



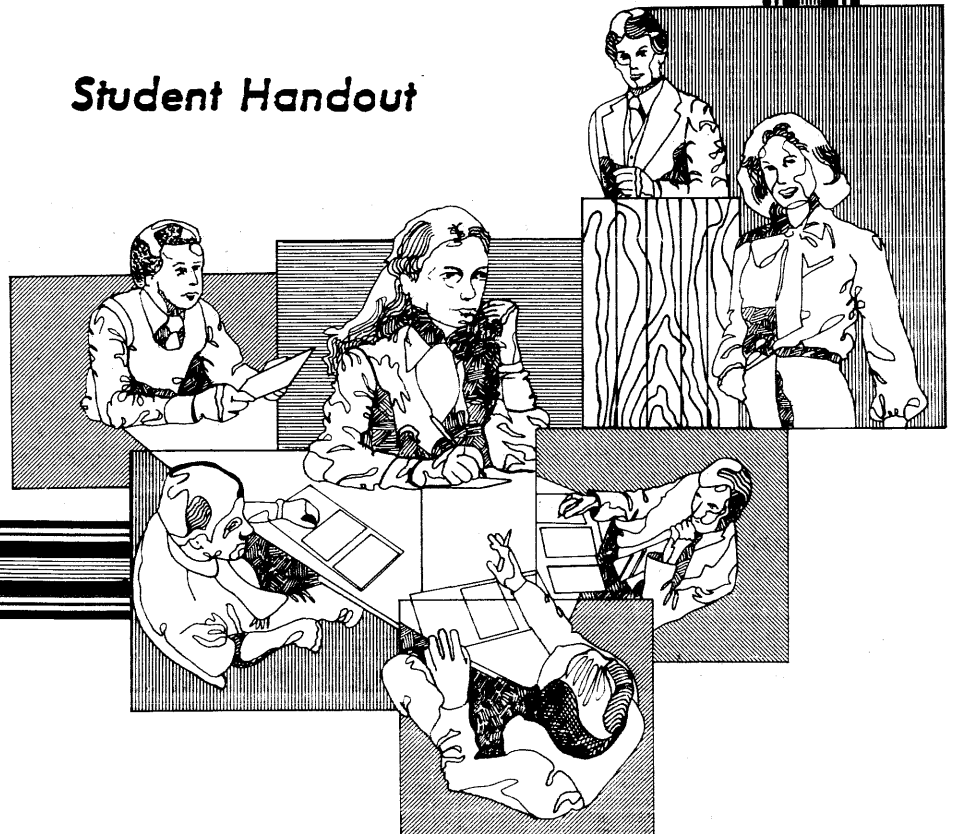
CONTROL DATA
CORPORATION

SEMINARS

Course No. FH4010-1

NOS Analysis

Student Handout



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NOS Analysis

Student Handout

REVISION C



**CONTROL DATA
CORPORATION**

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GENERAL DESCRIPTION

COURSE TITLE: NOS Analysis

COURSE NUMBER: FH4010

COURSE LENGTH: 10 days

DESCRIPTION:

This course is designed to train the student so that he/she will be conversant in NOS Operating System concepts and its internal workings. The course materials constitute a detailed overview of NOS and are not intended to make the student an "expert" in the details of any one system area.

This is primarily a lecture course. Student assignments consisting of question sets are provided for most of the topics covered by this course.

A set of basic topics should be covered as per the course outline. The block schedule does have "optional" periods that may be filled with one of the optional lessons (to suit the needs of the class) or used as a buffer against running behind "schedule".

PREREQUISITES:

Knowledge of NOS Job Control, NOS Advanced Coding, PP COMPASS.

The student should be familiar with NOS from a user viewpoint in order to be able to grasp the internal concepts presented in the course.

**NOS ANALYSIS
COURSE CHART**

HOUR	DAY 1	DAY 2	DAY 3	DAY 4	DAY 5
1	Administrative Details	CMR (continued)	Laboratory on CMR	Laboratory on Monitors	Laboratory on Storage Move, PPR, Mass Storage
	NOS Overview			Storage Move	
2	System Maintenance Concepts				
			3	Exchange Jump	Mass Storage Concepts
4	Central Memory Resident (CMR)				
			5	Delay/Recall	Display Console Driver
6					

**NOS ANALYSIS
COURSE CHART (CONTINUED)**

HOUR	DAY 6	DAY 7	DAY 8	DAY 9	DAY 10
1	Administrative Details	Job Processing (continued)	Laboratory on Job Processing, Accounting, Perm Files	Laboratory on Resources, Tape Subsystem Unit Record, Q Mgmt	Laboratory on Communications Subsystems
	Laboratory on DS/Recovery				
2	Job Processing	Accounting	Resource Control	Networks Overview	Multimainframe
3			Magnetic Tape Subsystem	Time Sharing Subsystem	
4		Permanent Files		Unit Record	Remote Batch Facility
5			File Routing Q Management		
6			Other Monitor Requests	Transaction Facility	Critique Administrative Details
			System Control Point		

NOS ANALYSIS
COURSE OUTLINE

<u>LESSON</u>	<u>TOPIC</u>	<u>LENGTH (hours)</u>
1	NETWORK OPERATING SYSTEM OVERVIEW	1
2	SYSTEM MAINTENANCE CONCEPTS	1-1/2
3	CENTRAL MEMORY RESIDENT Low Core Pointers Control Point Area PP Communication Area Dayfile Buffers and Pointers FNT Job Control Block Libraries and Directories	6
4	EXCHANGE JUMP	2-1/2
5	DELAY AND RECALL	1/2
6	CPUMTR	2-1/2
7	MTR	1-1/2
8	STORAGE MOVE	1-1/2
9	PP RESIDENT	1-1/2
10	MASS STORAGE CONCEPTS MST/TRT Mass Storage Driver ECS	2
11	DEADSTART AND RECOVERY THEORY Hardware Deadstart Deadstart Process Mass Storage Recovery System Checkpoints	2
12	LOGICAL INPUT/OUTPUT (CIO)	1
13	DISPLAY CONSOLE DRIVER	1
14	JOB PROCESSING Scheduling Job Initiation Special Entry Point Processing Control Card Processing Error Processing	6-1/2

NOS ANALYSIS
COURSE OUTLINE (Continued)

<u>LESSON</u>	<u>TOPIC</u>	<u>LENGTH</u> (hours)
14	JOB PROCESSING (Continued) Job Completion Field Length Management Rollin/Rollout DMP= and SSJ= Processing Subsystem Scheduling	
15	ACCOUNTING System Resource Unit Validation Files Project Profile Files	2
16	PERMANENT FILES User Index Mappings Indirect and Direct Access Files Catalog and Permit Entries	2
17	RESOURCE CONTROL Deadlock Prevention Resource Files	1
18	MAGNETIC TAPE SUBSYSTEM (MAGNET)	1
19	UNIT RECORD SUBSYSTEM (BATCHIO)	1/2
20	FILE ROUTING AND QUEUE MANAGEMENT	1/2
21	OTHER MONITOR (RA+1) REQUESTS	1/2
22	SYSTEM CONTROL POINT FACILITY	1/2
23	NETWORK PRODUCTS OVERVIEW	1
24	TIME SHARING SUBSYSTEM	1
25	REMOTE BATCH SUBSYSTEM (EI200)	1
26	TRANSACTION SUBSYSTEM (TRANEX/TAF)	1
27	MULTIMAINFRAME	2
28	MASS STORAGE SUBSYSTEM OVERVIEW	1

MATERIALS

STUDENT MATERIAL

PUBLICATION NUMBER

Student Handout NOS Reference Manual, Volume 1	60435400
NOS Reference Manual, Volume 2	60445300
NOS System Programmer's Instant	60449200
NOS Internal Maintenance Specification (IMS)	60454300
NOS Installation Handbook	60435700
NOS Operator's Guide	60435600
NOS System Maintenance Reference Manual	60455380
CYBER Hardware Reference Manual	60456100
MODIFY Reference Manual	60450100
Network Definition Language Reference Manual	60480000
Network Access Methods Reference Manual	60499500

Manual Abbreviations

RM = Reference Manual OG = Operator's Guide IHB = Installation Handbook SMRM = System Maintenance Reference Manual

COMPUTER TIME

Optional. The instruction of this course requires no computer time. However, the instructor may choose to use hands-on machine time for examples, and so forth.

NOMENCLATURE

The nomenclature used to reference sections and pages in the various reference manuals is as follows.

Reference Manual: volume-chapter-page1-page2. Individual pages may be listed as page1,page2,page3,... When the entire section is reference material, no pages will be given.

Installation Handbook: part-section-page1-page2. Individual pages may be listed as page1,page2,page3,... When the entire section is reference material, no pages will be given.

Others: All other manuals will be section-pages, where the page notation is as given above.

LESSON 1
NETWORK OPERATING SYSTEM OVERVIEW

LESSON PREVIEW:

This lesson overviews the Network Operating System, its evolution, its major design philosophies, and its use of the CYBER 170 style hardware.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe the evolution of the Network Operating System from its early Chippewa origins to the present day NOS system.
- Describe the control point concept and the meaning of the Reference Address (RA), Field Length (FL) and Program Address (P).
- Identify major NOS system components.
- List the types of files known to NOS and detail how each is used by the system and/or user.

REFERENCES:

NOS IMS - Chapters 1 and 11 NOS Reference Manual, 1-1, 1-2 CYBER 170 Hardware Reference Manual

SUPPLEMENTAL TEXT: HISTORY OF NOS

The CHIPPEWA operating system was the original developmental operating system for Control Data's 6000 computer line. Although there are many descendants of the CHIPPEWA system, Control Data is now primarily concerned with three: NOS, NOS/BE, and CMSE. Figure I-16 shows Control Data 6000, CYBER 70, and CYBER 170 Operating System genealogy.

CMSE (Common Maintenance Software Executive) is a operating system- like executive used by Engineering Services to maintain 6000, CYBER 70, CYBER 170 hardware.

NOS/BE evolved from the SCOPE operating system. SCOPE was the name given to the productized version of the CHIPPEWA operating system. Originally CDC planned to make SIPROS the standard 6000 operating system, but when it was delayed and a sizable customer base began using the CHIPPEWA system, SIPROS was abandoned and SCOPE became the major 6000 operating system in 1965.

Several major evolutionary milestones are notable for NOS/BE. In 1967, SCOPE 3.0 was released. This release represented a significant extension of the features previously available. By 1970, when SCOPE 3.3 was released, performance enhancements were needed. The entire I/O system was restructured at that time. In 1972, SCOPE 3.4 was released. This system added significant new features, including the record manager. The final node in the SCOPE to NOS/BE evolution occurred in 1976, with SCOPE being deemphasized and development being directed toward the CYBER 170 mainframe and the NOS/BE operating system.

KRONOS, the father of NOS, had its origin in the CHIPPEWA operating system as well. Unlike SCOPE, it did not immediately become a widely used product. It spent several years, under the name "MACE", as a high-performance benchmark system before it emerged in 1969 as the Time Shared Operating System (TSOS). TSOS was developed for United Computing Systems, a large successful commercial time-sharing company.

The name KRONOS was first used in 1970. KRONOS 1 was the product CYBERNET Services used to expand their existing remote batch capability into a viable time-sharing service. The major emphasis of this productized version of CDC's high-performance operating system was reliability.

KRONOS 2.0, released in 1971, was primarily an extension to the features of KRONOS 1. This emphasis was continued into KRONOS 2.1, a feature rich version of KRONOS 2.0, released in 1973. KRONOS 2.1 incorporated the same product set and data management system as that other operating system (SCOPE), signalling the first real breakthrough in Control Data's movement to common products and operating systems. This release also included the transaction processing subsystem TRANEX.

In 1974, with Control Data's introduction of the CYBER 170 computers and a thrust toward networks, KRONOS begat NOS, the Network Operating System. The first release of NOS consisted of a variety of features primarily directed to support the CYBER 170 RAM (Reliability, Availability, Maintainability) design, to increase its usability (particularly for CYBERNET Services), and to provide more commonality with the other operating system.

The second release of NOS in March, 1976, brought multi-mainframe support into NOS.

The third release of NOS in December, 1976, introduced Control Data's first Network Products offering with the Remote Batch Facility (RBF) and Transaction Facility (TAF, nee TRANEX) applications to the Network Access Method (NAM).

The fourth release of NOS in 1978 expanded upon the networks offerings with the Interactive Facility (IAF, nee TELEX) application. In addition to networks, this release of NOS provides support of full track recording on mass storage devices, and a variety of RAM enhancements.

The fifth release of NOS in 1979 introduced support of the CYBER 176, support of the 7155 mass storage controller and 885 disk drives, and system deadstart from mass storage.

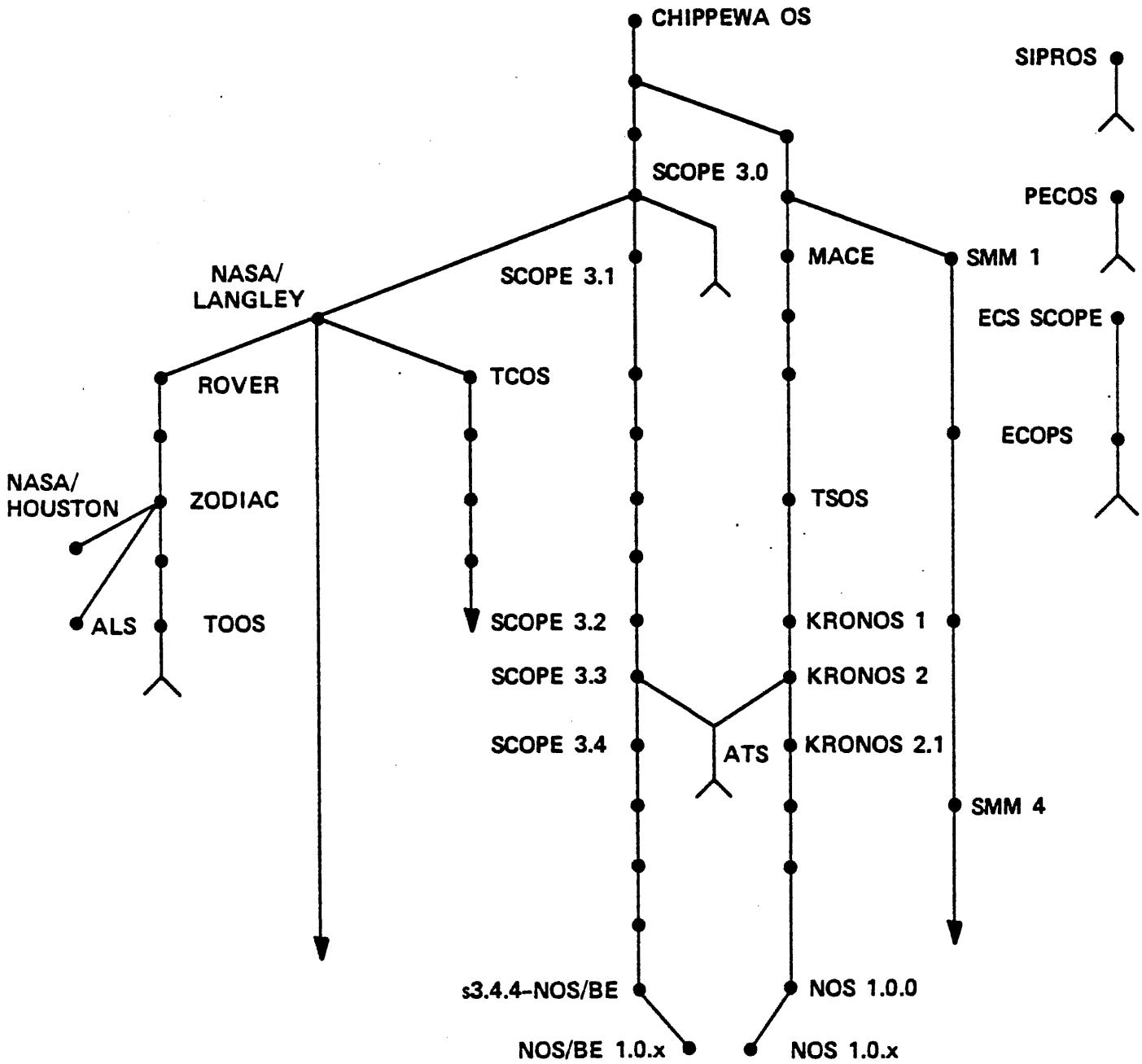
NOS continues enhancement into the 1980s, with a major release on approximately a yearly basis.

System Naming Conventions

- Operating Systems and the Product Set are generally referred to by a version number and/or the PSR Summary level that corresponds to its release. The nomenclature for NOS is as follows.

	Version	PSR level	Date
	-----	-----	----
KRONOS	2.1.1	387	12/74
NOS	1.0	404	6/75
KRONOS	2.1.2	404	6/75
NOS	1.1	419	3/76
NOS	1.2	439	12/76

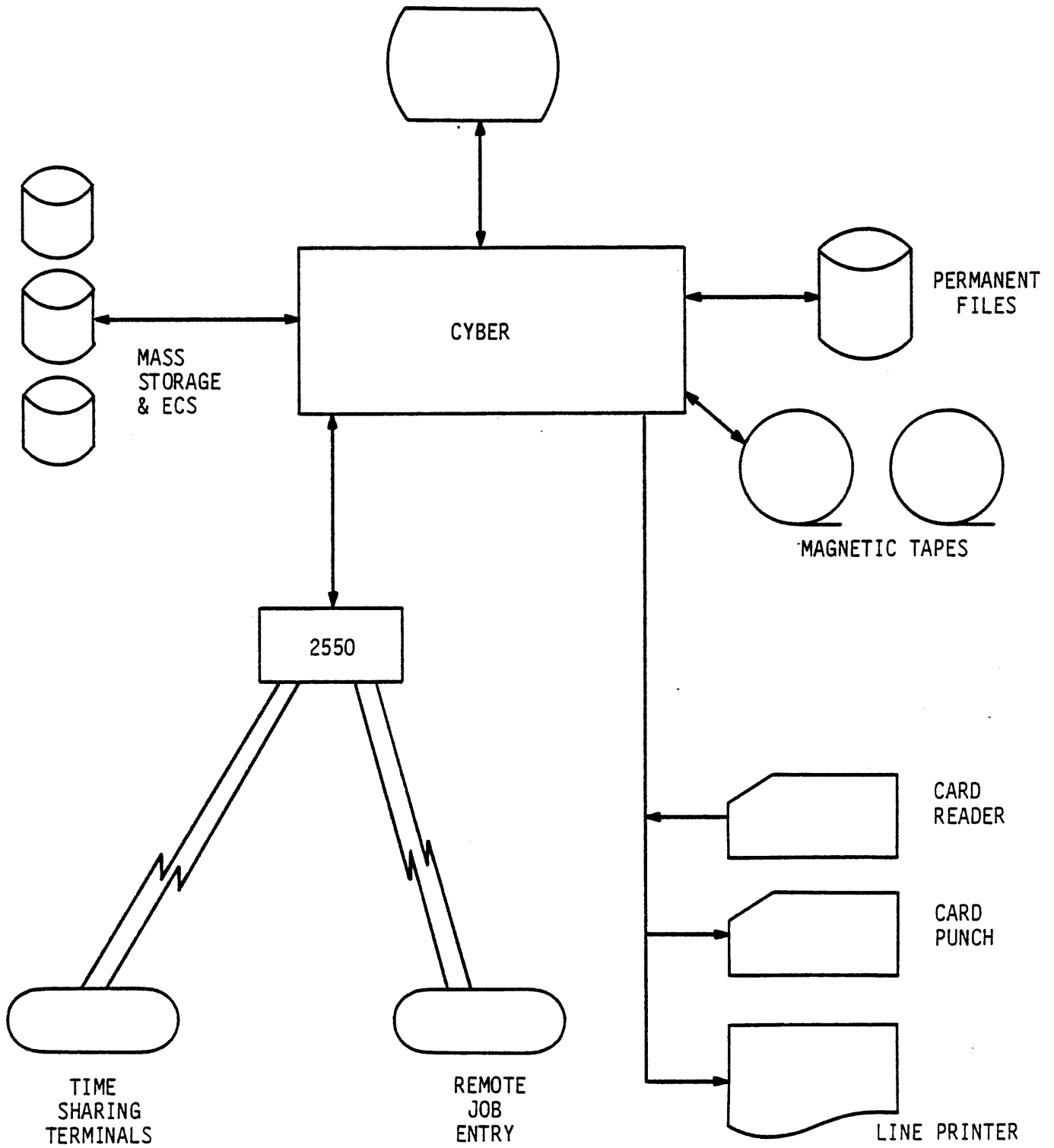
COMMON O/S MODULES
OPERATING SYSTEM GENEALOGY



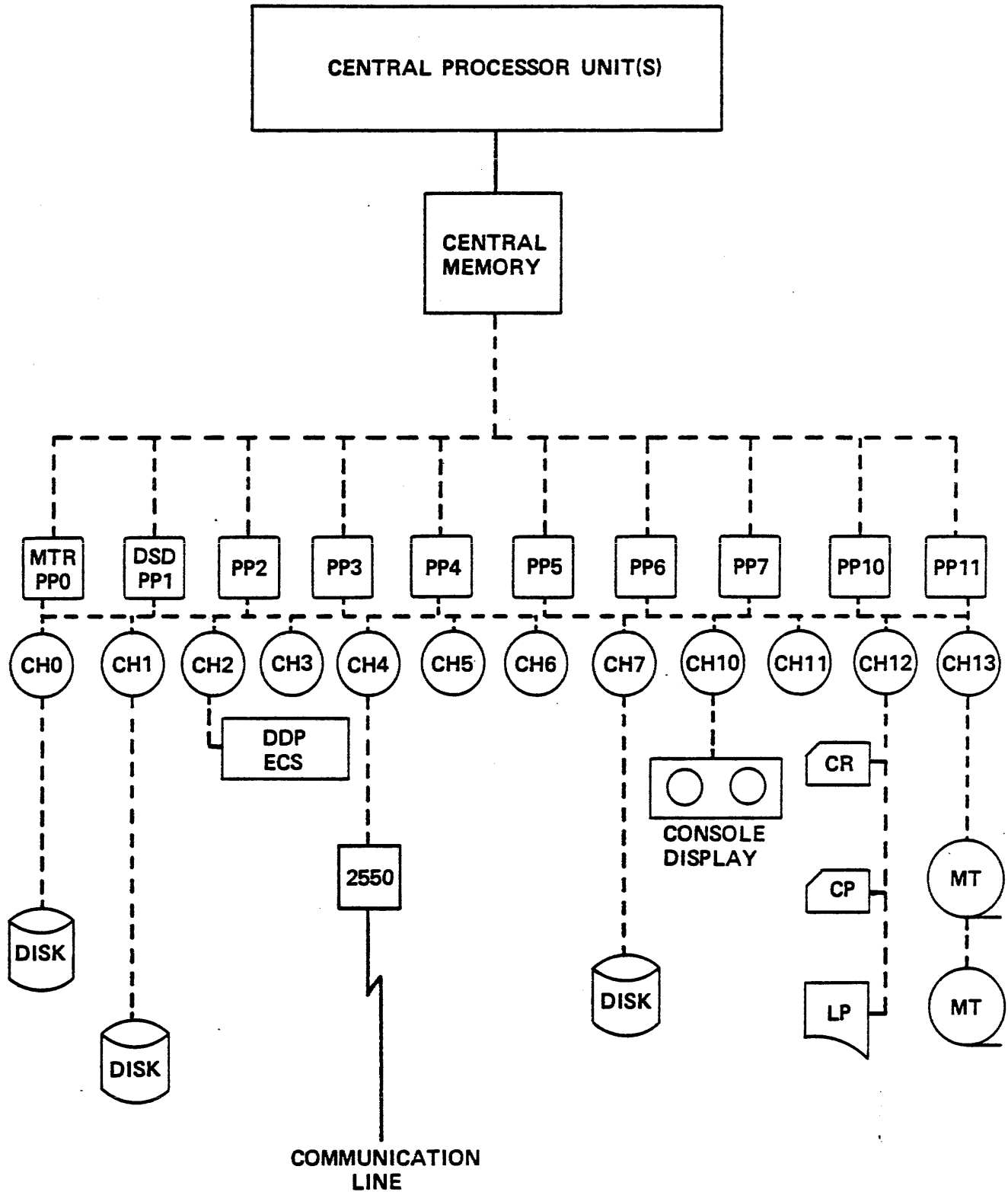
COMMON O/S MODULES
KRONOS/NOS HISTORY

1966	MACE	<ul style="list-style-type: none">● BENCHMARK SYSTEM● EMPHASIS ON PERFORMANCE
1969	TSOS	<ul style="list-style-type: none">● INTERACTIVE TIME SHARING● EMPHASIS ON PERFORMANCE AND RELIABILITY
1970	KRONOS 1	<ul style="list-style-type: none">● CDC PRODUCT FROM TSOS● EMPHASIS ON RELIABILITY
1971	KRONOS 2.0	<ul style="list-style-type: none">● MAJOR FEATURE ENHANCEMENTS● EMPHASIS ON FEATURES
1973	KRONOS 2.1	<ul style="list-style-type: none">● SCOPE 3.4 PRODUCT SET● TRANEX● EMPHASIS ON FEATURES
1974	NOS 1.0	<ul style="list-style-type: none">● 170 FEATURES● COMMON PRODUCT SET SUPPORT● EMPHASIS ON FEATURES
1976	NOS 1.1	<ul style="list-style-type: none">● MULTIMAINFRAME SUPPORT● 844-4X SUPPORT
1976	NOS 1.2	<ul style="list-style-type: none">● RBF● TAF
1978	NOS 1.3	<ul style="list-style-type: none">● IAF● FULL TRACKING● USER ACCESS TO ECS
1979	NOS 1.4	<ul style="list-style-type: none">● 7155/885 SUPPORT● RMS DEADSTART● CTI SUPPORT● EXTENDED CHARACTER SET SUPPORT

SYSTEM CONSOLE



TYPICAL NOS CONFIGURATION



NOS OPERATING SYSTEM

EFFICIENT PROCESSING

- SYSTEM CONSOLE JOBS
- LOCAL BATCH
- REMOTE BATCH
- TIME SHARING

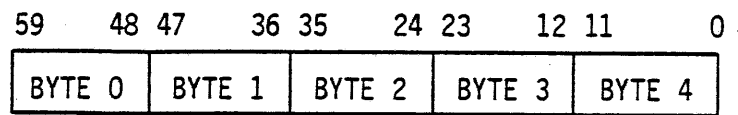
CPU (CENTRAL PROCESSING UNIT)

- COMPUTATIONAL TASKS
- NO INPUT/OUTPUT CAPABILITY
- COMMUNICATES WITH REST OF SYSTEM THRU CENTRAL MEMORY (RA+1 CALLS)
- USED FOR COMPILATIONS, ASSEMBLIES AND EXECUTION

PPU (PERIPHERAL PROCESSOR UNIT)

- UP TO 20 PPUS - INDEPENDENT
- PERFORMS TASKS FOR REQUESTING PROGRAMS
- 4K MEMORY (12 BIT, 1 BYTE WORDS)
- USED FOR CONTROL OF INPUT/OUTPUT, JOB SCHEDULING, ETC.

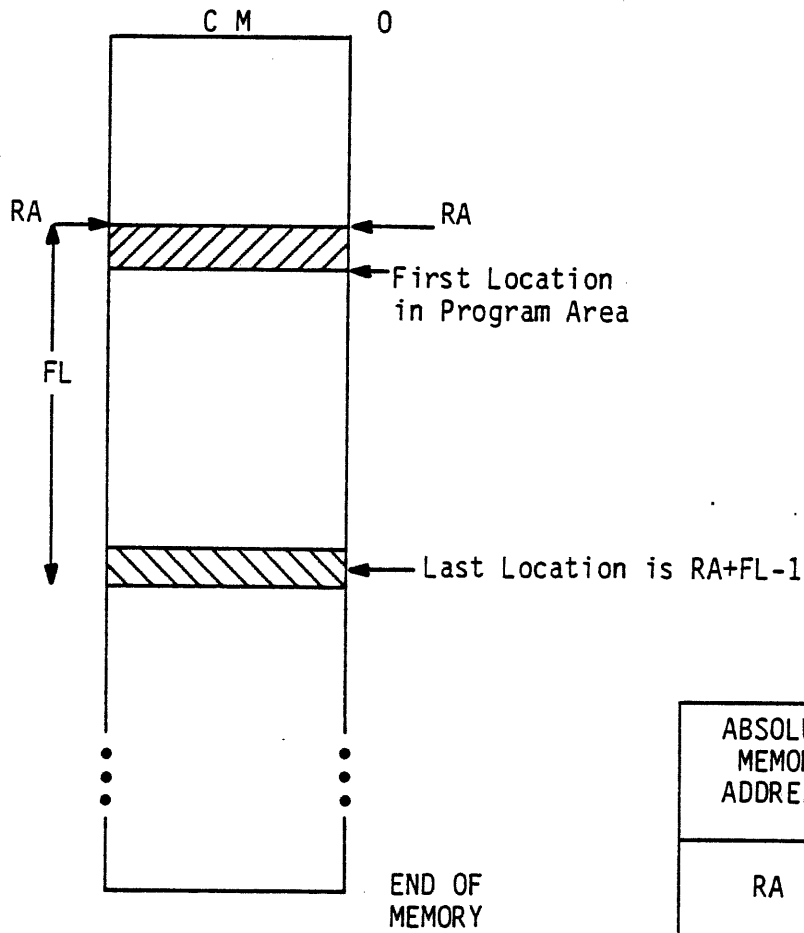
CENTRAL MEMORY



- 60 BITS LONG
- FIVE 12 BIT BYTES
- BYTES ARE NUMBERED 0-4 (LEFT TO RIGHT)
- 20 OCTAL DIGITS
- 10 DISPLAY CODED CHARACTERS
- 1 OCTAL DIGIT = 3 BITS

CENTRAL MEMORY USAGE

- RA = REFERENCE ADDRESS
Lower Limit of CM Field
- FL = FIELD LENGTH
Number of 60 Bit Words
- P = PROGRAM ADDRESS



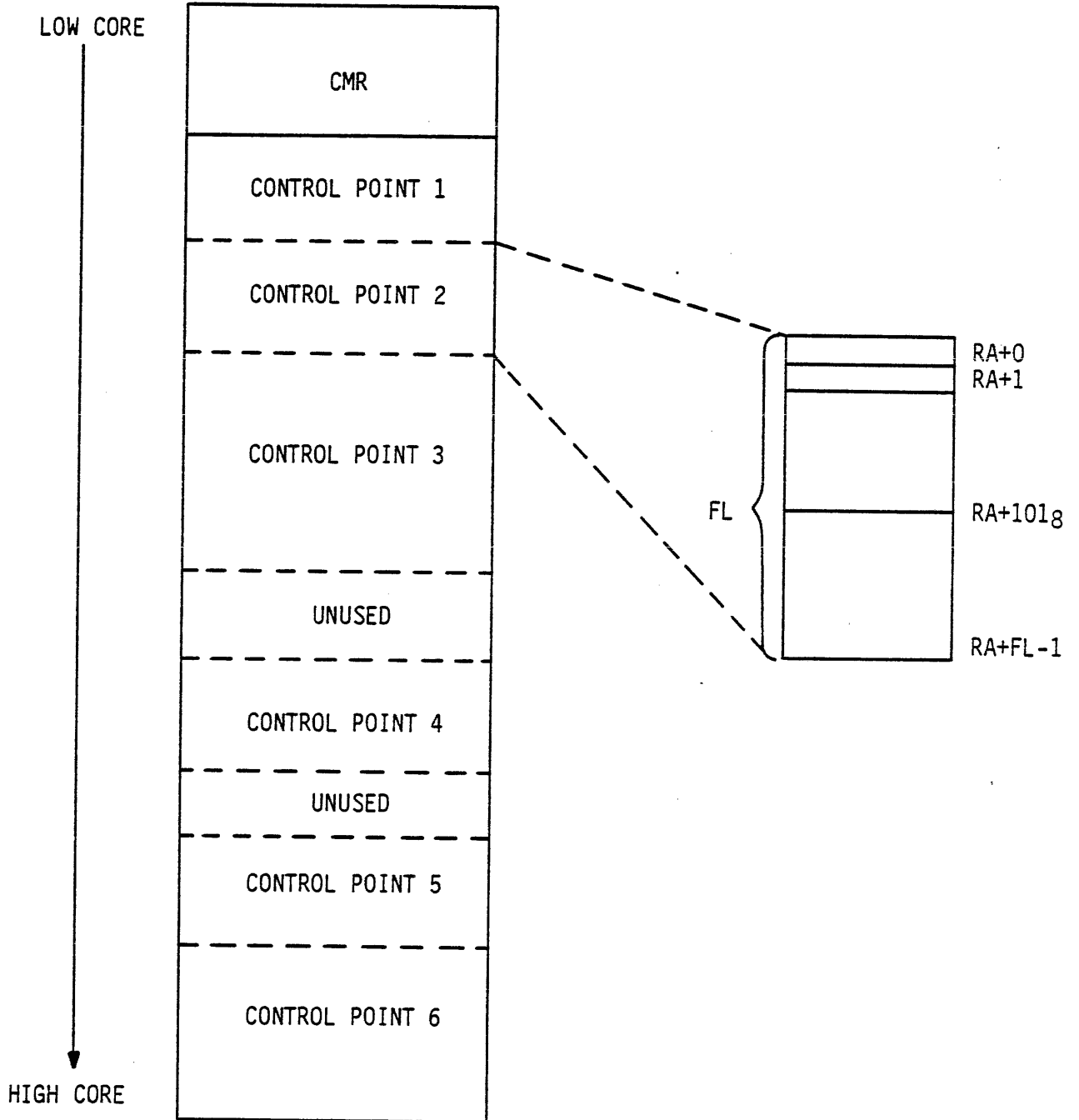
$$RA \leq RA+P < RA+FL$$

or

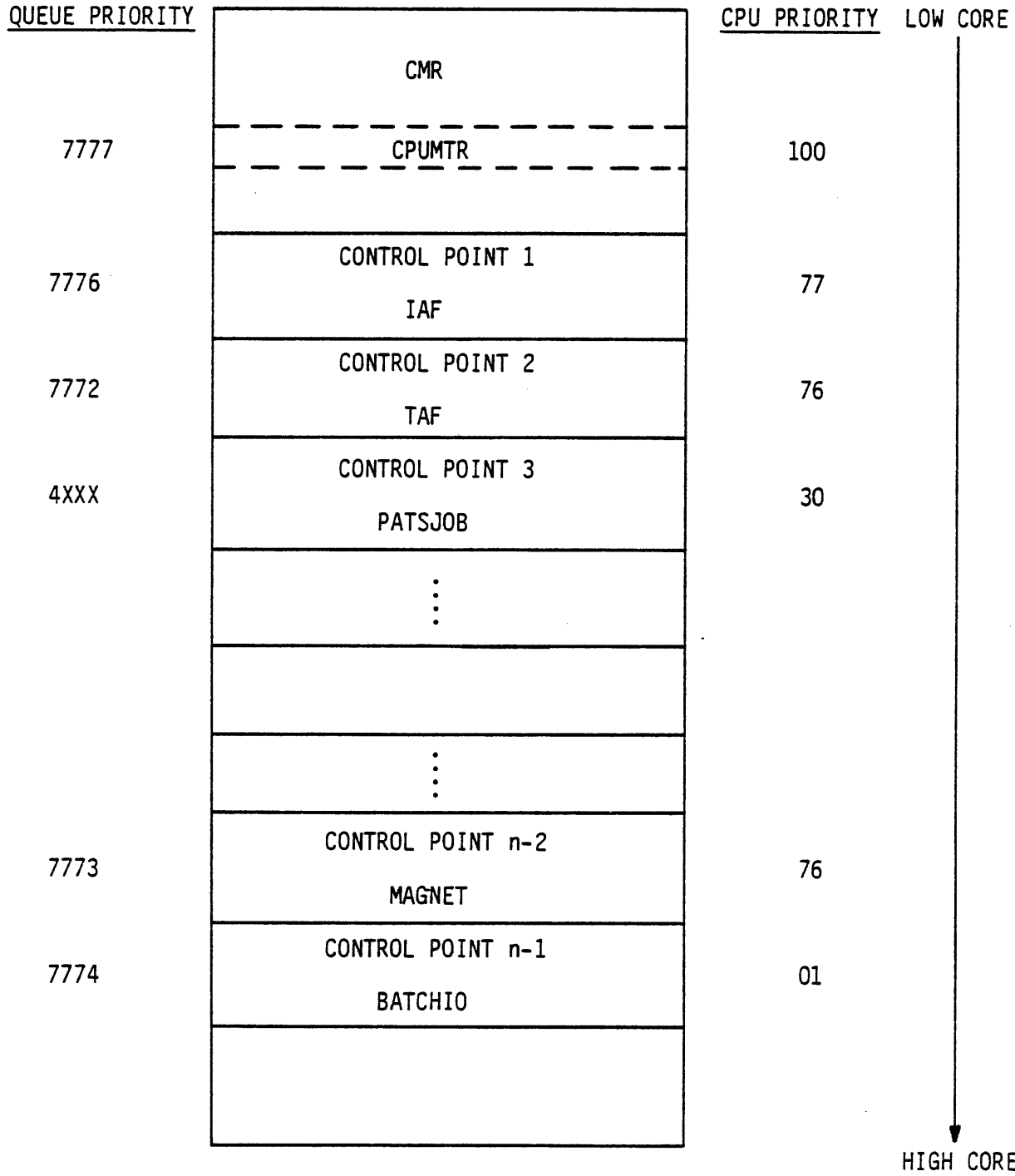
$$0 \leq P < FL$$

ABSOLUTE MEMORY ADDRESS	RELATIVE MEMORY ADDRESS
RA	P=0
RA+P	P < FL
RA+FL	P=FL

CONTROL POINT CONCEPT



CENTRAL MEMORY



NETWORK OPERATING SYSTEM

MONITORS

- CPUMTR
- MTR

CONTROL POINTS

- CONTROL POINT 0
- SYSTEM CONTROL POINT
- SUBCONTROL POINTS

JOB FIELD LENGTH

STORAGE MOVE

ROLLOUT/ROLLIN

PROGRAM/SYSTEM COMMUNICATION

RECALL

- PERIODIC
- AUTOMATIC

PRIORITY/RESOURCE TIMES

- CPU PRIORITY
- QUEUE PRIORITY
- CPU TIME SLOT
- CPU TIME SLICE
- CM TIME SLICE

NETWORK OPERATING SYSTEM

JOB ORIGINS

- SYSTEM CONSOLE (SYOT)
- LOCAL BATCH (BCOT)
- REMOTE BATCH (EIOT)
- TIME SHARING (TXOT)
- MULTI TERMINAL (MTOT)

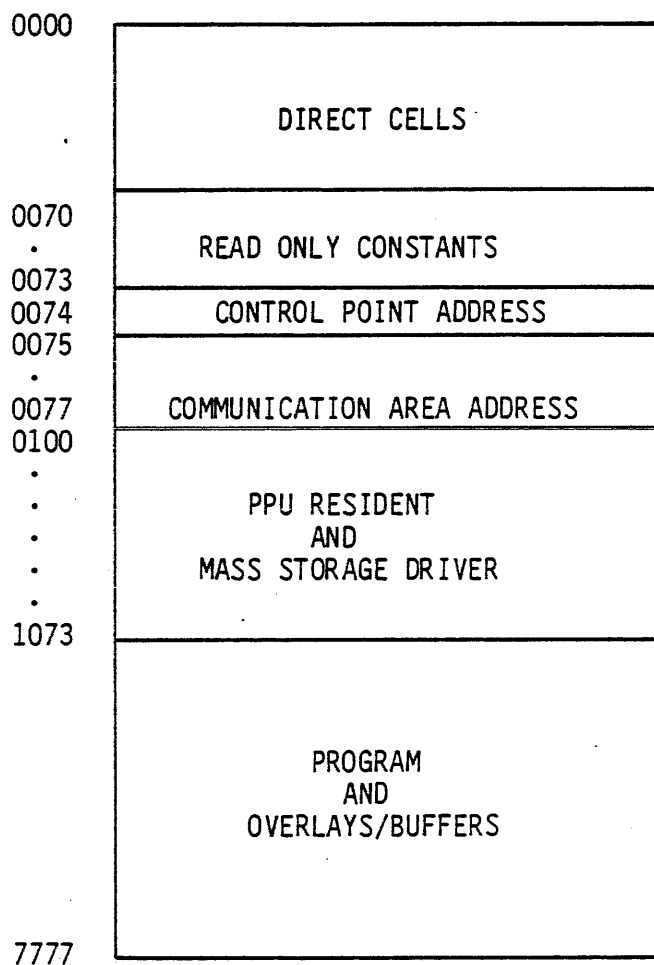
JOB CLASS

- NETWORK SUPERVISOR

PPU USAGE

POOL PROCESSORS

(PP2 through PP11 on 10 PP machines; PP2 through PP11 and PP20 through PP31 on 20 PP machines.)⁺



RESERVED PP

0	MTR
1	DSD

DEDICATED PP

A Pool PPU permanently assigned to a given control point

⁺ PP numbers are in octal notation.

LOCAL FILES

INFT	INPUT
PRFT PHFT	OUTPUT
ROFT TEFT	ROLLOUT
LOFT	LOCAL/SCRATCH
PMFT	DIRECT ACCESS PERMANENT FILE
LIFT	LIBRARY (LOCKED COMMON)
SYFT	SYSTEM
PTFT	PRIMARY

RESERVED NAMES

INPUT	PUNCH	SCR	Files beginning with five Z; for example, ZZZZEF
OUTPUT	PUNCHB	SCR1	
	P8	SCR2	
		SCR3	
		SCR4	

LESSON 2 SYSTEM MAINTENANCE OVERVIEW

LESSON PREVIEW:

The student will review how NOS source code is maintained using the MODIFY utility, how uniform coding techniques and system symbols are employed through various TEXTs to COMPASS and common decks, and the reports generated by the KRONREF utility.

In addition, this lesson introduces the student to the various usages of the term "library" in NOS and how each type of library is maintained.

The concepts discussed in this lesson should give the student a better understanding of why coding standards are enforced and some of the means of presenting a uniform coding approach to help insure the stability and ease of coding of the NOS Operating System.

This lesson also discusses the use of the DSDI (Deadstart Dump Interpreter) to assist the analyst in analyzing system dumps.

OBJECTIVES:

Upon successful completion of this lesson the student should be able to:

- Explain what system symbols and macros are available in various system texts and common decks.
- Describe the naming conventions for common decks and system routines.
- Describe the documentation and COMPASS column conventions required as part of the CODING standard by NOS.
- Explain the reports generated by the KRONREF utility and the value of these reports.
- Distinguish between the various uses of the term "library" and discuss how each "library" is managed in NOS.

REFERENCES:

COMPASS Reference Manual - section 4.3.8 (STEXT) Listing of Lower Cyber Coding standards - CODING from NOS OPL MODIFY Reference Manual NOS RM, 1-2-13-14, 1-13-2, 1-14 NOS RM, 2-1-6-15, 2-A, 2-I NOS IMS - Chapter 32 NOS SMRM, 10 (DSDI)

ASSIGNMENTS:

Read Appendix C of the NOS Reference Manual, Volume 2. Obtain a copy of the Coding Standard from the NOS program library (optional). Obtain a KRONREF of the Operating System. Obtain a CATALOG of the Operating System program library and NOS deadstart tape.

PROGRAM LIBRARY MAINTENANCE

SOURCE CODE FOR NOS IS MAINTAINED USING THE MODIFY UTILITY.

SOURCE CODE IS PASSED THROUGH MODIFY TO GENERATE A "PROGRAM LIBRARY" (PL).

EACH LINE OF SOURCE CODE CARRIES WITH IT A UNIQUE IDENTIFIER AND ACTIVITY INFORMATION.

THE PROGRAM LIBRARY IS THEN A "PERMANENT" MECHANISM TO MAINTAIN SOURCE CODE - RATHER THAN HAVE 600,000 PLUS CARDS, THE PROGRAM LIBRARY IS TYPICALLY MADE A PERMANENT FILE OR COPIES TO MAGNETIC TAPE.

A MODIFY PROGRAM LIBRARY CONSISTS OF THREE RECORD TYPES -

COMMON DECKS	(OPLC)
PROGRAM DECKS	(OPL)
DIRECTORY	(OPLD)

EACH CPU PROGRAM AND PPU ROUTINE RESIDES AS A SEPARATE DECK.

CPUMTR
CIO
DSD
DOPYB
MODIFY

PROGRAM LIBRARY MAINTENANCE

COMMON DECKS ARE ALSO SEPARATE DECKS BUT ARE INCLUDED INTO THE PROGRAM DECK WHEN THE PROGRAM IS BROUGHT TO THE COMPILE FILE.

COMMON DECKS ARE REFERENCED BY
A

*CALL DECKNAME
IN THE SOURCE CODE.

COMMON DECKS ARE USED -

- TO INCREASE EFFICIENCY IN WRITING CODE
- TO INSURE UNIFORMITY OF CODE
- TO DECREASE DEBUGGING TIME
- FOR MODULARITY

	IDENT	LOCM
	ENTRY	LCOM
*CALL	COMDECK	
	END	LCOM

COMMON DECK NAMING

COM Y XXX

XXX = NAME OF ROUTINE

Y = TYPE

C	=	CPU CODE/MACROS
P	=	PPU CODE/MACROS
S	=	SYMBOLS AND MACROS
T	=	TABLES
D	=	DISPLAYS SUBROUTINES
K	=	TAF (TRANEX) CODE/MACROS
M	=	MASS STORAGE
B	=	TAF DATA BASE MANAGER
I	=	INTERACTIVE
A	=	GENERAL MSS
E	=	MSS EXECUTIVE
U	=	MSS UTILITIES
Z	=	MSS DRIVER

SYSTEM TEXT

A SYSTEM TEXT IS AN OVERLAY GENERATED BY COMPASS AS THE RESULT OF THE STTEXT PSEUDO INSTRUCTION.

THE SYMBOLS INCLUDED IN THE SYSTEM TEXT OVERLAY ARE ALL SYMBOLS DEFINED IN THE ASSEMBLY EXCEPT THOSE WHICH MEET ONE OF THE FOLLOWING -

- IS RELOCATABLE OR EXTERNAL
- IS QUALIFIED
- IS REDEFINABLE (EG, SET, MIN, MAX, ETC)
- IS READ BY XTEXT
- IS BETWEEN CTEXT AND ENDX
- IS DEFINED BY SST
- IS 8 CHARACTERS LONG WITH ↑↓

SYMBOLS INCLUDED ALSO INCLUDE

MACROS

MICROS

PSEUDO-DEFINED OPCODES

THE PRIMARY SYSTEM TEXT USED BY THE NOS SYSTEM PROGRAMMER IS CALLED

NOSTEXT

IN ADDITION TO SYMBOLS FROM THE SYSTEM TEXT, ADDITIONAL MACROS AND SYMBOLS ARE AVAILABLE TO THE NOS SYSTEM PROGRAMMER THROUGH COMMON DECKS.

COMMON DECK AIDS TO SYSTEM TEXT

NOSTEXT = COMMON DECKS PPCOM
CPCOM
SYSTEXT = COMMON DECK CPCOM
PSSTEXT = COMMON DECK COMCMAC
COMCCMD

PPCOM - SYMBOL DEFINITIONS FOR CMR AND PPU INTER-COMMUNICATION

- QUEUE PRIORITIES
- DIRECT LOCATION ASSIGNMENT
- PPR ENTRY POINTS
- MS ENTRY POINTS AND ADDRESSES
- MONITOR FUNCTION CODES
- DAYFILE MESSAGE OPTIONS
- FILE TYPES
- JOB ORIGIN/CLASS TYPES
- ERROR FLAGS
- PSEUDO CHANNELS
- SYSTEM POINTERS/LOCATIONS
- CONTROL POINT AREA LOCATIONS
- MST LOCATIONS
- VARIOUS TABLE FORMATS
 - PP COMMUNICATION AREA
 - EST (EQUIPMENT STATUS TABLE)
 - FNT/FST (FILE NAME TABLE/FILE STATUS TABLE)
 - LIBRARY DIRECTOR ENTRIES
 - JOB CONTROL AREA

COMMON DECK AIDS TO SYSTEM TEXT

- CPCOM - SYSTEM MACROS FOR COMMONLY USED SYSTEM REQUESTS
- SYSCOM - COMMUNICATION AREA
 - SYSTEM MACROS
 - FET INITIALIZATION MACROS
 - FILE ACTION MACROS
 - PERMANENT FILE MACROS
 - DATA TRANSFER MACROS
- COMCMAC - SYSTEM PROGRAMMER MACROS
- COMCCMD - CENTRAL PROGRAM MACROS
- COMPMAC - SYSTEM PROGRAMMER MACROS FOR PPU PROGRAMS

S TYPE COMMON DECKS - COMSXXX

THE S TYPE COMMON DECKS CONSIST OF SYMBOL DEFINITIONS THAT HAVE A WIDE USE BUT ARE NOT FREQUENTLY USED TO BE SYSTEM TEXT SYMBOLS.

THE S TYPE COMMON DECKS USUALLY RELATE TO A PARTICULAR ASPECT OF THE SYSTEM.

ACC	ACCOUNTING	NCD	NETWORK COMMUNICATIONS
BIO	BATCHIO	NET	TERMINAL NETWORK
CIO	CIO	PFM	PFM SYMBOLS
CPS	CPUMTR SUBFUNCTIONS	PFS	PFM SUPERVISOR
DSL	DEADSTART	PFU	PF UTILITIES
ESS	DIAGNOSTICS	PRO	PROFILE
EVT	EVENT DESCRIPTIONS	PRD	PRIORITY DEFINITIONS
EXP	EI200	QFS	QUEUE SUPERVISOR
IOQ	I/O QUEUES	REM	INTERACTIVE SUBSYSTEM
JCE	JOB CONTROL DEFAULTS	RSX	RESEX
JIO	JOB I/O SS	SCP	SYSTEM CONTROL POINT FACILITY
JRO	JOB ROLLOUT	SCR	S/C REGISTER
LDR	CPU LOADING	SFS	SPECIAL FILE SUPERVISOR
LFM	LOCAL FILE MANAGER	SRU	SRU PARAMETERS
LSD	LABEL SECTOR	SSE	SYSTEM SECTOR
MMF	MULTIMAINFRAME	SSJ	SPECIAL SYSTEM JOB
MRT	MACHINE RECOVERY	TCM	TELEX COMMUNICATIONS
MSC	MISCELLANEOUS CONSTANTS	TDR	TERMINAL DRIVER
MSI	MS INITIALIZATION	TRX	TRANEX
MSP	MS PROCESSING	WEI	ENHANCED END-OF-INFORMATION
MST	MST INTERLOCKS	ZOL	ZERO LEVEL OVERLAYS
MTR	MTR/COUMTR FUNCTIONS	176	CYBER 176 PARAMETERS
MTX	TAPES	IDS	IDS FUNCTION CODE DEFINITIONS

PROGRAMMING CONVENTIONS

DOCUMENTATION

- DOCUMENT UTILITY

CODING CONVENTIONS

- CODING STANDARD
- COMPASS COLUMN CONVENTION
- NAMING CONVENTIONS

UNIFORM CODING APPROACH

- INCREASES EFFICIENCY OF PROGRAM DEVELOPMENT
- IMPROVES RELIABILITY AND MAINTAINABILITY
- AIDS MAINTENANCE AND TRAINING
- EASES PROGRAM UNDERSTANDING

STABILITY

KRONREF

CROSS REFERENCES SYSTEM SYMBOLS FROM SYSTEM TEXT WITH DECKS FROM A MODIFY PROGRAM LIBRARY AND CROSS REFERENCES COMMON DECKS FROM THAT PL WITH THE DECKS THAT CALL THEM.

LISTED AS OUTPUT OF KRONREF ARE THOSE DECKS THAT REFERENCE:

- PP DIRECT CELLS
- PPR ENTRY POINTS
- MONITOR FUNCTIONS
- CMR POINTERS
- CM LOCATIONS
- CONTROL POINT AREA WORDS
- DAYFILE MESSAGE OPTIONS
- FILE TYPES
- JOB ORIGIN, QUEUE TYPES AND QP
- ERROR FLAGS
- MISC. NOSTEXT SYMBOLS
- COMMON DECK CALLS
- PP ROUTINES CALLED
- SPECIAL ENTRY POINT USAGE
- USE OF SYSTEM MACRO

LOADER TABLES

77	PRFX	PREFIX
70	LDSET	OBJECT DIRECTIVE
60	CAPSULE	RELOCATABLE CAPSULE
54	EACPM	ABS OR OVERLAY W. ECS MULTIPLE ENTRY POINTS
53	ACPM	ABS OR OVERLAY W. ECS
51	EASCM	ABS W. MULTIPLE ENTRY POINTS
50	ASCM	ABS OR OVERLAY
-	6PPM	6000 STYLE PPU PROGRAM BITS 59-42 ARE 3 CHAR NAME OF PROGRAM
70	OPLD	DIRECTORY
76	ULIB	

APPENDIX D OF LOADER MANUAL

APPENDIX G OF REF. MAN. VOL. 2

LOADER TABLES

34	PIDL	PROGRAM LENGTH AND IDENTIFICATION
36	ENTR	ENTRY POINT DEFINITIONS
37	XTEXT	EXTENDED RELOCATABLE TEXT
40	TEXT	RELOCATABLE TEXT
41	XFILL	EXTENDED RELOCATION FILL
42	FILL	RELOCATION FILL
43	REPL	REPLICATION OF TEXT
47	XREPL	EXTENDED REPLICATION OF TEXT
44	LINK	EXTERNAL REFERENCE LINKAGE
45	XLINK	EXTENDED EXTERNAL REFERENCE LINKAGE
46	XFER	TRANSFER POINT

LOADER TABLES

PRFX (77)

7700	0016		
NAME			
DATE			
TIME			
SYSTEM IDENTIFICATION			
PROCESSOR		VERSION	
MODIFICATION LVL	TARGET	VALID	F
TYPE	HARDWARE REQUIRED		
COMMENTS			

LOADER TABLES

6PPM

NAME		FWA		WC
PP CODE				

EASCM (51)

5100	L1	L2	FWA	K
ENTRY POINT 1				
:				
:				
:				
ENTRY POINT K				
CPU CODE				

ASCM (50)

5000	L1	L2	FWA	ENTRY
CPU CODE				

- LOADER TABLES

RELOCATABLE

REL

COMCSRT =
SET RECORD TYPE

PRFX

LDSET (OPTIONAL)

PIDL

ENTR

TEXT
XTEXT

REPL
XREPL

FILL
XFILL

LINK
XLINK

XFER (OPTIONAL)

ABSOLUTE/OVERLAY

ABS
OVL

PRFX

ASCM ACPM
EASCM EACPM

PERIPHERAL PROCESSOR

PP

PRFX

6PPM

LOADER TABLES

SYSTEM TEXT

OVL (SPECIAL CASE)

PRFX

ASCM

LEVELS L1=L2=1

ORIGIN=ENTRY=0

CAPSULE

CAP

PRFX

CAPSULE

LIBRARIES

SYSTEM LIBRARY

SYSEDT

PROGRAM LIBRARY

MODIFY
UPDATE

USER LIBRARY

LIBGEN

LIBEDIT
CATALOG
ITEMIZE

LIBRARIES

SYSTEM LIBRARY

- SYSTEM FILE
- DIRECTORIES
 - PLD
 - CLD
 - LBD
- RESIDENCY
 - SYSTEM FILE
 - PPULIB
 - RPL
 - RCL
 - ASR

SYSEDT

BUILDS DIRECTORY AND RESIDENCY USING ROUTINES FROM THE SYSTEM FILE UNDER DIRECTION OF A LIBDECK

LIBRARIES

PROGRAM LIBRARY

- SOURCE CODE MAINTENANCE
- RECORD TYPES
 - OPL
 - OPLC
 - OPLD
- DIRECTORY SHOWING TYPE AND RANDOM ADDRESS OF ROUTINE WITHIN THE LIBRARY

MODIFY UPDATE

- BUILD PROGRAM LIBRARY
- COLLECT CODE FROM PROGRAM LIBRARY, ADDING OR DELETING FROM IT, TO
COMPILE FILE FOR PROCESSING BY COMPILER OR ASSEMBLER

LIBRARIES

USER LIBRARY

- USED BY LOADER TO SATISFY EXTERNAL REFERENCES - OBJECT TIME ROUTINES
- COLLECTION OF RELOCATABLE SUBROUTINES
- DIRECTORY CONTAINS ENTRY NAME AND RELATIVE ADDRESS WITHIN THE LIBRARY
- FORMAT

LIBRARY NAME	ULIB
ENTRY 1	REL
ENTRY 2	REL
ENTRY 3	REL
LIBRARY DIRECTORY	OPLD

LIBGEN

BUILDS USER LIBRARY FROM A FILE OF RELOCATABLES, PREFIXING THE LIBRARY WITH AN IDENTIFICATION RECORD (ULIB) and APPENDING A DIRECTORY RECORD (OPLD)

LIBRARIES

LIBEDIT

CATALOG/ITEMIZE

GTR

● RECORD TYPES (COMCSRT - SET RECORD TYPE)

ABS

CAP

OPL

OPLC

OPLD

OVL

REL

PP

PPU

TEXT

ULIB

PROC

LIBEDIT MANIPULATES RECORDS ON A LIBRARY FILE (DIRECTORY) EDITING OR REPLACING WITH RECORDS FROM A REPLACEMENT FILE.

CATALOG AND ITEMIZE LIST THE CONTENTS OF A FILE, IDENTIFYING EACH RECORD BY NAME AND TYPE AND LISTING APPROPRIATE INFORMATION ABOUT EACH RECORD.

GTR GETS A RECORD OR RECORDS FROM A FILE BY IDENTIFYING THE RECORD(S) BY TYPE AND NAME.

DSDI

Deadstart Dump Interpreter

Deadstart option dumps hardware registers and memory to a tape

DSDI reads the tape and formats dump data in a more human readable form

DSDI is directive driven -

- control over format of output file
- control over what data is dumped and format it is dumped in
- analysis of system tables
- analysis of major subsystems

EI200
BATCHIO
MAGNET
IAF/TELEX

QUESTION SET LESSON 2

1. List the libraries recognized in NOS and the system utilities or mechanisms to manage them.

LESSON 3 CENTRAL MEMORY RESIDENT

LESSON PREVIEW:

This lesson overviews the portion of the NOS operating system that is resident in central memory. The "central memory resident" portion of the system includes all pointers and tables, control point areas, dayfile buffers, PP communication area, PP and CPU routine libraries and directories, and CPUMTR (CPU monitor).

The information in this lesson is organized for a complete overview of medium detail, so that the student has been exposed to the tables and pointers and their contents prior to their use in other lessons.

OBJECTIVES:

Upon completion of this lesson, the student should be able to:

- Trace linkages from table pointers to the actual tables.
- Identify the content of the pointer and constant area (words 0 through 177) of Central Memory Resident.
- Identify the content of the words in the control point area.
- Have familiarity with the:
 - Equipment Status Table (EST)
 - File Name Table/File Status Table (FNT/FST)
 - Mass Storage Table (MST) and Track Reservation Table (TRT)
 - Job Control Block (JCB).
- Describe the relationship between the Resident Peripheral Library (RPL), the Resident Central Library (RCL) and the library directories (Peripheral Library Directory (PLD), Central Library Directory (CLD), User Library Directory (LBD)).
- Identify the contents of the words in the Job Communication Area (RA through RA+100) in the job Field Length.

REFERENCES:

NOS System Programmer's Instant, 3 NOS IMS - Chapter 2

CENTRAL MEMORY RESIDENT
CENTRAL MEMORY LAYOUT

000 . . 077	system pointers and control words
100 . . 111	channel status table
112 . . 122	status/control registers
123 . . 126	miscellaneous pointers and data
127 . . 141	reserved
142 . . 177	channel release table
200	control point areas
(n+1)*200	system control point
(n+2)*200	PP communication area (pointer in word 002, byte 4)

dayfile buffer pointers (pointer in word 003, byte 0)
equipment status table (EST) (pointer in word 005, byte 0)
file name/file status table (pointer in word 004, byte 0)
FNT interlock table (pointer in word 004, byte 1)
CDC CYBER 176 exchange package area
mass storage allocation area
mass storage tables (MST)
job control area
dayfile buffers
dayfile dump buffer
ECS/PP buffer
CPUMTR
resident peripheral library (RPL)
resident central library (RCL)
peripheral library directory (PLD)
central library directory (CLD)
system user library directory (LBD)

POINTERS AND CONSTANTS

	59	47	35	29	23	17	11	5	0	
000	zeros									
001	fwa resident PP library			number of PPU's	†1	memory size/100				RPLP,PPUL, CPUL,MFLL
002	fwa PP library directory				number of ctrl pts	PP comm area adr				PLDP,NCPL, PPCP
003	dayfile pntr fwa	fwa dayfile dump buffer			†2	no. excess dayfiles				DFPP
004	fwa FNT	lwa+1 FNT		fwa job control area						FNTP,JBCP
005	fwa EST	lwa+1 EST	lwa+1 ms equipment	fwa ECS/PP buffer						ESTP
006	fwa mass storage allocation			fwa user library directory						LBDP,MSAP
007	fwa CPU library directory			fwa COS format CPU lib directory				†3		CLDP
010	installation area									INOL,INSL
017										IN7L
020							CMR size /100			CMRL
021	system name							†4		
022				job sequence number counter						JSNL
023			avail ECS 1000B blocks				available mem/100B			ACML,AECL
024	job scheduler	CPU recall	PP/auto recall	job activity	job switch					MSCL
025	†5	ECS first user track	user 1000B word ECS blks	ECS RA/1000B for CPO	ECS FL/1000B for CPO					ECRL
026				julian date (yyddd)						JDAL
027				packed date (yr - 1970,mo,da,hr,mn,sc)						PDTL
030	time of day (Δhh.mm.ss.)									TIML
031	date (Δyy/mm/dd.)									DTEL
032	system title line									
035										
036	system version name									
037										
040							scheduler cy. intvl.			JSCL
041	†6	1CK recall time			1SP recall time					

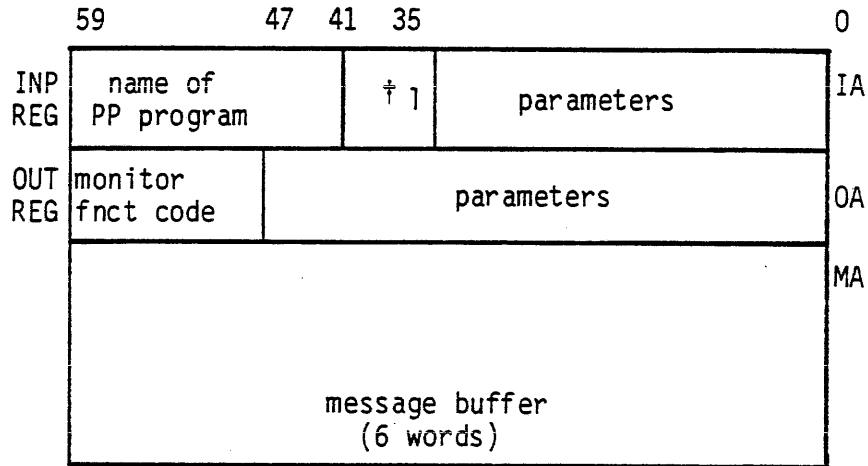
	59	47	35	23	17	11	0	
042	†1							IPRL
043	†2							SSTL
044	TELEX/IAF	EXPORT/ IMPORT	BATCHIO	MAGNET	TAF			SSCL
045	STIMULATOR	NETWORK INTER PROC	RBF	CDCS	MCS			
046	MASS STOR- AGE CONTROL	TRANSACTION STIMULATOR	reserved					
047	reserved							
050	reserved				IR addr next PPU			PPAL
051	idle time							
052	load code for MS error processors							MSEL
053								
054								
055	reserved							
056								
057	ctrl point for move	internal to MTR						CMCL
060	←†3	CPO ctrl pt assig		CPO exchange address			ACPL	
061	←†4	CPI ctrl pt assig		CPI exchange address				
062	/			address of PPO exchange package			PXPP	
063	first word of PP exchange package							
064	reserved							
065	zeros							ZERL
067	reserved							
⋮								
075								
076	reserved			CPUMTR exchange address for MTR				MTRL
077	EQ	CPSL	PS		O			CPSL

	59	47	35	23	17	11	0	
100	CH0	CH1	CH2	CH3	CH4	CTIL †1		
101	CH5	CH6	CH7	CH10	CH11			
102	CH12	CH13	CH14	CH15	CH16			
103	CH17 (unused)	CH20	CH21	CH22	CH23			
104	CH24	CH25	CH26	CH27	CH30			
105	CH31	CH32	CH33	CH34 (unused)	CH35 (unused)			
106	seconds		milliseconds			RTCL		
107	reserved							
110	†2							PFNL
111	†3							
112	†4							SCRL
113	4	3	2	1	0	S16L †5		
114	9	8	7	6	5			
115	14	13	12	11	10			
116				16	15			
117	4	3	2	1	0	S36L †6		
120	9	8	7	6	5			
121	14	13	12	11	10			
122				16	15			
123	MID	†7			machine index	MMFL		
124	reserved							
125	reserved							
126	reserved			flag register		EFRL		
127	†8							INWL
130	reserved		MXN time	worst case MTR cycle time	current MTR cycle time	SD0L		
131	count of ECS moves			count of CM moves			SD1L	
132	rollout count		count of sectors rolled				SD2L	
133	reserved	user commits + time slice with output		count of time slices			SD3L	
134	reserved			jobs in recall due to PP priority exchanges			SD4L	
135	reserved							
162								
163								
177	DSD - 1DS communication area							

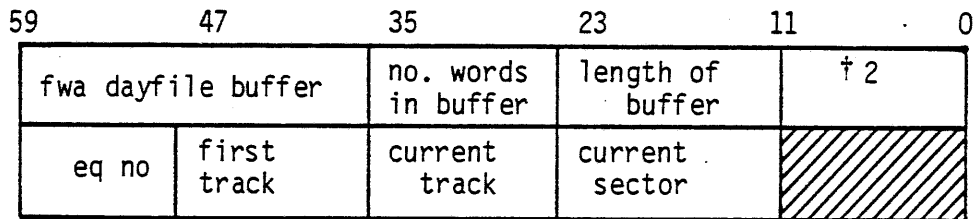
	59	47	41	35	29	23	17	11	5	0		
000	exchange package area											
017												
020	†1	error flags	activity count	RA/100B	FL/100B						STSW	
021	job name						job orgn	operator equipment			JNMW,OAEW	
022	CPU priority	queue priority	†2	/		CPUs allowable					JCIW	
023	CM residence time limit		†3	CPU time slice limit							TSCW	
024	time entered X status										CPCW	
025	†4	reserved			ECS RA/1000B	ECS FL/1000B					ECSW,CPIW	
026	PP recall register										RLPW	
027	†5							snsr swchs	/			SNSW
030											MS1W	
•												
•												
•												
034	message 1 area											
035											MS2W	
036	message 2 area											
037												
040											INOW	
•											•	
•											•	
•											•	
047											IN7W	
050	†6	SRU accumulator (micro units *10)									ACTW,SRUW	
051	CP accumulator										CPTW	
052	MS accumulator			MT accumulator			PF accumulator				IOAW	
053	M13=M1*M3			M14=M1*M4			/		adder accumulator			MP1W,ADAW
054	M1*1000			M12=M1*M2			reserved				ACTWE,MP2W	
055	← †7	CPM (SRU=SRU+ CPM*CP)				IOM (SRU=SRU+IOM*IO)					MP3W	
056	SRU account block limit			computed SRU job step limit							STLW	
057	reserved	SRU job step limit			SRU at beginning of job step						SRJW	
060	reserved	CP time job step limit			CP time at beginning of job step						CPJW	

	59	53	47	35	29	23	17	11	0	
061	†1									PPFW
062	†2					rollin FL		FL increase request		FLCW
063	†3					rollin ECS FL		ESC FL increase req		ELCW
064	†4									SSCW
065	TXOT	list of files address			TTY interrupt address †5		output pointer			TXSW,TIOW, TIAW,LOFW
066	auxiliary pack name						†6			PFCW
067	user number						†9	†17	user index	UIDW
070	†8			†11 terminal input pointer		error exit †10 return address				EECW,TINW
071	input FST	primary FST			event descriptor		rollout time			TFSW,TERW
072	†12		control statement count			next statement index		limit index		CSPW
073	†13	eq num	first track	current track	current sector	half sector flag				CSSW
074	job sequence number			control statement address (TCS)			demand file random index			RFCW
075	reserved		†14							ALMW
076	reserved	dayfile msg count	control stmt count	†15	mass storage PRU count					ACLW
077	each bit has a special meaning									AACW
100	buffer 0 length	buffer 0 address			buffer 1 length	buffer 1 address				ICAW
101	special entry point word †16									SEPW
102	system processor call word †17									SPCW
103	EFG	R1G		CCL data			reserved			JCDW
104	EF	R3		R2			R1			JCRW
105	†18	input buffer address			right screen buffer address		left screen buffer address			DBAW
106	loader control words †19									LB1W
107										LB2W
110										LB3W
111		†20					FWA of dump			PPDW
112	reserved						†21			SSOW
113	computed CP job step limit									CPLW
114	reserved									
•										
•										
127										
130	control statement buffer									CSBW
•										
•										
177										

PP COMMUNICATION AREA



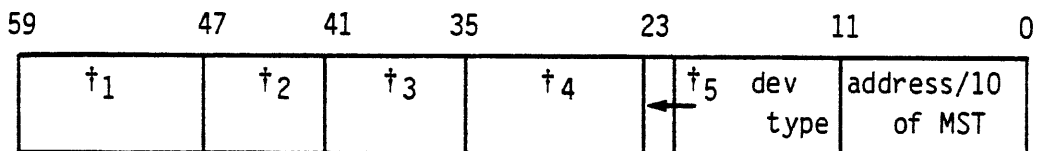
DAYFILE BUFFER POINTERS



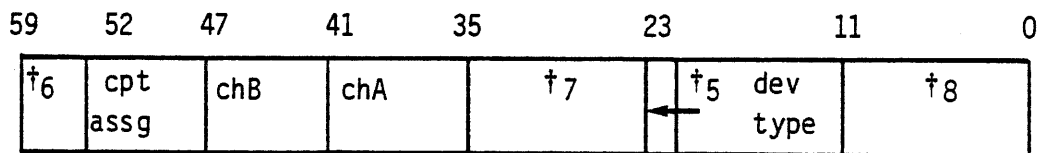
<u>REF</u>	<u>Bit No.</u>	<u>Description</u>
†1	41	Set if called with auto recall.
	40-36	Control point assignment.
†2	11-0	Interlock byte (0 = no dump in progress, 1 = dump in progress).

CENTRAL MEMORY TABLES
 Equipment Status Table (EST) Formats

Mass Storage Device



Nonmass Storage Device (3000 Type Equipment)



File Name/File Status Table (FNT/FST) Entry

File in Input Queue

59	53	47	35	23	17	11	5	0
job name					job org	type INFT	†1	
id code	eq no	first track	binary card sequence no	field length	queue priority			

File in Print Queue

59	53	47	35		17	11	5	0
job name					job org	type PRFT	†1	
†2	eq no	first track	†3		queue priority			

File in Punch Queue

59	53	47	35		17	11	5	0
job name					job org	type PHFT	†1	
†2	eq no	first track	†3		queue priority			

File in Rollout Queue

59	53	47	35	23	17	11	5	0
job name					job org	type ROFT	†4	
id code	eq no	first track	ECS FL/1000B no	field length	queue priority			

File in Time/Event Rollout Queue

59	53	47	35	23	17	11	5	0
job name					job org	type TEFT	†4	
event des	eq no	first track	event descriptor	field length	rollout time pd			

Mass Storage Files
 Not in Input, Print, Punch, or Rollout Queue

59 53 47 35 23 17 11 5 0

file name					†5	file type	cp
id code	eq no	first track	current track	current sector		†6	

Magnetic Tape Files

59 53 47 35 29 17 11 5 0

file name					†7	file type	0 cp
id code	eq no	UDT addr assign to	†8	VSN entry random address	†9	†6	

Fast Attach Permanent Files

59 53 47 35 23 17 11 5 0

file name					†10	type FAFT	cp
†11	eq no	first track	user ct READMD	us ct RDAP	us ct READ	†12	

Ref	Bit No.	Description
†1	5	Set if system sector contains control information.
†2	59-57	Device selection field.
	56-54	External characteristics.
†3	35-33	Forms code.
	32-12	Terminal identification (TID).
†4	5	Set if user job has subsystem connection (either long term connection or wait response).
†5	17	Unused.
	16	Set if extend-only file.
	15	Set if alter-only file.
	14	Set if execute-only file.
	13	Unused.
	12	Write lockout.
†6	10	Unused.
	9	Indicates the track interlock status of LIFT files (mass storage only).
	8	Set if file is opened.
	7	Set if file is written since last open.
	6	Set if file is written on.
	5-4	Unused.
	3-2	Read status (0 = incomplete read, 1 = EOR, 2 = EOF, 3 = EOI).
	1	Set if last operation write.
	0	Clear if busy status.

Mass Storage Allocation (MSA) Area

	59	47	0
000	last temp eq		temporary devices†
001	last input eq		input file devices†
002	last output eq		output file devices†
003	last rollout eq		rollout file devices†
004	last dayfile eq		user dayfile devices†
005	last primary eq		primary file devices†
006	last local eq		local file devices†
007	last LGO eq		LGO file devices†
008	last secondary rollout eq		secondary rollout file devices†

†Bit 47-eq is set for each equipment with the allocation type selected.

Mass Storage Table (MST)

	59	51	47	40	35	23	17	11	5	0	TDGL
000	† ₁				TRT length	† ₂	no. avail. tracks				TDGL
001	† ₃	user ECS first track		file count	IQFT track	† ₄				ACGL	
002	ECS address of MST/TRT			ECS MST/TRT update cnt			† ₅				SDGL
003	1st track IAF	label track	permits track	no. catalog tracks	DAT track						ALGL
004	family or pack name					DN			† ₆		PFGL
005	user number for private pack					† ₇				PUGL	
006	† ₈			driver name	0	sector limit				MDGL	
007											R1GL
010	installation area (global)										ISGL
011											I2GL
012	activity count	unit interlocks	current position	MTR internal	ECS error #						DALL
013	† ₉										DILL
014	DAYFILE track	ACCOUNT track	ERRLOG track	system table track	† ₁₀						DULL
015	† ₁₁				user count	† ₁₂				STLL	
016	† ₁₃										DDLL
017	installation area										ISLL

Track Reservation Table (TRT)

Word Format

59	47	35	23	11	0
track link	track link	track link	track link	†1	

<u>REF</u>	<u>Bit No.</u>	<u>Description</u>
†1	11-8 7-4 3-0	Each bit set indicates corresponding byte (0 through 3) is first track of a preserved file. Track interlock bits. Track reservation bits.

Track Link Byte (Format 1)

<u>Bit</u>	<u>Contents</u>
11 10-0	Set. Next track in track chain.

Track Link Byte (Format 2)

<u>Bit</u>	<u>Contents</u>
11 10-0	Clear. End of chain (EOI sector in file).

Track Link Byte (Format 3)

<u>Bit</u>	<u>Contents</u>
3777	Track is flawed.

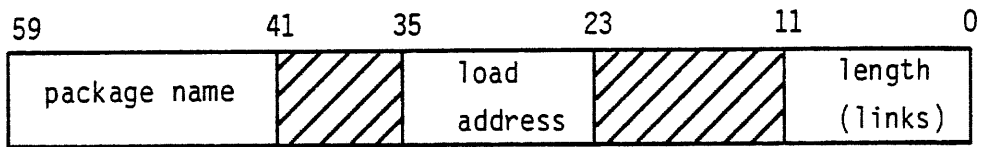
Job Control Area (JCB)

	59	47	35	23	11	0	
One for each origin type and job class	in. queue priority	lower bound	upper bound	priority age intvl	cur. intvl count		INQT
	in. queue priority	lower bound	upper bound	priority age intvl	cur. intvl count		ROQT
	in. queue priority	lower bound	upper bound	priority age intvl	cur. intvl count		OTQT
	init. CPU priority	CPU time slice	CM time slice				SVJT
	max jobs or users	max FL any job	max F1 all jobs	max ECS FL any job	max ECS FL all jobs		
	†1	reserved					PFCT
		reserved					ETB

<u>REF</u>	<u>Bit No.</u>	<u>Description</u>
†1	59-48	Index into tables of limits.
	59-57	Index a table of limits for size of each direct access file.
	56-54	Index a table of limits for number of permanent files.
	53-51	Index a table of limits for cumulative size of indirect access files.
	50-48	Index a table of limits for size of each indirect access file.

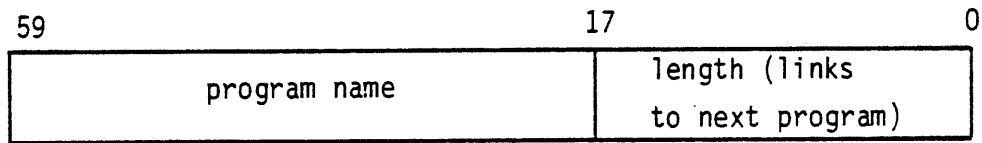
RESIDENT LIBRARIES

Resident PPU Library (RPL)

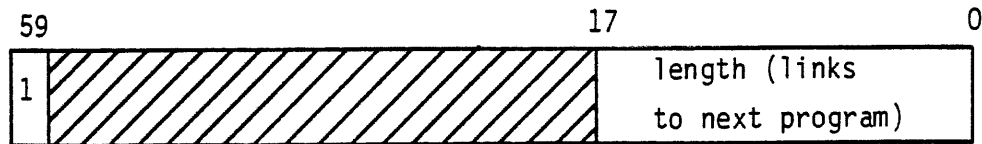


Resident CPU Library (RCL)

Type OVL



Type ABS



DIRECTORIES

PPU Library Directory (PLD)

CM Resident

59	41	35	23	11	0
package name	1	RPL address	length	load address	

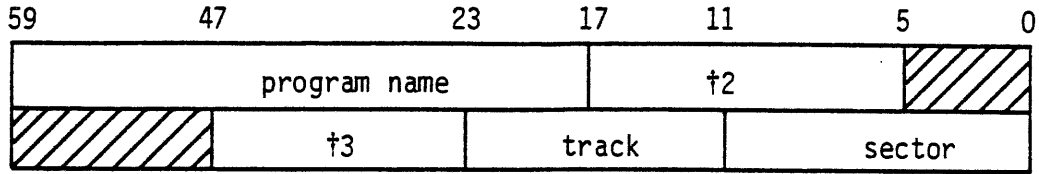
Non-CM Resident

59	41	35	23	11	0
package name	†1	track	sector	load address	

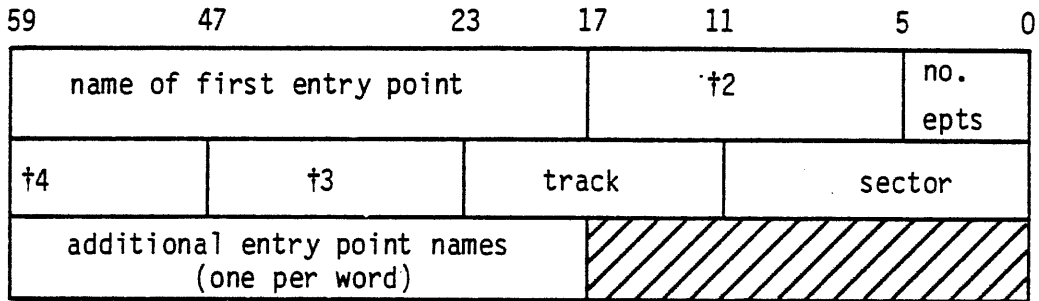
DIRECTORIES

CPU Library Directory (CLD)

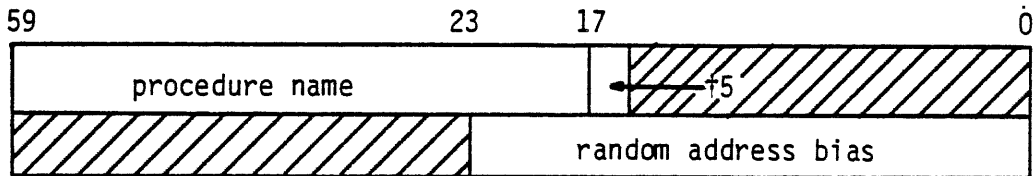
Type OVL



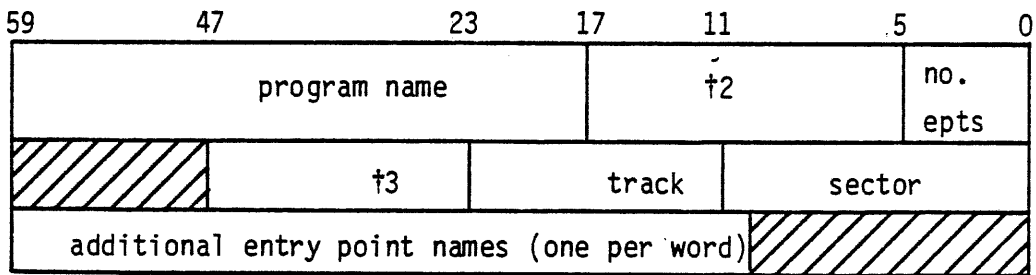
Type ABS



Type PROC

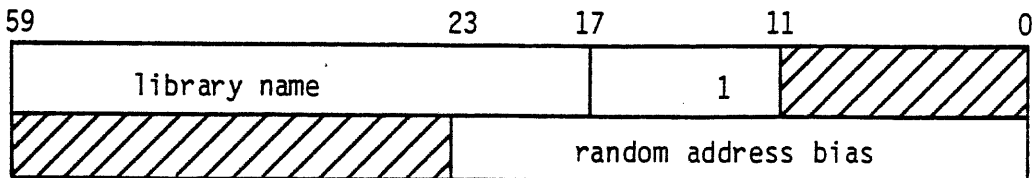


Type REL



User Library Directory (LBD)

Type ULIB



QUESTION SET LESSON 3

Obtain a dump of the current system CMR (Central Memory Resident) or use the study dump provided with this handout. (This study dump was obtained during the investigation of a problem that occurred on the inhouse version of NOS 1.4; this dump is being used as the study dump since it has many interesting configuration properties.) Answer the following questions.

1. For this system:
 - a. How many PPs?
 - b. How many control points?
 - c. How much central memory?
 - d. Does the CEJ/MEJ option exist?
 - e. How long (in words) is CMR?
2. Is there a PP program running in PP3? In PP4? If so, what is the name of the program?
3. Are any of the PPs making monitor requests? If so, which PPS and what are the requests?
4. Describe the peripheral equipment configuration for this system.
5. On what channels are the tape drives and unit record equipment?
6. Locate the system file; i.e., what equipment(s) and which track does the file reside on?
7. Identify the file name, file type, control point assignment, equipment, and file position for the files located at FNT locations:
6070 6110 6236 6410 6414
8. How much central memory is available?
9. What is the job switch delay?
10. What is the time of day?

11. To which control point(s) is (are) the CPU(s) currently assigned?
12. What is the original input queue priority for a job of batch origin?
13. What is the CPU priority for a remote batch origin job?
14. What are the ROLLOUT queue priorities for time-sharing origin jobs?
15. CIO is a PP program residing in the RPL (Resident Peripheral Library). Find its RPL entry.
16. What is the name and length of the program following CIO in the RPL?
17. What are the base addresses of the PLD (Peripheral Library Directory), the RCL (Resident Central Library), and CLD (Central Library Directory)?

What are the names of the first entries in each Library or Directory?
18. Where does the system dayfile reside in CMR? Where does the dayfile dump buffer reside in CMR?
19. Which PP has reserved channel 5? Channel 10?
20. What is the first unavailable channel?
21. The following questions refer to control point 12 in the study dump. (If you obtain your own dump, pick any control point that is actively running a job.)
 - a. What is the jobname and job origin?
 - b. What is the control point status?
 - c. How many PPs are assigned? Which ones are they and what function is being performed?
 - d. What are the control point RA and FL.
 - e. What are the CPU and QUEUE priorities?
 - f. How much CPU time has been accumulated?
 - g. What is the family, user number, user index for the job?
 - h. What is the value of the mass storage accumulator?
 - i. What is the first control card in the control card buffer?
 - j. What is the next control card to be executed?

22. Which PPs have been locked out (turned off) by the system and how did you arrive at your answer?
23. Why can't the FNT start or end beyond location 4096D?

LESSON 4 EXCHANGE JUMP

LESSON PREVIEW:

This lesson covers the use of the exchange jump hardware by the NOS Operating System. The student will learn what an exchange jump is, how the exchange address is determined, the four types of exchange jumps done by NOS, and how exchange packages are managed by the system.

OBJECTIVES:

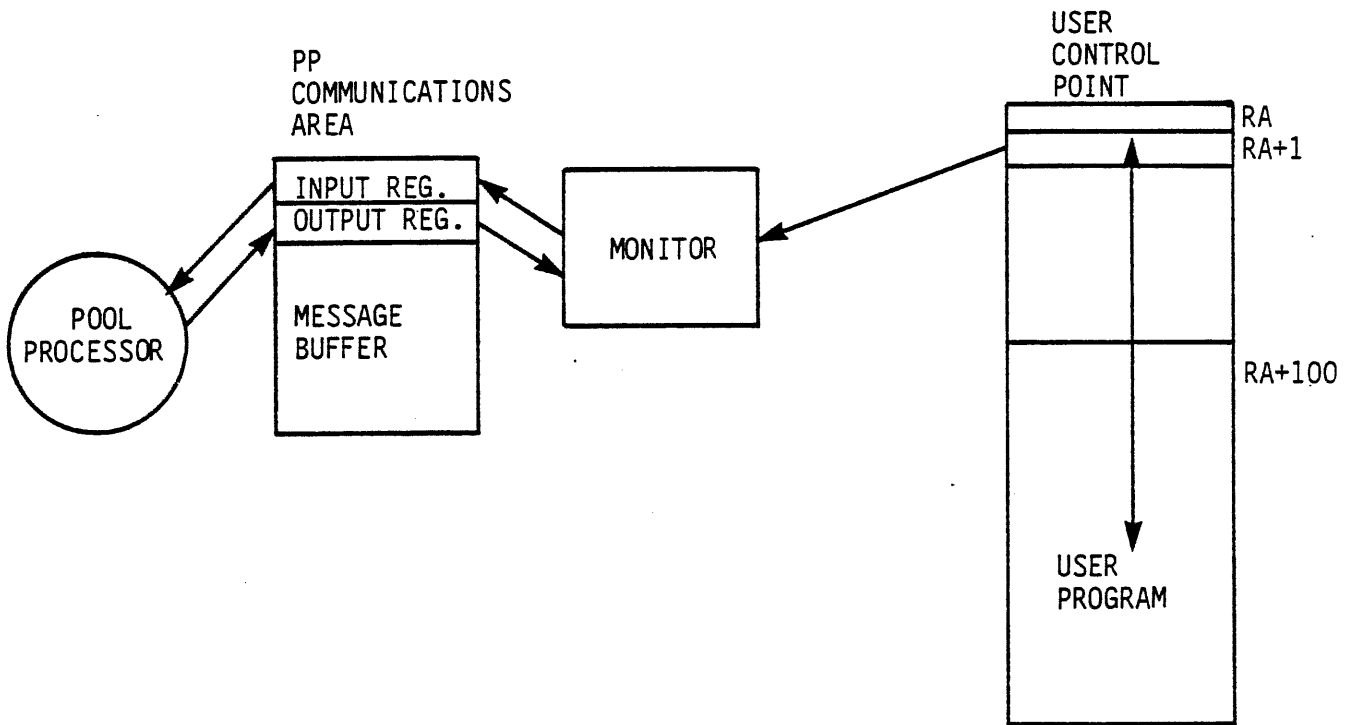
Upon the successful completion of this lesson, the student should be able to:

- Explain how the exchange jump hardware instruction works.
- Explain how the exchange address is computed in monitor mode and in program mode.
- Describe in detail each of the four modes of exchange done in NOS; namely,
 - MTR exchange
 - Pool PP exchange
 - CPU user program exchange
 - Program mode CPUMTR exchange
- Describe in detail how exchange packages are managed when a PP request causes a different CPU program to be brought into execution, rather than resuming the execution of the program that was interrupted by the exchange.

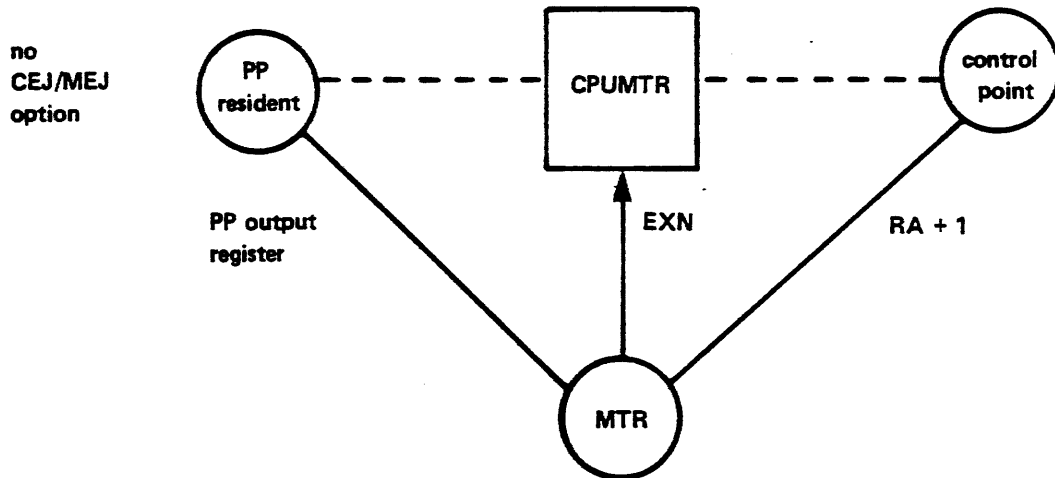
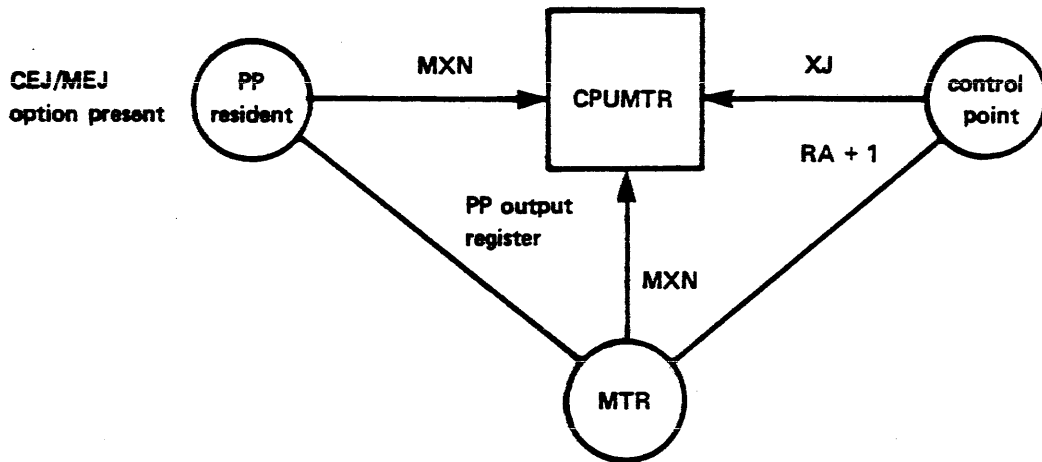
REFERENCES:

CYBER 170 Hardware Manual, 5-1-7 NOS IMS - Chapter 3

SYSTEM INTERACTION



MONITORS INTERACTION




EXCHANGE PACKAGE AREA

Exchange package area for CDC CYBER 170 Series, Models 171, 172, 173, 174, 175, 720, 730, 750, and 760; CDC CYBER 70 Series, Models 71, 72, 73, and 74; and CDC 6000 Series Computer Systems.

	59	53	47	41	35	17	0
000	/		P		A0	B0	
001	/		RA		A1	B1	
002	/		FL		A2	B2	
003	EM		/		A3	B3	
004			RAE		A4	B4	
005			FLE		A5	B5	
006	/		MA		A6	B6	
007	/				A7	B7	
010	X0						
011	X1						
012	X2						
013	X3						
014	X4						
015	X5						
016	X6						
017	X7						

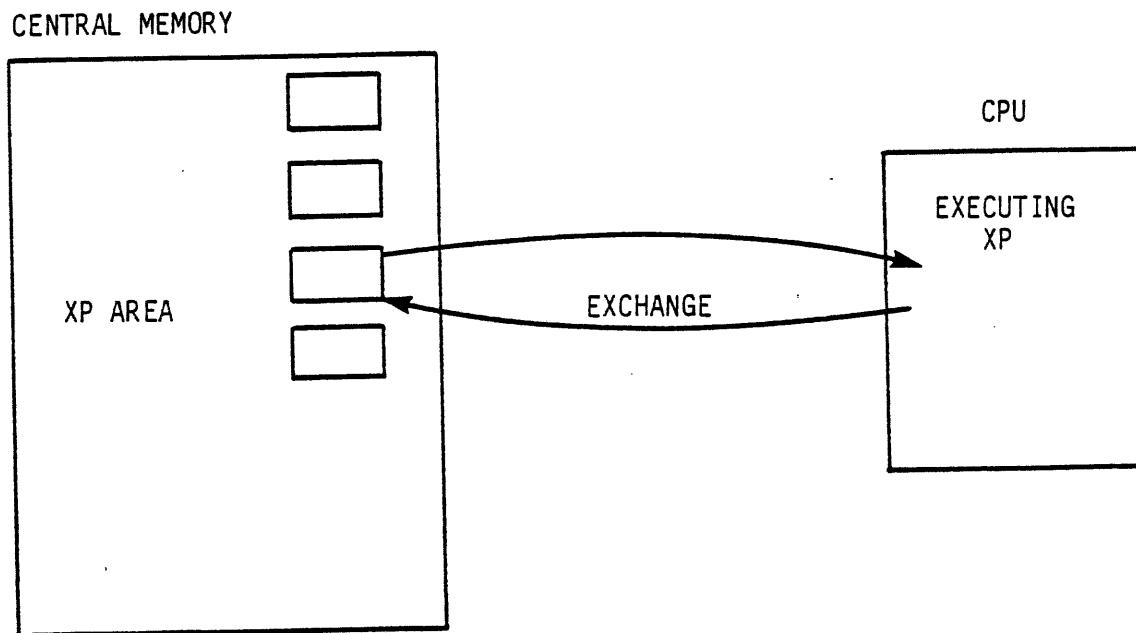
Exchange package area for CDC CYBER 170 Series,
Model 176 Computer Systems.

	59	53	35	17	0
000			P	A0	B0
001			RA	A1	B1
002			FL	A2	B2
003			PSD	A3	B3
004			RAE	A4	B4
005			FLE	A5	B5
006			NEA (MA)	A6	B6
007			EEA	A7	B7
010	X0				
011	X1				
012	X2				
013	X3				
014	X4				
015	X5				
016	X6				
017	X7				

EXCHANGE JUMP

Take the XP (exchange package) at this address and put it into the CPU hardware registers.

Take the CPU hardware registers and put them in exchange package format at this address.



EXCHANGE JUMP

MONITOR ADDRESS REGISTER (MA)

DEFINES STARTING ADDRESS OF XP FOR EXCHANGE THAT OCCURS WHEN NOT IN MONITOR MODE.

MONITOR FLAG BIT

HARDWARE "FLAG" THAT INDICATES WHETHER CPU IS INTERRUPTABLE (PROGRAM MODE) OR NOT INTERRUPTABLE (MONITOR MODE).

THE MONITOR FLAG ALSO DETERMINES HOW XJ INSTRUCTION IS TO BE EXECUTED.

XJ INSTRUCTION

013 XJ Bj+k

IF CPU IS IN MONITOR MODE, THE EXCHANGE IS MADE WITH THE ABSOLUTE ADDRESS Bj+k.

IF CPU IS IN PROGRAM MODE, THE EXCHANGE IS MADE WITH THE ABSOLUTE ADDRESS CONTAINED IN MA.

AN EXCHANGE TOGGLES THE MONITOR FLAG.

EXCHANGE JUMP

MXN INSTRUCTION

261 MXN CP

IF CPU IS IN MONITOR MODE, THE EXCHANGE
IS BLOCKED AND TREATED AS A PASS (PSN).

IF CPU IS IN PROGRAM MODE, THE EXCHANGE
IS MADE WITH THE ABSOLUTE ADDRESS CONTAINED
IN THE A REGISTER.

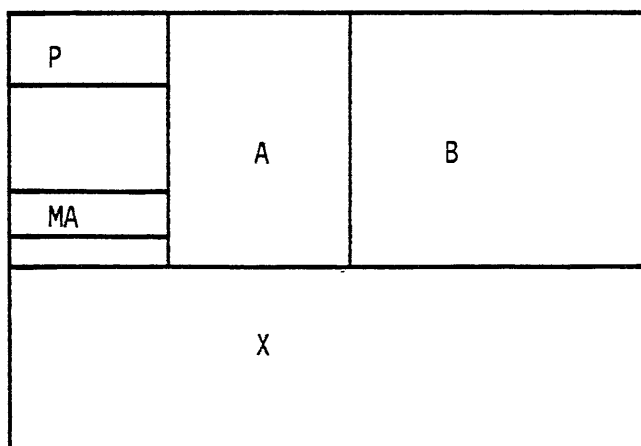
EXCHANGE JUMP

INSTRUCTION	MONITOR	PROGRAM
MXN PPU	PASS	EXCHANGE WITH ADDRESS FROM A REGISTER
XJ CPU	EXCHANGE WITH ADDRESS Bj+k 013jk kkkkk	EXCHANGE WITH ADDRESS FROM MA OF CURRENTLY EXECUTING XP

FOR EACH CONTROL POINT

(MA) = CONTROL POINT ADDRESS

THEREFORE (MA) OF EXECUTING CONTROL POINT XP IS THAT CONTROL POINT'S ADDRESS



EXCHANGE JUMP

FOUR TYPES OF EXCHANGE JUMP

- MTR
PPU MTR EXCHANGES WITH CPUMTR

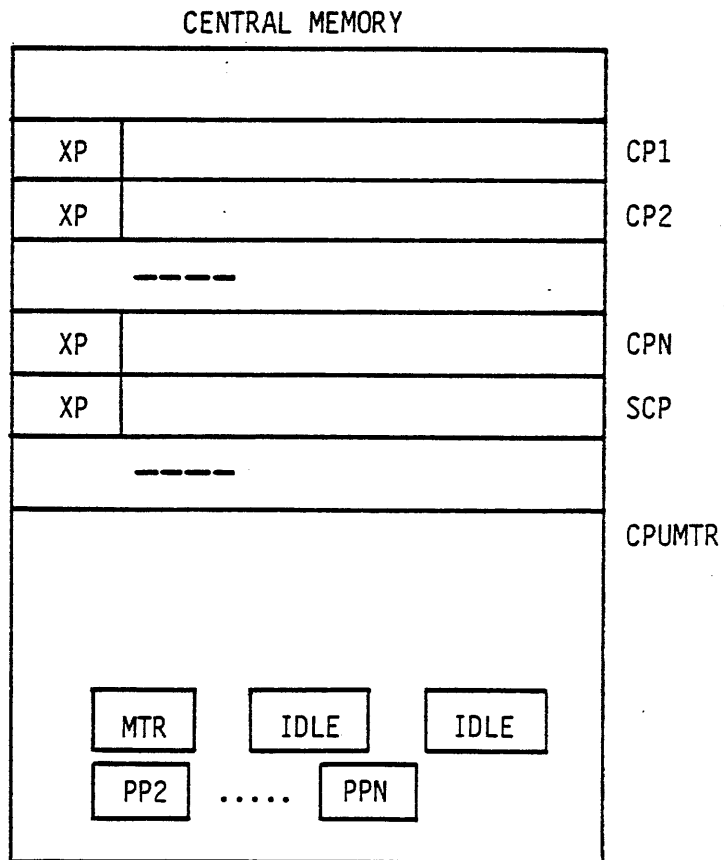
- POOL PPU
A PPU PROGRAM EXCHANGES WITH CPUMTR

- CPU PROGRAM
A PROGRAM AT A CONTROL POINT ACTIVE IN THE CPU
EXECUTES AN XJ TO EXCHANGE WITH CPUMTR

- SYSTEM CONTROL POINT
CPUMTR (IN PROGRAM MODE) EXECUTES AN XJ TO
EXCHANGE WITH MONITOR MODE CPUMTR

EXCHANGE PACKAGES

- MTR
- POOL PPU's (2-n)
- IDLE PACKAGE FOR EACH CPU
- EACH CONTROL POINT INCLUDING THE SYSTEM CONTROL POINT



EXCHANGE JUMP

MTR

4. MTR READS ITS XP'S FIRST WORD.
IF (BO)=0, THEN THE MXN WAS SUCCESSFUL
(CPU WAS IN PROGRAM MODE). OTHERWISE, MTR
REPEATS THE EXCHANGE (STEP 3) UNTIL SUCCESSFUL.

5. CPUMTR BEGINS EXECUTION AT PMN TO PROCESS THE
REQUEST IN XO.

6. WHEN COMPLETED, CPUMTR EXITS DOING

XJ B2

WHICH CAUSES MTR REQUEST PROCESSING TO COMPLETE
AND THE XP PREVIOUSLY IN EXECUTION TO BE BROUGHT
BACK INTO THE CPU AND RESUME EXECUTION.

7. WHEN MTR SENSES ITS EXCHANGE WAS SUCCESSFUL, IT
RESUMES ITS PROCESSING.

A NEW EXCHANGE REQUEST WILL NOT BE MADE WHILE
CPUMTR IS PROCESSING AN MTR REQUEST. MTR WAITS
FOR ITS EXCHANGE PACKAGE TO BECOME AVAILABLE BY
TESTING THE XP'S MA. IF (MA)=0, THE EXCHANGE
SEQUENCE WILL BE EXECUTED.

EXCHANGE JUMP

POOL PPU

1. EACH POOL PPU HAS ITS OWN EXCHANGE PACKAGE LOCATED WITHIN CPUMTR.
2. TYPICALLY, POOL PPU REQUESTS FOR CPUMTR ARE ISSUED BY PPU RESIDENT SUBROUTINE FTN.

FTN SETS UP TO DO EXCHANGE -

(P) = PPR ADDRESS IN CPUMTR WHERE EXECUTION
IS TO BEGIN

(B2) = ADDRESS OF PPU'S EXCHANGE PACKAGE WITHIN
CPUMTR

(BO) ≠ 0 MXN SUCCESSFUL FLAG

(OR) = REQUEST TO BE PROCESSED BY CPUMTR

3. FTN PERFORMS INSTRUCTIONS -

LDC ADDRESS OF PPU'S XP

MXN CP

TO EXCHANGE CPU *cp* WITH THE XP FOR THE PPU, *cp*
IS USUALLY 0 UNLESS CPU 0 IS OFF.

EXCHANGE JUMP

POOL PPU

4. FTN READS XP'S FIRST WORD TO DETERMINE IF EXCHANGE WAS SUCCESSFUL. IF (B0)=0, THE MXN WAS SUCCESSFUL. OTHERWISE, FTN REISSUES THE EXCHANGE (STEP 3) UNTIL SUCCESSFUL.

5. CPUMTR BEGINS EXECUTION AT PPR TO PROCESS THE REQUEST FROM THE OUTPUT REGISTER (OR).

6. WHEN COMPLETED, CPUMTR CLEARS BYTE 0 OF THE OUTPUT REGISTER AND EXITS BY DOING

XJ B2

WHICH CAUSES THE PREVIOUS XP TO BE BROUGHT BACK INTO EXECUTION (USUALLY).

7. FTN IS LOOPING WAITING FOR BYTE 0 OF THE OUTPUT REGISTER TO BECOME CLEAR. WHEN THIS IS SENSED, FTN RETURNS TO ITS CALLER AND EXECUTION IS RESUMED.

EXCHANGE JUMP

CPU PROGRAM

1. EACH CONTROL POINT HAS ITS OWN EXCHANGE PACKAGE IN ITS CONTROL POINT AREA.
2. THE EXCHANGE JUMP FOR A CPU PROGRAM IS ALWAYS SUCCESSFUL.
3. THE EXCHANGE WILL BE MADE WITH THE XP SPECIFIED BY THE ADDRESS CONTAINED IN MA.

MA IS ALWAYS THE CONTROL POINT AREA ADDRESS.

THE EXCHANGE PACKAGE LOCATED AT THE CPA ADDRESS HAS

(P) = MTR ADDRESS IN CPUMTR WHERE EXECUTION IS TO BEGIN FOR CPU PROGRAM REQUESTS

(B2) = CPA ADDRESS

(MA) = 0

4. THE CPU PROGRAM PLACES ITS MONITOR REQUEST IN RELATIVE LOCATION 1 (RA+1) AND DOES AN XJ INSTRUCTION. TYPICALLY, THIS IS DONE AS PART OF SYS= (COMCSYS) PROCESSING.

EXCHANGE JUMP

5. CPUMTR BEGINS EXECUTION AT ADDRESS MTR TO PROCESS THE REQUEST CONTAINED IN RA+1.

CPUMTR WOULD ALSO BEGIN EXECUTION AT MTR IF THE CPU PROGRAM HAD CAUSED AN EXCHANGE TO OCCUR BY DOING AN ILLEGAL OPERATION (HARDWARE DETECTED) SUCH AS EXECUTING A ZERO INSTRUCTION.

6. WHEN CPUMTR IS DONE PROCESSING THE RA+1 REQUEST, IT DOES A

```
      XJ B2  
MTR ....
```

WHICH RETURNS THE CONTROL POINT INTO EXECUTION (USUALLY).

THIS SEQUENCE OF CODE IN CPUMTR IS SUCH THAT THE NEXT ADDRESS IS MTR SO THE "CPUMTR" EXCHANGE PACKAGE RETURNED TO THE CONTROL POINT AREA IS PROPERLY SET WITH

(P) = MTR

7. RA+1 REQUESTS NOT PROCESSED BY CPUMTRA ARE DONE BY PPU ROUTINES. EXCEPT FOR CIO, THE CPU IS RELINQUISHED.

EXCHANGE JUMP

SYSTEM CONTROL POINT

5. CPUMTR EXITS WITH THE

XJ B2

CAUSING THE SYSTEM CONTROL POINT TO GO INTO EXECUTION
AND THE "CPUMTR" EXCHANGE PACKAGE WILL HAVE

(P) = MTR

6. WHEN PROGRAM MODE COMPLETES, IT DOES A

XJ

CAUSING AN EXCHANGE TO THE EXCHANGE PACKAGE AT THE
MA ADDRESS - THE SYSTEM CPA.

