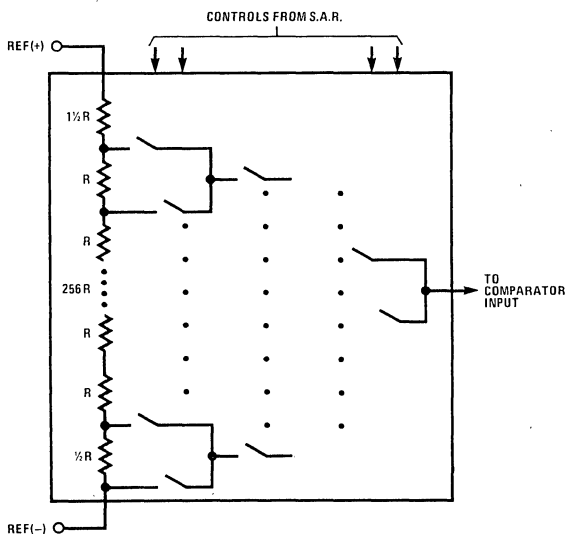


FIGURE 1. Resistor Ladder and Switch Tree

Functional Description (Continued)

The successive approximation register (SAR) performs 8 iterations to approximate the input voltage. For any SAR type converter, n-iterations are required for an n-bit converter. Figure 2 shows a typical example of a 3-bit converter. In the ADC0816, ADC0817, the approximation technique is extended to 8 bits using the 256R network.

The A/D converter's successive approximation register (SAR) is reset on the positive edge of the start conversion (SC) pulse. The conversion is begun on the falling edge of the start conversion pulse. A conversion in process will be interrupted by receipt of a new start conversion pulse. Continuous conversion may be accomplished by tying the end-of-conversion (EOC) output to the SC input. If used in this mode, an external start conversion pulse should be applied after power up. End-of-conversion will go low between 0 and 8 clock pulses after the rising edge of start conversion.

The most important section of the A/D converter is the comparator. It is this section which is responsible for the ultimate accuracy of the entire converter. It is also the comparator drift which has the greatest influence on the repeatability of the device. A chopper-stabilized comparator provides the most effective method of satisfying all the converter requirements.

The chopper-stabilized comparator converts the DC input signal into an AC signal. This signal is then fed through a high gain AC amplifier and has the DC level restored. This technique limits the drift component of the amplifier since the drift is a DC component which is not passed by the AC amplifier. This makes the entire A/D converter extremely insensitive to temperature, long term drift and input offset errors.

Figure 4 shows a typical error curve for the ADC0816 as measured using the procedures outlined in AN-179.

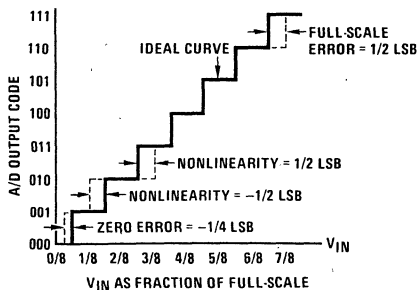


FIGURE 2. 3-bit A/D Transfer Curve

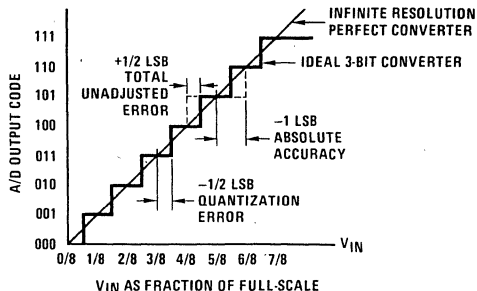


FIGURE 3. 3-bit A/D Absolute Accuracy Curve

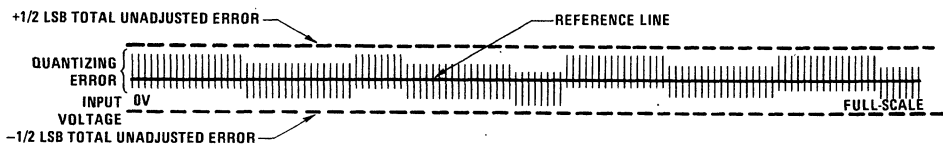
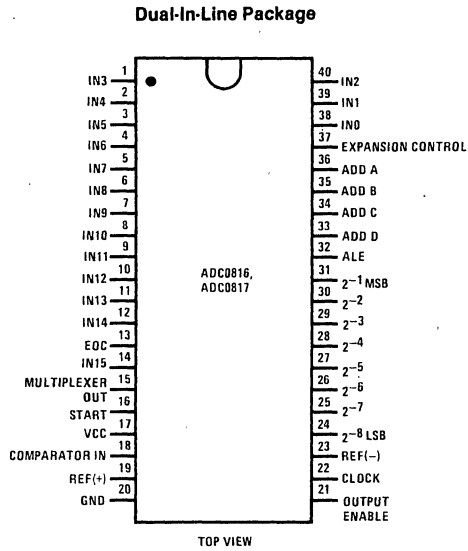


FIGURE 4. Typical Error Curve

Connection Diagram

ADC0816, ADC0817



Timing Diagram

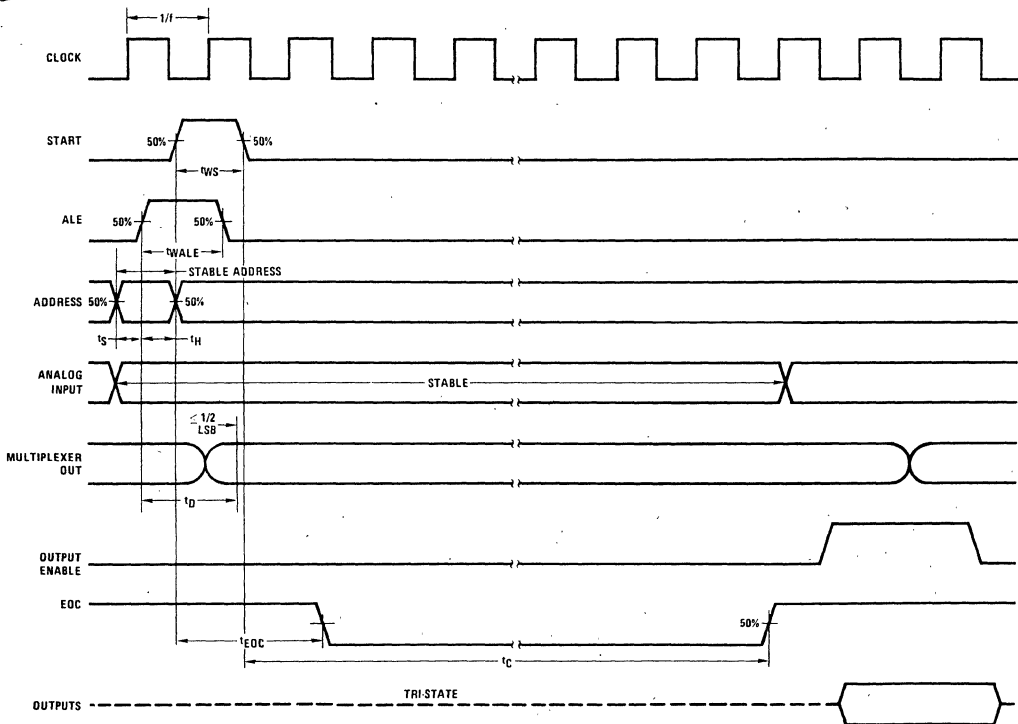


FIGURE 5

Typical Performance Characteristics

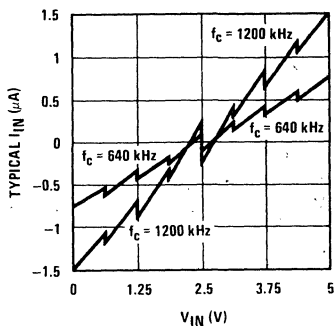


FIGURE 6. Comparator I_{IN} vs V_{IN}
($V_{CC} = V_{REF} = 5V$)

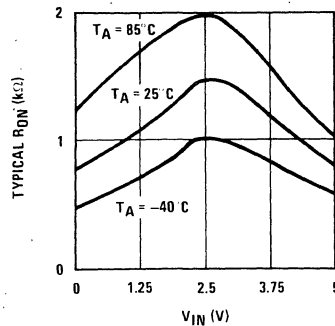


FIGURE 7. Multiplexer R_{ON} vs V_{IN}
($V_{CC} = V_{REF} = 5V$)

TRI-STATE® Test Circuits and Timing Diagrams

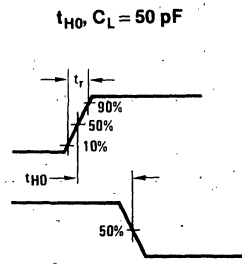
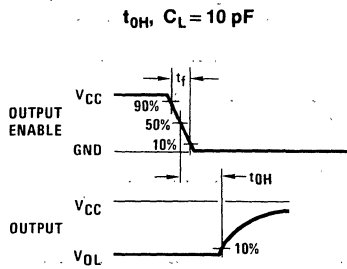
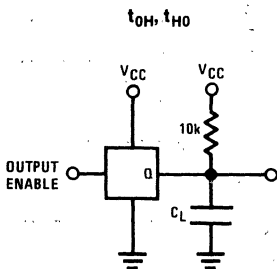
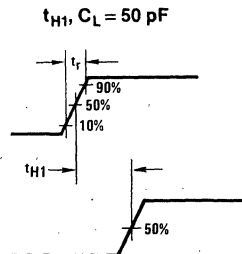
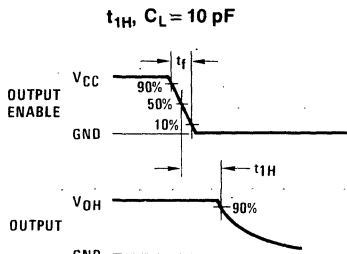
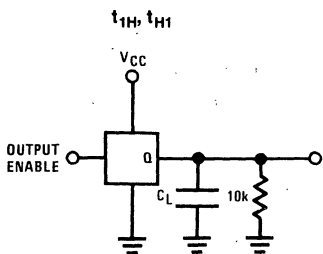


FIGURE 8

Applications Information

OPERATION

1.0 Ratiometric Conversion

The ADC0816, ADC0817 is designed as a complete Data Acquisition System (DAS) for ratiometric conversion systems. In ratiometric systems, the physical variable being measured is expressed as a percentage of full-scale which is not necessarily related to an absolute standard. The voltage input to the ADC0816 is expressed by the equation

$$\frac{V_{IN}}{V_{fs} - V_Z} = \frac{D_X}{D_{MAX} - D_{MIN}} \quad (1)$$

V_{IN} = Input voltage into the ADC0816

V_{fs} = Full-scale voltage

V_Z = Zero voltage

D_X = Data point being measured

D_{MAX} = Maximum data limit

D_{MIN} = Minimum data limit

A good example of a ratiometric transducer is a potentiometer used as a position sensor. The position of the wiper is directly proportional to the output voltage which is a ratio of the full-scale voltage across it. Since the data is represented as a proportion of full-scale, reference requirements are greatly reduced, eliminating a large source of error and cost for many applications. A major advantage of the ADC0816, ADC0817 is that the input voltage range is equal to the supply range so the transducers can be connected directly across the supply and their outputs connected directly into the multiplexer inputs, (Figure 9).

Ratiometric transducers such as potentiometers, strain gauges, thermistor bridges, pressure transducers, etc., are suitable for measuring proportional relationships; however, many types of measurements must be referred to an absolute standard such as voltage or current. This means a system reference must be used which relates the full-scale voltage to the standard volt. For example, if $V_{CC} = V_{REF} = 5.12V$, then the full-scale range is divided into 256 standard steps. The smallest standard step is 1 LSB which is then 20 mV.

2.0 Resistor Ladder Limitations

The voltages from the resistor ladder are compared to the selected input 8 times in a conversion. These voltages are coupled to the comparator via an analog switch tree which is referenced to the supply. The voltages at the top, center and bottom of the ladder must be controlled to maintain proper operation.

The top of the ladder, Ref(+), should not be more positive than the supply, and the bottom of the ladder, Ref(-), should not be more negative than ground. The center of the ladder voltage must also be near the center of the supply because the analog switch tree changes from N-channel switches to P-channel switches. These limitations are automatically satisfied in ratiometric systems and can be easily met in ground referenced systems.

Figure 10 shows a ground referenced system with a separate supply and reference. In this system, the supply must be trimmed to match the reference voltage. For instance, if a 5.12V reference is used, the supply should be adjusted to the same voltage within 0.1V.

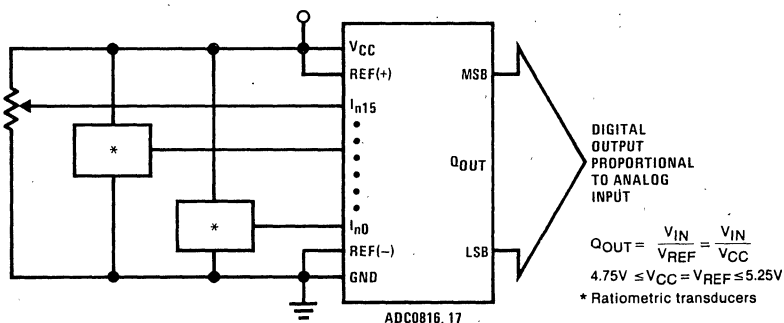


FIGURE 9. Ratiometric Conversion System

Applications Information (Continued)

The ADC0816 needs less than a milliamp of supply current so developing the supply from the reference is readily accomplished. In Figure 11 a ground referenced system is shown which generates the supply from the reference. The buffer shown can be an op amp of sufficient drive to supply the milliamp of supply current and the desired bus drive, or if a capacitive bus is driven by the outputs a large capacitor will supply the transient supply current as seen in Figure 12. The LM301 is overcompensated to insure stability when loaded by the 10 μ F output capacitor.

The top and bottom ladder voltages cannot exceed V_{CC} and ground, respectively, but they can be symmetrically less than V_{CC} and greater than ground. The center of the ladder voltage should always be near the center of the supply. The sensitivity of the converter can be increased, (i.e., size of the LSB steps decreased) by using a symmetrical reference system. In Figure 13, a 2.5V reference is symmetrically centered about $V_{CC}/2$ since the same current flows in identical resistors. This system with a 2.5V reference allows the LSB to be half the size of the LSB in a 5V reference system.

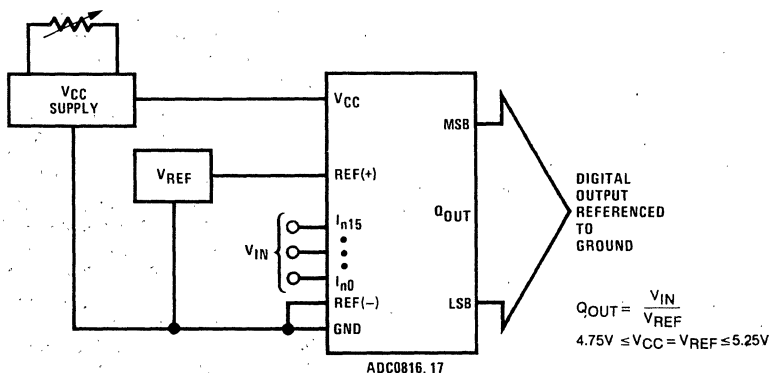


FIGURE 10. Ground Referenced Conversion System Using Trimmed Supply

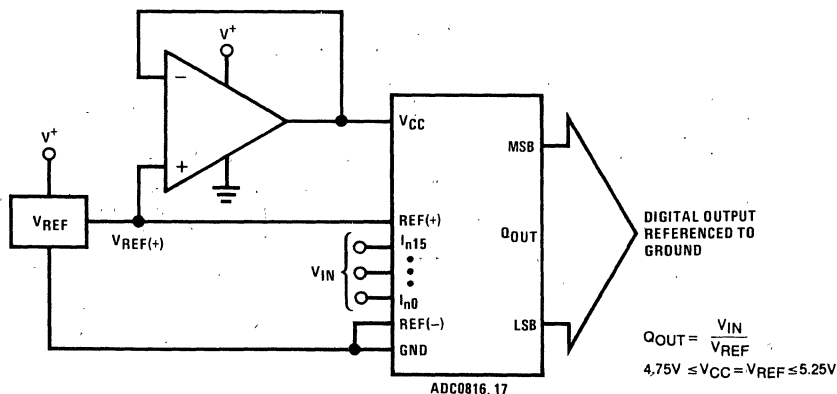


FIGURE 11. Ground Referenced Conversion System with Reference Generating V_{CC} Supply

Applications Information (Continued)

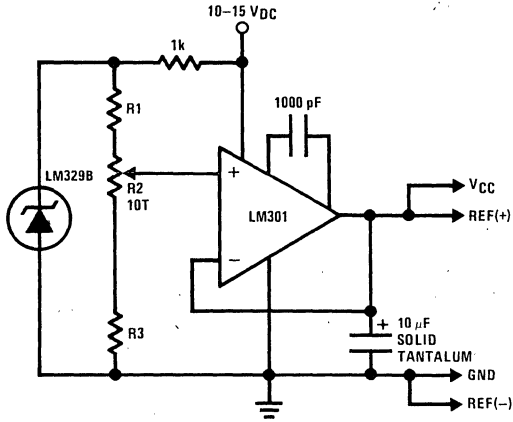


FIGURE 12. Typical Reference and Supply Circuit

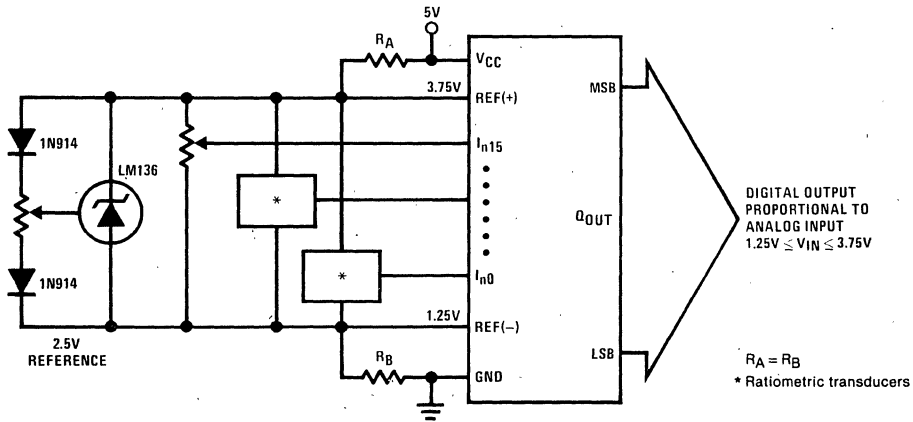


FIGURE 13. Symmetrically Centered Reference

3.0 Converter Equations

The transition between adjacent codes N and N + 1 is given by:

$$V_{IN} = \left\{ (V_{REF(+)} - V_{REF(-)}) \left[\frac{N}{256} + \frac{1}{512} \right] \pm V_{TUE} \right\} + V_{REF(-)} \quad (2)$$

The center of an output code N is given by:

$$V_{IN} = \left\{ (V_{REF(+)} - V_{REF(-)}) \left[\frac{N}{256} \right] \pm V_{TUE} \right\} + V_{REF(-)} \quad (3)$$

The output code N for an arbitrary input are the integers within the range:

$$N = \frac{V_{IN} - V_{REF(-)}}{V_{REF(+)} - V_{REF(-)}} \times 256 \pm \text{Absolute Accuracy} \quad (4)$$

where: V_{IN} = Voltage at comparator input

$V_{REF(+)}$ = Voltage at Ref (+)

$V_{REF(-)}$ = Voltage at Ref (-)

V_{TUE} = Total unadjusted error voltage (typically $V_{REF(+)} \div 512$)

Applications Information (Continued)

4.0 Analog Comparator Inputs

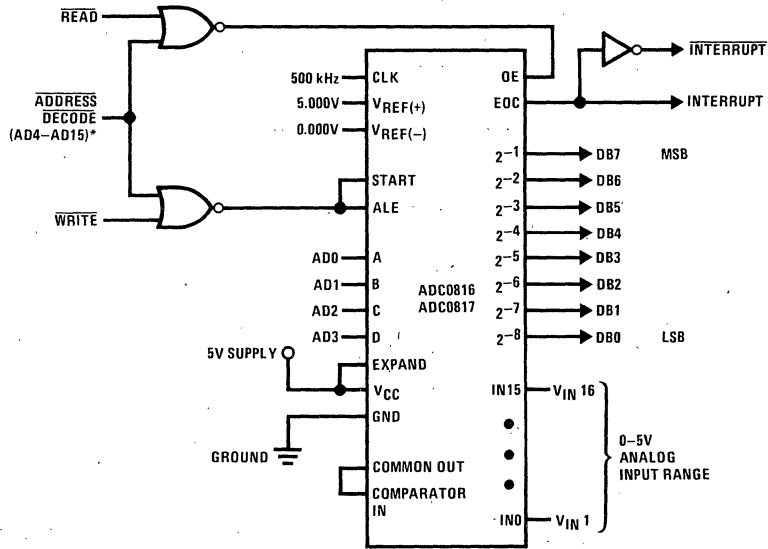
The dynamic comparator input current is caused by the periodic switching of on-chip stray capacitances. These are connected alternately to the output of the resistor ladder/switch tree network and to the comparator input as part of the operation of the chopper stabilized comparator.

The average value of the comparator input current varies directly with clock frequency and with V_{IN} as shown in Figure 6.

If no filter capacitors are used at the analog or comparator inputs and the signal source impedances are low, the comparator input current should not introduce converter errors, as the transient created by the capacitance discharge will die out before the comparator output is strobed.

If input filter capacitors are desired for noise reduction and signal conditioning they will tend to average out the dynamic comparator input current. It will then take on the characteristics of a DC bias current whose effect can be predicted conventionally.

Typical Application



* Address latches needed for 8085 and SC/MP interfacing the ADC0816, 17 to a microprocessor

Microprocessor Interface Table

| PROCESSOR | READ | WRITE | INTERRUPT (COMMENT) |
|-----------|--|--|---|
| 8080 | $\overline{\text{MEMR}}$ | $\overline{\text{MEMW}}$ | INTR (Thru RST Circuit) |
| 8085 | $\overline{\text{RD}}$ | $\overline{\text{WR}}$ | INTR (Thru RST Circuit) |
| Z-80 | $\overline{\text{RD}}$ | $\overline{\text{WR}}$ | $\overline{\text{INT}}$ (Thru RST Circuit, Mode 0) |
| SC/MP | NRDS | NWDS | SA (Thru Sense A) |
| 6800 | $\text{VMA} \cdot \phi 2 \cdot \text{R/W}$ | $\text{VMA} \cdot \phi 2 \cdot \text{R/W}$ | $\overline{\text{IRQA}}$ or $\overline{\text{IRQB}}$ (Thru PIA) |

Ordering Information

| TEMPERATURE RANGE | | -40°C to +85°C | | -55°C to +125°C |
|-------------------|--------------------------|-----------------|-------------------|-------------------|
| Error | $\pm 1/2$ Bit Unadjusted | ADC0816CCN | ADC0816CCJ | ADC0816CJ |
| | ± 1 Bit Unadjusted | ADC0817CCN | | |
| Package Outline | | N40A Molded DIP | J40A Hermetic DIP | J40A Hermetic DIP |

ADC1210, ADC1211 12-Bit CMOS A/D Converters

General Description

The ADC1210, ADC1211 are low power, medium speed, 12-bit successive approximation, analog-to-digital converters. The devices are complete converters requiring only the application of a reference voltage and a clock for operation. Included within the device are the successive approximation logic, CMOS analog switches, precision laser trimmed thin film R-2R ladder network and FET input comparator.

The ADC1210 offers 12-bit resolution and 12-bit accuracy, and the ADC1211 offers 12-bit resolution with 10-bit accuracy. The inverted binary outputs are directly compatible with CMOS logic. The ADC1210, ADC1211 will operate over a wide supply range, convert both bipolar and unipolar analog inputs, and operate in either a continuous conversion mode or logic-controlled

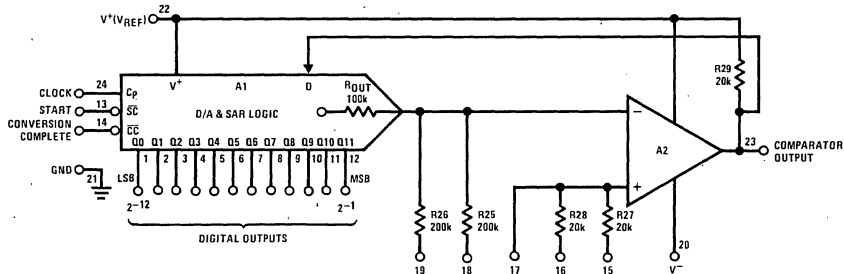
START-STOP conversion mode. The devices are capable of making a 12-bit conversion in 100 μ s typ, and can be connected to convert 10 bits in 30 μ s.

Both devices are available in military and industrial temperature ranges.

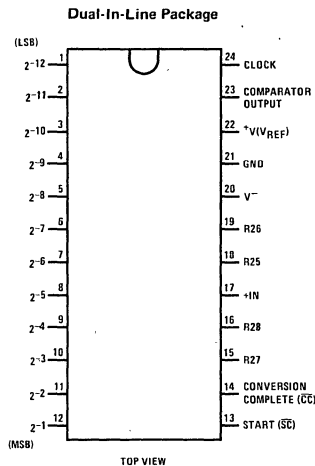
Features

- 12-bit resolution
- $\pm 1/2$ LSB linearity
- Single +5V to ± 15 V supply range
- 100 μ s 12-bit, 30 μ s 10-bit conversion rate
- CMOS compatible outputs
- Bipolar or unipolar analog inputs
- 200 k Ω analog input impedance
- Low cost

Block Diagram



Connection Diagram



Absolute Maximum Ratings

| | |
|--|--------------------|
| Maximum Reference Supply Voltage (V^+) | 16V |
| Maximum Negative Supply Voltage (V^-) | -20V |
| Voltage At Any Logic Pin | $V^+ + 0.3V$ |
| Analog Input Voltage | $\pm 15V$ |
| Maximum Digital Output Current | $\pm 10\text{ mA}$ |
| Maximum Comparator Output Current | 50 mA |
| Comparator Output Short-Circuit Duration | 5 Seconds |

| | |
|--|-----------------|
| Power Dissipation | See Curves |
| Operating Temperature Range | |
| ADC1210HD, ADC1211HD | -55°C to +125°C |
| ADC1210HCD, ADC1211HCD | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (Notes 1 and 2)

| PARAMETER | CONDITIONS | ADC1210 | | | ADC1211 | | | UNITS |
|--------------------------|---|---------|-----|--------------|---------|-----|--------------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 12 | | | 12 | | | Bits |
| Linearity Error | (Note 3) $f_{CLK} = 65\text{ kHz}$, $T_A = 25^\circ\text{C}$ $f_{CLK} = 65\text{ kHz}$ | | | ± 0.0122 | | | ± 0.0488 | % FS |
| | | | | ± 0.0244 | | | | % FS |
| Full Scale Error | $T_A = 25^\circ\text{C}$, Unadjusted | | | 0.1 | | | 0.25 | % FS |
| Zero Scale Error | $T_A = 25^\circ\text{C}$, Unadjusted | | | 0.1 | | | 0.25 | % FS |
| Quantization Error | | | | $\pm 1/2$ | | | $\pm 1/2$ | LSB |
| Input Resistor Values | R27, R28 | | 20 | | 20 | | | k Ω |
| Input Resistor Values | R25, R26 | | 200 | | 200 | | | k Ω |
| Input Resistor Ratios | R25/R26, R27/R28 | | | 0.1 | | | 0.1 | % |
| Logic "1" Input Voltage | | 8 | | | 8 | | | V |
| Logic "0" Input Voltage | | | | 2 | | | 2 | V |
| Logic "1" Input Current | $V_{IN} = 10.24V$ | | | 1 | | | 1 | μA |
| Logic "0" Input Current | $V_{IN} = 0V$ | | | -1 | | | -1 | μA |
| Logic "1" Output Voltage | $I_{OUT} \leq -1\ \mu\text{A}$ | 9.2 | | | 9.2 | | | V |
| Logic "0" Output Voltage | $I_{OUT} \leq 1\ \mu\text{A}$ | | | 0.5 | | | 0.5 | V |
| Positive Supply Current | $V^+ = 15V$, $f_{CLK} = 65\text{ kHz}$, $T_A = 25^\circ\text{C}$ | | 5 | 8 | | 5 | 8 | mA |
| Negative Supply Current | $V^- = -15V$, $T_A = 25^\circ\text{C}$ | | 4 | 6 | | 4 | 6 | mA |

AC Electrical Characteristics $T_A = 25^\circ\text{C}$, (Notes 1 and 2)

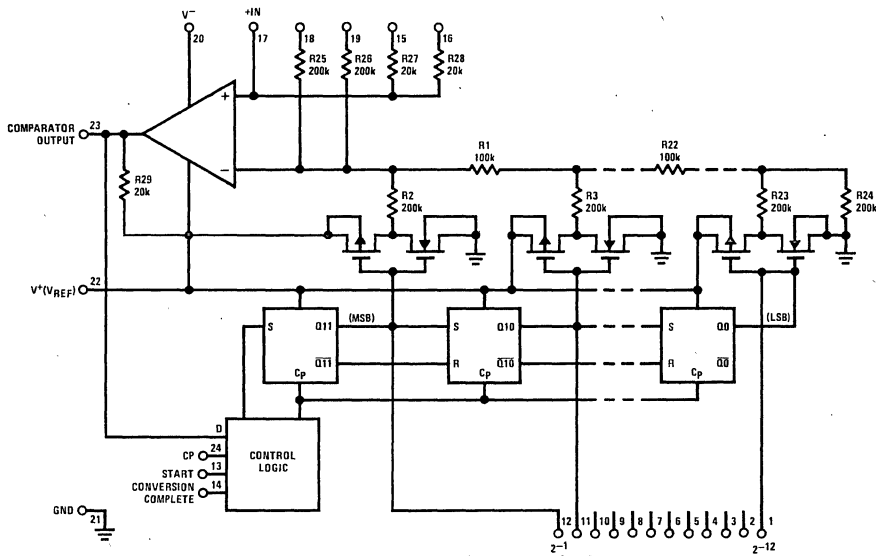
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|----------------------------------|-----|-----|-----|---------------|
| Conversion Time | | | 100 | 200 | μs |
| Maximum Clock Frequency | | | 130 | 65 | kHz |
| Maximum Clock Pulse Width | | 100 | 50 | | ns |
| Propagation Delay From Clock to Data Output (Q0 to Q11) | $t_r \leq t_f \leq 10\text{ ns}$ | | 60 | 150 | ns |
| Propagation Delay From Clock to Conversion Complete | $t_r \leq t_f \leq 10\text{ ns}$ | | 60 | 150 | ns |
| Clock Rise and Fall Time | | | | 5 | μs |
| Input Capacitance | | | 10 | | pF |
| Start Conversion Set-Up Time | | 30 | | | ns |

Note 1: Unless otherwise noted, these specifications apply for $V^+ = 10.240V$, $V^- = -15V$, over the temperature range -55°C to +125°C for the ADC1210HD, ADC1211HD, and -25°C to +85°C for the ADC1210HCD, ADC1211HCD.

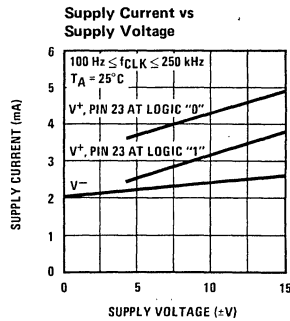
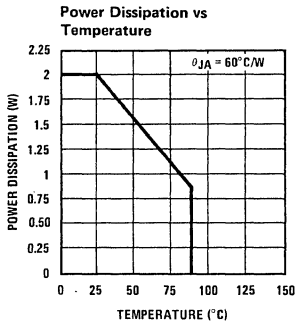
Note 2: All typical values are for $T_A = 25^\circ\text{C}$.

Note 3: Unless otherwise noted, this specification applies over the temperature range -25°C to +85°C. Provision is made to adjust zero scale error to 0V and full-scale to 10.2375V during testing. Standard linearity test circuit is shown in Figure 5a.

Schematic Diagram



Note: 3 bits shown for clarity



Applications Information

THEORY OF OPERATION

The ADC1210, ADC1211 are successive approximation analog-to-digital converters, i.e., the conversion takes place 1 bit at a time by comparing the output of the internal D/A to the (unknown) input voltage. The START input (pin 13), when taken low, causes the register to reset synchronously on the next CLOCK low-to-high transition. The MSB, Q11 is set to the low state, and the remaining bits, Q0 through Q10, will be set to the high state. The register will remain in this state until the SC input is taken high. When START goes high, the conversion will begin on the low-to-high transition of the CLOCK pulse. Q11 will then assume the state of pin 23. If pin 23 is high, Q11 will be high; if pin 23 is low, Q11 will remain low. At the same time, the next bit, Q10 is set low. All remaining bits, Q0-Q9

will remain unchanged (high). This process will continue until the LSB (Q0) is found. When the conversion process is completed, it is indicated by CONVERSION COMPLETE (CC) (pin 14) going low. The logic levels at the data output pins (pins 1-12) are the complemented-binary representation of the converted analog signal with Q11 being the MSB and Q0 being the LSB. The register will remain in the above state until the SC is again taken low.

An application example is shown in Figure 1. In this case, a 0 to -10.2375V input is being converted using the ADC1210 with $V^+ = 10.240V$, $V^- = -15V$. Figure 1b is the timing diagram for full scale input, Figure 1c is the timing diagram for zero scale input, Figure 1d is the timing diagram for -3.4125V input (0101010101 = output).

Applications Information (Continued)

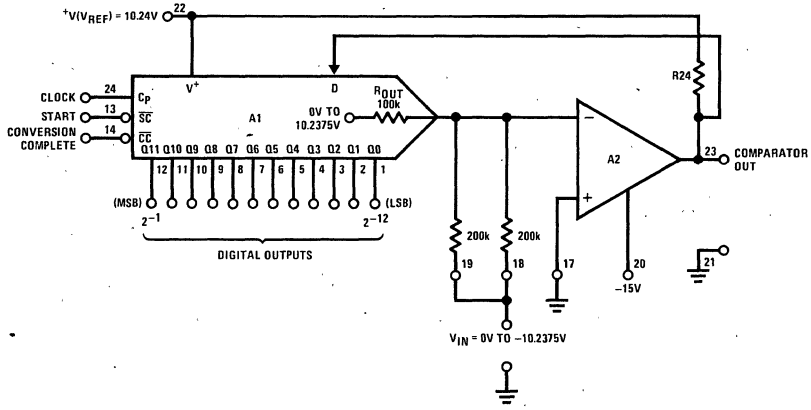


FIGURE 1a. ADC1210 Connected for 0V to -10.2375V (Natural Binary Output)

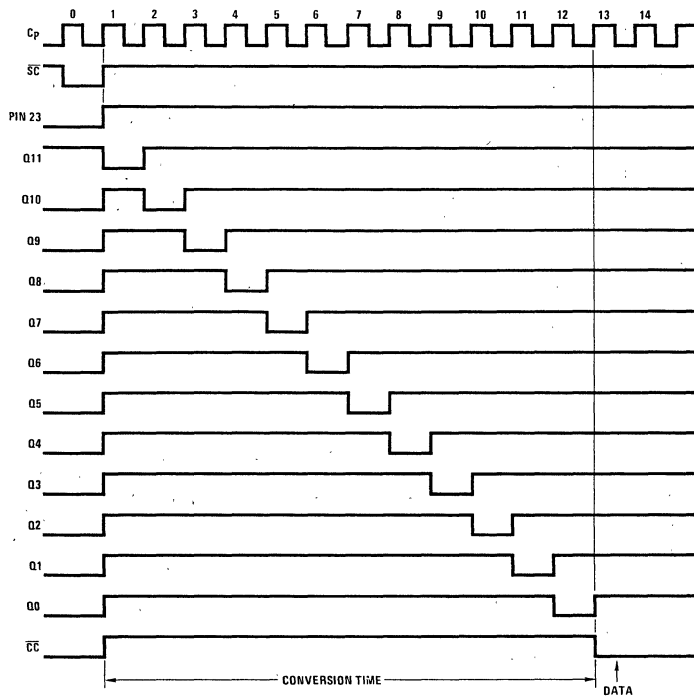


FIGURE 1b. Timing Diagram for V_{IN} = Full Scale Input

Applications Information (Continued)

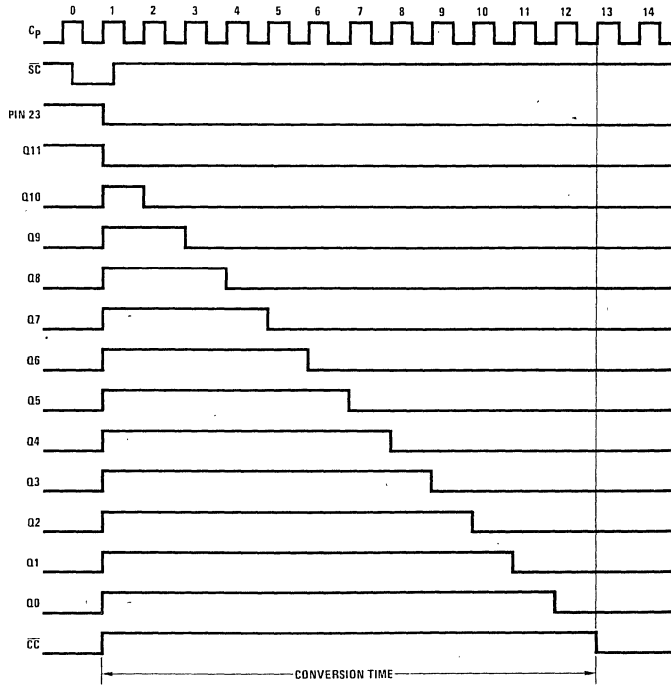


FIGURE 1c. Timing Diagram for $V_{IN} = \text{Zero Scale}$

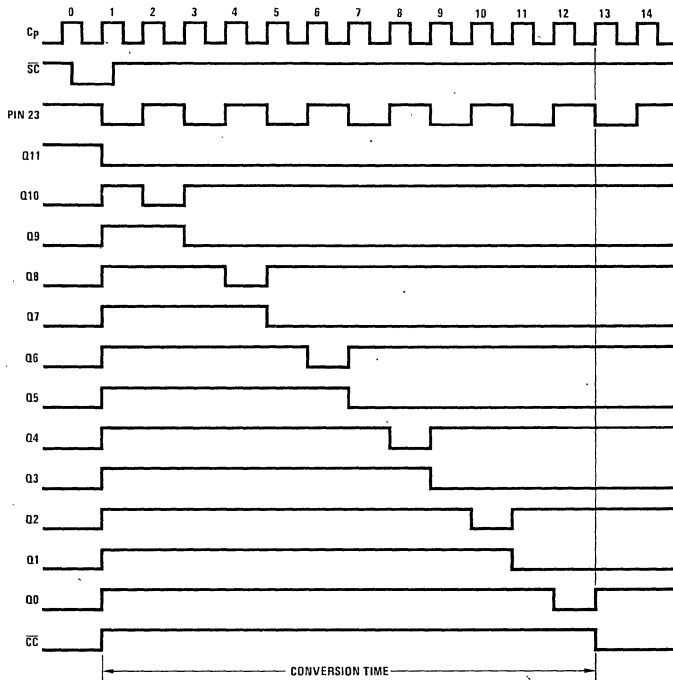


FIGURE 1d. Timing Diagram for $V_{IN} = -3.4125V$ (010101010101)

Applications Information (Continued)

TABLE I. Pin Assignments and Explanations

| PIN NUMBER | MNEMONIC | FUNCTION |
|------------|-----------------|---|
| 1-12 | Q11-Q0 | Digital (data) output pins. This information is a parallel 12-bit complemented binary representation of the converted analog signal. All data is valid when "Conversion Complete" goes low. Logic levels are ground and V^+ . |
| 13 | \overline{SC} | Start Conversion is a logic input which causes synchronous reset of the successive approximation register and initiates conversion. Logic levels are ground and V^+ . |
| 14 | \overline{CC} | "Conversion Complete" is a digital output signal which indicates the status of the converter. When \overline{CC} is high, conversion is taking place, when low conversion is completed. Logic levels are ground and V^+ . |
| 15, 16 | R27, R28 | R27 and R28 are two application resistors connected to the comparator non-inverting input. The resistors may be used in various modes of operation. Their nominal values are 20 k Ω each. See Applications section. |
| 17 | +IN | Non-inverting input of the analog comparator. This node is used in various configurations and for compensation of the loop. See Applications section. |
| 18, 19 | R25, R26 | R25 and R26 are two application resistors that are tied internally to the inverting input of the comparator. Their nominal values are 200 k Ω each. See Applications section. The R-2R ladder network will have the same temperature coefficient as these resistors. |
| 20 | V^- | Negative supply voltage for bias of the analog comparator. Optionally may be grounded or operated with voltages to -20V. |
| 21 | GND | Ground for both digital and analog signals. |
| 22 | $V^+(V_{REF})$ | V^+ sets both maximum full scale and input and output logic levels. |
| 23 | CO | Comparator output. |
| 24 | Cp | Clock is an input which causes the successive approximation (shift) register to advance through the conversion sequence. Logic levels are ground and V^+ . |

POWER SUPPLY CONSIDERATIONS AND DECOUPLING

Pin 22 is both the positive supply and voltage reference input to the ADC1210, ADC1211. The magnitude of V^+ determines the input logic "1" threshold and the output voltage from the CMOS SAR. The device will operate over a range of V^+ from 5V to 15V. However, in order to preserve 12-bit accuracy, V^+ should be well regulated (0.01%) and isolated from external switching transients. It is therefore recommended that pin 22 be decoupled with a 4.7 μ F tantalum capacitor in parallel with a 0.1 μ F ceramic disc capacitor.

The V^- supply (pin 20) provides negative bias for the FET comparator. Although pin 20 may be grounded in some applications, it must be at least 2V more negative than the most negative analog input signal. When a negative supply is used, pin 20 should also be bypassed with 4.7 μ F in parallel with 0.1 μ F.

Grounding and circuit layout are extremely important in preserving 12-bit accuracy. The user is advised to employ separate digital and analog returns, and to make these PC board traces as "heavy" as practical.

SHORT CYCLE FOR IMPROVED CONVERSION TIME (FIGURE 2)

The ADC1210, ADC1211 counting sequence may be truncated to decrease conversion time. For example, when using the ADC1211, 2 clock intervals may be

"saved" if 10-bit conversion accuracy is taking place. The Q2 output should be "OR'd" with CONVERSION COMPLETE (\overline{CC}) in order to ensure that the register does not lock-up upon power turn-on.

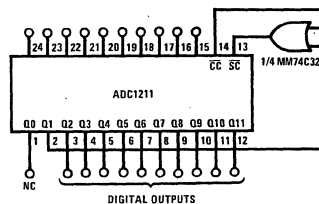


FIGURE 2. Short Cycling the ADC1211 to Improve 10-Bit Conversion Time (Continuous Conversion)

LOGIC COMPATIBILITY

The ADC1210, ADC1211 is intended to interface with CMOS logic levels: i.e., the logic inputs and outputs are directly compatible with series 54C/74C and CD4000 family of logic components. The outputs of the ADC1210, ADC1211 will not drive LPTTL, TTL or PMOS logic directly without degrading accuracy. Various recommended interface techniques are shown in Figures 3 and 4.

OPERATING CONFIGURATIONS

Several recommended operating configurations are shown in Figure 5.

Applications Information (Continued)

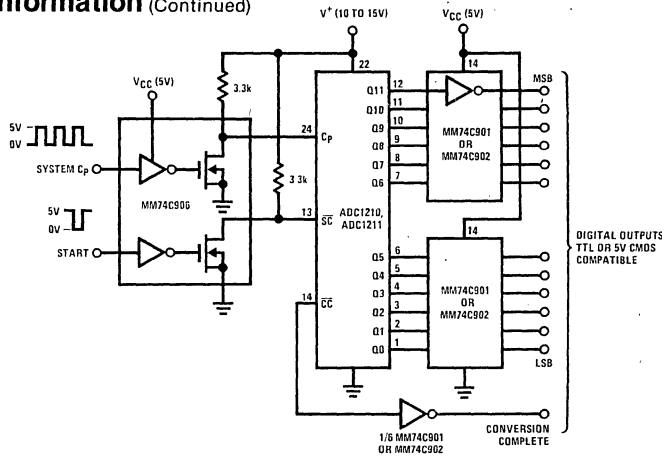


FIGURE 3. Interfacing an ADC1210, ADC1211 Running on $V^+ > V_{CC}$. Example: $V^+ = 10.24V$, System $V_{CC} = 5V$

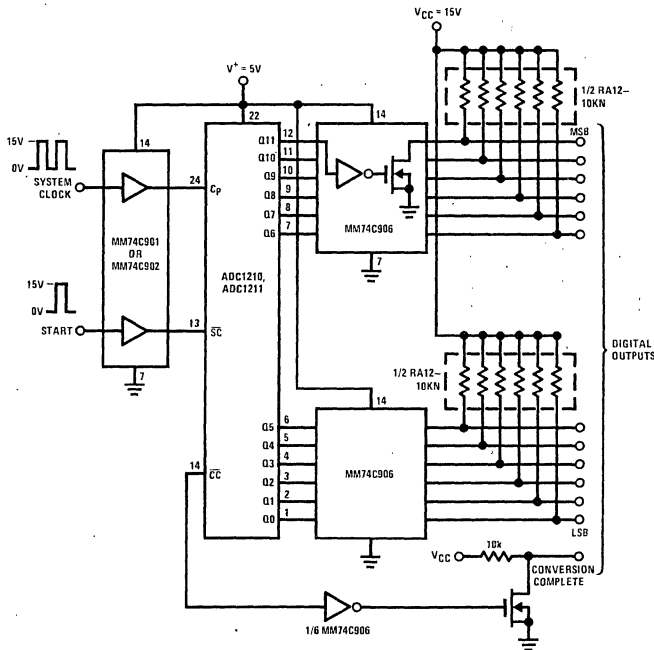


FIGURE 4. Interfacing an ADC1210, ADC1211 Running on $V^+ < V_{CC}$. Example: $V^+ = 5V$, $V_{CC} = 15V$

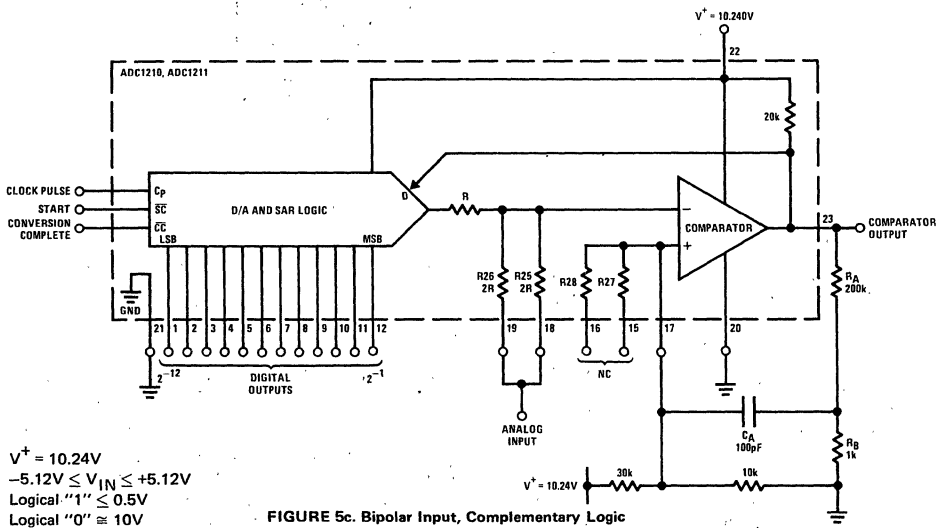
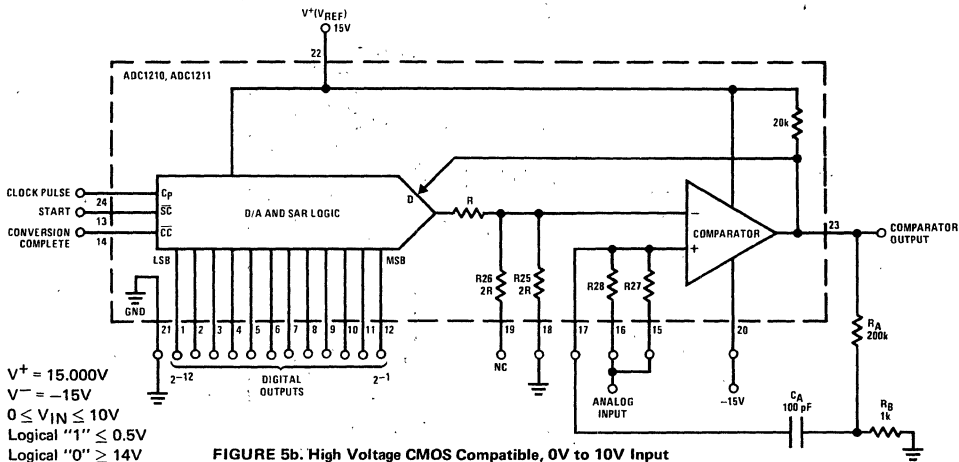
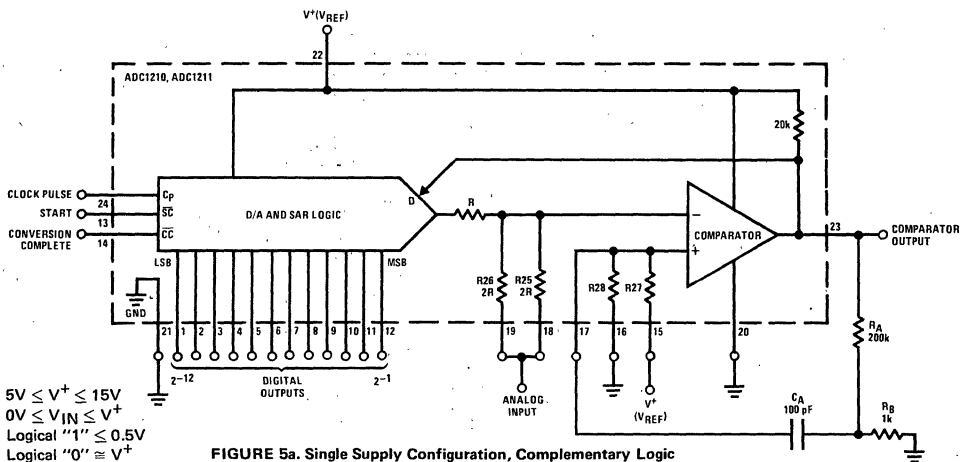
OFFSET AND FULL SCALE ADJUST

A variety of techniques may be employed to adjust Offset and Full Scale on the ADC1210, ADC1211. A straight-forward Full Scale Adjust is to incrementally vary V^+ (V_{REF}) to match the analog input voltage. A recommended technique is shown in Figure 6. An LM199 and low drift op amp (e.g., the LH0044) are used to provide the precision reference. The ADC1210, ADC1211 is put in the continuous convert mode by shorting pins 13 and 14. An analog voltage equal to V_{REF} minus 1 1/2 LSB (10.23625V) is applied to pins 18 and 19, and R1 is adjusted until the LSB flickers equally between logic "1" and logic "0" (all other out-

puts must be stable logic "0"). Offset Null is accomplished by then applying an analog input voltage equal to 1/2 LSB at pins 18 and 19. R2 is adjusted until the LSB output flickers equally between logic "1" and logic "0" (all other bits are stable). In the circuit of Figure 6, the ADC1210, ADC1211 is configured for Complementary Binary logic and the values shown are for $V^+ = 10.240V$, $V_{FS} = 10.2375V$, $LSB = 2.5 mV$.

An alternate technique is shown in Figure 7. In this instance, an LH0071 is used to provide the reference voltage. An analog input voltage equal to V_{REF} minus 1 1/2 LSB (10.23625V) is applied to pins 18 and 19.

Applications Information (Continued)



Applications Information (Continued)

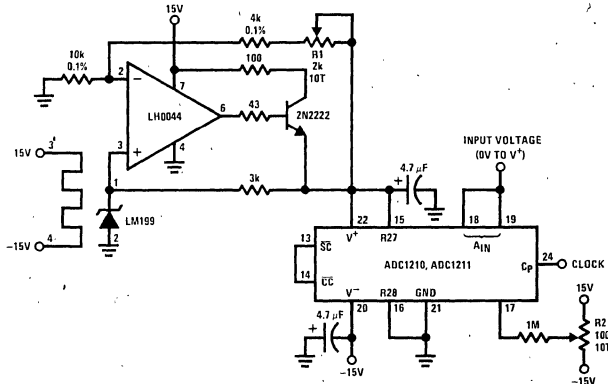


FIGURE 6. Offset and Full Scale Adjustment for Complementary Binary

R1 is adjusted until the LSB output flickers equally between logic "1" and logic "0" (all other outputs must be a stable logic "0"). For Offset Null, an analog voltage equal to 1/2 LSB (1.25 mV) is then applied to pins 18 and 19, and R2, is adjusted until the LSB output flickers equally between logic "1" and "0".

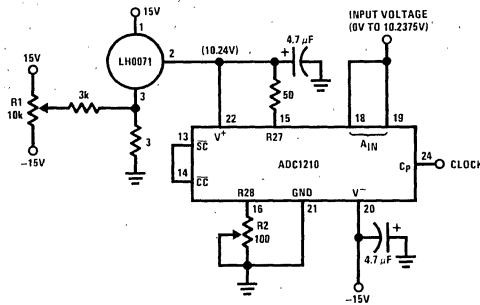


FIGURE 7. Offset and Full-Scale Adjustment Technique Using LHO071

In both techniques shown, adjusting the Full-Scale first and then Offset minimizes adjustment interaction. At least one iteration is recommended as a self-check.

Definition of Terms

Resolution: The Resolution of an A/D is an expression of the smallest change in input which will increment (or decrement) the output from one code to the next adjacent code. It is defined in number of bits, or 1 part in 2^n . The ADC1210 and ADC1211 have a resolution of 12 bits or 1 part in 4,096 (0.0244%).

Quantization Uncertainty: Quantization Uncertainty is a direct consequence of the resolution of the converter. All analog voltages within a given range are represented by a single digital output code. There is, therefore, an inherent conversion error even for a perfect A/D. As an example, the transfer characteristic of a perfect 3-bit A/D is shown in Figure 8.

As can be seen, all input voltages between 0V and 1V are represented by an output code of 000. All input voltages between 1V and 2V are represented by an output code of 001, etc. If the midpoint of the range is assumed to be the nominal value (e.g., 0.5V), there is an Uncertainty of $\pm 1/2$ LSB. It is common practice to

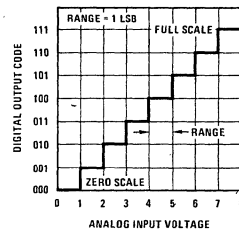


FIGURE 8. Quantization Uncertainty of a Perfect 3-Bit A/D

offset the converter 1/2 LSB in order to reduce the Uncertainty to $\pm 1/2$ LSB as shown in Figure 9. Rather than ± 1 , -0 bit shown in Figure 8. Quantization Uncertainty can only be reduced by increasing Resolution. It is expressed as $\pm 1/2$ LSB or as an error percentage of full scale ($\pm 0.0122\%$ FS for the ADC1210).

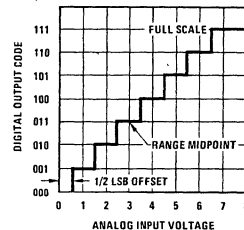


FIGURE 9. Transfer Characteristic Offset 1/2 LSB to Minimize Quantizing Uncertainty

Linearity Error: Linearity Error is the maximum deviation from a straight line passing through the end points of the A/D transfer characteristic. It is measured after calibrating Zero and Full Scale Error. The Linearity Error of the ADC1210 is guaranteed to be less than $\pm 1/2$ LSB or $\pm 0.0122\%$ of FS and $\pm 0.0488\%$ of FS for the AD1211. Linearity is a performance characteristic intrinsic to the device and cannot be externally adjusted.

Zero Scale Error (or Offset): Zero Scale Error is a measure of the difference between the output of an ideal and the actual A/D for zero input voltage. As shown in Figure 10, the effect of Zero Scale Error is to shift the transfer characteristic to the right or left along the abscissa. Any voltage more negative than the LSB transition gives an output code of 000. In practice, therefore, the voltage at which the 000 to 001 transition

Applications Information (Continued)

takes place is ascertained, this input voltage's departure from the ideal value is defined as the Zero Scale Error (Offset) and is expressed as a percentage of FS. In the example of *Figure 10*, the offset is 2 LSB's or 0.286% of FS.

The Zero Scale Error of the ADC1210, ADC1211 is caused primarily by offset voltage in the comparator. Because it is common practice to offset the A/D 1/2 LSB to minimize Quantization Error, the offsetting techniques described in the Applications Section may be used to null Zero Scale Error and accomplish the 1/2 LSB offset at the same time.

Full Scale Error (or Gain Error): Full Scale Error is a measure of the difference between the output of an ideal A/D converter and the actual A/D for an input voltage equal to full scale. As shown in *Figure 11*, the Full Scale Error effect is to rotate the transfer characteristic angularly about the origin. Any voltage more positive than the Full Scale transition gives an output code of 111. In practice, therefore, the voltage at which the transition from 111 to 110 occurs is ascertained. The input voltage's departure from the ideal value is defined as Full Scale Error and is expressed as a percentage of FS. In the example of *Figure 11*, Full Scale Error is 1 1/2 LSB's, or 0.214% of FS.

Full Scale Error of the ADC1210, ADC1211 is due primarily to mismatch in the R-2R ladder equivalent

output impedance and input resistors R25, R26, R27, and R28. The gain error may be adjusted to zero as outlined in the Applications section.

Monotonicity and Missing Codes: Monotonicity is a property of a D/A which requires an increasing or constant output voltage for an increasing digital input code. Monotonicity of a D/A converter does not, in itself, guarantee that an A/D built with that D/A will not have missing codes. However, the ADC1210 and ADC1211 are guaranteed to have no missing codes.

Conversion Time: The ADC1210, ADC1211 are successive approximation A/D converters requiring 13 clock intervals for a conversion to specified accuracy for the ADC1210 and 11 clocks for the ADC1211. There is a trade-off between accuracy and clock frequency due to settling time of the ladder and propagation delay through the comparator. By modifying the hysteresis network around the comparator, conversions with 10-bit accuracy can be made in 30 μ s. Replace R_A, R_B and C_A in *Figure 5* with a 10 M Ω resistor between pin 23 (Comparator Output) and pin 17 (+IN), and increase the clock rate to 366 kHz.

In order to prevent errors during conversion, the analog input voltage should not be allowed to change by more than $\pm 1/2$ LSB. This places a maximum slew rate of 12.5 μ V/ μ s on the analog input voltage. The usual solution to this restriction is to place a Sample and Hold in front of the A/D. See AN-154 for additional information.

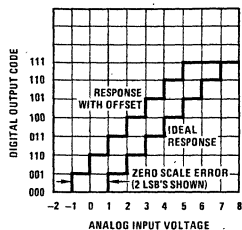


FIGURE 10. A/D Transfer Characteristic with Offset

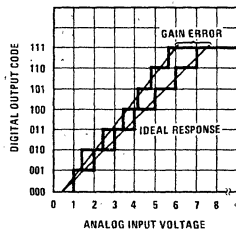


FIGURE 11. Full Scale (Gain Error)

Ordering Information

| PART NUMBER | OPERATING TEMPERATURE RANGE | 25°C LINEARITY |
|-------------|-----------------------------|----------------|
| ADC1210HD | -55°C to +125°C | 0.01% |
| ADC1210HCD | -25°C to +85°C | 0.01% |
| ADC1211HD | -55°C to +125°C | 0.05% |
| ADC1211HCD | -25°C to +85°C | 0.05% |

*See NS Package HY24A

DAC0800 (LMDAC08) 8-Bit Digital-to-Analog Converter

General Description

The DAC08 is a monolithic 8-bit high-speed current-output digital-to-analog converter (DAC) featuring typical settling times of 100 ns. When used as a multiplying DAC, monotonic performance over a 40 to 1 reference current range is possible. The DAC08 also features high compliance complementary current outputs to allow differential output voltages of 20 Vp-p with simple resistor loads as shown in *Figure 1*. The reference-to-full-scale current matching of better than ± 1 LSB eliminates the need for full scale trims in most applications while the nonlinearities of better than $\pm 0.1\%$ over temperature minimizes system error accumulations.

The noise immune inputs of the DAC08 will accept TTL levels with the logic threshold pin, V_{LC} , pin 1 grounded. Simple adjustments of the V_{LC} potential allow direct interface to all logic families. The performance and characteristics of the device are essentially unchanged over the full $\pm 4.5V$ to $\pm 18V$ power supply range; power dissipation is only 33 mW with $\pm 5V$ supplies and is independent of the logic input states.

The DAC0800L, DAC0802L, DAC0800LC, DAC0801LC and DAC0802LC are a direct replacement for the DAC08, DAC08A, DAC08C, DAC08E and DAC08H, respectively.

Features

- Fast settling output current 100 ns
- Full scale error ± 1 LSB
- Nonlinearity over temperature $\pm 0.1\%$
- Full scale current drift ± 10 ppm/ $^{\circ}C$
- High output compliance $-10V$ to $+18V$
- Complementary current outputs
- Interface directly with TTL, CMOS, PMOS and others
- 2 quadrant wide range multiplying capability
- Wide power supply range $\pm 4.5V$ to $\pm 18V$
- Low power consumption 33 mW at $\pm 5V$
- Low cost

Typical Applications

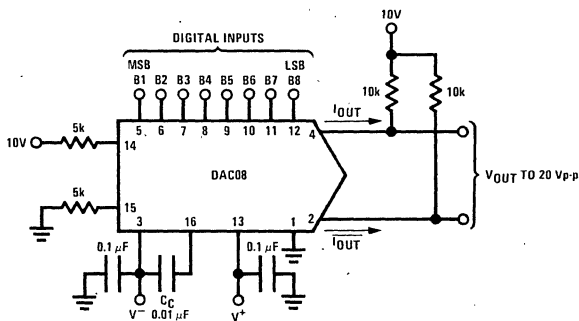
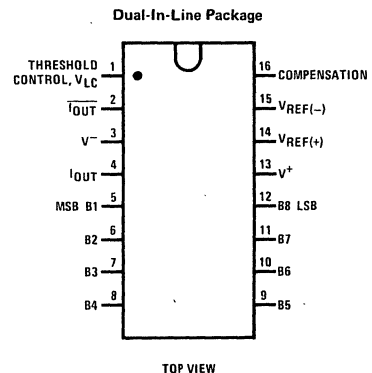


FIGURE 1. ± 20 Vp-p Output Digital-to-Analog Converter

Connection Diagram



Ordering Information

| NON LINEARITY | TEMPERATURE RANGE | ORDER NUMBERS* | | | | | |
|-----------------|--|------------------|-----------|------------------|-----------|------------------|-----------|
| | | D PACKAGE (D16C) | | J PACKAGE (J16A) | | N PACKAGE (N16A) | |
| $\pm 0.1\%$ FS | $-55^{\circ}C \leq T_A \leq +125^{\circ}C$ | DAC0802LD | LMDAC08AD | | | | |
| $\pm 0.1\%$ FS | $0^{\circ}C \leq T_A \leq +70^{\circ}C$ | | | DAC0802LCJ | LMDAC08HJ | DAC0802LCN | LMDAC08HN |
| $\pm 0.19\%$ FS | $-55^{\circ}C \leq T_A \leq +125^{\circ}C$ | DAC0800LD | LMDAC08D | | | | |
| $\pm 0.19\%$ FS | $0^{\circ}C \leq T_A \leq +70^{\circ}C$ | | | DAC0800LCJ | LMDAC08EJ | DAC0800LCN | LMDAC08EN |
| $\pm 0.39\%$ FS | $0^{\circ}C \leq T_A \leq +70^{\circ}C$ | | | DAC0801LCJ | LMDAC08CJ | DAC0801LCN | LMDAC08CN |

*Note. Devices may be ordered by using either order number.

Absolute Maximum Ratings

| | |
|---|---|
| Supply Voltage | ±18V or 36V |
| Power Dissipation (Note 1) | 500 mW |
| Reference Input Differential Voltage (V14 to V15) | V ⁻ to V ⁺ |
| Reference Input Common-Mode Range (V14, V15) | V ⁻ to V ⁺ |
| Reference Input Current | 5 mA |
| Logic Inputs | V ⁻ to V ⁻ plus 36V |
| Analog Current Outputs | Figure 24 |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Conditions

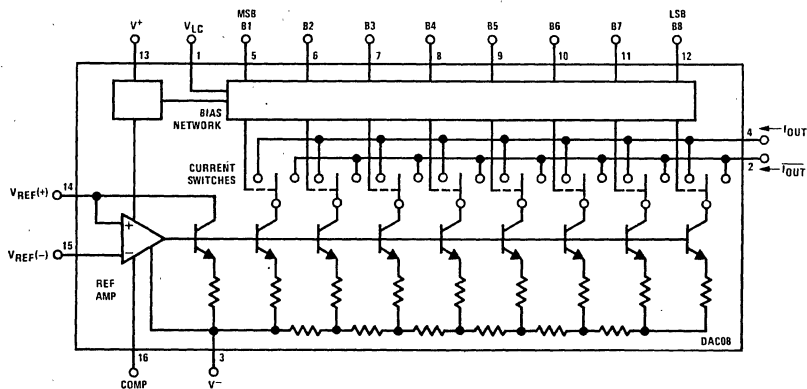
| Temperature (T _A) | MIN | MAX | UNITS |
|-------------------------------|-----|------|-------|
| DAC0802LA, LMDAC08A | -55 | +125 | °C |
| DAC0800L, LMDAC08 | -55 | +125 | °C |
| DAC0800LC, LMDAC08E, | 0 | +70 | °C |
| DAC0801LC, LMDAC08C, | 0 | +70 | °C |
| DAC0802LC, LMDAC08H | 0 | +70 | °C |

Electrical Characteristics (V_S = ±15V, I_{REF} = 2 mA, T_{MIN} ≤ T_A ≤ T_{MAX} unless otherwise specified. Output characteristics refer to both I_{OUT} and $\overline{I_{OUT}}$.)

| PARAMETER | CONDITIONS | DAC0802L/ DAC0802LC | | | DAC0800L/ DAC0800LC | | | DAC0801LC | | | UNITS |
|---|---|------------------------|--------|-------|------------------------|--------|-------|-----------|--------|-------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 | Bits |
| Monotonicity | | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 | Bits |
| Nonlinearity | | | | ±0.1 | | | ±0.19 | | | ±0.39 | %FS |
| t _S Settling Time | To ±1/2 LSB, All Bits Switched "ON" or "OFF", T _A = 25°C | | 100 | 135 | | | | | 100 | 150 | ns |
| | DAC0800L | | | | | 100 | 135 | | | | ns |
| | DAC0800LC | | | | | 100 | 150 | | | | ns |
| t _{PLH} , t _{PHL} Propagation Delay | T _A = 25°C | | | | | | | | | | |
| Each Bit | | | 35 | 60 | | 35 | 60 | | 35 | 60 | ns |
| All Bits Switched | | | 35 | 60 | | 35 | 60 | | 35 | 60 | ns |
| TC _{IFS} Full Scale Tempco | | | ±10 | ±50 | | ±10 | ±50 | | ±10 | ±80 | ppm/°C |
| V _{OC} Output Voltage Compliance | Full Scale Current Change < 1/2 LSB, R _{OUT} > 20 MΩ Typ | -10 | | 18 | -10 | | 18 | -10 | | 18 | V |
| I _{FS4} Full Scale Current | V _{REF} = 10,000V, R ₁₄ = 5,000 kΩ R ₁₅ = 5,000 kΩ, T _A = 25°C | 1.984 | 1.992 | 2.000 | 1.94 | 1.99 | 2.04 | 1.94 | 1.99 | 2.04 | mA |
| I _{FS5} Full Scale Symmetry | I _{FS4} - I _{FS2} | | ±0.5 | ±4.0 | | ±1 | ±8.0 | | ±2 | ±16 | μA |
| I _{Z5} Zero Scale Current | | | 0.1 | 1.0 | | 0.2 | 2.0 | | 0.2 | 4.0 | μA |
| I _{FSR} Output Current Range | V ⁻ = -5V | 0 | 2.0 | 2.1 | 0 | 2.0 | 2.1 | 0 | 2.0 | 2.1 | mA |
| | V ⁻ = -8V to -18V | 0 | 2.0 | 4.2 | 0 | 2.0 | 4.2 | 0 | 2.0 | 4.2 | mA |
| V _{IL} Logic Input Levels | | | | | | | | | | | |
| Logic "0" | V _{LC} = 0V | | | 0.8 | | | 0.8 | | | 0.8 | V |
| V _{IH} Logic "1" | | 2.0 | | | 2.0 | | | 2.0 | | | V |
| I _{IL} Logic Input Current | V _{LC} = 0V | | | | | | | | | | |
| Logic "0" | -10V ≤ V _{IN} ≤ +0.8V | -2.0 | | -10 | -2.0 | | -10 | -2.0 | | -10 | μA |
| Logic "1" | 2V ≤ V _{IN} ≤ +18V | 0.002 | | 10 | 0.002 | | 10 | 0.002 | | 10 | μA |
| V _{IS} Logic Input Swing | V ⁻ = -15V | -10 | | 18 | -10 | | 18 | -10 | | 18 | V |
| V _{THR} Logic Threshold Range | V _S = ±15V | -10 | | 13.5 | -10 | | 13.5 | -10 | | 13.5 | V |
| I ₁₅ Reference Bias Current | | | -1.0 | -3.0 | | -1.0 | -3.0 | | -1.0 | -3.0 | μA |
| dl/dt Reference Input Slew Rate | (Figure 24) | | 8.0 | | | 8.0 | | | 8.0 | | mA/μs |
| PSSI _{FS+} Power Supply Sensitivity | 4.5V ≤ V ⁺ ≤ 18V | | 0.0001 | 0.01 | | 0.0001 | 0.01 | | 0.0001 | 0.01 | %/% |
| PSSI _{FS-} Power Supply Sensitivity | -4.5V ≤ V ⁻ ≤ 18V I _{REF} = 1 mA | | 0.0001 | 0.01 | | 0.0001 | 0.01 | | 0.0001 | 0.01 | %/% |
| I ⁺ Power Supply Current | V _S = ±5V, I _{REF} = 1 mA | | 2.3 | 3.8 | | 2.3 | 3.8 | | 2.3 | 3.8 | mA |
| I ⁻ | | | -4.3 | -5.8 | | -4.3 | -5.8 | | -4.3 | -5.8 | mA |
| I ⁺ | V _S = 5V, -15V, I _{REF} = 2 mA | | 2.4 | 3.8 | | 2.4 | 3.8 | | 2.4 | 3.8 | mA |
| I ⁻ | | | -6.4 | -7.8 | | -6.4 | -7.8 | | -6.4 | -7.8 | mA |
| I ⁺ | V _S = ±15V, I _{REF} = 2 mA | | 2.5 | 3.8 | | 2.5 | 3.8 | | 2.5 | 3.8 | mA |
| I ⁻ | | | -6.5 | -7.8 | | -6.5 | -7.8 | | -6.5 | -7.8 | mA |
| P _D Power Dissipation | ±5V, I _{REF} = 1 mA | | 33 | 48 | | 33 | 48 | | 33 | 48 | mW |
| | 5V, -15V, I _{REF} = 2 mA | | 108 | 136 | | 108 | 136 | | 108 | 136 | mW |
| | ±15V, I _{REF} = 2 mA | | 135 | 174 | | 135 | 174 | | 135 | 174 | mW |

Note 1: The maximum junction temperature of the DAC0800, DAC0801 and DAC0802 is 100°C. For operating at elevated temperatures, devices in the dual-in-line J or D package must be derated based on a thermal resistance of 100°C/W, junction to ambient, 175°C/W for the molded dual-in-line N package.

Block Diagram



Equivalent Circuit

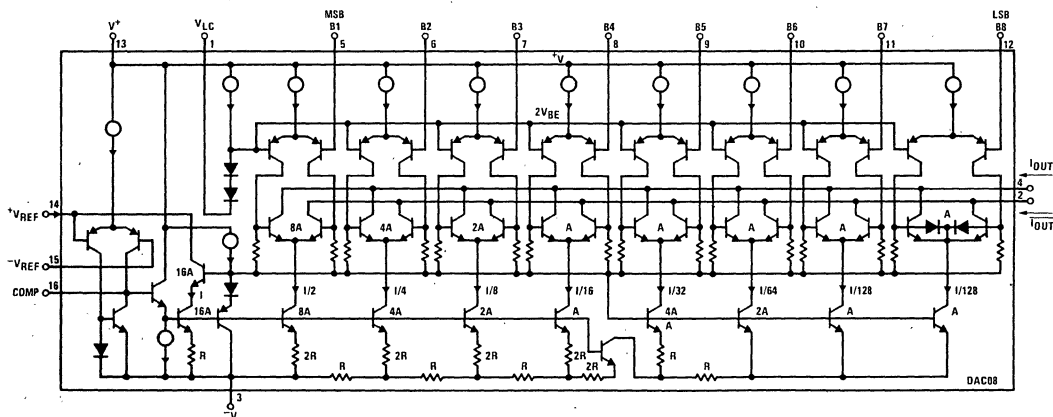


FIGURE 2

Typical Performance Characteristics

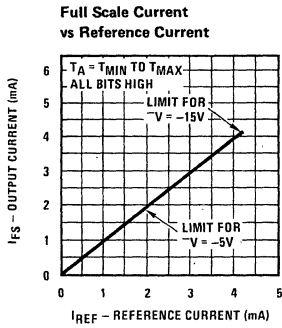


FIGURE 3

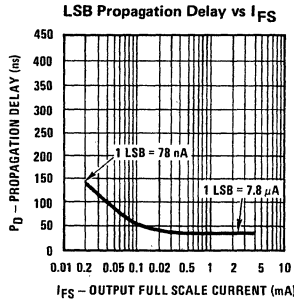
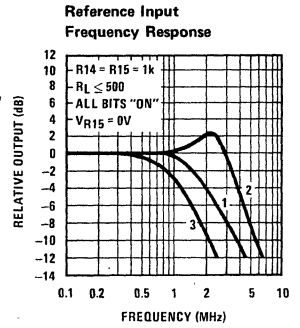
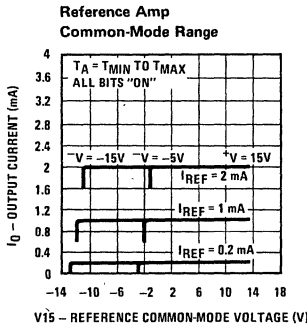


FIGURE 4



Curve 1: $C_C = 15 \text{ pF}$, $V_{IN} = 2 \text{ Vp-p}$ centered at 1 V .
 Curve 2: $C_C = 15 \text{ pF}$, $V_{IN} = 50 \text{ mVp-p}$ centered at 200 mV .
 Curve 3: $C_C = 0 \text{ pF}$, $V_{IN} = 100 \text{ mVp-p}$ at 0 V and applied through 50Ω connected to pin 14. 2 V applied to R_{14} .

FIGURE 5



Note. Positive common-mode range is always $(V_+) - 1.5 \text{ V}$.

FIGURE 6

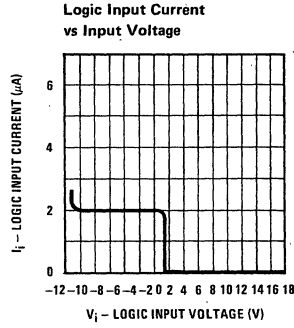


FIGURE 7

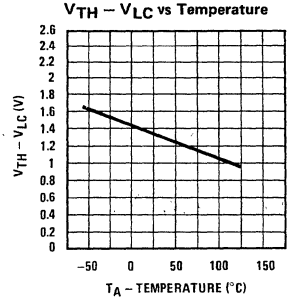


FIGURE 8

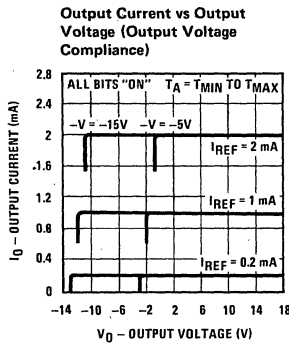


FIGURE 9

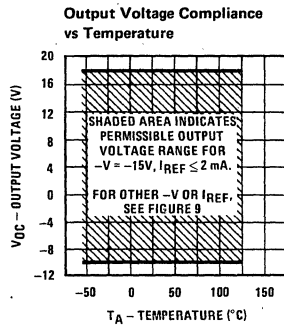
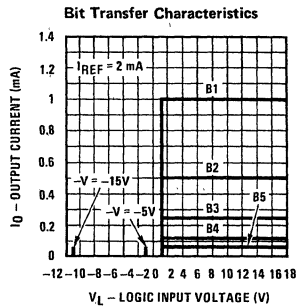


FIGURE 10



Note. B1-B8 have identical transfer characteristics. Bits are fully switched with less than $1/2 \text{ LSB}$ error, at less than $\pm 100 \text{ mV}$ from actual threshold. These switching points are guaranteed to lie between 0.8 and 2 V over the operating temperature range ($V_{LC} = 0 \text{ V}$).

FIGURE 11

Typical Performance Characteristics (Continued)

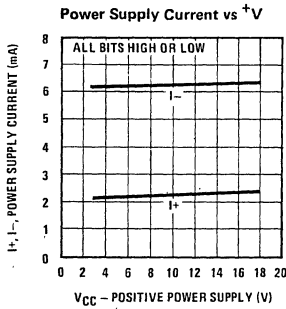


FIGURE 12

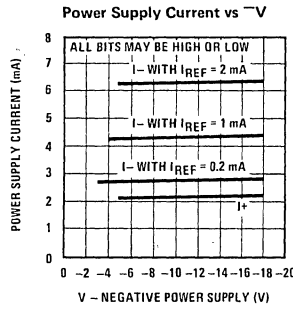


FIGURE 13

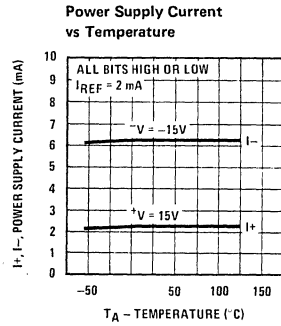


FIGURE 14

Typical Applications (Continued)

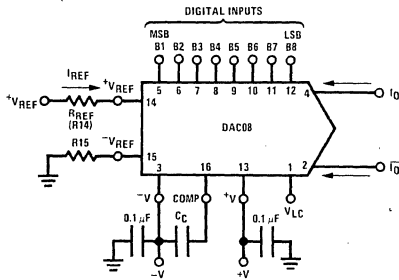


FIGURE 15. Basic Positive Reference Operation

$$I_{FS} \approx \frac{+V_{REF}}{R_{REF}} \times \frac{255}{256}$$

$I_0 + \bar{I}_0 = I_{FS}$ for all logic states

For fixed reference, TTL operation, typical values are:

- $V_{REF} = 10.000V$
- $R_{REF} = 5.000k$
- $R_{15} \approx R_{REF}$
- $C_C = 0.01 \mu F$
- $V_{LC} = 0V$ (Ground)

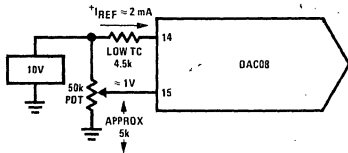
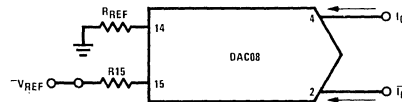


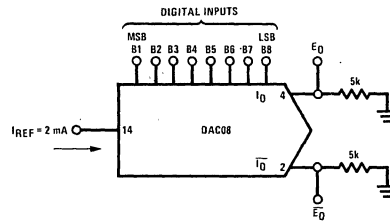
FIGURE 16. Recommended Full Scale Adjustment Circuit



$$I_{FS} \approx \frac{-V_{REF}}{R_{REF}} \times \frac{255}{256}$$

Note. R_{REF} sets I_{FS} ; R_{15} is for bias current cancellation

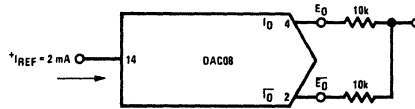
FIGURE 17. Basic Negative Reference Operation



| | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B8 | I_0 mA | \bar{I}_0 mA | E_0 | \bar{E}_0 |
|----------------|----|----|----|----|----|----|----|----|----------|----------------|--------|-------------|
| Full Scale | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1.992 | 0.000 | -9.960 | 0.000 |
| Full Scale-LSB | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1.984 | 0.008 | -9.920 | -0.040 |
| Half Scale+LSB | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1.008 | 0.984 | -5.040 | -4.920 |
| Half Scale | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1.000 | 0.992 | -5.000 | -4.960 |
| Half Scale-LSB | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0.992 | 1.000 | -4.960 | -5.000 |
| Zero Scale+LSB | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.008 | 1.984 | -0.040 | -9.920 |
| Zero Scale | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.000 | 1.992 | 0.000 | -9.960 |

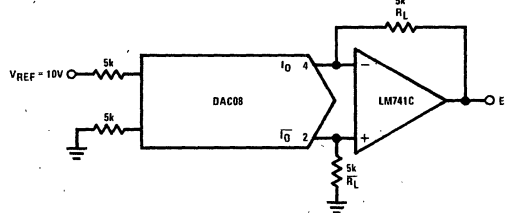
FIGURE 18. Basic Unipolar Negative Operation

Typical Applications (Continued)



| | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B8 | EO | EO-bar |
|---------------------|----|----|----|----|----|----|----|----|---------|---------|
| Pos. Full Scale | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | -9.920 | +10.000 |
| Pos. Full Scale-LSB | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | -9.840 | +9.920 |
| Zero Scale+LSB | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | -0.080 | +0.160 |
| Zero Scale | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.000 | +0.080 |
| Zero Scale-LSB | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | +0.080 | 0.000 |
| Neg. Full Scale+LSB | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | +9.920 | -9.840 |
| Neg. Full Scale | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | +10.000 | -9.920 |

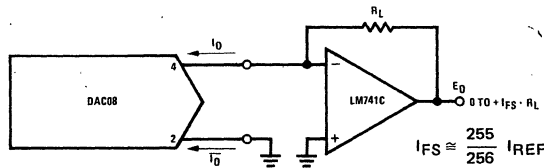
FIGURE 19. Basic Bipolar Output Operation



If $R_L = \bar{R}_L$ within $\pm 0.05\%$, output is symmetrical about ground

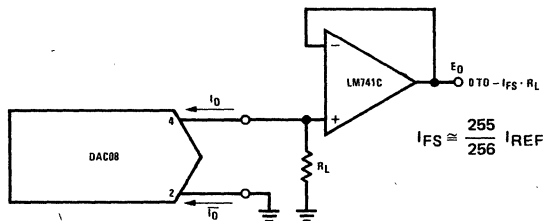
| | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B8 | EO |
|---------------------|----|----|----|----|----|----|----|----|--------|
| Pos. Full Scale | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | +9.920 |
| Pos. Full Scale-LSB | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | +9.840 |
| (+) Zero Scale | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | +0.040 |
| (-) Zero Scale | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | -0.040 |
| Neg. Full Scale+LSB | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | -9.840 |
| Neg. Full Scale | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | -9.920 |

FIGURE 20. Symmetrical Offset Binary Operation



For complementary output (operation as negative logic DAC), connect inverting input of op amp to \bar{I}_0 (pin 2), connect I_0 (pin 4) to ground.

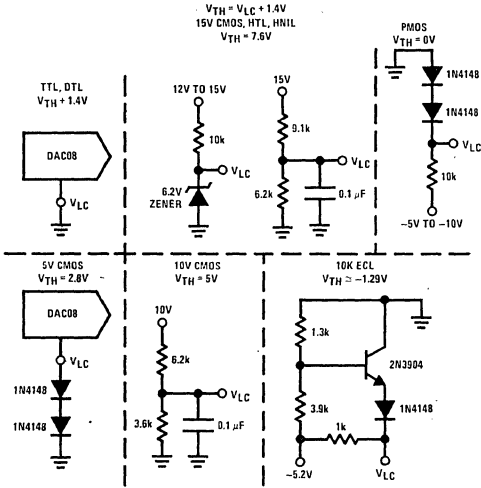
FIGURE 21. Positive Low Impedance Output Operation



For complementary output (operation as a negative logic DAC) connect non-inverting input of op amp to \bar{I}_0 (pin 2); connect I_0 (pin 4) to ground.

FIGURE 22. Negative Low Impedance Output Operation

Typical Applications (Continued)



Note. Do not exceed negative logic input range of DAC.

FIGURE 23. Interfacing with Various Logic Families

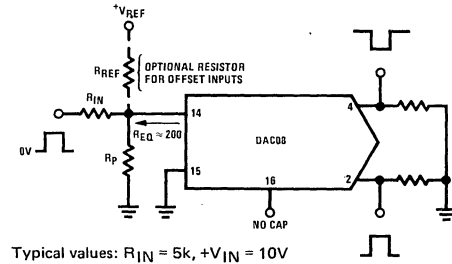
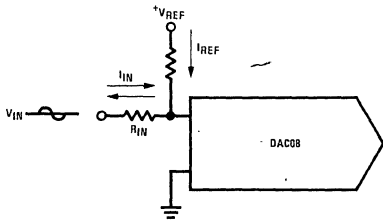
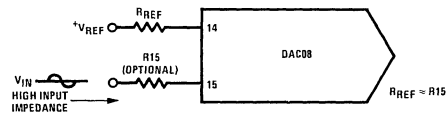


FIGURE 24. Pulsed Reference Operation



(a) $I_{REF} \geq$ peak negative swing of I_{IN}



(b) $+V_{REF}$ must be above peak positive swing of V_{IN}

FIGURE 25. Accommodating Bipolar References

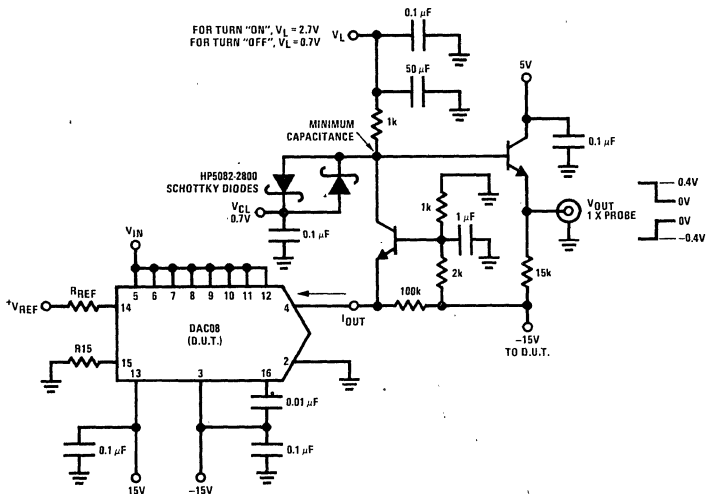
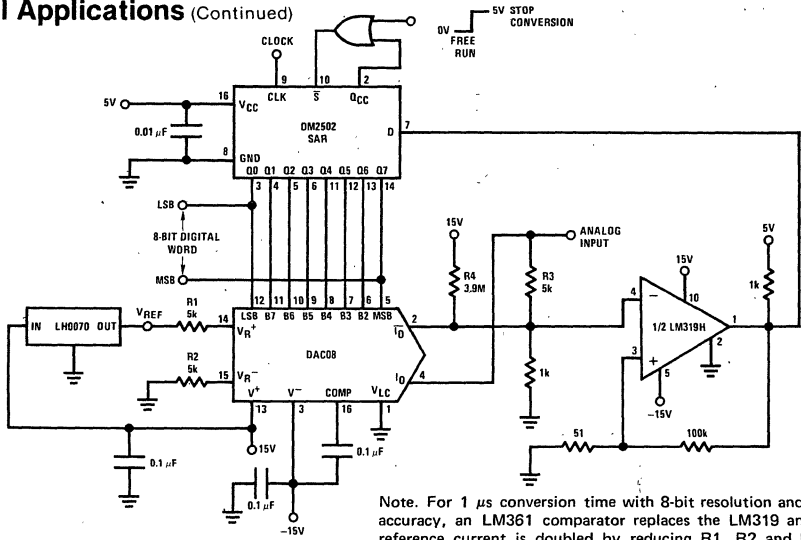


FIGURE 26. Settling Time Measurement

Typical Applications (Continued)



Note. For 1 μs conversion time with 8-bit resolution and 7-bit accuracy, an LM361 comparator replaces the LM319 and the reference current is doubled by reducing R1, R2 and R3 to 2.5 kΩ and R4 to 2 MΩ.

FIGURE 27. A Complete 2 μs Conversion Time, 8-Bit A/D Converter

DAC0808, DAC0807, DAC0806 8-Bit D/A Converters

General Description

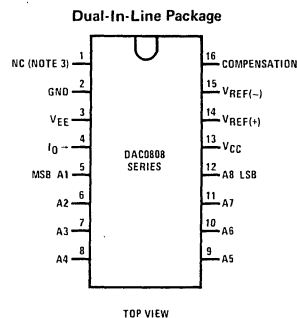
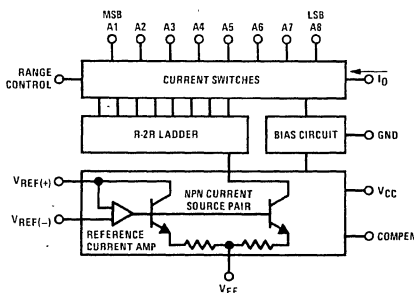
The DAC0808 series is an 8-bit monolithic digital-to-analog converter (DAC) featuring a full scale output current settling time of 150 ns while dissipating only 33 mW with $\pm 5V$ supplies. No reference current (I_{REF}) trimming is required for most applications since the full scale output current is typically ± 1 LSB of $255 I_{REF}/256$. Relative accuracies of better than $\pm 0.19\%$ assure 8-bit monotonicity and linearity while zero level output current of less than $4 \mu A$ provides 8-bit zero accuracy for $I_{REF} \geq 2$ mA. The power supply currents of the DAC0808 series are independent of bit codes, and exhibits essentially constant device characteristics over the entire supply voltage range.

The DAC0808 will interface directly with popular TTL, DTL or CMOS logic levels, and is a direct replacement for the MC1508/MC1408. For higher speed applications, see DAC0800 data sheet.

Features

- Relative accuracy: $\pm 0.19\%$ error maximum (DAC0808)
- Full scale current match: ± 1 LSB typ
- 7 and 6-bit accuracy available (DAC0807, DAC0806)
- Fast settling time: 150 ns typ
- Noninverting digital inputs are TTL and CMOS compatible
- High speed multiplying input slew rate: $8 \text{ mA}/\mu\text{s}$
- Power supply voltage range: $\pm 4.5V$ to $\pm 18V$
- Low power consumption: $33 \text{ mW} \pm 5V$

Block and Connection Diagrams



Typical Application

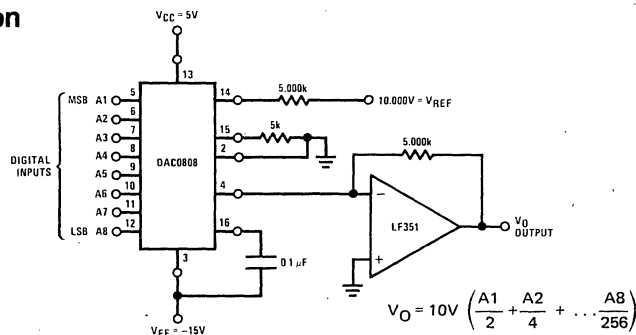


FIGURE 1. $\pm 10V$ Output Digital to Analog Converter

Ordering Information

| ACCURACY | OPERATING TEMPERATURE RANGE | ORDER NUMBERS* | | | | | |
|----------|--|------------------|-----------|------------------|------------------|------------|-----------|
| | | D PACKAGE (D16C) | | J PACKAGE (J16A) | N PACKAGE (N16A) | | |
| 8-bit | $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ | DAC0808LD | LM1508D-8 | DAC0808LCJ | LM1408J-8 | DAC0808LCN | LM1408N-8 |
| 8-bit | $0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}$ | | | DAC0807LCJ | LM1408J-7 | DAC0807LCN | LM1408N-7 |
| 7-bit | $0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}$ | | | DAC0806LCJ | LM1408J-6 | DAC0806LCN | LM1408N-6 |
| 6-bit | $0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}$ | | | | | | |

*Note. Devices may be ordered by using either order number.

Absolute Maximum Ratings (T_A = 25°C unless otherwise noted)

| | | | |
|---|--|--|---------------------------------|
| Power Supply Voltage | | Power Dissipation (Package Limitation) | |
| V _{CC} | +18 V _{DC} | Cavity Package | 1000 mW |
| V _{EE} | -18 V _{DC} | Derate above T _A = 25°C | 6.7 mW/°C |
| Digital Input Voltage, V ₅ -V ₁₂ | -10 V _{DC} to +18 V _{DC} | Operating Temperature Range | |
| Applied Output Voltage, V _O | -11 V _{DC} to +18 V _{DC} | DAC0808L | -55°C ≤ T _A ≤ +125°C |
| Reference Current, I ₁₄ | 5 mA | DAC0808LC Series | 0 ≤ T _A ≤ +75°C |
| Reference Amplifier Inputs, V ₁₄ , V ₁₅ | V _{CC} , V _{EE} | Storage Temperature Range | -65°C to +150°C |

Electrical Characteristics

(V_{CC} = 5V, V_{EE} = -15 V_{DC}, V_{REF}/R₁₄ = 2 mA, DAC0808L: T_A = -55°C to +125°C, DAC0808LC, DAC0807LC, DAC0806LC, T_A = 0°C to +75°C, and all digital inputs at high logic level unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|---|--------|---------------------------|------------------------------------|
| E _r | Relative Accuracy (Error Relative to Full Scale I _O) (Figure 4) | | | | % |
| | DAC0808L (LM1508-8), DAC0808LC (LM1408-8) | | | ±0.19 | % |
| | DAC0807LC (LM1408-7), (Note 1) | | | ±0.39 | % |
| | DAC0806LC (LM1408-6), (Note 1) | | | ±0.78 | % |
| | Settling Time to Within 1/2 LSB (Includes t _{PLH}) | T _A = 25°C (Note 2), (Figure 5) | 150 | | ns |
| t _{PLH} , t _{PHL} | Propagation Delay Time | T _A = 25°C, (Figure 5) | 30 | 100 | ns |
| TC _{IO} | Output Full Scale Current Drift | | ±20 | | ppm/°C |
| MSB | Digital Input Logic Levels (Figure 3) | | | | |
| V _{IH} | High Level, Logic "1" | 2 | | | V _{DC} |
| V _{IL} | Low Level, Logic "0" | | | 0.8 | V _{DC} |
| MSB | Digital Input Current (Figure 3) | | | | |
| | High Level | | 0 | 0.040 | mA |
| | Low Level | | -0.003 | -0.8 | mA |
| I ₁₅ | Reference Input Bias Current (Figure 3) | | -1 | -5 | μA |
| | Output Current Range (Figure 3) | | | | |
| | V _{EE} = -5V | 0 | 2.0 | 2.1 | mA |
| | V _{EE} = -15V, T _A = 25°C | 0 | 2.0 | 4.2 | mA |
| I _O | Output Current (Figure 3) | | | | |
| | V _{REF} = 2.000V, R ₁₄ = 1000Ω, (Figure 3) | 1.9 | 1.99 | 2.1 | mA |
| | Output Current, All Bits Low (Figure 3) | | 0 | 4 | μA |
| | Output Voltage Compliance Pin 1 Grounded, V _{EE} Below -10V | E _r ≤ 0.19%, T _A = 25°C | | -0.55, +0.4 -5.0, +0.4 | V _{DC} V _{DC} |
| SRI _{REF} | Reference Current Slew Rate (Figure 6) | | 8 | | mA/μs |
| | Output Current Power Supply Sensitivity | -5V ≤ V _{EE} ≤ -16.5V | 0.05 | 2.7 | μA/V |
| | Power Supply Current (All Bits Low) (Figure 3) | | | | |
| I _{CC} | | | 2.3 | 22 | mA |
| I _{EE} | | | -4.3 | -13 | mA |
| | Power Supply Voltage Range | T _A = 25°C, (Figure 3) | | | |
| V _{CC} | | 4.5 | 5.0 | 5.5 | V _{DC} |
| V _{EE} | | -4.5 | -15 | -16.5 | V _{DC} |
| | Power Dissipation | | | | |
| | All Bits Low | V _{CC} = 5V, V _{EE} = -5V | 33 | 170 | mW |
| | | V _{CC} = 5V, V _{EE} = -15V | 106 | 305 | mW |
| | All Bits High | V _{CC} = 15V, V _{EE} = -5V | 90 | | mW |
| | | V _{CC} = 15V, V _{EE} = -15V | 160 | | mW |

Note 1: All current switches are tested to guarantee at least 50% of rated current.

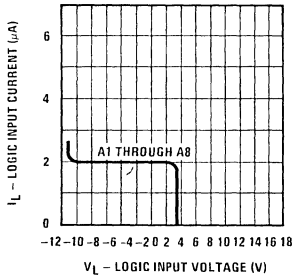
Note 2: All bits switched.

Note 3: Range control is not required.

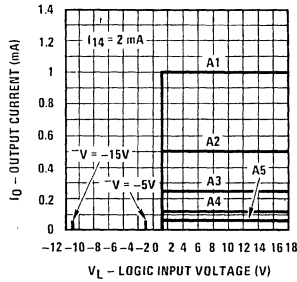
Typical Performance Characteristics

$V_{CC} = 5V$, $V_{EE} = -15V$, $T_A = 25^\circ C$, unless otherwise noted

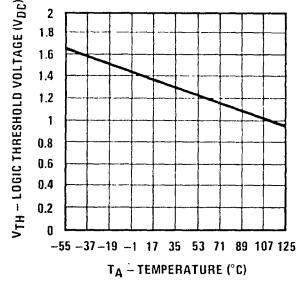
Logic Input Current vs Input Voltage



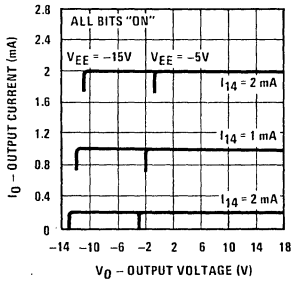
Bit Transfer Characteristics



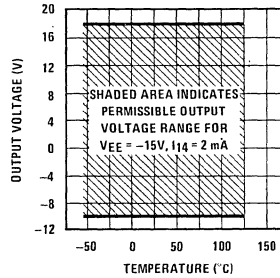
Logic Threshold Voltage vs Temperature



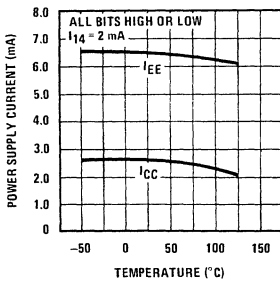
Output Current vs Output Voltage (Output Voltage Compliance)



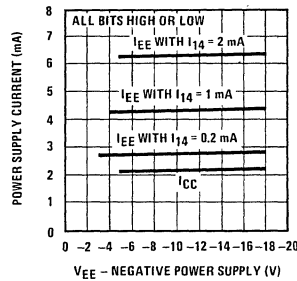
Output Voltage Compliance vs Temperature



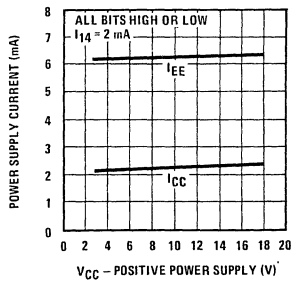
Typical Power Supply Current vs Temperature



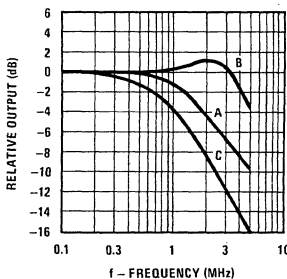
Typical Power Supply Current vs V_EE



Typical Power Supply Current vs V_CC



Reference Input Frequency Response



Unless otherwise specified: $R_{14} = 15\text{ k}\Omega$, $C = 15\text{ pF}$, pin 16 to V_{EE} ; $R_L = 50\Omega$, pin 4 to ground.

Curve A: Large Signal Bandwidth Method of Figure 7, $V_{REF} = 2\text{ Vp-p}$ offset 1 V above ground

Curve B: Small Signal Bandwidth Method of Figure 7, $R_L = 250\Omega$, $V_{REF} = 50\text{ mVp-p}$ offset 200 mV above ground.

Curve C: Large and Small Signal Bandwidth Method of Figure 9 (no op amp, $R_L = 50\Omega$), $R_S = 50\Omega$, $V_{REF} = 2\text{ V}$, $V_S = 100\text{ mVp-p}$ centered at 0V.

DAC0808, DAC0807, DAC0806

88-8

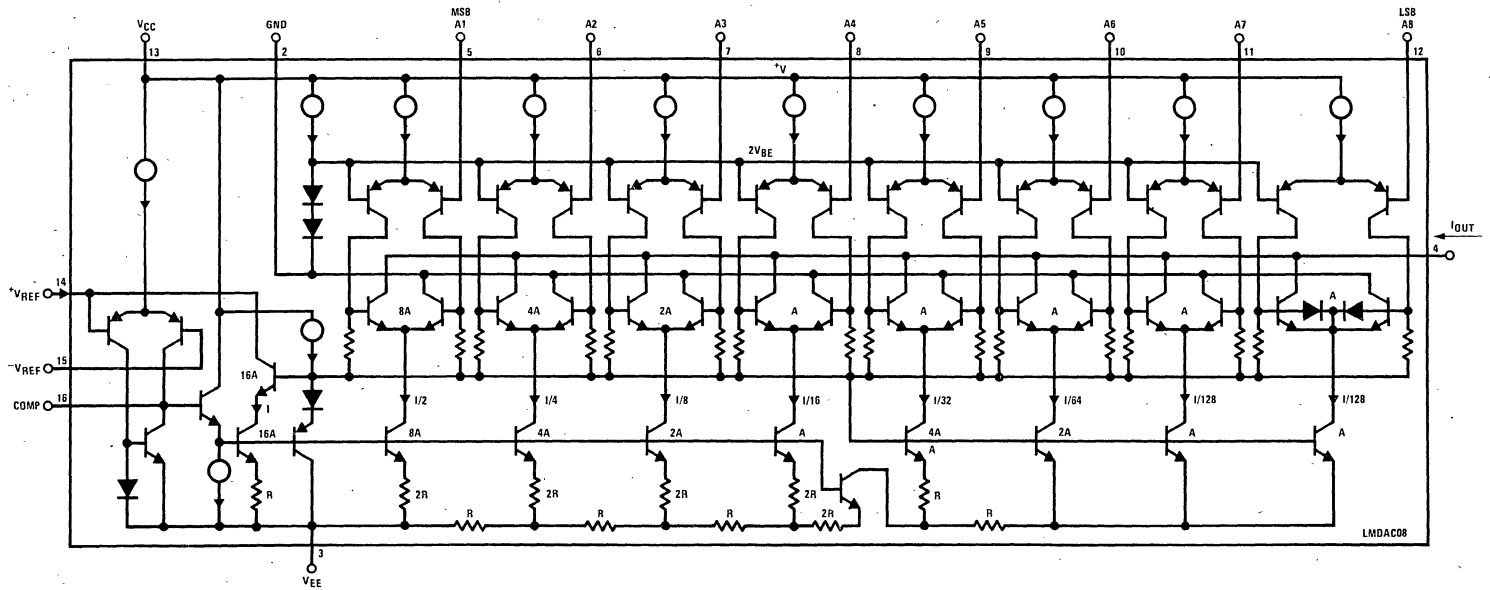
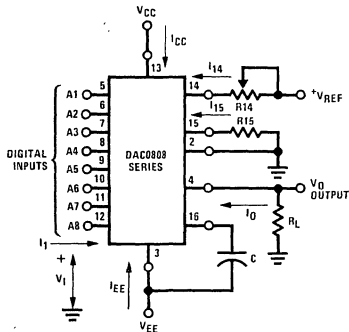


FIGURE 2. Equivalent Circuit of the DAC0808 Series

Test Circuits



V_I and I_1 apply to inputs A1–A8.

The resistor tied to pin 15 is to temperature compensate the bias current and may not be necessary for all applications.

$$I_O = K \left(\frac{A_1}{2} + \frac{A_2}{4} + \frac{A_4}{16} + \frac{A_5}{32} + \frac{A_6}{64} + \frac{A_7}{128} + \frac{A_8}{256} \right)$$

where $K \cong \frac{V_{REF}}{R_{14}}$

and $A_N = "1"$ if A_N is at high level
 $A_N = "0"$ if A_N is at low level

FIGURE 3. Notation Definitions Test Circuit

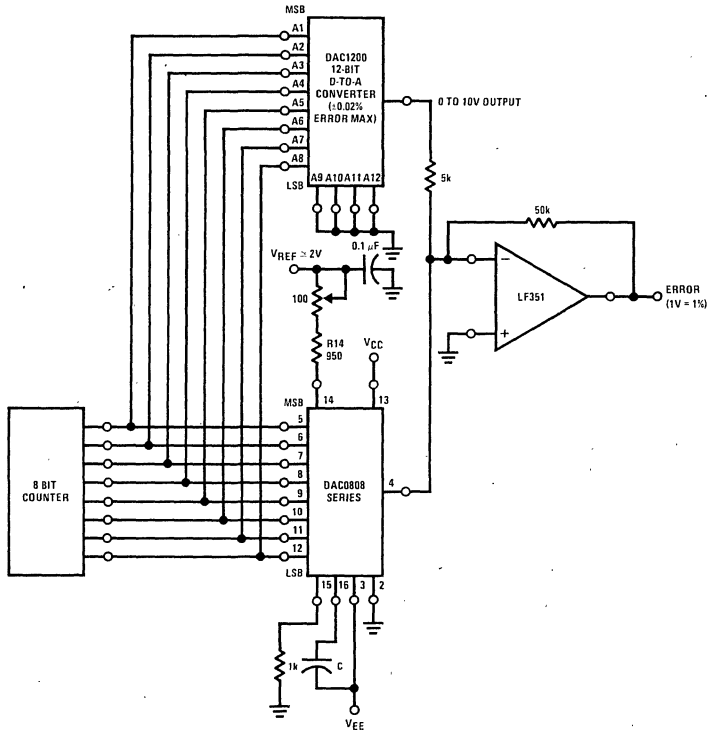


FIGURE 4. Relative Accuracy Test Circuit

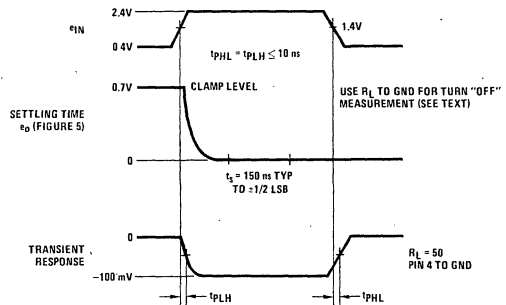
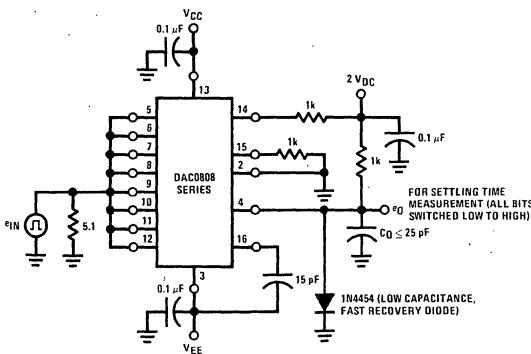


FIGURE 5. Transient Response and Settling Time

Test Circuits (Continued)

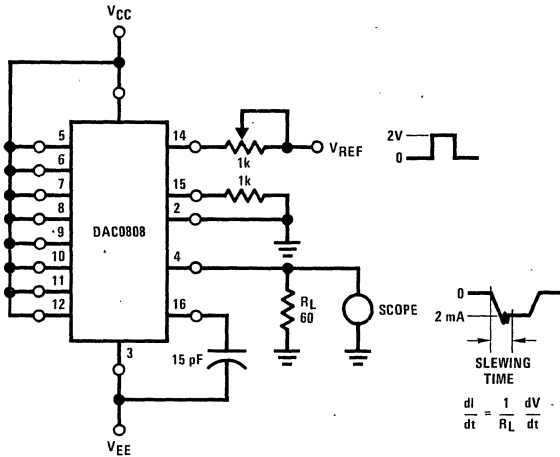


FIGURE 6. Reference Current Slew Rate Measurement

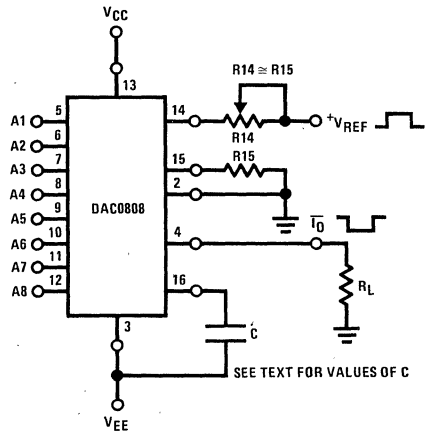


FIGURE 7. Positive VREF

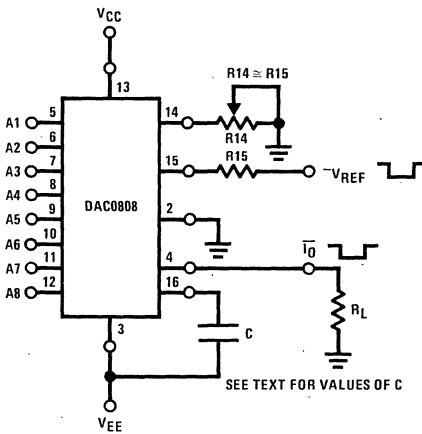


FIGURE 8. Negative VREF

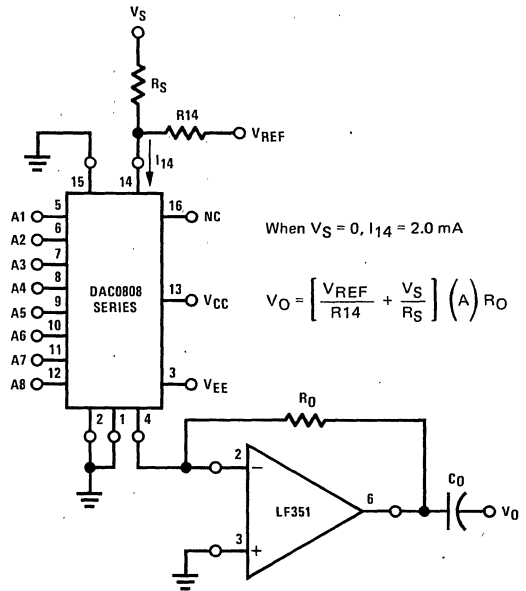


FIGURE 9. Programmable Gain Amplifier or Digital Attenuator Circuit

Application Hints

REFERENCE AMPLIFIER DRIVE AND COMPENSATION

The reference amplifier provides a voltage at pin 14 for converting the reference voltage to a current, and a turn-around circuit or current mirror for feeding the ladder. The reference amplifier input current, I14, must always flow into pin 14, regardless of the set-up method or reference voltage polarity.

Connections for a positive voltage are shown in Figure 7. The reference voltage source supplies the full current

I14. For bipolar reference signals, as in the multiplying mode, R15 can be tied to a negative voltage corresponding to the minimum input level. It is possible to eliminate R15 with only a small sacrifice in accuracy and temperature drift.

The compensation capacitor value must be increased with increases in R14 to maintain proper phase margin; for R14 values of 1, 2.5 and 5 kΩ, minimum capacitor values are 15, 37 and 75 pF. The capacitor may be tied to either VEE or ground, but using VEE increases negative supply rejection.

Application Hints (Continued)

A negative reference voltage may be used if R14 is grounded and the reference voltage is applied to R15 as shown in *Figure 8*. A high input impedance is the main advantage of this method. Compensation involves a capacitor to V_{EE} on pin 16, using the values of the previous paragraph. The negative reference voltage must be at least 4V above the V_{EE} supply. Bipolar input signals may be handled by connecting R14 to a positive reference voltage equal to the peak positive input level at pin 15.

When a DC reference voltage is used, capacitive bypass to ground is recommended. The 5V logic supply is not recommended as a reference voltage. If a well regulated 5V supply which drives logic is to be used as the reference, R14 should be decoupled by connecting it to 5V through another resistor and bypassing the junction of the 2 resistors with 0.1 μ F to ground. For reference voltages greater than 5V, a clamp diode is recommended between pin 14 and ground.

If pin 14 is driven by a high impedance such as a transistor current source, none of the above compensation methods apply and the amplifier must be heavily compensated, decreasing the overall bandwidth.

OUTPUT VOLTAGE RANGE

The voltage on pin 4 is restricted to a range of -0.6 to 0.5 V when $V_{EE} = -5$ V due to the current switching methods employed in the DAC0808.

The negative output voltage compliance of the DAC0808 is extended to -5 V where the negative supply voltage is more negative than -10 V. Using a full-scale current of 1.992 mA and load resistor of 2.5 k Ω between pin 4 and ground will yield a voltage output of 256 levels between 0 and -4.980 V. Floating pin 1 does not affect the converter speed or power dissipation. However, the value of the load resistor determines the switching time due to increased voltage swing. Values of R_L up to 500 Ω do not significantly affect performance, but a 2.5 k Ω load increases worst-case settling time to 1.2 μ s (when all bits are switched ON). Refer to the subsequent text section on Settling Time for more details on output loading.

OUTPUT CURRENT RANGE

The output current maximum rating of 4.2 mA may be used only for negative supply voltages more negative than -7 V, due to the increased voltage drop across the resistors in the reference current amplifier.

ACCURACY

Absolute accuracy is the measure of each output current level with respect to its intended value, and is dependent upon relative accuracy and full-scale current drift. Relative accuracy is the measure of each output current level as a fraction of the full-scale current. The relative accuracy of the DAC0808 is essentially constant with temperature due to the excellent temperature tracking

of the monolithic resistor ladder. The reference current may drift with temperature, causing a change in the absolute accuracy of output current. However, the DAC0808 has a very low full-scale current drift with temperature.

The DAC0808 series is guaranteed accurate to within $\pm 1/2$ LSB at a full-scale output current of 1.992 mA. This corresponds to a reference amplifier output current drive to the ladder network of 2 mA, with the loss of 1 LSB (8 μ A) which is the ladder remainder shunted to ground. The input current to pin 14 has a guaranteed value of between 1.9 and 2.1 mA, allowing some mismatch in the NPN current source pair. The accuracy test circuit is shown in *Figure 4*. The 12-bit converter is calibrated for a full-scale output current of 1.992 mA. This is an optional step since the DAC0808 accuracy is essentially the same between 1.5 and 2.5 mA. Then the DAC0808 circuits' full-scale current is trimmed to the same value with R14 so that a zero value appears at the error amplifier output. The counter is activated and the error band may be displayed on an oscilloscope, detected by comparators, or stored in a peak detector.

Two 8-bit D-to-A converters may not be used to construct a 16-bit accuracy D-to-A converter. 16-bit accuracy implies a total error of $\pm 1/2$ of one part in 65,536, or $\pm 0.00076\%$, which is much more accurate than the $\pm 0.019\%$ specification provided by the DAC0808.

MULTIPLYING ACCURACY

The DAC0808 may be used in the multiplying mode with 8-bit accuracy when the reference current is varied over a range of 256:1. If the reference current in the multiplying mode ranges from 16 μ A to 4 mA, the additional error contributions are less than 1.6 μ A. This is well within 8-bit accuracy when referred to full-scale.

A monotonic converter is one which supplies an increase in current for each increment in the binary word. Typically, the DAC0808 is monotonic for all values of reference current above 0.5 mA. The recommended range for operation with a DC reference current is 0.5 to 4 mA.

SETTLING TIME

The worst-case switching condition occurs when all bits are switched ON, which corresponds to a low-to-high transition for all bits. This time is typically 150 ns for settling to within $\pm 1/2$ LSB, for 8-bit accuracy, and 100 ns to $1/2$ LSB for 7 and 6-bit accuracy. The turn OFF is typically under 100 ns. These times apply when $R_L \leq 500\Omega$ and $C_O \leq 25$ pF.

Extra care must be taken in board layout since this is usually the dominant factor in satisfactory test results when measuring settling time. Short leads, 100 μ F supply bypassing for low frequencies, and minimum scope lead length are all mandatory.



MICRO-DAC™ DAC1000 through DAC1008 10-Bit, μ P Compatible, Double-Buffered D to A Converters

General Description

The DAC1000 through DAC1008 are advanced CMOS/Si-Cr 10-, 9- and 8-bit accurate multiplying DACs which are designed to interface directly with the 8080, 8048, 8085, Z-80 and other popular microprocessors. These DACs appear as a memory location or an I/O port to the μ P and no interfacing logic is needed.

These devices, combined with an external amplifier and voltage reference, can be used as standard D/A converters; and they are very attractive for multiplying applications (such as digitally controlled gain blocks) since their linearity error is essentially independent of the voltage reference. They become equally attractive in audio signal processing equipment as audio gain controls or as programmable attenuators which marry high quality audio signal processing to digitally based systems under microprocessor control.

All of these DACs are double buffered. They can load all 10 bits or two 8-bit bytes and the data format can be either right justified or left justified. The analog section of these DACs is essentially the same as that of the DAC1020.

| Part # | Accuracy (bits) | Pin | Description |
|----------|-----------------|-----|--------------------------|
| DAC1000 | 10 | 24 | Has all logic features |
| DAC1001 | 9 | | |
| DAC1002 | 8 | | |
| *DAC1003 | 10 | 20 | For right-justified data |
| *DAC1004 | 9 | | |
| *DAC1005 | 8 | | |
| DAC1006 | 10 | 20 | For left-justified data |
| DAC1007 | 9 | | |
| DAC1008 | 8 | | |

*Available on special order

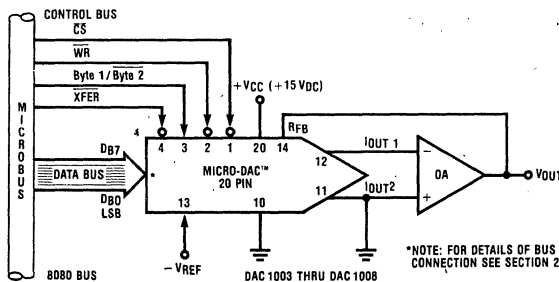
Features

- Uses easy to adjust END POINT specs, NOT BEST STRAIGHT LINE FIT
- Low power consumption
- Direct interface to all popular microprocessors.
- Integrated thin film on CMOS structure
- Double-buffered, single-buffered or flow through digital data inputs.
- Loads two 8-bit bytes or a single 10-bit word.
- Logic inputs which meet T²L voltage level specs (1.4V logic threshold).
- Works with ± 10 V reference — full 4-quadrant multiplication.
- Operates STAND ALONE (without μ P) if desired.
- Available in 0.3" standard 20-pin and 0.6" 24-pin package.

Key Specifications

- Output Current Settling Time 500 ns
- Resolution 10 bits
- Linearity 10, 9, and 8 bits
(guaranteed over temp.)
- Gain Tempo -0.0003% of FS/°C
- Low Power Dissipation (including ladder) 20mW
- Single Power Supply 5 to 15V_{DC}

Typical Application



Absolute Maximum Ratings (Notes 1 & 2)

| | |
|---|-----------------------------------|
| Supply Voltage (V_{CC}) | 17 V_{DC} |
| Voltage at Any Digital Input | V_{CC} to GND |
| Voltage at V_{REF} Input | $\pm 25V$ |
| Storage Temperature Range | $-65^{\circ}C$ to $+150^{\circ}C$ |
| Package Dissipation at $T_A = 25^{\circ}C$ (Note 3) | 875 mW |
| DC Voltage Applied to I_{OUT1} or I_{OUT2} (Note 4) | $-100mV$ to V_{CC} |
| Lead Temperature (soldering, 10 seconds) | $300^{\circ}C$ |

Operating Conditions (Note 2)

| | |
|------------------------------|--|
| Temperature Range | $-40^{\circ}C$ to $+85^{\circ}C$ (part numbers with "LCD" suffix) |
| | $-55^{\circ}C$ to $+125^{\circ}C$ (part numbers with "LD" suffix) |
| | $0^{\circ}C$ to $70^{\circ}C$ (part number with LCN suffix) |
| Range of V_{CC} | 5V to 16 V_{DC} |
| Voltage at Any Digital Input | V_{CC} to GND |

Converter Characteristics $V_{CC} = +15V_{DC}$, $V_{REF} = 10.000V_{DC}$ and $T_A = 25^{\circ}C$ unless otherwise stated

| Parameter | Conditions | Min | Typ | Max | Units |
|---|--|-----|-----------|------|-------------------|
| Resolution | | | | 10 | bits |
| Linearity Error | END POINT ADJUST ONLY (Note 5) | | | | |
| DAC1000, 1003 and 1006 | $T_{MIN} < T_A < T_{MAX}$ (Note 7) | | | 0.05 | % of FSR |
| DAC1001, 1004 and 1007 | $-10V \leq V_{REF} \leq +10V$ (Note 6) | | | 0.1 | % of FSR |
| DAC1002, 1005 and 1008 | (For definition of FSR see Note 8.) | | | 0.2 | % of FSR |
| Monotonicity | $T_{MIN} < T_A < T_{MAX}$ (Note 8) | | | | |
| DAC1000, 1003 and 1006 | | 10 | | | Bit |
| DAC1001, 1004 and 1007 | | 9 | | | Bit |
| DAC1002, 1005 and 1008 | | 8 | | | Bit |
| Gain Error | $-10V \leq V_{REF} \leq +10V$ (Note 6) Using internal R_{FB} resistor | | ± 0.3 | | % of FS |
| Gain Error Tempco | $T_{MIN} < T_A < T_{MAX}$ (Note 7) Using internal R_{FB} resistor | | -0.0003 | | % FS/ $^{\circ}C$ |
| Power Supply Rejection | Digital Input = 1111111111, $V_{CC} = 14V$ to $16V$ | | 0.003 | | % FSR/V |
| Reference Input Resistance (R of R-2R ladder) | | 10 | 15 | 20 | k Ω |
| Output Feedthrough Error | $V_{REF} = 20V_{P,P}$, 100kHz, all digital inputs low | | | | |
| | D Package | | 130 | | mV $_{P,P}$ |
| | N Package | | 90 | | mV $_{P,P}$ |

DC Electrical Characteristics $V_{CC} = +15V_{DC}$, $V_{REF} = 10.000V_{DC}$ and $T_{MIN} \leq T_A \leq T_{MAX}$ (Note 7) unless otherwise stated

| Parameter | Conditions | Min | Typ | Max | Units |
|--|-------------------------|-----|-------|--------|--------------|
| Supply Current Drain (I_{CC}) | | | 0.5 | 2.0 | mA $_{DC}$ |
| Output Leakage Current at I_{OUT1} or I_{OUT2} | | | | 200 | nA |
| Digital Inputs | | | | 0.8 | V_{DC} |
| Low State Threshold | | 2.0 | | | V_{DC} |
| High State Threshold | | | | | V_{DC} |
| Input Current | Digital Inputs $< 0.8V$ | | -40 | -150 | μA_{DC} |
| | Digital Inputs $> 2.0V$ | | 1.0 | 100 | μA_{DC} |

AC Electrical Characteristics $V_{CC} = +15V_{DC}$, $V_{REF} = 10.000V_{DC}$ and $T_A = 25^\circ C$

| Parameter | Conditions | Min | Typ | Max | Units |
|----------------------------|--------------------------------------|-----|-----|-----|-------|
| I_{OUT1} Settling Time | t_S $V_{IL} = 0V$ $V_{IH} = 5V$ | | 500 | | ns |
| Write and XFER Pulse Width | t_W $V_{IL} = 0V$ $V_{IH} = 5V$ | 150 | 30 | | ns |
| Data Setup Time | t_{DS} $V_{IL} = 0V$ $V_{IH} = 5V$ | 0 | | | ns |
| Data Hold Time | t_{DH} $V_{IL} = 0V$ $V_{IH} = 5V$ | 90 | | | ns |
| Control Setup Time | t_{CS} $V_{IL} = 0V$ $V_{IH} = 5V$ | 0 | | | ns |
| Control Hold Time | t_{CH} $V_{IL} = 0V$ $V_{IH} = 5V$ | 10 | 0 | | ns |
| Output Capacitance | | | | | |
| C_{OUT1} | All data inputs high | | 250 | | pF |
| C_{OUT2} | | | 60 | | pF |
| C_{OUT1} | All data inputs low | | 60 | | pF |
| C_{OUT2} | | | 250 | | pF |

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. These specifications are not meant to imply that the devices should be operated at these absolute maximum limits.

Note 2: All voltages are measured with respect to GND, unless otherwise specified.

Note 3: This 875 mW specification applies for all packages. The low intrinsic power dissipation of this part (and the fact that there is no way to significantly modify the power dissipation) removes concern for heat sinking and maximum junction temperature — even at $T_A = +125^\circ C$.

Note 4: For current switching applications, both I_{OUT1} and I_{OUT2} must go to ground or the "Virtual Ground" of an operational amplifier. For every millivolt offset voltage on I_{OUT1} or I_{OUT2} , 0.01% linearity error will be introduced.

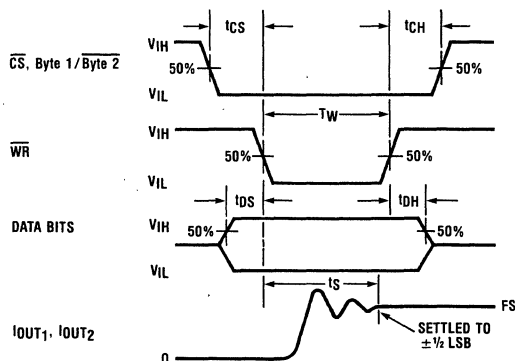
Note 5: This guarantees that after performing a zero and a full scale adjustment (see Application Hints), the plots of all of the 1024 analog voltage outputs will each be within 0.05% ($1/2$ LSB) of a straight line which passes through the endpoints (zero and full scale) of this output voltage data plot. No adjustment iterations are needed by the user to search for the Best Straight Line fit for each DAC. This reduces adjustment costs as compared with Best Straight Line specified DACs.

Note 6: Tested at $V_{REF} = \pm 10V_{DC}$ and $V_{REF} = \pm 1V_{DC}$ with the offset voltage of the external op amp nulled.

Note 7: $T_{MIN} = -40^\circ C$ and $T_{MAX} = 85^\circ C$ for "LCD" suffix parts. $T_{MIN} = -55^\circ C$ and $T_{MAX} = +125^\circ C$ for parts with "LD" suffix designation. $T_{MIN} = 0^\circ C$ and $T_{MAX} = +70^\circ C$ for LCN suffix designation.

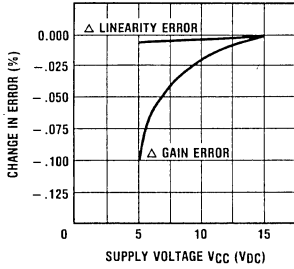
Note 8: The unit "FSR" stands for "full scale range." "Linearity Error" and "Power Supply Rejection" specs are based on this unit to eliminate dependence on a particular V_{REF} value and to indicate the true performance of the part.

Switching Waveforms

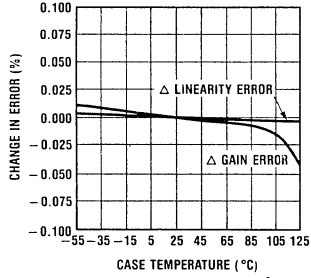


Typical Performance Characteristics

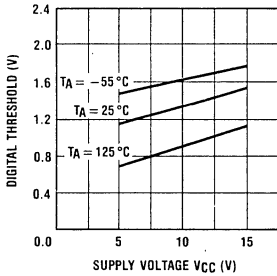
Errors vs Supply Voltage



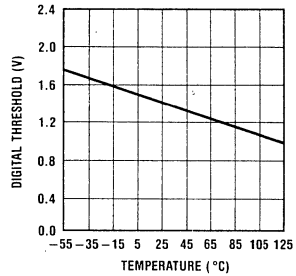
Errors vs Temperature



Digital Input Threshold vs Supply Voltage

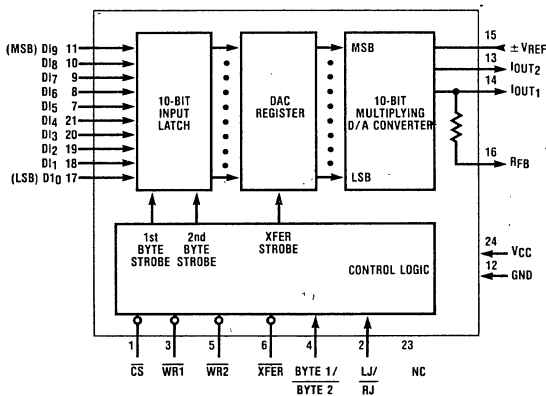


Digital Input Threshold vs Temperature

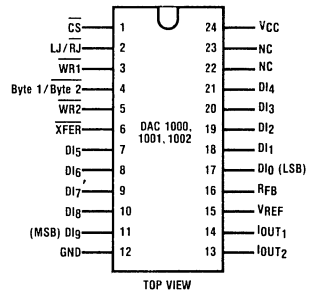


Block and Connection Diagrams

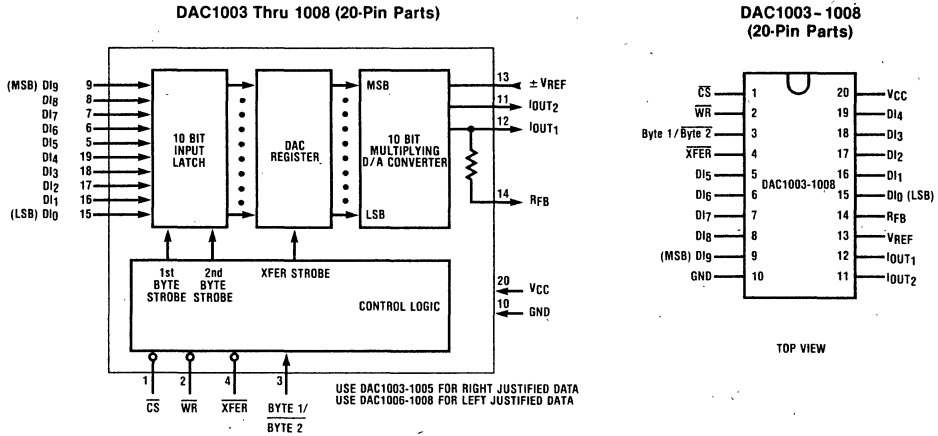
DAC1000/1001/1002 (24-Pin Parts)



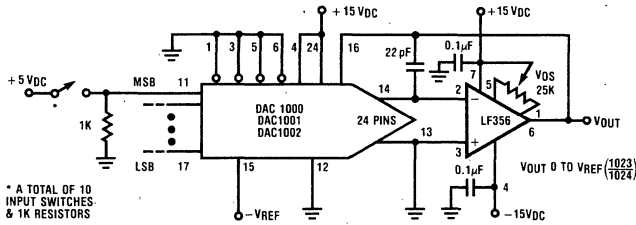
DAC1000-1002 (24-Pin Parts)



Block and Connection Diagrams (cont'd)



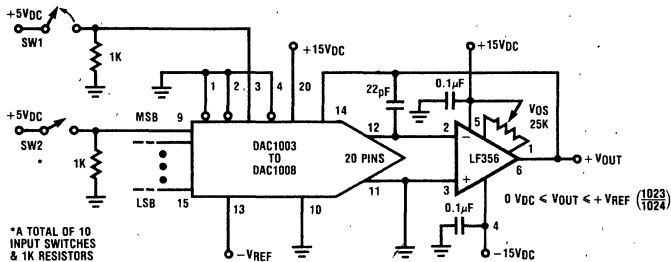
DAC1000/1001/1002 — Simple Hookup for a “Quick Look”



Notes:

1. For $V_{REF} = -10.240V_{DC}$ the output voltage steps are approximately 10 mV each.
2. Operation is set up for flow through — no latching of digital input data.
3. Single point ground is strongly recommended.

DAC1003-1008 — Simple Hookup for a “Quick Look”



Notes:

1. For $V_{REF} = -10.240V_{DC}$ the output voltage steps are approximately 10 mV each.
2. SW1 is a normally closed switch. While SW1 is closed, the DAC register is latched and new data can be loaded into the input latch via the 10 SW2 switches. When SW1 is momentarily opened the new data is transferred from the input latch to the DAC register and is latched when SW1 again closes.

1.0 Definition of Package Pinouts

1.1 Control Signals (All control signals are level actuated.)

CS: Chip Select — active low, it will enable \overline{WR} (DAC1003–1008) or \overline{WR}_1 (DAC1000–1002).

\overline{WR} or \overline{WR}_1 : Write — The active low \overline{WR} (or \overline{WR}_1 — DAC1000–1002) is used to load the digital data bits (DI) into the input latch. The data in the input latch is latched when \overline{WR} (or \overline{WR}_1) is high. The 10-bit input latch is split into two latches; one holds 8 bits and the other holds 2 bits. The Byte1/Byte2 control pin is used to select both input latches when Byte1/Byte2 = 1 or to overwrite the 2-bit input latch when in the low state.

\overline{WR}_2 : Extra Write (DAC1000–1002) — The active low \overline{WR}_2 is used to load the data from the input latch to the DAC register while \overline{XFER} is low. The data in the DAC register is latched when \overline{WR}_2 is high.

Byte1/Byte2: Byte Sequence Control — When this control is high, all ten locations of the input latch are enabled. When low, only two locations of the input latch are enabled and these two locations are overwritten on the second byte write.

\overline{XFER} : Transfer Control Signal, active low — This signal, in combination with others, is used to transfer the 10-bit data which is available in the input latch to the DAC register — see timing diagrams.

LJ/ \overline{RJ} : Left Justify/Right Justify (DAC1000–1002) — When LJ/ \overline{RJ} is high the part is set up for left justified (fractional) data format. (DAC1006–1008 have this done internally.) When LJ/ \overline{RJ} is low, the part is set up for right justified (integer) data. (DAC1003–1005 have this done internally.)

1.2 Other Pin Functions

DI_i (i=0 to 9): Digital Inputs — DI₀ is the least significant bit (LSB) and DI₉ is the most significant bit (MSB).

I_{OUT1}: DAC Current Output 1 — I_{OUT1} is a maximum for a digital input code of all 1s and is zero for a digital input code of all 0s.

I_{OUT2}: DAC Current Output 2 — I_{OUT2} is a constant minus I_{OUT1}, or

$$I_{OUT1} + I_{OUT2} = \frac{1023 V_{REF}}{1024 R}$$

where $R \approx 15 \text{ k}\Omega$.

R_{FB}: Feedback Resistor — This is provided on the IC chip for use as the shunt feedback resistor when an external op amp is used to provide an output voltage for the DAC. This on-chip resistor should always be used (not an external resistor) because it matches the resistors used in the on-chip R-2R ladder and tracks these resistors over temperature.

V_{REF}: Reference Voltage Input — This is the connection for the external precision voltage source which drives the R-2R ladder. V_{REF} can range from –10 to +10 volts. This is also the analog voltage input for a 4-quadrant multiplying DAC application.

V_{CC}: Digital Supply Voltage — This is the power supply pin for the part. V_{CC} can be from +5 to +15V_{DC}. Operation is optimum for +15V. The input threshold voltages are nearly independent of V_{CC}. (See Typical Performance Characteristics and Description in Section 3.0, T²L compatible logic inputs.)

GND: Ground — the ground pin for the part.

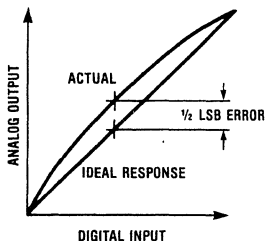
1.3 Definition of Terms

Resolution: Resolution is directly related to the number of switches or bits within the DAC. For example, the DAC1000 has 2¹⁰ or 1024 steps and therefore has 10-bit resolution.

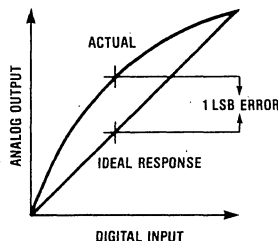
Linearity Error: Linearity error is the maximum deviation from a straight line passing through the endpoints of the DAC transfer characteristic. It is measured after adjusting for zero and full-scale. Linearity error is a parameter intrinsic to the device and cannot be externally adjusted.

National's linearity test (a) and the "best straight line" test (c) used by other suppliers are illustrated below. The "best straight line" (b) requires a special zero and FS adjustment for each part, which is almost impossible for the user to determine. The "end point test" uses a standard zero and FS adjustment procedure and is a much more stringent test for DAC linearity.

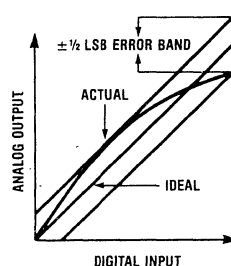
Power Supply Sensitivity: Power supply sensitivity is a measure of the effect of power supply changes on the DAC full-scale output (which is the worst case).



a. End Point Test After Zero and FS Adj.



b. Best Straight Line



c. Shifting FS Adj. to Pass Best Straight Line Test

Settling Time: Settling time is the time required from a code transition until the DAC output reaches within $\pm 1/2$ LSB of the final output value. Full-scale settling time requires a zero to full-scale or full-scale to zero output change.

Full-Scale Error: Full scale error is a measure of the output error between an ideal DAC and the actual device output. Ideally, for the DAC1000 series, full-scale is $V_{REF} - 1$ LSB. For $V_{REF} = -10V$ and unipolar operation, $V_{FULL\text{-}SCALE} = 10.0000V - 9.8\text{mV} = 9.9902V$. Full-scale error is adjustable to zero.

2.0 Double Buffering

These DACs are double-buffered, microprocessor compatible versions of the DAC1020 10-bit multiplying DAC. The addition of the buffers for the digital input data not only allows for storage of this data, but also provides a way to assemble the 10-bit input data word from two write cycles when using an 8-bit data bus. Thus, the next data update for the DAC output can be made with the complete new set of 10-bit data. Further, the double buffering allows many DACs in a system to store current data and also the next data. The updating of the new data for each DAC is also not time critical. When all DACs are updated, a common strobe signal can then be used to cause all DACs to switch to their new analog output levels.

3.0 T²L Compatible Logic Inputs

To guarantee T²L voltage compatibility of the logic inputs, a novel bipolar (NPN) regulator circuit is used. This makes the input logic thresholds equal to the forward drop of two diodes (and also matches the temperature variation) as occurs naturally in T²L. The basic circuit is shown in Figure 1. A curve of digital input threshold as a function of power supply voltage is shown in the Typical Performance Characteristics section.

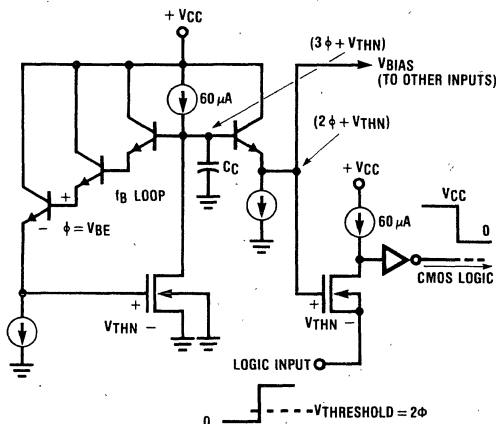


Figure 1. Basic Logic Threshold Loop

4.0 Application Hints

The DC stability of the V_{REF} source is the most important factor to maintain accuracy of the DAC over time and temperature changes. A good single point ground for the analog signals is next in importance.

These MICRO-DAC™ converters are CMOS products and reasonable care should be exercised in handling them prior to final mounting on a PC board. The digital inputs are protected, but permanent damage may occur if the part is subjected to high electrostatic fields. Store unused parts in conductive foam or anti-static rails.

4.1 Power Supply Sequencing & Decoupling

Some IC amplifiers draw excessive current from the Analog inputs to V_{-} when the supplies are first turned on. To prevent damage to the DAC — an external Schottky diode connected from I_{OUT1} or I_{OUT2} to ground may be required to prevent destructive currents in I_{OUT1} or I_{OUT2} . If an LM741 or LF356 is used — these diodes are not required.

The standard power supply decoupling capacitors which are used for the op amp are adequate for the DAC.

4.2 Op Amp Bias Current & Input Leads

The op amp bias current (I_B) CAN CAUSE DC ERRORS. BI-FET™ op amps have very low bias current, and therefore the error introduced is negligible. BI-FET™ op amps are strongly recommended for these DACs.

The distance from the I_{OUT1} pin of the DAC to the inverting input of the op amp should be kept as short as possible to prevent inadvertent noise pickup.

5.0 Analog Applications

The analog section of these DACs uses an R-2R ladder which can be operated both in the current switching mode and in the voltage switching mode.

The major product changes (compared with the DAC1020) have been made in the digital functioning of

the DAC. The analog functioning is reviewed here for completeness. For additional analog applications, such as multipliers, attenuators, digitally controlled amplifiers and low frequency sine wave oscillators, refer to the DAC1020 data sheet. Some basic circuit ideas are presented in this section in addition to complete applications circuits.

5.1 Operation in Current Switching Mode

The analog circuitry, Figure 2, consists of a silicon-chromium (Si-Cr) thin film R-2R ladder which is deposited on the surface oxide of the monolithic chip. As a result, there is no parasitic diode connected to the V_{REF} pin as would exist if diffused resistors were used. The reference voltage input (V_{REF}) can therefore range from $-10V$ to $+10V$.

The digital input code to the DAC simply controls the position of the SPDT current switches, SW0 to SW9. A logical 1 digital input causes the current switch to steer the available ladder current to the I_{OUT1} output pin. These MOS switches operate in the current mode with a small voltage drop across them and can therefore switch currents of either polarity. This is the basis for the 4-quadrant multiplying feature of this DAC.

5.1.1 Providing a Unipolar Output Voltage with the DAC in the Current Switching Mode

A voltage output is provided by making use of an external op amp as a current-to-voltage converter. The idea is to use the internal feedback resistor, R_{FB} , from the output of the op amp to the inverting (-) input. Now, when current is entered at this inverting input, the feedback action of the op amp keeps that input at ground potential. This causes the applied input current to be diverted to the feedback resistor. The output voltage of the op amp is forced to a voltage given by:

$$V_{OUT} = -(I_{OUT1} \times R_{FB})$$

Notice that the sign of the output voltage depends on the direction of current flow through the feedback resistor.

In current switching mode applications, both current output pins (I_{OUT1} and I_{OUT2}) should be operated at $0V_{DC}$. This is accomplished as shown in Figure 3. The capacitor, C_C , is used to compensate for the output capacitance of the DAC and the input capacitance of the op amp. The required feedback resistor, R_{FB} , is available on the chip (one end is internally tied to I_{OUT1})

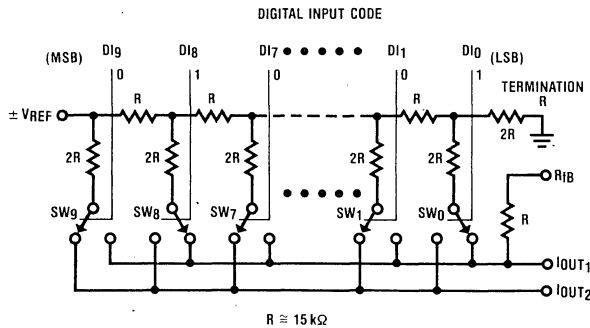


Figure 2. Current Mode Switching

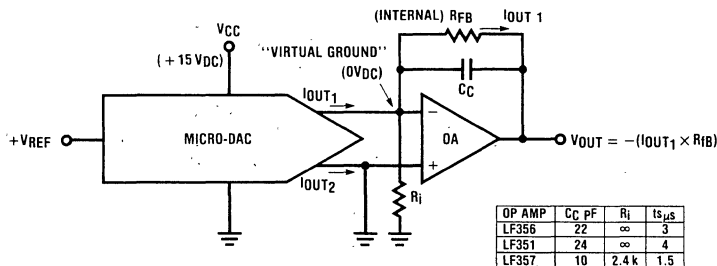


Figure 3. Converting I_{OUT} to V_{OUT}

and must be used since an external resistor will not provide the needed matching and temperature tracking. This circuit can therefore be simplified as shown in Figure 4, where the sign of the reference voltage has been changed to provide a positive output voltage. Note that the output current, I_{OUT1} , now flows through the R_{FB} pin.

5.1.2 Providing a Bipolar Output Voltage with the DAC in the Current Switching Mode

A bipolar output voltage ($\pm V_{OUT}$) is produced by the output op amp when a bipolar input current is provided. This is accomplished by making use of the second output current, I_{OUT2} . It is a characteristic of the R-2R ladder that the sum of both currents will remain constant (for a fixed reference voltage input). This I_{OUT2} output current is used to supply the $-V_{OUT}$ range as shown in Figure 5.

The main idea is that an additional op amp (OA2) causes I_{OUT2} to be entered at the summing junction [the (-) input] of the first op amp. This current direction causes a negative output voltage. The current, I_{OUT1} , extracted from this same summing junction causes a positive output voltage.

When operating in the bipolar mode, if a negative V_{REF} is used the digital input to the DAC should be offset binary code [all zeros = $-V_{REF}$ and all ones = $+V_{REF}$ (511/512)]. A 2's complement μP code can be changed to offset binary by complementing the MSB (with hardware or software). If a positive reference is used the digital input code should be complementary offset binary [all zeros = $+V_{REF}$ and all ones = $-V_{REF}$ (511/512)].

To provide a 0V_{DC} output voltage in bipolar operation requires that an external resistor be added to raise the

magnitude of I_{OUT2} . The zero code is half scale for the DAC and at half scale:

$$I_{OUT1} = \frac{V_{REF}}{R} \left(\frac{512}{1024} \right)$$

and

$$I_{OUT2} = \frac{V_{REF}}{R} \left(\frac{511}{1024} \right)$$

To make these currents equal (to provide a 0V_{DC} output voltage) requires an external resistor, R_{EXT} , connected from the V_{REF} terminal to the I_{OUT2} pin, which will add 1 bit weight of current or:

$$I_{EXT} = \frac{V_{REF}}{R_{EXT}} = \frac{V_{REF}}{R} \left(\frac{1}{1024} \right)$$

or

$$R_{EXT} = R \times 1024$$

where $R = 15k$ (of the R-2R ladder)

$$\text{so } R_{EXT} = 15 M\Omega$$

A low temperature coefficient resistor should be used to improve temperature stability as compared to the performance using a 5% composition resistor. This resistor also skews the output voltage swing from $-V_{REF}$ to $(511/512)V_{REF}$ for a negative V_{REF} or $-(511/512)V_{REF}$ to $+V_{REF}$ for a positive V_{REF} . If R_{EXT} is not used, the output voltage will range from $-(1023/1024)V_{REF}$ to $+(1023/1024)V_{REF}$ (for either polarity of V_{REF}) and will be symmetrical about (but never equal to) 0V.

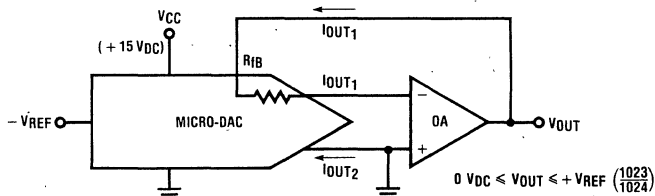


Figure 4. Providing a Unipolar Output Voltage

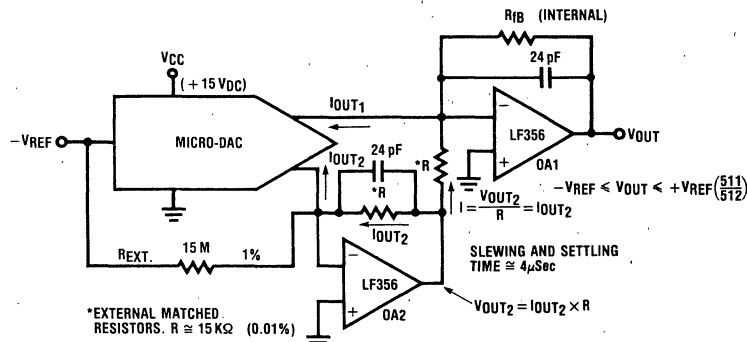


Figure 5. Providing a Bipolar Output Voltage with the DAC in the Current Switching Mode

5.2 Analog Operation in the Voltage Switching Mode

Some useful application circuits result if the R-2R ladder is operated in the voltage switching mode. There are two very important things to remember when using the DAC in the voltage mode. The reference voltage (+V) must always be positive since there are parasitic diodes to ground on the I_{OUT1} pin which would turn on if the reference voltage went negative. To maintain a degradation of linearity less than ±0.005%, keep +V ≤ 3V_{DC} and V_{CC} at least 10V more positive than +V. Figures 6 and 7 show these errors for the voltage switching mode. This operation appears unusual, since a reference voltage (+V) is applied to the I_{OUT1} pin and the voltage output is the V_{REF} pin. This basic idea is shown in Figure 8.

This V_{OUT} range can be scaled by use of a non-inverting gain stage as shown in Figure 9.

Notice that this is unipolar operation since all voltages are positive. A bipolar output voltage can be obtained by using a single op amp as shown in Figure 10. For a digital input code of all zeros, the output voltage from the V_{REF} pin is zero volts. The external op amp now has a single input of +V and is operating with a gain of -1 to this input. The output of the op amp therefore will be at -V for a digital input of all zeros. As the digital code increases, the output voltage at the V_{REF} pin increases.

Notice that the gain of the op amp to voltages which are applied to the (+) input is +2 and the gain to voltages which are applied to the input resistor, R₁, is -1. The output voltage of the op amp depends on both of these inputs and is given by:

$$V_{OUT} = (+V)(-1) + V_{REF}(+2)$$

The output voltage swing can be expanded by adding 2 resistors to Figure 10 as shown in Figure 11. These

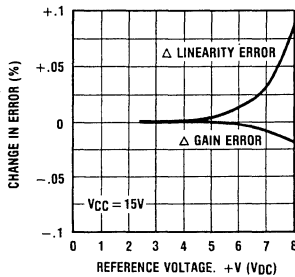


Figure 6.

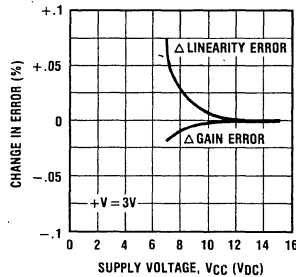


Figure 7.

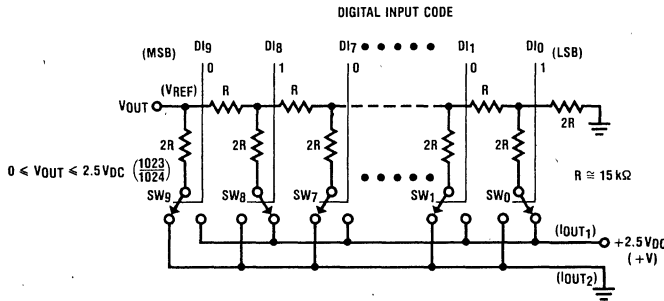


Figure 8. Voltage Mode Switching

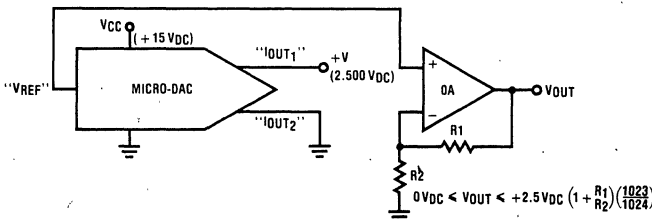


Figure 9. Amplifying the Voltage Mode Output

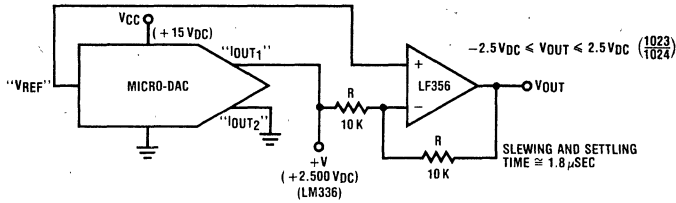


Figure 10. Providing a Bipolar Output Voltage with a Single Op Amp

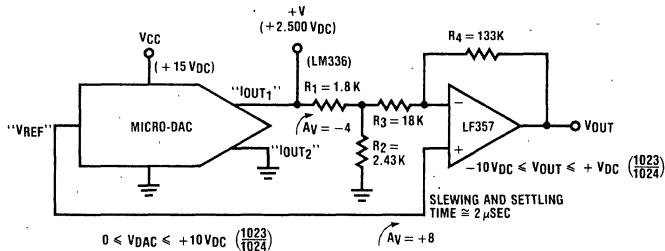


Figure 11. Increasing the Output Voltage Swing

added resistors are used to attenuate the +V voltage. The overall gain, $A_V(-)$, from the +V terminal to the output of the op amp determines the most negative output voltage, $-4(+V)$ (when the V_{REF} voltage at the + input of the op amp is zero) with the component values shown. The complete dynamic range of V_{OUT} is provided by the gain from the (+) input of the op amp. As the voltage at the V_{REF} pin ranges from 0V to +V (1023/1024) the output of the op amp will range from $-10V_{DC}$ to $+10V$ (1023/1024) when using a +V voltage of $+2.500V_{DC}$. The $2.5V_{DC}$ reference voltage can be easily developed by using the LM336 zener which can be biased through the R_{FB} internal resistor, connected to V_{CC} .

5.3 Op Amp V_{OS} Adjust (Zero Adjust) for Current Switching Mode

Proper operation of the ladder requires that all of the 2R legs always go to exactly $0V_{DC}$ (ground). Therefore offset voltage, V_{OS} , of the external op amp cannot be tolerated as every millivolt of V_{OS} will introduce 0.01% of added linearity error. At first this seems unusually sensitive, until it becomes clear the 1mV is 0.01% of the 10V reference! High resolution converters of high accuracy require attention to every detail in an application to achieve the available performance which is inherent in the part. To prevent this source of error, the V_{OS} of the op amp has to be initially zeroed. This is the "zero adjust" of the DAC calibration sequence and should be done first.

If the V_{OS} is to be adjusted there are a few points to consider. Note that no "dc balancing" resistance should be used in the grounded positive input lead of the op amp. This resistance and the input current of the op amp can also create errors. The low input biasing current of the Bi-FET™ op amps makes them ideal for use in DAC current to voltage applications. The V_{OS} of the op amp should be adjusted with a digital input of all zeros to force $I_{OUT} = 0mA$. A $1K\Omega$ resistor can be temporarily connected from the inverting input to ground to provide a dc gain of approximately 15 to the V_{OS} of the op amp and make the zeroing easier to sense.

5.4 Full-Scale Adjust

The full-scale adjust procedure depends on the application circuit and whether the DAC is operated in the current switching mode or in the voltage switching mode. Techniques are given below for all of the possible application circuits.

5.4.1 Current Switching with Unipolar Output Voltage

After doing a "zero adjust," set all of the digital input levels HIGH and adjust the magnitude of V_{REF} for

$$V_{OUT} = -(\text{ideal } V_{REF}) \frac{1023}{1024}$$

This completes the DAC calibration.

5.4.2 Current Switching with Bipolar Output Voltage

The circuit of Figure 12 shows the 4 adjustments which are needed. The first step is to set all of the digital inputs HIGH (to force $I_{OUT2} = 0$) and then trim "zero adj. 2" for an output voltage at V_{O2} (of OA2) of zero ± 1 mV. Then reset all of the bits to a LOW state. Now trim "zero adj. 1" for an output voltage at V_{OUT} (of OA1) of zero ± 1 mV.

The details of the FS trim depend upon the polarity of the V_{REF} input voltage. For a negative reference voltage an offset binary decoding results. Set the digital inputs all HIGH ($I_{OUT1} = \text{max}$) and trim "+ FS Adj." for a $V_{OUT} = +|(\text{ideal } V_{REF})|(511/512)$. Then set all the digital inputs LOW and trim "- FS Adj." for a $V_{OUT} = -|(\text{ideal } V_{REF})|$. For a positive reference voltage a complementary offset binary decoding results. To adjust, set all digital inputs high and adjust "- FS Adj." for an output voltage of $-V_{REF}(511/512)$. Then set all the digital inputs LOW and adjust "+ FS Adj." for an output voltage of $+(ideal V_{REF})$.

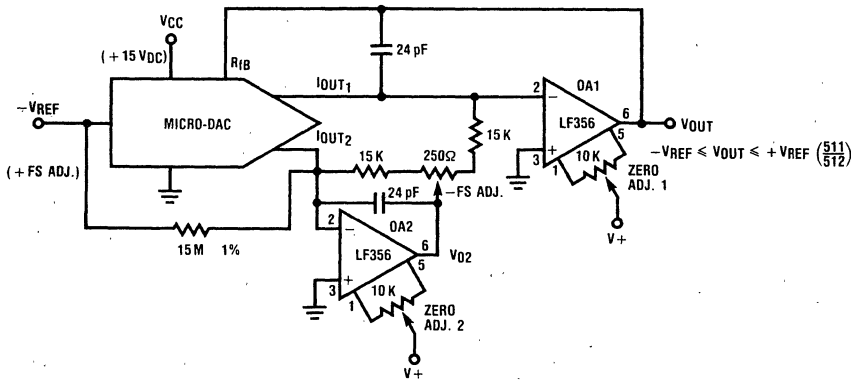


Figure 12. Full Scale Adjust — Current Switching with Bipolar Output Voltage

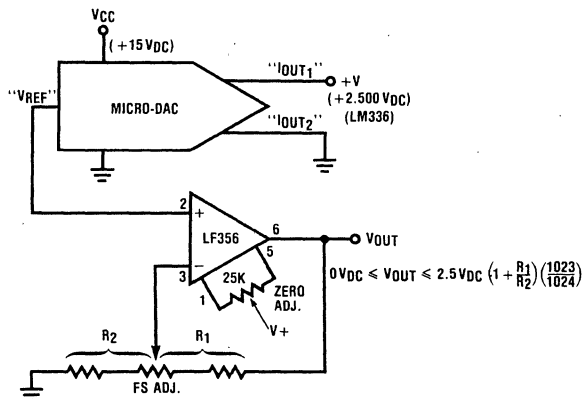


Figure 13. Full Scale Adjust — Unipolar Output Voltage

5.4.3 Voltage Switching with a Unipolar Output Voltage

Refer to the circuit of Figure 13 and set all digital inputs LOW. Trim the "zero adj." for $V_{OUT} = 0V_{DC} \pm 1$ mV. Then set all digital inputs HIGH and trim the "FS Adj." for:

$$V_{OUT} = (+V) \left(1 + \frac{R_1}{R_2} \right) \frac{1023}{1024}$$

5.4.4 Voltage Switching with a Bipolar Output Voltage

Refer to Figure 14 and set all digital inputs LOW. Trim the "- FS Adj." for $V_{OUT} = -2.5V_{DC}$. Then set all digital inputs HIGH and trim the "+ FS Adj." for $V_{OUT} = +2.5(511/512)V_{DC}$. Test the zero by setting the MS digital input HIGH and all the rest LOW. Adjust V_{OS} of amp #3, if necessary, and recheck the full-scale values.

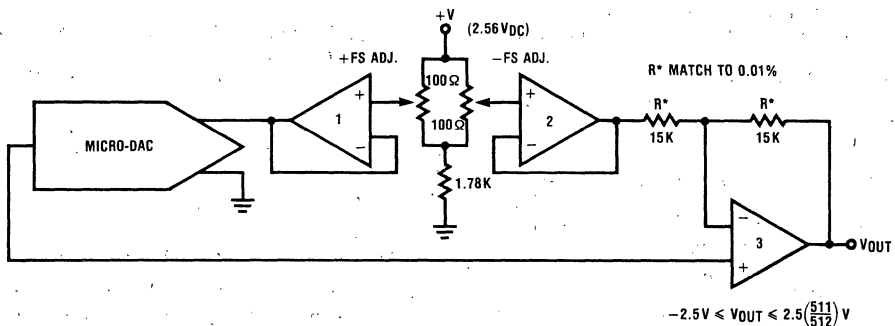


Figure 14. Voltage Switching with a Bipolar Output Voltage

6.0 Digital Control Description

The DAC1000 series of products can be used in a wide variety of operating modes. Most of the options are shown in Table 1. Also shown in this table are the section numbers of this data sheet where each of the operating modes is discussed. For example, if your main interest is interfacing to a μP with an 8-bit data bus you will be directed to Section 6.1.0.

The first consideration is "will the DAC be interfaced to a μP with an 8-bit or a 16-bit data bus or used in the stand-alone mode?" For the 8-bit data bus, a second selection is made on how the 2nd digital data buffer (the DAC Latch) is updated by a transfer from the 1st digital data buffer (the Input Latch). Three options are provided: 1) an automatic transfer when the 2nd data byte is written to the DAC, 2) a transfer which is under the control of the μP and can include more than one DAC in a simultaneous transfer, or 3) a transfer which is under the control of external logic. Further, the data format can be either left justified or right justified.

When interfacing to a μP with a 16-bit data bus only two selections are available: 1) operating the DAC with a single digital data buffer (the transfer of one DAC does not have to be synchronized with any other DACs in the system), or 2) operating with a double digital data buffer

for simultaneous transfer, or updating, of more than one DAC.

For operating without a μP in the stand alone mode, three options are provided: 1) using only a single digital data buffer, 2) using both digital data buffers — "double buffered," or 3) allowing the input digital data to "flow through" to provide the analog output without the use of any data latches.

To reduce the required reading, only the applicable sections of 6.1 through 6.4 need be considered.

6.1 Interfacing to an 8-Bit Data Bus

Transferring 10 bits of data over an 8-bit bus requires two write cycles and provides four possible combinations which depend upon two basic data format and protocol decisions:

1. Is the data to be left justified (considered as fractional binary data with the binary point to the left) or right justified (considered as binary weighted data with the binary point to the right)?
2. Which byte will be transferred first, the most significant byte (MS byte) or the least significant byte (LS byte)?

Table 1.

| Operating Mode → | Automatic Transfer | | | μP Control Transfer | | | External Transfer | | |
|-------------------------|--------------------|---------------------|---------------------|--------------------------------|---------------------|---------------------|-------------------|---------------------|---------------------|
| | Section | Figure No. (24-Pin) | Figure No. (20-Pin) | Section | Figure No. (24-Pin) | Figure No. (20-Pin) | Section | Figure No. (24-Pin) | Figure No. (20-Pin) |
| 8-Bit Data Bus (6.1.0) | | | | | | | | | |
| Right Justified (6.1.2) | 6.2.1 | 16 | 18 | 6.2.2 | 16 | 18 | 6.2.3 | 16 | 18 |
| Left Justified (6.1.3) | 6.2.1 | 17 | 19 | 6.2.2 | 17 | 19 | 6.2.3 | 17 | 19 |
| 16-Bit Data Bus (6.3.0) | Single Buffered | | | Double Buffered | | | Flow Through | | |
| | 6.3.1 | 20 | 21 | 6.3.2 | 20 | 21 | Not Applicable | | |
| Stand Alone (6.4.0) | Single Buffered | | | Double Buffered | | | Flow Through | | |
| | 6.4.1 | 20 | 21 | 6.4.2 | 20 | 21 | 6.4.3 | 20 | NA |

These data possibilities are shown in Figure 15. Note that the justification of data depends on how the 10-bit data word is located within the 16-bit data source (CPU) register. In either case, there is a surplus of 6 bits and these are shown as "don't care" terms ("X") in this figure.

All of these DACs load 10 bits on the 1st write cycle. A particular set of 2 bits is then overwritten on the 2nd write cycle, depending on the justification of the data. This requires the 1st write cycle to contain the LS or L0 Byte data group for all right justified data options. For all left justified data options, the 1st write cycle must contain the MS or Hi Byte data group.

6.1.1 Providing for Optional Data Format

The DAC1000/1/2 (24-pin parts) can be used for either data formatting by tying the LJ/RJ pin either high or low, respectively. A simplified logic diagram which shows the external connections to the data bus and the internal functions of both of the data buffer registers (Input Latch and DAC Register) is shown in Figure 16 for the right justified data operation. Figure 17 is for left justified data.

6.1.2 For Right Justified Data

For applications which require right justified data, DAC1003-1005 (20-pin parts) can be used. A simplified logic diagram which shows the external connections to

the data bus and the internal functions of both of the data buffer registers (Input Latch and DAC Register) is shown in Figure 18. These parts require the LS or L0 Byte data group to be transferred on the 1st write cycle.

6.1.3 For Left Justified Data

For applications which require left justified data, DAC1006-1008 (20-pin parts) can be used. A simplified logic diagram which shows the external connections to the data bus and the internal functions of both of the data buffer registers (Input Latch and DAC Register) is shown in Figure 19. These parts require the MS or Hi Byte data group to be transferred on the 1st write cycle.

6.2 Controlling Data Transfer for an 8-Bit Data Bus

Three operating modes are possible for controlling the transfer of data from the Input Latch to the DAC Register, where it will update the analog output voltage. The simplest is the automatic transfer mode, which causes the data transfer to occur at the time of the 2nd write cycle. This is recommended when the exact timing of the changes of the DAC analog output are not critical. This typically happens where each DAC is operating individually in a system and the analog updating of one DAC is not required to be synchronized to any other DAC. For synchronized DAC updating, two options are provided: μ P control via a common XFER strobe or external update timing control via an external strobe. The details of these options are now shown.

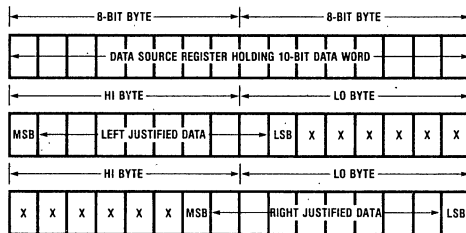


Figure 15. Fitting a 10-Bit Data Word into 16 Available Bit Locations

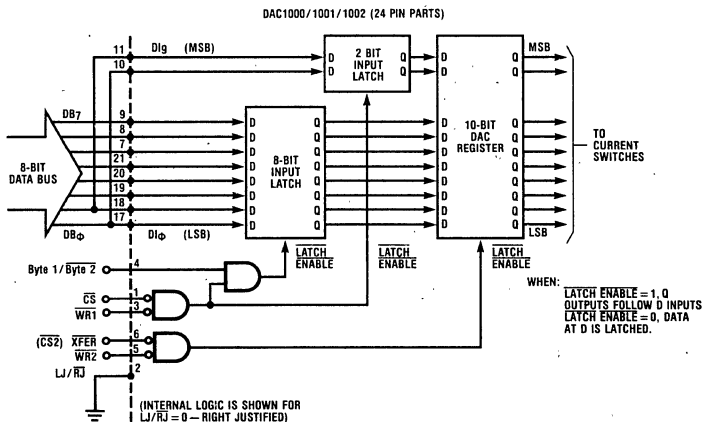


Figure 16. Input Connections and Controls for DAC1000-1002 Right Justified Data Option

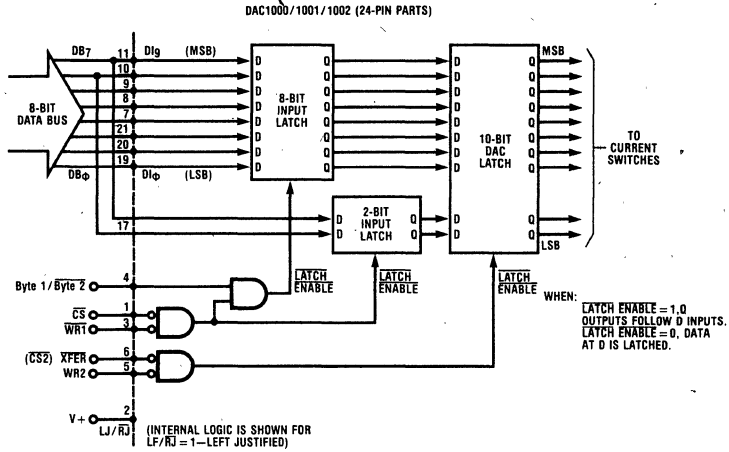


Figure 17. Input Connections and Controls for DAC1000-1002 Left Justified Data Option

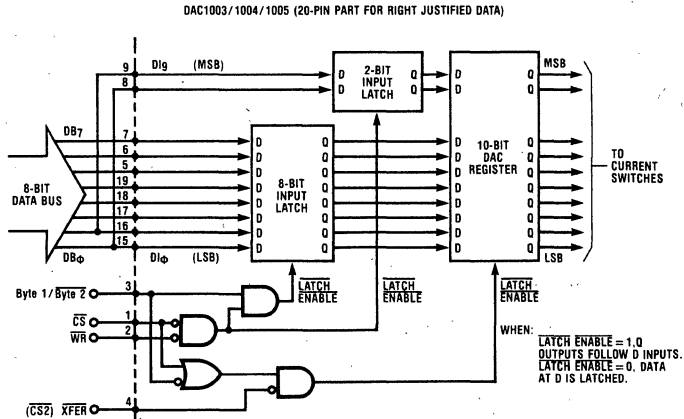


Figure 18. Input Connections and Controls for DAC1003-1005 Right Justified Data Option

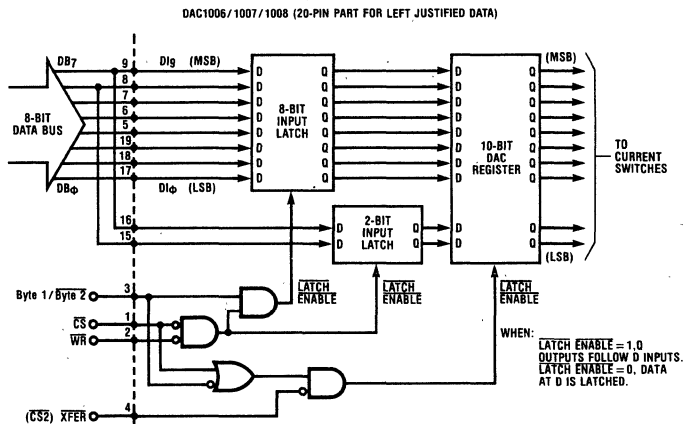
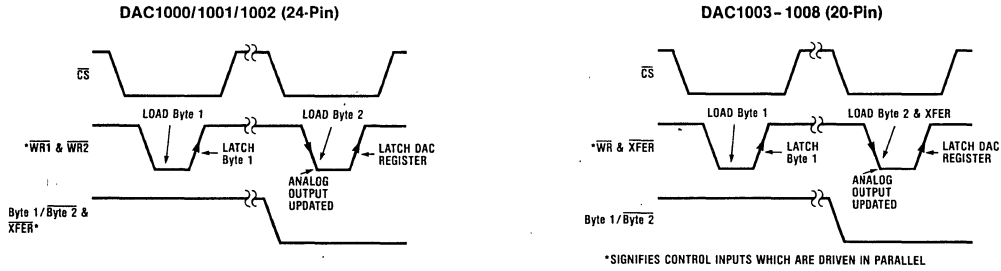


Figure 19. Input Connections and Controls for DAC1006-1008 Left Justified Data Option

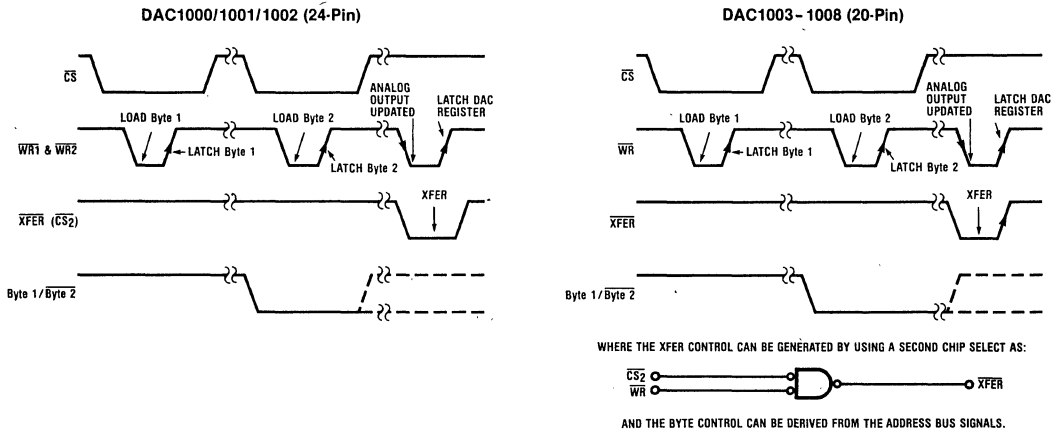
6.2.1 Automatic Transfer

This makes use of a double byte (double precision) write. The first byte (8 bits) is strobed into the input latch and the second byte causes a simultaneous strobe of the two remaining bits into the input latch and also the transfer of the complete 10-bit word from the input latch to the DAC register. This is shown in the following timing diagrams; the point in time where the analog output is updated is also indicated on these diagrams.



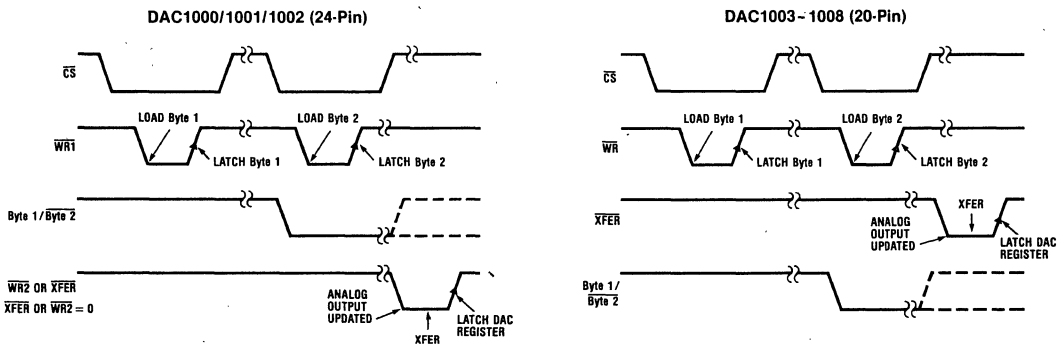
6.2.2 Transfer Using μ P Write Strobe

The input latch is loaded with the first two write strobes. The \overline{XFER} signal is provided by external logic, as shown below, to cause the transfer to be accomplished on a third write strobe. This is shown in the following diagrams:



6.2.3 Transfer Using an External Strobe

This is similar to the previous operation except the \overline{XFER} signal is not provided by the μ P. The timing diagram for this is:



6.3 Interfacing to a 16-Bit Data Bus

The interface to a 16-bit data bus is easily handled by connecting to 10 of the available bus lines. This allows a wiring selected right justified or left justified data format. This is shown in the connection diagrams of Figures 20 and 21, where the use of DB6 to DB15 gives left justified data operation and DB0 to DB9 provides for right justified data. Note that any part number can be used and the Byte1/Byte2 control should be wired Hi.

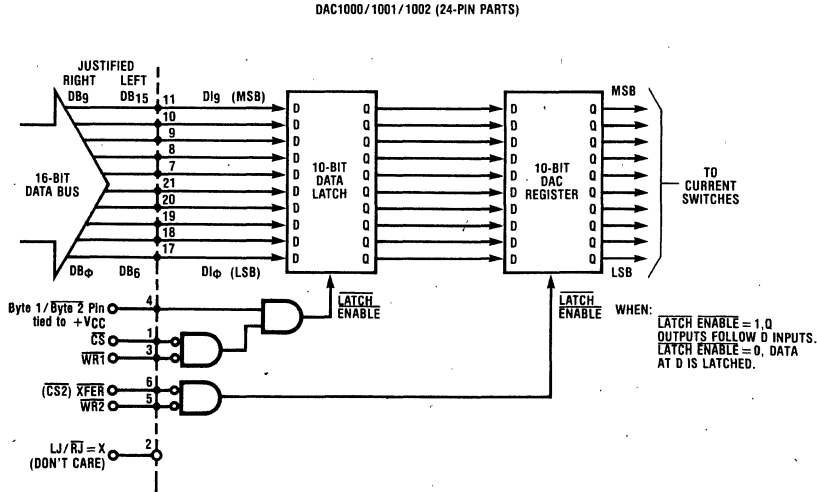


Figure 20. Input Connections and Logic for DAC1000-1002 with 16-Bit Data Bus

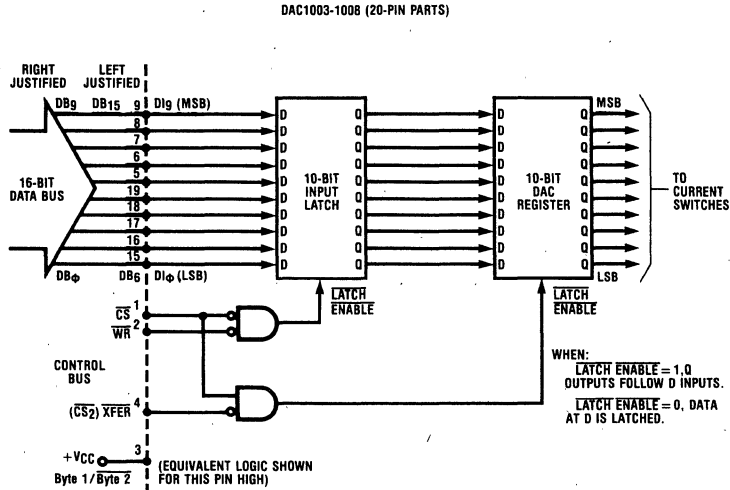
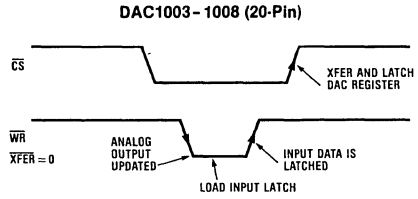
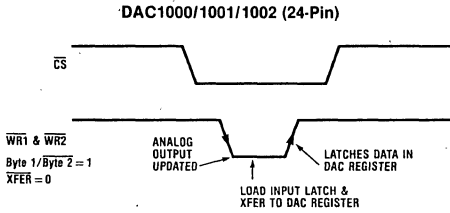


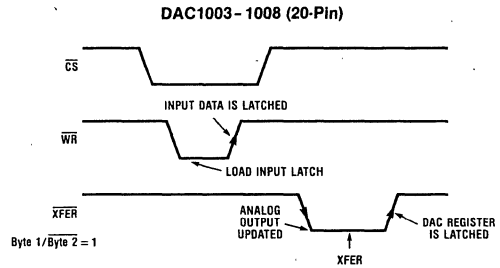
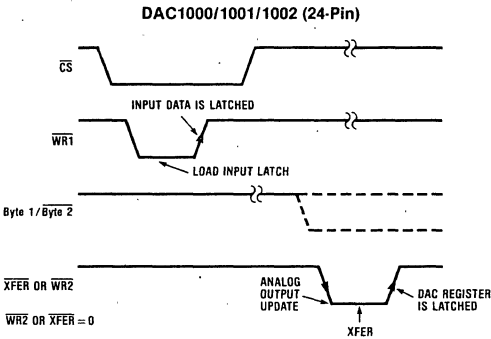
Figure 21. Input Connections and Logic for DAC1003-1008 with 16-Bit Data Bus

Three operating modes are possible: flow through, single buffered, or double buffered. The timing diagrams for these are shown below:

6.3.1 Single Buffered



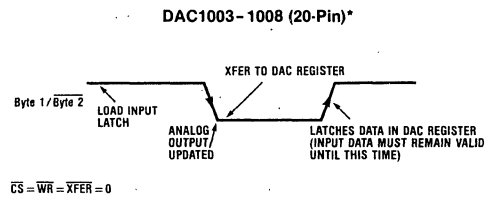
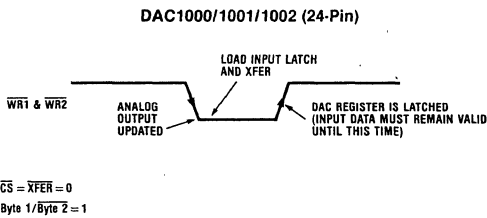
6.3.2 Double Buffered



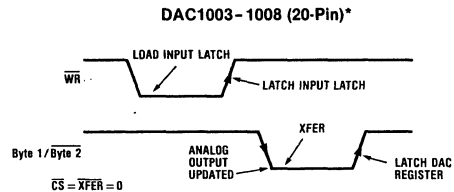
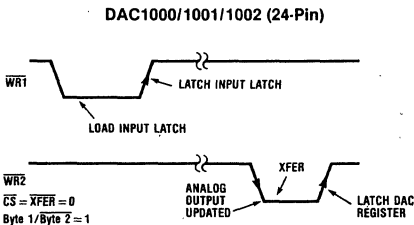
6.4 Stand Alone Operation

For applications for a DAC which are not under μ P control (stand alone) there are two basic operating modes, single buffered and double buffered. The timing diagrams for these are shown below:

6.4.1 Single Buffered



6.4.2 Double Buffered



*For a connection diagram of this operating mode use Figure 18 for the Logic and Figure 21 for the Data Input connections

6.4.3 Flow Through

This operating mode causes the 10-bit input word to directly create the DAC output without any latching involved.

DAC1000/1001/1002 (24-Pin)

$\overline{WR1} = \overline{WR2} = \overline{CS} = \overline{XFER} = 0$
 Byte 1/Byte 2 = 1

7.0 Microprocessor Interface

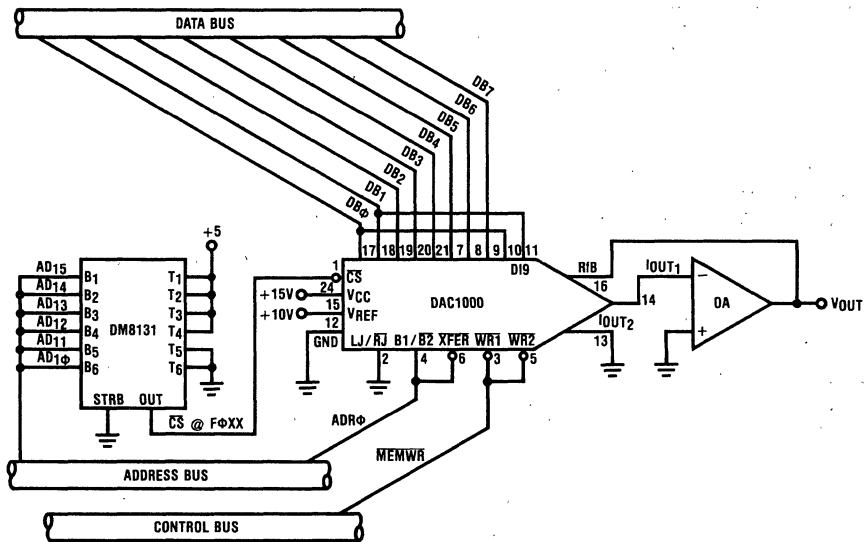
The logic functions of the DAC1000 family have been oriented towards an ease of interface with all popular μ Ps. The following sections discuss in detail a few useful interface schemes.

7.1 DAC1000/1/2 to INS8080A Interface

Figure 22 illustrates the simplicity of interfacing the DAC1000 to an INS8080A based microprocessor

system. The circuit will perform an automatic transfer of the 10 bits of output data from the CPU to the DAC register as outlined in Section 6.2.1, "Controlling Data Transfer for an 8-Bit Data Bus."

Since a double byte write is necessary to control the DAC with the INS8080A, a possible instruction to achieve this is a PUSH of a register pair onto a "stack" in memory. The 16-bit register pair word will contain the 10 bits of the eventual DAC input data in the proper



NOTE: DOUBLE BYTE STORES CAN BE USED.
 e.g. THE INSTRUCTION SHLD Fφφ1 STORES THE L
 REG INTO B1 AND THE H REG INTO B2 AND
 TRANSFERS THE RESULT TO THE DAC REGISTER.
 THE OPERAND OF THE SHLD INSTRUCTION MUST
 BE AN ODD ADDRESS FOR PROPER TRANSFER.

Figure 22. Interfacing the DAC1000 to the INS8080A CPU Group

sequence to conform to both the requirements of the DAC (with regard to right or left justified data) and the implementation of the PUSH instruction which will output the higher order byte of the register pair (i.e., register B of the BC pair) first. The DAC will actually appear as a two-byte "stack" in memory to the CPU. The auto-decrementing of the stack pointer during a PUSH allows using address bit 0 of the stack pointer as the Byte1/Byte2 and XFER strobes if bit 0 of the stack pointer address - 1, (SP - 1), is a "1" as presented to the DAC. Additional address decoding by the DM8131 will generate a unique DAC chip select (CS) and synchronize this CS to the two memory write strobes of the PUSH instruction.

To reset the stack pointer so new data may be output to the same DAC, a POP instruction followed by instructions to insure that proper data is in the DAC data register pair before it is "PUSHED" to the DAC should be executed, as the POP instruction will arbitrarily alter the contents of a register pair.

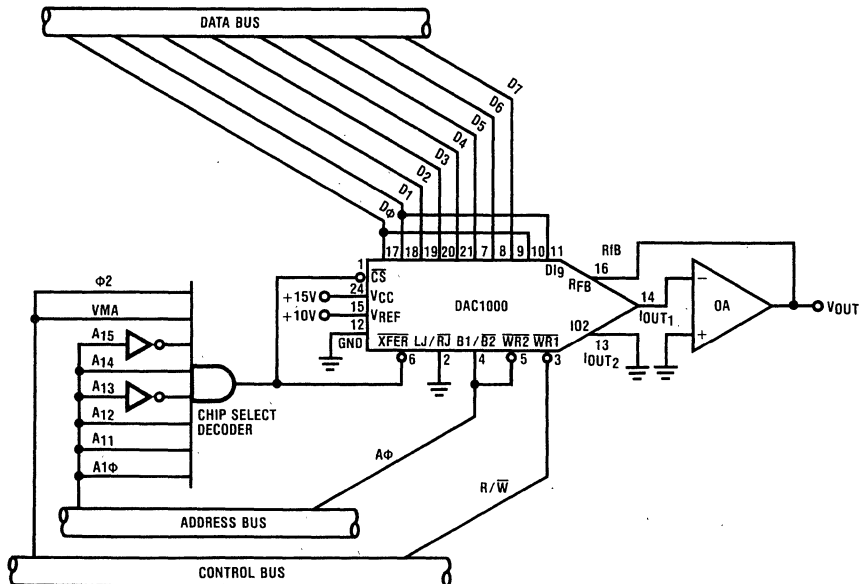
Another double byte write instruction is Store H and L Direct (SHLD), where the HL register pair would temporarily contain the DAC data and the two sequential addresses for the DAC are specified by the instruction op code. The auto incrementing of the DAC address by the SHLD instruction permits the same

simple scheme of using address bit 0 to generate the byte number and transfer strobes.

7.2 DAC1000 to M6800 Direct Interface

As in the INS8080A case, it is very simple to directly interface the DAC1000 to an M6800 system. Figure 23 illustrates such an interface assuming a right justified data structure. Except for address decoding, no external logic is necessary. The DAC1000 appears as two memory locations in the 6800 memory space. By using just an 8-input NAND gate and two inverters we have (arbitrarily) chosen these HEX addresses to be 5C00 and 5C01. Note, however, that any HEX address of the form 5CXX will also be decoded. This can easily be avoided by designing a more definitive address decoding scheme. Control lines O2 and VMA are included to insure stability of address and data lines before the DAC inputs are enabled.

In a normal operating mode the MPU would "store" two 8-bit bytes of right justified data into the DAC input latches: LOW byte first at location 5C01 and HIGH byte next at location 5C00. Upon storing the second byte, the 10-bit word is automatically transferred to the DAC register, therefore obtaining the desired analog output. This output will be maintained until the next two bytes of data are loaded into the DAC under MPU control.



NOTE: TWO SINGLE BYTE STORES (e.g. STA A, STA B) MUST BE USED SINCE A DOUBLE BYTE STORE (e.g. STX) WOULD TRANSFER AN INCOMPLETE WORD.

Figure 23. DAC1000 to MC6800 MPU Interface

7.3 DAC1000 to MC6820/1 PIA Interface

In Figure 24 the DAC1000 is interfaced to an M6800 system through an MC6820/1 Peripheral Interface Adapter (PIA). In this case the \overline{CS} pin of the DAC is grounded since the PIA is already mapped in the 6800 system memory space and no decoding is necessary. Furthermore, by using both Ports A and B of the PIA the 10-bit data transfer, assumed right justified again in two 8-bit bytes, is greatly simplified. The HIGH byte is loaded into Output Register A (ORA) of the PIA, and the LOW byte is loaded into ORB. The 10-bit data transfer to the DAC and the corresponding analog output change occur simultaneously upon CB2 going LOW under program control. The 10-bit data word in the DAC

register will be latched (and hence V_{OUT} will be fixed) when CB2 is brought back HIGH.

If both output ports of the PIA are not available, it is possible to interface the DAC1000 through a single port without much effort. However, additional logic at the CB2 (or CA2) lines or access to some of the 6800 system control lines will be required.

7.4 Digitally Controlled Amplifier/Attenuator

An unusual application of the DAC, Figure 25, applies the input voltage via the on-chip feedback resistor. The lower op amp automatically adjusts the $V_{REF IN}$ voltage such that I_{OUT1} is equal to the input current (V_{IN}/R_f).

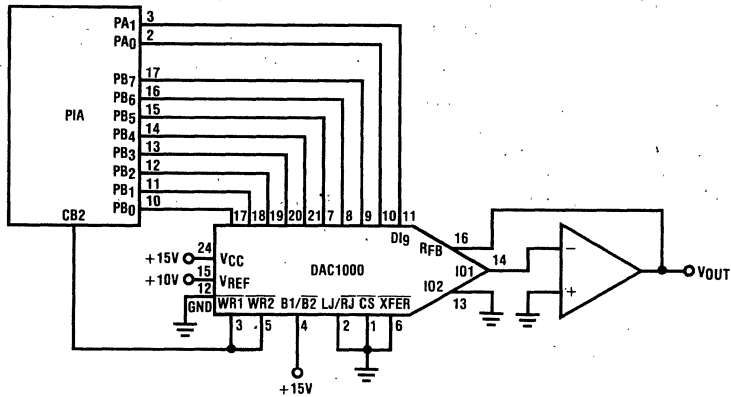


Figure 24. DAC1000 to MC6820/1 PIA Interface

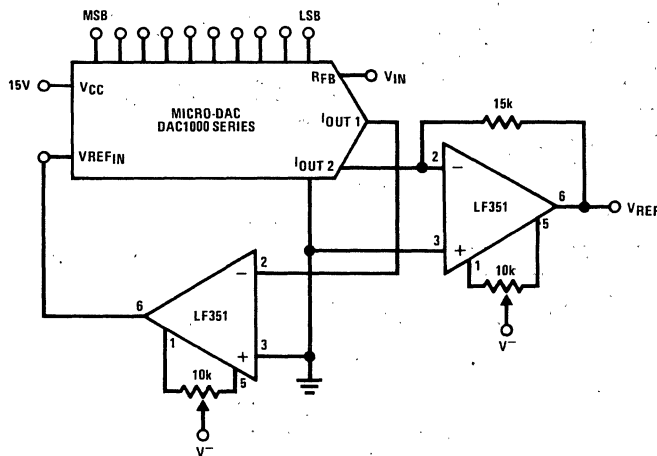


Figure 25. Digitally Controlled Amplifier/Attenuator

The magnitude of this $V_{REF IN}$ voltage depends on the digital word which is in the DAC register. I_{OUT2} then depends upon both the magnitude of V_{IN} and the digital word. The second op amp converts I_{OUT2} to a voltage, V_{OUT} , which is given by

$$V_{OUT} = V_{IN} \left(\frac{1023 - N}{N} \right), \text{ where } 0 < N \leq 1023.$$

Note that $N=0$ (or a digital code of all zeros) is not allowed or this will cause the output amplifier to saturate at either $\pm V_{MAX}$, depending on the sign of V_{IN} .

To provide a digitally controlled divider, the output op amp can be eliminated. Ground the I_{OUT2} pin of the DAC and V_{OUT} is now taken from the lower op amp (which also drives the V_{REF} input of the DAC). The expression for V_{OUT} is now given by

$$V_{OUT} = -\frac{V_{IN}}{M}$$

where M = Digital input (expressed as a fractional binary number). $0 < M < 1$.

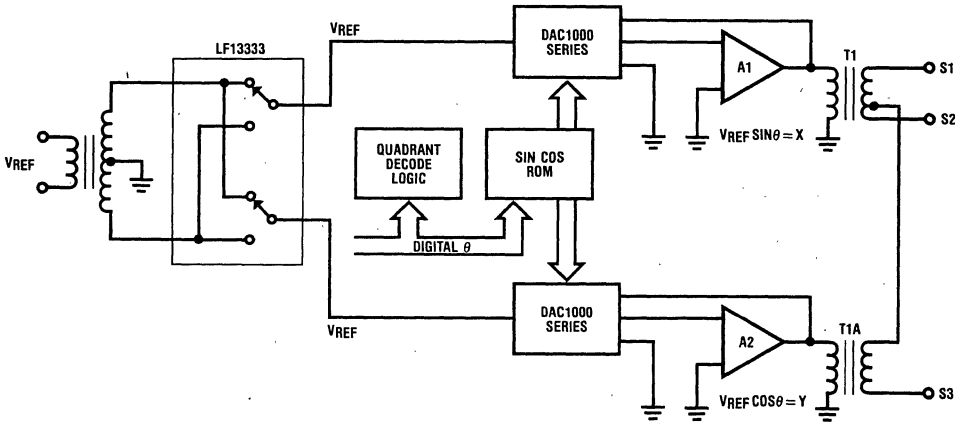


Figure 26. Digital to Synchro Converter

Ordering Information

1. All Logic Features — 24-pin package.

| Accuracy | Temperature Range | | |
|-----------------|-------------------|-----------------|--------------|
| | -40°C to +85°C | -55°C to +125°C | 0°C to +70°C |
| 0.05% (10-bit) | DAC1000LCD | DAC1000LD | DAC1000LCN |
| 0.10% (9-bit) | DAC1001LCD | DAC1001LD | DAC1001LCN |
| 0.20% (8-bit) | DAC1002LCD | DAC1002LD | DAC1002LCN |
| Package Outline | D24C | D24C | N24 |

2. For Right Justified Data — 20-pin package.

| Accuracy | Temperature Range | | |
|-----------------|-------------------|-----------------|--------------|
| | -40°C to +85°C | -55°C to +125°C | 0°C to +70°C |
| 0.05% (10-bit) | *DAC1003LCD | *DAC1003LD | *DAC1003LCN |
| 0.10% (9-bit) | *DAC1004LCD | *DAC1004LD | *DAC1004LCN |
| 0.20% (8-bit) | *DAC1005LCD | *DAC1005LD | *DAC1005LCN |
| Package Outline | D20 | D20 | N20 |

3. For Left Justified Data — 20-pin package. (See package outline D20.)

| Accuracy | Temperature Range | | |
|-----------------|-------------------|-----------------|--------------|
| | -40°C to +85°C | -55°C to +125°C | 0°C to +70°C |
| 0.05% (10-bit) | DAC1006LCD | DAC1006LD | DAC1006LCN |
| 0.10% (9-bit) | DAC1007LCD | DAC1007LD | DAC1007LCN |
| 0.20% (8-bit) | DAC1008LCD | DAC1008LD | DAC1008LCN |
| Package Outline | D20 | D20 | N20 |

*Available on special order



DAC1020 10-Bit Binary Multiplying D/A Converter

DAC1220 12-Bit Binary Multiplying D/A Converter

General Description

The DAC1020 and the DAC1220 are, respectively, 10 and 12-bit binary multiplying digital-to-analog converters. A deposited thin film R-2R resistor ladder divides the reference current and provides the circuit with excellent temperature tracking characteristics (0.0002%/°C linearity error temperature coefficient maximum). The circuit uses CMOS current switches and drive circuitry to achieve low power consumption (30 mW max) and low output leakages (200 nA max). The digital inputs are compatible with DTL/TTL logic levels as well as full CMOS logic level swings. This part, combined with an external amplifier and voltage reference, can be used as a standard D/A converter; however, it is also very attractive for multiplying applications (such as digitally controlled gain blocks) since its linearity error is essentially independent of the voltage reference. All inputs are protected from damage due to static discharge by diode clamps to V⁺ and ground.

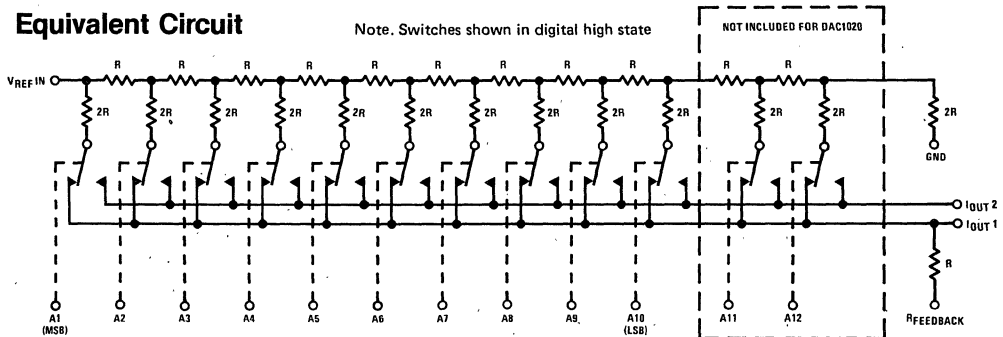
This part is available with 10-bit (0.05%), 9-bit (0.10%), and 8-bit (0.20%) non-linearity guaranteed over temperature (note 1 of electrical characteristics). The

DAC1020, DAC1021 and DAC1022 are direct replacements for the 10-bit resolution AD7520 and AD7530 and equivalent to the AD7533 family. The DAC1220, DAC1221 and DAC1222 are direct replacements for the 12-bit resolution AD7521 and AD7531 family.

Features

- Linearity specified with zero and full-scale adjust only
- Non-linearity guaranteed over temperature
- Integrated thin film on CMOS structure
- 10-bit or 12-bit resolution
- Low power dissipation 10 mW @ 15V typ
- Accepts variable or fixed reference $-25V \leq V_{REF} \leq +25V$
- 4-quadrant multiplying capability
- Interfaces directly with DTL, TTL and CMOS
- Fast settling time—500 ns typ
- Low feedthrough error—1/2 LSB @ 100 kHz typ

Equivalent Circuit



Ordering Information

10-BIT D/A CONVERTERS

| TEMPERATURE RANGE | | 0°C to 70°C | | -40°C to +85°C | | -55°C to +125°C | |
|-------------------|-------|-------------|----------------------|----------------|----------------------|-----------------|----------|
| ACCURACY | 0.05% | DAC1020LCN | AD7520LN AD7530LN | DAC1020LCD | AD7520LD AD7530LD | DAC1020LD | AD7520UD |
| | 0.10% | DAC1021LCN | AD7520KN AD7530KN | DAC1021LCD | AD7520KD AD7530KD | DAC1021LD | AD7520TD |
| | 0.20% | DAC1022LCN | AD7520JN AD7530JN | DAC1022LCD | AD7520JD AD7530JD | DAC1022LD | AD7520SD |
| PACKAGE OUTLINE | | N16A | | D16C | | D16C | |

12-BIT D/A CONVERTERS

| TEMPERATURE RANGE | | 0°C to 70°C | | -40°C to +85°C | | -55°C to +125°C | |
|-------------------|-------|-------------|----------------------|----------------|----------------------|-----------------|----------|
| ACCURACY | 0.05% | DAC1220LCN | AD7521LN AD7531LN | DAC1220LCD | AD7521LD AD7531LD | DAC1220LD | AD7521UD |
| | 0.10% | DAC1221LCN | AD7521KN AD7531KN | DAC1221LCD | AD7521KD AD7531KD | DAC1221LD | AD7521TD |
| | 0.20% | DAC1222LCN | AD7521JN AD7531JN | DAC1222LCD | AD7521JD AD7531JD | DAC1222LD | AD7521SD |
| PACKAGE OUTLINE | | N18A | | D18A | | D18A | |

Note. Devices may be ordered by either part number.

Absolute Maximum Ratings

| | |
|--|---|
| V^+ to Gnd | 17V |
| V_{REF} to Gnd | $\pm 25V$ |
| Digital Input Voltage Range | V^+ to Gnd |
| DC Voltage at Pin 1 or Pin 2 (Note 3) | $-100\text{ mV to }V^+$ |
| Storage Temperature Range | $-65^\circ\text{C to }+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Conditions

| | MIN | MAX | UNITS |
|-------------------------|-----|------|------------------|
| Temperature (T_A) | | | |
| DAC1020LD, DAC1021LD, | -55 | +125 | $^\circ\text{C}$ |
| DAC1022LD, DAC1220LD, | -55 | +125 | $^\circ\text{C}$ |
| DAC1221LD, DAC1222LD | -55 | +125 | $^\circ\text{C}$ |
| DAC1020LCD, DAC1021LCD, | -40 | +85 | $^\circ\text{C}$ |
| DAC1022LCD, DAC1220LCD, | -40 | +85 | $^\circ\text{C}$ |
| DAC1221LCD, DAC1222LCD | -40 | +85 | $^\circ\text{C}$ |
| DAC1020LCN, DAC1021LCN | 0 | +70 | $^\circ\text{C}$ |
| DAC1022LCN, DAC1220LCN | 0 | +70 | $^\circ\text{C}$ |
| DAC1221LCN, DAC1222LCN | 0 | +70 | $^\circ\text{C}$ |

Electrical Characteristics

($V^+ = 15V$, $V_{REF} = 10.000V$, $T_A = 25^\circ\text{C}$ unless otherwise specified)

| PARAMETER | CONDITIONS | DAC1020, DAC1021, DAC1022 | | | DAC1220, DAC1221, DAC1222 | | | UNITS |
|----------------------------------|--|---------------------------|-------|--------|---------------------------|-------|--------|------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 10 | | | 12 | | | Bits |
| Linearity Error | $T_{MIN} < T_A < T_{MAX}$; $-10V < V_{REF} < +10V$, (Note 1) End Point Adjustment Only (See Linearity Error in Definition of Terms) | | | | | | | |
| 10-Bit Parts | DAC1020, DAC1220 | | | 0.05 | | | 0.05 | % FSR |
| 9-Bit Parts | DAC1021, DAC1221 | | | 0.10 | | | 0.10 | % FSR |
| 8-Bit Parts | DAC1022, DAC1222 | | | 0.20 | | | 0.20 | % FSR |
| Linearity Error Tempco | $-10V \leq V_{REF} \leq +10V$, (Notes 1 and 2) | | | 0.0002 | | | 0.0002 | % FS/ $^\circ\text{C}$ |
| Full-Scale Error | $-10V \leq V_{REF} \leq +10V$, (Notes 1 and 2) | | 0.3 | 1.0 | | 0.3 | 1.0 | % FS |
| Full-Scale Error Tempco | $T_{MIN} < T_A < T_{MAX}$, (Note 2) | | | 0.001 | | | 0.001 | % FS/ $^\circ\text{C}$ |
| Output Leakage Current | $T_{MIN} \leq T_A \leq T_{MAX}$ | | | | | | | |
| I_{OUT1} | All Digital Inputs Low | | | 200 | | | 200 | nA |
| I_{OUT2} | All Digital Inputs High | | | 200 | | | 200 | nA |
| Power Supply Sensitivity | All Digital Inputs High, $14V \leq V^+ \leq 16V$, (Note 2), (Figure 2) | | 0.005 | 0.005 | | 0.005 | 0.005 | % FS/V |
| V_{REF} Input Resistance | | 10 | 15 | 20 | 10 | 15 | 20 | k Ω |
| Full-Scale Current Settling Time | $R_L = 100\Omega$ from 0 to 99.95% FS All Digital Inputs Switched Simultaneously | | 500 | | | 500 | | ns |
| V_{REF} Feedthrough | All Digital Inputs Low, $V_{REF} = 20\text{ Vp-p @ }100\text{ kHz}$ | | | 10 | | | 10 | mVp-p |
| | D Package (Note 4) | 6 | 9 | | 6 | 9 | | mVp-p |
| | N Package | 2 | 5 | | 2 | 5 | | mVp-p |
| Output Capacitance | | | | | | | | |
| I_{OUT1} | All Digital Inputs Low | | 40 | | | 40 | | pF |
| | All Digital Inputs High | | 200 | | | 200 | | pF |
| I_{OUT2} | All Digital Inputs Low | | 200 | | | 200 | | pF |
| | All Digital Inputs High | | 40 | | | 40 | | pF |
| Digital Input | (Figure 1) | | | | | | | |
| Low Threshold | $T_{MIN} < T_A < T_{MAX}$ | | | 0.8 | | | 0.8 | V |
| High Threshold | $T_{MIN} < T_A < T_{MAX}$ | 2.4 | | | 2.4 | | | V |



Electrical Characteristics (Continued)

($V^+ = 15V$, $V_{REF} = 10.000V$, $T_A = 25^\circ C$ unless otherwise specified)

| PARAMETER | CONDITIONS | DAC1020, DAC1021 DAC1022 | | | DAC1220, DAC1221 DAC1222 | | | UNITS |
|------------------------------|---------------------------------|-----------------------------|-----|------|-----------------------------|-----|------|---------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Digital Input Current | $T_{MIN} \leq T_A \leq T_{MAX}$ | | | | | | | |
| | Digital Input High | | 1 | 100 | | 1 | 100 | μA |
| | Digital Input Low | | -50 | -200 | | -50 | -200 | μA |
| Supply Current | All Digital Inputs High | | 0.2 | 1.6 | | 0.2 | 1.6 | mA |
| | All Digital Inputs Low | | 0.6 | 2 | | 0.6 | 2 | mA |
| Operating Power Supply Range | (Figures 1 and 2) | 5 | | 15 | 5 | | 15 | V |

Note 1: $V_{REF} = \pm 10V$ and $V_{REF} = \pm 1V$. A linearity error temperature coefficient of 0.0002% FS for a $45^\circ C$ rise only guarantees 0.009% maximum change in linearity error. For instance, if the linearity error at $25^\circ C$ is 0.045% FS it could increase to 0.054% at $70^\circ C$ and the DAC will be no longer a 10-bit part. Note, however, that the linearity error is specified over the device full temperature range which is a more stringent specification since it includes the linearity error temperature coefficient.

Note 2: Using internal feedback resistor as shown in Figure 3.

Note 3: Both I_{OUT1} and I_{OUT2} must go to ground or the virtual ground of an operational amplifier. If $V_{REF} = 10V$, every millivolt offset between I_{OUT1} or I_{OUT2} , 0.005% linearity error will be introduced.

Note 4: To achieve this low feedthrough in the D package, the user must ground the metal lid.

Typical Performance Characteristics

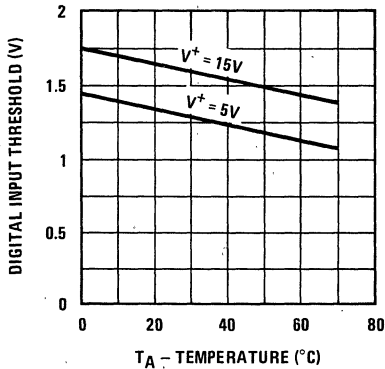


FIGURE 1. Digital Input Threshold vs Ambient Temperature

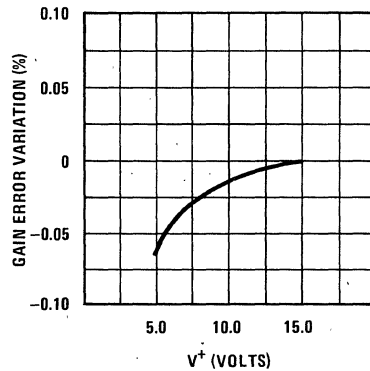


FIGURE 2. Gain Error Variation vs V^+

Typical Applications

The following applications are also valid for 12-bit systems using the DAC1220 and 2 additional digital inputs.

Operational Amplifier Bias Current (Figure 3)

The op amp bias current, I_b , flows through the 15k internal feedback resistor. BI-FET op amps have low I_b and, therefore, the $15k \times I_b$ error they introduce is negligible; they are strongly recommended for the DAC1020 applications.

V_{OS} Considerations

The output impedance, R_{OUT} , of the DAC is modulated by the digital input code which causes a modulation of the operational amplifier output offset. It is therefore recommended to adjust the op amp V_{OS} . R_{OUT} is $\sim 15k$ if more than 4 digital inputs are high; R_{OUT}

is $\sim 45k$ if a single digital input is high, and R_{OUT} approaches infinity if all inputs are low.

Operational Amplifier V_{OS} Adjust (Figure 3)

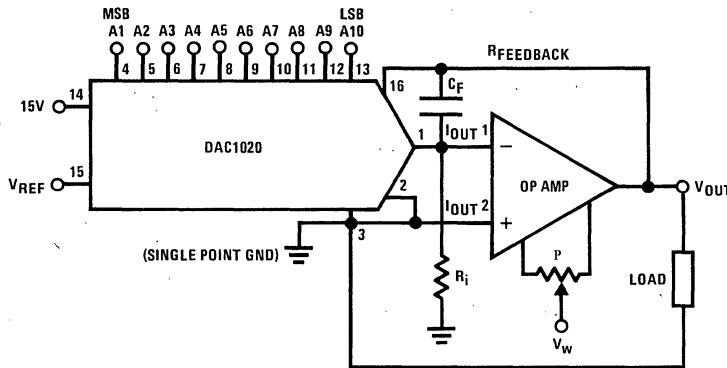
Connect all digital inputs, A1–A10, to ground and adjust the potentiometer to bring the op amp V_{OUT} pin to within ± 1 mV from ground potential. If V_{REF} is less than 10V, a finer V_{OS} adjustment is required. It is helpful to increase the resolution of the V_{OS} adjust procedure by connecting a 1 k Ω resistor between the inverting input of the op amp to ground. After V_{OS} has been adjusted, remove the 1 k Ω .

Full-Scale Adjust (Figure 4)

Switch high all the digital inputs, A1–A10, and measure the op amp output voltage. Use a 500 Ω potentiometer, as shown; to bring $|V_{OUT}|$ to a voltage equal to $V_{REF} \times 1023/1024$.

SELECTING AND COMPENSATING THE OPERATIONAL AMPLIFIER

| OP AMP FAMILY | C _F | R _i | P | V _w | CIRCUIT SETTLING TIME, t _s | CIRCUIT SMALL SIGNAL BW |
|---------------|----------------|----------------|-----|----------------|---------------------------------------|-------------------------|
| LM357 | 10 pF | 2.4k | 25k | V ⁺ | 1.5 μ s | 1M |
| LM356 | 22 pF | ∞ | 25k | V ⁺ | 3 μ s | 0.5M |
| LF351 | 24 pF | ∞ | 10k | V ⁻ | 4 μ s | 0.5M |
| LM741 | 0 | ∞ | 10k | V ⁻ | 40 μ s | 200 kHz |



$$V_{OUT} = -V_{REF} \left(\frac{A_1}{2} + \frac{A_2}{4} + \frac{A_3}{8} + \dots + \frac{A_{10}}{1024} \right)$$

$$-10V \leq V_{REF} \leq 10V$$

$$0 \leq V_{OUT} \leq -\frac{1023}{1024} V_{REF}$$

where $A_N = 1$ if the A_N digital input is high
 $A_N = 0$ if the A_N digital input is low

FIGURE 3. Basic Connection: Unipolar or 2-Quadrant Multiplying Configuration (Digital Attenuator)

Typical Applications (Continued)

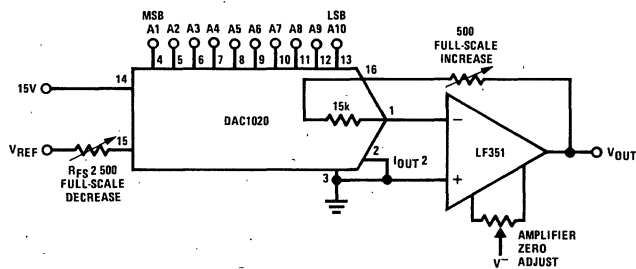


FIGURE 4: Full-Scale Adjust

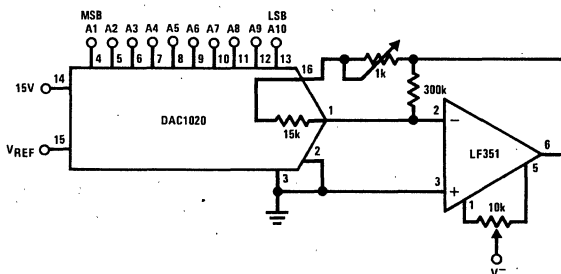
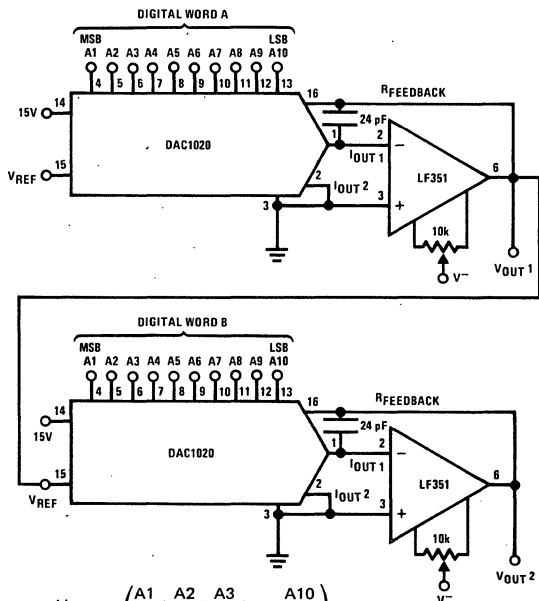


FIGURE 5: Alternate Full-Scale Adjust: (Allows Increasing or Decreasing the Gain)



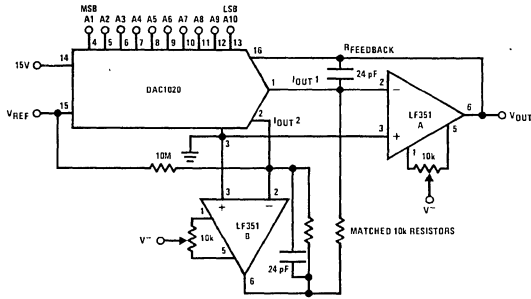
$$V_{OUT1} = -V_{REF} \left(\frac{A1}{2} + \frac{A2}{4} + \frac{A3}{8} + \dots + \frac{A10}{1024} \right)$$

$$V_{OUT2} = V_{REF} \left(\frac{A1}{2} + \frac{A2}{4} + \frac{A3}{8} + \dots + \frac{A10}{1024} \right) \times \left(\frac{B1}{2} + \frac{B2}{4} + \frac{B3}{8} + \dots + \frac{B10}{1024} \right)$$

where V_{REF} can be an AC signal

FIGURE 6: Precision Analog-to-Digital Multiplier

Typical Applications (Continued)



$$V_{OUT} = -V_{REF} \left(\frac{A1}{2} + \frac{A2}{4} + \dots + \frac{A10}{1024} - \frac{1}{1024} \right)$$

where: $A_N = +1$ if A_N input is high
 $A_N = -1$ if A_N input is low

FIGURE 7. Bipolar 4-Quadrant Multiplying Configuration

Operational Amplifiers V_{OS} Adjust (Figure 7)

- Switch all the digital inputs high; adjust the V_{OS} potentiometer of op amp B to bring its output to a value equal to $-(V_{REF}/1024)$ (V).
- Switch the MSB high and the remaining digital inputs low. Adjust the V_{OS} potentiometer of op amp A, to bring its output value to within a 1 mV from ground potential. For $V_{REF} < 10V$, a finer adjust is necessary, as already mentioned in the previous application.

Gain Adjust (Full-Scale Adjust)

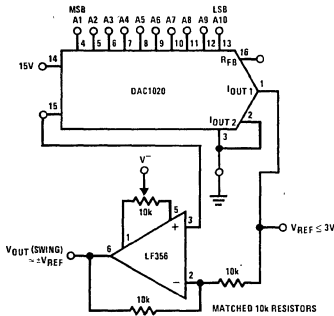
Assuming that the external 10k resistors are matched to better than 0.1%, the gain adjust of the circuit is the same with the one previously discussed.

COMPLEMENTARY OFFSET BINARY (BIPOlar) OPERATION

| DIGITAL INPUT | V_{OUT} |
|---------------------|----------------------------|
| 0 0 0 0 0 0 0 0 0 0 | $+V_{REF}$ |
| 0 0 0 0 0 0 0 0 0 1 | $V_{REF} \times 1022/1024$ |
| 0 1 1 1 1 1 1 1 1 1 | $V_{REF} \times 2/1024$ |
| 1 0 0 0 0 0 0 0 0 0 | 0 |
| 1 0 0 0 0 0 0 0 0 1 | $-V_{REF} \times 2/1024$ |
| 1 1 1 1 1 1 1 1 1 1 | $-V_{REF} (1022/1024)$ |

Note that:

- $I_{OUT1} + I_{OUT2} = \frac{V_{REF}}{R_{LADDER}} \times \left(\frac{1023}{1024} \right)$
- By doubling the output range we get half the resolution
- The 10M resistor, adds a 1 LSB "thump", to allow full offset binary operation where the output reaches zero for the half-scale code. If symmetrical output excursions are required, omit the 10M resistor.

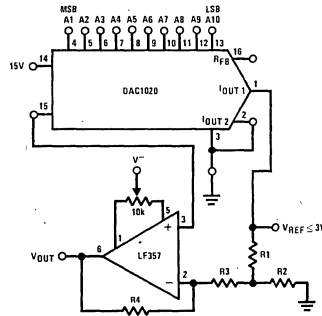


TRUE OFFSET BINARY OPERATION

| DIGITAL INPUT | V_{OUT} |
|---------------------|----------------------------|
| 1 1 1 1 1 1 1 1 1 1 | $V_{REF} \times 1022/1024$ |
| 1 0 0 0 0 0 0 0 0 0 | 0 |
| 0 0 0 0 0 0 0 0 0 0 | $-V_{REF}$ |

$t_s = 1.8 \mu s$
 use LM336 for a voltage reference

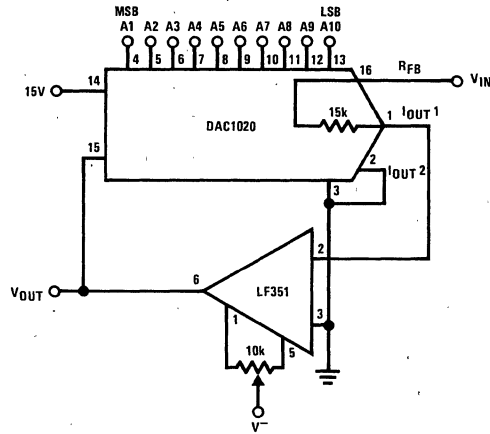
FIGURE 8. Bipolar Configuration with a Single Op Amp



- $R4 = (2A_V^- - 1)R$, $\frac{R2}{R1} = \frac{A_V^-}{A_V^- - 1}$
- $R3 + R1 || R2 = R$; $A_V^- = \frac{V_{OUT}(PEAK)}{V_{REF}}$, $R = 20k$
- Example: $V_{REF} = 2V$, $V_{OUT} (swing) \approx \pm 10V$; $A_V^- = 5V$
 Then $R4 = 9R$, $R1 = 0.8 R2$. If $R1 = 0.2R$ then $R2 = 0.25R$, $R3 = 0.64R$

FIGURE 9. Bipolar Configuration with Increased Output Swing

Typical Applications (Continued)

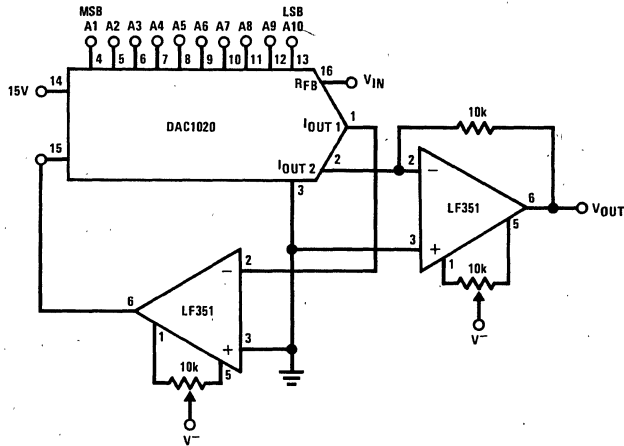


$$V_{OUT} = \frac{-V_{REF}}{\left(\frac{A_1}{2} + \frac{A_2}{4} + \frac{A_3}{8} + \dots + \frac{A_{10}}{1024}\right)}$$

where: V_{REF} can be an AC signal

- By connecting the DAC in the feedback loop of an operational amplifier a linear digitally control gain block can be realized
- Note that with all digital inputs low, the gain of the amplifier is infinity, that is, the op amp will saturate. In other words, we cannot divide the V_{REF} by zero!

FIGURE 10. Analog-to-Digital Divider (or Digitally Gain Controlled Amplifier)



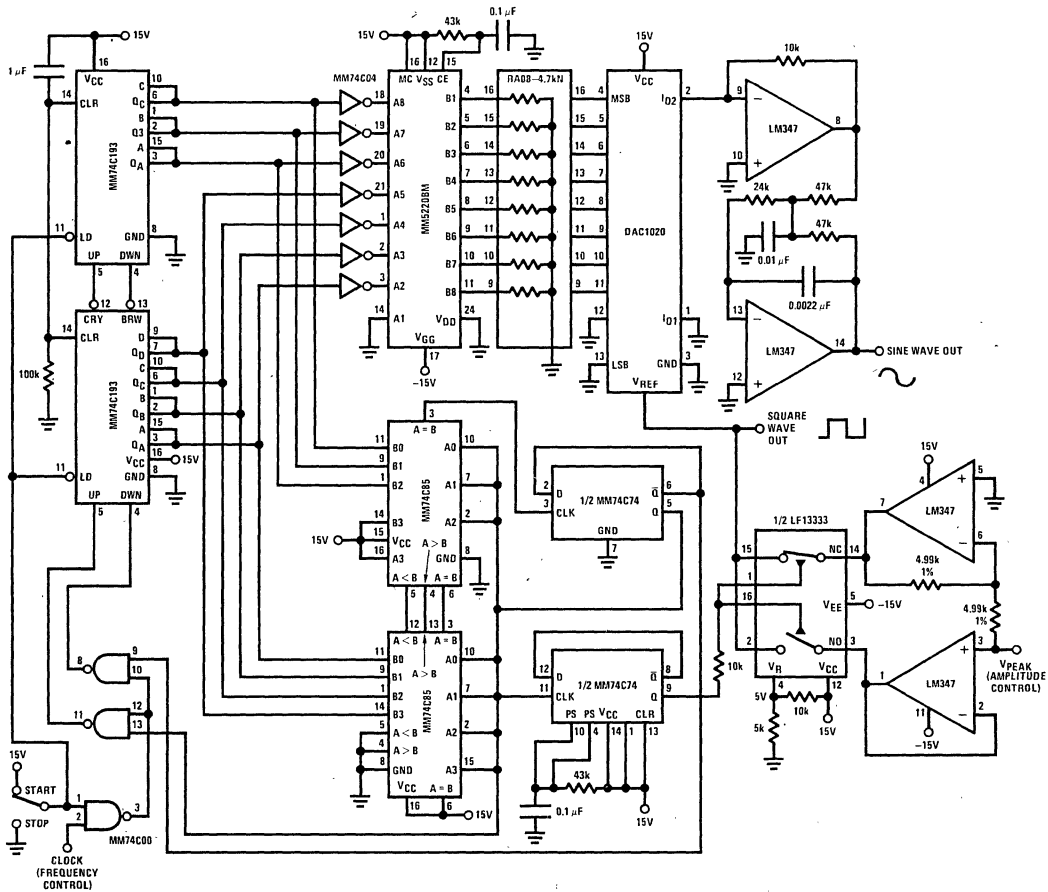
$$V_{OUT} = V_{REF} \left[\frac{\frac{A_1}{2} + \frac{A_2}{4} + \dots + \frac{A_{10}}{1024}}{\frac{A_1}{2} + \frac{A_2}{4} + \dots + \frac{A_{10}}{1024}} \right] \text{ or } V_{OUT} = V_{REF} \left(\frac{1023 - N}{N} \right)$$

where: $0 \leq N \leq 1023$
 $N = 0$ for $A_N =$ all zeros
 $N = 1$ for $A_{10} = 1, A_1 - A_9 = 0$

$N = 1023$ for $A_N =$ all 1's

FIGURE 11. Digitally Controlled Amplifier-Attenuator

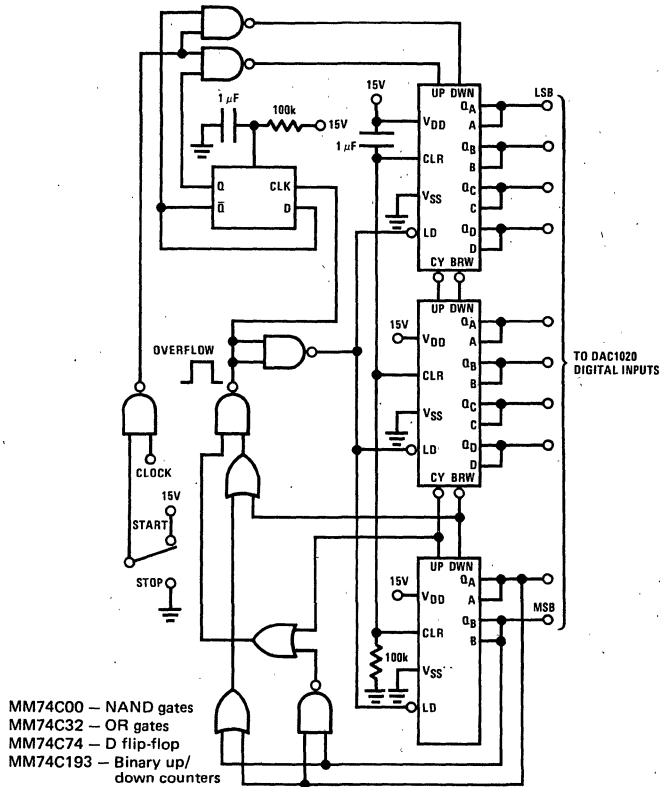
Typical Applications (Continued)



- Output frequency = $\frac{f_{CLK}}{512}$; $f_{MAX} \cong 2 \text{ kHz}$
- Output voltage range = 0V–10V peak
- THD < 0.2%
- Excellent amplitude and frequency stability with temperature
- Low pass filter shown has a 1 kHz corner (for output frequencies below 10 Hz, filter corner should be reduced)
- Any periodic function can be implemented by modifying the contents of the look up table ROM
- No start up problems

FIGURE 12. Precision Low Frequency Sine Wave Oscillator Using Sine Look-Up ROM

Typical Applications (Continued)



- Binary up/down counter digitally "ramps" the DAC output
- Can stop counting at any desired 10-bit input code
- Senses up or down count overflow and automatically reverses direction of count

FIGURE 13. A Useful Digital Input Code Generator for DAC Attenuator or Amplifier Circuits

Definition of Terms

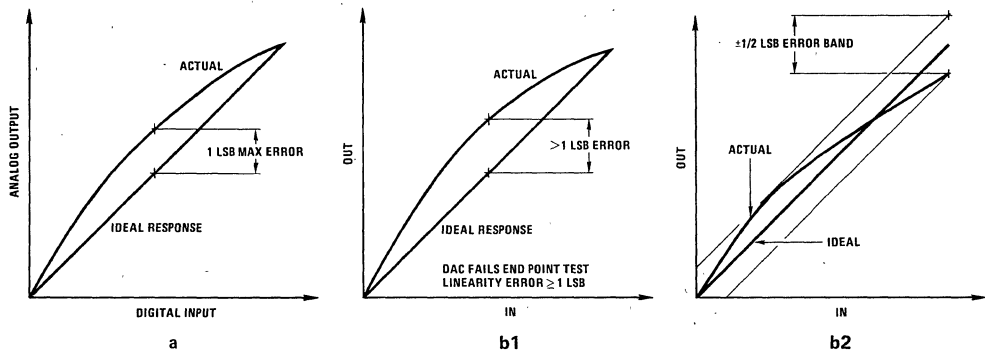
Resolution: Resolution is defined as the reciprocal of the number of discrete steps in the D/A output. It is directly related to the number of switches or bits within the D/A. For example, the DAC1020 has 2^{10} or 1024 steps while the DAC1220 has 2^{12} or 4096 steps. Therefore, the DAC1020 has 10-bit resolution, while the DAC1220 has 12-bit resolution.

Linearity Error: Linearity error is the maximum deviation from a straight line passing through the endpoints of the D/A transfer characteristic. It is measured after calibrating for zero (see V_{OS} adjust in typical applications) and full-scale. Linearity error is a design parameter intrinsic to the device and cannot be externally adjusted.

Power Supply Sensitivity: Power supply sensitivity is a measure of the effect of power supply changes on the D/A full-scale output.

Settling Time: Full-scale settling time requires a zero to full-scale or full-scale to zero output change. Settling time is the time required from a code transition until the D/A output reaches within $\pm 1/2$ LSB of final output value.

Full-Scale Error: Full-scale error is a measure of the output error between an ideal D/A and the actual device output. Ideally, for the DAC1020 full-scale is $V_{REF} - 1$ LSB. For $V_{REF} = 10V$ and unipolar operation, $V_{FULL-SCALE} = 10.0000V - 9.8 mV = 9.9902V$. Full-scale error is adjustable to zero as shown in Figure 5.

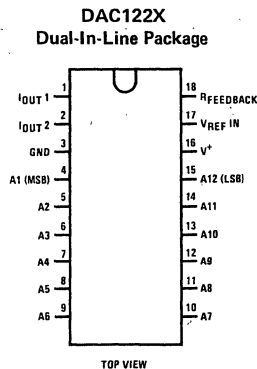
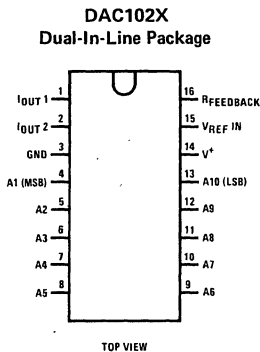


(a) End point test after zero and full-scale adjust. The DAC has 1 LSB linearity error

(b) By shifting the full-scale calibration on of the DAC of Figure (b1) we could pass the "best straight line" (b2) test and meet the $\pm 1/2$ LSB linearity error specification

Note. (a), (b1) and (b2) above illustrate the difference between "end point" National's linearity test (a) and "best straight line" test. Note that both devices in (a) and (b2) meet the $\pm 1/2$ LSB linearity error specification but the end point test is a more "real life" way of characterizing the DAC.

Connection Diagrams



DAC1200/DAC1201 12-Bit (Binary) Digital-to-Analog Converters

DAC1202/DAC1203 3-Digit (BCD) Digital-to-Analog Converters

General Description

The DAC1200 series of D/A converters is a family of precision low-cost converter building blocks intended to fulfill a wide range of industrial and military D/A applications. These devices are complete functional blocks requiring only application of power for operation. The design combines a precision 12-bit weighted current source (12 current switches and 12-bit thin-film resistor network), a rapid-settling operational amplifier, and 10.24V (for binary series) or 10.00V (for BCD series) buffered reference.

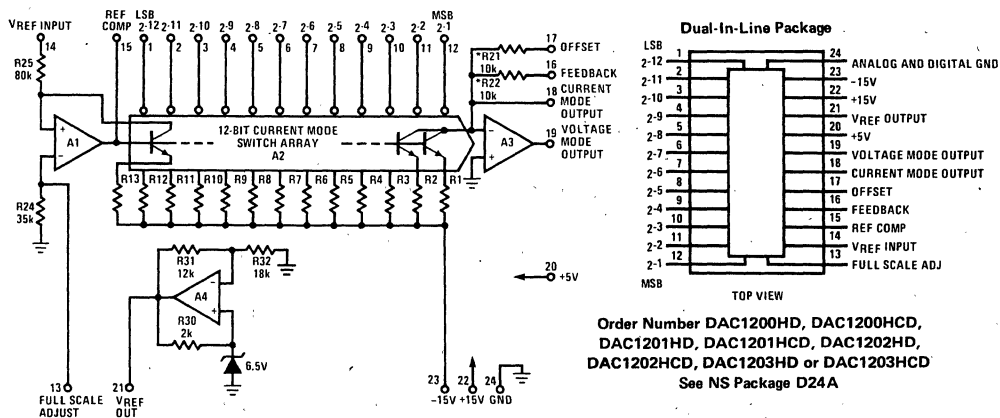
Input coding options include complementary binary and complementary BCD formats. In all instances, a logic "low" ($\leq 0.8V$) turns a given bit ON, and a logic "high" ($\geq 2.0V$) turns the bit OFF. Output format may be programmed for bipolar ($\pm 10V$) or unipolar (0 to 10V) operation using internally supplied thin-film resistor pin strap options. Current mode operation is also available from 0 to 2 mA (for binary) or 0 to 1.25 mA (for BCD).

The entire series is available in hermetically sealed 24-lead DIP.

Features

- Circuit completely self-contained
- Both current and voltage-mode outputs
- Standard power supplies: $\pm 15V$ and +5V
- Internal buffered reference: 10.24V for binary
10.00V for BCD
- 0 to 2 mA, $\pm 10V$ or 0 to 10V output by strapping internal resistors; other scales by external resistors
- $\pm 1/2$ LSB (binary) or $\pm 1/10$ LSD (BCD) linearity
- Fast settling time: 1.5 μs in current mode
2.5 μs in voltage mode
- High slew rate: 15 V/ μs
- TTL and CMOS compatible complementary binary or BCD input logic format
- 12 bit linearity
- Standard dual-width DIP package

Block and Connection Diagrams



Order Number DAC1200HD, DAC1200HCD,
DAC1201HD, DAC1201HCD, DAC1202HD,
DAC1202HCD, DAC1203HD or DAC1203HCD
See NS Package D24A

*R21 = R22 = 16k for DAC1202/1203 (BCD)

Absolute Maximum Ratings

| | |
|--|---|
| Supply Voltage (V^+ & V^-) | $\pm 18\text{ V}$ |
| Logic Supply Voltage (V_{CC}) | $+10\text{ V}$ |
| Logic Input Voltage | -0.7 V to $+18\text{ V}$ |
| Reference Input Voltage | -0 V , $+18\text{ V}$ |
| Power Dissipation | (see graphs) |
| Short Circuit Duration (pins 18, 19 & 21) | Continuous |
| Operating Temperature Range | |
| DAC1200HD, DAC1201HD, DAC1202HD, DAC1203HD | -55°C to $+125^\circ\text{C}$ |
| DAC1200HCD, DAC1201HCD, DAC1202HCD, DAC1203HCD | -25°C to $+85^\circ\text{C}$ |
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (soldering, 10 sec.) | 300°C |

DC Electrical Characteristics DAC1200/1201 Binary D/A (Notes 1, 2)

| PARAMETER | CONDITIONS | DAC1200/1200C | | | DAC1201/1201C | | | UNITS |
|---|---|---------------------------------------|----------|--------------|---------------|----------|--------------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 12 | | | 12 | | | Bits |
| Linearity Error (Note 3) | $T_A = 25^\circ\text{C}$ | | | ± 0.0122 | | | ± 0.0488 | % FS |
| | | | | ± 0.0244 | | | ± 0.0976 | % FS |
| Offset Voltage | $T_A = 25^\circ\text{C}$ | | 1 | 5 | 1 | 10 | | mV |
| | | | | 10 | | 15 | | mV |
| Voltage Mode Full-Scale Error (Note 3) | $V_{REF} = 10.240\text{ V}$ | | 0.01 | 0.1 | | 0.02 | 0.2 | % FS |
| Voltage Mode Full-Scale Error | Pin 21 connected to Pin 14, $T_A = 25^\circ\text{C}$ | | 0.1 | 0.6 | | 0.1 | 0.7 | % FS |
| Monotonicity (Notes 3, 4) | | Guaranteed over the temperature range | | | | | | |
| Voltage Mode Power Supply Sensitivity | $\Delta V^+ = \pm 2\text{ V}$ $\Delta V^- = \pm 2\text{ V}$ $\Delta V_{CC} = \pm 1\text{ V}$ $T_A = 25^\circ\text{C}$ $V_{REF} = 10.240\text{ V}$ | | 0.002 | 0.02 | 0.002 | 0.02 | | % FS/V |
| | | | 0.002 | 0.02 | 0.002 | 0.02 | | % FS/V |
| | | | 0.002 | 0.02 | 0.002 | 0.02 | | % FS/V |
| Output Voltage Range | $R_L = 5\text{ k}$ | ± 10.5 | ± 12 | | ± 10.5 | ± 12 | | V |
| Voltage Mode Output Short Circuit Current Limit | $T_A = 25^\circ\text{C}$ | | 20 | 50 | | 20 | 50 | mA |
| Current Mode Voltage Compliance | (Note 6) | ± 2.5 | | | ± 2.5 | | | V |
| Current Mode Output Impedance | | | 15 | | | 15 | | k Ω |
| Reference Voltage | $0\text{ mA} \leq I_{REF} \leq 2\text{ mA}$, $T_A = 25^\circ\text{C}$ | 10.190 | 10.240 | 10.290 | 10.190 | 10.240 | 10.290 | V |
| Logic "1" Input Voltage (Bit OFF) | | 2.0 | | | 2.0 | | | V |
| Logic "0" Input Voltage (Bit ON) | | | | 0.8 | | | 0.8 | V |
| Logic "1" Input Current (Bit OFF) | $V_{IN} = 2.5\text{ V}$ | | 1 | 10 | | 1 | 10 | μA |
| Logic "0" Input Current (Bit ON) | $V_{IN} = 0\text{ V}$ | | -10 | -100 | | -10 | -100 | μA |
| Power Supply Current | I^+ I^- I_{CC} $V^+ = 15.0\text{ V}$ $V^- = -15.0\text{ V}$ $V_{CC} = 5.0\text{ V}$ $T_A = 25^\circ\text{C}$ | | 10 | 15 | | 10 | 15 | mA |
| | | | 25 | 30 | | 25 | 30 | mA |
| | | | 20 | 25 | | 20 | 25 | mA |
| | | | 20 | 25 | | 20 | 25 | mA |

DC Electrical Characteristics DAC1202/1203 3-Digit BCD D/A (Notes 1, 2)

| PARAMETER | CONDITIONS | DAC1202/1202C | | | DAC1203/1203C | | | UNITS |
|---|---|--|----------|--------|---------------|----------|--------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 3 | | | 3 | | | Digits |
| Linearity Error (Note 5) | $T_A = 25^\circ\text{C}$ | | | 0.01 | | | 0.05 | % FS |
| | | | | 0.02 | | | 0.1 | % FS |
| Offset Voltage | $T_A = 25^\circ\text{C}$ | | 1 | 5 | 1 | 10 | 15 | mV |
| | | | | 10 | | | | mV |
| Voltage Mode Full-Scale Error (Note 5) | $V_{REF} = 10.000\text{V}$ | | 0.01 | 0.1 | 0.02 | 0.2 | 0.7 | % FS |
| Voltage Mode Full-Scale Error | Pin 21 connected to Pin 14, $T_A = 25^\circ\text{C}$ | | 0.5 | 0.6 | | | | % FS |
| Monotonicity (Notes 4, 5) | | Guaranteed over the temperature range | | | | | | |
| Voltage Mode Power Supply Sensitivity | $\Delta V^+ = \pm 2\text{V}$ $\Delta V^- = \pm 2\text{V}$ $\Delta V_{CC} = \pm 1\text{V}$ | $T_A = 25^\circ\text{C}$ $V_{REF} = 10.000\text{V}$ | 0.002 | 0.02 | | 0.002 | 0.02 | % FS/V |
| | | | 0.002 | 0.02 | | 0.002 | 0.02 | % FS/V |
| Voltage Mode Output Voltage Range | $R_L = 5\text{k}$ | ± 10.5 | ± 12 | | ± 10.5 | ± 12 | | V |
| | | | | | | | | |
| Voltage Mode Output Short Circuit Limit | $T_A = 25^\circ\text{C}$ | | 20 | 50 | 20 | 50 | | mA |
| Current Mode Compliance | (Note 6) | ± 2.5 | | | ± 2.5 | | | V |
| Current Mode Output Impedance | | | 10 | | 10 | | | k Ω |
| Reference Voltage | $0 \leq I_{REF} \leq 2\text{mA}$, $T_A = 25^\circ\text{C}$ | 9.950 | 10.000 | 10.050 | 9.950 | 10.000 | 10.050 | V |
| Logic "1" Input Voltage (Bit OFF) | | 2.0 | | | 2.0 | | | V |
| Logic "0" Input Voltage (Bit ON) | | | | 0.8 | | | 0.8 | V |
| Logic "1" Input Current (Bit OFF) | $V_{IN} = 2.5\text{V}$ | | 1 | 10 | | 1 | 10 | μA |
| Logic "0" Input Current (Bit ON) | $V_{IN} = 0\text{V}$ | | -10 | -100 | | -10 | -100 | μA |
| Power Supply Current | I^+ | | 10 | 15 | 10 | 15 | | mA |
| | I^- | | 25 | 30 | 25 | 30 | | mA |
| | I_{CC} | | 20 | 25 | 20 | 25 | | mA |

AC Electrical Characteristics DAC1200/1201/1202/1203

| PARAMETER | CONDITIONS ($T_A = 25^\circ\text{C}$) | MIN | TYP | MAX | UNITS |
|---|---|-----|-----|-----|------------------|
| Voltage Mode ± 1 LSB Settling Time (Note 6) | DAC1200/1202, $V_e \leq 1.25\text{mV}$ | | 1.5 | 3.0 | μs |
| | DAC1201/1203, $V_e \leq 5.0\text{mV}$ | | 1 | 3.0 | μs |
| Voltage Mode Full-Scale Change Settling Time (Note 6) | DAC1200/1202, $V_e \leq 1.25\text{mV}$ | | 2.5 | 5.0 | μs |
| | DAC1201/1203, $V_e \leq 5.0\text{mV}$ | | 2.0 | 5.0 | μs |
| Current Mode Full-Scale Settling Time | $R_L = 1\text{k}\Omega$, $C_L \leq 20\text{pF}$ $0 \leq \Delta I_{OUT} \leq 2\text{mA}$ | | 1.5 | | μs |
| Voltage Mode Slew Rate | $-10\text{V} \leq \Delta V_{OUT} \leq +10\text{V}$ | | 15 | | V/ μs |

Note 1: Unless otherwise noted, these specifications apply for $V^+ = 15.0\text{V}$, $V^- = -15.0\text{V}$, and $V_{CC} = 5.0\text{V}$ over the temperature range -55°C to $+125^\circ\text{C}$ for the DAC1200HD/1201/1202/1203 and -25°C to $+85^\circ\text{C}$ for the DAC1200HCD/1201/1202/1203.

Note 2: All typical values are for $T_A = 25^\circ\text{C}$.

Note 3: Unless otherwise noted, this specification applies for $V_{REF} = 10.24\text{V}$, and over the temperature range -25°C to $+85^\circ\text{C}$. Testing conditions include adjustment of offset to 0V and full-scale to 10.2375V.

Note 4: The DAC1200, DAC1202 and DAC1203 are tested for monotonicity by stimulating all bits; the DAC1201 is tested for monotonicity by stimulating only the 10 MSBs and holding the 2 LSBs at 2.0V (i.e., 2 LSBs are OFF).

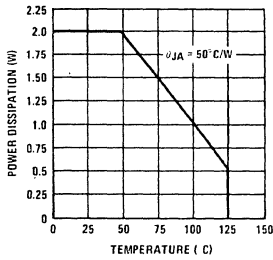
Note 5: Unless otherwise noted, this specification applies for $V_{REF} = 10.000\text{V}$, and over the temperature range -25°C to $+85^\circ\text{C}$. Testing conditions include adjustment of offset to 0V and full-scale to 9.990V.

Note 6: Not tested – guaranteed by design.

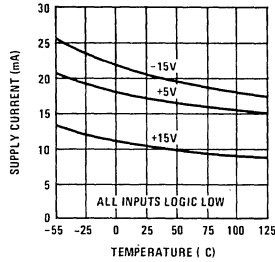
Note 7: ($\Delta V_{OUT} = 10\text{V}$)

Typical Performance Characteristics

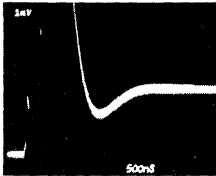
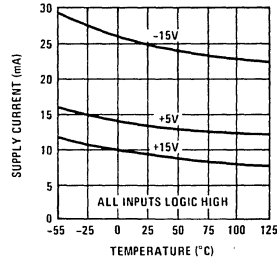
Maximum Power Dissipation



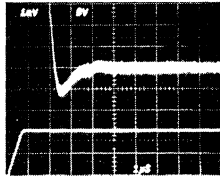
Supply Current vs Temperature



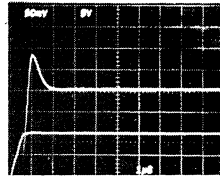
Supply Current vs Temperature



1 LSB Transition
1011 ... 1 → 1100 ... 0
 $V_O = 0, 10V$
 $C_F = 30pF$
 $T_A = 25^\circ C$



10V Full Scale Settling Time



10V Full Scale Pulse Response

Applications Information

1. Introduction

The DAC1200 series D/A converters are designed to minimize adjustments and user-supplied external components. For example, included in the package are a buffered reference, offset nulled output amplifier, and application resistors as well as the basic 12-bit current mode D/A.

However, the DAC1200 series is a sophisticated building block. Its principles of operation and the following applications information should be read before applying power to the device.

The user is referred to National Semiconductor Application Notes AN-156 and AN-157 for additional information.

2. Power Supply Selection & Decoupling

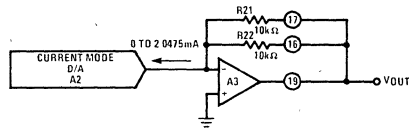
Selection of power supplies is important in applications requiring 0.01% accuracy. The $\pm 15V$ supplies should be well regulated ($\pm 15V \pm 0.1\%$) with less than 0.5mVrms of output noise and hum.

To realize the full speed capability of the device, all three power supply leads should be bypassed with 1 μF tantalum electrolytic capacitors in shunt with 0.01 μF ceramic disc capacitors no farther than 1/2 inch from the device package.

3. Unipolar and Bipolar Operation

The DAC1200 series D/A's may be configured for either unipolar or bipolar operation using resistors provided with the device. Figures 1A and 1B illustrate the proper connection for binary and BCD unipolar operation.

Bipolar operation is accomplished by offsetting the output amplifier A3 as shown in figures 2A and 2B.



$$V_{OUT} = (I_{ZERO} \text{ to } I_{FULLSCALE}) \left(\frac{R_{21} - R_{22}}{R_{21} + R_{22}} \right)$$

$$= (0mA \text{ to } 2.0475mA)(5k\Omega)$$

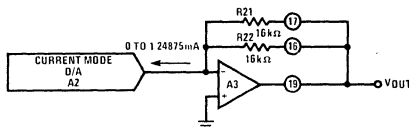
$$= 0V \text{ to } +10.2375V$$

*Values shown are for $V_{REF} = 10.240V$.

$$1 \text{ LSB Voltage Step} = \frac{10.240V}{4096} = 2.5mV$$

$$1 \text{ LSB Current Step} = \frac{2.5mV}{5.0k\Omega} = 0.5\mu A$$

FIGURE 1A. DAC1200/DAC1201 Unipolar Operation



$$V_{OUT} = (I_{ZERO} \text{ to } I_{FULLSCALE}) \left(\frac{R_{21} - R_{22}}{R_{21} + R_{22}} \right)$$

$$= (0 \text{ to } 1.24875mA)(8k\Omega)$$

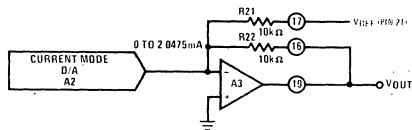
$$= 0V \text{ to } 9.990V$$

*Values shown are for $V_{REF} = 10.000V$.

$$1 \text{ LSD Voltage Step} = \frac{10.000}{1000} = 10mV$$

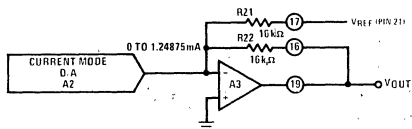
$$1 \text{ LSD Current Step} = \frac{10mV}{8k\Omega} = 1.25\mu A$$

FIGURE 1B. DAC1202/DAC1203 Unipolar Operation



$$\begin{aligned}
 *V_{OUT} &= (0 \text{ to } 2.0475 \text{ mA})R22 - \frac{V_{REF}}{R22} R21 \\
 &= (0 \text{ to } 2.0475 \text{ mA})R22 - V_{REF}, R21 \equiv R22 \\
 &= -10.240 \text{ to } +10.235 \text{ V} \\
 * \text{Values shown are for } V_{REF} &= 10.240 \text{ V} \\
 1 \text{ LSB} &= 5 \text{ mV.}
 \end{aligned}$$

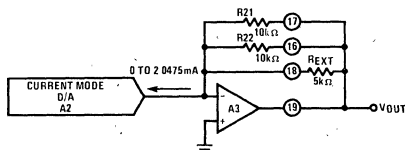
FIGURE 2A. DAC1200/DAC1201 Bipolar Operation



$$\begin{aligned}
 *V_{OUT} &= (0 \text{ mA to } 1.24875 \text{ mA})(R22) - \frac{R22}{R21} V_{REF} \\
 &= -10.000 \text{ V to } +9.80 \text{ V} \\
 * \text{Values shown are for } V_{REF} &= 10.000 \text{ V.} \\
 1 \text{ LSD Voltage Step} &= 20 \text{ mV.}
 \end{aligned}$$

FIGURE 2B. DAC1202/DAC1203 Bipolar Operation

External resistors may be used to achieve alternate zero and full-scale voltages. It is advantageous to utilize R21 and R22 even in these applications since they are closely matched in TCR and temperature to the internal array. Figure 3 illustrates the recommended circuit for zero to 5V operation. REXT should be of metal film or wire-wound construction with a TCR of less than 10ppm/°C.



$$R_{TOTAL} = (R21) \parallel (R22) \parallel (R_{EXT}) = \frac{V_{FULLSCALE}}{2.0475 \text{ mA}} = 2.5 \text{ k}\Omega.$$

FIGURE 3. DAC1200 0 to 5.120V Operation

4. Offset and Full-Scale Adjust

If higher precision is required in the zero and full-scale, external adjustments may be made. The circuit of figure 4 illustrates the recommended circuit to adjust offset and full-scale of the DAC1200 series. The circuit will work equally well for unipolar or bipolar operation.

In bipolar operation, the offset is adjusted at minus full-scale; in the unipolar case at zero scale.

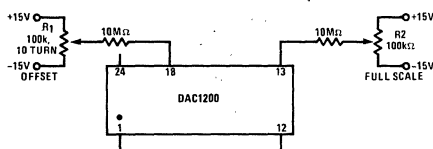


FIGURE 4. Offset & Full-Scale Adjust

For the values shown in figure 4, R1 will allow a ±7mV offset adjustment for the unipolar case and ±15 mV for the bipolar case. R2 will allow a ±50mV adjustment of full scale.

