## Data Conversion PRODUCTS CATALOG



## Data Conversion PRODUCTS CATALOG

## Anhloger. 1985



## TABLE OF CONTENTS

1. General Information
Introduction ..... 1-1
Placing An Order ..... 1-1
Data Sheets/Literature ..... 1-1
Prices and Terms ..... 1-1
Quotations ..... 1-1
Returns and Warranty Service ..... 1-1
Applications/Technical Assistance ..... 1-1
Sales Offices .(Inside Back Cover)
2. Amplifiers
Selection Guide ..... 2-2
Glossary ..... 2-3
AH201-1 Single Channel Audio Distortion Suppressor ..... 2-5
AH201-2 Dual Channel Audio Distortion Suppressor. ..... $2-5$
MP221 Low Noise Chopper Stabilized Amplifier ..... 2-11
MP227A Precision Isolation Amplifier ..... 2-17
3. Sample-and-Hold Amplifiers
Selection Guide ..... 3-2
Glossary ..... 3-3
MP260 $3 \mu \mathrm{~S}, 0.002 \%$ Linearity S/H (Optimized for Simultaneity). ..... 3-5
MP261 $5 \mu \mathrm{~s}, 0.002 \%$ Linearity, Low Droop S/H ..... 3-5
MP270 $1 \mu \mathrm{~s}, 0.005 \%$ Linearity S/H ..... 3-11
MP271 $1 \mu \mathrm{~s}, 0.003 \%$ Linearity S/H ..... 3-15
MP272 350 ns, $0.01 \%$ Linearity S/H ..... 3-21
MP282A Dual Simultaneous S/H with 1-bit Gain Ranging ..... 3-27
4. Analog-to-Digital Converters
Selection Guide ..... 4-2
Glossary ..... 4-3
MP2316 16-bit, Floating Input, Programmable Gain, Analog Processor ..... 4-11
MP2321 3 1/2 Digit BCD Output Integrating A/D ..... 4-21
MP2322 12-bit Binary Output Integrating A/D. ..... 4-21
MP2712D 12-bit, $5 \mu \mathrm{~s}$ A/D ..... 4-25
MP2713C 13-bit, $10 \mu \mathrm{~s}$ A/D ..... 4-25
MP2714C 14-bit, $10 \mu \mathrm{~s}$ A/D. ..... 4-25
MP2734 14-bit, $6.8 \mu \mathrm{~s}$ A/D. ..... 4-31
MP2735-1 Low Distortion, 15-bit Audio Digitizer (S/H and A/D) ..... 4-37
MP2735-2 Low Distortion, 15 -bit, $5 \mu \mathrm{~S}$ A/D. ..... 4-37
MP8014 14-bit, $10 \mu$ s Precision A/D ..... 4-43
MP8015 15-bit, $15 \mu$ s Precision A/D ..... 4-43
MP8016 16-bit, $32 \mu$ s Precision A/D ..... 4-43
MP8037 17-bit, 250 Hz Integrating A/D ..... 4-49
5. Data Acquisition Subsystems
Selection Guide ..... 5-2
ADAM-724 14-bit, $6.8 \mu \mathrm{~s}$ A/D with Integral S/H and Differential Amplifier. ..... 5-3
ADAM-812 Dual Simultaneous $\mathrm{S} / \mathrm{H}$ and 12-bit 50 kHz A/D ..... 5-13
ADAM-822 Dual Simultaneous S/H and 12-bit 26 kHz A/D ..... 5-17
ADAM-824A Low Power, 14 -bit, 50 kHz A/D with S/H ..... 5-23
ADAM-825A Low Power, 15 -bit, 50 kHz A/D with S/H ..... 5-23
ADAM-826 Family of 16 -bit, Ultra Speed A/D Converters ..... 5-27
ADAM-826-1 16-bit, $1.5 \mu \mathrm{~s}$ A/D with Integral 800 ns S/H ..... 5-33
ADAM-826-2 16-bit, $1.5 \mu \mathrm{~s}$ A/D with Integral 400 ns Buffer Amplifier ..... 5-37
ADAM-826-3 16-bit, $1.5 \mu \mathrm{~s}$ A/D (Unbuffered) ..... 5-41
ADAM-834A Low Power, Extended Temperature 14-bit A/D and S/H ..... 5-45
ADAM-835A Low Power, Extended Temperature 15-bit A/D and S/H ..... 5-45
MP8008R 8-bit, 300 kHz , Ultra-high Differential Linearity, Sampling A/D Converter5-49 SHAD2A Two-Channel, 16 -bit Audio Digitizing Subsystem ..... 5-53
6. Digital-to-Analog Converters
Selection Guide ..... 6-2
Glossary ..... 6-3
AH8304TC Triple 4-bit 100 MHz TTL-compatible Video D/A. ..... 6-7
AH8304TM Triple 4 -bit 20 MHz TTL-compatible Video D/A with 32 word color LUT memory ..... 6-7
AH8308E Single 8-bit, 150 MHz , ECL-compatible Video D/A ..... 6-13
AH8308T Single 8-bit, 100 MHz , TTL-compatible Video D/A ..... 6-21
AH8308TC Triple 8-bit, 100 MHz TTL-compatible Video D/A ..... 6-29
AH8404TC Triple 4-bit, 25 MHz TTL-compatible Video D/A ..... 6-33
AH8404TM Triple 4-bit, 20 MHz TTL-compatible Video D/A with 32-word color LUT memory ..... 6-33
MP1480S 12-bit D/A with 4-20 mA Current Loop or Voltage Output ..... 6-37
MP1814 14-bit General Purpose D/A ..... 6-43
MP1913A 13-bit Precision D/A ..... 6-47
MP1914A 14-bit Precision D/A ..... 6-47
MP1915A 15-bit Precision D/A. ..... 6-47
MP1916A 16-bit Precision D/A. ..... 6-47
MP1914TC 14-bit Temperature Stabilized Precision D/A ..... 6-51
MP1915TC 15-bit Temperature Stabilized Precision D/A ..... 6-51
MP1916TC 16-bit Temperature Stabilized Precision D/A ..... 6-51
MP1926A 16-bit Sign/Magnitude, Professional Audio D/A ..... 6-55
MP1926S 16-bit Ultra-stable Sign/Magnitude D/A ..... 6-55
MP1936 16-bit Sign/Mag. Professional Audio D/A with
Integral Distortion Suppressor ..... 6-63
MP8116 16-bit Ultra-Stable, Ultra-Precision D/A ..... 6-73
MP8308ECL 8-bit ECL-compatible Modular Composite Video D/A ..... 6-79
MP8308TTL 8-bit TTL-compatible Modular Composite Video D/A ..... 6-79
MP8318ECL 8-bit ECL-compatible non-composite Video D/A ..... 6-79
MP8318TTL 8-bit TTL-compatible non-composite Video D/A ..... 6-79
7. dc/dc Converters
Selection Guide ..... 7-2
Glossary ..... 7-3
MP3015 + 5V In, $\pm 15 \mathrm{~V} @ 100 \mathrm{~mA}$ Out, dc/dc Converter ..... 7-5
MP3020 +5 V In, $\pm 15 \mathrm{~V} @ 150 \mathrm{~mA}$ Out, dc/dc Converter ..... 7-9
MP3024 +5 V In, $\pm 15 \mathrm{~V} @ 75 \mathrm{~mA}$ Out, dc/dc Converter ..... 7-13
MP3026 + 5V In, $\pm 15 \mathrm{~V}$ @ 150 mA Out, dc/dc Converter ..... 7-13
MP3035 + 5V In, $\pm 15 \mathrm{~V} @ 165 \mathrm{~mA} \&+5 \mathrm{~V} @ 750 \mathrm{~mA}$ Out dc/dc Converter ..... 7-17

## ALPHANUMERIC PRODUCT INDEX

Model Product Page
ADAM-724 14-Bit, $6.8 \mu \mathrm{~s}$ A/D with S/H and Diff. Amp ..... 5-3
ADAM-812 Dual Simultaneous $\mathrm{S} / \mathrm{H}$ and 12-bit, 50 kHz A/D ..... 5-13
ADAM-822 Dual Simultaneous S/H and 12-bit, 25 kHz A/D. ..... 5-17
ADAM-824A Low Power, 14 -bit, 50 kHz A/D with Integral S/H ..... 5-23
ADAM-825A Low Power, 15 -bit, 50 kHz A/D with Integral S/H ..... 5-23
ADAM-826-1 16-bit, $1.5 \mu$ S A/D with Integral 800 ns S/H ..... 5-33
ADAM-826-2 16 -bit, $1.5 \mu \mathrm{~s}$ A/D with Integral 400 ns Buffer Amplifier ..... 5-37
ADAM-826-3 16-bit, $1.5 \mu \mathrm{~s}$ A/D (Unbuffered) ..... 5-41
ADAM-834A Low Power, Extended Temp. Range 14-bit A/D and S/H ..... 5-45
ADAM-835A Low Power, Extended Temp. Range 15-bit A/D and S/H ..... 5-45
AH201-1 Single Channel Audio Distortion Suppressor. ..... 2-5
AH201-2 Dual Channel Audio Distortion Suppressor ..... 2-5
AH8304TC Triple 4-bit, 100 MHz , TTL Video D/A Converter ..... 6-7
AH8304TM Triple 4-bit, 20 MHz TTL Video D/A with 32-word color LUT Memory ..... 6-7
AH8308E Single 8-bit, 150 MHz , ECL-compatible Video D/A ..... 6-13
AH8308T Single 8-bit, 100 MHz , TTL-compatible Video D/A ..... 6-21
AH8308TC Triple 8-bit, 100 MHz , TTL-compatible Video D/A ..... 6-29
AH8404TC Triple 4-bit, 25 MHz , TTL-compatible Video D/A ..... 6-33
AH8404TM Triple 4-bit, 20 MHz , TTL-compatible Video D/A with 32-word color LUT memory ..... 6-33
MP221 Low Noise Chopper Amplifier ..... 2-11
MP227A Precision Isolation Amplifier ..... 2-17
MP260 $3 \mu$ s Sample-and-Hold (Optimized for Simultaneity) ..... 3-5
MP261 $5 \mu$ s Sample-and-Hold ..... 3-5
MP270 $\quad 1 \mu \mathrm{~s}, 0.005 \%$ Linearity Sample-and-Hold ..... 3-11
MP271 $1 \mu \mathrm{~s}, 0.003 \%$ Linearity Sample-and-Hold ..... 3-15
MP272 350 ns, $0.01 \%$ Linearity Sample-and-Hold ..... 3-21
MP282A Dual Channel Sample-and-Hold with 1-bit Gain Ranging ..... 3-27
MP1480S 12-bit D/A with $4-20 \mathrm{~mA}$ Current Loop or Voltage Output ..... 6-37
MP1814 14-bit General Purpose D/A Converter ..... 6-43
MP1913A 13-bit Precision D/A Converter. ..... 6-47
MP1914A 14-bit Precision D/A Converter. ..... 6-47
MP1915A 15-bit Precision D/A Converter ..... 6-47
MP1916A 16-bit Precision D/A Converter ..... 6-47
MP1914TC 14-bit Temperature Stabilized Precision D/A Converter ..... 6-51
MP1915TC $\quad 15$-bit Temperature Stabilized Precision D/A Converter ..... 6-51
MP1916TC 16-bit Temperature Stabilized Precision D/A Converter ..... 6-51
MP1926A 16-bit Sign/Magnitude Professional Audio D/A Converter ..... 6-55
MP1926S 16-bit Ultra-stable Sign/Magnitude D/A Converter ..... 6-55
MP1936 16-bit Sign/Magnitude Professional Audio D/A with Audio Distortion Suppressor. ..... 6-63
MP2316 16-bit Floating Input, Programmable Gain, Analog Processor ..... 4-11
MP2321 3 1/2 Digit BCD Output Integrating A/D Converter. ..... 4-21
MP2322 12-bit Binary Output Integrating A/D Converter ..... 4-21
MP2712D 12-bit, $5 \mu \mathrm{~s}$ A/D Converter. ..... 4-25
MP2713C 13-bit, $10 \mu \mathrm{~s}$ A/D Converter. ..... 4-25
MP2714C $\quad$ 14-bit, $10 \mu \mathrm{~s}$ A/D Converter ..... 4-25
MP2734 14-bit, $6.8 \mu \mathrm{~s}$ A/D Converter ..... 4-31
MP2735-1 Low Distortion, 15-bit Audio Digitizer (A/D + S/H). ..... 4-37
MP2735-2 Low Distortion, 15-bit, $5 \mu \mathrm{~s}$ A/D Converter ..... 4-37
MP3015 +5V In, $\pm 15 \mathrm{~V} @ 100 \mathrm{~mA}$ Out, $0.01 \%$ Regulation dc/dc Converter ..... 7-5
MP3020 + 5V In, $\pm 15 \mathrm{~V} @ 150 \mathrm{~mA}$ Out, $0.1 \%$ Regulation dc/dc Converter. ..... 7-9
MP3024 +5V In, $\pm 15 \mathrm{~V} @ 75 \mathrm{~mA}$ Out, $0.75 \%$ Regulation dc/dc Converter ..... 7-13
MP3026 +5 V In, $\pm 15 \mathrm{~V} @ 150 \mathrm{~mA}$ Out, $0.2 \%$ Regulation dc/dc Converter ..... 7-13
MP3035 +5V In, $\pm 15 \mathrm{~V}$ @ 165 mA Out, $0.1 \%$ Regulation, +5V @ 750 mA Out 1\% Regulation dc/dc Converter. ..... 7-17
MP8008R $\quad 8$-bit, 300 kHz , Ultra-high Differential Linearity Sampling A/D ..... 5-49
MP8014 14-bit, $10 \mu \mathrm{~s}$ A/D Converter. ..... 4-43
MP8015 15-bit, $15 \mu$ S A/D Converter ..... 4-43
MP8016 16-bit, $32 \mu \mathrm{~s}$ A/D Converter. ..... 4-43
MP8037 17-bit, 250 Hz Integrating A/D Converter ..... 4-49
MP8116 16-bit, Ultra-Stable, Ultra-Precision D/A Converter. ..... 6-73
MP8308ECL 8-bit, ECL-compatible, modular composite video D/A Converter ..... 6-79
MP8308TTL 8-bit, TTL-compatible, modular composite video D/A Converter. ..... 6-79
MP8318ECL 8 -bit, ECL-compatible, modular non-composite video D/A ..... 6-79
MP8318TTL 8 -bit, TTL-compatible, modular non-composite video D/A. ..... 6-79
SHAD2A Two-channel, 16-bit Audio Digitizing Subsystem. ..... 5-53

## ANALOGC.

## SECTION 1

General Information

## INTRODUCTION

The purpose of this Catalog is to provide you, the system designer, with an easy to use reference on data conversion technology as well as a selection guide for Analogic's Data Conversion Products. Complete technical data is provided for all of our standard product line. Similar products are grouped according to function, i.e. all amplifiers are in one section, all sample-and-hold amplifiers are in another section, A/D converters in another, etc. Selection guides are provided to assist in the selection of the appropriate product with respect to the most critical parameters for a given application. If information on a specific product is required, an alphanumeric index of all products is also provided.
Special modifications to standard products are easily accomplished; please consult the factory for details.

## PLACING AN ORDER

Orders may be placed via mail, telephone, or Telex with any Regional Sales Office, sales representative, or our headquarters in Wakefield, Massachusetts. Our offices are listed on the inside back cover of the catalog. When placing your order, please provide complete information, including Analogic Model Number with all option designations, your Part Number (if required), product description or name, quantity required, and ship-to and bill-to addresses

## DATA SHEETS/LITERATURE

Product data sheets on new products not found in this Catalog, or containing more recent revisions, are available from your local sales representative or Analogic sales office.

## PRICING AND TERMS

Pricing on Analogic data conversion products is available from any of our Sales Offices, Subsidiaries, International Distributors and Sales Representatives, or direct from the factory.
All prices are FOB Wakefield, Massachusetts, USA, in US dollars unless otherwise noted. Applicable federal, state, and local taxes are extra. Terms are net 30 days.

## QUOTATIONS

Price quotations made by Analogic or its authorized field sales representatives are valid for 30 days. Delivery quotations are subject to reconfirmation at the time the order is placed.

## RETURNS AND WARRANTY SERVICE

When returning products for any reason, it is necessary to contact Analogic, prior to shipping, for authorization and shipping instructions. In the U.S., contact our Customer Service Department at the factory in Wakefield, MA at (617) 246-0300 or 1-800-237-2200. In other countries, contact your nearest Analogic sales office or representative.

## APPLICATIONS ASSISTANCE

If you need technical assistance regarding any aspect of the standard Data Conversion Products offered in this catalog, or, if you require a modification to a standard product to meet your requirements, or, if you would like to discuss your application and the use of Analogic's extensive expertise in the signal conditioning and data conversion areas to design and manufacture a subsystem or component to meet your specific requirements, please call our Applications Engineering Group at (617) 246-0300 Ext. 2368 or 2168.TABLE OF CONTENTS
Selection Guide ..... 2-2
Glossary ..... 2-3
AH201-1 Single Channel Audio Distortion Suppressor ..... 2-5
AH201-2 Dual Channel Audio Distortion Suppressor ..... 2-5
MP221 Low Noise Chopper Stabilized Amplifier ..... 2-11
MP227A Precision Isolation Amplifier ..... 2-17
MP230 Low Pass Modular Filter. ..... 2-17

## anamosac.

## SECTION 2

Amplifiers

SELECTION GUIDE

| MAJOR CHARACTERISTIC <br> OR APPLICATION REQ'MT | PRIMARY <br> PARAMETER | SECONDARY <br> PARAMETER | RECOMMENDED <br> MODEL NO. | DATA SHEET <br> ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| Signal Conditioning | Differential <br> Input | High Isolation <br> Voltage | MP227A | $2-17$ |
|  | Single-Ended <br> Input | Low Noise <br> Low Bandwidth | MP221 | $2-11$ |
| DAC Deglitching <br> Professional Audio | Low <br> Larmonic <br> Distortion | Single- <br> Channel | Dual-Channel | AH201-1 |
|  | AH201-2 | $2-5$ |  |  |

## GLOSSARY OF TERMS

## AMPLIFIERS

FULL POWER BANDWIDTH The highest frequency at which an amplifier, loaded to maximum rated output, will track a sinusoidal signal large enough to drive the output to its rated full-scale value at peak input. The nominal relationship between full power bandwidth and the slew rate is:
$\mathrm{f}=$ Slew Rate $/ 2 \pi \mathrm{e}_{\mathrm{fs}}$
where: $f=$ Full Power Bandwidth e
$\mathrm{e}_{\mathrm{fs}}=$ rated full scale output.
GAIN ACCURACY The maximum amount that the actual voltage gain deviates from the nominal value expressed as a percentage of that nominal value. This takes into account the effects of temperature variations, power supply variations, and drift with time, if significant.

ISOLATION AMPLIFIER A circuit that typically accepts a low level signal, often in the presence of a high level common mode voltage, from a transducer, and amplifies it to produce a clean, accurate output signal. Figure 1 shows a simplified functional diagram.

OVERLOAD RECOVERY TIME The time required for the circuit to return to linear operation, within a stated tolerance, after removal of a sustained input that was large enough to drive the circuit into complete saturation (i.e., a condition in which further increase in the input did not significantly increase the output).

SETTLING TIME The maximum time required for the output to track the input to within the specified accuracy after a full range step change.

SLEW RATE The maximum slew rate is the fastest rate of change of the output of the amplifier. This is normally obtained by a step input signal that drives the output from end to end of its range.

SMALL SIGNAL BANDWIDTH The maximum small signal bandwidth is the highest frequency at which an amplifier will track, to within 3 db of the low frequency response, a sinusoidal signal having an amplitude below that for which the slew rate limitation is significant.


Figure 1. Simplified Functional Diagram.


## ANVALDGTO

## AH201

Distortion Suppressor

## Description

The AH201 is a low-cost distortion suppressor, used to reduce the total distortion generated by unmatched bit switching in the decoder digital-to-analog (D/A) converter section of a digital audio or communications system. The AH201 features exceptionally low noise ( -115 dB ), and a time-constant limited response that eliminates slew-rate limiting problems, yet is short enough ( $3.4 \mu \mathrm{~s}$ ) to ensure no significant attenuation of signals up to 20 kHz . These features, combined with a typical feedthrough rejection of 100 dB , provide a significant improvement in the performance of any digital audio decoder. Optimum performance is obtained by using the AH2O1 in combination with a true 16-bit D/A converter such as the ANALOGIC MP1926A.
All D/A converters generate some dynamic distortion each time they perform a conversion. This distortion results from code-dependent switching glitches or from slew-rate limiting of the D/A's output amplifier. Conventional sample-and-hold (S/H) amplifiers used at the D/A output do not suppress this distortion adequately for high performance,
professional audio applications due to slew-rate limiting when changing modes. The AH201, however, can reduce the distortion from these nonlinearities by up to 40 dB or more, depending upon the decoder with which it is used. (Refer to Figure 2 for example).
The AH201 is a direct result of ANALOGIC's considerable experience in digital audio including professional audio recording, studio links, and telecommunications. Designed for ease of interconnection and maximum flexibility, the distortion suppressor requires a single control line per channel to provide all necessary control. The AH201 accepts a $\pm 10 \mathrm{~V}$ input and can drive up to $\pm 16 \mathrm{~mA}$ into a 600 -ohm load. The distortion suppressor is offered as a single or dual device, packaged in a 24 -pin, double-width DIP, fully shielded metal can. Its small size, low noise, low cost and exceptional performance qualify the AH201 for use in any digital-audio system.

## Features

## $\square$ Low Harmonic Distortion

 0.003\% (-90 dB), maximum■ Ultra-low Noise - - 115 dB

- Single-Channel (AH201-1) or Dual-Channel (AH201-2) Versions
- Time-Constant Limited Response Eliminates distortion due to slew-rate limiting
- Small Size - 24-pin DIP
- Single Control Line/Channel
- Optimized for D/A Deglitching


## Applications

- Professional Digital Recording Systems
- Satellite Downlinks
- Video Disc Audio
- Signal-Processing Systems
- Compact-Disc Systems


Figure 1. AH201-2 Functional Block Diagram

## SPECIFICATIONS

(All Specifications are guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## INPUT

## Input Voltage Range:

$\pm 10 \mathrm{~V}$
Input Voltage Without Damage:
$\pm 15 \mathrm{~V}$
Input Impedance:
5 kohms, $\pm 2 \%$

## OUTPUT

Output Voltage:
$\pm 10 \mathrm{~V}$
Load:
600 ohms, minimum
Protection:
Short circuit to ground
Output Impedance @ dc:
0.1 ohm, maximum

TRANSFER CHARACTERISTICS
Frequency Response
dc to $\mathbf{2 0} \mathbf{~ k H z}$ :
$0 \mathrm{~dB}, \pm 0.3 \mathrm{~dB}$ maximum
Time Constant':
$3.4 \mu \mathrm{~s}$, nominal
Settling Time:
Determined by time constant
Bandwidth (SAMPLE Mode):
46 kHz (Time-constant limited)
Gain ${ }^{2}$ :
-1, $\pm 0.02$, maximum
ACCURACY (AT $25^{\circ} \mathrm{C}$ )
Integral Nonlinearity:
$\pm 0.002 \%$ FSR, maximum
Noise ( $\mathbf{2 0} \mathbf{~ k H z}$ Bandwidth) ${ }^{3}$ :
$10 \mu \mathrm{~V} \mathrm{rms}$, maximum
Total Distortion:
Down by at least 90 dB for frequencies up to 20 kHz (including harmonic distortion)

## Peak Line Harmonic Distortion:

Down by at least 96 dB for frequencies up to 20 kHz
Output Offset Voltage (SAMPLE Mode) ${ }^{2}$ :
$\pm 12 \mathrm{mV}$, maximum
Feedthrough (HOLD Mode) ${ }^{5}$ :
Down by 96 dB minimum, 100 dB typical for $\pm 10 \mathrm{~V}$ sinewave up to 20 kHz
Power Supply Sensitivity Gain:
20 ppm FSR/V, maximum
Offset:
$20 \mu \mathrm{~V} / \mathrm{V}$, maximum

## Channel-to-Channel Crosstalk ${ }^{4}$ :

Down by at least 100 dB

DIGITAL CONTROL INPUT

## Logic Levels:

TTL compatible
SAMPLE Mode (Output Connected to Input): Logic $0 ; 0 \mathrm{~V}$ to 0.4 V , maximum
HOLD Mode (Output Disconnected from Input):
Logic $1 ;+2.4 \mathrm{~V}$, minimum to +5 V
POWER REQUIREMENTS (Exclusive of load)
+15V, $\pm 3 \%$ :
10 mA , maximum
(single channel, -1 )
20 mA , maximum
(dual channel, - 2 )
$-15 \mathrm{~V}, \pm 3 \%$ :
10 mA , maximum
(single channel, -1)
20 mA , maximum
(dual channel, -2 )

## ENVIRONMENTAL AND MECHANICAL

Operating Temperature Range:
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Storage Temperature Range:
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity:
0 to $85 \%$, noncondensing to $40^{\circ} \mathrm{C}$
Dimensions (Single or Dual Channel)
$1.305^{\prime \prime} \times 0.775^{\prime \prime} \times 0.3^{\prime \prime}$, maximum
( $20.07 \times 33.14 \times 7.62 \mathrm{~mm}$ )
24-pin double-width DIP
Pin Spacing:
$0.6^{\prime \prime} \times 0.1$ "
Packaging:
Metal can
Shielding:
Electromagnetic-6 sides
Electrostatic-6 sides

Note 1: Other time constants also available. Consult factory.
Note 2: From $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$.
Note 3: Measured at $50 \%$ duty cycle. $10 \mu \mathrm{~V}$ rms equals -115 dB referenced to rms full scale.
Note 4: Measured on one channel with its input grounded, with a $\pm 10 \mathrm{~V}$ sinewave of frequency up to 20 kHz applied to the input of the other channel; applies to dual-channel AH201-2 version only.
Note 5: Feedthrough specification given is for standard $3.4 \mu \mathrm{~s}$ time constant. Feedthrough performance will be different for time constants other than $3.4 \mu \mathrm{~s}$. Please consult factory.

## Theory of Operation

The operation of a single-channel $\mathrm{AH} 201-1$ is described. Each channel of the AH2O2-2 operates in a similar manner.
The AH201-1 consists of an inverting amplifier, a hold capacitor, and a pair of specially selected analog switches controlled by an external mode command. As shown in Figure 3, the mode is switched to minimize the effects of DAC nonlinearities on the output of the recovery system.
When the D/A output has settled to the value corresponding to the digital code at its input, the AH201 is commanded to the SAMPLE mode; shunt switch " A " opens and series switch "B" closes, connecting the settled D/A output to the output of the AH201. In this mode, the AH201's output response is exponential with the $3.4-\mu \mathrm{s}$ time constant.
The AH201 remains in the SAMPLE mode until just prior to the time when the D/A is updated to a new value, when it is commanded into the HOLD mode. The switch positions reverse, shunting the changing D/A output signal to ground. The previous output level, now stored on the capacitor, is maintained as the output of the AH201. The $96-\mathrm{dB}$, minimum, feedthrough rejection of the AH201 effectively isolates the output from the transients and other nonlinear settling characteristics of the D/A converter.
When the distortion suppressor is switched between its two modes, it passes signals up to 20 kHz without introducing significant distortion. For example, with the AH201 switching at 50 kHz , the peak line distortion for a full amplitude sinewave at 20 kHz is 96 dB down with respect to the full-scale level.

## USING THE AH201

## Grounding

The power return, analog input and output returns, and control return are all tied together internally and to the case. For convenience in pc-board layout, return pins for each function are located adjacent to the corresponding signal pins. To avoid ground loops, no connection should be made to the case ground pins 1,12 , and 15.
When using the AH201-1 single-channel version, it is necessary to connect pins 2 to 3 and 5 to 4 . In addition, no connection should be


Figure 2. System Improvement with AH201
made to pin 20. In both the single-channel AH201-1 and dual-channel AH201-2 versions, no connection should be made to pins $6,7,13$, $14,18,19$, or the case ground pins 1,12 , and 15.

## Control

One control line is provided for each channel of the AH201. A logic 0 selects the SAMPLE mode, connecting the output to the input; a logic 1 selects the HOLD mode, isolates the output from the input. Please refer to Figure 3 for typical timing information.


Figure 3. Typical Timing for a Single Channel System ( 44.1 kHz Sample Rate)

A time-constant limited response affects all input-voltage changes in the same proportion as long as the settling time allowed is constant. For this example, the on (SAMPLE) time
of $17 \mu \mathrm{~s}$ ( 5 time constants) results in a gain error of 0.1 dB . If required, this gain reduction can be corrected by the system gain adjustment.


Figure 4. Non-Simultaneous Updating of Multiple Audio Channels ( 15 kHz bandwidth per channel, 16 -bit resolution, 32 kHz sampling rate).

## TYPICAL APPLICATIONS

## Satellite Downlink Program Distribution

Multiple channels may be sequentially updated using one high-speed, high-accuracy D/A converter (such as the ANALOGIC MP1926A 16-bit Sign/Magnitude D/A) and multiple AH201s ( -1 or -2 ). For example, a satellite ground station used in a programchannel distribution system would be required to update multiple audio outputs, but not necessarily simultaneously. Figure 4 il-
lustrates one possible implementation using a single D/A converter to sequentially update four, $15-\mathrm{kHz}$ bandwidth, audio channels. A nominal $32-\mathrm{kHz}$ sample rate per channel is assumed. This means that the D/A converter must update four channels every $31.2 \mu \mathrm{~s}$ or one channel every $7.8 \mu \mathrm{~s}$, which is well within the settling capability of the MP1926A. The AH201 circuit in each channel is simply turned on (SAMPLE mode) for the last $6.8 \mu \mathrm{~s}$ of the corresponding MP1926A update period.


Mechanical \& Pinout

## ORDERING GUIDE

Single-Channel Distortion Suppressor...Specify AH201-1
Dual-Channel Distortion Suppressor...Specify AH201-2

## Stereo Program Distribution

Figure 5 illustrates the highest performance yet lowest cost method available for simultaneously updating stereo analog outputs, at rates up to 55 kHz from 16-bit resolution data ( 98 dB dynamic range). Conventional implementation requires two D/A converters plus digital double buffering to achieve simultaneous updating. The ANALOGIC MP1926A, with a voltage settling time of only $5 \mu \mathrm{~s}$ to 1 LSB for a 5V step, allows both channels to be updated from a single D/A converter within the $18 \mu \mathrm{~s}$ available. The only buffering required for simultaneous updating can be provided by an additonal AH2O1-2 configured as shown in Figure 5.
The timing diagram shows that the AH201 (Z1 in the Figure) samples the D/A output during a time slot assigned to Channel 1. It then holds this new Channel 1 level while the D/A output
settles to a new Channel 2 value. As a result of the AH201's 96 dB feedthrough rejection in the HOLD mode, the Channel 2 information signal has a negligible effect on Channel 1. When the inputs to the AH201-2 (Z2 in the Figure) have settled to the new levels, both channels are switched into the SAMPLE mode simultaneously, causing both channel outputs to be updated. It should be noted that the two channels will be 180 degrees out of phase due to the double inversion in Channel 1. To bring both channels in-phase, an AH201-2 can be substituted for the AH201-1 (Z1), and the control for its second channel can be hardwired in the SAMPLE mode, as shown in the inset of Figure 4; alternatively, the sign of the data for one of the channels can be inverted prior to being presented to the DAC inputs.


Figure 5. Simultaneous Updating of Stereo Audio Channels.


## ANALOGİ.

## MP221

Low Noise, Low Level Chopper Amplifier

## Description

The Analogic MP221 Chopper Amplifier provides unprecedented low level signal amplification for instrument and industrial applications in the microvolt-to-millivolt region. The MP221 design generates less than $0.1 \mu \mathrm{~V}$ p-p noise from dc to 1 Hz , less than $0.3 \mu \mathrm{~V}$ p-p from dc to 10 Hz , less than $1 \mu \mathrm{~V} p-\mathrm{p}$ from dc to 100 Hz , and less than 3 pA noise current from dc to 1 Hz . These superior specifications include flicker noise and Johnson noise components as well (See Figure 1). Moreover, the MP221 is virtually drift free with a maximum voltage drift of $0.05 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$, a maximum current drift of $2 \mathrm{pA} /{ }^{\circ} \mathrm{C}$, and a long term drift of $1 \mu \mathrm{~V} /$ month or $2 \mu \mathrm{~V} /$ year.

## Implementation

Optimized for non-inverting signal applications, the MP221 amplifier is normally soldered to a user's PC board. Gold-plated pins enhance solderability and conductivity. Amplifier gain is determined by selecting and connecting two resistors and a capacitor external to the MP221 as shown in Figure 1. Both resistors must possess an operational stability of $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or better to maintain the performance capability inherent in the MP221 advanced design. Thermal effects at the amplifier input terminals can be minimized by using low thermal solder and utilizing the installation precautions customary for low level signal circuits.

Current offset of the MP221 can be trimmed to zero by adjusting a built-in potentiometer. An external offset voltage adjustment may be incorprated as shown in Figure 4. When the MP221 is used in the noninverting mode, the offset voltage can be buffered from the input by using a voltage follower to avoid interaction with the gain components.

## Features

$<0.1 \mu \mathrm{~V}$ p-p
$<3$ pA p-p

- Low Drift
$<0.03 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ $<2 \mathrm{pA} /{ }^{\circ} \mathrm{C}$
- Gain Linearity within $\pm 0.002 \%$
- High Input Impedance $10^{9}$,
- Short-Circuit Protected


## Applications

Instrumentation, Load Cells, Thermocouples, Strain Gauges

- Measurement Preamplifiers

Low Level Buffers


Figure 1. MP221 Non-Inverting Pin Connections and Gain Resistor/Capacitor Calculations.
(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)
(Note: All performance at dc power of $\pm 15 \mathrm{~V}$, gain $=100, R_{1}=100 \Omega, R_{2}=10 \mathrm{k} \Omega$, and $C_{C O M P}=0.27 \mu \mathrm{~F}$.)

```
ANALOG INPUT
Noise Current ( 0 to 1 Hz )
3 pA p-p
Offset Voltage
\(\pm 2 \mu \mathrm{~V}\) typ., \(\pm 5 \mu \mathrm{~V}\) max. (ext. trim, Figure 4)
Bias Current (Non-Inverting)
\(\pm 20 \mathrm{pA}\) max. (trimmable to zero, Figure 3)
Bias Current (Inverting Mode)
\(\pm 2\) nA max.
Input Impedance
\(10^{9} \Omega\)
Common Mode Voltage
\(\pm 0.5 \mathrm{~V}\)
Commom Mode Rejection Ratio
140 dB
Maximum Input Without Damage \(\pm 20 \mathrm{~V}\)
```


## ANALOG OUTPUT <br> Voltage Range <br> $\pm 10 \mathrm{~V}$

Current
$\pm 3 \mathrm{~mA}$
Impedance at dc
$\pm 0.01 \Omega$
Load
$3 \mathrm{k} \Omega$ in parallel with $0.1 \mu \mathrm{~F}$ max.
Short-Circuit Protection
Output short-circuit protected ground
GAIN CHARACTERISTICS
Linearity
$\pm 0.002 \%$
Gain Range
10 to $10,000^{*}$
Open Loop Gain
160 dB
NOISE BANDWIDTH
dc to 1 Hz
$<0.1 \mu \mathrm{~V}$ p-p
dc to 10 Hz
$<0.3 \mu \mathrm{~V}$ p-p
dc to 100 Hz
$<1 \mu \mathrm{~V}$ p-p

## STABILITY

Tempco of Offset Voltage
$0.03 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typ., $0.05 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.
Tempco of Bias Current $2 \mathrm{pA} /{ }^{\circ} \mathrm{C}$ max.
Power Supply Sensitivity
$0.01 \mu \mathrm{~V} / 1 \%$ power supply change
Warmup Drift
To within $2 \mu \mathrm{~V}$ of final value in 2 minutes

## Long Term Drift

$1 \mu \mathrm{~V} /$ month, $2 \mu \mathrm{~V} /$ year
Thérmal Step Offset Recovery
5 minutes for $25^{\circ} \mathrm{C}$ step
Offset Resulting from ac Input
$1 \mu \mathrm{~V}$ for 4 mV p-p 60 Hz
Overlaod Recovery Time
200 ms to within $2 \mu \mathrm{~V}$ for $10 \times$ FSR input

## FREQUENCY RESPONSE

## Bandwidth

-3 dB at 100 Hz
Settling Time to $0.002 \%$ FS
(50 + 8Vsw)ms; Vsw = Output voltage swing Slew Rate
130 V/s

## POWER REQUIREMENTS

## $\pm 15 \mathrm{~V}$

2.5 mA plus load current

## ENVIRONMENTAL \& MECHANICAL

OPERATING TEMPERATURE
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Non-Operating Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $95 \%$, non-condensing
Shielding Protection
RFI 6 sides; EMI 5 sides
Dimensions
$2 \times 1 \times 0.39$ " Modupac ${ }^{\text {TM }}(50.8 \times 25.4 \times 9.91 \mathrm{~mm})$

[^0]
## Application Information

The Analogic MP221 Low Level Chopper Amplifier is designed to perform in the microvolt-to-millivolt signal range for instrument and industrial applications. This amplifier has been optimized for operation in the non-inverting mode so that gains from 10 to 10,000 can be achieved with minimum loading of the signal source. Because of its unique features, which include low noise, low thermal offset drift, and low bias current, the MP221 is ideally suited for use as a preamplifier with load cells, thermocouples, and other low level transducers. However, to obtain a level of performance consistent with the superior specifications of the MP221, some usage guidelines must be exercised. This application note provides several recommended techniques for operating the MP221 with low level input signals.

## Amplifier Operation

The MP221 amplifier has a chopper input that effectively samples the voltage difference between its plus (+) and minus ( - ) inputs. A circuit employing this amplifier should be considered a "sampled data" system, and proper attention must be paid to the generated errors. The most important error is unwanted signals or noise appearing at the amplifier output, which can be attributed to aliasing or intermodulation distortion. These effects can be reduced by
filtering the amplifier input and by choosing an optimum chopper frequency. Since most systems are subject to noise pickup at the line frequency and its harmonics, the MP221 has been set to sample at 925 Hz , which is 25 Hz removed from the nearest 60 Hz or 50 Hz harmonic. These harmonic components at the amplifier input are translated to 25 Hz at the output. Because most A/D converters can respond at this speed, post filtering is often necessary.

## Low Noise Techniques

For low noise operation, it is recommended that low-pass filtering be used before and after the amplifier. (See Figure 2). Because most active-type filters generate noise within the amplifier bandwidth, the pre-filter should be composed of passive components. Noise injected after the amplifier is less critical, and for that reason, a threepole active-type low pass filter can be used as a post-filter. The component values shown in Figure 2 are effective for 2 Hz filtering.
Another consideration is to limit the bandwidth of the MP221 to that required in the system. Because the output noise generated by the amplifier varies as the square root of the bandwidth, there is 10 times more noise at a 100 Hz bandwidth than at 1.0 Hz bandwidth. The output capacitor ( $\mathrm{C}_{\text {comp }}$ ) shown in Figure 2 sets the bandwidth for a given gain. The $\mathrm{C}_{\text {comp }}$


Figure 2. Recommended Filtering of MP221.


Figure 3. Switching Spikes vs. Input Source Impedance.
recommended value of (30/Gain) $\mu \mathrm{F}$ is for a 100 Hz bandwidth and bandwidth decreases proportionally as $\mathrm{C}_{\text {comp }}$ is increased. For example, at a gain of 100, a 3 $\mu \mathrm{F} \mathrm{C}_{\text {comp }}$ sets a bandwidth of 10 Hz . The parameters of the pre- and post-filters should also be set to obtain only the needed bandwidth. An additional source of noise appearing at the amplifier output is due to internal chopper switching transients. The magnitude of this noise depends upon the input resistances, primarily that between the minus ( - ) terminal and common. Figure 3 illustrates this dependence and also shows the reduction of this noise as $\mathrm{C}_{\text {comp }}$ is increased. Reduction of this noise is another reason why a post-filter is recommended.

For the stated reasons and because of the unavoidable Johnson noise effects, the resistors associated with the MP221 amplifier should be as low in magnitude as practical (a limitation being the current available to generate the output voltage levels). A maximum of $1 \mathrm{k} \Omega$ from the minus $(-)$ input to ground is recommended. Because carbon composition and some film resistors generate noise in excess of Johnson noise, only stable wirewound resistors or known low noise film resistors should be used.

The signal input wiring should be shielded to reduce pickup; a shielded-twisted pair is recommended.

The amplifier power supply inputs are decoupled internally, so that in most applications, external capacitors are not required.

## Thermal Offset Techniques

If noise could be reduced to that of the source (theoretical minimum), thermal offset voltages would still appear when amplifying microvolt input signals. These thermal offsets are caused by joining dissimilar metals and by existing temperature gradients across the input circuit. For example, a thermocouple of copper and lead/tin solder can generate an offset voltage of 0.3 $\mu \mathrm{V}$ for $0.1^{\circ} \mathrm{C}$ temperature difference between the metals. Since this temperature gradient varies with time, the thermal offset appears similar to low frequency noise or "wandering". The techniques used to minimize these thermal offsets are: (1) keep signal high and low input connections physically close to reduce temperature differences, (2) shield connections from all convection air currents (breezes), (3) heat sink the input connections tightly, and (4) only join similar metals (copper) using low thermal solder (cadmium/tin). When operating at the microvolt (or below) level, all four techniques may be required. If all copper connections are made at the MP221 input terminals using low thermal solder and the amplifier is wrapped in polyurethane foam, then the total thermal offset wandering should be less than $0.1 \mu \mathrm{~V}$.

## Bias Current Adjustment

Another low level error is caused by bias current flowing through the external source resistance, thereby generating offset voltages. These voltages can be balanced externally but they are temperature dependent. An adjustment is provided on the MP221 so that the bias current at either input can be set to zero. However, since the currents at the inputs are not equal, only one input can be compensated, leaving a residual bias current at the other input.


Figure 4. MP221 Amplification of the
Thermocouple Low Level Output and
Figure 4. MP221 Amplification of the
Thermocouple Low Level Output and Illustrating External Offset.

When an MP221 is used in the recommended positive gain configuration, the positive input bias current can be adjusted to zero with the negative input bias current remaining less than $\pm 2 \mathrm{nA}$. If the resistor connected to the negative input is less than 1 $k \Omega$ (R1, Figure 2), the offset voltage due to the $\pm 2 \mathrm{nA}$ should be only $\pm 2 \mu \mathrm{~V}$ (referred to the input). This value is much less than the offset voltage specification of the amplifier ( $\pm 5 \mu \mathrm{~V}$ maximum).


Figure 6. Mechanical \& Pinout.

## ORDERING GUIDE

Low Noise, Low Level Chopper Amplifier
Specify MP221.


Isolation Amplifier

## Description

The Analogic MP227A is a precision isolation amplifier that provides an unparalleled combination of linearity, stability, isolation, and very low cost. It is designed primarily to replace relays and filter elements in multichannel data acquisition systems. However, its unique features make it attractive wherever low-level, low frequency signals must be amplified in the presence of severe common mode interference.
The MP227A offers user-selectable gains from 10 to 1000, input fullscale voltage ranges from $\pm 10 \mathrm{mV}$ to $\pm 1 \mathrm{~V}$, 3-pole ( $60 \mathrm{~dB} /$ decade) filtering from 5 Hz , extremely good linearity, superb common-mode rejection, and very low drift. All parameters are commensurate with A/D conversion at levels up to 13 bits.
The MP227A includes an internal power oscillator and isolated supply so that no external drivers are needed. The isolated power $( \pm 4 \mathrm{~V}$ nominal) can be used for open thermocouple indication or offsetting strain gauge inputs.

## Features

- High Common Mode Rejection 170 dB
- Excellent Linearity 0.0075\%
- Selectable Input Range $\pm 10 \mathrm{mV}$ FS to $\pm 1 \mathrm{~V}$ FS


## $\square$ Low Noise

$<0.5 \mu \mathrm{~V}$ rms

- Low Drift
$3.0 \mu \mathrm{~V}$ RTI per month
- Built-in 3-pole Filtering
- Built-in Oscillator/Driver


## Applications

## - Thermocouple Temperature Measurement

- Weighing Systems
- Strain Gauge Measurements
- Remote Data Acquisition and Precision Telemetry Systems
- Microvolt and Millivolt Level Measurements
- Replacement for Classical Instrumentation Amplifier


Figure 1. MP227A Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG INPUT

## Gain Range

10 to 1000, non-inverting, resistor programmable; optimized for gains of 50 to 500

## Non-linearity

$\pm 0.0075 \%$ FSR maximum at $\mathrm{G}=50$ to 500 ;
$\pm 0.01 \%$ FSR maximum at $G=1000$;
$\pm 0.05 \%$ FSR maximum at $G=10$
Input Amplifier Type
Isolated Chopper
Linear Differential Input Voltage Range $\pm 10 \mathrm{mV}$ to $\pm 1 \mathrm{~V}$ full scale
Maximum Safe Differential Input Voltage
16 V rms continuous, without damage
Common Mode Isolation Voltage
1000 Vdc, 750 V rms, maximum
Common Mode Rejection Ratio
At dc, with $\mathrm{G}=100$ and 1000, 166 dB minimum;
$1 \mathrm{k} \Omega$ source unbalance
At 60 Hz , with $\mathrm{G}=100$ and $1000,176 \mathrm{~dB}$ typical, 160 dB minimum; $1 \mathrm{k} \Omega$ source unbalance

## Common Mode Impedance

10,000 M $\Omega$ / / 80 pF
Differential Input Impedance
At dc, $12 \mathrm{M} \Omega$; at ac, low-pass filter of $22 \mathrm{k} \Omega$ and $1.5 \mu \mathrm{~F}$
Overload Input Impedance
$22 \mathrm{k} \Omega$, at $50 / 60 \mathrm{~Hz}$
Input Bias Current
0.5 nA typical, 3.0 nA maximum; bias current increases if open input indicator circuit is used

## Offset Voltage

At $G=10, \pm 1 \mathrm{mV}$ typical, $\pm 5 \mathrm{mV}$ maximum; at $\mathrm{G}=1000, \pm 150 \mu \mathrm{~V}$ maximum; all referred to input (RTI); offset voltage may be determined by interpolation for other gain values
Voltage Noise ( 0.01 to 5 Hz )
At $\mathrm{G}=10,1.5 \mu \mathrm{~V}$ rms maximum; at $\mathrm{G}=100$ and 1000, $0.5 \mu \mathrm{~V}$ rms maximum; RTI
Bandwidth (See Note 1)
dc to 5 Hz nominal; 6 dB down at 5 Hz
Overall Filtering (See Note 2)
3-pole, $60 \mathrm{~dB} /$ decade roll-off ( -60 dB at 50 Hz ) Input Filter
1-pole RC, 3 dB cut-off at 5 Hz
Output Filter
2-pole Butterworth, 3 dB cut-off at 5 Hz

## ANALOG OUTPUT

Voltage Range
$\pm 10 \mathrm{~V}$ full scale
Output Impedance at dc
$0.1 \Omega$
Maximum Load
$\pm 5 \mathrm{~mA}$ and 500 pF

## Output Protection

Continuous short circuit to ground

## Output Chopper Noise ( 1 MHz BW)

$\pm 1 \mathrm{mV}$ p-p spike at approximately 10 kHz (See Note 3)

## STABILITY

Gain Tempco
At $\mathrm{G}=10$ and $100, \pm 25 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ maximum; at $G=1000, \pm 35 \mathrm{ppm} F S R /{ }^{\circ} \mathrm{C}$ maximum; exclusive of external gain setting resistor
Offset Voltage Tempco
At $\mathrm{G}=10, \pm 5.0 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum;
At $\mathrm{G}=100, \pm 1.7 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum;
At $\mathrm{G}=1000, \pm 0.5 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum;
all RTI
Bias Current Tempco
$100 \mathrm{pA} /{ }^{\circ} \mathrm{C}$ maximum, at $25^{\circ} \mathrm{C}$; doubles every $10^{\circ} \mathrm{C}$ (maximum)

## Power Supply Sensitivity

At $G=1000, \pm 2.0 \mu \mathrm{~V} / \%$; at $\mathrm{G}=10, \pm 10 \mu \mathrm{~V} / \%$ maximum; RTI
Warm up Drift (5 Minutes)
Within $2 \mu \mathrm{~V}$ RTI typical at $\mathrm{G}=1000$
Long Term Drift
$3.0 \mu \mathrm{~V} \mathrm{RTI} /$ month typical

## ISOLATED POWER SUPPLY OUTPUT

## Voltage

$\pm 4$ Vdc nominal, with respect to INPUT LO
Current
$\pm 3 \mathrm{~mA}$ full load

## Regulation

$12 \%$, no load to full load
Ripple
60 mV p-p at 10 kHz
INPUT POWER SUPPLY REQUIREMENTS
$+15 \mathrm{~V}, \pm 3 \%$
3 mA , no load
$-15 \mathrm{~V}, \pm 3 \%$
5 mA , no load
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature Range
$-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$

## Dimensions

$1.2^{\prime \prime} \times 2.8^{\prime \prime} \times 0.5^{\prime \prime}(30 \times 70 \times 12 \mathrm{~mm})$
Shielding
RFI: 6 sides; EMI: 5 sides

## NOTES:

1. Modifications for bandwidths from dc to 100 Hz , or optimized for specific settling times are available on special order. Please contact factory.
2. Filter nodes are externally accessible to allow modification of characteristics.
3. Output Chopper noise can be reduced to negligible level by suggested output multiplexer circuit.

## OPERATION DATA

## Application

The MP227A was designed as an economically competitive and functionally superior alternative to the relay multiplexing circuits traditionally used in multichannel data acquisition systems. In a typical thermocouple system, the MP227A replaces two functional blocks for each channel - the input filter and a dual relay, as well as the common channel high gain amplifier - and permits high-level, solidstate multiplexing to be used for low cost and high reliability.
The MP227A provides significantly better isolation and common-mode rejection than low-level relays and it puts the gain at a point in the system where the bandwidth is lowest (prior to multiplexing), thereby reducing total system noise. Even where multiplexing is not used, the unusual combination of performance and price makes the MP227A attractive for a wide variety of industrial applications.
When many MP227A's are used in a system, a high speed, high level analog multiplexer switches the MP227A outputs to a common analog output bus for subsequent A/D conversion. Any high precision isolation amplifier/filter used in such a configuration has an inherent error source of sizable magnitude that is often overlooked, ignored or simply unknown, that is, dumped charge effects. This Application Note discusses the problem, the solution, and the fringe benefits.

## Dumped Charge

Figure 2 shows the apparently straightforward connection of multiple amplifiers/filters and multiplexer to a common A/D converter.