THE (P) WILL BE PRG THE PROGRAM MODE PROCESSOR SO
THAT THE NEXT EXCHANGE TO PROGRAM MODE BEGINS EXECUTION
AT THIS ADDRESS

EXCHANGE JUMP

SYSTEM CONTROL POINT (CPUMTR PROGRAM MODE)

1. CPUMTR DETERMINES THAT A PROGRAM MODE SUBROUTINE IS REQUIRED TO COMPLETE A REQUEST.
2. THE PROGRAM MODE REQUEST IS ADDED TO THE PROGRAM MODE REQUEST QUEUE (PR).
3. IF PROGRAM MODE IS CURRENTLY ACTIVE, CPUMTR EXITS WITH A

XJ B2

SUCH THAT THE "CPUMTR" EXCHANGE PACKAGE WILL HAVE

(P) = MTR

SINCE THE CPU PROGRAM (CPUMTR PROGRAM MODE) RUNS AT A CONTROL POINT (THE SYSTEM CONTROL POINT) PROGRAM MODE WILL PROCESS THE REQUEST FROM THE PR QUEUE.

4. IF PROGRAM MODE IS NOT ACTIVE, CPUMTR CALLS SUBROUTINE BCP (BEGIN CENTRAL PROGRAM) TO CAUSE PROGRAM MODE (SYSTEM CP) TO GET THE CPU.

BCP PICKS THE SYSTEM CONTROL POINT AS THE CP TO GET THE CPU - IT IS THE HIGHEST CPU PRIORITY CP. (B2) BECOMES THE ADDRESS OF THE SYSTEM CP, WHICH IS THE PROGRAM MODE XP. THE PREVIOUS ACTIVE CP'S XP (FROM ACPL) IS RESTORED TO ITS CONTROL POINT AREA.

EXCHANGE JUMP

SWITCHING CONTROL POINT EXECUTION

1. ASSUME CP4 EXECUTING IN THE CPU
 - XP AT 1000 (CPA4) HAS (P) = MTR
 - ACPL POINTS TO CPA4 (1000)
 - XP IN CPU HAS (MA) = 1000
 - CPU IS IN PROGRAM MODE

2. PP2 WRITES AN RCPM (REQUEST CPU) REQUEST FOR CP6 INTO ITS OR AND DOES A MXN

(FIGURE 1)

3. EXCHANGE OCCURS SINCE CPU IS INTERRUPTIBLE
 - XP IN CPU IS NOW PP2'S XP WITH (MA)=0
 - CP4'S XP (FROM CPU) IS NOW RESIDING AT PPU'S XP ADDRESS IN CPUMTR
 - CPUMTR IS EXECUTING AT PPR FOR PP2

(FIGURE 2)

4. CPUMTR PROCESSES PP2'S OR REQUEST.
 - (B2) = PP2 XP ADDRESS

5. RCPM PROCESSING DECIDES TO START UP CP6 BY CALLING BNJ (BEGIN NEW JOB).

EXCHANGE JUMP

SWITCHING CONTROL POINT EXECUTION

6. BNJ MOVES XP FROM (B2) TO THE XP ADDRESS SPECIFIED IN ACPL.

THIS PUTS CP4'S XP INTO CP4'S CPA.

ACPL IS SET FOR CP6'S XP ADDRESS - CPA6. (1400)

PP2'S XP IS REBUILT FOR FUTURE PPU REQUESTS -

(RA) = 0 (RAX) = 0
(FL) = MFL (FLX) =
(B1) = 1
(B2) = PP2 XP ADDRESS
(MA) = 0
ERROR MODE SET

B2 IS THEN ENTERED WITH CP6'S XP ADDRESS WHICH IS THE ADDRESS OF CPA6.

PP2'S OUTPUT REGISTER IS CLEARED.

(FIGURE 3)

7. CPUMTR EXITS DOING A

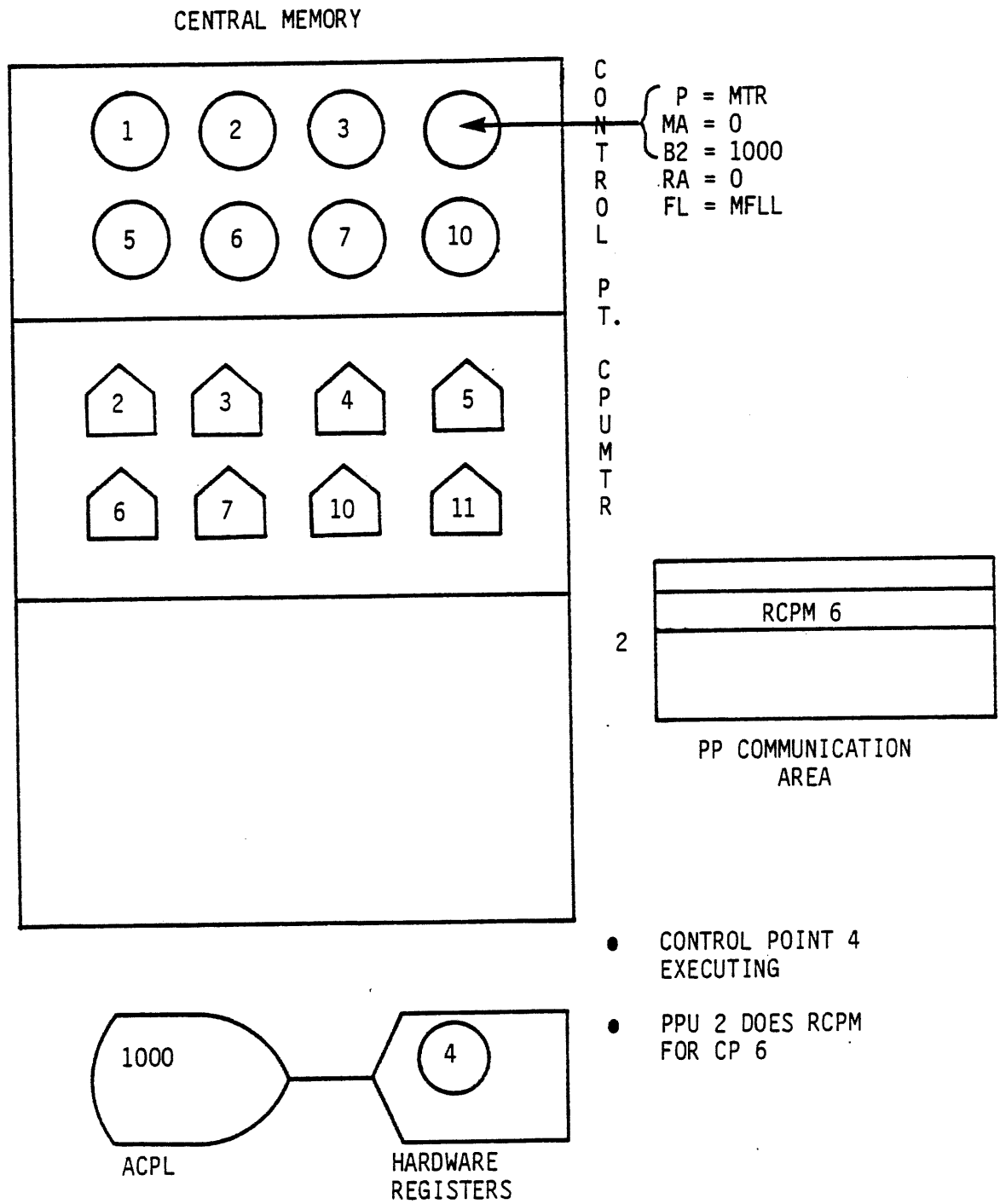
XJ B2

CAUSING THE EXCHANGE PACKAGE FOR CP6 TO ENTER THE CPU. THE "CPUMTR" PACKAGE NOW FOUND AT CPA6 HAS

(P) = MTR

(FIGURE 4)

CONTROL POINT SWITCHING



P = A
 MA = 1000
 RA = RA4
 FL = FL4

FIGURE 1

CONTROL POINT SWITCHING

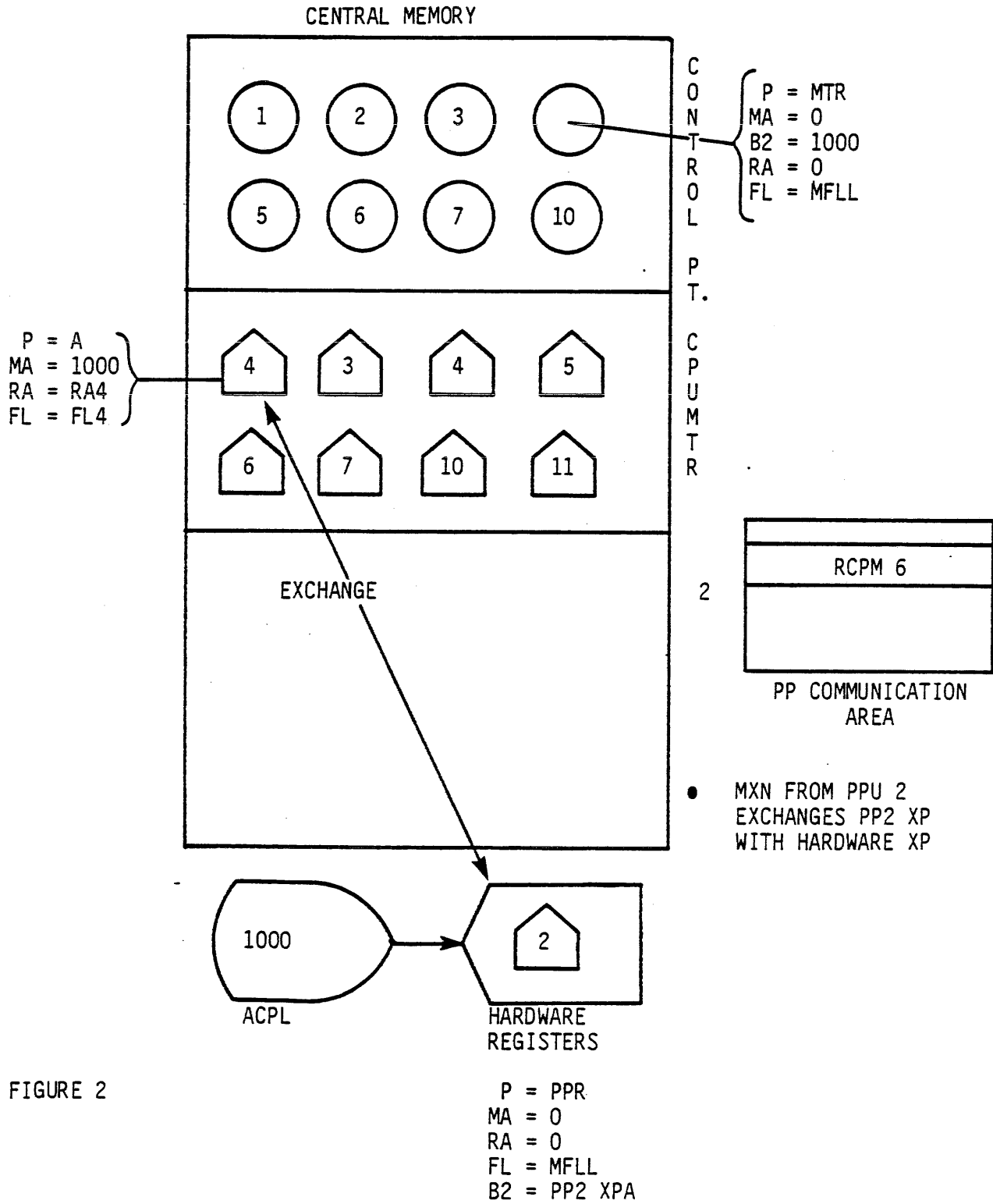


FIGURE 2

CONTROL POINT SWITCHING

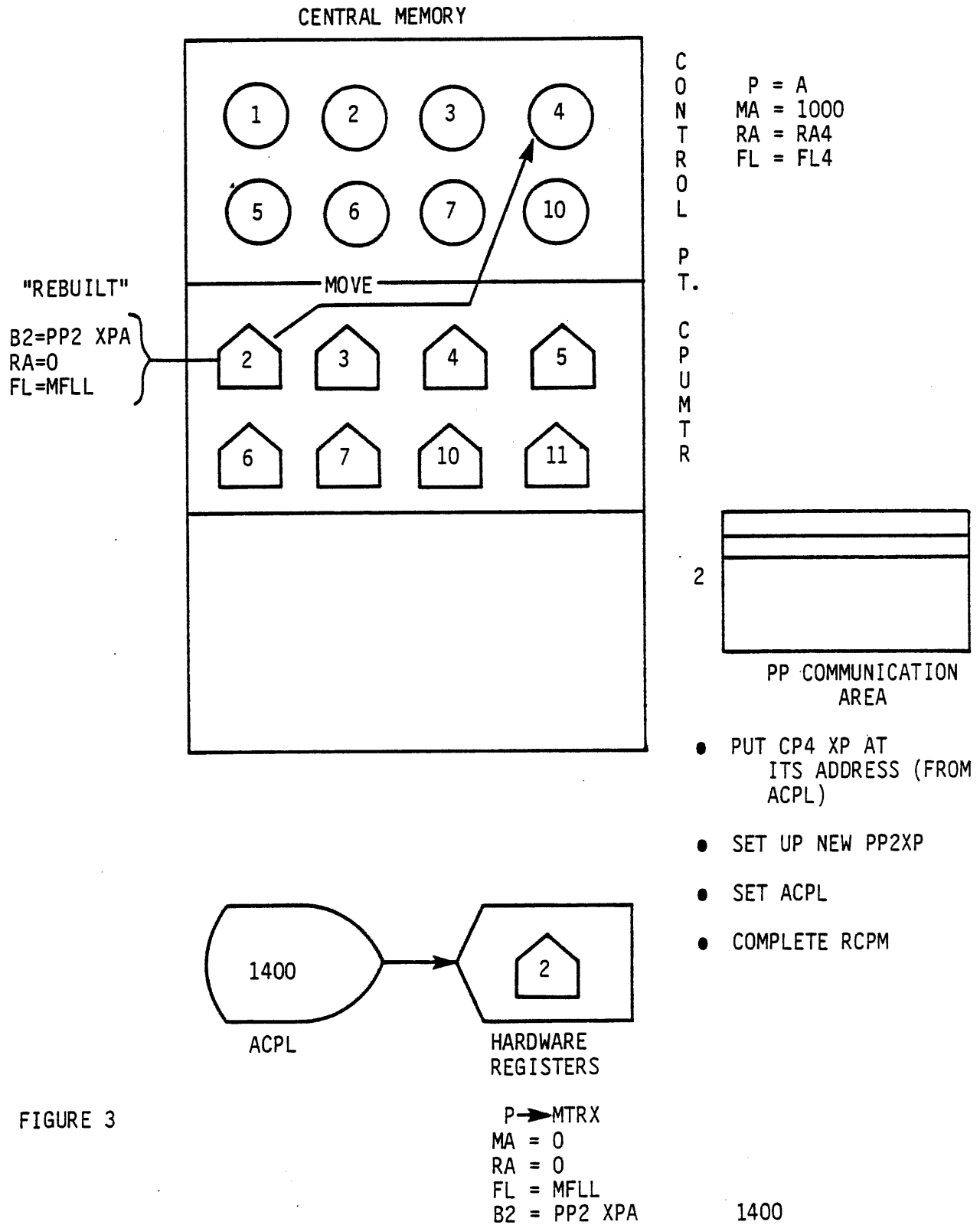


FIGURE 3

CONTROL POINT SWITCHING

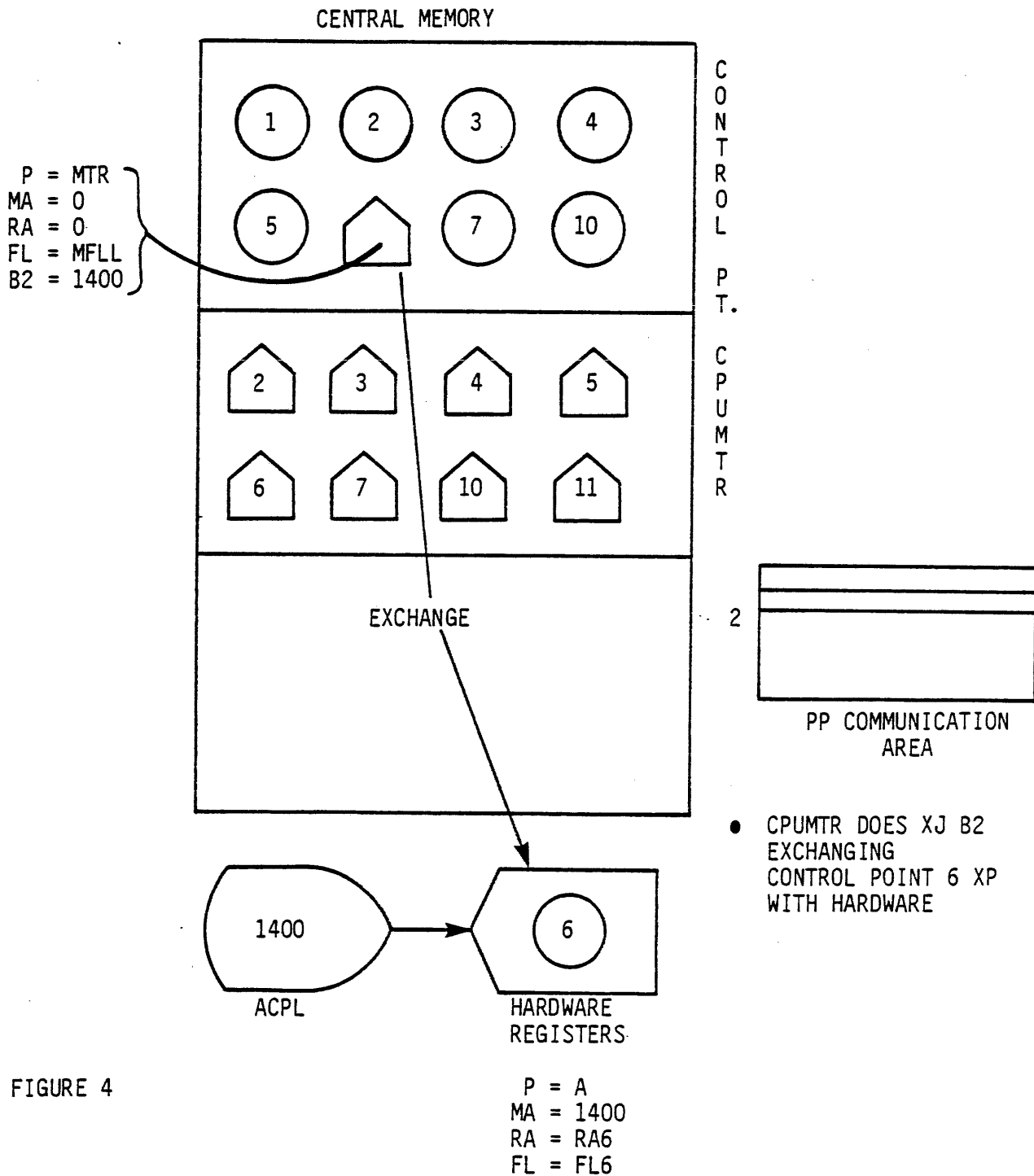


FIGURE 4

QUESTION SET LESSON 4

1. Explain the means of communication between Pool PPs, monitor (CPUMTR/MTR), and a Control Point (CPU job).
2. What exchange packages are present when CEJ/MEJ is present?
3. What does a Pool PP do to make a CPUMTR monitor function request?
4. How does MTR make a request to CPUMTR?
5. How does a CPU job make a system (monitor) request?
6. How does CPUMTR manage the exchange packages when activating a "new" control point?
7. What is the difference between CPUMTR program mode and monitor mode?
8. When in monitor mode what does a "XJ" instruction do? In program mode?

LESSON 5 DELAY AND RECALL

LESSON PREVIEW:

This lesson introduces the student to the system delay controls and the various recall mechanisms in the system. The delay controls regulate the frequency at which certain system operations are performed. The various forms of recall allow the user to optimize a CPU program to make efficient use of NOS multi-programming capabilities.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- List the system activities regulated by the delay controls.
- Explain the types of recall available in NOS and give an example of how each may be used.

REFERENCES:

NOS IMS - Chapter 1 NOS RM, 2-1-3-4, 2-11-12 NOS IHB, 8-15-16

ASSIGNMENT:

Write a CPU program using the different types of recall and measure the recall time period where possible.

SUPPLEMENTAL TEXT: RECALL

The CPU or job status in NOS is indicated by the values:

W Waiting for the CPU
X Waiting in Periodic Recall
I Auto Recall
A Job running in CPU 0
B Job running in CPU 1
" " No CPU status but other job activity in progress

Periodic Recall

"Periodic recall" means that a program is placed on recall until a certain period of time (specified by the CR delay value) has elapsed.

A program enters the "periodic recall" state by issuing a RCL RA+1 request. CPUMTR will set X status for the job and set a starting time in the control point area (word CPCW). CPUMTR eventually identifies the "oldest" job in X status. MTR recalls this job when the CR delay expires by issuing a RCLM (Recall) monitor function for that control point. The RCLM causes the job to be given W status.

Automatic Recall

"Automatic recall" means that a program is placed on recall until a particular RA+1 request has completed or is requested to resume execution by a PP program.

A program enters the "automatic recall" state by issuing a RA+1 request with the recall bit (bit 40 of RA+1) set to 1. This is usually an on recall until a particular RA+1 request has completed or is requested to resume execution by a PP program.

A program enters the "automatic recall" state by issuing a RA+1 request with the recall bit (bit 40 of RA+1) set to 1. This is usually an automatic condition since all RA+1 requests except for CIO requests and requests from jobs whose queue priority is greater or equal to MXPS are forced into automatic recall. There may be only one PP in automatic recall for a job at a given time. CPUMTR sets the CPU status to I and clears any existing X status, releases the CPU from the job, and assigns a PP to complete the RA+1 request. The PP program satisfying the RA+1 request causes the job to resume execution by dropping its PP or by clearing RA+1 and doing a RCPM (Request CPU) function for that control point. Either of these operations will cause the control point to reenter W status and wait for CPU assignment.

Auto Recall

"Auto recall" means that a program is placed on recall until the completion bit (bit 0) of a specified address is set to 1.

A program enters the "auto recall" state by issuing a RCLP RA+1 request (RCL with the recall bit (bit 40) set to 1) and a status address specified for completion bit checking. CPUMTR will set the job into X status, leaving RA+1 intact. Periodically, as controlled by the AR delay value, MTR checks for PP recalls. Jobs in I status with RA+1 requests are requested to be restarted. Jobs in X status with RA+1 requests are ignored unless the RA+1 request is an RCLP. If RCLP, that is a "auto recall" request, the completion bit is checked (bit 0 of the specified address), and if set, an RCLM (Recall) is done for the control point. If X or I status is not present, or X or I is set but no RA+1 request is present, the PP recall word RLPW is checked. If a request is present in RLPW, then a PP is requested for that PP program by a RPPM.

DELAY

DELAY SPECIFY SYSTEM DELAY PARAMETERS
 FOR PERIODIC OPERATIONS

JS JOB SCHEDULAR INTERVAL (SECONDS)

CR CPU PROGRAM RECALL INTERVAL
 HOW LONG IN X STATUS?

AR PPU AUTO RECALL INTERVAL

CS CS JOB SWITCH INTERVAL
 WHEN MTR DECIDES IT IS TIME TO DO ANOTHER JOB

RECALL

AUTOMATIC
RECALL

READ LFN,R

NEED READ TO COMPLETE AS COMPUTATION
NEEDS DATA FROM LFN

AUTO RECALL

READ LFN

COMPUTE

RECALL LFN

DO NOT NEED DATA FROM LFN IMMEDIATELY;
PROGRAM CAN DO SOME COMPUTATION BEFORE
NEEDING DATA

PERIODIC RECALL

DLY	SUBR		
	PDATE	DLYA	START
DLY1	RECALL		
	PDATE	DLYB	
	SA1	DLYA	
	SA2	A1+B1	
	SX5	B1+B1	
	BX2	X1-X2	
	BX5	X5-X2	
	ZR	X5,DLY1	IF MORE
	JP	DLYX	

QUESTION SET LESSON 5

1. What are the five CPU or job status values in NOS?
2. What is meant by the terms: Periodic Recall, Automatic Recall, and Auto Recall?

LESSON 6 CPUMTR

LESSON PREVIEW:

This lesson introduces the student to CPUMTR and overviews the communication between the user CPU program, Pool PP routines, and the system monitors: CPUMTR and MTR.

OBJECTIVES:

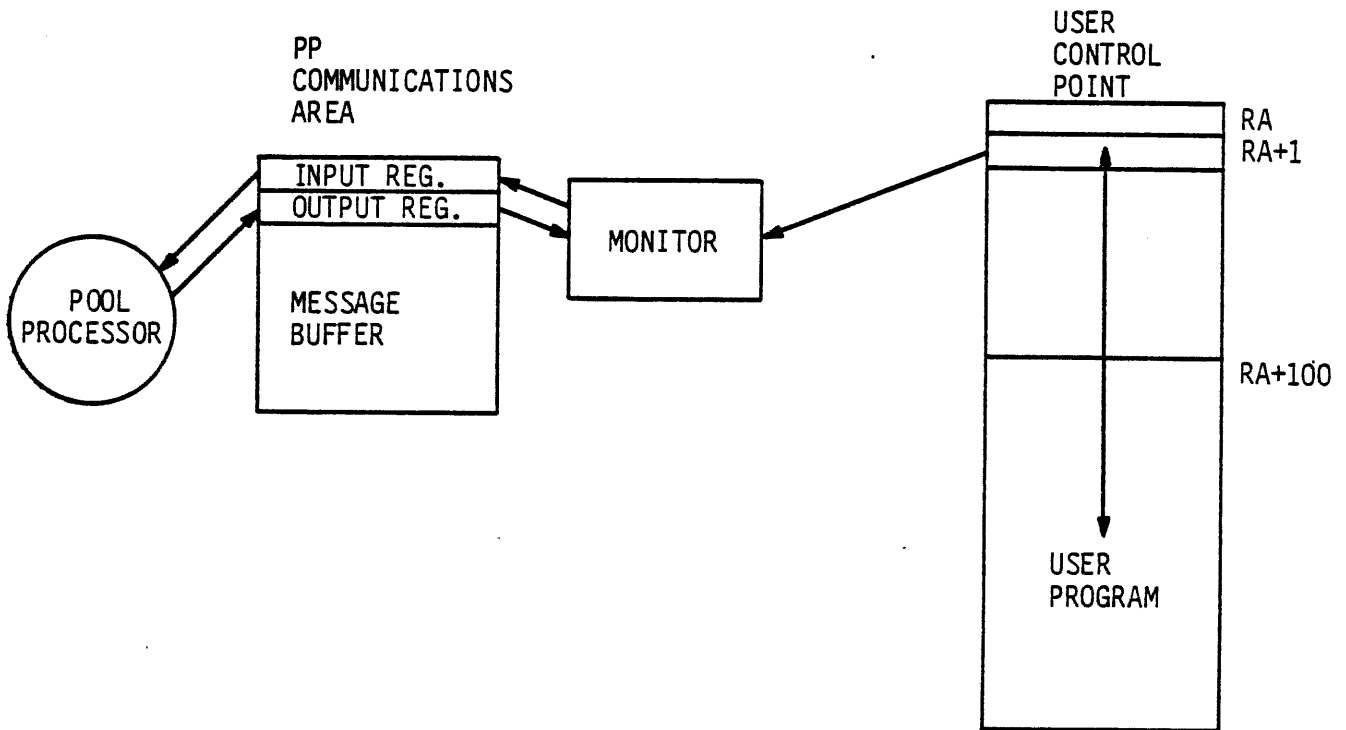
Upon the successful completion of this lesson, the student should be able to:

- Explain the communication between the system monitors (CPUMTR and MTR) and with user CPU programs and Pool PP routines.
- Explain the modular structure of CPUMTR, identifying what hardware/software property requires the loading of a corresponding module of CPUMTR.
- Describe the conditions under which CPUMTR is entered from a CPU program and what processing is done by CPUMTR for this case.
- Describe the conditions under which CPUMTR is entered from MTR and what processing is done by CPUMTR for this case.
- Describe the conditions under which CPUMTR is entered from a Pool PP and what processing is done by CPUMTR for this case.
- Describe the processing done by CPUMTR to begin and suspend execution of a CPU program.
- Describe the processing done by CPUMTR to assign a PP to a job (control point).
- Describe the processing done by CPUMTR to invoke job scheduling.
- Describe the job advancement process.
- Recognize the RA+1 requests, MTR/CPUMTR requests, and PP monitor functions processed by CPUMTR.

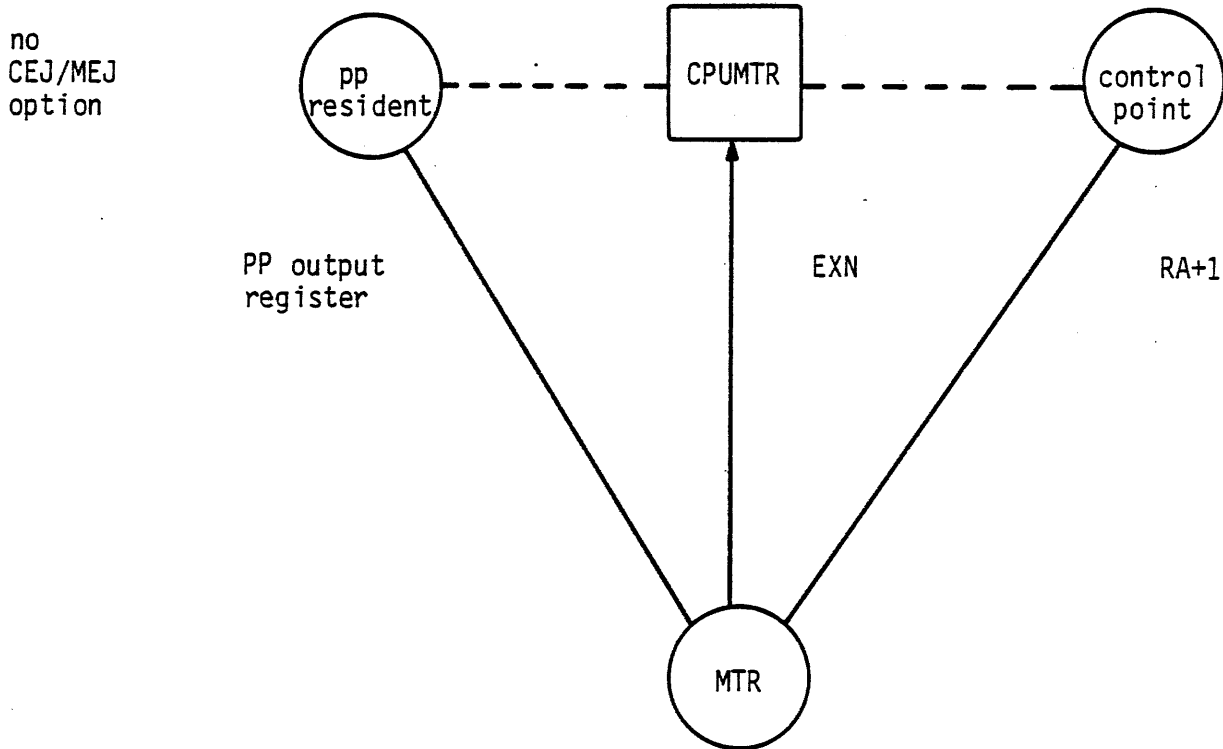
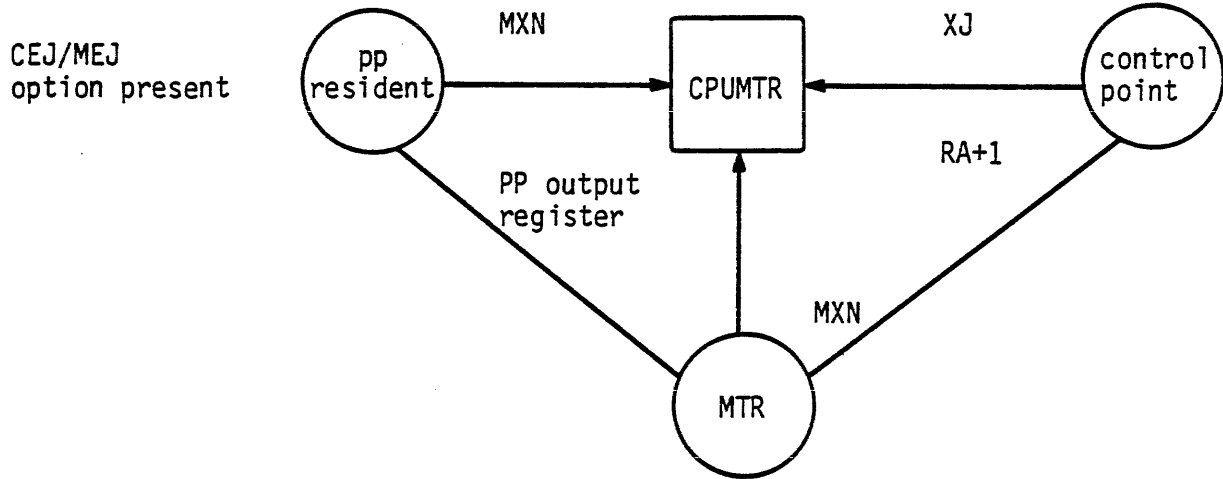
REFERENCES:

NOS IMS - Chapter 3

SYSTEM INTERACTION



Monitors Interaction



CPUMTR

MONITOR MODE
PROGRAM MODE
"CONDITIONAL" CODE BLOCKS
CMU/OCMU
CMUMTR/OCMUMTR
CEJ/OCEJ
EXPACS
DCP
SUBCP
SCP FACILITY
SCPUEC
ECS
ECSBUF
MMF/OMMF
MMFBUF
UEC
VMS
CP176
XP176

CPUMTR

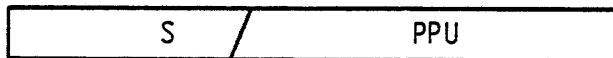
CONTROL WORDS

PX PROGRAM MODE EXIT REQUEST
 = 1 PROGRAM MODE COMPLETE
 = -1 PP REQUESTED BY PROGRAM MODE
 = 0 PX MAY BE USED AS TEMPORARY IF CEJ/MEJ NOT PRESENT

SM STORAGE MOVE REQUEST



PR PROGRAM MODE REQUEST
 STACK OF REQUESTS TO BE DONE IN PROGRAM MODE



S = STORAGE MOVE (BIT 30)
PPU = PPU REQUESTS (BITS 0 - 19)

ST CPU START TIMES (TWO WORDS)

STARTING TIMES FOR EACH CPU ARE UPDATED EACH TIME THAT THE CPU JOB TIME IS UPDATED.

CPUMTR

CONTROL WORDS

CR CPU REQUESTS (TWO WORDS)

STACK OF REQUESTS FOR CPU USAGE.
EACH BIT REPRESENTS A CP THAT NEEDS THE CPU.

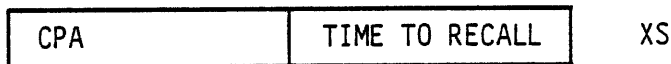
THE SECOND WORD (CR+1) CONTAINS A MASK BIT WHICH DETERMINES WHERE TO
START THE SCAN.

XS CPU RECALLS FOR INITIATED JOBS.

PS CPU RECALL FOR NO PPU.

XS INDICATES THE NEXT JOB TO BE RECALLED BY MTR.

PS INDICATES THE NEXT JOB TO BE RECALLED WHEN PP IS AVAILABLE.



CPUMTR

CONTROL WORDS

PP PP PRIORITY REQUEST

(PP) = OUTPUT REGISTER ADDRESS OF A PP WITH PENDING RPPM.

IF NEGATIVE, 1SP WAS REQUESTED BUT NO PPs WERE AVAILABLE.

IF MTR ISSUED THE RPPM, THE OUTPUT REGISTER WILL BE CLEARED
BUT PP IS RESERVED FOR MTR.

JA JOB ADVANCE REQUESTS

STACK OF BITS REPRESENTING CPS WAITING TO BE ADVANCED BUT NO PPs
WERE AVAILABLE TO DO SO.

CPUMTR

CONTROL WORDS

JS INPUT REGISTER FOR 1SJ CALL
SYSTEM CONTROL POINT NUMBER IS SET DURING CPUMTR PRESET

1 S J	SCP	
-------	-----	--

MP INPUT REGISTER FOR 1MA CALL
1MA IS USED FOR DAYFILE MESSAGES (MSG)
REQUEST FOR STORAGE INCREASES (MEM), AND SYSTEM CONTROL POINT
OPERATIONS (SSC,SSF).

1 M A	
-------	--

RC AUTO RECALL RA+1 REQUEST
USED TO TEST FOR RCLP

RCLP	
------	--

AM ACTIVITY MASK FOR PP AND TAPES
USED TO MASK NUMBER OF ASSIGNED PPs AND ACTIVITY COUNT FROM STSW

0037	0000	7777	0000	0000
------	------	------	------	------

CPUMTR

ENTRY FROM CPU PROGRAM

MTRX

.

.

.

XJ1 XJ B2 EXCHANGE TO PROGRAM

.

.

.

1. READ RA WORD FROM XP
2. READ (RA+1)
3. IF RA=0, CHECK PROGRAM MODE EXIT CALL
4. IF (RA+1) = 0, PROCESS CPU REQUEST (CPR)
5. IF CYBER 176, CHECK PSD REGISTER FOR ERRORS. IF NONE, CONTINUE WITH STEP 6. IF ERRORS, FORMAT (RA) TO LOOK LIKE A NON-CYBER 176 HARDWARE ERROR AND SET ARET (ARITHMETIC) ERROR FLAG.
6. IF (P) > 2, EXCHANGE BACK (GO TO XJ1)
7. CHECK JOB STATUS (CJS)

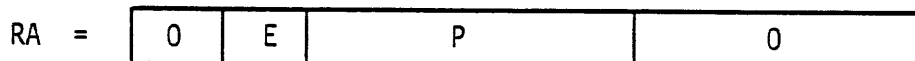
NOTE

ON A HARDWARE INTRODUCED INTERRUPT (MODE ERROR)

(P) = 0

EXIT MODE BITS = BITS 48 - 53 OF (RA)

P ADDRESS OF ERROR = BITS 30 - 47 OF (RA)



CPUMTR

CHECK JOB STATUS

CHECK FOR: MODE ERRORS, PROGRAM STOPS, TIME LIMIT, SRU LIMIT

1. READ RA, READ P, READ FL.
2. IF $P \geq FL$, GO SET PSET ERROR FLAG.
3. IF $P = 0$ OR 1 AND $(RA+1) = 0$, THE EXIT MODE BITS ARE RETRIEVED FROM (RA) AND EITHER PEET OR ARET ERROR FLAG IS SET.
4. READ (RA+P). IF ZERO INSTRUCTION, SET PSET ERROR FLAG.
5. CHECK SRUW FOR TIME LIMIT OR SRU LIMIT EXCEEDED FLAGS. SET TLET OR SRET ERROR FLAG.

CPUMTR

BEGIN CENTRAL PROGRAM (BCP)
BEGIN NEW JOB (BNJ)
END CENTRAL PROGRAM (ECP)

BCP - BEGIN CENTRAL PROGRAM

1. IF JOB IS IN W STATUS, CALL CJS. IF CJS FINDS NO ERRORS, STEP 6 IS DONE.
2. IF JOB HAS AN RCLP IN (RA+1) AND COMPLETION BIT IS SET, CLEAR RA+1, AND CALL CJS. IF CJS FINDS NO ERRORS, STEP 5 IS DONE. IF COMPLETION BIT IS NOT SET, GO TO STEP 4.
3. FOR NON-RCLP JOBS, CJS IS CALLED. IF CJS FINDS NO ERRORS, STEP 5 IS DONE.
4. ENTER JOB INTO X STATUS.
5. SET W STATUS FOR CONTROL POINT.
6. READ ACPL FOR THIS CPU TO FIND CURRENT ACTIVE JOB.
7. IF THIS JOB'S PR (FROM JCIW BYTE 0) < CURRENT JOB'S PR, THIS CP'S BIT IS MERGED INTO CR CONTROL WORD AND BCP RETURNS TO MTRX.
8. IF THIS JOB'S PR \geq CURRENT JOB'S PR, THIS CP'S BIT IS MERGED INTO CR.
9. BNJ (BEGIN NEW JOB) IS ENTERED.

CPUMTR

BNJ - BEGIN NEW JOB.

BNJ SETS UP EXCHANGE PACKAGES FOR "NEW" CPU PROGRAM EXECUTION.

1. COMPUTE CPU TIME FOR CURRENT JOB.
2. ACPL IS SET TO REFLECT NEW XP ADDRESS AND (B2) IS SET TO THIS ADDRESS ALSO.
3. IF THE OLD XP WAS NOT WHERE IT BELONGS, IT IS MOVED TO THE ADDRESS SPECIFIED IN THE OLD ACPL. THIS WOULD BE THE CASE IF A PPU CAUSED ANOTHER JOB TO GET THE CPU.

IF THE XP HAD TO BE MOVED, THEN A "NEW" XP IS BUILT WHERE IT HAD BEEN . . .

RA = 0
(B1) = 1
FL = MACHINE SIZE
(B2) = ADDRESS OF THIS PACKAGE
RAX = 0
FLX = ECS SIZE
(MA) = 0
(EM) = EEMC OR EEMC + 60B IF CYBER 176

4. THE ERROR EXIT ADDRESS (EEA) IS SET IN THE XP, IF CYBER 176

BNJ EXITS TO ADDRESS MTR TO TEST RA AND RA+1 FOR THE JOB BEING GIVEN THE CPU.

CPUMTR

ECP - END CENTRAL PROGRAM

1. REQUEST FOR THIS JOB CLEARED FROM CR.
2. REQUEST SET FOR THIS JOB IN XS.
3. STATUS IN STSW SET TO X OR I.
4. IF JOB WAS NOT RUNNING (ACPL NOT THIS JOB), EXITS CPUMTR.
5. IF JOB WAS RUNNING AND NO OTHER CR REQUESTS WERE FOUND, THE IDLE JOB IS RUN AFTER COMPUTING THE TIME FOR THIS JOB (CPT).
6. THE CR WORD IS SEARCHED FOR OTHER JOBS.
(CR+1) DETERMINES WHERE TO START EXAMINING JOBS WAITING FOR THE CPU.
THE PR (JCIW BYTE 0) OF THE CURRENT JOB AND WAITING JOBS ARE COMPARED FOR JOBS WANTING THIS CPU. THE HIGHEST PRIORITY JOB FOR THIS CPU IS FOUND.
7. THE CR REQUEST FOR THE "NEW" JOB IS CLEARED.
8. CPT IS CALLED TO DO ACCOUNTING FOR THE "OLD" JOB WITH CONTROL RETURNING TO BNJ WHEN CPT IS DONE.

CPUMTR

CPT - COMPUTE CPU TIME

CPT IS CALLED WHENEVER A JOB RELINQUISHES THE CPU.

1. THE AMOUNT OF TIME IN THE CPU IS DETERMINED BY

$$\Delta T = RTCL - ST$$

2. THE CURRENT RTCL TIME IS SET INTO THE START TIME (ST) FOR THE CPU.
3. IF CONTROL POINT 0 OR CPU MULTIPLIER (S0 OR S1) IS ZERO, THE ΔT IS NOT SCALED BY S0 OR S1.
4. CPTW (CPU TIME) IS ADVANCED BY ΔT .
5. IF TIME LIMIT HAS BEEN REACHED, THE TIME LIMIT FLAG (BIT 58) IS SET IN SRUW.
6. IF SRU ACCUMULATION IS ENABLED (BIT 59 OF MP3W CLEAR), THE SRU LIMIT IS CHECKED AND SRU LIMIT FLAG (BIT 56) SET IN SRUW, IF THE LIMIT HAS BEEN REACHED. THE CHANGE IN CPU TIME IS REFLECTED IN THE SRU ACCUMULATOR SRUW.

$$\begin{aligned} SRUW &= \Delta T - S0 * CPM + SRUW \\ &= \Delta T - S1 * CPM + SRUW \end{aligned}$$

CPUMTR

PP ASSIGNMENT

APJ - ASSIGN PPU JOB
APS - ASSIGN PPU AND SEARCH LIBRARY
SPL - SEARCH PERIPHERAL LIBRARY

APJ - ASSIGN PPU JOB

(RA+1) REQUEST NOT PROCESSED WITHIN CPUMTR. CIO (RA+1) REQUESTS ENTER APJ AT STEP 3

1. FORCE AUTO RECALL IF $QP < MXPS$.
2. IF OTHER PPU's or TAPE ACTIVITY (USE AM MASK), FORCE X STATUS (IF $QP < MXPS$).
3. IF PP SATURATION ($NP=0$) OR IF MTR REQUESTING ONLY PP ($PP = 0$), SET PS AND X STATUS.
4. IF ROLLOUT SET (JCIW BIT 24 SET) OR IF JOB EXCEEDS NPPS AND LESS THAN 3 PPs ARE AVAILABLE OR IF PLD LOCKED \rightarrow FORCE X STATUS.
5. SET RECALL BIT AS BIT 41 AND CP NUMBER AS BITS 40-36.
6. CALL APS.
7. IF I STATUS (AUTO RECALL) CALL, SET OUTPUT REGISTER ADDRESS OF PP ASSIGNED INTO RA+1 AND CALL ECP: RETURN OTHERWISE.

CPUMTR

APS - ASSIGN PPU AND SEARCH LIBRARY

FROM APJ OR RPPM REQUEST + OTHERS

NP NEXT AVAILABLE PPU

INPUT REGISTERS OF ALL AVAILABLE PPU_s ARE LINKED TOGETHER. THE START OF THIS LINKED STACK IS (NP) = (PPAL). THE END OF THE STACK IS A ZERO ADDRESS. WHEN PP IS ASSIGNED, ITS IR IS PLACED INTO NP. WHEN PP IS DROPPED, (NP) IS STORED INTO ITS IR AND THE IR ADDRESSED IS STORED IN NP.

1. IF NO PP AVAILABLE (NP=0), RETURN
2. IF CP FIELD LENGTH BEING MOVED, RETURN
3. CALL SPL
4. IF LIBRARY LOCKED, RETURN
5. PUT PROGRAM LOAD PARAMETERS INTO THE PP OUTPUT REGISTER
6. PUT COPY OF INPUT REGISTER IN MESSAGE BUFFER
7. ADJUST NP STACK LINKAGE
8. INDICATE DIRECTORY SEARCHED BY CLEARING BYTE 0 UPPER 6 BITS OF INPUT REGISTER
9. UPDATE STSW PP COUNT

CPUMTR

SPL - SEARCH PERIPHERAL LIBRARY

CALLED BY APS OR SPLM

1. RETRIEVE PERIPHERAL LIBRARY DIRECTORY (PLDP) POINTER FROM CMR
2. IF LIBRARY LOCKED, I.E., PLD ADDRESS = 0 AS WOULD BE THE CASE DURING A SYSEDIT, RETURN
3. SEARCH DIRECTORY FOR MATCH BY A BINARY SEARCH
4. IF NO MATCH AND 6XX, HANG
5. IF NO MATCH, USE SFP (SCOPE FUNCTION PROCESSOR) AS THE ROUTINE TO BE LOADED
6. RETURN LOAD PARAMETERS FOR ROUTINE (IF MATCH) OR SFP (NO MATCH)

CPUMTR

START UP SCHEDULER

SJS - START JOB SCHEDULER

CALLED BY RSJM, DPPM, ARTF, SFL.

RSJM TO START IT UP IF JOBS CHANGE.

DPPM IF 1SP IS WAITING FOR A PPU.

ARTF IF SCHEDULER CYCLE TIME HAS EXPIRED (RTCL-(JSCL +1)).

SFL AFTER ADJUSTING FIELD LENGTH.

1. IF SCHEDULING ALREADY ACTIVE, RETURN.
2. IF 1SP CYCLE TIME HAS ELAPSED, CALL APS FOR 1SP IF PP IS AVAILABLE.
3. IF PP IS NOT AVAILABLE FOR 1SP, SET REQUEST INTO PP CONTROL WORD SO THAT 1SP GETS NEXT AVAILABLE PPU.
4. IF 1SP IS NOT CALLED, 1SJ WILL BE. APS IS CALLED FOR 1SJ. IF PP IS NOT AVAILABLE, THAT'S OK.

CPUMTR

XS/PS CONTROL

XS

1. WHEN ENTERING X STATUS, THE CURRENT RTCL IS SET INTO CONTROL POINT WORD CPCW.
2. IF NO OTHER JOBS ARE IN RECALL ((XS)=0), XS IS ENTERED WITH THE CPA AND MSCS BYTE 1 - CPU RECALL VALUE (DELAY CR).
3. IF XS IS SET, THE JOB WILL HAVE TO WAIT ITS TURN.
4. IF A JOB IS TAKEN OUT OF X STATUS, CPCW IS CLEARED. IF THE JOB WAS IN XS, A NEW XS JOB WILL BE FOUND - THE OLDEST JOB ON X RECALL.
5. XS PROVIDES A FAST MECHANISM TO GET JOBS OUT OF RECALL WITHOUT A LOT OF OVERHEAD.

PS

IF PS IS ALREADY SET, XS CONTROL IS EXERCISED. OTHERWISE, THE REQUEST IS ENTERED INTO PS.

PS CONTROL IS ONLY USED AT SATURATION BY APJ AND SCP FACILITY.

CPUMTR

JOB ADVANCEMENT

- BY SCHEDULER STARTING NEW JOB
- NO ACTIVITY AT CONTROL POINT AND W AND X BITS CLEAR
- DIS OR EQUIVALENT WISHES TO PROCESS CONTROL STATEMENT OR ERROR FLAG

JAV - JOB ADVANCE

JOB IS ADVANCED (I.E., CALL 1AJ) IF PP IS AVAILABLE AND JOB ADVANCE CONDITIONS MET. IF NO PP IS AVAILABLE, JOB ADVANCE FLAG (STSW BIT 53) IS SET AND THE CPU DROPPED.

IF ROLLOUT FLAG SET (JCIW BIT 24), THEN

- NO PPs ASSIGNED
- PP AVAILABLE

IF ROLLOUT FLAG NOT SET, THEN

- NO PPs ASSIGNED
- PP AVAILABLE
- NO CPU ACTIVITY
- NO PPU IN RECALL (RLPW)
- NO TAPE ACTIVITY
- NO WAIT RESPONSE/LONG TERM CONNECTIONS
- FNT INTERLOCK NOT BUSY

JA IS SET WITH BIT FOR THIS JOB UNTIL 1AJ IS CALLED FOR THIS JOB.

CPUMTR

JOB ADVANCEMENT

1AJ IS CALLED BY A CALL TO APS

THE JAV SUBROUTINE IS CALLED:

BY SEF (SET ERROR FLAG)

BY END (RA+1) CALL PROCESSING

BY ROLF MTR/CPUMTR FUNCTION

BY CCAM

BY DCPM

BY DPPM

CPU PROGRAM REQUESTS

(RA + 1 REQUESTS)

18

6

36

NAME	R E C A L L	ARGUMENT(S)
------	----------------------------	-------------

ABT ABORT JOB
CIO CIRCULAR I/O
CLO CLOSE (CONVERTS TO CIO)
CPM CONTROL POINT MANAGER
END END JOB
LDR REQUEST OVERLAY LOAD
LDV REQUEST LOADER ACTION
LOD REQUEST AUTO LOAD OF RELOCATABLE
MEM REQUEST MEMORY
MSG SEND MESSAGE
OPE OPEN (CONVERTS TO CIO)
PFL SET (P) AND CHANGE FL

RCL PLACE PROGRAM ON RECALL
RFL REQUEST FIELD LENGTH
RPV RETRIEVE
RSB READ SUB-SYSTEM BLOCK
SIC SEND INTER-CONTROL POINT BLOCK
SPC SPECIAL PPU REQUEST ($MXPS \leq QP$)
TIM REQUEST SYSTEM TIME
XJP INITIATE SUB-CONTROL POINT (SUBCP)
XJR PROCESS EXCHANGE JUMP REQUEST (SUBCP)
SSC SUBSYSTEM CALL (SCP)
SSF SUBSYSTEM FUNCTION CALL (SCP)

ALL OTHER RA+1 REQUESTS ARE ATTEMPTED TO BE SATISFIED BY A PPU PROGRAM HAVING THE SPECIFIED REQUEST NAME.

PPU MONITOR REQUESTS

ARTF	ADVANCE RUNNING TIME
IARF	INITIATE AUTO RECALL
EPRF	ENTER PROGRAM MODE REQUEST
MRAF	MODIFY RA
MFLF	MODIFY FL
SCSF	RESET CPU I STATUS
SMSF	SET MONITOR STEP
CMSF	CLEAR MONITOR STEP
ROLF	SET ROLLOUT FLAG & CHECK JOB ADV.
ACSF	ADVANCE CPU JOB SWITCH
PCXF	PROCESS CPU EXCHANGE REQUEST
ARMF	ADVANCE RUNNING TIME & MMF CLOCKS
MREF	MODIFY ECS RA
MFEF	MODIFY ECS FL

PPU MONITOR REQUESTS

(PROGRAM MODE)

MSTF	STORAGE MOVE
PDMF	PROCESS DOWN MACHINE
PMRF	PROCESS INTER-MACHINE REQUEST
MECF	MOVE ECS STORAGE
TECF	PERFORM ECS TRANSFER (FOR ECXM)

PPU REQUESTS

ABTM	ABORT CONTROL POINT
ACTM	ACCOUNTING
CCAM	CHANGE CONTROL POINT ASSIGNMENT
CEFM	CHANGE ERROR FLAG
CKSM	CHECK SUM SPECIFIED AREA
CSTM	CLEAR STORAGE
DCPM	DROP CPU
DLKM	DELINK TRACKS
DPPM	DROP PPU
DTKM	DROP TRACKS
ECSM	ECS TRANSFERS

IAUM	INTERLOCK AND UPDATE
JACM	JOB ADVANCEMENT CONTROL
LCEM	LOAD CENTRAL PROGRAM
LDAM	LOAD ADDRESS FOR MASS STORAGE DRIVERS
MXFM	MAXIMUM FUNCTION NUMBER
PIOM	PP IO VIA CPU
RCLM	RECALL CPU
RCPM	REQUEST CPU
RDCM	REQUEST DATA CONVERSION
RLMM	REQUEST LIMIT
RPPM	REQUEST PPU TO BE ASSIGNED
RSJM	REQUEST JOB SCHEDULER
RTCM	REQUEST TRACK CHAIN

SFBM SET FILE BUSY
SFIM SET FNT INTERLOCK
SPLM SEARCH PERIPHERAL LIBRARY
STBM SET TRACK BIT
TDAM TRANSFER DATA BETWEEN JOB AND MESSAGE BUFFER
TIOM TAPE I/O PROCESSOR
UDAM UPDATE CONTROL POINT AREA
VMSM VALIDATE MASS STORAGE

MXFM MAXIMUM FUNCTION NUMBER

PP HUNG INDICATES SOMETHING WRONG WAS DETECTED DURING PROCESSING OF THESE FUNCTIONS

QUESTION SET LESSON 6

1. Who recognizes all RA+1 requests?
2. How is a PP assigned to a job to complete a RA+1 request?

LESSON 7 MTR

LESSON PREVIEW:

This lesson introduces the student to MTR, the portion of the system monitor that resides in the reserved PP, PP 0.

In addition, the monitor auxiliary PP routines, 1MA, 1MB, 1MC, will be studied.

This lesson contains a discussion of the philosophy of channel management in NOS.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe the processing done or initiated from the main loop of MTR.
- Explain how NOS updates its real time clock and why the clock must be updated at least every four milliseconds.
- Explain why MTR checks CPU programs for RA+1 requests.
- Explain the operation of the various DELAY intervals.
- Explain how MTR processes recalls.
- Describe the logic MTR uses to determine which control point it should request CPUMTR to assign the CPU.
- Recognize PP monitor functions that are processed by MTR.
- Discuss the roles played by the monitor auxiliary PP routines 1MA, 1MB, 1MC.
- Discuss the channel management and interlock philosophy in NOS.

REFERENCES:

NOS IMS - CHAPTER 3

SUPPLEMENTAL TEXT: CHANNEL MANAGEMENT PHILOSOPHY

NOS performance is directly related to channel usage. Consider a very minimal configuration in which there are two mass storage devices and one channel access to them.

All system, temporary, dayfile, permanent file, in fact all activity will occur over that one channel. This channel will almost always be busy. This causes a lot of waiting for that channel to become free.

Adding a second channel is called "dual access" and improves system performance, since the number of paths to the system, temporary, permanent files, etc., has been doubled.

NOS manages its channels and access to the equipments on them by a series of monitor functions and a channel reservation table. All channels must be reserved by the PP performing an operation over them. The PP reserving (owning) the channel is indicated in the channel reservation table. The channel reservation table is indexed by channel number and the PP having the channel is referenced by its PP index, not its PP number. (Remember the PP index is a reference from the beginning of the PP Communication area; thus PP 20 is actually PP index 12.)

To reserve a channel, the PP issues a RCHM (Request Channel) monitor function. If one of the channels in the request is free, it will be given to the requesting PP and an entry made in the channel reservation table. When the PP is done with the channel, it is returned via the DCHM (Drop Channel) monitor function, which clears the channel reservation table entry and issues an operation complete on the channel (if necessary). Monitor function CCHM (Check Channel) is also used in the channel reservation process. CCHM checks a specified channel and if that channel is available, assigns it to the PP and updates the channel reservation table. CCHM is primarily used in channel testing situations.

Channels should be requested and released by the use of the RCHAN and DCHAN macros. The PP program which issues these macros or manipulates channels using monitor functions RCHM and DCHM must allow for a storage move when requesting a channel.

If the channel(s) requested by a RCHAN macro or RCHM monitor function is(are) reserved, MTR will not return control to the calling PP program until the channel (or one of the channels) can be reserved for the calling PP. PP programs should not test channels by the use of the RCHAN/RCHM mechanism, as this could cause the PP to loop infinitely if the channel never becomes available. Monitor function CCHM should be used instead as it returns to the calling PP with an indication of the success or failure in reserving the desired channel and the calling PP can then process this status in an appropriate manner.

If the channel that is requested to be released by a DCHAN macro or the DCHM monitor function is not reserved to the calling PP, a HUNG PP condition will be detected.

Some monitor functions that deal with mass storage, namely, DSWM (Driver Seek Wait) and DEPM (Disk Error Processing Message) return the mass storage channel if held by the requesting PP in order to perform the desired operation without

causing a channel conflict (the PP would be trying to get a channel it already has). When control is returned to the PP, the original channel or second channel in dual channel access situations will have been reserved for the PP.

These monitor functions are all performed in MTR. MTR keeps a flag to indicate that the channel reservation table has been altered and will write it back to CMR only once per pass through its main loop.

As mentioned earlier, performance is directly related to channel usage. To minimize the amount of time a PP has a channel reserved, the system (and all system programmers) follow a general rule that all "housekeeping", such as mass storage space allocation, is not done with the channel reserved. This includes such operations as a pause (PRLM) and issuing dayfile messages (DFMM). Unnecessary channel reservations prevent other programs from using that channel or may cause the system to hang on a channel reservation conflict.

NOS also uses the terms "dedicated" and "non-dedicated" channels. A dedicated channel is one whose equipment on it is typically used by only one PP routine. An example of this would be the channel to a multiplexor used by 1TD. A non-dedicated channel is one whose equipment on it is typically used by any PP routine. The prime example of a non-dedicated channel is a mass storage channel. Having only one equipment on the channel is not sufficient for that channel to be dedicated; the usage of the equipment determines the dedication of the channel as well.

NOS never assumes that a particular equipment is on a particular channel. The equipment/channel relationship is specified through the EQ CMRDECK entry. All code that is written to use channels follows the conventions established by common decks COMPCHL and COMPCHI. These decks allow code to be written in a general way with the actual channel number inserted into the instructions through a preset operation at execution time.

MTR

MAIN LOOP

1. CHECK PP 1 FOR REQUEST FROM DSD.
2. CHECK EACH PPU OUTPUT REGISTER (OR) FOR REQUEST. PPU_s ARE PROCESSED IN ORDER (2,...10,11,20,21,...,31)
3. ADVANCE CLOCK (AVC).
4. WRITE CHANNEL STATUS TABLE TO CMR (IF NECESSARY).
5. CHECK FOR PP SATURATION (CPS).
6. CHECK CENTRAL PROGRAMS (CCP).
7. CHECK CPU SWITCH.
 - READ CPUMTR CX+2.
 - IF IMMEDIATE SWITCH, SEARCH FOR NEXT JOB (SNJ).
 - IF SINGLE CPU OR (CX+2)=0, CHECK ELAPSED TIME SCANNERS (CET).
8. CHECK CYBER 170 STATUS & CONTROL REG. (CSC).
9. CHECK PROGRAM RECALL BY READING CPUMTR XS. RECALL PROGRAM USING RCPM IF TIME TO RECALL.
10. UPDATE MTR CYCLE TIME STATISTICS IN SDOL.
11. ADVANCE CLOCK (AVC).
12. GO TO STEP 1.

MTR

ADVANCE CLOCK (AVC)

ENTRY AT LEAST EVERY FOUR MILLISECONDS

1. ADVANCES MILLISECOND CLOCK (RTCL) (TIM).
2. READS CPU 0 EXCHANGE REQUEST -
CPUMTR CX - IF REQUEST PRESENT, DOES PCXF.
3. READS CPU 1 EXCHANGE REQUEST -
CPUMTR CX+1 - IF REQUEST PRESENT, DOES PCXF + 10000.
4. IF NEITHER PCXF PERFORMED, THE TIME AND DATE IS ADVANCED (AVT).
5. IF PCXF DONE, AVC LOOPS UNTIL REQUEST HAS BEEN CLEARED BY CPUMTR (GO TO 2).
6. ADVANCES RUNNING TIMES ON EACH CPU.

ARTF + 10000 FOR CPU 1
ARTF or ARMF FOR CPU 0

MTR

ADVANCE TIME (AVT)

1. READS MSCL TO HAVE INTERNAL COPY OF IT. THIS ALLOWS MTR TO REACT TO DELAY CHANGES.
2. READS AND UPDATES TIME AND DATE WORDS.

JDAL
PDTL
TIML
DTEL

UPDATE REAL TIME CLOCK (TIM)

1. UPDATES RTCL EVERY MILLISECOND BY READING CLOCK CHANNEL 14 - IAN 14 - AND UPDATING RTCL WHEN CLOCK OVERFLOWS.

MTR

CHECK PP SATURATION (CPS)

1. READ PPAL FROM CMR.
2. IF BYTE 4 OF PPAL = 0, THEN NO PPs ARE AVAILABLE (DEFINITION OF SATURATION) AND RETURNS TO THE MAIN LOOP.
3. IF A PP REQUEST IS PRESENT, IT IS PROCESSED.
4. IF NO PP REQUESTS ARE PENDING, IS A JOB WAITING FOR A PP (CPUMTR WORD XS) IF SO, RECALL IT (RCLM) OTHERWISE RETURN.

CHECK STATUS AND CONTROL REGISTER (CSC)

1. READ FIRST BYTE ON SCR CHANNEL FOR EACH PPS.
2. IF ERROR PRESENT, CALL 1MB TO FORMAT SCR ERROR TO THE ERROR LOG.
3. THE INHIBIT BIT IS SET IN SCRL TO KEEP ONLY ONE COPY OF 1MB ACTIVE. 1MB WILL CLEAR THIS BIT WHEN COMPLETED.
4. 1MB LOGS FIRST TEN ERRORS PER HOUR. AFTER TEN ERRORS, LOGGING IS DISABLED UNTIL NEW HOUR IS BEGUN.

MTR

CHECK CENTRAL PROGRAM (CCP)

1. CHECK STORAGE MOVE IN PROGRESS. IF SO, JUMP TO MST TO COMPLETE THE STORAGE MOVE.
2. ADVANCE CLOCK (AVC).
3. READ CPU 1 ACPL.
IF IDLE PROGRAM (ACPL BYTE 2 = 0), READ CPU 0 ACPL.
IF IDLE PROGRAM, RETURN.
4. READ STSW FOR THE ACTIVE CP.
5. IF SYSTEM CP, TRY NEXT CPU IF ANY.
6. IF SUBCONTROL POINT, RETRIEVE ITS RA.
7. READ (RA+1) INTO OR
IF NON-ZERO, ASK CPUMTR TO CHECK IT.
8. REPEAT WITH NEXT CPU IF ANY.

MTR

CHECK ELAPSED TIME AND CALL SCANNERS (CET)

1. COMPARE INTERNAL CLOCK AGAINST PP/AUTO RECALL TIME INTERVAL (BYTE 2 OF MSCL: DELAY AR).
IF TIME EXPIRED, CALL PPL (PROCESS PP RECALLS).
2. COMPARE INTERNAL CLOCK AGAINST CPU JOB SWITCH TIME INTERVAL (BYTE 4 OF MSCL: DELAY CS).
IF TIME EXPIRED, CALL SNJ (SELECT NEW JOB).
3. OTHERWISE, CHECK CENTRAL PROGRAMS (CCP).

MTR

PROCESS PP RECALLS (PPL)

CHECKS UP TO 12₁₀ CONTROL POINTS PER PASS (OR ACTUAL IF LESS THAN 12).

1. READ CP'S STSW AND RLPW.
2. IF JOB ADVANCE SET (STSW BIT 53), GO TO NEXT CP AND REPEAT WITH STEP 1.
3. IF NOT IN X OR I RECALL STATUS (STSW BITS 58 OR 57) OR IF IN RECALL STATUS AND NO RA+1 REQUEST, CHECK RLPW.
4. IF NO RLPW, GO TO NEXT CP AND STEP 1.

IF A RLPW REQUEST IS PRESENT, READ JCIW. IF ROLLOUT SET (BYTE 2 OF JCIW), RETURN.

IF ROLLOUT NOT SET, REQUEST A PPU FOR THE RLPW REQUEST. IF NONE AVAILABLE, REQUEUE INTERNALLY.

5. IF IN RECALL AND RA+1 REQUEST PRESENT -
IF I RECALL, INITIATE AUTO RECALL IARF.

MTR

PROCESS PP RECALLS (PPL)

6. IF X RECALL, CHECK (RA+1) FOR RCLP.
IF NOT RCLP, CHECK RLPW (STEP 4).
IF RCLP, CHECK ADDRESS FOR COMPLETION BIT (BIT 0).
IF COMPLETION BIT NOT SET, CHECK RLPW (STEP 4).
IF COMPLETION BIT IS SET, RECALL CPU WITH A RCLM AND RETURN.

MTR

SELECT NEW JOB (SNJ)

ENTER WITH CPU TO SELECT.

1. READ ACPL FOR CURRENT JOB.
2. READ JOB'S JCIW TO GET CPU PRIORITY (BYTE 0 OF JCIW).
3. READ CPUMTR CR.
A BIT IS SET IN CR IF A CONTROL POINT NEEDS THE CPU.
LOOKS AT 12 CPs AT A TIME - FIRST 12, SECOND 12, REMAINDER.
4. IF A WAITING CP IS FOUND, ITS JCIW IS READ.
5. COMPARE WAITING CP'S CPU PRIORITY AGAINST CURRENT JOB'S (BASE) CPU PRIORITY.
WAITING BASE - FORGET IT! (STEP 6)
WAITING = BASE - IF NO SELECTION MADE OR CP IS HIGHER THAN CURRENT GO TO STEP
 7. (THIS ASSURES ROTATION OF EQUAL PRIORITY CPs)
WAITING BASE - GO TO STEP 7.
6. ADVANCE TO NEXT WAITING CP (STEP 4).

MTR

SELECT NEW JOB (SNJ)

7. IF JOB IN SAME CPU (COMPARE JCIW BYTE 4) OR NO CPU SPECIFIED, RESET BASE, IDENTIFYING CANDIDATE JOB, AND ADVANCE TO NEXT WAITING CP (STEP 4).
8. WHEN LOOPING HAS FINISHED, THE NEW BASE IS SET AND THE CPU REQUESTED TO BE GIVEN TO THAT JOB VIA ACSF.

MTR PP FUNCTION REQUESTS

CCHM	CHECK CHANNEL
DCHM	DROP CHANNEL
DEPM	DISK ERROR PROCESSOR
DEQM	DROP EQUIPMENT
DFMM	PROCESS DAYFILE MESSAGE
DRCM	DRIVER RECALL CPU
DSRM	DSD REQUESTS
DSWM	DRIVER SEEK WAIT
EATM	ENTER EVENT TABLE
ECXM	ECS TRANSFER

MTR PP FUNCTION REQUESTS (Continued)

PRLM	PAUSE FOR STORAGE RELOCATION
RCHM	REQUEST CHANNEL
REMM	REQUEST EXIT MODE
REQM	REQUEST EQUIPMENT
RJSM	REQUEST JOB SEQUENCE NUMBER
ROCM	ROLLOUT CONTROL POINT
RPRM	REQUEST PRIORITY
RSTM	REQUEST STORAGE
RSYM	REQUEST SYSTEM
SCPM	SELECT CPU
SEQM	SET EQUIPMENT PARAMETERS
TGPM	PROCESS REQUEST FOR POT CHAIN
TSEM	PROCESS TELEX REQUEST

HUNG PP INDICATES SOMETHING WRONG WAS DETECTED WHEN PROCESSING THESE FUNCTIONS.

MONITOR AUXILIARY PPU ROUTINES

IMA

- REQUEST STORAGE (MEM/RFL)
- MESSAGES (MSG)
 - DAYFILE
 - JOB DAYFILE
 - ERROR LOG
 - ACCOUNT
- SYSTEM CONTROL POINT FACILITY (SSC/SSF)

IMB

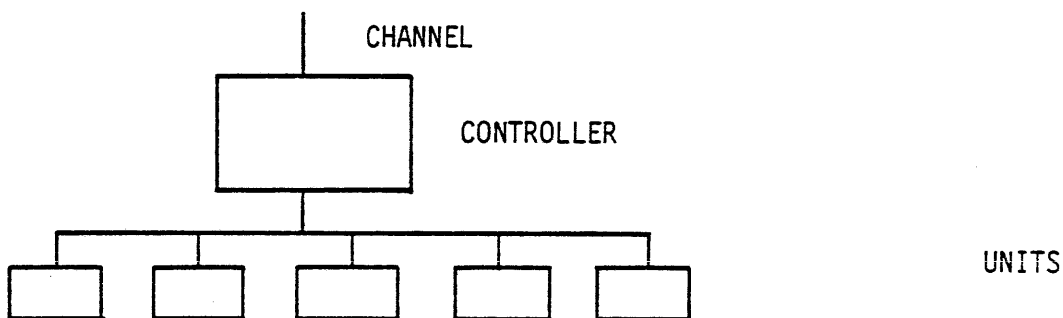
- REPORT STATUS AND CONTROL REGISTER ERRORS

IMC

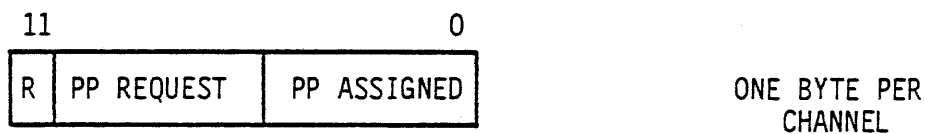
- REPORT ECS PARITY ERRORS

CHANNEL THEORY

- PERFORMANCE
- INTERLOCK
 - PSEUDO CHANNELS
 - CHANNELS TO I/O EQUIPMENT



- CHANNEL RESERVATION TABLE



- PP PROGRAM RESERVES CHANNEL VIA MACROS.

RCHAN
DCHAN

- PP MONITOR FUNCTIONS MANIPULATING CHANNELS

RCHM	CCHM	DEPM
DCHM		DSWM

- COMMON DECKS MANIPULATING CHANNELS

COMPCHI
COMPCHL

- NOS DOES NOT HARDCODE CHANNELS

COMMON DECK TECHNIQUES ALLOW PROGRAMS TO MODIFY THEMSELVES TO USE PROPER CHANNELS DURING PRESET OPERATIONS.

THIS ALLOWS FLEXIBILITY IN CONFIGURING SYSTEM WITHOUT REASSEMBLY OF SOFTWARE.

QUESTION SET LESSON 7

1. Explain what each of the scan times (delay cycles) accomplish?
2. How does MTR take a control point out of periodic recall?
3. What is the system mechanism that keeps two PPs from getting the same channel?

LESSON 8 STORAGE MOVE

LESSON PREVIEW:

This lesson details the process whereby the NOS Operating System obtains a contiguous block of memory to serve as a program's (control point's) Field Length. This process is known as "storage move" and is performed by the system monitors in response to a request for storage via the RSTM monitor function recognized by MTR.

This presentation covers only the central memory aspect of storage move. User ECS is also storage moved using the same logic, but with different monitor functions to interlock and adjust the RAE and FLE.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe how central memory is allocated among control points and CMR (central memory resident).
- Explain what is meant by "unused field length" and be able to compute the unused field length for each control point.
- Explain how the unused field length is used in the storage request (storage move) process.
- Describe how the storage move control word (CMCL) is set up to manage the movement of control point field lengths to obtain the required amount of memory as a contiguous block.
- Explain the logic used for advancing the storage move from one control point to the next.
- Describe the processing done by MTR and CPUMTR when moving a control point's field length.
- Explain why PPs assigned to a control point must pause for a storage move.

SUPPLEMENTAL TEXT: STORAGE MOVE

As you know (or should know by now), NOS allocates central memory into Central Memory Resident and Control Points. Each control point field length contains consecutive memory locations beginning with the reference address (RA) continuing through the field length (FL). Control point field length is allocated in central memory in ascending control point order; that is, control point 1's FL is a contiguous block before control point 2's FL, and so forth. NOS stores reference addresses and field lengths in multiples of 100B words. This allows RA and FL values to be contained in a 12-bit byte, or more accurately, in one PP word.

Memory Request

Memory for a control point (field length) is requested for the job at the control point by a PP. The CPU program may issue RA+1 requests MEM and RFL to specify a field length, but these requests are trapped by CPUMTR and the request for memory is made by CPUMTR's PP auxiliary 1MA. Monitor request RSTM (Request Storage) is issued by a PP to obtain storage for the control point to which the PP is assigned. RSTM is processed by MTR. This mechanism provides appropriate interlocks to prevent two or more control points from deadlocking themselves attempting to obtain memory.

If not enough memory is available to satisfy a RSTM request, MTR returns a "storage not available" status to the requesting PP. The PP may then take appropriate action to retry the request or call the scheduler to analyze the situation and possibly rollout lower priority jobs so that the desired field length is available.

If enough free memory is available to satisfy the request, it is usually necessary to collect the unused memory into a contiguous block at the requesting control point's relative position of control point memories. This is done by moving other control point memories within central memory, so that when the requesting control point is given the memory requested, the control point's memory will be a contiguous block and in ascending control point order. This technique is called STORAGE MOVE.

Determining the Move

MTR builds a table of the unused field length for each control point. Each entry in the Table of Unused Field Length (TUFL) is built using the formula:

$$\text{TUFL}(i) = \text{RA}(i+1) - \frac{1}{4}\text{RA}(i) + \text{FL}(i)\frac{1}{2}$$

where i is the control point number.

As MTR builds the TUFL, it also sums the TUFL entries to determine the amount of available memory (AM). This value will be stored in CMR location ACML.

If a control point requests a decrease in FL, the amount of decrease is taken from the current FL, and RSTM completes. If a job at the last control point, however, decreases its memory requirement, its field length will be moved to the end of memory. There will never be unused FL for the last control point.

If a control point requests additional memory and the unused field length for the control point will satisfy the request, the control point is given the memory increase and RSTM completes.

If the control point unused field length does not satisfy the request, and there is not enough available memory (AM) to satisfy the request, RSTM will be completed with a "storage not available" status. If there is memory available to satisfy the request, then storage move(s) will be done to collect the required amount of unused field length at the control point's relative position of control point field lengths. It should be noted at this time that the purpose of any storage movement is to move control point field lengths so that the unused field length of the requesting control point will satisfy the control point's memory request.

There are three cases of storage movement: 1.) the previous control point; 2.) control points above the requestor; and 3.) all control points. In the following discussion CP_i is the requesting control point and MI is the memory increase requested. A control word is set up by MTR to control the movement. This word resides in direct cells MM through MM+4 and is written into CMR at location CMCL. This word has the format:

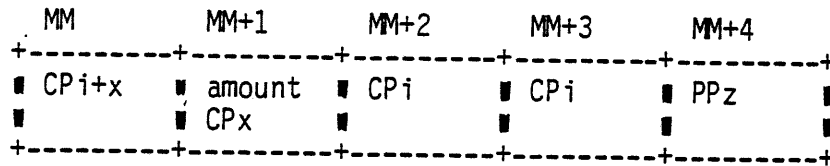
MM	MM+1	MM+2	MM+3	MM+4
moving CP	move amount	lower CP	request CP	request PP

The first case to consider is the previous control point: CP_{i-1}. Is MI = TUFL(CP_{i-1}) + TUFL(CP_i)? If not, go on to the next case. If so, the requesting control point CP_i's field length is moved downward to get the necessary memory in a continuous block. The CMCL control for this move would be:

MM	MM+1	MM+2	MM+3	MM+4
CP _i	TUFL(CP _{i-1})	CP _{i-1}	CP _i	PPz

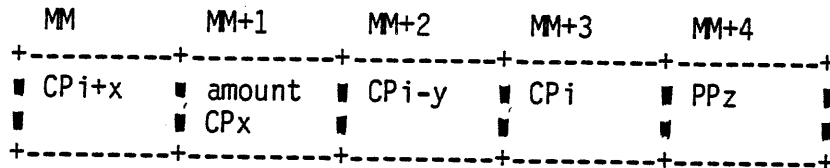
The second case to consider is the control points above the requestor: CP_{i+1}, CP_{i+2}, ..., CP_n. The TUFL of each control point is added to the TUFL(CP_i) until the last TUFL is reached or the request is satisfied. If the memory increase is not satisfied before reaching the last control point, then the next (and final) case is considered. If the request can be satisfied, the control point field lengths

above the requestor that are necessary to be moved are moved upward to get the memory in the contiguous block. The CMCL control for this move would be:



The amount (MM+1) will vary for each control point being moved.

The last case is to consider all control points. After determining the amount of memory available by moving control points above the requestor, MTR begins with the first control point below the requestor working down to the first control point, adding the control point's TUFL until the request can be satisfied. This case must be successful since AM = MI. If this case does not satisfy the request, MTR will hang to preserve the error for subsequent analysis. The CMCL control for this move will be:



The amount (MM+1) will vary for each control point being moved.

Advancing the Move

As each control point field length is moved, MM is adjusted to reflect the next control point to be moved. MM is decremented by 200B when doing an upper move until the the requesting CP (MM+3) is reached. If the requesting CP (MM+3) and the lower CP (MM+2) are not equal, then MM is set to the lower CP. MM will then be advanced by 200B and control points moved until the requesting CP FL has been moved. The amount of the move (MM+1) is positive for upper moves or negative for downward moves and is the amount the moving control point (MM) must be moved. The reason the upper move is done first is because it is faster to move upward using the CMU (Compare Move Unit) than downward.

Move Storage Subroutine (MST)

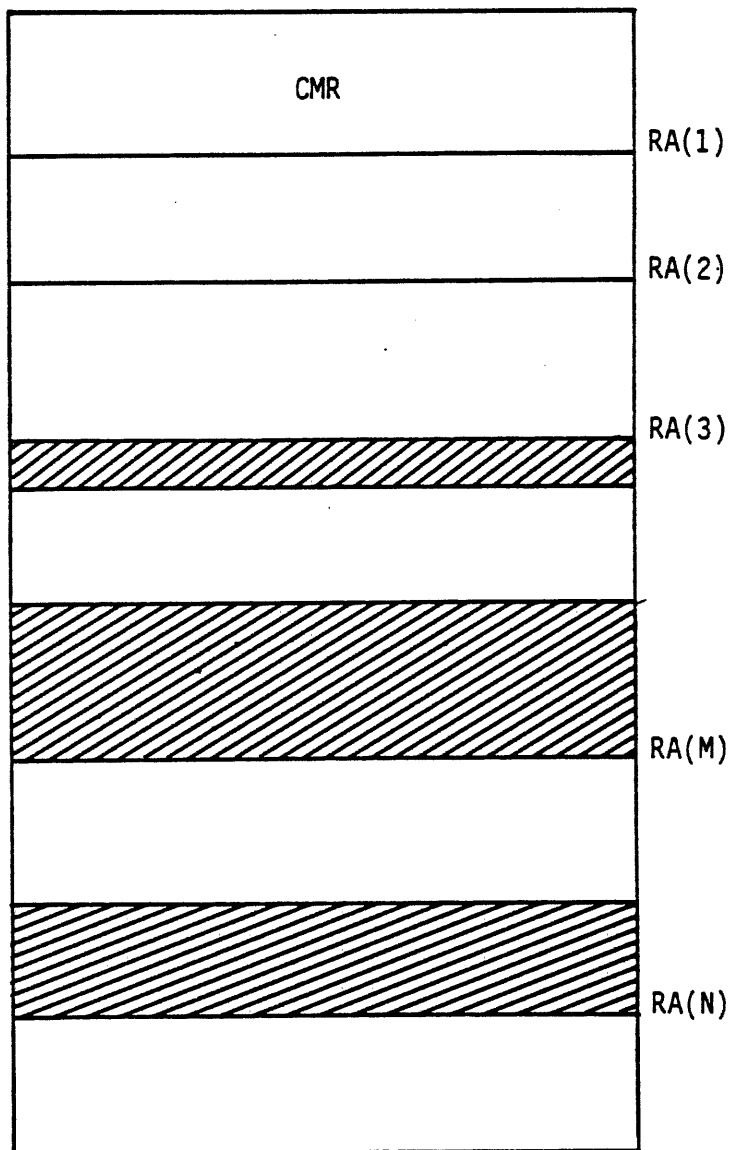
The logic for doing storage moves is found in MTR subroutine MST. The flow is as follows.

1. Issue ARTF+10000 function to CPUMTR; this interlocks the system for storage move.
2. Determine the move, setting up direct cells MM - MM+4.

3. If the moving control point (from MM) FL = 0, then
 - modify RA via MRAF
 - advance the move
 - quit when all CPs have been moved
4. If FL non-zero, then
 - issue DCPM on the CP (can not move active CP)
 - save CPU status (byte 0 of STSW)
 - issue MSTF to CPUMTR
 - modify PP scan loop to bypass the requesting PP
 - exit MST
 - CPUMTR sets its location SM from CMCL
 - CPUMTR moves the storage using
 - ECS
 - CMU
 - register-to-register
5. The completion of the storage move by CPUMTR is detected by MTR subroutine CCP (Check Control Point). If the move has completed, control returns to subroutine MST. Otherwise, MTR continues doing other business.
6. After the control point has been moved:
 - clear storage move control
 - modify RA via MRAF
 - reset CPU status, restarting CPU if necessary
 - advance move
 - quit when all CPs have been moved

In order to be moved, a control point with PPs must have those PPs in a pause condition, that is, PPs have issued a PRLM (Pause), DSWM (Driver Seek Wait), DFMM (Dayfile Message), RCHM (Request Channel), or RSTM (Request Storage) MTR function.

STORAGE MOVE



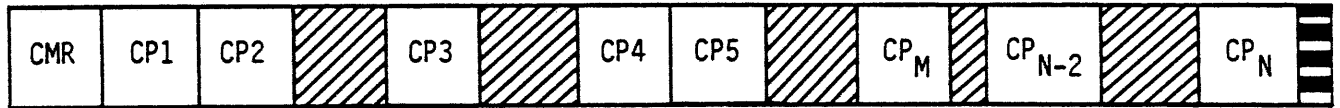
CENTRAL MEMORY

//// = UNUSED

LAST CP ALWAYS
AT END OF MEMORY

RSTM = REQUEST STORAGE

STORAGE MOVE



$$TUFL (I) = RA (I+1) - [RA (I) + FL (I)]$$

$$AM = \sum_{J=1}^N TUFL (J) \quad \text{AVAILABLE MEMORY (ACML)}$$

MOVE CONTROL

MM	MM+1	MM+2	MM+3	MM+4
MOVING CP	AMOUNT	LOWER CP	REQUEST CP	REQUEST PPU

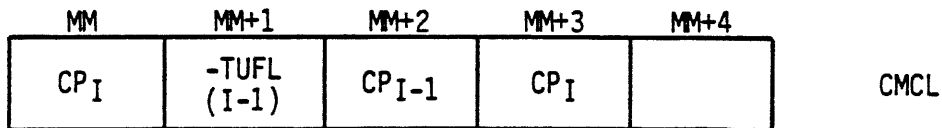
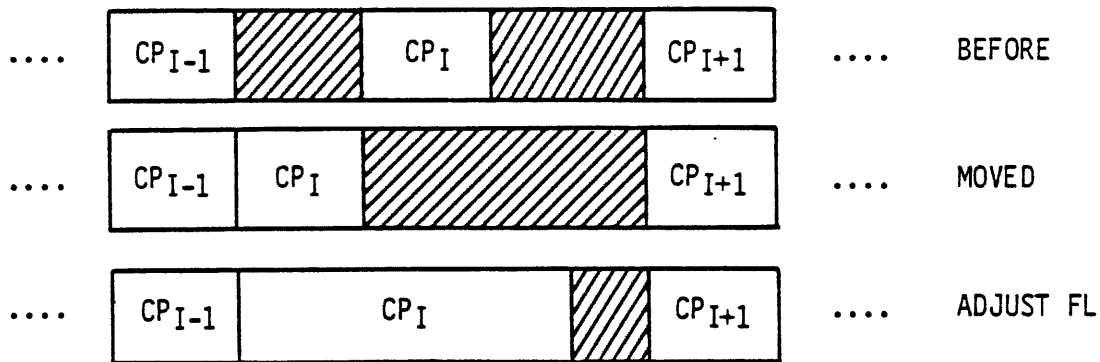
STORAGE MOVE

AM = AVAILABLE MEMORY

CP_I = REQUESTING CP

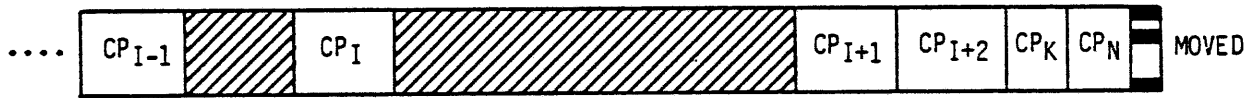
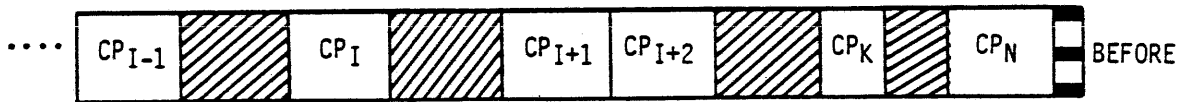
M_I = AMOUNT OF INCREASE

1. CP_I DECREASES - ADJUST FL
- EXCEPT IF CP_N, THEN MUST MOVE CP_N
TO END OF MEMORY
2. CP_I INCREASES - TUFL (I) ≥ MI, ADJUST FL
3. AM ≥ MI, IF NOT, "STORAGE NOT AVAILABLE"
4. MI ≤ TUFL (I) + FL (I-1)



STORAGE MOVE

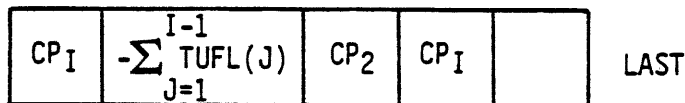
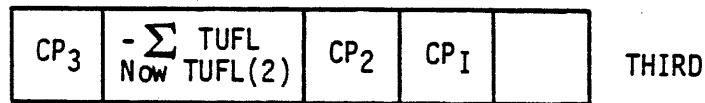
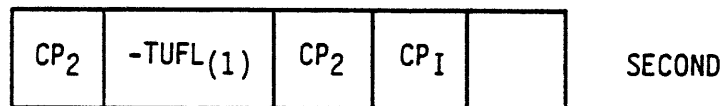
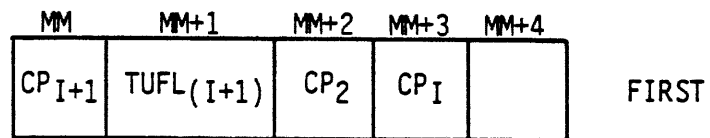
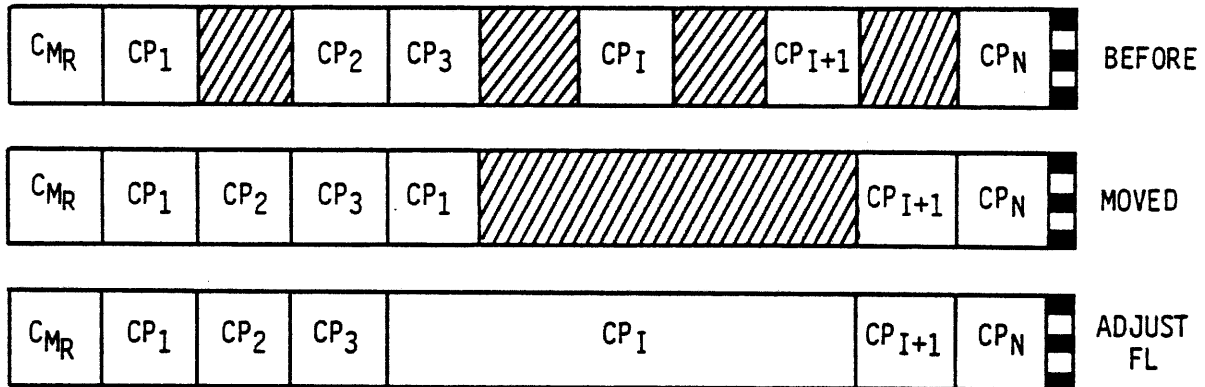
5. $AM = \sum_{J=1}^N TUFL(J)$ CONTROL POINTS ABOVE REQUESTOR



MM	MM+1	MM+2	MM+3	MM+4
CP _K ..	TUFL(X)	CP _I	CP _I	

STORAGE MOVE

6.
$$MI = \leq \sum_{J=1}^N \text{TUFL}(J) + \sum_{K=I-1}^I \text{TUFL}(K)$$
 ALL CONTROL POINTS



STORAGE MOVE

1. INTERLOCK SYSTEM WITH ARTF & 10000
2. IF MOVING CP HAS FL=0
 - MODIFY RA VIA MRAF (MREF IF ECS)
 - ADVANCE MOVE
3. IF MOVING CP HAS FL≠0
 - DCPM (CAN'T MOVE ACTIVE CP)
 - SAVE CPU STATUS
 - ASK CPUMTR TO MOVE VIA MSTF (MECF IF ECS)
 - MODIFY PPU SCAN TO SKIP THIS PPU (REQUESTING)
 - EXIT TO WAIT FOR MOVE
4. CPUMTR MOVES USING FASTEST MEDIUM
 - ECS
 - CMU
 - REGISTER TO REGISTER
5. MTR SUBROUTINE CCP (CHECK CONTROL POINT) FINDS MOVE COMPLETE
 - CLEAR MOVE CONTROL
 - MODIFY RA VIA MRAF (MREF IF ECS)
 - RESET CPU STATUS
 - RESTART CPU IF NECESSARY
 - ADVANCE MOVE
6. AFTER MOVING IS DONE,
 - MODIFY REQUESTING CP FL VIA MFLF (MFEF IF ECS)
 - COMPLETE RSTM
7. CP WITH ASSIGNED PPU_s MUST HAVE PPU_s IN PRLM (PAUSE), DSWM (DRIVER SEEK WAIT), OR DFMM (DAYFILE MESSAGE) IN ORDER TO BE MOVED

QUESTION SET LESSON 8

With the control point usage described below, answer the following questions on storage move:

1. Build a TUFL (Table of Unused Field Length).
2. How much memory is available? Where is this value stored?
3. What will CMCL be (MM - MM+4) if control point 7 wants its field length to be 35500 words? Assume the RSTM request is made by PP 5.
4. What will be the RA and FL values for each control point after the move in c. takes place?
5. Machine size is 200000. Where and in what form is this value stored?
6. What happens if the last (not system) control point makes a RSTM request?
7. Why are the last 100 words of a 262K CM configuration not used by NOS?

<u>CP</u>	<u>RA/100</u>	<u>FL/100</u>	<u>TUFL</u>	<u>RA/100</u>	<u>FL/100</u>
1	300	20	-----	-----	-----
2	320	320	-----	-----	-----
3	640	0	-----	-----	-----
4	650	0	-----	-----	-----
5	700	17	-----	-----	-----
6	1000	0	-----	-----	-----
7	1010	50	-----	-----	-----
10	1130	0	-----	-----	-----
11	1200	100	-----	-----	-----
12	1300	10	-----	-----	-----

<u>CP</u>	<u>RA/100</u>	<u>FL/100</u>	<u>TUFL</u>	<u>RA/100</u>	<u>FL/100</u>
13	1310	50	-----	-----	-----
14	1400	0	-----	-----	-----
15	1410	5	-----	-----	-----
16	1600	200	-----	-----	-----

LESSON 9
PP RESIDENT

LESSON PREVIEW:

This lesson describes the Peripheral Processor Resident (PPR) which resides in each Pool PP. PPR provides the communication link between the Pool PP and the system monitors (CPUMTR and MTR) and jobs at control points. The idle loop in PPR will always be running in the Pool PP if no other PP program is executing in that PP.

This lesson also introduces the student to the concept of zero level overlays (location free routines). These PP routines are used as subroutines by other PP programs.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe the operations performed in the main loop of PP Resident; namely, checking the PP's input register (IR) for a PP routine to be loaded into the PP and executed. The student has already seen the actual PP assignment in the lesson on CPUMTR. This discussion of this topic should be directed to what the PP does when it is assigned.
- Discuss the individual subroutines that comprise PP Resident:
 - Peripheral Library Loader
 - Monitor Function Requests
 - Pause for Storage Relocation
 - Request and Drop Channel
 - Issue Dayfile Message
 - Execute Routine
- Discuss programming conventions for interfacing a PP routine to PPR. This discussion should cover the following items:
 - Usage of Direct Cells and their symbols
 - Usage of EXECUTE, MONITOR, PAUSE macros
 - Memory allocation of Pool PPs
 - PP overlaying techniques
- Describe the role 1DD (Dump Dayfile Buffer) plays in the system.
- Describe the role 1RP (Restore PPR) plays in the system.
- Discuss the relocation techniques used by location free routines (zero level overlays).

REFERENCES:

NOS IMS - Chapter 4 and 29

ASSIGNMENT:

Read the text on "System Interface Techniques" that is found in this Handout. Obtain a listing of location free routine OVJ and common decks COMPRLI and COMPREL.

SUPPLEMENT TEXT: SYSTEM INTERFACE TECHNIQUES

The following techniques or rules apply when writing central processor and peripheral processor routines for system interface.

PP routines should be efficient and their use held to a minimum.

PP programs that interface with CPU programs should have some form of validation to ensure proper calling procedures or parameters. An example of this is CIO which checks all buffer parameters before performing any of the tasks requested. Great care should be taken to ensure that errors in arguments set up by the CPU program do not cause the PP routine to destroy an area other than the local field length of the calling program.

PP routines waiting for some system resource to become available always pause for storage relocation to allow other system processing to proceed.

The use of other PPs to assist in performing the assigned task is a practice that should be used only when absolutely necessary and with great caution. The fact that other PPs may not be available must be considered. The situation in which several PPs are waiting for pool processors should be prevented. The only sure way to do this is not to request helper PPs.

PP overlays can be used simply and without difficulty. The advantage of overlays is that a minimal amount of coding is loaded (from disk or CMR) every time a program is executed. Areas of programs that are used infrequently can be made overlays (for example, error processors). Certain system overlays are available for use by any program and are designed to be location-free. For use of the overlays, refer to the COMPASS SEGMENT or IDENT pseudo-ops.

PP memory direct cells 70 through 73 and 75 through 77 are set when PPR is loaded (at deadstart). Care should be taken not to destroy these cells, as these locations are not initialized after each PP program load. Direct cell 74 (CP) is set by PPR when a program is loaded through an input register request.

PP routines preparing for input/output to allocatable devices (mass storage) should request the mass storage space needed before reserving the channel. Also, when input/output is complete, the channel should be dropped before indicating which area of mass storage was not used.

PP routines doing input/output to a device should perform as much housekeeping as possible before the operation is initiated. Unnecessary reservation of channels prevents other programs from using that channel for input/output.

Buffers used by PP and CPU programs should be defined by EQU statements at the end of the program text and not made part of the text by using BSS statements. This eliminates the loading of the buffer area.

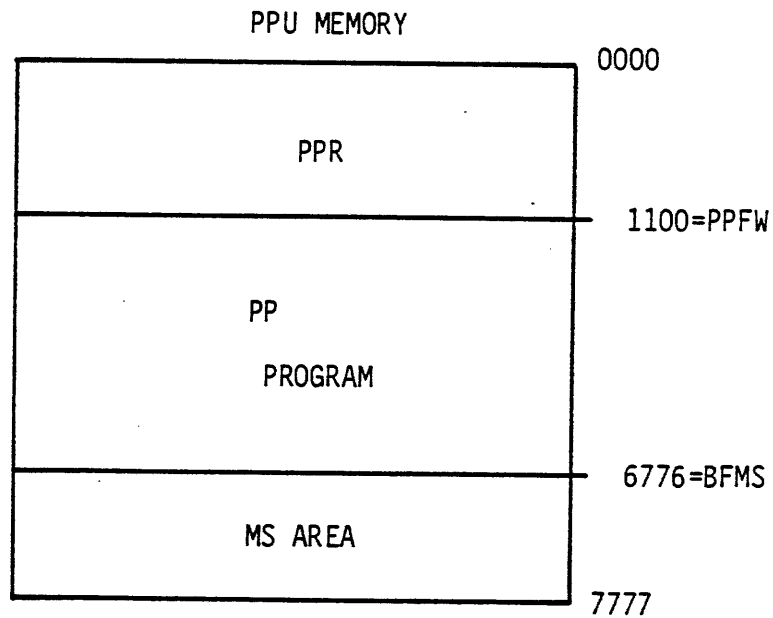
PP programs or overlays are loaded from disk. The last sector of a program or overlay must be loaded at an address below that which causes wrap-around.

System programmers should follow the guidance offered by any notes and cautions provided for PP and CPU macros and monitor functions. An example of this would be not pausing with a non-dedicated channel reserved.

PERIPHERAL PROCESSOR RESIDENT

PPR

- PROVIDES COMMUNICATION LINK BETWEEN PP'S AND CONTROL POINTS.
- PP IDLE PROGRAM
- LOADER OF PP PROGRAMS
- SOURCE OF COMMONLY USED SUBROUTINES
- PROVIDES CONSISTENCY OF PPU ACTIVITIES
- LOADED DIRECTLY INTO PPU MEMORY AT DEADSTART AND IS NOT CHANGED.
- MTR, DSD, AND SOME OTHERS DO NOT CONTAIN A COPY OF PPR.



PPR

INPUT REGISTER	IR	IA = 75	DIRECT CELLS HAVING ADDRESS
OUTPUT REGISTER	OR	OA = 76	
MESSAGE BUFFER (6 WORDS)	MA	MA = 77	DIRECT CELLS FOR IR
		IR = 50	

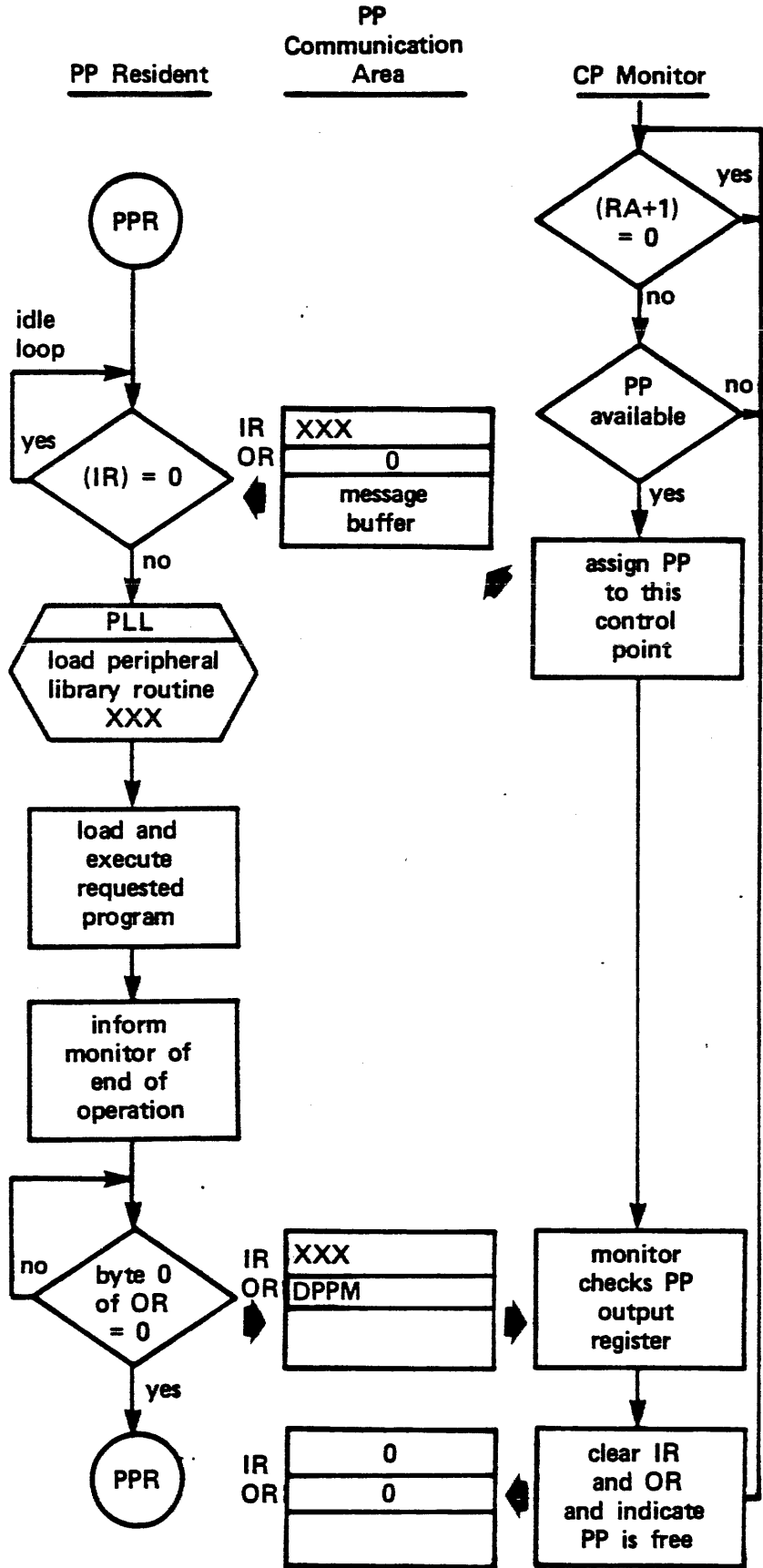
PPR IDLE LOOP CHECKS THE INPUT REGISTER (IR) FOR A REQUEST OF A PP PROGRAM TO BE LOADED.

CPUMTR WILL ENTER THE INPUT REGISTER WITH THE ROUTINE NAME TO BE LOADED INTO THIS PPU. THE EXISTING PP ROUTINE MAY REWRITE THE INPUT REGISTER AND JUMP TO THE IDLE LOOP TO RE-LOAD THE PPU WITH A DIFFERENT ROUTINE.

THE DPPM (DROP PPU) MONITOR FUNCTION WILL CLEAR THE INPUT REGISTER.

THE OUTPUT REGISTER IS USED TO MAKE CALLS TO CPUMTR AND MTR.

THE MESSAGE BUFFER USUALLY CONTAINS PARAMETERS FOR THE FUNCTIONS REQUESTED THROUGH THE OUTPUT REGISTER.



PP DIRECT CELL SYMBOLS

<u>LOCATION</u>	<u>SYMBOL</u>	<u>USAGE</u>
0	T0	TEMPORARIES
1	T1	
2	T2	
3	T3	
4	T4	
5	T5	
6	T6	
7	T7	
10-14	CM	CM WORD BUFFER
15	LA	PPU ROUTINE LOAD ADDRESS
16	T8	TEMPORARY
17	T9	TEMPORARY
50-54	IR	INPUT REGISTER
55	RA	REFERENCE ADDRESS
56	FL	FIELD LENGTH
70	ON	CONSTANT 1
71	HN	CONSTANT 100
72	TH	CONSTANT 1000
73	TR	CONSTANT 3
74	CP	CONTROL POINT ADDRESS
75	IA	INPUT REGISTER ADDRESS
76	OA	OUTPUT REGISTER ADDRESS
77	MA	MESSAGE BUFFER ADDRESS
100	DRSW	DRIVER SCRATCH
101	WDSE	WRITE ERROR PROCESSING ADDRESS
102	ERXA	RDS/WDS EXIT ADDRESS
103	RDCT	READ COUNT
104	STSA	DEVICE STATUS
105	UERR	ERROR PROCESSING
106	SLM	SECTOR LIMIT
107	MSD	MASS STORAGE DRIVER DESIGNATOR
110	CHRV	CHANNEL RESERVATION INDICATOR

PPR
SUBROUTINES

1. PPR IDLE LOOP

PPR READS IR FROM PP COMMUNICATION AREA EVERY 128 MICROSECONDS.

2. PLL PERIPHERAL LIBRARY LOADER

WHEN IR=0, PLL REQUESTS CPUMTR TO SEARCH THE PLD (PERIPHERAL LIBRARY DIRECTORY) FOR THE REQUESTED PP PROGRAM. THIS IS DONE VIA SPLM MONITOR FUNCTION.
IF LIBRARY ALREADY SEARCHED, UPPER 6 BITS OF IR=0
IF FOUND, THE ROUTINE IS LOADED INTO THE PP.
IF NOT FOUND, ROUTINE SFP IS LOADED.
IF THE ROUTINE IS NOT PART OF SFP, THE DIAGNOSTICS

 MONITOR CALL ERROR (IF RA+1 CALL)
OR XXX NOT IN PP LIB (IF DIRECT PP CALL)
ARE ISSUED.