5. Current Mode Operation

Access to the summing junction of A3 affords current mode operation either with a resistive load or to drive a fast-settling external operational amplifier. The loop around A3 should not be closed in current mode operation. There is a ±2.5V maximum compliance voltage at A2's output (pin 18) which restricts the maximum size of the load resistor; i.e., $R_L \times I_{FULLSCALE} \leq 2.5 \text{ V}$.

Note: $I_{FULLSCALE} \approx 2 \text{ mA}$ for DAC1200/DAC1201 and $\approx 1.25 \text{ mA}$ for DAC1202/DAC1203.

6. Settling Time & Glitch Minimization

The settling time of the DAC1200 series and the glitch which occurs between major input code changes may be improved by placing a 10 to 30pF capacitor between pins 18 (current-mode output) and 19 (voltage mode output). The capacitor is used to cancel output capacitance of the current mode D/A and stray capacitance at pin 18.

7. Current Output Boosting

The DAC1200 series may be operated as a "power D/A" by including a current buffer such as the LH0002 or LH0063 in the loop with A3 as shown in figure 5.

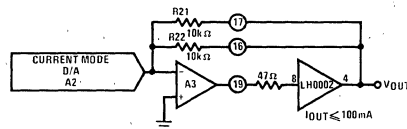


FIGURE 5. Current Boosted Output

8. Logic Input Coding

The sense of the logic inputs to the DAC1200 series is complementary; i.e., a given bit is turned ON by an active "low" input. Table I summarizes input status for the unipolar and bipolar complementary binary and BCD codes.

Other input codes may also be used. For example, the two's complement code, which is used extensively in computer and microprocessor applications, may be converted to the DAC1200 complementary bipolar format by inverting all bits except the MSB. The inversion may be accomplished in the microprocessor by software control, or by hardware using standard hex-inverters.

9. Reference Voltage

External reference voltages may be used with the DAC1200 series. Voltages other than 10.240 or 10.000V in the range of +5.0V to 11V will work satisfactorily for voltage mode operation. Full-scale voltage is always $V_{REF} - 1 \text{ LSB}$ where $1 \text{ LSB} = V_{REF}/4096$ (binary) or $V_{REF}/1000$ (BCD). Full-scale current (for binary) may be predicted by:

$$I_{FULLSCALE} = (V_{REF})/0.19995117 \text{ mA}$$

| CODE TYPE | (Note 8) INPUT CODE | | OUTPUT STATE | OUTPUT VOLTAGE (Note 9) | OUTPUT CURRENT |
|-------------------------------|------------------------|-----------|-----------------|----------------------------|----------------|
| | MSB | LSB | | | |
| Unipolar Complementary Binary | 0000 | 0000 0000 | Full-Scale | +10.2375V | 2.0475mA |
| | 1111 | 1111 1110 | 1 LSB ON | +2.500mV | 0.500 μ A |
| | 1111 | 1111 1111 | Zero Scale | Zero | Zero |
| Bipolar Complementary Binary | 0000 | 0000 0000 | Full-Scale | +10.235V | +1.0235mA |
| | 0111 | 1111 1111 | Half Full-Scale | -0.000V | 0.000mA |
| | 1111 | 1111 1110 | 1 LSB ON | -10.235V | -1.0235mA |
| | 1111 | 1111 1111 | Zero Scale | -10.240V | -1.0240mA |
| Unipolar Complementary BCD | 0110 | 0110 0110 | Full-Scale | +9.990V | 1.24875mA |
| | 1111 | 1111 1110 | 1 LSB ON | 10.000mV | 1.250 μ A |
| | 1111 | 1111 1111 | Zero Scale | Zero | Zero |
| Bipolar Complementary BCD | 0110 | 0110 0110 | Full-Scale | 9.980V | +0.62375mA |
| | 1010 | 1111 1111 | Half Full-Scale | 0.000V | Zero |
| | 1111 | 1111 1110 | 1 LSB ON | -9.980V | -0.62375mA |
| | 1111 | 1111 1111 | Zero Scale | -10.00V | -0.625mA |

Note 8: Logic input sense is such that an active low ($V_{IN} \leq 0.8V$) turns a given bit ON and is represented as a logic "0" in the table.

Note 9: $V_{REF} = 10.240V$ for the DAC1200/1201 and 10.000V for the DAC1202/1203.

Definition of Terms

Resolution

Resolution is defined as the reciprocal of the number of discrete steps in the D/A output (as designed). It is directly related to the number of switches or bits within the D/A. For example, the DAC1200 has 2^{12} or 4096 steps. Resolution may therefore be expressed variously as 12 bits, as 1 part in 2^{12} , as 1 part in 4096, or as a percentage ($1/4096 \times 100 = 0.0244\%$). The DAC1202 has 1000 steps and 3 BCD digits. Resolution may be expressed as 0.1% or 3 BCD digits.

Linearity Error

Linearity error is the maximum deviation from a straight line passing through the endpoints of the D/A transfer characteristic. It is measured after calibrating for zero and full-scale. The linearity error of the DAC1200 series is guaranteed to be less than $\pm 1/2$ LSB or 0.0122% of F.S. for the DAC1200/1200C and $\pm 0.0488\%$ of F.S. for the DAC1201/DAC1201C. Linearity error is a design parameter intrinsic to the device and cannot be externally adjusted.

Offset Voltage

Offset voltage is an output voltage other than zero volts for unipolar operation (and other than minus full-scale for bipolar operation) with all bits turned OFF. In the DAC1200 series this error resides primarily in the output amplifier, A3. Offset voltage is adjustable to zero as discussed in the applications section.

Power Supply Sensitivity

Power supply sensitivity is a measure of the effect of power supply changes on the D/A full-scale output.

Settling Time

Two settling time parameters are specified for the DAC1200 series. Full-scale settling time requires a zero to full-scale or full-scale to zero output change. One LSB settling time requires one LSB output change. In both instances, settling time is the time required from a code transition until the D/A output reaches within $\pm 1/2$ LSB of final output value.

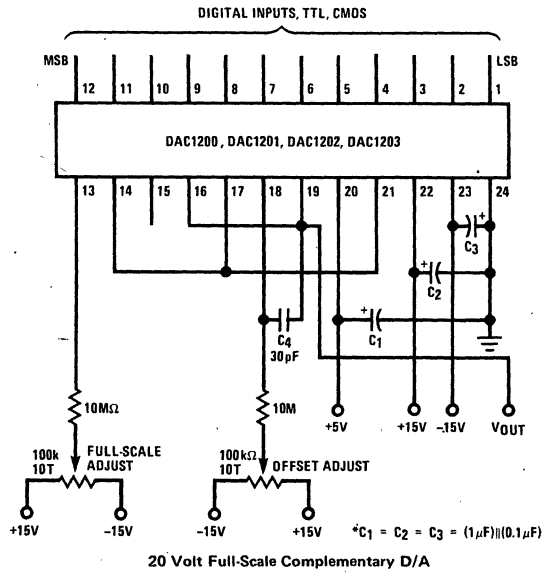
Monotonicity

Monotonicity is a characteristic of the D/A which requires a non-negative output step for an increasing input digital code. Monotonicity, therefore, demands no back steps or changes in sign of the slope of the D/A transfer characteristic.

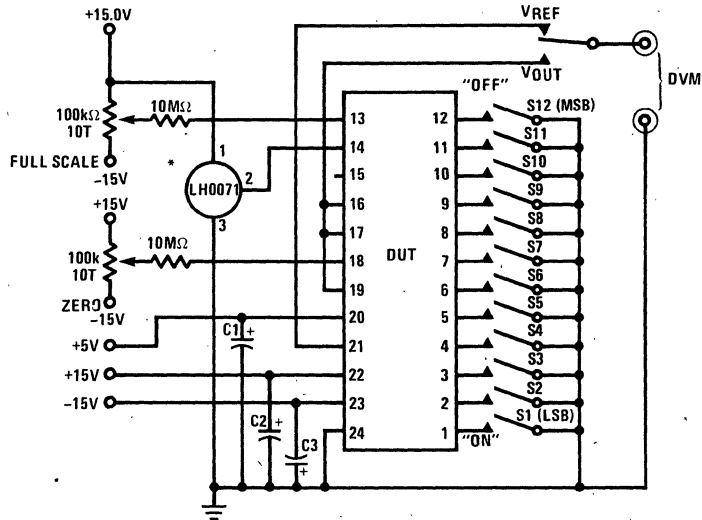
Full-Scale Error

Full-scale error is a measure of the output error between an ideal D/A and the actual device output. Ideally, for the DAC1200 full-scale is $V_{REF} - 1$ LSB. For $V_{REF} = 10.240V$ and unipolar operation, $V_{FULLSCALE} = 10.240V - 2.5mV = 10.2375V$. Departures from this value include internal gain, scaling, and reference errors. Full-scale error is adjustable to zero as discussed in the Applications section.

Typical Application



DC Test Circuit



*LH0070 for DAC1202/1203

C1 = C2 = C3 = 4.7 μF (solid tantalum) in parallel with a 0.01 μF ceramic disc

Ordering Information

| PART NUMBER | | PACKAGE | 25°C LINEARITY ERROR | OPERATING TEMPERATURE RANGE |
|-------------|------------|-------------|----------------------------|-----------------------------------|
| BINARY | BCD | | | |
| DAC1200HD | DAC1202HD | Ceramic DIP | 0.01% | -55°C to +125°C |
| DAC1201HD | DAC1203HD | Ceramic DIP | 0.05% | -55°C to +125°C |
| DAC1200HCD | DAC1202HCD | Ceramic DIP | 0.01% | -25°C to +85°C |
| DAC1201HCD | DAC1203HCD | Ceramic DIP | 0.05% | -25°C to +85°C |

See NS Package HY24A

DAC1280, DAC1285 12-Bit (Binary), DAC1286, DAC1287 3-Digit (BCD) Digital-to-Analog Converters

General Description

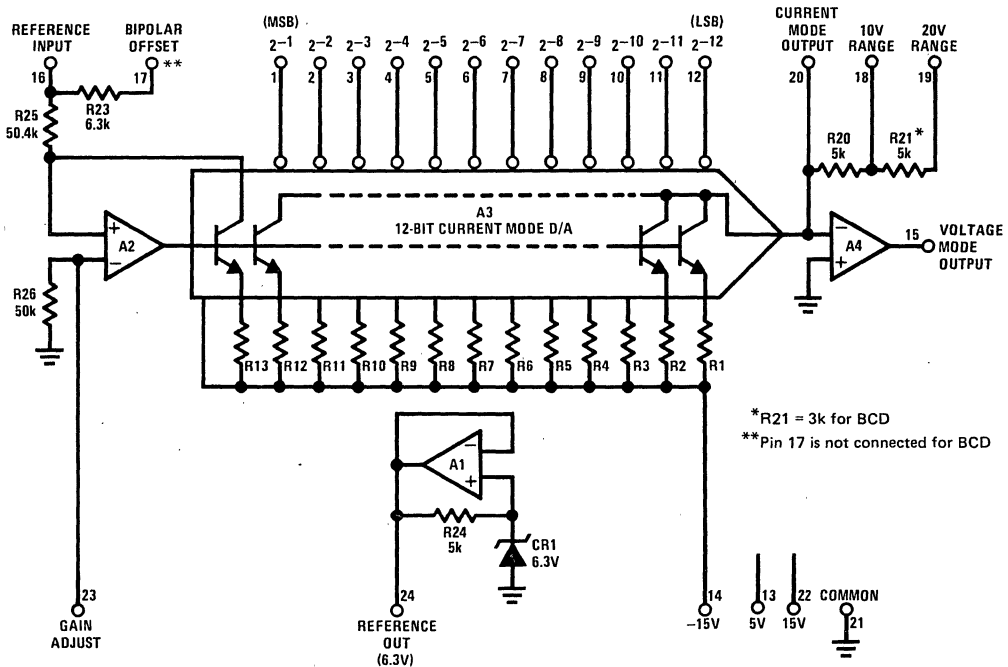
The DAC1280 series is a family of precision, low cost, fully self-contained digital-to-analog converters. The devices include 12 precision current switches, a 12-bit thin film resistor network, output amplifier, buffered internal reference, and several precision resistors, which allow the user to tailor his system needs to accommodate a variety of bipolar and unipolar output voltage and current ranges. Logic inputs are TTL, DTL and CMOS compatible, and are available in complementary binary (CBI) and complementary BCD (CCD) coding formats. In all instances, a logic low ($\leq 0.8V$) turns a given bit ON, and a logic high ($\geq 2V$) turns a given bit OFF. Internally supplied resistor options provide low drift bipolar output voltage ranges of $\pm 2.5V$, $\pm 5V$, $\pm 10V$, and unipolar ranges of 0 to 5V or 0 to 10V. Current mode output is also available 0 to 2 mA (binary models) and 1.25 mA (BCD models).

The entire series is available in a rugged side-brazed ceramic 24-lead DIP.

Features

- Completely self-contained with no external components required
- $\pm 1/2$ LSB linearity
- Standard power supplies: $\pm 15V$, 5V
- TTL, DTL, CMOS compatible binary or BCD
- $\pm 2.5V$, $\pm 5V$, $\pm 10V$, 0 to 5V, 0 to 10V voltage outputs
- 0 to 2 mA, 0 to 1.25 mA current output
- Internal reference
- Fast settling time: 300 ns current mode, 2.5 μs voltage mode
- Pin compatible with DAC80 and DAC85 series
- Full military temperature range operation

Block Diagram



Absolute Maximum Ratings

| | |
|---|-----------------|
| Supply Voltage (V+ and V-) | ±18V |
| Logic Supply Voltage (VCC) | 10V |
| Logic Input Voltage | -0.7V, 18V |
| Reference Input Voltage (VREF) | 0V, 18V |
| Power Dissipation | (See graph) |
| Short-Circuit Duration (Pins 15, 20 and 24) | Continuous |
| Operating Temperature Range | |
| DAC1285HD, DAC1286HD | -55°C to +125°C |
| DAC1285HCD, DAC1286HCD } | |
| DAC1280HCD, DAC1287HCD } | -25°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics DAC1285H, DAC1285HC, DAC1280HC Binary D/A (Notes 1 and 2)

| PARAMETER | CONDITIONS | DAC1285HD | | | DAC1285HCD | | | DAC1280HCD | | | UNITS |
|-----------------------------------|---|------------------------------------|-------|------|------------|-------|------|------------|-------|------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 12 | | | 12 | | | 12 | | | Bits |
| Linearity Error | T _A = 25°C | | | ±1/2 | | | ±1/2 | | | ±1 | LSB |
| | T _{MIN} ≤ T _A ≤ T _{MAX} . (Note 3) | | | ±1/2 | | | ±1/2 | | | ±2 | LSB |
| Differential Non-Linearity | | | ±1/2 | | | ±1/2 | | | ±1/2 | | LSB |
| Zero-Scale Error (Offset) | (Notes 4 and 5) | | ±0.05 | | | ±0.05 | | | ±0.05 | | % FSR |
| Zero-Scale Drift (Offset Drift) | Unipolar, T _{MIN} ≤ T _A ≤ T _{MAX} | | ±1 | | | ±1 | | | ±1 | | ppm of FSR/°C |
| | Bipolar, T _{MIN} ≤ T _A ≤ T _{MAX} | | ±3 | ±10 | | ±3 | ±15 | | ±10 | | ppm of FSR/°C |
| Full-Scale Error (Gain Error) | (Note 5) | | ±0.1 | | | ±0.1 | | | ±0.1 | | % of FSR |
| Full-Scale Drift (Gain Drift) | T _{MIN} ≤ T _A ≤ T _{MAX} | | | ±20 | | | ±30 | | ±10 | | ppm/°C |
| Output Voltage Range | Using Internally Supplied Resistors | ±2.5, ±5.0, ±10, 0 to +5, 0 to +10 | | | | | | | | | V |
| Output Voltage Swing | R _L ≥ 5 kΩ, Pin 15 | ±10 | ±12 | | ±10 | ±12 | | ±10 | ±12 | | V |
| Output Short-Circuit Current | Pin 15 | | ±20 | | | ±20 | | | ±20 | | mA |
| Output Impedance | Pin 15, Closed Loop | | 0.05 | | | 0.05 | | | 0.05 | | Ω |
| Current Mode Output Range | Unipolar, Pin 20 | 0 to -2 mA | | | | | | | | | mA |
| | Bipolar, Pin 20 | ±1.0 | | | | | | | | | |
| Current Mode Compliance | | ±2.5 | | | ±2.5 | | | ±2.5 | | | V |
| Current Mode Output Impedance | Unipolar | | 15 | | | 15 | | | 15 | | kΩ |
| | Bipolar | | 4.4 | | | 4.4 | | | 4.4 | | kΩ |
| Reference Voltage | -2 mA ≤ I _{REF} ≤ 2 mA | 6.0 | 6.3 | 6.6 | 6.0 | 6.3 | 6.6 | | 6.3 | | V |
| Logic "1" Input Voltage (Bit OFF) | | 2.0 | | | 2.0 | | | 2.0 | | | V |
| Logic "0" Input Voltage (Bit ON) | | | | 0.8 | | | 0.8 | | | 0.8 | V |
| Logic "1" Input Current | V _{IN} = 2.5V | | 1 | 10 | | 1 | 10 | | 1 | 10 | μA |
| Logic "0" Input Current | V _{IN} = 0V | | -10 | -100 | | -10 | -100 | | -10 | -100 | μA |
| Power Supply Current | I+ | | 10 | | | 10 | | | 10 | | mA |
| | I- | | 25 | | | 25 | | | 25 | | mA |
| | I _{CC} | | 20 | | | 20 | | | 20 | | mA |
| Power Supply Sensitivity | | | 0.002 | | | 0.002 | | | 0.002 | | % of FSR/%V |

DC Electrical Characteristics

DAC1286H, DAC1286HC, DAC1287HC BCD D/A (Notes 1 and 2)

| PARAMETER | CONDITIONS | DAC1286HD | | | DAC1286HCD | | | DAC1287HCD | | | UNITS |
|-----------------------------------|--|------------|----------|------------|------------|----------|------------|------------|----------|------------|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Resolution | | 3 | | | 3 | | | 3 | | | Digits |
| Linearity Error | $T_A = 25^\circ\text{C}$ | | | $\pm 1/2$ | | | $\pm 1/2$ | | | ± 1 | LSB |
| | $T_{\text{MIN}} \leq T_A \leq T_{\text{MAX}}$, (Note 3) | | | $\pm 1/2$ | | | $\pm 1/2$ | | | ± 1 | LSB |
| Differential Non-Linearity | | | | $\pm 1/2$ | | | $\pm 1/2$ | | | $\pm 1/2$ | LSB |
| Zero-Scale Error (Offset Error) | (Notes 4 and 5) | | | ± 0.05 | | | ± 0.05 | | | ± 0.05 | % FSR |
| Zero-Scale Drift (Offset Drift) | Unipolar, $T_{\text{MIN}} \leq T_A \leq T_{\text{MAX}}$ | | | ± 1 | | | ± 1 | | | ± 1 | ppm of FSR/ $^\circ\text{C}$ |
| Full-Scale Error (Gain Error) | (Note 5) | | | ± 0.1 | | | ± 0.1 | | | ± 0.1 | % of FSR |
| Full-Scale Drift (Gain Drift) | $T_{\text{MIN}} \leq T_A \leq T_{\text{MAX}}$ | | | ± 20 | | | ± 30 | | | ± 10 | ppm/ $^\circ\text{C}$ |
| Output Voltage Range | Using Internally Supplied Resistors | 0 to +10 | | | | | | | | | V |
| Output Voltage Swing | $R_L \geq 5\text{ k}\Omega$ | ± 10 | ± 12 | | ± 10 | ± 12 | | ± 10 | ± 12 | | V |
| Output Short-Circuit Current | | | ± 20 | | | ± 20 | | | ± 20 | | mA |
| Output Impedance | Pin 15, Closed Loop | | 0.05 | | | 0.05 | | | 0.05 | | Ω |
| Current Mode Output Range | Unipolar, Pin 20 | 0 to -1.25 | | | | | | | | | mA |
| Current Mode Compliance | | ± 2.5 | | | ± 2.5 | | | ± 2.5 | | | V |
| Current Mode Output Impedance | | | 15 | | | 15 | | | 15 | | k Ω |
| Reference Voltage | $-2\text{ mA} \leq I_{\text{REF}} \leq 2\text{ mA}$ | 6.0 | 6.3 | 6.6 | 6.0 | 6.3 | 6.6 | | 6.3 | | V |
| Logic "1" Input Voltage (Bit OFF) | | 2.0 | | | 2.0 | | | 2.0 | | | V |
| Logic "0" Input Voltage (Bit ON) | | | | 0.8 | | | 0.8 | | | 0.8 | V |
| Logic "1" Input Current | $V_{\text{IN}} = 2.5\text{V}$ | | 1 | 10 | | 1 | 10 | | 1 | 10 | μA |
| Logic "0" Input Current | $V_{\text{IN}} = 0\text{V}$ | | -10 | -100 | | -10 | -100 | | -10 | -100 | μA |
| Power Supply Current | I+ | | 10 | | | 10 | | | 10 | | mA |
| | I- | | 25 | | | 25 | | | 25 | | mA |
| | I _{CC} | | 20 | | | 20 | | | 20 | | mA |
| Power Supply Sensitivity | | | 0.002 | | | 0.002 | | | 0.002 | | % of FSR/%V |

Note 1: Unless otherwise specified, these specifications apply for $V^+ = 15\text{V}$, $V^- = -15\text{V}$ and $V_{\text{CC}} = 5\text{V}$ over the entire temperature range -55°C to $+125^\circ\text{C}$ for DAC1285HD and DAC1286HD, and -25°C to $+85^\circ\text{C}$ for DAC1285HCD, DAC1280HCD, DAC1286HCD and DAC1287HCD. For specified operation, the internal reference (pin 24) must be connected to the reference input (pin 16). The specifications are guaranteed after 30 seconds of warm-up after power turn-on.

Note 2: All typical values are for $T_A = 25^\circ\text{C}$.

Note 3: These specifications apply to the limited temperature range $T_{\text{MIN}} = -25^\circ\text{C}$ to $T_{\text{MAX}} = +85^\circ\text{C}$ for DAC1285HD and DAC1286HD, and $T_{\text{MIN}} = 0^\circ\text{C}$ to $T_{\text{MAX}} = +70^\circ\text{C}$ for DAC1285HCD, DAC1280HCD, DAC1286HCD and DAC1287HCD. For the entire temperature range, double the above specifications.

Note 4: FSR means "full-scale range" and is 20V for $\pm 10\text{V}$ range, 10V for $\pm 5\text{V}$, etc.

Note 5: Externally adjustable to zero.

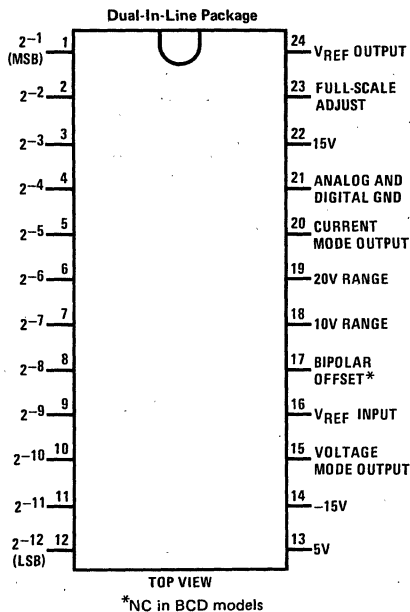
AC Electrical Characteristics

$T_A = 25^\circ\text{C}$, (Note 6)

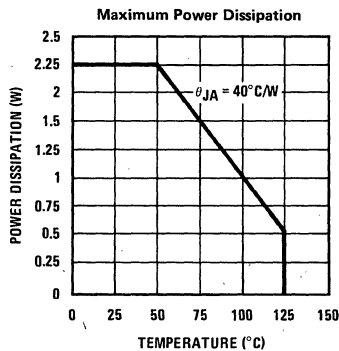
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-----|-----|-----|------------------|
| Voltage Mode ± 1 LSB Settling Time DAC1285, DAC1286 | $V_E \leq 1\text{ mV}$ | | 1.5 | 3.0 | μs |
| | $V_E \leq 5\text{ mV}$ | | 1.5 | 3.0 | μs |
| Voltage Mode Full-Scale Settling Time | $V_E \leq 1\text{ mV}$ | | 2.5 | 5.0 | μs |
| Current Mode Full-Scale Settling Time | $R_L = 100\Omega$ | | 300 | | ns |
| Voltage Mode Slew Rate | $-10\text{V} \leq V_{\text{OUT}} \leq +10\text{V}$ | | 20 | | V/ μs |

Note 6: Not tested, guaranteed by design.

Connection Diagram



Typical Performance Characteristics



Functional Description

The DAC1280 series is a sophisticated D/A building block. The user is encouraged to read the following applications information before applying power to the device. Refer to National Semiconductor Application Notes AN-156 and AN-159 for additional applications information.

Selection of power supplies is important in applications requiring 0.01% accuracy. The $\pm 15V$ supplies should be well regulated ($\pm 15V \pm 0.1\%$ with less than 0.5 mVrms of output noise and ripple.

To realize full speed capability of the device, all 3 power supply leads should be bypassed no further than 1/2 inch

from the device, with 1 μF tantalum electrolytic capacitors in parallel with 0.01 μF ceramic disc capacitors.

VOLTAGE MODE OPERATION

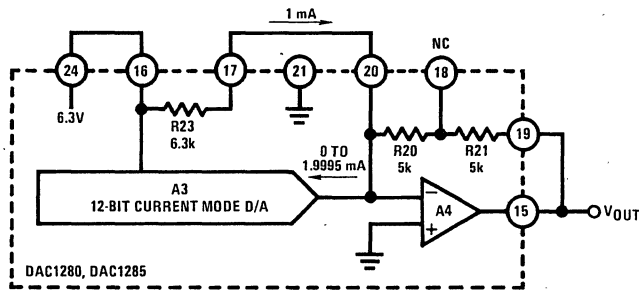
The DAC1280, DAC1285 binary and DAC1286, DAC1287 BCD D/A's provide internal scaling resistors which permit a wide range of bipolar and unipolar output configurations. Bipolar output formats of $\pm 2.5V$, $\pm 5V$, $\pm 10V$ and unipolar formats of 0 to 5V and 0 to 10V are possible using resistor strap options included within the device. Table I and Figures 1-4 summarize the proper pin connections required for these formats.

Functional Description (Continued)

TABLE I. Output Voltage/Current Ranges for DAC1280 Series

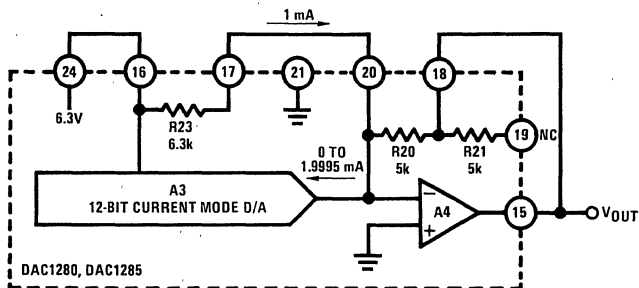
| OUTPUT VOLTAGE RANGE | DIGITAL INPUT CODE | CONNECT PIN 15 TO | CONNECT PIN 16 TO | CONNECT PIN 17 TO | CONNECT PIN 19 TO |
|----------------------|-----------------------------|-------------------|-------------------|-------------------|-------------------|
| ±10V | Complementary Offset Binary | 19 | 24 | 20 | 15 |
| ±5V | Complementary Offset Binary | 18 | 24 | 20 | NC |
| ±2.5V | Complementary Offset Binary | 18 | 24 | 20 | 20 |
| +10V | Complementary Binary | 18 | 24 | 21* | NC |
| +5V | Complementary Binary | 18 | 24 | 21* | 20 |
| ±1 mA | Complementary Offset Binary | NC | 24 | 20 | NC |
| -2 mA | Complementary Binary | NC | 24 | 21* | NC |
| +10V | Complementary BCD | 19 | 24 | NC | 15 |
| -1.25 mA | Complementary BCD | NC | 24 | NC | NC |

*Optional, no connection necessary



$$\begin{aligned}
 V_{OUT} &= (0 \text{ to } 1.9995 \text{ mA}) (R20 + R21) - (6.3V/R23)(R21 + R22) \\
 &= (0 \text{ to } 1.9995 \text{ mA}) (10k) - (1 \text{ mA}) (10k) \\
 &= -10V \text{ to } +9.995V \\
 1 \text{ LSB} &= 20V/4096 = 4.88 \text{ mV}
 \end{aligned}$$

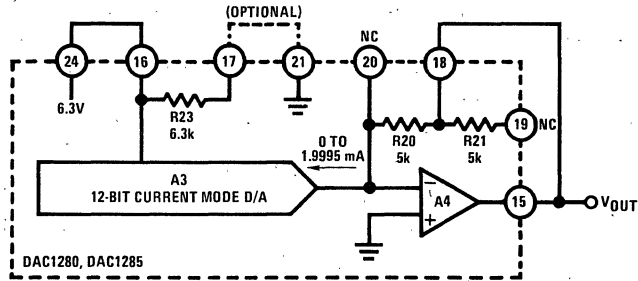
FIGURE 1. ±10V Bipolar Operation



$$\begin{aligned}
 V_{OUT} &= (0 \text{ to } 1.9995 \text{ mA}) (R20) - (R20/R23)(6.3V) \\
 &= (0 \text{ to } 1.9995 \text{ mA}) (5k) - (5k/6.3k) (6.3V) \\
 &= -5V \text{ to } 4.9975V \\
 1 \text{ LSB} &= 10V/4096 = 2.44 \text{ mV}
 \end{aligned}$$

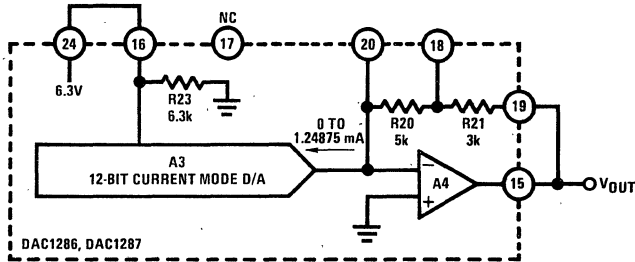
FIGURE 2. ±5V Bipolar Operation

Functional Description (Continued)



$$\begin{aligned}
 V_{OUT} &= (0 \text{ to } 1.9995 \text{ mA}) (R20) \\
 &= (0 \text{ to } 1.9995 \text{ mA}) (5k) \\
 &= 0 \text{ to } 9.9976V \\
 1 \text{ LSB} &= 2.44 \text{ mV}
 \end{aligned}$$

FIGURE 3. 10V Unipolar Operation



$$\begin{aligned}
 V_{OUT} &= (0 \text{ to } 1.24875 \text{ mA}) (R20 + R21) \\
 &= (0 \text{ to } 1.24875 \text{ mA}) (8k) \\
 &= 0 \text{ to } 9.990V \\
 1 \text{ LSB} &= 10 \text{ mV}
 \end{aligned}$$

FIGURE 4. 10V BCD Operation

CURRENT MODE OPERATION

Current mode applications which make use of an external op amp, comparator, or a resistive load are possible with the DAC1280 series using pin 20. When an external op amp is used, the internal scaling resistors should be utilized to minimize full-scale drift. Configurations shown in Table I apply directly. Figure 5 shows one application using an external fast operational amplifier.

Current mode operation into a resistive load should also utilize the internally supplied resistors. A compliance restriction of $\pm 2.5V$ at pin 20 is required for operation in the current output mode.

OFFSET AND FULL-SCALE ADJUST

The DAC1280 series may be offset and full-scale adjusted using the circuit shown in Figure 6. Offset voltage should be adjusted first. A logic "1" ($\geq 2V$) should be

applied to all logic inputs. In bipolar mode, the offset is adjusted to equal minus full-scale. In unipolar mode, the offset is adjusted to read 0V at the output. Full-scale is then adjusted by applying a logic "0" ($\leq 0.8V$) to all inputs for binary operation. For BCD, apply 011001100110 input coding. The range of R1 and R2 shown in Figure 6 is approximately $\pm 0.2\%$ of full-scale for the values shown.

A 30 second "warm-up" period should be allowed (after power turn-on) before making the above adjustments.

LOGIC INPUT CODING

The logic inputs to the DAC1280 series are complementary; i.e., a given bit is turned ON by an active low input. Table II summarizes input status for unipolar and bipolar codes.

Functional Description (Continued)

REFERENCE SUPPLY

The DAC1280 series is supplied with an internal 6.3V reference supply voltage (pin 24). In order to obtain the specified performance, pin 24 should be connected to the Reference Voltage Input (pin 16). Since the reference is buffered by an op amp, the reference may be used externally at currents up to 5 mA. The reference output is short-circuit limited to a nominal 20 mA. An external reference voltage may be used with the DAC1280 series. Voltage values between 5V and 11V will work satisfactorily. Full-scale current may be predicted by:

$$I_{\text{FULL-SCALE}} = (V_{\text{REF}}) (0.317381 \text{ mA/V})$$

LOGIC INPUT COMPATIBILITY

The design of the current mode switches in the DAC1280 series give the device true TTL compatibility. It is TTL compatible over the entire operating temperature range and is independent of the reference voltage and V_{CC} . Furthermore, since the input breakdown ratings are in excess of 18V, the DAC1280 series may be driven directly from high (or low) voltage CMOS.

TABLE II

| CODE TYPE | INPUT CODE (Note 7) | | | | | | | | | | | OUTPUT STATE | UNIPOLAR OUTPUT RANGES | | | |
|---------------|---------------------|---|---|---|---|---|---|---|---|---|-----|--------------|------------------------|---------|---------------------|------------|
| | MSB | | | | | | | | | | LSB | | 0 to 10V | 0 to 5V | 0–2 mA 0–1.25 mA | |
| Unipolar | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Full-Scale | 9.9976V | 4.9988V | –1.9995 mA |
| Complementary | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 LSB ON | 0.0024V | 0.0012V | 0.0005 mA |
| Binary | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Zero-Scale | 0.0000V | 0.0000V | 0.0000 mA |
| Unipolar | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | Full-Scale | 9.990V | | 1.2488 mA |
| Complementary | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 LSB ON | 0.010V | | 0.00125 mA |
| BCD | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Zero-Scale | 0.000V | | 0.0000 mA |

| CODE TYPE | INPUT CODE (Note 7) | | | | | | | | | | | OUTPUT STATE | BIPOLAR OUTPUT VOLTAGE RANGES | | | | |
|---------------|---------------------|---|---|---|---|---|---|---|---|---|-----|--------------|-------------------------------|-----------|----------|----------|------------|
| | MSB | | | | | | | | | | LSB | | ±10V | ±5V | ±2.5V | ±1 mA | |
| Bipolar | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Full-Scale | 9.9951V | –4.9976V | 2.4988V | –0.9995 mA |
| Complementary | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Half-Scale | 0.0000V | 0.0000V | 0.0000V | 0.0000 mA |
| Binary | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 LSB ON | –9.9951V | –4.9976V | –2.4988V | 0.9995 mA |
| | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Zero-Scale | –10.0000V | –5.0000V | –2.5000V | 1.0000 mA |

Note 7: Logic input sense is such that an active low ($V_{\text{IN}} \leq 0.8\text{V}$) turns a given bit ON and is represented as a logic "0" in the table.

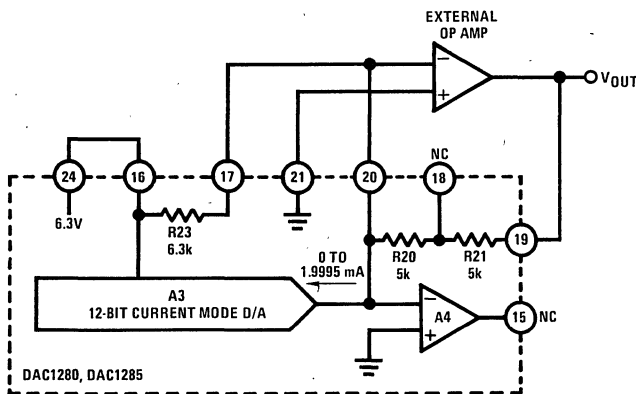


FIGURE 5. ±10V Bipolar Operation with External Operational Amplifier

Functional Description (Continued)

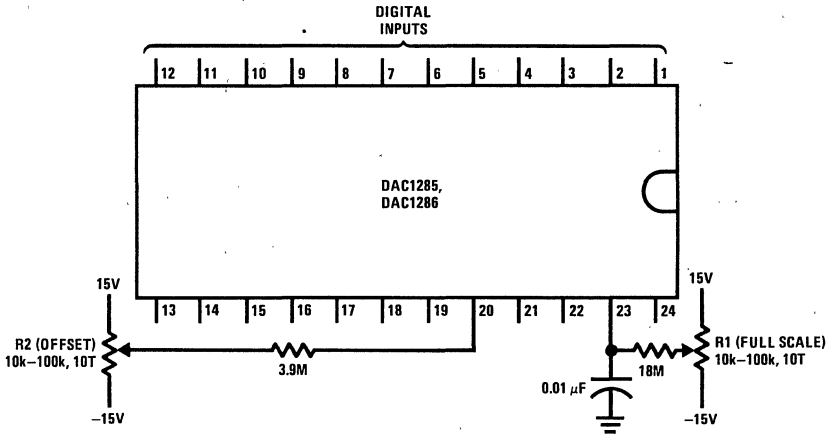


FIGURE 6. Full-Scale and Adjustment Circuits

Ordering Information

| PART NUMBER | | 25°C LINEARITY | PACKAGE | TEMPERATURE RANGE |
|-------------|------------|-------------------|---------|----------------------|
| BINARY | BCD | | | |
| DAC1285HD | DAC1286HD | 0.01% | DIP | -55°C to +125°C |
| DAC1285HCD | DAC1286HCD | 0.01% | DIP | -25°C to +85°C |
| DAC1280HCD | DAC1287HCD | 0.025% | DIP | -25°C to +85°C |

*See NS Package D24A



A to D, D to A

DM2502, DM2503, DM2504 Successive Approximation Registers

General Description

The DM2502, DM2503 and DM2504 are 8-bit and 12-bit TTL registers designed for use in successive approximation A/D converters. These devices contain all the logic and control circuits necessary in combination with a D/A converter to perform successive approximation analog-to-digital conversions.

The DM2502 has 8 bits with serial capability and is not expandable.

The DM2503 has 8 bits and is expandable without serial capability.

The DM2504 has 12 bits with serial capability and expandability.

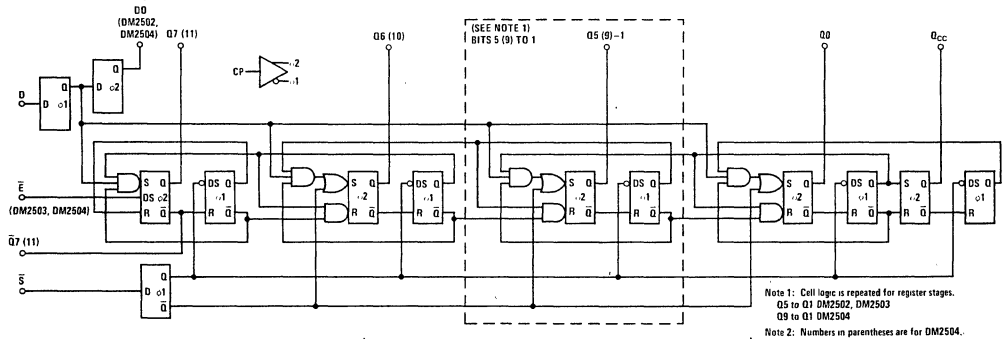
All three devices are available in ceramic DIP, ceramic flatpak, and molded Epoxy-B DIPs. The DM2502,

DM2503 and DM2504 operate over -55°C to $+125^{\circ}\text{C}$; the DM2502C, DM2503C and DM2504C operate over 0°C to $+70^{\circ}\text{C}$.

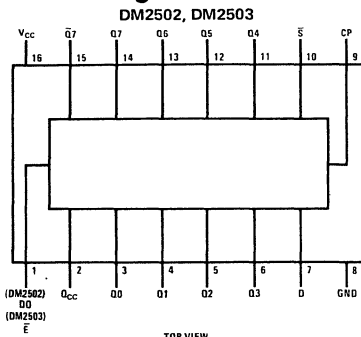
Features

- Complete logic for successive approximation A/D converters
- 8-bit and 12-bit registers
- Capable of short cycle or expanded operation
- Continuous or start-stop operation
- Compatible with D/A converters using any logic code
- Active low or active high logic outputs
- Use as general purpose serial-to-parallel converter or ring counter

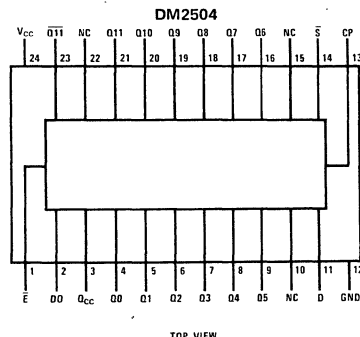
Logic Diagram



Connection Diagrams (Dual-In-Line and Flat Packages)



Order Number DM2502J, DM2502CJ, DM2503J or DM2503CJ
 See NS Package J16A
 Order Number DM2502CN or DM2503CN
 See NS Package N16A
 Order Number DM2502W, DM2502CW, DM2503W, or DM2503CW
 See NS Package W16A



Order Number DM2504F or DM2504CF
 See NS Package F24A
 Order Number DM2504J or DM2504CJ
 See NS Package J24A
 Order Number DM2504CN
 See NS Package N24A

DM2502, DM2503, DM2504

8

Absolute Maximum Ratings (Note 1)

| | |
|--|-----------------|
| Supply Voltage | 7V |
| Input Voltage | 5.5V |
| Output Voltage | 5.5V |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Operating Conditions

| | MIN | MAX | UNITS |
|---------------------------|------|------|-------|
| Supply Voltage, V_{CC} | | | |
| DM2502C, DM2503C, DM2504C | 4.75 | 5.25 | V |
| DM2502, DM2503, DM2504 | 4.5 | 5.5 | V |
| Temperature, T_A | | | |
| DM2502C, DM2503C, DM2504C | 0 | +70 | °C |
| DM2502, DM2503, DM2504 | -55 | +125 | °C |

Electrical Characteristics (Notes 2 and 3) $V_{CC} = 5.0V$, $T_A = 25^\circ C$, $C_L = 15$ pF, unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-----|------|------|---------|
| Logical "1" Input Voltage (V_{IH}) | $V_{CC} = \text{Min}$ | 2.0 | | | V |
| Logical "1" Input Current (I_{IH}) | $V_{CC} = \text{Max}$ | | | | |
| CP Input | $V_{IH} = 2.4V$ | | 6 | 40 | μA |
| D, \bar{E} , \bar{S} Inputs | $V_{IH} = 2.4V$ | | 6 | 80 | μA |
| All Inputs | $V_{IH} = 5.5V$ | | | 1.0 | mA |
| Logical "0" Input Voltage (V_{IL}) | $V_{CC} = \text{Min}$ | | | 0.8 | V |
| Logical "0" Input Current (I_{IL}) | $V_{CC} = \text{Max}$ | | | | |
| CP, \bar{S} Inputs | $V_{IL} = 0.4V$ | | -1.0 | -1.6 | mA |
| D, \bar{E} Inputs | $V_{IL} = 0.4V$ | | -1.0 | -3.2 | mA |
| Logical "1" Output Voltage (V_{OH}) | $V_{CC} = \text{Min}$, $I_{OH} = -0.48$ mA | 2.4 | 3.6 | | V |
| Output Short Circuit Current (Note 4) (I_{OS}) | $V_{CC} = \text{Max}$; $V_{OUT} = 0.0V$; Output High; CP, D, \bar{S} , High; \bar{E} Low | -10 | -20 | -45 | mA |
| Logical "0" Output Voltage (V_{OL}) | $V_{CC} = \text{Min}$, $I_{OL} = 9.6$ mA | | 0.2 | 0.4 | V |
| Supply Current (I_{CC}) | $V_{CC} = \text{Max}$, All Outputs Low | | | | |
| DM2502C | | | 65 | 95 | mA |
| DM2502 | | | 65 | 85 | mA |
| DM2503C | | | 60 | 90 | mA |
| DM2503 | | | 60 | 80 | mA |
| DM2504C | | | 90 | 124 | mA |
| DM2504 | | | 90 | 110 | mA |
| Propagation Delay to a Logical "0" From CP to Any Output (t_{pd0}) | | 10 | 18 | 28 | ns |
| Propagation Delay to a Logical "0" From \bar{E} to Q7 (Q11) Output (t_{pd0}) | CP High, \bar{S} Low DM2503, DM2503C, DM2504, DM2504C Only | | 16 | 24 | ns |
| Propagation Delay to a Logical "1" From CP to Any Output (t_{pd1}) | | 10 | 26 | 38 | ns |
| Propagation Delay to a Logical "1" From \bar{E} to Q7 (Q11) Output (t_{pd1}) | CP High, \bar{S} Low DM2503, DM2503C, DM2504, DM2504C Only | | 13 | 19 | ns |
| Set-Up Time Data Input ($t_{s(D)}$) | | -10 | 4 | 8 | ns |
| Set-Up Time Start Input ($t_{s(\bar{S})}$) | | 0 | 9 | 16 | ns |
| Minimum Low CP Width (t_{pWL}) | | | 30 | 42 | ns |
| Minimum High CP Width (t_{pWH}) | | | 17 | 24 | ns |
| Maximum Clock Frequency (f_{MAX}) | | 15 | 21 | | MHz |

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. Except for "Operating Temperature Range" they are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" provides conditions for actual device operation.

Note 2: Unless otherwise specified min/max limits apply across the -55°C to +125°C temperature range for the DM2502, DM2503 and DM2504, and across the 0°C to +70°C range for the DM2502C, DM2503C and DM2504C. All typicals are given for $V_{CC} = 5.0V$ and $T_A = 25^\circ C$.

Note 3: All currents into device pins shown as positive, out of device pins as negative, all voltages referenced to ground unless otherwise noted. All values shown as max or min on absolute value basis.

Note 4: Only one output at a time should be shorted.

Application Information

OPERATION

The registers consist of a set of master latches that act as the control elements in the device and change state on the input clock high-to-low transition and a set of slave latches that hold the register data and change on the input clock low-to-high transition. Externally the device acts as a special purpose serial-to-parallel converter that accepts data at the D input of the register and sends the data to the appropriate slave latch to appear at the register output and the DO output on the DM2502 and DM2504 when the clock goes from low-to-high. There are no restrictions on the data input; it can change state at any time except during a short interval centered about the clock low-to-high transition. At the same time that data enters the register bit the next less significant bit register is set to a low ready for the next iteration.

The register is reset by holding the \bar{S} (Start) signal low during the clock low-to-high transition. The register synchronously resets to the state Q7 (11) low, and all the remaining register outputs high. The Q_{CC} (Conversion Complete) signal is also set high at this time. The \bar{S} signal should not be brought back high until after the clock low-to-high transition in order to guarantee correct resetting. After the clock has gone high resetting the register, the \bar{S} signal must be removed. On the next clock low-to-high transition the data on the D input is set into the Q7 (11) register bit and the Q6 (10) register bit is set to a low ready for the next clock cycle. On the next clock low-to-high transition data enters the Q6 (10) register bit and Q5 (9) is set to a low. This operation is repeated for each register bit in turn until the register has been filled. When the data goes into Q0, the Q_{CC} signal goes low, and the register is inhibited from further change until reset by a Start signal.

The DM2502, DM2503 and DM2504 have a specially tailored two-phase clock generator to provide non-overlapping two-phase clock pulses (i.e., the clock waveforms intersect below the thresholds of the gates

they drive). Thus, even at very slow dV/dt rates at the clock input (such as from relatively weak comparator outputs), improper logic operation will not result.

LOGIC CODES

All three registers can be operated with various logic codes. Two's complement code is used by offsetting the comparator $1/2$ full range + $1/2$ LSB and using the complement of the MSB ($\bar{Q}7$ or $\bar{Q}11$) with a binary D/A converter. Offset binary is used in the same manner but with the MSB (Q7 or Q11). BCD D/A converters can be used with the addition of illegal code suppression logic.

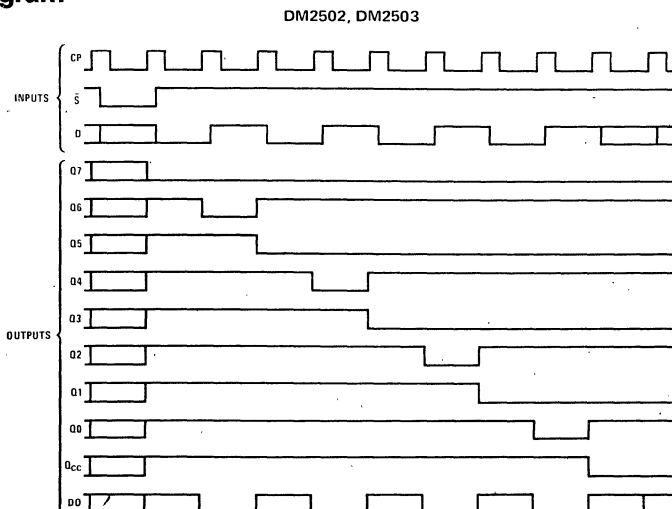
ACTIVE HIGH OR ACTIVE LOW LOGIC

The register can be used with either D/A converters that require a low voltage level to turn on, or D/A converters that require a high voltage level to turn the switch on. If D/A converters are used which turn on with a low logic level, the resulting digital output from the register is active low. That is, a logic "1" is represented as a low voltage level. If D/A converters are used that turn on with a high logic level then the digital output is active high; a logic "1" is represented as a high voltage level.

EXPANDED OPERATION

An active low enable input, \bar{E} , on the DM2503 and DM2504 allows registers to be connected together to form a longer register by connecting the clock, D, and \bar{S} inputs in parallel and connecting the Q_{CC} output of one register to the \bar{E} input of the next less significant register. When the start signal resets the register, the \bar{E} signal goes high, forcing the Q7 (11) bit high and inhibiting the register from accepting data until the previous register is full and its Q_{CC} goes low. If only one register is used the \bar{E} input should be held at a low logic level.

Timing Diagram



Application Information (Continued)

SHORT CYCLE

If all bits are not required, the register may be truncated and conversion time saved by using a register output going low rather than the Q_{CC} signal to indicate the end of conversion. If the register is truncated and operated in the continuous conversion mode, a lock-up condition may occur on power turn-on. This condition can be avoided by making the start input the OR function of Q_{CC} and the appropriate register output.

COMPARATOR BIAS

To minimize the digital error below $\pm 1/2$ LSB, the comparator must be biased. If a D/A converter is used which requires a low voltage level to turn on, the comparator should be biased $+1/2$ LSB. If the D/A converter requires a high logic level to turn on, the comparator must be biased $-1/2$ LSB.

Definition of Terms

CP: The clock input of the register.

D: The serial data input of the register.

DO: The serial data out. (The D input delayed one bit).

\bar{E} : The register enable. This input is used to expand the length of the register and when high forces the Q7 (11) register output high and inhibits conversion. When not used for expansion the enable is held at a low logic level (ground).

Q_i i = 7 (11) to 0: The outputs of the register.

Q_{CC} : The conversion complete output. This output remains high during a conversion and goes low when a conversion is complete.

Q7 (11): The true output of the MSB of the register.

$\bar{Q}7$ (11): The complement output of the MSB of the register.

\bar{S} : The start input. If the start input is held low for at least a clock period the register will be reset to Q7 (11) low and all the remaining outputs high. A start pulse that is low for a shorter period of time can be used if it meets the set-up time requirements of the \bar{S} input.

Truth Table

DM2502, DM2503

| TIME | INPUTS | | | OUTPUTS ¹ | | | | | | | | | | |
|------|--------|---|-----------|----------------------|-----------------|----|----|----|----|----|----|----|----|----------|
| | t_n | D | \bar{S} | \bar{E}^2 | D0 ³ | Q7 | Q6 | Q5 | Q4 | Q3 | Q2 | Q1 | Q0 | Q_{CC} |
| 0 | X | L | L | L | X | X | X | X | X | X | X | X | X | X |
| 1 | D7 | H | L | L | X | L | H | H | H | H | H | H | H | H |
| 2 | D6 | H | L | L | D7 | D7 | L | H | H | H | H | H | H | H |
| 3 | D5 | H | L | L | D6 | D7 | D6 | L | H | H | H | H | H | H |
| 4 | D4 | H | L | L | D5 | D7 | D6 | D5 | L | H | H | H | H | H |
| 5 | D3 | H | L | L | D4 | D7 | D6 | D5 | D4 | L | H | H | H | H |
| 6 | D2 | H | L | L | D3 | D7 | D6 | D5 | D4 | D3 | L | H | H | H |
| 7 | D1 | H | L | L | D2 | D7 | D6 | D5 | D4 | D3 | D2 | L | H | H |
| 8 | D0 | H | L | L | D1 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | L | H |
| 9 | X | H | L | L | D0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | L |
| 10 | X | X | L | L | X | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | L |
| | X | X | H | L | X | H | NC | NC | NC | NC | NC | NC | NC | NC |

Note 1: Truth table for DM2504 is extended to include 12 outputs.

Note 2: Truth table for DM2502 does not include \bar{E} column or last line in truth table shown.

Note 3: Truth table for DM2503 does not include D0 column.

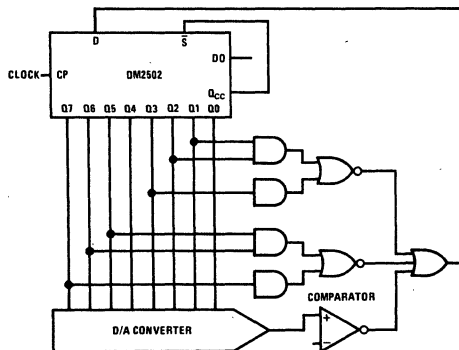
H = High Voltage Level

L = Low Voltage Level

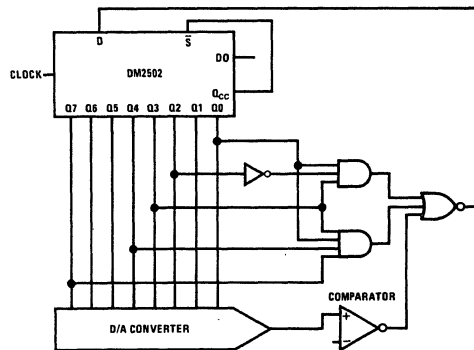
X = Don't Care

NC = No Change

Typical Applications



Active High

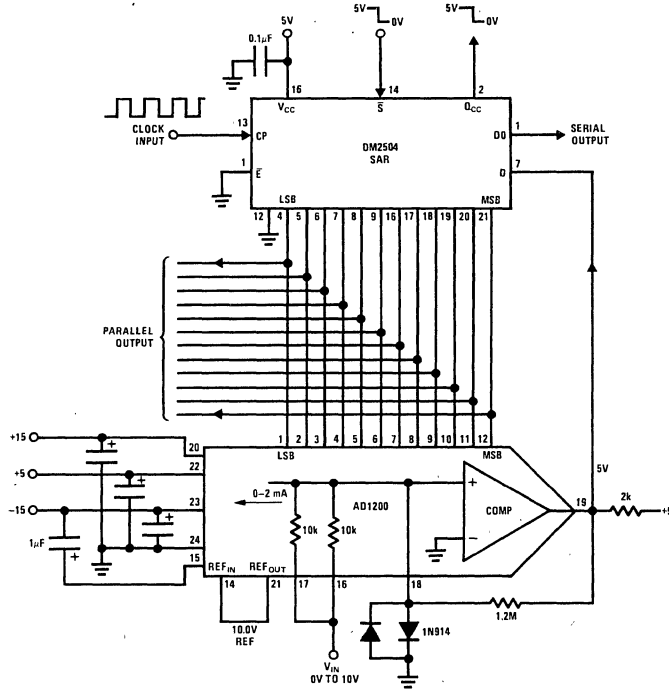


Active Low

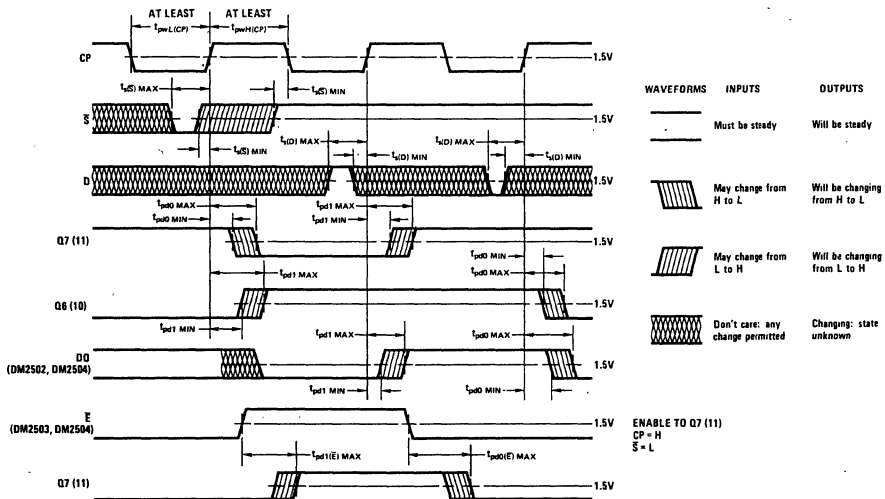
BCD Illegal Code Suppression

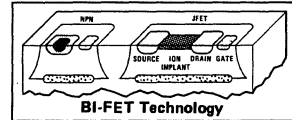
Typical Applications (Continued)

High Speed 12-Bit A/D Converter



Switching Time Waveforms





LF13300 Integrating A/D Analog Building Block

General Description

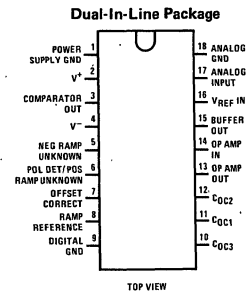
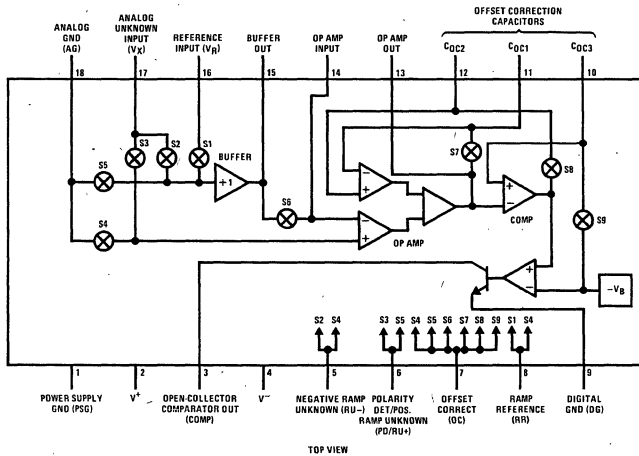
The LF13300 is the analog section of a precision integrating analog-to-digital (A/D) system. JFET and bipolar transistors (BI-FET) are combined on the same chip to provide a high input impedance unity gain buffer, comparator and integrator, along with 9 JFET analog switches. The LF13300 has sufficient resolution to construct up to a 4 1/2-digit Digital Panel Meter (DPM) or a 12-bit (plus sign) Data Acquisition System and is specifically designed for use with either the ADB4510 BCD digital building block or the ADB1200 (MM5863)* 12-bit binary building block.

*See ADB1200 (MM5863) data sheet for more information.

Features

- Rugged JFETs allow blow-out free handling
- High input impedance: 10,000 MΩ typ
- Automatic offset correction
- Analog circuitry can be physically and electrically isolated from high noise digital circuits
- Analog input range of ±11V with ±15V supplies
- Wide power supply voltage range ±5V to ±18V
- TTL and CMOS compatible logic
- Can interface directly with microprocessors
- Versatile: can be used as a 12-bit plus sign binary A/D, 4 1/2-digit, 3 3/4-digit and 3 1/2-digit Digital Panel Meter (DPM)
- Low cost

Block and Connection Diagrams



Order Number LF13300D
See NS Package D18A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | ±18V |
| Power Dissipation, (Note 1) | 570 mW |
| Junction Temperature | 110°C |
| Storage Temperature Range | -65°C to +150°C |
| Operating Temperature Range | 0°C to +70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

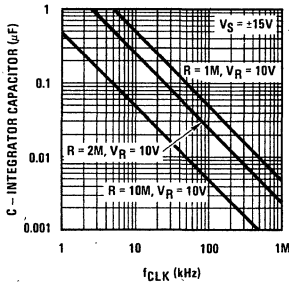
Electrical Characteristics (V_S = ±15V, T_A = 25°C, unless otherwise noted)

| PARAMETER | CONDITIONS | TEST CIRCUIT | LF13300 | | | UNITS |
|--|--|--------------|---------|--------|------|-------|
| | | | MIN | TYP | MAX | |
| Analog Input Current, I _{IN} | V _X = 0 | 1, 2 | | 80 | 500 | pA |
| | T _{MIN} ≤ T _A ≤ T _{MAX} | | | | 5 | nA |
| Analog Input Voltage Range | V _X Adjusted until I _{IN} ≥ 10 nA | 1, 2 | | | ±11 | V |
| Analog Input Resistance | V _X = 0 | 1, 2 | | 10,000 | | MΩ |
| Reference Input Currents, I _R | V _R = 10V | | | 1 | 100 | nA |
| | T _{MIN} ≤ T _A ≤ T _{MAX} | 3 | | | 10 | μA |
| Reference Input Voltage Range | V _R Adjusted until I _R ≥ 10 μA | 3 | 0 | | 11 | V |
| Reference Input Resistance | V _R = 10V | 3 | | 1000 | | MΩ |
| Offset Correction Voltage, -V _B | | 4 | | -12 | | V |
| Offset Correction | | 5 | | 20 | 2000 | pA |
| Input Current, I _{OC} | | 5 | | | 20 | nA |
| Op Amp Slew Rate | | 6 | | 10 | | V/μs |
| Op Amp Bandwidth | | 7 | | 3 | | MHz |
| Buffer Slew Rate | | 9 | | 25 | | V/μs |
| Comparator Response Time | 200 μV Input Stop, 100 μV Overdrive | 11 | | 2.5 | | μs |
| Comparator Output Saturation Voltage | V _{CC} = 5V, R _L = 2k, T _{MIN} ≤ T _A ≤ T _{MAX} | 11 | | 0.25 | 0.4 | V |
| Logic "1" Input Voltage | All Switching Input Pins 5, 6, 7, 8, T _{MIN} ≤ T _A ≤ T _{MAX} | | 2.0 | | 5.0 | V |
| Logic "0" Input Voltage | All Switching Input Pins 5, 6, 7, 8, T _{MIN} ≤ T _A ≤ T _{MAX} | | -2.0 | | 0.8 | V |
| Logic Input Current | All Switching Input Pins 5, 6, 7, 8, 0 ≤ V _L ≤ 5V, T _{MIN} ≤ T _A ≤ T _{MAX} | | | 15 | 50 | μA |
| Power Supply Voltage Range ±V _S | V _R ≤ V ⁺ - 3V, V _{IN} = 0V T _{MIN} ≤ T _A ≤ T _{MAX} | | ±4.75 | | ±18 | V |
| | | | | 3.0 | | mA |
| | | | | -5.5 | | mA |
| | | | | | ±11 | mA |

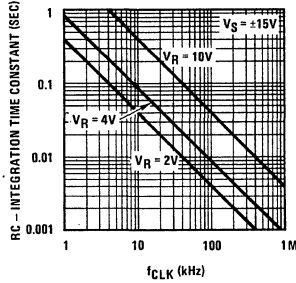
Note 1: For operating at elevated temperatures, the LF13300 in the dual-in-line package must be derated based on the thermal resistance of 100°C/W junction to ambient.

Typical Performance Characteristics

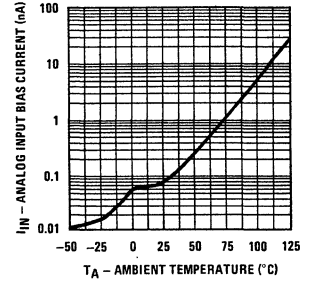
Integrator Capacitance, $C \sqrt{f_{CLK}}$ for Different Integrator Resistances, R



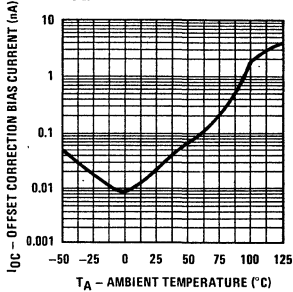
Integration Time Constant (RC) vs f_{CLK} for Different Reference Voltages, V_R



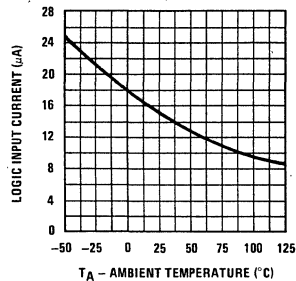
Analog Input Bias Current, I_{IN} , $V_X = 0V$, vs Temperature



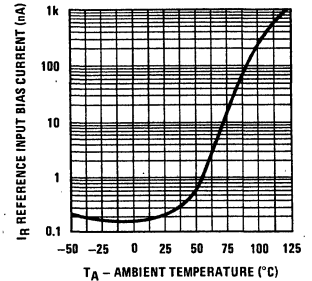
Offset Correction Bias Current, I_{OL} , vs Temperature



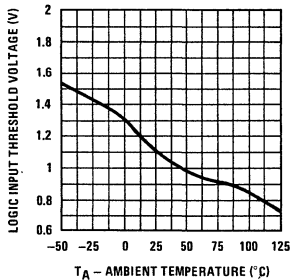
Logic Input Current vs Temperature



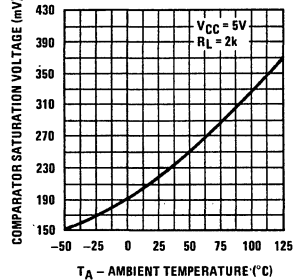
Reference Input Bias Current, I_R , vs Temperature



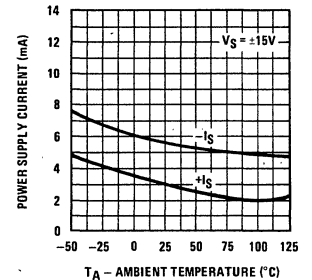
Logic Input Threshold Voltage vs Temperature



Comparator Saturation Voltage vs Temperature



Power Supply Current vs Temperature



Functional Description

The LF13300 goes through the following 5 states during normal cycle: 1) Offset Correction; 2) Polarity Determination; 3) Initialization; 4) Ramp Unknown; 5) Ramp Reference.

Offset Correction Description (Figure 1)

The Offset Correction scheme will drive the input of the comparator to its switching threshold when the analog input is zero and the timing components, RC, are bypassed.

The Offset Correction input (OC) is driven high, closing switches S4-S9.

The offset voltages are assigned as follows: V_{OS1} - the input offset voltage of the buffer; V_{OS2} - the input offset voltage of A1; V_{OS3} - the input offset voltage of A2; V_{OS4} - the input offset voltage of the comparator.

S5 grounds the input of the buffer so that its output voltage is simply V_{OS1} . S6 bypasses R to keep the integration time constant, RC, from affecting the circuit operation. S4 makes the total equivalent input voltage to A1 be $-V_{OS1} - V_{OS2}$. S7 puts the op amp in a unity gain configuration with respect to the input of A2. S8 keeps the output voltage of the op amp at $-V_B + V_{OS4} = -V_B'$ (the Offset Correction potential) since the comparator is placed inside the loop. C3 samples the output of the $-V_B$ generator. The voltage at the non-inverting input of A2 is $-V_B - V_{OS1} -$

Functional Description (Continued)

$V_{OS2} - V_{OS3} + V_{OS4} = V_1$. Thus, the sum of the offsets is stored on C1, and the differential voltage across the comparator is zero.

Polarity Determination (Figure 2)

The simplified diagram of the LF13300 in the Polarity Determination state is shown in Figure 2. S5 and S3 are closed during this period. S5 grounds the buffer input and V_X (the unknown voltage) is applied through S3 to the non-inverting input of A1. The equation that describes the op amp output voltage is given in Figure 2. When V_X is applied to A1 at t_1 , the output of the op amp slews to V_X and is integrated until t_2 , when S3 opens and S4 closes. At t_2 , V_{OUT} slews down by $-V_X$

leaving $\frac{1}{RC} \int_{t_2}^{t_2} V_X dt - V_{B'}$ at the op amp output.

Just before t_2 , the comparator senses the op amp output with respect to $-V_B$; the comparator output goes high if $V_X > 0$ and remains low if $V_X \leq 0$.

Initialization (Figure 1)

During initialization, the configuration is the same way as it is in the Offset Correction state and the op amp output is brought back to the Offset Correction potential $-V_{B'}$.

Ramp Unknown (Figures 2 and 3)

In the Ramp Unknown state, if $V_X \geq 0$, S3 and S5 are closed, as shown in Figure 2, and V_X is applied to the

+ input of the integrator. If $V_X < 0$, the device is connected as in Figure 3 with S2 and S4 closed. V_X is now applied through the buffer to the - input of the integrator. In either Ramp Unknown case, the op amp output ramps in the positive direction and V_X is applied to a high impedance JFET input.

Ramp Reference (Figure 4)

In this state, the LF13300 is configured with switches S1 and S4 closed. The reference voltage, V_R , a positive voltage, is applied to the buffer input and the op amp output ramps down until $V_{OUT} = -V_{B'}$ where the comparator will trip.

If V_X and V_R are assumed to be constant over their respective integration periods, the integrals of Figure 4 are reduced to,

$$\frac{V_X (t_4 - t_3)}{RC} = \frac{V_R (t_5 - t_4)}{RC}$$

or

$$\frac{V_X}{V_R} = \frac{t_5 - t_4}{t_4 - t_3}$$

Since $t_4 - t_3 = 4096$ clock periods and $t_5 - t_4$ can be measured in clock periods, $V_X/V_R = X/2^{12}$, where X is a digital binary output representing an analog input V_X with respect to V_R .

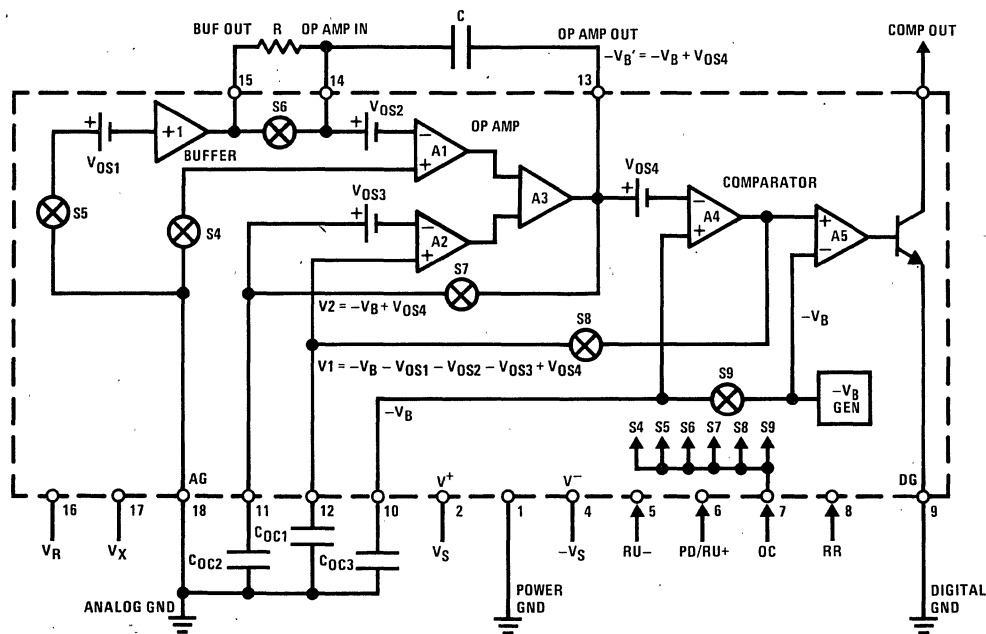


FIGURE 1. Offset Correction Circuit

Functional Description (Continued)

$$-V_B' + V_X + \frac{1}{RC} \int_{t_3}^{t_4} V_X dt: \text{Ramp Unknown for } V_X \geq 0$$

$$V_{OUT} =$$

$$-V_B' + V_X + \frac{1}{RC} \int_{t_1}^{t_2} V_X dt: \text{Polarity Determination}$$

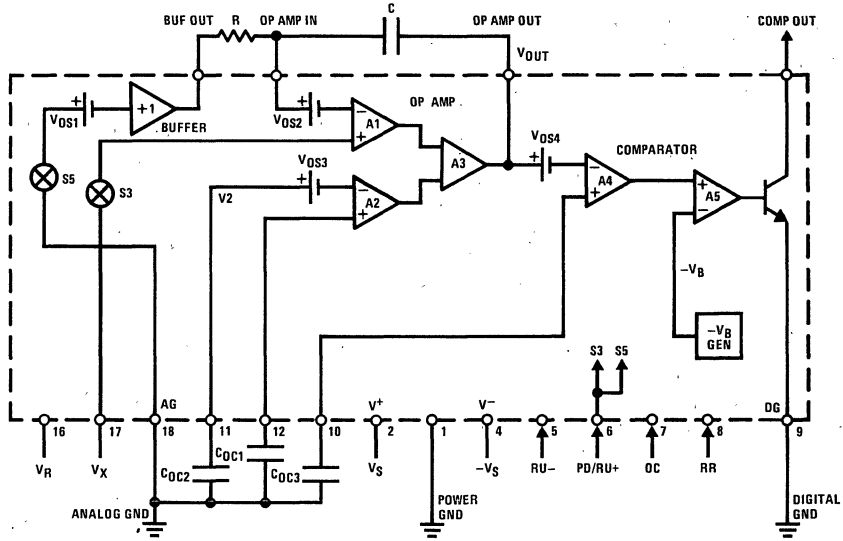


FIGURE 2. Polarity Determination Circuit or Ramp Unknown Circuit for $V_X \geq 0$

$$V_{OUT} = -V_B' + \frac{1}{RC} \int_{t_3}^{t_4} V_X dt: \text{Ramp Unknown for } V_X < 0$$

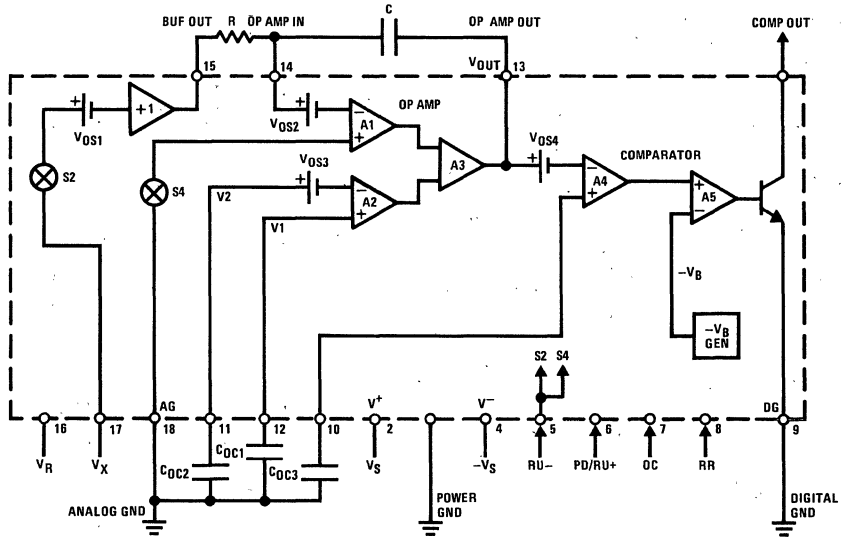
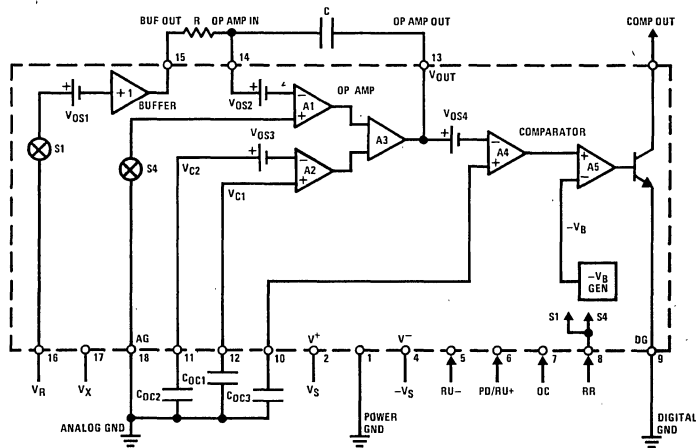


FIGURE 3. Ramp Unknown for $V_X < 0$

Functional Description (Continued)

$$V_{OUT}^* = -V_{B'} + \frac{1}{RC} \left(\int_{t_3}^{t_4} V_X dt - \int_{t_4}^{t_5} V_R dt \right)$$



*More accurately

$$V_{OUT} = -V_{B'} + \frac{1}{RC} \left(\int_{t_4}^{t_5+\Delta} V_R dt + \int_{t_3}^{t_4} V_X dt \right) + \delta$$

Where δ is the incremental voltage overdrive needed to fully switch the comparator and Δ is the sum of the additional time required to develop δ and the comparator propagation delay.

FIGURE 4. Ramp Reference Circuit

12-Bit A/D Converter Electrical Characteristics

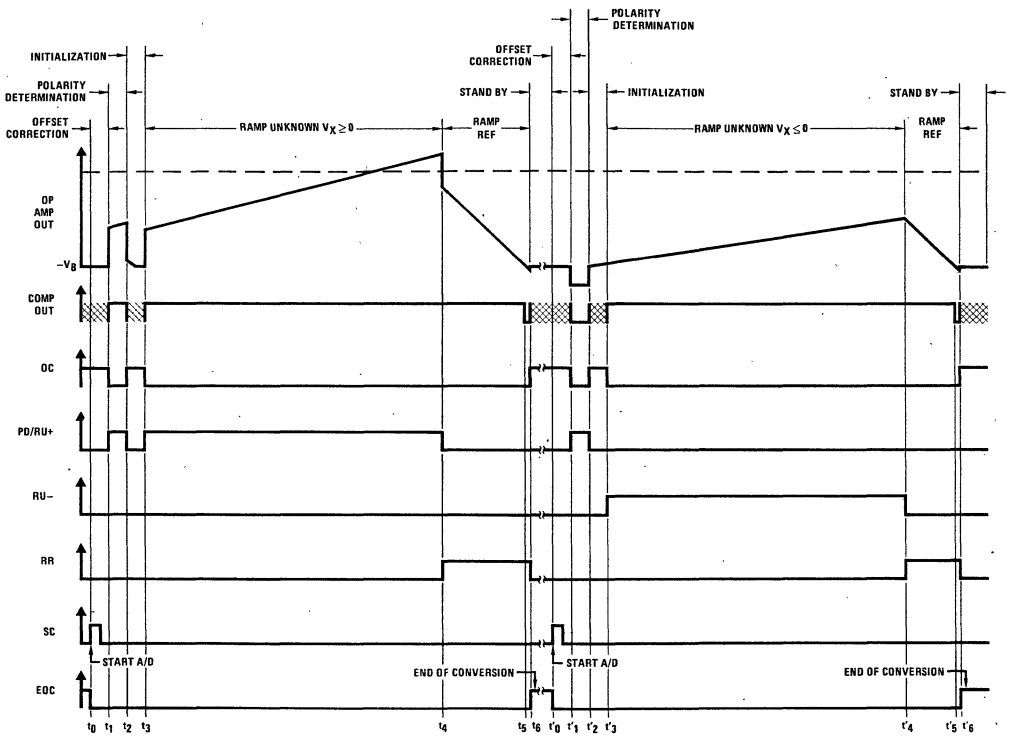
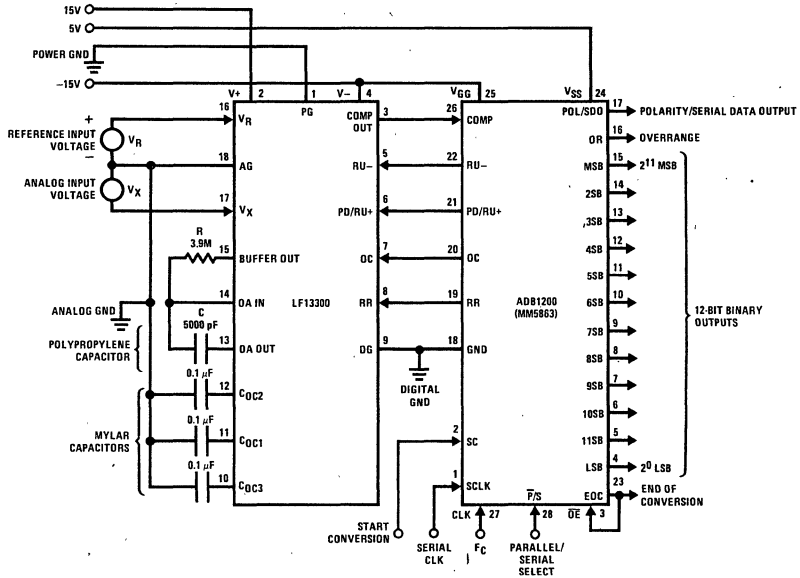
12-bit plus sign. (LF13300 with ADB1200 (MM5863)). ($V_R = 10.000V$, $F_C = 250$ kHz, $0^\circ C \leq T_A \leq +70^\circ C$ unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|--|----------|-----------|-----------|-----------------|
| Resolution (Note 3) | $V_R = 5.000V$, $-10V \leq V_X \leq +10V$ | 13 | | | Bits |
| | $F_C = 125$ kHz, $T_A = 25^\circ C$ | 14 | | | Bits |
| Non-Linearity | | | $\pm 1/8$ | $\pm 1/2$ | LSB |
| Ratiometric Gain Error (Def.) | $V_X = \pm 10.000V$, $T_A = 25^\circ C$, (Note 2) | | $\pm 1/2$ | ± 2 | LSB |
| Gain Error Drift | $V_X = 10.000V$ | | ± 1 | | ppm/ $^\circ C$ |
| Zero Reading Drift | $V_X = 0V$ | | ± 0.5 | | ppm/ $^\circ C$ |
| Analog Input Voltage Range | | ± 11 | ± 12 | | V |
| Analog Input Leakage Current | $V_X = 0V$, $T_A = 25^\circ C$ | | 80 | 500 | pA |
| Analog Input Resistance | $V_X = 0V$, $T_A = 25^\circ C$ | 100 | 1000 | | M Ω |
| Reference Input Voltage Range | V_R Varied, $T_A = 25^\circ C$ | 4 | | 12 | V |
| Reference Input Leakage Current | $V_R = 10.000V$, $T_A = 25^\circ C$ | | 1 | 100 | nA |
| Reference Input Resistance | $V_R = 10.000V$, $T_A = 25^\circ C$ | 100 | 1000 | | M Ω |
| Start Conversion Pulse Width | $V_{SC} = 2.4V$ | 2.4 | | | μs |
| Conversion Time | $V_{IN} = 10.000V$ $t_c = 8960/F_C$ | | | 36 | ms |
| 15V Supply Currents | LF13300, V^+ Current | | | 11 | mA |
| -15V Supply Currents | LF13300, V^- Current, ADB1200 (MM5863), V_{GG} Current | | 27 | 45 | mA |
| 5V Supply Currents | $V_{IN} = 0V$, ADB1200 (MM5863), V_{SS} Current | | 23 | 39 | mA |

Note 2: The A/D converter system must have been operational for a minimum of 30 seconds before this measurement is made. This is to relax the dielectric absorption effects of the integration capacitor, C.

Note 3: Polarity and Overrange outputs are considered as additional output bits.

12-Bit A/D Converter Circuit and Timing Diagrams



*Note. All TTL signal level.

FIGURE 5.

Application Hints

Increasing the Input Impedance of the LF13300, MM5863 12-Bit A/D Converter

The input impedance of the LF13300, ADB1200 (MM5863) A/D converter can be increased 1 to 2 orders of magnitude over the typical 1000 MΩ cited in the 12-bit A/D specifications by insuring that the signals that switch the LF13300 do not overlap. A circuit that eliminates switching overlap by introducing a Delay ($t_d \approx 3.3k \times 100 \text{ pF} \approx 300 \text{ ns}$ to the rising edge of the signals from the ADB1200 (MM5863) is shown in Figure 6. Figure 7 shows the operation of this circuit. The total delay time t_r' of the output will be equal to the inherent gate rise time, t_r , plus the RC delay, t_d . The fall time, t_f will be the basic gate delay.

Nulling the Residual Offset

The residual offset is $< 200 \mu\text{V}$ which is negligible for most applications. This can be reduced to $< 40 \mu\text{V}$ by lowering the clock frequency from 250 kHz to about 75 kHz. If a lower residual offset is required, we may trim out the remainder as shown in Figure 8. This circuit applies a negative step to the offset correction capacitor, C0C2, by means of a variable capacitor which is adjusted until charge injection imbalance of the offset correction switches are cancelled.

Eliminating Errors Due to Power Supply Noise

For many applications, power supply noise ($f \geq 10 \text{ Hz}$) causes errors which reduces the accuracy of the system. In most applications, noise can be adequately eliminated by putting a series resistor (100Ω) in the power supply line with a 10 μF tantalum capacitor connected at the power supply pins (Figure 9). The 10 μF capacitor is, in addition to the normal 0.1 μF ceramic disc capacitors, used as supply bypass capacitors.

Errors caused by noise on the negative supply, $-V_S$, can be further reduced by replacing, C0C3 with a 10 μF low leakage tantalum capacitor. Since $-V_B$ is 3V above $-V_S$, any noise appearing at $-V_S$ appears at $-V_B$; the 10 μF capacitor eliminates this noise.

Continuous Conversion Mode

For using the MM5863 in the continuous conversion mode, connect the end of conversion output, EOC (pin 23), to the output enable input, OE (pin 3), and connect the start conversion input, SC (pin 2) to 5V.

Miscellaneous

Since none of the output pins employ short-circuit protection, extreme care should be taken when bread-boarding or troubleshooting with the power ON.

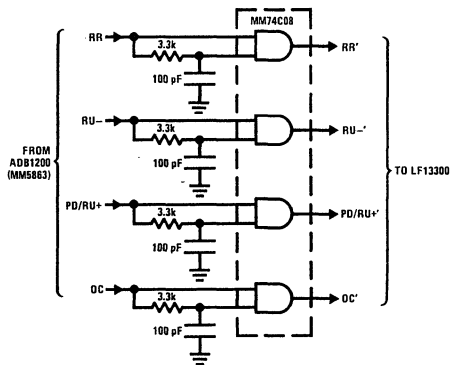


FIGURE 6. Overlap Elimination Circuit

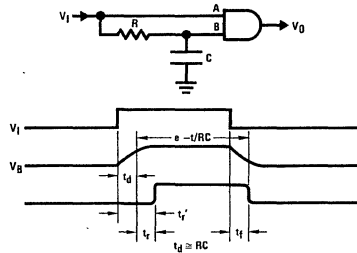


FIGURE 7. Rise Time Delay Circuit

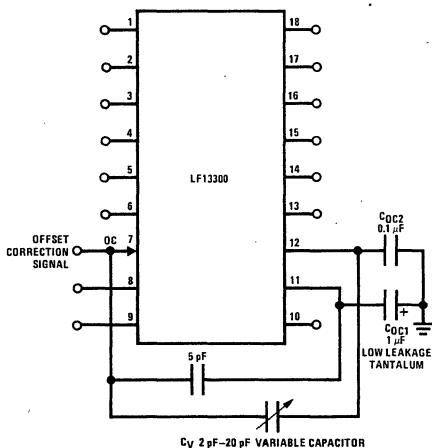


FIGURE 8. Residual Offset Nulling Circuit

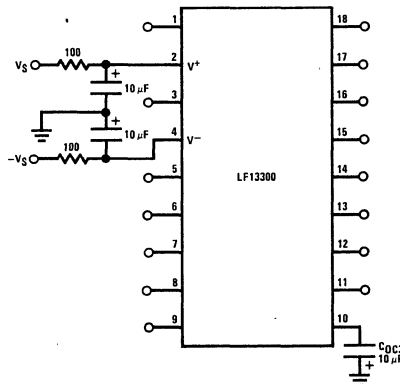
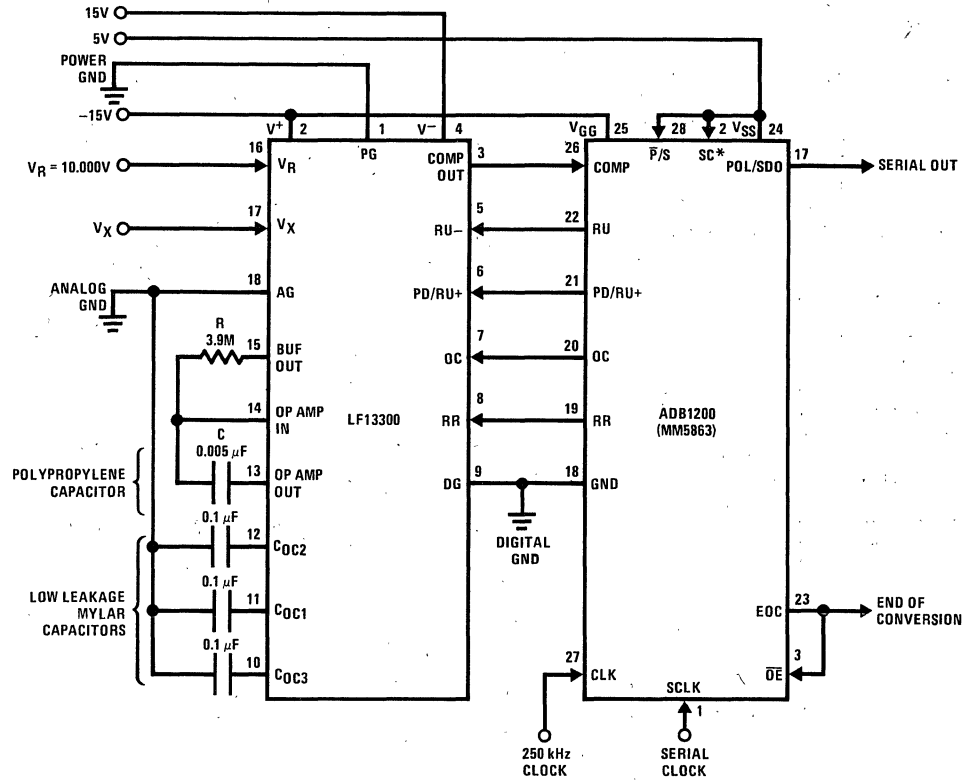


FIGURE 9. Power Supply Noise Reduction Circuit

Typical Applications



*SC at logic "1" for continuous conversion mode

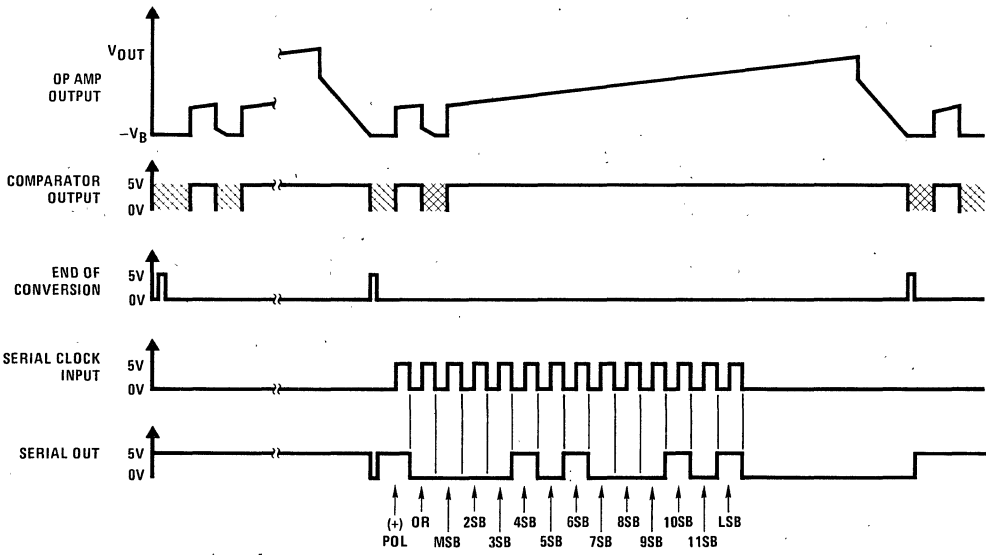
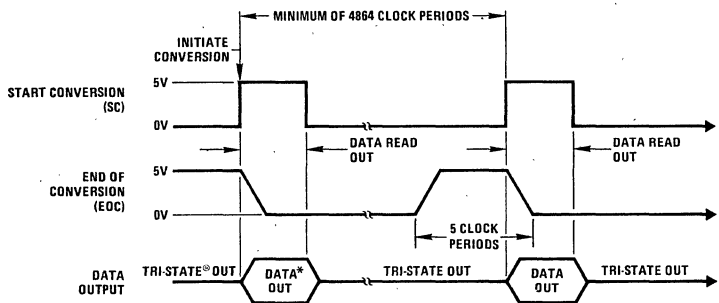
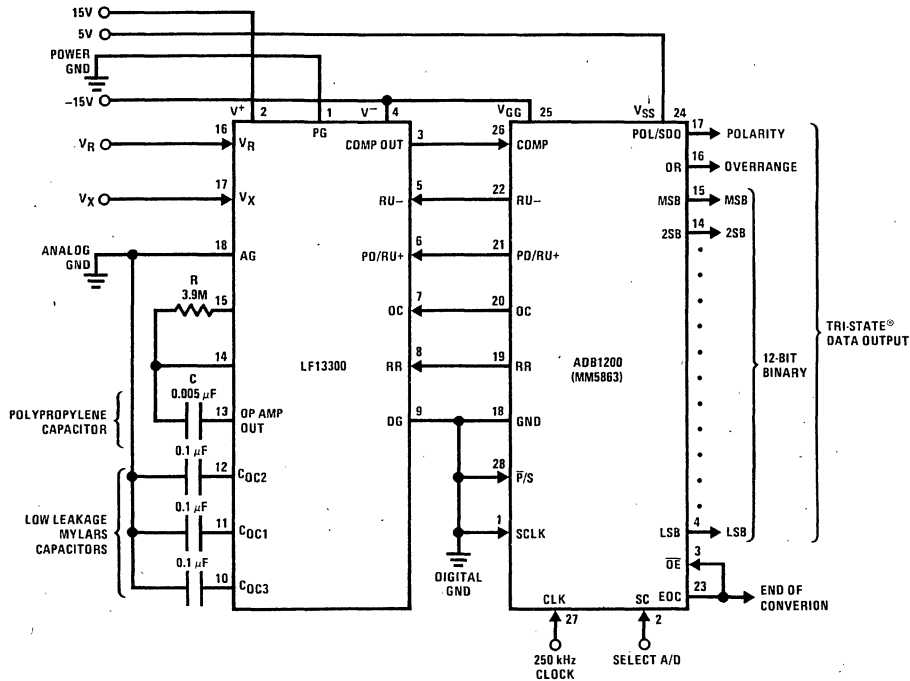


FIGURE 10. Continuous Conversion 12-Bit Plus Sign Serial Output A/D Using the LF13300 and the MM5863

Typical Applications (Continued)



* Note. Prior to the first conversion cycle, the data outputs will all be in a "1" state when the outputs are enabled (OE in "0" state).

FIGURE 11. 12-Bit Plus Sign A/D in Command Conversion Mode

4-Channel Differential Multiplexer with Autozeroed Instrumentation Amplifier and 12-Bit A/D Converter

Figure 12 shows a low speed, high accuracy, data acquisition unit where the analog input signal is acquired differentially and preconditioned through an LF352 monolithic instrumentation amplifier. To eliminate amplifier offset errors, autozeroing circuitry is added around the LF352 and is timed through the ADB1200 and flip-flop C. Flip-flops A and B form a 2-bit up counter for channel select.

The instrumentation amplifier is zeroed at power-up and after each conversion as shown in the timing diagram;

during autozero the multiplexer is disabled. When the system does polarity detection and A/D conversion, the LF352 is active and the multiplexer is enabled. The zeroing cycle for the LF13300 and the LF352 lasts for 256 clock periods, so the maximum clock frequency will depend upon the required accuracy and the minimum zeroing time of the instrumentation amplifier. Notice here that the system accuracy will be less than 12 bits since it will be affected by the gain linearity of the instrumentation amplifier.

For more details concerning data acquisition, see AN-156 and LF11508/LF11509 data sheet. For details on the instrumentation amplifier, see the LF352 data sheet.

Typical Applications (Continued)

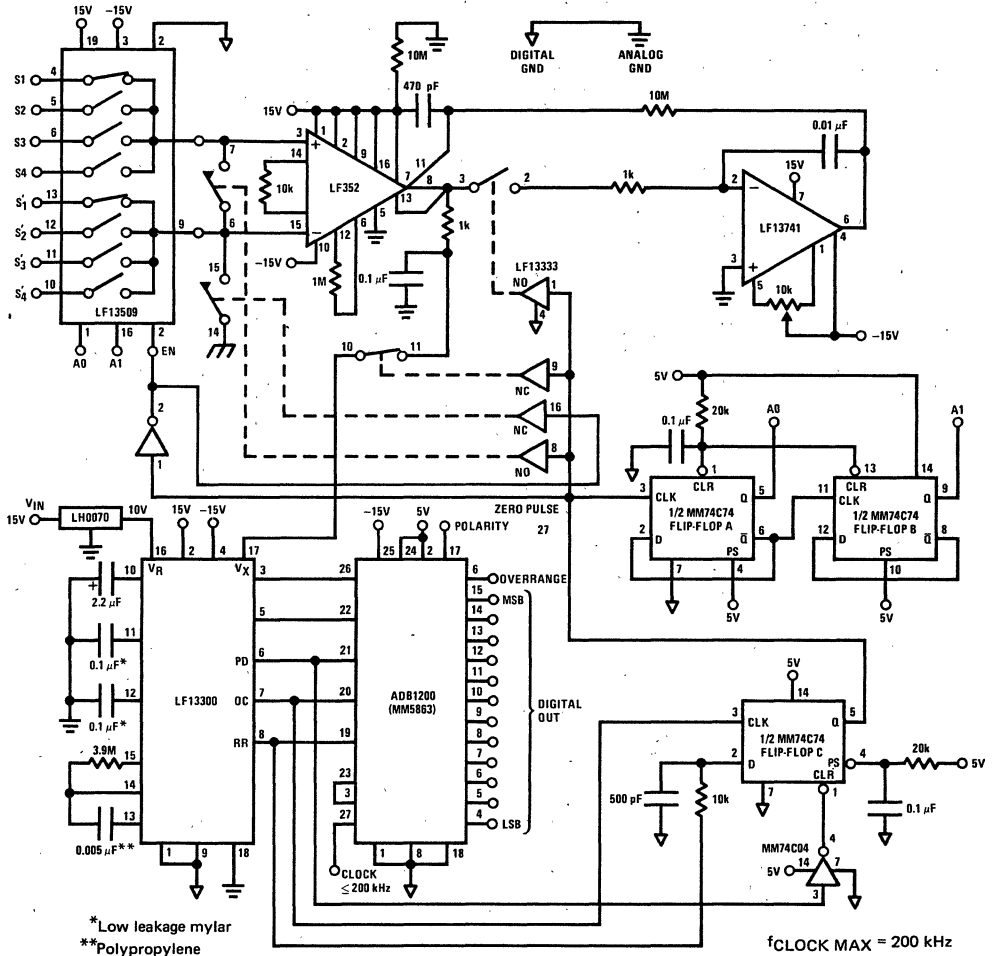


FIGURE 12. 4-Channel Differential Multiplexer with Autozeroed Instrumentation Amplifier and 12-Bit A/D Converter

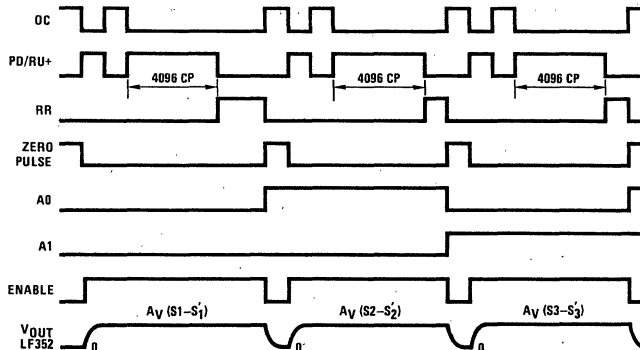
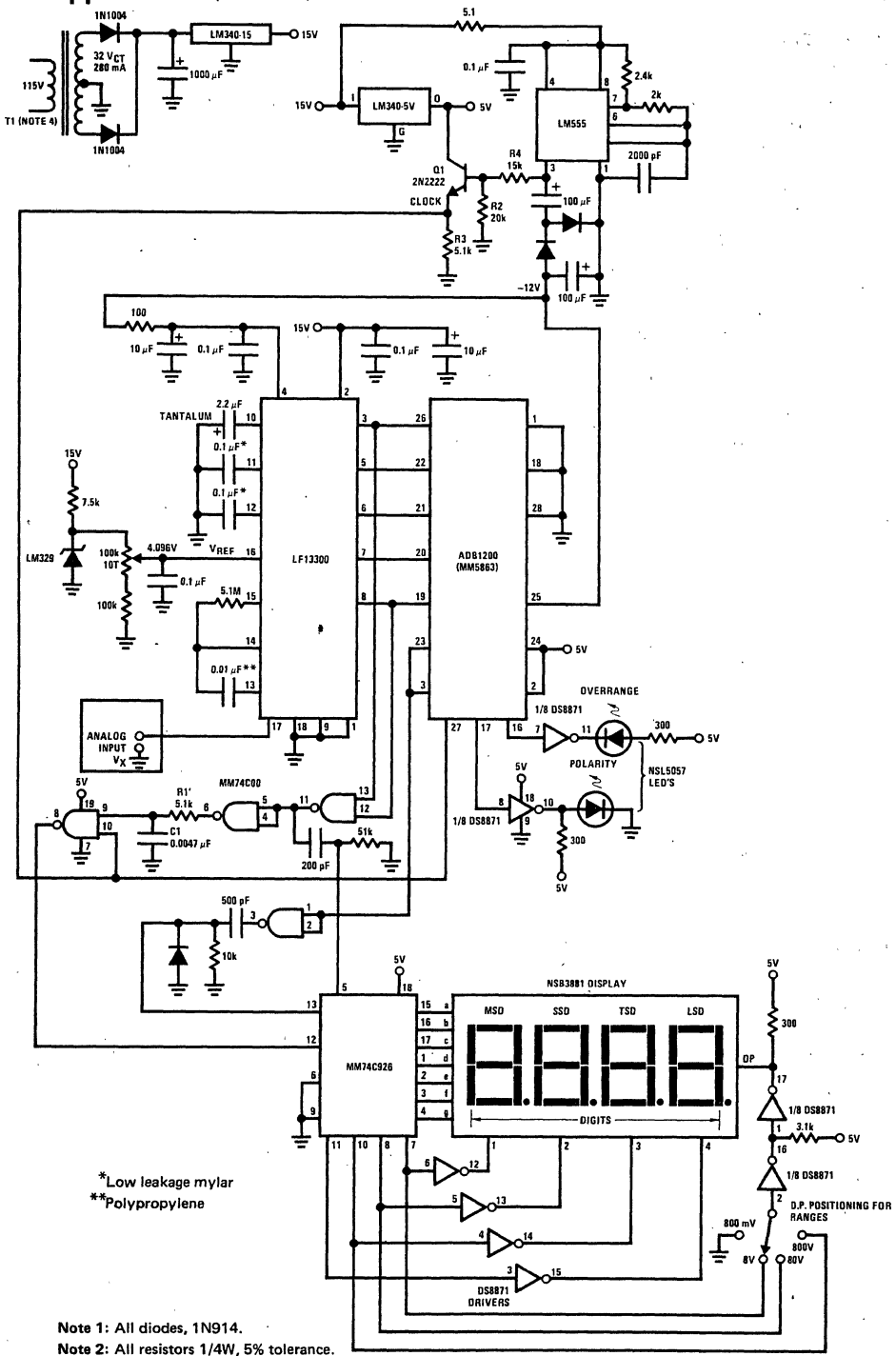


FIGURE 13. Timing Diagram for Figure 12

Typical Applications (Continued)



* Low leakage mylar
 ** Polypropylene

- Note 1: All diodes, 1N914.
- Note 2: All resistors 1/4W, 5% tolerance.
- Note 3: Circuit drawn for 8V full scale operation input scaling not shown.
- Note 4: Inductive components U4X003 or Microtran PC6714.

FIGURE 19. 3 3/4 Plus (±8191 Counts) and 3 1/2-Digit DPM Schematic Diagram

Typical Applications (Continued)

3 3/4 Plus Digit (± 8191 Counts)/3 1/2-Digit (± 1999 Counts) DPM

In this circuit of Figure 19, the LF13300 and ADB1200 interact as previously described. The CMOS counter (MM74C926, MM74C928) is connected to count clock pulses during the ramp reference cycle. The counts are latched into the display when the comparator output trips, (goes low), as shown in the timing diagram Figure 20.

The RC network consisting of R1 and C1 is a low pass filter that prohibits the fast transients that occur on the comparator output during Offset Correction from loading any erroneous counts into the counter.

The DPM is able to operate from a single 15V power supply with the aid of a dc-dc converter. The LM555 generates the negative voltages required in the circuit and also doubles as the clock. The combination of Q1, R2, R3 and R4 forms a level shift to convert the output swing of the LM555 to a 0V–5V swing that is compatible with the logic. The LM340–5 drops the incoming 15V to 5V for use by the logic circuits and the LED display.

This circuit can be a 3 3/4 plus digit DPM if the MM74C926 is used or a 3 1/2-digit DPM if the MM74C928 is used. These counters are pin compatible and physically interchangeable.

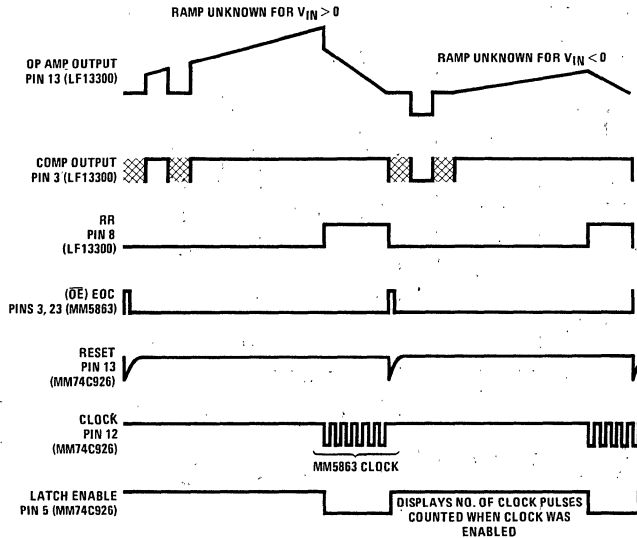


FIGURE 20. Timing Diagram for 3 3/4-Digit DVM

3 3/4-Digit DPM Electrical Characteristics

3 3/4 plus digits plus sign (± 8191 counts) DPM system characteristics. (Circuit as in Figure 18, $V_S = \pm 15V$, $V_R = 4.096V$, $T_A = 25^\circ C$, unless otherwise noted).

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|--|--------|-----------|-----------|-----------------|
| Resolution | $-8.2V \leq V_X \leq +8.2V$ | 16,382 | | | Counts |
| Nonlinearity | $V_{IN} = 4.000V$ | | $\pm 1/8$ | $\pm 1/2$ | Counts |
| Ratiometric Gain Error | $V_{IN} = 4.000V$ | | $\pm 1/2$ | ± 2 | Counts |
| Gain Error Drift | $V_{IN} = 4.000V, 0^\circ C \leq T_A \leq +70^\circ C$ | | ± 1 | | ppm/ $^\circ C$ |
| Zero Reading Drift | $V_{IN} = 0V$ | | ± 1 | | ppm/ $^\circ C$ |
| Analog Input Voltage Range | | | | ± 11 | V |
| Reference Input Voltage Range | Reference Varied | 0 | | +12 | V |
| Analog Input Leakage Current | $V_{IN} = 0V$ | | 80 | 500 | pA |
| Reference Input Leakage Current | | | 1 | 100 | nA |
| Analog Input Resistance | $V_{IN} = 0V$ | | 1000 | | M Ω |
| Conversion Time | $V_{IN} = 4.000V, f_C = 125$ kHz | | | 74 | ms |

Component Side Foil

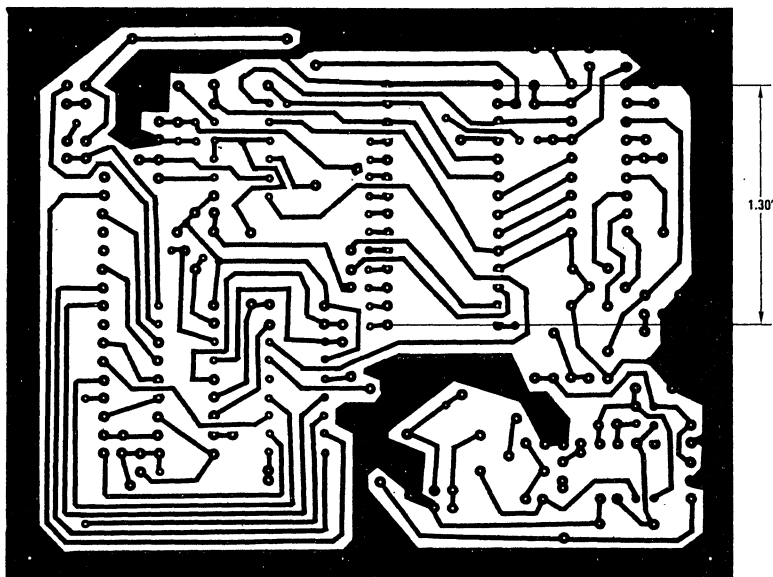


FIGURE 21. PC Board for 3 3/4 Plus (± 8191 Counts) and 3 1/2-Digit DPM

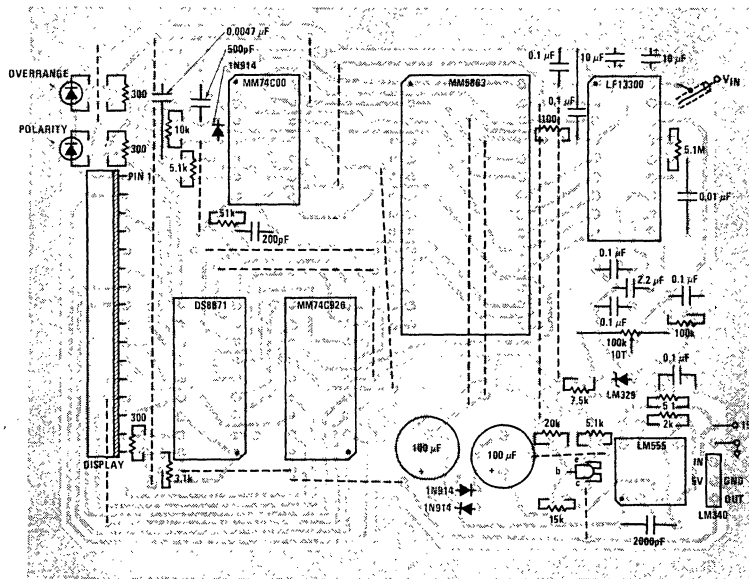
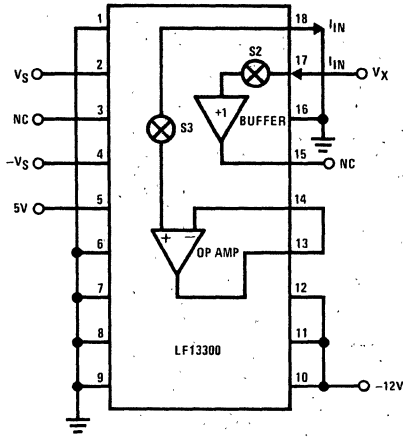


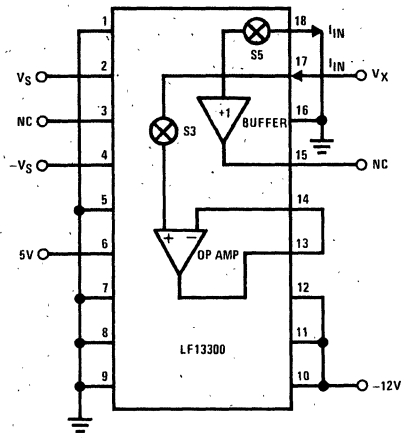
FIGURE 22. Stuffing Diagram for 3 3/4 Plus (± 8191 Counts) and 3 1/2-Digit DPM

AC Test Circuits

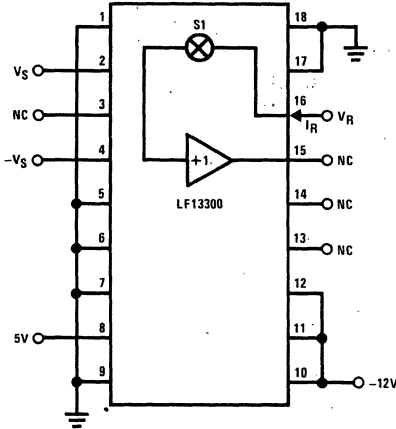
Test Circuit 1
Analog Input Characteristics Test with RU - High



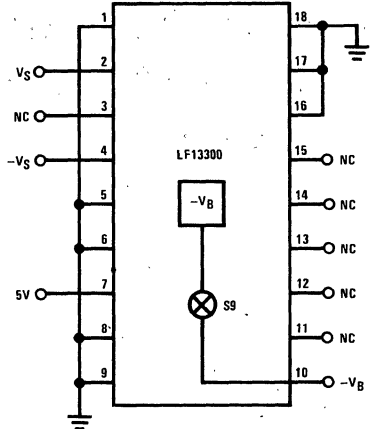
Test Circuit 2
Analog Input Characteristics Test with PD/RU+ High



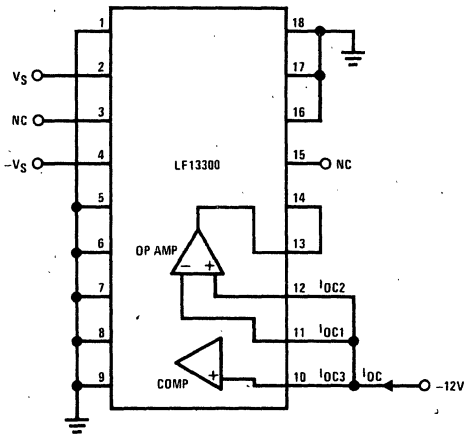
Test Circuit 3
Reference Input Characteristic Test with RR High



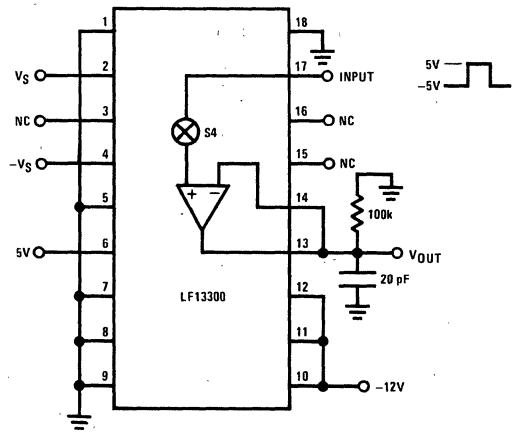
Test Circuit 4
-VB Voltage Measurement Test



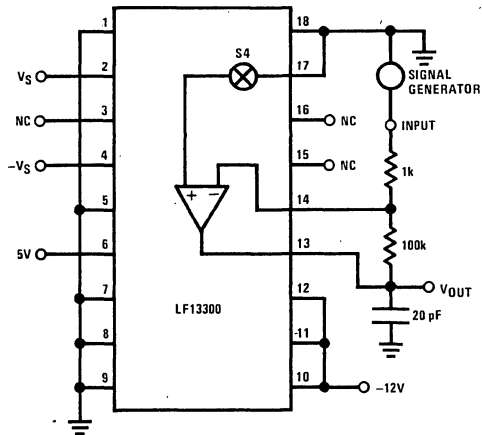
Test Circuit 5
Offset Correction Input Current, I_{OC} Test



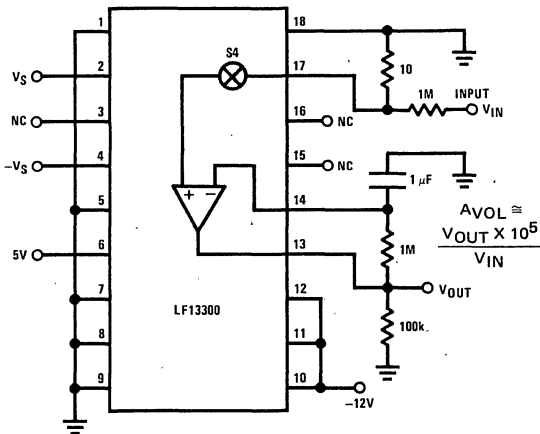
Test Circuit 6
Op Amp Slew Rate Test



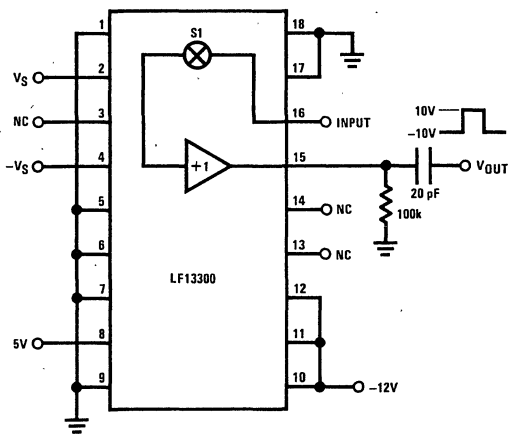
Test Circuit 7
Frequency Response Test



Test Circuit 8
Open Loop Gain Test

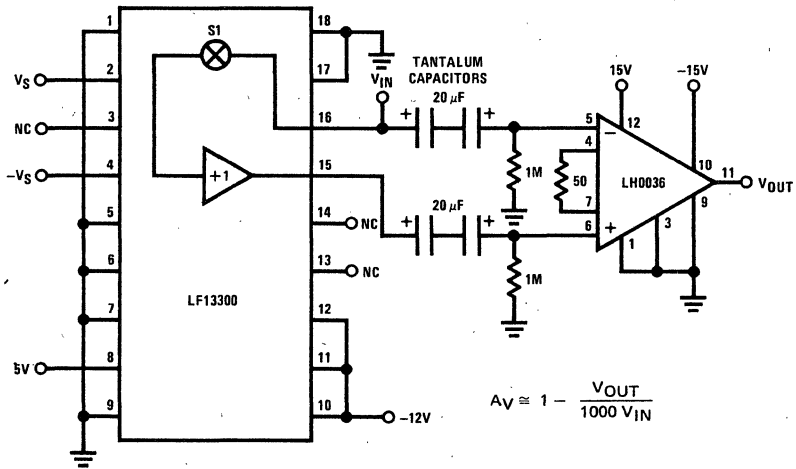


Test Circuit 9
Buffer Slow Rate Test

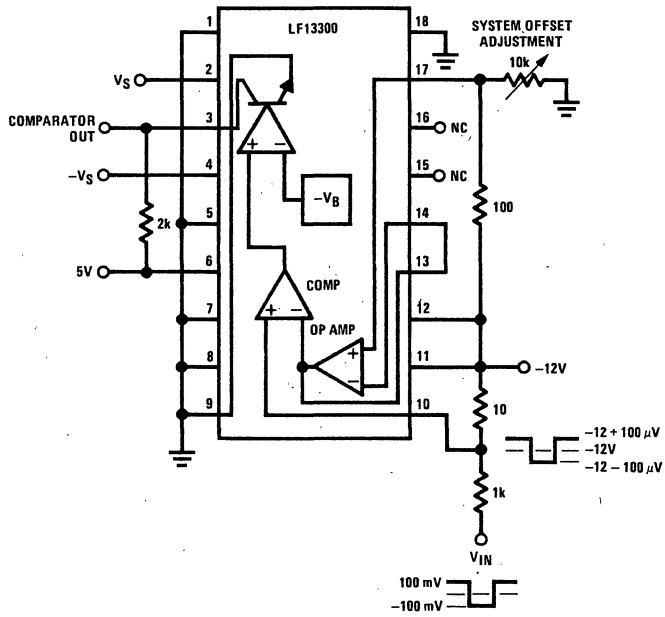


AC Test Circuits (Continued)

Test Circuit 10
Buffer Voltage Gain Test



Test Circuit 11
Comparator Response Time Test



Typical Applications (Continued)

LF11300

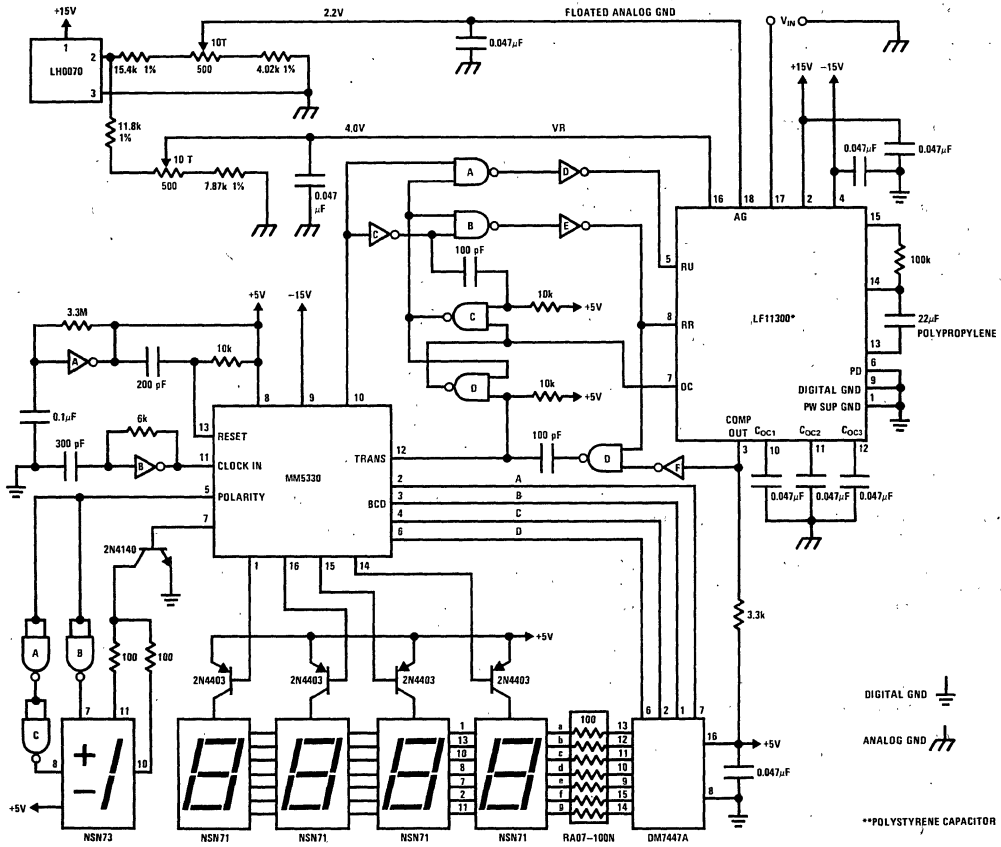


FIGURE 1. LF11300, MM5330 DPM Application

LM131A/LM131, LM231A/LM231, LM331A/LM331 Precision Voltage-to-Frequency Converters

General Description

The LM131/LM231/LM331 family of voltage-to-frequency converters are ideally suited for use in simple low-cost circuits for analog-to-digital conversion, precision frequency-to-voltage conversion, long-term integration, linear frequency modulation or demodulation, and many other functions. The output when used as a voltage-to-frequency converter is a pulse train at a frequency precisely proportional to the applied input voltage. Thus, it provides all the inherent advantages of the voltage-to-frequency conversion techniques, and is easy to apply in all standard voltage-to-frequency converter applications. Further, the LM131A/LM231A/LM331A attains a new high level of accuracy versus temperature which could only be attained with expensive voltage-to-frequency modules. Additionally the LM131 is ideally suited for use in digital systems at low power supply voltages and can provide low-cost analog-to-digital conversion in microprocessor-controlled systems. And, the frequency from a battery powered voltage-to-frequency converter can be easily channeled through a simple photoislator to provide isolation against high common mode levels.

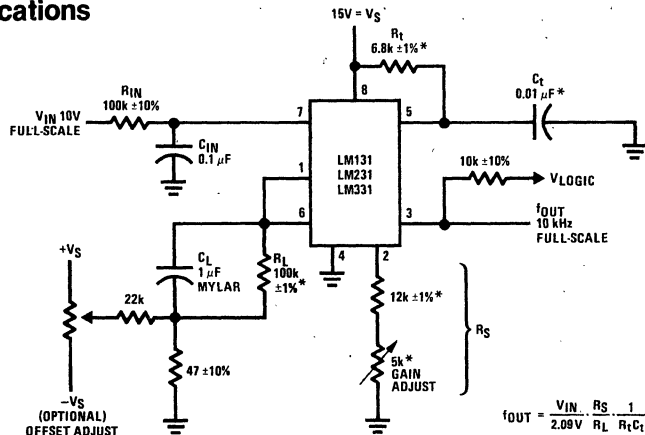
The LM131/LM231/LM331 utilizes a new temperature-compensated band-gap reference circuit, to provide excellent accuracy over the full operating temperature range, at power supplies as low as 4.0V. The precision timer circuit has low bias currents without degrading

the quick response necessary for 100 kHz voltage-to-frequency conversion. And the output is capable of driving 3 TTL loads, or a high voltage output up to 40V, yet is short-circuit-proof against V_{CC} .

Features

- Guaranteed linearity 0.01% max
- Improved performance in existing voltage-to-frequency conversion applications
- Split or single supply operation
- Operates on single 5V supply
- Pulse output compatible with all logic forms
- Excellent temperature stability, ± 50 ppm/ $^{\circ}$ C max
- Low power dissipation, 15 mW typical at 5V
- Wide dynamic range, 100 dB min at 10 kHz full scale frequency
- Wide range of full scale frequency, 1 Hz to 100 kHz
- Low cost

Typical Applications



*Use stable components with low temperature coefficients. See Typical Applications section.

FIGURE 1. Simple Stand-Alone Voltage-to-Frequency Converter with $\pm 0.03\%$ Typical Linearity ($f = 10$ Hz to 11 kHz)

Absolute Maximum Ratings

| | LM131A/LM131 | LM231A/LM231 | LM331A/LM331 |
|---|-----------------------------------|-----------------------------------|-----------------------------------|
| Supply Voltage | 40V | 40V | 40V |
| Output Short Circuit to Ground | Continuous | Continuous | Continuous |
| Output Short Circuit to V _{CC} | Continuous | Continuous | Continuous |
| Input Voltage | -0.2V to +V _S | -0.2V to +V _S | -0.2V to +V _S |
| | T _{MIN} T _{MAX} | T _{MIN} T _{MAX} | T _{MIN} T _{MAX} |
| Operating Ambient Temperature Range | -55°C to +125°C | -25°C to +85°C | 0°C to +70°C |
| Power Dissipation (P _D at 25°C) and Thermal Resistance (θ _{jA}) | | | |
| (H Package) P _D | 670 mW | 570 mW | 570 mW |
| θ _{jA} | 150°C/W | 150°C/W | 150°C/W |
| (N Package) P _D | | 500 mW | 500 mW |
| θ _{jA} | | 155°C/W | 155°C/W |

Electrical Characteristics T_A = 25°C unless otherwise specified. (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|------|--------|----------------------|------------------|
| VFC Non-Linearity (Note 2) | 4.5V ≤ V _S ≤ 20V | | ±0.003 | ±0.01 | % Full-Scale |
| | T _{MIN} ≤ T _A ≤ T _{MAX} | | ±0.006 | ±0.02 | % Full-Scale |
| In Circuit of Figure 1 | V _S = 15V, f = 10 Hz to 11 kHz | | ±0.024 | ±0.14 | % Full-Scale |
| Conversion Accuracy Scale Factor (Gain) | V _{IN} = -10V, R _S = 14 kΩ | | | | |
| LM131, LM131A, LM231, LM231A | | 0.95 | 1.00 | 1.05 | kHz/V |
| LM331, LM331A | | 0.90 | 1.00 | 1.10 | kHz/V |
| Temperature Stability of Gain | T _{MIN} ≤ T _A ≤ T _{MAX} , 4.5V ≤ V _S ≤ 20V | | | | |
| LM131/LM231/LM331 | | | ±30 | ±150 | ppm/°C |
| LM131A/LM231A/LM331A | | | ±20 | ±50 | ppm/°C |
| Change of Gain with V _S | 4.5V ≤ V _S ≤ 10V | | 0.01 | 0.1 | %/V |
| | 10V ≤ V _S ≤ 40V | | 0.006 | 0.06 | %/V |
| Rated Full-Scale Frequency | V _{IN} = -10V | 10.0 | | | kHz |
| Overrange (Beyond Full-Scale) Frequency | V _{IN} = -11V | 10 | | | % |
| INPUT COMPARATOR | | | | | |
| Offset Voltage | | | ±3 | ±10 | mV |
| LM131/LM231/LM331 | T _{MIN} ≤ T _A ≤ T _{MAX} | | ±4 | ±14 | mV |
| LM131A/LM231A/LM331A | T _{MIN} ≤ T _A ≤ T _{MAX} | | ±3 | ±10 | mV |
| Bias Current | | | -80 | -300 | nA |
| Offset Current | | | ±8 | ±100 | nA |
| Common-Mode Range | T _{MIN} ≤ T _A ≤ T _{MAX} | -0.2 | | V _{CC} -2.0 | V |
| TIMER | | | | | |
| Timer Threshold Voltage, Pin 5 | | 0.63 | 0.667 | 0.70 | x V _S |
| Input Bias Current, Pin 5 | V _S = 15V | | | | |
| All Devices | 0V ≤ V _{PIN 5} ≤ 9.9V | | ±10 | ±100 | nA |
| LM131/LM231/LM331 | V _{PIN 5} = 10V | | 200 | 1000 | nA |
| LM131A/LM231A/LM331A | V _{PIN 5} = 10V | | 200 | 500 | nA |
| V _{SAT} PIN 5 (Reset) | I = 5 mA | | 0.22 | 0.5 | V |

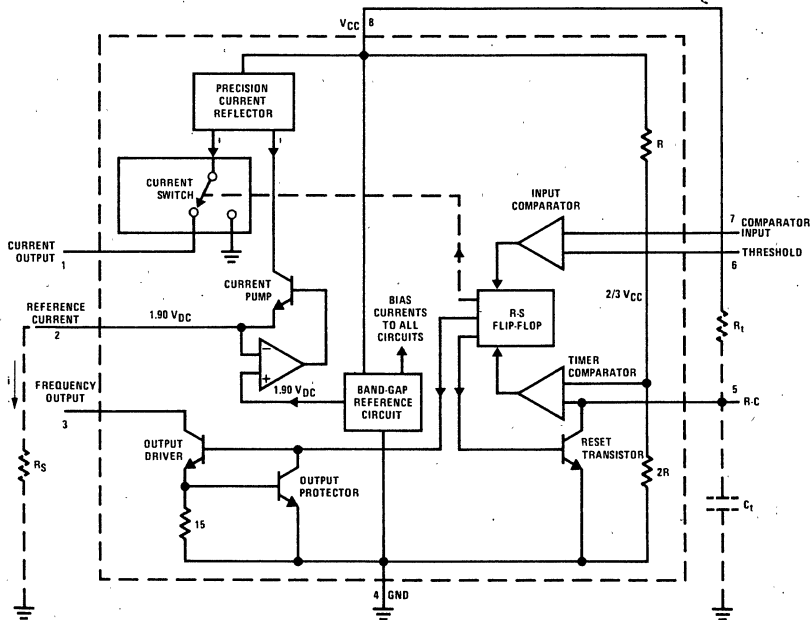
Electrical Characteristics (Continued) $T_A = 25^\circ\text{C}$ unless otherwise specified (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|--------------------------|--------------------------|--------------------------|-----------------------|
| CURRENT SOURCE (Pin 1) | | | | | |
| Output Current LM131, LM131A, LM231, LM231A LM331, LM331A | $R_S = 14\text{ k}\Omega$, $V_{PIN\ 1} = 0$ | 126 116 | 135 136 | 144 156 | μA |
| Change with Voltage | $0\text{V} \leq V_{PIN\ 1} \leq 10\text{V}$ | | 0.2 | 1.0 | μA |
| Current Source OFF Leakage LM131, LM131A LM231, LM231A, LM331, LM331A All Devices | $T_A = T_{MAX}$ | | 0.01 0.02 2.0 | 1.0 10.0 50.0 | nA |
| Operating Range of Current (Typical) | | | (10 to 500) | | μA |
| REFERENCE VOLTAGE (Pin 2) | | | | | |
| LM131, LM131A, LM231, LM231A LM331, LM331A | | 1.76 1.70 | 1.89 1.89 | 2.02 2.08 | V _{DC} |
| Stability vs Temperature | | | ± 60 | | ppm/ $^\circ\text{C}$ |
| Stability vs Time, 1000 Hours | | | ± 0.1 | | % |
| LOGIC OUTPUT (Pin 3) | | | | | |
| V _{SAT} | $I = 5\text{ mA}$ $I = 3.2\text{ mA}$ (2 TTL Loads), $T_{MIN} \leq T_A \leq T_{MAX}$ | | 0.15 0.10 | 0.50 0.40 | V |
| OFF Leakage | | | ± 0.05 | 1.0 | μA |
| SUPPLY CURRENT | | | | | |
| LM131, LM131A, LM231, LM231A LM331, LM331A | $V_S = 5\text{V}$ $V_S = 40\text{V}$ $V_S = 5\text{V}$ $V_S = 40\text{V}$ | 2.0 2.5 1.5 2.0 | 3.0 4.0 3.0 4.0 | 4.0 6.0 6.0 8.0 | mA |

Note 1: All specifications apply in the circuit of Figure 3, with $4.0\text{V} \leq V_S \leq 40\text{V}$, unless otherwise noted.

Note 2: Nonlinearity is defined as the deviation of f_{OUT} from $V_{IN} \times (10\text{ kHz}/10\text{ V}_{DC})$ when the circuit has been trimmed for zero error at 10 Hz and at 10 kHz, over the frequency range 1 Hz to 11 kHz. For the timing capacitor, C_T , use NPO ceramic, Teflon*, or polystyrene.

Functional Block Diagrams



*Registered trademark of DuPont

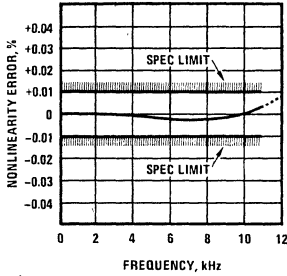
FIGURE 1a

Typical Performance Characteristics

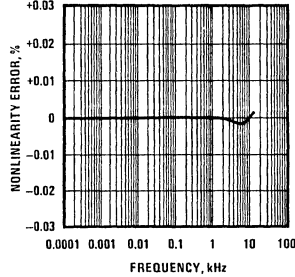
(All electrical characteristics apply for the circuit of *Figure 3*, unless otherwise noted.)

LM131A/LM131, LM231A/LM231, LM331A/LM331

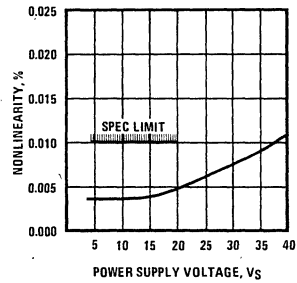
Nonlinearity Error, LM131 Family, as Precision V-to-F Converter (*Figure 3*)



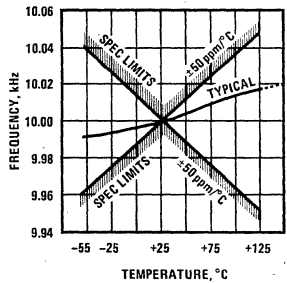
Nonlinearity Error, LM131 Family



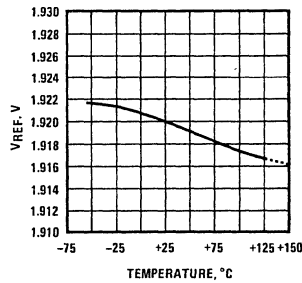
Nonlinearity vs Power Supply Voltage



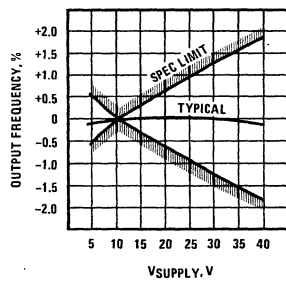
Frequency vs Temperature, LM131A



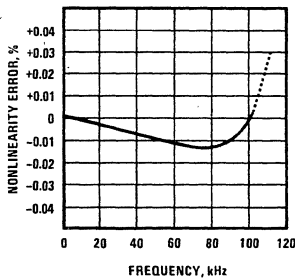
VREF vs Temperature, LM131A



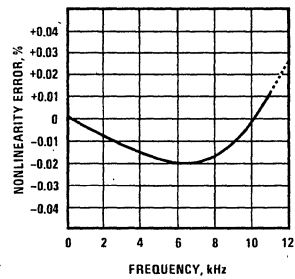
Output Frequency vs VSUPPLY



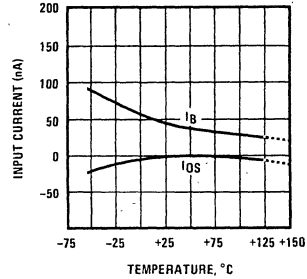
100kHz Nonlinearity Error, LM131 Family (*Figure 4*)



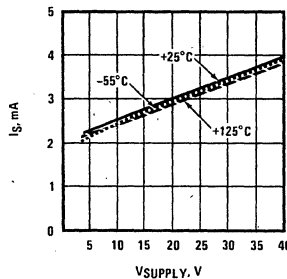
Nonlinearity Error, LM131 (*Figure 1*)



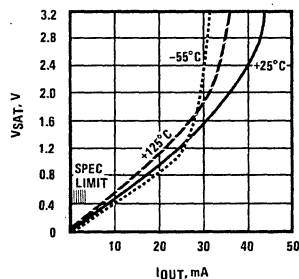
Input Current (Pins 6, 7) vs Temperature



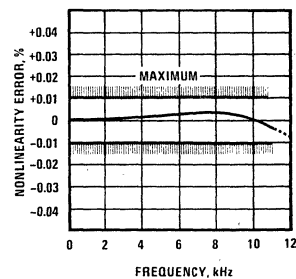
Power Drain vs VSUPPLY



Output Saturation Voltage vs IOU (Pin 3)



Nonlinearity Error, Precision F-to-V Converter (*Figure 6*)



Typical Applications (Continued)

PRINCIPLES OF OPERATION OF A SIMPLIFIED VOLTAGE-TO-FREQUENCY CONVERTER

The LM131 is a monolithic circuit designed for accuracy and versatile operation when applied as a voltage-to-frequency (V-to-F) converter or as a frequency-to-voltage (F-to-V) converter. A simplified block diagram of the LM131 is shown in *Figure 2* and consists of a switched current source, input comparator, and 1-shot timer.

The operation of these blocks is best understood by going through the operating cycle of the basic V-to-F converter, *Figure 2*, which consists of the simplified block diagram of the LM131 and the various resistors and capacitors connected to it.

The voltage comparator compares a positive input voltage, V_1 , at pin 7 to the voltage, V_X , at pin 6. If V_1 is greater, the comparator will trigger the 1-shot timer. The output of the timer will turn ON both the frequency output transistor and the switched current source for a period $t = 1.1 R_T C_T$. During this period, the current i will flow out of the switched current source and provide a fixed amount of charge, $Q = i \times t$, into the capacitor, C_L . This will normally charge V_X up to a higher level than V_1 . At the end of the timing period, the current i will turn OFF, and the timer will reset itself.

Now there is no current flowing from pin 1, and the capacitor C_L will be gradually discharged by R_L until V_X falls to the level of V_1 . Then the comparator will trigger the timer and start another cycle.

The current flowing into C_L is exactly $I_{AVE} = i \times (1.1 \times R_T C_T) \times f$, and the current flowing out of C_L is exactly $V_X/R_L \cong V_{IN}/R_L$. If V_{IN} is doubled, the frequency will double to maintain this balance. Even a simple V-to-F converter can provide a frequency precisely proportional to its input voltage over a wide range of frequencies.

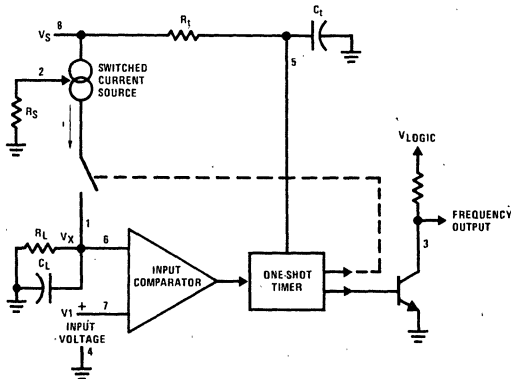


FIGURE 2. Simplified Block Diagram of Stand-Alone Voltage-to-Frequency Converter Showing LM131 and External Components

DETAIL OF OPERATION, FUNCTIONAL BLOCK DIAGRAM (FIGURE 1a)

The block diagram shows a band gap reference which provides a stable 1.9 V_{DC} output. This 1.9 V_{DC} is well regulated over a V_S range of 3.9V to 40V. It also has a flat, low temperature coefficient, and typically changes less than 1/2% over a 100°C temperature change.

The current pump circuit forces the voltage at pin 2 to be at .1.9V, and causes a current $i = 1.90V/R_S$ to flow. For $R_S = 14k$, $i = 135 \mu A$. The precision current reflector provides a current equal to i to the current switch. The current switch switches the current to pin 1 or to ground depending on the state of the R_S flip-flop.

The timing function consists of an R_S flip-flop, and a timer comparator connected to the external $R_T C_T$ network. When the input comparator detects a voltage at pin 7 higher than pin 6, it sets the R_S flip-flop which turns ON the current switch and the output driver transistor. When the voltage at pin 5 rises to 2/3 V_{CC} , the timer comparator causes the R_S flip-flop to reset. The reset transistor is then turned ON and the current switch is turned OFF.

However, if the input comparator still detects pin 7 higher than pin 6 when pin 5 crosses 2/3 V_{CC} , the flip-flop will not be reset, and the current at pin 1 will continue to flow, in its attempt to make the voltage at pin 6 higher than pin 7. This condition will usually apply under start-up conditions or in the case of an overload voltage at signal input. It should be noted that during this sort of overload, the output frequency will be 0; as soon as the signal is restored to the working range, the output frequency will be resumed.

The output driver transistor acts to saturate pin 3 with an ON resistance of about 50Ω. In case of overvoltage, the output current is actively limited to less than 50 mA.

The voltage at pin 2 is regulated at 1.90 V_{DC} for all values of i between 10 μA to 500 μA. It can be used as a voltage reference for other components, but care must be taken to ensure that current is not taken from it which could reduce the accuracy of the converter.

PRINCIPLES OF OPERATION OF BASIC VOLTAGE-TO-FREQUENCY CONVERTER (FIGURE 1)

The simple stand-alone V-to-F converter shown in *Figure 1* includes all the basic circuitry of *Figure 2* plus a few components for improved performance.

A resistor, $R_{1N} = 100 k\Omega \pm 10\%$, has been added in the path to pin 7, so that the bias current at pin 7 (−80 nA typical) will cancel the effect of the bias current at pin 6 and help provide minimum frequency offset.

The resistance R_S at pin 2 is made up of a 12 kΩ fixed resistor plus a 5 kΩ (cermet, preferably) gain adjust rheostat. The function of this adjustment is to trim out the gain tolerance of the LM131, and the tolerance of R_T , R_L and C_T . For best results, all the components

Typical Applications (Continued)

should be stable low-temperature-coefficient components, such as metal-film resistors. The capacitor should have low dielectric absorption; depending on the temperature characteristics desired, NPO ceramic, polystyrene, Teflon* or polypropylene are best suited.

A capacitor is added from pin 7 to ground to act as a filter for V_{IN} . A value of $0.01 \mu\text{F}$ to $0.1 \mu\text{F}$ will be adequate in most cases; however, in cases where better filtering is required, a $1 \mu\text{F}$ capacitor can be used. When the RC time constants are matched at pin 6 and pin 7, a voltage step at V_{IN} will cause a step change in f_{OUT} . If C_{IN} is much less than C_L , a step at V_{IN} may cause f_{OUT} to stop momentarily.

A 47Ω resistor, in series with the $1 \mu\text{F}$ C_L , is added to give hysteresis effect which helps the input comparator provide the excellent linearity (0.03% typical).

DETAIL OF OPERATION OF PRECISION V-TO-F CONVERTER (FIGURE 3)

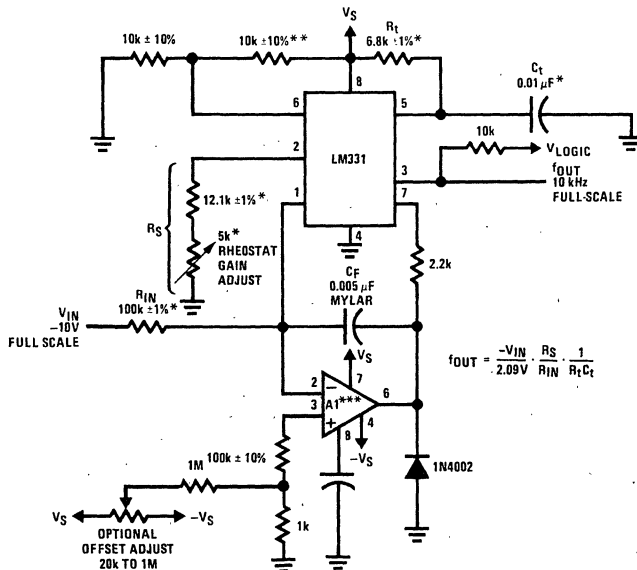
In this circuit, integration is performed by using a conventional operational amplifier and feedback capacitor, C_F . When the integrator's output crosses the nominal threshold level at pin 6 of the LM131, the timing cycle is

initiated. The average current fed into the op amp's summing point (pin 2) is $i \times (1.1 R_T C_T) \times f$ which is perfectly balanced with $-V_{IN}/R_{IN}$. In this circuit, the voltage offset of the LM131 input comparator does not affect the offset or accuracy of the V-to-F converter as it does in the stand-alone V-to-F converter; nor does the LM131 bias current or offset current. Instead, the offset voltage and offset current of the operational amplifier are the only limits on how small the signal can be accurately converted. Since op amps with voltage offset well below 1 mV and offset currents well below 2 nA are available at low cost, this circuit is recommended for best accuracy for small signals. This circuit also responds immediately to any change of input signal (which a stand-alone circuit does not) so that the output frequency will be an accurate representation of V_{IN} , as quickly as 2 output pulses' spacing can be measured.

In the precision mode, excellent linearity is obtained because the current source (pin 1) is always at ground potential and that voltage does not vary with V_{IN} or f_{OUT} . (In the stand-alone V-to-F converter, a major cause of non-linearity is the output impedance at pin 1 which causes i to change as a function of V_{IN}).

The circuit of Figure 4 operates in the same way as Figure 3, but with the necessary changes for high speed operation.

*Registered trademark of DuPont



*Use stable components with low temperature coefficients. See Typical Applications section.

**This resistor can be $5 \text{ k}\Omega$ or $10 \text{ k}\Omega$ for $V_S = 8 \text{ V}$ to 22 V , but must be $10 \text{ k}\Omega$ for $V_S = 4.5 \text{ V}$ to 8 V .

***Use low offset voltage and low offset current op amps for A1: recommended types LM108, LM308A, LF351B

FIGURE 3. Standard Test Circuit and Applications Circuit, Precision Voltage-to-Frequency Converter

Typical Applications (Continued)

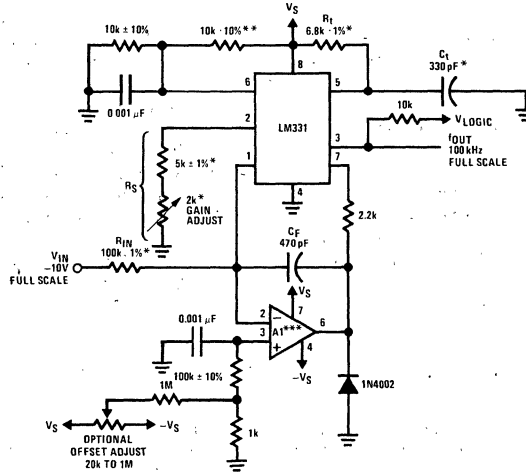
DETAILS OF OPERATION, FREQUENCY-TO-VOLTAGE CONVERTERS (FIGURES 5 AND 6)

In these applications, a pulse input at f_{IN} is differentiated by a C-R network and the negative-going edge at pin 6 causes the input comparator to trigger the timer circuit. Just as with a V-to-F converter, the average current flowing out of pin 1 is $I_{AVERAGE} = i \times (1.1 R_T C_T) \times f$.

In the simple circuit of Figure 5, this current is filtered in the network $R_L = 100 \text{ k}\Omega$ and $1 \mu\text{F}$. The ripple will be less than 10 mV peak, but the response will be slow,

with a 0.1 second time constant, and settling of 0.7 second to 0.1% accuracy.

In the precision circuit, an operational amplifier provides a buffered output and also acts as a 2-pole filter. The ripple will be less than 5 mV peak for all frequencies above 1 kHz, and the response time will be much quicker than in Figure 5. However, for input frequencies below 200 Hz, this circuit will have worse ripple than Figure 5. The engineering of the filter time-constants to get adequate response and small enough ripple simply requires a study of the compromises to be made. Inherently, V-to-F converter response can be fast, but F-to-V response can not.

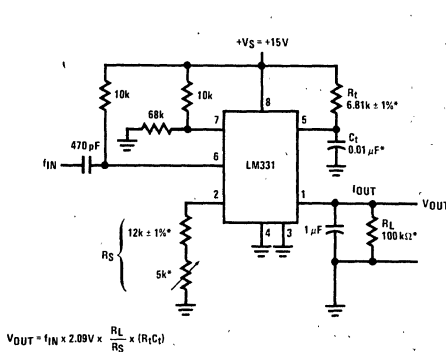


* Use stable components with low temperature coefficients. See Typical Applications section.

** This resistor can be 5 k Ω or 10 k Ω for $V_S = 8\text{V}$ to 22V, but must be 10 k Ω for $V_S = 4.5\text{V}$ to 8V.

*** Use low offset voltage and low offset current op amps for A1: recommended types LF351B or LF356.

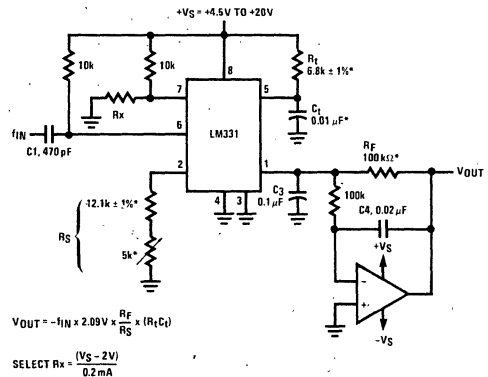
FIGURE 4. Precision Voltage-to-Frequency Converter, 100 kHz Full-Scale, $\pm 0.03\%$ Non-Linearity



$$V_{OUT} = f_{IN} \times 2.09V \times \frac{R_L}{R_S} \times (R_T C_T)$$

* Use stable components with low temperature coefficients.

FIGURE 5. Simple Frequency-to-Voltage Converter, 10 kHz Full-Scale, $\pm 0.06\%$ Non-Linearity



$$V_{OUT} = -f_{IN} \times 2.09V \times \frac{R_F}{R_S} \times (R_T C_T)$$

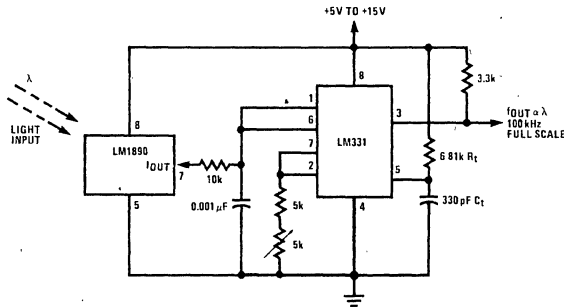
$$\text{SELECT } R_x = \frac{(V_S - 2V)}{0.2 \text{ mA}}$$

* Use stable components with low temperature coefficients.

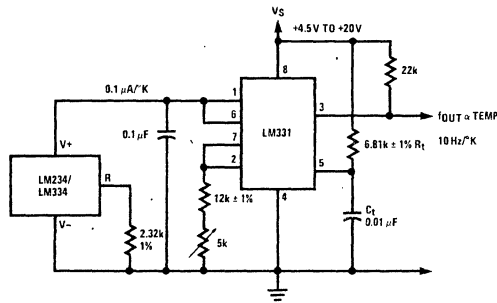
FIGURE 6. Precision Frequency-to-Voltage Converter, 10 kHz Full-Scale with 2-Pole Filter, $\pm 0.01\%$ Non-Linearity Maximum

Typical Applications (Continued)

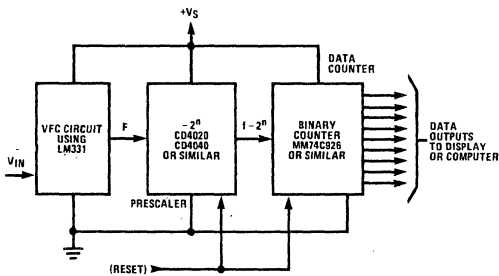
Light Intensity to Frequency Converter



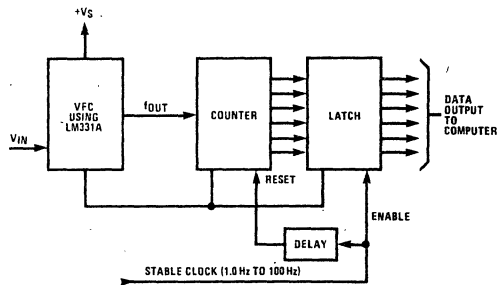
Temperature to Frequency Converter



Long-Term Digital Integrator Using VFC



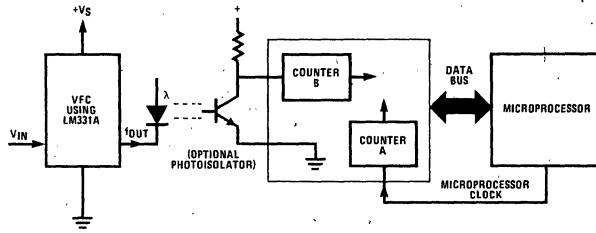
Basic Analog-to-Digital Converter Using Voltage-to-Frequency Converter



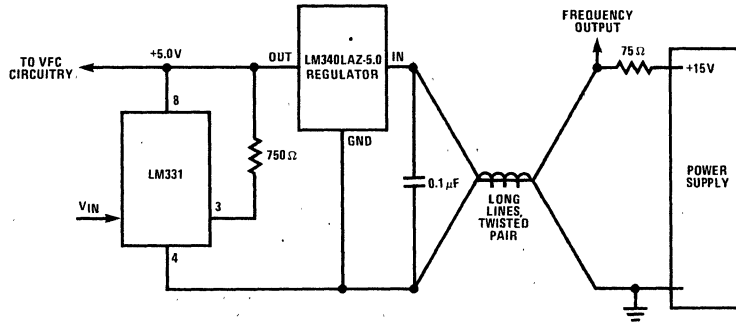
LM131A/LM131, LM231A/LM231, LM331A/LM331

Typical Applications (Continued)

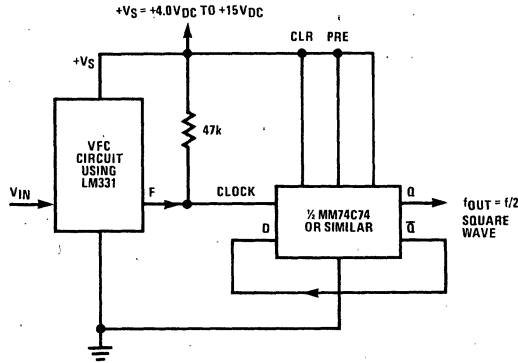
Analog-to-Digital Converter with Microprocessor



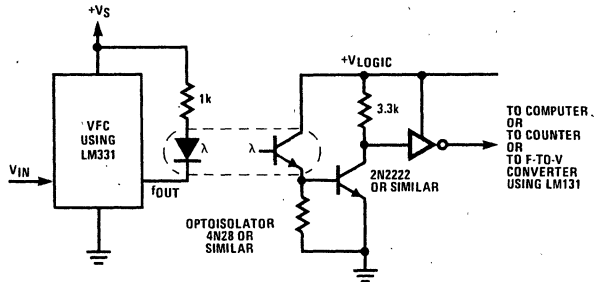
Remote Voltage-to-Frequency Converter with 2-Wire Transmitter and Receiver



Voltage-to-Frequency Converter with Square-Wave Output Using ÷2 Flip-Flop

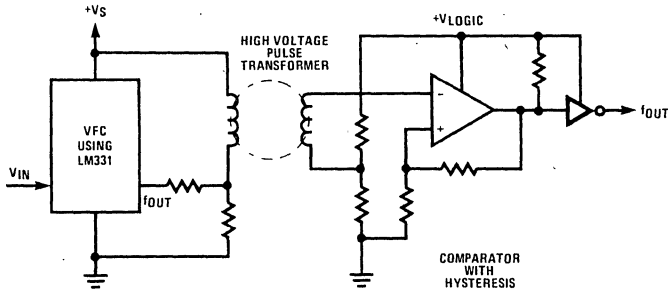


Voltage-to-Frequency Converter with Isolators

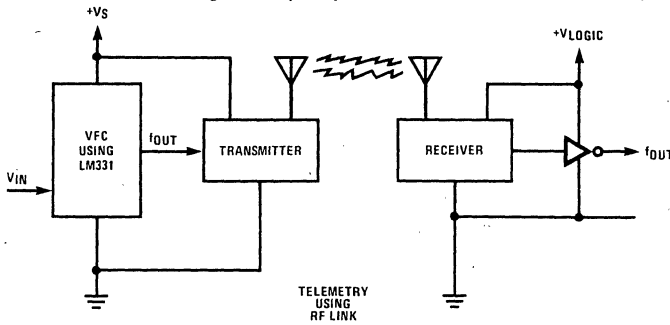


Typical Applications (Continued)

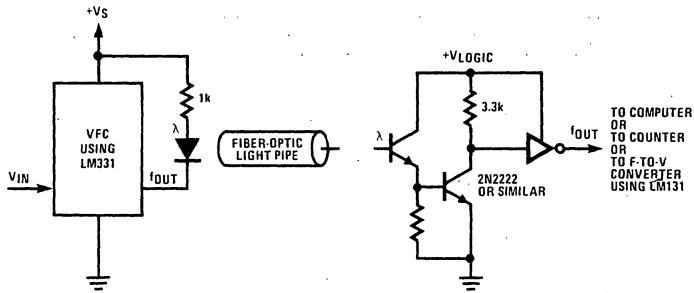
Voltage-to-Frequency Converter with Isolators



Voltage-to-Frequency Converter with Isolators

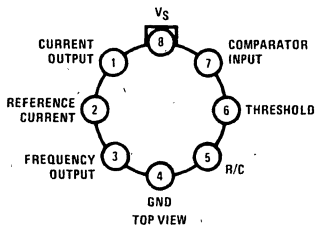


Voltage-to-Frequency Converter with Isolators



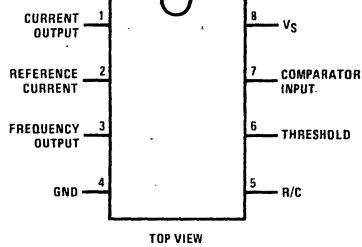
Connection Diagrams

Metal Can Package



Order Number LM131AH, LM131H, LM231AH,
LM231H, LM331AH or LM331H
See NS Package H08C

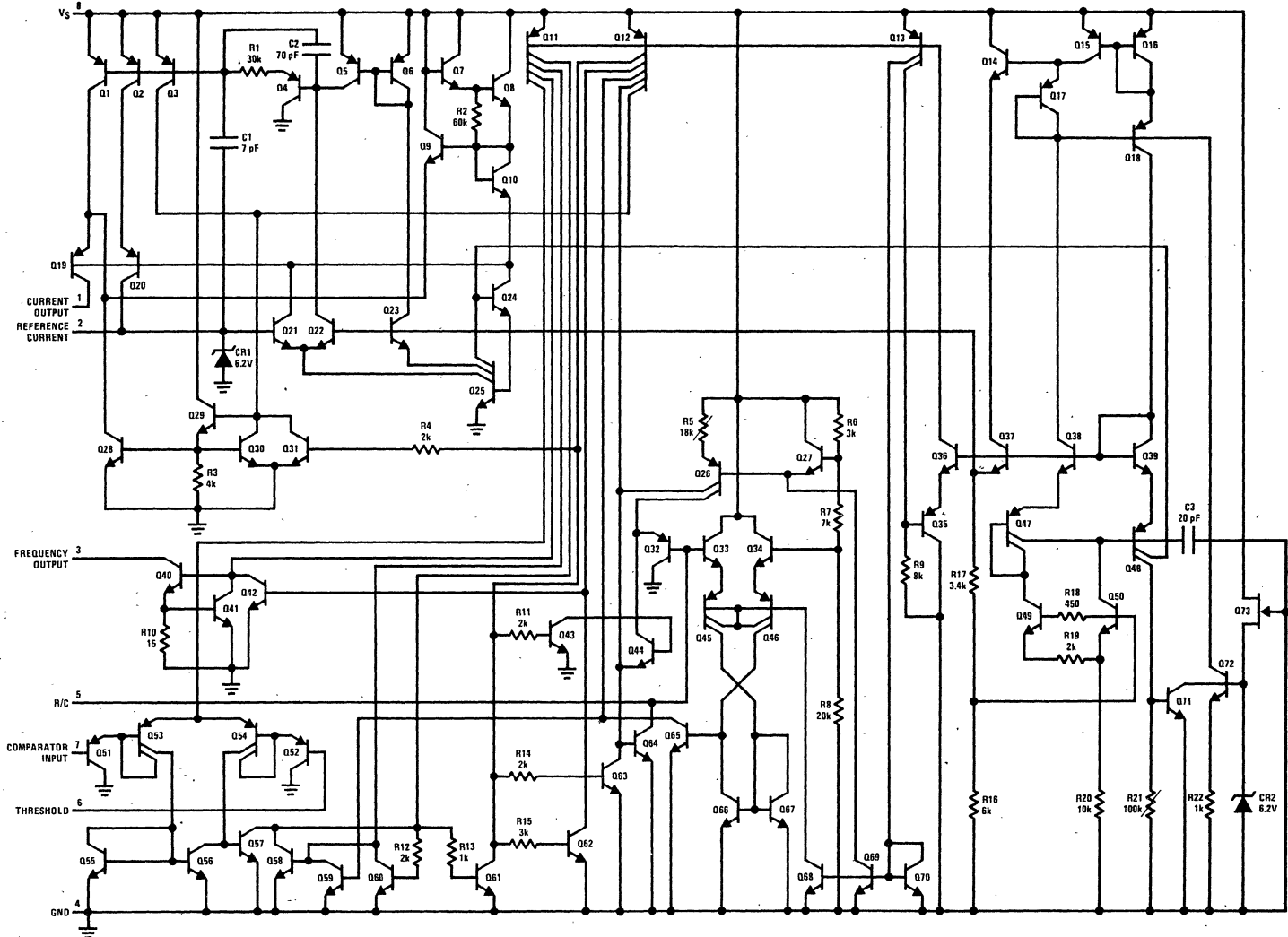
Dual-In-Line Package



Order Number LM231AN, LM231N, LM331AN,
or LM331N
See NS Package N08B

LM131A/LM131, LM231A/LM231, LM331A/LM331

Schematic Diagram



LM1508/LM1408 8-Bit D/A Converter

General Description

The LM1508/LM1408 is an 8-bit monolithic digital-to-analog converter (DAC) featuring a full scale output current settling time of 150 ns while dissipating only 33 mW with $\pm 5V$ supplies. No reference current (I_{REF}) trimming is required for most applications since the full scale output current is typically ± 1 LSB of 255 $I_{REF}/256$. Relative accuracies of better than $\pm 0.19\%$ assure 8-bit monotonicity and linearity while zero level output current of less than $4 \mu A$ provides 8-bit zero accuracy for $I_{REF} \geq 2$ mA. The power supply currents of the LM1508/LM1408 are independent of bit codes, and exhibits essentially constant device characteristics over the entire supply voltage range.

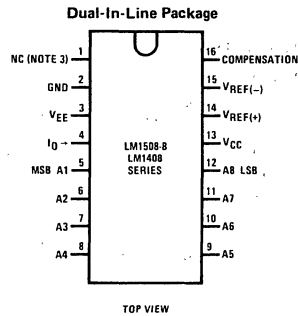
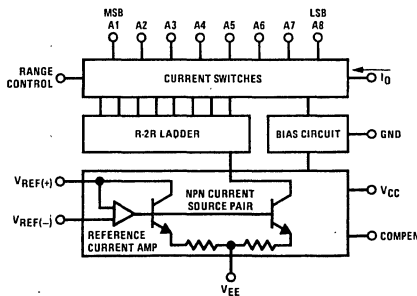
The LM1508/LM1408 will interface directly with popular TTL, DTL or CMOS logic levels, and is a direct replacement for the MC1508/MC1408. For higher speed

applications, see DAC0800 data sheet. For more information, see DAC0808 data sheet.

Features

- Relative accuracy: $\pm 0.19\%$ error maximum LM1508-8 and LM1408-8
- Full scale current match: ± 1 LSB typ
- 7 and 6-bit accuracy available
- Fast settling time: 150 ns typ
- Noninverting digital inputs are TTL and CMOS compatible
- High speed multiplying input slew rate: 8 mA/ μs
- Power supply voltage range: $\pm 4.5V$ to $\pm 18V$
- Low power consumption: 33 mW @ $\pm 5V$

Block and Connection Diagrams



Typical Application

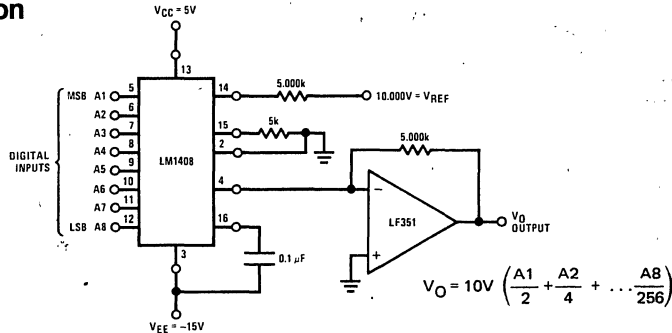


FIGURE 1. $\pm 10V$ Output Digital to Analog Converter

Ordering Information

| ACCURACY | OPERATING TEMPERATURE RANGE | ORDER NUMBERS* | | |
|----------|--|-------------------------|-------------------------|------------------------|
| | | HERMETIC PACKAGE (D16C) | HERMETIC PACKAGE (J16A) | PLASTIC PACKAGE (N16A) |
| 8-Bit | $-55^{\circ}C \leq T_A \leq +125^{\circ}C$ | LM1508D-8 | LM1508J-8 | |
| 8-Bit | $0^{\circ}C \leq T_A \leq +75^{\circ}C$ | | LM1408J-8 | LM1408N-8 |
| 7-Bit | $0^{\circ}C \leq T_A \leq +75^{\circ}C$ | | LM1408J-7 | LM1408N-7 |
| 6-Bit | $0^{\circ}C \leq T_A \leq +75^{\circ}C$ | | LM1408J-6 | LM1408N-6 |

*Note. Devices may be ordered by using either order number.

Absolute Maximum Ratings

| | | | |
|--|--------------------|--|--|
| Power Supply Voltage | | Power Dissipation (Package Limitation) | |
| V_{CC} | 5.5 VDC | Cavity Package | 1000 mW |
| V_{EE} | -16.5 VDC | Derate above $T_A = 25^\circ\text{C}$ | 6.7 mW/ $^\circ\text{C}$ |
| Digital Input Voltage, V_5-V_{12} | -10 VDC to +18 VDC | Operating Temperature Range | |
| Applied Output Voltage, V_O | -11 VDC to +18 VDC | LM1508-8 | $-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ |
| Reference Current, I_{14} | 5 mA | LM1408-8 Series | $0 \leq T_A \leq +75^\circ\text{C}$ |
| Reference Amplifier Inputs, V_{14}, V_{15} | V_{CC}, V_{EE} | Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |

Electrical Characteristics

($V_{CC} = 5\text{V}$, $V_{EE} = -15\text{VDC}$, $V_{REF}/R_{14} = 2\text{mA}$, LM1508-8: $T_A = -55^\circ\text{C}$ to $+125^\circ\text{C}$; LM1408-8, LM1408-7, LM1408-6, $T_A = 0^\circ\text{C}$ to $+75^\circ\text{C}$, and all digital inputs at high logic level unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------|---|--|----------|---------------------------|------------------------|
| E_r | Relative Accuracy (Error Relative to Full Scale I_O) | | | | % |
| | LM1508-8 | | | ± 0.19 | % |
| | LM1408-8 | | | ± 0.39 | % |
| | LM1408-7, (Note 1) | | | ± 0.78 | % |
| | LM1408-6, (Note 1) | | | | % |
| | Settling Time to Within 1/2 LSB (Includes t_{PLH}) | $T_A = 25^\circ\text{C}$ (Note 2) | 150 | | ns |
| t_{PLH} | Propagation Delay Time | $T_A = 25^\circ\text{C}$ | 30 | 100 | ns |
| t_{PHL} | | | | | |
| TC_{IO} | Output Full Scale Current Drift | | ± 20 | | ppm/ $^\circ\text{C}$ |
| MSB | Digital Input Logic Levels | | | | |
| V_{IH} | High Level, Logic "1" | 2 | | | VDC |
| V_{IL} | Low Level, Logic "0" | | | 0.8 | VDC |
| MSB | Digital Input Current | | | | |
| | High Level | $V_{IH} = 5\text{V}$ | 0 | 0.040 | mA |
| | Low Level | $V_{IL} = 0.8\text{V}$ | -0.003 | -0.8 | mA |
| I_{15} | Reference Input Bias Current | | -1 | -5 | μA |
| | Output Current Range | | | | |
| | | $V_{EE} = -5\text{V}$ | 0 | 2.0 | mA |
| | | $V_{EE} = -15\text{V}, T_A = 25^\circ\text{C}$ | 0 | 2.0 | mA |
| I_O | Output Current | $V_{REF} = 2.000\text{V}$, $R_{14} = 1000\Omega$ | 1.9 | 1.99 | mA |
| | Output Current, All Bits Low | | 0 | 4 | μA |
| | Output Voltage Compliance | $E_r \leq 0.19\%$, $T_A = 25^\circ\text{C}$ | | | |
| | Pin 1 Grounded, V_{EE} Below -10V | | | -0.55, +0.4 -5.0, +0.4 | VDC VDC |
| SRI_{REF} | Reference Current Slew Rate | | 8 | | mA/ μs |
| | Output Current Power Supply Sensitivity | $-5\text{V} \leq V_{EE} \leq -16.5\text{V}$ | 0.05 | 2.7 | $\mu\text{A}/\text{V}$ |
| | Power Supply Current (All Bits Low) | | | | |
| I_{CC} | | | 2.3 | 22 | mA |
| I_{EE} | | | -4.3 | -13 | mA |
| | Power Supply Voltage Range | $T_A = 25^\circ\text{C}$ | | | |
| V_{CC} | | 4.5 | 5.0 | 5.5 | VDC |
| V_{EE} | | -4.5 | -15 | -16.5 | VDC |
| | Power Dissipation | | | | |
| | All Bits Low | $V_{CC} = 5\text{V}, V_{EE} = -5\text{V}$ | 33 | 170 | mW |
| | | $V_{CC} = 5\text{V}, V_{EE} = -15\text{V}$ | 106 | 305 | mW |
| | All Bits High | $V_{CC} = 15\text{V}, V_{EE} = -5\text{V}$ | 90 | | mW |
| | | $V_{CC} = 15\text{V}, V_{EE} = -15\text{V}$ | 160 | | mW |

Note 1: All current switches are tested to guarantee at least 50% of rated current.

Note 2: All bits switched.

Note 3: Range control is not required.



**National
Semiconductor**

A to D, D to A

MM54C905/MM74C905 12-Bit Successive Approximation Register

General Description

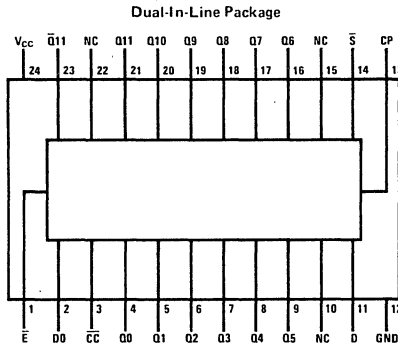
The MM54C905/MM74C905 CMOS 12-bit successive approximation register contains all the digit control and storage necessary for successive approximation analog-to-digital conversion. Because of the unique capability of CMOS to switch to each supply rail without any offset voltage, it can also be used in digital systems as the control and storage element in repetitive routines.

- Guaranteed noise margin 1.0V
- High noise immunity 0.45 V_{CC} typ
- Low power TTL compatibility fan out of 2 driving 74L
- Provision for register extension or truncation
- Operates in START/STOP or continuous conversion mode
- Drive ladder switches directly. For 10 bits or less with 50k/100k R/2R ladder network

Features

- Wide supply voltage range 3.0V to 15V

Connection Diagram



Order Number MM54C905D or MM74C905D
See NS Package D24A

Order Number MM74C905N
See NS Package N18A

Truth Table

| TIME | INPUTS | | | OUTPUTS | | | | | | | | | | | | | |
|------|--------|---|---|---------|-----|-----|----|----|----|----|----|----|----|----|----|----|----|
| | D | S | E | D0 | Q11 | Q10 | Q9 | Q8 | Q7 | Q6 | Q5 | Q4 | Q3 | Q2 | Q1 | Q0 | CC |
| 0 | X | L | L | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| 1 | D11 | H | L | X | L | H | H | H | H | H | H | H | H | H | H | H | H |
| 2 | D10 | H | L | D11 | D11 | L | H | H | H | H | H | H | H | H | H | H | H |
| 3 | D9 | H | L | D10 | D11 | D10 | L | H | H | H | H | H | H | H | H | H | H |
| 4 | D8 | H | L | D9 | D11 | D10 | D9 | L | H | H | H | H | H | H | H | H | H |
| 5 | D7 | H | L | D8 | D11 | D10 | D9 | D8 | L | H | H | H | H | H | H | H | H |
| 6 | D6 | H | L | D7 | D11 | D10 | D9 | D8 | D7 | L | H | H | H | H | H | H | H |
| 7 | D5 | H | L | D6 | D11 | D10 | D9 | D8 | D7 | D6 | L | H | H | H | H | H | H |
| 8 | D4 | H | L | D5 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | L | H | H | H | H | H |
| 9 | D3 | H | L | D4 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | L | H | H | H | H |
| 10 | D2 | H | L | D3 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | L | H | H | H |
| 11 | D1 | H | L | D2 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | L | H | H |
| 12 | D0 | H | L | D1 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | L | H |
| 13 | X | H | L | D0 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | L |
| 14 | X | X | L | X | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | L |
| | X | X | H | X | H | NC | NC | NC | NC | NC | NC | NC | NC | NC | NC | NC | NC |

H = High level
L = Low level
X = Don't care
NC = No change

MM54C905/MM74C905

8

Absolute Maximum Ratings (Note 1)

| | |
|--|--------------------------|
| Voltage at Any Pin | -0.3V to $V_{CC} + 0.3V$ |
| Operating Temperature Range | |
| MM54C905 | -55°C to +125°C |
| MM74C905 | -40°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Package Dissipation | 500 mW |
| Operating V_{CC} Range | 3.0V to 15V |
| Absolute Maximum V_{CC} | 16V |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics Min/max limits apply across temperature range, unless otherwise noted.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|------------------------------|--------|------------|----------|
| CMOS TO CMOS | | | | | |
| Logical "1" Input Voltage ($V_{IN(1)}$) | $V_{CC} = 5.0V$ $V_{CC} = 10V$ | 3.5 8.0 | | | V V |
| Logical "0" Input Voltage ($V_{IN(0)}$) | $V_{CC} = 5.0V$ $V_{CC} = 10V$ | | | 1.5 2.0 | V V |
| Logical "1" Output Voltage ($V_{OUT(1)}$) | $V_{CC} = 5.0V, I_O = -10\mu A$ $V_{CC} = 10V, I_O = -10\mu A$ | 4.5 9.0 | | | V V |
| Logical "0" Output Voltage ($V_{OUT(0)}$) | $V_{CC} = 5.0V, I_O = 10\mu A$ $V_{CC} = 10V, I_O = 10\mu A$ | | | 0.5 1.0 | V V |
| Logical "1" Input Current ($I_{IN(1)}$) | $V_{CC} = 15V, V_{IN} = 15V$ | | 0.005 | 1.0 | μA |
| Logical "0" Input Current ($I_{IN(0)}$) | $V_{CC} = 15V, V_{IN} = 0V$ | -1.0 | -0.005 | | μA |
| Supply Current (I_{CC}) | $V_{CC} = 15V$ | | 0.05 | 300 | μA |
| CMOS/LPTTL INTERFACE | | | | | |
| Logical "1" Input Voltage ($V_{IN(1)}$) MM54C905 MM74C905 | $V_{CC} = 4.5V$ $V_{CC} = 4.75V$ | $V_{CC}-1.5$ $V_{CC}-1.5$ | | | V V |
| Logical "0" Input Voltage ($V_{IN(0)}$) MM54C905 MM74C905 | $V_{CC} = 4.5V$ $V_{CC} = 4.75V$ | | | 0.8 0.8 | V V |
| Logical "1" Output Voltage ($V_{OUT(1)}$) MM54C905 MM74C905 | $V_{CC} = 4.5V, I_O = -360\mu A$ $V_{CC} = 4.75V, I_O = -360\mu A$ | 2.4 2.4 | | | V V |
| Logical "0" Output Voltage ($V_{OUT(0)}$) MM54C905 MM74C905 | $V_{CC} = 4.5V, I_O = 360\mu A$ $V_{CC} = 4.75V, I_O = 360\mu A$ | | | 0.4 0.4 | V V |
| OUTPUT DRIVE (See 54C/74C Family Characteristics Data Sheet) | | | | | |
| Output Source Current (I_{SOURCE}) (P-Channel) | $V_{CC} = 5.0V, V_{OUT} = 0V$ $T_A = 25^\circ C$ | -1.75 | -3.3 | | mA |
| Output Source Current (I_{SOURCE}) (P-Channel) | $V_{CC} = 10V, V_{OUT} = 0V$ $T_A = 25^\circ C$ | -8.0 | -15 | | mA |
| Output Sink Current (I_{SINK}) (N-Channel) | $V_{CC} = 5.0V, V_{OUT} = V_{CC}$ $T_A = 25^\circ C$ | 1.75 | 3.6 | | mA |
| Output Sink Current (I_{SINK}) (N-Channel) | $V_{CC} = 10V, V_{OUT} = V_{CC}$ $T_A = 25^\circ C$ | 8.0 | 16 | | mA |
| Q11-Q0 Outputs R_{SOURCE} | $V_{CC} = 10V \pm 5\%$ $V_{OUT} = V_{CC} - 0.3V$ $T_A = 25^\circ C$ | 150 | | 350 | Ω |
| R_{SINK} | $V_{CC} = 10V \pm 5\%$ $V_{OUT} = 0.3V$ $T_A = 25^\circ C$ | 80 | | 230 | Ω |

AC Electrical Characteristics $T_A = 25^\circ\text{C}$, $C_L = 50\text{ pF}$, unless otherwise specified.

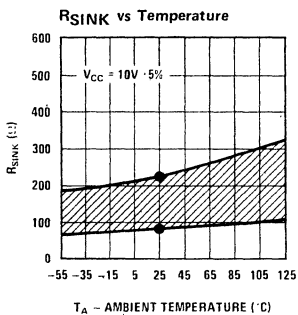
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--------------------------|-----|-----|------|---------------|
| Propagation Delay Time From Clock Input To Outputs (Q0–Q11) ($t_{pd(Q)}$) | $V_{CC} = 5.0\text{V}$ | | 200 | 350 | ns |
| | $V_{CC} = 10\text{V}$ | | 80 | 150 | ns |
| Propagation Delay Time From Clock Input To D_O ($t_{pd(D_O)}$) | $V_{CC} = 5.0\text{V}$ | | 180 | 325 | ns |
| | $V_{CC} = 10\text{V}$ | | 70 | 125 | ns |
| Propagation Delay Time From Register Enable (\bar{E}) To Output (Q11) ($t_{pd(\bar{E})}$) | $V_{CC} = 5.0\text{V}$ | | 190 | 350 | ns |
| | $V_{CC} = 10\text{V}$ | | 75 | 150 | ns |
| Propagation Delay Time From Clock To $\bar{C}\bar{C}$ ($t_{pd(\bar{C}\bar{C})}$) | $V_{CC} = 5.0\text{V}$ | | 190 | 350 | ns |
| | $V_{CC} = 10\text{V}$ | | 75 | 0.50 | ns |
| Data Input Set-Up Time (t_{DS}) | $V_{CC} = 5.0\text{V}$ | 80 | | | ns |
| | $V_{CC} = 10\text{V}$ | 30 | | | ns |
| Start Input Set-Up Time (t_{SS}) | $V_{CC} = 5.0\text{V}$ | 80 | | | ns |
| | $V_{CC} = 10\text{V}$ | 30 | | | ns |
| Minimum Clock Pulse Width (t_{PWL} , t_{PWH}) | $V_{CC} = 5.0\text{V}$ | 250 | 125 | | ns |
| | $V_{CC} = 10\text{V}$ | 100 | 50 | | ns |
| Maximum Clock Rise and Fall Time (t_r , t_f) | $V_{CC} = 5.0\text{V}$ | | | 15 | μs |
| | $V_{CC} = 10\text{V}$ | | | 5 | μs |
| Maximum Clock Frequency (f_{MAX}) | $V_{CC} = 5.0\text{V}$ | 2 | 4 | | MHz |
| | $V_{CC} = 10\text{V}$ | 5 | 10 | | MHz |
| Clock Input Capacitance (C_{CLK}) | Clock Input (Note 2) | | 10 | | pF |
| Input Capacitance (C_{IN}) | Any Other Input (Note 2) | | 5 | | pF |
| Power Dissipation Capacitance (C_{PD}) | (Note 3) | | 100 | | pF |

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. Except for "Operating Temperature Range" they are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" provides conditions for actual device operation.

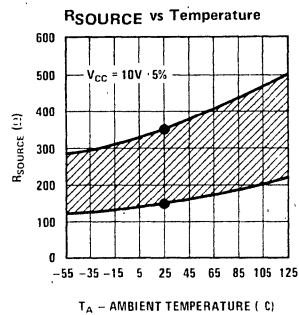
Note 2: Capacitance is guaranteed by periodic testing.

Note 3: C_{PD} determines the no load ac power consumption of any CMOS device. For complete explanation see 54C/74C Family Characteristics application note, AN-90.

Typical Performance Characteristics

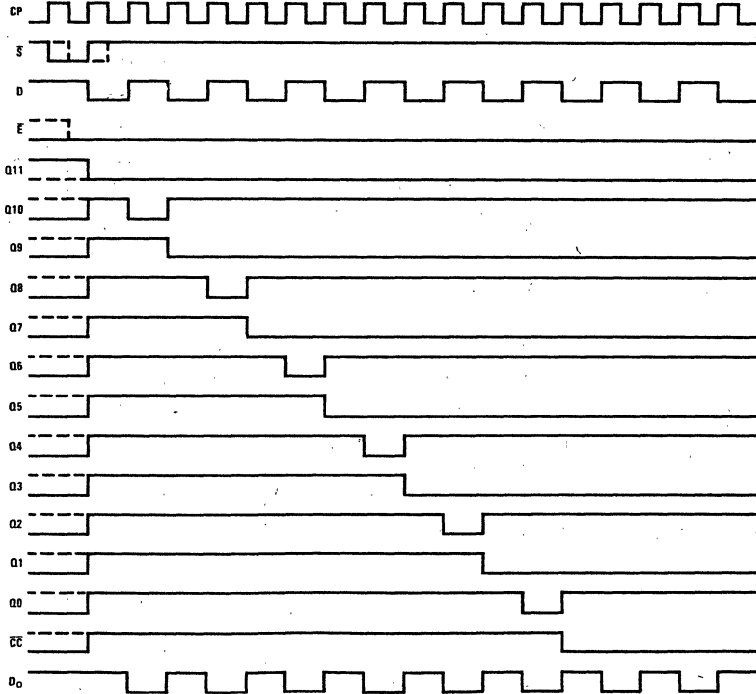


● These points are guaranteed by automatic testing.

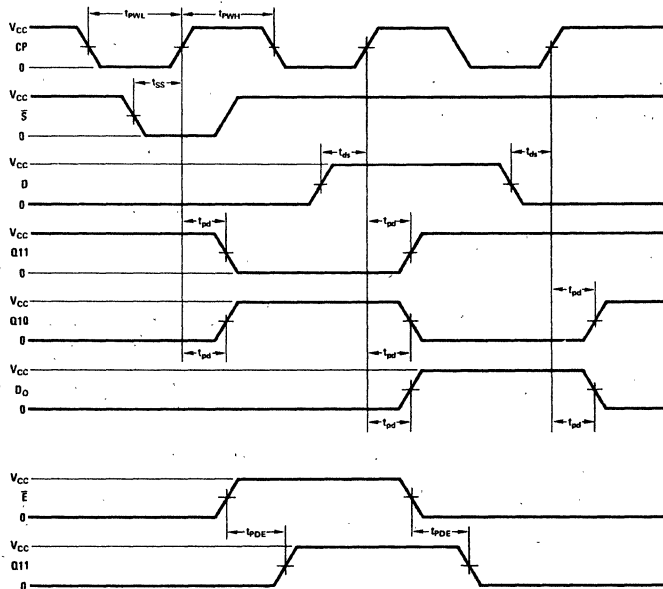


● These points are guaranteed by automatic testing.

Timing Diagram



Switching Time Waveforms



USER NOTES FOR A/D CONVERSION

The register can be used with either current switches that require a low voltage level to turn the switch ON or current switches that require a high voltage level to turn the switch ON. If current switches are used which turn ON with a low logic level, the resulting digit output from the register is active low. That is, a logic "1" is represented as a low voltage level. If current switches are used which turn ON with a high logic level, the resulting digit output is active high. A logic "1" is represented as a high voltage level.

For a maximum error of $\pm 1/2$ LSB, the comparator must be biased. If current switches that require a high voltage level to turn ON are used, the comparator should be biased $+1/2$ LSB and if the current switches require a low logic level to turn ON, then the comparator must be biased $-1/2$ LSB.

The register can be used to perform 2's complement conversion by offsetting the comparator one half full

range $+1/2$ LSB and using the complement of the MSB Q11 as the sign bit.

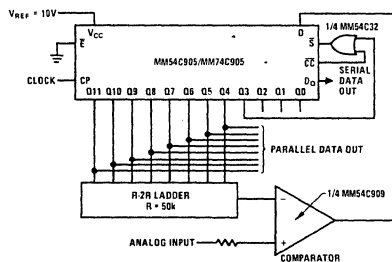
If the register is truncated and operated in the continuous conversion mode, a lock-up condition may occur on power-ON. This situation can be overcome by making the START input the "OR" function of \overline{CC} and the appropriate register output.

The register, by suitable selection of register ladder network, can be used to perform either binary or BCD conversion.

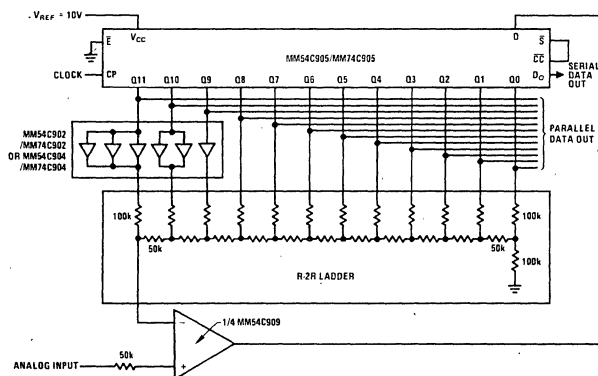
The register outputs can drive the 10 bits or less with 50k/100k R/2R ladder network directly for $V_{CC} = 10V$ or higher. In order to drive the 12-bit 50k/100k ladder network and have the $\pm 1/2$ LSB resolution, the MM54C902/MM74C902 or MM54C904/MM74C904 is used as buffers, three buffers for MSB (Q11), two buffers for Q10, and one buffer for Q9.

Typical Applications

12-Bit Successive Approximation A-to-D Converter Operating in Continuous 8-Bit Truncated Mode



12-Bit Successive Approximation A-to-D Converter, Operating in Continuous Mode, Drives the 50k/100k Ladder Network Directly



Definition of Terms

CP: Register clock input.

CC: Conversion complete—this output remains at $V_{OUT(1)}$ during a conversion and goes to $V_{OUT(0)}$ when conversion is complete.

D: Serial data input—connected to comparator output in A-to-D applications.

E: Register enable—this input is used to expand the length of the register. When E is at $V_{IN(1)}$ Q11 is forced to $V_{OUT(1)}$ and inhibits conversion. When not used for expansion E must be connected to $V_{IN(0)}$ (GND).

Q11: True register MSB output.

$\overline{Q11}$: Complement of register MSB output.

Qi (i = 0 to 11): Register outputs.

S: Start input—holding start input at $V_{IN(0)}$ for at least one clock period will initiate a conversion by setting MSB (Q11) at $V_{OUT(0)}$ and all other output (Q10-Q0) at $V_{OUT(1)}$. If set-up time requirements are met, a conversion may be initiated by holding start input at $V_{IN(0)}$ for less than one clock period.

DO: Serial data output—D input delayed by one clock period.



**National
Semiconductor**

TP3000 CODEC System (TP3001 μ -Law, TP3002 A-Law)

A to D, D to A

General Description

The TP3001 and TP3002 are Pulse Code Modulation (PCM) systems for the digital coding and decoding of analog signals in the voice frequency band. The TP3001 system utilizes μ -law coding of the analog signals while the TP3002 is an A-law system. Each system consists of 2 IC packages. The TP3001 system uses linear part LF3700 and CMOS part MM58100. The TP3002 system uses the same linear part and a different CMOS part (MM58150). Each system samples a filtered ($300 \text{ Hz} \leq f \leq 3.4 \text{ kHz}$) analog signal at an 8 kHz rate, converts this sampled voltage to an 8-bit companded digital code (μ -law or A-law) and loads this code into a high speed serial output buffer. This output buffer will operate at any speed between 64 and 2100 kilobits per second. Either system will also accept an incoming 8-bit PCM word (again, at any speed between 64 and 2100 kilobits per second) and will automatically interrupt the encode cycle to decode the PCM word and update the CODEC output sample and hold. After decoding, the systems will automatically return to the encoding cycle. This interrupt capability allows either CODEC system to send and receive PCM data asynchronously. These systems were specifically designed for low cost "per line" or per channel CODEC applications.

These IC's contain all the necessary elements required for a complete CODEC system—both the input and output sample and hold, comparator, stable voltage reference, non-linear D/A converter, successive approximation logic, control logic and digital input and output PCM buffers. The user must provide an input aliasing filter ($300 \text{ Hz} \leq f \leq 3.4 \text{ kHz}$) such as the AF133 or similar filter. The AF134, or similar filter, is available for use as the output filter ($300 \text{ Hz} \leq f \leq 3.4 \text{ kHz}$) which is needed to reject sidebands around 8 kHz and provide correction for the $\sin x/x$ frequency distortion introduced by the output sample and hold.

A special auto-zero circuit insures an extremely low idle channel noise and low crosstalk enhancement. During the decode cycle, the non-linear D/A converter is shifted $1/2$ LSB, thereby achieving a typical signal to total distortion performance of at least 3 dB better than the D3 channel bank specifications.

The TP3001 system also includes 4 pins for the insertion and extraction of the signaling bits required for D3 channel bank operation.

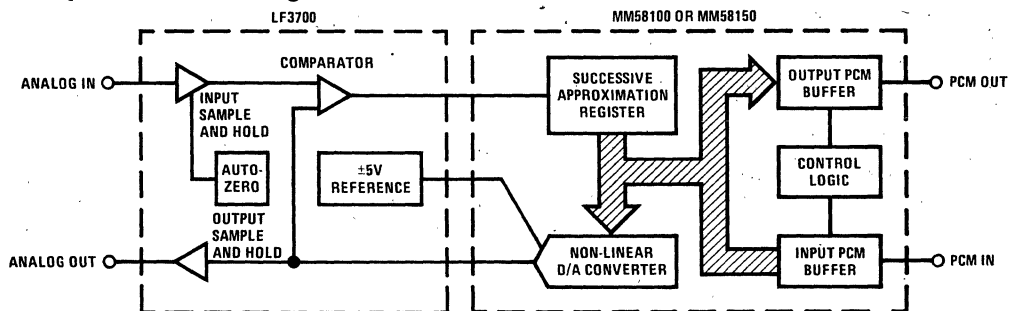
Features

- TP3001 uses the standard μ -255 code
- TP3002 uses the standard A-law code
- Each 2-chip system includes:
 - Non-linear D/A converter
 - Voltage reference with excellent long term stability
 - Comparator
 - Successive approximation logic
 - Input digital buffer
 - Output digital buffer
 - Input sample and hold
 - Output sample and hold
 - Auto-zero circuit
 - Control logic
- TP3001 system meets or exceeds all relevant D3 channel bank specifications
- Both systems meet or exceed all relevant CCITT specifications
- Analog input range of $\pm 5V$
- Analog output range of $\pm 5V$
- Input and output PCM words can be clocked at 64 to 2100 kilobits per second
- Incoming PCM word may be asynchronous
- Provision for the insertion and extraction of signaling bits in the TP3001 system
- Open drain PCM out for TRI-STATE[®] capability

Applications

- Use with digital switching systems in telephone central office or private branch exchange
- Replace 24 or 32-channel shared CODEC in telephone channel bank
- Use to digitize voice and similar analog signals for low noise transmission and reception

Simplified Block Diagram



Absolute Maximum Ratings

| | |
|---|----------------------------------|
| V ⁺ to Gnd | 15V |
| V ⁻ to Gnd | -15V |
| Voltage at Any Pin Except Digital Inputs or Digital Outputs | V ⁺ to V ⁻ |
| Voltage at Any Digital Input or Output | -0.3 to +5.5V |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

V⁺ = 12V, V⁻ = -12V, V_{EE} = -12V (Note 4) over operating temperature range, unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|------|-----------|------|---|
| Signal-to-Distortion TP3001 or TP3002 Either Encoding or Decoding | Method 1: A Suitable Noise Signal Applied to the Coder Input Between -55 dBm0 and -3 dBm0 (Refer to CCITT Rec. G712, Paragraph 9, Method 1), (Figure 4) Method 2: Measured with C Message Weighting Filter, 1020 Hz Input Signal 0 dBm0 to -30 dBm0 -40 dBm0 -45 dBm0 (Figure 5) | | 2 | | dB Above the CCITT Limits Shown in Figure 1. |
| Gain Tracking Error TP3001 or TP3002 Either Encoding or Decoding | Method 1: Deviation From Gain at -10 dBm0 A Suitable Noise Signal Applied to the Coder Input Between -60 dBm0 and -10 dBm0 (Refer to CCITT Rec. G712, Paragraph 11, Method 1, (Figure 4)) Method 2: Deviation From Gain at 0 dBm0 1020 Hz Input Signal 3 dBm0 to -37 dBm0 -37 dBm0 to -50 dBm0 (Figure 6) | | | | Within Limits Shown in Figure 2 (Note that Figure 2 is 1/2 of the Limits Set by CCITT.) |
| Idle Channel Noise TP3001 TP3002 | Input Terminated with 600Ω (Figure 7) | | 12 -72 | | dB _{rnc0} dB _{m0p} |
| Single Frequency Distortion | 1020 Hz Input Signal at 0 dBm0, (Figure 8) | | | -40 | dBm0 |
| Reference Voltage | (Note 1) | 5.25 | 5.50 | 5.75 | V |
| Temperature Coefficient of Reference Voltage | | | ±1.5 | | mV/°C |
| Decoder 0 dBm0 Output Level | (Note 1) | 2.58 | 2.70 | 2.82 | V _{rms} |
| Intrachannel Crosstalk Go-to-Return Crosstalk | Level at Decoder Output Due to a 0 dBm0 Signal Being Encoded (Figure 9) | | | -62 | dBm0 |
| Return-to-Go Crosstalk | Level at Encoder Output (Measured Via Independent Decoder) Due to a 0 dBm0 Signal Being Decoded (Figure 10) | | | -70 | dBm0 |

Electrical Characteristics (Continued)

$V^+ = 12V$, $V^- = -12V$, $V_{EE} = -12V$ (Note 4) over operating temperature range, unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|-----|------------|------|---|
| Interchannel Crosstalk (TP3001 Only) | Level at Decoder Output When a -80 dBm0 Signal is Applied to Encoder Input (Figure 11) | | -83 | | dBm0 |
| Analog Output Frequency Response | $300 \leq f \leq 3.4$ kHz | | ± 0.05 | | dB Deviation From Theoretical $\sin x/x$ Response (Figure 3) |
| Logical "1" Input Voltage | (Note 5) | 4.0 | | | V |
| Logical "1" Input Current | Digital $V_{IN} = 5V$ | | | 1 | μA |
| Logical "0" Input Voltage | | | | 0.8 | V |
| Logical "0" Input Current | Digital $V_{IN} = 0V$ | | | -1 | μA |
| Master Clock Frequency, F_C | For Proper Operation: Duty Cycle = $50\% \pm 10\%$ | | 128 | | kHz |
| Input and Output PCM Buffer Clocks (F_{bo} and F_{bi}) | F_o and $F_i = 8$ kHz F_{bo} , F_{bi} Duty Cycle = $40-60\%$ | 64 | | 2100 | kHz |
| Propagation Delay F_{bo} to Valid PCM Out | | 50 | 150 | 250 | ns |
| PCM Out Pin Capacitance | | | 4 | | pF |
| PCM Out Fall Time | 1 k Ω Resistor to V_{DD} 100 pF Capacitor to V_{SS} | | 50 | 150 | ns |
| System Power Dissipation | F_{bo} , $F_{bi} = 1.544$ MHz | | 250 | 300 | mW |
| Shutdown Mode (LF3701 Only) | Pin 3 at Logic High | | 10 | 20 | mW |

Note 1: The relationship between the digital coding and the relative audio signal level is fixed as follows: a sine wave of 1 kHz and a nominal level of 0 dBm0 should be present at the audio output of the decoder when the appropriate character sequence shown below is applied to the decoder input.

| TP3001 SYSTEM | | | | | | | |
|---------------|---|---|---|---|---|---|-----|
| μ -LAW | | | | | | | |
| MSB | 2 | 3 | 4 | 5 | 6 | 7 | LSB |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |

| TP3002 SYSTEM | | | | | | | |
|---------------|---|---|---|---|---|---|-----|
| A-LAW | | | | | | | |
| MSB | 2 | 3 | 4 | 5 | 6 | 7 | LSB |
| 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |

The resulting theoretical load capacity (T_{MAX}) is 3.17 dBm0 for the TP3001 system (μ -law) and 3.14 dBm0 for the TP3002 system (A-law).

Note 2: The PCM transmit filter must be AC coupled to the CODEC and a resistor of 24 k Ω or lower must be tied between analog in and analog ground. CODEC input impedance will then appear as 24 k Ω .

Note 3: PCM OUT and S_i are open drain outputs and will require external pull-up resistors to +6V maximum, 1 k Ω for PCM OUT and 10 k Ω for S_i are recommended when $F_{bo} = F_{bi} = 2.1$ MHz.

Note 4: Special care must be taken to assure that the substrate to ground pn junction is never forward biased. In cases where the negative power must be open circuited, it is recommended that a high current diode (1 amp Schottky) be placed between V^- and ground. It is further recommended that the power supply turn-on sequence be as follows: V^- or ground first, followed by V^+ . Power supply turn-off should reverse the procedure.

Note 5: For TTL or LS compatibility, external pull-up resistors are required between the digital inputs and the TTL or LS logic power supply.

System Description (Refer to block diagrams)

The master clock for the system is F_C and must be run at 128 kHz which divides the $125 \mu s$ ($1/8$ kHz) time-frame into 16 time slots. The rising edge of the Output Sync (F_O) initiates the encoding cycle. The Input Sample and Hold Control (IN S/H CNTL) will go high for $19 \mu s$ thereby causing the input sample and hold to acquire a new input analog voltage. This acquired analog voltage is presented to a UNITY GAIN BUFFER located on the CMOS chip and then forwarded to the positive comparator input on the linear chip. The successive approximation will then begin. The SUCCESSIVE APPROXIMATION REGISTER will first load a zero code into the NON-LINEAR D/A CONVERTER. The output of the D/A converter goes to a second unity gain buffer and then to the negative input of the comparator on the linear chip. The comparator will then decide if the sampled analog voltage is positive or negative. If the analog input voltage is positive, the CONTROL LOGIC will pull the polarity control line high, which in turn will cause the voltage reference on the linear chip to deliver a positive reference voltage to the NON-LINEAR D/A CONVERTER. Conversely, if the analog input voltage is negative, a negative reference voltage will be applied to the NON-LINEAR D/A. The successive approximation will turn ON the second bit to the NON-LINEAR D/A CONVERTER and a decision is made to either leave that bit ON, or turn it OFF. The logic will then turn ON the third bit and make a decision to leave that bit ON or turn it OFF. In this way, the analog input voltage can be converted into the standard 8-bit μ -law or A-law code in 8 clock cycles.

At the end of the encode cycle the 8-bit code is loaded into the OUTPUT PCM BUFFER. The word is read out serially (MSB first) on PCM OUT by the Output Clock (F_{BO}) and the Output Sync (F_O).

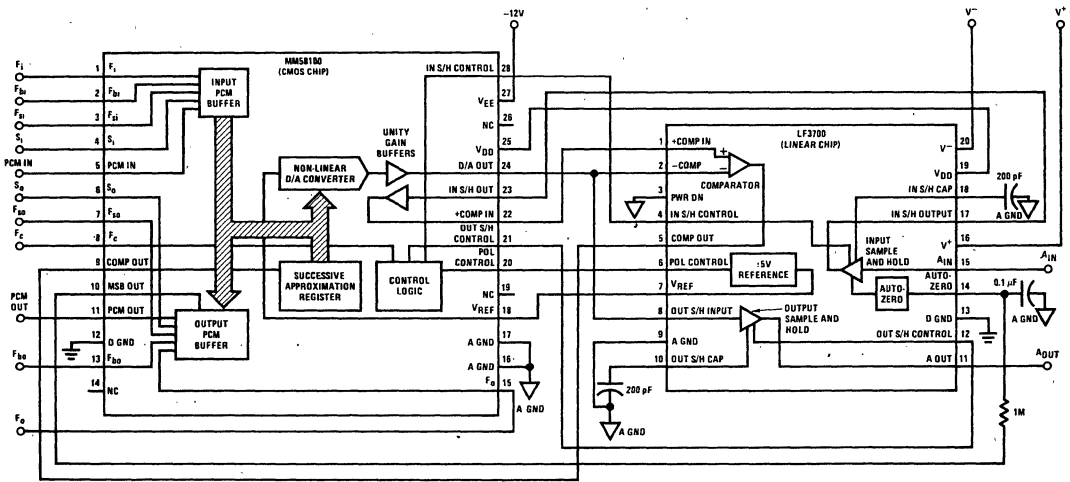
The incoming PCM word is read in serially (MSB first) on the PCM IN line by the Input Clock (F_{BI}) and the Input Sync (F_I). When the input word has been read in and F_I goes low, the system will immediately switch over to the decode mode. The current status of the successive approximation is temporarily stored while the decode word is delivered to the NON-LINEAR D/A CONVERTER. During decode, the ladder is shifted the required $1/2$ LSB to minimize distortion. The CONTROL LOGIC will then raise the Output S/H Control line so that the Output Sample and Hold will acquire this new output voltage. After 4 clock cycles the circuit will return to the encode mode. The analog output of the system will therefore be a staircase type output with the associated $\sin x/x$ frequency distortion, (Figure 3).

The system incorporates an AUTO-ZERO circuit to ensure a low DC offset for the encoding process, and very low idle channel noise. The encoded MSB (the sign bit) is latched on the MSB OUT pin. This signal then is fed to a simple external low pass RC filter (with a time constant of about 100 ms to 1 sec) and then to the AUTO-ZERO pin on the LF3700. The DC voltage on this pin will adjust the offset of the input sample and hold to correct for any offset voltage in the encoding path. This will also correct for up to ± 20 mV DC offset voltage present in the analog input signal. This scheme simply forces equal numbers of positive and negative voltages over the long term.

There are 4 pins available in the TP3001 system for the insertion and extraction of signaling bits. The operation of these pins is covered in the timing diagrams.

System Block Diagrams

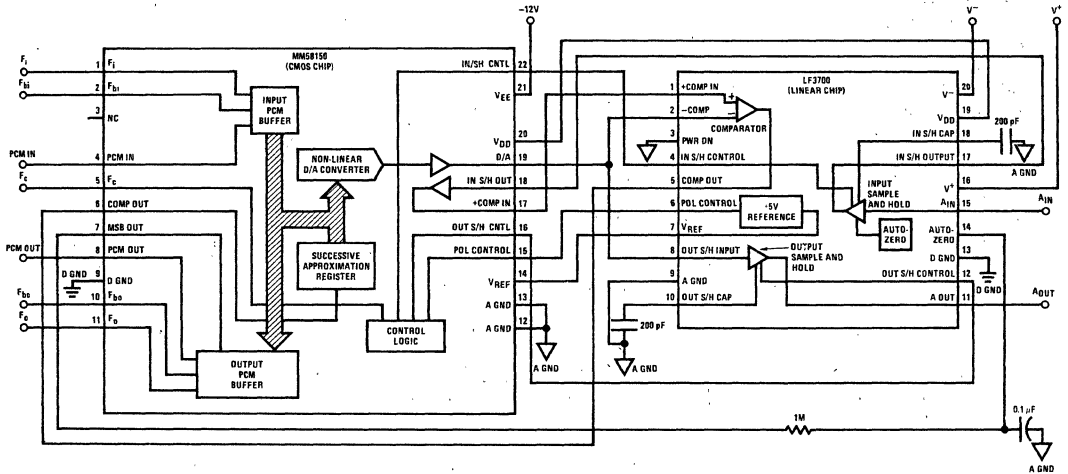
TP3001 System



Note. Pin 3 of the LF3700 should be connected to analog ground. Pin 3 of the LF3701 is a power down control; logic high (5V) is the power down standby mode for the TP3000 systems.

System Block Diagrams (Continued)

TP3002 System



Note. Pin 3 of the LF3700 should be connected to analog ground. Pin 3 of the LF3701 is a power down control; logic high (5V) is the power down standby mode for the TP3000 systems.

Ordering Information

| SYSTEM | ORDER LINEAR PART: D20A | AND CMOS PART: D24A |
|----------------|-------------------------|---------------------|
| TP3001 (μ-law) | LF3700D | MM58100D |
| TP3002 (A-law) | LF3700D | MM58150D |

Description of Pin Functions

CMOS PIN FUNCTIONS:

| MM58100 PIN NO. | MM58150 PIN NO. | NAME | FUNCTION |
|-----------------|-----------------|--|--|
| 1 | 1 | F _i (INPUT SYNC) | When this line goes high, the data on the PCM IN line is shifted into the INPUT PCM BUFFER by F _{bi} (INPUT CLOCK). This line must be high for 8 clock pulses of F _{bi} . When F _i goes low, the incoming PCM word is loaded into the NON-LINEAR D/A CONVERTER and the OUTPUT SAMPLE AND HOLD is placed in the acquire mode. During decode, the D/A converter is shifted 1/2 LSB. After the decode is complete, the successive approximation will resume. |
| 2 | 2 | F _{bi} (INPUT PCM CLOCK) | The leading edges of this clock will serially shift the data on the PCM IN line into the INPUT PCM BUFFER when the F _i (INPUT SYNC) line is high. |
| 3 | - | F _{si} (MM58100 INPUT SIGNALING ENABLE) | When this line is high, the falling edge of F _i (INPUT SYNC) will transfer the LSB of the incoming PCM word to S _i (INPUT SIGNALING BIT). The PCM word is then decoded as a 7-bit code. |
| 4 | - | S _i (MM58100 INPUT SIGNALING BIT) | When F _{si} (INPUT SIGNALING ENABLE) is high, the LSB of the incoming PCM word is transferred to this line and latched by the falling edge of F _i (INPUT SYNC). An external pull-up resistor of 10k to the digital positive supply is required. |

CMOS PIN FUNCTIONS: (Continued)

| MM58100 PIN NO. | MM58150 PIN NO. | NAME | FUNCTION |
|-----------------|-----------------|---|---|
| 5 | 4 | PCM IN | The incoming PCM word is received on this line. |
| 6 | - | S _o (MM58100 OUTPUT SIGNALING ENABLE) | When the F _{so} (OUTPUT SIGNALING ENABLE) line is high the LSB of the PCM word in the OUTPUT SIGNALING BUFFER is replaced by the logic state on this line. |
| 7 | - | F _{so} (MM58100 OUTPUT SIGNALING ENABLE) | When this line is high and F _o (OUTPUT SYNC) is low, the logic level on S _o (OUTPUT SIGNALING BIT) is transferred to the LSB of the OUTPUT PCM BUFFER. |
| 8 | 5 | F _c (MASTER CLOCK) | This is the principal clock of the CODEC system. All CODEC functions with the exception of F _i (INPUT SYNC) and F _{bi} (INPUT CLOCK) are synchronized to F _c . This clock frequency should be 128 kHz. |
| 9 | 6 | COMP OUT | This is the output of the analog comparator which is used in the successive approximation conversion. |
| 10 | 7 | MSB OUT | The encoded MSB appears on this line for use in the AUTO ZERO function. |
| 11 | 8 | PCM OUT | The result of the digital encoding is available on this line. A 1k external resistor to the digital positive supply is required. |
| 12 | 9 | D GND (DIGITAL GND) | All digital signals should be referenced to this line. |

Description of Pin Functions (Continued)

CMOS PIN FUNCTIONS: (Continued)

| MM58100 PIN NO. | MM58150 PIN NO. | NAME | FUNCTION |
|-----------------------|-----------------------|--|--|
| 13 | 10 | F _{BO} (OUTPUT PCM CLOCK) | The falling edges of this clock will serially shift the PCM word in the PCM OUTPUT BUFFER to the PCM OUTPUT line. |
| 14 | — | No Connection | |
| 15 | 11 | F _O (OUTPUT SYNC) | When this line goes high, the output PCM word can be shifted out by F _{BO} (OUTPUT CLOCK). This line must be high for 8 clock pulses of F _{BO} . When F _O goes high, the following sequence is initiated: the INPUT SAMPLE AND HOLD first acquires the ANALOG IN voltage and a successive approximation conversion is made on that voltage using the NON-LINEAR D/A CONVERTER and the COMPARATOR. The resulting 8-bit PCM word is then loaded into the OUTPUT PCM BUFFER. |
| 16 | 12 | A GND ₁ (ANALOG GROUND) | All analog signals should be referenced to this line. |
| 17 | 13 | A GND (ANALOG GROUND) | All analog signals should be referenced to this line. |
| 18 | 14 | VREF | This is the +VREF or the -VREF for the NON-LINEAR D/A CONVERTER. |
| 19 | — | No Connection | |
| 20 | 15 | POL CNTL (POLARITY CONTROL) | This is the digital command for +VREF or -VREF. |
| 21 | 16 | OUT S/H CNTL (OUTPUT SAMPLE AND HOLD CONTROL) | This is the digital command for the OUTPUT SAMPLE AND HOLD to acquire a new voltage. |
| 22 | 17 | +COMP IN (NON-INVERTING COMPARATOR INPUT) | This is the output of the buffer amplifier for the input sample and hold. This is connected to the +COMP IN pin on the linear chip. |
| 23 | 18 | IN S/H OUT (OUTPUT OF THE INPUT SAMPLE AND HOLD) | This is the input of the buffer amplifier for the input sample and hold. This is connected to the output of the input sample and hold on the linear chip. |
| 24 | 19 | D/A OUT | This is the output voltage of the NON-LINEAR D/A CONVERTER. |
| 25 | 20 | VDD | This is the positive voltage supply for the digital chip which is provided by the analog chip. |
| 26 | — | No Connection | |
| 27 | 21 | VEE | This is the negative supply voltage for the digital chip (-12V). |
| 28 | 22 | IN S/H CNTL (INPUT SAMPLE AND HOLD CONTROL) | This is the digital command for the INPUT SAMPLE AND HOLD to acquire a new voltage. |

LINEAR PIN FUNCTIONS:

| LF3700 PIN NO. | NAME | FUNCTION |
|----------------------|---|---|
| 1 | +COMP IN (NON-INVERTING COMPARATOR INPUT) | This is tied to the +COMP IN pin on the CMOS chip. |
| 2 | -COMP IN (INVERTING COMPARATOR INPUT) | This is tied to the D/A OUT pin on the CMOS chip and the OUTPUT SAMPLE AND HOLD INPUT pin on the linear chip. |
| 3 | POWER DOWN | Connect to Analog Gnd - LF3700 (LF3701 see note System Block Diagram). |
| 4 | IN S/H CNTL (INPUT SAMPLE AND HOLD CONTROL) | This is tied to the IN S/H CNTL pin on the CMOS chip. |
| 5 | COMP OUT (COMPARATOR OUTPUT) | This is tied to the COMP OUT pin on the CMOS chip. |
| 6 | POL CNTL (POLARITY CONTROL) | This is tied to the POL CNTL pin on the CMOS chip. |
| 7 | VREF | This is tied to VREF on the CMOS chip. |
| 8 | OUT S/H INPUT (INPUT TO OUTPUT SAMPLE AND HOLD) | This is the analog input to the OUTPUT SAMPLE AND HOLD. This should be connected to the D/A OUT pin on the CMOS chip and the inverting comparator input pin on the linear chip. |
| 9 | A GND (ANALOG GROUND) | All analog signals should be referenced to this line. |
| 10 | OUT S/H CAP (OUTPUT SAMPLE AND HOLD CAPACITOR) | A low leakage, 200 pF capacitor should be connected from this line to ANALOG GROUND. |
| 11 | A OUT (ANALOG OUT) | This is the output of the OUTPUT SAMPLE AND HOLD. |
| 12 | OUT S/H CNTL (OUTPUT SAMPLE AND HOLD CONTROL) | This is tied to the OUT S/H CNTL pin on the CMOS chip. |
| 13 | D GND (DIGITAL GROUND) | All digital signals should be referenced to this line. |
| 14 | AUTO Z (AUTO ZERO) | This is connected to the MSB OUT line of the CMOS chip after an external low pass filter. |
| 15 | A IN (ANALOG IN) | This is the appropriately filtered analog input. |
| 16 | V+ | This is the positive supply voltage for the analog chip. |
| 17 | IN S/H OUTPUT (OUTPUT OF INPUT SAMPLE AND HOLD) | This is the analog output voltage of the INPUT SAMPLE AND HOLD. This is tied to the IN S/H OUT pin on the CMOS chip. |
| 18 | IN S/H CAP (INPUT SAMPLE AND HOLD CAPACITOR) | A low leakage, 200 pF capacitor should be connected from this line to analog ground. |
| 19 | VDD | This is the positive supply voltage for the CMOS chip. This is tied to VDD on the CMOS chip. |
| 20 | V- | This is the negative supply for the linear chip. |

Typical Performance Characteristics

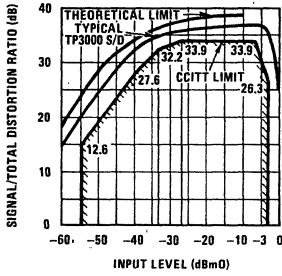


FIGURE 1. Typical Signal/Total Distortion Ratio as a Function of Input Level with a White Noise Source

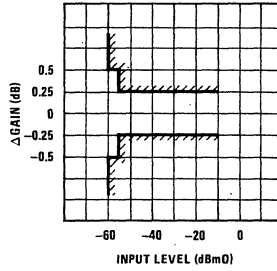


FIGURE 2. Maximum Gain Tracking Error (Δ Gain) as a Function of Input Level with a White Noise Source

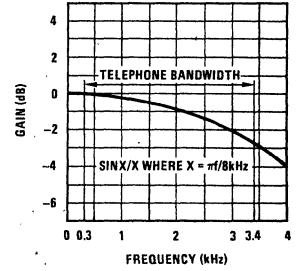
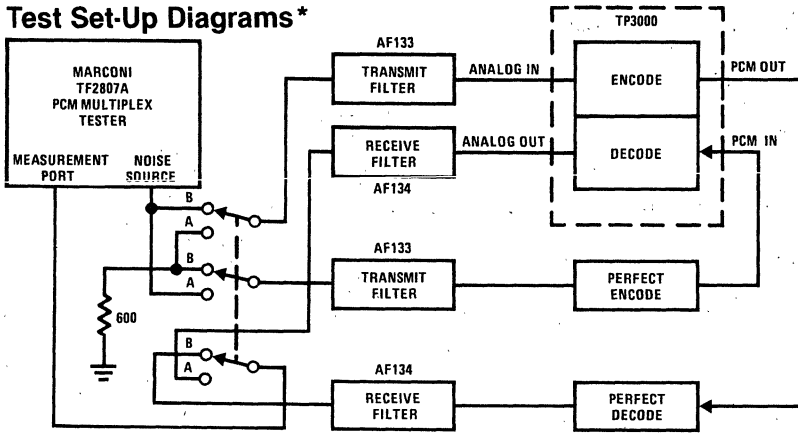


FIGURE 3. Output $\sin x/x$ Frequency Response

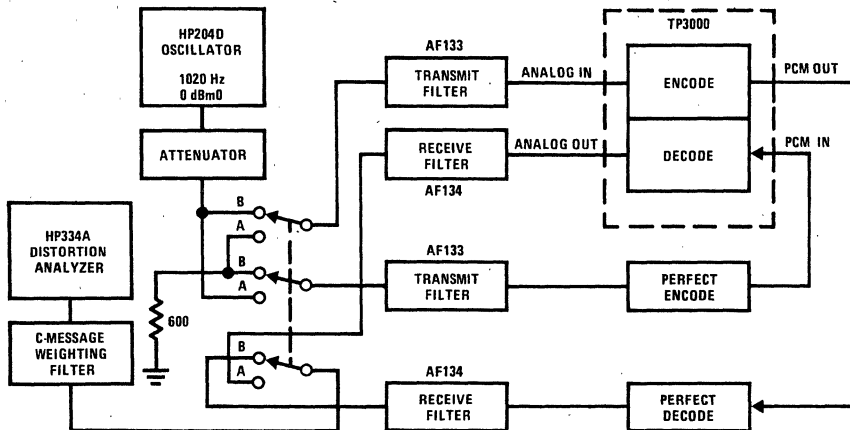
Test Set-Up Diagrams *



Switch position A — Perfect encode; decode TP3000.
Switch position B — Encode TP3000; perfect decode

The Marconi TF2807A's noise output has a probability distribution of amplitude approximating a Gaussian distribution which is band limited to conform with the latest CCITT recommendations.

FIGURE 4. Test Set-Up for Signal-to-Distortion and Gain Tracking Using a Noise Source

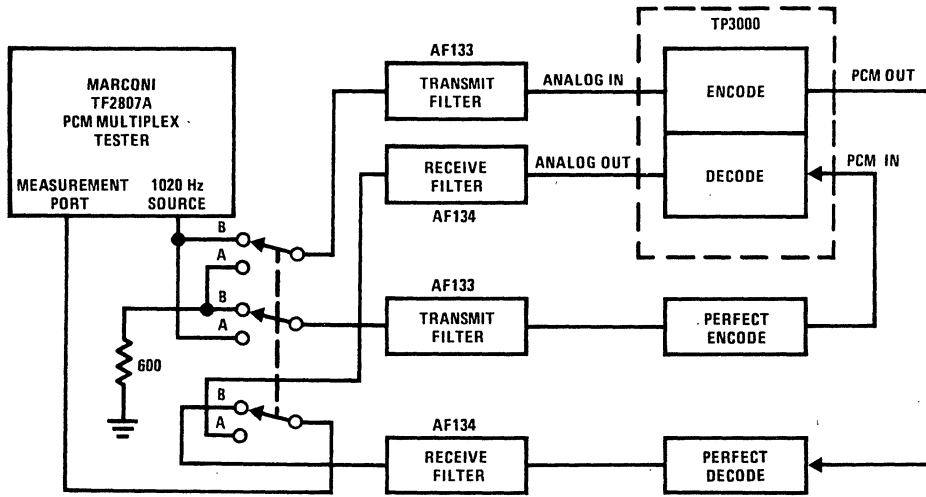


Switch position A — Perfect encode; decode TP3000
Switch position B — Encode TP3000; perfect decode

FIGURE 5. Test Set-Up for Signal-to-Distortion Using a 1020 Hz Signal

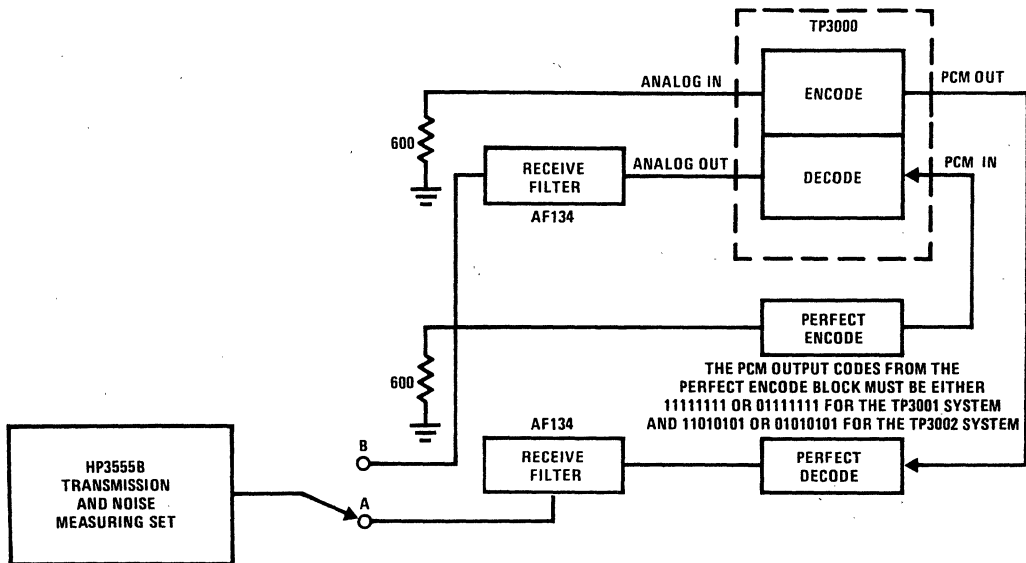
*Perfect encode or decode is μ -law when testing TP3001 and A-law when testing TP3002

Test Set-Up Diagrams* (Continued)



Switch position A -- Perfect encode; decode TP3000
 Switch position B -- Encode TP3000; perfect decode

FIGURE 6. Test Set-Up for Gain Tracking Using 1020 Hz Signal

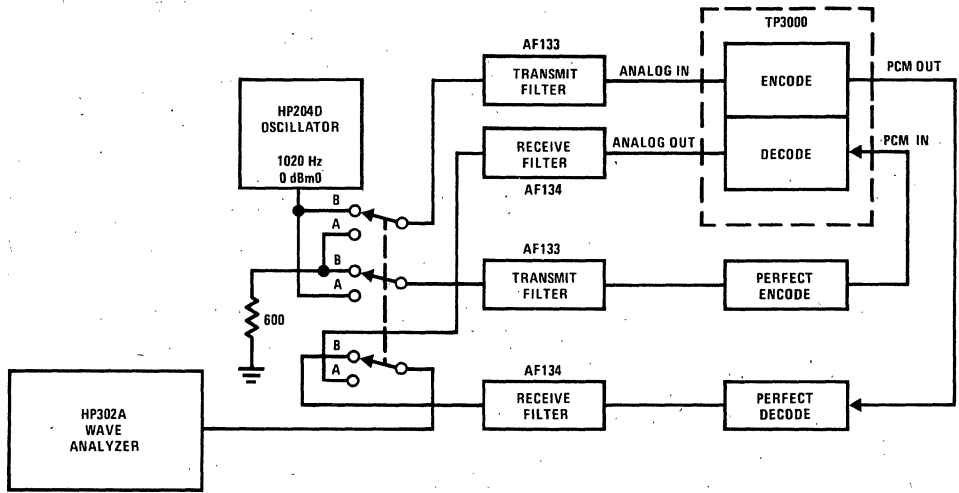


Determine the 0 dBm0 level on the HP3555B and then measure the idle channel noise with the HP3555B in the C-MSG-mode. The noise in dBm0c is 90 dBm0-A, where A is the idle channel noise measurement down from the 0 level (in dB).

FIGURE 7. Test Set-Up for Idle Channel Noise

*Perfect encode or decode is μ -law when testing TP3001 and A-law when testing TP3002

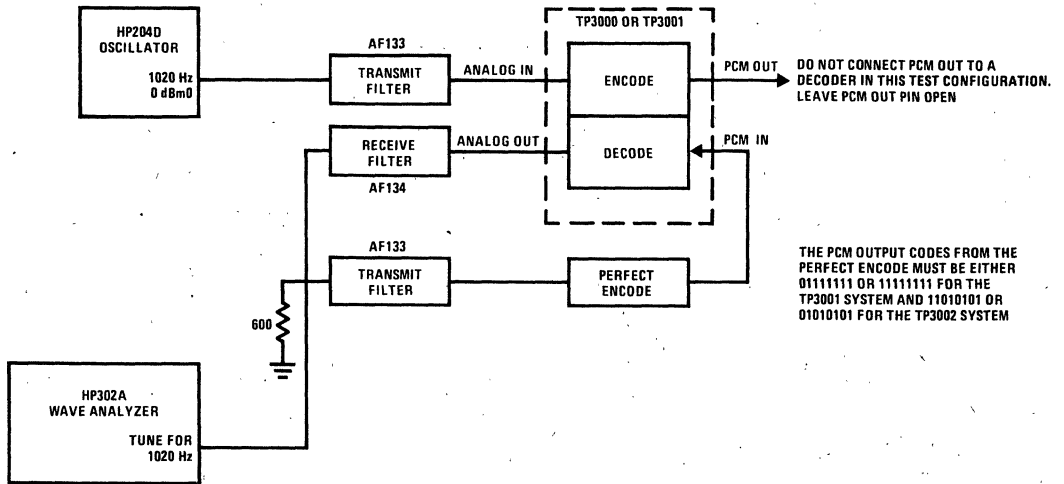
Test Set-Up Diagrams* (Continued)



The output at any frequency (except 1020 Hz) should be at least 40 dB down. The two frequencies of interest are the second and third harmonics (2040 Hz and 3060 Hz).

Switch position A – Perfect encode; decode TP3000
Switch position B – Encode TP3000; perfect decode

FIGURE 8. Test Set-Up for Single Frequency Distortion



DO NOT CONNECT PCM OUT TO A DECODER IN THIS TEST CONFIGURATION. LEAVE PCM OUT PIN OPEN

THE PCM OUTPUT CODES FROM THE PERFECT ENCODE MUST BE EITHER 01111111 OR 11111111 FOR THE TP3001 SYSTEM AND 11010101 OR 01010101 FOR THE TP3002 SYSTEM

FIGURE 9. Test Set-Up for Go-to-Return Crosstalk

*Perfect encode or decode is μ -law when testing TP3001 and A-law when testing TP3002

Test Set-Up Diagrams* (Continued)

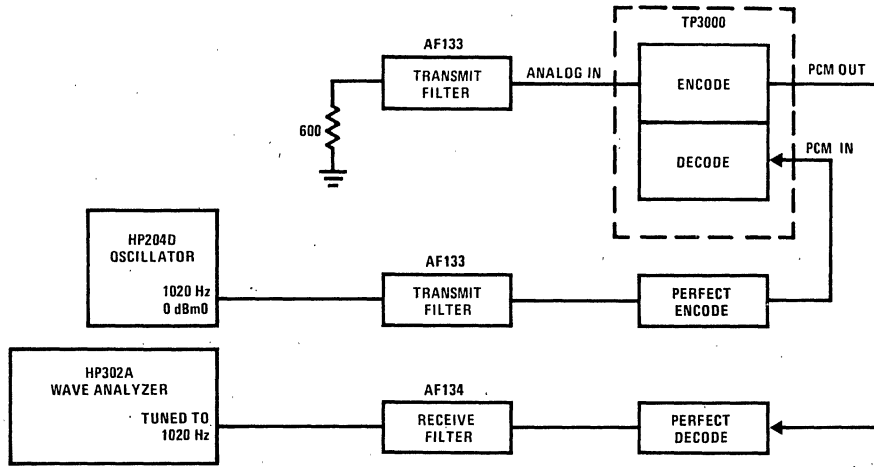
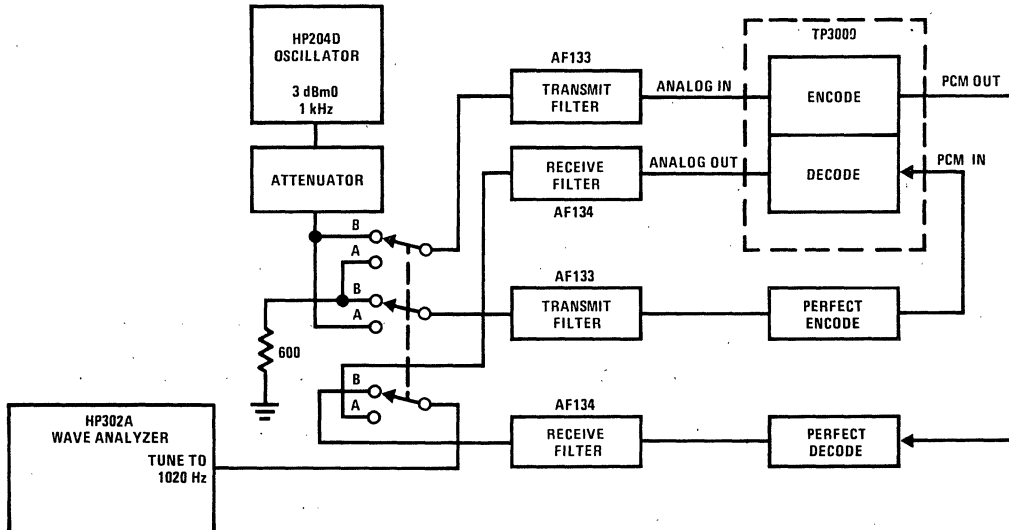


FIGURE 10. Test Set-Up for Return-to-Go Crosstalk



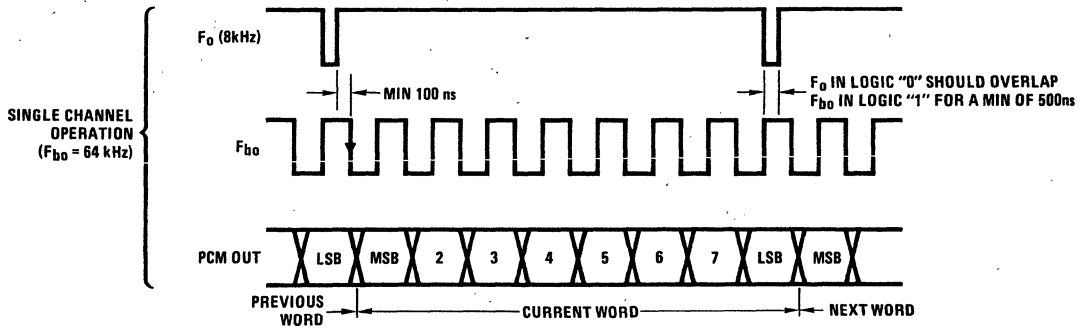
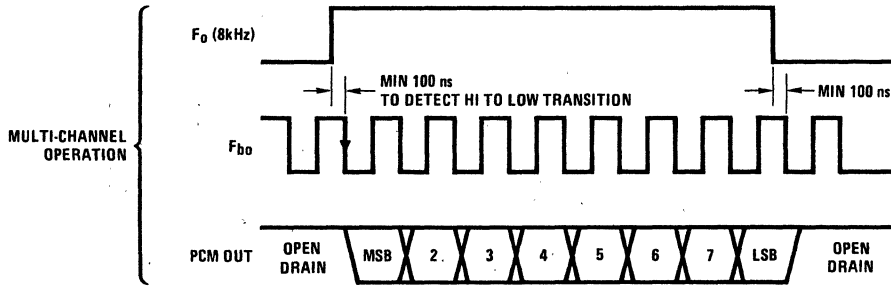
Switch position A — Perfect encode; decode TP3000
 Switch position B — Encode TP3000; perfect decode

FIGURE 11. Test Set-Up for Interchannel Crosstalk

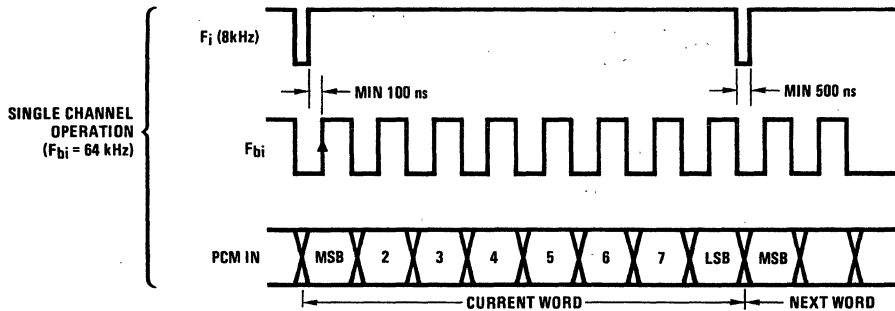
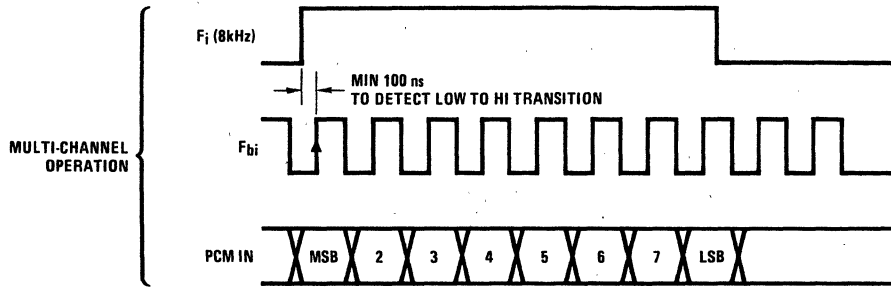
*Perfect encode or decode is μ -law when testing TP3001 and A-law when testing TP3002

Timing Diagrams

SYSTEM TIMING
 F_o , F_{bo} and PCM OUT Relationships



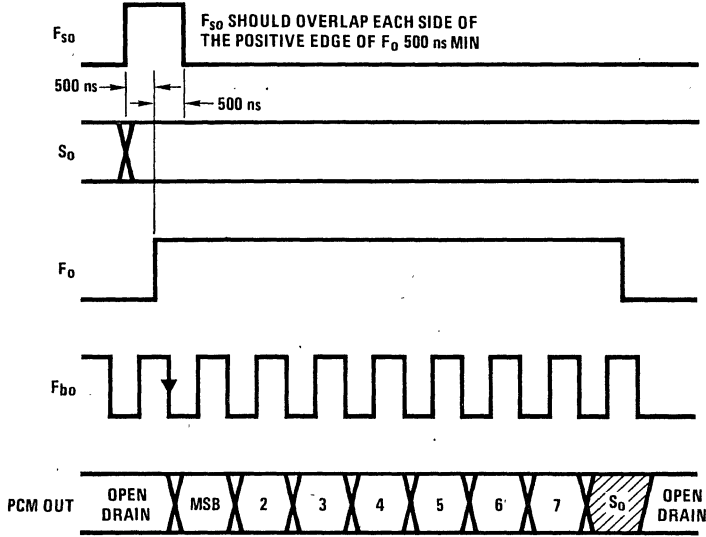
F_i , F_{bi} and PCM IN Relationships



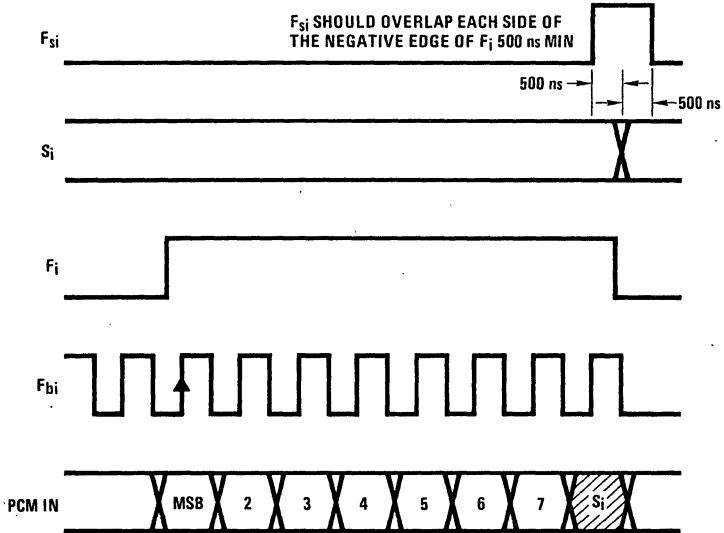
Timing Diagrams (Continued)

SIGNALING
(TP3001 Only)

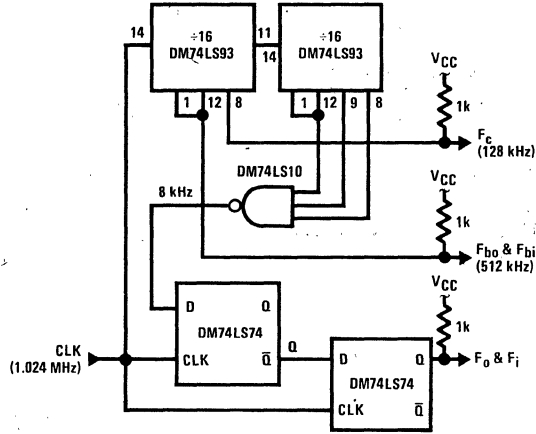
F_{SO} , S_O , F_O Timing Relationships



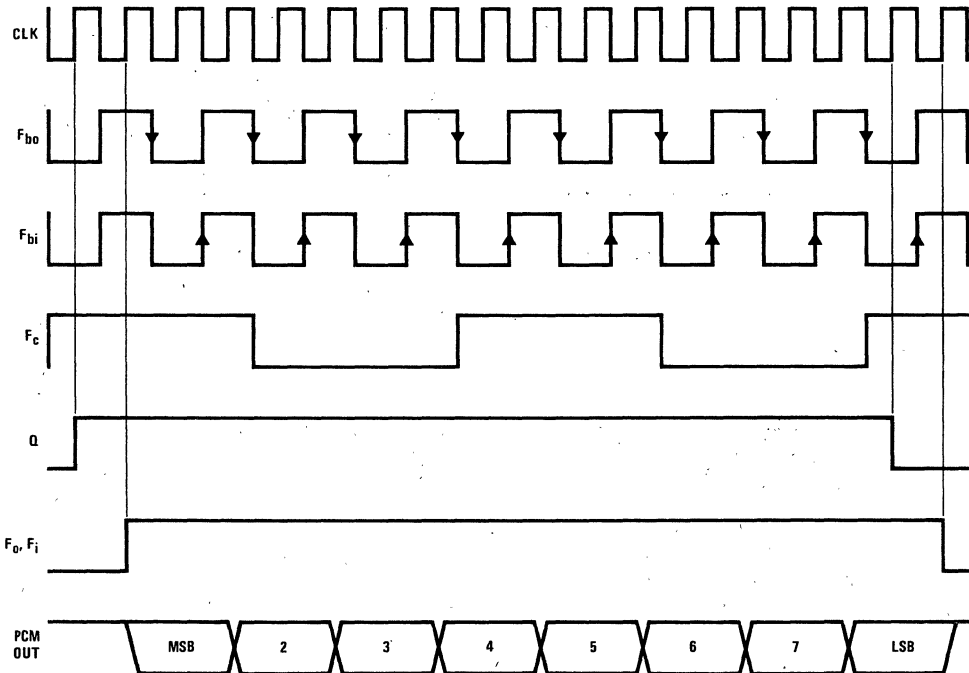
F_{Si} , S_i , F_i Timing Relationships



Timing Generator



Timing Generator Outputs



LH0091 True RMS to DC Converter

general description

The LH0091, rms to dc converter, generates a dc output equal to the rms value of any input per the transfer function:

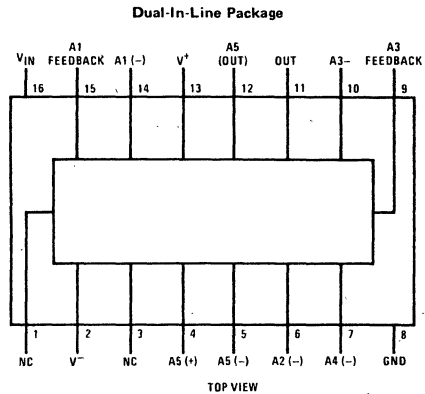
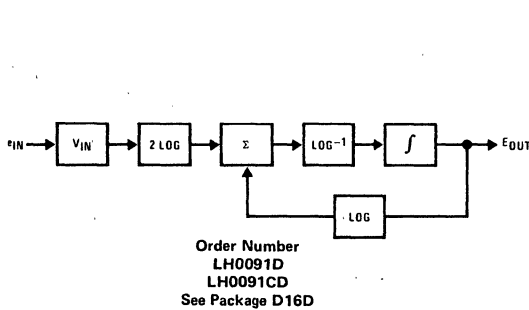
$$E_{OUT(DC)} = \sqrt{\frac{1}{T} \int_0^T E_{IN}^2(t) dt}$$

The device provides rms conversion to an accuracy of 0.1% of reading using the external trim procedure. It is possible to trim for maximum accuracy (0.5 mV ±0.05% typ) for decade ranges i.e., 10 mV → 100 mV, 0.7V → 7V, etc.

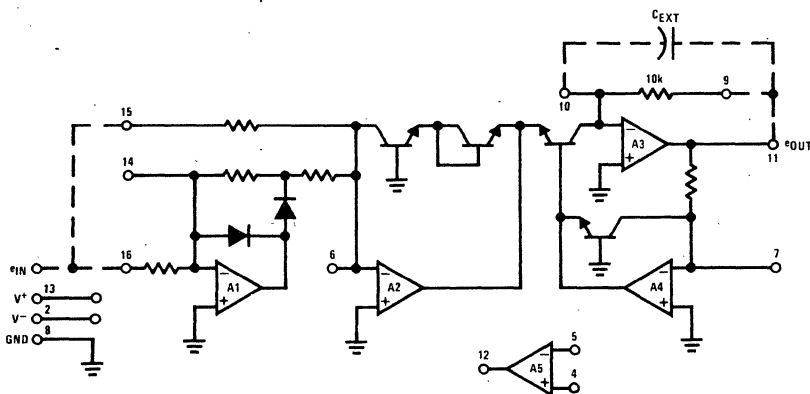
features

- Low cost
- True rms conversion
- 0.5% of reading accuracy untrimmed
- 0.05% of reading accuracy with external trim
- Minimum component count
- Input voltage to ±15V peak for $V_S = \pm 15V$
- Uncommitted amplifier for filtering, gain, or high crest factor configuration
- Military or commercial temperature range.

block and connection diagrams



simplified schematic



Note: Dotted lines denote external connections.

absolute maximum ratings

| | | |
|--|------------------|------------------|
| Supply Voltage | ±22V | |
| Input Voltage | ±15V peak | |
| Output Short Circuit Duration | Continuous | |
| Operating Temperature Range | T _{MIN} | T _{MAX} |
| LH0091 | -55°C | 125°C |
| LH0091C | -25°C | 85°C |
| Storage Temperature Range | | |
| LH0091 | -65°C to +150°C | |
| LH0091C | -25°C to +85°C | |
| Lead Temperature (Soldering, 10 seconds) | 300°C | |

electrical characteristics V_S = ±15V, T_A = 25°C, unless otherwise specified.

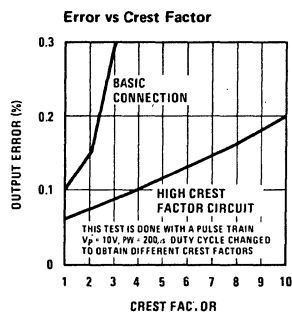
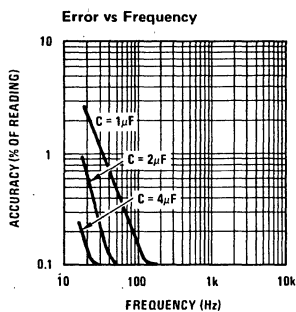
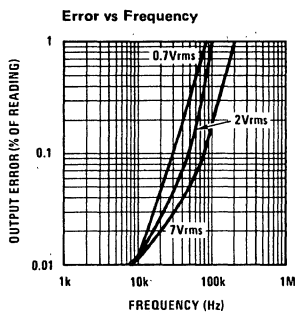
$$\text{Transfer Function} = E_O(\text{DC}) = \sqrt{\frac{1}{T} \int_0^T E_{IN}^2(t) dt}$$

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|-------|--------------|----------|----------|
| ACCURACY (See Definition of Terms) | | | | | |
| Total Unadjusted Error | 50 mVrms ≤ V _{IN} ≤ 7Vrms (Figure 1) | | 20, ±0.5 | 40, ±1.0 | mV, % |
| Total Adjusted Error | 50 mVrms ≤ V _{IN} ≤ 7Vrms (Figure 3) | | 0.5, ±0.05 | 1, ±0.2 | mV, % |
| Total Unadjusted Error vs Temperature | -25°C ≤ T _A ≤ +70°C | | 0.25, ±0.02% | | mV, %/°C |
| Total Unadjusted Error vs Supply Voltage | | | 1 | | mV/V |
| AC PERFORMANCE | | | | | |
| Frequency for Specified Adjusted Error | Input = 7Vrms, Sinewave (Figure 3) | 30 | 70 | | kHz |
| | Input = 0.7Vrms, Sinewave (Figure 3) | | 40 | | kHz |
| | Input = 0.1Vrms, Sinewave (Figure 3) | | 20 | | kHz |
| Frequency for 1% Additional Error | Input = 7Vrms, Sinewave (Figure 3) | 100 | 200 | | kHz |
| | Input = 0.7Vrms, Sinewave (Figure 3) | | 75 | | kHz |
| | Input = 0.1Vrms, Sinewave (Figure 3) | | 50 | | kHz |
| Bandwidth (3 dB) | Input = 7Vrms, Sinewave (Figure 3) | | 2 | | MHz |
| | Input = 0.7Vrms, Sinewave (Figure 3) | | 1.5 | | MHz |
| | Input = 0.1Vrms, Sinewave (Figure 3) | | 0.8 | | MHz |
| Crest Factor | Rated Adjusted Accuracy Using the High Crest Factor Circuit (Figure 5) | 5 | 10 | | |
| INPUT CHARACTERISTICS | | | | | |
| Input Voltage Range | For Rated Performance | ±0.05 | | ±11 | Vpeak |
| Input Impedance | | 4.5 | 5 | | kΩ |
| OUTPUT CHARACTERISTICS | | | | | |
| Rated Output Voltage | R _L ≥ 2.5 kΩ | 10 | | | V |
| Output Short Circuit Current | | | 22 | | mA |
| Output Impedance | | | 1 | | Ω |
| POWER SUPPLY REQUIREMENTS | | | | | |
| Operating Range | | ±5 | | ±20 | V |
| Quiescent Current | V _S = ±15V | | 14 | 18 | mA |

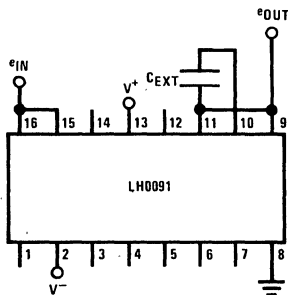
op amp electrical characteristics $V_S = \pm 15V, T_A = 25^\circ C$ unless otherwise specified

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------|--------------------------------|--|----------|----------|-----|-------|
| VOS | Input Offset Voltage | $R_S \leq 10\text{ k}\Omega$ | | 1.0 | 10 | mV |
| IOS | Input Offset Current | | | 4.0 | 200 | nA |
| I _B | Input Bias Current | | | 30 | 500 | nA |
| R _{IN} | Input Resistance | | | 2.5 | | MΩ |
| AOL | Large Signal Voltage Gain | $V_{OUT} = \pm 10V, R_L \geq 2\text{ k}\Omega$ | 15 | 160 | | V/mV |
| V _O | Output Voltage Swing | $R_L = 10\text{ k}\Omega$ | ± 10 | ± 13 | | V |
| V _I | Input Voltage Range | | ± 10 | | | V |
| CMRR | Common-Mode Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | | 90 | | dB |
| PSRR | Supply Voltage Rejection Ratio | $R_S \leq 10\text{ k}\Omega$ | | 96 | | dB |
| I _{SC} | Output Short-Circuit Current | | | 25 | | mA |
| S _r | Slew Rate (Unity Gain) | | | 0.5 | | V/μs |
| BW | Small Signal Bandwidth | | | 1.0 | | MHz |

typical performance characteristics



typical applications (All applications require power supply by-pass capacitors.)



$C_{EXT} \geq 1\mu F; \text{ frequency } \geq 1\text{ kHz}$

FIGURE 1. LH0091 Basic Connection (No Trim)

typical applications (con'd)

$R_T = 240k$
 $C_{EXT} \geq 1\mu F, f \geq 1 \text{ kHz}$

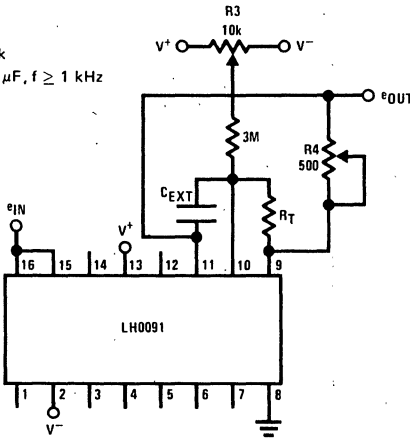


FIGURE 2. LH0091 "Easy Trim" (For ac Inputs Only)

Note. The easy trim procedure is used for ac coupled input signals. It involves two trims and can achieve accuracies of 2 mV offset $\pm 0.1\%$ reading.