Figure 2. Multiplexing Amplifier Outputs.
Each time the multiplexer in Figure 2 switches channels, for instance, from Channel 1 to Channel 2, the Channel 1 output appears across C 2 , the capacitance of the output bus. The output stage of Channel 2 must absorb that dumped charge before it can reach a true final value dependent only on its input. The exact magnitude of the dumped charge is not important: what is significant is that the Channel 2 amplifier may be forced to deliver a peak instantaneous current beyond its design specifications.
The dumped charge ( $Q$ ) is defined as, Q = idt,
where $\mathbf{i}=C \mathrm{dv} / \mathrm{dt}$
In a typical example, the outputs of the two channels could be at the extreme ends of the range.
Channel 1 output $=+10 \mathrm{~V}$.
Channel 2 output $=-10 \mathrm{~V}$.
This makes the voltage difference (dv).
$\mathrm{dv}=20$ volts.
Assume that the capacitance of the output bus C2 is about 500 pF , and a reasonable turn-on time for an analog switch is 100 ns , or,
$C=500\left(10^{12}\right)$
$\mathrm{dt}=100\left(10^{9}\right)$
Solving first for the current and then the dumped charge, gives:

$$
\begin{aligned}
& i=C(\mathrm{dv} / \mathrm{dt})=\frac{500\left(10^{12}\right)}{100\left(10^{9}\right)} 20=100 \mathrm{~mA} \\
& Q=\mathrm{idt}=(100)\left(10^{3}\right)(100)\left(10^{9}\right)=10,000 \\
& \text { pico Coulomb }
\end{aligned}
$$

Under these conditions, IC op amps, such as the popular 741, have been found to have full-scale current excursion lasting as long as a microsecond.
If the design factors allow a conventional IC output stage to drive the multiplexer instead of a high precision amplifier with an output/filter stage, no real harm is done by the dumped charge. The amplifier eventually recovers and C2 charges to the new value. The recovery time constant is the ON resistance of the multiplexer switch and C2
for $R$ on $=300 \Omega$
$\mathrm{C} 2=500 \mathrm{pF}$
$T=(300)(500) 10^{12}=0.15 \mu \mathrm{~s}$
In high resolution systems, 10 time constants should be allowed to reach a voltage within $0.005 \%$ of final value. Therefore, the actual time should be $1.5 \mu \mathrm{~s}$.
The $1.5 \mu \mathrm{~s}$ settling time required in this example is usually less than the settling time of the conventional buffer amplifier at the multiplexer output and the dumped charge effect can be safely ignored. The dumped charge cannot be ignored, however, when high precision amplifiers employing output filters are required.

## The Problem

Many isolation and/or instrumentation
amplifiers do not include an output filter. On the other hand, the MP227A has an integral two-pole Butterworth filter in the output stage. The feedback element of the MP227A is a capacitor and a sudden voltage step at the amplifier output, such as the dumped charge, presents a problem.
The dumped charge demands excessive current in too short a time and causes the amplifier to momentarily open-loop. The summing node changes to a large voltage, inducing current flow in the input resistor and causing an extraneous charge on the feedback capacitor.
This error source has produced observed errors as large as $0.05 \%$ in typical applications.

## The Solution

Figure 4 shows the addition of a single-pole filter (R1, C1) at the output of each MP227A and ahead of the multiplexer. C1 of the succeeding channel, now absorbs the charge accumulated on C2 from the preceding channel. The MP227A no longer sees a step but a well controlled exponential change, well within its capabilities. Hence, the output stage in the MP227A does not openloop, and no spurious charge is placed on the feedback capacitor.


Figure 3. MP227A Isolation Amplifier Functional Block Diagram.


Figure 4. MP227A with Output Filters Added.
The best results are obtained with a time constant between 0.25 and $0.5 \mu \mathrm{~s}$. This must be short for two reasons: 1) a settling time of up to 10RC does not significantly add to multiplexer settling time and 2) the recovery time is sufficiently short for final values that are independent of the duty cycle involved in reading a channel.
R1 should be between 50 and 270 : this value is kept intentionally low to reduce voltage divider error ( $\mathrm{R} 1+\mathrm{R}_{\text {on }}$ relative to $\mathrm{R}_{\text {in }}$ of the follower at the mulitiplexer output) to an insignificant level. These values of R1 yield values for C 1 between $10,000 \mathrm{pF}$ and $1,000 \mathrm{pF}$ which is an acceptable range for C 1 . In the capacitive voltage divider, formed by C1 and the bus capacitance C 2 , as C 1 decreases in size relative to C2, the initial voltage transferred to C1 by a succeeding channel approaches its final value and leaves a smaller exponential rise portion.
R1, C1 MUST BE INCLUDED FOR ALL HIGH RESOLUTION (>12 BITS) APPLICATIONS OF THE MP227A.

## Fringe Benefits

Noise spikes inherent in the design of high performance isolation amplifiers are attenuated by 10 dB or more by the R1 C1 output filter.
The superior isolation of the MP227A is provided by transformer coupling. A modulator/demodulator is used in the analog signal path and is driven by an integral chopper/power driver. It is impossible to avoid some stray capacitance between the driver circuitry and the output. Careful design and layout of the MP227A has reduced the resulting output noise spikes caused
by stray capacitance to $1 \mathrm{mVp}-\mathrm{p}$, which is $0.01 \%$ relative to 10 V F.S., when measured over a bandwidth of 1 MHz . The noise spikes repeat at 20 kHz , or twice the nominal 10 kHz frequency of the MP227A chopper driver.
If the output filter time constant (R1 C1) is equal to $0.5 \mu \mathrm{~s}$, then
$\mathrm{fc}=1 / 2 \pi \mathrm{RC}$
$=333 \mathrm{kHz}$
This low cut-off frequency ensures that the output spikes, over an effective bandwidth in excess of 1 MHz , are attenuated 10 dB or more, which is enough to reduce this error source from $.01 \%$ to a negligible level.

## USING THE MP277A <br> Offset Adjustment

Provision is made for external offset adjustment on the MP227A Precision Isolation Amplifier by connecting a 25 k or $50 \mathrm{k} \Omega$ ( $100 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or better) multi-turn potentiometer (R2) with a $1 \mathrm{M} \Omega$ resistor as shown in Figure 2. To adjust, momentarily short INPUT HI, INPUT LO, and AZ RTN to the output ANA RTN and set the offset potentiometer for zero output at the OUTPUT terminal.

## Setting the MP227A Gain

The gain of the MP227A may be set to any value from 10 to 1000 by connecting an external resistor $\left(R_{G}\right)$ between the GAIN and INPUT LO terminals as shown in Figure 2. Gain is equal to:

Gain $=\frac{10.27 \times 10^{3}}{R_{G} \Omega}$
An RN55E or better resistor is recommended for temperature stability. Untrimmed, the absolute gain will be within $+2 \%$ and $-3 \%$ of the calculated value.

## Gain Trimming

The gain may be deliberately fine-trimmed, if desired, by connecting a $500 \Omega$ ( $100 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or better) potentiometer (R1) between the FEEDBACK and OUTPUT terminals as shown in Figure 2. R1 compensates for the tolerance of $\mathrm{R}_{\mathrm{G}}$ plus the unit-to-unit gain variability (3\%) between multiple MP227As. This also allows standardization of the outputs of multiple MP227As to a common full-scale range. For volume production where cost is a factor, the trimpot may be replaced with a fixed resistor selected during final testing.

## Auto-Zero Return

The signal that is amplified by the MP227A is actually the difference between the INPUT LO and the Auto-Zero (AZ) voltages. For normal operation, tie the AZ terminal directly to the INPUT LO terminal. In some applications, it may be convenient to offset the input deliberately by an amount that exceeds the range of the OFFSET trimpot (for example, to obtain expanded scale operation or to cancel out the initial or "tare" output of a load cell). To do this, connect the AZ terminal to a source of voltage equal to the desired offset, with noise performance and stability at least as good as the signal source.
Observe that both the INPUT HI signal and the AZ signal (if any) are measured with respect to the INPUT LO terminal. For best linearity, each signal must be within $\pm 1 \mathrm{~V}$ of INPUT LO.

## Open Input Indication

The user-accessible isolated power supply voltages make it possible to use a simple open input indication network. Connect a resistor on the order of $180 \mathrm{M} \Omega$ to the INPUT HI and either the +4 V or -4 V isolated power output terminal. This network produces a bleeder current of approximately 20 nA through the input source circuitry. If the source should open, this bleeder current will drive the MP227A output into a saturated state. The speed of this response is a function of the MP227A gain setting and input time constant.

## Multiplexing MP227As

The outputs of multiple MP227As may be multiplexed to a common analog line as indicated in Figure 4. A single RC filter ahead of each MUX input is suggested.


Figure 5. Typical External Connections-MP227A.


Figure 6. MP227A Mechanical \& Pinout.

ORDERING GUIDE
Specify MP227A
Selection Guide. ..... 3-2
Glossary ..... 3-3
MP260 $3 \mu \mathrm{~s}, 0.002 \%$ Linearity S/H (Optimized for Simultaneity) ..... 3-5
MP2615 $\mu \mathrm{s}, 0.002 \%$ Linearity, Low Droop S/H ..... 3-5
MP270 $1 \mu \mathrm{~s}, 0.005 \%$ Linearity S/H ..... 3-11
MP271 $1 \mu \mathrm{~s}, 0.003 \%$ Linearity S/H ..... 3-15
MP272 350 ns, $0.01 \%$ Linearity S/H ..... 3-21
MP282A Dual Simultaneous S/H with 1-bit Gain Ranging ..... 3-27

## SECTION 3

## Sample-and-Hold Amplifiers

SELECTION GUIDE

| MAJOR CHARACTERISTIC <br> OR APPLICATION REQ'MT | PRIMARY <br> PARAMETER | SECONDARY <br> PARAMETER | RECOMMENDED <br> MODEL NO. | DATA SHEET <br> ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| Simultaneous <br> Multi-Channel <br> Sampling | Acquisition <br> Time | MP260 | $3-5$ |  |
|  |  | - | MP261 | $3-5$ |
| Multiple, Multiplexed <br> Inputs/Single <br> S/H | Acquisition <br> Time | High Linearity | MP270 | $3-11$ |
|  | Linearity | MP271 | $3-15$ |  |
|  | Acquisition <br> Time | Medium <br> Linearity | MP272 | $3-27$ |

## GLOSSARY OF TERMS

## SAMPLE AND HOLD AMPLIFIERS

ACQUISITION TIME The time it takes the S/H amplifier to start tracking the input signal. It is measured as the maximum elapse time between application of the sample command and the point at which the output starts to track the input within a specified accuracy regardless of the previous state of the output or the magnitude or polarity of the input. See Figure 1.
APERTURE DELAY TIME The time delay between the HOLD command and the actual start of the HOLD mode. In reference to the SAMPLE mode this is called the turn-off time. See Figure 1.
APERTURE UNCERTAINTY A specification indicating how much the aperture delay time varies. It is measured as the difference between the maximum turn-off time and the minimum turn-off time. See Figure 1.

$$
\Delta E=E_{s} K \log _{10}\left(\frac{t_{s}+t_{h}}{t_{s}}\right)
$$

where:
$\triangle E=$ Output voltage error
$\mathrm{E}_{\mathrm{S}}=$ Capacitor voltage change
$\mathrm{K}=$ Empirical constant for Hold capacitor dielectric ( $K=1.5 \times 10^{4}$ for polystyrene capacitor in MP270)
$\mathrm{t}_{\mathrm{s}}=$ Sample time; $\mathrm{t}_{\mathrm{h}}=$ Hold time
Example: For a 20 V step, a Sample time of $2 \mu \mathrm{~s}$, and a Hold time of $5 \mu \mathrm{~s}, \triangle \mathrm{E}=1.5 \mathrm{mV}$.

DIGITAL CONTROL SPECIFICATIONS These are specifications for interfacing the digital control signals to the S/H and include: the logic type, e.g., TTL; the sense of the logic, e.g., $1=$ SAMPLE, $0=$ HOLD; and the required speed of the rise or fall time between SAMPLE and HOLD modes.

DISTORTION Unwanted output signals generated as a result of non-linearities in the sample and hold.


Figure 1. S/H Amplifier Terminology.

DIELECTRIC ABSORPTION ERROR Dielectric absorption error is the decaying of the HOLD voltage on the HOLD capacitor due to the charge redistribution within the capacitor dielectric. This error occurs as a result of rapidly charging the HOLD capacitor and then disconnecting the charging source. The output voltage will decay according to the following relationship:

DROOP RATE The maximum rate of change of the output voltage in the HOLD mode.
FEEDTHROUGH REJECTION The ratio, in db , of a specified input signal to the resultant output signal, during HOLD, over a stated frequency range.

FULL POWER BANDWIDTH The highest frequency at which an analog circuit will track a sinusoidal signal large enough to drive
the output to its rated full-scale value at its maximum rated power. The equation is as follows:

$$
f=\text { Slew Rate } / 2 \pi \mathrm{e}_{\mathrm{fs}}
$$

where $f=$ Full Power Bandwidth and $e_{f s}=$ rated full scale output.

GAIN ACCURACY The maximum amount that the actual voltage gain deviates from the nominal value expressed as a percentage of that nominal value. This takes into account the effects of temperature variations, power supply variations, and drift with time, if significant.

INPUT IMPEDANCE Specified as a nominal resistance in parallel with a capacitance value, given for the SAMPLE mode. If the HOLD mode impedance is significantly different it will also be given. Input impedance is given at maximum rated input voltage.
INPUT SIGNAL RANGE The acceptable input signal levels, over the full power bandwidth, for which the S/H will maintain rated linearity.
LINEARITY In the sample mode, linearity is a measure of how accurately the output tracks the analog input signal. In the hold mode, it refers to the pedestal offset which varies over the input signal range.
OFFSET DRIFT The worst case variation in output offset voltage due to changes in ambient temperature, power supply voltage, and drift with time.
OUTPUT OFFSET VOLTAGE The maximum value of output voltage observed when sampling zero input at a stated temperature and power supply voltage.
OUTPUT VOLTAGE SWING The rated nominal output voltage range into a specified minimum load impedance.
OVERLOAD RECOVERY TIME The time required for the circuit to return to linear operation, within a stated tolerance, after removal of a sustained input that was large enough to drive the circuit into complete saturation (i.e., a condition in which further increase in the input did not significantly increase the output).

PEDESTAL OFFSET ERROR An offset error caused by switching to the HOLD mode. It is affected by a number of parameters including the capacitance of the mode con-
trol switch, the HOLD mode command signal level, the analog input signal level and the sample rate. The pedestal offset error may be nonlinear.
SAMPLE AND HOLD AMPLIFIER Sometimes called a track and hold amplifier, this is a circuit used to monitor a rapidly changing analog signal and, upon command, hold that signal level for processing by another circuit, typically an ADC. The S/H operates in two sequential modes, SAMPLE and HOLD, as determined by the state of a switch at the input to the amplifier which is controlled by an external digital control signal. In the SAMPLE mode the switch is closed, the input signal is connected to the amplifier and the output tracks it very closely. In the HOLD mode the switch is open, the input is disconnected from the amplifier and its level at the time of disconnect is maintained by a capacitor across the input. See Figure 2.


Figure 2. S/H Amplifier Block Diagram.
SETTLING TIME The maximum time required for the output to track the input to within the specified accuracy after a full range step change while in the SAMPLE mode.

SLEW RATE The maximum slew rate is the fastest rate of change of the output of the amplifier in the SAMPLE mode. The output changes most rapidly when a step change is applied at the input sufficient to drive the output from one end of its range to the other.

SMALL SIGNAL BANDWIDTH The maximum small signal bandwidth is the highest frequency at which an amplifier will track, to within 3 db of the low frequency response, a sinusoidal signal of less than the slew rate limited amplitude.
TURN OFF TIME See aperture delay time.
VOLTAGE GAIN The nominal ratio of output to input.


## ANMLOGIO.

MP260/MP261
Low Cost High Speed High Accuracy Sample \& Hold Amplifiers

## Description

The Analogic MP260 and MP261 are low cost, highly accurate Sample-and-Hold (S/H) Amplifiers that sustain precise over-all system performance in applications requiring resolutions of up to 16 -bits. The MP260 design is optimized for a time-shared $\mathrm{S} / \mathrm{H}$ function at the input of a high speed ( $50 \mu \mathrm{~s}$ or faster conversion time) analog-to-digital converter. Its fast acquisition time of $5 \mu \mathrm{~s}$ and excellent linearity of $0.002 \%$ are representative of its superior performance. The MP261, with its extremely low droop rate of only $20 \mu \mathrm{~V} / \mathrm{ms}$, is ideal for simultaneous sample-and-hold applications. For example, as many as 500 channels may be held and sequentially sampled (at 16-bit resolution, $30 \mu \mathrm{~s} /$ sample, $\pm 10 \mathrm{~V}$ full scale) before the last channel has drooped by only one significant bit $(300 \mu \mathrm{~V})$ ! The rated performance of these units is maintained in the presence of harsh electromagnetic and electrostatic interference by shielding all components, including the low dielectric absorption hold capacitor, within a 1" x 2 " Modupac ${ }^{\text {TM }}$ metal case.


Figure 1. MP260/MP261 Block Diagram.

## Features

## MP260/MP261

- Excellent Linearity $\pm 0.002 \%$ FSR maximum
- Negligible Feedthrough 100 dB Rejection (0.001\%)


## ■ Low Aperture Uncertainty

 1 nanosecond- Complete Small Size Module 1" x 2" Modupac ${ }^{\text {TM }}$ Case
- User-Selectable Input Configurations Buffer or Inverter
- Very Low Cost


## MP260

Optimized for Time-Shared S/H Applications

- Fast Acquisition time
$5 \mu \mathrm{~s}$ to $\pm 0.003 \%$ Full Scale Step
- Low Pedestal Non-Linearity $\pm 0.003 \%$ max.


## MP261

Optimized for Simultaneous S/H Applications

- Very Low Droop rate
$20 \mu \mathrm{~V} / \mathrm{rms}$ max.
- Very Low Pedestal NonLinearity $\pm 0.002 \%$ max.


## Applications

Low-Cost Simultaneous Sample \& Hold Systems

- Automatic Test Equipment Systems
- Multi-Channel, Multi-InputLevel, 12- to 16-bit Data Acquisition Systems
- High Resolution, High Speed Data Acquisition Systems
Audio Digitizing Systems.

SPECIFICATIONS
(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

```
SAMPLE MODE
(Input configured for Unity Gain Buffer)
Full Scale Linear Input Voltage Range (FSR)
\pm10V
Without Damage
\pm15V
Input Impedance
10}\Omega||10 p
Full Power Bandwidth
80 kHz, (MP261 - 20 kHz)
Small Signal Bandwidth
1 MHz, (MP261 - 150 kHz)
Slew Rate
10 V/\mus, (MP261 - 2 V/ / s)
Non-Linearity
\pm0.002% (max.)
Noise (300 kHz bandwidth)
40 \muV rms
Gain
1 }\pm0.02
Total Harmonic Distortion (20-20 kHz sinusoid
input)
0.002% max.
```


## SAMPLE-TO-HOLD TRANSITION

## Aperture Delay Time

50 ns
Aperture Uncertainty
1 ns
Switching Transient Decay Time to 0.003\% $0.5 \mu \mathrm{~s}$ typ., $1 \mu \mathrm{~s}$ max.

## HOLD MODE

Voltage Swing into $2 \mathrm{~K} \Omega$ \| 500 pF load)
$\pm 10 \mathrm{~V}$ min.
Impedance
$<18$ @ dc

## Hold Offset Pedestal

10 mV max; Proportional to input, (MP261 5 mV max; Constant for all input signals
Offset Pedestal Non-Linearity ( $\pm$ 5V FSR) $\pm 0.001 \%$ max.
Offset Pedestal Non-Linearity ( $\pm 10 \mathrm{~V}$ FSR) $\pm 0.003 \%$ max., (MP261 - $\pm 0.002 \%$ max.)
Offset @ $25^{\circ} \mathrm{C}$ (Externally Adjustable to Zero)
10 mV max., (MP261 - 5 mV max.)
Offset Tempco
(20 typ., 0.2 max. $\mu \mathrm{V} / \mu \mathrm{s}$, (MP261 - (5 typ., 15 max.) $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$
Voltage Feedthrough Attenuation
( 20 V p-p 100 kHz input)
100 dB typ., 96 dB min.
Droop Rate @ $25^{\circ} \mathrm{C}$ (typically doubles every $14{ }^{\circ} \mathrm{C}$ )
0.02 typ., 0.2 max. $\mu \mathrm{V} / \mu \mathrm{s}$, (MP261 - 1 typ., 20 max. $\mu \mathrm{V} / \mathrm{ms}$ )

## Noise ( 300 kHz bandwidth) <br> $50 \mu \mathrm{~V}$ rms <br> Dielectric Absorption Error ${ }^{1}$ <br> $\pm 0.003 \%$ of input voltage change typ.

HOLD-TO-SAMPLE TRANSITION
Acquisition Time
(Measured with $5 \mathrm{~K} \Omega \| 500 \mathrm{pF}$ load)
To within $\pm 0.01 \%$ of 10V Step
$3.5 \mu \mathrm{~s}$ max.
To within $0.003 \%$ of 10 V Step
$4.0 \mu \mathrm{~s}$ max., (MP261 - $10 \mu \mathrm{~s}$ max.)
To within $0.01 \%$ of 20 V Step
$4.5 \mu \mathrm{~s}$ max.
To within $0.003 \%$ of 20 V Step
$5.0 \mu \mathrm{~s}$ max., (MP261 - $15 \mu \mathrm{~s}$ max.)
DIGITAL CONTROL INPUT
Logic Type
TLL Compatible
Sample
Logic "1" ( $+3 V$ min.)
Hold
Logic "0" (0.4V max.)
Required Fall Time
10 ns max.

## POWER, MECHANICAL, ENVIRONMENTAL

Power Supply
$\pm 15 \mathrm{~V} \pm 3 \% @ 12 \mathrm{~mA}$ nom. (Plus load current),
(MP261 - $\pm 15 \pm 3 \%$ @ 6 mA nom. (Plus load
current)
Operating Temperature
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Relative Humidity (Up to $4 \mathbf{0}^{\circ} \mathrm{C}$ ) non-condensing 0 to 95\%
Modupac ${ }^{\text {TM }}$ Dimensions
1" x 2 " x 0.44 "
$(25.4 \times 50.8 \times 11.2 \mathrm{~mm})$
Shielding
RFI 6 sides; EMI 5 sides
${ }^{1}$ At Hold Time $=$ Twice Sample Time
**Unless otherwise stated, percentage values apply to FSR of 20 V .

The high speed Input Buffer Amplifier feedback path is completed at the $\mathrm{S} / \mathrm{H}$ pin terminals. This provides user capability for gain programming (Figure 1), or for replacing the amplifier stage in typical D/A converters. Performance specifications of the uncommited amplifier are furnished below.

[^1]
## Input Offset Current

## $<5 \mathrm{nA},(\mathrm{MP} 261-<1 \mathrm{nA}$ )

Input Bias Current
$<10 \mathrm{nA}$, (MP261 - < 2 nA )
Input Impedance
$10^{9} \Omega \| 10 \mathrm{pF}$
Gain Bandwidth Product
3 MHz
Output Voltage Swing
$\pm 10.5 \mathrm{~V} \mathrm{~min}$. ( $\mathrm{R}_{\mathrm{L}} \geq 5 \mathrm{k} \Omega$ )
Common Mode Rejection Ration (CMRR)
85 dB min.

## Design Features

The MP260 and MP261 support error budgets for system accuracy of 14 to 16-bits with a tracking linearity of $0.002 \%$, low noise of $50 \mu \mathrm{~V}$ rms and a pedestal offset uncertainty of only $0.001 \%$. System throughput speeds may actually be increased with these units by allowing input multiplexer switching to occur during A/D conversion (the Hold mode rejection is typically 100 dB or $0.001 \%$ ), without a significant reduction in accuracy.
Each $\mathrm{S} / \mathrm{H}$ is a complete flexible unit as shown in Figure 1. The non-commited input amplifier
may be used as a high impedance buffer (following a multiplexer) or as a high speed output amplifier (following a current output digital-to-analog converter) or providing gain to match a wide range of signal inputs.
Unlike IC S/H circuits, these modular units are thoroughly specified for all critical performance parameters, many of which aren't even mentioned on IC S/H specification sheets. Note also that these modular units occupy less PC-board "real estate" than many IC S/H designs with their requisite external discrete components.

## USING THE MP260/MP261 Input Buffer Configurations

Figure 2 illustrates how the input buffer amplifier may be configured to provide gains of one through ten so that the S/H output will have $\mathrm{a} \pm 10 \mathrm{~V}$ FSR swing.
The illustration also includes sample configurations of the input buffer when used to replace the current-to-voltage amplifiers of D/A converters in which the current outputs are usually available.


Figure 2. Input Configuration Connections for MP260/MP261, Including Use As Replacement for DIA Output Amplifiers.

## MP260/MP261 Trim Adjustments

As shown in Figure 3, the S/H MP260/MP261 may be adjusted to compensate for any $\mathrm{S} / \mathrm{H}$ offset and for system offsets common to all channels sampled through the installed S/H unit.
(1) Connect a potentiometer of indicated resistance to the $\mathrm{S} / \mathrm{H}$ trim terminals and the wiper to the +15 V supply.
(2) Sample a channel with desired zero voltage signal.
(3) Issue a train of SAMPLE and HOLD commands to obtain a stable output value.
(4) Adjust the trim potentiometer for zero voltage at the $\mathrm{S} / \mathrm{H}$ output.


Figure 3. Trimming MP260/MP261 for Zero Offset.

## Simultaneous S/H Application

Figure 4 illustrates the use of MP261 as simultaneous $\mathrm{S} / \mathrm{H}$ units in a multi-channel data acquisition system. As shwon, each S/H may be independently configured at the input for an appropriate gain, while the oututs are connected as differential inputs to an 8 -channel analog multiplexer.
In a typical seismic exploration application, for example, the control logic causes all inputs to be sampled and the tracked inputs to be "held" at the same time. With only 1 ns aperture uncertainty, the S/H output signal is accurate to within $1 / 2$ bit for signals are then converted sequentially in the MP8016 and eight parallel 16 -bit values are placed on the data bus of a minicomputer/microprocessor control system.
Figure 5 illustrates the use of high accuracy

MP261 S/H units in an Automatic Test Equipment (ATE) application. A high quality 16 -bit D/A converter, such as the Analogic MP1916TC, or 14-bit D/A converter MP1914TC), is programmed to supply accurate analog signals as stimuli for the unit under test (UUT). Each analog voltage is held at the output of a $\mathrm{S} / \mathrm{H}$ unit and connected to an appropriate analog stimulus node of the UUT.
Under program control, the recorded results are compared with the specified performance for the computer controlled profile of analog stimuli. The low cost per channel of the MP261 makes this application particularly cost effective for very high quality performance. The illustrated instrumentation is far less costly than the usual D/A-per-channel approach.


Figure 4. MP261 in a Simultaneous S/H Application, Showing Independent Gain Setup for Each Output Channel.


Figure 5. Time-Sharing a Precise D/A Converter with a S/H per channel for High Precision Analog Signal Stimulus in ATE Systems.

## MP260 Time-Shared Application

Figure 6 illustrates a typical application of the MP260. It provides the input to a 14-bit A/D converter (MP2734) from multiplexed analog channels with the same full scale range specifications. The excellent feedthrough rejection of the MP260 inputs may be switched from one full scale limit to the opposite polarity full scale limit.
For a 20 -volt step, the 100 dB rejection ratio means only 200 microvolts into the "held" channel ( $0.001 \%$ error). Thus, there is no significant penalty incurred by switching inputs during the conversion cycle. The S/H performance allows the multiplexer circuits to
stabilize for the next channel while the current channel is still being converted.
As shown in Figure 7, the sample/hold control timing sequence, that takes advantage of this "overlapping" of channel addressing and channel conversion, increases system throughput. The example in Figure 7 allows the MUX and amplifier circuits to stabilize before the value is switched to the $\mathrm{S} / \mathrm{H}$ input. For competitive S/H units with poorer feedthrough rejection, the S/H inpuyt must remain connected to the "held" channel until conversion is completed. Otherwise, an error will be introduced into the currently converted signal.


Figure 6. MP260 in a Time-Shared Application Block Diagram.


Figure 7. Timing S/H Waveforms, Showing Overlapped Switching and Converting Intervals for MP260 Instrumentation.


Figure 8. MP260/261 Mechanical \& Pinout.

## ORDERING GUIDE

Specify MP260 or MP261

## Description

The Analogic MP270 is a high speed, high accuracy sample and hold amplifier, featuring a low acquisition time of $1 \mu \mathrm{~s}$ aperture uncertainty time of less than 0.2 ns , and wide bandwidth, assuring compatibility with data acquisition systems having throughput rates up to 300 kHz . The high input impedance of the MP270 combined with its low noise and low feedthrough characteristics assure accuracies of $0.01 \%$ at these throughput rates.

## Performance

The $1 \mu \mathrm{~s}$ maximum acquisition time and the $0.01 \%$ accuracy of the MP270 are attained by placing a feedback loop around the switching circuit. This design technique provides compensation for any switching and non-linearity errors within the loop while forcing the output to follow the input. The introduction of very fast switching circuits limits the aperture uncertainty time to within 0.2 ns and virtually guarantees measurement repeatability. The 100s input impedance of the MP270 assures minimal source loading without additional external buffering, and the low hold mode decay rate of $2 \mu \mathrm{~V} / \mu \mathrm{s}$ assures highly accurate digitization even at slower conversion rates.

## Using the MP270

Because of the exceptionally high accuracy-with-speed performance of the MP270 and its low noise and wide bandwidth characteristics, care must be taken to minimize noise pickup on the signal input leads. All input and control pulse leads should be short and shielded, and a remotely generated control signal should be buffered close to the MP270 to prevent ringing.

## Features

- $1 \mu$ s Maximum Acquisition Time with 0.01\% Accuracy
- Wide Bandwidth: 500 kHz for Full Power
- High Input Impedance: $10^{8} \Omega$
- Low Aperture Uncertainty of 0.2 ns Guarantees Accurate Digitization
- Low Droop Rate:
$2 \mu \mathrm{~V} / \mu \mathrm{S}$


Figure 1. MP270 Sample and Hold Amplifier with MP2912A Analog-toDigital Converter and AN4716 Multiplexer Guarantees a Throughput Rate of Up to 140 kHz for a 12-Bit Data Acquisition Application.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

SAMPLE MODE
Input Voltage Range
$\pm 10 \mathrm{~V}$ max. useful signal, $\pm 15 \mathrm{~V}$ max. without damage
Gain
$+1.000 \pm 0.005 \%$
Small Signal Bandwidth
10 MHz min.
Full Power Bandwidth
500 kHz min.
Slew Rate
$50 \mathrm{~V} / \mu \mathrm{s}$ min.
Input Impedance
$10^{8} \Omega$ in parallel with 10 pF
Linearity
0.005\% max.

Settling Time
To $0.01 \%$ of 20V Input Step
700 ns typ., 900 ns max.
To $0.05 \%$ of 10 V Input
450 ns typ., 600 ns max.
Input Bias Current
$<100 \mathrm{pA}$
Input Offset Voltage
$\pm 20 \mathrm{mV}$ max., adjustable to zero (see Fig. 4)
Offset Tempco
$\pm 50 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typ.
Offset vs. Supply
$\pm 0.0015 \%$ FS voltage change typ.

## Noise

$300 \mu \mathrm{~V}$ p-p max.

## SAMPLE-TO-HOLD SWITCHING

Switching Transient Settling Time
(to $0.01 \%$ of FS )
150 ns typ., 400 ns max.
Aperture Time
10 ns typ.
Aperture Uncertainty Time
$\pm 0.2 \mathrm{~ns}$ typ.

HOLD MODE
Output Voltage
$\pm 10 \mathrm{~V}$ max.

## Maximum Load

$500 \Omega$ in parallel with 200 pF (short circuit protected)
Output Impedance
$0.1 \Omega$
Droop Rate
$2 \mu \mathrm{~V} / \mu \mathrm{s}$ max.
*Dielectric Absorption
Approx. $0.0075 \%$ @ $2 \mu \mathrm{~s}$ sample time, $5 \mu$ s hold time

Voltage Feedthrough ( $\mathbf{2 0 V}$ p-p 500 kHz Sinusoidal on Input)

- 80 dB max.

Hold Offset (pedestal)
$\pm 10 \mathrm{mV}$ adjustable to zero with externally ac-
cessible internal adjustment
Hold Offset Tempco
$\pm 30 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typ.
Hold Offset Non-Linearity (Pedestal Variation over Input Signal Range)
$\pm 0.005 \%$ max.
Output Voltage Variation due to Control Pulse Variation
1 mV per volt of change in control signal typ.

## Noise

0.5 mV p-p max.

## HOLD-TO-SAMPLE SWITCHING

Acquisition Time
To $\mathbf{0 . 0 1 \%}$ of $\mathbf{2 0 V}$ Step Input
800 ns typ., $1 \mu \mathrm{~s}$ max.
To $0.05 \%$ of 10 V Step Input
550 ns typ., 700 ns max.

DIGITAL CONTROL INPUT
Compatibility
TTL compatible, 2 logic loads
Input Impedance
$1 \mathrm{k} \Omega$ in parallel with 33 pF (3 mA sink current)
Sample
Logic "0" ( +0.4 V max.)
Hold
Logic "1" (+3.0V min.)
Required Rise Time
10 ns max. to obtain minimum aperture time

```
POWER SUPPLY
+15V }\pm3
60 mA max. + load current
-15V }\pm3
40 mA max. + load current
```

ENVIRONMENTAL \& PACKAGING
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $95 \%$, non-condensing
Modupac ${ }^{\text {TM }}$ Dimensions
$2 " \times 2$ " $\times 0.39$ " ( $50.8 \times 50.8 \times 9.9 \mathrm{~mm}$ )
Electrical Shielding
RFI 6 sides; EMI 5 sides


Figure 2. MP270 Output Characteristics Showing Acquisition Time. Upper Waveform Shows Response of MP270 to a 20V Step Input Signal. Lower Waveform is a 2500:1 Amplification of the Upper Trace and Shows Settling Characteristics of the MP270.


Figure 3. MP270 Output Characteristics Showing Hold Pedestal and Feedthrough Rejection Characteristics. The MP270 Samples the Input Signal Only While it is at +10 V . When the Input Signal Goes to - 10V, the MP270 Hold Voltage Changes by Less Than 1 mV .


Figure 4. MP270 Input Offset Adjustment.


Figure 5. MP270 Outline Drawing.
Input Voltage offset compensation is accomplished by connecting a potentiometer between the two OFFSET ADJ. terminals. The variable output of the potentiometer is adjusted until the offset is reduced to an acceptable level.

## *Dielectric Absorption

Dielectric absorption is the decaying of the Hold voltage (on the Hold capacitor) due to the charge redistribution within the capacitor dielectric. This error is a resultant of rapidly charging the Hold capacitor and disconnecting the charging source. The output voltage will decay according to the following relationship:

$$
\Delta E=E_{S} K \log 10 \quad\left(\frac{t_{s}+t_{h}}{t_{s}}\right)
$$

where:

$$
\begin{aligned}
\Delta \mathrm{E}= & \text { Output voltage error } \\
\mathrm{E}_{\mathrm{S}}= & \text { Capacitor voltage change } \\
\mathrm{K}= & \text { Empirical constant for Hold } \\
& \text { capacitor dielectric }(\mathrm{K}=1.5 \mathrm{x} \\
& 10^{4} \text { for polystyrene capacitor in } \\
& \text { MP270) } \\
\mathrm{t}_{\mathrm{S}}= & \text { Sample time } \\
\mathrm{t}_{\mathrm{h}}= & \text { Hold time }
\end{aligned}
$$

Example: For a 20 V step, a Sample time of $2 \mu \mathrm{~s}$, and a Hold time of $5 \mu \mathrm{~s}, \Delta \mathrm{E}=1.5 \mathrm{mV}$.

## ORDERING GUIDE

Specify MP270


ANALOGO.

## MP271

High Speed-Precision Sample \& Hold Amplifier

## Description

The MP271 (see Fig. 1) is one of thë highest performance sample-andhold amplifiers currently available and provides an exceptional combination of very high speed with precision. Performance is optimized for use in data acquisition systems which have sampling rates of up to 300 kHz and resolutions of up to 16 bits. The very high speed performance of the MP271 is evidenced by the acquisition time of $1.0 \mu \mathrm{~s}$, the aperture uncertainty of 0.2 ns , and the full power bandwidth of 600 kHz . The capability of the MP271, in high resolution systems of up to 16 bits, is demonstrated by its excellent linearity and feedthrough specifications. It has a non-linearity of $0.003 \%$ maximum while sampling, a sample-to-hold offset non-linearity of $0.002 \%$ maximum, and a high frequency feedthrough of typically $0.001 \%$ at 500 kHz .
No other sample-and-hold amplifier matches the overall performance of the MP271. It surpasses the previously best available modular unit (the Analogic MP270). In comparison with integrated circuit (IC) units, it is an order of magnitude better in specific features such as feedthrough, aperture jitter, linearity and pedestal non-linearity.


Figure 1. MP271 Sample \& Hold Amplifier Functional Block Diagram.

## Features

- Excellent Linearity: $\pm 0.003 \%$ max.
- Extremely Low Feedthrough: - 100 dB (0.001\%)
- Very Low Pedestal Variation: $\pm 0.002 \%$ max.
- Fast Acquisition:
$1.0 \mu \mathrm{~s}$ to $0.005 \%$
- Low Aperture Uncertainty:
0.2 ns
- Wide Bandwidth:

500 kHz full power

- High Input Impedance: $100 \mathrm{M} \Omega$
- Low Droop:
$2 \mu \mathrm{~V} / \mu \mathrm{s}$


## Applications <br> ■ Wideband Data Acquisition Systems

- Telecommunications Digitizing
- Industrial Process Control Systems
Medical Scanning Systems
Nuclear Research


## Using the MP271

The performance of the MP271 is optimized for use in multiplexed, high speed, high resolution, data acquisition systems. The very low hold mode feedthrough MP271 significantly increases system throughput rates by allowing the A/D conversion time to overlap the multiplexer switching time without degrading system accuracy.
Maximum throughput is achieved by switching the multiplexer to the next channel while the $\mathrm{S} / \mathrm{H}$ holds the previous channel value. The multiplexer settles fully to the new value while the A/D conversion is completed on the previous channel value. At the end of the conversion, the MP271 switches to the sample mode; it acquires the new input and the new conversion is triggered.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## SAMPLE MODE

Input Voltage Range
$\pm 10 \mathrm{~V}$ ( $\pm 15 \mathrm{~V}$ without damage)
Gain
$+1 \pm 0.01 \%$ max., $+1 \pm 0.003 \%$ typ.
Small Signal Bandwidth
10 MHz min.
Full Power Bandwidth
500 kHz min.
Slew Rate
$50 \mathrm{~V} / \mu \mathrm{s} \mathrm{min}$.
Input Impedance
$10^{8} \Omega$ in parallel with 10 pF
Nonlinearity (for 20V input)
$\pm 0.003 \%$ max.
Settling Time
To within $\pm \mathbf{0 . 0 0 5 \%}$ of 20 V Input Step
850 ns typ., $1.0 \mu \mathrm{~s}$ max.
To within $\pm 0.010 \%$ of 20 V Input Step
700 ns typ., 900 ns max.
To within $\pm \mathbf{0 . 0 5 0 \%}$ of 10 V Input Step
450 ns typ., 600 ns max.
Input Bias Current
100 pA max.
Input Offset Voltage
$\pm 20 \mathrm{mV}$ max., adjustable to zero
Offset Tempco
$\pm 50 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typ.
Offset vs. Supply
$\pm 0.0015 \%$ FS per $\%$ supply voltage change typ.
Noise ( 10 MHz bandwidth)
$300 \mu \mathrm{~V}$ p-p ( $\approx 50 \mu \mathrm{~V} \mathrm{rms}$ ) max.

## SAMPLE-TO-HOLD SWITCHING

Switching Transient Settling Time
(to $\pm \mathbf{0 . 0 1 \%}$ of FS)
150 ns typ., 400 ns max.
Aperture Time
10 ns typ.
Aperture Uncertainty
$\pm 0.2 \mathrm{~ns}$ typ.

## HOLD MODE

Output Voltage Range
$\pm 10 \mathrm{~V}$ min.
Maximum Load
$500 \Omega$ in parallel with 200 pF , short circuit pro-
tected (tested with 100 pF load)
Output Impedance (dc)
$0.1 \Omega$
Droop Rate (@ $25^{\circ} \mathrm{C}$ )
$2 \mu \mathrm{~V} / \mu \mathrm{s}$ max.
Dielectric Absorption
$0.0075 \%$ @ $2 \mu \mathrm{~s}$ sample time, $5 \mu \mathrm{~s}$ hold time

Voltage Feedthrough ( $\mathbf{2 0 V}$ p-p 500 kHz sinusoidal input)

- 100 dB typ., - 94 dB max.

Hold Offset (pedestal)
$\pm 10 \mathrm{mV}$ unadjusted. Adjustable to zero with externally accessible internal adjustment
Hold Offset (pedestal) Tempco $\pm 30 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typ.
Hold Offset Nonlinearity (pedestal variation over input signal range)
$\pm 0.002 \%$ max.
Output Voltage Variation due to Control Pulse Variation
1 mV per volt of change in control signal typ.
Noise ( 10 MHz bandwidth)
0.5 mV p-p typ., 1 mV p-p max. ( $\approx 150 \mu \mathrm{Vms}$ )

## HOLD-TO-SAMPLE SWITCHING

## Acquisition Time

To within $\pm 0.005 \%$ of 20 V Input Step $1.0 \mu \mathrm{~s}$ typ., $1.1 \mu \mathrm{~s}$ max.
To within $\pm 0.01 \%$ of 20 V Input Step 800 ns typ., $1.0 \mu \mathrm{~s}$ max.
To within $\pm 0.05 \%$ of 10 V Input Step 550 ns typ., 700 ns max.

## DIGITAL CONTROL INPUT

## Logic Type

TTL compatible, 1 logic load ( $1 \mu \mathrm{~A}$ load)

## Sample

Logic "0" ( +0.4 V max.)
Hold
Logic "1" ( +3 V min.)

## Required Rise Time

5 ns max. to obtain min. aperture time

> POWER SUPPLY
> $+15 \mathrm{~V} \pm 3 \%$
> 50 mA max. + load current
> $-15 \mathrm{~V} \pm 3 \%$
> 45 mA max. + load current

## ENVIRONMENTAL \& MECHANICAL

Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$
Modupac ${ }^{\text {TM }}$ Dimensions
2 " $\times 2$ " $\times 0.39^{\prime \prime}(50.8 \times 50.8 \times 9.9 \mathrm{~mm})$
Electrical Shielding
Electrostatic 6 sides; Electromagnetic 5 sides

## Using the MP271 (cont.)

High frequency components may be present at the S/H input from two sources: ultra fast multiplexer switching of full scale step inputs and high frequency data. The superior feedthrough characteristics of the MP271 result in the hold mode output voltage changing by only $0.001 \% ~(-100 \mathrm{~dB}$ ) with a 20 V p-p 500 kHz sinusoidal input applied.
Fig. 2 shows an application in which system speed and accuracy are optimized with the MP271. The MP2734 conversion time is only $6.8 \mu \mathrm{~s}$ to 14 bits and the differential linearity is $\pm 1 / 2$ LSB $( \pm 0.003 \%)$. The low feedthrough of the MP271 ( $0.001 \%$ ) complements system performance. The multiplexer is switched during the hold mode and its settling time overlaps the conversion time. The system throughput rate is determined solely by the $6.8 \mu \mathrm{~s}$ conversion time plus the $1.1 \mu \mathrm{~s}$ maximum acquisition time (to $\pm 0.005 \%$ ) of the MP271. This yields a system throughput rate of 125 kHz to 14 bits.

## System Considerations

A sample-and-hold amplifier is used to reduce the time uncertainty (and resultant amplitude error) in practical systems which have inherent finite sampling apertures. The MP271 reduces this time to only 0.2 ns ... the aperture uncertainty time. In a system without a sample-and-hold, the time uncertainty is the conversion time of the A/D converter, general-
ly measured in microseconds. See the Analogic Data-Conversion System Digest, for a complete treatment of this subject.
The time uncertainty used in calculating the error vs. information frequency, is the system time uncertainty. The system time uncertainty is the MP271 aperture time uncertainty, plus any jitter in generating the control input to the MP271. Control input jitter is frequently caused by triggering the A/D with the system clock and then using the end-of-conversion output of the A/D as the control input to the sample-and-hold amplifier. This source of jitter is eliminated when the system clock directly initiates the sample-to-hold control (see Fig. 2). Buffering (immediately adjacent to the MP271) is suggested to provide the very fast rise time ( 5 ns ) required by the control input.
The high impedance ( $10^{8} \Omega$ in parallel with 10 pF ) of the MP271 make it ideal as a buffer for the output of CMOS or FET analog multiplexers. Voltage divider error, caused by multiplexer switch ON resistance in series with the input impedance, is negligible.
The low droop rate ( $2 \mu \mathrm{~V} / \mu \mathrm{s}$ ) of the MP271 holds its output constant, even with 16 -bit converters. On a 10 V full scale range, a 16 -bit ADC such as the Analogic MP8016, has an LSB of $153 \mu \mathrm{~V}$. For the MP271 to discharge less than $1 / 2$ LSB (at $2 \mu \mathrm{~V} / \mu \mathrm{s}$ ) the conversion must be completed in less than $39 \mu \mathrm{~s}$, which is well within the limits of the MP8016.


Figure 2. High Accuracy, High Resolution, 125 kHz 14-Bit Data Acquisition System Using the MP271.


Figure 3. MP271 Output Showing Sample-to-Hold Switching Illustrating Low Droop Rate. Performance Limit is Two Divisions Vertically On Upper Trace ( $\mathbf{2 0 0} \mathbf{~ m V / 1 0 0 ~ m s ) . ~}$


Figure 4. MP271 Output Acquiring 20V Step Input. Upper Trace Shows Slew Rate of 50 V/us at 5V/Division. Lower Trace Shows Acquisition Time of 800 ns to $0.01 \%$ at $5 \mathrm{mV} /$ Division.

## Theory of Operation

The exceptional performance of the MP271 results directly from its unique combination of design features. As shown in the simplified block diagram of Fig. 5, the MP271 is basically, three circuits: 1) a voltage-to-current (VII) source amplifier, 2) an output amplifier/integrator, and 3) a switching circuit.
When the MP271 is in the sample mode (switches S1 and S3 are open, S2 and S4 are closed, and control is at logic " 0 ") the circuit functions as a unity gain follower with the voltage across the holding capacitor (C1) forced to equal the input voltage. The maximum acquisition time of only $1 \mu \mathrm{~s}$ (to $0.01 \%$
of final value) results from using a small value of C 1 , high speed amplifiers, and very fast switch drivers in addition to the high-power current source amplifier (V/I). Switching and non-linearity errors are held to a minimum by placing the switching circuits and the current source within the over-all feedback loop.
In the hold mode (switches S1 and S3 closed, S2 and S4 open, and control at logic " 1 ") the holding capacitor (C1) is part of the low leakage integrator. The discharge rate is slow enough to limit the droop to less than $1 / 2$ LSB. High input/output isolation is guaranteed by opening the input to C 1 with S ; opening the feedback loop with S2; and at the same time shorting the V/I inputs through S1 and grounding its output with S3. A 20 V p-p, 500 kHz sinusoidal input to the MP271 is typically attenuated by 100 dB .


Figure 5. MP271 Simplified Block Diagram.

## Adjustments

Provision is made to adjust the input offset voltage of the MP271 to zero externally by connecting a $200 \Omega$ potentiometer as shown in Fig. 6. To adjust, short the input to analog return, connect the control input to ground (placing the MP271 in the sample mode), and set the offset potentiometer for zero output from the MP271.
It is virtually impossible to avoid capacitance coupling between the switch drivers and the hold capacitor (C1), which results in a small charge being dumped onto C 1 when switching from sample to hold. This produces an offset, or pedestal, at the output which is mode
dependant. The MP271 includes an internal pedestal offset adjustment control. To adjust, short the input to analog return, switch the control input between sample and hold (a $50 \%$ duty cycle at 200 kHz is convenient), and set the pedestal control for zero output during the hold mode period.

The gain of the MP271 is typically within $\pm 300 \mu \mathrm{~V}$ of nominal $\pm 10 \mathrm{~V}$ output. Provision for gain adjustment is not included. The small gain error of the MP271 may be compensated via the gain adjustment potentiometer on the ADC following the sample-and-hold amplifier.


Figure 6. MP271 Mechanical Outline and Offset Adjustment.

## ORDERING GUIDE

Specify MP271


## MP272

## Very High Speed High Accuracy Inverting Sample-and-Hold

## Description

The Model MP272 is an inverting sample-and-hold (S/H) amplifier module with an unprecedented combination of high speed and high accuracy at low cost. Its maximum time for acquiring a 10 V input step to $\pm 0.01 \%$, including the settling time of its input buffer, is only 300 ns ( 350 ns max. for a 20 V step). This is faster than the "typical" acquisition time specified by many other manufacturers who frequently neglect the input buffer amplifier settling time.
The aperture uncertainty time of the MP272 is only 50 ps and its hold mode droop rate is $5 \mu \mathrm{~V} / \mu \mathrm{s}$ max.; each of these values is one-half to one-fifth of the corresponding specifications published for a variety of other high-speed models. These specifications translate directly into correspondingly greater overall system accuracy. Available at prices equal to or lower than those of less accurate models, the MP272 delivers the optimum S/H performance for transient analyzers, digital oscilloscopes, and other high-speed systems requiring up to 12 -bit resolution.
The Model MP272 includes a unitygain input buffer amplifier with $100 \mathrm{M} \Omega$ input impedance and a low 150 pA bias current. This stage is followed by a low output impedance, switch-controlled stage that acts as (continued)


Figure 1. MP272 Functional Block Diagram. Very fast operational amplifiers provide a 200 ns typical acquisition time to $0.01 \%$ for a 10 V step.

## Features

- High Speed

200 ns typ. acquisition time for a 10 V step (including input buffer settling time)
5 ns aperture time, typ.