3. LEP LOAD ERROR PROCESSOR

LOADS MASS STORAGE ERROR PROCESSOR ROUTINES (FROM CM) - PART OF THIS PROCESS RESIDES IN CMR.

PPR
SUBROUTINES (Continued)

4. FTN MONITOR FUNCTION REQUESTS

THE MONITOR FUNCTION (CPUMTR/MTR) IS STORED IN THE OUTPUT REGISTER (OR). FTN EXECUTES A MXN EXCHANGE FOR CPUMTR.

FTN WAITS FOR BYTE 0 OF THE OUTPUT REGISTER TO CLEAR (=0) BEFORE RETURNING CONTROL TO THE PP ROUTINE.

FTN ALSO PERFORMS PAUSE FOR STORAGE RELOCATION PROCESSING. WHEN A CP TO WHICH A PP IS ASSIGNED NEEDS TO BE STORAGE MOVED, THE PP MUST PAUSE TO ALLOW THE STORAGE MOVE TO TAKE PLACE. DIRECT CELLS RA AND FL WILL BE RESET AFTER THE PRLM MONITOR FUNCTION ISSUED BY PRL COMPLETES.

5. RCH REQUEST CHANNEL
DCH DROP CHANNEL

MONITOR FUNCTIONS RCHM AND DCHM ARE ISSUED TO REQUEST/DROP CHANNELS OR PSEUDO CHANNELS.

THESE ROUTINES WILL BE REMOVED IN A FUTURE RELEASE. THE USAGE OF RCHAN AND DCHAN MACROS IS PREFERRED.

PPR
SUBROUTINES (Continued)

6. DFM DAYFILE MESSAGE

USED BY PP TO ISSUE DAYFILE MESSAGE. THE MESSAGE IS PASSED IN MESSAGE BUFFER FOR DFMM MONITOR FUNCTION.

THIS SUBROUTINE SHOULD NOT BE CALLED WITH CHANNELS RESERVED. (NON-DEDICATED)

7. EXR EXECUTE ROUTINE

EXR LOADS AN OVERLAY INTO THIS PP. EXR CALLS PLL TO IDENTIFY AND LOAD THE ROUTINE.

8. SMS SET MASS STORAGE

SMS LOADS MASS STORAGE DRIVER INTO THIS PP. PLL IS CALLED TO FIND AND LOAD THE DRIVER.

9. RDS READ DISK SECTOR
WDS WRITE DISK SECTOR
EMS END MASS STORAGE OPERATION

THESE "SUBROUTINES" ARE DEFINED TO BE AT THE SAME LOCATION FOR ALL MASS STORAGE DRIVERS. THIS ALLOWS PP CODE TO BE MASS STORAGE INDEPENDENT WITH RESPECT TO I/O OPERATIONS.

PPR COMPMAC MACROS

- EXECUTE PROGRAM/OVERLAY CALL
EXECUTE NAME, ADDRESS
 NAME = NAME OF PPU ROUTINE
 ADDRESS = LOAD ADDRESS FOR ZERO LEVEL OVERLAY
 = * PUT NAME IN A BUT DO NOT EXECUTE
 = = DO NOT GENERATE CODE

DOES A RETURN JUMP TO EXR.

- MONITOR REQUEST MONITOR FUNCTION
MONITOR FUNC
 FUNC = FUNCTION TO PERFORM

DOES A RETURN JUMP TO FTN

- PAUSE PAUSE FOR RELOCATION AND
 RESET (RA) AND (FL)

DOES A MONITOR 0 WHICH IS SPECIAL CASED IN FTN

- DELAY DELAY FOR SYSTEM DELAY TIME.
 (APPROXIMATELY 130 MICROSECONDS)

PP ROUTINE RESIDENCE

- ALL PP ROUTINES RESIDE IN CENTRAL MEMORY AS PART OF THE RPL (RESIDENT PERIPHERAL LIBRARY) OR ON MASS STORAGE (AS PART OF PPULIB).

THE PERIPHERAL LIBRARY DIRECTORY (PLD) CONTAINS THE RESIDENCE ADDRESS FOR THE PP ROUTINE.

MONITOR FUNCTION SPLM (SEARCH PERIPHERAL LIBRARY) SEARCHES THE PLD AND RETURNS THE RESIDENCE ADDRESS FROM WHICH TO LOAD THE ROUTINE. THIS ADDRESS MAY BE FROM THE RPL, AN ASR (ALTERNATE SYSTEM RESIDENCE), OR MASS STORAGE.

- SYSTEM PERFORMANCE IS AFFECTED BY THE RESIDENCE OF FREQUENTLY USED ROUTINES.

THE PPU PROGRAMS - IDD, SFP, ODF, TSE, ALL MASS STORAGE DRIVERS AND ERROR PROCESSORS 1MB (ON CYBER 170s) MUST RESIDE IN THE RPL.

CONSULT THE SRB OR IHB FOR RECOMMENDED RPL RESIDENT ROUTINES.

PPR

1DD

1DD IS CALLED BY DFM TO DUMP A FULL DAYFILE BUFFER. A PORTION OF THE CURRENT PP ROUTINE IS WRITTEN TO THE DAYFILE DUMP BUFFER IN CMR WHILE 1DD IS LOADED INTO THAT AREA OF THE PPU FOR ITS EXECUTION.

1DD RE-LOADS THE CURRENT PROGRAM FROM THE DUMP BUFFER UPON COMPLETION.

IF THE DUMPING IS PROHIBITED BY AN UNRECOVERED WRITE ERROR, THE DIAGNOSTIC
"1DD ABT"

WILL BE DISPLAYED. THIS IS A WARNING - THE SYSTEM CONTINUES EXECUTION WITH FAULTY LINKAGE IN THE DAYFILE BEING DUMPED. OPERATOR SHOULD DFTERM THE AFFECTED DAYFILE.

1RP

1RP IS CALLED TO RESTORE PPR INTO A PP WHICH HAD DESTROYED IT OR USED ITS AREA.

1TD REQUESTS 1RP VIA RPPM. 1RP IS ASSIGNED A PPU (SAY PP4). 1RP WILL THEN PASS A COPY OF ITS PPR TO 1TD'S PP IN 6 WORD BLOCKS THROUGH THE MESSAGE BUFFER. DIRECT CELLS ARE MODIFIED TO REFLECT "HARD" VALUES AND THE REQUESTING PP'S COMMUNICATION AREA.

LOCATION FREE ROUTINES
(ZERO LEVEL OVERLAYS)

- BEGIN WITH ZERO
- RELOCATED FROM LOAD ADDRESS (LA)
 - COMPREL
 - COMPRLI
- LOAD VIA EXECUTE MACRO
- LENGTH CHECK VIA OVERFLOW MACRO AND COMSZOL

OAU	UPDATE PROFILA
OAV	VERIFY USER NUMBER
OBF	BEGIN FILE
ODF	DROP FILE
OBP	FORMAT BANNER PAGE
OFA	RELEASE FAST ATTACH FILE
OMF	INITIALIZE MMF LINK DEVICE
ORF	UPDATE RESOURCE FILES
ORP	RELEASE DIRECT PERMANENT FILE
OVJ	VERIFY JOB/USER STATEMENT
OCI	FIRMWARE IDENTIFIER
OTI	TRACK FLAW PROCESSOR
OPI	PACK SERIAL NUMBER PROCESSOR

QUESTION SET LESSON 9

1. Where must a PP routine be coded to run, if it is to interface with PPR (PP Resident)?
2. Why is it desirable to have a Pool PP pause for storage relocation?
3. What is a Pool PP doing when it is waiting for monitor to assign it to a job?
4. How does a Pool PP routine make monitor requests? How does it know if the request has been honored? How does the PP know when the request has been completed?
5. How does a Pool PP determine which control point it is assigned to?
6. How should a PP program write a message to the control point dayfile?
7. After pausing for storage relocation, where will a PP program find the updated RA and FL for the control point to which it is assigned? What programming considerations must the PP routine consider?
8. Since some PP routines will not fit in a PP, individual functions may have to be written as overlays. How can a PP program get one of these overlays loaded?
9. Why should a programmer be very careful about using locations 6776 - 7777 when dealing with mass storage input/output?
10. What is the difference between "PP HUNG" and "HUNG PP"?
11. Design, flowchart, and code a PP routine to list in the control point dayfile all rollout files names found in the FNT.

LESSON 10
MASS STORAGE CONCEPTS

LESSON PREVIEW:

In this lesson, the student will learn the concepts of mass storage in NOS, its allocation and the drivers to position, read and write it. The use of mass storage in this lesson is at the driver level and will be called "direct input/output".

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Discuss the mass storage allocation scheme employed in NOS.
- Describe in detail the Track Reservation Table (TRT) and how track chains are reserved.
- Describe the NOS sector format, complete with its header bytes.
- Describe the system conventions employed by the mass storage driver and the key PPR subroutines and entry points used to do.
direct Input/output.
- Discuss 6DI - the Mass storage Driver.
- Discuss the error processing options available to the PP programmer when doing direct input/output.
- Discuss the use of Extended Core Storage (ECS) as both a mass storage device and user accessible field length.

REFERENCES:

NOS IMS - Chapter 7 NOS SMRM, 1-12-15

MASS STORAGE

CRM MANIPULATES A FILE VIA THE FIT - FILE INFORMATION TABLE

THE OPERATING SYSTEM INPUT/OUTPUT ACTIVITY IS CONTROLLED THRU THE

FET - FILE ENVIRONMENT TABLE

AND THRU THE

FNT/FST - FILE NAME TABLE
 - FILE STATUS TABLE

THE PHYSICAL INPUT/OUTPUT ACTIVITY IS CONTROLLED BY THREE TABLES:

EST - EQUIPMENT STATUS TABLE
MST - MASS STORAGE TABLE
TRT - TRACK RESERVATION TABLE

FNT → CP AREA

FET → FST → EST → MST → TRT

RMS DEVICE COMPARISON

	INTERLACE	SECTORS/ TRACK	TRACKS/ DEVICE	WORDS/ DEVICE	MAXIMUM DATA RATE	MULTI-SPINDLE
844-21	DI HALF TRACK	107	1632	11,175,936	46.1K WORDS/SEC.	1-8
7054 7152 7154	DK FULL TRACK	112	1632	11,698,176	92.16K WORDS/SEC.	1--8
844-4X	DJ HALF TRACK	227	1640	23,825,920	46.1K WORDS/SEC.	1-8
7054 7152 7154 7155	DL FULL TRACK	227	1640	23,825,920	92.16K WORDS/SEC.	1-8
885	DM HALF TRACK	640	1682	68,894,720	61.44K WORDS/SEC.	1-3
7155	DQ FULL	640	1682	68,894,720	128.88K WORDS/SEC	1-3
ECS	DE				80K WORDS/SEC (1XPP)	
	DP	16			160K WORDS/SEC (2XPP)	NA

MASS STORAGE TABLE (MST)

	59	51	47	40	35	23	17	11	5	0	
000	†1				TRT length	†2	no. avail. tracks				TDGL
001	†3	user ECS first track			file count	IQFT track	†4				ACGL
002	ECS address of MST/TRT				ECS MST/TRT update cnt				†5		SDGL
003	1st track IAF	label track		permits track	no. catalog tracks		DAT track				ALGL
004	family or pack name						DN			†6	PFGL
005	user number for private pack						†7				PUGL
006	†8			driver name	0		sector limit				MDGL
007											R1GL
010	installation area (global)										ISGL
011											I2GL
012	activity count	unit interlocks		current position	MTR internal		ECS error #				DALL
013	†9										DILL
014	DAYFILE track	ACCOUNT track		ERRLOG track	system table track		†10				DULL
015	†11					user count		†12			STLL
016	†13										DDLL
017	installation area										ISLL

MASS STORAGE LABEL FORMAT
 DEVICE LABEL TRACK FORMAT

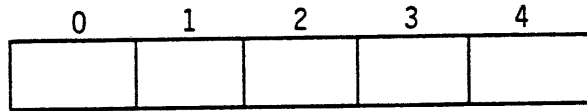
000	label sector
001	track reservation table
.	
.	
012	
013	sector of local information (2-word entries)
014	device information sector
015	intermachine communication area (ECS label track only)
016	MMF environment tables (ECS label track only)
017	CPUMTR storage move area for ECS (ECS label track only)

DEVICE LABEL SECTOR FORMAT

000	reserved		
001	reserved		
002	reserved		
003	label level	equipment type	reserved
004	reserved		
005	reserved		
006	reserved		
007	reserved		
010	reserved		
.	reserved		
.	reserved		
.	NOS MST		
027	reserved		
030	reserved		
.	reserved		
.	reserved		
.	unused		
077	reserved		

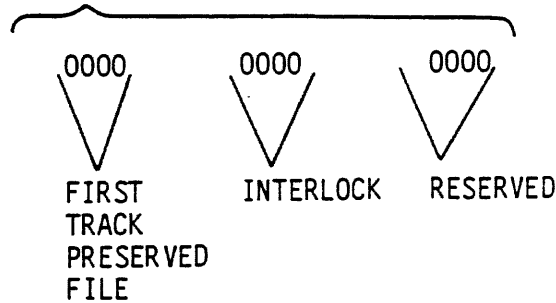
MASS STORAGE

TRT - TRACK RESERVATION TABLE



LINKAGE: 12 BITS

000 000 000 000



↑ BIT 11=1 INDICATES LINKED TRACK
10-0 IS NEXT TRACK

BIT 11=1 INDICATES TERMINAL CONDITION
10-0 EOI SECTOR
10-1 = 3777 = FLAWED TRACK

WORD BYTE
0/00 000 000 0/00

TO DETERMINE TRT WORD AND BYTE FOR A TRACK:

- IGNORE BIT 11
- BYTE = BITS 0.1
- WORD = BITS 10-2

EG: 4123 = $\begin{matrix} & 4 & 1 & 2 & 3 \\ & 000 & 000 & 000 & 000 \end{matrix}$
 $\underbrace{\hspace{10em}}_{24} = \text{WORD}$
 $\underbrace{\hspace{10em}}_{3} = \text{BYTE}$

TRT BASE ADDRESS = MST ADDRESS + MSTL
(208)

MASS STORAGE

	EQ	FIRST TRACK	CURRENT TRACK	CURRENT SECTOR		FST
--	----	-------------	---------------	----------------	--	-----

- EQ POINTS TO EST ENTRY
 BYTE 4 OF EST ENTRY IS MST ADDRESS/10g

	0		1		2		3	
	4	4012	5		6		7	0004
	10	3777	11	4014	12		13	0006
4015	14	4016	15	4017	16	4020	17	0017
0007	20		21		22		23	0010

	EQ	4005	4020	0007	
		FT	CT	CS	

FST

IF DL AT 343g SECTORS PER TRACK AND HAS THE ABOVE TRT

FILE IS _____ SECTORS LONG

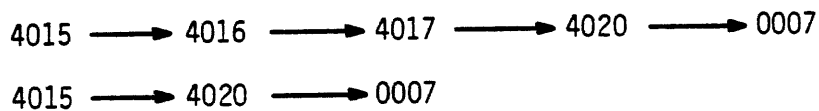
WHERE IS SECTOR 350g

CURRENT POSITION IS _____

MASS STORAGE

TRACK ALLOCATION/RESERVATION

- RTCM - REQUEST TRACK CHAIN FOR A SPECIFIED NUMBER OF SECTORS ON A SPECIFIED EQUIPMENT OR FROM A COLLECTION OF DESIGNATED EQUIPMENTS (MSAL)
GENERATES OR ADDS TO TRACK CHAIN
- DTKM - DROP TRACKS AND SET EOI SECTOR OR DROP ALL TRACKS. OPTIONALLY CAUSES DEVICE CHECKPOINT TO BE REQUESTED
- DLKM - DELINK TRACKS - DROPS LINKAGE WITHIN TRACK CHAIN.



USED TO PURGE LARGE INDIRECT FILES FROM DATA CHAIN

- STBM - SET TRACK BIT
- INTERLOCK SET/CLEAR
 - PRESERVE SET/CLEAR
 - FLAW SET/CLEAR

MASS STORAGE

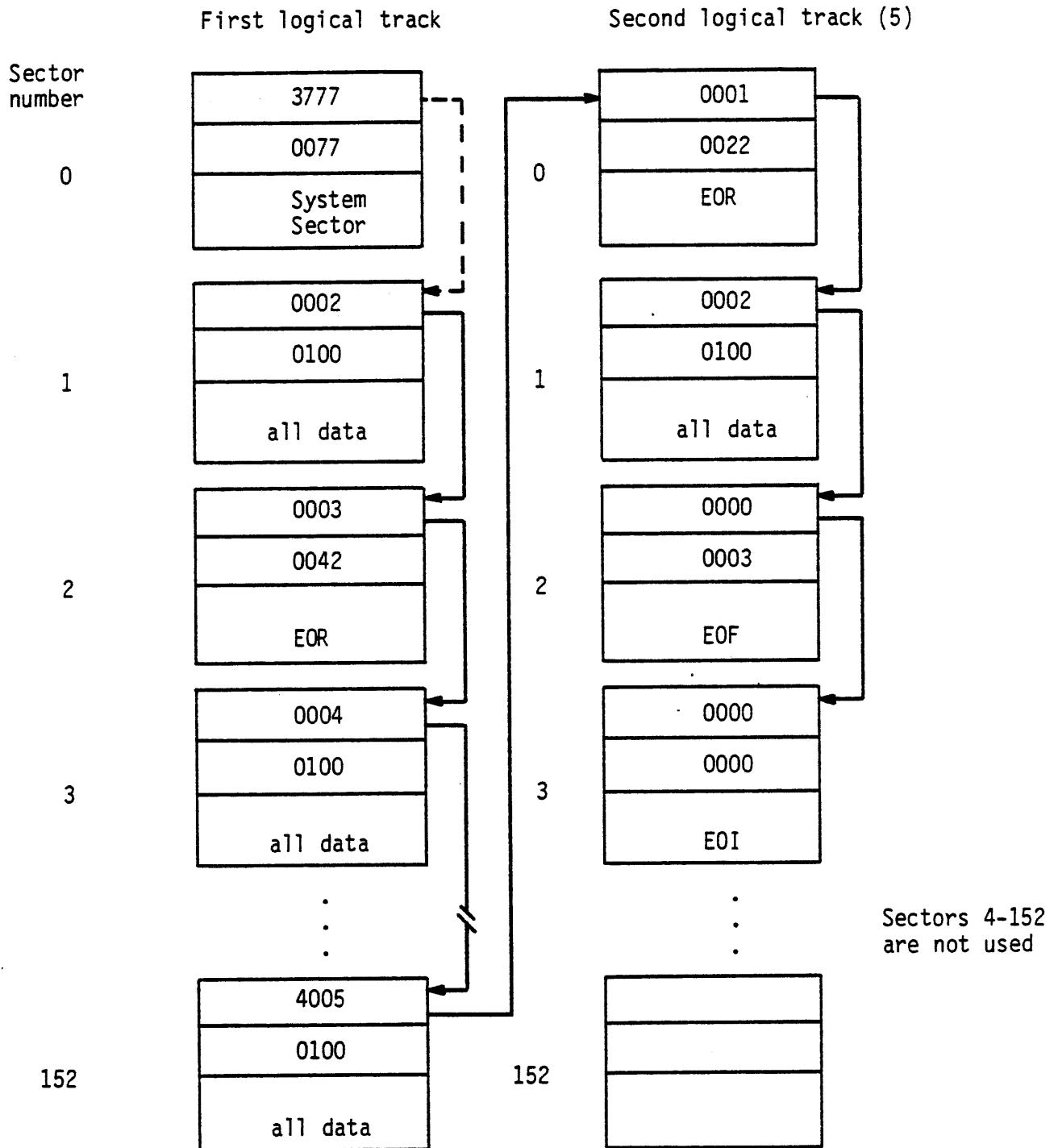
<u>TYPES OF SECTORS</u>	<u>HEADER BYTES</u>	
	<u>LINKAGE CONTROL</u>	<u>NUMBER OF WORDS</u>
SYSTEM SECTOR	3777	0077
FULL DATA SECTOR	NEXT TRACK OR SECTOR	0100
EOR (END OF RECORD)	NEXT TRACK OR SECTOR	$0 \leq WC \leq 0077$
EOF (END OF FILE)	0	NEXT TRACK OR SECTOR
EOI (END OF INFORMATION)	0	0

SYSTEM SECTOR HAS INFORMATION CONCERNING HOW THE FILE IS USED AND THAT INFORMATION AND ITS FORMAT VARIES ACCORDING TO USAGE.

THE END OF INFORMATION (EOI) SECTOR HAS INFORMATION THAT POINTS (LINKS) BACK TO THE SYSTEM SECTOR. THIS INFORMATION IS USED TO VALIDATE THE TRACK LINKAGE FOR THE FILE.

COMMON DECKS

COMSWEI	COMPWSS	COMPRSS
	COMPWEI	



SETMS - SET MASS STORAGE DRIVE PARAMETERS
ENDMS - END MASS STORAGE DRIVER ACCESS

SETMS PERFORMS THE FOLLOWING OPERATIONS

- PASSES READ/WRITE OPERATION TO THE DRIVER
- INSURES CORRECT DRIVER IS LOADED
- PRESETS DRIVER
- INITIALIZES DRIVER RELATED CELLS (DRSW, RDCT, STSA, WDSE)
- SETS WRITE ERROR PROCESSING BUFFER ADDRESS
- SELECTS ERROR PROCESSING OPTIONS
- ELIMINATED POS (POSITION) DRIVER ENTRY POINT

SETMS IS CALLED

- BEFORE ANY INITIAL READ OR WRITE OPERATION
- WHEN SWITCHING BETWEEN READ AND WRITE OPERATIONS
- WHEN SWITCHING LOGICAL TRACKS IF LAST SECTOR WAS NOT THE LAST SECTOR OF A LOGICAL TRACK
- WHEN CHANGING THE ERROR PROCESSING OPTIONS

SETMS CALL FORMAT

SETMS OP,(EP.....EP),WB

WHERE OP = READ READ OPERATION
 READSYS READ SYSTEM DEVICE
 WRITE WRITE OPERATION

 EP = NE NO ERROR PROCESSING
 SM SUPPRESS ERRLOG MESSAGE
 RR IMMEDIATE RETURN ON RESERVE
 NR RETURN ON NOT READY

 WB = ADDRESS ADDRESS OF WRITE ERROR
 PROCESSING BUFFER

ENDMS TERMINATES MASS STORAGE OPERATIONS

- RELEASES CHANNEL
- RELEASES CONTROLLER
- RELEASES DRIVE
- RELEASES OTHER RESOURCES RESERVED FOR I/O
- ELIMINATED CHANNEL RELEASE TABLE FROM CMR

LDD	FSTA	
CRD	FS	
LDD	FS	SET EQUIPMENT
LPN	77	
STD	T5	
LDD	FS+1	SET FIRST TRACK
STD	T6	
RJM	CRA	CONVERT RANDOM ADDRESS
SETMS	READ	

LDC	BUF	READ SECTOR
RJM	RDS	
MJN	ERR	IF ERROR DETECTED
ENDMS		

MASS STORAGE

BY SYSTEM CONVENTION

T4	=	CHANNEL
T5	=	EQUIPMENT (EST ORDINAL)
T6	=	TRACK
T7	=	SECTOR

MASS STORAGE

PPR DEFINITIONS:

DRSW - DRIVER SCRATCH WORD
WDSE - WRITE RECOVERY BUFFER ADDRESS
ERXA - RDS/WDS EXIT ADDRESS
RDCT - RETRY COUNTER
STSA - STATUS
UERP - ERROR PROCESSING OPTIONS
SLM - SECTOR LIMIT
MSD - DRIVER DESIGNATOR
CHRV - CHANNEL RESERVATION STATUS
SMSA - MMF FLAG
EMS - END MASS STORAGE
RDS - READ DISK SECTOR
WDS - WRITE DISK SECTOR

6DI - MASS STORAGE DRIVER

- PROCESSES EQUIPMENTS DI DJ DK DL DM DQ
- AUTOMATIC TRACK FLOWING USING HARDWARE INFORMATION RECORDED IN THE UTILITY SECTOR

881	(DI/DK)	CYLINDER	410
883	(DJ/DK)	CYLINDER	822
885	(DM/DQ)	CYLINDER	841

MANUFACTURING	FACTORY	UTILITY
0	1	2

- PACK SERIAL NUMBERS RECORDED IN ERRLOG FROM MANUFACTURING SECTOR
- CONTROLWARE REVISION NUMBER RECORDED IN ERRLOG
- SEEK OVERLAP (DSWM)
- LOGICAL TO PHYSICAL ADDRESS MAPPING (LDAM)

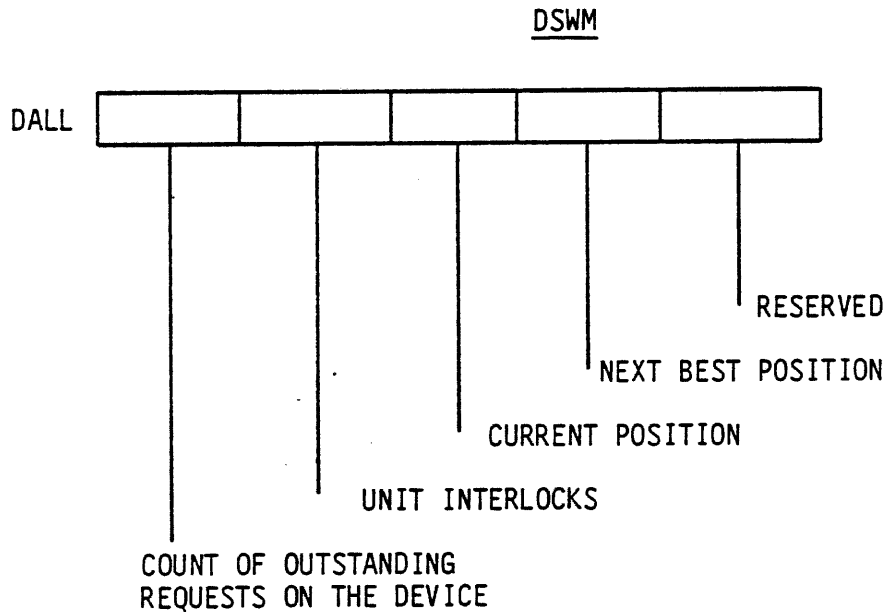
LDAM - LOGICAL TO PHYSICAL ADDRESS CONVERSION

DRIVER USES LDAM MONITOR FUNCTION TO CONVERT LOGICAL TRACK AND SECTOR TO PHYSICAL UNIT, CYLINDER, HEAD, AND SECTOR.

MULTIPLE SPINDLE EQUIPMENTS

- GROUP UNITS TOGETHER
- NUMBER OF SECTORS PER TRACK IS N TIMES THE NUMBER OF SECTORS/TRACK FOR A SINGLE SPINDLE WHERE N IS THE NUMBER OF SPINDLES.
- FOR EXAMPLE, DJ - 3

$$\text{SECTORS/TRACK} = 3 \times 227 = 671_{10} = 1251_8$$



ALL THE RESOURCES NEEDED TO DO AN I/O OPERATION ARE REQUESTED VIA DWSM.
THE ORDER OF RESOURCE ASSIGNMENT IS:

- IF A READSYS REQUEST IS PENDING AND MORE THAN ONE SYSTEM DEVICE IS PRESENT, THE SYSTEM DEVICE IS SELECTED AS FOLLOWS:
 - DEVICE WITH THE REQUIRED UNIT FREE
 - IF MORE THAN ONE DEVICE HAS A UNIT FREE, THE ONE WITH THE LEAST ACTIVITY IS CHOSEN BASED ON THE ACTIVITY COUNT IN MST WORD DALL
 - IF MORE THAN ONE DEVICE IS FOUND AND ACTIVITY COUNTS ARE EQUAL, THE ONE IS CHOSEN WITH THE LEAST DISTANCE TO MOVE THE POSITIONER

DSWM

- SOFTWARE UNIT INTERLOCK IS OBTAINED IN DALL - THIS INTERLOCK INSURES ONLY ONE REQUEST IS PROCESSED FOR A UNIT AT A TIME. IN THE NON-MMF CONFIGURATION, THIS INTERLOCK IS NEEDED BECAUSE THE DRIVER RELEASES THE DRIVE AFTER INITIATING THE SEEK WHEN THE POSITIONER IS BUSY. THE OPERATION MAY BE CONTINUED ON A CHANNEL DIFFERENT FROM THE ONE ON WHICH THE SEEK WAS INITIATED. IN THE MMF ENVIRONMENT, THE HARDWARE DRIVE RESERVE IS MAINTAINED IN ADDITION TO THE DALL INTERLOCK WHILE SEEKING SO THAT REQUESTS FROM ANOTHER MACHINE DO NOT GAIN ACCESS TO THE DRIVE AND RESEEK.
- CHANNEL IS SELECTED AND RESERVED.

MASS STORAGE

ERROR PROCESSING

PROCESSING OPTION SET IN UERP ALLOWS PROGRAM TO GAIN CONTROL OVER UNRECOVERED ERRORS.

<u>SYMBOL</u>	<u>VALUE</u>	<u>DEFINITION</u>
EPAR	23	RETURN ON ALL ERRORS
EPNE	10	DISABLE RETURN ON ALL ERRORS
EPSM	4	SUPPRESS ERRLOG MESSAGE
EPRR	2	IMMEDIATE RETURN ON RESERVES
EPNR	1	RETURN ON NOT-READY

- SET UP UERP USING SETMS

SETMS READ (NE, SM, RR, NR)
READSYS

- PERFORM READ OR WRITE OPERATION

RJM RDS READ SECTOR

- TEST ERROR (A) 0 IF ERROR

MJN PDE IF DISK ERROR

MASS STORAGE

ERROR PROCESSING

AN UNRECOVERED ERROR IS DECLARED WHEN THE OPERATION IS NOT SUCCESSFUL WITHIN A SPECIFIED NUMBER OF RETRIES.

NORMAL ERRORS

<u>SYMBOL</u>	<u>MNEMONIC</u>	<u>RETRY</u>	<u>ERROR TYPE</u>
PARE	PE	12	PARITY ERROR
ADDE	AD	12	ADDRESS ERROR
DSTE	ST	77	STATUS ERROR
FTON	FT	3	FUNCTION TIMEOUT

RESERVE ERRORS

RESE	RS	77	DEVICE RESERVED ERROR
CRSE	CR	77	CONTROLLER RESERVED ERROR

AUTO RETRY ERRORS

NRDE	NR	2	NOT READY ERROR
------	----	---	-----------------

MASS STORAGE

ERROR PROCESSING

DEPM (MTR FUNCTION)

- CHECKS VALIDITY OF DRIVER-SUPPLIED PARAMETERS
- FORMATS ERROR MESSAGE IN MESSAGE BUFFER
- REVERSES CHANNELS IN MTR TABLE (IF NEITHER CHANNEL IS 0)
- SETS UP 7EP PARAMETERS

DRIVER EXECUTES 7EP

- WRITES ERROR MESSAGE TO MSZW
- IF SPECIFIED, RETURNS IMMEDIATELY TO DRIVER
- TERMINATE MASS STORAGE PROCESSING (ENDMS)
- ISSUE DAYFILE AND ERRLOG MESSAGES AS APPROPRIATE
- ABORT JOB IF APPROPRIATE (UNRECOVERED AND NO USER ERROR PROCESSING SELECTED)
- RETURN TO DRIVER FOR RECOVERY ATTEMPT IF POSSIBLE
- DELAY FOR OPERATOR OVERRIDE IF ERROR IS "RETRY AFTER DELAY" TYPE
 - RETURN TO CALLER WITH UNRECOVERED STATUS OR ABORT JOB IF OVERRIDE ENTERED
 - AFTER DELAY, RETURN TO DRIVER TO RETRY OPERATOR IF OVERRIDE NOT ENTERED

DRIVER PERFORMS ERROR RECOVERY IF APPROPRIATE

MASS STORAGE

ERROR PROCESSING

FULL TRACK WRITE ERROR PROCESSING

- ERROR STATUS MAY NOT BE AVAILABLE IMMEDIATELY
- LAST SECTOR WRITE FUNCTION
- PREVIOUS SECTOR ERROR CONDITIONS
- USER PROCESSING OF ERRORS MAY BE SELECTED BY THE USE OF THE SECOND PARAMETER OF THE SETMS MACRO
- A RECOVERY BUFFER MAY BE DEFINED FOR USE IN PREVIOUS SECTOR RECOVERY BY THE USE OF THE THIRD PARAMETER ON THE SETMS MACRO

	USER PROCESSING NOT SELECTED ON SETMS	USER PROCESSING SELECTED ON SETMS
RECOVERY BUFFER SPECIFIED ON SETMS MACRO	<ul style="list-style-type: none"> • PREVIOUS DATA READ INTO RECOVERY BUFFER • CURRENT SECTOR RETRIED 	<ul style="list-style-type: none"> • READ PREVIOUS DATA INTO BUFFER AND RETRY RECOVERY • (A) = -0 IF PREVIOUS RETRY UNRECOVERED • CONTINUES IF PREVIOUS OK
RECOVERY BUFFER NOT SPECIFIED ON SETMS MACRO	ABORT RECOVERY	<ul style="list-style-type: none"> • READ PREVIOUS DATA OVER CURRENT AND RECOVER • (A) = -1 TO INDICATE CURRENT MUST BE REGENERATED

7X54/844-21 DISK STORAGE SUBSYSTEMS

Equipment type	DI (Half track, single density)
Sectors/track	107 x n
Tracks/device	1632
Words/device	11,175,936 x n
Maximum data rate	46.1K words per second

DI -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

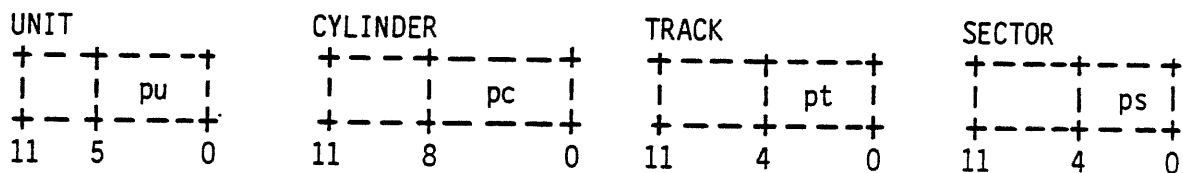
1 logical track = 107 physical sectors
 = 1/2 of 9 physical tracks

4 logical tracks = 1 physical cylinder

LOGICAL



PHYSICAL



Formulae

int(x) integer portion of x
 rem(x/y) remainder of x divided by y
 tk logical track
 sc logical sector
 pu physical unit number (bits 5 through 0)
 pc physical cylinder number (bits 8 through 0)
 pt physical track number (bits 4 through 0)
 lu logical unit
 ht half track bit (bit 1 of logical track)
 hc half cylinder bit (bit 0 of logical track)
 a intermediate result

$$lu = \text{int}(sc/153B)$$

$$a = ht + 2 \times \text{rem}(sc/153B)$$

$$ps = \text{rem}(a/30B)$$

pc = tk (bits 10 through 2)

pu = extracted from physical unit list in DLL MST word

DI -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = TRT ordinal

Physical head = 2 bytes in TRT word

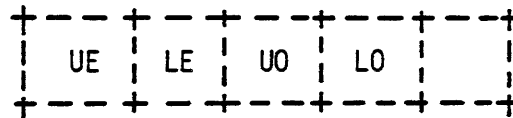
$0 \leq \text{physical head} \leq 10$

if physical sector is even, UE byte
if physical sector is odd, UO byte

$11 \leq \text{physical head} \leq 21$

if physical sector is even, LE byte
if physical sector is odd, LO byte

TRT ordinal



EVEN sector ODD sector

DI -- SECTOR ALLOCATION
 Logical track xxx0

PHYSICAL SECTOR

		00	01	02	03	...	24	25	26	27	
P H Y S I C A L H E A D T R A C K	00	000		001		...	012		013		
	01	014		015		...	026		027		
		
	07	124		125		...	136		137		
	10	140		141		...	152		XXX		
	.										
	.										
	21										
	22		THIS TRACK NOT USED BY NOS SOFTWARE								

DI -- SECTOR ALLOCATION
 Logical track xxx1

PHYSICAL SECTOR

P
H
Y
S
I
C
A
L

H
E
A
D

|

T
R
A
C
K

	00	01	02	03	...	24	25	26	27
00									
.									
.									
10									
11	000		001		...	012		013	
12	014		015		...	026		027	
.	
.									
20	124		125		...	136		137	
21	140		141		...	152		XXX	
22	THIS TRACK NOT USED BY NOS SOFTWARE								

DI -- SECTOR ALLOCATION
 Logical track xxx2

PHYSICAL SECTOR

		00	01	02	03	...	24	25	26	27	
P H Y S I C A L H E A D	00		000		001		...	012		013	
	01		014		015		...	026		027	
	
	.										
	07		124		125		...	136		137	
	T R A C K	10		140		141		...	152		XXX
		.									
		.									
		.									
		21									
22		THIS TRACK NOT USED BY NOS SOFTWARE									

DI -- SECTOR ALLOCATION
 Logical track xxx3

PHYSICAL SECTOR

		00	01	02	03	...	24	25	26	27
P H Y S I C A L H E A D	00									
	.									
	.									
	10									
	11		000		001		...	012		013
	12		014		015		...	026		027

	.									
	20		124		125		...	136		137
	21		140		141		...	152		XXX
T R A C K	22	THIS TRACK NOT USED BY NOS SOFTWARE								

7X54/844-4X DISK STORAGE SUBSYSTEMS

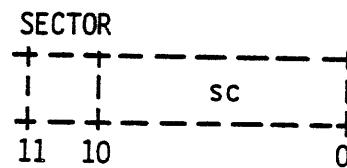
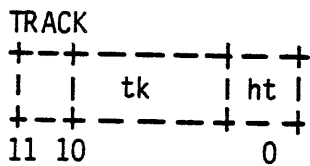
Equipment type	DJ (Half track, double density)
Sectors/track	227 x n
Tracks/device	1640
Words/device	23,825,920 x n
Maximum data rate	46.1K words per second

DI -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

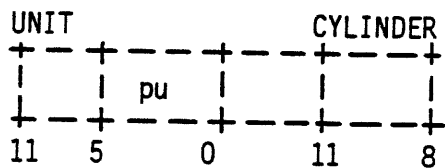
1 logical track = 227 physical sectors
 = 1/2 of 19 physical tracks

2 logical tracks = 1 physical cylinder

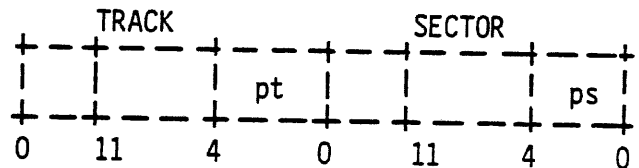
LOGICAL



PHYSICAL



pc



Formulae

int(x)	integer portion of x
rem(x/y)	remainder of x divided by y
tk	logical track
sc	logical sector
pu	physical unit number (bits 5 through 0)
pc	physical cylinder number (bits 9 through 0)
pt	physical track number (bits 4 through 0)
ps	physical sector number (bits 4 through 0)
lu	logical unit
ht	half track bit (bit 0 of logical sector)
a	intermediate result

$$lu = \text{int}(sc/343B)$$

$$a = ht + 2 \times \text{rem}(sc/343B)$$

$$pt = \text{int}(a/30B)$$

ps = rem(a/30B)

pc = tk (bits 10 through 1)

pu = extracted from physical unit list in DDLL MST word

DJ -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = 2 x TRT ordinal

INT (physical cylinder / 2) = TRT ordinal

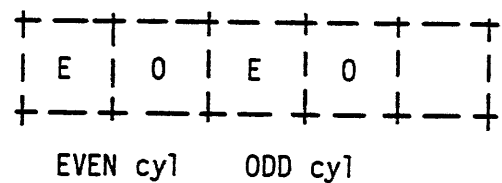
If physical cylinder is even = upper 2 bytes in TRT word

If physical cylinder is odd = lower 2 bytes in TRT word

If physical cylinder is even = upper of the two TRT bytes (E)

If physical cylinder is odd = lower of the two TRT bytes (O)

TRT ordinal



DJ -- SECTOR ALLOCATION
Even logical track

PHYSICAL SECTOR

		00	01	02	03	...	24	25	26	27
P H Y S I C A L H E A D T R A C K	00	000		001		...	012		013	
	01	014		015		...	026		027	
	02	030		031		...	042		043	
	03	044		045		...	056		057	
	
	.									
	17	250		251		...	276		277	
	20	300		301		...	312		313	
	21	314		315		...	326		327	
	22	330		331		...	342		XXX	

DJ -- SECTOR ALLOCATION
 Odd logical track

PHYSICAL SECTOR

		00	01	02	03	...	24	25	26	27
P H Y S I C A L H E A D T R A C K	00		000		001		...	012		013
	01		014		015		...	026		027
	02		030		031		...	042		043
	03		044		045		...	056		057

	.									
	17		250		251		...	276		277
	20		300		301		...	312		313
	21		314		315		...	326		327
	22		330		331		...	342		XXX

7154/844-21 DISK STORAGE SUBSYSTEMS

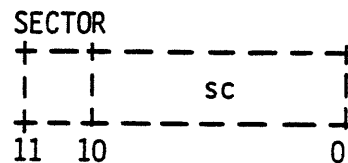
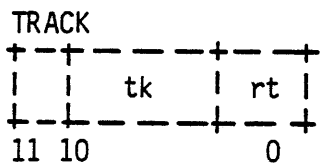
Equipment type	DK (Full track, single density)
Sectors/track	112 x n
Tracks/device	1632
Words/device	11,698,176 x n
Maximum data rate	92.16K words per second

DK -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

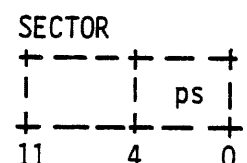
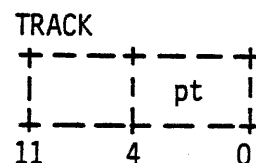
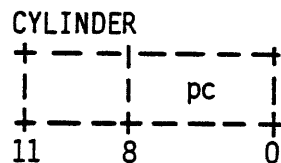
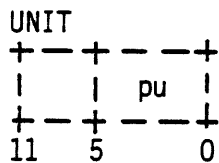
1 logical track = 112 physical sectors
 = 4 3/4 physical tracks
 = 4 physical tracks + 16 sectors

4 logical tracks = 1 physical cylinder

LOGICAL



PHYSICAL



Formulae

int(x) integer portion of x
 rem(x/y) remainder of x divided by y
 tk logical track
 sc logical sector
 lu logical unit
 pu physical unit number (bits 5 through 0)
 pc physical cylinder number (bits 8 through 0)
 pt physical track number (bits 4 through 0)
 ps physical sector number (bits 4 through 0)
 rt relative track in physical cylinder
 (bits 1, 0 of logical track)

$$lu = \text{int}(sc/160B)$$

$$ps = \text{rem}((rt \times 162B + \text{rem}(sc/160B))/30B)$$

$$pt = \text{int}((rt \times 162B + \text{rem}(sc/160B))/30B)$$

pc = tk (bits 10 through 2)

pu = extracted from physical unit list in DDLL MST word

DK -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = TRT ordinal

Physical head

00 <= head <= 03 = upper byte of TRT word

head = 04

00 <= physical sector <= 21 = upper byte

22 <= physical sector <= 27 = second byte

05 <= head <= 10 = second byte

head = 11

00 <= physical sector <= 13 = second byte

14 <= physical sector <= 27 = third byte

12 <= head <= 15 = third byte

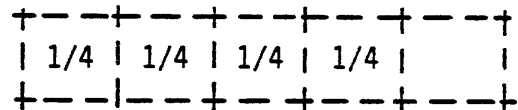
head = 16

00 <= physical sector <= 05 = third byte

06 <= physical sector <= 27 = fourth byte

17 <= head <= 22 = fourth byte

TRT ordinal



DK -- SECTOR ALLOCATION
 Logical track xxx0

PHYSICAL SECTOR

	00	01	...	17	20	21	...	26	27	
P H Y S I C A L H E A D T R A C K	00	000	001	...	017	020	021	...	026	027
	01	030	031	...	047	050	051	...	056	057
	02	060	061	...	077	100	101	...	056	057
	03	110	111	...	127	130	131	...	136	137
	04	140	141	...	157	* UNUSED *				
	05									
	.									
	.									
	22									

DK -- SECTOR ALLOCATION
 Logical track xxx1

PHYSICAL SECTOR

P
H
Y
S
I
C
A
L

H
E
A
D

|

T
R
A
C
K

	00	...	10	11	12	...	22	...	27
00									
.									
.									
04							000	...	005
05	006	...	017	020	021	...	030	...	035
06	036	...	047	050	051	...	060	...	065
07	066	...	077	100	101	...	110	...	115
10	116	...	127	130	131	...	140	...	145
11	146	...	157	* UNUSED *					
.									
.									
22									

DK -- SECTOR ALLOCATION
 Logical track xxx2

PHYSICAL SECTOR

P
H
Y
S
I
C
A
L

H
E
A
D

|

T
R
A
C
K

	00	...	03	04	05	...	14	...	27
00									
.									
.									
11							000	...	013
12	014	...	017	020	021	...	030	...	043
13	044	...	047	050	051	...	060	...	073
14	074	...	077	100	101	...	110	...	123
15	124	...	127	130	131	...	140	...	153
16	154	...	157	* UNUSED *					
.									
.									
22									

DK -- SECTOR ALLOCATION
 Logical track xxx3

PHYSICAL SECTOR

		00	01	...	06	...	24	25	26	27
P H Y S I C A L H E A D T R A C K	00									
	.									
	.									
	15									
	16				000	...	016	017	020	021
	17	022	023	...	030	...	046	047	050	051
	20	052	053	...	060	...	076	077	100	101
	21	102	103	...	110	...	126	127	130	131
	22	132	133	...	140	...	156	157	* UNUSED *	

7715X/844-4X DISK STORAGE SUBSYSTEM

Equipment type	DL (Full track, double density)
Sectors/track	227 x n
Tracks/device	1640
Words/device	23,825,920 x n
Maximum data rate	92.16K words per second

DL -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

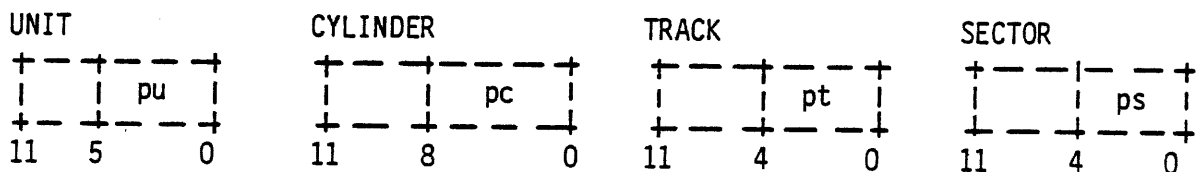
1 logical track = 227 physical sectors
= 9 1/2 physical tracks
= 9 physical tracks + 11 sectors

2 logical tracks = 1 physical cylinder

LOGICAL



PHYSICAL



Formulae

int(x) integer portion of x
rem(x/y) remainder of x divided by y
tk logical track
sc logical sector
lu logical unit
pu physical unit number (bits 5 through 0)
pc physical cylinder number (bits 9 through 0)
pt physical track number (bits 4 through 0)
ps physical sector number (bits 4 through 0)
rt relative track in physical cylinder
(bit 0 of logical track)

$$lu = \text{int}(sc/343B)$$

$$ps = \text{rem}((rt \times 345B + \text{rem}(sc/343B))/30B)$$

$$pt = \text{int}((rt \times 345B + \text{rem}(sc/343B))/30B)$$

pc = tk (bits 10 through 1)

pu = extracted from physical unit list in DLLL MST word

DL -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = TRT ordinal x 2

INT (physical cylinder / 2) = TRT ordinal

If physical cylinder is even = upper 2 bytes

If physical cylinder is odd = lower 2 bytes

00 <= physical head <= 10 = upper of the two bytes

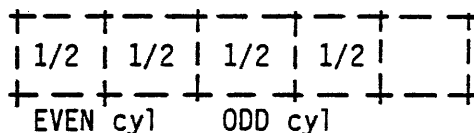
12 <= physical head <= 22 = lower of the two bytes

head = 11

00 <= physical sector <= 13 = upper of the two bytes

14 <= physical sector <= 27 = lower of the two bytes

TRT ordinal



DL -- SECTOR ALLOCATION
Even logical track

PHYSICAL SECTOR

		00	01	...	12	13	14	...	26	27
P H Y S I C A L H E A D T R A C K	00	000	001	...	012	013	014	...	026	027
	01	030	031	...	042	043	044	...	056	057
	02	060	061	...	072	073	074	...	106	107

	10	300	301	...	312	313	314	...	326	327
	11	330	331	...	342	* UNUSED *				
	12									
	.									
	.									
	22									

DL -- SECTOR ALLOCATION
 Odd logical track

PHYSICAL SECTOR

		00	01	...	13	14	15	...	26	27
P H Y S I C A L H E A D T R A C K	00									
	.									
	.									
	10									
	11				* UNUSED *		000	...	011	012
	12	013	014	...	026	027	030	...	041	042
	12	043	044	...	056	057	060	...	071	072
	.									
	.									
	21	263	264	...	276	277	300	...	311	312
22	313	314	...	326	327	330	...	341	342	

7155/555 DISK STORAGE SUBSYSTEMS

Equipment type	DM (Half track)
Sectors/track	640 x n (1 = n = 3)
Tracks/device	1682
Words/device	68,894,720 x n
Maximum data rate	61.44K words per sector

DM -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

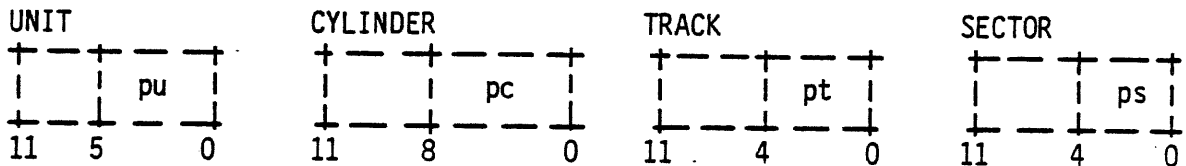
1 logical track = 640 physical sectors
 = 1/2 sectors of 40 physical tracks

2 logical tracks = 1 physical cylinder

LOGICAL



PHYSICAL



Formulae

int(x) integer portion of x
 rem(x/y) remainder of x divided by y
 tk logical track
 sc logical sector
 pu physical unit number (bits 5 through 0)
 pc physical cylinder number (bits 9 through 0)
 pt physical track number (bits 4 through 0)
 ps physical sector number (bits 4 through 0)
 ht half track bit (bit 0 of logical track)

$$lu = \text{int}(sc/1200B)$$

$$pt = \text{int}(sc/20B)$$

$$ps = ht + \text{rem}(sc/20B)$$

$$pc = tk \text{ (bits 10 through 1)}$$

pu = extracted from physical unit list in DDLL MST word

DM -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = 2 x TRT ordinal

INT (physical cylinder / 2) = TRT ordinal

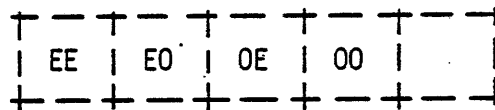
If physical cylinder is even = upper two bytes

If physical cylinder is odd = lower two bytes

If physical sector is even = upper of the two bytes

If physical sector is odd = lower of the two bytes

TRT ordinal



EVEN cyl ODD cyl

DM -- SECTOR ALLOCATION
Even logical track

		PHYSICAL SECTOR						SPARES*		
		00	01	02	03	...	36	37	40	41
P H Y S I C A L H E A D T R A C K	00	0000		0001		...	0017			
	01	0020		0021		...	0037			
	02	0040		0041		...	0057			
			
	.									
	22	0540		0541		...	0557			
	23	0560		0561		...	0577			
	24	0600		0601		...	0617			
			
	.									
47	1160		1161		...	1177				

* Spare sectors are used automatically when sector flaws exist.

DM -- SECTOR ALLOCATION
 Odd logical track

		PHYSICAL SECTOR						SPARES*		
		00	01	02	03	...	36	37	40	41
P H Y S I C A L H E A D T R A C K	00		0000		0001	...		0017		
	01		0020		0021	...		0037		
	02		0040		0041	...		0057		
		
	.									
	22		0540		0541	...		0557		
	23		0560		0561	...		0577		
	24		0600		0601	...		0617		
		
	.									
47		1160		1161	...		1177			

* Spare sectors are used automatically when sector flaws exist.

7155/845 DISK STORAGE SUBSYSTEMS

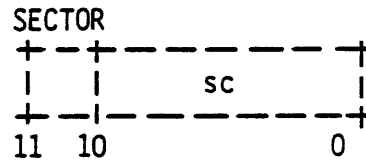
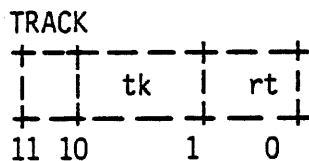
Equipment type	DQ (Full track)
Sectors/track	640 x n (1 ≤ n ≤ 3)
Tracks/device	1682
Words/device	68,894,720 x n
Maximum data rate	122.88K words per second

DQ -- LOGICAL TO PHYSICAL ADDRESS CONVERSION

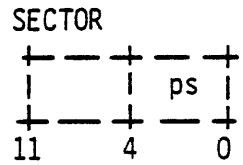
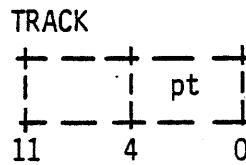
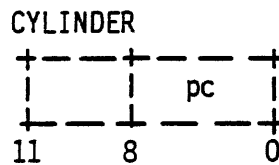
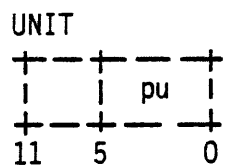
1 logical track = 640 physical sectors
 = 20 physical tracks

2 logical tracks = 1 physical cylinder

LOGICAL



PHYSICAL



Formulae

int(x)	integer portion of x
rem(x/y)	remainder of x divided by y
tk	logical track
sc	logical sector
pu	physical unit number (bits 5 through 0)
pc	physical cylinder number (bits 9 through 0)
pt	physical track number (bits 4 through 0)
ps	physical sector number (bits 4 through 0)
ht	half track bit (bit 0 of logical track)
rt	relative track in physical cylinder (bit 0 of logical track)

lu = int (sc/1200B)

pt. = rt x 24B + int(sc/40B)

ps = ht + rem(sc/40B)

pc = tk (bits 10 through 1)

pu = extracted from physical unit list in DDLL MST word

DQ -- PHYSICAL TO LOGICAL ADDRESS CONVERSION

Physical cylinder = 2 x TRT ordinal

INT (physical cylinder / 2) = TRT ordinal

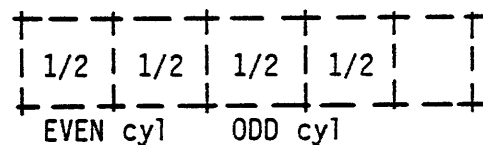
If physical cylinder is even = upper two bytes

If physical cylinder is odd = lower two bytes

00 < = physical head < = 23 = upper of the two bytes

24 < = physical head < = 47 = lower of the two bytes

TRT ordinal



DQ -- SECTOR ALLOCATION
Even logical track

		PHYSICAL SECTOR								
Odd logical track		00	01	02	03	...	36	37	SPARES*	
P H Y S I C A L H E A D T R A C K	00	0000	0001	0002	0003	...	0036	0037		
	01	0040	0041	0042	0043	...	0076	0077		
	02	0100	0101	0102	0103	...	0136	0137		
		
		
	22	1100	1101	1101	1103	...	1136	1137		
	23	1140	1141	1142	1143	...	1176	1177		
	24									
	.									
	.									
47										

* Spare sectors are used automatically when sector flaws exist.

DQ -- SECTOR ALLOCATION
 Odd logical track

		PHYSICAL SECTOR							SPARES*	
		00	01	02	03	...	36	37	40	41
P H Y S I C A L H E A D T R A C K	00									
	.									
	.									
	23									
	24	0000	0001	0002	0003	...	0036	0037		
	25	0040	0041	0042	0043	...	0076	0077		
	26	0100	0101	0102	0103	...	0136	0137		
		
	.									
	46	1100	1101	1102	1103	...	1136	1137		
47	1140	1141	1142	1143	...	1176	1177			

* Spare sectors are used automatically when sector flaws exist.

ECS

- MASS STORAGE DEVICE
- ALLOCATED BY TRACKS AND SECTORS
- 16_{10} SECTORS/TRACK
- 65_{10} WORD SECTORS (LINKAGE + DATA)
- LINKAGE WORDS GROUPED TOGETHER SO THAT ONE TRACK OF DATA IS CONTIGUOUS WORDS

$$\text{LINKAGE WORD ADDRESS} = T \times 2020_8 = S$$

$$\text{DATA ADDRESS} = (T \times 2020_8) + 20_8 + (S \times 100_8)$$

T = LOGICAL TRACK
S = LOGICAL SECTOR

- USED FOR ALL MASS STORAGE PROPERTIES
- WHEN USED AS LINK DEVICE IN MMF COMPLEX, LABEL TRACK HAS MMF TABLES

ECS

- USER PROGRAM FIELD LENGTH
FTN/COBOLS/SYMBOL/COMPASS
- DIRECT VS. INTERPRETIVE MODES
RE WE
COMCECM - ECSTEXT
COMCECS
RD WT
- UEC = CMRDECK ENTRY
- CPU 0
- FIELD LENGTH MANAGEMENT ANALOGOUS TO CENTRAL MEMORY

ECS Direct Access Chain

	59	47	35	23	17	11	5	0
000	** UECS.					LIFT		
001	eqss	ftss						
002			dtss					
003								
004	mid1	ft1	ln1	ra1	lt1			
005	mid2	ft2	ln2	ra2	lt2			
006	mid3	ft3	ln3	ra3	lt3			
007	mid4	ft4	ln4	ra4	lt4			

- eqss Equipment number.
- ftss First track.
- dtss Last modification date and time (packed format).
- mid Machine ID.
- ft First track of subchain.
- ln Length of ECS block.
- ra RAE of ECS block.
- lt Last track of subchain.

ECS

ACCESS UNDER CONTROL OF CPUMTR BY FUNCTION ECSM

- RRES/WRES
TRANSFER 1 TO 100g WORDS TO/FROM RELATIVE ECS TO A SPECIFIED CM BUFFER.
- RECS/WECS
TRANSFER 1 TO 100g WORDS TO/FROM ABSOLUTE ECS TO A SPECIFIED CM BUFFER.
- SFRS/CFRS
SET/CLEAR FLAG REGISTER BITS (AND SET/CLEAR INDICATION OF WHICH MAINFRAME HELD THE INTERLOCK (FLAG REGISTER BIT))
- RELS
READ ECS ACCORDING TO A LIST OF ABSOLUTE ADDRESSES. THIS IS USED TO READ DATA FOR ECS DISPLAYS.

ECS

ACCESS UNDER CONTROL OF CPUMTR BY FUNCTION PIOM

- REBS

REQUEST BUFFER INTERLOCK ON CENTRAL MEMORY ECS PPU BUFFER

- RESS/WESS

TRANSFER 1018 WORDS TO/FROM CENTRAL MEMORY ECS PPU BUFFER. THIS WORKS WITH DATA AS IF IT WERE A MASS STORAGE SECTOR: LINKAGE + DATA

ACCESS UNDER CONTROL OF MTR BY FUNCTION ECXM

ECXM IS USED TO READ/WRITE BLOCK OF ECS DATA TO CENTRAL MEMORY. THIS FUNCTION IS USED BY IRI/IRO TO ROLL JOB WITH ECS FIELD LENGTH.

QUESTION SET LESSON 10

1. Explain the purpose and usage of the SETMS and ENDMS macros.
2. How does a PP program request mass storage space?
3. What subroutine within a mass storage driver would you use to read a sector? Write a sector?
4. Why is the last operation when writing on mass storage a DTKM (Drop Track) monitor function?
5. For the file at FNT address 6362 in the study dump, how long is this file (in sectors)? Trace the track linkage.
6. Find the first two flaws on mass storage equipments 6 and 14. Give your answer by logical track.
7. Explain the concept of seek overlap.
8. Explain the recovery techniques used when writing in 1 to 1 interlace (full tracking) mode.
9. Mass storage equipment 14 is a multi-spindle device. How many sectors per track and what are the physical units for equipment.
14? This equipment would have what mnemonic?

LESSON 11 DEADSTART AND RECOVERY

LESSON PREVIEW:

In this lesson, the processing of deadstarting the NOS Operating System is presented. The particulars of the deadstart process as far as commands and panel setting are detailed in the NOS Installation and Maintenance course.

This lesson also covers the various levels of deadstart/recovery and overviews the operations performed to recover mass storage devices.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe how the NOS system uses the hardware deadstart properties to establish the operating system.
- Describe each logical step in the deadstart process, detailing what is done at each step and what routines are involved.
- Explain each type of recovery and tell what is recovered by that level of deadstart.
- Explain why a deadstart should not be done with device checkpoints pending.
- Identify the routines involved with mass storage recovery both at deadstart and on-line.

REFERENCES:

NOS IMS - Chapters 8 and 26 NOS Operator's Guide, 2 NOS IHB, 7, 8 NOS SMRM, 6 NOS Installation and Maintenance course materials

SUPPLEMENTAL TEXT: DEVICE CHECKPOINT

A "device checkpoint" consists of preserving the current CMR tables for a mass storage device (MST/TRT/MRT) in the label track of that device.

Anytime the system alters the mass storage allocation information of a mass storage device, a checkpoint will be requested on that device. This status is set in the device's MST. Periodically, ISP checks to see if any device checkpoints are pending and if so will call ICK to checkpoint the mass storage devices.

If "MS VALIDATION" is enabled, ICK will validate the device and, if the validation is successful, will write all mass storage tables into the label for the device. If the validation is not successful, the operator will be informed by messages at the system control point and the checkpoint will be aborted. This keeps incorrect data from being checkpointed to the device label.

HARDWARE DEADSTART

1. EACH CHANNEL IS CONNECTED TO ITS CORRESPONDING PPU (I.E., CH 1 TO PPU 1, CH 2 TO PPU 2, ETC.)
2. MASTER CLEAR IS DONE ON I/O CHANNELS WHICH SETS EACH CHANNEL ACTIVE AND EMPTY, READY TO ACCEPT INPUTS.
3. (A) OF EACH PPU IS SET TO 10000 SO THAT A PPU CAN INPUT ITS ENTIRE FL BEFORE AUTOMATIC DISCONNECT. P REGISTER CLEARED (SET = 0).
4. DEADSTART PANEL IS SENT ACROSS CHANNEL 0 INTO PPU 0 AT LOCATIONS 1-20 (1-14 NON-170).

A DCN IS ISSUED AND PPU 0 BEGINS EXECUTION AT $(P) + 1 = 0+1 = 1$.

5. EACH PPU SIMULATES AN IAM ON ITS CHANNEL.

I.E., LDC 10000
 IAM CH,0000

6. CPU DOES A HARDWARE IDLE.

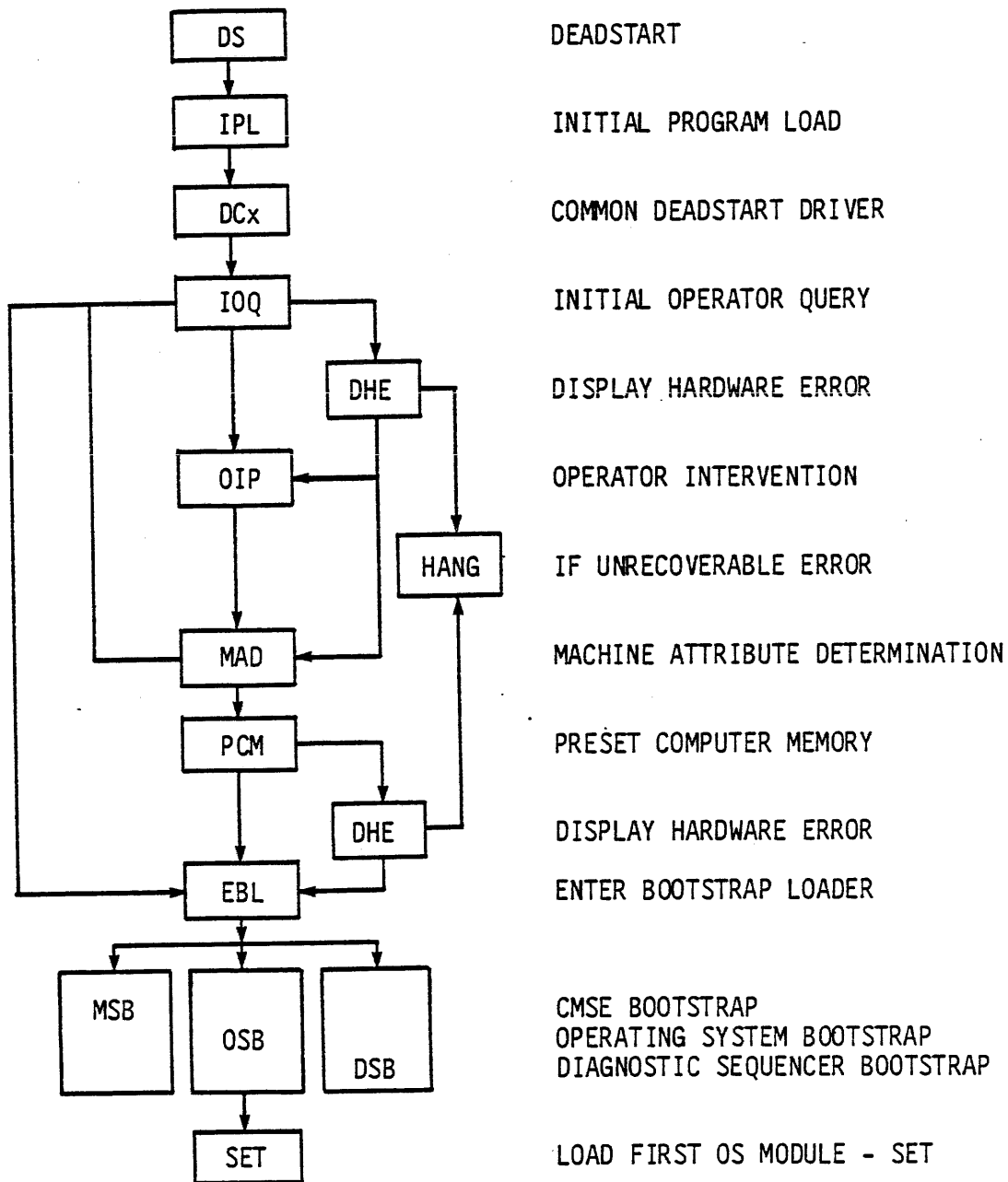
WHEN IAM BEGINS, (P) IS STORED IN LOCATION 0. AS EACH 12 BIT PP WORD IS RECEIVED, (A) IS DECREMENTED. WHEN (A)=0 OR CHANNEL IS DISCONNECTED, THE PPU STORES (0)+1 INTO P AND BEGINS EXECUTION.

THE PROGRAM INPUTTED BY THE PPU IS SUCH THAT THE LAST WORD READ WRAPS INTO LOCATION 0. THIS LAST WORD IS THE ADDRESS TO START EXECUTION.

DEADSTART/CTI

CTI - COMMON TEST AND INITIALIZATION

- ONE PANEL SETTING FOR NOS, NOS/BE, CMSE OVER ALL MAINFRAMES.
- OPERATOR DISPLAYS ALLOW SELECTION OF WHAT TO RUN, CONFIGURATION MODIFICATION, INSTALLATION OF MAINTENANCE MODULES.
- PASSES TO OPERATING SYSTEM OR DIAGNOSTICS A HARDWARE DESCRIPTOR TABLE (HDT) DESCRIBING THE PROPERTIES OF THE MAINFRAME CONFIGURATION, CONTENTS OF DEADSTART PANEL, DISK LOCATION POINTERS FOR CTI, CMSE, DDS, OS IN PPO.
- LOADS/BOOTSTRAPS TO CMSE, DIAGNOSTIC SEQUENCER (DDS) AND OPERATION SYSTEM (SET).



CTI MODULE DESCRIPTION

IPL - INITIAL PROGRAM LOAD

- CONTAINS POINTER TABLE.
- DETERMINES DS DEVICE TYPE AND LOADS APPROPRIATE DRIVER.

CD7 - 67X
CD6 - 66X
CD3 - 60X/65X
CD4 - 844
CD8 - 885

CDX - COMMON DEVICE DRIVER

- LOADS AND TRANSFERS CONTROL TO IOQ.
- CALLED TO LOAD EACH CTI MODULE.

IOQ - INITIAL OPERATOR QUERY

- PRESENTS INITIAL OPTIONS DISPLAY.
- INITIALIZES HARDWARE DESCRIPTOR TABLE (HDT).
- SAVES COPY OF DEADSTART PANEL.

OIP - OPERATOR INTERVENTION DISPLAY

- ALLOWS SELECTION OF DDS SELECTION.
- ALLOWS MODIFICATION OF D.S. PANEL (WORDS 12-14)
(MODIFIES DEADSTART PANEL IMAGE).
- ALLOWS SELECTION/DESELECTION OF MAINFRAME ATTRIBUTES
(MODIFIES HDT).

CTI MODULE DESCRIPTION (Continued)

MAD - MAINFRAME ATTRIBUTE DETERMINATION

- DETERMINES ACTUAL HARDWARE CONFIGURATION AND SETS APPROPRIATE BITS IN HDT (HAREWARE RECONFIGURATION VIA, H DISPLAY OVERRIDES ACTUAL CONFIGURATION).
- DEADSTARTS FIRST LEVEL PPU's.

PCM - PRESET COMPUTER MEMORY

- INITIALIZE PP MEMORIES (0'S THEN 1'S) CHECKING FOR ERRORS.
- INITIALIZES CM MEMORIES (0'S THEN 1'S) CHECKING FOR ERRORS (IF RECOVERY NOT SELECTED).
- IDLES DESELECTED PP'S.

EBL - EXTERNAL BOOTSTRAP LOADER

- ESTABLISHES CTI HANDOFF STATE.
- LOADS SELECTED BOOTSTRAP (OSB, MSB, DSB).

DHE - DISPLAY HARDWARE ERRORS

- CALLED BY IOQ OR PCM IF ERROR STATUS IS DETECTED IN SCR REGISTER.
- CLEARS NON-FATAL ERRORS (SINGLE BIT SECDED) AND RETURNS TO CALLING PROGRAM
- DISPLAYS FATAL ERROR STATUS AND HANGS.

AEI - UTILITY DISPLAY

- DISPLAYS CTI UTILITY OPTIONS.

SAD - SELECT ALTERNATE DEVICE

- ALLOWS DEADSTART FROM DEVICE OTHER THAN ORIGINAL DEADSTART DEVICE.

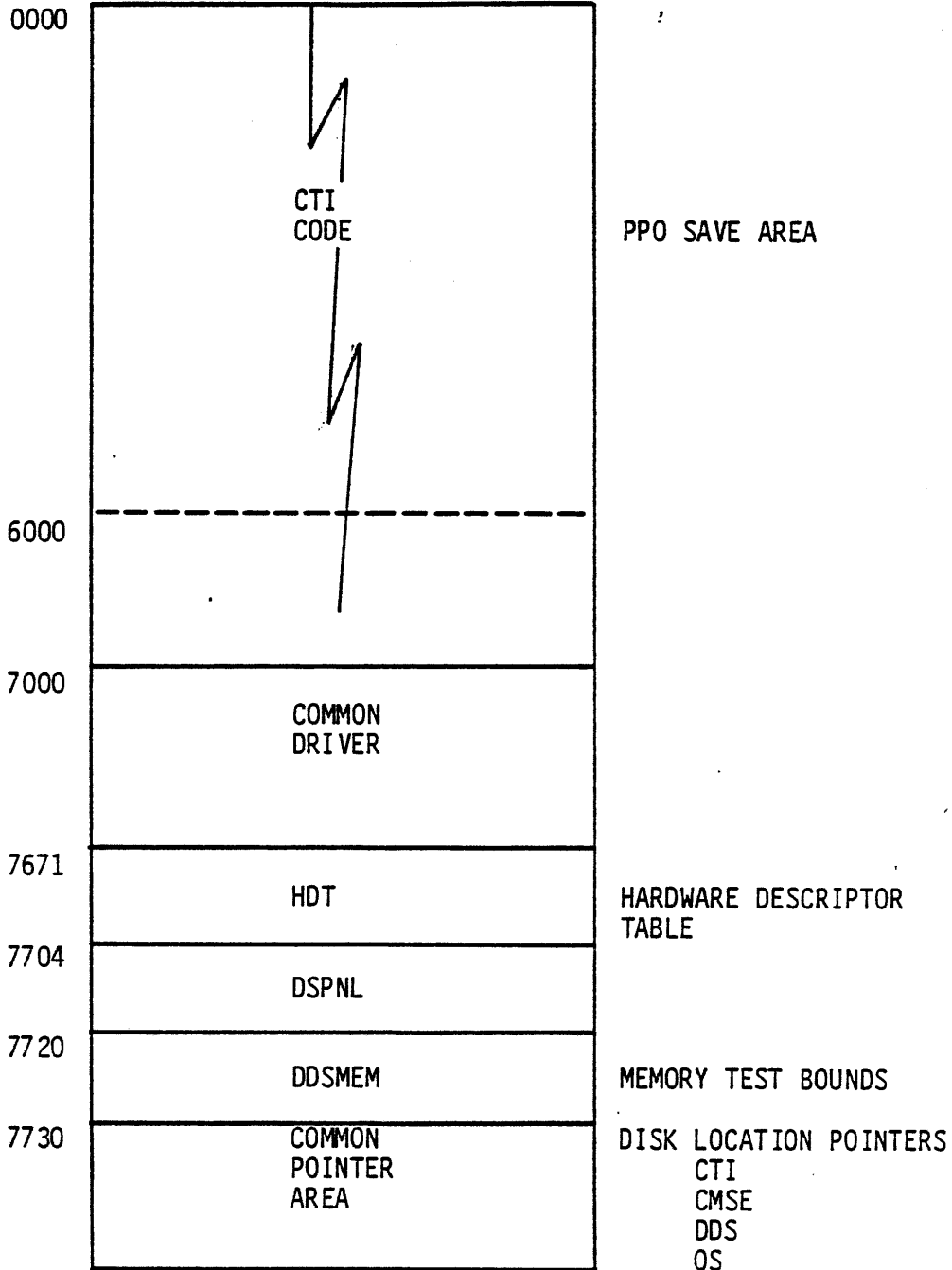
ICD - INSTALL CTI ON RMS DEVICE

- INSTALLS CTI ON SELECTED DEVICE.

EDD - EXPRESS DEADSTART DUMP

- ALLOWS SYSTEM DUMP TO TAPE.

CTI MEMORY MAP



HARDWARE DESCRIPTOR TABLE

WORD 1 WORD 2	CENTRAL MEMORY SIZE	MULTIPLES OF 100B
WORD 3	CPU OPTIONS*	1 BIT FOR EACH OPTION
WORD 4 WORD 5	PHYSICAL PPs PRESENT	1 BIT FOR EACH PP
WORD 6 WORD 7	LOGICALLY ON PPS	1 BIT FOR EACH PP
WORD 8 WORD 9	PHYSICAL PPU _s PRESENT	1 BIT FOR EACH PPU
WORD 10 WORD 11	LOGICALLY ON PP _s	1 BIT FOR EACH PPU

* BIT ASSIGNMENTS

CPU0
CPU1
CEJ/MEJ
CMU
INSTRUCTION STACK
SCR
ILR
C76A
C76B
C176

DEADSTART

DIO IS LOADED BY OSB (FROM CTI). DIO READS DEADSTART MEDIUM (TAPE OR DISK) DURING THE DEADSTART PROCESS. DIO LOADS SET INTO PPO AND TRANSFERS CONTROL TO IT.

SET USES PP10 AS A BUFFER FOR CMRDECK AND IPRDECK PROCESSING, AN IDLE PROGRAM, AND BUFFER PROCESSORS.

SET INITIALIZES THE SYSTEM:

1. SET LOADS CMR AND CMRINST AND FINDS THE SPECIFIED CMRDECK. CONSOLE INPUT TO ALTER THE CMRDECK MAY BE ENTERED. A "GO." OR "NEXT." CONTINUES THE DEADSTART SEQUENCE.
2. THE NEXT NON-TEXT ROUTINE (ICM) IS LOADED. ICM (INITIALIZE CENTRAL MEMORY) BUILDS THE FOLLOWING TABLES AND RETURNS TO SET:

EST	SYSTEM
FNT/FST/FNT INTERLOCK TABLE	VALIDUs
MST/TRT/MRT	SALVid
JOB CONTROL AREAS	RSXDid
CONTROL POINT AREAS	RSXVid
DAYFILE POINTERS	
PP COMMUNICATION AREA	

3. SET LOADS IPR AND IPRINST AND FINDS THE SPECIFIED IPRDECK. IPR SETS APPROPRIATE PORTIONS OF CENTRAL MEMORY RESIDENT - IPRL, JOB CONTROL AREAS, MSAL, ETC. - AS SPECIFIED BY IPRDECK ENTRIES AND RETURNS CONTROL TO SET.
4. SET FINDS NEXT NON-TEXT RECORD (PPR-PPU RESIDENT) AND READS IT INTO ITS PP BUFFER. PPR IS SENT TO PPU2 OVER CHANNEL 2. SET READS THE NEXT RECORD (STL - SYSTEM TAPE LOADER) AND SENDS IT TO PPU2. SET DCNs CHANNEL 2 CAUSING PPU2 TO BEGIN EXECUTING. PPU 0 ISSUES AN IAM ON CHANNEL 0 AND WAITS FOR INPUT.
5. STL IS NOW IN CONTROL. STL LOADS THE NEXT ROUTINES FROM THE DS FILE. THESE ROUTINES - CPUMTR, MASS STORAGE DRIVERS, ETC. - COMPRISE ENOUGH OF THE OPERATING SYSTEM TO ALLOW RECOVERY AND SYSEDIT TO EXECUTE WITHOUT A LOT OF SPECIAL CASING IN THE DS PROCESS.
 - A COPY OF PPR IS LOADED INTO ALL PPUs EXCEPT 0 AND 1.
 - MTR (PPU MONITOR) - NEXT RECORD ON DS TAPE - IS LOADED INTO PPU 0.

DEADSTART (Continued)

- CPUMTR IS LOADED. AN EXN STARTS CPUMTR EXECUTION. CPUMTR PRESENTS ITSELF BASED ON MODULES LOADED.
- DSD IS LOADED INTO PPU 1.
- RMS (RECOVERY MASS STORAGE) IS LOADED INTO NEXT AVAILABLE PPU (PPU 3).
- CHANNEL 0 IS DISCONNECTED WHICH CAUSES MTR TO BEGIN EXECUTION.
- MASS STORAGE DRIVERS AND REMAINING CODE (THROUGH SLL) ARE LOADED INTO A RPL (RESIDENT PERIPHERAL LIBRARY) AND A PLD (PERIPHERAL LIBRARY DIRECTORY) IS BUILT FOR THESE ROUTINES.
- SLL (SYSTEM LIBRARY LOADER) IS LOADED INTO THE NEXT AVAILABLE PPU (PPU4) ON LEVEL 0 OR 2 DEADSTARTS.
- A "LJM PPR" IS SENT TO ALL OTHER PPUs AND THEY ARE DISCONNECTED, CAUSING THEM TO BEGING EXECUTION.
- CONTROLWARE IS THEN LOADED INTO 7X5X CONTROLLERS. BCL IS READ AS AN OVERLAY TO STL; BCL READS BCS, BCF AND FMD AND OUTPUTS THE APPROPRIATE CONTROLWARE ON ALL CHANNELS WITH 7X5Xs. THE ENTIRE COPY OF THE FIRMWARE IS SENT ONE CHANNEL AT A TIME. THE EQUIPMENT TYPE AND LBC ENTRY DETERMINES WHICH CONTROLWARE IS LOADED. BCL ALSO VALIDATES WHETHER FULL TRACKING MAY BE DONE (2XPPU AND FULL TRACK ACCESS).

DEADSTART (Continued)

- LSL (LOAD SYSTEM LIBRARY) IS LOADED, IF LEVEL 0 OR 2, AS AN OVERLAY TO STL.
- LSL CCAM's TO CONTROL POINT 1, CONTROL POINT 1 IS CALLED THE "DEAD START CONTROL POINT." THE XP AND THE CONTROL POINT AREA ARE INITIALIZED; FL IS THE REMAINDER OF MEMORY UP TO 377700.
- LSL SET UP AN INPUT FILE FNT ENTRY SO THAT EVERYTHING RESEMBLES A "RUNNING" SYSTEM (UNLESS DEADSTART IS FROM DISK).
- LSL LOADS SYSEDIT INTO CP1's FIELD LENGTH AND REQUESTS THE CPU (RCPM) SO THAT SYSEDIT MAY BEGIN EXECUTION.
- SYSEDIT READS THE DS FILE VIA DIO OR CIO AND COPIES DATA DIRECTLY TO SYSTEM DEVICES USING SLL. SLL GUARANTEES EACH COPY OF THE SYSTEM USES THE SAME TRACKS.
- AT EOF, LSL RETURNS CONTROL TO STL. THE DS FILE IS REWOUND; STL MOVES TO THE SYSTEM CP VIA CCAM AND DROPS THE PPU VIA A DPPM. SYSEDIT BEGINS LIBRARY BUILDING.
- READING FROM THE FIRST SYSTEM DEVICE, SYSEDIT BUILDS THE RPL ACCORDING TO THE SPECIFIED LIBDECK AND COPIES IT TO CM USING SLL. RPL ENTRIES ARE MADE WITHOUT PREFIX (77) TABLES.

DEADSTART (Continued)

- A PPULIB FILE IS BUILT ON EACH SYSTEM DEVICE OF ALL PPU ROUTINES WITHOUT PREFIX TABLES. THE POINTER TO PPULIB IS CONTAINED IN THE SYSTEM SECTOR FOR THE SYSTEM FILE. THE PLD IS BUILT WITH THE NAME AND RESIDENCE OF ALL PPU ROUTINES IN ALPHABETICAL ORDER.
- THE RCL (RESIDENT CENTRAL LIBRARY) IS BUILT WITH THOSE CPU ROUTINES HAVING *CM LIBDECK DIRECTIVES.
- THE CLD (CENTRAL LIBRARY DIRECTORY) IS BUILT FOR ALL CPU ROUTINES, WITH THEIR NAMES, ENTRY POINTS, AND RESIDENCE.
- THE LBD (USER LIBRARY DIRECTORY) IS BUILT FOR ALL USER LIBRARIES WITH THEIR NAMES AND RESIDENCE.
- SYSEDIT COMPLETES WITH AN ENDRUN.

THE FULL OPERATING SYSTEM HAS BEEN ESTABLISHED AND IS COMPLETELY OPERATIONAL.

WHILE ALL OF THIS IS GOING ON ...

DEADSTART (Continued)

MASS STORAGE RECOVERY IS ACCOMPLISHED IN THE PPU_s VIA RMS - RECOVER MASS STORAGE - AND REC - SYSTEM RECOVERY PROCESSOR.

- RMS -

- READ MST_s FROM DEVICE LABELS.
- VALIDATES HALF TRACK AND FULL TRACK AVAILABILITY.
- RECOVERS TRT_s.
- VALIDATES AND RECOVERS SYSTEM DAYFILES.
- VALIDATES AND RECOVERS PRESERVED FILES.
- VALIDATES PERMANENT FILE CONFIGURATION.
- LOADS REC INTO THIS PPU.

- REC -

- READS SYSTEM TABLES (CHECKPOINT FILE)
- RECOVERS FNT AND CONTROL POINTS.
- ACTIVATES/INITIALIZES DAYFILES.
- WAITS FOR SYSEDIT/SLL TO COMPLETE. (I.E., SYSTEM FILE BECOMES NOT BUSY.)
- IQFT IS BUILT FROM QUEUED FILES FOUND ON DISK.
- DAF INTERLOCKS ARE CLEARED (LEVEL 0).
- DAYFILE MESSAGES ISSUED.
- CHECKPOINT SYSTEM AND ALL DEVICES.
- START 1TD IF TELEX RECOVERY REQUIRED.
- STARTS SCHEDULING VIA RSJM.
- DROP PPU VIA DPPM.

MASS STORAGE RECOVERY

RMS - RECOVER MASS STORAGE

CMS - CHECK MASS STORAGE

REC - SYSTEM RECOVERY PROCESSOR

DEVICE RECOVERY IMPLIES THAT ALL INFORMATION CONTAINED IN THE DEVICE'S LABEL IS TRANSFERRED TO THE DEVICE'S MST/TRT. AN INITIALIZATION ALTERS ALL OR SOME OF THE INFORMATION FROM THE LABEL WHEN MOVING IT TO THE MST/TRT.

DEVICE LABEL IS DEFINED IN COMMON DECKS COMSLSD.

RMS ATTEMPTS TO RECOVER ALL DEFINED MASS STORAGE EQUIPMENTS AT DEADSTART TIME.

RMS IS CALLED BY STL WITH THE RECOVERY LEVEL AS INPUT.

RMS HAS FIVE LOGICAL PHASES:

- PRESET.
- READ DEVICE LABELS.
- VALIDATE HALF TRACK AND FULL TRACK AVAILABILITY.
- CHECK AND RECOVER DEVICES.
- CALL REC INTO EXECUTION.

CMS VERIFIES THE PROPER DEVICES ARE MOUNTED AND MAKES THEM AVAILABLE FOR USER/SYSTEM ACCESS.

CMS IS CALLED ON A PERIODIC BASIS BY ISP OR WHEN AN ONLINE INITIALIZATION IS NEEDED (BY IMS). 1DS ALSO CALLS CMS AS THE RESULT OF AN UNLOAD OR MOUNT COMMAND.

CMS HAS SEVEN LOGICAL PHASES:

- PRESET.
- READ DEVICE LABELS.
- VALIDATE HALF TRACK AND FULL TRACK AVAILABILITY.
- CHECK AND RECOVER DEVICES.
- CHECK FOR INITIALIZATION REQUESTS.
- COUNT ACTIVE FAMILIES.
- CONTROLS DEADSTART SEQUENCING OPERATIONS.

REC PERFORMS A VARIETY OF RECOVERY FUNCTIONS INCLUDING:

- READING SYSTEM TABLES (CHECKPOINT FILE)
- RECOVERS FNT, CONTROL POINTS, ETC.
- INITIALIZES/ACTIVATES DAYFILES
- BUILDS IQFT (INACTIVE QUEUE)
- CLEARS DAF INTERLOCKS

REC IS LOADED INTO THE SAME PPU AS RMS BUT DOES NOT COMPLETE EXECUTION UNTIL SYSTEM FILE BECOMES NOT BUSY. SYSTEM IS BUSY IF THE SYSTEM IS BEING ESTABLISHED (LOADED) BY SYSEDIT/SLL.

RECOVERY DEADSTARTS

- LEVEL 0
 - SYSTEM LOADED FROM DS TAPE.
 - PRESERVED FILES RECOVERED.
- LEVEL 1
 - SYSTEM RESTORED FROM CHECKPOINT FILE.
 - JOBS AND FILES RECOVERED FROM CHECKPOINT FILE.
 - SUCCESSFUL CHECKPOINT SYSTEM.
 - ALL MASS STORAGE INTACT.
 - CMRDECK ENTRIES SAME AS LAST LEVEL 0 OR MATCH RECONFIGURATIONS (IF ANY).
- LEVEL 2
 - SYSTEM LOADED FROM DS TAPE.
 - JOBS AND FILES RECOVERED FROM CHECKPOINT FILE.
 - SUCCESSFUL CHECKPOINT SYSTEM.
 - ALL MASS STORAGE INTACT.
 - CMRDECK ENTRIES SAME AS LAST LEVEL 0 OR MATCH RECONFIGURATIONS (IF ANY).

RECOVERY DEADSTARTS

- LEVEL 3
- SYSTEM, FNT, MST/TRT, LOW CORE CMR AND CONTROL POINTS RECOVERED FROM CENTRAL MEMORY.
 - FNT, MST/TRT, LOW CORE CMR AND CONTROL POINTS MUST BE INTACT.
 - JOBS AT CONTROL POINTS RESTARTED (RERUN).
 - CMRDECK ENTRIES SAME AS LAST LEVEL 0 OR MATCH RECONFIGURATIONS (IF ANY).

RECOVERY DEADSTARTS

WHEN?

- LEVEL 0
 - INITIAL DEADSTART
 - RESTART FROM UNSUCCESSFUL LEVEL 3
 - AFTER MREC
- LEVEL 1
 - CONTROLLED IDLE DOWN BY CHECKPOINT SYSTEM
 - ALLOW SCHEDULED INTERRUPTION OF PRODUCTION FOR MAINTENANCE OR "SYSTEMS TIME"
- LEVEL 2
 - CONTROLLED IDLE DOWN BY CHECKPOINT SYSTEM
 - SYSTEMS TEST SITUATIONS
- LEVEL 3
 - EQUIPMENT MALFUNCTION HANG
 - SYSTEM HANG

RECOVERY DEADSTARTS

WHEN NOT?

LEVEL 0

LEVEL 1

- UNSUCCESSFUL CHECKPOINT SYSTEM
- RUNNING AFTER CHECKPOINT SYSTEM
- UNSUCCESSFUL LEVEL 3
- AFTER MREC

LEVEL 2

- SAME AS FOR LEVEL 1

LEVEL 3

- AFTER LEVEL 0, 1, 2 IS NOT SUCCESSFUL
- MREC HAS BEEN RUN FOR THIS MACHINE
- IF MEMORY HAS BEEN DESTROYED

FILE/MS VALIDATION

- A. TRT EOI = DISK EOI
READ DISK SECTOR POINTED TO BY TRT
- B. CHAIN FOR EOI
READ DISK BEGINNING AT BOI UNTIL EOI
- C. BOI/EOI
READ EOI; READ BOI POINTED TO AN EOI SECTOR
- D. CIRCULAR LINKAGE
IS (FIRST) TRACK POINTED TO WITHIN TRT?
- E. ONLINE CHECK OF TRT
UNRESERVED TRACKS AGREE
PRESERVED FILE COUNTS AGREE
PERMIT CHAIN RESERVED AND PRESERVED
CATALOG CHAIN RESERVED, PRESERVED, POWER OF 2, CORRECT LENGTH,
CONTIGUOUS (IF FLAGGED)
DATA (INDIRECT) CHAIN RESERVED AND PRESERVED

EI - ERROR IDLE (A - D)
NO PFM OR PF/QUEUE UTILITY OPERATIONS
NO NEW FILES

VE - VALIDATION ERRORS (E)

FILE/MS VALIDATION

- LEVEL 0 (OR ONLINE RECOVERY)

DAYFILES	B (CHAIN FOR EOI)
PERM FILE IN WRITE MODE	B (CHAIN FOR EOI)
OTHER PRESERVED FILES	A; B (IF A FAILS)
	D
	C (IF EEOI)

- LEVEL 1, 2

PRESERVED FILES	A
	C
	D (IF MS VALIDATION)

OTHER FNT ENTRIES	D (IF MS VALIDATION)
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- LEVEL 3

PRESERVED FILES	A
	C
	D
	D
	} REQUIRES BOTH
	} MS VALIDATION AND
	} PF VALIDATION

OTHER FNT ENTRIES	
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- DEVICE CHECKPOINT

	E (IF MS VALIDATION)
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- PERMANENT FILE ATTACH

	C (IF PF VALIDATION)
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RECOVERY DEADSTARTS

<u>LEVEL</u>	<u>JOB</u>	<u>ACTIVE FILES</u>	<u>PFS</u>	<u>DAYFILES</u>	<u>SYSTEM</u>	<u>FILE/MS VALIDATION</u>
0	QPROTECT	NO	YES	YES	LOADED	ALWAYS
1	CHECKPOINT FILE	CHECKPOINT FILE	YES	YES	CHECKPOINT FILE	MS
2	CHECKPOINT FILE	CHECKPOINT FILE	YES	YES	RELOADED	MS
3	CM DOPY OF FNT	CM COPY OF FNT	YES	YES	YES	MS PF

RECOVERY DEADSTARTS

ALL SYSTEM ACTIVITY SHOULD HAVE CEASED BEFORE DEADSTARTING AND ALL MASS STORAGE CHECKPOINTS SHOULD HAVE COMPLETED.

LEVEL 1/LEVEL 2

CHECKPOINT SYSTEM

LEVEL 3

1. ONSW1
1. IDLE.

}

IF TIME SHARING SUBSYSTEM ACTIVE

ALL LEVELS

E, M.

CHECK FOR DEVICE CHECKPOINTS

UNLOCK.

STEP.

RECOVERY DEADSTARTS

IF A SYSTEM MALFUNCTION PREVENTS A DEVICE CHECKPOINT FROM BEING DONE, THE CHECKPOINT STATUS WILL BE STILL SET OVER A LEVEL 3 DEADSTART AND WILL BE PERFORMED AFTER THE LEVEL 3 HAS BEEN SUCCESSFULLY COMPLETED.

IF THE LEVEL 3 SHOULD FAIL, AN ANALYSIS OF THE MASS STORAGE TABLES DUMP WILL REVEAL IF ANY CHECKPOINTS ARE PENDING. APPROPRIATE ACTION MAY BE TAKEN ON THE LEVEL 0 DEADSTART TO RESTORE THE FILES ON THE DEVICE.

DEVICE CHECKPOINT

CHECKPOINT - PRESERVE CURRENT CM TABLES IN DEVICE LABEL

- REQUEST CHECKPOINT IF MST/TRT ALTERED
 - CHECKPOINT STATUS IN STLL
- PERIODICALLY, 1CK IS CALLED TO CHECKPOINT DEVICES BY 1SP
- 1CK VALIDATES EACH DEVICE IF MS VALIDATION IS ENABLED
 - UNRESERVED TRACK COUNT AGREES
 - PRESERVED FILE COUNT AGREES
 - PERMIT CHAIN RESERVED/PRESERVED
 - DATA (INDIRECT) CHAIN RESERVED/PRESERVED
 - CATALOG CHAIN RESERVED/PRESERVED, POWER OF 2, CORRECT LENGTH, CONTIGUOUS (IF FLAGGED)
- 1CK WRITES TRT TO LABEL TRACK AND MST TO LABEL SECTOR
- 1CK CLEARS "CHECKPOINT REQUESTED" BIT WHEN FINISHED CHECKPOINTING THE DEVICE

SYSTEM CHECKPOINT

THE SYSTEM TABLE TRACK OR CHECKPOINT FILE CONTAINS A COPY OF CENTRAL MEMORY RESIDENT: LOW CORE POINTERS, THE EST, THE FNT, THE DAYFILE BUFFERS AND POINTERS AND FROM THE BEGINNING OF RPL TO THE END OF CMR.

CHECKPOINT SYSTEM

WHEN THE CHECKPOINT SYSTEM COMMAND IS ENTERED, THE FOLLOWING OPERATIONS OCCUR.

1. SET SENSE SWITCH FOR TIME SHARING SUBSYSTEM TO PLACE ALL USERS IN THE RECOVERY (SALVid) FILE ON AN OPERATOR DROP. TIME SHARING SUBSYSTEM IS THEN "OPERATOR DROPPED".
2. ALL JOB SCHEDULING IS INHIBITED. SAME AS IF IDLE HAD BEEN ENTERED.
3. JOBS WITH QUEUE PRIORITY MXPS ARE ROLLED OUT.
4. ALL OTHER JOBS EXCEPT MAGNET ARE ABORTED. MOST SUBSYSTEMS WILL CLEAN THEMSELVES UP.

SYSTEM CHECKPOINT

5. MAGNET IS ROLLED OUT.
6. CHECKPOINT FILE IS WRITTEN.
7. ALL DEVICES CHECKPOINTED INCLUDING MRTs FOR NON-REMOVABLE SHARED DEVICES.
8. SYSTEM IS LEFT IN AN IDLE STATE.

CHECKPOINT BY SYSEDT

THE CHECKPOINT REQUESTED BY SYSEDT WRITES THE CHECKPOINT FILE WITH THE CMR INFORMATION. THIS TYPE OF CHECKPOINT CANNOT BE USED FOR LEVEL 1 RECOVERY AS FAR AS RESTARTING JOBS IS CONCERNED. IT IS PRIMARILY USED TO GUARANTEE A SUCCESSFUL LEVEL 3 RECOVERY.

QUESTION SET LESSON 11

1. Why are all the PP A registers set to 10000B?
2. What are each of the PPs doing at deadstart time?
3. Why are the positions of the first PP routines on the deadstart file important?
4. What happens to the information represented on the deadstart panel at deadstart time?
5. What does NOS do with the Hardware Descriptor Table (HDT) it receives from CTI?
6. What does SYSEDIT do at deadstart time?
7. What is the PPLIB?
8. The last step in the deadstart process is usually a system checkpoint. Why?
9. Explain the four levels of deadstart recovery and what information is recovered by each level.
10. What happens when MS VALIDATION and PF VALIDATION are specified on a level 0 deadstart? On a level 3 deadstart?
11. Why is it advisable not to deadstart with device checkpoints pending?
12. What does the Deadstart Sequencing priority accomplish?

LESSON 12
LOGICAL INPUT/OUTPUT (CIO)

LESSON PREVIEW:

This lesson overviews the logical input/output processor CIO. The mnemonic CIO means combined input/output but is often called circular input/output because of the way the data buffer in the program's field length is managed.

This lesson does not deal with the end user particulars of doing logical input/output.

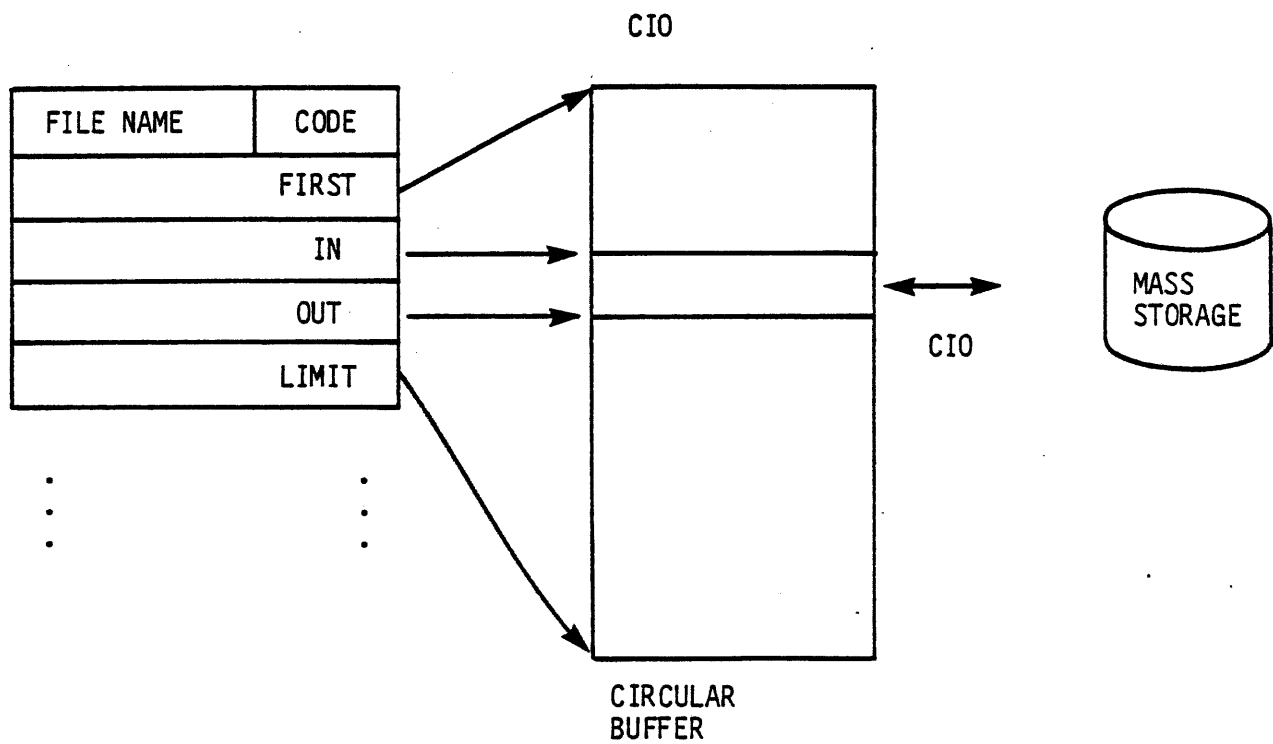
OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Overview the read and write technique to mass storage done by CIO.
- Describe how CIO does random input/output, including discussions of rewrite-in-place techniques.
- Describe how CIO processes input/output requests for magnetic tape resident files.
- Describe how CIO processes input/output requests for TTY resident files.
- Discuss how CIO knows when to terminate a read/write operation.

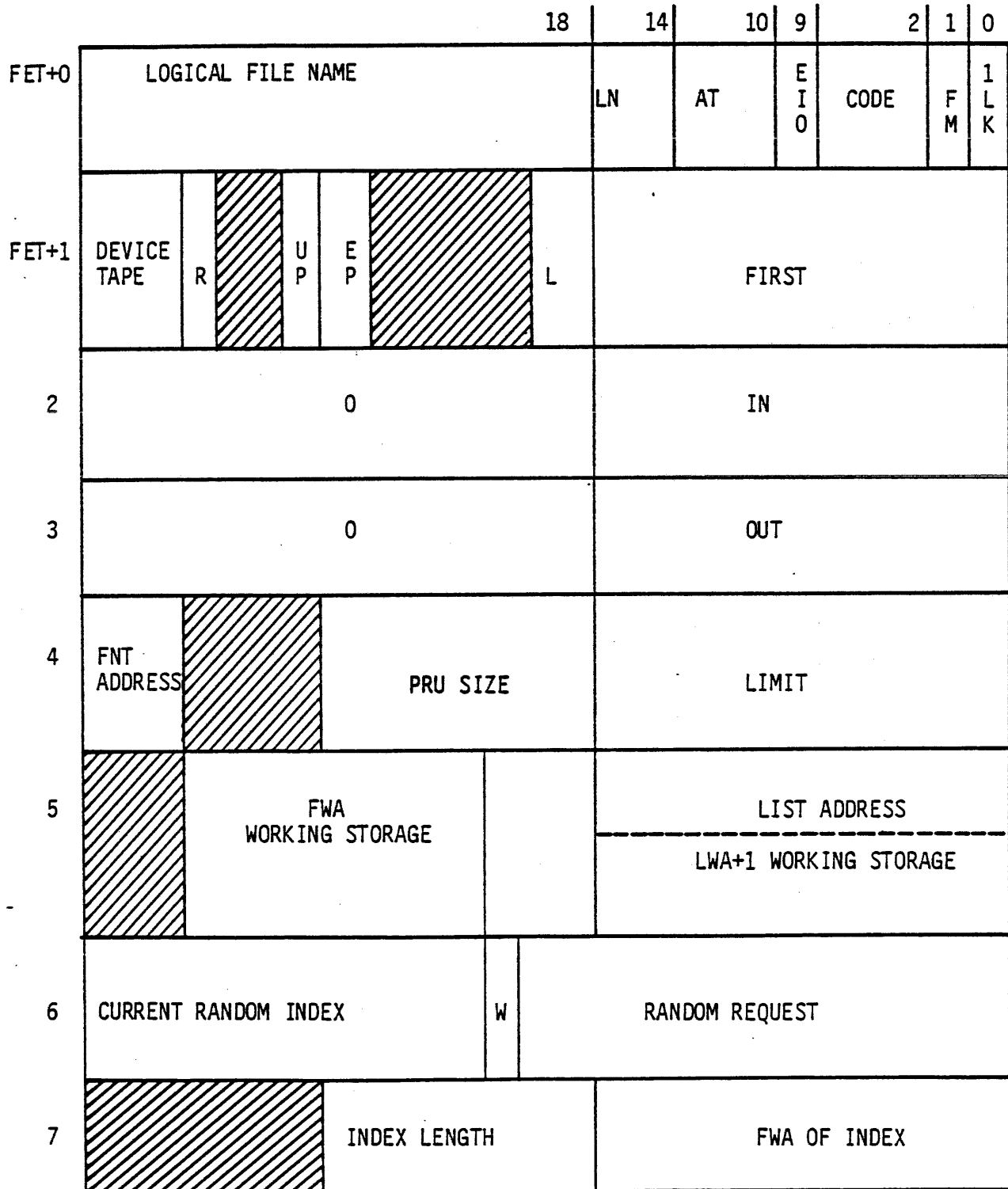
REFERENCES:

NOS IMS - Chapter 9 NOS Reference Manual, 2-2, 2-3 NOS Advanced Coding Student Handout



- MS - I/O DONE BY CIO DIRECTLY
- TAPE - CIO CALLS MAGNET
- TTY - CONTROL POINT WORDS SET UP AND ROLLOUT JOB

MASS STORAGE FET



CIO

● FET CREATION MACROS

FILEB	RFILEB
FILEC	RFILEC

● OPEN CLOSE
CLOSER

● READ/WRITE MACROS

RPHR	WPHR
READ	WRITE
READCW	WRITECW
READN	WRITEN

READSKP	WRITER
READLS	WRITEF
RPHRLS	
READNS	REWRITE
RADEI	REWRITER
	REWRITEF

● POSITIONING

BKSP	REWIND
BKSPRU	UNLOAD
	RETURN
SKIPF	EVICT
SKIPFF	
SKIPEI	
SKIPB	POSMF
SKIPFB	

CIO

STRUCTURE

- CIO - MAIN ROUTINE
- 2CA - IDENTIFY SPECIAL REQUEST
- 2CB - READ MASS STORAGE
- 2CC - SPECIAL MASS STORAGE READS
- 2CD - WRITE MASS STORAGE
- 2CE - SPECIAL MASS STORAGE WRITES
- 2CF - POSITION MASS STORAGE
- 2CG - CLOSE MASS STORAGE
- 2CH - TERMINAL I/O
- 2CI - MAGNETIC TAPE I/O
- 2CJ - MULTIFILE TAPE LABELS
- 2CK - ERROR PROCESSOR
- 2CL - ISSUE DAYFILE MESSAGES

CIO

1. READ AND VALIDATE FET
2. VALIDATE FUNCTION CODE
3. IDENTIFY REQUEST
4. SET SKIP COUNT, BINARY/CODED STATUS
5. SEARCH FOR FILE
 - CALL 2CJ IF POSMF
 - CREATE FILE IF FILE NOT FOUND
 - SET FILE BUSY
6. CHECK FILE ACCESS
 - CHECK PERMISSIONS
 - FILE RESIDENCE FOR OPERATION LEGALITY
 - SET RANDOM REQUEST
7. VALIDATE FIRST, IN, OUT, LIMIT
8. PROCESS FUNCTION
 - LOAD OVERLAY
9. COMPLETE FUNCTION
 - SET FET COMPLETE AND ANY STATUS
 - SET FILE NOT BUSY
 - SET STATUS INTO BYTE 4 OF FST
 - SET TRACK CURRENT POSITION INTO FST
 - PERFORM ACCOUNTING
 - DROP PP

CIO

READ MASS STORAGE (2CB/2CC)

1. IF FILE NOT EXISTENT, COMPLETE REQUEST WITH EOI STATUS.
2. IF RANDOM FUNCTION, POSITION FILE (2CF).
3. IF SPECIAL READ (RPHR, READEI, READNS, READSKP, READCW, RPHRLS, READLS), CALL 2CC TO INITIALIZE READ AND SET TERMINAL CONDITION.
4. SET UP TO READ (SETMS, SET ABSOLUTE ADDRESSES).
5. RECHECK ABSOLUTE ADDRESS (IF PAUSED).
6. LOAD BUFFER.
 - DETERMINE NUMBER OF BLOCKS IN BUFFER
 - READ DATA
 - HAVE FL/100 (STSW FL VALUE) SECTORS BEEN TRANSFERRED. IF SO, COMPLETE
 - PROCESS DATA
 - EOF/EOR
 - REPOSITION IF TRACK CHANGE
 - SEND DATA TO BUFFER
 - ADVANCE IN
 - IF TERMINATION CONDITION MET, QUIT; OTHERWISE, CONTINUE READING

CIO

TERMINAL I/O

WRITE

SET CONTROL INTO
CONTROL POINT WORD
TIOW (FET ADDRESS
OF OUTPUTTING FILE)

READ

SET CONTROL INTO
CONTROL POINT WORD
TINW (FET ADDRESS
OF INPUTTING FILE).