Procedure:

1. Apply 100 mV rms (sine wave) to input, adjust R3 until the output reads 100 mV_{DC}.
2. Apply 5 V_{rms} (sine wave) to input, adjust R4 until the output reads 5 V_{DC}.
3. Repeat steps 1 and 2 until the desired initial accuracy is achieved.

R1 = dc symmetry balance
 R2 = Input offset
 R3 = Output offset
 R4 = Gain adjust

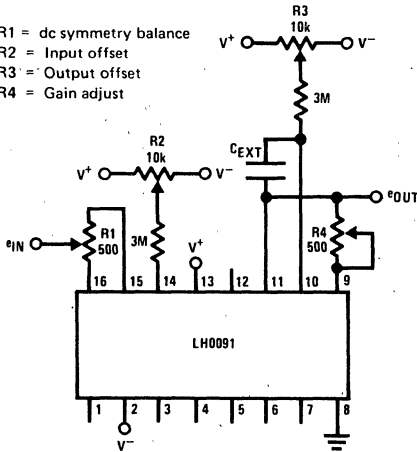


FIGURE 3. LH0091 Standard dc Trim Procedure

Note. This procedure will give accuracies of 0.5 mV offset $\pm 0.05\%$ reading for inputs from 0.05V peak to 10V peak.

Procedure:

1. Apply 50 mV_{DC} to the input. Read and record the output.
2. Apply -50 mV_{DC} to the input. Use R2 to adjust for an output of the same magnitude as in step 1.
3. Apply 50 mV to the input. Use R3 to adjust the output for 50 mV.
4. Apply -50 mV to input. Use R2 to adjust the output for 50 mV.
5. Apply +10V alternately to the input. Adjust R1 until the output readings for both polarities are equal (not necessary that they be exactly 10V).
6. Apply 10V to the input. Use R4 to adjust for 10V at the output.
7. Repeat this procedure to obtain the desired accuracy.

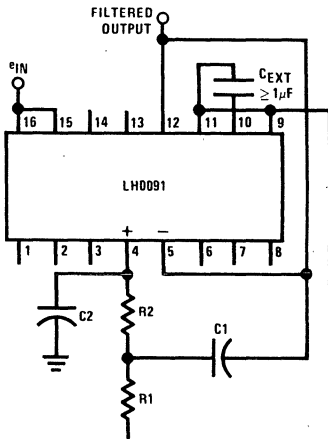
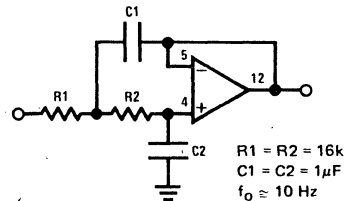


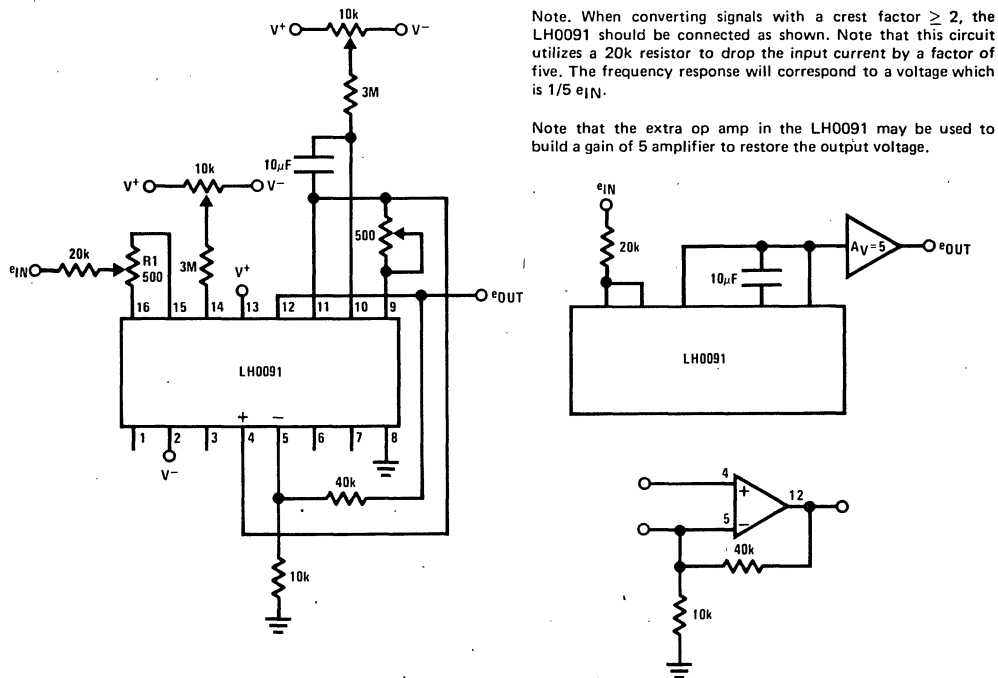
FIGURE 4. Output Filter Connection Using the Internal Op Amp

Note. The additional op amp in the LH0091 may be used as a low pass filter as shown in Figure 4.



$R_1 = R_2 = 16k$
 $C_1 = C_2 = 1\mu F$
 $f_o \approx 10 \text{ Hz}$

typical applications (con'd)



Note. When converting signals with a crest factor ≥ 2 , the LH0091 should be connected as shown. Note that this circuit utilizes a 20k resistor to drop the input current by a factor of five. The frequency response will correspond to a voltage which is $1/5 e_{IN}$.

Note that the extra op amp in the LH0091 may be used to build a gain of 5 amplifier to restore the output voltage.

Note. Response time of the dc output voltage is dominated by the RC time constant consisting of the total resistance between pins 9 and 10 and the external capacitor, C_{EX} .

FIGURE 5. High Crest Factor Circuit

definition of terms

True rms to dc Converter: A device which converts any signal (ac, dc, ac + dc) to the dc equivalent of the rms value.

Error: is the amount by which the actual output differs from the theoretical value. Error is defined as a sum of a fixed term and a percent of reading term. The fixed term remains constant, regardless of input while the percent of reading term varies with the input.

Total Unadjusted Error: The total error of the device without any external adjustments.

Bandwidth: The frequency at which the output dc voltage drops to 0.707 of the dc value at low frequency.

Frequency for Specified Error: The error at low frequency is governed by the size of the external averaging capacitor. At high frequencies, error is dependent on the frequency response of the internal circuitry. The frequency for specified error is the maximum input frequency for which the output will be within the specified error band (i.e., frequency for 1% error means the input frequency must be less than 200 kHz to maintain an output with an error of less than 1% of the initial reading).

Crest Factor: is the peak value of a waveform divided by the rms value of the same waveform. For high crest factor signals, the performance of the LH0091 can be improved by using the high crest factor connection.

LH0094 Multifunction Converter

General Description

The LH0094 multifunction converter generates an output voltage per the transfer function:

$$E_o = V_y \left(\frac{V_z}{V_x} \right)^m, 0.1 \leq m \leq 10, m \text{ continuously adjustable}$$

m is set by 2 resistors.

Features

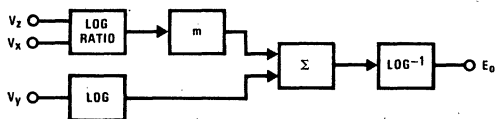
- Low cost
- Versatile
- High accuracy—0.05%
- Wide supply range—±5V to ±22V

- Minimum component count
- Internal matched resistor pair for setting $m = 2$ and $m = 0.5$

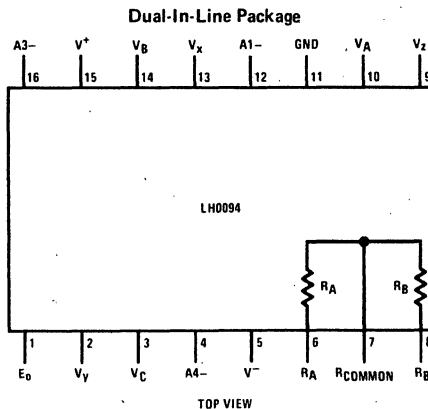
Applications

- Precision divider, multiplier
- Square root
- Square
- Trigonometric function generator
- Companding
- Linearization
- Control systems
- Log amp

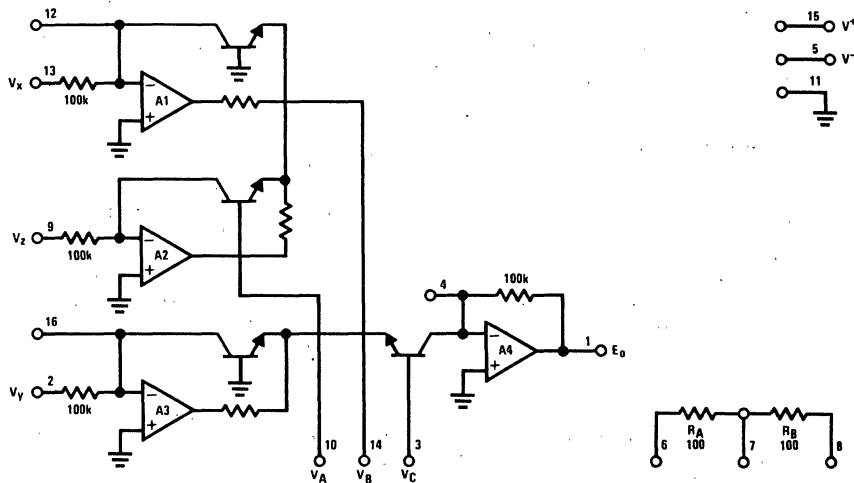
Block and Connection Diagrams



Order Number
LH0094D
LH0094CD
See Package D16D



Simplified Schematic



Absolute Maximum Ratings

| | |
|-------------------------------|-----------------|
| Supply Voltage | ±22V |
| Input Voltage | ±22V |
| Output Short-Circuit Duration | Continuous |
| Operating Temperature Range | |
| LH0094CD | -25°C to +85°C |
| LH0094D | -55°C to +125°C |

| | |
|--|-----------------|
| Storage Temperature Range | |
| LH0094D | -65°C to +150°C |
| LH0094CD | -55°C to +125°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

$V_S = \pm 15V$, $T_A = 25^\circ C$ unless otherwise specified. Transfer function: $E_O = V_Y \left(\frac{V_Z}{V_X} \right)^m$; $0.1 \leq m \leq 10$; $0V \leq V_X, V_Y, V_Z \leq 10V$

| PARAMETER | CONDITIONS | LH0094 | | | LH0094C | | | UNITS |
|-------------------------------|--|----------|-----------|------|----------|-----------|-----|------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| ACCURACY | | | | | | | | |
| Multiply | $E_O = \frac{V_Z V_Y}{10}$ ($0.03 \leq V_Y \leq 10V$; $0.01 \leq V_Z \leq 10V$) | | | | | | | |
| Untrimmed | (Figure 2) | | 0.25 | 0.45 | | 0.45 | 0.9 | % F.S. (10V) |
| External Trim | (Figure 3) vs Temperature | | 0.10 | | | 0.1 | | % F.S. |
| | | | | | | 0.2 | | mV/°C |
| Divide | $E_O = 10 V_Z / V_X$ | | | | | | | |
| Untrimmed | (Figure 4), ($0.5 \leq V_X \leq 10$; $0.01 \leq V_Z \leq 10$) | | 0.25 | 0.45 | | 0.45 | 0.9 | % F.S. |
| External Trim | (Figure 5), ($0.1 \leq V_X \leq 10$; $0.01 \leq V_Z \leq 10$) vs Temperature | | 0.10 | | | 0.1 | | % F.S. |
| | | | | | | 0.2 | | mV/°C |
| Sq. Root | $E_O = 10 \sqrt{V_Z / 10}$ | | | | | | | |
| Untrimmed | (Figure 8), ($0.03 \leq V_Z \leq 10$) | | 0.25 | 0.45 | | 0.45 | 0.9 | % F.S. |
| External Trim | (Figure 9), ($0.01 \leq V_Z \leq 10$) | | 0.15 | | | 0.15 | | % F.S. |
| Square | $E_O = 10 (V_Z / 10)^2$ ($0.1 \leq V_Z \leq 10$) | | | | | | | |
| Untrimmed | (Figure 6) | | 0.5 | 1.0 | | 1.0 | 2.0 | % F.S. |
| External Trim | (Figure 7) | | 0.15 | | | 0.15 | | % F.S. |
| Low Level | $E_O = \sqrt{10 V_Z}$; $5 \text{ mV} \leq V_Z \leq 10V$ | | 0.05 | | | 0.05 | | % F.S. |
| Sq. Root | (Figure 10) | | | | | | | |
| Exponential | $m = 0.2$ $E_O = 10 (V_Z / 10)^2$ | | 0.05 | | | 0.08 | | % F.S. |
| Circuits | (Figure 11), ($0.1 \leq V_Z \leq 10$) | | | | | | | |
| | $m = 5$ $E_O = 10 (V_Z / 10)^5$ | | 0.05 | | | 0.08 | | % F.S. |
| | (Figure 11), ($1 \leq V_Z \leq 10$) | | | | | | | |
| OUTPUT OFFSET | | | | | | | | |
| | $V_X = 10.0V, V_Y = V_Z = 0.0$ | | 2 | 5 | | 5 | 10 | mV |
| AC CHARACTERISTICS | | | | | | | | |
| 3 dB BANDWIDTH | $m = 1.0$ $V_X = V_Z = 10.0V$ $V_Y = 0.1 \text{ Vrms}$ | | 10 | | | 10 | | kHz |
| NOISE | 10 Hz to 1 kHz $m = 1, V_Y = V_Z = 0.0V$ $V_X = 10V$ $V_X = 0.1V$ | | 100 | | | 100 | | μVrms |
| | | | 300 | | | 300 | | μVrms |
| EXPONENTS | | | | | | | | |
| m | | 0.2 to 5 | 0.1 to 10 | | 0.2 to 5 | 0.1 to 10 | | |
| INPUT CHARACTERISTICS | | | | | | | | |
| Input Voltage | (For Rated Performance) | 0 | | 10 | 0 | | 10 | V |
| Input Impedance | (All Inputs) | 98 | 100 | | 98 | 100 | | k Ω |
| OUTPUT CHARACTERISTICS | | | | | | | | |
| Output Swing | ($R_L \geq 10k$) | 10 | 12 | | 10 | 12 | | V |
| Output Impedance | | | 1 | | | 1 | | Ω |
| Supply Current | ($V_S = \pm 15V$), Note 1 | | 3 | 5 | | 3 | 5 | mA |

Applications Information

GENERAL INFORMATION

Power supply bypass capacitors (0.1 μF) are recommended for all applications.

The LH0094 series is designed for positive input signals only. However, negative input up to the supply voltage will not damage the device.

A clamp diode (Figure 1) is recommended for those applications in which the inputs may be subjected to open circuit or negative input signals.

For basic applications (multiply, divide, square, square root) it is possible to use the device without any external adjustments or components. Two matched resistors are provided internally to set m for square or square root.

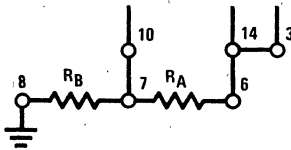
When using external resistors to set m , such resistors should be as close to the device as possible.

SELECTION OF RESISTORS TO SET m

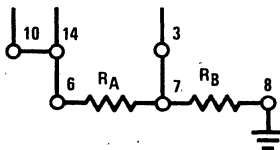
Internal Matched Resistors

R_A and R_B are matched internal resistors. They are $100\Omega \pm 10\%$, but matched to 0.1%.

(a) $m = 2^*$



(b) $m = 0.5^*$

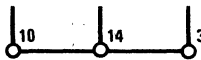


*No external resistors required, strap as indicated

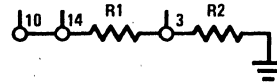
External Resistors

The exponent is set by 2 external resistors or it may be continuously varied by a single trim pot. ($R_1 + R_2 \leq 500\Omega$).

(a) $m = 1$

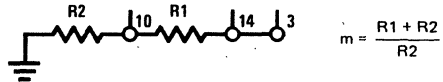


(b) $m < 1$



$$m = \frac{R_2}{R_1 + R_2} \quad R_1 + R_2 \approx 200\Omega$$

(c) $m > 1$



$$m = \frac{R_1 + R_2}{R_2}$$

ACCURACY (ERROR)

The accuracy of the LH0094 is specified for both externally adjusted and unadjusted cases.

Although it is customary to specify the errors in percent of full-scale (10V), it is seen from the typical performance curves that the actual errors are in percent of reading. Thus, the specified errors are overly conservative for small input voltages. An example of this is the LH0094 used in the multiplication mode. The specified typical error is 0.25% of full-scale (25 mV). As seen from the curve, the unadjusted error is ≈ 25 mV at 10V input, but the error is less than 10 mV for inputs up to 1V. Note also that if either the multiplicand or the multiplier is at less than 10V, (5V for example) the unadjusted error is less. Thus, the errors specified are at full-scale—the worst case.

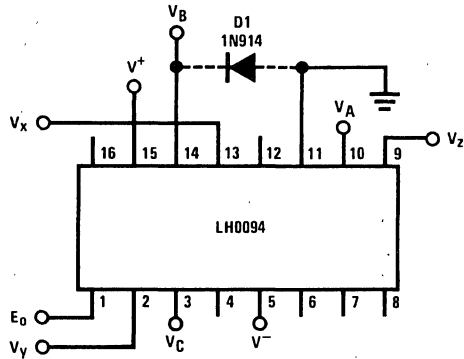
The LH0094 is designed such that the user is able to externally adjust the gain and offset of the device—thus trim out all of the errors of conversion. In most applications, the gain adjustment is the only external trim needed for super accuracy—except in division mode, where a denominator offset adjust is needed for small denominator voltages.

EXPONENTS

The LH0094 is capable of performing roots to 0.1 and powers up to 10. However, care should be taken when applying these exponents—otherwise, results may be misinterpreted. For example, consider the 1/10th power of a number: i.e., 0.001 raised to 0.1 power is 0.5011; 0.1 raised to the 0.1 power is 0.7943; and 10 raised to the 0.1 power is 1.2589. Thus, it is seen that while the input has changed 4 decades, the output has only changed a little more than a factor of 2. It is also seen that with as little as 1 mV of offset, the output will also be greater than zero with zero input.

Applications Information (Continued)

1. CLAMP DIODE CONNECTION



$$E_o = V_y \left(\frac{V_z}{V_x} \right)^m$$

$$0.1 \leq m \leq 10$$

Note. This clamp diode connection is recommended for those applications in which the inputs may be subject to open circuit or negative signals.

FIGURE 1. Clamp Diode Connection

2. MULTIPLY

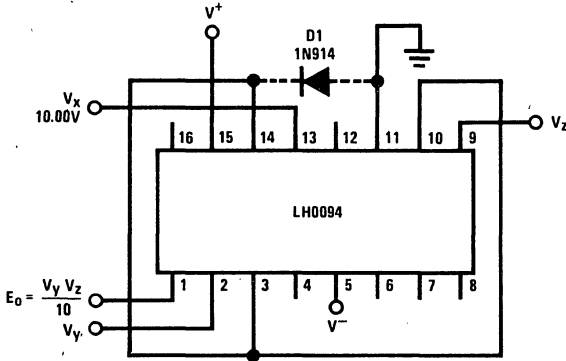


FIGURE 2a. LH0094 Used to Multiply (No External Adjustment)

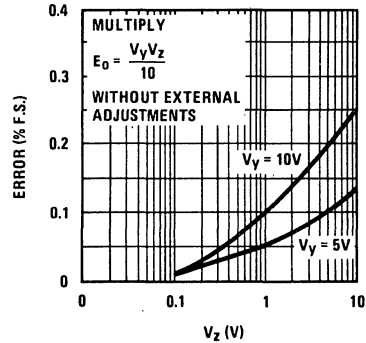
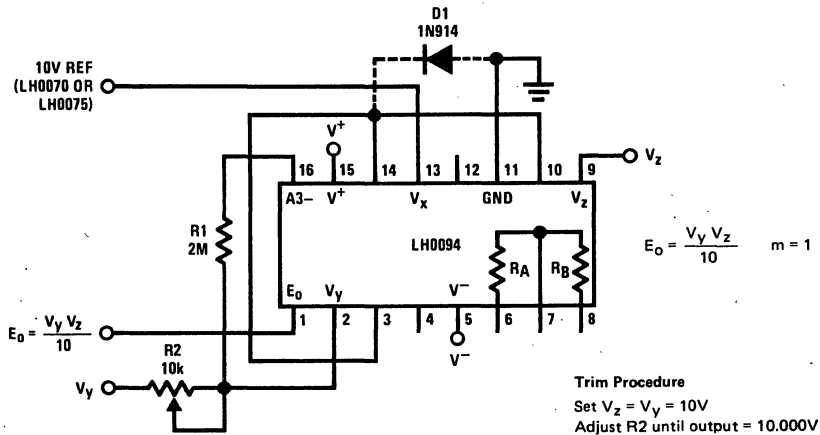


FIGURE 2b. Typical Performance of LH0094 in Multiply Mode Without External Adjustment



Trim Procedure
 Set $V_z = V_y = 10V$
 Adjust R2 until output = 10.000V

FIGURE 3. Precision Multiplier (0.02% Typ) with 1 External Adjustment

Applications Information (Continued)

3. DIVIDE

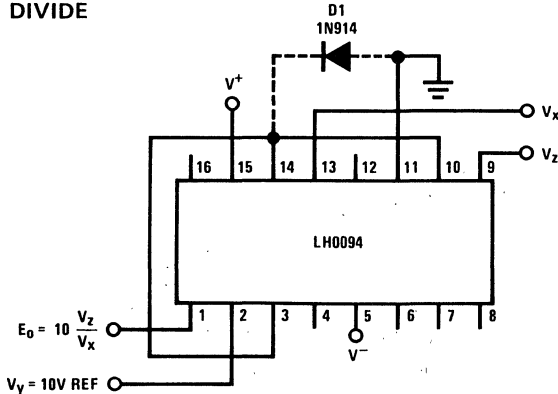


FIGURE 4a. LH0094 Used to Divide (No External Adjustment)

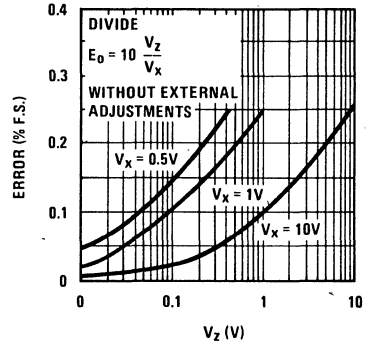


FIGURE 4b. Typical Performance, Divide Mode, Without External Adjustments

Trim Procedures

Apply 10V to Vy, 0.1V to Vx and Vz.
Adjust R3 until Eo = 10.000V.

Apply 10.000V to all inputs.
Adjust R2 until Eo = 10.000V

Repeat procedure.

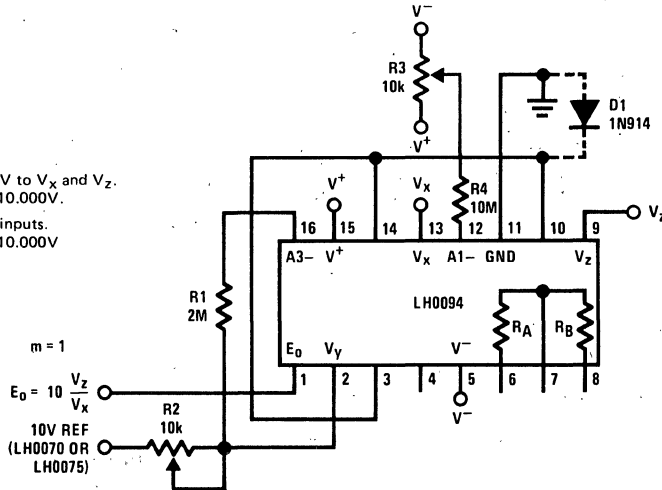


FIGURE 5. Precision Divider (0.05% Typ)

4. SQUARE

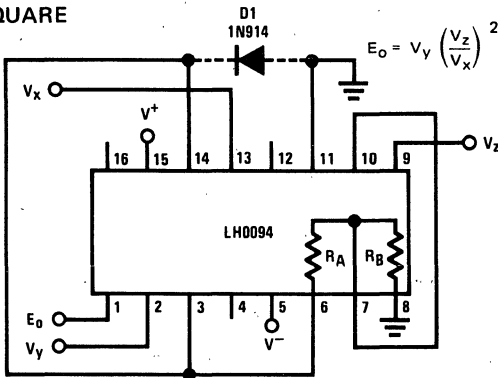


FIGURE 6a. Basic Connection of LH0094 (m = 2) without External Adjustment Using Internal Resistors to Set m

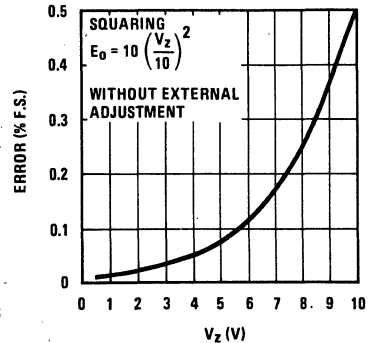


FIGURE 6b. Squaring Mode without External Adjustment

Applications Information (Continued)

4. SQUARE (Continued)

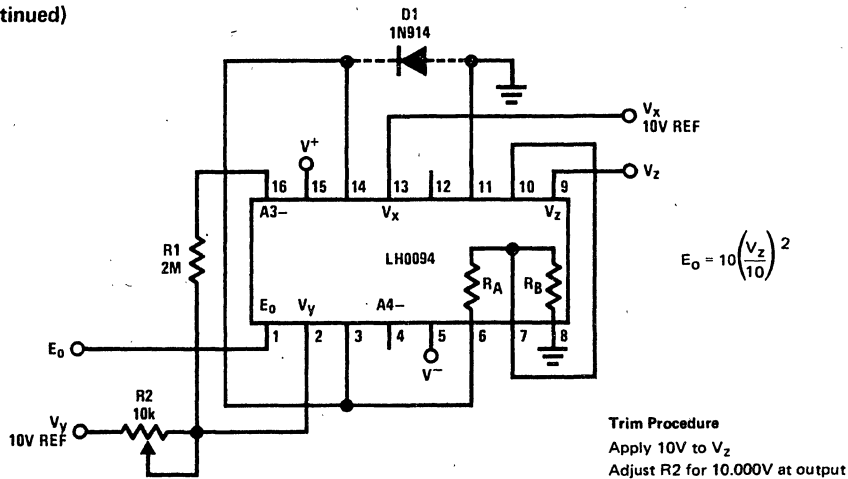


FIGURE 7. Precision Squaring Circuit (0.15% Typ)

5. SQUARE ROOT

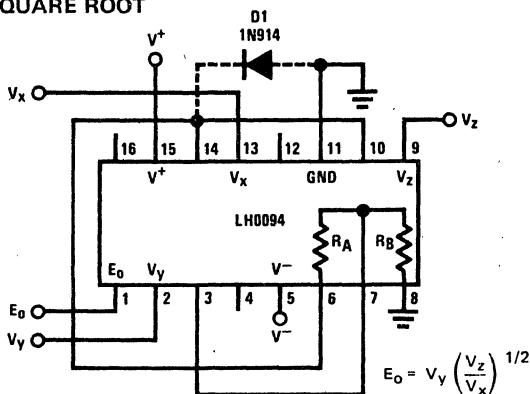


FIGURE 8a. Basic Connection of LH0094 ($m = 0.5$) without External Adjustment Using Internal Resistors to Set m

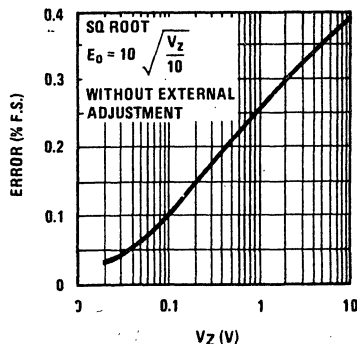


FIGURE 8b. Typical Performance Curve Square Root, No External Adjustment

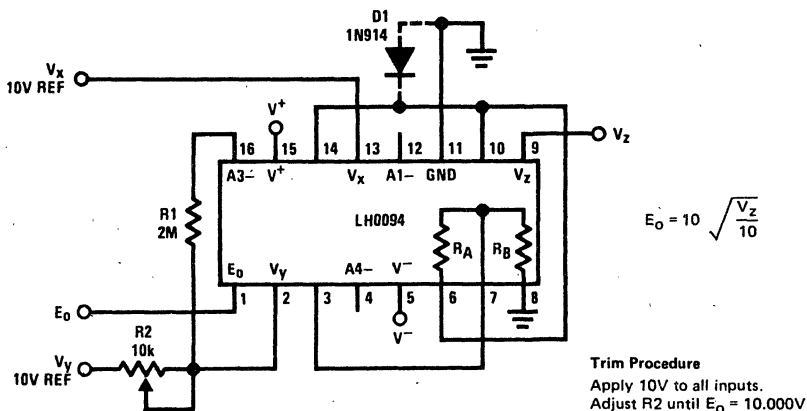


FIGURE 9. Precision Square Rooter (0.15% Typ)

Applications Information (Continued)

6. LOW LEVEL SQUARE ROOT

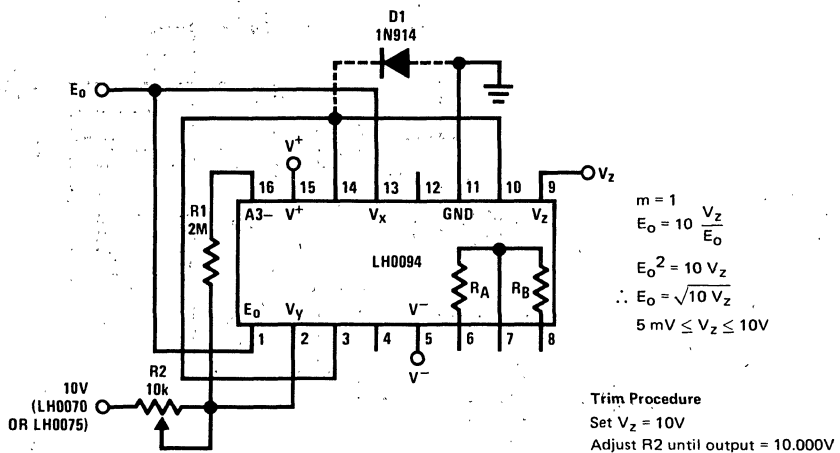


FIGURE 10. 3-Decade Precision Square Root Circuit Using the LH0094 with $m = 1$

Typical Applications

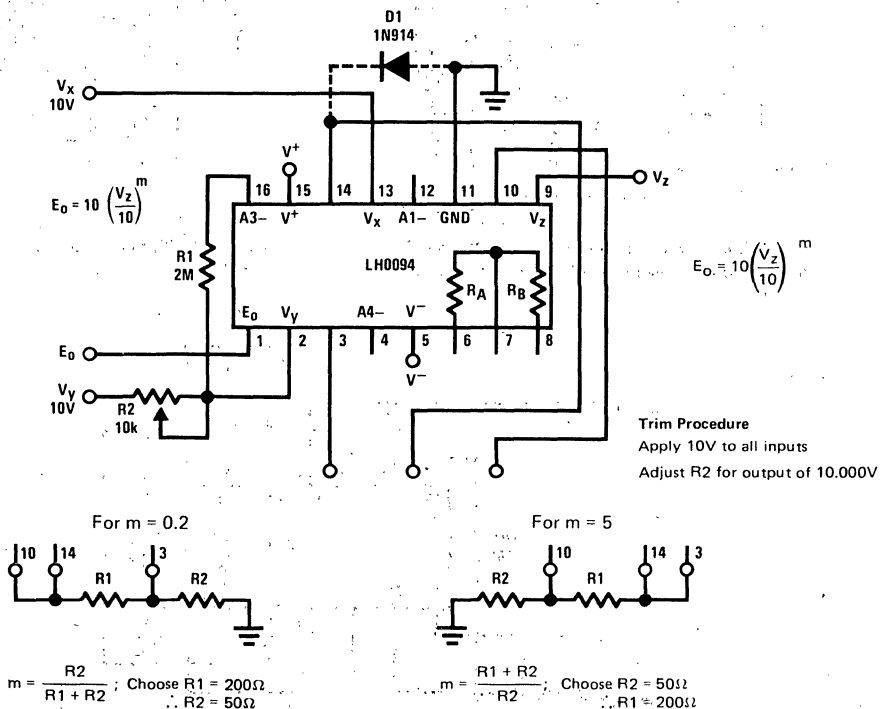
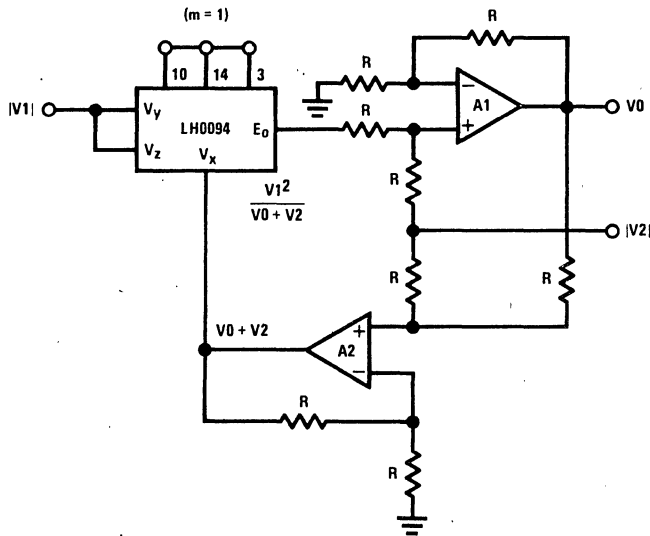


FIGURE 11. Precision Exponentiator ($m = 0.2$ to 5)

Typical Applications (Continued)



Note. The LH0094 may be used to generate a voltage equivalent to:

$$V_0 = \sqrt{V_1^2 + V_2^2}$$

$$V_0 = V_2 + \frac{V_1^2}{V_0 + V_2}$$

$$V_0^2 + V_0 V_2 = V_2 V_0 + V_2^2 + V_1^2$$

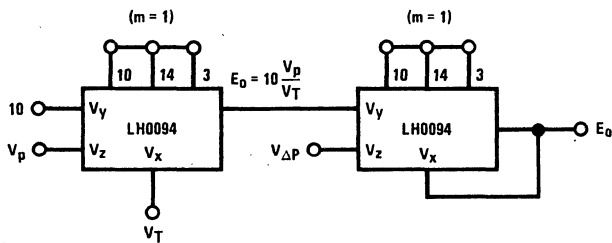
$$V_0^2 = V_1^2 + V_2^2$$

$$\therefore V_0 = \sqrt{V_1^2 + V_2^2} \quad V_1, V_2 \ 0 \rightarrow 10V$$

$R \approx 10k$

National Semiconductor resistor array RA08-10k is recommended

FIGURE 12. Vector Magnitude Function



Note. The LH0094 may be used in direct measurement of gas flow.

$$\text{Flow} \approx k \sqrt{\frac{P \Delta P}{T}}$$

$$E_o = 10 \frac{V_p}{V_t} \times \frac{V_{\Delta P}}{E_o}$$

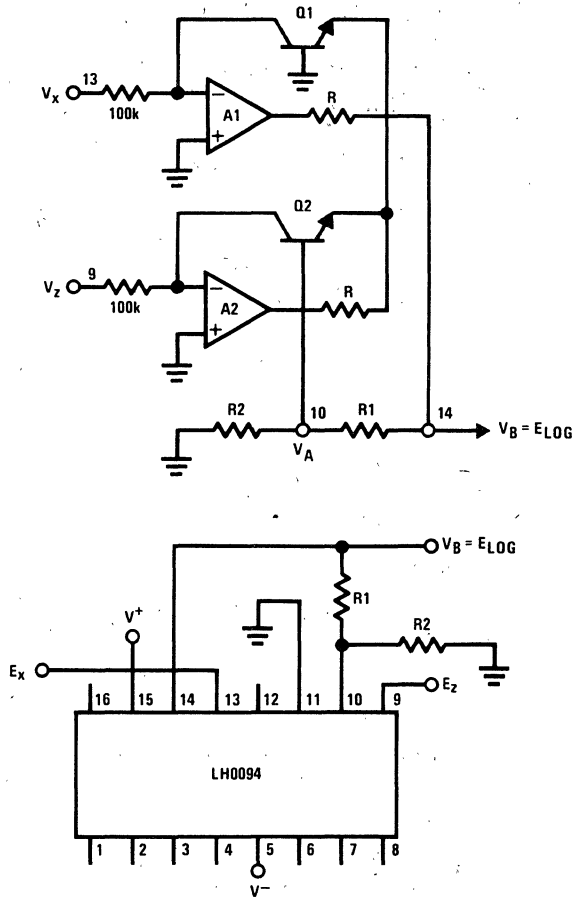
$$E_o^2 = 10 \frac{V_p V_{\Delta P}}{V_t}$$

$$E_o = \sqrt{10 \frac{V_p V_{\Delta P}}{V_t}}$$

P = Absolute pressure
 T = Absolute temperature
 ΔP = Pressure drop

FIGURE 13. Mass Gas Flow Circuit

Typical Applications (Continued)



Note. The LH0094 may also be used to generate the Log of a ratio of 2 voltages. The output is taken from pin 14 of the LH0094 for the Log application.

$$E_{LOG} = K1 \frac{KT}{q} \ln \frac{V_z}{V_x}$$

$$\text{where } K1 = \frac{R1 + R2}{R2}$$

$$\text{If } K1 = \frac{1}{KT/q \ln 10}$$

$$\text{then } E_{LOG} = \text{Log}_{10} \frac{V_z}{V_x}$$

$$R1 = 15.9 R2$$

$$R2 \approx 400\Omega$$

\$R2\$ must be a thermistor with a tempco of \$\approx 0.33\%/^{\circ}\text{C}\$ to be compensated over temperature.

FIGURE 14. Log Amp Application



Section 9
**Industrial/Automotive/
Functional Blocks/
Telecommunications**





Industrial/Automotive/Functional Blocks/ Telecommunications

Section Contents

| | |
|--|-------|
| Definition of Terms..... | 9-iv |
| Audio | |
| LM567/LM567C Tone Decoder..... | 9-46 |
| LM2877 Dual 4-Watt Power Audio Amplifier..... | 9-78 |
| LM3080/LM3080A Operational Transconductance Amplifier..... | 9-92 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| LM3915 Dot/Bar Display Driver..... | 9-120 |
| LM13600/LM13600A/LM11600A Dual Operational Transconductance Amplifiers With Linearizing Diodes and Buffers..... | 9-136 |
| Radio | |
| LM565/LM565C Phase Locked Loop..... | 9-38 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| LM3915 Dot/Bar Display Driver..... | 9-120 |
| Blocks | |
| LM131A/LM131, LM231A/LM231, LM331A/LM331 Precision Voltage-to-Frequency Converters..... | 8-162 |
| LM134/LM234/LM334 3-Terminal Adjustable Current Sources..... | 9-13 |
| LM135/LM235/LM335, LM135A/LM235A/LM335A Precision Temperature Sensors..... | 9-21 |
| LM555/LM555C Timer..... | 9-29 |
| LM556/LM556C Dual Timer..... | 9-35 |
| LM565/LM565C Phase Locked Loop..... | 9-38 |
| LM566/LM566C Voltage Controlled Oscillator..... | 9-43 |
| LM567/LM567C Tone Decoder..... | 9-46 |
| LM1014/LM1014A Motor Speed Regulator..... | 9-50 |
| LM1391 Phase-Locked Loop Block..... | 10-81 |
| LM1801 Smoke Detector..... | 9-54 |
| LM1812 Ultrasonic Transceiver..... | 9-58 |
| LM3080/LM3080A Operational Transconductance Amplifier..... | 9-92 |
| LM3909 LED Flasher/Oscillator..... | 9-96 |
| LM3911 Temperature Controller..... | 9-100 |
| LM13600/LM13600A/LM11600A Dual Operational Transconductance Amplifiers With Linearizing Diodes and Buffers..... | 9-136 |
| Appliance | |
| LM383/LM383A 8 Watt Audio Power Amplifier..... | 10-24 |
| LM1815 Adaptive Sense Amplifier..... | 9-64 |
| LM1830 Fluid Detector..... | 9-67 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| Automotive | |
| LM383/LM383A 8 Watt Audio Power Amplifier..... | 10-24 |
| LM1830 Fluid Detector..... | 9-67 |
| LM2900 Quad Amplifier..... | 3-215 |
| LM2901 Low Power Low Offset Voltage Quad Comparator..... | 5-23 |
| LM2902 Low Power Quad Operational Amplifier..... | 3-113 |
| LM2903 Low Power Low Offset Voltage Dual Comparator..... | 5-37 |
| LM2904 Low Power Dual Operational Amplifier..... | 3-157 |
| LM2907, LM2917 Frequency to Voltage Converter..... | 9-79 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| Telecommunications | |
| TP3000 CODEC System (TP3001 μ -Law, TP3002 A-Law)..... | 8-180 |

Section Contents (Continued)

Industrial Control Circuits

| | |
|--|-------|
| LM122/LM222/LM322, LM2905/LM3905 Precision Timers..... | 9-1 |
| LM131A/LM131, LM231A/LM231, LM331A/LM331 Precision Voltage-to-Frequency Converters..... | 8-162 |
| LM134/LM234/LM334 3-Terminal Adjustable Current Sources..... | 9-13 |
| LM3911 Temperature Controller..... | 9-100 |



Definition of Terms

Capacitor Saturation Voltage: The offset voltage remaining on the timing capacitor after capacitor discharge current has dropped to zero.

Collector Saturation Voltage: The collector to emitter voltage on the output transistor when it is in the "ON" state with specified sink current flowing into the collector terminal.

Common-Mode Rejection Ratio: The ratio of the change in input offset voltage to the peak-to-peak input voltage range.

Comparator Input Current: The average current flowing from the R/C pin during the timing cycle.

C_T : Timing capacitor connected between the R/C terminal and the ground terminal.

Emitter Saturation Voltage: The voltage across the output transistor when the collector is tied to V^+ , the transistor is in the "ON" state, and the specified output current is flowing from the emitter terminal.

Input Bias Current: The average of the two input currents.

Input Offset Current: The difference in the current into the two input terminals when the supply (output) current is 4.0 mA.

Input Offset Voltage: The voltage which must be applied between the input terminals through equal resistances to obtain 4.0 mA of supply (output) current.

Input Resistance: The ratio of the change in input voltage to the change in input current at either input with the other input connected to 1.0 Vdc.

Input Voltage Range: The range of voltages on the input terminals for which the device operates within specifications.

Linearity: The deviation in output voltage from a straight line output over a specified temperature excursion.

Long Term Stability: The change of a particular parameter when operated at maximum temperature for 1000 hours.

Maximum Power Dissipation: The maximum total device dissipation for which the timer will operate within specifications.

Open Loop Output Resistance: The ratio of a specified supply (output) voltage change to the resulting change in supply (output) current at the specified current level.

Open Loop Transconductance: The ratio of the supply (output) current SPAN to the input voltage required to produce that SPAN.

Open Loop Supply Current: The supply current required with the signal amplifier A2 biased off (inverting input positive, non-inverting input negative) and no load on the V_{REF} terminal.

This represents a measure of the minimum low end signal current.

Output Leakage Current: The maximum current flowing into the collector of the output transistor when the transistor is in the "OFF" state.

Output Sink Current: The current available to flow into a load from a positive supply over a specified output voltage range.

Output Source Current: The current available to flow into a load from the output to V^- , over a specified output voltage range.

Output Voltage: The voltage referred to the V^+ terminal from the output terminal with the input and output connected. (This voltage is the temperature output of the LM3911 and so includes errors in the sensor section and op amp section.)

Power Supply Rejection Ratio: The ratio of the change in input offset voltage to the change in supply (output) voltage producing it.

Reference Voltage Line Regulation: The ratio of the change in V_{REF} to the peak-to-peak change in supply (output) voltage producing it.

Reference Voltage Load Regulation: The change in V_{REF} for a stipulated change in I_{REF} .

Reset Resistor: The equivalent resistor which may be used to calculate the discharge time of the timing capacitor, $t_{DISCHARGE} = (5) (C_T) (R_{RESET})$.

Reverse Breakdown Voltage: The voltage appearing between the V^+ and V^- terminals at a specified current.

R_T : Timing resistor connected between V_{REF} and the R/C terminal.

Temperature Stability: The percentage in output voltage for a thermal variation from room temperature to either temperature extreme.

Timing Ratio: The ratio of the firing voltage at the R/C pin to the reference voltage.

Trigger Current: The current flowing into or out of the trigger terminal at the specified trigger voltage.

Trigger Voltage: The voltage required at the trigger terminal to initiate a timing cycle, referenced to the ground pin.

LM122/LM222/LM322, LM2905/LM3905 Precision Timers

General Description

The LM122 series are precision timers that offer great versatility with high accuracy. They operate with unregulated supplies from 4.5V to 40V while maintaining constant timing periods from microseconds to hours. Internal logic and regulator circuits complement the basic timing function enabling the LM122 series to operate in many different applications with a minimum of external components.

The output of the timer is a floating transistor with built in current limiting. It can drive either ground referred or supply referred loads up to 40V and 50 mA. The floating nature of this output makes it ideal for interfacing, lamp or relay driving, and signal conditioning where an open collector or emitter is required. A "logic reverse" circuit can be programmed by the user to make the output transistor either "on" or "off" during the timing period.

The **trigger** input to the LM122 series has a threshold of 1.6V independent of supply voltage, but it is fully protected against inputs as high as $\pm 40V$ — even when using a 5V supply. The circuitry reacts only to the rising edge of the trigger signal, and is immune to any trigger voltage during the timing periods.

An internal 3.15V regulator is included in the timer to reject supply voltage changes and to provide the user with a convenient reference for applications other than a basic timer. External loads up to 5 mA can be driven by the regulator. An internal 2V divider between the reference and ground sets the timing period to 1 RC. The timing period can be voltage controlled by driving this divider

with an external source through the V_{ADJ} pin. Timing ratios of 50:1 can be easily achieved.

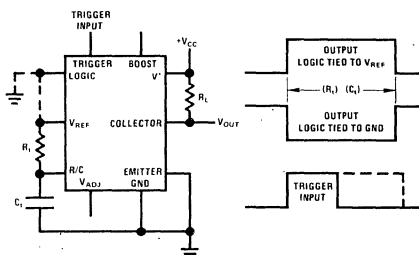
The comparator used in the LM122 utilizes high gain PNP input transistors to achieve 300 pA typical input bias current over a common mode range of 0V to 3V. A **boost** terminal allows the user to increase comparator operating current for timing periods less than 1 ms. This lets the timer operate over a 3 μ s to multi-hour timing range with excellent repeatability.

The LM122 operates over a temperature range of $-55^{\circ}C$ to $+125^{\circ}C$. An electrically identical LM222 is specified from $-25^{\circ}C$ to $+85^{\circ}C$, and the LM322 is specified from $0^{\circ}C$ to $+70^{\circ}C$. The LM2905/LM3905 are identical to the LM122 series except that the **boost** and V_{ADJ} pin options are not available, limiting minimum timing period to 1 ms.

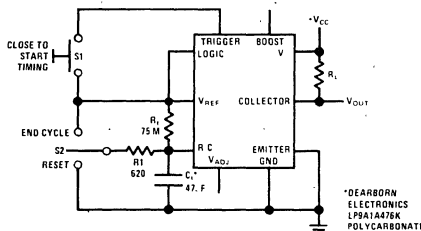
Features

- Immune to changes in trigger voltage during timing interval
- Timing periods from microseconds to hours
- Internal logic reversal
- Immune to power supply ripple during the timing interval
- Operates from 4.5V to 40V supplies
- Input protected to $\pm 40V$
- Floating transistor output with internal current limiting
- Internal regulated reference
- Timing period can be voltage controlled
- TTL compatible input and output

Typical Applications



Basic Timer-Collector Output and Timing Chart



One Hour Timer with Reset and Manual Cycle End

LM122/LM222/LM322, LM2905/LM3905

9

Absolute Maximum Ratings

| | | | |
|--|--------|-----------------------------|---------------------------------|
| Power Dissipation | 500 mW | Operating Temperature Range | |
| V ⁺ Voltage | 40V | LM122 | -55°C ≤ T _A ≤ +125°C |
| Collector Output Voltage | 40V | LM222 | -25°C ≤ T _A ≤ +85°C |
| V _{REF} Current | 5 mA | LM322 | 0°C ≤ T _A ≤ +70°C |
| Trigger Voltage | ±40V | LM2905 | -40°C ≤ T _A ≤ +85°C |
| V _{ADJ} Voltage (Forced) | 5V | LM3905 | 0°C ≤ T _A ≤ +70°C |
| Logic Reverse Voltage | 5.5V | | |
| Output Short Circuit Duration (Note 1) | | | |
| Lead Temperature (Soldering, 10 sec) | 300°C | | |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | LM122/LM222 | | | LM322 | | | LM2905/LM3905 | | | UNITS |
|------------------------------|--|-------------|-------|-------|-------|-------|-------|---------------|-------|-------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Timing Ratio | T _A = 25°C, 4.5V ≤ V ⁺ ≤ 40V | 0.626 | 0.632 | 0.638 | 0.620 | 0.632 | 0.644 | 0.620 | 0.632 | 0.644 | |
| | Boost Tied to V ⁺ , (Note 3) | 0.620 | 0.632 | 0.644 | 0.620 | 0.632 | 0.644 | | | | |
| Comparator Input Current | T _A = 25°C, 4.5V ≤ V ⁺ ≤ 40V | | 0.3 | 1.0 | | 0.3 | 1.5 | | 0.5 | 1.5 | nA |
| | Boost Tied to V ⁺ | | 30 | 100 | | 30 | 100 | | | | nA |
| Trigger Voltage | T _A = 25°C, 4.5V ≤ V ⁺ ≤ 40V | 1.2 | 1.6 | 2 | 1.2 | 1.6 | 2 | 1.2 | 1.6 | 2 | V |
| Trigger Current | T _A = 25°C, V _{TRIG} = 2V | | 25 | | | 25 | | | 25 | | μA |
| Supply Current | T _A ≥ 25°C, 4.5V ≤ V ⁺ ≤ 40V | | 2.5 | 4 | | 2.5 | 4.5 | | 2.5 | 4.5 | mA |
| Timing Ratio | 4.5V ≤ V ⁺ ≤ 40V | 0.62 | | 0.644 | 0.61 | | 0.654 | 0.61 | | 0.654 | |
| | Boost Tied to V ⁺ | 0.62 | | 0.644 | 0.61 | | 0.654 | | | | |
| Comparator Input Current | 4.5V ≤ V ⁺ ≤ 40V | -5 | | 5 | -2 | | 2 | -2.5 | | 2.5 | nA |
| | Boost Tied to V ⁺ , (Note 4) | | | 100 | | | 150 | | | | nA |
| Trigger Voltage | 4.5V ≤ V ⁺ ≤ 40V | 0.8 | | 2.5 | 0.8 | | 2.5 | 0.8 | | 2.5 | V |
| Trigger Current | V _{TRIG} = 2.5V | | | 200 | | | 200 | | | 200 | μA |
| Output Leakage Current | V _{CE} = 40V | | | 1 | | | 5 | | | 5 | μA |
| Capacitor Saturation Voltage | R _t ≥ 1 MΩ | | 2.5 | | | 2.5 | | 2.5 | | | mV |
| | R _t = 10 kΩ | | 25 | | | 25 | | 25 | | | mV |
| Reset Resistance | | | 150 | | | 150 | | 150 | | | Ω |
| Reference Voltage | T _A = 25°C | 3 | 3.15 | 3.3 | 3 | 3.15 | 3.3 | 3 | 3.15 | 3.3 | V |
| Reference Regulation | 0 ≤ I _{OUT} ≤ 3 mA | | 20 | 50 | | 20 | 50 | | 20 | 50 | mV |
| | 4.5V ≤ V ⁺ ≤ 40V | | 6 | 25 | | 6 | 25 | | 6 | 25 | mV |
| Collector Saturation Voltage | I _L = 8 mA | | 0.25 | 0.4 | | 0.25 | 0.4 | | 0.25 | 0.4 | V |
| | I _L = 50 mA | | 0.7 | 1.4 | | 0.7 | 1.4 | | 0.7 | 1.4 | V |
| Emitter Saturation Voltage | T _A = 25°C, I _L = 3 mA | | 1.8 | 2.2 | | 1.8 | 2.2 | | 1.8 | 2.2 | V |
| | T _A = 25°C, I _L = 50 mA | | 2.1 | 3 | | 2.1 | 3 | | 2.1 | 3 | V |
| Average Temperature | | | 0.003 | | | 0.003 | | | 0.003 | | %/°C |
| Coefficient of Timing Ratio | | | | | | | | | | | |
| Minimum Trigger Width | V _{TRIG} = 3V | | 0.25 | | | 0.25 | | | 0.25 | | μs |

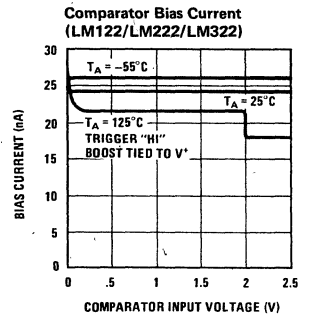
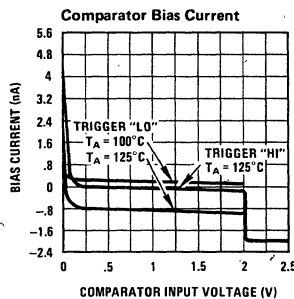
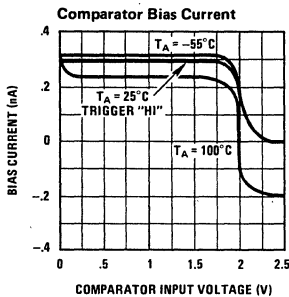
Note 1: Continuous output shorts are not allowed. Short circuit duration at ambient temperatures up to 40°C may be calculated from $t = 120/V_{CE}$ seconds, where V_{CE} is the collector to emitter voltage across the output transistor during the short.

Note 2: These specifications apply for $T_{AMIN} \leq T_A \leq T_{AMAX}$ unless otherwise noted.

Note 3: Output pulse width can be calculated from the following equation: $t = (R_t)(C_t)[1 - 2(0.632 - r) - V_C/V_{REF}]$ where r is timing ratio and V_C is capacitor saturation voltage. This reduces to $t = (R_t)(C_t)$ for all but the most critical applications.

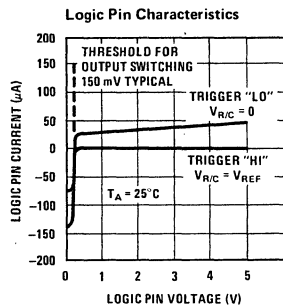
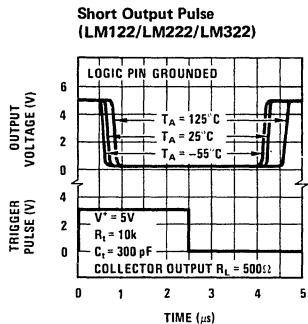
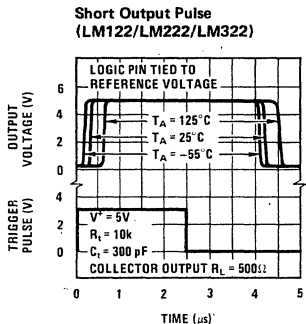
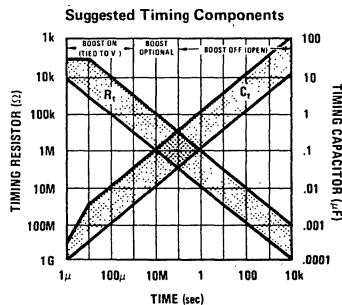
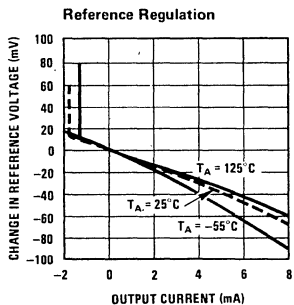
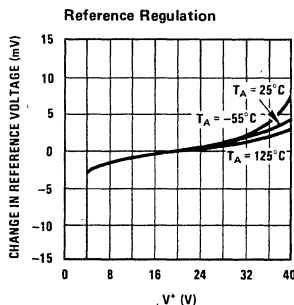
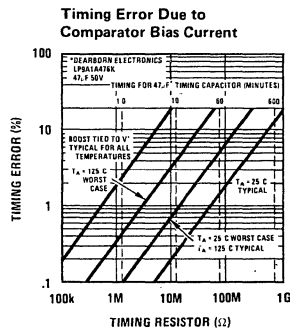
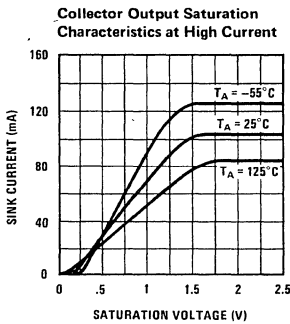
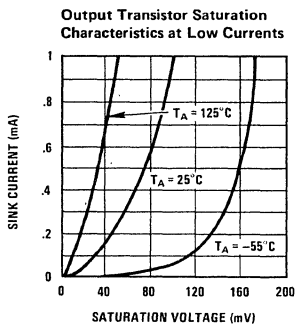
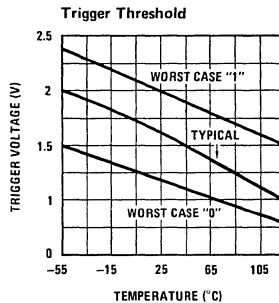
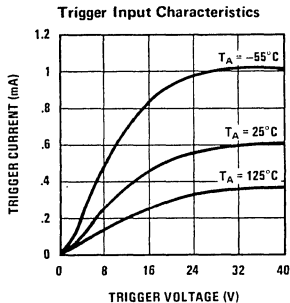
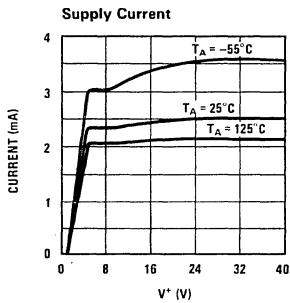
Note 4: Sign reversal may occur at high temperatures (> 100°C) where comparator input current is predominately leakage. See typical curves.

Typical Performance Characteristics

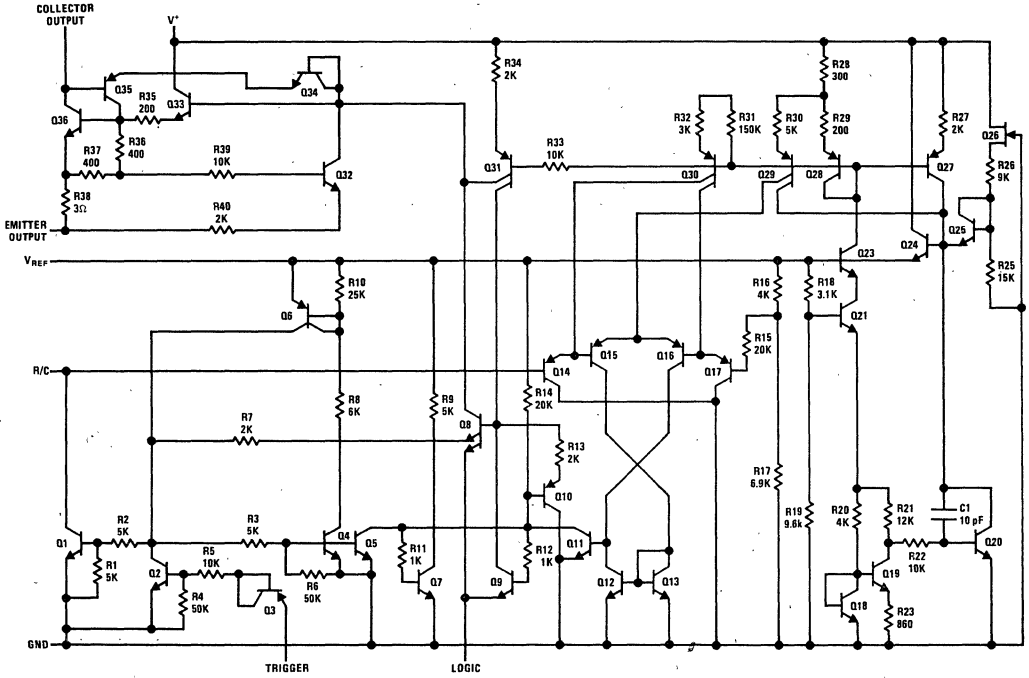


Typical Performance Characteristics (Continued)

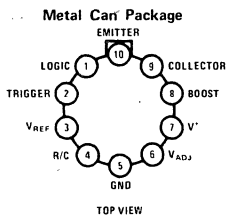
LM122/LM222/LM322, LM2905/LM3905



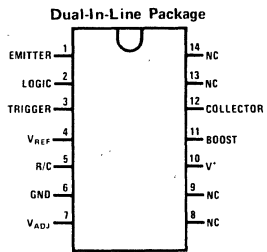
Schematic Diagram



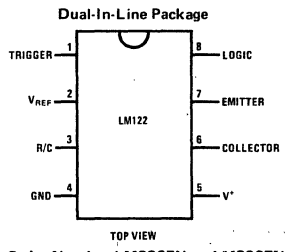
Connection Diagrams



Order Number LM122H,
LM222H or LM322H
See NS Package H10C

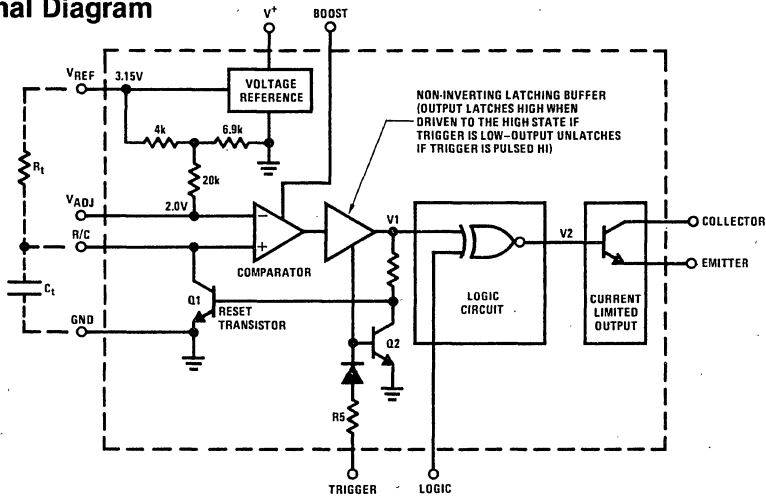


Order Number LM322N
See NS Package N14A

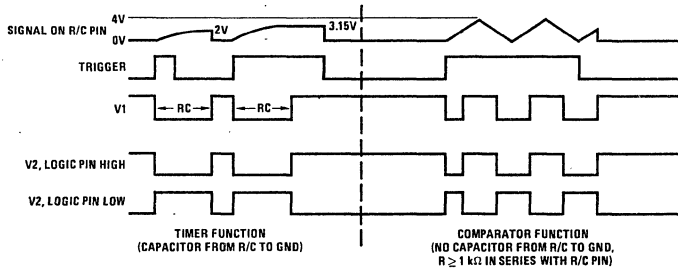


Order Number LM2905N or LM3905N
See NS Package N08B

Functional Diagram



Timing Diagram



Pin Function Description

One of the main features of the LM122 is its great versatility. Since this device is unique, a description of the functions and limitations of each pin is in order. This will make it much easier to follow the discussion of the various applications presented in this note.

V^+ is the positive supply terminal of the LM122. When using a single supply, this terminal may be driven by any voltage between 4.5V and 40V. The effect of supply variations on timing period is less than 0.005%/V, so supplies with high ripple content may be used without causing pulse width changes. Supply bypassing on V^+ is not generally needed but may be necessary when driving highly reactive loads. Quiescent current drawn from the V^+ terminal is typically 2.5 mA, independent of the supply voltage. Of course, additional current will be drawn if the reference is externally loaded.

The V_{REF} pin is the output of a 3.15V series regulator referenced to the ground pin. Up to 5.0 mA can be drawn from this pin for driving external networks. In most applications the timing resistor is tied to V_{REF} , but it need not be in situations where a more linear charging current is

required. The regulated voltage is very useful in applications where the LM122 is not used as a timer; such as switching regulators, variable reference comparators, and temperature controllers. Typical temperature drift of the reference is less than 0.01%/°C.

The **trigger** terminal is used to start a timing cycle (see functional diagram). Initially, Q1 is saturated, C_T is discharged and the latching buffer output (V1) is latched high. A trigger pulse unlatches the buffer, V1 goes low and turns Q1 off. The timing capacitor C_T connected from R/C to GND will begin to charge. When the voltage at the R/C terminal reaches the 2.0V threshold of the comparator, the comparator toggles, latching the buffer output (V1) in the high state. This turns on Q1, discharges the capacitor C_T and the cycle is ready to begin again.

If the **trigger** is held high as the timing period ends, the comparator will toggle and V1 will go high exactly as before. However, V1 will not be latched and the capacitor will not discharge until the trigger again goes low. When the trigger goes low, V1 remains high but is now latched.

Pin Function Description (Continued)

Trigger threshold is typically 1.6V at 25°C and has a temperature dependence of $-5.0 \text{ mV}/^\circ\text{C}$. Current drawn from the trigger source is typically $20 \mu\text{A}$ at threshold, rising to $600 \mu\text{A}$ at 30V, then leveling off due to FET action of the series resistor, R5. For negative input trigger voltages, the only current drawn is leakage in the nA region. The trigger can be driven from supplies as high as $\pm 40\text{V}$, even when device supply voltage is only 5V.

The R/C pin is tied to the non-inverting side of the comparator and to the collector of Q1. Timing ends when the voltage on this pin reaches 2.0V (1 RC time constant referenced to the 3.15V regulator). Q1 turns on only if the trigger voltage has dropped below threshold. In comparator or regulator applications of the timer, the trigger is held permanently high and the R/C pin acts just like the input to an ordinary comparator. The maximum voltages which can be applied to this pin are +5.5V and -0.7V . Current from the R/C pin is typically 300 pA when the voltage is negative with respect to the V_{ADJ} terminal. For higher voltages, the current drops to leakage levels: In the boosted mode, input current is typically 30 nA. Gain of the comparator is very high, 200,000 or more, depending on the state of the logic reverse pin and the connection of the output transistor.

The ground pin of the LM122 need not necessarily be tied to system ground. It can be connected to any positive or negative voltage as long as the supply is negative with respect to the V⁺ terminal. Level shifting may be necessary for the input trigger if the trigger voltage is referred to system ground. This can be done by capacitive coupling or by actual resistive or active level shifting. One point must be kept in mind; the emitter output must not be held above the ground terminal with a low source impedance. This could occur, for instance, if the emitter were grounded when the ground pin of the LM122 was tied to a negative supply.

The terminal labeled V_{ADJ} is tied to one side of the comparator and to a voltage divider between V_{REF} and ground. The divider voltage is set at 63.2% of V_{REF} with respect to ground—exactly one RC time constant. The impedance of the divider is increased to about 30k with a series resistor to present a minimum load on external signals tied to V_{ADJ}. This resistor is a pinched type with a typical variation in nominal value of -50% , $+100\%$, and a TC of $0.7\%/^\circ\text{C}$. For this reason, external signals (typically a pot between V_{REF} and ground) connected to V_{ADJ} should have a source resistance as low as possible. For small changes in V_{ADJ}, up to several k Ω is all right, but for large variations, 250 Ω or less should be maintained. This can be accomplished with a 1k pot, since the maximum impedance from the wiper is 250 Ω . If a voltage is forced on V_{ADJ} from a hard source, voltage should be limited to -0.5 , and $+5.0\text{V}$, or current limited to $\pm 1.0 \text{ mA}$. This

includes capacitively coupled signals because even small values of capacitors contain enough energy to degrade the input stage if the capacitor is driven with a large, fast slewing signal. The V_{ADJ} pin may be used to abort the timing cycle. Grounding this pin during the timing period causes the timer to react just as if the capacitor voltage had reached its normal RC trigger point; the capacitor discharges and the output changes state. An exception to this occurs if the trigger pin is held high when the V_{ADJ} pin is grounded. In this case, the output changes state, but the capacitor does not discharge.

If the trigger drops while V_{ADJ} is being held low, discharge will occur immediately and the cycle will be over. If the trigger is still high when V_{ADJ} is released, the output may or may not change state, depending the voltage across the timing capacitor. For voltages below 2.0V across the timing capacitor, the output will change state immediately, then once more as the voltage rises past 2.0V. For voltages above 2.0V, no change will occur in the output. This pin is not available on the LM2905/LM3905.

In noisy environments or in comparator-type applications, a bypass capacitor on the V_{ADJ} terminal may be needed to eliminate spurious outputs because it is high impedance point. The size of the cap will depend on the frequency and energy content of the noise. A 0.1 μF will generally suffice for spike suppression, but several μF may be used if the timer is subjected to high level 60 Hz EMI.

The emitter and the collector outputs of the timer can be treated just as if they were an ordinary transistor with 40V minimum collector-emitter breakdown voltage. Normally, the emitter is tied to the ground pin and the signal is taken from the collector, or the collector is tied to V⁺ and the signal is taken from the emitter. Variations on these basic connections are possible. The collector can be tied to any positive voltage up to 40V when the signal is taken from the emitter. However, the emitter will not be pulled higher than the supply voltage on the V⁺ pin. Connecting the collector to a voltage less than the V⁺ voltage is allowed. The emitter should not be connected to a low impedance load other than that to which the ground pin is tied. The transistor has built-in current limiting with a typical knee current of 120 mA. Temporary short circuits are allowed; even with collector-emitter voltages up to 40V. The power x time product, however; must not exceed 15 watt-seconds for power levels above the maximum rating of the package. A short to 30V, for instance, can not be held for more than 4 seconds. These levels are based on 40°C maximum initial chip temperature. When driving inductive loads, always use a clamp diode to protect the transistor from inductive kick-back.

A boost pin is provided on the LM122 to increase the speed of the internal comparator. The comparator is normally operated at low current levels for lowest possible input current.

Pin Function Description (Continued)

For timing periods less than 1 ms, where low input current is not needed, comparator operating current can be increased several orders of magnitude. Shorting the boost terminal to V^+ increases the emitter current of the vertical PNP drivers in the differential stage from 25 nA to $5\mu\text{A}$. This pin is not available on the LM2905/LM3905.

With the timer in the unboosted state, timing periods are accurate down to about 1 ms. In the boosted mode, loss of accuracy due to comparator speed is only about 800 ns, so timing periods of several microseconds can be used. The 800 ns error is relatively insensitive to temperature, so temperature coefficient of pulse width is still good.

The **Logic** pin is used to reverse the signal appearing at the output transistor. An open or "high" condition on the logic pin programs the output transistor to be "off" during the timing period and "on" all other times. Grounding the logic pin reverses the sequence to make the transistor "on" during the timing period. Threshold for the logic pin is typically 100 mV with $150\mu\text{A}$ flowing out of the terminal. If an active drive to the logic pin is desired, a saturated transistor drive is recommended, either with a discrete transistor or the open collector output of integrated logic. A maximum V_{SAT} of 25 mV at $200\mu\text{A}$ is required. Minimum and maximum voltages that may appear on the logic pin are 0 and +5.0, respectively.

Typical Applications (Continued)

Basic Timers

Figure 1 is a basic timer using the collector output. R_t and C_t set the time interval with R_L as the load. During the timing interval the output may be

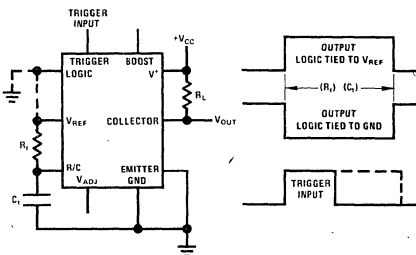


FIGURE 1. Basic Timer-Collector Output and Timing Chart

either high or low depending on the connection of the logic pin. Timing waveforms are shown in the sketch along side Figure 1. Note that the trigger pulse may be either shorter or longer than the output pulse width.

Figure 2 is again a basic timer, but with the output taken from the emitter of the output transistor. As with the collector output, either a high or low condition may be obtained during the timing period.

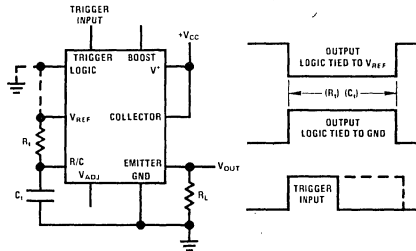


FIGURE 2. Basic Timer-Emitter Output and Timing Chart

Simulating a Thermal Delay Relay

Figure 3 is an application where the LM122 is used to simulate a thermal delay relay which

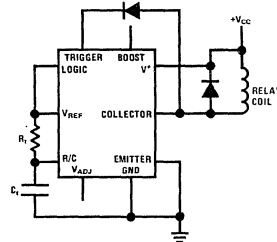


FIGURE 3. Time Out on Power Up (Relay Energized $R_t C_t$ Seconds After V_{CC} is Applied)

prevents power from being applied to other circuitry until the supply has been on for some time. The relay remains de-energized for $R_t C_t$ seconds after V_{CC} is applied, then closes and stays energized until V_{CC} is turned off. Figure 4 is a similar circuit except that the relay is energized

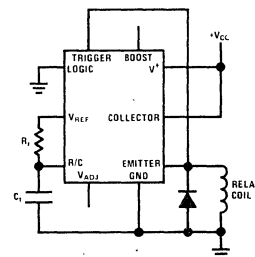


FIGURE 4. Time Out on Power Up (Relay Energized Until $R_t C_t$ Seconds After V_{CC} is Applied)

as soon as V_{CC} is applied. $R_t C_t$ seconds later, the relay is de-energized and stays off until the V_{CC} supply is recycled.

Typical Applications (Continued)

+5V Supply Driving 28V Relay

Figure 5 shows the timer interfacing 5V logic to a high voltage relay. Although the V^+ terminal could be tied to the +28V supply, this may be

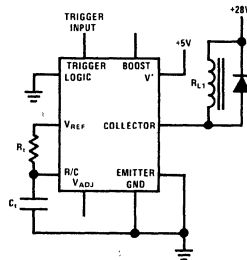


FIGURE 5. 5V Logic Supply Driving 28V Relay

an unnecessary waste of power in the IC or require extra wiring if the LM122 is on a logic card. In either case, the threshold for the trigger is 1.6V.

30V Supply Interfacing with 5V Logic

Figure 6 indicates the ability of the timer to interface to digital logic when operating off a high supply voltage. V_{OUT} swings between +5V and ground with a minimum fanout of 5 for medium speed TTL. If the logic is sensitive to rise/fall time of the trailing edge of the output pulse, the trigger pin should be low at that time.

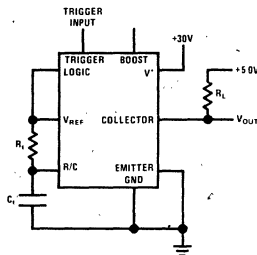


FIGURE 6. 30V Supply Interfacing with 5V Logic

Astable Operation

The LM122 can be made into a self-starting oscillator by feeding the output back to the trigger input through a capacitor as shown in Figure 7. Operating frequency is $1/(R_t + R_1)(C_t)$. The output is a narrow negative pulse whose width is approximately $2R_2 C_t$. For optimum frequency stability, C_t should be as small as possible. The minimum value is determined by the time required to discharge C_t through the internal discharge transistor. A conservative value for C_t can be chosen from the graph included with Figure 20. For frequencies below 1 kHz, the frequency error

introduced by C_f is a few tenths of one percent or less for $R_t \geq 500k$.

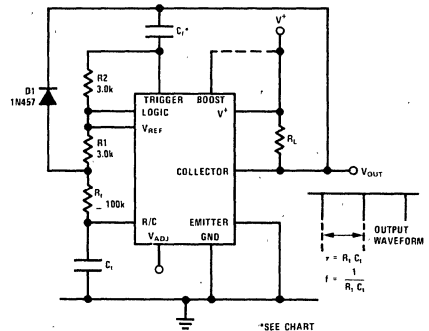


FIGURE 7. Oscillator

One Hour Timer with Reset and Manual Cycle End

Figure 8 shows the LM122 connected as a one hour timer with manual controls for start, reset, and cycle end. S1 starts timing, but has no effect after timing has started. S2 is a center off switch which can either end the cycle prematurely with the appropriate change in output state and discharging of C_t , or cause C_t to be reset to 0V without a change in output. In the latter case, a new timing period starts as soon as S2 is released.

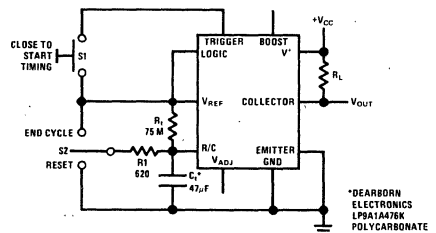


FIGURE 8. One Hour Timer with Reset and Manual Cycle End

The average charging current through R_t is about 30 nA, so some attention must be paid to parts layout to prevent stray leakage paths. The suggested timing capacitor has a typical self time constant of 300 hours and a guaranteed minimum of 25 hours at +25°C. Other capacitor types may be used if sufficient data is available on their leakage characteristics.

Typical Applications (Continued)

Two Terminal Time Delay Switch

The LM122 can be used as a two terminal time delay switch if an "on" voltage drop of 2V to 3V can be tolerated. In *Figure 9*, the timer is used to drive a relay "on" $R_t \cdot C_t$ seconds after application of power. "off" current of the switch is 4 mA maximum, and "on" current can be as high as 50 mA.

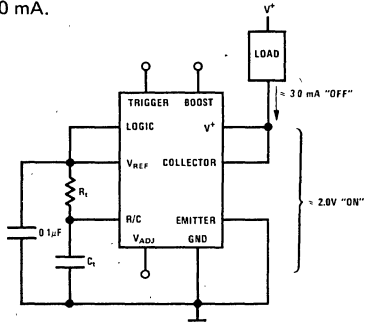


FIGURE 9. 2-Terminal Time Delay Switch

Zero Power Dissipation Between Timing Intervals

In some applications it is desirable to reduce supply current drain to zero between timing cycles. In *Figure 10* This is accomplished by using an external PNP to latch to drive the V^+ pin of the timer.

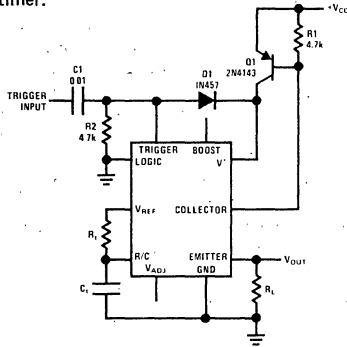


FIGURE 10. Zero Power Dissipation Between Timing Intervals

Between timing periods Q1 is off and no supply current is drawn. When a trigger pulse of 5V minimum amplitude is received, the LM122 output transistor and Q1 latch for the duration of the timing period. D1 prevents the step on the V^+ pin from coupling back into the trigger pin. If the trigger input is a short pulse, C1 and R2 may be eliminated. R_L must have a minimum value of $(V_{CC})/(2.5 \text{ mA})$.

Frequency to Voltage Converter

An accurate frequency to voltage converter can be made with the LM122 by averaging output pulses with a simple one pole filter as shown in *Figure 11*. Pulse width is adjusted with R2 to provide initial calibration at 10 kHz. The collector of the output transistor is tied to V_{REF} , giving constant amplitude pulses equal to V_{REF} at the emitter output. R4 and C1 filter the pulses to

give a dc output equal to, $(R_t)(C_t)(V_{REF})(f)$. Linearity is about 0.2% for a 0V to 1V output. If better linearity is desired R5 can be tied to the summing node of an op amp which has the filter in the feedback path. If a low output impedance is desired, a unity gain buffer such as the LM110 can be tied to the output. An analog meter can be driven directly by placing it in series with R5 to ground. A series RC network across the meter to provide damping will improve response at very low frequencies.

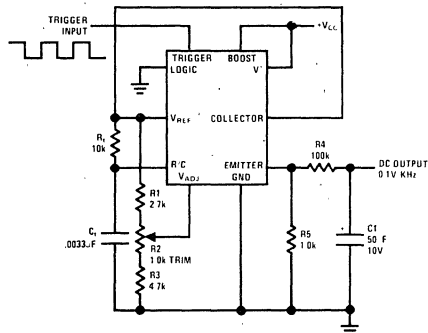


FIGURE 11. Frequency to Voltage Converter. (Tachometer) Output Independent of Supply Voltage

Pulse Width Detector

By driving the logic terminal of the LM122 simultaneous to the trigger input, a simple, accurate pulse width detector can be made (*Figure 12*).

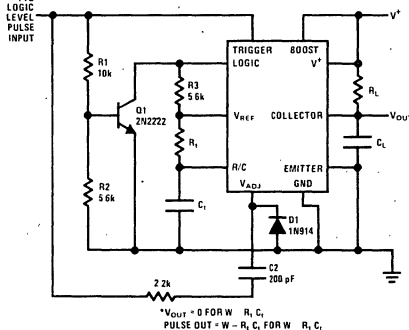


FIGURE 12. Pulse Width Detector

In this application the logic terminal is normally held high by R3. When a trigger pulse is received, Q1 is turned on, driving the logic terminal to ground. The result of triggering the timer and reversing the logic at the same time is that the output does not change from its initial low condition. The only time the output will change states is when the trigger input stays high longer than one time period set by R_t and C_t . The output pulse width is equal to the input trigger width minus $R_t \cdot C_t$. C2 insures no output pulse for short ($< RC$) trigger pulses by prematurely resetting the timing capacitor when the trigger pulse drops. C_L filters the narrow spikes which would occur at the output due to propagation delays during switching.



Typical Applications (Continued)

5V Switching Regulator

Figure 13 is an application where the LM122 does not use its timing function. A switching regulator is made using the internal reference and comparator to drive a PNP transistor switch. Features of this circuit include a 5.5V minimum input voltage at 1A output current, low part count, and good efficiency ($> 75\%$) for input voltages to 10V. Line and load regulation are less than 0.5% and output ripple at the switching frequency is only 30 mV. Q1 is an inexpensive plastic device which does not need a heatsink for ambient temperature up to 50°C. D1 should be a fast switching diode. Output voltage can be adjusted between 1V and 30V by choosing proper values for R2, R3, R4, and R5. For outputs less than 2V, a divider with 250Ω Thevinin resistance must be connected between V_{REF} and ground with its tap point tied to V_{ADJ} .

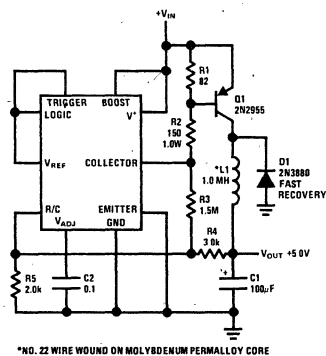


FIGURE 13. 5V Switching Regulator with 1 Amp Output and 5.5V Minimum Input

Application Hints

Aborting a Timing Cycle

The LM122 does not have an input specifically allocated to a stop-timing function. If such a function is desired, it may be accomplished several ways:

- Ground V_{ADJ}
- Raise R/C more positive than V_{ADJ}
- Wire "OR" the output

Grounding V_{ADJ} will end the timing cycle just as if the timing capacitor had reached its normal discharge point. A new timing cycle can be started by the trigger terminal as soon as the ground is released. A switching transistor is best for driving V_{ADJ} to as near ground as possible. Worst case sink current is about 300μA.

A timing cycle may also be ended by a positive pulse to a resistor ($R \leq R_T/100$) in series with the timing capacitor. The pulse amplitude must be at least equal to V_{ADJ} (2.0V), but should not exceed 5.0V. When the timing capacitor discharges,

a negative spike of up to 2.0V will occur across the resistor, so some caution must be used if the drive pulse is used for other circuitry.

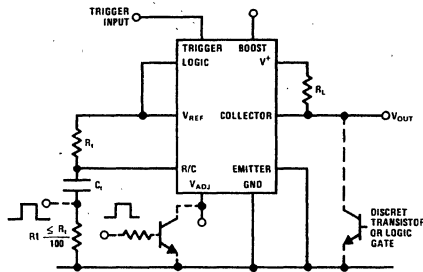


FIGURE 14. Cycle Interrupt

The output of the timer can be wire ORed with a discrete transistor or an open collector logic gate output. This allows overriding of the timer output, but does not cause the timer to be reset until its normal cycle time has elapsed.

Using the LM122 as a Comparator

A built-in reference and zero volt common mode limit make the LM122 very useful as a comparator. Threshold may be adjusted from zero to three volts by driving the V_{ADJ} terminal with a divider tied to V_{REF} . Stability of the reference voltage is typically $\pm 1\%$ over a temperature range of -55°C to $+125^\circ\text{C}$. Offset voltage drift in the comparator is typically $25\mu\text{V}/^\circ\text{C}$ in the boosted mode and $50\mu\text{V}/^\circ\text{C}$ unboosted. A resistor can be inserted in series with the input to allow overdrives up to $\pm 50\text{V}$ as shown in Figure 15. There is actually no limit on input voltage as long as current is limited to $\pm 1\text{mA}$. The resistor shown contributes

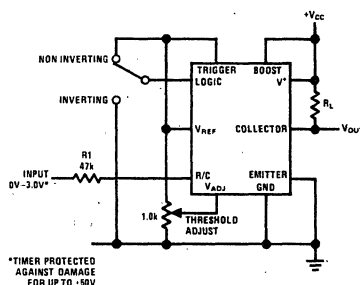


FIGURE 15. Comparator with 0V to 3V Threshold

a worst case of 5 mV to initial offset. In the unboosted mode, the error drops to 0.25 mV maximum. The capability of operating off a single 5V supply with internal reference should make this comparator very useful.

Application Hints (Continued)

Eliminating Timing Cycle Upon Initial Application of Power

The LM122 will normally start a timing cycle (with no trigger input) when V^+ is first turned on. If this characteristic is undesirable, it can be defeated by tying the timing capacitor to V_{REF} instead of ground as shown in Figure 16. This connection does not affect operation of the timer in any other way. If an electrolytic timing capacitor is used, be sure the negative end is tied to the R/C pin and the positive end to V_{REF} . A 1.0 k Ω resistor should be included in series with the timing capacitor to limit the surge current load on V_{REF} when the capacitor is discharged.

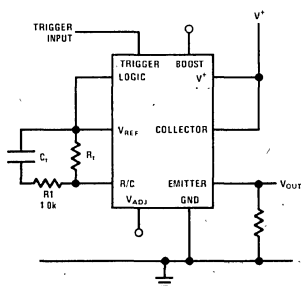
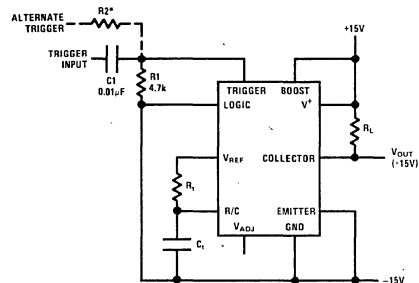


FIGURE 16. Eliminating Initial Timing Cycle

Using Dual Supplies

The LM122 can be operated off dual supplies as shown in Figure 17. The only limitation is that the emitter terminal cannot be tied to ground, it must either drive a load referred to V^- or be actually tied to V^- as shown. Although capacitive coupling is shown for the trigger input (to allow 5V triggering), a resistor can be substituted for C1. R2 must be chosen to give proper level shifting between the trigger signal and the trigger pin of the timer. Worst case "lo" on the trigger pin (with respect to V^-) is 0.8V, and worst case "high" is 2.5V. R2 may be calculated from the divider equation with R1 to give these levels.



*SELECT FOR PROPER LEVEL SHIFT
EMITTER TERMINAL OR EMITTER LOAD MUST BE TIED TO GND PIN OF TIMER.

FIGURE 17. Operating Off Dual Supplies

Linearizing the Charging Sweep

In some applications (such as a linear pulse width modulator) it may be desirable to have the timing capacitor charge from a constant current source. A simple way to accomplish this is shown in Figure 18.

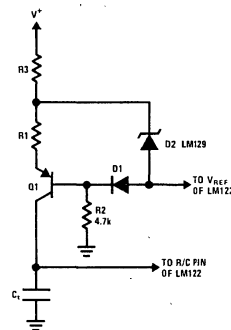


FIGURE 18. Temperature Compensated Linear Charging Sweep

Q1 converts the current through R1 to a current source independent of the voltage across C_1 . R2, R3, D1, and D2 are added to make the current through R1 independent of supply variations and temperature changes. (D2 is a low TC type) D2 and R3 can be omitted if the V^+ supply is stable and D1 and R2 can be omitted also if temperature stability is not critical. With D1, D2, R2 and R3 omitted, the current through R1 will change about 0.015%/°C with a 15V supply and 0.1%/°C with a 5.0V supply.

Triggering with Negative Edge

Although the LM122 is triggered by a positive going trigger signal, a differentiator tied to a normally "high" trigger will result in negative edge triggering. In Figure 19, R1 serves the dual purpose of holding the trigger pin normally high and differentiating the input trigger pulse coupled through C1. The timing diagram included with Figure 21 shows that triggering actually occurs a short time after the negative going trigger, while positive going triggers have no effect. The delay time between a negative trigger signal and actual

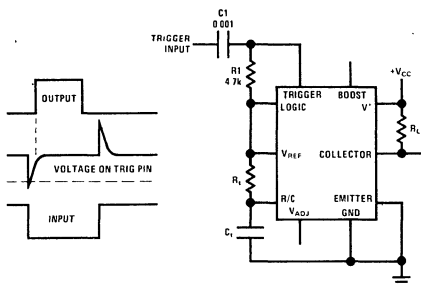


FIGURE 19. Timer Triggered by Negative Edge of Input Pulse

Application Hints (Continued)

starts of timing is approximately (0.5 to 1.5) ($R_1 \cdot C_1$) depending on the trigger amplitude, or about 2.5 to 7.5 μ s with the values shown. This time will have to be increased for C_t larger than 0.01 μ F because C_t is charged to V_{REF} whenever the trigger pin is kept high and must reset itself during the short time that the trigger pin voltage is low. A conservative value for C_1 is:

$$C_1 \geq \frac{C_t}{10}$$

Chain of Timers

The LM122 can be connected as a chain of timers quite easily with no interface required. In *Figure 20A and 20B*, two possible connections are shown. In both cases, the output of the timer is low during the timing period so that the positive going signal at the end of timing period can trigger the next timer. There is no limitation on the timing period of one timer with respect to any other timer before or after it, because the trigger input to any timer can be high or low when that timer ends its timing period.

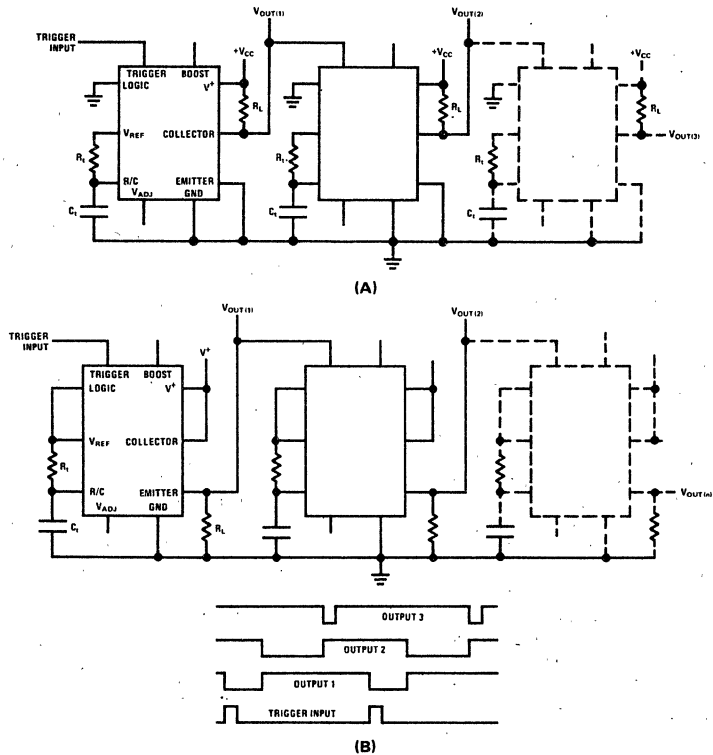


FIGURE 20. Chain of Timers

LM134/LM234/LM334 3-Terminal Adjustable Current Sources

General Description

The LM134/LM234/LM334 are 3-terminal adjustable current sources featuring 10,000:1 range in operating current, excellent current regulation and a wide dynamic voltage range of 1V to 40V. Current is established with one external resistor and no other parts are required. Initial current accuracy is $\pm 3\%$. The LM134/LM234/LM334 are true floating current sources with no separate power supply connections. In addition, reverse applied voltages of up to 20V will draw only a few microamperes of current, allowing the devices to act as both a rectifier and current source in AC applications.

The sense voltage used to establish operating current in the LM134 is 64 mV at 25°C and is directly proportional to absolute temperature (°K). The simplest one external resistor connection, then, generates a current with $\approx +0.33\%/^{\circ}\text{C}$ temperature dependence. Zero drift operation can be obtained by adding one extra resistor and a diode.

Applications for the new current sources include bias networks, surge protection, low power reference, ramp generation, LED driver, and temperature sensing. The

LM134-3/LM234-3 and LM134-6/LM234-6 are specified as true temperature sensors with guaranteed initial accuracy of $\pm 3^{\circ}\text{C}$ and $\pm 6^{\circ}\text{C}$, respectively. These devices are ideal in remote sense applications because series resistance in long wire runs does not affect accuracy. In addition, only 2 wires are required.

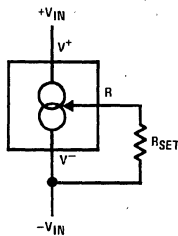
The LM134 is guaranteed over a temperature range of -55°C to $+125^{\circ}\text{C}$, the LM234 from -25°C to $+100^{\circ}\text{C}$ and the LM334 from 0°C to $+70^{\circ}\text{C}$. These devices are available in TO-46 hermetic and TO-92 plastic packages.

Features

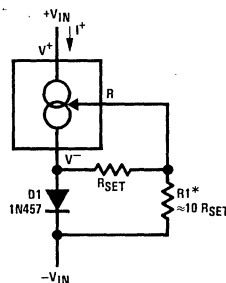
- Operates from 1V to 40V
- 0.02%/V current regulation
- Programmable from 1 μA to 10 mA
- True 2-terminal operation
- Available as fully specified temperature sensor
- $\pm 3\%$ initial accuracy

Typical Applications

Basic 2-Terminal Current Source

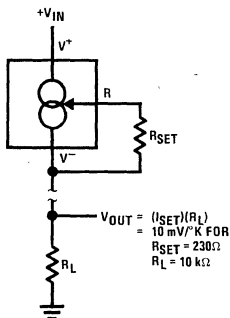


Zero Temperature Coefficient Current Source



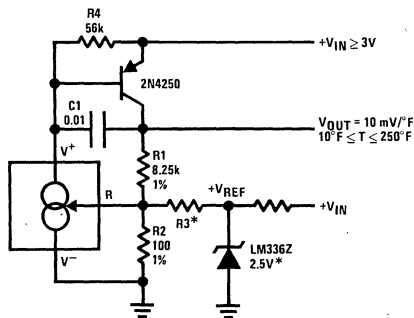
*Select ratio of R1 to RSET to obtain zero drift. $I^+ \approx 2 I_{SET}$

Terminating Remote Sensor for Voltage Output



$$V_{OUT} = \frac{I_{SET} R_L}{10 \text{ mV/K FOR } R_{SET} = 230\Omega, R_L = 10 \text{ k}\Omega}$$

Ground Referred Fahrenheit Thermometer



*Select $R_3 = V_{REF}/583 \mu\text{A}$. V_{REF} may be any stable positive voltage $\geq 2\text{V}$. Trim R3 to calibrate.

Absolute Maximum Ratings

| | |
|--|-----------------|
| V^+ to V^- Forward Voltage | |
| LM134/LM234 | 40V |
| LM334/LM134-3/LM134-6/LM234-3/LM234-6 | 30V |
| V^+ to V^- Reverse Voltage | 20V |
| R Pin to V^- Voltage | 5V |
| Set Current | 10 mA |
| Power Dissipation | 200 mW |
| Operating Temperature Range | |
| LM134/LM134-3/LM134-6 | -55°C to +125°C |
| LM234/LM234-3/LM234-6 | -25°C to +100°C |
| LM334 | 0°C to +70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM134/LM234 | | | LM334 | | | UNITS |
|---|---------------------------------------|-------------|------|-------|-------|------|-------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Set Current Error, $V^+ = 2.5V$, (Note 2) | $10 \mu A \leq I_{SET} \leq 1 mA$ | | | 3 | | | 6 | % |
| | $1 mA < I_{SET} \leq 5 mA$ | | | 5 | | | 8 | % |
| | $2 \mu A \leq I_{SET} < 10 \mu A$ | | | 5 | | | 8 | % |
| Ratio of Set Current to V^- Current | $10 \mu A \leq I_{SET} \leq 1 mA$ | 14 | 18 | 23 | 14 | 18 | 26 | |
| | $1 mA \leq I_{SET} \leq 5 mA$ | | 14 | | | 14 | | |
| | $2 \mu A \leq I_{SET} \leq 10 \mu A$ | 14 | 18 | 23 | 14 | 18 | 26 | |
| Minimum Operating Voltage | $2 \mu A \leq I_{SET} \leq 100 \mu A$ | | 0.8 | | | 0.8 | | V |
| | $100 \mu A < I_{SET} \leq 1 mA$ | | 0.9 | | | 0.9 | | V |
| | $1 mA < I_{SET} \leq 5 mA$ | | 1.0 | | | 1.0 | | V |
| Average Change in Set Current with Input Voltage | $1.5 \leq V^+ \leq 5V$ | | 0.02 | 0.05 | | 0.02 | 0.1 | %/V |
| | $2 \mu A \leq I_{SET} \leq 1 mA$ | | | | | | | |
| | $5V \leq V^+ \leq 40V$ | | 0.01 | 0.03 | | 0.01 | 0.05 | %/V |
| | $1.5V \leq V \leq 5V$ | | 0.03 | | | 0.03 | | %/V |
| | $1 mA < I_{SET} \leq 5 mA$ | | | | | | | |
| Temperature Dependence of Set Current (Note 3) | $5V \leq V \leq 40V$ | | 0.02 | | | 0.02 | | %/V |
| | $25 \mu A \leq I_{SET} \leq 1 mA$ | 0.96T | T | 1.04T | 0.96T | T | 1.04T | |
| Effective Shunt Capacitance | | | 15 | | | 15 | | pF |

Note 1: Unless otherwise specified, tests are performed at $T_j = 25^\circ C$ with pulse testing so that junction temperature does not change during test.

Note 2: Set current is the current flowing into the V^+ pin. It is determined by the following formula: $I_{SET} = 67.7 \text{ mV}/R_{SET}$ (@ $25^\circ C$). Set current error is expressed as a percent deviation from this amount. I_{SET} increases at $0.336\%/^\circ C$ @ $T_j = 25^\circ C$.

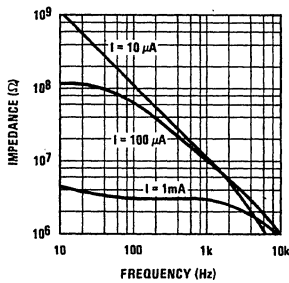
Note 3: I_{SET} is directly proportional to absolute temperature ($^\circ K$). I_{SET} at any temperature can be calculated from: $I_{SET} = I_o (T/T_o)$ where I_o is I_{SET} measured at T_o ($^\circ K$).

Electrical Characteristics (Continued) (Note 1)

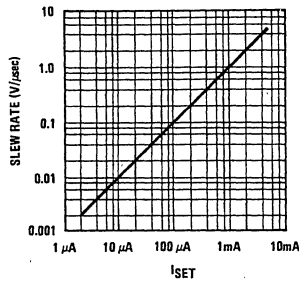
| PARAMETER | CONDITIONS | LM134-3, LM234-3 | | | LM134-6, LM234-6 | | | UNITS |
|---|--|------------------|------|---------|------------------|------|---------|------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Set Current Error, $V^+ = 2.5V$, (Note 2) | $100 \mu A \leq I_{SET} \leq 1 mA$ $T_j = 25^\circ C$ | | | ± 1 | | | ± 2 | % |
| Equivalent Temperature Error | | | | ± 3 | | | ± 6 | $^\circ C$ |
| Ratio of Set Current to V^- Current | $100 \mu A \leq I_{SET} \leq 1 mA$ | 14 | 18 | 26 | 14 | 18 | 26 | |
| Minimum Operating Voltage | $100 \mu A \leq I_{SET} \leq 1 mA$ | | 0.9 | | | 0.9 | | V |
| Average Change in Set Current with Input Voltage | $1.5 \leq V^+ \leq 5V$ $100 \mu A \leq I_{SET} \leq 1 mA$ | | 0.02 | 0.05 | | 0.02 | 0.1 | %/V |
| | $5V \leq V^+ \leq 30V$ | | 0.01 | 0.03 | | 0.01 | 0.05 | %/V |
| Temperature Dependence of Set Current (Note 3) and Equivalent Slope Error | $100 \mu A \leq I_{SET} \leq 1 mA$ | 0.98T | T | 1.02T | 0.97T | T | 1.03T | |
| | | | | ± 2 | | | ± 3 | % |
| Effective Shunt Capacitance | | | 15 | | | 15 | | pF |

Typical Performance Characteristics

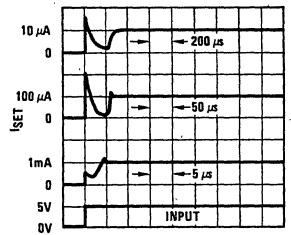
Output Impedance



Maximum Slew Rate for Linear Operation

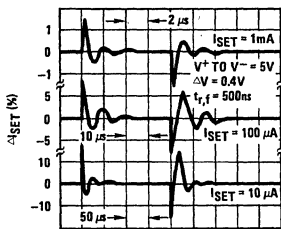


Start-Up



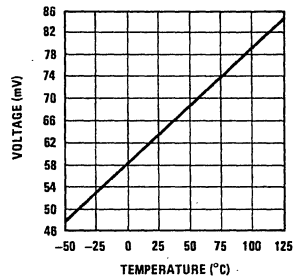
TIME (Note scale changes at each current level)

Transient Response

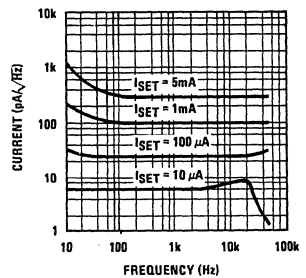


TIME (Note scale changes for each current)

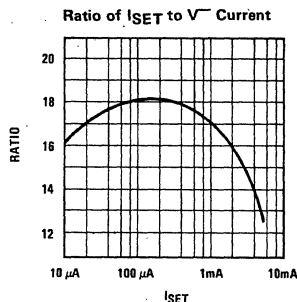
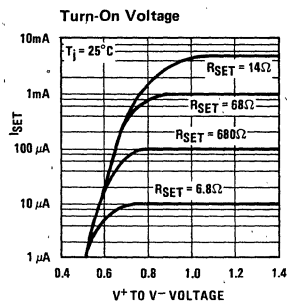
Voltage Across R_{SET}



Current Noise



Typical Performance Characteristics (Continued)



Application Hints

The LM134 has been designed for ease of application, but a general discussion of design features is presented here to familiarize the designer with device characteristics which may not be immediately obvious. These include the effects of slewing, power dissipation, capacitance, noise, and contact resistance.

SLEW RATE

At slew rates above a given threshold (see curve), the LM134 may exhibit non-linear current shifts. The slewing rate at which this occurs is directly proportional to I_{SET} . At $I_{SET} = 10 \mu\text{A}$, maximum dV/dt is $0.01V/\mu\text{s}$; at $I_{SET} = 1 \text{mA}$, the limit is $1V/\mu\text{s}$. Slew rates above the limit do not harm the LM134, or cause large currents to flow.

THERMAL EFFECTS

Internal heating can have a significant effect on current regulation for I_{SET} greater than $100 \mu\text{A}$. For example, each 1V increase across the LM134 at $I_{SET} = 1 \text{mA}$ will increase junction temperature by $\approx 0.4^\circ\text{C}$ in still air. Output current (I_{SET}) has a temperature coefficient of $\approx 0.33\%/^\circ\text{C}$, so the change in current due to temperature rise will be $(0.4)(0.33) = 0.132\%$. This is a 10:1 degradation in regulation compared to true electrical effects. Thermal effects, therefore, must be taken into account when DC regulation is critical and I_{SET} exceeds $100 \mu\text{A}$. Heat sinking of the TO-46 package or the TO-92 leads can reduce this effect by more than 3:1.

SHUNT CAPACITANCE

In certain applications, the 15 pF shunt capacitance of the LM134 may have to be reduced, either because of loading problems or because it limits the AC output impedance of the current source. This can be easily accomplished by buffering the LM134 with an FET as shown in the applications. This can reduce capacitance to less than 3 pF and improve regulation by at least an order of magnitude. DC characteristics (with the exception of minimum input voltage), are not affected.

NOISE

Current noise generated by the LM134 is approximately 4 times the shot noise of a transistor. If the LM134 is used as an active load for a transistor amplifier, input

referred noise will be increased by about 12 dB. In many cases, this is acceptable and a single stage amplifier can be built with a voltage gain exceeding 2000.

LEAD RESISTANCE

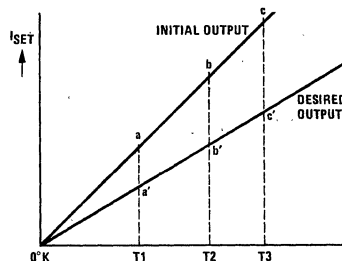
The sense voltage which determines operating current of the LM134 is less than 100 mV. At this level, thermocouple or lead resistance effects should be minimized by locating the current setting resistor physically close to the device. Sockets should be avoided if possible. It takes only 0.7Ω contact resistance to reduce output current by 1% at the 1 mA level.

SENSING TEMPERATURE

The LM134 makes an ideal remote temperature sensor because its current mode operation does not lose accuracy over long wire runs. Output current is directly proportional to absolute temperature in degrees Kelvin, according to the following formula:

$$I_{SET} = \frac{(227 \mu\text{V}/^\circ\text{K})(T)}{R_{SET}}$$

Calibration of the LM134 is greatly simplified because of the fact that most of the initial inaccuracy is due to a gain term (slope error) and not an offset. This means that a calibration consisting of a gain adjustment only will trim both slope and zero at the same time. In addition, gain adjustment is a one point trim because the output of the LM134 extrapolates to zero at 0°K , independent of R_{SET} or any initial inaccuracy.



This property of the LM134 is illustrated in the accompanying graph. Line abc is the sensor current before

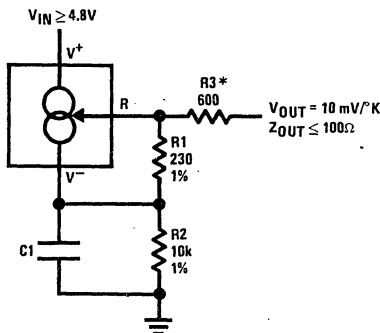
Application Hints (Continued)

trimming. Line a'b'c' is the desired output. A gain trim done at T2 will move the output from b to b' and will simultaneously correct the slope so that the output at T1 and T3 will be correct. This gain trim can be done on RSET or on the load resistor used to terminate the LM134. Slope error after trim will normally be less than ±1%. To maintain this accuracy, however, a low temperature coefficient resistor must be used for RSET.

A 33 ppm/°C drift of RSET will give a 1% slope error because the resistor will normally see about the same temperature variations as the LM134. Separating RSET from the LM134 requires 3 wires and has lead resistance problems, so is not normally recommended. Metal film resistors with less than 20 ppm/°C drift are readily available. Wire wound resistors may also be used where best stability is required.

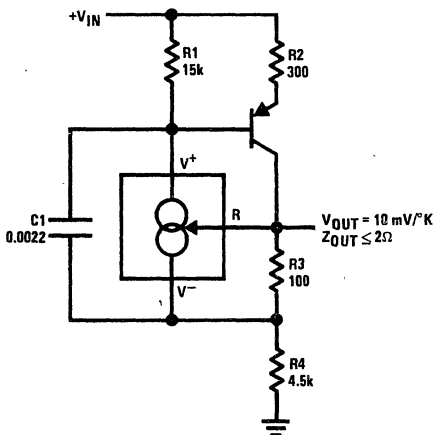
Typical Applications (Continued)

Low Output Impedance Thermometer

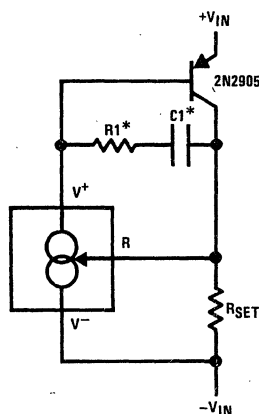


*Output impedance of the LM134 at the "R" pin is approximately $\frac{-R_O}{16}$, where R_O is the equivalent external resistance connected to the V^- pin. This negative resistance can be reduced by a factor of 5 or more by inserting an equivalent resistor in series with the output.

Low Output Impedance Thermometer



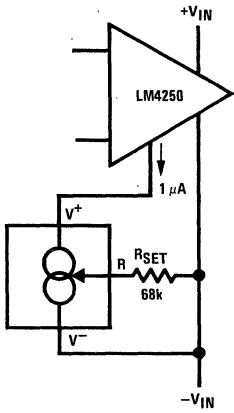
Higher Output Current



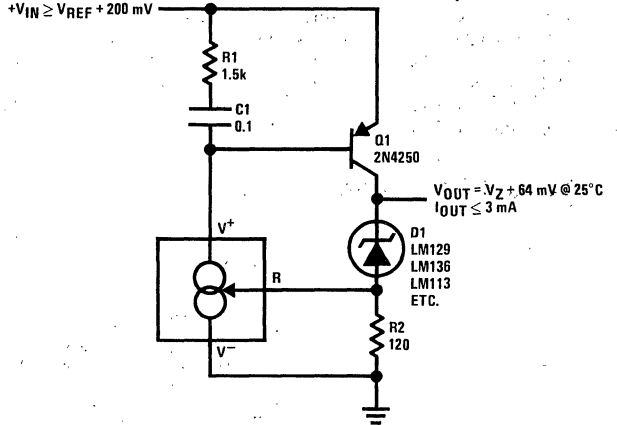
*Select R1 and C1 for optimum stability

Typical Applications (Continued)

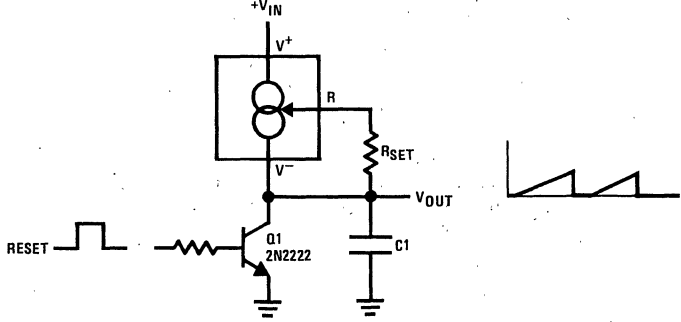
Micropower Bias



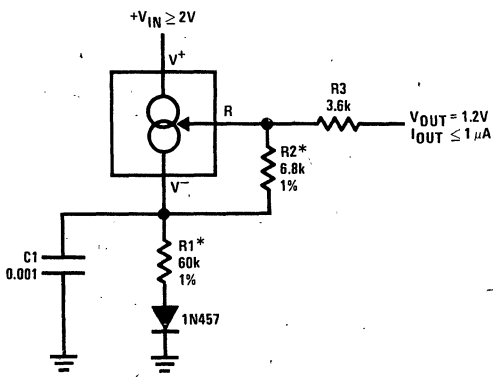
Low Input Voltage Reference Driver



Ramp Generator

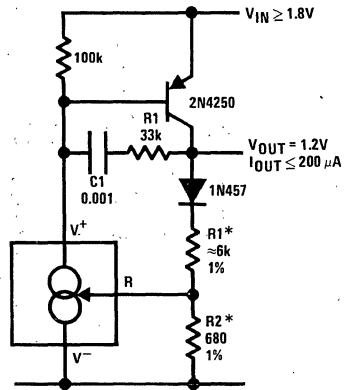


1.2V Reference Operates on 10 μA and 2V



*Select ratio of R1 to R2 to obtain zero temperature drift

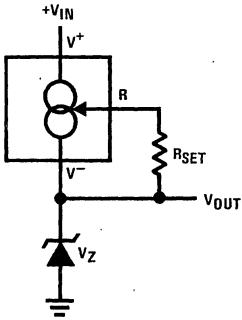
1.2V Regulator with 1.8V Minimum Input



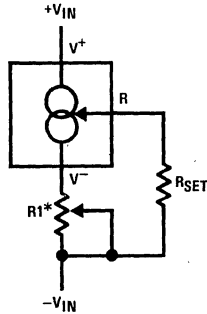
*Select ratio of R1 to R2 for zero temperature drift

Typical Applications (Continued)

Zener Biasing

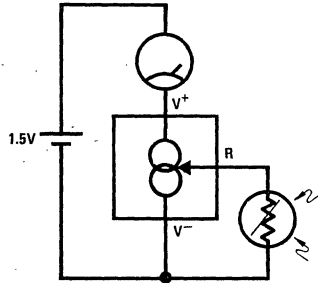


Alternate Trimming Technique

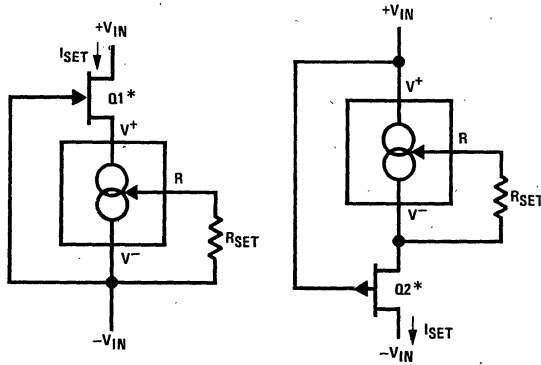


* For $\pm 10\%$ adjustment, select R_{SET} 10% high, and make $R1 \approx 3 R_{SET}$

Buffer for Photoconductive Cell

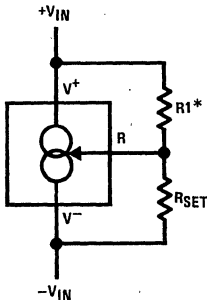


FET Cascoding for Low Capacitance and/or Ultra High Output Impedance



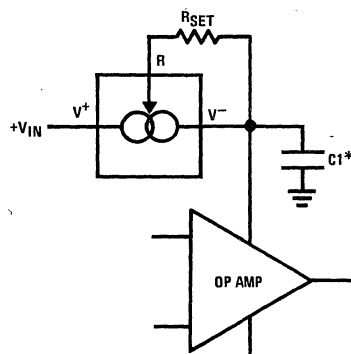
*Select Q1 or Q2 to ensure at least 1V across the LM134. $V_p (1 - |I_{SET}|/I_{DSS}) \geq 1.2V$.

Generating Negative Output Impedance



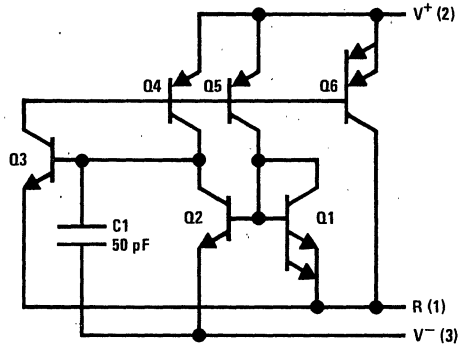
* $Z_{OUT} \approx -16 \cdot R1$ ($R1/V_{IN}$ must not exceed I_{SET})

In-Line Current Limiter

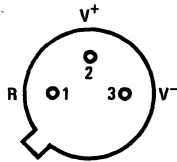


*Use minimum value required to ensure stability of protected device. This minimizes inrush current to a direct short.

Schematic and Connection Diagrams



TO-46
Metal Can Package

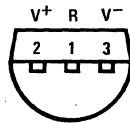


BOTTOM VIEW

Pin 3 is electrically connected to case

Order Number LM134H, LM134H-3,
LM134H-6, LM234H, LM234H-3,
LM234H-6 or LM334H
See NS Package H03H

TO-92
Plastic Package



BOTTOM VIEW

Order Number LM334Z, LM234Z-3
or LM234Z-6
See NS Package Z03A

LM135/LM235/LM335, LM135A/LM235A/LM335A Precision Temperature Sensors

General Description

The LM135 series are precision, easily-calibrated, integrated circuit temperature sensors. Operating as a 2-terminal zener, the LM135 has a breakdown voltage directly proportional to absolute temperature at +10 mV/°K. With less than 1Ω dynamic impedance the device operates over a current range of 400 μA to 5 mA with virtually no change in performance. When calibrated at 25°C the LM135 has typically less than 1°C error over a 100°C temperature range. Unlike other sensors the LM135 has a linear output.

Applications for the LM135 include almost any type of temperature sensing over a -55°C to +150°C temperature range. The low impedance and linear output make interfacing to readout or control circuitry especially easy.

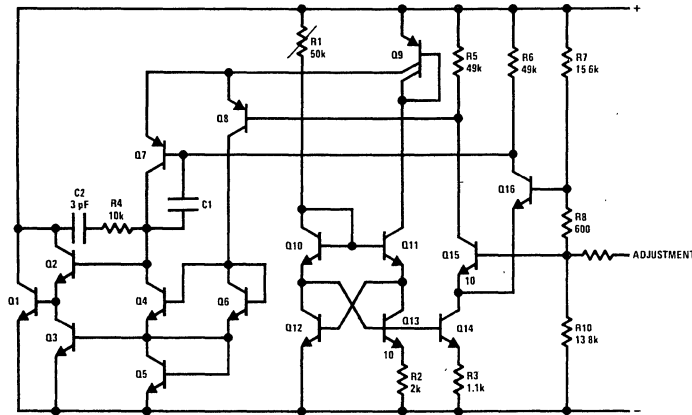
The LM135 operates over a -55°C to +150°C temperature range while the LM235 operates over a -40°C

to +125°C temperature range. The LM335 operates from -10°C to +100°C. The LM135/LM235/LM335 are available packaged in hermetic TO-46 transistor packages while the LM235 and LM335 are also available in plastic TO-92 packages.

Features

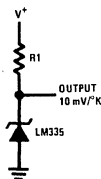
- Directly calibrated in °Kelvin
- 1°C initial accuracy available
- Operates from 400 μA to 5 mA
- Less than 1Ω dynamic impedance
- Easily calibrated
- Wide operating temperature range
- 200°C overrange
- Low cost

Schematic Diagram

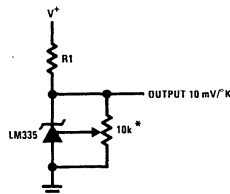


Typical Applications

Basic Temperature Sensor

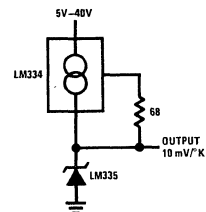


Calibrated Sensor



* Calibrate for 2.982V at 25°C

Wide Operating Supply



Absolute Maximum Ratings

| | |
|--|-------------------------------------|
| Reverse Current | 10 mA |
| Forward Current | 10 mA |
| Storage Temperature | |
| TO-46 Package | -60°C to +180°C |
| TO-92 Package | -60°C to +150°C |
| Specified Operating Temperature Range | |
| Continuous | Intermittent |
| LM135, LM135A | -55°C to +150°C 150°C to 200°C |
| LM235, LM235A | -40°C to +125°C 125°C to 150°C |
| LM335, LM335A | -10°C to +100°C 100°C to 125°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Temperature Accuracy LM135/LM235, LM135A/LM235A (Note 1)

| PARAMETER | CONDITIONS | LM135A/LM235A | | | LM135/LM235 | | | UNITS |
|---|--|---------------|------|------|-------------|------|------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Operating Output Voltage | $T_C = 25^\circ\text{C}, I_R = 1\text{ mA}$ | 2.97 | 2.98 | 2.99 | 2.95 | 2.98 | 3.01 | V |
| Uncalibrated Temperature Error | $T_C = 25^\circ\text{C}, I_R = 1\text{ mA}$ | | 0.5 | 1 | | 1 | 3 | °C |
| Uncalibrated Temperature Error | $T_{\text{MIN}} < T_C < T_{\text{MAX}}, I_R = 1\text{ mA}$ | | 1.3 | 2.7 | | 2 | 5 | °C |
| Temperature Error with 25°C Calibration | $T_{\text{MIN}} < T_C < T_{\text{MAX}}, I_R = 1\text{ mA}$ | | 0.3 | 1 | | 0.5 | 1.5 | °C |
| Calibrated Error at Extended Temperatures | $T_C = T_{\text{MAX}}$ (Intermittent) | | 2 | | | 2 | | °C |
| Non-Linearity | $I_R = 1\text{ mA}$ | | 0.3 | 0.5 | | 0.3 | 1 | °C |

Temperature Accuracy LM335, LM335A (Note 1)

| PARAMETER | CONDITIONS | LM335A | | | LM335 | | | UNITS |
|---|--|--------|------|------|-------|------|------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Operating Output Voltage | $T_C = 25^\circ\text{C}, I_R = 1\text{ mA}$ | 2.95 | 2.98 | 3.01 | 2.92 | 2.98 | 3.04 | V |
| Uncalibrated Temperature Error | $T_C = 25^\circ\text{C}, I_R = 1\text{ mA}$ | | 1 | 3 | | 2 | 6 | °C |
| Uncalibrated Temperature Error | $T_{\text{MIN}} < T_C < T_{\text{MAX}}, I_R = 1\text{ mA}$ | | 2 | 5 | | 4 | 9 | °C |
| Temperature Error with 25°C Calibration | $T_{\text{MIN}} < T_C < T_{\text{MAX}}, I_R = 1\text{ mA}$ | | 0.5 | 1 | | 1 | 2 | °C |
| Calibrated Error at Extended Temperatures | $T_C = T_{\text{MAX}}$ (Intermittent) | | 2 | | | 2 | | °C |
| Non-Linearity | $I_R = 1\text{ mA}$ | | 0.3 | 1.5 | | 0.3 | 1.5 | °C |

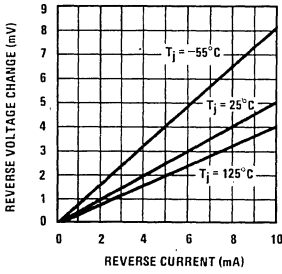
Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | LM135/LM235 LM135A/LM235A | | | LM335 LM335A | | | UNITS |
|----------------------------------|---------------------------|--|---|-----|-----------------|-----|-----|----------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| | | Operating Output Voltage Change with Current | $400\ \mu\text{A} < I_R < 5\text{ mA}$ At Constant Temperature | | 2.5 | 10 | | |
| Dynamic Impedance | $I_R = 1\text{ mA}$ | | 0.5 | | | 0.6 | | Ω |
| Output Voltage Temperature Drift | | | +10 | | | +10 | | mV/°C |
| Time Constant | Still Air | | 80 | | | 80 | | sec |
| | 100 ft/Min Air | | 10 | | | 10 | | sec |
| | Stirred Oil | | 1 | | | 1 | | sec |
| Time Stability | $T_C = 125^\circ\text{C}$ | | 0.2 | | | 0.2 | | °C/chr |

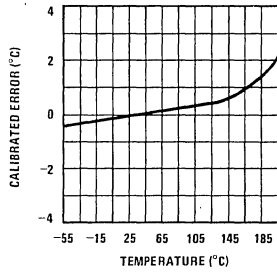
Note 1: Accuracy measurements are made in a well-stirred oil bath. For other conditions, self heating must be considered.

Typical Performance Characteristics

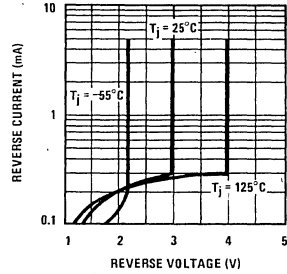
Reverse Voltage Change



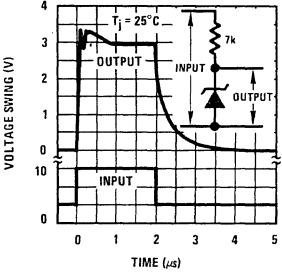
Calibrated Error



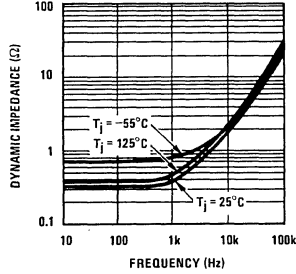
Reverse Characteristics



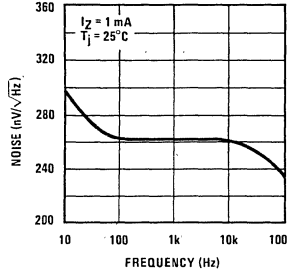
Response Time



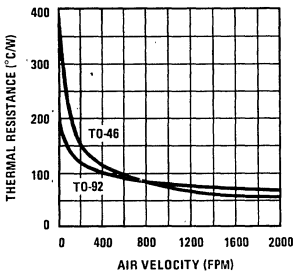
Dynamic Impedance



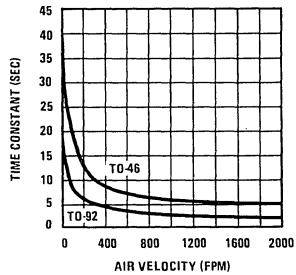
Noise Voltage



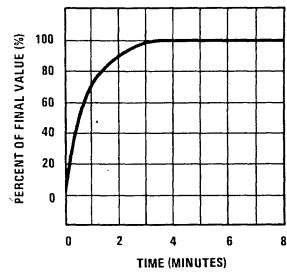
Thermal Resistance Junction to Air



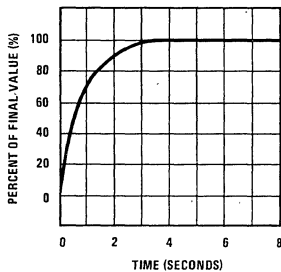
Thermal Time Constant



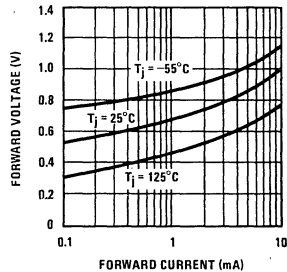
Thermal Response in Still Air



Thermal Response in Stirred Oil Bath



Forward Characteristics



Application Hints

CALIBRATING THE LM135

Included on the LM135 chip is an easy method of calibrating the device for higher accuracies. A pot connected across the LM135 with the arm tied to the adjustment terminal allows a 1-point calibration of the sensor that corrects for inaccuracy over the full temperature range.

This single point calibration works because the output of the LM135 is proportional to absolute temperature with the extrapolated output of sensor going to 0V output at 0°K (-273.15°C). Errors in output voltage versus temperature are only slope (or scale factor) so a slope calibration at one temperature corrects at all temperatures.

The output of the device (calibrated or uncalibrated) can be expressed as:

$$V_{OUT_T} = V_{OUT_{T_0}} \times \frac{T}{T_0}$$

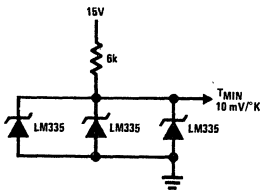
where T is the unknown temperature and T₀ is a reference temperature, both expressed in degrees Kelvin. By calibrating the output to read correctly at one temperature the output at all temperatures is correct. Nominally the output is calibrated at 10 mV/°K.

To insure good sensing accuracy several precautions must be taken. Like any temperature sensing device, self heating can reduce accuracy. The LM135 should be operated at the lowest current suitable for the application. Sufficient current, of course, must be available to drive both the sensor and the calibration pot at the maximum operating temperature.

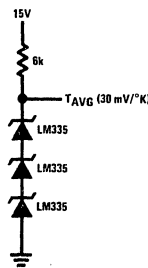
If the sensor is used in an ambient where the thermal resistance is constant, self heating errors can be calibrated out. This is possible if the device is run with a temperature stable current. Heating will then be proportional to zener voltage and therefore temperature. This makes the self heating error proportional to absolute temperature the same as scale factor errors.

Typical Applications (Continued)

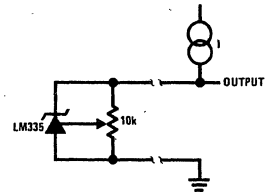
Minimum Temperature Sensing



Average Temperature Sensing



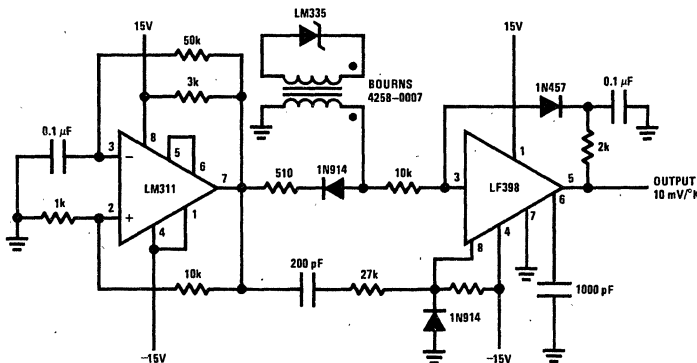
Remote Temperature Sensing



Wire length for 1° C error due to wire drop

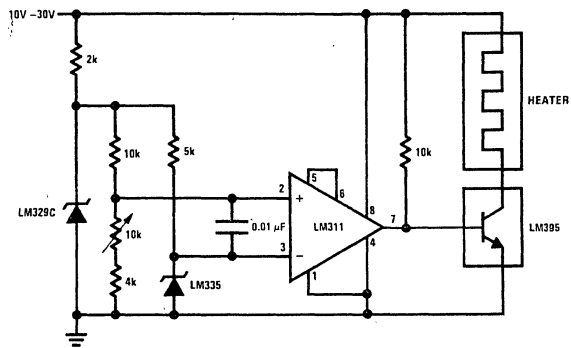
| AWG | I _R = 1 mA | I _R = 0.5 mA |
|-----|-----------------------|-------------------------|
| | FEET | FEET |
| 14 | 4000 | 8000 |
| 16 | 2500 | 5000 |
| 18 | 1600 | 3200 |
| 20 | 1000 | 2000 |
| 22 | 625 | 1250 |
| 24 | 400 | 800 |

Isolated Temperature Sensor

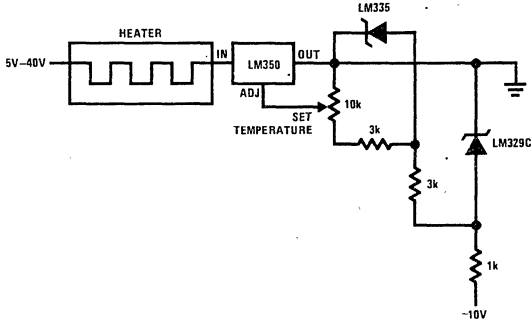


Typical Applications (Continued)

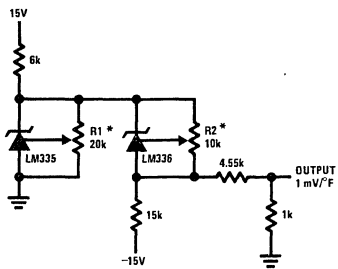
Simple Temperature Controller



Simple Temperature Control

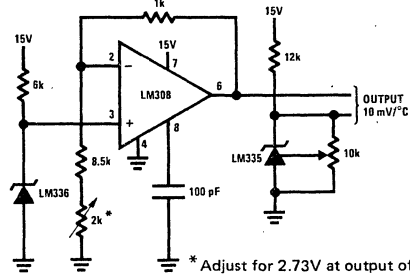


Ground Referred Fahrenheit Thermometer



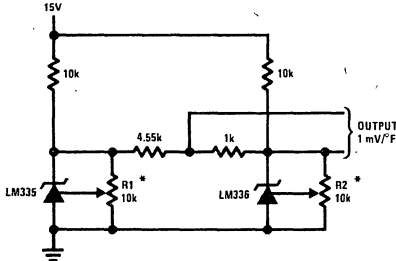
* Adjust R2 for 2.554V across LM336.
Adjust R1 for correct output.

Centigrade Thermometer



* Adjust for 2.73V at output of LM308

Fahrenheit Thermometer



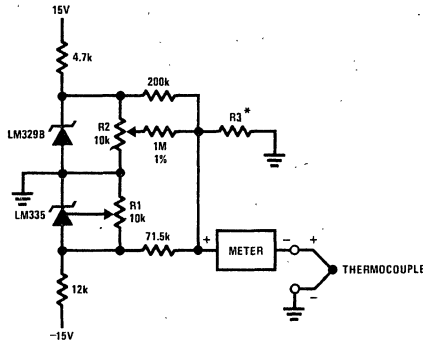
* To calibrate adjust R2 for 2.554V across LM336.
Adjust R1 for correct output.



Typical Applications (Continued)

THERMOCOUPLE COLD JUNCTION COMPENSATION

Compensation for Grounded Thermocouple



*Select R3 for proper thermocouple type

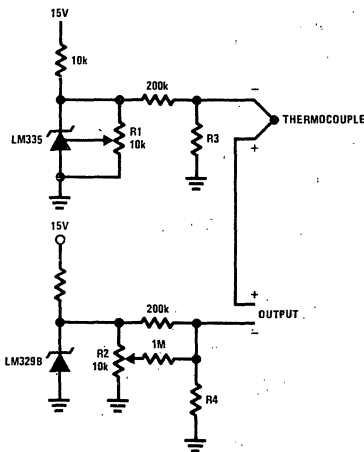
| THERMO-COUPLE | R3 | SEEBECK COEFFICIENT |
|---------------|-------|---------------------|
| J | 377Ω | 52.3 μV/°C |
| T | 308Ω | 42.8 μV/°C |
| K | 293Ω | 40.8 μV/°C |
| S | 45.8Ω | 6.4 μV/°C |

Adjustments: Compensates for both sensor and resistor tolerances

1. Short LM329B
2. Adjust R1 for Seebeck Coefficient times ambient temperature (in degrees K) across R3
3. Short LM335 and adjust R2 for voltage across R3 corresponding to thermocouple type

| | | | |
|---|----------|---|----------|
| J | 14.32 mV | K | 11.17 mV |
| T | 11.79 mV | S | 1.768 mV |

Single Power Supply Cold Junction Compensation



*Select R3 and R4 for thermocouple type

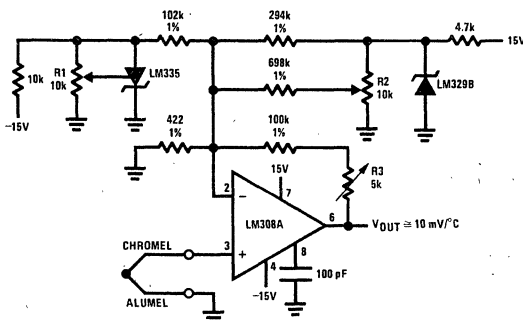
| THERMO-COUPLE | R3 | R4 | SEEBECK COEFFICIENT |
|---------------|-------|-------|---------------------|
| J | 1.05K | 385Ω | 52.3 μV/°C |
| T | 856Ω | 315Ω | 42.8 μV/°C |
| K | 816Ω | 300Ω | 40.8 μV/°C |
| S | 128Ω | 46.3Ω | 6.4 μV/°C |

Adjustments:

1. Adjust R1 for the voltage across R3 equal to the Seebeck Coefficient times ambient temperature in degrees Kelvin.
2. Adjust R2 for voltage across R4 corresponding to thermocouple

| | | | |
|---|----------|---|----------|
| J | 14.32 mV | K | 11.17 mV |
| T | 11.79 mV | S | 1.768 mV |

Centigrade Calibrated Thermocouple Thermometer



Terminate thermocouple reference junction in close proximity to LM335.

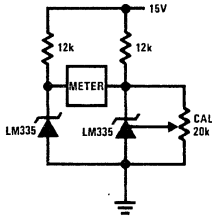
Adjustments:

1. Apply signal in place of thermocouple and adjust R3 for a gain of 245.7.
2. Short non-inverting input of LM308A and output of LM329B to ground.
3. Adjust R1 so that $V_{OUT} = 2.982V @ 25^{\circ}C$.
4. Remove short across LM329B and adjust R2 so that $V_{OUT} = 246 mV @ 25^{\circ}C$.
5. Remove short across thermocouple.

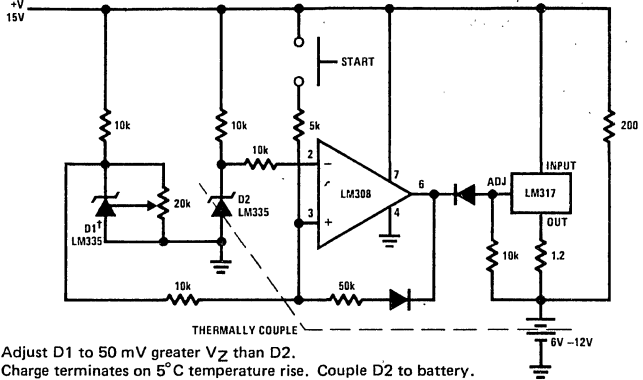
Typical Applications (Continued)

LM135/LM235/LM335, LM135A/LM235A/LM335A

Differential Temperature Sensor

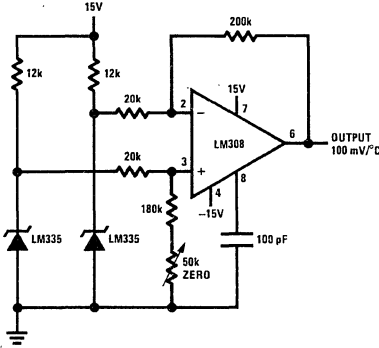


Fast Charger for Nickel-Cadmium Batteries

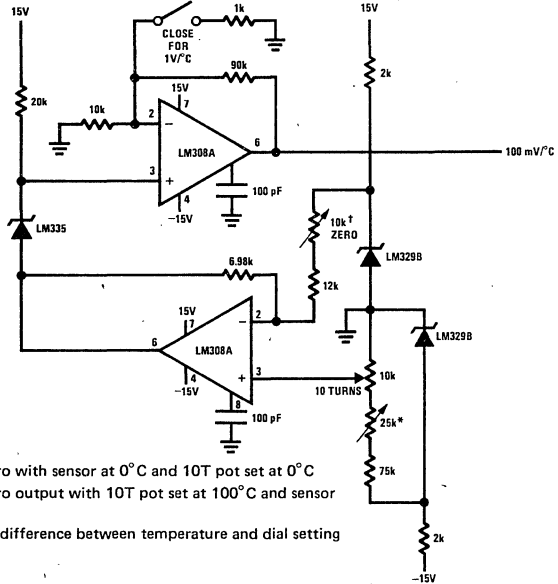


† Adjust D1 to 50 mV greater V_Z than D2.
Charge terminates on 5°C temperature rise. Couple D2 to battery.

Differential Temperature Sensor

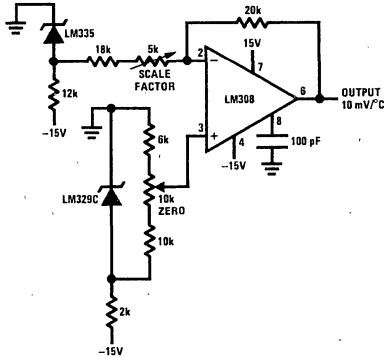


Variable Offset Thermometer †

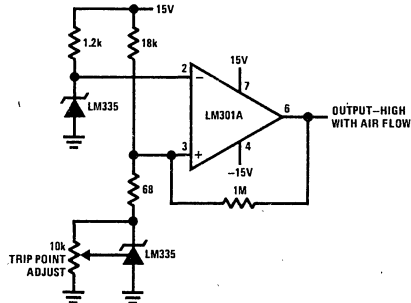


† Adjust for zero with sensor at 0°C and 10T pot set at 0°C
* Adjust for zero output with 10T pot set at 100°C and sensor at 100°C
‡ Output reads difference between temperature and dial setting of 10T pot

Ground Referred Centigrade Thermometer



Air Flow Detector*



* Self heating is used to detect air flow



Definition of Terms

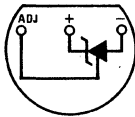
Operating Output Voltage: The voltage appearing across the positive and negative terminals of the device at specified conditions of operating temperature and current.

Uncalibrated Temperature Error: The error between the operating output voltage at $10 \text{ mV}/^\circ\text{K}$ and case temperature at specified conditions of current and case temperature.

Calibrated Temperature Error: The error between operating output voltage and case temperature at $10 \text{ mV}/^\circ\text{K}$ over a temperature range at a specified operating current with the 25°C error adjusted to zero.

Connection Diagrams

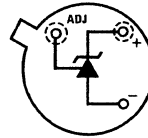
TO-92
Plastic Package



BOTTOM VIEW

Order Number LM235Z, LM335Z
or LM335AZ
See NS Package Z03A

TO-46
Metal Can Package*



BOTTOM VIEW

* Case is connected to negative pin

Order Number LM135H, LM235H,
LM335H, LM135AH, LM235AH
or LM335AH
See NS Package H03H

LM555/LM555C Timer

General Description

The LM555 is a highly stable device for generating accurate time delays or oscillation. Additional terminals are provided for triggering or resetting if desired. In the time delay mode of operation, the time is precisely controlled by one external resistor and capacitor. For astable operation as an oscillator, the free running frequency and duty cycle are accurately controlled with two external resistors and one capacitor. The circuit may be triggered and reset on falling waveforms, and the output circuit can source or sink up to 200 mA or drive TTL circuits.

- Adjustable duty cycle
- Output can source or sink 200 mA
- Output and supply TTL compatible
- Temperature stability better than 0.005% per °C
- Normally on and normally off output

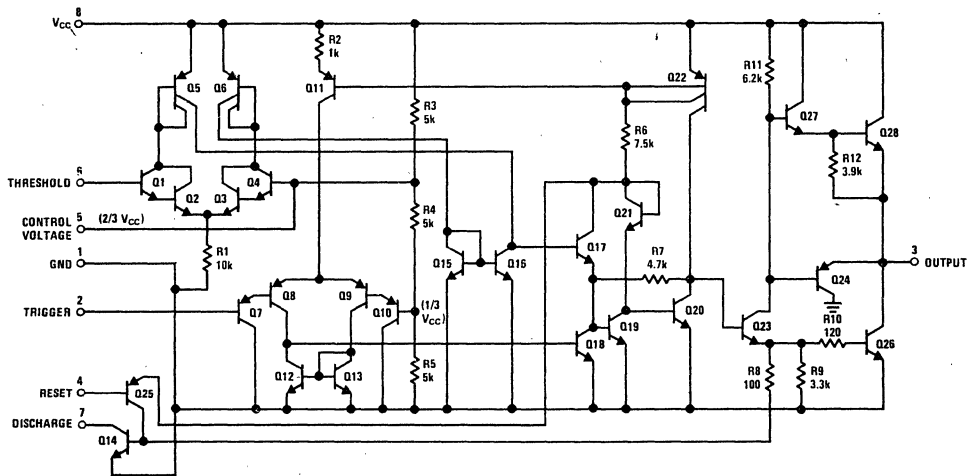
Applications

- Precision timing
- Pulse generation
- Sequential timing
- Time delay generation
- Pulse width modulation
- Pulse position modulation
- Linear ramp generator

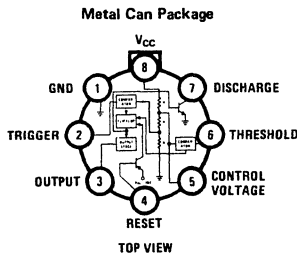
Features

- Direct replacement for SE555/NE555
- Timing from microseconds through hours
- Operates in both astable and monostable modes

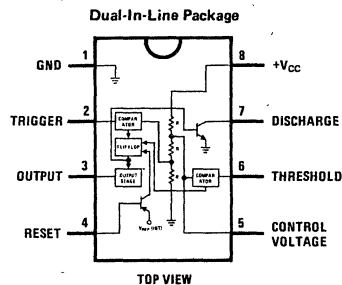
Schematic Diagram



Connection Diagrams



Order Number LM555H, LM555CH
See NS Package H08C



Order Number LM555CN
See NS Package N08B
Order Number LM555J or LM555CJ
See NS Package J08A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | +18V |
| Power Dissipation (Note 1) | 600 mW |
| Operating Temperature Ranges | |
| LM555C | 0°C to +70°C |
| LM555 | -55°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (T_A = 25°C, V_{CC} = +5V to +15V, unless otherwise specified)

| PARAMETER | CONDITIONS | LIMITS | | | | | | UNITS |
|----------------------------|---|--------|------|-------|--------|------|-------|-------------------|
| | | LM555 | | | LM555C | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage | | 4.5 | | 18 | 4.5 | | 16 | V |
| Supply Current | V _{CC} = 5V, R _L = ∞ | | 3 | 5 | | 3 | 6 | mA |
| | V _{CC} = 15V, R _L = ∞ (Low State) (Note 2) | | 10 | 12 | | 10 | 15 | mA |
| Timing Error, Monostable | | | | | | | | |
| Initial Accuracy | | | 0.5 | 2 | | 1 | | % |
| Drift with Temperature | R _A , R _B = 1k to 100 k, C = 0.1μF, (Note 3) | | 30 | | | 50 | | ppm/°C |
| Accuracy over Temperature | | | 1.5 | 3.0 | | 1.5 | | % |
| Drift with Supply | | | 0.05 | 0.2 | | 0.1 | | %/V |
| Timing Error, Astable | | | | | | | | |
| Initial Accuracy | | | 1.5 | 5 | | 2.25 | 7 | % |
| Drift with Temperature | | | 90 | | | 150 | | ppm/°C |
| Accuracy over Temperature | | | 2.5 | | | 3.0 | | % |
| Drift with Supply | | | 0.15 | 0.2 | | 0.30 | 0.5 | %/V |
| Threshold Voltage | | | | 0.667 | | | 0.667 | x V _{CC} |
| Trigger Voltage | V _{CC} = 15V | 4.8 | 5 | 5.2 | | 5 | | V |
| | V _{CC} = 5V | 1.45 | 1.67 | 1.9 | | 1.67 | | V |
| Trigger Current | | | 0.01 | 0.5 | | 0.5 | 0.9 | μA |
| Reset Voltage | | 0.4 | 0.5 | 1 | 0.4 | 0.5 | 1 | V |
| Reset Current | | | 0.1 | 0.4 | | 0.1 | 0.4 | mA |
| Threshold Current | (Note 4) | | 0.1 | 0.25 | | 0.1 | 0.25 | μA |
| Control Voltage Level | V _{CC} = 15V | 9.6 | 10 | 10.4 | 9 | 10 | 11 | V |
| | V _{CC} = 5V | 2.9 | 3.33 | 3.8 | 2.6 | 3.33 | 4 | V |
| Pin 7 Leakage Output High | | | 1 | 100 | | 1 | 100 | nA |
| Pin 7 Sat (Note 5) | | | | | | | | |
| Output Low | V _{CC} = 15V, I ₇ = 15 mA | | 150 | | | 180 | | mV |
| Output Low | V _{CC} = 4.5V, I ₇ = 4.5 mA | | 70 | 100 | | 80 | 200 | mV |
| Output Voltage Drop (Low) | V _{CC} = 15V | | | | | | | |
| | I _{SINK} = 10 mA | | 0.1 | 0.15 | | 0.1 | 0.25 | V |
| | I _{SINK} = 50 mA | | 0.4 | 0.5 | | 0.4 | 0.75 | V |
| | I _{SINK} = 100 mA | | 2 | 2.2 | | 2 | 2.5 | V |
| | I _{SINK} = 200 mA | | 2.5 | | | 2.5 | | V |
| | V _{CC} = 5V | | | | | | | |
| | I _{SINK} = 8 mA | | 0.1 | 0.25 | | | | V |
| | I _{SINK} = 5 mA | | | | | 0.25 | 0.35 | V |
| Output Voltage Drop (High) | I _{SOURCE} = 200 mA, V _{CC} = 15V | | 12.5 | | | 12.5 | | V |
| | I _{SOURCE} = 100 mA, V _{CC} = 15V | | 13.3 | | | 13.3 | | V |
| | V _{CC} = 5V | 3 | 3.3 | | 2.75 | 3.3 | | V |
| Rise Time of Output | | | 100 | | | 100 | | ns |
| Fall Time of Output | | | 100 | | | 100 | | ns |

Note 1: For operating at elevated temperatures the device must be derated based on a +150°C maximum junction temperature and a thermal resistance of +45°C/W junction to case for TO-5 and +150°C/W junction to ambient for both packages.

Note 2: Supply current when output high typically 1 mA less at V_{CC} = 5V.

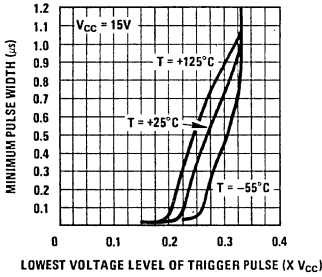
Note 3: Tested at V_{CC} = 5V and V_{CC} = 15V.

Note 4: This will determine the maximum value of R_A + R_B for 15V operation. The maximum total (R_A + R_B) is 20 MΩ.

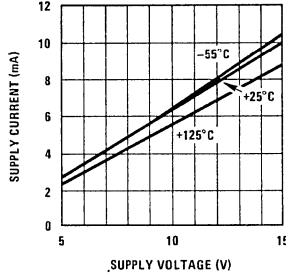
Note 5: No protection against excessive pin 7 current is necessary providing the package dissipation rating will not be exceeded.

Typical Performance Characteristics

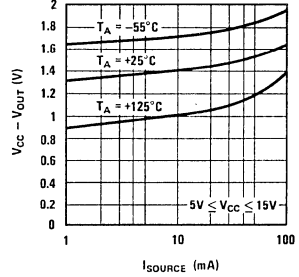
Minimum Pulse Width Required for Triggering



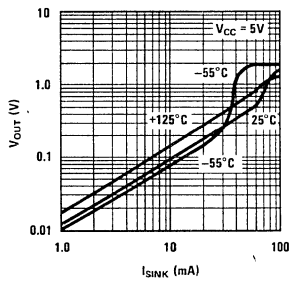
Supply Current vs Supply Voltage



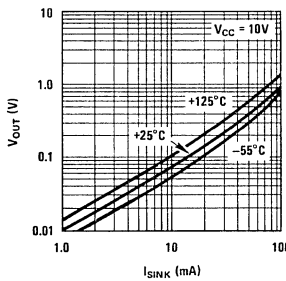
High Output Voltage vs Output Source Current



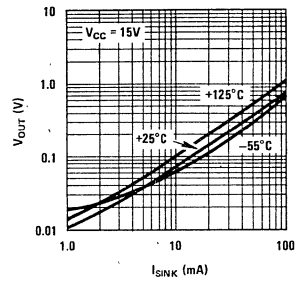
Low Output Voltage vs Output Sink Current



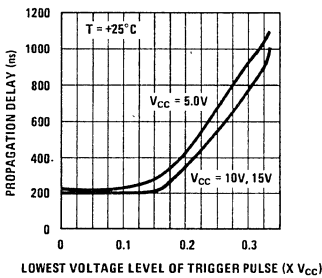
Low Output Voltage vs Output Sink Current



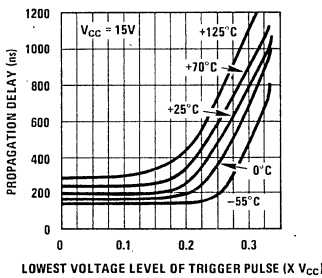
Low Output Voltage vs Output Sink Current



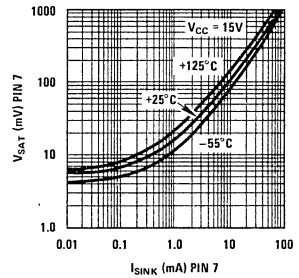
Output Propagation Delay vs Voltage Level of Trigger Pulse



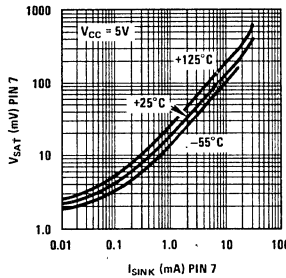
Output Propagation Delay vs Voltage Level of Trigger Pulse



Discharge Transistor (Pin 7) Voltage vs Sink Current



Discharge Transistor (Pin 7) Voltage vs Sink Current



Applications Information

MONOSTABLE OPERATION

In this mode of operation, the timer functions as a one-shot (Figure 1). The external capacitor is initially held discharged by a transistor inside the timer. Upon application of a negative trigger pulse of less than $1/3 V_{CC}$ to pin 2, the flip-flop is set which both releases the short circuit across the capacitor and drives the output high.

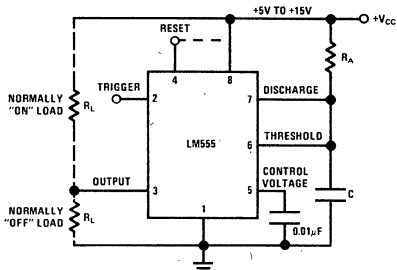


FIGURE 1. Monostable

The voltage across the capacitor then increases exponentially for a period of $t = 1.1 R_A C$, at the end of which time the voltage equals $2/3 V_{CC}$. The comparator then resets the flip-flop which in turn discharges the capacitor and drives the output to its low state. Figure 2 shows the waveforms generated in this mode of operation. Since the charge and the threshold level of the comparator are both directly proportional to supply voltage, the timing interval is independent of supply.

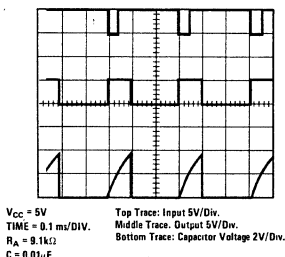


FIGURE 2. Monostable Waveforms

During the timing cycle when the output is high, the further application of a trigger pulse will not effect the circuit. However the circuit can be reset during this time by the application of a negative pulse to the reset terminal (pin 4). The output will then remain in the low state until a trigger pulse is again applied.

When the reset function is not in use, it is recommended that it be connected to V_{CC} to avoid any possibility of false triggering.

Figure 3 is a nomograph for easy determination of R, C values for various time delays.

NOTE: In monostable operation, the trigger should be driven high before the end of timing cycle.

ASTABLE OPERATION

If the circuit is connected as shown in Figure 4 (pins 2 and 6 connected) it will trigger itself and free run as a

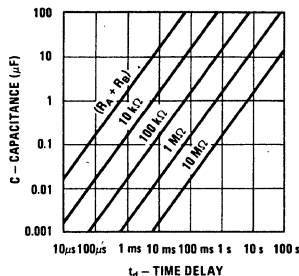


FIGURE 3. Time Delay

multivibrator. The external capacitor charges through $R_A + R_B$ and discharges through R_B . Thus the duty cycle may be precisely set by the ratio of these two resistors.

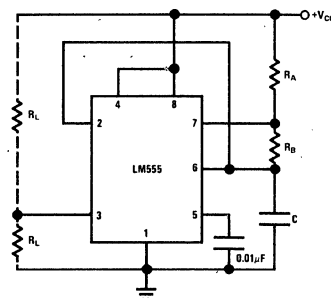


FIGURE 4. Astable

In this mode of operation, the capacitor charges and discharges between $1/3 V_{CC}$ and $2/3 V_{CC}$. As in the triggered mode, the charge and discharge times, and therefore the frequency are independent of the supply voltage.

Figure 5 shows the waveforms generated in this mode of operation.

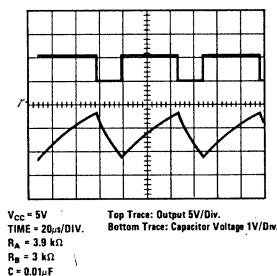


FIGURE 5. Astable Waveforms

The charge time (output high) is given by:
 $t_1 = 0.693 (R_A + R_B) C$

And the discharge time (output low) by:
 $t_2 = 0.693 (R_B) C$

Thus the total period is:
 $T = t_1 + t_2 = 0.693 (R_A + 2R_B) C$

Applications Information (Continued)

The frequency of oscillation is:

$$f = \frac{1}{T} = \frac{1.44}{(R_A + 2R_B)C}$$

Figure 6 may be used for quick determination of these RC values.

The duty cycle is:
$$D = \frac{R_B}{R_A + 2R_B}$$

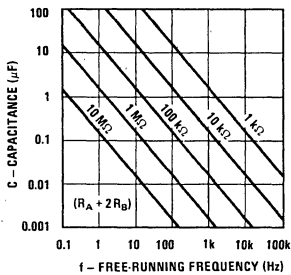
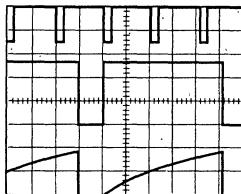


FIGURE 6. Free Running Frequency

FREQUENCY DIVIDER

The monostable circuit of Figure 1 can be used as a frequency divider by adjusting the length of the timing cycle. Figure 7 shows the waveforms generated in a divide by three circuit.



V_{CC} = 5V
TIME = 20µs/DIV.
R_A = 9.1 kΩ
C = 0.01µF

FIGURE 7. Frequency Divider

PULSE WIDTH MODULATOR

When the timer is connected in the monostable mode and triggered with a continuous pulse train, the output pulse width can be modulated by a signal applied to pin 5. Figure 8 shows the circuit, and in Figure 9 are some waveform examples.

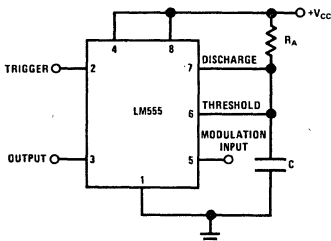
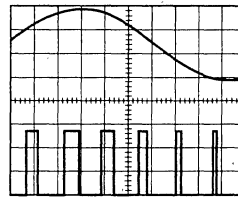


FIGURE 8. Pulse Width Modulator



V_{CC} = 5V
TIME = 0.2 ms/DIV.
R_A = 9.1 kΩ
C = 0.01µF

FIGURE 9. Pulse Width Modulator

PULSE POSITION MODULATOR

This application uses the timer connected for astable operation, as in Figure 10, with a modulating signal again applied to the control voltage terminal. The pulse position varies with the modulating signal, since the threshold voltage and hence the time delay is varied. Figure 11 shows the waveforms generated for a triangle wave modulation signal.

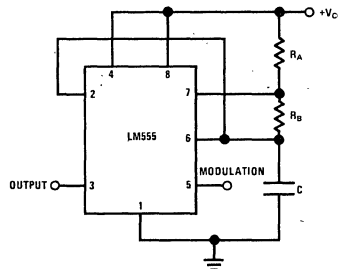
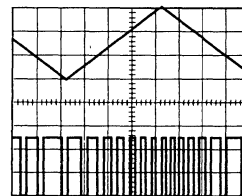


FIGURE 10. Pulse Position Modulator



V_{CC} = 5V
TIME = 0.1 ms/DIV.
R_A = 3.9 kΩ
R_B = 3 kΩ
C = 0.01µF

FIGURE 11. Pulse Position Modulator

LINEAR RAMP

When the pullup resistor, R_A, in the monostable circuit is replaced by a constant current source, a linear ramp is

Applications Information (Continued)

generated. Figure 12 shows a circuit configuration that will perform this function.

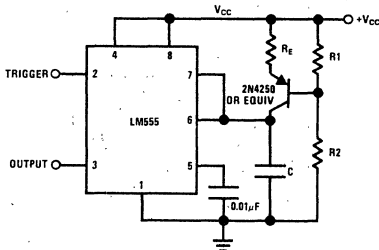


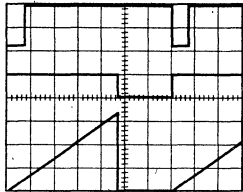
FIGURE 12.

Figure 13 shows waveforms generated by the linear ramp.

The time interval is given by:

$$T = \frac{2/3 V_{CC} R_E (R_1 + R_2) C}{R_1 V_{CC} - V_{BE} (R_1 + R_2)}$$

$V_{BE} \approx 0.6V$



$V_{CC} = 5V$
 TIME = 20µs/DIV.
 $R_1 = 47 k\Omega$
 $R_2 = 100 k\Omega$
 $R_E = 2.7 k\Omega$
 $C = 0.01\mu F$

FIGURE 13. Linear Ramp

50% DUTY CYCLE OSCILLATOR

For a 50% duty cycle, the resistors R_A and R_B may be connected as in Figure 14. The time period for the out-

put high is the same as previous, $t_1 = 0.693 R_A C$. For the output low it is $t_2 =$

$$[(R_A R_B)/(R_A + R_B)] C \ln \left[\frac{R_B - 2R_A}{2R_B - R_A} \right]$$

Thus the frequency of oscillation is $f = \frac{1}{t_1 + t_2}$

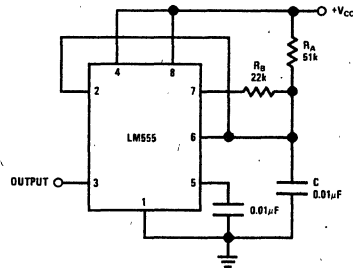


FIGURE 14. 50% Duty Cycle Oscillator

Note that this circuit will not oscillate if R_B is greater than $1/2 R_A$ because the junction of R_A and R_B cannot bring pin 2 down to $1/3 V_{CC}$ and trigger the lower comparator.

ADDITIONAL INFORMATION

Adequate power supply bypassing is necessary to protect associated circuitry. Minimum recommended is $0.1\mu F$ in parallel with $1\mu F$ electrolytic.

Lower comparator storage time can be as long as $10\mu s$ when pin 2 is driven fully to ground for triggering. This limits the monostable pulse width to $10\mu s$ minimum.

Delay time reset to output is $0.47\mu s$ typical. Minimum reset pulse width must be $0.3\mu s$, typical.

Pin 7 current switches within 30 ns of the output (pin 3) voltage.

LM556/LM556C Dual Timer

General Description

The LM556 Dual timing circuit is a highly stable controller capable of producing accurate time delays or oscillation. The 556 is a dual 555. Timing is provided by an external resistor and capacitor for each timing function. The two timers operate independently of each other sharing only V_{CC} and ground. The circuits may be triggered and reset on falling waveforms. The output structures may sink or source 200 mA.

Features

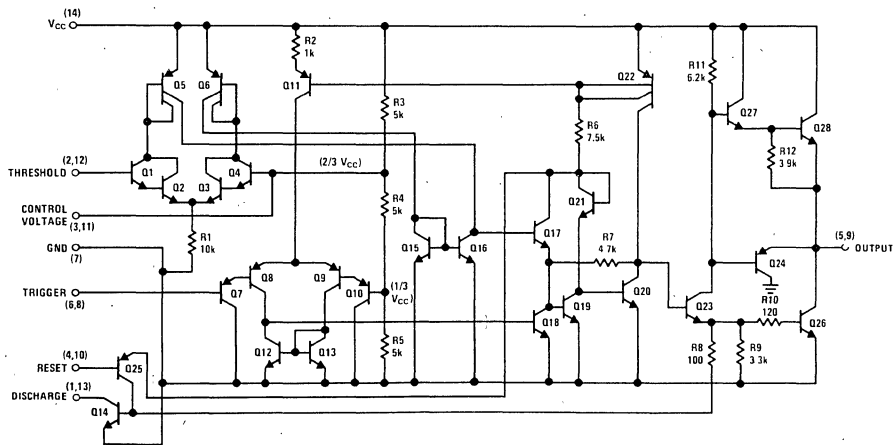
- Direct replacement for SE556/NE556
- Timing from microseconds through hours
- Operates in both astable and monostable modes
- Replaces two 555 timers

- Adjustable duty cycle
- Output can source or sink 200 mA
- Output and supply TTL compatible
- Temperature stability better than 0.005% per °C
- Normally on and normally off output

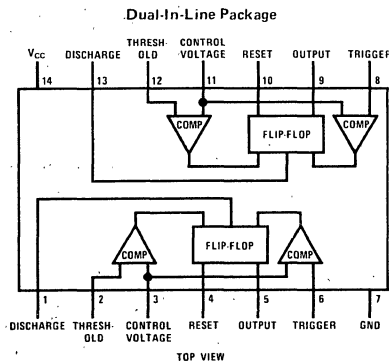
Applications

- Precision timing
- Pulse generation
- Sequential timing
- Time delay generation
- Pulse width modulation
- Pulse position modulation
- Linear ramp generator

Schematic Diagram



Connection Diagram



Order Number LM556CN
See NS Package N14A

Order Number LM556J or LM556CJ
See NS Package J14A



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | +18V |
| Power Dissipation (Note 1) | 600 mW |
| Operating Temperature Ranges | |
| LM556C | 0°C to +70°C |
| LM556 | -55°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (T_A = 25°C, V_{CC} = +5V to +15V, unless otherwise specified)

| PARAMETER | CONDITIONS | LM556 | | | LM556C | | | UNITS |
|-------------------------------|--|-------|------|------|--------|------|------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage | | 4.5 | | 18 | 4.5 | | 16 | V |
| Supply Current | V _{CC} = 5V, R _L = ∞ | | 3 | 5 | | 3 | 6 | mA |
| (Each Timer Section) | V _{CC} = 15V, R _L = ∞ (Low State) (Note 2) | | 10 | 11 | | 10 | 14 | mA |
| Timing Error, Monostable | | | | | | | | |
| Initial Accuracy | | | 0.5 | 1.5 | | 0.75 | 5.0 | % |
| Drift With Temperature | R _A , R _B = 1k to 100k, C = 0.1μF, (Note 3) | | 30 | | | 50 | | ppm/°C |
| Accuracy Over Temperature | | | 1.5 | 5 | | 1.5 | | % |
| Drift with Supply | | | 0.05 | 0.2 | | 0.1 | 0.4 | %/V |
| Timing Error, Astable | | | | | | | | |
| Initial Accuracy | | | 1.5 | | | 2.25 | 7 | % |
| Drift With Temperature | | | 90 | | | 150 | | ppm/°C |
| Accuracy Over Temperature | | | 2.5 | | | 3.0 | | % |
| Drift With Supply | | | 0.15 | 0.2 | | 0.30 | | %/V |
| Trigger Voltage | V _{CC} = 15V | 4.8 | 5 | 5.2 | 4.5 | 5 | 0.5 | V |
| | V _{CC} = 5V | 1.45 | 1.67 | 1.9 | 1.25 | 1.67 | 2.0 | V |
| Trigger Current | | | 0.1 | 0.5 | | 0.2 | 1.0 | μA |
| Reset Voltage | (Note 4) | 0.4 | 0.5 | 1 | 0.4 | 0.5 | 1 | V |
| Reset Current | | | 0.1 | 0.4 | | 0.1 | 0.6 | mA |
| Threshold Current | (Note 5) | | 0.03 | 0.1 | | 0.03 | 0.1 | μA |
| Control Voltage Level And | V _{CC} = 15V | 9.6 | 10 | 10.4 | 9 | 10 | 11 | V |
| Threshold Voltage | V _{CC} = 5V | 2.9 | 3.33 | 3.8 | 2.6 | 3.33 | 4 | V |
| Pin 1, 13 Leakage Output High | | | .1 | 100 | | 1 | 100 | nA |
| Pin 1, 13 Sat | (Note 6) | | | | | | | |
| Output Low | V _{CC} = 15V, I = 15 mA | | 150 | 240 | | 180 | 300 | mV |
| Output Low | V _{CC} = 4.5V, I = 4.5 mA | | 70 | 100 | | 80 | 200 | mV |
| Output Voltage Drop (Low) | V _{CC} = 15V | | | | | | | |
| | I _{SINK} = 10 mA | | 0.1 | 0.15 | | 0.1 | 0.25 | V |
| | I _{SINK} = 50 mA | | 0.4 | 0.5 | | 0.4 | 0.75 | V |
| | I _{SINK} = 100 mA | | 2 | 2.25 | | 2 | 2.75 | V |
| | I _{SINK} = 200 mA | | 2.5 | | | 2.5 | | V |
| | V _{CC} = 5V | | | | | | | |
| | I _{SINK} = 8 mA | | 0.1 | 0.25 | | | | V |
| | I _{SINK} = 5 mA | | | | | 0.25 | 0.35 | V |
| Output Voltage Drop (High) | I _{SOURCE} = 200 mA, V _{CC} = 15V | | 12.5 | | | 12.5 | | V |
| | I _{SOURCE} = 100 mA, V _{CC} = 15V | 13 | 13.3 | | 12.75 | 13.3 | | V |
| | V _{CC} = 5V | 3 | 3.3 | | 2.75 | 3.3 | | V |
| Rise Time of Output | | | 100 | | | 100 | | ns |
| Fall Time of Output | | | 100 | | | 100 | | ns |
| Matching Characteristics | (Note 7) | | | | | | | |
| Initial Timing Accuracy | | | 0.05 | 0.2 | | 0.1 | 2.0 | % |
| Timing Drift With Temperature | | | ±10 | | | ±10 | | ppm/°C |
| Drift With Supply Voltage | | | 0.1 | 0.2 | | 0.2 | 0.5 | %/V |

Note 1: For operating at elevated temperatures the device must be derated based on a +150°C maximum junction temperature and a thermal resistance of +150°C/W junction to ambient for both packages.

Note 2: Supply current when output high typically 1 mA less at V_{CC} = 5V.

Note 3: Tested at V_{CC} = 5V and V_{CC} = 15V.

Note 4: As reset voltage lowers, timing is inhibited and then the output goes low.

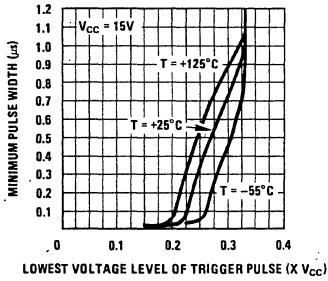
Note 5: This will determine the maximum value of R_A + R_B for 15V operation. The maximum total (R_A + R_B) is 20 MΩ.

Note 6: No protection against excessive pin 1, 13 current is necessary providing the package dissipation rating will not be exceeded.

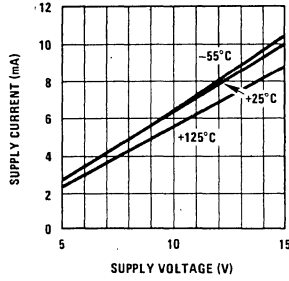
Note 7: Matching characteristics refer to the difference between performance characteristics of each timer section.

Typical Performance Characteristics

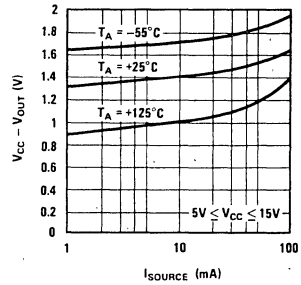
Minimum Pulse Width Required for Triggering



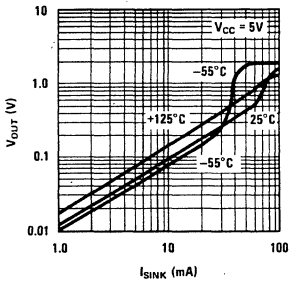
Supply Current vs. Supply Voltage (Each Section)



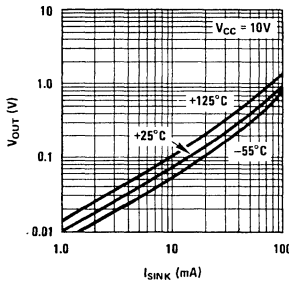
High Output Voltage vs. Output Source Current



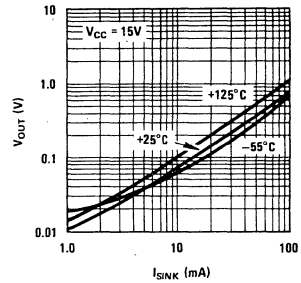
Low Output Voltage vs. Output Sink Current



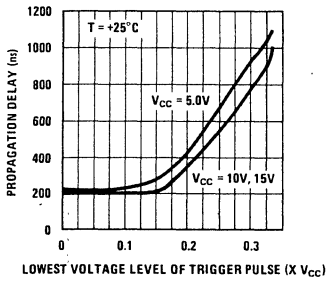
Low Output Voltage vs. Output Sink Current



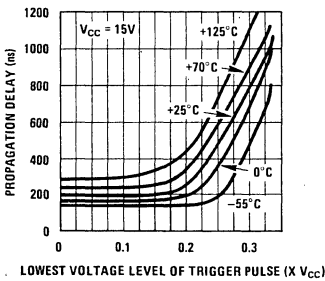
Low Output Voltage vs. Output Sink Current



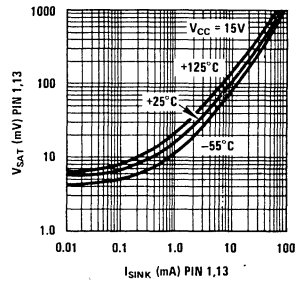
Output Propagation Delay vs. Voltage Level of Trigger Pulse



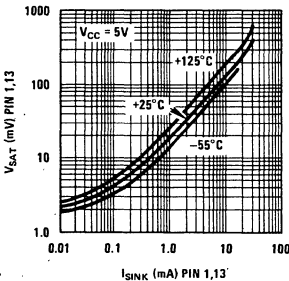
Output Propagation Delay vs. Voltage Level of Trigger Pulse



Discharge Transistor (Pin 1,13) Voltage vs. Sink Current



Discharge Transistor (Pin 1,13) Voltage vs. Sink Current





LM565/LM565C Phase Locked Loop

General Description

The LM565 and LM565C are general purpose phase locked loops containing a stable, highly linear voltage controlled oscillator for low distortion FM demodulation, and a double balanced phase detector with good carrier suppression. The VCO frequency is set with an external resistor and capacitor, and a tuning range of 10:1 can be obtained with the same capacitor. The characteristics of the closed loop system—bandwidth, response speed, capture and pull in range—may be adjusted over a wide range with an external resistor and capacitor. The loop may be broken between the VCO and the phase detector for insertion of a digital frequency divider to obtain frequency multiplication.

The LM565H is specified for operation over the -55°C to $+125^{\circ}\text{C}$ military temperature range. The LM565CH and LM565CN are specified for operation over the 0°C to $+70^{\circ}\text{C}$ temperature range.

Features

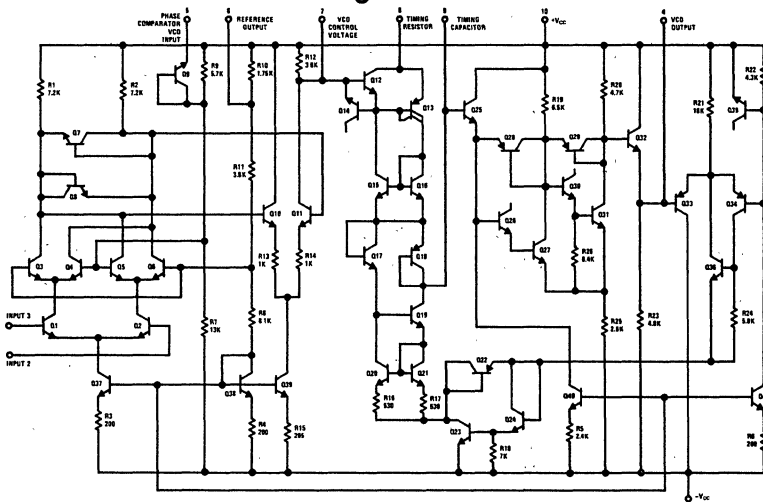
- 200 ppm/ $^{\circ}\text{C}$ frequency stability of the VCO

- Power supply range of ± 5 to ± 12 volts with 100 ppm/% typical
- 0.2% linearity of demodulated output
- Linear triangle wave with in phase zero crossings available
- TTL and DTL compatible phase detector input and square wave output
- Adjustable hold in range from $\pm 1\%$ to $> \pm 60\%$.

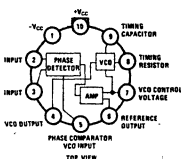
Applications

- Data and tape synchronization
- Modems
- FSK demodulation
- FM demodulation
- Frequency synthesizer
- Tone decoding
- Frequency multiplication and division
- SCA demodulators
- Telemetry receivers
- Signal regeneration
- Coherent demodulators.

Schematic and Connection Diagrams

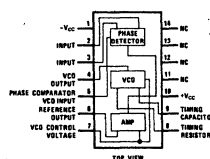


Metal Can Package



Order Number LM565H or LM565CH
See NS Package H10C

Dual-In-Line Package



Order Number LM565CN
See NS Package N14A

Absolute Maximum Ratings

| | |
|--------------------------------------|-----------------|
| Supply Voltage | ±12V |
| Power Dissipation (Note 1) | 300 mW |
| Differential Input Voltage | ±1V |
| Operating Temperature Range LM565H | -55°C to +125°C |
| LM565CH, LM565CN | 0°C to 70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

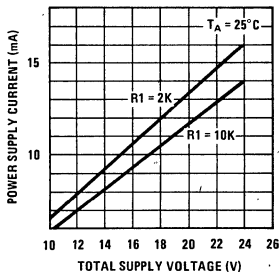
Electrical Characteristics (AC Test Circuit, $T_A = 25^\circ\text{C}$, $V_C = \pm 6\text{V}$)

| PARAMETER | CONDITIONS | LM565 | | | LM565C | | | UNITS |
|--|-------------------------------------|-------|------|------|--------|------|------|------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Power Supply Current | | | 8.0 | 12.5 | | 8.0 | 12.5 | mA |
| Input Impedance (Pins 2, 3) | $-4\text{V} < V_2, V_3 < 0\text{V}$ | 7 | 10 | | | 5 | | $k\Omega$ |
| VCO Maximum Operating Frequency | $C_o = 2.7 \text{ pF}$ | 300 | 500 | | 250 | 500 | | kHz |
| Operating Frequency Temperature Coefficient | | | -100 | 300 | | -200 | 500 | ppm/°C |
| Frequency Drift with Supply Voltage | | | 0.01 | 0.1 | | 0.05 | 0.2 | %/V |
| Triangle Wave Output Voltage | | 2 | 2.4 | 3 | 2 | 2.4 | 3 | V_{P-P} |
| Triangle Wave Output Linearity | | | 0.2 | 0.75 | | 0.5 | 1 | % |
| Square Wave Output Level | | 4.7 | 5.4 | | 4.7 | 5.4 | | V_{P-P} |
| Output Impedance (Pin 4) | | | 5 | | | 5 | | $k\Omega$ |
| Square Wave Duty Cycle | | 45 | 50 | 55 | 40 | 50 | 60 | % |
| Square Wave Rise Time | | | 20 | 100 | | 20 | | ns |
| Square Wave Fall Time | | | 50 | 200 | | 50 | | ns |
| Output Current Sink (Pin 4) | | 0.6 | 1 | | 0.6 | 1 | | mA |
| VCO Sensitivity | $f_o = 10 \text{ kHz}$ | 6400 | 6600 | 6800 | 6000 | 6600 | 7200 | Hz/V |
| Demodulated Output Voltage (Pin 7) | ±10% Frequency Deviation | 250 | 300 | 350 | 200 | 300 | 400 | mV_{P-P} |
| Total Harmonic Distortion | ±10% Frequency Deviation | | 0.2 | 0.75 | | 0.2 | 1.5 | % |
| Output Impedance (Pin 7) | | | 3.5 | | | 3.5 | | $k\Omega$ |
| DC Level (Pin 7) | | 4.25 | 4.5 | 4.75 | 4.0 | 4.5 | 5.0 | V |
| Output Offset Voltage $ V_7 - V_6 $ | | | 30 | 100 | | 50 | 200 | mV |
| Temperature Drift of $ V_7 - V_6 $ | | | 500 | | | 500 | | $\mu\text{V}/^\circ\text{C}$ |
| AM Rejection | | 30 | 40 | | | 40 | | dB |
| Phase Detector Sensitivity K_D | | 0.6 | .68 | 0.9 | 0.55 | .68 | 0.95 | V/radian |

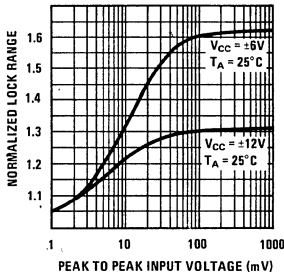
Note 1: The maximum junction temperature of the LM565 is 150°C, while that of the LM565C and LM565CN is 100°C. For operation at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W junction to ambient or 45°C/W junction to case. Thermal resistance of the dual-in-line package is 100°C/W.

Typical Performance Characteristics

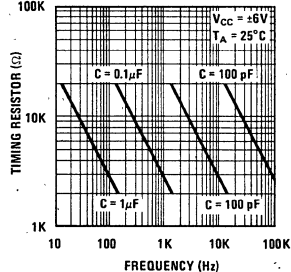
Power Supply Current as a Function of Supply Voltage



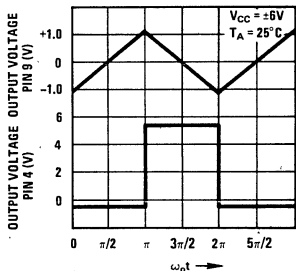
Lock Range as a Function of Input Voltage



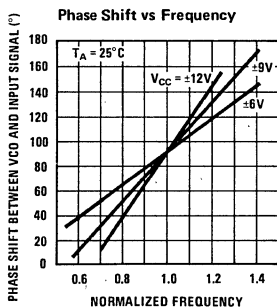
VCO Frequency



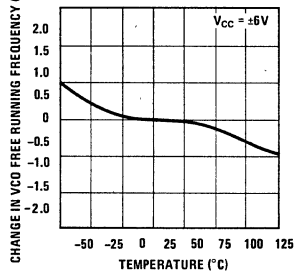
Oscillator Output Waveforms



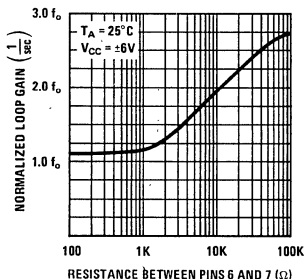
Phase Shift vs Frequency



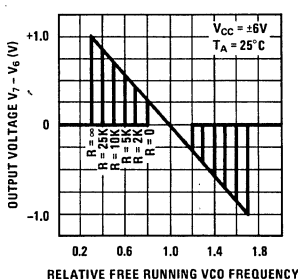
VCO Frequency as a Function of Temperature



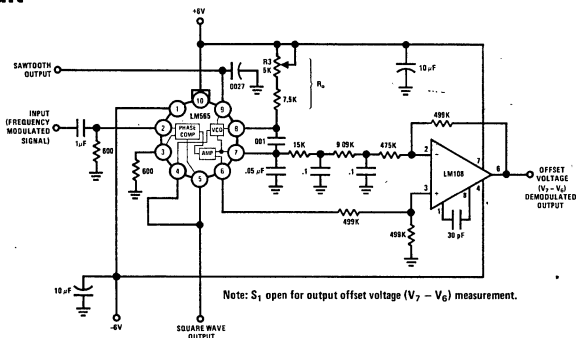
Loop Gain vs Load Resistance



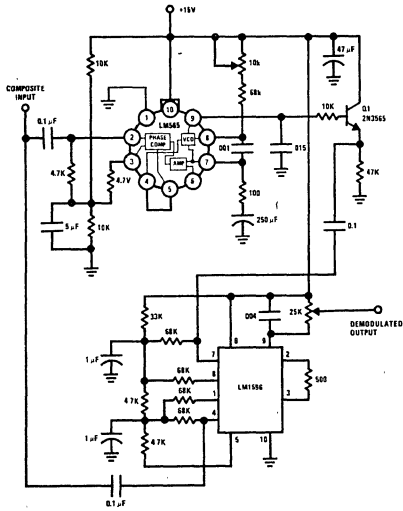
Hold in Range as a Function of R6-7



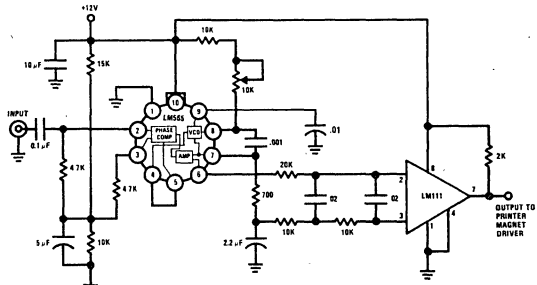
AC Test Circuit



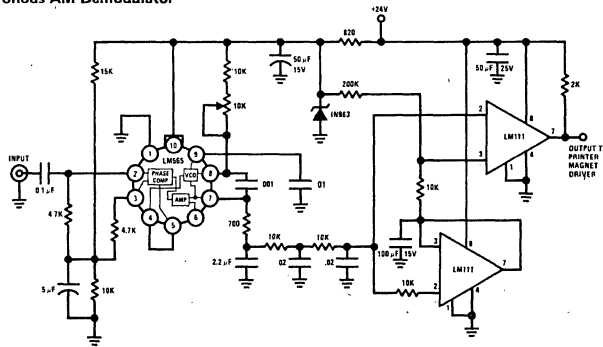
Typical Applications



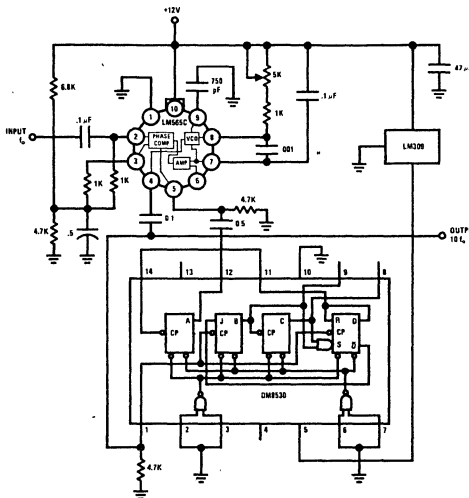
2400 Hz Synchronous AM Demodulator



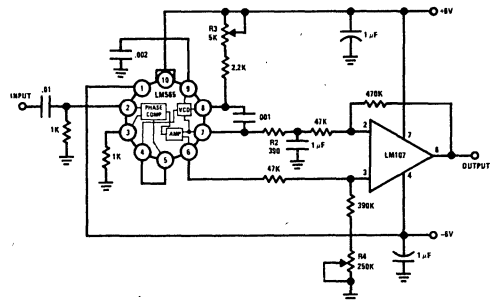
FSK Demodulator (2025-2225 cps)



FSK Demodulator with DC Restoration.



Frequency Multiplier (x10)



IRIG Channel 13 Demodulator

Applications Information

In designing with phase locked loops such as the LM565, the important parameters of interest are:

FREE RUNNING FREQUENCY

$$f_o \cong \frac{1}{3.7 R_o C_o}$$

LOOP GAIN: relates the amount of phase change between the input signal and the VCO signal for a shift in input signal frequency (assuming the loop remains in lock). In servo theory, this is called the "velocity error coefficient".

$$\text{Loop gain} = K_o K_D \left(\frac{1}{\text{sec}} \right)$$

$$K_o = \text{oscillator sensitivity} \left(\frac{\text{radians/sec}}{\text{volt}} \right)$$

$$K_D = \text{phase detector sensitivity} \left(\frac{\text{volts}}{\text{radian}} \right)$$

The loop gain of the LM565 is dependent on supply voltage, and may be found from:

$$K_o K_D = \frac{33.6 f_o}{V_c}$$

$$f_o = \text{VCO frequency in Hz}$$

$$V_c = \text{total supply voltage to circuit.}$$

Loop gain may be reduced by connecting a resistor between pins 6 and 7; this reduces the load impedance on the output amplifier and hence the loop gain.

HOLD IN RANGE: the range of frequencies that the loop will remain in lock after initially being locked.

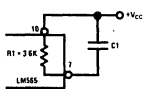
$$f_H = \pm \frac{8 f_o}{V_c}$$

$$f_o = \text{free running frequency of VCO}$$

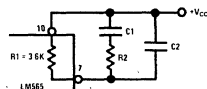
$$V_c = \text{total supply voltage to the circuit.}$$

THE LOOP FILTER

In almost all applications, it will be desirable to filter the signal at the output of the phase detector (pin 7) this filter may take one of two forms:



Simple Lag Filter



Lag-Lead Filter

A simple lag filter may be used for wide closed loop bandwidth applications such as modulation following where the frequency deviation of the carrier is fairly high (greater than 10%), or where wideband modulating signals must be followed.

The natural bandwidth of the closed loop response may be found from:

$$f_n = \frac{1}{2\pi} \sqrt{\frac{K_o K_D}{R_1 C_1}}$$

Associated with this is a damping factor:

$$\delta = \frac{1}{2} \sqrt{\frac{1}{R_1 C_1 K_o K_D}}$$

For narrow band applications where a narrow noise bandwidth is desired, such as applications involving tracking a slowly varying carrier, a lead lag filter should be used. In general, if $1/R_1 C_1 < K_o K_D$, the damping factor for the loop becomes quite small resulting in large overshoot and possible instability in the transient response of the loop. In this case, the natural frequency of the loop may be found from

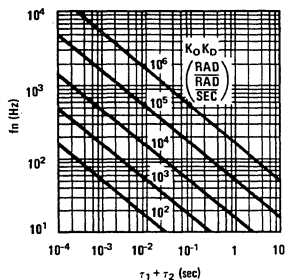
$$f_n = \frac{1}{2\pi} \sqrt{\frac{K_o K_D}{\tau_1 + \tau_2}}$$

$$\tau_1 + \tau_2 = (R_1 + R_2) C_1$$

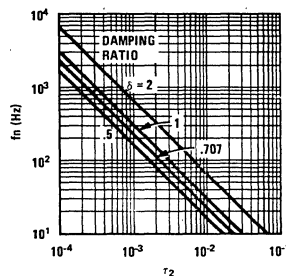
R_2 is selected to produce a desired damping factor δ , usually between 0.5 and 1.0. The damping factor is found from the approximation:

$$\delta \cong \pi \tau_2 f_n$$

These two equations are plotted for convenience.



Filter Time Constant vs Natural Frequency



Damping Time Constant vs Natural Frequency

Capacitor C_2 should be much smaller than C_1 since its function is to provide filtering of carrier. In general $C_2 \leq 0.1 C_1$.



LM566/LM566C Voltage Controlled Oscillator

General Description

The LM566/LM566C are general purpose voltage controlled oscillators which may be used to generate square and triangular waves, the frequency of which is a very linear function of a control voltage. The frequency is also a function of an external resistor and capacitor.

The LM566 is specified for operation over the -55°C to +125°C military temperature range. The LM566C is specified for operation over the 0°C to +70°C temperature range.

Features

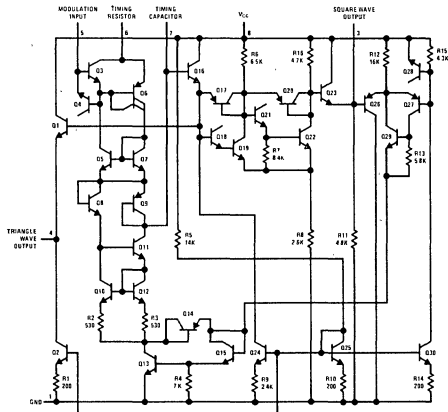
- Wide supply voltage range: 10 to 24 volts
- Very linear modulation characteristics

- High temperature stability
- Excellent supply voltage rejection
- 10 to 1 frequency range with fixed capacitor
- Frequency programmable by means of current, voltage, resistor or capacitor.

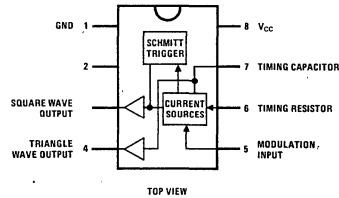
Applications

- FM modulation
- Signal generation
- Function generation
- Frequency shift keying
- Tone generation

Schematic and Connection Diagrams



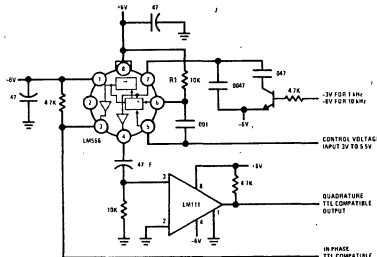
Dual-In-Line Package



Order Number LM566CN
See NS Package N08B

Typical Application

1 kHz and 10 kHz TTL Compatible Voltage Controlled Oscillator



Applications Information

The LM566 may be operated from either a single supply as shown in this test circuit, or from a split (\pm) power supply. When operating from a split supply, the square wave output (pin 4) is TTL compatible (2 mA current sink) with the addition of a 4.7 k Ω resistor from pin 3 to ground.

A .001 μ F capacitor is connected between pins 5 and 6 to prevent parasitic oscillations that may occur during VCO switching.

$$f_o = \frac{2(V^+ - V_G)}{R_1 C_1 V^+}$$

where

$$2K < R_1 < 20K$$

and V_G is voltage between pin 5 and pin 1

Absolute Maximum Ratings

| | |
|--------------------------------------|-----------------|
| Power Supply Voltage | 26V |
| Power Dissipation (Note 1) | 300 mW |
| Operating Temperature Range | -55°C to +125°C |
| LM566 | 0°C to 70°C |
| LM566C | 300°C |
| Lead Temperature (Soldering, 10 sec) | |

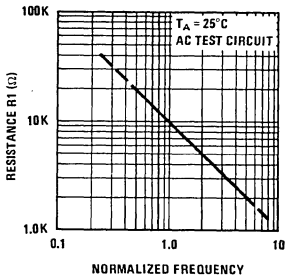
Electrical Characteristics $V_{CC} = 12V, T_A = 25^\circ C, AC$ Test Circuit

| PARAMETER | CONDITIONS | LM566 | | | LM566C | | | UNITS |
|--|--|--------------|-----|----------|--------------|-----|----------|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Maximum Operating Frequency | $R_0 = 2k$ $C_0 = 2.7 pF$ | 1 | | | 1 | | | MHz |
| Input Voltage Range Pin 5 | | $3/4 V_{CC}$ | | V_{CC} | $3/4 V_{CC}$ | | V_{CC} | |
| Average Temperature Coefficient of Operating Frequency | | 100 | | | 200 | | | ppm/°C |
| Supply Voltage Rejection | 10- 20V | 0.1 | | 1 | 0.1 | | 2 | %/V |
| Input Impedance Pin 5 | | 0.5 | 1 | | 0.5 | 1 | | MΩ |
| VCO Sensitivity | For Pin 5, From 8-10V, $f_0 = 10 kHz$ | 6.4 | 6.6 | 6.8 | 6.0 | 6.6 | 7.2 | kHz/V |
| FM Distortion | ±10% Deviation | 0.2 | | 0.75 | 0.2 | | 1.5 | % |
| Maximum Sweep Rate | | 800 | | | 500 | | | MHz |
| Sweep Range | | 10:1 | | | 10:1 | | | |
| Output Impedance | | | | | | | | |
| Pin 3 | | 50 | | | 50 | | | Ω |
| Pin 4 | | 50 | | | 50 | | | Ω |
| Square Wave Output Level | $R_{L1} = 10k$ | 5.0 | 5.4 | | 5.0 | 5.4 | | Vp-p |
| Triangle Wave Output Level | $R_{L2} = 10k$ | 2.0 | 2.4 | | 2.0 | 2.4 | | Vp-p |
| Square Wave Duty Cycle | | 45 | 50 | 55 | 40 | 50 | 60 | % |
| Square Wave Rise Time | | 20 | | | 20 | | | ns |
| Square Wave Fall Time | | 50 | | | 50 | | | ns |
| Triangle Wave Linearity | +1V Segment at $1/2 V_{CC}$ | 0.2 | | 0.75 | 0.5 | | 1 | % |

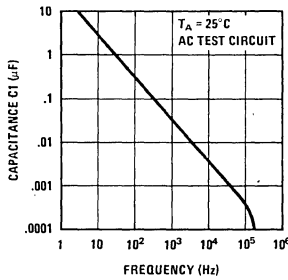
Note 1: The maximum junction temperature of the LM566 is 150°C, while that of the LM566C is 100°C. For operating at elevated junction temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W. The thermal resistance of the dual-in-line package is 100°C/W.

Typical Performance Characteristics

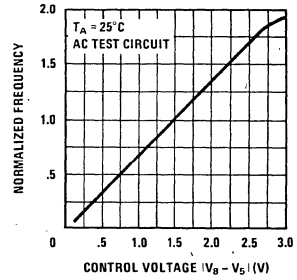
Operating Frequency as a Function of Timing Resistor



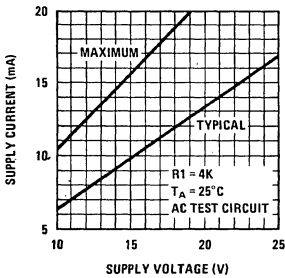
Operating Frequency as a Function of Timing Capacitor



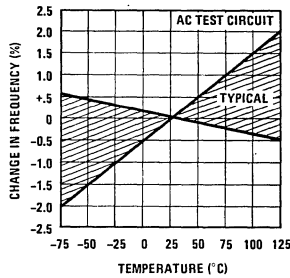
Normalized Frequency as a Function of Control Voltage



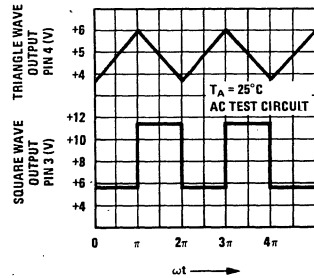
Power Supply Current



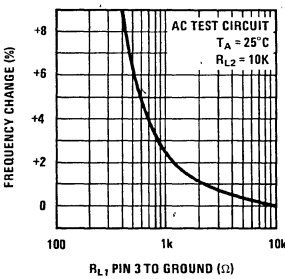
Temperature Stability



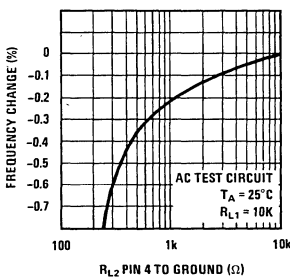
VCO Waveforms



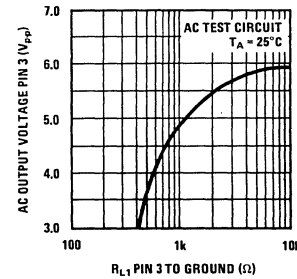
Frequency Stability vs Load Resistance (Square Wave Output)



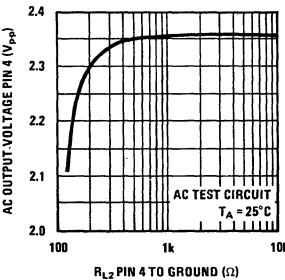
Frequency Stability vs Load Impedance (Triangle Output)



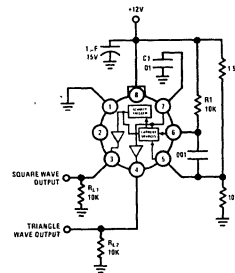
Square Wave Output Characteristics



Triangle Wave Output Characteristics



AC Test Circuit





LM567/LM567C Tone Decoder

General Description

The LM567 and LM567C are general purpose tone decoders designed to provide a saturated transistor switch to ground when an input signal is present within the passband. The circuit consists of an I and Q detector driven by a voltage controlled oscillator which determines the center frequency of the decoder. External components are used to independently set center frequency, bandwidth and output delay.

- High rejection of out of band signals and noise
- Immunity to false signals
- Highly stable center frequency
- Center frequency adjustable from 0.01 Hz to 500 kHz

Features

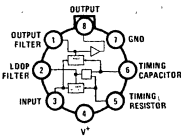
- 20 to 1 frequency range with an external resistor
- Logic compatible output with 100 mA current sinking capability
- Bandwidth adjustable from 0 to 14%

Applications

- Touch tone decoding
- Precision oscillator
- Frequency monitoring and control
- Wide band FSK demodulation
- Ultrasonic controls
- Carrier current remote controls
- Communications paging decoders

Schematic and Connection Diagrams

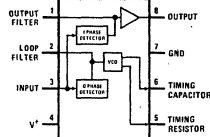
Metal Can Package



TOP VIEW

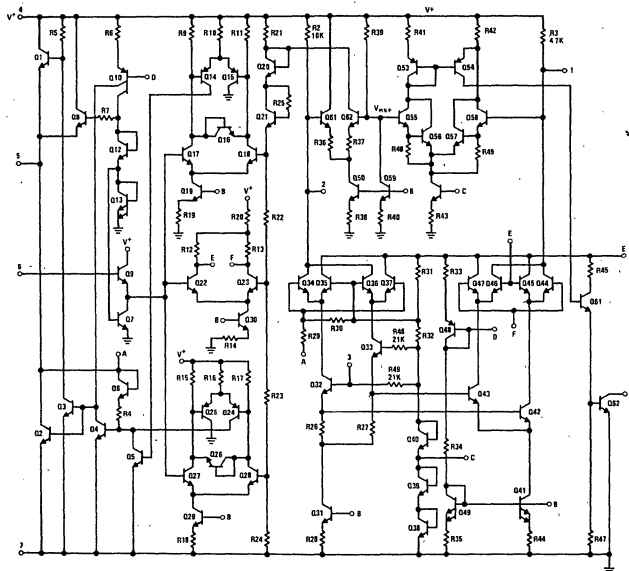
Order Number LM567H or LM567CH
See NS Package H08C

Dual-In-Line Package



TOP VIEW

Order Number LM567CN
See NS Package N08B



Absolute Maximum Ratings

| | |
|----------------------------|-----------------|
| Supply Voltage Pin | 10V |
| Power Dissipation (Note 1) | 300 mW |
| V_B | 15V |
| V_3 | -10V |
| V_3 | $V_B + 0.5V$ |
| Storage Temperature Range | -65°C to +150°C |

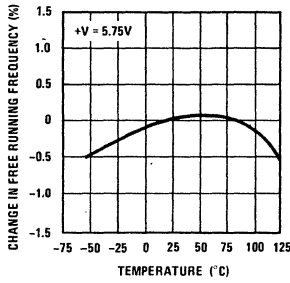
Electrical Characteristics (AC Test Circuit, $T_A = 25^\circ\text{C}$, $V_C = 5V$)

| PARAMETERS | CONDITIONS | LM567 | | | LM567C/LM567CN | | | UNITS |
|--|---|-------|--------------|---------|----------------|--------------|---------|---------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Power Supply Voltage Range | | 4.75 | 5.0 | 9.0 | 4.75 | 5.0 | 9.0 | V |
| Power Supply Current | $R_L = 20k$ | | | | | | | |
| Quiescent | | | 6 | 8 | | 7 | 10 | mA |
| Power Supply Current | $R_L = 20k$ | | | | | | | |
| Activated | | | 11 | 13 | | 12 | 15 | mA |
| Input Resistance | | 18 | 20 | 22 | 15 | 20 | 25 | k Ω |
| Smallest Detectable Input Voltage | $I_L = 100 \text{ mA}$, $f_i = f_o$ | | 20 | 25 | | 20 | 25 | mVrms |
| Largest No Output Input Voltage | $I_C = 100 \text{ mA}$, $f_i = f_o$ | 10 | 15 | | 10 | 15 | | mVrms |
| Largest Simultaneous Outband Signal to Inband Signal Ratio | | | 6 | | | 6 | | dB |
| Minimum Input Signal to Wideband Noise Ratio | $B_n = 140 \text{ kHz}$ | | -6 | | | -6 | | dB |
| Largest Detection Bandwidth | | 12 | 14 | 16 | 10 | 14 | 18 | % of f_o |
| Largest Detection Bandwidth Skew | | | 1 | 2 | | 2 | 3 | % of f_o |
| Largest Detection Bandwidth Variation with Temperature | | | ± 0.1 | 0.25 | | ± 0.1 | 0.5 | %/°C |
| Largest Detection Bandwidth Variation with Supply Voltage | 4.75V – 6.75V | | ± 1 | ± 2 | | ± 1 | ± 5 | %V |
| Highest Center Frequency | | 100 | 500 | | 100 | 500 | | kHz |
| Center Frequency Stability | $0 < T_A < 70$ | | 35 \pm 60 | | | 35 \pm 60 | | ppm/°C |
| | $-55 < T_A < +125$ | | 35 \pm 140 | | | 35 \pm 140 | | ppm/°C |
| Center Frequency Shift with Supply Voltage | 4.75V – 6.75V | | 0.5 | 1.0 | | 0.4 | 2.0 | %/V |
| Fastest ON-OFF Cycling Rate | | | $f_o/20$ | | | $f_o/20$ | | |
| Output Leakage Current | $V_B = 15V$ | | 0.01 | 25 | | 0.01 | 25 | μA |
| Output Saturation Voltage | $e_i = 25 \text{ mV}$, $I_B = 30 \text{ mA}$ | | 0.2 | 0.4 | | 0.2 | 0.4 | V |
| | $e_i = 25 \text{ mV}$, $I_B = 100 \text{ mA}$ | | 0.6 | 1.0 | | 0.6 | 1.0 | |
| Output Fall Time | | | 30 | | | 30 | | ns |
| Output Rise Time | | | 150 | | | 150 | | ns |

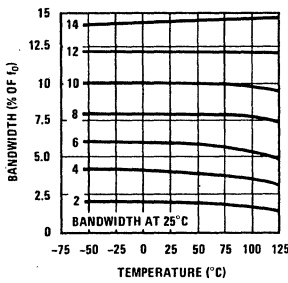
Note 1: The maximum junction temperature of the LM567 is 150°C, while that of the LM567C and LM567CN is 100°C. For operating at elevated temperatures, devices in the TO-5 package must be derated based on a thermal resistance of 150°C/W, junction to ambient or 45°C/W, junction to case. For the DIP the device must be derated based on a thermal resistance of 187°C/W, junction to ambient.

Typical Performance Characteristics

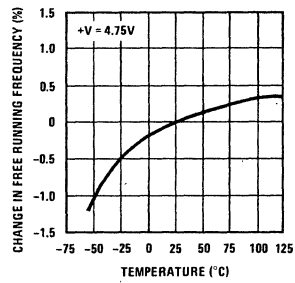
Typical Frequency Drift with Temperature (Mean and S.D.)



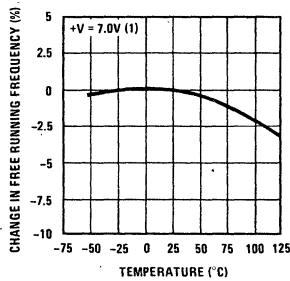
Typical Bandwidth Variation with Temperature



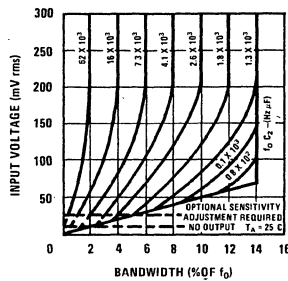
Typical Frequency Drift with (Mean and S.D.) Temperature



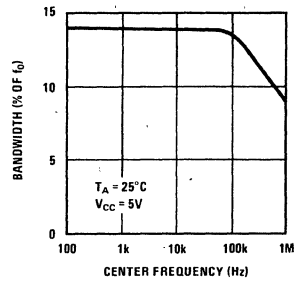
Typical Frequency Drift with Temperature (Mean and S.D.)



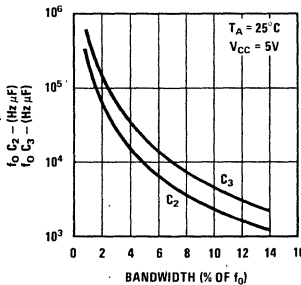
Bandwidth vs Input Signal Amplitude



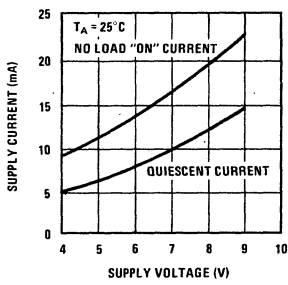
Largest Detection Bandwidth



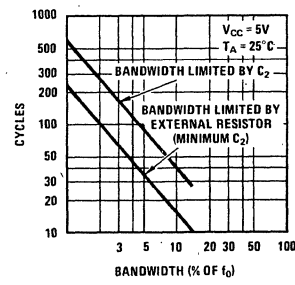
Detection Bandwidth as a Function of C2 and C3



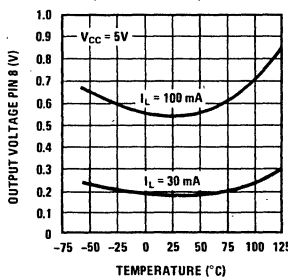
Typical Supply Current vs Supply Voltage



Greatest Number of Cycles Before Output

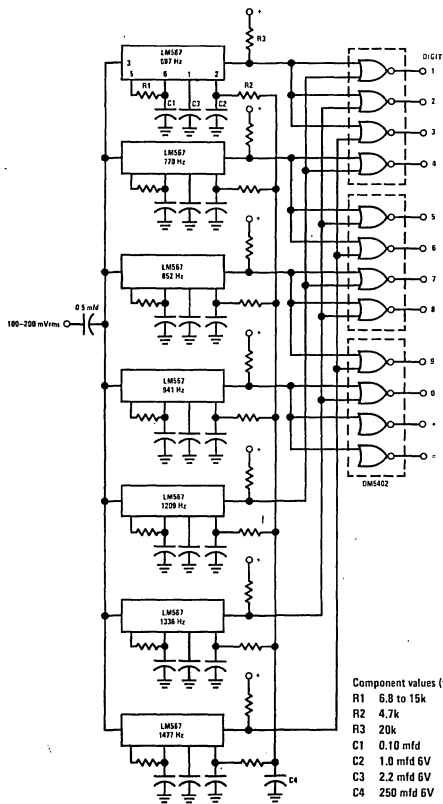


Typical Output Voltage vs Temperature

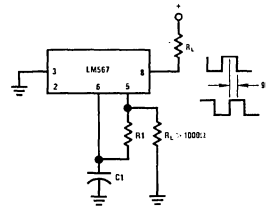


Typical Applications

Touch-Tone Decoder

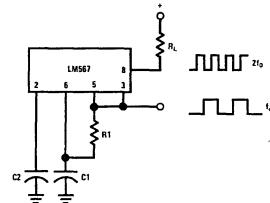


Oscillator with Quadrature Output

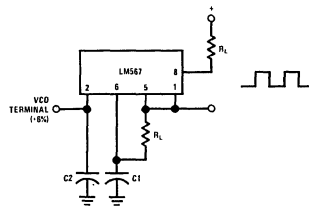


Connect pin 3 to 2.8V to invert output.

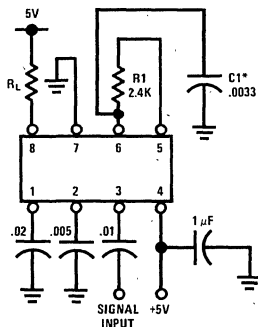
Oscillator with Double Frequency Output



Precision Oscillator Drive 100 mA Loads



AC Test Circuit



$f_0 = 100 \text{ kHz} + 5V$

*Note: Adjust for $f_0 = 100 \text{ kHz}$.

Applications Information

The center frequency of the tone decoder is equal to the free running frequency of the VCO. This is given by

$$f_0 \cong \frac{1}{R_1 C_1}$$

The bandwidth of the filter may be found from the approximation

$$BW = 1070 \sqrt{\frac{V_i}{f_0 C_2}} \text{ in \% of } f_0$$

Where:

V_i = Input voltage (volts rms), $V_i \leq 200 \text{ mV}$

C_2 = Capacitance at Pin 2 (μF)

LM1014/LM1014A Motor Speed Regulator

General Description

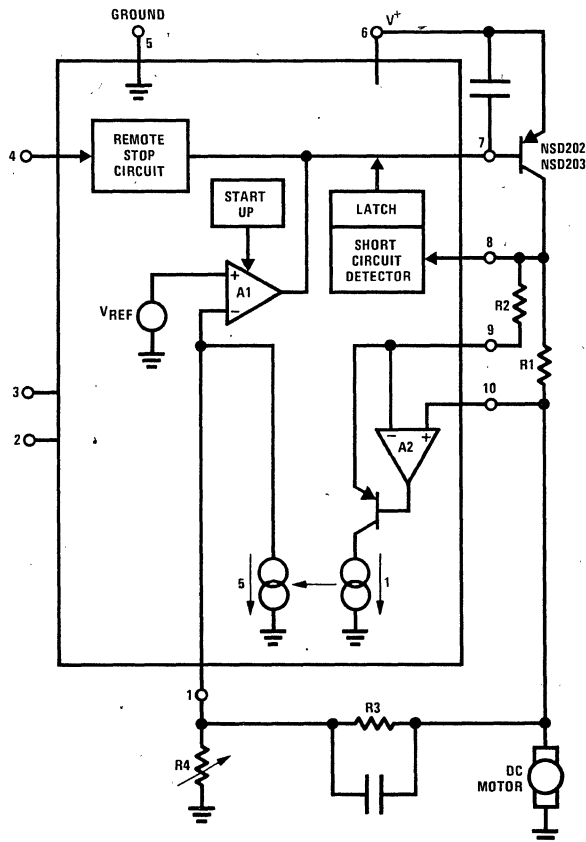
The LM1014 is a monolithic integrated circuit specifically designed to provide a low cost motor speed regulator for low voltage DC motors.

- Externally selectable temperature coefficient
- Remote pause control
- Saturation voltage 0.1V
- Motor connected to ground for ease of RF suppression
- Motor torque compensation
- Low current consumption

Features

- 5V to 20V operating voltage range
- Short circuit protection

Functional Block Diagram and Typical Connection



Absolute Maximum Ratings

| | |
|--|----------------|
| Supply Voltage | 24V |
| Operating Temperature Range | -20 to +70 °C |
| Storage Temperature Range | -65 to +150 °C |
| Lead Temperature (Soldering, 10 seconds) | 300 °C |

Electrical Characteristics (Note 1)

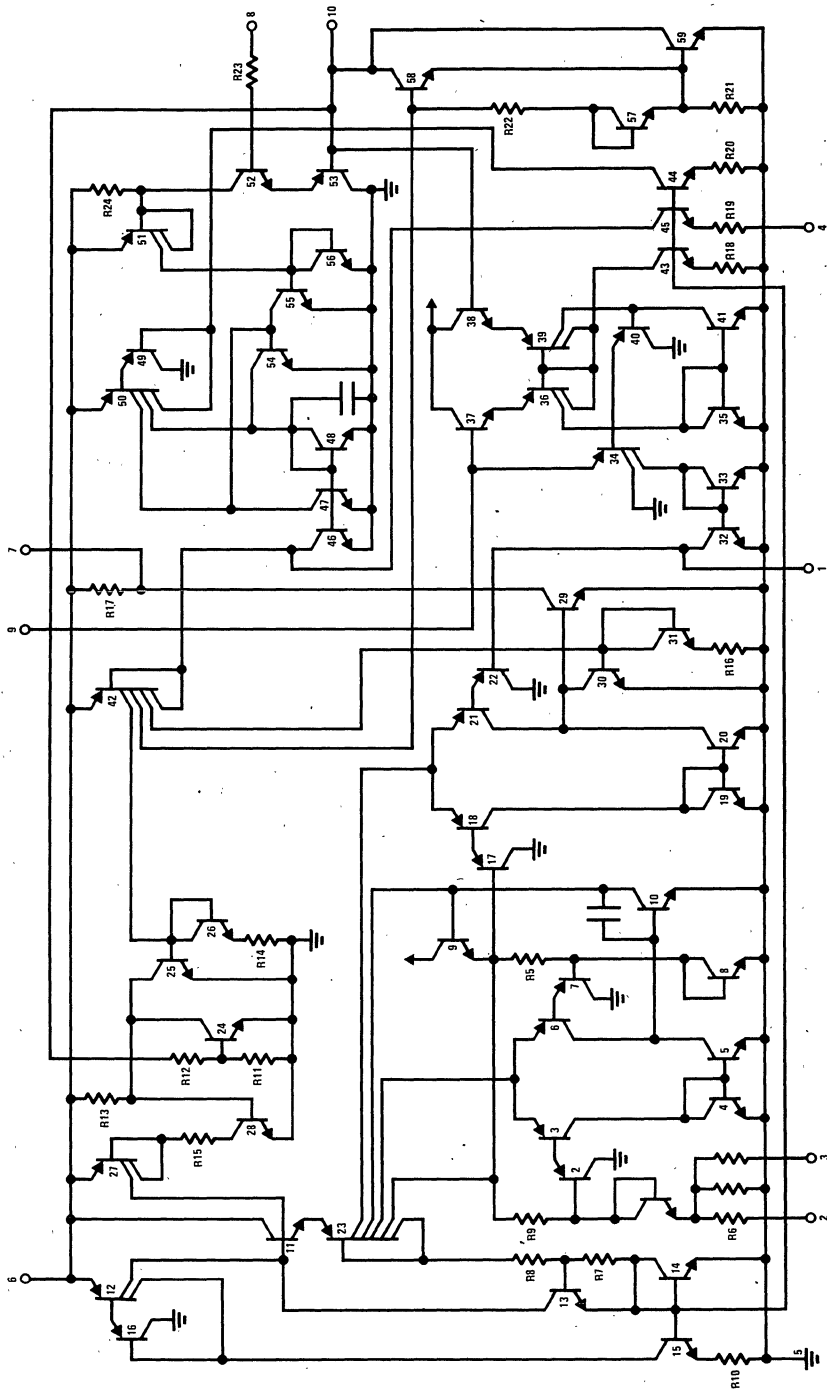
| Parameter | Conditions | Min | Typ | Max | Units | Comments |
|--------------------------------------|---|-----|-----------|------|-------------|---|
| Supply Voltage Range | | 5.0 | | 20.0 | V | |
| Supply Current | Current into Pin 6 | | 6.0 | 8.0 | mA | |
| Reference Voltages | Pin 2 and 3 Open | | 0.93 | | V | -1.0 mV/°C |
| | Pin 2 Gnd, Pin 3 Open | | 1.13 | | V | -0.3 mV/°C |
| | Pin 2 Open, Pin 3 Gnd | | 1.33 | | V | 0.3 mV/°C |
| | Pin 2 and 3 Gnd | | 1.53 | | V | 1.0 mV/°C |
| Line Regulation of Reference Voltage | $V_S = 5V$ to $V_S = 20V$ Pin 1 | | | 2.0 | % V_{REF} | LM1014 |
| | | | | 1.0 | % V_{REF} | LM1014A |
| Remote Stop Current | Current into Pin 4 When Grounded | | 125 | 200 | μA | Note 2 |
| Output Current A1 | $V_S = 5V$ Pin 1 Gnd | 15 | 40 | | mA | Current into Pin 7 |
| Short Circuit Current Limit | $R1 = 1\Omega$ | | 1.4 | | A | Note 3 |
| Motor Sense Current Deviation | $R1 = 1\Omega$, $R2 = 200\Omega$ Current into Pin 1:1 | | | | | ($I1/I_m - 1$) Exclusive of External Components Tolerances LM1014A LM1014 |
| | | | ± 1.5 | | % | |
| | | | ± 3.0 | | % | |

Note 1: Unless otherwise specified, $5V < V_S < 20V$ and $-15^\circ C < T_A < 55^\circ C$.

Note 2: The remote stop is activated by grounding pin 4. The motor restarts after disconnection of the ground connection.

Note 3: The current limit is set by resistor R1, i.e., $I \approx 1.4V/R1$. When the output current exceeds this limit, the drive to the output transistor is switched off by a latch circuit. The motor can only be restarted after interruption of the supply voltage.

Schematic Diagram



Typical Performance Characteristics/Application

1. The output voltage V_M is given by:

$$V_M = V_{REF} \left(1 + \frac{R_3}{R_4} \right) + I_M \frac{R_1 R_3}{5R_2}$$

2. $R_1 R_3/5R_2$ must be equal to dynamic motor winding resistance R_M in order to keep the speed constant during load torque variations.

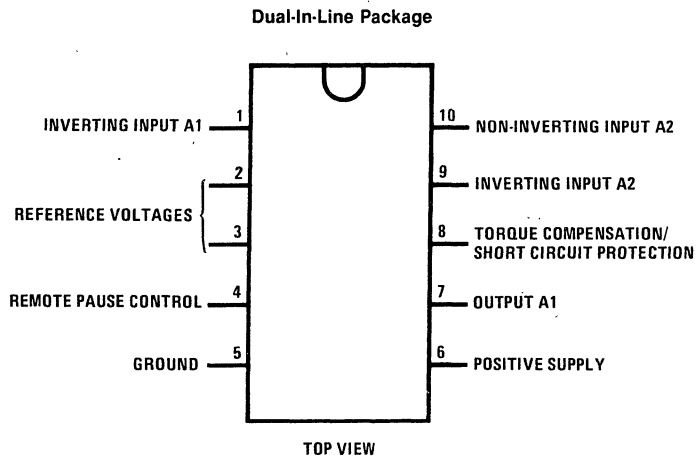
3. Four selectable temperature coefficients by grounding pin 2 and/or pin 3 for temperature compensation of motor characteristic.

4. Parameter of the motor used for the test results shown below:

$R_M = 16.3\Omega$ and back e.m.f. = 3.25V @ 2000 r.p.m.; torque constant 5.9 mA/mNm; External components: $R_1 = 1\Omega$ Cu, $R_2 = 200\Omega$ and $R_3 = 16\text{ k}\Omega$; $V_{REF} = 1.13\text{V}$ (pin 2 grounded); $C_{BE} = 2.2\ \mu\text{F}$ and $C_3 = 0.47\ \mu\text{F}$.

| Parameter | Conditions | Max |
|-------------------------------------|---|-------------|
| Motor Speed Deviation (Voltage) | $V_S = 5\text{V to } 10\text{V}$ | $\pm 0.5\%$ |
| | $V_S = 5\text{V to } 20\text{V}$ | $\pm 1.0\%$ |
| Motor Speed Deviation (Load) | $I_M = 25\text{ mA to } 125\text{ mA}$ | $\pm 1.0\%$ |
| Motor Speed Deviation (Temperature) | $T = +5^\circ\text{C to } +35^\circ\text{C}$ | 1.0% |
| | $T = -15^\circ\text{C to } +55^\circ\text{C}$ | 3.0% |

Connection Diagram



Order Number LM1014N
or LM1014AN
See NS Package N10B

LM1801 Smoke Detector

General Description

The LM1801 is designed to provide the functions of an ionization type smoke detector as specified by UL217. Though primarily designed to operate from a 9V alkaline battery, provision is made for operation at supplies up to 14V and for line operation.

Low battery threshold, alarm threshold, hysteresis and stand-by current drain are externally programmed by resistors. The LM1801 includes a power transistor capable of directly driving a typical 85 dB horn. The ionization chamber requires an external FET buffer.

A parallel alarm output is provided to enable up to 8 similar detectors to be connected in parallel. In this mode, a fault on the line cannot prevent local operation. The low battery alarm signal is confined to the local unit.

A 6V regulated output is provided for the chamber and FET supply and a second output with a different temperature coefficient is available for the alarm threshold potentiometer. This allows compensation of JFET drift.

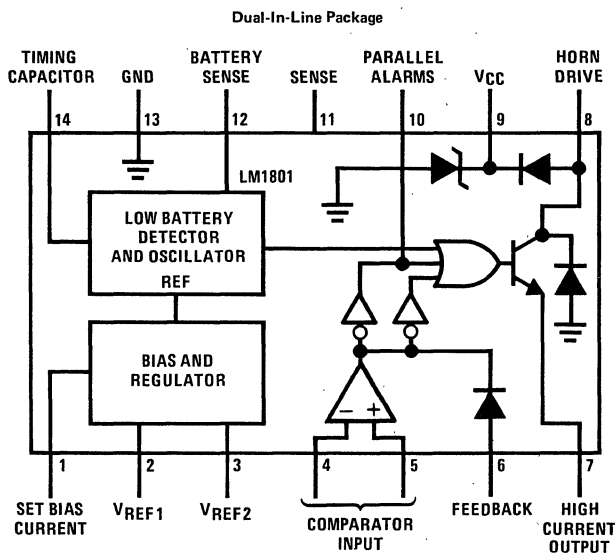
Features

- UL component recognized
- 9V to 14V operation
- Direct drive to horn
- Clamp diodes on chip
- Internal zener for line operation
- JFET and MOSFET compatible
- Parallel alarm capability
- Low stand-by current drain

Applications

- Domestic smoke detectors
- Line operated smoke detectors
- Gas detectors
- Intrusion alarms
- Battery operated detectors

Block and Connection Diagram



Order Number LM1801N
See NS Package N14A

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 14V |
| Input Voltage | -0.3V to 14V |
| Input Differential Voltage | ±14V |
| Power Dissipation (Note 1) | 300 mW |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -65°C to +125°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------------|--|-----|------|-----|-------|
| Comparator | | | | | |
| Input Offset Voltage | | | 3 | 15 | mV |
| Input Bias Current | | | 3 | 10 | nA |
| Input Offset Current | | | 0.5 | 3 | nA |
| Pin 6 Output Low | I _{SINK} = 100 μA | | 1.5 | 2.0 | V |
| Output Stage (Pin 8) | | | | | |
| Leakage Current | | | 45 | 500 | nA |
| Saturation Voltage | I _g = 200 mA | | 0.9 | 1.3 | V |
| Saturation Voltage | I _g = 500 mA | | 1.8 | | V |
| Common Alarm Line (Pin 10) | | | | | |
| Drive Capabilities | V ₄ > V ₅ | | | | |
| Output Voltage High | | 6.0 | 6.5 | | V |
| Output Current | V ₁₀ = 0.0V | 4.0 | 6.5 | | mA |
| Driver Requirements | V ₅ > V ₄ | | | | |
| Input Voltage | | | 3.6 | | V |
| Input Current | V ₈ = 1.5V, I _g = 200 mA | | 0.4 | | mA |
| Regulator | | | | | |
| Pin 2 Reference Voltage | I ₂ = 1 μA | 5.4 | 5.8 | 6.4 | V |
| Temperature Coefficient | | | 5 | | mV/°C |
| Pin 3 Reference Voltage | I ₂ = I ₃ = 1 μA | 4.8 | 5.3 | 5.8 | V |
| Temperature Coefficient | | | 7 | | mV/°C |
| Battery Check Oscillator | | | | | |
| Threshold Voltage (Pin 12) | | 5.5 | 6.0 | 6.5 | V |
| Period | V _{CC} = 7.5V, C ₁ = 10 μF | 28 | 42 | 50 | Sec |
| Beep Pulse Width | V _{CC} = 7.5V, C ₁ = 10 μF | | 30 | | ms |
| Supply Current (Note 3) | | | 7 | 9 | μA |
| Zener Clamp Voltage, V ₉ | I _g = 1 mA | 14 | 14.5 | 17 | V |

Note 1: For operating at elevated temperatures, the device must be derated based on a 125°C maximum junction temperature and a thermal resistance of 187°C/W junction to ambient.

Note 2: R_{SET} = 10 MΩ, V_{CC} = 9V, T_A = 25°C, (Figure 1).

Note 3: Stand-by mode. JFET is biased for I_{DS} = 1 μA.



Application Hints

The LM1801 is biased by a group of current sources which are controlled externally by a fixed resistor. In normal operation the stand-by current drain is nominally 6 times the set current at pin 1. The voltage at pin 1 is 2 diode drops below the positive supply voltage. The total stand-by current drain of the smoke detector will include, in addition to the above, the current drawn by the external circuits connected at pins 2, 3 and 12. These comprise the resistive dividers used to set the low battery threshold and alarm threshold plus the bias current in the ionization chamber and FET buffer.

The low battery threshold is set by R1 and R2 (Figure 1). Select these values so that the voltage at pin 12 is equal to the oscillator trip voltage when the battery voltage is

at the low limit at which the low battery alarm is to operate. The given values provide a warning at about 8.2V.

Hysteresis can be provided by R5, giving an added degree of noise immunity in high noise environments.

Figure 2 is a suggested PC board layout for the circuit of Figure 1.

Parallel operation of 2 or more units is easily achieved with a pair of wires connecting pin 10 of each unit and ground. In this mode, every alarm will sound should any single unit detect smoke.

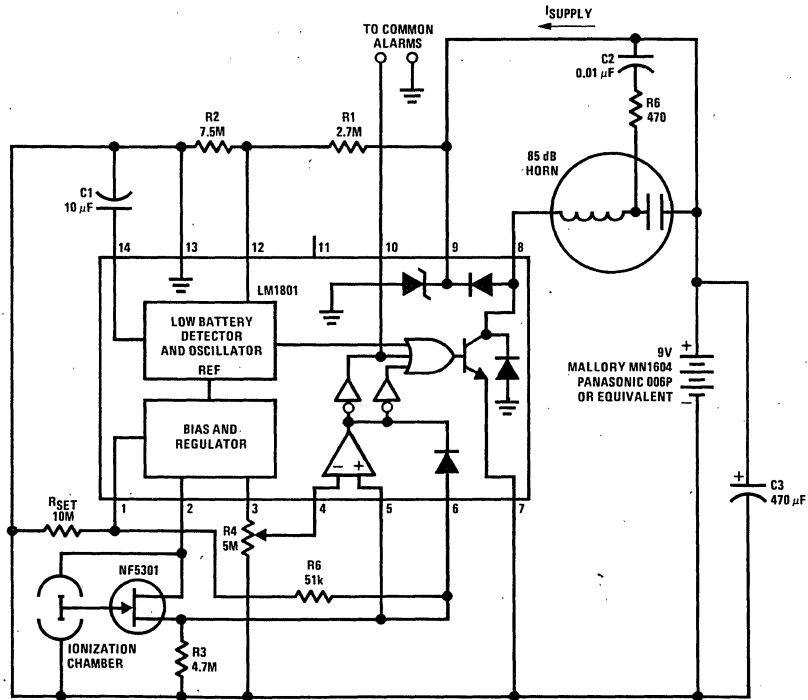


FIGURE 1. 9V Battery Operated Ionization Type Smoke Detector

Application Hints (Continued)

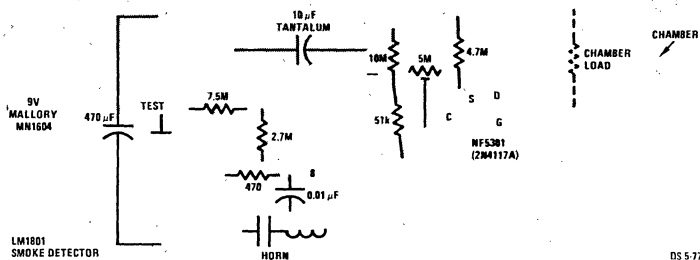


FIGURE 2. Smoke Detector PC Board Layout (Not to Scale)

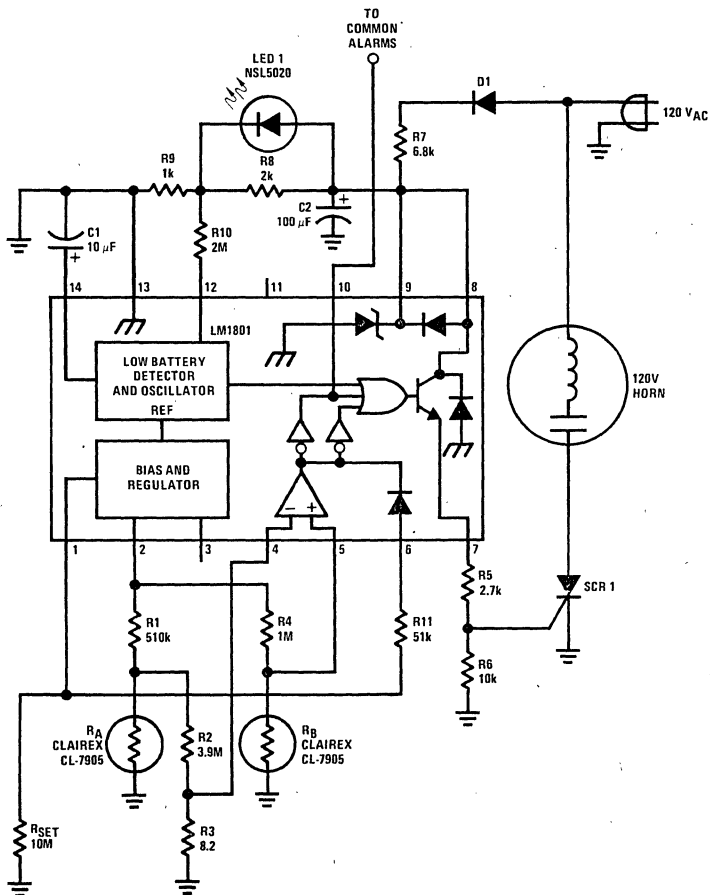


FIGURE 3. Line-Operated Photo-Electric Smoke Alarm Using Light Sensitive Resistor (Includes Detection of Open-Circuited LED)



LM1812 Ultrasonic Transceiver

General Description

The LM1812 is a special monolithic IC which consists of a 12W ultrasonic transmitter circuit, which uses novel circuitry to eliminate costly alignment adjustments, a selective receiver which uses only one external LC network, impulse noise rejection circuitry, a 10W display driver, and a keyed modulator.

The system operates from a 12V battery, drives power into a transducer, receives an echo and drives a display lamp.

A single LC network is time shared between the receiver and the transmitter to reduce external parts, to eliminate alignment labor and to guarantee that the received signal is always of the proper frequency.

Application areas include both sonar (distance measuring in water) and "sonic" radar (or "Sodar"—distance measuring in air) where a liquid level must be detected without actual immersion of a sensor or the presence of an object must be detected as in collision avoidance or an intrusion or burglar alarm system. As a sonar system, the presence of partially submerged objects can be detected, such as marine life, or the depth of a body of water can be determined (as for keel clearance or depth indicators). In addition, data transmission is possible for remote control applications such as in model submarines or hydroacoustic communication links.

Unique Characteristics

- RF transmitter design prevents "mode-hopping" of transducer
- Operates with interchangeable transducers without realignment

- Only one tuned circuit is used
- No additional transistors are needed
- A zero reference output, which "appears" the same as a normal return, is generated to coincide with the Tx. pulse
- Impulse noise is rejected
- Can be used with various displays

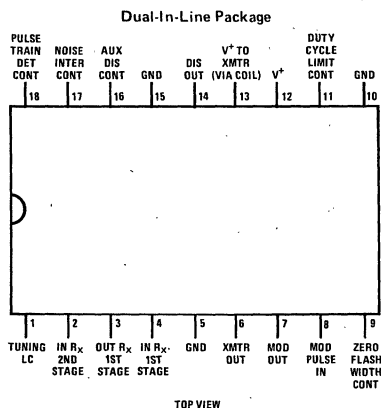
Advantages

- Reduces assembly labor content
- Allows transducer replacement in the field without a factory return
- Allows multiple transducers to be used with the same electronics
- Provides for more consistent system performance in production

Features

- Has special access pins (7 and 16) which allow adding an audible alarm feature to indicate an echo within a presettable maximum depth (or range)
- Does not require any heat sinking of the IC package
- Uses a built-in monostable multivibrator, with the capacitor on the chip, to pulse drive the transmitter for high efficiency and to minimize transducer interaction
- Has special circuitry to limit the maximum ON time of the display driver
- Can operate with a neon, a LED display device, a digital readout or a CRT

Connection Diagram



Order Number **LM1812N**
See NS Package **N18A**

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage, V^+ (Pins 12, 6 and 14) | 18 V_{DC} |
| Power Dissipation (Note 1) | 700 mW |
| Operating Temperature Range (T_A) | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 60 seconds) | 300°C |

| PIN NO. | FUNCTION | R_{EXT} (MIN) | V_{MAX} (Total Inst. Peak) | $I_{MAX DC}$ |
|---------|------------------------------|-----------------|---------------------------------|------------------|
| 1 | Tuning LC | | 30V | |
| 2 | Input R_X - 2nd Stage | | | 50 mA |
| 3 | Output R_X - 1st Stage | | 18 V_{DC} | |
| 4 | Input R_X - 1st Stage | | | 50 mA |
| 5 | Ground | | | |
| 6 | XMTR Output | | 36V (When OFF) | 1A for 1 μ s |
| 7 | Modulator Output | 75k | 18V | |
| 8 | Modulator Pulse Input | | | 50 mA |
| 9 | Zero Flash Width Control | | 7V | |
| 10 | Ground | | | |
| 11 | Duty Cycle Limit Control | | | 50 mA |
| 12 | V^+ | | 18V | |
| 13 | V^+ to XMTR (via Coil) | | 18V | |
| 14 | Display Output | | 25V (When OFF) | 1A for 1 ms |
| 15 | Ground | | | |
| 16 | Auxiliary Display Control | 2M | 18V | |
| 17 | Noise Integrator Control | | | 50 mA |
| 18 | Pulse Train Detector Control | | | 50 mA |

Electrical Characteristics ($V^+ = +12 V_{DC}$ and $T_A = 25^\circ C$, unless otherwise noted)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------|---|------|------|-----|------------|
| Sensitivity | (Figure 1) (Note 2) | | 200 | 600 | μ Vp-p |
| Transmitter (V_{SAT}) | (Figure 2), $R_L = 10\Omega$ (V_{SAT}) (Note 4) | | 1.3 | 3 | V_{DC} |
| Transmitter Leakage | Pin 6 = 32 V_{DC} , Pin 8 = Ground | | 0.01 | 1 | mA_{DC} |
| Modulator Threshold | (Figure 2) (Note 3) | 0.55 | 0.7 | 0.9 | V_P |
| Supply Current | (Figure 3) (I_D) | 5 | 8.5 | 20 | mA_{DC} |
| Display Driver (V_{SAT}) | (Figure 4) (V_{SAT}) (Note 4) | | 1.5 | 3 | V_{DC} |
| Display Driver Leakage | Pin 14 = 16 V_{DC} , Pin 17 = Ground | | 0.01 | 1 | mA_{DC} |

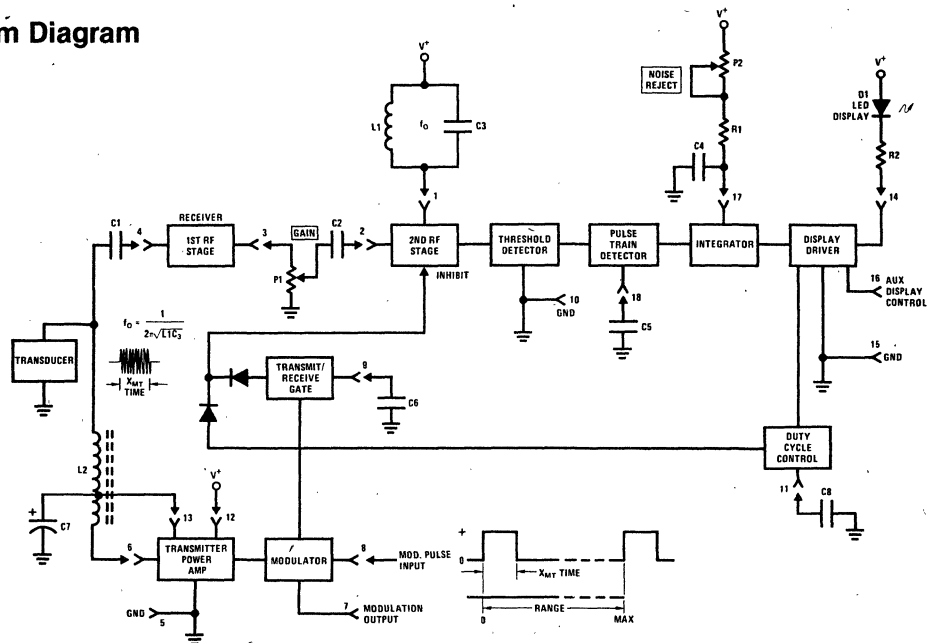
Note 1: For operating at high temperatures, the LM1812 must be derated based upon a +150°C maximum junction temperature and a thermal resistance of +175°C/W which applies for the device soldered in a printed circuit board and operating in a still air ambient. Due to the switching mode of operation, there is usually only a small power dissipation in the IC package.

Note 2: This sensitivity test uses the 500:1 attenuator to raise the input signal level for a more reliable reading and to reduce the chances for unintentional input-output coupling during the test.

Note 3: The "Modulator Threshold" is the voltage which must be applied to pin 8 to put the system in the transmit mode. The current input to pin 8 should be limited to 1–10 mA.

Note 4: As a check on the performance of the transformers used for both the RF transmitter and the neon bulb driver (if a neon display is used) a current probe should be used to display the current waveform on an oscilloscope. Peak values of current should not exceed 1.5 amps. Re-design the transformer if larger peak currents are noted.

System Diagram



AC Test Circuits

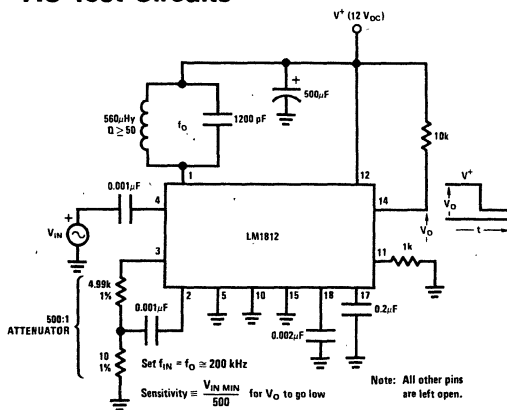


FIGURE 1. Sensitivity Test Circuit

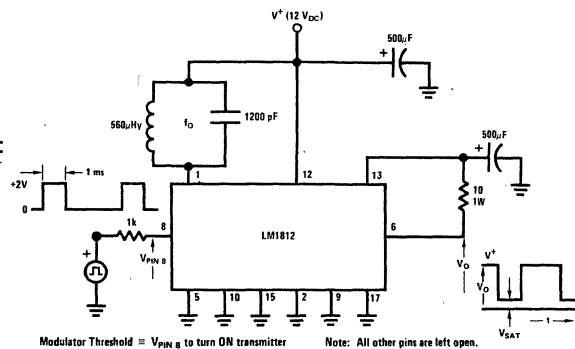


FIGURE 2. Transmitter V_{SAT} and Modulator Threshold Test Circuit

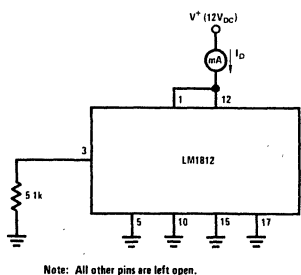


FIGURE 3. Current Drain Test Circuit

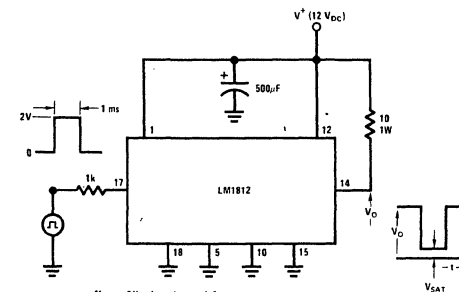


FIGURE 4. Neon Driver Test Circuit

Application Hints

As the LM1812 contains both a transmitter and a receiver in proximity, PC layouts or breadboarding has to be done with special attention to ground loops and common coupling paths. The use of three ground pins on the IC package helps reduce grounding problems, but at the time of transmission, with the display driver also ON, there can be 1–2A of peak current passed into the ground trace.

Local sources of high energy impulse noise, if not locally shielded, can cause an unwanted display "blip." This, for example, usually only occurs when using fly-ball governed dc display wheel drive motors and is due to the abrupt make-break action of the speed regulator contacts in combination with the large inductance of the lightly loaded motor. These "inductive kicks" can be locally filtered with a capacitor across the motor or a small valued capacitor (approximately 30 pF) can be connected across the first receive stage (between pins 3 and 4) to reduce the bandwidth and filter out these noise pulses.

For ranging applications, large transmit power levels are necessary due to the two-way path and the resulting received echo power falling as the fourth power of range (additional external receiver gain can be used to extend the range). One way communication links can use reduced power. Transmit power can be checked by measuring the voltage swing across the transducer (of known impedance) during the transmit mode. The magnitude of the transmitter power depends on the transducer impedance as presented to the transmitter power amplifier (usually a transformer is used to couple the transducer to the power amplifier). A minimum value of 10Ω causes approximately 1A peak current pulses out of this power amplifier. The inductance of the secondary should be designed to resonate with the sum of the capacitance associated with the cable feeding the transducer and that of the transducer. The low Q resonance allows transducer replacement without tuning.

An internal one-shot multivibrator with a fixed time of $1\mu\text{s}$ is used to drive the transmitter power amplifier into saturation for this time period once for each cycle of the transmit frequency. At a frequency of 200 kHz, this results in a high efficiency class-C type of operation for the power amplifier. The transmit frequency is equal to the natural resonance of the external LC network which is tied to pin 1. This network is also used to establish the center frequency and the selectivity of the receiver.

Impulse noise is rejected by the combined action of the "Pulse Train Detector" and the "Integrator" circuits. The integrator requires a number of cycles of valid returns to be received before turning ON the display driver. The pulse train detector will dump the integrator if a continuous train of pulses is not received (if 2 or 3 are missing, the integration capacitor is discharged to ground).

The collector of a grounded-emitter NPN transistor can be tied to pin 16 to allow an auxiliary control of the display driver. This transistor should normally be held OFF and should go ON for a time interval no longer than 1 ms if a neon display is used, due to the rapid current

build-up in the primary of the step-up transformer. If a LED is used as a display device with a series limiting resistor, this ON time can be made longer as it is now limited only by the increased dissipation of the IC which results from the saturation voltage at pin 14 and the ON current of the LED.

The step-up transformer for the neon display lamp has to have a relatively large magnetizing inductance to prevent large current build-up for the time duration of the flash. For this reason, iron-cored transformers are generally used and the large number of turns on the primary, which is required to achieve a high magnetizing inductance, requires an even larger number of turns, on the secondary to step up the 12V to over 100V to guarantee that the neon lamp fires. Rapid flashing of the neon lamp can cause a current build-up in the primary. This is the reason for the RC filter which powers the transformer. Under rapid flashing conditions, the voltage available falls and both the IC and the neon are saved from degradation due to large power dissipation. With normal operation, this network can easily supply the low power requirements of the neon display.

An IC audio amplifier can be used to amplitude modulate the carrier for an AM communication link. A high input impedance detector and audio amplifier attach to pin 1 for the receiver. One audio amplifier can be switched between the modulator and the receiver section. FM or pulse modulation techniques can also be used to reduce the modulator power requirements.

A digital depth (or range) readout can be used with the LM1812. This eliminates the requirement for the constant speed dc motor. The modulator, pin 8, is electronically pulsed ON for approximately a 1 ms transmit time at a repetition rate which controls the updating of the displayed information. The "neon driver," pin 14, will provide a negative output pulse (from V^+ to approximately $+1 V_{DC}$) if a load resistor ($5.1\text{ k}\Omega$) is used from pin 14 to V^+ . This pulse is used to latch the output of a counter. This output is decoded and then drives a 7-segment LED display. The repetition rate of the clock input to the counter provides a direct conversion from elapsed time (total count) to depth (or range).

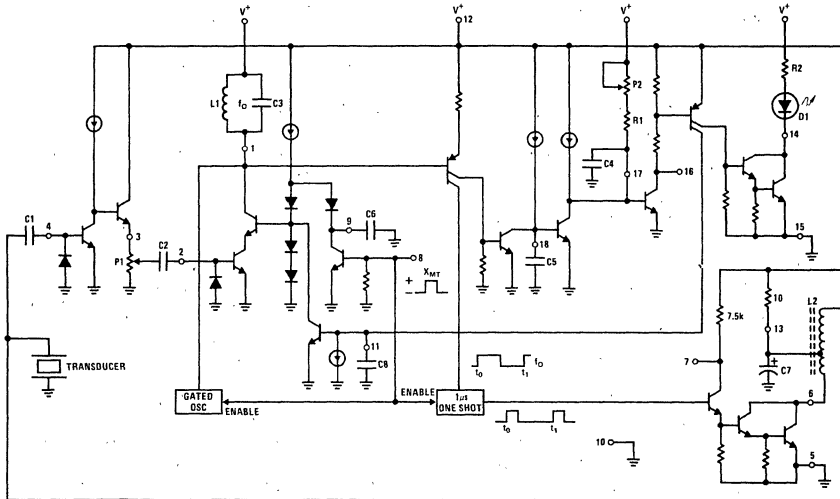
Transducers are available for use either in water or air. The appropriate transducer is important for proper functioning in the intended application; for example, the high frequency attenuation in air usually requires a lower operating frequency. The modifications for a 40 kHz system are shown in the applications section.

A simplified schematic diagram, complete with typical external components for a sonar system, is shown in Figure 5. This not only shows the operation of the system, but also indicates "what's on the other side of the IC pins" to aid the user in his application. When pin 8 is externally pulsed, the system is put in the transmit mode and a controlled amplitude sinewave oscillation waveform results across the LC resonator, pin 1. This is internally amplified and squared and each leading edge triggers the generation of a $1\mu\text{s}$ pulse. This pulse drives the RF power amplifier (output at pin 6) into saturation. During this transmit mode, the second RF stage is gated

Application Hints (Continued)

OFF to disable the receiver. The receiver is also disabled if the display driver is ON for too long a time interval. The capacitor at pin 11 does the necessary integration for this control.

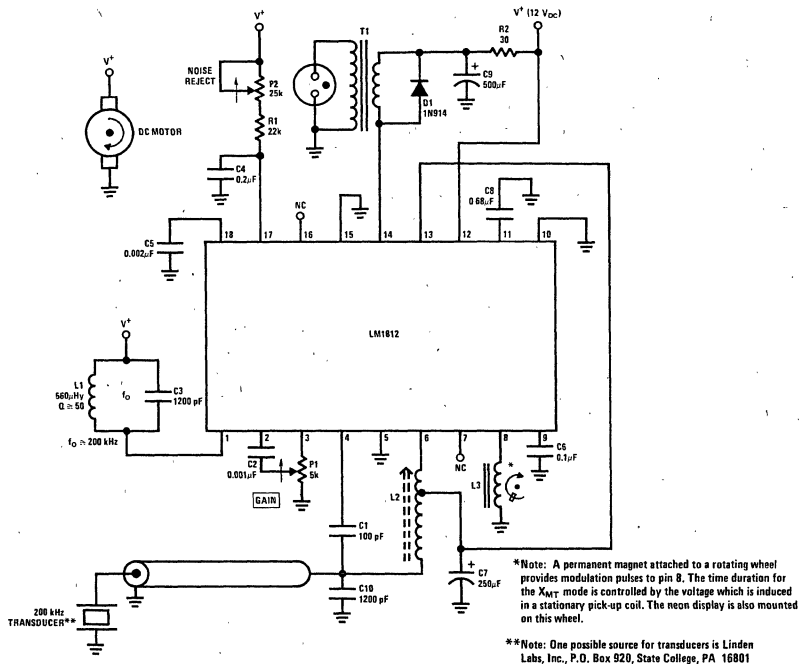
For additional information see *A Single-Chip Monolithic Sonar System*, T. M. Frederiksen and W. M. Howard, IEEE Journal of Solid State Circuits, Dec. 1974, Vol. SC-9, No. 6, pp. 394-403.



Note: Component numbering is the same as on the system and connection diagram.