- High Sampling Accuracy $\pm 0.005 \%$ FSR non-linearity, max. 50 ps aperture uncertainty upon transition to HOLD, typ.
- Exceptionally Low Bias Current 150 pA max. @ $25^{\circ} \mathrm{C}$
- High Holding Accuracy
$5 \mu \mathrm{~V} / \mu \mathrm{S}$ droop rate, max. @ $25^{\circ} \mathrm{C}$ $\pm 0.005 \%$ FSR offset nonlinearity, max.
- Low Dielectric Absorption $0.005 \%$ of voltage change per microsecond of hold time
- Wide Bandwidth
(in sample mode)
15 MHz small signal bandwidth ( -3 dB )
3 MHz full power bandwidth
- Low Noise
$200 \mu \mathrm{~V}$ rms ( 10 MHz ) max., in both SAMPLE and HOLD
- System Oriented Drives large capacitive load Consumes only 1.5 Watts Includes holding capacitor and provisions for optional external offset adjust
- Offers superior performance at low cost


## Applications

- Digital Oscilloscopes
- Transient Analyzers
- Automatic Test Equipment
- High Speed Data

Acquisition Systems

- Digital Signal Processors


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## SAMPLE MODE

Input Voltage Range (FSR)
$\pm 10 \mathrm{~V}\left( \pm \mathrm{V}_{\text {supply }}\right.$ without damage)
Gain

- 1

Gain Accuracy
$\pm 0.01 \%$ max. @ $25^{\circ} \mathrm{C}\left(10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}\right.$ max. tempco)
Non-linearity
$\pm 0.005 \%$ FSR max.
Settling Time:
to within $\pm 0.01 \%$ of 10 V input step-
200 ns typ., 300 ns max.
to within $\pm 0.01 \%$ of 20 V input step-
250 ns typ., 350 ns max.
Small Signal Bandwidth (-3 dB)
15 MHz typ.
Full Power Bandwidth
3 MHz typ.
Slew Rate
$200 \mathrm{~V} / \mu \mathrm{s}$, min.
Input Impedance
$100 \mathrm{M} \Omega \mid 15 \mathrm{pF}$ typ.
Input Bias Current (@25 ${ }^{\circ}$ ) *
150 pA max.
Input Offset Voltage (@25 ${ }^{\circ} \mathrm{C}$ )
$\pm 10 \mathrm{mV}$ max.
Offset Tempco
$\pm 100 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.
Offset vs. Supply
$200 \mu \mathrm{~V}$ per $1 \%$ change in supply voltage, max.
Noise ( 10 MHz bandwidth)
$200 \mu \mathrm{~V}$ rms max.
SAMPLE-TO-HOLD SWITCHING
Aperture Time
5 ns typ.
Aperture Uncertainty
50 ps typ.
Switching Transient Settling Time
(to $\pm 0.01 \%$ of FSR)
150 ns max.
HOLD MODE
Output Voltage Range
$\pm 10 \mathrm{~V}$
Maximum Load
$2 \mathrm{k} \Omega \| 50 \mathrm{pF}$
Droop Rate (@25 ${ }^{\circ}$ ) *
$5 \mu \mathrm{~V} / \mu \mathrm{s}$ max.

[^2]Dielectric Absorption
$0.005 \%$ of voltage change @ $0.3 \mu$ s sample time, $1 \mu$ s hold time typ.
Hold Offset (Pedestal) @ $25^{\circ} \mathrm{C}$
$\pm 0.5 \mathrm{mV}$ typ., $\pm 2 \mathrm{mV}$ max. (optionally ad-
justable to zero)
Hold Offset (Pedestal) Tempco
$\pm 40 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.
Hold Offset Non-linearity
$\pm 0.005 \%$ FSR max.
Voltage Feedthrough Rejection Ratio
(10V Input Step)
84 dB typ., 78 dB min.
Output Voltage Variation due to Control Pulse Variation
1 mV per volt of change in control signal max.
Noise ( 10 MHz Bandwidth)
$200 \mu \mathrm{~V}$ rms max.

## HOLD-TO-SAMPLE SWITCHING

Acquisition Time:
to within $\pm 0.01 \%$ of 10 V input step200 ns typ., 300 ns max.
to within $\pm 0.01 \%$ of 20 V input step250 ns typ., 350 ns max.

## DIGITAL CONTROL INPUT

## Logic Type

TTL compatible, 1 unit load

## Sample

Logic "0" (+ 0.4V max.)
Hold
Logic "1" (+3V min.)
Required Rise Time
5 ns max. to obtain min. aperture time
POWER SUPPLY (Exclusive of Load)
$+15 \mathrm{~V} \pm 3 \%$
50 mA typ.
$-15 \mathrm{~V} \pm 3 \%$
50 mA typ.

## ENVIRONMENTAL \& MECHANICAL

Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$
Modupac ${ }^{\text {TM }}$ Dimensions
$2 " \times 2$ " $\times 0.44$ " ( $50.8 \times 50.8 \times 11.2 \mathrm{~mm}$ )
Electrical Shielding
Electrostatic 6 sides; electromagnetic 5 sides

## Description (cont.)

a unity gain inverting amplifier in the sample or follow mode, and as a memory circuit in the hold mode. The low $5 \mu \mathrm{~V} / \mu \mathrm{s}$ droop rate in the hold mode ensures high measurement accuracy, even when used with a relatively slow analog-to-digital converter.
The module accepts a full scale input voltage of $\pm 10 \mathrm{~V}$. Output gain accuracy is $\pm 0.01 \%$ with a maximum non-linearity over the full range of less than $\pm 0.005 \%$. Noise level is maintained at less than $200 \mu \mathrm{~V}$ rms over a 10 MHz bandwidth. The hold mode offset is typically less than $\pm 0.5 \mathrm{mV}$ and is externally adjustable to zero. A combination of precision matched resistors and low temperature coefficient circuit components limits offset temperature coefficient to less than $\pm 40 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$.
Dielectric absorption error, commonly neglected or not even recognized by other manufacturers, is minimized in the MP272 by the use of an extremely high quality "hold" capacitor. As a result, the error, assuming $0.3 \mu \mathrm{~s}$ sample and $1 \mu \mathrm{~s}$ hold times, is typically $0.005 \%$ of voltage change, by actual measurement!
Even under worst case conditions, aperture time of 5 ns aperture uncertainty of 50 ps and switch settling time of 100 ns , the MP272 still allows up to 700,00 samples per second using a $1 \mu \mathrm{~S} A / D$ converter. Figure 2 shows acquisition time of a typical unit when a 20 V step is applied. The 140 ns acquisition time obtained is well within the 250 ns typical specification.
This compact module is enclosed in a metal case, 2" x 2" x 0.39 " ( $50.8 \times 50.8 \times 9.9 \mathrm{~mm}$ ), that provides electrostatic shielding on all six


Figure 2. MP272 Acquisition of a 20V Input Step. The middle trace shows a slew rate of $1000 \mathrm{~V} / \mu \mathrm{s}$. The upper trace shows acquisition, to within 2 mV ( $0.01 \%$ of final value), in 140 ns . Thus, this typical unit's speed is appreciably better than the specified value.
sides and electromagnetic shielding on five. Its power consumption of 1.5 W is approximately half that of some earlier S/H models, resulting in significantly lower internal operating temperatures, thereby improving reliability. Delivering the rated performance over a $0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ temperature span, with a relative humidity up to $85 \%$, the Model MP272 provides the highest speed-with-accuracy performance available for a wide variety of applications.

## TYPICAL TIMING AND APPLICATION

## General Timing Usage

Figure 3 shows a typical timing diagram for controlling the MP272 in multiplexed systems. The conversion time of the analog-to-digital converter used may be inserted in the time line shown, yielding the sampling period for a specific application. Note that in addition to the MP272's fast acquisition time, its low settling time upon switching from SAMPLE to HOLD contributes to its high throughput rate capability.

## Typical High Speed Multiplexed Data Acquisition System

The Model MP272's speed and accuracy provide several system advantages, even in applications not usually considered as "high speed". For example, a typical industrial process control system may be required to monitor numerous process parameters, most of which do not ordinarily change rapidly. Nevertheless, consideration of overall system throughput rate and processor utilization may dictate a need for high speed sampling, possibly in bursts. In addition, the higher the accuracy of each measurement made, the more precisely, and therefore economically, is the process controlled.
Figure 4 shows how the speed and accuracy of such a process control application are optimized with the Model MP272 Sample-andHold. The grounding and power distribution method shown is appropriate to nearly all high precision applications.
Use of a 12-bit analog-to-digital converter with differential non-linearity of $\pm 1 / 2$ LSB max. is recommended. To maximize throughput rate, a multiplexer is switched to each succeeding channel simultaneously with selection of the HOLD mode for the current channel (Figure 3). This allows time for multiplexing transients
to settle prior to the converter's first bit decision. When the system is ready to convert the next channel, no "waiting" time is expended for channel switching. The next channel, already connected to the MP272, can be acquired to $0.01 \%$ in 300 ns max. ( 10 V step).


Figure 3. Typical Timing For A High Speed Multiplexed Data Acquisition Subsystem Using the MP272 S/H.

## Aperture Uncertainty Effects

For any sampled data process, uncertainty in the time of taking a sample results in an equivalent amplitude error for a signal of frequency $f$. The uncertainty, $\Delta T$, includes system clock jitter and S/H aperture uncertainty. The error due to $\Delta T$ may be stated as rms \%FSR error $=222 \times f(\mathrm{~Hz}) \times \Delta \mathrm{T}(\mathrm{s})$. With $\Delta \mathrm{T}$ $=50 \mathrm{ps}$ for the MP272, assuming use of a
jitter-free CONTROL input and a sufficiently fast analog-to-digital converter, signals having frequency content approaching 1 MHz may be measured with less than $\pm 0.012 \%$ FSR rms aperture uncertainty error.
For applications requiring the maximum system accuracy, it is recommended that a crystal-controlled oscillator and fast rise time logic ( 5 ns max.) be used to generate a jitterfree CONTROL input. The end of conversion (EOC) output from the analog-to-digital converter used may have significant jitter relative to 50 ps . For this reason, in many applications, it should not be fed back directly as the MP272 CONTROL input. Rather, it is recommended that the EOC signal be used to gate the jitter-free clock to the MP272.

## Offset Adjustment

As shown in Figure 5, the MP272 may be adjusted to compensate for any S/H offset and for system offsets common to all channels that are sampled through the installed $\mathrm{S} / \mathrm{H}$ unit.

1. Connect a $20 \mathrm{k} \Omega$ potentiometer to the $\mathrm{S} / \mathrm{H}$ trim terminals and its wiper to the -15 V supply.
2. Sample a channel with a zero voltage input. 3. Issue a train of SAMPLE and HOLD commands per the system usage timing, via the CONTROL input.
3. Adjust the trim potentiometer for zero voltage, during the HOLD mode, at the $\mathrm{S} / \mathrm{H}$ output.


Figure 4. Typical High Accuracy, 12-bit Data Acquisition System. The grounding, control, and power distribution layout shown minimizes ground loop and other error effects. Keeping in-
terconnections shown in heavy line as short as possible will help ensure system accuracies that are fully consistent with the MP272's high precision.



Figure 5. Optional External Offset Adjustment Set-Up.


## Description

The Analogic MP282A is a highspeed dual-channel sample-and-hold module with built-in multiplexer and automatic gain-ranging amplifier. Optimized for professional audio recording and designed specifically to increase the dynamic range and improve the performance of audio bandwidth analog-to-digital conversion, it also offers a low priced alternative to previously available equipment for converting audio bandwidth signals to digital words for such wide-dynamic range applications as vibration analysis, spectrum analysis, seismic exploration and sonar systems.
To achieve the high performance standards required for high fidelity audio recording, signal conversion equipment must yield 16 bits of dynamic range and low harmonic distortion at high sampling rates. The MP282A, when connected to a 15-bit analog-to-digital converter (ADC), such as Analogic's MP2735-2, meets all the analog function requirements of professional audio recording at relatively low cost. Its one bit of automatic gain ranging (see Figure1) allows a 15 -bit ADC to give a total of 16 bits of dynamic range ( 98 dB ), eliminating the need for high-cost 16 -bit ADCs. Figure 2


Figure 1. MP282A Functional Block Diagram.

## SPECIFICATIONS

```
ANALOG INPUTS
Number of Inputs
2 channels
Full Scale Linear Range
\(\left( \pm 5 \mathrm{~V} \pm \mathrm{V}_{\text {supply }}\right.\) without damage)
Input Impedance
\(10 \mathrm{M} \Omega / / 10 \mathrm{pF}\) with input connected as voltage
follower
Input Bias Current
\(0.5 \mu \mathrm{~A}\) typ.
Comparator Input Impedance
\(12 \mathrm{k} \Omega\)
```


## ANALOG OUTPUT

## Number of Outputs

1 channel
Full Scale Linear Voltage Range $\pm 5 \mathrm{~V}$

Output Impedance @ dc
$0.1 \Omega$
Load
$2 \mathrm{k} \Omega$ min. \& 100 pF max.
Protection
Short circuit to ground
Multiplexer Out ${ }^{1}$
Same characteristics as above

## TRANSFER CHARACTERISTICS ${ }^{5}$

Full Power Bandwidth (sample mode)
150 kHz typ.
Slew Rate (sample mode)
$6 \mathrm{~V} / \mu \mathrm{s}$ typ.
Crosstalk ${ }^{2}$
-86 dB max.
Gain, Referred to Input (RTI)
+1 or +2
Sample and Hold Acquisition Time ${ }^{3}$
$3.5 \mu \mathrm{~s}$ max.
Aperture Delay Time
50 ns typ.
Aperture Uncertainty
0.4 ns typ.

Channel Select Multiplexer Settling Time ${ }^{3}$
$2.0 \mu \mathrm{~s}$ max.
Auto Range Amplifier Settling Time ${ }^{4}$
$1.5 \mu \mathrm{~s}$ max.
Sampling Rates (with MP2735-2 ADC)
2 Channels
57 kHz max.
1 Channel
105 kHz max.

## ACCURACY AND STABILITY ${ }^{5}$

Harmonic Distortion
-86 dB max. (see Fig. 2)
Gain Accuracy $\left(0^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ $\pm 0.1 \%$ max.
Offset Voltage $\left(0^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$
20 mV max. RTI
Noise (shorted input, 20 kHz bandwidth)

- 98 dB RTI referred to rms full scale

Droop Rate at $25^{\circ} \mathrm{C}$ (doubles every $10^{\circ} \mathrm{C}$ )
$0.05 \mu \mathrm{~V} / \mu \mathrm{s}$, typ.; $0.4 \mu \mathrm{~V} / \mu \mathrm{s}$, max.

## Linearity

 $\pm 0.002 \%$ FSR, max.
## DIGITAL INPUTS

## Logic Type

TTL
Control Channel 1 and Channel 2
2 lines
Sample Mode
TTL Low
Hold Mode
TTL High
Required Rise Time
10 ns max.
Channel Select
1 line
Channel 1
TTL High
Channel 2
TTL Low
Latch Control
1 line
Transparent
TTL High
Latches
High to low transition
Latch Control Simultaneously Affects Channel
Select and Gain Output

DIGITAL OUTPUT
Gain Output (controlled by latch)
1 line
Gain @ +1
TTL Low
Gain @ +2
TTL High

POWER, MECHANICAL, ENVIRONMENTAL
Analog Power Supplies ${ }^{6}$
$\pm 12 \mathrm{~V}$ to $\pm 15 \mathrm{~V} @ 35 \mathrm{~mA}$, typ. tracking @ $\pm 1 \%$
Digital Power Supply ${ }^{6}$
$+5 \mathrm{~V} \pm 5 \%$ @ 10 mA , typ.

Operating Temperature Range<br>$0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$<br>Storage Temperature Range<br>$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$<br>Relative Humidity<br>0 to $85 \%$, non-condensing to $40^{\circ} \mathrm{C}$<br>Modupac ${ }^{\text {TM }}$ Dimensions<br>2 " X 2" X 0.44 " ( $50.8 \times 50.8 \times 11.2 \mathrm{~mm}$ )<br>Electrostatic Shielding<br>6 sides<br>Electromagnetic Shielding<br>5 sides<br>Case Potential<br>Ground

## Notes:

1. User must connect comparator input with multiplexer output to enable gain ranger.
2. Over the frequency range of 20 kHz and inputs at 0 dB (FS) to -15 dB measured as the peak line by a spectrum analyzer with 100 Hz bandwidth.
3. To $\pm 0.005 \%$ final value.
4. Measured from high-to-low transition of latch control input.
5. Unless otherwise specified, these specifications apply at $25^{\circ} \mathrm{C}$ and with each input amplifier connected as a voltage follower.
6. Analog Power return, digital return and signal return are not internally connected.

## Description (cont.)

shows the broad signal range over which the MP282A, with Analogic's MP2735-2 ADC, maintains low harmonic distortion.
The MP282A's sampling versatility makes it suitable for several applications. Its low crosstalk ( -86 dB ) multiplexer enables one ADC to accept data from two channels (for a stereo system). Samples from each channel can be taken simultaneously (at 55 kHz sampling frequency), essential for multitrack pulse code modulation (PCM) recording. The dual channel capability halves the number of ADCs necessary for multitrack recording, substantially reducing total analog function costs. Where higher speed sampling from a single channel (such as for vibration analysis) is required, sampling rate can reach 111 kHz .
Furthermore, the MP282A S/H features low noise ( -98 db ) and low jitter or aperture uncertainty (less than 0.4 ns ), critical parameters in S/H circuits for audio applications. The low cost MP282A audio PCM front end thus features the wide dynamic range, low noise, low sampling uncertainty and low harmonic distortion at high sampling rates, required for professional quality audio recording and other similar applications.

## PRINCIPLES OF OPERATION

## Automatic Gain Ranging

The MP282A's automatic gain ranging amplifier increases the dynamic range of an associated ADC by one bit, boosting the output of a 15 -bit converter to 16 bits ( 98 dB dynamic range). The following equation* gives dynamic range as a function of bits:
where $\mathrm{n}=$ number of bits,

$$
\begin{aligned}
\text { dynamic range } & \approx 1.76+6.02 \mathrm{ndB} \\
& =1.76+6.02(16) \mathrm{dB} \\
& =98.08 \mathrm{~dB}
\end{aligned}
$$

The MP282A accomplishes this gain ranging by sensing the magnitude of the signal passing from the multiplexer to the ADC (refer to Figure 1). When the input is equal to or greater than approximately $1 / 2$ full scale, the signal is amplified by a gain of 1 . When the input is less than approximately $1 / 2$ full scale, the MP282A applies a gain of 2. The state of the gain range bit appears as a digital signal or binary exponent for shifting the ADC output word.
The latch control holds a particular gain setting constant for the duration of the conversion time. (The same latch input is also used to control the channel select for sequential sampling.)

## S/H Mode Control Lines

Each of the two S/H circuits of the MP282A is controlled by an external command, permitting simultaneous or consecutive dualchannel sampling, or single-channel sampling. For simultaneous sampling, the signal from one channel remains in the hold mode, while the other passes through the multiplexer, gain-ranger and converter. When conversion of one signal is complete, the other is multiplexed, gain-ranged and converted.

[^3]
## Channel Select Line

The multiplexer used in the MP282A allows a single ADC to time-share samples from two S/H circuits, enabling simultaneous recording for a stereo system. The multiplexer control line, which determines whether channel 1 or 2 will be applied to the gain range amplifier, is enabled when the latch input is high and is latched on the high-to-low transition of the latch input.

## Gain Output

The logic which triggers the gain bit in the MP282A relies on a comparator (refer to Figure 1); an unknown input is compared with a locally generated reference which marks nominal $1 / 2$ full scale, acting as a trip point. An internal Zener diode regulates the trip point for symmetrical power supply voltages from $\pm 12 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$. The trip point has been set nominally lower than $1 / 2$ full scale so that scaling action never takes place at a critical point, even when normal tolerances are taken into account.


Figure 2. Harmonic Distortion of MP282A and 15-bit A/D Converter: no more than - 84 dB below signal for sampling frequencies of 50 kHz , within signal magnitude/frequency range shown.

## Applications of the MP282A in Tandem with a High-Speed A/D Converter

The MP282A's sampling versatility makes it suitable for a wide range of applications, from multitrack audio PCM systems, to selfcontained record and playback systems, to high-speed vibration analysis systems. Analogic's SHAD-2 card (see Figure 3) is especially designed to meet the 16-bit dynamic range, high speed, low distortion requirements of these audio applications. The SHAD-2 combines the MP282A and the MP2735-2 15-bit ADC with the logic for automatically shifting the mantissa and achieving 16 -bit dynamic range (please refer to SHAD-2 and MP2735 data sheets, available from Analogic Corporation).

## For Multitrack Audio PCM

Because professional audio studios perform multitrack recording, taking signals from separate microphones, adjusting them according to desired tonal quality and mixing them for the final product, signal sampling must occur at precisely the same time for each channel. The MP282A, with a high-speed ADC such as the MP2735-2, allows for simul-
taneous dual-channel sampling at high speed ( 57 kHz , see Figure 4). This is enabled by short acquisition time ( $3.5 \mu \mathrm{~s}$ ), short multiplexer settling time ( $2 \mu \mathrm{~s}$ ), fast auto range amplifier settling time ( $1.5 \mu \mathrm{~s}$ ) and short ADC conversion time ( $5.5 \mu \mathrm{~S}$ ).

## For Single-Channel Sampling

Where single-channel sampling is required, the MP282, in tandem with a high-speed ADC, offers high-speed sampling at 105 kHz (see Figure 5) suitable for vibration and spectrum analysis.
The MP282A dual-channel audio PCM front end and MP2735-2 ADC combine with Analogic's MP1926A 16-bit digital-to-analog converter and MP201A audio distortion suppressor to form a complete data conversion system, offering the exceptional end-to-end accuracy required by the audio engineer at relatively low cost. For more information, please send for data sheets on each of these products.


Figure 3. MP282A Application on SHAD-2 Card.


Figure 4. Timing Diagram for Simultaneous Sampling.


Figure 5. Timing Diagram for Single Channel Sampling.

TABLE OF CONTENTS ..... PAGE
Selection Guide. ..... 4-2
Glossary. ..... 4-3
MP2316 16-bit Floating Input Programmable Gain Analog Processor ..... 4-11
MP2321 3 1/2 Digit BCD Output Integrating A/D ..... 4-21
MP2322 12-bit Binary Output Integrating A/D ..... 4-21
MP2712D 12-bit, 5 s A/D ..... 4-25
MP2713C 13-bit, $10 \mu \mathrm{~s}$ A/D ..... 4-25
MP2714C 14-bit, $10 \mu \mathrm{~s}$ A/D ..... 4-25
MP2734 14-bit, $6.8 \mu \mathrm{~s}$ A/D ..... 4-31
MP2735-1 Low Distortion, 15-bit Audio Digitizer (S/H and A/D). ..... 4-37
MP2735-2 Low Distortion, 15-bit, $5 \mu \mathrm{~s}$ A/D. ..... 4-37
MP8014 14-bit, $10 \mu \mathrm{~s}$ Precision A/D. ..... 4-43
MP8015 15-bit, $15 \mu$ s Precision A/D ..... 4-43
MP8016 16-bit, $32 \mu$ s Precision A/D. ..... 4-43
MP8037 17-bit, 250 Hz Integrating A/D ..... 4-49
ANALDGIC
Analog-to-DigitalConverters

## SELECTION GUIDE

| MAJOR CHARACTERISTIC OR APPLICATION REQ'MT | PRIMARY <br> PARAMETER | SECONDARY PARAMETER | $\begin{aligned} & \text { RECOMMENDED } \\ & \text { MODEL NO. } \end{aligned}$ | DATA SHEET ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| High Accuracy ( $\pm 0.00075 \%$ to $\pm 0.006 \%$ FSR) | High Speed | Stability, Diff. Input Amp. (internaloptional) | MP8016 MP8015 MP8014 | $\begin{aligned} & 4-43 \\ & 4-43 \\ & 4-43 \end{aligned}$ |
|  |  | Low Harmonic Distortion Wide Dynamic Range | $\begin{aligned} & \text { MP2735-2 } \\ & \text { MP2735-1 } \end{aligned}$ | $\begin{aligned} & 4-37 \\ & 4-37 \end{aligned}$ |
|  |  | Good Overall Performance | $\begin{aligned} & \text { MP2734 } \\ & \text { MP2714C } \end{aligned}$ | $\begin{aligned} & 4-31 \\ & 4-25 \end{aligned}$ |
|  |  | External Accuracy, Integrating | MP8037 | 4-49 |
|  | Low Speed | Fully Isolated, Floating, Integrating, High CMRR Programmable Gain | MP2316 | 4-11 |
| Moderate Accuracy $\text { ( } \pm 0.01 \% \text { to }$ $\pm 0.1 \% \text { FSR) }$ | High Speed | Good Overall Performance | $\begin{aligned} & \text { MP2713C } \\ & \text { MP2712D } \end{aligned}$ | $\begin{aligned} & 4-25 \\ & 4-25 \end{aligned}$ |
| Moderate Resolution (8- to 13-Bits) | Low Speed | High CMRR, Binary Output | MP2321 | 4-21 |
|  |  | High CMRR, BCD Output | MP2322 | 4-21 |

## GLOSSARY OF TERMS

## ANALOG TO DIGITAL CONVERTERS

ABSOLUTE ACCURACY A measure of the the largest static difference between the actual output code and that predicted by the ideal transfer function, expressed as a percentage of full scale. In the case of a bipolar input range, e.g., -10 V to +10 V , the absolute accuracy is computed as a percentage of the the full range, or 20 V . Absolute accuracy measurements must reference a voltage standard traceable to the NBS with at least an order of magnitude lower uncertainty than the difference represented by one LSB.

AD or ADC An Analog to Digital Converter is a device that accepts an analog input signal and generates the corresponding digital output code determined by its transfer function. The ideal output is accurate to $\pm 0.5$ LSB as shown by the quantizing error curve in Figure 1. A black-box representation of an ADC is shown in Figure 2. There are a number of different ADC architectures in use. Two of the most popular are the successive approximation ADC and the integrating ADC. Speed is an inherent advantage of the successive approximation ADC. In other respects, including cost and reliability, the integrating ADC is generally superior.


Figure 1. Theoretical Transfer Function of an ADC (first three LSBs only).


Figure 2. "Black Box" Representation of an ADC.

CMRR The Common-Mode Rejection Ratio is a measure of the ability of an ADC with a balanced differential input to attenuate signals common to both the INPUT HI and the INPUT LO lines. See Figure 3 for configuration and formulae used to calculate CMRR.

$A_{1}$ and $A_{2}$ are the gain magnitudes between the output and inputs 1 and 2 .
$Z_{0,}$, and $Z_{02}$ are "common-mode" input im. pedances at terminals 1 and 2.
$\mathbf{Z}_{12}$ is "differential" input impedance between terminals 1 and 2.
$Z_{\text {, and }} Z_{2}$ are source impedances.
$C_{1}$ and $C_{2}$ are capacitances from the inputs to ground including input capacitance of the device itself.
$e_{s}=$ differential input signal $=\left(e_{1}-e_{2}\right)$
CMV $=$ Common-mode voltage $=e_{1}-e_{S}$
For the device alone:
CMRR $=20 \log _{10}\left[\frac{1}{A_{1}-A_{i}}\right]$
To calculate effective external CMRR:


EXTERNAL CIRCUIT SIMPLIFIED
where $\frac{1}{\omega C_{1}} \gg R_{1}$ and $\frac{1}{\omega C_{i}} \gg R_{i}$
and $R_{1}-R_{z}=\Delta R$ and $C_{1}-C_{i}=\Delta C$
then $C M R R \cong 20 \log _{10}\left[\frac{1}{\omega\left(R_{1} C_{1}-R_{;} C_{2}\right)}\right]$
or $C M R R \cong 20 \log ^{\circ}\left[\frac{1}{\omega(R, \Delta C+C, \Delta R)}\right]$
Figure 3. Common-Mode Rejection Configurations and Basic Formulae.

CONVERSION TIME The time required to complete a conversion over the specified operating range. Conversion time can be expressed as time/bit for a converter with selectable resolution or as time/conversion when the number of bits is constant.

DIFFERENTIAL LINEARITY A parameter that measures the difference between the theoretically uniform voltage bandwidth corresponding to a given code and the worst case actual voltage bandwidth for a given code. It is expressed either as a percentage of the ideal voltage bandwidth or as a fraction of an LSB. Figure 4 demonstrates differential linearity.


GAIN The slope of the transfer curve. Gain is generally user adjustable to compensate for long term drift.

INTEGRAL LINEARITY A measure of how closely the actual transfer function of the ADC adheres to the ideal (straight line) transfer function.

INTEGRATING ADC The integrating ADC uses a converter architecture with inherent advantages over successive-approximation including: lower cost for a given resolution, accuracy, linearity and stability; inherent monotonicity; high NMRR; true averaging of the signal during conversion; and the ability to autozero before every conversion cycle. The only real disadvantage is speed.

As Figure 5 shows, the conversion is accomplished in two integration phases. Because of this it is often called a "dual slope" integrating converter. Operation is as follows:

1) In the first phase of the conversion a clock pulse generator is started and the unknown analog input signal, $\mathrm{E}_{\text {in }}$ charges the integrator for a fixed time interval, $\mathrm{N}_{\mathrm{s}}$. At the end of the time interval the charge on the integrator is proportional to $\mathrm{E}_{\mathrm{in}}$.

Figure 4. Differential Linearity.


Figure 5. Fundamental Block and Timing Diagrams of Dual-Slope Integrating A/D Converter.
2) In the second phase the clock is reset and an internal standard reference voltage of opposite polarity, $\mathrm{E}_{\text {ref }}$, is substituted for the input signal. This discharges the integrator, at a known rate, to zero. The time it takes to discharge the integrator, $N_{B}$, is proportional to the input signal: $N_{R}=\left(E_{\text {in }} / E_{\text {ref }}\right) \times N_{s}$

Since $E_{\text {ref }}$ and $N_{s}$ are fixed by the design, $N_{R}$ will be linearly proportional to $\mathrm{E}_{\text {in }}$ and can be easily scaled to read directly.

As long as the components of the integrator and the clock-counter have good short-term stability, changes in their values do not decrease accuracy because both charging and discharging are affected to the same degree.
Integrating converters have a zero offset error which can be corrected by an autozeroing function. This is done by shorting the input electronically between conversions and storing the resultant integrator output on a capacitor. This stored voltage is fed back during conversion. A dual-slope integrating converter with autozeroing is called a "three-phase" or "three- step" converter: 1) autozero; 2) ramp up; 3) ramp down.
ITERATIVE ADC This uses an architecture that achieves high speed throughput approaching that of a flash converter with high ( 14 to 16 bit) resolution and relatively lower cost.
Figure 6 shows a very high speed, 15-bit resolution iterative converter. It uses a very fast, ultra-stable, 8 -bit successive approximation ADC; the first 8 MSB's of an ultralinear, high speed 16-bit DAC; and some switch-control logic. The sequence of operation is as follows:

1) The input signal is first converted to an 8 -bit digital code by the ADC.
2) The output of the ADC provides the highorder 8 bits. The output is also fed into the first 8 MSB's of the DAC where it is converted back to analog.
3) The output of the DAC is subtracted from the the input to the ADC.
4) The ADC performs a conversion on the difference to provide the low-order 8 bits.
5) The result of the first conversion is moved to the first 8 MSB's of the output register.
6) The result of the second conversion is moved to the 8 LSB's of the overlapping adder. The output register now contains the 15-bit converted result.

MONOTONICITY Is a characteristic that describes an aspect of the code to code progression from minimum to maximum input. A device is said to be monotonic if the output code continuously increases as the input signal increases, and if the output code continuously decreases as the input signal decreases. Figure 7 demonstrates nonmonotonic behavior.


Figure 7. Non-Monotonic Behavior.


Figure 6. Iterative A/D Converter Architecture.

MULTI-SPEED INTEGRATING ADC This is an integrating ADC that uses two or more integration speeds to: 1) increase the overall throughput rate; or 2) increase the resolution achievable at a dynamically limited conversion rate; or both. A converter of this type with two integration speeds is designated a "two speed, triple slope" converter.
Figure 8 demonstrates the sequence of operation of a multi-speed integrating converter. The first two ramps are much steeper than they would be in a dual-slope (singlespeed) ADC. The first ramp "acquires" the input signal very quickly. The second ramp integrates the reference voltage at the same rapid pace converting the integrator output to the MSB's, until the integrator output approaches a small percentage of full scale, typically $1 \%$. At that point the internal control logic reduces the reference voltage to $1 \%$ of its previous value and shifts the counter outputs to the LSB's. This effectively adds a vernier mode to the reference integration phase to provide greater precision at a faster rate.

The auto-zero function has been left out for clarity.

NMRR Abbreviation for Normal Mode Rejection Ratio. NMRR is a measure of the ability of a converter to attenuate unwanted signals, particularly noise at line frequency and its harmonics. As it pertains to an ADC it is the ratio of the transfer function of the signal component of interest to the transfer function of unwanted signal components (noise, line frequency pickup, etc.) as a function of frequency. It is is expressed in decibels as follows:

$$
\text { NMRR }=20 \log _{10}\left(K\left(f_{0}\right) / K(f)\right)
$$

where $K\left(f_{0}\right)$ is the transfer function $e_{\text {out }} / e_{\text {in }}$ at the frequency of the signal component of interest; $f_{0}$ is usually either 0 (dc) or a frequency consistent with the highest rate of change of the sampled input signal; and $\mathrm{K}(\mathrm{f})$ is the transfer function for the frequency at which NMRR is calculated - typically an integral multiple of the line frequency. Figure 9 shows NMRR as a function of frequency for a typical $A / D$ converter.


Figure 8. Block and Timing Diagrams of a Triple-Slope Integrating A/D Converter.


Figure 9. NMRR vs. Frequency of a Typical Integrating ADC.


Figure 10. Effect of Noise on Conversion Accuracy.


Figure 11. How Noise Affects Output-Code Transitions.

NOISE ERRORS These are errors in the output code caused by the presence of signals other than those one is trying to measure (see Figure 10). There are four main types of noise: 1) power line frequency (common mode ); 2) electrical interference on the input lines (normal mode); 3) noise generated by the signal conditioning circuitry; and 4) noise generated by the ADC during the conversion process. Common mode noise can be filtered out by the integrator or by signal conditioners in the front end. Normal mode noise can usually be reduced by low pass filtering. Internally generated noise is inherent to the converter and tends to be random in nature.

The characteristics of random noise can be described by statistical measures using the Gaussian distribution function and the dispersion value (sigma). See Figure 11. Noise generated by the ADC is specified over $\pm 3 \sigma$ in $\mu \mathrm{V}$ RMS. This number can be used to calculate the percentage of time during which the noise level will exceed the 1-bit threshold and cause an incorrect output code. The table in Figure 12 shows that if the 1-bit threshold is greater than the $\pm 3 \sigma$ noise level ( $p$-p threshold $=6 \times$ RMS noise level), a 1-bit or greater code error of either polarity will occur less than $0.3 \%$ of the time; a unipolar error will occur less than $0.15 \%$ of the time.

NOMINAL DIGITAL LEVELS Digital output signal level convention. This is typically binary or tristate, standard TTL, ECL, etc., or two specific voltage ranges.

OUTPUT CODE The output of an ADC may be one of a number of binary codes. The various codes include: unipolar binary, offset binary, one's complement and two's complement. Examples of these codes are shown in Figure 13, for a 12-bit device.

| PERCENT OF TIME RMS <br> NOISE LEVEL IS EXCEEDED <br> IN EITHER DIRECTION | PERCENT OF TIME RMS <br> NOISE LEVEL IS EXCEEDED <br> IN ONE DIRECTION | PEAK-TO-PEAK <br> NOISE LEVEL |
| :---: | :---: | :---: |
| $31.8 \%$ | $15.9 \%$ | $\pm 1 \sigma(2 \times \mathrm{RMS})$ |
| $20 \%$ | $10 \%$ | $\pm 1.64 \circ(3.3 \times \mathrm{RMS})$ |
| $4.6 \%$ | $2.3 \%$ | $\pm 2 \sigma(4 \times \mathrm{RMS})$ |
| $0.3 \%$ | $0.15 \%$ | $\pm 3 \sigma(6 \times \mathrm{RMS})$ |
| $0.02 \%$ | $0.01 \%$ | $\pm 3.89 \circ(7.8 \times \mathrm{RMS})$ |

Figure 12. Probability Table for Figure 11.

## Unipolar Binary:

For a device with a nominal FSR of 0 to 10 V ,
$V_{\text {max }}=111111111111=+9.9976 \mathrm{~V}$,
$\mathrm{V}_{\text {min }}=000000000000=0.0000 \mathrm{~V}$.
Offset Binary:
For a device with a nominal FSR of -10 V to +10 V ,
$\mathrm{V}_{\text {max pos. }}=111111111111=+9.9951 \mathrm{~V}$,
$\mathrm{V}_{\text {midrange }}=100000000000=0.0000 \mathrm{~V}$,
$\mathrm{V}_{\text {max neg. }}=100000000000=-10.0000 \mathrm{~V}$.
One's Complement:
For a device with a nominal FSR of -10 V to +10 V ,
$\mathrm{V}_{\text {max pos }}=011111111111=+9.9951 \mathrm{~V}$,
$V_{\text {midrange }}=\left\{\begin{array}{c}000000000000 \\ 111111111111\end{array}\right\}=0.0000 \mathrm{~V}$,
$\mathrm{V}_{\text {max neg }}=100000000000=-9.9951 \mathrm{~V}$.

## Two's Complement:

For a device with a nominal FSR of -10 V to +10 V ,
$\mathrm{V}_{\text {max pos }}=011111111111=+9.9951 \mathrm{~V}$,
$\mathrm{V}_{\text {midrange }}=000000000000=0.0000 \mathrm{~V}$,
$\mathrm{V}_{\text {max neg }}=100000000000=-10.0000 \mathrm{~V}$.
Figure 13. Most Common Binary Codes.
PARALLEL THRESHOLD (FLASH) ADC The flash converter uses an architecture that achieves very fast conversions. The input signal is simultaneously applied to a large number of comparators each of which represents a successively higher LSB step. The output of the comparators is decoded to a binary value representing the highest step level attained. A block diagram of a 4-bit flash converter is shown in Figure 14.

Because the number of components rises exponentially as the number of bits of resolution increases, the practical implementation of this architecture is limited to 8 -bits. Resolution can be significantly increased, without an exponential increase in the circuitry, by performing a sequencing operation: flash encode the signal to yield outputs for the MSB's; convert the MSB's to an analog value and subtract that from the original input; flash encode the new input through a similar circuit to yield outputs for the LSB's.

POWER SUPPLY COEFFICIENTS Also stated as power supply sensitivity, these specifications indicate how the power supply voltage affects various parameters of


Figure 14. "Flash" A/D.
the ADC, e.g., $\pm 0.001 \%$ per $1 \%$ change in power supply voltage.
QUANTIZING ERROR The conversion error equal to the smallest quantization level of the converter, $\pm 0.5$ LSB. This error is demonstrated in Figure 1.
RELATIVE ACCURACY This is a measure of the largest deviation of the converter's actual transfer function from the best straight line approximation of the actual transfer function, expressed as a percentage of full scale range. It comprises errors due to linearity, drift and circuit component tolerances:
e.g., $\pm 0.005 \%$ of FSR.

RESOLUTION - ACTUAL VS. AVAILABLE The available resolution of an N -bit converter is $2^{\mathrm{N}}$. This means it is theoretically possible to generate $2^{\mathrm{N}}$ unique output codes. Excessive internal noise and/or component drift can exclude the possibility of obtaining some output codes, reducing the actual resolution.

SUCCESSIVE APPROXIMATION ADC The successive approximation converter uses an architecture with inherently high throughput rates which converts high fre-
quency signals with great accuracy. A sample and hold type circuit can be used on the input to freeze these signals during conversion.
An N-bit successive approximation converter performs a sequence of tests comparing the input voltage to a successively
narrower voltage range. The first range is half full scale, the next is quarter full scale, etc., until it reaches the Nth test which narrows it to a range of $1 / 2^{\mathrm{N}}$ of full scale. The conversion time is fixed by the clock frequency and is thus independent of the input voltage.


Figure 15. Block Diagram of a Successive Approximation A/D.

TEMPERATURE COEFFICIENTS Changes in the operating temperature can affect a number of parameters including zero offset, gain and differential linearity. The temperature coefficient, or tempco, of one of these parameters is computed as the change in that parameter over a specified temperature range divided by the number of degrees in that temperature range. This yields an average tempco over the temperature range, not the worst case. Analogic tempco specifications are conservative and generally may be considered worst case values.

THROUGHPUT Maximum throughput is the greatest number of conversions per second at which an ADC will deliver its full rated performance. This is equivalent to the inverse of the sum of the multiplex time (if applicable), the S/H settling time and the conversion time.

ZERO OFFSET The input voltage required to yield an output code corresponding to zero. Provision is normally made to allow the user to adjust the zero offset.

## Description

The MP2316 is a floating input, self-powered, programmable gain analog converter-processor frontend that provides very high isolation between high resolution digital systems and large numbers of multiplexed analog input signals, especially in high common-mode voltage industrial environments such as process control, data acquisition systems and HVAC systems.
The MP2316 consists of an input stage, a 13 -gain programmable gain amplifier, a buffered dualslope integrating A/D, a precision reference, an isolated dc/dc converter, and all of the circuits required to complete the analog portion of a precision, 16-bit data acquisition system. The entire interface to the digital host system is through three transformer-isolated lines, two inputs for control and one output line for conversion results, which are in the form of an elapsed time between a pulse on one control line and the End-ofConversion (EOC) signal from the converter.
The high isolation of the analog inputs from the digital output is achieved by an intrinsic CMRR of 90 dB due to high-quality magnetic isolators, an overall CMRR of 150 dB , a 60 dB line frequency normal mode rejection ratio, and up to $\pm 500 \mathrm{~V}$ (ac peak and dc) of common mode isolation.
(continued)

## Features

- Programmable Gain Amplifier Provides 13 switch selectable full scale ranges from $\pm 10 \mathrm{mV}$ to $\pm 50 \mathrm{~V}$
- Floating Isolated Input Provides 500 V isolation from signal common to output common
- 150 dB Common Mode Rejection Ratio
- Guarded Input Allows multiplexing of input lead shields
- Time interval output proportional to input voltage
- $\pm 0.001 \%$ FSR Linearity Consistent performance with 16-bit resolution
- Isolated Output Voltages Provides power for sensors
- High Stability
$0.3 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ offset
$12 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ range
- Wide Power Supply

Requirement
+12 V to +15 V

- Small Size
$2^{\prime \prime} \times 3$ " $\times 0.51^{\prime \prime}$


## Applications

- Industrial Process Control

Heating, Ventilating and Air Conditioning (HVAC)

- Thermocouple Measurement
- Bridge Measurement

Data Acquisition Systems


Figure 1. MP2316 Functional Block Diagram.

## SPECIFICATIONS (Note 1.)

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted.)

## ANALOG INPUT

## Configuration

Floating, isolated, three wire
Full Scale Range (FSR)
Selectable ranges from $\pm 10 \mathrm{mV}$ to $\pm 50 \mathrm{~V}$ (See Table 1)

## Maximum Common Mode Voltage

$\pm 500$ Vdc or ac peak, minimum; (SIGNAL
RETURN to POWER RETURN) (see Note 2.)
Common Mode Rejection Ratio
150 dB minimum at 50 or 60 Hz , with
integration period within $\pm 0.05 \%$ of the power
line frequency
Input Impedance
FSR $\leq \pm 5 \mathrm{~V}$
$100 \mathrm{M} \Omega$ minimum
FSR $> \pm 5 \mathrm{~V}$
$1 \mathrm{M} \Omega$ nominal
Bias Current
300 pA, typical (see Note 3.)
Maximum Input
264 Vac rms continuous without damage (See Notes 2, and 4.)

## ISOLATED VOLTAGE OUTPUTS

## Output Voltage

+8 V nominal $(\mathrm{V}+$ );

- 10V nominal ( V - );
the amount of current drawn from $\mathrm{V}+$ must never exceed that drawn from $V$ - by more than 3 mA ; the total current drawn from both outputs must not exceed 6 mA


## ACCURACY

## Output Coding

Time interval proportional to the magnitude of the input voltage, plus sign decision based on polarity of input

## Resolution

Depends on count rate of external counter; up to 16 bits ( 15 magnitude bits plus sign bit)
achievable with appropriate external logic
Transfer Accuracy
Consistent with 15-bit resolution, with external calibration adjustment
Differential Non-linearity
$\pm 0.001 \%$ FSR, typical
Integral Non-linearity
$\pm 0.006 \%$ FSR, typical

## Offset

RTI
Externally adjustable to zero (see Note 5.)
RTO
$\pm 15 \mathrm{ppm}$ FSR, maximum (see Note 6.)

## Noise

$3 \mu \mathrm{~V}$ rms or 10 ppm FSR rms maximum, whichever is greater; assumes a $1.5 \mu \mathrm{~F}$ capacitor (Cx) across IN3 and SIGNAL RETURN per Figure 1

## STABILITY

## Range Tempco $\left(0^{\circ} \mathrm{C}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$

$\mathrm{FSR} \leq \pm 5 \mathrm{~V}$
$\pm 12 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typical,
$\pm 25 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ maximum
FSR $> \pm 5 \mathrm{~V}$
$\pm 20 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typical,
$\pm 30 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ maximum
RTI Offset Tempco ( $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ ) $\pm 0.3 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typical
Power Supply Rejection Ratio $\pm 0.002 \%$ FSR/percent power supply change
Recommended Recalibration Intervals 6 months

## DYNAMIC PERFORMANCE

Input Integration Time (Phase 1)
$1 / 60$ second $\pm 0.05 \%$ when synchronized to 60 Hz power line; $1 / 50$ second $\pm 0.05 \%$ when synchronized to 50 Hz power line (see Note 7.)
Full Scale Reference Integration Time (Phase 2) One-half the input integration time, nominal
Integrator Autozero Time (Phase 3)
$1.9 \mu \mathrm{~s}$, minimum, no maximum limit
Time to recover from Overrange Input $1.9 \mu \mathrm{~s}$ (see Note 8.)

## Overall Throughput Rate

Up to 37 measurements/second when synchronized to 60 Hz line; Up to 31 measurements/second when synchronized to 50 Hz line

DIGITAL INPUT/OUTPUT (see Figure 3)

## Input Lines

12 V CMOS compatible; negative pulses
Reset Line
A negative pulse on this line initiates the autozero phase; low level is active; 200 ns pulse width minimum, $3 \mu \mathrm{~s}$ maximum (see Note 9.)
Clock Advance Line (see Figure 6)
Negative-going (leading) edge is active; each pulse must be low for 100 ns minimum
First Pulse ( $\Phi 1$ )
Initiates input integration
Second Pulse ( $\Phi 2$ )
Strobes out the Polarity (decision) Pulse
Third Pulse ( $\varnothing 3$ )
Initiates reference integration

## Output Line

12V CMOS compatible, positive pulses; positivegoing (leading) edge is active; 100 ns minimum pulse width, $4 \mu \mathrm{~s}$ maximum; 100 ns rise and fall times, typical

## Polarity Pulse

Occurrence of an output pulse upon receipt of the polarity strobe ( $\Phi 2$ ) indicates that the input signal has a negative polarity; absence of a pulse at this time indicates positive polarity End-of-Conversion (EOC) Pulse
The elapsed time from the start of reference integration until EOC occurs is directly proportional to the magnitude of the input signal plus a constant $1 \mu \mathrm{~s}$, nominal, delay

POWER SUPPLY REQUIREMENTS
+12 V to +15 V
80 mA typical
125 mA maximum
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $80 \%$, non-condensing to $40^{\circ} \mathrm{C}$
Dimensions
$2.0^{\prime \prime} \times 3.0^{\prime \prime} \times 0.51^{\prime \prime}$
$(50.8 \times 76.2 \times 12.9 \mathrm{~mm}$ )
Shielding
Electrostatic 6 sides
Electromagnetic 5 sides
Case Potential
At the GUARD potential (equals common mode potential referenced to POWER RETURN)

## Notes:

1. Assumes a $1 \mathrm{k} \Omega$ gain adjust potentiometer is connected per Figure 1.
2. With $C x=1.5 \mu \mathrm{~F}$ installed between AUTOZERO RETURN and IN3, or with external diode input protection circuit per Figure.
3. 500 pA maximum at $40^{\circ} \mathrm{C}$; doubles every $10^{\circ} \mathrm{C}$ above $40^{\circ} \mathrm{C}$.
4. Input 1 to SIGNAL RETURN; INPUT 2 to SIGNAL RETURN.
5. $\pm 50 \mu \mathrm{~V}$ maximum, externally adjustable to zero via AUTOZERO RETURN (See Autozero Connection Section).
6. Externally adjustable via $1 \mu \mathrm{~s}$ nominal delay between Clock Advance $\Phi 3$ and start of user's counter.
7. Sign decision is made immediately prior to completion of the input integration phase.
8. Assumes that Reset is issued whenever EOC does not occur within the nominal full scale integration time.
9. Measured between $50 \%$ points.

## Description (cont.)

The programmable gain amplifier (PGA) provides a simple and flexible scheme for selecting a $\pm 10 \mathrm{mV}$ to $\pm 50 \mathrm{~V}$ full scale range while maintaining full isolation. Gain may be changed by applying the MP2316's own isolated auxiliary voltage outputs, via switches, to the gain programming pins (see GAIN PROGRAMMING). An auto-zero return from the PGA allows long-term system offset drifts to be essentially eliminated. Both the PGA and the integrator are auto-zeroed between conversions, so that dc offset is less than $50 \mu \mathrm{~V}$ RTI (adjustable to zero).
By fully implementing the most difficult (analog) functions, the MP2316 is an ideal starting point for designing a wide variety of low speed, precision data acquisition systems. By parallel connection of multiple units, higher throughputs can be achieved.

## USING THE MP2316

## Gain Programming

The three gain stages shown in Figure 2 allow selecting any of the 13 gains from 0.05 to 250 inclusive, providing full scale ranges from $\pm 50 \mathrm{~V}$ to $\pm 10 \mathrm{mV}$. The external potentiometer connections shown allow fine adjustment of any selected range. For example, a $1 \mathrm{k} \Omega$ pot provides a $\pm 4.5 \%$ adjustment, more than adequate for obtaining either $\mathrm{a} \pm 1.000 \mathrm{~V}$ FSR or $\mathrm{a} \pm 1.024 \mathrm{~V}$ FSR with one basic gain selection.
Each of the gain stages may be externally configured using either switches, relays, opto-isolators, or by any other convenient means available in the host system. The module's own floating output voltages may be used for controlling the MP2316's internal solid-state switches, A through $H$, per the inset of Figure 2.
External gain and ortset adjustment potentiometers, if used, can be switched similarly . It is possible, then, to configure and trim the MP2316 to provide nearly any desired full scale range(s) and/or any desired range-to-range absolute accuracy, while maintaining full isolation. When the maximum obtainable accuracy is required, it is recommended that each range be calibrated individually.


|  | Gain Select $^{\prime}$ |  |  |  |  |  | Pin Connections ${ }^{2}$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | ---: |
| FSR $^{1}$ | A | B | C | D | E | F | H | $\mathrm{G}_{1}{ }^{3}$ |
| $\pm 10 \mathrm{mV}$ | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| $\pm 20 \mathrm{mV}$ | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 |
| $\pm 50 \mathrm{mV}$ | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| $\pm 100 \mathrm{mV}$ | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| $\pm 200 \mathrm{mV}$ | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 |
| $\pm 1 \mathrm{~V}$ | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |
| $\pm 2 \mathrm{~V}$ | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 1 |
| $\pm 2.5 \mathrm{~V}$ | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| $\pm 5 \mathrm{~V}$ | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |
| $\pm 10 \mathrm{~V}$ | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0.1 |
| $\pm 20 \mathrm{~V}$ | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0.1 |
| $\pm 25 \mathrm{~V}$ | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0.1 |
| $\pm 50 \mathrm{~V}$ | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0.1 |

Table I. MP2316 Range Programming

## NOTES TO TABLE I

[^4]
## INPUT CONSIDERATIONS Input Connections

For full scale ranges larger than $\pm 5 \mathrm{~V}$, the analog input signal is connected to IN 1 , and IN2 is externally connected to SIGNAL RETURN. In this configuration, the input stage's gain of 0.1 allows use with input signals having full scale ranges up to $\pm 50 \mathrm{~V}$.
For full scale ranges nominally $\leq \pm 5 \mathrm{~V}$, the analog input signal is connected to IN2, which provides unity gain. IN1 should be tied to IN2 to prevent noise pick-up. By connecting a $1.5 \mu \mathrm{~F}$ capacitor between IN3 and ground, high frequency noise filtering on any range can be accomplished. The lowpass filter thus formed ( $\mathrm{RC}=900 \mathrm{k} \Omega / 1.5 \mu \mathrm{~F}$ for $\operatorname{IN} 1$ and $\mathrm{RC}=100 \mathrm{k} \Omega / 1.5 \mu \mathrm{~F}$ for IN 2 ) will reduce the usable input signal bandwidth.