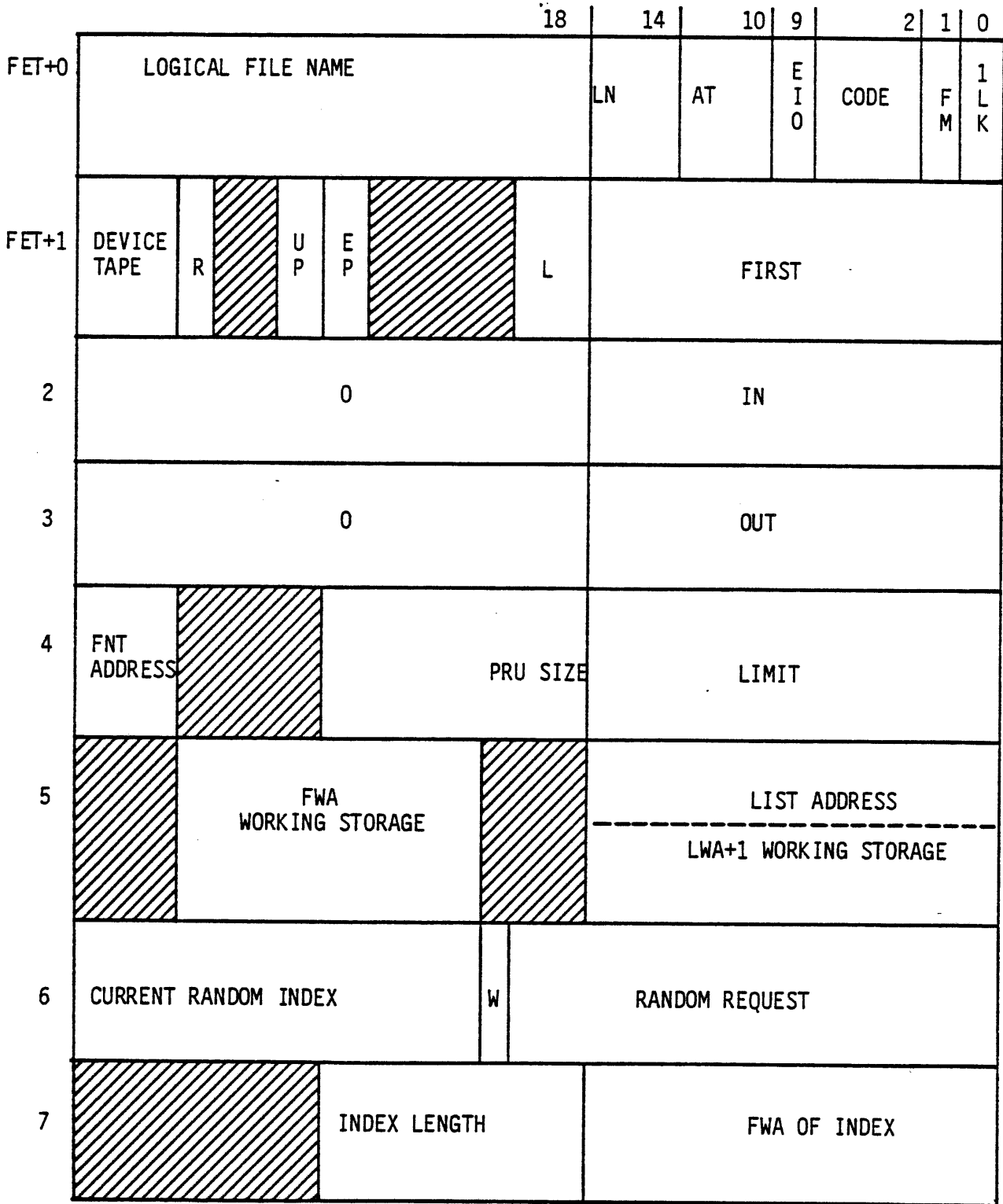
- ROLLOUT CONTROL POINT (ROCM)
- SET FILE COMPLETE
- IF NOT AUTO RECALL, DROP PP
- IF AUTO RECALL, WRITE RCLP INTO RA+1 AND DROP PP

CIO

TAPE I/O

- SET UP INFORMATION FOR TAPE I/O PROCESSING
- SEND REQUEST TO MAGNET VIA TDAM FUNCTION
- IF AUTO RECALL, SET RCLP INTO RA+1
- SET UP "ACCOUNTING" TO SET TAPE ACTIVITY IN STSW
- EXIT NORMALLY

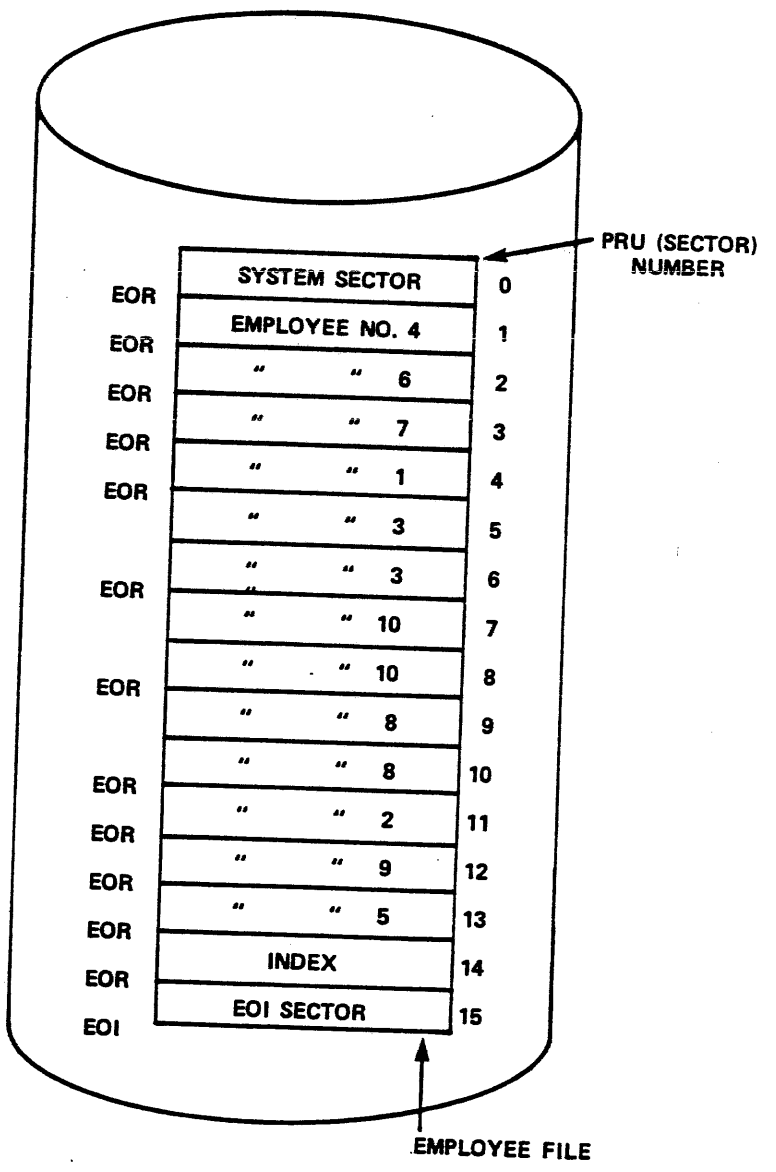
MASS STORAGE FET



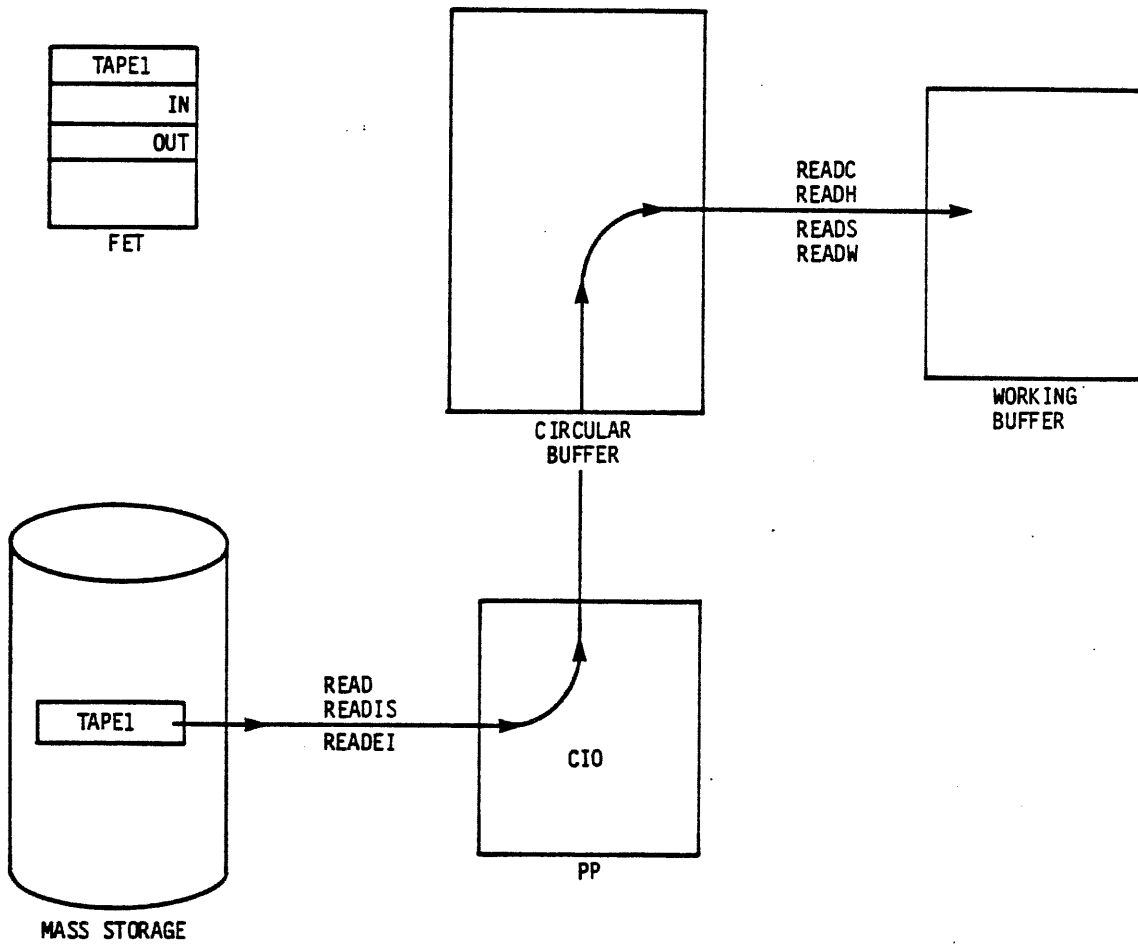
RANDOM INDEX

<u>CM WORD NUMBER</u>	
0	0
4	1
11	2
5	3
1	4
13	5
2	6
3	7
9	8
12	9
7	10

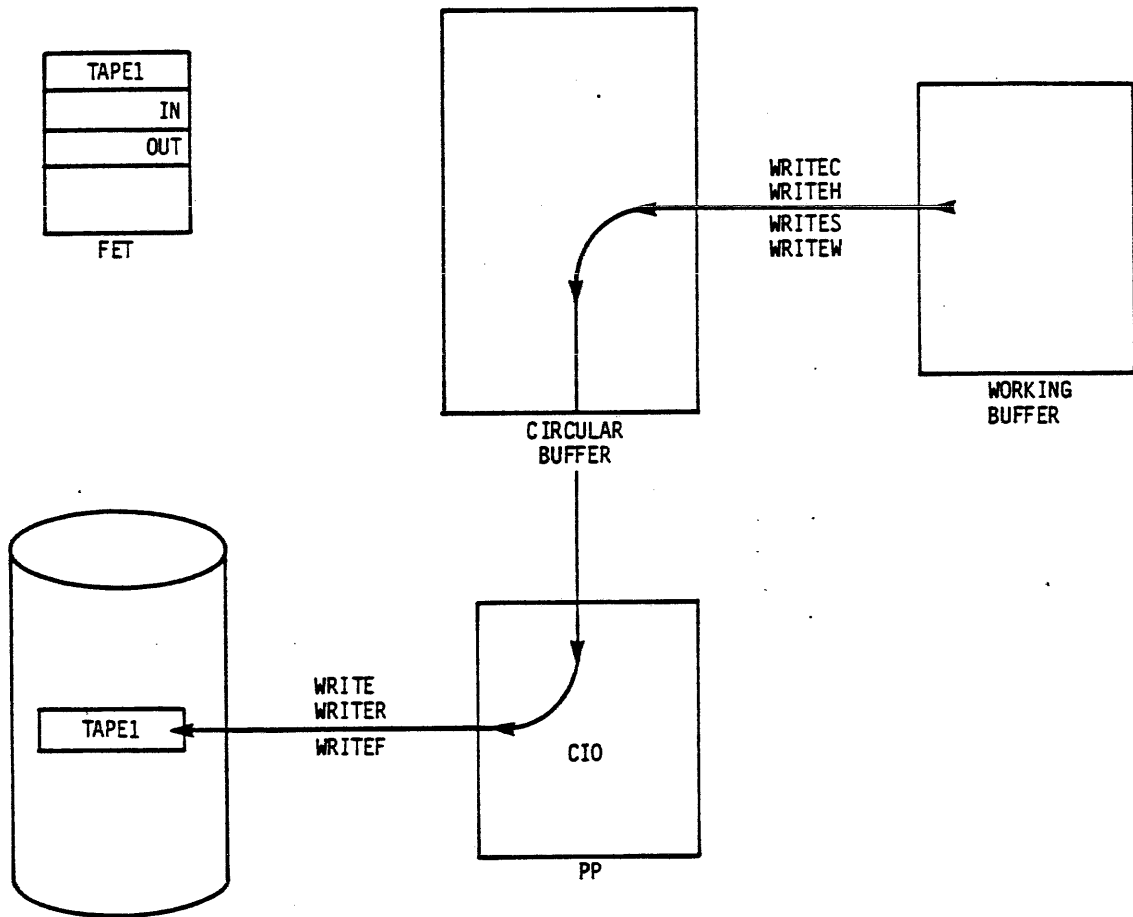
HUNDRED INDEX



DATA TRANSFER MACROS INPUT DATA FLOW



DATA TRANSFER MACROS OUTPUT DATA FLOW



QUESTION SET LESSON 12

1. If CIO gets a request to process a non-existent file, what happens?
2. Does CIO need help from any other PP routine to do mass storage input/output?
3. Explain what happens during a mass storage read/write operation.
4. How does CIO process random I/O requests? To elaborate on your previous answer, discuss what happens on a random read request.
5. Explain the term "rewrite-in-place".
6. When doing a mass storage read or write operation, CIO will terminate the operation when a termination condition is met.
What are the termination conditions for a read operation? A
write operation?
7. What does CIO do when requested to perform an operation on a magnetic tape file?
8. What does CIO do when requested to perform a read or write request on a time-sharing terminal file?

LESSON 13 DISPLAY CONSOLE DRIVERS

LESSON PREVIEW:

This lesson presents the system display console driver, DSD, and the system programmer display console driver, DIS. This lesson will cover display and syntax overlay processing used by these drivers and their sharing of the display channel.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe the interpretative syntax technique employed by DSD.
- Map the PP memory allocation for DSD.
- Discuss the technique used to load DSD overlays.
- Explain how DSD and DIS "share" the display channel.
- Describe the function of the auxiliary PP routine 1DS.

REFERENCES:

NOS IMS - Chapter 27 NOS Operator's Guide, 3, 4, 8 NOS System Programmer's Instant, 1, 2

DSD

OVERLAYS

SYNTAX
DISPLAY
COMMAND PROCESSOR

DSD (PP1)

RESIDENT SYNTAX TABLE
MASTER DISPLAY ROUTINES
RESIDENT PROGRAMS
KEY BOARD PROCESSOR
SYNTAX OR COMMAND OVERLAY
LEFT SCREEN DISPLAY ROUTINE
RIGHT SCREEN DISPLAY ROUTINE

DSD

DSD PROVIDES OVERALL SYSTEM STATUS VIA THE DISPLAY CONSOLE

ACCEPTS OPERATOR COMMANDS TO CONTROL OPERATION OF SYSTEM PERIPHERALS
AND SYSTEM PERFORMANCE

INTERPRETIVE SYNTAX TABLES

ENABLE, REMOVABLE PACKS

E SYNTAX OVERLAY FOR "E"

EN SYNTAX OVERLAY FOR "EN"

ENA B L E,

SYNTAX OVERLAY FOR "ENABLE"
REMAINING SYNTAX FILLED IN

ENABLE, R E M O V A B L E P A C K S,
REMAINING SYNTAX FILLED IN

ONCE COMMAND IS DETERMINED, THEN DSD LOADS THE PROCESSOR OVERLAY

1DL

DISPLAY OVERLAY LOADER

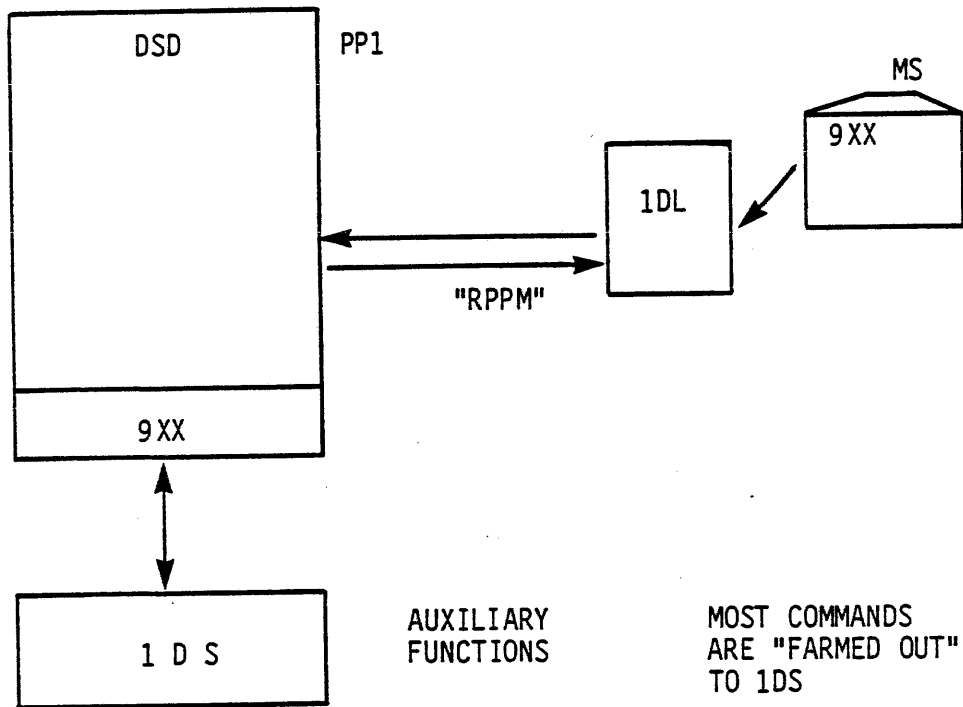
- SYSEDIT BUILDS DISPLAY OVERLAYS WITH ONLY THE FIRST ENTRY OF A GROUP

9AA . . .
9BA . . .
9CA . . .

EXCEPT FOR RCL OR ASR DISPLAY OVERLAYS

- FROM BASE OVERLAY, 1DL READS DOWN THAT TRACK CHAIN UNTIL DESIRED OVERLAY IS FOUND
- 1DL TRANSFERS THE OVERLAY TO THE REQUESTING PPU OVER A SPECIFIED CHANNEL
- 1DL MAY ALSO TRANSFER THE OVERLAY TO THE REQUESTING PPU ROUTINE USING THAT PPU'S MESSAGE BUFFER

DSD



1DS FUNCTIONS ARE FOUND IN COMMON DECK COMS1DS. ANY ROUTINE CAN USE 1DS BY PASSING THE COMMAND TO 1DS IN THE DSD/1DS COMMUNICATION BUFFER IN LOW CORE.

QUESTION SET LESSON 13

1. How and why does DSD use 1DS?
2. Map the memory allocation of the DSD PP.
3. What is meant by "interpretative syntax"?
4. How do DSD and DIS both use the display console and its channel?
5. How does DSD load its overlays?
6. How are the console displays formatted?

LESSON 14 JOB PROCESSING

LESSON PREVIEW:

This lesson describes the flow of a job through the system. The student, having developed a basic foundation of NOS in the preceding lessons, now begins to see the various system components being brought together to accomplish the processing of user jobs.

This lesson covers all aspects of the flow of a job through the system. The individual topics covered are: FNT interlocking, scheduling, job initiation and completion, rollin and rollout, control card processing, error processing, field length management, special entry point processing with emphasis on DMP= and SSJ=, and subsystem scheduling.

The scheduling, job initiation and completion, and rollin/rollout discussions are coupled with the NOS FNT interlock mechanism and cover how a job is brought to and removed from a control point.

A "rollout" is the copying of all information about a job from central memory and ECS (control point area, dayfile buffer, FNT/FST entries, and program field length (CM and ECS)) to a mass storage file called the "rollout file". A "rollin" is the copying of the information written on a rollout file to a control point (may be the same control point or different from the control point number that was vacated); restoring the control point area, dayfile buffer, FNT/FST entries, and CM and EC program field lengths. The program resumes execution with the rollout/rollin process completely transparent to the user program (with some exceptions for certain types of rollout).

"Special Entry Points" serve as flags and/or values that indicate a requirement for special processing. The special entry points, while entry points in the program in which they are assembled, are entered into the Central Library Directory (CLD) entry for the program as bits in a special entry point word rather than as individual entry points.

The field length management discussion covers the determination of the initial field length for each job step. The algorithm used to determine the initial field length for the job step, various field length related definitions, and the RFL= and MFL= special entry points are covered in detail.

The error processing discussion details the techniques available to recover from hardware/software/limit errors that may be incurred by the user's job.

The subsystem scheduling discussion presents the concept of a NOS "subsystem". The priorities and requirements of subsystems will be discussed, as well as the special operations done to schedule as the them.

The discussion of DMP= and SSJ= special entry points also covers the "special call mechanism". The operations governed by DMP= and SSJ= are quite complex because they each require the transfer of data between job steps and are often used

together in the same job step (program). The DMP= entry point causes the previous program field length to be written on a file called "DM*" in a manner similar to the rollout file (except field length is not written in a reverse order). This allows the control point's field length to be used by another CPU program transparent to the user program. The system uses this technique to take advantage of system features available to CPU programs to do system related tasks. The SSJ= entry point causes a block of user validation data to be retrieved from the control point area when the program is loaded and replaced in the control point area when the program terminates. The data being manipulated are words UIDW, ALMW, ACLW, and AACW. SSJ= also carries with it certain permissions for which particular system imposed constraints and validations may be overridden; and the capability of setting time limit, CPU and Queue Priorities for the job step. The special call mechanism uses control point area word SPCW to make a request for executing a CPU program in the control point's field length and then returning to the original program. The SPCW mechanism is available only to a PP program but may be triggered by a user program making a RA+1 request, which is then processed by SFP.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Detail the major steps in processing a user's job from its entry into the input queue to the disposal of its output from the output queue.
- Describe in detail the Job Control Block (JCB), what each field means, and how the block is entered with data.
- Explain the concept of "priority aging" and how it is accomplished in NOS.
- Explain how the scheduler (either 1SJ or 1SP) is called into execution.
- Describe the selection criteria for identifying a candidate job to be brought to a control point for subsequent execution, and what technique 1SJ uses to accomplish bringing the candidate to a control point.
- Describe the selection criteria for choosing the control point for the candidate job.
- Identify the various tables used by the scheduler in order to select the candidate job.
- Describe the selection process by major subroutines in the scheduler (1SJ) and the priority evaluator (1SP).
- Explain who determines if a job's CM or CPU time slices have expired and what is done when these values are exceeded.
- Discuss the various mechanisms by which a job may be introduced to the system (i.e., entered into the input queue).
- Describe how NOS determines the name of a job.

- Describe the initialization of the control point area by 1AJ overlay 3AA (Begin Job) when a job is brought to a control point to begin its execution from the input queue.
- Identify the special entry points processed by NOS and what each entry point indicates.
- Describe the CLD entry of a routine with special entry points.
- List the steps involved in processing a control statement.
- Describe the differences between operating system argument processing and product set argument processing.
- Identify steps in the control statement processing where the processing may be altered due to the presence of a special entry point.
- Discuss the loading of programs (both absolutes and relocatables).
- Define the terms: SYSMAX, MAXFL, MFL, RFL, NFL and SYSDEF.
- Describe the initial field length selection process for central memory and for user access ECS.
- Explain the use of the RFL= and MFL= special entry points and the *FL LIBDECK value in field length management.
- Compute a program's initial field length when given the current field length, the contents of FLCW and the program's CLD entry.
- Discuss the job clean-up operations performed by routine 1CJ (Complete Job).
- Discuss extended reprieve, reprieve, and EREXIT processing.
- Describe what happens when a program is aborted due to an error. This discussion should include the function of 1AJ overlay 3AB (Error Processor), file flushing, list of files, and so forth.
- Identify the contents of the rollout file and its system sector.
- Describe the rolling mechanism between mass storage and central memory.
- Describe the DMP= entry point value, detailing the options that may be specified by it.
- Describe the DMP= process when that process is required due to a control statement request from a program that has a DMP=entry point.
- Describe the DMP= process when that process is required due to a SPCW request from a PP program that had been called by a user program RA+1 request.
- Describe the SSJ= entry point value, detailing the options that may be specified by it.

- Describe the SSJ= process, what data is transferred, how priorities and time limit may be specified, and what processing is done at the end of a job step for files created by the SSJ= job step.
- Discuss the processing done when a program combines DMP= and SSJ=processing.
- List the characteristics of a subsystem.
- Explain the queue priority relationship for a subsystem.
- Identify the NOS subsystems, their queue priorities, and any control point requirements.
- Discuss the mechanism by which subsystems are scheduled, detailing the use of the SSCL and SSTL words of CMR and the building of the FNT/FST input queue entry for the subsystem initialization routine by IDS.

REFERENCES:

NOS IMS - Chapter 5, 6 and 35 NOS RM, 1-2, 1-3, 1-5, 1-6 NOS RM, 2-6, 2-10, 2-F
NOS SMRM, 6-5 NOS IHB, 8-5

SUPPLEMENTAL TEXT: FNT INTERLOCKING

The interlocking of a FNT entry provides protection from alteration or processing by another routine while that entry is currently being manipulated. The concepts involved in interlocking an FNT entry include protecting the job while it is moving from one job state to another (transition state), protecting queue entries, and guaranteeing that the FNT is not being accessed simultaneously.

Individual FNT Interlock

Interlocking an individual FNT entry is done by the SFIM monitor function. This function sets or clears an interlock bit in the "FNT Interlock Table" for a particular FNT entry. The individual interlock technique is used in the following circumstances:

- Bringing an input file into execution
- Performing a job advance
- Rolling in or rolling out a job
- Terminating a job
- Altering the FNT or system sector of a queued file
- Moving a file from one queue to another
- Assigning a queue file to a control point

Global FNT Interlock

The FNT may be globally interlocked by the reservation of the FNT pseudo-channel FNCT. The use of this mechanism is to avoid conflicts which may occur when more than one system routine attempts to update the FST entry of a queued file. The global interlock is only used when the contents of queued file FSTs are to be altered. As the priority evaluation scheme is disabled by this interlock, it should be used with caution.

In cases where the individual FNT interlock (SFIM) and global interlock (FNCT) are both required, the SFIM interlock should be obtained first. This order must be maintained to avoid deadlock situations.

An example of where the FNCT interlock is used is the DSD command ENQP. ISP is periodically called to do queue priority evaluation and will update the priority field in queued file FSTs. DSD will update the priority field when performing the ENQP command. If both DSD and ISP tried to update the same FST, a conflict would occur. DSD performs the following sequence to avoid the possibility of making a conflicting ENQP entry. First, the desired FNT is interlocked via SFIM. Then the entire FNT is interlocked by DSD reserving the FNCT pseudo-channel. When DSD completes, it drops the FNCT pseudo-channel and then clears the SFIM interlock.

FNT Entry Interlock

The FNT is also globally interlocked by those system routines making new FNT entries by the reservation of the FNT Entry pseudo- channel FECT. This mechanism guarantees that a system routine may determine when and where within the FNT to write a FNT/FST entry without being disturbed by another system routine making FNT/FST entries.

An example of the use of the FECT interlock mechanism is found in routine OBF. OBF obtains the FECT interlock by reserving the FECT pseudo-channel. It then scans the FNT for an empty position. OBF writes the new entry at this position and then drops the pseudo- channel, clearing the interlock.

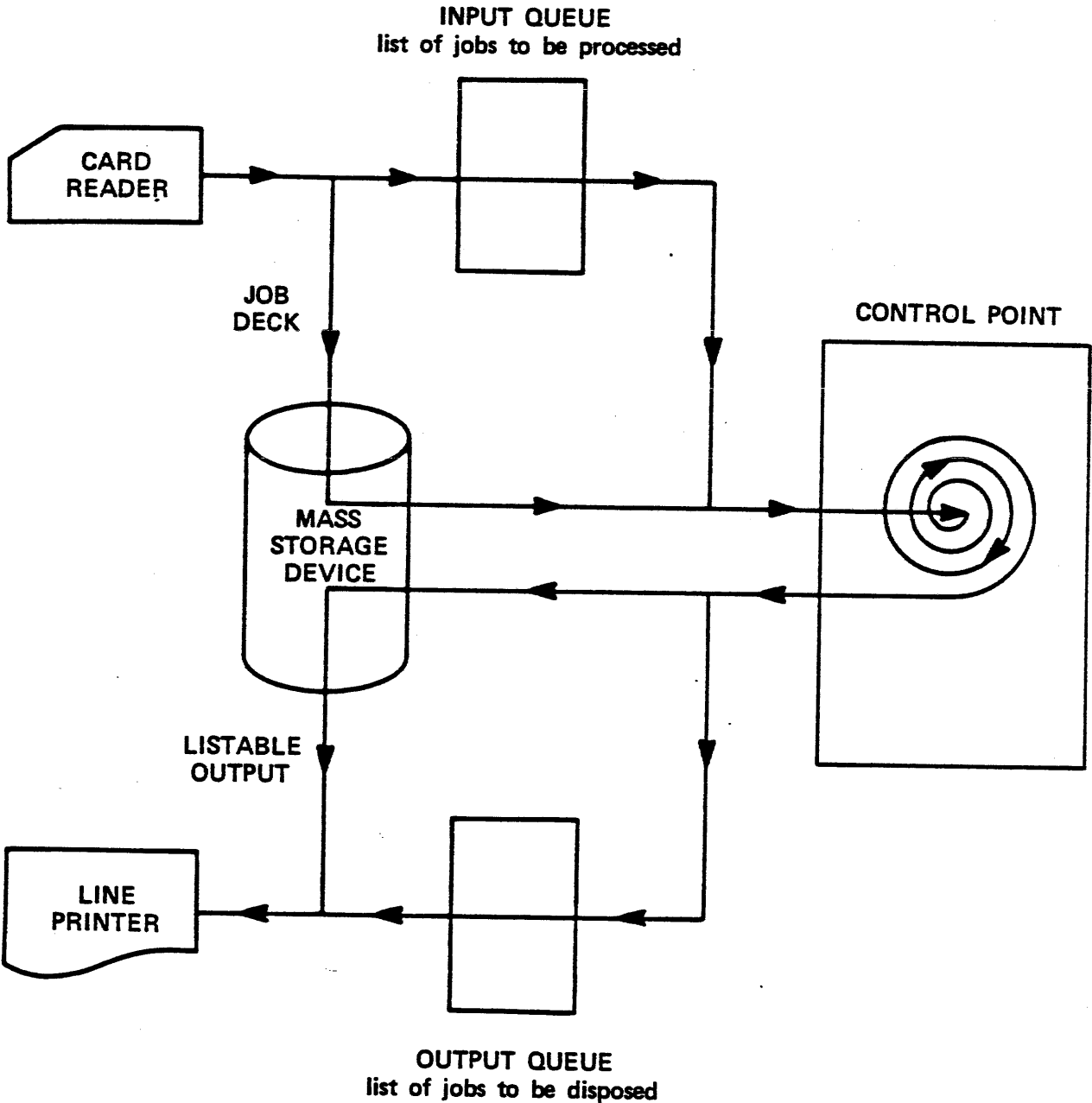
Job Advancement

The individual FNT interlock must be not set on the job's input file in order for the job to be advanced. The job advancement process will automatically set the FNT interlock on the job's input file to indicate that it is in a transition state. Thus, the FNT interlock will always be set for a job if the job advancement flag is set; the converse of this is not true, however. The issuance of the JACM monitor function by the system routines involved in the job advancement process (1AJ, 1RO, 1CJ) will clear the FNT interlock when the job advance flag is cleared. The job advancement process sets the interlock for the FNT/FST position pointed to by control point word TFSW.

Transition State Scheduling

In order to properly control transition state activity, it is necessary to set the FNT interlock on the queued file or input/ rollout file being manipulated before any transition activity may take place. With this structure, system routines are able to identify when transition states are completed by the successful issuance of their own FNT interlock (SFIM) request. This in turn prohibits a transition state from occurring while they perform their specified function on that job or queued file.

GENERAL SYSTEM FLOW



JOB ENTERS SYSTEM

JOB SCHEDULED FOR EXECUTION

JOB BEGINS EXECUTION

CONTROL STATEMENTS PROCESSED

JOB ROLLS OUT

JOB SCHEDULED TO RESUME EXECUTION

JOB ROLLS IN

...

JOB COMPLETES

OUTPUT PROCESSED

1. ISP PERIODICALLY EVALUATES QP-ADVANCES QP

2. 1SJ SCHEDULES JOB FROM INPUT QUEUE

3. 1SJ CALLS 1AJ TO BEGIN JOB

4. CPUMTR CALLS 1AJ TO ADVANCE JOB

- JACM

5. 1SP EVALUATES QP.

1SP EVALUATES CPU TIME SLICE AND CM SLICE. IF EITHER HAS EXPIRED, JOB'S QP IS SET TO THE JOB ORIGIN LOWER BOUND FOR TYPE (INPUT OR ROLLOUT).

6. 1RO ROLLS OUT JOB

THE JOB INPUT FNT/FST ENTRY POINTED TO BY TFSW WILL BECOME THE FNT/FST ENTRY FOR THE ROLLOUT FILE. DURING THE "TRANSITION STATE" THE FNT INTERLOCK HAS BEEN SET ON THIS ENTRY VIA SFIM.

7. 1SJ (CALLED BY 1SP OR CPUMTR) SCHEDULES THE JOB TO BE ROLLED IN FROM THE ROLLOUT QUEUE. THE FNT/FST ENTRY IS INTERLOCKED VIA SFIM DURING THIS TRANSITION STATE.

8. 1RI ROLLS IN THE JOB.

THE JOB GETS A FRESH CPU TIME SLICE AND CM SLICE. ROLLOUT FNT/FST ENTRY IS REPLACED BY THE INPUT FNT/FST ENTRY. THE FNT INTERLOCK IS RELEASED WHEN THE JOB IS READY TO RESUME EXECUTION.

9. WHEN 1AJ DETECTS THE END OF CONTROL STATEMENTS OR DETECTS A FATAL ERROR CONDITION, IT CALLS 1CJ TO COMPLETE THE JOB.
10. 1CJ RETURNS ALL FILES, DISPOSES OUTPUT FILES TO OUTPUT QUEUES WITH JOBNAME AND PRFT/PHFT, DOES JOB ACCOUNTING, APPENDS DAYFILE TO OUTPUT FILE.
11. OUTPUT IS RETRIEVED FROM OUTPUT QUEUES BASED ON THE ROUTING INFORMATION. THIS OPERATION IS USUALLY PERFORMED BY QAC.
12. 1SP EVALUATES QP FOR OUTPUT FILES...

FNT INTERLOCKING

INDIVIDUAL ENTRY INT ERLOCK

- SFIM MONITOR FUNCTION
- TRANSITION STATES
 - BRING JOB INTO EXECUTION
 - JOB ADVANCE
 - ROLLING IN OR OUT A JOB
 - JOB TERMINATION
 - ALTERING FNT OR SYSTEM SECTOR OF QUEUED FILE
 - MOVING FILE FROM ONE QUEUE TO ANOTHER
 - ASSIGNING QUEUE FILE TO CONTROL POINT

GLOBAL INTERLOCK (CHANNEL 15)

- FNCT PSEUDO-CHANNEL

FNT ENTRY INTERLOCK (CHANNEL 14)

- FECT PSEUDO-CHANNEL

SCHEDULING

JOB CONTROL BLOCK (JCB)

ONE BLOCK FOR EACH ORIGIN/CLASS.

1. QUEUE CONTROL QUEUE CONSOLE OR IPRDECK ENTRY

FIRST 3 WORDS OF JCB ARE USED FOR JOB AGING - IN INPUT, ROLLOUT AND OUTPUT QUEUES.

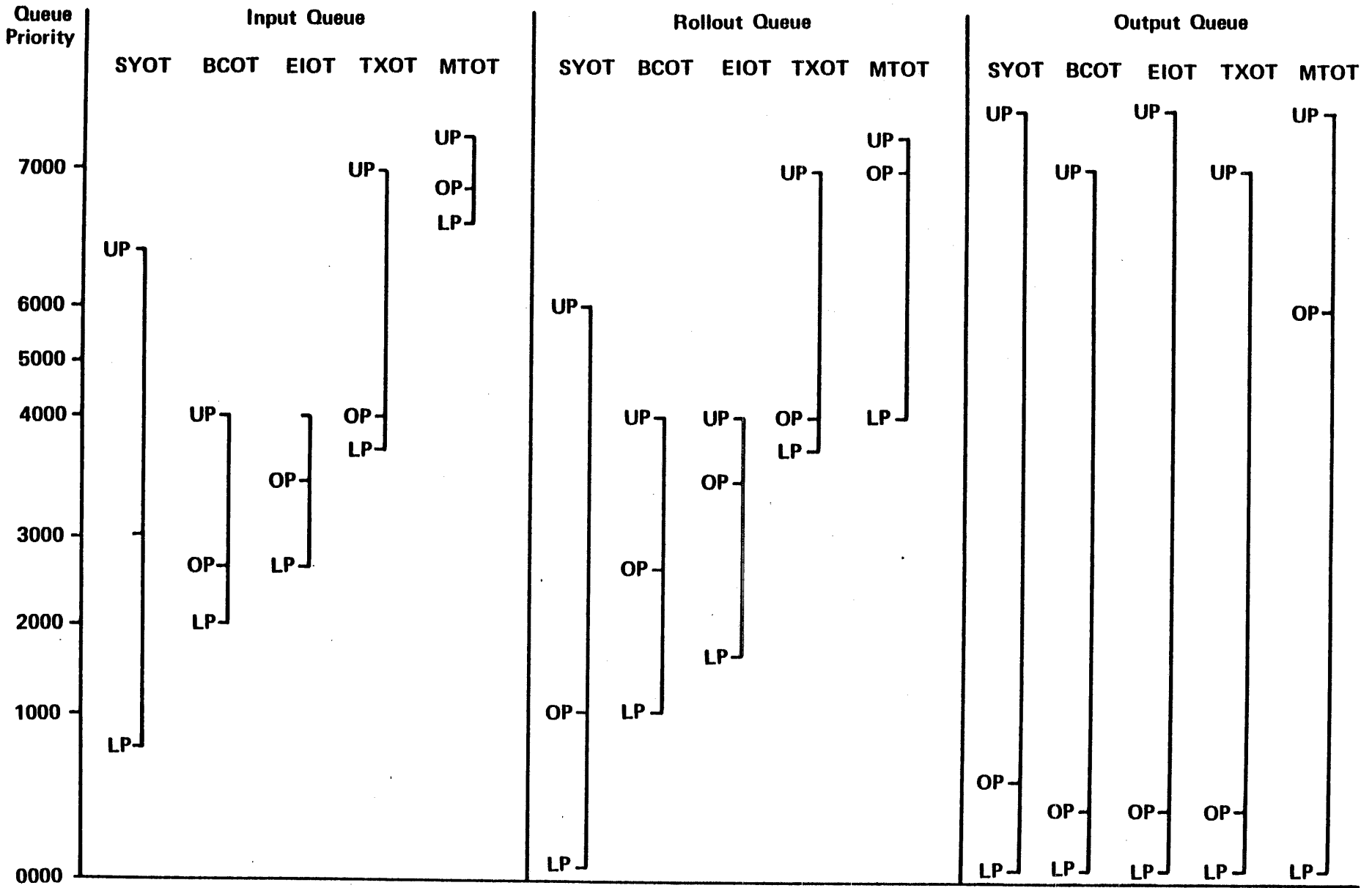
BYTE 0 - ORIGINAL (ENTRY) QUEUE PRIORITY (OP)
BYTE 1 - LOWER BOUND FOR QUEUE PRIORITY (LP)
BYTE 2 - UPPER BOUND FOR QUEUE PRIORITY (UP)
BYTE 3 - PRIORITY INCREMENT (IN)
BYTE 4 - INCREMENT INTERVAL COUNT

OP	LP	UP	IN	COUNT
----	----	----	----	-------

JOB PRIORITY MUST BE BETWEEN LP AND UP TO BE AGED IN THE QUEUE.

EACH TIME 1SP CYCLES THROUGH THE QUEUES, BYTE 4 IS ADVANCED BY ONE. IF BYTE 3 = BYTE 4, THE QP FOR ALL JOBS OF THIS QUEUE AND ORIGIN TYPE IS INCREMENTED BY 1, BYTE 4 IS CLEARED.

THE QUEUE CONTROL MECHANISM ALLOWS A SITE TO GIVE PREFERRED TREATMENT TO JOBS OF A CERTAIN ORIGIN.



SCHEDULING

JOB CONTROL BLOCK (JCB)

2. CONTROL POINT CONTROL SERVICE CONSOLE OR IPRDECK ENTRY

FOURTH WORD OF JCB CONTROLS A JOB WHILE AT A CP (BY ORIGIN)

BYTE 0 - INITIAL CPU PRIORITY SET AT START OF JOB OR LOGIN (PR)
BYTE 1 - CPU TIME SLICE IN MILLESECS/64₁₀(CP)
BYTE 2 - CM TIME SLICE IN SECONDS (CM)

PR	CP	CM		
----	----	----	--	--

JOB LEAVES CM BECAUSE:

- COMPLETES OR ABORTS
- TERMINAL INPUT/OUTPUT IS REQUIRED
- CM IS NEEDED BY A HIGHER PRIORITY JOB (KEEPS JOB FROM MONOPOLIZING CM)

SIMILAR LOGIC IS FOLLOWED FOR THE CPU.

A JOB REMAINS IN CM AND MAY USE THE CPU UNTIL/UNLESS A HIGHER PRIORITY JOB NEEDS THE MEMORY OF THE CPU.

SCHEDULING

JOB CONTROL BLOCK (JCB)

3. MEMORY CONTROL SERVICE CONSOLE OR IPRDECK ENTRY

FIFTH WORD IN JCB HAS MAXIMUM MEMORY ALLOWED FOR JOBS WITHIN THE JOB ORIGIN.

- BYTE 0 - MAXIMUM NUMBER OF JOBS (NJ)
- BYTE 1 - MAXIMUM FL/100 FOR ANY JOB (FL)
- BYTE 2 - MAXIMUM FL/100 FOR ALL JOBS (AM)
- BYTE 3 - MAXIMUM ECS FL FOR JOB (EC)
- BYTE 4 - MAXIMUM ECS FL FOR ALL JOBS (EM)

NJ	FL	AM	EC	EM
----	----	----	----	----

FL/EC AND AM/EM ARE IGNORED WHEN SYSTEM IS IDLE. THE SCHEDULAR WILL ATTEMPT TO KEEP THE SYSTEM "BUSY" REGARDLESS OF FL/EC AND AM/EM.

SCHEDULING

JOB SELECTION

1. HIGHEST PRIORITY (QP) JOB THAT FITS INTO UNASSIGNED OR AVAILABLE MEMORY WITHIN SERVICE CONSTRAINTS (FL/AM, EC/EM) FOR THE CANDIDATE'S ORIGIN TYPE.
2. EQUAL CANDIDATES - SELECT JOB ON THE MASS STORAGE DEVICE WITH LEAST ACTIVITY
 - NO FREE CHANNEL
 - CHANNEL REQUESTED MS ACTIVITY
 - FIRST UNIT RESERVED
3. MS ACTIVITY EQUAL - SELECT JOB WITH LARGEST FL.
4. IF NO JOB WAS SELECTED BUT ONE WAS REJECTED BECAUSE OF SERVICE CONSTRAINTS, IT WILL BE SELECTED IF NO JOBS HAVE TO BE ROLLED OUT FOR IT TO FIT. ITS QP WILL BE SET AT THE ORIGIN'S LOWER BOUND.

THIS STEP PREVENTS THE SYSTEM FROM SITTING IDLE DURING PERIODS OF LOW ACTIVITY.

SCHEDULING

CONTROL POINT SELECTION

1. CONSIDER A CONTROL POINT'S FIELD LENGTH TO BE ALL THE FL OF UNOCCUPIED CPs FOLLOWING THE CANDIDATE. THE SELECTION ORDER IS -
 - EXACT FIX
 - SMALLEST HOLE THAT IS LARGER THAN NEEDED
 - LARGEST HOLE IF NONE IS BIG ENOUGH
 - IF NO CPs ARE AVAILABLE OR ROLLING OUT, THE FIRST CP ENCOUNTERED WITH A LOWER QUEUE PRIORITY (QP) IS SELECTED TO BE ROLLED OUT. IF ALL CPs HAVE A HIGHER QP, NONE IS SELECTED.
2. FL IS OBTAINED BASED ON THE CP SELECTED. THE ABOVE SEQUENCE IS SUCH THAT THE CP SELECTED REQUIRES THE MINIMUM AMOUNT OF STORAGE MOVEMENT.

SCHEDULING

1SJ

TABLES

TACP ACTIVE CONTROL POINTS
IN DESCENDING PRIORITY



RI=ROLLOUT IN PROGRESS
RR=ROLLOUT REQUESTED

TRST ROLLOUT STATUS INDEXED
BY CONTROL POINT NUMBER



TJFL JOB FIELD LENGTH
INDEXED BY CONTROL POINT NUMBER



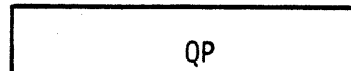
BYTE 4 OF STSW

TJEC JOB ECS FIELD LENGTH
INDEXED BY CONTROL POINT NUMBER



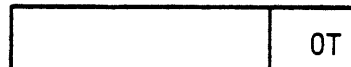
BYTE 4 OF ECSW

TJPR JOB PRIORITY INDEXED BY
CONTROL POINT NUMBER



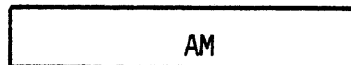
BYTE 1 OF JCIW

TJOT JOB ORIGIN TYPE INDEXED
BY CONTROL POINT NUMBER



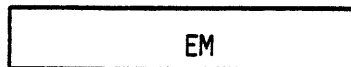
RIGHT 6 BITS
OF BYTE 3 JNMW

TMFO TOTAL AVAILABLE FIELD LENGTH
FOR ALL JOBS OF AN ORIGIN TYPE
(INDEXED BY ORIGIN TYPE)



AM SERVICE VALUE

TMEO TOTAL AVAILABLE ECS FIELD LENGTH
FOR ALL JOBS OF AN ORIGIN TYPE
(INDEXED BY ORIGIN TYPE)



EM SERVICE VALUE

SCHEDULING (Continued)

TAFO	ASSIGNED FIELD LENGTH BY ORIGIN TYPE (INDEXED BY ORIGIN TYPE)	AFL
TAE0	ASSIGNED ECS FIELD LENGTH BY ORIGIN TYPE (INDEXED BY ORIGIN TYPE)	AEC

SCHEDULING

1SJ	TABLES		
TMJO	MAXIMUM FIELD LENGTH PER JOB BY ORIGIN (INDEXED BY ORIGIN TYPE)	<table border="1"><tr><td>FL</td></tr></table> FL SERVICE VALUE	FL
FL			
TMXO	MAXIMUM ECS FIELD LENGTH PER JOB BY ORIGIN TYPE (INDEXED BY ORIGIN TYPE)	<table border="1"><tr><td>EC</td></tr></table> EC SERVICE VALUE	EC
EC			
CSTB	CHANNEL STATUS TABLE	EXACT COPY OF CITL FROM LOW CORE CMR	
DACT	DEVICE ACTIVITY COUNT, INDEXED BY EQUIPMENT NUMBER	COUNT= NO FREE CHANNEL + CHANNEL REQUEST + FIRST UNIT RESERVE	
ESTB	EST - MASS STORAGE ENTRIES	COPY OF EST ENTRY	

SCHEDULING

1SJ SUBROUTINES

- SET CONTROL POINT STATUS SCS
BUILDS TACP, TJFL, TRST, TJOT, TJPR, TAFD,
TJEC, TAE0
- SET JOB CONTROL SJC
BUILDS TMJO, TMFO, TMX0, TME0
- DETERMINE DISK ACTIVITY DDA
BUILDS CSTB, DACT, ESTB,
CSTB AND ESTB ARE USED ONLY TO BUILD
THE DACT.
- SEARCH FOR JOB SFJ
CHOOSES BEST CANDIDATE. IF NO JOB
CHOSEN ON FIRST PASS, SETS TMJO/TMX0
AND TMFO/TME0 TO UNLIMITED, DISALLOWS
ROLLOUT, AND MAKES A SECOND PASS.
- COMMIT FIELD LENGTH CFL
SELECTS JOBS NEEDED TO BE ROLLED OUT
TO OBTAIN DESIRED AMOUNT OF MEMORY.
JOBS OF SAME ORIGIN ARE ROLLED BEFORE
JOBS OF DIFFERENT ORIGINS.
- COMMIT CONTROL POINT CCP
SELECTS CONTROL POINT FOR THE JOB.
- ASSIGN JOB ASJ
REQUEST STORAGE, SET JNMW, TFSW, JCIW,
TSCW AND CALLS 1AJ or 1RI (INTO THIS PP IS
ANOTHER IS NOT AVAILABLE)

SCHEDULING

1SP

WHAT 1SP DOES (BY SUBROUTINE)

- ADJUST JOB PRIORITIES
CM AND CPU TIME SLICE EVALUATION
USER ECS DISABLED AJP

- ADVANCE TIME INCREMENT
ADDS TO BYTE 4 OF QUEUE CONTROL WORDS. IF
BYTE 3 = BYTE 4, CLEARS BYTE 4. THIS IS THE
FLAG USED TO DETERMINE WHETHER TO ADVANCE QA. ATI

- ADJUST FILE PRIORITIES
IF BYTE 4 OF QUEUE CONTROL FOR QUEUE TYPE
AND JOB ORIGIN IS 0, ADD ONE TO QP IN FST ENTRY. AFP

- CHECK EVENT TABLE
IF EVENT HAS OCCURRED FOR TIMED/EVENT
ROLLOUT FILES, THEY ARE MADE READY FOR
SCHEDULING (QP = UP) AND EVENT TABLE
CLEARED. READS SYSTEM SECTOR TO RESET
FST ENTRY. CET

- CHECK MASS STORAGE
CALLS CMS TO RECOVER REMOVABLE DEVICES,
CALLS 2SP TO POST MASS STORAGE ERRORS,
AND SO FORTH. CMS

SCHEDULING

1SP

- CHECK DEVICE CHECKPOINT
CALLS 1CK IF CHECKPOINT BIT SET IN
MST FOR A MS DEVICE
- PROCESS ACCUMULATOR OVERFLOW
CALLS OAU TO PROCESS SRU ACCUMULATOR
OVERFLOW

CDV

POF

SCHEDULING

CPU OR CM SLICE EXCEEDED

1. QUEUE PRIORITY SET TO LOWER BOUND FOR INPUT OR ROLLOUT FOR THE ORIGIN TYPE.
JOB DOES NOT AUTOMATICALLY GIVE UP CM OR CPU WHEN SLICE EXPIRES.
2. ANY JOB OF HIGHER PRIORITY WILL FORCE JOB OUT OF CPU OR OUT OF CM (ROLLED OUT)
3. JOB AGES IN ROLLOUT QUEUE UNTIL IT BECOMES A CANDIDATE FOR SCHEDULING. AGING WILL OCCUR ONLY IF JOB'S ROLLOUT QP IS WITHIN LP→UP RANGE.
4. WHEN ROLLED BACK IN, JOB IS GIVEN A QP EQUAL TO HIGHER OF THE OP AND UP AND GIVEN FRESH CM AND CPU TIME SLICES.

AUTOROLL.

ENABLES/DISABLES THE AUTOMATIC ROLLOUT OF JOBS SO JOB MAY BE SCHEDULED FROM INPUT OR ROLLOUT QUEUE.

PRIORITY.

ENABLES/DISABLES THE AGING OF THE QUEUE PRIORITY.

INPUT FILE

LOCAL BATCH
 REMOTE BATCH
 SUBMIT
 QUEUE LOADING

OVJ - VERIFY JOB/USER STATEMENT

- CRACK AND VALIDATE JOB CARD PARAMETERS
- INITIALIZE INPUT FILE SYSTEM SECTOR
- CRACK AND VALIDATE USER CARD PARAMETERS
- GENERATE JOB HASH
- RESULTS RETURNED FOR PROCESSING BY CALLING PROGRAM

MASS STORAGE ASSIGNMENT, SYSTEM SECTOR COMPLETED, AND FILE RELEASED TO INPUT QUEUE BY PROCESSING ROUTINE

DSP
 QFM
 VEJ
 QAP
 XSP

JOB NAME				ORIGIN	INFT	1	0
ID	EQ	FIRST TRACK	ERROR CONTROL	FL	QP		

USER INDEX HASH

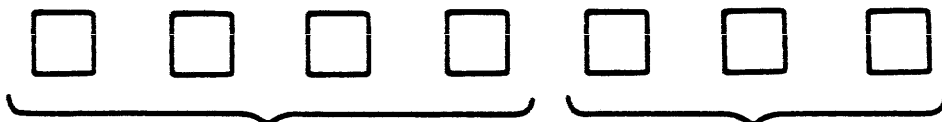
GBN - GENERATE BANNER NAME

ALGORITHM:

1. PAD USER INDEX WITH 3 ZERO BITS ON RIGHT
2. SPLIT INTO 4 GROUPS OF 5 BITS
3. ADD 1 TO EACH GROUP, GIVING DISPLAY CHARACTER

2061	=	00 000	010	000	110	001	000	
		00000	01000		01100		01000	
		0+1=1	10+1=11		14+1=15		10+1=11	
		A	I		M		I	
123456=		01	010	011	10	101	110	000
		10100		01110		01011		10000
		12+1=13		16+1=17		13+1=4		20+1=21
		K		O		L		Q

JOB NAME



USER INDEX
HASH

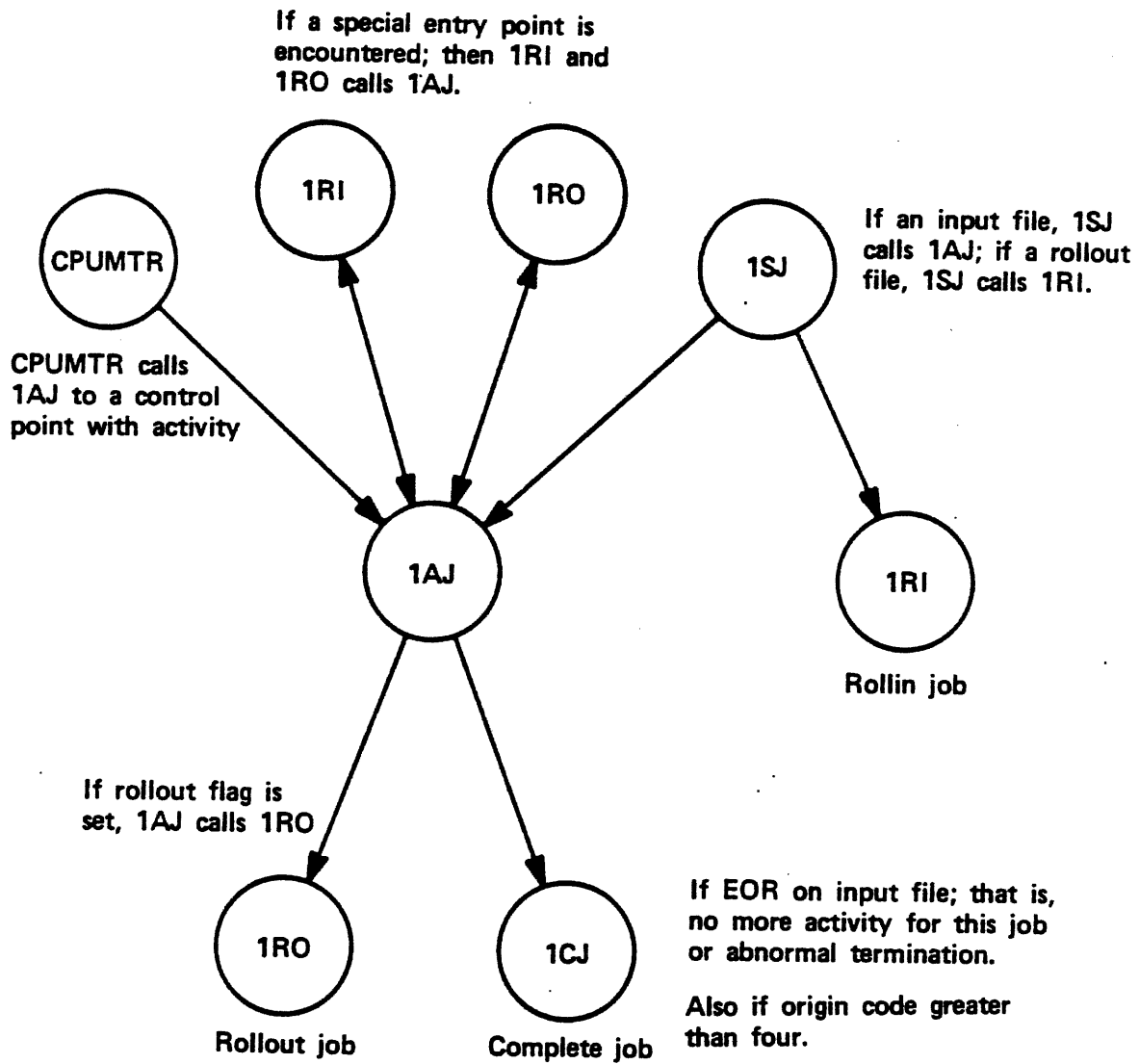
1. IF TIME-SHARING JOB,
TERMINAL NUMBER (OCTAL)
IN DISPLAY CODE
2. NOT-TIME-SHARING JOB,
LOWER 3 LETTERS OF
JOB SEQUENCE NUMBER
(RJSM)

A I M I 1 2 3

USER: TURKEY, TROT

(UI= 2061)

TERMINAL: 123,TTY



JOB BEGINS EXECUTION (1AJ/3AA)

1. CLEAR CONTROL POINT AREA FROM CPCW TO END, EXCEPT FOR ECSW.
2. SET DEFAULT SRU AND TIME LIMITS IN CPTW AND STLW.
3. READ JOB CONTROL STATEMENTS INTO CSBW AREA AND SET CSPW AND CSSW. (INPUT FILE POSITIONED AT EOR).
4. SET TRACK/SECTOR INFORMATION INTO INPUT FILE FST.
5. SET INPUT FILE FST ADDRESS INTO TFSW.
6. SET CONTROL POINT AREA FIELDS:

KEYPUNCH MODE IN SNSW
JOB SEQUENCE NUMBER (FROM SS) IN RFCW
EXIT MODE (EEMC) INTO XP
PERMANENT FILE DEFAULT FAMILY IN PFCW
ADVANCE FAMILY ACTIVITY COUNT
FIELD LENGTH CONTROL IN FLCW AND ELCW
DEFAULT VALIDATION IN ALMW, ACLW, AACW
VALIDATION REQUIRED IN UIDW
SRU DEFAULTS VIA ABBF/ACTM
TIME LIMIT (FROM SS) INTO STLW
ISSUE JOB CARD TO DAYFILE
ISSUE CARDS READ ACCOUNTING MESSAGE (UCCR)

JOB BEGINS EXECUTION (1AJ/3AA)

7. CHECKS ERRORS

- JOB CARD ERROR
- JOB IN NORERUN STATE ON RECOVERY
- BINARY CARD SEQUENCE ERROR

8. ADVANCE TO NEXT JOB STEP

EXECUTE TCS

TRANSLATE CONTROL STATEMENT (TCS)

1. READ STATEMENT

- CONTROL STATEMENT BUFFER
- MS1W (DIS)
- JOB'S FL (TCS.RA+1 CALL)

2. FIND KEYWORD

3. SEARCH FOR PROGRAM

- INTERNAL TO TCS CTIME/RTIME/STIME/HTIME
- LOCAL FILE (\$ = IGNORE)
- CLD
- PLD

VAL =

4. MANAGE MEMORY

RFL =

MFL =

5. LOAD PROGRAM

- ABS - DIRECTLY INTO FL
- RELOCATABLE - CYBER LOADER

SDM =

6. ISSUE STATEMENT TO DAYFILE

7. UPDATE CSPW (IF NECESSARY)

8. ADVANCE JOB (JACM) DROP PP (DPPM) (RA+1 CALL)

PROGRAM LOADING

- ABSOLUTES AND OVERLAYS
- RELOCATABLES

1. PROGRAM NAME (KEYWORD) IDENTIFIED
2. STORAGE REQUESTED
3. LOAD PROGRAM (LDR/3AE)

- ABSOLUTES OR OVERLAYS

- IF NO MASS STORAGE, THE PROGRAM IS READ FROM SYSTEM LIBRARY OR LOCAL FILE DIRECTLY INTO THE CONTROL POINT FIELD LENGTH. THIS LOAD IS CHARGED THE NUMBER OF SECTORS TRANSFERRED AND A DEFAULT LOAD CHARGE.
- IF IN CM OR ON ECS (ECS IS AN ASR), THE PROGRAM IS TRANSFERRED INTO THE CONTROL POINT FIELD LENGTH BY THE LCEM MONITOR FUNCTION.
- IF SYSEDT IS ACTIVE, THE PROGRAM WILL BE LOADED FROM MASS STORAGE.
- IF AN ECS ERROR OCCURS, THE ASR RESIDENCY FOR THE ROUTINE IS CLEARED AND ANOTHER SOURCE (MASS STORAGE) IS USED TO LOAD THE PROGRAM.

PROGRAM LOADING

- RELOCATABLES

- IF THE PROGRAM IS A RELOCATABLE, THE CYBER LOADER (AN ABSOLUTE) IS LOADED. THE CYBER LOADER WILL THEN LOAD THE RELOCATABLE.

4. EXCHANGE PACKAGE IS SET UP.
5. PRIVATE FILES RETURNED (PRIVACY FLAG CLEARED)
6. ARGUMENTS PASSED IN RA+ARGR THRU RA+63
7. CLEAR MEMORY CSTM
8. START JOB STEP RLJS/RLMM

ARG =

ARGUMENT PROCESSING

- | PRODUCT SET | OPERATING SYSTEM |
|----------------|-------------------------------|
| ● LOACL FILES | ● CLD DEFAULT |
| ● CLD WITH *SC | ● LOCAL FILES WITH "/" PREFIX |

PARAMETER	ID
-----------	----

ID=		ID= SEPARATOR CHARACTER
1	,	= 0 IF TERMINATOR OR COMMA
2	=	
3	≠	
4	(
5	+	
6	-	
7	SPACE	
10	;	
17	TERMINATOR:) OR.	

ARGUMENTS ARE PROCESSED ONLY IF ARG= IS NOT SPECIFIED.

TCS MACROS

USER PROGRAM MAY CALL TCS DIRECTLY VIA A RA+1 REQUEST

THE MACROS

CONTROL
EXCST

ALLOW THE USER TO READ THE NEXT CONTROL STATEMENT FROM THE CONTROL CARD BUFFER AND ALLOW THE USER TO GIVE THE SYSTEM A CONTROL STATEMENT TO BE EXECUTED AS THE NEXT STATEMENT TO BE PROCESSED.

THIS ALLOWS A USER PROGRAM TO "READ AHEAD" DOING ALL SUBSEQUENT CONTROL STATEMENTS IT CAN PROCESS.

THIS ALSO ALLOWS A USER PROGRAM TO EXECUTE ANOTHER ROUTINE BEFORE REENTERING THE CONTROL CARD STREAM.

FIELD LENGTH MANAGEMENT

SYSMAX MAXIMUM FL CURRENTLY AVAILABLE FOR ANY JOB (BY ORIGIN)
BCOT/EIOT/SYOT:
 $SYSMAX = MACHINE\ SIZE - CMR\ SIZE - K$
TXOT/MTOT
 $SYSMAX = MACHINE\ SIZE - CMR\ SIZE - TK$
 $TK = K + TIME\ SHARING\ EXECUTIVE\ FL$

MAXFL MAXIMUM FIELD LENGTH THE JOB MAY EVER ATTAIN (BY ORIGIN)
 MIN { JOB CARD CM, VALIDATION, SYSMAX, SERVICE }

MFL CURRENT JOB STEP MAXIMUM FIELD LENGTH

RFL CURRENT FIELD LENGTH (RUNNING FIELD LENGTH)

NFL NOMINAL FIELD LENGTH = RFL

SYSDEF DEFAULT INITIAL FIELD LENGTH IF NO OTHER FL CAN BE DETERMINED AND
 RFL IS 0

FIELD LENGTH MANAGEMENT

INITIAL FIELD LENGTH IS THE FIRST ONE OF THE FOLLOWING THAT APPLIES:

1. FL REQUIRED SPECIFIED BY RFL = /MFL=
2. ROUTINE HAS REQUIRED FL IN A LOADER (54) TABLE
3. RFL HAS BEEN SPECIFIED BY A RFL MACRO OR CONTROL STATEMENT
4. USE THE SMALLER OF MFL AND SYSDEF

AFTER PROCESSING HAS BEGUN, ADDITIONAL FL MAY BE ACQUIRED VIA MEMORY MACRO, UP TO MFL.

$$RFL \leq MFL \leq MAXFL$$

MFL	RFL	MAXFL	ROLLIN FL	FLINCR. REQUEST
-----	-----	-------	--------------	--------------------

FLCW

FIELD LENGTH MANAGEMENT

ECS FIELD LENGTH IS THE FIRST ONE OF THE FOLLOWING THAT APPLIES:

1. ROUTINE HAS REQUIRED ECS FL IN A LOADER (54) TABLE
2. ECS FL HAS BEEN SPECIFIED BY A RFL MACRO OR CONTROL STATEMENT

AFTER PROCESSING HAS BEGUN, ADDITIONAL ECS FL MAY BE ACQUIRED VIA MEMORY MACRO, UP TO MFL.

$$RFL \leq MFL \leq MAXFL$$

MFL	RFL	MAXFL	ROLLIN FL	FLINCR. REQUEST
-----	-----	-------	--------------	--------------------

ELCW

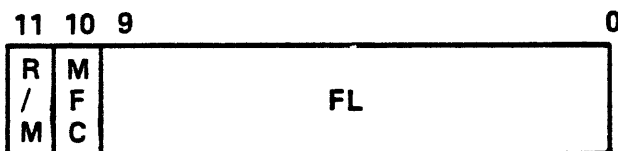
NOTE: ECS FIELD LENGTH IS NOT ROLLED BETWEEN JOB STEPS UNLESS PROTECTED VIA PROTECT MACRO/STATEMENT.

FIELD LENGTH MANAGEMENT

- RFL = MFL = ENTRY POINTS
- *FL LIBDECK SPECIFICATION

ABS	NAME OF FIRST ENTRY	R E L	S C	A S R	NO. EPTS
CLD	FLC	RCL/ASR	TRACK	SECTOR	
ENTRY	ENTRY POINT 1				
	.				
	.				
	.				
	ENTRY POINT N-1				

FLC



R/M = RFL = /MFL = FLAG. IF R/M=0, THEN RFL = VALUE IS ASSUMED.

MFC = MFL = CONTROL FLAG. IF MFC=0, THEN REQUIRED FL IS THE MAXIMUM OF EXISTING FL (FROM STSW) AND FL. IF MFC=1, THEN REQUIRED FL IS THE MAXIMUM OF THE CURRENT RFL (FROM FLCW) AND FL.

FIELD LENGTH MANAGEMENT

- RFL = ENTRY POINT
ENTRY RFL =
.
.
.
RFL = EQU *

THE RFL= VALUE IS ROUNDED UP TO THE NEXT MULTIPLE OF 100₈ AND SET INTO THE CLD ENTRY FOR THE ROUTINE BY SYSEDIT. WHEN THIS ROUTINE IS TO BE LOADED, THE RFL= VALUE WILL BE USED AS THE RUNNING FL (STSW).

- MFL= ENTRY POINT

THE MFL= VALUE IS ROUNDED UP TO THE NEXT MULTIPLE OF 100₈ AND SET INTO THE CLD ENTRY WITH R/M = 1 BY SYSEDIT.

WHEN THIS ROUTINE IS TO BE LOADED, IF THE MFL= VALUE IS < 2000 (MFC=0), THE MAXIMUM OF RFL (FROM FLCW) AND THE MFL VALUE IS USED AS THE RUNNING FL (STSW). OTHERWISE, THE MAXIMUM OF THE RUNNING FL (STSW) AND THE MFL VALUE IS USED AS THE RUNNING FL.

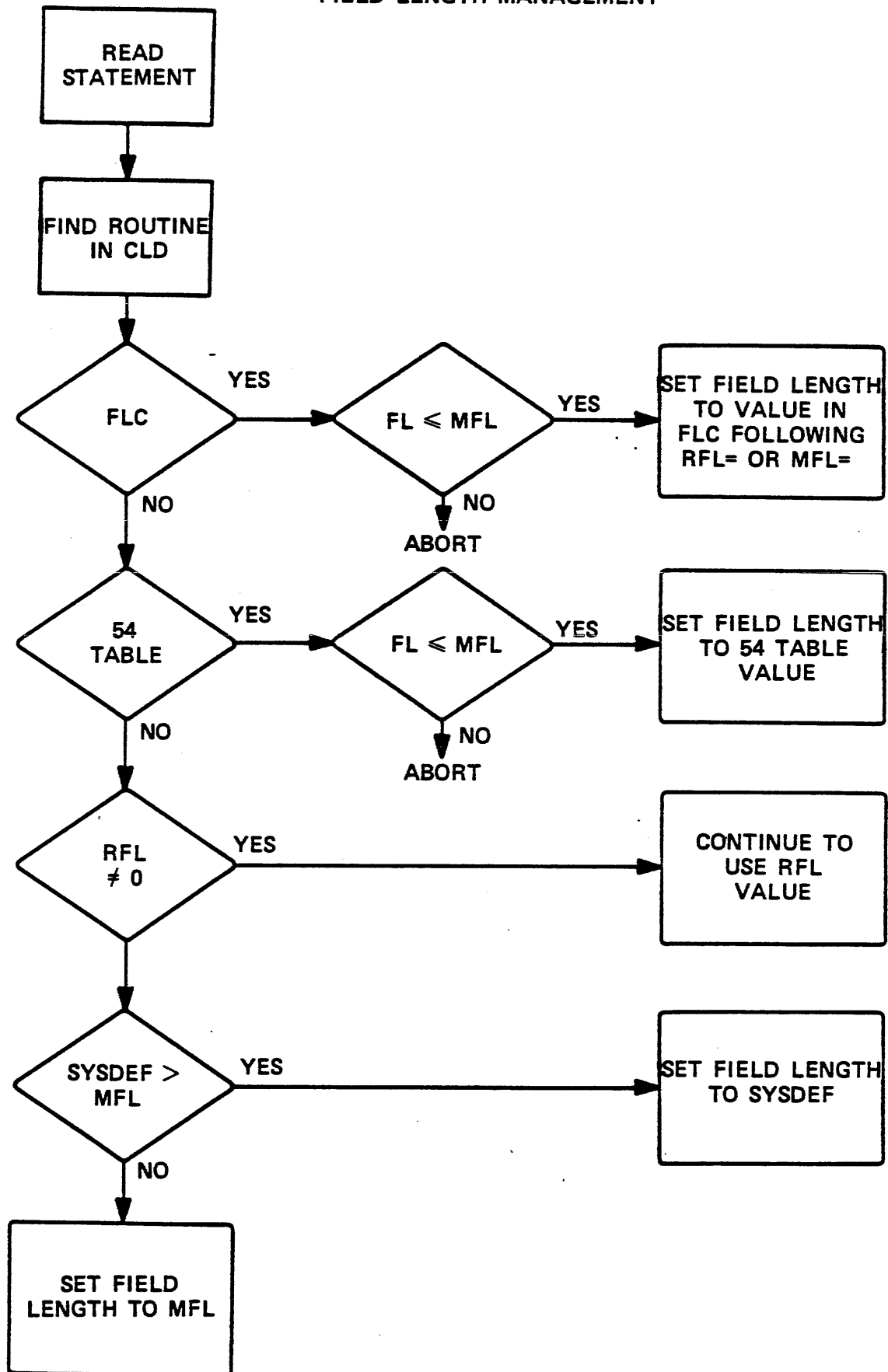
FIELD LENGTH MANAGEMENT

- *FL LIBDECK DIRECTIVE
 - *FL, TY/REC-FLC
 - *FL, ABS/FTN-64LO

THE *FL DIRECTIVE ALLOWS THE FLC VALUE TO BE SPECIFIED BY SYSEDIT.

THE *FL VALUE IS PRIMARILY USED FOR PRODUCTS THAT DO NOT HAVE RFL= OR MFL= ENTRY POINTS TO OPTIMIZE THEIR MEMORY MANAGEMENT.

FIELD LENGTH MANAGEMENT



COMPLETE JOB

1CJ - JOB TERMINATION

- RELEASE STORAGE (RSTM FL=0)
- RELEASE FILES
 - DROP FILES (ODF) EXCEPT QUEUE TYPES
- RELEASE EQUIPMENT (FROM EST)
- UPDATE DEMAND FILE (ORF)
- RECORD RUNNING DATA
 - UPDATE PROFILA (OAU)
 - ISSUE ACCOUNTING SUMMARY
 - AESR UECP UEAD
 - UEMS UEMT UEPF
- DISPOSE OUTPUT TO QUEUE
 - COPY JOB DAYFILE TO PRINT FILE
 - ENTER DISPOSAL INFORMATION AND ROUTING DATA IN FNT/FST AND SYSTEM SECTOR
 - QUEUE FILE
- DROP INPUT FILE TRACKS (QPROTECT)
- DROP JOB DAYFILE TRACKS
- DECREMENT FAMILY ACTIVITY COUNT
- CLEAR FNT INTERLOCK
- CLEAR CONTROL POINT AND DROP PPU VIA JACM SUBFUNCTION 3.

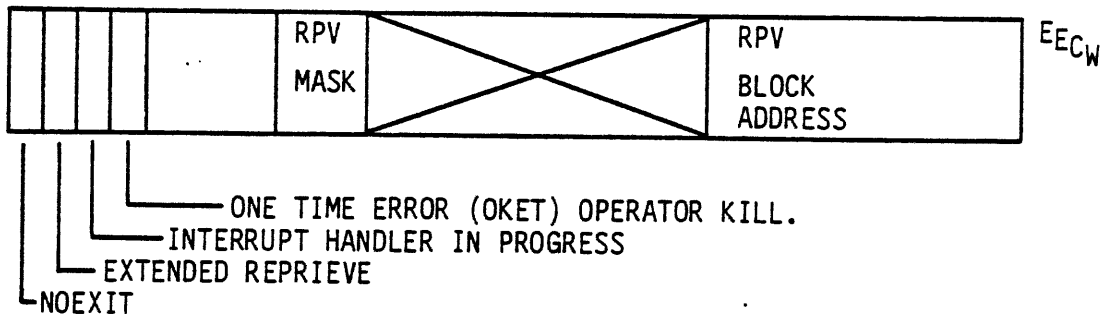
ERROR PROCESSING

ON ENTRY TO 1AJ, OVERLAY 3AB (PROCESS ERROR FLAG) WILL BE CALLED IF:

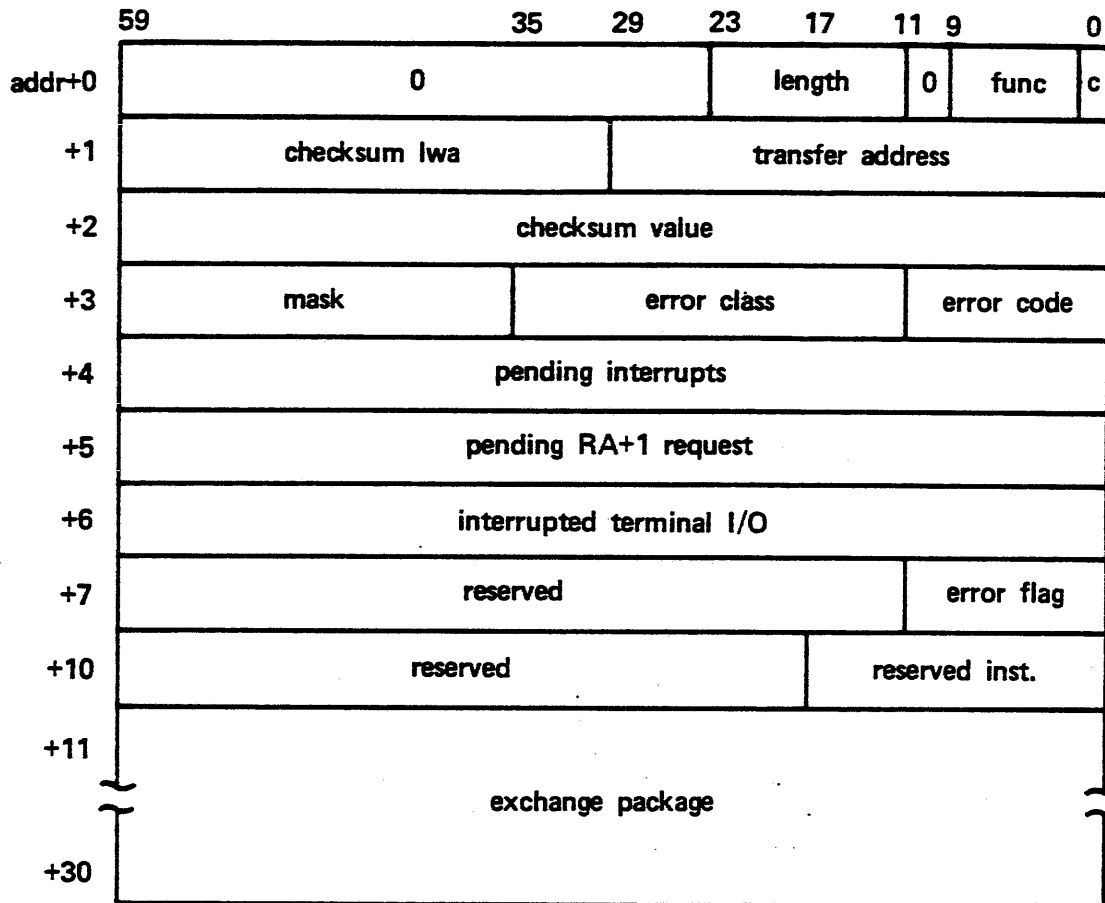
- ERROR FLAG IS SET IN STSW
- ERROR EXIT OR REPRIEVE CONTROL IN EECW
 - EXTENDED REPRIEVE
 - EREXIT/REPRIEVE
 - EXIT. STATEMENT (NOEXIT.)
 - ABORT JOB

ERROR PROCESSING

EXTENDED REPRIEVE



- VALIDATE PARAMETERS AND CHECKSUM
- INTERRUPT HANDLER ACTIVE AND BEING ABORTED, PERFORM EXIT PROCESSING
- INTERRUPT HANDLER NOT ACTIVE,
 - WRITE P, EXCHANGE PACKAGE, ERROR CODES, (RA+1) TO REPRIEVE BLOCK
 - CLEAR RA+1
 - SET INTERRUPT PROCESSING ACTIVE (INTERRUPT HANDLER)
 - RESTART JOB
- INTERRUPT HANDLER ACTIVE,
 - SET PENDING INTERRUPT CONTROL IN REPRIEVE BLOCK
 - RESTART JOB
- RESTART JOB
 - UPDATE EECW
 - INCREMENT TL OR SL
 - CLEAR DUMP CONTROL
 - REQUEST CPU (RCPM)
 - DROP PPU AND CLEAR JOB ADVANCE



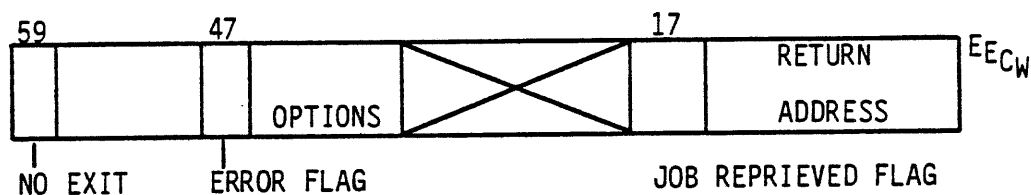
length Length of the parameter block including the exchange package area [minimum of 25 (31B) words].

func Function code:

- 1 Setup
- 2 Resume
- 3 Reset

ERROR PROCESSING

EREXIT/REPRIEVE



- VALIDATE ADDRESS
- IF REPRIEVE
 - VALIDATE OPTIONS AND CHECKSUM
 - WRITE EXCHANGE PACKAGE, ERROR CODES, (RA+1) TO REPRIEVE BLOCK
 - ISSUE JOB REPRIEVED MESSAGE
 - SET P TO REPRIEVE ADDRESS
 - CLEAR RA+1
 - SET JOB REPRIEVED FLAG
 - RESTART JOB
- IF EEXIT
 - SET (RA) WITH P AND ERROR CODE
 - SET P TO ERROR EXIT ADDRESS
 - CLEAR RA+1
 - CLEAR ERROR EXIT ADDRESS FROM EECW
 - RESTART JOB
- RESTART JOB
 - UPDATE EECW
 - INCREMENT TL OR SL
 - CLEAR DUMP CONTROL
 - REQUEST CPU (RCPM)
 - DROP PPU AND CLEAR JOB ADVANCE

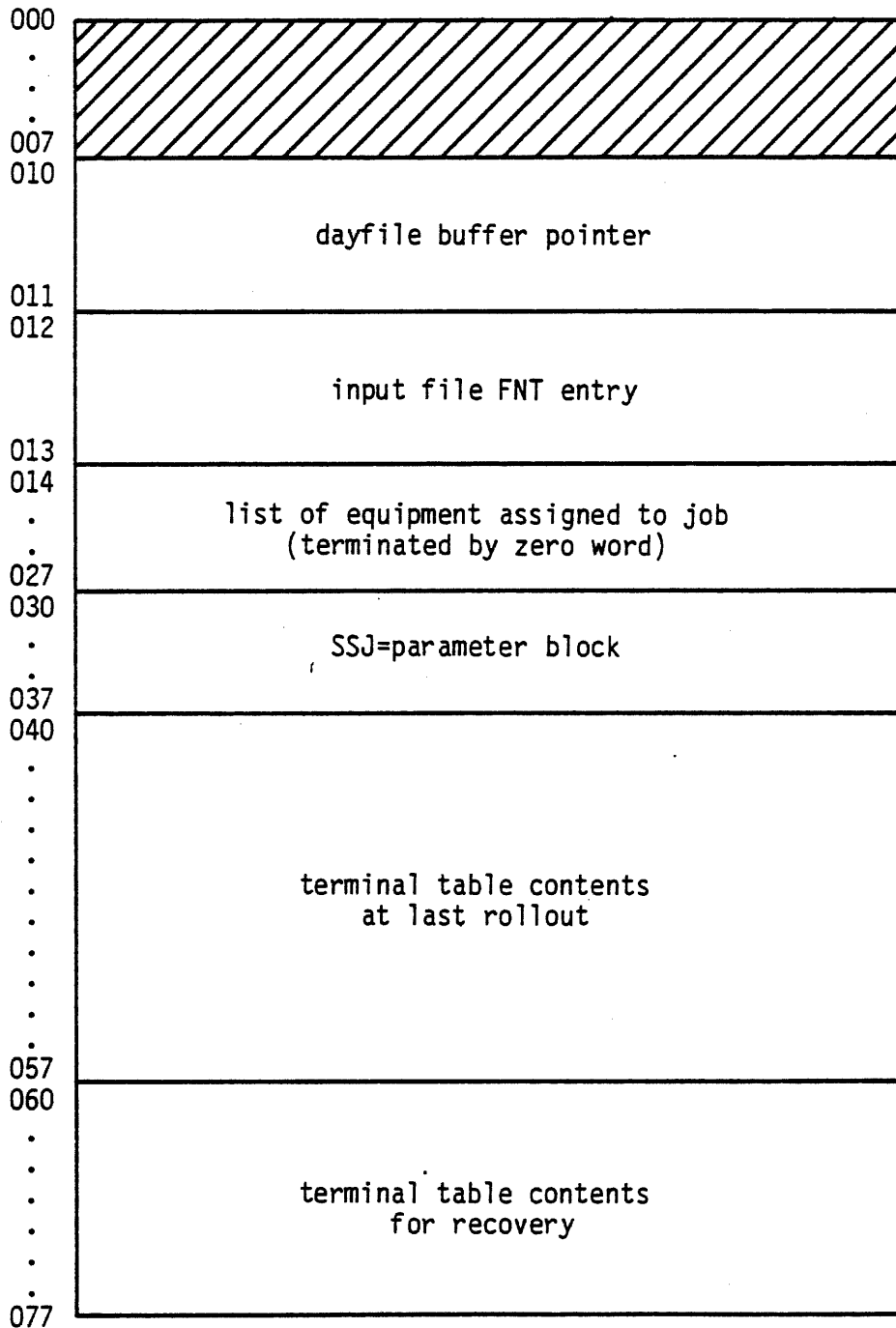
ERROR PROCESSING

EXIT

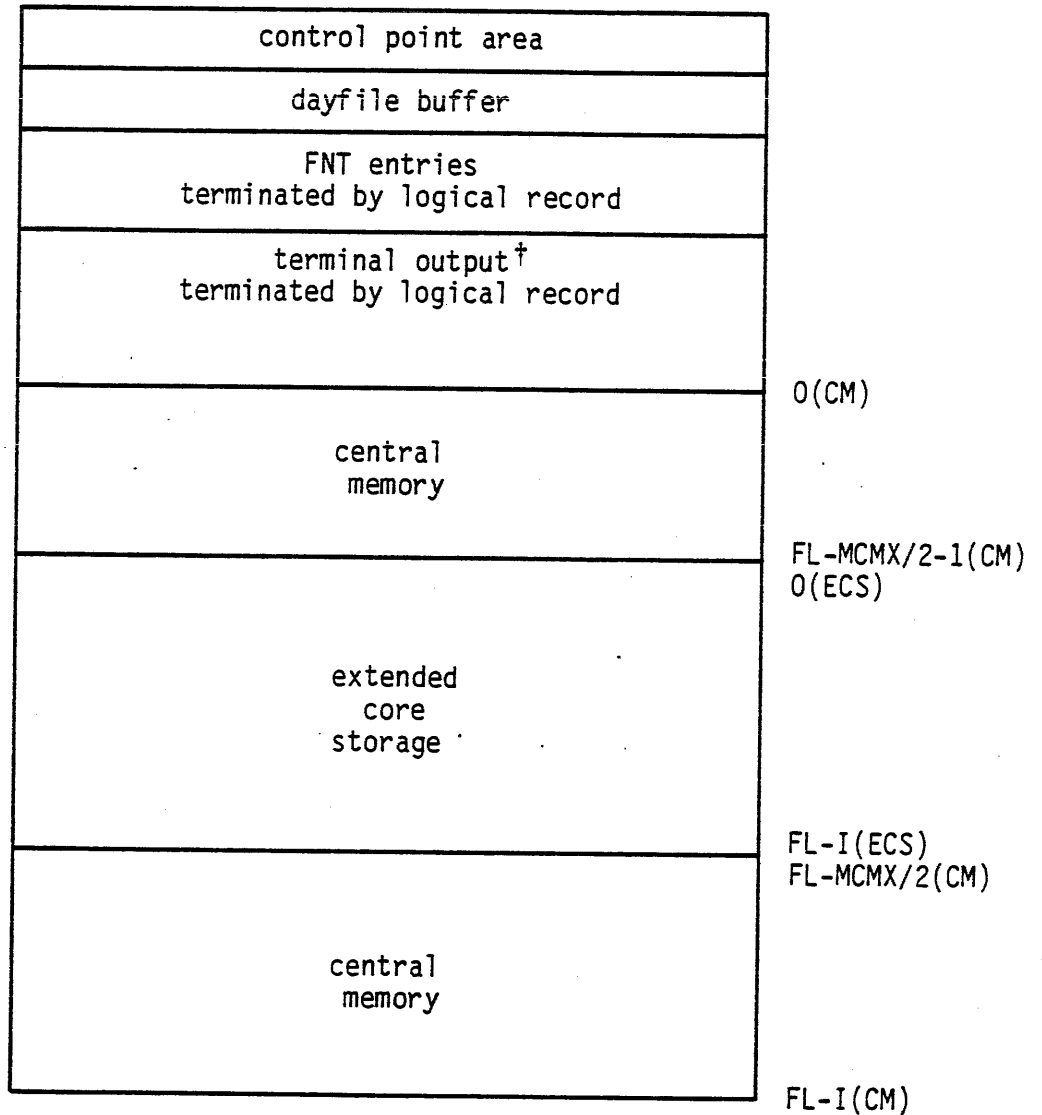
- IF ERROR < SPET, FIELD LENGTH PRESENT AND NON-MTOT JOB, THEN COMPLETE FILES
 - IF LIST OF FILES PRESENT (LOFW), COMPLETE FILES IN THE LOF LIST, FILES ARE FLUSHED IF
 - FET BUFFER HAS DATA AND WITHIN FL
 - WRITE BIT SET, OPEN ALTER, OR NO CIO CALLS
 - OUTPUT NOT FLUSHED IF TXOT
 - IF LIST OF FILES IS NOT PRESENT, FILE POINTERS FROM RA+2 TO RA+63 ARE EXAMINED FOR FET/FIT POINTERS. FLUSHES UNDER SAME CONDITIONS AS ABOVE FOR
 - OUTPUT (IF NOT TXOT)
 - PUNCH
 - P8
 - PUNCHB
 - FLUSHING IS DONE BY A WRITER CIO REQUEST
- SET SKIP FOR EXIT. STATEMENT (UNLESS NOEXIT) AND SET ERROR FLAG IN JCRW
- PROCESS SPECIFIC ERROR AND ISSUE APPROPRIATE DIAGNOSTIC
- REQUEST DUMP VIA SPCW
- AFTER DUMP, JOB ADVANCES TO EXIT. STATEMENT OR TO 1CJ (COMPLETE JOB).

ROLLOUT FILE

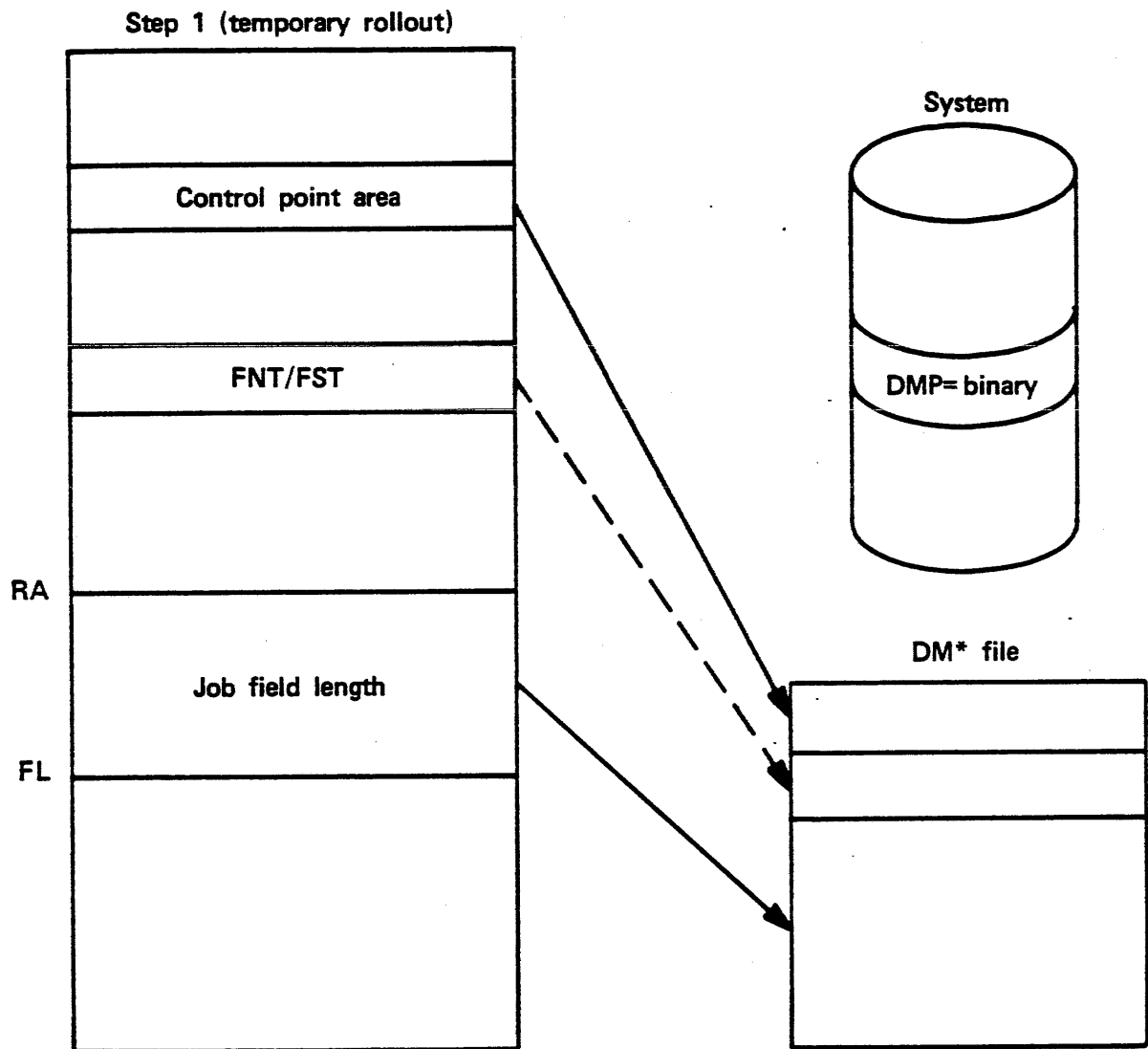
System Sector



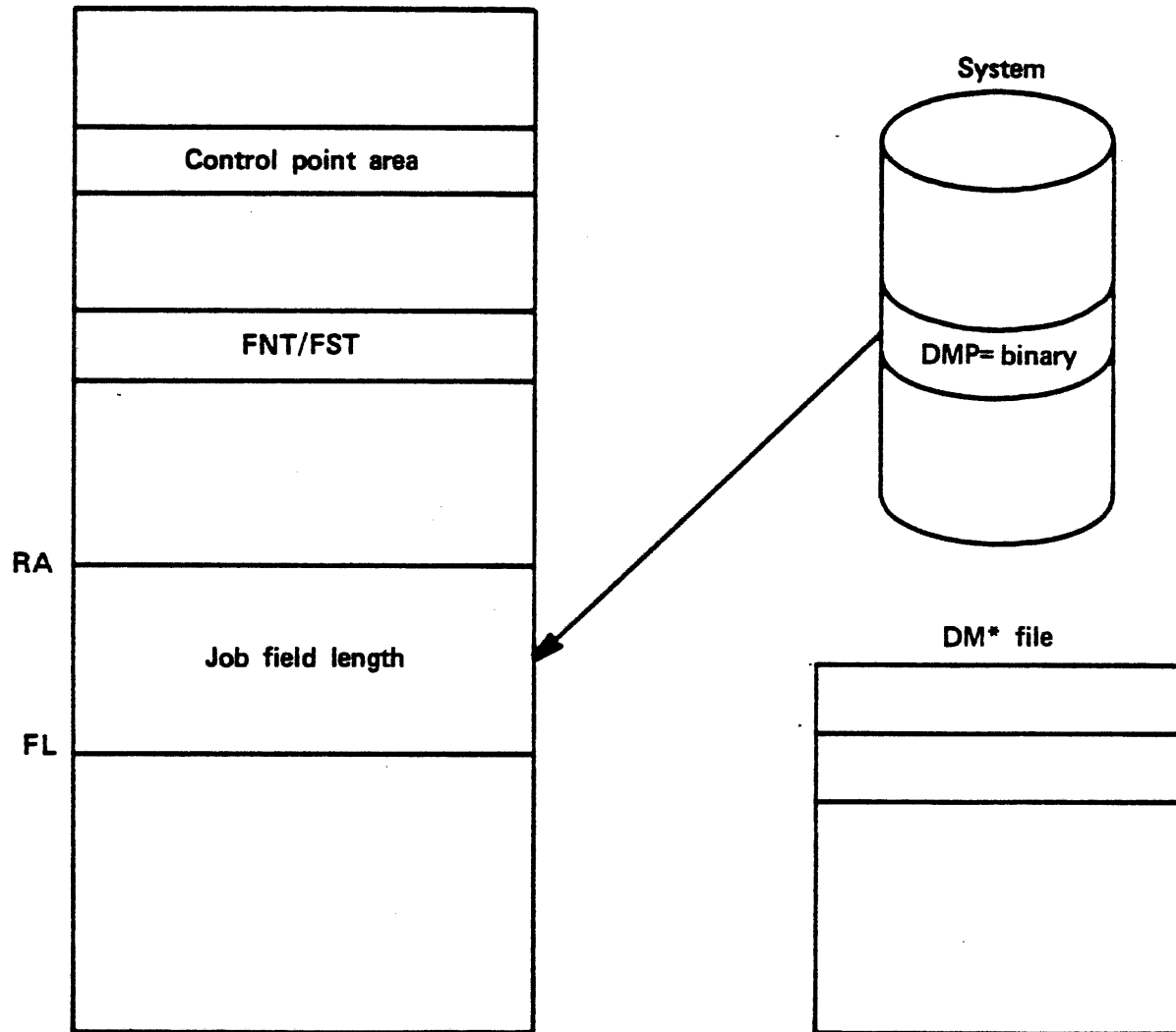
File Format

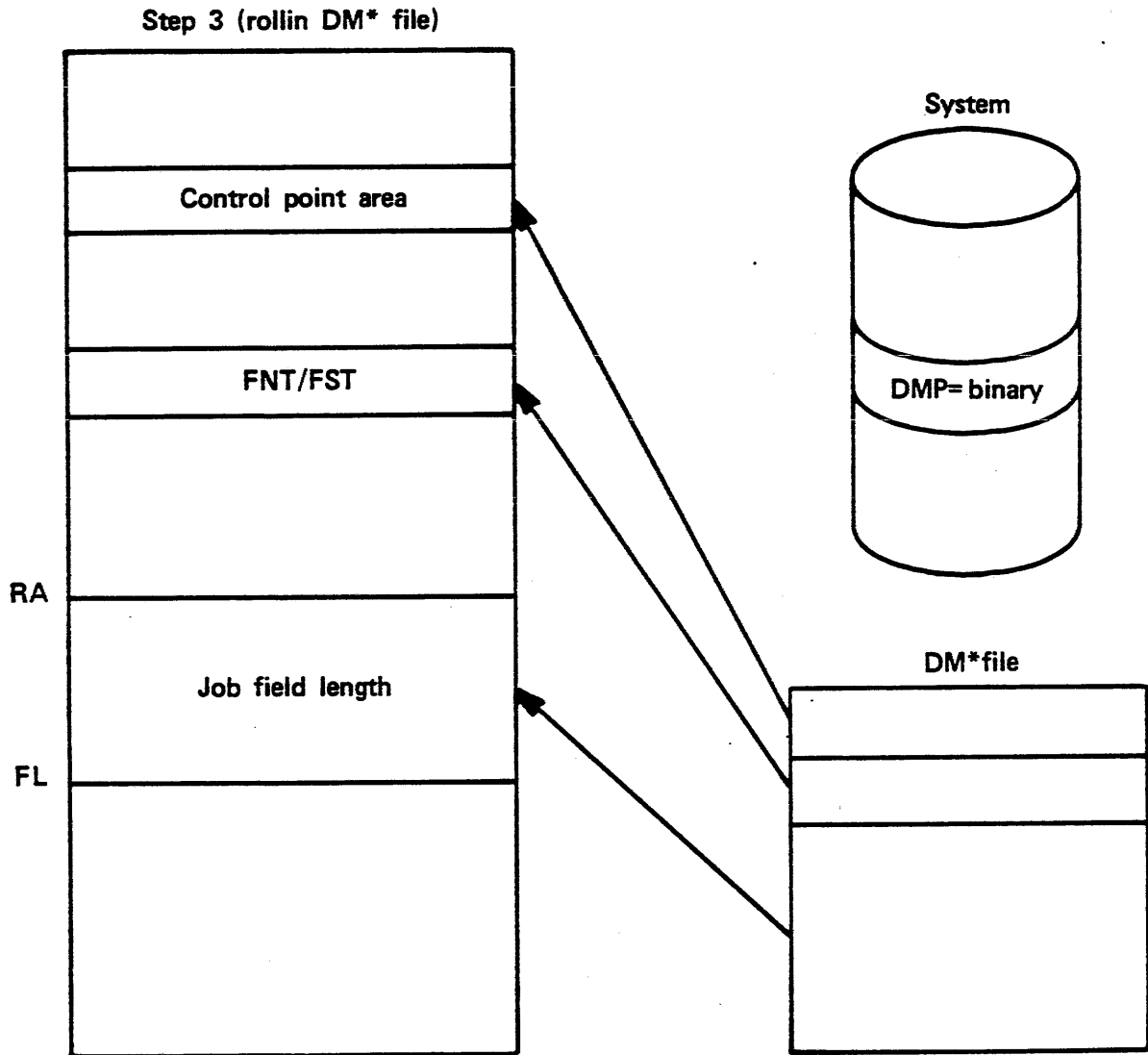


†This part of the rollout file is used only for TXOT jobs.



Step 2 (DMP= job load and execution)





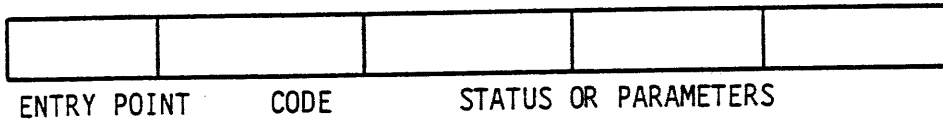
SPCW

SPECIAL CALL FOR DMP= PROCESSOR.

1. CP PROGRAM MAKES RA+1 REQUEST.
2. PPU ROUTINE SATISFYING REQUEST NEEDS A CPU ROUTINE TO ACTUALLY DO THE PROCESSING.
3. PPU ROUTINE PLACES REQUEST INTO CONTROL POINT WORD SPCW.
4. PPU ROUTINE DOES A ROCM - THIS WILL GET 1AJ TO PROCESS AN "ADVANCING" CONDITION.
5. 1AJ SENSES REQUEST IN SPCW AND SEARCHES CLD.
6. FL AND CP AREA ARE DUMPED TO DM* BASED ON DMP= VALUE BY 1RO.
7. 1AJ LOADS DMP= PROCESSOR.
8. PROCESSOR DOES ITS THING.
9. 1AJ REQUEST 1RI TO RESTORE FL AND CP AREA FROM DM* AS REQUIRED.
10. PPU ROUTINE COMES BACK TO COMPLETE REQUEST OR CPU ROUTINE THAT MADE THE RA+1 REQUEST RESUMES OR 1AJ ADVANCES TO NEXT JOB STEP.

DMP=

SPCW FORMAT



CODE 1/A, 1/B, 1/C, 1/D, 1/E, 1/O

- * A REQUEST ACTIVE
- B CLEAR RA+1 BEFORE RESUMING IF NOT SET
- C REMAINDER OF WORD IS PARAMETER LIST, NOT ADDRESS OF PARAMETERS
- * D DO NOT RESTART CPU
- * E DMP= IN PROGRESS

- * SET BY 1AJ

THE SPCW REQUEST WILL BE PASSED ON TO THE DMP= PROCESSOR (WHEN IT IS LOADED) AT ADDRESS SPPR (27) OF FIELD LENGTH.

WHEN PROGRAM TERMINATES SPPR IS USED TO PASS STATUS BACK THROUGH SPCW.