FIGURE 5. Simplified Schematic Diagram in Typical Application

Typical Applications

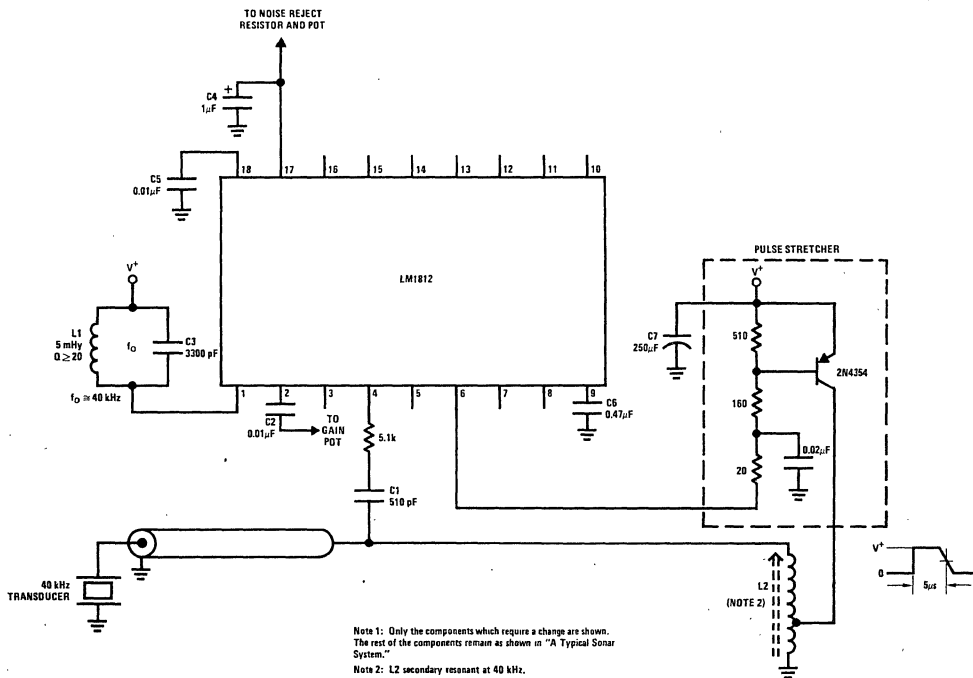


*Note: A permanent magnet attached to a rotating wheel provides modulation pulses to pin 8. The time duration for the X_{MY} mode is controlled by the voltage which is induced in a stationary pick-up coil. The neon display is also mounted on this wheel.

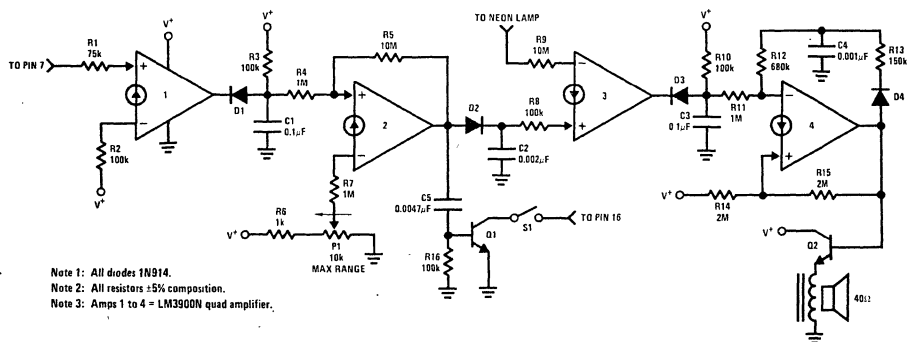
**Note: One possible source for transducers is Linden Labs, Inc., P.D. Box 920, State College, PA 16801

A Typical Sonar Application

Typical Applications (Continued)



Component Changes for Operation in Air (40 kHz)



Electronics for Adding an Echo Annunciator

LM1815 Adaptive Sense Amplifier

General Description

The LM1815 is an adaptive sense amplifier and default gating circuit for motor control applications. The sense amplifier provides a one-shot pulse output whose leading edge coincides with the negative-going zero crossing of a ground referenced input signal such as from a variable reluctance magnetic pick-up coil.

In normal operation, this timing reference signal is processed (delayed) externally and returned to the LM1815. A logic input is then able to select either the timing reference or the processed signal for transmission to the output driver stage.

The adaptive sense amplifier operates with a positive-going threshold which is derived by peak detecting the incoming signal and dividing this down. Thus the input hysteresis varies with input signal amplitude. This enables the circuit to sense in situations where the high speed noise is greater than the low speed signal amplitude. Minimum input signal is 100 mVp-p.

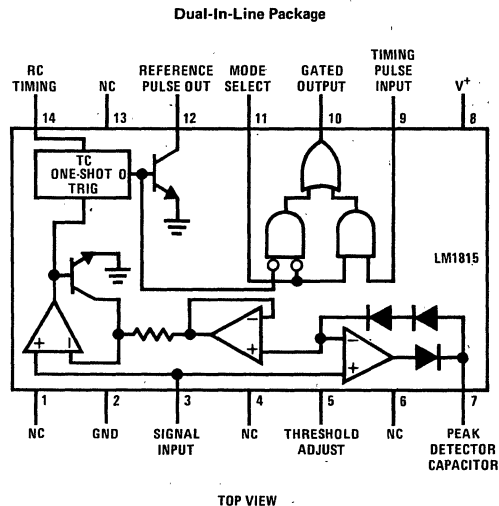
Features

- Adaptive hysteresis
- Single supply operation
- Ground referenced input
- True zero crossing timing reference
- Operates from 2V to 12V supply voltage
- Handles inputs from 100 mV to over 120V with external resistor
- CMOS compatible logic

Applications

- Position sensing with notched wheels
- Zero crossing switch
- Motor speed control
- Tachometer
- Engine testing

Connection Diagram



Order Number LM1815N
See NS Package N14A

Absolute Maximum Ratings

| | |
|-------------------------------|-----------------|
| Supply Voltage | 12V |
| Power Dissipation (Note 1) | 230 mW |
| Operating Temperature Range | -40°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Junction Temperature (Note 2) | 125°C |
| Input Current | ±30 mA |

Electrical Characteristics (T_A = 25°C, V_{CC} = 10V, unless otherwise specified, see Figure 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------|---|-----|----------------------------|-----|------------------------|
| Operating Supply Voltage | | 2.5 | 10 | 12 | V |
| Supply Current | f _{IN} = 500 Hz, Pin 9 = 2V, Pin 11 = 0.8V | | 3.6 | | mA |
| Reference Pulse Width | f _{IN} = 1 Hz to 2 kHz | 70 | 100 | 130 | μs |
| Input Bias Current | V _{IN} = 2V, (Pin 9 and Pin 11) | | | 5 | μA |
| Input Bias Current | V _{IN} = 0V dc, (Pin 3) | | 200 | | nA |
| Input Impedance | V _{IN} = 5Vrms, (Note 3) | 12 | 20 | 28 | kΩ |
| Zero Crossing Threshold | V _{IN} = 100 mVp-p, (Pin 3) | | | 25 | mV |
| Logic Threshold | (Pin 9 and Pin 11) | 0.8 | 1.1 | 2.0 | V |
| V _{OUT} High | R _L = 1 kΩ, (Pin 10) | 7.5 | 8.6 | | V |
| V _{OUT} Low | I _{SINK} = 0.1 mA, (Pin 10) | | 0.3 | 0.4 | V |
| Input Arming Threshold | Pin 5 Open, V _{IN} ≤ 135 mVp-p | 45 | } 80% of V ₃ Pk | 60 | % of V ₃ Pk |
| | Pin 5 Open, V _{IN} ≥ 230 mVp-p | 40 | | | |
| | Pin 5 to V ⁺ | 250 | | | |
| | Pin 5 to Gnd | -25 | | | |
| Output Leakage Pin 12 | V ₁₂ = 11V | | 0.01 | 10 | μA |
| Saturation Voltage P12 | I ₁₂ = 2 mA | | 0.2 | 0.4 | V |

Note 1: Derate at 5.7 mW/°C for ambient temperatures above 85°C. This applies when the device is soldered into a printed circuit board, operating in still air ambient.

Note 2: Temporary excursions to 150°C can be tolerated.

Note 3: Measured at input to external 18 kΩ resistor. IC contains 1 kΩ in series with a diode to attenuate the input signal.

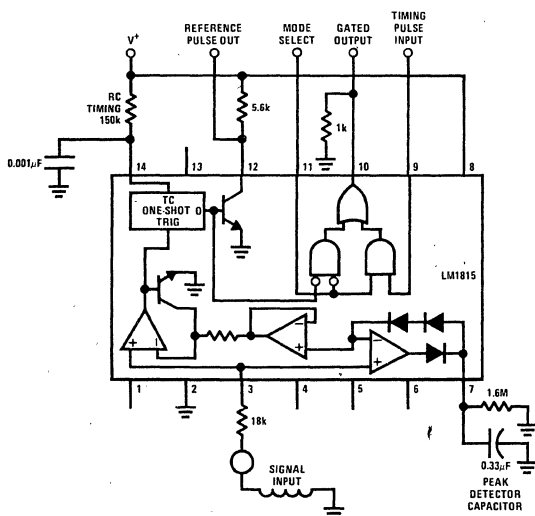


FIGURE 1. LM1815 Adaptive Sense Amplifier

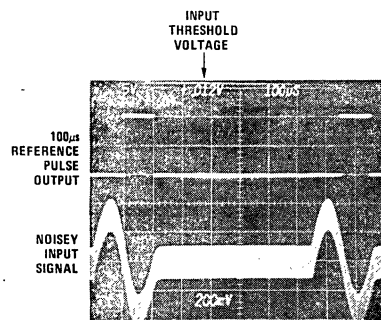
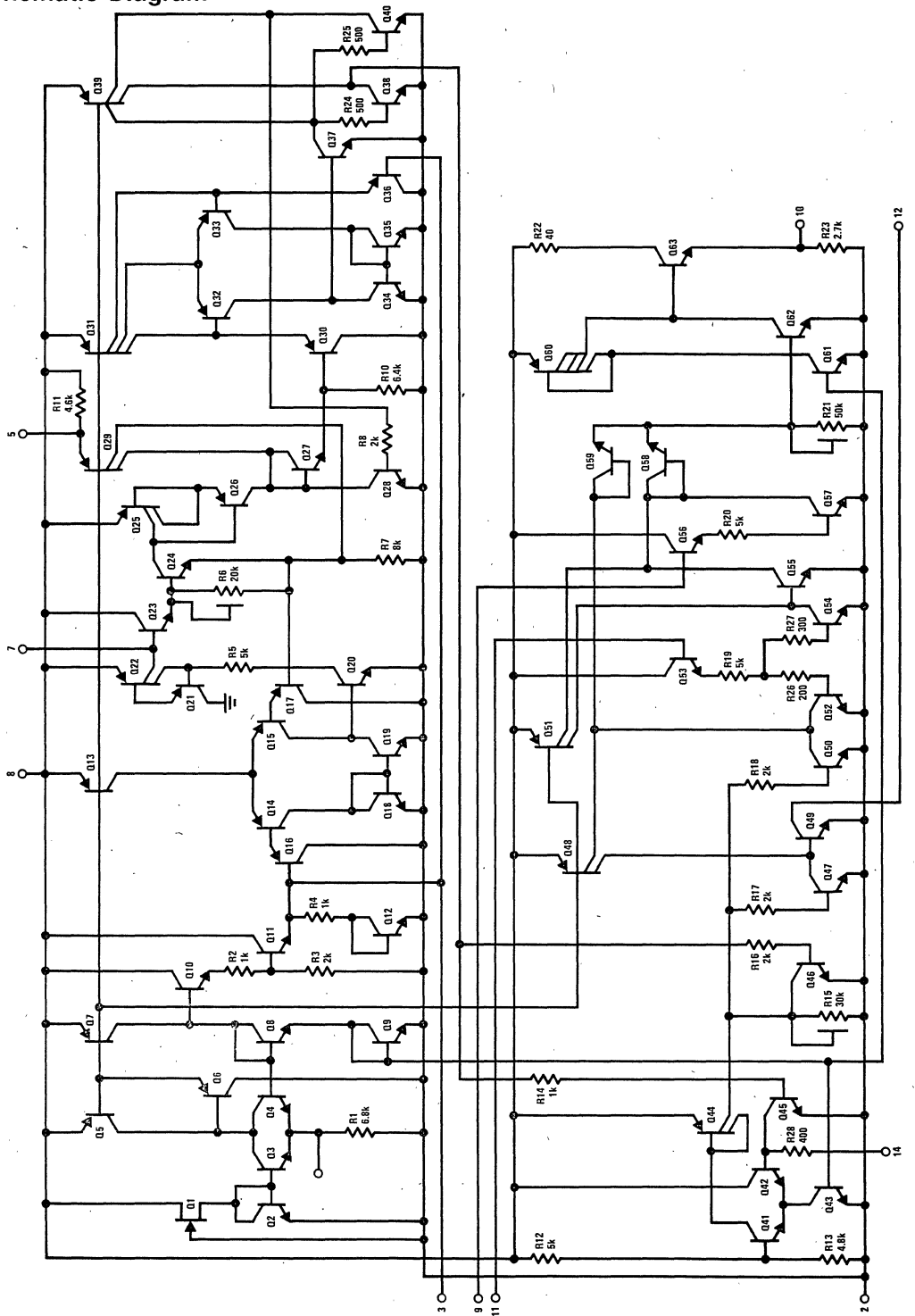


FIGURE 2. LM1815 Oscilloscope

Schematic Diagram



LM1830 Fluid Detector

General Description

The LM1830 is a monolithic bipolar integrated circuit designed for use in fluid detection systems. The circuit is ideal for detecting the presence, absence, or level of water, or other polar liquids. An ac signal is passed through two probes within the fluid. A detector determines the presence or absence of the fluid by comparing the resistance of the fluid between the probes with the resistance internal to the integrated circuit. An ac signal is used to overcome plating problems incurred by using a dc source. A pin is available for connecting an external resistance in cases where the fluid impedance is of a different magnitude than that of the internal resistor. When the probe resistance increases above the preset value, the oscillator signal is coupled to the base of the open-collector output transistor. In a typical application, the output could be used to drive a LED, loud speaker or a low current relay.

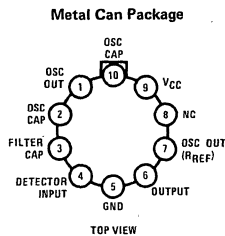
Features

- Low external parts count
- Wide supply operating range
- One side of probe input can be grounded
- ac coupling to probe to prevent plating
- Internally regulated supply
- ac or dc output

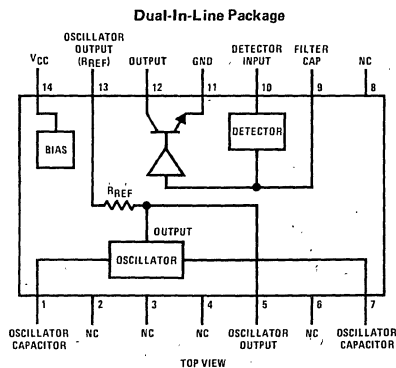
Applications

- Beverage dispensers
- Water softeners
- Irrigation
- Sump pumps
- Aquaria
- Radiators
- Washing machines
- Reservoirs
- Boilers

Logic and Connection Diagrams



Order Number LM1830H
See NS Package H10C



Order Number LM1830N
See NS Package N14A

Absolute Maximum Ratings

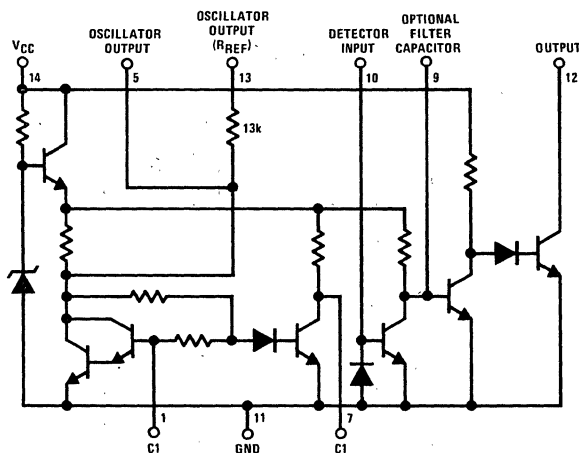
| | |
|--|-----------------|
| Supply Voltage | 28V |
| Power Dissipation (Note 1) | 300 mW |
| Output Sink Current | 20 mA |
| Operating Temperature Range | -40°C to +85°C |
| Storage Temperature Range | -40°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics ($V^+ = 16V$, $T_A = 25^\circ C$ unless otherwise specified)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|---------------------|-----|-----|-----|------------|
| Supply Current | | | 5.5 | 10 | mA |
| Oscillator Output Voltage | | | | | |
| Low | | | 1.1 | | V |
| High | | | 4.2 | | V |
| Internal Reference Resistor | | 8 | 13 | 25 | k Ω |
| Detector Threshold Voltage | | | 680 | | mV |
| Detector Threshold Resistance | | 5 | 10 | 15 | k Ω |
| Output Saturation Voltage | $I_O = 10$ mA | | 0.5 | 2.0 | V |
| Output Leakage | $V_{PIN\ 12} = 16V$ | | | 10 | μA |
| Oscillator Frequency | $C_1 = 0.001\mu F$ | 4 | 7 | 12 | kHz |

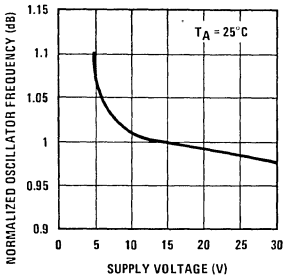
Note 1: The maximum junction temperature rating of the LM1830N is 150°C. For operation at elevated temperatures, devices in the dual-in-line plastic package must be derated based on a thermal resistance of 175°C/W.

Schematic Diagram

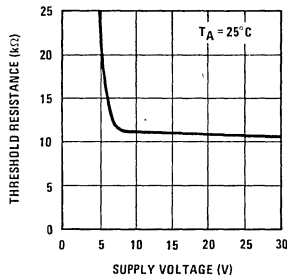


Typical Performance Characteristics

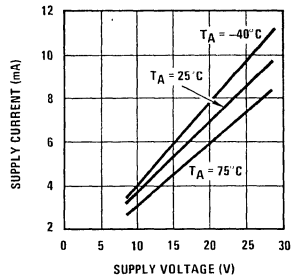
Normalized Oscillator Frequency vs Supply Voltage



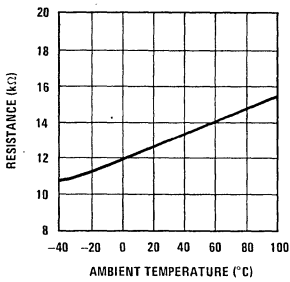
Threshold Resistance vs Supply Voltage



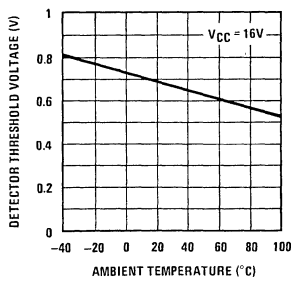
Power Supply Current vs Supply Voltage



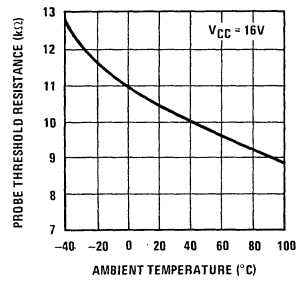
Reference Resistor vs Ambient Temperature



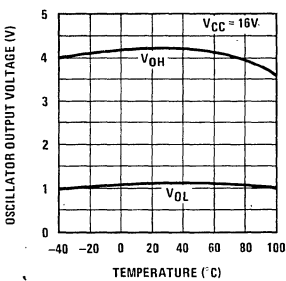
Detector Threshold Voltage vs Temperature



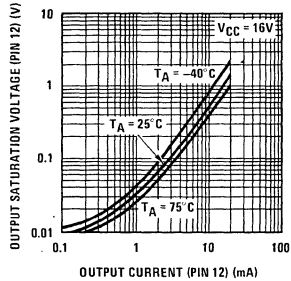
Probe Threshold Resistance vs Temperature



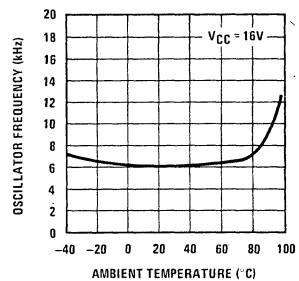
Oscillator V_{OH} and V_{OL} vs Ambient Temperature



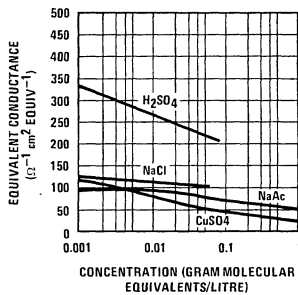
Output Saturation Voltage vs Output Current



Oscillator Frequency vs Ambient Temperature



Equivalent Resistance vs Concentration of Several Solutions



Application Hints

The LM1830 requires only an external capacitor to complete the oscillator circuit. The frequency of oscillation is inversely proportional to the external capacitor value. Using 0.001 μ F capacitor, the output frequency is approximately 6 kHz. The output from the oscillator is available at pin 5. In normal applications, the output is taken from pin 13 so that the internal 13k resistor can be used to compare with the probe resistance. Pin13 is coupled to the probe by a blocking capacitor so that there is no net dc on the probe.

Since the output amplitude from the oscillator is approximately 4 V_{BE}, the detector (which is an emitter base junction) will be turned "ON" when the probe resistance to ground is equal to the internal 13 k Ω resistor. An internal diode across the detector emitter base junction provides symmetrical limiting of the detector input signal so that the probe is excited with ± 2 V_{BE} from a 13 k Ω source. In cases where the 13 k Ω resistor is not compatible with the probe resistance range, an external resistor may be added by coupling the probe to pin 5 through the external resistor as shown in *Figure 2*. The collector of the detecting transistor is brought out to pin 9 enabling a filter capacitor to be connected so that the output will switch "ON" or "OFF" depending on the probe resistance. If this capacitor is omitted, the output will be switched at approximately 50% duty cycle when the probe resistance exceeds the reference resistance. This can be useful when an audio output is required and the output transistor can be used to directly drive a loud speaker. In addition, LED indicators do not require dc excitation. Therefore, the cost of a capacitor for filtering can be saved.

In the case of inductive loads or incandescent lamp loads, it is recommended that a filter capacitor be employed.

In a typical application where the device is employed for sensing low water level in a tank, a simple steel probe may be inserted in the top of the tank with the tank grounded. Then when the water level drops below the tip of the probe, the resistance will rise between the probe and the tank and the alarm will be operated. This is illustrated in *Figure 3*. In situations where a non-conductive container is used, the probe may be designed in a number of ways. In some cases a simple phono plug can be employed. Other probe designs include conductive parallel strips on printed circuit boards.

It is possible to calculate the resistance of any aqueous solution of an electrolyte for different concentrations, provided the dimensions of the electrodes and their spacing is known.

The resistance of a simple parallel plate probe is given by:

$$R = \frac{1000}{c \cdot p} \cdot \frac{d}{A} \quad \Omega$$

where A = area of plates (cm²)
 d = separation of plates (cm)
 c = concentration (gm. mol. equivalent/litre)
 p = equivalent conductance
 (Ω^{-1} cm² equiv.⁻¹)

(An equivalent is the number of moles of a substance that gives one mole of positive charge and one mole of negative charge. For example, one mole of NaCl gives Na⁺ + Cl⁻ so the equivalent is 1. One mole of CaCl₂ gives Ca⁺⁺ + 2Cl⁻ so the equivalent is 1/2.)

Usually the probe dimensions are not measured physically, but the ratio d/A is determined by measuring the resistance of a cell of known concentration c and equivalent conductance of 1. A graph of common solutions and their equivalent conductances is shown for reference. The data was derived from D.A. MacInnes, "The Principles of Electrochemistry," Reinhold Publishing Corp., New York., 1939.

In automotive and other applications where the power source is known to contain significant transient voltages, the internal regulator on the LM1830 allows protection to be provided by the simple means of using a series resistor in the power supply line as illustrated in *Figure 4*. If the output load is required to be returned directly to the power supply because of the high current required, it will be necessary to provide protection for the output transistor if the voltages are expected to exceed the data sheet limits.

Although the LM1830 is designed primarily for use in sensing conductive fluids, it can be used with any variable resistance device, such as light dependent resistor or thermistor or resistive position transducer.

The following table lists some common fluids which may and may not be detected by resistive probe techniques.

| Conductive Fluids | Non-Conductive Fluids |
|--------------------------|-----------------------|
| City water | Pure water |
| Sea water | Gasoline |
| Copper sulphate solution | Oil |
| Weak acid | Brake fluid |
| Weak base | Alcohol |
| Household ammonia | Ethylene glycol |
| Water and glycol mixture | Paraffin |
| Wet soil | Dry soil |
| Coffee | Whiskey |

Application Hints (Continued)

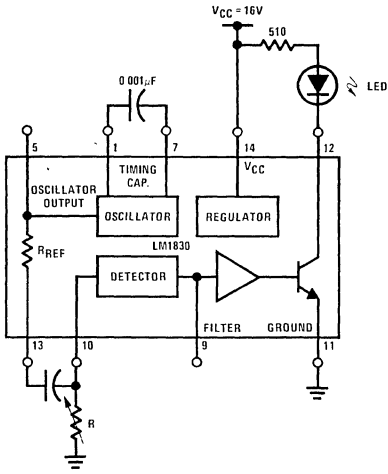


FIGURE 1. Test Circuit

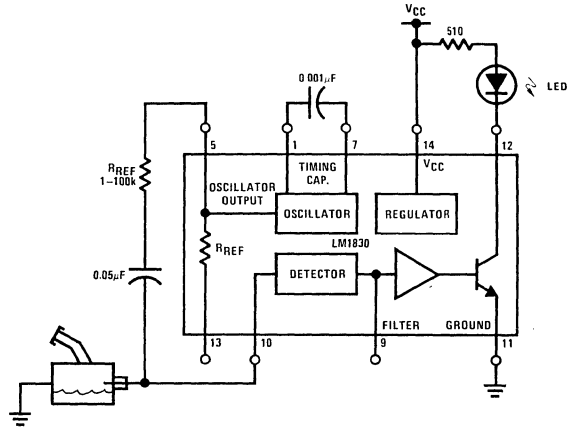


FIGURE 2. Application Using External Reference Resistor

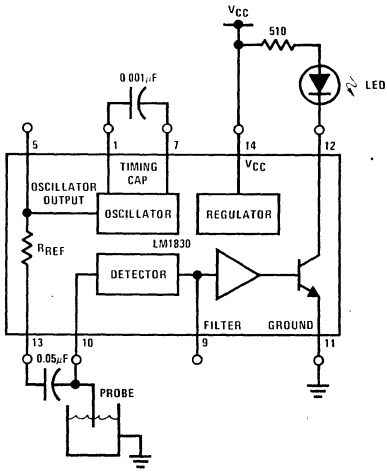
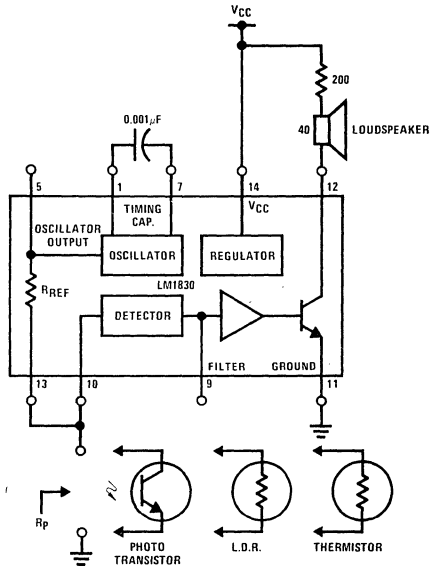


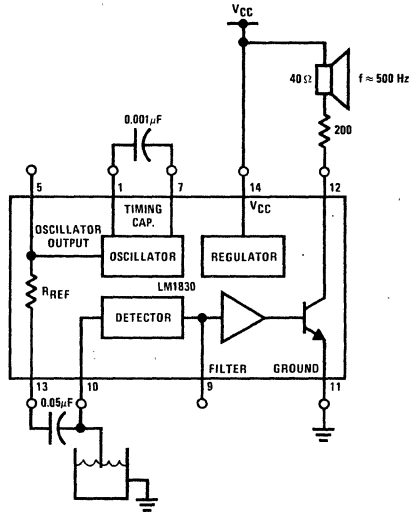
FIGURE 3. Basic Low Level Warning Device with LED Indication



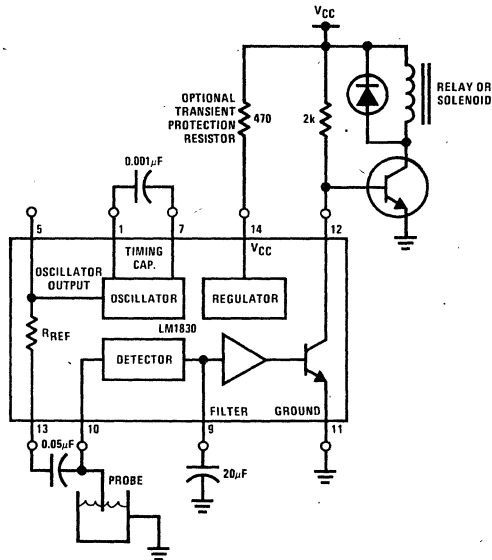
Output is activated when $R_p \approx 1/3 R_{REF}$

FIGURE 4. Direct Coupled Applications

Typical Applications



Low Level Warning with Audio Output



The output is suitable for driving a sump pump or opening a drain valve, etc.

High Level Warning Device

LM2877 Dual 4-Watt Power Audio Amplifier

General Description

The LM2877 is a monolithic dual power amplifier designed to deliver 4W/channel continuous into 8Ω loads. The LM2877 is designed to operate with a low number of external components, and still provide flexibility for use in stereo phonographs, tape recorders and AM-FM stereo receivers, etc. Each power amplifier is biased from a common internal regulator to provide high power supply rejection and output Q point centering. The LM2877 is internally compensated for all gains greater than 10, and comes in an 11-lead single-in-line package.

Features

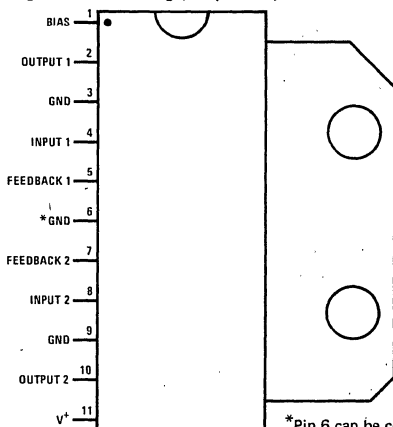
- 4W/channel
- -68 dB ripple rejection, output referred
- -70 dB channel separation, output referred

- Wide supply range, 6-24V
- Very low cross-over distortion
- Low audio band noise
- Internal current limiting, short circuit protection
- Internal thermal shutdown

Applications

- Multi-channel audio systems
- Stereo phonographs
- Tape recorders and players
- AM-FM radio receivers
- Servo amplifiers
- Intercom systems
- Automotive products

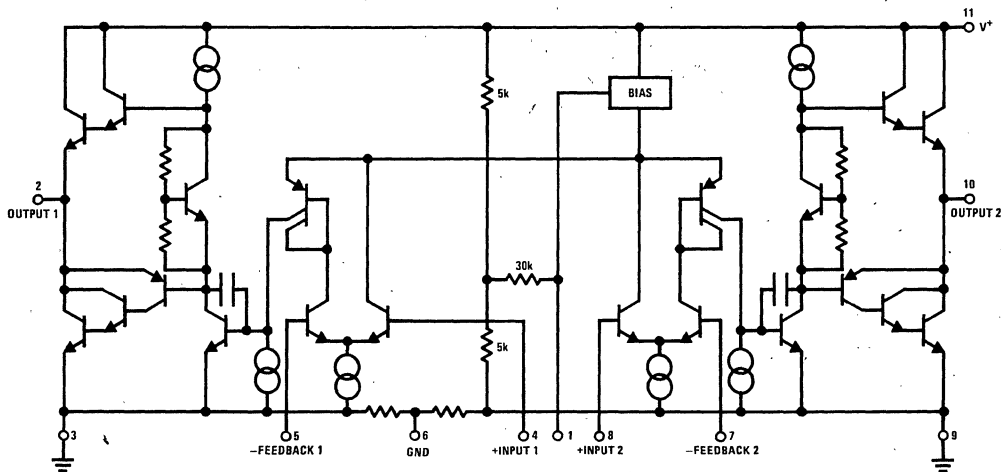
Connection Diagram (Single-In-Line Package, Top View)



Order Number LM2877P
See NS Package P11A

*Pin 6 can be connected to pin 3 or pin 9, if not, pin 6 must be left with NO connection.

Equivalent Schematic Diagram



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 26V |
| Input Voltage | ±0.7V |
| Operating Temperature | 0°C to +70°C |
| Storage Temperature | -65°C to +150°C |
| Junction Temperature | 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

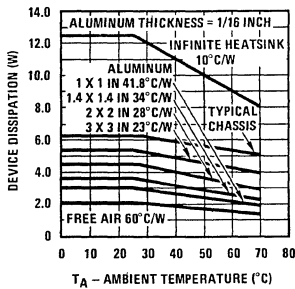
Electrical Characteristics $V_S = 20V$, $T_A = 25^\circ C$, $R_L = 8\Omega$, $A_V = 50$ (34 dB) unless otherwise specified

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------------|---|-----|-----------|-----|------------|
| Total Supply Current | $P_O = 0W$ | | 25 | 50 | mA |
| Operating Supply Voltage | | 6 | | 24 | V |
| Output Power/Channel | $f = 1 \text{ kHz}$, THD = 10% | | | | |
| | $V_S = 20V$ | 4.0 | 4.5 | | W |
| | $V_S = 18V$ | | 3.6 | | W |
| | $V_S = 12V$, $R_L = 4\Omega$ | 1.5 | 1.9 | | W |
| Distortion, THD | $f = 1 \text{ kHz}$, $V_S = 20V$ | | | | |
| | $P_O = 50 \text{ mW/Channel}$ | | 0.1 | | % |
| | $P_O = 1W/Channel$ | | 0.07 | | % |
| | $P_O = 2W/Channel$ | | 0.07 | 1 | % |
| | $f = 1 \text{ kHz}$, $V_S = 12V$, $R_L = 4\Omega$ | | | | |
| | $P_O = 50 \text{ mW/Channel}$ | | 0.25 | | % |
| | $P_O = 500 \text{ mW/Channel}$ | | 0.20 | | % |
| | $P_O = 1W/Channel$ | | 0.15 | 1 | % |
| Output Swing | $R_L = 8\Omega$ | | $V_S - 4$ | | Vp-p |
| Channel Separation | $C_F = 50 \mu F$, $C_{IN} = 0.1 \mu F$, $f = 1 \text{ kHz}$, Output Referred | | | | |
| | $V_S = 20V$, $V_O = 4 \text{ Vrms}$ | -50 | -70 | | dB |
| | $V_S = 7V$, $V_O = 0.5 \text{ Vrms}$ | | -60 | | dB |
| PSRR Power Supply Rejection Ratio | $C_F = 50 \mu F$, $C_{IN} = 0.1 \mu F$, $f = 120 \text{ Hz}$, Output Referred | | | | |
| | $V_S = 20V$, $V_{RIPPLE} = 1 \text{ Vrms}$ | -50 | -68 | | dB |
| | $V_S = 7V$, $V_{RIPPLE} = 0.5 \text{ Vrms}$ | | -40 | | dB |
| Noise | Equivalent Input Noise | | | | |
| | $R_S = 0$, $C_{IN} = 0.1 \mu F$, $BW = 20 \text{ Hz} - 20 \text{ kHz}$ | | 2.5 | | μV |
| | Output Noise Wideband | | | | |
| | $R_S = 0$, $C_{IN} = 0.1 \mu F$, $A_V = 200$ | | 0.80 | | mV |
| Open Loop Gain | $R_S = 0$, $f = 1 \text{ kHz}$, $R_L = 8\Omega$ | | 70 | | dB |
| Input Offset Voltage | | | 15 | | mV |
| Input Bias Current | | | 50 | | nA |
| Input Impedance | Open Loop | | 4 | | M Ω |
| DC Output Level | $V_S = 20V$ | 9 | 10 | 11 | V |
| Slew Rate | | | 2.0 | | V/ μs |
| Power Bandwidth | | | 65 | | kHz |
| Current Limit | | | 1.0 | | A |

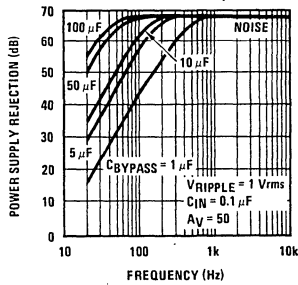
Note 1: For operation at ambient temperature greater than 25°C, the LM2877 must be derated based on a maximum 150°C junction temperature using a thermal resistance which depends upon device mounting techniques.

Typical Performance Characteristics

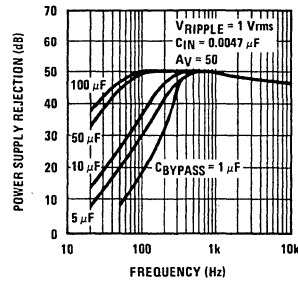
Device Dissipation vs Ambient Temperature



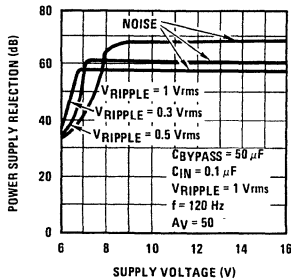
Power Supply Rejection Ratio (Referred to the Output) vs Frequency



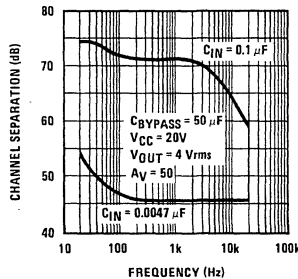
Power Supply Rejection Ratio (Referred to the Output) vs Frequency



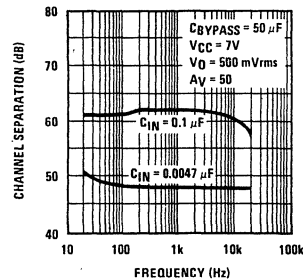
Power Supply Rejection Ratio (Referred to the Output) vs Supply Voltage



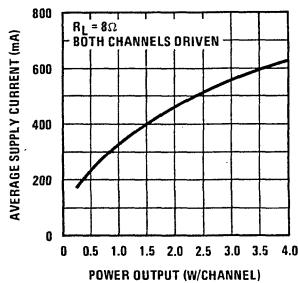
Channel Separation (Referred to the Output) vs Frequency



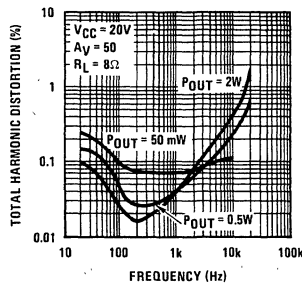
Channel Separation (Referred to the Output) vs Frequency



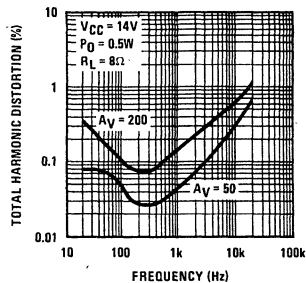
Average Supply Current vs Power Output



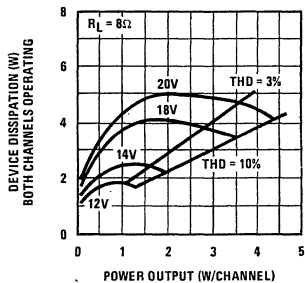
Total Harmonic Distortion vs Frequency



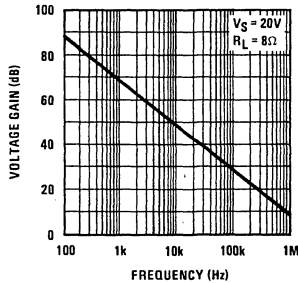
Total Harmonic Distortion vs Frequency



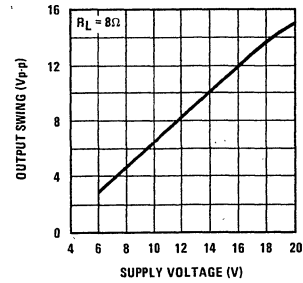
Power Dissipation vs Power Output



Open Loop Gain vs Frequency

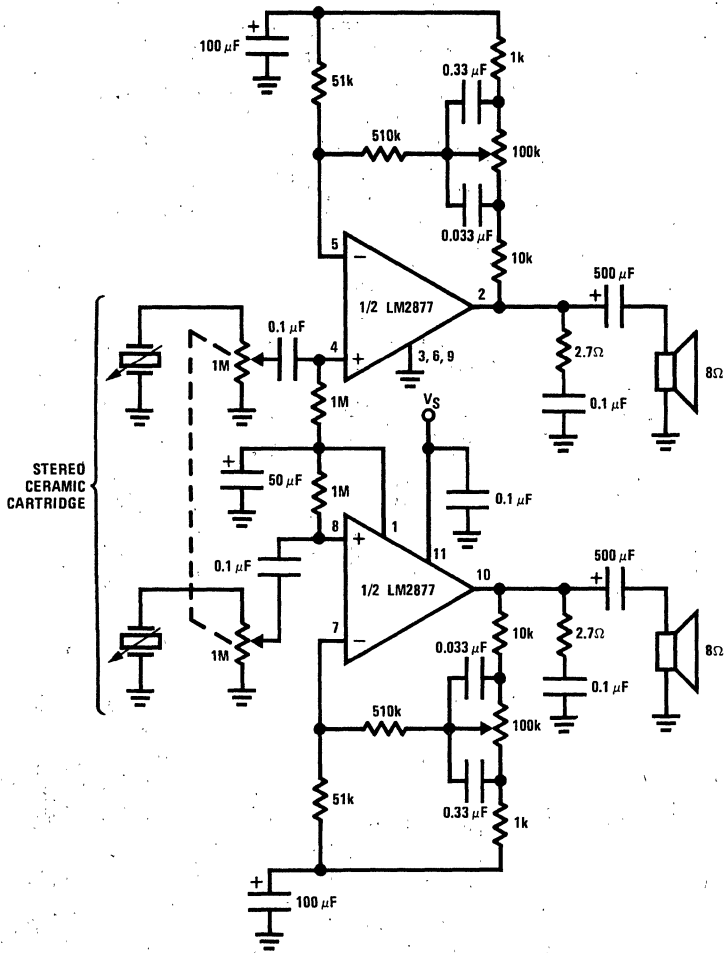


Output Swing vs Supply Voltage

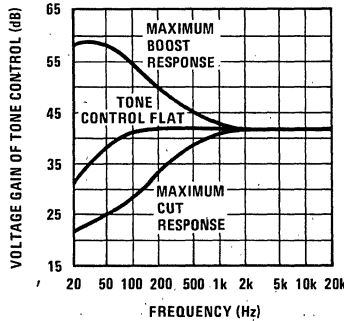


Typical Applications

Stereo Phonograph Amplifier with Bass Tone Control

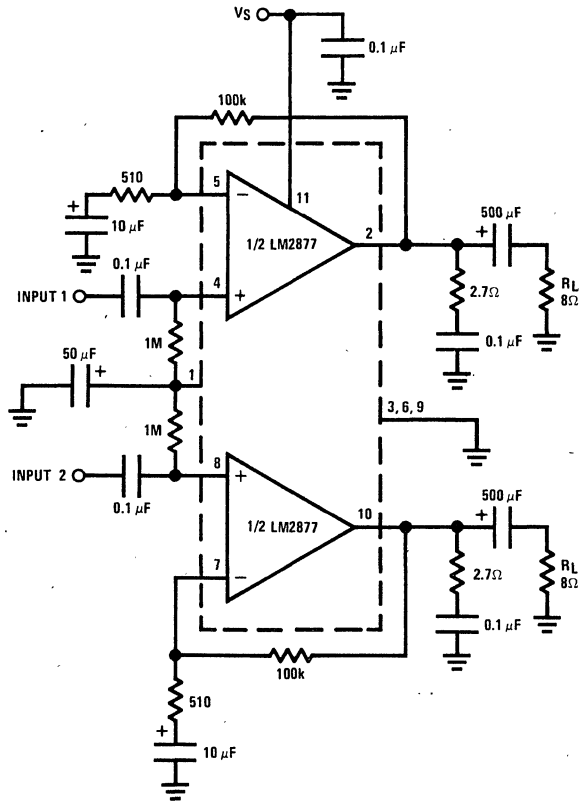


Frequency Response of Bass Tone Control

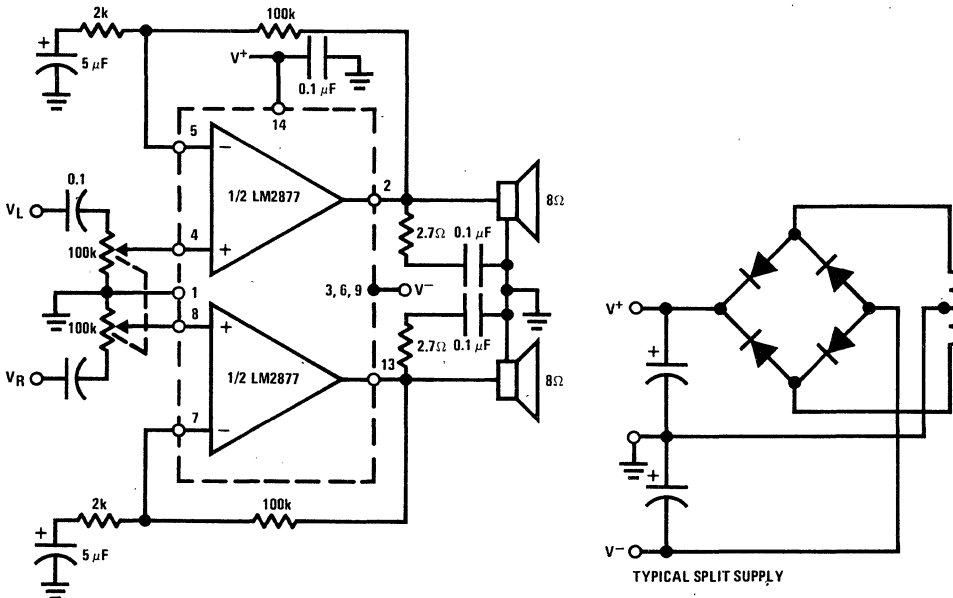


Typical Applications (Continued)

Stereo Amplifier with $A_v = 200$

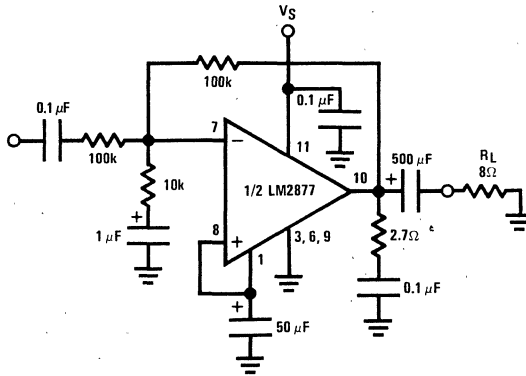


Non-Inverting Amplifier Using Split Supply



Typical Applications (Continued)

Inverting Unity Gain Amplifier



LM2907, LM2917 Frequency to Voltage Converter

General Description

The LM2907, LM2917 series are monolithic frequency to voltage converters with a high gain op amp/comparator designed to operate a relay, lamp, or other load when the input frequency reaches or exceeds a selected rate. The tachometer uses a charge pump technique and offers frequency doubling for low ripple, full input protection in two versions (LM2907-8, LM2917-8) and its output swings to ground for a zero frequency input.

(Continued on page 9-83)

Advantages

- Output swings to ground for zero frequency input
- Easy to use; $V_{OUT} = f_{IN} \times V_{CC} \times R1 \times C1$
- Only one RC network provides frequency doubling
- Zener regulator on chip allows accurate and stable frequency to voltage or current conversion. (LM2917)

Features

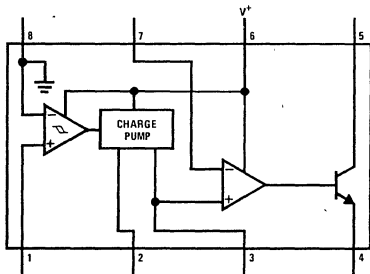
- Ground referenced tachometer input interfaces directly with variable reluctance magnetic pickups
- Op amp/comparator has floating transistor output
- 50 mA sink or source to operate relays, solenoids, meters, or LEDs

- Frequency doubling for low ripple
- Tachometer has built-in hysteresis with either differential input or ground referenced input
- Built-in zener on LM2917
- $\pm 0.3\%$ linearity typical
- Ground referenced tachometer is fully protected from damage due to swings above V_{CC} and below ground

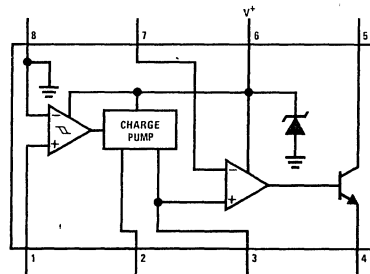
Applications

- Over/under speed sensing
- Frequency to voltage conversion (tachometer)
- Speedometers
- Breaker point dwell meters
- Hand-held tachometer
- Speed governors
- Cruise control
- Automotive door lock control
- Clutch control
- Horn control
- Touch or sound switches

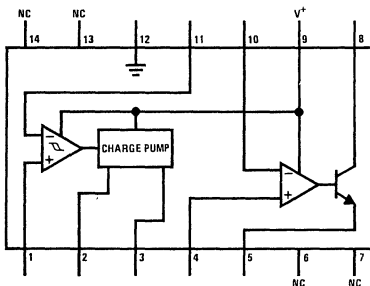
Block and Connection Diagrams Dual-In-Line Packages, Top Views



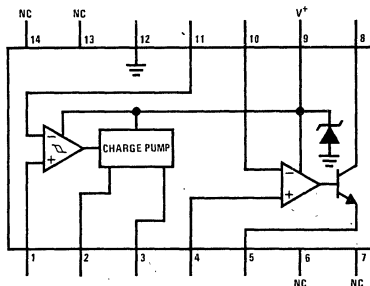
Order Number LM2907N-8
See NS Package N08B



Order Number LM2917N-8
See NS Package N08B



Order Number LM2907J
See NS Package J14A
Order Number LM2907N
See NS Package N14A



Order Number LM2917J
See NS Package J14A
Order Number LM2917N
See NS Package N14A

Absolute Maximum Ratings (Note 1)

| | |
|--------------------------------|-------|
| Supply Voltage | 28V |
| Supply Current (Zener Options) | 25 mA |
| Collector Voltage | 28V |
| Differential Input Voltage | |
| Tachometer | 28V |
| Op Amp/Comparator | 28V |

| | |
|--|-----------------|
| Input Voltage Range | |
| Tachometer LM2907-8, LM2917-8 | ±28V |
| LM2907, LM2917 | 0.0V to +28V |
| Op Amp/Comparator | 0.0V to +28V |
| Power Dissipation | 500 mW |
| Operating Temperature Range | -40°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $V_{CC} = 12 V_{DC}$, $T_A = 25^\circ C$, see test circuit

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------------------|--|------|------|-----------------|-------|
| TACHOMETER | | | | | |
| Input Thresholds | $V_{IN} = 250 \text{ mVp-p} @ 1 \text{ kHz}$ (Note 2) | ±10 | ±15 | ±40 | mV |
| Hysteresis | $V_{IN} = 250 \text{ mVp-p} @ 1 \text{ kHz}$ (Note 2) | | 30 | | mV |
| Offset Voltage | $V_{IN} = 250 \text{ mVp-p} @ 1 \text{ kHz}$ (Note 2) | | | | |
| LM2907/LM2917 | | | 3.5 | 10 | mV |
| LM2907-8/LM2917-8 | | | 5 | 15 | mV |
| Input Bias Current | $V_{IN} = \pm 50 \text{ mV}_{DC}$ | | 0.1 | 1 | μA |
| V_{OH} | $V_{IN} = +125 \text{ mV}_{DC}$ (Note 3) | | 8.3 | | V |
| Pin 2 | | | | | |
| V_{OL} | $V_{IN} = -125 \text{ mV}_{DC}$ (Note 3) | | 2.3 | | V |
| Output Current; I_2, I_3 | $V_2 = V_3 = 6.0V$ (Note 4) | 140 | 180 | 240 | μA |
| Leakage Current; I_3 | $I_2 = 0, V_3 = 0$ | | | 0.1 | μA |
| Gain Constant, K | (Note 3) | 0.9 | 1.0 | 1.1 | |
| Linearity | $f_{IN} = 1 \text{ kHz}, 5 \text{ kHz}, 10 \text{ kHz}$, (Note 5) | -1.0 | 0.3 | +1.0 | % |
| OP/AMP COMPARATOR | | | | | |
| V_{OS} | $V_{IN} = 6.0V$ | | 3 | 10 | mV |
| I_{BIAS} | $V_{IN} = 6.0V$ | | 50 | 500 | nA |
| Input Common-Mode Voltage | | 0 | | $V_{CC} - 1.5V$ | V |
| Voltage Gain | | | 200 | | V/mV |
| Output Sink Current | $V_C = 1.0$ | 40 | 50 | | mA |
| Output Source Current | $V_E = V_{CC} - 2.0$ | | 10 | | mA |
| Saturation Voltage | $I_{SINK} = 5 \text{ mA}$ | | 0.1 | 0.5 | V |
| | $I_{SINK} = 20 \text{ mA}$ | | | 1.0 | V |
| | $I_{SINK} = 50 \text{ mA}$ | | 1.0 | 1.5 | V |
| ZENER REGULATOR | | | | | |
| Regulator Voltage | $R_{DROP} = 470\Omega$ | | 7.56 | | V |
| Series Resistance | | | 10.5 | 15 | Ω |
| Temperature Stability | | | +1 | | mV/°C |
| TOTAL SUPPLY CURRENT | | | 3.8 | 6 | mA |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient for package 22 and 16 or a thermal resistance of 187°C/W junction to ambient for package 20.

Note 2: Hysteresis is the sum $+V_{TH} - (-V_{TH})$, offset voltage is their difference. See test circuit.

Note 3: V_{OH} is equal to $3/4 \times V_{CC} - 1 V_{BE}$, V_{OL} is equal to $1/4 \times V_{CC} - 1 V_{BE}$ therefore $V_{OH} - V_{OL} = V_{CC}/2$. The difference, $V_{OH} - V_{OL}$, and the mirror gain, I_2/I_3 , are the two factors that cause the tachometer gain constant to vary from 1.0.

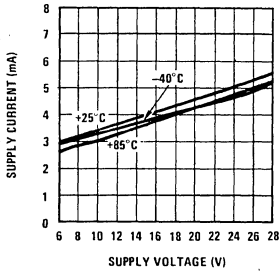
Note 4: Be sure when choosing the time constant $R1 \times C1$ that $R1$ is such that the maximum anticipated output voltage at pin 3 can be reached with $I_3 \times R1$. The maximum value for $R1$ is limited by the output resistance of pin 3 which is greater than 10 MΩ typically.

Note 5: Nonlinearity is defined as the deviation of V_{OUT} (@ pin 3) for $f_{IN} = 5 \text{ kHz}$ from a straight line defined by the V_{OUT} @ 1 kHz and V_{OUT} @ 10 kHz. $C1 = 1000 \text{ pF}$, $R1 = 68k$ and $C2 = 0.22 \text{ mFd}$.

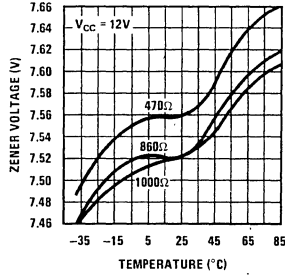
Typical Performance Characteristics

LM2907, LM2917

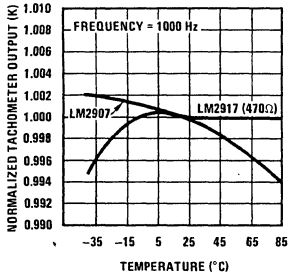
Total Supply Current



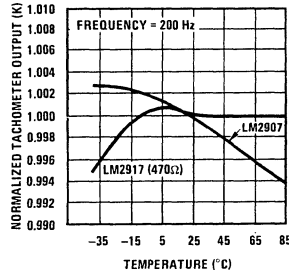
Zener Voltage vs Temperature



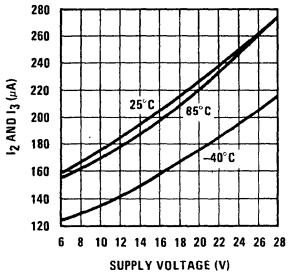
Normalized Tachometer Output vs Temperature



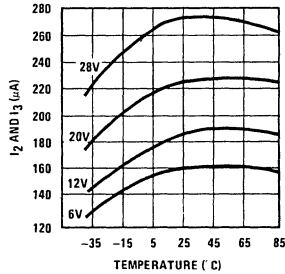
Normalized Tachometer Output vs Temperature



Tachometer Currents I₂ and I₃ vs Supply Voltage

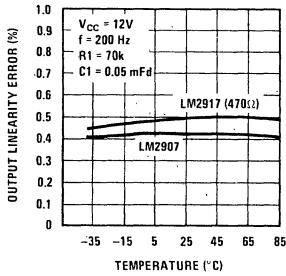


Tachometer Currents I₂ and I₃ vs Temperature

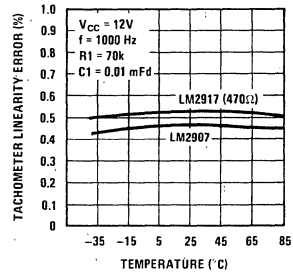


Typical Performance Characteristics (Continued)

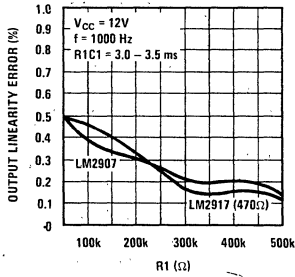
Tachometer Linearity vs Temperature



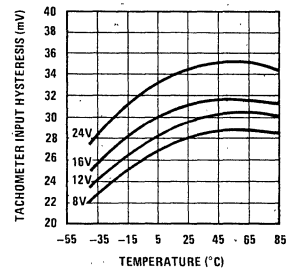
Tachometer Linearity vs Temperature



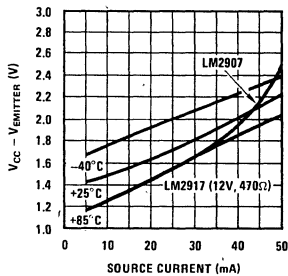
Tachometer Linearity vs R1



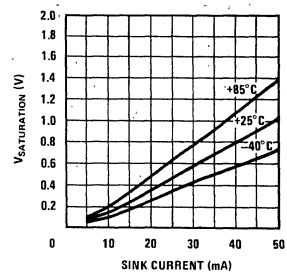
Tachometer Input Hysteresis vs Temperature



Op Amp Output Transistor Characteristics



Op Amp Output Transistor Characteristics



General Description (Continued)

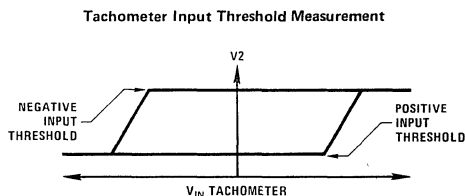
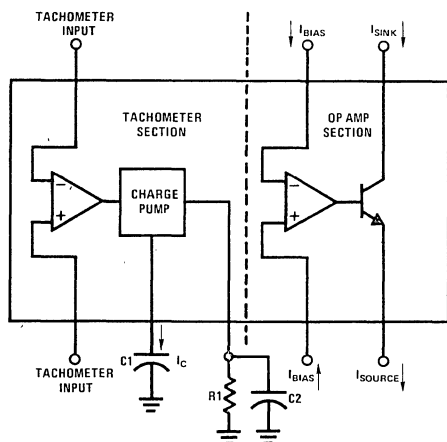
The op amp/comparator is fully compatible with the tachometer and has a floating transistor as its output. This feature allows either a ground or supply referred load of up to 50 mA. The collector may be taken above V_{CC} up to a maximum V_{CE} of 28V.

The two basic configurations offered include an 8-pin device with a *ground referenced tachometer* input and an internal connection between the tachometer output and the op amp non-inverting input. This version is well suited for single speed or frequency switching or fully buffered frequency to voltage conversion applications.

The more versatile configurations provide differential tachometer input and uncommitted op amp inputs. With this version the tachometer input may be floated and the op amp becomes suitable for active filter conditioning of the tachometer output.

Both of these configurations are available with an active shunt regulator connected across the power leads. The regulator clamps the supply such that stable frequency to voltage and frequency to current operations are possible with any supply voltage and a suitable resistor.

Test Circuit and Waveform



Applications Information

The LM2907 series of tachometer circuits is designed for minimum external part count applications and maximum versatility. In order to fully exploit its features and advantages let's examine its theory of operation. The first stage of operation is a differential amplifier driving a positive feedback flip-flop circuit. The input threshold voltage is the amount of differential input voltage at which the output of this stage changes state. Two options (LM2907-8, LM2917-8) have one input internally grounded so that an input signal must swing above and below ground and exceed the input thresholds to produce an output. This is offered specifically for magnetic variable reluctance pickups which typically provide a single-ended ac output. This single input is also fully protected against voltage swings to $\pm 28V$, which are easily attained with these types of pickups.

The differential input options (LM2907, LM2917) give the user the option of setting his own input switching level and still have the hysteresis around that level for excellent noise rejection in any application. Of course in order to allow the inputs to attain common-mode voltages above ground, input protection is removed

and neither input should be taken outside the limits of the supply voltage being used. It is very important that an input not go below ground without some resistance in its lead to limit the current that will then flow in the epi-substrate diode.

Following the input stage is the charge pump where the input frequency is converted to a dc voltage. To do this requires one timing capacitor, one output resistor, and an integrating or filter capacitor. When the input stage changes state (due to a suitable zero crossing or differential voltage on the input) the timing capacitor is either charged or discharged linearly between two voltages whose difference is $V_{CC}/2$. Then in one half cycle of the input frequency or a time equal to $1/2 f_{IN}$ the change in charge on the timing capacitor is equal to $V_{CC}/2 \times C1$. The average amount of current pumped into or out of the capacitor then is:

$$\frac{\Delta Q}{T} = i_{c(AVG)} = C1 \times \frac{V_{CC}}{2} \times (2f_{IN}) = V_{CC} \times f_{IN} \times C1$$

The output circuit mirrors this current very accurately into the load resistor R1, connected to ground, such that if the pulses of current are integrated with a filter

Applications Information (Continued)

capacitor, then, $V_o = i_c \times R1$, and the total conversion equation becomes:

$$V_o = V_{CC} \times f_{IN} \times C1 \times R1 \times K$$

Where K is the gain constant—typically 1.0.

The size of C2 is dependent only on the amount of ripple voltage allowable and the required response time.

CHOOSING R1 AND C1

There are some limitations on the choice of R1 and C1 which should be considered for optimum performance. The timing capacitor also provides internal compensation for the charge pump and should be kept larger than 100 pF for very accurate operation. Smaller values can cause an error current on R1, especially at low temperatures. Several considerations must be met when choosing R1. The output current at pin 3 is internally fixed and therefore $V_o/R1$ must be less than or equal to this value. If R1 is too large, it can become a significant fraction of the output impedance at pin 3 which degrades linearity. Also output ripple voltage must be considered and the size of C2 is affected by R1. An expression that describes the ripple content on pin 3 for a single R1C2 combination is:

$$V_{RIPPLE} = \frac{V_{CC}}{2} \times \frac{C1}{C2} \times \left(1 - \frac{V_{CC} \times f_{IN} \times C1}{I_2}\right) \text{ pK-pK}$$

It appears R1 can be chosen independent of ripple,

however response time, or the time it takes V_{OUT} to stabilize at a new voltage increases as the size of C2 increases so a compromise between ripple, response time, and linearity must be chosen carefully.

As a final consideration, the maximum attainable input frequency is determined by V_{CC} , C1 and I_2 :

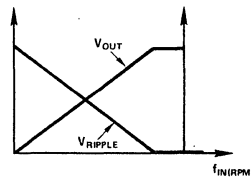
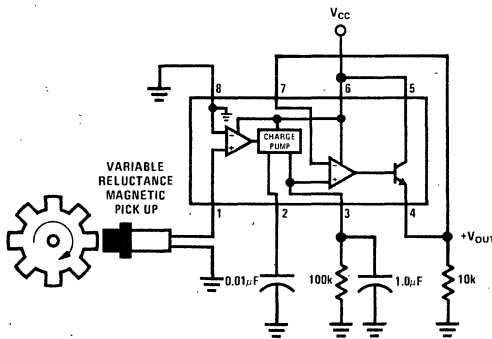
$$f_{MAX} = \frac{I_2}{C1 \times V_{CC}}$$

USING ZENER REGULATED OPTIONS (LM2917)

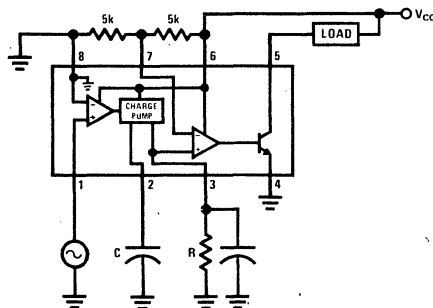
For those applications where an output voltage or current must be obtained independent of supply voltage variations, the LM2917 is offered. The most important consideration in choosing a dropping resistor from the unregulated supply to the device is that the tachometer and op amp circuitry alone require about 3 mA at the voltage level provided by the zener. At low supply voltages there must be some current flowing in the resistor above the 3 mA circuit current to operate the regulator. As an example, if the raw supply varies from 9 to 16V, a resistance of 470Ω will minimize the zener voltage variation to 160 mV. If the resistance goes under 400Ω or over 600Ω the zener variation quickly rises above 200 mV for the same input variation.

Typical Applications

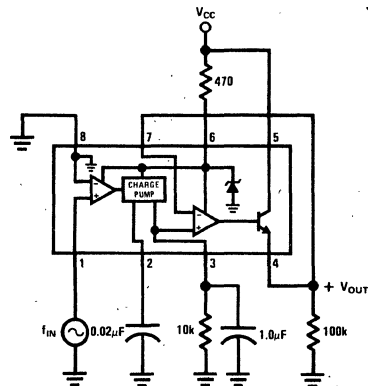
Minimum Component Tachometer



"Speed Switch" Load is Energized When $f_{IN} \geq \frac{1}{2RC}$

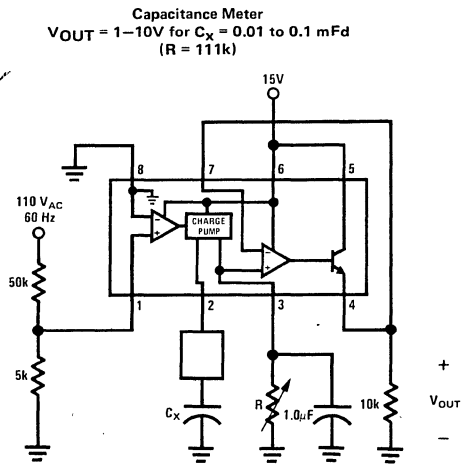
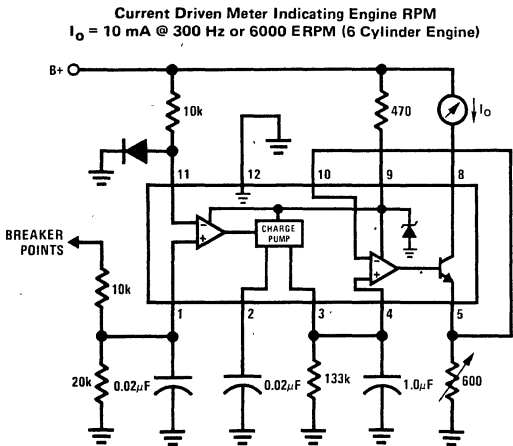
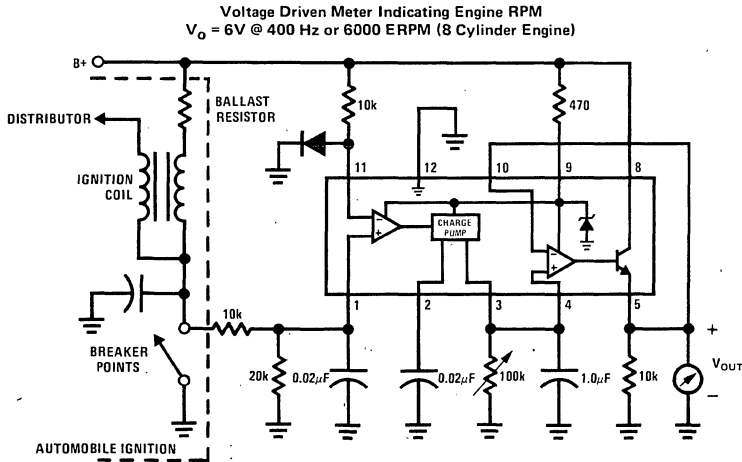
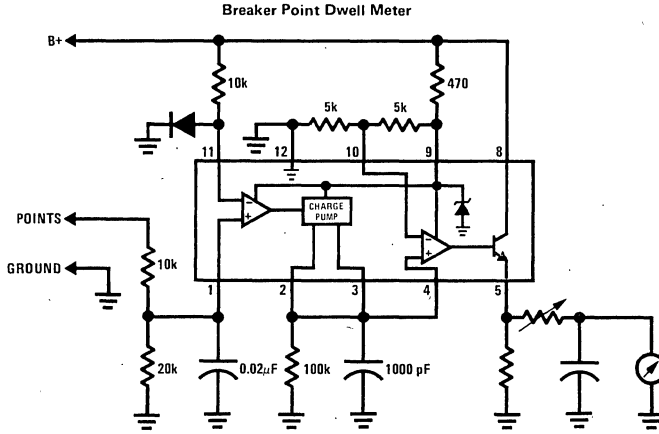


Zener Regulated Frequency to Voltage Converter



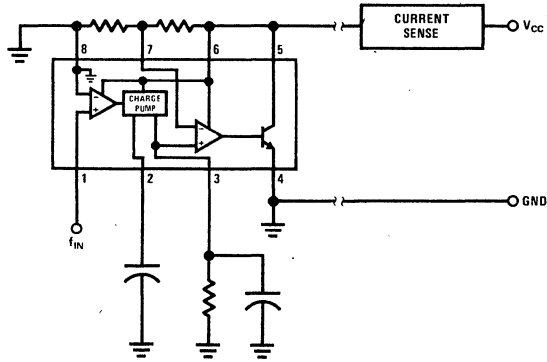
Typical Applications (Continued)

LM2907, LM2917

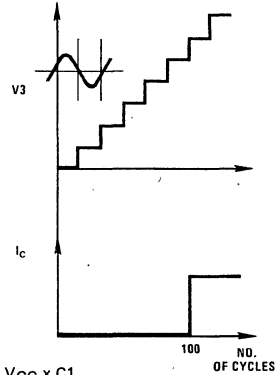
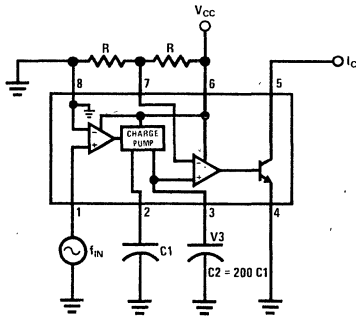


Typical Applications (Continued)

Two-Wire Remote Speed Switch



100 Cycle Delay Switch



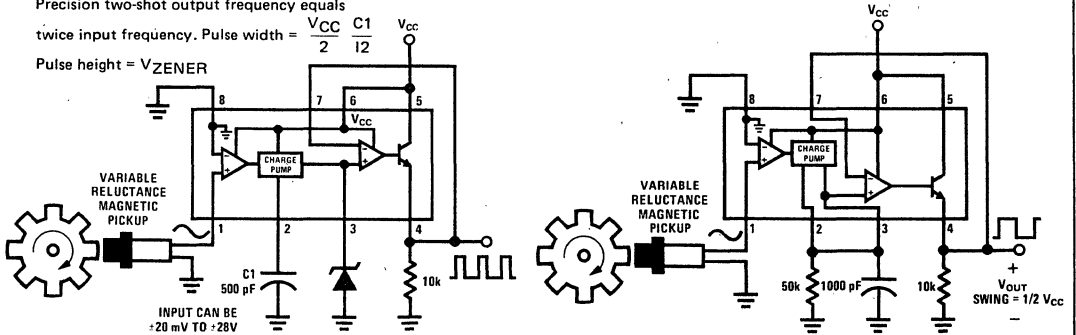
$V3$ steps up in voltage by the amount $\frac{V_{CC} \times C1}{C2}$ for each complete input cycle (2 zero crossings)
 Example:
 If $C2 = 200 C1$ after 100 consecutive input cycles.
 $V3 = 1/2 V_{CC}$

Variable Reluctance Magnetic Pickup Buffer Circuits

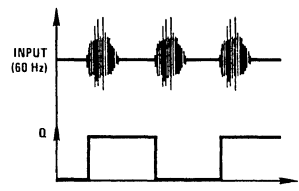
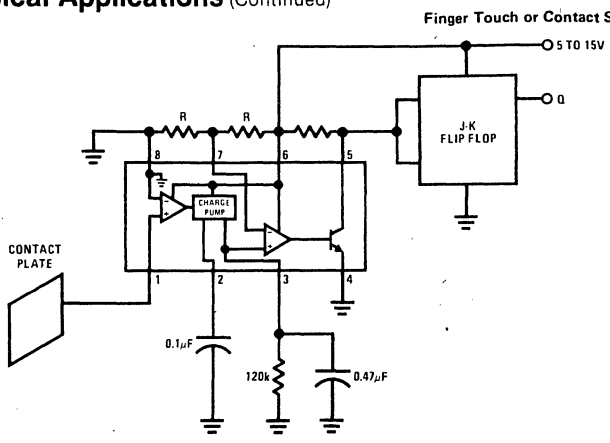
Precision two-shot output frequency equals

twice input frequency. Pulse width = $\frac{V_{CC}}{2} \frac{C1}{I2}$

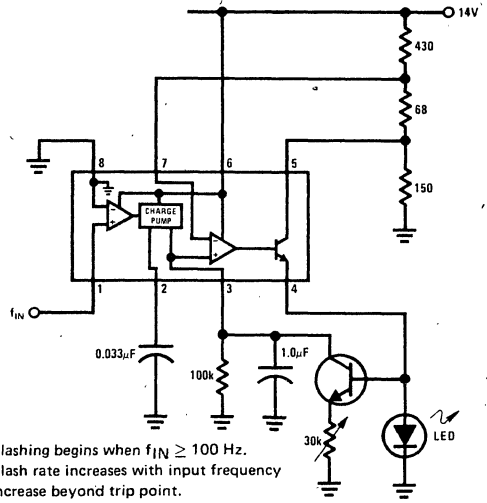
Pulse height = V_{ZENER}



Typical Applications (Continued)

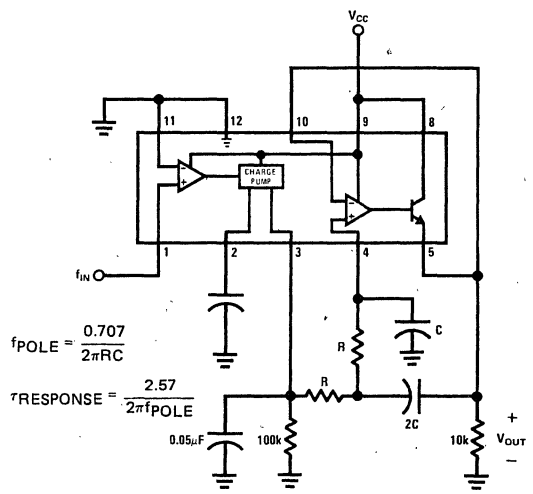


Flashing LED Indicates Overspeed



Flashing begins when $f_{IN} \geq 100$ Hz.
Flash rate increases with input frequency increase beyond trip point.

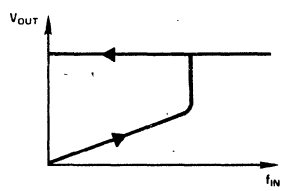
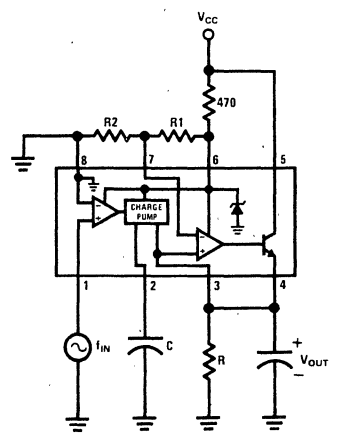
Frequency to Voltage Converter with 2 Pole Butterworth Filter to Reduce Ripple



$$f_{POLE} = \frac{0.707}{2\pi RC}$$

$$\tau_{RESPONSE} = \frac{2.57}{2\pi f_{POLE}}$$

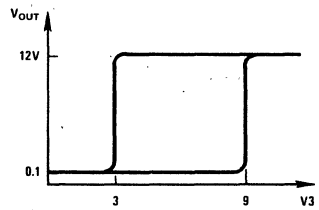
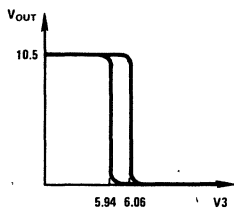
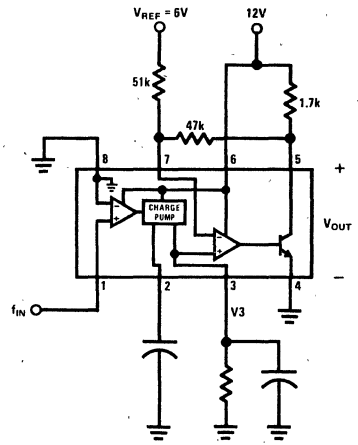
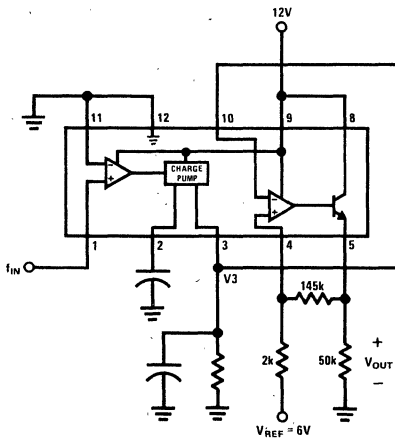
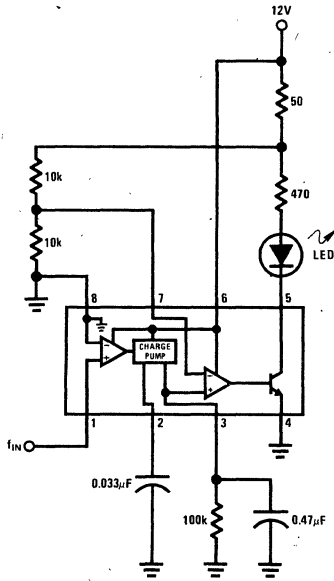
Overspeed Latch



Output latches when
 $f_{IN} = \frac{R2}{R1 + R2} \frac{1}{RC}$
Reset by removing V_{CC} .

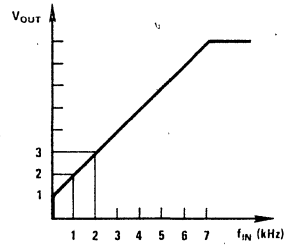
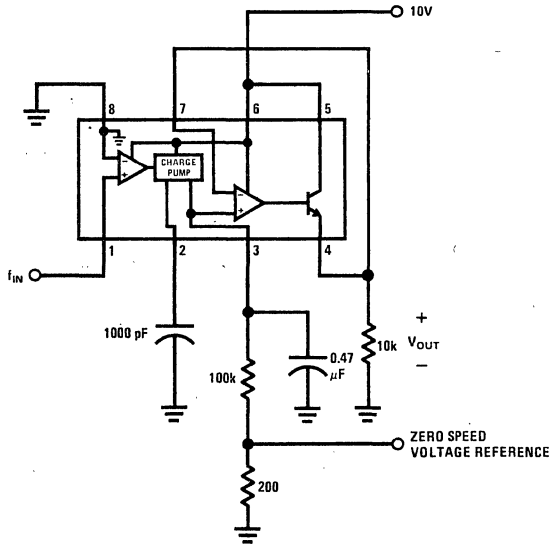
Typical Applications (Continued)

Some Frequency Switch Applications May Require Hysteresis in the Comparator Function Which Can Be Implemented in Several Ways:

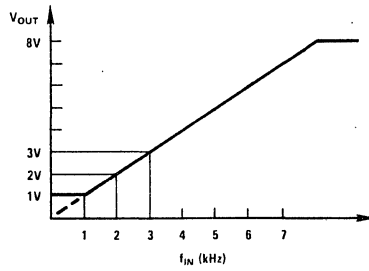
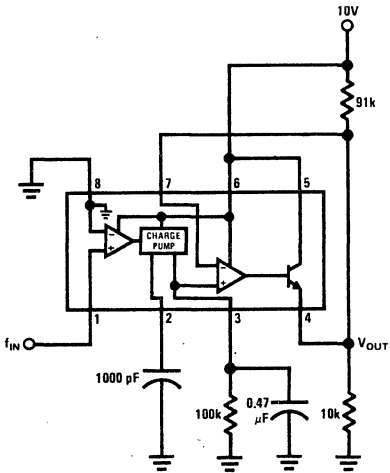


Typical Applications (Continued)

Changing the Output Voltage for an Input Frequency of Zero

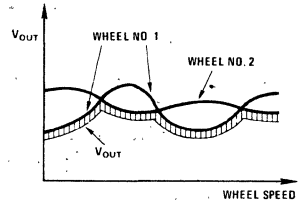
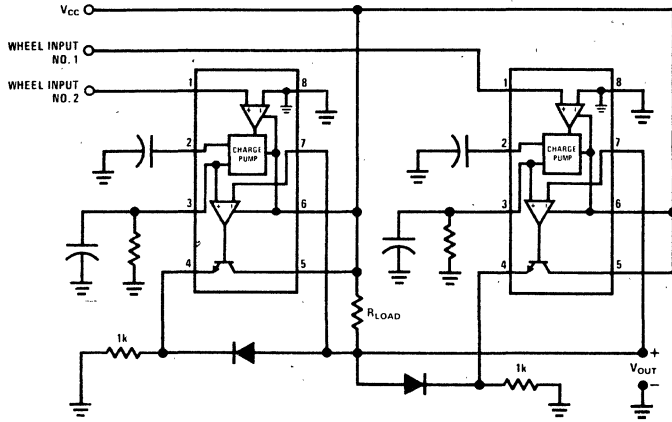


Changing Tachometer Gain Curve or Clamping the Minimum Output Voltage



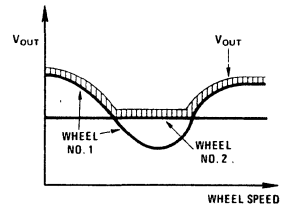
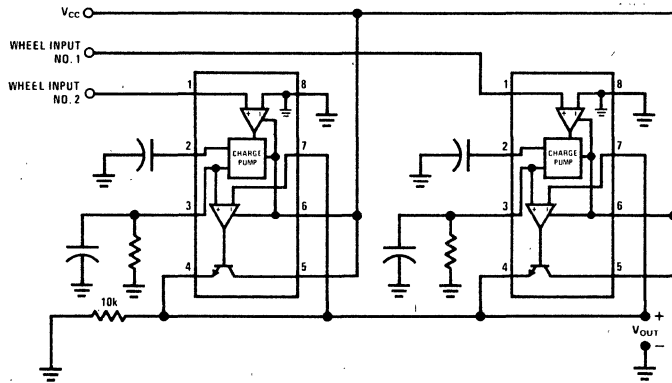
Anti-Skid Circuit Functions

"Select-Low" Circuit



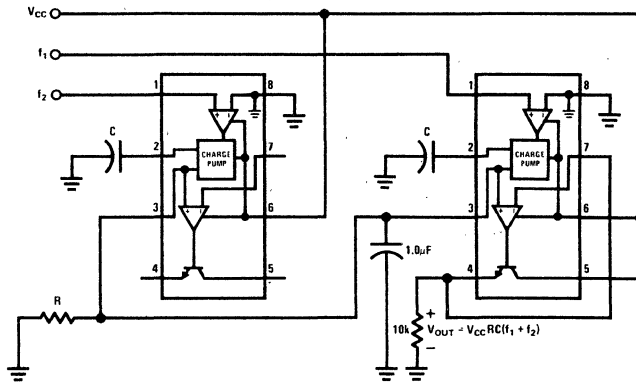
V_{OUT} is proportional to the lower of the two input wheel speeds.

"Select-High" Circuit

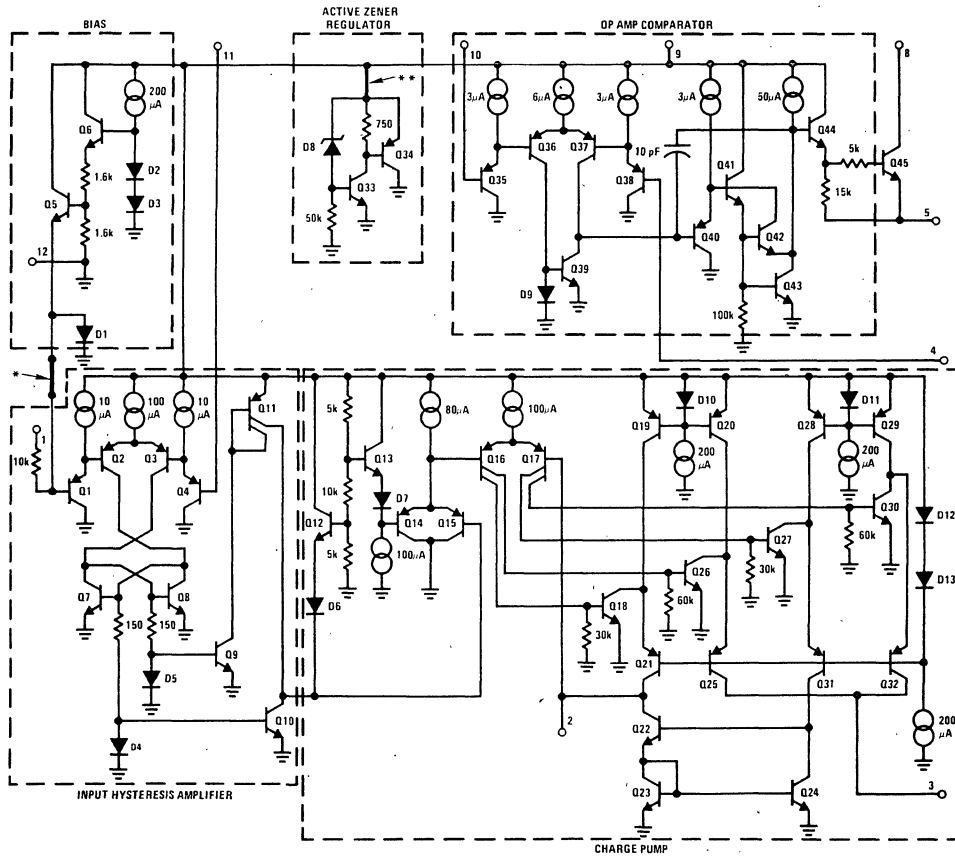


V_{OUT} is proportional to the higher of the two input wheel speeds.

"Select-Average" Circuit



Equivalent Schematic Diagram



* Note: This connection made on LM2907-8 and LM2917-8 only.

** Note: This connection made on LM2917 and LM2917-8 only.



LM3080/LM3080A Operational Transconductance Amplifier

General Description

The LM3080 is a programmable transconductance block intended to fulfill a wide variety of variable gain applications. The LM3080 has differential inputs and high impedance push-pull outputs. The device has high input impedance and its transconductance (gm) is directly proportional to the amplifier bias current (I_{ABC}).

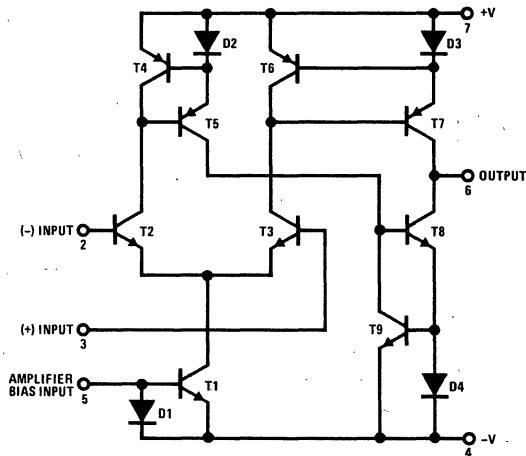
High slew rate together with programmable gain make the LM3080 an ideal choice for variable gain applications such as sample and hold, multiplexing, filtering, and multiplying.

The LM3080AH and LM3080AJ are guaranteed over the temperature range -55°C to $+125^{\circ}\text{C}$; the LM3080N, LM3080H, LM3080AN and LM3080J are guaranteed from 0°C to $+70^{\circ}\text{C}$.

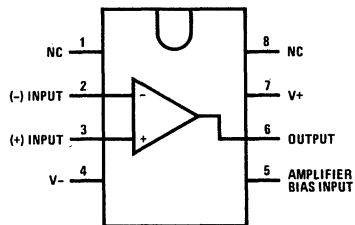
Features

- Slew Rate (unity gain compensated): $50\text{ V}/\mu\text{s}$
- Fully Adjustable Gain: 0 to $gm R_L$ limit
- Extended gm Linearity: 3 decades
- Flexible Supply Voltage Range: $\pm 2\text{V}$ to $\pm 18\text{V}$
- Adjustable Power Consumption

Schematic and Connection Diagrams



Dual-In-Line Package



TOP VIEW

Order Number LM3080AJ or LM3080J
See NS Package J08A
Order Number LM3080AN
See NS Package N08B

Absolute Maximum Ratings

| | |
|--|--------------------|
| Supply Voltage (Note 2) | |
| LM3080 | ±18 V |
| LM3080A | ±22 V |
| Power Dissipation | 250 mW |
| Differential Input Voltage | ±5 V |
| Amplifier Bias Current (I_{ABC}) | 2 mA |
| DC Input Voltage | + V_S to - V_S |
| Output Short Circuit Duration | Indefinite |
| Operating Temperature Range | |
| LM3080N, LM3080H, LM3080AN | |
| or LM3080J | 0°C to +70°C |
| LM3080AH or LM3080AJ | -55°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

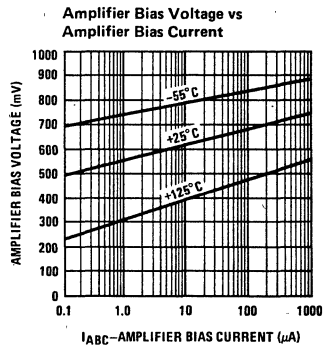
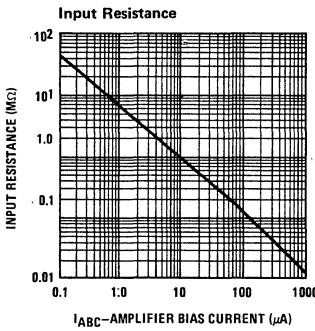
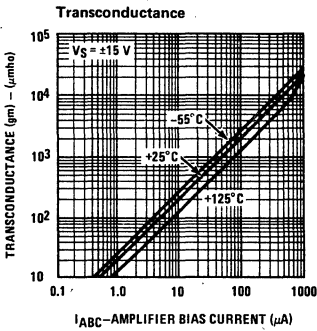
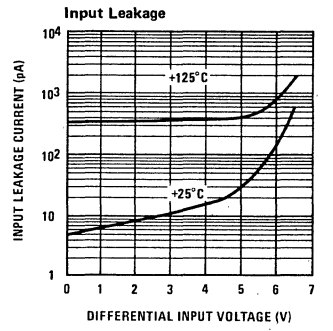
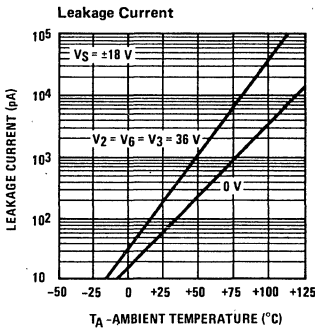
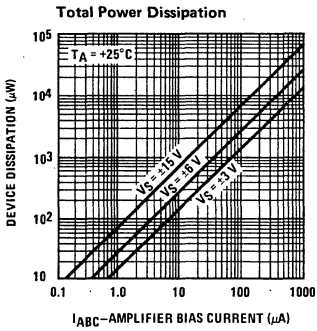
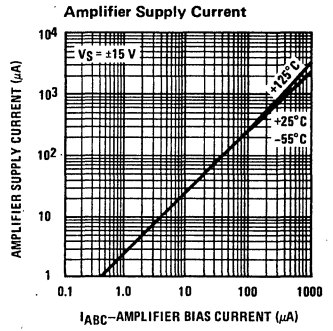
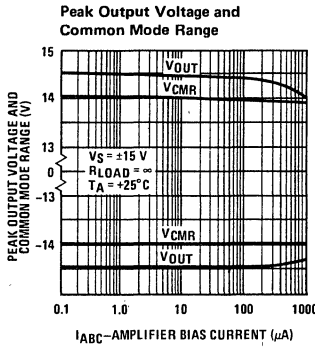
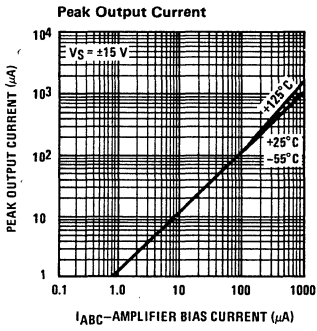
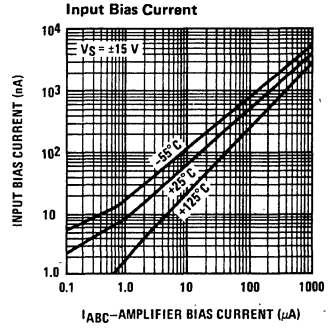
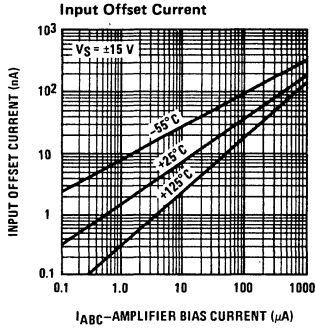
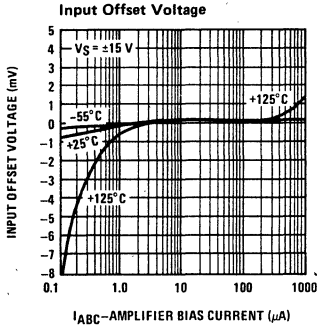
Electrical Characteristics (Note 1)

| Parameter | Conditions | LM3080 | | | LM3080A | | | Units |
|----------------------------------|---|--------|-------|-------|---------|-------|-------|------------|
| | | Min. | Typ. | Max. | Min. | Typ. | Max. | |
| Input Offset Voltage | Over Specified Temperature Range | | 0.4 | 5 | | 0.4 | 2 | mV |
| | $I_{ABC} = 5 \mu A$ | | | 6 | | | 5 | mV |
| Input Offset Voltage Change | $5 \mu A \leq I_{ABC} \leq 500 \mu A$ | | 0.3 | | | 0.3 | 2 | mV |
| | | | 0.1 | | | 0.1 | 3 | mV |
| Input Offset Current | | | 0.1 | 0.6 | | 0.1 | 0.6 | μA |
| Input Bias Current | Over Specified Temperature Range | | 0.4 | 5 | | 0.4 | 5 | μA |
| | | | 1 | 7 | | 1 | 8 | μA |
| Forward Transconductance (gm) | | 6700 | 9600 | 13000 | 7700 | 9600 | 12000 | μmho |
| | Over Specified Temperature Range | 5400 | | | 4000 | | | μmho |
| Peak Output Current | $R_L = 0, I_{ABC} = 5 \mu A$ | | 5 | | 3 | 5 | 7 | μA |
| | $R_L = 0$ | 350 | 500 | 650 | 350 | 500 | 650 | μA |
| | Over Specified Temperature Range | 300 | | | 300 | | | μA |
| Peak Output Voltage | $R_L = \infty, 5 \mu A \leq I_{ABC} \leq 500 \mu A$ | +12 | +14.2 | | +12 | +14.2 | | V |
| | $R_L = \infty, 5 \mu A \leq I_{ABC} \leq 500 \mu A$ | -12 | -14.4 | | -12 | -14.4 | | V |
| Amplifier Supply Current | | | 1.1 | | | 1.1 | | mA |
| Input Offset Voltage Sensitivity | Positive | | 20 | 150 | | 20 | 150 | $\mu V/V$ |
| | Negative | | 20 | 150 | | 20 | 150 | $\mu V/V$ |
| Common Mode Rejection Ratio | | 80 | 110 | | 80 | 110 | | dB |
| Common Mode Range | | ±12 | ±14 | | ±12 | ±14 | | V |
| Input Resistance | | 10 | 26 | | 10 | 26 | | k Ω |
| Magnitude of Leakage Current | $I_{ABC} = 0$ | | 0.2 | 100 | | 0.2 | 5 | nA |
| Differential Input Current | $I_{ABC} = 0, Input = \pm 4 V$ | | 0.02 | 100 | | 0.02 | 5 | nA |
| Open Loop Bandwidth | | | 2 | | | 2 | | MHz |
| Slew Rate | Unity Gain Compensated | | 50 | | | 50 | | V/ μs |

Note 1: These specifications apply for $V_S = \pm 15 V$ and $T_A = 25^\circ C$, amplifier bias current (I_{ABC}) = 500 μA , unless otherwise specified.

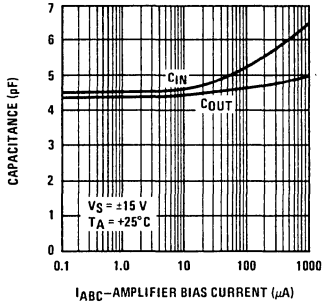
Note 2: Selections to supply voltage above ±22V, contact the factory.

Typical Performance Characteristics

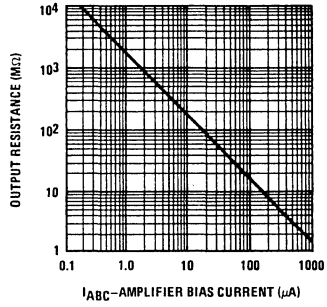


Typical Performance Characteristics (Continued)

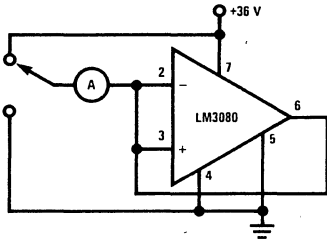
Input and Output Capacitance



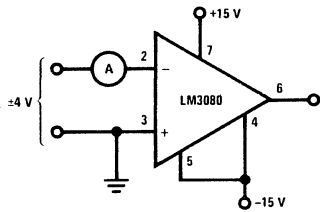
Output Resistance



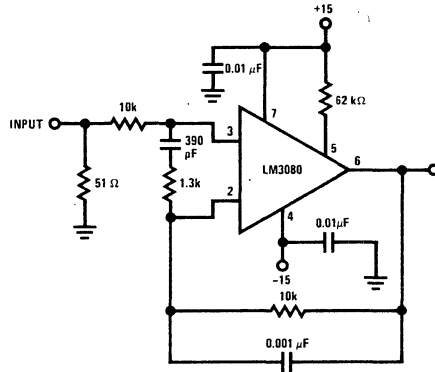
Leakage Current Test Circuit



Differential Input Current Test Circuit



Unity Gain Follower



LM3909 LED Flasher/Oscillator

General Description

The LM3909 is a monolithic oscillator specifically designed to flash Light Emitting Diodes. By using the timing capacitor for voltage boost, it delivers pulses of 2 or more volts to the LED while operating on a supply of 1.5V or less. The circuit is inherently self-starting, and requires addition of only a battery and capacitor to function as a LED flasher.

Packaged in an 8-lead plastic mini-DIP, the LM3909 will operate over the extended consumer temperature range of -25°C to $+70^{\circ}\text{C}$. It has been optimized for low power drain and operation from weak batteries so that continuous operation life exceeds that expected from battery rating.

Application is made simple by inclusion of internal timing resistors and an internal LED current limit resistor. As shown in the first two application circuits, the timing resistors supplied are optimized for nominal flashing rates and minimum power drain at 1.5V and 3V.

Timing capacitors will generally be of the electrolytic type, and a small 3V rated part will be suitable for any LED flasher using a supply up to 6V. However, when picking flash rates, it should be remembered that some electrolytics have very broad capacitance tolerances, for example -20% to $+100\%$.

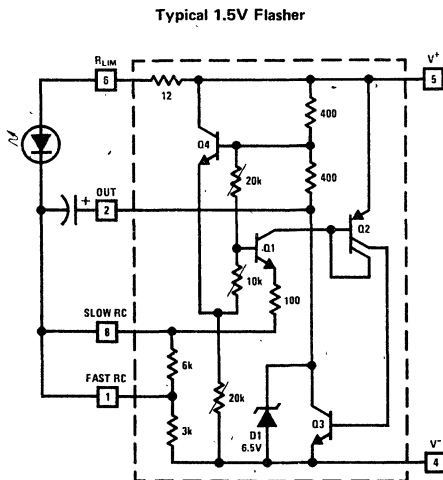
Features

- Operation over one year from one C size flashlight cell
- Bright, high current LED pulse
- Minimum external parts
- Low cost
- Low voltage operation, from just over 1V to 5V
- Low current drain, averages under 0.5 mA during battery life
- Powerful; as an oscillator directly drives an 8Ω speaker
- Wide temperature range

Applications

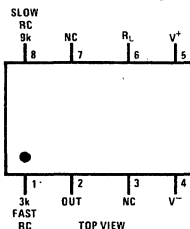
- Finding flashlights in the dark, or locating boat mooring floats
- Sales and advertising gimmicks
- Emergency locators, for instance on fire extinguishers
- Toys and novelties
- Electronic applications such as trigger and sawtooth generators
- Siren for toy fire engine, (combined oscillator, speaker driver)
- Warning indicators powered by 1.4 to 200V

Schematic Diagram



Connection Diagram

Dual-In-Line Package

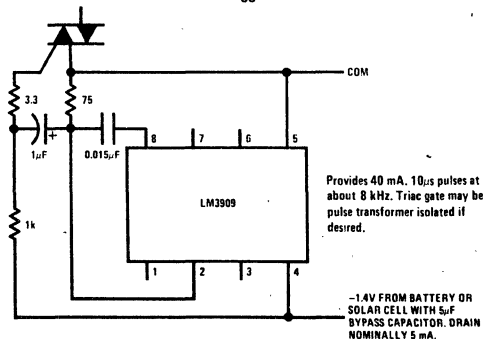


Order Number LM3909N
See NS Package N08B

Typical Application

(See applications notes on page 9-97).

Triac Trigger



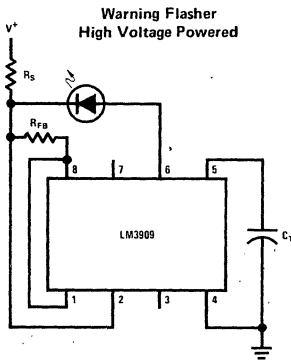
Absolute Maximum Ratings

| | |
|-----------------------------|----------------|
| Power Dissipation | 500 mW |
| V ⁺ Voltage | 6.4V |
| Operating Temperature Range | -25°C to +70°C |

Electrical Characteristics

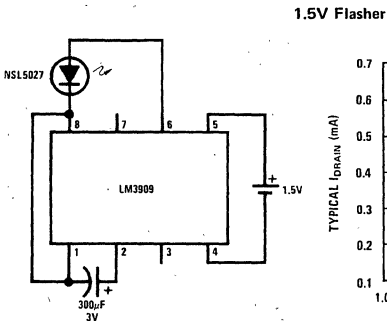
| PARAMETER | CONDITIONS (Applications Note 3) | MIN | TYP | MAX | UNITS |
|-----------------------------|-------------------------------------|------|------|------|-------|
| Supply Voltage | (In Oscillation) | 1.15 | | 6.0 | V |
| Operating Current | | | 0.55 | 0.75 | mA |
| Flash Frequency | 300μF, 5% Capacitor | 0.65 | 1.0 | 1.3 | Hz |
| High Flash Frequency | 0.30μF, 5% Capacitor | | 1.1 | | kHz |
| Compatible LED Forward Drop | 1 mA Forward Current | 1.35 | | 2.1 | V |
| Peak LED Current | 350μF Capacitor | | 45 | | mA |
| Pulse Width | 350μF Capacitors at 1/2 Amplitude | | 6.0 | | ms |

Additional Typical Applications (See applications notes below.)



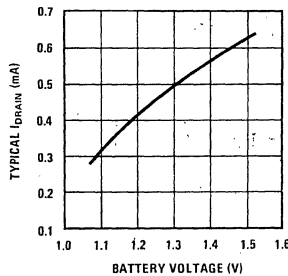
Typical Operating Conditions

| V ⁺ | NOMINAL FLASH Hz | C _T | R _S | R _{FB} | V _{RANGE} |
|----------------|------------------|----------------|----------------|-----------------|--------------------|
| 6V | 2 | 400μF | 1k | 1.5k | 5-25V |
| 15V | 2 | 180μF | 3.9k | 1k | 13-50V |
| 100V | 1.7 | 180μF | 43k 1W | 1k | 85-200V |



Estimated Battery Life
(Continuous 1.5V Flasher Operation)

| SIZE CELL | TYPE | |
|-----------|-----------|-----------|
| | STANDARD | ALKALINE |
| AA | 3 months | 6 months |
| C | 7 months | 15 months |
| D | 1.3 years | 2.6 years |



Note: Estimates are made from our tests and manufacturers data. Conditions are fresh batteries and room temperature. Clad or "leak-proof" batteries are recommended for any application of five months or more. Nickel Cadmium cells are not recommended.

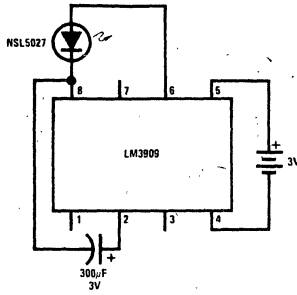


APPLICATIONS NOTES

- Note 1:** All capacitors shown are electrolytic unless marked otherwise.
- Note 2:** Flash rates and frequencies assume a ±5% capacitor tolerance. Electrolytics may vary -20% to +100% of their stated value.
- Note 3:** Unless noted, measurements above are made with a 1.4V supply, a 25°C ambient temperature, and a LED with a forward drop of 1.5V to 1.7V at 1 mA forward current.
- Note 4:** Occasionally a flasher circuit will fail to oscillate due to a LED defect that may be missed because it only reduces light output 10% or so. Such LEDs can be identified by a large increase in conduction between 0.9V and 1.2V.

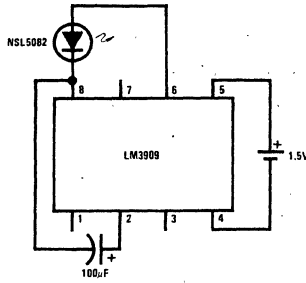
Typical Applications (Continued) (See applications notes on page 9-97)

3V Flasher



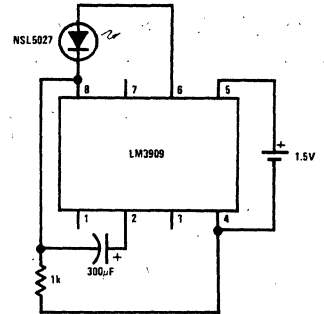
Note: Nominal flash rate: 1 Hz. Average $I_{DRAIN} = 0.77$ mA.

Minimum Power at 1.5V



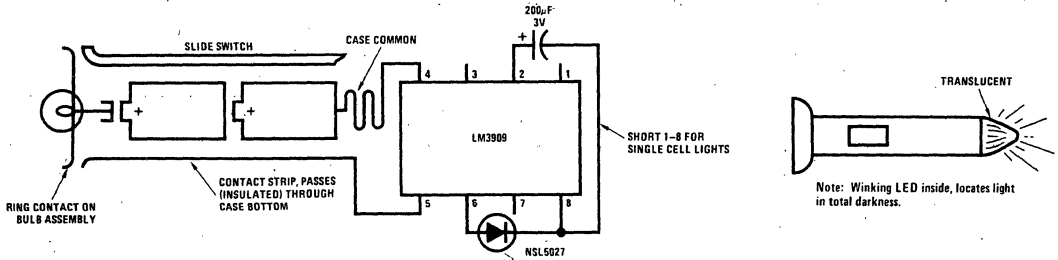
Note: Nominal flash rate: 1.1 Hz. Average $I_{DRAIN} = 0.32$ mA.

Fast Blinker



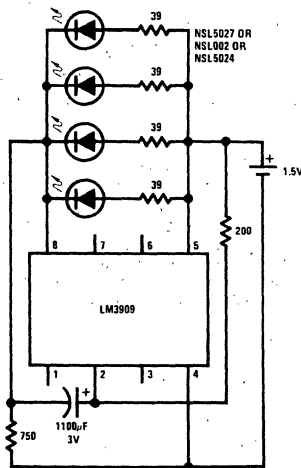
Note: Nominal flash rate: 2.6 Hz. Average $I_{DRAIN} = 1.2$ mA.

Flashlight Finder



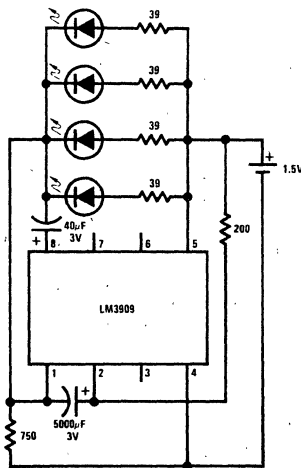
Note: LM3909, capacitor, and LED are installed in a white translucent cap on the flashlight's back end. Only one contact strip (in addition to the case connection) is needed for flasher power. Drawing current through the bulb simplifies wiring and causes negligible loss since bulb resistance cold is typically less than 2Ω.

4 Parallel LEDs



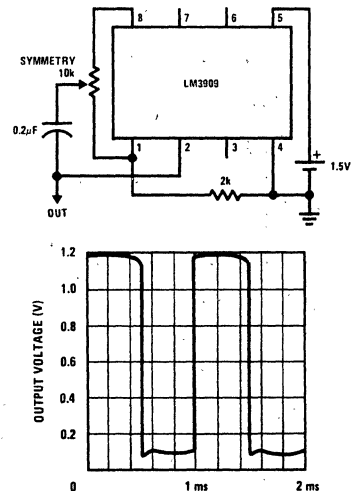
Note: Nominal flash rate: 1.3 Hz. Average $I_{DRAIN} = 2$ mA.

High Efficiency Parallel Circuit



Note: Nominal flash rate: 1.5 Hz. Average $I_{DRAIN} = 1.5$ mA.

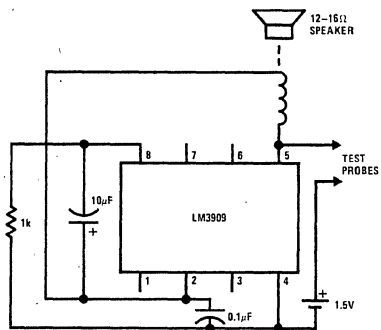
1 kHz Square Wave Oscillator



Note: Output voltage through a 10k load to ground.

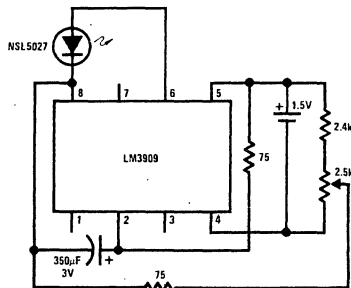
Typical Applications (Continued) (See applications notes on page 9-97)

"Buzz Box" Continuity and Coil Checker



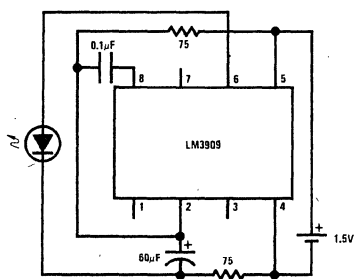
Note: Differences between shorts, coils, and a few ohms of resistance can be heard.

Variable Flasher



Note: Flash rate: 0-20 Hz.

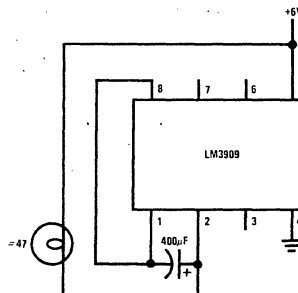
LED Booster



Note: High efficiency, 4 mA drain.

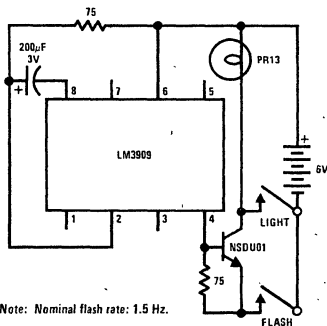
Note: Continuous appearing light obtained by supplying short, high current, pulses (2 kHz) to LEDs with higher than battery voltage available.

Incandescent Bulb Flasher



Note: Flash rate: 1.5 Hz.

Emergency Lantern/Flasher



Note: Nominal flash rate: 1.5 Hz.

LM3911 Temperature Controller

General Description

The LM3911 is a highly accurate temperature measurement and/or control system for use over a -25°C to $+85^{\circ}\text{C}$ temperature range. Fabricated on a single monolithic chip, it includes a temperature sensor, a stable voltage reference and an operational amplifier.

The output voltage of the LM3911 is directly proportional to temperature in degrees Kelvin at $10\text{ mV}/^{\circ}\text{K}$. Using the internal op amp with external resistors any temperature scale factor is easily obtained. By connecting the op amp as a comparator, the output will switch as the temperature transverse the set-point making the device useful as an on-off temperature controller.

An active shunt regulator is connected across the power leads of the LM3911 to provide a stable 6.8V voltage reference for the sensing system. This allows the use of any power supply voltage with suitable external resistors.

The input bias current is low and relatively constant with temperature, ensuring high accuracy when high source impedance is used. Further, the output collector can be returned to a voltage higher than 6.8V allowing the LM3911 to drive lamps and relays up to a 35V supply.

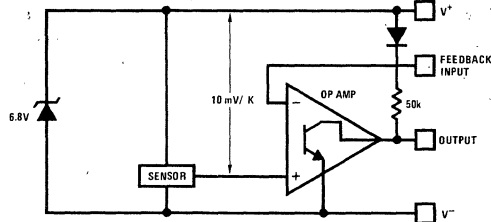
The LM3911 uses the difference in emitter-base voltage of transistors operating at different current densities as the basic temperature sensitive element. Since this output depends only on transistor matching the same reliability and stability as present op amps can be expected.

The LM3911 is available in three package styles—a metal can 4-lead TO-5, a metal can TO-46 and an 8-lead epoxy mini-DIP. In the epoxy package all electrical connections are made on one side of the device allowing the other 4 leads to be used for attaching the LM3911 to the temperature source. The LM3911 is rated for operation over a -25°C to $+85^{\circ}\text{C}$ temperature range.

Features

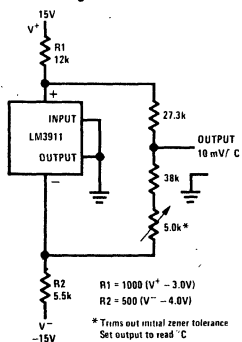
- Uncalibrated accuracy $\pm 10^{\circ}\text{C}$
- Internal op amp with frequency compensation
- Linear output of $10\text{ mV}/^{\circ}\text{K}$ ($10\text{ mV}/^{\circ}\text{C}$)
- Can be calibrated in degrees Kelvin, Celsius or Fahrenheit
- Output can drive loads up to 35V
- Internal stable voltage reference
- Low cost

Block Diagram

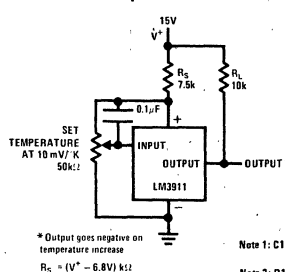


Typical Applications

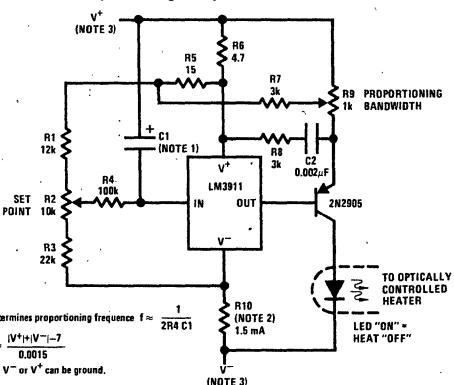
Ground Referred Centigrade Thermometer



Basic Temperature Controller



Proportioning Temperature Controller



Absolute Maximum Ratings

| | | | |
|------------------------------------|-------------|--|-----------------|
| Supply Current (Externally Set) | 10 mA | Operating Temperature Range | -25°C to +85°C |
| Output Collector Voltage, V^{++} | 36V | Storage Temperature Range | -65°C to +150°C |
| Feedback Input Voltage Range | 0V to +7.0V | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Output Short Circuit Duration | Indefinite | | |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|------|-------|------|---------------|
| SENSOR | | | | | |
| Output Voltage | $T_A = -25^\circ\text{C}$, (Note 2) | 2.36 | 2.48 | 2.60 | V |
| Output Voltage | $T_A = 25^\circ\text{C}$, (Note 2) | 2.88 | 2.98 | 3.08 | V |
| Output Voltage | $T_A = 85^\circ\text{C}$, (Note 2) | 3.46 | 3.58 | 3.70 | V |
| Linearity | $\Delta T = 100^\circ\text{C}$ | | 0.5 | 2 | % |
| Long-Term Stability | | | 0.3 | | % |
| Repeatability | | | 0.3 | | % |
| VOLTAGE REFERENCE | | | | | |
| Reverse Breakdown Voltage | $1\text{ mA} \leq I_Z \leq 5\text{ mA}$ | 6.55 | 6.85 | 7.25 | V |
| Reverse Breakdown Voltage Change With Current | $1\text{ mA} \leq I_Z \leq 5\text{ mA}$ | | 10 | 35 | mV |
| Temperature Stability | | | 20 | 85 | mV |
| Dynamic Impedance | $I_Z = 1\text{ mA}$ | | 3.0 | | Ω |
| RMS Noise Voltage | $10\text{ Hz} \leq f \leq 10\text{ kHz}$ | | 30 | | μV |
| Long Term Stability | $T_A = +85^\circ\text{C}$ | | 6.0 | | mV |
| OP AMP | | | | | |
| Input Bias Current | $T_A = +25^\circ\text{C}$ | | 35 | 150 | nA |
| Input Bias Current | | | 45 | 250 | nA |
| Voltage Gain | $R_L = 36\text{k}$, $V^{++} = 36\text{V}$ | 2500 | 15000 | | V/V |
| Output Leakage Current | $T_A = 25^\circ\text{C}$ (Note 3) | | 0.2 | 2 | μA |
| Output Leakage Current | (Note 3) | | 1.0 | 8 | μA |
| Output Source Current | $V_{\text{OUT}} \leq 3.70$ | 10 | | | μA |
| Output Sink Current | $1\text{V} \leq V_{\text{OUT}} \leq 36\text{V}$ | 2.0 | | | mA |

Note 1: These specifications apply for $-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ and $0.9\text{ mA} \leq I_{\text{SUPPLY}} \leq 1.1\text{ mA}$ unless otherwise specified; $C_L \leq 50\text{ pF}$.

Note 2: The output voltage applies to the basic thermometer configuration with the output and input terminals shorted and a load resistance of $\geq 1.0\text{ M}\Omega$. This is the feedback sense voltage and includes errors in both the sensor and op amp. This voltage is specified for the sensor in a rapidly stirred oil bath. The output is referred to V^- .

Note 3: The output leakage current is specified with $\geq 100\text{ mV}$ overdrive. Since this voltage changes with temperature, the voltage drive for turn-off changes and is defined as V_{OUT} (with output and input shorted) -100 mV . This specification applies for $V_{\text{OUT}} = 36\text{V}$.

Application Hints

Although the LM3911 is designed to be totally trouble-free, certain precautions should be taken to insure the best possible performance.

As with any temperature sensor, internal power dissipation will raise the sensor's temperature above ambient. Nominal suggested operating current for the shunt regulator is 1.0 mA and causes 7.0 mW of power dissipation. In free, still, air this raises the package temperature by about 1.2°K. Although the regulator will operate at higher reverse currents and the output will drive loads up to 5.0 mA, these higher currents will raise the sensor temperature to about 19°K above ambient—degrading accuracy. Therefore, the sensor should be operated at the lowest possible power level.

With moving air, liquid or surface temperature sensing, self-heating is not as great a problem since the measured

media will conduct the heat from the sensor. Also, there are many small heat sinks designed for transistors which will improve heat transfer to the sensor from the surrounding medium. A small finned clip-on heat sink is quite effective in free-air. It should be mentioned that the LM3911 die is on the base of the package and therefore coupling to the base is preferable.

The internal reference regulator provides a temperature stable voltage for offsetting the output or setting a comparison point in temperature controllers. However, since this reference is at the same temperature as the sensor temperature changes will also cause reference drift. For application where maximum accuracy is needed an external reference should be used. Of course, for fixed temperature controllers the internal reference is adequate.

Typical Performance Characteristics

Temperature Conversion

$$T_{\text{CENTIGRADE}} = T_C$$

$$T_{\text{FAHRENHEIT}} = T_F$$

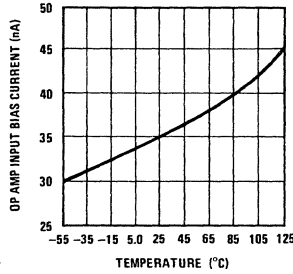
$$T_{\text{KELVIN}} = T_K$$

$$T_K = T_C + 273$$

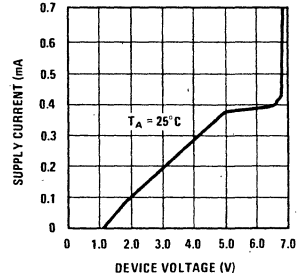
$$T_C = (40 + T_F) \frac{5}{9} - 40$$

$$T_F = (40 + T_C) \frac{9}{5} - 40$$

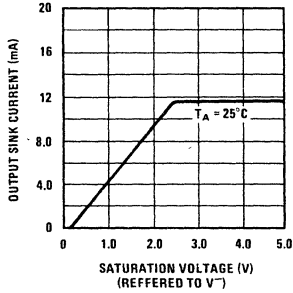
Op Amp Input Current



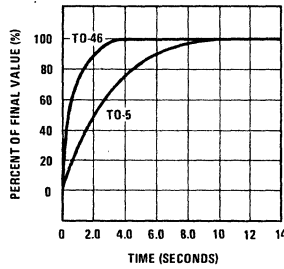
Power Supply Current



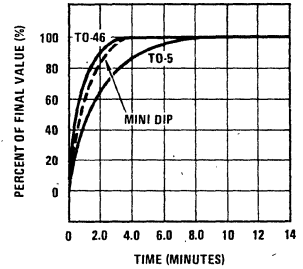
Output Saturation Voltage



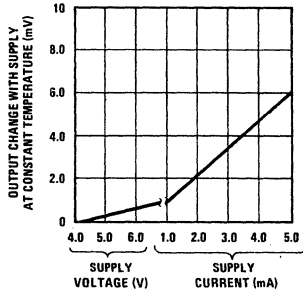
Thermal Time Constant in Stirred Oil Bath



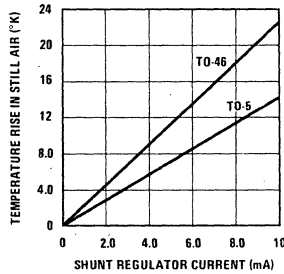
Thermal Time Constant in Still Air



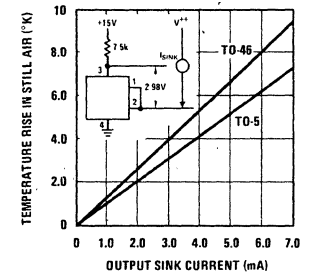
Supply Sensitivity



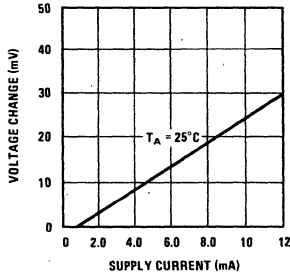
Device Temperature Rise



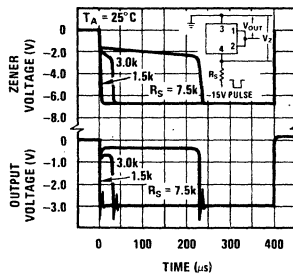
Device Temperature Rise



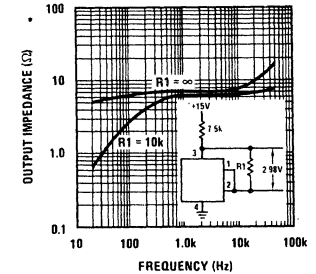
Reference Regulation



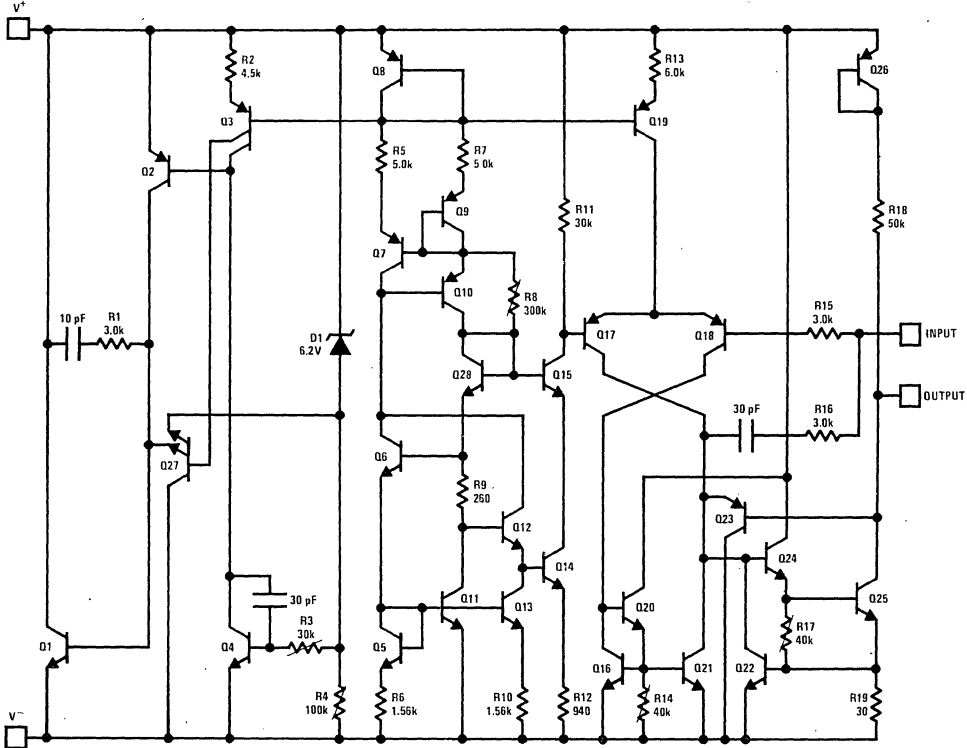
Turn "ON" Response



Amplifier Output Impedance

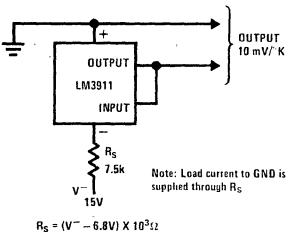


Schematic Diagram

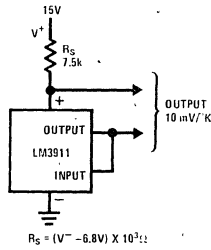


Typical Applications (Continued)

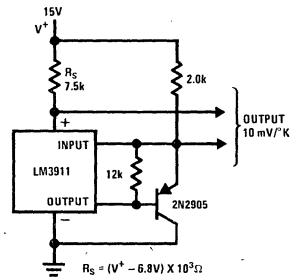
Basic Thermometer for Negative Supply



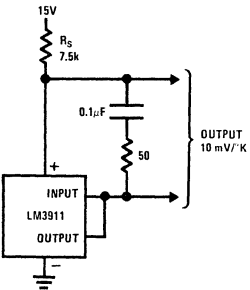
Basic Thermometer for Positive Supply



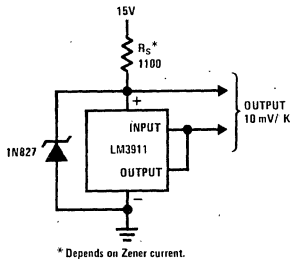
Increasing Gain and Output Drive



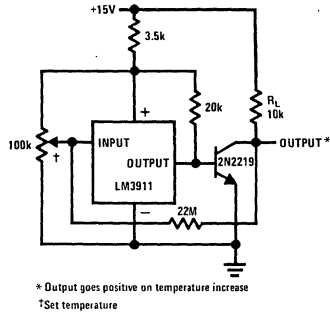
External Frequency Compensation for Greater Stability when Driving Capacitive Loads



Operating With External Zener for Lower Power Dissipation and Ambient Reference

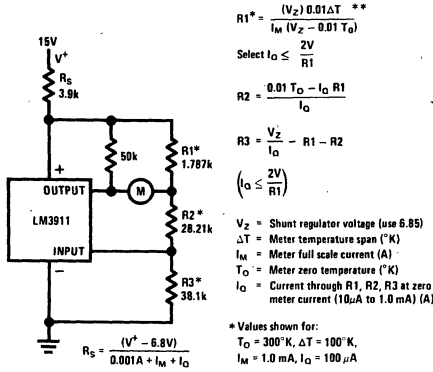


Temperature Controller With Hysteresis



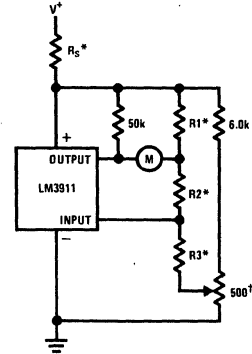
Typical Applications (Continued)

Thermometer With Meter Output



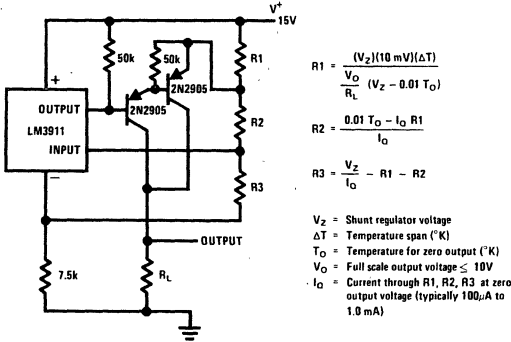
** The 0.01 in the above and following equations is in units of V/ K or V/ C, and is a result of the basic 0.01V/ K sensitivity of the transducer

Meter Thermometer With Trimmed Output

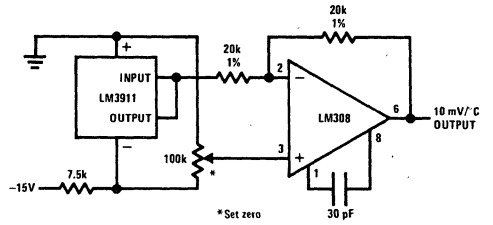


* Selected as for meter thermometer except T_0 should be 5 $^{\circ}K$ more than desired and $I_0 = 100 \mu A$
 \dagger Calibrates T_0

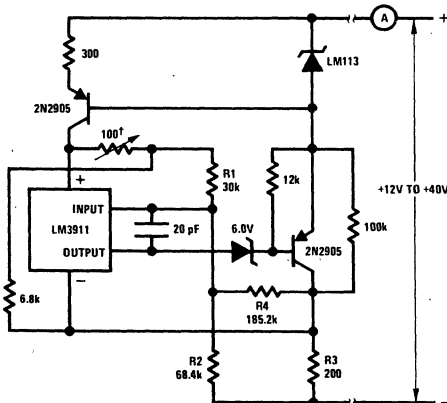
Ground Referred Thermometer



Ground Referred Centigrade Thermometer



Two Terminal Temperature to Current Transducer*



$$R2 (\Omega) = \frac{(V_Z - 0.01 T_L) \left(I_H - \frac{0.01 T_H}{R1} \right) + (V_Z - 0.01 T_H) \left(\frac{0.01 T_L}{R1} - I_L \right)}{\frac{0.01}{R1 R3} \left[T_H (V_Z - 0.01 T_L) - T_L (V_Z - 0.01 T_H) \right]}$$

$$R3 (\Omega) \geq \frac{V_Z \left(\frac{T_H}{T_L} - 1 \right)}{I_H - \frac{I_L T_H}{T_L}}$$

$$\frac{1}{R4} = \frac{1}{(V_Z - 0.01 T_L)(R2)} \left[\frac{(R2)(0.01 T_L)}{R1} + \frac{(V_Z - 0.01 T_L) - I_L}{R2} \right] - \frac{1}{R2}$$

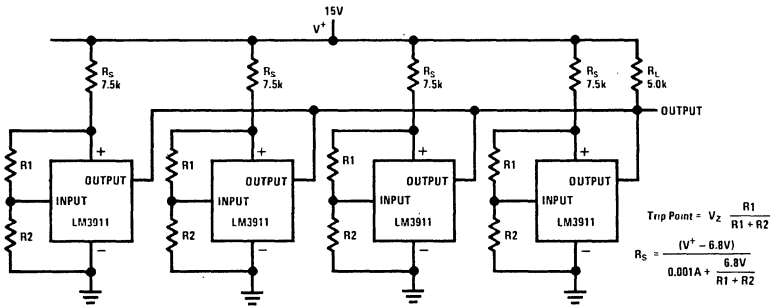
$T_L =$ Temperature for I_L (K)
 $T_H =$ Temperature for I_H (K)
 $V_Z =$ Zener voltage (V)
 $I_L =$ Low temperature output current (A)
 $I_H =$ High temperature output current (A)

* Values shown for $I_{OUT} = 1 mA$ to 10 mA for 10 $^{\circ}F$ to 100 $^{\circ}F$
 \dagger Set temperature

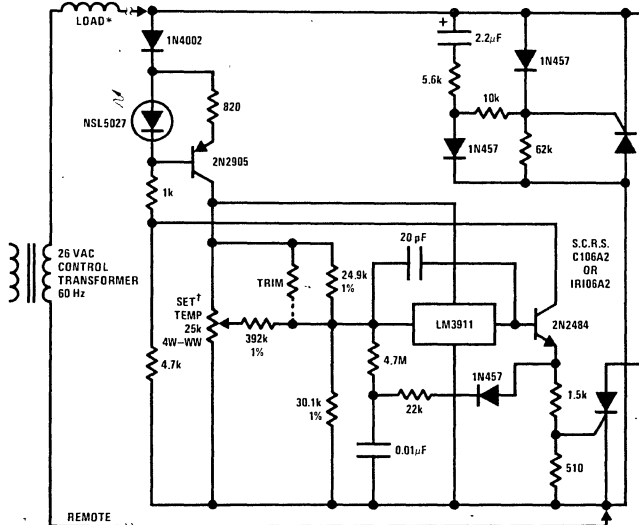
** The 0.01 in the above and following equations is in units of V/ K or V/ C, and is a result of the basic 0.01V/ K sensitivity of the transducer

Typical Applications (Continued)

Over Temperature Detectors With Common Output



Two-Wire Remote A.C. Electronic Thermostat (Gas or Oil Furnace Control)

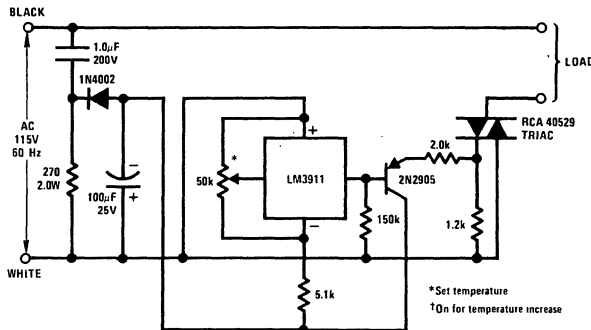


* Solenoid or 6-15W heater

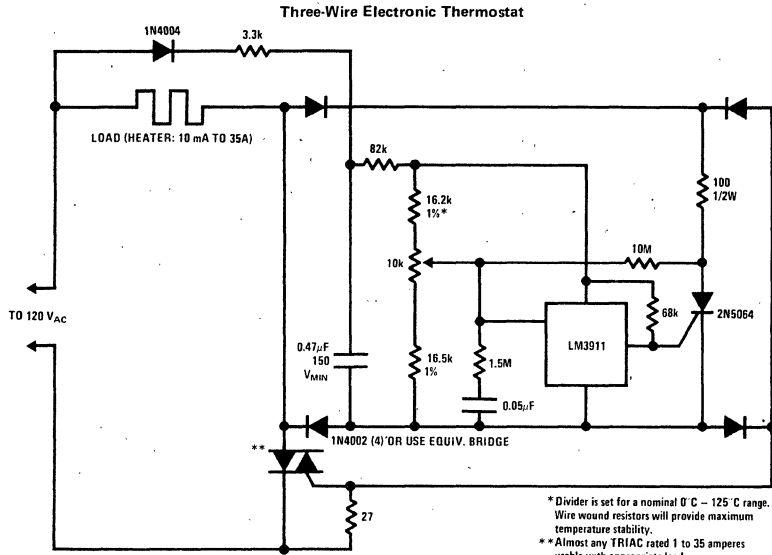
† Pot will provide about a 50° F to 90° F setting range. The trim resistor (100k) is selected to bring 70° F near the middle of the pot rotation.

SCR heating, by proper positioning, can preheat the sensor giving control anticipation as is presently used in many home thermostats.

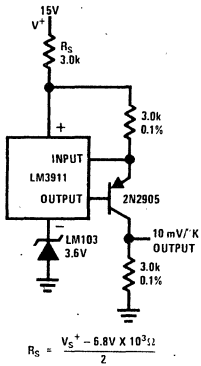
Temperature Controller Driving TRIAC



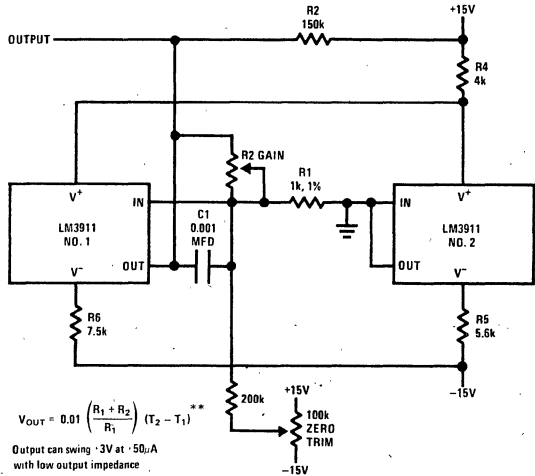
Typical Applications (Continued)



Kelvin Thermometer With Ground Referred Output

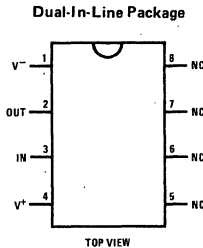


Differential Thermometer



** The 0.01 in the above equation is in units of V/ K or V/ C, and is a result of the basic 0.01 V/ K sensitivity of the transducer

Connection Diagram



Order Number LM3911N
See NS Package N08B

LM3914 Dot/Bar Display Driver

General Description

The LM3914 is a monolithic integrated circuit that senses analog voltage levels and drives 10 LEDs, providing a linear analog display. A single pin changes the display from a moving dot to a bar graph. Current drive to the LEDs is regulated and programmable, eliminating the need for resistors. This feature is one that allows operation of the whole system from less than 3V.

The circuit contains its own adjustable reference and accurate 10-step voltage divider. The low-bias-current input buffer accepts signals down to ground, or V^- , yet needs no protection against inputs of 35V above or below ground. The buffer drives 10 individual comparators referenced to the precision divider. Indication non-linearity can thus be held typically to 1/2%, even over a wide temperature range.

Versatility was designed into the LM3914 so that controller, visual alarm, and expanded scale functions are easily added on to the display system. The circuit can drive LEDs of many colors, or low-current incandescent lamps. Many LM3914s can be "chained" to form displays of 20 to over 100 segments. Both ends of the voltage divider are externally available so that 2 drivers can be made into a zero-center meter.

The LM3914 is very easy to apply as an analog meter circuit. A 1.2V full-scale meter requires only 1 resistor and a single 3V to 15V supply in addition to the 10 display LEDs. If the 1 resistor is a pot, it becomes the LED brightness control. The simplified block diagram illustrates this extremely simple external circuitry.

When in the dot mode, there is a small amount of overlap or "fade" (about 1 mV) between segments. This assures that at no time will all LEDs be "OFF", and

thus any ambiguous display is avoided. Various novel displays are possible.

Much of the display flexibility derives from the fact that all outputs are individual, DC regulated currents. Various effects can be achieved by modulating these currents. The individual outputs can drive a transistor as well as a LED at the same time, so controller functions including "staging" control can be performed. The LM3914 can also act as a programmer, or sequencer.

Features

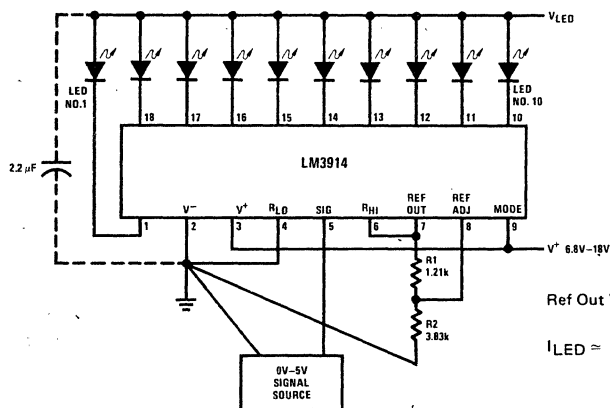
- Drives LEDs, LCDs or vacuum fluorescent
- Bar or dot display mode externally selectable by user
- Expandable to displays of 100 steps
- Internal voltage reference from 1.2V to 12V
- Operates with single supply of less than 3V
- Inputs operate down to ground
- Output current programmable from 2 to 30 mA
- No multiplex switching or interaction between outputs
- Input withstands $\pm 35V$ without damage or false outputs
- LED driver outputs are current regulated, open-collectors
- Outputs can interface with TTL or CMOS logic
- The internal 10-step divider is floating and can be referenced to a wide range of voltages

The LM3914 is rated for operation from $0^{\circ}C$ to $+70^{\circ}C$. The LM3914N is available in an 18-lead molded (N) package and the LM3914J comes in the 18-lead ceramic DIP.

The following typical application illustrates adjusting of the reference to a desired value, and proper grounding for accurate operation, and avoiding oscillations.

Typical Applications

0V to 5V Bar Graph Meter



Note 1: Grounding method is typical of all uses. The 2.2 μF tantalum or 10 μF aluminum electrolytic capacitor is needed if leads to the LED supply are 6" or longer.

$$\text{Ref Out } V = 1.25 \left(1 + \frac{R2}{R1} \right)$$

$$I_{LED} = \frac{12.5}{R1}$$

Absolute Maximum Ratings

Power Dissipation (Note 5)

Ceramic DIP (J)

Molded DIP (N)

Supply Voltage

Voltage on Output Drivers

1W

625 mW

25V

25V

Input Signal Overvoltage (Note 3)

Divider Voltage

Reference Load Current

Storage Temperature Range

Lead Temperature (Soldering, 10 seconds)

±35V

-100 mV to V^+

10 mA

-55°C to +150°C

300°C

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS (Note 1) | MIN | TYP | MAX | UNITS |
|--|---|-----|-------------|-----------|---------------|
| COMPARATOR | | | | | |
| Offset Voltage, Buffer and First Comparator | $0V \leq V_{RLO} = V_{RHI} \leq 12V$, $I_{LED} = 1 \text{ mA}$ | | 3 | 10 | mV |
| Offset Voltage, Buffer and Any Other Comparator | $0V \leq V_{RLO} = V_{RHI} \leq 12V$, $I_{LED} = 1 \text{ mA}$ | | 3 | 15 | mV |
| Gain ($\Delta I_{LED}/\Delta V_{IN}$) | $I_L(REF) = 2 \text{ mA}$, $I_{LED} = 10 \text{ mA}$ | 3 | 8 | | mA/mV |
| Input Bias Current (at Pin 5) | $0V \leq V_{IN} \leq V^+ - 1.5V$ | | 10 | 50 | nA |
| Input Signal Overvoltage | No Change in Display | -35 | | 35 | V |
| VOLTAGE-DIVIDER | | | | | |
| Divider Resistance | Total, Pin 6 to 4 | 6.5 | 10 | 15 | k Ω |
| Accuracy | (Note 2) | | 0.5 | 2 | % |
| VOLTAGE REFERENCE | | | | | |
| Output Voltage | $0.1 \text{ mA} \leq I_L(REF) \leq 4 \text{ mA}$, $V^+ = V_{LED} = 5V$ | 1.2 | 1.28 | 1.34 | V |
| Line Regulation | $3V \leq V^+ \leq 18V$ | | 0.01 | 0.03 | %/V |
| Load Regulation | $0.1 \text{ mA} \leq I_L(REF) \leq 4 \text{ mA}$, $V^+ = V_{LED} = 5V$ | | 0.4 | 2 | % |
| Output Voltage Change With Temperature | $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$, $I_L(REF) = 1 \text{ mA}$, $V^+ = 5V$ | | 1 | | % |
| Adjust Pin Current | | | 75 | 120 | μA |
| OUTPUT DRIVERS | | | | | |
| LED Current | $V^+ = V_{LED} = 5V$, $I_L(REF) = 1 \text{ mA}$ | 7 | 10 | 13 | mA |
| LED Current Difference (Between Largest and Smallest LED Currents) | $V_{LED} = 5V$, $I_{LED} = 2 \text{ mA}$ $V_{LED} = 5V$, $I_{LED} = 20 \text{ mA}$ | | 0.12 1.2 | 0.4 3 | mA |
| LED Current Regulation | $2V \leq V_{LED} \leq 17V$, $I_{LED} = 2 \text{ mA}$ $I_{LED} = 20 \text{ mA}$ | | 0.1 1 | 0.25 3 | mA |
| Dropout Voltage | $I_{LED(ON)} = 20 \text{ mA}$, $V_{LED} = 5V$, $\Delta I_{LED} = 2 \text{ mA}$ | | | 1.5 | V |
| Saturation Voltage | $I_{LED} = 2.0 \text{ mA}$, $I_L(REF) = 0.4 \text{ mA}$ | | 0.15 | 0.4 | V |
| Output Leakage, Each Collector | (Bar Mode) (Note 4) | | 0.1 | 10 | μA |
| Output Leakage | (Dot Mode) (Note 4) | | | | |
| Pins 10-18 | | | 0.1 | 10 | μA |
| Pin 1 | | 60 | 150 | 450 | μA |
| SUPPLY CURRENT | | | | | |
| | $V^+ = 5V$, $I_L(REF) = 0.2 \text{ mA}$ | | 2.4 | 4.2 | mA |
| | $V^+ = 20V$, $I_L(REF) = 1.0 \text{ mA}$ | | 6.1 | 9.2 | mA |

Note 1: Unless otherwise stated, all specifications apply with the following conditions:

$$3 V_{DC} \leq V^+ \leq 20 V_{DC}$$

$$3 V_{DC} \leq V_{LED} \leq V^+$$

$$-0.015V \leq V_{RLO} \leq 12 V_{DC}$$

$$V_{REF}, V_{RHI}, V_{RLO} \leq (V^+ - 1.5V)$$

$$0V \leq V_{IN} \leq V^+ - 1.5V$$

$$T_A = +25^\circ\text{C}, I_L(REF) = 0.2 \text{ mA}, V_{LED} = 3.0V, \text{ pin 9 connected to pin 3 (Bar Mode).}$$

For higher power dissipations, pulse testing is used.

Note 2: Accuracy is measured referred to +10,000 V_{DC} at pin 6, with 0.000 V_{DC} at pin 4. At lower full-scale voltages, buffer and comparator offset voltage may add significant error.

Note 3: Pin 5 input current must be limited to $\pm 3 \text{ mA}$. The addition of a 39k resistor in series with pin 5 allows $\pm 100V$ signals without damage.

Note 4: Bar mode results when pin 9 is within 20 mV of V^+ . Dot mode results when pin 9 is pulled at least 200 mV below V^+ or left open circuit. LED No. 10 (pin 10 output current) is disabled if pin 9 is pulled 0.9V or more below V_{LED} .

Note 5: The maximum junction temperature of the LM3914 is 100°C. Devices must be derated for operation at elevated temperatures. Junction to ambient thermal resistance is 75°C/W for the ceramic DIP (J package) and 120°C/W for the molded DIP (N package).

Definition of Terms

Accuracy: The difference between the observed threshold voltage and the ideal threshold voltage for each comparator. Specified and tested with 10V across the internal voltage divider so that resistor ratio matching error predominates over comparator offset voltage.

Adjust Pin Current: Current flowing out of the reference adjust pin when the reference amplifier is in the linear region.

Comparator Gain: The ratio of the change in output current (I_{LED}) to the change in input voltage (V_{IN}) required to produce it for a comparator in the linear region.

Dropout Voltage: The voltage measured at the current source outputs required to make the output current fall by 10%.

Input Bias Current: Current flowing out of the signal input when the input buffer is in the linear region.

LED Current Regulation: The change in output current over the specified range of LED supply voltage (V_{LED}) as measured at the current source outputs. As the forward voltage of an LED does not change significantly with a small change in forward current, this is equivalent to changing the voltage at the LED anodes by the same amount.

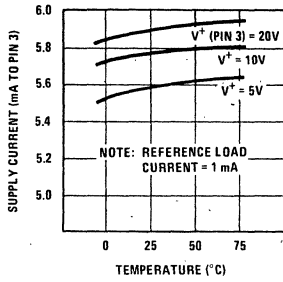
Line Regulation: The average change in reference output voltage over the specified range of supply voltage (V^+).

Load Regulation: The change in reference output voltage (V_{REF}) over the specified range of load current ($I_{L(REF)}$).

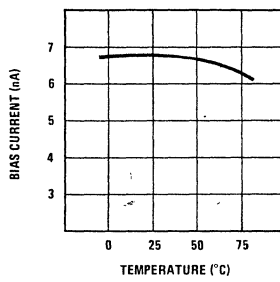
Offset Voltage: The differential input voltage which must be applied to each comparator to bias the output in the linear region. Most significant error when the voltage across the internal voltage divider is small. Specified and tested with pin 6 voltage (V_{RH}) equal to pin 4 voltage (V_{RLO}).

Typical Performance Characteristics

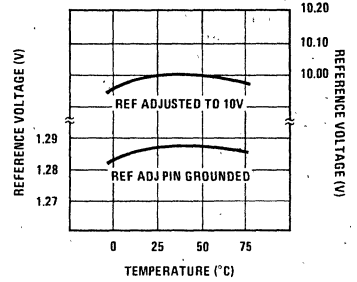
Supply Current vs Temperature



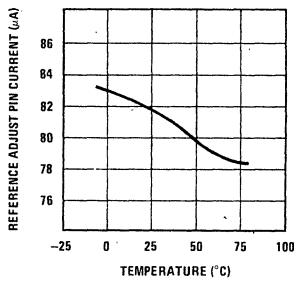
Operating Input Bias Current vs Temperature



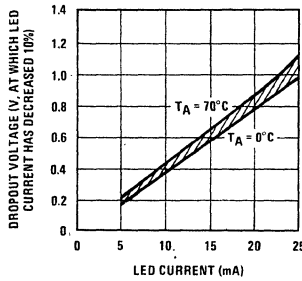
Reference Voltage vs Temperature



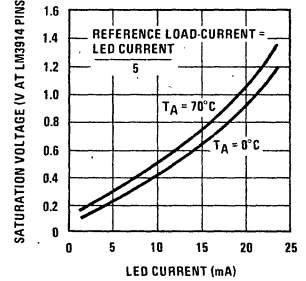
Reference Adjust Pin Current vs Temperature



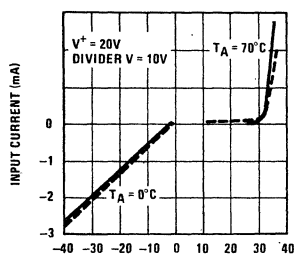
LED Current-Regulation Dropout



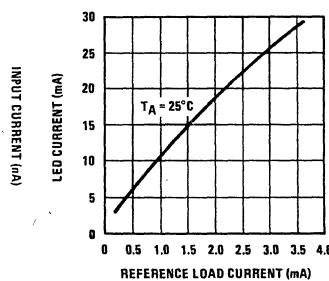
LED Driver Saturation Voltage



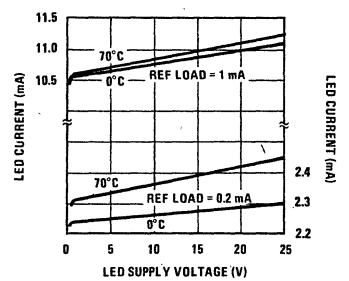
Input Current Beyond Signal Range (Pin 5)



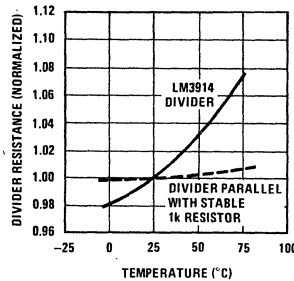
LED Current vs Reference Loading



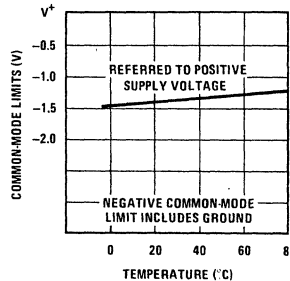
LED Driver Current Regulation



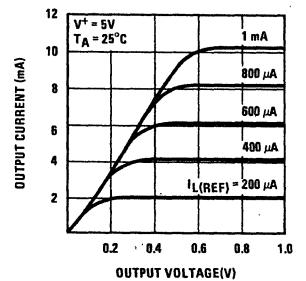
Total Divider Resistance vs Temperature



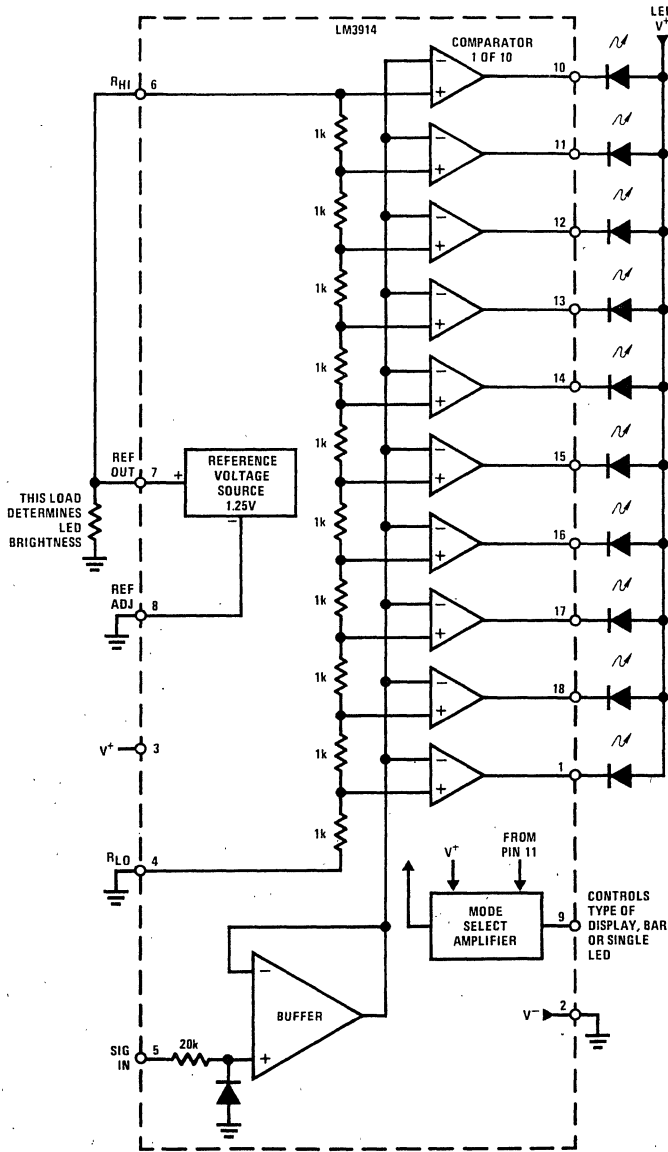
Common-Mode Limits



Output Characteristics



Block Diagram (Showing Simplest Application)



Functional Description

The simplified LM3914 block diagram is to give the general idea of the circuit's operation. A high input impedance buffer operates with signals from ground to 12V, and is protected against reverse and overvoltage signals. The signal is then applied to a series of 10 comparators; each of which is biased to a different comparison level by the resistor string.

In the example illustrated, the resistor string is connected to the internal 1.25V reference voltage. In this case, for each 125 mV that the input signal increases, a comparator will switch on another indicating LED. This

resistor divider can be connected between any 2 voltages, providing that they are 1.5V below V^+ and no less than V^- . If an expanded scale meter display is desired, the total divider voltage can be as little as 200 mV. Expanded-scale meter displays are more accurate and the segments light uniformly only if bar mode is used. At 50 mV or more per step, dot mode is usable.

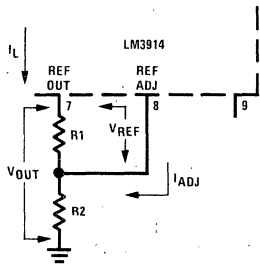
Internal Voltage Reference

The reference is designed to be adjustable and develops a nominal 1.25V between the REF OUT (pin 7) and

Functional Description (Continued)

REF ADJ (pin 8) terminals. The reference voltage is impressed across program resistor R1 and, since the voltage is constant, a constant current I_1 then flows through the output set resistor R2 giving an output voltage of:

$$V_{OUT} = V_{REF} \left(1 + \frac{R_2}{R_1} \right) + I_{ADJ} R_2$$



Since the $120 \mu\text{A}$ current (max) from the adjust terminal represents an error term, the reference was designed to minimize changes of this current with V^+ and load changes.

Current Programming

A feature not completely illustrated by the block diagram is the LED brightness control. The current drawn out of the reference voltage pin (pin 7) determines LED current. Approximately 10 times this current will be drawn through each lighted LED, and this current will be relatively constant despite supply voltage and temperature changes. Current drawn by the internal 10-resistor divider, as well as by the external current and voltage-setting divider should be included in calculating LED drive current. The ability to modulate LED brightness with time, or in proportion to input voltage and other signals can lead to a number of novel displays or ways of indicating input overvoltages, alarms, etc.

Mode Pin Use

Pin 9, the Mode Select input controls chaining of multiple LM3914s, and controls bar or dot mode operation. The following tabulation shows the basic ways of using this input. Other more complex uses will be illustrated in the applications.

Bar Graph Display: Wire Mode Select (pin 9) *directly* to pin 3 (V^+ pin).

Dot Display, Single LM3914 Driver: Leave the Mode Select pin open circuit.

Dot Display, 20 or More LEDs: Connect pin 9 of the *first* driver in the series (i.e., the one with the lowest input voltage comparison points) to pin 1 of the next higher LM3914 driver. Continue connecting pin 9 of lower input drivers to pin 1 of higher input drivers for 30, 40, or more LED displays. The last LM3914 driver in the chain will have pin 9 wired to pin 11. All previous drivers should have a 20k resistor in parallel with LED No. 9 (pin 11 to V_{LED}).

Characteristics of Mode Select Pin (Pin 9)

The connections for using this pin have already been summarized. The mode pin will cause the bar graph display to appear if within 20 mV of V^+ voltage (pin 3). The dot LED display will occur if the mode pin is 200 mV or more below V^+ voltage. LED No. 10 will be turned OFF if pin 9 is pulled 0.9V below V_{LED} . A 20k 5% resistor must be in place from pin 11 to V_{LED} (i.e., in parallel with LED No. 9) for dot displays using 2 or more LM3914s. The less than $100 \mu\text{A}$ shunted away by this resistor will make a negligible difference in the brightness of almost any red LED display. For other colors of LEDs, the resistor value can increase in direct proportion to the typical LED voltage drop.

In "chaining" display drivers, some further characteristics must be considered. Bar graph displays of 20 or more segments are simple. All that is needed is to connect the mode pin of each device to pin 3 of the *same* device (the V^+ pin). It should be noted that the Mode Select Amplifier looks at 3 inputs to determine whether to show a bar display, a dot display, or a dot display using multiple LM3914 devices. This last action is the "chaining" or carry function that turns OFF LED No. 10 of one LM3914 when the first LED of the next device up the chain turns ON. The 3 needed inputs to the Mode Select Amplifier are; pin 9, the devices V^+ pin and pin 11 (the cathode of LED No. 9).

If, for instance, a 20-segment dot mode display is desired, the mode pin of the first LM3914 is connected to pin 1 of the second device (which is actually driving LED No. 11 of the entire display). Even if this LED is OFF, if any LED numbered 12 through 20 is ON, about $100 \mu\text{A}$ will be sunk by pin 1 of this second device (minimum $60 \mu\text{A}$). This is not enough to light LED No. 11 significantly, but is sufficient to be sensed by the mode pin and turn OFF LED No. 10 of the first device for proper display.

Other Device Characteristics

The LM3914 is relatively low-powered itself, and since any number of LEDs can be powered from about 3V , it is a very efficient display driver. Typical standby supply current (all LEDs OFF) is 1.6 mA (2.5 mA max). However, any reference loading adds 4 times that current drain to the V^+ (pin 3) supply input. For example, an LM3914 with a 1 mA reference pin load (1.3k), would supply almost 10 mA to every LED while drawing only 5.6 mA from its V^+ pin supply. At full-scale, the IC is typically drawing less than 7% of the current supplied to the display.

The display driver does not have built-in hysteresis so that the display does not jump instantly from one LED to the next. Under rapidly changing signal conditions, this cuts down high frequency noise and often an annoying flicker. An "overlap" is built in so that at no time between segments are all LEDs completely OFF in the dot mode. Generally 1 LED fades in while the other fades out over a mV or more of range (Note 2). The change may be much more rapid between LED No. 10 of one device and LED No. 1 of a *second* device "chained" to the first.

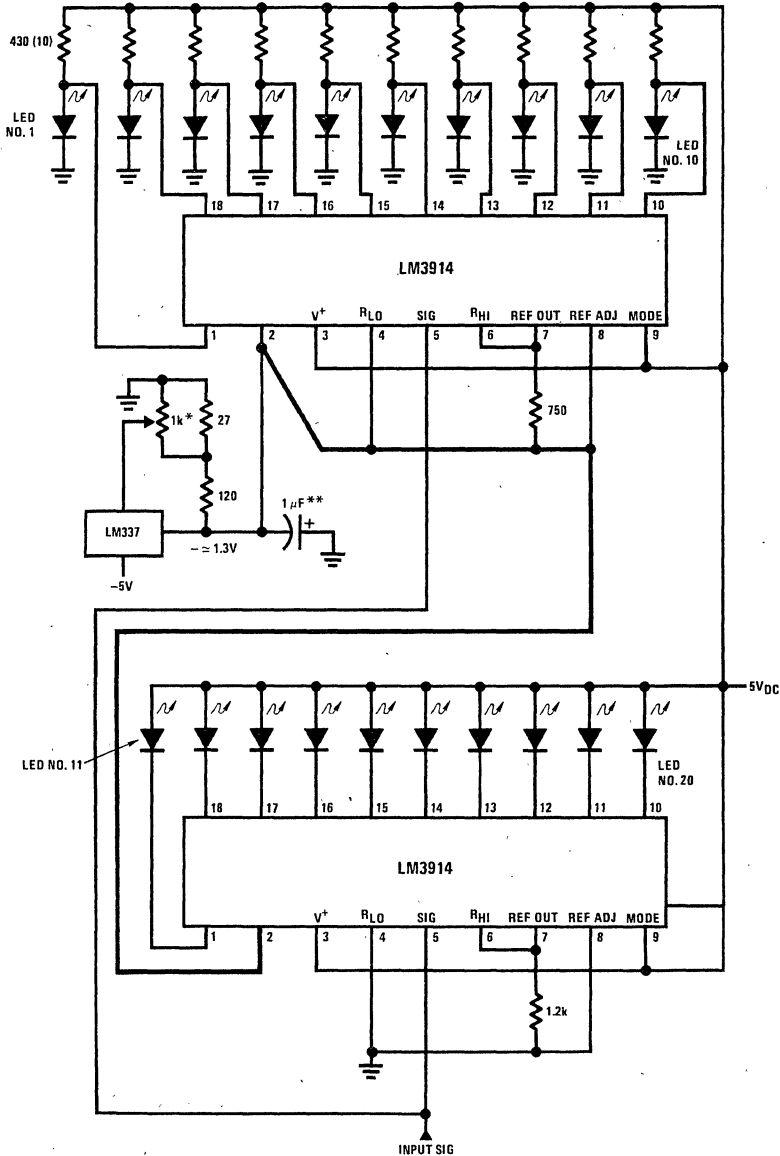
Functional Description (Continued)

The LM3914 features individually current regulated LED driver transistors. Further internal circuitry detects when any driver transistor goes into saturation, and prevents other circuitry from drawing excess current. This results in the ability of the LM3914 to drive and regulate LEDs powered from a pulsating DC power source, i.e., largely unfiltered. (Due to possible oscillations at low voltages a

nominal bypass capacitor consisting of a 2.2 μF solid tantalum connected from the pulsating LED supply to pin 2 of the LM3914 is recommended.) This ability to operate with low or fluctuating voltages also allows the display driver to interface with logic circuitry, opto-coupled solid-state relays, and low-current incandescent lamps.

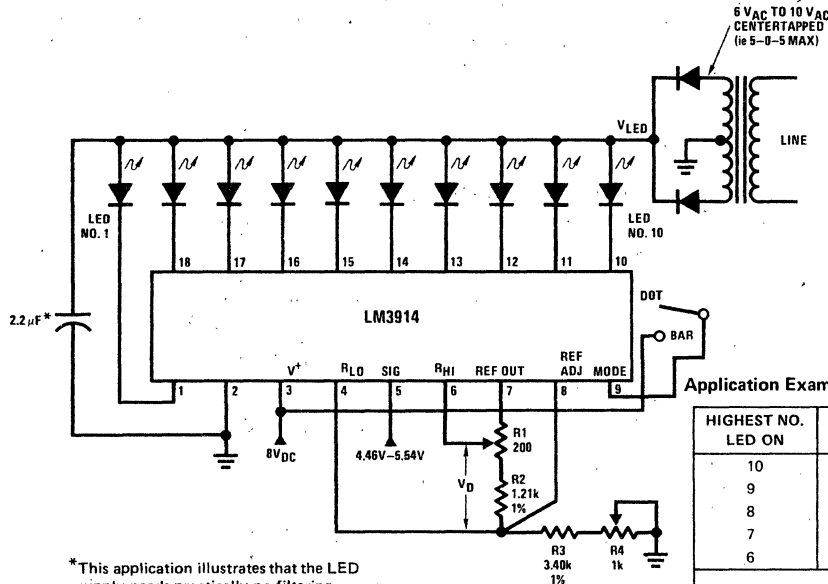
Typical Applications (Continued)

Zero-Center Meter, 20-Segment



Typical Applications (Continued)

Expanded Scale Meter, Dot or Bar



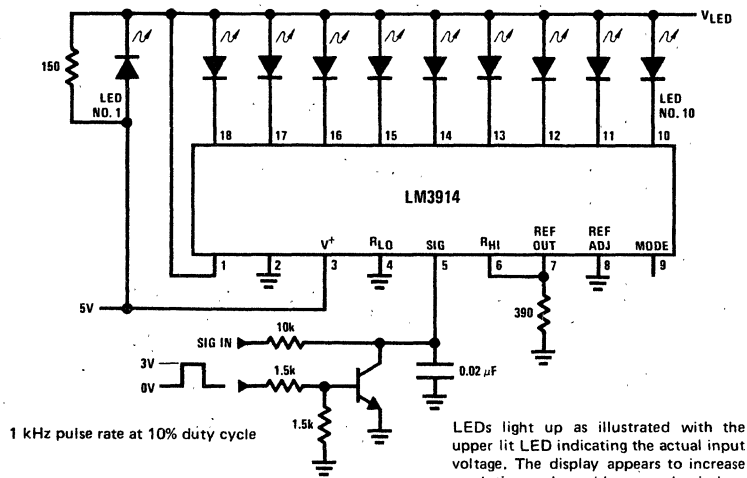
Application Example: Grading 5V Regulators

| HIGHEST NO. LED ON | COLOR | V _{OUT} (MIN) |
|--------------------|--------|------------------------|
| 10 | Red | 5.54 |
| 9 | Red | 5.42 |
| 8 | Yellow | 5.30 |
| 7 | Green | 5.18 |
| 6 | Green | 5.06 |
| 5V | | |
| 5 | Green | 4.94 |
| 4 | Green | 4.82 |
| 3 | Yellow | 4.7 |
| 2 | Red | 4.58 |
| 1 | Red | 4.46 |

*This application illustrates that the LED supply needs practically no filtering

Calibration: With a precision meter between pins 4 and 6 adjust R1 for voltage V_D of 1.20V. Apply 4.94V to pin 5, and adjust R4 until LED No. 5 just lights. The adjustments are non-interacting.

"Exclamation Point" Display



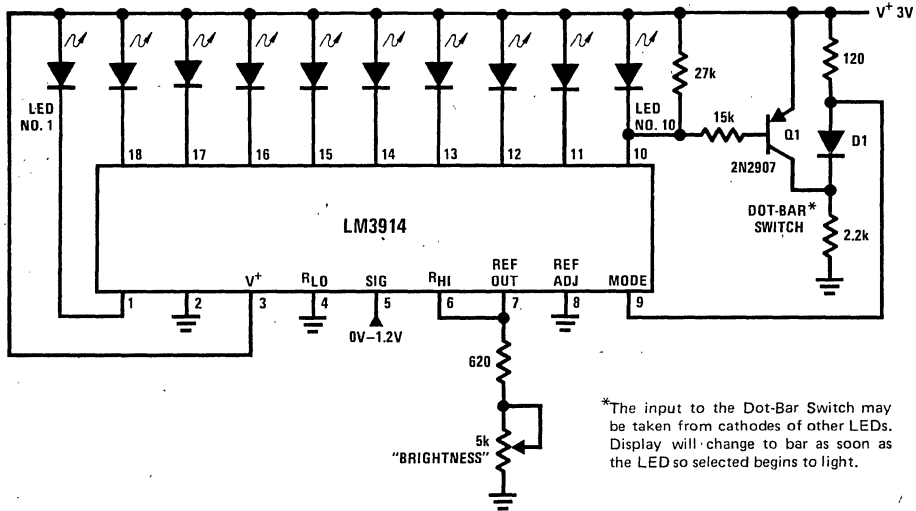
1 kHz pulse rate at 10% duty cycle

LEDs light up as illustrated with the upper lit LED indicating the actual input voltage. The display appears to increase resolution and provides an analog indication of overrange.

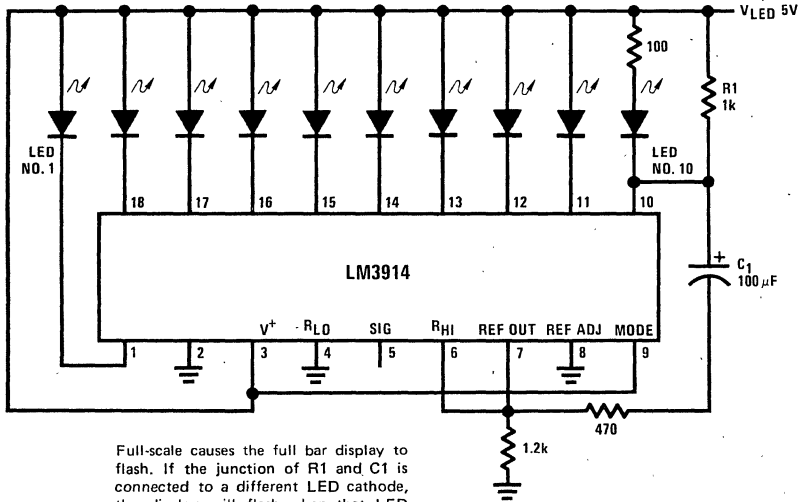
Typical Applications (Continued)

LM3914

Indicator and Alarm, Full-Scale Changes Display From Dot to Bar

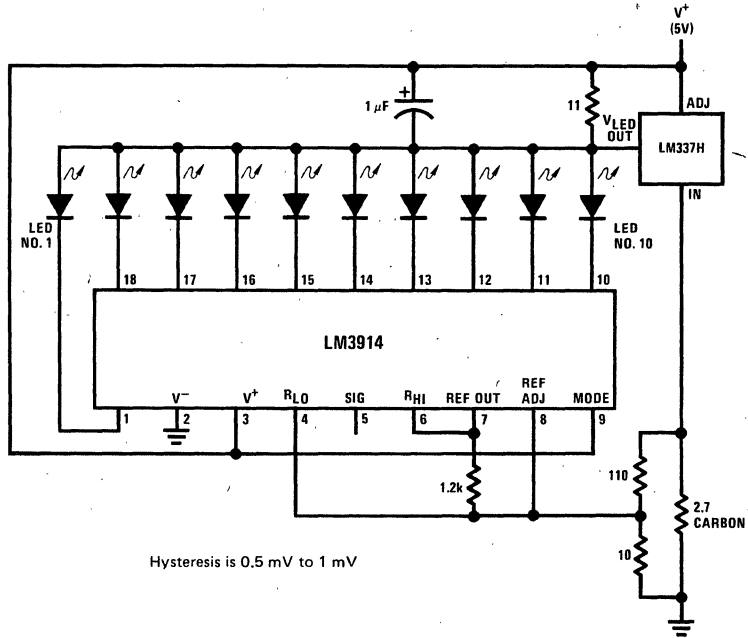


Bar Display with Alarm Flasher

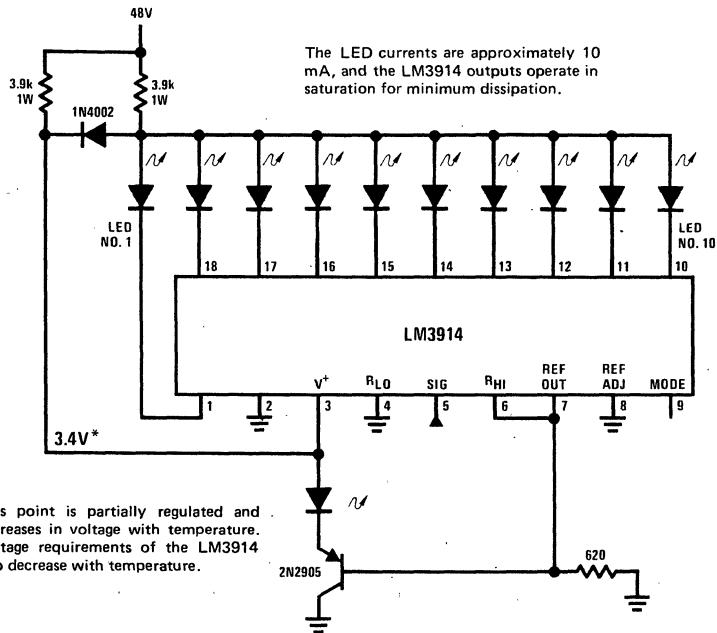


Typical Applications (Continued)

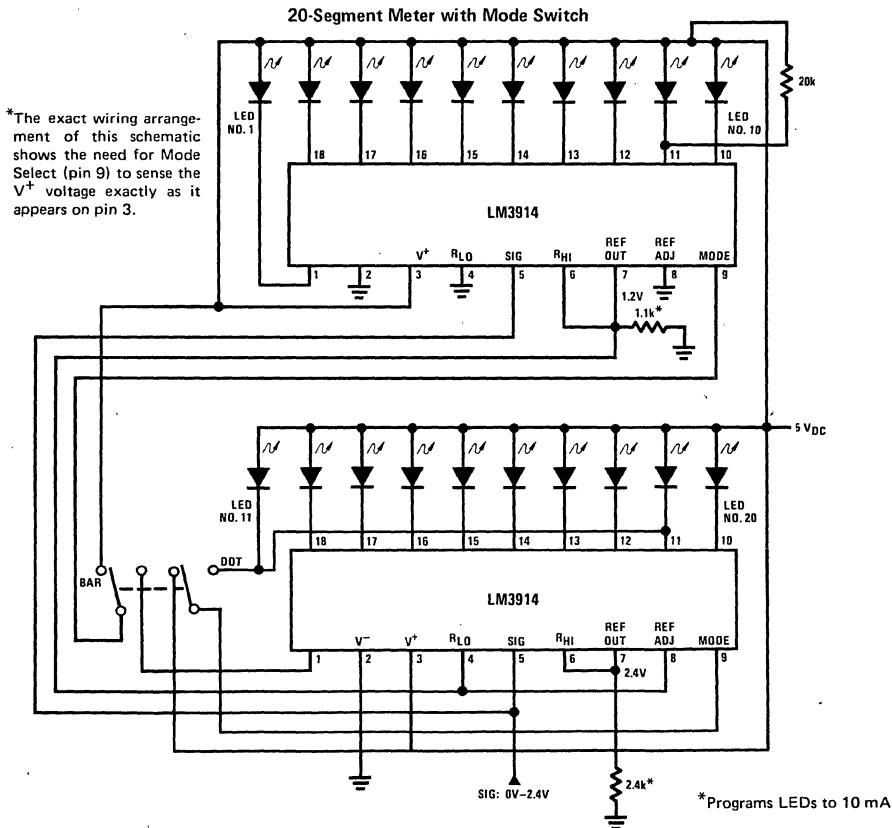
Adding Hysteresis (Single Supply, Bar Mode Only)



Operating with a High Voltage Supply (Dot Mode Only)



Typical Applications (Continued)



Application Hints

Three of the most commonly needed precautions for using the LM3914 are shown in the first typical application drawing (see page 9-108) showing a 0V–5V bar graph meter. The most difficult problem occurs when large LED currents are being drawn, especially in bar graph mode. These currents flowing out of the ground pin cause voltage drops in external wiring, and thus errors and oscillations. Bringing the return wires from signal sources, reference ground and bottom of the resistor string (as illustrated) to a single point very near pin 2 is the best solution.

Long wires from V_{LED} to LED anode common can cause oscillations. Depending on the severity of the problem 0.05 μF to 2.2 μF decoupling capacitors from LED anode common to pin 2 will damp the circuit. If LED anode line wiring is inaccessible, often similar decoupling from pin 1 to pin 2 will be sufficient.

If LED turn ON seems slow (bar mode) or several LEDs light (dot mode), oscillation or excessive noise is usually the problem. In cases where proper wiring and bypassing fail to stop oscillations, V^+ voltage at pin 3 is usually below suggested limits (see Note 2, page 9-108). Expanded scale meter applications may have one or both ends of the internal voltage divider terminated at rela-

tively high value resistors. These high-impedance ends should be bypassed to pin 2 with at least a 0.001 μF capacitor, or up to 0.1 μF in noisy environments.

Power dissipation, especially in bar mode should be given consideration. For example, with a 5V supply and all LEDs programmed to 20 mA the driver will dissipate over 600 mW. In this case a 7.5 Ω resistor in series with the LED supply will cut device heating in half. The negative end of the resistor should be bypassed with a 2.2 μF solid tantalum capacitor to pin 2 of the LM3914.

Turning OFF of most of the internal current sources is accomplished by pulling positive on the reference with a current source or resistance supplying 100 μA or so. Alternately, the input signal can be gated OFF with a transistor switch.

Other special features and applications characteristics will be illustrated in the following applications schematics. Notes have been added in many cases, attempting to cover any special procedures or unusual characteristics of these applications. A special section called "Application Tips for the LM3914 Adjustable Reference" has been included with these schematics.

Application Hints (Continued)

APPLICATION TIPS FOR THE LM3914s ADJUSTABLE REFERENCE

Greatly Expanded Scale (Bar Mode Only)

Placing the LM3914s internal resistor divider in parallel with a section ($\approx 230\Omega$) of a stable, low resistance divider greatly reduces voltage changes due to IC resistor value changes with temperature. Voltage V_1 should be trimmed to 1.1V first by use of R2. Then the voltage V_2 across the IC divider string can be adjusted to 200 mV, using R5 without affecting V_1 . LED current will be approximately 10 mA.

Non-Interacting Adjustments for Expanded Scale Meter (4.5V to 5V, Bar or Dot Mode)

This arrangement allows independent adjustment of LED brightness regardless of meter span and zero adjustments.

First, V_1 is adjusted to 5V, using R2. Then the span (voltage across R4) can be adjusted to exactly 0.5V using R6 without affecting the previous adjustment.

R9 programs LED currents within a range of 2.2 mA to 20 mA after the above settings are made.

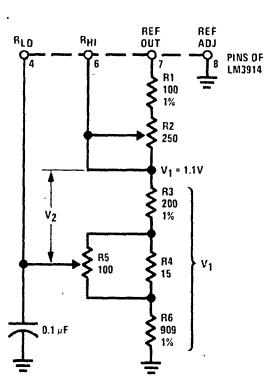
Adjusting Linearity of Several Stacked Dividers

Three internal voltage dividers are shown connected in series to provide a 30-step display. If the resulting analog meter is to be accurate and linear the voltage on each divider must be adjusted, preferably without affecting any other adjustments. To do this, adjust R2 first, so that the voltage across R5 is exactly 1V. Then the voltages across R3 and R4 can be independently adjusted by shunting each with selected resistors of 6 k Ω or higher resistance. This is possible because the reference of LM3914 No. 3 is acting as a constant current source.

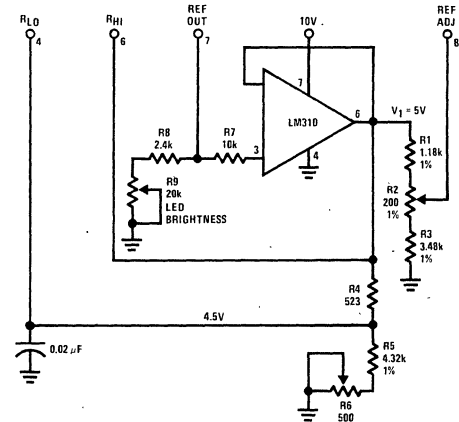
The references associated with LM3914s No. 1 and No. 2 should have their Ref Adj pins (pin 8) wired to ground, and their Ref Outputs loaded by a 620 Ω resistor to ground. This makes available similar 20 mA current outputs to all the LEDs in the system.

If an independent LED brightness control is desired (as in the previous application), a unity gain buffer, such as the LM310, should be placed between pin 7 and R1, similar to the previous application.

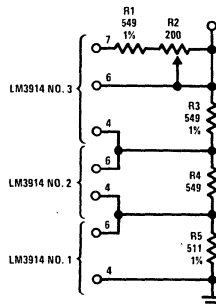
Greatly Expanded Scale (Bar Mode Only)



Non-Interacting Adjustments for Expanded Scale Meter (4.5V to 5V, Bar or Dot Mode)



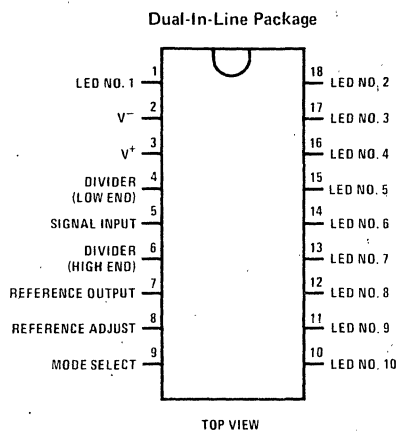
Adjusting Linearity of Several Stacked Dividers



Other Applications

- "Slow" – fade bar or dot display (doubles resolution)
- 20-step meter with single pot brightness control
- 10-step (or multiples) programmer
- Multi-step or "staging" controller
- Combined controller and process deviation meter
- Direction and rate indicator (to add to DVMs)
- Exclamation point display for power saving
- Graduations can be added to dot displays. Dimly light every other LED using a resistor to ground
- Electronic "meter-relay"—display could be circle or semi-circle
- Moving "hole" display—indicator LED is dark, rest of bar lit
- Drives vacuum-fluorescent and LCDs using added passive parts

Connection Diagram



Order Number LM3914N
See NS Package N18A
Order Number LM3914J
See NS Package J18A

LM3915 Dot/Bar Display Driver

General Description

The LM3915 is a monolithic integrated circuit that senses analog voltage levels and drives ten LEDs, LCDs or vacuum fluorescent displays, providing a logarithmic 3 dB/step analog display. One pin changes the display from a bar graph to a moving dot display. LED current drive is regulated and programmable, eliminating the need for current limiting resistors. The whole display system can operate from a single supply as low as 3V or as high as 25V.

The IC contains an adjustable voltage reference and an accurate ten-step voltage divider. The high-impedance input buffer accepts signals down to ground and up to within 1.5V of the positive supply. Further, it needs no protection against inputs of $\pm 35V$. The input buffer drives 10 individual comparators referenced to the precision divider. Accuracy is typically better than 1 dB.

The LM3915's 3 dB/step display is suited for signals with wide dynamic range, such as audio level, power, light intensity or vibration. Audio applications include average or peak level indicators, power meters and RF signal strength meters. Replacing conventional meters with an LED bar graph results in a faster responding, more rugged display with high visibility that retains the ease of interpretation of an analog display.

The LM3915 is extremely easy to apply. A 1.2V full-scale meter requires only one resistor in addition to the ten LEDs. One more resistor programs the full-scale anywhere from 1.2V to 12V independent of supply voltage. LED brightness is easily controlled with a single pot.

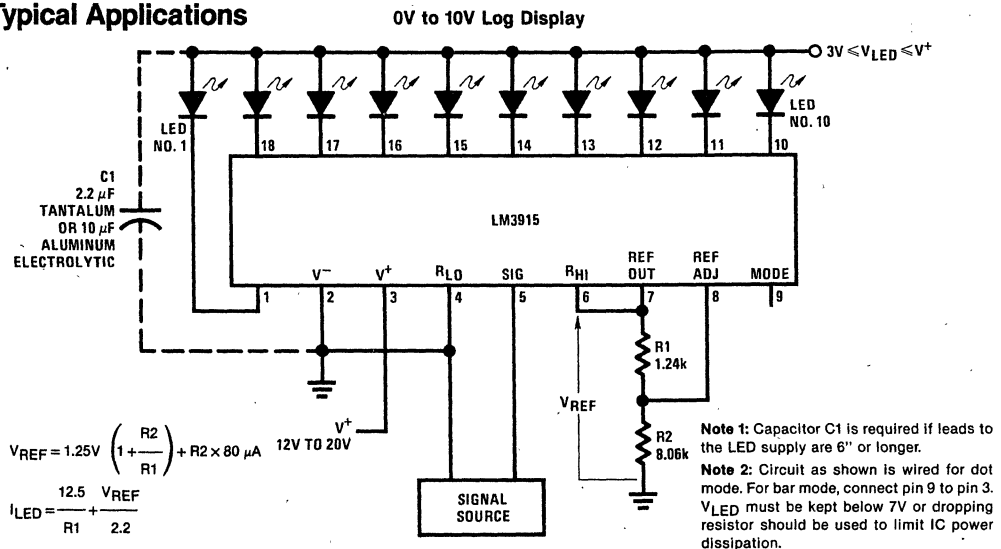
The LM3915 is very versatile. The outputs can drive LCDs, vacuum fluorescents and incandescent bulbs as well as LEDs of any color. Multiple devices can be cascaded for a dot or bar mode display with a range of 60 or 90 dB. LM3915s can also be cascaded with LM3914s for a linear/log display or with LM3916s for an extended-range VU meter.

Features

- 3 dB/step, 30 dB range
- Drives LEDs, LCDs, or vacuum fluorescents
- Bar or dot display mode externally selectable by user
- Expandable to displays of 90 dB
- Internal voltage reference from 1.2V to 12V
- Operates with single supply of 3V to 25V
- Inputs operate down to ground
- Output current programmable from 1 mA to 30 mA
- Input withstands $\pm 35V$ without damage or false outputs
- Outputs are current regulated, open collectors
- Directly drives TTL or CMOS
- The internal 10-step divider is floating and can be referenced to a wide range of voltages

The LM3915 is rated for operation from $0^{\circ}C$ to $+70^{\circ}C$. The LM3915N is available in an 18-lead molded DIP package and the LM3915J comes in the 18-lead ceramic DIP.

Typical Applications



Absolute Maximum Ratings

| | | | |
|----------------------------|--------|--|----------------------------|
| Power Dissipation (Note 5) | 1W | Input Signal Overvoltage (Note 3) | ± 35V |
| Ceramic DIP(J) | 625 mW | Divider Voltage | - 100 mV to V ⁺ |
| Molded DIP(N) | 25V | Reference Load Current | 10 mA |
| Supply Voltage | 25V | Storage Temperature Range | - 55 °C to + 150 °C |
| Voltage on Output Drivers | 25V | Lead Temperature (Soldering, 10 seconds) | 300 °C |

Electrical Characteristics (Note 1)

| Parameter | Conditions (Note 1) | Min | Typ | Max | Units |
|--|---|-------|-------------|-----------|----------|
| Comparators | | | | | |
| Offset Voltage, Buffer and First Comparator | $0V \leq V_{RLO} = V_{RHI} \leq 12V$, $I_{LED} = 1 \text{ mA}$ | | 3 | 10 | mV |
| Offset Voltage, Buffer and Any Other Comparator | $0V \leq V_{RLO} = V_{RHI} \leq 12V$, $I_{LED} = 1 \text{ mA}$ | | 3 | 15 | mV |
| Gain ($\Delta I_{LED} / \Delta V_{IN}$) | $I_{L(REF)} = 2 \text{ mA}$, $I_{LED} = 10 \text{ mA}$ | 3 | 8 | | mA/mV |
| Input Bias Current (at Pin 5) | $0V \leq V_{IN} \leq (V^+ - 1.5V)$ | | 10 | 50 | nA |
| Input Signal Overvoltage | No Change in Display | - 35 | | 35 | V |
| Voltage-Divider | | | | | |
| Divider Resistance | Total, Pin 6 to 4 | 15 | 22 | 30 | kΩ |
| Relative Accuracy (Input Change Between Any Two Threshold Points) | (Note 2) | 2.0 | 3.0 | 4.0 | dB |
| Absolute Accuracy at Each Threshold Point | (Note 2) | | | | |
| | $V_{IN} = -3, -6 \text{ dB}$ | - 0.5 | | + 0.5 | dB |
| | $V_{IN} = -9 \text{ dB}$ | - 0.5 | | + 0.65 | dB |
| | $V_{IN} = -12, -15, -18 \text{ dB}$ | - 0.5 | | + 1.0 | dB |
| | $V_{IN} = -21, -24, -27 \text{ dB}$ | - 0.5 | | + 1.5 | dB |
| Voltage Reference | | | | | |
| Output Voltage | $0.1 \text{ mA} \leq I_{L(REF)} \leq 4 \text{ mA}$, $V^+ = V_{LED} = 5V$ | 1.2 | 1.28 | 1.34 | V |
| Line Regulation | $3V \leq V^+ \leq 18V$ | | 0.01 | 0.03 | %/V |
| Load Regulation | $0.1 \text{ mA} \leq I_{L(REF)} \leq 4 \text{ mA}$, $V^+ = V_{LED} = 5V$ | | 0.4 | 2 | % |
| Output Voltage Change with Temperature | $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$, $I_{L(REF)} = 1 \text{ mA}$, $V^+ = V_{LED} = 5V$ | | 1 | | % |
| Adjust Pin Current | | | 75 | 120 | μA |
| Output Drivers | | | | | |
| LED Current | $V^+ = V_{LED} = 5V$, $I_{L(REF)} = 1 \text{ mA}$ | 7 | 10 | 13 | mA |
| LED Current Difference (Between Largest and Smallest LED Currents) | $V_{LED} = 5V$, $I_{LED} = 2 \text{ mA}$ $V_{LED} = 5V$, $I_{LED} = 20 \text{ mA}$ | | 0.12 1.2 | 0.4 3 | mA mA |
| LED Current Regulation | $2V \leq V_{LED} \leq 17V$ $I_{LED} = 2 \text{ mA}$ $I_{LED} = 20 \text{ mA}$ | | 0.1 1 | 0.25 3 | mA mA |
| Dropout Voltage | $I_{LED(ON)} = 20 \text{ mA}$ @ $V_{LED} = 5V$, $\Delta I_{LED} = 2 \text{ mA}$ | | | 1.5 | V |
| Saturation Voltage | $I_{LED} = 2.0 \text{ mA}$, $I_{L(REF)} = 0.4 \text{ mA}$ | | 0.15 | 0.4 | V |
| Output Leakage, Each Collector | Bar Mode (Note 4) | | 0.1 | 10 | μA |
| Output Leakage | Dot Mode (Note 4) | | | | |
| Pins 10 - 18 | | | 0.1 | 10 | μA |
| Pin 1 | | 60 | 150 | 450 | μA |
| Supply Current | | | | | |
| | $V^+ = +5V$, $I_{L(REF)} = 0.2 \text{ mA}$ | | 2.4 | 4.2 | mA |
| | $V^+ = +20V$, $I_{L(REF)} = 1.0 \text{ mA}$ | | 6.1 | 9.2 | mA |

Notes

Note 1: Unless otherwise stated, all specifications apply with the following conditions:

$$3V_{DC} < V^+ < 20V_{DC}$$

$$3V_{DC} < V_{LED} < V^+$$

$$-0.015V < V_{RH} < 12V_{DC}$$

$$-0.015V < V_{RLO} < 12V_{DC}$$

$$V_{REF}, V_{RH}, V_{RLO} < (V^+ - 1.5V)$$

$$0V < V_{IN} < V^+ - 1.5V$$

$T_A = 25^\circ\text{C}$, $I_L(\text{REF}) = 0.2\text{ mA}$, pin 9 connected to pin 3 (bar mode).
For higher power dissipations, pulse testing is used.

Note 2: Accuracy is measured referred to 0 dB = +10.000V_{DC} at pin 5, with +10.000V_{DC} at pin 6, and 0.000V_{DC} at pin 4. At lower full scale voltages, buffer and comparator offset voltage may add significant error. See table for threshold voltages.

Note 3: Pin 5 input current must be limited to $\pm 3\text{ mA}$. The addition of a 39k resistor in series with pin 5 allows $\pm 100\text{V}$ signals without damage.

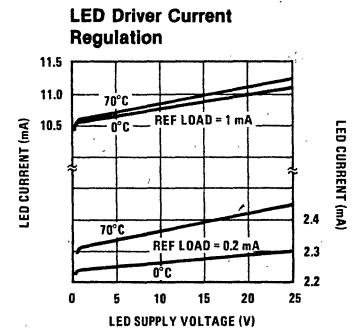
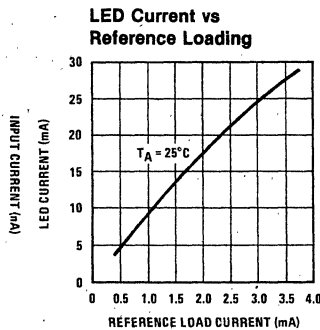
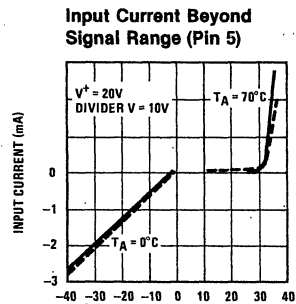
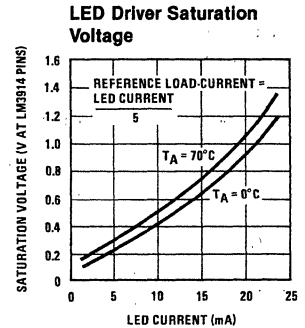
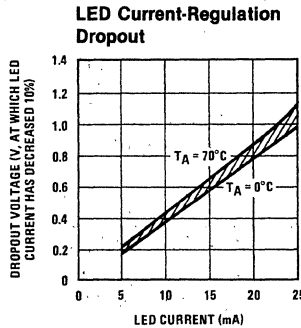
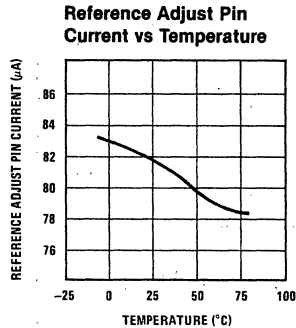
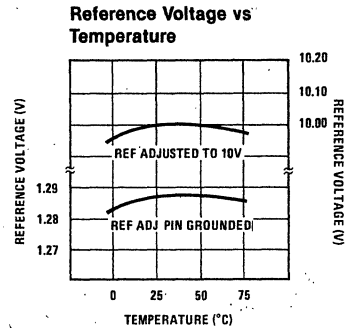
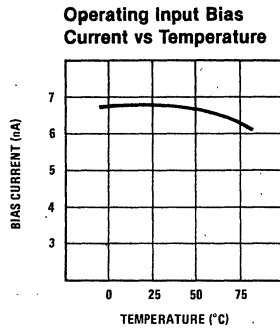
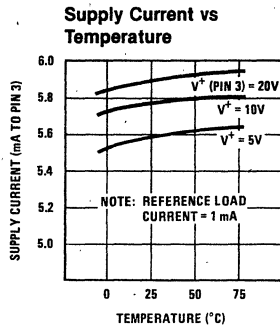
Note 4: Bar mode results when pin 9 is within 20 mV of V^+ . Dot mode results when pin 9 is pulled at least 200 mV below V^+ . LED #10 (pin 10 output current) is disabled if pin 9 is pulled 0.9V or more below V_{LED} .

Note 5: The maximum junction temperature of the LM3915 is 100°C. Devices must be derated for operation at elevated temperatures. Junction to ambient thermal resistance is 75°C/W for the ceramic DIP (J package) and 120°C/W for the molded DIP (N package).

THRESHOLD VOLTAGE (Note 2)

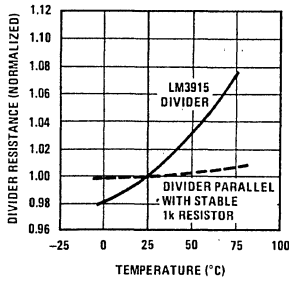
| Output | dB | Min | Typ | Max | Output | dB | Min | Typ | Max |
|--------|-----|-------|-------|-------|--------|-----|-------|-------|--------|
| 1 | -27 | 0.422 | 0.447 | 0.531 | 6 | -12 | 2.372 | 2.512 | 2.819 |
| 2 | -24 | 0.596 | 0.631 | 0.750 | 7 | -9 | 3.350 | 3.548 | 3.825 |
| 3 | -21 | 0.841 | 0.891 | 1.059 | 8 | -6 | 4.732 | 5.012 | 5.309 |
| 4 | -18 | 1.189 | 1.259 | 1.413 | 9 | -3 | 6.683 | 7.079 | 7.498 |
| 5 | -15 | 1.679 | 1.778 | 1.995 | 10 | 0 | 9.985 | 10 | 10.015 |

Typical Performance Characteristics

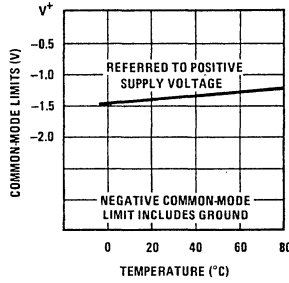


Typical Performance Characteristics (Continued)

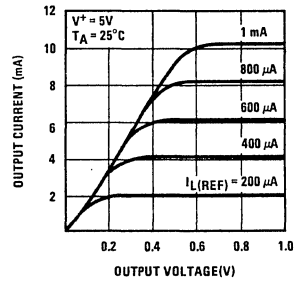
Total Divider Resistance vs Temperature



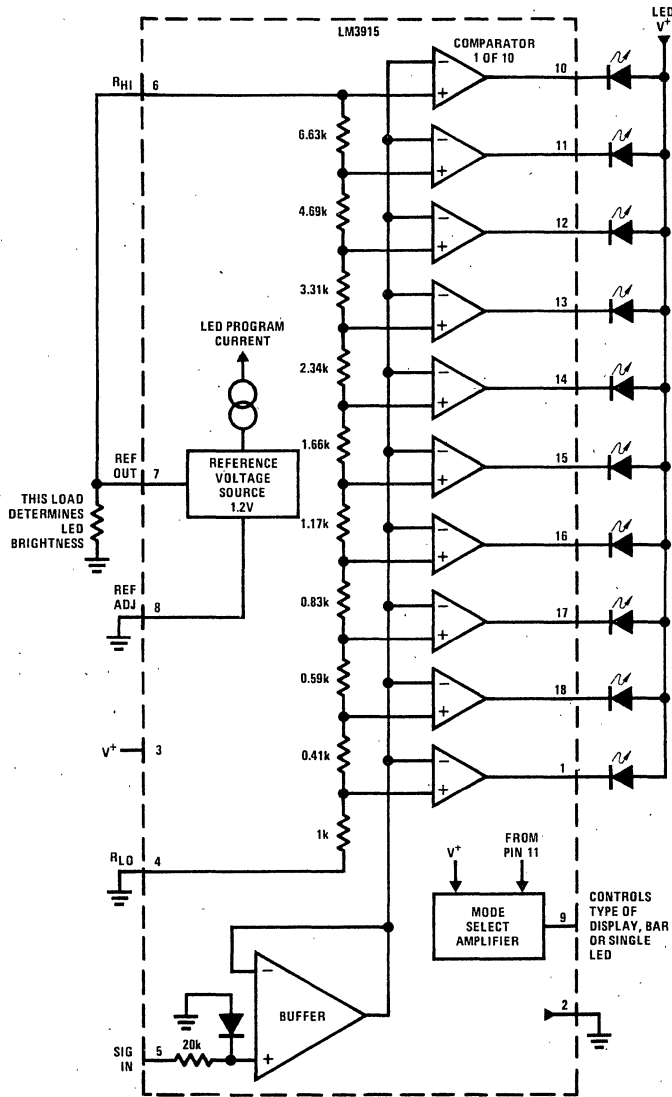
Common-Mode Limits



Output Characteristics



Block Diagram (Showing Simplest Application)



Functional Description

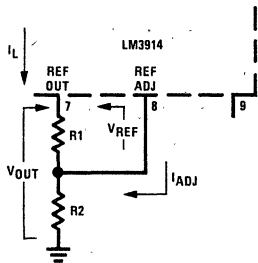
The simplified LM3915 block diagram is included to give the general idea of the circuit's operation. A high input impedance buffer operates with signals from ground to 12V, and is protected against reverse and overvoltage signals. The signal is then applied to a series of 10 comparators; each of which is biased to a different comparison level by the resistor string.

In the example illustrated, the resistor string is connected to the internal 1.25V reference voltage. In this case, for each 3 dB that the input signal increases, a comparator will switch on another indicating LED. This resistor divider can be connected between any 2 voltages, providing that they are at least 1.5V below V^+ and no lower than V^- .

Internal Voltage Reference

The reference is designed to be adjustable and develops a nominal 1.25V between the REF OUT (pin 7) and REF ADJ (pin 8) terminals. The reference voltage is impressed across program resistor R_1 and, since the voltage is constant, a constant current I_1 then flows through the output set resistor R_2 giving an output voltage of:

$$V_{OUT} = V_{REF} \left(1 + \frac{R_2}{R_1} \right) + I_{ADJ} R_2$$



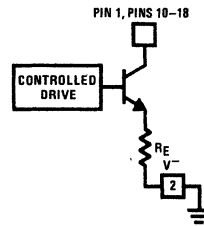
Since the 120 μ A current (max) from the adjust terminal represents an error term, the reference was designed to minimize changes of this current with V^+ and load changes. For correct operation, reference load current should be between 80 μ A and 5 mA. Load capacitance should be less than 0.05 μ F.

Current Programming

A feature not completely illustrated by the block diagram is the LED brightness control. The current drawn out of the reference voltage pin (pin 7) determines LED current. Approximately 10 times this current will be drawn through each lighted LED, and this current will be relatively constant despite supply voltage and temperature changes. Current drawn by the internal 10-resistor divider, as well as by the external current and voltage-setting divider should be included in calculating LED drive current. The ability to modulate LED brightness with time, or in proportion to input voltage and other signals can lead to a number of novel displays or ways of indicating input overvoltages, alarms, etc.

The LM3915 outputs are current-limited NPN transistors as shown below. An internal feedback loop regulates the transistor drive. Output current is held at about 10 times the reference load current, independent of output voltage and processing variables, as long as the transistor is not saturated.

LM3915 Output Circuit



Outputs may be run in saturation with no adverse effects, making it possible to directly drive logic. The effective saturation resistance of the output transistors, equal to R_E plus the transistors' collector resistance, is about 50 Ω . It's also possible to drive LEDs from rectified AC with no filtering. To avoid oscillations, the LED supply should be bypassed with a 2.2 μ F tantalum or 10 μ F aluminum electrolytic capacitor.

Mode Pin Use

Pin 9, the Mode Select input, permits chaining of multiple LM3915s, and controls bar or dot mode operation. The following tabulation shows the basic ways of using this input. Other more complex uses will be illustrated in the applications.

Bar Graph Display: Wire Mode Select (pin 9) directly to pin 3 (V^+ pin).

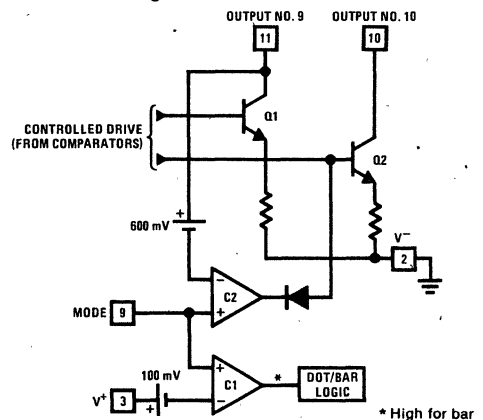
Dot Display, Single LM3915 Driver: Leave the Mode Select pin open circuit.

Dot Display, 20 or More LEDs: Connect pin 9 of the first driver in the series (i.e., the one with the lowest input voltage comparison points) to pin 1 of the next higher LM3915 driver. Continue connecting pin 9 of lower input drivers to pin 1 of higher input drivers for 30 or more LED displays. The last LM3915 driver in the chain will have pin 9 left open. All previous drivers should have a 20k resistor in parallel with LED #9 (pin 11 to V_{LED}).

Mode Pin Functional Description

This pin actually performs two functions. Refer to the simplified block diagram below.

Block Diagram of Mode Pin Function



Mode Pin Functional Description (Continued)

Dot or Bar Mode Selection

The voltage at pin 9 is sensed by comparator C1, nominally referenced to ($V^+ - 100$ mV). The chip is in bar mode when pin 9 is above this level; otherwise it's in dot mode. The comparator is designed so that pin 9 can be left open circuit for dot mode.

Taking into account comparator gain and variation in the 100 mV reference level, pin 9 should be no more than 20 mV below V^+ for bar mode and more than 200 mV below V^+ (or open circuit) for dot mode. In most applications, pin 9 is either open (dot mode) or tied to V^+ (bar mode). In bar mode, pin 9 should be connected directly to pin 3. Large currents drawn from the power supply (LED current, for example) should not share this path so that large IR drops are avoided.

Dot Mode Carry

In order for the display to make sense when multiple LM3915s are cascaded in dot mode, special circuitry has been included to shut off LED #10 of the first device when LED #1 of the second device comes on. The connection for cascading in dot mode has already been described and is depicted below.

As long as the input signal voltage is below the threshold of the second LM3915, LED #11 is off. Pin 9 of LM3915 #1 thus sees effectively an open circuit so the chip is in dot mode. As soon as the input voltage reaches the threshold of LED #11, pin 9 of LM3915 #1 is pulled an LED drop (1.5V or more) below V_{LED} . This condition is sensed by comparator C2, referenced 600 mV below V_{LED} . This forces the output of C2 low, which shuts off output transistor Q2, extinguishing LED #10.

V_{LED} is sensed via the 20k resistor connected to pin 11. The very small current (less than 100 μ A) that is diverted from LED #9 does not noticeably affect its intensity.

An auxiliary current source at pin 1 keeps at least 100 μ A flowing through LED #11 even if the input voltage rises high enough to extinguish the LED. This ensures that pin 9 of LM3915 #1 is held low enough to force LED #10 off when any higher LED is illuminated. While 100 μ A does not normally produce significant LED illumination, it may be noticeable when using high-efficiency LEDs in a dark environment. If this is bothersome, the simple cure is to shunt LED #11 with a 10k resistor. The 1V IR drop is more than the 900 mV worst case required to hold off LED #10 yet small enough that LED #11 does not conduct significantly.

Other Device Characteristics

The LM3915 is relatively low-powered itself, and since any number of LEDs can be powered from about 3V, it is a very efficient display driver. Typical standby supply current (all LEDs OFF) is 1.6 mA (2.5 mA max). However, any reference loading adds 4 times that current drain to the V^+ (pin 3) supply input. For example, an LM3915 with a 1 mA reference pin load (1.3k) would supply almost 10 mA to every LED while drawing only 5.6 mA from its V^+ pin supply. At full-scale, the IC is typically drawing less than 7% of the current supplied to the display.

The display driver does not have built-in hysteresis so that the display does not jump instantly from one LED to the next. Under rapidly changing signal conditions, this cuts down high frequency noise and often an annoying flicker. An "overlap" is built in so that at no time are all segments completely off in the dot mode. Generally 1 LED fades in while the other fades out over a mV or more of range. The change may be much more rapid between LED #10 of one device and LED #1 of a second device "chained" to the first.

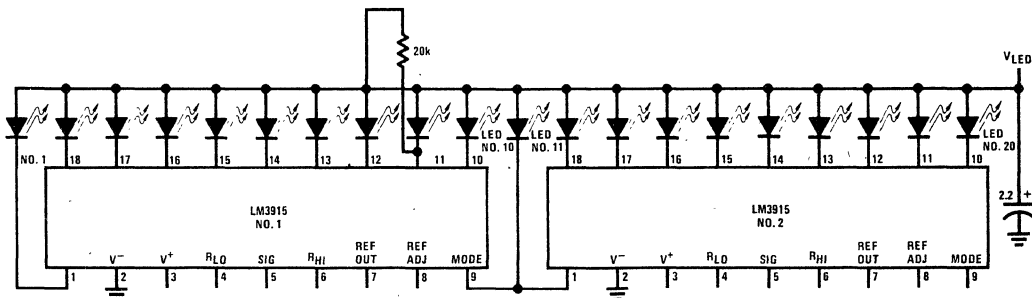
Application Hints

The most difficult problem occurs when large LED currents are being drawn, especially in bar graph mode. These currents flowing out of the ground pin cause voltage drops in external wiring, and thus errors and oscillations. Bringing the return wires from signal sources, reference ground and bottom of the resistor string to a single point very near pin 2 is the best solution.

Long wires from V_{LED} to LED anode common can cause oscillations. Depending on the severity of the problem 0.05 μ F to 2.2 μ F decoupling capacitors from LED anode common to pin 2 will damp the circuit. If LED anode line wiring is inaccessible, often similar decoupling from pin 1 to pin 2 will be sufficient.

If LED turn ON seems slow (bar mode) or several LEDs light (dot mode), oscillation or excessive noise is usually the problem. In cases where proper wiring and bypassing fail to stop oscillations, V^+ voltage at pin 3 is usually below suggested limits. Expanded scale meter applications may have one or both ends of the internal voltage divider terminated at relatively high value resistors. These high-impedance ends should be bypassed to pin 2 with at least a 0.001 μ F capacitor, or up to 0.1 μ F in noisy environments.

Cascading LM3915s in Dot Mode



Application Hints (Continued)

Power dissipation, especially in bar mode should be given consideration. For example, with a 5V supply and all LEDs programmed to 20 mA the driver will dissipate over 600 mW. In this case a 7.5Ω resistor in series with the LED supply will cut device heating in half. The negative end of the resistor should be bypassed with a 2.2 μF solid tantalum capacitor to pin 2.

Tips on Rectifier Circuits

The simplest way to display an AC signal using the LM3915 is to apply it right to pin 5 unrectified. Since the LED illuminated represents the instantaneous value of the AC waveform, one can readily discern both peak and average values of audio signals in this manner. The LM3915 will respond to positive half-cycles only but will not be damaged by signals up to ±35V (or up to ±100V if a 39k resistor is in series with the input). It's recommended to use dot mode and to run the LEDs at 30 mA for high enough average intensity.

True average or peak detection requires rectification. If an LM3915 is set up with 10V full scale across its voltage divider, the turn-on point for the first LED is only 450 mV. A simple silicon diode rectifier won't work well at the low end due to the 600 mV diode threshold. The half-wave peak detector in Figure 1 uses a PNP emitter-follower in front of the diode. Now, the transistor's base-emitter voltage cancels out the diode offset, within about 100 mV. This approach is usually satisfactory when a single LM3915 is used for a 30 dB display.

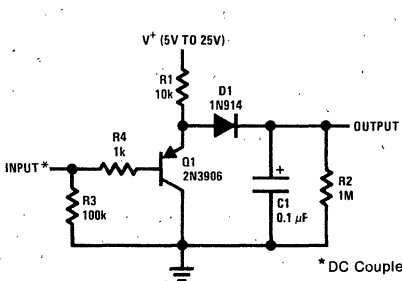


FIGURE 1. Half-Wave Peak Detector

Display circuits using two or more LM3915s for a dynamic range of 60 dB or greater require more accurate detection. In the precision half-wave rectifier of Figure 2 the effective diode offset is reduced by a factor equal to the open-loop gain of the op amp. Filter capacitor C2 charges through R3 and discharges through R2 and R3, so that appropriate selection of these values results in either a peak or an average detector. The circuit has a gain equal to R2/R1.

It's best to capacitively couple the input. Audio sources frequently have a small DC offset that can cause significant error at the low end of the log display. Op amps that slew quickly, such as the LF351, LF353 or LF356, are needed to faithfully respond to sudden transients. It may be necessary to trim out the op amp DC offset voltage to accurately cover a 60 dB range. Best results are obtained if the circuit is adjusted for the correct output when a low-level AC signal (10 to 20 mV) is applied, rather than adjusting for zero output with zero input.

For precision full-wave averaging use the circuit in Figure 3. Using 1% resistors for R1 through R4, gain for positive and negative signal differs by only 0.5 dB worst case. Substituting 5% resistors increases this to 2 dB worst case. (A 2 dB gain difference means that the display may have a ±1 dB error when the input is a nonsymmetrical transient). The averaging time constant is R5 · C2. A simple modification results in the precision full-wave detector of Figure 4. Since the filter capacitor is not buffered, this circuit can drive only high impedance loads such as the input of an LM3915.

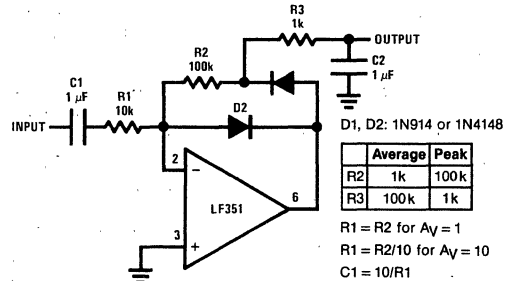


FIGURE 2. Precision Half-Wave Rectifier

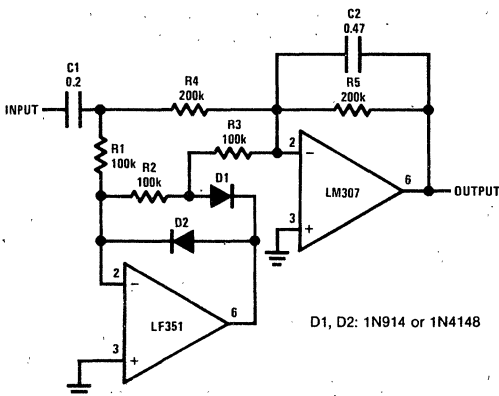


FIGURE 3. Precision Full-Wave Average Detector

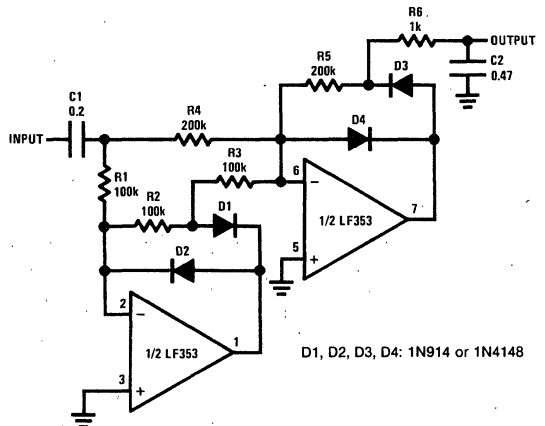


FIGURE 4. Precision Full-Wave Peak Detector

Application Hints (Continued)

Cascading the LM3915

To display signals of 60 or 90 dB dynamic range, multiple LM3915s can be easily cascaded. Alternatively, it is possible to cascade an LM3915 with LM3914s for a log/linear display or with an LM3916 to get an extended range VU meter.

A simple, low cost approach to cascading two LM3915s is to set the reference voltages of the two chips 30 dB apart as in *Figure 5*. Potentiometer R1 is used to adjust the full scale voltage of LM3915 #1 to 316 mV nominally while the second IC's reference is set at 10V by R4. The drawback of this method is that the threshold of LED #1 is only 14 mV and, since the LM3915 can have an offset voltage as high as 10 mV, large errors can occur. This technique is not recommended for 60 dB displays requiring good accuracy at the first few display thresholds.

A better approach shown in *Figure 6* is to keep the reference at 10V for both LM3915s and amplify the input

signal to the lower LM3915 by 30 dB. Since two 1% resistors can set the amplifier gain within ± 0.2 dB, a gain trim is unnecessary. However, an op amp offset voltage of 5 mV will shift the first LED threshold as much as 4 dB, so that an offset trim may be required. Note that a single adjustment can null out offset in both the precision rectifier and the 30 dB gain stage. Alternatively, instead of amplifying, input signals of sufficient amplitude can be fed directly to the lower LM3915 and *attenuated* by 30 dB to drive the second LM3915.

To extend this approach to get a 90 dB display, another 30 dB of amplification must be placed in the signal path ahead of the lowest LM3915. Extreme care is required as the lowest LM3915 displays input signals down to 0.5 mV! Several offset nulls may be required. High currents should not share the same path as the low level signal. Also power line wiring should be kept away from signal lines.

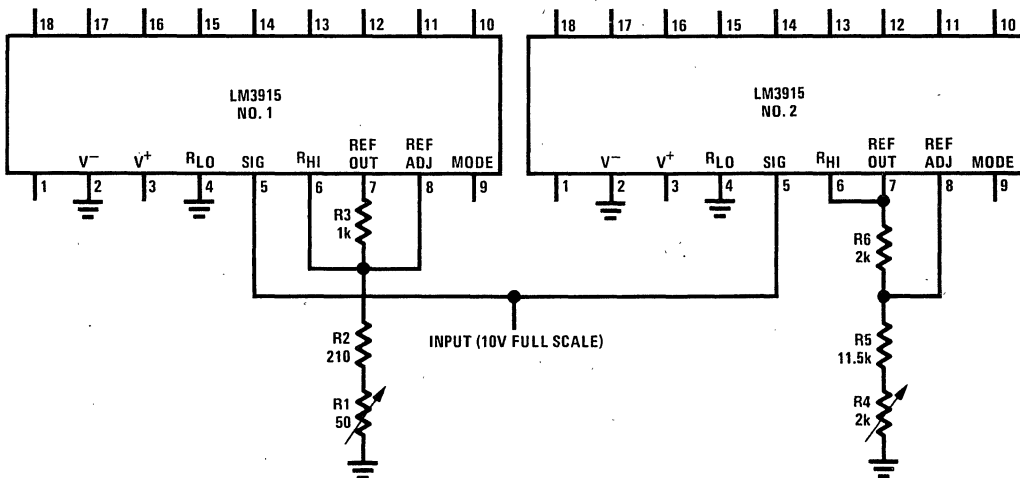


FIGURE 5. Low Cost Circuit for 60 dB Display

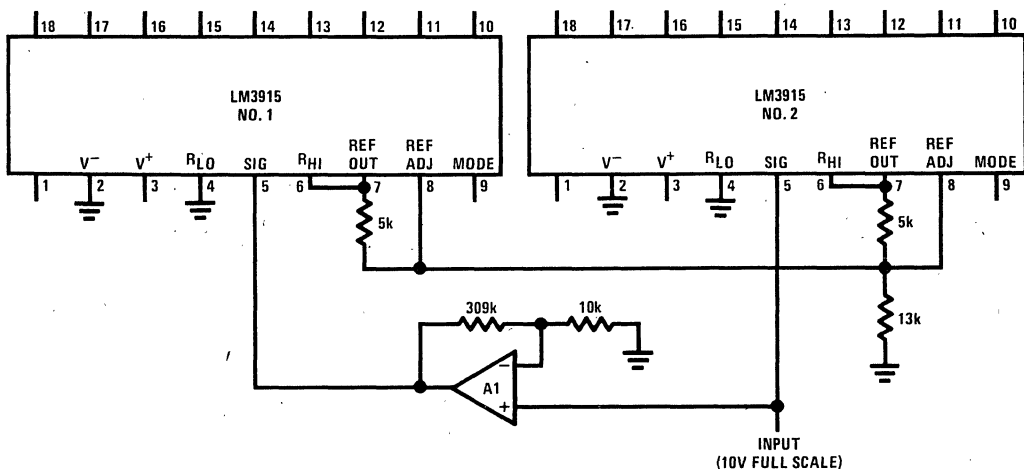


FIGURE 6. Improved Circuit for 60 dB Display

Application Hints (Continued)

TIPS ON REFERENCE VOLTAGE AND LED CURRENT PROGRAMMING

Single LM3915

The equations in *Figure 7* illustrate how to choose resistor values to set reference voltage for the simple case where no LED intensity adjustment is required. A LED current of 10 mA to 20 mA generally produces adequate illumination. Having 10V full-scale across the internal voltage divider gives best accuracy by keeping signal level high relative to the offset voltage of the internal comparators. However, this causes 450 μ A to flow from pin 7 into the divider which means that the LED current will be at least 5 mA. R1 will typically be between 1 k Ω and 2 k Ω . To trim the reference voltage, vary R2.

The circuit in *Figure 8* shows how to add a LED intensity control which can vary LED current from 9 mA to 28 mA.

The reference adjustment has some effect on LED intensity but the reverse is not true.

Multiple LM3915s

Figure 9 shows how to obtain a common reference trim and intensity control for two LM3915s. The two ICs may be connected in cascade for a 60 dB display or may be handling separate channels for stereo. This technique can be extended for larger numbers of LM3915s by varying the values of R1, R2 and R3 in inverse proportion to the number of devices tied in. The ICs' internal references track within 100 mV so that worst case error from chip to chip is only 0.1 dB for $V_{REF} = 10V$.

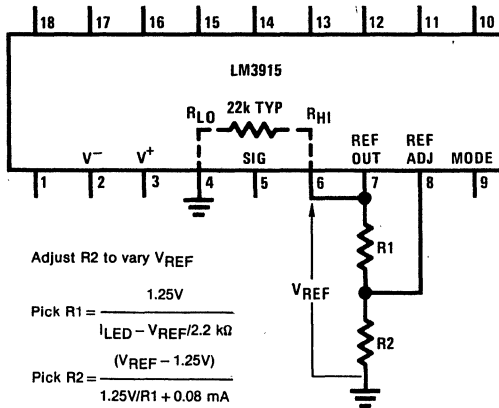


FIGURE 7. Design Equations for Fixed LED Intensity

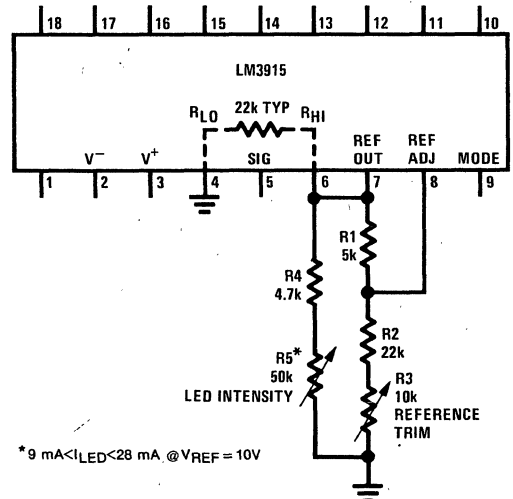


FIGURE 8. Varying LED Intensity

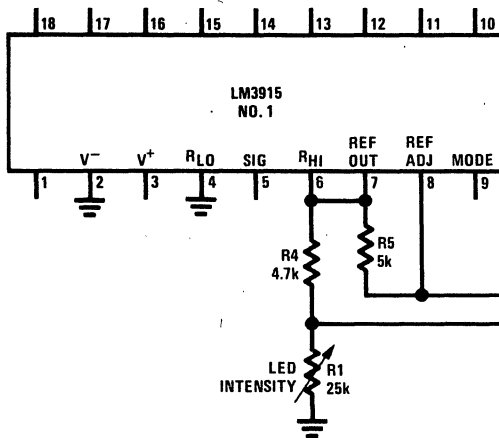


FIGURE 9. Independent Adjustment of Reference Voltage and LED Intensity for Multiple LM3915s

Application Hints (Continued)

The scheme in *Figure 10* is useful when the reference and LED intensity must be adjusted independently over a wide range. The R_{HI} voltage can be adjusted from 1.2V to 10V with no effect on LED current. Since the internal divider here does not load down the reference, minimum LED current is much lower. At the minimum recommended reference load of 80 μ A, LED current is about 0.8 mA. The resistor values shown give a LED current range from 1.5 mA to 20 mA.

At the low end of the intensity adjustment, the voltage drop across the 510 Ω current-sharing resistors is so small that chip to chip variation in reference voltage may yield a visible variation in LED intensity. The optional approach shown of connecting the bottom end of the intensity control pot to a negative supply overcomes this problem by allowing a larger voltage drop across the (larger) current-sharing resistors.

Other Applications

For increased resolution, it's possible to obtain a display with a smooth transition between LEDs. This is accomplished by varying the reference level at pin 6 by 3 dBp-p as shown in *Figure 11*. The signal can be a triangle, sawtooth or sine wave from 60 Hz to 1 kHz. The display can be run in either dot or bar mode.

When an exponentially decaying RC discharge waveform is applied to pin 5, the LM3915's outputs will switch at equal intervals. This makes a simple timer or sequencer. Each time interval is equal to RC/3. The output may be used to drive logic, opto-couplers, relays or PNP transistors, for example.

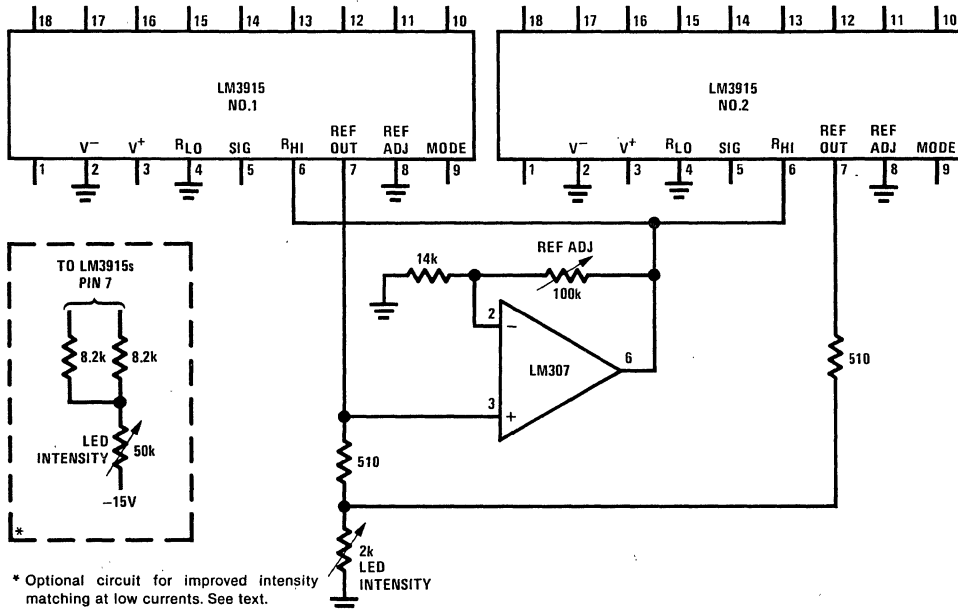


FIGURE 10. Wide-Range Adjustment of Reference Voltage and LED Intensity for Multiple LM3915s

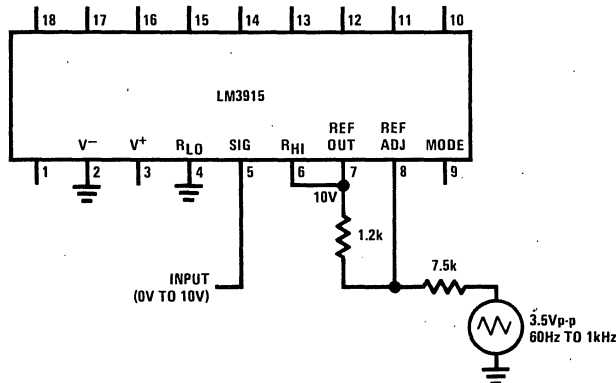
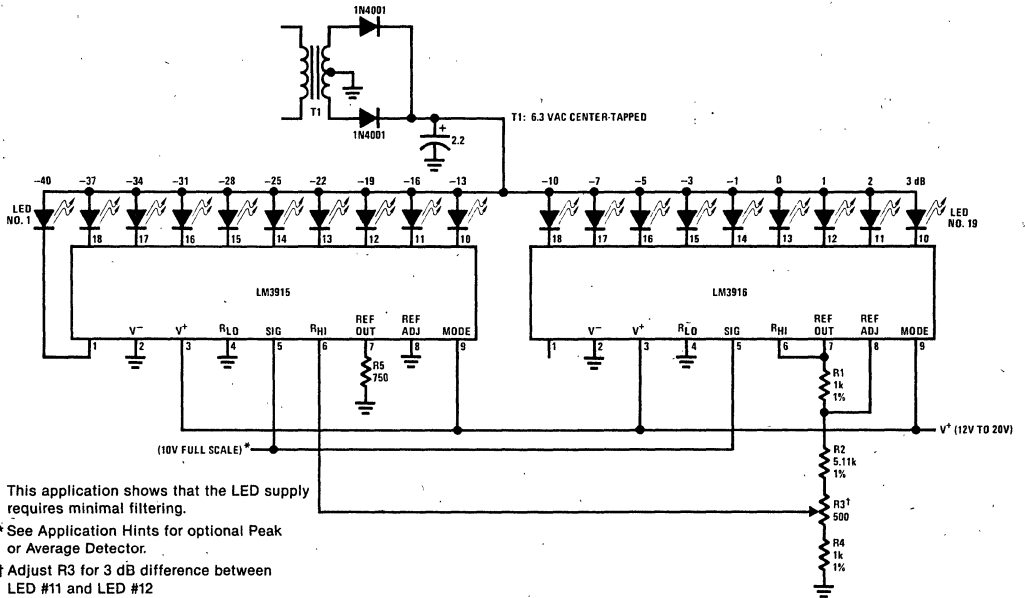


FIGURE 11. 0V to 10V Log Display with Smooth Transitions

Typical Applications (Continued) Extended Range VU Meter

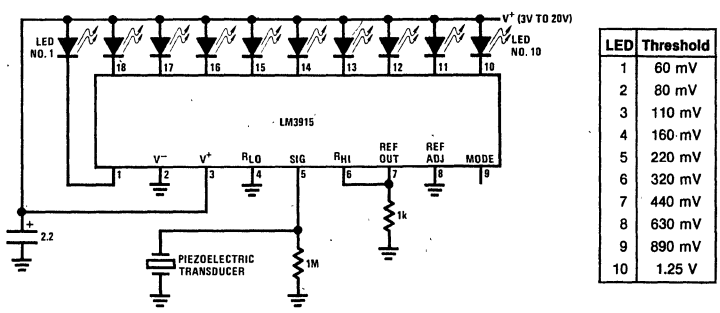


This application shows that the LED supply requires minimal filtering.

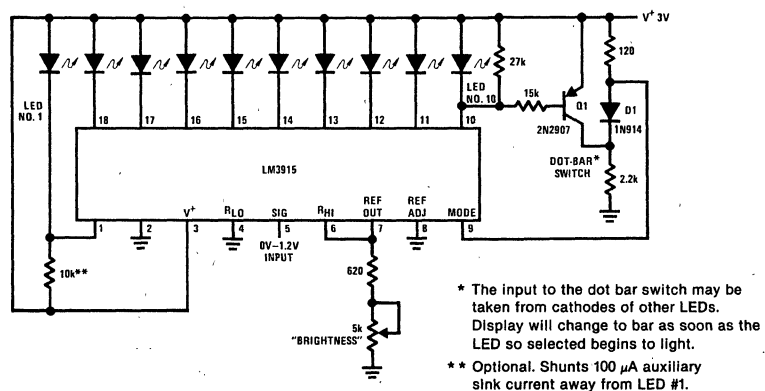
* See Application Hints for optional Peak or Average Detector.

† Adjust R3 for 3 dB difference between LED #11 and LED #12

Vibration Meter



Indicator and Alarm, Full-Scale Changes Display From Dot to Bar

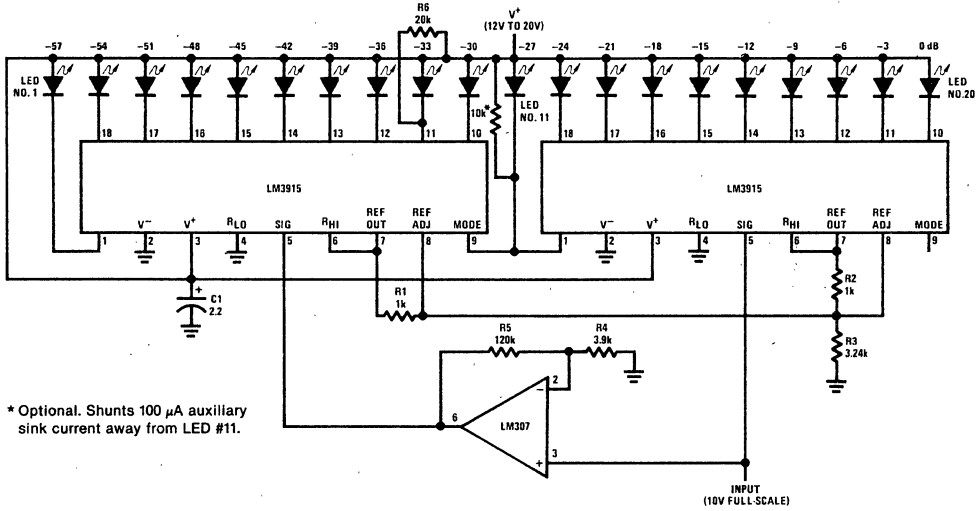


* The input to the dot bar switch may be taken from cathodes of other LEDs. Display will change to bar as soon as the LED so selected begins to light.

** Optional. Shunts 100 μ A auxiliary sink current away from LED #1.

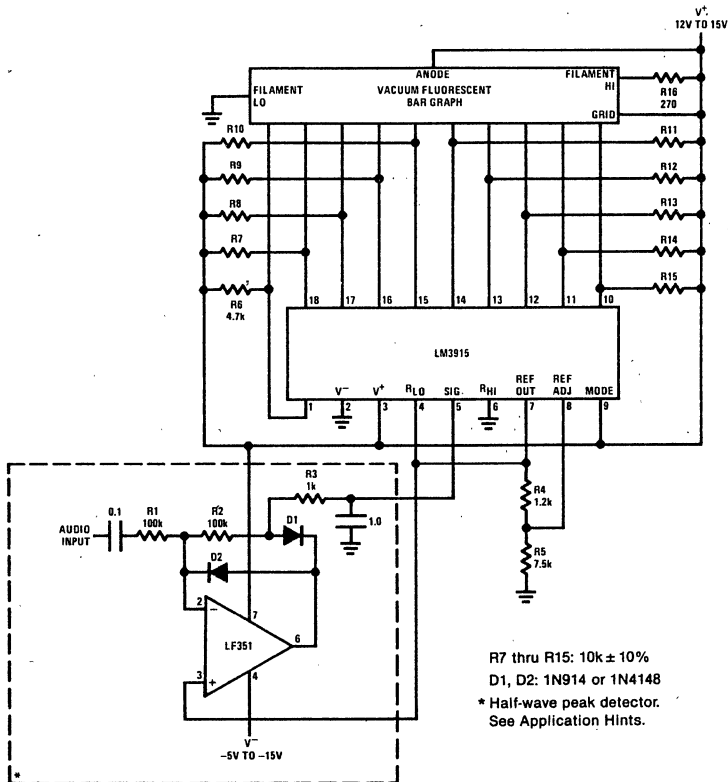
Typical Applications (Continued)

60 dB Dot Mode Display



* Optional. Shunts 100 μ A auxiliary sink current away from LED #11.

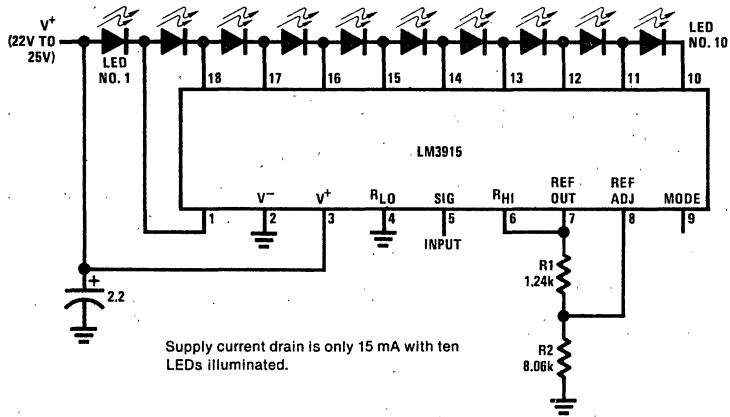
Driving Vacuum Fluorescent Display



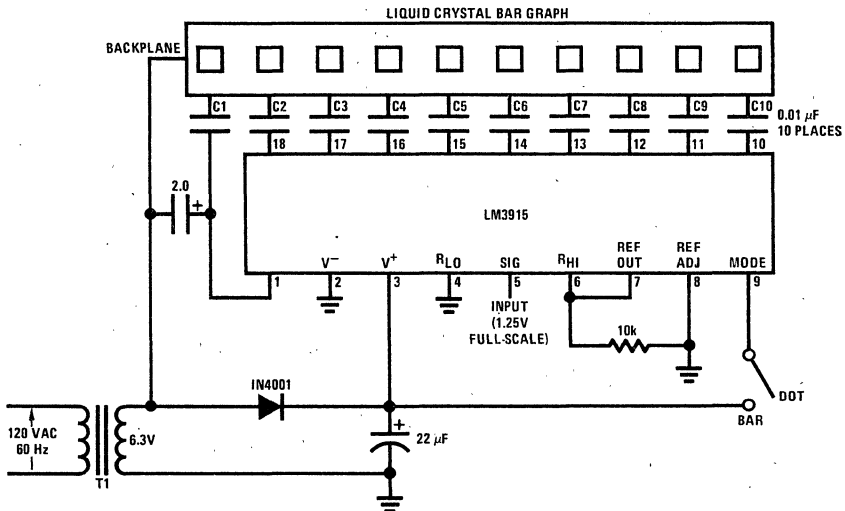
R7 thru R15: 10k \pm 10%
 D1, D2: 1N914 or 1N4148
 * Half-wave peak detector.
 See Application Hints.

Typical Applications (Continued)

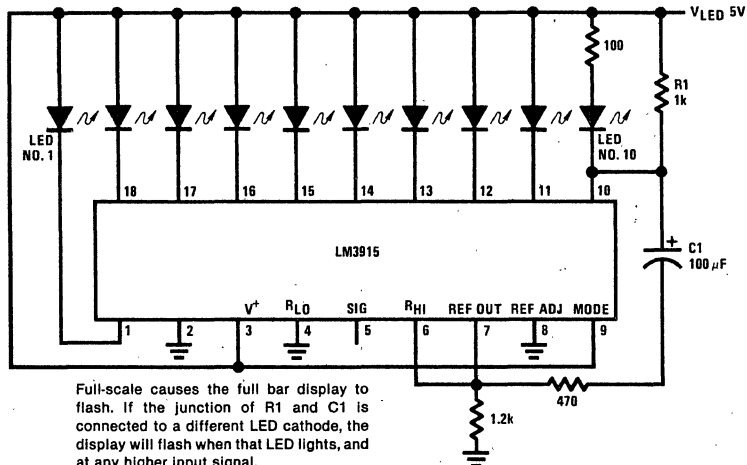
Low Current Bar Mode Display



Driving Liquid Crystal Display

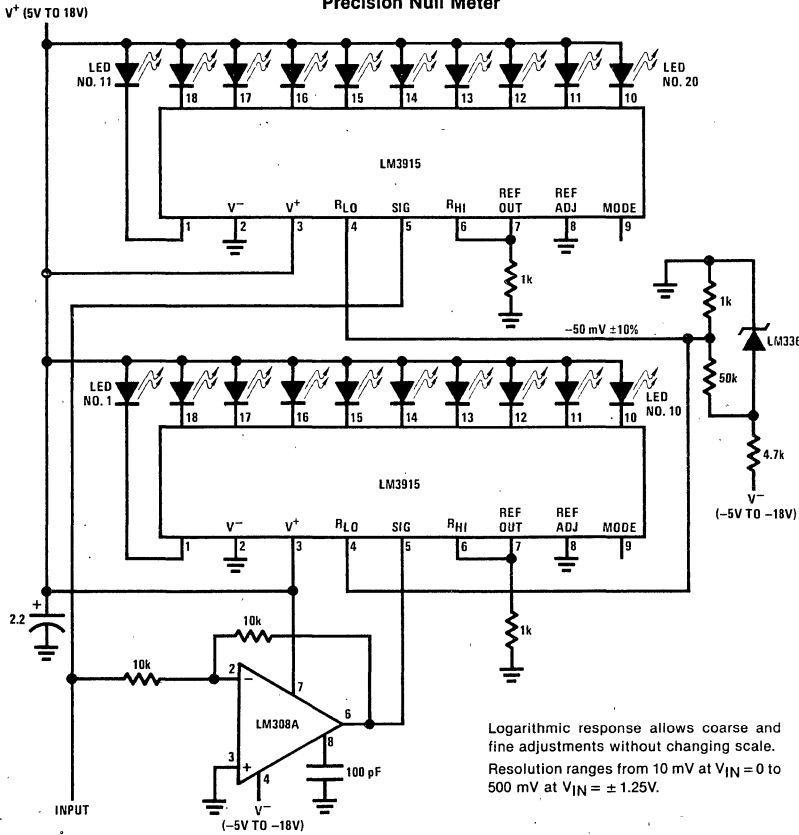


Bar Display with Alarm Flasher

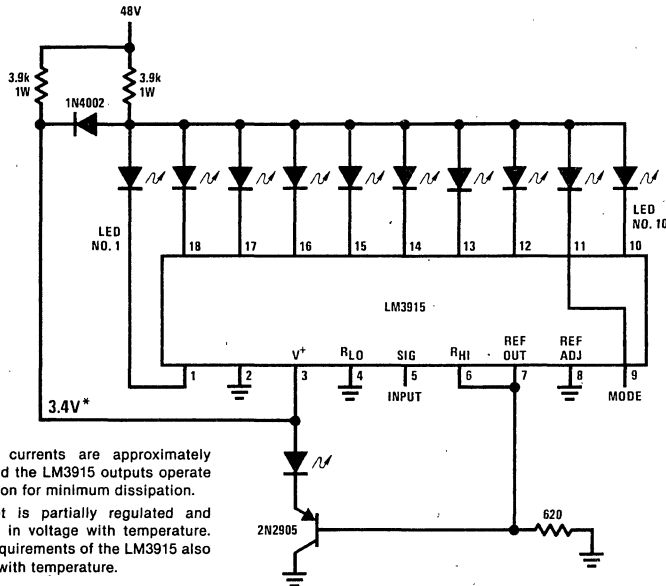


Typical Applications (Continued)

Precision Null Meter



Operating with a High Voltage Supply (Dot Mode Only)

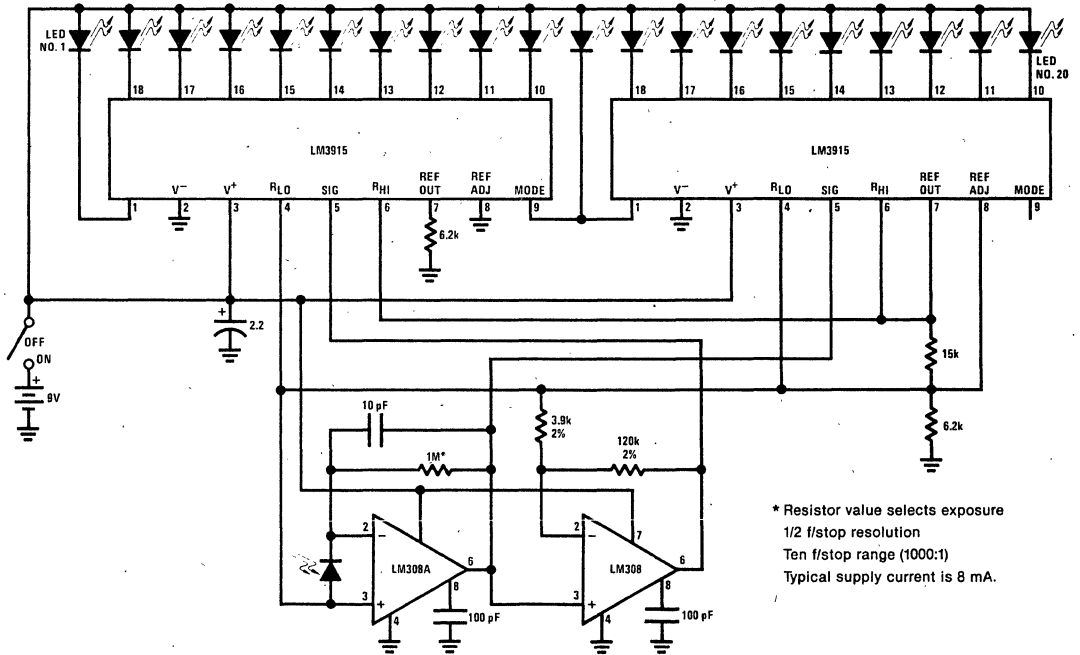


The LED currents are approximately 10 mA, and the LM3915 outputs operate in saturation for minimum dissipation.

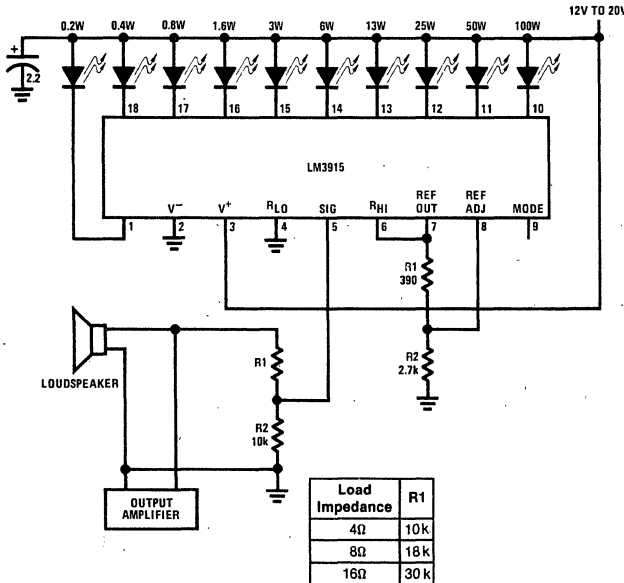
* This point is partially regulated and decreases in voltage with temperature. Voltage requirements of the LM3915 also decrease with temperature.

Typical Applications (Continued)

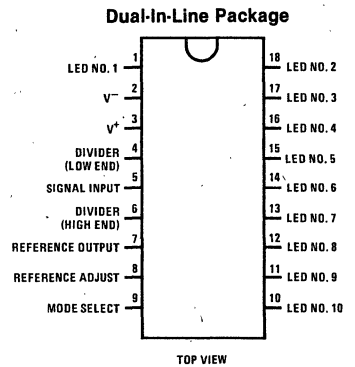
Light Meter



Audio Power Meter



Connection Diagram



Order Number LM3915J
See NS Package J18A
Order Number LM3915N
See NS Package N18A

See Application Hints for optional Peak or Average Detector

Definition of Terms

Absolute Accuracy: The difference between the observed threshold voltage and the ideal threshold voltage for each comparator. Specified and tested with 10V across the internal voltage divider so that resistor ratio matching error predominates over comparator offset voltage.

Adjust Pin Current: Current flowing out of the reference adjust pin when the reference amplifier is in the linear region.

Comparator Gain: The ratio of the change in output current (I_{LED}) to the change in input voltage (V_{IN}) required to produce it for a comparator in the linear region.

Dropout Voltage: The voltage measured at the current source outputs required to make the output current fall by 10%.

Input Bias Current: Current flowing out of the signal input when the input buffer is in the linear region.

LED Current Regulation: The change in output current over the specified range of LED supply voltage (V_{LED}) as measured at the current source outputs. As the forward

voltage of an LED does not change significantly with a small change in forward current, this is equivalent to changing the voltage at the LED anodes by the same amount.

Line Regulation: The average change in reference output voltage (V_{REF}) over the specified range of supply voltage (V^+).

Load Regulation: The change in reference output voltage over the specified range of load current ($I_{L(REF)}$).

Offset Voltage: The differential input voltage which must be applied to each comparator to bias the output in the linear region. Most significant error when the voltage across the internal voltage divider is small. Specified and tested with pin 6 voltage (V_{RH}) equal to pin 4 voltage (V_{RLO}).

Relative Accuracy: The difference between any two adjacent threshold points. Specified and tested with 10V across the internal voltage divider so that resistor ratio matching error predominates over comparator offset voltage.

LM13600/LM13600A/LM11600A Dual Operational Transconductance Amplifiers With Linearizing Diodes and Buffers

General Description

The LM13600 series consists of two current controlled transconductance amplifiers each with differential inputs and a push pull output. The two amplifiers share common supplies but otherwise operate independently. Linearizing diodes are provided at the inputs to reduce distortion and allow higher input levels. The results is a 10 dB signal-to-noise improvement referenced to 0.5 percent THD. Controlled impedance buffers are provided which are especially designed to complement the dynamic range of the amplifiers.

- Excellent gm linearity
- Excellent matching between amplifiers
- Linearizing diodes
- Controlled impedance buffers
- High output signal to noise ratio
- Wide supply range $\pm 2V$ to $\pm 22V$.