## Case Potential

The Case (GUARD) pin may be tied to SIGNAL RETURN as shown in Figure 1, and/or to the lead shield, if one is used. If


No Normal-Mode Noise Present (Observe CMOS Handling Precedures)


Normal Mode Noise Present
${ }^{*} \mathrm{C}_{\mathrm{X}}=0.1 \mu \mathrm{~F}$ for thermocouple inputs
$=1.5 \mu \mathrm{~F}$ minimum for 264 V rms ac input protection
$=0.75 \mu \mathrm{~F}$ minimum for 130 V rms ac input protection

Figure 3. Input Configurations.


Figure 4. Diode Input Protection Circuit.
lead shields for different channels carry different potentials in the system, and the shields, are not multiplexed to the Case pin, it is recommended that each shield be tied to local earth at its sensor, while the Case pin is tied to SIGNAL RETURN. Optimum system performance will generally be obtained by using twisted shielded pair for each channel.

## Input Overvoltage

The Specifications call out a maximum continuous input without damage of 264 Vac rms. This assumes a value for Cx of $1.5 \mu \mathrm{~F}$ connected between the IN3 and SIGNAL LO pins as shown in Figure 2. Failure to use this capacitor will result in damage to the unit under the specified input conditions. It should be noted that this capacitor will
form a low-pass filter on the input ( $\mathrm{RC}=900 \mathrm{k} \Omega / 1.5 \mu \mathrm{~F}$ for INPUT 1 and RC $=100 \mathrm{k} \Omega / 1.5 \mu \mathrm{~F}$ for INPUT 2). This will reduce the usable signal bandwidth at the input to the A/D.

## Noise

The Specification for noise performance assumes a value of $1.5 \mu \mathrm{~F}$ for Cx . If the capacitor is not used to low-pass filter the input, noise in excess of the specification can occur.
The input configuration can be modified depending on whether or not normal mode noise is present. See Figure 3.

## Thermocouple Inputs

When used with thermocouple inputs, the value of Cx between IN3 and SIGNAL LO should be $\geq 0.1 \mu \mathrm{~F}$ to limit the input response to approximately 12 Hz .

## Input Protection

It is recommended that the diode input protection circuit in Figure 4 be used to protect the MP2316 from large common mode and normal mode spikes, such as those that occur when relay contacts are switching signal sources to the MP2316 input.

## Autozero Connection

Using the AUTOZERO RETURN, offsets that may occur between the SIGNAL RETURN and the common of the sensor subsystem (see Figure 5) can essentially be eliminated. The maximum offset that can be eliminated is $20 \%$ of the selected full scale range if the input voltage divider gain is set at unity. For larger full scale ranges where the input divider is set at 0.1, the maximum offset eliminated is $2 \%$ of the full scale range. A small signal potentiometer installed between SIGNAL RETURN and AUTOZERO RETURN can be used to zero the MP2316's small ( $\pm 50 \mu \mathrm{~V}$ RTI maximum) offset, per Figure 5.

## Isolated Output Voltages

The MP2316 is provided with isolated voltage outputs of +8 V and -10 V nominal. These can be used to power strain gauges, or other sensors. It is important to limit the total current drawn from both outputs to 6 mA or less, and to ensure that the amount of current drawn from the $\mathrm{V}+$ output never exceeds that drawn from the V - output by more than 3 mA .


Figure 5. The MP2316's Three-Wire Input Configuration. Essentially Eliminates Long Term Sensor System Offsets.


Figure 6. MP2316 Timing Diagram.

## Reference Connections

The MP2316 contains its own isolated precision reference source $(-4.75 \mathrm{~V})$. This reference is brought out as a test point (INTERNAL REFERENCE OUT), and should be jumpered to REFERENCE IN for most applications.
For true ratiometric applications, a floating external supply that excites the system's sensors may also be applied, via a buffer, to REFERENCE IN (while INTERNAL REFERENCE OUT floats). If used, such a reference should be $-4.75 \mathrm{~V} \pm 10 \%$.


Figure 7. Application Diagram - Functional Block Diagram of MP2316 External Control Logic, Implementable in either Hardware/Software.

(Note: pulse polarity inverted for display only)
Figure 8. MP2316 Common Mode Rejection Ratio Test ( 360 V rms CMV, 37 Hz measurement rate, $\pm 50 \mathrm{mV}$ FSR). The upper trace shows the Polarity and EOC pulses for a zero volt input with no common mode voltage present. The lower trace shows the same pulses when 360 V rms of CMV is present, also with a zero volt input signal. A time exposure is used to display both conversion results. In the lower trace, EOC occurs $0.5 \mu$ s later than in the upper trace. At 16 -bit resolution, this shift is equivalent to 2 LSB's, or only $3 \mu \mathrm{~V}$ common mode error on a full scale range of $\pm 50 \mathrm{mV}$ resulting from 360 V rms CMV. Thus the CMRR measured is greater than 160 dB , 10 dB better than the MP2316 specification!

## Timing and Control

The Timing Diagram (see Figure 6) shows the operation of a multiplexed data acquisition system that uses the MP2316; the Ap-
plications Diagram (Figure 7) indicates the corresponding external logic functions. These functions can be implemented via either hardware or software, depending on the economics of the host digital system. The operational timing contains three phases summarized as follows:

1. Integrate the input signal;
2. Integrate the precision reference for a maximum of one-half of the input integration time;
3. Autozero the integrator.

Operation during each of these phases is described below, starting with the autozero phase.

## Autozero Phase

Each measurement cycle begins with a pulse on the RESET line, which initiates autozeroing of the precision integrator. A minimum of 1.9 ms should be allowed for autozeroing. If the MP2316 input is overranged, the autozero circuit will ensure recovery within this time.

## Input Integration Phase

When the first pulse ( $\Phi 1$ ) is received on the CLOCK ADVANCE line, the autozero cycle terminates and integration of the input signal begins.
The second pulse on the CLOCK ADVANCE line (\$2) strobes out the results of a polarity test which the module performs on the input signal during the integration. This second pulse should occur from $10 \mu \mathrm{~s}$ before the end of this signal integration period. If the input signal is negative, the MP2316 issues a pulse on the EOC/POLARITY line nominally within $1 \mu \mathrm{~s}$ of receipt of the $\Phi 2$ pulse. If the input signal is positive, the MP2316 issues no pulse on the EOC/ POLARITY line at this time.

## Reference Integration Phase

The third pulse is applied to the CLOCK ADVANCE ( $\Phi 3$ ) from $4-16 \mu \mathrm{~s}$ after the $\Phi 2$ pulse, at which time the module automatically switches the integrator's input to the precision reference, and the pre-amplifier's input to the AUTOZERO RETURN line. Because the preamplifier is disconnected from the integrator, any gain and/or multiplexer switching needed for the next measurement may be made during this phase without affecting the accuracy of the reference integration.

Within nominally $1 \mu$ s after receiving $\Phi 3$, the MP2316 begins discharging the integration capacitor via a precision reference of opposite polarity from that of the input signal. If the magnitude of the integrated signal is within the integrator's full scale range, the capacitor will be fully discharged during this phase, causing a pulse to appear on the EOC/POLARITY line. The table in Figure 8 shows the linear relationship between (1) the integrated input signal, and (2) the elapsed time between the $\Phi 3$ and EOC pulses.
If the magnitude of the integrated signal exceeds the integrator's full scale range, EOC will not be issued. In such a case, a pulse must be issued on the RESET line after the maximum reference integration time has elapsed; this will cause the overrange condition to be cleared by the autozero circuit.

## Timing Resolution and Code Conversion

The resolution of the analog-to-digital conversion may be established at any desired level continuously up to 16 binary bits or 4 full BCD digits plus sign. Linearity will be $0.001 \%$ FSR regardless of the resolution selected. Selection of resolution is accomplished by specifying the external counter's clock rate in accordance with the following relationship:

$$
\text { Fclock }={\frac{B^{(n-1)}}{T} \text { at } \pm \text { full scale) }}^{\text {(the maximum col }}
$$

where n is the desired resolution (including the sign bit), $B$ is the counting base (normally 2 or binary) and $T$ is the maximum reference integration time. As an example, for 15-bit binary resolution with 60 Hz power line:

$$
\text { Fclock }=\frac{2^{(15-1)}}{8.33 \mathrm{~ms}}=1.966 \mathrm{MHz}
$$

A 2 MHz clock may be used for convenience in this case, which will slightly increase the resolution with no change in linearity. As a second example, for a full 4 digit BCD display plus sign with 50 Hz power line:

$$
\text { Fclock }=\frac{10^{(5-1)}}{10.0 \mathrm{~ms}}=1.00 \mathrm{MHz}
$$

Other coding, such as two's complement, can be established by simple logic at the counter's output.

## Calibration

The MP2316 is inherently stable, and in most applications, will not require recalibration more often than every six months. When recalibrating the system, adjust offset before adjusting range.

## Offset Adjustment

RTI offset may be adjusted to zero via external potentiometer installed between AUTOZERO RETURN and the SIGNAL RETURN (see Figure 9); RTO offset may be adjusted via a time delay between $\Phi 3$ and the start of the external software or hardware counter. With a OV input signal, adjust the offset signal via the selected method(s) so that the reference integration time is within the desired tolerance (e.g., within one or two clock periods of the counter start.)

## Range Adjustment

Range may be adjusted via a potentiometer installed between the PGA OUTPUT pin and the INTEGRATOR INPUT pin (see section on gain programming). It is recommended that an input voltage of roughly $10 \%$ less than full scale be used during this adjustment procedure to avoid overrange conditions during adjustment. Adjust the range so that the dual-slope-derived reference integration time, as shown by an external counter, is proportional to the input voltage to within the desired tolerance.


Figure 9. Optional RTI Offset Compensation.

## ORDERING GUIDE

Specify MP2316

Notice: The Analogic MP2316 is protected under one or more of the following U.S. patents and others pending: 3,051,939; 3,054,910; 3,316,547; 3,649,924; 3,750,146.


Figure 10. Mechanical \& Pinout.


## ANALOGC.

## MP2321/2322

## Isolated, Floating <br> 3112-Digit BCD or 12-Bit <br> Binary Integrating A/D Converters

## Description

Analogic's MP2321 and MP2322 are high performance, low cost extremely versatile integrating analog-todigital converters that feature well isolated, floating, guarded, bipolar analog inputs. They are designed for use by OEM's in a broad range of recording, analytical and industrial control instrumentation systems. These converters reject high common mode levels of $\pm 300 \mathrm{~V}$ with respect to system ground, are accurate to $0.05 \%$, exhibit an accuracy tempco that is less than $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ of reading, and require but a single 5 V supply. They therefore allow economical, extremely accurate and highly stable $31 / 2$ BCD digit or 12 -bit (sign and magnitude) data transformation in severe common mode environments, a capability frequently required in process control instrumentation and single current loop remote indicator systems. The DTUTTL compatible output and control lines provided by these digitizers permit easy automatic examination of the data by local and remote displays and printers, and facilitate control of the data acquisition by computer-oriented hardware.

Figure 1. Functional Block Diagram.

The MP2321 and MP2322 are particularly qualified as the nuclei of measurement systems. The isolated floating front end allows digital conversion of remote signals which may not be referred to ground; and the computer-compatible control and status connections permit easy interfacing to ancillary equipment. Additionally, these converters are easily customized for use in a gamut of OEM applications simply by selecting the proper pins for the following operations: Ratiometric A/D conversion, useful for automatic compensation of transducer excitation supply drift, or standard digitization (see Figs. 4 and 6); control of the conversion rate - up to 100 readings per second (see Figs. 3 and 5), or conversion initiation by external command (see Figs. 5 and 7) so that digitizations occur exactly when required, and for the MP2322, a choice of output binary codes (see Fig. 9).

## Features

## - True Floating Isolated Inputs

- 2 Versions

BCD Outputs - MP2321
Binary Outputs - MP2322

- 600V p-p Common Mode Voltage
- Automatic Zero

Negligible Offset

- Ratiometric Conversion Available
- Only Single 5 Vdc Power Supply Required
Floating Supply Built-in
- Up to 100 Conversions/second
- Low Cost
- Shielded Metal DIP Case

2" x 4 " $\times 0.49$ "

## Applications <br> - Medical Instrumentation Systems <br> - Industrial Transducer Digitization <br> - Analytical Instruments <br> - Industrial Process Control



## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

```
ANALOG INPUT
Configuration
Bipolar, floating, isolated, guarded and shielded
Full Scale Range
MP2321: }\pm1.999\textrm{V}\mathrm{ or }\pm199.9\textrm{mV}\mathrm{ standard, +1V
or + 100 mV Ratiometric
MP2322: }\pm2V\mathrm{ or }\pm1\textrm{V}\mathrm{ or }\pm200\textrm{mV}\mathrm{ or }\pm100\textrm{mV
depending on output code (see Fig. 9) standard;
+1V or }100\textrm{mV}\mathrm{ ratiometric
Input Impedance
500 M\Omega nom.
Bias Current
1 nA nom.
Common Mode Voltage (Between SIG RTN and
DIG RTN)
\pm300 Vdc, }600\mathrm{ Vac p-p
Common Mode Rejection (With 1 K}\Omega\mathrm{ Unbalance)
120 dB min.@ dc, 100 dB min.@ 60 Hz, 60 dB
min. @ 1 kHz
```


## ACCURACY

## Resolution

MP2321: 1 part in 2000 counts, $31 / 2$ BCD digits plus sign
MP2322: 1 part in 2048 counts, 11 bits plus sign
Relative Accuracy (Linearity)
$0.05 \%$ rdg $\pm 1$ count
Offset
$50 \mu \mathrm{~V}$ typ., $75 \mu \mathrm{~V}$ max.
Monotonicity
Guaranteed
STABILITY
Range Tempco
50 ppm rdg $/{ }^{\circ} \mathrm{C}$ max. for 1 V or 2 V FSR
$75 \mathrm{ppm} \mathrm{rdg} /{ }^{\circ} \mathrm{C}$ max. for 100 mV or 200 mV FSR
Offset Tempco
$1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.

## CONVERSION

## Technique

Dual slope bipolar integration with auto-zero; complete conversion in each cycle
First Integration Time
2 ms nom. See timing diagram
Auto-zero Time
3 ms min. See timing diagram
Reading Rate
Internal trigger: 4/s nom.
External trigger: 100/s max. See Fig. 5

## CONTROL INPUTS

## External Trigger

TTL/DTL compatible
Negative pulse $1.5 \mu \mathrm{~s}$ min., 1.8 ms max.
See Fig. 5

## Hold

Conversion held by connecting a $47 \mathrm{k} \Omega$ resistor between INT RATE and DIG RTN. See Fig. 7
Line Frequency Sync
Connecting 10 Vac p-p max. at power line frequency to sync input will minimize effect of normal mode noise

DIGITAL OUTPUTS
Compatibility
TTLDTL compatibility, sinks 5 mA max. (3 loads)
Output Data Codes
MP2321: Bipolar BCD (sign and magnitude)
MP2322: Bipolar binary (sign and magnitude) offset binary, and 2's complement. Pin selectable. See Fig. 9

## Polarity

High (logic "1") level indicates positive input signal
Overload
High (logic "1") level indicates input signal amplitude greater than FSR

## Convert

High level indicates conversion in process. Negative going transition signifies end of conversion. See timing diagram. Note: Internal clock is available; consult factory.

POWER SUPPLY
$+5 \mathrm{Vdc} \pm 5 \%$
300 mA
ENVIRONMENTAL \& PHYSICAL
Operating Temperature
$-10^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-15^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $95 \%$ non-condensing
Electrical Shielding
RFI 6 sides; EMI 5 sides
Overvoltage Protection (Between SIG IN and SIG RTN)
$\pm 15 \mathrm{~V}$ maximum input without damage
Packaging MP232X
2" x 4" $\times 0.49$ " ( $50.8 \times 101.6 \times 12.45 \mathrm{~mm}$ ) see Fig. 10

## CALIBRATION AND OPERATION

## Calibration

The Models MP2321 and MP2322 self-zeroing A/D converters require only a single adjustment for complete calibration to specified accuracy. RANGE is calibrated by applying a voltage level such as +1.9985 V or +0.9985 V , or +199.85 mV or +99.85 mV (depending on output code and model, see Fig. 9) to the input, and trimming the RANGE control so that the LSB only of the output code alternates equally between " 1 " and " 0 ".

## Internal Triggering Control

Adjustment of the built-in triggering rate (4 conversions/s) may be implemented by the circuitry described in Fig. 3. The sampling rate is approximately $1.44 / \mathrm{R}_{\mathrm{T}} \mathrm{C}_{\mathrm{T}}$, where $\mathrm{R}_{\mathrm{T}}$ is $\mathrm{R}_{1}$ in parallel with the internal $82 \mathrm{k} \Omega$ and $\mathrm{C}_{\mathrm{T}}$ is $\mathrm{C}_{1}$ in parallel with the internal $3.3 \mu \mathrm{~F}$.


Figure 3. Connections for Adjusting Internal Triggering Rate.

## Hold or Convert on Command

Holding or continuously converting the analog input can be selected by means of the circuitry presented in Figure 7. When the CONVERT/HOLD switch is in the HOLD position, the last conversion will be "held" indefinitely; in the CONVERT position, the analog input will be digitized at the rate selected by the methods shown in Figures 3 and 5.

## External Triggering

Triggering the conversion cycle externally is implemented by means of the external circuitry shown in Figure 5, and applying a negative pulse (logic " 1 " to logic " 0 ") $1.5 \mu \mathrm{~s}$ min . and 1.8 ms max. duration. The negative going transition initiates the conversion cycle. The maximum conversion rate to specified accuracy is 100/s.

## Conversion Operation Selection

The MP2321 and MP2322 can perform standard or ratiometric AID conversions by implementing the connections described below.


Figure 2. MP2321 and MP2322 Timing Diagram.


Figure 4. Connections for Standard AID Conversions.


Figure 5. Connections for External Triggering.


Figure 6. Connections for Ratiometric A/D Conversion.


Figure 7. Connections for Commanding Hold or Continuous Conversion.


Figure 8. Typical Connections Showing Use of MP2321 GUARD to Minimize Pick-Up Noise.

## Typical Hook-Up Connections

In a typical application the GUARD may be used to minimize stray pick-up noise and enhance common mode rejection by wiring it to the shield of the signal source leads.

## Output Code Selection

The output code for Model MP2321 is $31 / 2$ digits BCD plus sign. The output code for Model MP2322 is pin selectable. Figure 9 presents the appropriate connections and full scale values for the available codes.

| Converter Model | *F Full Scale Input Voltage | Output Code | Jumper Connections |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Bipolar BCD } \\ & 31 / 2 \text { BCD Digits + Sign } \\ & \text { (MP2321) } \end{aligned}$ | $\begin{array}{r} +1.999 \\ 0.000 \\ 0.000 \\ -1.999 \end{array}$ | 11100110011001 <br> 10000000000000 <br> 00000000000000 <br> 01100110011001 <br> -P. D4B1, D388, ...D181 | None |
| $\begin{aligned} & \text { Bipolar Binary } \\ & 11 \text { Bits + Sign } \\ & \text { (MP2322) } \end{aligned}$ | $\begin{array}{r} +1.999 \\ 0.000 \\ 0.000 \\ -1.999 \end{array}$ |  | Connect <br> AUTO ZERO RET to <br> SIG RTN |
| $\begin{aligned} & \text { t Offset } \\ & \text { Binary - } 11 \text { bits } \\ & \text { (MP2322) } \end{aligned}$ | $\begin{array}{r} -0.999 \\ 0.000 \\ +1.000 \end{array}$ |  | Connect AUTO ZERO RET to RATIO REFIN |
| $\begin{aligned} & \dagger \text { Two's } \\ & \text { Complement - } 11 \text { bits } \\ & \text { (MP2322) } \end{aligned}$ | $\begin{array}{r} -0.999 \\ 0.000 \\ +1.000 \end{array}$ |  | $\begin{aligned} & \text { Connect } \\ & \text { AUTO ZERO RET } \\ & \text { to } \\ & \text { RATIO REF IN } \\ & \hline \end{aligned}$ |

Figure 9. Table Showing Available Full Scale Value and Jumper Connection Required for Selected Output Code.
** For 100 mV or 200 mV units divide input voltage by 10

* P: polarity (or sign) bit; D4B1: fist bit of the fourth digit; NSB: most significant bit
$\dagger$ Reverse signal input leads to obtain true 2's complement or offset binary output


Figure 10. MP2321 and MP2322 Outline Drawing.
ORDERING GUIDE

| For | Specify |  |
| :---: | :---: | :---: |
| 31⁄2 Digit BCD Output | MP2321* | *For 1 V and 2V units. To specify 100 mV and |
| Sign11 Bit Binary + Output | MP2322* | 199.9 mV FSR, add "-01" to ordering code. |
|  |  | For example a "MP2321-01" converts |


analoge.

## MP2700

SERIES
AID Converters

## Description

The MP2700 Series are general purpose A/D converters offering high speed, accuracy and stability, with resolutions of 12, 13 and 14 bits. All of the converters in the Series feature both parallel or serial (NRZ) data outputs, internal offset and gain adjustment potentiometers, and pin-selectable input voltage ranges.
Each model in the MP2700 Series is packaged in a 2" x 4" metal can that provides RFI shielding on six sides, and EMI shielding on five.

## Features

- Pin-selectable Input Ranges 0 V to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ and 0 V to +5 V .
- Parallel and Serial Data Outputs
- Can be short-cycled for increased throughput
- Buffered outputs

Internal Offset and Range Adjustment Potentiometers

## Applications

## - General Purpose Analog Computer Interface <br> - Multi-channel Process Control <br> Analytical Instrumentation <br> - Telemetry



Figure 1. MP2712D Functional Block Diagram.
(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG INPUT

Input Voltage (Full Scale Range)
0 to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$, or 0 to +5 V
Input Impedance
$125 \Omega / \mathrm{V}$ of FSR

## ACCURACY

Absolute Accuracy
(Traceable to NBS Standards)
Calibrated to:
0.015\% max. (MP2712D),
0.009\% max. (MP2713C),
0.007\% max. (MP2714C)

Relative Accuracy
$\pm 0.012 \%$ max. (MP2712D), $\pm 0.006 \%$ max. (MP2713C \& MP2714C)
Differential Linearity
$\pm 0.012 \%$ FSR max. (MP2712D), $\pm 0.006 \%$ FSR max. (MP2713C \& MP2714C)
3oNoise (Includes Reference Noise)
$0.01 \%$ FSR p-p, max. referred to input (MP2712D),
$0.005 \%$ p-p, max. referred to input (MP2713C \& MP2714C)

## Monotonicity

Guaranteed

## STABILITY

Tempco of Differential Linearity
$< \pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max.
Tempco of Gain
$< \pm 12 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. (MP2712D),
$< \pm 10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. (MP2713C),
$< \pm 8 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. (MP2714C)

## Tempco of Offset

$< \pm 12 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max.
Clock Stability
$\pm 0.1 \% /{ }^{\circ} \mathrm{C}$
Power Supply Sensitivity
$\pm 0.0012 \% / \%$ max. change in supply voltage
Recommended Recalibration Interval
6 months
Repeatability
Defined by Noise and Accuracy

## CONVERSION TIME

## Total Conversion

$5 \mu \mathrm{~s}$ max. (MP2712D),
$10 \mu \mathrm{~s}$ max. (MP2713C \& MP2714C)

Serial Output (see Timing Diagram)
Negative pulses simultaneous with clock pulse
for "0". Max. Ioad 30 pF
Coding
Pin selectable

## Trigger Input

$3.5 \mathrm{~V} \pm 1 \mathrm{~V}$ pulse. See Timing Diagram
Trigger Input Transition
$\leq 200$ ns ( $90 \%$ to $10 \%$ )
End of Conversion, EOC
"1" to " 0 " level transition, nominally 100 ns after LSB data pulse. TTL compatible, 9 loads.
(See Timing Diagram)
EOC Transition
$\leq 20 \mathrm{~ns}$ ( $10 \%$ to $90 \%$ )

## Clock Output

TTL compatible (See Timing Diagram)
Clock Output External Capacitance
30 pF maximum allowable

## Selectable Word Length

2 to 12 bits (MP2712D),
2 to 13 bits (MP2713C),
2 to 14 bits (MP2714C)
POWER SUPPLY
$+15 \mathrm{~V} \pm 3 \%$
60 mA, max.
$-15 \mathrm{~V} \pm 3 \%$
60 mA, max.
$+5 \mathrm{~V} \pm 5 \%$
300 mA , max.
ENVIRONMENTAL, PHYSICAL, \& RELIABILITY
Maximum Input Without Damage
$\pm 200 \%$ of Full Scale Range

## Missing Codes

None
Warm-up Time to Stated Accuracy
$<5$ minutes
Operating Temperature
$0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Electrical Shielding
RFI 6 sides; EMI 5 sides
Packaging MP27xx
2" x 4" x 0.44" Metal Case
( $51 \times 102 \times 11.3 \mathrm{~mm}$ )

## DIGITAL SIGNALS

## Parallel Output (see Timing Diagram)

Binary B1, B1 to B12 (MP2712D),
Binary $\overline{\mathrm{B1}}, \mathrm{~B} 1$ to B 13 (MP2713C),
Binary B1, B1 to B14 (MP2714C)
Standard TTL, 2 unit load/line

## USING THE MP2700 SERIES <br> Input Voltage Range Selection

Three input pins are provided to allow user selection of one of four standard input voltage ranges. "IN 1", "IN 2", and "IN 3" must be connected in accordance with the following tables and illustrations to select the desired full-scale range.

## Output Word Length Selection

The number of bits in the output word is pin selectable. To operate the ADC at its full capacity, $\mathrm{B}(\mathrm{N}+1)$ must be connected to WRD LTH IN. To operate the converter at less than its full digital output capacity, WRD LTH IN must be connected only to the terminal identified as one bit more than the desired number of bits out. EXAMPLE: When the ADC is operated as an 8-bit converter, connect WRD LTH IN to B9 only. Refer to the accompanying chart for the binary output coding.

## CALIBRATION

## Zero Offset Calibration

To recalibrate the OFFSET:

1. Apply input voltage shown in accompanying table and,
2. Adjust the OFFSET control so that the LSB of the output code 100...00/1 for bipolar units and $00 . .00 / 1$ for unipolar units alternates equally between " 1 " and " 0 ". Offset should be readjusted whenever the selected full scale range is changed.

Zero Offset should be calibrated before recalibrating RANGE.

## Range Calibration.

Internal: A built-in 0.1\% adjustment of the full scale voltage is provided. To recalibrate the RANGE:

1. Apply input voltage shown in the accompanying table and,
2. Adjust the RANGE control so that the LSB of the output code, 111...110/1 ( $\mathrm{B} 1, \ldots \mathrm{~B}(\mathrm{~N})$ ), alternates equally between " 1 " and " 0 ". RANGE should be readjusted whenever the selected full scale range is changed.

## External Connection

A wider range adjustment may be implemented by connecting a $20 \mathrm{k} \Omega$ poten-
tiometer between "+10V REF" and "ANA RTN"; and connecting a resistor, R, between the wiper arm of the $20 \mathrm{k} \Omega$ potentiometer and "RANGE ADJ". The adjustment range will be $+5 \%$ to $-0.3 \%$ for $R=470 \mathrm{k} \Omega$ and $+5 \%$ to $-2.8 \%$ for $R=47 \mathrm{k} \Omega$. This latter value permits the calibration of a unit to be set for the socalled binary adjusted scale factors of 10.24 V or 5.12 V .

## Typical Application

An MP2712D Analog-to-Digital Converter is shown connected to a high speed-high resolution multiplexed data conversion subsystem. The subsystem provides 12 -bit data conversion at thru-put rates up to 200,000 conversions per second.


Figure 2. Jumper Connections for Input Voltage Range Selection.


Figure 3. Typical Application of MP2712D A/D Converter.

| INPUT RANGE CONNECTION TABLE |  |  |  |
| :---: | :---: | :---: | :---: |
| Nominal Full Scale Range | MP2710D, MP2712C, MP2713C, MP2714C |  |  |
|  | IN 1 | IN 2 | IN 3 |
| $\begin{gathered} -10 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ 0 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ -5 \mathrm{~V} \text { to }+5 \mathrm{~V} \\ 0 \mathrm{~V} \text { to }+5 \mathrm{~V} \end{gathered}$ | to ANA RTN to ANA RTN to ANA INPUT to ANA INPUT | to ANA INPUT to ANA INPUT to ANA RTN to ANA INPUT | to + 10V REF to ANA INPUT to +10 V REF to ANA INPUT |


| INPUT VOLTAGES FOR CALIBRATION |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Nominal Full Scale Range | MP2712D For |  | MP2713C For |  | MP2714C For |  |
| $\begin{aligned} & -10 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ & 0 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ & -5 \mathrm{~V} \text { to }+5 \mathrm{~V} \\ & 0 \mathrm{~V} \text { to }+5 \mathrm{~V} \end{aligned}$ | Zero Cal. | Range Cal. | Zero Cal. | Range Cal. | Zero Cal. | Range Cal. |
|  | +0.0024V | +9.9927V | +0.0012V | +9.9963V | +0.00061V | +9.9982V |
|  | +0.0012V | +9.9963V | $+0.0006 \mathrm{~V}$ | +9.9982V | +0.00031V | +9.9991V |
|  | +0.0012V | + 4.9963V | $+0.0006 \mathrm{~V}$ | + 4.9982V | + 0.00031 V | + 4.9991V |
|  | +0.0006V | +4.9982V | + 0.0003 V | + 4.9991V | $+0.00015 \mathrm{~V}$ | +4.9995V |


| 12 BIT RESOLUTION | 13 BIT RESOLUTION | 14 BIT RESOLUTION |
| :---: | :---: | :---: |
| Unipolar binary: $\begin{aligned} +9.9976 \mathrm{~V} & =111111111111 \\ 0.0000 \mathrm{~V} & =000000000000 \\ \text { Pin Label } & =\mathrm{B} 1, \mathrm{~B} 2 . . . . . \mathrm{B} 12 \end{aligned}$ | Unipolar binary: $\begin{aligned} & +9.9988 \mathrm{~V}=1111111111111 \\ & 0.0000 \mathrm{~V}=0000000000000 \\ & \text { Pin Label }=\mathrm{B} 1, \mathrm{~B} 2 . . . . . \mathrm{B} 13 \end{aligned}$ | Unipolar binary: $\begin{aligned} +9.9994 \mathrm{~V} & =11111111111111 \\ 0.0000 \mathrm{~V} & =00000000000000 \\ \text { Pin Label } & =\mathrm{B} 1, \mathrm{~B} 2 . . . . . \mathrm{B} 14 \end{aligned}$ |
| Two's complement**: $\begin{aligned} & +9.9951 \mathrm{~V}=011111111111 \\ & 0.0000 \mathrm{~V}=000000000000 \\ & -10.0000 \mathrm{~V}=100000000000 \\ & \text { Pin Label }=\overline{\mathrm{B} 1}, \mathrm{~B} 2 . \ldots . . \mathrm{B} 12 \end{aligned}$ | Two's complement**: $\begin{aligned} & +9.9976 \mathrm{~V}=0111111111111 \\ & 0.0000 \mathrm{~V}=0000000000000 \\ & -10.0000 \mathrm{~V}=1000000000000 \\ & \text { Pin Label }=\overline{\mathrm{B} 1}, \mathrm{~B} 2 . . . . \mathrm{B} 13 \end{aligned}$ | Two's complement**: $\begin{aligned} & +9.9988 \mathrm{~V}=01111111111111 \\ & 0.0000 \mathrm{~V}=00000000000000 \\ & -10.0000 \mathrm{~V}=10000000000000 \\ & \operatorname{Pin} \text { Label }=\overline{\mathrm{B} 1}, \mathrm{~B} 2 . . . . \mathrm{B} 14 \end{aligned}$ |

**To change to offset binary, use B1 instead of $\overline{\mathrm{B} 1}$. For 5 V units, divide input voltage by 2.


Figure 5. Outline Drawing.


Figure 6. Timing Diagram for MP2714C

ORDERING GUIDE



## MP2734

## Very High Speed <br> Low Cost 14-Bit A/D Converter

## Description

The MP2734, an economical, high speed 14-bit successive approximation analog-to-digital converter, features not only a $7 \mu \mathrm{~s}$ conversion time, but also a superb differential linearity of $\pm 0.5$ LSB, a relative accuracy of $+0.006 \%$, very low noise, and an exceptionally low differential non-linearity tempco of $\pm 1 \mathrm{ppm}$. Such stability not only assures unusually uniform code widths, but also provides accurate, reliable performance for critical high speed, high accuracy applications, such as precision data acquisition and medical imaging systems.
Its superior performance is augmented by its interfacing flexibility and versatility. With four pinprogrammable full-scale ranges, 0 to $+5 \mathrm{~V}, 0$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$, the MP2734 accepts all standard signal input ranges. The latched tri-state outputs allow high system throughput by holding the digital data for a full conversion period. In addition, the Modupac ${ }^{T M}$ construction preserves the MP2734's performance in the presence of harsh electrostatic and electromagnetic interference. Finally, since the unit is pin-compatible with the industrial


Figure 1. Functional Block Diagram.
standard MP2714, for most applications, existing systems can be easily upgraded with the MP2734.
Built-in gain and offset adjustments eliminate the need for external adjustments since the adjustments are driven from an internal precision reference supply rather than from external potentiometers driven by raw $\pm 15 \mathrm{~V}$ power supplies. Furthermore, each individual MP2734 undergoes an exhaustive computer-programmed test, traceable to NBS standards; and the results are printed out and shipped with each unit. Thus, it is assured that the MP2734 will offer state-of-the-art, high speed, 14-bit performance under worst-case conditions.

## Features

- 14-bit Resolution
- 7 s Conversion Time
- Low Cost
- Latched, Tri-State Output Buffers
- Pin Compatible with Industrial Standard MP2714

■ $\pm 0.5$ LSB Differential Linearity

- $\pm 1 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ Differential NonLinearity Tempco
- 0.005\% p-p Noise

■ Built-in Gain and Offset Adjustments

- Pin Programmable Input Ranging

Four full-scale ranges provide a 4 to 1 sensitivity range (choose range best matched to data system).

## Applications

- High Speed Computer Interfacing
- Wide Band Data Digitizing
- Multi-Channel Process Control
- Audio Digitizing
- Mass Spectroscopy

■ Biomedical Instrumentation

- Seismic Array Digitizing
- Telemetry
- Research Instrumentation


## SPECIFICATIONS

(All Specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG INPUT

Full Scale Range (FSR)
0 to $+5 \mathrm{~V}, 0$ to +10 V , $\pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ (See Table 3)
Impedance
250 ת/V of FSR
Maximum Voltage Without Damage $\pm 200 \%$ of FSR

## Offset

Adjustable to Zero

## ACCURACY

## Resolution

14-bits binary
Relative Accuracy @ $\mathbf{1 4 2} \mathbf{~ k H z}$
$\pm 0.006 \%$ FSR max.
Absolute Accuracy ${ }^{1}$
$\pm 0.007 \%$ FSR max.
Differential Non-linearity
$\pm 0.5$ LSB typ., $\pm 0.7$ LSB max.
Noise on 0 to +10 V FSR
$83 \mu \mathrm{~V}$ rms
Monotonicity
Guaranteed

## DYNAMIC PERFORMANCE

Throughput Rate
142 kHz , min.
A/D Conversion Time
$7.0 \mu \mathrm{~s}$ max.

## STABILITY

Differential Non-linearity Tempco
$\pm 1 \mathrm{ppm} \mathrm{FSR}^{\circ} \mathrm{C}^{5}$ typ.

## Gain Tempco

$\pm 8 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ typ.
Offset Tempco
$\pm 3 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typ.
Warm-up Time ${ }^{2}$
10 minutes
Recommended Calibration Interval
6 months
Power Supply Sensitivity
(per $1 \%$ change in supply voltages)
$\pm 12 \mathrm{ppm}$ FSR

## POWER REQUIREMENTS

Typical Power
2 watts
$+15 \mathrm{~V} \pm 3 \%$
40 mA max.
$-15 \mathrm{~V} \pm 3 \%$
50 mA max.
$+5 \mathrm{~V} \pm 5 \%$
300 mA max.

## ENVIRONMENTAL \& MECHANICAL

Operating Temperature
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
$5 \%$ to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$
Shielding
Electrostatic and Electromagnetic
Package Size
$2 "$ x 4" x 0.44 " ( $50.8 \times 101.6$ X 11.2 mm )

| SIGNAL | FAN IN <br> (unit <br> loads) | HIGH <br> STATE $=" 1 "$ | LOW <br> STATE $=" 0 "$ | COMMENTS |
| :--- | :--- | :--- | :--- | :--- |
| A/D <br> Trigger | 0.25 | $0.1 \mu \mathrm{~s}, \mathrm{~min}$. | $0.2 \mu \mathrm{~s}, \mathrm{~min}$. | Negative <br> edge starts <br> conversion |
| High Byte 0.25 <br> Enable | Outputs at <br> high <br> impedance. | $\overline{\mathrm{B1}, \mathrm{B1} \text { through }} \mathrm{B6}$ active |  |  |
| Low Byte <br> Enable | 0.25 | Outputs at <br> high <br> impedance. | B7 through <br> B14 active |  |

Table 1. Digital Control Inputs 3,4

| SIGNAL | FAN OUT ${ }^{2}$ (unit loads) | TIMING | COMMENTS |
| :---: | :---: | :---: | :---: |
| $\overline{B 1}$ and $B 1$ through B14 | 2 | Updated during the time that EOC is high and B15 is low. | Parallel data from tri-state latches. |
| End-ofConversion (EOC) | 2 | Goes high $0.1 \mu \mathrm{~s}$ (typical) after A/D trigger falls. Goes low at end of conversion. | $\overline{\mathrm{B} 1}$ and B1 through B14 are updated $0.3 \mu \mathrm{~s}$ before "1-to-0" transition of EOC. |
| Data Update B15 | 2 | " 1 -to-0" transition signals that B1 and B1 through B14 will update nominally $0.1 \mu \mathrm{~s}$ later. | Will arbitrarily be a " 1 " or " 0 " between conversions. |

Table 2. Digital Outputs 3,4

## NOTES

1. Calibrated on $\pm 10 \mathrm{~V}$ FSR. The gain potentiometer can be adjusted for zero error.
2. To specified accuracy.
3. Digital inputs and outputs are 74LS TTL with all input loads less than 0.4 mA .
4. See Timing Diagram.
5. Typical.

## Using the MP2734

Four full-scale ranges, 0 to $+5 \mathrm{~V}, 0$ to +10 V , $\pm 5 \mathrm{~V}$, or $\pm 10 \mathrm{~V}$, offer a 4 to 1 sensitivity range. By connecting "IN 1," "IN 2," and "IN 3" in accordance with Figure 3 and Table 3, the
operating range best matched to the data system can be selected. The latched tri-state outputs (DTLTTL compatible) allow full system interfacing to either 8 or 16 bit data busses.

## CALIBRATIONS

## Zero Offset Calibration

To recalibrate the OFFSET:

1. Apply the input voltage shown in Table 4.
2. Adjust the OFFSET control so that the LSB of the output code 100...00/1 for bipolar units and 000...00/1 for unipolar units alternates equally between " 1 " and " 0 ". The offset should be readjusted whenever the selected full scale range is changed.

Zero offset should be calibrated before recalibrating the RANGE.

## Range Calibration

Internal: A built-in adjustment range of $0.1 \%$ of the full scale voltage is provided. To recalibrate the RANGE:

1. Apply the input voltage shown in Table 4.
2. Adjust the RANGE control so that the LSB of the output code 111...110/1 (B1...B14) alternates equally between " 1 " and " 0 ". The RANGE should be readjusted whenever the selected full scale range is changed.


Figure 2. Timing Diagram.

| Nominal Full Scale Range | IN 1 | IN 2 | IN 3 |
| :---: | :---: | :---: | :---: |
| -10 V to +10 V | to ANA RTN | to ANA INPUT | to + 10V REF |
| 0 V to +10 V | to ANA RTN | to ANA INPUT | to ANA INPUT |
| -5 V to +5 V | to ANA INPUT | to ANA RTN | to + 10 V REF |
| 0 V to +5 V | to ANA INPUT | to ANA INPUT | to ANA INPUT |

Table 3. Input Range Connections.

| Nominal Full <br> Scale Range | Zero CaI. | Range Cal. |
| :--- | :---: | :---: |
| -10 V to +10 V | +0.00061 V | +9.9982 V |
| 0 to +10 V | +0.00031 V | +9.9991 V |
| -5 V to +5 V | +0.00031 V | +4.9991 V |
| 0 to +5 V | +0.00015 V | +4.9995 V |

Table 4. Input Voltages for Calibration.

## Unipolar binary

$$
\begin{aligned}
& +9.9994 \mathrm{~V}=11111111111111 \\
& 0.0000 \mathrm{~V}=00000000000000 \\
& \text { Pin Label }=\text { B1, B2.......B14 } \\
& \text { Two's complement** } \\
& +9.9988 \mathrm{~V}=01111111111111 \\
& 0.0000 \mathrm{~V}=00000000000000 \\
& -10.0000 \mathrm{~V}=10000000000000 \\
& \text { Pin Label }=\overline{\mathrm{Bi}}, \mathrm{~B} 2 . . . . . . \mathrm{B} 14
\end{aligned}
$$

## Table 5. Binary Output Coding

[^5]

Figure 3. Jumper Connections for Input Voltage Range Selection.


Figure 4. Mounting Dimensions.


Figure 5. Typical $8 \mu$ s Conversion Application.


## ANALDGI.

## MP2735

Low Distortion, High Speed, 15-Bit Sampling A/D Converter

## Description

The MP2735, a high speed, 15-bit sampling analog-to-digital converter, features zero crossover linearity and a differential linearity about mid-range that is actually better than that of most 16 -bit converters. It is designed specifically to digitize dynamic complex waveforms, particularly audio or acoustic signals that have a substantial amount of information content around "zero volts" (midrange). With a $5 \mu$ s conversion time, a low harmonic distortion of $\pm 0.005 \%$ ( -86 dB of peak full scale), a noise power ratio (NPR) of 65 dB , low idle noise (within 3 dB of the theoretical level), and wide dynamic range ( 90 dB ), the MP2735 is suitably designed for professional audio applications.
The MP2735 exhibits excellent stability and reliability over temperature and time because its internal DAC has a sign/magnitude architecture, which is relatively insensitive to resistor instabilities especially around mid-range. In fact, because of this architecture, the MP2735 provides a monotonic and continuous transfer function through zero volts and is sig-

## Features

- Low Harmonic Distortion $\pm 0.005 \%$
$\square$ Ultra-Iow Idle Noise within 3 dB of theoretical level
- High Noise Power Ratio 65 dB for FDM/PCM Telecommunications
- Wide Dynamic Range 90 dB
- Low Cost
- Low Power 1.5 watts
- High Speed $5 \mu \mathrm{~S}$
- Built-in Sample-and-Hold
- Stable and Reliable Performance over Time and Temperature


## Applications

■ Professional Audio Systems

- FDM/PCM Telecommunications
- Seismic Data Acquisition
- High Frequency Communications
- Satellite Communications
- High Speed Data Acquisition
- Imaging Data Acquisition
- High Speed Automatic Test Equipment


Figure 1. Functional Block Diagram.

ANALOG INPUT
Full Scale Range (FSR)
$\pm 5 \mathrm{~V}$
Input Impedance
$100 \mathrm{M} \Omega \mid 110 \mathrm{pf}$
Reference Input Voltage
-6.4V
Reference Input Impedance
$2.7 \mathrm{k} \Omega$

## ACCURACY

## Resolution

15-bits
Quantization Error
$\pm 0.5$ LSB
Relative Accuracy of ADC @ 200 kHz
Conversion Rate
$\pm 0.005 \%$ FSR
FSR Factory Calibrated to $\pm 0.01 \%^{1}$
Offset Factory Adjusted to
$\pm 1 \mathrm{mV}^{1}$
Differential Linearity
$\pm 0.5$ LSB max., 0.25 LSB typical at $\leq 0.25$ FSR
$\pm 1$ LSB max., $\pm 0.25$ LSB typical at $\geq 0.25$ FSR
Monotonicity
Guaranteed
Noise ( $\mathbf{1 0 ~ H z}$ to $\mathbf{1 0 0} \mathbf{~ k H z ) ~}$
$25 \mu \mathrm{~V}$ rms
Zero Code $0^{\circ}$ to $60^{\circ} \mathrm{C}$
Continuous and monotonic through zero

## STABILITY

Tempco of Differential Linearity
For Mid-Range Outputs Centered About
Zero Volts ( $\pm 0.125$ FSR)
$\pm 0.5 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$, max.
Over the Full Scale Range
$\pm 1 \mathrm{ppm}$ FSR ${ }^{\circ} \mathrm{C}$, max.
Tempco of Gain
$\pm 10 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}^{4}$
Tempco of Offset
$\pm 10 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$, max.
Power Supply Sensitivity
Gain
$\pm 0.001 \%$ of FSR/\% change in power supply
Offset
15 ppm of FSR/volt change in power supply
Warm-up Time
5 minutes

SIGNAL DYNAMICS
A/D Conversion Rate
MP2735-1
125 kHz , min. ${ }^{2}$
MP2735-2
200 kHz, min.

AD Conversion Time
MP2735-1
$5 \mu \mathrm{~s}$, max.
MP2735-2
$5 \mu \mathrm{~s}$, max.
S/H Acquisition Time
$3 \mu \mathrm{~s}$
Slew Rate
$10 \mathrm{~V} / \mu \mathrm{s}$
Aperture Delay
30 ns, typical
Aperture Uncertainty
$\pm 0.4 \mathrm{~ns}$, typical
Sample \& Hold Feedthrough

- 86 dB

Harmonic Distortion up to 108 kHz
$\pm 0.005 \%$

DIGITAL INPUT CONTROLS
Code Compatibility
TTL Logic Levels
Trigger (positive transition)
Fan In
1 TTL Unit Load
Width
500 ns min.
DIGITAL OUTPUTS
Parallel Data
Fan Out
2 TTL Unit Loads/Line
Coding
Complementary Offset Binary ${ }^{3}$
End of Conversion (EOC)
High During Conversion
Fan Out
2 TTL Unit Loads
POWER SUPPLY ${ }^{4}$
$+15 \mathrm{~V}(+10 \mathrm{~V})$
35 mA
$-15 \mathrm{~V}(-10 \mathrm{~V})$
35 mA
$+5 \mathrm{~V}$
90 mA
$-5 \mathrm{~V}$
50 mA
ENVIRONMENTAL \& MECHANICAL
Temperature Range
Rated Performance
$0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$
Storage
$-25^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$ non-condensing up to $40^{\circ} \mathrm{C}$

## Packaging Dimensions

3" $\times 4$ " $\times 0.44$ "
Shielding
Electromagnetic 5 sides
Electrostatic 6 sides
Case Potential
Ground

## Notes

'Internal pots allow field calibration.
${ }^{2}$ Including internal S/H.
${ }^{3}$ Refer to "Calibration Procedures."
${ }^{4}$ Typical Values are shown.

## Description (cont.)

nificantly more stable over temperature and time than a conventional 16 -bit converter with an offset binary architecture. The MP2735 attains a differential linearity of $\pm 0.5$ LSB maximum and $\pm 0.25$ LSB typical at less than 0.25 full scale range, and it has no missing codes.
Furthermore, the unit's high speed conversion time of $5 \mu \mathrm{~s}$ allows two channels to be multiplexed and sampled at 55 kHz each and provides an ideal design for digitizing telephone group set FDM (frequency division multiplexed) analog data with a frequency band from 60 kHz to 108 kHz and a data update rate of 112 kHz , for multiplexed audio applications with a typical sampling rate from 32 kHz to 55 kHz , and for seismic data acquisition with a typical sampling rate of 32 kHz to 110 kHz .
The MP2735 is available in two versions: the MP2735-1 has a built-in sample-and-hold and features a conversion time of $5.0 \mu \mathrm{~s}$ for the A/D converter and a total conversion time of $8.0 \mu \mathrm{~s}$; the MP2735-2, without a sample-and-hold, has a conversion time of $5.0 \mu \mathrm{~s}$. The MP2735-2, which is designed specifically to be used with the dual channel MP282 Sample-and-Hold on one PC card, available as the Analogic SHAD2, features an increased dynamic range of 98 dB .
The MP2735, with the benefits of low power (only 1.5 watts), low cost, a wide analog power supply range of $\pm$ ( 10 to 15 volts), and excellent crossover linearity near zero volts, is the ideal choice for even the most demanding applications.

## PRINCIPLES OF OPERATION

The MP2735 uses a two-step successive approximation (iterative) technique to attain a 15-bit analog-to-digital conversion in $5 \mu \mathrm{~s}$. (Refer to the Functional Block Diagram of Figure 1 and the Timing Diagram of Figure 2). It has a unique internal architecture consisting of a buffer amplifier, an 8 -bit ADC, an 8 -bit DAC with 16 -bit accuracy, associated timing and logic control with an internal reference and clock, parallel outputs, and an optional sample-and-hold amplifier that provides convenience and simplification of system integration problems.
If the optional sample-and-hold is not used (MP2735-2), the buffered analog input signal is presented directly to the ADC; if the sample-and-hold is used (MP2735-1), the signal is stored within the S\&H capacitor. The ADC then converts the input signal to an 8 -bit word accurate to within 0.5 LSB, and this digital output is stored in a holding register in the logic control.
The 8 -bit DAC, with 16 -bit accuracy, converts this digital output to an analog signal. An error amplifier expands the difference between this signal and the original analog input signal. That value is recirculated through the ADC, and the resulting 8 LSB's of the final 15 -bit digital code are presented to the parallel output data bits. This second decision may change the 8 MSB's stored in the holding register from the first conversion since the MSB of the 8 LSB's and the LSB of the 8 MSB's overlap. These final 8 MSB's then enter the parallel output data bits, thus producing a 15 -bit digital code of the original analog input.
The low harmonic distortion - 0.005\% ( -86 dB !) - is principally due to the sign/magnitude architecture of the 8 -bit DAC. As opposed to conventional offset binary, the sign/magnitude architecture of the DAC provides excellent differential linearity; and to maintain that high differential linearity near zero volts, there is an internal 0.5 LSB offset of the DAC's output, thereby avoiding the " +0 V " and " -0 V " implicit in the sign/magnitude architecture.
This DAC also provides excellent stability and reliability over time and temperature. In offset binary converters resistor drifts fre-
quently cause significant linearity drift for signals near zero volts; for example, most resistors, except for laboratory standard wire-wound types, have tracking ratios greater than 15 ppm/year. However, converters with sign/magnitude architecture are four to five times less sensitive to resistor drift.
Thus, the MP2735, with its high noise power ratio, low power consumption, high speed, excellent stability and reliability, superb differential linearity, and exceptionally low harmonic distortion, offers superior, state-of-the-art performance.