IF A PARAMETER ADDRESS IS SPECIFIED, A BLOCK OF DATA (20 WORDS) WILL BE TRANSFERRED FROM THE ORIGINAL PROGRAM TO THE DMP= PROCESSOR AT ADDRESS SPPR+1.

WHEN DMP= PROGRAM TERMINATES, THIS BLOCK IS RESTORED INTO THE ORIGINAL PROGRAM AT THE PARAMETER ADDRESS

SSJ=

WHY

1. PASS VALIDATION INFORMATION FROM CONTROL POINT AREA TO PROGRAM.
2. PASS VALIDATION INFORMATION TO CONTROL POINT AREA FROM PROGRAM.
3. ALLOW PROGRAM TO HAVE CERTAIN PRIVILEGES.
4. ALLOW PROGRAM TO HAVE TL, PR, QP FOR ONLY ITSELF, NOT THE ENTIRE JOB.

HOW

SSJ= VALUE AND PARAMETER BLOCK

	TL	PR	QP
USER NUMBER			USER INDEX
ALMW			
ACLW			
AACW			

	400000	4AAAAA	OAAAAA	000000
DROP FILES SSID	Y	Y	Y	N
SWAP BLOCK	N	Y	Y	N
SSJ PRIVILEGES	Y	Y	Y	Y
CREATE SSID FILES	N	Y	Y	N

SSJ=

1. IF PARAMETER BLOCK ADDRESS IS SPECIFIED, WHEN PROGRAM IS LOADED:

1AJ SETS TL, PR, QP IF SPECIFIED
 RETURNS CURRENT TL, PR, QP TO PROGRAM

 UIDW
 ALMW
 ACLW
 AACW

 SETS UIDW TO SYSTEMX, 377777
 ALMW, ACLW, AACW UNLIMITED

2. WHEN PROGRAM TERMINATES, 1AJ

 RESETS TL,PR, QP FROM BLOCK
 SETS UIDW FROM BLOCK
 ALMW (NEW OR RESTORED VALUES)
 ACLW
 AACW

 RETURNS ALL FILES WITH SSID

SUBSYSTEMS

CHARACTERISTICS

1. NOT ROLLABLE - NO ROLLOUT
2. INTER CONTROL POINT COMMUNICATIONS (RSB/SIC)
3. HIGH CPU PRIORITY
4. DOES NOT ABIDE BY JCB CONTROLS
CM AND CPU SLICES - INFINITE
5. MAY HAVE A USER NUMBER IN UIDW
TRANEX/TAF
6. MAY RESIDE AT A SPECIFIED CP
7. IMPLICIT SSJ= AND ARE SYOT
8. USE OF SPC (NEE TLX) RA+1 CALL

TO BE A SUBSYSTEM

1. UNIQUE QP DEFINED TO FIT INTO SSCL WORDS OF CNR
2. 1DS TABLE ENTRY TO START UP EXECUTIVE
3. QP IDENTIFIES THE SUBSYSTEM (OPERATING SYSTEM TESTS FOR A GIVEN SUBSYSTEM BY ITS QUEUE PRIORITY)

SUBSYSTEMS

<u>SUBSYSTEM</u>	<u>QP SYMBOL</u>	<u>QP</u>	<u>PP INIT.</u>	<u>CONTROL PT.</u>
TIME-SHARING	TXPS	7776	1SI	1
TELEX IAF				
REMOTE BATCH	EIPS	7775	1LS	77
EI200				
UNIT RECORD	BIPS	7774	1IO	76
BATCHIO				
TAPES	MTPS	7773	1MT	75
MAGNET				
TRANSACTION	TRPS	7772		
TRANEX TAF			1TP 1SI	
NETWORK INTERFACE	NMPS	7770	1SI	74
NIP				
REMOTE BATCH (NETWORK)	RBPS	7767	1SI	73
RBF				
MESSAGE CONTROL SYS	MCPS	7765	1SI	72
CDCS	CDPS	7766	1SI	71
TIME SHARE STIM	STPS	7771	1SI	77
STIMULA				
MASS STORAGE CONTROL	MSPS	7764	CMS	74
MASS STORAGE SUBSYSTEM	MFPS	7763	1SI	70
MSSEXEC				

SUBSYSTEMS

SCHEDULING

AUTO.	}	1DS FUNCTION 33
MAINTENANCE		
MAGNET. ETC.		1DS FUNCTION 32

1DS HAS A TABLE OF SUBSYSTEMS. ON FUNCTION 33 1DS CHECKS TO SEE IF SUBSYSTEM IS ENABLED AND IF SO AUTOMATICALLY INITIATES IT. (SSTL)

SSCL IS CHECKED TO DETERMINE IF SUBSYSTEM IS ALREADY ACTIVE. IF SO, 1DS 33/32 ACTION FOR THAT SUBSYSTEM IS IGNORED.

A FNT/FST ENTRY FOR THE SUBSYSTEM IS BUILT AND ENTERED INTO THE INPUT QUEUE.

1SI		CP		JOB SEQN NUMBER				S Y O T	I N F T	O	FNT
0	77	F	F	F	F	F	F	FL	QP	QP	FST

SUBSYSTEMS ARE SCHEDULED BY 1SJ OVERLAY 3SA. SSCL WILL BE ENTERED WITH THE CP GIVEN TO THE SUBSYSTEM.

CP IS ACTUAL CP IF < 408; OTHERWISE $NCP - \overline{CP} - 1$.

QUESTION SET LESSON 14

1. When and how is 1SJ called into execution?
2. How do queue priorities get aged? What routine does the aging?
3. What routine checks CPU and CM time slices? What happens to the job if either one of these slices expires?
4. Can you disable priority evaluation? Auto rollout? Job Scheduling?
5. Under what conditions might the job scheduler request that a job be rolled out?
6. What criteria does 1SJ use to determine the "best" job for scheduling?
7. What criteria does 1SJ use to determine the "best" control point to be assigned to the job?
8. Why does 1SJ call 1AJ and 1RI? What does 1SJ do if a PP is not available for 1AJ or 1RI?
9. Why does CPUMTR call 1AJ?
10. Explain what the Begin Job overlay (3AA) accomplishes. Why is 3AA called?
11. Explain what the Error Processing overlay (3AB) does and why it would be called.
12. Which 1AJ overlay is called to process control statements?
13. Which control statements are processed entirely within the 1AJ (TCS) PP?
14. Explain the differences between Operating System argument processing and Product Set argument processing.
15. How is a program loaded from the Resident Central Library? From an ECS ASR? From mass storage?

16. Are relocatables and absolute routines loaded in the same manner? Explain your answer.
17. Is it legal to call a PP routine from a control statement? If so, how does 1AJ process it?
18. Explain how 1DS causes subsystems to be initiated.
19. Define the terms:
 - SYSMAX
 - MAXFL
 - MFL
 - RFL
 - SYSDEF
20. How does the system determine a program's initial central memory field length?
21. How does the system determine a program's initial ECS field length?
22. The CLD entry contains a field length control field. Explain the values this field may assume with respect to RFL=, MFL= and *FL values.
23. Your CPU program does a DMP RA+1 request. How does the system process this request? Your answer should discuss DMP= and SPCW processing.
24. Discuss the processing of the SSJ= entry point. What privileges can the program have? What happens to files created by SSJ= programs when they terminate?

LESSON 15 ACCOUNTING

LESSON PREVIEW:

This lesson presents the accounting and validation philosophy of NOS. The ACCOUNT dayfile and its entries, the System Resource Unit (SRU), the monitor functions and subroutines, and validation files will be discussed. The resource controls placed on the user by the user number and charge/project number will also be discussed.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Detail the standard message format that appears in the ACCOUNT dayfile.
- Explain what a System Resource Unit (SRU) is and give its formula.
- Briefly explain how each value in the SRU formula is computed and the SRU accumulated by CPUMTR.
- Define the term "account block".
- Describe the monitor functions ACTM and RLMM and describe the accounting aspects of monitor functions TIOM and UADM.
- Discuss the validation files VALIDUS and VALINDs and what information they contain.
- Explain the various internal representations for limit values.
- Discuss the project profile file PROFILA and what information it contains.

REFERENCES:

NOS IMS - Chapter 20 NOS SMRM, 5 NOS RM, 1-3-7, 1-6-2,33-34

ACCOUNTING

ACCOUNT DAYFILE

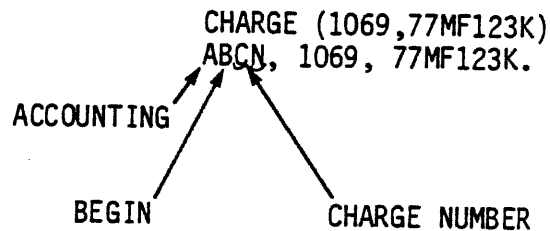
HISTORY OF SYSTEM AND RESOURCE USAGE TO -

- PROPERLY BILL USERS OF THE SYSTEM
- ANALYZE SYSTEM USAGE

STANDARD MESSAGE FORMAT

HH.MM.SS. JOBNAMEO, GEAC, INFORMATION.

G = GROUP {S = STATISTICAL, U = USAGE, A = ACCOUNTING}
E = EVENT
AC = ACTIVITY



SRU

BASIC ACCOUNTING UNIT IS THE SYSTEM RESOURCE UNIT OR SRU. IT IS A MEASURE OF THE RESOURCES USED BY A JOB OR TTY SESSION.

- CM FIELD LENGTH
- ECS FIELD LENGTH
- CPU TIME
- MS USAGE
- PF USAGE
- MT USAGE

ACCOUNT BLOCK

SRUs FROM CHARGE TO ANOTHER CHARGE OR END OF JOB.

ACCOUNTING

SRU ALGORITHM

$$\text{SRU} = (\text{M1}(\text{CP} + \text{M2} \cdot \text{IO}) + \text{M3}(\text{CP} + \text{IO})\text{CM} + \text{M4}(\text{CP} + \text{IO})\text{EC}) + \text{AD}$$

CP CENTRAL PROCESSOR USAGE IN MILLIUNITS

$$\text{CP} = \text{S0} \cdot \text{CP0} + \text{S1} \cdot \text{CP1}$$

S0, S1 ARE MULTIPLIERS TO NORMALIZE CP TIME IN A DUAL CPU MACHINE OR MAINFRAMES AT THE SITE.

CP_i IS ACCUMULATED TIME IN CPU_i IN MILLISECONDS.

IO MEASURE OF ACCUMULATED I/O ACTIVITY (MILLIUNITS)

$$\text{IO} = \text{S2} \cdot \text{MS} + \text{S3} \cdot \text{MT} + \text{S4} \cdot \text{PF}$$

S2, S3, S4 MULTIPLIERS WEIGHT MS, MT, PF AGAINST EACH OTHER

MS = MASS STORAGE ACTIVITY
MT = MAGNETIC TAPE ACTIVITY
PF = PERMANENT FILE ACTIVITY

CM CENTRAL MEMORY FIELD LENGTH IN WORDS/100₈
EC ECS FIELD LENGTH IN TRACKS (WORDS/1000₈)

AD ADDER APPLIED AS AN ACCUMULATION OF INDIVIDUAL UNIT CHARGES
M1 OVERALL SRU SCALE MULTIPLIER
M2 MULTIPLIER TO WEIGHT IO AGAINST CP EC CM
M3 MULTIPLIER TO WEIGHT CM AGAINST CP EC IO
M4 MULTIPLIER TO WEIGHT EC AGAINST CP IO CM

ACCOUNTING

SRU UPDATING IN CPUMTR

AAD - APPLY ADDER
CALLED BY UADM

$$SRU = SRU + AD$$

AIO - APPLY IO
CALLED BY UADM
TIOM

$$IO = S2 \cdot MS + S3 \cdot MT + S4 \cdot PF$$

$$SRU = SRU + IO \cdot IOM$$

CPT - APPLY CP TIME
CALLED BY TIM

$$CP = S0 \cdot CPO + S1 \cdot CP1$$

$$SRU = SRU + CP \cdot CPM$$

OR WHEN CONTROL POINT IS GIVEN OR GIVES UP THE CPU

SRU - CALCULATE IOM AND CPM MULTIPLIERS
CALLED WHEN CM/ECS FL CHANGES OR M1-M4
MULTIPLIERS CHANGE BY NEW ACCOUNT BLOCK

$$SRU = M1(CP + M2 \cdot IO + M3(CP + IO)CM + M4(CP + IO)EC) + AD$$

$$= M1(1 + M3 \cdot CM + M4 \cdot EC)CP + M1(M2 + M3 \cdot CM + M4 \cdot EC)IO + AD$$

$$= (M1 + M1 \cdot M3 \cdot CM + M1 \cdot M4 \cdot EC)CP + (M1 \cdot M2 + M1 \cdot M3 \cdot CM + M1 \cdot M4 \cdot EC)IO + AD$$

$$= CPM \cdot CP + IOM \cdot IO + AD$$

$$CPM = M1 + M1 \cdot M3 \cdot CM + M1 \cdot M4 \cdot EC$$

$$IOM = M1 \cdot M2 + M1 \cdot M3 \cdot CM + M1 \cdot M4 \cdot EC$$

ACCOUNTING

CPUMTR FUNCTIONS

ACTM - ACCOUNTING FUNCTIONS

SUBFUNCTIONS

ABBF	BEGIN ACCOUNT BLOCK	FIRST CHARGE OR DEFAULT MULTIPLIERS
ABSF	RESET MULTIPLIERS	IRI RESTARTS JOB •CPM •IOM
ABCF	CHANGE/END ACCOUNT BLOCK	SECOND CHARGE
ABEF	CALCULATE ELAPSED SRUs	IRO COMPLETES TTY JOB STEP
ABVF	CONVERT ACCUMULATORS	ACCOUNT BLOCK END MESSAGES
ABIF	MAKE SRU ACCUMULATOR INTEGER	INCREMENT SRU ACCUMULATOR IN PROFILE
RLMM	- REQUEST LIMIT	

SUBFUNCTIONS

RLCO	CLEAR OVERFLOW FLAGS
RLIT	INCREMENT JOB STEP TIME LIMIT
RLIS	INCREMENT JOB STEP SRU LIMIT
RLJS	START JOB STEP
RLTL	SET TIME LIMIT
RLSL	SET SRU LIMIT

ACCOUNTING

VALIDATION FILES

SYSTEM VALIDATION (VALIDUs) AND PROJECT PROFILE (PROFILa) FILES ARE USED TO VALIDATE USER ACCESS TO SYSTEM.

- DETERMINE IF A USER IS ALLOWED TO USE THE SYSTEM.
- CHARGE THE USER FOR HIS RESOURCE USAGE.
- RESTRICT THE USER TO CERTAIN RESOURCE USAGE.
- MAINTAIN PERMANENT FILE CATALOGS FOR THE USER BY MAPPING THE USER'S USER NUMBER INTO A SPECIFIC USER INDEX.

ACCOUNTING

VALIDATION FILES

VALIDUS - HAS USER VALIDATION INFORMATION.

VALINDS - HAS A BIT FOR EACH USER INDEX IN USE (42108 WORDS REPRESENT USER INDICES 1 THROUGH 37700 (AUIMX)).

MODVAL - MAINTENANCE UTILITY

VALIDUS IS A TREE STRUCTURED FILE.

TREE STRUCTURED FILES ARE MANAGED VIA COMMON DECK COMSSFS AND SYSTEM ROUTINE SFS - SPECIAL SYSTEM FILE SUPERVISOR.

EACH TREE NODE IS CALLED A LEVEL. TYPICALLY WE HAVE LEVEL-0, LEVEL-1, LEVEL-2 AND LEVEL-3 DATA BLOCKS IN THE VALIDUS AND PROFILA FILES.

VALIDUS LEVEL-0 CONTAINS HISTORY INFORMATION AND THE FIRST USER NUMBER AND RANDOM ADDRESS OF EACH PRIMARY LEVEL-1 BLOCK.
(CREATED ON OP=C)

VALIDUS LEVEL-1 BLOCKS CONTAIN THE USER NUMBER AND RANDOM ADDRESS OF THE LEVEL-2 BLOCKS.

VALIDUS LEVEL-2 BLOCKS CONTAIN THE USER VALIDATION INFORMATION FOR UP TO FOUR USER NUMBERS.

ACCOUNTING

VALIDATION FILES

VALIDATION BLOCK (LAYOUT BY COMSACC)

UN USER NUMBER	1-7 CHARACTERS (ALPHANUMERIC)
UI USER INDEX	SUPPLIED THROUGH VALINDS (377777)
PW PASSWORD	1-7 CHARACTERS (ALPHANUMERIC)
SC SECURITY COUNT	NUMBER OF SECURITY VIOLATIONS
AB ANSWERBACK	ANSWERBACK TERMINAL CODES
MT MAGNETIC TAPE	MAX, MAGNETIC TAPES ALLOWED
RP REMOVABLE PACKS	MAX, REMOVABLE PACKS ALLOWED
TL JOB STEP TIME LIMIT	MAX, SETTING FOR TIME LIMIT
SL JOB STEP SRU LIMIT	MAX, SETTING FOR SRU LIMIT
DF DAYFILE MESSAGES	NUMBER OF MESSAGES ALLOWED
CC CONTROL STATEMENT	NUMBER OF CONTROL STATEMENTS ALLOWED
CM CENTRAL MEMORY	MAX, CM FIELD LENGTH SETTING

EC	ECS	MAX, ECS FIELD LENGTH SETTING
LP	LINES PRINTED	NUMBER OF LINES PRINTED ALLOWED
CP	CARDS PUNCHED	NUMBER OF CARDS PUNCHED ALLOWED
OF	DISPOSED OUTPUT	NUMBER OF OUTPUT QUEUE FILES ALLOWED
DB	DEFERRED BATCH	NUMBER OF SUBMITS ALLOWED
MS	MASS STORAGE	AMOUNT OF MASS STORAGE IN USE/JOB
NF	NUMBER OF FILE	NUMBER OF LOCAL FILES PER JOB
AW	ACCESS WORD	VARIETY OF INDIVIDUAL PERMISSIONS
		CPWC (0)
		CTPC (1)
		CLPF (2)
		CSPF (3)
		CSOJ (4)
		CASF (5)
		CAND (6)
		CCNR (7)
		CSRP (10)
		CSTP (11)
		CTIM (12)
		CUCP (13)
		CSAP (14)
		CBIO (15)
		CPRT (16)
AP	APPLICATION	IAF (24)
		RBF (25)
		TAF (26)
		MCS (27)
		TVF (28)
		NOP (29)
		LOP (30)
		NOPLP (31)

ACCOUNTING

VALIDATION FILES

VALIDATION BLOCK

FC	PERM, FILE COUNT	NUMBER OF PFS ALLOWED
FS	IAFSIZE	MAX, SIZE OF IAF
CS	TOTAL IAF SIZE	COMMULATIVE IAF ALLOWED
DS	DAF SIZE	MAX, SIZE OF DAF
PX	TRANSMISSION	FULL OR HALF ECHOPLEX
RO	RUB OUTS	RUBOUT COUNT
PA	PARITY	TERMINAL PARITY (EVEN/ODD)
TT	TERMINAL TYPE	TYPE OF TERMINAL (EG. COR)
TC	CHARACTER SET	DEFAULT CSET (EG. ASCII)
IS	INITIAL SUBSYSTEM	DEFAULT SUBSYSTEM (EG. BASIC)

ACCOUNTING

VALIDATION FILE

LIMIT MANAGEMENT - CONVERT INDEX INTO LIMIT VALUE

- COMCCVI
 - COMPCVI
- YYIS DEF 1
*CALL COMxCVI

LIMIT INDEX

LIMIT = INDEX·MULTIPLIER+CONSTANT

TLI	LPI	NFI	ECI
SLI	CPI	CMI	DBI

INDEX TABLE

INDEX POINTS TO TABLE ENTRY HAVING LIMIT

FCI	DSI	FSI	CSI
-----	-----	-----	-----

COUNTING LIMIT

VALUE COMPUTED BY THE LIMIT INDEX SCHEME, STORED IN ACLW AND MANIPULATED VIA UADM

MSI	CCI	DFI	OFI
-----	-----	-----	-----

ACTUAL VALUES

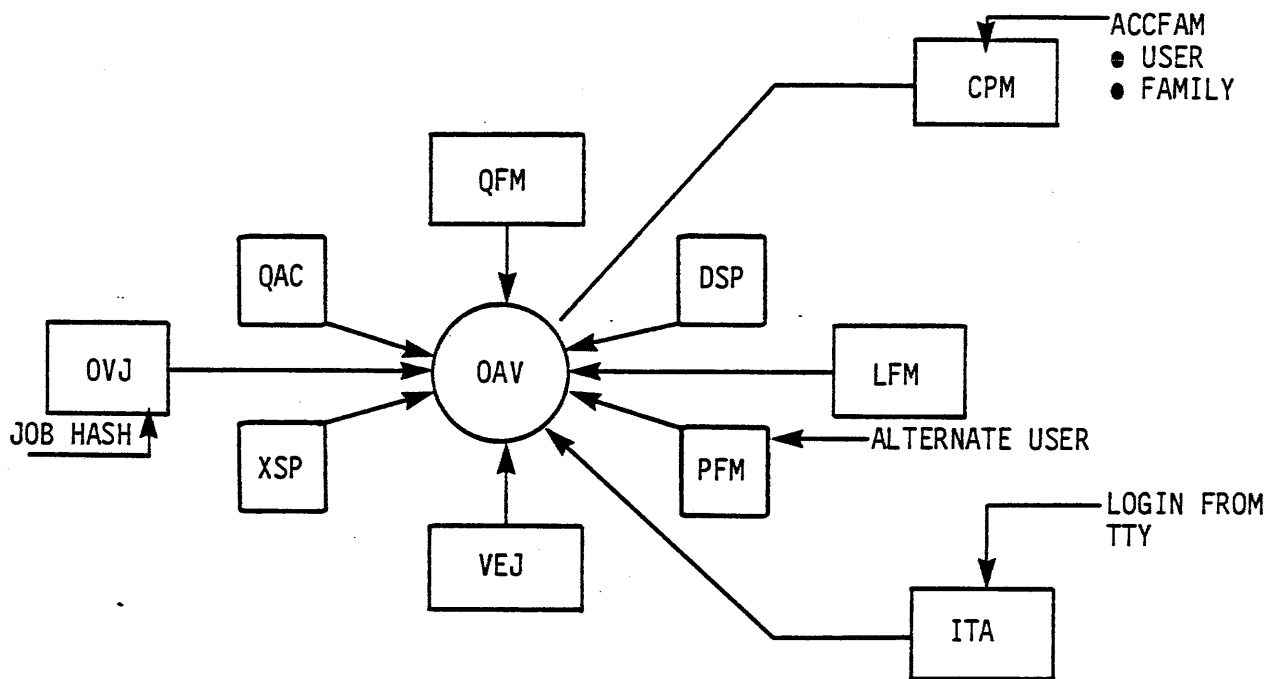
ACTUAL VALUE IS LIMIT - TAPES AND PACKS

ACCOUNTING

VALIDATION FILES

OAV - VALIDATES USER NUMBER AND INDICATES WHERE LEVEL-2 BLOCK IS FOR USE BY ITS CALLER

- OPTIONALLY DECREMENTS SECURITY COUNT



ACCOUNTING

PROJECT PROFILE

PROFILa - CHARGE, PROJECT ACCOUNTING INFORMATION FILE

- SYSTEM ORIGIN - CREATES CHARGE AND MASTER USER SKELETON
- SPECIAL USERS - CSAP IN AACW
- MASTER USER - PROJECT MAINTENANCE WITHIN CHARGE

PROFILE - MAINTENANCE UTILITY

PROFILa LEVEL-0 CONTAINS HISTORY INFORMATION AND FIRST CHARGE NUMBER AND RANDOM ADDRESS OF EACH LEVEL-1 BLOCK.

LEVEL-1 CONTAINS M1-M4,AD VALUES FOR THE CHARGE NUMBER, PROJECT COUNTS, CHARGE EXPIRATION, AND MASTER USER NUMBER. LEVEL-1 BLOCK POINTS TO THE LEVEL-2 BLOCK.

LEVEL-2 BLOCK CONTAINS PROJECT NUMBERS WITH RANDOM ADDRESS FOR THEIR LEVEL-3 DATA.

LEVEL-3 BLOCK HAS SRU ACCUMULATION AND A LIST OF VALIDATED USERS (AS MANY OVERFLOW BLOCKS TO ACCOMMODATE USERS AS NEEDED)

ACCOUNTING

PROJECT PROFILE

LEVEL-3 BLOCK "PROJECT BLOCK"

- PROJECT EXPIRATION DATE
- TIME IN - TIME OUT
- LAST UPDATE DATE/TIME (BY OAU)
- SRU LIMIT AND ACCUMULATOR
- INSTALLATION LIMIT AND ACCUMULATORS
- USER NUMBERS OF USERS IN THE PROJECT

ACCOUNTING

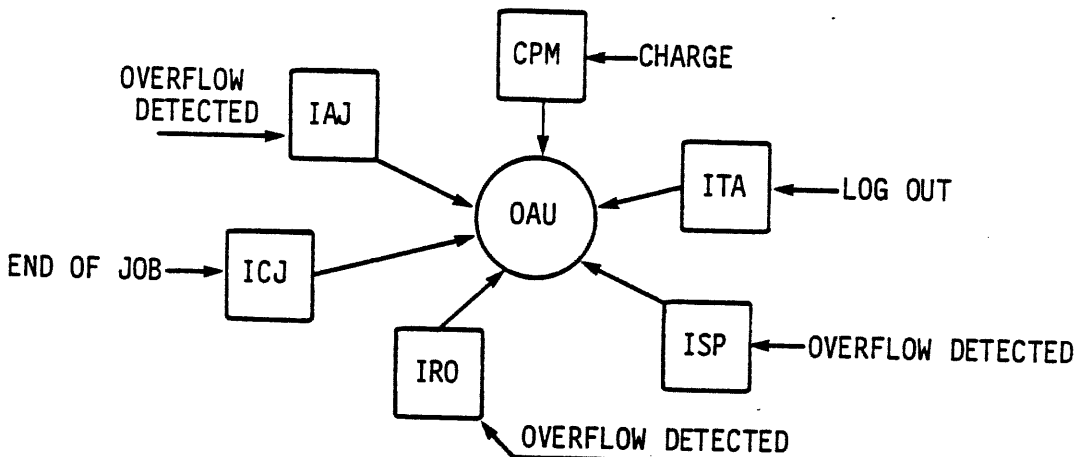
PROJECT PROFILE

CHARGE

1. INDICATE USER'S CHARGE AND PROJECT NUMBERS TO ACCOUNT DAYFILE.
2. ENTER SRU MULTIPLIERS (M1-M4,AD) INTO CONTROL POINT VIA CPM RA+1 REQUEST.
3. ON SUBSEQUENT CHARGE STATEMENTS, ENTER ACCUMULATOR INFORMATION INTO DAYFILE, SRU ACCUMULATION INTO ACCOUNT DAYFILE AND UPDATE LEVEL-3 BLOCK (OAU). MULTIPLIERS ARE RESET (STEP 2).
4. CLEAR SRU ACCUMULATOR BUT LEAVE OTHER ACCUMULATORS (AD, CP, MS, MT, PF) AS IS.

OAU

UPDATES LEVEL-3 BLOCK WITH SRU ACCUMULATION



QUESTION SET LESSON 15

1. What is an SRU? What is the SRU algorithm?
2. CPUMTR processes the SRU in various components. Describe what the following CPUMTR subroutines do:
 - Apply Adder (AAD)
 - Apply I/O Increment (AIO)
 - Compute CP Time (CPT)
 - Calculate SRU Multipliers (SRU)
3. What is an "account block"?
4. What information is kept in the validation file VALIDUs? VALINDs?
5. What information is kept in the project profile file PROFILa?
6. What is the relationship between the validation files and the project profile file?
7. What does the "GEAC" code in an ACCOUNT dayfile message indicate?
8. What information does the level-2 block in VALIDUs contain?
9. What information is contained in the level-1 PROFILa block? The level-2 block? The level-3 block?

LESSON 16 PERMANENT FILES

LESSON PREVIEW:

This lesson discusses how the system manages permanent files. The use of permanent files by the user is presented in many reference manuals and user's guides, and will not be covered in this lesson. Thus, it is assumed that the student is familiar with NOS permanent files on the end user level.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Explain the permanent file "family" concept of NOS.
- Define the types of permanent files in NOS and why there are two types of access.
- Discuss in detail the relationship the user's user index has to permanent files.
- Detail the information in a permanent files's catalog and permit entry.
- Describe the process for cataloging an indirect access permanent file.
- Describe the process for cataloging a direct access permanent file.
- Define a "hole" and discuss its use.
- Detail the Mass Storage Table words associated with permanent files.
- Explain what "catalog track overflow" is.
- Explain how more than one user can have access to a direct access file and a indirect access file.

REFERENCES:

NOS IMS - Chapter 14 NOS Reference Manual, 1-2-7, 1-8, 2-5 NOS IHB, 7-31-41 NOS SMRM, 1-1-19

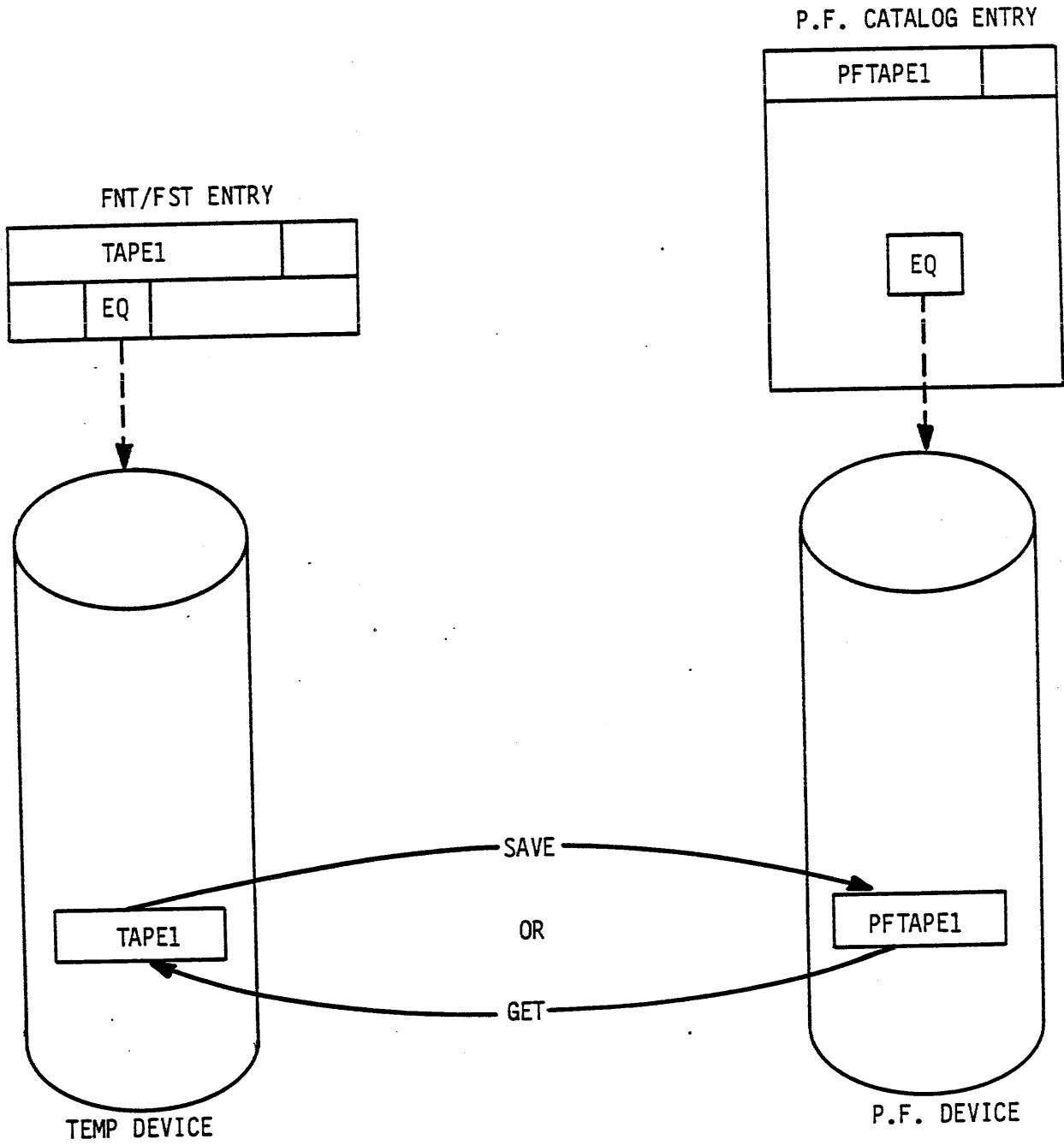
ASSIGNMENT:

Read NOS System Maintenance Reference Manual, pages 1-1 through 1- 19.

NOS PERMANENT FILE CONCEPTS

- NOS SUPPORTS TWO TYPES OF PERMANENT FILES.
 - DIRECT ACCESS FILES (DAFS)
 - INDIRECT ACCESS FILES (IAFS)
- MASS STORAGE DEVICES CONTAINING PERMANENT FILES ARE GROUPED INTO FAMILIES.
 - FILES MAY ALSO RESIDE ON PRIVATE PACKS.
- A PERMANENT FILE FAMILY CONSISTS OF MASTER DEVICES AND SECONDARY DEVICES.
 - MASTER DEVICES CONTAIN PERMANENT FILE CATALOG (PFC) ENTRIES, PERMIT AND ACCESS CHAINS, INDIRECT ACCESS FILES (IAFS), DIRECT ACCESS FILES (DAFS).
 - SECONDARY DEVICES CONTAIN DIRECT ACCESS FILES.
- PERMANENT FILE ACTIVITY IS CONTROLLED BY USER NAME, USER INDEX, AND INSTALLATION DEFINED LIMITS.

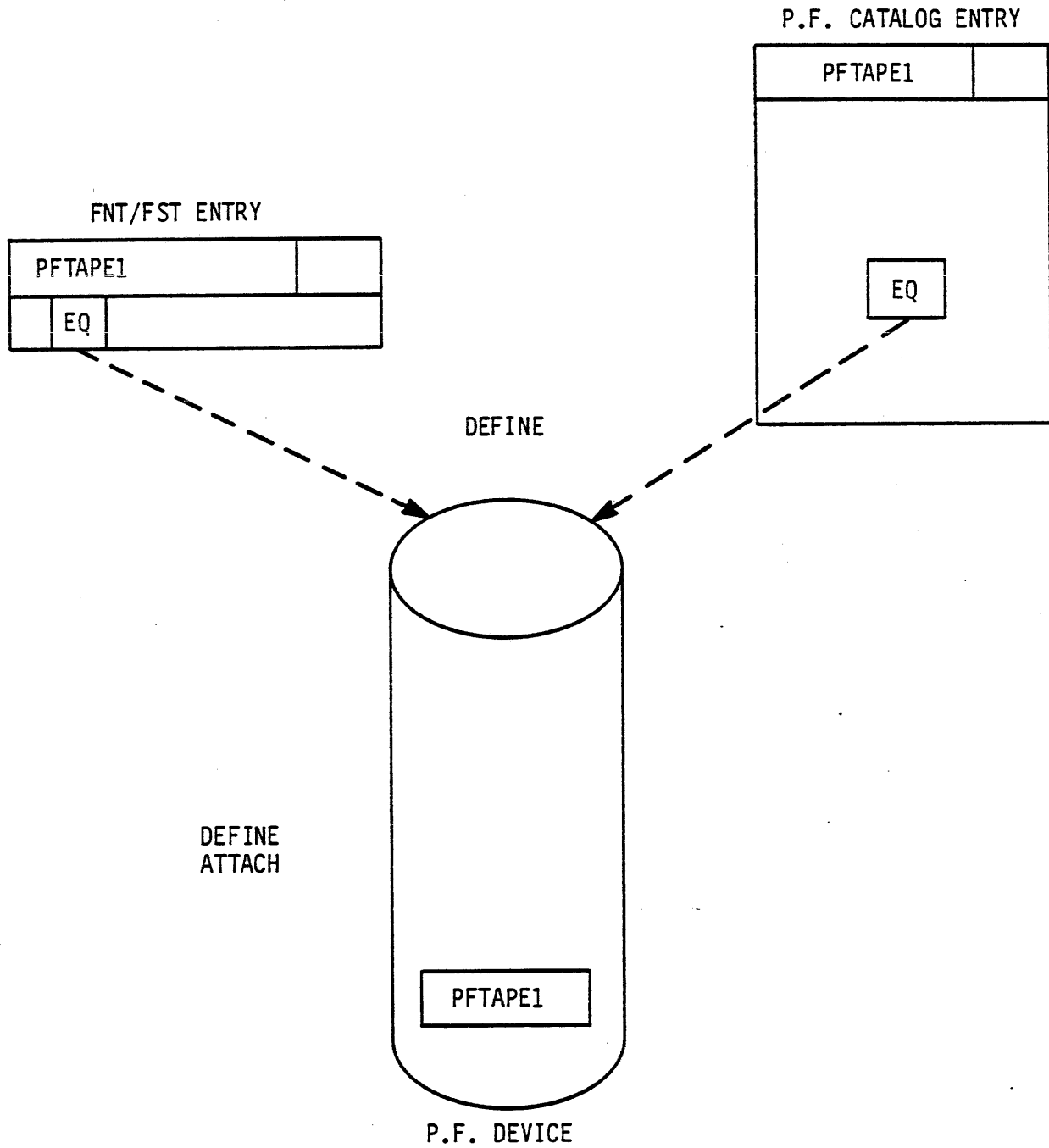
INDIRECT ACCESS PERMANENT FILE



INDIRECT ACCESS FILES

- USER OBTAINS AND MANIPULATES A LOCAL COPY OF THE FILE.
- THE PERMANENT COPY IS NOT CHANGED UNTIL THE USER DIRECTS THE SYSTEM TO REPLACE THE PERMANENT COPY OF FILE WITH THE LOCAL COPY.
- NORMALLY USED FOR RELATIVELY SMALL FILES. INDIRECT ACCESS FILE STORAGE IS ALLOCATED IN MASS STORAGE PRU INCREMENTS (100B CM WORDS).
- ALWAYS RESIDE ON THE OWNER'S MASTER DEVICE.

DIRECT ACCESS PERMANENT FILE



DIRECT ACCESS FILES

- USER ATTACHES AND MANIPULATES THE FILE ITSELF.
- SEVERAL USERS MAY SIMULTANEOUSLY ATTACH THE FILE IN READ MODE.
- NORMALLY USED FOR LARGE FILES. DIRECT ACCESS FILES ARE ALLOCATED IN INCREMENTS OF LOGICAL TRACKS.
- MAY RESIDE ON THE OWNER'S MASTER DEVICE OR ON A SECONDARY DEVICE.

NOS "FAMILY" CONCEPTS

- A FAMILY CONSISTS OF 1-8 MASTER DEVICES AND 0 OR MORE SECONDARY DEVICES. THE NUMBER OF SECONDARY DEVICES IS LIMITED BY PRACTICAL CONSIDERATIONS SUCH AS NUMBER OF MASS STORAGE DEVICES AVAILABLE, EST SIZE, ETC.
- IN A TYPICAL OPERATING ENVIRONMENT, EACH FAMILY CONTAINS A "VALIDUS" FILE WHICH IS A LIST OF VALIDATED USER NAMES AND CORRESPONDING USER INDICES AND OTHER INSTALLATION DEFINED VALIDATION LIMITS.
- ALL FILES AND CATALOG ENTRIES ASSOCIATED WITH A USER NUMBER/USER INDEX RESIDE WITHIN THE FAMILY IN WHICH THE USER NUMBER IS DEFINED.
- MORE THAN ONE FAMILY MAY BE ACTIVE DURING SYSTEM OPERATION. (USERS MUST SPECIFY A FAMILY NAME AT LOGIN TIME, OR ON THEIR USER STATEMENT IF THE DESIRED FAMILY IS NOT THE INSTALLATION DEFINED DEFAULT).
- EACH DEVICE WITHIN A FAMILY HAS A PRIMARY MASK AND SECONDARY MASK ASSOCIATED WITH IT.
 - MASKS ARE DEFINED BY SITE PERSONNEL.
 - MASKS ARE USED TO ASSIGN USER FILES, CATALOG ENTRIES, ETC., TO SPECIFIC DEVICES WITHIN A FAMILY.

PERMANENT FILES

ALL PERMANENT FILE ACTIVITY IS CONTROLLED BY THE USER'S USER NUMBER AND USER INDEX.

USER INDEX

- ABILITY TO USE PFS

DIRECT ACCESS FILES
INDIRECT ACCESS FILES
AUXILIARY COMMANDS
(REMOVABLE PACKS)

CLPF
CSPF
CSRP

- DETERMINE WHICH DEVICE IN THE FAMILY IS THE USER'S MASTER DEVICE.
- DETERMINE WHICH DEVICE IN THE FAMILY IS THE USER'S SECONDARY DEVICE.
- DETERMINE WHICH CATALOG TRACK HOLDS THE USER'S PERMANENT FILE CATALOG ENTRIES.

DIRECT ACCESS FILE - USER GETS FILE WITH ITS TRACK/SECTORS "LIVE".

INDIRECT ACCESS FILE - USER GETS COPY OF FILE, ORIGINAL FILE REMAINS UNTOUCHED UNLESS REPLACED/PURGED.

USER INDEX

- EACH USER NUMBER HAS A 17-BIT USER INDEX ASSOCIATED WITH IT. THIS ASSOCIATION IS THROUGH AN ENTRY IN THE *VALIDUS* FILE WHICH IS SET UP BY THE INSTALLATION.
- SPECIAL USER NAMES/USER INDICES

<u>USER NAME</u>	<u>USER INDEX</u>
SYSTEMX	377777B
LIBRARY	377776B

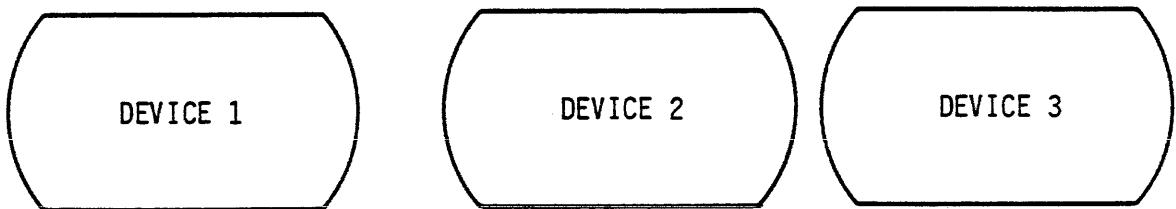
(NOT TO BE CONFUSED WITH THE NOS CONCEPT OF A USER OR SYSTEM LIBRARY OR THE *LIBRARY* CONTROL STATEMENT.)

- THE USER INDEX, TOGETHER WITH DEVICE MASK VALUES, DETERMINE WHICH DEVICE(S) THE USER'S FILES, CATALOG, AND PERMITS RESIDE.
- *SUI* CONTROL STATEMENT AND *SETUI* COMPASS MACRO SERVE TO PROVIDE SYSTEM ORIGIN JOBS WITH A CONVENIENT MEANS OF ACCESSING CATALOGS.

USING THE USER INDEX TO
LOCATE THE MASTER DEVICE

- NOTE:
- 1) THE USER'S MASTER DEVICE CONTAINS ALL CATALOG ENTRIES ASSOCIATED WITH A GIVEN USER INDEX/USER NAME.
 - 2) EACH USER INDEX HAS EXACTLY ONE MASTER DEVICE ASSOCIATED WITH IT.
 - 3) EACH MASTER DEVICE IN THE FAMILY HAS AN 8-BIT PRIMARY DEVICE MASK ASSOCIATED WITH IT.
 - 4) A FAMILY CAN CONTAIN AT MOST 8 MASTER DEVICE MASKS.
-
- 1) TAKE THE RIGHTMOST 3-BITS (OCTAL DIGIT) OF THE USER INDEX.
 - 2) BITS OF THE DEVICE MASKS ARE NUMBERED 0-7 WITH BIT 0 BEING THE RIGHTMOST BIT IN THE MASK.
 - 3) GIVEN THAT THE RIGHTMOST OCTAL DIGIT OF THE U.I. IS N, THE DEVICE WHOSE DEVICE MASK CONTAINS A 1 IN BIT POSITION N (SEE 2 ABOVE) IS THE MASTER DEVICE FOR THE U.I.

EXAMPLE:



MASK=061B
(00110001)

MASK=302B
(11000010)

MASK=014B
(00001100)

BIT POSITIONS

↑↑↑↑↑↑↑↑
76543210

↑↑↑↑↑↑↑↑
76543210

MASTER DEVICE

1
2
3
3
1
1
2
2

RIGHTMOST OCTAL DIGIT OF U.I.

0
1
2
3
4
5
6
7

SAMPLE U.I.

001467B
100104B
000012B

DEVICE NO.

2
1
1

NOTE: THE LOGICAL SUM OF ALL PRIMARY DEVICE MASKS WITHIN A FAMILY MUST BE 377B.
 MASTER DEVICE ASSIGNMENTS MUST BE UNIQUE.

FROM OUR PREVIOUS
 EXAMPLE

DEVICE 1 MASK = 00110001 (061B)
 DEVICE 2 MASK = 11000010 (302B)
 DEVICE 3 MASK = 00001100 (014B)

LOGICAL SUM = 11111111 (377B)

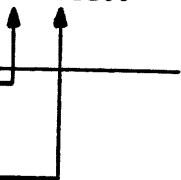
EACH COLUMN
 MUST HAVE
 EXACTLY ONE 1
 IN IT.

INVALID DEVICE
 MASK ASSIGNMENT

DN1 00110001
 DN2 01010010
 DN3 00001100

NO 1'S IN
 THIS COLUMN

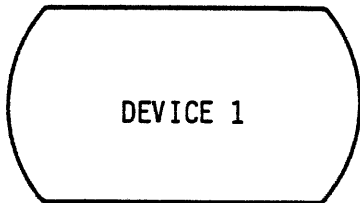
MORE THAN ONE
 1 IN THIS COLUMN



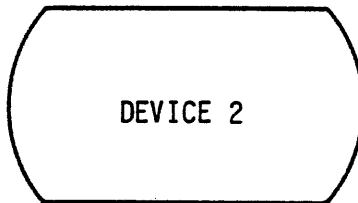
USING THE USER INDEX TO
LOCATE THE CATALOG TRACK
ON THE MASTER DEVICE

- NOTE: 1) EACH MASTER DEVICE CONTAINS A PREALLOCATED NUMBER OF TRACKS WHICH ARE RESERVED FOR CATALOG ENTRIES.
- 2) THE NUMBER OF CATALOG TRACKS ON EACH DEVICE IS INSTALLATION DEFINABLE.
- 3) THE NUMBER PREALLOCATED OF CATALOG TRACKS ON EACH DEVICE MUST BE AN EXACT POWER OF 2 IN THE RANGE 1B-200B (2^{**N} , $0 \leq N \leq 7$).
- 4) PROVISION IS MADE FOR CATALOG TRACK OVERFLOW.
-
- 1) DELETE THE RIGHTMOST 3 BITS (OCTAL DIGIT) FROM THE USER INDEX.
- 2) FORM A MASK BY SUBTRACTING 1 FROM THE NUMBER OF PREALLOCATED TRACKS FOR THE DEVICE. THIS MASK WILL BE N-BITS LONG WHERE N IS THE POWER OF 2 DEFINING THE NUMBER OF CATALOG TRACKS.
- 3) FORM THE LOGICAL PRODUCT BETWEEN THE MASK IN 2) AND THE RIGHTMOST N-BITS OF THE VALUE OBTAINED IN 1). THE RESULT IS THE NUMBER OF THE LOGICAL TRACK CONTAINING CATALOG ENTRIES FOR THE GIVEN U.I.

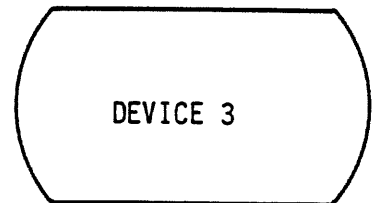
EXAMPLE:



MASK = 00110001 (061B)
 NC = 100000 (40B)



11000010 (302B)
 10000 (20B)



00001100 (014B)
 1000000 (100B)

<u>UI</u>	<u>MASTER DEVICE</u>	<u>CATALOG TRACK</u>	
123456 B	2	001010011100101	(12345B)
		NC-1 = 001111	(17B)
		LOGICAL PRODUCT = 101	5B
		CATALOG TRACK = 101	5B
1433 B	3	001100011	(143B)
		NC-1 = 111111	(77B)
		LOGICAL PRODUCT = 100011	(43B)
		CATALOG TRACK = 100011	(43B)

RIGHTMOST OCTAL DIGIT
 DETERMINES MASTER DEVICE

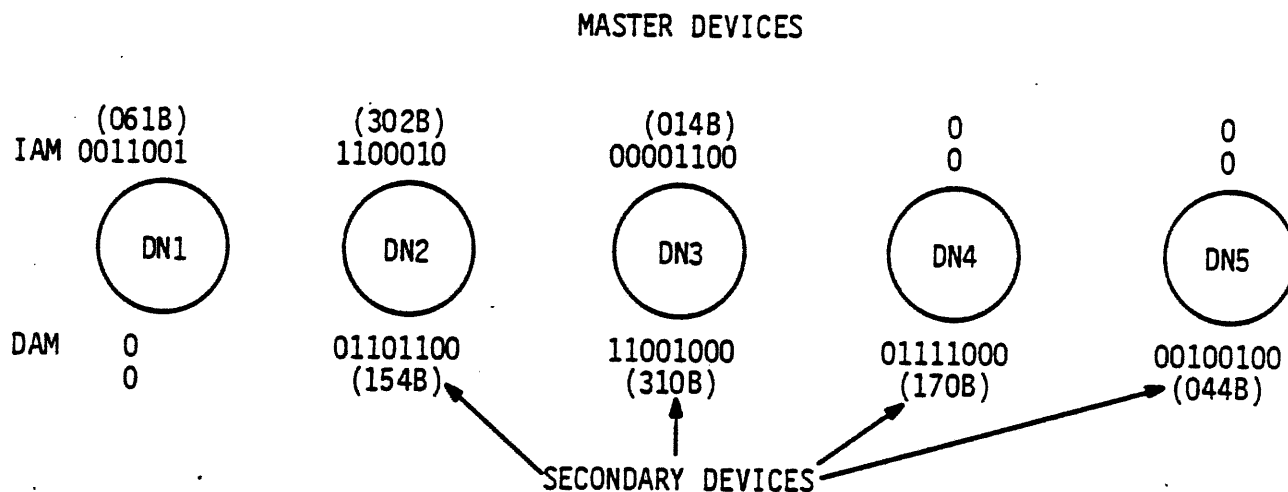
REMAINING OCTAL DIGITS
 DETERMINES CATALOG TRACK

SECONDARY DEVICE MASKS

- 1) USED TOGETHER WITH THE U.I. TO ASSIGN DIRECT ACCESS FILES TO DEVICES.
- 2) THE LOGICAL SUM OF SECONDARY DEVICE MASKS NEED NOT BE 377B.
- 3) BIT ASSIGNMENTS NEED NOT BE UNIQUE.
- 4) MORE THAN 8 SECONDARY DEVICES MAY BE PRESENT WITHIN A FAMILY.
- 5) A SECONDARY DEVICE MAY ALSO BE A MASTER DEVICE, BUT NEED NOT BE.
- 6) USER INDICES ARE ASSOCIATED WITH SECONDARY DEVICE MASKS IN A MANNER SIMILAR TO PRIMARY DEVICE MASKS.

EXAMPLE:

IAM = PRIMARY DEVICE MASK
 DAM = SECONDARY DEVICE MASKS



PFFAM

DN	UI'S	SECONDARY MASKS	
1	NONE	00000000	0
2	6, 5, 3, 2	01101100	154B
3	7, 6, 3	11001000	310B
4	6, 5, 4, 3	01111000	170B
5	5, 2	00100100	044B
LOGICAL SUM =		11111100	

NOTE: UI'S ENDING IN 1 OR 0 CANNOT HAVE DIRECT ACCESS FILES.

THE CATALOG ENTRY FOR A DAF MAY BE ON A DIFFERENT DEVICE FROM THE FILE ITSELF.

PERMANENT FILE CATALOG ENTRY

	59	56	53	47	44	41	35		23	17	11	0
word 0	file name										user index	
1	file length								track		sector	
2	random index						creation date and time					
3	access count						data modification date and time					
4	ct	mode	ef	ec	dn	last access date and time						
5							control modification date and time					
6	pr	br	ss			utility control date and time						
7	file password											
8												
9												
10												
11												
12												
13												
14	user control word											
15	reserved for installation											

CATALOG TRACK ORGANIZATION

- 1) 4 PFC ENTRIES PER PRU.
- 2) NUMBER OF PRU'S PER TRACK IS DEVICE DEPENDENT.
- 3) AVAILABLE PFC ENTRIES HAVE UI=0. ENTRIES ARE REUSED WHEN FILES ARE PURGED.
- 4) CATALOG TRACK IS SEARCHED SEQUENTIALLY.
- 5) CATALOG TRACK OVERFLOW IS HANDLED USING TRACK LINKING.

PERMANENT FILES

PF PERMIT ENTRY

35		11			
NEXT RANDOM INDEX		USER INDEX		FPRI	FPUI
MODIFICATION DATE/TIME				FPUD	
PERMITTED USER NUMBER		USER INDEX		FPAN	FPPI
ACCOUNT COUNT	MO	ACCESS DATE/TIME		FPAC	} PERMIT ENTRY
				FPMD	
				FPAD/FPAT	

OVERFLOW TO NEXT SECTOR

NEXT RANDOM INDEX IF OVERFLOW FOR THIS FILE = 0 IS THE END FOR THIS FILE.

EXPLICIT - OWNER DEFINES PERMIT ALLOWING OR DISALLOWING ACCESS AND MODE FOR THE PERMITTED USER.

IMPLICIT - AUTOMATIC RECORDING OF ACCESS BY ANY USER TO SEMI-PRIVATE FILE WHEN ACCESS IS MADE.

MASTER USER

*IN USER NUMBER OK
NON-* MUST MATCH

USER*** U*S*E*R
USERABC U1S1E2R

AUTOMATIC READ ONLY PERMISSION TO FILES IN THAT USER'S CATALOG.

CATLIST,LO=F.

CATALOG OF ARR2061

FM/NOSCLSH 79/10/22. 09.35.57.

FILE NAME ACCESS FILE-TYPE LENGTH DN CREATION ACCESS DATA MOD
PASSWORD MD/CNT INDEX PERM. SUBSYS DATE/TIME DATE/TIME DATE/TIME
PR BR RS

1	CASDATA	DIR. PRIVATE	32	*	79/09/10.	79/10/17.	79/10/17.
		63	WRITE		15.38.43.	15.50.44.	15.48.56.
	N Y D						
2	MIKEY	DIR. SEMI-PR	377	*	79/04/23.	79/09/19.	79/07/20.
		184	READ		15.40.13.	16.15.59.	13.47.01.
	N Y D						
3	FRED	IND. PRIVATE	1		79/08/22.	79/09/06.	79/08/22.
		10	WRITE FTNTS		16.19.54.	13.07.22.	16.19.54.
	N Y D						
4	PROCFIL	IND. PRIVATE	2		79/09/07.	79/10/16.	79/09/07.
		42	WRITE		11.05.19.	16.11.52.	15.54.25.
	N Y D						
5	CASTPSR	DIR. PRIVATE	3	*	79/09/06.	79/10/17.	79/09/06.
		51	WRITE		09.22.29.	15.50.41.	09.22.29.
	N Y D						
6	CNTCRDS	IND. PRIVATE	20		79/09/07.	79/10/16.	79/09/07.
		32	WRITE		11.05.20.	16.11.53.	11.05.20.
	N Y D						
7	EJECT	IND. PRIVATE	3		79/09/07.	79/10/16.	79/09/07.
		32	WRITE		11.05.19.	16.11.53.	11.05.19.
	N Y D						
8	QUCAT	DIR. PRIVATE	27	*	79/09/07.	79/10/17.	79/09/07.
		13	WRITE		08.39.51.	15.29.15.	08.39.51.
	N Y D						
9	IMT15	IND. PRIVATE	2		79/09/19.	79/09/20.	79/09/19.
		1	WRITE		14.40.31.	14.44.32.	14.40.31.
	N Y D						

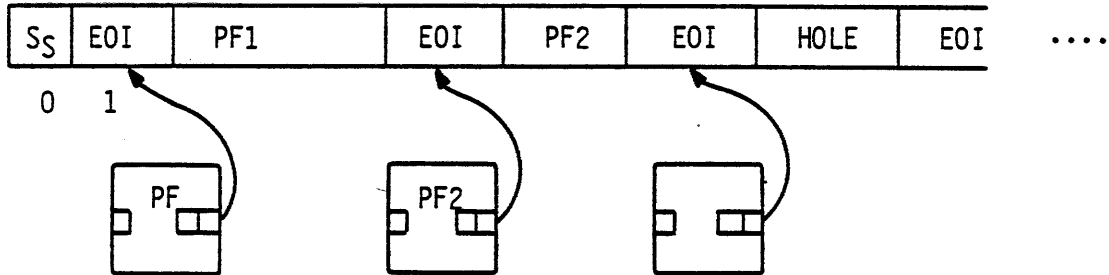
5 INDIRECT ACCESS FILE(S), TOTAL PRUS = 28.
4 DIRECT ACCESS FILE(S), TOTAL PRUS = 439.

READY.

PERMANENT FILES

IAF CREATION

IAF (DATA) CHAIN ON MASTER DEVICE



- SAVE/REPLACE (NO EXISTING FILE)
- HOLE WITH EXACT FIT
- LARGEST HOLE LARGER THAN FILE
- END OF IAF CHAIN
- BUILD CATALOG ENTRY
- REPLACE (EXISTING FILE)
- SAME SIZE - WRITE OVER EXISTING DATA
- OLD FILE LARGER - WRITE OVER EXISTING DATA; CREATE HOLE ENTRY IF RESIDUE GREATER THAN ONE SECTOR.
- OLD FILE SMALLER - OLD ENTRY MADE INTO HOLE ENTRY, FIND NEW HOLE (AS ABOVE)

HOLE

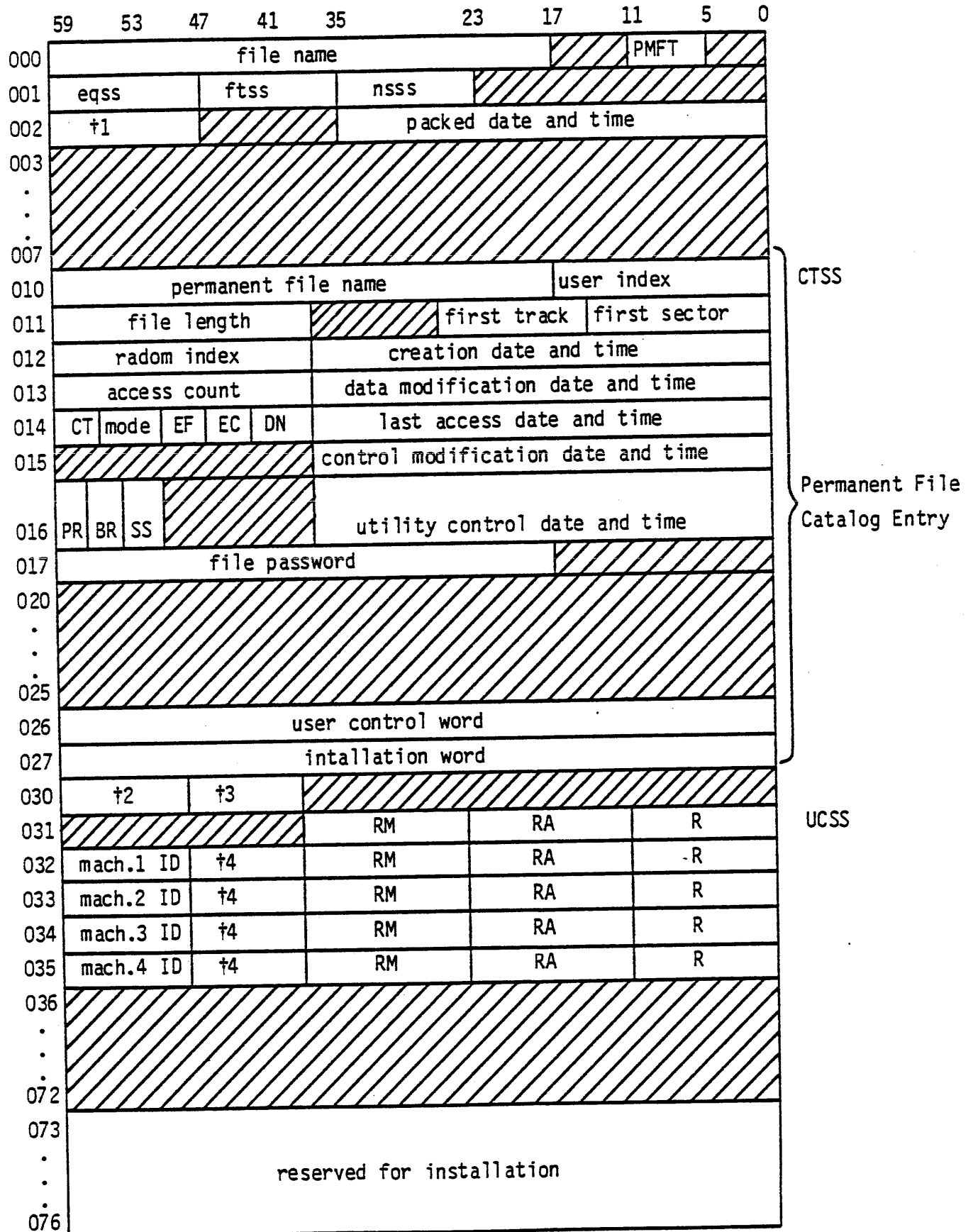
- CATALOG ENTRY POINTING TO UNUSED SPACE
- HAS $UI=0$ WITH SAME TRACK, SECTOR AND LENGTH VALUES

PERMANENT FILES

DAF CREATION

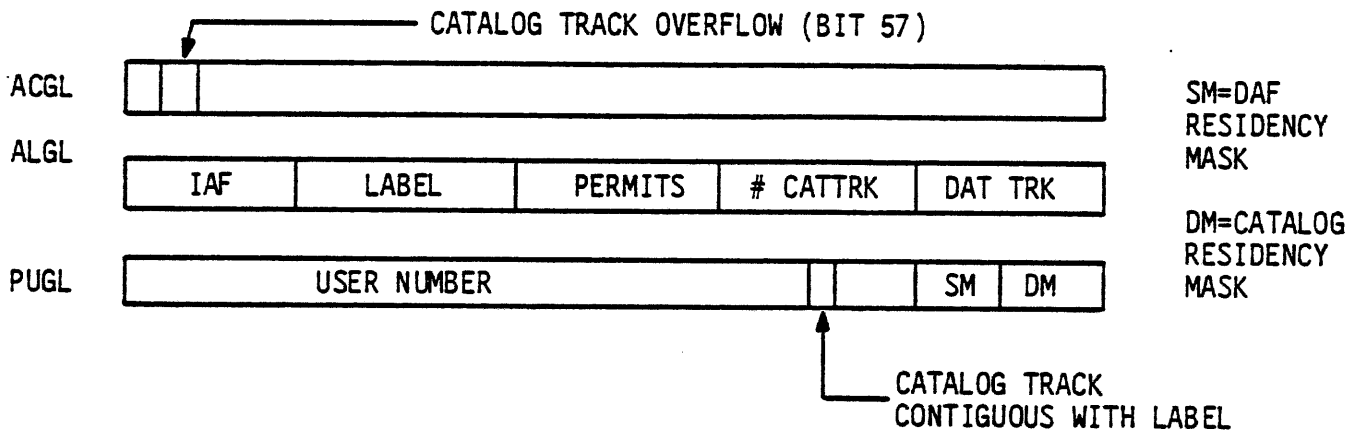
- CATALOG IS ON MASTER DEVICE.
- PERMITS ON MASTER DEVICE.
- FILE RESIDENCY DETERMINED BY SECONDARY MASK.
- DEFINE.
 - IF FILE NOT PRESENT ON SECONDARY DEVICE, CONTINUE; OTHERWISE ABORT.
 - IF NOT PRESENT, SELECT SECONDARY DEVICE IN FAMILY WITH MOST SPACE.
 - REQUEST SPACE ON SELECTED DEVICE.
 - BUILD CATALOG ENTRY ON MASTER DEVICE WITH DN FOR SECONDARY DEVICE.
 - SET FIRST TRACK
 - SET SECTOR TO 4000
 - WRITE SYSTEM SECTOR
 - PRESERVE FILE BY SETTING PRESERVE TRT BIT FOR FIRST TRACK VIA STBM.
 - WRITE EOI AT SECTOR 1.
- WHEN FILE RETURNED, ODF (DROP FILE) DETECTS PMFT AND CALLS ORP WHICH UPDATES SYSTEM SECTOR MODES, DATES, SECTOR LENGTH.

Direct Access File System Sector Format



PERMANENT FILES

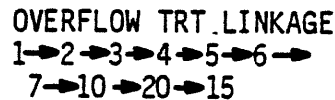
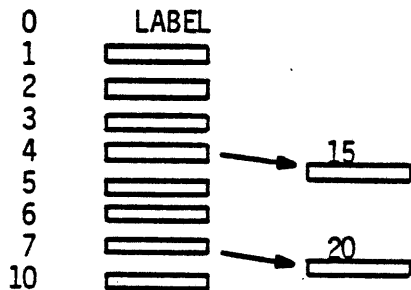
MST



IN TRT, CATALOG TRACK CHAIN IS LINKED BUT INDIVIDUAL SECTOR LINKAGE IS NOT PRESENT EXCEPT FOR CATALOG TRACK OVERFLOW.

ON CATALOG TRACK OVERFLOW, THE TRT LINKAGE IS TO THE OVERFLOW TRACK BUT ONLY THE TRACK THAT OVERFLOWS POINTS TO AN OVERFLOW TRACK.

TRK



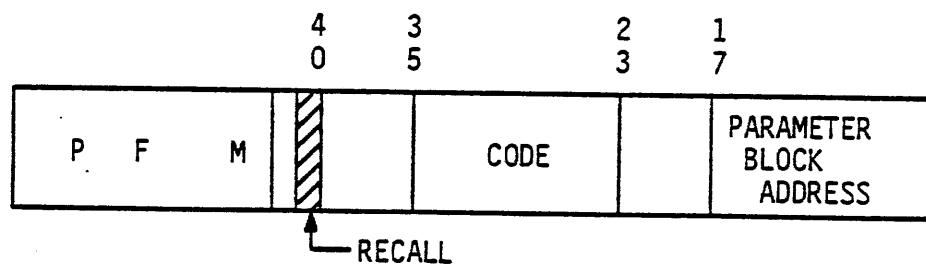
PERMANENT FILES

<u>FUNCTION CODE</u>	<u>MACRO</u>	<u>CONTROL STATEMENT</u>
1 CCSV	SAVE	SAVE
2 CCGT	GET	GET
3 CCPG	PURGE	PURGE
4 CCCT	CATLIST	*CATLIST
5 CCPM	PERMIT	PERMIT
6 CCRP	REPLACE	REPLACE
7 CCAP	APPEND	APPEND
10 CCDF	DEFINE	DEFINE
11 CCAT	ATTACH	ATTACH
12 CCCG	CHANGE	CHANGE *PURGALL

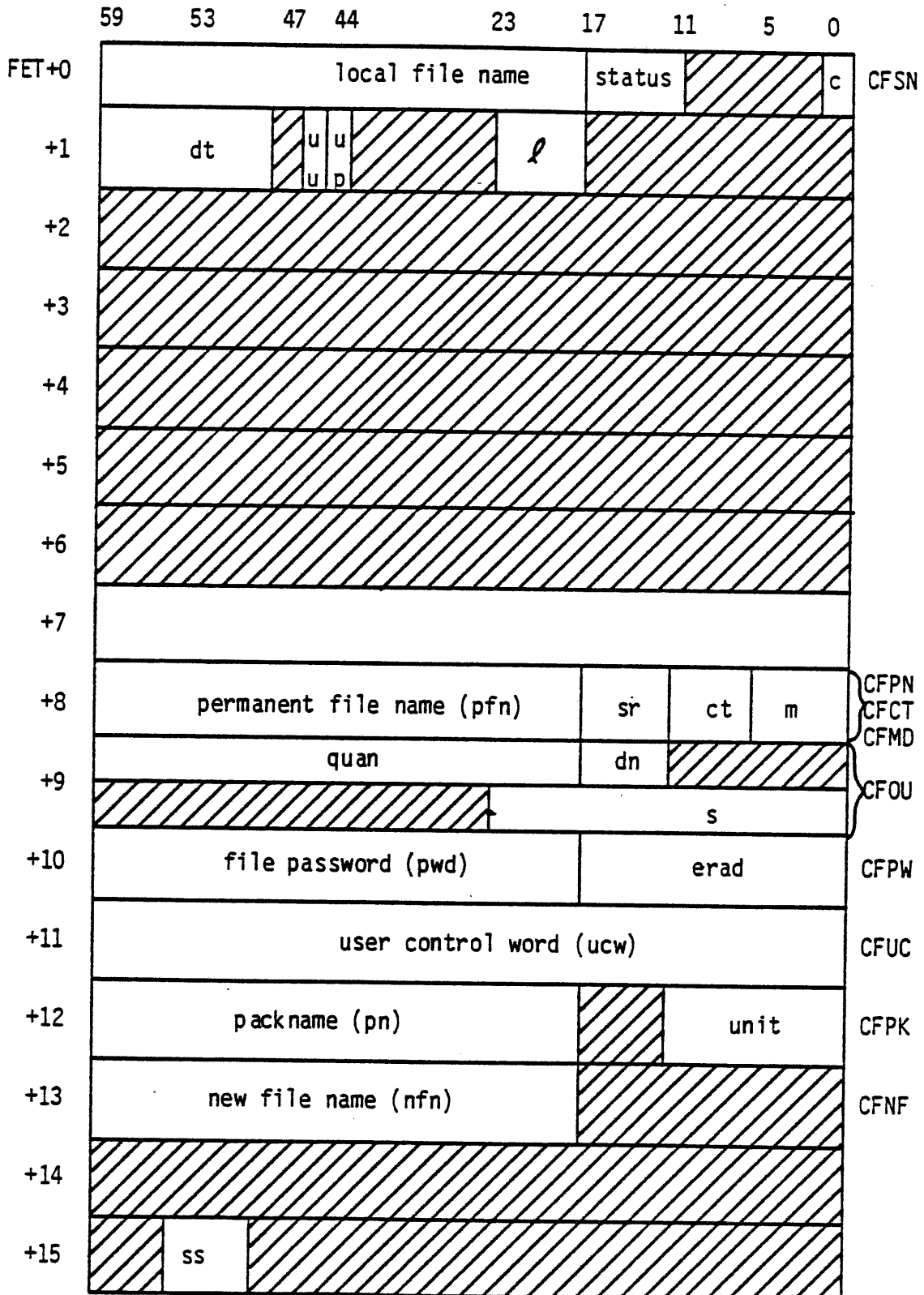
2000 + CODE IGNORE DEFAULT PACKNAME

1000 + CODE USE DEFAULT FAMILY

*OWN ROUTINES,
OTHERS IN PFILES



PFM FET



PERMANENT FILES

STRUCTURE OF PFM

PRESET

OVERLAYS

3PA	COMMAND PROCESSOR
3PB	SAVE/REPLACE
3PC	APPEND
3PD	ATTACH
3PE	CATALOG LIST
3PF	DEFINE
3PG	PERMIT/PURGE
3PH	ERROR PROCESSOR
3PI	AUXILIARY ROUTINES
3PJ	CHANGE
3PK	DEVICE-TO-DEVICE
3PL	APPEND - ORIGINAL MOVE
3PM	DEFINE AUXILIARY

PRESET

- VERIFY PARAMETERS IN CALL BLOCK
- VERIFY VALIDATION CONSTRAINTS
- RECALL IF CATALOG TRACK INTERLOCKED
- ISSUE ACCOUNTING MESSAGES
- CALL RESOURCE EXECUTIVE (RESEX.)
- PROCESS FUNCTION (LOAD 3PA OR 3PE)

EXAMPLE

GET

1. DO IPAS/IAUM FUNCTION TO INCREMENT PF ACTIVITY.
2. FIND DEVICE WITH CATALOG.
3. TEST FOR PF UTILITY ACTIVE VIA TUAS/STBM.
4. DETERMINE IF TRACK (CATALOG TRACK) IS INTERLOCKED. COMMON DECK COMPDTS DOES THIS; IN A MMF CONDITION, DTS ISSUES A ECSM TO HAVE CPUMTR READ THE TRT WORD FROM THE ECS COPY OF THE TRT.
5. SET CATALOG TRACK INTERLOCK. COMMON DECK COMPSTI DOES THIS VIA STIS/STBM.
6. READ CATALOG TRACK AND FIND ENTRY.
7. UPDATE CATALOG ENTRY AND PERMITS.
8. REQUEST TRACKS ON TEMP DEVICE VIA RTCM.
9. LOAD 3PK AND DO DEVICE-TO-DEVICE TRANSFER.
10. WRITE EOI SECTOR AND UPDATE TRACK CHAIN VIA DTKM.
11. CLEAR CATALOG TRACK INTERLOCK. COMMON DECK COMPCTI DOES THIS VIA CTIS/STBM.
12. DECREMENT PF ACTIVITY BY DOING A DPAS/IAUM.

WITH THE EXCEPTION OF CODE IN COMPDTS TO READ TRT WORD FROM ECS, THIS LOGIC IS TRANSPARENT TO ANY MMP CONSIDERATIONS.

IN MOST CASES, SYSTEM CODE FOLLOWS SINGLE MAINFRAME DESIGN AND LETS CPUMTR MANAGE THE ACTUAL MAINFRAME ENVIRONMENT BY PRESETTING INDIVIDUAL MONITOR FUNCTIONS (RTCM, DTKM, DLKM, IAUM, STBM) TO REFLECT A STAND-ALONE OR MMF CONDITION.

QUESTION SET LESSON 16

1. How does PFM keep track of "holes" in the indirect chain?
2. What implied permission does user number USER*** have to files belonging to user number USERXYZ?
3. What is the difference between a semi-private and a public (library) file?
4. Must indirect access permanent files reside on a user's master device? Must direct access permanent files reside on a user's master device?
5. Is multi-read access possible with direct access permanent files? If so, how is it implemented?
6. Why is multi-read access no problem when working with indirect access permanent files?
7. What happens when a direct access file is ATTACHed with WRITE permission? If one user attaches a file with WRITE permission, can another user attach this file? Why?
8. What happens when a direct access file is PURGEd? An indirect access file is PURGEd?
9. What happens if the user DEFINEs an existing file that resides on a device not configured to hold direct access permanent files? Could this situation ever occur?
10. What happens when the user SAVEs a file? REPLACEs a file?

The following questions apply to family NOSCLSH and each equipment in this family. Use the study dump to answer these questions.

11. What is the first track of the indirect file chain? The permit chain?
12. How many tracks are allocated to indirect access permanent files? How did you derive your answer?

13. How many tracks are allocated for permit entries? For catalog entries?
14. What are the device masks and secondary masks for each equipment in the family?
15. Has catalog track overflow occurred on any of the equipments? How did you derive your answer?

For the following questions, family PSD has been defined as follows:

```

EQ4=DI-1,ON,0,0,5.
EQ5=DI-1,ON,0,1,5.
EQ6=DI-1,ON,0,2,5.
EQ7=DI-2,ON,0,3,5.
PF=4,F,201,303,PSD,7,10.
PF=5,F,102,303,PSD,6,40.
PF=6,F,44,74,PSD,5.
PF=7,F,30,74,PSD,4.

```

Assume all devices have no tracks flawed.

16. What tracks are in the catalog track chain for EQ4?
17. Complete the following table:

User Index Ending In Digit -----	Master Device -----	Secondary Device -----
0	-----	-----
1	-----	-----
2	-----	-----
3	-----	-----
4	-----	-----
5	-----	-----
6	-----	-----
7	-----	-----

18. What is the master device/catalog track mapping for user 1231? For user index 1237?

```

1231 master ----- catalog track -----
1237 master ----- catalog track -----

```

19. How many catalog tracks on device 4? On device 5?
20. Track 4234 is the first available track. If the second catalog track on device 7 overflows, describe the TRT and mass storage linkages.

LESSON 17
RESOURCE CONTROL

LESSON PREVIEW:

In this lesson, the student will learn the concepts of the allocation of magnetic tape and removable pack resources in NOS. The lesson consists of discussion on the resource executive (RESEX) and the files it uses, deadlock prevention, and magnetic tape assignment control statements.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Discuss the resource deadlock prevention mechanism employed by NOS.
- Detail the contents of the resource files and the relationships between them and FNT/FST entries for files residing on the magnetic tape and removable pack resource units.
- Discuss the role of routine ORF.
- Identify control statements processed by RESEX.
- Explain the terms "internal call" and "external call" to the resource executive.

REFERENCES:

NOS IMS - Chapter 12 NOS RM, 1-6-18-22

RESOURCE CONTROL

RESEX - RESOURCE EXECUTIVE MANAGES THE ALLOCATION OF MAGNETIC TAPE AND REMOVABLE PACK RESOURCES IN SUCH A WAY AS TO PREVENT A DEADLOCK FROM OCCURRING.

DEADLOCK

RESOURCE UNIT

RESOURCE TYPE

RESOURCE DEMAND

DEMAND COUNT

ASSIGN COUNT

DEMAND FILE

DEMAND FILE ENTRY

VSN FILE

VSN FILE ENTRY

RESOURCE ENVIRONMENT

SHARE TABLE

OVERCOMMITMENT ALGORITHM

PACK SHARING

SMALLEST SPINDLE RESIDUE

RESOURCE CONTROL

DEADLOCK PREVENTION

1. RESOURC CONTROL STATEMENT REQUIRED FOR ANY JOB USING MORE THAN ONE RESOURCE UNIT CONCURRENTLY.
2. RESEX BUILDS DEMAND FILE ENTRY FOR THE JOB AND WRITES IT TO THE DEMAND FILE. THE ENTRY IS USUALLY BUILT FROM THE RESOURC STATEMENT, WHICH TELLS WHAT THE JOB'S CONCURRENT DEMANDS ARE, AND INCLUDES THE JOB SEQUENCE NUMBER (RFCW) AND JOB NAME (JNMW).
3. RESEX VALIDATES THE DEMAND TO DETERMINE IF ENOUGH RESOURCE UNITS EXIST TO SUPPORT THE DEMAND AND THE USER IS VALIDATED TO HAVE THAT MANY RESOURCE UNITS (MT AND RP). THE VERIFICATION OF THE USER'S VALIDATION TO USE THE RESOURCE UNIT (CAND/CSOJ OR CSRJ) WILL OCCUR WHEN USER ATTEMPTS TO ASSIGN THE UNIT.
4. WHEN ATTEMPT IS MADE TO ASSIGN RESOURCE UNITS, RESEX VERIFIES THAT THERE EXISTS A SEQUENCE OF JOB COMPLETIONS SUCH THAT ALL JOBS WITH ASSIGNED RESOURCES WILL COMPLETE.

RESOURCE CONTROL

DEADLOCK PREVENTION

5. BUILD "SCRATCH" FILE OF ALL JOBS WITH ASSIGNED RESOURCES.

STEP 1, READ SCRATCH FILE ENTRY

ARE JOB'S DEMANDS SATISFIABLE?

- CHAIN PACKS IF NECESSARY

IF YES, LOGICALLY RETURN ALL RESOURCE UNITS AND GO READ NEXT SCRATCH FILE ENTRY (STEP 1)

IF NO, COPY ENTRY TO SECOND SCRATCH FILE AND GO READ NEXT SCRATCH FILE ENTRY (STEP 1)

- AT EOR,
- A) IF SECOND SCRATCH FILE IS EMPTY, ALL JOBS HAVE COMPLETED AND EVERYTHING IS OK!
 - B) FIRST SCRATCH = SECOND SCRATCH, OVER-COMMITTED (I.E., DEADLOCK)
 - C) SWITCH SCRATCH FILES, REWIND, GO TO STEP 1.

6. IF OK, ASSIGN RESOURCE.
IF OVERCOMMITTED, ABORT OR ROLLOUT.

RESOURCE CONTROL

RESOURCE FILES

RSXDid - DEMAND FILE

RSXVid - VSN FILE

EACH FILE HAS ENTRY = ONE PRU

FILE BUILD AND UPDATED BY RESEX
ENTRIES UPDATED/CLEARED BY ORF

ENTRY STRUCTURE DEFINED IN COMMON DECK
COMSRX

HEADER (IDENTIFIES JOB)

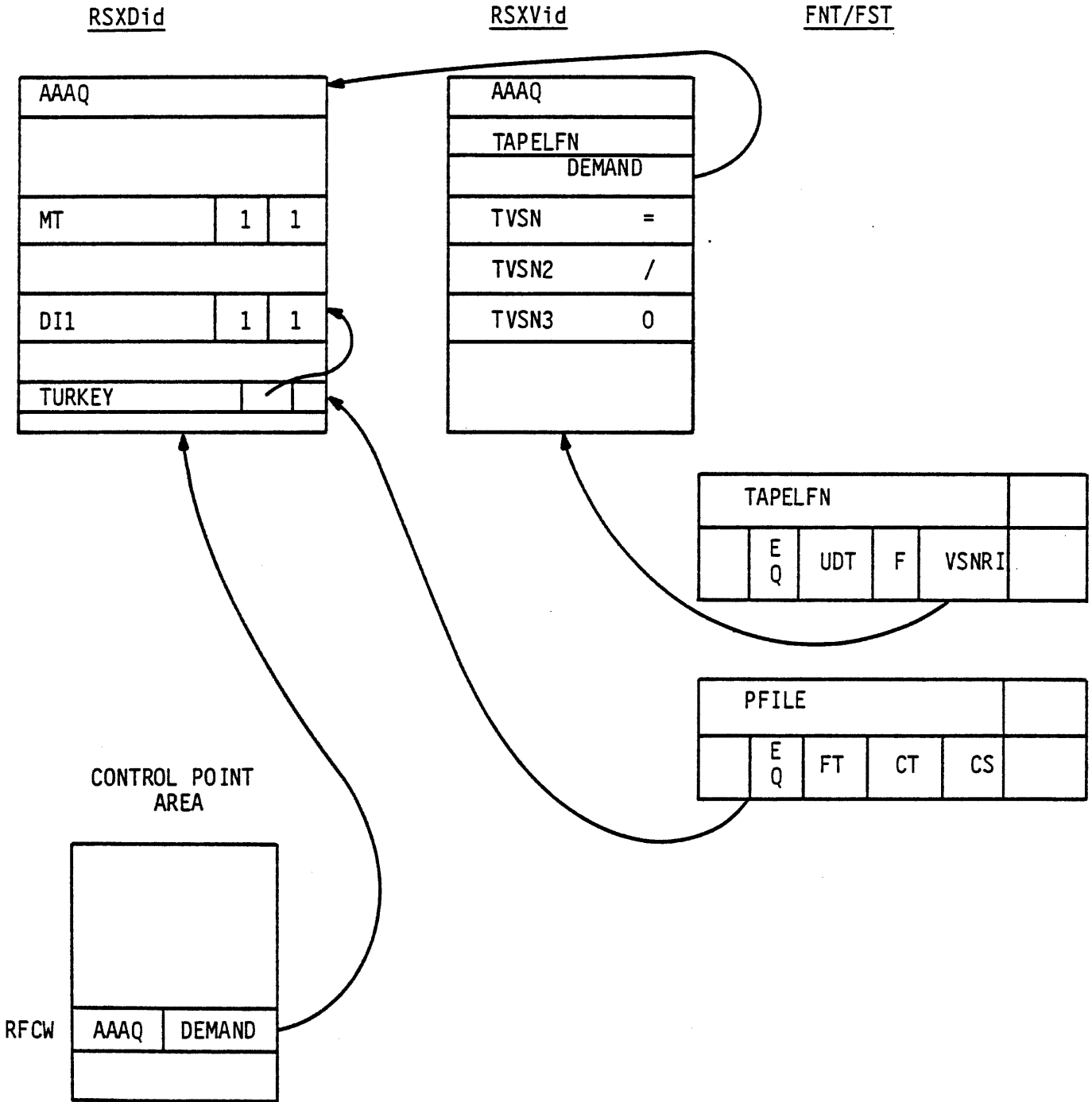
DEMANDS (RSXDid)

- ASSIGN COUNT
- DEMAND COUNT
- VALIDATION MT/RP
- PREVIEW DATA
- SHARE TABLE

VSN (RSXVid)

- FILE NAME
- DEMAND ADDRESS AND INDEX
- VSN WITH SEPARATOR
- 0 = END
- / = MULTIPLE
- = = EQUIVALENCE

RESOURCE CONTROL

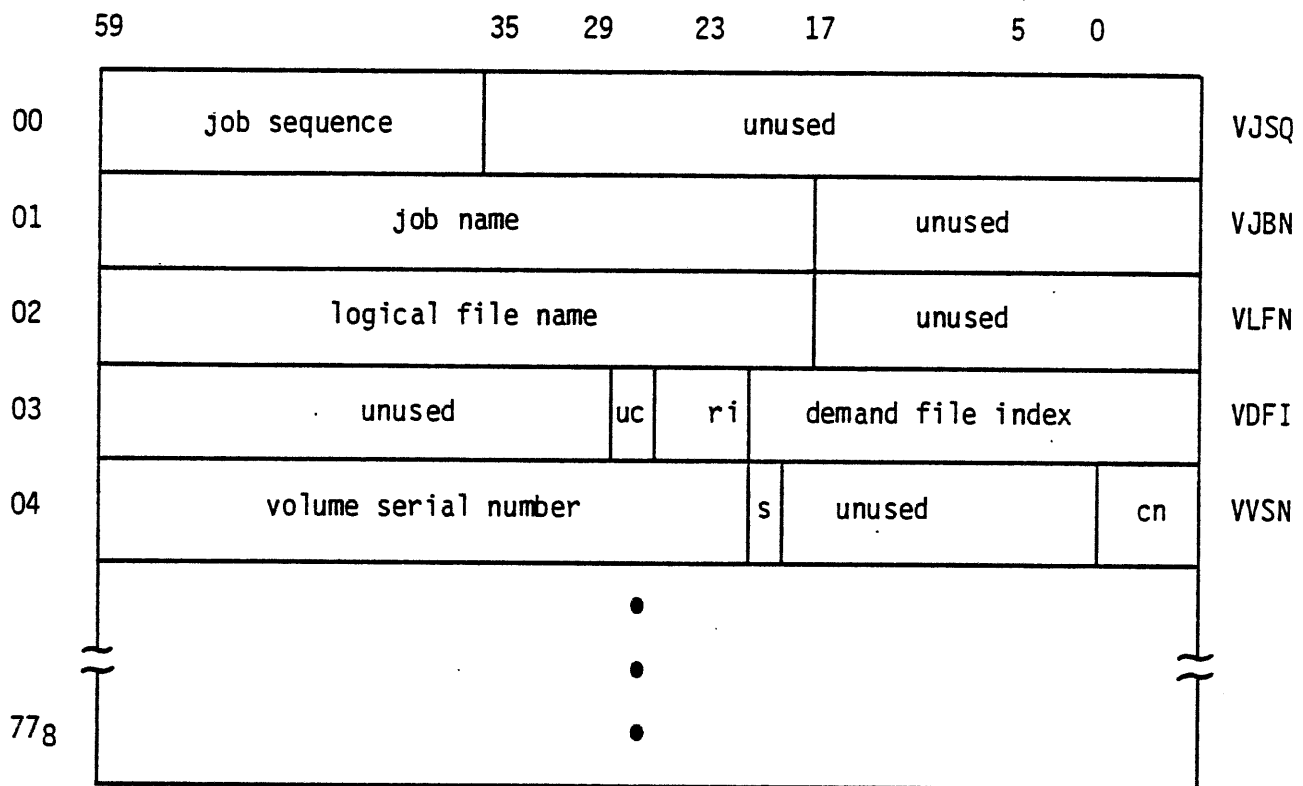


VSN File Entry (RSXVid)

The VSN file (RSXVid) contains the volume serial numbers associated with a particular file (refer to figure below). The entries in the VSN file contain the random index of the job's entry in the demand file and the resource index of the assigned tape within the demand file. The entries in these two files are associated with a particular job and are identified by the job's sequence number. Entries in both files are one PRU (64 words) in length.

These files are updated by RESEX and PP routine ORF. Routine ORF (described later in this section) updates demand and VSN file entries upon the return/unload of a tape file or the job's last direct access file on a pack and at job completion.

VSN File Entry (RSXVid)



- uc Unit count (always 1)
- ri Resource index; points to a word in the demand file entry between RMTP and RGEF; zero if tape is not yet assigned
- s Scratch VSN (if set)
- cn Control byte as follows:

<u>Value</u>	<u>Meaning</u>
/	Multireel
=	Alternate reel
0	End of entries

RESEX/MAGNET Call Block

	59	47	35	29	23	17	11	5	0
RCAL+0	fc	interlock							
+1	0	ec	0	user options			UDT address		
+2	0						den	cnv	
+3	word count	ouc	format	est	ns	software options			
+4	sequence number		0	vsn	VSN random address				
+5	job name					org	0		
+6	volume serial number				0				
+7	user number					fm	0		

fc Function code (0=assign unit, 1=set error code in UVSN word of UDT)
 ec Error code for function 1
 den Density
 cnv Conversion
 ouc Overflow unused characters
 est EST ordinal
 ns Noise
 vsn VSN index
 org Job origin
 fm Family ordinal

RMT then updates the job's demand file entry, builds the preview display buffer, and performs any file opening required. RMT exits and control is returned to the routine that called RESEX. The format of the preview display buffer is as follows.

RESOURCE CONTROL

ORF - UPDATE RESOURCE FILES

CLEANS UP VSN AND DEMAND FILES WHEN FILE RETURN/UNLOADED/EVICTED OR AT JOB COMPLETION

- PACKS, CALLED WHEN LAST (DAF) FILE ON PACK (FOR JOB) IS RETURNED/UNLOADED
 - CLEAR SHARE TABLE ENTRY
 - DECREMENT ASSIGN COUNT
 - DECREMENT DEMAND COUNT IF RETURN AND TOTAL DEMAND MET
 - DOES NOT DECREMENT DEMAND COUNT ON UNLOAD
- TAPES, CALLED WHEN FILE RETURNED/UNLOADED
 - CLEAR VSN ENTRY
 - DECREMENT ASSIGN COUNT
 - DECREMENT DEMAND COUNT IF RETURN AND TOTAL DEMAND MET
 - DOES NOT DECREMENT DEMAND COUNT ON UNLOAD
 - CALLS MAGNET TO PHYSICALLY PROCESS THE TAPE (TDAM REQUEST)
- IF ONLY ONE DEMAND, CLEARS ENTIRE ENTRY
- VSN (UNASSIGNED), CALLED WHEN FILE RETURNED OR UNLOADED
 - CLEAR VSN ENTRY
- AT END OF JOB, CLEAR DEMAND FILE ENTRY

RESOURCE CONTROL

TAPE ASSIGNMENT CONTROL STATEMENTS

ASSIGN
REQUEST
LABEL

VSN CONTROL

VSN

RESOURCE CONTROL

RESOURCE

} CONTROL STATEMENTS PROCESSED BY
RESEX

"EXTERNAL" CALLS VIA SPCW

LFM FUNCTION 0 RENAME
 25 LABEL

PFM

REQ (NOS/BE REQUEST FROM SFP)

QUESTION SET LESSON 17

1. List the control statements processed by RESEX?
2. What does "deadlock prevention" mean?
3. Name each resource file and list what information each resource file contains.
4. How does RESEX assign a tape unit to the job? A removable pack?
5. What is an internal call to RESEX? An external call?
6. Define the following terms:

- Deadlock
- Resource unit
- Resource type
- Demand and Assigned counts
- Demand File and VSN File
- Demand File and VSN File Entries
- Resource Environment
- Share Table
- Pack Sharing
- Overcommitment Algorithm

LESSON 18
MAGNETIC TAPE SUBSYSTEM (MAGNET)

LESSON PREVIEW:

In this lesson, the student will study the magnetic tape subsystem which consists of an executive, MAGNET, and a driver, 1MT. This lesson is not meant to be a tutorial on the usage of tapes but rather an overview of the magnetic tape subsystem.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Describe the Unit Descriptor Table (UDT) and what each word in the table means.
- Describe the interfaces between the subsystem (MAGNET/1MT) and other system components, such as RESEX, DSD/1DS, CIO, and so forth.
- Briefly discuss the variety of ANSI standard and optional tape labels.
- Briefly discuss the PROC macro of MAGNET.
- Map the layout of MAGNET's field length.

REFERENCES:

NOS IMS - Chapter 13 NOS Reference Manual, 1-10, 1-G

MAGNET/1MT

1. CONTROLS ALL MAGNETIC TAPE OPERATIONS.
2. MAGNET EXECUTES AT A CONTROL POINT AND MAINTAINS INFORMATION ABOUT TAPES AND FOR RESEX AND SYSTEM.

3. STRUCTURE -

CP ROUTINES

MAGNET

- EXECUTIVE, PROCESSES REQUESTS FROM RESEX, CIO, DSD.

MAGNET1

- TERMINATION PROCESSOR

PP ROUTINES

1MT

- TAPE DRIVER - MANY OVERLAYS (25).

COMMON DECK

COMSMTX

- UDT LAYOUT, MAGNET FL LAYOUT, FUNCTIONS, ETC.

4. SUBSYSTEM

MAGNET/1MT

MAGNET/1MT BUILDS A UNIT DESCRIPTOR TABLE (UDT) FOR EACH DEFINED TAPE UNIT.

MAGNET CALLS 1MT TO PERFORM CERTAIN TAPE OPERATIONS THAT WERE INITIATED BY A CIO, RESEX, DSD/1DS REQUEST.

IN GENERAL, 1MT SEARCHES UDT FOR REQUESTS TO PROCESS. FIRST WORD OF UDT CONTAINS THE REQUEST. AS REQUESTS ARE COMPLETED, A RETURN CODE IS PLACED IN THE FIRST WORD OF THE UDT.

THERE WILL BE ONE COPY OF 1MT ACTIVE FOR EACH TAPE CHANNEL. EACH 1MT PROCESSES ONLY THOSE UDTs ON ITS CHANNEL.

TAPE LABELS

- UNIQUELY IDENTIFY FILE AND REEL ON WHICH IT RESIDES.
- MARK BEGINNING AND END OF FILE OR REEL.

<u>REQUIRED</u>	<u>OPTIONAL</u>	
VOL1	UVL1 - 9	VOLUME
HDR1	HDR2 - 9 UHLx	HEADER
EOF1	EOF2 - 9 UTLx	END OF FILE
EOV1	EOV2 - 9	END OF VOLUME

TAPE LABELS

VOLUME

LABEL IDENTIFIER
LABEL NUMBER
VOLUME SERIAL NUMBER (VSN)
VOLUME ACCESSIBILITY
OWNER IDENTIFICATION
LABEL STANDARD LEVEL

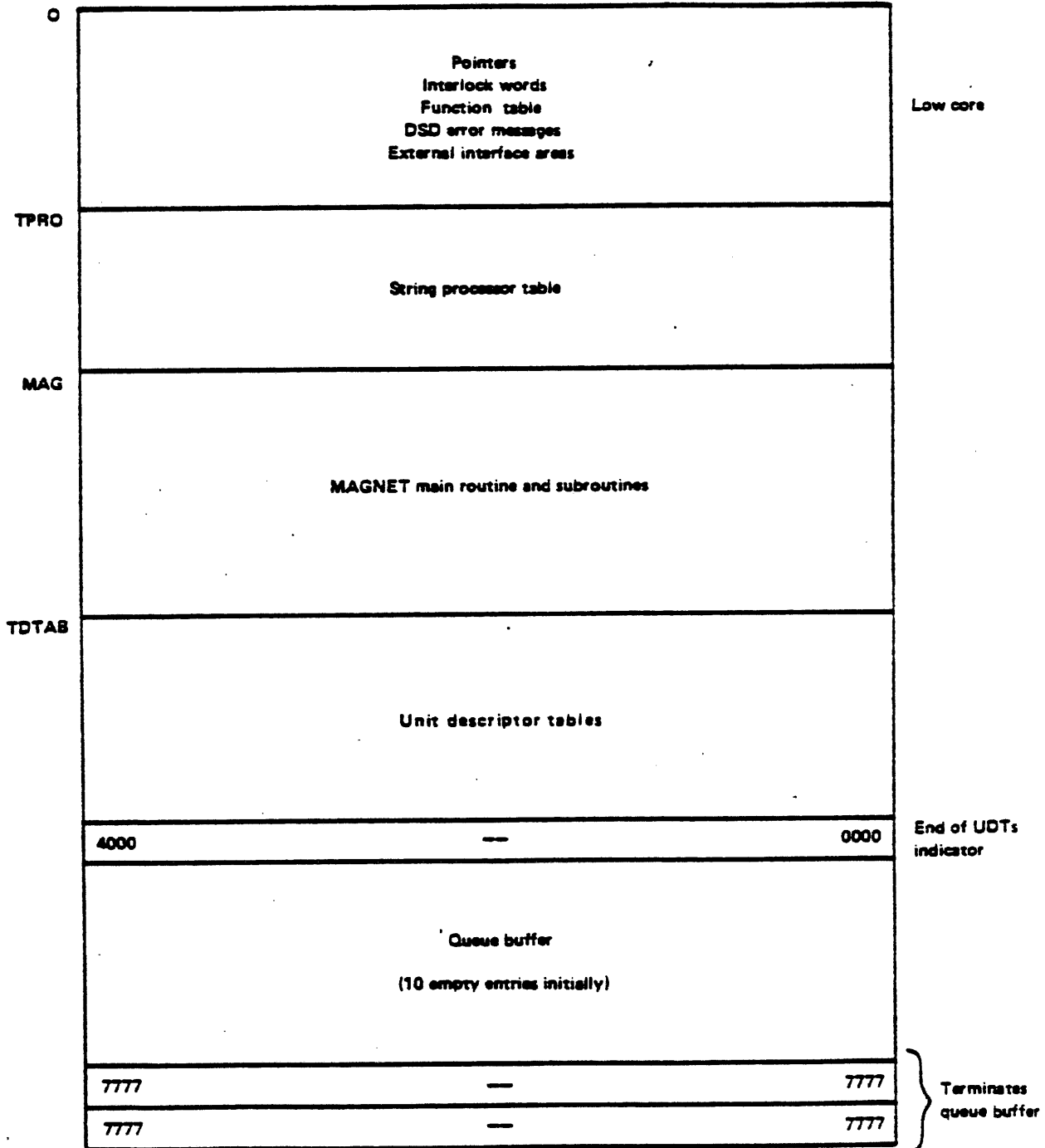
BLOCK COUNT

HEADER

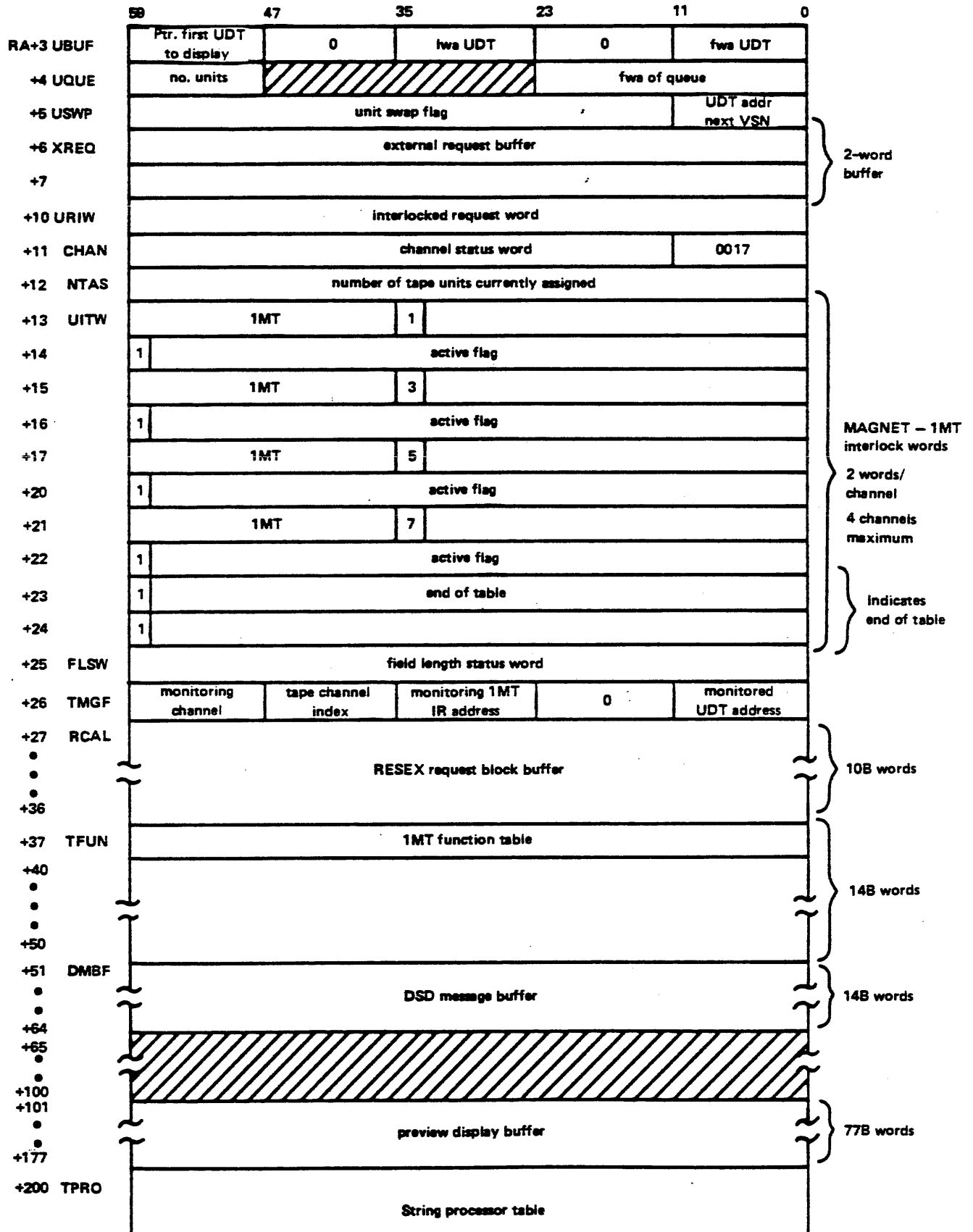
LABEL IDENTIFIER
LABEL NUMBER
FILE IDENTIFIER
SET IDENTIFICATION
FILE SECTION NUMBER
FILE SEQUENCE NUMBER
GENERATION NUMBER
GENERATION VERSION NUMBER
CREATION DATE
EXPIRATION DATE
FILE ACCESSIBILITY
SYSTEM CODE

BLOCK COUNT

OVERVIEW OF MAGNET AFTER INITIALIZATION



DETAILED MAP OF MAGNET LOW CORE



UNIT DESCRIPTOR TABLE FORMAT

		59	53	47	35	29	23	17	11	5	0		
0	UXRQ	rs		fn		mode		ps		pb			
1	UCIA	codes		skip count			FET address						
2	UCIB	a	b	external CIO code		FET options		level	record/request/return information MLRS				
3	UCIC	FL		FIRST			LIMIT						
4	UST1	eq	dn	un	hp		error code		es		ds		
5	UST2	error iteration		wp		tape block count			user options				
6	UST3	last good record			error parameter (ep)				den	cv			
7	UST4	word count		ov		format		est ord	noise	software options			
10	UST5	MTS/ATS detailed status											
11	UST6	MTS/ATS detailed status					MTS/ATS format						
12	UST7	ATS format		ATS unit status									
13	UST8	ATS unit status			block - ID window								
14	UST9	block-ID window											
15	UBLCL	blocks read accumulator				blocks written accumulator				blocks skipped			

} 3-word block sent by CIO

} for 66X/67X units only

UNIT DESCRIPTOR TABLE FORMAT (Continued)

	59	53	47	35	29	23	17	11	5	0		
16	ULRQ	MAGNET last request										
17	UREQ	req	shift	proc addr	B2	B3	X5					
20	UFLA	stack	stack flag									
21	UJSQ	job sequence number			control point no.	VSN index	VSN random index					
22	UBJN	job name					ot	next UDT to display ptr.				
23	UUFN	user number				dm	fam. index	est. writ.	vac			
24	UVSN	vsn				l c	s v	c w	e v	ec	d l	reel number
25	UFID	file identifier								mf		
26	UFSN	file identifier (continued)						file section number				
27	USID	set identifier				fac		file sequence number				
30	UGNU					generation version number		generation number				
31	UDAT	creation date				expiration date						

MAGNET/1MT

PROC MACRO

THE PROC MACRO DEFINES A "QUEUE" OF SUBFUNCTIONS THAT NEED TO BE PROCESSED TO COMPLETE A TAPE OPERATION. THE "QUEUE" MAY CONSIST OF OPERATIONS THAT MAY BE PERFORMED BY MAGNET, 1MT OR BOTH, OR OTHER PROCEDURE QUEUES.

THE POSITION OF THE QUEUE IS KEPT IN THE UDT.

FOR EXAMPLE,

PEOI PROC PROCESS EOI
 (EOI, FET, CET)

PWHL PROC WRITE MULTI-FILE HDR1
 (PTM, PWHD, PWTL, FET1)

MAGNET/1MT

PREVIEW

MAGNET MAINTAINS BUFFER SPACE FOR THE PREVIEW DISPLAY.

RESEX DETERMINES THE CONTENT OF THE PREVIEW DISPLAY, COMPACTS THE DATA, AND SENDS IT TO MAGNET VIA SIC RA+1 CALL.

DSD E,P DISPLAY PROCESSOR EXTRACTS DATA FROM THE UDTS AND THE PREVIEW BUFFER AND "PAINTS" THE DISPLAY ON THE DISPLAY CONSOLE.

SINCE RESEX IS THE ACTUAL FORMATTOR OF THE PREVIEW DISPLAY, IT (E,P DISPLAY) IS ONLY UPDATED BY A CALL TO REXES. ANY CALL TO RESEX WILL CAUSE A FORMATTING OF THE PREVIEW BUFFER.

QUESTION SET LESSON 18

1. What information is kept in the Unit Descriptor Table (UDT)?
2. How do other system routines make requests to the tape executive MAGNET?
3. The buffer for the preview display (E,P) is kept in MAGNET's Field length. Who updates the information in that buffer?
4. Why do tapes have labels? What information may be found in required ANSI labels?
5. MAGNET/IMT process three different types of tape controllers. How does it handle the function code and operational differences between them?