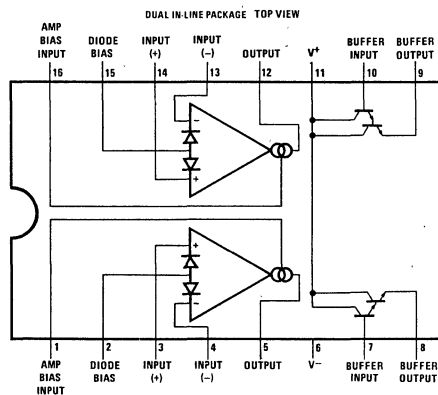
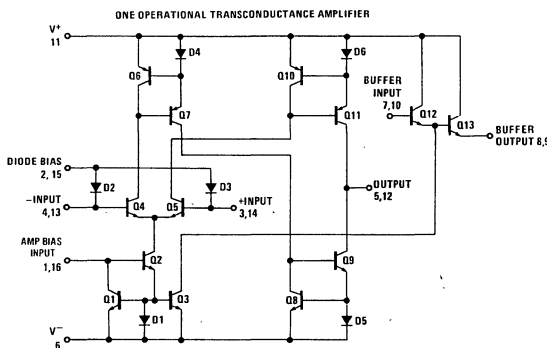
Features

- gm adjustable over 6 decades

Applications

- Current controlled amplifiers
- Current controlled impedances
- Current controlled filters
- Current controlled oscillators
- Multiplexers
- Timers
- Sample and hold circuits

Schematic and Connection Diagrams



Order Number LM11600AJ
See NS Package J16A
Order Number LM13600N
or LM13600AN
See NS Package N16A

Absolute Maximum Ratings

| | | |
|---|--|-------------------------------------|
| Supply Voltage (Note 1) | | |
| LM13600 | | 36 V _{DC} or ± 18 V |
| LM13600A, LM11600A | | 44 V _{DC} or ± 22 V |
| Power Dissipation (Note 2) T _A = 25° C | | |
| LM13600N, LM13600AN | | 570 mW |
| LM13600J, LM11600AJ | | 600 mW |
| Differential Input Voltage | | ± 5 V |
| Diode Bias Current (I _D) | | 2 mA |
| Amplifier Bias Current (I _{ABC}) | | 2 mA |
| Output Short Circuit Duration | | Indefinite |
| Buffer Output Current (Note 3) | | 20 mA |
| Operating Temperature Range | | |
| LM13600N, LM13600AN, LM13600J | | 0° C to + 70° C |
| LM11600AJ | | -55° C to + 125° C |
| DC Input Voltage | | + V _S to -V _S |
| Storage Temperature Range | | -65° C to + 150° C |
| Lead Temperature (Soldering, 10 Seconds) | | 300° C |

Electrical Characteristics (Note 4)

| Parameters | Conditions | LM13600 | | | LM13600A LM11600A | | | Units |
|--|--|---------|--------|-------|-------------------|--------|-------|--------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Input Offset Voltage (V _{OS}) | | | 0.4 | 5 | | 0.4 | 2 | mV |
| | Over Specified Temperature Range | | | | | | 5 | mV |
| V _{OS} Including Diodes | I _{ABC} = 5 μA | | 0.3 | 5 | | 0.3 | 2 | mV |
| | Diode Bias Current (I _D) = 500 μA | | 0.5 | 5 | | 0.5 | 2 | mV |
| Input Offset Change | 5 μA ≤ I _{ABC} ≤ 500 μA | | 0.1 | | | 0.1 | 3 | mV |
| Input Offset Current | | | 0.1 | 0.6 | | 0.1 | 0.6 | μA |
| Input Bias Current | | | 0.4 | 5 | | 0.4 | 5 | μA |
| Forward Transconductance (g _m) | Over Specified Temperature Range | | 1 | 8 | | 1 | 7 | μA |
| | | 6700 | 9600 | 13000 | 7700 | 9600 | 12000 | μmho |
| gm Tracking | Over specified Temp Range | 5400 | | | 4000 | | | μmho |
| Peak Output Current | RL = ∞, I _{ABC} = 5 μA | | 0.3 | | | 0.3 | | dB |
| Peak Output Voltage | RL = ∞, I _{ABC} = 500 μA | | 5 | | 3 | 5 | 7 | μA |
| | RL = ∞, Over Specified Temp Range | 350 | 500 | 650 | 350 | 500 | 650 | μA |
| Positive | RL = ∞, 5 μA ≤ I _{ABC} ≤ 500 μA | | | | | | | μA |
| | RL = ∞, 5 μA ≤ I _{ABC} ≤ 500 μA | + 12 | + 14.2 | | + 12 | + 14.2 | | V |
| Negative | RL = ∞, 5 μA ≤ I _{ABC} ≤ 500 μA | - 12 | - 14.4 | | - 12 | - 14.4 | | V |
| | I _{ABC} = 500 μA, Both Channels | | 2.6 | | | 2.6 | | mA |
| Supply Current | | | | | | | | |
| V _{OS} Sensitivity | Positive | | 20 | 150 | | 20 | 150 | μV/V |
| | Negative | | 20 | 150 | | 20 | 150 | μV/V |
| CMRR | | 80 | 110 | | 80 | 110 | | dB |
| Common Mode Range | | ± 12 | ± 13.5 | | ± 12 | ± 13.5 | | V |
| Crosstalk | Referred to Input (Note 5) 20 Hz < f < 20 KHz | | 100 | | | 100 | | dB |
| Diff. Input Current | I _{ABC} = 0, Input = ± 4 V | | 0.02 | 100 | | 0.02 | 10 | nA |
| Leakage Current | I _{ABC} = 0 (Refer To Test Circuit) | | 0.2 | 100 | | 0.2 | 5 | nA |
| Input Resistance | | 10 | 26 | | 10 | 26 | | KΩ |
| Open Loop Bandwidth | | | 2 | | | 2 | | MHz |
| Slew Rate | Unity Gain Compensated | | 50 | | | 50 | | V/μSec |
| Buff. Input Current | (Note 5) | | 0.4 | 5 | | 0.4 | 5 | μA |
| Peak Buffer Output Voltage | (Note 5) | 10 | | | 10 | | | V |

Note 1. For selections to a supply voltage above ± 22V, contact factory.

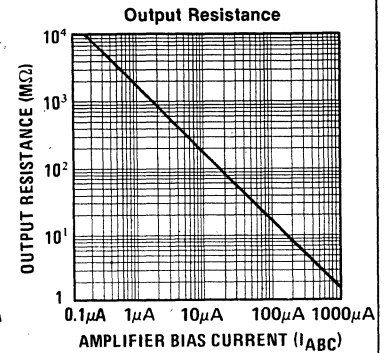
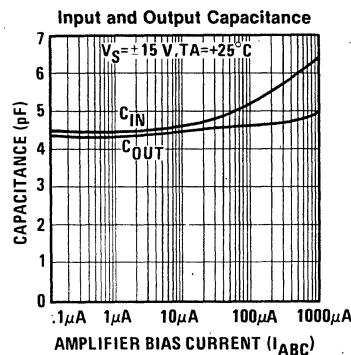
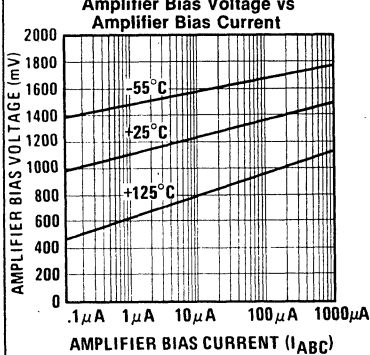
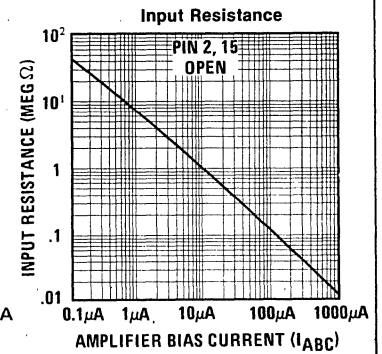
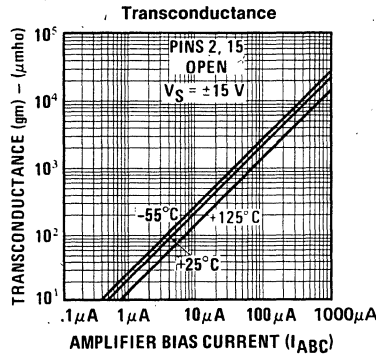
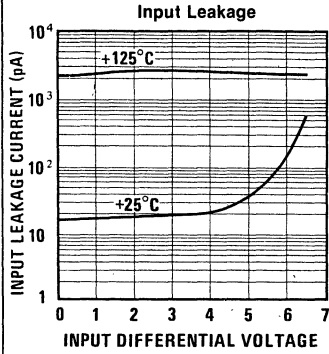
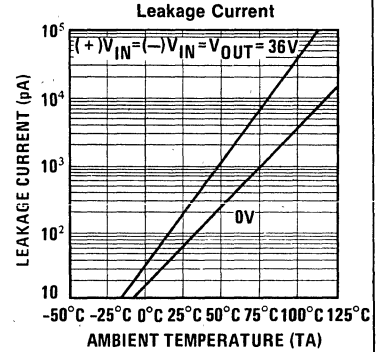
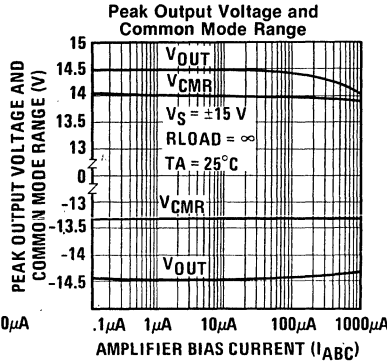
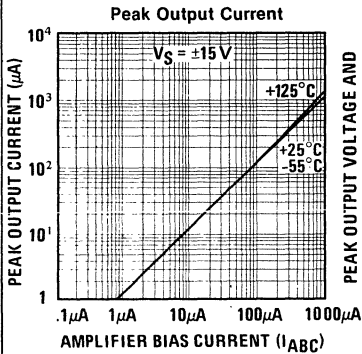
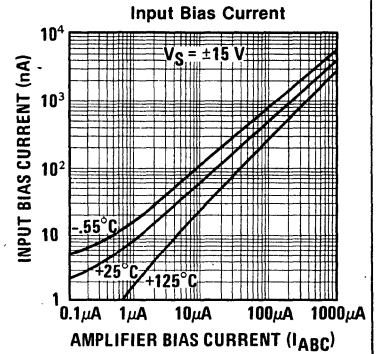
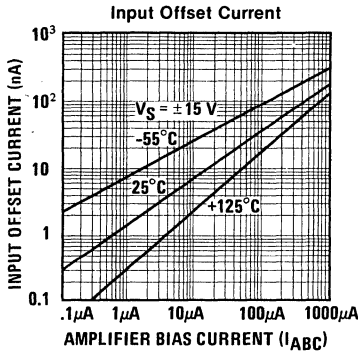
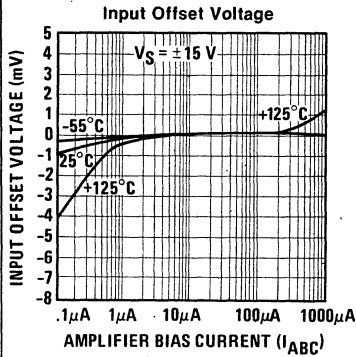
Note 2. For operating at high temperatures, the device must be derated based on a 150° C maximum junction temperature and a thermal resistance of 175° C/W which applies for the device soldered in a printed circuit board, operating in still air.

Note 3. Buffer output current should be limited so as to not exceed package dissipation.

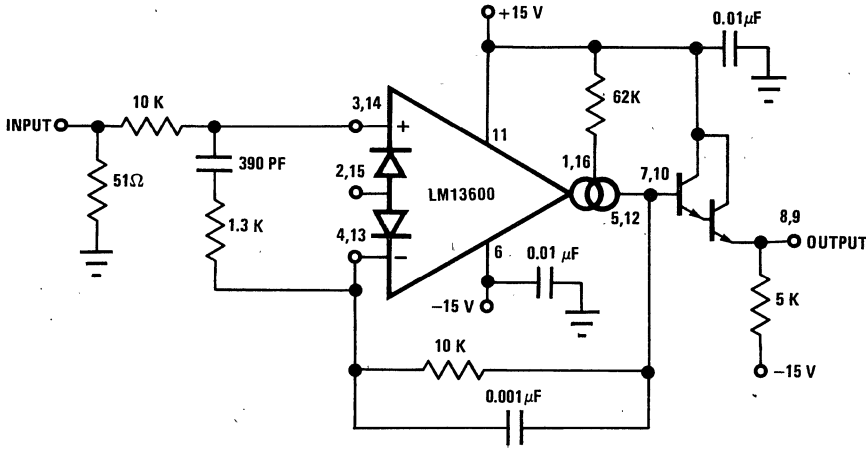
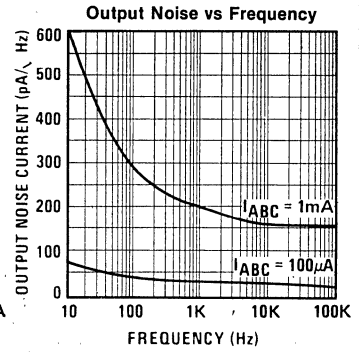
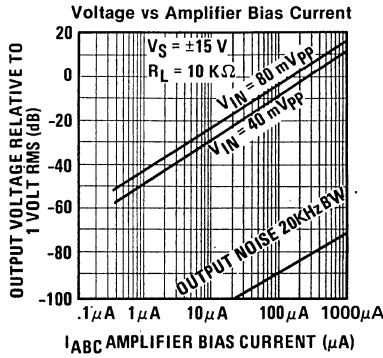
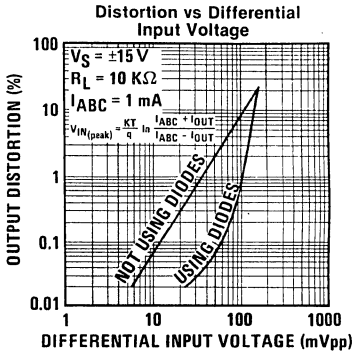
Note 4. These specifications apply for V_S = ± 15 V, T_A = 25° C, amplifier bias current (I_{ABC}) = 500 μA, pins 2 and 15 open unless otherwise specified. The inputs to the buffers are grounded and outputs are open.

Note 5. These specifications apply for V_S = ± 15V, I_{ABC} = 500 μA, R_{OUT} = 5 KΩ connected from the buffer output to -V_S and the input of the buffer is connected to the transconductance amplifier output.

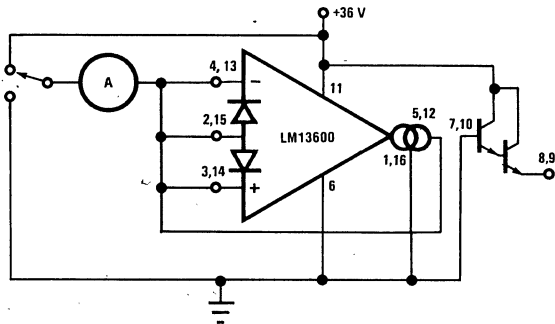
Typical Performance Characteristics



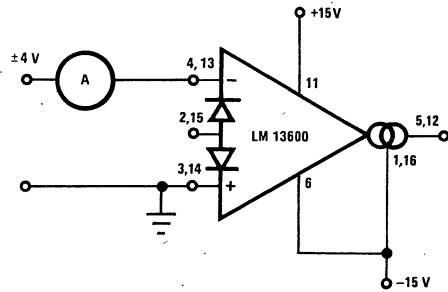
Typical Performance Characteristics (Cont'd)



UNITY GAIN FOLLOWER



LEAKAGE CURRENT TEST CIRCUIT



DIFFERENTIAL INPUT CURRENT TEST CIRCUIT

Circuit Description

The differential transistor pair Q4 and Q5 form a transconductance stage in that the ratio of their collector currents is defined by the differential input voltage according to the transfer function:

$$V_{IN} = \frac{KT}{q} \ln \frac{I_5}{I_4} \quad (1)$$

where V_{IN} is the differential input voltage, KT/q is approximately 26 mV at 25° C and I_5 and I_4 are the collector currents of transistors Q5 and Q4 respectively. With the exception of Q3 and Q13, all transistors and diodes are identical in size. Transistors Q1 and Q2 with Diode D1 form a current mirror which forces the sum of currents I_4 and I_5 to equal I_{ABC} :

$$I_4 + I_5 = I_{ABC} \quad (2)$$

where I_{ABC} is the amplifier bias current applied to the gain pin.

For small differential input voltages the ratio of I_4 and I_5 approaches unity and the Taylor series of the ln function can be approximated as:

$$\frac{KT}{q} \ln \frac{I_5}{I_4} \approx \frac{KT}{q} \frac{I_5 - I_4}{I_4} \quad (3)$$

$$I_4 \approx I_5 \approx \frac{I_{ABC}}{2}$$

$$V_{IN} \left[\frac{I_{ABC} q}{2KT} \right] = I_5 - I_4 \quad (4)$$

Collector currents I_4 and I_5 are not very useful by themselves and it is necessary to subtract one current from the other. The remaining transistors and diodes form three current mirrors that produce an output current equal to I_5 minus I_4 thus:

$$V_{IN} \left[\frac{I_{ABC} q}{2KT} \right] = I_{OUT} \quad (5)$$

The term in brackets is then the transconductance of the amplifier and is proportional to I_{ABC} .

Linearizing Diodes

For differential voltages greater than a few millivolts, Equation 3 becomes less valid and the transconductance becomes increasingly nonlinear. Figure 1 demonstrates how the internal diodes can linearize the transfer function of the amplifier. For convenience assume the diodes are biased with current sources and the input signal is in the form of current I_S . Since

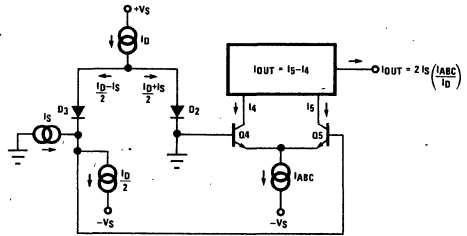


Figure 1. Linearizing Diodes

the sum of I_4 and I_5 is I_{ABC} and the difference is I_{OUT} , currents I_4 and I_5 can be written as follows:

$$I_4 = \frac{I_{ABC}}{2} - \frac{I_{OUT}}{2}, \quad I_5 = \frac{I_{ABC}}{2} + \frac{I_{OUT}}{2}$$

Since the diodes and the input transistors have identical geometries and are subject to similar voltages and temperatures, the following is true:

$$\frac{KT}{q} \ln \frac{I_D}{\frac{I_D}{2} + I_S} = \frac{KT}{q} \ln \frac{\frac{I_{ABC}}{2} + \frac{I_{OUT}}{2}}{\frac{I_{ABC}}{2} - \frac{I_{OUT}}{2}}$$

$$\therefore I_{OUT} = I_S \left(\frac{2I_{ABC}}{I_D} \right) \quad \text{for } |I_S| < \frac{I_D}{2} \quad (6)$$

Notice that in deriving Equation 6 no approximations have been made and there are no temperature dependent terms. The limitations are that the signal current not exceed $I_D/2$ and that the diodes be biased with currents. In practice, replacing the current sources with resistors will generate insignificant errors.

Controlled Impedance Buffers

The upper limit of transconductance is defined by the maximum value of I_{ABC} (2 mA). The lowest value of I_{ABC} for which the amplifier will function therefore determines the overall dynamic range. At very low values of I_{ABC} , a buffer which has very low input bias current is desirable. A FET follower satisfies the low input current requirement, but is some what nonlinear for large voltage swing. The controlled impedance buffer is a Darlington which modifies its input bias current to suit the need. For low values of I_{ABC} , the buffer's input current is minimal. At higher levels of I_{ABC} , transistor Q3 biases up Q12 with a current proportional to I_{ABC} for fast slew rate.

Applications/Voltage Controlled Amplifiers

Figure 2 shows how the linearizing diodes can be used in a voltage controlled amplifier. To understand the input biasing, it is best to consider the 13 K Ω resistor as a current source and use a Thevenin equivalent circuit as shown in Figure 3. This circuit is similar to Figure 1 and operates the same. The potentiometer in Figure 2 is adjusted to minimize the effects of the control signal at the output.

For optimum signal-to-noise performance, I_{ABC} should be as large as possible as shown by the Output Voltage vs. Amplifier Bias Current graph. Larger amplitudes of input signal also improve the S/N ratio. The linearizing diodes

help here by allowing larger input signals for the same output distortion as shown by the Distortion vs. Differential Input Voltage graph. S/N may be optimized by adjusting the magnitude of the input signal via R_{IN} (Figure 2) until the output distortion is below some desired level. The output voltage swing can then be set at any level by selecting R_L .

Although the noise contribution of the linearizing diodes is negligible relative to the contribution of the amplifier's internal transistors, I_D should be as large as possible. This minimizes the dynamic junction resistance of the diodes (r_e) and maximizes their linearizing action when balanced against R_{IN} . A value of 1 mA is recommended for I_D unless the specific application demands otherwise.

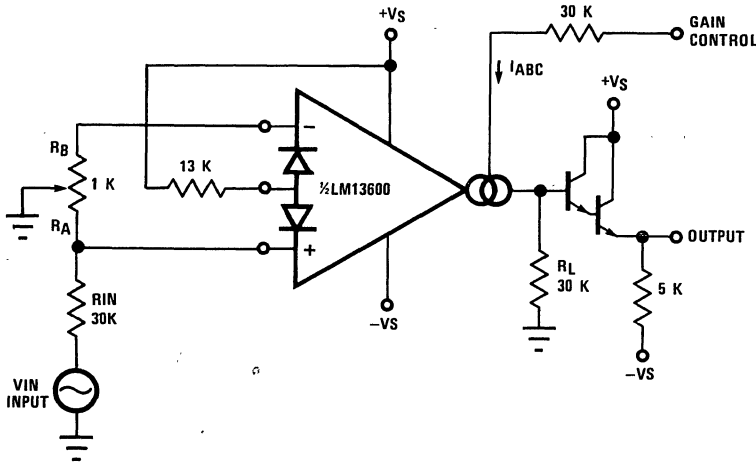


Figure 2 Voltage Controlled Amplifier

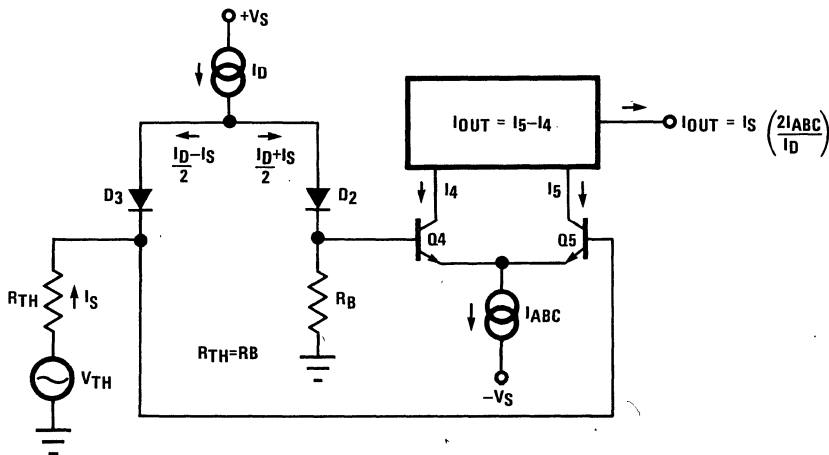


Figure 3. Equivalent VCA Input Circuit



Stereo Volume Control

The circuit of Figure 4 uses the excellent matching of the two LM13600 amplifiers to provide a Stereo Volume Control with a typical channel-to-channel gain tracking of 0.3 dB. R_p is provided to minimize the output offset voltage and may be replaced with two 510 Ω resistors in AC-coupled applications. For the component values given, amplifier gain is derived from Figure 2 as being:

$$\frac{V_O}{V_{IN}} = 940 \times I_{ABC}$$

If V_C is derived from a second signal source then the circuit becomes an amplitude modulator or two-quadrant multiplier as shown in Figure 5, where:

$$I_O = \frac{-2I_S}{I_D} (I_{ABC}) = \frac{-2I_S}{I_D} \frac{V_{IN2}}{R_C} - \frac{2I_S}{I_D} \frac{(V^- + 1.4V)}{R_C}$$

The constant term in the above equation may be cancelled by feeding $I_S \times I_D R_C / 2(V^- + 1.4V)$ into I_O . The circuit of Figure 6 adds R_M to provide

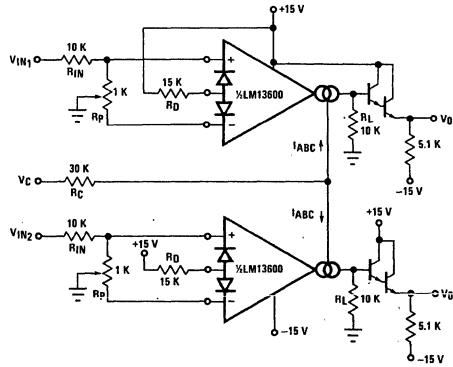


Figure 4. Stereo Volume Control

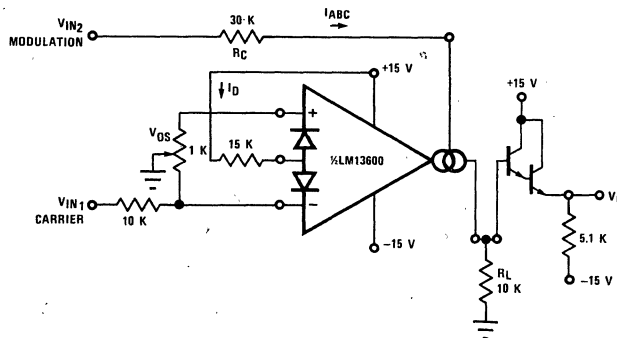


Figure 5. Amplitude Modulator

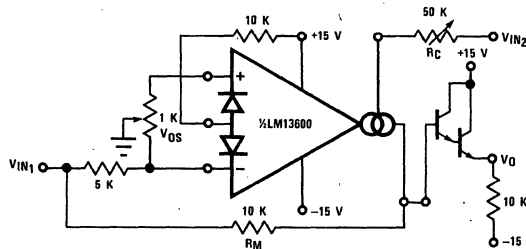


Figure 6. Four-Quadrant Multiplier

this current, resulting in a four-quadrant multiplier where R_C is trimmed such that $V_O = 0V$ for $V_{IN2} = 0V$. R_M also serves as the load resistor for I_O .

Noting that the gain of the LM13600 amplifier of Figure 3 may be controlled by varying the linearizing diode current I_D as well as by varying I_{ABC} , Figure 7 shows an AGC Amplifier using this approach. As V_O reaches a high enough amplitude ($3V_{BE}$) to turn on the Darlington transistors and the linearizing diodes, the increase in I_D reduces the amplifier gain so as to hold V_O at that level.

Voltage Controlled Resistors

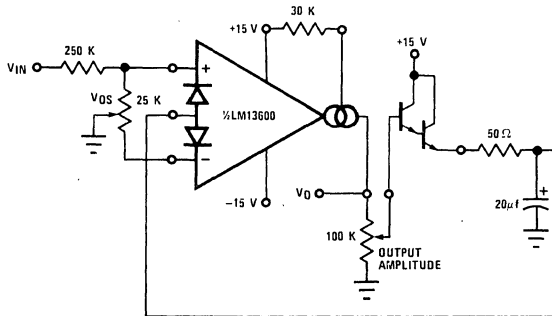
An Operational Transconductance Amplifier (OTA) may be used to implement a Voltage Controlled Resistor as shown in Figure 8. A signal

voltage applied at R_X generates a V_{IN} to the LM13600 which is then multiplied by the g_m of the amplifier to produce an output current, thus:

$$R_X = \frac{R + R_A}{g_m R_A}$$

where $g_m \approx 19.2I_{ABC}$ at $25^\circ C$. Note that the attenuation of V_O by R and R_A is necessary to maintain V_{IN} within the linear range of the LM13600 input.

Figure 9 shows a similar VCR where the linearizing diodes are added, essentially improving the noise performance of the resistor. A floating VCR



7. AGC Amplifier

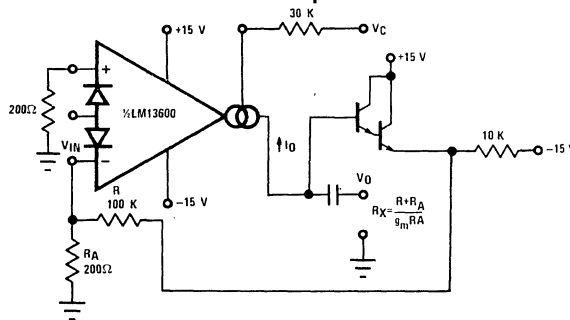


Figure 8. Voltage Controlled Resistor, Single-Ended

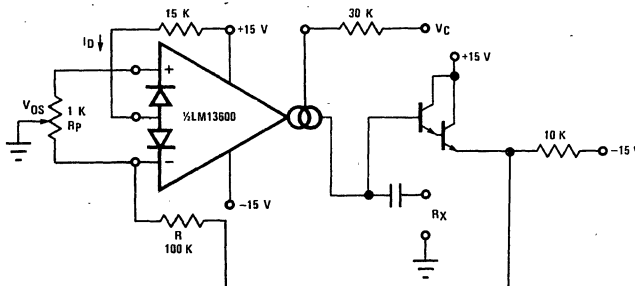


Figure 9. Voltage Controlled Resistor With Linearizing Diodes



is shown in Figure 10, where each "end" of the "resistor" may be at any voltage within the output voltage range of the LM13600.

Voltage Controlled Filters

OTA's are extremely useful for implementing voltage controlled filters, with the LM13600

having the advantage that the required buffers are included on the I.C. The VC Lo-Pass Filter of Figure 11 performs as a unity-gain buffer amplifier at frequencies below cut-off, with the cut-off frequency being the point at which X_C/g_m equals the closed-loop gain of (R/R_A) . At frequencies above cut-off the circuit provides a single RC roll-off (6 dB per octave) of the input signal amplitude with a -3 dB point defined by the given equation,

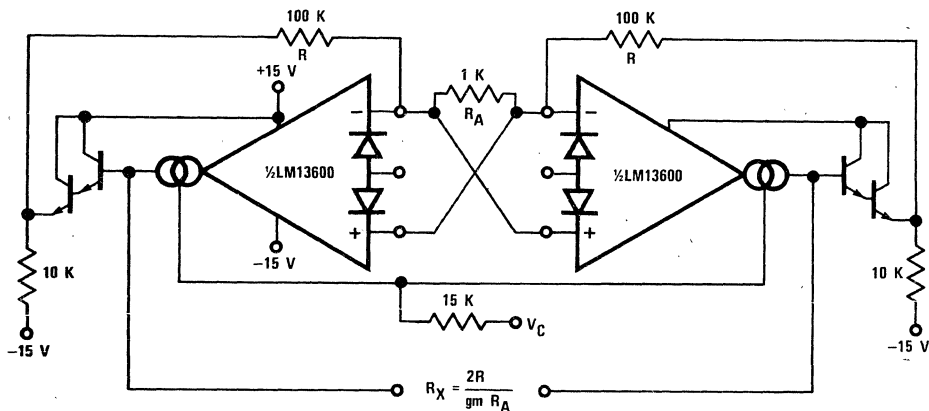


Figure 10. Floating Voltage Controlled Resistor

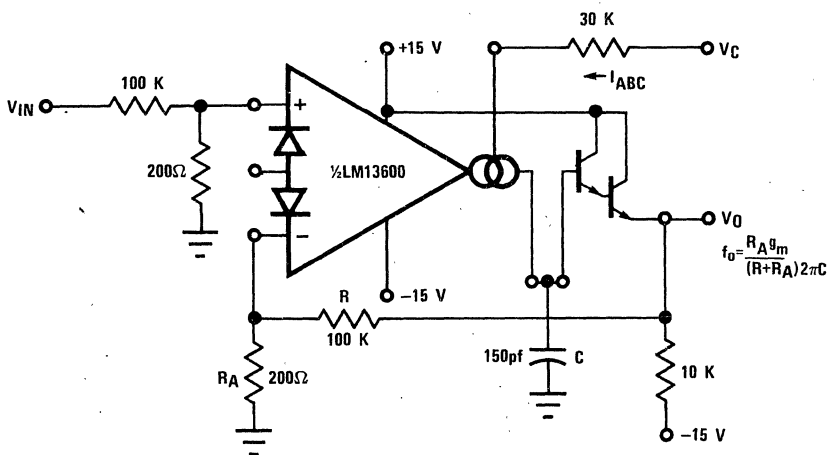


Figure 11. Voltage Controlled Low-Pass Filter

where g_m is again $19.2 \times I_{ABC}$ at room temperature. Figure 12 shows a VC High-Pass Filter which operates in much the same manner, providing a single RC roll-off below the defined cut-off frequency.

Additional amplifiers may be used to implement

higher order filters as demonstrated by the two-pole Butterworth Lo-Pass Filter of Figure 13 and the state variable filter of Figure 14. Due to the excellent g_m tracking of the two amplifiers and the varied bias of the buffer Darlingtons, these filters perform well over several decades of frequency.

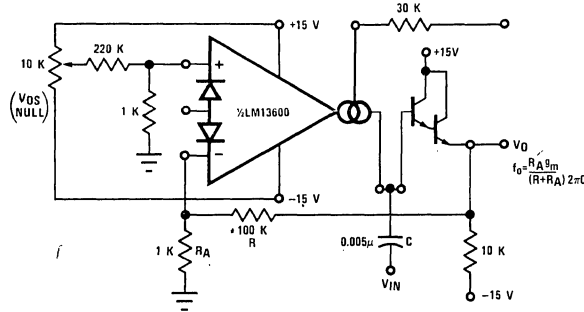


Figure 12. Voltage Controlled Hi-Pass Filter

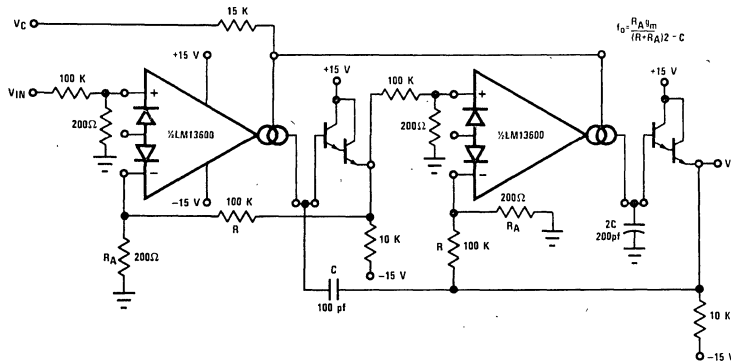


Figure 13. Voltage Controlled 2-pole Butterworth Lo-Pass Filter

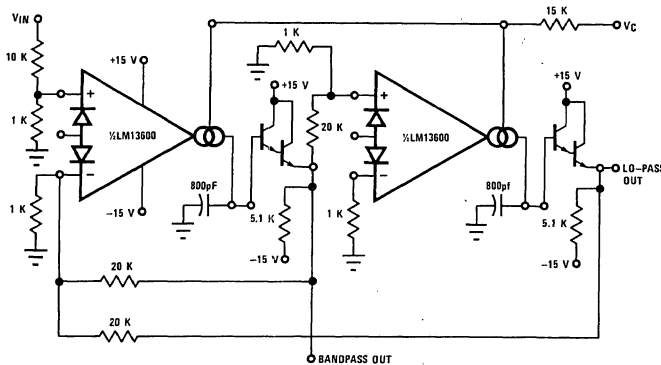


Figure 14. Voltage Controlled State Variable Filter

Voltage Controlled Oscillators

The classic Triangular/Square Wave VCO of Figure 15 is one of a variety of Voltage Controlled Oscillators which may be built utilizing the LM13600. With the component values shown, this oscillator provides signals from 200 kHz to below 2 Hz as I_C is varied from 1mA to 10nA. The output amplitudes are set by $I_A \times R_A$. Note that the peak differential input voltage must be less than 5 volts to prevent zenering the inputs.

A few modifications to this circuit produce the ramp/pulse VCO of Figure 16. When V_{O2} is high,

I_F is added to I_C to increase amplifier A1's bias current and thus to increase the charging rate of capacitor C. When V_{O2} is low, I_F goes to zero and the capacitor discharge current is set by I_C .

The VC Lo-Pass Filter of Figure 11 may be used to produce a high-quality sinusoidal VCO. The circuit of Figure 16 employs two LM13600 packages, with three of the amplifiers configured as lo-pass filters and the fourth as a limiter/inverter. The circuit oscillates at the frequency at which the loop phase-shift is 360° or 180° for the inverter and 60° per filter stage. This VCO operates from 5 Hz to 50 kHz with less than 1% THD.

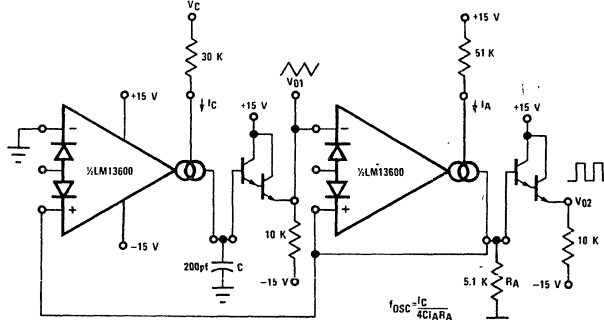


Figure 15. Triangular/Square-Wave VCO

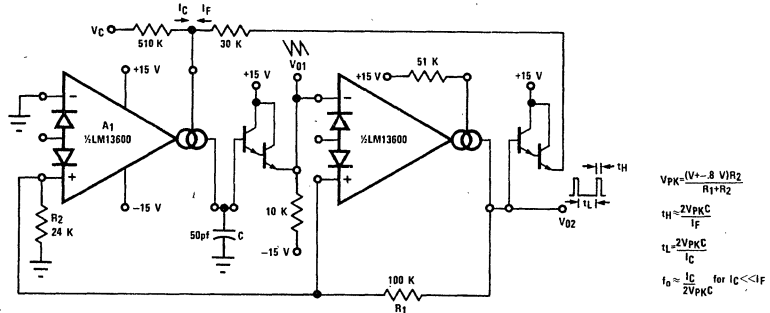


Figure 16. Ramp/Pulse VCO

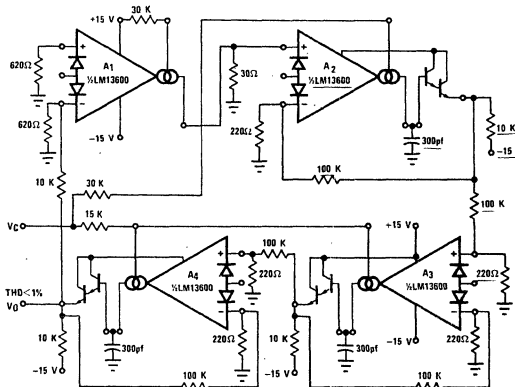


Figure 17. Sinusoidal VCO

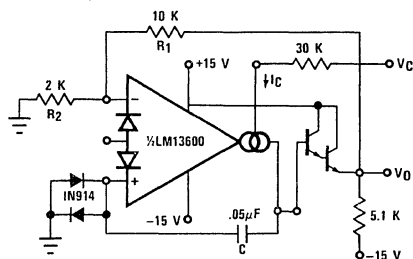


Figure 18. Single Amplifier VCO

Figure 18 shows how to build a VCO using one amplifier when the other amplifier is needed for another function.

Additional Applications

Figure 19 presents an interesting one-shot which draws no power supply current until it is triggered. A positive-going trigger pulse of at least 2V amplitude turns on the amplifier through R_B and pulls the non-inverting input high. The amplifier regenerates and latches its output high until capacitor C charges to the voltage level on the non-inverting input. The output then switches low, turning off the amplifier and discharging the capacitor. The capacitor discharge rate is speeded up by shorting the diode bias pin to the inverting input so that an additional discharge current flows through D_1 when the amplifier output switches low. A special feature of this timer is that the other amplifier, when biased from V_O , can perform another function and draw zero stand-by power as well.

The operation of the multiplexer of Figure 20 is very straightforward. When A1 is turned on it holds V_O equal to V_{IN1} and when A2 is supplied with bias current then it controls V_O . C_C and R_C serve to stabilize the unity-gain

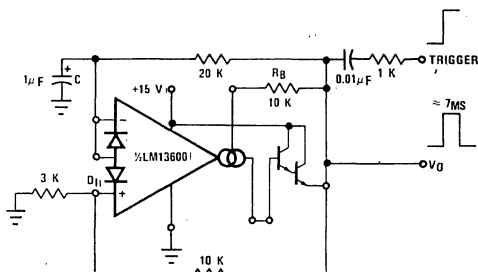


Figure 19. Zero Stand-by Power Timer

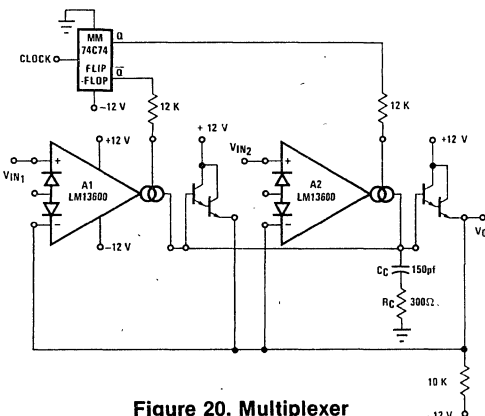


Figure 20. Multiplexer

configuration of amplifiers A1 and A2. The maximum clock rate is limited to about 200 KHz by the LM13600 slew rate into 150 pF when the ($V_{IN1}-V_{IN2}$) differential is at its maximum allowable value of 5 volts.

The Phase-Locked Loop of Figure 21 uses the four-quadrant multiplier of Figure 6 and the VCO of Figure 18 to produce a PLL with a $\pm 5\%$ hold-in range and an input sensitivity of about 300 mV.

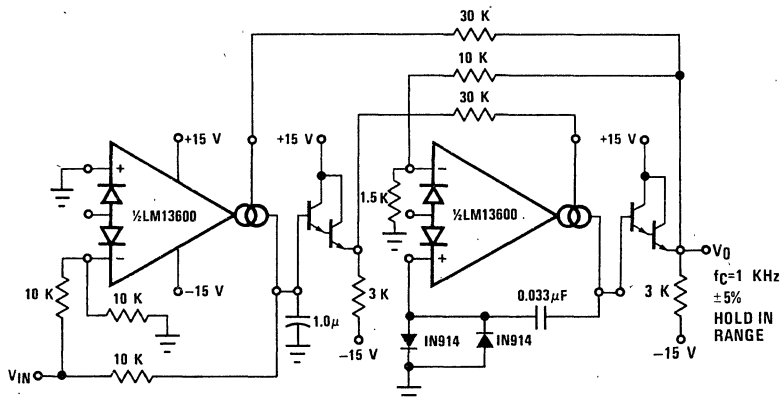


Figure 21. Phase Lock Loop

The Schmitt Trigger of Figure 22 uses the amplifier output current into R to set the hysteresis of the comparator; thus $V_H = 2 \times R \times$

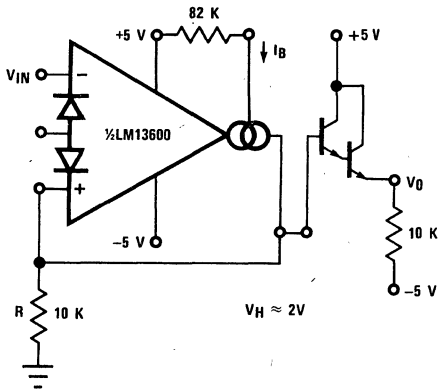


Figure 22. Schmitt Trigger

I_B . Varying I_B will produce a Schmitt Trigger with variable hysteresis.

Figure 23 shows a Tachometer or Frequency-to-Voltage converter. Whenever A1 is toggled by a positive-going input, an amount of charge equal to $(V_H - V_L) C_T$ is sourced into C_T and R_T . This once per cycle charge is then balanced by the current of V_O/R_T . The maximum F_{IN} is limited by the amount of time required to charge C_T from V_L to V_H with a current of I_B , where V_L and V_H represent the maximum low and maximum high output voltage swing of the LM13600. D1 is added to provide a discharge path for C_T when A1 switches low.

The Peak Detector of Figure 24 uses A2 to turn on A1 whenever V_{IN} becomes more positive than V_O . A1 then charges storage capacitor C to hold V_O equal to $V_{IN PK}$. One precaution to observe when using this circuit: the Darlington transistor used must be on the same side of the package as A2 since the A1 Darlington will be turned on and off with A1. Pulling the output of A2 low through D1 serves to turn off A1 so that V_O remains constant.

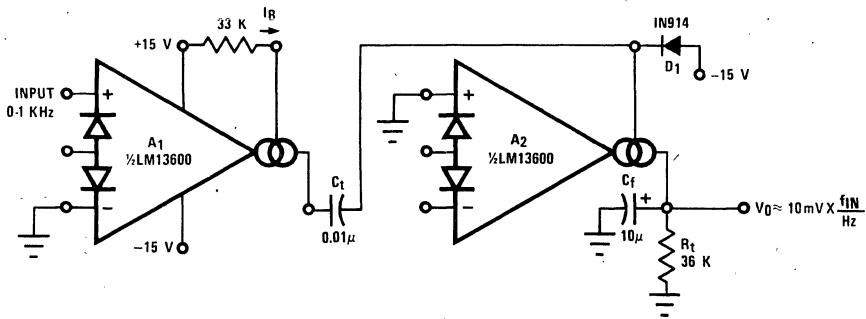


Figure 23. Tachometer

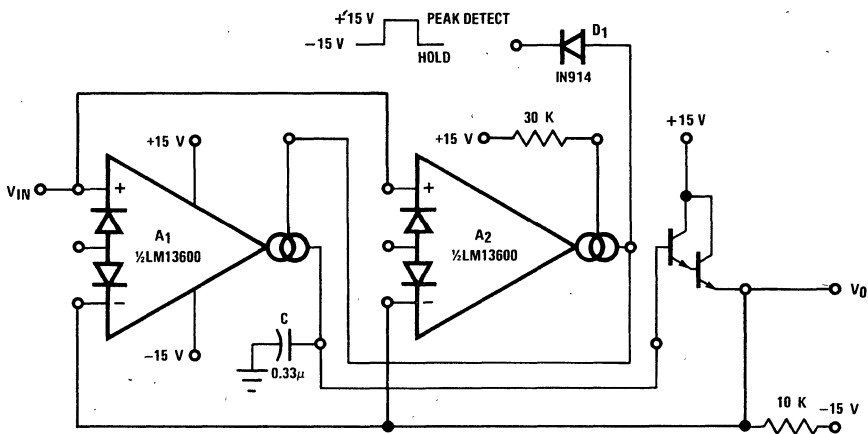


Figure 24. Peak Detector and Hold Circuit

The Sample-Hold circuit of Figure 25 also requires that the Darlington buffer used be from the other (A2) half of the package and that the corresponding amplifier be biased on continuously.

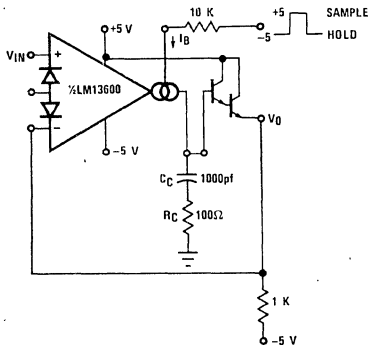


Figure 25. Sample-Hold Circuit

The Ramp-and-Hold of Figure 26 sources I_B into capacitor C whenever the input to A1 is brought high, giving a ramp-rate of about IV/ms for the component values shown.

The true RMS converter of Figure 27 is essentially an automatic gain control amplifier which adjusts its gain such that the AC power at the output of amplifier A1 is constant. The output power of amplifier A1 is monitored by squaring amplifier A2 and the average compared to a reference voltage with amplifier A3. The output of A3 provides bias current to the diodes of A1 to attenuate the input signal. Because the output power of A1 is held constant, the RMS value is constant and the attenuation is directly proportional to the RMS value of the input voltage. The attenuation is also proportional to the diode bias current. Amplifier A4 adjusts the ratio of currents through the diodes to be equal and therefore the voltage at the output of A4 is proportional to the RMS value of the input voltage. The calibration potentiometer is set such that V_0 reads directly in RMS volts.

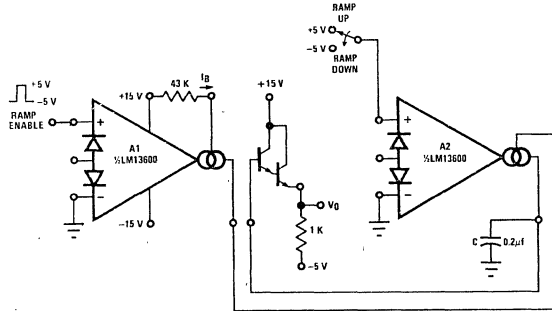


Figure 26. Ramp and Hold

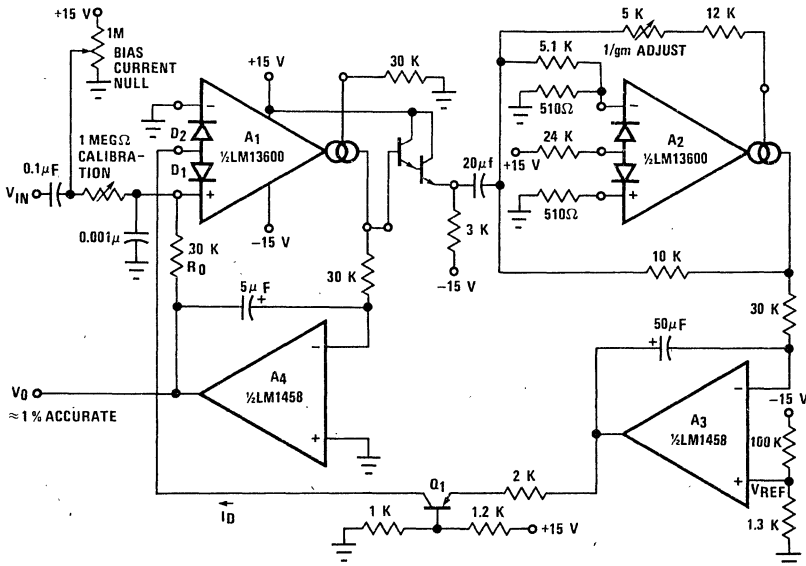


Figure 27. True RMS Converter

The circuit of Figure 28 is a voltage reference of variable Temperature Coefficient. The 100 K potentiometer adjusts the output voltage which has a positive TC above 1.2 volts, zero TC at about 1.2 volts and negative TC below 1.2 volts. This is accomplished by balancing the TC of the A2 transfer function against the complementary TC of D1

The log amplifier of Figure 29 responds to the ratio of current thru buffer transistors Q3 and Q4. Zero temperature dependence for V_{OUT} is ensured in that the TC of the A2 transfer function is equal and opposite to the TC of the logging transistors Q3 and Q4.

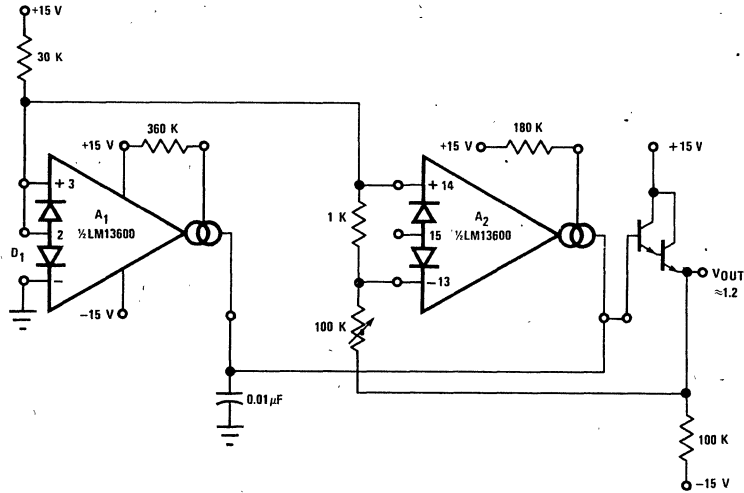


Figure 28. Delta-VBE Reference

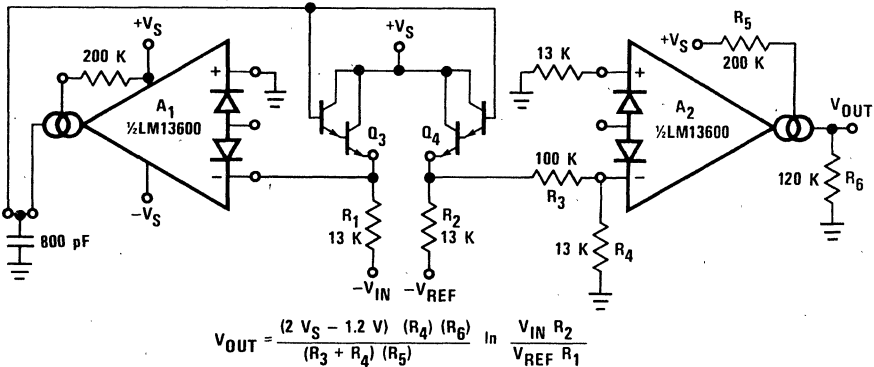


Figure 29. Log Amplifier

The wide dynamic range of the LM13600 allows easy control of the output pulse width in the Pulse Width Modulator of Figure 30.

For generating I_{ABC} over a range of 4 to 6 decades of current, the system of Figure 31 provides a logarithmic current out for a linear voltage in.

Since the closed-loop configuration ensures that the input to A2 is held equal to O_V , the output current of A1 is equal to $I_3 = -V_C/R_C$.

The differential voltage between Q1 and Q2 is attenuated by the R_1, R_2 network so that A1 may be assumed to be operating within its linear range. From equation (5), the input voltage to A1 is:

$$V_{IN1} = \frac{-2KT I_3}{q I_2} = \frac{2KT V_C}{q I_2 R_C}$$

The voltage on the base of Q1 is then

$$V_{B1} = \frac{(R_1 + R_2) V_{IN1}}{R_1}$$

The ratio of the Q1 to Q2 collector currents is defined by:

$$V_{B1} = \frac{KT}{q} \ln \frac{I_{C2}}{I_{C1}} \approx \frac{KT}{q} \ln \frac{I_{ABC}}{I_1}$$

Combining and solving for I_{ABC} yields:

$$I_{ABC} = I_{1e} \frac{2(R_1 + R_2) V_C}{R_1 I_2 R_C}$$

This logarithmic current can be used to bias the circuit of Figure 4 to provide temperature independent stereo attenuation characteristic.

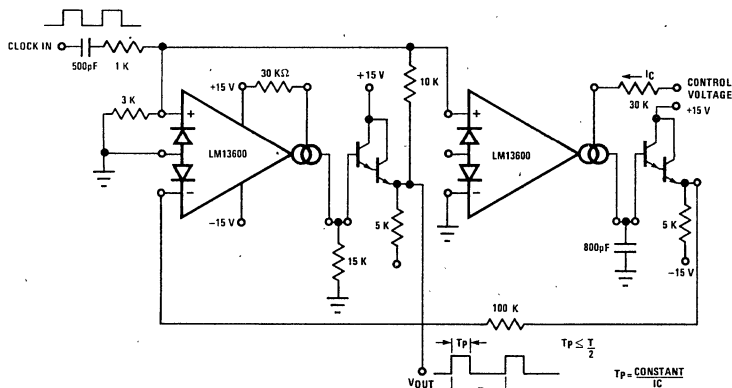


Figure 30. Pulse Width Modulator

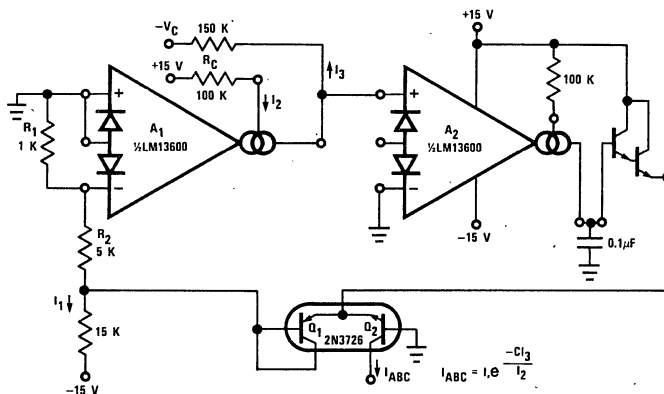


Figure 31. Logarithmic Current Source







Section 10
**Audio, Radio
and TV Circuits**





Section Contents

| | |
|--|--------|
| Audio Selection Guide..... | 10-iv |
| Definition of Terms..... | 1-viii |
| Audio Radio Circuits | |
| LM377 Dual 2 Watt Audio Amplifier..... | 10-1 |
| LM378 Dual 4 Watt Audio Amplifier..... | 10-6 |
| LM379 Dual 6 Watt Audio Amplifier..... | 10-10 |
| LM380 Audio Power Amplifier..... | 10-14 |
| LM381/LM381A Low Noise Dual Preamplifier..... | 10-18 |
| LM382 Low Noise Dual Preamplifier..... | 10-21 |
| LM383/LM383A 8 Watt Audio Power Amplifier..... | 10-24 |
| LM384 5 Watt Audio Power Amplifier..... | 10-28 |
| LM386 Low Voltage Audio Power Amplifier..... | 10-32 |
| LM387/LM387A Low Noise Dual Preamplifier..... | 10-36 |
| LM388 1.5 Watt Audio Power Amplifier..... | 10-39 |
| LM389 Low Voltage Audio Power Amplifier with NPN Transistor Array..... | 10-44 |
| LM390 1 Watt Battery Operated Audio Power Amplifier..... | 10-51 |
| LM391 Audio Power Driver..... | 10-56 |
| LM565/LM565C Phase Locked Loop..... | 9-38 |
| LM567/LM567C Tone Decoder..... | 9-46 |
| LM733/LM733C Differential Video Amplifier..... | 3-198 |
| LM1011, LM1011A Dolby B-Type Noise Reduction Processor..... | 10-67 |
| LM1019N Digital Tuning Station Detector..... | 10-74 |
| LM1303 Stereo Preamplifier..... | 10-77 |
| LM1310 Phase Locked Loop FM Stereo Demodulator..... | 10-79 |
| LM1596/LM1496 Balanced Modulator-Demodulator..... | 10-84 |
| LM1800 Phase Locked Loop FM Stereo Demodulator..... | 10-88 |
| LM1818 Electronically Switched Audio Tape System..... | 10-90 |
| LM1870 Stereo Demodulator with Blend..... | 10-102 |
| LM1877 Dual Power Audio Amplifier..... | 10-108 |
| LM1896/LM2896 Dual Power Audio Amplifier..... | 10-134 |
| LM2000 Low Voltage Audio Driver..... | 10-141 |
| LM2001 Low Voltage Audio Driver..... | 10-147 |
| LM2002/LM2002A 8 Watt Audio Power Amplifier..... | 10-152 |
| LM2877 Dual 4-Watt Power Audio Amplifier..... | 9-73 |
| LM3011 Wide Band Amplifier..... | 10-160 |
| LM3075 FM Detector/Limiter and Audio Preamplifier..... | 10-164 |
| LM3080/LM3080A Operational Transconductance Amplifier..... | 9-92 |
| LM3089 FM Receiver IF System..... | 10-166 |
| LM3189 FM Receiver IF System..... | 10-170 |
| LM3820 AM Radio System..... | 10-176 |
| LM3914 Dot/Bar Display Driver..... | 9-107 |
| LM3915 Dot/Bar Display Driver..... | 9-120 |
| LM4500A High Fidelity FM Stereo Blend Demodulator..... | 10-180 |
| LM13600/LM13600A/LM11600A Dual Operational Transconductance Amplifiers With Linearizing Diodes and Buffers..... | 9-136 |
| TBA120S IF Amplifier and Detector..... | 10-181 |
| TBA120U/TBA120T IF Amplifier and Detector..... | 10-184 |

Section Contents (Continued)

TV Circuits

| | |
|--|--------|
| LM1017 4-Bit Binary 7-Segment Decoder/Driver..... | 10-70 |
| LM1019N Digital Tuning Station Detector..... | 10-74 |
| LM1303 Stereo Preamplifier..... | 10-77 |
| LM1391 Phase-Locked Loop Block..... | 10-81 |
| LM1828, LM1848 Color Television Chroma Demodulator..... | 10-99 |
| LM1880 No-Holds Vertical/Horizontal..... | 10-113 |
| LM1886 TV Video Matrix D to A..... | 10-120 |
| LM1889 TV Video Modulator..... | 10-125 |
| LM2808 Monolithic TV Sound System..... | 10-156 |
| LM3064 Television Automatic Fine Tuning..... | 10-162 |
| TBA440C Monolithic Video IF Amplifier..... | 10-188 |
| TBA510 Chrominance Combination..... | 10-190 |
| TBA530 RGB Matrix Preamplifier..... | 10-194 |
| TBA540 Reference Combination..... | 10-197 |
| TBA560C Luminance and Chrominance Control Combination..... | 10-201 |
| TBA920/TBA920S Line Oscillator Combination..... | 10-205 |
| TBA950-2 Television Signal Processing Circuit..... | 10-208 |
| TBA970 Television Video Amplifier..... | 10-212 |
| TBA990 Color Demodulator..... | 10-215 |
| TDA440 Video IF Amplifier..... | 10-217 |
| TDA2522 Color Demodulation Combination..... | 10-221 |
| TDA2530, TDA2531 R-G-B Matrix Preamplifiers with Clamps..... | 10-223 |
| TDA2560 Luminance and Chrominance Control Combination..... | 10-226 |
| TDA2590 Line Oscillator Combination..... | 10-229 |

TABLE I. DUAL AUDIO AMPLIFIER TYPICAL P_o @ 10% THD

| Supply | Device | | | | Load Impedance | |
|--------|--------|-------|-------|-------|---------------------|-------------|
| | | | | | 8 Ω | 16 Ω |
| 8 | LM1877 | | | | 0.5W | 0.25W |
| 12 | | LM377 | LM378 | LM379 | 1.2W | 0.75W |
| 16 | | | | | 2.2W | 1.5W |
| 18 | | | | | 3.0W | 1.8W |
| 20 | | | | | 3.8W | 2.4W |
| 22 | | | | | 4.6W | 2.8W |
| 24 | | | | | 5.4W ⁽¹⁾ | 3.6W |
| | | | | | 1.5W ⁽²⁾ | 4.2W |
| 26 | | | | | 6.0W | |
| 28 | | | | | 7.0W | 5.0W |
| 30 | | | | | | 5.5W |

Note 1: LM379.

Note 2: LM378 (thermal limit).

KEY TECHNICAL SPECIFICATIONS

| NSC Device Type | Features | Applications | Order Number | P_o (Minimum) | | | Supply Voltage (V_s) | Quiescent Current (I_Q) | Channel Separation $f = 1$ kHz (output ref) | Equiv Input Noise (e_n) | Open Loop Gain | Output Voltage Swing | Slew Rate $V/\mu s$ |
|-----------------|------------------------------|-----------------------------|--------------|-----------------|-------------|-------|--------------------------|-----------------------------|---|-----------------------------|----------------|----------------------|---------------------|
| | | | | V_s | R_L | P_o | | | | | | | |
| LM1877 | Adjustable gain 50-250 | Stereo phonograph | LM1877N-2' | 14V | 8 Ω | 1.0W | 6-20V | 25 mA | 70 dB | 2.5 μ Vrms | 90 dB | 8V | 2 |
| | High PSRR - 68 dB | Stereo tape recorders | LM1877N-6' | 16V | 8 Ω | 2.0W | 6-26V | 25 mA | 70 dB | 2.5 μ Vrms | 90 dB | 10V | 2 |
| | Current limiting | Bridge output stages | LM1877N-8' | 18V | 8 Ω | 3.5W | 6-26V | 25 mA | 70 dB | 2.5 μ Vrms | 90 dB | 12V | 2 |
| | Thermal shutdown | Receivers | LM1877N-10' | 20V | 8 Ω | 4.0W | 6-26V | 25 mA | 70 dB | 2.5 μ Vrms | 90 dB | 14V | 2 |
| | Low noise | | | | | | | | | | | | |
| LM378 | A_{VO} typical 90 dB | AM/FM stereo receivers | LM378N | 24V | 8 Ω | 4.0W | 10-35V | 15 mA | 70 dB | 3.0 μ Vrms | 90 dB | 16V | 14 |
| | 3 M Ω input impedance | Movie projectors | | | | | | | | | | | |
| LM379 | Current limiting | Tape recorders | | | | | | | | | | | |
| | Thermal shutdown | Multi-channel audio systems | LM378N | 30V | 16 Ω | 4.0W | 10-35V | 15 mA | 70 dB | 3.0 μ Vrms | 90 dB | 16V | 14 |
| LM379 | Self centering bias | Multi-channel audio | | | | | | | | | | | |
| | Current limiting | Tape recorders/players | LM379S | 28V | 8 Ω | 6.0W | 10-35V | 15 mA | 70 dB | 3.0 μ Vrms | 90 dB | 16V | 14 |
| | Thermal shutdown | AM/FM radios | | | | | | | | | | | |
| | Internal stabilization | Movie projectors | | | | | | | | | | | |

Note 1: Refer to NSC data sheet LM1877 for additional standard selections.

Note 2: For operation at ambient temperatures greater than 25°C the IC must be derated based on a maximum 150°C junction temperature using a thermal resistance obtained from the device data sheet.

Note 3: Output protection included on all devices.

KEY TECHNICAL SPECIFICATIONS

**TABLE II.
CLIC MONO-AUDIO AMPLIFIER**

| Supply | Device | Load Impedance | | | |
|-----------|----------------|----------------|------------|------------|-------------|
| | | 2 Ω | 4 Ω | 8 Ω | 16 Ω |
| 3V | LM2001 | 400 mW | 250 mW | | |
| 6V | LM383 | 1.4W | 800 mW | 440 mW | 240 mW |
| | LM386, LM389 | | 340 mW | 320 mW | 180 mW |
| | LM388 | | 900 mW | 600 mW | 300 mW |
| | LM390 | | 950 mW | 650 mW | 325 mW |
| | LM2000 | | 2.0W | 1.0W | |
| 9V | LM383 | 3.5W | 2.1W | 1.2W | 630 mW |
| | LM386, LM389 | | 380 mW | 780 mW | 500 mW |
| | LM388 | | 1.8W | 1.3W | 650 mW |
| | LM390 | | 2.0W | 1.4W | 700 mW |
| | LM2000 | | 4.0W | 2.2W | |
| 12V | LM380 | 6.4W | 2.4W | 1.5W | 500 mW |
| | LM383 | | 4.0W | 2.3W | 1.2W |
| | LM386A, LM389 | | | 820 mW | 950 mW |
| | LM388 | | 2.4W | 2.2W | 1.3W |
| | | | | | |
| 14V | LM380 | 8.9W | 3.3W | 2.3W | 1.0W |
| | LM383 | | 5.6W | 3.7W | 1.7W |
| | LM386A | | | | 1.3W |
| | LM388A | | 3.0W | 3.0W | 0.5W |
| 16V | LM380 | | | 3.0W | 1.6W |
| | LM386A | | | | 1.6W |
| | LM388A | 3.6W | 3.8W | 1.9W | |
| 18V | LM380 | | | 4.0W | 2.2W |
| | LM383 | | 9.6W | 5.5W | 2.9W |
| | LM384 | | 4.2W | 4.0W | 2.2W |
| 22V | LM384 | | 3.5W | 5.7W | 3.5W |
| $\pm 22V$ | LM391 (Note 1) | | 30W | 20W | |
| $\pm 30V$ | LM391 (Note 1) | | 60W | 40W | |

Note 1: THD < 0.25%.

| NSC Device Type | Features | Applications | Order Number | P _o (Minimum) @ 10% THD | | | Supply Voltage (V _{CC}) | Gain (A _v)/V/V | Quiescent Current I _Q (typ) |
|----------------------|---------------------------------------|--------------------------------|--------------|------------------------------------|-----------------|----------------|-----------------------------------|----------------------------|--|
| | | | | P _o | V _{CC} | R _L | | | |
| LM386 | Battery operation | AM/FM radio amplifier | LM386N-1 | 250 mW | 6V | 8 Ω | 4V-12V | 20-200 | 4 mA |
| | Low quiescent current | Cassette amplifier | LM386N-3 | 500 mW | 9V | 8 Ω | 4V-12V | 20-200 | 4.5 mA |
| | Ground ref input | Phono cartridge amp | LM386N-4 | 700 mW | 16V | 32 Ω | 5V-18V | 20-200 | 7 mA |
| | 8 pin miniDIP | Walkie-talkie | | | | | | | |
| LM389 | Battery operation | Portable tape recorders | LM389N | 250 mW | 6V | 8 Ω | 4V-12V | 20-200 | 12 mA |
| | Low distortion | Phono cartridge amp | | | | | | | |
| | Includes NPN (3) transistor array | Intercoms | | | | | | | |
| | Freq (DC to 100 MHz) | AM/FM radio Walkie-talkie | | | | | | | |
| LM388 | Low voltage operation | AM/FM radio amplifiers | LM388N-1 | 1500 mW | 12V | 8 Ω | 4V-12V | 20-200 | 8 mA |
| | Variable voltage gain | Portable tape recorders | LM388N-2 | 800 mW | 6V | 4 Ω | 4V-12V | 20-200 | 5 mA |
| | Excellent supply rejection | Squelch circuits | LM388N-3 | 2500 mW | 16V | 8 Ω | 5V-18V | 20-200 | 15 mA |
| | 14-pin DIP | for FM scanners | | | | | | | |
| LM380 | Ground referenced inputs | Phono amplifiers | | | | | | | |
| | Voltage gain fixed at 50 | Cassette amplifiers | LM380N | 2500 mW | 18V | 8 Ω | 8V-22V | 50 | 10 mA |
| | High input impedance | | | | | | | | |
| | Short circuit current (1.3A) | | | | | | | | |
| LM390 | Ground referenced inputs | Bridge amplifiers | | | | | | | |
| | Automatic bias at 1/2 V _{SS} | Intercom | | | | | | | |
| | Bias current 250 nA (typ) | Portable tape amplifiers | LM390N | 800 mW | 6V | 4 Ω | 3.5V-9V | 20-200 | 10 mA |
| LM384 | Ground referenced inputs | AM/FM radio | LM384N | 5000 mW | 22V | 8 Ω | 12V-26V | 50 | 8.5 mA |
| | Fixed gain (A _v = 50) | Sound projector systems | | | | | | | |
| | Thermal shut-down | Tape cassettes | | | | | | | |
| | High input impedance | 8-track tape systems | | | | | | | |
| LM383 | Short circuit protection | Automotive audio amp | LM383T | 4800 mW | 14.4V | 4 Ω | 5V-20V | 50-500 | 45 mA |
| | Peak current (3.5A) | CB radio | | 7000 mW | 14.4V | 2 Ω | 5V-20V | | |
| | Programmable gain | Bridge amplifiers | | | | | | | |
| | Large output swing | | | | | | | | |
| 5-pin TO-220 package | | | | | | | | | |
| LM391 | High V _{CC} (60V-80V) | Hi-fidelity audio amplifiers | LM391N-80 | 40W ¹ | $\pm 31V$ | 8 Ω | $\pm 40V$ | 20-200 | — |
| | Low THD $\leq 0.01\%$ | | | 60W ¹ | $\pm 27V$ | 4 Ω | $\pm 40V$ | | |
| | P _o = 40W | Hi-fidelity receivers | | | | | | | |
| LM2001 | Battery operation min 1.8V | Battery operated audio systems | LM2001N | 500 mW | 6V | 8 Ω | 1.8V-6V | — | — |
| | Adjustable gain/bandwidth | | | | | | | | |
| | Stable A-B bias | | | | | | | | |

Note 1: P_o rated at specified conditions except THD 0.10%.

TABLE III. Dual Preamplifier Characteristics

| PARAMETER | CONDITIONS | LM381N (14-PIN DIP) | | | LM382N (14-PIN DIP) | | | LM387N (8-PIN DIP) | | | LM1303N (14-PIN DIP) | | | UNITS |
|-------------------------------|--------------------------------------|------------------------|-----------|----------|------------------------|-----------|-----|-----------------------|-----------|--------|-------------------------|--------|-----|------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage | | 9 | | 40 | 9 | | 40 | 9 | | 40 | ±4.5 | | ±15 | Vrms |
| Quiescent Supply Current | | | 10 | | | 10 | 16 | | 10 | | | | 15 | mA |
| Input Resistance (Open Loop) | | | | | | | | | | | | | | |
| Positive Input | | | 100k | | | 100k | | 50k | 100k | | | 25k | | Ω |
| Negative Input | | | 200k | | | 200k | | | 200k | | | 25k | | Ω |
| Open Loop Gain | | | 104 | | | 100k | | | 104 | | 76 | 80 | | dBV |
| Output Voltage Swing | $R_L = 10\text{ k}\Omega$ | | $V_S - 2$ | | | $V_S - 2$ | | | $V_S - 2$ | | 11.3 | 15.6 | | Vp-p |
| Output Current | | | | | | | | | | | | | | |
| Source | | | 8(2) | | | 8(2) | | | 8(2) | | 0.6 | 0.8 | | mA |
| Sink | | | 2 | | | 2 | | | 2 | | 0.6 | 0.8 | | mA |
| Output Resistance (Open Loop) | | | 150 | | | 150 | | | 150 | | | 4k | | Ω |
| Slew Rate | ($A_V = 40\text{ dB}$) | | 4.7 | | | 4.7 | | | 4.7 | | | 5.0(7) | | V/ μ s |
| Power Bandwidth | 20 Vp-p ($V_S = 24\text{V}$) | | 75 | | | 75 | | | 75 | | | 100 | | kHz |
| | 11.3 Vp-p ($V_S = \pm 13\text{V}$) | | | | | | | | | | | | | kHz |
| Unity Gain Bandwidth | | | 15 | | | 15 | | | 15 | | | 20 | | MHz |
| Input Voltage | | | | | | | | | | | | | | |
| Positive Input | | | | 300 | | | 300 | | | 300 | | | | mVrms |
| Either Input | | | | | | | | | | | | | ±5 | V |
| Supply Rejection Ratio | Input Referred, 1 kHz | | 120 | | | 120 | | | 110 | | | | | dBV |
| Channel Separation | $f = 1\text{ kHz}$ | | 60 | | 40 | 60 | | 40 | 60 | | 60 | 70 | | dBV |
| Total Harmonic Distortion | $f = 1\text{ kHz}$ (3) | | 0.1 | | | 0.1 | 0.3 | | 0.1 | 0.5 | | 0.1 | | % |
| Total Equivalent Input Noise | $R_S = 600\Omega$, 10–10 kHz | | 0.5(4) | 1.0(4) | | 0.8 | 1.2 | | 0.8 | 1.2 | | | | μ Vrms |
| | $R_S = 600\Omega$, 10–10 kHz | | 0.5(4,5) | 0.7(4,5) | | | | | 0.65(6) | 0.9(6) | | | | μ Vrms |
| Total NAB(8) | | | 190 | | | | | | 230 | | | | | μ Vrms |
| Output Noise | $R_S = 600\Omega$, 10–10 kHz | | | 140(5) | | | | | | 180(6) | | | | μ Vrms |

Note (1): Specifications apply for $T_A = 25^\circ\text{C}$ with $V_S = 14\text{V}$ for LM381, LM382, LM387 and $V_S = \pm 13\text{V}$ for LM1303 unless otherwise noted.

Note (2): DC current; symmetrical ac current = 2 mA p-p.

Note (3): LM381 and LM387 gain = 60 dB; LM382 gain = 60 dB; LM1303 gain = 40 dB.

Note (4): Single ended input biasing.

Note (5): LM381AN.

Note (6): LM387AN.

Note (7): Frequency compensation: $C = 0.0047\mu\text{F}$, pins 3 to 4.

Note (8): NAB reference level: 37 dBV gain at 1 kHz. Tape playback circuit.

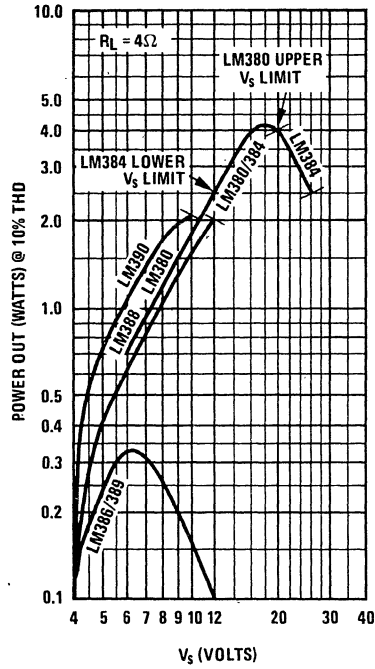


FIGURE 1. P_O vs V_S For $R_L = 4\Omega$

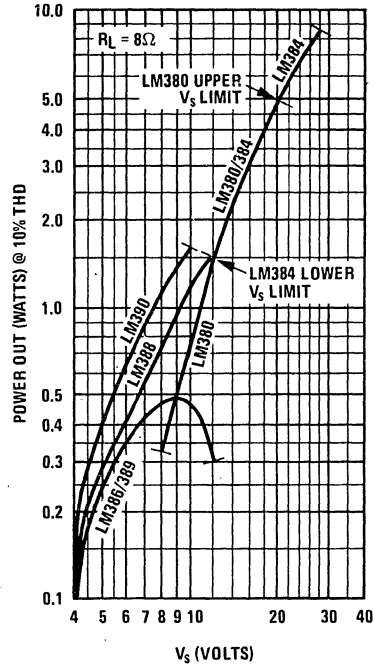


FIGURE 2. P_O vs V_S For $R_L = 8\Omega$

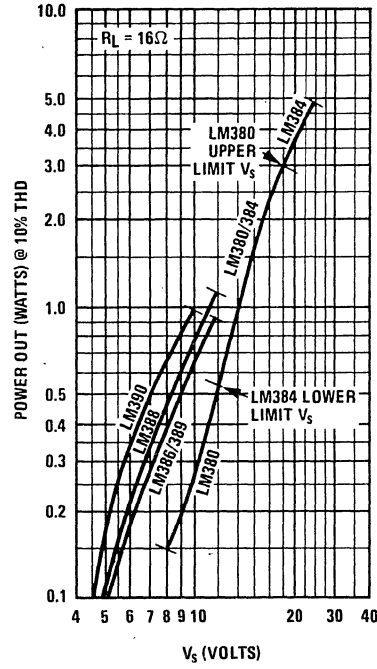


FIGURE 3. P_O vs V_S For $R_L = 16\Omega$



Definition of Terms

AGC dc Output Shift: The shift of the quiescent IC output voltage of the AGC section for a given change in AGC central voltage.

AGC Figure of Merit (AGC Range): The widest possible range of input signal level required to make the output drop by a specified amount from the specified maximum output level.

AGC Input Current: The current required to bias the central voltage input of the AGC section.

AM Rejection Ratio: The ratio of the recovered audio output produced by a desired FM signal of specified level and duration to the recovered audio output produced by an unwanted AM signal of specified amplitude and modulating index.

Channel Separation: The level of output signal of an undriven amplifier with respect to the output level of an adjacent driven amplifier.

Detection Bandwidth: That frequency range about the free running frequency of the tone decoder/phase locked loop where a signal above a specified level will cause a detected signal condition at the output.

Detection Bandwidth Skew: The measure of how well the detection bandwidth is centered about the free running frequency. It is equal to the maximum detection bandwidth frequency plus the minimum detection bandwidth frequency minus twice the free running frequency.

Hold In Range: That range of frequencies about the free running frequency for which the phase locked loop will stay in lock if initially starting out in lock.

Input Bias Current: The average of the two input currents.

Input Resistance: The ratio of the change in input voltage to the change in input current on either input with the other grounded.

Input Sensitivity: The minimum level of input signal at a specified frequency required to produce a specified signal-to-noise ratio at the recovered audio output.

Input Voltage Range: The range of voltages on the input terminals for which the amplifier operates within specifications.

Large-Signal Voltage Gain: The ratio of the output voltage swing to the change in input voltage required to drive the output from zero to this voltage.

Limiting Threshold: In FM the input signal level which causes the recovered audio output level to drop 3 dB from the output level with a specified large signal input.

Lock In Range: That range of frequencies about the free running frequency for which the phase locked loop will come into lock if initially starting out of lock.

Maximum Sweep Rate: The maximum rate that the VCO may be made to vary its oscillating frequency over its Sweep Range.

Output Resistance: The ratio of the change in output voltage to the change in output current with the output around zero.

Output Voltage Swing: The peak output voltage swing, referred to zero, that can be obtained without clipping.

Phase Detector Sensitivity: The change in the output voltage of the phase detector for a given change in phase between the two input signals to the phase detector.

Power Bandwidth: That frequency at which the voltage gain reduces to $1/\sqrt{2}$ with respect to the flat band voltage gain specified for a given load and output power.

Power Supply Rejection: The ratio of the change in input offset voltage to the change in power supply voltages producing it.

Slew Rate: The internally limited rate of change in output voltage with a large amplitude step function applied to the input.

Supply Current: The current required from the power supply to operate the amplifier with no load and the output at zero.

Sweep Range: That ratio of maximum oscillating frequency to minimum operating frequency produced by varying the central voltage of the VCO from its maximum value to its minimum value with fixed values of timing resistance and capacitance.

VCO Sensitivity: The change in operating frequency for a given change in VCO central voltage.

LM377 Dual 2 Watt Audio Amplifier

General Description

The LM377 is a monolithic dual power amplifier which offers high quality performance for stereo phonographs, tape players, recorders, and AM-FM stereo receivers, etc.

The LM377 will deliver 2W/channel into 8 or 16Ω loads. The amplifier is designed to operate with a minimum of external components and contains an internal bias regulator to bias each amplifier. Device overload protection consists of both internal current limit and thermal shutdown. For more information, see AN-125. The LM377 is not recommended for new designs; see the LM1877 data sheet for an improved pin-for-pin replacement to the LM377 in audio applications.

Features

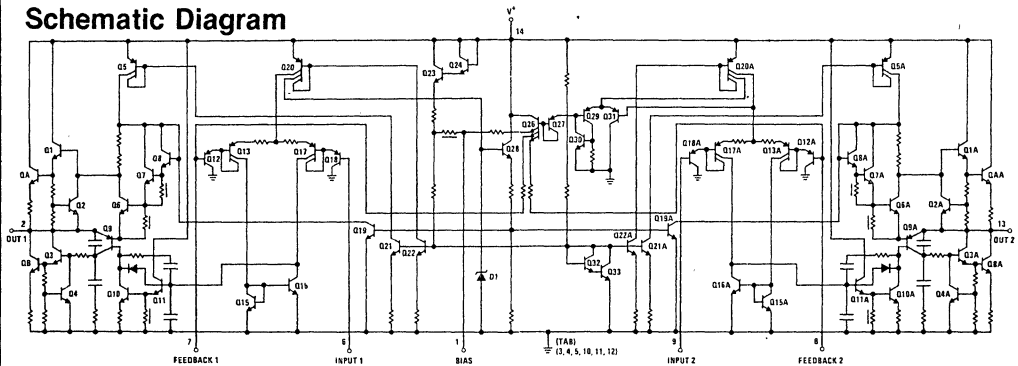
- A_{VO} typical 90 dB
- 2W per channel
- 70 dB ripple rejection
- 75 dB channel separation
- Internal stabilization

- Self centered biasing
- 3 MΩ input impedance
- 10–26V operation
- Internal current limiting
- Internal thermal protection

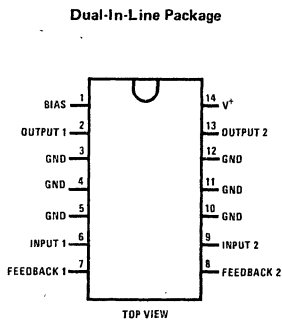
Applications

- Multi-channel audio systems
- Tape recorders and players
- Movie projectors
- Automotive systems
- Stereo phonographs
- Bridge output stages
- AM-FM radio receivers
- Intercoms
- Servo amplifiers
- Instrument systems

Schematic Diagram



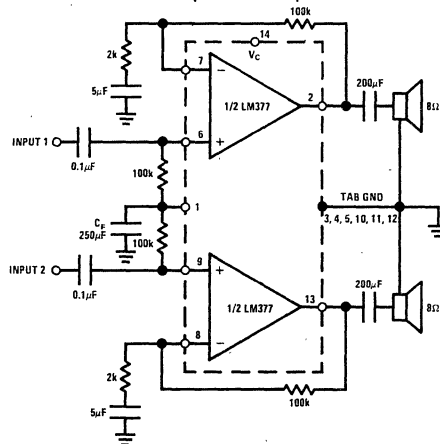
Connection Diagram



Order Number LM377N
See NS Package N14A

Typical Applications

Simple Stereo Amplifier



Absolute Maximum Ratings

| | |
|--|-----------------------------------|
| Supply Voltage | 26V |
| Input Voltage | $0V - V_{SUPPLY}$ |
| Operating Temperature | $0^{\circ}C$ to $+70^{\circ}C$ |
| Storage Temperature | $-65^{\circ}C$ to $+150^{\circ}C$ |
| Junction Temperature | $150^{\circ}C$ |
| Lead Temperature (Soldering, 10 seconds) | $300^{\circ}C$ |

Electrical Characteristics

$V_S = 20V$, $T_{TAB} = 25^{\circ}C$, $R_L = 8\Omega$, $A_V = 50$ (34 dB), unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|---|-----|----------------------|-----------|---------------|
| Total Supply Current | $P_{OUT} = 0W$ $P_{OUT} = 1.5W/Channel$ | | 15 430 | 50 500 | mA mA |
| DC Output Level | | | 10 | | V |
| Supply Voltage | | 10 | | 26 | V |
| Output Power | T.H.D. = < 5% | 2 | 2.5 | | W |
| T.H.D. | $P_{OUT} = 0.05W/Channel$, $f = 1 kHz$ $P_{OUT} = 1W/Channel$, $f = 1 kHz$ $P_{OUT} = 2W/Channel$, $f = 1 kHz$ | | 0.25 0.07 0.10 | 1 | % % % |
| Offset Voltage | | | 15 | | mV |
| Input Bias Current | | | 100 | | nA |
| Input Impedance | | 3 | | | $M\Omega$ |
| Open Loop Gain | $R_S = 0\Omega$ | 66 | 90 | | dB |
| Output Swing | | | $V_S - 6$ | | V_{P-P} |
| Channel Separation | $C_F = 250\mu F$, $f = 1 kHz$ | 50 | 70 | | dB |
| Ripple Rejection | $f = 120 Hz$, $C_F = 250\mu F$ | 60 | 70 | | dB |
| Current Limit | | | 1.5 | | A |
| Slew Rate | | | 1.4 | | $V/\mu s$ |
| Equivalent Input Noise Voltage | $R_S = 600\Omega$, 100 Hz – 10 kHz | | 3 | | μV_{rms} |

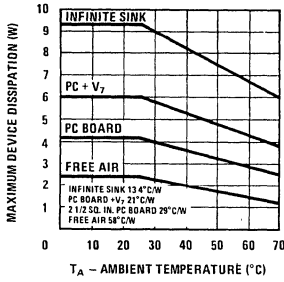
Note 1: For operation at ambient temperatures greater than $25^{\circ}C$ the LM377 must be derated based on a maximum $150^{\circ}C$ junction temperature using a thermal resistance which depends upon device mounting techniques.

Note 2: Dissipation characteristics are shown for four mounting configurations.

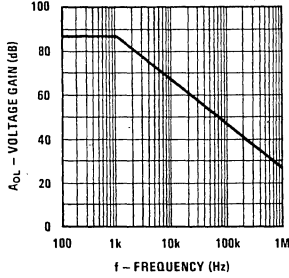
- Infinite sink – $13.4^{\circ}C/W$
- P.C. board + V_7 sink – $21^{\circ}C/W$. P.C. board is 2 1/2 square inches. Staver V_7 sink is 0.02 inch thick copper and has a radiating surface area of 10 square inches.
- P.C. board only – $29^{\circ}C/W$. Device soldered to 2 1/2 square inch P.C. board.
- Free air – $58^{\circ}C/W$.

Typical Performance Characteristics

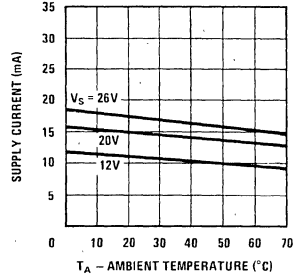
Maximum Dissipation vs Ambient Temperature



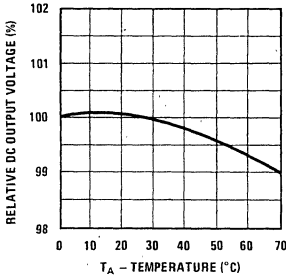
Open Loop Gain



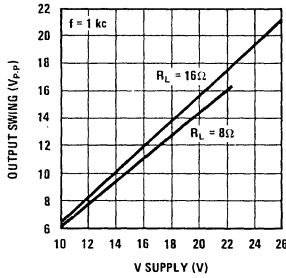
Supply Current vs Temperature



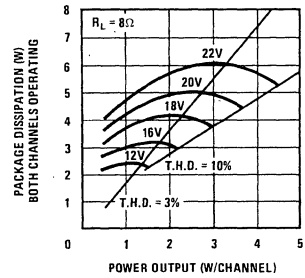
DC Output Level vs Temperature



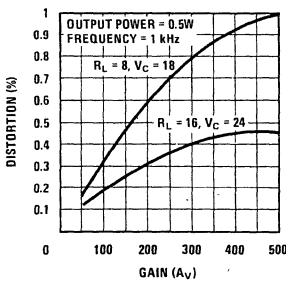
Output Swing vs V_S



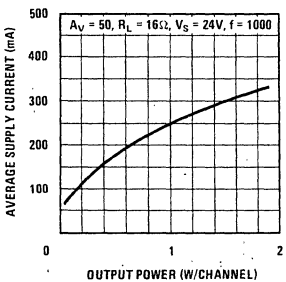
Power Dissipation vs Power Output



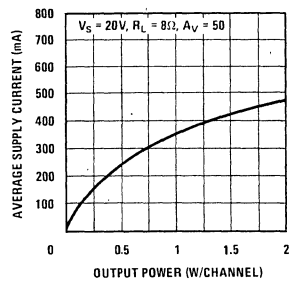
Distortion vs Gain



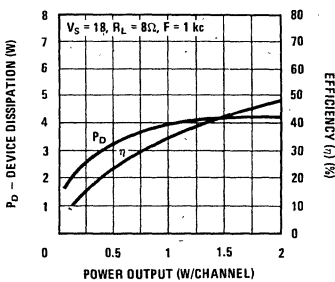
Supply Current vs Output Power



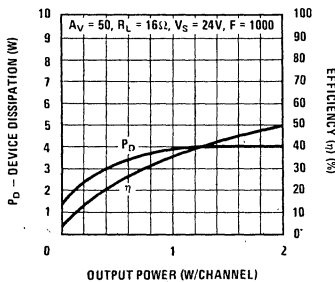
Supply Current vs P_{OUT}



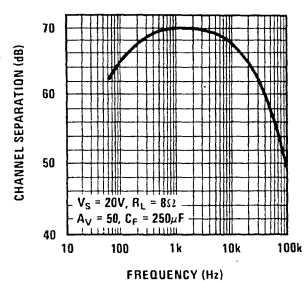
Dissipation and Efficiency vs P_{OUT}



Dissipation and Efficiency vs P_{OUT}

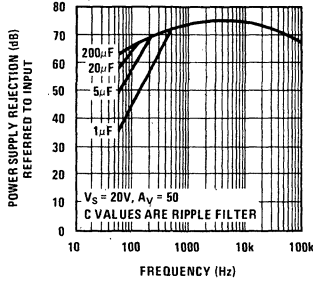


Channel Separation

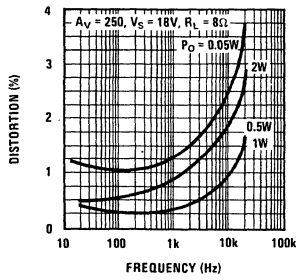


Typical Performance Characteristics (Continued)

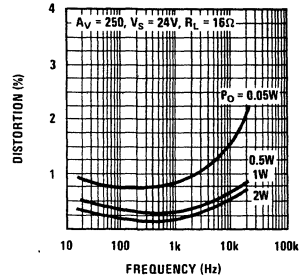
Supply Rejection vs Frequency



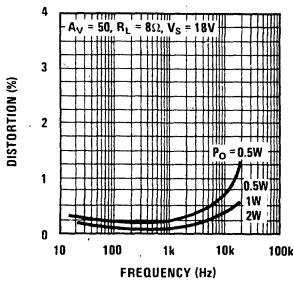
Distortion vs Frequency



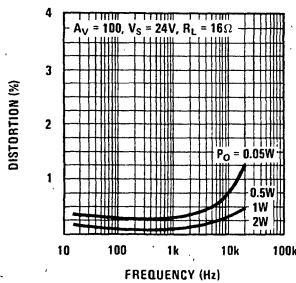
Distortion vs Frequency



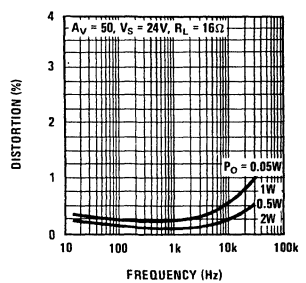
Distortion vs Frequency



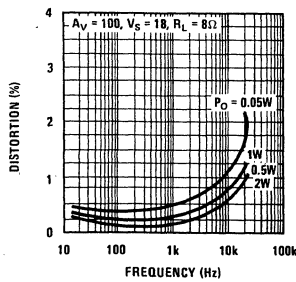
Distortion vs Frequency



Distortion vs Frequency

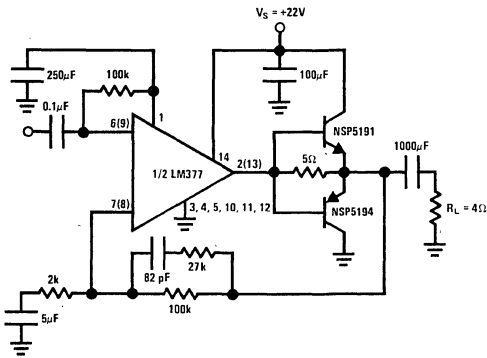


Distortion vs Frequency

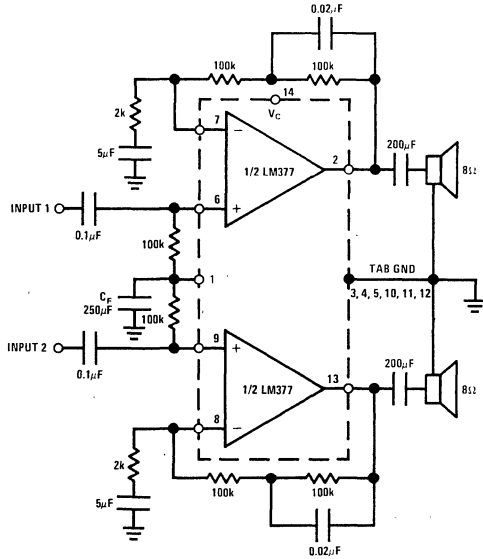


Typical Applications (Continued)

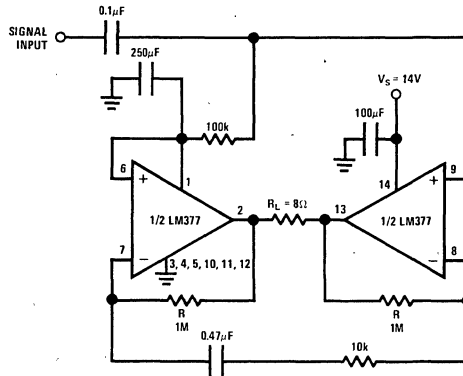
10W Per Channel Audio Amplifier



Simple Stereo Amplifier with Bass Boost



4W Bridge Amplifier



LM378 Dual 4 Watt Audio Amplifier

General Description

The LM378 is a monolithic dual power amplifier which offers high quality performance for stereo phonographs, tape players, recorders, and AM-FM stereo receivers, etc.

The LM378 will deliver 4W channel into 8 or 16Ω loads. The amplifier is designed to operate with a minimum of external components and contains an internal bias regulator to bias each amplifier. Device overload protection consists of both internal current limit and thermal shutdown. For more information see AN-125.

Features

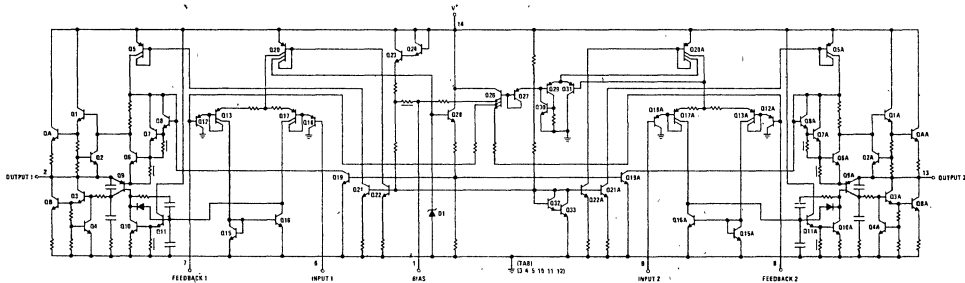
- A_{VO} typical 90 dB
- 4W per channel
- 70 dB ripple rejection
- 75 dB channel separation
- Internal stabilization

- Self centered biasing
- 3 MΩ input impedance
- Internal current limiting
- Internal thermal protection

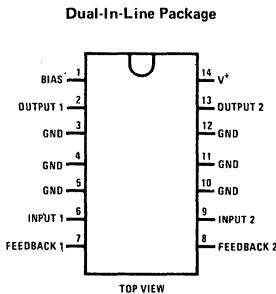
Applications

- Multi-channel audio systems
- Tape recorders and players
- Movie projectors
- Automotive systems
- Stereo phonographs
- Bridge output stages
- AM-FM radio receivers
- Intercoms
- Servo amplifiers
- Instrument systems

Schematic Diagram

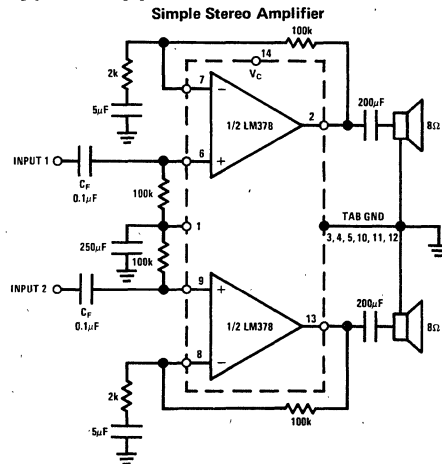


Connection Diagram



Order Number LM378N
See NS Package N14A

Typical Applications



Absolute Maximum Ratings

| | |
|--|-----------------------------------|
| Supply Voltage | 35V |
| Input Voltage | $0V - V_{SUPPLY}$ |
| Operating Temperature | $0^{\circ}C$ to $+70^{\circ}C$ |
| Storage Temperature | $-65^{\circ}C$ to $+150^{\circ}C$ |
| Junction Temperature | $150^{\circ}C$ |
| Lead Temperature (Soldering, 10 seconds) | $300^{\circ}C$ |

Electrical Characteristics

$V_S = 24V$, $T_{TAB} = 25^{\circ}C$, $R_L = 8\Omega$, $A_V = 50$ (34 dB), unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|---|-----|------|-----|---------------|
| Total Supply Current | $P_{OUT} = 0W$ | | 15 | 50 | mA |
| | $P_{OUT} = 1.5W/Channel$ | | 430 | 500 | mA |
| DC Output Level | | | 12 | | V |
| Supply Voltage | | 10 | | | V |
| Output Power | T.H.D. = $< 5\%$, $R_L = 8\Omega$ | 4 | 5 | | W |
| | T.H.D. = $< 5\%$, $R_L = 16\Omega$ | 4 | 5 | | W* |
| T.H.D. | $P_{OUT} = 0.05W/Channel$, $f = 1$ kHz | | 0.25 | | % |
| | $P_{OUT} = 1W/Channel$, $f = 1$ kHz | | 0.07 | 1 | % |
| | $P_{OUT} = 2W/Channel$, $f = 1$ kHz | | 0.10 | | % |
| Offset Voltage | | | 15 | | mV |
| Input Bias Current | | | 100 | | nA |
| Input Impedance | | 3 | | | M Ω |
| Open Loop Gain | $R_S = 0\Omega$ | 66 | 90 | | dB |
| Channel Separation | $C_F = 250\mu F$, $f = 1$ kHz | 50 | 70 | | dB |
| Ripple Rejection | $f = 120$ Hz, $C_F = 250\mu F$ | 60 | 70 | | dB |
| Current Limit | | | 1.5 | | A |
| Slew Rate | | | 1.4 | | V/ μs |
| Equivalent Input Noise Voltage | $R_S = 600\Omega$, 100 Hz – 10 kHz | | 3 | | μV_{rms} |

Note 1: For operation at ambient temperatures greater than $25^{\circ}C$ the LM378 must be derated based on a maximum $150^{\circ}C$ junction temperature using a thermal resistance which depends upon device mounting techniques.

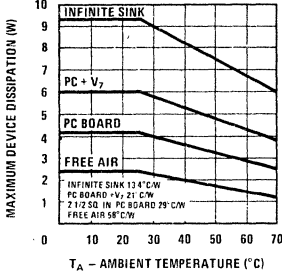
Note 2: Dissipation characteristics are shown for four mounting configurations.

- Infinite sink – $13.4^{\circ}C/W$
- P.C. board +V₇ sink – $21^{\circ}C/W$. P.C. board is 2 1/2 square inches. Staver V₇ sink is 0.02 inch thick copper and has a radiating surface area of 10 square inches.
- P.C. board only – $29^{\circ}C/W$. Device soldered to 2 1/2 square inch P.C. board.
- Free air – $58^{\circ}C/W$.

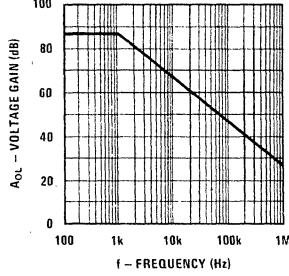
*Tested at $V_S = 30V$.

Typical Performance Characteristics

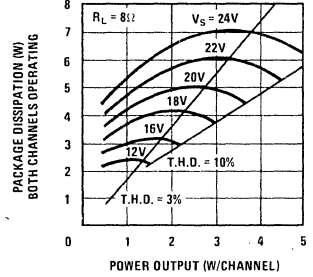
Maximum Dissipation vs Ambient Temperature



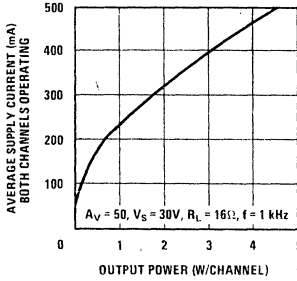
Open Loop Gain



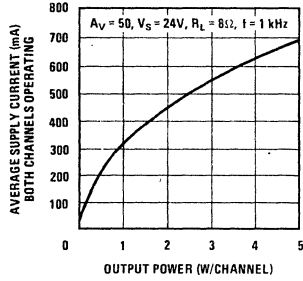
Power Dissipation vs Power Output



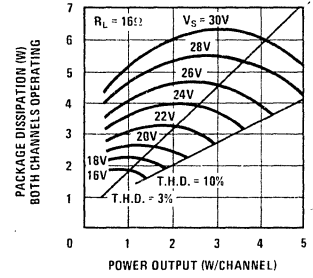
Supply Current vs Output Power



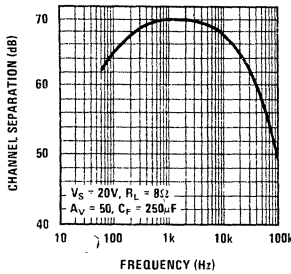
Supply Current vs Output Power



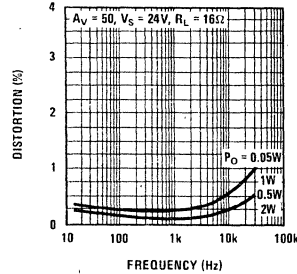
Power Dissipation vs Power Output



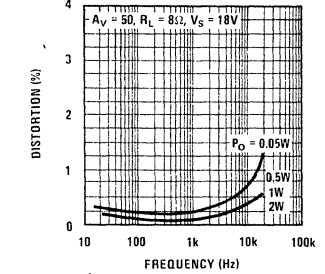
Channel Separation



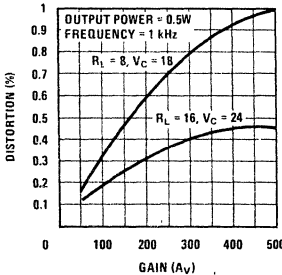
Distortion vs Frequency



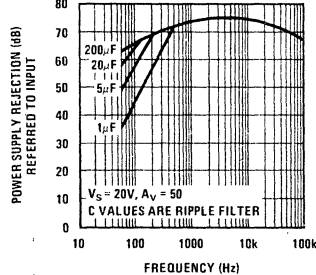
Distortion vs Frequency



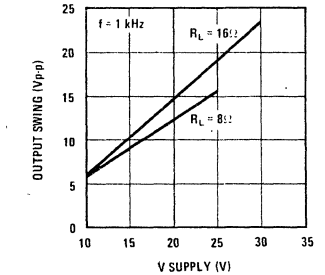
Distortion vs Gain



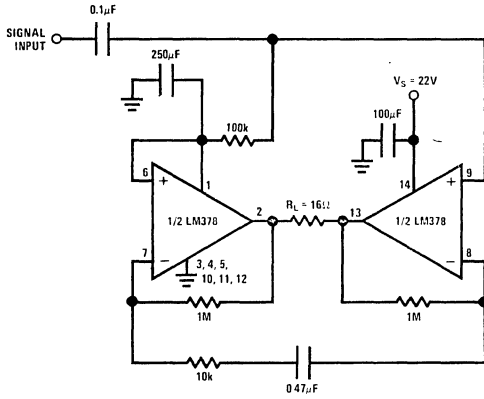
Supply Rejection vs Frequency



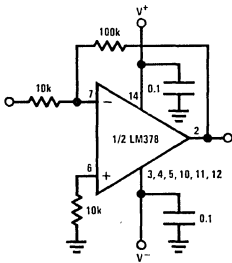
Output Swing vs V_S



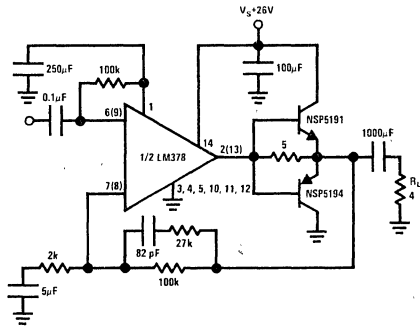
Typical Applications (Continued)



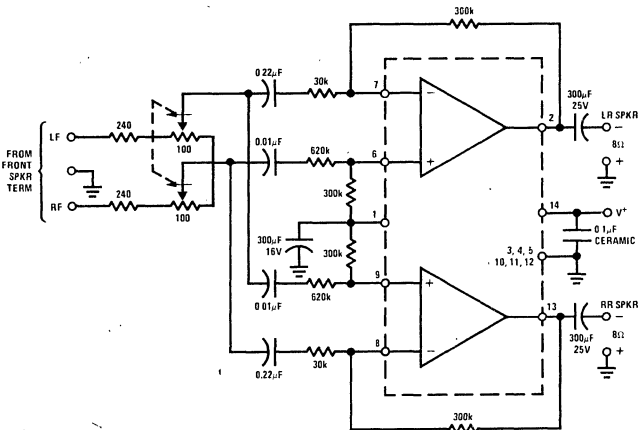
8W Bridge Amplifier



Power Op Amp
(Using Split Supplies)



15W Per Channel Audio Amplifier



Rear Speaker Ambience (4-Channel) Amplifier

LM379 Dual 6 Watt Audio Amplifier

General Description

The LM379 is a monolithic dual power amplifier which offers high quality performance for stereo phonographs, tape players, recorders, and AM-FM stereo receivers, etc.

The LM379 will deliver 6W/channel to an 8Ω load. The amplifier is designed to operate with a minimum of external components and contains an internal bias regulator to bias each amplifier. Device overload protection consists of both internal current limit and thermal shutdown. For more information, see AN-125.

Features

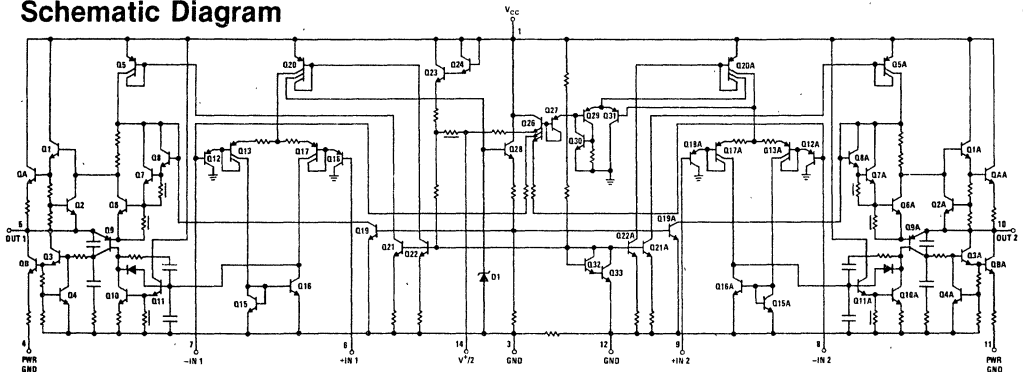
- A_{VO} typical 90 dB
- 6W per channel
- 70 dB ripple rejection
- 75 dB channel separation
- Internal stabilization

- Self centered biasing
- 3 MΩ input impedance
- Internal current limiting
- Internal thermal protection

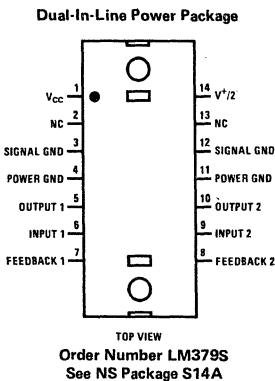
Applications

- Multi-channel audio systems
- Tape recorders and players
- Movie projectors
- Automotive systems
- Stereo phonographs
- Bridge output stages
- AM-FM radio receivers
- Intercoms
- Servo amplifiers
- Instrument systems

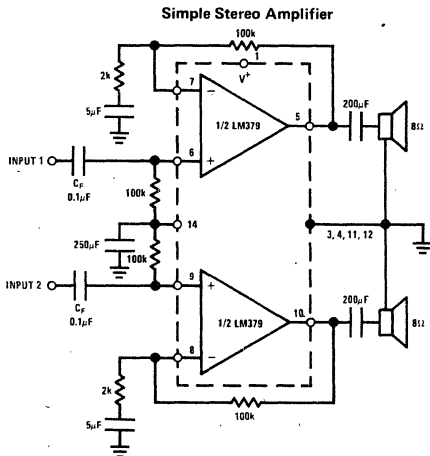
Schematic Diagram



Connection Diagram



Typical Applications



Absolute Maximum Ratings

| | |
|--|--------------------------|
| Supply Voltage | 35V |
| Input Voltage | 0V – V _{SUPPLY} |
| Operating Temperature | 0°C to +70°C |
| Storage Temperature | -65°C to +150°C |
| Junction Temperature | 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

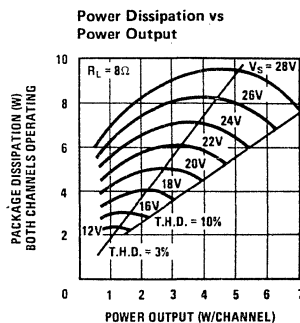
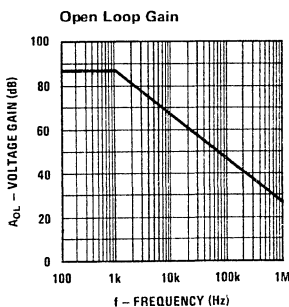
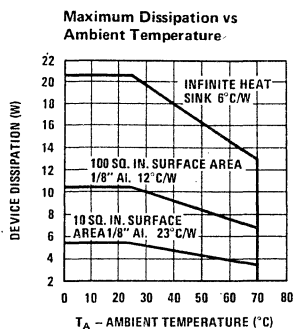
Electrical Characteristics

V_S = 28V, T_{TAB} = 25°C, R_L = 8Ω, A_V = 50 (34 dB), unless otherwise specified.

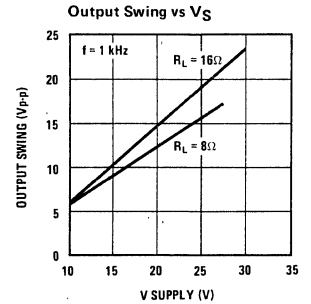
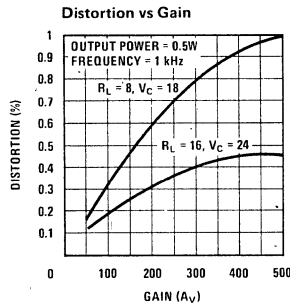
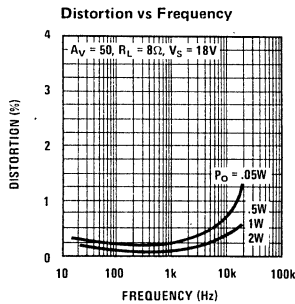
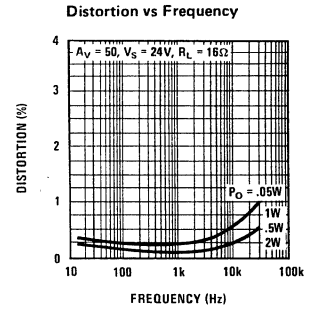
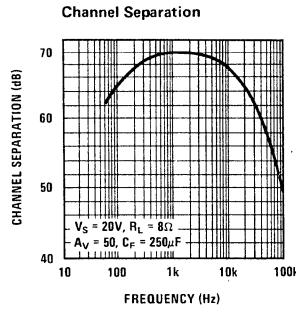
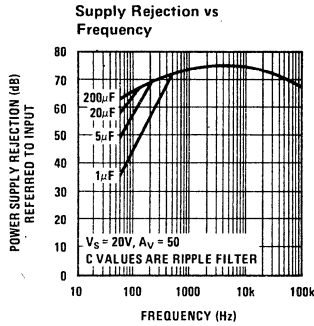
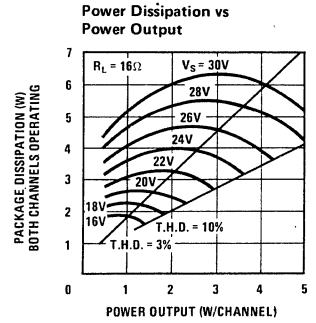
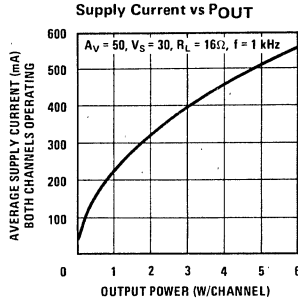
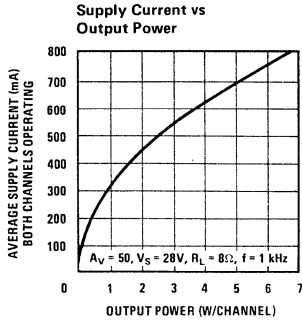
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|--|-----|------|-----|-------------------|
| Total Supply Current | P _{OUT} = 0W | | 15 | 65 | mA |
| | P _{OUT} = 1.5W/Channel | | 430 | | mA |
| DC Output Level | | | 14 | | V |
| Supply Voltage | | 10 | | | V |
| Output Power | T.H.D. = 5% | | 6 | | W |
| | T.H.D. = 10% | 6 | 7 | | W |
| T.H.D. | P _{OUT} = 1W/Channel, f = 1 kHz | | 0.07 | 1 | % |
| | P _{OUT} = 4W/Channel, f = 1 kHz | | 0.2 | | % |
| Offset Voltage | | | 15 | | mV |
| Input Bias Current | | | 100 | | nA |
| Input Impedance | | 3 | | | MΩ |
| Open Loop Gain | R _S = 0Ω | 66 | 90 | | dB |
| Channel Separation | C _F = 250μF, f = 1 kHz | 50 | 70 | | dB |
| Ripple Rejection | f = 120 Hz, C _F = 250μF | | 70 | | dB |
| Current Limit | | | 1.5 | | A |
| Slew Rate | | | 1.4 | | V/μs |
| Equivalent Input Noise Voltage | R _S = 600Ω, 100 Hz – 10 kHz | | 3 | | μV _{rms} |

Note 1: For operation at ambient temperatures greater than 25°C the LM379 must be derated based on a maximum 150°C junction temperature using a thermal resistance which depends upon device mounting techniques. In most applications it is advisable to heat sink to the chassis. See curves.

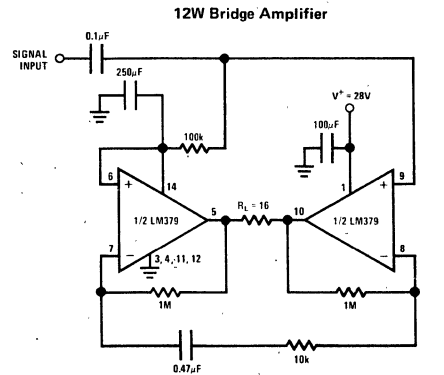
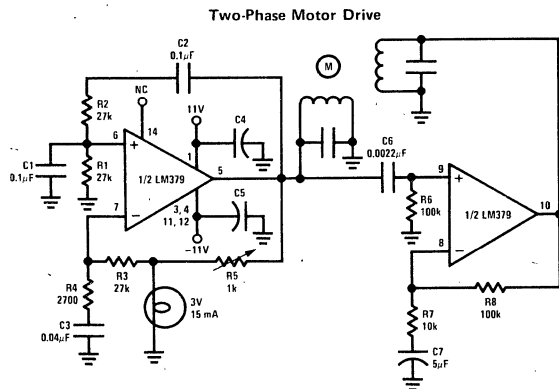
Typical Performance Characteristics



Typical Performance Characteristics (Continued)

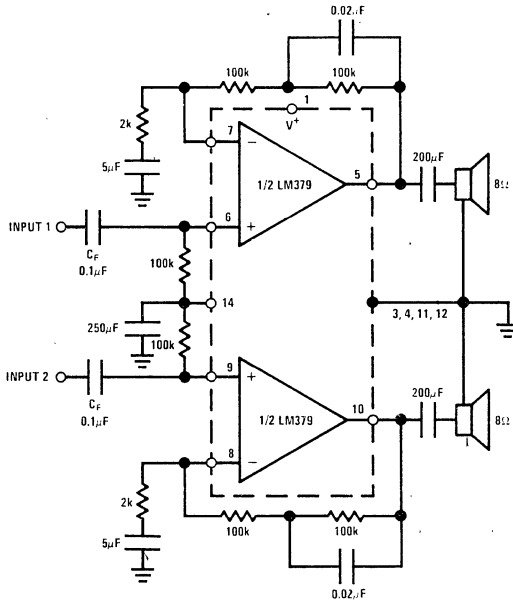


Typical Applications (Continued)

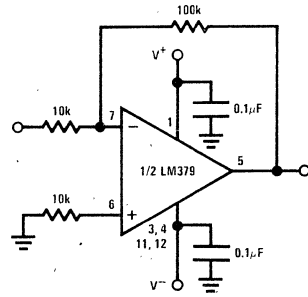


Typical Applications (Continued)

Simple Stereo Amplifier with Bass Boost



Power Op Amp (Using Split Supplies)



LM380 Audio Power Amplifier

General Description

The LM380 is a power audio amplifier for consumer application. In order to hold system cost to a minimum, gain is internally fixed at 34 dB. A unique input stage allows inputs to be ground referenced. The output is automatically self centering to one half the supply voltage.

The output is short circuit proof with internal thermal limiting. The package outline is standard dual-in-line. A copper lead frame is used with the center three pins on either side comprising a heat sink. This makes the device easy to use in standard p-c layout.

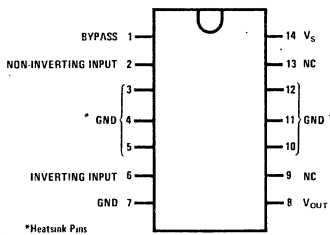
Uses include simple phonograph amplifiers, intercoms, line drivers, teaching machine outputs, alarms, ultrasonic drivers, TV sound systems, AM-FM radio, small servo drivers, power converters, etc.

A selected part for more power on higher supply voltages is available as the LM384. For more information see AN-69.

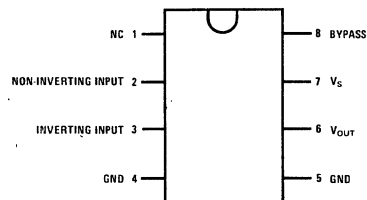
Features

- Wide supply voltage range
- Low quiescent power drain
- Voltage gain fixed at 50
- High peak current capability
- Input referenced to GND
- High input impedance
- Low distortion
- Quiescent output voltage is at one-half of the supply voltage
- Standard dual-in-line package

Connection Diagrams (Dual-In-Line Packages, Top View)

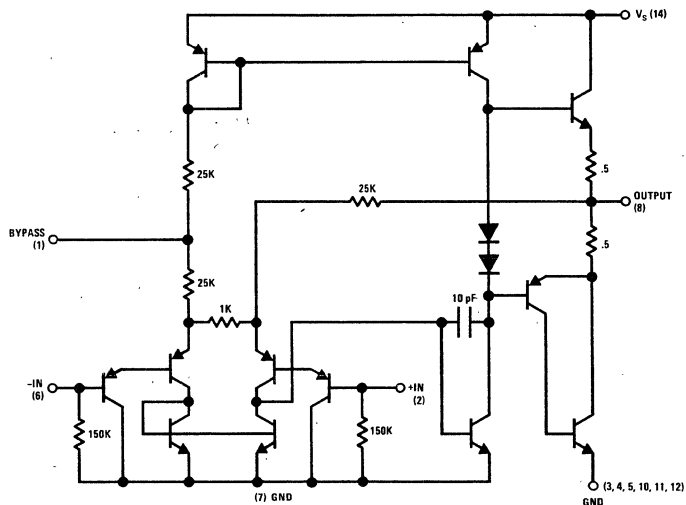
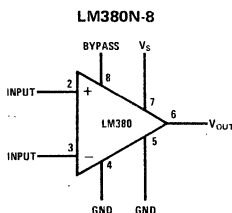
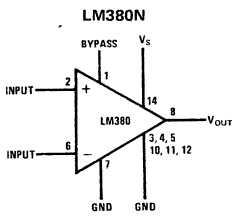


Order Number LM380N
See NS Package N14A



Order Number LM380N-8
See NS Package N08B

Block and Schematic Diagrams



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 22V |
| Peak Current | 1.3A |
| Package Dissipation 14-Pin DIP (Notes 6 and 7) | 10W |
| Input Voltage | ±0.5V |
| Storage Temperature | -65°C to +150°C |
| Operating Temperature | 0°C to +70°C |
| Junction Temperature | +150°C |
| Lead Temperature (Soldering, 10 sec) | +300°C |

Electrical Characteristics (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------|----------------|---|-----|------|-----|----------|
| Output Power | $P_{OUT(RMS)}$ | (Notes 3, 4) $R_L = 8\Omega$, THD = 3% | 2.5 | | | W |
| Gain | A_V | | 40 | 50 | 60 | V/V |
| Output Voltage Swing | V_{OUT} | $R_L = 8\Omega$ | | 14 | | V_{PP} |
| Input Resistance | Z_{IN} | | | 150k | | Ω |
| Total Harmonic Distortion | THD | (Note 4, 5) | | 0.2 | | % |
| Power Supply Rejection Ratio | PSRR | (Note 2) | | 38 | | dB |
| Supply Voltage | V_S | | 8 | | 22 | V |
| Bandwidth | BW | $P_{OUT} = 2W$, $R_L = 8\Omega$ | | 100k | | Hz |
| Quiescent Supply Current | I_Q | | | 7 | 25 | mA |
| Quiescent Output Voltage | V_{OUTQ} | | 8 | 9.0 | 10 | V |
| Bias Current | I_{BIAS} | Inputs Floating | | 100 | | nA |
| Short Circuit Current | I_{SC} | | | 1.3 | | A |

Note 1: $V_S = 18V$ and $T_A = 25^\circ C$ unless otherwise specified.

Note 2: Rejection ratio referred to the output with $C_{BYPASS} = 5 \mu F$.

Note 3: With device Pins 3, 4, 5, 10, 11, 12 soldered into a 1/16" epoxy glass board with 2 ounce copper foil with a minimum surface of 6 square inches.

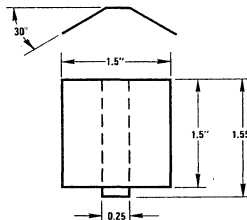
Note 4: If oscillation exists under some load conditions, add 2.7 Ω and 0.1 μF series network from Pin 8 to Gnd.

Note 5: $C_{BYPASS} = 0.47 \mu F$ on Pin 1.

Note 6: The maximum junction temperature of the LM380 is 150°C.

Note 7: The package is to be derated at 12°C/W junction to heat sink pins.

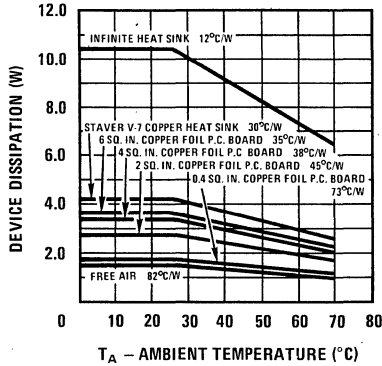
Heat Sink Dimensions



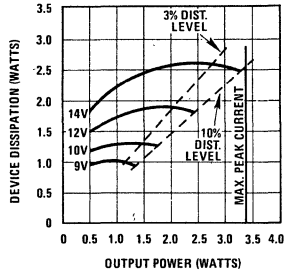
COPPER WINGS
2 REQUIRED
SOLDERED TO
PINS 3, 4, 5,
10, 11, 12
THICKNESS 0.04
INCHES

Typical Performance Characteristics

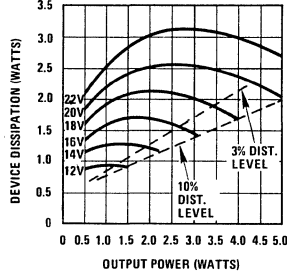
Device Dissipation vs Ambient Temperature



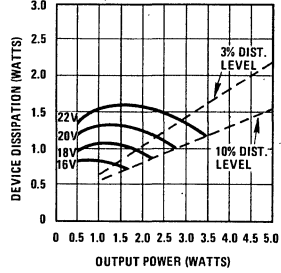
Device Dissipation vs Output Power - 4Ω Load



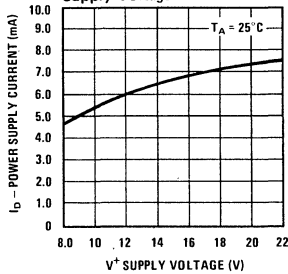
Device Dissipation vs Output Power - 8Ω Load



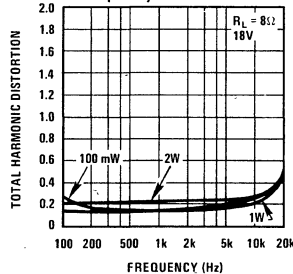
Device Dissipation vs Output Power - 16Ω Load



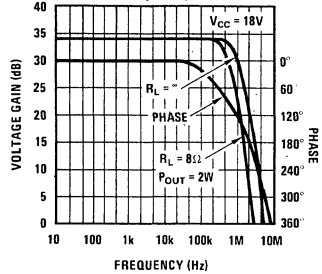
Power Supply Current vs Supply Voltage



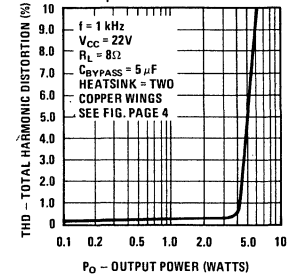
Total Harmonic Distortion vs Frequency



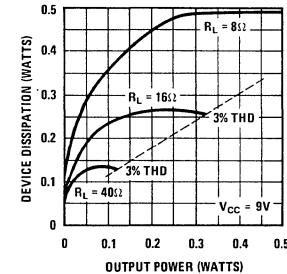
Output Voltage Gain and Phase vs Frequency



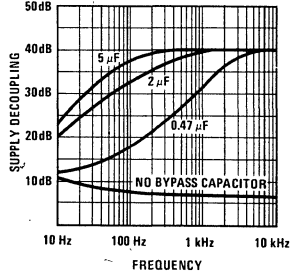
Total Harmonic Distortion vs Output Power



Device Dissipation vs Output Power

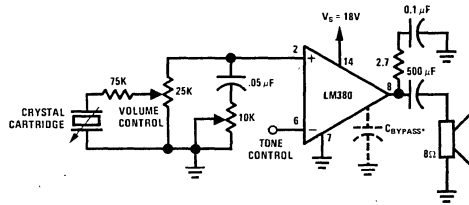


Supply Decoupling vs Frequency

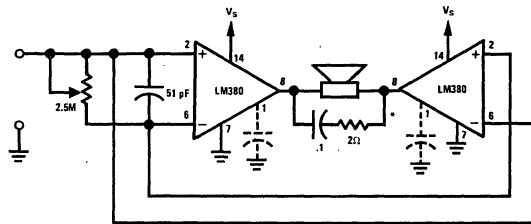


Typical Applications

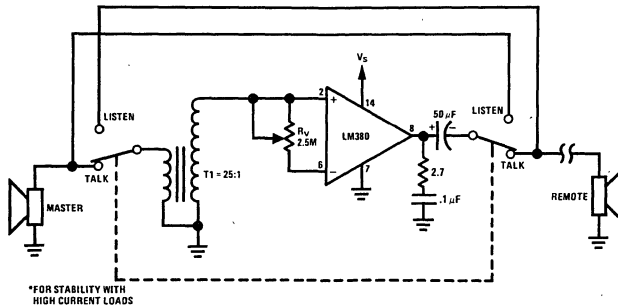
Phono Amplifier



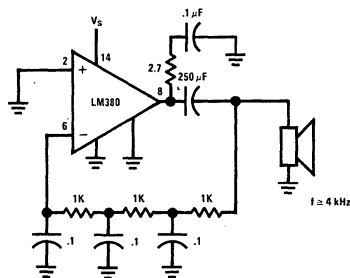
Bridge Amplifier



Intercom



Phase Shift Oscillator





LM381/LM381A Low Noise Dual Preamplifier

General Description

The LM381/LM381A is a dual preamplifier for the amplification of low level signals in applications requiring optimum noise performance. Each of the two amplifiers is completely independent, with individual internal power supply decoupler, regulator, providing 120 dB supply rejection and 60 dB channel separation. Other outstanding features include high gain (112 dB), large output voltage swing ($V_{CC} - 2V$) p-p, and wide power bandwidth (75 kHz, 20V_{p-p}). The LM381/LM381A operates from a single supply across the wide range of 9 to 40V.

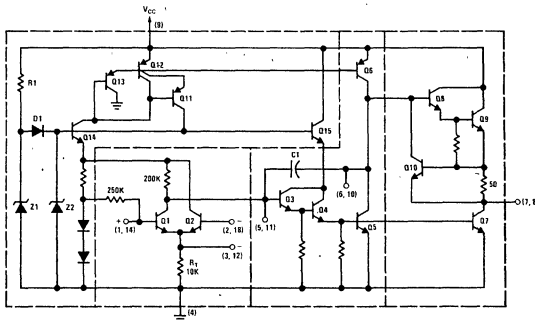
Either differential input or single ended input configurations may be selected. The amplifier is internally compensated with the provision for additional external compensation for narrow band

applications. For additional information see AN-64, AN-104.

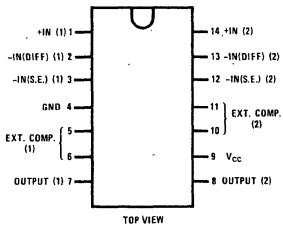
Features

- Low Noise — $.5 \mu V$ total input noise
- High Gain — 112 dB open loop
- Single Supply Operation
- Wide supply range 9–40V
- Power supply rejection 120 dB
- Large output voltage swing ($V_{CC} - 2V$)_{p-p}
- Wide bandwidth 15 MHz unity gain
- Power bandwidth 75 kHz, 20 V_{p-p}
- Internally compensated
- Short circuit protected

Schematic and Connection Diagrams

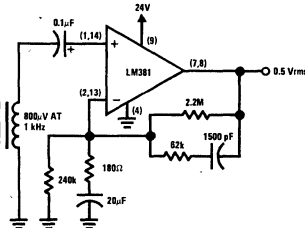


Dual-In-Line Package

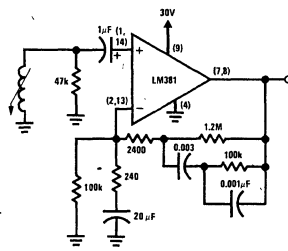


Order Number LM381N or LM381AN
See NS Package N14A

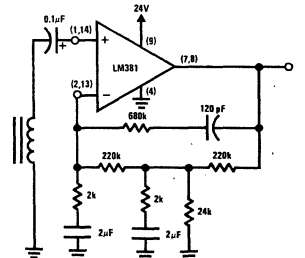
Typical Applications



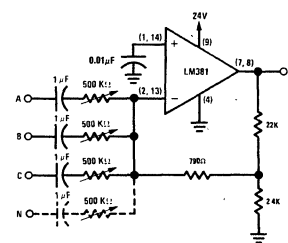
Typical Tape Playback Amplifier



Typical Magnetic Phono Preamp



Two-Pole Fast Turn-On NAB Tape Preamp



Audio Mixer

Absolute Maximum Ratings

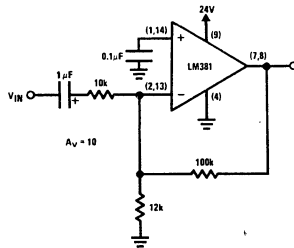
| | |
|--------------------------------------|-----------------|
| Supply Voltage | +40V |
| Power Dissipation (Note 1) | 715 mW |
| Operating Temperature Range | 0°C to 70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $V_{CC} = 14\text{V}$, unless otherwise stated.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------|---|--------|--------------|-----|------------------|
| Voltage Gain | Open Loop (Differential Input), $f = 100\text{ Hz}$ | | 160,000 | | V/V |
| | Open Loop (Single Ended), $f = 100\text{ Hz}$ | | 320,000 | | V/V |
| Supply Current | V_{CC} 9 to 40V, $R_L = \infty$ | | 10 | | mA |
| Input Resistance | (Positive Input) | | 100 | | k Ω |
| | (Negative Input) | | 200 | | k Ω |
| Input Current | (Negative Input) | | 0.5 | | μA |
| Output Resistance | Open Loop | | 150 | | Ω |
| Output Current | Source | | 8 | | mA |
| | Sink | | 2 | | mA |
| Output Voltage Swing | Peak-to-Peak | | $V_{CC} - 2$ | | V |
| Unity Gain Bandwidth | | | 15 | | MHz |
| Power Bandwidth | $20 V_{p-p}$ ($V_{CC} = 24\text{V}$) | | 75 | | kHz |
| Maximum Input Voltage | Linear Operation | | | 300 | mVrms |
| Supply Rejection Ratio | $f = 1\text{ kHz}$ | | 120 | | dB |
| Channel Separation | $f = 1\text{ kHz}$ | | 60 | | dB |
| Total Harmonic Distortion | 60 dB Gain, $f = 1\text{ kHz}$ | | 0.1 | | % |
| Total Equivalent Input Noise | $R_S = 600\Omega$, 10 - 10,000 Hz (Single Ended Input, Flat Gain Circuit, $A_V = 1000$) | | | | |
| | | LM381A | | 0.5 | 0.7 |
| LM381 | | | 0.5 | 1.0 | μVrms |

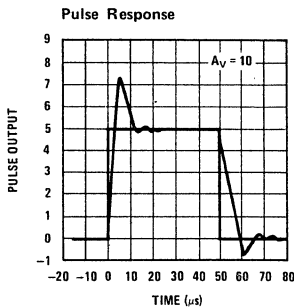
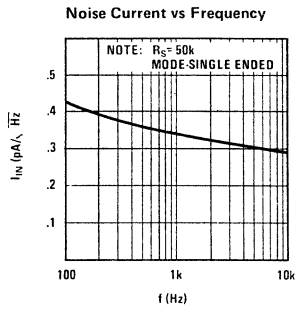
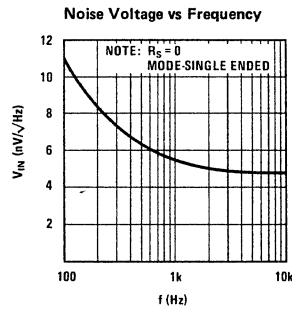
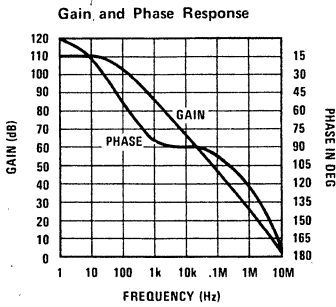
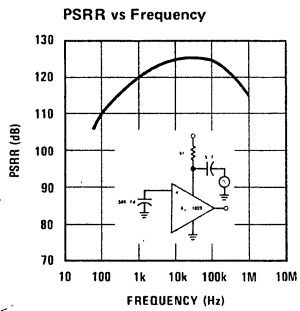
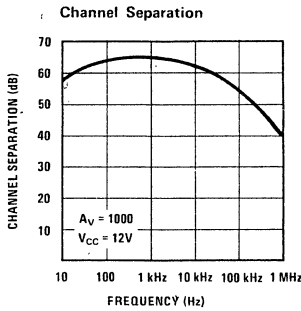
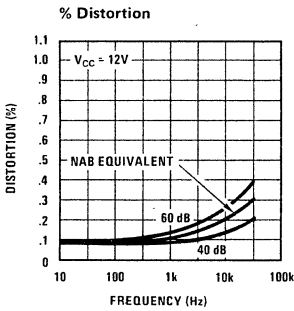
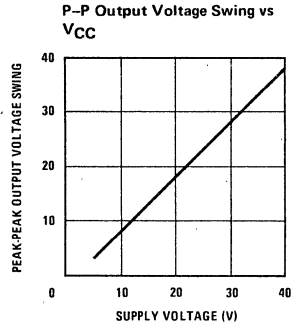
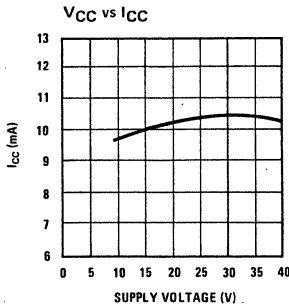
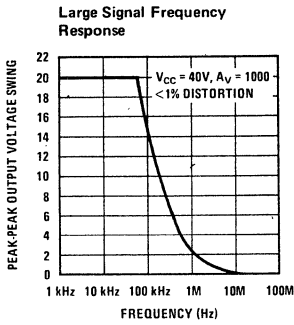
Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Typical Applications (Continued)



Ultra-Low Distortion Amplifier
 $(A_V = 10, \text{THD} < 0.05\%, V_{OUT} = 3\text{ V}_{RMS})$

Typical Performance Characteristics



LM382 Low Noise Dual Preamplifier

General Description

The LM382 is a dual preamplifier for the amplification of low level signals in applications requiring optimum noise performance. Each of the two amplifiers is completely independent, with individual internal power supply decoupler-regulator, providing 120 dB supply rejection and 60 dB channel separation. Other outstanding features include high gain (100 dB), and wide power bandwidth (75 kHz, 20 V_{p-p}). The LM382 operates from a single supply across the wide range of 9 to 40V.

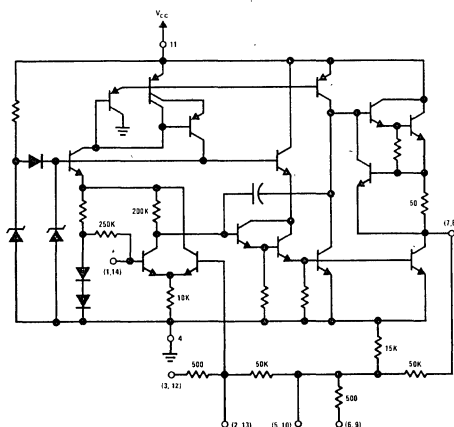
A resistor matrix is provided on the chip to allow the user to select a variety of closed loop gain options and frequency response characteristics such as flat-band, NAB or RIAA equalization. The

circuit is supplied in the 14 lead dual-in-line package.

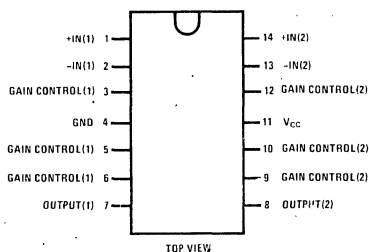
Features

- Low noise — 0.8 μ V total equivalent input noise
- High gain — 100 dB open loop
- Single supply operation
- Wide supply range 9 to 40V
- Power supply rejection — 120 dB
- Large output voltage swing
- Wide bandwidth — 15 MHz unity gain
- Power bandwidth — 75 kHz, 20 V_{p-p}
- Internally compensated
- Short circuit protected.

Schematic and Connection Diagrams

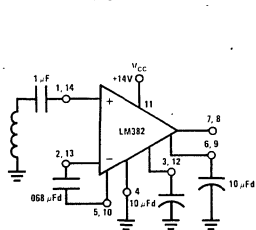


Dual-In-Line Package

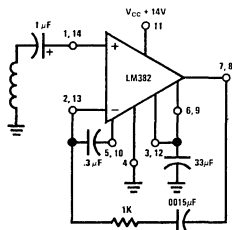


Order Number LM382N
See NS Package N14A

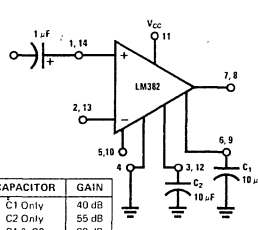
Typical Applications



Tape Preamp (NAB Equalization)



Phono Preamp (RIAA Equalization)



| CAPACITOR | GAIN |
|---------------------------------|-------|
| C ₁ Only | 40 dB |
| C ₂ Only | 55 dB |
| C ₁ & C ₂ | 80 dB |

Flat Response — Fixed Gain Configuration

Absolute Maximum Ratings

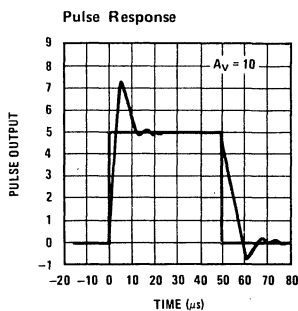
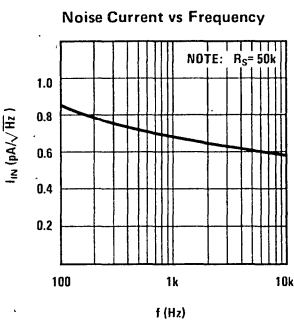
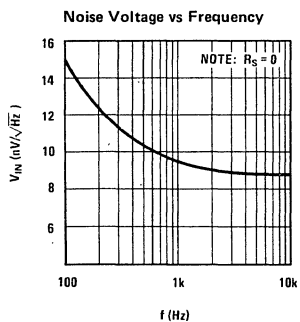
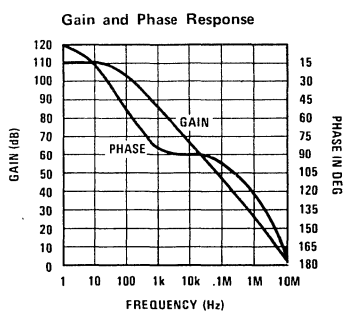
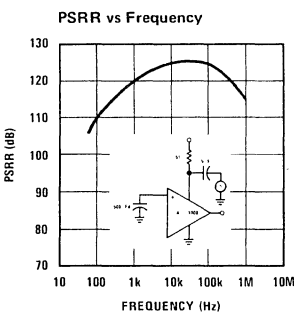
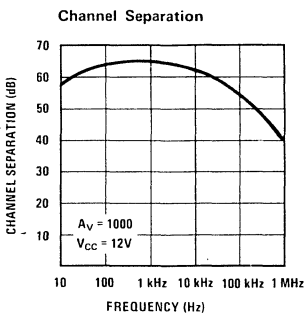
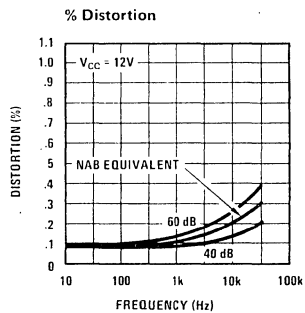
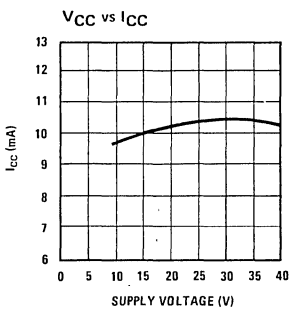
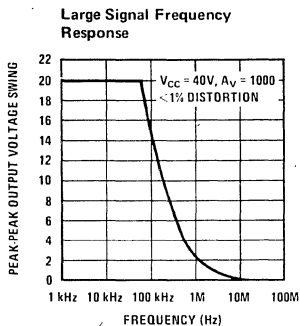
| | |
|--------------------------------------|-----------------|
| Supply Voltage | +40V |
| Power Dissipation (Note 1) | 715 mW |
| Operating Temperature Range | 0°C to 70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $V_{CC} = 14\text{V}$, unless otherwise stated.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------|--|-----|---------|-----|---------------------|
| Voltage Gain | Open Loop, $f = 100\text{ Hz}$ | | 100,000 | | V/V |
| Supply Current | $V_{CC} 9\text{ to }40\text{V}$, $R_L = \infty$ | | 10 | 16 | mA |
| Output DC Voltage | | | 6 | | V |
| Input Resistance | | | | | |
| (Positive Input) | | | 100 | | k Ω |
| (Negative Input) | | | 200 | | k Ω |
| Input Current | | | | | |
| (Negative Input) | | | 0.5 | | μA |
| Output Resistance | Open Loop | | 150 | | Ω |
| Output Current | Source | | 8 | | mA |
| | Sink | | 2 | | mA |
| Output Voltage Swing | Peak-to-Peak, $R_L = 10\text{k}$ | | 12 | | V |
| Unity Gain Bandwidth | | | 15 | | MHz |
| Power Bandwidth | 20 V _{p-p} ($V_{CC} = 24\text{V}$) | | 75 | | kHz |
| Maximum Input Voltage | Linear Operation | | | 300 | mV _{rms} |
| Supply Rejection Ratio | $f = 1\text{ kHz}$ | | 120 | | dB |
| Channel Separation | $f = 1\text{ kHz}$ | 40 | 60 | | dB |
| Total Harmonic Distortion | 60 dB Gain, $f = 1\text{ kHz}$ | | 0.1 | 0.3 | % |
| Total Equivalent Input Noise | $R_S = 600\Omega$, 100 – 10,000 Hz (Flat Response Circuit) | | 0.8 | 1.2 | μV_{rms} |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Typical Performance Characteristics



LM383/LM383A 8 Watt Audio Power Amplifier

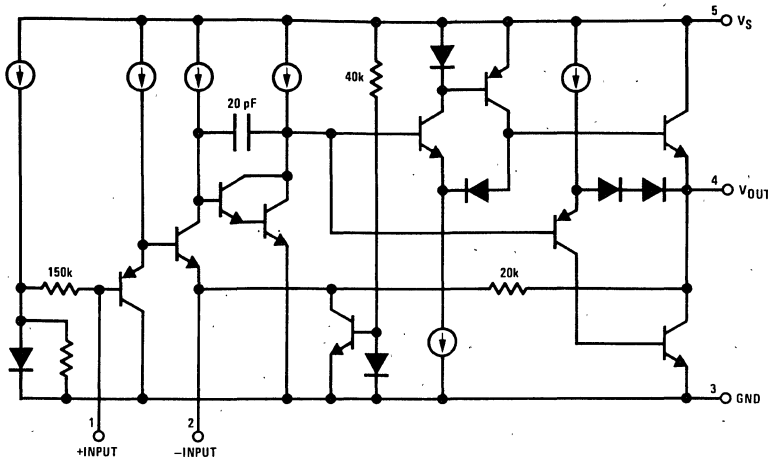
General Description

The LM383 is a cost effective, high power amplifier suited for automotive applications. High current capability (3.5A) enables the device to drive low impedance loads with low distortion. The LM383 is current limited and thermally protected. High voltage protection is available (LM383A) which enables the amplifier to withstand 40V transients on its supply. The LM383 comes in a 5-pin TO-220 package.

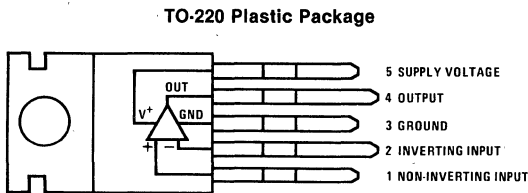
Features

- High peak current capability (3.5A)
- Large output voltage swing
- Externally programmable gain
- Wide supply voltage range (5V-20V)
- Few external parts required
- Low distortion
- High input impedance
- No turn-on transients
- High voltage protection available (LM383A)
- Low noise
- Short circuit protected

Equivalent Schematic

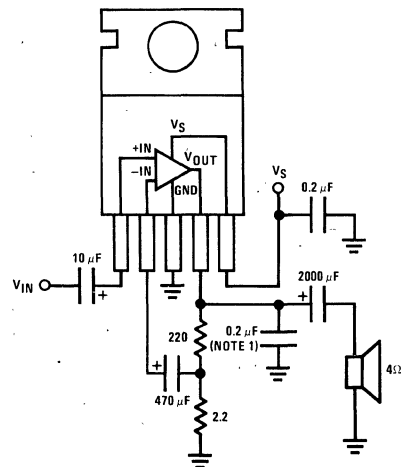


Connection Diagram



Order Number LM383T or LM383AT
See NS Package T05A

Typical Applications



Absolute Maximum Ratings

| | |
|--|-----------------|
| Peak Supply Voltage (50 ms) | |
| LM383A (Note 2) | 40V |
| LM383 | 25V |
| Operating Supply Voltage | 20V |
| Output Current | |
| Repetitive | 3.5A |
| Non-repetitive | 4.5A |
| Input Voltage | $\pm 0.5V$ |
| Power Dissipation (Note 3) | 15W |
| Operating Temperature | 0°C to +70°C |
| Storage Temperature | -60°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $V_S = 14.4V$, $T_{TAB} = 25^\circ C$, $A_V = 100$ (40 dB), $R_L = 4\Omega$, unless otherwise specified

| Parameter | Conditions | Min | Typ | Max | Units |
|--------------------------|--|-----|------|-----|------------|
| DC Output Level | | 6.4 | 7.2 | 8 | V |
| Quiescent Supply Current | Excludes Current in Feedback Resistors | | 45 | 80 | mA |
| Supply Voltage Range | | 5 | | 20 | V |
| Input Resistance | | | 150 | | k Ω |
| Bandwidth | Gain = 40 dB | | 30 | | kHz |
| Output Power | $V_S = 13.2V$, $f = 1$ kHz | | | | |
| | $R_L = 4\Omega$, THD = 10% | | 4.7 | | W |
| | $R_L = 2\Omega$, THD = 10% | | 7.2 | | W |
| | $V_S = 13.8V$, $f = 1$ kHz | | | | |
| | $R_L = 4\Omega$, THD = 10% | | 5.1 | | W |
| | $R_L = 2\Omega$, THD = 10% | | 7.8 | | W |
| | $V_S = 14.4V$, $f = 1$ kHz | | | | |
| | $R_L = 4\Omega$, THD = 10% | 4.8 | 5.5 | | W |
| | | 7 | 8.6 | | W |
| | $V_S = 16V$, $f = 1$ kHz | | | | |
| | $R_L = 4\Omega$, THD = 10% | | 7 | | W |
| | $R_L = 2\Omega$, THD = 10% | | 10.5 | | W |
| THD | $P_o = 2W$, $R_L = 4\Omega$, $f = 1$ kHz | | 0.2 | | % |
| | $P_o = 4W$, $R_L = 2\Omega$, $f = 1$ kHz | | 0.2 | | % |
| Ripple Rejection | $R_S = 50\Omega$, $f = 100$ Hz | 30 | 40 | | dB |
| | $R_S = 50\Omega$, $f = 1$ kHz | | 44 | | dB |
| Input Noise Voltage | $R_S = 0$, 15 kHz Bandwidth | | 2 | | μV |
| Input Noise Current | $R_S = 100$ k Ω , 15 kHz Bandwidth | | 40 | | pA |

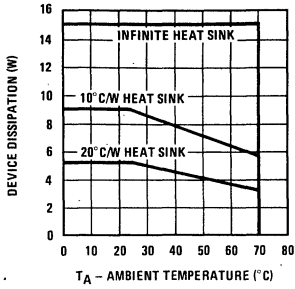
Note 1: A 0.2 μF capacitor should be placed as close as possible to pins 3 and 4 for stability.

Note 2: The LM383 shuts down above 25V.

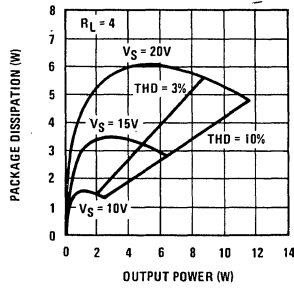
Note 3: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 4°C/W junction to case.

Typical Performance Characteristics

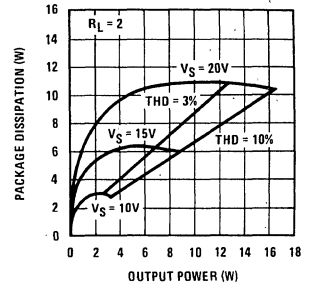
Device Dissipation vs Ambient Temperature



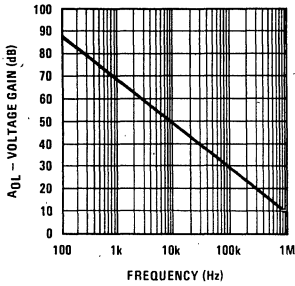
Power Dissipation vs Output Power



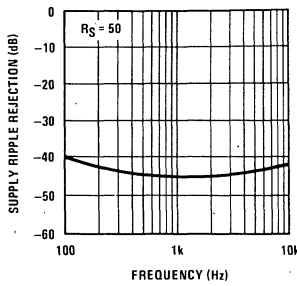
Power Dissipation vs Output Power



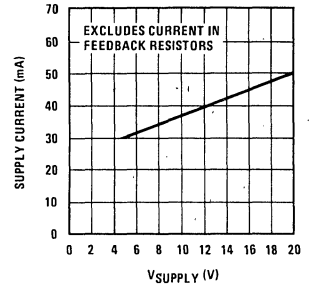
Open Loop Gain vs Frequency



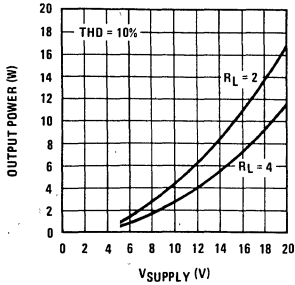
Supply Ripple Rejection vs Frequency



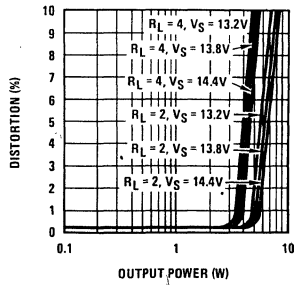
Supply Current vs Supply Voltage



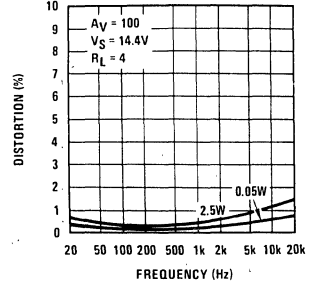
Output Power vs Supply Voltage



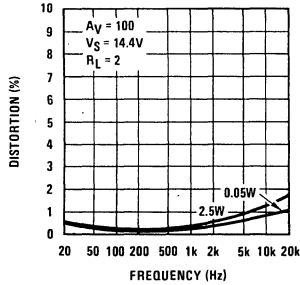
Distortion vs Output Power



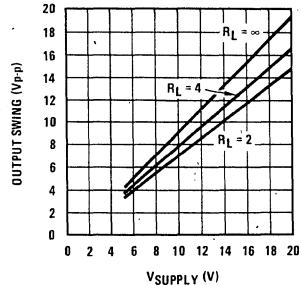
Distortion vs Frequency



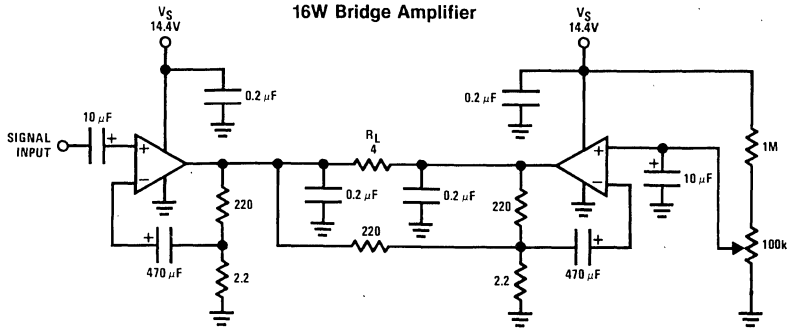
Distortion vs Frequency



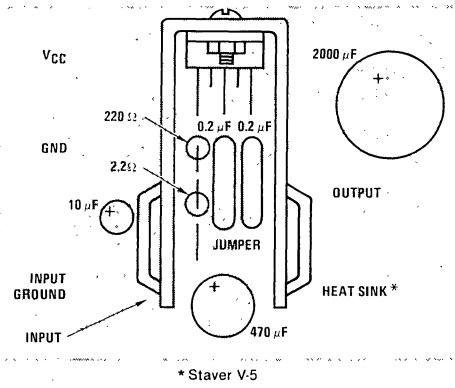
Output Swing vs Supply Voltage



Typical Applications (Continued)



Component Layout



*Staver V-5

LM384 5 Watt Audio Power Amplifier

General Description

The LM384 is a power audio amplifier for consumer application. In order to hold system cost to a minimum, gain is internally fixed at 34 dB. A unique input stage allows inputs to be ground referenced. The output is automatically self-centering to one half the supply voltage.

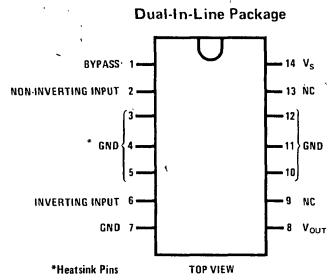
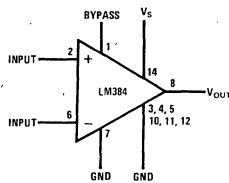
The output is short-circuit proof with internal thermal limiting. The package outline is standard dual-in-line. A copper lead frame is used with the center three pins on either side comprising a heat sink. This makes the device easy to use in standard p-c layout.

Uses include simple phonograph amplifiers, intercoms, line drivers, teaching machine outputs, alarms, ultrasonic drivers, TV sound systems, AM-FM radio, sound projector systems, etc. See AN-69 for circuit details.

Features

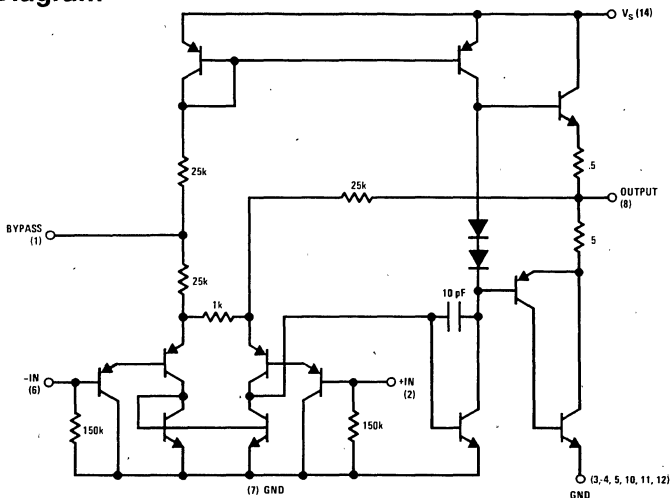
- Wide supply voltage range
- Low quiescent power drain
- Voltage gain fixed at 50
- High peak current capability
- Input referenced to GND
- High input impedance
- Low distortion
- Quiescent output voltage is at one half of the supply voltage
- Standard dual-in-line package

Block and Connection Diagrams



Order Number LM384N
See NS Package N14A

Schematic Diagram



Absolute Maximum Ratings

| | |
|--|-----------------------------------|
| Supply Voltage | 28V |
| Peak Current | 1.3A |
| Power Dissipation | (See Notes 3 and 4) |
| Input Voltage | $\pm 0.5V$ |
| Storage Temperature | $-65^{\circ}C$ to $+150^{\circ}C$ |
| Operating Temperature | $0^{\circ}C$ to $+70^{\circ}C$ |
| Lead Temperature (Soldering, 10 seconds) | $300^{\circ}C$ |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-------------------------------|-----|------|-----|-----------|
| Input Resistance (Z_{IN}) | | | 150 | | $k\Omega$ |
| Bias Current (I_{BIAS}) | Inputs Floating | | 100 | | nA |
| Gain (A_V) | | 40 | 50 | 60 | V/V |
| Output Power (P_{OUT}) | THD = 10%, $R_L = 8\Omega$ | 5 | 5.5 | | W |
| Quiescent Supply Current (I_Q) | | | 8.5 | 25 | mA |
| Quiescent Output Voltage (V_{OUTQ}) | | | 11 | | V |
| Bandwidth (BW) | $P_{OUT} = 2W, R_L = 8\Omega$ | | 450 | | kHz |
| Supply Voltage (V^+) | | 12 | | 26 | V |
| Short Circuit Current (I_{SC}) | | | 1.3 | | A |
| Power Supply Rejection Ratio (PSRR _{RTO}) (Note 2) | | | 31 | | dB |
| Total Harmonic Distortion (THD) | $P_{OUT} = 4W, R_L = 8\Omega$ | | 0.25 | 1.0 | % |

Note 1: $V^+ = 22V$ and $T_A = 25^{\circ}C$ operating with a Staver V7 heat sink for 30 seconds.

Note 2: Rejection ratio referred to the output with $C_{BYPASS} = 5\mu F$, freq = 120 Hz.

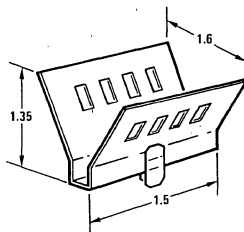
Note 3: The maximum junction temperature of the LM384 is $150^{\circ}C$.

Note 4: The package is to be derated at $12^{\circ}C/W$ junction to heat sink pins.

Note 5: Output is fully protected against a shorted speaker condition at all voltages up to 22V.

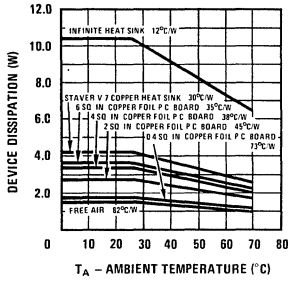
Heat Sink Dimensions

Staver "V7" Heat Sink

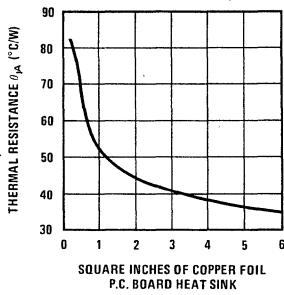


Typical Performance Characteristics

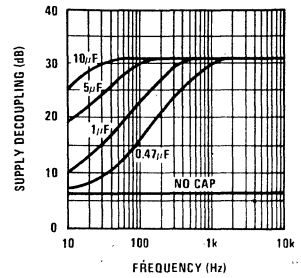
Device Dissipation vs. Ambient Temperature



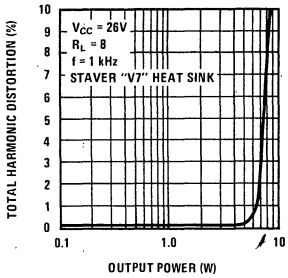
Thermal Resistance vs Square Inches



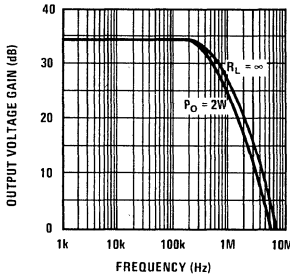
Supply Decoupling vs Frequency



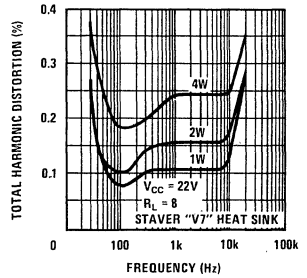
Total Harmonic Distortion vs Output Power



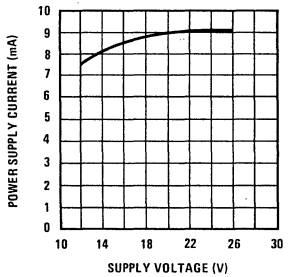
Output Voltage Gain vs Frequency



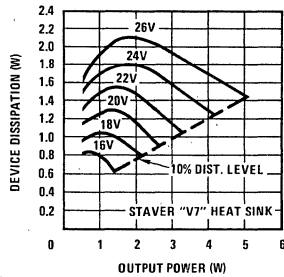
Total Harmonic Distortion vs Frequency



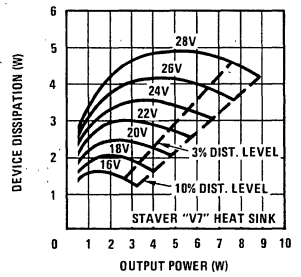
Power Supply Current vs Supply Voltage



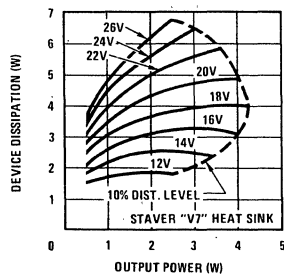
Device Dissipation vs Output Power—16 Ω Load



Device Dissipation vs Output Power—8 Ω Load

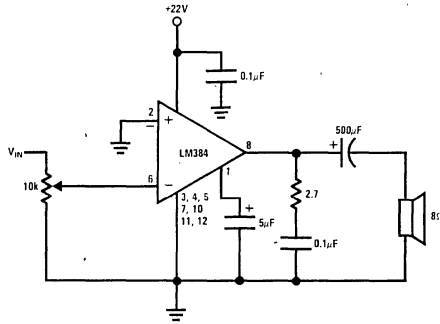


Device Dissipation vs Output Power—4 Ω Load

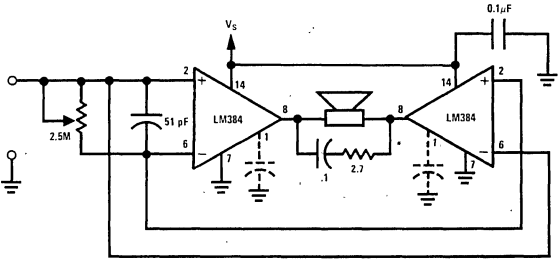


Typical Applications

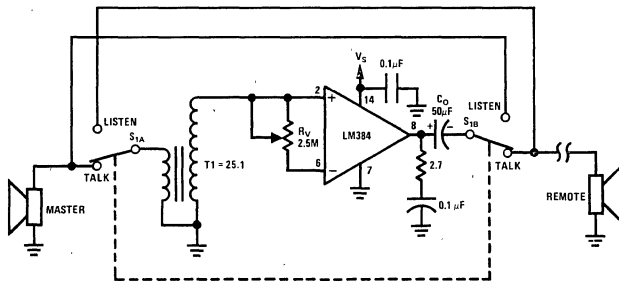
Typical 5W Amplifier



Bridge Amplifier

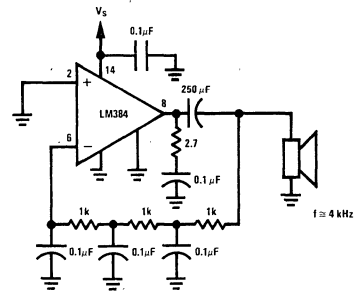


Intercom



* For stability with high current loads

Phase Shift Oscillator



LM386 Low Voltage Audio Power Amplifier

General Description

The LM386 is a power amplifier designed for use in low voltage consumer applications. The gain is internally set to 20 to keep external part count low, but the addition of an external resistor and capacitor between pins 1 and 8 will increase the gain to any value up to 200.

The inputs are ground referenced while the output is automatically biased to one half the supply voltage. The quiescent power drain is only 24 milliwatts when operating from a 6 volt supply, making the LM386 ideal for battery operation.

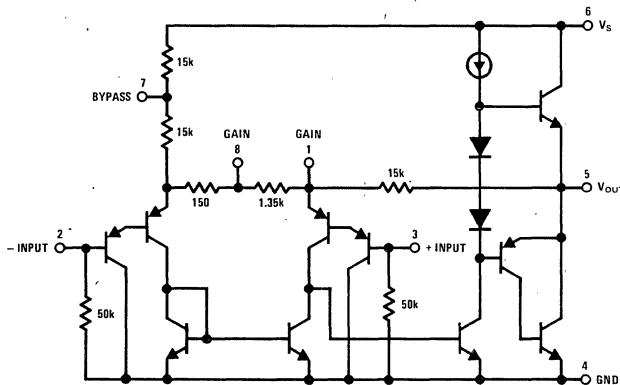
Features

- Battery operation
- Minimum external parts
- Wide supply voltage range 4V–12V or 5V–18V
- Low quiescent current drain 4 mA
- Voltage gains from 20 to 200
- Ground referenced input
- Self-centering output quiescent voltage
- Low distortion
- Eight pin dual-in-line package

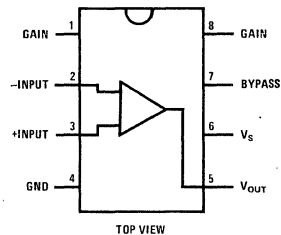
Applications

- AM-FM radio amplifiers
- Portable tape player amplifiers
- Intercoms
- TV sound systems
- Line drivers
- Ultrasonic drivers
- Small servo drivers
- Power converters

Equivalent Schematic and Connection Diagrams



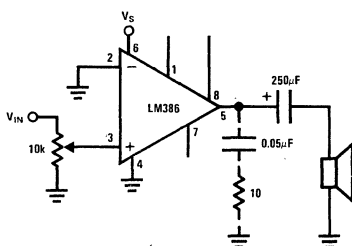
Dual-In-Line Package



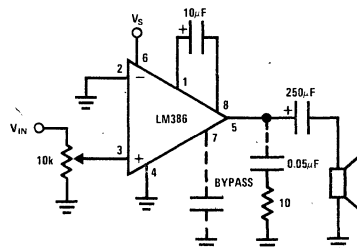
Order Number LM386N-1,
LM386N-3 or LM386N-4
See NS Package NO8B

Typical Applications

Amplifier with Gain = 20
Minimum Parts



Amplifier with Gain = 200



Absolute Maximum Ratings

| | | | |
|---|--------|--|-----------------|
| Supply Voltage (LM386N) | 15V | Storage Temperature | -65°C to +150°C |
| Supply Voltage (LM386N-4) | 22V | Operating Temperature | 0°C to +70°C |
| Package Dissipation (Note 1) (LM386N-4) | 1.25W | Junction Temperature | +150°C |
| Package Dissipation (Note 2) (LM386) | 660 mW | Lead Temperature (Soldering, 10 seconds) | +300°C |
| Input Voltage | ±0.4V | | |

Electrical Characteristics $T_A = 25^\circ\text{C}$

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------------|--|-----|------|-----|------------|
| Operating Supply Voltage (V_S) | | | | | |
| LM386 | | 4 | | 12 | V |
| LM386N-4 | | 5 | | 18 | V |
| Quiescent Current (I_Q) | $V_S = 6V, V_{IN} = 0$ | | 4 | 8 | mA |
| Output Power (P_{OUT}) | | | | | |
| LM386N-1 | $V_S = 6V, R_L = 8\Omega, THD = 10\%$ | 250 | 325 | | mW |
| LM386N-3 | $V_S = 9V, R_L = 8\Omega, THD = 10\%$ | 500 | 700 | | mW |
| LM386N-4 | $V_S = 16V, R_L = 32\Omega, THD = 10\%$ | 700 | 1000 | | mW |
| Voltage Gain (A_V) | $V_S = 6V, f = 1\text{ kHz}$ | | 26 | | dB |
| | 10 μ F from Pin 1 to 8 | | 46 | | dB |
| Bandwidth (BW) | $V_S = 6V, \text{Pins 1 and 8 Open}$ | | 300 | | kHz |
| Total Harmonic Distortion (THD) | $V_S = 6V, R_L = 8\Omega, P_{OUT} = 125\text{ mW}$ $f = 1\text{ kHz, Pins 1 and 8 Open}$ | | 0.2 | | % |
| Power Supply Rejection Ratio (PSRR) | $V_S = 6V, f = 1\text{ kHz, } C_{BYPASS} = 10\mu\text{F}$ Pins 1 and 8 Open, Referred to Output | | 50 | | dB |
| Input Resistance (R_{IN}) | | | 50 | | k Ω |
| Input Bias Current (I_{BIAS}) | $V_S = 6V, \text{Pins 2 and 3 Open}$ | | 250 | | nA |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 100°C/W junction to ambient.

Note 2: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 187°C junction to ambient.

Application Hints

GAIN CONTROL

To make the LM386 a more versatile amplifier, two pins (1 and 8) are provided for gain control. With pins 1 and 8 open the 1.35 k Ω resistor sets the gain at 20 (26 dB). If a capacitor is put from pin 1 to 8, bypassing the 1.35 k Ω resistor, the gain will go up to 200 (46 dB). If a resistor is placed in series with the capacitor, the gain can be set to any value from 20 to 200. Gain control can also be done by capacitively coupling a resistor (or FET) from pin 1 to ground.

Additional external components can be placed in parallel with the internal feedback resistors to tailor the gain and frequency response for individual applications. For example, we can compensate poor speaker bass response by frequency shaping the feedback path. This is done with a series RC from pin 1 to 5 (paralleling the internal 15 k Ω resistor). For 6 dB effective bass boost: $R \cong 15\text{ k}\Omega$, the lowest value for good stable operation is $R = 10\text{ k}\Omega$ if pin 8 is open. If pins 1 and 8 are bypassed then R as low as 2 k Ω can be used. This restriction is because the amplifier is only compensated for closed-loop gains greater than 9.

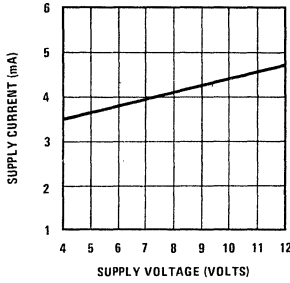
INPUT BIASING

The schematic shows that both inputs are biased to ground with a 50 k Ω resistor. The base current of the input transistors is about 250 nA, so the inputs are at about 12.5 mV when left open. If the dc source resistance driving the LM386 is higher than 250 k Ω it will contribute very little additional offset (about 2.5 mV at the input, 50 mV at the output). If the dc source resistance is less than 10 k Ω , then shorting the unused input to ground will keep the offset low (about 2.5 mV at the input, 50 mV at the output). For dc source resistances between these values we can eliminate excess offset by putting a resistor from the unused input to ground, equal in value to the dc source resistance. Of course all offset problems are eliminated if the input is capacitively coupled.

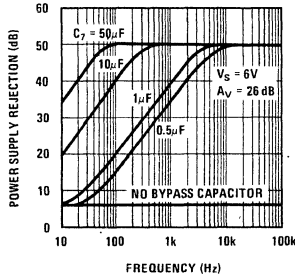
When using the LM386 with higher gains (bypassing the 1.35 k Ω resistor between pins 1 and 8) it is necessary to bypass the unused input, preventing degradation of gain and possible instabilities. This is done with a 0.1 μ F capacitor or a short to ground depending on the dc source resistance on the driven input.

Typical Performance Characteristics

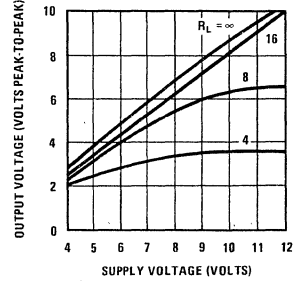
Quiescent Supply Current vs Supply Voltage



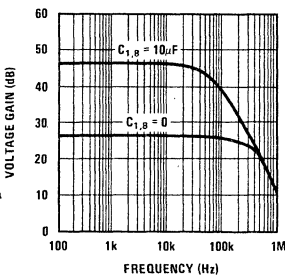
Power Supply Rejection Ratio (Referred to the Output) vs Frequency



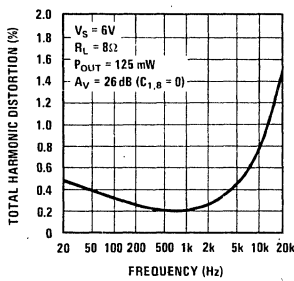
Peak-to-Peak Output Voltage Swing vs Supply Voltage



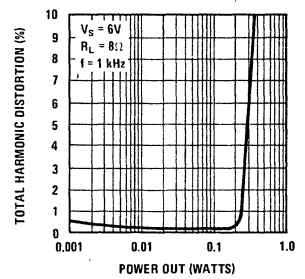
Voltage Gain vs Frequency



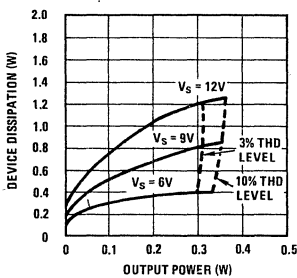
Distortion vs Frequency



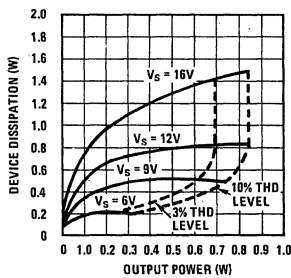
Distortion vs Output Power



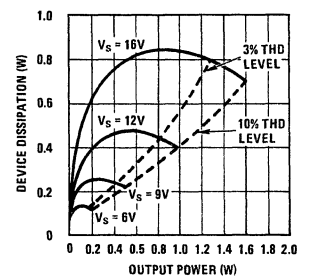
Device Dissipation vs Output Power—4Ω Load



Device Dissipation vs Output Power—8Ω Load

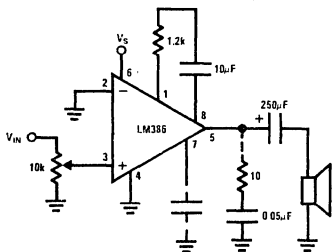


Device Dissipation vs Output Power—16Ω Load

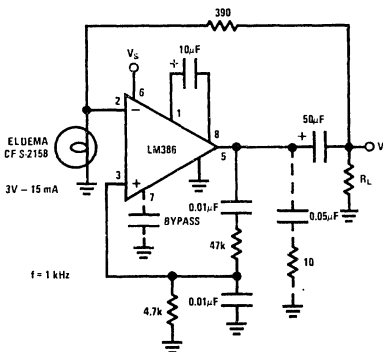


Typical Applications (Continued)

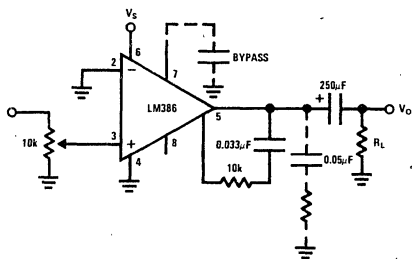
Amplifier with Gain = 50



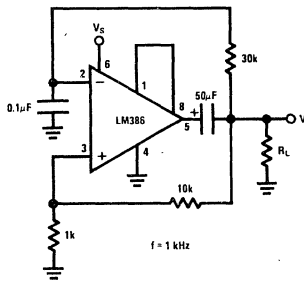
Low Distortion Power Wienbridge Oscillator



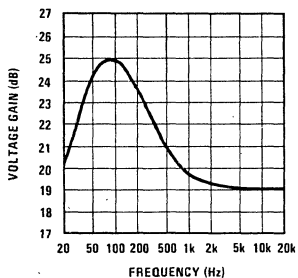
Amplifier with Bass Boost



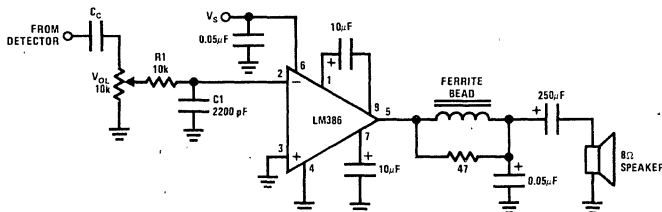
Square Wave Oscillator



Frequency Response with Bass Boost



AM Radio Power Amplifier



Note 1: Twist supply lead and supply ground very tightly.

Note 2: Twist speaker lead and ground very tightly.

Note 3: Ferrite bead is Ferroxcube K5-001-001/3B with 3 turns of wire.

Note 4: R1C1 band limits input signals.

Note 5: All components must be spaced very close to IC.



LM387/LM387A Low Noise Dual Preampifier

General Description

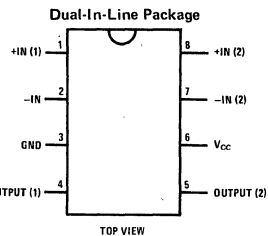
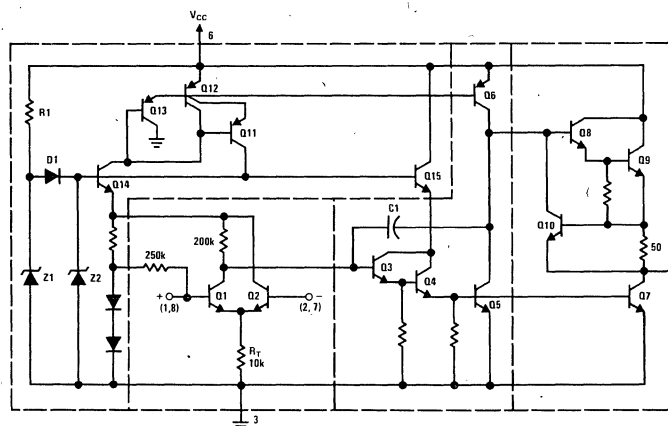
The LM387 is a dual preamplifier for the amplification of low level signals in applications requiring optimum noise performance. Each of the two amplifiers is completely independent, with an internal power supply decoupler-regulator, providing 110 dB supply rejection and 60 dB channel separation. Other outstanding features include high gain (104 dB), large output voltage swing ($V_{CC} - 2V$)p-p, and wide power bandwidth (75 kHz, 20 Vp-p). The LM387A is a selected version of the LM387 that has lower noise and can operate on a larger supply voltage. The LM387 operates from a single supply across the wide range of 9V to 30V, the LM387A operates on a supply of 9V to 40V.

The amplifiers are internally compensated for gains greater than 10. The LM387, LM387A is available in an 8-lead dual-in-line package. The LM387, LM387A is biased like the LM381. See AN-64 and AN-104.

Features

- Low noise LM387 0.8 μ V total input noise
LM387A 0.65 μ V total input noise
- High gain 104 dB open loop
- Single supply operation
- Wide supply range LM387 9 to 30V
LM387A 9 to 40V
- Power supply rejection 110 dB
- Large output voltage swing ($V_{CC} - 2V$)p-p
- Wide bandwidth 15 MHz unity gain
- Power bandwidth 75 kHz, 20 Vp-p
- Internally compensated
- Short circuit protected
- Performance similar to LM381

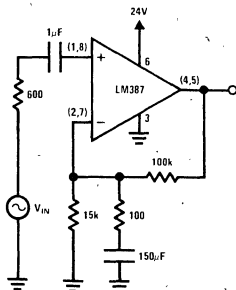
Schematic and Connection Diagrams



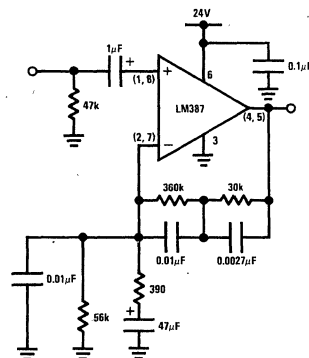
Order Number LM387N
or LM387AN
See NS Package N08B

Typical Applications

Flat Gain Circuit ($A_V = 1000$)



Typical Magnetic Phono Preamplifier



Absolute Maximum Ratings

Supply Voltage

LM387

+30V

LM387A

+40V

Power Dissipation (Note 1)

660 mW

Operating Temperature Range

0°C to +70°C

Storage Temperature Range

-65°C to +150°C

Lead Temperature (Soldering, 10 seconds)

300°C

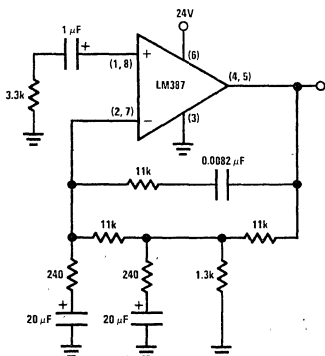
Electrical Characteristics $T_A = 25^\circ\text{C}$, $V_{CC} = 14\text{V}$, unless otherwise stated.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|--|--|-----|------------|-----|------------------|----------------|
| Voltage Gain | Open Loop, $f = 100\text{ Hz}$ | | 160,000 | | V/V | |
| Supply Current | LM387, $V_{CC} 9\text{--}30\text{V}$, $R_L = \infty$ | | 10 | | mA | |
| | LM387A, $V_{CC} 9\text{--}40\text{V}$, $R_L = \infty$ | | 10 | | mA | |
| Input Resistance | | 50 | 100 | | k Ω | |
| | | | 200 | | k Ω | |
| Input Current | | | 0.5 | 3.1 | μA | |
| | | | | | | Negative Input |
| Output Resistance | Open Loop | | 150 | | Ω | |
| Output Current | Source | | 8 | | mA | |
| | Sink | | 2 | | mA | |
| Output Voltage Swing | Peak-to-Peak | | $V_{CC}-2$ | | V | |
| Unity Gain Bandwidth | | | 15 | | MHz | |
| Large Signal Frequency Response | 20 Vp-p ($V_{CC} > 24\text{V}$), THD $\leq 1\%$ | | 75 | | kHz | |
| Maximum Input Voltage | Linear Operation | | | 300 | mVrms | |
| Supply Rejection Ratio | $f = 1\text{ kHz}$ | | 110 | | dB | |
| | | | | | | Input Referred |
| Channel Separation | $f = 1\text{ kHz}$ | 40 | 60 | | dB | |
| Total Harmonic Distortion | 60 dB Gain, $f = 1\text{ kHz}$ | | 0.1 | 0.5 | % | |
| Total Equivalent Input Noise (Flat Gain Circuit) | 10–10,000 Hz | | 0.8 | 1.2 | μVrms | |
| | | | | | | LM387 |
| | | | | | | LM387A |
| Output Noise NAB Tape Playback Circuit | 10–10,000 Hz | | 230 | | μVrms | |
| | | | | | | LM387A |

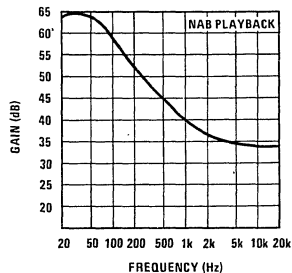
Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 187°C/W junction to ambient.

Typical Applications (Continued)

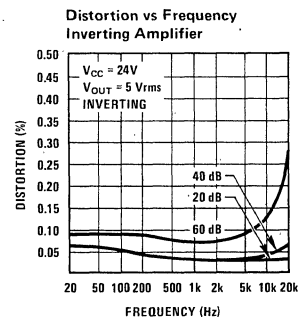
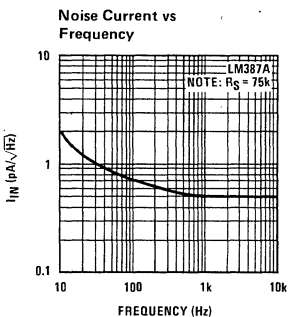
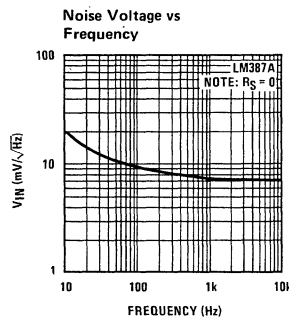
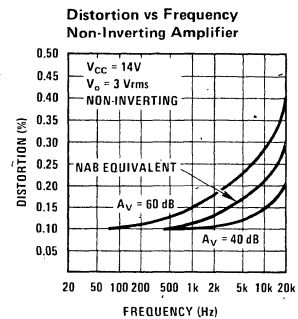
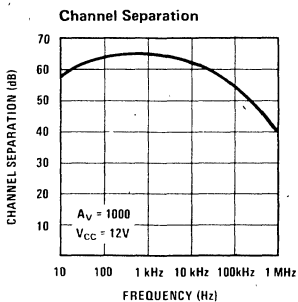
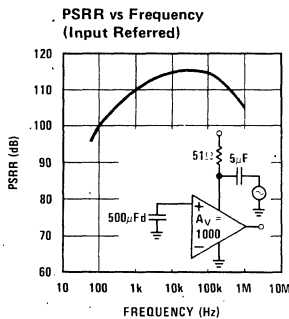
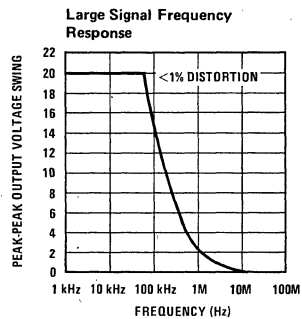
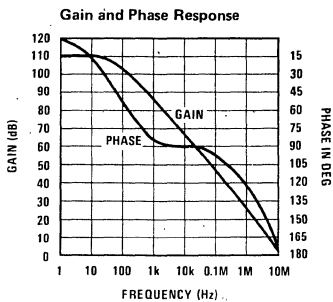
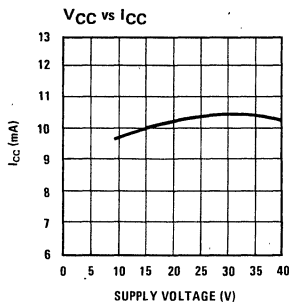
Two-Pole Fast Turn-ON NAB Tape Preamplifier



Frequency Response of NAB Circuit

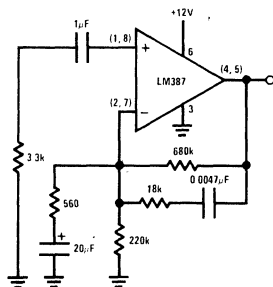


Typical Performance Characteristics

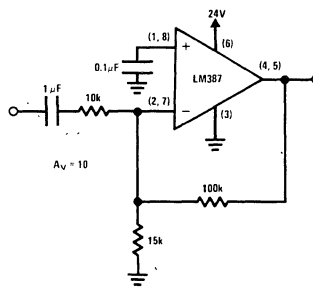


Typical Applications (Continued)

NAB Tape Circuit



Inverting Amplifier Ultra-Low Distortion



LM388 1.5 Watt Audio Power Amplifier

General Description

The LM388 is an audio amplifier designed for use in medium power consumer applications. The gain is internally set to 20 to keep external part count low, but the addition of an external resistor and capacitor between pins 2 and 6 will increase the gain to any value up to 200.

The inputs are ground referenced while the output is automatically biased to one half the supply voltage.

Features

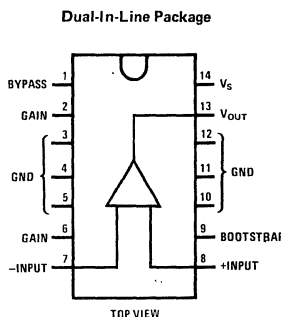
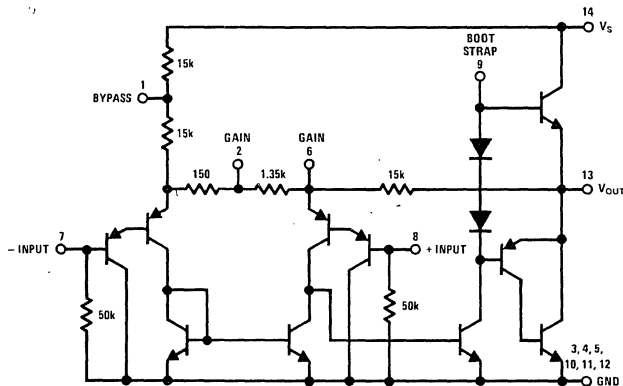
- Minimum external parts
- Wide supply voltage range
- Excellent supply rejection
- Ground referenced input
- Self-centering output quiescent voltage

- Variable voltage gain
- Low distortion
- Fourteen pin dual-in-line package
- Low voltage operation, 4V

Applications

- AM-FM radio amplifiers
- Portable tape player amplifiers
- Intercoms
- TV sound systems
- Lamp drivers
- Line drivers
- Ultrasonic drivers
- Small servo drivers
- Power converters

Equivalent Schematic and Connection Diagram



Order Number LM388N-1,
LM388N-2 or LM388N-3
See NS Package N14A

Typical Applications

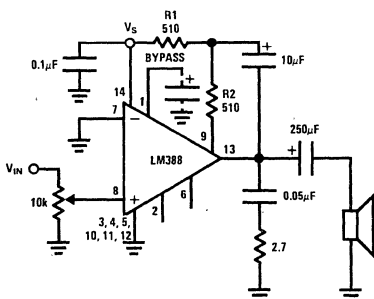


FIGURE 1. Load Returned to Ground
(Amplifier with Gain = 20)

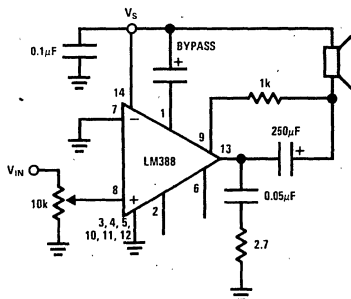


FIGURE 2. Load Returned to V_S
(Amplifier with Gain = 20)

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 15V |
| Supply Voltage (LM388N-3 Only) | 22V |
| Package Dissipation 14-Pin DIP (Note 1) | 8.3W |
| Input Voltage | ±0.4V |
| Storage Temperature | -65°C to +150°C |
| Operating Temperature | 0°C to +70°C |
| Junction Temperature | 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, (Figure 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|-----|-----|------------|
| Operating Supply Voltage (V_S) | | | | | |
| LM388 | | 4 | | 12 | V |
| LM388N-3 | | 5 | | 18 | V |
| Quiescent Current (I_Q) | $V_{IN} = 0$ | | | | |
| LM388 | $V_S = 12\text{V}$ | | 16 | 23 | mA |
| LM388N-3 | $V_S = 16\text{V}$ | | 20 | 35 | mA |
| Output Power (P_{OUT}), (Note 2) | $R_1 = R_2 = 180\Omega$, THD = 10% | | | | |
| LM388N-1 | $V_S = 12\text{V}$, $R_L = 8\Omega$ | 1.5 | 2.2 | | W |
| LM388N-2 | $V_S = 6\text{V}$, $R_L = 4\Omega$ | 0.6 | 0.8 | | W |
| LM388N-3 | $V_S = 6\text{V}$, $R_L = 4\Omega$ | 0.8 | 0.9 | | W |
| | $V_S = 16\text{V}$, $R_L = 8\Omega$ | 2.5 | 3.8 | | W |
| Voltage Gain (A_V) | $V_S = 12\text{V}$, $f = 1\text{ kHz}$ | 23 | 26 | 30 | dB |
| | 10 μF From Pin 2 to 6 | | 46 | | dB |
| Bandwidth (BW) | $V_S = 12\text{V}$, Pins 2 and 6 Open | | 300 | | kHz |
| Total Harmonic Distortion (THD) | $V_S = 12\text{V}$, $R_L = 8\Omega$, $P_{OUT} = 500\text{ mW}$, $f = 1\text{ kHz}$, Pins 2 and 6 Open | | 0.1 | 1 | % |
| Power Supply Rejection Ratio (PSRR), (Note 3) | $V_S = 12\text{V}$, $f = 1\text{ kHz}$, $C_{BYPASS} = 10\mu\text{F}$, Pins 2 and 6 Open, Referred to Output | | 50 | | dB |
| Input Resistance (R_{IN}) | | 10 | 50 | | k Ω |
| Input Bias Current (I_{BIAS}) | $V_S = 12\text{V}$, Pins 7 and 8 Open | | 250 | | nA |

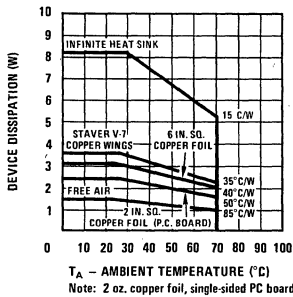
Note 1: Pins 3, 4, 5, 10, 11, 12 at 25°C. Derate at 15°C/W above 25°C case.

Note 2: The amplifier should be in high gain for full swing on higher supplies due to input voltage limitations.

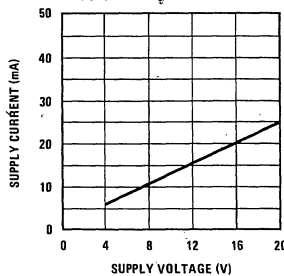
Note 3: If load and bypass capacitor are returned to V_S (Figure 2), rather than ground (Figure 1), PSRR is typically 30 dB.

Typical Performance Characteristics

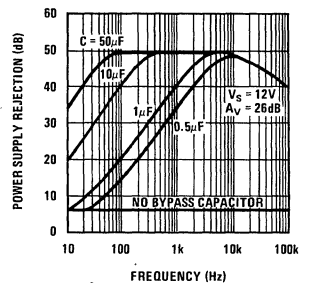
Maximum Device Dissipation vs Ambient Temperature



Quiescent Supply Current vs Supply Voltage

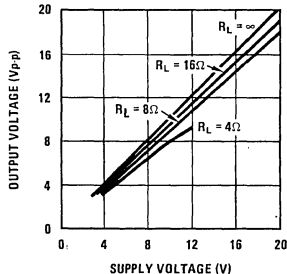


Power Supply Rejection Ratio (Referred to the Output) vs Frequency

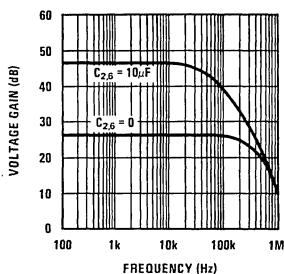


Typical Performance Characteristics (Continued)

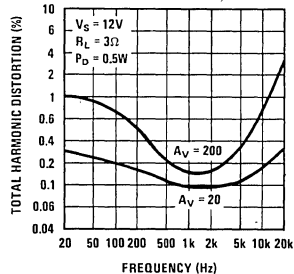
Peak-to-Peak Output Voltage Swing vs Supply Voltage



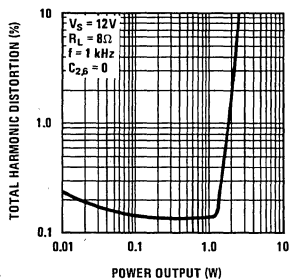
Voltage Gain vs Frequency



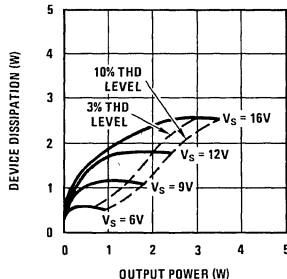
Distortion vs Frequency



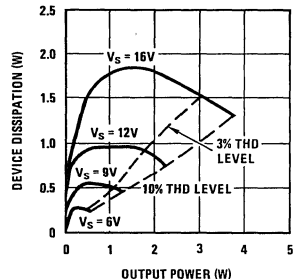
Distortion vs Output Power



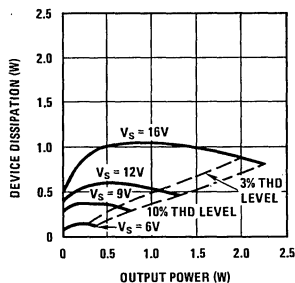
Device Dissipation vs Output Power—4Ω Load



Device Dissipation vs Output Power—8Ω Load



Device Dissipation vs Output Power—16Ω Load



Application Hints

Gain Control

To make the LM388 a more versatile amplifier, two pins (2 and 6) are provided for gain control. With pins 2 and 6 open, the 1.35 k Ω resistor sets the gain at 20 (26 dB). If a capacitor is put from pin 2 to 6, bypassing the 1.35 k Ω resistor, the gain will go up to 200 (46 dB). If a resistor is placed in series with the capacitor, the gain can be set to any value from 20 to 200. A low frequency pole in the gain response is caused by the capacitor working against the external resistor in series with the 150 Ω internal resistor. If the capacitor is eliminated and a resistor connects pin 2 to 6 then the output dc level

may shift due to the additional dc gain. Gain control can also be done by capacitively coupling a resistor (or FET) from pin 6 to ground, as in *Figure 7*.

Additional external components can be placed in parallel with the internal feedback resistors to tailor the gain and frequency response for individual applications. For example, we can compensate poor speaker bass response by frequency shaping the feedback path. This is done with a series RC from pin 6 to 13 (paralleling the internal 15 k Ω resistor). For 6 dB effective bass boost: $R \approx$

Application Hints (Continued)

15 kΩ, the lowest value for good stable operation is R = 10 kΩ if pin 2 is open. If pins 2 and 6 are bypassed then R as low as 2 kΩ can be used. This restriction is because the amplifier is only compensated for closed-loop gains greater than 9 V/V.

Input Biasing

The schematic shows that both inputs are biased to ground with a 50 kΩ resistor. The base current of the input transistors is about 250 nA, so the inputs are at about 12.5 mV when left open. If the dc source resistance driving the LM388 is higher than 250 kΩ it will contribute very little additional offset (about 2.5 mV at the input, 50 mV at the output). If the dc source resistance is less than 10 kΩ, then shorting the unused input to ground will keep the offset low (about 2.5 mV at the input, 50 mV at the output). For dc source resistances between these values we can eliminate excess offset by putting a resistor from the unused input to ground, equal in value to the dc source resistance. Of course all offset problems are eliminated if the input is capacitively coupled.

When using the LM388 with higher gains (bypassing the 1.35 kΩ resistor between pins 2 and 6) it is necessary to bypass the unused input, preventing degradation of gain and possible instabilities. This is done with a 0.1 μF capacitor or a short to ground depending on the dc source resistance on the driven input.

Bootstrapping

The base of the output transistor of the LM388 is brought out to pin 9 for Bootstrapping. The output stage of the amplifier during positive swing is shown in Figure 3 with its external circuitry.

R1 + R2 set the amount of base current available to the output transistor. The maximum output current divided by Beta is the value required for the current in R1 and R2:

$$(R1 + R2) = \beta_O \frac{(V_S/2) - V_{BE}}{I_{O\ MAX}}$$

Good design values are $V_{BE} = 0.7V$ and $\beta_O = 100$.

Example: 1 WATT into 8Ω load with $V_S = 12V$.

$$I_{O\ MAX} = \sqrt{\frac{2 P_O}{R_L}} = 500\ mA$$

$$(R1 + R2) = 100 \left(\frac{(12/2) - 0.7}{0.5} \right) = 1060\ \Omega$$

To keep the current in R2 constant during positive swing capacitor C_B is added. As the output swings positive C_B lifts R1 and R2 above the supply, maintaining a constant voltage across R2. To minimize the value of C_B , $R1 = R2$. The pole due to C_B and R1 and R2 is usually set equal to the pole due to the output coupling capacitor and the load. This gives:

$$C_B \approx \frac{4C_c}{\beta_O} \approx \frac{C_c}{25}$$

Example: for 100 Hz pole and $R_L = 8\ \Omega$; $C_c = 200\ \mu F$ and $C_B = 8\ \mu F$, if R1 is made a diode and R2 increased to give the same current, C_B can be decreased by about a factor of 4, as in Figure 4.

For reduced component count the load can replace R1. The value of (R1 + R2) is the same, so R2 is increased. Now C_B is both the coupling and the bootstrapping capacitor (see Figure 2).

Typical Applications (Continued)

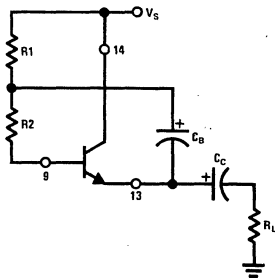


FIGURE 3.

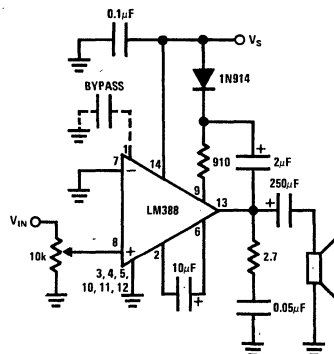
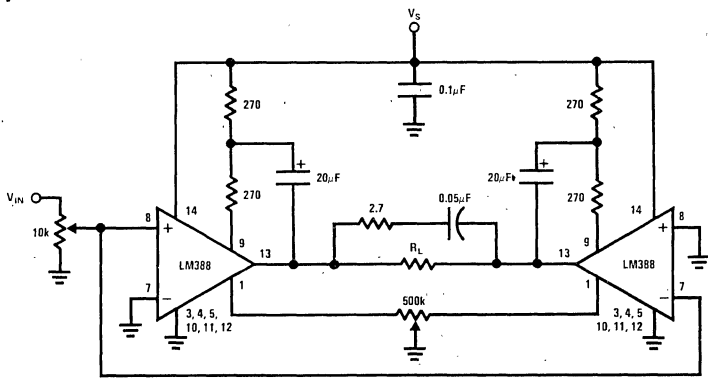


FIGURE 4. Amplifier with Gain = 200 and Minimum C_B

Typical Applications (Continued)



$V_{CC} = 6V \quad R_L = 4\Omega \quad P_O = 1.0W$
 $V_{CC} = 12V \quad R_L = 8\Omega \quad P_O = 4W$

FIGURE 5. Bridge Amp

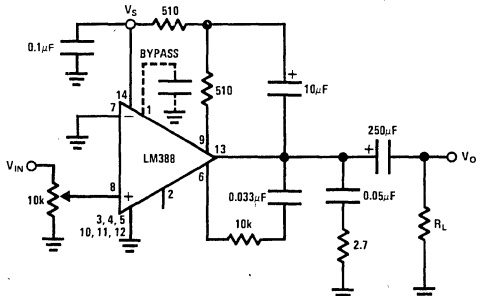


FIGURE 6a. Amplifier with Bass Boost

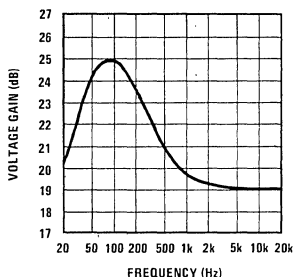


FIGURE 6b. Frequency Response with Bass Boost

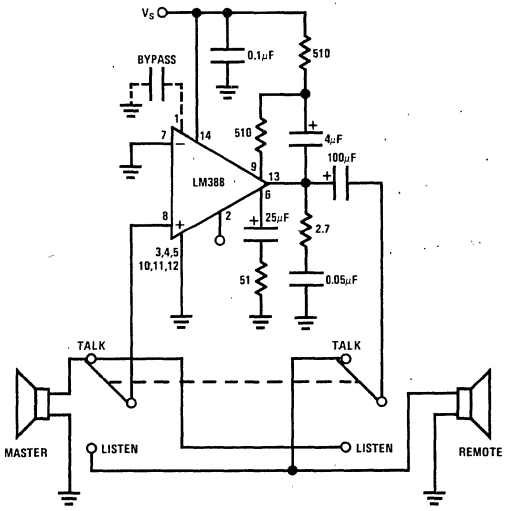


FIGURE 7. Intercom

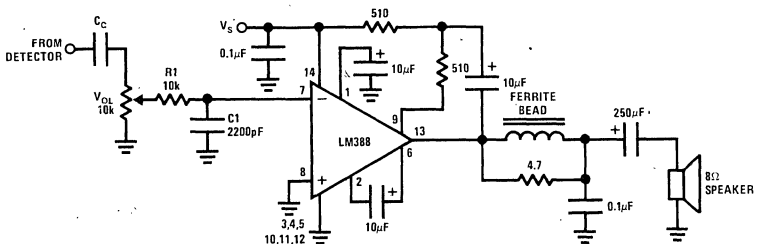


FIGURE 8. AM Radio Power Amplifier

Note 1: Twist supply lead and supply ground very tightly.

Note 2: Twist speaker lead and ground very tightly.

Note 3: Ferrite bead is Ferroxcube K5-001-001/3B with 3 turns of wire.

Note 4: R1C1 band limits input signals.

Note 5: All components must be spaced very close to IC.



LM389 Low Voltage Audio Power Amplifier With NPN Transistor Array

General Description

The LM389 is an array of three NPN transistors on the same substrate with an audio power amplifier similar to the LM386.

The amplifier inputs are ground referenced while the output is automatically biased to one half the supply voltage. The gain is internally set at 20 to minimize external parts, but the addition of an external resistor and capacitor between pins 4 and 12 will increase the gain to any value up to 200.

The three transistors have high gain and excellent matching characteristics. They are well suited to a wide variety of applications in dc through VHF systems.

- Low quiescent current drain
- Voltage gains from 20 to 200
- Ground referenced input
- Self-centering output quiescent voltage
- Low distortion

Transistors

- Operation from 1 μ A to 25 mA
- Frequency range from dc to 100 MHz
- Excellent matching

Features

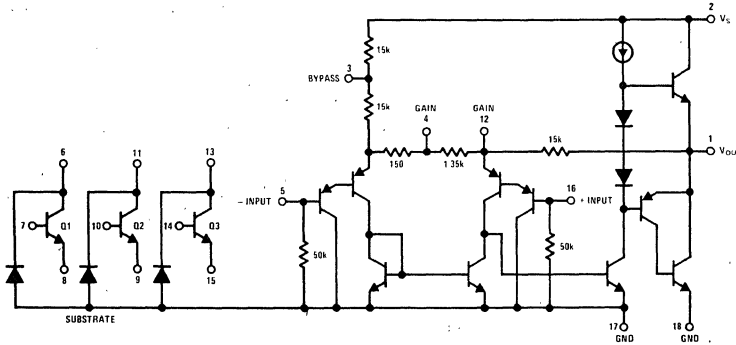
Amplifier

- Battery operation
- Minimum external parts
- Wide supply voltage range

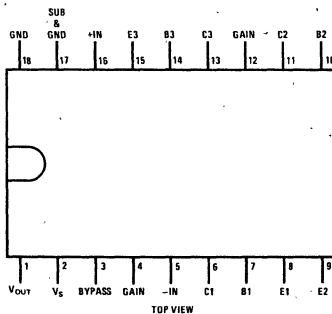
Applications

- AM-FM radios
- Portable tape recorders
- Intercoms
- Toys and games
- Walkie-talkies
- Portable phonographs
- Power converters

Equivalent Schematic and Connection Diagrams



Dual-In-Line Package



Order Number LM389N
See NS Package N18A

Absolute Maximum Ratings

| | | | |
|--|-----------------------------------|---|--------|
| Supply Voltage | 15V | Collector to Emitter Voltage, V_{CE0} | 12V |
| Package Dissipation (Note 1) | 715 mW | Collector to Base Voltage, V_{CB0} | 15V |
| Input Voltage | $\pm 0.4V$ | Collector to Substrate Voltage, V_{C10} (Note 2) | 15V |
| Storage Temperature | $-65^{\circ}C$ to $+150^{\circ}C$ | Collector Current, I_C | 25 mA |
| Operating Temperature | $0^{\circ}C$ to $+70^{\circ}C$ | Emitter Current, I_E | 25 mA |
| Junction Temperature | $150^{\circ}C$ | Base Current, I_B | 5 mA |
| Lead Temperature (Soldering, 10 seconds) | $300^{\circ}C$ | Power Dissipation (Each Transistor) $T_A \leq +70^{\circ}C$ | 150 mW |

Electrical Characteristics $T_A = 25^{\circ}C$

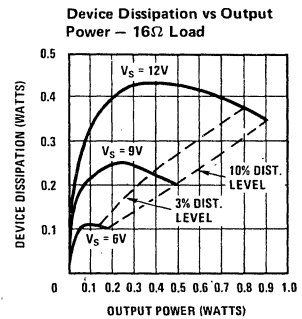
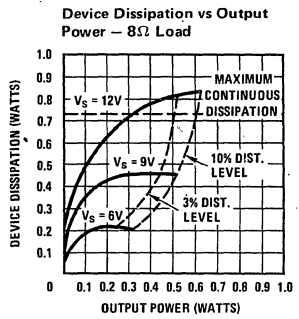
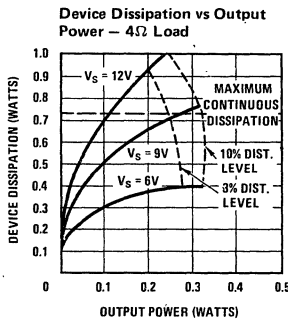
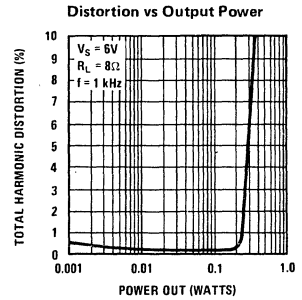
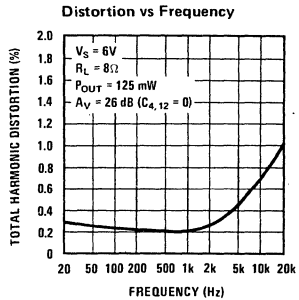
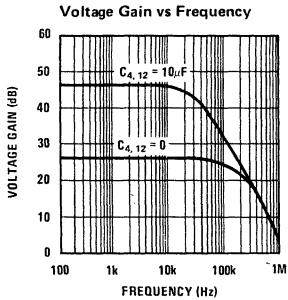
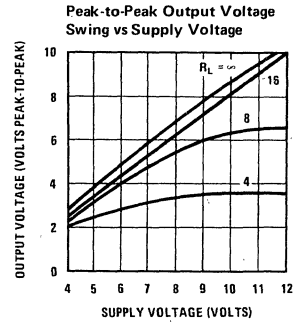
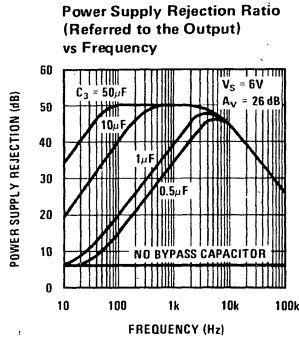
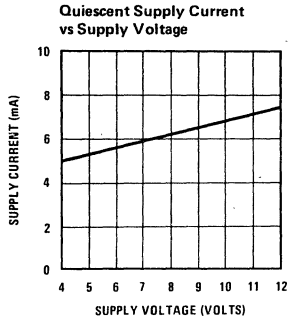
| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------------|---|---|-----|------------|------|------------|
| AMPLIFIER | | | | | | |
| V_S | Operating Supply Voltage | | 4 | | 12 | V |
| I_Q | Quiescent Current | $V_S = 6V, V_{IN} = 0V$ | | 6 | 12 | mA |
| P_{OUT} | Output Power (Note 3) | THD = 10% $V_S = 6V, R_L = 8\Omega$ $V_S = 9V, R_L = 16\Omega$ | 250 | 325 500 | | mW mW |
| A_V | Voltage Gain | $V_S = 6V, f = 1\text{ kHz}$ 10 μ F From Pins 4 to 12 | 23 | 26 46 | 30 | dB dB |
| BW | Bandwidth | $V_S = 6V$, Pins 4 and 12 Open | | 250 | | kHz |
| THD | Total Harmonic Distortion | $V_S = 6V, R_L = 8\Omega, P_{OUT} = 125\text{ mW}$, $f = 1\text{ kHz}$, Pins 4 and 12 Open | | 0.2 | 3.0 | % |
| PSRR | Power Supply Rejection Ratio | $V_S = 6V, f = 1\text{ kHz}, C_{BYPASS} = 10\mu F$, Pins 4 and 12 Open, Referred to Output | 30 | 50 | | dB |
| R_{IN} | Input Resistance | | 10 | 50 | | k Ω |
| I_{BIAS} | Input Bias Current | $V_S = 6V$, Pins 5 and 16 Open | | 250 | | nA |
| TRANSISTORS | | | | | | |
| V_{CE0} | Collector to Emitter Breakdown Voltage | $I_C = 1\text{ mA}, I_B = 0$ | 12 | 20 | | V |
| V_{CB0} | Collector to Base Breakdown Voltage | $I_C = 10\mu A, I_E = 0$ | 15 | 40 | | V |
| V_{C10} | Collector to Substrate Breakdown Voltage | $I_C = 10\mu A, I_E = I_B = 0$ | 15 | 40 | | V |
| V_{EBO} | Emitter to Base Breakdown Voltage | $I_E = 10\mu A, I_C = 0$ | 6.4 | 7.1 | 7.8 | V |
| H_{FE} | Static Forward Current Transfer Ratio (Static Beta) | $I_C = 10\mu A$ $I_C = 1\text{ mA}$ $I_C = 10\text{ mA}$ | 100 | 275 275 | | |
| h_{oe} | Open-Circuit Output Admittance | $I_C = 1\text{ mA}, V_{CE} = 5V, f = 1.0\text{ kHz}$ | | 20 | | μ mho |
| V_{BE} | Base to Emitter Voltage | $I_E = 1\text{ mA}$ | | 0.7 | 0.85 | V |
| $ V_{BE1} - V_{BE2} $ | Base to Emitter Voltage Offset | $I_E = 1\text{ mA}$ | | 1 | 5 | mV |
| V_{CESAT} | Collector to Emitter Saturation Voltage | $I_C = 10\text{ mA}, I_B = 1\text{ mA}$ | | 0.15 | 0.5 | V |
| C_{EB} | Emitter to Base Capacitance | $V_{EB} = 3V$ | | 1.5 | | pF |
| C_{CB} | Collector to Base Capacitance | $V_{CB} = 3V$ | | 2 | | pF |
| C_{C1} | Collector to Substrate Capacitance | $V_{C1} = 3V$ | | 3.5 | | pF |
| h_{fe} | High Frequency Current Gain | $I_C = 10\text{ mA}, V_{CE} = 5V, f = 100\text{ MHz}$ | 1.5 | 5.5 | | |

Note 1: For operation in ambient temperatures above $25^{\circ}C$, the device must be derated based on a $150^{\circ}C$ maximum junction temperature and a thermal resistance of $175^{\circ}C/W$ junction to ambient.

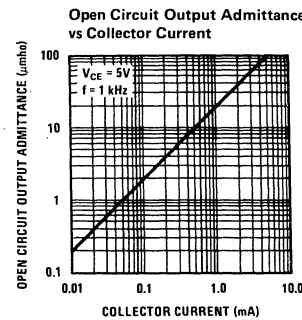
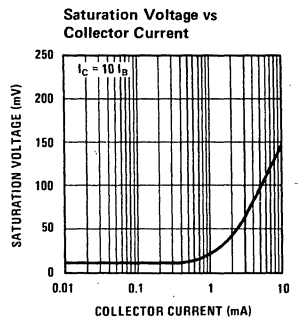
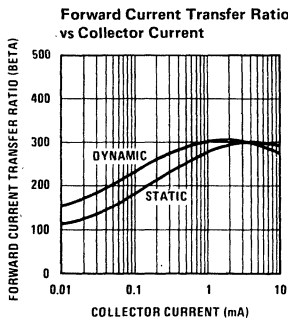
Note 2: The collector of each transistor is isolated from the substrate by an integral diode. Therefore, the collector voltage should remain positive with respect to pin 17 at all times.

Note 3: If oscillation exists under some load conditions, add 2.7 Ω and 0.05 μF series network from pin 1 to ground.

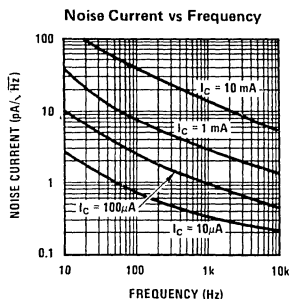
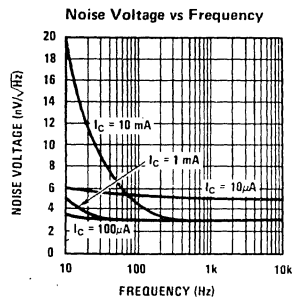
Typical Amplifier Performance Characteristics



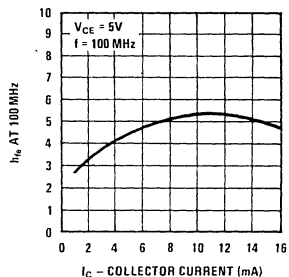
Typical Transistor Performance Characteristics



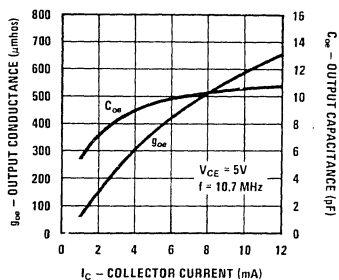
Typical Transistor Performance Characteristics (Continued)



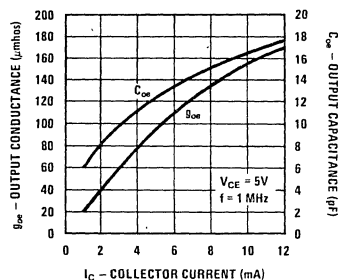
High Frequency Current Gain vs Collector Current



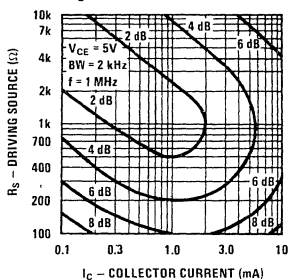
g_{oe} and C_{oe} vs Collector Current



g_{oe} and C_{oe} vs Collector Current



Contours of Constant Noise Figure



Application Hints

Gain Control

To make the LM389 a more versatile amplifier, two pins (4 and 12) are provided for gain control. With pins 4 and 12 open, the 1.35 k Ω resistor sets the gain at 20 (26 dB). If a capacitor is put from pin 4 to 12, bypassing the 1.35 k Ω resistor, the gain will go up to 200 (46 dB). If a resistor is placed in series with the capacitor, the gain can be set to any value from 20 to 200. A low frequency pole in the gain response is caused by the capacitor working against the external resistor in series with the 150 Ω internal resistor. If the capacitor is eliminated and a resistor connects pin 4 to 12, then the output dc level may shift due to the additional dc gain. Gain control can also be done by capacitively coupling a resistor (or FET) from pin 12 to ground.

Additional external components can be placed in parallel with the internal feedback resistors to tailor the gain and frequency response for individual applications. For example, we can compensate poor speaker bass response by frequency shaping the feedback path. This is done with a series RC from pin 1 to 12 (paralleling the internal 15 k Ω resistor). For 6 dB effective bass boost: $R \approx 15 \text{ k}\Omega$, the lowest value for good stable operation is $R = 10 \text{ k}\Omega$ if pin 4 is open. If pins 4 and 12 are bypassed then R as low as 2 k Ω can be used. This restriction is because the amplifier is only compensated for closed-loop gains greater than 9V/V.

Input Biasing

The schematic shows that both inputs are biased to ground with a 50 k Ω resistor. The base current of the input transistors is about 250 nA, so the inputs are at about 12.5 mV when left open. If the dc source resis-

tance driving the LM389 is higher than 250 k Ω it will contribute very little additional offset (about 2.5 mV at the input, 50 mV at the output). If the dc source resistance is less than 10 k Ω , then shorting the unused input to ground will keep the offset low (about 2.5 mV at the input, 50 mV at the output). For dc source resistances between these values we can eliminate excess offset by putting a resistor from the unused input to ground, equal in value to the dc source resistance. Of course all offset problems are eliminated if the input is capacitively coupled.

When using the LM389 with higher gains (bypassing the 1.35 k Ω resistor between pins 4 and 12) it is necessary to bypass the unused input, preventing degradation of gain and possible instabilities. This is done with a 0.1 μF capacitor or a short to ground depending on the dc source resistance of the driven input.

Supplies and Grounds

The LM389 has excellent supply rejection and does not require a well regulated supply. However, to eliminate possible high frequency stability problems, the supply should be decoupled to ground with a 0.1 μF capacitor. The high current ground of the output transistor, pin 18, is brought out separately from small signal ground, pin 17. If the two ground leads are returned separately to supply then the parasitic resistance in the power ground lead will not cause stability problems. The parasitic resistance in the signal ground can cause stability problems and it should be minimized. Care should also be taken to insure that the power dissipation does not

Application Hints (Continued)

exceed the maximum dissipation of the package for a given temperature. There are two ways to mute the LM389 amplifier. Shorting pin 3 to the supply voltage, or shorting pin 12 to ground will turn the amplifier off without affecting the input signal.

Transistors

The three transistors on the LM389 are general purpose devices that can be used the same as other small signal transistors. As long as the currents and voltages are kept within the absolute maximum limitations, and the collectors are never at a negative potential with respect to pin 17, there is no limit on the way they can be used.

For example, the emitter-base breakdown voltage of 7.1V can be used as a zener diode at currents from $1\mu\text{A}$ to 5 mA. These transistors make good LED driver devices, V_{SAT} is only 150 mV when sinking 10 mA.

In the linear region, these transistors have been used in AM and FM radios, tape recorders, phonographs, and many other applications. Using the characteristic curves on noise voltage and noise current, the level of the collector current can be set to optimize noise performance for a given source impedance. Some of the circuits that have been built are shown in Figures 1-7. This is by no means a complete list of applications, since that is limited only by the designers imagination.

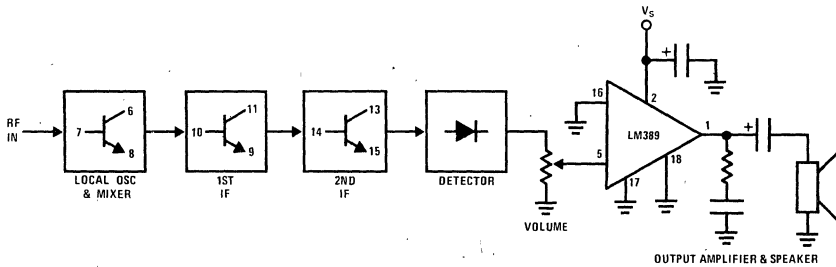


FIGURE 1. AM Radio

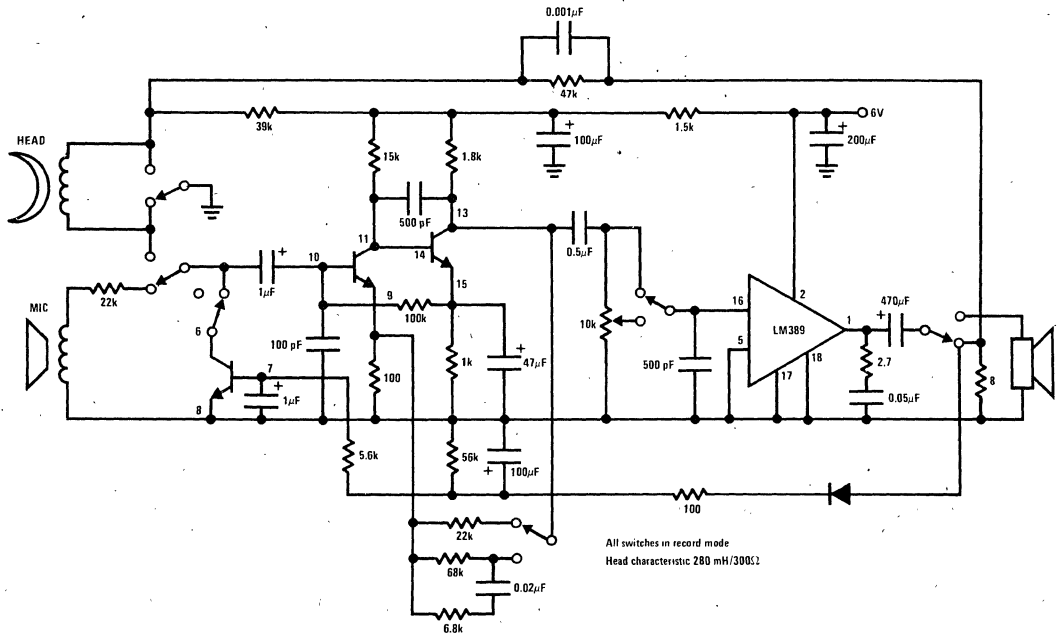


FIGURE 2. Tape Recorder

Application Hints (Continued)

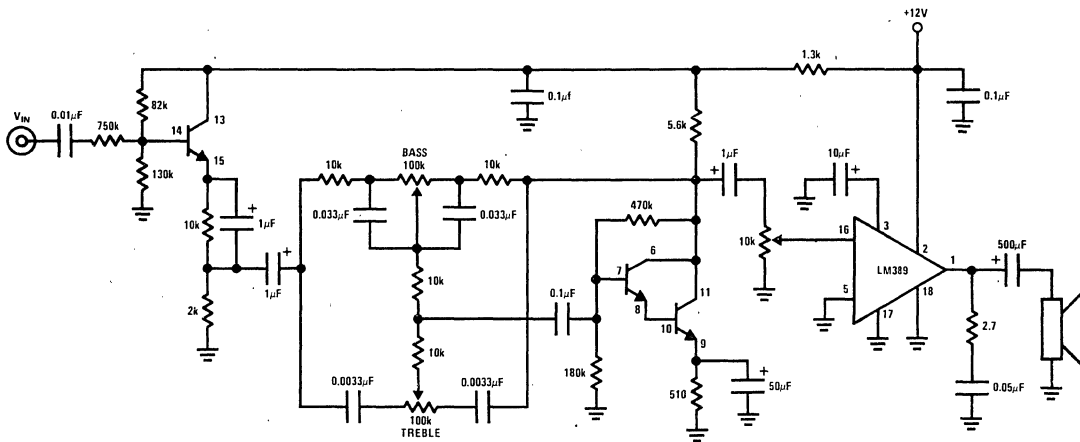


FIGURE 3. Ceramic Phono Amplifier with Tone Controls

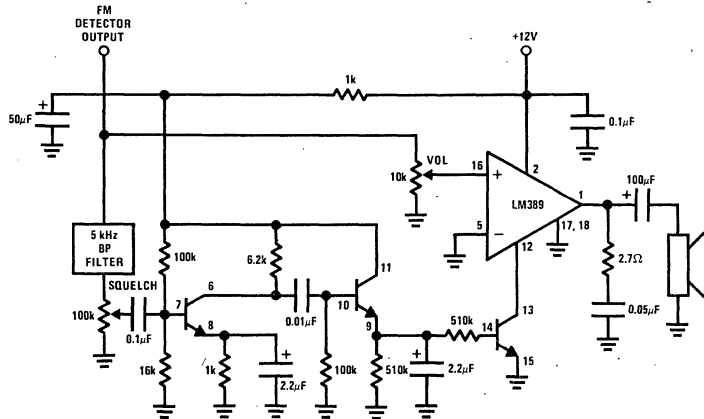


FIGURE 4. FM Scanner Noise Squelch Circuit

Application Hints (Continued)

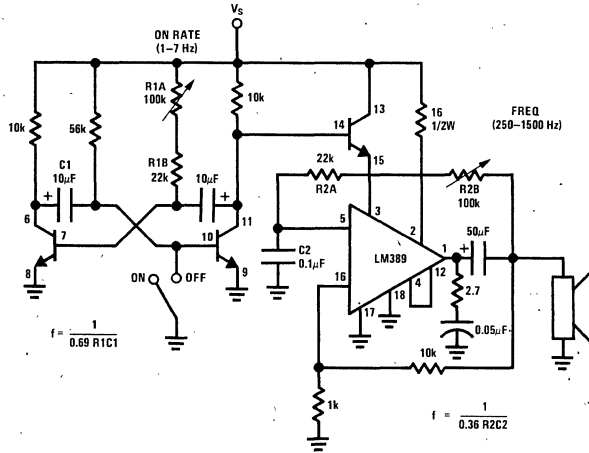


FIGURE 5. Siren

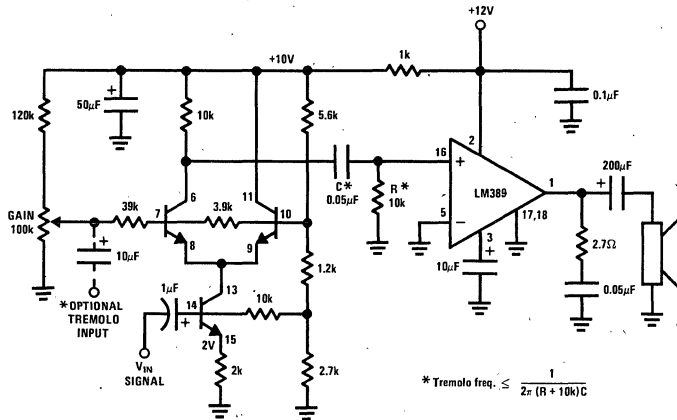


FIGURE 6. Voltage-Controlled Amplifier or Tremolo Circuit

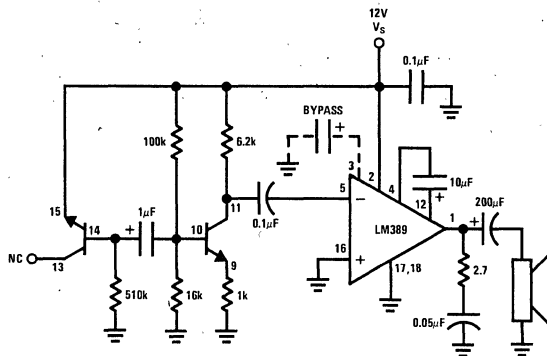


FIGURE 7. Noise Generator Using Zener Diode

LM390 1 Watt Battery Operated Audio Power Amplifier

General Description

The LM390 Power Audio Amplifier is optimized for 6V, 7.5V, 9V operation into low impedance loads. The gain is internally set at 20 to keep the external part count low, but the addition of an external resistor and capacitor between pins 2 and 6 will increase the gain to any value up to 200. The inputs are ground referenced while the output is automatically biased to one half the supply voltage.

Features

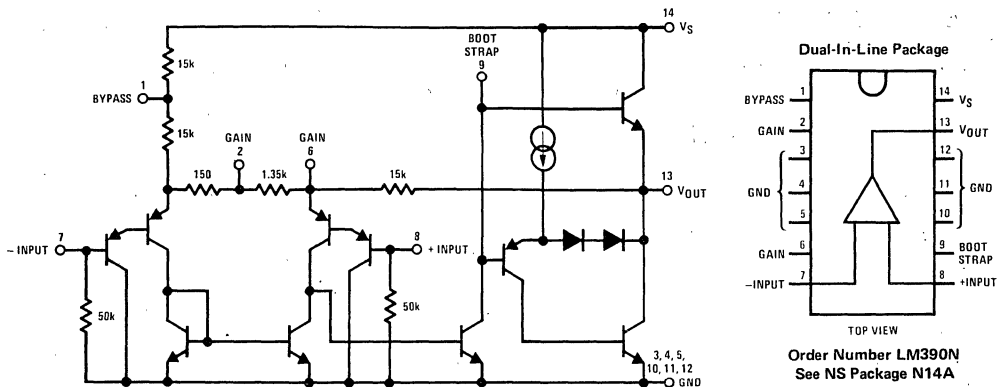
- Battery operation
- 1W output power
- Minimum external parts
- Excellent supply rejection
- Ground referenced input
- Self-centering output quiescent voltage

- Variable voltage gain
- Low distortion
- Fourteen pin dual-in-line package

Applications

- AM-FM radio amplifiers
- Portable tape player amplifiers
- Intercoms
- TV sound systems
- Lamp drivers
- Line drivers
- Ultrasonic drivers
- Small servo drivers
- Power converters

Equivalent Schematic and Connection Diagrams



Typical Applications

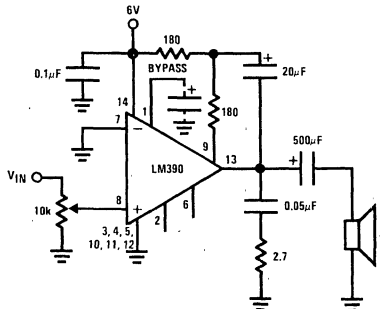


FIGURE 1. Load Returned to Ground
(Amplifier with Gain = 20)

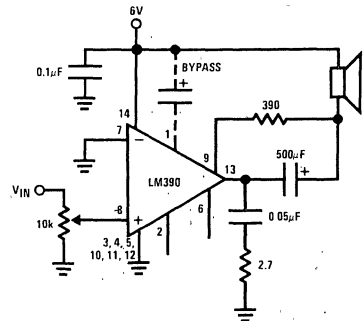


FIGURE 2. Load Returned to Supply
(Amplifier with Gain = 20)

Absolute Maximum Ratings (Note 1)

| | |
|--|-----------------|
| Supply Voltage | 10V |
| Package Dissipation 14-Pin DIP | 8.3W |
| Input Voltage | ±0.4V |
| Storage Temperature | -65°C to +150°C |
| Operating Temperature | 0°C to +70°C |
| Junction Temperature | 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, (Figure 1)

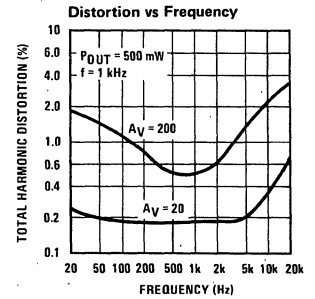
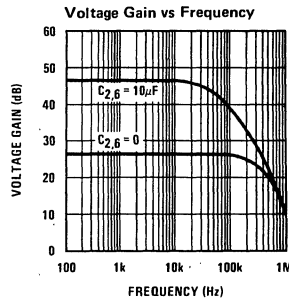
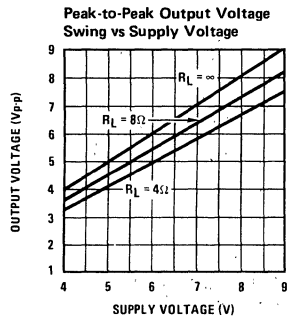
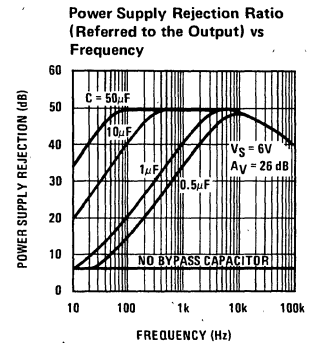
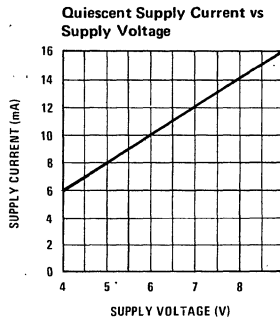
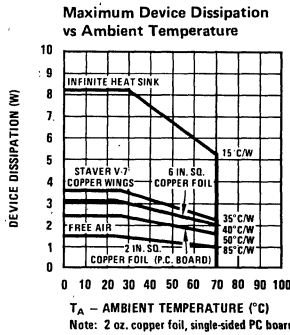
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|------------|------------------------------|--|-----|-----|-------|------------|
| V_S | Operating Supply Voltage | 4 | | 9 | V | |
| I_Q | Quiescent Current | $V_S = 6\text{V}, V_{IN} = 0$ | 10 | 20 | mA | |
| P_{OUT} | Output Power | $V_S = 6\text{V}, R_L = 4\Omega, \text{THD} = 10\%$, (Note 2) | 0.8 | 1.0 | W | |
| A_V | Voltage Gain | $V_S = 6\text{V}, f = 1\text{ kHz}$ $10\mu\text{F}$ from Pin 2 to 6 | 23 | 26 | 30 | dB |
| BW | Bandwidth | $V_S = 6\text{V}$, Pins 2 and 6 Open | | 46 | | dB |
| THD | Total Harmonic Distortion | $V_S = 6\text{V}, R_L = 4\Omega, P_{OUT} = 500\text{ mW}$ $f = 1\text{ kHz}$, Pins 2 and 6 Open | | 300 | | kHz |
| PSRR | Power Supply Rejection Ratio | $V_S = 6\text{V}, f = 1\text{ kHz}, C_{BYPASS} = 10\mu\text{F}$, Pins 2 and 6 Open, Referred to Output (Note 3) | 0.2 | 1 | | % |
| R_{IN} | Input Resistance | | 10 | 50 | | k Ω |
| I_{BIAS} | Input Bias Current | $V_S = 6\text{V}$, Pins 7 and 8 Open | | 250 | | nA |

Note 1: Pins 3, 4, 5, 10, 11, 12 at 25°C. Derate at 15°C/W above 25°C case.

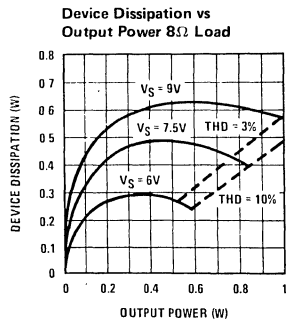
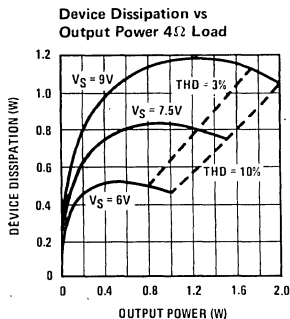
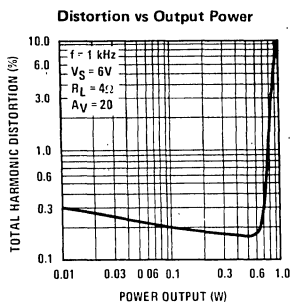
Note 2: If oscillation exists under some load conditions, add 2.7 Ω and 0.05 μF series network from pin 13 to ground.

Note 3: If load and bypass capacitor are returned to V_S (Figure 2), rather than ground (Figure 1), PSRR is typically 30 dB.

Typical Performance Characteristics



Typical Performance Characteristics (Continued)



Application Hints

Gain Control

To make the LM390 a more versatile amplifier, two pins (2 and 6) are provided for gain control. With pins 2 and 6 open, the 1.35 kΩ resistor sets the gain at 20 (26 dB). If a capacitor is put from pin 2 to 6, bypassing the 1.35 kΩ resistor, the gain will go up to 200 (46 dB). If a resistor is placed in series with the capacitor, the gain can be set to any value from 20 to 200. A low frequency pole in the gain response is caused by the capacitor working against the external resistor in series with the 150Ω internal resistor. If the capacitor is eliminated and a resistor connects pin 2 to 6 then the output dc level may shift due to the additional dc gain. Gain control can also be done by capacitively coupling a resistor (or FET) from pin 6 to ground, as in *Figure 7*.

Additional external components can be placed in parallel with the internal feedback resistors to tailor the gain and frequency response for individual applications. For example, we can compensate poor speaker bass response by frequency shaping the feedback path. This is done with a series RC from pin 6 to 13 (paralleling the internal 15 kΩ resistor). For 6 dB effective bass boost: $R \cong 15 \text{ k}\Omega$, the lowest value for good stable operation is $R = 10 \text{ k}\Omega$ if pin 2 is open. If pins 2 and 6 are bypassed then R as low as 2 kΩ can be used. This restriction is because the amplifier is only compensated for closed-loop gains greater than 9 V/V.

Typical Applications (Continued)

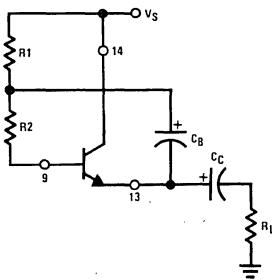


FIGURE 3.

Input Biasing

The schematic shows that both inputs are biased to ground with a 50 kΩ resistor. The base current of the input transistors is about 250 nA, so the inputs are at about 12.5 mV when left open. If the dc source resistance driving the LM390 is higher than 250 kΩ it will contribute very little additional offset (about 2.5 mV at the input, 50 mV at the output). If the dc source resistance is less than 10 kΩ, then shorting the unused input to ground will keep the offset low (about 2.5 mV at the input, 50 mV at the output). For dc source resistances between these values we can eliminate excess offset by putting a resistor from the unused input to ground, equal in value to the dc source resistance. Of course all offset problems are eliminated if the input is capacitively coupled.

When using the LM390 with higher gains (bypassing the 1.35 kΩ resistor between pins 2 and 6) it is necessary to bypass the unused input, preventing degradation of gain and possible instabilities. This is done with a 0.1μF capacitor or a short to ground depending on the dc source resistance on the driven input.

Bootstrapping

The base of the output transistor of the LM390 is brought out to pin 9 for Bootstrapping. The output stage of the amplifier during positive swing is shown in *Figure 3* with its external circuitry.

Application Hints (Continued)

R1 + R2 set the amount of base current available to the output transistor. The maximum output current divided by Beta is the value required for the current in R1 and R2:

$$(R1 + R2) = \beta_O \frac{(V_S/2) - V_{BE}}{I_{O\ MAX}}$$

Good design values are $V_{BE} = 0.7V$ and $\beta_O = 100$.

Example 0.8WATT into 4Ω load with $V_S = 6V$.

$$I_{O\ MAX} = \sqrt{\frac{2 P_O}{R_L}} = 632\ \text{mA}$$

$$(R1 + R2) = 100 \left(\frac{(6/2) - 0.7}{0.632} \right) = 364\ \Omega$$

To keep the current in R2 constant during positive swing capacitor C_B is added. As the output swings positive C_B lifts R1 and R2 above the supply, maintaining a constant voltage across R2. To minimize the value of C_B , $R1 = R2$. The pole due to C_B and R1 and R2 is usually set equal to the pole due to the output coupling capacitor and the load. This gives:

$$C_B \approx \frac{4C_c}{\beta_O} \approx \frac{C_c}{25}$$

Example: for 100 Hz pole and $R_L = 4\Omega$; $C_c = 400\mu F$ and $C_B = 16\mu F$, if R1 is made a diode and R2 increased to give the same current, C_B can be decreased by about a factor of 4, as in Figure 4.

For reduced component count the load can replace R1. The value of (R1 + R2) is the same, so R2 is increased. Now C_B is both the coupling and the bootstrapping capacitor (see Figure 2).

Typical Applications (Continued)

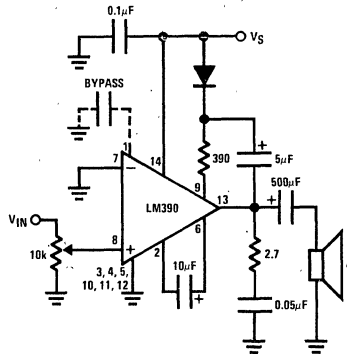


FIGURE 4. Amplifier with Gain = 200 and Minimum C_B

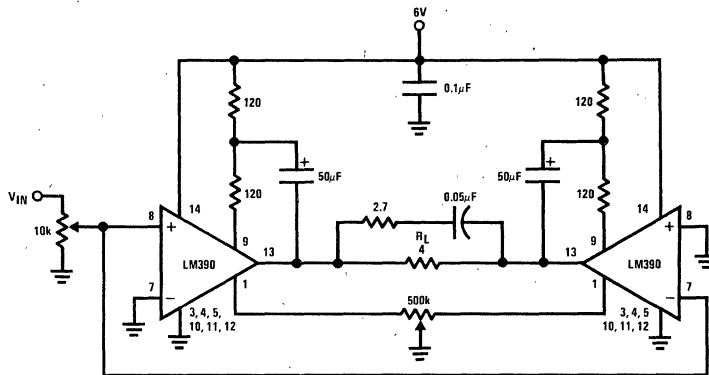


FIGURE 5. 2.5W Bridge Amplifier

Typical Applications (Continued)

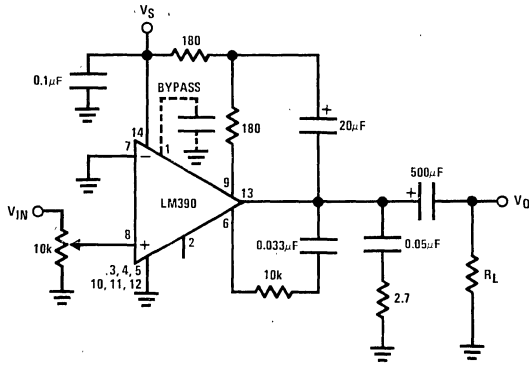


FIGURE 6(a). Amplifier with Bass Boost

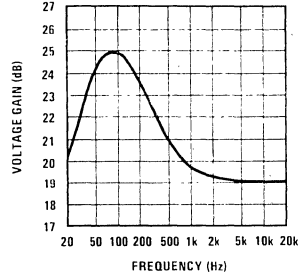


FIGURE 6(b). Frequency Response with Bass Boost

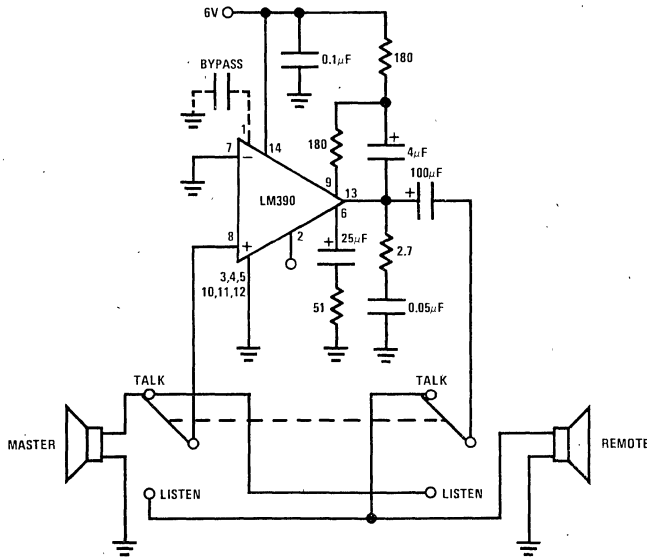


FIGURE 7. Intercom

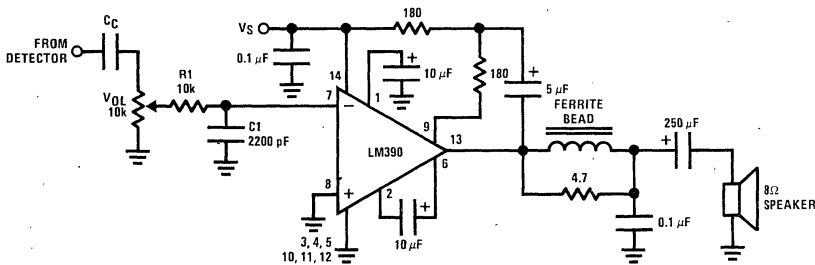


FIGURE 8. AM Radio Power Amplifier

Note 1: Twist supply lead and supply ground very tightly.

Note 2: Twist speaker lead and ground very tightly.

Note 3: Ferrite bead is Ferroxcube K5-001-001/3B with 3 turns of wire.

Note 4: R1C1 band limits input signals.

Note 5: All components must be spaced very close to IC.

LM391 Audio Power Driver

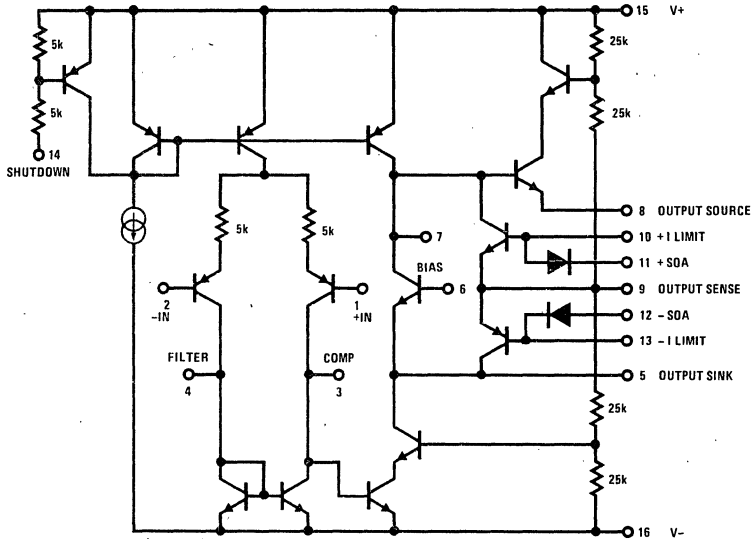
General Description

The LM391 audio power driver is designed to drive external power transistors in 10 to 100 watt power amplifier designs. High power supply voltage operation and true high fidelity performance distinguish this IC. The LM391 is internally protected for output faults and thermal overloads; circuitry providing output transistor protection is user programmable.