Figure 2. Timing Diagram of MP2735-1.

## APPLICATIONS

## Professional Audio Digitizing

The MP2735, with its wide dynamic range, low harmonic distortion, and ultra-low idle noise, is designed to meet the demands of professional audio applications, such as multi-track audio PCM systems or selfcontained record and playback systems. With conversion rates of 125 kHz and 200 kHz for the MP2735-1 and MP2735-2, respectively, the frequency of this converter is more than adequate for high fidelity audio signals.
Since professional audio studios perform multi-track recording, processing signals from separate microphones, adjusting them according to desired tonal quality, and mixing them to attain the final product, signal sampling must occur at precisely the same time for each channel. When the MP2735-2 is used with the dual channel MP282A sample-and-hold, a pair of stereo channels can be sampled simultaneously at 55 kHz with 16 -bit dynamic range.
A typical application is illustrated in Figure 3. Two inputs from separate microphones pass through anti-aliasing filters and are sampled simultaneously, or separately, by the MP282A, where they are multiplexed. Then the MP2735-2 converts each input to 15-bit digital data, which is combined with the gain ranging bit of the MP282A to provide 16 -bit data for storage, processing, or mixing. The MP1926 converts the processed digital data back to an analog signal,


Figure 3. Professional Audio Application.
which, after being multiplexed, passes through a sample-and-hold, two deglitch amplifiers, and two low pass filters that include $(\sin x) / x$ compensation. The low harmonic distortion achieved with the MP2735 in a similar application is demonstrated in the spectral analysis shown in Figure 4.
The MP2735 is also applicable for a selfcontained record and playback system, which does not require simultaneous sampling because incoming signals, although dual channeled, are not separated, manipulated, and mixed, but are played back immediately. The high speed MP2735 allows overlapping between signal acquisition from one channel and signal conversion from another.
Furthermore, for a single channel audio application, the 125 kHz conversion rate of the MP2735 is more than adequate for the 32 kHz sampling rate required for broadcast applications.


Figure 4. Photo of Spectral Analysis Showing Low Harmonic Distortion.

## CALIBRATION

Although not usually required in practice, gain and offset may be adjusted through the top edge of the board. The offset should be adjusted until the least significant bit (LSB) of the output code, 100...00/1, alternates equally between " 0 " and " 1 " when the measured potential across pins A14 and A 15 is -0.000153 V . The gain should be adjusted until the LSB of the output code, $111 . .10 / 1$, alternates equally between " 0 " and " 1 " when the measured potential across pins A14 and A15 of the MP2735 is -4.99954 V .

## TELECOMMUNICATIONS DIGITIZING

In a telecommunications application (refer to Figure 5) the MP2735-1 digitizes Frequency Division Multiplexing (FDM) group band signals for Digital Signal Processing. The frequencies of interest are in the band from 60 kHz to 108 kHz , thus a sampling frequency of 112 kHz is chosen.
All system measurements are specified with input and output filters in the system. The input filter limits the input signal to the frequency band of 60 kHz to 108 kHz , and the output filter has a passband of 60 kHz to 108 kHz . The composite D/A and filter will have a flat response over the 60 kHz to 108 kHz frequency range. The D/A output is gated with a deglitch amplifier to reduce the amount of $(\sin x) / x$ compensation and eliminate D/A glitches.
The MP2735 achieves a high NPR of 65 dB because of its low distortion and low idle noise. NPR is the measured decibel ratio between the noise level in one of the 12 channels with the baseband ( $60-108 \mathrm{kHz}$ ) fully noise loaded (typically at -18 dB of full scale range) and the level in that channel with all the baseband noise loaded except in that channel.


Figure 5. Telecommunications.

## ORDERING GUIDE

For A/D Converter and Optional S/H:
Specify MP2735-1
For A/D Converter only:
Specify MP2735-2


## Description

The MP8000 Series of A/D converters offers the system designer a wide choice of resolution, conversion rate, analog input and digital output configuration, while providing high accuracy and long-term time and temperature stability. Resolutions of 14 -, 15 -, and 16 -bits, at conversion rates externally adjustable from 0.6 - $2.5 \mu \mathrm{~s} / \mathrm{bit}$ are accommodated. Input full scale ranges of OV to +10 V unipolar, or $\pm 10 \mathrm{~V}$ bipolar are pin-selectable, as is an input configuration of either low impedance single-ended, or very high impedance true differential (using an internal buffer amplifier). The digital output code may be pin-selected to provide either unipolar binary, offset binary or two's complement parallel data, or NRZ serial data formats, and the converters can be short-cycled to increase throughput if required.
The relative accuracy of each model in the MP8000 Series is appropriate for its resolution, ranging from $0.0015 \%$ to $0.006 \%$ FSR (16-bits to 14-bits respectively), while absolute accuracy (NBS traceable) is guaranteed from 0.003\% to 0.006\% FSR. Temperature stability is equally good, with tempcos for gain and offset of $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ and $2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$. The Differential Linearity tempco is $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, monotonicity is guaranteed and there are no missing codes
over a $0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ temperature range.
The MP8000 Series of A/D converters is packaged in a fully shielded $3^{\prime \prime} x$ 4.6" metal can. Pin locations and functions on all three MP8000 Series converters are identical and can be plugged into two standard 24-pin connectors for rapid insertion/removal. Internal potentiometers are provided for adjusting gain and offset.

## Features

## 14-, 15-, and 16-bit Resolution

- High Accuracy

Relative Accuracy of 0.0015\% to $0.006 \%$ FSR

- Absolute Accuracy NBS Traceable $0.003 \%$ to $0.006 \%$ FSR
- Single-ended or true differential input
- Parallel or NRZ Serial Output Data Format
- Short-cycle capability
- Excellent Stability Gain Tempco $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ Offset Tempco $2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$


## Applications

## Data Acquisition Systems <br> Medical Electronics <br> Automated Test Equipment <br> Digital Audio



Figure 1. Functional Block Diagram for MP8000 Series.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

| ANALOG INPUT | CONVERSION TIME |
| :---: | :---: |
| Input Voltage (Full Scale Range) | Clock Rate (Externally Adjustable) |
| 0 to +10 V unipolar; -10 V to +10 V bipolar | 1.0 to $2.5 \mu \mathrm{~s} / \mathrm{bit}$ (MP8016) |
| Input Configuration | 0.8 to $2.0 \mu \mathrm{~s} / \mathrm{bit}$ (MP8015) |
| Differential or direct, pin selectable | 0.6 to $1.5 \mu \mathrm{~s} / \mathrm{bit}$ (MP8014) |
| Input Impedance Differential $10^{9} \Omega$ | LOGIC SIGNALS |
| Direct, 0 to +10V FSR $2.5 \mathrm{k} \Omega$ | Digital Output Codes <br> Unipolar: binary; bipolar: offset binary or 2's complement |
| Direct, $\mathbf{- 1 0 V}$ to +10V FSR $5.0 \mathrm{k} \Omega$ | Compatibility Standards DTLTTL logic levels, positive true B1 |
| Common Mode Voltage Plus Signal +11V max. | through Bn and $\overline{\mathrm{B} 1}$. Data available 100 ns (nominal) after EOC and remains at output |
| Common Mode Rejection Ratio $>75$ dB | register terminals until new TRIGGER occurs. Capable of driving 8 TTL Loads |
| ACCURACY | Serial Data Outputs <br> After a complete conversion, SERIAL OUT re- |
| Resolution (With Short Cycle Capability) 16 bits (MP8016), 15 bits (MP8015), | mains in condition of last bit until new TRIGGER occurs |
| 14 bits (MP8014) | Trigger (Start Convert) |
| Relative Accuracy $\pm 0.0015 \%$ FSR max. @ $2 \mu \mathrm{~s} / \mathrm{bit}$ (MP8016) $\pm 0.003 \%$ FSR max. @ $1 \mu \mathrm{~s} / \mathrm{bit}$ (MP8015) $\pm 0.006 \%$ FSR max. @ . $72 \mu \mathrm{~s} /$ bit (MP8014) | Conversion initiated by negative-going edge of positive or negative $+3.5 \pm 1 \mathrm{~V}$ pulse having 100 ns maximum transition time. Positive pulse width: $3 \mu \mathrm{~s}$ minimum; negative pulse width: |
| Absolute Accuracy (NBS Traceable) $\pm 0.003 \%$ FSR max. @ $2 \mu \mathrm{~s} /$ bit (MP8016 | 800 ns minimum 1 TTL Load |
| $\pm 0.006 \%$ FSR max.@ $1 \mu \mathrm{~s} / \mathrm{bit}$ (MP8015) | EOC (End-of-Converstion) |
| $\pm 0.006 \%$ FSR max. @ . $72 \mu \mathrm{~s} / \mathrm{bit}$ (MP8014) | Negative-going signal with $\leq 20$ ns transition |
| Quantizing Error <br> $\pm 1 / 2$ LSB @ $2 \mu \mathrm{~S} / \mathrm{bit}$ (MP8016) <br> $\pm 1 / 2$ LSB @ $1 \mu \mathrm{~S} / \mathrm{bit}$ (MP8015) | time occurs @ leading edge of last clock pulse ( 100 ns before TRIGGER occurs). Capable of driving 10 TL Loads |
| $\pm 1 / 2$ LSB @ . $72 \mu \mathrm{~s} / \mathrm{bit}$ (MP8014) | Clock (Internal) Output (see Fig. 3) |
| Monotonicity | Negative-going pulse of 200 ns width. Maximum |
| Guaranteed @ $2 \mu \mathrm{~s} / \mathrm{bit}$ (MP8016) | allowable external capacitance: 30 pF . Capable |
| Guaranteed @ $1 \mu \mathrm{~s} / \mathrm{bit}$ (MP8015) | of driving 10 TTL Loads |
| Guaranteed @ . $72 \mu \mathrm{~s} / \mathrm{bit}$ (MP8014) | Short Cycle Capability |
| $3{ }_{3}$ Noise (Including Ref.) | 8 to 15 bits (MP8016) |
| $300 \mu \vee \mathrm{p}$-p | 8 to 14 bits (MP8015) |
| STABILITY |  |
| Tempco of Differential Linearity | POWER SUPPLY |
| $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max. | $\pm 15 \pm 0.5 \mathrm{Vdc}$ |
| Tempco of Gain | 40 mA max. |
| $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR typ.; $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max. | $-15 \pm 0.5 \mathrm{Vdc}$ |
| Tempco of Offset | 65 mA max. |
| $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max. | $+5 \pm 0.25 \mathrm{Vdc}$ |
| Clock Stability | 300 mA max. |
| $0.1 \% /{ }^{\circ} \mathrm{C}$ | ENVIRONMENTAL \& PHYSICAL |
| Power Supply Sensitivity (per 1\% Change in Power Supply Voltage) $0.0005 \%$ | Operating Temperature Range $0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$ |
| Recommended Calibration Interval 6 months | Storage Temperature Range $-25^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C}$ |
| Warmup Time to Spec. Accuracy 10 minutes | Relative Humidity $5 \%$ to $95 \%$, noncondensing |

## Electrical Shielding

RFI 6 sides; EMI 5 sides

## Dimensions

$4 \times 3 \times 0.375$ inches ( $101.6 \times 76.2 \times 12.7 \mathrm{~mm}$ )
Right-Angle Connectors
15-300014, 2 each, supplied

## USING THE MP8000 SERIES A/D CONVERTERS <br> Data Output

Both parallel and serial data output formats are available at the converter pins, plus an EOC (End-of-Conversion) indication at the end of the data output. (See timing diagram). The MP8000 Series provides for the control of the digital output word length so that the user can preselect any number of bits from 8 to either 14, 15, or 16 . To operate this MP8016 converter at its full digital output capacity, externally connect the WRD LTH IN terminal (Pin 35B) to the B16 terminal (Pin 25T). To operate this converter at less than full capacity, thereby decreasing the total conversion time, connect Pin 35B to the desired bit output terminal (B8 to B15). For example, for 10-bit operation, connect Pin 35B to Pin 28T (B10).
Binary output coding is used for unipolar operation, while for bipolar operation, the parallel output data can be either offset binary or 2's complement, as pin selected by the user.

## Timing

As shown in Figure 2 for the MP8014 converter, the negative-going edge (" 1 " to " 0 " transition) of the TRIGGER pulse enables: (1) EOC to high, (2) B1 to High (B1 to Low), (3) all other bit outputs (B2 to B14) to Low and (4) CLOCK pulse train. Conversion begins when the negative-going edge of the first clock pulse goes to Low. The bit decisions are made on successive negative-going pulse transitions with the MSB bit occurring at the second clock pulse.
Conversion is completed when EOC goes to Low on the negative-going edge of the last clock pulse. EOC remains at Low until the next TRIGGER pulse is initiated. Parallel data is available 100 ns after EOC goes to Low and remains valid at the output register terminals until the next TRIGGER pulse.


Figure 2. Typical Timing Diagram. (MP8014 shown)

The conversion rate can be usercontrolled by connecting pin 12T (CLOCK CONTROL) through a $25 \mathrm{k} \Omega$ potentiometer to +5 V as shown. Direct connection to +5 V results in a minimum conversion rate. Pin 12T must be terminated as above for proper operation of the module; clock will not operate with 12T floating.


The 200 ns wide clock pulses are used to synchronize the transmission of serial data. After B1 is set to " 1 " by the TRIGGER pulse, the MSB decision is made one clock period later. Thereafter, each bit is set to " 1 " or " 0 " according to each successive decision, coincident with the negative-going edge of the clock pulses. After a complete conversion, NRZ SERIAL OUT remains in the condition of the last bit transmitted until a new TRIGGER pulse occurs. Pin 12T, connected in accordance with Figure 3, enables the internal clock.

## Input Configuration

Figure 4 illustrates how the internal buffer amplifier may be configured for either a single-ended or differential input to the A/D converter.

For Standard (Direct Input) Impedance. The three input pins (IN 1, IN 2, \& IN 3) permit user selection of the two input voltage ranges $(+10 \mathrm{~V} \& \pm 10 \mathrm{~V})$ at low impedance ( 2.5 to 5 k ). Make the connections shown below.


For High (Differential Input) Impedance. The differential amplifier allows user selection of the two input voltage ranges $(+10 \mathrm{~V} \& \pm 10 \mathrm{~V})$ at high impedance $\left(10^{\circ} \Omega\right)$. Make the connections below.


Figure 4. Input Configuration.


| INPUT/OUTPUT DIGITAL CODING |  |  |
| :---: | :---: | :---: |
| 14 BIT RESOLUTION | 15 BIT RESOLUTION | 16 BIT RESOLUTION |
| Unipolar Binary <br> $11111111111111=+9.99939 \mathrm{~V}$ <br> $00000000000000=0.0000 \mathrm{~V}$ <br> B1, B2 . . . . . . B14 $=$ Pin Label | Unipolar Binary <br> $111111111111111=+9.99970 \mathrm{~V}$ <br> $000000000000000=0.0000 \mathrm{~V}$ <br> B1, B2 ....... B15 = Pin Label | Unipolar Binary <br> $1111111111111111=+9.99985 \mathrm{~V}$ <br> $0000000000000000=0.0000 \mathrm{~V}$ <br> $\mathrm{B} 1, \mathrm{~B} 2 \ldots \ldots . . \mathrm{B} 16=$ Pin Label |
| Offset Binary <br> $11111111111111=+9.99878 \mathrm{~V}$ <br> $10000000000000=0.0000 \mathrm{~V}$ <br> $00000000000000=-10.0000 \mathrm{~V}$ <br> B1, B2 $\ldots \ldots$. . $14=$ Pin Label | Offset Binary <br> $111111111111111=+9.99939 \mathrm{~V}$ <br> $100000000000000=0.0000 \mathrm{~V}$ <br> $000000000000000=-10.0000 \mathrm{~V}$ <br> B1, B2 $\ldots . \ldots$. . B15 = Pin Label | $\begin{aligned} & \text { Offset Binary } \\ & 1111111111111111=+9.99970 \mathrm{~V} \\ & 1000000000000000=0.0000 \mathrm{~V} \\ & 0000000000000000=-10.0000 \mathrm{~V} \\ & \mathrm{~B} 1, \mathrm{~B} 2 \ldots \ldots \ldots \ldots \mathrm{~B} 16=\text { Pin Label } \end{aligned}$ |
| 2's Complement* <br> $01111111111111=+9.99878 \mathrm{~V}$ <br> $00000000000000=0.0000 \mathrm{~V}$ <br> $10000000000000=-10.0000 \mathrm{~V}$ <br> $\overline{\mathrm{B} 1}, \mathrm{~B} 2 \ldots \ldots . \mathrm{B} 14=$ Pin Label | 2's Complement* <br> $011111111111111=+9.99939 \mathrm{~V}$ $000000000000000=0.0000 \mathrm{~V}$ <br> $100000000000000=-10.0000 \mathrm{~V}$ <br> $\overline{\mathrm{B} 1}, \mathrm{~B} 2 \ldots \ldots . \mathrm{B} 15=$ Pin Label | 2's Complement* <br> $0111111111111111=+9.99970 \mathrm{~V}$ <br> $0000000000000000=0.0000 \mathrm{~V}$ <br> $1000000000000000=-10.0000 \mathrm{~V}$ <br> $\overline{\mathrm{B} 1}, \mathrm{~B} 2 \ldots \ldots \ldots \mathrm{~B} 16=$ Pin Label |

*To change to Offset Binary, use B1 instead of $\overline{\mathrm{B} 1}$.


Figure 5. Mechanical.

| MP8000 SERIES PIN DESIGNATIONS |  |  |  |
| :---: | :---: | :---: | :---: |
| $\pm 15 \mathrm{~V}$ RTN | 18 |  | $\pm 15 \mathrm{~V}$ RTN |
| -15V | 2B | 2 T | -15V |
| +15V | 3B | $3 T$ | +15V |
| (OPTIONAL) IN 1 | 4B | 4 T | AMP NEG IN |
| IN 2 | 5B | $5 T$ | DIFF AMP OUT |
| IN 3 | 68 | $6 T$ | AMP POS IN |
|  | 78 | 7 T |  |
| +10V REF OUT | 8B | 8 T | +10V REF OUT |
| ANA GND | 98 | 9 T | ANA GND |
|  | 10B | 10 T |  |
|  | 118 | 11 T |  |
|  | 12B | 12T | CLOCK CONTROL |
| B15 | 25B | $25 T$ | B16 |
| B13 | 26B | 26T | B14 |
| B11 | 27B | 27 T | B12 |
| B9 | 28B | 28 T | B10 |
| B7 | 298 | 29 T | B8 |
| B5 | 30B | 307 | B6 |
| B3 | 31B | 31 T | B4 |
| B1 | 32B | 32T | B2 |
| SER DATA OUT | 33B | 33T | $\overline{\text { B1 }}$ |
| EOC OUT | 34B | 34 T | CLOCK OUT |
| WRD LTH IN | 358 | 35 T | TRIGGER IN |
| +5V RTN | 36B | 36 T | $+5 \mathrm{~V}$ |

ORDERING GUIDE

| For | Specify |
| :---: | :---: |
| 14-Bit ModupacTM | MP8014 |
| 15-Bit ModupacTM | MP8015 |
| 16-Bit Modupac | MP |



ANMLCGEB

## MP8037

17-Bit, Moderate Speed Triple-Slope Integrating AD Converter

## Description

Analogic's MP8037 is a ultra-high resolution, integrating A/D converter that provides exceptional performance in a smaller size and at a lower cost than previously available. The MP8037 is the first integrating converter to offer true 17-bit resolution. Its conversion speed of 250 conversions per second and TTL compatibility make it ideal for universal interfacing with the high precision data acquisition and control systems used in industrial, analytical and environments.

## Performance Features

The MP8037 features an innovative quadraphasic triple-slope integrating conversion design that completes the 17-bit conversion, including autozero, in 4.0 ms maximum. The MP8037 automatically autozeros whenever it is in the standby mode, guaranteeing accurate conversions each and every time by effectively eliminating internal drifts. MP8037 relative accuracy (linearity), stability, and differential linearity are consistent with the unit's high $0.00075 \%$ FSR resolution. Absolute accuracy traceable to NBS standards is factory set to $\pm 0.005 \%$ FSR and is adjustable to within $\pm 0.002 \%$ FSR. Integral linearity within $\pm 0.00075 \%$ FSR, differential linearity of $\pm 0.00025 \%$ FSR, which guarantees monotonicity, assure meaningful 17-bit information.


Figure 1. MP8037 Block Diagram.

## Features

- Ultra-high Resolution 17 bits (16 data, 1 polarity)
- High Speed Up to 250 conversions/second External trigger control
- Small Size

Standard $2 \times 4$ " Modupac ${ }^{\text {TM }}$

- High Accuracy \& Stability Linearity error $<7.5 \mathrm{ppm}$ FSR Auto-stabilized Zero
- High Differential Linearity $\pm 2.5 \mathrm{ppm}$ FSR
- Guaranteed Monotonicity
- True Ratio Measurements Pin-programmable precision internal reference Or user supplied external reference
- Low Input Current 50 nA @ 100 conversions/second
- High Input Impedance $1000 \mathrm{M} \Omega$, minimum 50 pF , maximum
- Universal Data Systems Compatibility
Data fanout for 2 TTL loads


## Applications

- Precision Chemical Process Control Systems
- Digital Signal Processing Systems
- High Resolution Monitoring and Control Systems
- Precision Pharmaceutical Mixing \& Grading Systems
- High Resolution Laboratory and R \& D Systems
- Gas Chromatography
- Analytical Instrumentation


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

```
ANALOG
Input Configuration Differential (See Figure 4)
Input Range (Operating)
\(\pm 10 \mathrm{~V}\) max.*
Input Range (Without Damage)
\(\pm 15 \mathrm{~V}\) max.
Input Impedance
\(1000 \mathrm{M} \Omega\) min., 50 pF max.
Input Current
50 nA @ 100 conversions/second
Input Integration Time
\(640 \mu \mathrm{~S}^{*}\)
```

ACCURACY (@ $25^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$ )
Relative Accuracy
$\pm 7.5 \mathrm{ppm}$ FSR max.
Differential Linearity
$\pm 2.5 \mathrm{ppm}$ FSR max.

## Resolution

16 bits and sign
Noise
$15 \mu \mathrm{~V}$ rms
Absolute Accuracy
$\pm 0.005 \%$ FSR, without adjustment; $\pm 0.0027$
FSR, adjusted
STABILITY
Zero Tempco
$\pm 6 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.
Gain Tempco
$\pm 10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.

## CONVERSION

## Technique

4-phase, triple slope integrating analog-todigital conversion, autozeroed before each conversion

## Rate

250 conversions per second, max., controlled by external command

## SYSTEM INPUTS

## External Trigger

$0.1 \mu \mathrm{~s}$ min., negative pulse, TTL compatible, must drive 6 loads; 3 CMOS and 3 low-powered Schotky: Conversion starts on positive transition. See Figure 2

[^6]
## DIGITAL OUTPUTS

## Data Output

16 data bits, SIGN, and SIGN
EOC
High level indicates conversion is in process; low level indicates outputs are valid.
Allow 10 ns delay from EOC high to low transi-
tion before reading data
Compatibility
1 LS load each for 16 data bits; 2 TTL loads each for SIGN, SIGN, and EOC
Code Format
Sign and absolute value
POWER SUPPLY
$\pm 5 \mathrm{Vdc} \pm 5 \%$
200 mA, typ.
+15 Vdc $\pm 3 \%$
20 mA, typ.
-15 Vdc $\pm 3 \%$
16 mA , typ.
ENVIRONMENTAL \& MECHANICAL
Operating Temperature
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $95 \%$, non-condensing
Modupac ${ }^{\text {TM }}$ Dimensions
$2 \times 4 \times 0.440$ in., ( $50.8 \times 101.6 \times 111.8 \mathrm{~mm}$ ) (See
Figure 7)
Shielding
RFI 6 sides; EMI 5 sides

## SPECIAL FEATURES

Ratiometric Measurements
$+10 \mathrm{~V} \pm 0 \%$ external reference may be used in place of internal reference. Connect to REF IN
External System Offset Compensation
$\pm 50 \mathrm{mV}$ max. may be compensated. Connect to A/Z RTN

## Performance Features

The guaranteed differential linearity of the MP8037 makes it adaptable for use in computer-based data acquisition systems to accomplish statistical processing and achieve an effective resolution up to 20 -bits. Simple pin programming achieves true ratiometric measurements with 17-bit resolution by connecting an external in place of the precision internal reference.
The high quality performance of the MP8037 is confirmed by comprehensive computer-controlled factory acceptance tests, whose results are shipped with each module. Reliable performance is further supported by the Analogic standard QC procedure, including vendor qualification, rigid incoming inspection, and $100 \%$ burn-in cycling under power of all critical components.

## Principles of Operation

The innovative quadraphasic design of the MP8037 completes a conversion in 4 phases, the operation of which may be best understood with reference to Figures 1 and 2. The four phases are: the autozeroing phase (AZ), the signal integration phase ( $\int x$ ), integration of ref high ( $\int$ ref hi), and integration of ref low ( $\int$ ref lo). Timing signals for each of the phases is developed in pro-


Figure 2. Quadraphasic Timing Waveforms.
grammed read-only memory (PROM's) in response to input signal magnitude and polarity. When not in a conversion mode, the converter is placed automatically into its auto zero phase. The unit need only remain in this phase for a minimum of $600 \mu \mathrm{~s}$ to assure that the charge on the integrating capacitor is reduced to reference zero level. It also assures that the memory capacitor is charged to balance out any internal drifts as well as compensate for any external offsets introduced at the module pin connections.

When the trigger pulse is received, the low level transition causes the counters to be reset to zero. The rising edge generated by the return of the pulse to a positive level triggers the converter, and phase 1 begins. The input signal (and any stored AZ offset) is integrated for a period of $640 \mu \mathrm{~s}$. Program control shifts the unit into phase 2, where the input signal is replaced by a high current, opposite polarity reference. This discharges the integrating capacitor at a high rate as shown in Figure 2. During this phase, the counters are incremented beginning with B9 counting up to B1 (MSB).
When the integrating capacitor has been discharged to a preset level, the program control begins phase 3. The high current reference is then replaced by a low current reference, and the low bit counters beginning with B16 (LSB) are incremented. This phase continues until the integrating capacitor is discharged to its initial value, when an end of conversion signal (EOC) is generated. At this time, the output data is valid, and program control is returned to the AZ phase. Suitable pauses are introduced between phases to eliminate conversion errors which could result from the settling of the program-switching circuits. The result is true 17-bit performance.

## Initial Installation

As shown in Figure 3, the MP8037 is connected to the signal source, a trigger command, two sources of power ( 5 Vdc and $\pm 15 \mathrm{Vdc}$ ), and an optional external reference. The second signal input may be used to remove common mode voltages that may exist between signal and MP8037 grounds, or to introduce corrections to the input signal resulting from other system considerations.

The external reference, if used, should be within $\pm 10 \%$ of the internal value of 10 Vdc. If an external reference is not used, then the REF OUT and REF IN pin terminals must be jumpered.
Be sure the MP8037 completes a conversion before applying a new trigger.


Figure 3. Connecting Power \& signals to MP8037.

## Calibrating The MP8037

The MP8037 is calibrated at the factory traceable to NBS Standards and is ready for immediate use. For special system applications, the 3 -wire input capability of the MP8037 provides for high accuracy systems recalibration of the module to achieve true 17-bit system converter performance. As shown in Figure 4, connecting the system calibrating voltage source COM to the MP8037 A/Z RTN effectively removes up to $\pm 50 \mathrm{mV}$ of CMV between the two units.

## Procedure:

Set the input for a value of +9.999977 Vdc Trigger the MP8037; read the binary data output.
Adjust the + RANGE control for a positive full scale binary output (1 11111111111111111), where the positive true SIGN bit is sensed, and set the control just past the transition of the LSB.
Reverse the input leads.
Adjust the - RANGE control for a negative full scale binary output (0 1111111111111111), where the positive true SIGN bit is sensed, and set the control just past the transistion of the LSB.


Figure 4. MP8037 Calibration Setup.

## Input Connections to MP8037

Input Signals: The MP8037 encodes the difference between two input signals (Figure 5), thereby providing a differential input for systems applications. Small system ground-loop voltages, (up to 50 mV ) common mode voltages, and minor system offsets are almost completely removed by using this 3 -terminal input configuration as shown in the illustration.
Reference: True Ratiometric Measurements may be made with the MP8037 by replacing the internal reference with an external reference. Simply remove the jumper between pin terminals REF OUT and REF IN, and connect $+10 \mathrm{Vdc} \pm 10 \%$ between REF IN and ANA RTN.


Figure 5. Connecting Input Signals to Remove CMV.

## Typical Application

The MP8037 can be used to provide very wide dynamic range when connected as shown in Figure 6. Here the output of the Gas Chromatagraph is connected to a programmable gain amplifier (PGA). The output of the PGa is fed to the MP8037 and the selected gain is indicated by 3 output bits.

Once the gain has been properly set and sufficient time has been allotted after EOC for autozero, the Control Logic issues a convert command to the MP8037. When the EOC signal is obtained, valid 20 -bit data digitizing a 21 -bit input dynamic range is available at the output. In this system, the MP8037 A/Z RTN is jumpered to ANA RTN, and any CMV between source, system and measuring system grounds is rejected in the PGA.


Figure 6. Using MP8037 for 20-bit Data Gas Chromatograph Instrumentation.


Figure 7. MP8037 Outline \& Mounting Dimensions.

## ORDERING GUIDE

Specify MP8037.
For Full Scale Ranges other than $\pm 10 \mathrm{~V}$, or for Signal Integration times other than $640 \mu \mathrm{~s}$, or for
Conversion Rates greater than 250 per second, Consult Factory.

## ANALOGC

## Data Acquisition Systems

TABLE OF CONTENTS PAGE
Selection Guide................................................................................................5-2
ADAM-724 14-bit, $6.8 \mu \mathrm{~s}$ A/D with Integral S/H and
Differential Amplifier............................................................................5-3
ADAM-812 Dual Simultaneous S/H and 12-bit 50 kHz A/D........................5-13
ADAM-822 Dual Simultaneous S/H and 12-bit 26 kHz A/D........................5-17
ADAM-824A Low Power, 14-bit, 50 kHz A/D with S/H.................................5-23
ADAM-825A Low Power, 15-bit, 50 kHz A/D with S/H.................................5-23
ADAM-826 Family of 16-bit, Ultra Speed A/D Converters..........................5-27
ADAM-826-1 16-bit, $1.5 \mu \mathrm{~s}$ A/D with Integral 800 ns S/H.............................5-33
ADAM-826-2 16-bit, $1.5 \mu$ s A/D with Integral 400 ns Buffer Amplifier.......5-37
ADAM-826-3 16-bit, $1.5 \mu \mathrm{~s}$ A/D (Unbuffered).................................................5-41
ADAM-834A Low Power, Extended Temperature 14-bit A/D and S/H......5-45
ADAM-835A Low Power, Extended Temperature 15-bit A/D and S/H......5-45
MP8008R 8-bit 300 kHz Ultra-high Differential
Linearity Sampling A/D Converter.
5-49
SHAD2A Two-Channel, 16-bit Audio Digitizing Subsystem......................5-53

SELECTION GUIDE

| MAJOR CHARACTERISTIC OR APPLICATION REQ'MT | PRIMARY PARAMETER | SECONDARY PARAMETER | RECOMMENDED MODEL NO. | DATA SHEET ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| Sampling Time or Phase Related Signals | Simultaneity | 26 kHz Sampling Rate | ADAM-822 | 5-17 |
|  |  | 51 kHz Sampling Rate | ADAM-812 | 5-13 |
| High Speed Data Acquisition | 14-Bit Resolution | Programmable Gain | ADAM-724 | 5-3 |
|  | 16-Bit | Internal Sample \& Hold (2.3 $\mu \mathrm{s}$ ) | ADAM-826-1 | 5-33 |
|  |  | Buffered A/D $(2.0 \mu \mathrm{~s})$ | ADAM-826-2 | 5-37 |
|  |  | Unbuffered A/D (1.5 $\mu \mathrm{s}$ ) | ADAM-826-3 | 5-41 |
| Stereo Audio Digitizing | Low Distortion | Complete PCM Front-End | SHAD2A | 5-53 |
| Integral S/H and $A / D$, 20 kHz Throughput | Low Power | 14-Bit <br> Accuracy | ADAM-834A | 5-45 |
|  |  | 15-Bit Accuracy | ADAM-835A | 5-45 |
|  | Stability | 14-Bit <br> Accuracy | ADAM-824A | 5-23 |
|  |  | 15-Bit Accuracy | ADAM-825A | 5-23 |
| Nuclear Event Monitoring | Ultra-High Differential Linearity | High Speed | MP8008R | 5-49 |



## ANALOGB.

## A/DIA/M-724

Very High-Speed 14-bit, Multifunction Sampling A/D Converter

## Description

In a single low-profile module ( 0.375 " high), the ADAM-724 provides a $6.8 \mu \mathrm{~s}$, 14-bit, analog-to-digital converter plus three other user-accessible circuits - a sample-and-hold, a programmable gain differential amplifier, and a buffer amplifier. With this very high speed converter the ADAM-724 offers end-to-end throughput rates (including all four functions) that exceed 100,000 measurements/second. When used alone the converter provides throughput rates approaching 150 kHz . High accuracy has been maintained at these very high speeds; for example, end-to-end differential non-linearity is a superb $\pm 0.003 \%$ FSR max. ( $\pm 1 / 2$ LSB), with a tempco of only $\pm 3 \mathrm{ppm}$ FSR/ $/{ }^{\circ} \mathrm{C}$, max. A metal case preserves the module's performance in the presence of harsh electromagnetic and electrostatic interference. Moreover, using the ADAM-724 costs less than combining separate circuits that offer lesser performance.

The A/D/A/M-series of Analog Data Acquisition Modules was introduced to simplify the integration of high accuracy systems. Accordingly, the ADAM-724 offers flexibility and
(continued)


Figure 1. A/D/A/M-724 Functional Block Diagram.

## Features

■ Combined S/H, A/D, and Signal Conditioning in One Module

- Lower Cost than Separate AID and S/H
- Latched, Tri-State Outputs, Byte Selectable
- Complete in Low Profile 0.375 " ( 0.95 cm ) High, Shielded Case
- User Accessible $6.8 \mu \mathrm{~s}$, 14-bit A/D
- Input Flexibility

Differential input
Low feedthrough S/H
Pin programmable input ranges to 50V
End-to-End Performance Better than Separate Modules
$\pm 1 / 2$ LSB, max., differential non-linearity
$\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR, max., non-linearity tempco

## Applications

- Precision Data Acquisition Systems
$\square$ Medical Imaging
- Telecommunications
- Automatic Test Equipment
- Industrial Process Control. Systems

High Speed Burst Sampling
Nuclear Instrumentation

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG INPUT

Full Scale Range (FSR)
0 to $+5 \mathrm{~V}, 0$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ (See Table 3)
Impedance
$10^{9} \Omega \| 10 \mathrm{pF}$
Bias Current
10 nA max.
Maximum Voltage ${ }^{2}$ (signal plus common mode) $\pm 11 \mathrm{~V}$
Offset
Adjustable to zero

## ACCURACY@ $\mathbf{2 5}^{\mathbf{}}{ }^{\mathbf{C}}$

## Resolution

14 bits binary
Relative Accuracy @ 100 kHz ${ }^{3}$ (combined performance of buffer amp, PGA, S/H \& A/D) $\pm 0.006 \%$ FSR max.
Absolute Accuracy ${ }^{4}$
$\pm 0.01 \%$ FSR max.
Differential Non-Linearity
$\pm 1 / 2$ LSB max.
Quantizing Error
$\pm 1 / 2$ LSB
$\pm 3 \sigma$ Noise on 0 to +10 V FSR
$83 \mu \mathrm{~V}$ rms
Monotonicity
Guaranteed

## DYNAMIC PERFORMANCE ${ }^{1}$

Throughput Rate
100 kHz min.
A/D Conversion Time
$6.8 \mu \mathrm{~s}$ max.
S/H Acquisition Time
$3.0 \mu \mathrm{~s}$ max.
S/H Aperture Delay Time
30 ns
S/H Aperture Uncertainty ${ }^{5}$
$\pm 0.4$ ns
S/H Hold Mode Feedthrough -86 dB min.

## TEMPERATURE COEFFICIENTS

Differential Non-Linearity
$\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ typ.
$\pm 8 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typ.

> Gain
> $\pm 8 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ.
> Offset
> $\pm 12 \mathrm{ppm}$ FSRR $/{ }^{\circ} \mathrm{C}$ typ.
> Offset (A/D Ony)
> $\pm 3 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typ.

## STABILITY

Warm-Up Time ${ }^{2}$
10 minutes
Recommended Calibration Interval 6 months
Power Supply Sensitivity (per 1\% change in supply voltage)
$\pm 12 \mathrm{ppm}$ FSR max.

## POWER REQUIREMENTS

$+15 \mathrm{~V} \pm 3 \%$
50 mA
$-15 \mathrm{~V} \pm 3 \%$
50 mA
$+5 \mathrm{~V} \pm 5 \%$
300 mA

[^7]| Signal | Fan In (unit loads) | High State $=$ " 1 " | Low State = "0" | Comments |
| :---: | :---: | :---: | :---: | :---: |
| S/H MODE CONTROL | 2 | SAMPLE Mode ( $3 \mu \mathrm{~s} \mathrm{~min}$ ) $" 1 "=+3 V \mathrm{~min}$. | HOLD Mode (During conversion) " 0 " $=0.4 \mathrm{~V}$ max. | 10 ns max fall time |
| INTERLOCK | 1 | Inhibits SAMPLE Mode | No Effect | Normally tied to EOC |
| A/D TRIGGER | 1/4 | $0.1 \mu \mathrm{~s} \mathrm{~min}$. | $0.2 \mu \mathrm{smin}$. | Negative edge starts conversion |
| HIGH BYTE ENABLE | 1/4 | Outputs at High Impedance | $\mathrm{B} 1, \mathrm{~B} 1$ thru B6 active | - |
| LOW BYTE ENABLE | 1/4 | Outputs at High Impedance | B7 thru B14 active | - |

Digital Outputs ${ }^{6,7} \quad$ Table 2.

| Signal | Fan Out <br> (unit loads) | Timing | Comments |
| :---: | :---: | :---: | :---: |
| B1 and B1 thru B14 | 2 | Updated during the time <br> that EOC is <br> high and B15 is low <br> Goes high $0.1 ~$ s (typ.) after | Parallel data from tri-state <br> latches |
| End-of-Conversion (EOC) | 2 | B1 and B1 thru B14 are <br> A/D TRIGGER fall. Goes low <br> at end of conversion <br> "1-to-0" transition signals <br> that B1and B1 thru B14 will <br> update nominally $0.1 \mu \mathrm{~S}$ | "1-to-0" transition of EOC <br> later |

The AID/A/M-724 is normally operated using its built-in precision reference (REF IN tied to REF OUT). For ratiometric operation see Table 5.

## NOTES

1. Digital inputs and outputs are TTL compatible.
2. See timing diagram.

## Description (cont.)

control simplicity. Thus system designers can easily exploit its speed in numerous high accuracy applications such as precision data acquisition systems and medical imaging systems. Analog flexibility is provided by the module's differential input amplifier, by user access to the $6.8 \mu \mathrm{~s}$ A/D converter ( 147 kHz throughput rate), and by a capability for ratiometric measurements. Digital flexibility is provided by latched, tri-state, byte selectable output buffers that will directly drive a computer system data bus. Control is
simplified by a unique interlock on the $\mathrm{S} / \mathrm{H}$ which allows a single, easy to generate, input signal to control both the A/D and $\mathrm{S} / \mathrm{H}$.
Further, as a part of the A/D/A/M-series, the module offers overall performance that has been optimized through use of a rigorous error budget. Systems using this module are not subject to the surprises that commonly occur when separate amplifier, S/H and A/D circuits are interfaced. The ADAM-724's end-to-end accuracy is guaranteed and is actually better than that of many S/H circuits alone.

## USING THE ADAM-724

## Accuracy

Interface problems commonly restrict accuracy in high speed systems that incorporate separate S/H and A/D units - problems such as ground loops, crosstalk, impedance mismatch, and radiated interference. Using the ADAM-724 totally avoids such problems. The module performs the functions of buffering, amplification, sampling, and conversion with its inputs and outputs interconnected per Figure 2. Figure 3 shows that end-to-end accuracy of these four functions is exceptional, well within the specified $\pm 1 / 2$ LSB differential non-linearity.

## Ease of Control

Using the ADAM-724 requires a minimum of control curcuitry. Conversions may be obtained via one control signal supplied in parallel to both the S/H MODE CONTROL input and the A/D TRIGGER (Figure 2). This signal may be simply a $50 \%$ duty cycle square wave pulse train of frequency equal to the required conversion rate. This duty cycle need not be carefully controlled, because connecting the EOC output to the S/H INTERLOCK input as shown automatically keeps the $\mathrm{S} / \mathrm{H}$ in the HOLD mode during a conversion and returns it to SAMPLE when the conversion is complete.


Figure 2. Typical Interconnection.

## Interface Flexibility

The module's flexibility makes its accuracy and control simplicity available for use with a wide variety of analog front ends and digital processing/display subsystems.

Analog Interface Flexibility: A programmable gain amplifier allows pin-programming of bipolar and unipolar inputs, with ranges from 2 V to 50 V . The $\mathrm{S} / \mathrm{H}$ reduces aperture uncertainty to $\pm 0.4 \mathrm{~ns}$, allowing acquisition of high frequency inputs.


Figure 3. ADAM-724 Crossplot shows highly linear end-to-end performance.

Digital Interface Flexibility: The 14 parallel output data lines are tri-state buffered and may be enabled in two bytes for interfacing with an 8-bit wide data bus, or in one byte. The output of the ADAM-724 is statically available most of the time. Data from each measurement is latched at the end of the conversion (EOC) and then remains available during sampling and conversion of the next measurement. The data invalid time is the period between DATA UPDATE and EOC (nominally $0.4 \mu \mathrm{~s}$; see SYSTEM TIMING). This latching architecture simplifies processor software by allowing nearly a full measurement period for reading the results of a conversion. For example, a system may trigger several ADAM-724 modules simultaneously and then sequentially strobe their outputs onto a common data bus.

BUFFER AMPLIFIER: This circuit's ultrahigh input impedance minimizes source loading errors (especially useful when interfacing to an analog input multiplexer).
PROGRAMMABLE GAIN AMPLIFIER: The PGA is a differential amplifier used to provide scaling, offsetting, and inversion as detailed under RANGE PROGRAMMING. It accepts unipolar and bipolar inputs, and may be connected to provide gains from 0.2 to 5 . Because the PGA is differential, it may also be connected to reject common mode voltage as shown under APPLICATIONS.


## System Timing

SAMPLE-AND-HOLD: The Sample-and-Hold is a fast circuit with an acquisition time of $3 \mu \mathrm{~s}$. Its low aperture uncertainty ( $\Delta \mathrm{t}=0.8 \mathrm{~ns}$ ) reduces rms aperture error to $\sim 1$ LSB even at 50 kHz , the maximum information frequency of data that can be properly digitized without aliasing at the module's 100 kHz sampling rate (single channel application). This may be seen from the relationship:
rms error $(\% \mathrm{FSR})=222 \times f(\mathrm{~Hz}) \times \Delta \mathrm{t}(\mathrm{sec})$.
For multiple-channel applications, excellent feedthrough performance is obtained by switching the multiplexer channels coincident with the S/H switching to either mode.
The INTERLOCK input may be used to prevent switching of the S/H during a conversion. When the INTERLOCK signal is low, it has no effect. When INTERLOCK goes high, it inhibits the S/H from taking a new sample. (Suggested usage is to connect the EOC output, which is high during a conversion, to the INTERLOCK input. This allows the S/H MODE CONTROL to return to the SAMPLE state prior to the end of a conversion, yet keeps the S/H in the HOLD mode. At the end of the conversion EOC goes low and the $\mathrm{S} / \mathrm{H}$ automatically switches to the SAMPLE mode.)
For arbitrary signal processing, you may connect directly to the S/H (see APPLICATION). Its input range is 0 to +10 V .

ANALOG-TO-DIGITAL CONVERTER: The A/D is a fast, current-steering successive approximation converter with low offset drift. It is user-accessible, providing up to a 128 kHz throughput rate when used with an external sample-and-hold such as the $1 \mu \mathrm{~s}$ MP271, or a 147 kHz throughput rate when used with no sample-and-hold. Its reference input allows true ratiometric measurements as shown under APPLICATIONS.
The A/D's outputs are from tri-state buffers which drive up to 2 standard TTL loads. The output devices are 74LS374 IC's.
For arbitrary signal processing, you may connect directly to the A/D. Its input impedance is $2.5 \mathrm{k} \Omega$ and its input range is 0 to +10 V . When using the A/D converter by itself, it is important to note that THE LOGIC SENSE OF THE AID OUTPUT, 'REFERENCED TO THE AID INPUT, IS OP. POSITE THAT OF COMMON PRACTICE. For a nominal +10 V input to the $A / D$, its output is all zeros; for a 0 V input, its output is all ones. THIS IS INVISIBLE TO THE MODULE USER WHO CONNECTS THE PGA PER RECOMMENDATIONS AS AN IN. VERTER WITH OFFSET. (see RANGE PROGRAMMING for recommendations. Information published in this data sheet is based on the use of these recommendations.


Figure 4. ADAM-724 Simplified Schematic.

## RANGE PROGRAMMING



Figure 5. Programmable Gain Amplifier provides gains from 0.2 to 5 (to produce 0 to 10 V output) and accepts differential inputs.


## Output Coding

Table 3. Recommended PGA Connections.

## APPLICATIONS

## Direct Wiring to Data Bus

Figure 6 illustrates the easy connection of multiple ADAM-724 modules to a micro or mini-computer data bus. In applications such as multi-channel scanning systems several A/D converters may present data to a single bus-oriented computer system. The ADAM-724 data outputs may be connected directly to the bus lines and will drive them
without the need for separate interface or pull-up components. The tri-state output devices allow direct wire "OR" connection. Because the outputs are latched, data may be transferred at any time, even during a conversion, except for a very short interval (nominally $0.4 \mu \mathrm{~s}$ ). The 14 -bit data word may be taken as two successive 8 -bit bytes or as one 14-bit byte. Figure 6 shows right justification onto an 8 -bit bus, with two diodes used to "zerofill" the two MSB's of the High Byte.


Figure 6. Connecting Several A/D/A/M-724's to a Data Bus is made simple by latched, two byte, tri-state outputs.

## Rejection of Common Mode Voltage

Figure 7 illustrates the flexibility inherent in the ADAM-724. The internal buffer amplifier and the PGA, plus a single external buffer amplifier connected at the signal low input, form a high input impedance differential amplifier. This arrangement buffers the out-
puts of the multiplexer to provide full differential multiplexing. Common mode voltages of up to $\pm 6 \mathrm{~V}$, for example due to the ground potential differences between the signal sources and the converter common, are rejected by this arrangement.


Figure 7. Rejection of Common Mode Voltages using the differential input capability of the A/D/A/M-724.

## Automation Compensation

Figure 8 illustrates yet another advantage of the ADAM-724 - ratiometric operation. The output of the strain gauge, for example, is meaningful only with respect to its excitation voltage, i.e., it is their ratio which conveys information. A common practice is to digitize both the strain gauge output and its excita-
tion voltage, and then digitally compute the true reading. The ADAM-724 module allows the excitation voltage to be used in place of its internal precision reference. Slow variations of $E_{e x}$ with time and temperature would then be compensated automatically, and there would be a corresponding reduction in computer loading.


Figure 8. Automatic Compensation of strain gauge excitation voltage drift using the ratiometric capability of the A/D/A/M-724.

## CALIBRATION

Due to its excellent long-term stability, the ADAM-724 will rarely require recalibration. However, it should be recalibrated whenever the full scale range is changed.

## Comments

1. Readjust the ZERO OFFSET control before readjusting the RANGE control.
2. The voltages in the Zero Adjust column of Table 4 are $11 / 2$ LSB's below nominal FSR; those in the Range Adjust column are $1 / 2$ LSB above the most negative point of the input range.
3. The span of each adjustment is $\pm 0.1 \%$ FSR.

Zero Offset Adjustment Procedure

1. Apply the input voltage shown in Table 4.
2. Adjust the ZERO OFFSET control so that the LSB of the output code, $111 \ldots 110 / 1$ ( $\mathrm{B}_{1}, \ldots, \mathrm{~B}_{14}$ ), alternates equally between " 1 " and " 0 ".
Range Adjustment Procedure
3. Apply the input voltage shown in Table 4.
4. Adjust the RANGE control so that the LSB of the output code, $000 \ldots$. 000/1, alternates equally between " 1 " and '0"'.
Table 4. Buffer Amp Input Voltages for Module Calibration*

| Nominal FSR | Zero Adj. | Range Adj. | LSB Size |
| :---: | :---: | :---: | ---: |
| 0 V to +5 V | +4.99954 V | +0.00015 V | $305 \mu \mathrm{~V}$ |
| 0 V to +10 V | +9.99909 V | +0.00031 V | $610 \mu \mathrm{~V}$ |
| -5 V to +5 V | +4.99909 V | -4.99969 V | $610 \mu \mathrm{~V}$ |
| -10 V to +10 V | +9.99817 V | -9.99939 V | $1221 \mu \mathrm{~V}$ |




Pin Designations

## REFERENCE SPECIFICATIONS

## REFERENCE OUTPUT*

Voltage $+10 \mathrm{~V} \pm 0.005 \mathrm{~V}$ Impedance $0.1 \Omega$ Current 1 mA
$\qquad$

REFERENCE INPUT for full accuracy 5 V to 10 V
$1 \mu \mathrm{~A}$
*Independent of Range Pot Setting

Table 5


## ANALOGC.

A/D/A/M-812
Dual Channel Simultaneously Sampling 51 KHz 12-Bit AD Converter

## Description

The ADAM-812 is a two-channel data acquisition system consisting of two simultaneously operating Sample-and-Hold Amplifiers $(S / H)$ and a 12-bit Analog-to-Digital Converter (ADC). The dual S/H's allow near simultaneous (within 5 ns ) sampling of time- or phase-related signals, thereby reducing the complexity of expensive hardware and/or software time-skew correction in systems such as quadrature demodulated signal processing front-ends, component transfer function testers, and colorimeters.
In systems using time-shared S/H's or dedicated S/H's controlled with insufficient simultaneity, the information contained within the time or phase interrelationship can be lost. Sequential sampling of these signals may require costly correcting of errors induced by the sampling process; these correction methods are of use only if the delay between the samples is known precisely. By sampling the input pair within 5 ns of one another, the ADAM-812 significantly reduces these sources of error.
The ADAM-812 provides a twochannel throughput rate of 51 kHz (single channel throughput of 91 kHz ). ADAM-812 specifications are based on an end-to-end error


Figure 1. ADAM-812 Functional Block Diagram.
budget that accounts for all internal error sources, including S/H droop at a 51 kHz sampling rate, errors due to aperture uncertainty for bandlimited signals up to 25 kHz , S/H pedestal non-linearities, and A/D nonlinearities. The design of the ADAM-812 takes maximum advantage of the temperature and time stability of discrete components, and offers an end-to-end accuracy of $\pm 1$ LSB maximum; this is in direct contrast to monolithic S/H's which commonly exhibit more than 1 LSB equivalent error at the 12-bit level by themselves.
The fully integrated ADAM-812 is tested as a subsystem by ANALOGIC, which frees the system designer from performing a myriad of time-consuming design and testing tasks, and minimizes system production and test efforts. A fully tested and shielded subsystem, the ADAM-812 offers superior performance, ease of use and integration, at a lower cost than the parts alone for a custom design.