LESSON 19
UNIT RECORD SUBSYSTEM (BATCHIO)

LESSON PREVIEW:

This lesson introduces the student to the unit record subsystem BATCHIO.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Identify the components of BATCHIO, and explain in detail the flow through IIO, ICD, and QAP.
- Discuss "buffer points".
- Describe the "driver control word" and "driver request word".
- Map BATCHIO's control point field length and the FET for active buffer points.

REFERENCES:

NOS IMS - Chapter 17 NOS Operator's Guide, 3 NOS IHB, 7-9-10 NOS SMRM, 9

BATCHIO

BATCHIO IS A SUBSYSTEM THAT PROCESSES DATA TRANSFERS BETWEEN THE MAINFRAME AND THE UNIT RECORD PERIPHERALS ATTACHED TO IT.

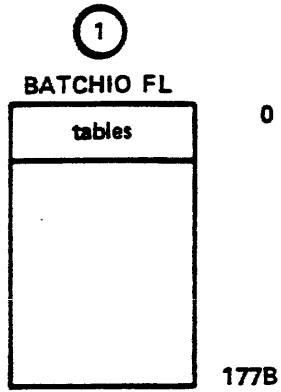
CARD READER	405		
CARD PUNCH	415		
LINE PRINTER	512	580	580PFC

- READS CARDS FROM CARD READER.
CREATES INPUT FILE.
ENTERS JOB (INPUT FILE) INTO QUEUE.
- LOCATES FILES IN PRINT OR PUNCH QUEUE AND DISPOSES THEM.
- PROCESSES OPERATOR COMMANDS FOR UNIT RECORD EQUIPMENT (FROM DSD) AND PROVIDES EQUIPMENT INFORMATION FOR THE I DISPLAY.

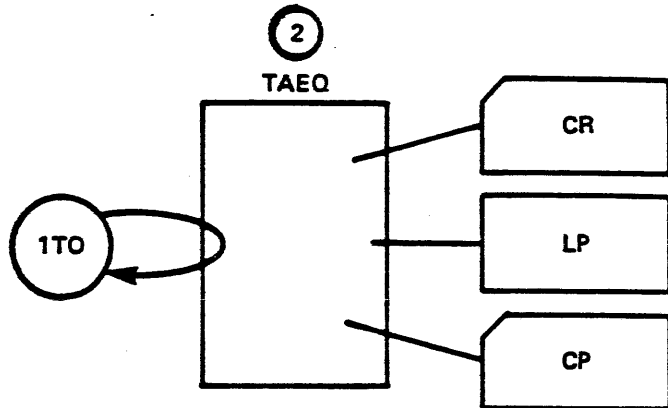
1IO - EXECUTIVE
1CD - PERIPHERAL DRIVER (CR, CP, LP)
QAP - AUXILIARY
COMSBIO - COMMON DECK

NO CPU CODE - FL USED FOR BUFFERS/FETS

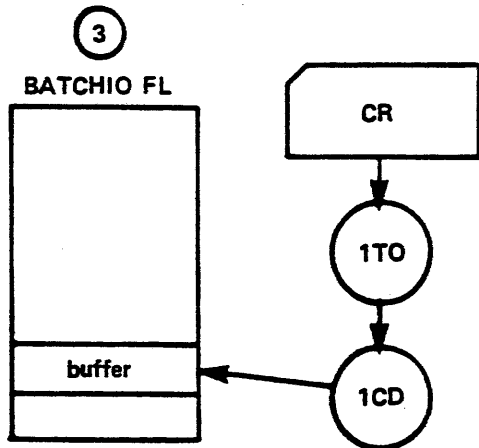
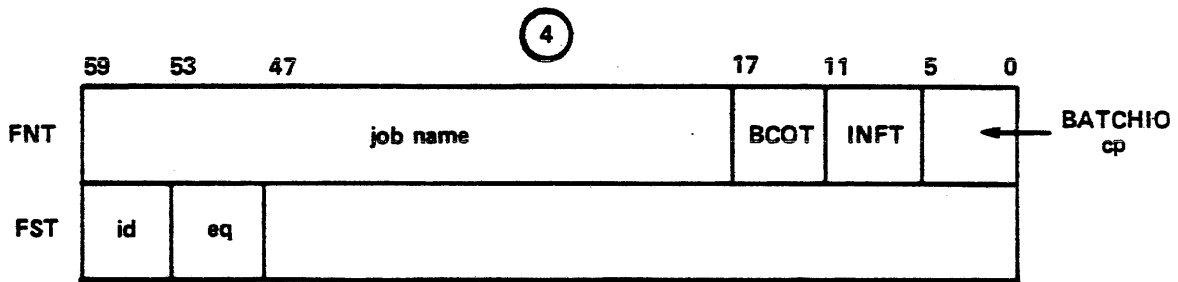
BATCHIO OVERVIEW



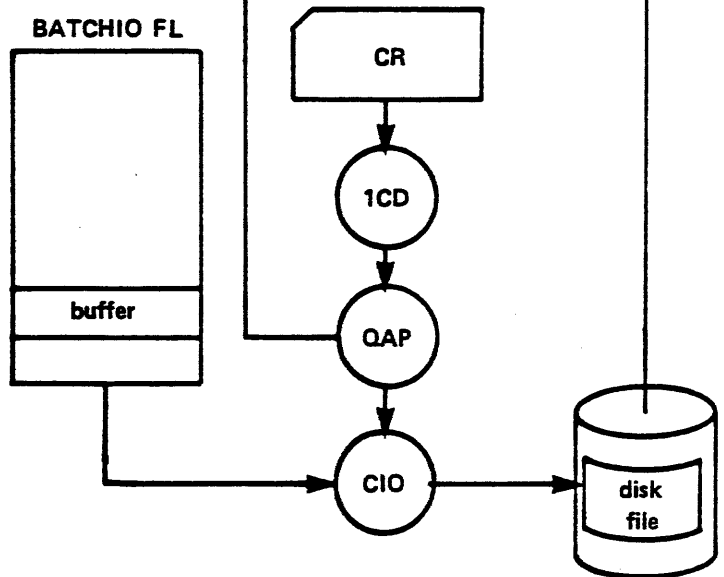
1
BATCHIO control point idle, FL is 200B.



2
1TO is recalled (RLPW word in control point area) and begins scan of available unit record equipment.

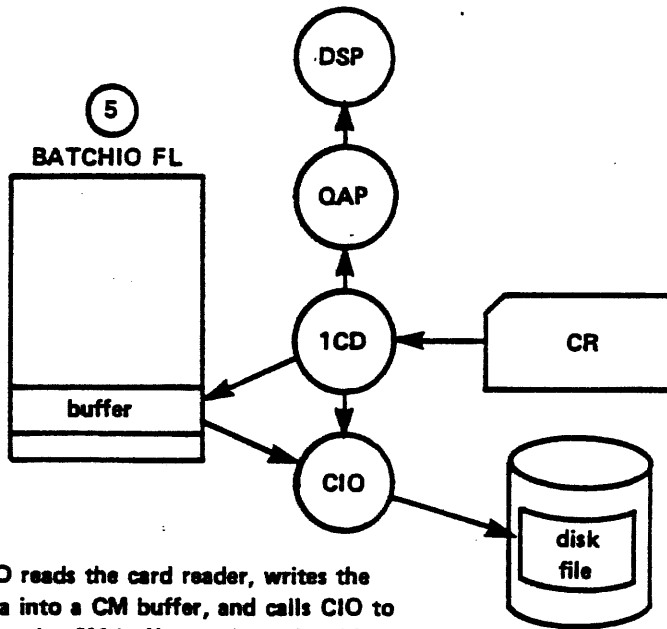


3
1TO finds a card reader ready and calls 1CD for processing.



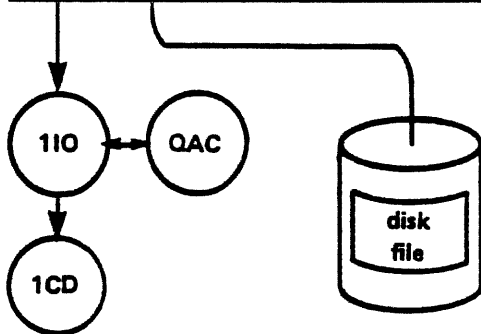
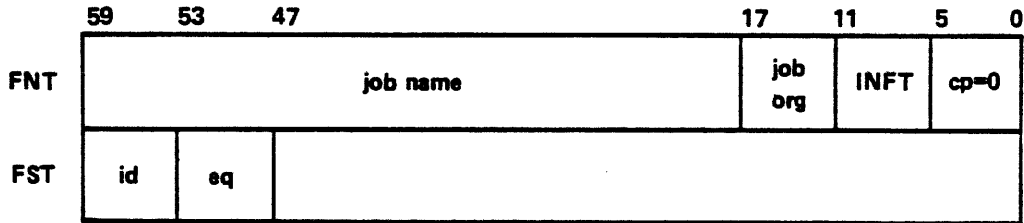
4
1CD calls QAP to build an input file entry and write the data to the disk via CIO.

BATCHIO OVERVIEW (Continued)



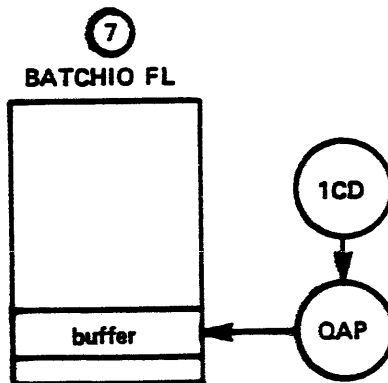
1CD reads the card reader, writes the data into a CM buffer, and calls CIO to write the CM buffer to the disk. After the file has been completely read, 1CD calls QAP who in turn calls DSP to put the file into the input queue.

6

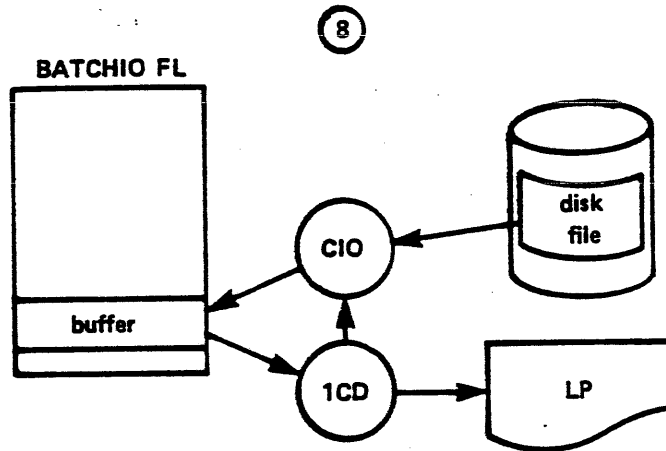


1IO calls QAC to find an output queue entry and then calls 1CD.

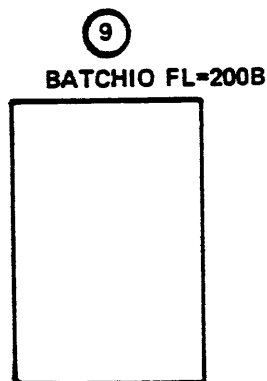
BATCHIO OVERVIEW (Continued)



1CD calls QAP to create a banner page (QAP calls OBP) in the CM buffer.



1CD reads the rest of the file to the CM buffer via CIO and prints the data on the printer.



1CD completes and drops; BATCHIO is now idle.

BATCHIO

TABLES AND BUFFERS ARE MAINTAINED IN BATCHIO CONTROL POINT AREA AND FIELD LENGTH FOR USE AND COMMUNICATION BY 1IO/1CD/QAP.

THE CONTROL CARD BUFFER (CSBW) IS USED FOR "BUFFER POINTS", TWO WORDS PER ENTRY FOR EACH PERIPHERAL. BEGINNING WITH NOS 1.3, THESE BUFFER POINTS ARE REFERENCED BY THE OUTSIDE WORLD BY THE EQUIPMENT NUMBER OF THE BUFFER POINT.

FILENAME			EQ	RC	OR
I	DFM	MP1	MP2	MP3	

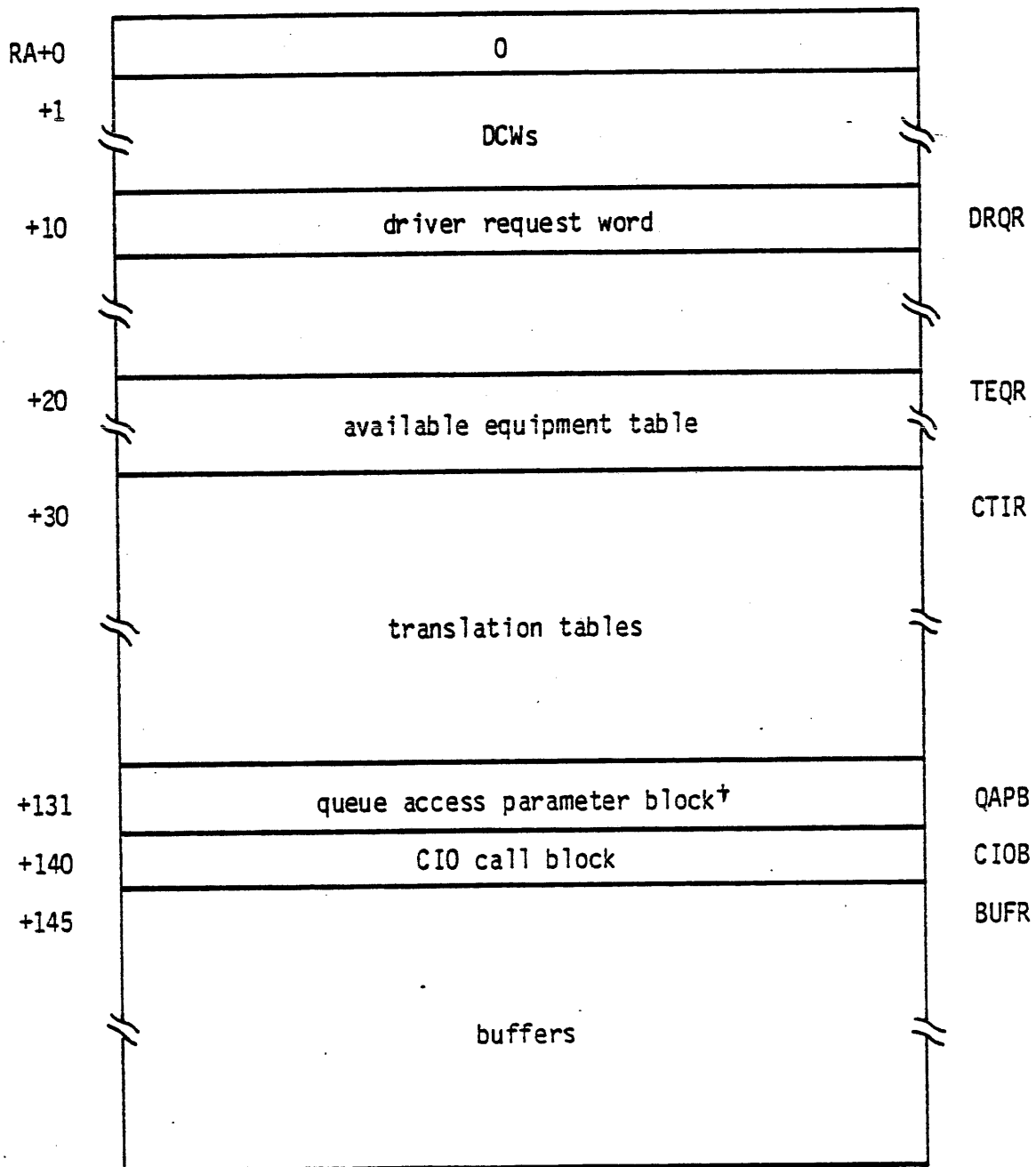
OR = OPERATOR REQUEST

1	END
2	REPEAT
3	SURPRESS
4	RERUN
5	HOLD
6	CONTINUE
7	BKSP PRU
10	BKSP RECORD
11	BKSP FILE
12	SKIP PRU
13	SKIP RECORD
14	SKIP FILE

RC	= REPEAT COUNT
I	= I DISPLAY
	MESSAGE CODE
DFM	= DAYFILE/ERRLOG
	MESSAGE CODE
MP1/MP2/	= MESSAGE
MP3	PARAMETERS

BATCHIO CENTRAL MEMORY LAYOUT

The core Layout of the BATCHIO control point is shown below.



† Built by IIO for QAC call to locate an unavailable qualifying file.

BATCHIO

FET IN BATCHIO FL

FILENAME			STATUS	
			FIRST	
			IN	
			OUT	
FST/ADDR			LIMIT	
BN	P1	P2	OT	
CS	ES		USER LIMITS	
Q A C			PARAMETER BLOCK	
USER NUMBER				
JOB NAME				

FET+13

FET+14

BUFFER FOLLOWS FET

BUFFER SIZE	1020 ₈	PRINT
	420 ₈	PUNCH
	1020 ₈	READER

BATCHIO

DRIVER CONTROL WORD

DCW

ONE DCW FOR EACH COPY OF 1CD

EACH 1CD SUPPORTS UP TO EIGHT PERIPHERALS

1	C	D	o	DCW INDEX	NO. OF REQUESTS	o
---	---	---	---	--------------	--------------------	---

RA+2
↓
RA+7

DRIVER REQUEST WORD

DRQR

REQUEST FOR 1CD TO DO SOMETHING

DCW INDEX	EST ORDINAL	BUFFER POINT	BUFFER ADDRESS
--------------	----------------	-----------------	-------------------

RA+10

BATCHIO

1 IO EXECUTIVE

1	I	O	CP	F	RS	BN	AB
---	---	---	----	---	----	----	----

F FILE PREVIOUSLY REQUESTED
RS RELEASE STORAGE REPEAT COUNT
BN CURRENT BUFFER POINT
AB NUMBER OF ACTIVE BUFFERS

1 IO WRITES ITS INPUT REGISTER (IR) INTO RPLW AND DROPS
1 IO WILL BE RECALLED AT THE DELAY AR INTERVAL BY MTR.

1. BUILD A REQUEST FOR 1CD IN DRQR IF DCW EXISTS AND HAS LESS THAN 8 PERIPHERALS, ADD TO THAT DCW. OTHERWISE, MAKE A NEW DCW AND CALL 1CD OVER ITSELF AFTER SETTING UP RECALL (IR) → (RLPW).
2. CALL QAC FOR OUTPUT. CALLS QAC INTO THIS PP AFTER SETTING UP RECALL (IR) → (RLPW)

BATCHIO

1CD - COMBINED PERIPHERAL DRIVER

1CD CHECKS FOR REQUEST IN DRQR

● READER

- READ FULL BUFFER OF CARDS (1020₈ WORDS) AND CALL QAP TO PROCESS INPUT FILE.
- QAP CALLS OVJ TO PROCESS JOB CARD, CREATES INFT FNT/FST ENTRY.
- 1CD KEEPS READING
- QAP CALLS CIO TO WRITE DATA TO DISK
- AT END OF READING, QAP IS CALLED TO CALL DSP AND PUT FILE INTO THE INPUT QUEUE WITH QUEUE SYSTEM SECTOR
- ACCOUNTS FOR NUMBER OF CARDS READ (PASSED IN SYSTEM SECTOR)

● PRINTER/PUNCH

- 1CD CALLS QAP TO GET BANNER PAGE OR LACE CARD (OBP) FORMATTED INTO BUFFER
- QAP CALLS CIO TO READ THE OUTPUT FILE AND FILL THE BUFFER (1020₈ = PRINT, 420₈ = PUNCH, 2040₈ = 199 PRINT)
- 1CD PRINTS/PUNCHES
- QAP IS CALLED TO FILL BUFFER
- AT END OF PRINTING/PUNCHING, QAP IS CALLED TO ACCOUNT FOR IT AND QAP CALLS DSP TO DECREMENT THE REPEAT COUNT (IF ANY)
- IF REPEAT COUNT IS ZERO → QUIT. OTHERWISE PRINT/PUNCH FROM THE BEGINNING

QUIT: 1IO MAY RELEASE BUFFERS IF NO LONGER REQUIRED AND LAST BUFFERS

BATCHIO

QAP - QUEUE ACCESS PROCESSOR

PERFORM FUNCTIONS FOR BATCHIO AND RBF

	<u>FUNCTION</u>	<u>SYMBOL</u>
DAYFILE MESSAGES (ERROR DIAGNOSTICS)	400	PDMF
INITIATE INPUT FILE WITH WRITE	410	WTIF
INITIATE INPUT FILE WITH WRITE EOR	420	WRIF
INITIATE INPUT FILE WITH WRITE EOF	430	WFIF
CHANNEL ERROR CLEAN-UP	440	CECF
OPERATOR REQUESTS	450	CORF
REQUEUE FILE	460	RQFF
LOAD 580 PFC (INCLUDING USER ARRAYS)	470	PFCF
LOAD INITIAL PRINT DATA (BANNER PAGE)	500	GBPF
LOAD INITIAL PUNCH DATA (LACE CARD)	510	GLCF
LIMIT EXCEEDED	520	PLEF
ACCOUNTING	530	ACTF

PRINT TRAINS AND IMAGE MEMORY

SOFTWARE MAPPING OF PRINTER TRAIN SLUGS IS CALLED IMAGE MEMORY

OVERLAY (110)

5IA 595-1	512	SLUG
5IC 595-4, 595-5		MACRO
5IE 596-1	580	
5IG 596-4, 596-5		

580 PFC: PROGRAMMABLE FORMAT CONTROL ARRAYS

5BA 6 LINES PER INCH	SOFTWARE SPECIFIED
5BB 8 LINES PER INCH	"CARRIAGE TAPE"

QUESTION SET LESSON 19

1. What programs are involved in the BATCHIO subsystem?
2. How is the BATCHIO control point and its field length utilized?
3. What is happening when BATCHIO is in its "idle" state?
4. How does the unit record driver (ICD) do input/output to/from mass storage?
5. What does BATCHIO do to submit a job to the system?
6. How does BATCHIO utilize the ID field in an FST entry?
7. What function do the DCW (Driver Control Word) words serve?
8. How is the DRQR one word request stack utilized?
9. Can BATCHIO be rolled out? Why?

LESSON 20
FILE ROUTING AND QUEUE MANAGEMENT

LESSON PREVIEW:

This lesson introduces the student to the file routing and queue management features of NOS. To more fully understand this lesson, the student should review the ROUTE control statement and macro.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Explain what is meant by Queued File Terminal Addressing, Alternate Routings, Device Specification, Forms Control, External and Internal Characteristics, Deferred Route.
- Detail the queued file system sector.
- Discuss the operations performed by QAC (Queue Access Control).
- Discuss the proper technique for creating a queue file.

REFERENCES:

NOS IMS - Chapter 19 and 34 NOS RM, 1-2-4,6, 1-7-19,30,36-40, 2-7, 2-8

ASSIGNMENT:

Design, flowchart and code system utility programs to list the system sector data for a queued output file.

FILE ROUTING/QUEUE MANAGEMENT

QUEUE FILE INFT PRFT PHFT
 S1FT S2FT S3FT
 WITH CONTROL POINT IN FNT = 0

QUEUE FILE SYSTEM SECTOR

COMSSSE

TERMINAL ADDRESSING

FDSS	DESTINATION FAMILY	}	TO WHERE
DASS	DESTINATION USER		
DISS	DESTINATION INDEX		

DISS FOR BATCH = FILE ID

FDSS/DASS/DISS FOR EIOT/RBF DEFINE THE RJE TERMINAL FOR DISPOSAL

ALTERNATE ROUTINGS

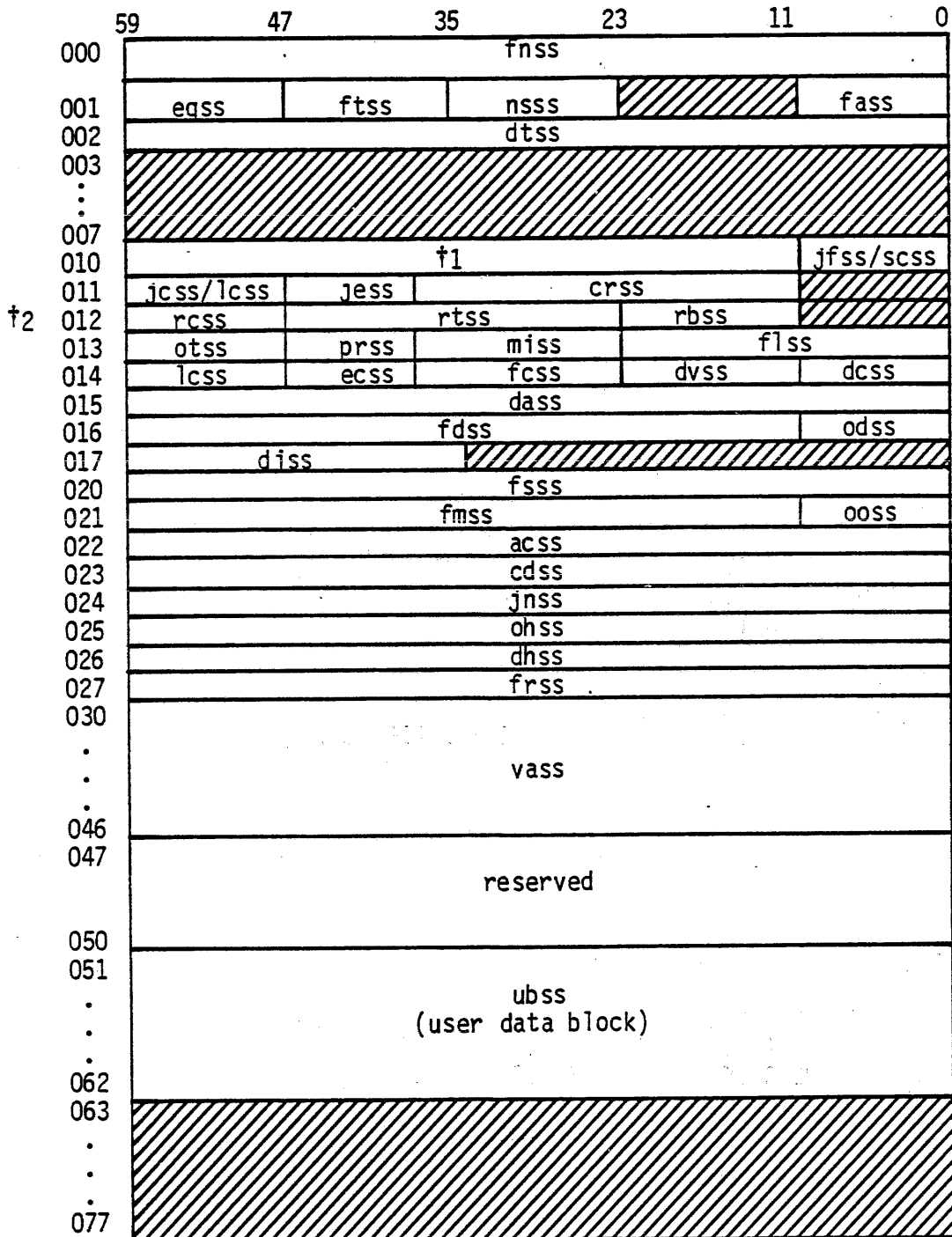
USER SPECIFIES DESTINATION FAMILY AND USER NUMBER/INDEX

DEVICE SPECIFICATION

SPECIFIES DISPOSAL EQUIPMENT

DVSS	DEVICE CODE
ECSS	EXTERNAL CHARACTERISTICS
FCSS	FORMS CODE (00, AA-AF, OTHERS)

SYSTEM SECTOR FORMAT
Standard Format



†1 For print/punch files, pfss (bits 47-36), rass (bits 35-12); for input files, jsss (bits 59-36), bits 35-24 unused, jtss (bits 23-12).

†2 For input files, bits 59-18 are defined as terminal name (tnss).

The following apply to all system sectors.

fnss	FNT entry.
eqss	Equipment number.
ftss	First track.
nsss	Next sector.
fass	Address of FST entry.
dtss	Last modification date and time (packed format).

The following apply to input files only.

jsss	Job sequence number.
jtss	Job time limit.
jfss	Job flags.
jcsc	Job statement CM field length.
jess	Job statement ECS field length.
crss	Cards read.
tnss	Terminal name.

The following apply to print/punch files only.

pfss	Punch format.
rass	Random address of dayfile.
scss	Spacing code for 580 PFC support.
lcsc	Lines or statement limit index.
rcsc	Repeat count.
rtss	Random index.
rbss	Requeue number.

The following apply to all queued files.

otss	Origin type.
prss	Priority.
miss	Machine ID.
flss	File size (sectors/10g).
icss	Internal characteristics.
ecss	External characteristics.
fcsc	Forms code.
dvss	Device code.
dcsc	NOS/BE device code.
dass	Destination user number.
fdss	Destination family name.
odss	Family ordinal of destination (future).
diss	Destination terminal identification (TID).
fsss	FST entry.
fmss	Family name of creator.
ooss	Family ordinal of creator (future).
acsc	User number of creator.
cdss	Queued file creation date and time.
jnss	Job statement name.
ohss	Origination host name (future).
dhss	Destination host name (future).
frss	File routing control.
vass	Account file validation block.
ubss	User block.

FILE ROUTING/QUEUE MANAGEMENT

RETRIEVING QUEUE FILE

QAC

- IDENTIFY FILES FOR DISPOSAL
- ALTER FIELDS
- COUNT/PEEK

VALIDATE CONTROL POINT INFORMATION (VCI)
 VALIDATE MASS STORAGE INFORMATION (VMI)

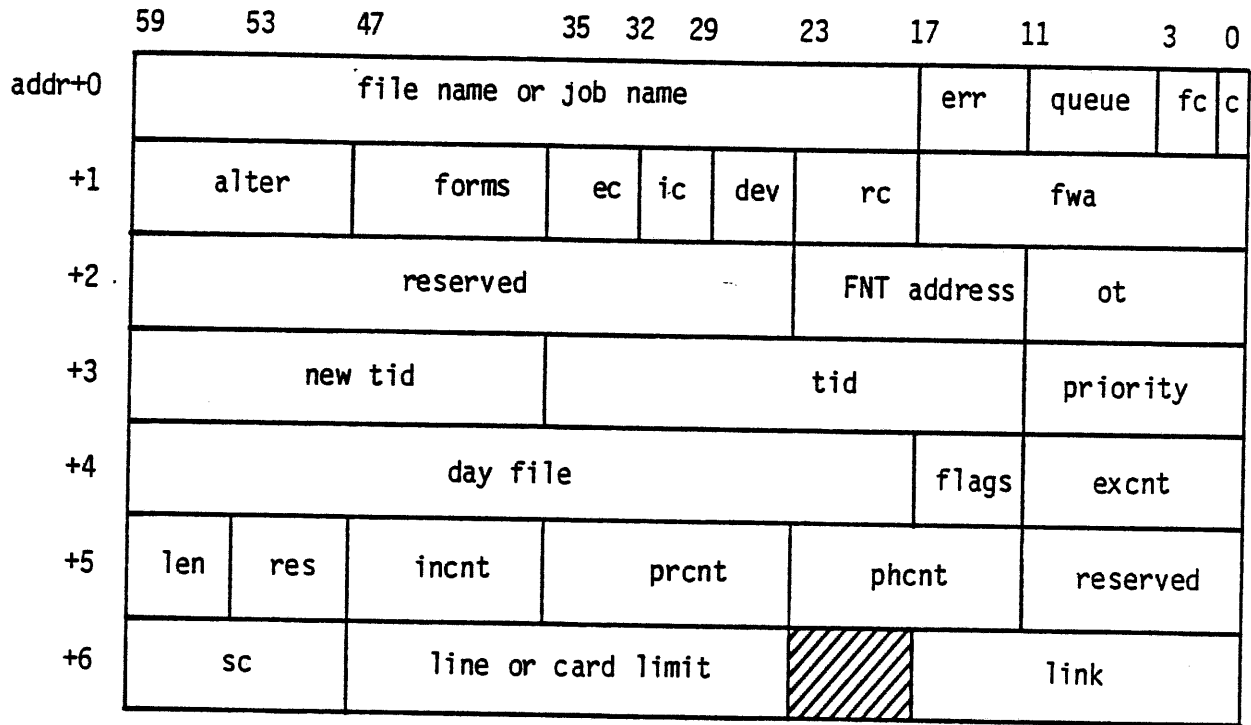
- CHECK FST FOR TID AND D, F, X
- READ SYSTEM SECTOR IF D, F, X EXTENDED CODES
- IF MATCH AND NOT EIOT → OK
- IF EIOT WHEN FAMILY MUST MATCH (READ SYSTEM SECTOR)

JOBNAME					ORIGIN	QT	1	0
D	X	EQ	FT	F	TID	QP		

FNT

FST

The parameter block format is as follows.



err Error code returned (complete description follows).

queue Queue type:

<u>Queue</u>	<u>Description</u>
1	Input file
2	Output file
4	Punch file
8	Special output
16	Executing job (at control point or in rollout queue)

fc Function code:

<u>Code</u>	<u>Description</u>
0	ALTER function
1	GET function
2	PEEK function
3	COUNT function

c Completion bit. Must be 0 on call; set to 1 upon completion.

FILE ROUTING/QUEUE MANAGEMENT

CREATING A QUEUE FILE

1. INPUT FILE BY BATCHIO/EI200/RBF

FDSS/DASS/DISS FROM "CARD READER"
DESTINATION FAMILY/USER/INDEX

2. QUEUE FILE AT THE "USER CONTROL POINT"

BY	ROUTE	1CJ	
	DISPOSE	CIO	CLOSE-
	SUBMIT		UNLOAD
	OUT		CLOSE-
			RETURN

THROUGH USE OF:

COMPUSS - UPDATE SYSTEM SECTOR (USS)
- WRITE QUEUED FILE S.S. (WQS)

DSP - UPDATES SYSTEM SECTOR (USS)
- SETS APPROPRIATE FIELDS
- WRITES SYSTEM SECTOR (WQS)
- WRITE FNT/FST, PUTTING INTO QUEUE IF IMMEDIATE ROUTE. IF DEFERRED ROUTE, FILE IS NOT QUEUED (CONTROL POINT NOT 0) BUT SYSTEM SECTOR INFORMATION BIT (FNT BIT 5) IS SET. ROUTING INFORMATION WILL BE USED WHEN FILE DISPOSED TO QUEUE.

QUESTION SET LESSON 20

1. The most important item in queue management and file routing is the queued file's system sector. Why?
2. What common deck is used to generate the queued file system sector?
3. Explain what is meant by "terminal addressing". What FNT and/or system sector fields are used in terminal addressing?
4. There are three file routing properties that describe what is required of the peripheral device on which a file is to be disposed. Describe these three properties and explain their usage in the FST and system sector.
5. What is a deferred route?
6. Why is QAP (discussed in lesson 19) part of File Routing and Queue Management?

LESSON 21
OTHER MONITOR (RA+1) REQUESTS

LESSON PREVIEW:

This optional lesson presents other RA+1 requests that are found throughout the NOS system. The requests are used by both the system programmer and the user COMPASS programmer and are satisfied by PP routines.

As with most NOS PP routines that are user callable through RA+1, these requests have a macro call and in most cases a corresponding control statement which, in turn, uses the macro.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Identify commonly used PP routines called by the end user or system programmer through RA+1 requests.

REFERENCES:

NOS Reference Manual, all of volume 2 NOS IMS - Chapters 10, 11, 19 and 30

OTHER RA+1 REQUESTS

CPM - CONTROL POINT MANAGER
LFM - LOCAL FILE MANAGER
QFM - QUEUE FILE MANAGER
SFM - SYSTEM FILE MANAGER
TLX - TERMINAL ACTION PROCESSOR
FDL - FAST DYNAMIC LOADER
PFU - PERMANENT FILE UTILITY
VEJ - VERIFY JOB FILE INFORMATION
RDM - REDEFINE MASS STORAGE
RPV - REPRIEVE CENTRAL PROGRAM
CVL - COMMON VALIDATION INTERFACE
ELM - ERROR LOG MESSAGES

STS - STATUS PROCESSOR
MSD - SDA/SIS MESSAGE GENERATOR
PFE - ALTER FUNCTION
ACE - ADVANCE CONTROL CARD
PRM - PERMISSION CHECK
CKP - CHECKPOINT
REQ - EQUIPMENT REQUEST
DMD - DUMP WITH DISPLAY CODE
DMP - DUMP FL
DOO - ERROR TEXT PROCESSOR

} SFP

CPM

SETQP
SETPR
SETASL
SETJSL
SETTL
SETJCR
SETSS
SETLC
SETGLS
SETLOF
SETJCI
SETUI
SETRFL
SETMFL
SETSSM

MODE
EREXIT
CONSOLE
ROLL OUT
ONSW
OFFSW
USECPU
PACKNAM

GETQP
GETPR
GETASL
GETJSL
GETTL
GETJCR
GETSS
GETLC
GETGLS
GETLOF
GETACT
GETEM
GETJO
GETJA
GETFLC
GETPFP
GETJCI
GETJN
USERNUM

MACHID
VERSION

PROTECT

DISSJ
DISSR RENS
EESR
ENFAM

VALID
SETOV

LFM

RENAME
ASSIGN
COMMON
RELEASE
LOCK
UNLOCK
STATUS
FILINFO
REQUEST
LABEL
SETID
ENCSF
PSCSF
GETFNT
PRIMARY

ACCSF

SFM

DAYFILE

- USER
- SYSTEM
- ACCOUNT
- ERRLOG

ESYF

RDVF

DFAT

ENFA

QFM

RERUN
NORERUN
SUBMIT
FORCE EQUIPMENT

VEJ

- VERIFYJ

SFP

- CHECKPT

TLX

CSET
DISTC
PARITY
TSTATUS

LESSON 22
SYSTEM CONTROL POINT FACILITY

LESSON PREVIEW:

This lesson details the internal interfaces of the System Control Point Facility and the role it plays in NOS.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Discuss the requirements necessary for using the System Control Point Facility.
- Identify the components that make up the System Control Point Facility.
- Describe the interfaces between a system control point (subsystem) and a user control point.
- Explain the significance of the subsystem queue priority relative to using the System Control Point Facility.

REFERENCES:

NOS IMS - Chapter 18

SYSTEM CONTROL POINT FACILITY

CENTRALIZED FACILITY WHICH ALLOWS A MODULE OR GROUP OF MODULES TO BE USED BY ONE OR MORE JOBS RESIDING AT OTHER CONTROL POINTS.

PROVIDES -

- CENTRALIZED CONTROL
- REDUCTION OF CENTRAL MEMORY USAGE

SYSTEM CONTROL POINT FACILITY

DEFINITIONS

SUBSYSTEM - MODULE OR GROUP OF MODULES WHICH PERFORM A SPECIFIED SET OF FUNCTION.
EXECUTES AT A CONTROL POINT WITH SPECIAL SYSTEM PRIVILEGES.

SYSTEM CONTROL POINT - CONTROL POINT OCCUPIED BY A SUBSYSTEM.

USER CONTROL POINT - JOB AT A CONTROL POINT WHICH MAKES A REQUEST TO A SUBSYSTEM.
MAY BE A BATCH JOB OR A SUBSYSTEM.

SUBSYSTEMS

CHARACTERISTICS

1. NOT ROLLABLE - NO ROLLOUT
2. INTER CONTROL POINT COMMUNICATIONS (RSB/SIC)
3. HIGH CPU PRIORITY
4. DOES NOT ABIDE BY JCB CONTROLS CM AND CPU SLICES - INFINITE
5. MAY HAVE A USER NUMBER IN UIDW TRANEX/TAF
6. MAY RESIDE AT A SPECIFIED CP
7. IMPLICIT SSJ = AND ARE SYOT
8. USE OF SPC (NEE TLX) RA+1 CALL

TO BE A SUBSYSTEM

1. UNIQUE QP DEFINED TO FIT INTO SSCL WORDS OF CMR
2. 1DS TABLE ENTRY TO START UP EXECUTIVE
3. QP IDENTIFIES THE SUBSYSTEM (OPERATING SYSTEM TESTS FOR A GIVEN SUBSYSTEM BY ITS QUEUE PRIORITY)

SUBSYSTEMS

<u>SUBSYSTEM</u>	<u>QP SYMBOL</u>	<u>QP</u>	<u>PP INIT.</u>	<u>CONTROL PT.</u>
TIME-SHARING	TXPS	7776	1SI	1
TELEX IAF				
REMOTE BATCH	EIPS	7775	1LS	77
E1200				
UNIT RECORD	BIPS	7774	1IO	76
BATCHIO				
TAPES	MTPS	7773	1MT	75
MAGNET				
TRANSACTION	TRPS	7772		2
TRANEX TAF			1TP 1SI	
NETWORK INTERFACE	NMPS	7770	1SI	74
NIP				
REMOTE BATCH (NETWORK)	RBPS	7767	1SI	73
RBF				
MESSAGE CONTROL SYS	MCPS	7765	1SI	72
CDCS	CDPS	7766	1SI	71
TIME SHARE STIM	STPS	7771	1SI	77
STIMULA				
MASS STORAGE CONTROL	MSPS	7764	CMS	74
MSS STORAGE SUBSYSTEM	MFPS	7763	1SI	70
EXECUTIVE				
MSSEXEC				

SYSTEM CONTROL POINT FACILITY

CPUMTR - INSTALLATION SELECTABLE MODULE

- SSF RA+1 CALL - SUBSYSTEM
- SSC RA+1 CALL - USER CONTROL POINT

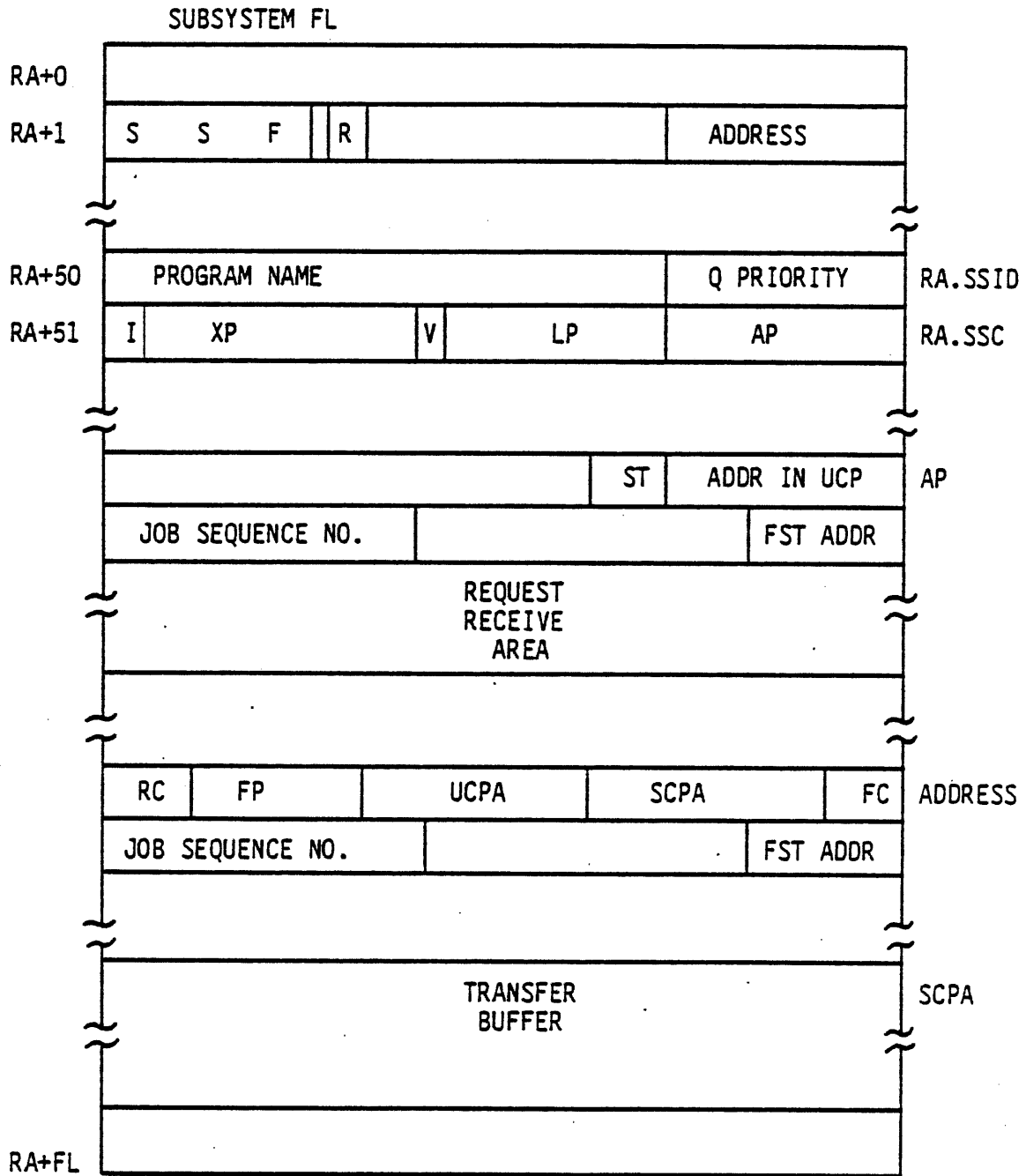
SSYTEXT

- MACRO INTERFACES
 - CALLSS - USER CONTROL POINT
 - SFCALL - SUBSYSTEM
- SYMBOL DEFINITIONS
 - SPECIAL WORD LOCATIONS
 - FUNCTION CODES

COMSSCP - SYSTEM CONTROL POINT EQUIVALENCES

- SPECIAL WORD LOCATIONS
- FUNCTION CODES
- REPLY CODES
- ERROR STATUS CODES

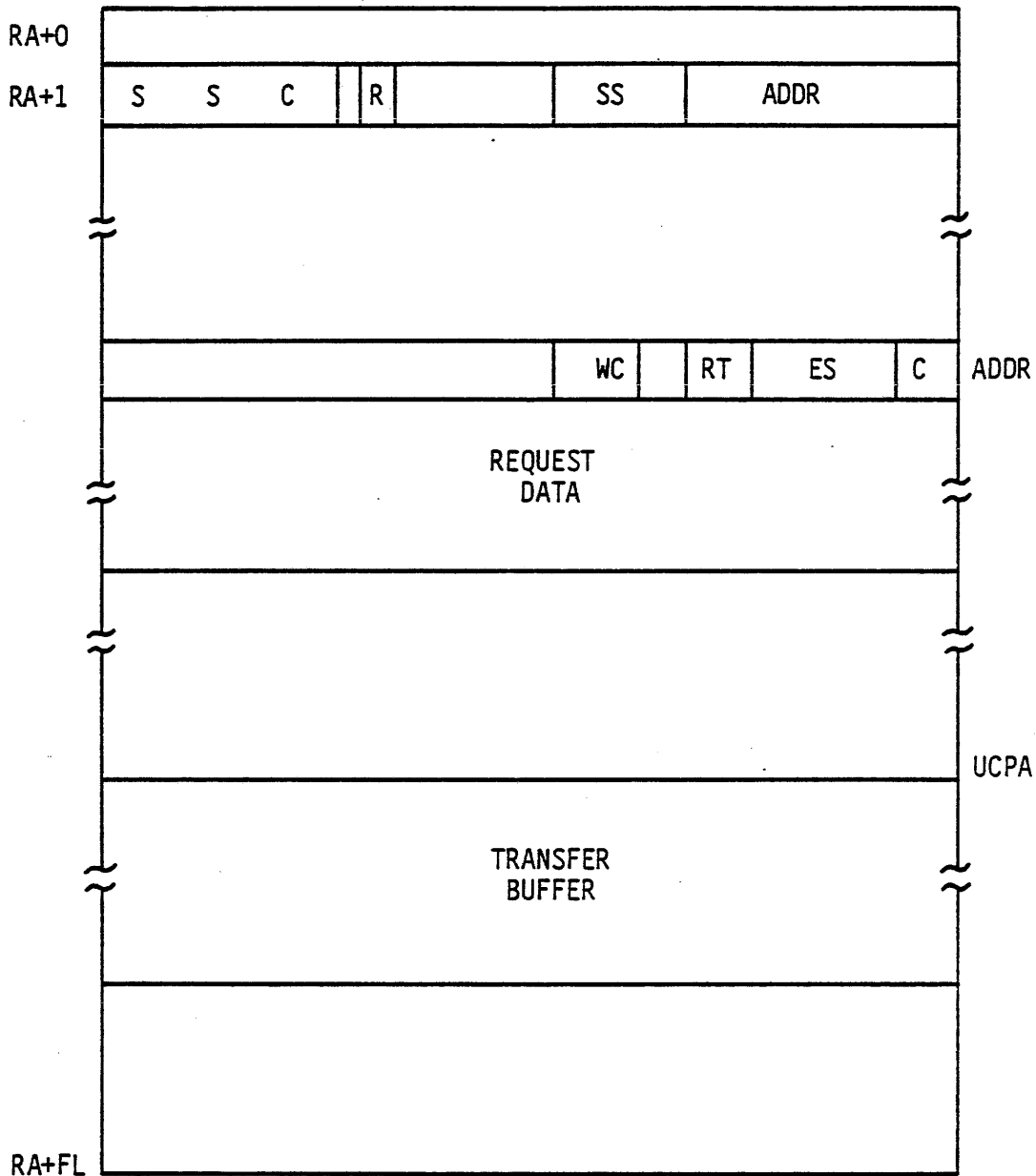
SYSTEM CONTROL POINT FACILITY



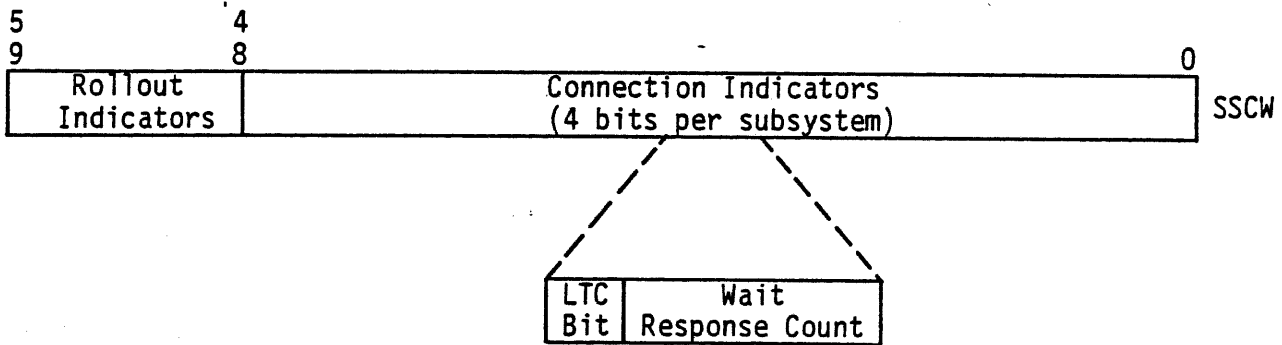
- I = Request Present Flag (Set by (CPUMTR)
- XP = UCP Exchange Package Address in Subsystem
- V = Variable Transfer Flag
- LP = Length of Parameter Area
- ST = UCP Status (End/Abort/Override)
- RC = Response Code
- FP = Function Parameter
- FC = SSF Function Code

SYSTEM CONTROL POINT FACILITY

USER CONTROL POINT



WC = Word Count -1 of Request
 RT = Return Control (Busy/Non Fatal Error)
 ES = Error and Status (Present/Busy/Illegal)
 C = Completion Bit
 SS = Subsystem Queue Priority



Subsystem Control Word in UCP
Control Point Area

Long-Term Connection	N	N	Y	Y
Wait Response Non-Zero	N	Y	N	Y
No Connection	X			
Awaiting Response		X		X
Lock In		X		X
Candidate for Rollout	X		X	
SF. SLTC Allowed		X		
SF. SWPO Allowed		X		X
SF. SWPI Allowed			X	
SF. CLTC Allowed			X	X

User Control Point
Connection State Table

SYSTEM CONTROL POINT FACILITY

SSF FUNCTION CODES

SF.REGR	-	MESSAGE IN UCP DAYFILE AND/OR ABORT UCP
SE.ENDT	-	COMPLETE USER REQUEST
SF.READ	-	READ UCP MEMORY
SF.STAT	-	REQUEST UCP STATUS
SF.WRIT	-	WRITE UCP MEMORY
SF.EXIT	-	EXIT SUBSYSTEM STATUS
SF.SWPO	-	ALLOW UCP SWAPOUT
SF.SWPI	-	REQUEST UCP SWAPIN
SF.SLTC	-	SET LONG TERM CONNECTION
SF.CLTC	-	CLEAR LONG TERM CONNECTION
SF.LIST	-	MULTIPLE REQUEST
SF.XRED	-	EXTENDED READ
SF.XWRT	-	EXTENDED WRITE
SF.XLST	-	EXTENDED MULTIPLE REQUEST

SYSTEM CONTROL POINT FACILITY

SSF RESPONSE CODES

- 00 - NO ERROR
- 40 - ERROR IN LIST REQUEST
- 41 - JOB IDENTIFIER INVALID
- 42 - SCPA OUT OF RANGE
- 43 - UCPA OUT OF RANGE
- 44 - UCP SWAPPED OUT
- 45 - UCP NOT IN SYSTEM
- 56 - ECS PARITY ERROR
- 57 - CONNECTION PREVIOUSLY ESTABLISHED
- 60 - CONNECTION REJECTED
- 61 - CONNECTION NOT PREVIOUSLY ESTABLISHED
- 62 - TRANSFER TOO LONG
- 63 - UCP NOT ESTABLISHED WITH SUBSYSTEM
- 64 - SUBSYSTEM ESTABLISHED WITH RECEIVER
- 65 - ATTEMPT TO SET ILLEGAL ERROR FLAG
- 66 - ILLEGAL DAYFILE PROCESSING FLAG

NIP/SCP ERROR RC=rc JOBID=jobid

QUESTION SET LESSON 22

1. Explain the difference between a system control point, a user control point, and THE SYSTEM control point.
2. Describe the interfaces provided by the System Control Point Facility for transferring data between a system control point and a user control point.

LESSON 23
NETWORK PRODUCTS OVERVIEW

LESSON PREVIEW:

This lesson introduces the student to the Network Products and the terminology used within the Network Products context. This lesson is not a detailed discussion of Networks, but rather an overview of the concepts of NOS Network Products.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be familiar with the concepts and terminology of Network Products under NOS.

REFERENCES:

Network Access Method Reference Manual
NAM Network Definition Language Reference Manual

NETWORK PRODUCTS

NAM NETWORK ACCESS METHOD

- SUPERVISORY MODULES

 - NS NETWORK SUPERVISOR

 - CS COMMUNICATION SUPERVISOR

- COMMUNICATIONS CONTROL

 - NPU NETWORK PROCESSING UNIT (2550)

 - CCP COMMUNICATIONS CONTROL PROGRAM

 - TIP TERMINAL INTERFACE PROGRAM

 - HIP HOST INTERFACE PROGRAM

 - LIP LINK INTERFACE PROGRAM

- INTERFACE PROGRAMS

 - NIP NETWORK INTERFACE PROGRAM

 - PIP PERIPHERAL INTERFACE PROGRAM

 - AIP APPLICATION INTERFACE PROGRAM

NETWORK PRODUCTS

NAM NETWORK ACCESS METHOD

- VALIDATION

NVF NETWORK VALIDATION FACILITY

- APPLICATIONS

RBF REMOTE BATCH FACILITY

TAF TRANSACTION FACILITY

IAF INTERACTIVE FACILITY

TVF TERMINAL VALIDATION FACILITY

- UTILITIES

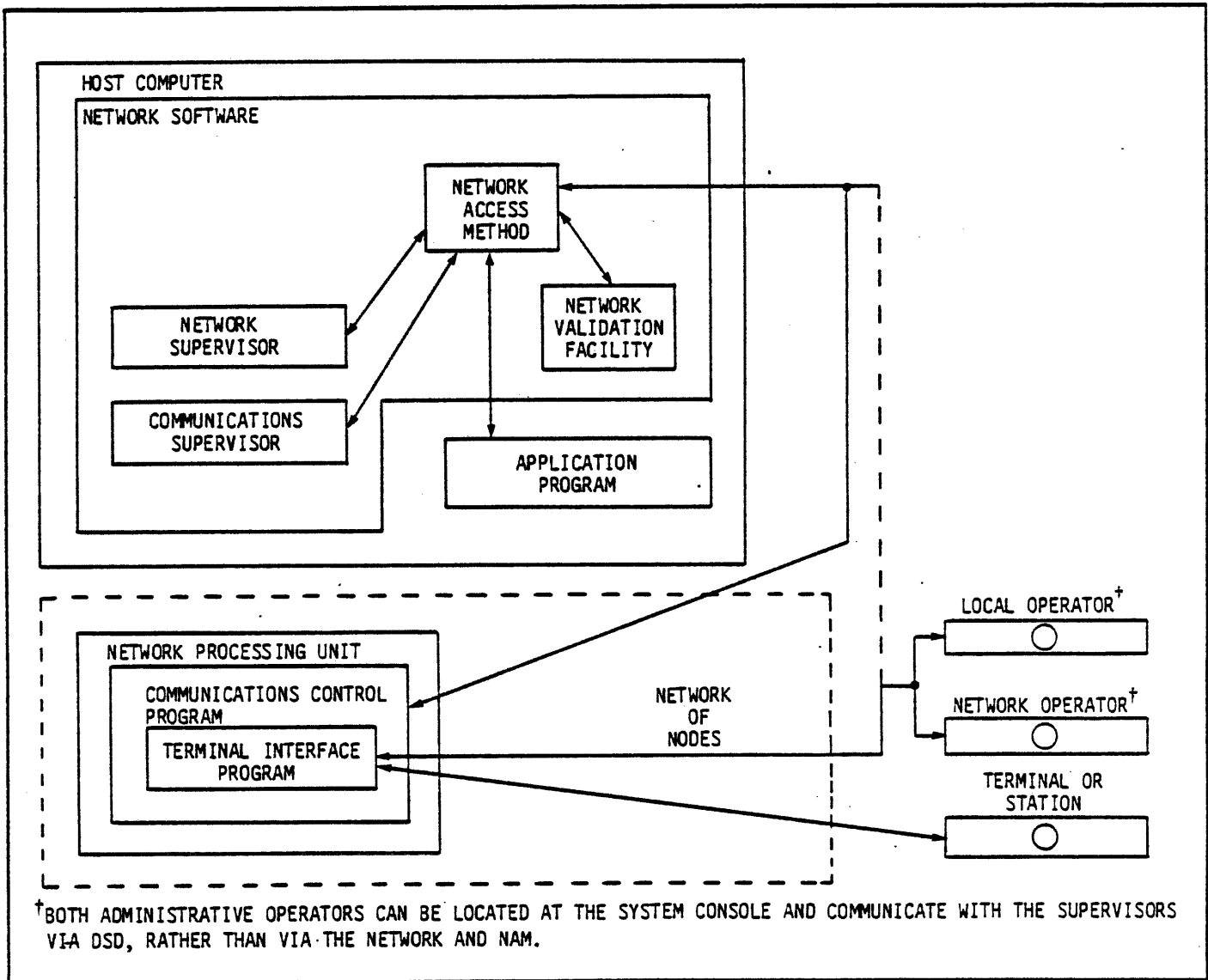
NDL NETWORK DEFINITION LANGUAGE

NPS NETWORK PRODUCT STIMULATOR

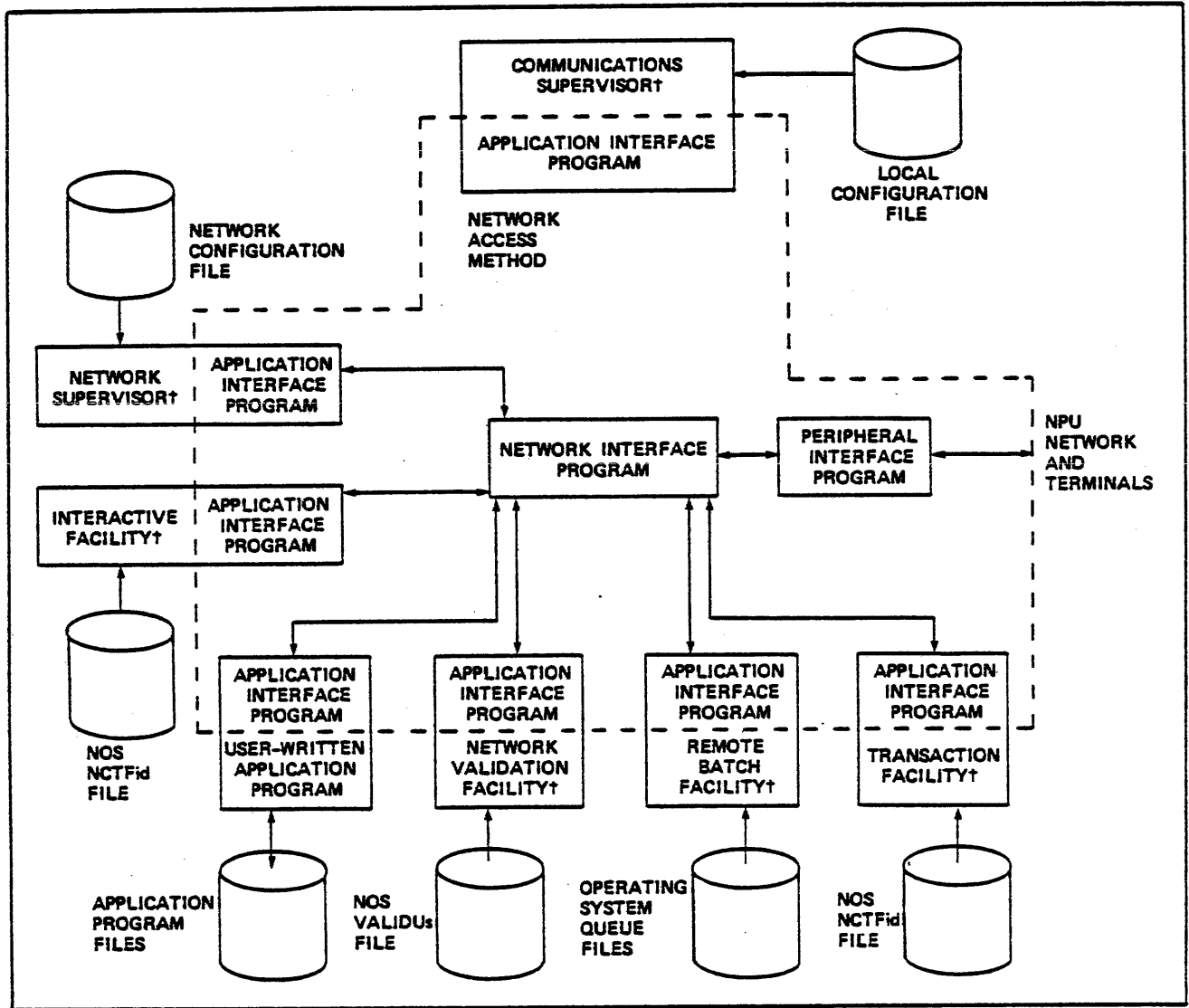
CROSS PASCAL COMPILER FOR CCP

NDA NETWORK DUMP ANALYZER

NETWORK SOFTWARE RELATIONSHIPS



NETWORK ACCESS METHOD COMPONENTS



TYPICAL APPLICATION PROGRAM PROCESSING FLOW

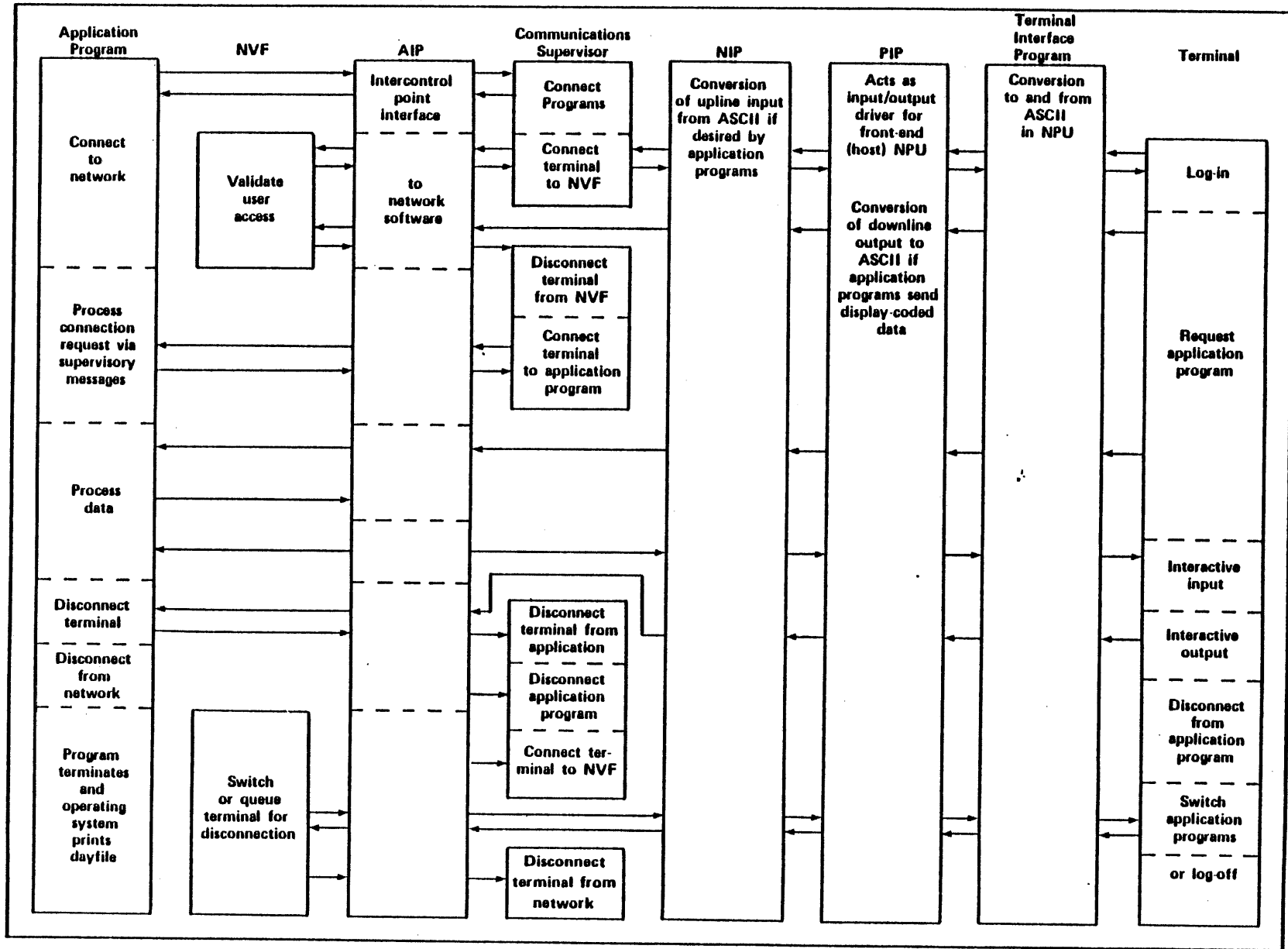


TABLE 1-1. SUPPORTED TERMINAL CLASSES†

Line Protocol	Terminal Class	Device and Archetype Terminal				
		Console	Card Reader	PLine Printer	Card Punch	Plotter
Asynchronous	1	M33				
	2	713				
	3	M1240				
	4	2741				
	5	M40				
	6	H2000				
	7	751††				
	8	T4014				
HASP Synchronous	9	HASP	HASP	HASP	HASP	HASP
Mode 4 Synchronous	10	200UT	200UT	200UT		
	11	214				
	12	711				
	13	714				
	14	731	200UT	200UT		
	15	734	200UT	200UT		

LESSON 24 TIME-SHARING SUBSYSTEM

LESSON PREVIEW:

This lesson introduces the student to the NOS time-sharing subsystem. NOS has two time-sharing subsystems: TELEX and the Interactive Facility (IAF). IAF is a successor to TELEX under the Network Products offering.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Identify the routines that compose the time-sharing subsystem and detail their major features.
- Briefly describe the initialization of the subsystem.
- Describe how the system does input/output with a time sharing terminal.
- Describe how the time-sharing subsystem brings terminal jobs into execution.
- Describe the processing of line numbered data.
- Detail the main loop of the executive program.
- List and detail the various internal queues managed by the time-sharing subsystem.
- Map the time-sharing control point field length allocation.
- Detail the terminal table.
- Describe the acquisition and releasing of POTs and their linkage.
- Discuss the re-entry concepts used in the time-sharing subsystem.
- Describe how the time-sharing executive makes requests for its PP auxiliaries.
- Explain why an output to a terminal is followed by an input from that terminal.

REFERENCES:

NOS IMS - Chapters 15 and 37

TELEX

EXECUTIVE - TELEX
TELEX - INITIALIZATION
TELEX1 - WORKING EXECUTIVE
TELEX2 - EXECUTIVE ERROR EXIT
TELEX3 - TERMINATION

DRIVER - 1TD
2TD - INITIALIZATION
1TD - LOW-SPEED DRIVER
6676
6671
2550-100

AUXILIARY - 1TA

AUXILIARY FUNCTION PROCESSOR CALLED VIA TLX RA+1 CALL BY TELEX

- 1TO

I/O AUXILIARY CALLED WHEN TERMINAL
I/O REQUIRES MASS STORAGE ACTIVITY

- TLX

USER CONTROL RA+1 CALL

COMMON DECKS

COMSREM - TELEX SYSTEM PARAMETERS
COMSTCM - COMMUNICATION
COMSTOR - DRIVER

TELEX

INITIALIZATION

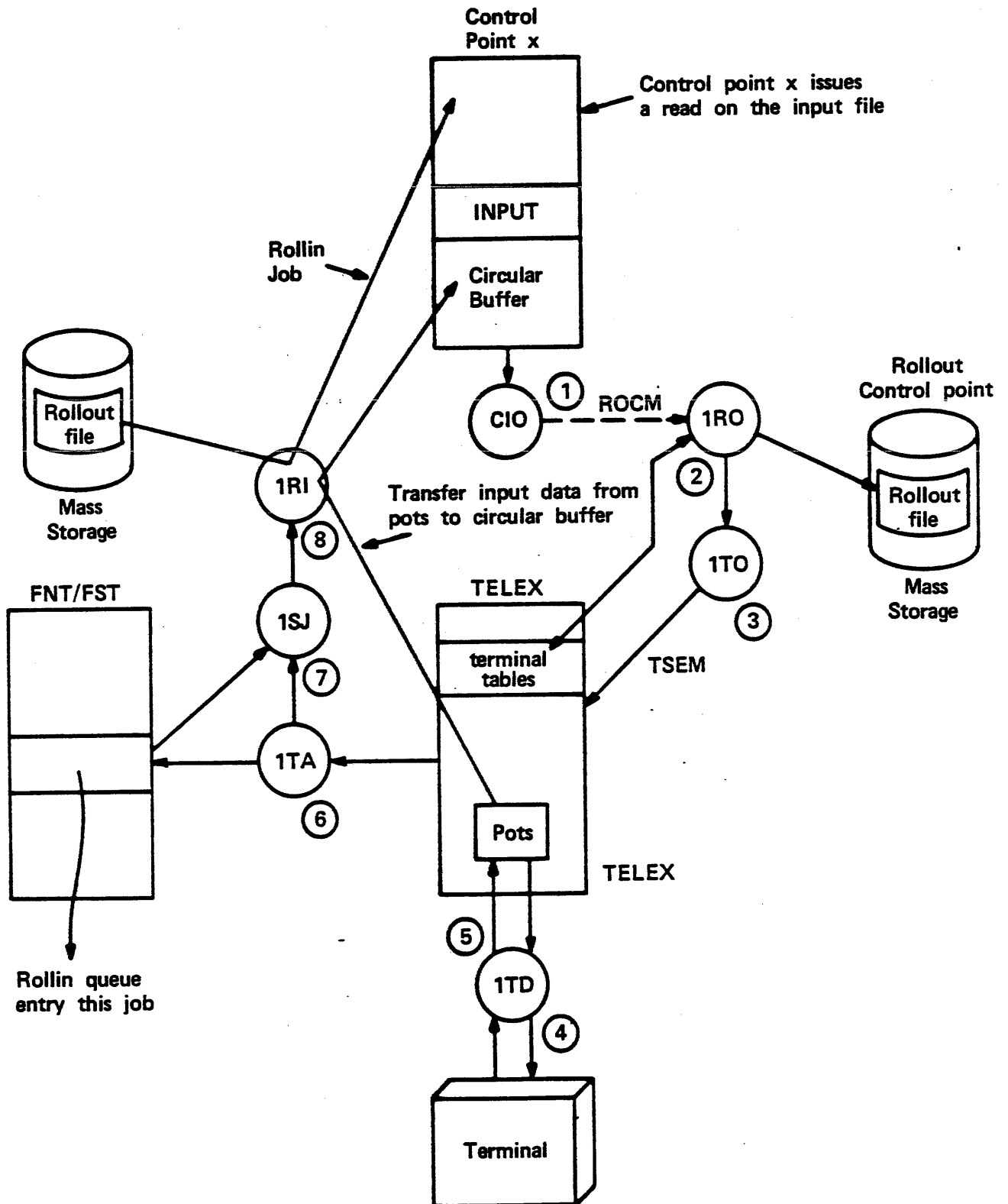
1. IDS SETS UP FNT/FST INPUT QUEUE ENTRY FOR 1SI AND CONTROL POINT 1
2. 1SJ/3SA SCHEDULES CONTROL POINT 1 AND EXECUTES PROCEDURE FILE SPECIFIED THROUGH 1SI
3. TELEX BEGINS EXECUTION IN CP (CP1) AND CALLS INITIALIZATION ROUTINE 1TD
4. NETWORK/SIMULATOR FILE READ AND TERMINAL TABLES BUILT
5. POT CHAIN BUILT BASED ON NUMBER OF TERMINALS
6. STATISTICAL ACCUMULATORS INITIALIZED
7. TELEX QUEUE AREAS INITIALIZED
8. ALL TERMINAL TABLES SET "COMPLETE"
9. HEADER ADDRESS IS SET IN WARN ADDRESS AREA
10. DRIVER QUEUE INITIALIZED
11. DRIVER STARTED AND CONTROL GIVEN TO TELEX1

TELEX

INPUT FROM A TTY

1. JOB ISSUES A READ REQUEST ON INPUT FILE - CALLS CIO. CIO SETS UP TINW AND DOES A ROCM - REQUEST ROLLOUT
2. 1RO DOES ROLLOUT AND CALLS 1TO. NO QUEUE ENTRY IS MADE FOR ROLLOUT FILE
3. 1TO ISSUES TSEM TO INFORM TELEX OF INPUT REQUEST
4. TELEX CALLS 1TD TO ISSUE PROMPT "?" TO USER AT TERMINAL
5. USER INPUTS DATA; 1TD STORES DATA IN POTs
6. WHEN CARRIAGE RETURN IS SENSED, TELEX CALLS 1TA TO REINITIATE THE JOB. 1TA BUILDS ROLLOUT QUEUE FNT/FST ENTRY
7. 1RI ROLLS IN JOB TO A CONTROL POINT AND TRANSFERS DATA FROM THE POTs TO THE JOB'S CIRCULAR BUFFER
8. JOB IS GIVEN THE CPU AND CONTINUES EXECUTION . . .

TERMINAL JOB INTERACTION (INPUT)



TELEX

OUTPUT TO A TTY

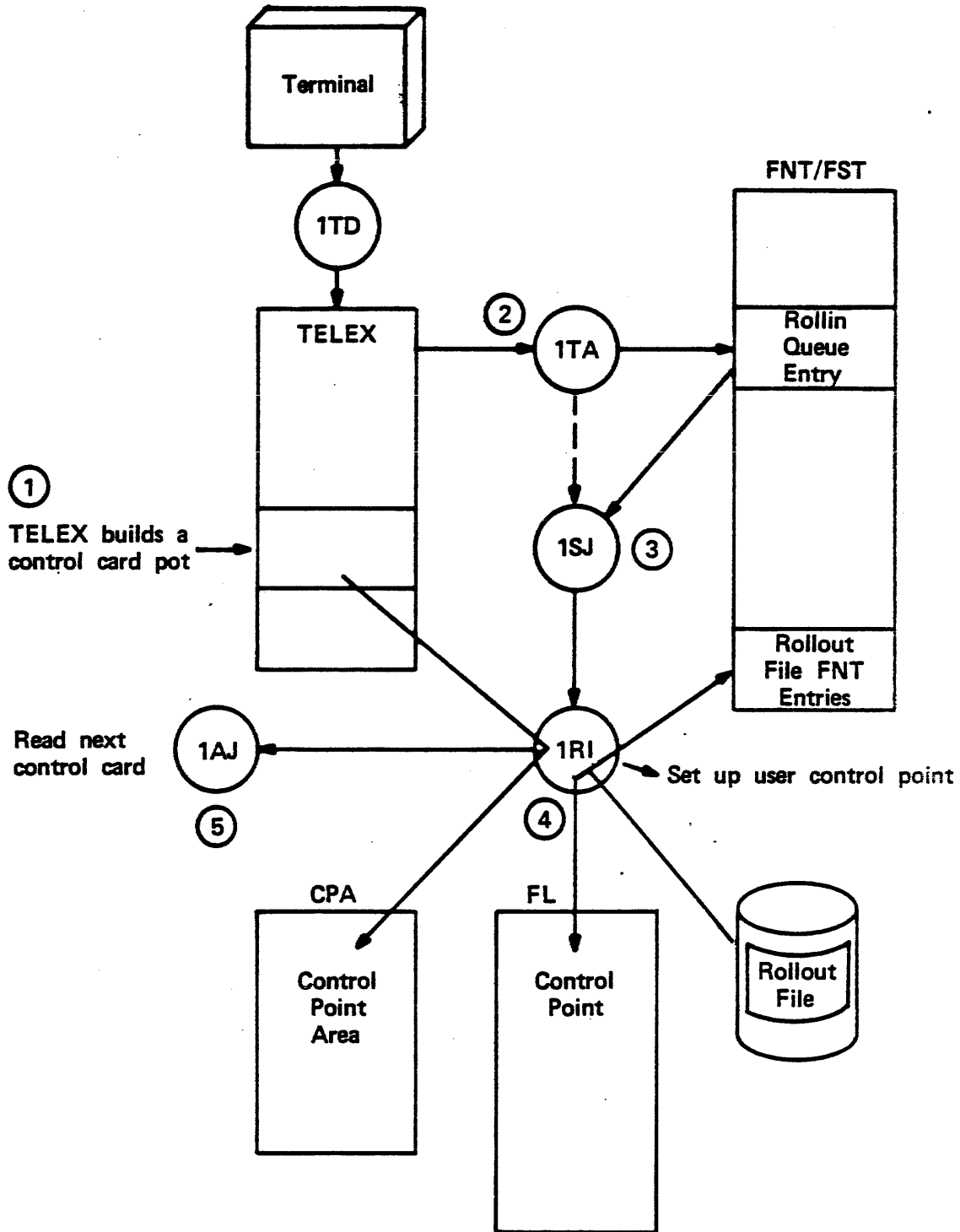
1. JOB ISSUES A WRITE REQUEST ON OUTPUT FILE - CALLS CIO. CIO SETS TIOW AND DOES A ROCM - REQUEST ROLLOUT
2. IRO DOES THE ROLLOUT BUT MAKES NO ROLLOUT QUEUE ENTRY. IRO PUTS THE FIRST SECTOR OF DATA INTO ITS PP MEMORY
3. IRO CAUSES ITO TO BE LOADED INTO ITS PPU
4. ITO DOES A TGPM TO GET POTs FOR DATA. ITO PUTS THE DATA INTO THE POTs AND CALLS TELEX VIA TSEM TO INDICATE OUTPUT IS AVAILABLE
5. TELEX CALLS ITD TO TRANSMIT DATA IN THE POTs TO THE TTY. ITD WILL ASK TELEX FOR MORE DATA AND TELEX WILL CALL ITO TO GET IT UNTIL ALL DATA HAS BEEN TRANSFERRED
6. TELEX CALLS ITA TO REINITIATE JOB AFTER ALL DATA HAS BEEN SENT. ITA BUILDS A ROLLOUT QUEUE FNT/FST ENTRY
7. IRI ROLLS JOB IN; JOB BECOMES A CANDIDATE FOR EXECUTION

TELEX

JOB INITIATION (JOB STEP)

1. CONTROL STATEMENT PUT INTO POT BY TELEX
2. 1TA CALLED
3. 1TA BUILDS ROLLOUT ENTRY AND PUTS CONTROL STATEMENT INTO MS1W AREA OF CONTROL POINT AREA
4. 1RI ROLLS JOB IN
5. 1RI CALLS 1AJ TO ADVANCE JOB AND 1AJ WILL CALL TCS TO PROCESS THE CONTROL STATEMENT

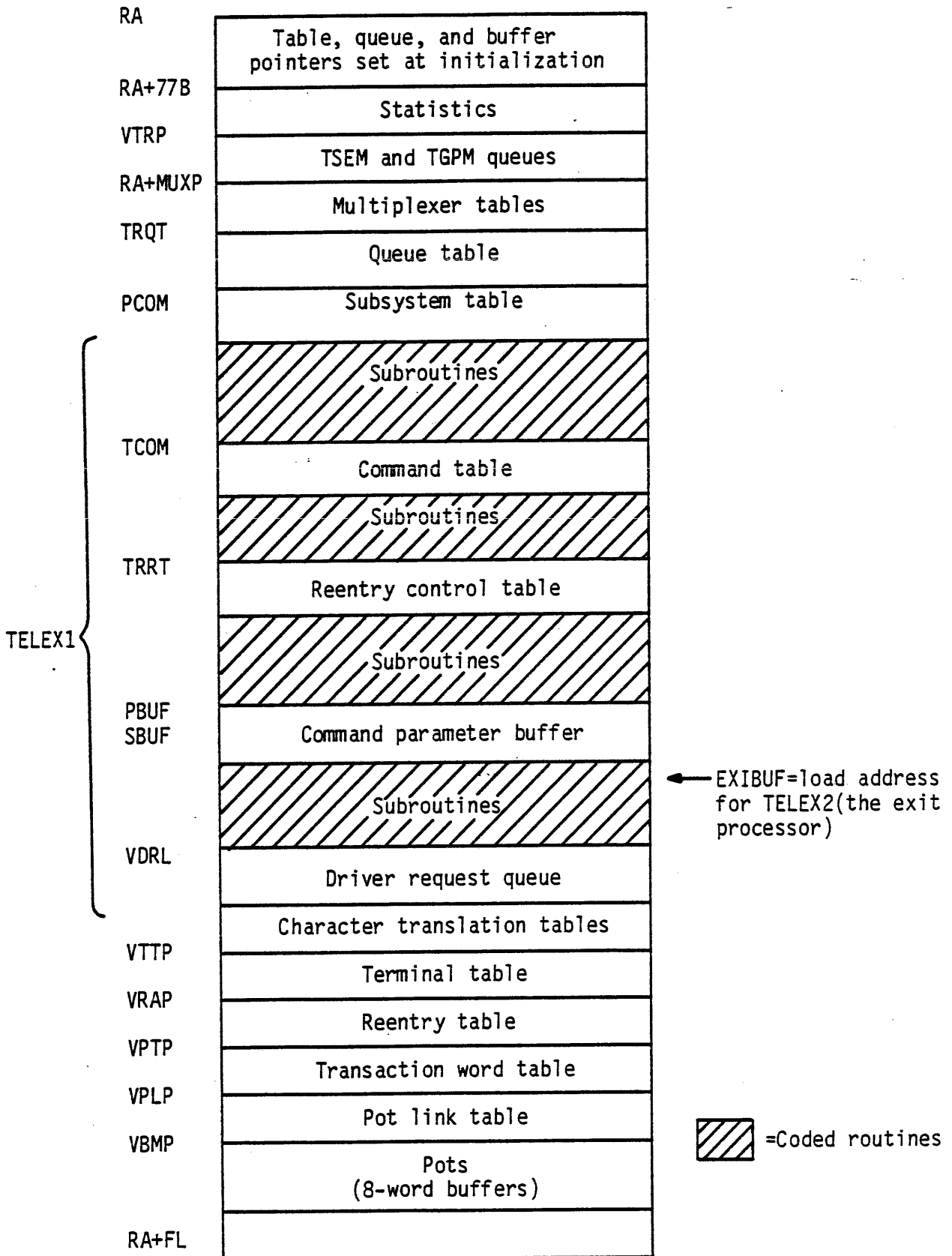
TERMINAL JOB INITIATION



TELEX

LINE NUMBERED DATA

1. USER ENTERS DATA AT TERMINAL
2. DATA BUILD CHARACTER BY CHARACTER AND ENTERED INTO POTs
3. WHEN VIPL POTs HAVE BEEN FILLED, 1TD ISSUES A REQUEST TO DUMP THE POTs (VIPL=2)
4. TELEX SENSES THE DUMP REQUEST AND CALLS 1TO TO DUMP THE POTs TO MASS STORAGE
5. 1TO DUMPS POTs TO ONE MS SECTOR
6. MEANWHILE, 1TD MAY BE FILLING MORE POTs
7. THIS CONTINUES UNTIL USER CAUSES A SORT TO BE DONE
8. MSORT (NOS's ONLY MTOT JOB) IS CALLED
9. MSORT DOES A SHELL SORT AND PACKS DATA INTO FULL SECTORS
10. 1RO SET TERMINAL INTO ACTIVE MODE
11. TELEX PROCESSES THE COMMAND THAT CAUSED THE SORT

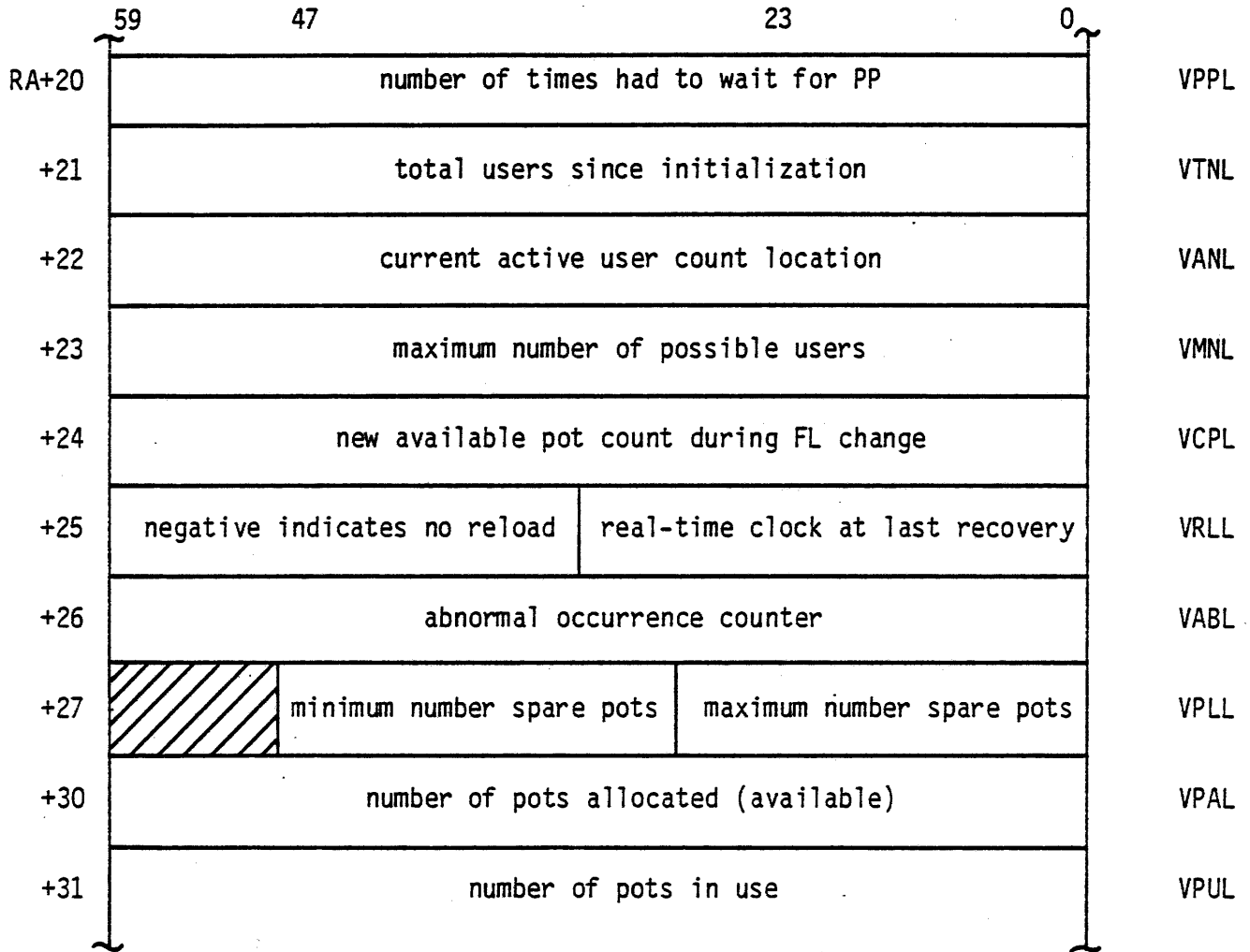


POINTER ADDRESSES

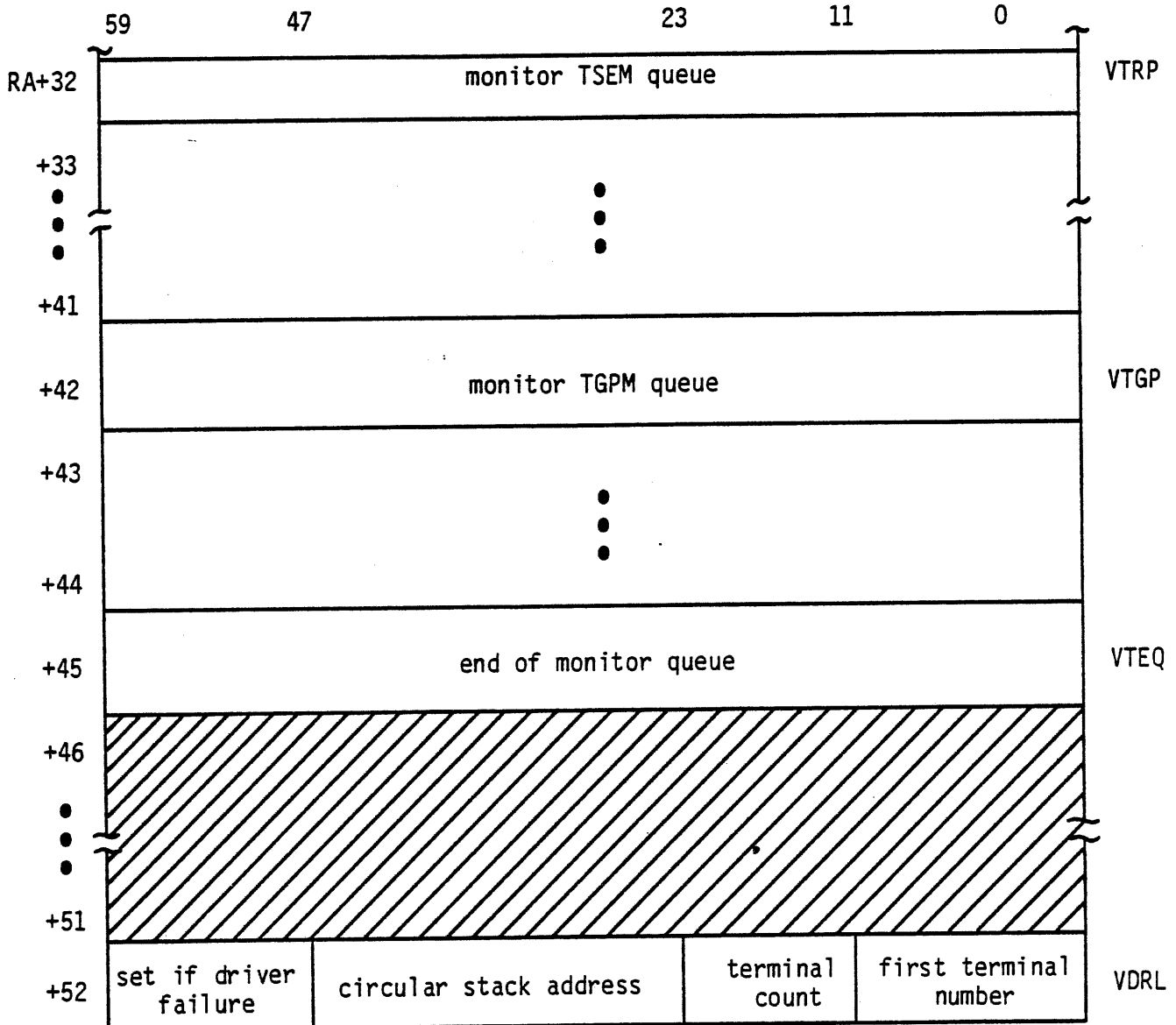
	59	47	41	35	23	17	11	0	
RA+3	FWA terminal tables			LWA+terminal tables				VTPP	
+4	first network terminal number				last network terminal number				VNTP
+5	fwa message status table				lwa+1 message activity table				VMST
+6	fwa network activity table				lwa+1 network activity table				VNAT
+7	length pot link table	FWA pot link table			LWA+1 pot link table				VPLP
+10	FWA command table			LWA+1 command table				VCTP	
+11	FWA pot memory							VBMP	
+12	FWA warn message			FWA header message				VWMP	
+13	FWA reentry table			LWA+1 reentry table				VRAP	
+14	FWA transaction word table			LWA transaction word table				VPTP	
+15	FWA transaction receive buffer			FWA transaction send buffer				UTRN	
+16	1TD minimum cycle time	move to byte 4 each cycle		if non zero *2 driver stops				DEBUG *1	
+17	PFNL word								VFNL

*1 Driver debug word.
 *2 Useful in debugging 1TD.

POINTER ADDRESSES (Continued)



POINTER ADDRESSES (Continued)



TELEX

TELEX MAIN LOOP

- DRI PROCESS DRIVER QUEUE (1TD REQUESTS)
- STM SEND TRANEX MESSAGES
- URT UPDATE RUNNING TIME
- STR PROCESS SYSTEM REQUESTS (TSEM)
- RPC REFILL POT CHAIN QUEUE (TGPM)
- TDQ PROCESS TIME DELAY QUEUE
- CSF CHECK SALVARE FILE
- SOR PROCESS SORT QUEUE
- SCH SCHEDULE JOBS (JOB QUEUE)
- TSH CHECK REQUEST COMPLETIONS (WAIT QUEUE)
- PPU PROCESS PPU REQUESTS
- CTB CHECK TRANSACTION BUFFER
- SPR CHECK FOR FL CHANGE (GET/RETURN POTs)
- EPP ENTER PPU REQUESTS
- DRI
- STR
- RPC
- RECALL
- GO BACK TO TOP

TELEX

DRIVER REQUEST QUEUE

CIRCULAR STACK BUILT BY 1TD (SIMILAR TO A FET I/O BUFFER, 100 WORD QUEUE).

EACH REQUEST IS BIASED BY 2000₈ SO THAT TABLE INDEX IS EASILY RETRIEVED BY AN UNPACK INSTRUCTION UX1,B7 X2

B7 = REQUEST

X1 = ARGUMENTS/PARAMETERS

RQ+2000		P2	P1	TN
---------	--	----	----	----

MONITOR REQUEST QUEUE

BUILT VIA TSEM FUNCTION (10 WORD QUEUE)

FN+2000	P1	P2	P3	P4
---------	----	----	----	----

FUNCTIONS DEFINED IN COMSREM

POT REQUEST QUEUE

BUILT VIA TGPM FUNCTION (3 WORD QUEUE)

TELEX

TERMINAL TABLE

EIGHT WORD ENTRY FOR EACH POSSIBLE ACTIVE USER (IE, ONE FOR EACH MUX PORT)

0	VUIT	USER NUMBER	USER INDEX
---	------	-------------	------------

1	VFNT	PRIMARY FILE NAME	M	BFL
---	------	-------------------	---	-----

M = MODE 2^0 - WRITE LOCKOUT
 2^2 - EXECUTE ONLY

BFL = BATCH FIELD LENGTH

2	VFST	EQ LIST	PRIM EQ	PRIM. FT	CT	CS	0
---	------	---------	---------	----------	----	----	---

3	VROT	WC	ROLL EQ	ROLLOUT FT	FL	SUB STATUS	STATUS
---	------	----	---------	------------	----	------------	--------

SUBSTATUS (1RI)	STATUS	BIT=VALUE
LLLLooFTIsss	TELEX IN CONTROL	0=1
LLLL=LEVEL	SYSTEM IN CONTROL	0=0
I=INTERRUPT	JOB IN SYSTEM	1=0
F=ROLLIN FL	JOB TO BE ROLLED IN	2=1
T=TERMINATE SSJ	JOB WAITING INPUT	3=1
sss= 1 - EOR	OUTPUT AVAILABLE	4=1
2 - EOF	TRANEX OUTPUT	4=1
3 - EOI	SSJ	5=1
	LIST	6=1
	MULTI TERMINAL	7=1
	SUSPENDED	9=1
	ERROR ON LAST OPERATION	11=1

TELEX

TERMINAL TABLE

4	VDPT	FIRST POT	CURRENT POT	POT POSITION	CONTROL FLAGS	ROUTINE ADDR
---	------	--------------	----------------	-----------------	------------------	-----------------

POT POSITION

- 9-11 FIRST WORD IN POT
- 8 INPUT INITIATED IF = 1
- 7 NEXT INPUT POT REQUESTED IF = 1
- 4-6 CURRENT WORD IN POT
- 0-3 CHARACTER NUMBER IN WORD

CONTROL FLAGS

- 7-11 TRANSLATION TABLE INDEX
- 6 FULL DUPLEX
- 5 ERROR FLAG/UPPER CASE FLAG
- 4 MONITOR MODE
- 3 BINARY TRANSMISSION
- 2 TRANSPARENT INPUT
- 1 EXTENDED MODE
- 0 ODD PARITY

5	VCHT	BUFFER	CHR COUNT	SCRATCH	INPUT CC	OUTPUT CC
---	------	--------	--------------	---------	-------------	--------------

6	VDCT	FLAGS	TERM, CONTROL	AUTO MONITOR	ACCESS (AACW)	NEXT MESSAGE
---	------	-------	------------------	-----------------	------------------	-----------------

TELEX

TERMINAL TABLE

7	VSTT	FLAGS	FIRST POT	COMM, INDEX		SUBS	QUEUED
---	------	-------	--------------	----------------	--	------	--------

FLAGS (BIT)

- 0 LOGOUT IN PROGRESS
- 1 LOGOUT ABORT
- 2 WARNING ISSUED
- 3 RUN COMPLETE MESSAGE
- 4 SORT FLAG
- 5 TIME/SRU LIMIT FLAG
- 6 JOB COMPLETE FLAG
- 7 INPUT LOST/JOB NOT STARTED
- 8
- 9 CHARGE REQUIRED
- 10
- 11 DISABLE TERMINAL CONTROL

SUBS = SUBSYSTEM

- 0 NULL
- 1 BASIC
- 2 TSRUN
- 3 FTNTS
- 4 EXECUTE
- 5 BATCH
- 6 ACCESS
- 7 TRANSACTION

TELEX

POT LINK TABLE

PLT CONTROLS POTS IN A MANNER SIMILAR TO HOW TRT CONTROLS TRACKS

PLP	0	1	2	3	4
	7777	0002 1	0003 2	0004 3	0017
	0005 4	0000 5	0007 6	0000 7	0017
	0000 10	0012 11	0013 12	0014 13	0007
	0000 14	0000 15	0000 16	0000 17	0010

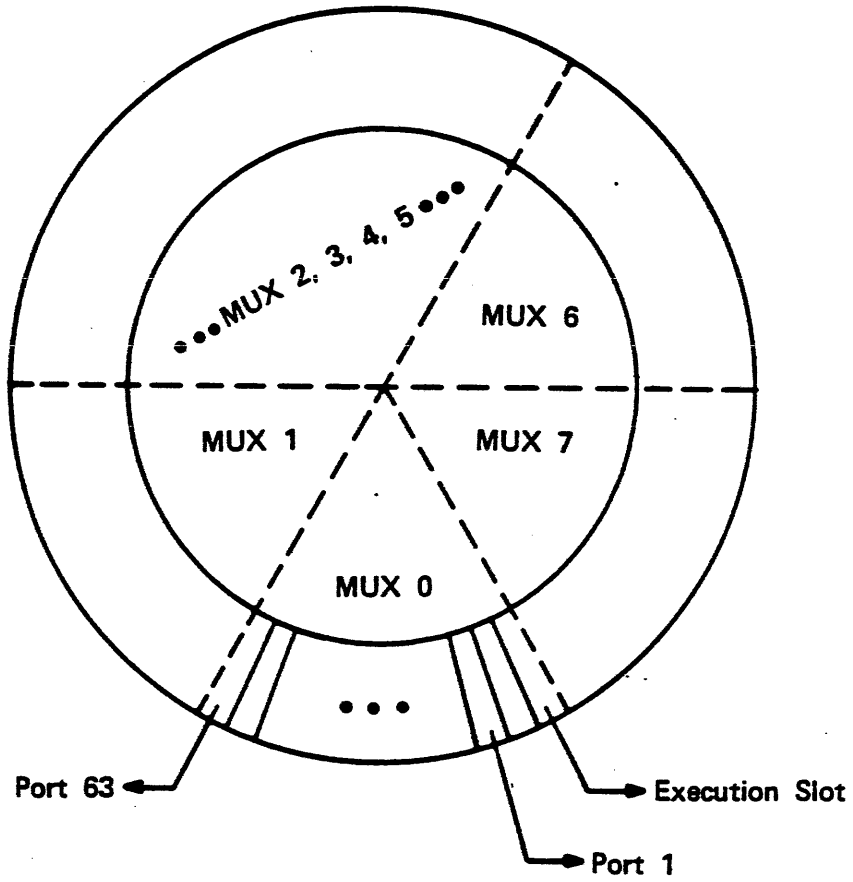
0000 0000 0000
0123

RESERVATION BITS

000 000 000 0 | 00
WORD | BYTE

- POT 0 ALWAYS 7777
- LAST POT IN CHAIN = 0000
- UNUSED POT ALSO = 0000 BUT NOT RESERVED

MULTIPLEXER SERVICING CONCEPT



TELEX

DRIVER

- 1TD ● CAPACITY - 5120 CHARACTERS/SEC
(SIMULTANEOUS BURST)
512 10 CPS TERMINALS
- HALF DUPLEX
- MOST ASCII COMPATIBLE TERMINALS
- TRANSLATION TABLES

AUXILIARY - PP ACTION FOR TELEX

1TA CALLED WITH LIST OF REQUESTS IN POTs OR SINGLE REQUEST

<u>FUNCTION</u>	<u>DESCRIPTION</u>
1	ADJUST TELEX FL
2	RETURN TERMINAL JOB
3	CREATE ROLLOUT FILE
4	LOGOUT TERMINAL
5	DISPLAY ACCOUNTING
6	TERMINAL RECOVERY
7	INCREMENT RESOURCE LIMIT (TL, SRU)
10	RECOVERY FILE PROCESSOR
11	SCHEDULE JOBS
12	GATHER STATISTICS
13	CLEAN UP SALVARE

TELEX

1TO AUXILIARY - TTY INPUT/OUTPUT

1TO DOES TERMINAL INPUT/OUTPUT THAT REQUIRES MASS STORAGE REQUESTS

RECOVERY FILE - SALVARE

- BUILT AT INITIALIZATION TIME
- TWO WORDS FOR EACH DEFINED TERMINAL

	E Q	FT	HH MM SS	UI
--	--------	----	----------	----

EQ = ROLLOUT FILE EQUIPMENT
FT = ROLLOUT FILE FIRST TRACK
HHMMSS = LAST ENTRY TIME
UI = USER INDEX

- ENTRIES CLEARED AFTER 10 MINUTES
- IN RECOVERY, BOI + EOI OF USER'S FILES ARE VALIDATED IF SENSE SWITCH SET

TELEX

RE-ENTRY

RE-ENTRY TABLE FOR RETURNING CONTROL OR HAVING FUNCTIONS PERFORMED WHEN A SET OF CONDITIONS ARE MET.