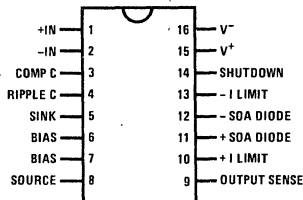
Features

- High Supply Voltage $\pm 30, \pm 40, \text{ or } \pm 50\text{V max}$
- Low Distortion **0.01%**
- Low Input Noise **$3\mu\text{V}$**
- High Supply Rejection **90dB**
- Gain and Bandwidth Selectable
- Dual Slope SOA Protection
- Shutdown Pin

Equivalent Schematic and Connection Diagram



Dual-In-Line Package



Top View

Order Number LM391N-60, LM391N-80
 LM391N-100
 See NS Package N16A

Absolute Maximum Ratings

| | | | |
|----------------|-------------------------|--|-----------------|
| Supply Voltage | | Shutdown Current (Pin 14) | 1 mA |
| LM391N - 60 | ± 30 V or +60 V | Package Dissipation (Note 1) | 1.39 W |
| LM391N - 80 | ± 40 V or +80 V | Storage Temperature | -65°C to +150°C |
| LM391N - 100 | ± 50 V or +100 V | Operating Temperature | 0°C to +70°C |
| Input Voltage | Supply Voltage less 5 V | Lead Temperature (Soldering, 10 seconds) | +300°C |

Electrical Characteristics

$T_A = 25^\circ\text{C}$ (The following are for $V^+ = 90\% V_{MAX}^+$ and $V^- = 90\% V_{MAX}^-$.)

| Parameter | Conditions | Min | Typ | Max | Units |
|-------------------------------------|-------------------|-----------|-----------|------|---------------|
| Quiescent Current | current in pin 15 | | | | |
| LM391N - 60 | $V_{IN} = 0$ | | 3 | 10 | mA |
| LM391N - 80 | | | 4 | 8 | mA |
| LM391N - 100 | | | 5 | 6 | mA |
| Output Swing | positive | $V^+ - 7$ | $V^+ - 5$ | | V |
| | negative | $V^- + 7$ | $V^- + 5$ | | V |
| Drive Current | source (pin 8) | 5 | | | mA |
| | sink (pin 5) | 5 | | | mA |
| Noise (20 - 20 kHz) | input referred | | 3 | | μV |
| Supply Rejection | input referred | 70 | 90 | | dB |
| Total Harmonic Distortion | $f = 1$ kHz | | 0.01 | | % |
| | $f = 20$ kHz | | 0.10 | 0.25 | % |
| Intermodulation Distortion | 60 Hz, 7 kHz, 4:1 | | 0.01 | | % |
| Open Loop Gain | $f = 1$ kHz | 1000 | 5500 | | V/V |
| Input Bias Current | | | 0.1 | 1.0 | μA |
| Input Offset Voltage | | | 5 | 20 | mV |
| Positive Current Limit V_{BE} | pin 10 - 9 | | 650 | | mV |
| Negative Current Limit V_{BE} | pin 9 - 13 | | 650 | | mV |
| Positive Current Limit Bias Current | pin 10 | | 10 | 100 | μA |
| Negative Current Limit Bias Current | pin 13 | | 10 | 100 | μA |

Pin 14 Current Comments

Minimum pin 14 current required for shutdown is 0.5 mA, and must not exceed 1 mA.

Maximum pin 14 current for amplifier not shut down is 0.05 mA.

The typical shutdown switch point current is 0.2 mA.

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

Typical Applications

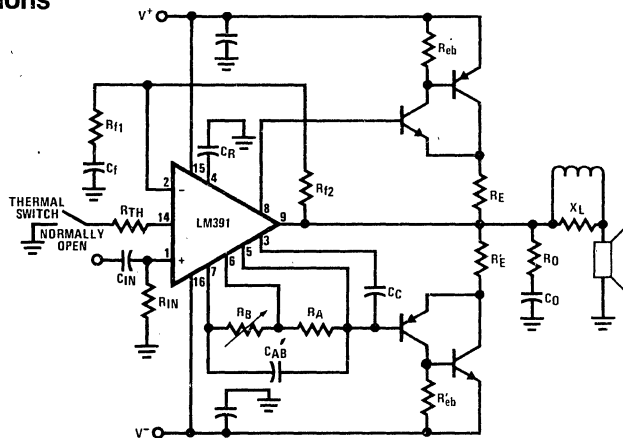
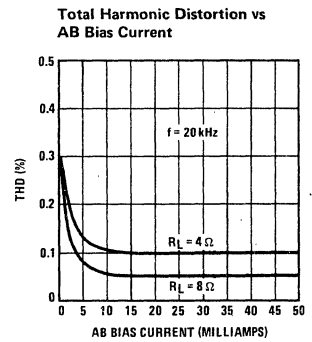
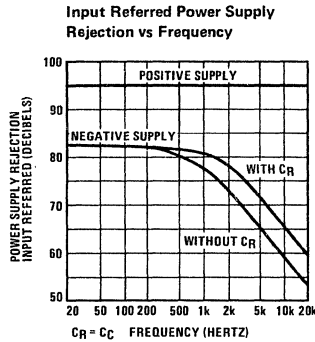
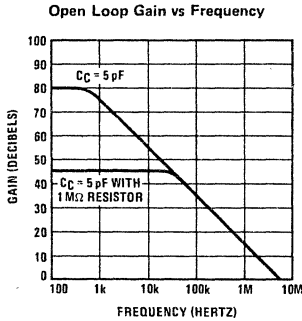
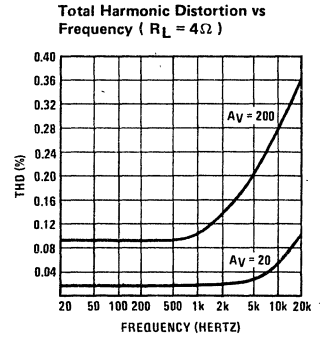
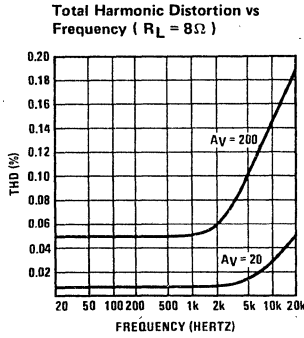
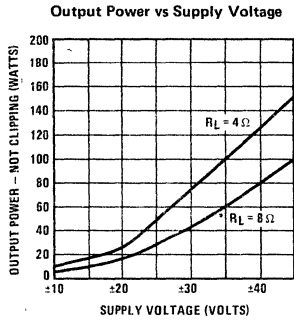


Figure 1. LM391 with External Components - Protection Circuitry Not Shown

Typical Performance Characteristics



Pin Descriptions

| Pin No. | Pin Name | Comments |
|---------|-----------------|---|
| 1 | + Input | Audio input |
| 2 | - Input | Feedback input |
| 3 | Compensation | Sets the dominant pole |
| 4 | Ripple Filter | Improves negative supply rejection |
| 5 | Sink Output | Drives output devices and is emitter of AB bias V_{BE} multiplier |
| 6 | BIAS | Base of V_{BE} multiplier |
| 7 | BIAS | Collector of V_{BE} multiplier |
| 8 | Source Output | Drives output devices |
| 9 | Output Sense | Biases the IC and is used in protection circuits |
| 10 | + Current Limit | Base of positive side protection circuit transistor |
| 11 | + SOA Diode | Diode used for dual slope SOA protection |
| 12 | - SOA Diode | Diode used for dual slope SOA protection |
| 13 | - Current Limit | Base of negative side protection circuit transistor |
| 14 | Shutdown | Shuts off amplifier when current is pulled out of pin |
| 15 | V^+ | Positive supply |
| 16 | V^- | Negative supply |

External Components (figure 1)

| Component | Typical Value | Comments |
|-------------|--------------------------|--|
| C_{IN} | 1 μ F | Input coupling capacitor sets a low frequency pole with R_{IN} . $f_L = \frac{1}{2\pi R_{IN} C_{IN}}$ |
| R_{IN} | 100k | Sets input impedance and DC bias to input. |
| R_{f2} | 100k | Feedback resistor; for minimum offset voltage at the output this should be equal to R_{IN} . |
| R_{f1} | 5.1k | Feedback resistor that works with R_{f2} to set the voltage gain. $A_V = 1 + \frac{R_{f2}}{R_{f1}}$ |
| C_f | 10 μ F | Feedback capacitor. This reduces the gain to unity at DC for minimum offset voltage at the output. Also sets a low frequency pole with R_{f1} . $f_L = \frac{1}{2\pi R_{f1} C_f}$ |
| C_C | 5 pF | Compensation capacitor. Sets gain bandwidth product and a high frequency pole. $GBW = \frac{1}{2\pi 5000 C_C}, f_h = \frac{GBW}{A_V}$ Max f_h for stable design \approx 500 kHz. |
| R_A | 3.9k | AB bias resistor. |
| R_B | 10k | AB bias potentiometer. Adjust to set bias current in the output stage. |
| C_{AB} | 0.1 μ F | Bypass capacitor for bias. This improves high frequency distortion and transient response. |
| C_R | 5 pF | Ripple capacitor. This improves negative supply rejection at midband and high frequencies. C_R , if used, must equal C_C . |
| R_{eb} | 100 Ω | Bleed resistor. This removes stored charge in output transistors. |
| R_O | 2.7 Ω | Output compensation resistor. This resistor and C_O compensate the output stage. This value will vary slightly for different output devices. |
| C_O | 0.1 μ F | Output compensation capacitor. This works with R_O to form a zero that cancels f_β of the output power transistors. |
| R_E | 0.3 Ω | Emitter degeneration resistor. This resistor gives thermal stability to the output stage quiescent current. IRC PW5 type. |
| R_{TH} | 39k | Shutdown resistor. Sets the amount of current pulled out of pin 14 during shutdown. |
| C_2, C_2' | 1000 pF | Compensation capacitors for protection circuitry. |
| X_L | 10 Ω 5 μ H | Used to isolate capacitive loads, usually 20 turns of wire wrapped around a 10 Ω , 2W resistor. |

Application Hints

GENERALIZED AUDIO POWER AMP DESIGN

Givens: Power Output
Load Impedance
Input Sensitivity
Input Impedance
Bandwidth

The power output and load impedance determine the power supply requirements. Output signal swing and current are found from:

$$V_{O\text{peak}} = \sqrt{2 R_L P_O} \quad (1)$$

$$I_{O\text{peak}} = \sqrt{\frac{2 P_O}{R_L}} \quad (2)$$

Add 5 volts to the peak output swing (V_{OP}) for transistor voltage to get the supplies, i.e., $\pm(V_{OP} + 5V)$ at a current of I_{peak} . The regulation of the supply determines the unloaded voltage, usually about 15% higher. Supply voltage will also rise 10% during high line conditions.

$$\text{max supplies} \approx \pm(V_{O\text{peak}} + 5)(1 + \text{regulation})(1.1) \quad (3)$$

The input sensitivity and output power specs determine the required gain.

$$A_V \geq \frac{\sqrt{P_O R_L}}{V_{IN}} = \frac{V_{ORMS}}{V_{INRMS}} \quad (4)$$

Normally the gain is set between 20 and 200; for a 25 watt, 8 ohm amplifier this results in a sensitivity of 710 mV and 71 mV, respectively. The higher the gain, the higher the THD, as can be seen from the characteristics curves. Higher gain also results in more hum and noise at the output.

The desired input impedance is set by R_{IN} . Very high values can cause board layout problems and DC offsets at the output. The bandwidth requirements determine the size of C_f and C_C as indicated in the external component listing.

The output transistors and drivers must have a breakdown voltage greater than the voltage determined by equation (3). The current gain of the driver and output device must be high enough to supply $I_{O\text{peak}}$ with 5 mA of drive from the LM391. The power transistors must be able to dissipate approximately 40% of the maximum output power; the drivers must dissipate this amount divided by the current gain of the outputs. See the output transistor selection guide, table A.

To prevent thermal runaway of the AB bias current the following equation must be valid:

$$\theta_{JA} \leq \frac{R_E (\beta_{\text{MIN}} + 1)}{V_{CEQ\text{MAX}} (K)} \quad (5)$$

where:

θ_{JA} is the thermal resistance of the driver transistor, junction to ambient, in $^{\circ}\text{C}/\text{W}$.

R_E is the emitter degeneration resistance in ohms.

β_{min} is that of the output transistor.

$V_{CEQ\text{MAX}}$ is the highest possible value of one supply from equation (3).

K is the temperature coefficient of the driver base-emitter voltage, typically $2\text{mV}/^{\circ}\text{C}$.

Often the value of R_E is to be determined and equation (5) is rearranged to be:

$$R_E \geq \frac{\theta_{JA} (V_{CEQ\text{MAX}}) K}{\beta_{\text{MIN}} + 1} \quad (6)$$

The maximum average power dissipation in each output transistor is:

$$\overline{P}_{D\text{MAX}} = 0.4 P_{O\text{MAX}} \quad (7)$$

The power dissipation in the driver transistor is:

$$\overline{P}_{\text{DRIVER}(\text{MAX})} = \frac{\overline{P}_{D\text{MAX}}}{\beta_{\text{MIN}}} \quad (8)$$

Heat sink requirements are found using the following formulas:

$$\theta_{JA} \leq \frac{T_{J\text{MAX}} - T_{A\text{MAX}}}{P_D} \quad (9)$$

$$\theta_{SA} \leq \theta_{JA} - \theta_{JC} - \theta_{CS} \quad (10)$$

where:

$T_{J\text{MAX}}$ is maximum transistor junction temperature.

$T_{A\text{MAX}}$ is maximum ambient temperature.

θ_{JA} is thermal resistance junction to ambient.

θ_{SA} is thermal resistance sink to ambient.

θ_{JC} is thermal resistance junction to case.

θ_{CS} is thermal resistance case to sink, typically $1^{\circ}\text{C}/\text{W}$ for most mountings.

Application Hints (Continued)

PROTECTION CIRCUITRY

The protection circuits of the LM391 are very flexible and should be tailored to the output transistor's safe operating area. The protection V-I characteristics, circuitry, and resistor formulas are described below. The diodes from the output to each supply prevent the output voltage from exceeding the supplies and harming the output transistors. The output will do this if the protection circuitry is activated while driving an inductive load.

TURN-ON DELAY

It is often desirable to delay the turn-ON of the power amplifier so turn-ON pops in the preamplifier do not go to the speakers.

This is easily implemented by putting a resistor in series with a capacitor from pin 14 to ground. The value of

the resistor is set to limit the current to less than 1 mA (the absolute maximum). This resistor with the capacitor gives a time constant of RC. The turn-ON delay is approximately 2 time constants.

Example:

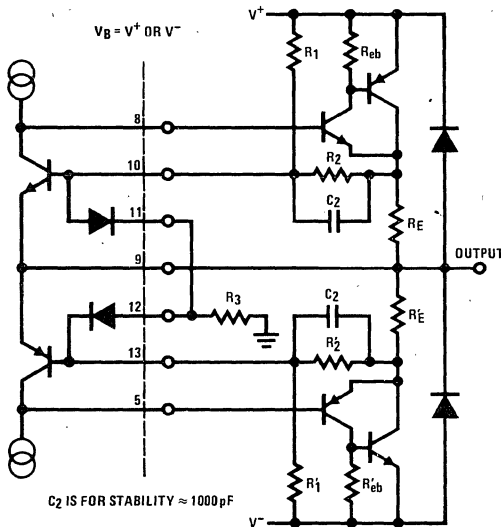
Amplifier with maximum supply of 30V, like the 20 W, 8Ω example in the data sheet, requiring a delay of 1 second.

$$\text{Time delay} = 2 RC$$

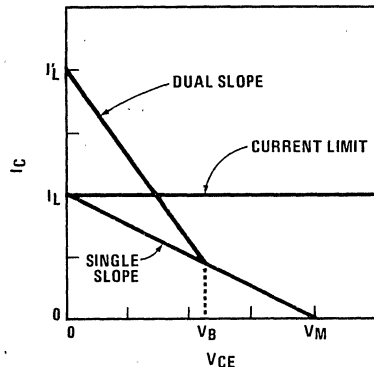
$$R = \frac{\text{Max } V^+}{1 \text{ mA}}$$

So:

R = 30k. Solving for C gives 16.7 μF. Use C = 20 μF with a 30V rating.



Protection Circuitry with External Components



Protection Characteristics

Protection Circuit Resistor Formulas ($V_B = V^+$)

| Type of Protection | $R_E, R_{E'}$ | R_1, R_1' | R_2, R_2' | R_3, R_3' |
|---|--------------------------|--|-------------|---|
| Current Limit | $R_E = \frac{\phi}{I_L}$ | Not Required | Short | Not Required |
| Single Slope SOA Protection | $R_E = \frac{\phi}{I_L}$ | $R_1 = R_2 \left(\frac{V_M - \phi}{\phi} \right)$ | 1 kΩ | Not Required |
| Dual Slope SOA Protection ($V_B = V^+$) | $R_E = \frac{\phi}{I_L}$ | $R_1 = R_2 \left(\frac{V_M - \phi}{\phi} \right)$ | 1 kΩ | $R_3 = R_2 \left[\frac{V^+}{I_L R_E - \phi} - 1 \right]$ |

Note: φ is the current limit V_{BE} voltage, 650 mV. Assumptions: $V^+ \gg \phi$, $V_M \gg \phi$. V^+ is the load supply voltage. V_M is the maximum rated V_{CE} of the output transistors.

Application Hints (Continued)

TRANSIENT INTERMODULATION DISTORTION

There has been a lot of interest in recent years about transient intermodulation distortion. Matti Ojala of University of Oulu, Oulu, Finland has published several papers on the subject. The results of these investigations show that the open loop pole of the power amplifier should be above 20 kHz.

To do this with the LM391 is easy. Put a $1\text{M}\Omega$ resistor from pin 3 to the output and the open loop gain is reduced to about 46 dB. Now the open loop pole is at 30 kHz. The current in this resistor causes an offset in the input stage that can be cancelled with a resistor from pin 4 to ground. The resistor from pin 4 to ground should be $910\text{k}\Omega$ rather than $1\text{M}\Omega$ to insure that the shutdown circuitry will operate correctly. The slight difference in resistors results in about 15 mV of offset. The 40W, 8Ω amplifier schematic shows the hookup of these two resistors.

BRIDGE AMPLIFIER

A switch can be added to convert a stereo amplifier to a single bridge amplifier. The diagram below shows where the switch and one resistor are added. When operating in the bridge mode the output load is connected between the two outputs, the input is $V_{IN \#1}$, and $V_{IN \#2}$ is disconnected.

OSCILLATIONS & GROUNDING

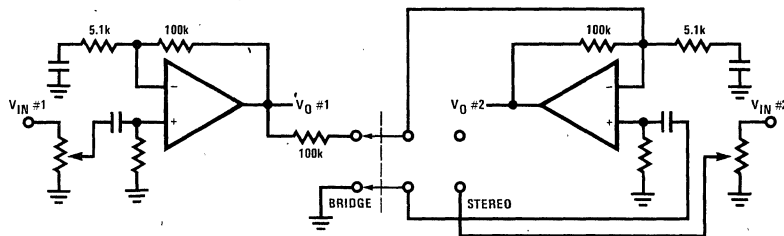
Most power amplifiers work the first time they are turned on. They also tend to oscillate and have excess THD. Most oscillation problems are due to inadequate supply bypassing and/or ground loops. A $10\mu\text{F}$, 50 V electrolytic on each power supply will stop supply-related oscillations. However, if the signal ground is used for these bypass caps the THD is usually excessive. The signal ground must return to the power supply alone, as must the output load ground. All other grounds — bypass, output R-C, protection, etc., can tie together and then return to supply. This ground is called high frequency ground. On the 40W amplifier schematic all the grounds are labeled.

Capacitive loads can cause instabilities, so they are isolated from the amplifier with an inductor and resistor in the output lead.

AB BIAS CURRENT

To reduce distortion in the output stage, all the transistors are biased ON slightly. This results in class AB operation and reduces the crossover (notch) distortion of the class B stage to a low level, (see the curve on page 10-70). The potentiometer, R_B , from pins 6–7 is adjusted to give about 25 mA of current in the output stage. This current is usually monitored at the supply or by measuring the voltage across R_E .

Typical Applications (Continued)



Bridge Circuit Diagram

Output Transistors Selection Guide

Table A.

| Output Power | Driver Transistor | | Output Transistor | |
|------------------------------------|-------------------|-------|-------------------|-------|
| | PNP | NPN | PNP | NPN |
| 20W @ 8Ω 30W @ 4Ω | BD344 | BD345 | BD346 | BD347 |
| 40W @ 8Ω 60W @ 4Ω | BD348 | BD349 | BD350 | BD351 |

Application Hints (Continued)

A 20 W, 8 Ω; 30 W, 4 Ω AMPLIFIER

Given:

| | |
|-------------------|--------------------------------|
| Power output | 20 W into 8 Ω 30 W into 4 Ω |
| Input Sensitivity | 1 V r _{max} |
| Input Impedance | 100k |
| Bandwidth | 20 Hz - 20 kHz ± 0.25 dB |

Equations (1) and (2) give:

$$\begin{aligned} 20\text{W}/8\Omega \quad V_{OP} &= 17.9\text{V} & I_{OP} &= 2.24\text{A} \\ 30\text{W}/4\Omega \quad V_{OP} &= 15.5\text{V} & I_{OP} &= 3.87\text{A} \end{aligned}$$

Therefore the supply required is:

$$\begin{aligned} \pm 23\text{V} @ 2.24\text{A}, \text{ reducing to } \dots \\ \pm 21\text{V} @ 3.87\text{A} \end{aligned}$$

With 15% regulation and high line we get ±29 V from equation (3).

Sensitivity and equation (4) set minimum gain:

$$A_V \geq \frac{\sqrt{20 \times 8}}{1} = 12.65$$

We will use a gain of 20 with resulting sensitivity of 632 mV.

Letting R_{IN} equal 100k gives the required input impedance. For low DC offsets at the output we let R_{f2} = 100k. Solving for R_{f1} gives:

$$R_{f2} = 100k$$

$$R_{f1} = \frac{100k}{20 - 1} = 5.26k; \text{ use } 5.1k$$

The bandwidth requirement must be stated as a pole, i.e., the 3dB frequency. Five times away from a pole gives 0.17 dB down, which is better than the required 0.25 dB. Therefore:

$$f_L = \frac{20}{5} = 4\text{ Hz}$$

$$f_H = 20k \times 5 = 100\text{ kHz}$$

Solving for C_f:

$$C_f \geq \frac{1}{2\pi R_{f1} f_L} = 7.8\ \mu\text{F}; \text{ use } 10\ \mu\text{F}$$

The recommended value for C_C is 5 pF for gains of 20 or larger. This gives a gain-bandwidth product of 6.4 MHz and a resulting bandwidth of 320 kHz, better than required.

The breakdown voltage requirement is set by the maximum supply; we need a minimum of 58 V and will use 60 V. We must now select a 60 V power transistor with reasonable beta at I_{Opeak}, 3.87 A. The National BD346, BD347 complementary pair are 60 V, 60 W transistors with a minimum beta of 30 at 4 A. The driver transistor must supply the base drive given 5 mA drive from the LM391. The National BD344, BD345 complementary driver transistors are 60 V devices with a minimum beta of 40 at 200 mA. The driver transistors should be much faster (higher f_T) than the output transistors to insure that the R-C on the output will prevent instability.

To find the heat sink required for each output transistor we use equations (7), (9), and (10):

$$\overline{P}_D = 0.4(30) = 12\text{W} \quad (7)$$

$$\theta_{JA} \leq \frac{150^\circ\text{C} - 55^\circ\text{C}}{12} = 7.9^\circ\text{C/W} \text{ for } T_{AMAX} = 55^\circ\text{C} \quad (9)$$

$$\theta_{SA} \leq 7.9 - 2.1 - 1.0 = 4.8^\circ\text{C/W} \quad (10)$$

If both transistors are mounted on one heat sink the thermal resistance should be halved to 2.4°C/W.

The maximum average power dissipation in each driver is found using equation (8):

$$\overline{P}_{DRIVER(MAX)} = \frac{12}{30} = 400\text{ mW}$$

Using equation (9):

$$\theta_{JA} \leq \frac{155 - 55}{0.4} = 237^\circ\text{C/W}$$

Application Hints (Continued)

Since the free air thermal resistance of the National BD344, BD345 is 100°C/W, no heat sink is required. Using this information and equation (6) we can find the minimum value of R_E required to prevent thermal runaway.

$$R_E \geq \frac{100(30)(0.002)}{30 + 1} = 0.19 \Omega \quad (6)$$

We must now use the SOA data on the National BD346, BD347 transistors to set up the protection circuit. Below is the SOA curve with the 4 Ω and 8 Ω load lines. Also shown are the desired protection lines. Note the value of V_B is equal to the supply voltage, so we use the formulas in the table.

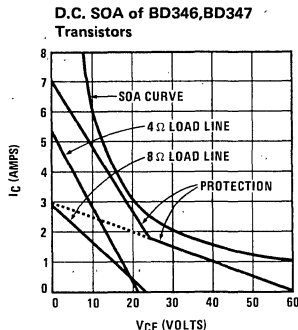


Figure Y.

The data points from the curve are:

$$V_M = 60 \text{ V}, V_B = 23 \text{ V}, I_L = 3 \text{ A}, I_L' = 7 \text{ A}$$

Using the dual slope protection formulas:

$$R_E = \frac{0.65}{3} = 0.22 \Omega$$

$$R_2 = 1 \text{ k}$$

$$R_1 = 1 \text{ k} \left(\frac{60 - 0.65}{0.65} \right) \approx 91 \text{ k}$$

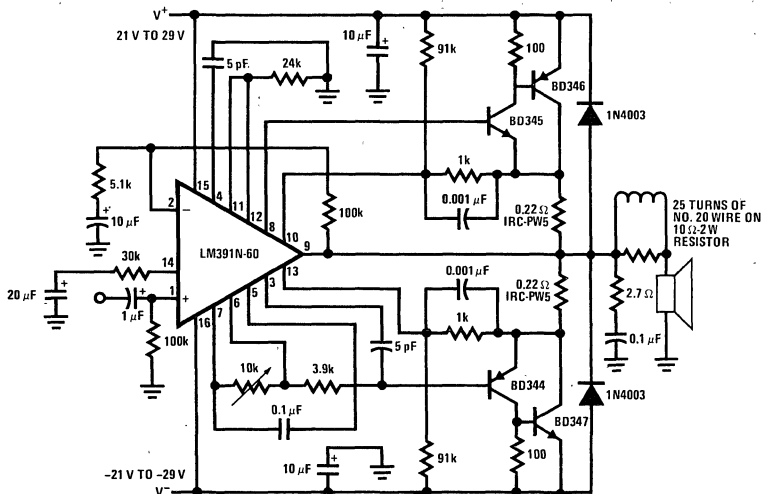
$$R_3 = 1 \text{ k} \left(\frac{23}{7(0.22) - 0.65} - 1 \right) \approx 24 \text{ k}$$

Note that an R_E of 0.22 Ω satisfies equation (6). The final schematic of this amplifier is below. If the output is shorted the current will be 1.8 A and V_{CE} is 23 V. Since the input is AC, the average power is:

$$\text{short } \overline{P_D} = \frac{1}{2} (1.8)(23) \approx 21 \text{ W}$$

This power is greater than was used in the heat sink calculations, so the transistors will overheat for long-duration shorts unless a larger heat sink is used.

Typical Applications (Continued)



20 W-8 Ω, 30 W-4 Ω Amplifier with 1 Second Turn-ON Delay

Application Hints (Continued)

A 40 W/8 Ω, 60 W/4 Ω AMPLIFIER

Given:

| | |
|-------------------|--------------------------|
| Power Output | 40 W/8 Ω 60 W/4 Ω |
| Input Sensitivity | 1 V max |
| Input Impedance | 100k |
| Bandwidth | 20 Hz - 20 kHz ± 0.25 dB |

Equations (1) and (2) give:

$$40 \text{ W}/8 \Omega \quad V_{O\text{peak}} = 25.3 \text{ V} \quad I_{O\text{peak}} = 3.16 \text{ A}$$

$$60 \text{ W}/4 \Omega \quad V_{O\text{peak}} = 21.9 \text{ V} \quad I_{O\text{peak}} = 5.48 \text{ A}$$

Therefore the supply required is:

$$\pm 30.3 \text{ V} @ 3.16 \text{ A, reducing to } \dots$$

$$\pm 26.9 \text{ V} @ 5.48 \text{ A}$$

With 15% regulation and high line we get $\pm 38.3 \text{ V}$ using equation (3).

The minimum gain from equation (4) is:

$$A_V \geq 18$$

We select a gain of 20; resulting sensitivity is 900 mV.

The input impedance and bandwidth are the same as the 20 watt amplifier so the components are the same.

$$R_{f1} = 5.1 \text{ k} \quad R_{IN} = 100 \text{ k} \quad C_C = 5 \text{ pF}$$

$$R_{f2} = 100 \text{ k} \quad C_f = 10 \text{ } \mu\text{F}$$

The maximum supplies dictate using 80 V devices. The National BD350, BD351 pair are 80 V, 160 W transistors with a minimum beta of 40 at 2 A and 20 at 6 A. This corresponds to a minimum beta of 22.5 at 5.5 A ($I_{O\text{peak}}$). The National BD348, BD349 driver pair are 80 V transistors with a minimum beta of 50 at 250 mA. This output combination guarantees $I_{O\text{peak}}$ with 5 mA from the LM391.

Output transistor heat sink requirements are found using equations (7), (9), and (10):

$$\overline{P}_D = 0.4 (60) = 24 \text{ W} \quad (7)$$

$$\theta_{JA} \leq \frac{200 - 55}{24} = 6.0^\circ \text{C/W for } T_{A\text{MAX}} = 55^\circ \text{C} \quad (9)$$

$$\theta_{SA} \leq 6.0 - 1.1 - 1.0 = 3.9^\circ \text{C/W} \quad (10)$$

For both output transistors on one heat sink the thermal resistance should be 1.9°C/W .

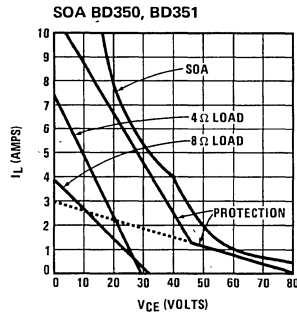
Now using equation (8) we find the power dissipation in the driver:

$$\overline{P}_{\text{DRIVER}} = \frac{24}{20} = 1.2 \text{ W} \quad (8)$$

$$\theta_{JA} \leq \frac{150 - 55}{1.2} = 79^\circ \text{C/W} \quad (9)$$

Since a heat sink is required on the driver, we should investigate the output stage thermal stability at the same time to optimize the design. If we find a value of R_E that is good for the protection circuitry, we can then use equation (5) to find the heat sink required for the drivers.

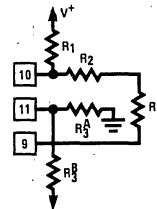
The SOA characteristics of the National BD350, BD351 transistors are shown in the following curve along with a desired protection line.



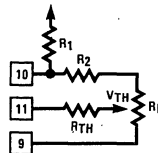
The desired data points are:

$$V_M = 80 \text{ V} \quad V_B = 47 \text{ V} \quad I_L = 3 \text{ A} \quad I_L = 11 \text{ A}$$

Since the break voltage is not equal to the supply, we will use two resistors to replace R_3 and move V_B .



Circuit Used



Thevenin Equivalent

$$\text{WHERE: } R_{TH} = R_3 \parallel R_B$$

$$V_{TH} = V^+ \left[\frac{R_3}{R_3 + R_B} \right]$$

Application Hints (Continued)

The formulas for R_E , R_1 , and R_2 do not change:

$$R_E = \frac{0.65}{3A} = 0.22\Omega$$

$$R_2 = 1k \quad R_1 = 1k \frac{80 - 0.65}{0.65} = 120k$$

The formula for R_3 now gives R_{TH} when the V^+ in the formula becomes V_B .

$$R_{TH} = R_2 \left[\frac{V_B}{I_L R_E - \phi} - 1 \right]$$

$$= 1k \left[\frac{47}{11(0.22) - 0.65} - 1 \right] = 25.55k$$

V_{TH} is the additional voltage added to the supply voltage to get V_B .

$$V_{TH} = -(V_B - V^+) = -(47 - 30) = -17V$$

Now we must find R_3^A and R_3^B using the Thevenin formulas. Putting V_{TH} , V^- , and R_{TH} into the appropriate formulas reduces to:

$$R_3^B = 0.76 R_3^A \quad \text{and} \quad 25.55k = R_3^A \parallel R_3^B$$

The easiest way to solve these equations is to iterate with standard values. If we guess $R_3^A = 62k$, then $R_3^B = 47.12k$; use $47k$. The Thevin impedance comes out $26.7k$, which is close enough to $25.55k$.

Now we will use equation (5) to determine the heat sinking requirements of the drivers to insure thermal stability:

$$\theta_{JA} \leq \frac{0.22(20 + 1)}{40(0.002)} \approx 57^\circ C/W \quad (5)$$

This value is lower than we got with equation (9), so we will use it in equation (10):

$$\theta_{SA} \leq 57 - 6 - 1 = 50^\circ C/W \quad (10)$$

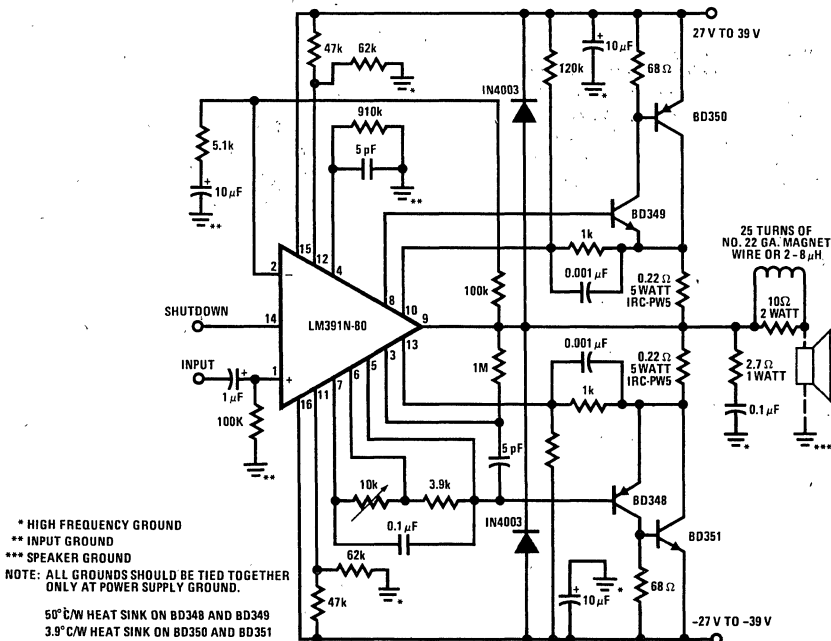
This is the required heat sink for each driver. For low TIM we add the $1M\Omega$ resistor from pin 3 to the output and a $910k$ resistor from pin 4 to ground. The complete schematic is on page 11.

If the output is shorted, the transistor voltage is about $28V$ and the current is $5A$. Therefore the average power is:

$$\text{short } \overline{P}_D = \frac{1}{2}(28)5 = 70W$$

This is much larger than the power used to calculate the heat sinks and the output transistors will overheat if the output is shorted too long.

Typical Applications (Continued)



* HIGH FREQUENCY GROUND
 ** INPUT GROUND
 *** SPEAKER GROUND
 NOTE: ALL GROUNDS SHOULD BE TIED TOGETHER ONLY AT POWER SUPPLY GROUND.

50°C/W HEAT SINK ON BD348 AND BD349
 3.9°C/W HEAT SINK ON BD350 AND BD351

40W-8Ω, 60W-4Ω Amplifier

LM1011, LM1011A Dolby B-Type Noise Reduction Processor

General Description

The LM1011, LM1011A are monolithic integrated circuits specifically designed to realize the Dolby B-type noise reduction system. It is a replacement for the Signetics NE545B, but with several improved features.

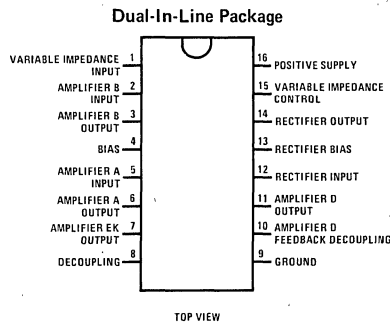
Features

- Reduced distortion at high frequencies and high signal levels
- Improved transient stability with signal bursts
- Wide operating voltage range
- Low supply current

Available only to licensees of Dolby Laboratories Licensing Corporation, San Francisco, from whom licensing and application information must be obtained.

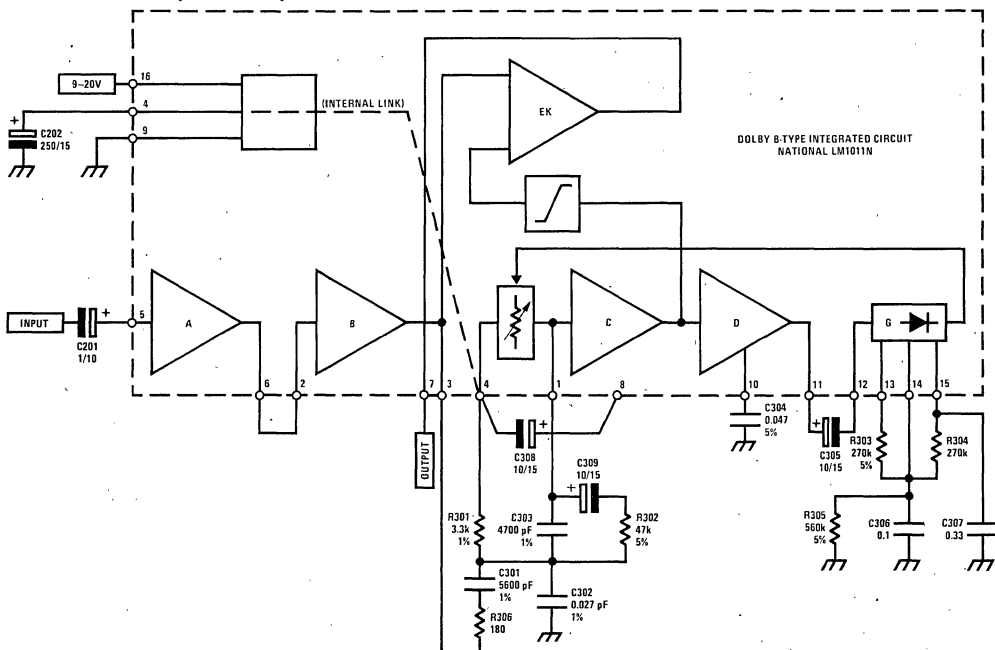
'Dolby' and the double-D symbol are trademarks of Dolby Laboratories Inc.

Connection Diagram



Order Number LM1011N or LM1011AN
See NS Package N16A

Test Circuit (Encode)



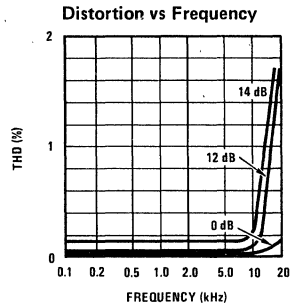
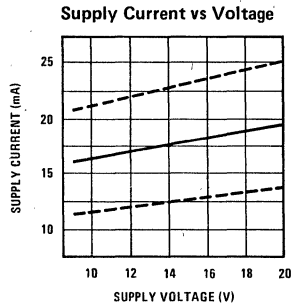
Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 24V |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (V_{CC} = 12V, T_A = 25°C) NB 0 dB refers to 580 mVrms Dolby level at pin 3

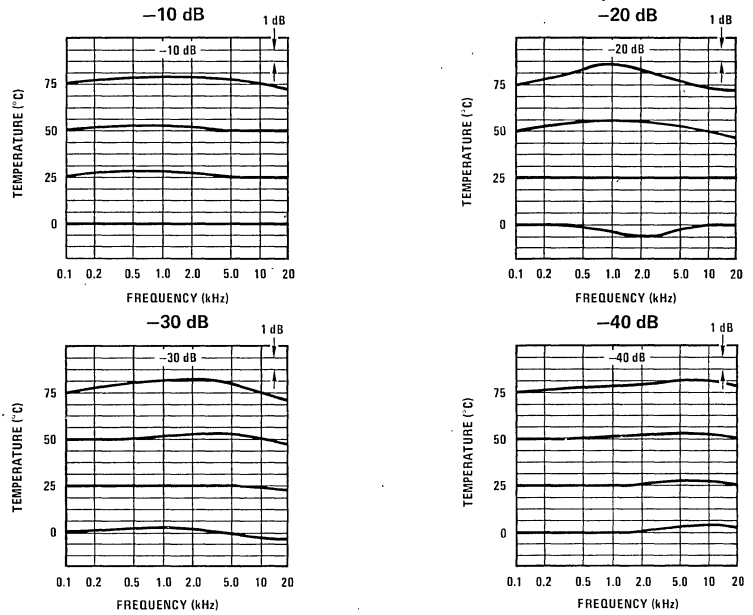
| PARAMETER | CONDITIONS | LM1011A | | | LM1011 | | | UNITS |
|---------------------------------|--|---------|-------|-------|--------|-------|-------|-------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Supply Voltage Range | | 9 | | 20 | 9 | | 20 | V |
| Supply Current | | 12 | 17 | 22 | 12 | 17 | 22 | mA |
| Voltage Gain (Pins 5-3) | 1 kHz Pins 6 and 2 Connected | 24.5 | 26 | 27.5 | 24 | 26 | 28 | dB |
| Voltage Gain (Pins 3-7) | 1 kHz (Noise Reduction Out) | -0.5 | 0 | 0.5 | -1 | 0 | 1 | dB |
| Distortion | 1 kHz, 0 dB | | 0.05 | 0.1 | | 0.05 | 0.1 | % |
| | 10 kHz, 10 dB | | 0.1 | 0.3 | | 0.1 | 0.3 | % |
| Signal Handling | 1 kHz 0.3% Distortion | 10 | 14 | | 10 | 14 | | dB |
| Signal/Noise Ratio | 6 and 2 Connected, R _S = 10 kΩ | | | | | | | |
| Encode | CCIR Weighted | 67 | 70 | | 65 | 70 | | dB |
| Decode | | 77 | 80 | | 75 | 80 | | dB |
| Encode Characteristics | Input to Pin 5 | | | | | | | |
| | 1.3 kHz, -20 dB | -16.7 | -15.7 | -14.7 | -17.2 | -15.7 | -14.2 | dB |
| | 2.5 kHz, -20 dB | -16.9 | -15.9 | -14.9 | -17.4 | -15.9 | -14.4 | dB |
| | 3.0 kHz, -30 dB | -22.2 | -21.2 | -20.2 | -22.7 | -21.2 | -19.7 | dB |
| | 5.0 kHz, -30 dB | -22.8 | -21.8 | -20.8 | -23.3 | -21.8 | -20.3 | dB |
| | 10 kHz, 0 dB | -0.5 | 0.5 | 1.5 | -1.0 | 0.5 | 2.0 | dB |
| | 10 kHz, -40 dB | -30.6 | -29.6 | -28.6 | -31.1 | -29.6 | -28.1 | dB |
| 14 kHz, -30 dB | -24.9 | -23.9 | -22.9 | -25.4 | -23.9 | -22.4 | dB | |
| Back-to-Back Frequency Response | With Standard Dolby B-Type Processor | -1 | 0 | 1 | -1.5 | 0 | 1.5 | dB |
| Input Resistance | Pin 5 | 45 | 65 | 85 | 45 | 65 | 85 | kΩ |
| | Pin 2 | 4.3 | 5.6 | 6.9 | 4.3 | 5.6 | 6.9 | kΩ |
| Output Resistance | Pin 6 | 1.8 | 2.4 | 3.0 | 1.8 | 2.4 | 3.0 | kΩ |
| | Pin 3 | | 80 | 120 | | 80 | 120 | Ω |
| | Pin 7 | | 80 | 120 | | 80 | 120 | Ω |

Typical Performance Characteristics



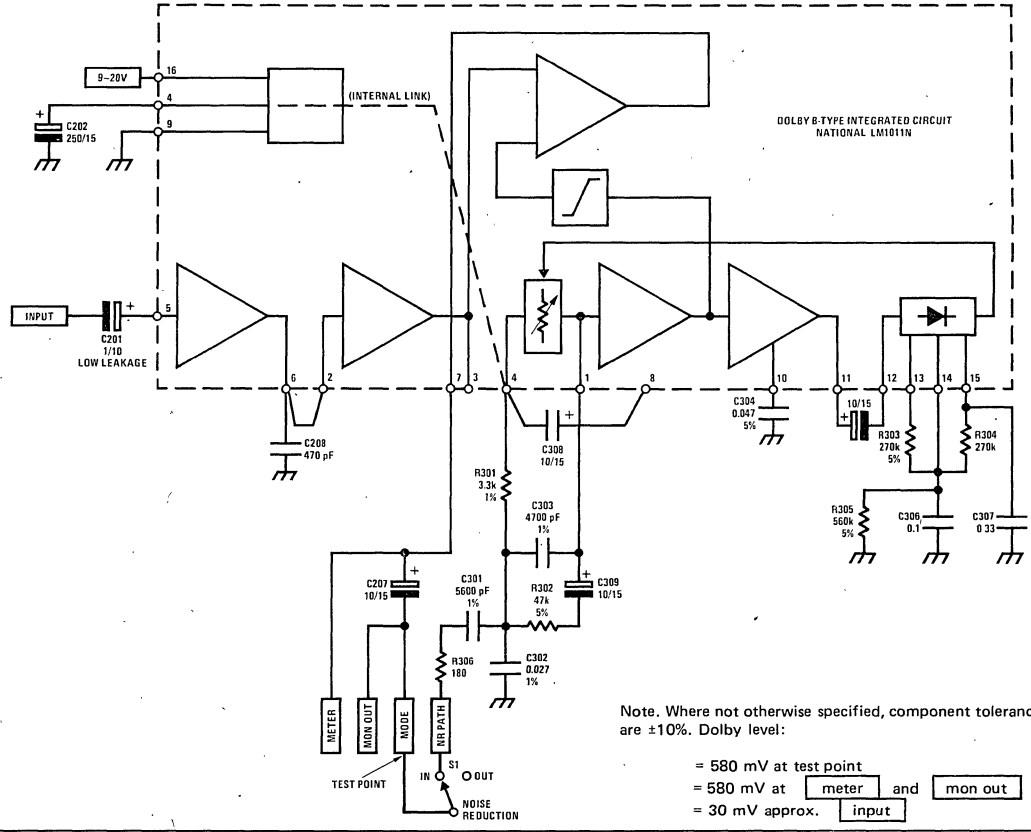
Typical Performance Characteristics (Continued)

Deviation from Standard Encode Characteristics vs Temperature



Typical Application

IC Decode Processor Without Filter



Note. Where not otherwise specified, component tolerances are $\pm 10\%$. Dolby level:

- = 580 mV at test point
- = 580 mV at meter and mon out
- = 30 mV approx. input



LM1017 4-Bit Binary 7-Segment Decoder/Driver

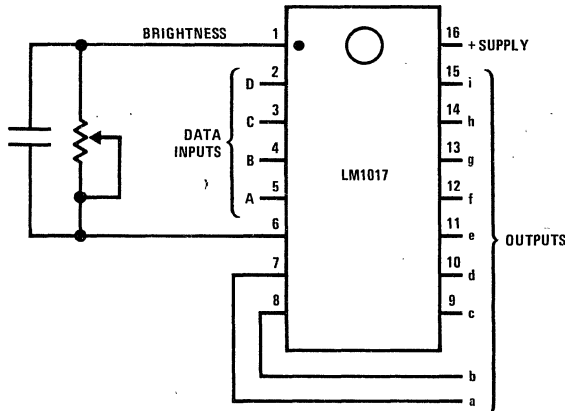
General Description

The LM1017 is a monolithic IC which decodes 4-bit "binary plus one" coded input signals and supplies 1 1/2-digit TV channel display information. The outputs are designed to drive a 7-segment common cathode LED display with up to 25 mA depending on thermal dissipation requirements. Improvements in circuit design enable the device to operate from 5V to 12V supply. A brightness control facility is included.

Features

- A direct replacement for SN29764 but with 12V supply capability
- TTL compatible inputs with high input voltage immunity
- Channel displays are from 1 to 16
- Current-driven output stages for LEDs protect against excess thermal dissipation
- Continuously variable brightness control
- Low stand-by quiescent current supply consumption
- Suitable for NSN583 0.5 inch LED display
- Inputs are suitable for direct drive from MOS outputs

Connection Diagram



Order Number LM1017N
See NS Package N16A

$V_{SUPPLY} = 5V$

For 12V supply, external resistors must be used between the output pin and segment to limit device dissipation.

Absolute Maximum Ratings

| | | | |
|-----------------------------|--------------|--|-----------------|
| Supply Voltage, Pin 16 | 13.5V | Storage Temperature Range | -55°C to +150°C |
| Input Voltage, Pins 2-5 | 30V | Junction Temperature | 150°C |
| Input Voltage, Pin 1 | 13.5V | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Operating Temperature Range | 0°C to +70°C | | |

Electrical Characteristics $V_{16} = 5V, T_A = 25^\circ C$

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---------------------------|-----|------|-----|--------------|
| Current per Segment Quiescent Current, Pin 16 | Pin 1 = 2V | | 12 | 20 | mA |
| | Pin 1 = 5V | | 4 | | mA |
| Input Logic Voltage | Pins 2-5 | 2 | | | |
| | | | | | 0.8 |
| Input Current, Pins 2-5 | V2-5 = 2.4V | | | 1 | μA |
| | V2-5 = 0V | | | -5 | μA |
| Input Current, Pin 1 | I7-15 = -15 mA | | -350 | | μA |
| Output Current, Pins 7-15 | V1 = 0V | -16 | -22 | | mA |
| | V1 = 2V | | -12 | | mA |
| | V1 = V16 | | | -20 | μA |
| Minimum Saturation Between Output Terminals 7-15 and 16 | I _{OUT} = -20 mA | | 1.4 | | V |
| Package Thermal Resistance, θ_{JA} | | | | 100 | $^\circ C/W$ |

Note. To limit device temperature at supply voltages > 5V, the following condition must be maintained: $8 (V_{SUPPLY} - V_{OUT}) I_{OUT} < \frac{150 - T_A}{\theta_{JA}}$

Eg. For 12V supply and 20 mA I_{OUT} into 2V LED, T_A = 25°C: $8 (12 - V_O) 0.02 < \frac{125}{100}$

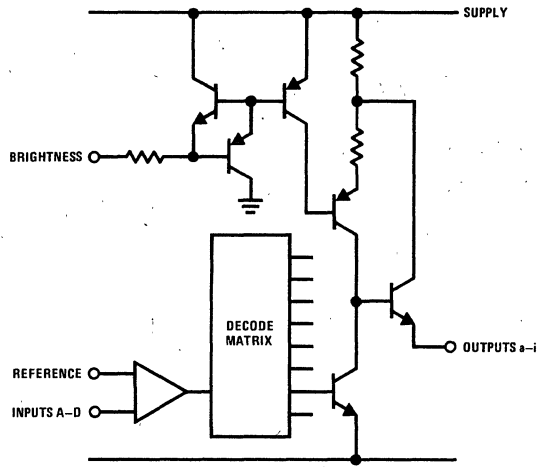
i.e., $V_O > 4.2V \therefore$ series output resistance = $\frac{2.2V}{20 mA} = 110\Omega$.

See application notes for use of common series resistance between LED cathodes and ground.

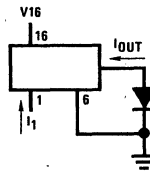
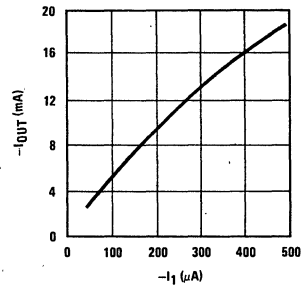
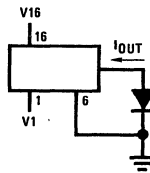
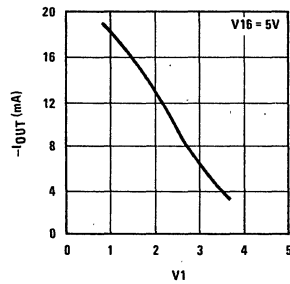
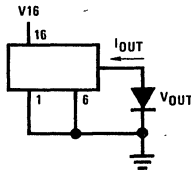
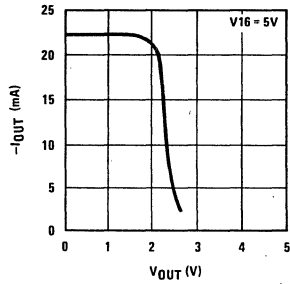
Truth Table

| CHANNEL | INPUT | | | | | OUTPUT | | | | | | | | | |
|---------|-------|---|---|---|----|--------|----|----|----|----|----|----|----|----|--|
| | D | C | B | A | BR | a | b | c | d | e | f | g | h | i | |
| 1 | L | L | L | L | L | | ON | ON | | | | | | | |
| 2 | L | L | L | H | L | ON | ON | | ON | ON | | | ON | | |
| 3 | L | L | H | L | L | ON | ON | ON | ON | | | | ON | | |
| 4 | L | L | H | H | L | | ON | ON | | | | ON | ON | | |
| 5 | L | H | L | L | L | ON | | | ON | ON | | | ON | ON | |
| 6 | L | H | L | H | L | ON | | ON | ON | ON | ON | ON | ON | | |
| 7 | L | H | H | L | L | ON | ON | ON | | | | | | | |
| 8 | L | H | H | H | L | ON | ON | ON | ON | ON | ON | ON | ON | | |
| 9 | H | L | L | L | L | ON | ON | ON | ON | | ON | ON | | | |
| 10 | H | L | L | H | L | ON | ON | ON | ON | ON | ON | | ON | ON | |
| 11 | H | L | H | L | L | | ON | ON | | | | | ON | ON | |
| 12 | H | L | H | H | L | ON | ON | | ON | ON | | | ON | ON | |
| 13 | H | H | L | L | L | ON | ON | ON | ON | | | | ON | ON | |
| 14 | H | H | L | H | L | | ON | ON | | | | ON | ON | ON | |
| 15 | H | H | H | L | L | ON | | ON | ON | | ON | ON | ON | ON | |
| 16 | H | H | H | H | L | ON | | ON | ON | ON | ON | ON | ON | ON | |
| OFF | X | X | X | X | H | | | | | | | | | | |

Circuit Schematic (One Circuit Shown)



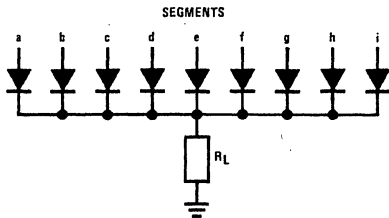
Output Characteristics



Typical Applications

When operating with a 12V supply line, it is necessary to limit the power dissipation in the IC by means of external resistance in series with the LED segments. (Max package dissipation at 70°C = 800 mW.)

A minimum voltage of 2.5V should be allowed across the output driver pins between supply and outputs. Allowing 1.4V for the LED segments, a simple economical solution using *only 1 resistor* can be proposed as follows:



Maximum no of ON segments = 8

For 20 mA/segment, maximum voltage allowed across R_L will be:

$$12 - 2.5 - 1.4 \cong 8V$$

$$\therefore R_L \text{ max} = 8/8 \times 0.02 \cong 47\Omega$$

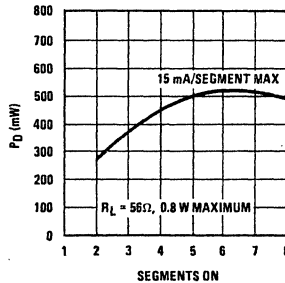
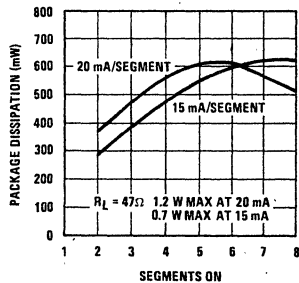
For 15 mA/segment (max), $R_L \text{ max} = 56\Omega$.

Alternative methods of limiting P_D at 12V supply.

With a series resistance between each output and segment, the recommended resistance per segment at 20 mA maximum will be:

$$(12 - 2.5 - 1.4)/0.02 \cong 390\Omega$$

If a zener is used, maximum zener voltage = 8V. (The zener can be common between LED display cathode and ground.)



LM1019N Digital Tuning Station Detector

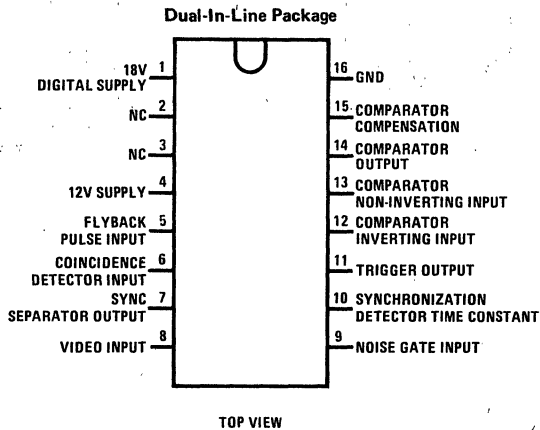
General Description

The LM1019N is a monolithic integrated circuit for identifying a valid picture when digitally tuned television receivers are used in the "search" mode.

Features

- Noise gated sync separator
- Coincidence detector between sync and flyback
- Comparator to set AFC voltage at which output triggers

Connection Diagram



Order Number LM1019N
See NS Package N16A

Absolute Maximum Ratings

| | |
|--|-----------------|
| V1-16 | 20V |
| V3-16 | 14V |
| I ₁₁ | 10 mA |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics V1-16 = 18V, V3-16 = 12V, T_A = 25°C

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------------|---------------------------------|------|------|------|------------------|
| Supply Current, I ₃ | | | 6 | | mA |
| Supply Current, I ₁ | | | 2 | | mA |
| Video Signal | | | | | |
| Input Voltage Range | | 1 | | 7 | V _{p-p} |
| Input Current Driving Sync Pulse | | | 100 | | μA |
| Noise Gating | | | | | |
| Input Voltage | | 0.7 | | | V |
| Input Current | | 0.03 | | 10 | mA |
| Flyback Pulse | | | | | |
| Input Voltage | | 0.7 | | | V |
| Input Current | | 0.05 | 1 | | mA |
| Input Resistance | | | 400 | | Ω |
| Pulse Deviation | f = 15,625 Hz | 10 | | | μs |
| Composite Sync Pulse Output (Pin 7) | | | | | |
| Output Voltage | | | 10 | | V _{p-p} |
| Output Resistance at Leading Edge | | | 50 | | Ω |
| Output Resistance at Trailing Edge | | | 2 | | kΩ |
| Coincidence Detector | | | | | |
| Sync Input Voltage | (DC Restored by Internal Diode) | 6 | | | V |
| Input Resistance | V _S > 0.7V | | 5 | | kΩ |
| | V _S < 0.7V | | 10 | | kΩ |
| Trigger Circuit | | | | | |
| Input Voltage, V10 | V11 High | | | 2 | V |
| | V11 Low | 4.5 | | | V |
| Output Leakage, I ₁₁ | V10 < 2V | | | 100 | μA |
| Output Voltage, V11 | V10 > 4.5V | | 0.2 | 0.5 | V |
| | I ₁₁ = 1 mA | | | | |
| Comparator | | | | | |
| Input Bias Current | | | 1 | 10 | μA |
| Input Offset Voltage | | | | 25 | mV |
| Voltage Gain | Pin 14 Open Circuit | | 5000 | | |
| Output Current | | | | 10 | mA |
| Internal Load Resistance | | | | | |
| R1-14 | | 7 | | 13 | kΩ |
| Input Common-Mode Range | | 0 | | V1-5 | V |

Typical Applications

The LM1019 provides a "stop" signal to the tuning system when a picture is received but because of the delay in the system when operating in the fast ramp mode, the tuner will normally have passed the optimum tuning point. The "stop" signal therefore ceases and the tuning system reverses direction at a reduced rate. When the AFC reaches its correct level a further "stop" signal is given which ends the search routine.

Figure 1 shows the block schematic of the LM1019 with the required external components for a typical application.

Video with positive-going sync pulses is fed through a low pass filter to prevent noise being mistaken as sync pulses. It is then fed to a sync separator which gives a positive signal output at pin 7 during the sync period.

A noise gate is also provided such that when the voltage on pin 9 exceeds 0.7V the sync separator is inhibited. This can be utilized by coupling video through a high pass filter into pin 9. However, the system works well even without this, and if not required, pin 9 can either be grounded or left open.

The processed sync pulses are AC coupled to the coincidence detector on pin 6 because in the event of there being no video input, pin 7 rises to the high state. Flyback pulses of greater than 1V in amplitude are applied to pin 5 and when this is coincident with the video sync pulse, a current pulse is provided by pin 10.

After a predetermined number of coincident pulses (set by the delay capacitor on pin 10), the Schmitt trigger operates, grounding pin 11. This brings down the voltage applied to the final comparator input from 12V to the required AFC trigger level set by R1 and R2. Typically this will be in the range of 6–10V.

The AFC control voltage is applied to pin 13. This is always less than 12V so that until the sync pulses and the flyback are synchronized, the main output on pin 14 is always low. However, once synchronization is achieved and pin 12 is at a lower reference level, the AFC voltage will rise above this reference and then below it as the tuner passes through the AFC detector range.

Pin 14 thus rises to 18V and then returns to a low level. As the tuner then reverses slowly, pin 14 again goes high when the AFC voltage equals the reference on pin 12. This terminates the search routine.

Positive feedback can be provided to give a clean transition and to prevent multiple pulses being sent to the tuning circuits.

This is merely one possible configuration of the circuit. The output amplifier can be used in the inverting mode if the AFC S curve is inverted. A compensation point is also provided for application involving negative feedback where the amplifier may need stabilizing.

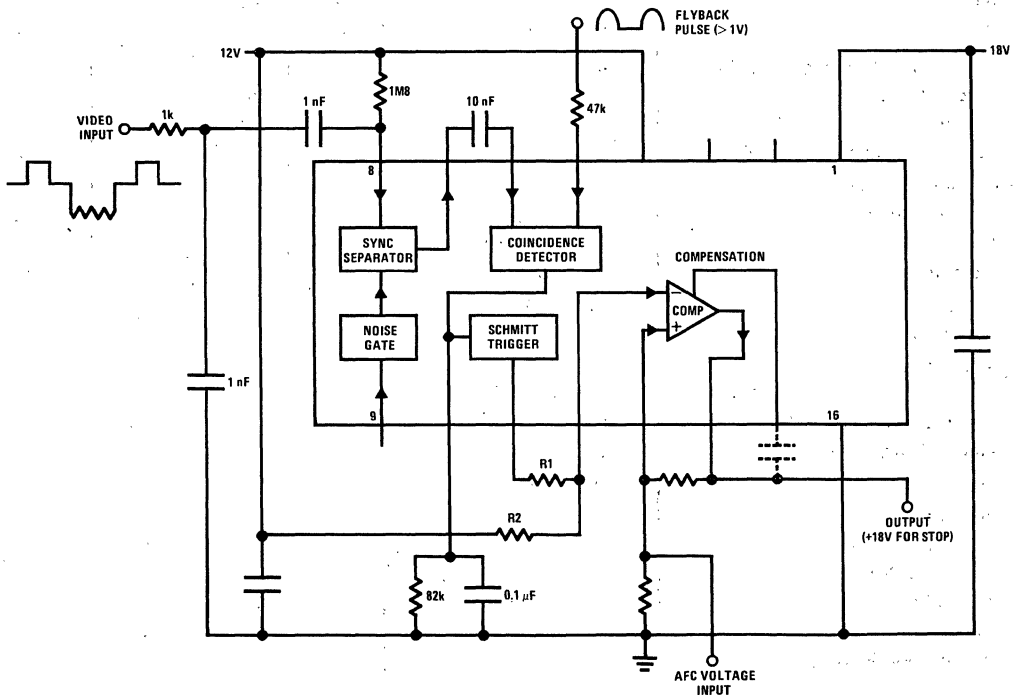


FIGURE 1

LM1303 Stereo Preampifier

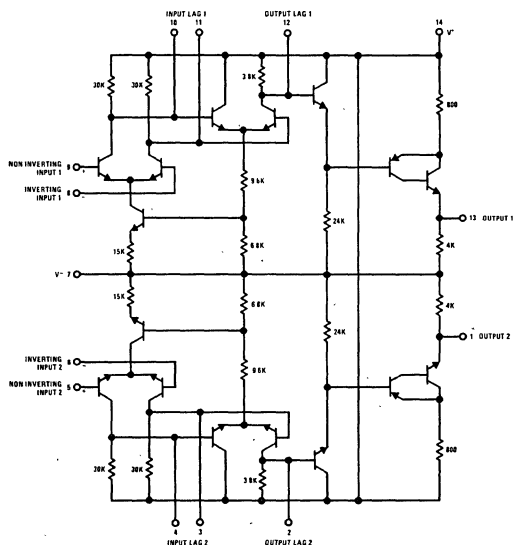
General Description

The LM1303 consists of two identical operational amplifiers constructed on a single silicon chip. Intended for amplification of low-level stereo signals, the LM1303 features low input noise voltage, high open-loop voltage gain, large output voltage swing and short circuit protection.

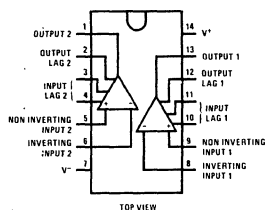
Features

- Large Output Voltage Swing 4.0V rms min
- High Open-Loop Voltage Gain 6,000 min
- Channel Separation, 60 dB min at 10 kHz

Schematic and Connection Diagrams



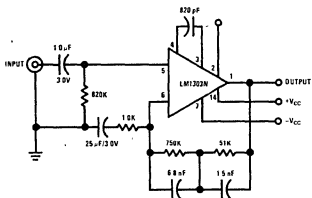
Dual-In-Line Package



Order Number LM1303N
See NS Package N14A

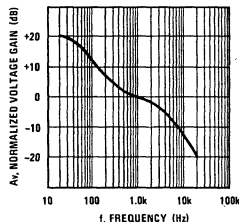
Typical Application and Characteristic

Magnetic Phono Playback Preamplifier/R IAA Equalized



- Voltage gain 34 dB at 1 KHz
- Input overload point 100 mVrms at 1 KHz
- Output voltage swing 5.0 Vrms at 1 KHz and 0.1% THD
- Output noise level Better than 70 dB below 10 mV phono input (input shorted)

FIGURE 1



10

Absolute Maximum Ratings

| | |
|--------------------------------------|----------------|
| Supply Voltage | ±15V |
| Power Dissipation (Note 1) | 715 mW |
| Operating Temperature Range | 0 to 75°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (Note 2)

| PARAMETER | MIN | TYP | MAX | UNITS |
|---|-------|--------|-----|-------|
| Input Offset Voltage | | 1.5 | 10 | mV |
| Input Offset Current | | 0.2 | 0.4 | μA |
| Input Bias Current | | 1.0 | 10 | μA |
| Supply Current Both Amplifiers $V_{OUT} = 0V$ | | | 15 | mA |
| Large Signal Voltage Gain | 6,000 | 10,000 | | V/V |
| Channel Separation $f = 10$ kHz | 60 | 70 | | dB |
| Output Voltage Swing $R_L = 10$ kΩ | 4.0 | 5.5 | | Vrms |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Note 2: These specifications apply for $V_S = \pm 13V$ and $T_A = 25^\circ C$, unless otherwise specified.

Typical Application and Characteristic (Continued)

Tape Head Playback Preamplifier/NAB Equalization

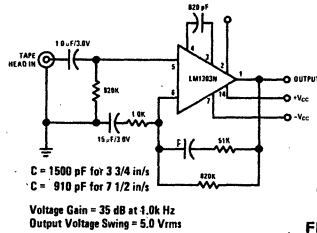
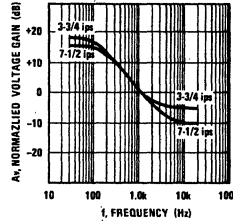
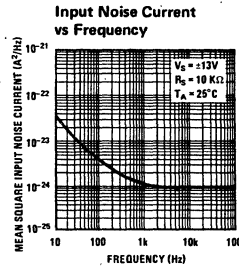
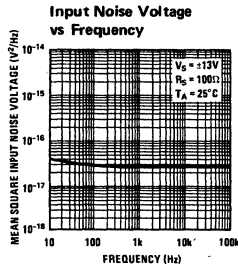


FIGURE 2



Typical Performance Characteristics



LM1310 Phase-Locked Loop FM Stereo Demodulator

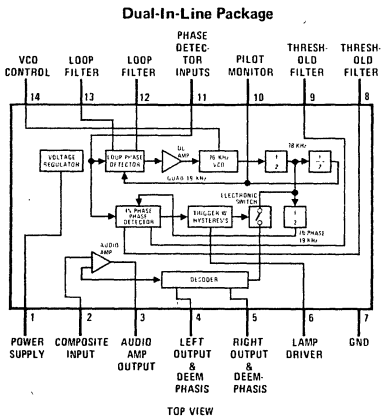
General Description

The LM1310 is an integrated FM stereo demodulator using phase locked loop techniques to regenerate the 38 kHz subcarrier. A second version also available is the LM1800 (see separate data sheet) which adds superb power supply rejection and buffered (emitter follower) outputs to the basic phase locked decoder circuit. The features available in these integrated circuits make possible a system delivering high fidelity sound within the cost restraints of inexpensive stereo receivers.

Features

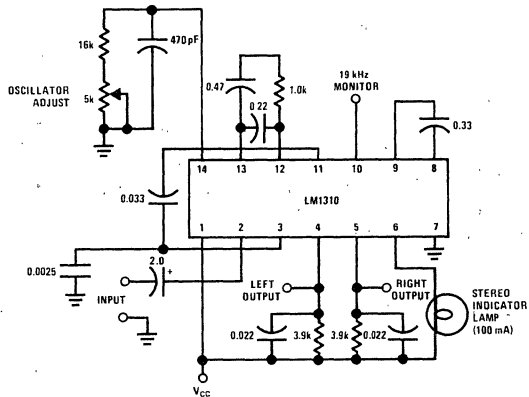
- Automatic stereo/monaural switching
- No coils, all tuning performed with single potentiometer
- Wide supply operating voltage range
- Excellent channel separation

Connection Diagram

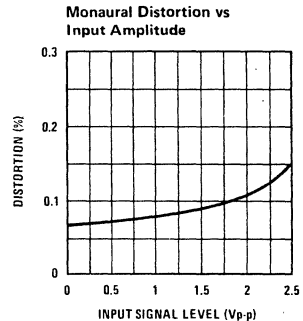
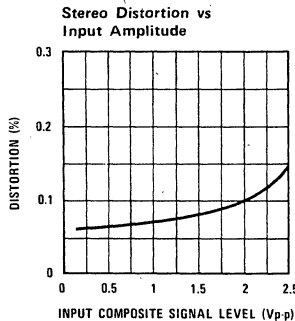
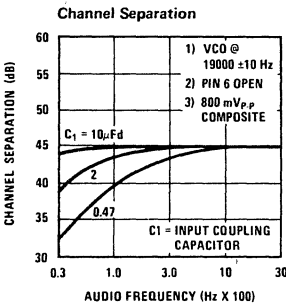


Order Number LM1310N
See NS Package N14A

Typical Application



Typical Performance Characteristics



Absolute Maximum Ratings

| | | | |
|-----------------------------|--------------|--|-----------------|
| Supply Voltage | 18V | Operating Supply Voltage Range | 10V to 18V |
| Power Dissipation (Note 2) | 715 mW | Storage Temperature Range | -65°C to +150°C |
| Operating Temperature Range | 0°C to +70°C | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

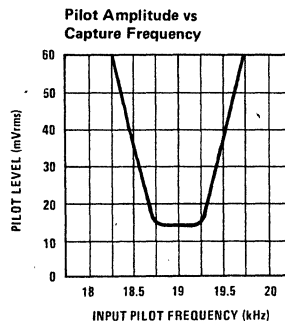
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|---|-----|------|-----|------------|
| Supply Current | Lamp "OFF" | | 18 | | mA |
| Lamp Driver Saturation | 100 mA Lamp Current | | 1.3 | | V |
| Lamp Driver Leakage | | | 1.0 | | nA |
| Pilot Level for Lamp "ON" | Pin 11 Adjusted to 19.00 kHz | | 15 | 20 | mVrms |
| Pilot Level for Lamp "OFF" | Pin 11 Adjusted to 19.00 kHz | 3.0 | 7.0 | | mVrms |
| Composite Input | Maximum for THD < 0.5% | 2.8 | | | Vp-p |
| Monaural Input | Maximum for THD < 1.0% | 2.8 | | | Vp-p |
| Stereo Channel Separation | | 30 | 40 | | dB |
| | 2.0Vp-p Composite with 10% Pilot | | 45 | | dB |
| Monaural Channel Unbalance | Pilot "OFF" | | 0.3 | 1.5 | dB |
| Recovered Audio | | | 485 | | mVrms |
| Total Harmonic Distortion | | | 0.3 | | % |
| Total Harmonic Distortion | 2.0 Vp-p Composite with 10% Pilot | | 0.15 | | % |
| Capture Range | 50 mVrms of Pilot | | ±3.5 | | % of f_o |
| Ultrasonic Frequency Rejection | 19 kHz | | 35 | | dB |
| | 38 kHz | | 45 | | dB |
| Dynamic Input Resistance | | 20 | 50 | | k Ω |
| SCA Rejection | f = 67 kHz; Measure 9 kHz Beat Note with 1 kHz Modulation "OFF" | | 75 | | dB |

Note 1: Unless otherwise noted: $V_{CC} = +12 V_{DC}$ and $T_A = +25^\circ C$. The input signal is a 2.8 Vp-p standard multiplex composite signal using 10% Pilot and with L or R-channel only modulated at 1.0 kHz.

Note 2: For operation in ambient temperatures above $25^\circ C$, the device must be derated based on a $150^\circ C$ maximum junction temperature and a thermal resistance of $175^\circ C/W$ junction to ambient.

Note 3: The VCO can be defeated (sometimes desirable when using an AM-FM receiver in the AM mode) by returning pin 14 to ground through a 2.2 k Ω resistor.

Typical Performance Characteristics (Continued)



LM1391 Phase-Locked Loop Block

General Description

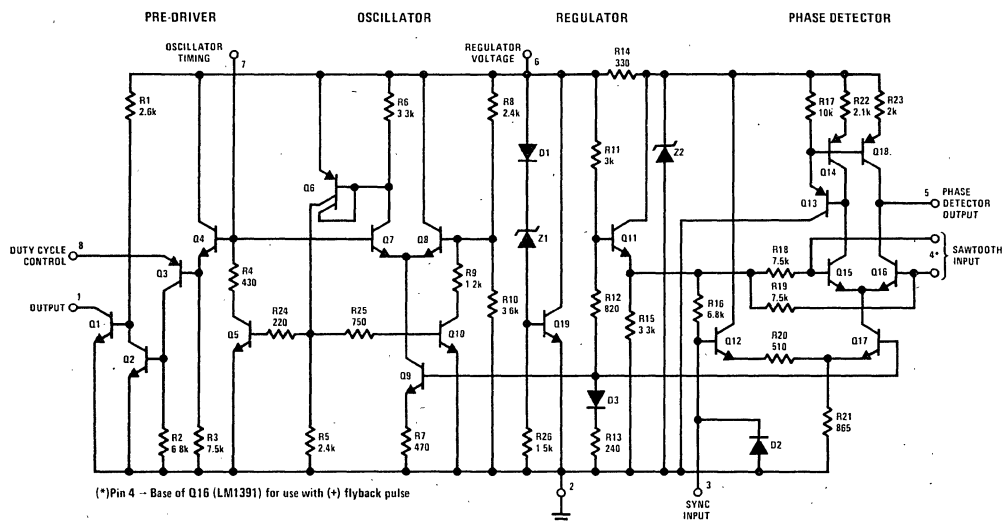
The LM1391 integrated circuit has been designed primarily for use in the horizontal section of TV receivers, but may find use in other low frequency signal processing applications. It includes a stable VCO, linear pulse phase detector, and variable duty cycle output driver.

- Output transistor with low saturation and high voltage swing
- APC of the oscillator with a synchronizing signal
- DC controlled output duty cycle
- ± 300 Hz typical pull-in
- Linear balanced phase detector
- Low thermal frequency drift
- Small static phase error
- Adjustable dc loop gain

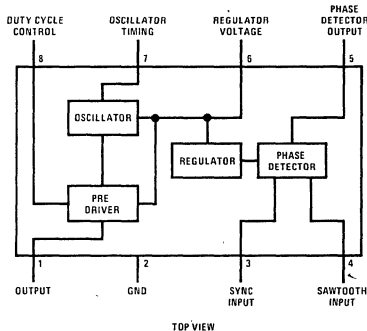
Features

- Internal active regulator for improved supply rejection
- Uncommitted collector of output transistor

Schematic and Connection Diagrams



Dual-In-Line Package



Order Number LM1391N
See NS Package N08B

Absolute Maximum Ratings

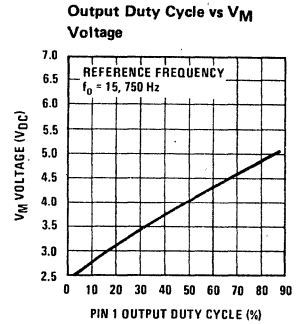
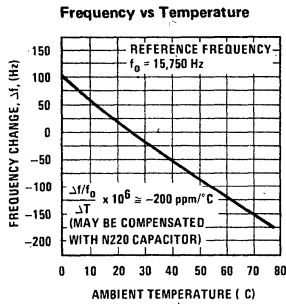
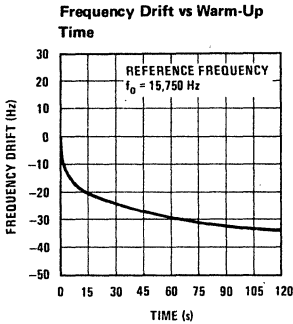
| | | | |
|-------------------------------|----------------------|--|-----------------|
| Supply Current | 40 mA _{DC} | Power Dissipation (Package Limitation) | 1250 mW |
| Output Voltage | 40 V _{DC} | Plastic Package (Note 1) | 0°C to +75°C |
| Output Current | 30 mA _{DC} | Operating Temperature Range (Ambient) | -65°C to +150°C |
| Sync Input Voltage (Pin 3) | 5.0 V _{p-p} | Storage Temperature Range | |
| Flyback Input Voltage (Pin 4) | 5.0 V _{p-p} | | |

Electrical Characteristics $T_A = 25^\circ\text{C}$ (see test circuit, all switches in position 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|-----------------------------|-----|------|------|--------------------|
| Regulated Voltage (Pin 6) | $I_6 = 22 \text{ mA}_{DC}$ | 8.0 | 8.6 | 9.2 | V _{DC} |
| Supply Current (Pin 6) | | | 20 | | mA _{DC} |
| Collector-Emitter Saturation Voltage of Output Transistor (Pin 1) | $I_{C1} = 20 \text{ mA}$ | | 0.30 | 0.40 | V _{DC} |
| Pin 4 Voltage | | | 2.0 | | V _{DC} |
| Oscillator Pull-in Range | Adjust R _H | | ±300 | | Hz |
| Oscillator Hold-in Range | Adjust R _H | | ±900 | | Hz |
| Static Phase Error | $\Delta f = 300 \text{ Hz}$ | | 0.5 | | μs |
| Free-running Frequency Supply Dependence | S1 in position 2 | | ±3.0 | | Hz/V _{DC} |
| Phase Detector Leakage (Pin 5) | All switches in position 2 | | | ±1.0 | μA |
| Sync Input Voltage (Pin 3) | | 2.0 | | 5.0 | V _{p-p} |
| Sawtooth Input Voltage (Pin 4) | | 1.0 | | 3.0 | V _{p-p} |
| Maximum Oscillator Frequency | | | 500 | | kHz |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 100°C/W junction to ambient.

Typical Performance Characteristics



Application Information

The following equations may be considered when using the LM1391 in a particular application.

$$R201 = R301 = \frac{V_{CC} - 8.6}{0.02} \Omega$$

$$f_0 \cong \frac{1}{0.6 R_0 C_0} \text{ Hz} \quad 1.5\text{k} \leq R_0 < 51\text{k}$$

$$R204 \cong 10 R_0$$

$$C203 = C204 \cong \frac{1}{600 f_0 (\text{Hz})} \text{ F}$$

$$\text{DC Loop Gain } \mu\beta \cong 3.2 \times 10^{-5} R_0 f_0 \text{ Hz/rad}$$

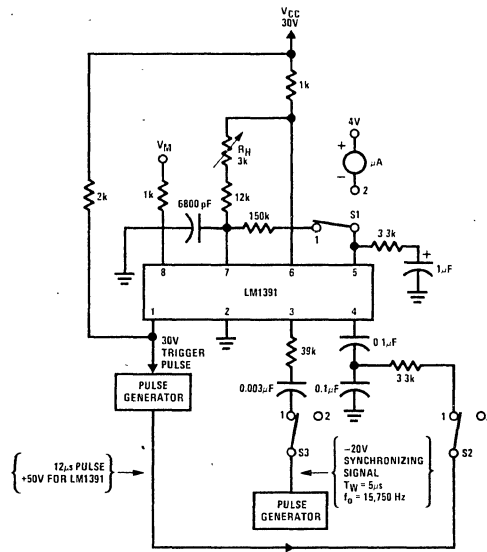
Noise Bandwidth

$$f_{nn} \cong \frac{1 + 2\pi \frac{R_X^2}{R_Y} C_c \mu\beta}{4R_X C_c} \text{ Hz}$$

Damping Factor

$$K \cong \frac{\pi}{2} \frac{R_X^2}{R_Y} C_c \mu\beta$$

Test Circuit



Typical Applications

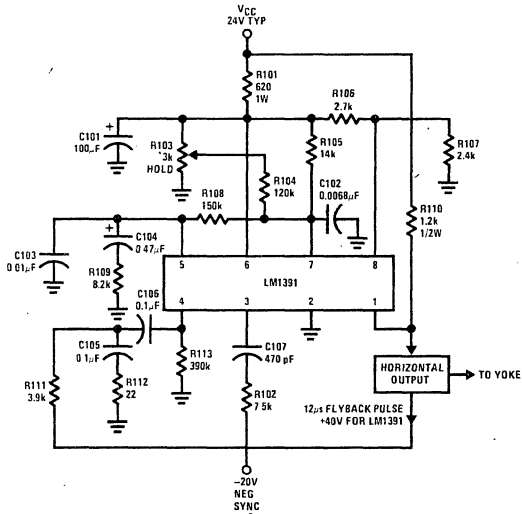


FIGURE 1. TV Horizontal Processor

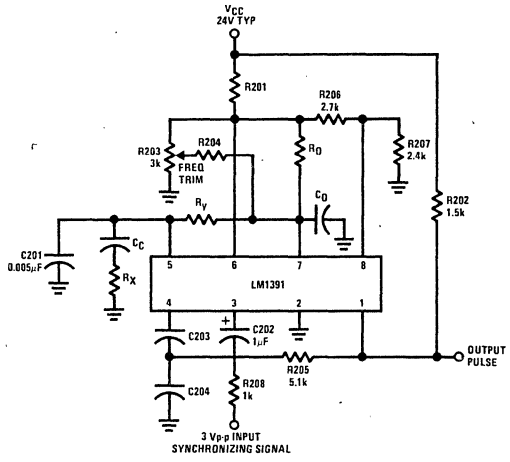


FIGURE 2. General Purpose Phase-Lock Loop (See Applications Information)

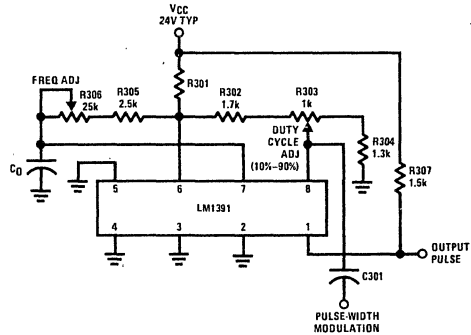


FIGURE 3. Variable Duty Cycle Oscillator (See Applications Information)



LM1596/LM1496 Balanced Modulator-Demodulator

General Description

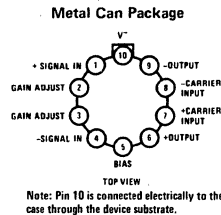
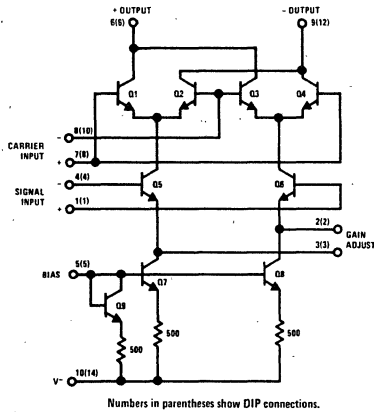
The LM1596/LM1496 are double balanced modulator-demodulators which produce an output voltage proportional to the product of an input (signal) voltage and a switching (carrier) signal. Typical applications include suppressed carrier modulation, amplitude modulation, synchronous detection, FM or PM detection, broadband frequency doubling and chopping.

The LM1596 is specified for operation over the -55°C to +125°C military temperature range. The LM1496 is specified for operation over the 0°C to +70°C temperature range.

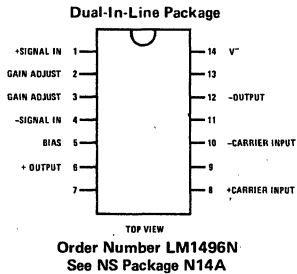
Features

- Excellent carrier suppression
 - 65 dB typical at 0.5 MHz
 - 50 dB typical at 10 MHz
- Adjustable gain and signal handling
- Fully balanced inputs and outputs
- Low offset and drift
- Wide frequency response up to 100 MHz

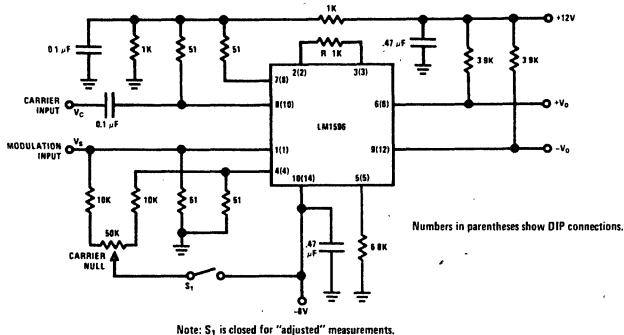
Schematic and Connection Diagrams



Order Number LM1496H or LM1596H
See NS Package H08C



Typical Application and Test Circuit



Suppressed Carrier Modulator

Absolute Maximum Ratings

| | |
|---|------------------------|
| Internal Power Dissipation (Note 1) | 500 mW |
| Applied Voltage (Note 2) | 30V |
| Differential Input Signal ($V_7 - V_8$) | $\pm 5.0V$ |
| Differential Input Signal ($V_4 - V_1$) | $\pm(5+I_B R_{th})V$ |
| Input Signal ($V_2 - V_1, V_3 - V_4$) | 5.0V |
| Bias Current (I_B) | 12 mA |
| Operating Temperature Range | LM1596 -55°C to +125°C |
| | LM1496 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

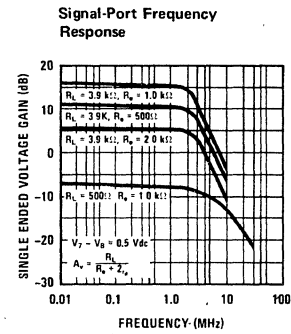
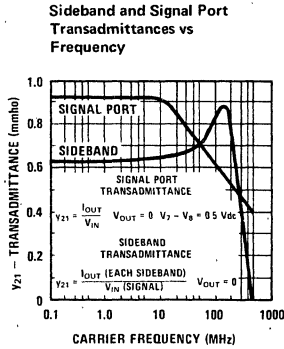
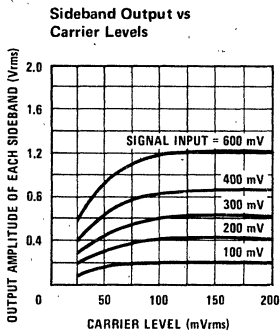
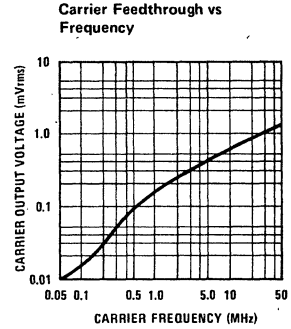
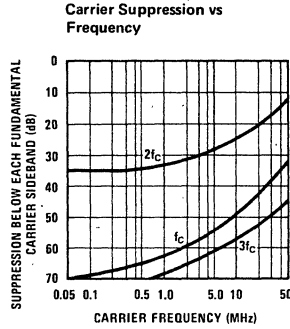
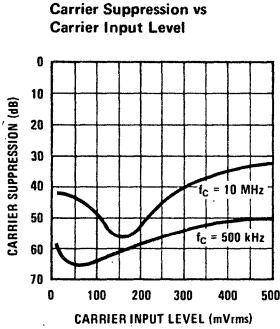
Electrical Characteristics ($T_A = 25^\circ C$, unless otherwise specified, see test circuit)

| PARAMETER | CONDITIONS | LM1596 | | | LM1496 | | | UNITS |
|--|--|--------|------|-----|--------|------|-----|----------------------------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Carrier Feedthrough | $V_C = 60$ mVrms sine wave $f_C = 1.0$ kHz, offset adjusted | | 40 | | | 40 | | μ Vrms |
| | $V_C = 60$ mVrms sine wave $f_C = 10$ MHz, offset adjusted | | 140 | | | 140 | | μ Vrms |
| | $V_C = 300$ mV _{pp} square wave $f_C = 1.0$ kHz, offset adjusted | | 0.04 | 0.2 | | 0.04 | 0.2 | mVrms |
| | $V_C = 300$ mV _{pp} square wave $f_C = 1.0$ kHz, offset not adjusted | | 20 | 100 | | 20 | 150 | mVrms |
| Carrier Suppression | $f_S = 10$ kHz, 300 mVrms $f_C = 500$ kHz, 60 mVrms sine wave offset adjusted | 50 | 65 | | 50 | 65 | | dB |
| | $f_S = 10$ kHz, 300 mVrms $f_C = 10$ MHz, 60 mVrms sine wave offset adjusted | | 50 | | | 50 | | dB |
| Transadmittance Bandwidth | $R_L = 50\Omega$ Carrier Input Port, $V_C = 60$ mVrms sine wave $f_S = 1.0$ kHz, 300 mVrms sine wave | | 300 | | | 300 | | MHz |
| | Signal Input Port, $V_S = 300$ mVrms sine wave $V_7 - V_8 = 0.5Vdc$ | | 80 | | | 80 | | MHz |
| | | | 2.5 | 3.5 | | 2.5 | 3.5 | V/V |
| Voltage Gain, Signal Channel | $V_S = 100$ mVrms, $f = 1.0$ kHz $V_7 - V_8 = 0.5Vdc$ | | | | | | | |
| Input Resistance, Signal Port | $f = 5.0$ MHz $V_7 - V_8 = 0.5 Vdc$ | | 200 | | | 200 | | k Ω |
| Input Capacitance, Signal Port | $f = 5.0$ MHz $V_7 - V_8 = 0.5 Vdc$ | | 2.0 | | | 2.0 | | pF |
| Single Ended Output Resistance | $f = 10$ MHz | | 40 | | | 40 | | k Ω |
| Single Ended Output Capacitance | $f = 10$ MHz | | 5.0 | | | 5.0 | | pF |
| Input Bias Current | $(I_1 + I_4)/2$ | | 12 | 25 | | 12 | 30 | μA |
| Input Bias Current | $(I_7 + I_8)/2$ | | 12 | 25 | | 12 | 30 | μA |
| Input Offset Current | $(I_1 - I_4)$ | | 0.7 | 5.0 | | 0.7 | 5.0 | μA |
| Input Offset Current | $(I_7 - I_8)$ | | 0.7 | 5.0 | | 0.7 | 5.0 | μA |
| Average Temperature Coefficient of Input Offset Current | $(-55^\circ C < T_A < +125^\circ C)$ $(0^\circ C < T_A < +70^\circ C)$ | | 2.0 | | | 2.0 | | nA/ $^\circ C$ nA/ $^\circ C$ |
| Output Offset Current | $(I_6 - I_9)$ | | 14 | 50 | | 14 | 60 | μA |
| Average Temperature Coefficient of Output Offset Current | $(-55^\circ C < T_A < +125^\circ C)$ $(0^\circ C < T_A < +70^\circ C)$ | | 90 | | | 90 | | nA/ $^\circ C$ nA/ $^\circ C$ |
| Signal Port Common Mode Input Voltage Range | $f_S = 1.0$ kHz | | 5.0 | | | 5.0 | | V _{pp} |
| Signal Port Common Mode Rejection Ratio | $V_7 - V_8 = 0.5 Vdc$ | | -85 | | | -85 | | dB |
| Common Mode Quiescent Output Voltage | | | 8.0 | | | 8.0 | | Vdc |
| Differential Output Swing Capability | | | 8.0 | | | 8.0 | | V _{pp} |
| Positive Supply Current | $(I_6 + I_9)$ | | 2.0 | 3.0 | | 2.0 | 3.0 | mA |
| Negative Supply Current | (I_{10}) | | 3.0 | 4.0 | | 3.0 | 4.0 | mA |
| Power Dissipation | | | 33 | | | 33 | | mW |

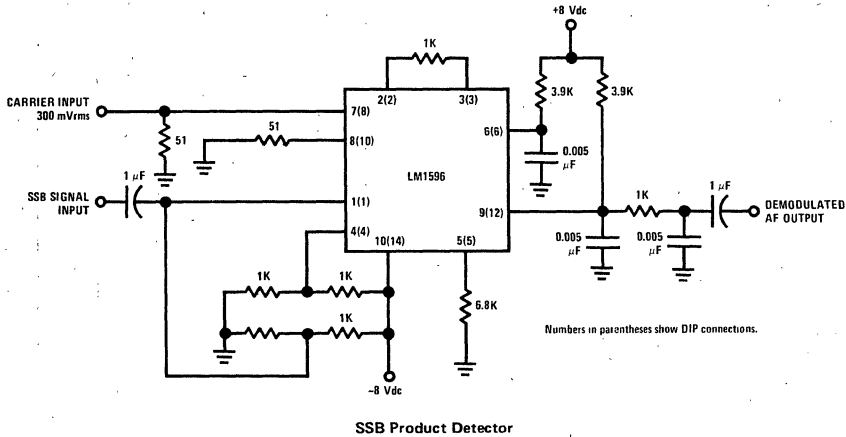
Note 1: LM1596 rating applies to case temperatures to +125°C; derate linearly at 6.5 mW/ $^\circ C$ for ambient temperature above 75°C. LM1496 rating applies to case temperatures to +70°C.

Note 2: Voltage applied between pins 6-7, 8-1, 9-7, 9-8, 7-4, 7-1, 8-4, 6-8, 2-5, 3-5.

Typical Performance Characteristics

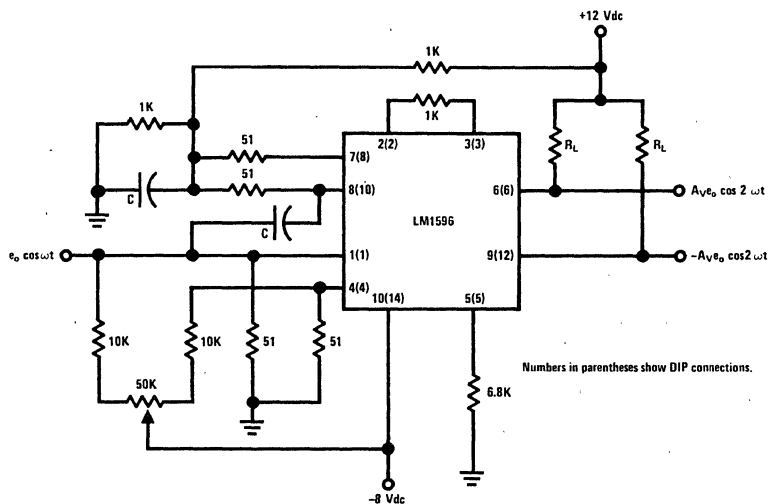


Typical Applications (Continued)



This figure shows the LM1596 used as a single sideband (SSB) suppressed carrier demodulator (product detector). The carrier signal is applied to the carrier input port with sufficient amplitude for switching operation. A carrier input level of 300 mVrms is optimum. The composite SSB signal is applied to the signal input port with an amplitude of 5.0 to 500 mVrms. All output signal components except the desired demodulated audio are filtered out, so that an offset adjustment is not required. This circuit may also be used as an AM detector by applying composite and carrier signals in the same manner as described for product detector operation.

Typical Applications (Continued)



Broadband Frequency Doubler

The frequency doubler circuit shown will double low-level signals with low distortion. The value of C should be chosen for low reactance at the operating frequency.

Signal level at the carrier input must be less than 25 mV peak to maintain operation in the linear region of the switching differential amplifier. Levels to 50 mV peak may be used with some distortion of the output waveform. If a larger input signal is available a resistive divider may be used at the carrier input, with full signal applied to the signal input.

LM1800 Phase-Locked Loop FM Stereo Demodulator

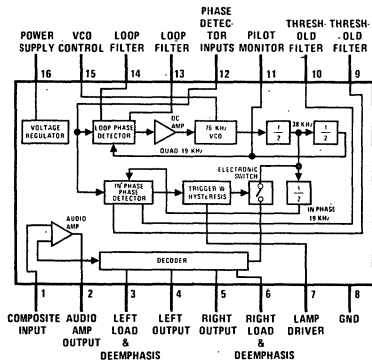
General Description

The LM1800 is a second generation integrated FM stereo demodulator using phase locked loop techniques to regenerate the 38 kHz subcarrier. The numerous features integrated on the die make possible a system delivering high fidelity sound while still meeting the cost requirements of inexpensive stereo receivers. More information available in AN-81.

Features

- Automatic stereo/monaural switching
- 45 dB power supply rejection
- No coils, all tuning performed with single potentiometer
- Wide operating supply voltage range
- Excellent channel separation
- Emitter follower output buffers

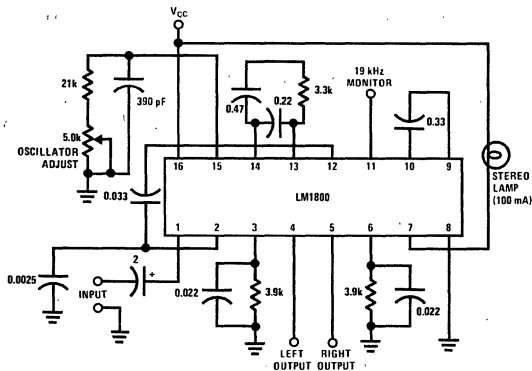
Connection Diagram



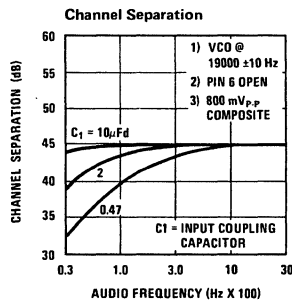
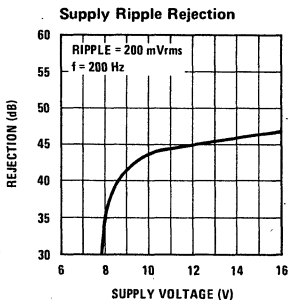
TOP VIEW

Order Number LM1800N
See NS Package N16A

Typical Application



Typical Performance Characteristics



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 18V |
| Power Dissipation (Note 3) | 715 mW |
| Operating Temperature Range | 0°C to +70°C |
| Operating Supply Voltage Range | +10V to +18V |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------------------|--|------|------|------|------------|
| Supply Current | Lamp "off" | | 21 | 30 | mA |
| Lamp Driver Saturation | 100 mA Lamp Current | | 1.3 | 1.8 | V |
| Lamp Driver Leakage | | | 1.0 | | nA |
| Pilot Level for Lamp "ON" | Pin 11 Adjusted to 19.00 kHz | | 15 | 20 | mVrms |
| Pilot Level for Lamp "OFF" | Pin 11 Adjusted to 19.00 kHz | 3.0 | 7.0 | | mVrms |
| Stereo Lamp Hysteresis | | 3.0 | 6.0 | | dB |
| Stereo Channel Separation | 100 Hz (Note 2) | | 40 | | dB |
| | 1000 Hz (Note 2) | 30 | 45 | | dB |
| | 10000 Hz (Note 2) | | 45 | | dB |
| Monaural Channel Unbalance | 200 mVrms, 1000 Hz Input | | 0.3 | 1.5 | dB |
| Monaural Voltage Gain | 200 mVrms, 400 Hz Input | 140 | 200 | 260 | mVrms |
| Total Harmonic Distortion | 500 mVrms, 1000 Hz Input | | 0.4 | | % |
| Total Harmonic Distortion | 500 mVrms, 1000 Hz Input, 1800A Only | | 0.1 | 0.3 | % |
| Capture Range | 25 mVrms of Pilot | ±2.0 | | ±6.0 | % of f_0 |
| Supply Ripple Rejection | 200 mVrms of 200 Hz Ripple | 35 | 45 | | dB |
| Dynamic Input Resistance | | 20 | 45 | | k Ω |
| Dynamic Output Resistance | | 900 | 1300 | 2000 | Ω |
| SCA Rejection | (Note 4) | | 70 | | dB |
| Ultrasonic Freq. Rejection | Combined 19 and 38 kHz, Ref. to Output | | 33 | | dB |

Note 1: $T_A = 25^\circ\text{C}$ and $V^+ = 12\text{V}$ unless otherwise specified.

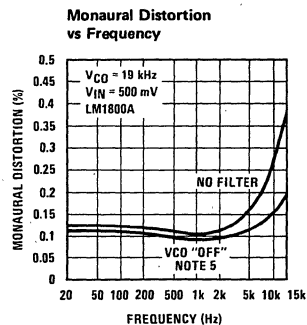
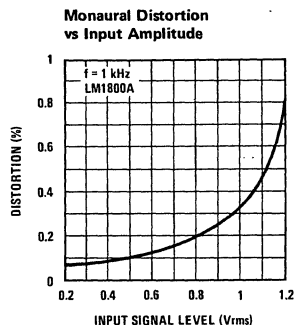
Note 2: The stereo input signal is made by summing 123 mVrms LEFT or RIGHT modulated signal with 25 mVrms of 19 kHz pilot tone, measuring all voltages with an average responding meter calibrated in rms. The resulting waveform is about 800 mVp-p.

Note 3: For operation in ambient temperatures above 25°C , the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Note 4: Measured with a stereo composite signal consistency of 80% stereo, 10% pilot and 10% SCA as defined in the FCC Rules on Broadcasting.

Note 5: VCO "OFF" curve represents the distortion attainable using good 19 kHz and 38 kHz filters.

Typical Performance Characteristics (Continued)



LM1818 Electronically Switched Audio Tape System

General Description

The LM1818 is a linear integrated circuit containing all of the active electronics necessary for building a tape recorder deck (excluding the bias oscillator). The electronic functions on the chip include: a microphone and playback preamplifier, record and playback amplifiers, a meter driving circuit, and an automatic input level control circuit. The IC features complete internal electronic switching between the record and playback modes of operation. The multipole switch used in previous systems to switch between record and playback modes is replaced by a single pole switch, thereby allowing for more flexibility and reliability in the recorder design.*

*Monaural operation, Figure 9.

Features

- Electronic record/play switching
- 85 dB power supply rejection
- Motional peak level meter circuitry
- Low noise preamplifier circuitry
- 3.5V to 18V supply operation
- Provision for external low noise input transistor

Order Number LM1818N
See NS Package N20A

Typical Applications

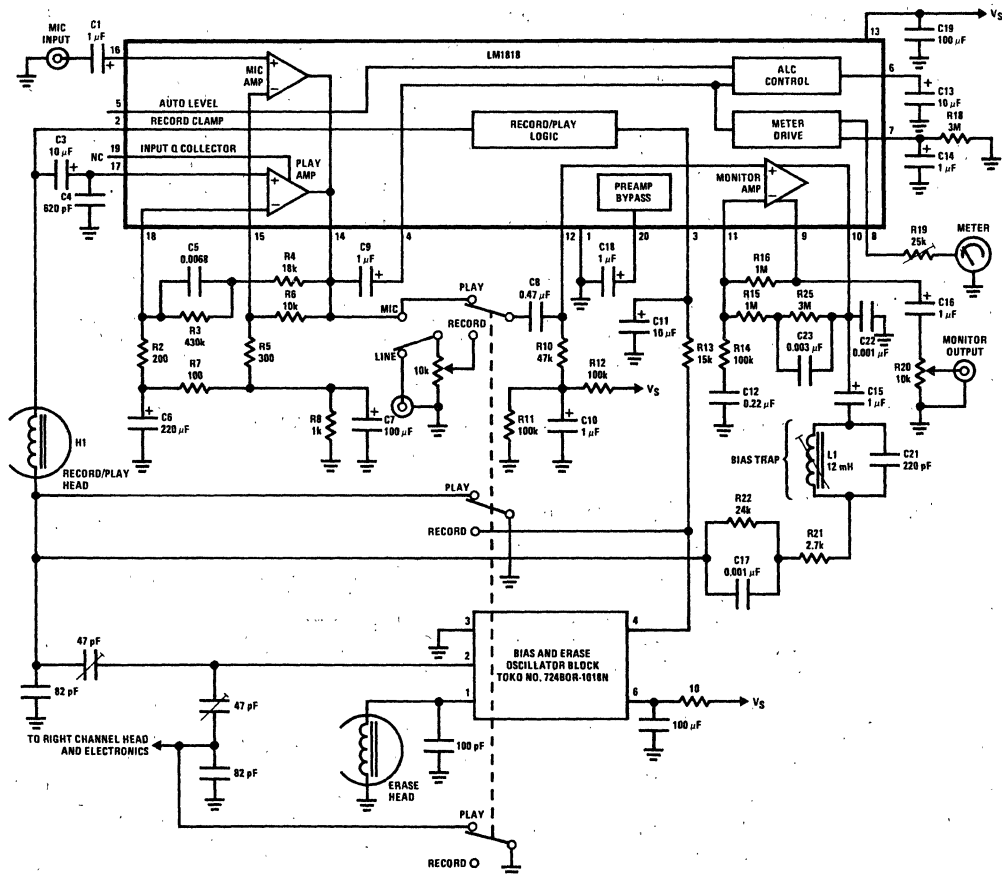


FIGURE 1. Stereo Application Circuit (Left Channel Shown), $V_S = 15V$

Absolute Maximum Ratings

| | |
|--|----------------------|
| Supply Voltage | 18V |
| Package Dissipation, (Note 1) | 715 mW |
| Storage Temperature | -65°C to +150°C |
| Operating Temperature | 0°C to +70°C |
| Junction Temperature | 150°C |
| Minimum Voltage on Any Pin | -0.1 V _{DC} |
| Maximum Voltage on Pins 2 and 5 | 0.1 V _{DC} |
| Maximum Current Out of Pin 14 | 5 mA _{DC} |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $V_{CC} = 6V, T_A = 25^\circ C$, See Test Circuits (Figures 2 and 3)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|------|-----|-------------------|
| Operating Supply Voltage Range | | 3.5 | | 18 | V _{DC} |
| Supply Current | Test Circuit (Figure 2) | | 5 | 12 | mA |
| Turn-ON Time | Externally Programmable | 50 | 400 | | ms |
| Playback Signal to Noise | DIN Eq. (3180 and 120 μ s), 20–20 kHz, $R_S = 0$, Unweighted, $V_{REF} = 1$ mV at 400 Hz | | 74 | | dB |
| Record Signal to Noise | Flat Gain, 20–20 kHz, $R_S = 0$, ALC OFF, $V_{REF} = 1$ mV at 1 kHz, Unweighted | | 69 | | dB |
| Fast Turn-ON Charging Current | Pins 16 and 17 | | 200 | | μ A |
| Record and Playback Preamplifier Open Loop Voltage Gain | $f = 100$ Hz | | 100 | | dB |
| Preamplifiers' Input Impedance | | | 50 | | k Ω |
| Preamplifiers' Input Referred PSRR | 1 kHz—Flat Gain | | 85 | | dB |
| Bias Voltage on Pin 18 in Play Mode or Pin 15 in Record Mode | | | 0.5 | | V |
| Monitor Amplifier Input Bias Current | Pins 11 and 12 | | 0.5 | | μ A |
| Monitor Amplifier Open Loop Voltage Gain | Record or Playback, $f = 100$ Hz | | 80 | | dB |
| Monitor Outputs Current Capability | Pins 9 and 10, Source Current Available | 400 | 750 | | μ A |
| Monitor Amplifier's Output Swing | $R_L = 10k$, AC Load | 1.2 | 1.65 | | V _{rms} |
| THD, All Amplifiers | At 1 kHz, 40 dB Closed Loop Gain | | 0.05 | | % |
| Record-Playback Switching Time | As in Test Circuit | | 50 | | ms |
| Input ALC Range | ΔV_{IN} for $\Delta V_{OUT} = 8$ dB | | 40 | | dB |
| Input Voltage on ALC Pin for Start of ALC Action | | | 25 | | mV _{rms} |
| ALC Input Impedance | | | 2 | | k Ω |
| ALC Attack Time | $C_{13} = 10 \mu F$ | | 7 | | ms |
| ALC Decay Time | $R_{17} = \infty, C_{13} = 10 \mu F$ | | 30 | | sec |
| Meter Output Gain | 100 mV _{rms} at 1 kHz into Pin 4 | | 800 | | mV _{DC} |
| Meter Output Current Capability | | 2 | | | mA _{DC} |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Test Circuits

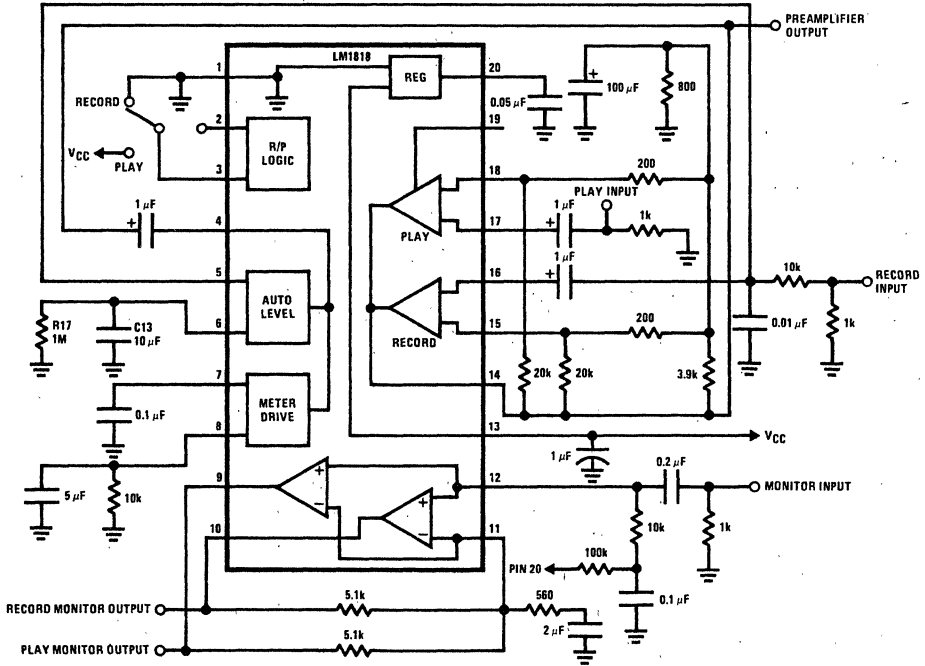


FIGURE 2. General Test Circuit

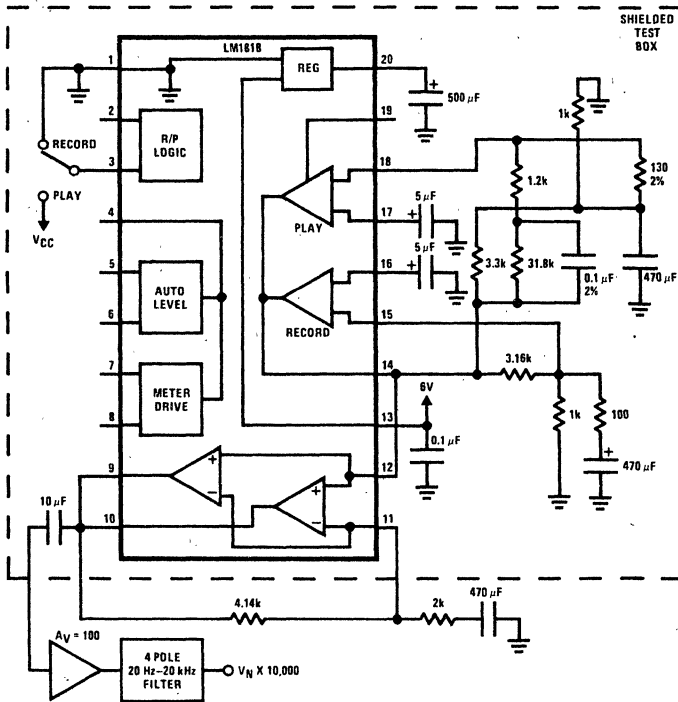


FIGURE 3. Noise Test Circuit

Equivalent Schematic Diagram

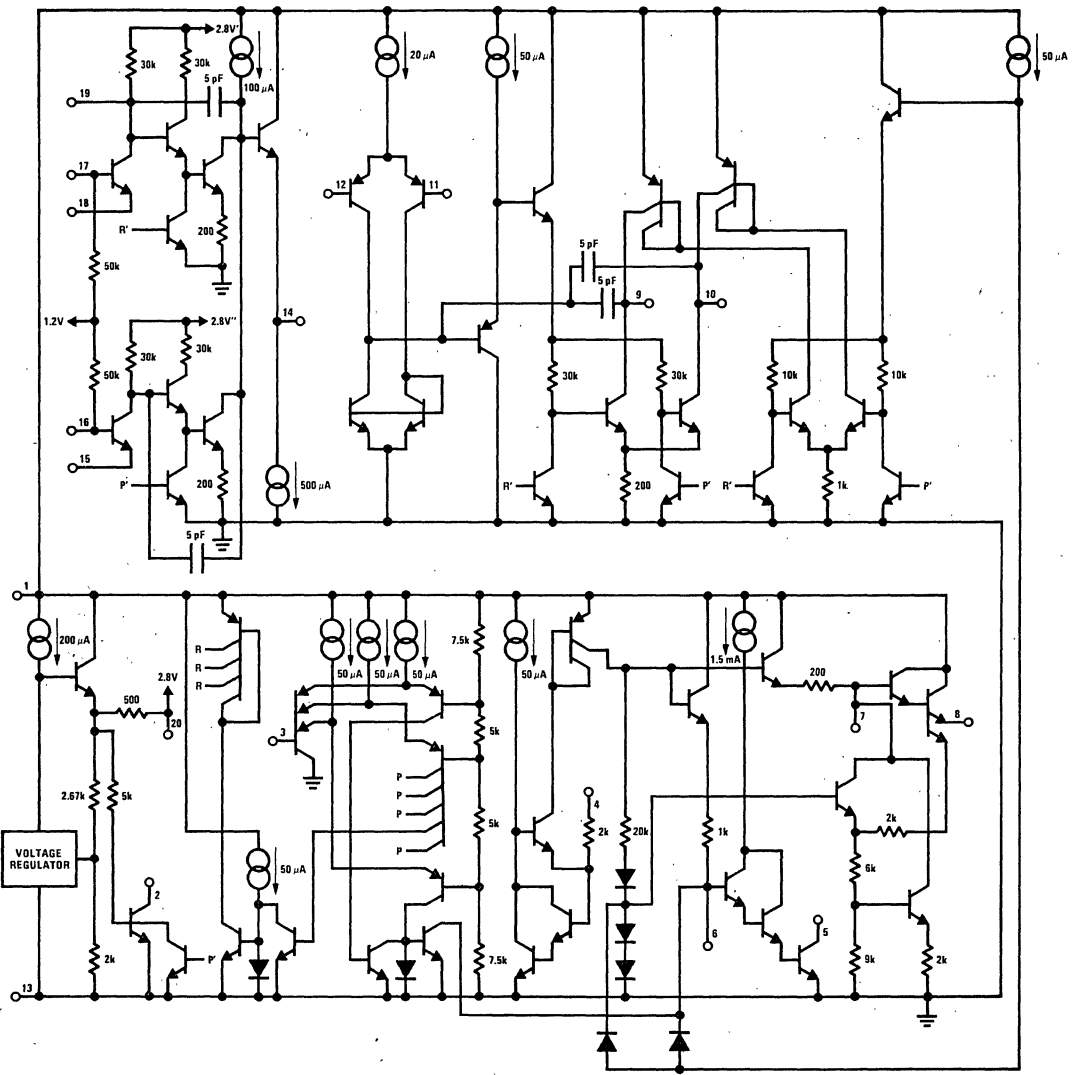
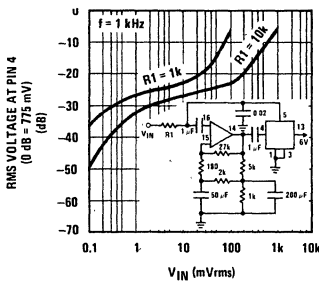


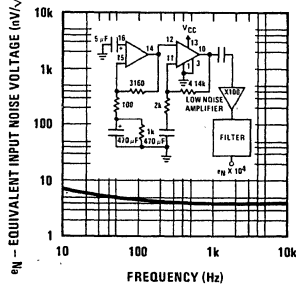
FIGURE 4

Typical Performance Characteristics

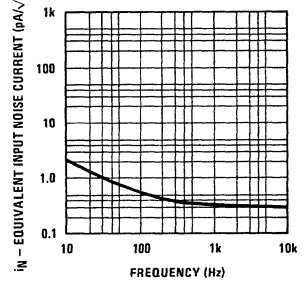
Automatic Level Control (ALC) Response Characteristic



Preamp Input Noise Voltage



Preamp Input Noise Current



Application Hints

Preamplifiers (Figure 5)

There are 2 identical preamplifiers with 1 common output pin on the IC. One amplifies low level inputs such as a microphone in the record mode and another amplifies the signal from the playback head in the playback mode. The amplifiers use a common capacitor, C6, to set the low frequency pole of the closed loop responses. On the playback amplifier, the collector of the input device is made available so that an external low noise device can be connected in critical applications. When using an external low noise transistor, pins 17 and 18 of the IC are shorted together to ensure that the internal input transistor is turned OFF and the external transistor's collector is tied to pin 19. The input and feedback connections are now made to the external input transistor. The amplifiers are stable for all gains above 5 and have a typical open loop gain of 100 dB. R8 and R9 enable C6 to be quickly charged and set the DC gain. Internal biasing provides a DC voltage independent of temperature at pin 17 so that the preamplifier DC output will remain relatively constant with temperature. Supply decoupling is provided by an internal regulator. Additional decoupling can be added for the input stages by increasing the size of the capacitor on pin 20 of the IC. A fast charging circuit is connected to the preamplifiers' input capacitors (pins 16 and 17) to decrease the turn-ON time. Larger input capacitors decrease the noise by reducing the source impedance at lower frequencies where 1/f noise current produces an input noise voltage. The input resistance of the preamplifiers is typically 50 k Ω .

Monitor and Record Amplifiers (Figure 6)

The monitor and record amplifiers share common input and feedback connections but have separate outputs. During playback, the input signal is amplified and appears only at the playback monitor output. Because

the outputs are separate, different feedback components can be used and, as a result, totally different responses can be set. The amplifiers are stable for all closed loop gains above 3 and have an open loop gain of typically 80 dB. The outputs are capable of supplying a minimum of 400 μ A into a load and swing within 500 mV of either V_{CC} or ground. If more than 400 μ A is needed to drive a load, an external pull-up resistor on the output of these amplifiers can increase the load driving capability.

Automatic Level Control – ALC (Figure 7)

The automatic level control provides a constant output level for a wide range of record source input levels. The ALC works on the varying impedance characteristic of a saturated transistor. The impedance of the saturated transistor forms a voltage divider with the source impedance of a series resistor (R1 in Figure 9). The input signal is decreased as the ALC transistor is increasingly forward biased. The ALC transistor will be forward biased when the preamplifier's AC output (pin 14), coupled to the combination ALC-meter drive input (pin 4) reaches 40 mV peak (25 mVrms). The gain of the ALC loop is such that a preamp input signal increase of 10 dB will result in a 2 dB increase on the AC output of the preamplifier. If greater than 25 mVrms is desired at the output of the preamp, a series resistor can be added between the preamp output coupling capacitor and the ALC input (pin 4). The input impedance of the ALC circuit is 2 k Ω ; therefore, if a 2 k Ω series resistor is added, ALC action will begin at 50 mVrms.

The ALC memory capacitor connected to pin 6 has the additional function of amplifier anti-pop control; for this reason, it is necessary that a capacitor be connected to pin 6 even if ALC is not used.

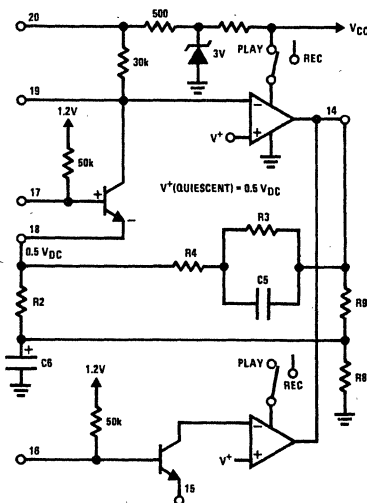


FIGURE 5. Preamplifier

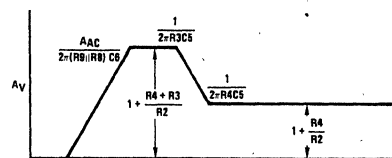
Quiescent DC Output Voltage

$$V_{DC} = \left(1 + \frac{R_9}{R_8}\right) (0.5 - 50 \times 10^{-6} R_2) \text{V if } R_2 + R_3 > 10 R_E$$

$$\text{where } R_E = \frac{R_8 R_9}{R_8 + R_9}$$

AC Voltage Gain

$$A_{AC} = \frac{R_4 + \frac{R_3}{1 + sC_5 R_3}}{R_2} + 1$$



Application Hints (Continued)

Meter Driving—Motional Peak Level Response (Figure 7)

The meter drive output (pin 8) is capable of supplying 1–2 mA at a filtered DC voltage that is typically equal to 10 times the RMS value of the signal applied to the ALC-meter drive input pin (pin 4). The RC network connected to pin 7 of the IC determines the memory constant of the meter circuit. It is therefore possible to store the peak input signal by giving this RC network a long time constant, or read the instantaneous signal level by giving this RC network a very short time constant (i.e., no capacitor). This memory capacitor is discharged within the integrated circuit at a discharge rate related to the DC level on the meter output pin. When the meter output pin is between 0 V_{DC} and 0.7 V_{DC} there is a 50 μA discharge current; when the

pin is between 0.7V and 1.1V there is no internal discharge current; and when the voltage on pin 8 is greater than 1.1V there is a discharge equivalent to a 3.3k resistor across the memory capacitor. These different discharge rates allow the meter circuit to display fast, accurate responses on the lower portion of the meter display, slow responses in the higher portion of the meter display, and rapid discharge when the voltage is above the maximum reading the meter can display. The resistor in series with the meter can be adjusted such that the previously mentioned responses coincide with the proper points (0 VU and +3 VU) on the meter scale.

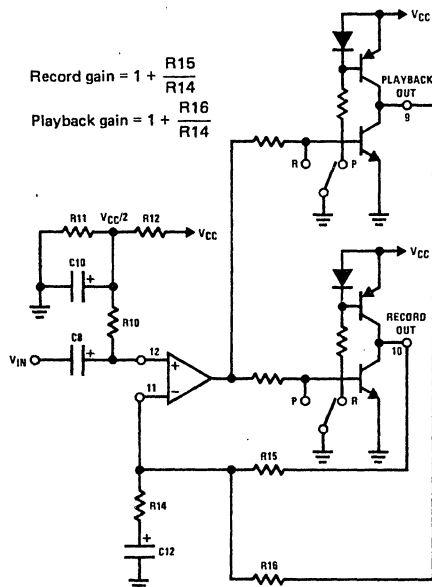


FIGURE 6. Monitor Amplifier

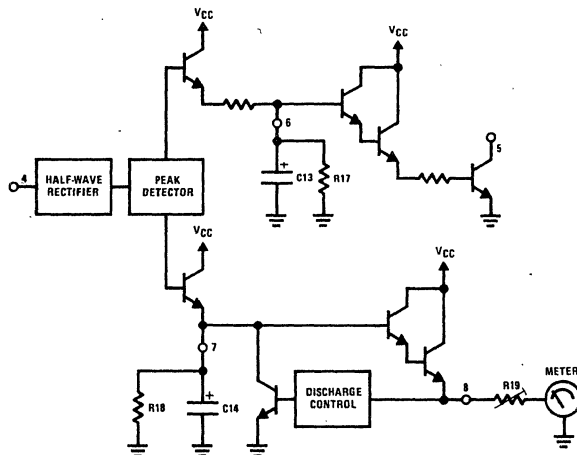


FIGURE 7. Auto Level-Meter Circuit

Application Hints (Continued)

Anti-Pop Circuitry (Figure 8)

The capacitor on pin 3 is used in a time delay system in conjunction with C13, the ALC capacitor, to suppress pops when switching between record and playback. Figure 8 illustrates how this is done. The output amplifier, either record or playback, is shut off prior to switching and carefully rebased after switching takes place. It is therefore required that a proper ratio is selected between the ALC capacitor and the logic input RC time constant. The ALC capacitor must be discharged to 0.7V within the time it takes the logic input capacitor to: 1) charge from $V_{CC}/2$ to 0.7 V_{CC} when switching from record to playback, or 2) discharge from $V_{CC}/2$ to 0.3 V_{CC} when switching from playback to record. These times would normally be similar; however, the ALC capacitor can be charged to a different initial value depending upon the input to the ALC circuit. The maximum value to which the ALC memory capacitor will normally charge is 3.2V, therefore, the maximum time allowed for discharging C13 is given by:

$$t_1 = \frac{(C13 \times \Delta V)}{I_1} = C13 \frac{(3.2V - 0.7V)}{350 \mu A}$$

$$= C13 \times 7.2 \times 10^4$$

If $C13 = 10 \mu F$, $t_1 = 72 \text{ ms}$

It is now necessary to determine the minimum value for the R/P logic capacitor. This is done by computing the time between the 2 voltage switching points using the exponential equations for a single RC network.

$$t_2 = R13 C11 \ln \left[\frac{V_{CC}}{0.3 V_{CC}} \right] -$$

$$R13 C11 \ln \left[\frac{V_{CC}}{0.5 V_{CC}} \right] = 0.51 R13 C11$$

To be sure that C13 is completely discharged, let $t_2 > t_1$.

$$R13 C11 > \frac{t_1}{0.51} = \frac{(72 \text{ ms})}{0.15} = 141 \text{ ms}$$

If $C11 = 10 \mu F$, $R13 = 15 \text{ k}\Omega$

$R13$ should be kept to a value less than $50 \text{ k}\Omega$ to insure that bias current existing from pin 3 does not cause an offset voltage above 200 mV. Typically this bias current is less than $3 \mu A$.

Record Playback Switch

When the voltage on pin 3 of the IC is greater than $0.5 V_{CC}$, the internal record-playback switch switches into the playback mode. During playback the record preamplifier remains partially biased but the input signal to this preamp does not appear at the preamplifier output. In addition, during the playback mode, the record monitor output (pin 9) is disabled and the ALC circuit operates to minimize the signal into the record preamp input. The meter circuit is operational in the playback as well as the record mode. Similarly, during the record mode, the playback preamp input is ignored and the playback monitor output is disabled. In addition, a pin is available to hold one side of the record head at ground potential while sinking up to $500 \mu A$ of AC bias and record current.

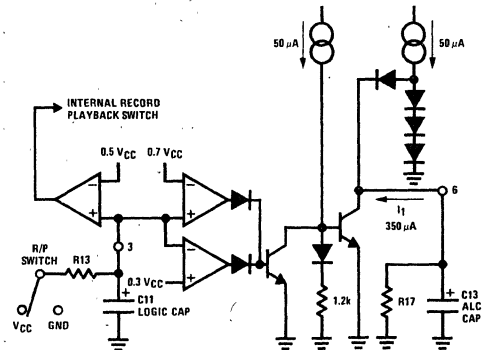


FIGURE 8A. Anti-Pop Circuit

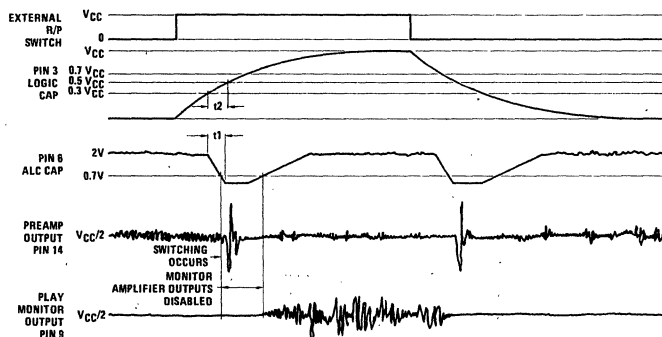


FIGURE 8B. Waveform for Anti-Pop Circuit

External Components

(Refer to Figure 9, Monaural Application Circuit)

| COMPONENT | EXTERNAL COMPONENT FUNCTION | NORMAL RANGE OF VALUE |
|-----------|---|---|
| R1 | Used in conjunction with varying impedance of pin 5, forming a resistor divider network to reduce input level in automatic level control circuit | 500 Ω –20 k Ω |
| C2 | Forms a noise reduction system by varying bandwidth as a function of the changing impedance on pin 5. With a small input signal, the bandwidth is reduced by R1 and C2. As the input level increases, so does the bandwidth. | 0.01 μ F–0.5 μ F |
| C1, C3 | Coupling capacitors. Because these are part of the source impedance, it is important to use the larger values to keep low frequency source impedance at a minimum. | 0.5 μ F–10 μ F |
| C4 | Radio frequency interference roll-off capacitor | 100 pF–300 pF |
| R2 | Playback response equalization. C5 and R3 form a pole in the amplifier response at 50 Hz. C5 and R4 form a zero in the response at 1.3 kHz for 120 μ s equalization and 2.3 kHz for 70 μ s equalization. | 50 Ω –200 Ω |
| R3 | | 47 k Ω –3.3 M Ω |
| R4 | | 2 k Ω –200 k Ω |
| C5 | | |
| R5 | Microphone preamplifier gain equalization | 50 Ω –200 Ω |
| R6 | | 5 k Ω –200 k Ω |
| R7 | DC feedback path. Provides a low impedance path to the negative input in order to sink the 50 μ A negative input amplifier current. C6, R9, R7 and C7 provide isolation from the output so that adequate gain can be obtained at 20 Hz. This 2-pole technique also provides fast turn-ON settling time. | 0–2 k Ω |
| R8 | | 200 Ω –5 k Ω |
| R9 | | 1 k Ω –30 k Ω |
| C6 | | 200 μ F–1000 μ F |
| C7 | | 0–100 μ F |
| C8 | Preamplifier output to monitor amplifier input coupling | 0.05 μ F–1 μ F |
| C9 | ALC coupling capacitor. Note that ALC input impedance is 2 k Ω | 0.1 μ F–5 μ F |
| R10 | These components bias the monitor amplifier output to half supply since the amplifier is unity gain at DC. This allows for maximum output swing on a varying supply. | 10 k Ω –100 k Ω |
| R11 | | 10 k Ω –100 k Ω |
| R12 | | 10 k Ω –100 k Ω |
| C10 | | 1 μ F–100 μ F |
| C11 | Exponentially falling or rising signal on pin 3 determines sequencing, time delay, and operational mode of the record/play anti-pop circuitry. See anti-pop diagram. | 0–10 μ F |
| R13 | | 0–50 k Ω |
| R14 | R16, R14 and C12 determine monitor amplifier response in the play mode. R15, R14 and C12 determine monitor amplifier response in the record mode. | 1k–100k |
| R15 | | 30 k Ω –3 M Ω |
| R16 | | 30 k Ω –3 M Ω |
| C12 | | 0.1 μ F–20 μ F |
| C13 | Determines decay response on ALC characteristic and reduces amplifier pop | 5 μ F–20 μ F |
| R17 | | 100k– ∞ |
| C14 | Determines time constant of meter driving circuitry | 0.1 μ F–10 μ F |
| R18 | | 100k– ∞ |
| R19 | Meter sensitivity adjust | 10 k Ω –100 k Ω |
| C15 | Record output DC blocking capacitor | 1 μ F–10 μ F |
| C16 | Play output DC blocking capacitor | 0.1 μ F–10 μ F |
| C17 | Changes record output response to approximate a constant current output in conjunction with record head impedance resulting in proper recording equalization | 500 pF–0.1 μ F |
| R21 | | 5 k Ω –100 k Ω |
| R22 | | 5 k Ω –100 k Ω |
| C18 | Preamplifier supply decoupling capacitor. Note that large value capacitor will increase turn-ON time | 0.1 μ F–500 μ F |
| C19 | Supply decoupling capacitor | 100 μ F–1000 μ F |
| C20 | Decouples bias oscillator supply | 10 μ F–500 μ F |
| R23 | Allows bias level adjustment | 0–1 k Ω |
| R24 | Adjusts DC erase current in DC erase machines (for AC erase, "Stereo Application Hook-up") | |
| L1 | Optional bias trap | 1 mH–30 mH |
| C21 | | 100 pF–2000 pF |
| C22 | Bias Roll-Off | 0.001 μ F–0.01 μ F |
| H1 | Record/play head | 100 Ω –500 Ω ; 70 mH–300 mH |
| H2 | Erase head (DC type, AC optional) | 10 Ω –300 Ω |

Typical Applications (Continued)

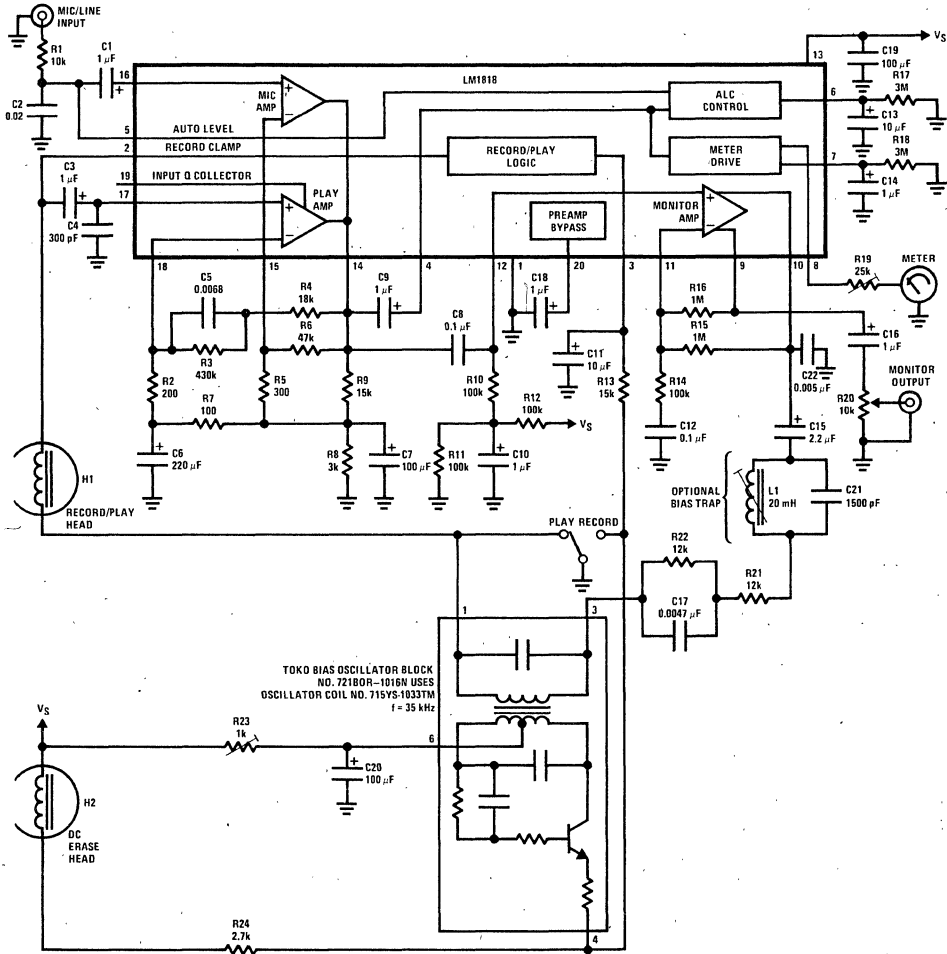


FIGURE 9A. Monaural Application Circuit

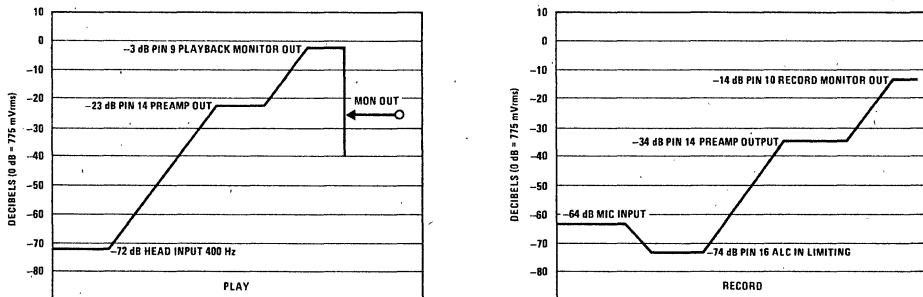


FIGURE 9B. Level Diagram for Monaural Application Circuit

LM1828, LM1848 Color Television Chroma Demodulator

General Description

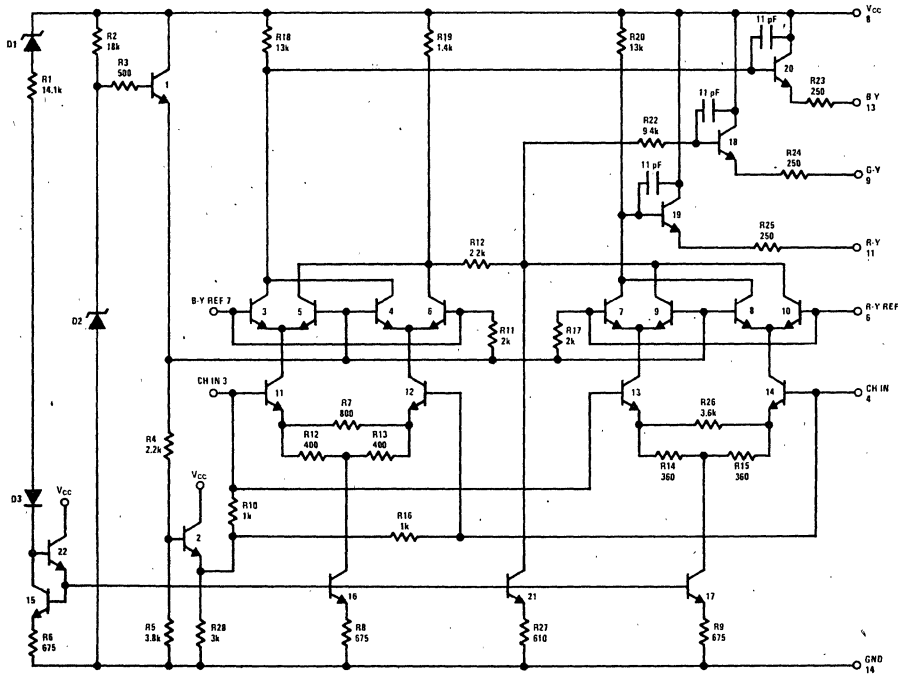
The LM1828, LM1848 are monolithic silicon integrated circuits which demodulate the chroma sub-carrier information contained in a color television video signal and provide color-difference signals at the outputs.

The low dc voltage drift of the outputs insures excellent performance in direct-coupled chrominance output circuitry.

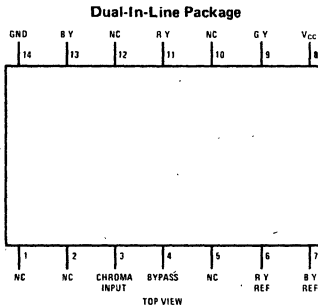
Features

- Low output voltage drift with temperature
- Doubly balanced demodulation
- 10 V_{p-p} E_B-E_Y output
- Built-in ripple filter capacitors
- Standard matrix in LM1828
- Revised matrix in LM1848
- Pin compatible with LM746, CA3072

Schematic Diagram



Connection Diagram



Order Number LM1828N
or LM1848N
See NS Package N14A

Absolute Maximum Ratings

| | |
|-----------------------------|-----------------|
| Power Dissipation (Note 2) | 715 mW |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Supply Voltage | 30V |
| Reference Input | 5 Vp-p |
| Chroma Input | 5 Vp-p |

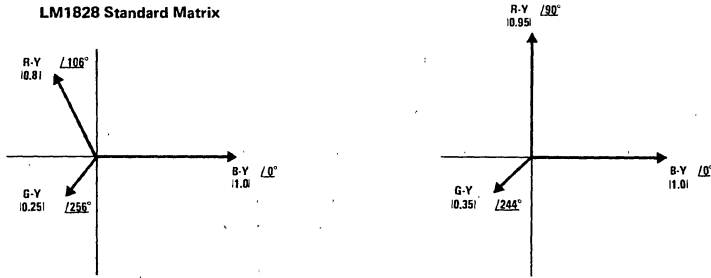
Electrical Characteristics $T_A = 25^\circ\text{C}$, $V_{CC} = 24\text{V}$, $R_L = 3.3\text{k}$, Note 1

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------|--------------------------|---------------------------------|------|------|------|-------|
| STATIC | | | | | | |
| I_s | Supply Current | $e_c = 0$ $R_L = 1\text{M}$ | 5.5 | 9.0 | 12.5 | mA |
| | | $R_L = 3.3\text{k}$ | 16.5 | 22 | 25.5 | mA |
| P_D | Power Dissipation | $e_c = 0$ | | 340 | 430 | mW |
| V9, V11, V13 | dc Output Voltage | $e_c = 0$, $R_L = 3.3\text{k}$ | 13 | 14.5 | 16 | V |
| $ \Delta V_O $ | Output Differential | $e_c = 0$, $R_L = 3.3\text{k}$ | | 100 | 600 | mV |
| | Output Tempo | $e_c = 0$ | | 3 | | mV/°C |
| V6, V7 | Reference Input dc | | | 6.2 | | V |
| V3, V4 | Chroma Input dc | | | 3.4 | | V |
| DYNAMIC | | | | | | |
| e_c | Chroma Input Sensitivity | B-Y = 5 Vp-p | | 0.4 | 0.7 | Vp-p |
| V13 | Max B-Y Output | $e_c = 1.5$ Vp-p | 8 | 10 | | Vp-p |
| | ac Unbalance | $e_c = 0$ | | 0.1 | 0.8 | Vp-p |
| V9, V11, V13 | Residual Carrier | B-Y = 5 Vp-p | | | 1.5 | Vp-p |
| | R-Y Output | B-Y = 5 Vp-p | | | | |
| | LM1828 | | 3.5 | 3.8 | 4.2 | Vp-p |
| | LM1848 | | 4.2 | 4.75 | 5.25 | Vp-p |
| | G-Y Output | | | | | |
| | LM1828 | | 0.75 | 1.0 | 1.25 | Vp-p |
| | LM1848 | | 1.3 | 1.75 | 2.2 | Vp-p |

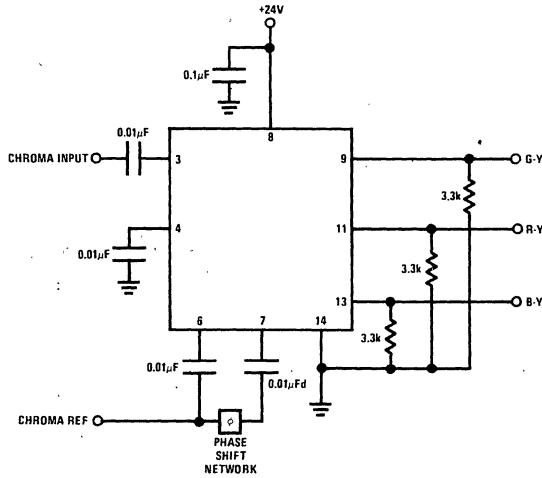
Note 1: Values measured in test circuit.

Note 2: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

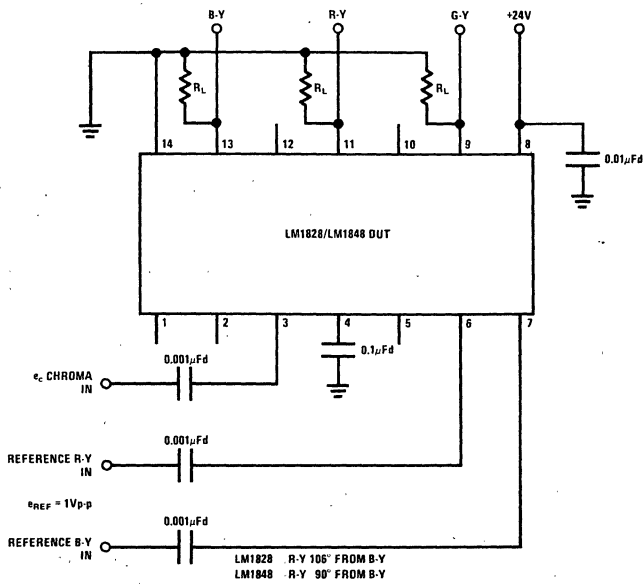
Typical Vector Output Diagrams



Typical Application



Test Circuit



LM1870 Stereo Demodulator with Blend

General Description

The LM1870 is a phase locked loop FM stereo demodulator with a DC control pin for reducing noise by decreasing separation during weak signal conditions.

Applications

- Automobile radios
- Hi Fi receivers and tuners
- High performance portable radios

Features

- Blend control
- Large input overload
- Low beat note distortion
- Low THD diode switching outputs
- VCO stop function
- Wide supply range, 7V to 15V
- Mono override pin

Typical Application and Test Circuit

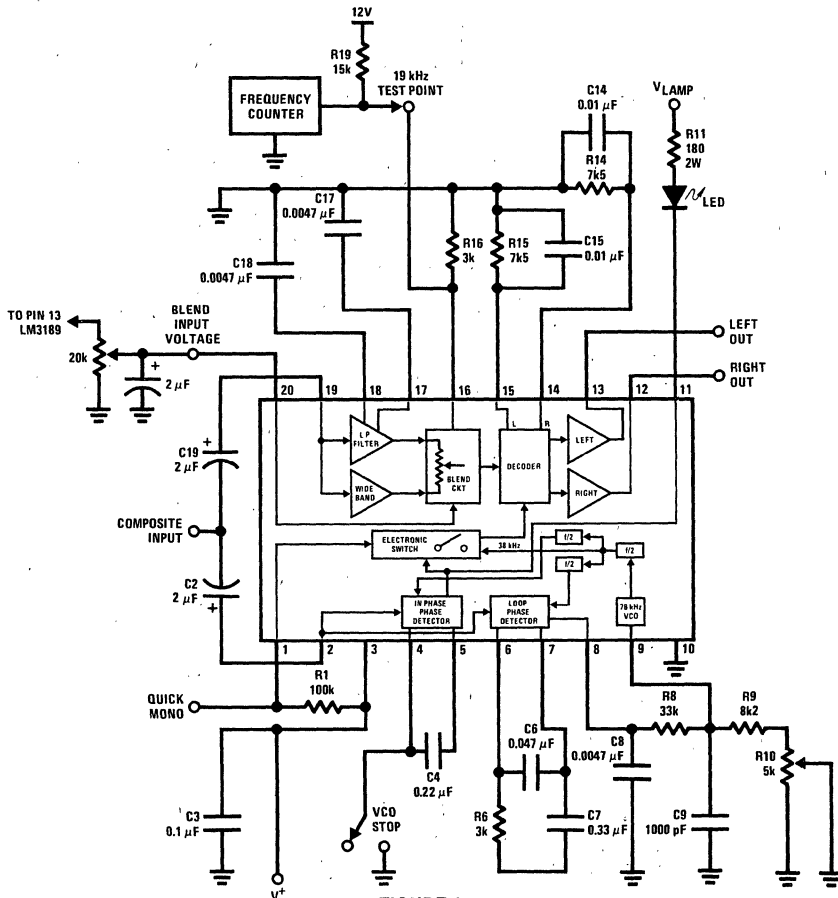


FIGURE 1

Pin Functions

- | | | | |
|----------------------------|---------------|------------------------------|---|
| 1 Quick Mono | 6 Loop Filter | 11 Lamp Driver | 16 Blend Resistor and 19 kHz Test Point |
| 2 PLL Input | 7 Loop Filter | 12 Right Output | 17 Blend Filter |
| 3 V+ | 8 VCO Tuning | 13 Left Output | 18 Blend Filter |
| 4 Lamp Filter and VCO Stop | 9 VCO Tuning | 14 Right Gain and Deemphasis | 19 Audio Input |
| 5 Lamp Filter | 10 Ground | 15 Left Gain and Deemphasis | 20 Blend Control Voltage |

Absolute Maximum Ratings

| | |
|--|------------------------|
| Supply Voltage, Pin 3 | 15V |
| Lamp Driver Voltage, Pin 11 | 18V |
| Output Voltage, Pin 12, 13, Supply Off | 7V |
| Quick Mono Input (Pin 1) | V ⁺ (Pin 3) |
| Blend Input (Pin 20) | 15V |
| Operating Temperature Range | 0°C to +70°C |
| Power Dissipation (Note 1) | 1W |
| Storage Temperature | -65°C to +125°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $V^+ = 8\text{V}$, Figure 1

| Parameter | Conditions | Min | Typ | Max | Units |
|--|---------------------------------|---------|-----------|-----------|---------------|
| DC | | | | | |
| Operating Supply Voltage | | 7 | 8 | 15 | V |
| Supply Current | | | 26 | 45 | mA |
| Input DC Voltage | Pin 19 | | 4 | | V |
| Input DC Voltage | Pin 2 | | 1.8 | | V |
| Supply Rejection | | 15 | 30 | | dB |
| Lamp Leakage Current | Lamp Off, Pin 11 = 16V | | 0.1 | 100 | μA |
| Lamp Saturation Voltage | Lamp On, Pin 11 @ 75 mA | | 1.4 | 2.0 | V |
| VCO Stop Voltage | Voltage at Pin 4 to Stop VCO | 0.2 | 0.4 | | V |
| VCO Stop Current | Pin 4 = 0.2V | | -30 | -100 | μA |
| Blend Input Bias Current | Pin 20 = 0V | | -2 | -20 | μA |
| Quick Mono Switch Voltage | | | 4 | | V |
| Quick Mono Bias Current | Pin 1 = 8V | | 2 | | μA |
| Output Leakage | Pin 12 or 13 = 6.5V, Pin 3 = 0V | | 0.1 | 20 | μA |
| Audio | | | | | |
| Mono Gain | 1 kHz | -4 | -1 | +2 | dB |
| Mono THD | 1 kHz @ 200 mVrms | | 0.05 | 0.25 | % |
| Channel Balance | | | ± 0.4 | ± 1.5 | dB |
| Gain Shift | Mono to Stereo | | ± 0.1 | ± 1.0 | dB |
| Channel Separation | Pin 20 $\geq 1.1\text{V}$ | 30 | 45 | | dB |
| Output DC Shift | Mono to Stereo | | ± 15 | ± 100 | mV |
| Input Resistance | Pin 19 | 20 | 40 | | k Ω |
| Output Resistance | Pin 12, 13 | | 65 | 200 | Ω |
| Ultrasonic Rejection | 19 kHz + 38 kHz | | 30 | | dB |
| SCA Rejection | (Note 2) | | 70 | | dB |
| Signal To Noise | 1 kHz @ 200 mVrms Mono | | 68 | | dB |
| PLL | | | | | |
| Lamp On Voltage | 19 kHz on Pin 2 | | 15 | 20 | mV |
| Lamp Off Voltage | 19 kHz on Pin 2 | 2.5 | 5 | | mV |
| Lamp Hysteresis | | | 10 | | dB |
| Capture Range | 25 mVrms on Pin 2 | ± 2 | ± 4 | ± 6 | % |
| Hold In Range | 25 mVrms on Pin 2 | | ± 12 | | % |
| Input Resistance | Pin 2 | 8 | 14 | | k Ω |
| Blend Pin 20 from 1.1V to 0.2V | | | | | |
| Stereo Gain Change | 1 kHz L = R Input | -25 | -35 | | dB |
| Mono Gain Change | 1 kHz L = R Input | -1.5 | -0.5 | 0.5 | dB |
| | 10 kHz L = R Input | -8 | -14 | -20 | dB |
| Output DC Shift | | | ± 40 | ± 100 | mV |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 125°C/W junction to ambient.

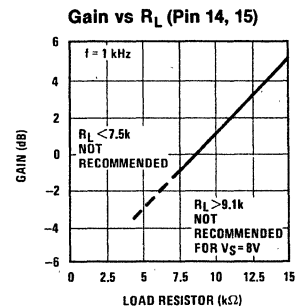
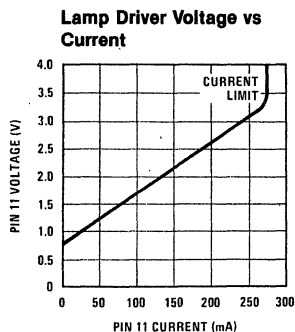
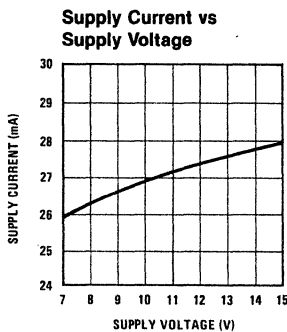
Note 2: Input is 10% SCA (74.5 kHz), 9% pilot and 1 kHz left or right. Rejection is ratio of 1 kHz output to 1.5 kHz output.

External Components

| Part # | Recommended Value | Purpose | Affect | | Remarks |
|-----------------|-------------------------------------|--------------------------------|---|---|--|
| | | | Smaller | Larger | |
| R1 | 100k | Pull Up for Quick Mono | OK | Errors Due to Pin 1 Bias Current | Pin 1 Can Be Shorted to Supply if Quick Mono is Not Used |
| C2 | 2 μ F | PLL Input Coupling | Loading of Source varies with Frequency | | For Source of Less Than 100 Ω , Can Use 0.1 μ F |
| C3 | 0.1 μ F | Supply Bypass | | | |
| C4 | 0.22 μ F | Lamp Filter | Shorter Time to Switch Mono to Stereo | Longer Time to Switch Mono to Stereo | High Dielectric Resistance |
| R6 C6 C7 | 3k 0.047 μ F 0.33 μ F | Loop Filter | High Stereo Distortion | Narrower Capture Range | |
| R8 C8 | 33k 0.0047 μ F | Loop Filter | High Stereo Distortion | Loop not Lock Narrower Capture Range | |
| C9 R9 R10 | 1000 pF 8.2k 5k | Set VCO Free Running Frequency | High VCO Jitter VCO Not Adjustable with C9 | Narrower Capture Range | NPO 5% Metalfilm |
| R11 | 180 Ω | Sets Lamp Current | Excess IC Dissipation | Dim Lamp | |
| R14 R15 | 7.5k 7.5k | Load Resistors | Low Output Voltage | Output Clip Earlier | |
| C14 C15 | 0.01 μ F 0.01 μ F | Deemphasis | | | |
| R16 | 3k | Sets Blend Characteristic | See Curves | | |
| C17 C18 | 0.0047 μ F 0.0047 μ F | Filter for Blend | Insufficient Blend | Reduced Blend Bandwidth | |
| C19 | 2 μ F | Audio Input Coupling | Poor Low Frequency Response and Separation | Turn On Delay | |
| R19 | 15k | Allows VCO Monitoring | Excess IC Dissipation | Reduces 19 kHz Output Voltage | Only Need During Set Up |

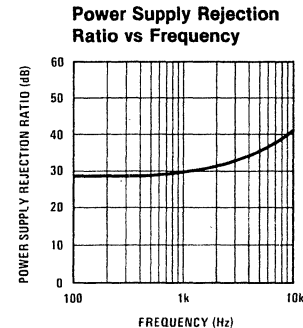
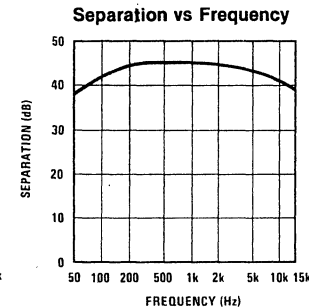
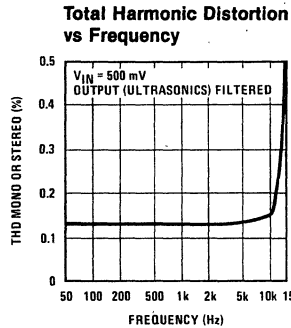
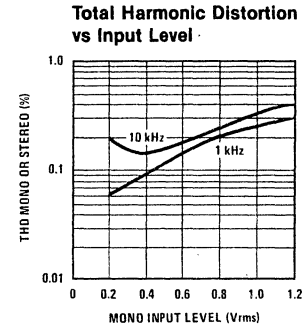
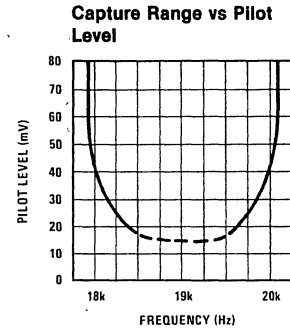
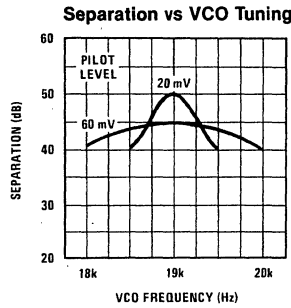
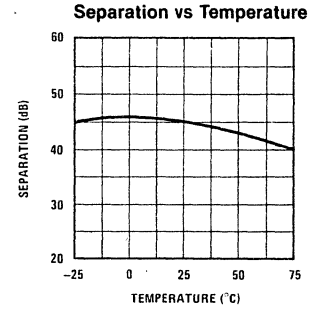
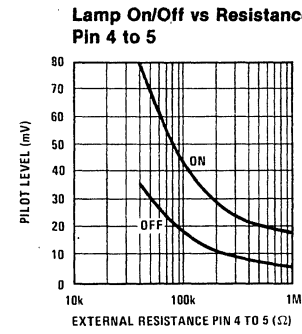
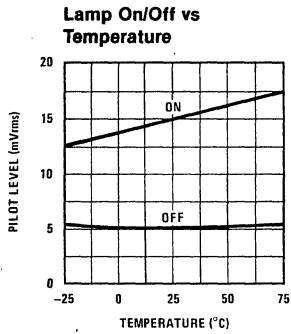
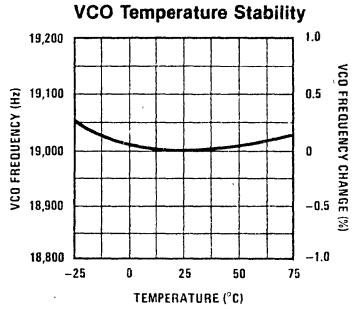
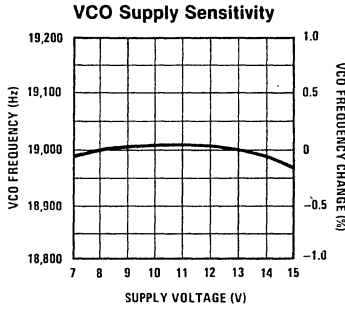
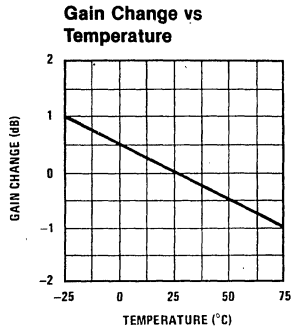
Typical Performance Characteristics

Blend off unless otherwise stated



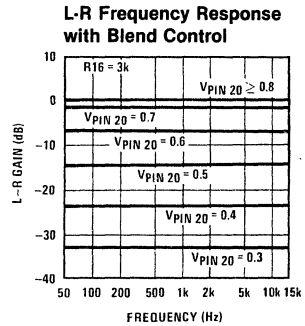
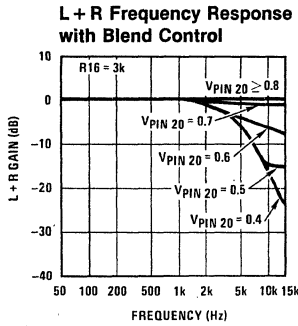
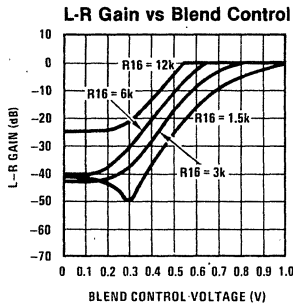
Typical Performance Characteristics Blend off unless otherwise stated

LM1870



10

Typical Performance Characteristics Blend off unless otherwise stated

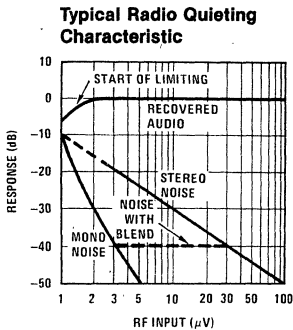


Application Hints

Blend—What & Why?

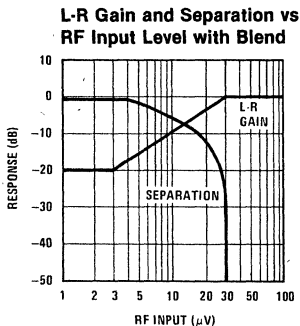
The signal to noise of a weak FM stereo signal is worse than that of an equally weak FM mono signal. For this reason FM mono radios often perform better than FM stereo radios, unless the latter is forced into mono.

The typical quieting curves of an FM stereo radio look like this:



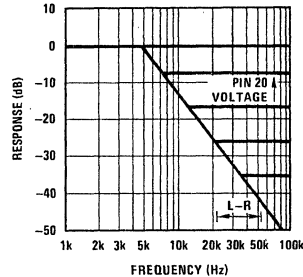
If an acceptable signal to noise is 40 dB, then 20 dB more signal is required in stereo compared to mono, 30 μV vs 3 μV. The degradation in noise is due to the L-R or difference channel. If the gain of the L-R is reduced, then the noise associated with it will be reduced. However, there will also be a reduction in separation.

To maintain a 40 dB signal to noise in the above example, the gain of the L-R signal should be reduced from 0 dB gain @ 30 μV downward to -20 dB at 3 μV. If this is done properly the dashed line will result. Below is a plot of L-R gain and resulting separation.



The LM1870 reduces the gain of the L-R channel before it is demodulated. This is done by a voltage controlled shelving filter. The Bode plot of this filter is shown below:

Blend Filter Response



The full blend response is a two pole roll-off with each pole set by an internal 6.8k resistor and the capacitance from pins 17 and 18 to ground. The standard value for both capacitors is 4.7 nF resulting in two 5 kHz poles. The blend input (pin 20) is derived from the meter drive output of the FM IF chip (LM3089 or LM3189 pin 13). To adjust for variations in RF gain and other IC parameters, it is recommended that an adjustment be made on each radio.

Mono-Stereo Switching

The LM1870 automatically switches from mono to stereo when the level of pilot at pin 2 is about 15 mV or more. This value can be increased by putting a resistor between pins 4 and 5, as shown graphically in the Typical Performance curves.

If it is desired to switch to mono without turning off the lamp driver, pin 1 should be taken below 4V. This is a high impedance input that can be electronically switched by a transistor with a pull up resistor to the IC supply.

Outputs

The LM1870 has emitter-follower outputs resulting in a low output impedance. The output will sink or source one mA, therefore it will drive AC coupled loads greater than 2 kΩ.

In AM-FM radios the switching can be cumbersome at best. To ease the problem the outputs of the LM1870 (pins 12 and 13) are open circuit when the supply (pin 3) is open or grounded. This reduces the numbered switch poles required since the outputs can remain connected at all times. This technique is commonly called diode switching but the method used in the LM1870 results in substantially lower distortion than obtained with discrete diodes.

Application Hints (Continued)

VCO

The stereo performance of the LM1870 is very constant for small (<2%) changes in the free running frequency of the VCO. To insure that the frequency stays within 2%, low temperature coefficient components should be used for the tuning capacitor (1000 pF) and resistor (8.2k). The internal oscillator has a temperature coefficient of about 50 ppm/°C (see curve). With an NPO capacitor and a metalfilm resistor the total variation in the free running frequency will be less than 1% over the full temperature range. Tuning the VCO is done by adjusting the 5 k Ω potentiometer to get 19 kHz \pm 50 Hz with no input on pin 2.

The VCO frequency is monitored at pin 16 when current is supplied to the pin. During normal operation the 19 kHz square wave is not available and the resistor from pin 16 to ground programs the blend characteristics (see curves).

The VCO of the LM1870 can be stopped by taking pin 4 low. In addition to being useful for turning off the stereo indicator and forcing mono FM reception, this also allows other mono sources, such as AM, to be fed into the decoder and come out both channels. The signal will not be inadvertently decoded with the VCO off and it will have the same gain and balance characteristics as the FM. The de-emphasis capacitors may need to be removed for proper frequency response. The voltage on pin 20 will also affect the frequency response.

It should be noted that a stopped VCO cannot radiate into the rest of the radio and cause interference. Pin 4 can be taken low with a mechanical switch or an NPN transistor. If a transistor is used it must have low leakage, less than 100 nA at 3 volts V_{CE} , and low saturation, less than 200 mV at 100 μ A collector current.

PLL

To properly demodulate the L-R signal the decoder must generate a 38 kHz signal that is locked in phase with the 19 kHz pilot signal at the input. This is done with a phase locked loop consisting of a phase detector, a loop filter (pins 6 and 7) and a VCO (pins 8 and 9).

The loop filter is similar to other standard decoders however the VCO incorporates an additional low pass filter (4.7 nF and 33 k Ω) to reduce beat note distortion an additional 20 dB.

Input Interface

There are two inputs to the LM1870, one for the PLL (pin 2) and the normal audio input (pin 19). The input impedance of the audio input is about 40 k Ω . The input coupling capacitor works with this input resistance and sets the low frequency response and separation.

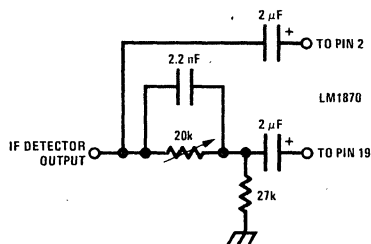
The PLL input (pin 2) locks onto the 19 kHz pilot and rejects the rest of the composite signal. For this reason it is only necessary to use a coupling capacitor large enough to insure there is no phase shift at 19 kHz. The input resistance of the PLL is 14 k Ω so a capacitor between 0.01 μ F and 0.1 μ F would be fine. However, the source driving this input must not be affected by this load. This is true only when the source is low impedance (less than 100 Ω).

Typical FM IF circuits have detector output impedance of 5 k Ω or more. This will cause very poor low frequency response and separation unless the loading is made constant over frequency. For this reason the typical input coupling capacitor is 2 μ F.

IF Correction

The separation in most radios is limited by the response of the IF. The input lead network below can often be used to improve radio separation.

IF Correction Lead Network



Power Supply

The LM1870 is designed to work on supplies from 7V to 15V. For automotive applications a regulator is recommended to protect against transients; the LM2930-8V is the ideal choice.

LM1877 Dual Power Audio Amplifier

General Description

The LM1877 is a monolithic dual power amplifier designed to deliver 2W/channel continuous into 8 Ω loads. The LM1877 is designed to operate with a low number of external components, and still provide flexibility for use in stereo phonographs, tape recorders and AM-FM stereo receivers, etc. Each power amplifier is biased from a common internal regulator to provide high power supply rejection, and output Q point centering. The LM1877 is internally compensated for all gains greater than 10, and is a pin-for-pin replacement for the LM377 in audio applications.

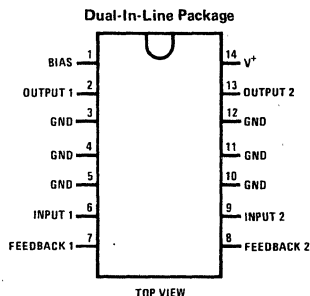
Features

- 2W/channel
- -65 dB ripple rejection, output referred
- -65 dB channel separation, output referred
- Wide supply range, 6-24V
- Very low cross-over distortion
- Low audio band noise
- Internal current limiting, short circuit protection
- Internal thermal shutdown

Applications

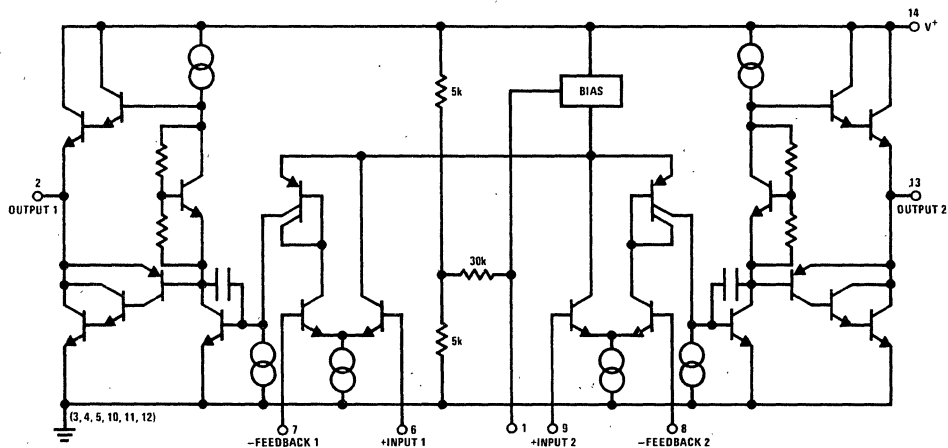
- Multi-channel audio systems
- Stereo phonographs
- Tape recorders and players
- AM-FM radio receivers
- Servo amplifiers
- Intercom systems
- Automotive products

Connection Diagram



Order Number LM1877N-XX (N-1 through N-10)
See NS Package N14A

Equivalent Schematic Diagram



Absolute Maximum Ratings

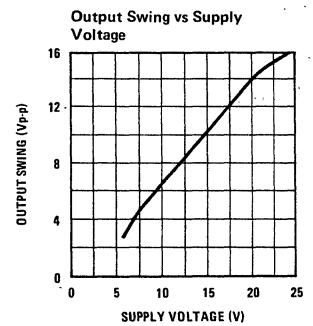
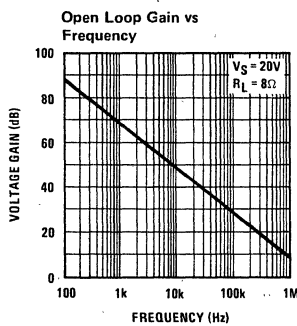
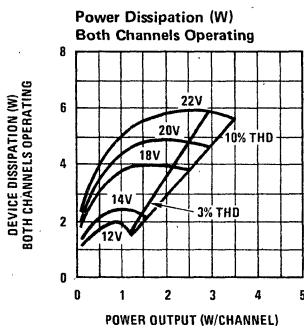
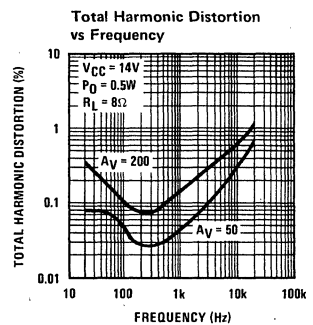
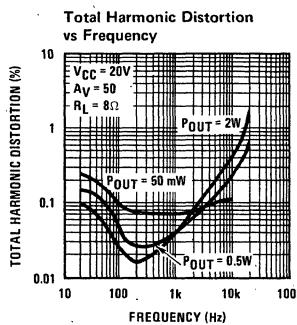
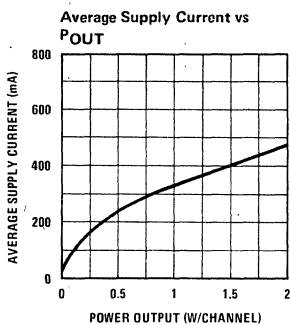
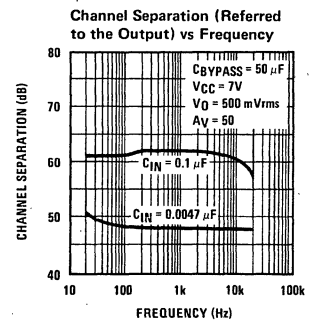
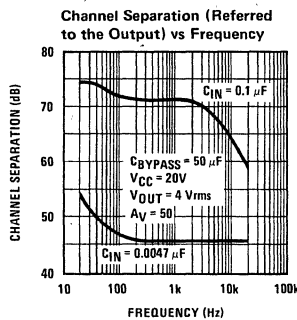
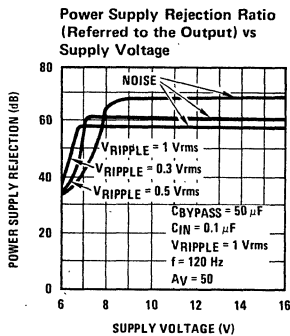
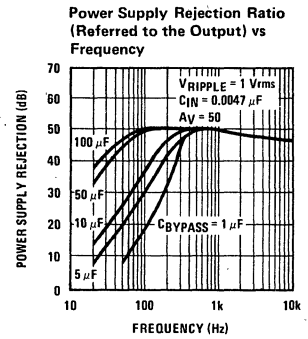
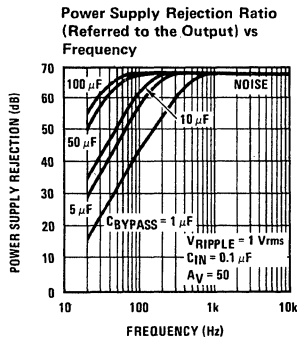
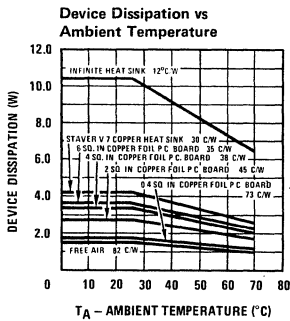
| | | |
|--|--|-----------------|
| Supply Voltage | | |
| LM1877N-1 to LM1877N-4 | | 20V |
| LM1877N-5 to LM1877N-10 | | 26V |
| Input Voltage | | ±0.7V |
| Operating Temperature | | 0°C to +70°C |
| Storage Temperature | | -65°C to +150°C |
| Junction Temperature | | 150°C |
| Lead Temperature (Soldering, 10 seconds) | | 300°C |

Electrical Characteristics $V_S = 20V$, $T_A = 25^\circ C$, $R_L = 8\Omega$, $A_V = 50$ (34 dB) unless otherwise specified

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------------------------|--|-----|-----------|-----|------------|
| Total Supply Current | $P_O = 0W$ | | 25 | 50 | mA |
| Output Power | THD = 10% | | | | |
| LM1877N-1 | $V_S = 12V$, $R_L = 4\Omega$ | 2.0 | | | W |
| LM1877N-2 | $V_S = 14V$, $R_L = 8\Omega$ | 1.0 | | | W |
| LM1877N-3 | $V_S = 14V$, $R_L = 8\Omega$ | 1.5 | | | W |
| LM1877N-4 | $V_S = 14V$, $R_L = 8\Omega$ | 2.0 | | | W |
| LM1877N-5 | $V_S = 16V$, $R_L = 8\Omega$ | 1.5 | | | W |
| LM1877N-6 | $V_S = 16V$, $R_L = 8\Omega$ | 2.0 | | | W |
| LM1877N-7 | $V_S = 16V$, $R_L = 8\Omega$ | 2.5 | | | W |
| LM1877N-8 | $V_S = 18V$, $R_L = 8\Omega$ | 3.5 | | | W |
| LM1877N-9 | $V_S = 20V$, $R_L = 8\Omega$ | 2.0 | | | W |
| LM1877N-10 | $V_S = 20V$, $R_L = 8\Omega$ | 4.0 | | | W |
| Total Harmonic Distortion | | | | | |
| LM1877 | $f = 1\text{ kHz}$, $V_S = 14V$ | | 0.075 | | |
| | $P_O = 50\text{ mW/Channel}$ | | 0.045 | | % |
| | $P_O = 500\text{ mW/Channel}$ | | 0.055 | | % |
| | $P_O = 1W/Channel$ | | $V_S - 6$ | | % |
| Output Swing | $R_L = 8\Omega$ | | | | Vp-p |
| Channel Separation | $C_F = 50\ \mu F$, $C_{IN} = 0.1\ \mu F$, $f = 1\text{ kHz}$, Output Referred | | | | |
| | $V_S = 20V$, $V_O = 4\text{ Vrms}$ | -50 | -70 | | dB |
| | $V_S = 7V$, $V_O = 0.5\text{ Vrms}$ | | -60 | | dB |
| PSRR Power Supply Rejection Ratio | $C_F = 50\ \mu F$, $C_{IN} = 0.1\ \mu F$, $f = 120\text{ Hz}$, Output Referred | | | | |
| | $V_S = 20V$, $V_{RIPPLE} = 1\text{ Vrms}$ | -50 | -65 | | dB |
| | $V_S = 7V$, $V_{RIPPLE} = 0.5\text{ Vrms}$ | | -40 | | dB |
| Noise | Equivalent Input Noise | | | | |
| | $R_S = 0$, $C_{IN} = 0.1\ \mu F$, $BW = 20\text{ Hz} - 20\text{ kHz}$ | | 2.5 | | μV |
| | Output Noise Wideband | | | | |
| | $R_S = 0$, $C_{IN} = 0.1\ \mu F$, $A_V = 200$ | | 0.80 | | mV |
| Open Loop Gain | $R_S = 0$, $f = 100\text{ kHz}$, $R_L = 8\Omega$ | | 70 | | dB |
| Input Offset Voltage | | | 15 | | mV |
| Input Bias Current | | | 50 | | nA |
| Input Impedance | Open Loop | 9 | 4 | 11 | M Ω |
| DC Output Level | $V_S = 20V$ | | 10 | | V |
| Slew Rate | | | 2.0 | | V/ μs |
| Power Bandwidth | | | 65 | | kHz |
| Current Limit | | | 1.0 | | A |

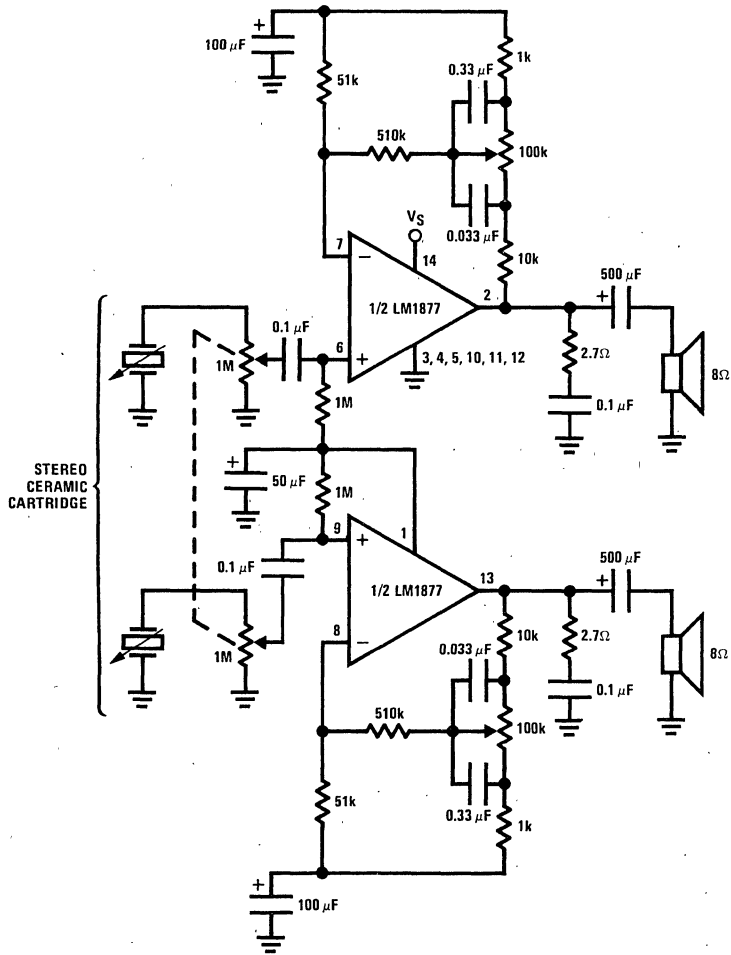
Note 1: For operation at ambient temperature greater than 25°C, the LM1877 must be derated based on a maximum 150°C junction temperature using a thermal resistance which depends upon device mounting techniques.

Typical Performance Characteristics

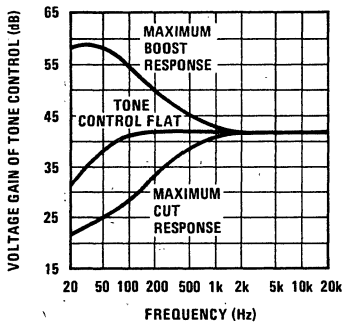


Typical Applications

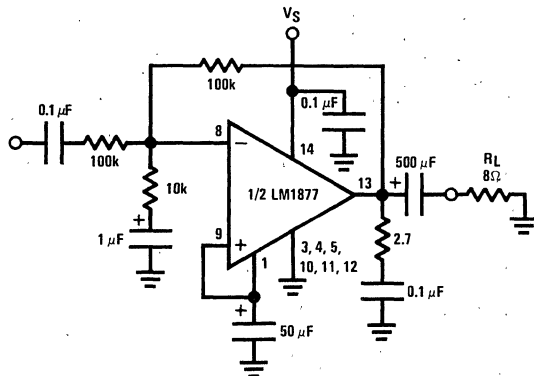
Stereo Phonograph Amplifier with Bass Tone Control



Frequency Response of Bass Tone Control

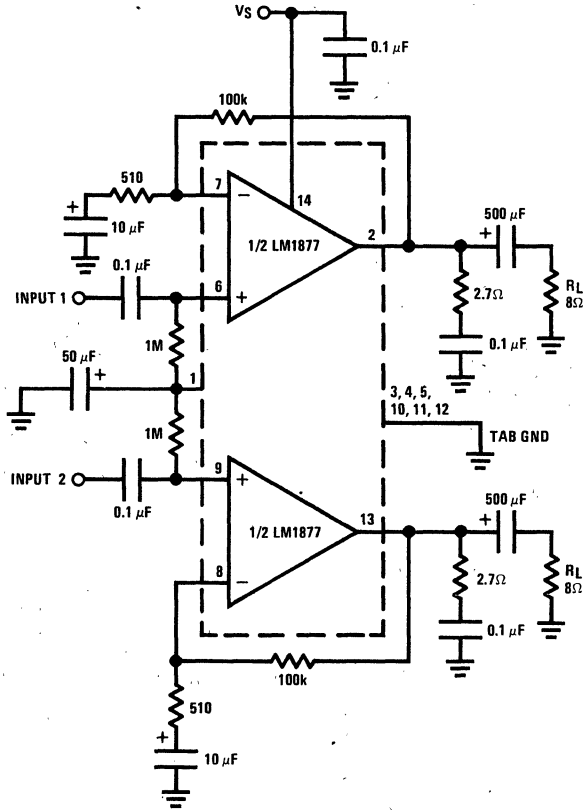


Inverting Unity Gain Amplifier

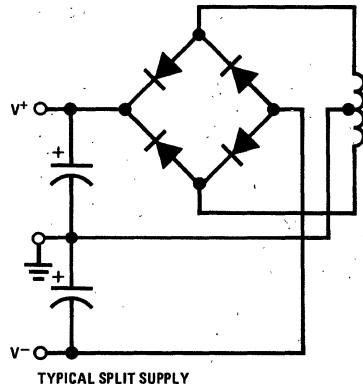
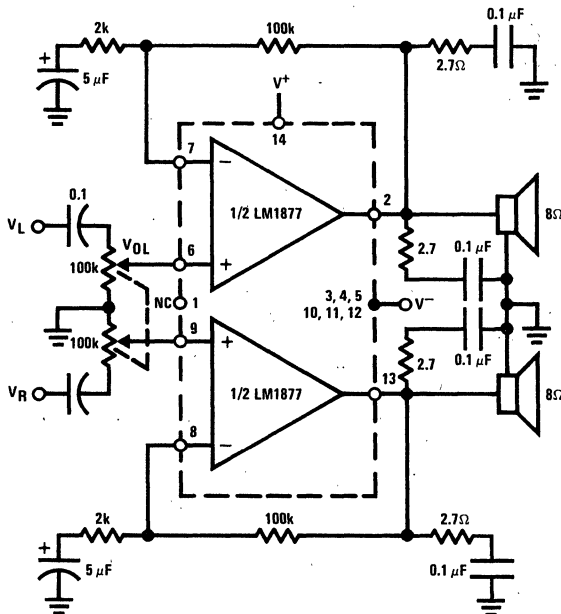


Typical Applications (Continued)

Stereo Amplifier with $A_V = 200$



Non-Inverting Amplifier Using Split Supply



TYPICAL SPLIT SUPPLY

LM1880 No-Holds Vertical/Horizontal

General Description

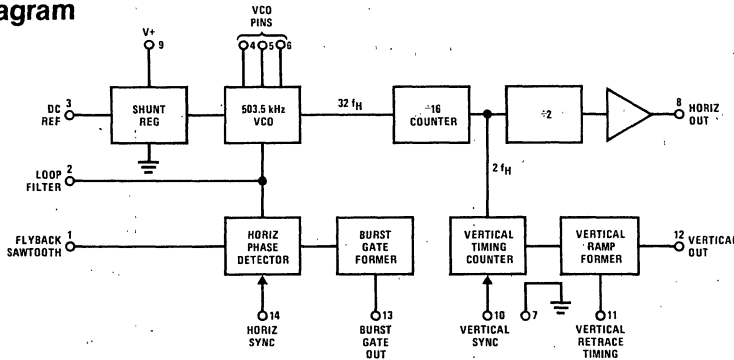
The LM1880 uses compatible Linear/ i^2L technology to produce the first T.V. horizontal and vertical processing system which completely eliminates the hold controls. The heart of the system is a precision 32 times horizontal frequency VCO which is designed to use a low-cost ceramic resonator as a tuning element.

The VCO signal is divided down in the horizontal section to produce a pre-driver output which is locked to negative sync by means of an on-chip phase detector. The vertical output ramp is injection-locked by vertical sync subject to a sync window derived from the vertical countdown section. A gate pulse centered on the chroma burst is also provided.

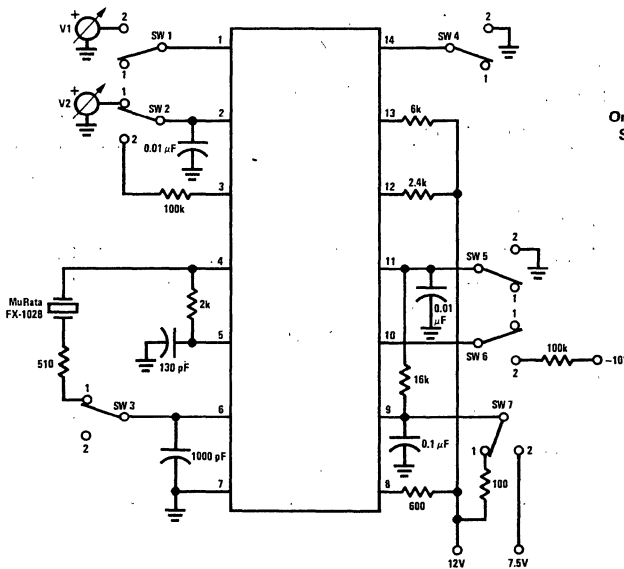
Features

- No frequency set-up required for horizontal or vertical
- Ceramic resonator frequency reference
- Accurate horizontal pre-driver duty cycle
- Vertical sync window referenced to horizontal
- Precise interlaced vertical output
- APC loop parameters completely adjustable
- Vertical retrace time adjustable
- Chroma burst gate output
- Internal voltage regulator

Block Diagram



Test Circuit



Order Number LM1880N
See NS Package N14A

Absolute Maximum Ratings

| | | | |
|-----------------------------------|--------|---|---|
| Supply Current (Pin 9) | 40 mA | Sawtooth Input Voltage (Pin 1) | 5 Vp-p |
| Output Voltage (Pins 8, 12, 13) | 12V | Package Dissipation, $T_A = 25^\circ\text{C}$ | 0.83W |
| Output Current | | Above $T_A = 25^\circ\text{C}$, Derate Based on | |
| Pin 8 | 50 mA | $T_J(\text{MAX}) = 150^\circ\text{C}$ and $\theta_{JA} = 150^\circ\text{C/W}$ | |
| Pin 12 | 15 mA | Storage Temperature Range | -55°C to $+150^\circ\text{C}$ |
| Pin 13 | 10 mA | Operating Temperature Range | 0°C to $+70^\circ\text{C}$ |
| Sync. Input Voltage (Pins 10, 14) | 5 Vp-p | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Test circuit, all SW normally pos, 1, $T_A = 25^\circ\text{C}$)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---------------------------------------|--------|--------|--------|---------------|
| Regulated Voltage (Pin 9) | | 8.2 | 8.7 | 9.2 | V |
| Supply Current (Pin 9) | SW 7 Pos. 2 | 12 | 18 | 24 | mA |
| VCO Reference Voltage (Pin 3) | | | 5.1 | | V |
| VCO Control Current (Pin 2) | V2 = 5V | | 0.25 | 1.0 | μA |
| Horizontal Phase Detector Sink Current (Pin 2) | SW 1, SW 4 Pos. 2, V1 = 3.9V, V2 = 5V | 0.3 | 0.5 | | mA |
| Horizontal Phase Detector Source Current (Pin 2) | SW 1, SW 4 Pos. 2, V1 = 1.9V, V2 = 5V | 0.3 | 0.5 | | mA |
| Horizontal Output Leakage (Pin 8, OFF Condition) | Change SW 3 to Pos. 2 with Pin 8 High | | | 150 | μA |
| Horizontal Output Saturation Voltage (Pin 8, ON Condition) | Change SW 3 to Pos. 2 with Pin 8 Low | | 0.15 | 0.4 | V |
| Vertical Output Saturation Voltage (Pin 12) | SW 3, SW 5 Pos. 2 | | 0.25 | 0.5 | V |
| Burst Gate Saturation Voltage (Pin 13) | SW 1, SW 4 Pos. 2, V1 = 1.9V | | 0.15 | 0.4 | V |
| Horizontal Oscillator Free-Running Frequency (Pin 8), (Note 1) | SW 2 Pos. 2 | 15,550 | 15,750 | 15,950 | Hz |
| Horizontal Oscillator Maximum Frequency (Pin 8) | V2 = 7V | 16,300 | | | Hz |
| Horizontal Oscillator Minimum Frequency (Pin 8) | V2 = 3V | | | 15,150 | Hz |
| Vertical Minimum Lock Frequency (Pin 12) | $f_H = 15,734$ Hz | | | 58.1 | Hz |
| Vertical Maximum Lock Frequency (Pin 12) | SW 6 Pos. 2, $f_H = 15,734$ Hz | 61.7 | | | Hz |

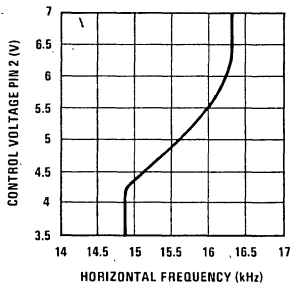
Note 1: Assumes ceramic resonator $f_R = 503.48$ kHz.

Design Parameters (Application Circuit)

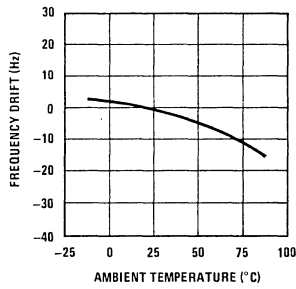
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|----------------------------------|-----|-----------|-----|---------------|
| Horizontal Pull-In Range | | | ± 600 | | Hz |
| Horizontal Static Phase Error (S.P.E.) | $\Delta f_H = \pm 600$ Hz | | ± 0.5 | | μs |
| Horizontal Output Duty Cycle | | | 50 | | % |
| Horizontal Oscillator Supply Sensitivity | | | -1 | | Hz/V |
| Vertical Output Retrace Time | | | 600 | | μs |
| Burst Gate Width | Flyback Width = 12 μs | | 5 | | μs |

Typical Performance Characteristics

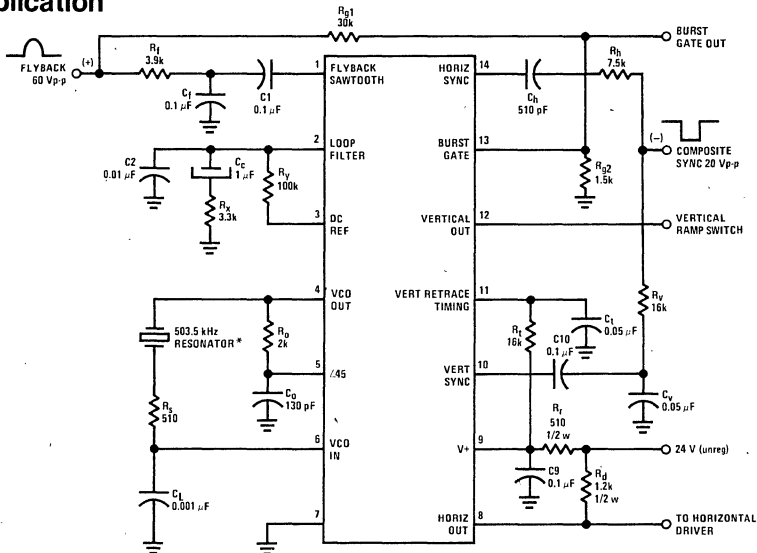
VCO Control Characteristic



Horizontal Free-Running Frequency vs Temperature



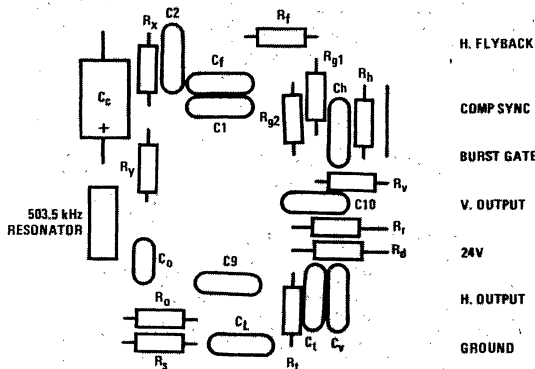
Typical Application



*MuRata Corporation of America, Part No. FX-1028, Vernitron Corp. VTFA3-01-503.5

Printed Circuit Layout

(COMPONENT SIDE)



External Components (Application Circuit)

| Component | Typical Value | Comments | Component | Typical Value | Comments |
|-----------------|---------------|--|----------------|---------------|--|
| R _{g1} | 30k | Burst Gate series resistor. | C _t | 0.05 μF | Vertical Retrace timing capacitor, works with R _t to determine ON time of vertical ramp switch at pin 12. t _v , RETRACE ≈ 0.75 R _t C _t sec. |
| R _{g2} | 1.5k | Burst Gate shunt resistor, works with R _{g1} to divide flyback pulse and set Burst Gate amplitude. | R _o | 2k | Oscillator phase shift resistor. |
| | | $V_{B.G. pk} = \frac{R_{g2}}{R_{g1} + R_{g2}} V_{FLYBACK}$ | C _o | 130 pF | Works with R _o to produce 45° lag required by VCO phase shifter. |
| R _f | 3.9k | Flyback Sawtooth integrator resistor, works with C _f to integrate flyback pulse to 1 V _{p-p} min sawtooth. For C _f = 0.1 μF, $V_{SAW p-p} \approx \frac{85 V_{FLYBACK}}{R_f}$ | R _s | 510 Ω | Defines Q of ceramic resonator tuned network, which affects VCO control curve. |
| C _f | 0.1 μF | Flyback Sawtooth integrator capacitor. | C _L | 1000 pF | Completes VCO loop with phase lag, required to sustain oscillation and suppress resonator overtones. |
| C1 | 0.1 μF | Sawtooth input coupling capacitor. | R _r | 510 Ω | Series resistor to device supply pin 9. Must supply sufficient current to activate internal shunt regulator. |
| R _h | 7.5k | Horizontal Sync input coupling resistor. $R_h = 0.4 \times V_{SYNC p-p} k\Omega$ | | | $R_r = \frac{V_{(unreg)} - 9V}{0.03} \Omega$ |
| C _h | 510 pF | Horizontal Sync input coupling capacitor, blocks vertical sync components. | C9 | 0.1 μF | Device supply decoupling capacitor. |
| R _v | 16k | Vertical sync input integrator resistor. | R _d | 1.2k | Horizontal pre-driver output resistor, supplies base current to Horizontal driver transistor when pin 8 is OFF. |
| C _v | 0.05 μF | Vertical sync input integrator capacitor, works with R _v to integrate composite sync to -2 V _{p-p} min pulse. For N.T.S.C. sync, Vert. sync ≈ 1.4 × 10 ⁻⁴ $\frac{R_v C_v}{(Comp. sync) V_{p-p}}$ | C2 | 0.01 μF | Horizontal APC loop filter high frequency roll-off. C2 also prevents signal on loop filter from saturating phase detector output. |
| C10 | 0.1 μF | Vertical sync coupling capacitor. | R _x | 3.3k | R _x , R _y and C _c form the Horizontal APC loop filter. See Applications Information to modify loop parameters. |
| R _t | 16k | Vertical Retrace timing resistor. | R _y | 100k | |
| | | | C _c | 1 μF | |

Applications Information

I. VERTICAL COUNTER

The vertical counter in the LM1880 replaces the conventional vertical oscillator in a television receiver. The vertical lock-in range is governed by the width of the vertical sync window, which opens from count 510 to count 542 following a vertical reset. The vertical lock frequencies are referenced to twice horizontal frequency to insure interlaced vertical and horizontal outputs. For $f_{\text{HORIZ}} = 15,734$ Hz, the vertical lock frequencies are calculated as follows:

$$f_{V, \text{HIGH}} = \frac{2(15,734)}{510} = 61.7 \text{ Hz.}$$

$$f_{V, \text{LOW}} = \frac{2(15,734)}{542} = 58 \text{ Hz.}$$

In virtually all standard and non-standard sync signals the vertical sync is also derived from the horizontal, so that as long as the horizontal sync frequency is within the pull-in range of the LM1880 (approximately ± 600 Hz), the vertical lock window will remain centered on the vertical sync. Thus, the effective vertical lock range is increased by the horizontal APC:

$$f_{V, \text{HIGH}} (\text{EFF}) = \frac{2(15,734 + 600)}{510} = 64 \text{ Hz.}$$

$$f_{V, \text{LOW}} (\text{EFF}) = \frac{2(15,734 - 600)}{542} = 55.8 \text{ Hz.}$$

The time required for the vertical to "roll-thru" and lock is a function of the difference frequency and relative phase of $f_{V, \text{LOW}}$ and the vertical sync:

$$t_{\text{ROLL-THRU}} (\text{AVG}) = \frac{1}{2} \frac{1}{60 - 58 \text{ Hz}} = 250 \text{ ms}$$

II. HORIZONTAL APC LOOP PARAMETERS

The following information is given to provide a basis for modifying the filter to achieve the desired loop performance. Although the VCO is actually running at 503.5 kHz, for convenience all parameters are referenced to the actual horizontal output frequency at pin 8.

DC Loop Gain

The DC loop gain is the product of the phase detector conversion gain (μ) and the VCO sensitivity (β). For the typical application circuit,

$$\mu = 1.6 \times 10^{-4} R_Y \text{ V/Rad}$$

and

$$\beta = 800 \text{ Hz/V}$$

$$\mu\beta = 0.13 R_Y \text{ Hz/Rad}$$

$$\text{for } R_Y = 100 \text{ k}\Omega, \mu\beta = 13,000 \text{ Hz/Rad}$$

In order to determine static phase error (S.P.E.), the loop gain may be expressed in Hz/ μ s:

$$\mu\beta = \frac{13,000 \times 2\pi}{63.5 \mu\text{s}} = 1,286 \text{ Hz}/\mu\text{s}$$

For comparison, this value is nearly double the loop gain of the LM1391. The increased loop gain (reduced phase error) guarantees accurate centering of the burst gate pulse on pin 13 of the LM1880.

The following equations cover AC loop parameters of interest:

Noise Bandwidth

$$f_{\text{NN}} \cong \frac{1 + 2\pi (R_X^2/R_Y) C_C \mu\beta}{4R_X C_C} \text{ Hz}$$

Damping Factor

$$K \cong \frac{\pi}{2} \frac{R_X^2}{R_Y} C_C \mu\beta$$

Pull-In Range

The pull-in and hold-in range of the LM1880 horizontal APC loop are directly determined by the VCO control range. Thus the loop would be capable of pulling the VCO further than ± 600 Hz, but it has well defined frequency limits which prevent it from doing so. As a result of these built-in "stops", the loop parameters may be varied over a large range without affecting pull-in performance.

The VCO control range, and hence pull-in, can be modified to some extent by varying the Q of the ceramic resonator with resistor R_S :

Incr. $R_S \rightarrow$ Incr. Pull-in

Reduce $R_S \rightarrow$ Reduce Pull-in

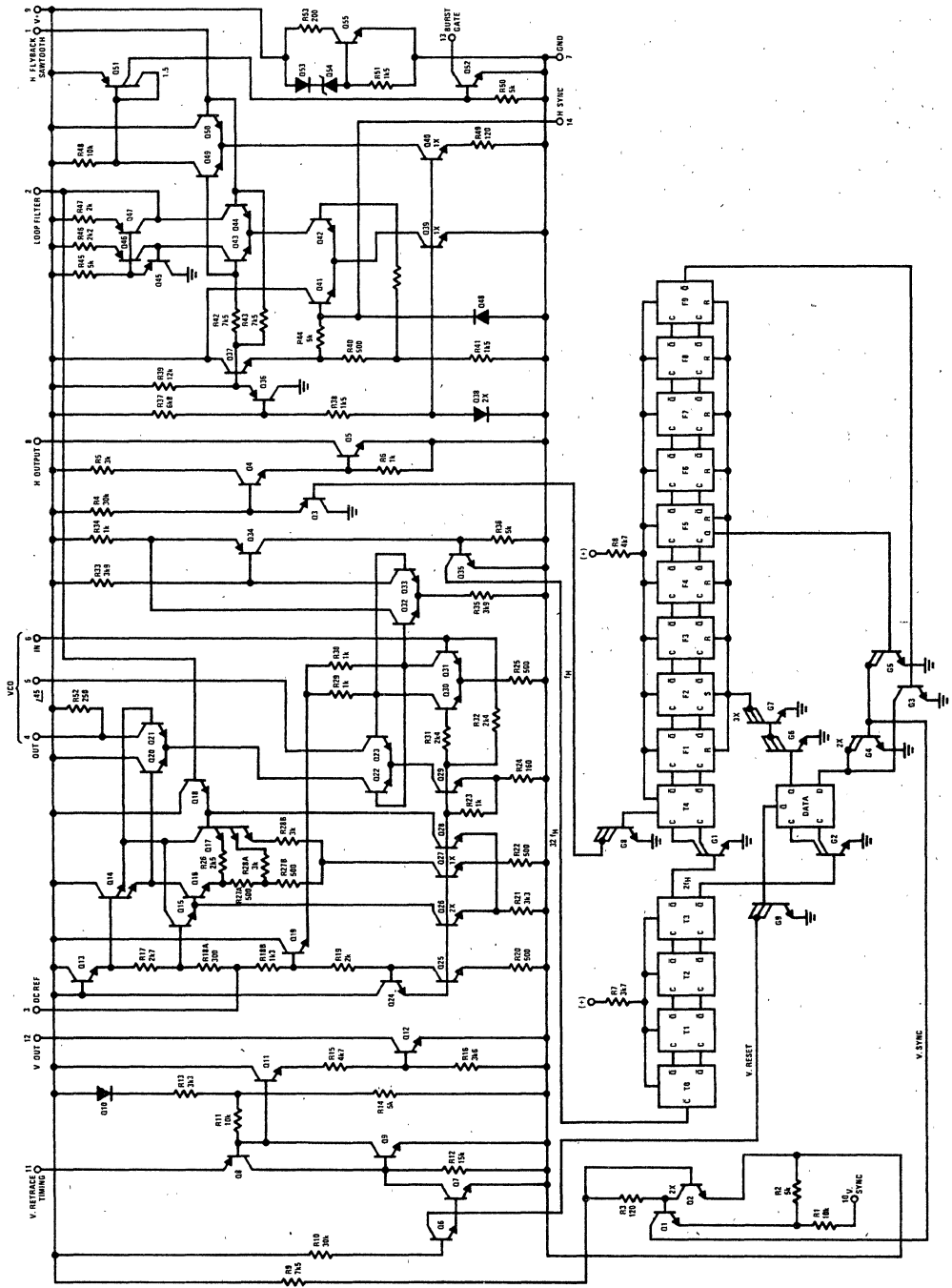
However, because of the non-linearity of the resonator, R_S has a much greater effect on the negative side pull-in than the positive side.

III. LAYOUT NOTES

Since the LM1880 uses a counter to derive the horizontal frequency, care must be taken to prevent extraneous signals from the horizontal driver and output stages from feeding back to the VCO where they could cause false counts and consequent severe phase jitter. The following guidelines will prevent this problem from occurring:

- Keep the VCO feedback capacitor, C_L , as close as possible to device pins 6 and 7.
- Limit the lead length on the horizontal output pin 8. If a long line is required to the driver base, isolate it with a small series resistor (200–300 Ω) next to pin 8.

Schematic Diagram



Circuit Description (See Schematic Diagram)

The LM1880 uses a phase-shift type voltage-controlled oscillator (VCO). The gain for the oscillator loop is derived from differential amplifiers Q30, Q31 and Q22, Q23. The collector current in Q23 is phase-shifted 45° at pin 5 and summed with a portion of the current in Q22, controlled by differential amplifier Q20, Q21. The resulting output phase at pin 4 coupled through the ceramic resonator to pin 6 defines the oscillation frequency. Differential amplifier Q16, Q17, controlled by the pin 2 voltage, determines the current split in Q20 and Q21 and, consequently, the pin 4 phase and oscillation frequency. The multiple-emitter degeneration in Q17 compensates the resonator phase characteristic to produce a nearly linear VCO control curve.

The 503.5 kHz output of the VCO is taken from squaring amplifier Q32, Q33 through Q34 and Q35 to the I^2L $\div 16$ pre-scaler T0–T3. The $2f_H$ output is then divided again in T4 to produce the desired horizontal frequency at gate G8. The horizontal pre-driver section consists of Q3, Q4 and Q5, which produce an open-collector output square-wave at pin 8.

The $2f_H$ pre-scaler output also drives a data flip-flop which resets the vertical counter F1–F9. The data input of the reset flip-flop is controlled by the vertical sync from pin 10 subject to gates G3 and G5. After 510 $2f_H$ cycles following reset, vertical sync from Q1 and G4 is enabled by G3. A sync pulse received after this time initiates reset on the next $2f_H$ cycle. If no pulse is received after 542 cycles, G5 will initiate the reset process. A reset pulse from the counter is taken via G9 to the retrace timing section. SCR Q8, Q9 is normally

ON, holding a capacitor on pin 11 near ground. During this time Q11 and Q12 are OFF, allowing the vertical ramp to form on pin 12. When the reset pulse is received, Q7 turns Q8, Q9 OFF and Q11, Q12 ON, discharging the vertical ramp for the duration of the retrace time. Retrace is completed when the pin 11 capacitor charges to the Q8 threshold, and the SCR again latches.

The remaining sections of the device are the horizontal phase detector and burst gate former. The balanced phase detector consists of comparator Q43, Q44 and current source Q39 gated by differential amplifier Q41, Q42. Negative horizontal sync pulses on pin 14 enable the comparator, and the flyback sawtooth on pin 1 switches the current from Q43 to Q44 based on the relative phase between the sync and sawtooth. Q44 takes a (–) current pulse from pin 2, while the pulse in Q43 is turned around in the current mirror Q45, Q46 and Q47 to produce a (+) current pulse at pin 2. These currents are then integrated by the external loop filter to control the VCO.

The flyback sawtooth also switches differential amplifier Q49, Q50, which activates the burst gate. During the first half of the flyback pulse Q49 will be ON, which turns Q51 and Q52 ON and clamps pin 13 near ground. The sawtooth switches Q49, Q51 and Q52 OFF at the peak of the flyback, releasing pin 13. In this manner, the second half of a flyback pulse fed to pin 13 can be used as a burst gate.

Q53, Q54 and Q55 form the active shunt regulator which holds the supply pin 9 at 8.7V typ.

LM1886 TV Video Matrix D to A

General Description

The LM1886 is a TV video matrix D to A converter which encodes luminance and color difference signals from 3-bit red, green and blue inputs. The luminance output is encoded from the NTSC equation $Y = 0.3R + 0.59G + 0.11B$ and the R-Y and B-Y outputs are weighted to prevent over-modulation. A built-in R-Y and burst gate polarity switch allow European PAL compatible signals to be encoded. All output levels including an RF Carrier Bias Voltage have been referenced to 5V for direct connection to the LM1889 TV video modulator. When used in combination with the LM1889 and a suitable sync generator, 3-bit R, G and B information may be encoded to both composite video and RF channel carrier.

Features

- Complete digital to RF encoding with LM1889
- 1-pin PAL/NTSC mode select
- True NTSC matrix
- 8 levels of grey scale
- Allows wide range of colorimetry
- Low power TTL inputs
- Wideband luminance output
- Weighted R-Y, B-Y outputs

Connection Diagram

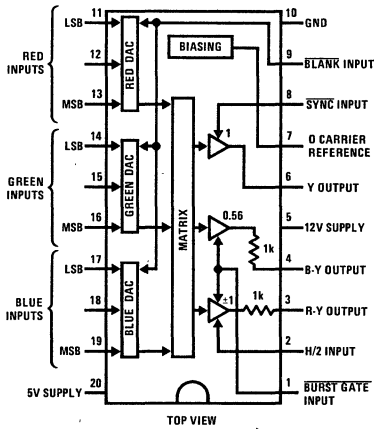


FIGURE 1

Order Number LM1886N
See NS Package N20A

Test Circuits

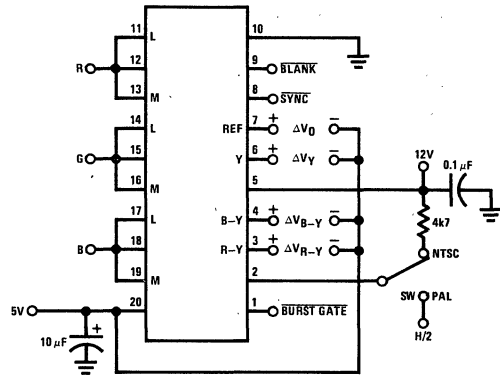


FIGURE 2a. 6-Color Input Connection

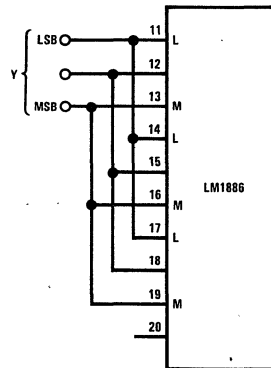


FIGURE 2b. 8-Level, Grey Scale Input Connection

Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | |
| Pin 5 | 15V |
| Pin 20 | 6V |
| Input Voltage (Pins 1, 8, 9, 11–19) | –0.5V, +12V |
| Pin 2 Voltage Relative to Pin 20 | 0.8V |
| Output Current | 5 mA |
| Power Dissipation, $T_A = 25^\circ\text{C}$ (Note 1) | 1.67 W |
| Storage Temperature Range | –55°C to +150°C |
| Operating Temperature Range | 0°C to 70°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

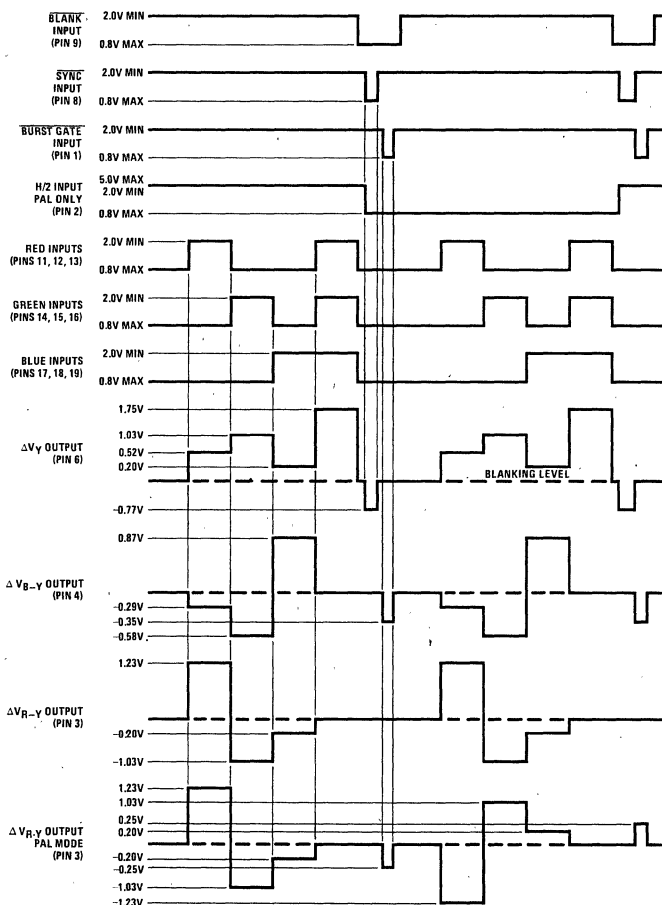
Electrical Characteristics $T_A = 25^\circ\text{C}$, (Figure 2, Note 2)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|-------|---------|-----------|---------------|
| 5V Supply Current (Pin 20) | $\overline{\text{BLANK}} = 0.8\text{V}$ | 7 | 11 | 16 | mA |
| 12V Supply Current (Pin 5) | $\overline{\text{BLANK}} = 0.8\text{V}$ | 9 | 13 | 17 | mA |
| Logic "1" Input Current (Pins 1, 2, 8, 9, 11–19) | Input Voltage = 5.0V | | 0 | 10 | μA |
| Logic "0" Input Current (Pins 1, 2, 8, 9, 11–19) | Input Voltage = 0.3V | | –0.01 | –0.18 | mA |
| Output Offsets | R, G, B = 0.8V | | | | |
| ΔV_Y | | | 0 | ± 50 | mV |
| ΔV_{R-Y} | | | 0 | ± 50 | mV |
| ΔV_{B-Y} | | | 0 | ± 50 | mV |
| R-Y Full Scale, $(\Delta V_{R-Y})_{FS}$ | R = 2V; G, B = 0.8V | 1.0 | 1.23 | 1.4 | V |
| B-Y Full Scale, $(\Delta V_{B-Y})_{FS}$ | B = 2V; R, G = 0.8V | 0.7 | 0.87 | 1.0 | V |
| Green Full Scale | G = 2V; R, B = 0.8V | | | | |
| ΔV_{R-Y} | | –0.85 | –1.03 | –1.2 | V |
| ΔV_{B-Y} | | –0.45 | –0.58 | –0.7 | V |
| Y Full Scale | R, G, B = 2V | | | | |
| $(\Delta V_Y)_{FS}$ | | 1.6 | 1.75 | 1.9 | V |
| ΔV_{R-Y} | | | 0 | ± 100 | mV |
| ΔV_{B-Y} | | | 0 | ± 75 | mV |
| O Carrier Reference, ΔV_O | | 2.0 | 2.2 | 2.5 | V |
| Blanking Level, ΔV_Y | $\overline{\text{BLANK}} = 0.8\text{V}$ | | 0 | ± 50 | mV |
| Sync Level, ΔV_Y | $\overline{\text{BLANK}}, \overline{\text{SYNC}} = 0.8\text{V}$ | –0.67 | –0.77 | –0.87 | V |
| NTSC Burst, ΔV_{B-Y} | $\overline{\text{BLANK}}, \overline{\text{BURST GATE}} = 0.8\text{V}$ | –0.26 | –0.35 | –0.46 | V |
| PAL Burst | | | | | |
| ΔV_{R-Y} | SW in PAL Position; | –0.2 | –0.25 | –0.32 | V |
| ΔV_{B-Y} | $\overline{\text{BLANK}}, \overline{\text{BURST GATE}},$ H/2 = 0.8V | –0.2 | –0.25 | –0.32 | V |
| PAL Inversion Ratio $(\Delta V_{R-Y})_{PAL}/(\Delta V_{R-Y})_{FS}$ | R = 2V; G, B, H/2 = 0.8V SW to PAL Position | –0.9 | –1.0 | –1.1 | |
| Y Linearity Error | Figure 2b Input Connection | | ± 1 | ± 6 | %FS |
| Y Switching Times | 15 kHz Square Wave Switching R, G, B in Parallel | | | | |
| Rise Time, t_R | | | 35 | | ns |
| Fall Time, t_F | | | 30 | | ns |
| Settling Time ± 1 LSB | | | 50 | | ns |

Note 1: Above $T_A = 25^\circ\text{C}$, derate based on $T_J(\text{MAX}) = 150^\circ\text{C}$ and $\theta_{JA} = 75^\circ\text{C/W}$.

Note 2: Unless otherwise noted, $\overline{\text{BLANK}}$, $\overline{\text{SYNC}}$, $\overline{\text{BURST GATE}} = 2\text{V}$ and SW is in NTSC position. All outputs are referenced to the +5V supply as shown in Figure 2a.

Typical Input and Output Waveforms



Application Notes (Refer to Figure 3)

SYNC, BLANK, and BURST GATE may be obtained from a sync generator IC similar to MM5320 or MM5321. For PAL operation, the H/2 square wave may be obtained by a ± 2 from horizontal sync.

All inputs are low-power TTL compatible. Because of the very low typical input currents, the color inputs may be paralleled in various combinations. For simple color requirements, the Figure 2a input connection may be used to produce the 6 primary and complementary colors listed in Table I, along with black and white. To add complex colors such as those at the bottom of Table I, all 9 input bits may be required separately. When choosing input codes for other colors, always check the new color against both light and dark backgrounds.

All outputs are referenced to the +5V supply for direct connection to the LM1889. The resistor on the luminance output pin 6 is used to sum the chroma subcarrier from the LM1889 and must be wired as tightly as possible to preserve the video bandwidth. For the addition of sound or a second RF channel, refer to the LM1889 data sheet.

TABLE I. INPUT CODE EXAMPLES FOR COMMON COLORS

| | | INPUT CODE | | | | | |
|---------------|---------|------------|---|-------|---|------|---|
| | | RED | | GREEN | | BLUE | |
| COLOR | | M | L | M | L | M | L |
| Black | | 0 | 0 | 0 | 0 | 0 | 0 |
| Dark Grey | | 0 | 1 | 0 | 0 | 1 | 0 |
| Light Grey | | 1 | 0 | 1 | 0 | 1 | 0 |
| White | | 1 | 1 | 1 | 1 | 1 | 1 |
| Primary | Red | 1 | 1 | 0 | 0 | 0 | 0 |
| | Green | 0 | 0 | 1 | 1 | 0 | 0 |
| | Blue | 0 | 0 | 0 | 0 | 1 | 1 |
| Complementary | Cyan | 0 | 0 | 1 | 1 | 1 | 1 |
| | Magenta | 1 | 1 | 0 | 0 | 1 | 1 |
| | Yellow | 1 | 1 | 1 | 1 | 0 | 0 |
| Brown | | 0 | 1 | 0 | 1 | 0 | 0 |
| Orange | | 1 | 1 | 1 | 0 | 0 | 0 |
| Flesh tone | | 1 | 1 | 1 | 1 | 0 | 1 |
| Pink | | 1 | 1 | 1 | 1 | 1 | 0 |
| Sky Blue | | 1 | 0 | 1 | 0 | 1 | 1 |

Typical Application

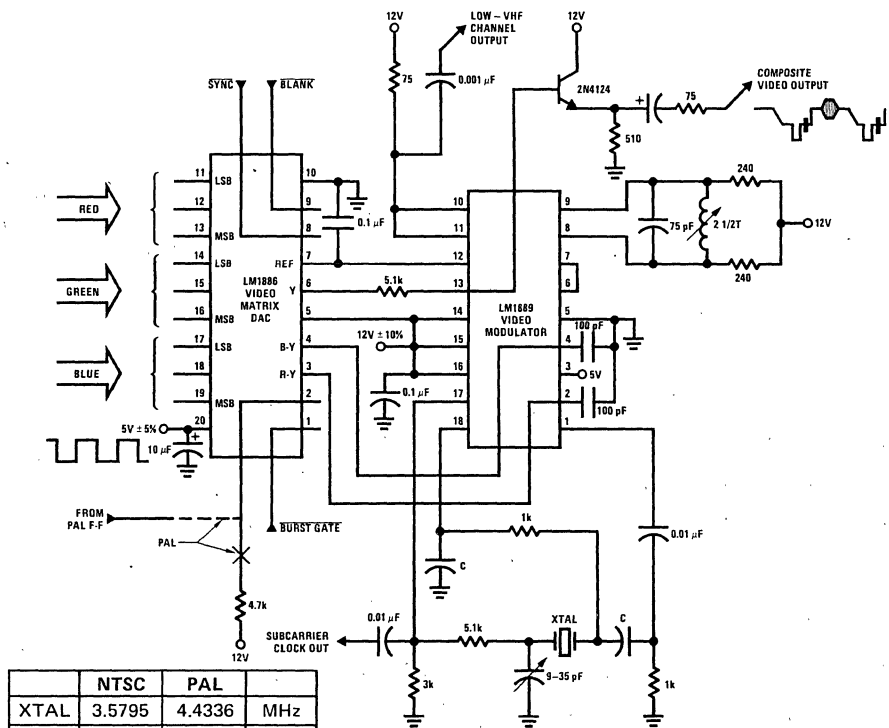


FIGURE 3

Circuit Description (Refer to Figure 4)

The 3-bit red, green, and blue inputs go to identical 3-bit current-mode digital-to-analog converters (DACs). Each DAC consists of three binary-weighted current sources controlled by diff-amp current switches. The DAC output currents are arbitrarily given a weighting factor of 0.59, which is the green coefficient in the luminance equation. Portions of the red and blue currents are split off, so that the remaining currents combined with the green current form the luminance current $I_Y = 0.3 I_R + 0.59 I_G + 0.11 I_B$. I_Y develops the luminance voltage V_Y across R_O in a summing amplifier referenced to the +5V supply. A current switch operated by pin 8 adds (-) sync pulses to the Y output at pin 6.

The portions of red and blue currents previously split off flow through resistors $R_O/0.29$ and $R_O/0.48$, which are weighted to form the red and blue voltages respectively. Since the opposite ends of the 2 resistors are connected to V_Y , the red and blue voltages across the resistors subtract from V_Y to develop the color difference voltages V_{Y-R} and V_{Y-B} . V_{Y-B} is coupled through a X.56 gain, 5V-referenced inverting amplifier to the B-Y output at pin 4. V_{Y-R} feeds parallel inverting and non-inverting unity gain amplifiers which allow either polarity to be coupled to the R-Y output pin 3. Switching between the 2 amplifiers is controlled by a current switch activated by the H/2 pin 2. A (-) burst gate pulse on pin 1 controls current switches which add the burst pulse components to the B-Y and R-Y outputs.

The requirements for PAL and NTSC encoding differ in the areas of burst gate operation and R-Y polarity, both of which are controlled via pin 2 as follows:

PAL, pin 2 fed by a half-line frequency TTL square wave—in this mode a PNP switch between pin 2 and +5V is held off continuously, which results in equal burst pulse components on the B-Y and R-Y outputs. In addition, the H/2 square wave causes the R-Y output polarity to reverse every line. (When fed to the LM1889 chroma modulator this causes the phase of the R-Y subcarrier to change 180° as required in PAL.)

NTSC, pin 2 tied through an external resistor to +12V—this turns on the PNP switch continuously, which eliminates the burst pulse on the R-Y output and increases the amplitude of the B-Y pulse. Since pin 2 is being held high, the R-Y output is locked in the positive polarity.

Blanking is activated by a low on pin 9, which de-biases the left side of the DAC diff-amps, so that $I_R = I_G = I_B = 0$ independent of the input states. When blanked, the Y, B-Y and R-Y outputs all go to +5V. An additional amplifier produces a 0 carrier reference voltage at pin 7 which is 25% above the peak white voltage on the Y output, relative to +5V.

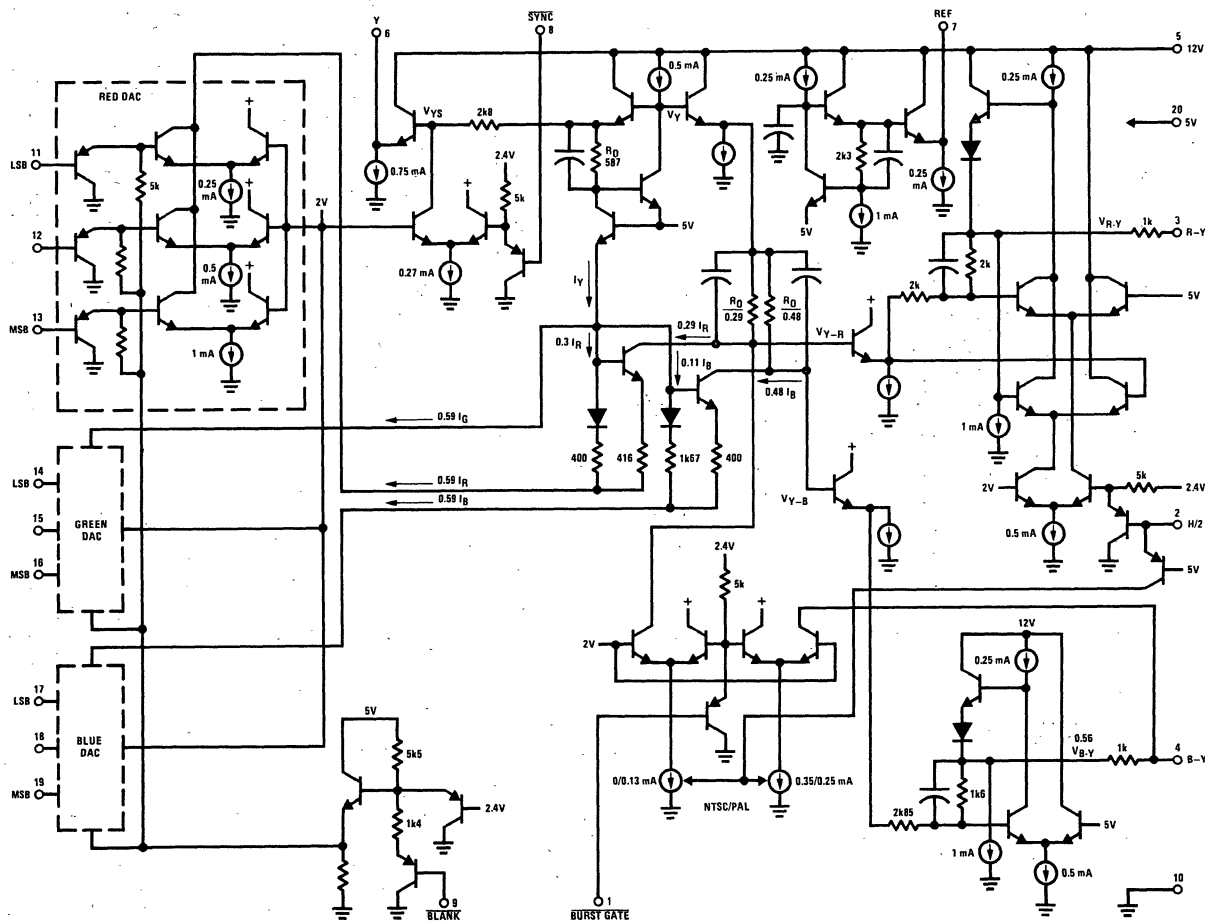


FIGURE 4. LM1886 Equivalent Schematic

LM1889 TV Video Modulator

General Description

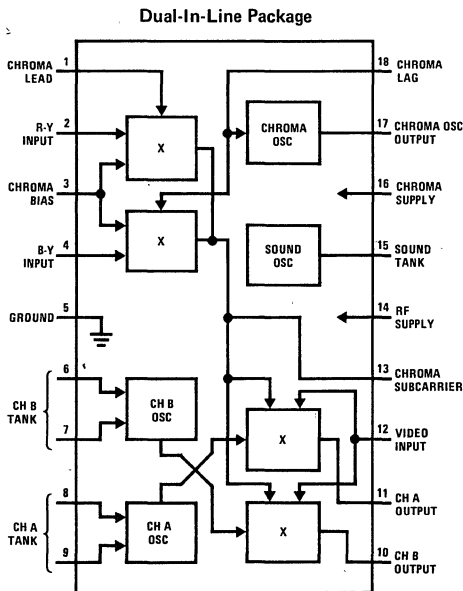
The LM1889 is designed to interface audio, color difference, and luminance signals to the antenna terminals of a TV receiver. It consists of a sound subcarrier oscillator, chroma subcarrier oscillator, quadrature chroma modulators, and RF oscillators and modulators for two low-VHF channels.

The LM1889 allows video information from VTR's, games, test equipment, or similar sources to be displayed on black and white or color TV receivers. When used with the MM57100 and MM53104, a complete TV game is formed.

Features

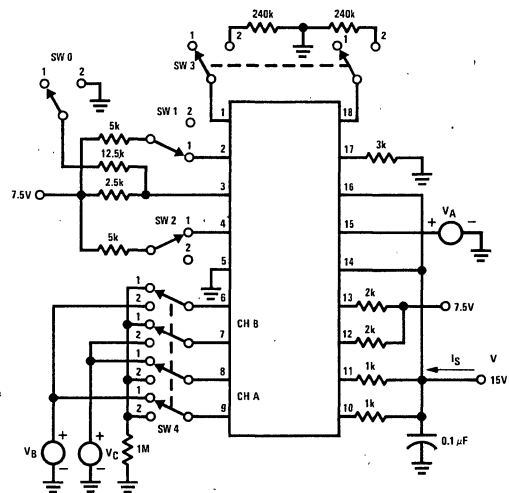
- dc channel switching
- 12V to 18V supply operation
- Excellent oscillator stability
- Low intermodulation products
- 5 Vp-p chroma reference signal
- May be used to encode composite video

Block Diagram



Order Number LM1889N
See NS Package N18A

DC Test Circuit



Absolute Maximum Ratings

| | |
|--|---------------------|
| Supply Voltage V ₁₄ , V ₁₆ max | 19 V _{dc} |
| Power Dissipation Package (Note 1) | 1390 mW |
| Operating Temperature Range | 0°C to +70°C |
| Storage Temperature Range | -55°C to +150°C |
| Chroma Osc Current I ₁₇ max | 10 mA _{dc} |
| (V ₁₆ -V ₁₅) max | ±5 V _{dc} |
| (V ₁₄ -V ₁₀) max | 7V |
| (V ₁₄ -V ₁₁) max | 7V |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

DC Electrical Characteristics (dc Test Circuit, All SW Normally Pos. 1, V_A = 15V, V_B = V_C = 12V)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|------|------|------|-------|
| Supply Current, I _S | | 20 | 35 | 45 | mA |
| Sound Oscillator, Current Change, ΔI ₁₅ | Change V _A From 12.5V to 17.5V | 0.3 | 0.6 | 0.9 | mA |
| Chroma Oscillator Balance, V ₁₇ | | 9.5 | 11.0 | 12.5 | V |
| Chroma Modulator Balance, V ₁₃ | | 7.0 | 7.4 | 7.8 | V |
| R-Y Modulator Output Level, ΔV ₁₃ | SW 3, Pos. 2, Change SW 1 From Pos. 1 to Pos. 2 | 0.6 | 0.9 | 1.2 | V |
| B-Y Modulator Output Level, ΔV ₁₃ | SW 3, Pos. 2, Change SW 2 From Pos. 1 to Pos. 2 | 0.6 | 0.9 | 1.2 | V |
| Chroma Modulator Conversion Ratio, ΔV ₁₃ /ΔV ₃ | SW 3, Pos. 2, Change SW 0 From Pos. 1 to Pos. 2. Divide ΔV ₁₃ by ΔV ₃ | 0.45 | 0.70 | 0.95 | V/V |
| Ch. A Oscillator "OFF" Voltage, V ₈ , V ₉ | SW 4, Pos. 2 | 0.5 | 1.5 | 3.0 | V |
| Ch. A Oscillator Current Level, I _g | V _B = 12V, V _C = 13V | 2.5 | 3.5 | 5 | mA |
| Ch. B Oscillator "OFF" Voltage, V ₆ , V ₇ | | 0.5 | 1.5 | 3.0 | V |
| Ch. B Oscillator Current Level, I _g | SW 4, Pos. 2, V _B = 12V, V _C = 13V | 2.5 | 3.5 | 5 | mA |
| Ch. A Modulator Conversion Ratio, ΔV ₁₁ /(V ₁₃ -V ₁₂) | SW 1, SW 2, SW 3, Pos. 2, V _B = 12V, Change V _C From 13V to 11V For ΔV ₁₁ Divide By V ₁₃ -V ₁₂ | 0.40 | 0.55 | 0.70 | V/V |
| Ch. B Modulator Conversion Ratio, ΔV ₁₀ /(V ₁₃ -V ₁₂) | All SW, Pos. 2, V _B = 12V, Change V _C From 13V to 11V Divide as Above | 0.40 | 0.55 | 0.70 | V/V |

AC Electrical Characteristics (ac Test Circuit, V = 15V)

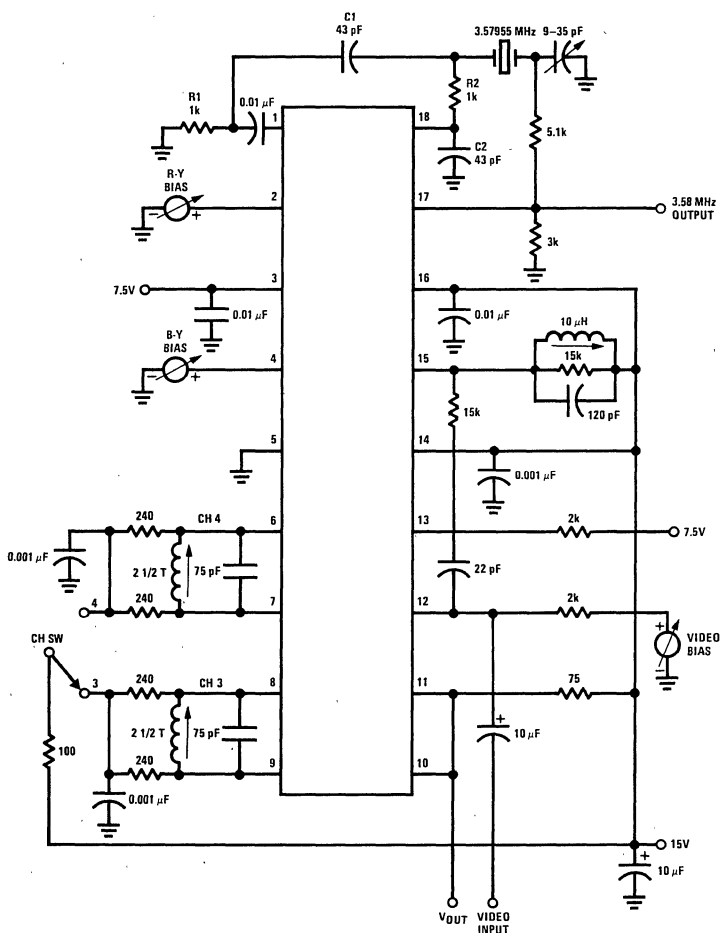
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-----|-----|-----|-------|
| Chroma Oscillator Output Level, V ₁₇ | C _{LOAD} ≤ 20 pF | 4 | 5 | | Vp-p |
| Sound Carrier Oscillator Level, V ₁₅ | Loaded by RC Coupling Network | 2 | 3 | 4 | Vp-p |
| Ch. 3 RF Oscillator Level, V ₈ , V ₉ | Ch. Sw. Pos. 3, f = 61.25 MHz, Use FET Probe | 200 | 350 | | mVp-p |
| Ch. 4 RF Oscillator Level, V ₆ , V ₇ | Ch. Sw. Pos. 4, f = 67.25 MHz, Use FET Probe | 200 | 350 | | mVp-p |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

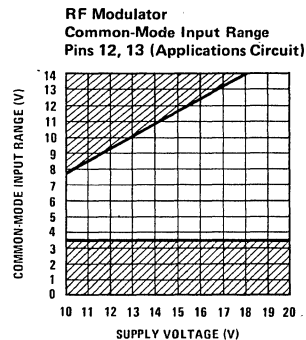
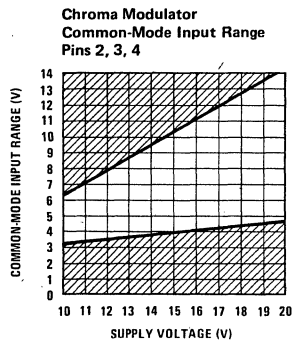
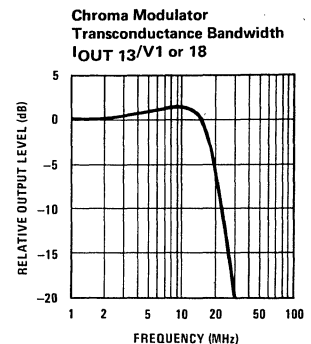
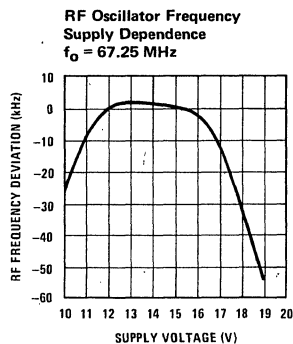
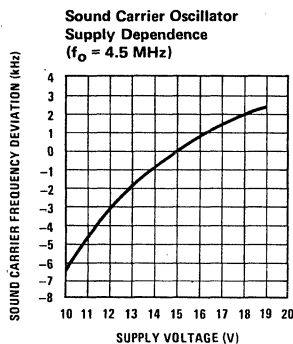
Design Characteristics (ac Test Circuit, V = 15V)

| PARAMETER | TYP | UNITS | PARAMETER | TYP | UNITS |
|---|------------|--------|-----------------------------------|--------------|---------|
| Oscillator Supply Dependence | | | RF Modulator | | |
| Chroma, $f_o = 3.579545$ MHz | 3 | Hz/V | Conversion Gain, $f = 61.25$ MHz, | | |
| Sound Carrier, RF | See Curves | | $V_{OUT}/(V_{13}-V_{12})$ | 10 | mVrms/V |
| Oscillator Temperature Dependence (IC Only) | | | 3.58 MHz Differential Gain | 5 | % |
| Chroma | 0.05 | ppm/°C | Differential Phase | 3 | degrees |
| Sound Carrier | -15 | ppm/°C | 2.5 Vp-p Video, 87.5% mod. | | |
| RF | -50 | ppm/°C | Output Harmonics Below Carrier | | |
| Chroma Oscillator Output, Pin 17 | | | 2nd, 3rd | -12 | dB |
| t_{RISE} , 10-90% | 20 | ns | 4th and above | -20 | dB |
| t_{FALL} , 90-10% | 30 | ns | Input Impedances | | |
| Duty Cycle (+) Half Cycle | 51 | % | Chroma Modulator, Pins 2, 4 | 500k//2 pF | |
| (-) Half Cycle | 49 | % | RF Modulator, Pin 12 | 1M//2 pF | |
| RF Oscillator Maximum Operating Frequency | 100 | MHz | Pin 13 | 250k//3.5 pF | |
| (Temperature Stability Degraded) | | | | | |
| Chroma Modulator ($f = 3.58$ MHz) | | | | | |
| B-Y Conversion Gain $V_{13}/(V_4-V_3)$ | 0.6 | Vp-p/V | | | |
| R-Y Conversion Gain $V_{13}/(V_2-V_3)$ | 0.6 | Vp-p/V | | | |
| Gain Balance | ±0.5 | dB | | | |
| Bandwidth | See Curve | | | | |

AC Test Circuit



Typical Performance Characteristics



Circuit Description (Refer to Circuit Diagram)

The sound carrier oscillator is formed by differential amplifier Q3, Q4 operated with positive feedback from the pin 15 tank to the base of Q4.

The chroma oscillator consists of the inverting amplifier Q16, Q17 and Darlington emitter follower Q11, Q12. An external RC and crystal network from pin 17 to pin 18 provides an additional 180 degrees phase lag back to the base of Q17 to produce oscillation at the crystal resonance frequency. (See ac test circuit).

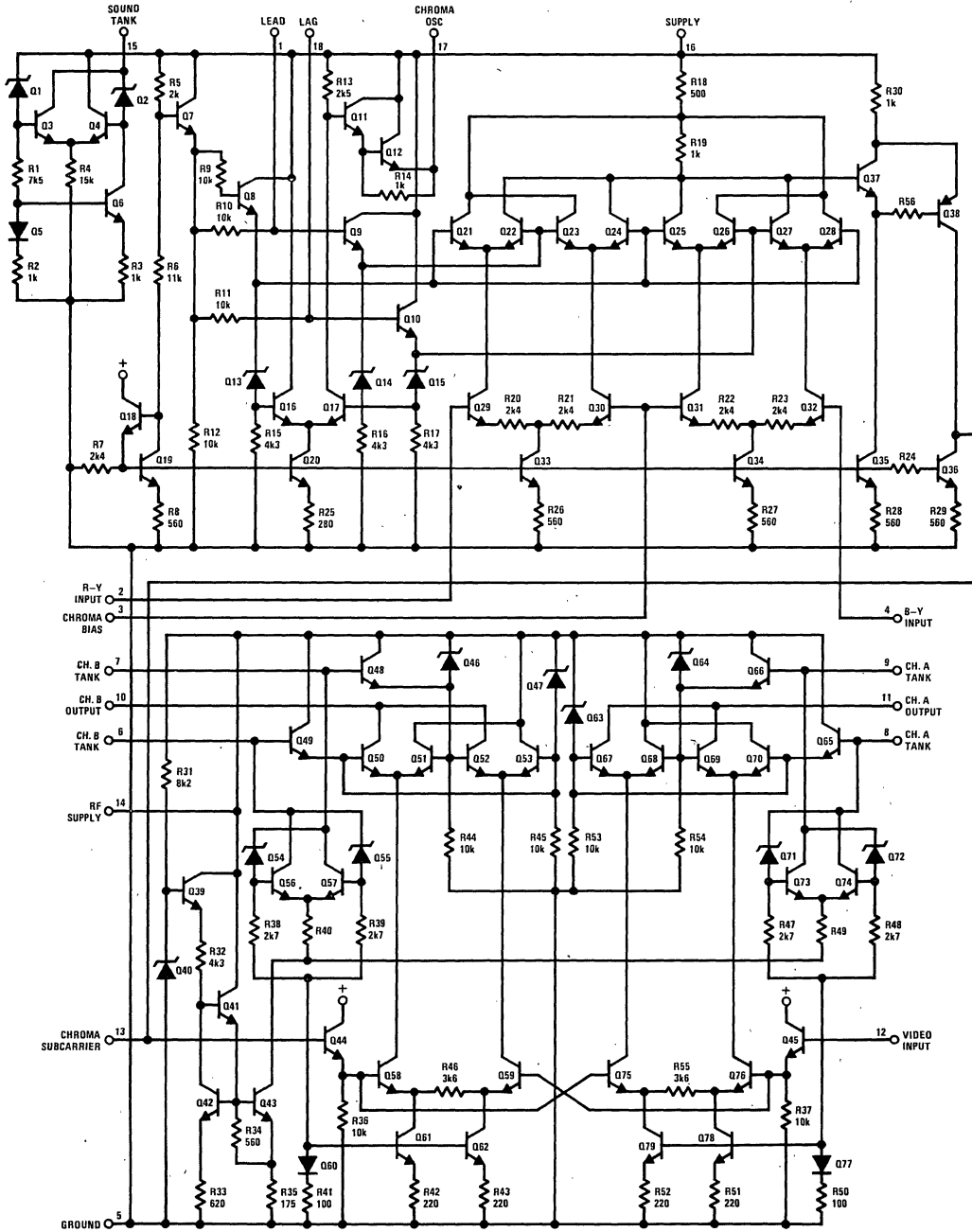
The feedback signal from the crystal is split in a lead-lag network to pins 1 and 18, respectively, to generate the subcarrier reference signals for the chroma modulators. The R-Y modulator consists of multiplier devices Q29, Q30 and Q21-Q24, while the B-Y modulator consists of Q31, Q32 and Q25-Q28. The multiplier outputs are coupled through a balanced summing amplifier Q37, Q38 to the input of the RF modulators at pin 13. With 0 offset at the lower pairs of the multipliers, no chroma output is produced. However, when either pin 2 or pin 4 is offset relative to pin 3 a subcarrier output current of the appropriate phase is produced at pin 13.

The channel B oscillator consists of devices Q56 and Q57 cross-coupled through level-shift zener diodes Q54 and Q55. A current regulator consisting of devices Q39-Q43 is used to achieve good RF frequency stability over supply and temperature. The channel B modulator consists of multiplier devices Q58, Q59 and Q50-Q53. The top quad is coupled to the channel B tank through isolating devices Q48 and Q49. A dc offset between pins 12 and 13 offsets the lower pair to produce an output RF carrier at pin 10. That carrier is then modulated by both the chroma signal at pin 13 and the video and sound carrier signals at pin 12. The channel A modulator shares pin 12 and 13 buffers Q45 and Q44 with channel B and operates in an identical manner.

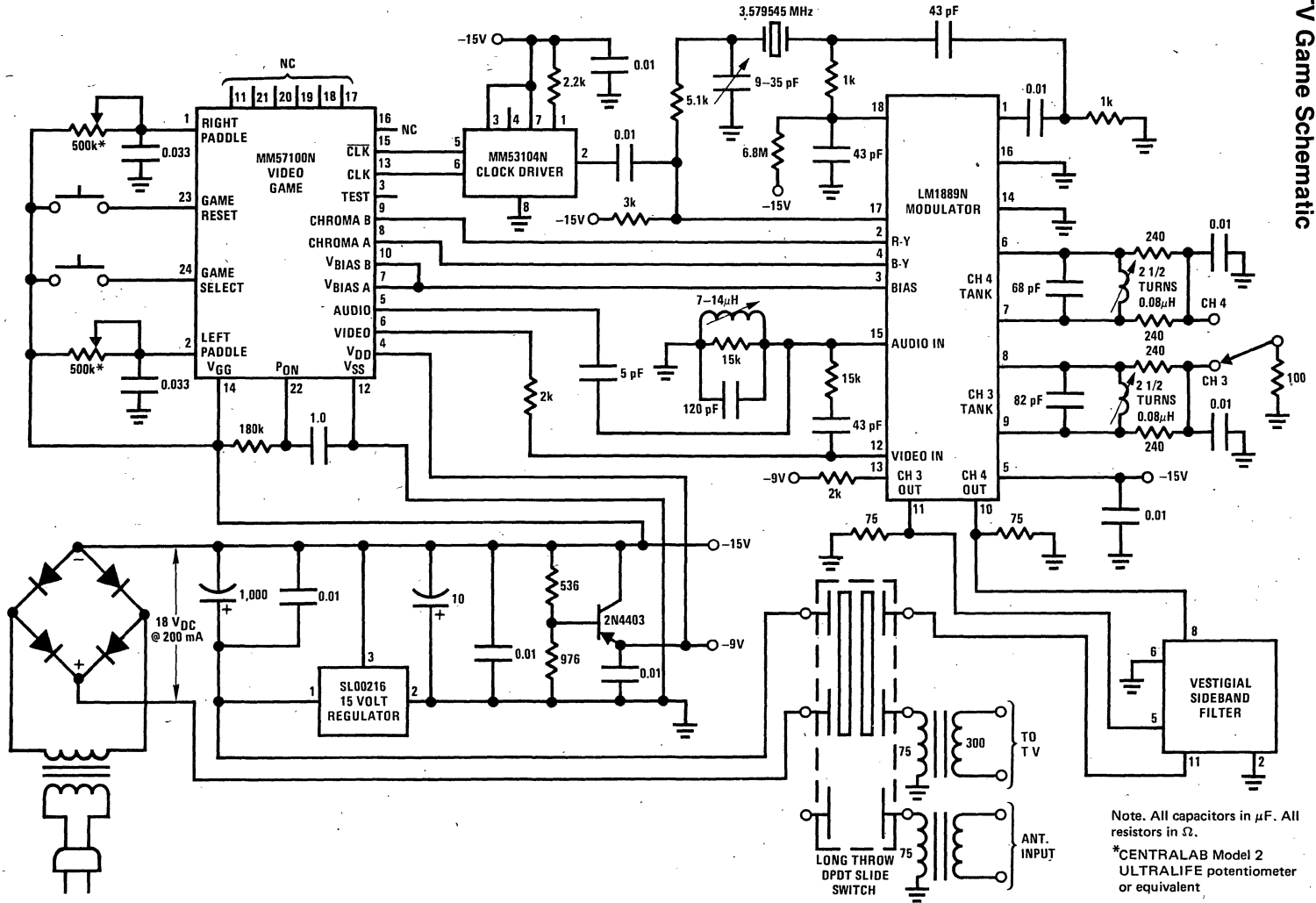
The current flowing through channel B oscillator diodes Q54, Q55 is turned around in Q60, Q61 and Q62 to source current for the channel B RF modulator. In the same manner, the channel A oscillator Q71-Q74 uses turn around Q77, Q78 and Q79 to source the channel A modulator. One oscillator at a time may be activated by connecting its tank to supply (see ac test circuit). The corresponding modulator is then activated by its current turn-around, and the other oscillator/modulator combination remains "OFF".

Circuit Diagram

LM1889



10-130



Note. All capacitors in μF . All resistors in Ω .
 *CENTRALAB Model 2 ULTRALIFE potentiometer or equivalent

Applications Information

Subcarrier Oscillator

The oscillator is a crystal-controlled design to ensure the accuracy and stability required of the subcarrier frequency for use with television receivers. Lag-lead networks (R2C2 and C1R1) define a quadrature phase relationship between pins 1 and 18 at the subcarrier frequency of 3.579545 MHz. Other frequencies can be used and where high stability is not a requirement, the crystal can be replaced with a parallel resonant L-C tank circuit—to provide a 2 MHz clock, for example. Note that since one of the chrominance modulators is internally connected to the feedback path of the oscillator, operation of the oscillator at other than the correct subcarrier frequency precludes chrominance modulation.