## Features

- Guaranteed Overall Transfer Accuracy $\pm 0.025 \%$ FSR, maximum
- High Throughput Rate 51,000 two-channel samples per second 91,000 single-channel samples per second
- Low Aperture Uncertainty Time 5 ns-minimizes phase error between simultaneously sampled channels
- Universal Data Systems Compatibility Standard TTL digital inputs/outputs
- Low Noise $165 \mu \mathrm{~V}$ rms
- Separate Reference Input and Output
Allows ratiometric operation
$\square$ Small Size 2" x 3" x $0.375^{\prime \prime}$
■ RFI and EMI Shielded
(All Specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted.)


## ANALOG INPUTS

## Number of Channels:

2
Configuration:
Voltage Follower Input
Full Scale Range (FSR):
0 to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}$, or $\pm 10 \mathrm{~V}$; Factory configured
Maximum Input Without Damage:
$\pm 15 \mathrm{~V}$
Input Impedance:
$>100$ Megohms
Input Bias Current':
$<1 \mathrm{nA}\left(\right.$ at $\left.25^{\circ} \mathrm{C}\right)$

## ACCURACY

(at 51 kHz Sampling Rate, at $25^{\circ} \mathrm{C}$, nominal)
Relative Accuracy ${ }^{2}$ :
$\pm 0.025 \%$ FSR, maximum
Differential Non-linearity:
$\pm 1 / 2$ LSB, maximum

## Noise:

$165 \mu \mathrm{~V}$ rms maximum for 10V FSR; $320 \mu \mathrm{~V}$ rms maximum for 20 V FSR; referred to input; measured over dc to 1 MHz bandwidth

## Monotonicity:

Guaranteed; No missing codes
S/H Hold Mode Feedthrough Rejection Ratio ${ }^{3}$ :
-82 dB minimim; measured with 1 kHz
squarewave, full scale
Channel-to-Channel Crosstalk ${ }^{4}$ :
-110 dB at 10 kHz
Total Offset Error (Untrimmed, including pedestal Error) ${ }^{5}$ :
25 mV maximum; adjustable to zero
Gain Error ${ }^{5,6}$ :
$\pm 0.025 \%$ FSR, maximum
Gain Accuracy Between Channels:
$\pm 7.5 \mathrm{mV}$, maximum

## DYNAMIC PERFORMANCE

Maximum Dual Channel Sampling Rate ${ }^{7}$ :
2 samples $19.5 \mu \mathrm{~s}(51 \mathrm{kHz})$
Maximum Single Channel Sampling Rate ${ }^{7}$ :
1 sample/11.0 $\mu \mathrm{S}(91 \mathrm{kHz})$
S/H Acquisition Time to $\mathbf{1 / 2}$ LSB:
$4.5 \mu \mathrm{~s}$ maximum
S/H Droop Rate (at $25^{\circ} \mathrm{C}$ ) ${ }^{1}$ :
$0.02 \mu \mathrm{~V} / \mu \mathrm{s}$, typical, $0.2 \mu \mathrm{~V} / \mu \mathrm{s}$, maximum
S/H Multiplexer Settling Time to $\pm 1 / 2$ LSB:
Refer to Timing Diagram
S/H Aperture Delay Time:
50 ns typical
S/H Aperture Uncertainty Time:
5 ns typical

## STABILITY

Differential Non-linearity Temperature Coefficient:
$\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum
Offset Temperature Coefficient Unipolar:
$\pm 10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR Maximum
Bipolar:
$\pm 15 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum
Gain Temperature Coefficient:
$\pm 20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum
Power Supply Sensitivity:
$0.003 \%$ FSR per percent change in Supply
Voltage
Warm-up Time to Specified Accuracy:
5 Minutes

DIGITAL INPUT/OUTPUT
General:
Inputs: 1 TTL LS Load, each; Outputs: 2 TTL Load Fanout, each
TTL positive true is Logic " 1 "
Logic " 0 " $=0.4 \mathrm{~V}$ maximum for output; 0.8 V maximum for input
Logic " 1 " $=2.4 \mathrm{~V}$ minimum for output; 2.0 V minimum for input
S/H Select:
Logic " 0 " selects S/H A, logic "1" selects S/H B
S/H Mode Control:
Logic " 0 " selects HOLD mode, logic " 1 " selects SAMPLE mode for both channels

## A/D Trigger:

Positive pulse, trailing edge triggered; 100 ns minimum pulse width

## Data:

12 data bits plus MSB; binary, offset binary, or two's complement coding
EOC:
Logic " 1 " during conversion; " 1 " to " 0 " transition indicates data available

## POWER REQUIREMENT ${ }^{8}$

$+15 \mathrm{~V}, \pm 3 \%$
60 mA maximum
$-15 \mathrm{~V}, \pm 3 \%$
70 mA maximum
$+5 \mathrm{~V}, \pm 3 \%$
65 mA maximum

## ENVIRONMENTAL AND MECHANICAL

Operating Temperature:
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature:
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

Relative Humidity:
Up to $95 \%$, non-condensing

## Dimensions:

2:00" x 3.00" x 0.375 "
( $50.8 \times 76.2 \times 9.53 \mathrm{~mm}$ )

## Shielding:

Electromagnetic 5 sides
Electrostatic 6 sides

## NOTES:

1. Doubles every $10^{\circ} \mathrm{C}$
2. Includes effects of input switching, buffer amplifier, S/H amplifier and ADC
3. Measured on S/H output, in HOLD mode with input signal as stated
4. Measured on Channel A S/H output with input grounded. Input signal applied to Channel B input. Both channels in SAMPLE mode
5. Offset and gain errors are externally adjustable to zero
6. With 50 ohm, $1 \%$ fixed resistor installed in series with Reference input
7. On $\pm 10 \mathrm{~V}$ FSR
8. Digital ground, analog ground and case are tied internally

## Typical Timing

Figure 2 depicts a typical timing relationship among the various control signals required by the ADAM-812. Channel $A$ and $B$ are simultaneously sampled, then sequentially converted to digital data.
The S/H amplifiers require $4.5 \mu \mathrm{~s}$ to simultaneously acquire the signals on both input channels (to within 1/2 LSB for a worst case full-scale input step). Once the signal pair is acquired, the S/H Control can be switched into the HOLD mode. If the application warrants, the S/H Control input can also be used as the A/D Trigger input.
The diagram indicates that the output data from the A/D converter is valid after a 10 ns delay from the logic " 1 " to " 0 " transition of EOC. The output data can be read at this time or at any time up to the next $A / D$ trig-
ger, since the last bit (LSB) decision is made, and the result settled prior to the EOC transition. The S/H Control can be switched to SAMPLE while the second data word is being read, with no effect on the data.

## Offset

A separate, external 20 kohm multi-turn potentiometer for each S/H amplifier is recommended, per Figure 3 . The +15 V source used to power the ADAM-812 should be used for the offset circuit as well.
With S/H A selected and the S/H Control line at logic " 1 " (SAMPLE), supply the input indicated in the Calibration Voltages table to input A. Adjust the S/H A offset pot until the LSB of the output data word varies equally between 0 and 1. Repeat the above procedure for $\mathrm{S} / \mathrm{H} \mathrm{B}$.

## Gain

If gain trimming is required by the application, a 100 ohm, multi-turn potentiometer connected between the 10V REF OUT and REF IN pins per Figure 3 will provide an approximate $\pm 0.25 \%$ FSR adjustment in gain. For many applications, a fixed 50 ohm, $1 \%$ resistor may be used in place of the trimpot.
Gain will rarely require recalibration in most applications. If gain is to be adjusted, follow the procedure below, after performing the offset procedure for both S/H's.
Select either the A or B S/H, and supply a logic " 1 " to the S/H Control line (SAMPLE). Supply the input indicated in the Calibration Voltages table to the selected input. Adjust the optional 100 ohm trimpot until the LSB of the data word varies equally between 0 and 1 .


Figure 2. ADAM-812 Typical Timing Diagram for Single-Channel or Dual-Channel Simultaneous Sampling, $\pm 10 \mathrm{~V}$ FSR.

## Unipolar Binary

| Input | $\mathbf{B 1}$, | $\mathbf{B 2}$, | $\mathbf{B 3}$, | $\mathbf{B 4}$, | $\mathbf{B 5}$, | $\mathbf{B 6}$, | $\mathbf{B 7}$, | $\mathbf{B 8}$, | $\mathbf{B 9}$, | $\mathbf{B 1 0}$, | $\mathbf{B 1 1}$, | $\mathbf{B 1 2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| +9.9976 V | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0.0000 V | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Offset Binary*

| Input | $\mathbf{B 1}$, | $\mathbf{B 2}$, | $\mathbf{B 3}$, | $\mathbf{B 4}$, | $\mathbf{B 5}$, | $\mathbf{B 6}$, | $\mathbf{B 7}$, | $\mathbf{B 8}$, | $\mathbf{B 9}$, | $\mathbf{B 1 0}$, | $\mathbf{B 1 1}$, | $\mathbf{B 1 2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| +9.9951 V | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0.0000 V | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| -10.0000 V | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Two's Complement*

| Input | B1, | B2, | B3, | B4, | B5, | B6, | B7, | B8, | B9, | B10, | B11, |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | B12

Output Coding. *For $\pm 5 \mathrm{~V}$ Full Scale Range, divide voltages by 2



Figure 3. Gain and Offset Trimming of ADAM-812

| Calibration Voltages |  |  |  |
| :---: | :---: | :---: | :---: |
| Adjustment <br> Procedure | Input Full Scale Range |  |  |
|  | 0 to +10 V | $\pm 10 \mathrm{~V}$ | $\pm 5 \mathrm{~V}$ |
| Offset | +0.0012 V | +0.0024 V | +0.0012 V |
| Gain | +9.9976 V | +9.9951 V | +4.9975 |

ORDERING GUIDE
For an input voltage range of: Specify:
0 V to +10 V FSR
ADAM-812-1
$\pm 10 \mathrm{~V}$ FSRADAM-812-2
$\pm 5 \mathrm{~V}$ FSR
ADAM-812-3


## ANALOGC:

ADAM-822
Simultaneously Sampling Low Cost 12-Bit Analog-to-Digital Converter

## Description

The ADAM-822 is a self-contained, two channel, analog-to-digital conversion module complete with two simultaneously operating sample-and-hold ( $\mathrm{S} / \mathrm{H}$ ) amplifiers, a stable reference, and a 12-bit successive approximation A/D converter. An added feature is the fact that this unit includes four input channels that can be chosen in two groups of two each. This module has been designed to simplify the hardware and software of systems that utilize two or more phase- or time-related signal channels or cross-channel measurements such as quadrature demodulated signal processor front-ends, component transfer function testers, and colorimeters. By adding a multiplexer to each of the four inputs of the ADAM-822, a mini-DAS (Data Acquisition System) can be configured at a very modest cost.
In many systems, information of interest is often carried by the time-or phase-interrelationship among signal channels. Such information may be lost when time-shared S/H's are used or when dedicated S/H's are triggered with insufficient simul-


Figure 1. ADAM-822 Functional Block Diagram. High precision sample \& holds ensure low aperture uncertainty and high measurement accuracy.
taneity. Sequential sampling of the related signals may require costly software correction of errors induced by the sampling process; such correction methods are generally useful only if the delay between samples is known precisely. The
(continued)

## Features

- Guaranteed Overall Transfer Accuracy
$\pm 0.025 \%$ FSR, maximum
- High Throughput Rate at Low Cost
Two Channels at 26,000 samples per second each
Single Channel at 52,600 samples per second
- Low Aperture Uncertainty Time-5 ns Minimizes phase error between simultaneously sampled channels
- Universal Data Systems Compatibility
Standard TTL digital inputs/outputs
- Low Power
1.25W, typ.

■ Low Noise
0.01\% FSR

- Flexibility Independently selectable input channel pairs
Multiple units can be driven by single TTL line driver for multiple simultaneously sampled channels
- Ratiometric Operation
- Superior Performance

Lower cost and higher overall accuracy when compared to functionally equivalent designs based on integrated circuits

- Small Size

2" X 3" X 0.375 "
( $50.8 \times 76.2 \times 9.53 \mathrm{~mm}$ )

- RFI \& EMI Shielding


## SPECIFICATIONS

```
ANALOG INPUTS
Number of Channels
4 (2 pair)
Configuration
Voltage follower input
Full Scale Range (FSR)
0 to \(+0 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}\) (see Ordering Guide)
Maximum Input Without Damage
\(\pm 15 \mathrm{~V}\)
Input Impedance
\(>100 \mathrm{M} \Omega\)
Input Bias Current
\(\leq 1 \mathrm{nA}\left(\right.\) at \(25^{\circ} \mathrm{C}\) )
```

ACCURACY (at 26 kHz sampling rate and $25^{\circ} \mathrm{C}$, nominal)
Relative accuracy ${ }^{2}$ $\pm 0.025 \%$ FSR max.
Differential Non-Linearity
$\pm 1 / 2$ LSB max.
$\pm 3 \sigma$ Noise (Shorted input, measured over dc to
1 MHz Bandwidth)
$0.01 \%$ FSR, p-p Referenced to input, max.
Monotonicity
Guaranteed; No missing codes
S/H Hold Mode Feedthrough Rejection Ratio ${ }^{3}$
$-82 \mathrm{~dB} ; 1 \mathrm{kHz}$ square wave, full scale
Channel-to-Channel Crosstalk ${ }^{4}$

- 110 dB @ 10 kHz

Offset Error (Untrimmed) ${ }^{5}$
25 mV , max.; adjustable to zero
Gain Error (Untrimmed) ${ }^{5}{ }^{6}$
$\pm 0.25 \%$ FSR max.
Gain Accuracy Between Channels $\pm 7.5 \mathrm{mV}$ max.

## DYNAMIC PEFORMANCE

Maximum Dual Channel Sampling Rate ${ }^{7}$ 26 kHz (2 samples $/ 39 \mu \mathrm{~s}$ )
Maximum Single Channel Sampling Rate ${ }^{8}$
52.6 kHz

S/H Acquisition Time to $1 / 2$ LSB
$5 \mu \mathrm{~S}$ max.
S/H Aperture Delay Time
50 ns typ.
S/H Aperture Uncertainty Time
5 ns typ.
S/H Droop Rate (at $25^{\circ} \mathrm{C}$ )
$0.02 \mu \mathrm{~V} / \mu \mathrm{S}$ typ., $0.2 \mu \mathrm{~V} / \mu \mathrm{s}$ max.
Input Switching and S/H Multiplexer Settling
Time to $\pm 1 / 2$ LSB
Refer to timing diagram (Figure 2)

STABILITY
Tempco of Differential Non-Linearity $\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR max.

Tempco of Offset - Unipolar
$\pm 10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, FSR max.
Tempco of Offset - Bipolar
$\pm 15 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, FSR max.
Tempco of Gain
$\pm 20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, FSR max.
Power Supply Sensitivity
$0.003 \%$ FSR/\% change in Vsupply
Recommended Recalibration Interval 6 months
Warm-Up Time to Specified Accuracy 5 minutes

## DIGITAL INTERFACES

General
Inputs: 1 TTL LS Load, each; Outputs: 2 TTL load fanout, each
TTL positive true is logic " 1 "
Logic " 0 ": 0.4 V max. for outputs; 0.8 V max. for inputs
Logic " 1 ": 2.4 V min. for outputs; 2.0 V min. for inputs
Inputs
Input Channel Select
Logic " 0 " selects channel 1;
logic " 1 " selects channel 2
S/H Select
Logic "0" selects S/H A; logic " 1 " selects S/H B S/H (Mode) Control
Logic " 0 " selects HOLD mode; logic " 1 " selects SAMPLE
A/D Trigger
Positive Pulse, trailing edge triggered; $0.1 \mu \mathrm{~s}$
pulse width minimum
Outputs
Data
12 data bits in Binary, 2's Complement, or Offset Binary (see Coding Table for format)
EOC
Logic "1" during conversion

## POWER \& ENVIRONMENTAL

Analog Power Requirements ${ }^{\ominus}$
$+15 \mathrm{~V} \pm 3 \%$ @ 35 mA , typ. \& - 15V @ 35 mA ,
typ.
Digital Power Requirement ${ }^{9}$
$+5 \mathrm{~V}, \pm 3 \% 40 \mathrm{~mA}$, typ.
Operating Temperature
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
Up to $95 \%$, non-condensing
Modupac ${ }^{\text {TM }}$ Dimensions
2" x 3" $\times 0.375$ "
$(50.8 \times 76.2 \times 9.53 \mathrm{~mm}$ )

## Electromagnetic Shielding

## 5 sides

Electrostatic Shielding
6 sides

## NOTES:

1. Doubles every $10^{\circ} \mathrm{C}$.
2. Includes effects of input switching, buffer, amplifiers, S/H Amp and ADC.
3. Measured on S/H output, in HOLD mode with input signal as stated.
4. Measured on Channel A S/H output with input grounded. Input signal applied to Channel B input. Both channels in SAMPLE mode.
5. Offset and gain errors are extremely adjustable - see Figures 3 and 4.
6. With $50 \Omega, 1 \%$ fixed resistor installed per Figure 4.
7. On $\pm 10 \mathrm{~V}$ FSR.
8. On $\pm 5 \mathrm{~V}$ FSR; 50 kHz on $\pm 10 \mathrm{~V}$ FSR.
9. Digital Ground, Analog Ground, and case are tied internally.

## Description (cont.)

ADAM-822 eliminates these sources of error and additional system cost by providing simultaneous sampling of either channel pair - within 5 ns of each other. For an equivalent system configuration, only half of the number of A/D converters need be used, further reducing overall system costs.
The specification for the ADAM-822 is based on an end-to-end error budget that accounts for all internal error sources, including $\mathrm{S} / \mathrm{H}$ droop at a 26 kHz sampling rate, error due to aperture uncertainty for band limited signals up to $12.5 \mathrm{kHz}, \mathrm{S} / \mathrm{H}$ pedestal non-linearities, input switching crosstalk, and A/D nonlinearities. With a throughput time for two digitized samples of less than $40 \mu \mathrm{~s}$, it provides 12 -bit ( $\pm 1$ LSB) overall accuracy. The use of discrete component $\mathrm{S} / \mathrm{H}$ amplifiers contributes greatly to the overall accuracy of the ADAM-822 - by contrast functionally comparable monolithic S/H's commonly exhibit more than 1 LSB equivalent error at the 12-bit level by themselves.

As a member of the ADAM Series of analog data acquisition modules, the ADAM-822 is fully integrated and tested as a subsystem. This frees the system engineer from performing a myriad of time-consuming design tasks and minimizes system production and test efforts. With no need to design a printed circuit layout for critical analog components, users avoid potential costly PC design iterations, which are commonly required to eliminate ground loops and other noise and error sources. A fully tested
and shielded subsystem, the ADAM-822 offers superior performance, ease of use, and integration, at a lower cost than the parts alone for a comparable custom design.

## Typical Timing

Figure 2 shows the typical timing relationship among the various control signals required by the ADAM-822. In this example, channels 2A and 2B are selected first. Their input signals are sampled simultaneously, then the samples are sequentially converted to digital data. Subsequently, the process is repeated for channels 1 A and 1B. The S/H amplifiers require $5 \mu \mathrm{~s}$ to simultaneously acquire the signals on both input channels (to within $1 / 2$ LSB for a worst case full-scale input step). Once the signal pair is acquired, the S/H Control can be switched to the HOLD mode. Because the sample-to-hold mode settling time (input switch settling time) is less than the A/D Trigger's internal propagation delay, the S/H Control input can be used as the A/D Trigger input, if the application warrants.
The diagram shows input switch settling time and S/H Select settling time to be $2 \mu \mathrm{~s}$ each. These are the maximum times; typical values are $1 \mu \mathrm{~s}$ each. The diagram also shows that the output data from the A/D converter is valid at the instant of the EOC falling edge transition. The output data can be read at this instant or at any time up to the next A/D Trigger, since the last bit (LSB) decision is made, and the result settled, prior to the EOC transition. The S/H Control can be switched to SAMPLE while the data is being read, with no effect on the data.

## ADJUSTMENTS \& CALIBRATION Offset

A separate, external $20 \mathrm{k} \Omega$ multi-turn potentiometer for each S/H amplifier is recommended, per Figure 3. The +15 V source used to power the ADAM-822 may be used for the offset circuit as well.
With S/H A selected and the S/H Control line at logic " 1 " (Sample), supply the input indicated in the Calibration Voltages table to either Ch. 1 or Ch. 2. Adjust the S/H A offset pot until the LSB of the output data word varies equally between 0 and 1. Repeat the above procedure for $\mathrm{S} / \mathrm{H} \mathrm{B}$.


Figure 2. ADAM-822 Typical Timing Diagram for Dual-Channel Simultaneous Sampling, $\pm 10 \mathrm{~V}$ FSR.

## Gain

If gain trimming is required by the application, a $100 \Omega$, multi-turn potentiometer connected between the 10V Ref Out and Ref In pins per Figure 4 will provide an approximate $\pm 0.25 \%$ FSR adjustment in gain. For many applications, a fixed $50 \Omega 1 \%$ resistor may be used in place of the trimpot.
Gain will rarely require recalibration in most applications. If gain is to be adjusted, follow the procedure below, after performing the offset adjust procedure for both S/H's.
Select any channel by providing the appropriate logic levels to the Channel Select, S/H Select, and S/H Control lines (S/H Control should be in the SAMPLE mode-logic "1"). Supply the input indicated in the Calibration Voltages table to the selected channel. Adjust the optional 100 trimpot until the LSB of the data word varies equally between 0 and 1 .


Figure 3. Offset Trimming Circuit.


## Output Coding



Figure 4. Gain Trimming Circuit.

| Calibration Voltages |  |  |  |
| :---: | :---: | :---: | :---: |
| Adjustment <br> Procedure | Input Full Scale Range |  |  |
|  | 0 to +10 V | $\pm 10 \mathrm{~V}$ | $\pm 5 \mathrm{~V}$ |
| Offset | +0.0012 V | +0.0024 V | +0.0012 V |
| Gain | +9.9976 V | +9.9951 V | +4.9975 |



ORDERING GUIDE
For an input voltage range of:
Specify:

$$
\begin{aligned}
0 \text { to } & +10 \mathrm{~V} \text { FSR } \\
& \pm 10 \mathrm{VFSR} \\
& \pm 5 \mathrm{~V} \text { FSR }
\end{aligned}
$$A/D/A/M 822-3



## ANALOGC.

## ADAM-824AI 825A

14- and 15-Bit
Highly Stable, Low Power Sampling AJD Converters

## Description

The ADAM-824A and -825A analog-to-digital converters (ADCs), with their integral sample-and-hold amplifiers, are complete data acquisition subsystems that provide overall accuracies better than many ADCs alone. This high level of accuracy is accompanied by improved stability and reduced power dissipation over previous converters of similar architecture. For example, with a differential linearity tempco of $\pm 3 \mathrm{ppm}$, the 14-bit accuracy of the ADAM-824A is maintained over a full $20^{\circ} \mathrm{C}$ temperature rise! Due to the integral sample-and-hold (S/H) circuits, the ADAM-824A and -825A give the system designer optimized system performance and eliminate the potential difficulties in integrating the $\mathrm{S} / \mathrm{H}$ and $\mathrm{A} / \mathrm{D}$ of precision data acquisition systems.
Both the ADAM-824A and 825A provide guaranteed end-to-end performance in a small 2" x 4" modular package. Their accuracy, along with features such as tri-state output, low power dissipation, and low cost, make them an excellent choice for a variety of data acquisition systems, automatic test equipment, and analytical instrumentation.

## Features

■ Combined S/H and A/D in a 2" x 4" x 0.44 " Module

- High Throughput Rate 20 kHz (Includes both sampling and conversion time)
- Low Power 0.9W
- Precision S/H

True 14-bit performance

- Low Differential Nonlinearity $\pm 1 / 2$ LSB maximum (824A)
- Low Tempco

Differential nonlinearity $\pm 2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum (825A)

- Low Noise
$50 \mu \mathrm{~V}$ rms (ADC)
- Byte-Selectable Tri-State Buffered Outputs
- Pin-Programmable Input Voltage Range
0 V to $+5 \mathrm{~V}, 0 \mathrm{~V}$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}$, $\pm 10 \mathrm{~V}$


## Applications

Automatic Test Equipment
Analytical Instrumentation
Precision Data Acquisition Systems
Materials Testing


Figure 1. ADAM-824A/5A Functional Block Diagram.

## SPECIFICATIONS

(Includes combined S/H and A/D performance, and applies to both ADAM-824A and ADAM-825A except where noted)
(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG INPUT

Full Scale Range (FSR)
0 V to $+5 \mathrm{~V}, 0 \mathrm{~V}$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$
Maximum Input Without Damage
15V
Impedance
100 Megohm || 5 pF
Bias Current ${ }^{1}$
1 nA maximum

## ACCURACY

Absolute Accuracy ${ }^{2}$
Calibrated to $\pm 0.006 \%$ FSR
Relative Accuracy ${ }^{3}$
$\pm 0.005 \%$ FSR maximum (ADAM-824A),
$\pm 0.003 \%$ FSR maximum (ADAM-825A)
Differential Nonlinearity
$\pm 0.003 \%$ FSR maximum (ADAM-824A),
$\pm 0.002 \%$ FSR maximum (ADAM-825A)
Quantizing Error
$\pm 1 / 2$ LSB
Noise (S/H plus AD)
$75 \mu \mathrm{~V}$ rms
Noise (A/D only)
$50 \mu \mathrm{~V}$ rms,
Monotonicity
Guaranteed

## STABILITY

Differential Nonlinearity Tempco
$\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum (ADAM-824A),
$\pm 2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum (ADAM-825A)
Gain Tempco
$\pm 8 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum

## Offiset Tempco

$\pm 30 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typical, $\pm 80 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum
Clock Stability
$\pm 0.03 \% /{ }^{\circ} \mathrm{C}$
Power Supply Sensitivity
$\pm 0.001 \%$ per $1 \%$ change in supply voltage
Warm-up Time to Specified Accuracy
5 minutes
Recommended Recalibration Interval 6 months

## DYNAMIC PERFORMANCE

Maximum Throughput Rate ${ }^{4}$
20,000 measurement/seconds (ADAM-824A)
17,800 measurement/seconds (ADAM-825A)
S/H Aperture Delay
50 ns
S/H Aperture Uncertainty
1 ns

SIH Hold Mode Feedthrough Rejection
90 dB , measured with 20 V p-p
10 kHz sinewave input
S/H Droop Rate ${ }^{1}$
$0.2 \mu \mathrm{~V} / \mu \mathrm{s}$
S/H Dielectric Absorption Error ${ }^{5}$
$\pm 0.005 \%$ of input voltage change

## DIGITAL OUTPUTS

## General

Tri-state CMOS
Parallel Data
Positive true; unipolar binary, offset binary, or two's complement (see Table 1)

## End of Conversion (EOC)

Positive true

## DIGITAL INPUTS

## General

Standard TTL compatible, one unit load/line
S/H Mode Control
Logic $1=$ SAMPLE ( $6 \mu \mathrm{~s}$ minimum)
Logic $0=$ HOLD (conversion time minimum);
logic 1 to logic 0 transition time 10 ns maximum
AD Trigger
Negative-going edge; logic 1 to logic 0 transition 50 ns maximum
Low/High Byte Enable
Logic $0=$ enable
POWER REQUIREMENTS
$\pm 15 \mathrm{~V}, \pm 3 \%$
37 mA maximum
$-15 \mathrm{~V}, \pm 3 \%$
29 mA maximum
$+5 \mathrm{~V}, \pm 5 \%$
9 mA maximum
Power Dissipation
0.9W

ENVIRONMENTAL AND MECHANICAL
Operating Temperature
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
$5 \%$ to $95 \%$ noncondensing to $40^{\circ} \mathrm{C}$

## Shielding

Electrostatic (RFI) 6 sides;
Electrostatic (EMI) 5 sides
Package Size
$2.0^{\prime \prime} \times 4.0^{\prime \prime} \times 0.44$ "
$(50.8 \times 101.6 \times 11.18 \mathrm{~mm})$

## Shielding

Electrostatic (RFI) 6 sides;
Electrostatic (EMI) 5 sides
Package Size
$2.0^{\prime \prime} \times 4.0^{\prime \prime} \times 0.44^{\prime \prime}$
$(50.8 \times 101.6 \times 11.18 \mathrm{~mm}$ )

## Notes:

1. Doubles every $10^{\circ} \mathrm{C}$.
2. Traceable to NBS, calibrated on $\pm 10 \mathrm{~V}$ range.
3. Worst-case summation of $\mathrm{S} / \mathrm{H}$ and $\mathrm{A} / \mathrm{D}$ nonlinearity errors.
4. Includes $6 \mu \mathrm{~S}$ maximum for $\mathrm{S} / \mathrm{H}$ acquisition and $44 \mu \mathrm{~s}$ maximum for 824A A/D, $50 \mu \mathrm{~s}$ maximum for 825A A/D.
5. At maximum throughput rate. The error decreases as sampling time is decreased.

## Operation

The ADAM-824A and -825A interface directly to most commonly available input devices (multiplexers, amplifiers, etc.). The high impedance of the fast, fully buffered, unity gain S/H input amplifier minimizes source loading errors. Excellent hold-mode feedthrough performance is provided even at 10 kHz -the maximum information frequency of data that can be digitized at the module's 20 kHz sampling rate (single-channel application). For multichannel inputs, excellent feedthrough rejection is maintained by switching the multiplexer channels coincident with either edge of the S/H mode control.
Parallel data bits are driven by tri-state buffers and may be enabled in one or two bytes. (If the tri-state feature is not needed, normal binary outputs can be obtained by connecting the enable pins to ground.) To obtain two's complement, use B1 instead of B1 (the MSB). Maximum system throughput rate is attained by reading the output of an A/D conversion while the $S / H$ is acquiring the next sample.
To operate with a single control pulse, connect the $\mathrm{S} / \mathrm{H}$ mode control input to the A/D trigger, and observe the timing requirements for the S/H mode control (Figure 2).
Operating range is established by connecting the $\mathrm{S} / \mathrm{H}$ output to the appropriate $A / D$ input pins (see Table 1). These pins provide access to the S/H output (a low-impedance buffer amp) for arbitrary signal processing prior to A/D conversion. The S/H can be bypassed for applications requiring direct input to a low noise A/D converter.

## Performance Features

In most high accuracy applications the $\mathrm{S} / \mathrm{H}$, $A / D$, and related interfaces constitute the key
subsystem of the data conversion process. By using an ADAM-series module that has been "worst-case" designed, the system engineer avoids the problems that commonly occur when transforming a 14-bit breadboard into a finished product.
End-to-end performance is not subject to the surprises that usually result from $\mathrm{S} / \mathrm{H}$ output spikes, ground loops, timing problems, and so on. Offset is specified (and trimmed) as a single characteristic. The signal path from the $S / H$ to the A/D is very short, minimizing noise pick-up, cross-talk, etc.; trim potentiometers and the bypass capacitors that filter power supply noise are in the module, not on the PC board. The module is EMI/RFI shielded.
The integral $\mathrm{S} / \mathrm{H}$ is a precision circuit similar to Analogic's model MP260, so the total S/H error is very small. Due to the module's low power dissipation, errors induced by selfheating of the module are negligible. Internal temperature rise is only $12.5^{\circ} \mathrm{C}$ above external ambient, much less than in many other A/D converters.
The resulting performance is exceptional. Figure 3 shows a dynamic crossplot taken for the ADAM-824A with worst-case inputs (small signals). This crossplot allows visual detection of very small errors (approaching 1/8 LSB). The unit displays differential nonlinearity that is well within the specified $\pm 1 / 2$ LSB.


Figure 2. ADAM-824A/5A Timing.

| A/D Input Connections |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Full Scale Range | Connect IN 1 to | Connect IN 2 to | Connect IN 3 to | Input Impedance |
| 0 to +5V | $\begin{aligned} & \text { S/H ANA } \\ & \text { OUT } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { S/H ANA } \\ & \text { OUT } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { S/H ANA } \\ & \text { OUT } \\ & \hline \end{aligned}$ | $1.25 \mathrm{k} \Omega$ |
| 0 to +10V | ANA RTN | SIH ANA OUT | S:H ANA OUT | $2.5 \mathrm{k} \Omega$ |
| $-5 V$ to $+5 V$ | S/H ANA OUT | + 10V REF | ANA RTN | $2.5 \mathrm{k} \Omega$ |
| -10 V to +10 V | ANA RTN | + 10V REF | $\begin{aligned} & \text { S/H ANA } \\ & \text { OUT } \end{aligned}$ | $5.0 \mathrm{k} \Omega$ |
| Output Codes |  |  |  |  |
| AD/AM-824A (14 bits) |  | ADIAM-825A (15 bits) |  |  |
| Unipolar Binary |  |  |  |  |
| 11111111111111 | $=+9.9993$ | ** 11111111 | $11111111=$ | +9.99969 ${ }^{*}$ |
| $11111111111111=+9.99878 \mathrm{Vt}$ Off $111111111111111=+9.99939 \mathrm{~V} \dagger$ |  |  |  |  |
|  |  |  |  |  |
| 10000000000000 | $=0.0000$ | $V 10000000$ | 000 $000000=$ | 0.00000 V |
| Two's Complement |  |  |  |  |
| 01111111111111 <br> 00000000000000 | $\begin{aligned} & =+9.998 \\ & =0.0000 \end{aligned}$ | $\begin{array}{ll} \text { ivt } 0111111 \\ \text { iv } & 000000 \\ \text { iv } & 1000000 \end{array}$ | $11111111=$ 0000000 000 | $\begin{gathered} +9.99939 \mathrm{~V} \dagger \\ 0.00000 \mathrm{~V} \end{gathered}$ |
| 10000000000000 | =-10.0000 | 1000000 | $00000000=$ | $-10.00000 \mathrm{~V}$ |

*For +5 V FSR, divide voltage by two $\dagger$ For $\pm 5 \mathrm{~V}$ FSR, divide voltage by two
Table 1. Range Programming and Output Coding


The upper trace shows an input that ramps repetitively from -9.77 mV to +9.77 mV and back very slowly in relation to the module's 20 kHz sampling rate. The module output is used to drive a digital-to-analog converter, whose output is then shown on the lower trace. Thus each level on the staircase corresponds to a set of conversions made around a code center voltage, and the transitions show when the module toggles its LSB. This type of plot may be used to measure differential nonlinearity (the most significant A/D performance parameter for most applications) and to determine by inspection the existence of errors such as wide code. narrow code. missing code. non-monotonicity. etc. Because the input is dynamically changing. this type of test simulates actual operation very well.

MOUNTING DIMENSIONS \& PINOUTS


Notes

- Pin spacing on $2.54 \mathrm{~mm}\left(0.10^{\prime \prime}\right)$ centers. Double spacing between
pins 8 \& 9 as shown.
- ADAM-824A and -825A identical except B15 not used on

ADAM-824A.

- Modupac ${ }^{\text {M }}$ may be mounted in any orientation.


## CALIBRATION

Due to excellent long-term stability, these modules will rarely require re-calibration. They should, however, be readjusted when the selected FSR is changed. Offset should be zeroed prior to trimming the range.

## Offset Zeroing Procedure

1. Provide the $S / H$ analog input voltage shown in the accompanying table.
2. Adjust the Offset pot until the module output code corresponds to OV , with the LSB alternating equally between 0 and 1 .
Range Trimming Procedure (Gain Adjust)
3. Provide the $S / H$ analog input voltage shown in the accompanying table.
4. Adjust the Gain pot until the module output code is all 1 's, with the LSB alternating equally between 0 and 1 .

| Input Voltages For Calibration |  |  |  |  |
| :---: | :---: | ---: | ---: | ---: |
|  | ADAM-824A |  | ADAM-825A |  |
| Nominal FSR | Offset | Range | Offset | Range |
| 0 to +5 V | $153 \mu \mathrm{~V}$ | +4.99954 V | $76 \mu \mathrm{~V}$ | +4.99977 V |
| 0 to +10 V | $305 \mu \mathrm{~V}$ | +9.99909 V | $153 \mu \mathrm{~V}$ | +9.99954 V |
| -5 to +5 V | $305 \mu \mathrm{~V}$ | +4.99909 V | $153 \mu \mathrm{~V}$ | +4.99954 V |
| -10 to +10 V | $610 \mu \mathrm{~V}$ | +9.99817 V | $305 \mu \mathrm{~V}$ | +9.99909 V |

Figure 3. ADAM-824A/5A Crossplot Shows Highly Linear Performance.

ORDERING GUIDE
Simply Specify
$\square$ ADAM-824AADAM-825A


## ANALOGI.

## A/DIA/M-826

High Performance, 16-Bit, 500 kHz A/D Converter Family

## Description

The ADAM-826 is a 16 -bit, $1.5 \mu \mathrm{~s}$ analog-to-digital converter (ADC) available with or without input buffer or Sample-and-Hold Amplifier. In any of its three input configurations, the ADAM-826 represents the ultimate combination of conversion rate, accuracy, flexibility, package size, and power dissipation.
The ADAM-826 converters have been designed to operate effectively in applications which involve either a single input channel or multiplexed signal sources, system configurations which often place different demands on the functions of the analog-to-digital converter (ADC) and sample-and-hold amplifier (S/H). The ADAM-826 is therefore an appropriate choice for Automatic Test Equipment, waveform analyzers, NMR and other applications requiring conversion rates to 500 kHz .
In many applications, differential linearity is of primary importance. All configurations of the ADAM-826 provide $\pm 1 / 4$ LSB typical code differential linearity error and all are guaranteed to have NO MISSING CODES. Furthermore, the differential linearity is extremely stable over temperature, having a temperature coefficient of better than $\pm 1$ $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$.
Power dissipation is quite low, ranging from 2.75 watts (maximum) for the ADAM-826-3 to 3.5 watts (maximum) for the ADAM-826-1. All versions are available in two mechanical packages - the low profile Modupac ${ }^{\circledR}$ measuring 3 "x 5 " $x$ $0.44^{\prime \prime}$, or an optional package with (continued)


Figure 1. Deriving -6V from - 15V Power Supply.

## Features

- 16-bit Resolution
- Superb Differential Linearity $\pm 1 / 4$ LSB typical code
$\pm 3 / 4$ LSB maximum code
- Excellent Stability $\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. differential non-linearity tempco
- Flexible Configuration Capability

A/D Converter (ADAM-826-3) Highest Conversion Rate $1.5 \mu \mathrm{~S}$
Buffered ADC (ADAM-826-2) 100 M : Input Impedance $2.0 \mu \mathrm{~s}$ Conversion Rate
Sampling ADC (ADAM-826-1) Guaranteed end-to-end specifications
$2.3 \mu \mathrm{~s}$ Sampling/Conversion Rate
including S/H function

- Unipolar/Bipolar Input (Factory configured; specified on order)
- Low Power
3.25 watts maximum for the ADC alone
4.5 watts maximum for the ADC with S/H
- Tri-state Data Output

Bus Compatibility
Code Flexibility

- Two Packaging Options

Available
Pin solderable for lowest profile

- Modupac ${ }^{\circledR}$

Plug-in socket mounted for ease of removal

## Applications

- Nuclear Magnetic Resonance
- Automatic Test Equipment
- Analytical Instrumentation
- Data Acquisition Systems
- Digital Audio/Communications
- Spectroscopy

■ Signal Analysis

## Description (cont.)

connectors and mating pc board-mounted sockets (included) which allow the module to be easily removed from the board. (Available October, 1985).
Often it is impractical for users to adequately test 16 -bit high speed ADCs, except by measuring overall performance in the completed system. Under these conditions, tracing an anomaly back to its source may prove exceedingly difficult. Therefore, Analogic recognizes its responsibility to provide units fully tested to meet guaranteed maximum and minimum specifications. Every ADAM-826 is subjected to extensive, automated testing and temperature cycling, followed by a final re-test, and is delivered to the customer with documented test data.
The ADAM-826 is offered in three configurations each of which is described more fully on the following pages:

The ADAM-826-1 - combines the ADAM-826 A/D with an extremely fast and accurate Sample-and-Hold Amplifier (S/H) (better than $\pm 0.0015 \%$ in less than 800 ns for a full 20 V step) to produce a complete acquisition and conversion in $2.3 \mu \mathrm{~s}$.
The ADAM-826-2 - provides a $100 \mathrm{M} \Omega$ input impedance buffer amplifier with full scale settling in less than 400 ns to yield an overall conversion rate of 500 kHz .
The ADAM-826-3 - offers the designer the opportunity to take maximum advantage of the A/D's $1.5 \mu \mathrm{~s}$ conversion time by eliminating both the input buffer and S/H where the application or system architecture will allow.
We invite systems designers to take advantage of Analogic's considerable experience in implementing systems accurate to 16 bits and beyond. The suggestions given in the sections on PC Board Layout, Power Supplies and Timing in this Data Sheet will help eliminate a number of potential problem areas. If the need arises, we will be happy to provide personal assistance; please call on us directly.

## USING THE ADAM-826 <br> P.C. Board Layout

The analog input lead lengths should be as short as possible, preferably surrounded on both sides by an analog ground plane. The module has been carefully laid out internally to separate the analog input from the digital output and control lines. This practice should be extended to the pc board as
much as possible. Figure 2 depicts a typical pc board layout illustrating the recommended routing, etch width and length, and grounding scheme.
Analog and digital ground should be totally separated in the system, except for the connection internal to the ADAM-826. If multiple ground connections in the system cannot be avoided, then the use of one, massive ground plane on the pc board is strongly recommended, with all ground connections made to this groundplane. This precaution will minimize both the effects of ground loops and the possibility of digital noise coupling into the analog circuitry.

## Mechanical Packaging

The flexibility of the performance of the ADAM-826 is extended to its packaging options as well. The ADAM-826 is available in our standard Modupac, measuring 3" x 5", which when soldered into the pc board, will provide the lowest profile. Where board spacing is not a problem, and/or where ease of removal for recalibration is required, all versions of the ADAM-826 are offered with edge connectors and mating sockets (included) (available October, 1985). Both packaging options are illustrated in the Figures "MECHANICAL \& PINOUT" for each version of the ADAM-826.

## Power Supplies

In order to take advantage of the full 16-bit accuracy of the ADAM-826, it is recommended that well-regulated linear power supplies be used for the $\pm 15 \mathrm{~V}$ required by the ADAM-826; these supplies must have no more than 5 mV p-p ripple. A switching supply must not be used for the $\pm 15 \mathrm{~V}$ supplies. A linear +5 V supply is recommended, although a switching type can be used since the ADAM-826 is well bypassed internally.
The required -6 V may pose a problem for some designers whose systems do not have a -6 V supply readily available. The -6 V can be generated by using the circuit shown in Figure 1. The three terminal regulator can be any type of negative voltage regulator that can provide the 125 mA required by the ADAM-826. When this circuit is used, it is imperative that the ANALOG and DIGITAL RETURNS be tied together by a massive ground connection (plane) at the module.

## Timing

Figures 5, 8, and 10 depict the typical timing of control signals and data output for each
version of the ADAM-826. All versions of the converter are triggered on the falling edge of the Trigger pulse applied to the TRIGGER INPUT pin. The minimum and recommended pulse width is 50 ns , with a maximum width of no more than 200 ns.
The TRANSFER (XFER) line is normally high. Approximately 225 ns prior to the time when valid data is available at the converter's outputs, XFER goes low, and remains so for 175 ns . At the end of this time, XFER again goes high. This rising edge loads the data for the just completed conversion into the tri-state output latches.

After a delay of 50 ns from this rising edge, the data is valid. Therefore the actual conversion is completed when XFER goes low.

## Data Outputs

The 16-bit data available in the tri-state output latches at the end of a conversion can be formatted in any of three ways. For a OV to +10 V FS input signal, the output data is unipolar binary; for bipolar $\pm 10 \mathrm{~V}$ FS inputs, using B 1 (MSB) as the sign bit provides offset binary data; $\overline{\mathrm{B} 1}$ (MSB) provides two's complement data.

| Unipolar Binary MSB |  |
| :---: | :---: |
| $\begin{array}{lllllllllllllllll}1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1\end{array}$ | +9.99985V |
| 0000000000000000 | 0.00000 V |
| B1,B2, . . . . . . . . . . . B16 | Pin Label |
| Offset Binary |  |
| MSB LSB |  |
| $\begin{array}{llllllllllllllllll}1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1\end{array}$ | +9.99970V |
| $1000000000000000=$ | 0.0000 V |
| 0000000000000000 | -10.0000V |
| B1,B2, . . . . . . . . . . . B16 | Pin Label |
| 2's Complement |  |
| MSB LSB |  |
| $\begin{array}{llllllllllllllllll}0 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & = \\ \end{array}$ | +9.99970V |
| $0000000000000000=$ | 0.0000 V |
| $100000000000000=$ | -10.0000V |
| B1,B2, . . . . . . . . . . . B16 = | Pin Label |

Table 1. Output Coding for ADAM-826 Family.


Figure 2. Typical PC Board Layout.

If the -6 V power supply voltage is derived from the -15 V supply on the pc board, then an additional heavy ground connection between power supply returns back at the supplies themselves is suggested. This will provide a "path of least resistance" for the -6 V return current back to the -15 V supply (see "Correct Method" in Figure 3). If this path is not provided, the IR drop between the DIGITAL and ANALOG RETURN's can become significant relative to 1 LSB at the 16-bit level (see "Incorrect Method" in Figure 3). If the -6 V is NOT derived in this manner, this connection is not necessary.
LC filtering on the power supply inputs should be used right at the ADAM-826 module. A $100 \mu \mathrm{H}$ inductor and a $15 \mu \mathrm{~F}$ capacitor are recommended. If the -6 V regulator is used, then an RC low-pass filter of $22 \Omega$ (1 watt) and


Figure 3. Ground Return Connections.
$6.8 \mu \mathrm{~F}(20 \mathrm{~V})$ at the input of the regulator is requred. The LC filter above should be used at the -6 V input to the ADAM-826.

## Grounding

The pc board that the ADAM-826 is mounted on should make use of a single, massive ground plane for both analog and digital ground. This ground plane should cover as much of at least one side, and preferably both sides of the pc board as possible. If an extensive ground plane can be utilized on both sides of the board, then many feedthroughs should be used to connect the two sides together. You can't use to many feedthroughs (except to endanger the mechanical integrity of the board).
Separate ground return lines back to the +5 V and $\pm 15 \mathrm{~V}$ power supplies is very important, as is a separate analog input return back to the signal source. All of these grounds are connected to the ground plane at the pc board.
If the ADAM-826 is mounted on a pc board plugged into a card cage, use any free pins to carry ground to the pc board ground plane. Extend the ground plane concept as much as possible in the design.

## CALIBRATION SUGGESTIONS

Recalibration of the ADAM-826 for absolute accuracy (gain \& offset) is normally required every six months. However, the application will determine how frequently recalibration needs to be performed. Please remember that the very high-speed ADAM-826 performance specifications approach laboratory standard parameters. In applications where temperature fluctuates more than several degrees Celsius and power is cycled on and off frequently, recalibration may be performed more frequently. Where offset and/or gain calibration are performed digitally, hardware calibration may not need to be performed at all. In any case, recalibration of the offset and range potentiometers should be performed as described below in accordance with the system performance needs.

## Offset Calibration

Apply the input voltage specified in the Table for the input full scale range in use. Adjust the OFFSET potentiometer so that the LSB of the appropriate output code alternates equally between " 0 " and " 1 ". The OFFSET pot should be readjusted whenever the selected full scale range is changed.

## Range Calibration

Offset should be calibrated before adjusting range. Apply the input voltage specified in the Table for the input full scale range in use. Adjust the RANGE potentiometer such that the LSB of the appropriate output code alternates equally between " 0 " and " 1 ".

|  | Input Voltage |  |
| :---: | :---: | :---: |
| Full Scale Range | Offset | Range |
| 0 V to +10 V | +76.3 V | +9.99977 V |
| -10 V to +10 V | +152.6 V | +9.99955 V |

## Your Assurance of Quality

The ADAM-826 family represents a major design achievement as reflected in these specifications. In order to guarantee that all of the design capabilities are present in the delivered product, every step of the manufacturing cycle must be meticulously controlled. Critical components are burned-in and screened to exacting standards prior to assembly. In-process inspection and testing is conducted on every unit at several stages of construction, and is followed by a poweredup temperature cycling of the completed unit.
An exhaustive final test of all guaranteed specifications is then conducted on every unit at ambient and at the extremes of the operating temperature range using specially designed automatic test equipment. As an example, Differential Linearity is measured to better than 0.1 LSB for every single code over the entire transfer curve under both sequential dynamic and psudo-random dynamic conditions, in each case making over $65,000,000$ conversions.
A histogram is printed out showing the distribution of errors as part of the Test Report, a copy of which is shipped with the unit (see Figure 3.) This Test Report, along with your knowledge of the care exercised in its construction, is your assurance that the ADAM-826 delivered to you is the finest converter of its type available.


Figure 4. Sample ADAM-826 Final Test Report.