ONE WORD PER TERMINAL WITH INDEX TO TABLE OF RE-ENTRY PROCESSORS DEFINED VIA COMMAND MACRO

1TD RE-ENTRY

ENTRY POINTS WHICH ARE JUMPED TO BY ANY SUBROUTINE THAT CANNOT COMPLETE ITS TASK IN A SINGLE INTERNAL TIME SLICE

RETURN MACRO

IAF

EXECUTIVE - IAFEX

IAFEX - INITIALIZATION
IAFEX1 - WORKING EXECUTIVE
IAFEX2 - DUMP EXECUTIVE
IAFEX3 - TERMINATION
IAFEX4 - INTERFACE TO NAM

INITIALIZATION - 1TN

AUXILIARY - 1TA

AUXILIARY FUNCTION PROCESSOR CALLED VIA SPC RA+1 CALL BY IAF

- 1T0

I/O AUXILIARY CALLED WHEN TERMINAL
I/O REQUIRES MASS STORAGE ACTIVITY

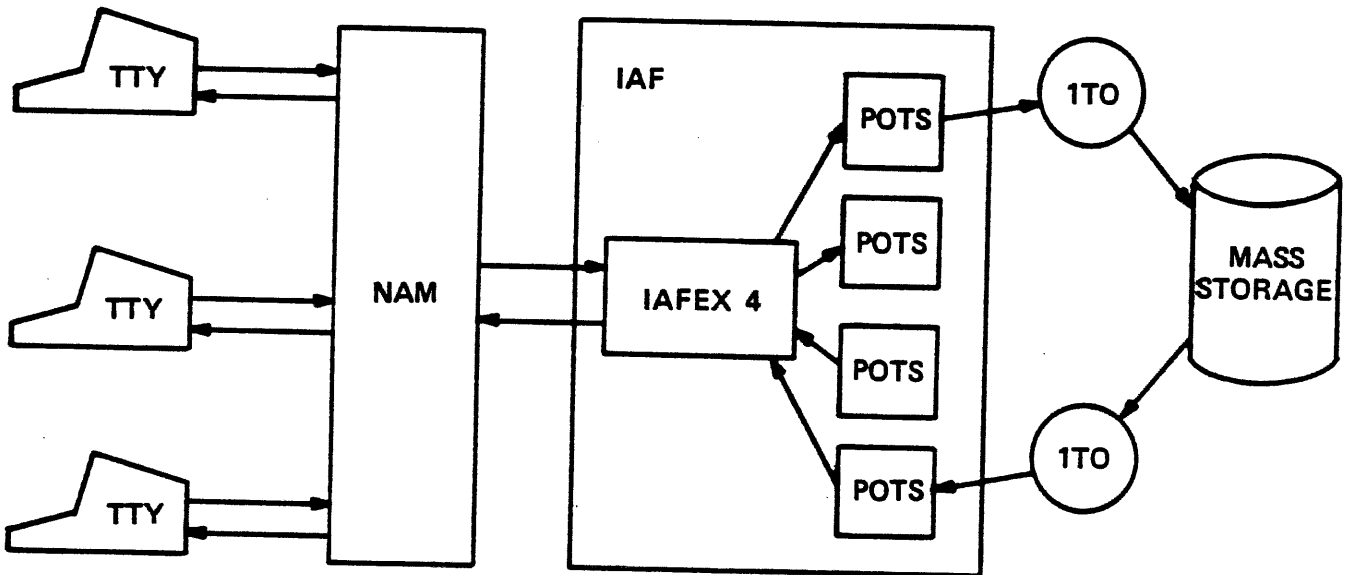
- TLX

USER CONTROL RA+1 CALL

COMMON DECKS

COMSNET - NETWORK PARAMETERS
COMSREM - TELEX SYSTEM PARAMETERS
COMSTCM - COMMUNICATION
COMSTDR - DRIVER
COMIICS - INITIAL CONTROL STATEMENTS
COMIIES - EST SEARCH
COMSNCD - NETWORK COMMUNICATION

IAF



IAF

INITIALIZATION

1. IDS SETS UP FNT/FST INPUT QUEUE ENTRY FOR ISI AND CONTROL POINT 1
2. ISJ/3SA SCHEDULES CONTROL POINT 1 AND LOADS EXECUTES PROCEDURE FILE SPECIFIED THROUGH ISI
3. IAFEX BEGINS EXECUTION IN CP (CP1) AND CALLS INITIALIZATION ROUTINE 1TN
4. EST ENTRY 76B READ AND TERMINAL TABLES BUILT
5. POT CHAIN BUILT BASED ON NUMBER OF TERMINALS
6. STATISTICAL ACCUMULATORS INITIALIZED
7. IAF QUEUE AREAS INITIALIZED
8. ALL TERMINAL TABLES SET "COMPLETE"
9. HEADER ADDRESS IS SET IN WARN ADDRESS AREA
10. DRIVER QUEUE INITIALIZED
11. CONTROL GIVEN TO IAFEX1

IAF

INPUT FROM A TTY

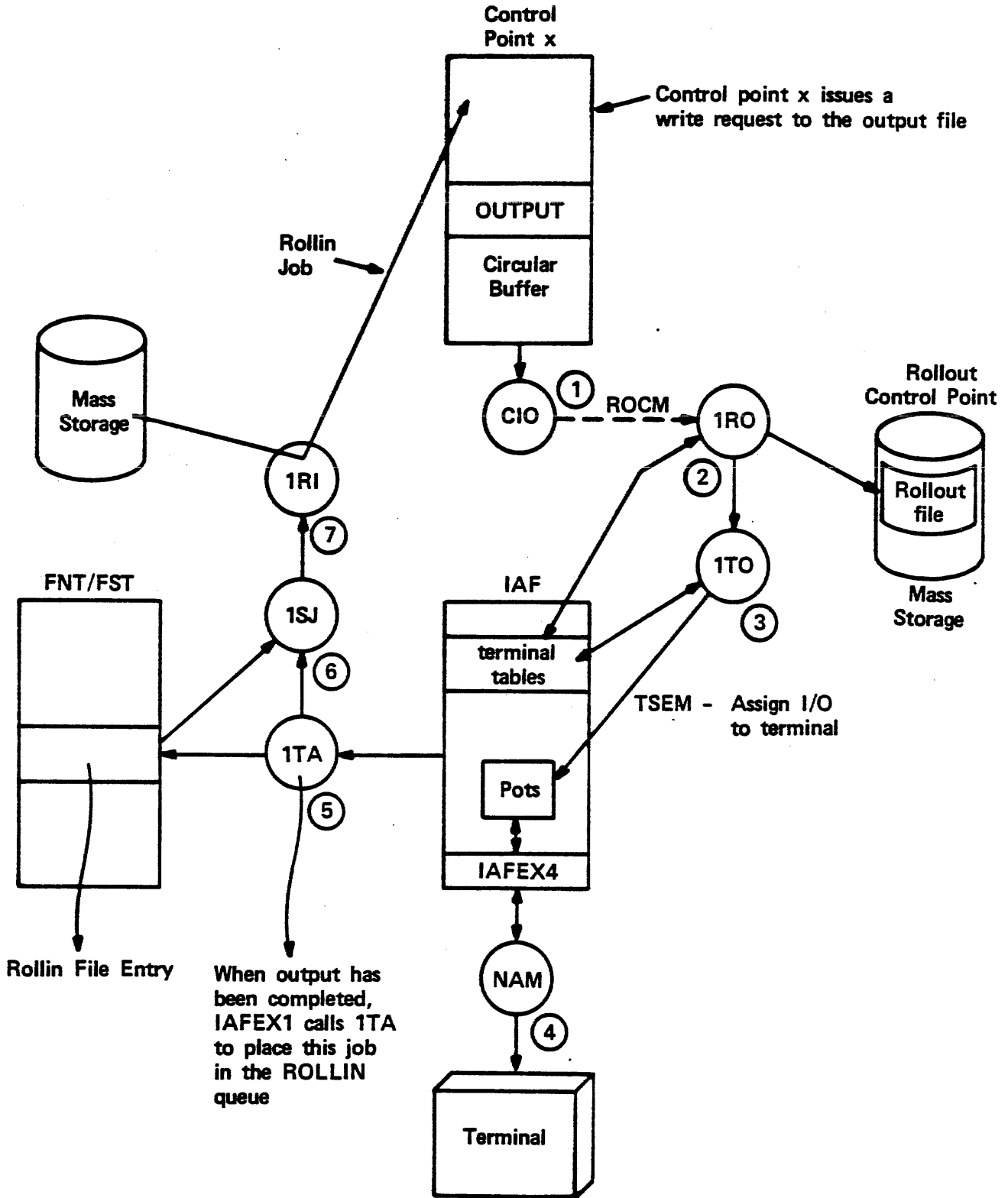
1. JOB ISSUES A READ REQUEST ON INPUT FILE - CALLS CIO. CIO SETS UP TINW AND DOES A ROCM - REQUEST ROLLOUT
2. 1RO DOES ROLLOUT AND CALLS 1TO. NO QUEUE ENTRY IS MADE FOR ROLLOUT FILE.
3. 1TO ISSUES TSEM TO INFORM IAF OF INPUT REQUEST
4. IAFEX4 CAUSES NAM TO ISSUE PROMPT "?" TO USER AT TERMINAL
5. USER INPUTS DATA; IAFEX4 STORES DATA IN POTs
6. WHEN END-OF-LINE IS SENSED, IAF CALLS 1TA TO REINITIATE THE JOB. 1TA BUILDS ROLLOUT QUEUE FNT/FST ENTRY
7. 1RI ROLLS IN JOB TO A CONTROL POINT AND TRANSFERS DATA FROM THE POTs TO THE JOB'S CIRCULAR BUFFER
8. JOB IS GIVEN THE CPU AND CONTINUES EXECUTION . . .

IAF

OUTPUT TO A TTY

1. JOB ISSUES A WRITE REQUEST ON OUTPUT FILE - CALLS CIO. CIO SETS TIOW AND DOES A ROCM - REQUEST ROLLOUT
2. IRO DOES THE ROLLOUT BUT MAKES NO ROLLOUT QUEUE ENTRY. IRO PUTS THE FIRST SECTOR OF DATA INTO ITS PP.MEMORY
3. IRO CAUSES ITO TO BE LOADED INTO ITS PPU
ITO DOES A TGPM TO GET POTs FOR DATA. ITO PUTS THE DATA INTO THE POTs AND CALLS IAF VIA TSEM TO INDICATE OUTPUT IS AVAILABLE
4. IAFEX1 CALLS IAFEX4 TO TRANSMIT DATA IN THE POTs TO THE TTY (USING NAM). IAFEX4 WILL ASK IAFEX1 FOR MORE DATA AND IAFEX1 WILL CALL ITO TO GET IT UNTIL ALL DATA HAS BEEN TRANSFERRED
5. IAF CALLS ITA TO REINITIATE JOB AFTER ALL DATA HAS BEEN SENT. ITA BUILDS A ROLLOUT QUEUE FNT/FST ENTRY
6. IRI ROLLS JOB IN; JOB BECOMES A CANDIDATE FOR EXECUTION

TERMINAL JOB INTERACTION (OUTPUT)

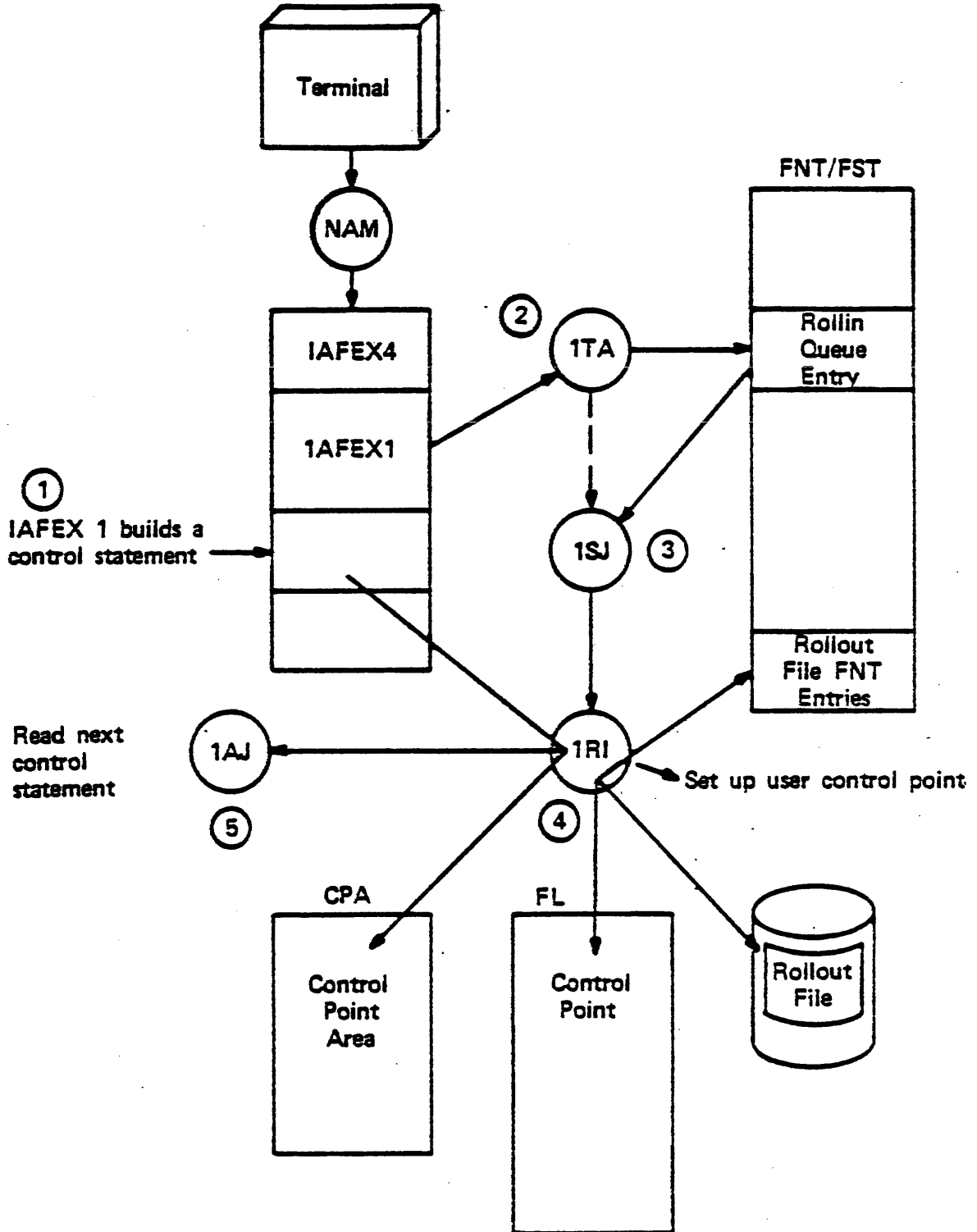


IAF

JOB INITIATION (JOB STEP)

1. CONTROL STATEMENT PUT INTO POT BY IAF AND CALLS 1TA
2. 1TA BUILDS ROLLOUT ENTRY AND PUTS CONTROL STATEMENT INTO MS1W AREA OF CONTROL POINT AREA
3. 1SJ SCHEDULES JOB FOR EXECUTION
4. IRI ROLLS JOB IN
5. IRI CALLS 1AJ TO ADVANCE JOB AND 1AJ WILL CALL TCS TO PROCESS THE CONTROL STATEMENT

TERMINAL JOB INITIATION



IAF

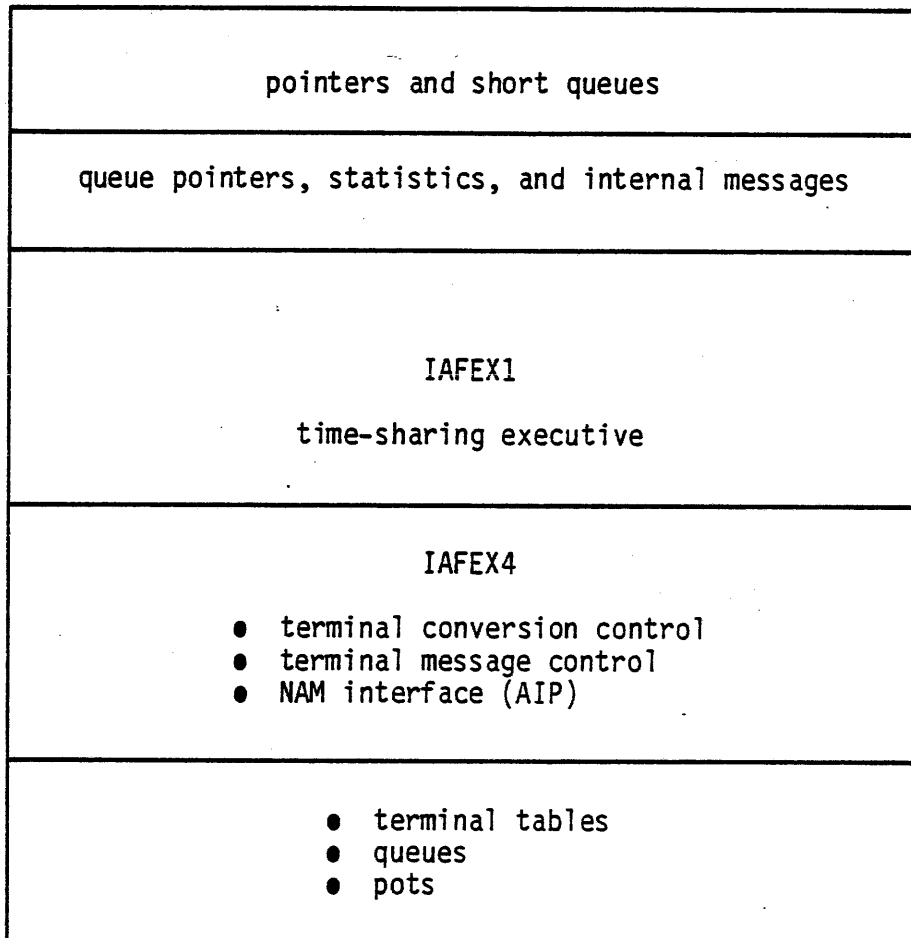
LINE NUMBERED DATA

1. . USER ENTERS DATA AT TERMINAL
2. DATA BUILT CHARACTER BY CHARACTER AND ENTERED INTO POTs
3. WHEN VIPL POTs HAVE BEEN FILLED, IAFEX4 ISSUES A REQUEST TO DUMP THE POTs (VIPL=2)
4. IAF SENSES THE DUMP REQUEST AND CALLS 1TO TO DUMP THE POTs TO MASS STORAGE
5. 1TO DUMPS POTs TO ONE MS SECTOR
6. MEANWHILE, IAFEX4 MAY BE FILLING MORE POTs
7. THIS CONTINUES UNTIL USER CAUSES A SORT TO BE DONE
8. MSORT (NOS's ONLY MTOT JOB) IS CALLED
9. MSORT DOES A SHELL SORT AND PACKS DATA INTO FULL SECTORS
10. 1RO SET TERMINAL INTO ACTIVE MODE
11. IAF PROCESSES THE COMMAND THAT CAUSED THE SORT

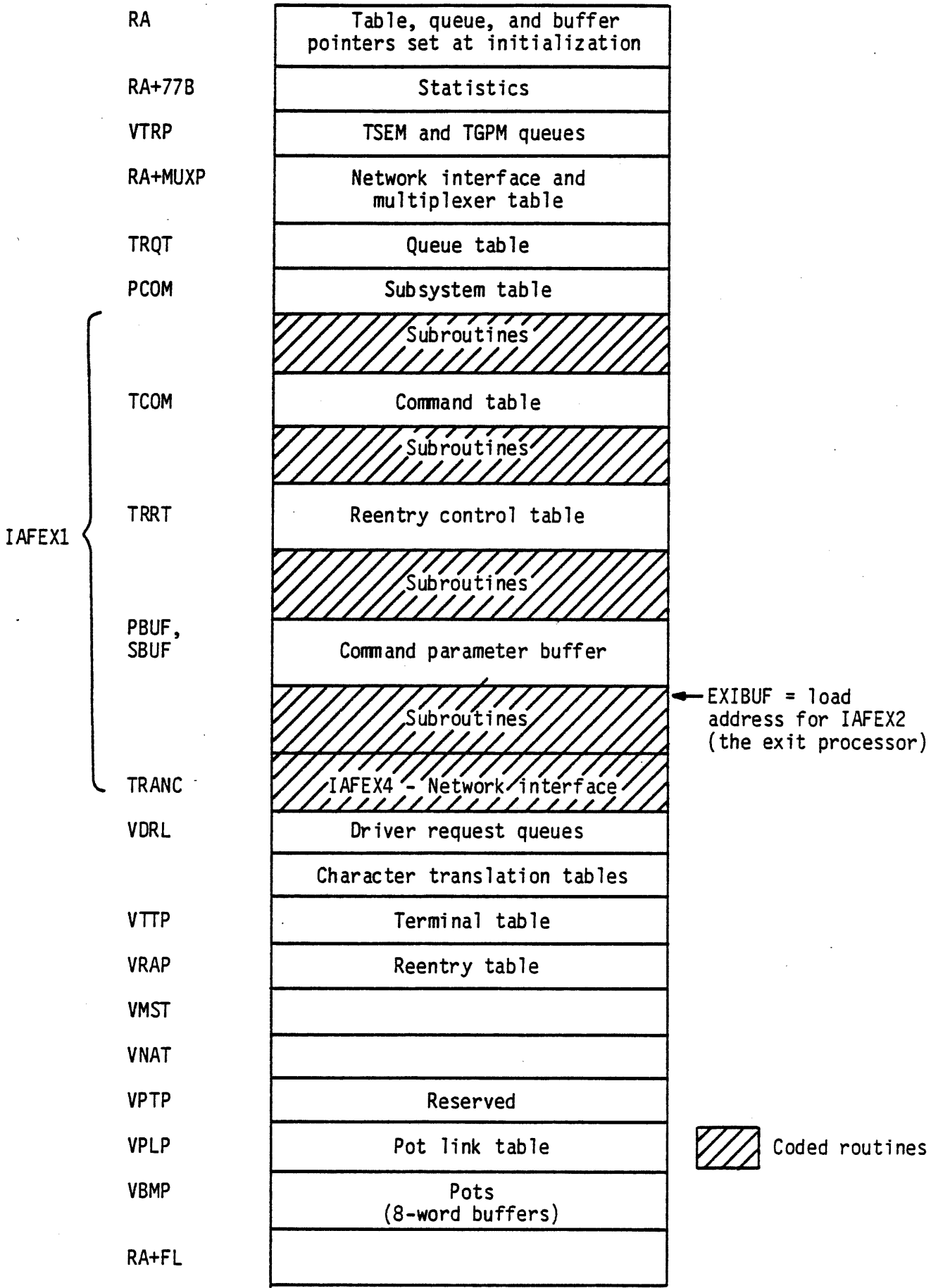
IAFEX CONTROL POINT

RA

RA+TXORG



IAFEX1 MEMORY MAP

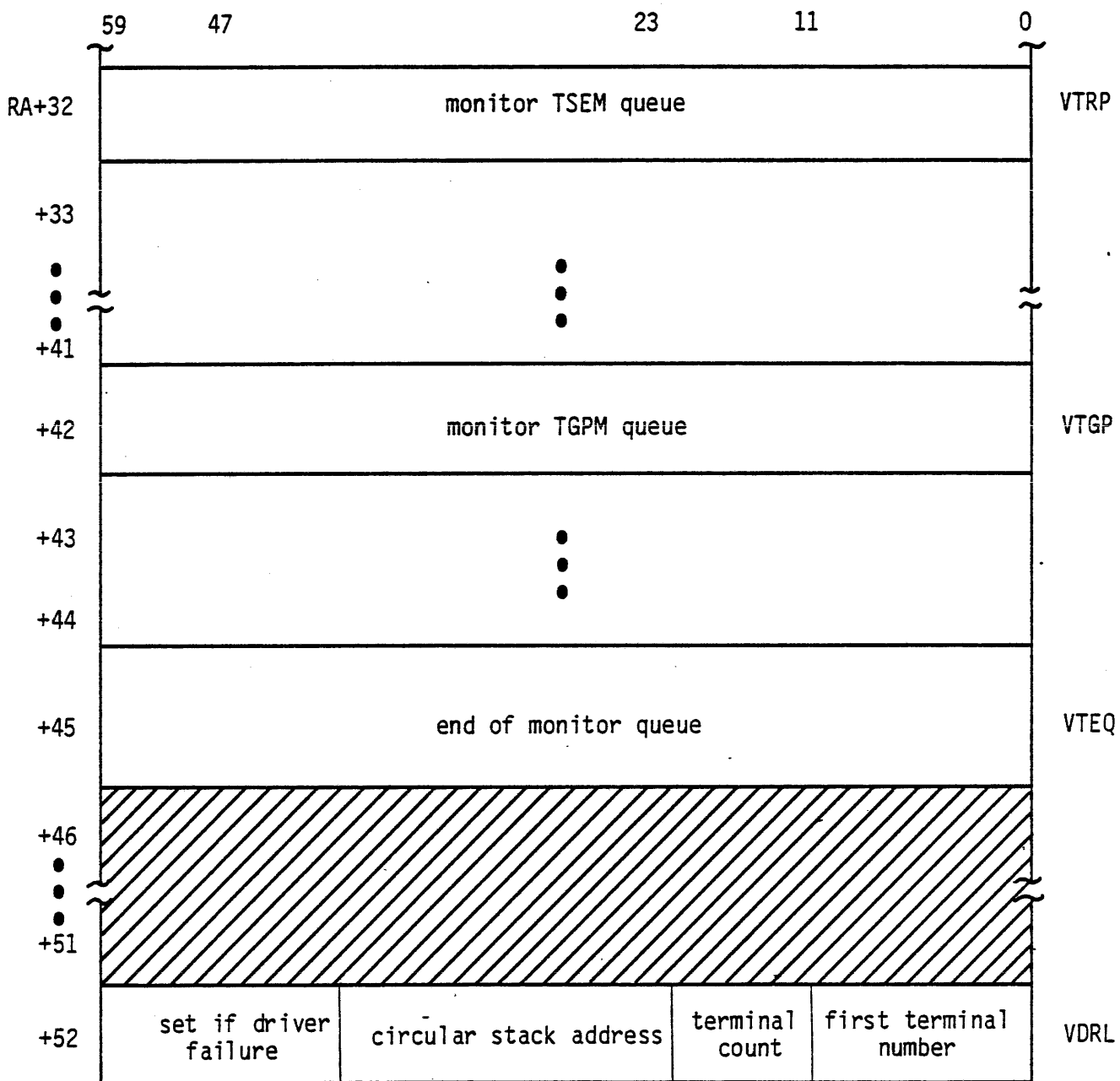


POINTER ADDRESSES

	59	47	41	35	23	17	11	0		
RA+ 3				FWA terminal tables			LWA+1 terminal tables		VTTP	
+ 4	first network terminal number				last network terminal number				VNTP	
+ 5	fwa message status table				lwa+1 message status table				VMST	
+ 6	fwa network activity table				lwa+1 network activity table				VNAT	
+ 7	length pot link table				FWA pot link table				LWA+1 pot link table	VPLP
+10				FWA command table				LWA+1 command table	VCTP	
+11							FWA pot memory		VBMP	
+12				FWA warn message				FWA header message		VWMP
+13				FWA reentry table				LWA+1 reentry table		VRAP
+14				reserved				reserved		VPTP
+15				reserved				reserved		UTRN
+16			driver minimum cycle time				move to byte 4 each cycle		if non zero ^{*2} driver stops	DEBUG *1
+17	PFNL word								VFNL	

*1 Driver debug word
 *2 Useful in debugging 1TD

POINTER ADDRESSES (Continued)



IAF

IAF MAIN LOOP

- DRI PROCESS DRIVER QUEUE (DRIVER REQUESTS)
- URT UPDATE RUNNING TIME
- STR PROCESS SYSTEM REQUESTS (TSEM)
- RPC REFILL POT CHAINQUEUE (TGPM)
- TDQ PROCESS TIME DELAY QUEUE
- CSF CHECK SALVARE FILE
- SOR PROCESS SORT QUEUE
- SCH SCHEDULE JOBS (JOB QUEUE)
- TSH CHECK REQUEST COMPLETIONS (WAIT QUEUE)
- PPU PROCESS PPU REQUESTS
- NDR INTERFACE TO NAM
- SPR CHECK FOR FL CHANGE (GET/RETURN POTs)
- EPP ENTER PPU REQUESTS
- DRI
- STR
- RPC
- RECALL
- GO BACK TO TOP

IAF

DRIVER REQUEST QUEUE

CIRCULAR STACK BUILT BY IAFEX4 (SIMILAR TO A FET I/O BUFFER, 100 WORD QUEUE).

EACH REQUEST IS BIASED BY 2000₈ SO THAT TABLE INDEX IS EASILY RETRIEVED BY AN UNPACK INSTRUCTION UX1,B7 X2

B7 = REQUEST
X1 = ARGUMENTS/PARAMETERS

RQ+2000		P2	P1	TN
---------	--	----	----	----

MONITOR REQUEST QUEUE

BUILT VIA TSEM FUNCTION (10 WORD QUEUE)

FN+2000	P1	P2	P3	P4
---------	----	----	----	----

FUNCTIONS DEFINED IN COMSREM

POT REQUEST QUEUE

BUILT VIA TGPM FUNCTION (3 WORD QUEUE)

IAF

TERMINAL TABLE

EIGHT WORD ENTRY FOR EACH POSSIBLE ACTIVE USER (IE, ONE FOR EACH MUX PORT)

0	VUIT	USER NUMBER	USER INDEX
---	------	-------------	------------

1	VFNT	PRIMARY FILE NAME	M	BFL
---	------	-------------------	---	-----

M = MODE 2⁰ - WRITE LOCKOUT

2² - EXECUTE ONLY

BFL = BATCH FIELD LENGTH

2	VFST	EQ LIST	PRIM EQ	PRIM FT	CT		STATUS
---	------	---------	---------	---------	----	--	--------

AA

- LIST OR PRIMARY FILE CURRENT SECTOR
- CONTROL STATEMENT POT
- ACCOUNTING POT

STATUS

11-6	UNUSED
5	LINE CONTINUATION
4	7400 ESCAPE
3	7600 ESCAPE
2	BINARY
1	TRANSPARENT
0	EXTENDED

IAF

TERMINAL TABLE (CON'T)

3	VROT	WC	ROLL EQ	ROLLOUT FT	FL	SUB STATUS	STATUS
---	------	----	------------	---------------	----	---------------	--------

SUBSTATUS (IRI)	STATUS	BIT=VALUE
LLLLooFTIsss	IAF IN CONTROL	0=1
LLLL=LEVEL	SYSTEM IN CONTROL	0=0
I=INTERRUPT	JOB IN SYSTEM	1=0
F=ROLLIN FL	JOB TO BE ROLLED IN	2=1
T=TERMINATE SSJ	JOB WAITING INPUT	3=1
SSS=1 - EOR	OUTPUT AVAILABLE	4=1
2 - EOF	SSJ	5=1
3 - EOI	LIST	6=1
	MULTI TERMINAL	7=1
	SUSPENDED	9=1
	ERROR ON LAST OPERATION	11=1

IAF

TERMINAL TABLE

4	VDPT	FIRST POT	LAST POT	FW	WC	CONTROL FLAGS	
---	------	-----------	----------	----	----	---------------	--

FW FIRST WORD OF FIRST POT

WC LAST POT WORD COUNT

CONTROL FLAGS

- 11-5 UNUSED
- 4 SOURCE INPUT
- 3 BINARY TRANSMISSION
- 2 TRANSPARENT INPUT
- 1 UNUSED
- 0 UNUSED

5	VCHT	NDR REENTRY		POT POINTER	INPUT CC	OUTPUT CC
---	------	-------------	--	-------------	----------	-----------

6	VDCT	FLAGS	TERM. CONTROL	AUTO INCR.	ACCESS (AACW)	NEXT MESSAGE
---	------	-------	---------------	------------	---------------	--------------

FLAGS

- 11 DRIVER REQUEST FROM IAFEX1
- 10 INTERRUPT COMPLETE
- 9 USER LOGGED IN
- 8 INPUT REQUESTED
- 7 UNUSED
- 6 READ DATA MODE
- 5 UNUSED
- 4 UNUSED
- 3 EXTERNAL MODE
- 2 TEXT MODE
- 1 AUTO MODE
- 0 TAPE MODE

IAF

TERMINAL TABLE

7	VSTT	FLAGS	FIRST POT	COMM. INDEX		S U B S	QUEUED
---	------	-------	--------------	----------------	--	------------------	--------

FLAGS (BIT)

- 0 LOGOUT IN PROGRESS
- 1 UNCONDITIONAL ABORT FLAG
- 2 WARNING ISSUED
- 3 RUN COMPLETE MESSAGE
- 4 SORT FLAG
- 5 TIME/SRU LIMIT FLAG
- 6 JOB COMPLETE FLAG
- 7 INPUT LOST/JOB NOT STARTED
- 8
- 9 CHARGE REQUIRED
- 10 CONDITIONAL ABORT FLAG
- 11 DISABLE TERMINAL CONTROL

SUBS = SUBSYSTEM

- 0 NULL
- 1 BASIC
- 3 FTNTS
- 4 EXECUTE
- 5 BATCH
- 6 ACCESS

IAF

POT LINK TABLE

PLT CONTROLS POTS IN A MANNER SIMILAR TO HOW TRT CONTROLS TRACKS

PLP	0	1	2	3	4
	7777	0002 1	0003 2	0004 3	0017
	0005 4	0000 5	0007 6	0000 7	0017
	0000 10	0012 11	0013 12	0014 13	0007
	0000 14	0000 15	0000 16	0000 17	0010

0000 0000 0000
 0123
 RESERVATION BITS

000 000 000 0 | 00
 WORD | BYTE

- POT 0 ALWAYS 7777
- LAST POT IN CHAIN = 0000
- UNUSED POT ALSO = 0000 BUT NOT RESERVED

IAF

RE-ENTRY

RE-ENTRY FOR RETURNING CONTROL OR HAVING FUNCTIONS PERFORMED WHEN A SET OF CONDITIONS ARE MET.

ONE WORD PER TERMINAL WITH INDEX TO TABLE OF RE-ENTRY PROCESSORS DEFINED VIA COMMND MACRO.

IAF

NAM INTERFACE - IAFEX4

SEND AND RECEIVE DATA FROM TERMINALS THAT ARE CONNECTED TO IAF THROUGH NAM

- RECEIVES, INTERPRETS, AND SENDS SUPERVISORY MESSAGES
- TRANSFORMS OUTGOING DATA FROM INTERNAL FORMS TO THE APPROPRIATE NETWORK FORMAT
- TRANSFORMS INCOMING DATA FROM NETWORK FORMAT TO INTERNAL FORMAT
- MANAGES DATA TRAFFIC TO OPTIMIZE INTERACTIVE PERFORMANCE

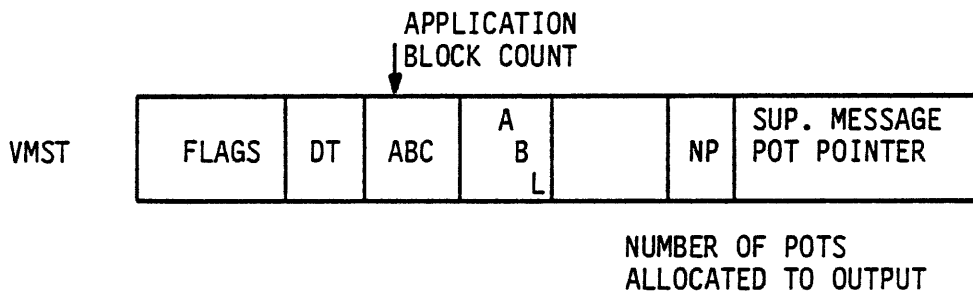
FUNCTIONS

- CONNECTION ESTABLISHMENT (LOG IN)
- COMMAND LINE ENTRY
- SOURCE LINE ENTRY
- INPUT TO RUNNING PROGRAM
- OUTPUT PROCESSING
- SESSION TERMINATION

interface control words interface statistics message headers and fixed messages
IAF/network interface control
terminal manager
supervisory message processor
upline data manager
network interface control subroutines
general subroutines
data translation subroutines
common decks and code conversion tables
interface buffers
application interface program (AIP)

MESSAGE STATUS TABLE

1 WORD/NETWORK TERMINAL



FLAGS

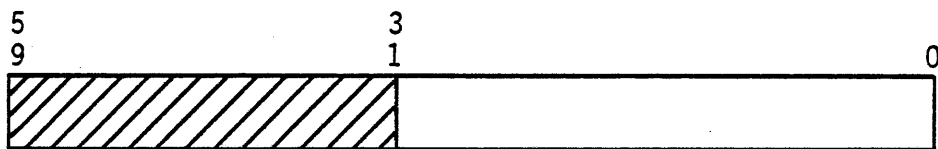
- BIT 59 = TERMINAL ON-LINE
- 58 = SUSPEND TRAFFIC
- 57 = BREAK IN PROGRESS
- 56 = SHUTDOWN WARNING SENT
- 55 = END-CONNECTION IN PROGRESS
- 54 = DATA RECEIVED
- 53 = INPUT ENABLED (MSG BLOCK SENT)

NETWORK ACTIVITY TABLE

VNAT - ONE BIT FOR EACH NETWORK TERMINAL

WORD LOCATION = (TERM. NUMBER - 1ST NETWORK TERM. NO.)/32

BIT LOCATION = (TERM. NUMBER - 1ST NETWORK TERM. NO.) MOD 32



IAF

AUXILIARY - PP ACTION FOR IAF

ITA CALLED WITH LIST OF REQUESTS IN POTs OR SINGLE REQUEST

<u>FUNCTION</u>	<u>DESCRIPTION</u>
1	ADJUST IAF FL
2	RETURN TERMINAL JOB
3	CREATE ROLLOUT FILE
4	LOGOUT TERMINAL
5	DISPLAY ACCOUNTING MESSAGE
6	TERMINAL RECOVERY
7	INCREMENT RESOURCE LIMIT (TL, SRU)
10	RECOVERY FILE PROCESSOR
11	SCHEDULE JOBS
12	GATHER STATISTICS
13	CLEAN UP SALVARE

IAF

AUXILIARY - TTY INPUT/OUTPUT

1TO DOES TERMINAL INPUT/OUTPUT THAT REQUIRES MASS STORAGE REQUESTS

RECOVERY FILE - SALVARE

- BUILT AT INITIALIZATION TIME
- TWO WORDS FOR EACH DEFINED TERMINAL

F O	E Q	FT	HH MM SS	UI
--------	--------	----	----------	----

IA		TO
----	--	----

FO = FAMILY ORDINAL
EQ = ROLLOUT FILE EQUIPMENT
FT = ROLLOUT FILE FIRST TRACK
HHMMSS = LAST ENTRY TIME
UI = USER INDEX
IA = INSTALLATION AREA
TO = TERMINAL TABLE ORDINAL

- ENTRIES CLEARED AFTER 10 MINUTES
- IN RECOVERY, BOI + EOI OF USER'S FILES ARE VALIDATED IF SENSE SWITCH SET.

QUESTION SET LESSON 24

1. What routines make up the time-sharing subsystem?
2. How is the dynamic memory associated with POTS managed?
3. Explain in general the time-sharing origin job flow for each of the following:
 - a. Job initiation
 - b. Terminal input
 - c. Terminal output
4. Where is all the information about any active terminal kept?
5. What is a multi-terminal job?
6. How do the terminals get processed as the time-sharing executive progresses around its main loop?
7. How does the time-sharing executive make requests for its auxiliary PP routines? What happens if no PPs are available?
8. Why does the time-sharing executive queue a group of request for the auxiliary routine 1TA?
9. Why are all time-sharing jobs scheduled to the rollout queue instead of the input queue?
10. What happens when a time-sharing origin job step aborts? What happens when the user logs off?
11. What function does the auxiliary routine 1T0 perform?

LESSON 25
REMOTE BATCH SUBSYSTEM

LESSON PREVIEW:

This lesson introduces the student to the remote batch entry subsystem, Export/Import 200 or EI200, as it is more commonly called. EI200 has been succeeded by the Remote Batch Facility (RBF) Networks Products offering.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Identify the components of the EI200 subsystem and detail their major functions.
- Map the allocation of EI200's control point field length and the port table.
- Detail the job flow through the subsystem from the submittal of the job to the disposition of job output.
- Describe the services performed for the subsystem by the auxiliary PP routine XSP.

REFERENCES:

NOS IMS - Chapter 33

EI200
EXPORT/IMPORT

REMOTE BATCH ENTRY

RJE - REMOTE JOB ENTRY

- MODE 4A 200 UT PROTOCOL
- 2000 2400 4800 (9600) BAUD LINE SPEEDS
- UP TO 16 TERMINALS 6671
2550-100
- BCD CHARACTER SET (63 CHARACTER SET)

E200CP - CPU PROGRAM
FETS AND BUFFERS IN UPPER FL

1LS - AUXILIARY (TRANSIENT PP)
USES "RPL" OVERLAYS FROM E200CP

1ED - DRIVER (DEDICATED PP)

XSP - AUXILIARY (TRANSIENT PP)

COMSEXP - CONSTANTS, POINTERS, TABLE AREA DEFINITIONS

EI200
MEMORY LAYOUT

POINTERS	
FUNCTION STATUS TABLE	TFS
MESSAGE BUFFER AREA	MSGB
LOGIN TABLE	LINF
CPU INTERLOCK TABLE	CPIK
DROP JOB TABLE	DPJT
JOB STATISTICS TABLE	JST
FAMILY NAME TABLE	FAMT
USER NUMBER TABLE	UNJC
QAC PARAMETER BLOCK	QAPB
QAC PARAMETER BLOCK	QAPC
E200CP MAIN LOOP/SUBROUTINES	
LOCAL OVERLAY LIBRARY (MINI RPL)	
<p>ALLOCATED</p> <p>FETS</p> <p>AND</p> <p>BUFFERS</p>	

PORT TABLE LAYOUT

59	47	35	23	17	11	0	
function LED to ILS	terminal number	mux eq. number					TFS
CP I/O status	I/O drive	input FET address	output FET address				status word
messages to/from remote terminal							MSGB
user number					0		LINF
hashed job name		user index			status		LINF+1
			input active	output active			CPIK
internal system job name				reply			DPJT
hh	mm		no. inputs processed	no. output processed			JST
family name							FAMT
user number							UNJC
job card name							
nine-word parameter block							QAPB
input FET							
output FET							

EXPORT/IMPORT FETs

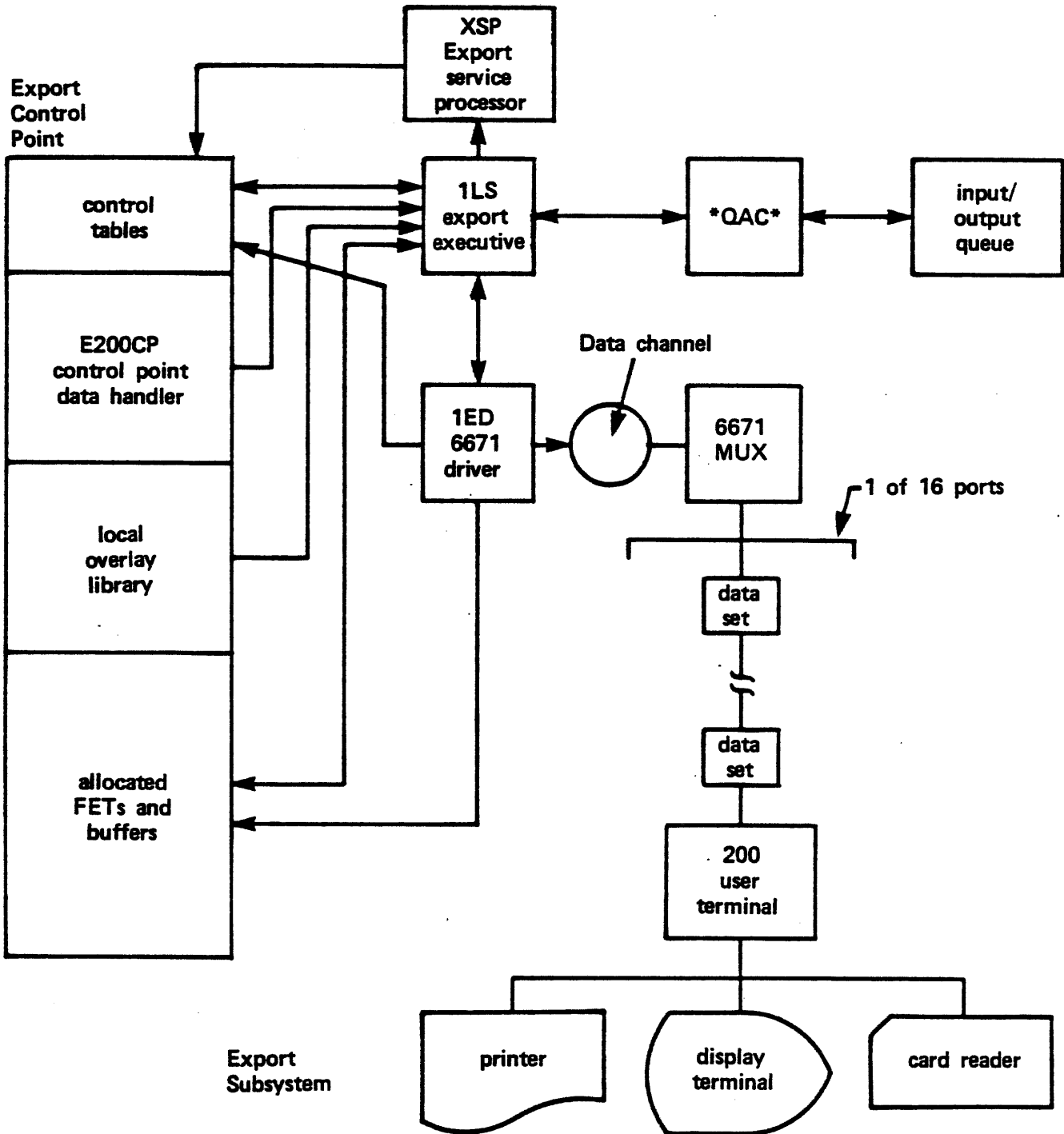
INPUT FET

FET+0	internal system name			code/status
1				FIRST
2				IN
3				OUT
4	FNT address	0		LIMIT
5	full/empty driver flag	job card processing in progress	address of line following EOR	address of line following EOF
6	job sequence number		0	pointer to next allocated FET
7	job priority	job time limit	job FL 0	card count

OUTPUT FET

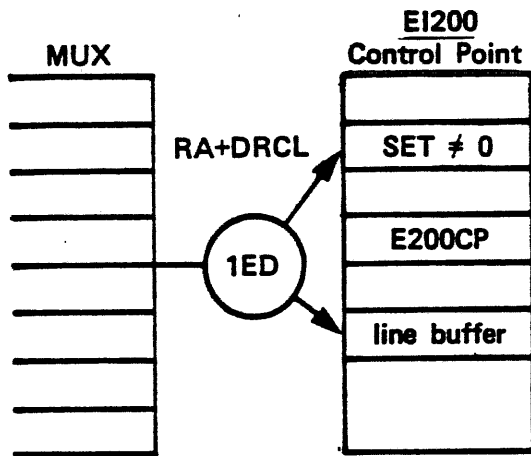
FET+0	internal system name			code/status
1			01	FIRST
2	0			IN
3	0			OUT
4	FNT address	dayfile first track	dayfile first sector 0	LIMIT
5	full/empty driver flag	0		
6	job sequence number		0	pointer to next allocated FET
7	print line count			

TAF ENVIRONMENT

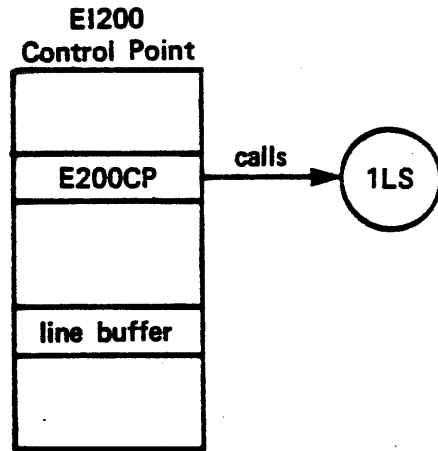


EI200

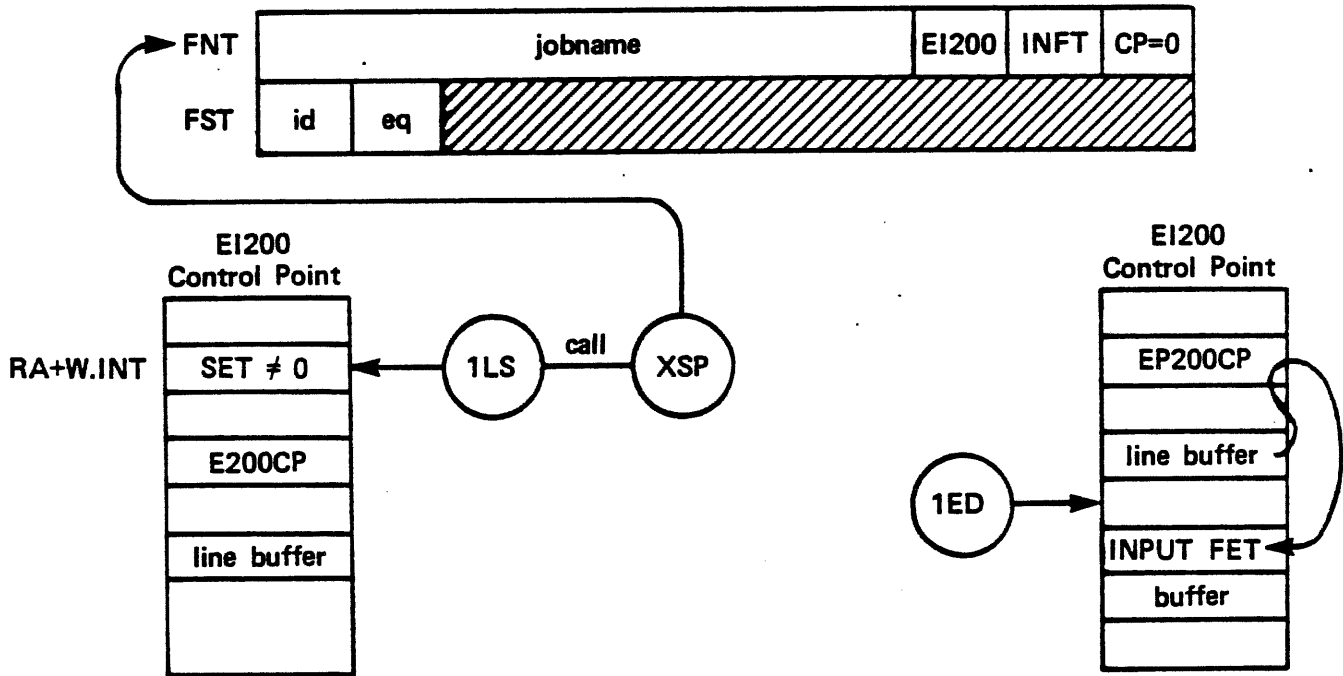
1. 1ED READS DATA FROM MUX TO LINE BUFFER (IN E200CP FL) AND RECALLS E200CP.
2. E200CP BEGINS AND CALLS 1LS AND GOES BACK INTO RECALL.
3. 1LS GETS E200CP OUT OF RECALL INTO EXECUTION.
4. 1LS CALLS XSP TO BUILD INPUT QUEUE ENTRY FOR JOB IN THE LINE BUFFER.
5. E200CP REFORMATS THE LINE BUFFER AS 1ED PASSES IT AND MOVES THE DATA TO THE TERMINAL'S INPUT BUFFER. E200CP CALLS CIO TO EMPTY THE BUFFER. THIS CONTINUES UNTIL ENTIRE JOB DECK HAS BEEN READ (EOI SENSED).
6. RUN THE JOB. OUTPUT AVAILABLE IN OUTPUT QUEUE.
7. 1LS FINDS OUTPUT QUEUE ENTRY WITH TERMINAL ID (TID) MATCHING ONE OF THE ACTIVE PORTS. CALLS OBP TO BUILD BANNER PAGE. TELLS E200CP THAT OUTPUT IS READY.
8. E200CP READS OUTPUT FILE TO TERMINAL'S OUTPUT BUFFER.
9. E200CP FORMATS DATA FROM OUTPUT BUFFER INTO LINE BUFFER AND TELLS 1ED.
10. 1ED SENDS DATA FROM LINE BUFFER TO RJE TERMINAL.
11. E200CP FILLS BUFFER (VIA CIO) AND PASSES FORMATTED LINES TO 1ED UNTIL EOI IS REACHED.
12. E200CP GOES INTO AUTO RECALL AND 1ED KEEPS ROLLING MUX LOOPING FOR INPUT.



1ED reads from multiplexer to line buffer and sets RA+DRCL words to nonzero. This takes E200CP out of autorecall.



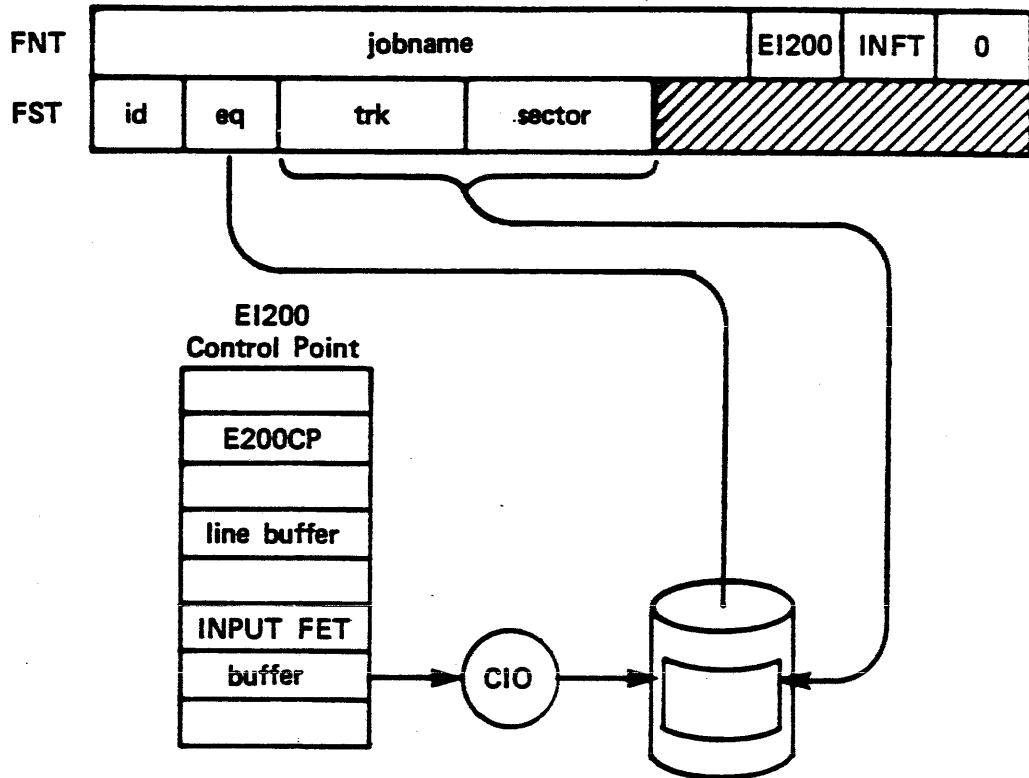
E200CP calls 1LS and goes into autorecall.



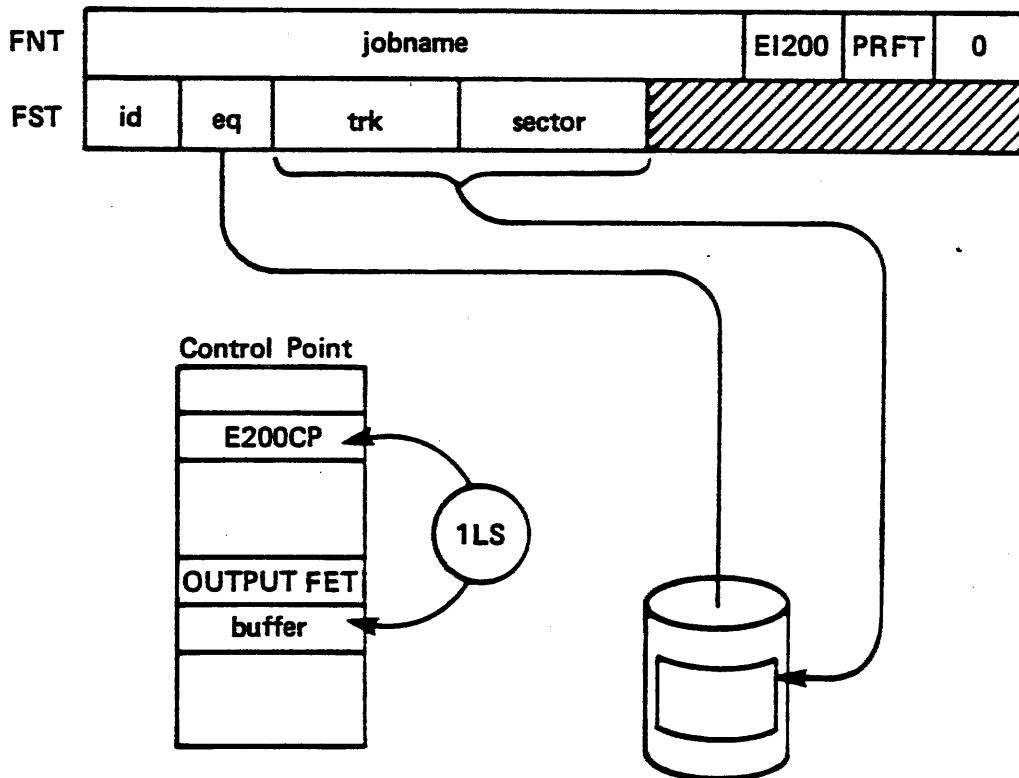
1LS sets RA+W.INT to nonzero, which takes E200CP out of autorecall. 1LS calls XSP to create an FNT/FST input queue entry for the job in the line buffer, using OBF and OVJ to crack the job card.

E200CP reformats the line buffer data as 1ED passes it and moves the data to the input FET buffer.

E/I OPERATION (Continued)

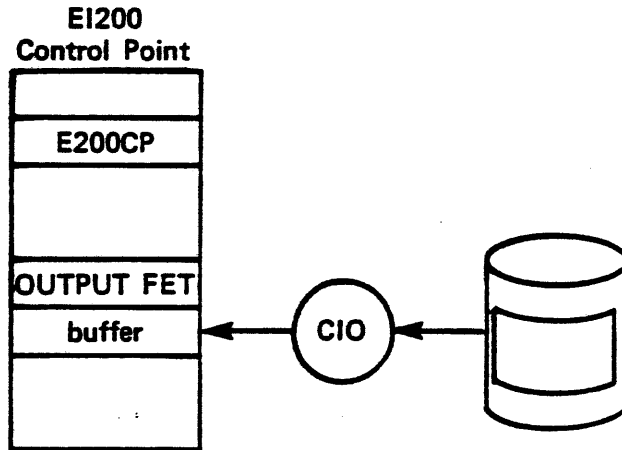


E200CP calls CIO to write the data from the input FET buffer to the disk.



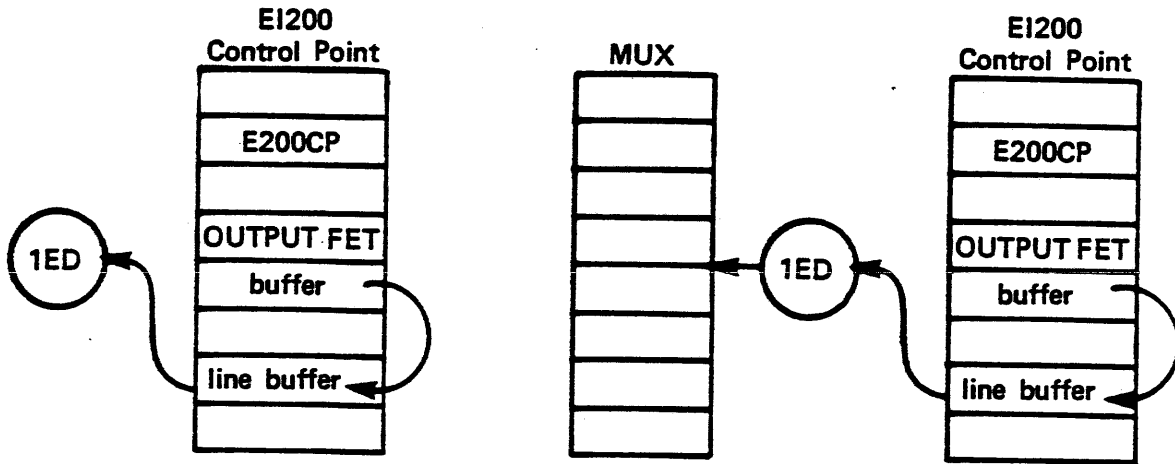
1LS finds an output queue entry and calls OBP to create a banner page in the output FET buffer and informs E200CP.

E/I OPERATION (Continued)



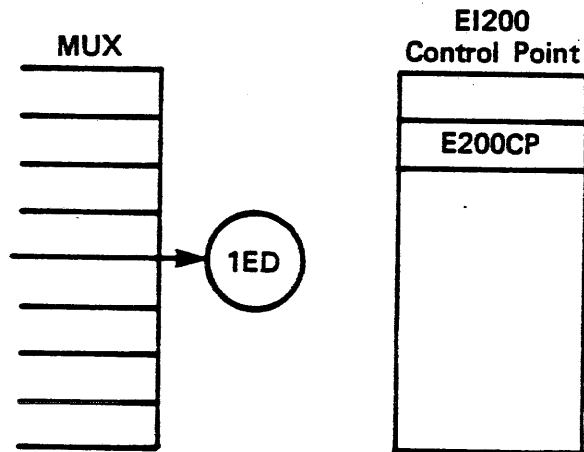
E200CP reads the output file via CIO into the output FET buffer.

E/I OPERATION (Continued)



E200CP formats the output FET buffer for the remote printer and informs 1ED.

1ED sends the line buffer data, one line at a time, to the remote printer.



E200CP goes into autorecall and 1ED continues to poll the multiplexer.

XSP

1. VALIDATES TERMINAL'S USER NUMBER DURING LOGIN OF TERMINAL

2. MAKE JOB ENTRY (USER JOB SUBMITTAL)

- OVJ - JOB CARD CRACKER
 - JOB CARD
 - USER CARD
- JOB SEQUENCE NUMBER (RJSM)
- BUILDS FNT/FST INPUT ENTRY
- BUILDS SYSTEM SECTOR - WITH DESTINATION FAMILY, USER NUMBER, USER INDEX OF TERMINAL. THESE ARE USED FOR OUTPUT TID.

QUESTION SET LESSON 25

1. How is the EI200 control point's field length used?
2. What tables are associated with each terminal?
3. How does the EI200 subsystem perform mass storage I/O?
4. Trace the flow of data from the remote batch terminal to the system input queue. Trace the flow of data from the system output queue to the remote batch terminal.
5. How does EI200 determine which terminal a file in the output queue should be routed to?
6. What does the auxiliary routine XSP do for the EI200 subsystem?
7. What characteristic of the driver (1ED) enables the remote batch terminal user to suspend a file which is currently being printed?

LESSON 26
TRANSACTION SUBSYSTEM (TRANEX/TAF)

LESSON PREVIEW:

The purpose of this lesson is to introduce the student to transaction processing and the NOS subsystem dedicated to transaction processing: the Transaction Facility, TAF.

This lesson is not to be an in-depth study of TAF, but to give the student an overview of TAF and its capabilities.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

- Define a "transaction".
- List data base managers that interface with TAF.
- Define a "task".
- List the capabilities of TAF.

REFERENCES:

NOS IMS - Chapter 16.

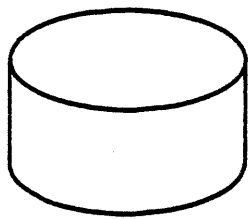
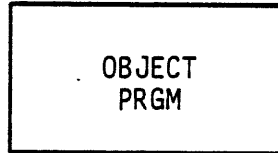
ON LINE
TRANSACTION



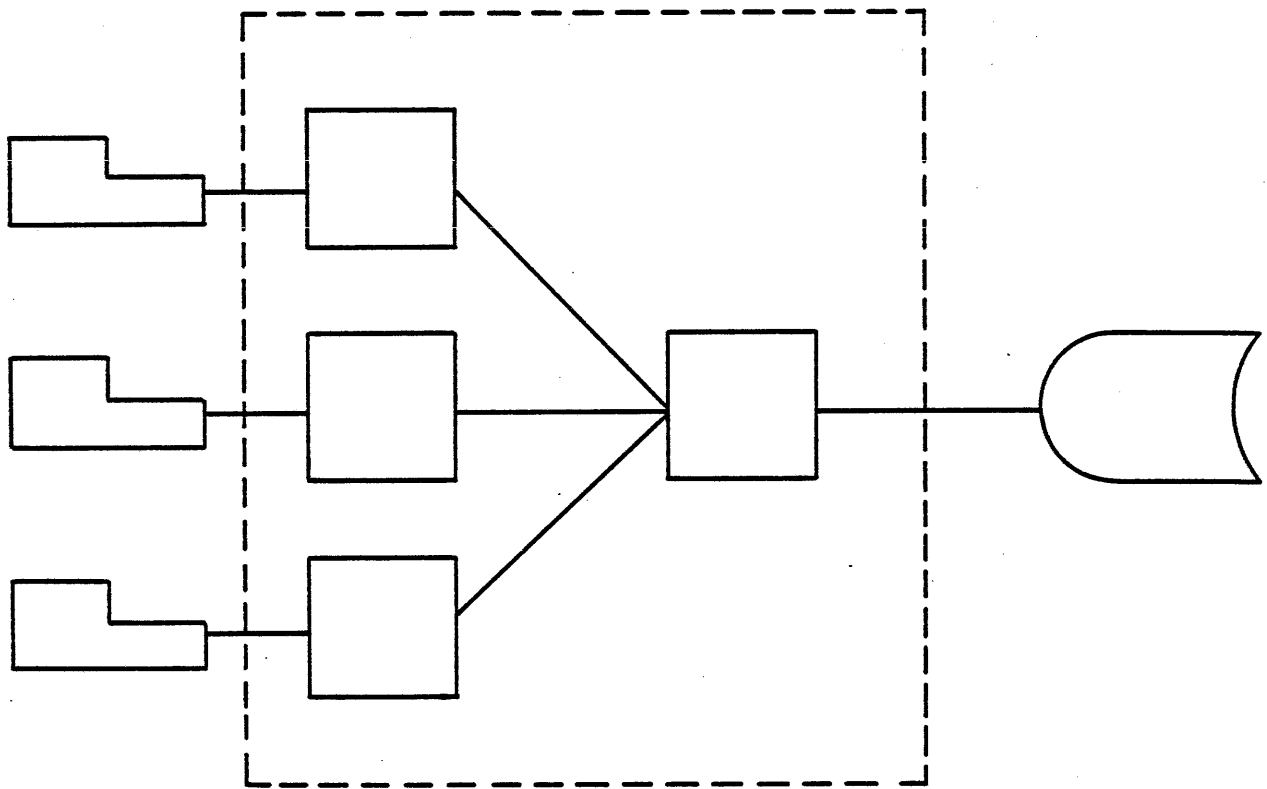
DATA:
STRUCTURED:
OFT REPEATED:
NON VARYING



OBJECT
PRGM



Conceptual requirement for a transaction system.



Multiple terminals

One data base

TRANSACTION SYSTEM

I. Characteristics

Multiple Terminals

One Data Base

Repetitive Input with few variations

II. Types

Inquiry/Update

Mostly Inquiry

Mostly Update

Inventory Control

Credit Validation

Consumer Load

Reservation Systems

Stock Quotation

Data Collection

Brokerage Systems

III. Implementation

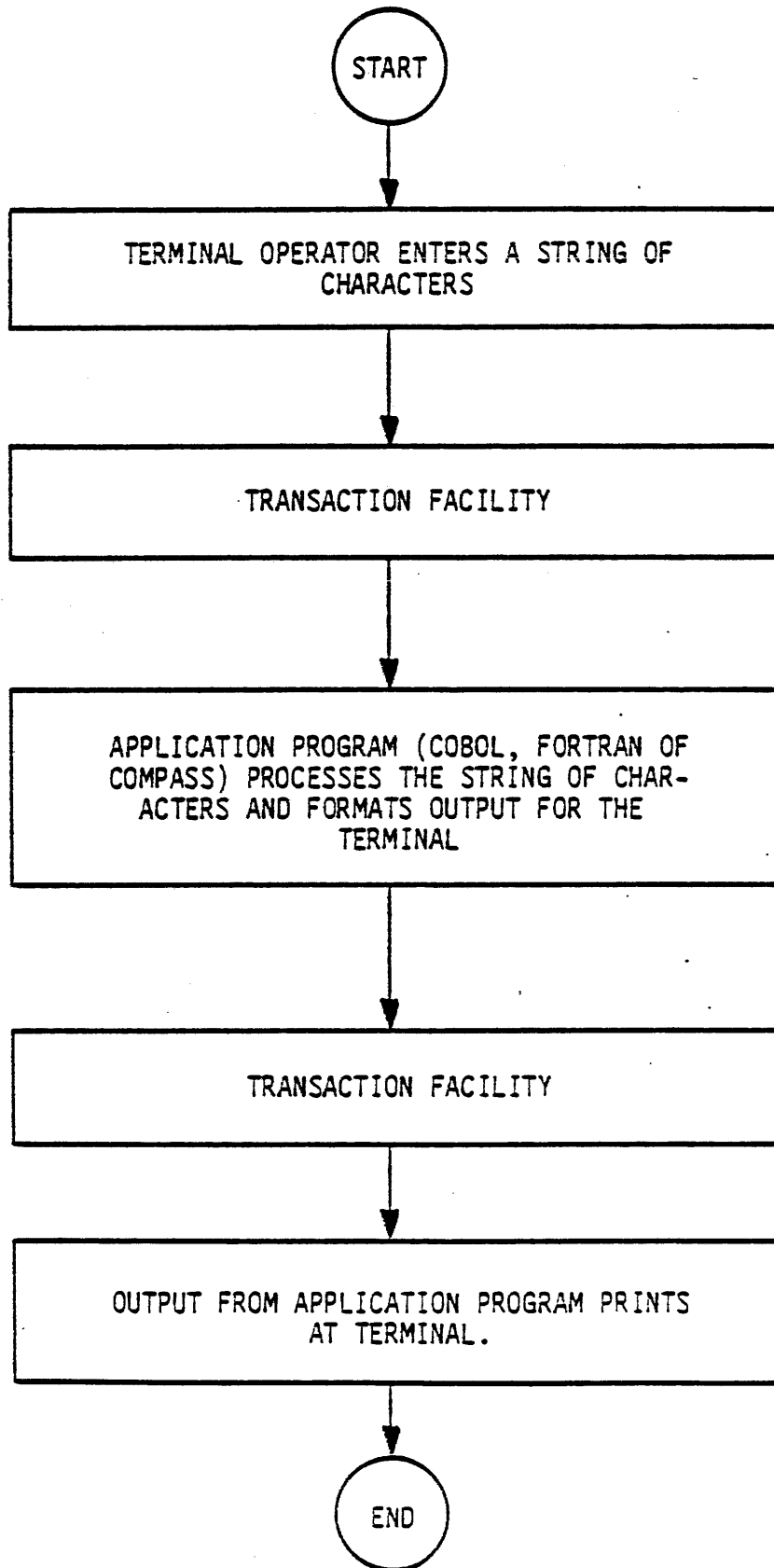
Dedicated transaction processing systems

Add transaction processing to an existing batch/time sharing system

TAF

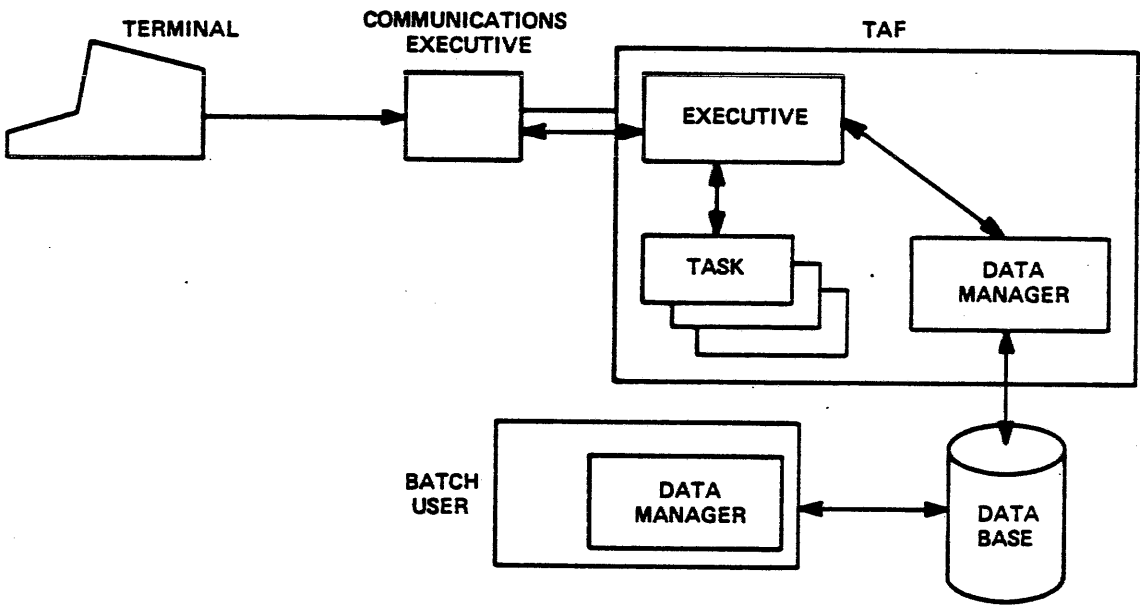
- Looks like one job to the operating system
- Allows up to 31 subcontrol points
- Allows multiple data bases (multiple users)
- Validates data base accesses on a terminal basis
- Uses a separate task library for each data base
- Schedules tasks
- Contains and controls execution of the data manager(s)
- Regulates its field length

A TRANSACTION

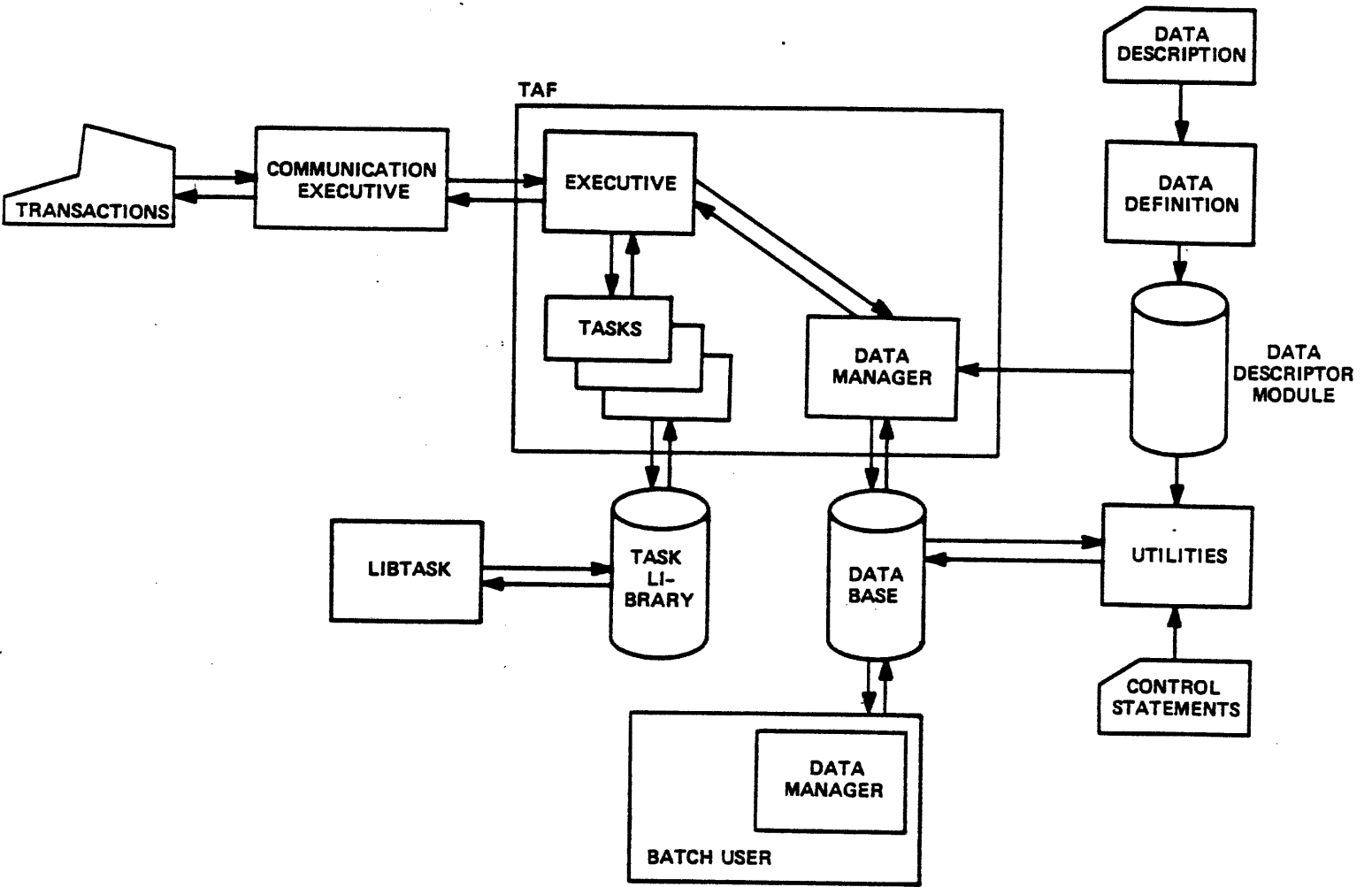


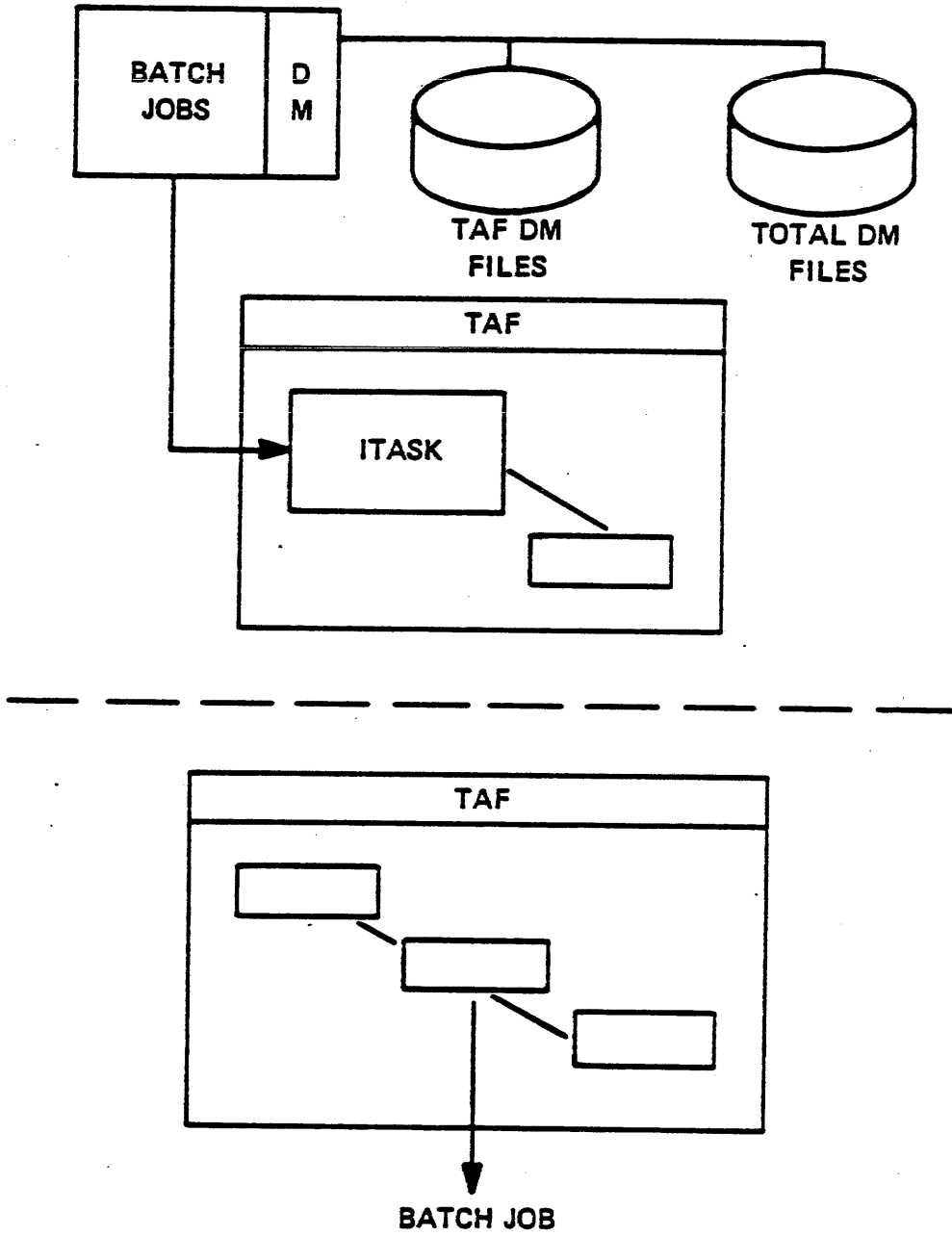
FIVE COMPONENTS OF THE NOS TRANSACTION FACILITY

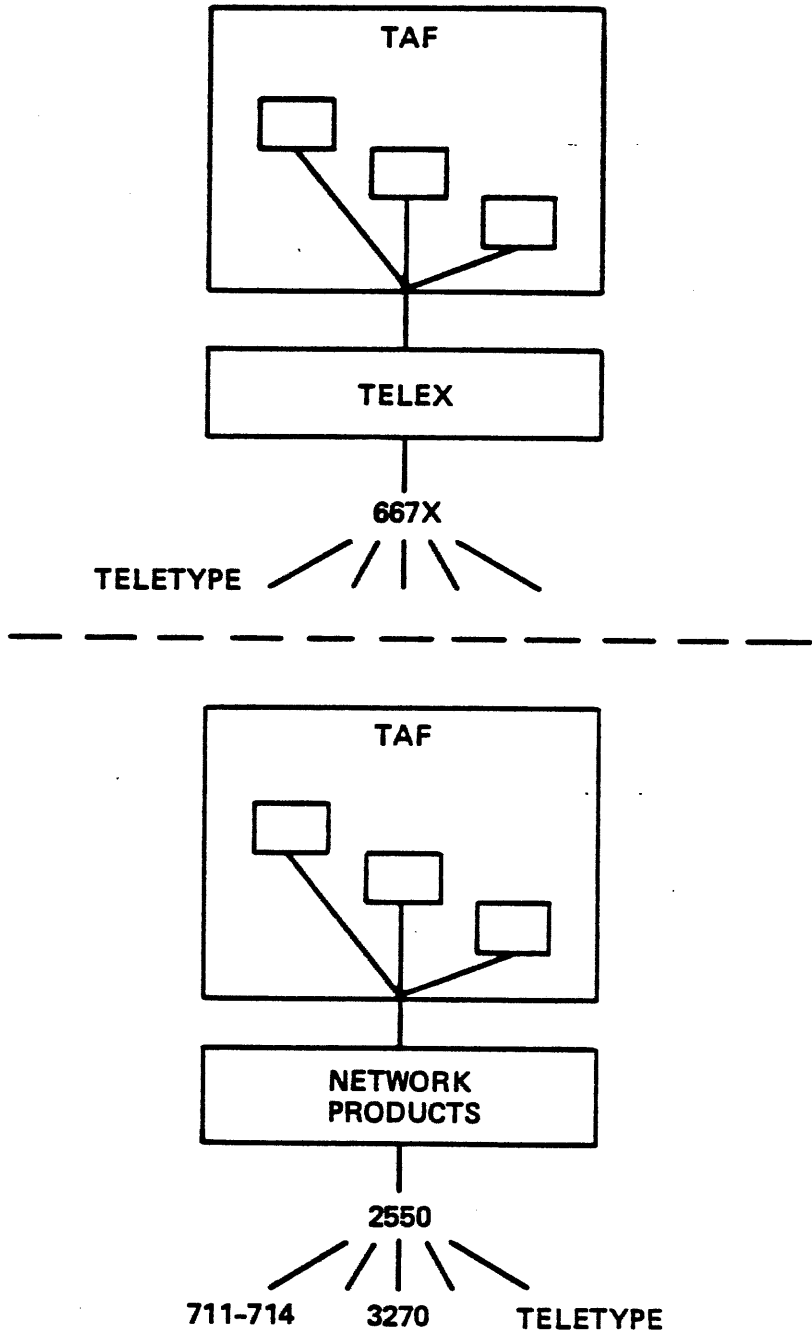
- I. NAM or T/S - The NOS communications executive program that controls terminal input/output.
- II. TAF - The NOS transaction executive program that coordinates and controls the execution of user application programs and the data manager(s).
- III. Data Manager - When operating as a subset of TAF, processes all data manager requests issued by user application programs. In this manner it can provide record level interlocks that allow concurrently-executing programs to access the same file (but not the same record within the file).
- IV. User Tasks - Programs written in COBOL or FORTRAN that process transaction terminal input.
- V. Utility Programs - Auxiliary operating system programs used for the creation and maintenance of data bases and task libraries.



TAF ENVIRONMENT



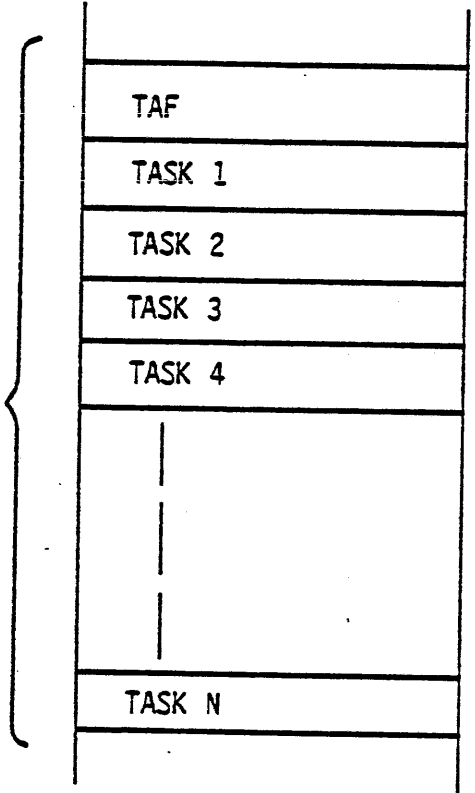


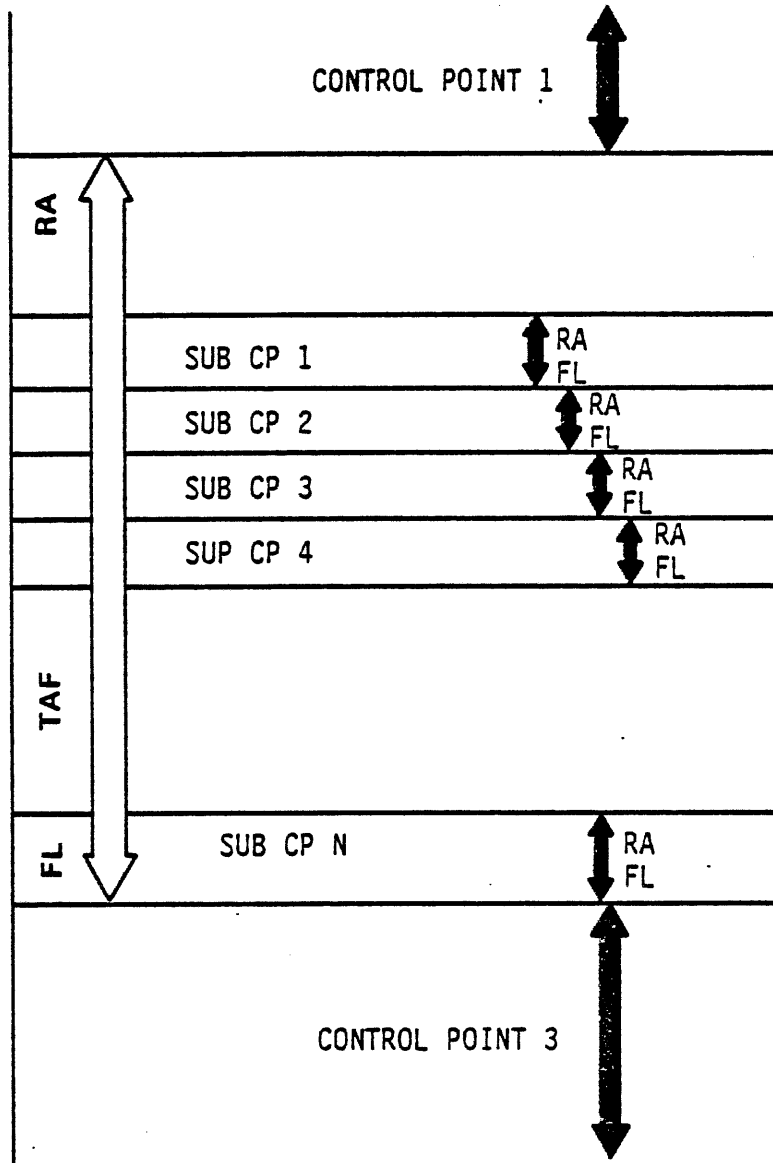


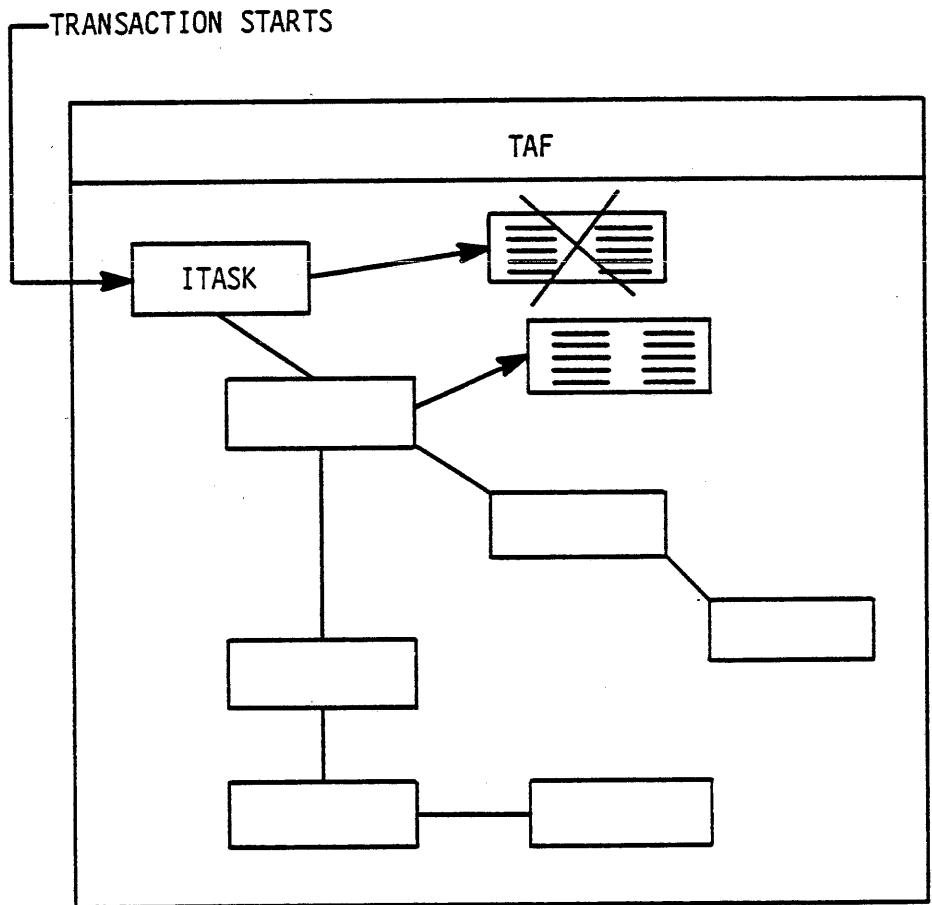
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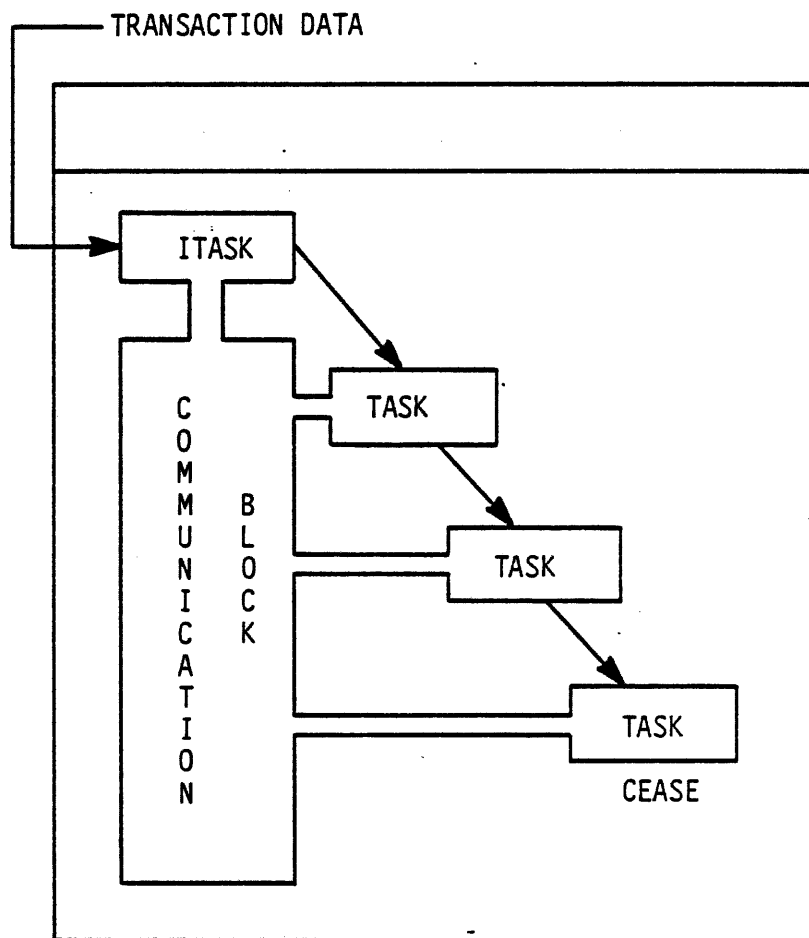
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QUESTION SET LESSON 26

1. How does an end user (at a terminal) view transaction processing?
2. What is a "transaction"?
3. What is a "task" and how does it relate to a transaction?
4. What are the five components of TAF?
5. Can a data base be accessed from both a batch job and a terminal under TAF?
6. Why use a transaction executive?

LESSON 27
MULTIMAINFRAME

LESSON PREVIEW:

This lesson presents the NOS Multimainframe package: the support theory and how NOS shares permanent files using ECS as a link device.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be able to:

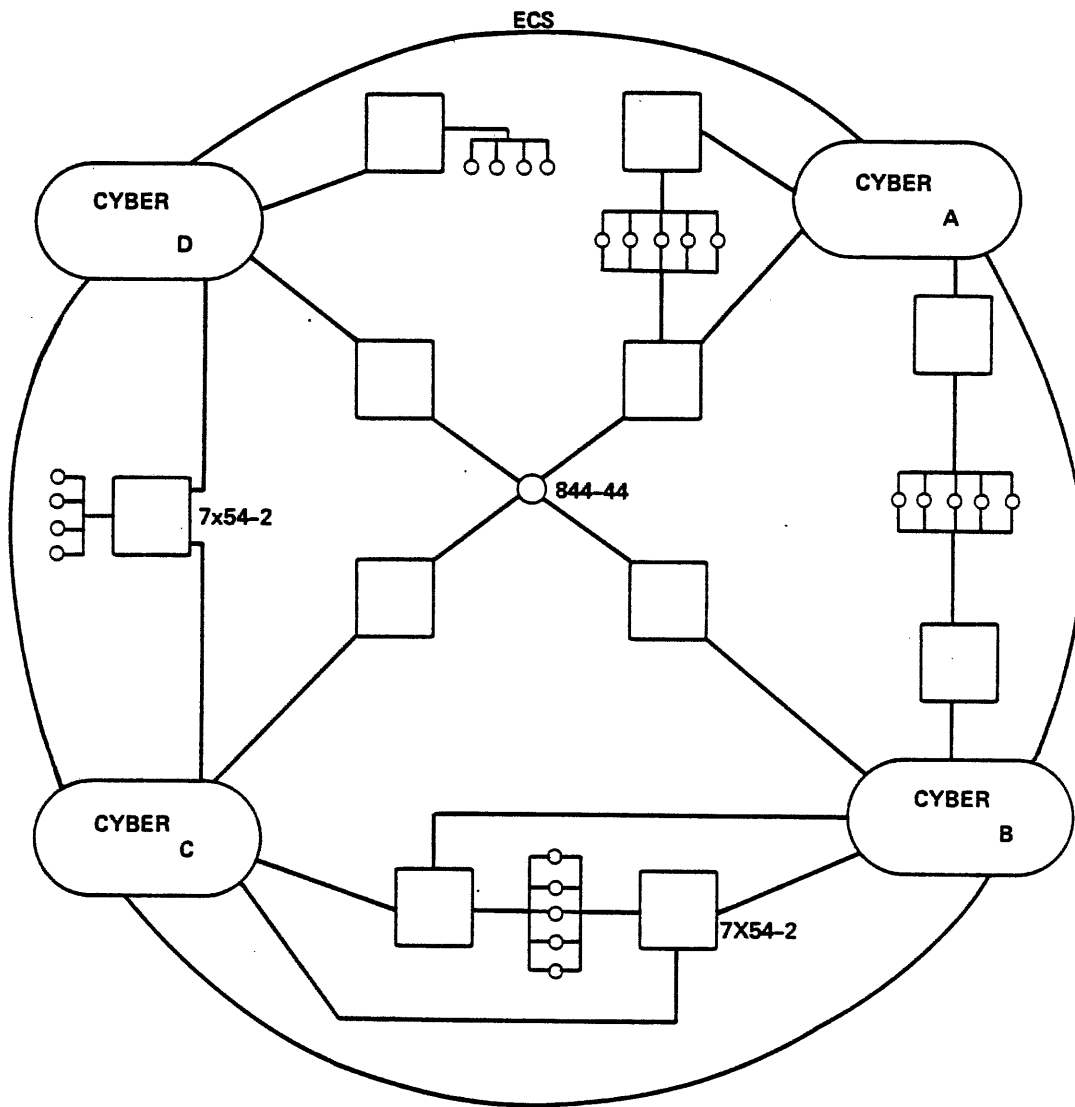
- Configure a MMF shared permanent file system.
- Discuss how the mass storage tables (MST/TRT/MRT) are accessed and updated in a MMF complex.
- Discuss the processing of a down machine, including its removal from and re-introduction into the MMF complex.
- Discuss the usage of ECS as the MMF link device.

REFERENCES:

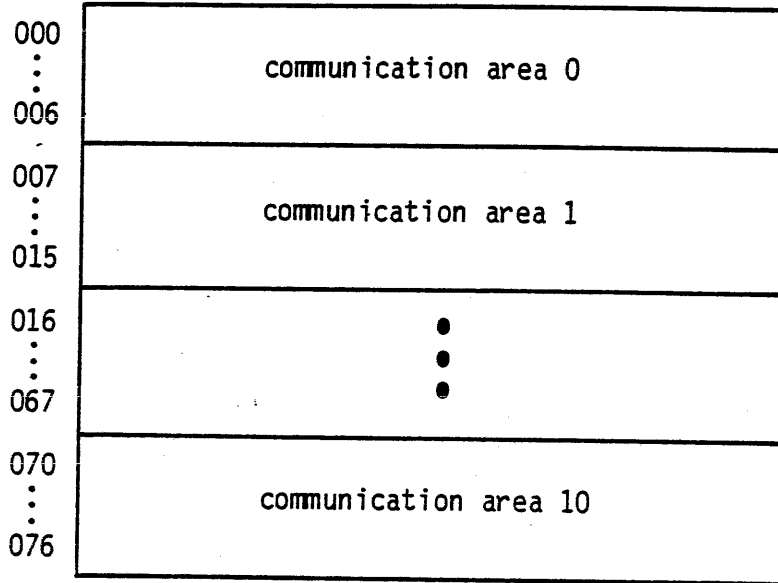
NOS IMS, Chapter 21 NOS SMRM, 8

MULTI-MAINFRAME

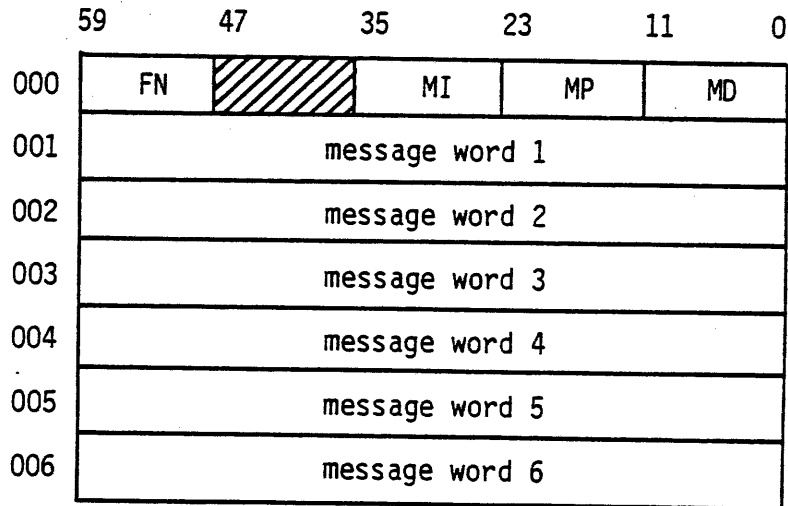
- SHARED PERMANENT FILES
- 2 TO 4 MAINFRAMES
- ECS AS LINK



MULTIMAINFRAME TABLES
INTERMACHINE COMMUNICATION AREA



Each communication area has the following format.



FN Intermachine function number.
MI Machine initiating request.
MP Machines to process request.
MD Machines done processing request.

MMF ENVIRONMENT TABLES

Sector 16g of the ECS label track is defined as follows:

	59	47	11	0
000	MMFL for mainframe 1			
001	MMFL for mainframe 2			
002	MMFL for mainframe 3			
003	MMFL for mainframe 4			
004	multimainframe 1 system time			
005	multimainframe 2 system time			
006	multimainframe 3 system time			
007	multimainframe 4 system time			
010	next DAT track			DAT count
011				FAT count
012	One word per flag register bit. Each			
.	word contains the MMFL word of the			
.	machine which currently has the corre-			
.	sponding flag register interlock.			
033				
034	machine 1 requests			
035	machine 2 requests			
036	machine 3 requests			
037	machine 4 requests			
040	machine 1 requests			
041	machine 2 requests			
042	machine 3 requests			
043	machine 4 requests			
044				
.				
.				
067				
070				
.				
.				
077	installation area			

MMF - DAT TRACK CHAIN (ECS)

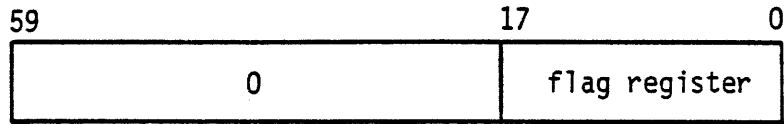
Track N

0000 : 0777 1000	device access table (DAT)
	fast attach table (FAT)

Track M (same format for each device)

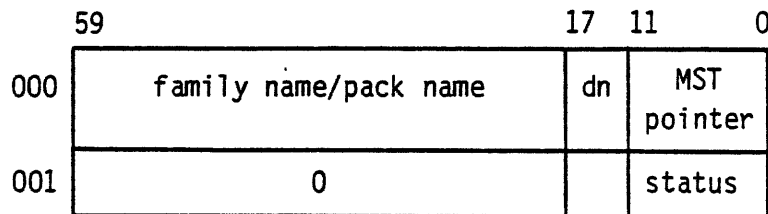
0000 : 0011 0012 : 0017 0020 : 0025 0026 : 0033 0034 : 0041 0042 : 0077 0100 : 1077 1100 : 1177 1200 : 1277 1300 : 1377 1400 : 1477	MST for shared device (global area) local area for machine index 1 local area for machine index 2 local area for machine index 3 local area for machine index 4 unused TRT for device MRT1 (machine recovery table) MRT2 MRT3 MRT4
---	--

MMF - ECS FLAG REGISTER FORMAT



<u>Bit Set</u>	<u>Name</u>	<u>Description</u>
17-12	---	Reserved.
11	COMI	CPUMTR intermachine communication request present.
10	CIRI	CPUMTR interlock recovery.
9	FATI, PFNI	FAT and PFNL interlock.
8	IFRI	Intermachine function request interlock.
7	BTRI	Block transfer in progress.
6	PRSI	Deadstart ECS preset in progress.
5	DATI	Device access table interlock.
4	TRTI	TRT interlock; machine. Specified by bits 3-0 is requesting a TRT interlock.
3-0	---	Machine mask indicating which machine has TRT interlock bit set.

DEVICE ACCESS TABLE (DAT) ENTRY



dn Device number.
MST pointer If zero, device is not shared.
status Bits 11-5 are reserved, bit 4 is set if recovery is in progress, and bits 3-0 are machine mask of machines accessing device.

FAST ATTACH TABLE (FAT) ENTRY - GLOBAL

	59	47	35	23	17	11	0
000	fast attach file name						
001		first trk	RM	RA	R		
002	mach.1 ID		RM	RA	R		
003	mach.2 ID		RM	RA	R		
004	mach.3 ID		RM	RA	R		
005	mach.4 ID		RM	RA	R		
006	family name				dn		
007	0						

RM READMD users.
 RA READAP users.
 R Read/write users.
 dn Device number.

PFNL ENTRY FORMAT - GLOBAL

000	0
001	PFNL (global)
002	PFNL for mainframe 1
003	PFNL for mainframe 2
004	PFNL for mainframe 3
005	PFNL for mainframe 4
006	0
007	0

The first entry of the FAT is an 8-word entry of PFNL words in the preceding format.

ECS

FLAG REGISTER INTERLOCKS

TRTI SECURED WHENEVER UPDATING MST OR TRT IN ECS.
 MACHINE MASK BIT IS ALSO SET FOR THE MACHINE.

PRSI SECURED WHEN UPDATING MACHINE ID WORDS IN ENVIRONMENT
 TABLE. OCCURS FOR ALL LEVELS OF DEADSTART.

BTRI SECURED WHEN MACHINE WANTS TO PERFORM A BLOCK
 TRANSFER VIA ECS STORAGE MOVE AREA.

IFRI SECURED BY CPUMTR WHEN ENTERING AN INTERMACHINE
 FUNCTION.

FATI/PFNI SECURED BY CPUMTR OR MREC TO UPDATE PFNL WORDS OR
 TO UPDATE EXISTING FAST ATTACH ENTRIES.

DATI SECURED BY ANY PROGRAM THAT IS SEARCHING, ADDING
 ENTRIES TO OR DELETING ENTRIES FROM THE FAT OR
 THE DAT, OR BY ANY PROGRAM ALTERING THE DAET OR
 FAET ENTRIES.

CIRI SECURED BY CPUMTR WHEN CLEANING UP FLAG REGISTER
 INTERLOCKS FOR A DOWN MACHINE.

COMI SECURED BY CPUMTR WHEN COMMUNICATION PROCESSING IS
 REQUESTED OF OTHER MACHINES.

ECS FLAG REGISTER

COMMUNICATION REGISTER: COMPUTER TO COMPUTER COMMUNICATION WITHOUT ECS MEMORY REFERENCE.

FLAG REGISTER IS 18 BITS IN LENGTH AND PART OF THE ECS CONTROLLER.

FLAG REGISTER OPERATIONS ARE ECS RE/WE WITH BIT 23 OF ECS ADDRESS SET=1. BITS 22-21 OF ECS ADDRESS SPECIFY THE FLAG REGISTER OPERATION.

BITS 17-0 OF ECS ADDRESS IS THE FLAG WORD. BITS ARE CLEARED/ ENTERED IN THE FLAG REGISTER FROM THE FLAG WORD DEPENDING ON THE FUNCTION.