When an external subcarrier source is available or preferred, this can be used instead. For proper modulator operation, a subcarrier amplitude of 500 mVp-p is required at pins 1 and 18. If the quadrature phase shift networks shown in the application circuit are retained, about 1 Vp-p subcarrier injected at the junction of C1 and R2 is sufficient. The crystal, C4 and R3 are eliminated and pin 17 provides a 5 Vp-p signal shifted +125° from the external reference.

Chrominance Modulation

The simplest method of chroma encoding is to define the quadrature phases provided at pins 1 and 18 as the color difference axes R-Y and B-Y. A signal at pin 2 (R-Y) will give a chrominance subcarrier output from the modulator with a relative phase of 90° compared to the subcarrier output produced by a signal at pin 4 (B-Y). The zero signal dc level of the R-Y and B-Y inputs will determine the bias level required at pin 3. For example, a pin 2 signal that is 1V positive with respect to pin 3 will give 0.6 Vp-p subcarrier at a relative phase of 90°. If pin 2 is 1V negative with respect to pin 3, the output is again 0.6 Vp-p, but with a relative phase of 270°. When a simultaneous signal exists at pin 4, the subcarrier output level and phase will be the vector sum of the quadrature components produced by pin 2 and 4 inputs. Clearly, with the modulation axes defined as above, a negative pulse on pin 4 during the burst gate period will produce the chrominance synchronizing "burst" with a phase of 180°. Both color difference signals must be dc coupled to the modulators and the zero signal dc level of both must be the same and within the common-mode range of the modulators.

The 0.6 Vp-p/V_{dc} conversion gain of the chrominance modulators is obtained with a 2 kΩ resistor connected at pin 13. Larger resistor values can be used to increase the gain, but capacitance at pin 13 will reduce the bandwidth. Notice that equi-bandwidth encoding of the color difference signals is implied as both modulator outputs are internally connected and summed into the same load resistor.

Sound Oscillator

Frequency modulation is achieved by using a 4.5 MHz tank circuit and deviating the center frequency via a capacitor or a varactor diode. Switching a 5 pF capacitor

to ground at an audio frequency rate will cause a 50 kHz deviation from 4.5 MHz. A 1N5447 diode biased -4V from pin 16 will give ±20 kHz deviation with a 1 Vp-p audio signal. The coupling network to the video modulator input and the varactor diode bias must be included when the tank circuit is tuned to center frequency.

A good level for the RF sound carrier is between 2% and 20% of the picture carrier level. For example, if the peak video signal offset of pin 12 with respect to pin 13 is 3V, this corresponds to a 30 mVrms picture RF carrier. The source impedance at pin 12 is defined by the external 2 kΩ resistor and so a series network of 15 kΩ and 24 pF will give a sound carrier level at -32 dB to the picture carrier.

RF Modulation

Two RF channels are available, with carrier frequencies up to 100 MHz being determined by L-C tank circuits at pins 6, 7, 8 and 9. The signal inputs (pins 12, 13) to both modulators are common, but removing the power supply from an RF oscillator tank circuit will also disable that modulator.

As with the chrominance modulators, it is the offset between the two signal input pins that determines the level of RF carrier output. Since one signal input (pin 13) is also internally connected to the chrominance modulators, the 2 kΩ load resistor at this point should be connected to a bias source within the common-mode input range of the video modulators. However, this bias source is independent of the chrominance modulator bias and where chrominance modulation is not used, the 2 kΩ resistor is eliminated and the bias source connected directly to pin 13.

To preserve the dc content of the video signal, amplitude modulation of the RF carrier is done in one direction only, with increasing video (toward peak white) decreasing the carrier level. This means the active composite video signal at pin 12 must be offset with respect to pin 13 and the sync pulse should produce the largest offset (i.e., the offset voltage of pin 12 with respect to pin 13 should have the same polarity as the sync pulses).

The largest video signal (peak white) should not be able to suppress the carrier completely, particularly if sound transmission is needed. For example, a signal with 1V sync amplitude and 2.5V peak white (3.5 Vp-p — negative polarity sync) and a black level at 5 V_{dc} will require a dc bias of 8V on pin 13 for correct modulation. A simple way of obtaining the required offset is to bias pin 13 at 4 x (sync amplitude) from the sync tip level at pin 12.

Composite Video Output

When both chrominance and luminance modulation is being done, a simple technique can be used to check the chrominance to luminance ratio before modulation on the RF carrier. This is shown in *Figure 1* where the tank circuit of one RF oscillator has been replaced. Pin 8 is

Applications Information (Continued)

held one diode voltage drop below pin 9, thereby offsetting the upper rank of the modulator which now behaves as a cascade stage for the composite video signal. A $1.8\text{ k}\Omega$ resistor as a load at pin 11 gives a gain of about 0.5. If pin 11 is buffered by an external amplifier, composite video at 75Ω can be made available for injection into the video stage of a TV receiver. Putting the diode D1 in series with pin 9 will reverse the video polarity.

Split Power Supplies

The LM1889 is designed to operate over a wide range of supply voltages so that much of the time it can utilize the signal source power supplies. An example of this is shown in Figure 2 where the composite video signal from a character generator is modulated onto an RF carrier for display on a conventional home TV receiver. The LM1889 is biased between the -12V and $+5\text{V}$ supplies and pin 13 is put at ground. A $9.1\text{ k}\Omega$ resistor from pin 12 to -12V dc offsets the video input signal

(which has sync tips at ground) to establish the proper modulation depth — $R1/R2 = V_{IN}/12 \times 0.875$. This design is for monochrome transmission and features an extremely low external parts count.

Frequently, the use of split power supplies will make matching the LM1889 to available signal generator outputs a simple process. Figure 3a shows the LM1889 configured to accept the composite video patterns available from a Tektronix Type 144 generator that has black level at ground and negative polarity syncs. In this application the oscillator amplifier is used to provide a gain of two and a $10\text{ k}\Omega$ pot adjusts the over-all dc level of the amplified signal. Since the generator does not conveniently provide the required supply voltages, a circuit is shown in Figure 3b that will split 15V into $+5\text{V}$ and -10V . An advantage is that the supplies will track with the 15V source. However, once the modulation depth has been set, the supply voltage should be stabilized. The power supply "split" is set by the resistor connected to pin 1 of the LM380.

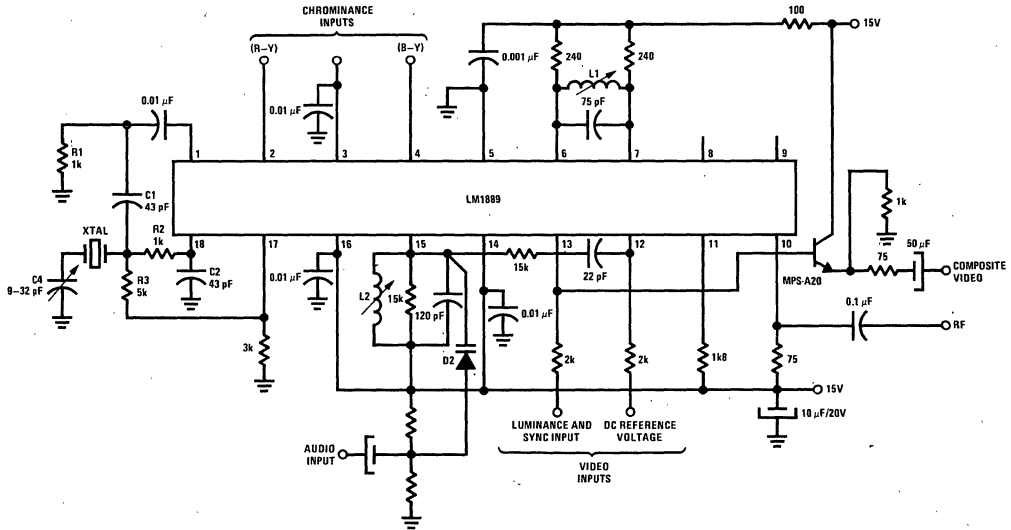


FIGURE 1. Luminance and Chrominance Encoding Composite Video or RF Output

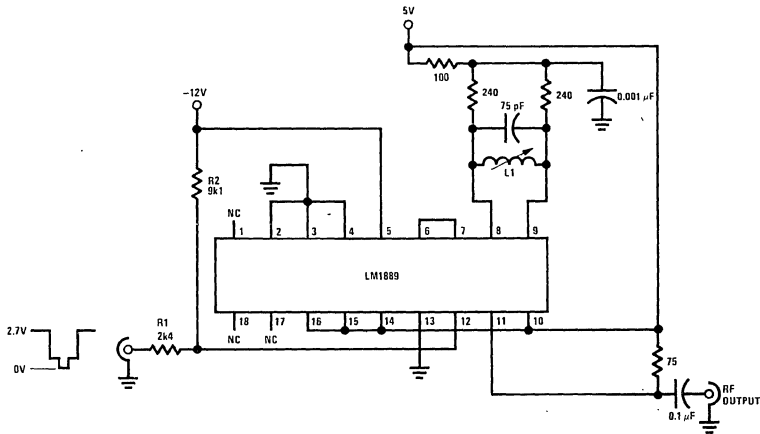


FIGURE 2. Low-Cost Monochrome Modulator for Character Generator Display

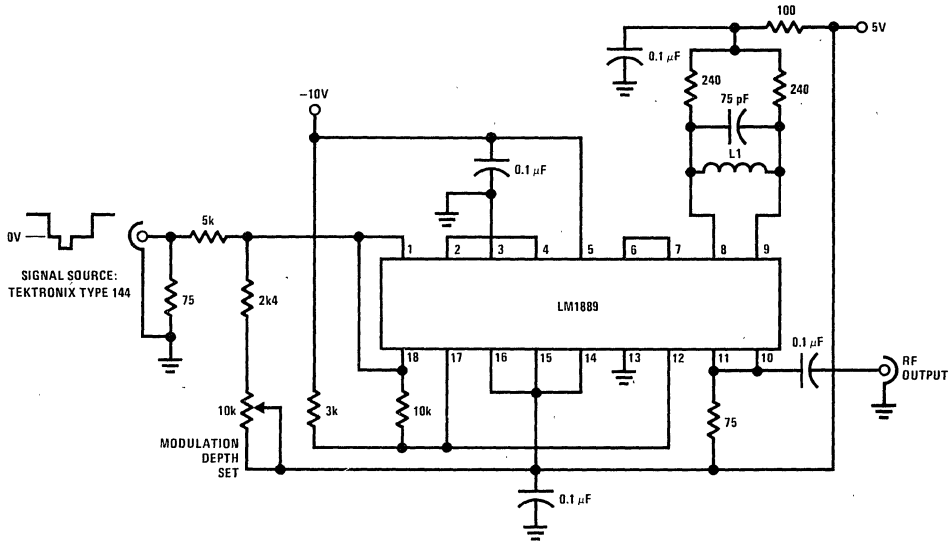


FIGURE 3a. dc Coupled Modulator for NTSC Pattern Generators

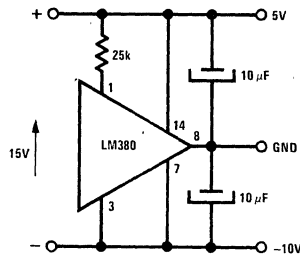


FIGURE 3b. Tracking Split Power Supply

LM1896/LM2896 Dual Power Audio Amplifier

General Description

The LM1896 is a high performance 6V stereo power amplifier designed to deliver 1 watt/channel into 4Ω or 2 watts bridged monaural into 8Ω. Utilizing a unique patented compensation scheme, the LM1896 is ideal for sensitive AM radio applications. This new circuit technique exhibits lower wideband noise, lower distortion, and less AM radiation than conventional designs. The amplifier's wide supply range (3V-9V) is ideal for battery operation. For higher supplies ($V_S > 9V$) the LM2896 is available in an 11-lead single-in-line package.

- 3V, 4Ω, stereo $P_o = 250$ mW
- Wide supply operation 3V-15V (LM2896)
- Low distortion
- No turn on "pop"
- Adjustable voltage gain and bandwidth
- Smooth waveform clipping
- $P_o = 9W$ bridged, LM2896

Features

- Low AM radiation
- Low noise

Applications

- Compact AM-FM radios
- Stereo tape recorders and players
- High power portable stereos

Typical Applications

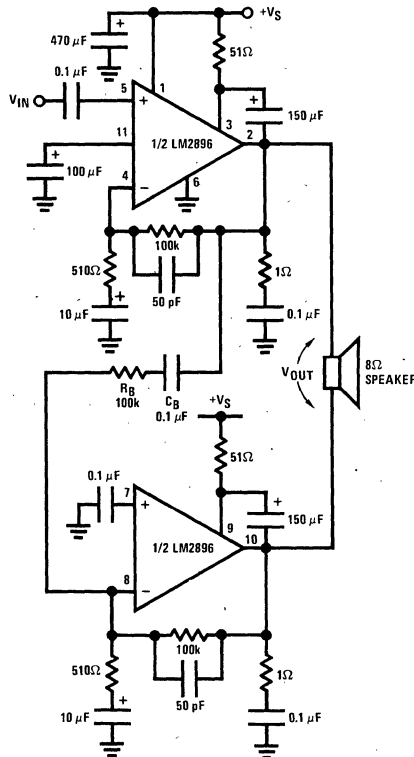


FIGURE 1. LM2896 in Bridge Configuration ($A_v = 400$, $BW = 20$ kHz)

Absolute Maximum Ratings

| | |
|---|---------------------------------|
| Supply Voltage | |
| LM1896 | $V_S = 12V$ |
| LM2896 | $V_S = 18V$ |
| Operating Temperature(Note 1) | $0^\circ C$ to $+70^\circ C$ |
| Storage Temperature | $-65^\circ C$ to $+150^\circ C$ |
| Junction Temperature | $150^\circ C$ |
| Lead Temperature(Soldering, 10 seconds) | $300^\circ C$ |

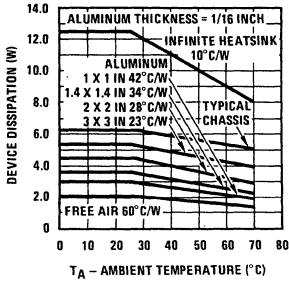
Electrical Characteristics Unless otherwise specified, $T_A = 25^\circ C$, $A_V = 200(46 \text{ dB})$. For the LM1896, $V_S = 6V$ and $R_L = 4\Omega$. For the LM2896, $V_S = 12V$ and $R_L = 8\Omega$. Test circuit shown in *Figure 2*.

| Parameter | Conditions | LM1896 | | | LM2896 | | | Units |
|-------------------------------------|---|--------|------|-----|--------|------|-----|------------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Supply Current | $P_O = 0W$, Dual Mode | | 15 | 25 | | 25 | 40 | mA |
| Operating Supply Voltage | | 3 | | 10 | 3 | | 15 | V |
| Output Power | THD = 10%, $f = 1 \text{ kHz}$ | | | | | | | |
| LM1896N-1 | $V_S = 6V$, $R_L = 4\Omega$ Dual Mode | 0.9 | 1.1 | | | | | W |
| LM1896N-2 | $V_S = 6V$, $R_L = 8\Omega$ Bridge Mode | 1.8 | 2.1 | | | | | W |
| | $V_S = 9V$, $R_L = 8\Omega$ Dual Mode | | 1.3 | | | | | W |
| LM2896P-1 | $V_S = 12V$, $R_L = 8\Omega$ Dual Mode | | | | 2.0 | 2.5 | | W |
| LM2896P-2 | $V_S = 12V$, $R_L = 8\Omega$ Bridge Mode | | | | 7.2 | 9.0 | | W |
| | $V_S = 9V$, $R_L = 4\Omega$ Bridge Mode | | | | | 7.8 | | W |
| | $V_S = 9V$, $R_L = 4\Omega$ Dual Mode | | | | | 2.5 | | W |
| Distortion | $f = 1 \text{ kHz}$ | | | | | | | |
| | $P_O = 50 \text{ mW}$ | | 0.09 | | | 0.09 | | % |
| | $P_O = 0.5W$ | | 0.11 | | | 0.11 | | % |
| | $P_O = 1W$ | | | | | 0.14 | | % |
| Power Supply Rejection Ratio (PSRR) | $C_{BY} = 100 \mu F$, $f = 1 \text{ kHz}$, $C_{IN} = 0.1 \mu F$ Output Referred, $V_{RIPPLE} = 250 \text{ mV}$ | -40 | -54 | | -40 | -54 | | dB |
| Channel Separation | $C_{BY} = 100 \mu F$, $f = 1 \text{ kHz}$, $C_{IN} = 0.1 \mu F$ Output Referred | -50 | -64 | | -50 | -64 | | dB |
| Noise | Equivalent input noise $R_S = 0$, $C_{IN} = 0.1 \mu F$, BW = 20 – 20 kHz | | 1.4 | | | 1.4 | | μV |
| | CCIR/ARM | | 1.4 | | | 1.4 | | μV |
| | Wideband | | 2.0 | | | 2.0 | | μV |
| DC Output Level | | 2.8 | 3 | 3.2 | 5.6 | 6 | 6.4 | V |
| Input Impedance | | 50 | 100 | 350 | 50 | 100 | 350 | k Ω |
| Input Offset Voltage | | | 5 | | | 5 | | mV |
| Voltage Difference Between Outputs | LM1896N-2, LM2896P-2 | | 10 | 20 | | 10 | 20 | mV |
| Input Bias Current | | | | 120 | | | 120 | nA |

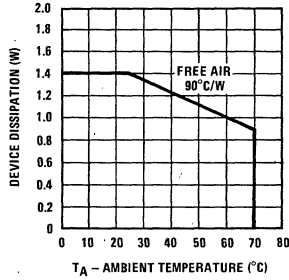
Note 1: For operation at ambient temperature greater than $25^\circ C$, the LM1896/LM2896 must be derated based on a maximum $150^\circ C$ junction temperature using a thermal resistance which depends upon mounting techniques.

Typical Performance Curves

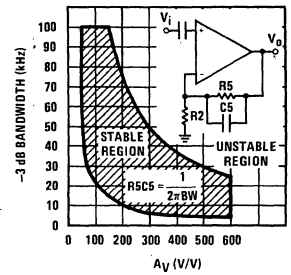
LM2896 Device Dissipation vs Ambient Temperature



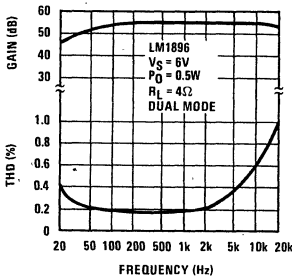
LM1896 Maximum Device Dissipation vs Ambient Temperature



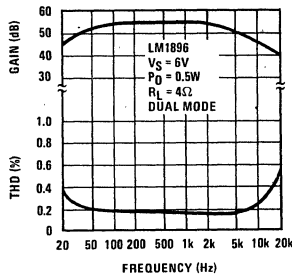
-3 dB Bandwidth vs Voltage Gain for Stable Operation



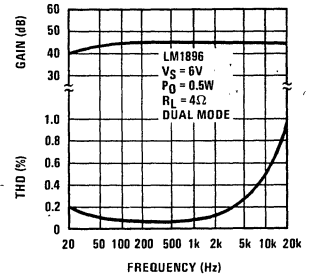
**THD and Gain vs Frequency
 $A_V = 54$ dB, BW = 30 kHz**



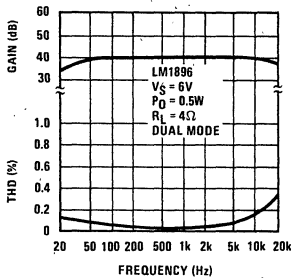
**THD and Gain vs Frequency
 $A_V = 54$ dB, BW = 5 kHz**



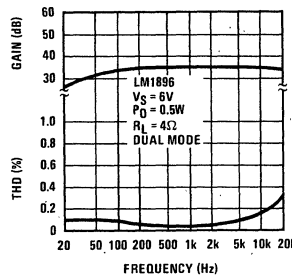
**THD and Gain vs Frequency
 $A_V = 46$ dB, BW = 50 kHz**



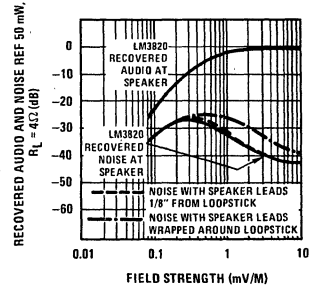
**THD and Gain vs Frequency
 $A_V = 40$ dB, BW = 20 kHz**



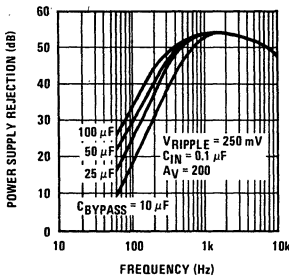
**THD and Gain vs Frequency
 $A_V = 34$ dB, BW = 50 kHz**



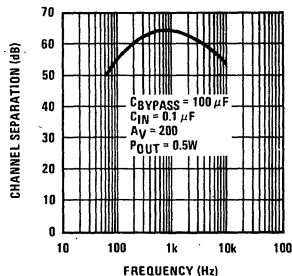
AM Recovered Audio and Noise vs Field Strength for Different Speaker Lead Placement



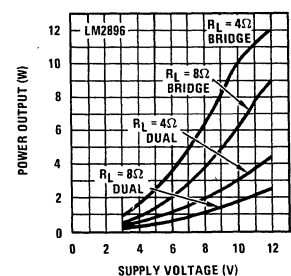
Power Supply Rejection Ratio (Referred to the Output) vs Frequency



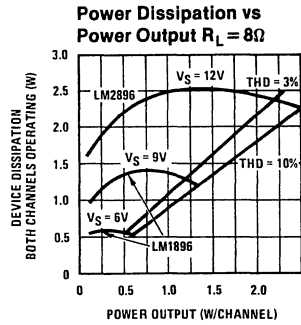
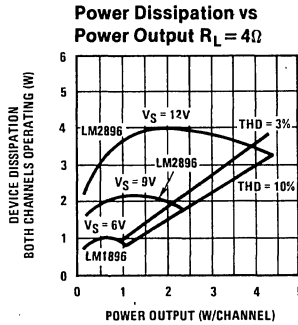
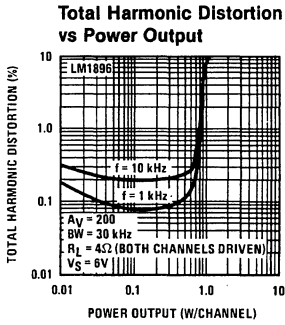
Channel Separation (Referred to the Output) vs Frequency



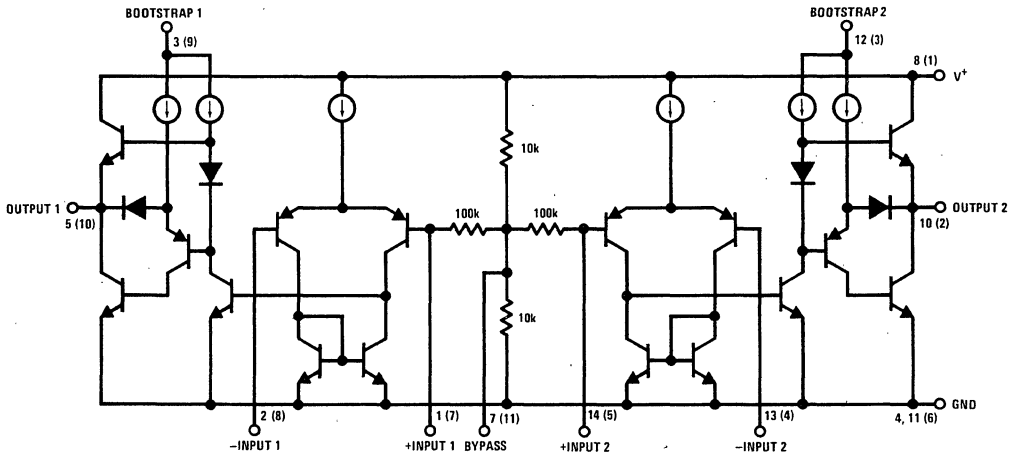
Power Output vs Supply Voltage



Typical Performance Curves (Continued)

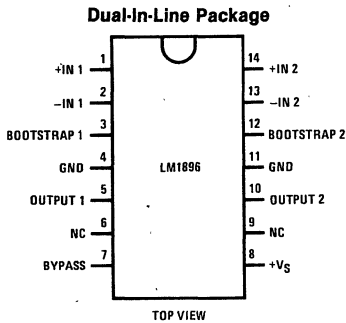


Equivalent Schematic

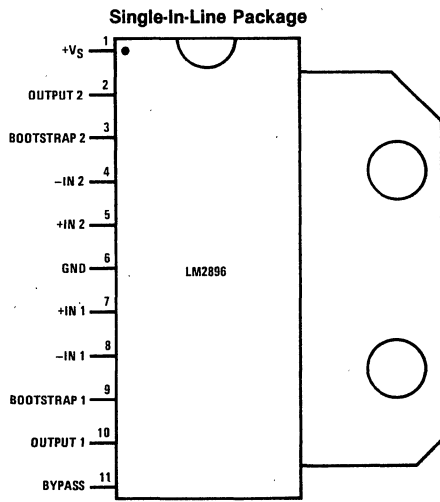


6, 9 No connection on LM1896
 () Indicates pin number for LM2896

Connection Diagrams

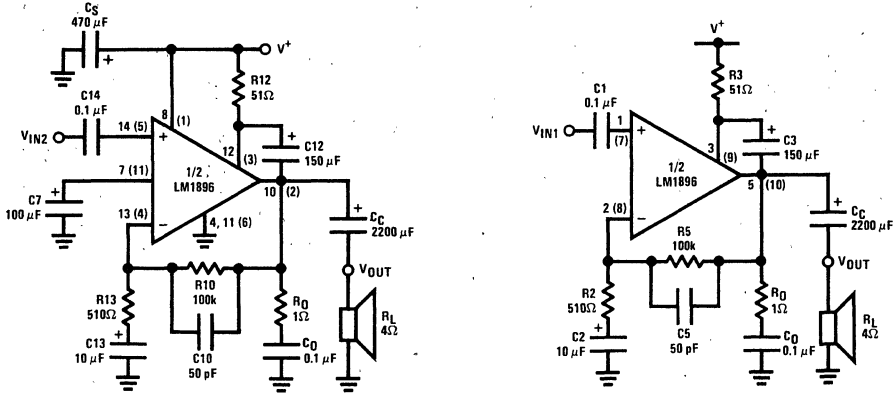


Order Number LM1896N
 See NS Package N14A



Order Number LM2896P
 See NS Package P11A

Typical Applications (Continued)



6, 9 No connection on LM1896
 () Indicates pin number for LM2896

FIGURE 2. Stereo Amplifier with $A_V = 200$, $BW = 30$ kHz

External Components (Figure 2)

| Components | Comments |
|---------------------|---|
| 1. R2, R5, R10, R13 | Sets voltage gain, $A_V = 1 + R5/R2$ for one channel and $A_V = 1 + R10/R13$ for the other channel. |
| 2. R3, R12 | Bootstrap resistor sets drive current for output stage and allows pins 3 and 12 to go above V_S . |
| 3. R_O | Works with C_O to stabilize output stage. |
| 4. C1, C14 | Input coupling capacitor. Pins 1 and 14 are at a DC potential of $V_S/2$. Low frequency pole set by: $f_L = \frac{1}{2\pi R_{IN} C1}$ |
| 5. C2, C13 | Feedback capacitors. Ensure unity gain at DC. Also a low frequency pole at: $f_L = \frac{1}{2\pi R2 C2}$ |
| 6. C3, C12 | Bootstrap capacitors, used to increase drive to output stage. A low frequency pole is set by: $f_L = \frac{1}{2\pi R3 C3}$ |
| 7. C5, C10 | Compensation capacitor. These stabilize the amplifiers and adjust their bandwidth. See curve of bandwidth vs allowable gain. |
| 8. C7 | Improves power supply rejection (See Typical Performance Curves). Increasing C7 increases turn-on delay. |
| 9. C_C | Output coupling capacitor. Isolates pins 5 and 10 from the load. Low frequency pole set by: $f_L = \frac{1}{2\pi C_C R_L}$ |
| 10. C_O | Works with R_O to stabilize output stage. |
| 11. C_S | Provides power supply filtering. |

Application Hints

AM Radios

The LM1896/LM2896 have been designed to fill a wide range of audio power applications. A common problem with IC audio power amplifiers has been poor signal-to-noise performance when used in AM radio applications. In a typical radio application, the loopstick antenna is in close proximity to the audio amplifier. Current flowing in the speaker and power supply leads can cause electromagnetic coupling to the loopstick, resulting in system oscillation. In addition, most audio power amplifiers are not optimized for lowest noise because of compensation requirements. If noise from the audio amplifier radiates into the AM section, the sensitivity and signal-to-noise ratio will be degraded.

The LM1896 exhibits extremely low wideband noise due in part to an external capacitor C5 which is used to tailor the bandwidth. The circuit shown in Figure 2 is capable of a signal-to-noise ratio in excess of 60 dB referred to 50 mW. Capacitor C5 not only limits the closed loop bandwidth, it also provides overall loop compensation. Neglecting C2 in Figure 2, the gain is:

$$A_V(S) = \frac{S + A_V \omega_o}{S + \omega_o}$$

where $A_V = \frac{R2 + R5}{R2}$, $\omega_o = \frac{1}{R5C5}$

A curve of -3 dB BW (ω_o) vs A_V is shown in the Typical Performance Curves.

Figure 3 shows a plot of recovered audio as a function of field strength in $\mu V/M$. The receiver section in this example is an LM3820. The power amplifier is located about two inches from the loopstick antenna. Speaker leads run parallel to the loopstick and are 1/8 inch from it. Referenced to a 20 dB S/N ratio, the improvement in noise performance over conventional designs is about 10 dB. This corresponds to an increase in usable sensitivity of about 8.5 dB.

Bridge Amplifiers

The LM1896/LM2896 can be used in the bridge mode as a monaural power amplifier. In addition to much higher power output, the bridge configuration does not require output coupling capacitors. The load is connected directly between the amplifier outputs as shown in Figure 4.

Amp 1 has a voltage gain set by $1 + R5/R2$. The output of amp 1 drives amp 2 which is configured as an inverting amplifier with unity gain. Because of this phase inversion in amp 2, there is a 6 dB increase in voltage gain referenced to V_i . The voltage gain in bridge is:

$$\frac{V_o}{V_i} = 2 \left(1 + \frac{R5}{R2} \right)$$

C_B is used to prevent DC voltage on the output of amp 1 from causing offset in amp 2. Low frequency response is influenced by:

$$f_L = \frac{1}{2\pi R_B C_B}$$

Several precautions should be observed when using the LM1896/LM2896 in bridge configuration. Because the amplifiers are driving the load out of phase, an 8 Ω speaker will appear as a 4 Ω load, and a 4 Ω speaker will appear as a 2 Ω load. Power dissipation is twice as severe in this situation. For example, if $V_S = 6V$ and $R_L = 8\Omega$ bridged, then the maximum dissipation is:

$$P_D = \frac{V_S^2}{20 R_L} \times 2 = \frac{6^2}{20 \times 4} \times 2$$

$$P_D = 0.9 \text{ Watts}$$

This amount of dissipation is equivalent to driving two 4 Ω loads in the stereo configuration.

When adjusting the frequency response in the bridge configuration, R5C5 and R10C10 form a 2 pole cascade and the -3 dB bandwidth is actually shifted to a lower frequency:

$$BW = \frac{0.64}{2\pi RC}$$

where R = feedback resistor

C = feedback capacitor

To measure the output voltage, a floating or differential meter should be used because a prolonged output short will over dissipate the package. Figure 1 shows the complete bridge amplifier.

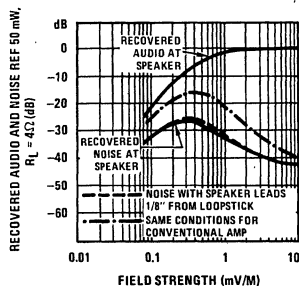


FIGURE 3. Improved AM Sensitivity Over Conventional Design

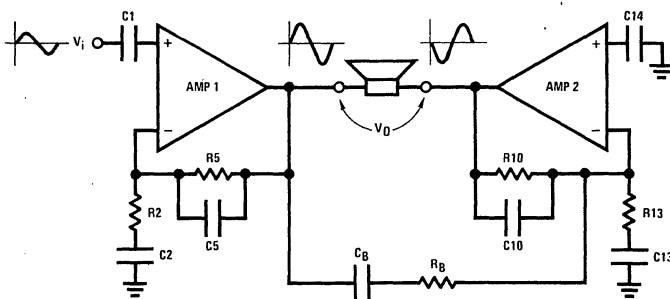


FIGURE 4. Bridge Amplifier Connection

Printed Circuit Layout

Printed Circuit Board Layout

Figure 5 and Figure 6 show printed circuit board layouts for the LM1896 and LM2896. The circuits are wired as stereo amplifiers. The signal source ground should return to the input ground shown on the boards. Returning the loads to power supply ground through a separate wire will keep the THD at its lowest value. The inputs should be terminated in less than 50 kΩ to prevent an input-output oscillation. This

oscillation is dependent on the gain and the proximity of the bridge elements R_B and C_B to the (+) input. If the bridge mode is not used, do not insert R_B , C_B into the PCB.

To wire the amplifier into the bridge configuration, short the capacitor on pin 7 (pin 1 of the LM1896) to ground. Connect together the nodes labeled BRIDGE and drive the capacitor connected to pin 5 (pin 14 of the LM1896).

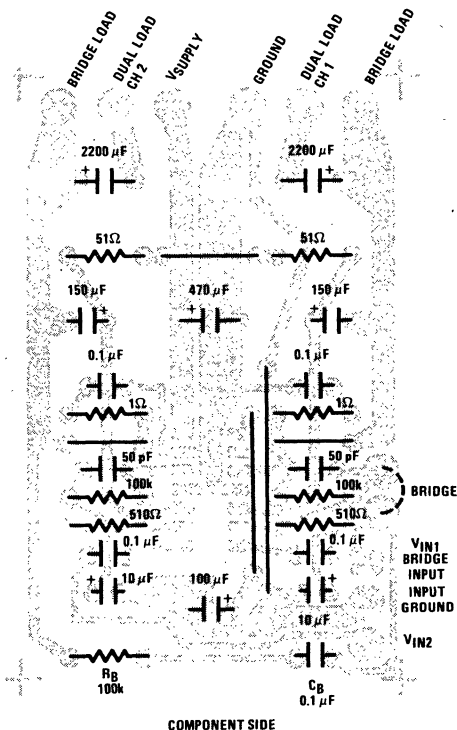


FIGURE 5. Printed Circuit Board Layout for the LM1896

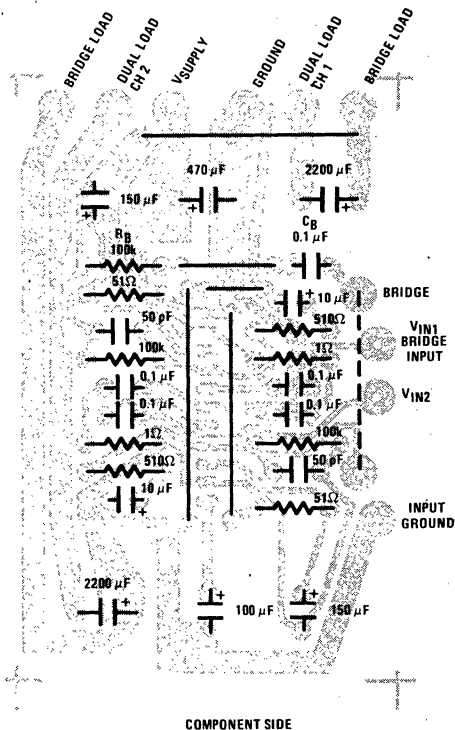


FIGURE 6. Printed Circuit Board Layout for the LM2896

LM2000 Audio Driver

General Description

The LM2000 is a low cost Audio Driver, designed to drive external power transistors. The amplifier will typically deliver 5 W into 4 Ω with a 12V supply. The LM2000 can operate with complementary NPN/PNP output transistors or with just PNP output devices.

A stable class A-B biasing scheme has been designed to prevent thermal runaway in the output transistors. The A-B bias transistor is internal, yet the amount of A-B bias current in the output stage can be externally adjusted. The bias stability is accomplished by forcing the base current in the power transistors instead of forcing their $V_{BE(on)}$.

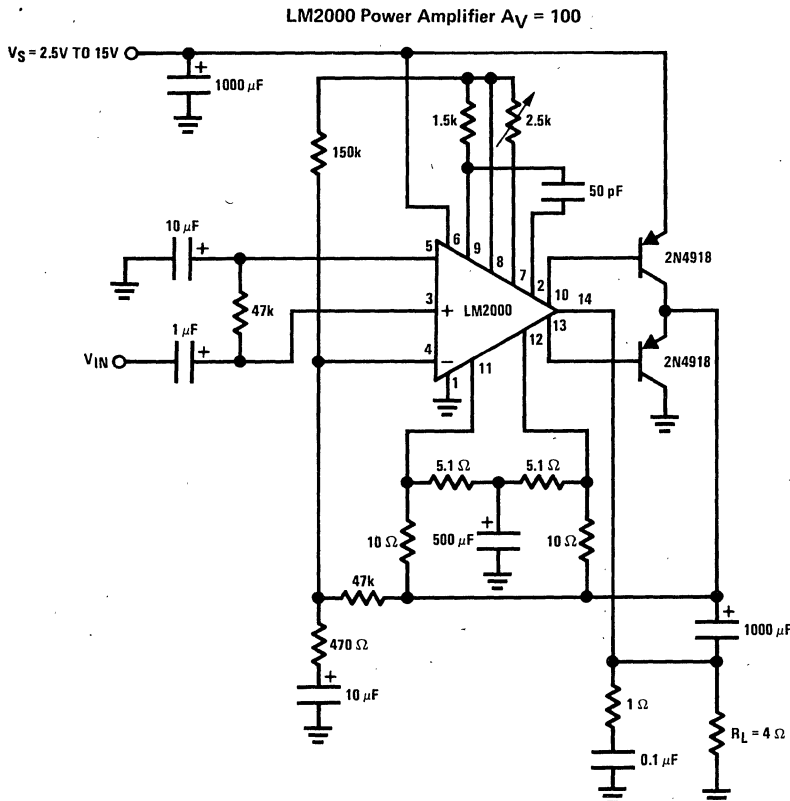
Features

- Battery operation
- Wide supply operation, 2.5–15V
- High output power
- Stable A-B bias current
- Adjustable drive current
- Adjustable gain and bandwidth
- No turn-on or turn-off "pops"
- Self-centered biasing

Applications

- AM-FM radios
- Cassette recorders
- Motor speed controls
- Toys
- Portable tape recorders/phonographs
- Intercoms

Typical Applications



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 18V |
| Package Dissipation (Note 1) | 1.39 W |
| Storage Temperature | -65°C to +150°C |
| Operating Temperature | 0°C to +70°C |
| Junction Temperature | 150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

$T_A = 25^\circ\text{C}$, $V_S = 9\text{V}$, $R_L = 4\ \Omega$, $A_V = 100$ (40 dB), $f = 1\ \text{kHz}$, 2N4918 output transistors, unless otherwise specified.

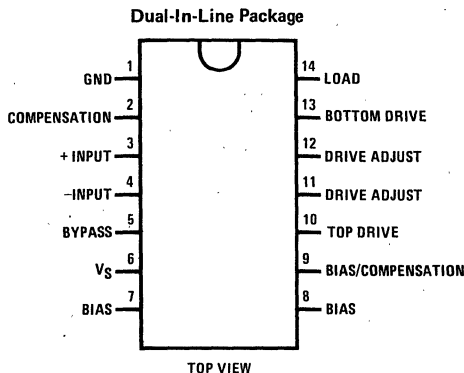
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------|---|--------------------|------|-----|---------------|
| Total Supply Current | $P_O = 0\ \text{W}$ | | 25 | | mA |
| IC Supply Current | Current Measured at Pin 6 | | 7 | 14 | mA |
| Operating Supply Voltage | | 2.5 | | 15 | V |
| Output Power (Note 2) | THD = 10% | | | | |
| | $V_S = 9\text{V}$, $R_L = 2\ \Omega$ | | 4.8 | | W |
| | $V_S = 9\text{V}$, $R_L = 4\ \Omega$ | | 2.8 | | W |
| | $V_S = 9\text{V}$, $R_L = 8\ \Omega$ | | 1.5 | | W |
| | $V_S = 12\text{V}$, $R_L = 2\ \Omega$ | | 8.8 | | W |
| | $V_S = 12\text{V}$, $R_L = 4\ \Omega$ | | 5 | | W |
| | $V_S = 12\text{V}$, $R_L = 8\ \Omega$ | | 2.6 | | W |
| Drive Current | Top or Bottom Side Sinking Current, Current Set Resistors 5.1 Ω and 10 Ω | 100 | 200 | | mA |
| Output Swing | $R_L = 2\ \Omega, 4\ \Omega, 8\ \Omega$ | $V_S - 2\ V_{SAT}$ | | | Vp-p |
| Total Harmonic Distortion | $P_O = 0.5\ \text{W}$, $f = 1\ \text{kHz}$ | | 0.25 | | % |
| Ripple Rejection | $C_{BYPASS} = 5\ \mu\text{F}$, $f = 1\ \text{kHz}$; Output Referred | 40 | 55 | | dB |
| Equivalent Input Noise | $R_S = 0$, $BW = 10\ \text{kHz}$ | | 3 | | μV |
| -3 dB Bandwidth | $C_{COMP} = 50\ \text{pF}$ (Note 3) | | 50 | | kHz |
| Input Bias Current | | | 1 | 4 | μA |

Note 1: For operating at elevated temperature, the device must be derated based on 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

Note 2: Output power is a function of the $V_{BE(on)}$ and R_{SAT} of the output transistors.

Note 3: C_{COMP} is the compensation capacitor used between pins 2 and 9.

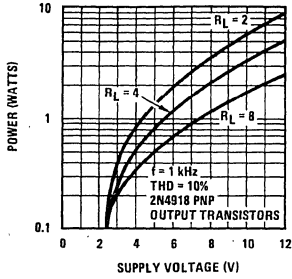
Connection Diagram



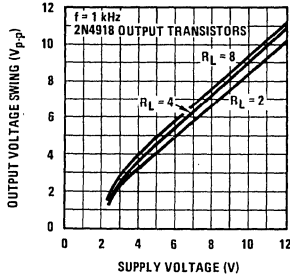
Order Number LM2000N
See NS Package N14A

Typical Performance Characteristics

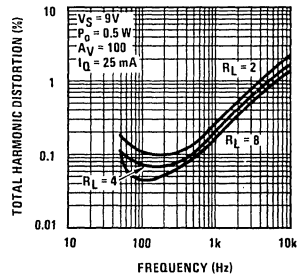
Power Output vs Supply Voltage



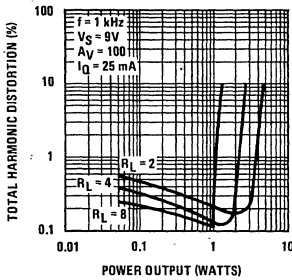
Peak-to-Peak Output Swing vs Supply Voltage



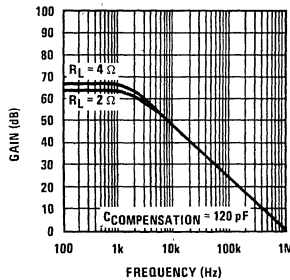
Distortion vs Frequency



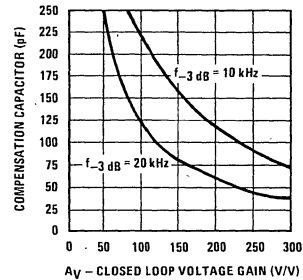
Distortion vs Output Power



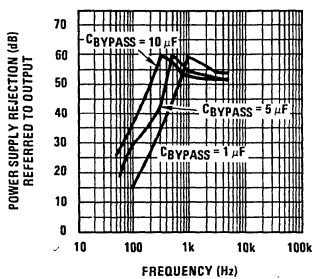
Open Loop Gain vs Frequency



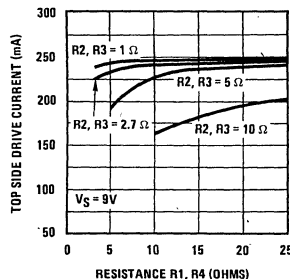
Compensation Capacitance vs Closed Loop Voltage Gain and Bandwidth



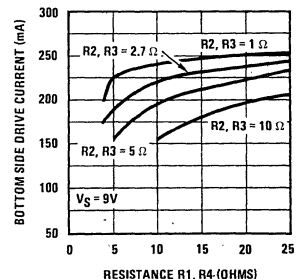
Power Supply Rejection Ratio vs Frequency



Top Side Drive Current vs Resistance (See Figure 1a)



Bottom Side Drive Current vs Resistance (See Figure 1a)

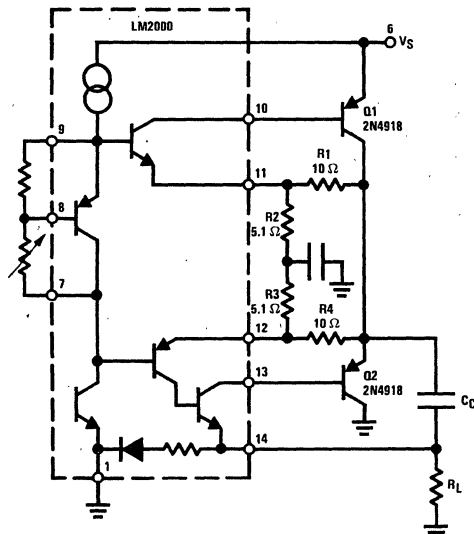


Circuit Description

The LM2000 Audio Driver has been designed to deliver maximum power into a 2 Ω, 4 Ω, or 8 Ω load, when used on a 2.5V to 12V supply. This high power is accomplished by using external power transistors with very low R_{SAT} . Figure 1a shows the output stage of the LM2000 which saturates these output devices. The output transistor completes a local feedback loop with the output stage of the driver. This output stage has voltage gain, set by R1, R2, R3 and R4 to allow the output sense to swing from V_S to ground without saturating any internal nodes. The output stage voltage gain is independent of the overall voltage gain A_V . Output transistors with low forced beta can be used since the drive current can be adjusted to meet the base current requirements of the output devices (see curves). In addition, C_C acts as a negative side bootstrap and acts to pull Q2 into saturation.

The LM2000 can be used to drive a complementary output pair as shown in Figure 1b. In this circuit, the coupling capacitor C_C no longer works as a bootstrap capacitor; Q2 will still saturate because large drive current supplied by the Darlington connection. This circuit performs optimally on $V_S = 4.5V$ to 15V. In a 70°C ambient temperature, power dissipation dictates allowable resistor and supply voltage ranges. For R2, R3 of Figures 1a and 1b, allowable values are:

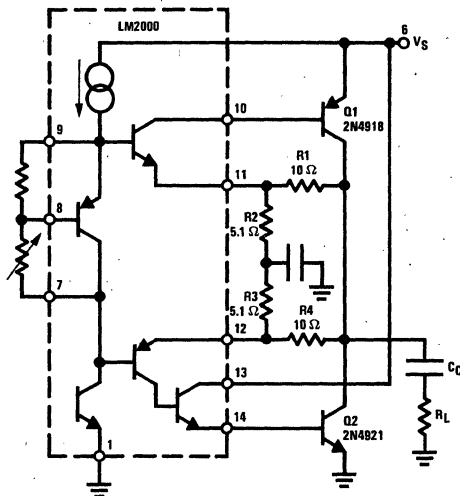
| min R2, R3 | V_S |
|------------|-------|
| 1 Ω | ≤ 9V |
| 2.7 Ω | ≤ 12V |
| 5.1 Ω | ≤ 15V |



○ DENOTES IC PIN CONNECTIONS

For $V_S \geq 12V$, make R1, R2, R3, R4 1 watt resistors.

FIGURE 1a. Output Stage of the LM2000 Driving PNP Output Transistors



For $V_S \geq 12V$, make R1, R2, R3, R4 1 watt resistors.

FIGURE 1b. Output Stage of the LM2000 Driving A Complementary Pair

Typical Applications (Continued)

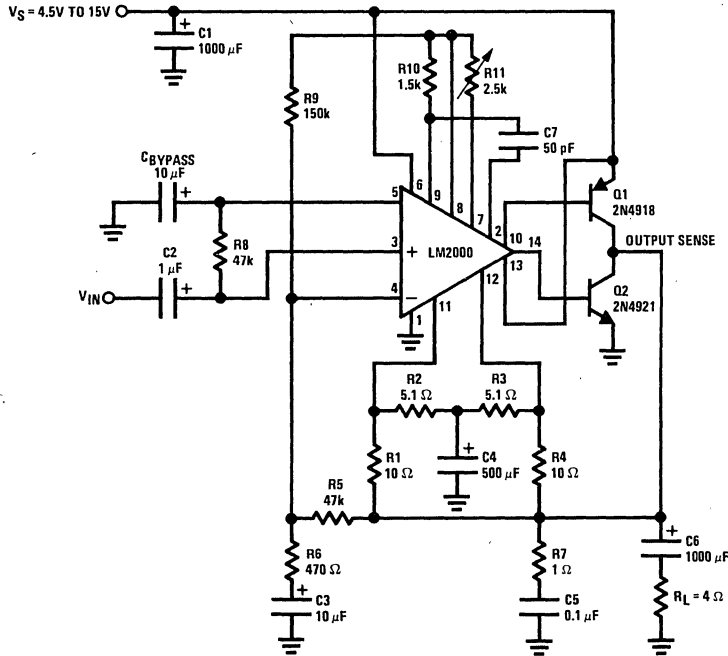
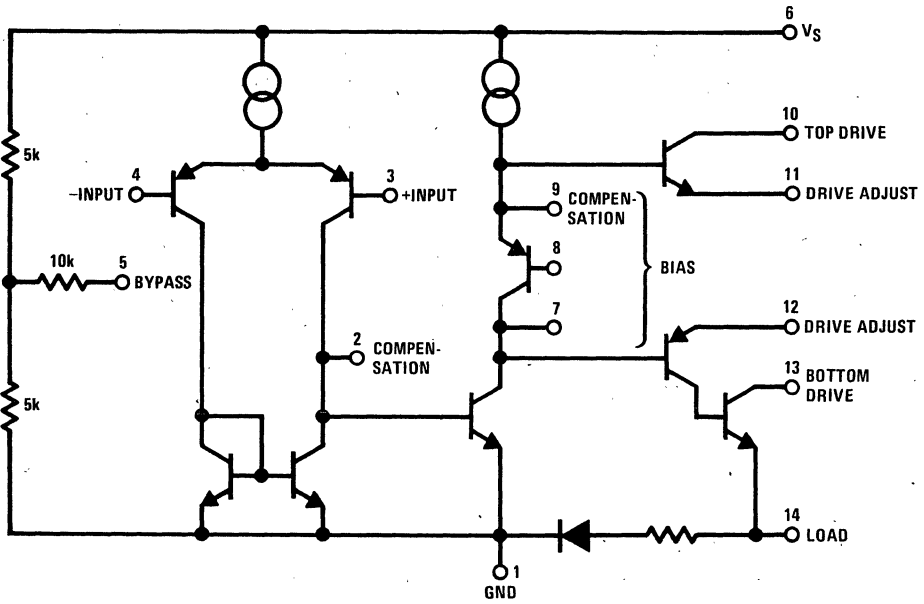


FIGURE 2. LM2000 Driving Complementary Pair

External Components (See Figure 2)

| COMPONENTS | COMMENTS | COMPONENTS | COMMENTS |
|-------------------|---|------------|--|
| 1. R1, R2, R3, R4 | Sets base drive current to output transistors and adjust voltage gain in output stage (See curves). For $V_S \geq 12V$ make resistors 1 watt. | 9. C2 | Input coupling capacitor. Pin 3 is at a DC potential of $V_{CC}/2$. Low frequency pole is set at: $f_L = \frac{1}{2\pi R8C2}$ |
| 2. R5, R6 | Sets amplifier voltage gain $A_V = 1 + R5/R6$. R5 should be less than 200k because of input bias current voltage drop. | 10. C3 | Feedback capacitor. Ensures unity gain at DC for minimum offset at output. Also sets a low frequency pole at: $f_L = \frac{1}{2\pi R6C3}$ |
| 3. R7, C5 | Stabilizes output stage. | 11. C4 | Sinks and sources drive current for output transistors Q1 and Q2. |
| 4. R8 | Sets input impedance and DC bias to + input. For minimum offset voltage, make $R8 = R5$. | 12. C6 | Output coupling capacitor. Isolates output sense from load. Low frequency effected by: $f_L = \frac{1}{2\pi C6R_L}$ |
| 5. R9 | Improves clipping waveform. | 13. C7 | C7 gives overall loop stability and adjusts bandwidth (See curves). |
| 6. R10, R11 | Sets A-B bias current in output transistors Q1 and Q2. | 14. Q1, Q2 | Power transistors. Supply current to load R_L . |
| 7. C1 | Provides power supply filtering. | | |
| 8. CBYPASS | Improves power supply rejection (See curves). | | |

Equivalent Schematic Diagram



LM2001 Low Voltage Audio Driver

General Description

The LM2001 is a low voltage audio driver, designed to drive low cost external power transistors. The driver is capable of delivering 100 mA of drive current on a 6V supply. Optimized for driving low impedance loads, the amplifier typically delivers 2.0W into 2Ω on a 6V supply. The LM2001 is designed to operate on supply voltages as low as 1.8V.

A stable AB bias scheme has been designed to prevent thermal runaway in the output transistors. The AB bias transistor is internal, yet the amount of AB bias current in the output stage can be externally adjusted. The bias stability is accomplished by forcing base current in the power transistors instead of forcing their $V_{BE(ON)}$.

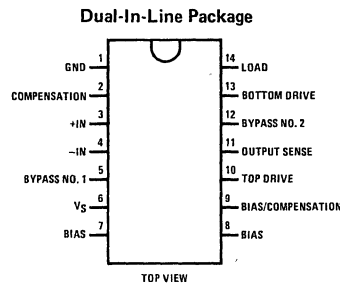
Features

- Battery operation
- Very low supply voltage operation, 1.8V
- High output power
- Stable AB bias current
- Adjustable gain and bandwidth
- No turn-ON or turn-OFF pops
- Self-centered biasing

Applications

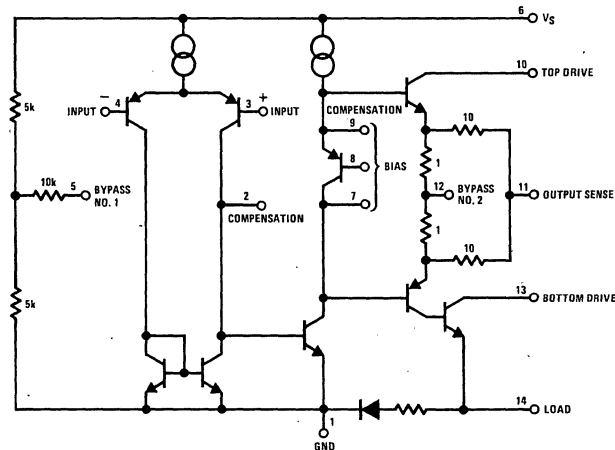
- AM-FM radios
- Cassette recorders
- Motor speed controls
- Toys
- Portable tape recorders/phonographs
- Intercoms

Connection Diagram



Order Number LM2001N
See NS Package N14A

Equivalent Schematic Diagram



Absolute Maximum Ratings

| | | | |
|------------------------------|-----------------|--|--------------|
| Supply Voltage | 7V | Operating Temperature | 0°C to +70°C |
| Package Dissipation (Note 1) | 1.39W | Junction Temperature | 150°C |
| Storage Temperature | -65°C to +150°C | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

$T_A = 25^\circ\text{C}$, $V_S = 6\text{V}$, $R_L = 2\Omega$, $A_V = 100$ (400 dB), $f = 1$ kHz, 92PE77A output transistors, unless otherwise specified.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------|---|------------------|------|-----|------------------|
| Total Supply Current | $P_O = 0\text{W}$ | | 25 | | mA |
| IC Supply Current | Current Measured at Pin 6 | | 5 | 10 | mA |
| Operating Supply Voltage | | 1.8 | | 6 | V |
| Output Power | THD = 10% | | | | |
| | $V_S = 6\text{V}$, $R_L = 2\Omega$ | | 2 | | W |
| | $V_S = 6\text{V}$, $R_L = 4\Omega$ | | 1.2 | | W |
| | $V_S = 6\text{V}$, $R_L = 8\Omega$ | | 600 | | mW |
| | $V_S = 3\text{V}$, $R_L = 2\Omega$ | | 480 | | mW |
| | $V_S = 3\text{V}$, $R_L = 4\Omega$ | | 280 | | mW |
| Drive Current | $V_S = 3\text{V}$, $R_L = 8\Omega$ | | 160 | | mW |
| | Top or Bottom Side Sinking Current, External Power Transistors $V_{BE(ON)} = 0.9\text{V}$ | 100 | 150 | | mA |
| Output Swing | $R_L = 2\Omega$, 4Ω or 8Ω | $V_S - 2V_{SAT}$ | | | V _{p-p} |
| Total Harmonic Distortion | $V_S = 6\text{V}$, $R_L = 2\Omega$, $P_O = 0.5\text{W}$, $f = 1$ kHz | | 0.25 | | % |
| Ripple Rejection | $C_{BYPASS NO. 1} = 5 \mu\text{F}$, $f = 1$ kHz, Output Referred | 40 | 60 | | dB |
| Equivalent Input Noise | $R_S = 0$, $BW = 10$ kHz | | 3 | | μV |
| -3 dB Bandwidth | $C_{COMP} = 50$ pF | | 50 | | kHz |
| Input Bias Current | | | 1 | 4 | μA |

Note 1: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

External Components (Figure 2)

| COMPONENTS | COMMENTS | COMPONENTS | COMMENTS |
|------------|---|------------------------|---|
| 1. R1 | Sets input impedance and DC bias to +input. For minimum offset voltage, make $R1 = R3$. | 7. C3 | Provides power supply filtering. |
| 2. R2, R3 | Sets voltage gain, $A_V = 1 + R3/R2$. R3 should be less than 200k because of input bias current voltage drop. | 8. C4 | C4 gives overall loop stability and adjusts bandwidth (see curves). |
| 3. R4, R5 | Set AB bias current in output transistors Q1 and Q2. | 9. C5 | Output coupling capacitor. Isolates pin 11 from load. Low frequency effected by: $f_L = \frac{1}{2\pi C5 R_L}$ |
| 4. R6, C6 | Stabilizes output stage. | 10. $C_{BYPASS NO. 1}$ | Improves power supply rejection (see curves). |
| 5. C1 | Input coupling capacitor. Pin 3 is at a DC potential of $V_{CC}/2$. Low frequency pole is set at: $f_L = \frac{1}{2\pi R1 C1}$ | 11. $C_{BYPASS NO. 2}$ | Sinks and sources drive current for output transistors Q1 and Q2. |
| 6. C2 | Feedback capacitor. Ensures unity gain at DC for minimum offset at output. Also sets a low frequency pole at: $f_L = \frac{1}{2\pi R2 C2}$ | 12. R7 | Improves clipping waveform. |
| | | 13. Q1, Q2 | Power transistors. Supply current to load R_L . |

Circuit Description

The LM2001 audio driver has been designed to fill a large number of low voltage applications. The requirements of adjustable gain, bandwidth, and quiescent current as well as high power output, low voltage operation, and a stable bias scheme makes this driver quite versatile.

High output power is achieved by using external PNP transistors with low R_{SAT} . As seen in *Figure 1*, the

output transistors complete a local feedback loop with the output stage of the driver. This output stage has voltage gain to allow the output sense pin to swing from V_S to ground without saturating internal nodes of the driver. Output transistors with a forced beta as low as 10 are capable of supplying 1A to the load because $C_{BYPASS\ NO.\ 2}$ enables the drive transistors to sink 100 mA. The output coupling capacitor C_C acts as a negative side bootstrap. When the output signal swings negative, C_C acts to pull Q2 into saturation.

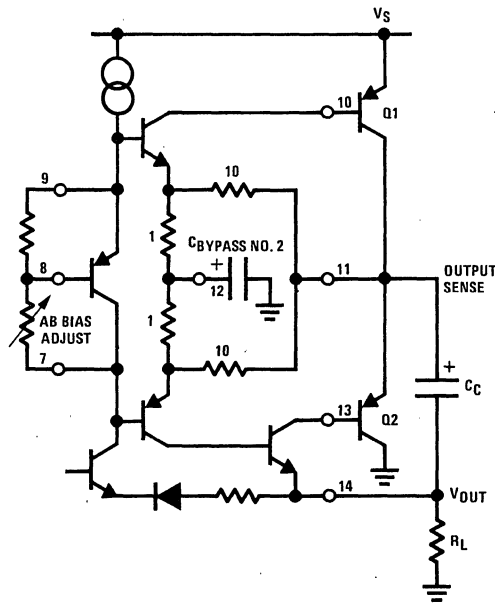


FIGURE 1. Output Stage of the LM2001

Typical Applications

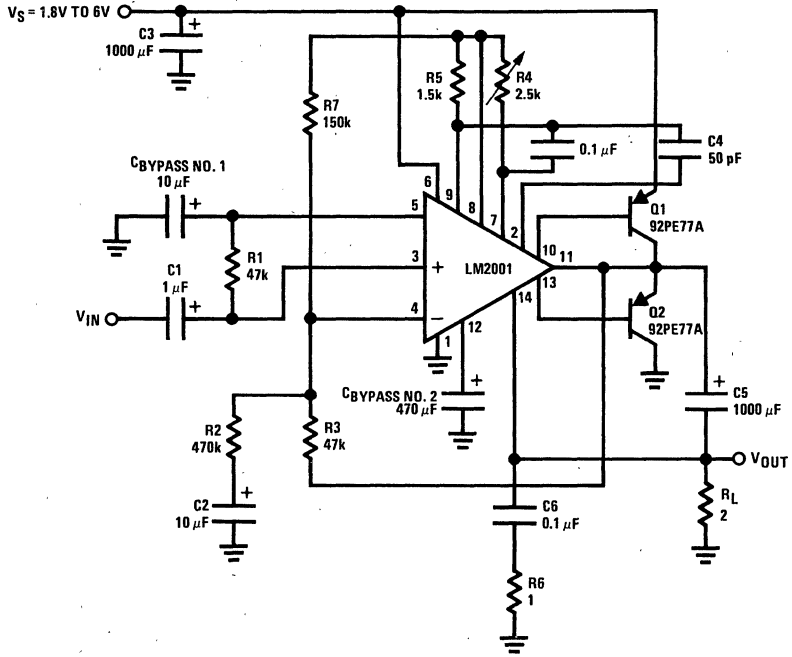


FIGURE 2. LM2001 Power Amplifier, $A_V \cong 100$

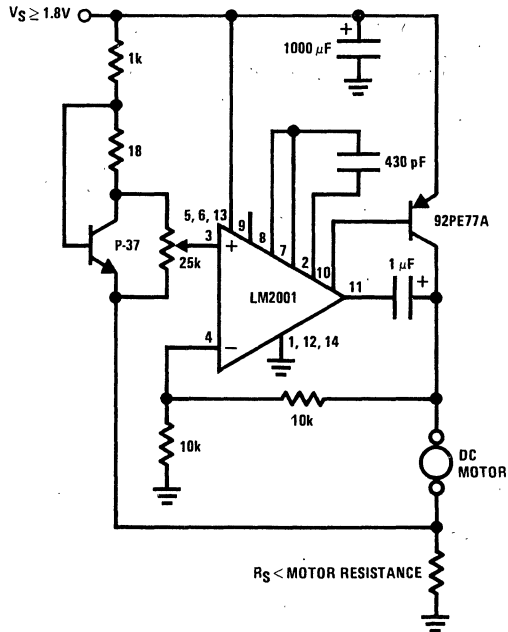
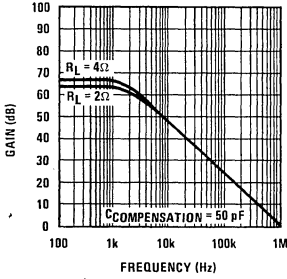


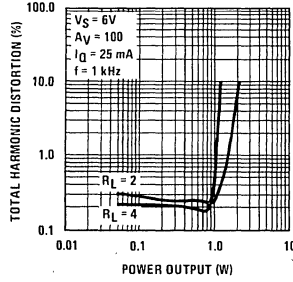
FIGURE 3. LM2001 Motor Speed Control

Typical Performance Characteristics

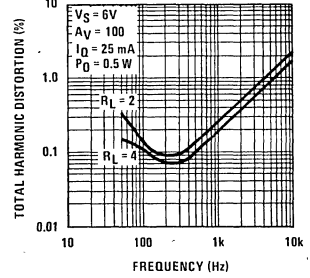
Open Loop Gain vs Frequency



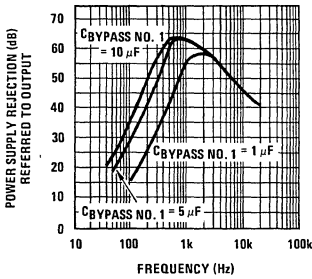
Distortion vs Output Power



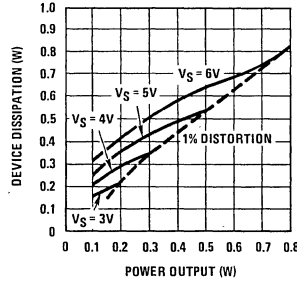
Distortion vs Frequency



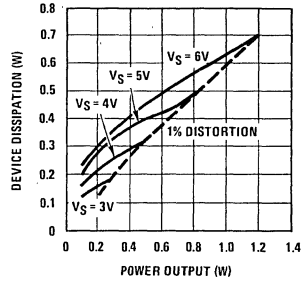
Power Supply Rejection Ratio vs Frequency



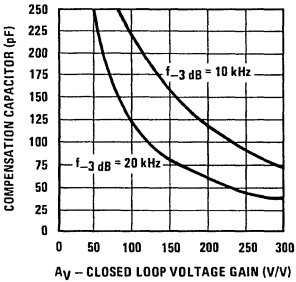
Device Dissipation vs Output Power 4Ω Load



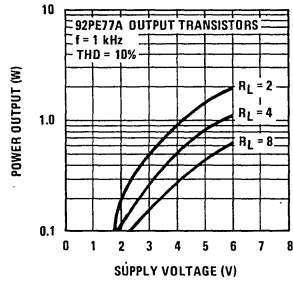
Device Dissipation vs Output Power 2Ω Load



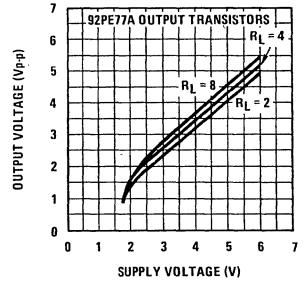
Compensation Capacitor vs Closed Loop Voltage Gain and Bandwidth



Power Output vs Supply Voltage



Peak-to-Peak Output Voltage Swing vs Supply Voltage





LM2002/LM2002A 8 Watt Audio Power Amplifier

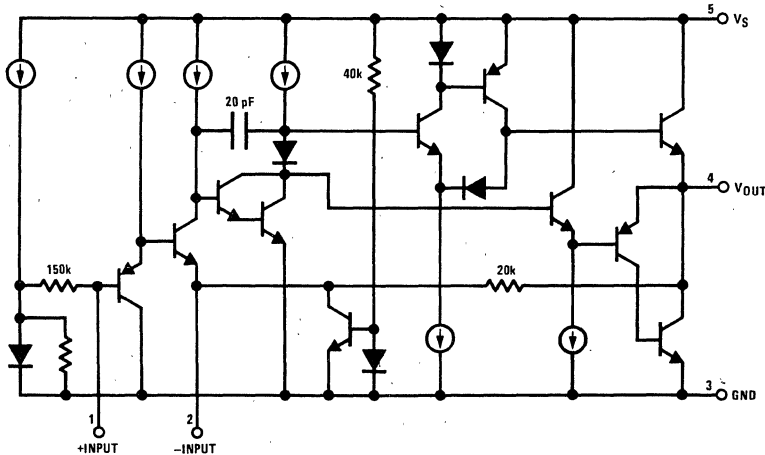
General Description

The LM2002 is a cost effective, high power amplifier suited for automotive applications. High current capability (3.5A) enables the device to drive low impedance loads with low distortion. The LM2002 is current limited and thermally protected. High voltage protection is available (LM2002A) which enables the amplifier to withstand 40V transients on its supply. The LM2002 comes in a 5-pin TO-220 package.

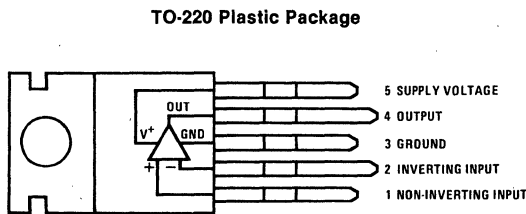
Features

- High, peak current capability (3.5A)
- Large output voltage swing
- Externally programmable gain
- Wide supply voltage range (5V-20V)
- Few external parts required
- Low distortion
- High input impedance
- No turn-on transients
- High voltage protection available (LM2002A)
- Low noise
- Short circuit protected
- Pin for pin compatible with TDA2002

Equivalent Schematic

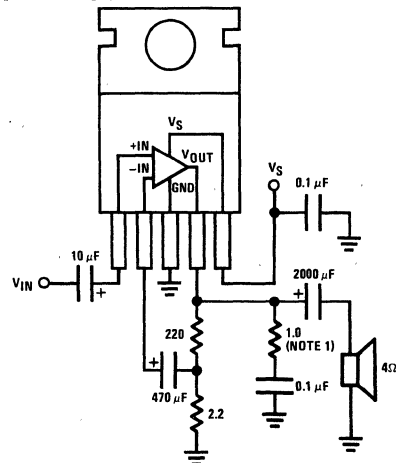


Connection Diagram



Order Number LM2002T or LM2002AT
See NS Package T05A

Typical Applications



Absolute Maximum Ratings

| | |
|---|-------------------|
| Peak Supply Voltage (50 ms) | |
| LM2002A(Note2) | 40V |
| LM2002 | 25V |
| Operating Supply Voltage | 20V |
| Output Current | |
| Repetitive | 3.5A |
| Non-repetitive | 4.5A |
| Input Voltage | ± 0.5V |
| Power Dissipation(Note3) | 15W |
| Operating Temperature | 0°C to + 70°C |
| Storage Temperature | - 60°C to + 150°C |
| Lead Temperature(Soldering, 10 seconds) | 300°C |

Electrical Characteristics $V_S = 14.4V$, $T_{TAB} = 25^\circ C$, $A_V = 100$ (40 dB), $R_L = 4\Omega$, unless otherwise specified

| Parameter | Conditions | Min | Typ | Max | Units |
|--------------------------|--|----------|-------------------|-----|-------------|
| DC Output Level | | 6.4 | 7.2 | 8 | V |
| Quiescent Supply Current | Excludes Current in Feedback Resistors | | 45 | 80 | mA |
| Supply Voltage Range | | 5 | | 20 | V |
| Input Resistance | | | 150 | | k Ω |
| Bandwidth | Gain = 40 dB | | 100 | | kHz |
| Output Power | $V_S = 13.2V$, $f = 1$ kHz $R_L = 4\Omega$, THD = 10% $R_L = 2\Omega$, THD = 10% | | 4.3 6.5 | | W W |
| | $V_S = 13.8V$, $f = 1$ kHz $R_L = 4\Omega$, THD = 10% $R_L = 2\Omega$, THD = 10% | | 4.8 7.4 | | W W |
| | $V_S = 14.4V$, $f = 1$ kHz $R_L = 4\Omega$, THD = 10% $R_L = 2\Omega$, THD = 10% $R_L = 1.6\Omega$, THD = 10% | 4.8 7 | 5.2 8 9 | | W W W |
| | $V_S = 16V$, $f = 1$ kHz $R_L = 4\Omega$, THD = 10% $R_L = 2\Omega$, THD = 10% $R_L = 1.6\Omega$, THD = 10% | | 6.5 10 10.5 | | W W W |
| THD | $P_O = 2W$, $R_L = 4\Omega$, $f = 1$ kHz $P_O = 4W$, $R_L = 2\Omega$, $f = 1$ kHz | | 0.1 0.1 | | % % |
| Ripple Rejection | $R_S = 50\Omega$, $f = 100$ Hz $R_S = 50\Omega$, $f = 1$ kHz | 30 | 40 44 | | dB dB |
| Input Noise Voltage | $R_S = 0$, 15 kHz Bandwidth | | 2 | | μV |
| Input Noise Current | $R_S = 100$ k Ω , 15 kHz Bandwidth | | 40 | | pA |

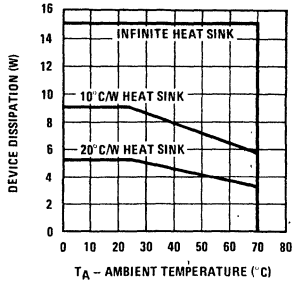
Note 1: A 1.0 resistor and 0.1 μF capacitor should be placed as close as possible to pins 3 and 4 for stability.

Note 2: The LM2002 shuts down above 25V.

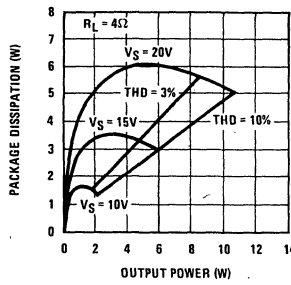
Note 3: For operating at elevated temperatures, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 4°C/W junction to case.

Typical Performance Characteristics

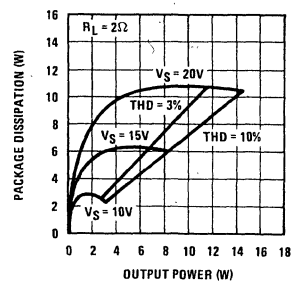
Device Dissipation vs Ambient Temperature



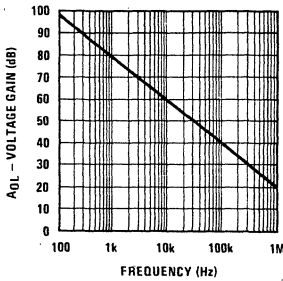
Power Dissipation vs Output Power



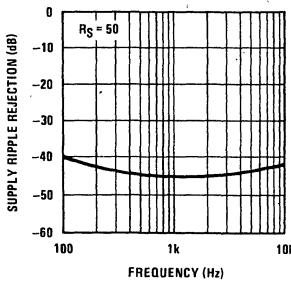
Power Dissipation vs Output Power



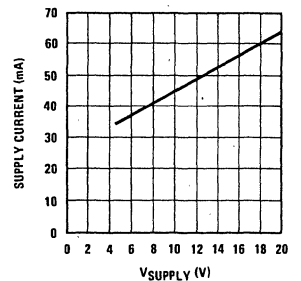
Open Loop Gain vs Frequency



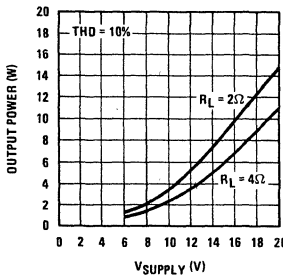
Supply Ripple Rejection vs Frequency



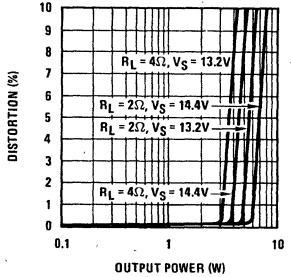
Supply Current vs Supply Voltage



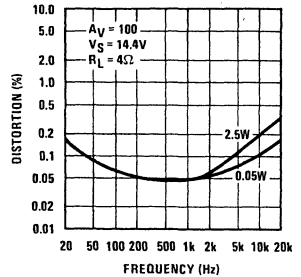
Output Power vs Supply Voltage



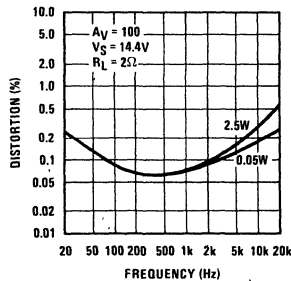
Distortion vs Output Power



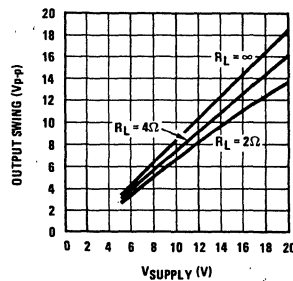
Distortion vs Frequency



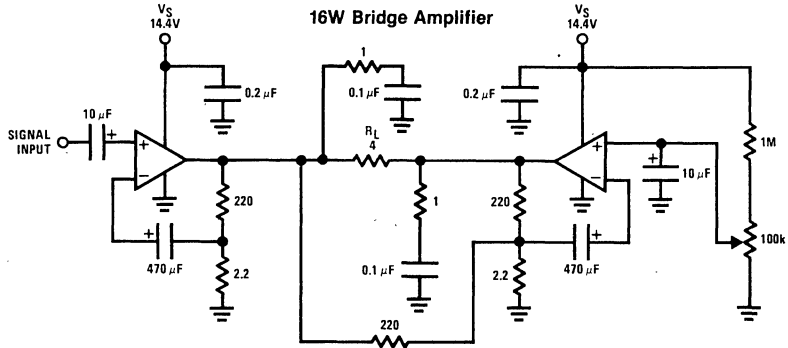
Distortion vs Frequency



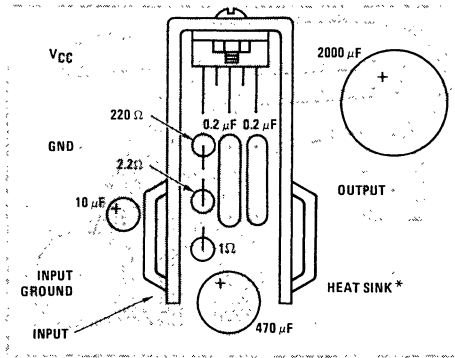
Output Swing vs Supply Voltage



Typical Applications (Continued)



Component Layout



* Staver V-5

LM2808 Monolithic TV Sound System

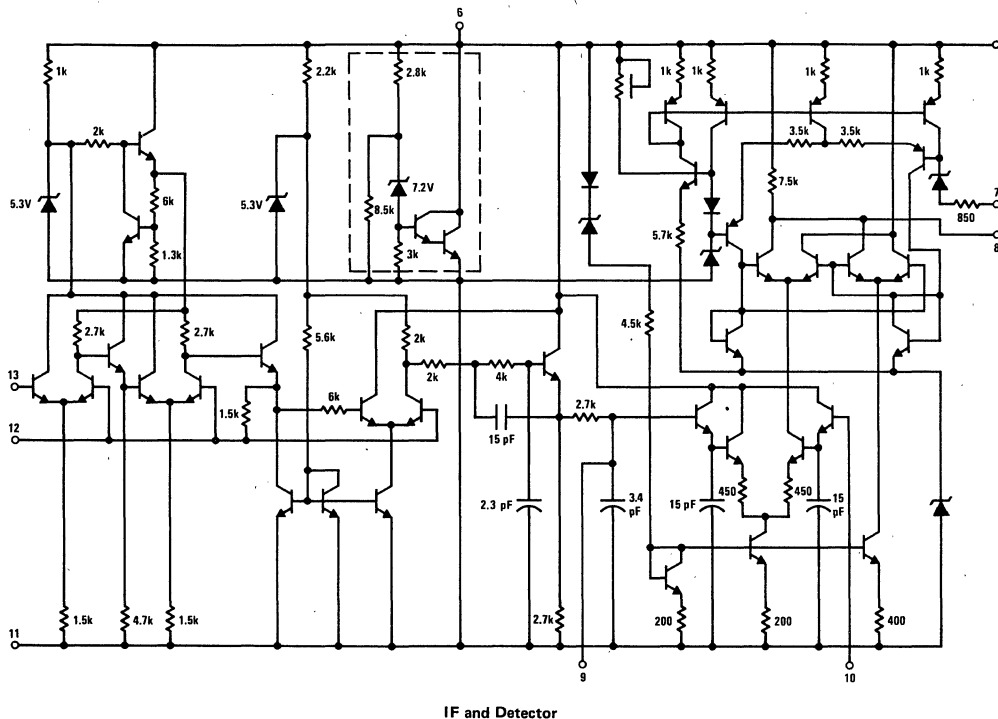
General Description

The LM2808 2W sound IF circuit is designed for television and related applications. The circuit is comprised of 2 independent functions: a sound IF and an audio power amplifier. An improved volume control circuit is included, however, so that recovered audio is a linear function of the resistance of the control potentiometer. Audio power amplification is accomplished with circuitry similar to the popular LM380 audio power amplifier, featuring both short circuit and thermal protection.

Features

- Minimum undistorted output
LM2808 — 0.5W
- Linear volume control — 75 dB range
- Fixed voltage gain in audio amplifier
- Short circuit and thermal protection
- Standard dual-in-line package

Schematic Diagrams (For power amplifier section of schematic, see next page)



Absolute Maximum Ratings

Supply Voltage, V_{CC} (Pin 2)

LM2808

20V

Input Current, I_{MAX} (Pin 6)

50 mA

Input Signal Voltage (Between Pins 12 and 13)

3 Vp-p

Storage Temperature Range

-65°C to +150°C

Operating Temperature Range

0°C to +70°C

Maximum Junction Temperature

150°C

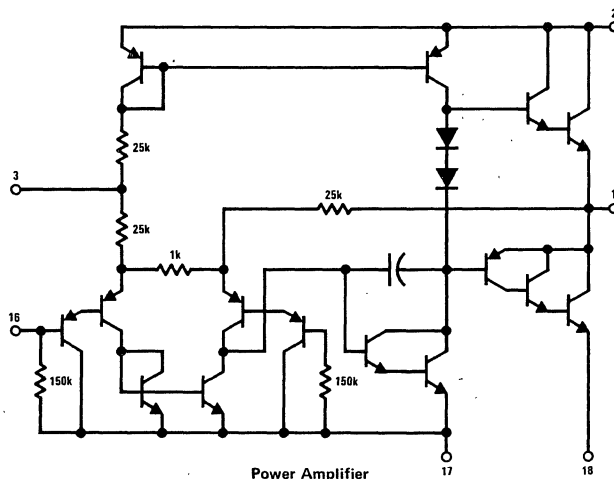
Lead Temperature (Soldering, 10 seconds)

300°C

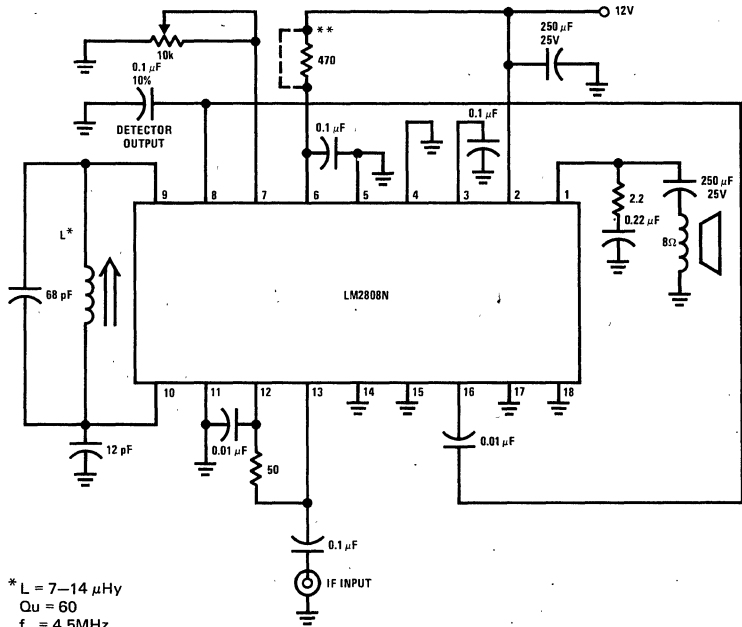
Electrical Characteristics (See test circuit)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|-----|------|-----|------------|
| P_o @ 10% THD LM2808 | $V_{CC} = 16V, R_L = 8\Omega$ | | 2.6 | | W |
| | $V_{CC} = 14V, R_L = 8\Omega$ | | 1.9 | | W |
| | $V_{CC} = 12V, R_L = 8\Omega$ | | 1.3 | | W |
| Feedthrough Signal (Pin 1) | $R_{Pin 7} = 0\Omega$ | | | 15 | mVrms |
| Current into Pin 6 | $V_{Pin 6} = 10V$ | 7 | 10.8 | 15 | mA |
| AM Rejection | $V_{IN} = 10$ mVrms, $\Delta f = 25$ kHz, AM = 30% | 40 | | | dB |
| Recovered Audio (Pin 8) | | 350 | 500 | | mVrms |
| Input Limiting Voltage at 4.5 MHz | | | 200 | 400 | μV |
| Audio Power Amp Voltage Gain (Pin 16 to Pin 1) | | 40 | | 60 | V/V |
| Output Noise, Input Signal Removed (Pin 1) | $R_{Pin 7} = 0\Omega$ | | 70 | 150 | mVrms |
| Distortion (Pin 8) | $\Delta F = 25$ kHz, $f_o = 4.5$ MHz | | 1.2 | 2 | % |
| Distortion (Pin 1) | | | | | |
| LM2808 | $P_o = 0.5W, R_L = 8\Omega$ | | 1.2 | 2 | % |
| Input Impedance (Pin 16) | | 50 | 200 | | k Ω |
| Current into Pin 2 (Zero Audio Output at Pin 1) | $V_2 = 24V$ | 2 | 5 | 20 | mA |

Schematic Diagrams (Continued)



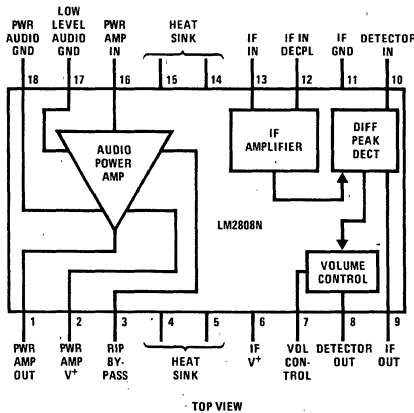
Typical Application and Test Circuit



Television Sound System

Connection Diagram

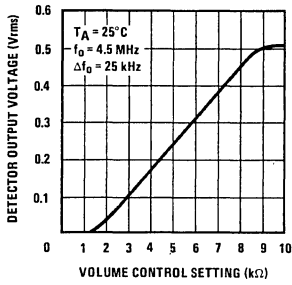
Dual-In-Line Package



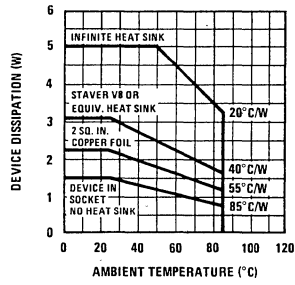
Order Number LM2808N
 See NS Package N18A

Typical Performance Characteristics

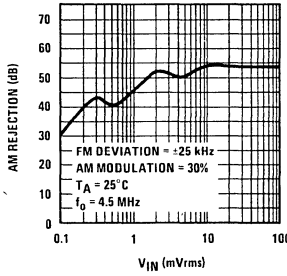
Volume Control Characteristic



Allowable Device Dissipation vs Ambient Temperature



AM Rejection vs Input Signal Level



LM3011 Wide Band Amplifier

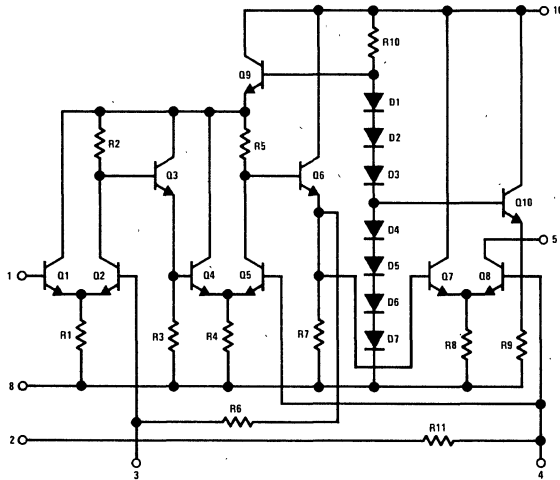
General Description

The LM3011 is a monolithic wide band amplifier circuit that requires a minimum of external components for operation. It includes three stages of limiting.

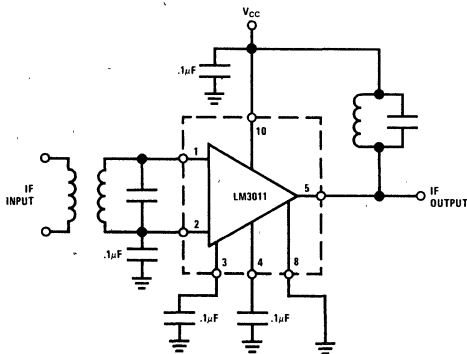
Features

- A direct replacement for CA3011
- High amplifier gain
- Excellent limiting characteristics
- Wide frequency capability

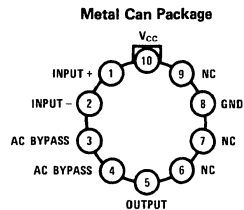
Schematic Diagram



Block Diagram



Connection Diagram



Order Number LM3011H
See NS Package H10C

Absolute Maximum Ratings

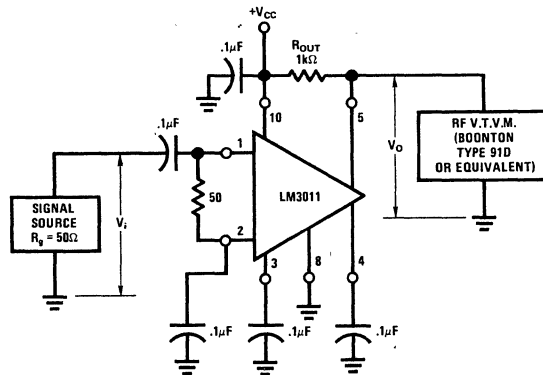
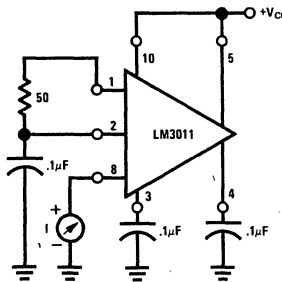
| | | | |
|----------------------------------|--------|--------------------------------------|-----------------|
| Supply Voltage | 15V | Operating Temperature Range | -55°C to +75°C |
| Input Signal (P _{in} 1) | ±3V | Storage Temperature Range | -65°C to +150°C |
| Power Dissipation (Note 1) | 715 mW | Lead Temperature (Soldering, 10 sec) | 300°C |

Electrical Characteristics (T_A = 25°C)

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|--|---|--------|------|-----|-------|
| | | MIN | TYP | MAX | |
| STATIC CHARACTERISTICS | | | | | |
| Total Device Dissipation (P _T) | V _{CC} = 6V (Figure 1) | 60 | 90 | 133 | mW |
| Total Device Dissipation (P _T) | V _{CC} = 7.5V (Figure 1) | 95 | 120 | 187 | mW |
| DYNAMIC CHARACTERISTICS V _{CC} = 7.5V, F = 4.5 MHz, unless otherwise noted | | | | | |
| Voltage Gain (A) | V _{CC} = 6V, f = 1 MHz (Figure 2) | 60 | 66 | | dB |
| Voltage Gain (A) | V _{CC} = 7.5V, f = 1 MHz (Figure 2) | 65 | 70 | | dB |
| Voltage Gain (A) | V _{CC} = 7.5V, f = 10.7 MHz (Figure 2) | 55 | 61 | | dB |
| Parallel Input Resistance (R _{IN}) | | | 3 | | kΩ |
| Parallel Input Capacitance (C _{IN}) | | | 7 | | pF |
| Parallel Output Resistance (R _{OUT}) | | | 31.5 | | kΩ |
| Parallel Output Capacitance (C _{OUT}) | | | 4.2 | | pF |
| Noise Figure (NF) | | | 8.7 | | dB |
| Input Limiting Voltage (V _{IN(LIM)}) | (-3 dB) (Figure 2) | | 300 | 400 | μV |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Test Circuits



LM3064 Television Automatic Fine Tuning

General Description

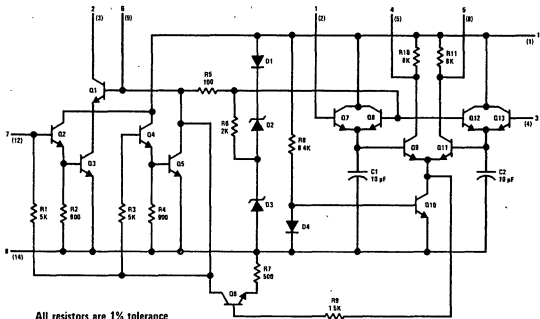
The LM3064 is a monolithic integrated circuit designed primarily for AFT (automatic fine tuning) applications. It includes a zener regulated power supply, IF amp, differential peak detector, and an AGC circuit.

The LM3064 is supplied in both the formed and straight lead 14-lead dual-in-line package.

Features

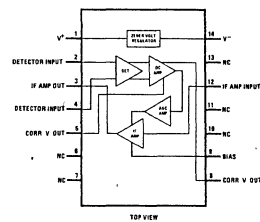
- Primarily intended for AFT applications
- High gain input amp (18 mV for rated output)
- Differential output correction voltage
- Wide operating temperature -40°C to +85°C
- Formed leads available for easy PC board design

Schematic and Connection Diagrams



All resistors are 1% tolerance and are in ohms.

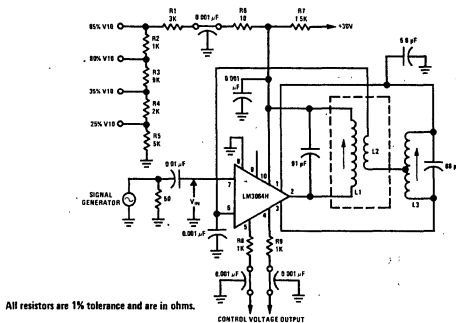
Dual-In-Line Package



Order Number LM3064N
See NS Package N14A

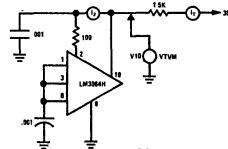
Order Number LM3064N-01
See NS Package N14C

Test Circuits



All resistors are 1% tolerance and are in ohms.

Test Circuit 1
Correction Voltage Test Circuit



DC parameter test circuit tests:
*Total device dissipation.
*Zener regulating voltage.
*Quiescent operating current.
*Quiescent current into pin 2.

Test Circuit 2
DC Parameter Test Circuit

Absolute Maximum Ratings

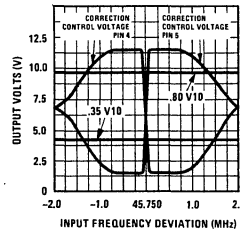
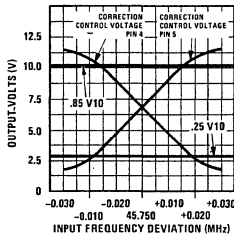
| | |
|-----------------------------|-----------------|
| Power Dissipation (Note 1) | 715 mW |
| Operating Temperature Range | -40°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Power Supply Current | 50 mA |

Electrical Characteristics (T_A = 25°C)

| PARAMETER | SYMBOL | TEST CIRCUIT | CONDITIONS | LIMITS | | UNITS | | | | | |
|--|--------------------------------|--------------|---|-----------------------------------|---|-------|---------------------|----------------|----|---------------------|----|
| | | | | MIN | MAX | | | | | | |
| STATIC | | | | | | | | | | | |
| Device Dissipation | P _T | 2 | V _{CC} = 30V; R _S = 1.5k | 130 | 150 | mW | | | | | |
| Current Drain | I _T | 2 | V _{I0} = 10.5V | 4.0 | 9.5 | mA | | | | | |
| Zener Regulating Voltage | V _{I0} | 2 | V _{CC} = 30V; R _S = 1.5k | 10.9 | 12.8 | V | | | | | |
| Quiescent Current into Pin 2 | I ₂ | 2 | V _{CC} = 30V; R _S = 1.5k | 1 | 4 | mA | | | | | |
| Quiescent Voltage at Pin 4 | V ₄ | 1 | V _{CC} = 30V; R _S = 1.5k | 5.0 | 8.0 | V | | | | | |
| Quiescent Voltage at Pin 5 | V ₅ | 1 | V _{CC} = 30V; R _S = 1.5k | 5.0 | 8.0 | V | | | | | |
| Output Offset Voltage between Pins 4 & 5 | V ₄ -V ₅ | 1 | V _{CC} = 30V; R _S = 1.5k | -1.0 | +1.0 | V | | | | | |
| DYNAMIC - Output Voltage vs Frequency Deviation AFT | | | | | | | | | | | |
| Correction Control Voltage at Pin 4 | V ₄ | 1 | V _{CC} = 30V; R _S = 1.5k V _i = 18 mV f = 45.75 - .03 MHz | Correction Voltage as Shown Below | | V | | | | | |
| | | | | % of V _{I0} | % of V _{I0} | | | | | | |
| | | | | 85 | 25 | | | | | | |
| | | | | f = 45.75 + .03 MHz | 80 | | 35 | | | | |
| | | | | | f = 45.75 - .9 MHz | | 80 | 80 | | | |
| | | | | | | | f = 45.75 + .9 MHz | 35 | 25 | | |
| | | | | | Correction Control Voltage at Pin 5 See Curves | | | V ₅ | 1 | f = 45.75 - 1.5 MHz | 80 |
| | | | | f = 45.75 + 1.5 MHz | | | 35 | | | | 80 |
| | | | | | | | f = 45.75 - .03 MHz | | | | 85 |
| | | | | f = 45.75 + .03 MHz | | | | | | | 80 |
| f = 45.75 - .9 MHz | 80 | 35 | | | | | | | | | |
| | f = 45.75 + .9 MHz | 35 | 80 | | | | | | | | |
| f = 45.75 - 1.5 MHz | | 35 | 80 | | | | | | | | |
| | f = 45.75 + 1.5 MHz | 35 | 80 | | | | | | | | |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Correction Control Voltage



Coil Winding Data

COIL DATA FOR DISCRIMINATOR WINDINGS

L₁ - Discriminator Primary: 3-1/6 turns; No. 20 Enamel-covered wire—close-wound, at bottom of coil form. Inductance of L₁ = 0.165 μH; Q₀ = 120 at f₀ = 45.75 MHz.

Start winding at Terminal No. 6; finish at Terminal No. 1. See Notes below.

L₂ - Tertiary Windings: 2-1/6 turns; No. 20 Enamel-covered wire—close-wound over bottom end of L₁. Start winding at Terminal No. 3; finish at Terminal No. 4. See Notes below.

L₃ - Discriminator Secondary: 3-1/2 turns; center-tapped, space wound at bottom of coil form. Inductance of L₃ = 0.180 μH; Q₀ = 150 at f₀ = 45.75 MHz.

Start winding at Terminal No. 2; finish at Terminal No. 5, connect center tap to Terminal No. 7. See Notes.

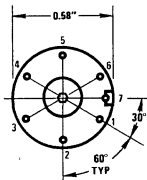
Note 1: Coil Forms; Cylindrical; -0.30" dia. max.

Note 2: Tuning Core: 0.250" dia. x 0.37" length.

Material: Carbinol J or equivalent.

Note 3: Coil Form Base: See drawing below.

Note 4: End of coil nearest terminal board to be designated the winding start end.



L₁ is aligned for symmetrical bandwidth on either side of 45.750 MHz.

L₂ tertiary winding wound on L₁ coil form.

L₃ is aligned for zero differential output between terminals 4 and 5 at f₀ = 45.750 MHz.

LM3075 FM Detector/Limiter and Audio Preamplifier

General Description

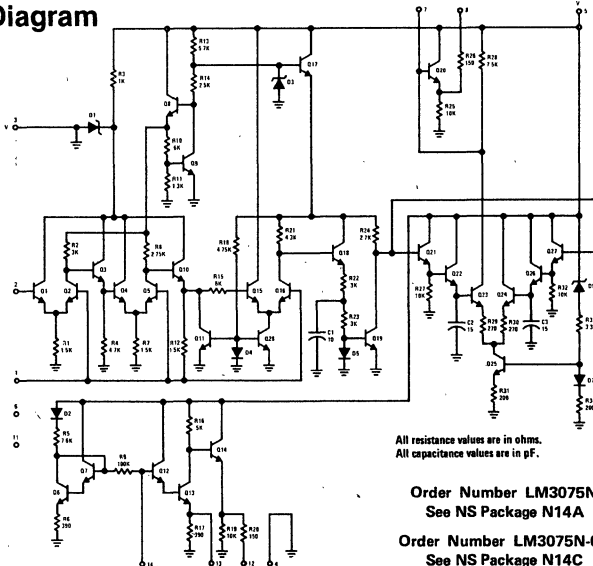
The LM3075 is a monolithic integrated circuit FM detector/limiter and audio preamplifier that requires a minimum of external components for operation. It includes three stages of IF limiting and a differential-peak-detection circuit.

- Simple detector alignment: one coil
- Sensitivity: 3 dB limiting voltage 250 μ V typical at 10.7 MHz
- Low harmonic distortion
- Excellent AM rejection 55 dB typ. at 10.7 MHz
- Internal audio preamplifier

Features

- A direct replacement for the CA3075

Schematic Diagram

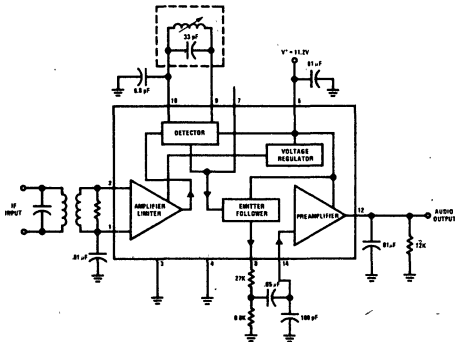


All resistance values are in ohms.
All capacitance values are in pF.

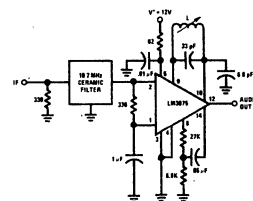
Order Number LM3075N
See NS Package N14A

Order Number LM3075N-01
See NS Package N14C

Block Diagram



Typical Application



Absolute Maximum Ratings

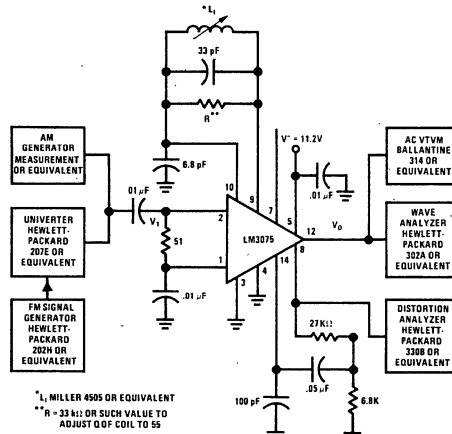
| | | | |
|------------------------------|--------|--|-----------------|
| Power Supply Current (Pin 5) | 30 mA | Operating Temperature Range | -40°C to +85°C |
| Supply Voltage (Pin 5) | 12.5V | Storage Temperature Range | -65°C to +150°C |
| Power Dissipation (Note 1) | 715 mW | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$

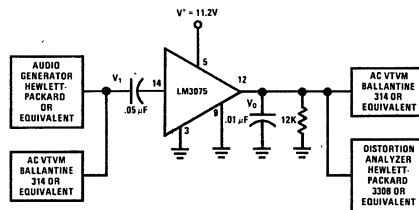
| PARAMETER | SYMBOL | TEST CIRCUIT | CONDITIONS | LIMITS | | | UNITS |
|--|---------------|--------------|--|--------|------------------|-----|----------------|
| | | | | MIN | TYP | MAX | |
| STATIC CHARACTERISTICS | | | | | | | |
| Supply Current | I_5 | | $V_{CC} = 8.5\text{V}$ $V_{CC} = 11.2\text{V}$ $V_{CC} = 12.5\text{V}$ | 8.5 | 15 17.5 19 | | mA mA mA |
| Detector Output Level (High) | V_7 | | | | 6.1 | | V |
| Detector Output Level (Low) | V_8 | | $V_{CC} = 11.2\text{V}$ | | 5.4 | | V |
| Audio Amplifier Output Level | V_{12} | | | | 5.2 | | V |
| DYNAMIC CHARACTERISTICS AT $V^+ = 11.2\text{V}$, $f_0 = 10.7\text{ MHz}$, $\Delta f = \pm 75\text{ kHz}$, $f_m = 400\text{ Hz}$ | | | | | | | |
| Input Limiting Threshold | $V_{IN(LIM)}$ | 1 | | | 250 | 600 | μV |
| AM Rejection | AMR | 1 | AM: 1 kHz @ 30% $V_{IN} = 100\text{ mV}$ | | 55 | | dB |
| Recovered AF Voltage (At Terminal 12) | $V_D (AF)$ | 1 | | | 1.5 | | V |
| Total Harmonic Distortion | T_{HD} | 1 | | | 1 | 2 | % |
| Audio Preamplifier Voltage Gain | $A_{V(AF)}$ | 2 | $V_{IN} = 100\text{ mV}$, $f = 400\text{ Hz}$ | | 21 | | dB |
| Total Harmonic Distortion | T_{HD} | 2 | $V_{OUT} = 2\text{V}$, $f = 400\text{ Hz}$ | | 1.5 | 5 | % |

Note 1: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Test Circuits



TEST CIRCUIT 1



TEST CIRCUIT 2

LM3089 FM Receiver IF System

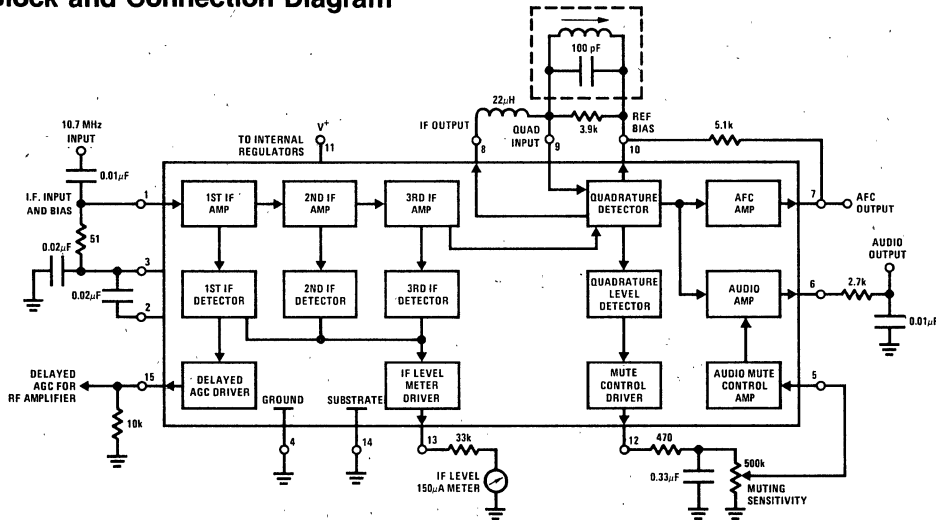
General Description

The LM3089 has been designed to provide all the major functions required for modern FM IF designs of automotive, high-fidelity and communications receivers.

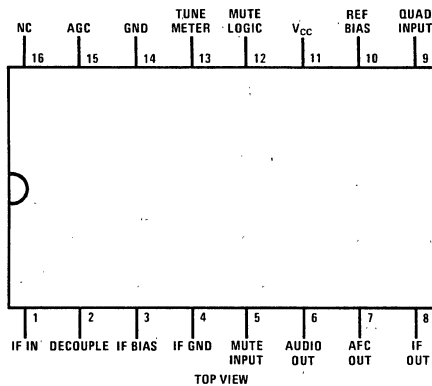
Features

- Three stage IF amplifier/limiter provides 12 μ V (typ) -3 dB limiting sensitivity
- Balanced product detector and audio amplifier provide 400 mV (typ) of recovered audio with distortion as low as 0.1% with proper external coil designs
- Four internal carrier level detectors provide delayed AGC signal to tuner, IF level meter drive current and interchannel mute control
- AFC amplifier provides AFC current for tuner and/or center tuning meters
- Improved operating and temperature performance, especially when using high Q quadrature coils in narrow band FM communications receivers
- No mute circuit latchup problems
- A direct replacement for CA3089E

Block and Connection Diagram



Dual-In-Line Package



Order Number LM3089N
See NS Package N16E

Absolute Maximum Ratings

| | | | |
|--|------|--|-----------------|
| Supply Voltage Between Pin 11 and Pins 4, 14 | +16V | Power Dissipation (Note 2) | 1390 mW |
| DC Current Out of Pin 12 | 5 mA | Operating Temperature Range | -40°C to +85°C |
| DC Current Out of Pin 13 | 5 mA | Storage Temperature Range | -65°C to +150°C |
| DC Current Out of Pin 15 | 2 mA | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (T_A = 25°C, V_{CC} = +12V, see Test Circuit)

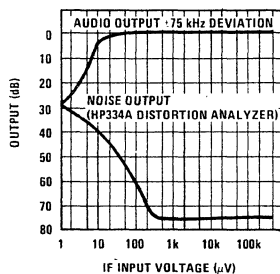
| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|--|-----|-----|-----|-------|
| DC CHARACTERISTICS (V_{IN} = 0, NOT MUTED) | | | | | | |
| I ₁₁ | Supply Current | | 16 | 23 | 30 | mA |
| V _{1, 2, 3} | IF Input and Bias | | 1.2 | 1.9 | 2.4 | V |
| V ₆ | Audio Output | | 5.0 | 5.6 | 6.0 | V |
| V ₇ | AFC Output | | 5.0 | 5.6 | 6.0 | V |
| V ₁₀ | Reference Bias | | 5.0 | 5.6 | 6.0 | V |
| V ₁₂ | Mute Control | | 5.0 | 5.4 | 6.0 | V |
| V ₁₃ | IF Level | | | 0 | 0.5 | V |
| V ₁₅ | Delayed AGC | | 4.2 | 4.7 | 5.3 | V |
| DYNAMIC CHARACTERISTICS f_o = 10.7 MHz, Δf = ±75 kHz @ 400 Hz | | | | | | |
| V _{IN} (LIM) | Input Limiting -3 dB | | | 12 | 25 | μV |
| AMR | AM Rejection | V _{IN} = 100 mV, AM: 30% | 45 | 55 | | -dB |
| V _O (AF) | Recovered Audio | V _{IN} = 10 mV | 300 | 400 | 500 | mVrms |
| THD | Total Harmonic Distortion Single Tuned (Note 1) | V _{IN} = 100 mV | | 0.5 | 1.0 | % |
| | | V _{IN} = 100 mV | | 0.1 | 0.3 | % |
| S+N/N | Signal to Noise Ratio | V _{IN} = 100 mV | 60 | 70 | | dB |
| V ₁₂ | Mute Control | V _{IN} = 100 mV | | 0 | 0.5 | V |
| V ₁₃ | IF Level | V _{IN} = 100 mV | 4.0 | 5.0 | 6.0 | V |
| V ₁₃ | IF Level | V _{IN} = 500 μV | 1.0 | 1.5 | 2.0 | V |
| V ₁₅ | Delayed AGC | V _{IN} = 100 mV | | 0.1 | 0.5 | V |
| V ₁₅ | Delayed AGC | V _{IN} = 30 mV | | 2.5 | | V |
| V _O (AF) | Audio Muted | V _{IN} = 100 mV, V ₅ = +2.5V | | 60 | | -dB |

Note 1: Distortion is a function of quadrature coil used.

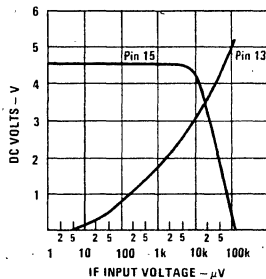
Note 2: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

Typical Performance Characteristics

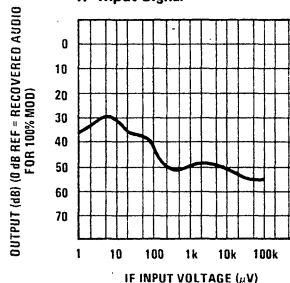
Typical S + N/N and IF Limiting Sensitivity vs IF Input Signal

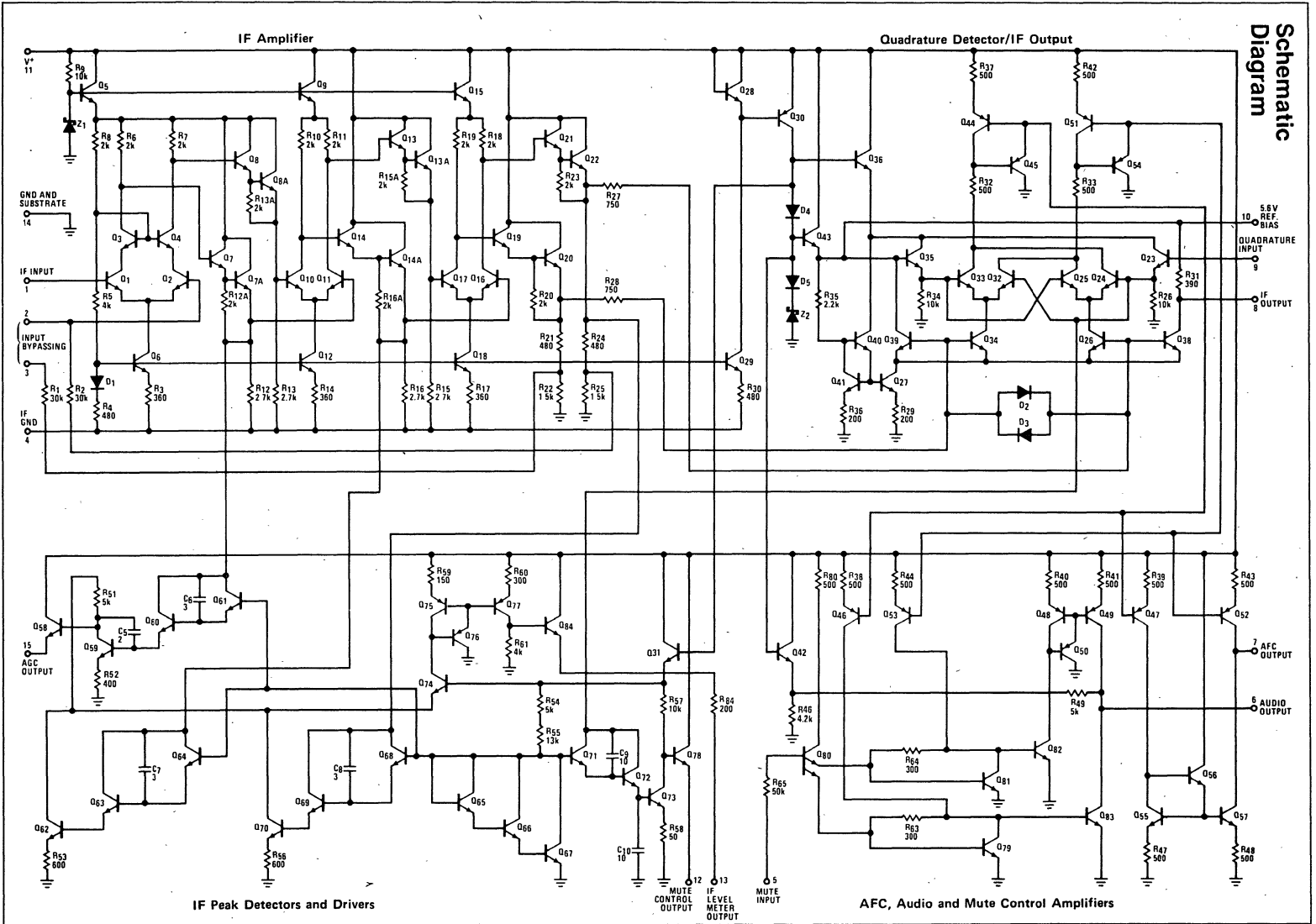


Typical AGC (Pin 15) and Meter Output (Pin 13) vs IF Input Signal



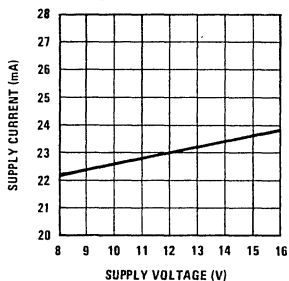
AM Rejection (30% Mod) vs IF Input Signal



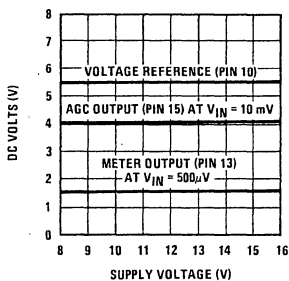


Typical Performance Characteristics (Continued)

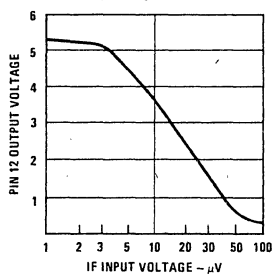
Supply Current (I₁₁) vs Supply Voltage (V₁₁)



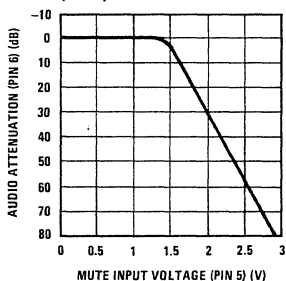
Reference Voltage, AGC and Meter Output vs Supply Voltage



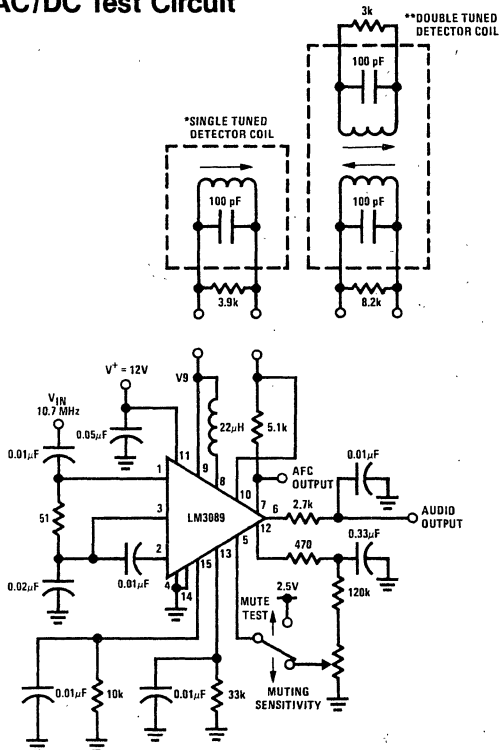
Mute Control Output (Pin 12) vs IF Input Signal



Typical Audio Attenuation (Pin 6) vs Mute Input Voltage (Pin 5)



AC/DC Test Circuit



*For single tuned detector coil:
 L_0 tunes with 100 pF at 10.7 MHz
 Q_{UL} (unloaded) ≈ 75
 Q_L (loaded) ≈ 13 for $V_9 \approx 150$ mVrms

**For double tuned detector coil:
 $Q_{ULPRI} = Q_{ULSEC} \approx 75$
 $kQ \approx 0.7$ for $V_9 \approx 150$ mVrms

Note:

The recovered audio output voltage will be approximately 0.5 dB less when using the double tuned detector coil.

For proper operation of the mute circuit, the RF voltage at pin 9 should be 150 mVrms ± 30 V.

LM3189 FM IF System

General Description

The LM3189 is a monolithic integrated circuit that provides all the functions of a comprehensive FM IF system. The block diagram of the LM3189 includes a three stage FM IF amplifier/limiter configuration with level detectors for each stage, a doubly balanced quadrature FM detector and an audio amplifier that features the optional use of a muting (squelch) circuit.

The advanced circuit design of the IF system includes desirable deluxe features such as programmable delayed AGC for the RF tuner, an AFC drive circuit, and an output signal to drive a tuning meter and/or provide stereo switching logic. In addition, internal power supply regulators maintain a nearly constant current drain over the voltage supply range of +8.5V to +16V.

The LM3189 is ideal for high fidelity operation. Distortion in an LM3189 FM IF system is primarily a function of the phase linearity characteristic of the outboard detector coil.

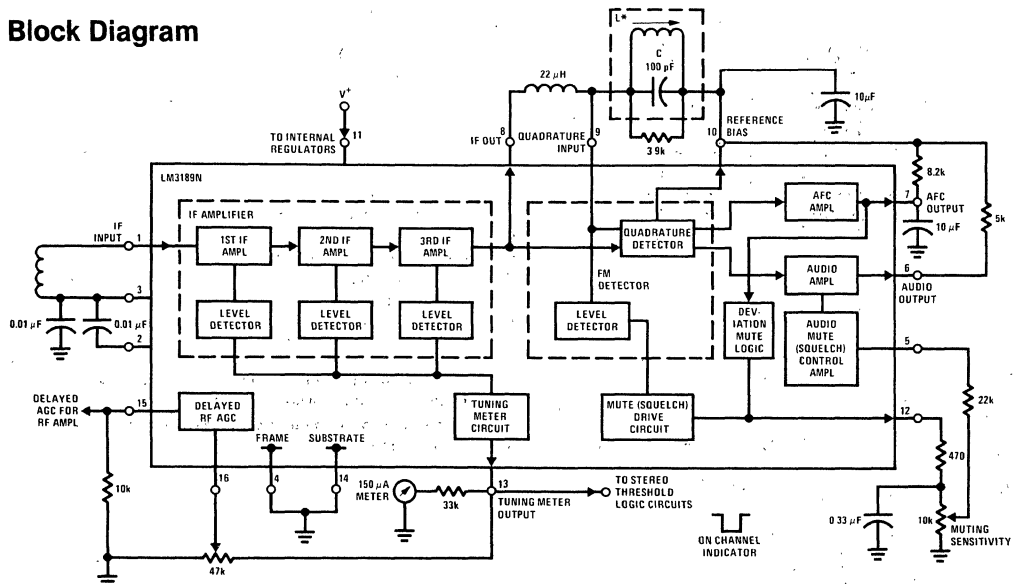
The LM3189 has all the features of the LM3039N plus additions.

The LM3189 utilizes the 16-lead dual-in-line plastic package and can operate over the ambient temperature range of -40°C to $+85^{\circ}\text{C}$.

Features

- Exceptional limiting sensitivity: $12\mu\text{V}$ typ at -3 dB point
- Low distortion: 0.1% typ (with double-tuned coil)
- Single-coil tuning capability
- Improved (S + N)/N ratio
- Externally programmable recovered audio level
- Provides specific signal for control of inter-channel muting (squelch)
- Provides specific signal for direct drive of a tuning meter
- On channel step for search control
- Provides programmable AGC voltage for RF amplifier
- Provides a specific circuit for flexible audio output
- Internal supply voltage regulators
- Externally programmable ON channel step width, and deviation at which muting occurs

Block Diagram



All resistance values are in ohms

* L tunes with 100 pF (C) at 10.7 MHz , $Q_0 \approx 75$
(Tokio No. KACS K586HM or equivalent)

Absolute Maximum Ratings

| | |
|--|-------------------|
| Supply Voltage Between Pin 11 and Pins 4, 14 | 16V |
| DC Current Out of Pin 12 | 5 mA |
| DC Current Out of Pin 13 | 5 mA |
| DC Current Out of Pin 15 | 2 mA |
| Power Dissipation (Note 2) | 1390 mW |
| Operating Temperature Range | -40 °C to +85 °C |
| Storage Temperature Range | -65 °C to +150 °C |
| Lead Temperature (Soldering, 10 seconds) | 300 °C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $V^+ = 12\text{V}$

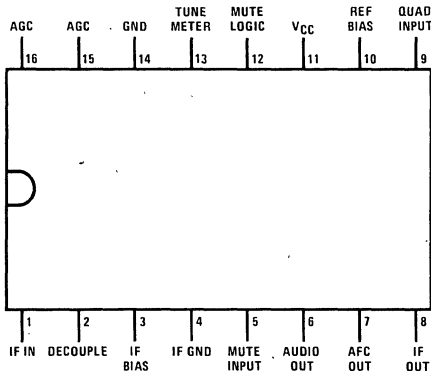
| Symbol | Parameter | Conditions (see single-tuned test circuit) | Min | Typ | Max | Units |
|------------------------------------|--|---|--|----------|-----|---------------|
| STATIC (DC) CHARACTERISTICS | | | | | | |
| I_{11} | Quiescent Circuit Current | No Signal Input, Non Muted | 20 | 31 | 44 | mA |
| V1 | DC Voltages: Terminal 1 (IF Input) | | 1.2 | 2.0 | 2.4 | V |
| V2 | Terminal 2 (AC Return to Input) | | 1.2 | 2.0 | 2.4 | V |
| V3 | Terminal 3 (DC Bias to Input) | | 1.2 | 2.0 | 2.4 | V |
| V15 | Terminal 15 (RF AGC) | | 7.5 | 9.5 | 11 | V |
| V10 | Terminal 10 (DC Reference) | | 5 | 5.75 | 6 | V |
| DYNAMIC CHARACTERISTICS | | | | | | |
| $V_i(\text{lim})$ | Input Limiting Voltage (-3 dB Point) | $V_{IN} = 0.1\text{V}$ | | 12 | 25 | μV |
| AMR | AM Rejection (Term. 6) | | 45 | 55 | | dB |
| $V_o(\text{AF})$ | Recovered AF Voltage (Term. 6) | AM Mod. = 30% | 325 | 500 | 650 | mV |
| THD | Total Harmonic Distortion (Note 1) Single Tuned (Term. 6) Double Tuned (Term. 6) | $V_{IN} = 0.1\text{V}$ | $f_o = 10.7\text{ MHz}$, $f_{\text{mod}} = 400\text{ Hz}$, Deviation $\pm 75\text{ kHz}$ | 0.5 | 1 | % |
| S + N/N | Signal plus Noise to Noise Ratio (Term. 6) | | | 65 | 80 | |
| f_{DEV} | Deviation Mute Frequency | | $f_{\text{mod}} = 0$ | ± 40 | | kHz |
| V16 | RF AGC Threshold | | | 1.25 | | V |
| V12 | On Channel Step | $V_{IN} = 0.1\text{V}$ | $f_{\text{DEV}} < \pm 40\text{ kHz}$ $f_{\text{DEV}} > \pm 40\text{ kHz}$ | 0 5.6 | | V |

Note 1: THD characteristics are essentially a function of the phase characteristics of the network connected between terminals 8, 9, and 10.

Note 2: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 90°C/W junction to ambient.

Connection Diagram

Dual-In-Line Package



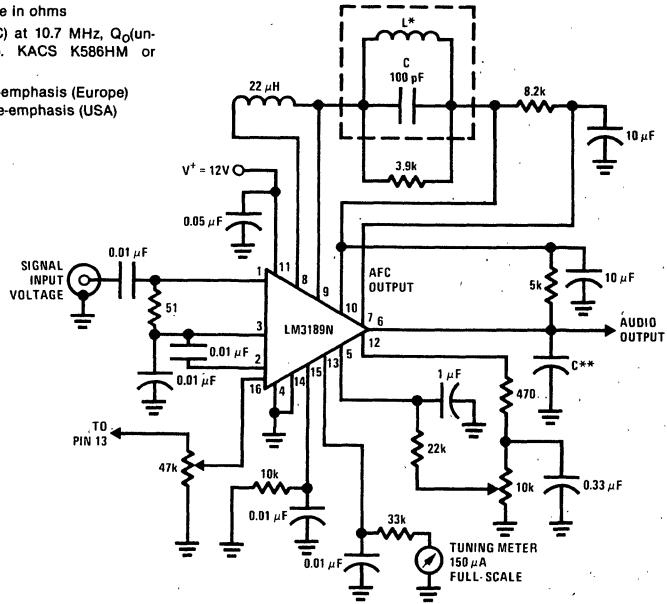
Order Number LM3189N
See NS Package N16A

TOP VIEW

Test Circuits

Test Circuit for LM3189N Using a Single-Tuned Detector Coil

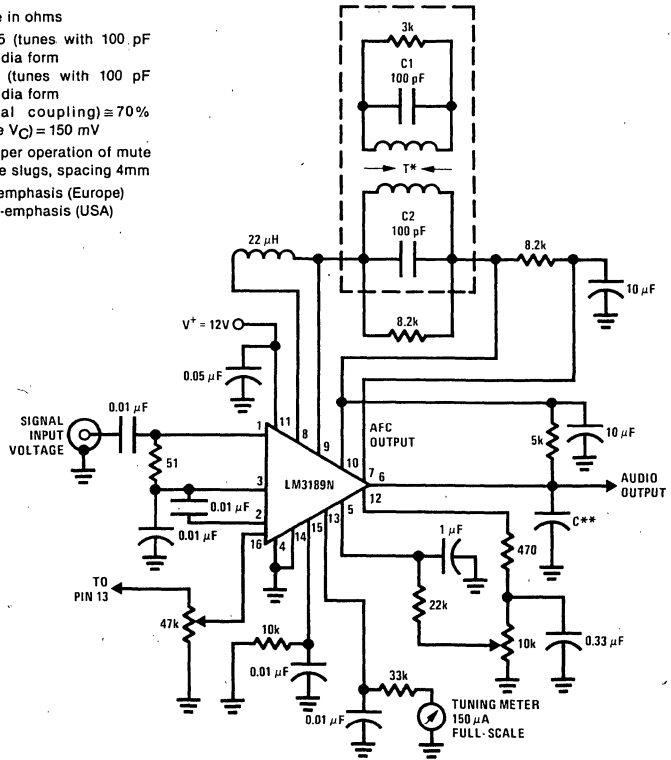
- All resistance values are in ohms
- * L tunes with 100 pF (C) at 10.7 MHz, Q_0 (unloaded) \cong 75 (Toko No. KACS K586HM or equivalent)
 - ** C = 0.01 μ F for 50 μ s de-emphasis (Europe)
= 0.015 μ F for 75 μ s de-emphasis (USA)



Test Circuits (Continued)

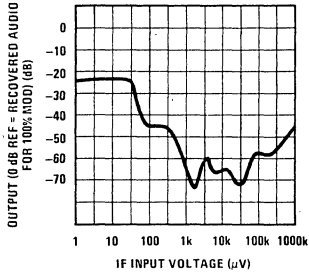
Test Circuit for LM3189N Using a Double-Tuned Detector Coil

- All resistance values are in ohms
- * T:PRI— Q_0 (unloaded) $\cong 75$ (tunes with 100 pF (C1) 20t of 34e on 7/32" dia form
 - SEC— Q_0 (unloaded) $\cong 75$ (tunes with 100 pF (C2) 20t of 34e on 7/32" dia form
 - kQ(percent of critical coupling) $\cong 70\%$ (adjusted for coil voltage V_C) = 150 mV
- Above values permit proper operation of mute (squetch) circuit "E" type slugs, spacing 4mm
- ** C = 0.01 μ F for 50 μ s de-emphasis (Europe)
 - = 0.015 μ F for 75 μ s de-emphasis (USA)

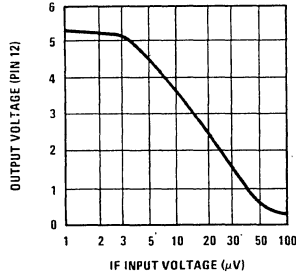


Typical Performance Characteristics

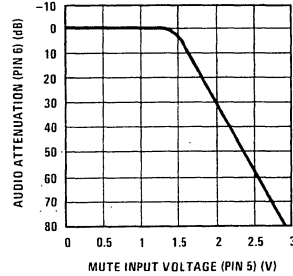
AM Rejection (30% Mod) vs IF Input Signal



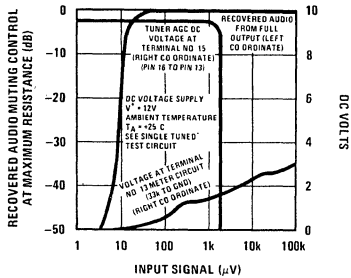
Mute Control Output (Pin 12) vs IF Input Signal



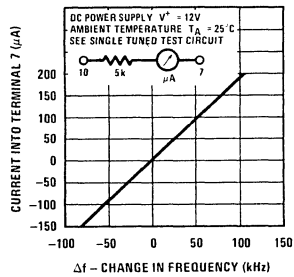
Typical Audio Attenuation (Pin 6) vs Mute Input Voltage (Pin 5)



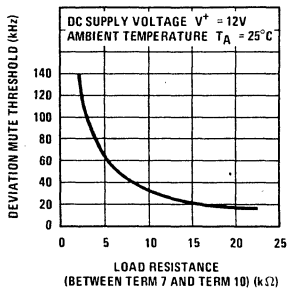
Muting Action, Tuner AGC, and Tuning Meter Output as a Function of Input Signal Voltage



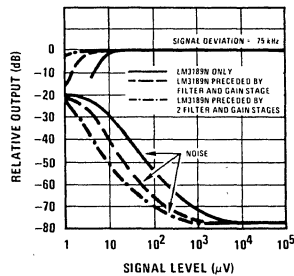
AFC Characteristics (Current at Term 7 as a Function of Change in Frequency)



Deviation Mute Threshold as a Function of Load Resistance (Between Term 7 and Term 10)



Typical Limiting and Noise Characteristics



LM3820 AM Radio System

General Description

The LM3820 is a 3-stage AM radio IC consisting of an RF amplifier, oscillator, mixer, IF amplifier, AGC detector, and zener regulator.

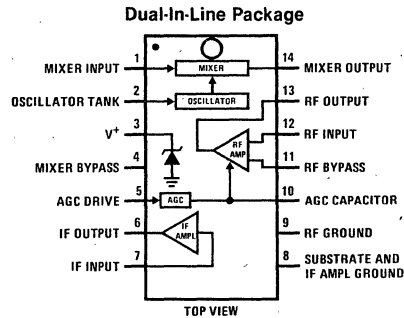
The device was originally designed for use in slug-tuned auto radio applications, but is also suitable for capacitor-tuned portable radios.

The LM3820 is an improved replacement for the LM1820.

Features

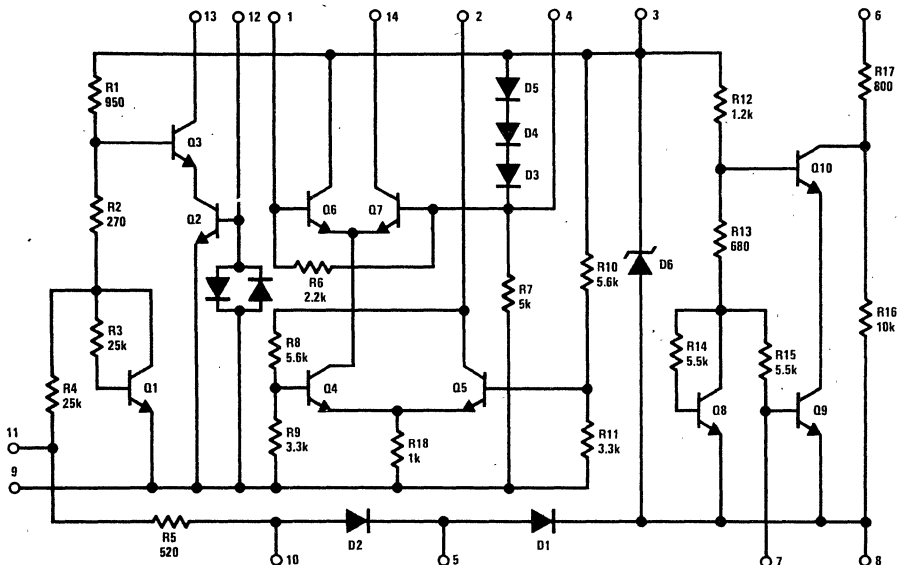
- Input protection diodes
- Good control on sensitivity
- Improved S/N and tweet
- Versatile building-block approach
- Gain-controlled RF stage
- Cascode IF amplifier
- Regulated supply
- Pin compatible with LM1820

Connection Diagram



Order Number LM3820N
See NS Package N14A

Circuit Schematic



Absolute Maximum Ratings

| | | | |
|--------------------------------------|--------|--|----------------|
| Power Dissipation (Note 1) | 700 mW | Operating Temperature Range | -25°C to 85°C |
| Supply Voltage | 16V | Storage Temperature Range | -65°C to 150°C |
| Current into Supply Terminal (Pin 3) | 35 mA | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (Figure 1, T_A = 25°C, V_S = 6V unless noted)

| Parameter | Conditions | Min | Typ | Max | Units |
|--|---|-----|-----|-----|-------|
| Supply Current (I _S) | No RF Input | 12 | 18 | 24 | mA |
| Internal Zener Voltage (V _Z) | | 7.0 | 7.5 | 8.0 | V |
| Input Sensitivity | f = 1 MHz, 30% Mod 400 Hz Measure RF Input Level for 10 mV Audio Output with Tuning Peaked | 15 | 35 | 70 | μV |
| Signal to Noise Ratio | f = 1 MHz, 30% Mod 1 kHz (S + N)/N at Audio Output with 100 μV RF Input | 22 | 28 | — | dB |
| Overload Distortion | f = 1 MHz, 90% Mod 1 kHz THD at Audio Output with 30 mV RF Input | — | 6 | 10 | % |

Note 1: Above T_A = 25°C, derate based on T_{J(MAX)} = 150°C and θ_{JA} = 180°C/W

Typical Applications

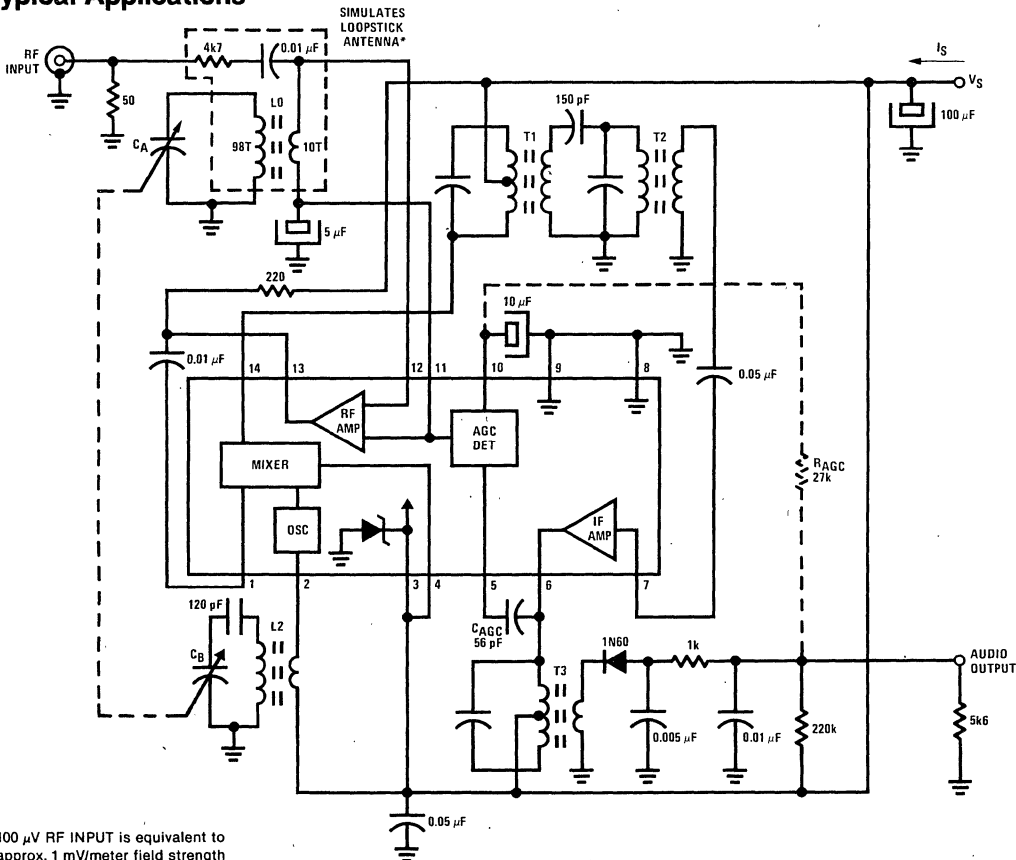


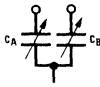
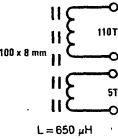
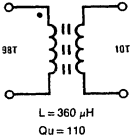
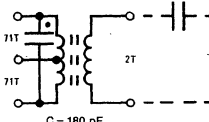
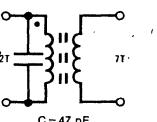
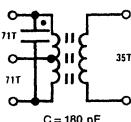
FIGURE 1. Capacitor-Tuned Test Fixture

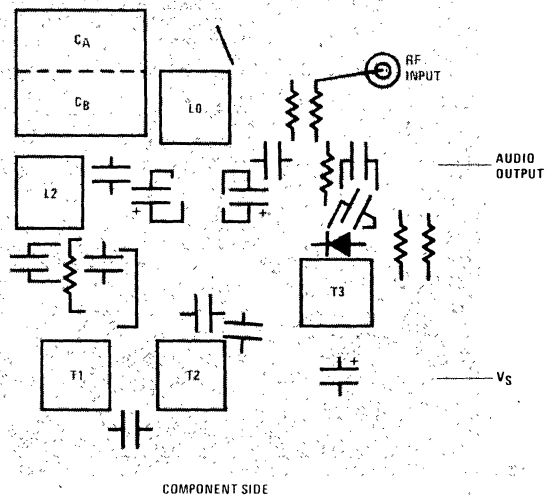
Applications Information

The circuit shown in *Figure 1* is recommended as a starting point for portable radio designs. Loopstick antenna L1 is used in place of L0, and the RF amplifier is used with a resistor load to drive the mixer. A double tuned circuit at the output of the mixer provides selectivity, while the remainder of the gain is provided by the IF section, which is matched to the diode through a unity turns ratio transformer. R_{AGC} may be used in place of C_{AGC} to bypass the internal AGC detector and provide more recovered audio.

An AM automobile radio design is shown in *Figure 2*. Tuning of both the input and the output of the RF amplifier and the mixer is accomplished with variable inductors. Better selectivity is obtained through the use of double tuned interstage transformers. Input circuits are inductively tuned to prevent microphonics and provide a linear tuning motion to facilitate push-button operation.

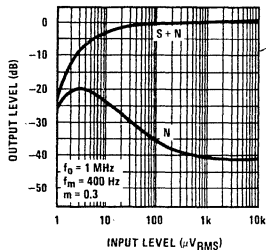
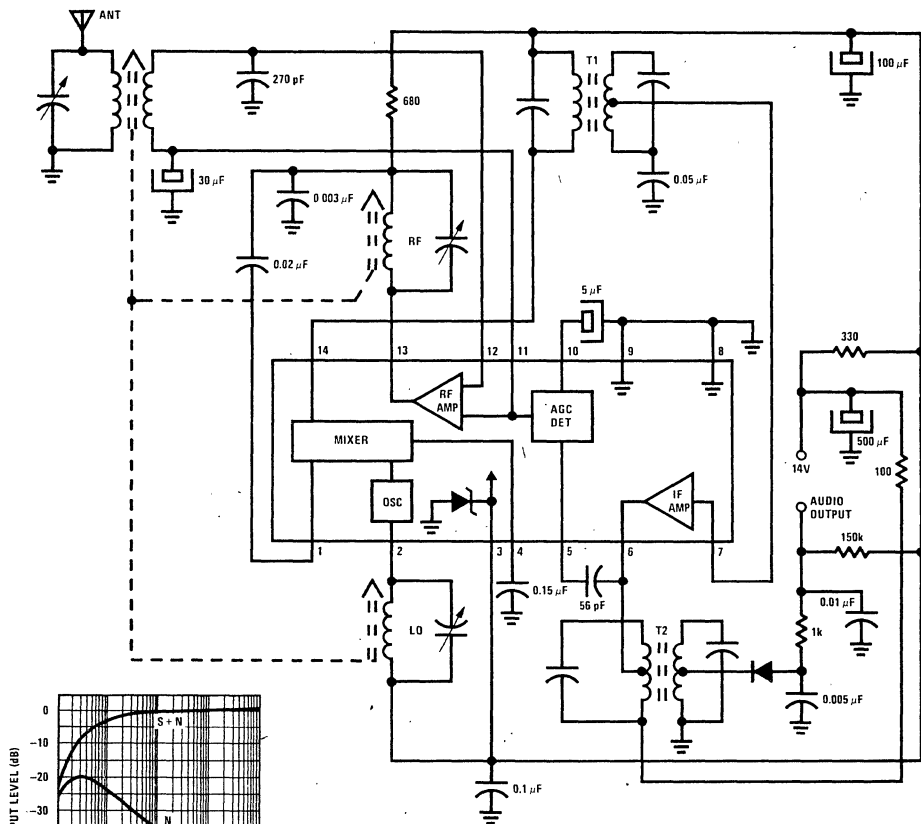
Coil specifications for *Figure 1* are as follows:

| VC | AM PVC | L1 | AM ANT 525 kHz-1650 kHz | L0, L2 | AM OSC 980 kHz-2105 kHz |
|----|---|----|---|--------|---|
| |  | |  | |  |
| | $C_A = 140 \text{ pF}$ $C_B = 60 \text{ pF}$ | | $L = 650 \text{ } \mu\text{H}$ $Q_u = 250$ | | $L = 360 \text{ } \mu\text{H}$ $Q_u = 110$ |
| T1 | AM 1st IF 455 kHz | T2 | AM 2nd IF 455 kHz | T3 | AM 3rd IF 455 kHz |
| |  | |  | |  |
| | $C = 180 \text{ pF}$ $Q_u = 140$ | | $C = 47 \text{ pF}$ $Q_u = 120$ | | $C = 180 \text{ pF}$ $Q_u = 140$ |



PCB Layout for *Figure 1* Circuit

Typical Applications (Continued)



TRANSFORMERS

T1: C = 130 pF primary & secondary
 primary to secondary tap ratio—30:1
 Q = 60
 coupling—critical

T2: C = 130 pF primary & secondary
 primary tap ratio—8.5:1
 secondary tap ratio—8.5:1
 Q = 60
 coupling—critical

FIGURE 2. Slug-Tuned Auto Radio

LM4500A High Fidelity FM Stereo Blend Demodulator

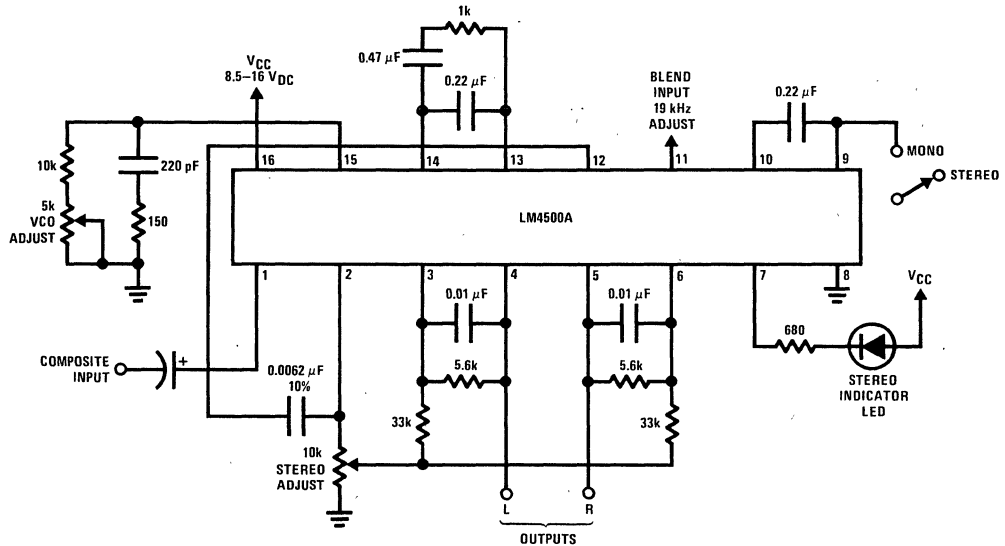
General Description

The LM4500A provides low distortion and high FM stereo channel separation required in high fidelity stereo receivers. A phase locked loop technique is implemented in order to reject subcarrier harmonics and to remove all inductive components from the final system. The circuit can provide overall gain and prevents stereo to mono switching transients. An external voltage input is available for voltage controlled blend.

Features

- Low distortion 0.1% typ
- High separation over the entire audio spectrum
- Adjustable gain
- High power supply rejection 45 dB typ
- Transient-free, automatic stereo/mono switching
- Requires no inductors
- Low output impedance
- Large input dynamic range 2.5 Vp-p
- High subcarrier harmonic rejection
- Voltage controlled blend

Block Diagram



Order Number LM4500AN
See NS Package N16A

TBA120S IF Amplifier and Detector

General Description

The TBA120S is a monolithic integrated circuit specifically designed for audio detection in TV and FM radio receivers. It incorporates an 8-stage limiting IF amplifier and balanced detector plus a dc operated volume control.

The TBA120S is supplied in four groups depending on the resistance required between pin 5 and ground to attenuate the audio output by 30 dB. The group number as defined below is marked on the package.

Features

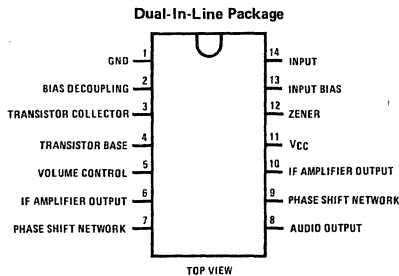
- Electronic attenuator: replaces conventional ac volume control
- Volume reduction range 85 dB typ
- Sensitivity: 3 dB limiting voltage $30\mu\text{V}$ typ
- Excellent AM rejection 68 dB typ at 10 mV
- Audio output voltage 1V typ
- Wide supply voltage range (6-18V)
- Internal zener diode regulator
- Very low external component requirement
- Simple detector alignment: one coil

| GROUP | II | III | IV | V | |
|--------|---------|---------|---------|---------|------------|
| R5-Gnd | 1.9-2.2 | 2.1-2.5 | 2.4-2.9 | 2.8-3.3 | k Ω |

Pins 3 and 4 are connected to the collector and base of a transistor which may be used as an AF-preamplifier or as a switch.

At pin 12 a zener-diode is accessible which can be used to stabilize the supply voltage of this integrated circuit or the voltage of other circuit elements in the set.

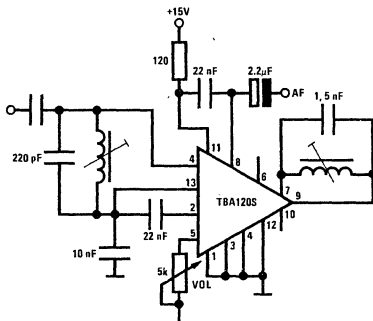
Connection Diagram



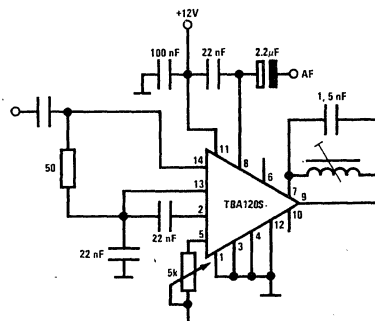
Order Number TBA120S II, TBA120S III,
TBA120S IV or TBA120S V
See NS Package N14A

Order Number TBA120SQ II, TBA120SQ III,
TBA120SQ IV, TBA120SQ V
See NS Package N14C

Typical Application (5.5 MHz)



Test Circuit (5.5 MHz)



Absolute Maximum Ratings

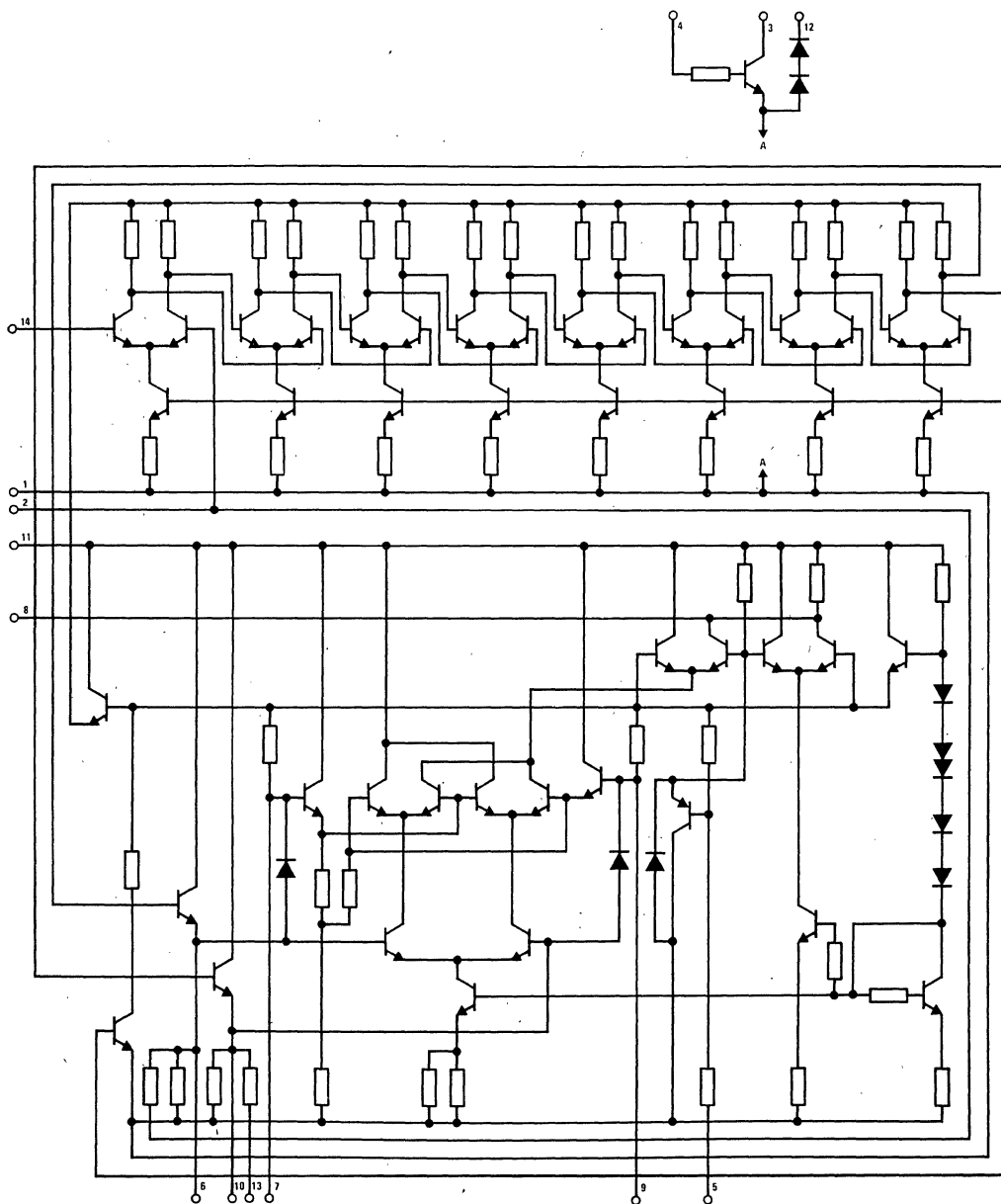
| | | | |
|--|-------|---|-----------------|
| Supply Voltage, V11 | 18V | Transistor Base Current, I ₄ | 2 mA |
| Volume Control Voltage, V5 | 4V | Bias Resistance (Max), R13-14 | 1 kΩ |
| Zener Current, I ₁₂ | 20 mA | Operating Temperature Range | -15°C to +70°C |
| Transistor Collector Current, I ₃ | 5 mA | Storage Temperature Range | -65°C to +150°C |

Electrical Characteristics (V_{CC} = 12V, T_A = 25°C)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|-----------------------------------|---|--|------|--------|-------|-------|
| I _{CC} | Supply Current | R5 = ∞ | 10 | 14 | 18 | mA |
| | | R5 = 0 | 11 | | 20 | mA |
| G _V | IF Voltage Gain | f = 5.5 MHz | | 68 | | dB |
| V _O | IF Output Voltage, Each Output, at Limiting | | 170 | 250 | | mVp-p |
| V _{af} | AF Output Voltage | f = 5.5 MHz, Δf = ±50 kHz, f _{MOD} = 1 kHz, V _I = 10 mV, Q = 45 | 0.7 | 1.0 | | V |
| | Distortion (5.5 MHz) | f = 5.5 MHz, Δf = 25 kHz, f _{MOD} = 1 kHz, V _I = 10 mV, Q = 45 | | 1.5 | | % |
| | Distortion (10.7 MHz) | f = 10.7 MHz, Δf = ±50 kHz, f _{MOD} = 1 kHz, V _I = 10 mV, Q = 20 | | 0.2 | | % |
| V _{LIM} | Input Voltage Before Limiting | f = 5.5 MHz, Δf = ±50 kHz, f _{MOD} = 1 kHz, Q = 45 | | 30 | 60 | μV |
| Z _I | Input Impedance | f = 5.5 MHz | 15/6 | 40/4.5 | | kΩ/pF |
| R _O | Output Resistance | | 1.9 | 2.6 | 3.3 | kΩ |
| $\frac{V_{af\ max}}{V_{af\ min}}$ | Volume Control Range | | 70 | 85 | | dB |
| V ₈ | DC Component of the Output Signal | V _I = 0 | 6.2 | 7.3 | 8.4 | V |
| a _{AM} | AM Rejection | f = 5.5 MHz, Δf = ±50 kHz, f _{MOD} = 1 kHz, V _I = 500μV, m = 30% | 50 | 60 | | dB |
| a _{AM} | AM Rejection | f = 5.5 MHz, Δf = ±50 kHz, f _{MOD} = 1 kHz, V _I = 10 mV, m = 30% | | 68 | | dB |
| R5 | Potentiometer Resistance | 1 dB Attenuation | | 3.7 | 4.7 | kΩ |
| V5 | Voltage | 1 dB Attenuation | | 2.2 | 2.5 | V |
| R5 | Potentiometer Resistance | 70 dB Attenuation | 1.0 | 1.4 | | kΩ |
| V5 | Voltage | 70 dB Attenuation | | 1.2 | | V |
| | Noise Voltage at Output | V _I = 10 mV | | 30 | | μV |
| V ₁₂ | Zener Voltage | I ₁₂ = 5 mA | 11.2 | 12 | 13.4 | V |
| R _Z | Zener Slope Resistance | | | 30 | 50 | Ω |
| V _{cbo} | Breakdown Voltage | | 45 | 65 | | V |
| V _{ceo} | Breakdown Voltage | I ₃ = 500μA | 18 | 24 | | V |
| h _{fe} | Current Gain | I ₃ = 1 mA | 50 | 100 | 500 | |

Schematic Diagram

TBA120S



10



TBA120U, TBA120T IF Amplifier and Detector

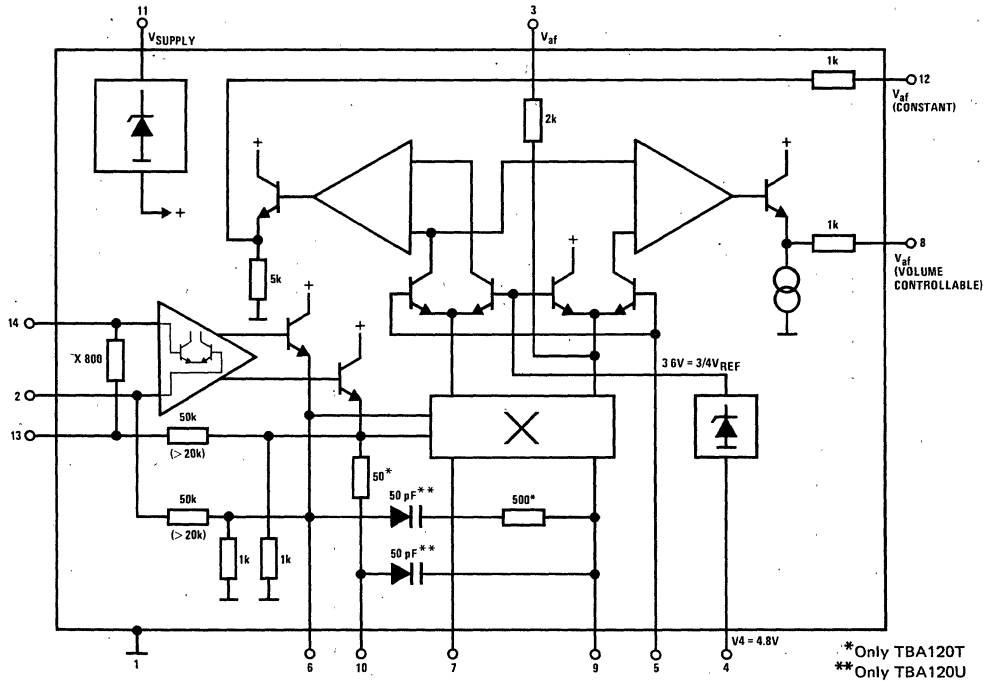
General Description

The TBA120U, TBA120T is a monolithic integrated circuit specifically designed for audio detection in TV and FM radio receivers. It incorporates an 8 stage limiting IF amplifier and balanced detector plus a DC operated volume control. The circuit also provides connection facilities for a video tape recorder. The TBA120T is designed primarily for use with ceramic filters while the TBA120U is optimized for inductive tuning.

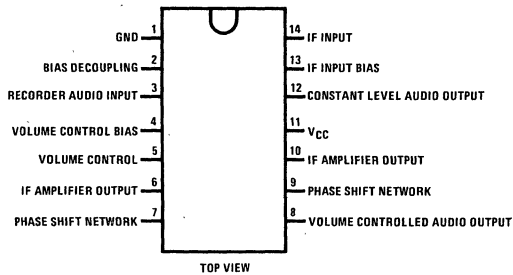
Features

- Electronic attenuator: replaces conventional AC volume control
- Volume reduction range: 85 dB typ
- Sensitivity: 3 dB limiting voltage 30 μ V typ
- Excellent AM rejection 68 dB typ 500 μ V
- Wide supply voltage range (6 to 18V)
- Easy video recorder connection
- Very low external component requirement
- Simple detector alignment: one coil

Block and Connection Diagrams



Dual-In-Line Package



Order Number TBA120U or TBA120T
See NS Package N14A

Order Number TBA120TQ or TBA120UQ
See NS Package N14C

Absolute Maximum Ratings

| | | | |
|---|-----------------|-------------------------------------|-------------|
| Supply Voltage, V ₁₁ | 18V | Current Pin 4, I ₄ | 5 mA |
| Operating Temperature Range, T _U | -15°C to +70°C | Operating Frequency Range, f | 0 to 12 MHz |
| Storage Temperature Range, T _S | -40°C to +125°C | Power Dissipation, P _{tot} | 400 mW |
| Voltage Pin 5, V ₅ | 6V | Resistor Parallel to Pins 13 and 14 | 1 kΩ |

Electrical Characteristics (V_{CC} = 12V, T_A = 25°C)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|-----------------------------------|--|---|------|------|-------------------|----|
| I _{CC} | Supply Current | 9.5 | 13.5 | 17.5 | mA | |
| G _V | IF Voltage Gain | f = 5.5 MHz | 68 | | dB | |
| V _O | IF Output Voltage (Each Output Limiting) | | 250 | | mV _{p-p} | |
| R ₈ | Output Impedance | | 1.1 | | kΩ | |
| R ₁₂ | | | 1.1 | | kΩ | |
| R ₃ | Input Impedance | | 2 | | kΩ | |
| R ₄ | Regulator Impedance | | 12 | | Ω | |
| V ₈ | DC Output Level | V _i = 0 | 4 | | V | |
| V ₁₂ | | V _i = 0 | 5.6 | | V | |
| V ₄ | Regulator Voltage | 4.2 | 4.8 | 5.3 | V | |
| $\frac{V_{af\ max}}{V_{af\ min}}$ | Volume Control | 70 | 85 | | dB | |
| $\frac{V_{af8}}{V_{af3}}$ | Video Recorder Output Ratio | | 7.5 | | | |
| V _{LIM} | Sensitivity | V _{af} - 3 dB, f = 5.5 MHz | 30 | 60 | μV | |
| $\frac{V_8}{V_{11}}$ | Supply Rejection | | 35 | | dB | |
| $\frac{V_{12}}{V_{11}}$ | | | 30 | | dB | |
| R _{4-R5} | Impedance | 1 | | 10 | kΩ | |
| $\frac{V_{af\ max}}{V_{af8}}$ | Output Ratio | R _{4-R5} = 5 kΩ R _{5-R1} = 13 kΩ | 20 | 28 | 36 | dB |

TBA120T Only

| | | | | | | |
|-------------------|---------------------|---|----|-------|--|------|
| Z _i | Input Impedance | f = 5.5 MHz | | 800/5 | | Ω/pF |
| a _{AM} | AM Rejection | f = 5.5 MHz m = 30% Δf = ±50 kHz V _i = 500 μV f _{MOD} = 1 kHz | 50 | 60 | | dB |
| V _{af8} | A.F. Output Voltage | f = 5.5 MHz f _{MOD} = 1 kHz | | 900 | | mV |
| V _{af12} | | Δf = ±50 kHz | | 650 | | mV |

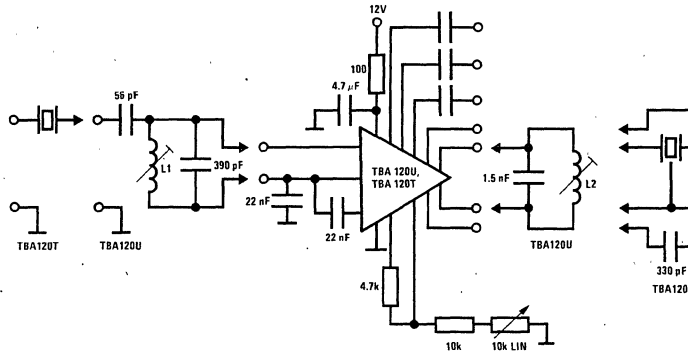
TBA120U Only

| | | | | | | |
|-----------------|-----------------|---|------|--------|--|-------|
| Z _i | Input Impedance | f = 5.5 MHz | 15/6 | 40/4.5 | | kΩ/pF |
| a _{AM} | AM Rejection | f = 5.5 MHz V _i = 500 μV f _{MOD} = 1 kHz Δf = ±50 kHz m = 30% | 50 | 60 | | dB |

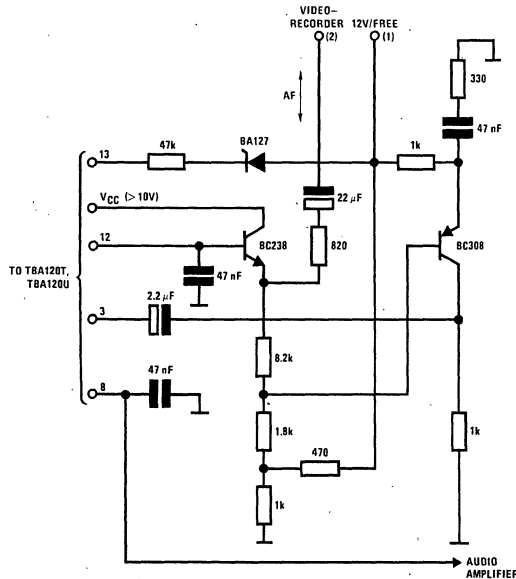
Electrical Characteristics (Continued) ($V_{CC} = 12V, T_A = 25^\circ C$)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|-----------------------------------|---|----------|-----|--------|
| TBA120U Only (Continued) | | | | | |
| Vaf8 | A.F. Output Voltage | f = 5.5 MHz f _{MOD} = 1 kHz $\Delta f = \pm 50$ kHz V _i = 10 mV Q _B = 45 | 1.3 | | V |
| Vaf12 k | A.F. Output Voltage Distortion | f = 5.5 MHz $\Delta f = \pm 50$ kHz f _{MOD} = 1 kHz Q _B = 45 V _i = 10 mV | 1.0 1 | | V % |

Typical Application (5.5 MHz)

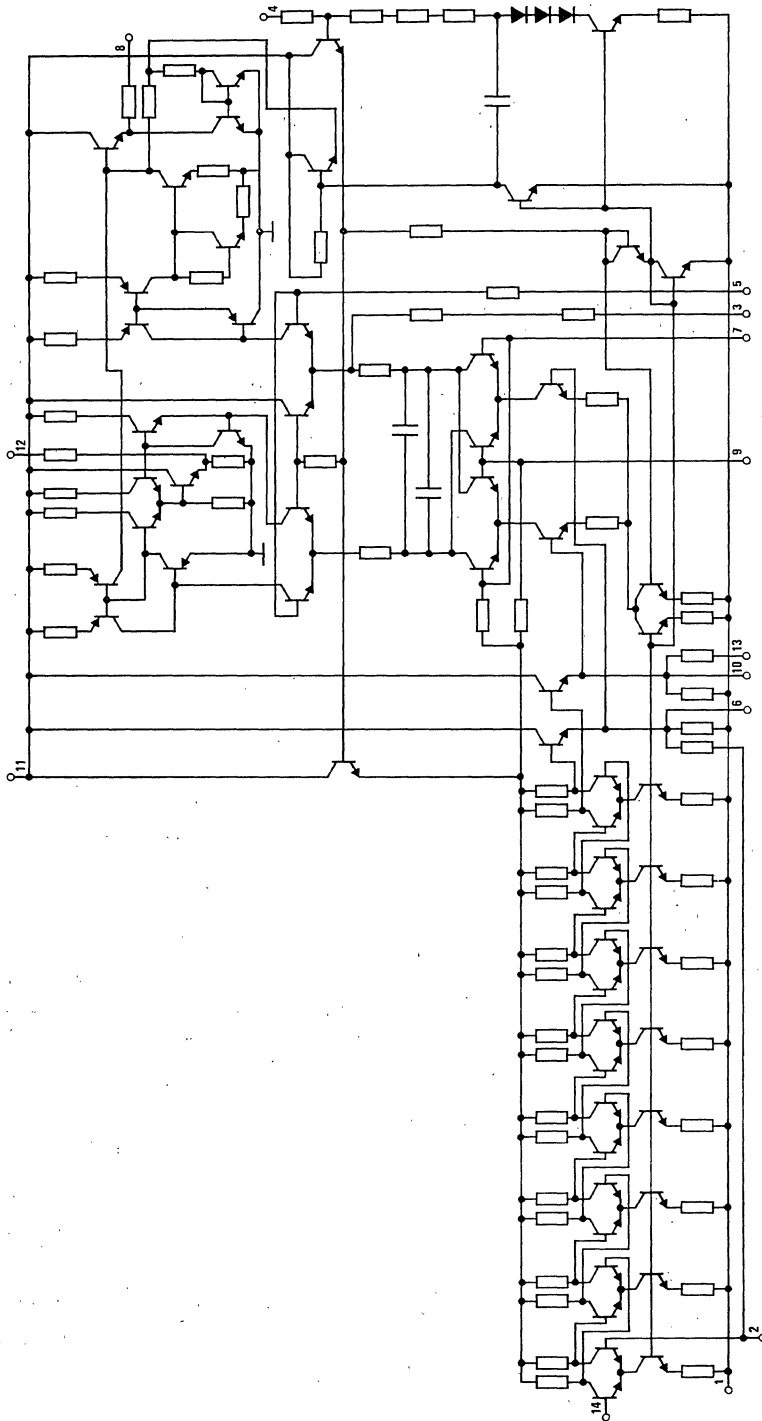


Circuit for Direct Connection to Video Recorders



Socket 1: Switching voltage: on playback
12V on record open circuit.
Socket 2: Video recorder input/output.

Schematic Diagram TBA120U



TBA120U, TBA120T

TBA440C Monolithic Video IF Amplifier

General Description

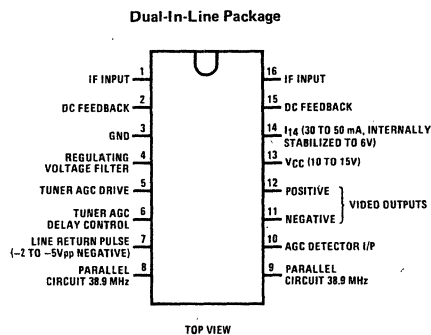
The TBA440C is a monolithic video IF amplifier for color and monochrome television receivers.

The circuit includes three IF amplifier stages, a balanced video IF detector and a gated AGC section for the IF amplifier and PNP tuner.

Features

- High gain—high stability
- Minimal noise increase, incurred by use of AGC
- Minimum RF breakthrough to video outputs
- Fast AGC action—gating largely independent of pulse shape and amplitude
- Very low intermodulation products
- Positive and negative video signals are available from low impedance outputs
- Integrated temperature compensating circuit

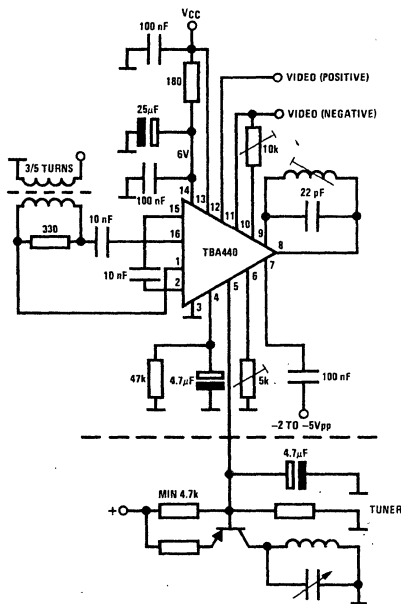
Connection Diagram



Order Number TBA440C
See NS Package N16A

Order Number TBA440CC
See NS Package N16C

Test Circuit



Absolute Maximum Ratings

| | |
|--|-----------------|
| Supply Voltage | 15V |
| Current Into Pin 14 | 50 mA |
| Power Dissipation | 700 mW |
| Maximum Resistance Between Pins 8 and 9 | 20Ω |
| Operating Temperature Range | -25°C to +70°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (T_A = 25°C, V_{CC} = 13V, I₁₄ = 40 mA, unless otherwise specified)

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------------------------|--|---|------|-------|------|-------|
| I ₁₃ | Current Consumption | V ₁₃ = 15V | 14.5 | 17.5 | 20.5 | mA |
| V ₁₄ | Internal Supply Voltage | I ₁₄ = 40 mA, V _{IN} = 0 | 5.5 | 6.0 | 6.8 | V |
| V ₁₁ | DC Voltage at Output | V _{IN} = 0 | 5.5 | 7 | 8.5 | V |
| V ₁₂ | DC Voltage at Output | | 1.7 | 3 | 4.3 | V |
| I ₅ | Control Current for Tuner AGC | (10 dB After Beginning of the Tuner AGC, V ₅ ≥ 2V) | 3 | | | mA |
| V ₄ | IF Control Voltage for G _{MAX} | | 0 | | 0.5 | V |
| V ₄ | IF Control Voltage for G _{MIN} | | 2.5 | | | V |
| V ₇ | Voltage for AGC Gating Input | | -5 | | -2 | V |
| R ₁₀₋₁₁ | Resistance for Output Voltage | V ₁₁ = 3 V _{p-p} | 3 | 4 | 10 | kΩ |
| I ₁₁ , I ₁₂ | Available Output Current to Ground | | | | 5 | mA |
| I ₁₁ , I ₁₂ | Available Output Current to V _{CC+} | | -1 | | | mA |
| Z ₁₋₁₆ | Input Impedance at G _{MAX} | | | 1.8/2 | | kΩ/pF |
| Z ₁₋₁₆ | Input Impedance at G _{MIN} | | | 1.9/0 | | kΩ/pF |
| V _{IN} | Input Voltage | V ₁₁ = 2 V _{p-p} , (Note 1) | | 100 | | μV |
| V _{IN} | Input Voltage | V ₁₁ = 3 V _{p-p} , (Note 1) | | 150 | | μV |
| B _{VIDEO} | Video Bandwidth | | | 9 | | MHz |
| G _V | AGC Range | | 50 | 55 | | dB |
| | Sound/Chroma Intermodulation Products | (Note 2) | -40 | | | dB |

Note 1: RMS of sync tip voltage, see test circuit.

Note 2: Sound subcarrier -24 dB
Color subcarrier -2 dB

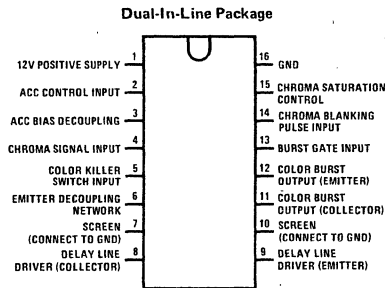
TBA510 Chrominance Combination

General Description

The TBA510 is an integrated chrominance amplifier circuit for color TV receivers incorporating a variable gain ACC circuit, a dc control for chroma saturation

which can be ganged to the receiver contrast control, chroma blanking and burst gating functions, a burst output stage, a color killer and a PAL delay line driver.

Connection Diagram

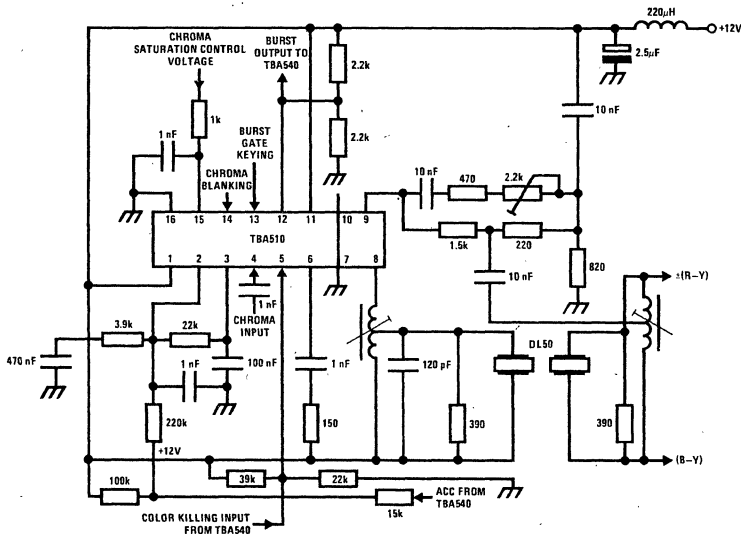


TOP VIEW

Dual-In-Line Package, Order Number TBA510
See NS Package N16A

Quad-In-Line Package, Order Number TBA510Q
See NS Package N16C

Typical Application



Note: The A.C.C. loop gain can be defined by inserting a suitable resistor between pins 2 & 3. (Example 22 kΩ).

Absolute Maximum Ratings

| | |
|---|---|
| Power Dissipation, ($T_A = 60^\circ\text{C}$) | 550 mW |
| V1-16 | 13.2V |
| V13-16 | -5V |
| V14-16 | -5V |
| V8-16 | +20V |
| V11-16 | +20V |
| $I_g = -I_g$ | 20 mA |
| $I_{11} = -I_{12}$ | 20 mA |
| Operating Temperature Range | -20°C to $+60^\circ\text{C}$ |
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics ($V_{1-16} = 12\text{V}$, $T_A = 25^\circ\text{C}$)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|-----|-----|------------|
| CHROMINANCE SIGNAL (FED IN VIA 1 nF) | | | | | |
| V4-16 | Input Voltage Range | 15 | | 300 | mVp-p |
| Z4-16 | Input Impedance | 2 | 3 | | k Ω |
| BURST SIGNAL OUTPUT | | | | | |
| V12-16 | DC Voltage | | 7.7 | | V |
| V12-16 | Output Signal | | 1 | | Vp-p |
| I_{11} | Collector Current of Output Transistor | | 4 | | mA |
| CHROMINANCE SIGNAL OUTPUT (BURST BLANKED INTERNALLY) | | | | | |
| V9-16 | DC Voltage | | 6.8 | | V |
| V9-16 | Output Signal (Color Bars) at Nominal Saturation and Maximum Contrast | | 1 | | Vp-p |
| | Range of Contrast and Saturation Control | -30 | | +6 | dB |
| I_g | Collector Current of Output Transistor | | 5 | | mA |
| ACC INPUT | | | | | |
| V2-16 | ACC Threshold Voltage | | 2.5 | | V |
| Z2-16 | Input Impedance | 50 | | | k Ω |
| CHROMA-SATURATION CONTROL | | | | | |
| V15-16 | Control Voltage Range | 1.5 | | 4.5 | V |
| Z15-16 | Input Impedance | 50 | | | k Ω |
| CHROMA BLANKING PULSE | | | | | |
| V14-16 | Switching Level | | -1 | | V |
| Z14-16 | Input Impedance | | 2 | | k Ω |

Electrical Characteristics (Continued), (V₁₋₁₆ = 12V, T_A = 25°C)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------------------------|------------|-----|------|-----|-------|
| BURST GATE PULSE | | | | | |
| V13-16 Switching Level | | | -2.2 | | V |
| Z13-16 Input Impedance | | | 4 | | kΩ |
| COLOR KILLER | | | | | |
| V5-16 Input Voltage For: | | | | | |
| Color "ON" | | 2.3 | | | V |
| Color "OFF" | | | | 1.9 | V |
| Signal Suppression at Color "OFF" | | | 50 | | dB |
| Z5-16 Input Impedance | | 50 | | | kΩ |

Note 1: The phase difference between the chroma and burst outputs at nominal saturation is less than 5°.

Note 2: Phase shift of chroma output signal over saturation control range +6 to -10 dB is less than 5°.

Pin Function Description

1. Positive 12V supply.

2. ACC control potential input. The potential required at pin 2 for maximum gain is about 2.5V; gain reduction occurs when this potential is reduced, $Z_{IN} > 50 \text{ k}\Omega$.

3. ACC gain adjustment point. The internal ACC circuit consists of a long-tailed pair system. The "cold" side of the pair is internally established at a dc potential of 2.5V and is brought out on pin 3. This enables a decoupling capacitor to be connected. A very high loop gain in the ACC system is possible but as this is not necessarily desirable, because of stability and ripple considerations, a resistor of a suitable value can be connected between pins 2 and 3 to reduce the control sensitivity to any desired level.

4. Chroma input signal. The input voltage range is 15 to 300 mVp-p (26 dB) with a color bar signal.

5. Color killer switching input. The input impedance is greater than 50 kΩ. Color "ON" 2.3V; color "OFF" 1.9V. The chroma signal suppression when killed is greater than 50 dB.

6. Emitter decoupling network. The series network decouples an emitter of an amplifier stage. The value of resistance influences the gain of both the chroma channel and the burst channel.

7. Screen. This pin must be connected to pin 10 and taken via a direct path to earth. The function of this is to minimize crosstalk between burst and chroma channels.

8. Delay line driver (collector). Supplies the chroma signal drive to the delay line driver transformer, the cold end of which is connected to +12V. The maximum permitted voltage excursion at this pin is to 20V peak. Maximum ac signal current swing, 12 mA-p.

9. Delay line driver (emitter). Supplies the chroma to the network which provides the non-delayed signal to the delay line output transformer. The emitter is established internally at a potential of $6.8 \pm 1V$ and the external

network, which must incorporate a resistive dc path to earth, must not demand more than 20 mA peak current.

10. Screen. Connect to pin 7 and then to earth.

11. Color burst output (collector). If a low impedance color burst is required (from the emitter of the color burst output, pin 12) pin 11 will be connected to the +12V supply. The maximum voltage and current excursions permitted on pin 11 are 20V peak and 20 mA peak.

12. Color burst output (emitter). An external load resistor of 2 kΩ is required, connected to earth, and a dc potential of 7.7V is established on pin 11 due to the internal circuitry. The burst output voltage is 1 Vp-p $\pm 1 \text{ dB}$ over the chroma input signal range of amplitudes.

13. Burst gate gating pulse. A pulse derived from the horizontal flyback pulse can be used as a source of gating waveform. A negative-going pulse of not greater than 5V amplitude is necessary, the input impedance is 4 kΩ and the switching is about -2.2V.

14. Chroma blanking pulse input. A negative-going horizontal flyback pulse can be used here. Its amplitude should not exceed 5V. The input impedance at this pin is 2 kΩ and the switching level is about -1.0V. This pulse is used to blank the burst output from the chroma channel.

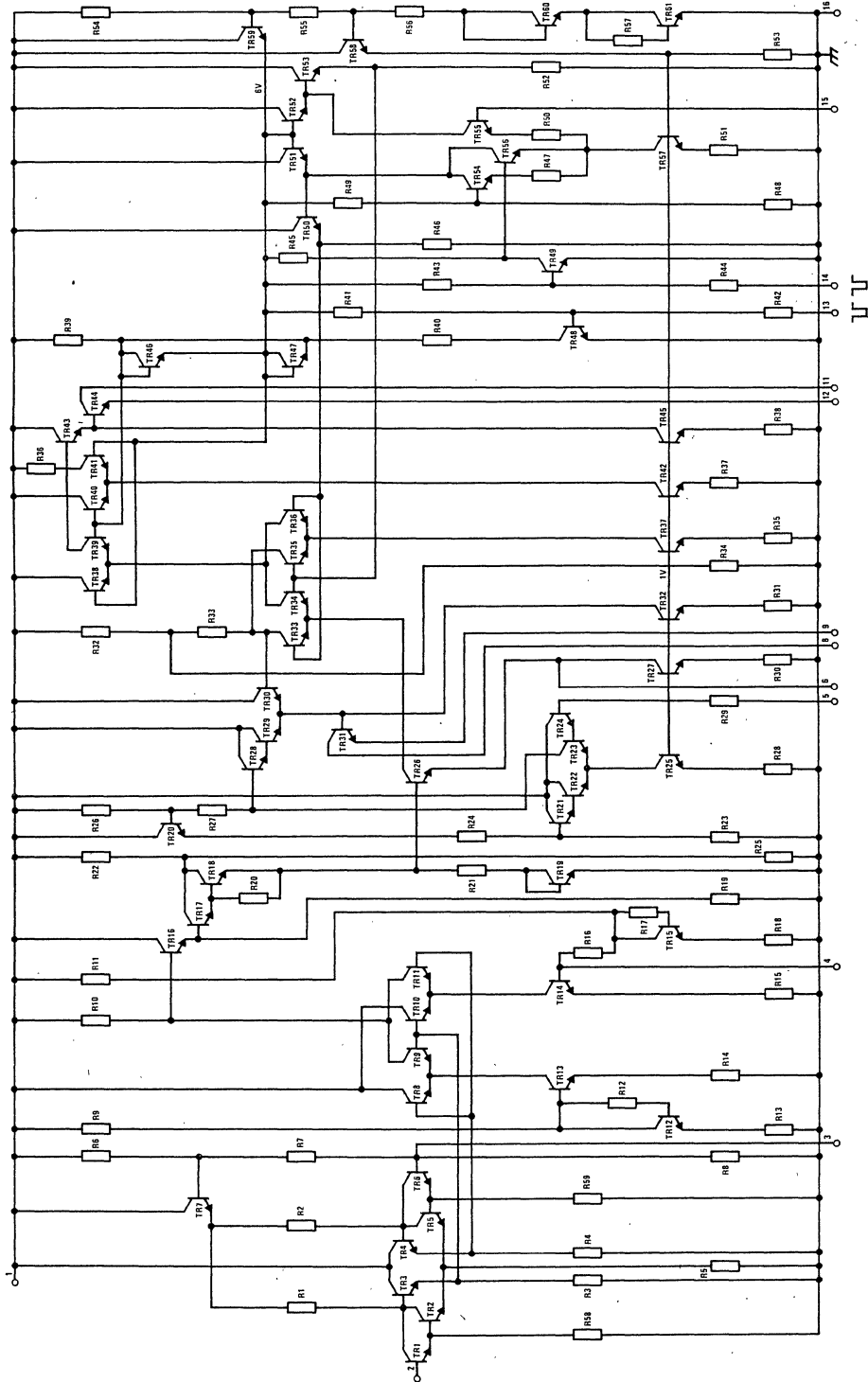
15. Chroma saturation control. The dc control voltage range required is from 1.5-4.5V (highest gain at -4.5V). The input impedance is greater than 50k and a control range of from +6 to -30 dB is given.

16. Negative supply or earth.

PERFORMANCE COMMENTS

- The phase difference between the chroma and burst outputs at nominal saturation is less than 5°.
- Phase shift of chroma output signal over saturation control range +6 to -10 dB is less than 5°.

Schematic Diagram



TBA510

10

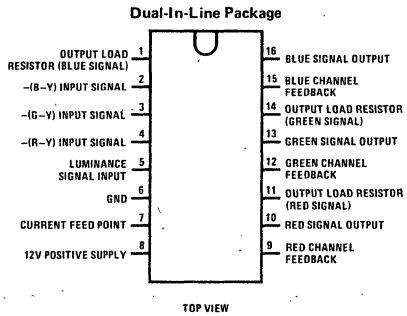
TBA530 RGB Matrix Preamplifier

General Description

The TBA530 is an integrated circuit for color TV receivers incorporating a matrix preamplifier for R-G-B cathode or grid drive of the picture tube without clamping circuits.

It has been designed to be driven from the TBA990 or TBA520 synchronous demodulator circuits and exhibits excellent channel matching and stability.

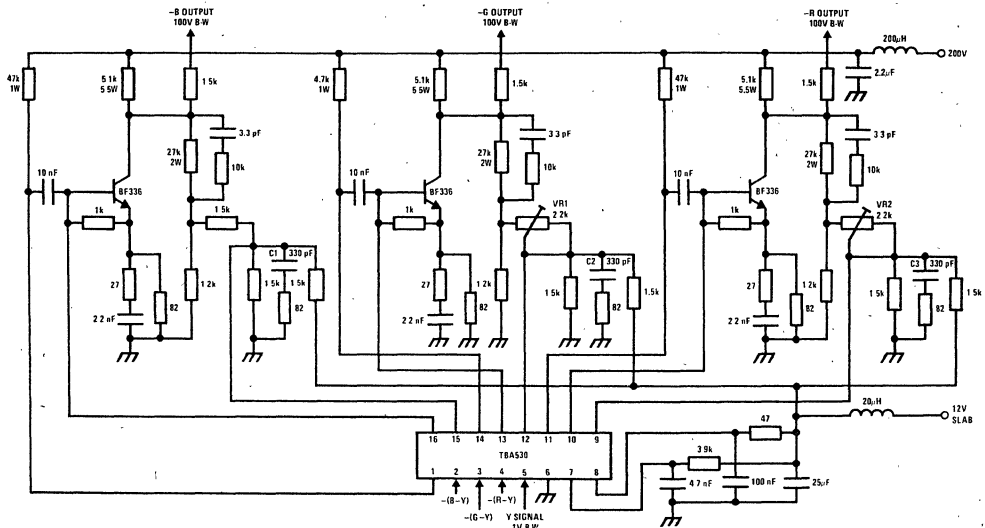
Connection Diagram



Dual-In-Line Package, Order Number TBA530
See NS Package N16A

Quad-In-Line Package, Order Number TBA530Q
See NS Package N16C

Typical Application



- Note 1:** DC output voltages R, G and B are typically 140V in this circuit.
- Note 2:** The voltage gain between pins 2, 3, 4 and collectors (BF336) is typically 100.
- Note 3:** The normal bias voltage on pins 1, 11, 14 is 8V.
- Note 4:** Pin 7 requires a 4.7 nF decoupling capacitor.
- Note 5:** DC bias level shift, provided by internal zeners between pins 1-16, 14-13 and 11-10, requires 10 nF bypass capacitors for H.F.

Absolute Maximum Ratings

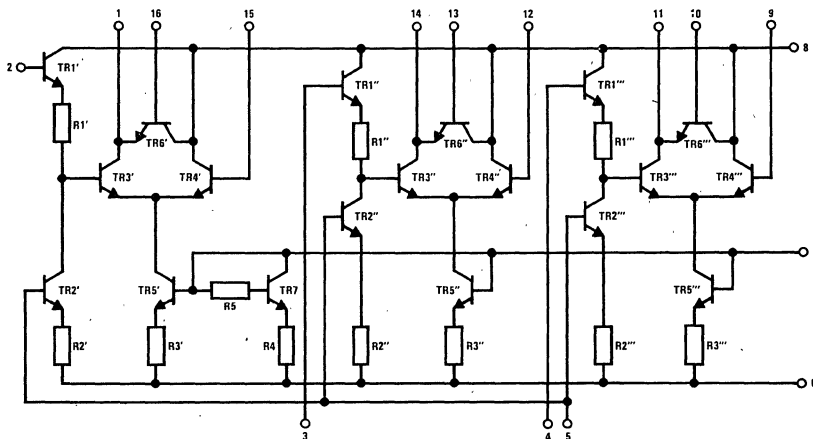
| | |
|--|-----------------|
| V8-6 | 13.2V |
| I1, I11, I14 | 10 mA |
| I10, I13, I16 | 50 mA |
| Power Dissipation (TA = 60°C) | 400 mW |
| Operating Temperature Range | -20°C to +60°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics

Measuring Conditions: Black Level: $V_{R-Y} = V_{G-Y} = V_{B-Y} = 7.5V$, $V_Y = 1.5V$, V8-6 = 12V, TA = 25°C

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|-----|-----|-----|-------|
| Ratio of Gain of Luminance Amplifier to Color Amplifiers | As Measured in Application Circuit | 0.9 | | 1.1 | |
| R2-6 | Input Resistance of Color | | 60 | | kΩ |
| R3-6 | Difference Amplifiers | | 60 | | kΩ |
| R4-6 | | | 60 | | kΩ |
| C2-6 | Input Capacitance of Color | | 3 | | pF |
| C3-6 | Difference Amplifiers | | 3 | | pF |
| C4-6 | | | 3 | | pF |
| R5-6 | Input Resistance of Luminance Amplifier | | 20 | | kΩ |
| C5-6 | Input Capacitance of Luminance Amplifier | | 10 | | pF |
| B | Bandwidth of all Channels | | 6 | | MHz |
| I8 | Total Current Drain | | 30 | | mA |
| I7 | Bias Current | | 2.5 | | mA |

Schematic Diagram



Pin Function Description

The function is quoted against the corresponding pin number.

1. Output load resistor, blue signal. (Also pins 11 and 14 for red and green signals respectively.) Resistors (47 k Ω , 1W) connected to +200V provide the high value loads for the internal amplifying stages. The nominal operating potential on these pins is defined by the IC and dc feedback and is approximately +8V. The maximum current which can be allowed at each of these pins is 10 mA.

2. -(B-Y) input signal. This signal is fed via a low-pass filter from the TBA520 demodulator IC (pin 7) having a dc level of about +7.5V. The input resistance for this pin is typically 60 k Ω with an input capacitance of less than 5 pF (similarly for pins 3 and 4).

3. -(G-Y) input signal. The dc black level of this signal is about +7.5V. (See pin 2.)

4. -(R-Y) input signal. The dc black level of this signal is about +7.5V. (See pin 2.)

5. Luminance signal input. The dc level on this pin for picture black is +1.6V. The required signal amplitude is 1V black-to-white with negative-going syncs (or blanking) for cathode drive as shown. The input resistance at this pin is 20 k Ω approximately with a capacitance of less than 15 pF.

6. Negative supply (earth).

7. Current feed point. A current of approximately 2.5 mA is required at this pin, fed via a 3.9 k Ω resistor from +12V, to bias the internal differential amplifiers. A decoupling capacitor of 4.7 nF is necessary.

8. Positive 12V supply. Maximum supply voltage permitted, 13.2V. Current consumption approximately 30 mA.

9. Red channel feedback (green channel, pin 12; blue channel, pin 15). The dc working points and gains of both the output stages and the IC amplifier stages are stabilized by the feedback circuits. The black level potentials at the collectors of the output stages (tube cut-off) are adjusted by setting correctly the dc levels of the color difference signals produced by the TBA520 demodulator IC. The gains of the R-G-B output stages are adjusted to give the correct white points setting on the picture tube by adjusting the potentiometers in the feedback paths (VR1, VR2). (See notes on setting up decoder.)

10. Red signal output (green and blue signal outputs on 13 and 16). These pins are internally connected with pins 11, 14 and 1 respectively via zener type junctions to give a dc level shift appropriate for driving the output transistor bases directly. To bypass the zener junctions at h.f. three 10 nF capacitors are required.

11. Output load resistor, red channel (see pin 1).

12. Green channel feedback (see pin 9).

13. Green signal output (see pin 10).

14. Output load resistors, green channel (see pin 1).

15. Blue channel feedback (see pin 9).

16. Blue signal output (see pin 10).

Note 1: Careful attention to earth paths should be given, avoiding common impedances between the input (decoder) side and the output stages. Also, to enable matched performance to be achieved, a symmetrical board and component layout should be adopted for the three output stages. To compensate for the effect upon h.f. response of inevitable differences the compensating capacitors C1 and C2 and C3 may be appropriately selected for any given board layout.

Note 2: The signal black level at the collectors of the R-G-B output stages depends upon the +12V supply, the dc level of the color difference signals from the TBA520 demodulator IC and the black level potential of the luminance signal applied to the TBA530 matrix IC. The dc levels of the signals produced and handled by the IC's are designed to have approximately proportional tracking with the 12V supply potential,

$$\text{i.e., } \frac{\Delta V(\text{dc level, signal})}{\Delta V_{12V}} \approx \frac{V_{\text{nom}}(\text{dc level, signal})}{12}$$

To ensure that changes in picture black level due to variations on the 12V supply to the IC's occur in a predictable way, all the IC's should be operated from a common supply line. This is specially important for the TBA520 and TBA530. Furthermore, to limit the changes in picture black level during receiver operation, the 12V supply should have a stability of not worse than $\pm 3\%$ due to operational variations.

Note 3: To reduce the possibility of patterning on the picture due to radiation of the harmonics of the products of the demodulation process, the leads carrying the drive signals to the picture tube should be as short as the receiver layout will allow. Resistors (typically 1k 5 Ω) connected in series with the leads and mounted close to the collectors of the output transistors provide useful additional filtering of harmonics.

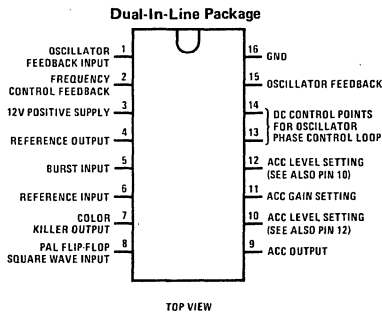
TBA540 Reference Combination

General Description

The TBA540 is an integrated 'color reference' oscillator circuit for PAL TV receivers. The oscillator employs a quartz crystal and incorporates automatic phase and amplitude control. A synchronous demodulator is used to compare the phase and amplitude of the swinging

burst ripple with the PAL flip-flop waveform and generates appropriate ACC color killer and identification signals. A high standard of noise immunity has been obtained by using synchronous demodulation.

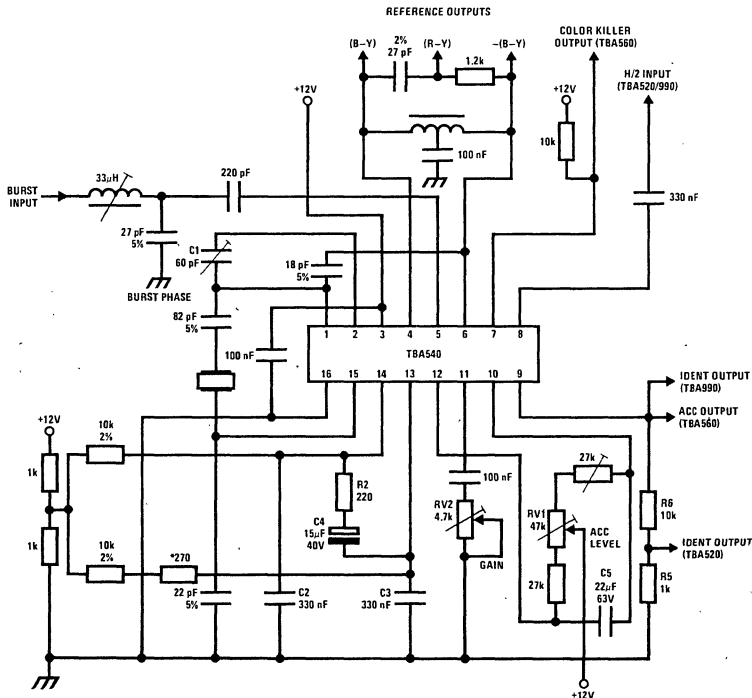
Connection Diagram



Dual-In-Line Package, Order Number TBA540
See NS Package N16A

Quad-In-Line Package, Order Number TBA540Q
See NS Package N16C

Typical Application



Absolute Maximum Ratings

| | | | |
|---|----------------|--|-----------------|
| V3-16 | 13.2V | Storage Temperature Range | -65°C to +150°C |
| Power Dissipation (T _A = 60°C) | 780 mW | Lead Temperature (Soldering, 10 seconds) | 300°C |
| Operating Temperature Range | -20°C to +60°C | | |

Electrical Characteristics (V3-16 = 12V, T_A = 25°C as measured in typical application circuit)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|--|---------------------------|----------|-----|-------------------|
| Output Signals | | | | | |
| V4-16 | B-Y Reference Signal Output | 1 | 1.4 | 2 | V _{p-p} |
| V7-16 | Color Killer Output | | | | |
| | Color "ON" | | 12 | | V |
| | Color "OFF" | | 100 | 250 | mV |
| V9-16 | ACC Output Signal Range | | | | |
| | At Correct Phase of PAL Switch | | 4 to 0.2 | | V |
| | At Incorrect Phase of PAL Switch | | 4 to 11 | | V |
| Oscillator Section (Amplifier) | | | | | |
| R15-16 | Input Resistance | | 3.5 | | kΩ |
| C15-16 | Input Capacitance | | 5 | | pF |
| G15-1 | Voltage Gain | | 4.7 | | |
| Reactance Control Section | | | | | |
| G15-2 | Voltage Gain With Pins 13 and 14 Shorted | | 1.3 | | |
| ΔG15-2 | Rate of Change of Gain G15-2 | | 5 | | rad ⁻¹ |
| Δφ5-4 | With Phase Difference Between Burst and Reference Signal | | | | |
| Burst Input | | | | | |
| R5-16 | Input Resistance | | 1 | | kΩ |
| | Burst Input Level | 0.7 | 1.5 | | V _{p-p} |
| Flip-Flop Input | | | | | |
| V8-16 | Voltage | | 2.5 | | V _{p-p} |
| R8-16 | Resistance | | 3.3 | | kΩ |
| Phase Lock Loop | | | | | |
| | Oscillator Phase Error for a Burst Signal | Crystal Frequency 1400 Hz | | ±10 | DEG |
| | Holding Range | | ±600 | | Hz |
| | Pull-in Range | | ±300 | | Hz |
| | Temperature Coefficient of Oscillator | | | 2 | Hz/°C |

Application Notes

A dc connection between pins 4 and 6 is necessary via the bifilar coupling inductor. The function of this inductor is to produce, on pin 6, a signal of equal amplitude and opposite phase (B-Y) to that on pin 4. A center tap on the inductor, connected to earth via a dc blocking capacitor, is therefore necessary.

DC Control Points in Reference Control Loop

Pins 13 and 14 are connected to opposite sides of a differential amplifier circuit and are brought out for the purpose of dc balancing of the reactance stage and the connection of the bandwidth-determining filter network. Two 2% tolerance 10k resistors with the addition of a 270Ω resistor at pin 13 are used in place of the previous

balancing network. The 270Ω resistor may be modified according to the nature of the noise that appears at pin 5.

Initial Adjustment

- (a) Remove burst signal.
- (b) Short-circuit pins 13-14. Adjust oscillator to correct frequency by C1.
- (c) Set the ACC level adjustment RV1, to give +4V on pin 9. Remove short circuit.
- (d) Apply burst signal.
- (e) Adjust ACC gain, RV2, to give a burst amplitude of 1.5V_{p-p} on pin 5.

Pin Function Description

1. Oscillator feedback output. The crystal receives its energy from this pin. The output impedance is approximately $2\text{ k}\Omega$ in parallel with 5 pF .

2. Reactance control stage feedback. This pin is fed internally with a sine wave derived from the reference output (pin 4) and controlled in amplitude by the internal reactance control circuit. The phase of the feedback from pin 2 to the crystal via C1 is such that the value of C1 is effectively increased. Pin 2 is held internally at a very low impedance, therefore the tuning of the crystal is controlled automatically by the amplitude of the feedback waveform and its influence on the effective value of C1.

3. Positive 12V supply. The maximum voltage must not exceed 13.2V .

4. Reference waveform output. This pin is driven internally by the regenerated subcarrier waveform in B-Y phase. (The output is in B-Y rather than R-Y phase as the burst phase network produces a lag of 90° of the burst applied to pin 5). An output amplitude of nominally 1.4Vp-p is produced at low impedance. No dc load to earth is required. A dc connection between pins 4 and 6 is, however, necessary via the bifilar coupling inductor. The function of this inductor is to produce, on pin 6, a signal of equal amplitude and opposite phase $-(B-Y)$ to that on pin 4. A center tap on the inductor, connected to earth via a dc blocking capacitor, is therefore necessary.

5. Burst waveform input. A burst waveform amplitude of 1.5Vp-p is required to be ac-coupled to this pin. The amplitude of the burst will normally be controlled by the adjustment and operation of the ACC circuit. The input impedance at this pin is approximately $1\text{ k}\Omega$ and a threshold level of 0.7V must be exceeded before the burst signal becomes effective. A dc bias of 400 mV is internally derived for pin 5.

The absolute level of the tip of the burst at pin 5 will normally reach 1.5V (1.5Vp-p burst amplitude).

6. Reference waveform input. This pin requires a reference waveform in the $-(B-Y)$ phase, derived from pin 4 via a bifilar transformer (see pin 4), to drive the internal balanced reactance control stage. A dc connection between pins 4 and 6 must be made via the transformer.

7. Color killer output. This pin is driven from the collector of an internal switching transistor and requires an external load resistor (typically $10\text{ k}\Omega$) connected to $+12\text{V}$. The unkilld and killed voltages on this pin are then

$+12\text{V}$ and $< 250\text{ mV}$ respectively. (The voltage range on pin 9 over which switching of the color killed output on pin 7 occurs is nominally $+2.5\text{V}$.)

8. PAL flip-flop square wave input. A 2.5Vp-p square wave derived from the PAL flip-flop (in the TBA520 or TBA990 demodulator IC) is required at this pin, ac-coupled via a capacitor. The input impedance is about $3.3\text{ k}\Omega$.

9. ACC output. An emitter follower provides a low impedance output potential which is negative-going with a rising burst input amplitude. With zero burst input signal the dc potential produced at pin 9 is set to be $+4\text{V}$ (RV1). The appearance of a burst signal on pin 5 will cause the potential on pin 9 to go in a negative direction in the event that the PAL flip-flop is identified to be in the correct phase. The range of potential over which full ACC control is exercised at pin 9 is determined by the control characteristic of the ACC amplifier, i.e., for the TBA560 from 0.8 to 1V . The potential on pin 9 will fall to a value within this range as the burst input signal is stabilized to an amplitude of 1.5Vp-p . The latter condition is achieved by correct adjustment of RV2. If, however, the PAL flip-flop phase is wrong the potential on pin 9 will move positively. The potential divider R5, R6 will then operate a PAL switch cut-off function in the TBA520 demodulator IC.

10. ACC level setting. The network connected between pins 10 and 12 balances the ACC circuit and RV1 is adjusted to give $+4\text{V}$ on pin 9 with no burst input signal to pin 5. C5 provides filtering.

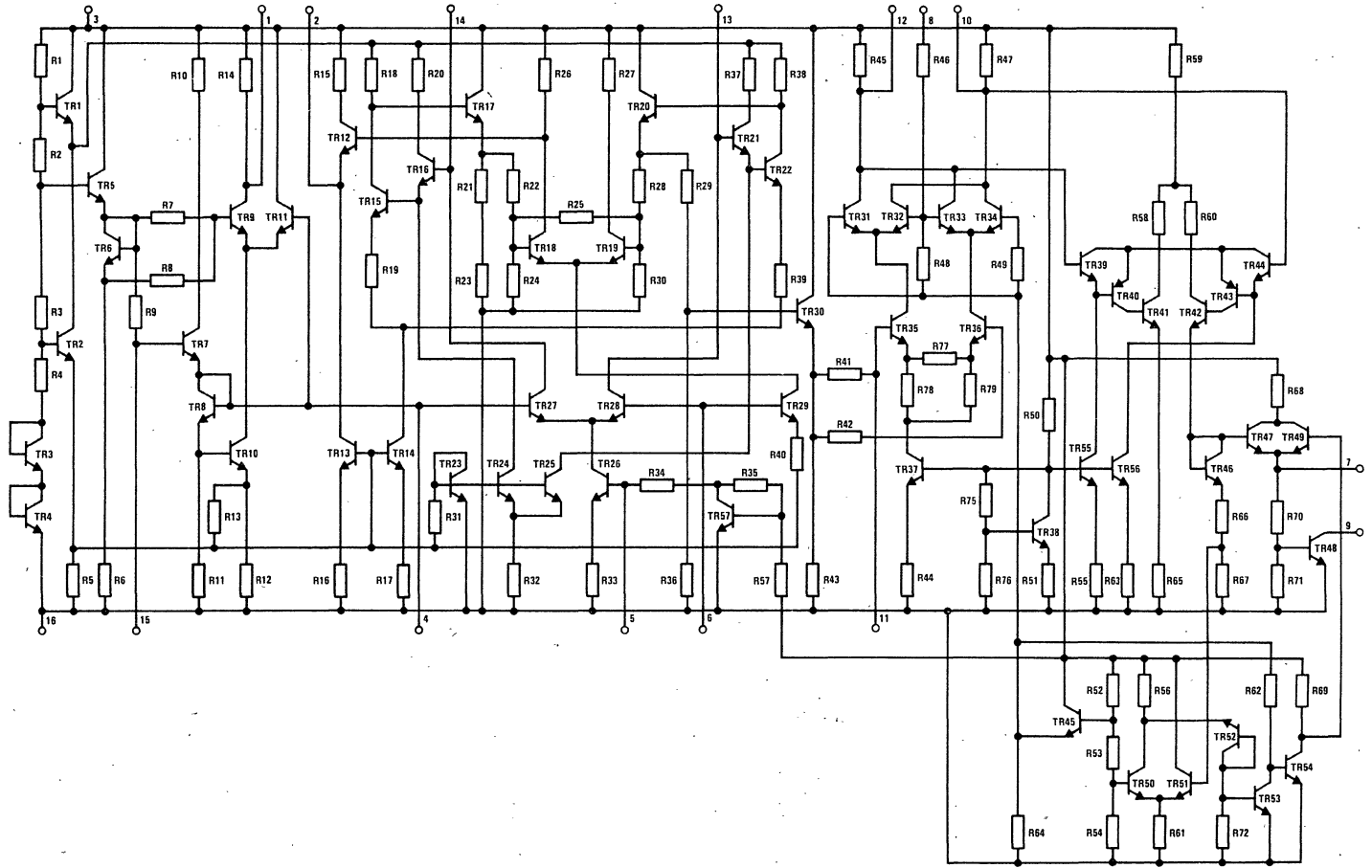
11. ACC gain control. RV2 is adjusted to give the correct amplitude of burst signal on pin 5 (1.5Vp-p) under ACC control.

12. See pin 10.

13. See pin 14.

14. DC control points in reference control loop. Pins 13 and 14 are connected to opposite sides of a differential amplifier circuit and are brought out for the purpose of dc balancing of the reactance stage and the connection of the bandwidth-determining filter network. Two 2% tolerance $10\text{ k}\Omega$ resistors with the addition of a 270Ω resistor at pin 13 are used in place of the previous balancing network. The 270Ω resistor may be modified according to the nature of the noise that appears at pin 5.

The filter network consists of R2, C2, C3 and C4. The dc potentials on these pins are nominally $+6\text{V}$.



Absolute Maximum Ratings (Note 1)

| | | | |
|-------------|--------------|--|-----------------|
| V11-16 | 13.2V | I _Q | -10 mA |
| V8-16 Min. | -5V | Continuous Total Power Dissipation | 550 mW |
| V10-16 Min. | -5V | Operating Free Air Temperature Range | -20°C to +60°C |
| V12-16 | -5V to +6V | Storage Temperature Range | -65°C to +150°C |
| V13-16 | -3V to +6.5V | Lead Temperature (Soldering, 10 seconds) | 300°C |
| V14-16 Min. | -5V | | |

Electrical Characteristics with V11-16 = 12V, T_A = 25°C (as measured in typical application circuit)

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------------|---|--|------|-------------------|-----|-------------|
| V1-15 | Chrominance Input Signal Range (Value of Color Bars With 75% Saturation) | | 4 | | 80 | mVp-p |
| I ₃ | Luminance Input Current Black to White | | | 0.5 | 1.5 | mA p-p |
| V2-16 | Contrast Control Characteristic | Full Gain 6 dB Attenuation 20 dB Attenuation (Note 2) | | 5.6 3.7 2.0 | | V V V |
| V6-16 | Brightness Control Voltage for Black Level of 1.5V at Pin 5 | (Note 3) | | 1.3 | | V |
| V8-16 | Flyback Blanking Pulses | | | | | |
| V8-16 | For 0V Blanking Level at Pin 5 | | 0 | -0.5 | -1 | Vp-p |
| V8-16 | For 1.5V Blanking Level at Pin 5 | | -2 | -2.5 | -3 | Vp-p |
| V13-16 | Saturation Control Characteristic | Full Gain 6 dB Attenuation 20 dB Attenuation (Note 2) | | 6.2 4.4 2.7 | | V V V |
| I ₁₀ | Burst Gating Pulse | | 0.05 | | 1 | mA p-p |
| V13-16 | Color Killer | | 0.5 | | 1 | V |
| V14-16 | Automatic Chrominance Control | | | | | |
| V14-16 | Voltage for Maximum Gain | | | 1.2 | | V |
| V14-16 | Voltage for Minimum Gain | | | 0.5 | | V |
| V14-16 | Gain Reduction | | | 26 | | dB |
| V14-16 | Input Resistance | | 50 | | | kΩ |
| V5-16 | Luminance Output Voltage (Black-White) at Nominal Contrast and Input Current as above | (Note 2) | | 1 | 3 | Vp-p |
| V5-16 | Black Level Shift Due to Changes of Contrast and Video Content at Constant Brightness Setting | | | | 100 | mV |
| V7-16 | Burst Output | | | 1 | | Vp-p |
| V9-16 | Chrominance Output at Nominal Contrast and Saturation | (Note 2) | | 1 | | Vp-p |
| V9-16 | 3 dB Bandwidth of Chrominance and Luminance Amplifier | | | 5 | | MHz |
| V9-16 | Matching of Luminance to Chrominance Ratio at 10 dB Contrast Control | | | | 2 | dB |

Note 1: V2-16 and V13-16 must always be lower than V11-16.

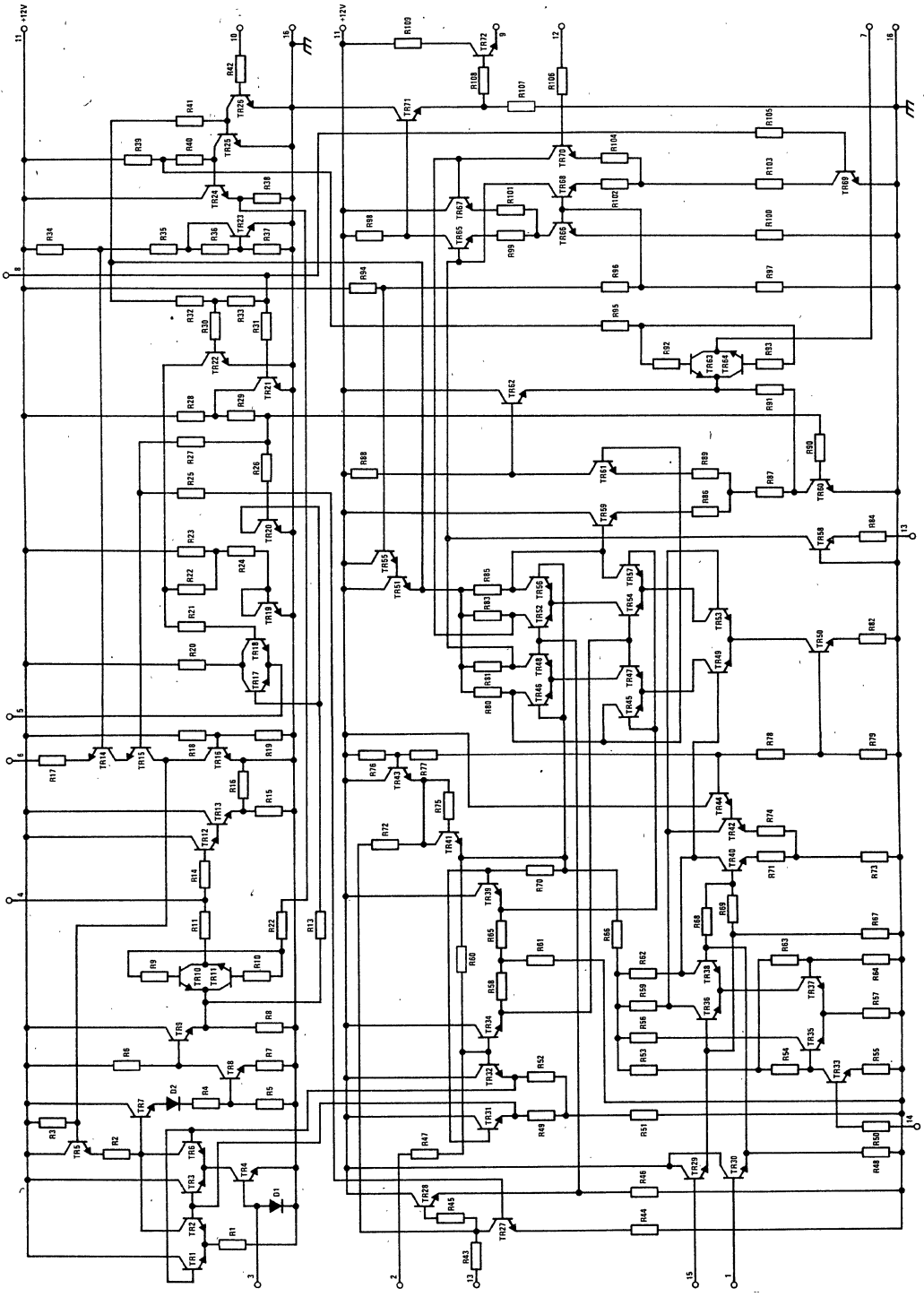
Note 2: Typical or nominal contrast or saturation = maximum value -6 dB. Thus the control is +6 to -14 dB on the nominal.

Note 3: When V6-16 is increased above 1.7V the black level of the output signal remains at 2.7V.

Pin Function Description

1. **Balanced chroma signal input (in conjunction with pin 15).** This is derived from the chroma signal bandpass filter, designed to provide a push-pull input. An input signal amplitude of at least 4 mVp-p is required between pins 1 and 15. Both pins require a dc potential of approximately +3.0V. This is derived as a common mode signal from a network connected to pin 7 (burst output). In this way dc feedback is provided over the burst channel to stabilize its operation. All figures for the chrominance signal are based on a color bar signal with 75% saturation; i.e., burst-to-chroma ratio of input signal is 1:2.
2. **DC contrast control.** With +3.7V on this pin, the gain in the luminance channel is such that a 0.5 mA black-to-white input signal to pin 3 gives a luminance output signal amplitude on pin 5 of 1V black-to-white. A variation of voltage on pin 2 between +5.6V and +2V gives a corresponding gain variation of +6 to > -14 dB. A similar variation in gain in the chroma channel occurs in order to provide the correct tracking between the two signals. Beam current limiting can be applied via the contrast control network as shown in the peripheral circuit, when a separate overwind is available on the line output transformer.
3. **Luminance signal input.** This terminal has a very low input impedance and acts as a current sink. The luminance signal from the delay line is fed via a series terminating resistor and a dc blocking capacitor and requires to be about 0.5 mA p-p amplitude. A dc bias current is required via a 12 k Ω resistor to the +12V line.
4. **Charge storage capacitor for black level clamp.**
5. **Luminance signal output.** An emitter follower provides a low impedance output signal of 1V black-to-white amplitude at nominal contrast setting having a nominal black level in the range 0 to +2.7V. An external emitter load resistor is required, not less than 1 k Ω . If a greater luminance output is required than 1V, with normal control settings, the input current swing at pin 3 should be increased in proportion.
6. **Brightness control.** Over the range of potential +0.9 to +1.7V the black level of the luminance output signal (pin 5) is increased from 0 to +2.7V. The output signal black level remains at +2.7V when the potential on pin 6 is increased above +1.7V.
7. **Burst output.** A 1 Vp-p burst (controlled by the ACC system) is produced here. Also, to achieve good dc stability by negative feedback in the burst channel the dc potential at this pin is fed back to pins 1 and 15 via the chroma input transformer.
8. **Flyback blanking input waveform.** Negative-going horizontal and vertical blanking pulses may be applied here. If rectangular blanking pulses of not greater than -1V negative excursion, or dc coupled pulses of similar amplitude whose negative excursion is at zero volts dc are applied, the signal level at the luminance output (pin 5) during blanking will be 0V. However, if the blanking pulses applied to pin 8 have an amplitude of -2 to -3V the signal level at the luminance output during blanking will be +1.5V. The negative pulse amplitude should not exceed -5V.
9. **Chroma signal output.** With a 1 Vp-p burst output signal (pin 7) and at nominal contrast and saturation setting (pins 2 and 13) the chroma signal output amplitude is 1 Vp-p. An external network is required which provides dc negative feedback in the chroma channel via pin 12.
10. **Burst gating and clamping pulse input.** A positive pulse of not less than 50 μ A is required on this pin to provide gating in the burst channel and luminance channel black-level clamp circuit. The timing and width of this current pulse should be such that no appreciable encroachment occurs into the sync pulse or picture line periods during normal operation of the receiver.
11. **+12V LT supply.** Correct operation occurs within the range 10.8 to 13.2V. All signal and control levels have a linear dependency on supply voltage but, in any given receiver design this range may be restricted due to considerations of tracking between the power supply variations and picture contrast and chroma levels. The power dissipation must not exceed 550 mW at 60°C ambient temperature.
12. **DC feedback for chroma channel (see pin 9).**
13. **Chroma saturation control.** A control range of +6 to > -14 dB is provided over a range of dc potential on pin 13 from 6.2 to 2.7V. Color killing is also achieved at this terminal by reducing the dc potential to less than +1V, e.g., from the TBA540 color killer output terminal. The minimum "kill factor" is 40 dB.
14. **ACC input.** A negative-going potential gives an ACC range of about 26 dB starting at +1.2V. From 1V to 800 mV the steepest part of the characteristic occurs, but a small amount of gain reduction also occurs from 800 mV to 500 mV. The input resistance is at least 50 k Ω .
15. **Chroma signal input (see pin 1).**
16. **Negative supply, 0V (Earth).**

Schematic Diagram



TBA920/TBA920S Line Oscillator Combination

General Description

The TBA920 is a monolithic integrated circuit intended for TV receivers with transistor-thyristor- or valve equipped output stages.

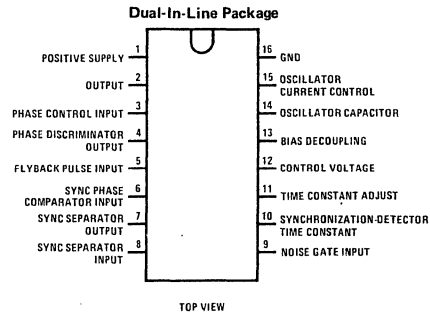
It combines the following functions:

- Noise gated sync separator
- Phase comparison between sync pulse and oscillator
- Line oscillator
- Loop gain and time constant switching (also for video recorder applications)
- Phase comparison between line-flyback pulse and oscillator
- Output stage for driving a variety of line output stages

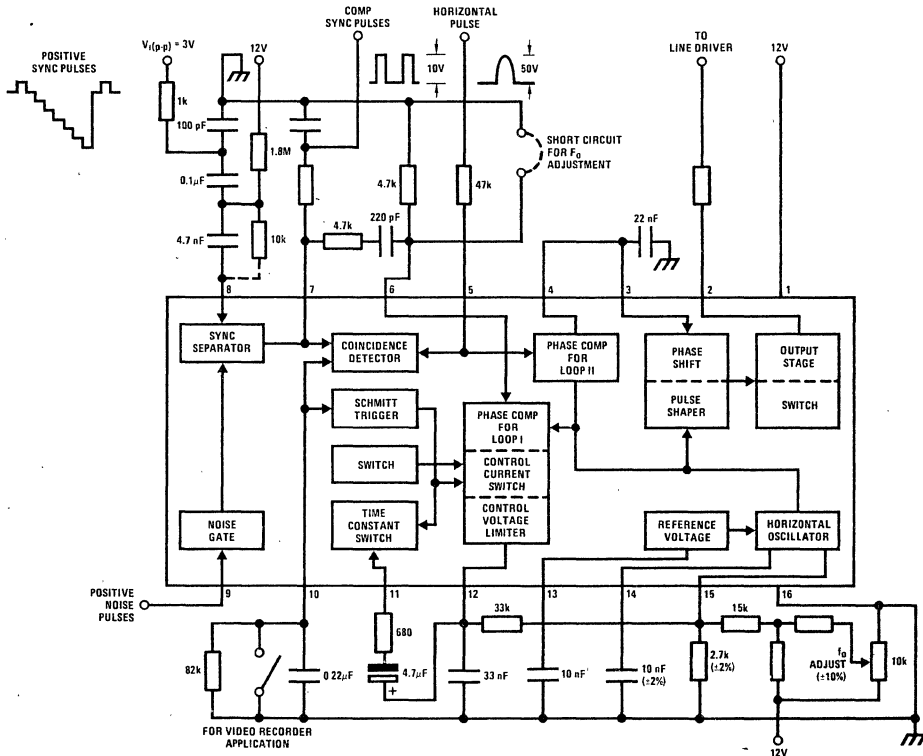
Connection Diagram

Dual-In-Line Package, Order Number TBA920 or TBA920S
See NS Package N16A

Quad-In-Line Package, Order Number TBA920Q
See NS Package N16C



Typical Application



Absolute Maximum Ratings

| | | | |
|--|--------|---|-----------------|
| V1-16 | 13.2V | Operating Temperature Range | -20°C to +60°C |
| I ₂ (Mean) | 20 mA | Storage Temperature Range | -65°C to +150°C |
| I ₂ (Peak) | 200 mA | Lead Temperature (Soldering, 10 seconds) | 300°C |
| I ₅ , I ₇ , I ₉ | 10 mA | Power Dissipation (T _A = 60°C) | 600 mW |

Electrical Characteristics at V1-16 = 12V, T_A = 25°C as measured in application circuit

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|---------------------------|------|--------|-------|
| Current Consumption | | | | | |
| I ₁ | I ₂ = 0 | | 36 | | mA |
| Video Signal | | | | | |
| V1 | Input Voltage Range | 1 | | 7 | Vp-p |
| I _Q | Input Current During Sync Pulse | | 100 | | μA |
| Noise Gating (Pin 9) | | | | | |
| V9-16 | Input Voltage (Peak Value) | 0.7 | | | V |
| I ₉ | Input Current (Peak Value) | 0.03 | | 10 | mA |
| Flyback Pulse (Pin 5) | | | | | |
| V5-16 | Input Voltage (Peak Value) | | ±1 | | V |
| I ₅ | Input Current (Peak Value) | 0.05 | 1 | | mA |
| R5-16 | Input Resistance | | 400 | | Ω |
| t ₅ | Pulse Duration at 15,625 Hz | 10 | | | μs |
| Composite Sync Pulses (Positive: Pin 7) | | | | | |
| V7-16 | Output Voltage | | 10 | | Vp-p |
| Output Resistance | | | | | |
| R7-16 | At Leading Edge of Pulse (Emitter Follower) | | 50 | | Ω |
| R7-16 | At Trailing Edge | | 2.2 | | kΩ |
| R7-16 (ext) | Additional External Load Resistance | 2 | | | kΩ |
| Driver Pulse (Pin 2) | | | | | |
| V2-16 | Output Voltage | | 10 | | Vp-p |
| I ₂ | Average Output Current | | | 20 | mA |
| I ₂ | Peak Output Current | | | 200 | mA |
| t ₂ | Output Pulse Duration When Synchronized | 12 | | 32 | μs |
| t _{o tot} | Permissible Delay Between Leading Edge of Output Pulse and Flyback Pulse at t ₅ = 12μs | 0 | | 15 | μs |
| V1-16 | Supply Voltage at Which Output Pulses are Obtained | 4 | | | V |
| Oscillator | | | | | |
| f _o | Frequency; Free Running | R15-16 = 3.3 kΩ, (Note 1) | | 15,625 | Hz |
| $\frac{\Delta f_o}{f_o}$ | Spread of Frequency at Nominal Values of Peripheral Components | | | ±5 | % |
| $\left \frac{\Delta f_o}{f_o} \right $ | Frequency Change When Decreasing the Supply Down to Minimum 4V | | | 10 | % |
| $\frac{\delta f_o}{f_o} / \frac{\delta V_P}{V_{Phom}}$ | Influence of Supply Voltage on Frequency at V _P = 12V | | | 5 | % |
| δf _o /δI ₁₅ | Frequency Control Sensitivity | | 16.5 | | Hz/μA |
| Control Loop I (Between Sync Pulse and Oscillator) | | | | | |
| V12-16 | Control Voltage Range | 0.8 | | 5.5 | V |
| Control Current (Peak Values) | | | | | |
| I _{12M} | V10-16 > 4.5V, V6-16 > 1.5V | | ±2 | | mA |
| I _{12M} | V10-16 < 2V, V6-16 > 1.5V | | ±6 | | mA |

Electrical Characteristics (Continued)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|---|---------|---------|--------------|
| Loop Gain of APC System | | | | | |
| $\frac{\Delta f}{\Delta t}$ | Time Coincidence Between Sync Pulse and Flyback Pulse or V10-16 > 4.5V | | 1 | | kHz/ μ s |
| $\frac{\Delta f}{\Delta t}$ | No Time Coincidence or V10-16 < 2V | | 3 | | kHz/ μ s |
| Δf | Catching and Holding Range | (Note 2) | ± 1 | | kHz |
| t | Pull-in Time | $\Delta f/f_0 = \pm 3\%$ ($\Delta f = 470$ Hz) | 20 | | ms |
| t | Switch-over From Large Control Sensitivity to Small Control Sensitivity After Catching | | 20 | | ms |
| Control Loop II (Between Flyback Pulse and Oscillator) | | | | | |
| t _{d tot} | Permissible Delay Between Leading Edge of Output Pulse (Pin 2) and Leading Edge of Flyback Pulse | 0 | | 15 | μ s |
| $\frac{\Delta t}{\Delta t_d}$ | Static Control Error | (Note 3) | | 0.5 | % |
| Overall Phase Relation | | | | | |
| t | Phase Relation Between Leading Edge of Sync Pulse and Middle of Flyback Pulse | (Note 4) | 4.9 | | μ s |
| \Delta t | Tolerance of Phase Relation | (Note 5) | | 1 | μ s |
| $\frac{\Delta f}{f_0}$ | Spread of Frequency at Nominal Values of Peripheral Components | | | | |
| | TBA920 | | | ± 5 | % |
| | TBA920S | | | ± 2 | % |
| V3-16 | Voltage | t ₂ = 12 μ s | 6 | | V |
| V3-16 | | t ₁ = 32 μ s | 8 | | V |
| I ₃ | Input Current | | | 2 | μ A |
| V10-16 | Time Constant Switch Voltage on Pin 10 | For Internal R11 = 150 Ω | 4.5 | | V |
| V10-16 | | For Internal R11 = 2 k Ω | | 2 | V |

Note 1: The oscillator frequency can be changed for other TV standards by an appropriate value of C14-16.

Note 2: Adjustable with R12-15.

Note 3: The control error is the remaining error in reference to the nominal phase position between leading edge of the sync pulse and the middle of the flyback pulse caused by a variation in delay of the line output stage.

Note 4: This phase relation assumes a luminance delay line with a delay of 500 ns between the input of the sync separator and the drive to the picture tube. If the sync separator is inserted after the luminance delay line or if there is no delay line at all (black-and-white sets), then the phase relation is achieved by C5-16 = 560 pF.

Note 5: The adjustment of the overall phase relation and consequently the leading edge of the output pulse at pin 2 occurs automatically by the control loop II or by applying a dc voltage to pin 3.

TBA950-2 Television Signal Processing Circuit

General Description

The TBA950-2 is a monolithic integrated circuit for pulse separation and line synchronization in TV receivers with transistor output stages.

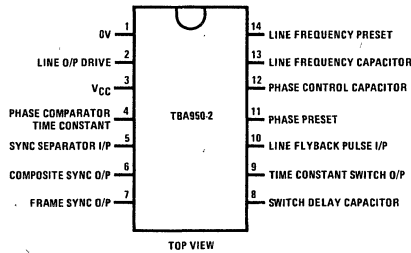
The TBA950 comprises the sync separator with noise suppression, the frame pulse integrator, the phase comparator, a switching stage for automatic changeover of

noise immunity, the line oscillator with frequency range limiter, a phase control circuit and the output stage.

It delivers prepared frame sync pulses for triggering the frame oscillator. The phase comparator may be switched for video recording operation. Due to the large scale of integration, few external components are needed.

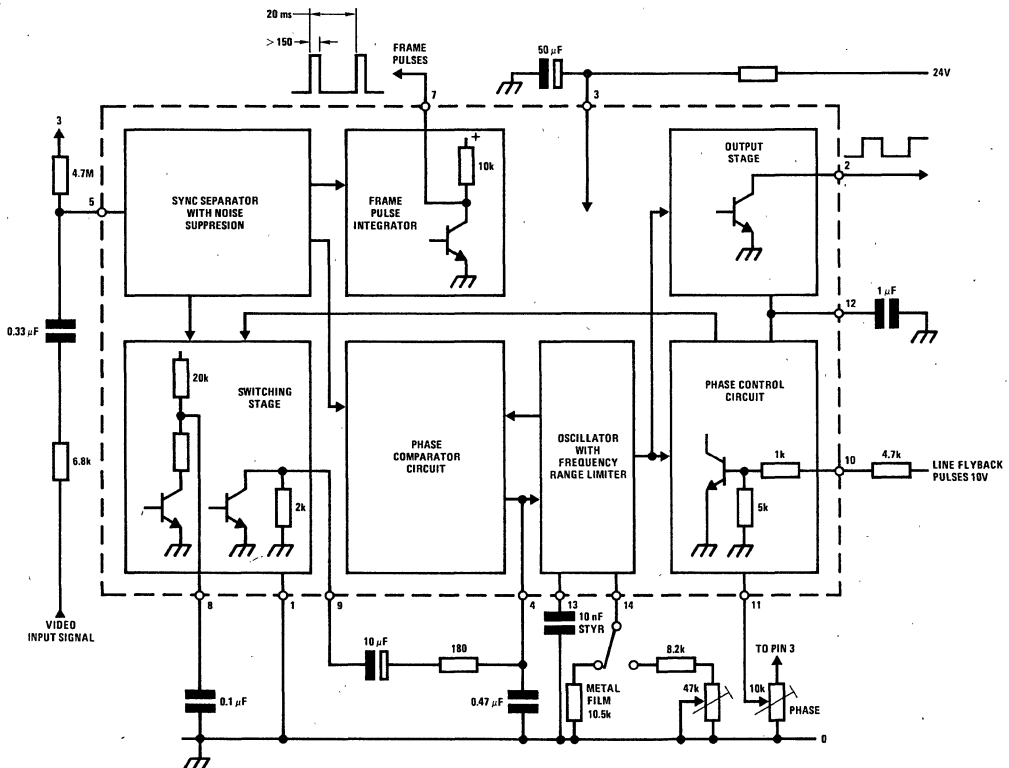
Connection and Block Diagrams

Dual-In-Line Package



Dual-In-Line Package, Order Number TBA950-2
See NS Package N14A

Quad-In-Line Package, Order Number TBA950-2Q
See NS Package N14C



Absolute Maximum Ratings

All voltages are referred to pin 1

| | |
|---|---------|
| I_3 , Supply Current (Figure 6) | 45 mA |
| I_5 , Input Current | 2 mA |
| V5, Input Voltage | -6V |
| I_2 , Output Current | 22 mA |
| V2, Output Voltage | 12V |
| I_8 , Switch-Over Current for Video Recording | 5 mA |
| I_{10} , Flyback Peak Pulse Current | 5 mA |
| V11, Phase Correction Voltage | 0 to V3 |
| T_A , Ambient Temperature | -60°C |

Recommended Operating Conditions

(For operating circuits Figures 4 and 5)

| | |
|--|-------------------|
| I_5 , Input Current During Sync Pulse | > 5 μ A |
| V_{IN} p-p, Composite Video Input Signal | 3 (1 to 6)V |
| I_{10} , Input Current During Line Flyback Pulse | 0.2 to 2 mA |
| I_8 , Switch-Over Current | > 2 mA |
| t_d , Time Difference Between the Output Pulse at Pin 2 and the Line Flyback Pulse at 10 | \leq 20 μ s |
| I_3 , Current Consumption (Figure 6) | \leq 45 mA |
| T_A , Ambient Operating Temperature Range | 0°C to +60°C |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $f_o = 15,625$ Hz in the test circuit Figure 2 (Note 1)

| SYMBOL | CHARACTERISTIC | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------|--|--|-------|-------|-------|--------------|
| V7 | Amplitude of the Frame Pulse | | | >8 | | V |
| t7 | Frame Pulse Durations | | | >150 | | μ s |
| R _{OUT 7} | Output Resistance at Pin 7 (High State) | | 7.5 | 10 | 13 | k Ω |
| t2 | Output Pulse Duration | Typical Ranges | 25 | | 28 | μ s |
| V2 Res | Residual Output Voltage | $I_2 = 20$ mA | | <0.55 | | V |
| f_o | Oscillator Frequency | C13/1 = 10 nF, R14/1 = 10.5 k Ω | 14063 | 15625 | 17187 | Hz |
| $\pm\Delta f_f$ | Frequency Pull-In Range | | 400 | | 1000 | Hz |
| $\pm\Delta f_H$ | Frequency Holding Range | Typical Ranges | 400 | | 1000 | Hz |
| df_o/dt_d | Slope of Phase Comparator Control Loop | | | 2 | | kHz/ μ s |
| dt_d/dt_p | Gain of Phase Control | | | 20 | | |
| t_p | Phase Shift Between Leading Edge of Composite Video Signal and Line Flyback Pulse (Note 2) Adjustable by V11 | Typical Range | 0 | | 3.5 | μ s |

Note 1: By modification of the frequency-determining network at pins 13 and 14, these ICs can also be used for other line frequencies.

Note 2: The limited flyback pulse should overlap the video signal sync pulse on both edges.

Functional Description

The sync separator separates the synchronizing pulses from the composite video signal. The noise inverter circuit, which needs no external components, in connection with an integrating and differentiating network frees the synchronizing signal from distortion and noise.

The frame sync pulse is obtained by multiple integration and limitation of the synchronizing signal, and is available at pin 7. The RC network, hitherto required between sync separator and frame oscillator is no longer needed. Since the frame sync pulse duration at pin 7 is subject to production spreads, it is recommended to use the leading edge of this pulse for triggering.

The frequency of the line oscillator is determined by a 10 nF polystyrene capacitor at pin 13 which is charged and discharged periodically by 2 internal current sources. The external resistor at pin 14 defines the charging current and consequently in conjunction with the oscillator capacitor the line frequency.

The phase comparator compares the sawtooth voltage of the oscillator with the line sync pulses. Simultaneously, an AFC voltage is generated which influences the oscillator frequency. A frequency range limiter restricts the frequency holding range.

The oscillator sawtooth voltage, which is in a fixed ratio to the line sync pulses, is compared with the flyback pulse in the phase control circuit, in this way compensating all drift of delay times in driver and line output stage. The correct phase position and hence the horizontal position of the picture can be adjusted by the 10 k Ω potentiometer connected to pin 11. Within the adjustable range the output pulse duration (pin 2) is constant. Any larger displacements of the picture, e.g., due to non-symmetrical picture tube, should not be corrected by the phase potentiometer, since in all cases the flyback pulse must overlap the sync pulse on both edges (Figure 3).

Functional Description (Continued)

The switching stage has an auxiliary function. When the 2 signals supplied by the sync separator and the phase control circuit, respectively, are in synchronism, a saturated transistor is in parallel with the integrated 2 kΩ resistor at pin 9. Thus the time constant of the filter network at pin 4 increases and consequently reduces the pull-in range of the phase comparator circuit for the synchronized state to approximately 50 Hz. This arrangement ensures disturbance-free operation.

For video recording operation, this automatic switchover can be blocked by a positive current fed into pin 8, e.g., via a resistor connected to pin 3. It may also be useful to connect a resistor of about 680 Ω or 1 kΩ between pin 9 and earth. The capacitor at pin 4 may be lowered, e.g., to 0.1 μF. These alterations do not significantly

influence the normal operation of the IC and thus do not need to be switched.

The output stage delivers at pin 2 output pulses of duration and polarity suitable for driving the line driver stage. If the supply voltage goes down (e.g., by switching off the mains) a built-in protection circuit ensures defined line frequency pulses down to V3 = 4V and shuts off when V3 falls below 4V, thus preventing pulses of undefined duration and frequency. Conversely, if the supply voltage rises, pulses defined in duration and frequency will appear at the output pin as soon as V3 reaches 4.5V. In the range between V3 = 4.5V and full supply the shape and frequency of the output pulses are practically constant.

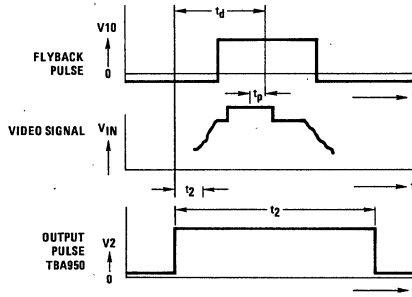
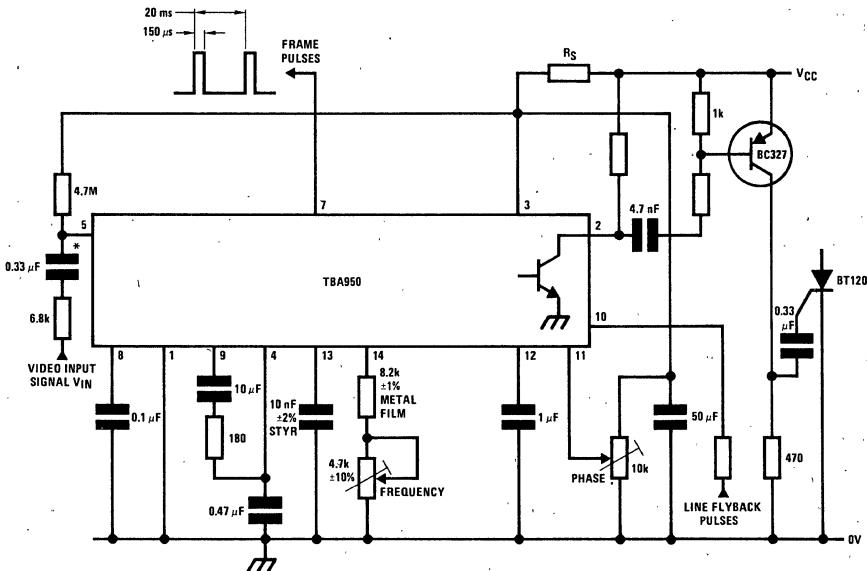


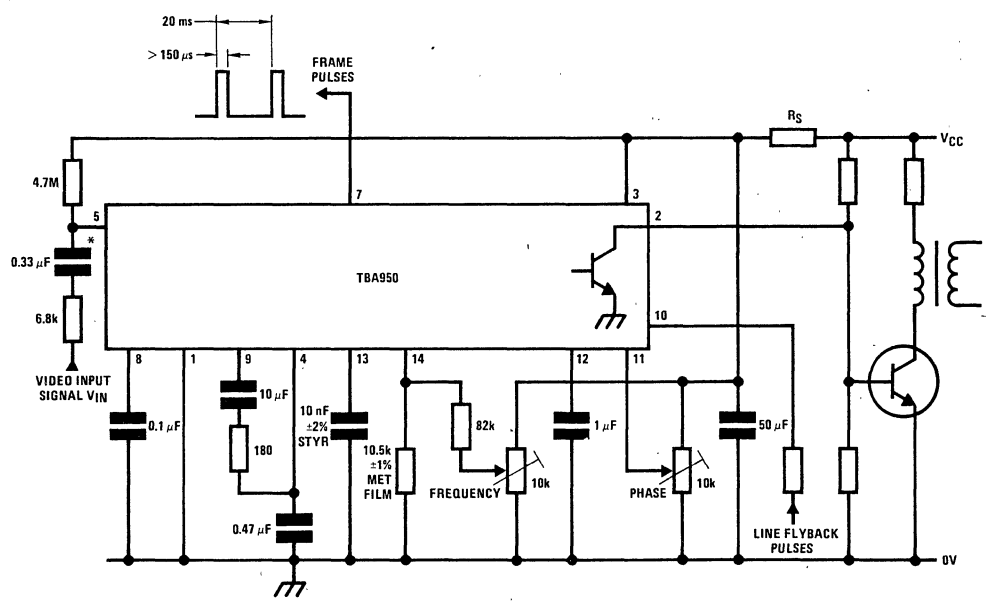
FIGURE 3. Phase Relationships



*Input circuitry must be optimized

FIGURE 4. Operating Circuit (Thyristor Output Stage)

Functional Description (Continued)



*Input circuitry must be optimized

FIGURE 5. Another Possibility for Line Frequency Adjustment (Transistor Output Stage)

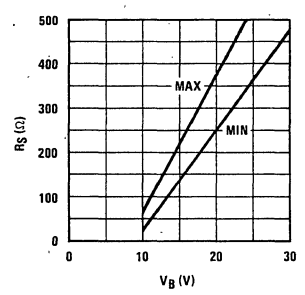


FIGURE 6. Graph for Determining the Supply Series Resistor, R_S

TBA970 Television Video Amplifier

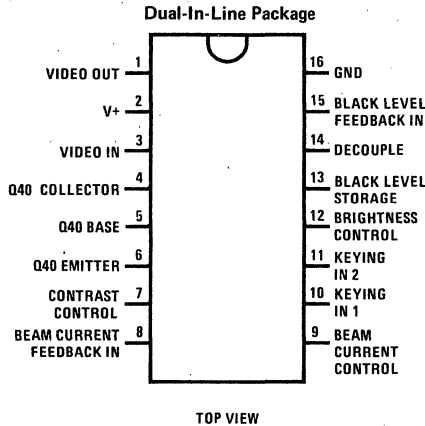
General Description

The TBA970 is a monolithic video amplifier for television receivers. The circuitry includes a video preamplifier, DC contrast control utilizing a linear potentiometer which can be ganged to the chroma gain control, beam current limiting via contrast. Beam current limiting could be obtained with either positive or negative control voltage. Black level control is achieved by a clamped feedback circuit combined with the brightness control. Emitter follower output could be used to directly drive the video output stage. A separate NPN transistor (Q40) is provided on the chip.

Features

- DC contrast control
- DC brightness control
- Black level clamping
- Beam current limiting
- Low impedance output

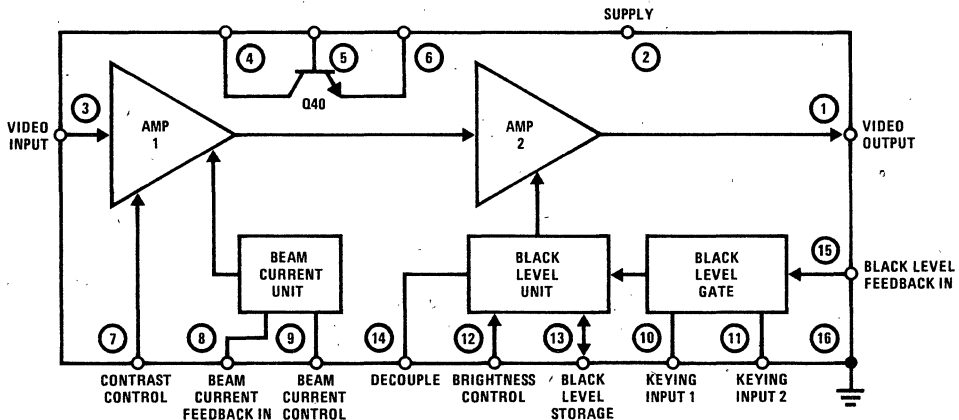
Connection Diagram



Dual-In-Line Package, Order Number TBA970
See NS Package N16A

Quad-In-Line Package, Order Number TBA970Q
See NS Package N16C

Block Diagram



Absolute Maximum Ratings

| | | | |
|----------------------------|--------|--|-----------------|
| Supply Voltage | 15.5V | V _{CE} Q40 | 15.5V |
| Internal Power Dissipation | 750 mW | Operating Temperature Range | -20°C to +45°C |
| Collector Current Q40 | 10 mA | Storage Temperature Range | -55°C to +125°C |
| Power Dissipation Q40 | 20 mW | Lead Temperature (Soldering, 10 seconds) | 260°C |
| V _{CE0} Q40 | 13.2V | | |

Electrical Characteristics $T_A = 25^\circ\text{C}$, $V^+ = 15\text{V}$, See Test Circuit, unless otherwise specified

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|---|--|-----|-----|-----|------------------|
| I ₂ | Supply Current | (Note 1) | | 27 | 36 | mA |
| V ₃ p-p | Peak-to-Peak Input Voltage | (Note 2) | | | 1.6 | V _{p-p} |
| R ₃ | Input Resistance | | | 12 | | kΩ |
| | Voltage Gain | | | 2.4 | | |
| | 3.0 dB Bandwidth | | | 6.0 | | MHz |
| | 6.0 dB Bandwidth | | | 9.0 | | MHz |
| | Linearity of Black-to-White Video Output Signal | | 0.9 | | | |
| V ₁₅ | Low Black Level Voltage | | | | 0.2 | V |
| V ₁₅ | High Black Level Voltage | | 3.0 | | | V |
| | Contrast Control Range | $1.5\text{V} \leq V_7 \leq 4.5\text{V}$ | 36 | | | dB |
| R ₁₂ | Input Resistance for Brightness Control | | | 200 | | kΩ |
| ΔV ₁₅ | Change of Black Level | (Note 3) | | | 20 | mV |
| V ₈ , V ₉ | DC Voltage for Beam Current Limiting Inputs | (Note 4) | | 2.0 | | V |
| | Separate Transistor Q40 Gain | I _C = I ₄ = 1.0 mA | 40 | | | |

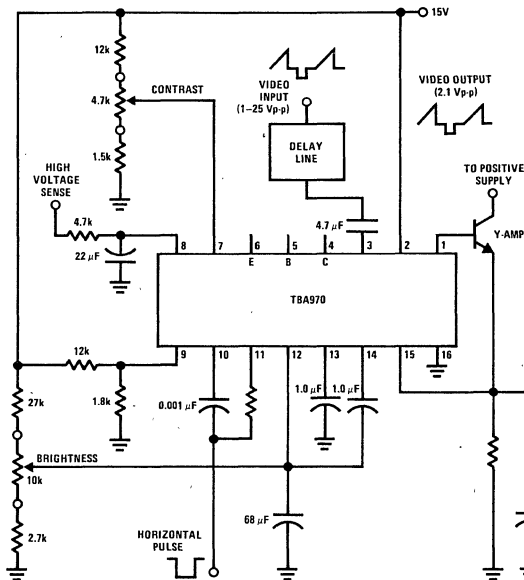
Note 1: No input signal and at minimum brightness.