## ORDERING GUIDE




## ANALDG․․

## ADAM-826-1

16-Bit, $2.3 \mu \mathrm{~s}$ AID<br>Converter with Integral Sample-and-Hold

## Description

Superior performance and relative ease of system implementation make the ADAM-826-1 the ideal solution for those applications requiring a sample-and-hold amplifier (S/H) directly at the input to the AID Converter. The unit can be ordered with either a $\pm 10 \mathrm{~V}$ bipolar or $0-10 \mathrm{~V}$ unipolar input and provides 16 -bit two's complement or offset binary output data in $2.3 \mu \mathrm{~s}$, including acquisition time. The differential linearity error of the ADAM-826-1 is typically less than $\pm 1 / 4$ LSB with a worst case maximum of less than $\pm 3 / 4$ LSB. The internal S/H represents a significant technical achievement in its own right, with an acquisition time of less than 800 ns for full scale input step change extremely fast for an amplifier whose linearity is better than $\pm 0.001 \%$ !
The selection of the ADAM-826-1, with its integral $\mathrm{S} / \mathrm{H}$, benefits overall system performance in at least two ways. First, the $\mathrm{S} / \mathrm{H}$ has been designed specifically to match the requirements of the A/D Converter. For example, great care has been exercised in the internal timing to avoid overlap of critical functions which might impair system performance.


Furthermore, S/H performance criteria such as acquisition time, hold mode settling, droop rate, and the like, have been optimized for the AID Converter, resulting in exceptional combined overall performance as reflected in its specifications. The second benefit to the designer is that by selecting the ADAM-826-1, he can sidestep the sometimes costly iterations of printed circuit board layout often necessary to avoid degradation of 16 -bit system performance due to ground loops, signal coupling, and digital noise introduced when separate S/H and A/D Converters are interconnected. To our knowledge at the time of writing, separately or together, there are no better commercially available 16-bit, 500 kHz Sample-and-Holds or Analog-to-Digital Converters, than those contained in the ADAM-826.

## Using the ADAM-826-1

In most cases, the ADAM-826-1 will be connected as shown in the Block Diagram of Figure 4, in which case, a single trigger/start convert command will cause the $\mathrm{S} / \mathrm{H}$ to go into the hold mode. Under control of the internal timing logic, the AID Converter will then begin the conversion while hold mode settling takes place. At the completion of the conversion process, the S/H will automatically be returned to the sample mode to await the next trigger/start convert command. Please refer to the Timing Diagram of Figure 5 and to the section on Timing. It is important to note that the connection to the TRANSFER line must be kept as short as possible, or alternatively, buffered prior to connection to external circuitry.
If external system considerations so dictate, control of the $\mathrm{S} / \mathrm{H}$ and $A / D$ Converter may be accomplished independently through external logic provided by the user. This is achieved by disconnecting the S/H CONTROL OUT pin from the S/H CONTROL IN pin, as shown in the Block

Figure 4. ADAM-826-1 Block Diagram

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ and nominal power supply voltages unless otherwise noted)

## COMBINED S/H AND A/D CONVERTER PERFORMANCE (ADAM-826-1) (See Note 1.)

Note: These specifications represent the total error of all sources, including both the S/H and A/D Converter errors. As tabulated in subsequent sections, the specifications for the S/H and A/D by themselves are even better.

## INPUT

Input Voltage Range
0 V to +10 V unipolar (See Note 2.) -10 V to +10 V bipolar

## Maximum Input Without Damage

$\pm$ Supply
Input Impedance
$100 \mathrm{M} \Omega / / 10 \mathrm{pF}$ typical
Input Bias Current
$\pm 100 \mathrm{pA}$ maximum (doubles every $10^{\circ} \mathrm{C}$ )
Initial Offset Voltage
$\pm 5 \mathrm{mV}$ maximum, adjustable to zero

## THROUGHPUT

## Conversion Time

$2.3 \mu \mathrm{~s}$, maximum
Maximum Conversion Rate
435,000 samples per second

## ACCURACY

## Resolution

16 bits
Differential Non-Linearity
$\pm 1 / 4$ LSB typical, $\pm 3 / 4$ LSB maximum
Monotonicity
Guaranteed; no missing codes
Quantization Error
$\pm 1 / 2$ LSB
Relative Accuracy
$\pm 0.0015 \%$ FSR typical (See Note 3.) $\pm 0.003 \%$ FSR maximum (See Note 3.)
Absolute Accuracy (Includes Reference
Accuracy)
$\pm 0.005 \%$ FSR maximum (See Note 4.) The Internal Reference (and offset) may be adjusted against a standard source traceable to the Na tional Bureau of Standards for even better Absolute Accuracy

## Noise

Unipolar: $60 \mu \mathrm{~V}$ rms maximum, Bipolar: $80 \mu \mathrm{~V}$ rms maximum

## STABILITY

Differential Non-Linearity Tempco
$\pm 1 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ maximum
Total Offset Tempco (including Pedestal)
$\pm 5 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ maximum
Gain Tempco
$\pm 5 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ maximum

Warmup Time
10 minutes to specified accuracy (See Note 5.)
Power Supply Sensitivity Gain
$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Offset
$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Recommended Recalibration Interval
6 months
DIGITAL INPUTSIOUTPUTS INPUTS

## Trigger

Negative edge triggered; 1 LSTTL load; 50 ns pulse width minimum, 200 ns maximum; (See Note 9.) CMOS and 74LSTTL Compatible
S/H Mode Control
Logic 1 is HOLD mode, logic 0 is SAMPLE,
Logic 1 must be +5 V , drive with CMOS gate or
TTL gate with $<470 \Omega$ pullup
Tri-state Control
HI Byte Enable
Logic 1 produces high impedance
LO Byte Enable
Logic 1 produces high impedance, CMOS and 74LSTTL Compatible

## OUTPUTS

Data
16 bits data plus $\overline{B 1}$; Offset Binary or two's complement; See Coding Table; Tri-state CMOS latch (Silicon gate)
Data Output Loading Transfer (XFER)
1 LSTTL load, positive edge loads output data latches; data ready after 50 ns delay
Transfer (XFER) Loading
1 LSTTL Load
POWER REQUIREMENTS
$+15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
85 mA , typical
$-15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
95 mA , typical
$+5 \mathrm{~V} \pm 0.25 \mathrm{~V}$
65 mA , typical
$-6 \mathrm{~V} \pm 0.25 \mathrm{~V}$
150 mA , typical (See Note 8.)
Note: At power on, a 200 mA maximum current surge on the $\pm 15 \mathrm{~V}$ supply lines will occur, and will last for no more than 5 seconds. This surge is caused by the Reference heater circuit when starting "cold".
Note: The $\pm 15 \mathrm{~V}$ power supplies must have no more than 5 mV p-p ripple.

```
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
\(0^{\circ} \mathrm{C}\) to \(+60^{\circ} \mathrm{C}\)
Storage Temperature Range
\(-25^{\circ} \mathrm{C}\) to \(+70^{\circ} \mathrm{C}\)
```


## Relative Humidity

0 to $85 \%$, non condensing
Dimensions and Shielding
Modupac
$3.00^{\prime \prime} \times 5.00^{\prime \prime} \times 0.44^{\prime \prime}$
( $76.2 \times 127.0 \times 11.17 \mathrm{~mm}$ )
RFI 6 sides, EMI 5 sides

## Socket Mount Option

$3.45^{\prime \prime} \times 5.00^{\prime \prime} \times 0.55^{\prime \prime}(87.63 \times 127.00 \times 13.97 \mathrm{~mm})$ RFI 6 sides, EMI 6 sides

## SAMPLE-AND.HOLD AMPLIFIER ONLY INPUT

Input Voltage Range
$\pm 10 \mathrm{~V}$, (See Note 2.)
Maximum Input Without Damage
$\pm$ Supply
Input Impedance
$100 \mathrm{M} \Omega / / 10 \mathrm{pF}$ typical
Input Bias Current
$\pm 100 \mathrm{pA}$ maximum (doubles every $10^{\circ} \mathrm{C}$ )
Initial Offset Voltage
$\pm 5 \mathrm{mV}$ maximum, adjustable to zero

## SAMPLE MODE

## Gain

$+1$
Small Signal Bandwidth
5 MHz typical

## Full Power Bandwidth

250 kHz

## Acquisition Time

800 ns maximum to $0.0015 \%$ for 20 V full scale step. Acquisition time for smaller steps will be
less.
Non-Linearity
$\pm 0.001 \%$ ( 20 V input)

## Noise

$40 \mu \mathrm{~V}$ rms typ., 50 V rms max. Unipolar or Bipolar
SAMPLE-TO-HOLD SWITCHING

## Aperture Uncertainty

150 ps typical
Aperture Time
15 ns typical
Switching Transient Settling Time
150 ns maximum (See Note 6.) to $\pm 0.0015 \%$ FSR

## HOLD MODE

Output Drive Capability $1 \mathrm{k} \Omega / / 50 \mathrm{pF}$ Short-circuit protected

## Droop Rate

$5 \mu \mathrm{~V} / \mu \mathrm{s}$ maximum (See Note 7.)
Dielectric Absorption
$\pm 0.001 \%$ of voltage change, typical (800 ns Sample, $1.5 \mu \mathrm{~s}$ Hold)

## Pedestal Non-Linearity

$\pm 0.0015 \%$ FSR maximum

## A/D CONVERTER ONLY

## Input Voltage

0 V to +10 V unipolar; -10 V to +10 V bipolar, Factory configured

## Input Impedance

$1.4 \mathrm{k} \Omega$ unipolar, $2.8 \mathrm{k} \Omega$ bipolar

## ACCURACY

## Resolution

16 bits
Differential Non-Linearity $\pm 1 / 4$ LSB typical, $\pm 3 / 4$ LSB maximum
Monotonicity
Guaranteed; no missing codes
Quantization Error
$\pm 1 / 2$ LSB
Relative Accuracy
$\pm 0.0015 \%$ FSR maximum

## Absolute Accuracy

$\pm 0.003 \%$ FSR maximum
Noise (Including Ref.)
Unipolar: $30 \mu \mathrm{~V} \mathrm{rms}$, maximum, Bipolar: $60 \mu \mathrm{~V}$ rms, maximum

## STABILITY

Differential Non-Linearity
$\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum

## Tempco

$\pm 5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Gain Tempco
Unipolar: $\pm 1.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum,
Bipolar: $\pm 4.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Warmup Time
10 minutes to specified accuracy
Recommended Recalibration Interval 6 months

## THROUGHPUT

Conversion Time
$1.5 \mu \mathrm{~s}$ maximum
Note 1: Specifications apply when S/H control is internally generated. See text and Figure 4.
Note 2: Input voltage range is determined by the A/D Converter. The S/H is a unity gain device.
Note 3: Specified as the maximum deviation from a best fit line. Maximum deviation from straight line drawn through full scale end points is $0.004 \%$.
Note 4: Absolute Accuracy is the worst case summation of all error sources for both the Analog-to-Digital Converter and the Sample-and-Hold Amplifier.
Note 5: Time required for internal reference heater to stabilize.
Note 6: Specified for completeness only - this settling time is overlapped by the A/D conversion time and does not affect throughput.
Note 7: Specified for completeness only - droop rate does not affect the accuracy of the $1.5 \mu \mathrm{~s}$ conversion process.
Note 8: -6 V may be readily derived from the -15 V power supply using a 7906-type three-terminal regulator. See Figure 1.
Note 9: The 50 ns pulse width is recommended where possible.

## Using the ADAM-826-1 (cont.)

Diagram of Figure 4, and supplying an external S/H mode control signal to the S/H CONTROL IN pin. This signal should be provided by a HCMOS driver so that the logic " 1 " (HOLD mode) is a solid +5 V .
In some system architectures, it may be desirable to introduce a signal, such as a digitally controlled overall system offset correction, between the S/H output and the A/D Converter input. A provision for this is made in the ADAM-826-1 allowing the user to add appropriate circuitry between the S/H OUT and A/D IN pins. If this offset correction signal is changed when the ADAM-826-1 is in the sample mode, then the timing as shown in Figure 4 will not be affected, provided the D/A converter supplying the correction voltage is completely settled prior to the next trigger/start convert command. The connection to the S/H OUT-A/D IN pins from the D/A must be as short as possible; refer to the sections on pc board layout, and the text on the ADAM-826-3.


Figure 5. Typical Timing - ADAM-826-1


Figure 6. ADAM-826-1 Mechanical \& Pinout


## analogic.

ADAM-826-2
16-Bit, $2.0 \mu \mathrm{~s}$ AID Converter with Input Buffer Amplifier

## Description

In systems that simultaneously sample multiple channels prior to multiplexing the analog signal, a sample-and-hold (S/H) directly at the input to the AID Converter is not required. In other multi-channel systems, the analog inputs will be essentially low frequency and stable during conversion. In either case, the high conversion rate of the ADAM-826-2 may be desirable in order to minimize the time required to input the data and clear the input channel to the computer. The unit includes a high input impedance ( $100 \mathrm{M} \Omega$ ) buffer with settling time of less than 400 ns resulting in an overall conversion time of $2.0 \mu \mathrm{~s}$. Input full scale ranges of $\pm 10 \mathrm{~V}$ bipolar or 0 V to +10 V unipolar can be accommodated. To make the ADAM-826-2 even more flexible, the output of the buffer amplifier and the input to the A/D Converter are brought out to separate pins. Normally, these two pins would be connected together as shown in the Block Diagram in Figure 7; however, this connection may be broken, or signals may be injected at this point. This should be done only when absolutely required by external system considerations as the output of the
buffer amplifier is not short-circuit protected. Refer also to the sections on the ADAM-826-3 and PC BOARD LAYOUT.
In order to determine whether an error will occur due to the changing signal without using a $S / H$, the system designer need only consider the first $1.5 \mu \mathrm{~s}$ of the conversion process. Any change in input signal thereafter will not affect the result as this remaining time is used to complete the conversion and to transfer the resulting data word to the internal output data register. This timing relationship is depicted in the Typical Timing Diagram of Figure 8.


Figure 8. Typical Timing -ADAM-826-2.


Figure 7. Block Diagram - ADAM-826-2.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## COMBINED BUFFER AMPLIFIER AND AID PERFORMANCE

Note: These specifications represent the total error of all sources including both the Buffer Amplifier and A/D converter errors. As tabulated in subsequent sections, the specifications for the Buffer Amplifier and A/D by themselves are even better.

```
INPUT
Input Voltage Range
OV to +10 V Unipolar
(See Note 1.)
\(\pm 10 \mathrm{~V}\) Bipolar
Factory configured
Maximum Input Without Damage
\(\pm\) Supply
Input Impedance
\(100 \mathrm{M} \Omega / / 10 \mathrm{pF}\) typical
Input Bias Current
\(\pm 100\) pA maximum
```


## THROUGHPUT

## Conversion Time

$2.0 \mu \mathrm{~s}$ maximum
Conversion Rate
500,000 samples per second

## ACCURACY

## Resolution

16-bits
Differential Non-linearity
$\pm 1 / 4$ LSB typical,
$\pm 3 / 4$ LSB maximum
Monotonicity
Guaranteed; no missing codes
Quantization Error
$\pm 1 / 2$ LSB

## Relative Accuracy

$\pm 0.0015 \%$ FSR typical (See Note 2.)
$\pm 0.0025 \%$ FSR maximum (See Note 2.)
Absolute Accuracy (Includes Reference Accuracy)
$\pm 0.004 \%$ FSR maximum. The Internal Reference (and offset) may be adjusted against a standard source traceable to the National Bureau of Standards for even better Absolute Accuracy

## Noise

Unipolar: $45 \mu \mathrm{~V}$ rms maximum Bipolar: $70 \mu \mathrm{~V}$ rms maximum

## STABILITY

Differential Non-linearity Tempco
$\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum

## Offset Tempco

Unipolar: $\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Bipolar: $\pm 5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum

## Gain Tempco

## $\pm 5 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ maximum

## Power Supply Sensitivity Gain

$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Offset
$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Warmup Time to Specified Accuracy 10 minutes (See Note 3.)

## Recommended Recalibration Interval

 6 months
## DIGITAL INPUTS/OUTPUTS INPUTS

## Trigger

Negative edge triggered; 1 LSTTL load; 50 ns pulse width minimum, 200 ns maximum; CMOS and 74 LSTTL Compatible (See Note 5.)

## Tri-state Control

HI Byte Enable
Logic 1 produces high impedance

## LO Byte Enable

Logic 1 produces high impedance CMOS and 74 LSTTL Compatible

## OUTPUTS

## Data

16 bits data plus B1; Offset Binary or two's complement; See Coding Table; Tri-state CMOS latch (Silicon gate)
Data Output Loading
1 LSTTL load
Transfer (XFER)
Positive edge loads output data latches; data ready after 50 ns delay
Transfer (XFER) Loading
1 LSTTL Load
POWER REQUIREMENTS
$+15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
55 mA , typical
$-15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
80 mA , typical
$+5 \mathrm{~V} \pm 0.25 \mathrm{~V}$
65 mA , typical
$-6 \mathrm{~V} \pm 0.25 \mathrm{~V}$
150 mA , typical (See Note 4.)

## Note:

At power on, a 200 mA maximum current surge on the $\pm 15 \mathrm{~V}$ supply lines will occur, and will last for no more than 5 seconds. This surge is caused by the Reference heater circuit when starting "cold".

## Note:

The $\pm 15 \mathrm{~V}$ power supplies must have no more than 5 mV p-p ripple.

## ENVIRONMENTAL AND MECHANICAL

Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non condensing
Dimensions and Shielding Modupac ${ }^{\circledR}$
$3.00^{\prime \prime} \times 5.00^{\prime \prime} \times 0.44^{\prime \prime}$
$(76.2 \times 127.0 \times 11.17 \mathrm{~mm})$
RFI 6 sides, EMI 5 sides
Socket Mount Option
3.45 " x 5.00 " $\times 0.55$ "
( $87.63 \times 127.00 \times 13.97 \mathrm{~mm}$ )
RFI 6 sides, EMI 6 sides

```
INPUT BUFFER AMPLIFIER ONLY INPUT
Input Voltage Range
0 V to +10 V Unipolar
\(\pm 10 \mathrm{~V}\) Bipolar
Factory configured
Maximum Input Without Damage
\(\pm\) Supply
Input Impedance
\(100 \mathrm{M} \Omega / / 10 \mathrm{pF}\) typical
Input Bias Current
\(\pm 100\) pA maximum
```

AC PERFORMANCE
Small Signal Bandwidth
5 MHz typical
Full Power Bandwidth
250 kHz
Non-linearity
$\pm 0.001 \%$ FSR maximum
Buffer Settling Time
400 ns to $\pm 0.0015 \%$ of Full Scale step
Noise
$25 \mu \mathrm{~V}$ rms typical, $35 \mu \mathrm{~V}$ rms maximum
Output Drive Capability
$1 \mathrm{k} \Omega / / 50 \mathrm{pF}$; This output is NOT short circuit protected

## AID CONVERTER ONLY

ANALOG INPUT
Input Voltage
0 V to +10 V unipolar
-10 V to +10 V bipolar
Factory configured

## Input Impedance

$1.4 \mathrm{k} \Omega$ unipolar
$2.8 \mathrm{k} \Omega$ bipolar

## ACCURACY

## Resolution

16 bits
Differential Non-linearity
$\pm 1 / 4$ LSB typical,
$\pm 3 / 4$ LSB maximum
Monotonicity
Guaranteed; no missing codes
Quantization Error
$\pm 1 / 2$ LSB
Relative Accuracy $\pm 0.0015 \%$ FSR maximum

## Absolute Accuracy

 $\pm 0.003 \%$ FSR maximumNoise (Including Ref.)
Unipolar: $30 \mu \mathrm{~V}$ rms, maximum
Bipolar: $60 \mu \mathrm{~V}$ rms, maximum

## STABILITY

Differential Non-Linearity Tempco $\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum

## Offset Tempco

Unipolar: $\pm 1.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Bipolar: $\pm 4.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Gain Tempco
$\pm 5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Warmup Time
10 minutes to specified accuracy
Recommended Recalibration Interval 6 months

THROUGHPUT
Conversion Time
$1.5 \mu \mathrm{~s}$ maximum

Note 1: Input Voltage range is determined by the A/D Converter. The Buffer Amplifier is a unity gain device.
Note 2: Specified as the maximum deviation from a best fit line. Maximum deviation from a straight line drawn through the full scale end points is $\pm 0.0035 \%$. Note 3: Time required for internal reference heater to stabilize.
Note 4: -6 V may be readily derived from the -15 V
power supply using a 7906 -type three-terminal regulator. See Figure 5.
Note 5: The 50 ns pulse width is recommended where possible.


Figure 9. ADAM-826-2 Mechanical \& Pinout.

## Description

The $1.5 \mu \mathrm{~s}$ A/D Converter itself is available for those applications where the signal has already been conditioned and only the A/D conversion function is required. In this configuration, as depicted in the Block Diagram of Figure 10, the duplication of circuitry and errors associated with an internal buffer amplifier or $\mathrm{S} / \mathrm{H}$ are eliminated.
To preserve the full performance capability inherent in the A/D, whether configured for $\pm 10 \mathrm{~V}$ bipolar or 0 V to +10 V unipolar signals, care must be exercised in its implementation in the system. The input impedance of the unbuffered A/D is $1.4 \mathrm{k} \Omega$ unipolar or $2.8 \mathrm{k} \Omega$ bipolar. The pc etch that connects the A/D input to the signal source(s) must be carefully routed to avoid other etches carrying digital signals to prevent coupling of digital noise into the analog input. In addition, the physical dimensions (length and width) of this etch must be controlled to reduce the effects of temperature on the overall gain specification of the ADAM-826-3. For example, for 2 ounce copper-clad pc board, and a etch width of 0.025 ", the etch will have a dc resistance of $0.010 \Omega$ per inch. If we assume a six
inch etch length, the total dc resistance of this etch is $0.060 \Omega$. This etch, which forms a resistive divider with the A/D Converter input impedance, has a temperature coefficient of $0.39 \% /{ }^{\circ} \mathrm{C}$. For a temperature rise of $35^{\circ} \mathrm{C}$ from $25^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$, the etch resistance will change by a sufficient amount to cause the gain to change by 0.4 LSB at the 16 -bit level. This example illustrates the effects on conversion accuracy of typical pc etch dimensions found in many data acquisition systems. Wherever possible pc etch lengths should be kept as short as absolutely necessary to reduce these errors.

The maximum frequency of the signal at the input to the ADAM-826-3 can be determined by the timing relationships as shown in the Typical Timing Diagram of Figure 11. As shown, the actual conversion requires only $1.5 \mu$ s while the last 225 ns is used to complete the internal conversion process and to transfer the resulting data word into the internal data register. As long as the signal does not change during the first $1.5 \mu \mathrm{~s}$ of the conversion cycle, no errors will be introduced from this source.


Figure 10. Block Diagram - ADAM-826-3.

## SPECIFICATIONS

(All Specifications are guaranteed at $25^{\circ} \mathrm{C}$ and nominal power supply voltages unless otherwise noted)

## ANALOG INPUT <br> Input Voltage

OV to + 10V Unipolar
-10 V to +10 V Bipolar
Factory configured
Input Impedance
$1.4 \mathrm{k} \Omega$ Unipolar
2.8 k $\Omega$ Bipolar

## ACCURACY

Resolution
16-bits
Differential Non-linearity
$\pm 1 / 4$ LSB typical,
$\pm 3 / 4$ LSB maximum
Monotonicity
Guaranteed; no missing codes
Quantization Error
$\pm 1 / 2$ LSB
Relative Accuracy
$\pm 0.0015 \%$ FSR maximum
Absolute Accuracy
$\pm 0.003 \%$ FSR maximum
Noise (Including Ref.)
Unipolar: $30 \mu \mathrm{~V}$ rms, maximum
Bipolar: $60, \mu \mathrm{~V}$ rms, maximum

## STABILITY

Differential Non-linearity Tempco
$\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum

## Offset Tempco

Unipolar: $\pm 1.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Bipolar: $\pm 4.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Gain Tempco
$\pm 5 \mathrm{ppm}$ FSR/ ${ }^{\circ} \mathrm{C}$ maximum
Power Supply Sensitivity Gain
$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Offset
$\pm 10 \mathrm{ppm} / \Delta 1 \%$ each supply, maximum
Warmup Time
10 minutes to specified accuracy
Recommended Recalibration Interval
6 months
THROUGHPUT
Conversion Time
$1.5 \mu \mathrm{~s}$ maximum

## DIGITAL INPUTSIOUTPUTS

INPUTS
Please refer to ADAM-826-2

## Trigger

Negative edge triggered; 1 LSTTL load; 50 ns pulse width minimum, 200 ns maximum; CMOS
and 74 LSTTL Compatible

## Tri-state Control <br> HI Byte Enable <br> Logic 1 produces high impedance <br> LO Byte Enable <br> Logic 1 produces high impedance CMOS and 74LSTTL Compatible

## OUTPUTS

## Data

16 bits data plus $\overline{\mathrm{B1}}$; Offset Binary or two's complement; See Coding Table; Tri-state CMOS latch (Silicon gate)
Data Output Loading
1 LSTTL load
Transfer (XFER)
Positive edge loads output data latches; data ready after 50 ns delay
Transfer (XFER) Loading
1 LSTTL Load

## POWER REQUIREMENTS

$+15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
40 mA , typical
$-15 \mathrm{~V} \pm 0.5 \mathrm{~V}$
65 mA , typical
$+5 \mathrm{~V} \pm 0.25 \mathrm{~V}$
65 mA, typical
$-6 \mathrm{~V} \pm 0.25 \mathrm{~V}$
150 mA , typical (See Note 2.)

## Note:

At power on, a 200 mA maximum current surge on the $\pm 15 \mathrm{~V}$ supply lines will occur, and will last for no more than 5 seconds. This surge is caused by the Reference heater circuit when starting "cold".
Note:
The $\pm 15 \mathrm{~V}$ power supplies must have no more than 5 mV p-p ripple.

ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non condensing
Dimensions and Shielding Modupac ${ }^{\circledR}$
$3.00^{\prime \prime} \times 5.00^{\prime \prime} \times 0.44$ "
$(76.2 \times 127.0 \times 11.17 \mathrm{~mm}$ )
RFI 6 sides, EMI 5 sides
Socket Mount Option
3.45 " $\times 5.00^{\prime \prime} \times 0.55$ "
( $57.63 \times 127.0 \times 13.97 \mathrm{~mm}$ )
RFI 6 sides, EMI 6 sides

Note 1: Time for internal reference heater to stabilize.
Note 2: -6 V may be readily derived from the -15 V power supply using a 7906-type three-terminal regulator. See Figure 1.


Figure 11. Typical Timing - ADAM-826-3.


Figure 12. ADAM-826-3 Mechanical \& Pinout.


## ANMLOGRB

## A/DIA/M-834AI 835A

14- and 15-Bit Extended Temperature Range
Sampling A/D Converters

## Description

Analogic's ADAM-834A and 835A are 14 - and 15 -bit analog-to-digital converters (ADCs) with integral sample-and-hold amplifiers (S/H) that offer significantly improved stability and reduced power dissipation over previous converters of similar architecture. Their low noise, low power dissipation, and guaranteed end-to-end S/H plus A/D performance over a wide temperature range make them ideal for applications requiring high precision in severe environments, such as seismic exploration and field testing. Both combine a precision S/H circuit and a high accuracy A/D converter with tri-state output buffers in a single module, eliminating the interface problems that often accompany the integration of individual modules. (See Figure 1).
The ADAM-834A and 835A feature exceptional accuracy and stability over temperature, including a maximum Differential Nonlinearity Tempco of $\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, clock stability of $\pm 0.03 \% /{ }^{\circ} \mathrm{C}$ maximum, and rapid stabilization at power up. Offering guaranteed performance over the temperature range of $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, the ADAM-834A and 835A satisfy the most stringent industrial and geophysical data acquisition requirements. Low


Figure 1. A/D/A/M-834A/835A Functional Block Diagram.
power dissipation ( 0.9 W ), very low noise ( $75 \mu \mathrm{~V}$ rms), and wide dynamic range ( 15 bits) allow the user to perform sophisticated measurements with a much higher level of confidence in the results than would otherwise be possible in these severe environments.
The ADAM-834A and 835A are fully shielded in 2 " x 4" x 0.37 " metal packages. Each is fully tested and supplied with its documented test data.

## Features

- Guaranteed performance over extended temperature range $\left(-25^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$
- Low Noise $50 \mu \mathrm{~V}$ (ADC)
- Low differential nonlinearity $\pm 0.0015 \%$ FSR maximum (835A)
- Low Drift $\pm 1 \mathrm{pm} /{ }^{\circ} \mathrm{C}$ differential nonlinearity tempco (835A)
- Low Power 0.9W
- Byte-selectable CMOS tri-state buffered outputs
- High Throughput Rate 16.6 kHz
- Pin-programmable input voltage range
0 V to $+5 \mathrm{~V}, 0 \mathrm{~V}$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}$, $\pm 10 \mathrm{~V}$


## Applications

For severe temperature environments including:

- Seismic Data Acquisition
- Portable Field-Test Equipment

Automatic Test Equipment

- Materials Testing


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)
(includes combined S/H and A/D performance, and applies to both ADAM -834A and ADAM-835A except where noted)

## ANALOG INPUTS

Full Scale Range (FSR)
0 V to $+5 \mathrm{~V}, 0 \mathrm{~V}$ to $+10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ (see Table 1)

Maximum Input Without Damage
$\pm 15 \mathrm{~V}$
Impedance
$100 \mathrm{M} \Omega / 15 \mathrm{pF}$
Bias Current
1 nA maximum

## ACCURACY

Absolute Accuracy (Traceable to NBS)
Calibrated to $\pm 0.006 \%$ FSR

## Relative Accuracy

$\pm 0.005 \%$ FSR maximum (ADAM-834A)
$\pm 0.003 \%$ FSR maximum (ADAM-835A)

## Differential Nonlinearity

$\pm 0.003 \%$ FSR maximum (ADAM-834A)
$\pm 0.0015 \%$ FSR maximum (ADAM-835A)
Quantizing Error
$\pm 1 / 2$ LSB
Noise (S/H plus A/D)
$75 \mu \mathrm{~V}$ rms, $\pm 10 \mathrm{~V}$ range
Noise (AID only)
$50 \mu \mathrm{~V}$ rms, $\pm 10 \mathrm{~V}$ range
Monotonicity
Guaranteed

## STABILITY

Tempco of Differential Nonlinearity
$\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum (ADAM-834A)
$\pm 1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum (ADAM-835A)

## Gain Tempco

$\pm 8 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ FSR maximum

## Offset Tempco

$\pm 30 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typical, $\pm 40 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum
Clock Stability
$\pm 0.03 \% /{ }^{\circ} \mathrm{C}$ maximum
Power Supply Sensitivity
$\pm 0.001 \%$ per $1 \%$ change in supply voltage
Warm-up Time to Specified Accuracy 1 minute
Recommended Recalibration Interval 6 months

## DYNAMIC PERFORMANCE

Maximum Throughput Rate
16,600 measurements/second
S/H Aperture Delay
50 ns
S/H Aperture Uncertainty 1 ns

## S/H Hold Mode Feedthrough Rejection

90 dB minimum, measured with 20 V p-p, 10 kHz sine wave input

## S/H Droop Rate

$0.2 \mu \mathrm{~V} / \mu \mathrm{s}$ at $25^{\circ} \mathrm{C}$, doubles every $10^{\circ} \mathrm{C}$
S/H Dielectric Absorption Error
$\pm 0.005 \%$ of input voltage change at maximum throughput rate. Error decreases as sampling time is decreased

## DIGITAL OUTPUTS

## General

Tri-state CMOS
End of Conversion (EOC)
Positive true, 2 unit loads/line, (see Figure 3 for timing) CMOS

## Parallel Data Codes

Positive true, tri-state buffered CMOS; unipolar binary, offset binary, or two's complement (see Table 1)

## DIGITAL INPUTS

## General

Standard TTL, one unit load/line

## S/H Mode Control

Sample $=$ Logic 1 ( $10 \mu \mathrm{~s}$ minimum )
Hold = Logic 0 (minimum $=$ conversion time)
Logic 1 to logic 0 transition time 10 ns
maximum

## A/D Trigger

Negative-going edge; logic 1 to logic 0 transi-
tion 50 ns maximum
Low/High Byte Enable
Logic $0=$ enable
Logic $1=3.5 \mathrm{~V}$ minimum @ $1 \mu \mathrm{~A}$, CMOS
Logic 0 - 1.5 V maximum @ $1 \mu \mathrm{~A}$, CMOS
POWER REQUIREMENTS
$+15 \mathrm{~V}, \pm 3 \%$
37 mA maximum
$-15 \mathrm{~V}, \pm 3 \%$
29 mA maximum
$+5 \mathrm{~V}, \pm 5 \%$
9 mA maximum
Power Dissipation
0.9W

## ENVIRONMENTAL \& MECHANICAL

Operating Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
$5 \%$ to $95 \%$ non-condensing to $40^{\circ} \mathrm{C}$

## Shielding

Electrostatic (RFI) 6 sides; Electromagnetic (EMI) 5 sides
Package Size
$2.00 \times 4.0 \times 0.375$ " ( $50.8 \times 101.6 \times 9.53 \mathrm{~mm}$ )

## Operation

The ADAM-834A and 835A interface directly to most commonly available input devices (multiplexers, amplifiers, etc.). The high input impedance of the fast, fully-buffered unity gain S/H amplifier minimizes source loading errors; the hold mode feedthrough rejection and droop rate allow optimum performance in multichannel systems.
The parallel binary data information is CMOS tri-state buffered allowing access as either two 8 -bit bytes or as a single 16-bit (including B1) data word. (If the tri-state feature is not needed, normal binary outputs can be obtained by connecting the byte enable pins to ground.) For two's complement operation, use B1 instead of B1 (the MSB).
For operation with a single external control pulse, the $\mathrm{S} / \mathrm{H}$ mode control input may be connected to the A/D trigger. Figure 3 shows the timing requirements for the digital control signals.
Input voltage range is established by connecting the $\mathrm{S} / \mathrm{H}$ output to the appropriate A/D input pins (see Table 1). These pins provide access to the S/H output for arbitrary signal processing prior to analog-to-digital conversion. In addition, the S/H may be bypassed for applications requiring direct input to the A/D converter.


Table 1

## Applications

Designed to operate within the $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range with high accuracy and low drift, the ADAM-834A and 835A can serve a variety of applications, including field testing, such as portable multichannel seismic data acquisition systems to provide rapid, highly-linear, and stable A/D conversion. In these systems, geophones receive artificially induced shock wave reflected off the different subsurface strata at various angles and velocities. The weakest signals may travel up to 5 miles through the lithosphere, and are difficult to distinguish from the noise and interference caused by ground roll. After appropriate front-end preamplification and filtering, the analog signals are converted to digital form and stored for processing. The ADAM-834A and 835A provide the low noise and required throughput to digitize data from 16 channels, while maintaining a 1 kHZ -per-Channel sampling rate.


The upper race shows an input that ramps repetitively from -4.88 mV to +4.88 mV and back very slowly in relation to the module's 16.6 kHz sampling rate. The module output is used to drive a digital-to-analog converter, whose output is then shown on the lower trace Thus each level on the staircase corresponds to a set of conversions made around a code center voltage, and the transitions show when the module toggles its LSB. This type of plot may be used to measure differential nonlinearity (the most significant A/D performancce parameter for most applications) and to determine by inspection the existence of errors such as wide code, nar row code, missing code, non-monotonicity, etc. Because the input is dynamically changing, this type of test simulates actual operation very well.

Figure 2. A/D/A/M-835A Crossplot Shows Highly Linear Performance.


Output data registers are National Semiconductor MM74C373,
tPZL, tPZH from falling edge of byte en to B outputs: 105 ns typical, 225 ns Maximum tPLZ, tPHZ from rising edge of byte en to B outputs: 105 ns typical, 225 ns Maximum
Figure 3. ADAM-834A/835A Timing.


## CALIBRATION

Due to excellent long-term stability, these modules will rarely require re-calibration. They should, however, be readjusted when the selected FSR is changed. Offset should be zeroed prior to trimming the range.
Offset Zeroing Procedure

1. Provide the $S / H$ analog input voltage shown in the accompanying table.
2. Adjust the Offset pot until the module output code corresponds to OV, with the LSB alternating equally between 0 and 1.
Range Trimming Procedure (Gain Adjust)
3. Provide the $\mathrm{S} / \mathrm{H}$ analog input voltage shown in the accompanying table.
4. Adjust the Gain pot until the module output code is all 1 's, with the LSB alternating equally between 0 and 1.

| Input Voltages For Calibration |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | ADAM-834A. |  | ADAM-835A. |  |
| Nominal FSR | Offset | Range | Offset | Range |
| 0 to $+5 V$ | $153 \mu V$ | $+4.99954 V$ | $76 \mu \mathrm{~V}$ | +4.99977 V |
| 0 to +10 V | $305 \mu \mathrm{~V}$ | +9.99909 V | $153 \mu \mathrm{~V}$ | +9.99954 V |
| -5 to +5 V | $305 \mu \mathrm{~V}$ | +4.99909 V | $153 \mu \mathrm{~V}$ | +4.99954 V |
| -10 to +10 V | $610 \mu \mathrm{~V}$ | +9.99817 V | $305 \mu \mathrm{~V}$ | +9.99909 V |

## ORDERING GUIDE

Specify
ADAM-834A. 14-bit Resolution
ADAM-835A. 15-bit Resolution


## ANALOGC.

## MP8008R

8-Bit, $3.0 \mu \mathrm{~s}$ Ultra-High, Differential-Linearity, Sampling AID Converter

## Description

The MP8008R, a high speed, 8-bit, sampling analog-to-digital converter (a form of randomizing converter) is designed especially for imaging applications that are based on statistical principles, such as nuclear pulse height analysis. In critical applications, such as nuclear medical diagnostic imaging, where it is imperative to reduce artifacts in the displayed data, high differential-linearity must be attained. The MP8008R provides a basic single-measurement ultrahigh differential-linearity of 0.02\% and provides an even superior differential-linearity of approximately $0.004 \%$ when the dithered offset or randomizing mode of operation is utilized for multiple measurements. This is equivalent to the statistical performance consistent with the near perfect measurement of approximately $10^{11}$ samples of nuclear events of a random amplitude distribution.
The unit employs a unique architecture consisting of a sample-andhold, an A/D converter, two D/A converters, a random number generator, and associated control and output logic. However, unlike previously available averaging-type A/D converters, which typically (continued)


Figure 1. Function Block Diagram.

## Features

Ultra-High Differential Linearity Enhanced differential linearity for large samples ( $1 \%$ of one LSB differential linearity consistent with nuclear even sample quantitites of $10^{4} /$ channel code)

- Low Cost - Very High Speed $3.0 \mu \mathrm{~s}$ Overall Sampling and Conversion Time
- 8-Bit Precision Resolution
- Averaging Scheme Reduces Artifacts
- Low Power
3.3W, typical
- Versatile Input/Output Interfacing TTL Commpatible Latched, Tri-State Outputs
Excellent Stability Over Time and Temperature
$\left(0^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$


## Applications

## Nuclear Medical Diagnostic Imaging <br> - Nuclear Pulse Height Analysis <br> General Scientific Research

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)
ANALOG INPUT
Full Scale Range (FSR)
$\pm 5 \mathrm{~V}$
Impedance
$1.7 \mathrm{k} \Omega \| 10 \mathrm{pF}$

ACCURACY
Resolution
8-bits binary
Differential Non-Linearity
Randomizer on ${ }^{1}$
$1 \%$ of an LSB, max.
Randomizer of $\mathbf{f}^{\mathbf{2}}$
0.003\% FSR typ., 0.005\% FSR max.

Noise
Randomizer on
25• of an LSB p-p
Randomizer off
$1 \%$ of an LSB p-p
Absolute Accuracy
$\pm 0.1 \%$ FSR

## DYNAMIC PERFORMANCE

Throughput Rate
33 kHz , min.
S \& H Acquisition Time
$1.0 \mu \mathrm{~s}$, max.
Conversion Time
$2.0 \mu \mathrm{~s}$, max.
Overload Recovery Time ${ }^{3}$
$1 \mu \mathrm{~s}$, max.

## STABILITY

Differential Non-Linearity (for 1 year from $0^{\circ} \mathrm{C}$
to $+60^{\circ} \mathrm{C}$, with $\pm 3 \%$ power supply variations)
Randomizer on ${ }^{1}$
$1 \%$ of an LSB, max.
Randomizer off ${ }^{2}$
$0.02 \%$ FSR, max.
Gain $0^{\circ} \mathrm{Co}+60^{\circ} \mathrm{C}$
$\pm 0.1 \%$ FSR, max.
Offset $0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
$\pm 0.1 \%$ FSR, max.
Warm-Up Time ${ }^{4}$
5 minutes
POWER SUPPLY
$+15 \mathrm{~V} \pm 3 \%$
75 mA
$-15 \mathrm{~V} \pm 3 \%$
90 mA
$+5 \mathrm{~V} \pm 5 \%$
160 mA
$-5 V \pm 3 \%$
70 mA

## Typical Power Dissipation <br> 3.3W

## DIGITAL CONTROL INPUTS ${ }^{5}$

Start Conversion
Fan In
2 TTL loads
Pulse Width
$100 \mathrm{~ns}, \mathrm{~min}$.
Randomizer Control
0 : Randomizer off
1: Randomizer on

## DIGITAL OUTPUTS ${ }^{5}$

Data
Resolution
8 -bits, overrange
Fan Out
2 TTL, Tri-state Driver
Format
Offset Binary
Data Enable
Low activates data outputs
End of Conversion (EOC)
Fan Out
2 TTL
Busy
Logic "1"

## ENVIRONMENTAL \& MECHANICAL <br> Operating Temperature <br> $0^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ <br> Storage Temperature $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ <br> Relative Humidity <br> $5 \%$ to $85 \%$, non-condensing to $40^{\circ} \mathrm{C}$ <br> Shielding <br> Electromagnetic 6 sides, Electrostatic 6 sides <br> Case Potential <br> Ground <br> Dimensions <br> $4.60 \times 4.60 \times 0.375$ " $\max .(116.8 \times 116.8 \times 9.7$ mm )

## Notes

1. Consistent with nuclear event large sample quantities per channel.
2. Per individual measurement.
3. From 100\% overload (typical range of zoom amplifier.
4. To specified accuracy.
5. TTL compatible.

## Description (cont.)

have depended solely on the random number generator to correct for the relatively low differential-linearity characterisitic of high speed converters, the MP8008R has a superior design, highlighted by an 8-bit A/D converter whose components are physically compatible with a true 15 -bit connverter and that can attain an ultra-high differentiallinearity even with the random number generator turned off. The random number generator, which further minimizes any code width errors by averaging them across a range of N codes, thereby creating virtually equal adjacent code widths, is added to the high-quality basic architecture to assure stability and ultra-high differentiallinearity over time and temperature.
With a high speed conversion time of $2.0 \mu \mathrm{~s}$, the MP8008R provides ultimate 8-bit resolution, utilizing a two-step successive approximation technique of the input signal: an 8 -bit approximation of the signal occurs in about $0.5 \mu \mathrm{~s}$ with $1 / 2$ LSB accuracy; this value is then compared to the analog input signal, and, if necessary, a correction is made to the digital output. This second step takes approximately $1 \mu \mathrm{~s}$. This technique, therefore, requires only one "slower" major decision, not eight faster decisions as with a conventional 8 -bit successive approximation technique.
The MP8008R not only provides ultra-high differential-linearity at a low cost, but with extraordinary versatility. It can easily directly interface with most gamma cameras and data systems now available. It provides reliable performance over a wide temperature range, from $0^{\circ}$ to $60^{\circ} \mathrm{C}$. Including its built-in sample-and-hold function, it occupies only 8 cubic inches and typically requires only 3.3 watts. It performs with excellent stability and performance over extended periods of time. The MP8008R is thus a state-of-the-art economical averaging A/D converter.

## Principles of Operation

The operation of the MP8008R may be best understood by referring to the Functional Block Diagram and the Timing Diagram in Figures 1 and 3.
In a typical imaging application the MP8008R interfaces with two external systems, a gamma camera and a data system, to produce a digitized image of a nuclear event. The gamma camera


Figure 2. Graph of Differential Linearity.


Figure 3. Timing Diagram.
translates each nuclear event into two voltage signals, the amplitude of each signal corresponding to the " X " or " $Y$ " coordinate of the event's position. Each of these signals enters its respective " $X$ " or " $Y$ " MP8008R unit, which converts the amplitude of the analog signal to a digital code. Finally, the digital codes from the " $X$ " and " $Y$ " MP8008R are processed by an external data system that creates a histogram, or image of the nuclear event. The versatile input and output interfacing of the MP8008R allows it to connect easily to most gamma cameras and data systems now available.
The following discussion is limited to the operational analysis of one of the two MP8008R units used in the above process; it should be kept in mind, however, that the " $X$ " and " $Y$ " units function simultaneously and identically.

When a nuclear event occurs, the gamma camera presents an analog voltage signal, ranging from -5 V to +5 V , to the MP80008R. A random digital output from the random number generator is converted to an analog output by the secondary D/A conveter. This analog output is added to the input signal from the gamma camera, and the "sum" is stored across the sample and hold capacitor.
When the exernally presented start conversion signal occurs, the capacitor voltage is frozen and the ADC converts this voltage "sum" to an 8 -bit digital code in $0.5 \mu \mathrm{~s}$. This code is stored in a register in the A/D converter. The primary precision D/A converter then converts this digital code to an analog output which, in $1 \mu \mathrm{~s}$, is compared to the previous voltage "sum" by a comparator. The digital output from the register enters the adder, where any changes to the digital code required by the comparator occur and where the random number is then subtracted. The final 8-bit digital code of the analog input signal is presented to the latched, tri-state outputs.


Figure 4. Effect of Randomizing Technique on Differential Linearity. (See text).

By adding a random number to the analog input signal and then subtracting that number from the digital output, all code width errors are averaged over a range of N codes (see Figure 4). Without this averaging scheme a systematic error would result in wide and narrow codes whenever an analog input signal is equal to a point at which the DAC has an error. This method, therefore, substantially reduces these systematic errors by converting the "sum" of a particular analog input signal and a random number at a different, randomly determined code for each measurement, thus averaging differences between adjacent codes over a range of N codes, and thereby achieving virtually equal code widths and an effective
differential-linearity of approximately $1 \%$ of one LSB for large sample quantities per channel. Ultimately, the result is a substantial reduction of artifacts in the displayed data.


Figure 5. MP8008R Mounting Dimensions.

| Signal | Pin | Pin | Signal |
| :---: | :---: | :---: | :---: |
| + 15V | 17 | 18 | +15V |
| Analog Return | 2 T | 2B | Analog Return |
| -15V | 3 T | 3B | - 15V |
| Analog Return | 4 T | 4B | Analog Return |
| Analog in | 5 T | 5B | Analog Return |
| Analog Return | 67 | 6B | Analog Return |
| -5V | 77 | 7B | -5V |
| Out of Range | 87 | 8B | Data Enable |
| Randomizer Off | 9 T | 98 | No Connection |
| Start Conversion | 10 T | 108 | End of Conversion |
| B1 (MSB) | 11T | 11B | B2 |
| B3 | 12T | 12B | B4 |
| B5 | 13T | 13B | B6 |
| B7 | 14T | 14B | B8 (LSB) |
| No Connection | 15 T | 15B | No Connection |
| No Connection | 16T | 18B | No Connection |
| Digital Return | 17 T | 178 | Digital Return |
| $+5 \mathrm{~V}$ | 18 T | 18B | +5V |

ORDERING GUIDE
Specify: MP8008R.


## ANALOGIC。

## SHAD-2

Low Distortion, Stereo Pair, Audio Digitizing Subsystem

## Description

Analogic's SHAD-2 card with two sample-and-holds, 1 -bit auto gain ranger and 15-bit analog-to-digital converter is, we believe, the optimal cost/performance solution to professional audio digitizing. Its 16 -bit dynamic range, high-speed, dualchannel sampling capability (up to 57 kHz simultaneous sampling, to 105 kHz single-channel sampling), low harmonic distortion ( -86 dB ) and exceptionally high linearity ( $\pm 0.25$ LSB) near zero volts ensure that the SHAD-2 satisfies the stringent requirements of audio pulse-code-modulation (PCM) systems and other high precision audio bandwidth applications. Because the SHAD-2 performs simultaneous dual-channel sampling with a single analog-to-digital converter (ADC) and because its one bit of gain ranging combines with a 15 -bit ADC to give 16 -bit dynamic range, eliminating the need for an expensive 16 -bit ADC, the SHAD-2 reduces the cost of audio digitizing by approximately one-half without sacrificing accuracy or speed.