- BIT BY BIT COMPARISON OF FLAG REGISTER AND FLAG WORD. IF BITS SET IN THE WORD ARE CLEAR IN THE REGISTER, THEN ALL THE BITS SET IN THE FLAG WORD ARE SET IN THE FLAG REGISTER. IF NOT ALL BITS ARE CLEAR IN THE FLAG REGISTER FOR BITS SET IN THE FLAG WORD, THE ERROR HALF-EXIT IS TAKEN.

(R) = 010	(R) = 010
(W) = 101	(W) = 111
(A) = 111	ABORT

ECS FLAG REGISTER

1 BITS IN THE FLAG WORD ARE SET IN THE FLAG REGISTER

(R) = 010
(W) = 100
(A) = 110

2 BIT BY BIT COMPARISON OF FLAG REGISTER AND FLAG WORD. IF ALL BITS IN THE FLAG REGISTER ARE CLEAR FOR BITS SET IN THE FLAG WORD, THEN THE FUNCTION HAS COMPLETED NORMALLY. OTHERWISE, THE ERROR HALF-EXIT IS TAKEN. THIS IS THE SAME LOGIC AS FUNCTION 0 EXCEPT NO DATA IS CHANGED IN THE FLAG REGISTER.

(R) = 010	(R) = 010
(W) = 101	(W) = 111
EXECUTE NEXT WORD	ABORT
(A) = 010	(A) = 010

3 BITS IN THE FLAG WORD ARE CLEARED IN THE FLAG REGISTER.

(R) = 110
(W) = 101
(A) = 010

MRT

THE MACHINE RECOVER TABLE (MRT) WORKS HAND IN HAND WITH THE TRACK RESERVATION TABLE (TRT) TO INDICATE THE LOCAL OR SHARED STATUS OF THE TRACKS ON A MASS STORAGE DEVICE.

<u>TRT</u>	<u>MRT</u>	
.0	0	TRACK NOT INTERLOCKED OR IT IS LOCAL TO ANOTHER MF
0	1	FIRST TRACK OF A FILE LOCAL TO THIS MAINFRAME
1	0	TRACK INTERLOCKED BY ANOTHER MAINFRAME
1	1	TRACK INTERLOCKED BY THIS MAINFRAME

THE MRT IS USED TO:

1. CLEAR INTERLOCKS ON PRESERVED FILES THAT ARE HELD BY A DOWN MACHINE.
1. CLEAN UP LOCAL FILE USAGE BY A DOWN MACHINE UNDER MREC CONTROL.

MRT/MST/TRT UPDATING

CPUMTR UPDATES LOCAL MACHINE COPIES OF THE TRT AND MST FROM ECS AND UPDATES THE ECS COPIES OF THE TRT, MST AND MRT WHEN PROCESSING MONITOR FUNCTIONS DLKM, DTKM, RTCM AND MOST SUBFUNCTIONS OF STBM.

EACH MACHINE HAS A LOCAL COPY OF THE MRT AS WELL AS AN ECS COPY. AS THE MRT NEEDS TO BE UPDATED, ONLY THE WORD CONTAINING THE BIT TO BE CHANGED IS WRITTEN TO ECS.

EACH MACHINE HAS A LOCAL COPY OF THE TRT. IF THE MACHINE WAS NOT THE LAST UPDATER OF THE TRT, THE TRT IS READ FROM ECS. WHEN UPDATING THE TRT, THE TRT WORDS FROM THE LOCAL TRT ARE WRITTEN TO ECS. THE AMOUNT WRITTEN IS FROM THE FIRST TRT WORD ALTERED TO THE LAST ALTERED WORD. THE SDGL WORD IN THE MST ECS COPY IS UPDATED TO INDICATE THE LAST UPDATER OF THE TRT.

FOR THE MOST PART, SYSTEM ROUTINES DO NOT KNOW THAT THE MACHINE IS PART OF AN MMF COMPLEX. THEY ISSUE MONITOR FUNCTIONS AND CPUMTR DOES THE REQUIRED OPERATION.

MRT/MST/TRT UPDATING

READING TRT

1. DETERMINE IF DEVICE IS SHARED (IF SO, THERE WILL BE AN ECS ADDRESS IN MST WORD SDGL).
2. OBTAIN TRTI FLAG REGISTER INTERLOCK.
3. READ GLOBAL MST (FIRST THREE WORDS) ONLY FIRST THREE GLOBAL WORDS ARE NECESSARY; REST OF GLOBAL AREA IS ONLY USED TO IDENTIFY THE DEVICE-LABEL RECOVERY.
4. MST/TRT IS INTERLOCKED THROUGH SDGL. IF ANOTHER MACHINE'S MASK IS PRESENT, THE TRTI INTERLOCK IS RELEASED AND THE MONITOR FUNCTION REJECTED.

IF THIS MACHINE HAD LAST ACCESSED THE MST/TRT (THIS INFORMATION IS ALSO IN SDGL) THERE IS NO NEED TO REREAD THE TRT NOW. OTHERWISE, THE TRT AND MST ARE READ FROM ECS, THEN MOVED TO THE LOCAL TRT/MST AREA.

THE FIRST THREE GLOBAL MST WORDS ARE WRITTEN TO ECS, THUS INTERLOCKING THE TRT/MST FOR THIS MACHINE.

5. THE TRTI INTERLOCK IS NOW RELEASED.

MRT/TRT/MST UPDATING

RTCM

1. READ TRT AND INTERLOCK IT VIA SDGL IN MST.
2. FIND AVAILABLE TRACK. IF FIRST TRACK, SET MRT BIT (LOCAL AND ECS) FOR THIS TRACK.
3. RESERVE DESIRED NUMBER OF TRACKS IN LOCAL TRT. THE TRT WORD ADDRESSES FOR THE FIRST AND LAST TRACKS RESERVED ARE SAVED.
4. UPDATE THE ECS COPY OF THE TRT BY DOING A BLOCK WRITE FROM THE FIRST TRT WORD USED TO THE LAST TRT WORD USED.
5. CLEAR INTERLOCK IN SDGL BY REWRITING THE THREE GLOBAL MST WORDS.

MRT/TRT/MST UPDATING

DLKM/DTKM

1. READ TRT AND INTERLOCK IT VIA SDGL.
2. PERFORM OPERATION ON LOCAL TRT. THE TRT WORD ADDRESSES FOR THE "FIRST" AND "LAST" TRACKS RESERVED ARE SAVED.
3. IF ENTIRE TRACK CHAIN IS BEING RELEASED, THE MRT BIT (LOCAL AND ECS) IS CLEARED.
4. UPDATE ECS COPY OF THE TRT BY DOING A BLOCK WRITE FROM THE "LOWEST" TRT WORD USED TO THE "HIGHEST" WORD USED.
5. CLEAR INTERLOCK IN SDGL BY REWRITING THE THREE GLOBAL MST WORDS.

MRT/TRT/MST UPDATING

STBM

STBM HAS A VARIETY OF FUNCTIONS THAT UPDATE TRT AND MST FIELDS.

THE LOGIC FOLLOWED FOR TRT FUNCTIONS IS THE SAME AS FOR RTCM/DLKM/DTKM EXCEPT THAT ONLY ONE TRT WORD IS BEING UPDATED.

THE STBM SUBFUNCTIONS STIS/CTIS (SET/CLEAR TRACK INTERLOCK) AND SPFS/CPFS (SET/CLEAR PRESERVED FILE STATUS) WILL CAUSE THE MRT BIT (LOCAL AND ECS) TO BE SET/CLEARED FOR THE TRACK.

IAUM

CPUMTR FUNCTION IAUM PERFORMS A VARIETY OF FUNCTIONS WITH PERMANENT FILE CONTROLS, IN PARTICULAR, FAST ATTACH FILES AND THE PFNL WORD.

IN THE MULTIMAINFRAME ENVIRONMENT, IAUM WORKS ON THE FAT (FAST ATTACH TABLE) TRACK IN ECS.

IAUM WILL

1. OBTAIN FATI INTERLOCK IN ECS FLAG REGISTER
2. READ ENTRY (8 WORDS) FROM FAT. (RECALL THAT THE FIRST ENTRY ON THE FAT IS THE GLOBAL PFNL ENTRY)
3. UPDATE THE ENTRY AND WRITE IT BACK INTO ECS
4. RELEASE FATI INTERLOCK

MMF DEADSTART

THE PRESENCE OF A LINK DEVICE IS THE "SYSTEM FLAG" THAT INDICATES THAT A MACHINE IS TO BE PART OF AN MMF COMPLEX.

THE FOLLOWING CMRDECK ENTRIES ARE RELATED TO MMF PROCESSING:

LINK=EQ.	DEFINES EQ AS THE LINK DEVICE; EQ IS ECS EST ORDINAL.
SHARE=EQ ₁ ,EQ ₂ ,...EQ _N .	DEFINES EQ _I TO BE SHARED BY OTHER MACHINES IN THE MMF COMPLEX.
PRESET,N.	REQUESTS THAT ECS TABLE SPACE BE ALLOCATED FOR N SHARED DEVICES.

AFTER PROCESSING THE CMRDECK, SET ALLOCATES/RECOVERS SPACE FOR THE TRT/MST/MRT FOR MASS STORAGE DEVICES.

FOR LEVEL 0, 1, 2 RECOVERY, THE MST IS INITIALIZED. FOR LEVEL 3 RECOVERY, ONLY INTERLOCKS (SDGL, PF UTILITY, DISK DRIVER) ARE CLEARED.

MMF DEADSTART

SET PASSES THE MULTIMAINFRAME AND RECOVERY INFORMATION TO STL. SOME OF THIS INFORMATION IS PASSED IN MMFL AND ERFL.

MID	NS	LD			MIN	MMFL
-----	----	----	--	--	-----	------

	RS	PI			ELT	ERFL
--	----	----	--	--	-----	------

- MID = MACHINE ID (USES CM MMFL IF LEVEL 3)
- MIN = MACHINE INDEX
- NS = NUMBER OF SHARED DEVICES
- LD = LINK DEVICE (FROM CM MMFL IF LEVEL 3)
- RS = RECOVERY LEVEL
- P = PRESET
- I = INITIALIZE
- ELT = ECS LABEL TRACK (FROM ALGL LEVEL 3)

STL LOADS AND STARTS UP CPUMTR.

CPUMTR PROCESSES THE LINK DEVICE DEPENDING ON PRESET AND INITIALIZE STATUS AND RECOVERY LEVEL.

MMF DEADSTART

CPUMTR
PRESET MACHINE

CLEARs ECS FLAG REGISTER

SETS PRESET BIT IN FLAG REGISTER .PRSI

IF NOT INITIALIZING, VERIFIES LINK DEVICE LABEL TRACK.

CLEARs COMMUNICATION AND ENVIRONMENT SECTORS IN ECS LABEL TRACK

SETS MMFL AS FIRST ENTRY. IN MFET

SETS INTERNAL MMF CLOCKS FROM STET

CLEARs PRESET BIT FROM FLAG REGISTER

MACHINE RECOVERY TABLE (MRT) ADDRESS SET BASED ON MACHINE INDEX

MMF DEADSTART

CPUMTR
NON-PRESET MACHINE

SETS PRESET BIT IN ECS FLAG REGISTER .PRSI

VERIFIES LINK DEVICE LABEL TRACK

IF LEVEL 3 RECOVERY, MMFL MUST AGREE WITH ENTRY IN MFET.
IF SO, INTERNAL CLOCKS ARE RESET FROM STET AND FLAG
REGISTER PRESET BIT CLEARED. ALL MMF INTERLOCKS PREVIOUSLY
HELD BY THIS MACHINE ARE CLEARED AS FOLLOWS:

- .CIRI INTERLOCK IS OBTAINED
- ALL FLAG REGISTER BITS HELD BY THIS MACHINE
ARE CLEARED
- .FATI INTERLOCK IS OBTAINED
- THE PFNL FOR THIS MACHINE IS CLEARED AND GLOBAL
PFNL IS ADJUSTED
- .FATI INTERLOCK IS CLEARED
- ALL DEVICE INTERLOCKS FOR SHARED DEVICES ARE CLEARED
(SDGL)
- LOCAL PF UTILITY ACTIVITY (ACGL) AND DEVICE INTERLOCKS
(SDGL) ARE CLEARED FOR ALL MASS STORAGE DEVICES
- .CIRI INTERLOCK IS CLEARED

MMF DEADSTART

IF NOT A LEVEL 3 RECOVERY, THE MFET IS CHECKED TO DETERMINE IF THE MACHINE IS ALREADY IN THE MMF COMPLEX.

IF A MATCH OCCURS BETWEEN THE MACHINE'S MMFL AND AN ENTRY IN THE MFET AND THE DEADSTART IS A LEVEL 0, THE DIAGNOSTIC

"MID CURRENTLY ACTIVE"

IS DISPLAYED, THE .PRSI INTERLOCK RELEASED AND DEADSTART ABORTED.

IF THE MATCH OCCURRED AND THE DEADSTART IS A LEVEL 1 OR 2, THERE MUST BE A LINK EQUIPMENT DEFINED. IF SO, THE MMFL IS RESET IN MFET, THE INTERNAL CLOCKS RESET FROM STET AND THE .PRSI INTERLOCK RELEASED. IF NO LINK DEVICE IS PRESENT, THE DIAGNOSTIC:

"MID UNDEFINED IN ECS"

IS DISPLAYED, THE .PRSI INTERLOCK RELEASED AND DEADSTART ABORTED.

MMF DEADSTART

IF THE MATCH DID NOT OCCUR AND THE DEADSTART IS A LEVEL 0,
IF AN EMPTY ENTRY WAS FOUND IN MFET, THE MMFL IS SET INTO
MFET, THE INTERNAL CLOCKS RESET FROM STET, THE .PRSI
INTERLOCK RELEASED. IF NO ENTRY WAS FOUND, THE DIAGNOSTIC

"MAXIMUM NUMBER OF MIDS ACTIVE"

IS DISPLAYED, THE .PRSI INTERLOCK RELEASED AND DEADSTART
ABORTED.

IF THE MATCH DID NOT OCCUR AND THE DEADSTART IS A LEVEL 1
OR 2, THE DIAGNOSTIC

"MID UNDEFINED IN ECS"

IS DISPLAYED, THE .PRSI INTERLOCK RELEASED AND DEADSTART
ABORTED.

OTHER DIAGNOSTICS THAT MAY BE ISSUED:

"ECS LABEL TRACK NOT FOUND"

VERIFICATION OF LABEL TRACK FAILED, THE .PRSI INTERLOCK IS
RELEASED AND DEADSTART ABORTED.

"ECS READ/WRITE PARITY ERRORS"

ERRORS OCCURRED WHEN READING OR WRITING ECS MMF TABLES. THE
.PRSI INTERLOCK IS RELEASED AND DEADSTART ABORTED.

MMF DEADSTART

WHEN CPUMTR COMPLETES, STL STARTS UP RMS. RMS RECEIVES DEADSTART INFORMATION FROM STL IN ITS INPUT REGISTER.

RMS	CP	LD	PI	EC	RS
-----	----	----	----	----	----

CP = CONTROL POINT NUMBER

LD = LINK DEVICE EST ORDINAL

P = PRESET

I = INITIALIZE

EC = CPUMTR LINK DEVICE INITIALIZATION ERROR CODE

RS = RECOVERY LEVEL

MMF DEADSTART

RMS OBTAINS THE DATI INTERLOCK IN THE FLAG REGISTER IF LEVEL 0, 1 OR 2 RECOVERY.

IT THEN RECOVERS THE LINK DEVICE. IF NOT BEING PRESET, THE DAT IS READ FROM ECS. IF A PRESET IS BEING DONE, OMF IS CALLED.

OMF INITIALIZES THE DAT TRACK.

RMS THEN READS THE LABELS FOR ALL MASS STORAGE DEVICES. THIS IDENTIFIES WHAT DEVICES EXIST ON THE SYSTEM. LABEL READING CONSISTS PRIMARILY OF READING THE MST TO A CENTRAL MEMORY AREA.

RMS (LEVEL 0, 1, 2) THEN RECOVERS THE MASS STORAGE DEVICES. THE ACTION TAKEN BEGINS WITH CHECKING THE DAT FOR DEVICES AND WHETHER THEY WERE LAST ACCESSED BY THIS MACHINE. IF A DEVICE WAS FOUND ACCESSED BY ANOTHER MACHINE, ITS MST IS READ FROM ECS TO THE CM AREA. THE DAT ENTRY FOR THE DEVICE IS UPDATED BASED ON THIS MACHINE'S ACCESS TO IT AND RECOVERY LEVEL. THE DAT INDEX IS SET IN THE MST MDGL WORD.

MMF DEADSTART

RMS THEN PROCESSES THE TRT. IF A DEVICE IS SHARED, AND HAS A TRT IN ECS, IT WILL BE READ FROM ECS TO THE TRT AREA IN CENTRAL MEMORY RECOVERY AREA. OTHERWISE, THE TRT IS READ FROM THE DEVICE'S LABEL TRACK.

THE TRT IS THEN EDITED (LEVEL 0) UNLESS IT IS A PREVIOUSLY ACCESSED SHARED DEVICE. THE EDITING REMOVES NON-PRESERVED TRACK LINKAGES WHILE COPYING THE TRT FROM THE RECOVERY AREA TO THE ACTUAL TRT RESIDENCE.

FOR NON-LEVEL 0 DEADSTARTS, THE TRT IS SIMPLY COPIED FROM THE RECOVERY AREA TO THE ACTUAL TRT RESIDENCE, UNLESS IT IS A PREVIOUSLY ACCESSED SHARED DEVICE.

THE MST IS THEN WRITTEN TO ITS RESIDENCE FROM THE RECOVERY AREA.

THE TRACK COUNT IS ADJUSTED, UNLESS IT IS A PREVIOUSLY ACCESSED SHARED DEVICE.

THE DAT IMAGE IS THEN WRITTEN BACK TO ECS FROM THE RECOVERY AREA, UNLESS THIS IS A LEVEL 3 RECOVERY.

MMF DEADSTART

RMS NOW UPDATES THE ECS TABLES. IF THE DEVICE HAD NOT BEEN PREVIOUSLY ACCESSED BUT IS SHARED, THE MST/TRT IS WRITTEN TO ECS AND THE MRTs ARE CLEARED.

IF THE DEVICE WAS A SHARED DEVICE PREVIOUSLY ACCESSED (BY THIS MACHINE), THEN THE MRT IS EDITED AND LOCAL TRACK INTERLOCKS ARE CLEARED. IF THIS IS A LEVEL 0 DEADSTART, THE TRACK CHAINS FOR NON-PRESERVED FILES ARE RELEASED.

THE MRT IS THEN WRITTEN TO ECS.

IF THE DEADSTART IS A LEVEL 1 OR 2, THE DATI FLAG REGISTER INTERLOCK IS RELEASED. LEVEL 0 DEADSTART DATI WILL BE RELEASED LATER AND THE DATI INTERLOCK WAS NOT OBTAINED FOR A LEVEL 3 RECOVERY.

IF ANY DEVICES WERE RECOVERED AND THIS IS A LEVEL 0, 1 OR 2 DEADSTART, THE PERMANENT FILE SUBSYSTEM IS VALIDATED. THIS MEANS THAT THERE CAN BE NO DUPLICATES IN DEVICE NUMBERS WITHIN A FAMILY OR DUPLICATE AUXILIARY PACKS MOUNTED.

REC IS THEN LOADED INTO THIS PPU AND CONTROL GIVEN TO IT.

MASS STORAGE DEVICE RECOVERY

	STAND ALONE	SHARED - NOT IN DAT	SHARED - IN DAT	
LEVEL 0	2,4,6,7,8,14	1,4,6,7,8,9,10,14	3,11	NOT PREVIOUSLY ACCESSED
	N/A	N/A	11,12,13	PREVIOUSLY ACCESSED
1 & 2	2,4,7	1,4,5,7,9	3,11	NOT PREVIOUSLY ACCESSED
	4,7	N/A	11,13	PREVIOUSLY ACCESSED
3	ERROR	ERROR	ERROR	NOT PREVIOUSLY ACCESSED
	4,7	N/A	11,13	PREVIOUSLY ACCESSED

MASS STORAGE DEVICE RECOVERY

1. DATA ENTRY NOT FOUND. MAKE DAT ENTRY INDICATING THIS MACHINE ONLY ACCESSOR.
2. DAT ENTRY NOT FOUND. MAKE DAT ENTRY INDICATING THIS MACHINE IS ACCESSING BUT NO ECS POINTER IN MST (NOT SHARED).
3. ADD INDICATION THAT THIS MACHINE IS ACCESSING TO EXISTING DAT ENTRY.
4. RETRIEVE MST FROM LABEL AND PRESET INTO ECS. RETRIEVE TRT FROM LABEL.
5. SET MRTs FROM DEVICE INTO ECS.
6. EDIT TRT.
7. CLEAR TRACK INTERLOCKS FOR ALL MACHINES.
8. CLEAN UP SYSTEM SECTOR FOR ALL MACHINES.
9. SET TRT INTO ECS.
10. CLEAR MRTs FOR ALL MACHINES.
11. RETRIEVE TRT/MST FROM ECS. GET LOCAL MST FROM LABEL AND CLEAN IT UP.
12. PROCESS MRT DROPPING LOCAL TRACKS.
13. PROCESS MRT CLEARING LOCAL TRACK INTERLOCKS.
14. BUILD IQFT.

MMF DEADSTART

REC RECOVERS REMNANTS OF THE PREVIOUS SYSTEM OPERATION FROM THE SYSTEM TABLE TRACK. THE SYSTEM TABLE TRACK WAS BUILT AS PART OF A SYSTEM CHECKPOINT OPERATION BY ICK.

FOR LEVEL 1 AND 2 RECOVERIES, THE EST AND FNT ARE RESTORED FROM THE SYSTEM TABLE TRACK. FOR LEVEL 2 RECOVERY, THE EST ENTRIES BUILT BY RMS ARE USED FOR MASS STORAGE EQUIPMENTS INSTEAD OF THOSE FROM THE SYSTEM TABLE. UNTIL THIS TIME, ALL RECOVERY OPERATIONS HAVE TAKEN PLACE USING INFORMATION FROM THE CMRDECK. ANY CHANGES IN THE CMRDECK FROM THE INITIAL LEVEL 0 MUST BE REFLECTED IN THE RECOVERY DEADSTART CMRDECK, OTHERWISE THE RECOVERY MAY NOT BE SUCCESSFUL.

FOR LEVEL 1 RECOVERY, THE DAYFILE POINTERS AND BUFFERS ARE RE-ESTABLISHED FROM THE SYSTEM TABLE.

FOR LEVEL 1 AND 3 RECOVERY, THE LIBRARY TABLES ARE RESTORED FROM THE SYSTEM TABLE. THIS IS THE RE-SETTING OF DIRECTORY TABLES (PLD, CLD, LBD) AND CENTRAL RESIDENT ROUTINES (RPL, RCL). UNTIL THIS TIME, THE ROUTINE USED IN RECOVERY CAME FROM THE TAPE DEADSTARTED.

MMF DEADSTART

REC THEN PROCESSES CONTROL POINTS AND THE FNT; FILES ARE DROPPED OR RE-QUEUED AS NEEDED. CONTROL POINTS ARE RE-INITIALIZED.

THE SYSTEM DAYFILE, ERRLOG AND ACCOUNT FILES ARE RECOVERED/INITIALIZED WITH THE TIME AND TYPE OF DEADSTART.

AT THIS TIME THE "RECOVERY COMPLETE" MESSAGE IS MADE AVAILABLE AND DSD INFORMED OF THIS FACT.

FOR LEVEL 0 AND 2 DEADSTARTS, REC NOW WAITS FOR THE SYSTEM TAPE TO BE LOADED AND SYSEDT TO COMPLETE ITS TABLE BUILDING.

ONCE THE TAPE HAS BEEN LOADED (IF REQUIRED), REC RECOVERS PRESERVED FILE CHAINS FOR ALL AVAILABLE MASS STORAGE. IT IS AT THIS POINT IN TIME, THAT THE DATI FLAG REGISTER INTERLOCK FOR A LEVEL 0 DEADSTART IS CLEARED.

JOBS ARE RESTARTED AND SCHEDULAR CONTROL RESET.

FOR A LEVEL 0 DEADSTART, THE SYSTEM TABLE TRACK IS BUILT BY A CHECKPOINT REQUEST TO 1CK WHICH ALSO CAUSES EACH MASS STORAGE DEVICE TO BE CHECKPOINTED.

THE SYSTEM IS NOW FULLY OPERATIONAL.

DOWN MACHINE

CPUMTR IS CALLED BY MRT WITH FUNCTION ARMF TO ADVANCE RUNNING TIME AND STATUS ECS CLOCKS.

CPUMTR WRITES THIS MACHINE'S CLOCK TO ITS PLACE IN STET. THE FLAG REGISTER IS READ AND SAVED IN EFRL.

WHEN THE ECS CLOCKS ARE STATUSED (EVERY TWO SECONDS), IF A MACHINE'S CLOCK HAS NOT CHANGED IN TWO STATUSES (FOUR SECONDS), THE MACHINE IS SAID TO BE "DOWN".

IF A MACHINE IS DOWN, THE CIRI INTERLOCK IS OBTAINED (RELEASING THE DOWN MACHINE'S CIRI INTERLOCK IF HELD).

ALL FLAG REGISTER INTERLOCKS HELD BY THE DOWN MACHINE ARE RELEASED. FRET INDICATES WHICH MACHINE SET WHICH INTERLOCK, SO CPUMTR KNOWS WHO HAS WHAT INTERLOCK BY READING FRET FROM ECS.

CPUMTR THEN READS THE GLOBAL MST FOR EACH SHARED DEVICE AND RELEASES ANY INTERLOCK THE DOWN MACHINE HAD BY CLEARING THE INTERLOCK FIELD IN SDGL AND WRITING THE GLOBAL INFORMATION BACK TO ECS.

THE CIRI INTERLOCK IS RELEASED AND THE REMAINDER OF DOWN MACHINE PROCESSING DONE IN PROGRAM MODE.

DOWN MACHINE

NOW IN PROGRAM MODE, CPUMTR "CLEANS UP" THE DOWN MACHINE'S TRT INTERLOCKS.

THE MST/TRT IS INTERLOCKED IN THE USUAL MANNER FOR EACH SHARED DEVICE (VIA SDGL) AND TRT READ FROM ECS.

THE PF UTILITY INTERLOCK IS CLEARED FROM ACGL (IF HELD BY THE DOWN MACHINE). THE GLOBAL CLEARING WILL OCCUR WHEN THE SDGL INTERLOCK IS RELEASED.

THE MRT IS READ FROM ECS IN 100₈ WORD BLOCKS. IF AN MRT BIT IS SET, THEN THE CORRESPONDING TRACK IS EXAMINED IN THE TRT. IF THE TRACK IS INTERLOCKED, THEN THE INTERLOCK BIT IS CLEARED IN THE TRT AND THE TRACK BIT IS CLEARED FROM THE MRT. THE 100₈ MRT BLOCK IS WRITTEN TO ECS AND NEXT BLOCK IS READ.

WHEN THE MRT HAS BEEN PROCESSED, THE TRT IS WRITTEN TO ECS AND THE MST/TRT SDGL INTERLOCK CLEARED.

THIS LOGIC CONTINUES UNTIL ALL SHARED DEVICES HAVE BEEN PROCESSED.

MREC

THE MAIN FUNCTION OF MREC IS TO CLEAR INTERLOCKS HELD BY AN INTERRUPTED MACHINE WHICH HAVE NOT BEEN CLEARED BY CPUMTR DURING DOWN MACHINE PROCESSING. MREC ALSO RECOVERS SPACE ON A SHARED DEVICE THAT IS NOT ACCESSIBLE BECAUSE ONE OF THE OTHER MACHINES IN THE COMPLEX IS INTERRUPTED.

MREC DISPLAYS THE STATUS OF DEVICES THIS MACHINE IS SHARING AND THE MACHINES IT IS SHARING THEM WITH.

THE OPERATOR SPECIFIES THE MACHINE ID (MID) AND DEVICES TO BE RECOVERED. THE FOLLOWING STEPS ARE PERFORMED:

- CLEAR ANY HARDWARE UNIT RESERVATIONS PREVENTING OTHER MACHINES FROM ACCESSING THE DEVICE. OPERATOR ASSISTANCE MAY BE REQUIRED.
- CLEAR DEVICE ACCESSED BIT FOR INTERRUPTED MACHINE IN THE DAT. THIS PROHIBITS A NON-LEVEL 0 RECOVERY.
- CLEARS INTERLOCKS AND USER COUNTS IN SYSTEM SECTORS FOR DOWN MACHINE.
- PROCESSES MRT TO RELEASE ALL LOCAL SPACE HELD BY DOWNED MACHINE.

MREC

MREC MAY NEED TO BE RUN ON ALL MACHINES TO COMPLETELY REMOVE DOWN MACHINE.

ONCE MREC HAS RUN ON A MACHINE,
ONLY A LEVEL 0 CAN BE DONE TO
RE-INTRODUCE THE MACHINE INTO
THE COMPLEX.

QUESTION SET LESSON 27

1. How is the Machine Recovery Table (MRT) used in conjunction with the TRT?
2. Describe the technique used to retrieve the "up-to-date" copy of the TRT for those CPUMTR operations that reference the TRT.
3. What is the difference between the machine ID, machine mask, and machine index?
4. ECS is used to link machines in the MMF complex. What tables are kept in ECS?
5. How does the system determine when a machine is down?
6. What does MREC do? After an MREC has been performed for a down machine, what must be done to re-introduce that machine into the complex?

LESSON 28
MASS STORAGE SUBSYSTEM OVERVIEW

LESSON PREVIEW:

This lesson presents an overview of Mass Storage Facility support in NOS. The objectives of this support and its hardware and software components are described. This lesson is not a detailed discussion of Mass Storage Facility, but is an overview intended to introduce the student to the terminology and concepts involved with NOS usage of this storage media.

OBJECTIVES:

Upon the successful completion of this lesson, the student should be familiar with:

- The objectives of Mass Storage Facility support in NOS.
- The hardware components of the Mass Storage Facility.
- The software components used in NOS or with NOS to support Mass Storage Facility.
- Mass Storage Facility relationship with NOS permanent files.
- Mass Storage Facility use in Multi-mainframe environments.

REFERENCES:

NOS IHB - Chapters 4, 7, 8 NOS Reference Manual, 1-2, 1-8, 2-5 NOS Operator's Guide, Chapter 3 NOS SMRM - Chapters 1, 8, 13

DISCLAIMER:

Some of the reference material may not be available until this support is officially released under NOS.

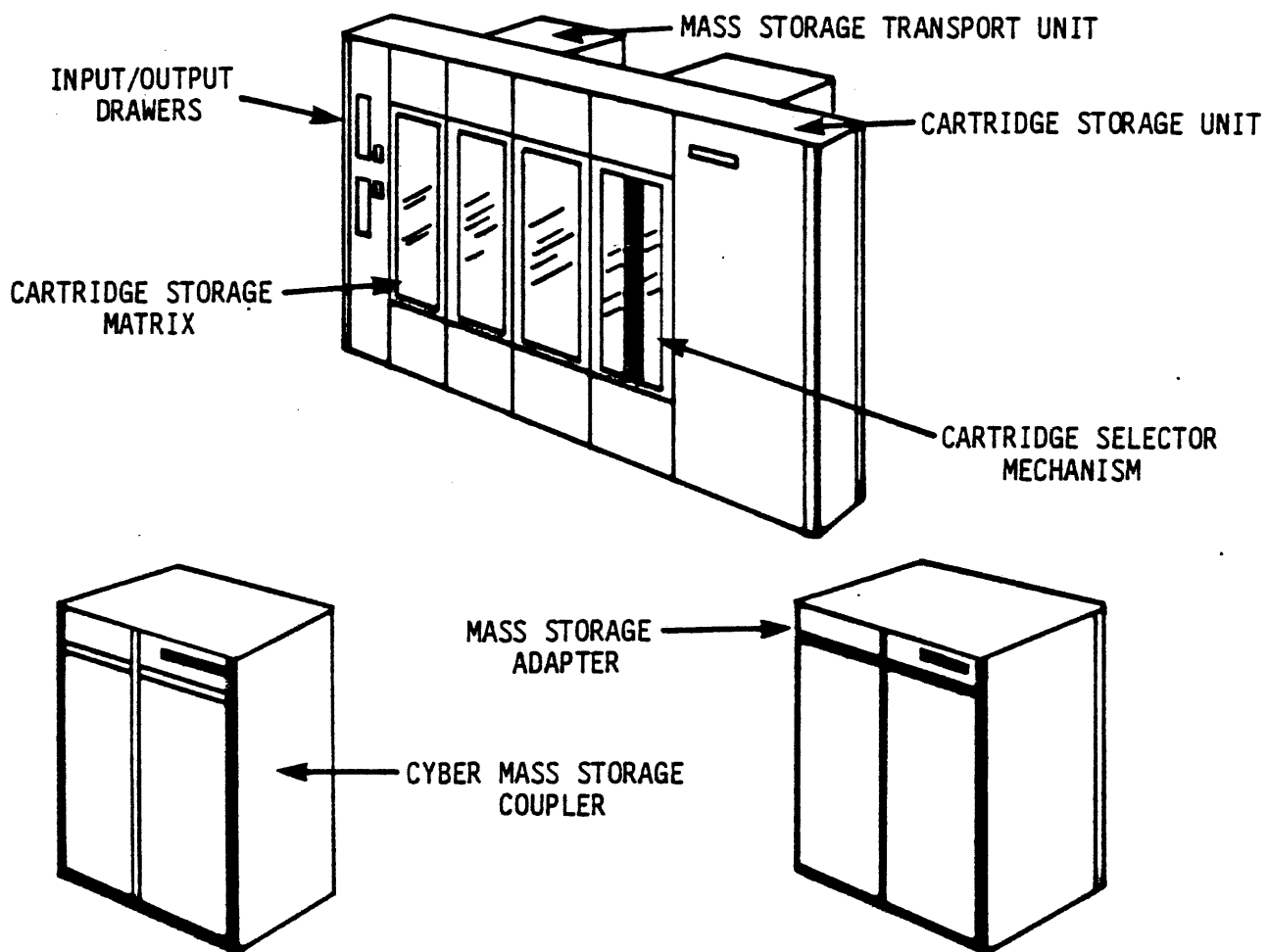
MASS STORAGE SUBSYSTEM OBJECTIVES

- REDUCE TAPE MOUNTS
- REDUCE DISK SPACE FOR INFREQUENTLY USED FILES
- PROVIDE A MULTI-LEVEL FILE SYSTEM
- SUPPORT A LARGE ON-LINE FILE BASE

BASIC MASS
STORAGE COMPONENTS.

- CYBER MASS STORAGE COUPLER
- MASS STORAGE ADAPTER
- CARTRIDGE STORAGE UNIT
- MASS STORAGE TRANSPORT
- MASS STORAGE CARTRIDGES

CONTROL DATA CYBER®
MASS STORAGE SYSTEM



CYBER MASS STORAGE COUPLER
INTERFACES 12-BIT CYBER PERIPHERAL
PROCESSOR WITH
8-BIT BYTE ORIENTED MSA

FUNCTIONS

- TWO PP ACCESSES (TWO MORE OPTIONAL)
- 4K X 24-BIT DATA BUFFER
- 12/8 CONVERSION NETWORK
- CONTROL INTERFACE THAT CONNECTS TO MSA

MASS STORAGE ADAPTER
INTERFACES CYBER COUPLER WITH MST/CSU

FUNCTIONS

- CONTROL INTERFACE THAT CONNECTS TO CMSC
- 16-BIT MICROPROCESSOR
- FLEXIBLE DISK DRIVE FOR LOADING CONTROLWARE AND DIAGNOSTICS
- READ/WRITE LOGIC
- DEVICE INTERFACE THAT ACCOMMODATES UP TO 8 DEVICES (CSU OR MST)
- A SECOND DEVICE INTERFACE MAY BE ADDED ALLOWING A MSA TO ACCESS 16 TOTAL DEVICES

MASS STORAGE TRANSPORT

EXCHANGES CARTRIDGES WITH CSU AND
TRANSFERS DATA BETWEEN TAPE AND MSA

FUNCTIONS

- 6250 GCR RECORDING
- TAPE SPEED: 129 IPS
- DATA RATE: 806 KB
- TRACK POSITIONING: 20 MS VOICE COIL
- DUAL PATH TO ALTERNATE MSA
- 5 STATION CARTRIDGE QUEUE

MASS STORAGE CARTRIDGE

CARTRIDGE CONSISTS OF A PLASTIC CASE
CONTAINING 2.7 INCH-WIDE (6.85 CM) MAGNETIC TAPE
WITH USABLE RECORDING LENGTH OF 8.3 FT. (253 CM)

DATA ORGANIZATION

- STREAM IS SMALLEST STORAGE UNIT TO WHICH A SEEK OPERATION CAN BE DIRECTED
- STREAM IS 9 BITS WIDE
- 16 STREAMS PER TAPE (144 TRACKS)
- 614,400 6-BIT CHARACTERS PER STREAM
- OVER 9.8 MILLION 6-BIT CHARACTERS PER CARTRIDGE

MASS STORAGE SUBSYSTEM CAPACITY

	DESCRIPTION	CAPACITY
CARTRIDGE	CHAR/STREAM	614,400
	STREAM/CARTRIDGE	16
	CHAR/CARTRIDGE	9.8 MILLION
CSU	CARTRIDGES/CSU	2,000
	CHAR/CSU	19.6 BILLION
	CHAR/5 CSU'S	98 BILLION
	844-21/CSU	166
	FILES/CSU (RELEASE 1.0)	32,000
	FILES/CSU (FUTURE)	LARGE
9 TRACK TAPE 2400- REEL	CARTRIDGES/TAPE	
	800 BPI	2.3
	1600 BPI	4.6
	6250 BPI	18

MASS STORAGE SOFTWARE APPROACH

- PHASED SOFTWARE DELIVERIES
- OPERATE IN MULTI-COMPUTER ENVIRONMENT
- MAKE TRANSPARENT TO APPLICATION PROGRAMS
- ELIMINATE NEED FOR MANUAL CONTROL OF DATA BASE
- PROVIDE AUTOMATIC MANAGEMENT OF DISK SPACE
- EXTENSION OF CURRENT PERM FILE SYSTEMS
- COMPATIBLE WITH CURRENT PERM FILE SYSTEMS

MASS STORAGE
SUBSYSTEM - RELEASE 1

- STAGED ACCESS
- BASIC MULTI-LEVEL FILE SYSTEM
- MULTI-COMPUTER ACCESS
- CARTRIDGE MAINTENANCE
- DISK SPACE MANAGEMENT
- BASIC MSS UTILITIES
- TAPE BACKUP
- ON-LINE DIAGNOSTICS

MASS STORAGE SUBSYSTEM
COMPONENTS

OPERATING SYSTEM ADDITIONS

- PFM MODIFICATIONS
- 16 WORD PF CATALOG
- SYSTEM TABLE CHANGES
- DSD MODIFICATIONS
- PF UTILITIES MODIFICATIONS

EXECUTIVE CONTROL

- MSSEEXEC (MASTER) - MASTER MSF CONTROL
- MSSEEXEC (SLAVE) - SLAVE MSF CONTROL
- PPU DRIVER

MSSEXEC (MASTER)

MSSEXEC IS A CM RESIDENT PROGRAM THAT WORKS WITH THE MSS PPU DRIVER TO PERFORM ALL MSS CARTRIDGE MOVEMENT AND DATA TRANSFERS IN SUPPORT OF THE MSS SOFTWARE SUBSYSTEM

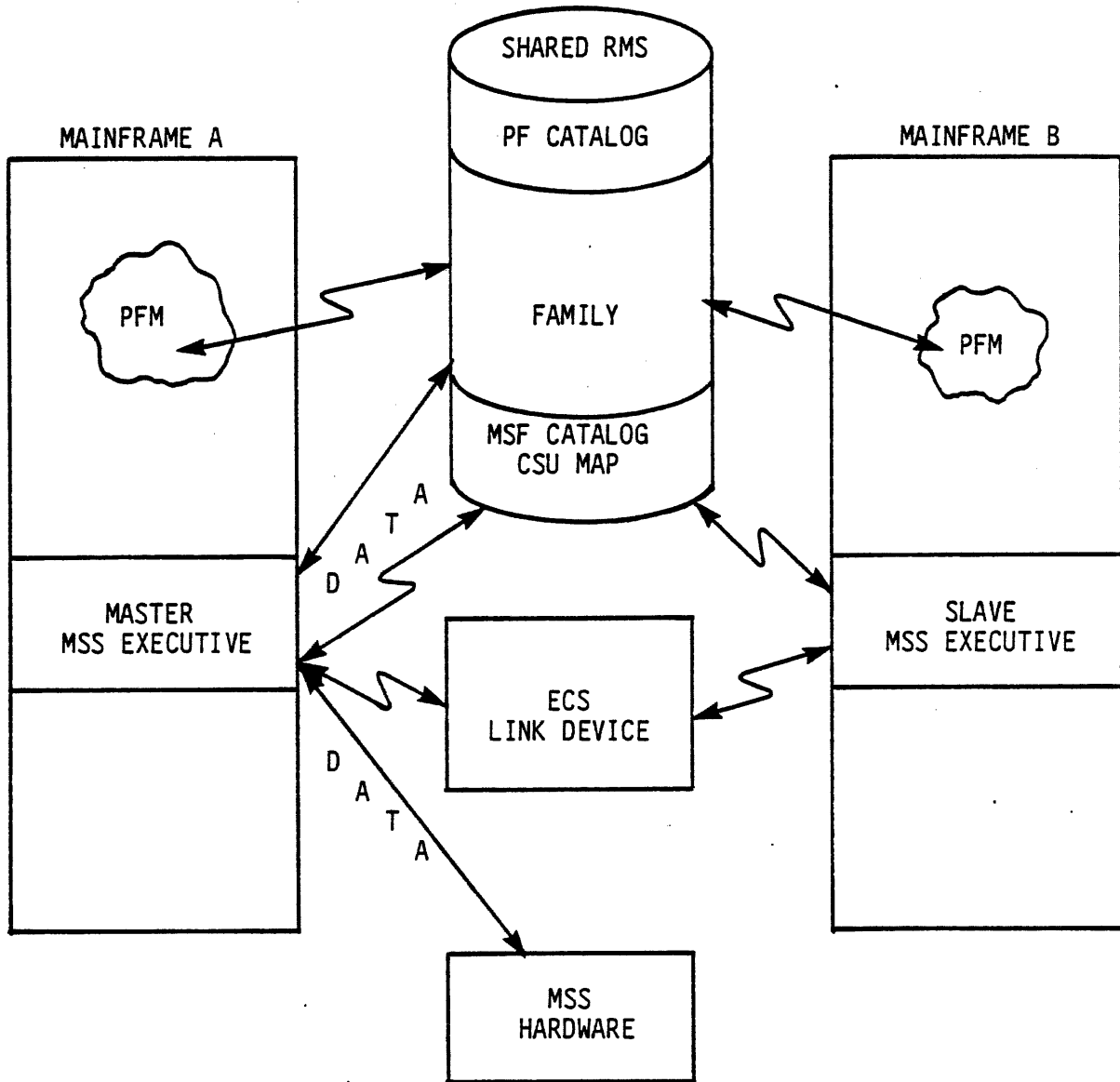
- MOVES DATA TO/FROM MSF
- MAINTAINS MSF CATALOG AND CSU MAP
- MANAGES MSF HARDWARE
- ALLOCATE MSF SPACE AND CREATE NEW MSF FILES IN RESPONSE TO REQUESTS FROM MOVE UTILITY
- STAGE FILES TO DISK IN SUPPORT OF ATTACH REQUESTS FROM MASTER OR SLAVE MAINFRAMES
- PROVIDE ACCOUNTING AND STATISTICAL INFORMATION
- SUPPORT ON-LINE DIAGNOSTICS
- MAINTAIN CARTRIDGE LOAD AND TAPE PASS STATISTICS
- DYNAMICALLY DETECT INCONSISTENCIES BETWEEN MSS CATALOG AND CARTRIDGE CONTENTS.

MSSEXEC (SLAVE)

CM RESIDENT PROGRAM THAT WORKS WITH MASTER MSSEXEC TO PROCESS ATTACH REQUEST FROM JOBS RUNNING IN SLAVE MAINFRAME

- ENTERS STAGING REQUESTS IN COMMUNICATION REQUEST FILE
- PROCESSES RESPONSES FROM MASTER MSSEXEC
- HAS JOB WAITING FOR FILE RESUMED WHEN FILE STAGED
- PROVIDES ACCOUNTING AND STATISTICAL INFORMATION FOR SLAVE MAINFRAME

MSS MULTIMAINFRAME



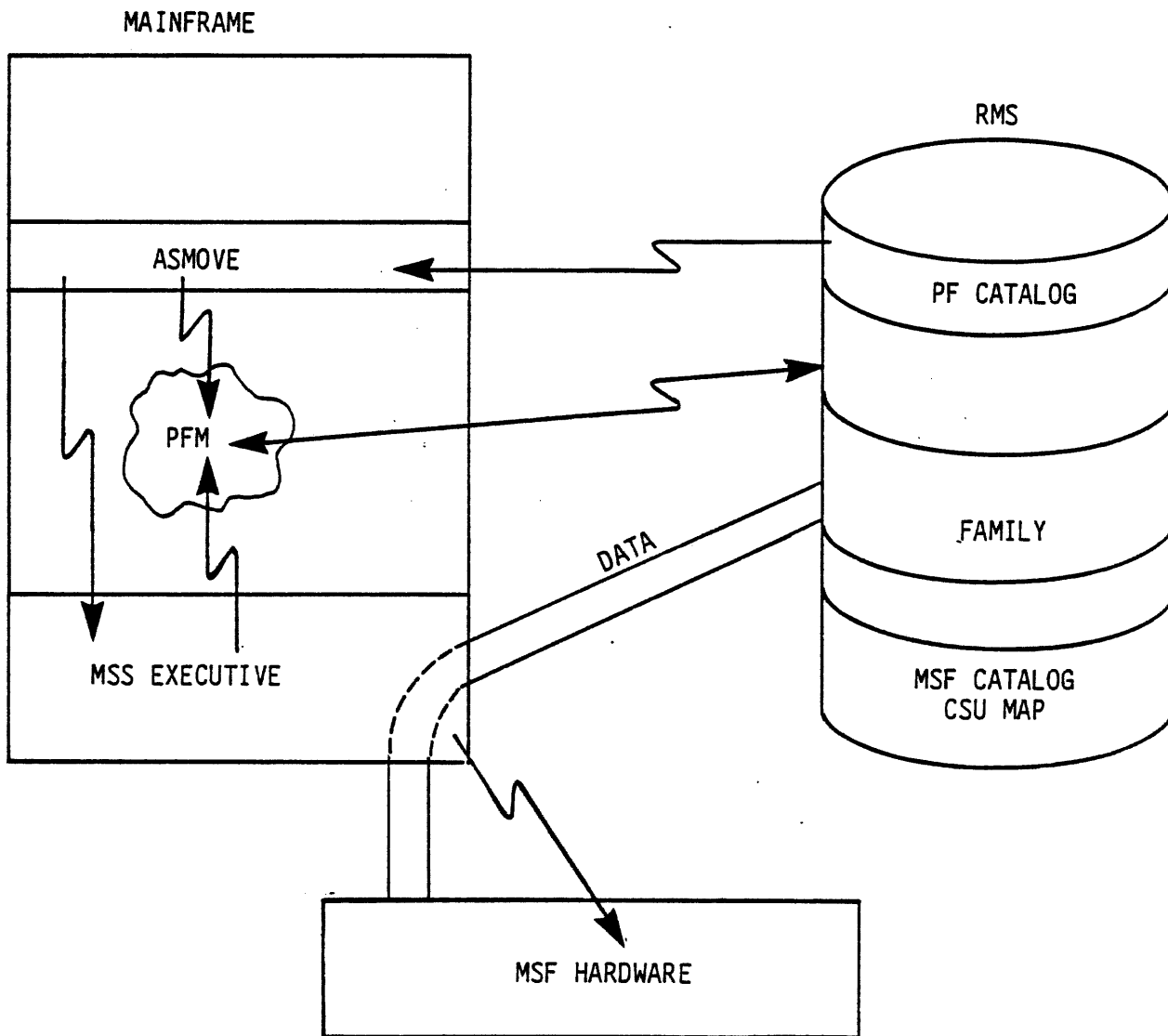
- PERMANENT, FILE SET MUST BE SHARED
- MASTER AND SLAVE COMMUNICATE VIA LINK DEVICE
- MASTER FUNCTIONS MSS HARDWARE

ASMOVE UTILITY

THE MOVE UTILITY CAUSES PERMANENT FILES TO RESIDE ON DISK AND/OR MSF IN SUPPORT OF THE SITE'S OBJECTIVES FOR DISK SPACE MANAGEMENT AND BACKUP

- DECIDES ON RESIDENCE OF FILES PER A DISK SPACE MANAGEMENT ALGORITHM THAT USES:
 - RUN TIME PARAMETERS
 - INSTALLATION PARAMETERS
 - NOS TABLE INFORMATION, PFC, ETC.
- CAUSES MSSEXEC TO PERFORM FILE DESTAGING OPERATIONS AND OPTIONALLY RELEASE DISK SPACE
- GENERATES MSS ACTIVITY REPORTS
- INVOKED MANUALLY BY SITE PERSONNEL

ASMOVE UTILITY

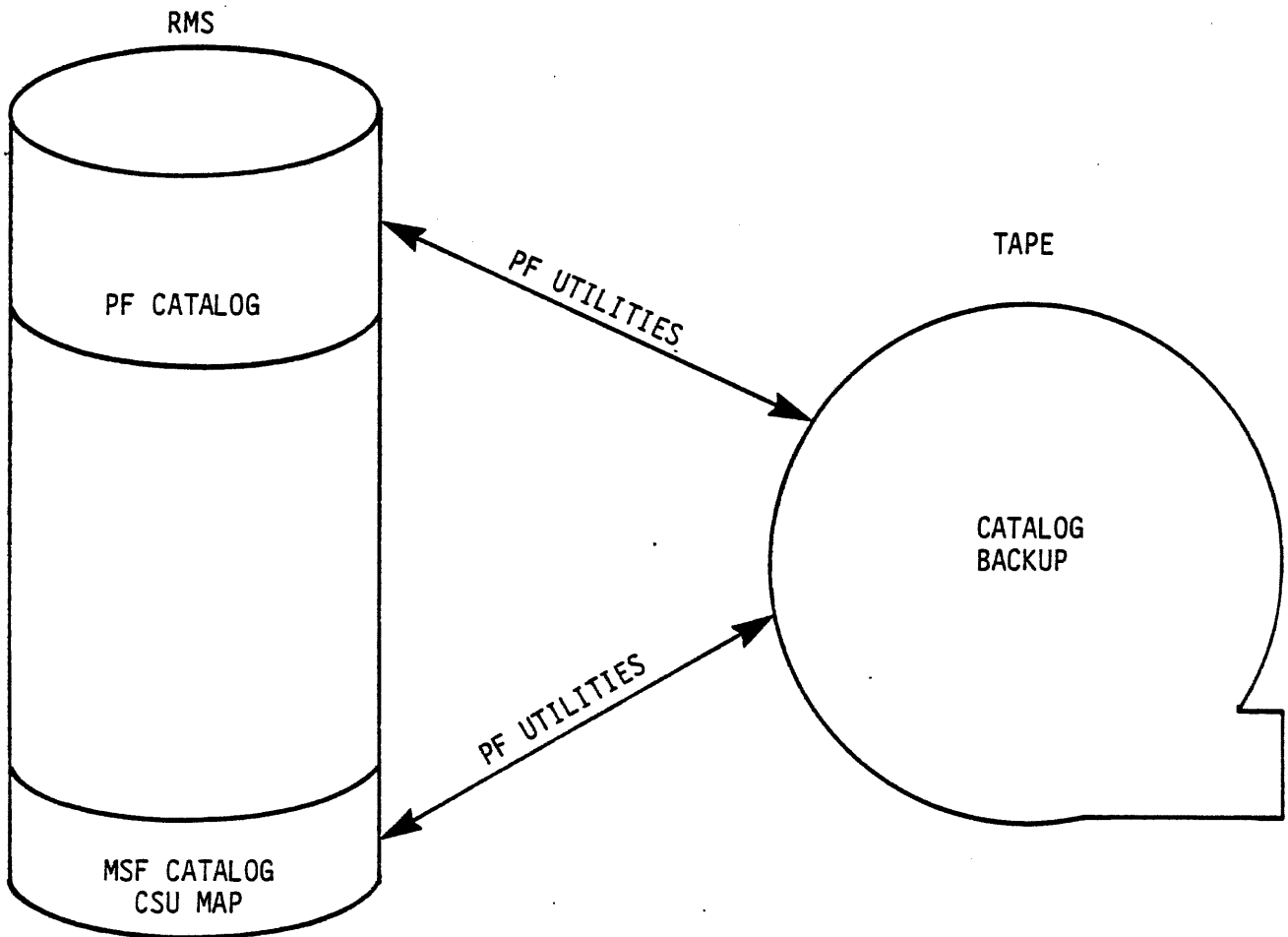


- SCANS PFC FOR MSF FILES
- SELECTS FILES TO BE MOVED TO MSF
- SELECTS FILES TO RELEASE DISK SPACE
- REQUESTS MSSEXEC TO MOVE FILES
- CALLED BY CONSOLE OPERATOR
- MSSEXEC WILL COPY FILE TO MSF AND RECATALOG FILE IN PFC

MASS STORAGE
SUBSYSTEM UTILITIES

- ASLABEL - CARTRIDGE MANAGEMENT
- ASUSE - CARTRIDGE UTILIZATION
- ASDEF - DEFINE MSF CATALOGS AND CSU MAPS
- ASVAL - INSURE MSF CATALOG INTEGRITY
- RELEASE SPACE FOR PURGED MSF FILES
- ASDEBUG - DUMPS CARTRIDGE DATA IN RAW FORM
- RESOLVES MSF CATALOG INCONSISTENCIES

TAPE BACKUP



- PF CATALOG BACKED UP BY PF UTILITIES
- MSF CATALOG AND CSU MAP BACKED UP BY PF UTILITIES

MASS STORAGE SUBSYSTEM
RELIABILITY FEATURES

- GCR RECORDING, CRC CODES
- SINGLE BIT ERRORS, MOST TWO BIT ERRORS CORRECTED
- REDUNDANT CONFIGURATION ALTERNATIVES
- AUTOMATIC WRITE ERROR RECOVERY
- FLAGGING OF UNUSABLE STREAMS
- RETRY ON READ ERRORS
- ERRORS RECORDED
- USAGE STATISTICS MAINTAINED
- ON-LINE DIAGNOSTICS
- TAPE BACKUP
- EXTENSIVE LABELING CONVENTIONS
- RECOVERY AND DEBUG UTILITIES

MASS STORAGE
SUBSYSTEM - FUTURE

- ENHANCED DISK SPACE MANAGEMENT
- DIRECT ACCESS
- DATA COMPACTION
- PRIVATE CARTRIDGES
- CARTRIDGE REMOVABILITY
- PERFORMANCE ANALYSIS
- MULTI-FILES PER STREAM
- STAGE/DESTAGE OF INDIRECT ACCESS FILES
- LOAD AND DUMP PERMANENT FILES TO MSS

QUESTION SET LESSON 28

1. Describe the hardware components of the Mass Storage Facility.
2. What is the difference between master and slave versions of MSS Executive?
3. What utilities are provided with the Mass Storage Subsystem and what are their functions?

SECTION 29

ANSWER SETS

ANSWER SET LESSON 2

1. The system library is the collection of all routines contained on the deadstart tape or introduced as part of the system online via SYSEDIT. SYSEDIT builds directories for system routines as part of Central Memory Resident.

A program library is a collection of source code routines (source code and common decks) maintained by the utility programs MODIFY and UPDATE.

A user library is a collection of relocatable routines containing a directory for use by the CYBER Loader. A user library can be built only by using the LIBGEN utility. Typically, the routines in a user library are associated with use of a given product, such as the COBOL user library.

Any file with a directory can be considered to be a "library". The records within a library file can be manipulated by the LIBEDIT utility and the contents of a library file (or any file for that matter) can be listed using the CATALOG and ITEMIZE utilities.

ANSWER SET LESSON 3

The answers in this question set refer to the study dump found in this Handout. If the study dump is not used, the instructor will be supplying you with a set of correct answers for the dump you are using.

1. a. 24B = 20
b. 24B = 20
c. 7777B = 262K
d. yes
e. 76000B; found in word CMRL
2. PP3: CIO
PP4: none
3. PP0 MTR 46
PP1 DSD 53
PP2 CPM 33
PP3 CIO 30
PP7 STM 46
PP11 QAP 33
PP22 QAP 61
PP24 CIO 61
PP26 LDQ 33
PP30 IMA 44
4. EQ0=RD.
EQ75=TT.
EQ76=TE.
EQ77=NE.

The above entries are automatic. The following is the CMRDECK used for the system on which the study dump was taken.

```
CMRDC35
NAME= (35) CYBER 174 S/N 620 CLSH.
VERSION=NOS 1-8J03T/R2B.
MID=62.
NCP=24.
IPD=3.
FNT=1756.
CM=7777.
EQ01=DQ-1,ON,0,42,5,7. SYSTEM, TEMP
EQ02=DQ-1,ON,0,43,5,7. SYSTEM,TEMP
EQ04=DI-1,ON,0,6,21,20. TEMP
EQ05=DI-1,ON,0,16,20,21. TEMP
EQ06=DK-2,ON,4,26,20,21. PF/40
EQ07=DI-N3,ON,0,24,34,44,22,24.
EQ10=DS,ON,7,0,10.
EQ11=DJ-1,ON,0,2,23,24. RMVE
EQ12=DQ-1,ON,0,40,7,5. PF/42
EQ13=DQ-1,ON,0,41,5,7. PF/43
```

EQ14=DJ-N2,ON,0,3,4,21,20. PF/44
 EQ15=DI-1,ON,0,5,23,24.
 EQ16=DI-1,ON,0,6,23,24.
 EQ17=DI-1,ON,0,4,23,24.
 EQ20=DI-1,ON,0,54,24,22. RMVE
 EQ21=DI-1,ON,0,64,22,24. RMVE
 EQ22=DJ-1,ON,0,0,22,23. FMD DRIVE FOR TESTING
 EQ23=DI-1,ON,0,35,22,23. RMVE
 EQ24=DJ-1,ON,0,1,24,22. RMVE
 EQ27=DJ-1,ON,0,3,22,23. RMVE
 EQ30=DK-1,ON,0,46,20,21. RMVE, FT.
 EQ32=DI-1,ON,0,7,23,24. RMVE
 EQ33=DJ-1,ON,0,5,20,21. RMVE
 EQ34=DJ-1,ON,0,0,7,5. RMVE
 EQ35=DJ-1,ON,0,1,5,7. RMVE
 EQ36=DI-1,ON,0,14,22,24.
 EQ37=DI-1,ON,0,15,22,23.
 EQ40=TT,OFF,7,2,0,,30. TRANEX STIMULATOR
 EQ41=TT,OFF,0,1,0,0,100. STIMULATOR
 EQ42=TT,ON,2,,2,,100. 2550-100 (6676 EMULATOR)
 EQ43=ST,OFF,7,,4. 6671
 EQ44=NP,ON,7,1,1,,2. NPU NODE3
 EQ45=NP,OFF,7,1,6,,2. LOCAL/REMOTE NPU NODE7
 EQ46=SE,ON,7,,4. STEM 6671 S/N 183.
 EQ47=CR,ON,4,,12.
 EQ50=MT-10,ON,0,0,13,32,,20. 66X
 EQ60=MT-10,ON,4,0,31,33,,10. 67X
 EQ70=CP,ON,7,,12.
 EQ71=LP,ON,3,,12. 512
 EQ72=LP,ON,2,,12.
 EQ73=LT-6,ON,5,,12. 580 UPPER/LOWER CASE
 EQ74=LS-1P,ON,6,,12. 580-20 PFC
 PF=6,F,140,140,NOSCLSH,40.
 PF=7,F,010,010,NOSCLSH,41.
 PF=12,F,003,003,NOSCLSH,42.
 PF=13,F,200,200,NOSCLSH,43.
 PF=14,F,024,024,NOSCLSH,44.
 TEMP=1,2,4,5.
 REMOVE=11,15,16,17,20,21,22,23,24,27,30,32,33,34,35,36,37.
 FAMILY=13.
 SYSTEM=1,2.
 NAMIAF=102.

5. Tape channels are 13, 31, 32, 33
Unit record channel is 12
 6. EQ = 1 and 2, track = 4004, FNT address = 6020
 7. 6070 file = PROFILB, type = FAFT, control point = 0
EQ = 13, FT = 5674, FAFT files do not have CT/CS
- 6110 file = OUTPUT, type = PRFT, control point = 2
EQ = 2, FT = 4133, CT = 4133, CS = 2

6236 file = CS00ABR, type = ROFT, control point = 0
EQ = 1, FT = 4206, ROFT files do not have CT/CS
note that the job has a subsystem connection

6410 file = EPLVER, type = PMFT, control point = 14
EQ = 13, FT = 5647, CT = 5647, CS = 1
note that the file is in read only ("write lockout" bit set to 1)

6414 file = AMBY010, type = PRFT, control point = 23
EQ = 5, FT = 5160, CT = 5201, CS = 63
note that the system sector bit is set

8. 303300B from word ACML -
9. Normally found in byte 4 of MSCL (word 24); however, this word has been destroyed which is why this system dump was necessary.
10. 16.23.30. from word TIML
11. Idle program, address in ACPL(0) is 45776B (part of CPUMTR) control point 7, address in ACPL(1) is 1600B
12. 2400 from job control block at word 35700
13. 30 from job control block at word 35713
14. OP = 4004, LP = 3740, UP = 7000 from job control block at 35721
15. location 46477: 0311 1700 1073 0000 0340
16. location 47037: 2CA, length 62B
17. PLD at 72015: 0102 2001 4114 0601 1073
RCL - none; would begin at location 71710
CLD at 72464: 0203 2300 0000 0000 0000
18. System dayfile: 40350
Dayfile Pointers: 5640
Dayfile Dump Buffer: 41450
19. CH 5 = PP 3 CH 10 = PP 1
20. None; all channels are available.
21. The control point area for control point 12 is found at address 2400B.
 - a. ALMY024 TXOT
 - b. I
 - c. One PP assigned: PP26 LDQ function 33
 - d. RA = 432600 FL = 55700
 - e. PR = 30, QP = 7000

- f. 2452211750000B quarter nanoseconds
 - g. user: AD2000 index: 2663B family default (EQ = 13B)
 - h. 241631B units
 - i. AD20GX,9,C.
 - j. EOR
22. None. When "turned off", the upper 18 bits of the PP input register would be "***".
23. FNT pointers are limited to 12 bits in word FNTF. Therefore, the maximum is 7777B = 4095.

ANSWER SET LESSON 4

1. A CPU program communicates with monitor by making RA+1 requests. Pool PPs communicate with monitor by making requests through the PP's output register in the PP's communication area. MTR makes requests to CPUMTR through a central exchange with the request in register XO of MTR's exchange package.
2. An idle exchange package for each CPU; an exchange package for each Pool PP (PP2 through PP N); an exchange package for MTR; an exchange package for each control point area.

A CYBER 176 has an additional exchange package for error exits located in CMR, following the FNT.
3. The Pool PP sets up its exchange package in CPUMTR's memory with (P) = PPR and (BO) nonzero; it writes the monitor request into the output register in the communication area; it does a central exchange (MXN); it reads the first word of its exchange package; if (BO) is nonzero, then the exchange is retried as the exchange did not take place; if (BO) = 0, the exchange took place and the Pool PP waits for the function to be completed by waiting for byte 0 of its output register to become zero.
4. MTR sets up its exchange package in CPUMTR's memory with (P) = PMN, (BO) nonzero and (XO) = request; it does a central exchange (MXN); it reads the first word of its exchange package; if (BO) is nonzero, the request is retried; if (BO) = 0, processing continues. MTR does not wait for CPUMTR to complete its request before continuing.
5. The program writes its system request into location 1 of its field length (RA+1) and executes an XJ instruction.
6. The "old" active exchange package is moved to its address from ACPL. "New" exchange package information is set into ACPL and B2. If necessary, CPUMTR rebuilds the PP's exchange package. CPUMTR exchanges to the address in B2, thus starting the new program.
7. Program mode is interruptable by another exchange; monitor mode is not interruptible. Program mode is used for time consuming tasks.
8. In monitor mode, an XJ exchanges with the address specified in the instruction, namely, Bj+K. In program mode, an XJ exchanges with the address contained in the executing exchange package's MA (monitor address) register.

ANSWER SET LESSON 5

1. W = waiting for the CPU
X = waiting in periodic recall
I = auto recall
A = active in CPU 0
B = active in CPU 1
" " = no CPU status but other job activity

2. Periodic recall means that the CPU program has relinquished the CPU for a installation specified period of time. Automatic recall means that the CPU program has relinquished the CPU until a pending RA+1 request completes or the program is restarted by the PP routine that satisfied the RA+1 request. Auto recall means that the CPU program has relinquished the CPU until a previous RA+1 request completes, that is, the completion bit (bit 0) in a status words becomes set to 1.

ANSWER SET LESSON 6

1. CPUMTR; some requests are processed directly by CPUMTR, other requests are satisfied by CPUMTR assigning a PP to accomplish the request.
2. CPUMTR will execute subroutine APJ (Assign PP Job) if it does not process the RA+1 request internally. If the job has QP , MXPS, APJ will force the request to be made with auto recall and will not assign a PP if there is other PP or tape activity present. (CIO requests skip these checks.) If not at PP saturation, APJ calls APS (Assign PP and Search Library). APS will search the PLD by executing subroutine SPL (Search Peripheral Library). SPL returns the residency address (load parameters) for the desired routine or for SFP (if the routine was not found). APS retrieves the next PP from the NP stack, sets the routine name in the message buffer, clears the upper six bits of the request as a flag indicating the directory has already been searched, writes the request into the PP's input register, and then updates the NP stack linkage and the PP count in STSW. APS returns to APJ which will end the program's CPU usage (ECP) if an auto recall request and indicate the PP involved by setting the PP's output register address into RA+1.

ANSWER SET LESSON 7

1. The delays balance system activity by causing certain system activities, such as job switching and PP recall, to occur periodically.
2. MTR issues an RCLM monitor request for the waiting control point if the recall delay time has expired.
3. Channels are interlocked by MTR in the channel reservation table. All routines reserving channels must use the RCHAN (reserve channel) or DCHAN (release channel) macros or the RCHM (reserve channel) or DCHM (drop channel) functions to guarantee that channel reservations are properly maintained.

ANSWER SET LESSON 8

1. TUFL Table.

<u>CP</u>	<u>RA/100</u>	<u>FL/100</u>	<u>TUFL</u>	<u>RA/100</u>	<u>FL/100</u>
1	300	20	0	300	20
2	320	320	0	320	320
3	640	0	10	640	0
4	650	0	30	650	0
5	700	17	61	700	17
6	1000	0	10	1000	0
7	1010	50	50	1010	355
10	1130	0	50	1413	0
11	1200	100	0	1413	100
12	1300	10	0	1513	10
13	1310	50	20	1523	50
14	1400	0	10	1573	0
15	1410	5	163	1573	5
16	1600	200	-0-	1600	200

2. 46400 from word ACML in low core CMR
3. The sum of TUFL values from control point 7 to N give $50+50+20+10+163 = 333$ which is greater than 305 (amount of increase/100)
 $MM = 15, MM+1 = 163, MM+2 = 7, MM+3 = 7, MM+4 = 5$
4. See table
5. 2000 in word 1 of CMR (MFLL)
6. A storage move will occur so that this control point's field length is at the end of memory.
7. NOS manages field length in multiples of 100B and stores RA and FL in 12 bit bytes. A 262K CM configuration is 1000000B words; thus with the largest address for NOS being 777700B (stored as 7777B), the last 100B words cannot be accessed.

ANSWER SET LESSON 9

1. At PPFW. It must load at PPFW-5 for the 5 byte header, and if using mass storage drivers, should not use memory beyond BFMS (6776), since that area is the driver's default buffer area.
2. To insure proper operation of the system, it is necessary to move control point field lengths in central memory and ECS. In most cases, a control point cannot be moved while it has PP activity. Therefore, a PP should PAUSE occasionally for storage movement to occur.
3. Pool PPs loop reading their input registers (IR); if the input register becomes non-zero, it is because CPUMTR chose that PP to execute a particular PP routine.
4. A Pool PP program makes monitor requests by using the MONITOR macro, which jumps to PPR subroutine FTN. FTN writes the request into the PP's output register (OR), sets up the PP's exchange package in CPUMTR with (P) = PPR and (BO) nonzero. After doing a MXN, FTN reads the first word of the PP's exchange package and if (BO) = 0, the exchange was successful. FTN then loops reading the output register. Byte 0 of the output register will be set to zero to indicate that the request has completed. Monitor requests processed by MTR are handled in a similar manner, except that the MXN and BO checks are not done.
5. The control point assignment is found as the lower 5 bits of byte 1 of the input register. PPR will store the control point address for this control point number in direct cell CP (74).
6. PP routines use PPR subroutine DFM to write messages into all dayfiles, whether they be the system, account, control point or error log dayfiles.
7. The updated RA and FL will be found in direct cells RA and FL, which are set by the PP resident subroutine PRL, which gets these values from bytes 3 and 4 of control point word STSW. After a pause, if the RA or FL has changed, any absolute addresses stored in the program must be re-absolutized. This includes all places where instruction modification was done to use absolute addresses.
8. Overlays may be called into a PP by using the EXECUTE macro, which jumps to PP resident subroutine EXR. EXR in turn jumps to subroutine PLL to load the routine into the PP, then EXR enters the overlay for execution.
9. These locations are used by the mass storage drivers for error processing and as a default buffer.

10. A "PP HUNG" indicates that a PP has issued a monitor function for which CPUMTR finds something wrong during its processing. A "HUNG PP" indicates that a PP has issued a monitor function for which MTR finds something wrong during its processing. Both messages are displayed from the system control point's MS2W message area. The packed time and date (PDTL) is entered into the last word of the "hung" PP's communication area. The system will continue to operate as much as possible, so more than one PP could become "hung" at a time.
11. Left to the student.

ANSWER SET LESSON 10

1. SETMS (Set mass storage driver parameters) performs the following operations: passes read/write operation to the driver insures correct driver is loaded presets the driver initializes DRSW, RDCT, STSA, WDSE sets write error buffer address selects error processing options SETMS is called:

- before any initial read/write
- switching between read and write
- switching logical tracks
- changing error processing options

ENDMS (End mass storage driver access) performs the following operations:

- releases channel
- releases controller
- releases drive
- releaes other I/O resources

2. A PP routine requests mass storage space by using the monitor function RTCM (Request Track Chain) for the desired number of sectors on the desired equipment (either the type of equipment or equipment number). CPUMTR will allocate a track chain for at least that many sectors in multiples of tracks.
3. Read sector = RDS; Write sector = WDS.
4. The drop track (DTKM) monitor function is issued after writing a disk file so that any unused tracks may be returned to the pool of allocatable tracks. The DTKM function also enters the sector number of the EOI (end-of-information) in the track linkage byte of the track in which it occurs.
5. The first track is 5702 which links to 5746, 6016, 6121, 6122, 6123, 6124, 5365, 6135 where the EOI is in sector 76. Since this is a DI-3, there are 501B sectors per track; therefore, the file length is 5106B sectors long (10B x 501B + 76B).
6. The flaws are:

EQ=6	111	141
EQ=14	4	166
7. The mass storage driver performs a seek operation to inform the disk controller of an address to position to in preparation for the next data transfer. Once the seek is initiated by the controller, the disk drive can complete the positioning without further direction from the controller. This allows the controller to perform read and write operations or to initiate positioning on other drives that may be accessed through the controller. This overlapping of head positioning with reading, writing, or initiation of head movement is called seek overlap. Seek overlap is managed through the driver seek wait (DSWM) monitor function. There are two options for seek overlap: waiting for position and waiting for unit. Waiting for position

typically occurs if the drive is currently positioning or the position sought is not in the same cylinder as the current position. Waiting for unit typically occurs when another PP is in a waiting for position condition with the unit reserved.

8. When writing in 1-to-1 interlace (full tracking), the error status for a write is not always immediately available. In order to correctly process write errors, some special considerations are needed. If the "last sector write" function is used, the status is immediately available and error processing continues normally. To recover from certain errors when not doing a "last sector write" and the error occurs in the previous sector, the processing done depends on the error processing options selected and the presence of a recovery buffer specified in the SETMS call.

If a recovery buffer is specified and write error processing is not selected, the previous data is read into the recovery buffer and recovery is attempted. If the recovery is successful, the current sector is retried.

If a recovery buffer is specified and write error recovery is also specified, the previous data is read into the recovery buffer and recovery is attempted. If the retry is unsuccessful the (A) = -0 is returned. If the retry is successful, writing continues with the current sector.

If a recovery buffer is not specified and write error processing is not selected, the operation is aborted as an unrecoverable error.

If a recovery buffer is not specified and write error recovery is specified, the previous data is read over the current sector and recovery is attempted. If recovery is successful, the (A) = -1 is returned to indicate that the current data must be regenerated. A status of (A) = -0 indicates the previous sector recovery was not successful.

9. 706B sectors per track
physical units 03 and 04 (from MST word DDLL)

DJ-2

ANSWER SET LESSON 11

1. The A register is set to 10000B so that the PP can input its entire field length before being released from the IAM instruction (disconnected).
2. At deadstart time, each PP is hung on a input on its channel to read into the PP beginning at word 0. That is,

IAM ppch,0
3. Routine SET and subsequent routines expect to find routines in a certain order.
4. The deadstart panel is read into PPO beginning at word 1 through word 17 (CYBER 17X, word 14 for 6000/CYBER 70) and are used to load the initial program. Panel words 5 through 20 are passed to SET by CTI.
5. NOS uses the HDT to indicate to the system software what hardware features are available for use, such as, central memory size, number and status of PPs and PPs, number of CPUs, CMU, CEJ/MEJ, instruction stack, and so on. Various system tables will be defined and system code loaded and/or executed based on the hardware properties.
6. At deadstart time, SYSEDIT builds the PPLIB, RPL, RCL, PLD, and CLD. It builds these tables in the same manner when it is run "online".
7. PPLIB contains all the PP routines that are not in the RPL. The PP routines have their prefix (77) table stripped from them leaving only the single word PP header. These routines are still complete with prefix tables on the SYSTEM file. The PLD points to the address of the routine in the PPLIB, rather than the address of the routine on the SYSTEM file.
8. The system checkpoint builds the skeleton of the system table or checkpoint file on the first system device. This checkpoint file is used for subsequent deadstart recoveries.
9. A level 0 recovery is used to initialize the system (initial deadstart) and to recover from unsuccessful level 3 deadstarts. Jobs are recovered by the QREC utility if QPROTECT had been enabled when the jobs were introduced to the system, and permanent files and dayfiles are recovered from the mass storage devices on which they reside.

A level 1 recovery is used to resume system operations after a controlled idle down and a CHECKPOINT SYSTEM. The operating system and active jobs and files are recovered from the checkpoint file.

A level 2 recovery is used to resume system operations after a controlled idle down and a CHECKPOINT SYSTEM (as a level 1) with the operating system being re-established from the deadstart file. Active jobs and files are recovered from the checkpoint file.

A level 3 recovery is used to resume operations from a system hang or equipment malfunction interruption. Active jobs and files and the operating system are recovered from central memory tables (FNT, libraries and directories).

10. On a level 0 deadstart, MS VALIDATION and PF VALIDATION have no special meaning. Dayfiles, permanent files in write mode, and other preserved files are verified with respect to their EOI.

On a level 3 deadstart, MS VALIDATION and PF VALIDATION play a major role. Both must be specified, and if so, EOI verification is done for all preserved track chains, and circular linkage is checked for all recoverable files (entries in FNTs).

11. Deadstarting with device checkpoints pending may destroy the integrity of permanent files, since track linkages may be lost during recovery of the devices.
12. The Deadstart Sequencing priority calling of CMS causes CMS to issue certain control statements which must run to completion before any job processing may be done. The scheduler will not schedule any jobs if a job with the Deadstart Sequencing priority is at a control point.

ANSWER SET LESSON 12

1. For a write request, an FNT/FST entry will be created and the write performed. For a read request, an FNT/FST entry will be created and a EOI status returned.
2. CIO performs all mass storage input/output and position operations using its main routine and appropriate CIO overlays.
3. CIO extracts the function code from the FET, loads an appropriate overlay, and performs the requested read/write/ position operation until the operation has completed, the FET buffer becomes full or empty, or a given number of sectors are transferred.
4. Random input/output is accomplished by the user specifying logical addresses of records from which CIO computes a corresponding logical disk address for the particular record.

For a random read, the user sets the contents of FET+6 to the logical address of the record desired and issues a random read request with the random bit set in FET+1. CIO will convert the specified address into a logical disk address, position the disk to that address, and begins transferring data from that disk address to the FET buffer.

5. "Rewrite-in-place" is the random output technique of writing a new logical record over an existing logical record. The "rewrite" CIO functions do not alter the end-of-information of the file (unless the file is lengthened) but may alter the file data structure with record or file marks.
6. CIO terminates an operation when the buffer is full/empty, FL/ 100 sectors have been transferred, or when the desired file structure mark (EOR, EOF, EOI, BOI) is reached (for reads only).
7. CIO sends a three word parameter block to a specific unit descriptor table (UDT) address within MAGNET's field length by using the TDAM monitor function. CIO forces the request into recall and MAGNET will eventually complete the request.
8. CIO stores the FET address in the control point area word TIOW (output) or TINW (input), forces the request into recall, and issues the rollout (ROCM) monitor function to roll the job out. IRO then handles the data transfer with the time-sharing subsystem.

ANSWER SET LESSON 13

1. IDS is used when DSD must perform a request on a given control point or file, do mass storage activity, or any time consuming task. The text of the command is passed to IDS in the DSD/IDS communication buffer in CMR.
2. Resident syntax table
 - Master display routines
 - Keyboard processor
 - Resident subroutines
 - Syntax and Function Overlay area
 - Left Screen program
 - Right Screen program
3. Interpretative syntax works as follows. As the operator enters a command, if DSD can determine the remaining characters of the command uniquely from the characters entered so far, it will fill them in or even complete the command phrase and display them for the operator automatically.
4. They sense an "*" from the keyboard. If "*" is sensed as the first character, the routine releases the channel. When the routine (either DSD or DIS) is not connected to the display channel, it periodically checks the channel status table to determine if the display channel is available. If available, the routine will request the channel via the RCHM monitor function.
5. DSD does not have a PP resident. It also cannot risk blanking the screens by attempting to load one of its overlays from disk. Therefore, to load overlays, DSD calls PP routine 1DL via a RPPM. 1DL selects the desired routine and sends it to DSD via the display channel. CM resident DSD overlays are read directly by DSD.
6. Console displays are formatted and painted on the screen one line at a time. The display overlay issues the display coordinates for each piece of information to be displayed as it processes the information.

ANSWER SET LESSON 14

1. The scheduler should be called whenever there is a change in system resources. The scheduler is requested for this case by the RSJM monitor function. However, the scheduler is also called on a periodic basis by the system monitors. MTR requests CPUMTR to call the scheduler and CPUMTR will assign a PP to ISJ or ISP accordingly.
2. Queue priorities are aged by ISP. Each time ISP is called, it adds 1 to the increment interval (byte 4) of the queue control word. If byte 4 is equal to the increment (byte 3), byte 4 is cleared and this serves as a flag to ISP to add 1 to the queue priority for all files of the origin and queue type as long queue priority lies between the lower (LP) and upper (UP) aging bounds.
3. ISP checks for CM and CPU time slice expirations. If either slice expires, the queue priority for the job is set to the lower bound for the origin.
4. Disable priority evaluation - yes via PRIORITY command; disable autoroll - yes via AUTOROLL command; job scheduling - no.
5. The scheduler may request a job be rolled out if it finds a candidate job with a higher priority needing field length or a control point so that it might begin/resume execution.
6. Job selection is done as follows.
 - o Select the highest queue priority job that fits into unassigned or available memory within the service constraints (FL/EC, AM/EM) for the candidate's origin type.
 - o For equal candidates, select the job from the device with the least mass storage activity as determined by:
 - no free channel
 - channel requested
 - first unit reserved
 - o When the mass storage activity is also equal, select the job with the largest FL requirement
 - o If no job was selected, but one was rejected because of the service constraints, repeat the selection process above but consider only those jobs that will fit in central memory without rolling out other jobs. The job selected by this process will have its queue priority set to its origin's lower bound. (This step prevents the system from sitting idle during periods of low activity.)

7. Control point selection is done as follows.

Considering a control point's field length to be all the FL of unoccupied control points following the candidate, the selection order is: choose the control point that is

- o an exact fit
- o the smallest hole larger than what is needed
- o the largest hole if none satisfies
- o if no control points are available or rolling out, the first control point encountered with a lower queue priority than the candidate is selected to be rolled out. If all control points have a higher QP, no control point is selected.

Field length is then obtained based on the control point selected. The above sequence is such that the control point selected requires the minimum amount of storage movement to obtain the desired memory.

8. 1AJ is called when scheduling a job from the input queue while 1RI is called when scheduling a job from the rollout queue.

If a PP is not available, 1SJ writes the 1AJ/1RI request into its input register, requests the scheduler via the RSJM function, and jumps to PP resident which will cause the new PP routine to be loaded into this PP.

9. CPUMTR calls 1AJ when there is no activity (zero status) or the rollout flag is set for the control point. This is called "job advancement".
10. 3AA is called by 1AJ to begin a new job. Typically this is the case on calls to 1AJ from the scheduler. 3AA will read the control statement record into the control statement buffer (CSBW), process the job card (which has already been cracked by OVJ), initialize the control point area, and initiate job processing.
11. The error processing overlay (3AB) is called by 1AJ upon the detection of an error flag in STSW or error exit or reprieve control in EECW. 3AB processes Extended Reprieve, EREXIT/ Reprieve, EXIT., and abort job processing. Depending on the type of abort and recovery options selected by the job, 3AB flushes output files (using the list of files (LOFW) pointer if present), issues diagnostics, takes dumps, and either recovers the job either in the same job step (reprieve and EREXIT) or another job step (EXIT.), or terminates the job.
12. Overlay TCS (Translate Control Statement) processes control statements and may be called via a RA+1 request or by the main 1AJ routine in a job advancement situation.
13. STIME. RTIME. CTIME. HTIME.

14. Operating system argument processing uses the actual separator when passing the arguments while Product Set format uses a code for the separator. This allows the Product Set format to use (eventually) 7 8-bit characters and a 4-bit code in a 60-bit word.
15. If a CPU program to be loaded is in the RCL or in an ECS ASR, the program is transferred into the control point field length by the LCEM monitor function. If SYSEDT is active, however, the program will be loaded from mass storage. The LCEM function will use the fastest transfer mechanism available on the system (ECS, CMU, register-register). For programs being loaded from mass storage, the program is read from the system library (or local file) directly into the control point field length.
16. Absolutes and overlays are loaded directly into the field length by 1AJ. Relocatables are loaded by the CYBER Loader (which is an absolute).
17. A PP routine may be called from a control statement provided the caller is of system origin or has system origin privileges with DEBUG mode on. 1AJ searches the PLD for the routine and loads it into its PP.
18. 1DS has a table of subsystems. On function 33 (AUTO/MAINTENANCE) 1DS checks the SSTL word to see if the subsystem is enabled and if so, automatically initiates it. 1DS then checks SSCL if determine if the subsystem is already active, and if so, ignores the request to activate it. 1DS then builds an input file FNT/FST entry for the PP routine routine that will initiate the subsystem, including the control point requirement, initial FL, and subsystem QP. The scheduler will select this entry from the input queue and call overlay 3SA to initiate the PP initializer routine.
19. SYSMAX is the maximum FL currently available for any job, computed on a job origin basis. $SYSMAX = \text{machine size} - \text{CMR size} - \text{constant}$. MAXFL is the maximum field length the job may ever attain, computed on a job origin basis. $MAXFL = \min \frac{1}{2} \text{ job card CM, validation CM, SYSMAX, service FL } \frac{1}{2}$. MFL is the current job step maximum field length. RFL is the current field length (running field length). NFL is the nominal field length (same as RFL). SYSDEF is the default initial field length if no other FL can be determined and RFL is zero.
20. Initial field length is the first one of the following that applies:
 - o FL required specified by CLD field length control (RFL=or MFL=)
 - o Routine has required FL in loader (54) table
 - o RFL specified by an RFL macro or statement
 - o use the smaller of MFL and SYSDEF
21. Initial field length for ECS is the first one of the following that applies:
 - o routine has required ECS FL in a loader (54) table
 - o ECS FL has been specified by a RFL macro or statement

ECS field length is not preserved between job steps unless protected via the PROTECT statement or macro.

22. The field length control in the CLD entry represents either a RFL= or a MFL= initial FL specification; the *FL directive simply allows a RFL=/MFL= to be specified if the program does not have either of these entry points.

For RFL=, the specified field length will be set as the RFL value in FLCW and used as the initial field length.

For MFL=, if the MFL= control flag is 0, then the maximum of the existing FL (STSW) and the specified MFL will be used as the initial running field length. If the MFL= control flag is 1, the the maximum of the current RFL (FLCW) and the specified MFL will be used as the initial running field length.

23. The DMP RA+1 request is processed by PP routine SFP. SFP makes a SPCW call for DMP, issuing a ROCM on the control point. IAJ is called and senses a SPCW request. It (IAJ) searches the CLD for entry point DMP, which it finds in routine CPMEM. CPMEM has a DMP=entry point. IAJ calls IRO to process the DMP=value, creating a DM* file with the appropriate field length from the calling program. IAJ returns and loads CPMEM into the field length space written on DM* by IRO. CPMEM begins execution at the DMP entry point. When CPMEM completes and IAJ is called to advance the job, it senses the completed SPCW call, reloads the original program field length from the DM* file by calling IRI. When IAJ resumes control after IRI has restored the field length, control returns to the program at the instruction word after the DMP RA+1 call.
24. The SSJ= entry point allows the program containing it to have certain system privileges not normally given to CPU programs, such as using Fast Attach files; allows the program to specify time limit, CPU and Queue priorities; and may transfer user validation between the control point area and the user program field length. The UIDW, ALMW, ACLW, and AACW control point words are transferred to the program's field length when loaded, and are reset in the control point area when the program terminates. Any time limit, CPU or queue priority values specified in the SSJ block are entered into the control point area when the program is loaded, with the current values entered into the SSJ block, from which they will be reset when the job step terminates. Files created by a SSJ= program have special file identification SSID; these files will be automatically returned at the end of the job step.

ANSWER SET LESSON 15

1. A system resource unit (SRU) is a measure of resources used by a job or terminal session. The SRU combines measurement of central memory field length, ECS field length, CPU time, mass storage, magnetic tape and permanent file usage into a single unit. The algorithm is:

$$SRU=M1(CP+M2*IO)+M3(CP+IO)CM+M4(CP+IO)EC)+AD$$

2. ADD applies the adder to the SRU accumulator: $SRU = SRU + AD$;

AIO applies the I/O increment to the SRU accumulator:
 $IO = S2*MS + S3*MT + S4*PF$ then $SRU = SRU + IO*IOM$;

CPT applies CPU time to the SRU accumulator:
 $CP = S0*CP0 + S1*CP1$ then $SRU = SRU + CP*CPM$;

SRU calculates the SRU multipliers CPM and IOM when field lengths change:
 $CPM = M1 + M1*M3 + M1*M4$ and $IOM = M1*M2 + M1*M3 + M1*M4$.

3. An "account block" is the SRU accumulation from one CHARGE statement to the next (or end of job). In effect, it is the SRU accumulation for a given charge/project.
4. The VALIDUs file contains limits on resource usage, various permissions, and default TELEX terminal characteristics for each user number. The VALINDs file indicates the user indices that have been assigned to user numbers. Each bit in this file represents a user index; if the bit is set, the corresponding user index is in use.
5. The PROFILa file contains charge numbers, project numbers, SRU multipliers M1 - M4 and AD, allowed access times, user numbers permitted to use the project numbers, and project SRU accumulation and limit values.
6. The only relationship is that user numbers are used in the project entries to (optionally) restrict project usage to those users.
7. GEAC uniquely describes the conditions that prompted the issuance of the ACCOUNT file entry: G = group, E = event, AC = activity.
8. The VALIDUs level-2 block contains validation entries for up to four user numbers.
9. The level-1 block contains the charge number, master user number, and SRU multipliers M1 - M4 and AD. The level-2 block contains the project numbers. The level-3 block contains detailed project information.

ANSWER SET LESSON 16

1. "Holes" in the indirect chain are pointed to by empty catalog entries (UI = 0).
2. "Master" users have implicit read permission for permanent files cataloged under user numbers that match in non-asterisk positions. Therefore, user USER*** has read permission for USERXYZ's files.
3. Both a semi-private file or a library (public) file can be accessed by any user by specifying the permanent file name, the user number under which it is cataloged, and the password (if defined). The system records the number of times the file was accessed for either file category. However, for semi-private files the user number and last access date/time of the accessor are also recorded.
4. Indirect files must reside on the user's master device since that is where the indirect chain resides. Direct access permanent files may reside on any device within the family that has the appropriate secondary mask bit set for the user's user index.
5. For direct access permanent files, each user attaching the file in read mode will have their own FNT/FST entry for the file. The number of users accessing the file is kept in the DAF's system sector.
6. Each user receives a complete local copy of the permanent file and manipulates that local file rather than the original permanent file.
7. Attaching a direct access permanent file with "write" permission essentially locks the file in that no other user can access it until it is returned. This prevents two users from modifying the file at the same time. However, if any users have attached the file in read mode prior to the attempt to attach in write mode, the write requestor will be aborted. The write accessor may choose to wait until the file becomes available for write access by using the NA (no abort) option.
8. When a direct access file is purged, the user index in the catalog entry is cleared and all tracks released. When an indirect access file is purged, the user index in the catalog entry is cleared (creating a hole in the indirect chain.) If the amount of space returned includes one or more logical track, the track(s) is(are) returned to the system and the indirect chain relinked by the DLKM (Delink Tracks) monitor function. The catalog entry is updated to reflect the new length of the hole.
9. If the appropriate secondary mask is not set, the DEFINE is aborted. This situation easily occurs if the existing file is not on the proper device when the DEFINE is performed.
10. PFM searches the user's catalog track for a hole that is an exact fit (same number of sectors), and if one exists, it is used. If there is no exact fit, then PFM uses the largest hole and creates a new hole entry for the residue (if more than one sector). If no holes satisfy the request, a new catalog

entry is created at the end of the catalog chain. The file is then copied into the hole space or at the end of the data chain. For a REPLACE, the file is copied over the existing entry if it is an exact fit or if the new file is smaller, in which case, a hole will be created for residues larger than one sector. If the new file is larger, a hole will be made of the existing entry, and the process described above will be followed to create a new catalog entry for the file.

11 - 14. The following table contains the answers for questions 11 through 14.

	<u>EQ 6</u>	<u>EQ 7</u>	<u>EQ 12</u>	<u>EQ13</u>	<u>EQ 14</u>	
Permit FT (11)	4043	4043	4013	4013	4044	Data FT (11)
4042	4042	4012	4012	4043	Data Length (12)	52D+265B 44D+24B
27D+334B	28D+275B	60D+252B	Permit Length (13)	151	231	250 226
227	Catalog tracks (13)	40	40	10	10	40 Device Mask (14)
140	10	3	200	24	Secondary Mask (14)	140 10
3	200	24				

Data length is in tracks + sectors;
Permit length is in sectors.

15. Catalog track overflow is indicated by bit 57 in MST word ACGL. None of these master devices has catalog track overflow.
16. 4001 4002 4003 4004
4005 4006 4007 4010
17. 0, MD = 7, SD = 7 and 6
1, MD = 6, SD = 7 and 6
2, MD = 5, SD = 5 and 4
3, MD = 4, SD = 5 and 4
4, MD = 4, SD = 5 and 4
5, MD = 5, SD = 5 and 4
6, MD = 6, SD = 7 and 6
7, MD = 7, SD = 7 and 6
18. 1231, MD = 6, CT = 23 = 4024
1237, MD = 7, CT = 3 = 4004
19. Device 4 has 40B catalog tracks.
Device 5 has 40B catalog tracks.
20. TRT linkage will link track 4010 to track 4234. Mass storage linkage with the catalog tracks will link from the last sector of track 4002 to track 4234 sector 0.

ANSWER SET LESSON 17

1. Control statements processed by RESEX are:

LABEL
ASSIGN
REQUEST
RESOURC
VSN

2. Deadlock prevention is a process performed by RESEX to guarantee that the assignment of a tape or pack will not cause a deadlock on tape/pack resources. All jobs must still be able to complete after the requestor has been assigned the requested resource.
3. RSXDId is the demand file. In addition to a header that identifies the job for the demand file entry, each entry contains assign counts, demand counts, MT/RP validation limits, preview data, and the share table. RSXVid is the VSN file. In addition to the header, it contains the file name, the demand entry address and index to the resource entry within the demand entry, and volume serial numbers (VSNs). The VSN entries end with a code that describes the VSN usage ("0" = end of VSNS, "/" = multiple reels, "=" = equivalenced VSNs).
4. The assignment order within RESEX is:
 - a. search environment for VSN or PACKNAME
 - b. perform deadlock prevention (overcommitment algorithm)
 - c. send call block to MAGNET via SIC with tape data
 - d. make share table entry if removable pack
 - e. update demand file entry
5. An "internal call" is the assignment of a tape resource when called by a control statement; the arguments are processed, then the resource assignment process is entered. An "external call" is the entry into the assignment process via the special call (SPCW) mechanism because of user RA+1 assignment requests (PFM, LFM, REQ).
6. A "deadlock" or "potential deadlock" condition exists when two or more jobs demand resource units such that no more resources are available (deadlock) or there are not enough free resource units available to satisfy the resource requirements of these jobs (potential deadlock).

A "resource unit" is any magnetic tape drive or removable mass storage equipment.

The "resource type" is the mnemonic that refers to a type of resource unit. Tape resource types are the tape densities (LO, HI, HY, HD, PE, GE) and removable pack types are the mass storage mnemonic and number of spindles (DI1, DK2).

The "demand count" is the number of resource units required by the job and may be used to refer to an individual resource type or to the demand for all resource types. The "assigned count" is the number of resource units currently assigned to the job, both on an individual and total resource type basis.

The "demand file" is a fast attach permanent file that contains job demand information for all jobs in the system. The "VSN file" is a fast attach permanent file that contains the file name/VSN correspondence for all tape files in the system.

The "demand file entry" is the job's entry on the demand file containing its resource demands and assignment counts.

A "VSN file entry" is an entry on the VSN file that consists of Volume Serial Numbers associated with a given tape file.

The "resource environment" is a snapshot of all the resource units in the system, what tapes or packs are mounted on them, and the jobs to which they are assigned. The environment is built from the EST, MSTs, and UDTs.

The "share table" is part of a job's demand file entry and is used to keep track of which removable packs are assigned to the job.

"Pack sharing" is the ability for more than one job to use the same removable pack. If the pack is mounted, then it can be shared. A job cannot ever assume that pack sharing will or will not take place.

The term "overcommitment algorithm" is used to describe the entire deadlock prevention mechanism as well as the main subroutine of that process, OCA (Overcommitment Algorithm).

ANSWER SET LESSON 18

1. The UDT contains hardware properties of the tape unit, software and processing properties associated with the tape being manipulated, label information, operation control information for interaction between MAGNET and IMT, and job assignment information.
2. CIO writes its requests to MAGNET directly into the tape unit's UDT via the TDAM monitor function.

RESEX makes requests of MAGNET through its call block RCAL using the SIC RA+1 request. The RESEX call block and the preview buffer are the two buffers identified for SIC communication in the ICAW word.

Other PP routines (IDS, REC, ORF, ...) make requests to MAGNET by writing their requests in the external request buffer XREQ using TDAM. The functions performed via this mechanism are:

- 0 - return unit
- 1 - enter VSN
- 2 - unload VSN
- 3 - scratch VSN
- 4 - up/down channel
- 5 - on/off unit

3. RESEX sends compressed data via a SIC RA+1 request to the preview buffer PBUF in MAGNET's field length. DSD processes this compressed data while painting the E,P display.
4. Tape labels uniquely identify the file and the reel on which it resides, and they mark the beginning and end of a tape file and reel.

VOL1 contains the VSN, volume accessibility code, and owner identification.

HDR1 contains the file identifier, set identifier, file section number, file sequence number, generation number, generation version number, file accessibility, creation date, expiration date, and system identification code.

EOF1 matches the HDR1 label but additionally contains a block count of the number of PRUs in the file.

EOV1 matches the VOL1 label but additionally contains a block count of the number of PRUs in the reel.

5. IMT contains many overlays that perform given functions. As IMT and each overlay are loaded, it determines various tape properties for the tape unit being processed from the UDT and presets operations (function codes, error recovery, etc.) depending upon the type of tape drive. This preset operation allows the processing logic to be generally written; that is, there need not be a separate driver for each type of tape hardware.

ANSWER SET LESSON 19

1. IIO (executive), ICD (driver), QAP (auxiliary), and COMSBIO (common deck).
2. BATCHIO's field length is used for communication, FETs and buffers. There is no CPU code for BATCHIO.
3. When in the "idle" state, IIO is recalled from RLPW to status unit record equipment. If there is no unit record activity to be done, IIO writes its input register into RLPW and drops its PP, going on recall.
4. ICD does mass storage input/output by making CIO requests.
5. IIO calls ICD which in turn calls QAP to create an input queue entry (a FNT/FST entry of type INFT). QAP call OVJ to validate the job card and generate the jobname hash.
6. Example.

The LQyy,xx. DSD command allows the operator to set an ID on a particular card reader, punch, or printer. Jobs that enter via a card reader with an ID of xx will have their output processed on printers or punches with IDs of xx. When IIO calls QAC to search for disposable output, it specifies the TID field (in this case the ID of the peripheral) on which a match should occur.

7. The DCWs serve to indicate whether a copy of ICD is active and how many peripherals that copy is driving.
8. The DRQR is used to request an active copy of ICD to perform a given operation. The copy of ICD that should perform the operation, the operation and the buffer point are specified in the DRQR request.
9. BATCHIO is a subsystem with a queue priority greater than MXPS: it cannot be rolled out.

ANSWER SET LESSON 20

1. All routing and disposition information is found in the system sector.
2. COMPUSS. . System sector definitions are found in COMSSSE.
3. "Terminal addressing" is the identification of the family/user number/user index of the remote batch terminal that can process the output or has submitted the input. The terminal ID (TID) field is found in the FST with expanded information being found in system sector words FDSS, DASS, and DISS.
4. F - forms code, X - external characteristics, D - device code.

There is limited space within the FST for these values. If a value beyond the FST field is necessary, the system sector must be read to obtain the actual value.

5. A deferred route is the setting up of the system sector without disposing the file. The system sector information bit (bit 5 in the FNT) is set when the field is necessary, the system sector must be read to obtain the actual value.
6. A deferred route is the setting up of the system sector without disposing the file. The system sector information bit (bit 5 in the FNT) is set when the system sector already contains the routing and disposal information.
7. QAP is part of File Routing and Queue Management since it is used by both BATCHIO and RBF to process disposed output files in a uniform manner, thus giving consistent accounting, banner pages, and so forth for all printer output.

ANSWER SET LESSON 22

1. A system control point must be a subsystem (i.e., have a unique queue priority assigned and associated with a byte in the SSCL words of CMR). A system control point processes requests from user control points. A user control point requires no special privileges to access the System Control Point Facility but must know the queue priority and protocol of the subsystem it will use. THE SYSTEM control point is the last control point plus 1 and is the "control point" for CPUMTR program mode executions.
2. The user control point uses the SSC RA+1 call or the CALLSS macro to transfer an array of request data to a subsystem. The user control point uses the subsystem queue priority to specify the system control point being accessed.

The system control point uses the SSF RA+1 call or the SFCALL macro to transfer data to or from a user control point's field length. The SSF call or SFCALL macro accesses a parameter array which includes the transfer buffer address in both the system control point and the user control point. Actual data transfers are done by the SCP module of CPUMTR in program mode.

ANSWER SET LESSON 25

1. EI200's control point field length is used for communication buffers, I/O buffers, port tables, a "mini"-RPL of ILS overlays, and data conversion subroutines.
2. Port table and input/output FETs and buffers.
3. It uses CIO.
4. Data is transferred from the terminal over the communication lines to the multiplexor. LED takes the data from the mux and passes it to a line buffer within the EI200 control point's field length. The data is converted into a FET buffer from which it can be written to mass storage by CIO as the buffer fills. At the end of the file transfer, ILS and XSP cause the file to be validated and entered into the input queue.

For output, ILS retrieves the file for the RJE terminal from the output queue. A banner page is formatted into the FET buffer and the buffer is filled by reading the file using CIO. Data is taken from the FET buffer and converted into the line buffer. LED reads the data from the line buffer, sends it to the multiplexor, which in turn passes on to the terminal.

5. The terminal ID and destination information from the system sector are matched with the family/user number/user index of logged-in remote batch terminals. The highest priority file is then disposed by ILS, based on the destination information.
6. XSP processes drop job requests, logs in terminals, and makes initial input queue entries for jobs read from the remote batch terminal.
7. While LED is transmitting print data or receiving card reader input from the terminal, it monitors the keyboard. All keyboard entries except the interrupt key are ignored. If LED senses the interrupt key, it will stop transmitting and receive input from the keyboard. At that time, the terminal operator can suspend or end the operation.

ANSWER SET LESSON 26

1. The typical end user knows only a login/logoff procedure and a set of scripts that need to be followed for each type of transaction. The end user does no programming and for the most part simply "fills in the blanks".
2. A transaction is an inquiry or change of a data base. A transaction has three phases: data acquisition, processing of data, and data output.
3. A task is a small piece of coding. One or more of these pieces (tasks) make up a transaction. These tasks are used to build the transaction application system. A task may be written in COBOL, FORTRAN or COMPASS, and a total transaction may involve tasks written in any (or all) of these languages. All tasks may be collected onto a library file (Task Library) maintained by the utility LIBTASK.
4. The five components of TAF are: NAM or TELEX to control terminal input/output; TAF, the executive that controls the execution of applications and data managers; Data Manager; User Tasks; and Utility programs.
5. Yes.
6. The transaction executive coordinates and controls the execution of applications and the data manager and affords task isolation and recovery mechanism as well as interfacing to the input/output mechanisms.

ANSWER SET LESSON 27

1. The MRT indicates the local or shared status of the tracks reserved on a shared mass storage device. The MRT is used to clear interlocks on preserved files that are held by a down machine, and to clean up local file usage by a down machine under MREC control.
2. The following procedure is used to retrieve the "up-to-date" TRT.

Determine if device is shared by examining SDGL for the ECS address of the MST.

Obtain the TRTI interlock.

Read first three words of global MST.

Reject function if another machine's mask is found in SDGL.

Examine SDGL to determine if this machine was the last accessor; if so, this machine has the "up-to-date" TRT. Otherwise, the MST and TRT are read from ECS to the ECS buffer and then moved to the MST/TRT area for the device. (This allows error recovery without destroying good data.)

Set the machine mask in SDGL and write these three words back to ECS to interlock this operation.

Release TRTI interlock.

3. The "machine ID" is a two character identifier for the machine supplied by CMRDECK entry MID. The "machine index" is the position that the machine's MMFL word is entered in MFET when the machine is introduced into the complex. The "machine mask" is a mask bit 2^{**} (machine index - 1) that is used for identifying interlock holders. Machine index may be 1, 2, 3, 4 and machine mask may be 1, 2, 4, 10.
4. The main MMF tables kept in ECS are: the MMF Environment Table, the Intermachine Communication Area, the Device Access Tables, the Fast Attach Table and the global PFNL. The MST/TRT/MRT for shared devices are part of the DAT.
5. Every two seconds, the clock area is read from ECS. If a machine's clock has not changed every other read (four seconds), that machine will be declared "down".
6. MREC clears up hardware reservations preventing other machines from accessing shared devices; clears access information in the DAT; clears interlocks and user counts in system sectors of files shared with the down machine; processes the MRT to release all local space held by the down machine.

Once MREC has been run for a down machine, all information about that machine has been cleared. The only way to re-introduce the machine is by a level 0 deadstart.

ANSWER SET LESSON 28

1. Hardware components of the Mass Storage Facility are:

CYBER Mass Storage Coupler which interfaces the 12-bit CDC CYBER peripheral processor with the 8-bit byte-oriented Mass Storage Adapter.

Mass Storage Adapter is a micro-programmable processor providing the overall control of the Mass Storage Facility in response to functions received from the CYBER PP via the Mass Storage Coupler.

Cartridge Storage Unit stores cartridges in a matrix and transfers them between input/output drawers, the matrix, and Mass Storage Transport I/O stations.

Mass Storage Transport exchanges cartridges with the Cartridge Storage Unit and transfers data between the cartridge tape and the Mass Storage Adapter.

Mass Storage Cartridge consists of a plastic case containing the magnetic tape used for data recording.

2. In a multimainframe complex only one mainframe can be driving the Mass Storage Facility. This mainframe is the master mainframe and contains the Mass Storage Subsystem master executive. The primary differences between master and slave executives are:

Master executive contains the driver interface and the CPU portion of the driver.

Master executive requests the actual staging and destaging of files between disk storage and tape cartridges.

Slave executive processes all file staging requests by transferring the request to the master executive via communication files in the link device.

3. Mass Storage Subsystem utilities are:

ASMOVE provides the logic for selecting which direct access permanent files are candidates for staging to the Mass Storage Facility

ASLABEL provides the cartridge management functions for Mass Storage Facility

ASDEF initializes the Mass Storage Subsystem system files necessary for mass storage processing, i.e., the CSUMAP files and the MSF catalog files.

ASVAL examines the MSF catalog files and the permanent file catalogs and issues a report on any irregularities or discrepancies found. This utility also releases Mass Storage Facility space for files that have been purged from the permanent file base.

ASUSE produces reports detailing cartridge usage.

ASDEBUG dumps data from cartridges in raw form for problem analysis. This utility also releases Mass Storage Facility space or system file entries to resolve previously detailed inconsistencies.

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EVALUATION FORM

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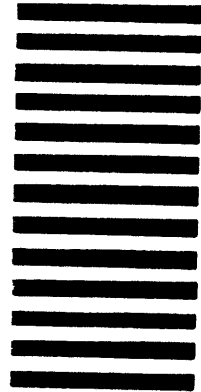
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