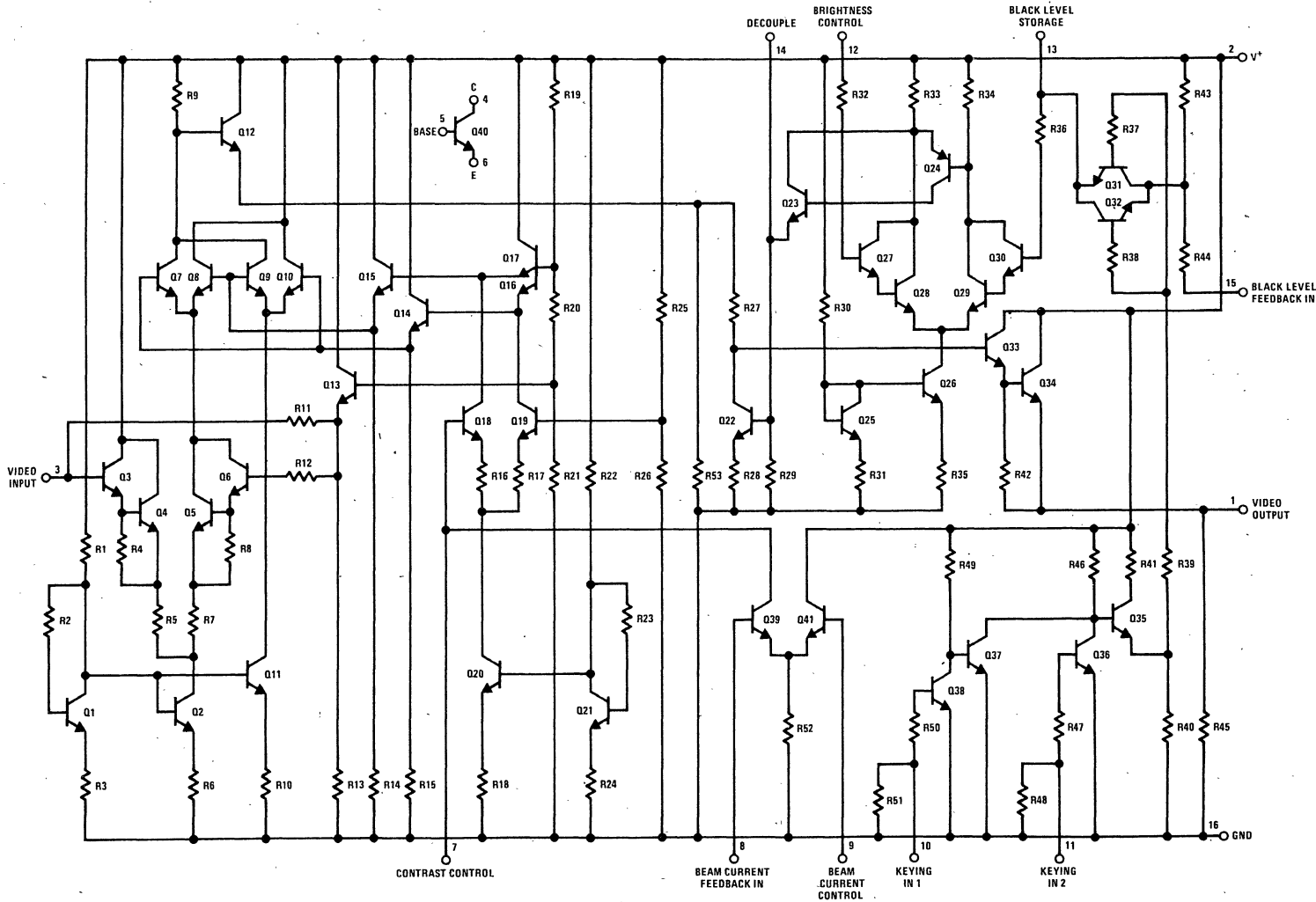
Note 2: With negative-going synchronizing pulse.

Note 3: With constant brightness setting, due to change of picture content, contrast control setting and change in ambient temperature ($\Delta T_A = 20^\circ\text{C}$); black level clamping with $t_c = 1 \mu\text{s}$, I₁₀ ≥ 0.25 mA, V₁₁ ≤ 0.3V.

Note 4: Beam current limiting occurs at V₈ ≥ V₉.

Test Circuit





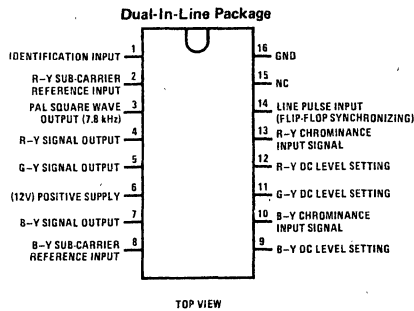
TBA990 Color Demodulator

General Description

The TBA990 is an integrated color demodulator circuit for color television receivers incorporating two active synchronous demodulators for the R-Y and B-Y chrominance signals, a matrix (producing the G-Y color difference signal), PAL phase switch and flip-flop. It is

suitable for dc coupled drive to the picture tube when associated with the matrix integrated circuit (TBA530) and R-G-B output stages. Special attention has been given in the design to minimizing dc level drift with temperature.

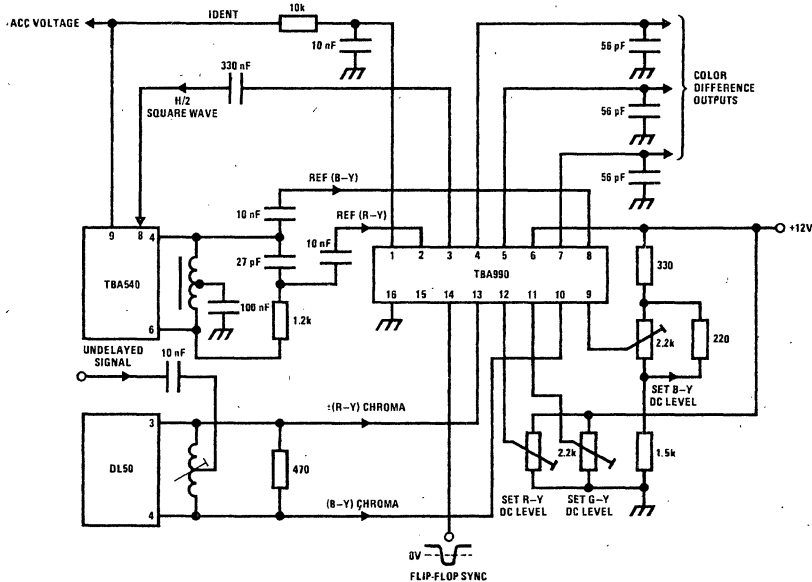
Connection Diagram



Dual-In-Line Package, Order Number TBA990
See NS Package N16A

Quad-In-Line Package, Order Number TBA990Q
See NS Package N16C

Typical Application



Pin Function Description

1. Identification bias. The PAL flip-flop is stopped, for identification purposes, when the voltage on pin 1 increases above 6V. This threshold is internally generated and has a proportional behavior with the 12V supply voltage. The threshold level of 6V is chosen to match the output characteristic of the TBA540 and has a sufficiently high safety margin above the zero chroma signal level of 4V to eliminate spurious identifying.

2. R-Y subcarrier reference input. A 1Vp-p signal is required via a dc blocking capacitor. Under no circumstances should this signal be less than 0.5 Vp-p. The input resistance at this pin is typically 5 k Ω .

3. PAL square wave output. The amplitude is 3Vp-p from an emitter follower. No external load resistor is required.

4. R-Y signal output (G-Y at pin 5 and B-Y at pin 7). These outputs require no external dc loads except that direct connection must be made via the low pass filters to the appropriate pins on the R-G-B matrix TBA530. In a complete circuit using the TBA530 and video output stages the dc levels of these outputs will be adjusted to give the correct setting of the picture tube drive black levels. The changes in dc level with supply voltage are proportional and track together.

The unwanted products of demodulation occurring in the color difference outputs are chiefly 8.86 MHz and harmonics together with a small amount of 4.43 MHz due to possible unbalance in the demodulators. To avoid possible troubles in the receiver because of radiation of these demodulation products from the R-G-B drive circuits, low-pass filters must be employed in each of the color difference outputs. The filters shown have a -3 dB bandwidth of 1 MHz, adequate attenuation of the 8.8 MHz component, and sufficient attenuation of the 4.4 MHz component to give less than 4 Vp-p amplitude at the picture tube cathodes.

5. G-Y signal output (see pin 4).

6. Positive supply. The maximum allowable voltage on this pin is 13.2V.

7. B-Y signal output (see pin 4).

8. B-Y subcarrier reference input. The requirements here are identical with those for pin 2.

9. DC level setting for B-Y output signal. This is a "common adjustment" which controls all three output dc levels together.

10. Chrominance B-Y input signal. An input signal of approximately 360 mVp-p (color bars) is required at this pin. The input resistance is greater than 800 Ω and the input capacitance is less than 10 pF. The spread in gain of the internal circuitry in the chrominance channel is $\pm 10\%$ maximum.

11. DC level setting for G-Y output signal. This adjusts the G-Y output dc level relative to the B-Y dc level.

12. DC level setting for R-Y output signal. This adjusts the R-Y output dc level relative to the B-Y dc level.

13. Chrominance R-Y input signal. An input signal of approximately 500 mVp-p (color bars) is required at this pin. The input impedance and spread in gain is the same as for pin 9.

14. Line pulse input (flip-flop synchronizing). A waveform derived from the line timebase can be used for synchronizing providing that its amplitude lies between 2V and 5Vp-p. The trigger point occurs where the negative-going edge crosses approximately +0.6V. Prior to this sufficient current must be supplied to pin 14 to turn the input transistor fully on.

15. N.C. This pin should not be used for external connections.

16. Negative supply (earth).

TDA440 Video IF Amplifier
General Description

The integrated circuit has the following functions incorporated: 3 symmetrical IF (broad band) amplifier with first and second regulated stages, controlled color carrier demodulator; video post-amplifier with low pass response and output independent of supply fluctuations; gated AGC section for the IF amplifier; delayed regulated output voltage for the tuner pre-stage.

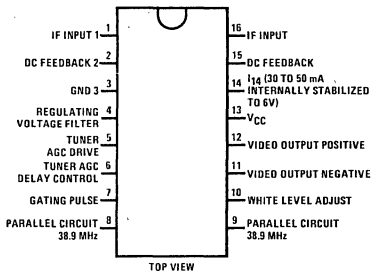
Features

- High gain — high stability
- Constant input impedance independent of AGC
- Poor noise increase due to AGC action
- Negative video signal hardly affected by supply voltage variations

- Minimum RF breakthrough to video outputs
- Fast AGC action — gating largely independent of pulse shape and amplitude
- Very low intermodulation products
- Minimum differential error
- Positive as well as negative video signal available from low impedance outputs
- Integrated temperature compensating circuit
- DC output component adjustable (peak white)

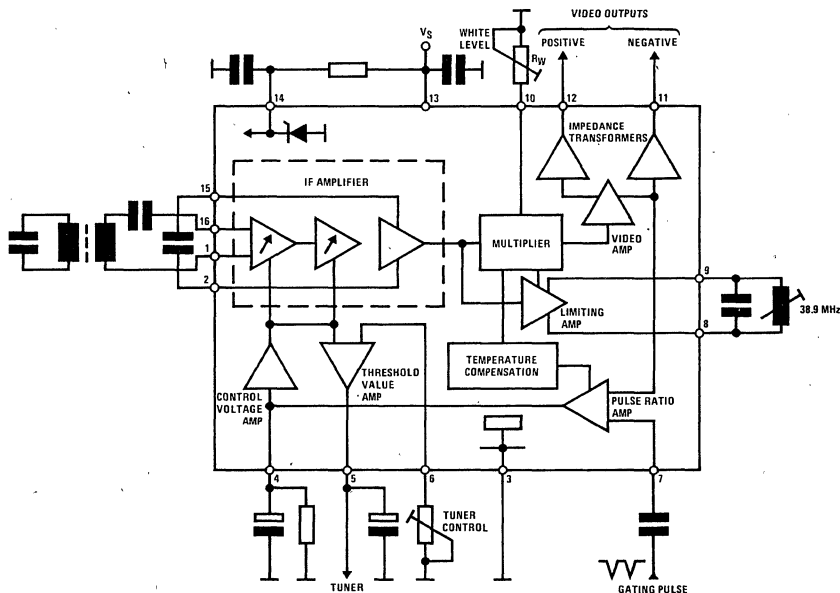
Applications

- Video IF amplifier for color and monochrome television receivers

Connection and Block Diagrams
Dual-In-Line Package


Dual-In-Line Package, Order Number TDA440
See NS Package N16A

Quad-In-Line Package, Order Number TDA440Q
See NS Package N16C



Absolute Maximum Ratings

| | | | |
|--|-----------|--|-----------------|
| V _S , Supply Voltage Range (Pin 13) | 10 to 15V | V _{EXT} , External Voltage (Pin 4) | 3.2V |
| I _S , Supply Current of Low Voltage Stabilizer (Pin 14) | 50 mA | Power Dissipation | |
| V _Q , Open Loop Voltage (Pin 5) | 15V | PTOT, T _A ≤ 55°C | 700 mW |
| Video DC Output Current | | T _J , Junction Temperature | 125°C |
| I _Q , Positive (Pin 12) | 5 mA | T _A , Ambient Temperature Range | -25°C to +70°C |
| I _Q , Positive (Pin 12) | 30 mA | t _{STG} , Storage Temperature Range | -25°C to +125°C |
| I _Q , Negative (Pin 11) | 5 mA | | |
| I _Q , Negative (Pin 11) | 30 mA | Thermal Resistance | |
| V _W , White Level Control (R _W) (Pin 10) | -1 to +3V | R _{thJA} , Junction Ambient | 100°C/W Max |

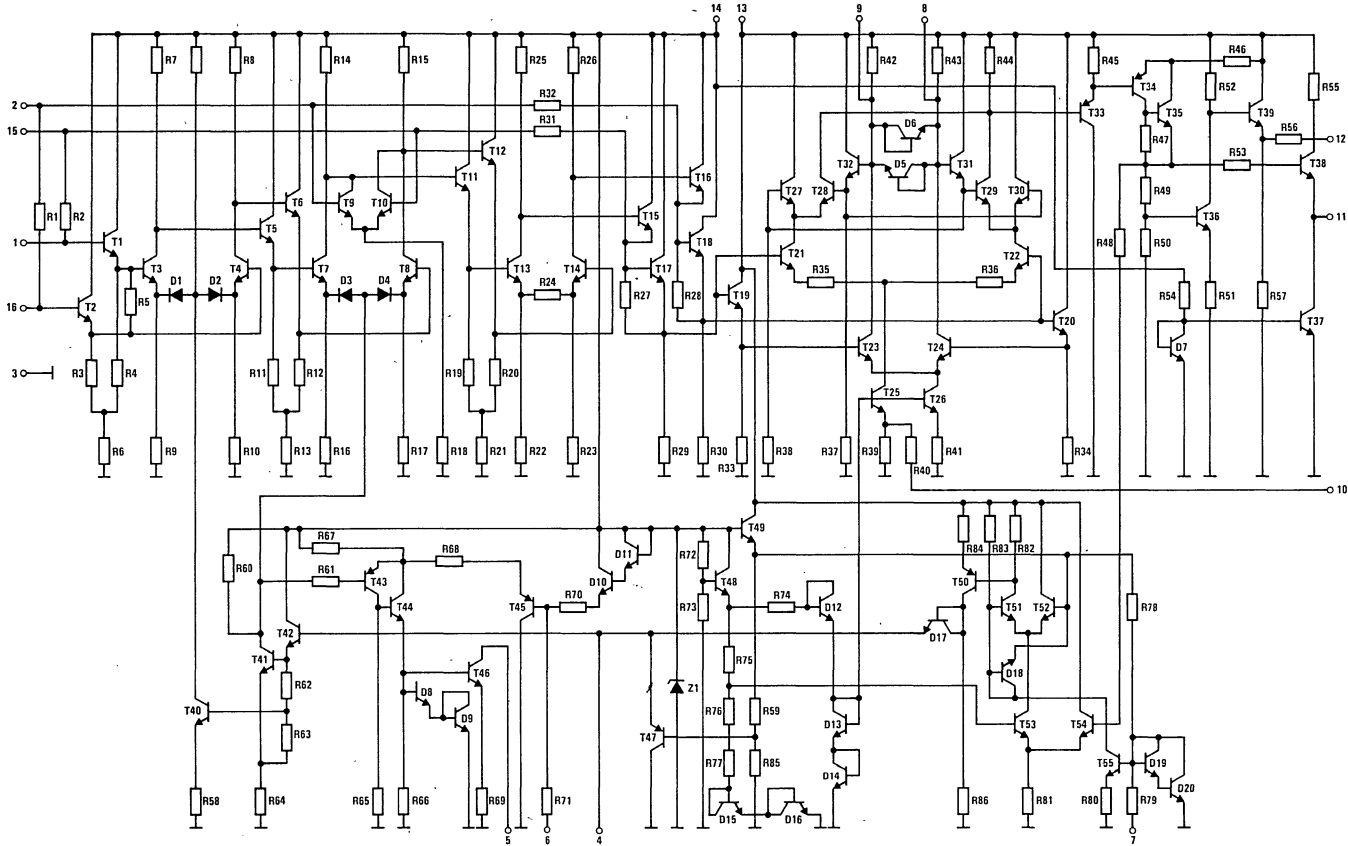
Electrical Characteristics

V_S = 12V, T_A = 25°C, Reference point pin 3 unless otherwise specified

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|---------------------|--|---|------|-----|-------|-----------------|
| V _S | Supply Voltage | Pin 13 | 10 | 12 | 15 | V |
| I _S | Supply Current | Pin 13 | 15 | 19 | 25 | mA |
| V _S | Supply Voltage | Pin 14, I _S = 40 mA | 5.5 | 5.8 | 6.4 | V |
| V _Q | Negative Video DC Output Voltage | Pin 11 | | 5.5 | | V |
| V _Q | With White Level Adjustable | Pins 10 and 11, R _W = ∞ | | | 4.8 | V |
| V _Q | Peak Black Clamping Level for Negative Video DC Output Voltage | R _W = 0 | 6.5 | | | V |
| V _Q | Peak Black Clamping Level for Negative Video DC Output Voltage | Pin 11 | 1.75 | 1.9 | 2.15 | V |
| I _Q | Output DC Current | | | | | |
| | Reference Point | Pins 11 and 13 | | 3.2 | | mA |
| V _Q | Positive Video DC Output Voltage | Pin 12 | | 5.6 | | V |
| I _Q | Available Tuner Control Current | Pin 5 | 3 | 4.5 | | mA |
| | 10 dB after Onset of Tuner Control Action (Note 1) | | | | | |
| V _i | Negative Gating Pulse | Pin 7 | 1.5 | 3 | 5 | V _{SS} |
| -v _q | Composite Video Output, Level | Pin 11 | | | | |
| | | V _Q = 5.5V | | 3.3 | | V _{SS} |
| | | V _Q = 6.4V | | 4.2 | | V _{SS} |
| ΔA _(IF) | AGC Range | | 50 | 56 | | dB |
| B _{VIDEO} | Video Bandwidth | Δv _{VIDEO} = -3 dB | 8 | 10 | | MHz |
| Δv _{VIDEO} | Video Frequency Response Change | ΔA _(IF) = 50 dB, B _{VIDEO} = 0-5 MHz | | 1.0 | 2.0 | dB |
| v _i | Symmetrical Input Voltage | Pins 1-16, -v _q = 3.3 V _{SS} (Pin 11) | 100 | 150 | 220 | μV |
| | Maximum IF Voltage Level Present at Video Outputs Over the Full AGC Range | Pins 11 and 12 | | | 30 | mV |
| | | f = 38.9 MHz | | | 50 | mV |
| | | f = 77.8 MHz (2. Harm) | | | | |
| | Sound IF Voltage Level Present at Video Outputs with Selective Circuit | Pin 12, f = 5.5 MHz, B _T /T _T = 30 dB | 30 | | | mV |
| d | Differential Gain of Negative Comp. Video Output Signal, for Full Black to White Swing | | | | 15 | % |
| ΔIM | Suppression of Sound Carrier/Color Subcarrier IP (1.07 MHz) with Respect to Color Subcarrier Level | | 40 | | | dB |
| | Picture Carrier | | | 0 | | dB |
| | IF Color Subcarrier Level | | | -6 | | dB |
| | IF Sound Carrier Level | | | -24 | | dB |
| | Input Impedance | | | | | |
| | Reference Point | Pin 16 | | | | |
| R _i | A _(IF) Max | Pin 1 | | 1.4 | | kΩ |
| C _i | | | | 2 | | pF |
| R _i | A _(IF) Min | Pin 1 | | 1.4 | | kΩ |
| C _i | | | | 1.9 | | pF |

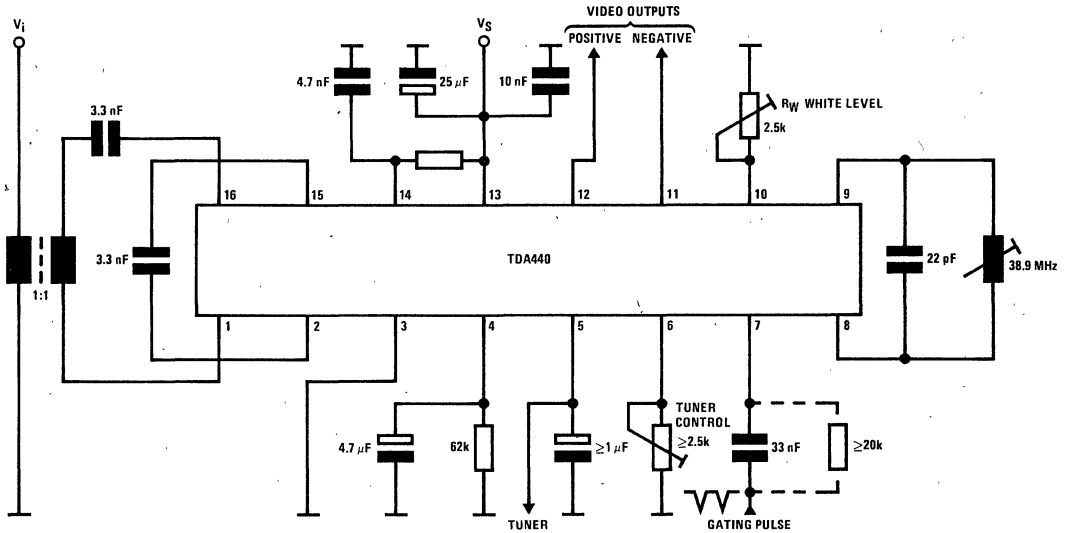
Note 1: On request ≥ 7 mA

Application Note for Reference Circuit to Improve
Audio Interference and Cross Color Characteristics



10-219

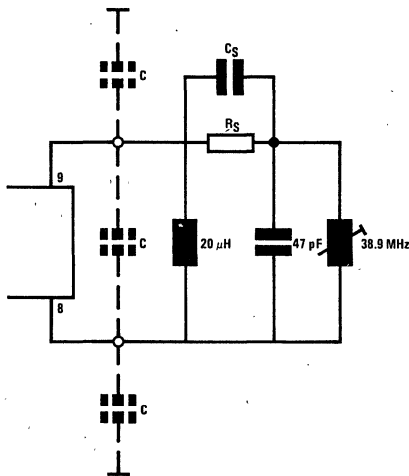
Test Circuit



Note. Supply voltage *must be disconnected* before inserting the integrated circuit in the socket.

Typical Application

Improved Tank Circuit to Reduce Audio Interference and Chroma Beat



- C = Parasitic capacitance at pins 8 and 9 should be kept minimum
- CS = 6–10 pF -- series capacitance
- $f_0 = 38.9 - (1.8 - 2.75)$ MHz -- series resonance frequency
- RS = 1.8–3.3 kΩ -- series resonance damping determine the tuning characteristics
- i.e., RS = 2.4 kΩ tuning range, f = 3 MHz

TDA2522 Color Demodulation Combination

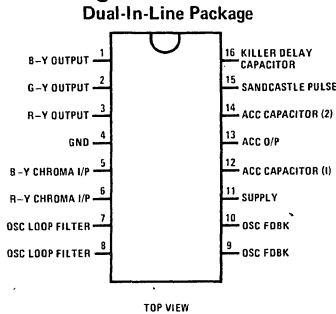
General Description

The TDA2522 is an integrated synchronous demodulator combination for color television receivers incorporating the following features.

Features

- 8.8 MHz oscillator followed by a divider giving two 4.4 MHz signals used as reference signals
- Keyed burst phase comparison for optimum noise behavior
- ACC detector and amplifier
- A color killer
- Two synchronous demodulators for the (B-Y) and (R-Y) signals
- Temperature compensated emitter follower outputs
- PAL switch and PAL flip-flop with internal identification
- Integrated capacitors in the symmetrical demodulators reduce unwanted carrier-signals at the outputs

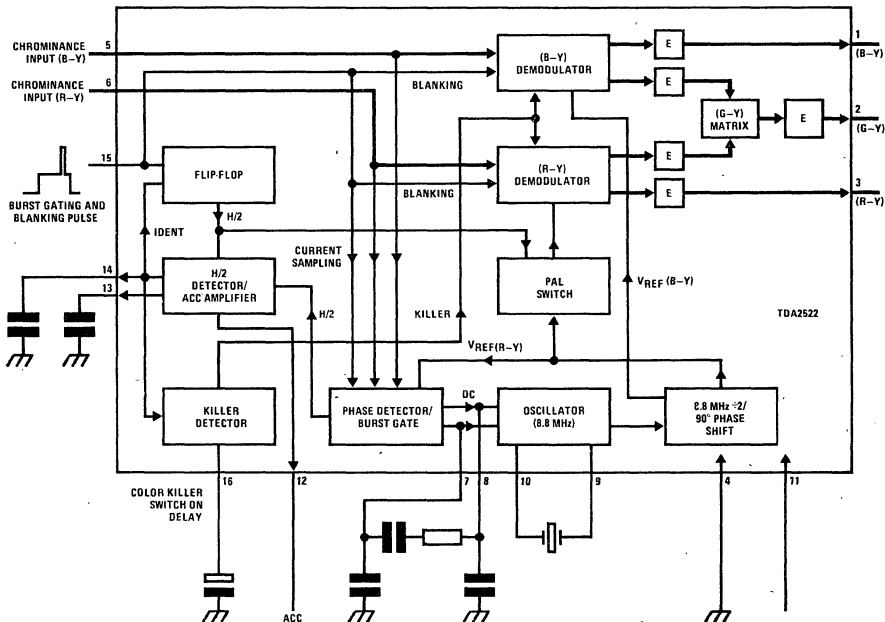
Connection Diagram



Dual-In-Line Package, Order Number TDA2522
See NS Package N16A

Quad-In-Line Package, Order Number TDA2522Q
See NS Package N16C

Block Diagram



Absolute Maximum Ratings

| | |
|---|-----------------|
| V11-4, Supply Voltage | 14V |
| P _{TOT} , Total Power Dissipation (Note 3) | 600 mW |
| T _{STG} , Storage Temperature | -20°C to +125°C |
| T _A , Operating Ambient Temperature | -20°C to +60°C |

Electrical Characteristics V11-4 = 12V, T_A = 25°C

| PARAMETER | MIN | TYP | MAX | UNITS |
|---|------|------|-----|-------|
| Supply Current | | 40 | | mA |
| Demodulator Section | | | | |
| Ratio of Demodulator Signals | | | | |
| B-Y/R-Y, $\frac{V1-4}{V3-4}$ | | 1.78 | | |
| G-Y/R-Y, $\frac{V2-4}{V3-4}$ (Note 1) | | 0.85 | | |
| G-Y/R-Y, $\frac{V2-4}{V3-4}$ (Note 2) | | 0.17 | | |
| Color Difference Output Signals, Peak-to-Peak Values | | | | |
| R-Y, V3-4 (p-p) | 2.40 | | | V |
| G-Y, V2-4 (p-p) | 1.35 | | | V |
| B-Y, V1-4 (p-p) | 3.00 | | | V |
| Impedance of Color Difference Signal Outputs | | | | |
| Z3-4 | | 250 | | Ω |
| Z2-4 | | 250 | | Ω |
| Z1-4 | | 250 | | Ω |
| H/2 Ripple at R-Y Output (Peak-to-Peak Value) | | | 10 | mV |
| V15-4 Burst Keying Pulse (Positive-Going) | 1.5 | | | V |
| Chrominance Input Signal (Including Burst) Peak-to-Peak Value | | | | |
| R-Y, V6-4 | | 500 | | mV |
| B-Y, V5-4 | | 350 | | mV |
| Reference Section | | | | |
| Phase Difference Between Reference Burst Signals for ±400 Hz Deviation of Crystal Frequency | -5 | | 5 | Deg. |
| Holding Range with Typical Crystal | | ±500 | | Hz |
| V13-4 ACC Reference Voltage | | 7 | | V |
| ACC Voltage with 0.5V Peak-to-Peak Burst At Correct Phase | | 5.5 | | V |
| V14-4 With Zero Burst | | 7.0 | | V |
| V12-4 ACC Amplifier Output with 0.5V Peak-to-Peak Burst of Correct Phase | | | 1.5 | V |
| R _{G-F} Oscillator Input Resistance | | 270 | | Ω |
| R _{H-F} Oscillator Output Resistance | | 200 | | Ω |

Note 1: The demodulators are driven by a chrominance signal of equal amplitude for the (R-Y) and the (B-Y) components. The phase of the (R-Y) chrominance signal equals the phase of the (R-Y) reference signal. The same holds for the (B-Y) signals.

Note 2: As under note 1, but the phase of the (R-Y) reference signal reversed.

Note 3: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

TDA2530, TDA2531 R-G-B Matrix Preamplifiers With Clamps

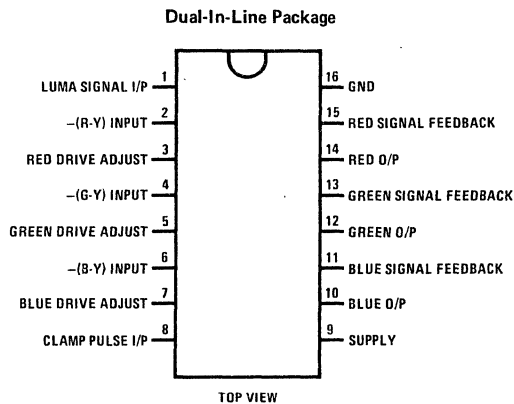
General Description

The TDA2530, TDA2531 are integrated R-G-B matrix preamplifiers for color television receivers, incorporating a matrix preamplifier for R-G-B cathode drive of the picture tube with clamping circuits. The TDA2531 has an emitter drive circuit while the TDA2530 has a base driver amplifier. Also, each channel follows an identical layout to ensure equal frequency behavior of the 3 channels.

This integrated circuit has been designed to be driven from the TDA2522 synchronous demodulator and oscillator integrated circuit.

The device is also available in a zig-zag quad-in-line package, this version being denoted by the suffix Q, i.e., TDA2530Q.

Connection Diagram



Dual-In-Line Package, Order Number TDA2530 or TDA2531
See NS Package N16A

Quad-In-Line Package, Order Number TDA2530Q or TDA2531Q
See NS Package N16C

Reference Data

| | |
|---|----------------|
| Supply Voltage (Nominal) | 12V |
| Operating Ambient Temperature Range | -25°C to +60°C |
| Gain of Luminance and Color-Difference Channels (Typical) | 100 |

Absolute Maximum Ratings

| | |
|---|-----------------|
| Supply Voltage (V8-6 Maximum) | 13.2V |
| Storage Temperature, T _{STG} | -25°C to +125°C |
| Operating Ambient Temperature, T _A | -25°C to +60°C |

Electrical Characteristics V8-6 = 12V, V1-16 = 1.5V, T_A = 25°C

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|------------|-----|-----|-----|-------|
| Gain of Color Channels (B-Y; G-Y; R-Y) at f = 0.5 MHz (Note 1) | G2-16 | | 100 | | |
| | G4-16 | | 100 | | |
| | G6-16 | | 100 | | |
| Ratio of Gain of Luminance Amplifier to Color Amplifiers | | 0.9 | | 1.1 | |
| Input Resistance of Color Difference Amplifiers at f = 1 kHz | R2-6 | 100 | | | kΩ |
| | R3-6 | 100 | | | kΩ |
| | R4-6 | 100 | | | kΩ |
| Input Resistance of Luminance Amplifier at f = 1 kHz | R5-6 | 100 | | | kΩ |

Note 1: G is defined as the voltage ratio between the input signals at the pins 2, 4 and 6 and the output signals at the collectors of the output transistors.

Pin Function Description

- Luminance signal input.** A 1V black to white positive-going luminance input signal is required. Blanking level should be at 1.5V and black level at 1.7V.
- (R-Y) input signal.** The input signal is required to be AC coupled from a low impedance source such as the TDA2522. The coupling capacitor also acts as a clamp capacitor for the TDA2530 red output. As the color difference input impedance is at least 100 kΩ, low value coupling capacitors may be used.
- Red drive adjustment.** A gain variation of the red channel of at least ±3 dB about the typical, is obtained as the DC potential at this pin is varied by ±5V about the typical of 5V. If no connection is made to a gain controlling pin the channel concerned assumes the typical gain.
- (G-Y) input signal (see pin 2).**
- Green drive adjustment (see pin 3).**
- (B-Y) input signal (see pin 2).**
- Blue drive adjustment (see pin 3).**
- Clamp pulse input.** A positive-going line pulse input is required and the pulse should exceed a threshold DC level set by the TDA2530 of 7V. An input current of about 1 mA is required.

9. Positive 12V supply.

10. Blue signal output. As far as video output stage drive is concerned, there are 2 possible drive modes from the output signal pins of the TDA2530. These are:

- Type A, output stage base drive, (TDA2530).
- Type B, output stage emitter drive, (TDA2531).

11. Blue signal feedback. The signal gain of both the video output stages and IC amplifier are stabilized by the feedback circuits. DC clamping is achieved by sampling of the feedback level during blanking. The black level potentials at the collectors of the video output stages may be varied independently by adjustable DC current sources applied to the feedback input pins. The DC levels at these pins are such that the feedback resistor and a resistor network between the 12V supply and earth provide a potential of 6V during blanking.

12. Green signal output (see pin 10).

13. Green signal feedback (see pin 11).

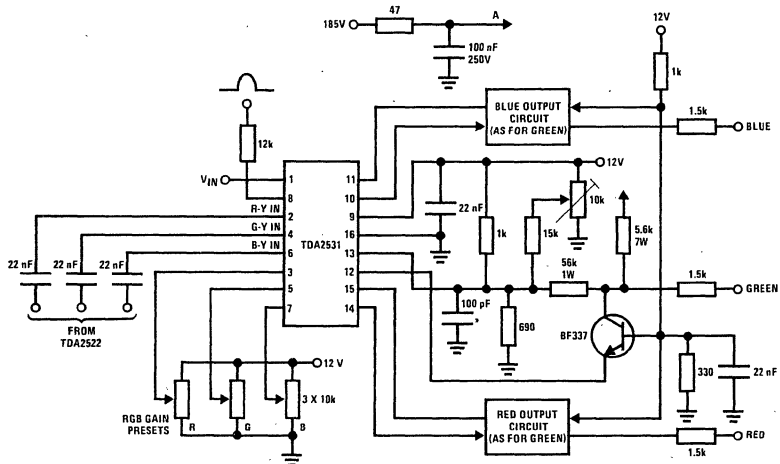
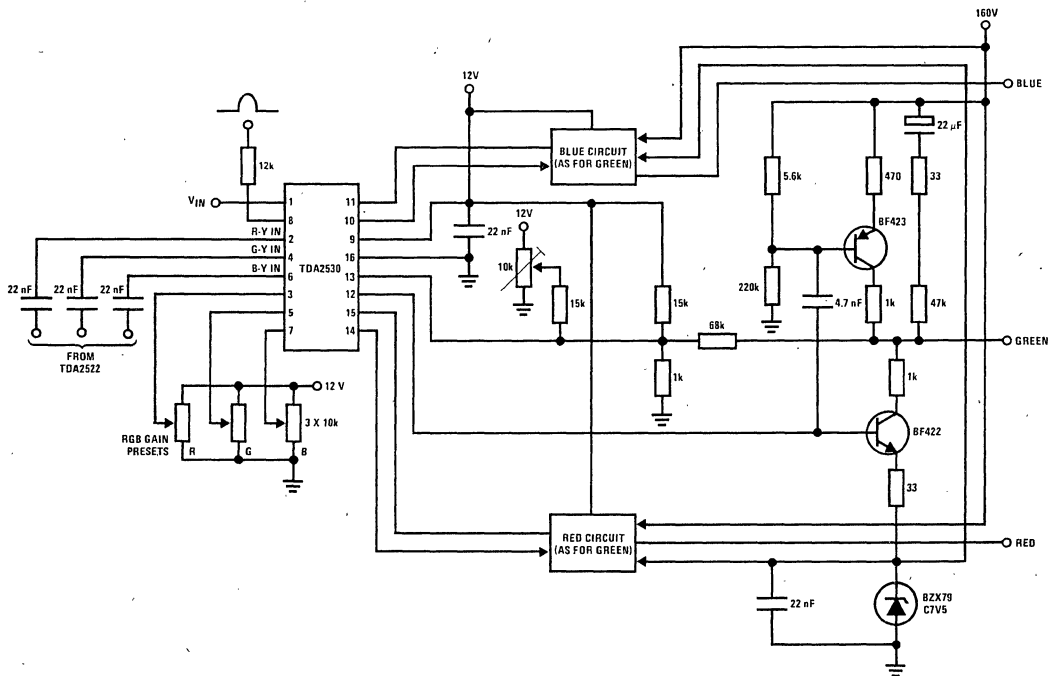
14. Red signal output (see pin 10).

15. Red signal feedback (see pin 11).

16. Negative supply (earth).

Application Information (Peripheral Circuitry)

TDA2530, TDA2531



Note 1: Attention should be given to earth paths, avoiding common impedances between the input (decoder) side and the output stages.

Note 2: Printed track area connected to the feedback pins should be kept to a minimum.

Note 3: To ensure a matched performance of the video output stages, a symmetrical layout of the 3 stages should be employed.

10

TDA2560 Luminance and Chrominance Control Combination

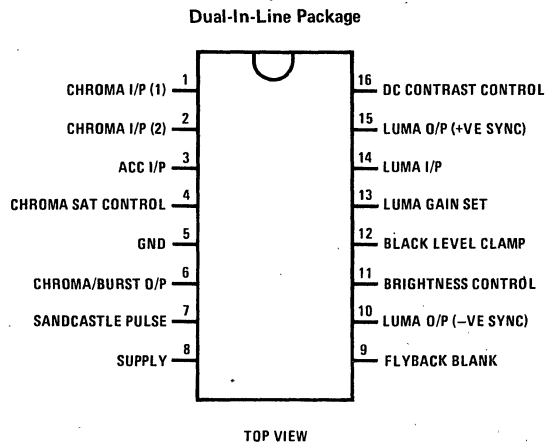
General Description

The TDA2560 is a monolithic integrated circuit for use in decoding systems of color television receivers. The circuit consists of a luminance and chrominance amplifier. The luminance amplifier has a low input impedance so that matching of the luminance delay line is very easy.

Features

- DC contrast control
 - Brightness control
 - Black level clamp
 - Blanking
 - Additional video output with positive-going sync
- The chrominance amplifier comprises:
- Gain controlled amplifier
 - Chrominance gain control tracked with contrast control
 - Separate DC saturation control
 - Combined chroma and burst output, burst signal amplitude not affected by contrast and saturation control
 - The delay line can directly be driven by the IC

Connection Diagram



Dual-In-Line Package, Order Number TDA2560
See NS Package N16A

Quad-In-Line Package, Order Number TDA2560Q
See NS Package N16C

Absolute Maximum Ratings

| | |
|--|-----------------|
| V _{B-5} , Supply Voltage | 14V |
| T _{STG} , Storage Temperature | -55°C to +125°C |
| T _A , Operating Ambient Temperature | -25°C to +70°C |

Electrical Characteristics

| PARAMETER | | MIN | TYP | MAX | UNITS |
|--|--|-----|-----|-----|-------|
| V _{B-5} | Supply Voltage Range | 9 | 12 | 14 | V |
| I _g | Supply Current | | 46 | | mA |
| V _{B-5} (p-p) | Allowable Hum on Supply Line (Peak-to-Peak Value) | | | 100 | mA |
| The following data are measured at V _B = 12V, T _A = 25°C | | | | | |
| Luminance Amplifier | | | | | |
| I _R (p-p) | Input Current; Black-to-White Level (Peak-to-Peak Value) | | 0.2 | | mA |
| Z | Input Impedance | | 75 | | Ω |
| Gain (Pin D), (Note 1) | | | | | |
| V ₆₋₅ | Burst Signal (Peak-to-Peak Value) | | | 6 | V |
| | Contrast Control Range | 20 | | | dB |
| V ₁₁ | Brightness Control Range (Black Level) | 1 | | 3 | V |
| | Black Level Stability When Changing Contrast, Video Contents and Temperature | | ±20 | | mV |
| B | Bandwidth (-3 dB) | | 5 | | MHz |
| V ₁₅₋₅ | Output Voltage (Additional; Positive-Going Sync) Peak-to-Peak Value | | 3.4 | | V |
| V ₇₋₅ | Black Level Clamp Pulse (Note 2) | | 6 | | V |
| | Blanking Pulse (Note 3) | | | | |
| V ₉ | At 0V at the Output | | 2 | | V |
| V ₉ | At 1.5V at the Output | | 5 | | V |
| Chrominance Amplifier | | | | | |
| V ₁₋₂ (p-p) | Input Signal Range (Peak-to-Peak Value) | 4 | | 80 | mV |
| V ₆₋₅ (p-p) | Obtainable Chrominance Output Signal (Note 4) Peak-to-Peak Value | | 2 | | |
| | Ratio of Burst and Chrominance at Nominal Contrast and Saturation, (Note 5) | | | | |
| V ₃₋₅ | ACC Starting Voltage (Note 6) | | 1.2 | | V |
| | ACC Range | 30 | | | dB |
| | Tracking with Contrast Control (10 dB Control) | -1 | | 1 | dB |
| | Saturation Control Range | 20 | | | dB |
| V ₇₋₅ | Burst Gate Pulse (Note 2) | | 1.5 | | V |
| S/N | Signal to Noise Ratio at Nominal Input Voltage | 50 | | | dB |
| | Phase of Burst to Chrominance | -5 | | 5 | Deg. |

Note 1: The gain of the luminance amplifier can be adjusted, by setting the gain of the contrast control circuit by selection of discrete resistor R_G (see also circuits on pages xx and xx). This circuit configuration has been chosen to reduce the spread of the gain to a minimum (main cause of spread is now the spread of the ratio of the delay line matching resistors and the resistor R_G). At R_G = 2.7 kΩ the output voltage at nominal contrast (maximum - 3 dB) is 3V black to white.

Note 2: This pin (7) is used for burst gate and black level clamping. The latter function is actuated at a 6V level. The input pulse must have such an amplitude that the clamping circuit is active only during the back porch of the blanking interval. The burst gate, which switches the gain of the chroma amplifier to maximum during the flyback time, is actuated at a 1.5V level.

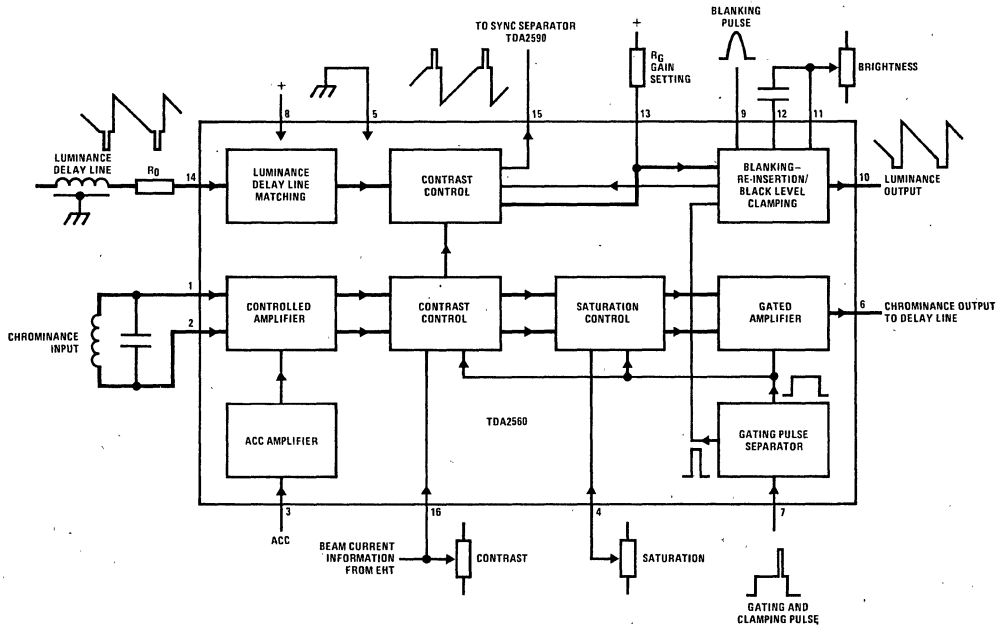
Note 3: This pin (9) is used for blanking the luminance amplifier. When the input pulse exceeds the 2V level the output signal is blanked to a level of about 0V. When the input exceeds a 5V level, a fixed level of about 1.5V is available at the output. This level can be used for clamping purposes.

Note 4: The chrominance and burst signal are both available on this pin (6). The burst signal is not affected by the contrast and saturation control and is kept constant by the ACC circuit of the TDA2522. The output signal amplitude is, therefore, determined by the losses in the delay line. At nominal contrast and saturation setting, the burst to chrominance ratio at the output is typically identical to the ratio at the input.

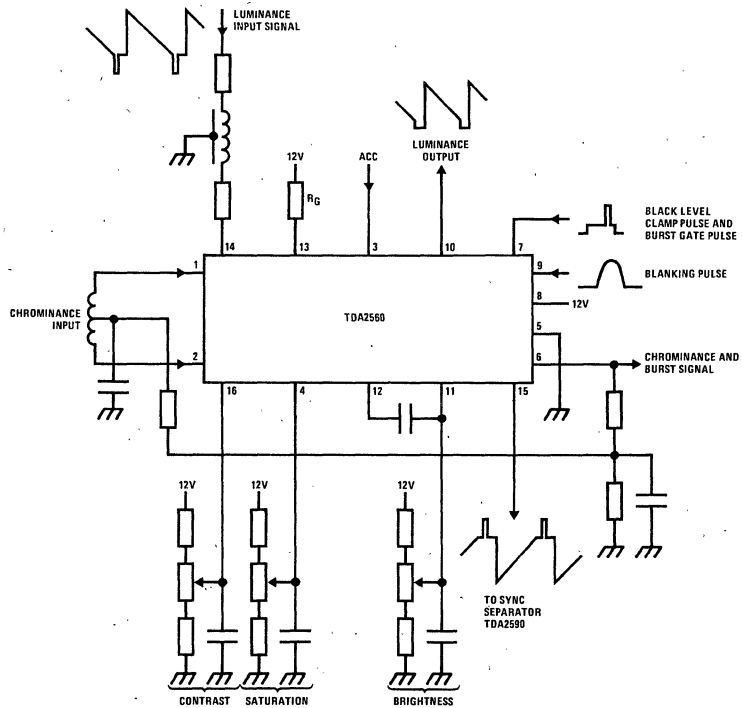
Note 5: Nominal contrast is specified as maximum contrast -3 dB. Nominal saturation is specified as maximum saturation -6 dB.

Note 6: A negative-going control voltage gives a decrease in gain.

Block Diagram



Application Information



TDA2590 Line Oscillator Combination

General Description

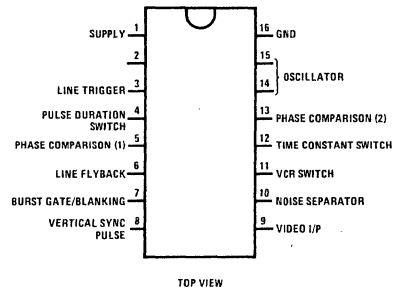
The TDA2590 is an integrated line oscillator circuit for color television receivers using thyristor or transistor line deflection output stages.

Features

- Line oscillator based on the threshold switching principle
- Phase comparison between sync pulse and oscillator voltage
- Phase comparison between line flyback pulse and oscillator voltage
- Switch for changing the filter characteristic and the gate circuit (when used for VCR)
- Coincidence detector
- Sync separator
- Noise separator
- Vertical sync separator
- Color burst keying and line flyback blanking pulse generator
- Phase shifter for the output pulse
- Output pulse duration switching
- Output stage for direct drive of thyristor deflection circuits

Connection Diagram

Dual-In-Line Package



Dual-In-Line Package, Order Number TDA2590
See NS Package N16A

Quad-In-Line Package, Order Number TDA2590Q
See NS Package N16C

Reference Data

| PARAMETERS | | MIN | TYP | MAX | UNITS |
|-----------------------|--|-----|------|------|-------|
| V1-16 | Supply Voltage | | 12 | | V |
| I_1 | Supply Current | | 30 | | mA |
| Input Signals | | | | | |
| V9-16 (p-p) | Sync Separator Input Voltage (Peak-to-Peak Value) | | 3 | | V |
| V10-16 (p-p) | Noise Separator Input Voltage (Peak-to-Peak Value) | | 3 | | V |
| | Pulse Duration Switch Input Voltage | | | | |
| V4-16 | $t = 6 \mu s$ | 8.2 | | 13.2 | V |
| V4-16 | $t = 24 \mu s + t_D$ | 0 | | 4.0 | V |
| V11-16 | Voltage for Switching on VCR | 9 | | 12 | V |
| | | 0 | | 1.5 | V |
| Output Signals | | | | | |
| V8-16 (p-p) | Vertical Sync Output Pulse (Peak-to-Peak Value) | | 11 | | V |
| V7-16 (p-p) | Burst Gating Output Pulse (Peak-to-Peak Value) | | 11 | | V |
| V3-16 (p-p) | Line Trigger Pulse (Peak-to-Peak Value) | | 10.5 | | V |

Absolute Maximum Ratings

Voltages

| | |
|--|------------|
| V1-16, Supply Voltage at Pin 1 (When Supplied by the IC) | 13.2V |
| V2-16, Supply Voltage at Pin 2 | 18V |
| V4-16, Pin 4 Voltage | 0 to 13.2V |
| V9-16, Pin 9 Voltage | -6 to +6V |
| V10-16, Pin 10 Voltage | -6 to +6V |
| V11-16, Pin 11 Voltage | 0 to 13.2V |

Currents

| | |
|--|--------|
| I _{2M} , Pin 2 Current (Peak Value) | 400 mA |
| I _{3M} , Pin 3 Current (Peak Value) | 400 mA |

| | |
|----------------------------------|-------|
| I ₄ , Pin 4 Current | 1 mA |
| ±I ₆ , Pin 6 Current | 10 mA |
| I ₇ , Pin 7 Current | 10 mA |
| I ₁₁ , Pin 11 Current | 2 mA |

Power Dissipation

| | |
|---|--------|
| P _{TOT} , Total Power Dissipation (Note 6) | 715 mW |
|---|--------|

Temperatures

| | |
|--|-----------------|
| T _{STG} , Storage Temperature | -20°C to +125°C |
| T _A , Operating Ambient Temperature | -20°C to +60°C |

Electrical Characteristics V1-16 = 12V; T_A = 25°C

| PARAMETER | | MIN | TYP | MAX | UNITS |
|---|--|------|------|------|-------|
| REQUIRED INPUT SIGNALS | | | | | |
| Sync Separator | | | | | |
| V9-16 | Input Switching Voltage | | 0.8 | | V |
| I _g | Input Switching Current | 5 | | 100 | μA |
| -I _g | Input Blocking Current at V9-16 = -5V | | <1 | | μA |
| Noise Separator | | | | | |
| V10-16 | Input Keying Voltage | | 1.0 | | V |
| V10-16 | Input Switching Voltage | | 1.4 | | V |
| I ₁₀ | Input Keying Current | 5 | | 100 | μA |
| I ₁₀ | Input Switching Current | | 150 | | μA |
| I ₁₀ | Input Blocking Current at V10-16 = -5V | | <1 | | μA |
| Line Flyback Pulse | | | | | |
| I ₆ | Input Current | | >10 | | μA |
| V6-16 | Input Switching Voltage | | 0.8 | | V |
| V6-16 | Input Limiting Voltage | -0.7 | | 1.4 | V |
| R6-16 | Input Resistance | | 0.4 | | kΩ |
| Pulse Duration Switch | | | | | |
| For t = 6 μs | | | | | |
| V4-16 | Input Voltage | 8.2 | | 13.2 | V |
| I ₄ | Input Current | | >200 | | μA |
| For t = 24 μs + t _d | | | | | |
| V4-16 | Input Voltage | 0 | | 4.0 | V |
| -I ₄ | Input Current | | >200 | | μA |
| For t = 0; V4-16 = 0 | | | | | |
| V4-16 | Input Voltage, (Note 1) | | 6.0 | | V |
| I ₄ | Input Current (Input Open) | | 0 | | μA |
| Switching on VCR | | | | | |
| V11-16 | Input Voltage, (Note 2) | 0 | | 1.5 | V |
| V11-16 | | 9 | | 13.2 | V |
| -I ₁₁ | Input Current, (Note 2) | | >200 | | μA |
| I ₁₁ | | 1 | | 2 | mA |
| DELIVERED OUTPUT SIGNALS | | | | | |
| Vertical Sync Pulse (Positive-Going) | | | | | |
| V8-16 (p-p) | Output Voltage (Peak-to-Peak Value) | 10 | 11 | | V |
| R8 | Output Resistance | | 5 | | kΩ |
| Burst Gating Pulse (Positive-Going) | | | | | |
| V7-16 | Output Voltage (Peak-to-Peak Value) | 10 | 11 | | V |
| R7 | Output Resistance | | 0.4 | | kΩ |

Electrical Characteristics (Continued)

| PARAMETER | | MIN | TYP | MAX | UNITS |
|---|---|-----|------|-----|-------|
| DELIVERED OUTPUT SIGNALS (CONTINUED) | | | | | |
| Blanking Pulse | | | | | |
| V7-16 (p-p) | Output Voltage (Peak-to-Peak Value) | | 3.0 | | V |
| R7 | Output Resistance | | 0.4 | | kΩ |
| Line Trigger Pulse (Positive-Going) | | | | | |
| V3-16 (p-p) | Output Voltage (Peak-to-Peak Value) | | 10.5 | | V |
| I3(AV) | Output Current (Average Value), (Note 3) | | | | mA |
| R3-16 | Output Resistance for Leading Edge of Line Pulse | | 2.5 | | Ω |
| R3-16 | Output Resistance for Trailing Edge of Line Pulse | | 20 | | Ω |
| Oscillator | | | | | |
| V14-16 | Threshold Voltage Low Level | | 4.4 | | V |
| V14-16 | Threshold Voltage High Level | | 7.6 | | V |
| ±I14 | Discharge Current | | 0.47 | | mA |
| V15-16 | Current Source Supply Voltage | | 6.0 | | V |
| -I15 | Current Source Supply Current | | 0.5 | | mA |
| Phase Comparison (φ1; Sync Pulse-Oscillator) | | | | | |
| V13-16 | Control Voltage Range | 3.8 | | 8.2 | V |
| ±I13M | Control Current (Peak Value) | 1.9 | 2.1 | 2.3 | mA |
| I13 | Output Blocking Current | | | | |
| | At V13-16 = 4-8V | | | 1 | μA |
| | Output Resistance | | | | |
| | At V13-16 = 4-8V, High Ohmic (Note 4) | | | | |
| | At V13-16 < 3.8V or > 8.2V, Low Ohmic, (Note 5) | | | | |
| Time Constant Switch | | | | | |
| V12-16 | Output Voltage | | 6 | | V |
| ±I12 | Output Current | | | 1 | mA |
| | Output Resistance | | | | |
| R12-16 | At V11-16 = 2.5 to 7V | | 0.1 | | kΩ |
| R12-16 | At V11-16 < 1.5V or > 9V | | 60 | | kΩ |
| Coincidence Detector (φ3) | | | | | |
| V11-16 | Output Voltage | 0.5 | | 6 | V |
| | Output Current (Peak Value) | | | | |
| I11M | Without Coincidence | | 0.1 | | mA |
| -I11M | With Coincidence | | 0.5 | | mA |
| Phase Comparison (φ2; Oscillator-Line Flyback Pulse) | | | | | |
| V5-16 | Control Voltage Range | 5.4 | | 7.6 | V |
| ±I5 | Control Current (Peak Value) | | 1 | | mA |
| | Output (Input) Resistance | | | | |
| | At V5-16 = 5.4 to 7.6V, High Ohmic, (Note 4) | | | | |
| R5-16 | At V5-16 < 5.4V or > 7.6V | | 8 | | kΩ |
| I5 | Input Current at Blocked Phase Detector | | | | |
| | V5-16 = 6.5V | | | 5 | μA |

Note 1: Can also be not connected.

Note 2: When supplied by the IC.

Note 3: Higher values are allowed when reducing P_{tot}.

Note 4: Current source.

Note 5: Emitter follower.

Note 6: For operation in ambient temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W junction to ambient.

Applications Information

| PARAMETER | | MIN | TYP | MAX | UNITS |
|--|--|-----------------|--------|-----|--------|
| Sync Separator | | | | | |
| V9-16 (p-p) | Input Voltage (Without Video; Peak-to-Peak Value) | 1 | 3 | 7 | V |
| I _g | Input Keying Control | | | 100 | μA |
| Noise Signal Keying | | | | | |
| V10-16 (p-p) | Input Voltage (Without Video; Peak-to-Peak Value) | 1 | 3 | 7 | V |
| I ₁₀ | Input Keying Current | | | 100 | μA |
| V _n (p-p) | Superimposed Noise Voltage (Peak-to-Peak Value) | | | 7 | V |
| Vertical Sync Pulse Separator | | | | | |
| t _{ON} | Delay Between Leading Edge of Input and Output Signal | | 12 | | μs |
| t _{OFF} | Delay Between Trailing Edge of Input and Output Signal | t _{ON} | | | μs |
| V8-16 (p-p) | Output Voltage (Peak-to-Peak Value) | | 11 | | V |
| R8-16 | Output Resistance | | 5 | | kΩ |
| Oscillator | | | | | |
| f _o | Frequency; Free Running (C14-6 = 4.7 nF, R15-16 = 12 kΩ) | | 15.625 | | kHz |
| Δf _o /f _o | Spread of Frequency, (Note 1) | | <±5 | | % |
| Δf _o /ΔI ₁₅ | Frequency Control Sensitivity | | 31 | | Hz/μA |
| Δf _o /f _o | Adjustment Range of Network in <i>Figure 1</i> | | ±10 | | % |
| $\frac{\Delta f_o/f_o}{\Delta V/V_{TYP}}$ | Influence of Supply Voltage on Frequency at V1-16 = 12V, (Note 1) | | | 5 | % |
| Δf _o | Change of Frequency when V1-16 Drops to 4V | | | 10 | % |
| Phase Comparison (φ₁; Sync Pulse-Oscillator) | | | | | |
| | Control Sensitivity | | 2 | | kHz/μs |
| | Spread of Control Sensitivity, (Note 1) | | ±10 | | % |
| Δf | Catching and Holding Range (82 kΩ) | | ±780 | | Hz |
| Δf/f | Spread of Catching and Holding Range, (Note 1) | | ±10 | | % |
| Phase Comparison (φ₂; Oscillator-Line Flyback Pulse) | | | | | |
| t _d | Permissible Delay Between Leading Edge of Output Pulse and Leading Edge of Flyback Pulse | 15 | | | μs |
| Δt/Δt _d | Static Control Error | | <0.2 | | % |
| Overall Phase Relation | | | | | |
| t | Phase Relation Between Middle of Sync Pulse and the Middle of the Flyback Pulse | | 2.6 | | μs |
| Δt | Tolerance of Phase Relation | | | 0.7 | μs |
| Adjustment Sensitivity, Caused By: (Note 2) | | | | | |
| ΔV5-16/Δt | Adjustment Voltage | | 0.1 | | V/μs |
| ΔI5/Δt | Adjustment Current | | 30 | | μA/μs |
| | Spread of Adjustment Current, (Note 1) | | <10 | | % |
| Burst Gating Pulse | | | | | |
| t | Phase Relation Between Middle of Sync Pulse at the Input and the Trailing Edge of the Burst Gating Pulse; V7-16 = 7V | 5.8 | 6.75 | 7.7 | μs |
| t7 | Burst Gating Pulse Duration | | 5 | | μs |

Applications Information (Continued)

| PARAMETER | | MIN | TYP | MAX | UNITS |
|------------------------------|---|-----|----------|-----|---------|
| Line Trigger Pulse | | | | | |
| t_p | Output Pulse Duration | 4.5 | 6 | 7.5 | μs |
| | At $V_{4-16} > 8.2V$ | | | | |
| t_p | At $V_{4-16} < 4V$ | | $24+t_d$ | | μs |
| V_{1-16} | Supply Voltage for Switching Off the Output Pulse | | 4 | | V |
| Internal Gating Pulse | | | | | |
| t_p | Pulse Duration | | 7.5 | | μs |
| t | Time Between Leading Edge of the Gating Pulse and the Middle of the Sync Pulse | | >2.75 | | μs |
| | | | 3.75 | | μs |
| t | Time Between Trailing Edge of the Gating Pulse and the Middle of the Sync Pulse | | >2.75 | | μs |
| | | | 3.75 | | μs |

Note 1: Exclusive external components tolerances.

Note 2: The adjustment of the overall phase relation and consequently the leading edge of the output pulse occurs automatically by phase control ϕ_2 . The values beyond this point count if additional adjustment is required.

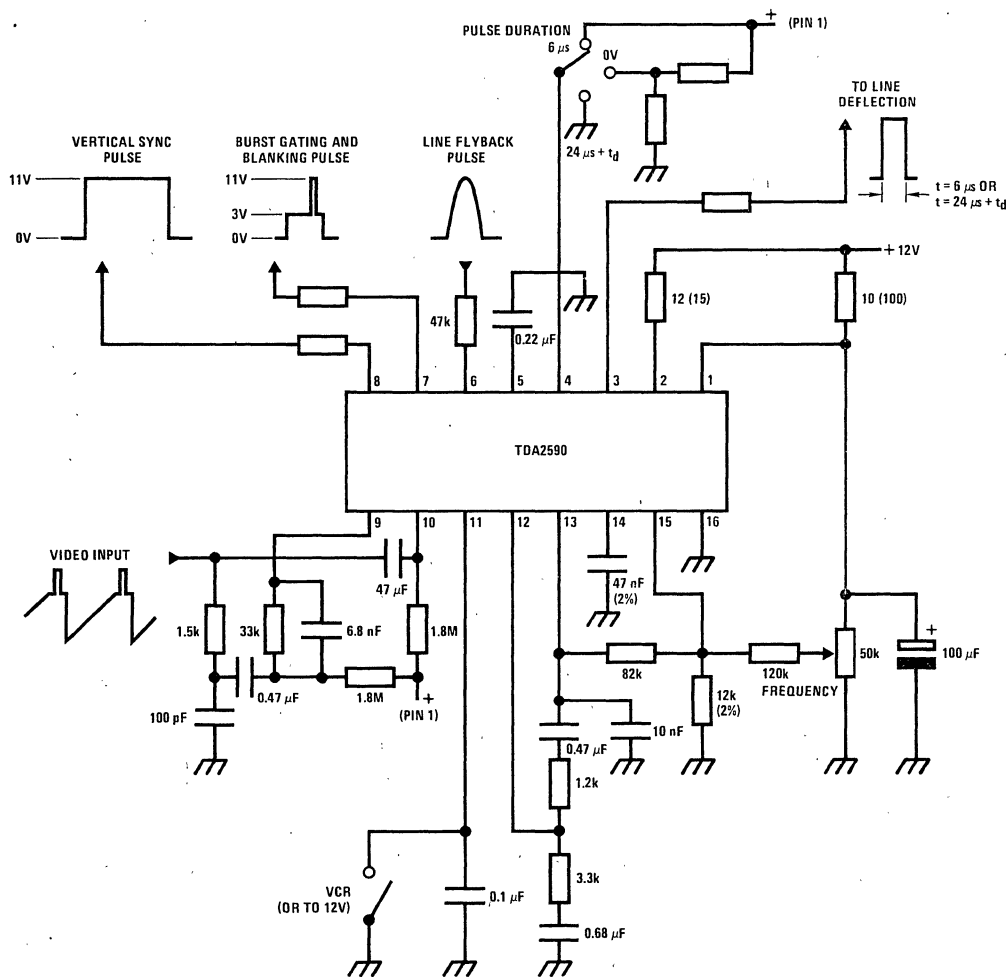
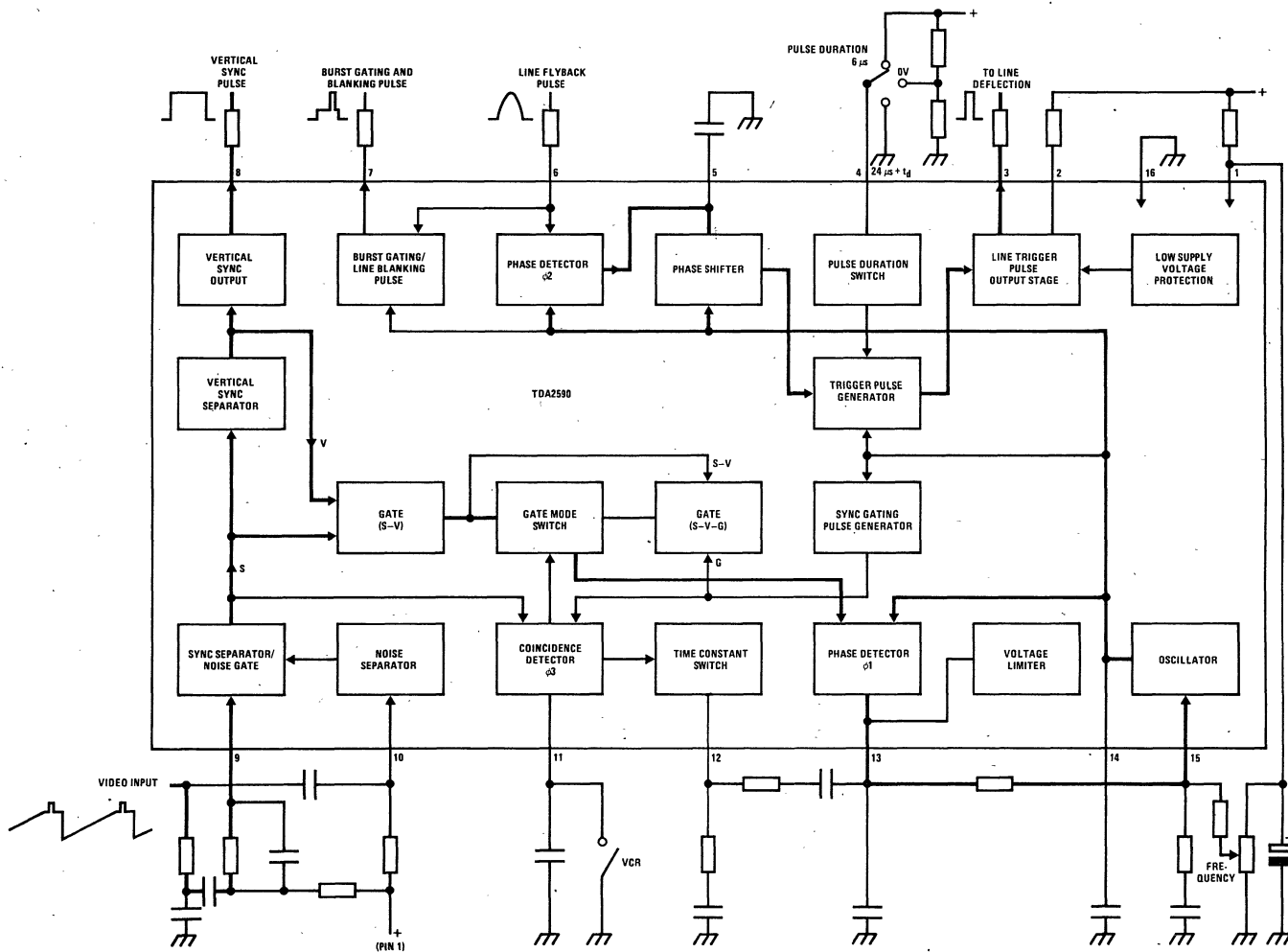


FIGURE 1





Section 11
**Transistor/
Diode Arrays**



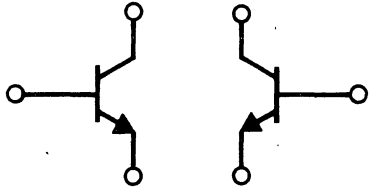


Section Contents

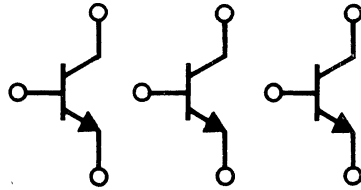
| | |
|---|--------|
| Transistor/Diode Arrays Selection Guide..... | 11-iii |
| LM194/LM394 Supermatch Pair..... | 11-1 |
| LM195/LM295/LM395 Ultra Reliable Power Transistors..... | 11-7 |
| LM3045, LM3046, LM3086 Transistor Arrays..... | 11-15 |
| LM3146 High Voltage Transistor Array..... | 11-20 |

Transistor/Diode Arrays

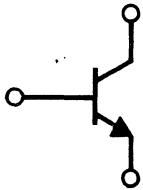
Selection Guide



LM194/LM394



LM3045
LM3046
LM3086
LM3146



LM195/LM295/LM395
(Current Limit, Thermal Limit,
Safe Area Protection)

LM194/LM394 Supermatch Pair

General Description

The LM194 and LM394 are junction isolated ultra well-matched monolithic NPN transistor pairs with an order of magnitude improvement in matching over conventional transistor pairs. This was accomplished by advanced linear processing and a unique new device structure.

Electrical characteristics of these devices such as drift versus initial offset voltage, noise, and the exponential relationship of base-emitter voltage to collector current closely approach those of a theoretical transistor. Extrinsic emitter and base resistances are much lower than presently available pairs, either monolithic or discrete, giving extremely low noise and theoretical operation over a wide current range. Most parameters are guaranteed over a current range of $1\mu\text{A}$ to 1mA and 0V up to 40V collector-base voltage, ensuring superior performance in nearly all applications.

To guarantee long term stability of matching parameters, internal clamp diodes have been added across the emitter-base junction of each transistor. These prevent degradation due to reverse biased emitter current—the most common cause of field failures in matched devices. The parasitic isolation junction formed by the diodes also clamps the substrate region to the most negative emitter to ensure complete isolation between devices.

The LM194 and LM394 will provide a considerable improvement in performance in most applications requiring a closely matched transistor pair. In many cases, trimming can be eliminated entirely, improving reliability and decreasing costs. Additionally, the low noise and high gain make this device attractive even where matching is not critical.

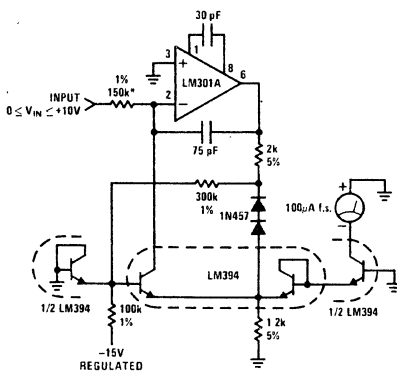
The LM194 and LM394/LM394B/LM394C are available in an isolated header 6-lead TO-5 metal can package. The LM194 is identical to the LM394 except for tighter electrical specifications and wider temperature range.

Features

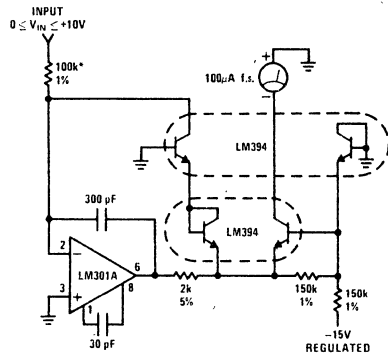
- Emitter-base voltage matched to $50\mu\text{V}$
- Offset voltage drift less than $0.1\mu\text{V}/^\circ\text{C}$
- Current gain (h_{FE}) matched to 2%
- Common-mode rejection ratio greater than 120 dB
- Parameters guaranteed over $1\mu\text{A}$ to 1mA collector current
- Extremely low noise
- Superior logging characteristics compared to conventional pairs
- Plug-in replacement for presently available devices

Typical Applications

Low Cost Accurate Square Root Circuit
 $I_{OUT} = 10^{-5} \cdot \sqrt{10 V_{IN}}$



Low Cost Accurate Squaring Circuit
 $I_{OUT} = 10^{-6} (V_{IN})^2$



*Trim for full scale accuracy

Absolute Maximum Ratings

| | | | |
|-----------------------------|------------------|--|-----------------|
| Collector Current | 20 mA | Collector-Collector Voltage | 40V |
| Collector-Emitter Voltage | V _{MAX} | LM394C | 20V |
| Collector-Emitter Voltage | 40V | Base-Emitter Current | ±10 mA |
| LM394C | 20V | Power Dissipation | 500 mW |
| Collector-Base Voltage | 40V | Junction Temperature | |
| LM394C | 20V | LM194 | -55°C to +125°C |
| Collector-Substrate Voltage | 40V | LM394/LM394B/LM394C | -25°C to +85°C |
| LM394C | 20V | Storage Temperature Range | -65°C to +150°C |
| | | Lead Temperature (Soldering, 10 seconds) | 300°C |

Electrical Characteristics (T_J = 25°C)

| PARAMETER | CONDITIONS | LM194 | | | LM394 | | | LM394B/LM394C | | | UNITS |
|--|---|-------|------|------|-------|------|-----|---------------|------|-----|--------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| Current Gain (h _{FE}) | V _{CB} = 0V to V _{MAX} (Note 1) | | | | | | | | | | |
| | I _C = 1 mA | 500 | 700 | | 300 | 700 | | 225 | .500 | | |
| | I _C = 100μA | 400 | 550 | | 250 | 550 | | 200 | 400 | | |
| | I _C = 10μA | 300 | 450 | | 200 | 450 | | 150 | 300 | | |
| | I _C = 1μA | 200 | 300 | | 150 | 300 | | 100 | 200 | | |
| Current Gain Match (h _{FE} Match) = $\frac{100 [\Delta I_B] [h_{FE(MIN)}]}{I_C}$ | V _{CB} = 0V to V _{MAX} | | 0.5 | 2 | | 0.5 | 4 | | 1.0 | 5 | % |
| | I _C = 10μA to 1 mA | | 1.0 | | | 1.0 | | | 2.0 | | % |
| | I _C = 1μA | | 25 | 50 | | 25 | 150 | | 50 | 200 | μV |
| Emitter-Base Offset Voltage | V _{CB} = 0 | | | | | | | | | | |
| | I _C = 1μA to 1 mA | | | | | | | | | | |
| Change in Emitter-Base Offset Voltage vs Collector-Base Voltage (CMRR) | (Note 1) | | 10 | 25 | | 10 | 50 | | 10 | 100 | μV |
| Change in Emitter-Base Offset Voltage vs Collector Current | I _C = 1μA to 1 mA, V _{CB} = 0V to V _{MAX} | | | | | | | | | | |
| Emitter-Base Offset Voltage Temperature Drift | V _{CB} = 0V, I _C = 1μA to 0.3 mA | | 5 | 25 | | 5 | 50 | | 5 | 50 | μV |
| Logging Conformity | I _C = 10μA to 1 mA (Note 2) | | 0.08 | 0.3 | | 0.08 | 1.0 | | 0.2 | 1.5 | μV/°C |
| | I _{C1} = I _{C2} | | 0.03 | 0.1 | | 0.03 | 0.3 | | 0.03 | 0.5 | μV/°C |
| | V _{OS} Trimmed to 0 at 25°C | | 150 | | | 150 | | | 150 | | μV |
| Collector-Base Leakage | I _C = 3 nA to 300μA, V _{CB} = 0, (Note 3) | | 0.05 | 0.25 | | 0.05 | 0.5 | | 0.05 | 0.5 | nA |
| Collector-Collector Leakage | V _{CB} = V _{MAX} | | 0.1 | 2.0 | | 0.1 | 5.0 | | 0.1 | 5.0 | nA |
| Input Voltage Noise | I _C = 100μA, V _{CB} = 0V, f = 100 Hz to 100 kHz | | 1.8 | | | 1.8 | | | 1.8 | | nV/√Hz |
| Collector to Emitter Saturation Voltage | I _C = 1 mA, I _B = 10μA | | 0.2 | | | 0.2 | | | 0.2 | | V |
| | I _C = 1 mA, I _B = 100μA | | 0.1 | | | 0.1 | | | 0.1 | | V |

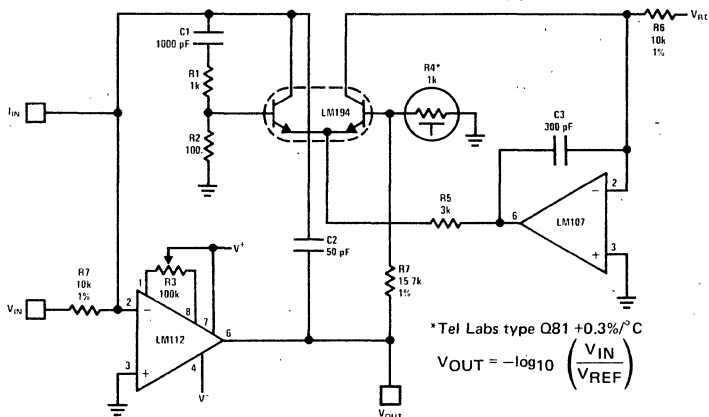
Note 1: Collector-base voltage is swept from 0 to V_{MAX} at a collector current of 1μA, 10μA, 100μA, and 1 mA.

Note 2: Offset voltage drift with V_{OS} = 0 at T_A = 25°C is valid only when the ratio of I_{C1} to I_{C2} is adjusted to give the initial zero offset. This ratio must be held to within 0.003% over the entire temperature range. Measurements taken at +25°C and temperature extremes.

Note 3: Logging conformity is measured by computing the best fit to a true exponential and expressing the error as a base-emitter voltage deviation.

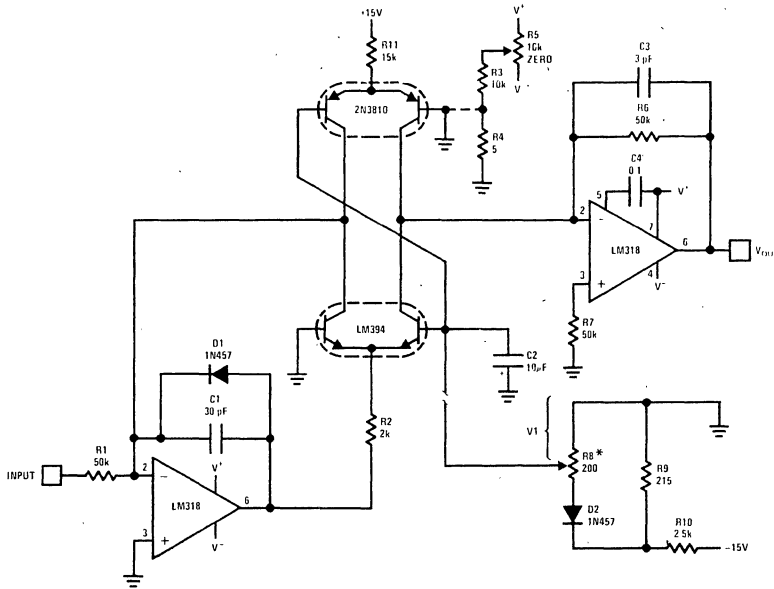
Typical Applications (Continued)

Fast, Accurate Logging Amplifier, V_{IN} = 10V to 0.1 mV or I_{IN} = 1 mA to 10 nA



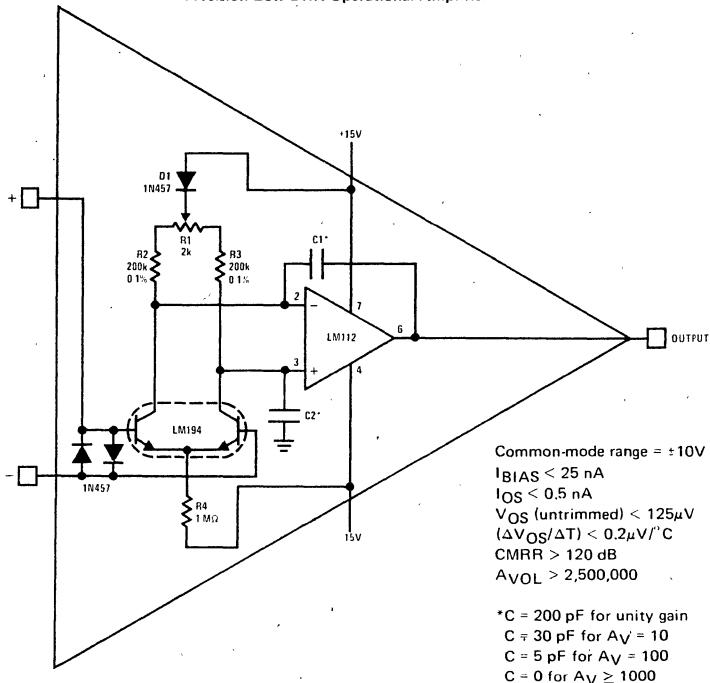
Typical Applications (Continued)

Voltage Controlled Variable Gain Amplifier



*R8 - R10 and D2 provide a temperature independent gain control.
 $G = -336 V_1$ (dB)
 Distortion < 0.1%
 Bandwidth \approx 1 MHz
 100 dB gain range

Precision Low Drift Operational Amplifier

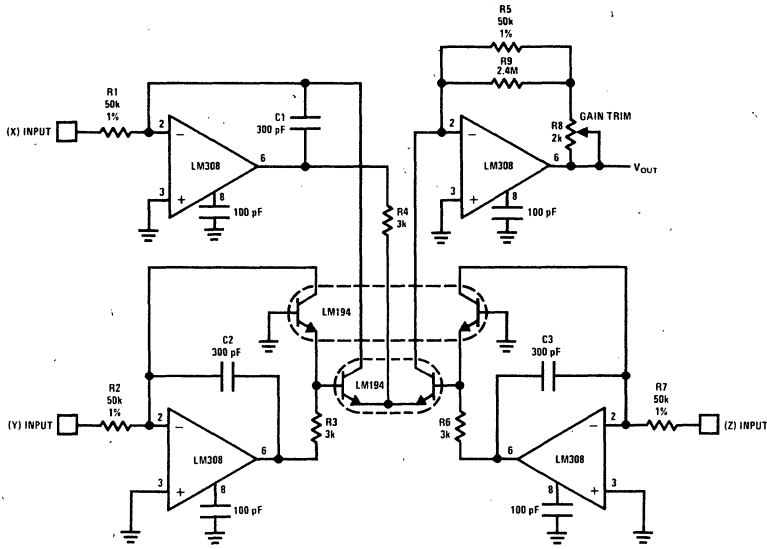


Common-mode range = $\pm 10V$
 $I_{BIAS} < 25$ nA
 $I_{OS} < 0.5$ nA
 V_{OS} (untrimmed) < 125 μV
 $(\Delta V_{OS}/\Delta T) < 0.2 \mu V/^{\circ}C$
 CMRR > 120 dB
 $A_{VOL} > 2,500,000$

*C = 200 pF for unity gain
 C = 30 pF for $A_V = 10$
 C = 5 pF for $A_V = 100$
 C = 0 for $A_V \geq 1000$

Typical Applications (Continued)

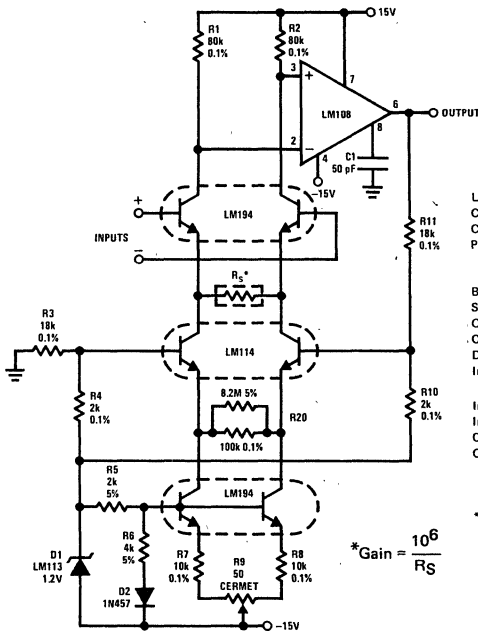
High Accuracy One Quadrant Multiplier/Divider



$$V_{OUT} = \frac{(X)(Y)}{(Z)} ; \text{positive inputs only.}$$

*Typical linearity 0.1%

High Performance Instrumentation Amplifier



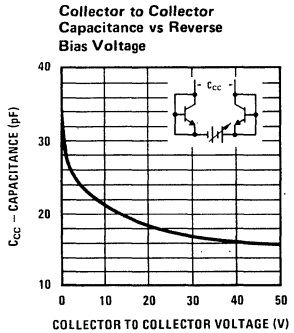
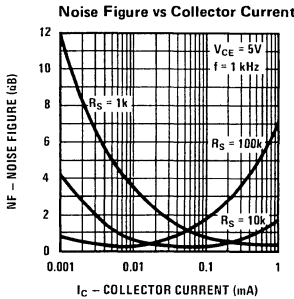
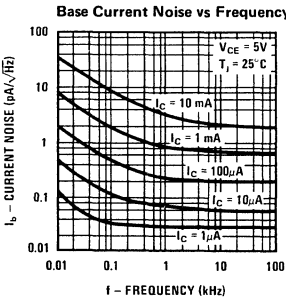
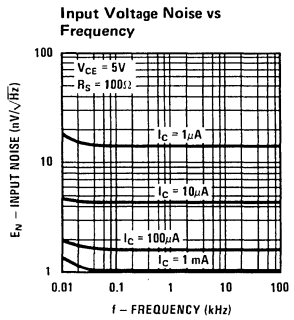
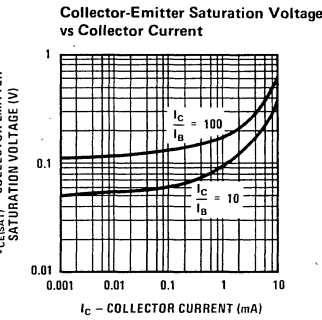
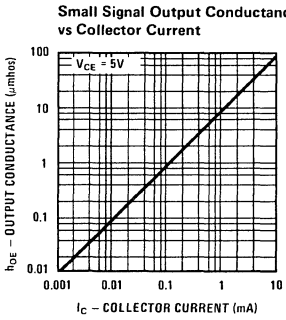
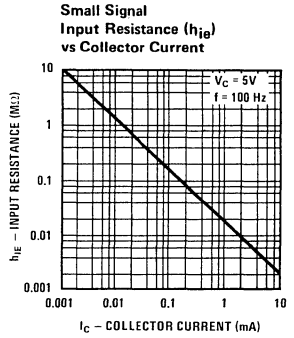
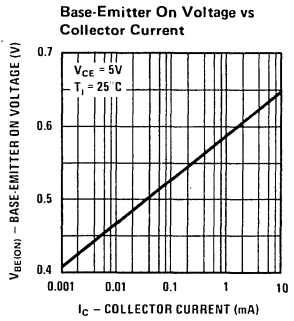
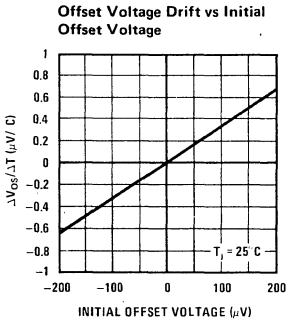
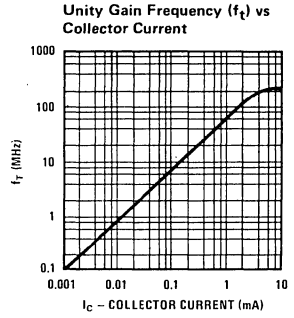
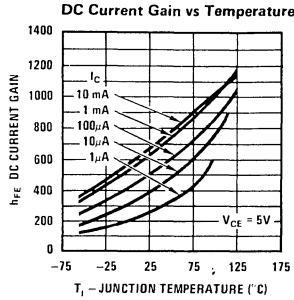
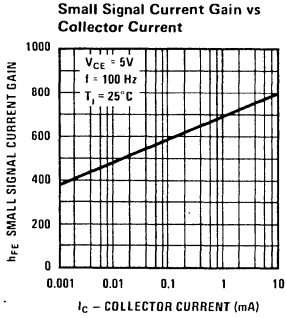
$$*Gain = \frac{10^6}{R_5}$$

Performance Characteristics

| | G = 10,000 | G = 1,000 | G = 100 | G = 10 | |
|--|-------------------|-------------------|-------------------|-------------------|------------------------|
| Linearity of Gain ($\pm 10V$ Output) | ≤ 0.01 | ≤ 0.01 | ≤ 0.02 | ≤ 0.05 | % |
| Common-Mode Rejection Ratio (60 Hz) | ≥ 120 | ≥ 120 | ≥ 110 | ≥ 90 | dB |
| Common-Mode Rejection Ratio (1 kHz) | ≥ 110 | ≥ 110 | ≥ 90 | ≥ 70 | dB |
| Power Supply Rejection Ratio | | | | | |
| + Supply | > 110 | > 110 | > 110 | > 110 | dB |
| - Supply | > 110 | > 110 | > 90 | > 70 | dB |
| Bandwidth (-3 dB) | 50 | 50 | 50 | 50 | kHz |
| Slew Rate | 0.3 | 0.3 | 0.3 | 0.3 | V/ μ s |
| Offset Voltage Drift** | ≤ 0.25 | ≤ 0.4 | ≤ 2 | ≤ 10 | μ V/ $^{\circ}$ C |
| Common-Mode Input Resistance | $> 10^9$ | $> 10^9$ | $> 10^9$ | $> 10^9$ | Ω |
| Differential Input Resistance | $> 3 \times 10^8$ | $> 3 \times 10^8$ | $> 3 \times 10^8$ | $> 3 \times 10^8$ | Ω |
| Input Referred Noise (100 Hz $\leq f \leq 10$ kHz) | 5 | 6 | 12 | 70 | $\frac{nV}{\sqrt{Hz}}$ |
| Input Bias Current | 75 | 75 | 75 | 75 | nA |
| Input Offset Current | 1.5 | 1.5 | 1.5 | 1.5 | nA |
| Common-Mode Range | ± 11 | ± 11 | ± 11 | ± 10 | V |
| Output Swing ($R_L = 10$ k Ω) | ± 13 | ± 13 | ± 13 | ± 13 | V |

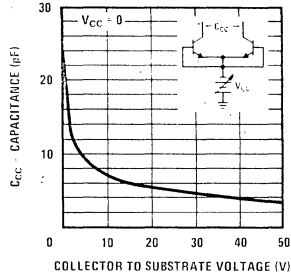
** Assumes ≤ 5 ppm/ $^{\circ}$ C tracking of resistors

Typical Performance Characteristics

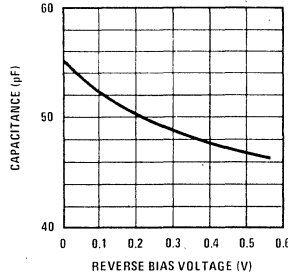


Typical Performance Characteristics (Continued)

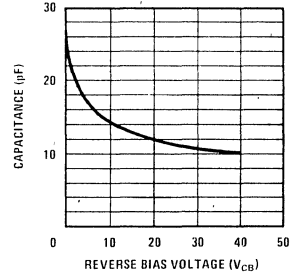
Collector to Collector Capacitance vs Collector-Substrate Voltage



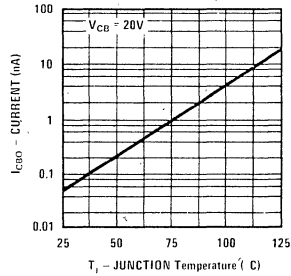
Emitter-Base Capacitance vs Reverse Bias Voltage



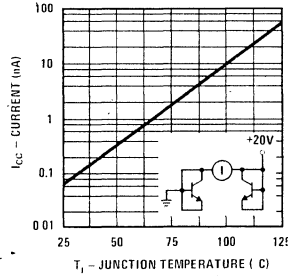
Collector-Base Capacitance vs Reverse Bias Voltage



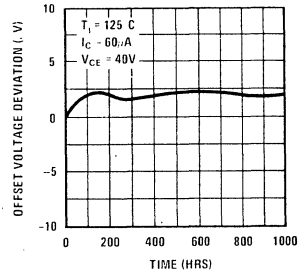
Collector-Base Leakage vs Temperature



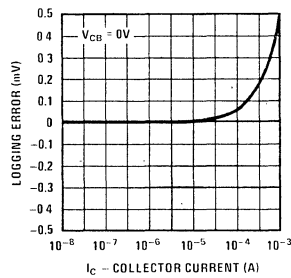
Collector to Collector Leakage vs Temperature



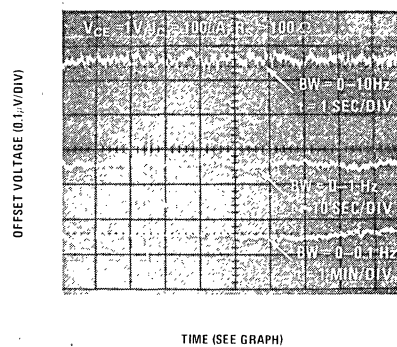
Offset Voltage Long Term Stability at High Temperature



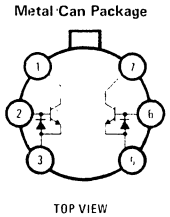
Emitter-Base Log Conformity



Low Frequency Noise of Differential Pair*



Connection Diagram



Order Number LM194H, LM394H
LM394BH or LM394CH
See NS Package H06C

*Unit must be in still air environment so that differential lead temperature is held to less than 0.0003°C.

LM195/LM295/LM395 Ultra Reliable Power Transistors

General Description

The LM195/LM295/LM395 are fast, monolithic power transistors with complete overload protection. These devices, which act as high gain power transistors, have included on the chip, current limiting, power limiting, and thermal overload protection making them virtually impossible to destroy from any type of overload. In the standard TO-3 transistor power package, the LM195 will deliver load currents in excess of 1.0A and can switch 40V in 500 ns.

The inclusion of thermal limiting, a feature not easily available in discrete designs, provides virtually absolute protection against overload. Excessive power dissipation or inadequate heat sinking causes the thermal limiting circuitry to turn off the device preventing excessive heating.

Features

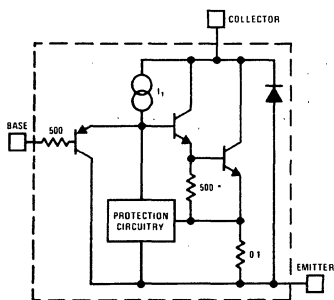
- Internal thermal limiting
- Greater than 1.0A output current
- 3.0 μ A typical base current
- 500 ns switching time
- 2.0V saturation
- Base can be driven up to 40V without damage
- Directly interfaces with CMOS or TTL
- 100% electrical burn-in

The LM195 offers a significant increase in reliability as well as simplifying power circuitry. In some applications, where protection is unusually difficult, such as switching regulators, lamp or solenoid drivers where normal power dissipation is low, the LM195 is especially advantageous.

The LM195 is easy to use and only a few precautions need be observed. Excessive collector to emitter voltage can destroy the LM195 as with any power transistor. When the device is used as an emitter follower with low source impedance, it is necessary to insert a 5.0k resistor in series with the base lead to prevent possible emitter follower oscillations. Although the device is usually stable as an emitter follower, the resistor eliminates the possibility of trouble without degrading performance. Finally, since it has good high frequency response, supply by passing is recommended.

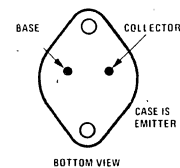
The LM195/LM295/LM395 are available in standard TO-3 power packages and solid Kovar TO-5. The LM195 is rated for operation from -55°C to $+150^{\circ}\text{C}$, the LM295 from -25°C to $+150^{\circ}\text{C}$ and the LM395 from 0°C to $+125^{\circ}\text{C}$.

Simplified Circuit and Connection Diagrams



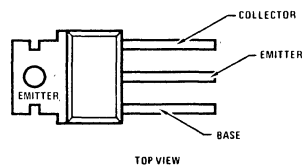
Simplified Circuit of the LM195

TO-3 Metal Can Package



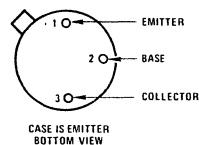
Order Number LM195K,
LM295K or LM395K
See NS Package K02A

TO-220 Power Package



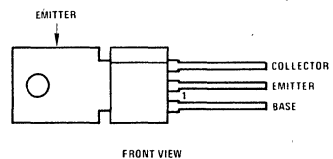
Order Number LM395T
See NS Package T03B

TO-5 Metal Can Package



Order Number LM195H,
LM295H or LM395H
See NS Package H03B

TO-202 Power Package



Order Number LM395P
See NS Package P03A

Absolute Maximum Ratings

| | |
|--|--------------------|
| Collector to Emitter Voltage | |
| LM195, LM295 | 42V |
| LM395 | 36V |
| Collector to Base Voltage | |
| LM195, LM295 | 42V |
| LM395 | 36V |
| Base to Emitter Voltage (Forward) | |
| LM195, LM295 | 42V |
| LM395 | 36V |
| Base to Emitter Voltage (Reverse) | 20V |
| Collector Current | Internally Limited |
| Power Dissipation | Internally Limited |
| Operating Temperature Range | |
| LM195 | -55°C to +150°C |
| LM295 | -25°C to +150°C |
| LM395 | 0°C to +125°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (Soldering, 10 seconds) | 300°C |

Preconditioning

100% Burn-In In Thermal Limit

Electrical Characteristics (Note 1)

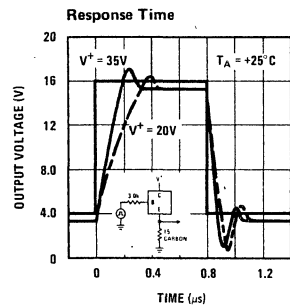
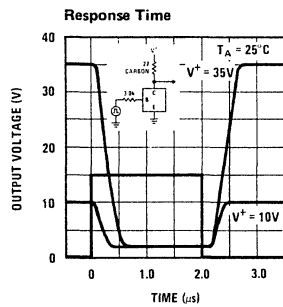
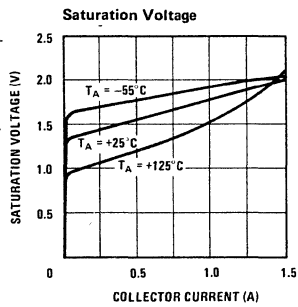
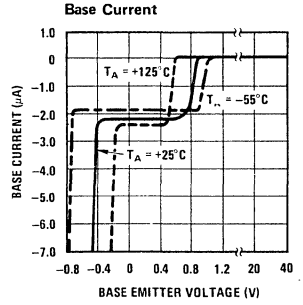
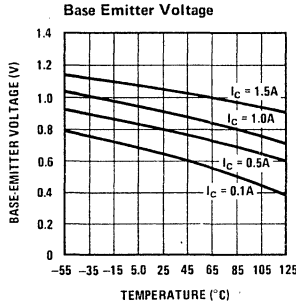
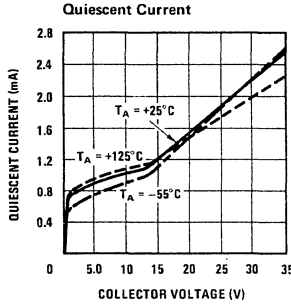
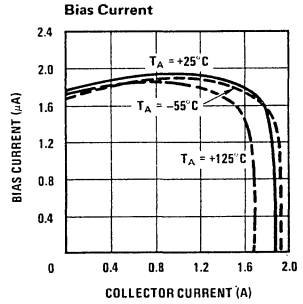
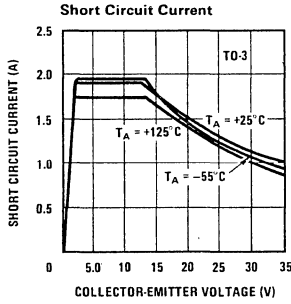
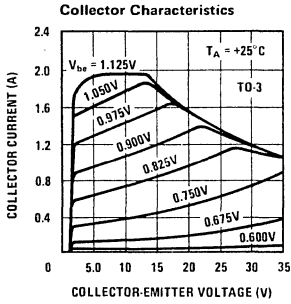
| PARAMETER | CONDITIONS | LM195, LM295 | | | LM395 | | | UNITS |
|---|---|--------------|-----|-----|-------|-----|-----|--------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Collector-Emitter Operating Voltage (Note 3) | $I_Q \leq I_C \leq I_{MAX}$ | | | 42 | | | 36 | V |
| Base to Emitter Breakdown Voltage | $0 \leq V_{CE} \leq V_{CEMAX}$ | 42 | | | 36 | 60 | | V |
| Collector Current | $V_{CE} \leq 15V$ | 1.2 | 2.2 | | 1.0 | 2.2 | | A |
| TO-3, TO-220 | $V_{CE} \leq 7.0V$ | 1.2 | 1.8 | | 1.0 | 1.8 | | A |
| TO-5, TO-202 | | | | | | | | |
| Saturation Voltage | $I_C \leq 1.0A, T_A = 25^\circ C$ | | 1.8 | 2.0 | | 1.8 | 2.2 | V |
| Base Current | $0 \leq I_C \leq I_{MAX}$ $0 \leq V_{CE} \leq V_{CEMAX}$ | | 3.0 | 5.0 | | 3.0 | 10 | μA |
| Quiescent Current (I_Q) | $V_{be} = 0$ $0 \leq V_{CE} \leq V_{CEMAX}$ | | 2.0 | 5.0 | | 2.0 | 10 | mA |
| Base to Emitter Voltage | $I_C = 1.0A, T_A = 25^\circ C$ | | 0.9 | | | 0.9 | | V |
| Switching Time | $V_{CE} = 36V, R_L = 36\Omega,$ $T_A = 25^\circ C$ | | 500 | | | 500 | | ns |
| Thermal Resistance Junction to Case (Note 2): | TO-3 Package | | 2.3 | 3.0 | | 2.3 | 3.0 | $^\circ C/W$ |
| | TO-5 Package | | 12 | 15 | | 12 | 15 | $^\circ C/W$ |

Note 1: Unless otherwise specified, these specifications apply for $-55^\circ C \leq T_j \leq +150^\circ C$ for the LM195, $-25^\circ C \leq T_j \leq +150^\circ C$ for the LM295 and $0^\circ C \leq +125^\circ C$ for the LM395.

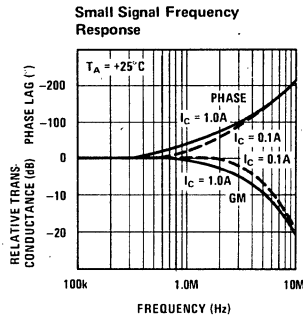
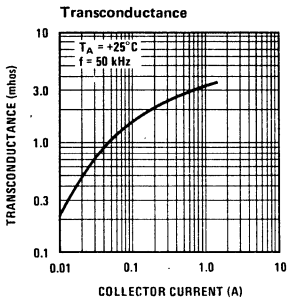
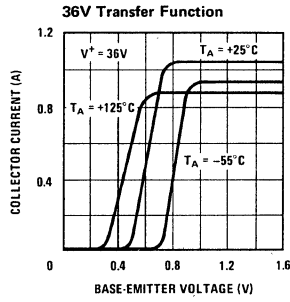
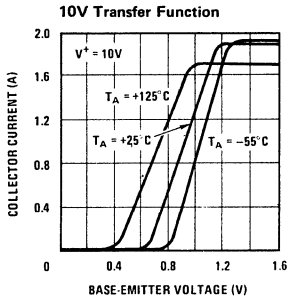
Note 2: Without a heat sink, the thermal resistance of the TO-5 package is about $+150^\circ C/W$, while that of the TO-3 package is $+35^\circ C/W$.

Note 3: Selected devices with higher breakdown available.

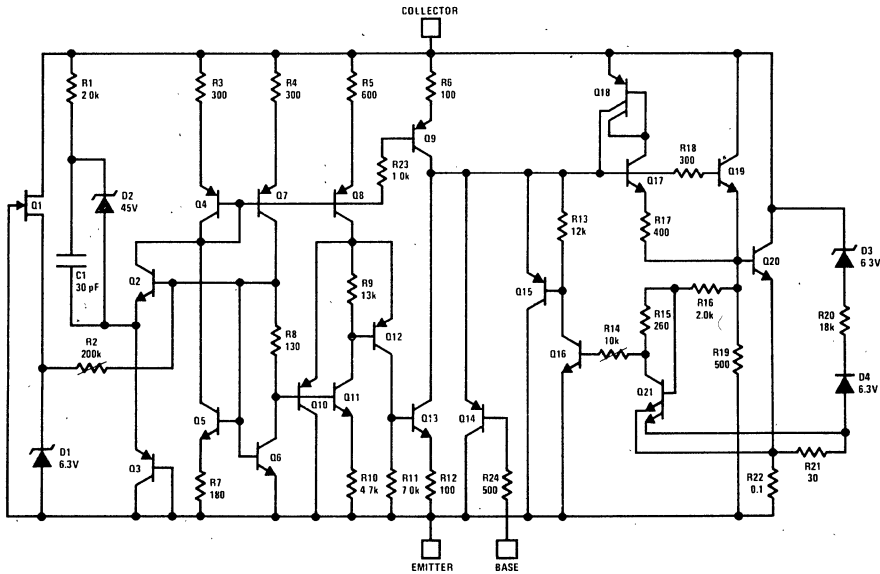
Typical Performance Characteristics



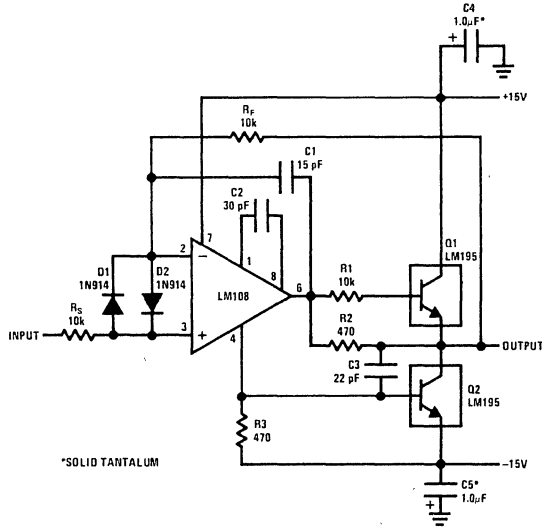
Typical Performance Characteristics (Continued)



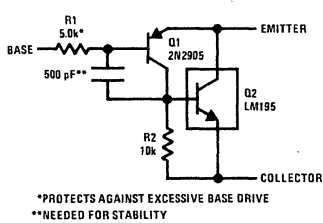
Schematic Diagram



Typical Applications

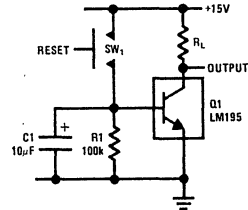


1.0 Amp Voltage Follower

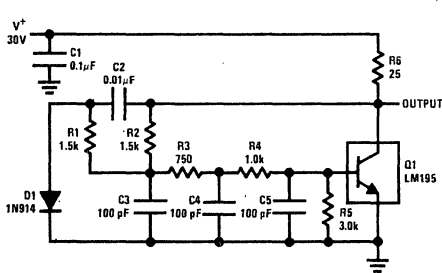


Power PNP

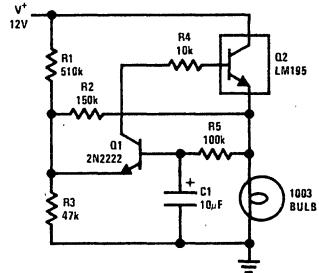
*PROTECTS AGAINST EXCESSIVE BASE DRIVE
**NEEDED FOR STABILITY



Time Delay

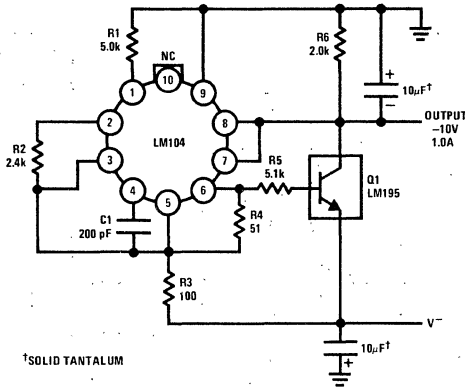


1.0 MHz Oscillator



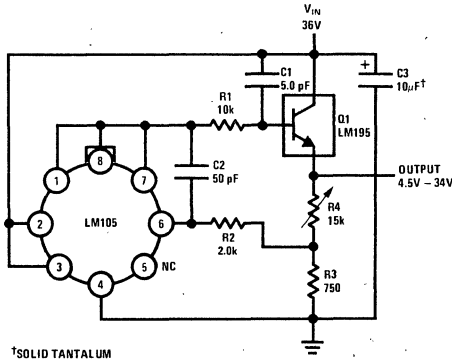
1.0 Amp Lamp Flasher

Typical Applications (Continued)



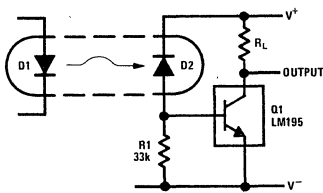
[†]SOLID TANTALUM

1.0 Amp Negative Regulator

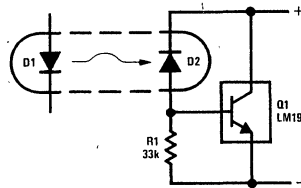


[†]SOLID TANTALUM

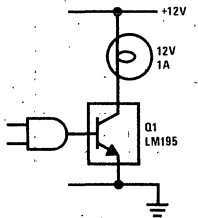
1.0 Amp Positive Voltage Regulator



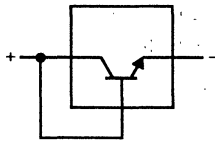
Fast Optically Isolated Switch



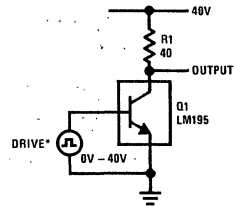
Optically Isolated Power Transistor



CMOS or TTL Lamp Interface



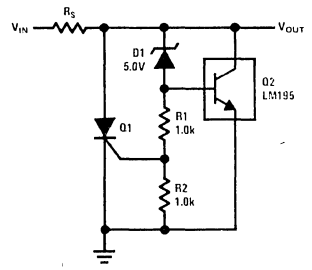
Two Terminal Current Limiter



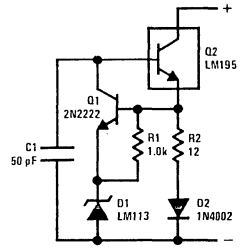
*DRIVE VOLTAGE 0V TO $\geq 1.0V \leq 42V$

40V Switch

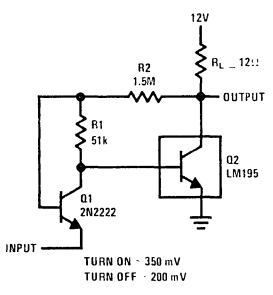
Typical Applications (Continued)



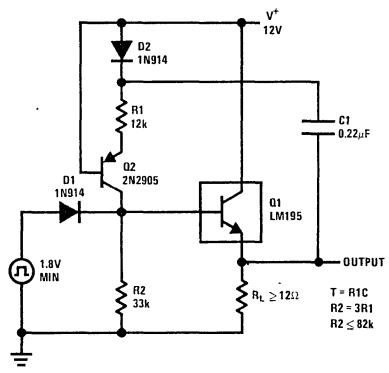
6.0V Shunt Regulator with Crowbar



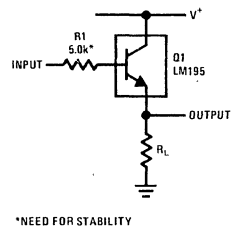
Two Terminal 100 mA Current Regulator



Low Level Power Switch

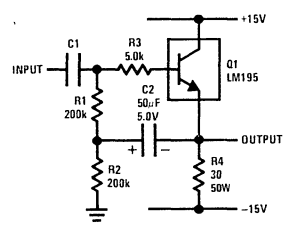


Power One-Shot

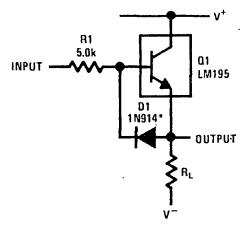


*NEED FOR STABILITY

Emmitter Follower



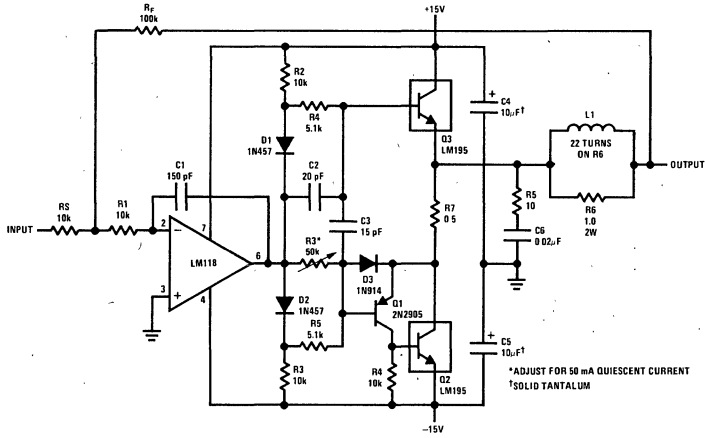
High Input Impedance AC Emmitter Follower



*PREVENTS STORAGE WITH FAST FALL TIME SQUARE WAVE DRIVE

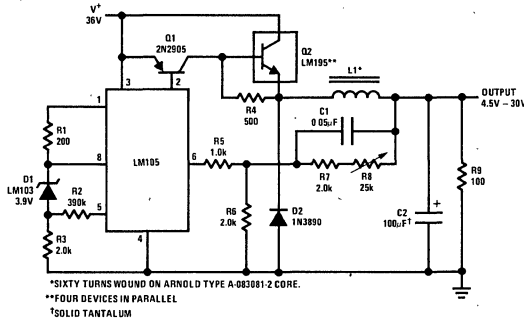
Fast Follower

Typical Applications (Continued)



*ADJUST FOR 50 mA QUIESCENT CURRENT
 †SOLID TANTALUM

Power Op Amp



*SIXTY TURNS WOUND ON ARNOLD TYPE A-002081-2 CORE.
 **FOUR DEVICES IN PARALLEL
 †SOLID TANTALUM

6.0 Amp Variable Output Switching Regulator

LM3045, LM3046, LM3086 Transistor Arrays

General Description

The LM3045, LM3046, and LM3086 each consist of five general purpose silicon NPN transistors on a common monolithic substrate. Two of the transistors are internally connected to form a differentially-connected pair. The transistors are well suited to a wide variety of applications in low power system in the DC through VHF range. They may be used as discrete transistors in conventional circuits however, in addition, they provide the very significant inherent integrated circuit advantages of close electrical and thermal matching. The LM3045 is supplied in a 14-lead cavity dual-in-line package rated for operation over the full military temperature range. The LM3046 and LM3086 are electrically identical to the LM3045 but are supplied in a 14-lead molded dual-in-line package for applications requiring only a limited temperature range.

Features

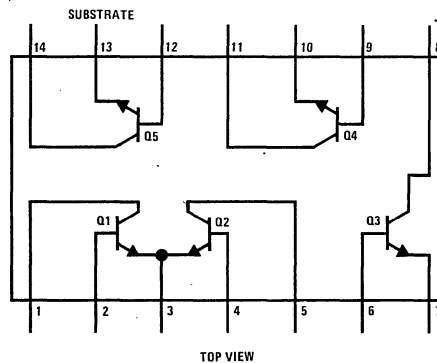
- Two matched pairs of transistors
 V_{BE} matched ± 5 mV
 Input offset current $2\mu\text{A}$ max at $I_C = 1$ mA
- Five general purpose monolithic transistors
- Operation from DC to 120 MHz
- Wide operating current range
- Low noise figure 3.2 dB typ at 1 kHz
- Full military
 temperature range (LM3045) -55°C to $+125^\circ\text{C}$

Applications

- General use in all types of signal processing systems operating anywhere in the frequency range from DC to VHF
- Custom designed differential amplifiers
- Temperature compensated amplifiers

Schematic and Connection Diagram

Dual-In-Line Package



Order Number LM3045J
 See NS Package J14A
 Order Number LM3046N
 or LM3086N
 See NS Package N14A

Absolute Maximum Ratings (T_A = 25°C)

| | LM3045 | | LM3046/LM3086 | | Units |
|---|-----------------|---------------|-----------------|---------------|-------|
| | Each Transistor | Total Package | Each Transistor | Total Package | |
| Power Dissipation: | | | | | |
| T _A = 25°C | 300 | 750 | 300 | 750 | mW |
| T _A = 25°C to 55°C | | | 300 | 750 | mW |
| T _A > 55°C | | | Derate at 6.67 | | mW/°C |
| T _A = 25°C to 75°C | 300 | 750 | | | mW |
| T _A > 75°C | Derate at 8 | | | | mW/°C |
| Collector to Emitter Voltage, V _{CE0} | 15 | | 15 | | V |
| Collector to Base Voltage, V _{CB0} | 20 | | 20 | | V |
| Collector to Substrate Voltage, V _{CIO} (Note 1) | 20 | | 20 | | V |
| Emitter to Base Voltage, V _{EBO} | 5 | | 5 | | V |
| Collector Current, I _C | 50 | | 50 | | mA |
| Operating Temperature Range | -55°C to +125°C | | -40°C to +85°C | | |
| Storage Temperature Range | -65°C to +150°C | | -65°C to +85°C | | |
| Lead Temperature (Soldering, 10 sec) | 300 | | 300 | | °C |

Electrical Characteristics (T_A = 25°C unless otherwise specified)

| PARAMETER | CONDITIONS | LIMITS | | | LIMITS | | | UNITS |
|---|--|----------------|------------------|-----|--------|------------------|-----|-------|
| | | LM3045, LM3046 | | | LM3086 | | | |
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| Collector to Base Breakdown Voltage (V _{(BR)CB0}) | I _C = 10μA, I _E = 0 | 20 | 60 | | 20 | 60 | | V |
| Collector to Emitter Breakdown Voltage (V _{(BR)CE0}) | I _C = 1 mA, I _B = 0 | 15 | 24 | | 15 | 24 | | V |
| Collector to Substrate Breakdown Voltage (V _{(BR)CIO}) | I _C = 10μA, I _{CI} = 0 | 20 | 60 | | 20 | 60 | | V |
| Emitter to Base Breakdown Voltage (V _{(BR)EB0}) | I _E = 10μA, I _C = 0 | 5 | 7 | | 5 | 7 | | V |
| Collector Cutoff Current (I _{CB0}) | V _{CB} = 10V, I _E = 0 | | .002 | 40 | | .002 | 100 | nA |
| Collector Cutoff Current (I _{CE0}) | V _{CE} = 10V, I _B = 0 | | | .5 | | | 5 | μA |
| Static Forward Current Transfer Ratio (Static Beta) (h _{FE}) | V _{CE} = 3V $\begin{cases} I_C = 10 \text{ mA} \\ I_C = 1 \text{ mA} \\ I_C = 10 \mu\text{A} \end{cases}$ | 40 | 100 100 54 | | 40 | 100 100 54 | | |
| Input Offset Current for Matched Pair Q ₁ and Q ₂ (I _{O1} - I _{O2}) | V _{CE} = 3V, I _C = 1 mA | | .3 | 2 | | | | μA |
| Base to Emitter Voltage (V _{BE}) | V _{CE} = 3V $\begin{cases} I_E = 1 \text{ mA} \\ I_E = 10 \text{ mA} \end{cases}$ | | .715 .800 | | | .715 .800 | | V |
| Magnitude of Input Offset Voltage for Differential Pair V _{BE1} - V _{BE2} | V _{CE} = 3V, I _C = 1 mA | | .45 | 5 | | | | mV |
| Magnitude of Input Offset Voltage for Isolated Transistors V _{BE3} - V _{BE4} , V _{BE4} - V _{BE5} , V _{BE5} - V _{BE3} | V _{CE} = 3V, I _C = 1 mA | | .45 | 5 | | | | mV |
| Temperature Coefficient of Base to Emitter Voltage $\left(\frac{\Delta V_{BE}}{\Delta T}\right)$ | V _{CE} = 3V, I _C = 1 mA | | -1.9 | | | -1.9 | | mV/°C |
| Collector to Emitter Saturation Voltage (V _{CE(SAT)}) | I _B = 1 mA, I _C = 10 mA | | .23 | | | .23 | | V |
| Temperature Coefficient of Input Offset Voltage $\left(\frac{\Delta V_{IO}}{\Delta T}\right)$ | V _{CE} = 3V, I _C = 1 mA | | 1.1 | | | | | μV/°C |

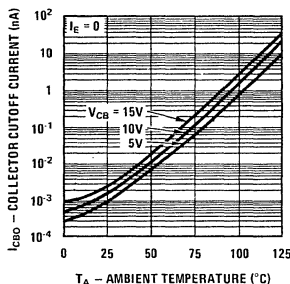
Note 1: The collector of each transistor of the LM3045, LM3046, and LM3086 is isolated from the substrate by an integral diode. The substrate (terminal 13) must be connected to the most negative point in the external circuit to maintain isolation between transistors and to provide for normal transistor action.

Electrical Characteristics (Continued)

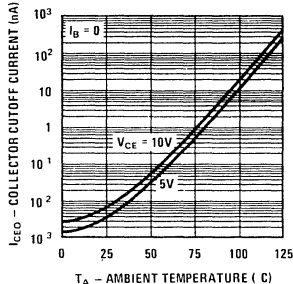
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---|-----|----------------------------------|-----|------------------|
| Low Frequency Noise Figure (NF) | $f = 1 \text{ kHz}; V_{CE} = 3V, I_C = 100\mu A$ $R_S = 1 \text{ k}\Omega$ | | 3.25 | | dB |
| Low Frequency, Small Signal Equivalent Circuit Characteristics: | | | | | |
| Forward Current Transfer Ratio (h_{fe}) | $f = 1 \text{ kHz}, V_{CE} = 3V, I_C = 1 \text{ mA}$ | | 110 (LM3045, LM3046) (LM3086) | | |
| Short Circuit Input Impedance (h_{ie}) | | | 3.5 | | $\text{k}\Omega$ |
| Open Circuit Output Impedance (h_{oe}) | | | 15.6 | | μmho |
| Open Circuit Reverse Voltage Transfer Ratio (h_{re}) | | | 1.8×10^{-4} | | |
| Admittance Characteristics: | | | | | |
| Forward Transfer Admittance (Y_{fe}) | $f = 1 \text{ MHz}, V_{CE} = 3V, I_C = 1 \text{ mA}$ | | $31 - j 1.5$ | | |
| Input Admittance (Y_{ie}) | | | $0.3 + j 0.04$ | | |
| Output Admittance (Y_{oe}) | | | $0.001 + j 0.03$ | | |
| Reverse Transfer Admittance (Y_{re}) | | | See curve | | |
| Gain Bandwidth Product (f_T) | $V_{CE} = 3V, I_C = 3 \text{ mA}$ | 300 | 550 | | |
| Emitter to Base Capacitance (C_{EB}) | $V_{EB} = 3V, I_E = 0$ | | .6 | | pF |
| Collector to Base Capacitance (C_{CB}) | $V_{CB} = 3V, I_C = 0$ | | .58 | | pF |
| Collector to Substrate Capacitance (C_{CI}) | $V_{CS} = 3V, I_C = 0$ | | 2.8 | | pF |

Typical Performance Characteristics

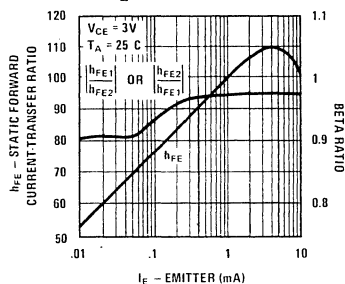
Typical Collector To Base Cutoff Current vs Ambient Temperature for Each Transistor



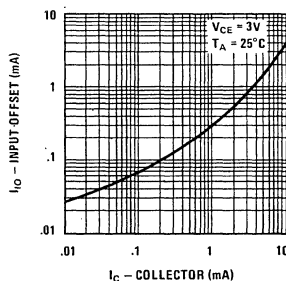
Typical Collector To Emitter Cutoff Current vs Ambient Temperature for Each Transistor



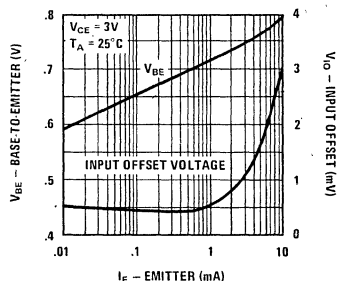
Typical Static Forward Current-Transfer Ratio and Beta Ratio for Transistors Q₁ and Q₂ vs Emitter Current



Typical Input Offset Current for Matched Transistor Pair Q₁ Q₂ vs Collector Current

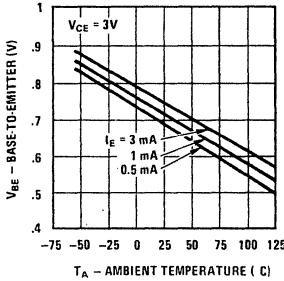


Typical Static Base To Emitter Voltage Characteristic and Input Offset Voltage for Differential Pair and Paired Isolated Transistors vs Emitter Current

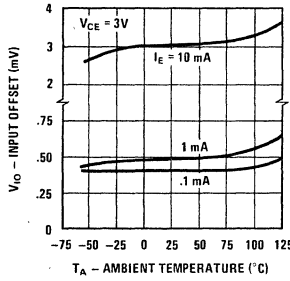


Typical Performance Characteristics (Continued)

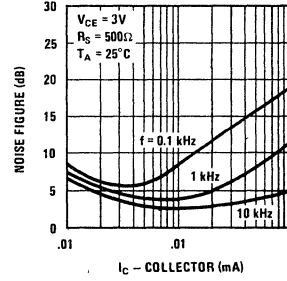
Typical Base To Emitter Voltage Characteristic for Each Transistor vs Ambient Temperature



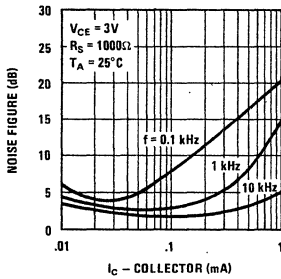
Typical Input Offset Voltage Characteristics for Differential Pair and Paired Isolated Transistors vs Ambient Temperature



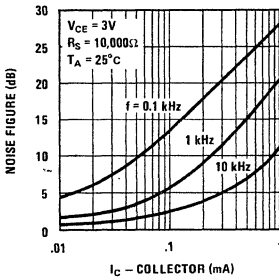
Typical Noise Figure vs Collector Current



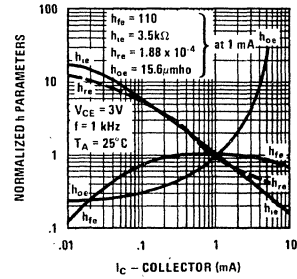
Typical Noise Figure vs Collector Current



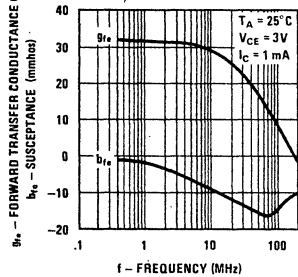
Typical Noise Figure vs Collector Current



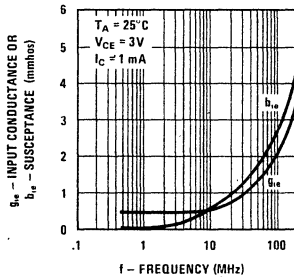
Typical Normalized Forward Current Transfer Ratio, Short Circuit Input Impedance, Open Circuit Output Impedance, and Open Circuit Reverse Voltage Transfer Ratio vs Collector Current



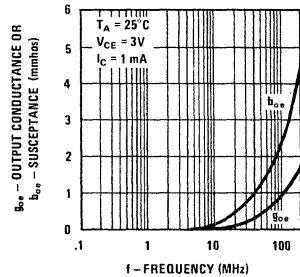
Typical Forward Transfer Admittance vs Frequency



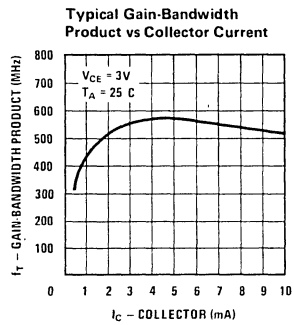
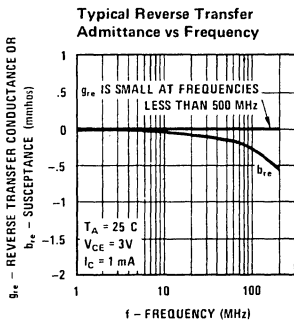
Typical Input Admittance vs Frequency



Typical Output Admittance vs Frequency



Typical Performance Characteristics (Continued)



LM3045, LM3046, LM3086

LM3146 High Voltage Transistor Array

General Description

The LM3146 consists of five high voltage general purpose silicon NPN transistors on a common monolithic substrate. Two of the transistors are internally connected to form a differentially-connected pair. The transistors are well suited to a wide variety of applications in low power system in the dc through VHF range. They may be used as discrete transistors in conventional circuits however, in addition, they provide the very significant inherent integrated circuit advantages of close electrical and thermal matching. The LM3146 is supplied in a 14-lead molded dual-in-line package for applications requiring only a limited temperature range.

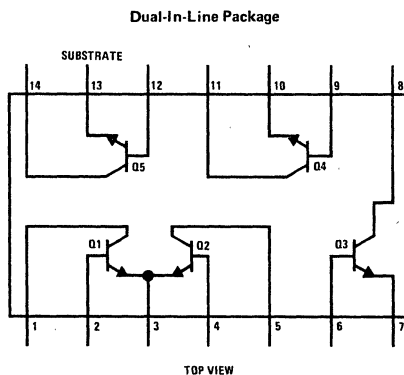
Features

- High voltage matched pairs of transistors, V_{BE} matched ± 5 mV, input offset current $2\mu\text{A}$ max at $I_C = 1$ mA
- Five general purpose monolithic transistors
- Operation from dc to 120 MHz
- Wide operating current range
- Low noise figure 3.2 dB typ at 1 kHz

Applications

- General use in all types of signal processing systems operating anywhere in the frequency range from dc to VHF
- Custom designed differential amplifiers
- Temperature compensated amplifiers

Connection Diagram



Order Number LM3146N
See NS Package N14A

Absolute Maximum Ratings

| | LM3146 | UNITS |
|--|----------------|----------------------------|
| Power Dissipation: Each Transistor | | |
| $T_A = 25^\circ\text{C}$ to 55°C | 300 | mW |
| $T_A > 55^\circ\text{C}$ | Derate at 6.67 | $\text{mW}/^\circ\text{C}$ |
| Power Dissipation: Total Package | | |
| $T_A = 25^\circ\text{C}$ | 500 | mW |
| $T_A > 25^\circ\text{C}$ | Derate at 6.67 | $\text{mW}/^\circ\text{C}$ |
| Collector to Emitter Voltage, V_{CE0} | 30 | V |
| Collector to Base Voltage, V_{CBO} | 40 | V |
| Collector to Substrate Voltage, V_{C10} (Note 1) | 40 | V |
| Emitter to Base Voltage, V_{EBO} (Note 2) | 5 | V |
| Collector Current, I_C | 50 | mA |
| Operating Temperature Range | -40 to +85 | $^\circ\text{C}$ |
| Storage Temperature Range | -65 to +150 | $^\circ\text{C}$ |
| Lead Temperature (Soldering, 10 seconds) | 300 | $^\circ\text{C}$ |

DC Electrical Characteristics $T_A = 25^\circ\text{C}$

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---|---|--------|-----------------|------|------------------------------|
| | | MIN | TYP | MAX | |
| Collector to Base Breakdown Voltage ($V_{(BR)CBO}$) | $I_C = 10\mu\text{A}$, $I_E = 0$ | 40 | 72 | | V |
| Collector to Emitter Breakdown Voltage ($V_{(BR)CEO}$) | $I_C = 1\text{ mA}$, $I_B = 0$ | 30 | 56 | | V |
| Collector to Substrate Breakdown Voltage ($V_{(BR)C10}$) | $I_{C1} = 10\mu\text{A}$, $I_B = 0$, $I_E = 0$ | 40 | 72 | | V |
| Emitter to Base Breakdown Voltage ($V_{(BR)EBO}$) (Note 2) | $I_C = 0$, $I_E = 10\mu\text{A}$ | 5 | 7 | | V |
| Collector Cutoff Current (I_{CBO}) | $V_{CB} = 10\text{V}$, $I_E = 0$ | | 0.002 | 100 | nA |
| Collector Cutoff Current (I_{CEO}) | $V_{CE} = 10\text{V}$, $I_B = 0$ | | (Note 3) | 5 | μA |
| Static Forward Current Transfer Ratio (Static Beta) (h_{FE}) | $I_C = 10\text{ mA}$, $V_{CE} = 5\text{V}$ $I_C = 1\text{ mA}$, $V_{CE} = 5\text{V}$ $I_C = 10\mu\text{A}$, $V_{CE} = 5\text{V}$ | 30 | 85 100 90 | | |
| Input Offset Current for Matched Pair Q1 and Q2 $ I_{B1} - I_{B2} $ | $I_{C1} = I_{C2} = 1\text{ mA}$, $V_{CE} = 5\text{V}$ | | 0.3 | 2 | μA |
| Base to Emitter Voltage (V_{BE}) | $I_C = 1\text{ mA}$, $V_{CE} = 3\text{V}$ | 0.63 | 0.73 | 0.83 | V |
| Magnitude of Input Offset Voltage for Differential Pair $ V_{BE1} - V_{BE2} $ | $V_{CE} = 5\text{V}$, $I_E = 1\text{ mA}$ | | 0.48 | 5 | mV |
| Temperature Coefficient of Base to Emitter Voltage ($\Delta V_{BE}/\Delta T$) | $V_{CE} = 5\text{V}$, $I_E = 1\text{ mA}$ | | -1.9 | | $\text{mV}/^\circ\text{C}$ |
| Collector to Emitter Saturation Voltage ($V_{CE(SAT)}$) | $I_C = 10\text{ mA}$, $I_B = 1\text{ mA}$ | | 0.33 | | V |
| Temperature Coefficient of Input Offset Voltage ($\Delta V_{10}/\Delta T$) | $I_C = 1\text{ mA}$, $V_{CE} = 5\text{V}$ | | 1.1 | | $\mu\text{V}/^\circ\text{C}$ |

Note 1: The collector of each transistor is isolated from the substrate by an integral diode. The substrate must be connected to a voltage which is more negative than any collector voltage in order to maintain isolation between transistors and provide normal transistor action. To avoid undesired coupling between transistors, the substrate terminal should be maintained at either dc or signal (ac) ground. A suitable bypass capacitor can be used to establish a signal ground.

Note 2: If the transistors are forced into zener breakdown ($V_{(BR)EBO}$), degradation of forward transfer current ratio (h_{FE}) can occur.

Note 3: See curve.

AC Electrical Characteristics

| PARAMETER | CONDITIONS | LIMITS | | | UNITS |
|---|--|--------|----------------------|-----|------------------|
| | | MIN | TYP | MAX | |
| Low Frequency Noise Figure (NF) | $f = 1 \text{ kHz}, V_{CE} = 5V,$ $I_C = 100\mu A, R_S = 1 \text{ k}\Omega$ | | 3.25 | | dB |
| Gain Bandwidth Product (f_T) | $V_{CE} = 5V, I_C = 3 \text{ mA}$ | 300 | 500 | | MHz |
| Emitter to Base Capacitance (C_{EB}) | $V_{EB} = 5V, I_E = 0$ | | 0.70 | | pF |
| Collector to Base Capacitance (C_{CB}) | $V_{CB} = 5V, I_C = 0$ | | 0.37 | | pF |
| Collector to Substrate Capacitance (C_{CI}) | $V_{CI} = 5V, I_C = 0$ | | 2.2 | | pF |
| LOW FREQUENCY, SMALL SIGNAL EQUIVALENT CIRCUIT CHARACTERISTICS | | | | | |
| Forward Current Transfer Ratio (h_{fe}) | $f = 1 \text{ kHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | 100 | | |
| Short Circuit Input Impedance (h_{ie}) | $f = 1 \text{ kHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | 3.5 | | $\text{k}\Omega$ |
| Open Circuit Output Impedance (h_{oe}) | $f = 1 \text{ kHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | 15.6 | | μmho |
| Open Circuit Reverse Voltage Transfer Ratio (h_{re}) | $f = 1 \text{ kHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | 1.8×10^{-4} | | |
| ADMITTANCE CHARACTERISTICS | | | | | |
| Forward Transfer Admittance (Y_{fe}) | $f = 1 \text{ MHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | $31 - j 1.5$ | | mmho |
| Input Admittance (Y_{ie}) | $f = 1 \text{ MHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | $0.3 + j 0.04$ | | mmho |
| Output Admittance (Y_{oe}) | $f = 1 \text{ MHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | $0.001 + j 0.03$ | | mmho |
| Reverse Transfer Admittance (Y_{re}) | $f = 1 \text{ MHz}, V_{CE} = 3V,$ $I_C = 1 \text{ mA}$ | | (Note 3) | | mmho |

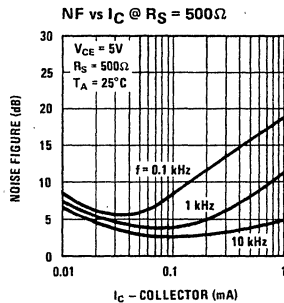
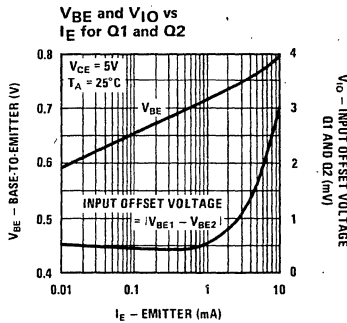
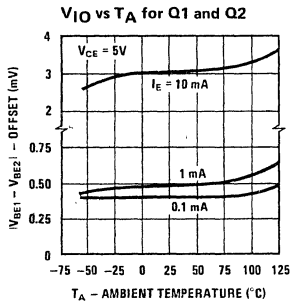
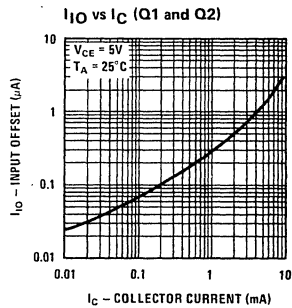
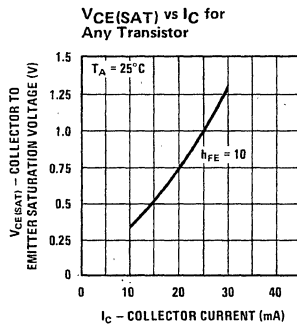
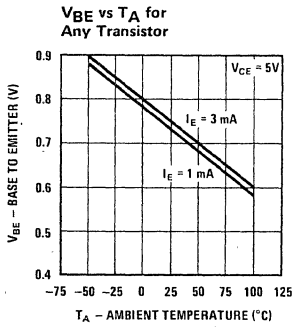
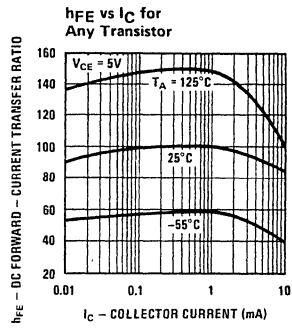
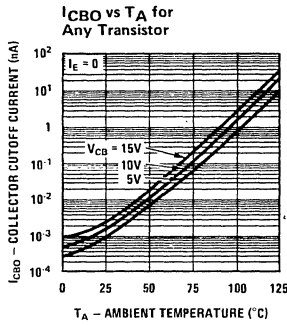
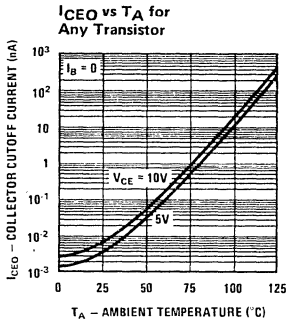
Note 1: The collector of each transistor is isolated from the substrate by an integral diode. The substrate must be connected to a voltage which is more negative than any collector voltage in order to maintain isolation between transistors and provide normal transistor action. To avoid undesired coupling between transistors, the substrate terminal should be maintained at either dc or signal (ac) ground. A suitable bypass capacitor can be used to establish a signal ground.

Note 2: If the transistors are forced into zener breakdown ($V_{(BR)EBO}$), degradation of forward transfer current ratio (h_{FE}) can occur.

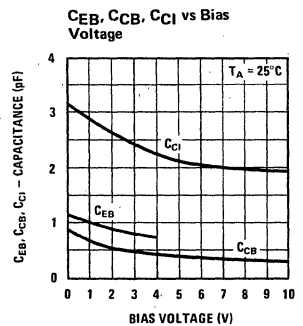
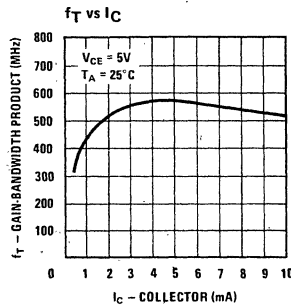
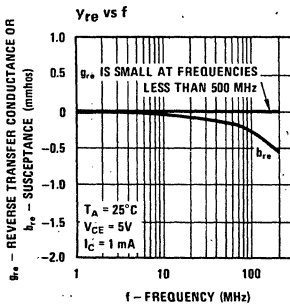
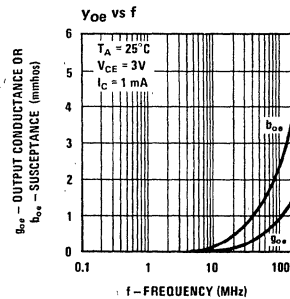
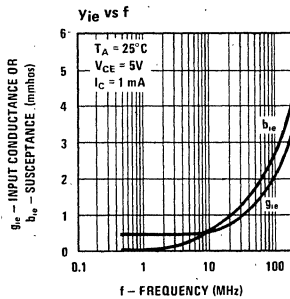
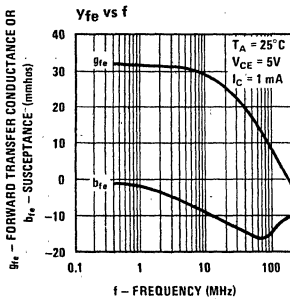
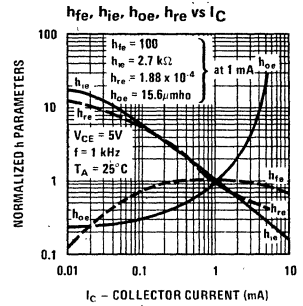
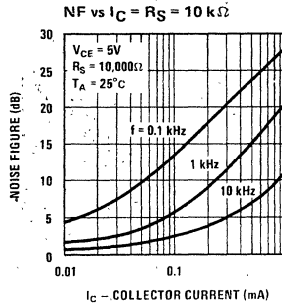
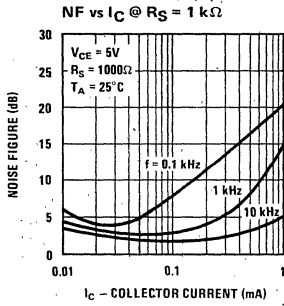
Note 3: See curve.

Typical Performance Characteristics

LM3146



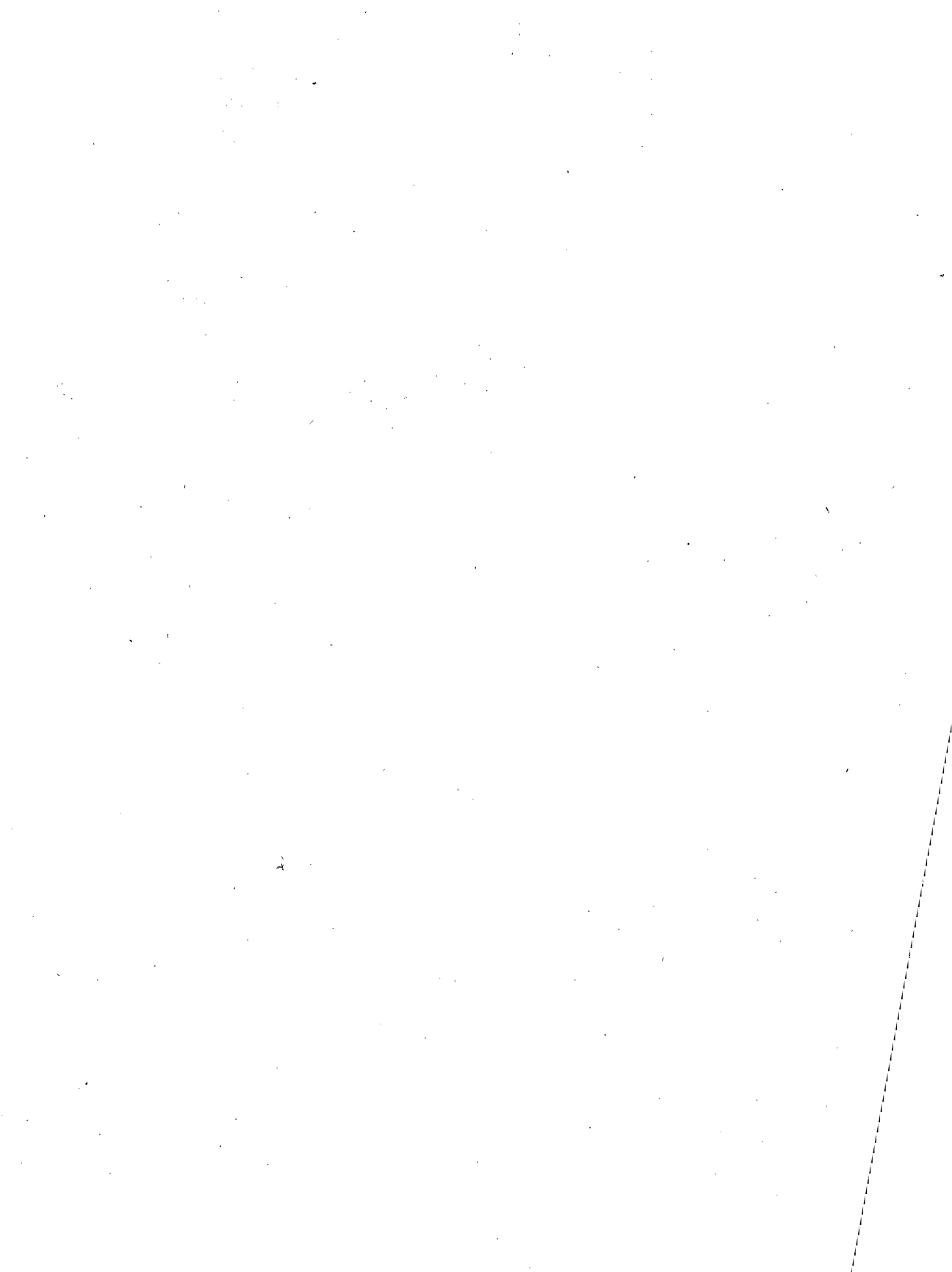
Typical Performance Characteristics (Continued)





Section 12
**Appendices/
Physical Dimensions**

12



I. RELIABILITY vs. QUALITY

The words "reliability" and "quality" are often used interchangeably, as though they connoted identical facets of a product's merit. But reliability and quality are different, and IC users must understand the essential difference between the two concepts in order to properly evaluate which of National's extended screening programs, A+ or B+ will offer the most cost effective product improvement for his application.

QUALITY

The concept of QUALITY gives us information about the population of faulty IC devices among good devices, and generally relates to the number of faulty devices that arrive at a user's plant. Looked at in another way, quality then relates to the number of faulty IC's that escape detection at the IC vendor's plant.

At National, it is the charter of the Quality Control (QC) Operation to continually monitor and reduce the number of faulty IC's that escape detection. QC does this by testing the outgoing parts on an Acceptance Quality Level (AQL) basis.¹ The tighter the AQL testing, the more difficult it becomes for a defective part to escape detection, thus the quality of the shipped product increases.

RELIABILITY

The concept of RELIABILITY, on the other hand, refers to how well a part that is initially good will withstand its environment. *Reliability cannot be tested into a device.* Reliability is principally a function of device design, die size, power dissipation, assembly methods and material, etc. Still there are tests and procedures that an IC vendor can implement which will subject the IC to stress in excess of what it will endure in actual use, which will eliminate marginal, short-life parts.

On this basis, it is easily seen that it is possible that high quality IC's may, in fact, have low reliability, while low quality IC's may have high reliability. The object of extended screening programs is: (1) to enhance the quality by reducing the population of faulty devices among good devices and by so doing, eliminate the costly requirement of incoming tests by the user, and (2) provide maximum long term reliability minimizing equipment down-time, costly repairs and maintenance.

II. QUALITY SAVES YOU MONEY

When an IC vendor specifies 100% final testing of his parts then, in theory, every shipped part should be a good part. However, in any population of mass-produced items there does exist a small percentage of defective parts.

One of the best ways to reduce the number of such faulty parts is, simply, to retest the parts prior to shipment. Thus, if there is a one percent chance that a bad part will escape detection initially, retesting the parts reduces that probability to only 0.01 percent. This is exactly what tightening of the outgoing AQL level achieves.

WHAT IS AQL?

A good example of savings which can be achieved by taking advantage of tighter AQL⁽¹⁾ inspection levels is illustrated as follows:

Assume a system uses 100 devices of a certain type which are procured to a 1% AQL level, and no incoming inspection/testing is done by the user. Statistically it can be shown that the number of systems that will require rework will be 80% of all systems manufactured! If enough devices are purchased to manufacture 100 systems (10,000 devices) and the cost to trouble shoot and repair each system is \$30.00, the total cost of repair will be \$2,400 (80% of 100 systems at \$30.00 each).

Thus, the need for some preliminary component screening prior to system assembly becomes obvious.

However, if the same devices are procured to a 0.14% AQL level, which is seven times tighter than originally assumed, it can be shown that the number of systems requiring rework is reduced by a factor of four, *without the need for incoming inspection.*

Thus, on a 100 system basis, 20 systems will require repair at \$30.00 per system, or a total of \$600.00. A savings of \$1,800 is realized, and the user need not invest in expensive capital equipment, procedures, and paper work.

On a "savings per device" basis, this is a savings of 18¢ per device. Indeed, *Quality saves you money!*

This is the value added by the A+ and B+ Linear programs.

III. RELIABILITY SAVES YOU MONEY

With the increased population of integrated circuits in modern electronics systems has come an increased concern with IC failures. And rightly so, for at least two major reasons. First, the effect of component reliability on system reliability can be quite dramatic. For example, suppose that you, as a system manufacturer, were to choose an IC that is 99% reliable. You would find that if your system used only 70 such IC's the overall reliability of the system's IC portion would be only 50%.

In other words, one out of every two systems in the field would fail. The result? A system that is very costly to produce, costly to maintain, and probably very difficult to sell.

Second, whether the system is large or small you cannot afford unnecessary maintenance costs. Not only have labor, repair and rework costs risen – and promise to continue to rise – but also, field replacement may be prohibitively expensive or impossible. If you ship a system that contains a marginally performing IC, and that IC later fails in the field, the cost of repair and replacement may be literally hundreds of times more than the cost of the failed IC itself.

(1) AQL testing is not to be confused with "in process" or electrical parameter testing in the normal product flow. All National products are 100% tested for electrical data sheet parameters.

IV. IMPROVING THE RELIABILITY OF SHIPPED PARTS

As was previously mentioned, reliability, in the true sense cannot be tested into a product. The most important factors that affect reliability are design, construction, materials and the assembly method. However, many of these can be examined and monitored by testing. As a matter of routine, National frequently performs 1000 hour burn-in life test and accelerated life tests to continually guarantee the quality and reliability of the linear product which is being shipped to customers. For example, the quality of the die attach for voltage regulators can be monitored by observing the thermal characteristics associated with "pulse loading" the regulator. This is a technique which National Linear pioneered over 10 years ago and still performs on a 100% basis on three terminal regulators at no additional cost to the user. Many such tests, including destructive and non-destructive wire bond pull tests are a matter of routine with National.

Further, in any test of reliability, the weaker parts will fail first. Stress tests will accelerate, or shorten the time of failure of the weak parts. Because the stress test causes weak parts to fail prior to shipment, the population of shipped parts will in fact demonstrate a higher reliability.

One of, if not the most effective screening procedures in the Semiconductor industry, is the use of a burn-in to stress and accelerate the failure of weak parts.

Thus, burn-in screen plus the tightened AQL outgoing testing, is the key to the A+ Linear Program.

QUALITY AND RELIABILITY PROGRAMS FOR MOLDED LINEAR PRODUCTS

One concern, with regard to quality and reliability in molded plastic products, is the problem of thermal intermittents. This problem first came to light in 1970 and plagued all semiconductor manufacturers. Since that time considerable efforts have been focused on improving lead bonding and lead frames to make them stronger and more reliable as well as improvements in the package molding material itself.

To better understand the problems a brief discussion of thermal intermittents is in order.

Because wires and bonds are completely imbedded in plastic, molded integrated circuits are extremely rugged devices. They can survive mechanical shock and vibration conditions which would literally tear the bonds and wires to pieces in a cavity type package. However, the non-cavity construction does present a unique problem. Should a bond fracture or a wire break for some reason, the broken bond will remain in contact as long as the surrounding encapsulant continues to exert a compressive force on the bond. However, as the temperature increases, the compressive forces tend to relax due to the thermal mismatches between the lead frame, die, wires and the plastic.

Ultimately, if a high enough temperature is reached, the broken bond will separate, causing an electrical discontinuity. The phenomenon is frequently

reversible, that is, as temperature decreases, electrical continuity is restored. This type of discontinuity is commonly referred to as a THERMAL INTERMITTENT OPEN. If electrical continuity does not return when the package temperature returns to ambient, then a permanent open has occurred.

If such defects occur during the manufacturing cycle of the device, and are not screened out by the manufacturer's testing sequence or by some screening test imposed by the user, they will show up as infant mortality failures in the user's equipment. If they occur during the user's equipment manufacturing cycle (due to solder heat exposure, for example) they will also show up as infant mortality failure.

The best way to screen for this phenomenon is to perform temperature cycling and "Hot Rail" testing after the device has been manufactured. The temperature cycling will stress the package mechanically to force the intermittent to occur if such a failure exists. The "Hot Rail" testing is performed to determine the functionality of the device at 100°C to ensure there are no open bonds at the worst case condition.

NATIONAL'S B+ LINEAR PROGRAM GETS IT ALL TOGETHER

We have stated that the B+ program improves both the quality and reliability of National's molded integrated circuits, and pointed out the difference between those two concepts. Now, how do we bring them together? The answer is in the B+ program processing, which is a continuum of stress and double testing. With the exception of the final QC inspection, which is a tightened sample program, *all steps of the B+ process are performed on 100% of the parts.* The following flow chart shows how we do it, step by step.

EPOXY B PROCESSING FOR ALL MOLDED PARTS -

At National, all molded semiconductors, including IC's have been built by this process for some time. All processing steps, inspections and QC monitoring are designed to provide highly reliable products. (Reliability reports are available that give, in detail, the background of Epoxy B, the reason for its selection at National and reliability data that proves its success.)

SIX HOUR, 150°C BAKE -

This stress places the die bond and all wire bonds into a combined tensile and shear stress mode, and helps eliminate marginal bonds and electrical connections.

FIVE TEMPERATURE CYCLES (0°C to 100°C)

Exercising the circuits over a 100°C temperature range further stresses the bonds and eliminates marginal bonds missed during the bake.

ELECTRICAL TESTING

These room-temperature functional and parametric tests are the normal final tests through which all National products pass.

HIGH TEMPERATURE (100°C) FUNCTIONAL ELECTRICAL TEST –

A high temperature test such as this with voltages applied places the die under the most severe stress possible. The test is actually performed at 100°C – 30°C higher than the commercial ambient limit. *All devices are thoroughly exercised at the 100°C ambient.* (Even though Epoxy B processing has virtually eliminated thermal intermittents, we perform this test to ensure against even the remote possibility of such a problem.)

100% DC FUNCTIONAL AND PARAMETRIC TESTS –

This is the second time that room-temperature functional and parametric tests are performed to National data sheet electrical limits.

TIGHTER-THAN-NORMAL QC INSPECTION PLANS –

Most vendors sample inspect outgoing parts to a 0.65% (or in some cases a 1%) AQL. When you specify the B+ program, however, not only do we sample your parts to a 0.28% AQL for all data sheet dc parameters, but they receive a 0.14% AQL for functionality as well. (Functional failures – not parameter shifts – cause most system failures.) Thus, the five to seven-times tightening of the AQL procedure gives a substantially higher quality to your B+ parts. And you can rely on the integrity of your received IC's without incoming tests at your facility.

SHIP PARTS

Here are the QC Procedures used in our B+ test program:

| TEST | TEMPERATURE | AQL |
|--------------------------|-------------|-------|
| Electrical Functionality | 25°C | 0.14% |
| Parametric, dc | 25°C | 0.28% |
| Major Mechanical | 25°C | 0.25% |
| Minor Mechanical | 25°C | 1% |

NATIONAL'S A+ LINEAR PROGRAM – THE ULTIMATE IN QUALITY AND RELIABILITY

National has combined the successful B+ program with the Military/Aerospace processing specifications and provides the A+ program as the best cost-effective approach to maximum quality and reliability on molded devices. The following flow chart shows how we do it step by step. *The major difference between B+ and the A+ is the burn-in associated with the A+ program.*

SEM –

Randomly selected wafers are taken from production regularly and subjected to SEM analysis.

EPOXY B SEAL –

At National, all molded semiconductors, including IC's have been built by this process for some time. All processing steps, inspections and QC monitoring are designed to provide highly reliable products.

SIX HOUR, 150°C BAKE –

This stress places the die bond and all wire bonds into a combined tensile and shear stress mode, and helps eliminate marginal bonds and electrical connections.

FIVE TEMPERATURE CYCLES (0°C to 100°C) –

Exercising the circuits over 100°C temperature range further stresses the bonds and eliminates any marginal bonds missed during the bake.

ELECTRICAL TESTING –

These room-temperature functional and parametric tests are the normal final tests through which all National products pass.

BURN-IN TEST –

Devices are stressed at maximum operating conditions to eliminate marginal devices. Test is performed per MIL-STD-883A, Method 1015.1.

HIGH TEMPERATURE (100°C) FUNCTIONAL ELECTRICAL TEST –

A high temperature test with voltages applied places the die under the most severe stress possible. The test is actually performed at 100°C – 30°C higher than the commercial ambient limit. *All devices are thoroughly exercised at the 100°C ambient.*

100% DC FUNCTIONAL AND PARAMETRIC TESTS –

This is the second time that room-temperature functional and parametric tests are performed to National data sheet electrical limits.

TIGHTER-THAN-NORMAL QC INSPECTION PLANS –

Most vendors sample inspect outgoing parts to a 0.65% (or in some cases a 1%) AQL. When you specify the A+ program, however, not only do we sample your parts to a 0.28% AQL for all data sheet dc parameters, but they receive 0.14% AQL for functionality as well. (Functional failures – not parameter shifts beyond spec – cause most system failures.) Thus, the five- to seven-times tightening of the sampling AQL procedure gives a substantially higher quality to your A+ parts. And you can rely on the integrity of your received IC's without incoming tests at your facility.

SHIP PARTS

Here is the QC procedure used in our A+ test program:

| TEST | TEMPERATURE | AQL |
|--------------------------|-------------|-------|
| Electrical Functionality | 25°C | 0.14% |
| Parametric, dc | 25°C | 0.28% |
| Major Mechanical | 25°C | 0.25% |
| Minor Mechanical | 25°C | 1% |

QUALITY AND RELIABILITY PROGRAM FOR HERMETIC PACKAGED LINEAR PRODUCT

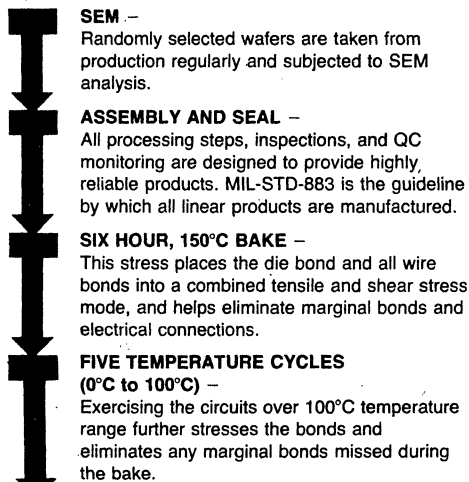
An improved quality and reliability program, similar to that which is available for molded products, is also available for commercial temperature range hermetic packages.

There is one major difference between the molded A+ program and the hermetic package A+ program. Since there is no material in contact with the wire bonds in a hermetic package, the need for "Hot Rail" functional testing at 100°C is of no benefit and therefore not included. The devices are electrically tested (100%), then burned-in and then 100% electrically tested again. If a bond failure were to occur during burn-in, there is no material in contact with the bond (such as plastic in the case of molded products) that would tend to restore the bond when the device cooled. The result is that a weak bonding wire, once broken causing an "open" will remain open and be caught at the second 100% electrical screening.

The A+ hermetic package program flow chart is shown below.

NATIONAL'S A+ PROGRAM FLOW CHART FOR HERMETIC PACKAGES

National has extended the successful B+ and A+ molded product programs to hermetic packages. We believe this to be the best practical approach to maximum quality and reliability for commercial devices. The following flow chart explains this program step by step.



ELECTRICAL TESTING – Every device will be 100% tested at 25°C for functional and dc parameters.

BURN-IN – Devices are stressed at maximum operating conditions to eliminate marginal devices. Test is performed per MIL-STD-883A method 1015.1.

DC FUNCTIONAL AND PARAMETRIC TESTS – These room temperature functional and parametric tests are the normal, final tests through which all National products pass. This is the second time 100% electrical testing is performed.

TIGHTER-THAN-NORMAL QC INSPECTION PLANS – Most vendors sample inspect outgoing parts to a 0.65% (or in some cases a 1%) AQL. When you specify the A+ program, however, not only do we sample your parts to a 0.28% AQL for all data sheet dc parameters, but they receive 0.14% AQL for functionality as well. (Functional failures – not parameter shifts beyond spec – cause most system failures.) Thus, the five- to seven-times tightening of the sampling procedure gives the highest quality to your A+ parts. And you can rely on the integrity of your received IC's without incoming tests at your facility.

SHIP PARTS
Here are the QC Sampling plans used in our A+ test program:

| TEST | TEMPERATURE | AQL |
|--------------------------|-------------|-------|
| Electrical Functionality | 25°C | 0.14% |
| Parametric, dc | 25°C | 0.28% |
| Major Mechanical | 25°C | 0.25% |
| Minor Mechanical | 25°C | 1% |

| PROCESS FLOW | MOLDED N PACKAGE | | HERMETIC H AND J PACKAGE |
|---|--------------------|------------|--------------------------|
| | A+ | B+ | A+ |
| DESCRIPTION | | | |
| 100% High Temperature Storage – 6 Hours @ 150°C | X | X | X |
| 100% Temperature Cycling, 5 Cycles – 0° to 100°C | X | X | X |
| 100% Burn-in per MIL-STD-883A, Method 1015.1 | X | | X |
| 100% High Temperature Test for Functionality at 100% | X | X | |
| 100% DC Functional parametric Tests at Room Temperature | X | X | X |
| Tightened QC Inspection Plan | X | X | X |
| Q.C. SAMPLE PLAN | | | |
| TEST | TEMPERATURE | AQL | |
| Electrical Functionality | 25°C | 0.14% | |
| Parametric, dc | 25°C | 0.28% | |
| Major Mechanical | 25°C | 0.25% | |
| Minor Mechanical | 25°C | 1% | |

A synopsis of the A+ and B+ programs is shown on the preceding page. Also shown below is a listing of some of the most popular devices which are processed to this program and are readily available.

For more information about this, or other National Linear programs, please contact your local representative.

| | | | | | |
|---------|--------|--------|--------|---------|--------|
| LF13331 | LM1458 | LM307 | LM324 | LM3900 | LM723C |
| LF13741 | LM1496 | LM308 | LM3301 | LM393 | LM725C |
| LF347 | LM2900 | LM3080 | LM3302 | LM4250C | LM733 |
| LF351 | LM2901 | LM310 | LM339 | LM555C | LM741C |
| LF353 | LM2902 | LM311 | LM3401 | LM556 | LM747C |
| LF355 | LM2903 | LM318 | LM346 | LM566 | LM748C |
| LF356 | LM2904 | LM319 | LM348 | LM567 | |
| LF357 | LM301A | | LM358 | LM709C | |
| | | | LM360 | | |
| | | | LM361 | | |

SUMMARY

The B+ program, although offering improved Reliability attendant with additional stress testing, is primarily aimed at enhancing the quality of incoming devices and thus eliminating the need for incoming testing by the user. This program offers significant cost savings to the user and eliminates the need for the investment in expensive capital equipment to perform this testing. For all general, but relatively non-critical circuits, the B+ program is the most cost-effective.

The A+ program incorporates not only the quality inherent with B+ program, but also adds burn-in for the ultimate in Reliability testing. The A+ program is recommended as the most cost-effective program for components which the user deems to be the most critical in his system.

Both programs, A+ and B+, incorporate high temperature stress, double testing, and very tight out-going AQL QC procedures.

ORDER INFORMATION

Any of the devices listed molded or hermetic package, may be ordered to the A+ program simply by adding the term A+ behind the device number, with a slash (/) in between.

Examples:

- LM348N/A+
- LF356H/A+
- LM1458J/A+

Likewise, any molded (N package) product may be ordered to the B+ program by adding the term B+ behind the device number.

Examples:

- LF351N/B+
- LM741CN/B+

For devices not listed, contact your local National Semiconductor Sales office for information on availability and ordering information.



MIL-STD-883

Mil-Standard-883 is a Test Methods and Procedures Document for Microelectronic Circuits. It was derived from MIL-S-19500, MIL-STD-750, and MIL-STD-202C for transistors and diodes at about the time that National Semiconductor Corporation was entering the military microelectronics market. As a result, our standard quality control operations are written around MIL-STD-883. The bonding control, visual inspections, and post seal screening requirements set forth by 883 (as well as added control procedures beyond the requirements of 883) have been part of National's quality control procedures almost from the start. Our Quality Assurance Procedures Manual is available upon request.

We offer a complete line of linear/883 (Class B) products as standard, off-the-shelf items. Special Linear/883 data sheets have been prepared to reflect this capability. They show process flow, electrical parameters, end of test criteria, and test circuits. We save you the problem of specifying test and inspection procedures, and offer significant cost savings by having an off-the-shelf, "to the letter" 883 program. In addition, we will test any of our integrated circuits to any class of MIL-STD-883.

MIL-M-38510

MIL-M-38510 specifies the general requirements for supplying microcircuits. These are; product assurance, which includes screening and quality conformance inspection; design and construction; marking; and workmanship. The screening and quality conformance inspection are conducted in accordance with MIL-STD-883.

Screening

All microcircuits delivered in accordance with MIL-M-38510 must have been subjected to, and passed all the screening tests detailed in Method 5004 of MIL-STD-883 for the type of microcircuit and product assurance level.

The device electrical and package requirements of MIL-M-38510 are detailed by a device specification referred to as a slash sheet. Each slash sheet defines the microcircuit electrical performance and mechanical requirements. Each device listed on a slash sheet is referred to as a slash number and the group of the microcircuits contained on a slash sheet is defined as a family of devices. The device may be Class B or C as defined by MIL-STD-883, Method 5004 and 5005. Three lead finishes are allowed by the slash sheet, pot solder dip, bright tin plate, and gold plate.

The MIL-M-38510 specs for standard linear devices require 100% DC testing at 25°C, -55°C and +125°C. AC testing is performed at +25°C. The electrical parameters specified are tighter than the normal data sheet guaranteed limits. Additionally, MIL-M-38510 requires device traceability, extensive documentation and closely matched maintenance.

Quality Conformance

Quality conformance inspection is conducted in accordance with the applicable requirements of Group A, (electrical test), Group B and C, (environmental test) of Method 5005, MIL-STD-883. These tests are conducted on a sample basis with Group A performed on each subplot, Group B on each lot, and Group C as specified (usually every three months).

To supply devices to MIL-M-38510, the IC manufacturer must qualify the devices he plans to supply to the detail specifications. Qualification consists of notifying the qualifying activity of one's intent to qualify to MIL-M-38510. After passing comprehensive audits of facilities and documentation systems, the IC manufacturer will subject the device to and demonstrate that they satisfy all of the Group A, B, and C requirements of Method 5005 of MIL-STD-883 for the specified classes and types of IC. The qualification tests shall be monitored by the qualifying agency. Finally the IC manufacturer shall prepare and submit qualification test data to the qualifying agency. Groups A, B, and C inspections then shall be performed at intervals no greater than three months.

The purpose of qualification testing is to assure that the device and lot quality conform to certain standard limits. In effect, lot qualification tests tend to ensure that once a particular device type is demonstrated to be acceptable, it's production, including materials, processing, and testing will continue to be acceptable. These limits are specified in MIL-STD-883 in terms of LTPD's (Lot Tolerance Percent Defective) for the various qualification test sub-groups. Qualification testing is performed on a sample of devices which are chosen at random from a lot of devices that has satisfactorily completed the screening of Method 5004 must be performed on each device, i.e. on a 100% basis as opposed to qualification testing (Method 5005) which occurs on a random sample basis.

In summary, the entire purpose of MIL-M-38510 and MIL-STD-883 is to provide the military, through its contractors with standard devices.

We at National Semiconductor have supplied and are supplying devices to the MIL-M-38510 specifications. To order a MIL-M-38510 microcircuit, specify the following:

For example; to specify an LM741 in a DIP processed to the requirements of MIL-M-38510, Class B, with gold plated leads, specify M-38510/10101BCC.

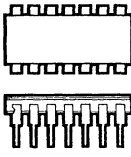
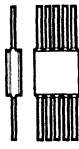

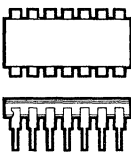
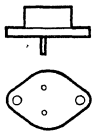
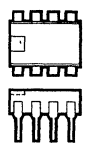
| | | | | | |
|---|-----------------|-------------|--------------|--------------|-------------|
| MM38510/ | XXX | XX | X | X | X |
| Specifies the General Requirements of MIL-M-38510 | Slash Sheet No. | Device Type | Device Class | Case Outline | Lead Finish |

| Device No. | Function | National Direct Replacement | Device No. | Function | National Direct Replacement |
|------------------|------------------------------------|-----------------------------|------------------------------|---|-----------------------------|
| FAIRCHILD | | | FAIRCHILD (Continued) | | |
| μA101AFM | General Purpose Op Amp | LM101AF | μA748CH | Op Amp | LM748CH |
| μA101AHM | General Purpose Op Amp | LM101AH | μA748HM | Op Amp | LM748HM |
| μA102HM | Voltage Follower | LM102H | μA748TC | Op Amp | LM748CN |
| μA104HM | Negative Voltage Regulator | LM104H | μA760HC | High Speed Differential Comparator | LM760CH |
| μA105HM | Voltage Regulator | LM105H | μA796HC | 3-Terminal Positive Voltage Regulator | LM1496H |
| μA107HM | General Purpose Op Amp | LM107H | μA796PC | 3-Terminal Positive Voltage Regulator | LM1496M |
| μA108AHM | Super Beta Op Amp | LM108AH | μA798HM | Dual Op Amp | LM358H |
| μA108HM | Super Beta Op Amp | LM108H | μA1558HM | Dual Internally Compensated Op Amp | LM1558H |
| μA110HM | Voltage Comparator | LM110H | μA2901PC | Dual Internally Compensated Op Amp | LM2901N |
| μA111HM | Voltage Comparator | LM111H | μA3046DC | Transistor Array | LM3046N |
| μA111RM | Voltage Comparator | LM111J-8 | μA3064PC | TV Automatic Fine-Tuning Circuit | LM3064N |
| μA201AHM | General Purpose Op Amp | LM201AH | μA3075PC | FM IF Limiter/Detector/Audio Preamplifier | LM3075N |
| μA201AT | General Purpose Op Amp | LM201AN | μA3086PC | Transistor Array | LM3086N |
| μA207HM | General Purpose Op Amp | LM207H | μA3301P | Quad Single Supply Amplifier | LM3301N |
| μA208AHM | Super Beta Op Amp | LM208AH | μA3302P | Quad Comparator | LM3302N |
| μA208HM | Super Beta Op Amp | LM208H | μA3401P | Quad Single Supply Amplifier | LM3401N |
| μA301AHC | General Purpose Op Amp | LM301AH | μAF111HM | Voltage Comparator | LF111H |
| μA301ATC | General Purpose Op Amp | LM301AN | μAF155AHM | Monolithic JFET Input Op Amp | LF155AH |
| μA302HC | Voltage Follower | LM302H | μAF155HM | Monolithic JFET Input Op Amp | LF155H |
| μA304HC | Negative Voltage Regulator | LM304H | μAF156AHM | Wideband Mono. JFET Input Op Amp | LF156AH |
| μA305AHC | Voltage Regulator | LM305AH | μAF156HM | Wideband Mono. JFET Input Op Amp | LF156H |
| μA305HC | Voltage Regulator | LM305H | μAF157AHM | Wideband Mono. JFET Input Op Amp | LF157AH |
| μA307HC | General Purpose Op Amp | LM307H | μAF157HM | Wideband Mono. JFET Input Op Amp | LF157H |
| μA307TC | General Purpose Op Amp | LM307N | μAF211HM | Voltage Comparator | LF211H |
| μA308AHC | Super Beta Op Amp | LM308AH | μAF311HC | Voltage Comparator | LF311H |
| μA308HC | Super Beta Op Amp | LM308H | μAF355AHC | Monolithic JFET Input Op Amp | LF355AH |
| μA309KC | 5 Volt Regulator | LM309KC | μAF355HC | Monolithic JFET Input Op Amp | LF355H |
| μA310HC | Voltage Follower | LM310H | μAF356AHC | Wideband Mono JFET Input Op Amp | LF356AH |
| μA311HC' | Voltage Comparator | LM311H | μAF356HC | Wideband Mono JFET Input Op Amp | LF356H |
| μA311R | Voltage Comparator | LM311J-8 | μAF357AHC | Wideband Mono JFET Input Op Amp | LF357AH |
| μA311TC | Voltage Comparator | LM311N | μAF357HC | Wideband Mono JFET Input Op Amp | LF357H |
| μA324PC | Quad Op Amp | LM324N | MOTOROLA | | |
| μA339APC | Quad Comparator | LM339AN | LF155AH | Monolithic JFET Op Amp | LF155AH |
| μA339PC | Quad Comparator | LM339N | LF155H | Monolithic JFET Op Amp | LF155H |
| μA376TC | Voltage Regulator | LM376N | LF156AH | Monolithic JFET Op Amp | LF156AH |
| μA555HC | Single Timing Circuit | LM555CH | LF156H | Monolithic JFET Op Amp | LF156H |
| μA555HM | Single Timing Circuit | LM555H | LF157AH | Monolithic JFET Op Amp | LF157AH |
| μA555TC | Single Timing Circuit | LM555CN | LF157H | Monolithic JFET Op Amp | LF157H |
| μA556PC | Dual Timing Circuit | LM556CN | LF355AH | Monolithic JFET Op Amp | LF355AH |
| μA709AHM | High Performance Op Amp | LM709AH | LF355H | Monolithic JFET Op Amp | LF355H |
| μA709HC | High Performance Op Amp | LM709CH | LF355N | Monolithic JFET Op Amp | LF355N |
| μA709HM | High Performance Op Amp | LM709H | LF356AH | Monolithic JFET Op Amp | LF356AH |
| μA709PC | High Performance Op Amp | LM709CN | LF356H | Monolithic JFET Op Amp | LF356H |
| μA709TC | High Performance Op Amp | LM709CN-8 | LF356N | Monolithic JFET Op Amp | LF356N |
| μA710FM | High Speed Differential Comparator | LM710F | LM117H | 3-Terminal Adj. Positive Regulator | LM117H |
| μA710HC | High Speed Differential Comparator | LM710CH | LM117K | 3-Terminal Adj. Positive Regulator | LM117K |
| μA710HM | High Speed Differential Comparator | LM710H | LM123K | Positive Voltage Regulator | LM123K |
| μA710PC | High Speed Differential Comparator | LM710CN | LM317H | 3-Terminal Adj. Positive Regulator | LM317H |
| μA711HC | Dual Comparator | LM711CH | LM317K | 3-Terminal Adj. Positive Regulator | LM317K |
| μA711HM | Dual Comparator | LM711H | LM317T | 3-Terminal Adj. Positive Regulator | LM317T |
| μA711PC | Dual Comparator | LM711CN | MC1303P | Dual Stereo Preamplifier | LM1303N |
| μA723DC | Precision Voltage Regulator | LM723CJ | MC1310P | FM Stereo Demodulator | LM1310N |
| μA723DM | Precision Voltage Regulator | LM723J | MC1408L6 | 8-Bit Multiplying D/A Converter | LM1408J-6 |
| μA723HC | Precision Voltage Regulator | LM723CH | MC1408L7 | 8-Bit Multiplying D/A Converter | LM1408J-7 |
| μA723HM | Precision Voltage Regulator | LM723H | MC1408L8 | 8-Bit Multiplying D/A Converter | LM1408J-8 |
| μA723PC | Precision Voltage Regulator | LM723CN | MC1408P6 | 8-Bit Multiplying D/A Converter | LM1408N-6 |
| μA725AHM | Instrumentation Op Amp | LM725AH | MC1408P7 | 8-Bit Multiplying D/A Converter | LM1408N-7 |
| μA725HC | Instrumentation Op Amp | LM725CH | MC1408P8 | 8-Bit Multiplying D/A Converter | LM1408N-8 |
| μA725HM | Instrumentation Op Amp | LM725H | MC1414L | Dual Differential Comparator | LM1414J |
| μA733HC | Differential Video | LM733CH | MC1414P | Dual Differential Comparator | LM1414N |
| μA733HM | Differential Video | LM733H | MC1496G | Balanced Modulator-Demodulator | LM1496H |
| μA741AFM | Frequency Compensated Op Amp | LM741AF | MC1496P | Balanced Modulator-Demodulator | LM1496N |
| μA741AHM | Frequency Compensated Op Amp | LM741AH | MC1508L8 | 8-Bit Multiplying D/A Converter | LM1508J-8 |
| μA741DC | Frequency Compensated Op Amp | LM741CJ-14 | MC1514L | Dual Differential Comparator | LM1514J |
| μA741EHC | Frequency Compensated Op Amp | LM741EH | MC1596G | Balanced Modulator-Demodulator | LM1596H |
| μA741HC | Frequency Compensated Op Amp | LM741CH | MC1710AG | Differential Comparator | LM710AH |
| μA741HM | Frequency Compensated Op Amp | LM741H | MC1710CG | Differential Comparator | LM710CH |
| μA741PC | Frequency Compensated Op Amp | LM741CN-14 | MC1710CP | Differential Comparator | LM710CN |
| μA741RC | Frequency Compensated Op Amp | LM741CJ | MC1710G | Differential Comparator | LM710H |
| μA741TC | Frequency Compensated Op Amp | LM741CN | MC1711CG | Dual Differential Comparator | LM711CH |
| μA746PC | Chroma Demodulator | LM746N | MC1711CP | Dual Differential Comparator | LM711CN |
| μA747AHM | Dual Frequency Compensated Op Amp | LM747AH | MC1711G | Dual Differential Comparator | LM711H |
| μA747EHC | Dual Frequency Compensated Op Amp | LM747EH | MC1723CL | Adj. Positive or Negative Volt. Regulator | LM723CJ |
| μA747HC | Dual Frequency Compensated Op Amp | LM747CH | MC1723CP | Adj. Positive or Negative Volt. Regulator | LM723CN |
| μA747HM | Dual Frequency Compensated Op Amp | LM747H | MC1723L | Adj. Positive or Negative Volt. Regulator | LM723J |
| μA747PC | Dual Frequency Compensated Op Amp | LM747CN | | | |

| Device No. | Function | National Direct Replacement | Device No. | Function | National Direct Replacement |
|-----------------------------|---------------------------------------|-----------------------------|-----------------------------|---------------------------------------|-----------------------------|
| MOTOROLA (Continued) | | | MOTOROLA (Continued) | | |
| MC1733CG | Differential Video Amp | LM733CH | MLM304G | Adjustable Negative Voltage Regulator | LM304H |
| MC1733CP | Differential Video Amp | LM733CN | MLM305G | Adjustable Positive Voltage Regulator | LM305H |
| MC1733G | Differential Video Amp | LM733H | MLM307G | General Purpose Op Amp | LM307H |
| MC1741CG | General Purpose Op Amp | LM741CH | MLM307PI | General Purpose Op Amp | LM307N |
| MC1741CL | General Purpose Op Amp | LM741CJ-14 | MLM307U | General Purpose Op Amp | LM307J |
| MC1741CP1 | General Purpose Op Amp | LM741CN | MLM308AG | Precision Op Amp | LM308AH |
| MC1741CP2 | General Purpose Op Amp | LM741CN-14 | MLM308AL | Precision Op Amp | LM308AJ |
| MC1741G | General Purpose Op Amp | LM741H | MLM308API | Precision Op Amp | LM308AN |
| MC1741I | General Purpose Op Amp | LM741J-14 | MLM308AU | Precision Op Amp | LM308AJ-8 |
| MC1741U | General Purpose Op Amp | LM741J | MLM308G | Precision Op Amp | LM308H |
| MC1747CG | Dual MC1741 Op Amp | LM747CH | MLM308L | Precision Op Amp | LM308J |
| MC1747CL | Dual MC1741 Op Amp | LM747CJ | MLM308PI | Precision Op Amp | LM308N |
| MC1747CP2 | Dual MC1741 Op Amp | LM747CN | MLM308U | Precision Op Amp | LM308J-8 |
| MC1747G | Dual MC1741 Op Amp | LM747H | MLM309G | Positive Voltage Regulator | LM309H |
| MC1747L | Dual MC1741 Op Amp | LM747J | MLM309K | Positive Voltage Regulator | LM309K |
| MC1748CG | General Purpose Op Amp | LM748CH | MLM310G | Unity Gain Op Amp | LM310H |
| MC1748CP1 | General Purpose Op Amp | LM748CN | MLM310PI | Unity Gain Op Amp | LM310N |
| MC1748CU | General Purpose Op Amp | LM748CJ | MLM310U | Unity Gain Op Amp | LM310J-8 |
| MC1748G | General Purpose Op Amp | LM748H | MLM311G | Voltage Comparator | LM311H |
| MC1748U | General Purpose Op Amp | LM748J | MLM311L | Voltage Comparator | LM311J |
| MC2901P | Quad Comparator | LM2901N | MLM311PI | Voltage Comparator | LM311N |
| MC2902P | Quad Op Amp | LM2902N | MLM311U | Voltage Comparator | LM311J-8 |
| MC3301P | Quad Op Amp | LM3301N | MLM324L | Quad Op Amp | LM324J |
| MC3302P | Quad Comparator | LM3302N | MLM324P | Quad Op Amp | LM324N |
| MC3401P | Quad Op Amp | LM3401N | MLM339AL | Quad Comparator | LM339AJ |
| MC78XXCK | Positive Voltage Regulator | LM78XXCK | MLM339AP | Quad Comparator | LM339AN |
| MC78XXCT | Positive Voltage Regulator | LM78XXCT | MLM339L | Quad Comparator | LM339J |
| MC78LXXACG | Positive Voltage Regulator | LM78LXXACH | MLM339P | Quad Comparator | LM339N |
| MC78LXXACP | Positive Voltage Regulator | LM78LXXACZ | MLM358G | Dual Op Amp | LM358H |
| MC78LXXCG | Positive Voltage Regulator | LM78LXXCH | MLM358PI | Dual Op Amp | LM358N |
| MC78LXXCP | Positive Voltage Regulator | LM78LXXCZ | MLM565CP | Phase Locked Loop | LM565CN |
| MC79XXCK | Negative Voltage Regulator | LM79XXCK | | | |
| MC79XXCT | Negative Voltage Regulator | LM79XXCT | PMI | | |
| MC79LXXACP | Negative Voltage Regulator | LM79LXXACZ | PM108AJ | Operational Amplifier | LM108AH |
| MC79LXXCP | Negative Voltage Regulator | LM79LXXCZ | PM108J | Operational Amplifier | LM108H |
| MLM101AG | Gen. Purpose Adj. Op Amp | LM101AH | PM155AJ | JFET Input Op Amp | LF155AH |
| MLM101AU | Gen. Purpose Adj. Op Amp | LM101AJ | PM155J | JFET Input Op Amp | LF155H |
| MLM104G | Adjustable Negative Volt. Regulator | LM104H | PM156AJ | JFET Input Op Amp | LF156AH |
| MLM105G | Adjustable Positive Volt. Regulator | LM105H | PM156J | JFET Input Op Amp | LF156H |
| MLM107G | General Purpose Op Amp | LM107H | PM157AJ | JFET Input Op Amp | LF157AH |
| MLM107U | General Purpose Op Amp | LM107J | PM157J | JFET Input Op Amp | LF157H |
| MLM108AG | Precision Op Amp | LM108AH | PM208AJ | Operational Amplifier | LM208AH |
| MLM108AU | Precision Op Amp | LM108AJ | PM208J | Operational Amplifier | LM208H |
| MLM109G | Positive Voltage Regulator | LM109H | PM255J | JFET Input Op Amp | LF255H |
| MLM110G | Unity Gain Op Amp | LM110H | PM256J | JFET Input Op Amp | LF256H |
| MLM110U | Unity Gain Op Amp | LM110J-8 | PM257J | JFET Input Op Amp | LF257H |
| MLM111G | Voltage Comparator | LM111H | PM308AJ | Operational Amplifier | LM308AH |
| MLM111L | Voltage Comparator | LM111J | PM308J | Operational Amplifier | LM308H |
| MLM111U | Voltage Comparator | LM111J-8 | PM355AJ | JFET Input Op Amp | LF355AH |
| MLM124L | Quad Op Amp | LM124J | PM355J | JFET Input Op Amp | LF355H |
| MLM124P | Quad Op Amp | LM124N | PM356AJ | JFET Input Op Amp | LF356AH |
| MLM139AL | Quad Comparator | LM139AJ | PM356J | JFET Input Op Amp | LF356H |
| MLM139L | Quad Comparator | LM139J | PM357AJ | JFET Input Op Amp | LF357AH |
| MLM158G | Dual Op Amp | LM158H | PM357J | JFET Input Op Amp | LF357H |
| MLM201AG | General Purpose Op Amp | LM201AH | PM725CJ | Operational Amplifier | LM725CH |
| MLM201API | General Purpose Op Amp | LM201AN | PM725J | Operational Amplifier | LM725H |
| MLM204G | Adjustable Negative Voltage Regulator | LM204H | PM741CJ | Compensated Op Amp | LM741CH |
| MLM205G | Adjustable Positive Voltage Regulator | LM205H | PM741J | Compensated Op Amp | LM741H |
| MLM207G | General Purpose Op Amp | LM207H | PM747CJ | Dual Compensated Op Amp | LM747CH |
| MLM207U | General Purpose Op Amp | LM207J | PM747J | Dual Compensated Op Amp | LM747H |
| MLM208AG | Precision Op Amp | LM208AH | PM1558J | Dual Compensated Op Amp | LM1558H |
| MLM208AL | Precision Op Amp | LM208AJ | | | |
| MLM208AU | Precision Op Amp | LM208AJ-8 | SIGNETICS | | |
| MLM208G | Precision Op Amp | LM208H | μA709AT | Operational Amplifier | LM709AH |
| MLM208L | Precision Op Amp | LM208J | μA709CN | Operational Amplifier | LM709CN-8 |
| MLM208U | Precision Op Amp | LM208J-8 | μA709CN-14 | Operational Amplifier | LM709CN |
| MLM209G | Positive Voltage Regulator | LM209H | μA709CT | Operational Amplifier | LM709CH |
| MLM211G | Voltage Comparator | LM211H | μA709T | Operational Amplifier | LM709H |
| MLM211L | Voltage Comparator | LM211J | μA710CN-14 | Differential Voltage Comparator | LM710CN |
| MLM211U | Voltage Comparator | LM211J-8 | μA710CT | Differential Voltage Comparator | LM710CH |
| MLM224L | Quad Op Amp | LM224J | μA710T | Differential Voltage Comparator | LM710H |
| MLM239AL | Quad Comparator | LM239AJ | μA711CN | Dual Voltage Comparator | LM711CN |
| MLM239L | Quad Comparator | LM239J | μA711CT | Dual Voltage Comparator | LM711CH |
| MLM258G | Dual Op Amp | LM258H | μA711K | Dual Voltage Comparator | LM711H |
| MLM301AG | General Purpose Op Amp | LM301AH | μA723CF | Precision Voltage Regulator | LM723CJ |
| MLM301API | General Purpose Op Amp | LM301AN | μA723CL | Precision Voltage Regulator | LM723CH |

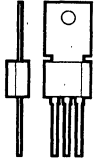
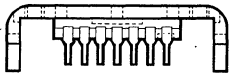
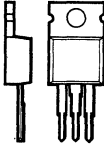
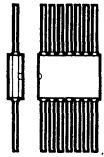

| Device No. | Function | National Direct Replacement | Device No. | Function | National Direct Replacement |
|------------------------------|---------------------------------------|-----------------------------|------------------------------|---------------------------------------|-----------------------------|
| SIGNETICS (Continued) | | | SIGNETICS (Continued) | | |
| μA723CN | Precision Voltage Regulator | LN723CN | LM224AN | Gen Purpose Single Supply Op Amp | LM224AN |
| μA723F | Precision Voltage Regulator | LM723J | LM224F | Gen Purpose Single Supply Op Amp | LM224J |
| μA723L | Precision Voltage Regulator | LM723H | LM239AF | Quad Voltage Comparator | LM239AJ |
| μA733CN | Differential Video Amp | LM733CN | LM239F | Quad Voltage Comparator | LM239J |
| μA733CT | Differential Video Amp | LM733CH | LM258T | Gen Purpose Single Supply Op Amp | LM258H |
| μA733F | Differential Video Amp | LM733H | LM293T | Low Power Dual Voltage Comparator | LM293H |
| μA741CF | General Purpose Op Amp | LM741CJ-14 | LM301AF | High Performance Amplifier | LM301AJ-14 |
| μA741CN | General Purpose Op Amp | LM741CN | LM301AN | High Performance Amplifier | LM301AN |
| μA741CN-14 | General Purpose Op Amp | LM741CN-14 | LM301AT | High Performance Amplifier | LM301H |
| μA741CT | General Purpose Op Amp | LM741CH | LM307F | General Purpose Op Amp | LM307J-14 |
| μA741F | General Purpose Op Amp | LM741J-14 | LM307N | General Purpose Op Amp | LM307N |
| μA741T | General Purpose Op Amp | LM741H | LM307T | General Purpose Op Amp | LM307H |
| μA747CN | Dual Op Amp | LM747CN | LM308AF | Precision Op Amp | LM308AJ |
| μA748CF | General Purpose Op Amp | LM748CJ | LM308AN | Precision Op Amp | LM308AN |
| μA748CN | General Purpose Op Amp | LM748CN | LM308AT | Precision Op Amp | LM308AH |
| μA748CT | General Purpose Op Amp | LM748CH | LM308F | Precision Op Amp | LM308J |
| μA748F | General Purpose Op Amp | LM748J-14 | LM308N | Precision Op Amp | LM308N |
| μA748T | General Purpose Op Amp | LM748H | LM308T | Precision Op Amp | LM308H |
| 78XXCU | 3-Terminal Positive Voltage Regulator | LM78XXCT | LM309DA | 5 Volt Regulator | LM309K |
| 78XXDA | 3-Terminal Positive Voltage Regulator | LM78XXCX | LM309DB | 5 Volt Regulator | LM309H |
| 78LXXACS | 3-Terminal Positive Voltage Regulator | LM78LXXACZ | LM311F | Voltage Comparator | LM311J |
| 78LXXADB | 3-Terminal Positive Voltage Regulator | LM78LXXACH | LM311N | Voltage Comparator | LM311N |
| 78LXXCDB | 3-Terminal Positive Voltage Regulator | LM78LXXCH | LM311N-14 | Voltage Comparator | LM311N-14 |
| 78LXXCS | 3-Terminal Positive Voltage Regulator | LM78LXXCX | LM311T | Voltage Comparator | LM311H |
| 79XXCU | 3-Terminal Negative Voltage Regulator | LM79XXCT | LM319F | Dual Voltage Comparator | LM319J |
| 79XXDA | 3-Terminal Negative Voltage Regulator | LM79XXCX | LM319K | Dual Voltage Comparator | LM319H |
| LF155AT | Hi Performance JFET Input Op Amp | LF155AH | LM319N | Dual Voltage Comparator | LM319N |
| LF155T | Hi Performance JFET Input Op Amp | LF155H | LM324AF | Gen Purpose Single Supply Op Amp | LM324AJ |
| LF156AT | Hi Performance JFET Input Op Amp | LF156AH | LM324AN | Gen Purpose Single Supply Op Amp | LM324AN |
| LF156T | Hi Performance JFET Input Op Amp | LF156H | LM324F | Gen Purpose Single Supply Op Amp | LM324J |
| LF157AT | Hi Performance JFET Input Op Amp | LF157AH | LM324N | Gen Purpose Single Supply Op Amp | LM324N |
| LF157T | Hi Performance JFET Input Op Amp | LF157H | LM339AF | Quad Voltage Comparator | LM339AJ |
| LF255T | Hi Performance JFET Input Op Amp | LF255H | LM339AN | Quad Voltage Comparator | LM339AN |
| LF256T | Hi Performance JFET Input Op Amp | LF256H | LM339F | Quad Voltage Comparator | LM339J |
| LF257T | Hi Performance JFET Input Op Amp | LF257H | LM339N | Quad Voltage Comparator | LM339N |
| LF355AT | Hi Performance JFET Input Op Amp | LF355AH | LM340XXDA | 3-Terminal Positive Voltage Regulator | LM340KXX |
| LF355T | Hi Performance JFET Input Op Amp | LF355H | LM340XXLL | 3-Terminal Positive Voltage Regulator | LM340TXX |
| LF356AT | Hi Performance JFET Input Op Amp | LF356AH | LM381AN | Dual Low Noise Preamplifier | LM381AN |
| LF356T | Hi Performance JFET Input Op Amp | LF356H | LM381N | Dual Low Noise Preamplifier | LM381N |
| LF357AT | Hi Performance JFET Input Op Amp | LF357AH | LM382N | Dual Low Noise Preamplifier | LM382N |
| LF357T | Hi Performance JFET Input Op Amp | LF357H | LM387N | Dual Low Noise Preamplifier | LM387N |
| LM101AF | High Performance Amplifier | LM101AJ-14 | LM393AN | Low Power Dual Voltage Comparator | LM393AN |
| LM101AT | High Performance Amplifier | LM101AH | LM393AT | Low Power Dual Voltage Comparator | LM393AH |
| LM107F | General Purpose Op Amp | LM107J-14 | LM393N | Low Power Dual Voltage Comparator | LM393N |
| LM107T | General Purpose Op Amp | LM107H | LM393T | Low Power Dual Voltage Comparator | LM393H |
| LM108AF | Precision Op Amp | LM108AJ | LM2901F | Quad Voltage Comparator | LM2901J |
| LM108AT | Precision Op Amp | LM108AH | LM2901N | Quad Voltage Comparator | LM2901N |
| LM108F | Precision Op Amp | LM108J | LM2903N | Low Power Dual Voltage Comparator | LM2903N |
| LM108T | Precision Op Amp | LM108H | MC1408-7F | 8-Bit Multiplying D/A Converter | LM1407J-7 |
| LM109DB | 5 Volt Regulator | LM109H | MC1408-8F | 8-Bit Multiplying D/A Converter | LM1408J-8 |
| LM111F | Voltage Comparator | LM111J | MC1408-7N | 8-Bit Multiplying D/A Converter | LM1408N-7 |
| LM111T | Voltage Comparator | LM111H | MC1408-8N | 8-Bit Multiplying D/A Converter | LM1408N-8 |
| LM119F | Dual Voltage Comparator | LM119J | MC1496K | Balanced Modulator Demodulator | LM1496H |
| LM119K | Dual Voltage Comparator | LM119H | MC1496N | Balanced Modulator Demodulator | LM1496N |
| LM124AF | Gen Purpose Single Supply Op Amp | LM124AJ | MC1596K | Balanced Modulator Demodulator | LM1596H |
| LM124F | Gen Purpose Single Supply Op Amp | LM124J | MC3302N | Quad Voltage Comparator | LM3302N |
| LM124AN | Gen Purpose Single Supply Op Amp | LM124N | NE555T | Timer | LM555CH |
| LM139AF | Quad Voltage Comparator | LM139AJ | NE555N | Timer | LM555CN |
| LM139F | Quad Voltage Comparator | LM139J | NE556N | Dual Timer | LM556CN |
| LM193AT | Low Power Dual Voltage Comparator | LM193AH | NE556F | Dual Timer | LM556J |
| LM193T | Low Power Dual Voltage Comparator | LM193H | NE565K | Phase Locked Loop | LM565CH |
| LM201AF | High Performance Amplifier | LM201AJ-14 | NE565N | Phase Locked Loop | LM565CN |
| LM201AN | High Performance Amplifier | LM201AH | NE566N | Function Generator | LM566CN |
| LM201AT | High Performance Amplifier | LM201H | NE567T | Tone Decoder/Phase Locked Loop | LM567CH |
| LM207F | General Purpose Op Amp | LM207J-14 | NE567N | Tone Decoder/Phase Locked Loop | LM567CN |
| LM207T | General Purpose Op Amp | LM207H | SE555T | Timer | LM555H |
| LM208AF | General Purpose Op Amp | LM208AJ | SE565K | Phase Locked Loop | LM565H |
| LM208AT | Precision Operational Amp | LM208AH | SE567T | Tone Decoder/Phase Locked Loop | LM567H |
| LM208F | Precision Operational Amp | LM208J | TBA120N | FM IF Amp & Demodulator | TBA120T |
| LM208T | Precision Operational Amp | LM208H | TBA120S-2 | 8-Stage Amp w/Balanced Demodulator | TBA120S II |
| LM209DB | 5 Volt Regulator | LM209H | TBA120S-3 | 8-Stage Amp w/Balanced Demodulator | TBA120S III |
| LM211F | Voltage Comparator | LM211J | TBA120S-4 | 8-Stage Amp w/Balanced Demodulator | TBA120S IV |
| LM211T | Voltage Comparator | LM211H | TBA120S-5 | 8-Stage Amp w/Balanced Demodulator | TBA120S V |
| LM219F | Dual Voltage Comparator | LM219J | TBA120SN | 8-Stage w/Balanced Demodulator | TBA120SQ |
| LM219K | Dual Voltage Comparator | LM219H | TBA120S-2N | 8-Stage w/Balanced Demodulator | TBA120SQ II |
| LM224AF | Gen Purpose Single Supply Op Amp | LM224AJ | TBA120S-3N | 8-Stage w/Balanced Demodulator | TBA120SQ III |

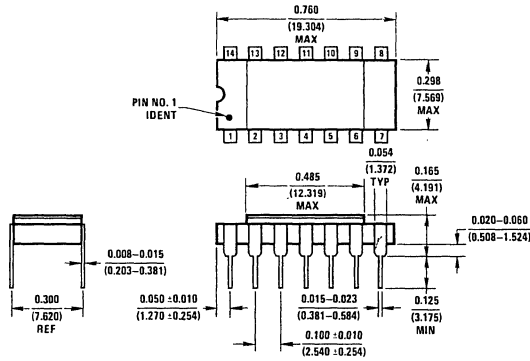
| Device No. | Function | National Direct Replacement | Device No. | Function | National Direct Replacement |
|------------------------------|---------------------------------|-----------------------------|--------------------------------------|---------------------------------|-----------------------------|
| SIGNETICS (Continued) | | | TEXAS INSTRUMENTS (Continued) | | |
| TBA120S-4N | 8-Stage w/Balanced Demodulator | TBA120SQ IV | LM117LA | 3-Terminal Adjustable Regulator | LM117H |
| TBA120S-5N | 8-Stage w/Balanced Demodulator | TBA120SQ V | LM118JG | High Slew Rate Op Amp | LM118J |
| TBA120U | FM IF Amp & Demodulator | TBA120U | LM118L | High Slew Rate Op Amp | LM118H |
| TBA120UN | FM IF Amp & Demodulator | TBA120UQ | LM124J | Quad Op Amp | LM124J |
| TEXAS INSTRUMENTS | | | LM124N | Quad Op Amp | LM1524N |
| μA70AML | Op Amp | LM709AH | LM139J | Quad Comparator | LM139J |
| μA709CL | Op Amp | LM709CH | LM158L | Dual Op Amp | eLM158H |
| μA709CN | Op Amp | LM709CN | LM193L | Dual Comparator | LM193H |
| μA709CP | Op Amp | LM709CN-8 | LM201AJ | Improved Op Amp | LM201AJ-14 |
| μA709ML | Op Amp | LM709H | LM201AJG | Improved Op Amp | LM201AJ |
| μA710ML | Comparator | LM710H | LM201AL | Improved Op Amp | LM201AH |
| μA711CL | Dual Comparator | LM711CH | LM201AN | Improved Op Amp | LM201AN |
| μA711CN | Dual Comparator | LM711CN | LM204L | Negative Voltage Regulator | LM204H |
| μA711ML | Dual Comparator | LM711H | LM205L | Positive Voltage Regulator | LM205H |
| μA723CJ | Voltage Regulator | LM723CJ | LM206L | Voltage Comparator | LM206H |
| μA723CL | Voltage Regulator | LM723CH | LM207J | Compensated Op Amp | LM207J-14 |
| μA723CN | Voltage Regulator | LM723CN | LM207JG | Compensated Op Amp | LM207J |
| μA723MJ | Voltage Regulator | LM723J | LM207L | Compensated Op Amp | LM207H |
| μA723ML | Voltage Regulator | LM723H | LM209LA | 5V Regulator | LM209H |
| μA733CL | Video Amp | LM733CH | LM217H | 3-Terminal Adjustable Regulator | LM217LA |
| μA733CN | Video Amp | LM733CN | LM217KA | 3-Terminal Adjustable Regulator | LM217K |
| μA733ML | Video Amp | LM733H | LM218JG | High Slew Rate Op Amp | LM218J-8 |
| μA741CJ | Compensated Op Amp | LM741CJ-14 | LM218L | High Slew Rate Op Amp | LM218H |
| μA741CJG | Compensated Op Amp | LM741CN-14 | LM224J | Quad Op Amp | LM224J |
| μA741CL | Compensated Op Amp | LM741CJ | LM239J | Quad Comparator | LM239J |
| μA741CP | Compensated Op Amp | LM741CH | LM258L | Dual Op Amp | LM258H |
| μA741MJ | Compensated Op Amp | LM741CN | LM293L | Dual Comparator | LM293H |
| μA741MJG | Compensated Op Amp | LM741J-14 | LM301AJ | Improved Op Amp | LM301AJ-14 |
| μA741ML | Compensated Op Amp | LM741J | LM301AJG | Improved Op Amp | LM301AJ |
| μA748CJG | Op Amp | LM741H | LM301AL | Improved Op Amp | LM301AH |
| μA748CL | Op Amp | LM748CJ | LM301AN | Improved Op Amp | LM301AN |
| μA748CN | Op Amp | IM748CH | LM304L | Negative Voltage Regulator | LM304H |
| μA748MJ | Op Amp | LM748CN | LM305AL | Positive Voltage Regulator | LM305AH |
| μA748MJG | Op Amp | LM748J-14 | LM305L | Positive Voltage Regulator | LM305H |
| μA748ML | Op Amp | LM748J | LM306L | Voltage Comparator | LM306H |
| μA78XXCKA | Positive Voltage Regulator | LM748H | LM307J | Compensated Op Amp | LM307J-14 |
| μA78XXCKC | Positive Voltage Regulator | LM78XXCK | LM307JG | Compensated Op Amp | LM307J |
| μA78LXXACL | Positive Voltage Regulator | LM78XXCT | LM307L | Compensated Op Amp | LM307H |
| μA78LXXCLP | Positive Voltage Regulator | LM78LXXACZ | LM307N | Compensated Op Amp | LM307N |
| μA78MXXCKD | Positive Voltage Regulator | LM78MXXCPC | LM309LA | 5V Regulator | LM309H |
| μA79XXCKA | Negative Voltage Regulator | LM79XXCK | LM311J | Voltage Comparator | LM311J |
| μA79XXCKC | Negative Voltage Regulator | LM79XXCT | LM311JG | Voltage Comparator | LM311J-8 |
| μA79MXXCKD | Negative Voltage Regulator | LM79MXXCPC | LM311L | Voltage Comparator | LM311H |
| μA79MXXCLA | Negative Voltage Regulator | LM79MXXCH | LM311N | Voltage Comparator | LM311N-14 |
| μA79MXXLA | Negative Voltage Regulator | LM79MXXH | LM311P | Voltage Comparator | LM311N |
| LF155AL | JFET Input Op Amp | LF155AH | LM317KA | 3-Terminal Adjustable Regulator | LM317K |
| LF155L | JFET Input Op Amp | LF155H | LM317KC | 3-Terminal Adjustable Regulator | LM317T |
| LF156AL | JFET Input Op Amp | LF156AH | LM317LA | 3-Terminal Adjustable Regulator | LM317H |
| LF156L | JFET Input Op Amp | LF156H | LM318JG | High Slew Rate Op Amp | LM318J-8 |
| LF157AL | JFET Input Op Amp | LF157AH | LM318L | High Slew Rate Op Amp | LM318H |
| LF157L | JFET Input Op Amp | LF157H | LM318P | High Slew Rate Op Amp | LM318N |
| LF255L | JFET Input Op Amp | LF255H | LM324J | Quad Op Amp | LM324J |
| LF256L | JFET Input Op Amp | LF256H | LM324N | Quad Op Amp | LM324N |
| LF257L | JFET Input Op Amp | LF257H | LM339J | Quad Comparator | LM339J |
| LF355AL | JFET Input Op Amp | LF355AH | LM339N | Quad Comparator | LM339N |
| LF355L | JFET Input Op Amp | LF355H | LM358L | Dual Op Amp | LM358H |
| LF356L | JFET Input Op Amp | LF356AH | LM358P | Dual Op Amp | LM358N |
| LF356L | JFET Input Op Amp | LF356H | LM376P | Positive Voltage Regulator | LM376N |
| LF356P | JFET Input Op Amp | LF356N | LM393L | Dual Comparator | LM393H |
| LM101AJ | Improved Op Amp | LM101AF | LM393P | Dual Comparator | LM393N |
| LM101AJG | Improved Op Amp | LM101AH | LM2901N | Quad Comparator | LM2901N |
| LM101AL | Improved Op Amp | LM101AF | LM2902J | Quad Op Amp | LM2902J |
| LM101AU | Improved Op Amp | LM104H | LM2902N | Quad Op Amp | LM2902N |
| LM104L | Negative Voltage Regulator | LM105H | LM2903P | Dual Comparator | LM2903N |
| LM105L | Positive Voltage Regulator | LM106H | LM2904P | Dual Op Amp | LM2904N |
| LM106L | Voltage Comparator | LM107J-14 | MC1558JG | Dual Compensated Op Amp | LM1558J |
| LM107J | Compensated Op Amp | LM107J | MC1558L | Dual Compensated Op Amp | LM1558H |
| LM107JG | Compensated Op Amp | LM107H | NE555CJG | Timer | LM555CJ |
| LM107L | Compensated Op Amp | LM109H | NE555CL | Timer | LM555CH |
| LM109LA | 5V Regulator | LM111J | SE555JG | Timer | LM555J |
| LM111J | Voltage Comparator | LM111J-8 | SE555L | Timer | LM555H |
| LM111JG | Voltage Comparator | LM111H | TL081ACL | Single Low Cost Bi-Fet Op Amp | LF351AH |
| LM111L | Voltage Comparator | LM117K | TL081ACN | Single Low Cost Bi-Fet Op Amp | LF351AN |
| LM117KA | 3-Terminal Adjustable Regulator | | TL081CL | Single Low Cost Bi-Fet Op Amp | LF351H |
| | | | TL081CN | Single Low Cost Bi-Fet Op Amp | LF351N |
| | | | TL710CL | Comparator | LM710CH |
| | | | TL710CN | Comparator | LM710CN |

| | | NSC | Signetics | Fairchild | Motorola | TI | RCA | Silicon General | AMD | Raytheon |
|---|---|-----|----------------------|-----------|----------|---------|-------------|-----------------|-----|------------------------|
|  | 14/16 Lead Glass/Metal DIP | D | I | D | L | | D | D | D | D, M |
|  | Glass/Metal Flat-Pack | F | Q | F | F | F, S | K | F | F | J, F, Q |
|  | TO-99, TO-100, TO-5 | H | T, K, L, DB | H | G | L | S*, V1** | T | H | T, H |
|  | 8, 14 and 16-Lead Low-Temperature Ceramic DIP | J | F | R, D | U | J | | | | DC, DD |
|  | (Steel) | K | | | KS | | | K | | K |
| | (Aluminum) | KC | DA | K | K | K | | K | | LK, TK |
|  | 8, 14 and 16-Lead Plastic DIP | N | V, A, B | T, P | P | P, N | E | M, N | PC | N, DN, DP, MP |

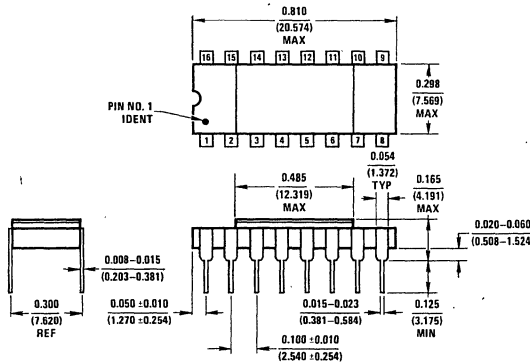
*With dual-in-line formed leads.
**With radially formed leads.

Industry Package Cross Reference Guide

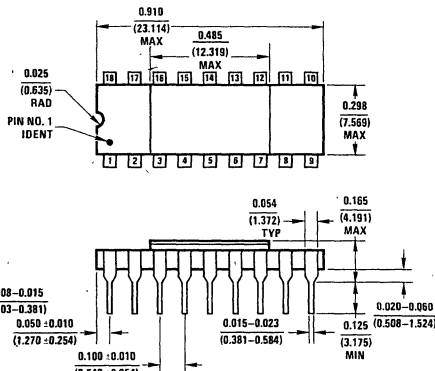
| | | NSC | Signetics | Fairchild | Motorola | TI | RCA | Silicon General | AMD | Raytheon |
|--|---|-----|-----------|-----------|----------|----|-----|-----------------|-----|----------|
|  <p>TO-202 (D-40, Durawatt)</p> | P | | | | | KD | | | | |
|  <p>"SGS" Type Power DIP</p> | S | | BP | | | | | | | |
|  <p>TO-220</p> | T | U | U | | | KC | | | | |
|  <p>Low Temperature Glass Hermetic Flat Pack</p> | W | | F | F | | W | | FM | | |
|  <p>TO-92 (Plastic)</p> | Z | S | W | P | | LP | | | | |



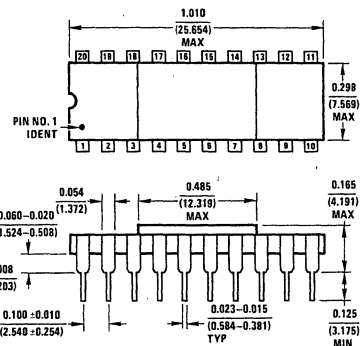
NS Package D14E
14-Lead Cavity DIP (D)
(Side Brazed)



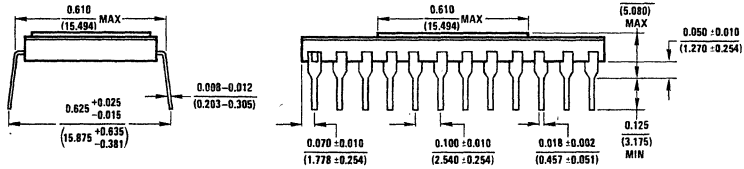
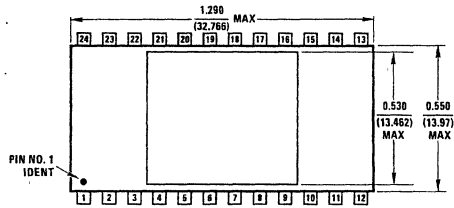
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16-Lead Cavity DIP (D)
(Side Brazed)



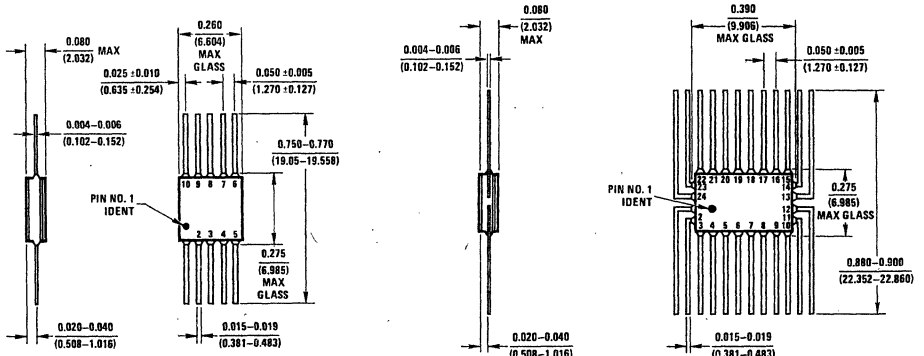
NS Package D18A
18-Lead Cavity DIP (D)
(Side Brazed)



NS Package D20A
20-Lead Cavity DIP (D)

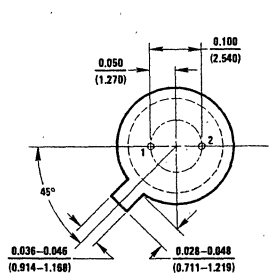
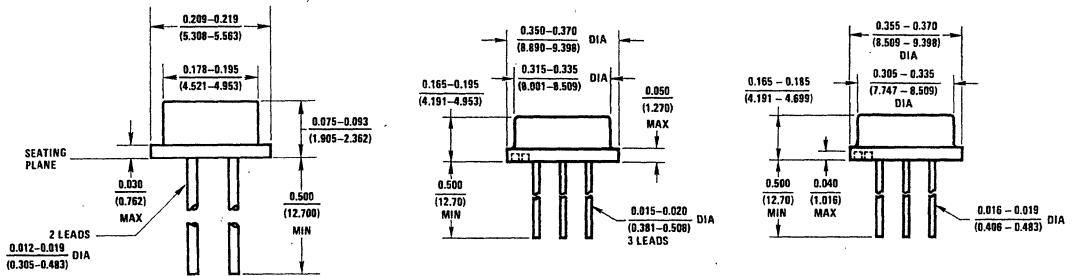


NS Package D24A
24-Lead Cavity DIP (D)

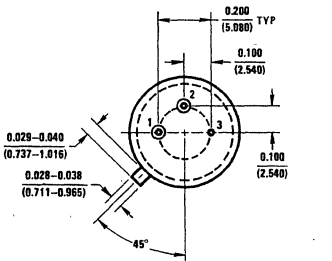


NS Package F10A
10-Lead Flat Package (F)

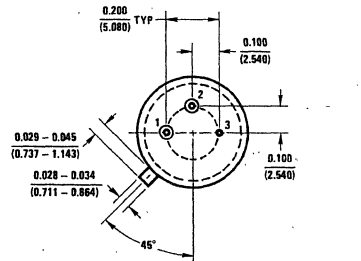
NS Package F24A
24-Lead Flat Package (F)



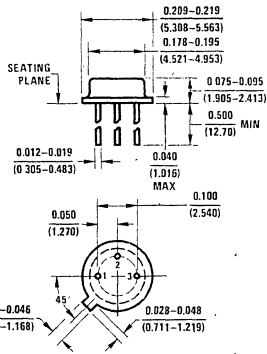
NS Package H02A
2-Lead TO-46 Metal Can Package (H)



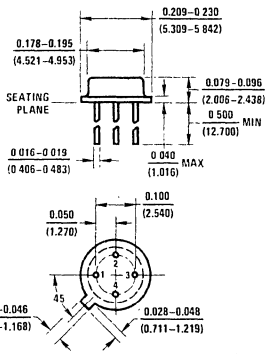
NS Package H03A
3-Lead TO-39 Metal Can Package (H)



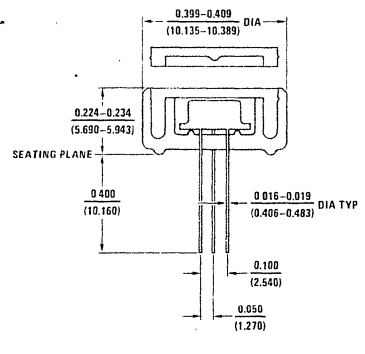
NS Package H03B
3-Lead TO-5 Metal Can Package (H)



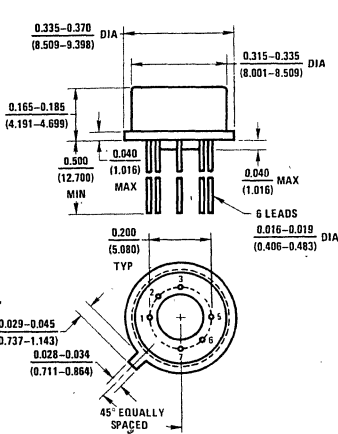
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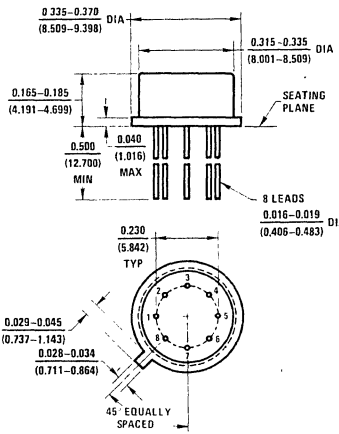
NS Package H04A
4-Lead TO-46 Metal Can Package (H)



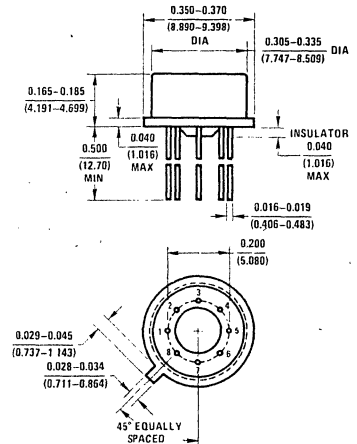
NS Package H04D
Thermal Shield for H04A



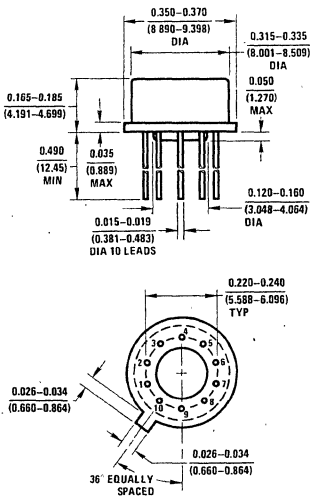
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6-Lead TO-5 Metal Can Package (H)



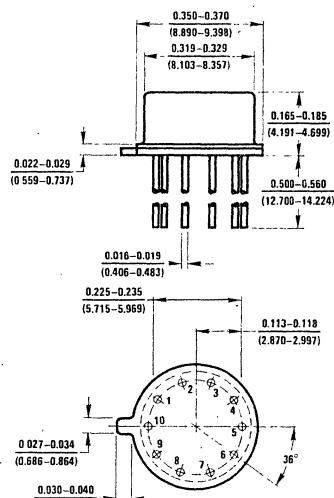
NS Package H08A
8-Lead TO-5 Metal Can Package (H)



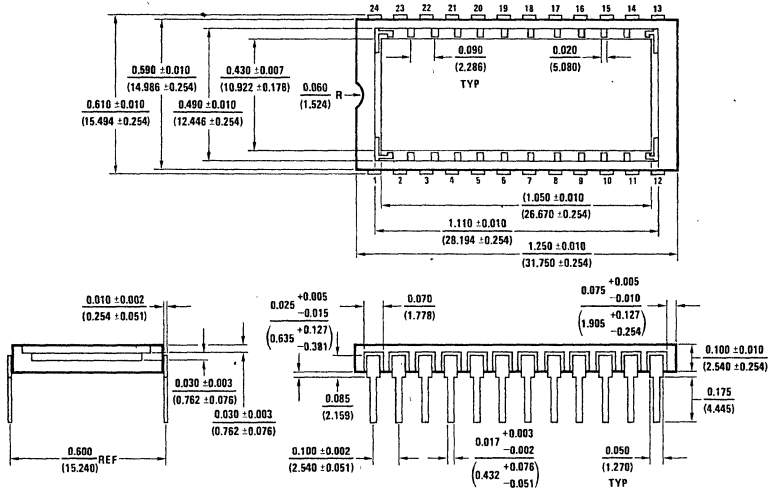
NS Package H08C
8-Lead TO-5 Metal Can Package (H)



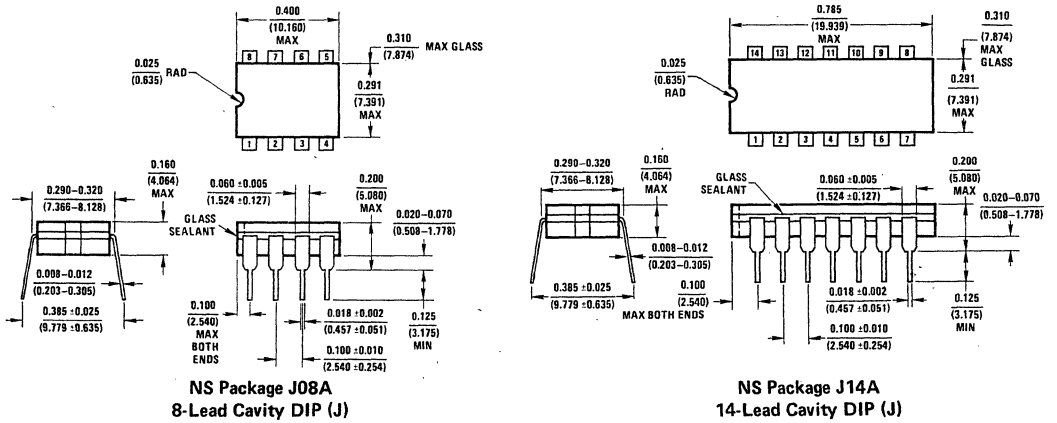
NS Package H10C
10-Lead TO-5 Metal Can Package (H)
(Low Profile)



NS Package H10D
10-Lead TO-5 Metal Can Package (H)

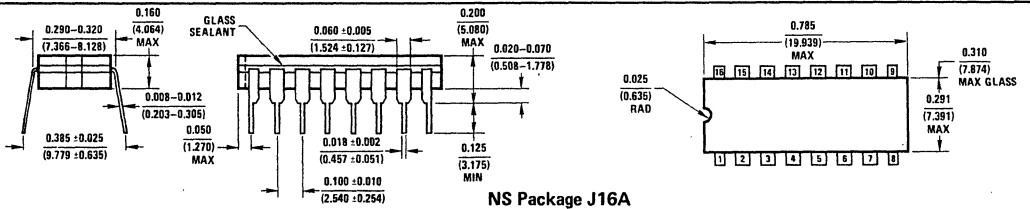


NS Package HY24A
24-Lead Cavity DIP (J)
(Hybrid Side Brazed)

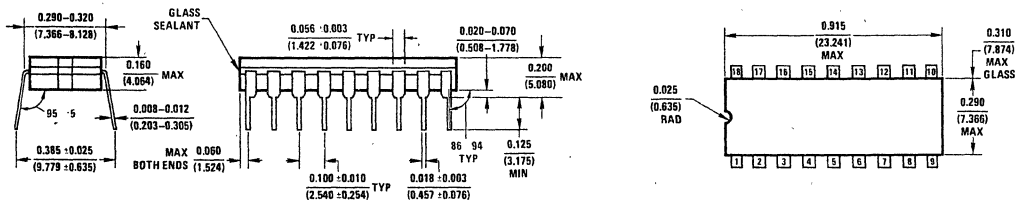


NS Package J08A
8-Lead Cavity DIP (J)

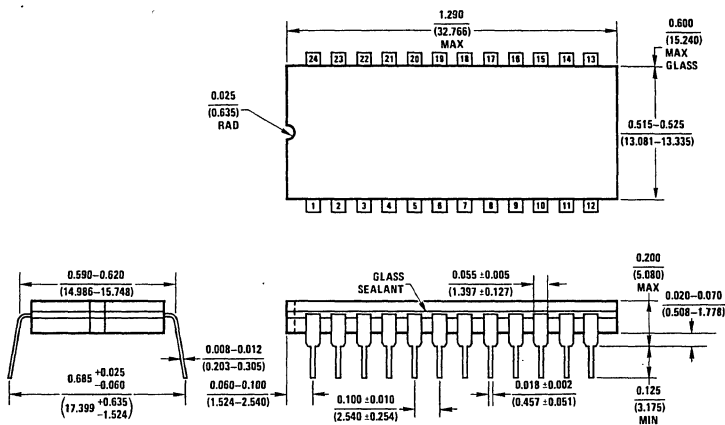
NS Package J14A
14-Lead Cavity DIP (J)



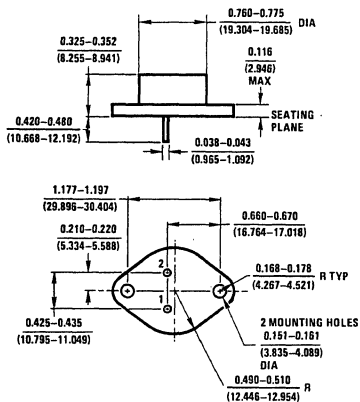
NS Package J16A
16-Lead Cavity DIP (J)



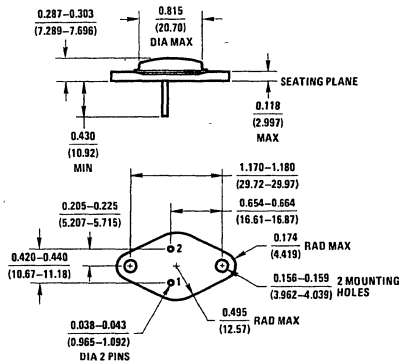
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18-Lead Cavity DIP (J)



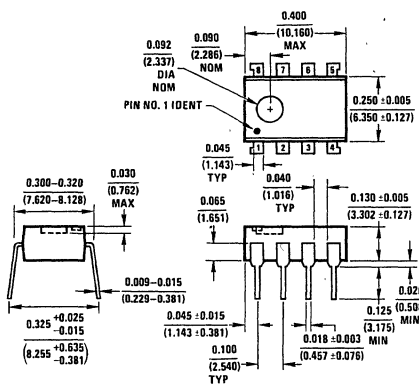
NS Package J24A
24-Lead Cavity DIP (J)



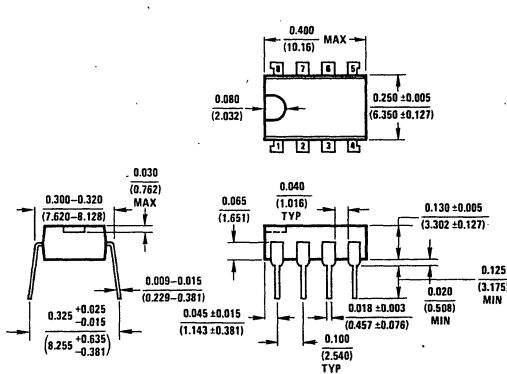
NS Package K02A
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(Steel)



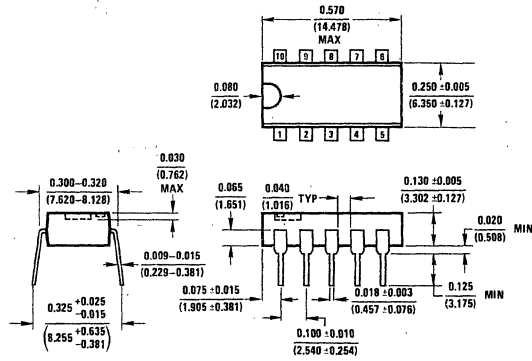
NS Package KC02A
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(Aluminum)



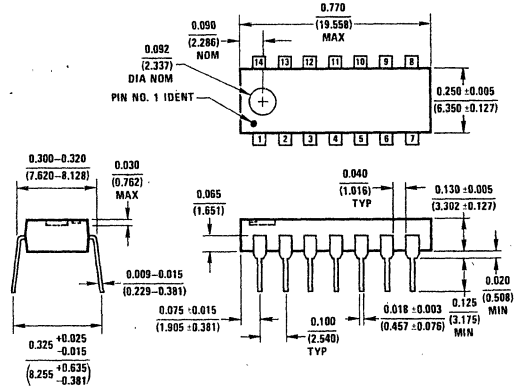
NS Package N08A
8-Lead Molded Mini-DIP (N)



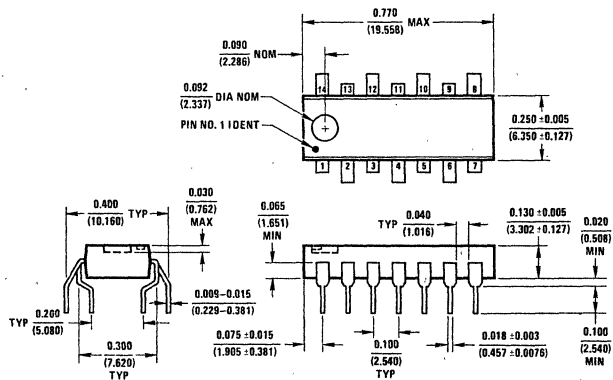
NS Package N08B
8-Lead Molded Mini-DIP (N)



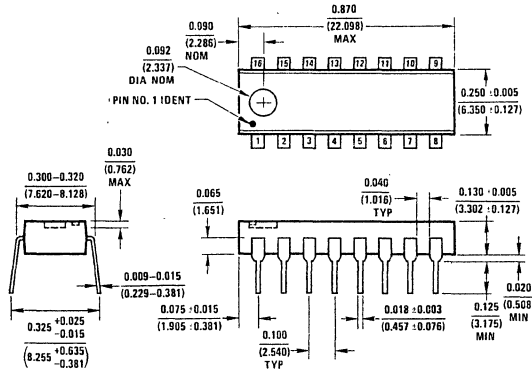
NS Package N10B
10-Lead Molded DIP (N)



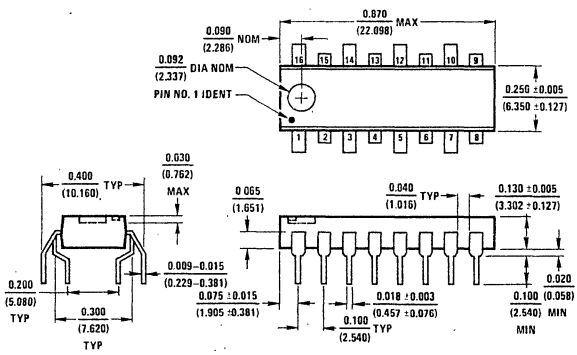
NS Package N14A
14-Lead Molded DIP (N)



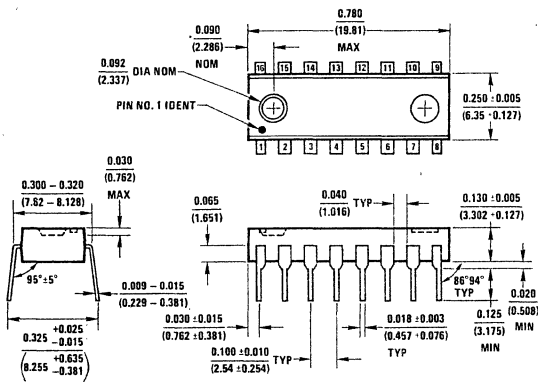
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14-Lead Molded DIP (N-01)
(Staggered Leads)



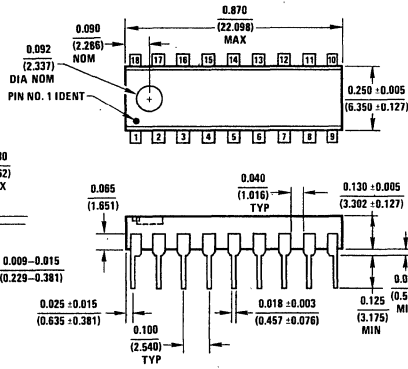
NS Package N16A
16-Lead Molded DIP (N)



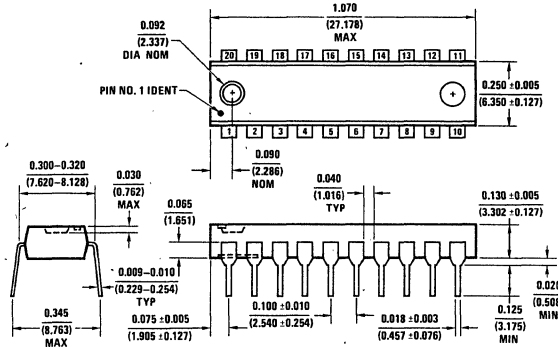
NS Package N16C
16-Lead Molded DIP (N-01)
(Staggered Leads)



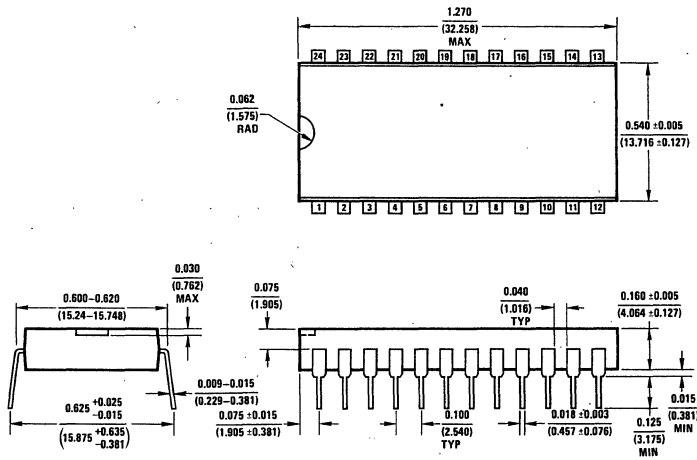
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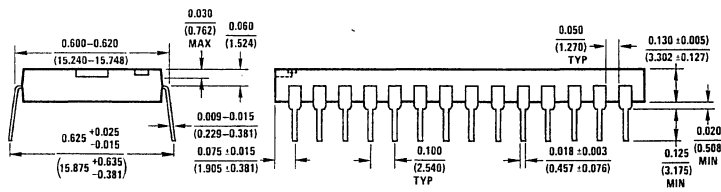
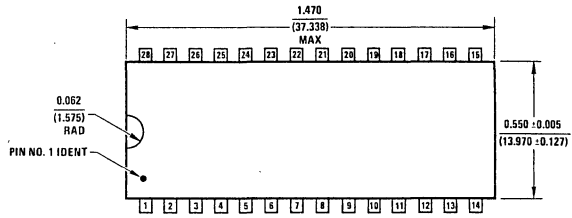
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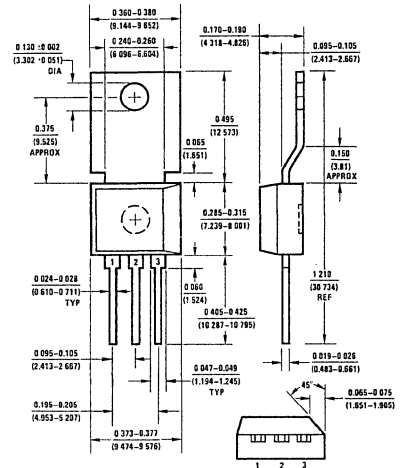
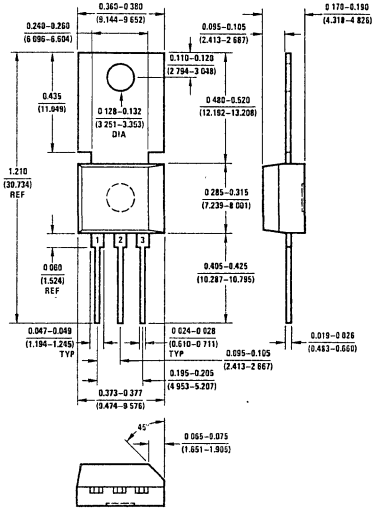
NS Package N20A
20-Lead Molded DIP (N)



NS Package N24A
24-Lead Molded DIP (N)

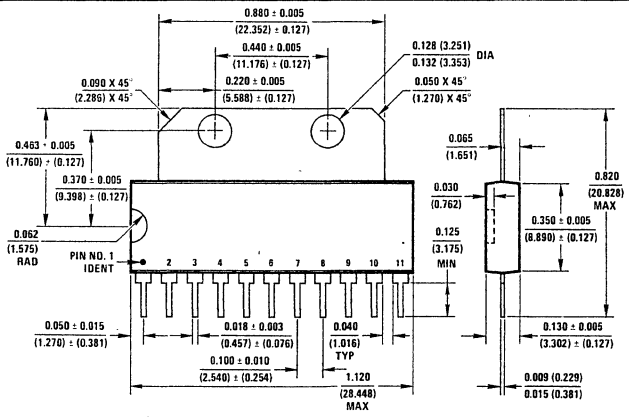


NS Package N28A
28-Lead Molded DIP (N)

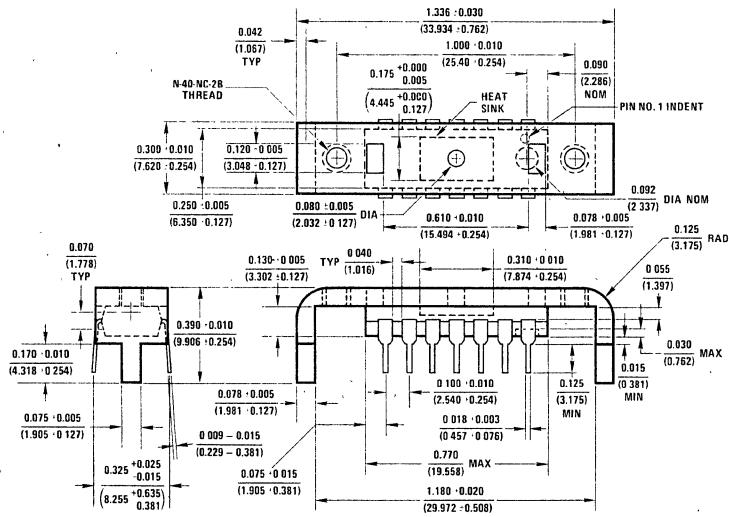


NS Package P03A
3-Lead TO-202 Power Package (P)

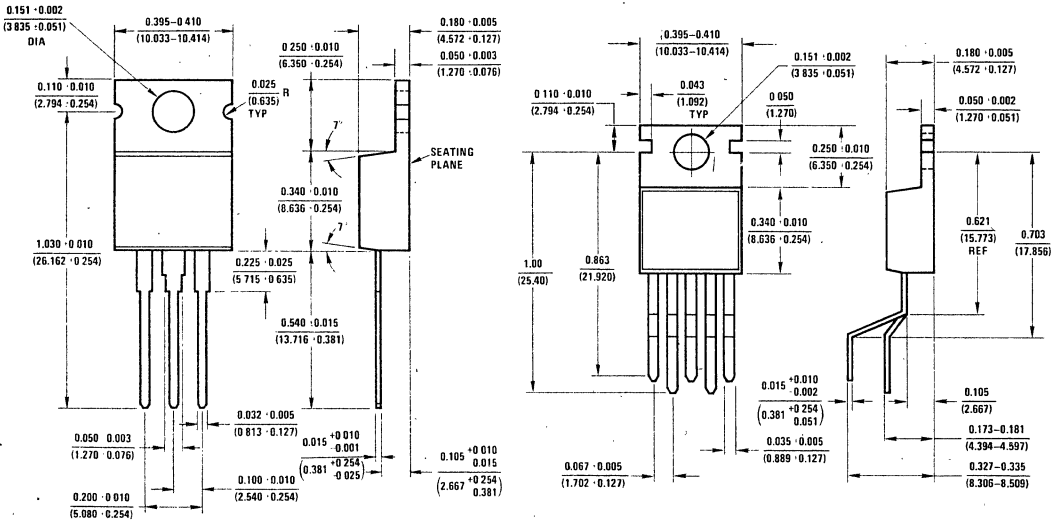
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Tab Formed 3-Lead
TO-202 Power Package (P)



NS Package P11A
11-Lead Single-In-Line Package (P)

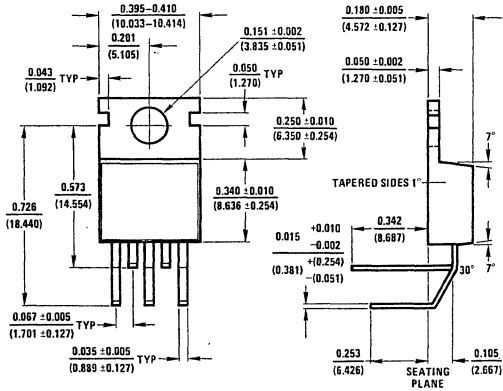


NS Package S14A
14-Lead "SGS" Type Power DIP (S)

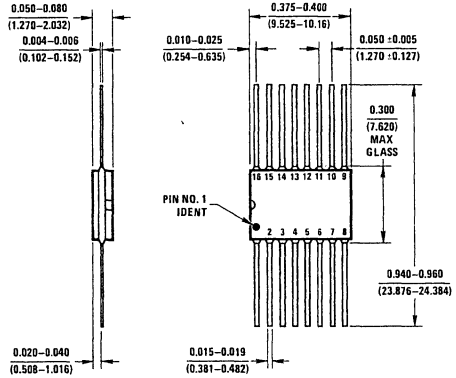


NS Package TO3B
3-Lead TO-220 Power Package (T)

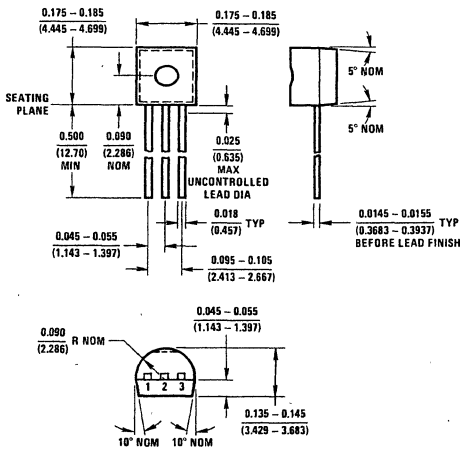
NS Package TO5B
5-Lead TO-220 Power Package (T)



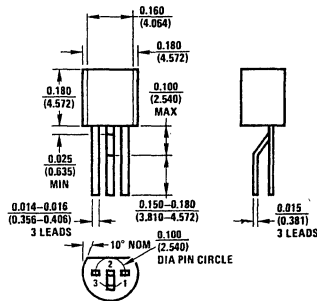
NS Package T05C
5-Lead TO-220 Power Package (T)



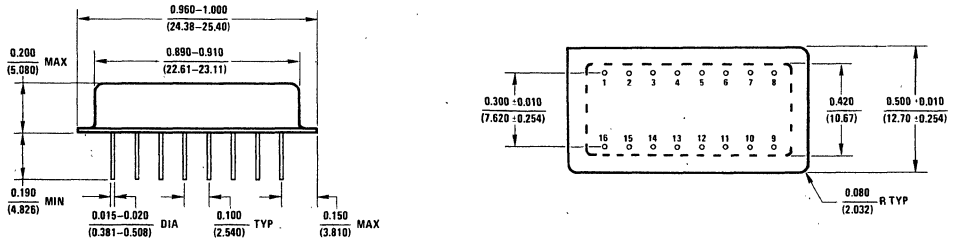
NS Package W16A
16-Lead Flat Package (W)



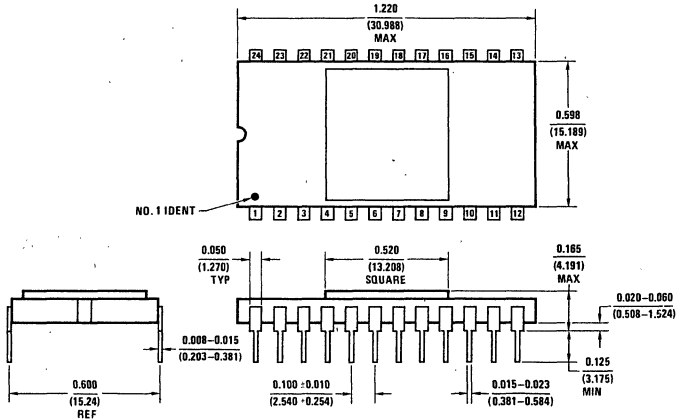
NS Package Z03A
3-Lead TO-92 Plastic Package (Z)



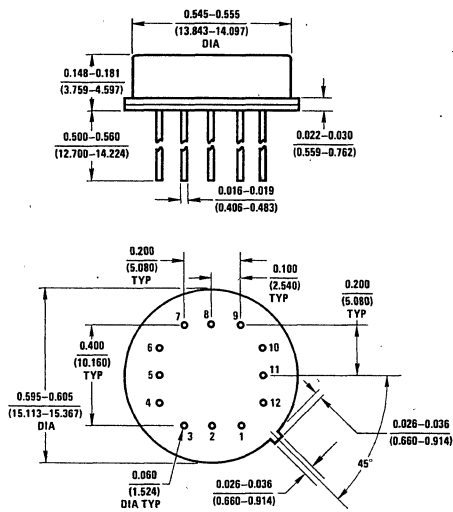
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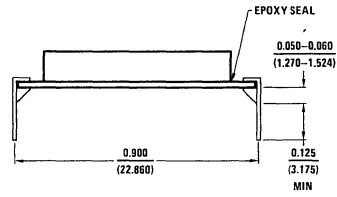
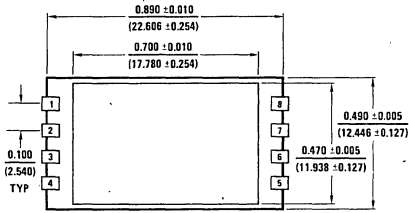
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16-Lead Cavity DIP (D)



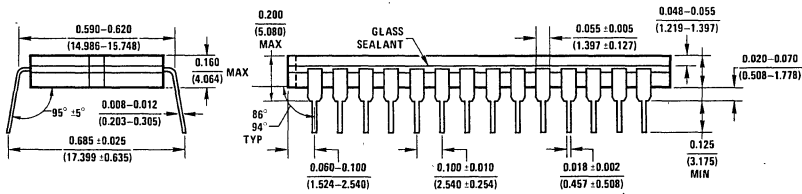
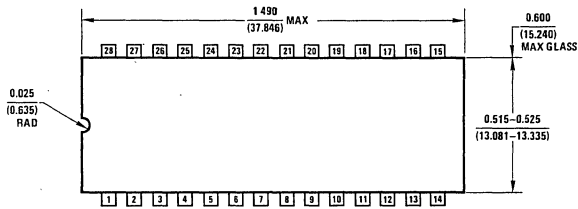
NS Package D24C
24-Lead Cavity DIP (D)



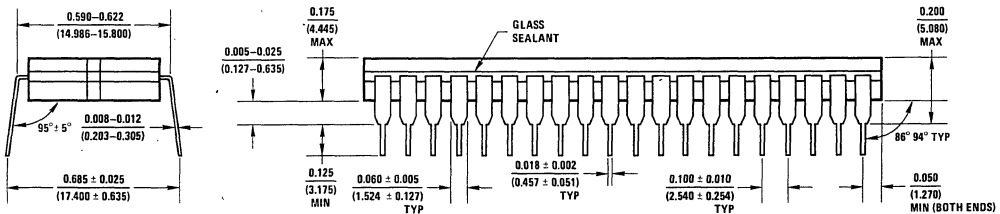
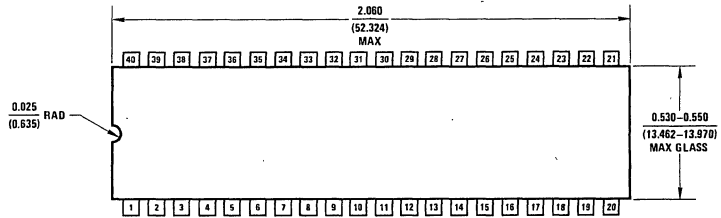
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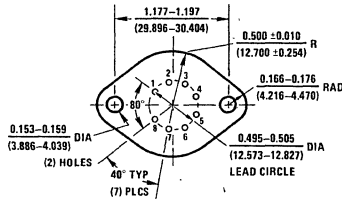
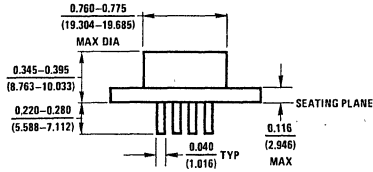
NS Package HY08A
8-Lead Cavity DIP (J) (Hybrid)



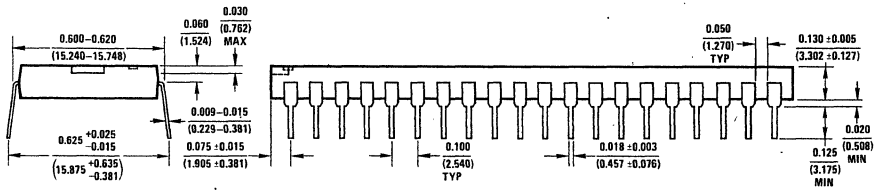
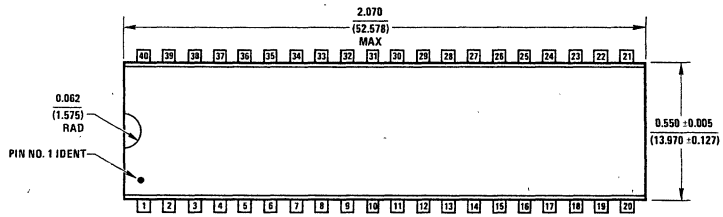
NS Package J28A
28-Lead Cavity Dip (J)



NS Package J40A
40-Lead Cavity DIP (J)



NS Package K08A
8-Lead TO-3 Metal Can Package (K)



NS Package N40A
40-Lead Molded DIP (N)

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