## Operation

SHAD-2 operation can be adjusted to meet the requirements of the user. For example, sampling flexibility is provided through separate sample


Figure 1. SHAD-2 Functional Block Diagram.
controls in the MP282A which allow simultaneous dual or single-channel sampling. The unit can also be set for parallel or serial data output. For parallel output, the serial clock input should be tied to ground. Serial data is strobed by the falling edge of the clock with the first bit valid after the falling edge of the data ready output (see Figure 2).
Although not usually required in practice, gain and offset may be adjusted through the top edge of the card. To obtain minimum distortion, the potentiometer adjustments should be done with one input connected to a low distortion sine wave with an amplitude just below full scale at a frequency of less than 5 kHz . The MP2735A's offset potentiometer should be adjusted to null the even harmonics, and the
(continued)

## Features

- Low Harmonic Distortion $-86 \mathrm{~dB}$
- Wide Dynamic Range 98 dB
- High-Speed Sampling 105 kHz single channel 57 kHz dual channel
- Low Noise
-92 dB at 20 kHz bandwidth
- Low Cost
- Automatic 1-Bit Gain Ranging
- Low Crosstalk $-86 \mathrm{~dB}$
- Low Aperture Uncertainty less than 0.4 ns
- High Stability Over Time and Temperature


## Applications

[^8]| ANALOG INPUTS <br> Number of Inputs 2 channels | Tempco of Gain |
| :---: | :---: |
|  | $\pm 15 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}^{7}$ |
|  | Tempco of Offset |
|  |  |
| Voltage, damage limit $\pm 15 \mathrm{~V}$ | DIGITAL INPUTS |
|  | Logic Type |
| Impedance $47 \mathrm{k} \Omega / / 10 \mathrm{pF}^{1}$ | Control Channel 1 or Channel 2 2 lines |
| TRANSFER CHARACTERISTICS <br> Full Power Bandwidth (Sample Mode) 150 kHz typ. | Sample Mode |
|  | TTL Low |
|  | Hold Mode |
| Slew Rate (Sample Mode) $6 \mathrm{~V} / \mu \mathrm{s}$ typ. | TTL High |
|  | Required Rise Time |
| $\begin{aligned} & \text { Crosstalk }^{2} \\ & -86 \mathrm{~dB} \end{aligned}$ | 10 ns max. |
|  | Channel Select |
| Gain, Referred to Input (RTI)$+1 \text { or }+2$ | 1 line |
|  | Channel 1 |
| Sample and Hold Acquisition Time ${ }^{3}$ $3.0 \mu \mathrm{~s}$ max. | TTL High |
|  | Channel 2 |
|  | TTL Low |
| Aperture Delay Time 50 ns | Latch Control 1 line |
| Aperture Uncertainty 0.4 ns | Transparent TTL High |
| Channel Select Multiplexer Settling Time ${ }^{3}$ $2.0 \mu \mathrm{~s}$ max. | Latches <br> High-to-low transition |
| Auto Range Amplifier | Latch Control Simultaneously Effects Channel |
| Settling Time ${ }^{4}$ | Select and Gain Output |
| $1.0 \mu \mathrm{~s}$ max. | Trigger Load |
| Sampling Rates | 2 TLL |
| Single-Channel | Width |
| 105 kHz | 100 ns min . |
| Dual-Channel | $5 \mu \mathrm{~s}$ max. |
| 57 kHz | Conversion Starts On low-to-high transition |
| ACCURACY AND STABILITY <br> Harmonic Distortion <br> 20 Hz to 10 kHz <br> -86 dB max. | Serial Clock Load 2 TTL |
|  | Rate <br> 5 MHz max. |
| 10 kHz to 20 kHz <br> -84 dB max. | Timing <br> High-to-low transition shifts data |
| Gain Accuracy $\left(0^{\circ} \mathrm{C}\right.$ to $60^{\circ} \mathrm{C}$ ) $\pm 0.1 \mathrm{~dB}$ max. | Serial Direction <br> High, MSB first out at MSB, low LSB first out at LSB |
| Noise (shorted input; 20 kHz bandwidth) -92 dB , Referred to rms full scale | $\begin{aligned} & \text { Load } \\ & 2 T \mathrm{TL} \end{aligned}$ |
| Gain Change Trip Point (RTI) <br> $\pm 2.35 \mathrm{~V}$ nominal |  |
| at $25^{\circ} \mathrm{C}$ from $0^{\circ}$ to $60^{\circ} \mathrm{C}$ $\leq 2.47 \mathrm{~V}$ | DIGITAL OUTPUT |
|  | Digital Word Length |
| Differential Nonlinearity <br> $\pm 0.5$ LSB max., 0.25 LSB typ. at $\pm 0.25 \mathrm{FSR}$ <br> $\pm 1.0$ LSB max., 0.25 LSB typ. at $\geq 0.25$ FSR | 16 bits |
|  | Coding Complementary offset binary |

## Dynamic Range

16 bits total; 1 bit multiplier plus 15 bits mantissa, including sign

## Internal Architecture

1 sign bit plus 1 gain bit plus 14 magnitude bits
Multiplier (Gain)
1 or 2
Parallel Data
TTL positive true 5 unit loads/line, 16 lines

## Serial Data

Complementary offset binary out of MSB or LSB output lines

## DIGITAL OUTPUT

End of Conversion (EOC, A/D ready $\downarrow$ )
High during conversion; 2 TTL unit loads
Data ready (SHAD-2 ready $\downarrow$ )
Falling edge

## POWER, MECHANICAL, ENVIRONMENTAL

Power Supplies ${ }^{5}$
+10 V to $+15 \mathrm{~V} @ 80 \mathrm{~mA}$ typ.
-10V to -15V @125mA typ.
$+5 \mathrm{~V} \pm 5 \%$ @ 200mA typ.
SHAD-2 Printed Circuit Card
(4.62" x 5.78 " x $\left.0.55^{\prime \prime}\right)^{6}$
( $117 \times 147 \times 14 \mathrm{~mm}$ )

## NOTES

1. If other values are required, please consult factory.
2. Over the frequency range of 20 kHz and inputs at 0 dB (FS) to -15 dB
measured as the peak line by a spectrum analyzer with 100 Hz
bandwidth.
3. To $\pm 0.005 \%$ final value.
4. Measured from high-to-low transition of latch control input.
5. Separate analog, digital and signal returns all internally connected.
6. From surface of board to top of modules (please see mounting diagram).
7. Typical values.

## Operation (cont.)

MP282A's gain potentiometer (controlling the gain ranging amplifier) should be adjusted to null the odd harmonics. For instrumentation applications, the offset potentiometer on the SHAD-2 board should be adjusted until the least significant bit (LSB) of the output code, 100...00/1 alternates equally between " 0 " and " 1 " when the measured potential across pins X and W of the SHAD-2 is $-150 \mu \mathrm{Vdc}$. The gain potentiometer of the MP2735-2 should be adjusted until the LSB of the output code 111...10/1 alternates equally between " 0 " and " 1 " when the same input potential of the SHAD-2 is -4.99954 Vdc .

## Application

The SHAD-2, with its wide dynamic range, low harmonic distortion, dual channel sampling and ultra-low idle noise, is designed to meet the demands of professional audio applications and digital transmission systems. Placed back-to-back with the MP1926A or MP1936 digital-to-analog converters, and the MP201A or AH201 distortion suppressors, the SHAD-2 becomes part of a total audio system* offering exceptional performance at remarkably low cost.

[^9]

Figure 2. Timing for SHAD-2 Serial Data Output.


## ORDERING GUIDE

Specify SHAD-2
Selection Guide ..... 6-2
Glossary. ..... 6-3
AH8304TC Triple 4-bit 100 MHz TTL-compatible Video D/A ..... 6-7
AH8304TM Triple 4-bit 20 MHz TTL-compatible Video D/A with 32 word color LUT memory ..... 6-7
AH8308E Single 8-bit, 150 MHz , ECL-compatible Video D/A ..... 6-13
AH8308T Single 8-bit, 100 MHz , TTL-compatible Video D/A. ..... 6-21
AH8308TC Triple 8-bit, 100 MHz TTL-compatible Video D/A ..... 6-29
AH8404TC Triple 4-bit 25 MHz TTL-compatible Video D/A ..... 6-33
AH8404TM Triple 4-bit 20 MHz TTL-compatible Video D/A with 32-word color LUT memory ..... 6-33
MP1480S 12-bit D/A with 4-20 mA Current Loop or Voltage Output ..... 6-37
MP1814 14-bit General Purpose D/A. ..... 6-43
MP1913A 13-bit Precision D/A ..... 6-47
MP1914A 14-bit Precision D/A ..... 6-47
MP1915A 15-bit Precision D/A ..... 6-47
MP1916A 16-bit Precision D/A ..... 6-47
MP1914TC 14-bit Temperature Stabilized Precision D/A ..... 6-51
MP1915TC 15-bit Temperature Stabilized Precision D/A ..... 6-51
MP1916TC 16-bit Temperature Stabilized Precision D/A ..... 6-51
MP1926A 16-bit Sign/Magnitude, Professional Audio D/A ..... 6-55
MP1926S 16-bit Ultra-stable Sign/Magnitude D/A. ..... 6-55
MP1936 16-bit Sign/Mag. Professional Audio D/A with Integral Distortion Suppressor ..... 6-63
MP8116 16-bit Ultra-Stable, Ultra-Precision D/A ..... 6-73
MP8308ECL 8-bit ECL-compatible Modular Composite Video D/A ..... 6-79
MP8308TTL 8-bit TTL-compatible Modular Composite Video D/A. ..... 6-79
MP8318ECL 8-bit ECL-compatible non-composite Video D/A ..... 6-79
MP8318TTL 8-bit TTL-compatible non-composite Video D/A. ..... 6-79

## SELECTION GUIDE

| MAJOR CHARACTERISTIC OR APPLICATION REQ'MT | PRIMARY PARAMETER | SECONDARY PARAMETER | RECOMMENDED MODEL NO. | DATA SHEET ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| Repeatability | High Stability | 13-Bit Accuracy | MP1913A | 6-47 |
|  |  | 14-Bit Accuracy | MP1914A | 6-47 |
|  |  | 15-Bit Accuracy | MP1915A | 6-47 |
|  |  | 16-Bit Accuracy | MP1916A | 6-47 |
|  | High Stability Temperature Compensated | 14-Bit <br> Accuracy | MP1914TC | 6-51 |
|  |  | 15-Bit <br> Accuracy | MP1915TC | 6-51 |
|  |  | 16-Bit Accuracy | MP1916TC | 6-51 |
| Extreme Repeatability | Extreme Stability High Absolute Acc. | 16-Bit <br> Accuracy | MP8116 | 6-73 |
| Digital Audio Reproduction | Low <br> Harmonic Distortion, High Throughput \& Stability | Low Drift | MP1926A | 6-55 |
|  |  | Low Drift Integral Distortion Suppressor | MP1936 | 6-63 |
| High Stability | Long-Term Drift | Moderate Settling Time | MP1926S | 6-55 |
| Process Control | 4-20 mA Current Loop Output | $\begin{aligned} & \text { 12-Bit Binary } \\ & \text { or } 3 \text { Digit } \\ & \text { BCD Input } \end{aligned}$ | MP1480S | 6-37 |
| Overall Performance | 14-Bit <br> Accuracy | Ease of Implementation | MP1814 | 6-43 |


| Monochrome Composite Video | $\begin{aligned} & \text { 8-Bit } \\ & \text { TTL } \end{aligned}$ | $\begin{gathered} 40 \mathrm{MHz} \\ \text { Pixel Rate } \end{gathered}$ | MP8308 TTL | 6-79 |
| :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{aligned} & 100 \mathrm{MHz} \\ & \text { Pixel Rate } \end{aligned}$ | AH8308T | 6-21 |
|  | 8-Bit ECL | $\begin{aligned} & 100 \mathrm{MHz} \\ & \text { Pixel Rate } \end{aligned}$ | MP8308 ECL | 6-79 |
|  |  | $\begin{aligned} & 150 \mathrm{MHz} \\ & \text { Pixel Rate } \end{aligned}$ | AH8308E | 6-13 |
| Monochrome Non-Composite Video | 8-Bit, TTL | 40 MHz <br> Pixel Rate | MP8318 TTL | 6-79 |
|  | 8-Bit, ECL | $\begin{aligned} & 100 \mathrm{MHz} \\ & \text { Pixel Rate } \end{aligned}$ | MP8318 ECL | 6-79 |
| RGB Composite Video | 4-Bit | 100 MHz | AH8304TC | 6-7 |
|  |  | 25 MHz | AH8404TC | 6-33 |
|  | 4-Bit, with 32 Word, LUT Memory | 20 MHz | AH8304TM | 6-7 |
|  |  | 20 MHz | AH8404TM | 6-33 |
|  | 8-Bit | 100 MHz | AH8308TC | 6-29 |

## GLOSSARY OF TERMS

## DIGITAL TO ANALOG CONVERTERS

ABSOLUTE ACCURACY A measure of the largest static difference between the actual output and that predicted by the ideal transfer function, expressed as a percentage of full-scale output. In the case of a bipolar output range, e.g., -10 V to +10 V , the absolute accuracy is computed as a percentage of the the full range, or 20 V . Absolute accuracy measurements must reference a voltage standard traceable to the NBS with at least an order of magnitude lower uncertainty than the difference represented by one LSB.

DAC A Digital to Analog Converter is a device that accepts signals in the form of a binary code at its input terminals and generates a corresponding analog output. Figure 1 shows the black box representation of a DAC. The ideal transfer function for a three bit, unipolar binary DAC is shown in Figure 2.


Figure 1. "Black Box" Representation of a DAC.


Figure 2. Theoretical Transfer Function of a DAC (first three LSBs only).

DIFFERENTIAL LINEARITY A parameter that measures the actual change in output voltage between adjacent codes compared to the ideal voltage change for adjacent codes. It is expressed as a percentage of the ideal voltage bandwidth or as a fraction of an LSB. Figure 3 demonstrates differential linearity.


Figure 3. Differential Linearity.
DRIFT WITH TIME Drift with time is a change in parameters as a result of component aging. The parameters most affected are offset and gain. Linearity and the tempco's may also be slightly affected. Burn-in at the factory significantly decreases the long term drift. Provision is generally made for recalibration after a specified time period to maintain the rated accuracy.

GAIN The slope of the transfer curve. Gain is generally user adjustable to compensate for long term drift. See Figure 4.


Figure 4. Gain and Offset.
GLITCH A noise spike at the output of a DAC caused by unequal propagation delays through the input registers and the equidelay current switches. Glitches typically occur at major carry points when running at high update rates.
GLITCH AREA The energy content of a glitch, measured in volt-seconds. It is the area under the curve in Figure 5.
GLITCH SETTLING TIME A measure of the duration of a glitch as a result of a worst case transition. It is specified as the length of time that its level exceeds 1 LSB.


Figure 5. Typical Glitch at Major Carry (worst-case transition). Glitch is Approximately 40 mV -ns.

INPUT CODE The binary code for the input of a particular DAC. The various codes include: unipolar binary, offset binary, one's complement and two's complement, as shown in Figure 6. Another popular code is $B C D$, not shown.

Unipolar Binary

$$
V_{\text {out }}=V_{F S}\left[\sum_{n=1}^{n=N}\left(\frac{a_{n}}{2^{n}}\right)\right] \text { where } a_{n}=1 \text { or } 0
$$

This expression relates the actual output voltage ( $\mathrm{V}_{\mathrm{ou}}$ ) to the nominal full-scale voltage ( $\mathrm{V}_{\mathrm{FS}}$ ), for a finite bit-length ( N ). Note that, for $\mathrm{N}=\infty$, and all ONES (all $\mathrm{a}_{\mathrm{n}}$ 's set at 1 ), $\mathrm{V}_{\text {out }}=\mathrm{V}_{\mathrm{FS}}$. For a finite number of bits (finite $N$ ), the maximum output ( $\mathrm{V}_{\text {max }}$ ) is less than $\mathrm{V}_{\mathrm{r} \cdot \mathrm{S}}$, and is given by:

$$
V_{\max }=V_{F S}\left[1-\frac{1}{2^{N}}\right]
$$

Example: for a 12 -bit unipolar binary device with a 0 to +10 Volt nominal full-scale range,

$$
V_{\max }=111111111111=+9.9976 \text { Volts } \quad V_{\min }=000000000000=0.0000 \text { Volts }
$$

Offset Binary Using the same nomenclature as above,

$$
\begin{aligned}
& V_{o u t}=V_{F S}\left[\sum_{n=1}^{n=N}\left(\frac{a_{n}}{2^{(n-1)}}-1\right)\right] \\
& \text { and } V_{\max }(p o s i t i v e)=V_{F S}\left[1-\frac{1}{2^{(N-1)}}\right] \quad \text { and } V_{\max }(\text { negative })=V_{F S}
\end{aligned}
$$

Example: for a 12 -bit offset-binary device with a -10 Volt to +10 Volt nominal full-scale range,
$V_{\max }($ positive $)=111111111111=+9.9951$ Volts
$V(\operatorname{mid}$ scale $)=100000000000=0.0000$ Volts
$V_{\max }($ negative $)=000000000000=-10.0000$ Volts

One's Complement

$$
\begin{aligned}
& \text { mplement } \\
& V_{\text {out }}=V_{F S}\left[\sum_{n=2}^{n=N}\left(\frac{a_{n}}{2^{(n-1)}}\right)-a_{1}+\frac{a_{1}}{2^{(N-1)}}\right] \\
& V_{\max }(\text { positive })=V_{F S}\left[1-\frac{1}{2^{(N-1)}}\right] \text { and } V_{\max }(\text { negative })=-V_{F S}\left[1-\frac{1}{2^{(N-1)}}\right]
\end{aligned}
$$

Example: for a 12 -bit device with one's complement coding, and a nominal full-scale range of -10 Volts to +10 Volts, $\quad V_{\max }($ positive $)=011111111111=+9.9951$ Volts
$V($ mid scale $)=\left\{\begin{array}{cccc}000 & 000 & 000 & 000 \\ 111 & 111 & 111 & 111\end{array}\right\}=0.0000$ Volts
$V_{\max }($ negative $)=100000000000=-9.9951$ Volts

Two's Complement

$$
V_{o u t}=V_{F S}\left[\sum_{n=2}^{n=N}\left(\frac{a_{n}}{2^{(n-1)}}\right)-a_{1}\right] \quad \text { and } V_{\max }=V_{F S}\left[1-\frac{1}{2^{(N-1)}}\right]
$$

Example: for a 12 -bit device with two's complement coding and a nominal full-scale range of -10 Volts to +10 Volts, $V_{\max }($ positive $)=011111111111=+9.9951$ Volts $V$ (mid scale) $=000000000000=0.0000$ Volts $V_{\max }($ negative $)=100000000000=-10.0000$ Volts

Figure 6. Most Common Binary Codes.
MONOTONICITY Is a characteristic that describes an aspect of the code to code progression from minimum to maximum input. A device is said to be monotonic if the output voltage (current) continuously increases as the input code increases, and if the output voltage (current) continuously decreases as the input code decreases. Figure 7 demonstrates non-monotonic behavior.

NOMINAL DIGITAL LEVELS Digital input signal level convention. This is typically TTL, ECL, etc., or two specific voltage ranges.



OUTPUT RANGE The polarity, magnitude and unit of measure of the analog output corresponding to minimum and maximum input codes. Unipolar outputs range from 0 to full scale. Bipolar outputs range from negative full scale to positive full scale. The unit of measure is specified as either voltage or current.

POWER SUPPLY COEFFICIENTS Also stated as power supply sensitivity, this specification indicates how the output of the DAC is affected by changes in the power supply voltage. e.g., 5 ppm FSR/\% change in dc voltage.

RELATIVE ACCURACY This is a measure of the largest deviation of the DAC's actual transfer function from the best straight line approximation of the actual transfer function, expressed as a percentage of full scale range. It comprises errors due to linearity, drift and circuit component tolerances. e.g., $\pm 0.005 \%$ of FSR.

RESOLUTION The number of unique codes the converter will accept at the input data lines. The resolution of an N -bit converter is $2^{N}$.
SETTLING TIME The time it takes for the output of a device to stabilize after an instantaneous code change at the input. It is measured as shown in Figure 8 starting from the leading edge of the input to the point where it enters a defined equilibrium band, typically $\pm 0.5$ LSB.


Figure 8. Defining Slew Rate and Settling Time.

SLEW RATE The maximum slew rate is the fastest rate of change of the output of the DAC as shown in Figure 8. It limits the highest frequency of large-signal sine wave output that can be obtained from the circuit.

TEMPERATURE COEFFICIENTS Changes in the operating temperature can affect a number of parameters including zero offset, gain and differential linearity. The temperature coefficient, or tempco, of one of these parameters is computed as the change in that parameter over a specified temperature range divided by the number of degrees in that temperature range. This yields an average tempco over the temperature range, not the worst case. Analogic tempco specifications are conservative and generally may be considered worst case values.

THROUGHPUT The maximum throughput rate is the greatest number of D/A conversions per second at which a DAC will deliver its full rated static performance regardless of the rate at which the output changes.

VIDEO DAC Video DAC's are specialized digital to analog converters designed specifically for use in video or graphics display systems, where low resolution and high speed are the dominant requirements. Digital inputs include the video data and lines for strobe, sync, blanking, etc. The inputs are converted to a composite video output signal, compatible with RS170, RS330 and/or RS343, for driving a video monitor.

ZERO OFFSET The actual DAC output obtained by applying the input code corresponding to theoretical zero output. Provision is normally made to allow the user to adjust the zero offset to compensate for temperature, power supply voltage, drift with time, etc. See Figure 4.


## ANALOGC.․

## AH8304TMITC

RGB 4-Bit Composite Video D/A Converters

## Description

The AH8304 video D/A converters are third generation hybrid devices that provide designers of low- to mediumcost color display systems with a complete, self-contained, TTL compatible, composite video subsystem in a 24 pin DIP. Offered as both an RGB 4-bit D/A only, or with integral color look-up table memory, the AH8304 features advanced singlechip design that provides low power, high reliability, small size and low cost.
The AH8304TM color-mapped video D/A converter is designed for the color graphic system where space is at a premium. Both the functions of triple (RGB) video D/A converter and color look-up table memory are provided within a single 24-pin package. Data can be written into the internal 32 word RAM (one for each color channel) such that 32 colors can be defined out of a possible 4096 at any given time. During the display (Read) interval, any of these 32 colors can be addressed from a 5 -bit bus. Separate Sync, Blanking and D/A Strobe control inputs are provided.
The AH8304TC D/A converter only is offered for those systems where a different configuration of look-up
table memory is required. The D/A accepts 4-bit TTL data at an update rate of up to 100 MHz for each D/A. Common Blanking, Strobe and Sync (Green Channel only) controls are provided. The output of each channel is RS170/RS330/RS343 compatible, providing a $75 \Omega$ source impedance and 1 Vp -p output signal.

## Features

- Available with and without color look-up table
AH8304TC 100 MHz D/A
AH8304TM 20 MHz D/A with 32 word memory
- TTL compatible
- Synchronous Blanking
- 4096 color palette
- RS170/RS330/RS343 composite video output
- Low Power Dissipation
2.0W maximum for D/A and memory
1.75W maximum for D/A only
- 24-pin DIP


## Applications

- Color graphic workstations
- Personal Computers
- Low-end CAD/CAM Systems



## SPECIFICATIONS

(All specifications are guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted) (All specifications applied to both AH8304TC and AH8304TM unless otherwise noted)

## OUTPUT CHARACTERISTICS (Each Channel)

Gray Scale Output
0.000 V to $-0.643 \mathrm{~V}, \pm 3 \%$ of Gray Scale;
assumes load of $75 \Omega \pm 0.5 \%$ and -5.0 V power supply
Recommended Load Impedance
$75 \Omega, \pm 5 \%$; dc to 50 MHz
Source (Thevenin) Impedance
$75 \Omega, \pm 3 \%$; dc to 50 MHz

## LSB Size

42.9 mV , nominal

Full Scale Step Settling Time
5 ns typical, 7 ns maximum to 1 LSB after propagation delay

## Glitch

Total Glitch Energy less than 250 pV -s for major code transition (0111 to 1000 or vice versa)

## Cable Drive Capability

$75 \Omega$ characteristic impedance; to avoid ap-
preciable signal loss, total length should have
no more than $7.5 \Omega$ dc resistance

## RGB Blanking Level

-0.714 V , with 71 mV (10 IRE Unit) setup; offset is 2 mV maximum, from $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$
Sync Level (Green Channel Only)
$-1.000 \mathrm{~V} ;-0.286 \mathrm{~V}$ ( -40 IRE Units) with respect to Blanking level

## TRANSFER CHARACTERISTICS (Each Channel)

## Resolution

4-bits, 16 Gray Scale levels; 42.9 mV per step nominal

## Reference White Level

1111 produces 0.000 V absolute; 100 IRE Units relative to Blanking level
Reference Black Level
0000 produces -0.643 V absolute, 10 IRE
relative to Blanking level

## Blanking Level

Active BLANKING control reset all DACs to
0000 and drives all outputs to -0.714 V
Differential Non-linearity
$\pm 1 / 2$ LSB, maximum
Monotonicity
Guaranteed
Transfer Gain (Slope) Tempco
$\pm 0.1 \%$ FSR $/{ }^{\circ} \mathrm{C}$
RGB Blanking Input Delay
7 ns typical to $10 \%$ of final value after STROBE goes low

INPUT CHARACTERISTICS
Logic Levels (all inputs)
Standard TTL levels
Logic $1>2.4 \mathrm{~V}$
Logic $0<0.4 \mathrm{~V}$
No input to go below -0.3 V
(CMOS limits)

Loading -
Data, Address, and Strobe
2 Unit Load
Control Inputs
2 Unit Load
Coding -
Data and Address
Binary
Data Update Rate
100 MHz maximum (AH8304TC); 20 MHz maximum (AH8304TM)

## Memory Size

32 word by 4-bit (each RAM/channel) (AH8304TM only)
Control Inputs -

## DAC Strobe

Input data entered into all three DAC channels
simultaneously on negative-going edge
Rise and Fall Time
$<10 \mathrm{~ns}$ ( $10 \%$ to $90 \%$ )
DAC Propagation Delay
7 ns typical, $\overline{\text { STROBE }}$ to output, $50 \%$ points
Blanking Rise and Fall Time
<10 ns (10\% to 90\%)

## RGB Blanking

Logic 1 on RGB Blanking input resets all DAC inputs to 0000 and drives all DAC outputs to -0.714 V ; RGB Blanking is synchronous with STROBE; next STROBE after Blanking released loads input data

## Sync

Logic 1 on RGB Blanking and Sync inputs resets all DAC inputs to 0000 drives Red and Blue outputs to -0.714 V , and Green output to -1.000 V absolute, -0.286 V ( -40 IRE Units) relative to Blanking level
Sync Rise and Fall Time
$<10 \mathrm{~ns}$ ( $10 \%$ to $90 \%$ )

## Read/Write

(AH8304TM only)
Logic 0 select Read operation; logic 1 selects Write operation; DAC outputs will retain previous Read value until STROBE input is applied; STROBE applied during Write operation causes Reference Black output level from all

## DACs

## Address - 5-bits (AO to A4)

(AH8304TM only)
Determines location in memory for Read or
Write operation; used as Address input to load
RAM arrays in Write mode and as look up table
inputs in Read (Display) mode
Chip Select - CSR, CSG, CSB
(AH8304TM only)
CHIP SELECT for each channel (RED, GREEN,
BLUE); logic 0 selects RAM channel for Read or Write operation; when deselected, RAM data output is all 0's to DAC inputs; DAC output of
deselected channels will retain last Read level if no STROBE applied, otherwise output will fall to Reference Black level; normally only one input at a time is enabled (selected) to write data to its corresponding RAM; all inputs are enabled to read data during display; these may be held at logic 0 throughout the read cycle

## Data

16 Valid levels per channel;
D0-D3 (AH8304TC only)
R0-R3 (Red) (AH8304TM only)
G0-G3 (Green) (AH8304TM only)
B0-B3 (Blue) (AH8304TM only)
DYNAMIC CHARACTERISTICS
Width of Write Pulse
25 ns minimum (AH8304TM only)
Data and Address Before Write
30 ns minimum (AH8304TM only)
Data and Address Hold Time
20 ns minimum (AH8304TM only)
Data Setup Time
2 ns minimum (AH8304TC only)
Data Hold Time
1.5 ns minimum (AH8304TC only)

Address Access Time
(after valid address)
48 ns maximum (AH8304TM only)
Chip Select Access
40 ns minimum (AH8304TM only)
Chip Select Disable
35 ns maximum (AH8304TM only)

## POWER REQUIREMENTS

$+5.0 \mathrm{~V}, \pm 5 \%$
50 mA maximum; 50 mVp -p ripple maximum
(AH8304TC)
100 mA maximum; 50 mVp -p ripple maximum (AH8304TM)

- 5.0 V

200 mA maximum; 30 mVp -p ripple maximum
( -4.75 V to -5.5 V operating range)

## Power Dissipation

1.25W typical, 1.75W maximum (AH8304TC)
1.50 W typical, 1.56 W maximum (AH8304TM)

ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$

## Dimensions

$1.00^{\prime \prime} \times 1.30$ " x 0.3 " maximum
$(25.4 \times 33.14 \times 7.62 \mathrm{~mm}$ )
24-pin triple width DIP

## SPECIAL TESTING

Burn-in
24 Hours at $+125^{\circ} \mathrm{C}$ to be performed prior to final test

## Operation

The AH8304TM consists of two major functional blocks: (1) a memory organized as three 32 -word by 4-bit blocks, one for each color channel, with common data, Read/Write control, and address inputs, separate chip select inputs and data outputs, and (2) a triple 4-bit D/A converter with common Sync, Blanking and Strobe control inputs. Data flow is always from the output of the memory to the input of the D/A converter.
During a Write operation, data to be loaded into the look-up table RAM is presented to the DATA inputs. The CHIP SELECT line for the color channel RAM that is to receive the data is brought low to enable it. The READMRITE line is pulsed, causing the data to be written into the RAM location corresponding to the address that is presented to the five ADDRESS inputs. The CHIP SELECT line is then brought high to disable that channel. The process can then be repeated for other addresses and/or color channels.
During a Read (display) cycle, all three CHIP
SELECT lines are brought low to enable all
channels, and the RAM address for the color to be displayed is presented to the ADDRESS inputs. After a propagation delay through the memory of 48 ns maximum, the data from the addressed RAM location appears at the output of the memory. The D/A STROBE line is then pulsed to latch the data into the D/A converter input register. After a propagation delay through the D/A converter, the corresponding analog output voltages appear at the three D/A outputs.
The AH8304TC D/A only (and the D/A portion of the AH8304TM) accepts a 4-bit data word for each of the three video channels (Red, Green, and Blue). The data is presented to the DATA inputs and held for the duration of the setup time, and the STROBE is pulsed to load ing interval, the BLANKING control line is activated by a logic 1. At the next STROBE pulse, this resets the three input registers to 0000 and drives the D/A outputs to the blanking level. When the SYNC line is activated, the output of the Green channel is driven to the sync level. At the end of the blanking/sync in-
terval, the SYNC and BLANKING controls are released (i.e. returned to a logic 0 ). At the next STROBE to the D/A, the data present at the

DATA inputs to the D/A is loaded into the input registers, and will subsequently appear at the D/A outputs after the D/A propagation delay.

| INPUTS |  |  |  |  |  |  | FUNCTION |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { DATA } \\ & \text { D3-D0 } \end{aligned}$ | $\left\|\begin{array}{c} \text { ADDRESS } \\ \text { A4-AO } \end{array}\right\|$ | $\overline{\mathrm{CS}}$ | $\overline{\mathbf{R}} / \mathbf{W}$ | BLANKING | SYNC | STROBE |  |
| X | VALID | L | L | L | L | $\mathrm{H} \rightarrow \mathrm{L}$ | RAM Data Loaded into DAC |
| X | X | L | L | H | L | H | Previous Data Value From RAM at DAC Output |
| X | X | L | L | H | L | $\mathrm{H} \rightarrow \mathrm{L}$ | DAC Output at Blanking Level |
| $x$ | $x$ | L | L | H | H | X | DAC Output at SYNC Level |
| X | X | H | L | L | L | $\mathrm{H} \rightarrow \mathrm{L}$ | DAC Output at Ref. Black Level |
| X | X | H | L | H | L | L | Last Data Value at DAC Output |
| VALID | VALID | L | H | H | L | $\begin{aligned} & \mathrm{H} \rightarrow \mathrm{~L}, \\ & \text { then } X \end{aligned}$ | Data Loaded into RAM, DAC Out at Blanking Level |
| VALID | VALID | L | H | L | L | $\mathrm{H} \rightarrow \mathrm{L}$ | DAC Output at Reference Black |

Truth Table - AH8304TM


## TYPICAL TIMING AH8304TM/TC



## ORDERING GUIDE

20 MHz , RGB 4-bit D/A with 32 word lookup

## Description

The AH8308E is an optimally designed, low power, minimum glitch, high-speed 8-bit composite video D/A converter intended for use in both color and monochromatic Digital Display Systems. It accepts 8-bit digital video data plus sync and blanking commands from an ECL source and produces a composite video output to directly drive a $75 \Omega$ load at an update rate as high as 150 MHz .* The 150 MHz update rate, uncontested by competing units, makes this device compatible with the highest resolution monitors available.
A second generation unit drawing on the success of the current industry standard MP8308, the AH8308E represents a completely new design utilizing an optimum combination of hybrid techniques and the successful marriage of both analog and digital circuits on a single custom monolithic VLSI chip. This combination is a significant advance over competing units which are either discrete component devices (modules) or "hybridized" versions of


Figure 1. AH8308E Functional Block Diagram.
discrete designs. Of particular importance is that the AH8308E achieves its remarkable 150 MHz data update rate at a power dissipation level $25 \%$ lower than that of the earlier generation MP8308 or of the other competing modular or hybrid devices patterned after it. All of this has been accomplished without
*A TTL version is also available from Analogic. Please consult the factory for information and applications assistance.
(continued)

## Features

■ Up to 150 MHz Update Rate Extends display system capabilities
■ Direct Drive to $75 \Omega$ Coaxial Cable/TV Monitor
Requires no additional circuitry

- "Glitch-free" performance Simplifies display system design
- Single - 5V Supply

Reduces power requirements

- Composite Sync and Blanking Control Inputs
Eliminates need for additional logic or amplifiers
- 10\% Overbright Control Input Provides Simple Cursor Generation
- 3 ns Rise and Fall Time Provides accurate, high-speed data update
- RS170A/RS343A Compatible Output Directly drives monitor
- Standard 0.790" X 1.305" X $0.295 "$ Package Size Reduces pc board area requirements
- Pin Compatible with Hybrid Reproductions of Our Earlier Generation MP8308

Applications
■ CAD/CAM Display Systems
Medical Imaging Systems
■ "Quick Look" Display Systems

- Image Processing Systems
- Workstations
- Monochrome or Color Display Systems


## SPECIFICATIONS

(All specification guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## OUTPUT CHARACTERISTICS

## Output Voltage Range

Composite Video
0 V to $-1.064 \mathrm{~V} ; \pm 3 \%$ into $75 \Omega$ termination
Gray Scale
-0.064 V to $-0.707 \mathrm{~V} ; \pm 3 \%$ into $75 \Omega$
termination

## Output Current (Gray Scale)

- 17 mA

Recommended Load Impedance
$75 \Omega \pm 5 \%$, dc to 50 MHz
Source (Thevenin) Impedance
$75 \Omega \pm 5 \%$, dc to 50 MHz
LSB Size
2.5 mV , nominal

Rise and Fall Time
3 ns , typical, 4 ns maximum ( $10 \%$ to $90 \%$ )
Full Step Settling Time
8 ns typical to 1 LSB (0.4\%)
Glitch Settling Time
5 ns to <1 LSB for worst MSB transition
Glitch Area
50 pV -s typical, 70 pV -s max.
Compliance Voltage
+1.1 V to -1.1 V typical
Cable Drive Capacity
$75 \Omega$ characteristic impedance. Total length to have $7.5 \Omega$ dc resistance maximum.

## Composite Sync Level

-1.064 V with Standard Setup
-0.286 V ( -40 IRE Units) with respect to blanking level (back porch)
Composite Blanking Level
-0.778 V , with Standard Setup
10\% Overbright Level
OV

## TRANSFER CHARACTERISTICS

Resolution
8 Bits, 256 Gray Scale Levels
2.5 mV per step, nominal

Coding
Binary
Reference White Level
11111111 produces -0.064 V absolute, +0.714 V
(100 IRE Units) relative to blanking level with
Standard Set-up; +0.643 V relative to Reference Black
Reference Black
00000000 produces -0.707 V absolute, +0.071 V (10 IRE Units) relative to blanking level with Standard Set-up
Differential Linearity
$\pm 1 / 2$ LSB maximum

## Monotonicity

Guaranteed
Offset (dc output with 10\% Overbright Actuated)
$\pm 1 / 2$ LSB maximum, $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$
Transfer Gain (Slope) Tempco
$\pm 0.1 \%$ FSR $/{ }^{\circ} \mathrm{C}$ maximum
Propagation Delay
5 ns typical, strobe to output, $50 \%$ points
Control Input Speed
(Sync, Blanking, Ref. White and 10\% Overbright)
8 ns typical to settle to $10 \%$ of final value

## INPUT CHARACTERISTICS

Logic Levels (all inputs)
10,000 Series ECL
Logic $0=-1.75 \mathrm{~V}$
Logic $1=-0.9 \mathrm{~V}$
Loading (all inputs)
5 pF ; open transistor base;
open input is logic " 0 "
Data
8 ECL compatible inputs
Validity
Data must be valid 2.0 ns min., prior to Strobe and remain valid for 1.5 ns after data Strobed
Update Rate
150 MHz maximum

## Strobe Input

Data entered on positive-going edge (Timing
Reference)
Pulse width
3 ns minimum
Setup (Reference Black to Blanking)
Input open: Standard 71 mV (10 IRE Units)
Input to -5.0 V : 142 mV (20 IRE Units)
Input to Ground: 0 mV (0 IRE Units)
Composite Sync Level
Logic " 0 " on Sync and Blanking inputs simultaneously resets the input register to 00000000 and drives the output to -1.0643 V

## Composite Blanking Level

Logic " 0 " on Blanking input simultaneously resets the input register and drives the output to -0.778 V
Reference White Level
Logic "0" on Ref. White input simultaneously sets input register to 11111111 and drives output to -0.064 V
10\% Overbright Level
Logic " 0 " on input raises output level by 0.064 V .
Logic " 0 " on Ref. White and 10\% Overbright
drives output to OV
Rise and Fall Time (all inputs)
$<10$ ns ( $10 \%$ to $90 \%$ )

## Glitch Adjust

Control Port Input Impedance
$7.5 \mathrm{k} \Omega$
Control Sensitivity
50 pV -s per volt applied to Glitch Adjust pin

POWER SUPPLY REQUIREMENTS
Power Dissipation
0.875 watt typical, 1.0 watt maximum

Power Supply Required Regulation
-5.0 V @ 200 mA maximum 5 mV p-p ripple
-4.75 V to -5.5 V operating range

ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range (Ambient)
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $+40^{\circ} \mathrm{C}$
Mechanical Dimensions
0.790 " X 1.305 " X 0.295 "
(20.07 X $33.14 \times 7.49 \mathrm{~mm}$ )

24-pin DIP
Shielding
Steel foil

## Description (cont.)

sacrifice of the trend-setting features of its discrete predecessor such as composite video $75 \Omega$ output and "glitch free" performance.
Because of its single chip design, the unit has fewer internal wire bonds than other presently available devices and should therefore prove to be considerably more reliable over the life of the system in which it is used. Reliability is further enhanced by its reduced power consumption and lower resultant operating temperature rise.
The very fast ( 3 ns ) rise time analog output directly drives a $75 \Omega$ coaxial cable and monitor with a $1 \mathrm{Vp}-\mathrm{p}$ signal. No additional amplifiers are required. Output transitions exhibit sufficiently low glitch that no further processing is required. Separate digital inputs for sync and blanking allow the AH8308E to produce EIA Standard RS170A and RS343A compatible composite video; these plus additional inputs for Reference White and 10\% Overbright combine to provide a complete, highly flexible, improved performance video D/A converter subsystem in a $0.790^{\prime \prime} \times 1.305$ " 24 pin dual-in-line package.

## Theory of Operation

Eight bit digital data presented to the AH8308E on the data inputs is latched into the $D$ flip-flops at the rising edge of the STROBE pulse applied to the STROBE control input. The outputs of the flip-flops, drive high speed switches that steer current into a summing network with an output impedance of $75 \Omega$, developing a $1 \mathrm{Vp}-\mathrm{p}$ signal directly. Due to the extremely small differential delay among the eight data channels, the code switching output glitches are invisible even on the best video monitor.
Digital control inputs for REFERENCE WHITE, SYNC, BLANKING and 10\% OVERBRIGHT are provided. A logic 0 on the REF. WHITE input sets the flip-flops and drives the output to -0.064 V . Logic 0 on $10 \%$ OVERBRIGHT increases the output by 0.064 V . Used in conjunction with REF. WHITE, the flip-flops are set and the output is driven to 0 V . Logic 0 on the BLANKING and SYNC inputs resets the flip-flops and drives the output to -0.778 V and -1.064 V respectively. Combinations of BLANKING/SYNC and REF. WHITE/10\% OVERBRIGHT should be avoided. While no damage will result, active levels on both the SET and RESET inputs of the D flip-flops will cause an indeterminate output. The condition of the SETUP line determines the relative levels between Reference Black and the Blanking level-left open, the standard 71 mV ( 10 IRE units) is produced; tied to $-5.0 \mathrm{~V}, 142 \mathrm{mV}$ (20 IRE units) is produced; tied to ground, 0 mV (0 IRE units) is produced. (See Chart on last page).
Please refer to the Timing Diagram, Applications Considerations and Video System Display Application sections for examples of operation.

## ENGINEER'S NOTEBOOK

## Power Supply Requirements

The AH8308E is capable of operating from a single supply voltage between -4.75 V and -5.5 V . The output amplitudes specified are nominal values based on a -5.0 V supply and will change in direct proportion to the supply voltage.
The unit can be powered from a +5.0 V positive supply voltage if +5.0 V is connected to the GROUND pin(s) and digital return is connected to the -5.0 V pin. Under these conditions, the composite video signal will vary from +3.935 V to +5.0 V , and THE CASE WILL BE AT A +5.0 V POTENTIAL.


Figure 2. Glitch Adjust

The glitch area will vary as a function of the supply voltage. The factory trim is normally carried out at -5.0 V , and may be done at another voltage if specified when ordering.
If other than -5.0 V is used with a unit trimmed for -5.0 V operation, provisions should be made on the PC board for a $10 \mathrm{k} \Omega$ potentiometer connected to the GLITCH ADJUST terminal as shown (in Figure 2). The pot should be adjusted to reduce the glitch area to a minimum.


Figure 3. Glitch Area at Major Code Transition.

## Grounding

There are six ground pins all tied together internally and to the case of the AH8308E.

## ECL Terminators

ECL terminators are not included in the AH8308E. If the source of the video data and control inputs is more than a few inches away from these units, ECL terminators should be connected in close proximity to the inputs of the DAC.


Figure 4. Full Scale Step Rise Time.

## Current Output

The AH8308E can be used as a current output device by connecting the inverting input of an op-amp to the AH8308E output and then selecting the appropriate op amp feedback resistor for the required voltage output.

## Timing

Figure 5 shows a detailed diagram depicting the timing required to generate composite video for the case of a full-scale (black to white) transition. 10\% OVERBRIGHT, BLANKING PEDESTAL and SYNC are generated after the transition to illustrate their timing.

## Cursor

To produce a cursor on a display, both $10 \%$ OVERBRIGHT and REF. WHITE should be brought to a logic " 0 " which will drive the output to 0 V . If $10 \%$ OVERBRIGHT only is brought to logic " 0 ", the output of the AH8308E will increase +0.064 V above its prior output.

## APPLICATION CONSIDERATIONS

## Color Graphic Systems

The AH8308E is ideally suited for both monochrome composite video and RGB color applications. Normally only one channel (the green) carries the SYNC signal. For use in the other channels of such systems, the SYNC and BLANKING lines of the AH8308E can be disabled by tying them to logic " 1 ".

While using a 4 - or 5 -bit DAC on each color channel may give the display system designer an acceptable color palette, the low resolution of these DACs may not be sufficient to allow anti-aliasing techniques to be employed successfully. One advantage to using an 8 -bit DAC may not be readily apparent - one that is especially important in CAD/CAM type applications where single lines are drawn on the display. When a diagonal line is drawn on the screen, "bunching" of the pixels causes a stair-stepping effect as opposed to a smooth, straight line. Increased display resolution helps to reduce the size of the "jaggies" and smooth out the line, but cannot eliminate them. Various digital-differential analysis (DDA) procedures have been used to attempt to solve this problem and minimize its effect. By using a higher Z-axis resolution (8 bits versus 4 or 5 ), further improvements in the
smoothing process are realized with these DDA procedures due to the increased control over the line intensity.

## Broadcast Usage

The AH3808E is normally used in Digital Display applications. It can, however, be used for broadcast applications in which case additional circuitry is required in order to achieve full compliance with EIA Industrial Electronics Tentative Standard No. 1 (part of RS170A). This Standard details the exact waveform and timing characteristics of the broadcast composite video signal. The additional circuitry would, at a minimum, provide $\sin x / x$ correction and bandwidth filtering. In addition, the set-up on the AH8308E should be changed to 7.5 IRE units by placing a nominal $560 \Omega$ resistor between the SETUP terminal and ground.


Figure 5. Typical Timing Diagram.


Figure 6. Typical AH8308E Application.

## Video Display System Application

An example of a video display subsystem using the AH8308E is shown in block diagram form in Figure 6. Only the portion of the subsystem directly involving the AH8308E is shown. The memory and monitor circuits are not discussed in any detail, since system requirements vary. It is assumed that eight bits of digital data are available from some source for use by the AH8308E and that a monitor and/or sinx/x filter is being driven by the AH8308E. If fewer than eight bits are used, tie the unused LSBs to logic 0. Any AH8308E control signals not required in a particular system application should be tied to logic 1 to prevent erroneous operation. The timing relationships of the various signals are shown in Figure 5.
Timing for the overall display subsystem is derived from the system Master Clock. Through a suitable divider chain, a frequency of either $2.04 \mathrm{M} \nmid \mathrm{I}$ is generated and applied to the clock input of the 3262A Sync Generator IC or equivalent (see Note*). From this clock signal, the 3262A generates the Sync and Blanking signals. The Composite Sync and Blanking Signals are applied to the corresponding control inputs on the AH8308E after first passing through TTL to ECL
translators (all 3262A outputs are TTL). The Sync and Blanking signals are also sent to the Memory System for use by the Memory Address logic if required. The 3262A also produces a timing signal which is valid during the Vertical Interval at the start of the odd Field for interlaced systems. This signal may be used to control Memory addressing.
In most systems the "setup" level is left at one particular value such as the Standard 71 mV . In rare cases where the application requires, the setup level can be controlled digitally by means of a DAC with either a current or voltage output. If the SETUP pin is driven as a voltage point, values from -1 to -5 V will produce 0 to 20 IRE units respectively. If a current is injected into the SETUP pin, approximately 11 mA is needed to produce 0 IRE units.
The composite video output from the AH8308E is connected directly to the (758terminated) video input of the monitor by a length of coax cable. The length of the cable should be limited to prevent the dc resistance of the cable run from exceeding 7.5 $\Omega$. If an amplifier is used between the AH8308E output and the monitor, longer lengths of cable can be allowed.

## *PLEASE NOTE

Comparable IC's providing similar functions to the 3262A are available from several manufacturers. The Fairchild part number 3262A is used by way of example, and no endorsement by Analogic of this part is intended or implied. Also, Analogic is not responsible for the accuracy of technical information supplied by other manufacturers.

## The Video Signal

The EIA Standards RS170 and RS343 define the video signal in detail and refer to the IRE units for measuring the various components of the signal. The total peak amplitude of the standard video signal, from the maximum white level to the sync level is 140 IRE units. The standards further define the video signal as $1 \mathrm{Vp}-\mathrm{p}$; therefore, 1 IRE unit is 7.14 mV . The maximum white level is the most positive amplitude of the video signal, and sync the most negative; this is referred to as a blacknegative (as opposed to a black-positive) video signal. The illustration in Figure 7 depicts the composite video signal produced by the AH8308E.
The AH8308E provides a $10 \%$ Overbright feature which causes a negative shift in all of the various levels (i.e. Reference White, Reference Black, Blanking and Sync) by approximately 9 IRE units. The relative number of IRE units between each of these levels is compatible with the EIA Standards. As the definitions are given for the various levels in the AH8308E composite signal, it should be remembered that they differ from the standard RS170/RS343 absolute levels by 9 IRE units ( 0.064 V ).

The most positive amplitude level is the 10\% Overbright. As its name implies, this level is higher than the whitest level of the picture information by $10 \%$ of the signal or 0.064 V ( $10 \%$ of 0.643 V ). This level is most often used to define a cursor on a display screen. By making the cursor $10 \%$ brighter than the remainder of the picture, it can be located easily. REFERENCE WHITE is the most positive amplitude of the normal picture information, while REFERENCE BLACK is the most negative. The span of signal from REFERENCE WHITE to REFERENCE BLACK is 90 IRE units or 0.643 V . This span is divided into 256 discrete levels (gray scale) because of the 8 -bit resolution of the AH8308E.
The BLANKING LEVEL is 10 IRE units below REFERENCE BLACK in a standard video signal and is the voltage level that will completely cut off the display screen. The AH8308E provides a means of varying the relative distance between the REFERENCE BLACK and BLANKING LEVEL, referred to as the setup. The SETUP pin on the AH8308E can be programmed to provide a set-up of 0 mV ., 71 mV or 142 mV (0 IRE, 10 IRE or 20 IRE units). Left open, the standard setup of 71 mV (10 IRE units) is produced. Tied to -5 V , 142 mV (20 IRE units) is produced; tied to ground, 0 mV ( 0 IRE units) is produced. The BLANKING LEVEL is also referred to as the PEDESTAL, BACK PORCH or FRONT PORCH.
(continued)


Figure 7. The Composite Video Signal (Not to Scale).

## The Video Signal (cont.)

The most negative amplitude of video signal is the SYNC LEVEL at -40 IRE $(0.286 \mathrm{~V})$ below the BLANKING LEVEL. Relative to $10 \%$ OVERBRIGHT, this level is -1.064 V . The SYNC level is used to synchronize the scanning circuits in the display system. It is this sync level (along with BLANKING) produced directly by the AH8308E that provides the composite video signal.
All of the above definitions apply to both monochrome and color (RED/BLUE/GREEN) display systems. In color systems, the composite signal is produced on only one channel (usually the green). The other two DACs producing the Red and Blue video have the Sync and Blanking levels disabled by tying them to logic 1.


ORDERING GUIDE
150 MHz 8-Bit ECL Video DAC...
Specify AH8308E


## Available Options

The AH8308E is normally supplied with eight DATA INPUTS, STROBE, REFERENCE WHITE, 10\% OVERBRIGHT, BLANKING and SYNC control inputs, capable of driving a 75 ohm terminated monitor. We invite inquiries on modifications such as dual monitor capability, REFERENCE BLACK CONTROL and other custom requirements.


ANMLDGIS.
AH8308T

## 8-Bit Composite Video D/A Converter

## Description

The AH8308T is a complete 8-bit composite video D/A converter subsystem intended for use in monochromatic and color Digital Display Systems. Unlike other devices which require external power-hungry TTL to ECL level translators, the AH8308T accepts 8 -bit digital video data plus sync and blanking commands directly from a TTL source and produces a composite video output that drives into a $75 \Omega$ load at an update rate as high as $65 \mathrm{MHz}^{*}$.
The 1.15 watt maximum power dissipation of the AH8308T is significantly lower than its competition; other devices typically require as much as 1.7 watts just for the video DAC (plus another 300 plus milliwatts for the external level translators for a total of over 2.0 watts!).
The single chip design of the AH8308T means far fewer internal wire bonds than other presently available devices and a considerable improvement in reliability over the life of the system in which it is used. Reliability is further enhanced by its reduced power dissipation and lower resultant operating temperature rise. The analog output, which has a typical full scale settling time of 7.5 ns , will directly drive a $75 \Omega$ coaxial cable and monitor with a $1 \mathrm{Vp}-\mathrm{p}$ signal. No additional amplifiers are
*A 150 MHz ECL video D/A Converter, the AH8308E, is also available. Please consult the factory for technical/applications information.


Figure 1. AH8308T Functional Block Diagram.
required. Output transitions exhibit sufficiently low glitch that no further processing is required. Because these parts, as well as TTL to ECL level translators are not required, the AH8308T provides savings in PC board area, parts count and product cost.
Separate inputs for sync and blanking allow the AH8308T to produce EIA standards RS170A and RS343A compatible composite video; these plus additional inputs for Reference White and $10 \%$ Overbright combine to provide a complete, highly flexible, low power, improved performance video D/A converter subsystem in a $0.78^{\prime \prime} \times 1.30^{\prime \prime} \times 0.3^{\prime \prime}, 24$ pin dual-inline package.

## Features

- Lower Power - 1.15 watt maximum
Extends reliability over other devices
- Complete TTL input Video DIA Subsystem Requires no external level translators
- Up to 65 MHz Update Rate Extends display system capabilities
- "Glitch-free" Performance Simplifies display system design
- Direct Drive to 75 Coaxial Cable/Monitor
Requires no additional circuitry
- Composite Sync and Blanking Control Inputs
Directly produces RS170A/RS343A compatible output
- 10\% Overbright Control Input Provides simple cursor generation
■ Standard $0.78^{\prime \prime} \times 1.305^{\prime \prime} \times 0.3^{\prime \prime}$ Package Size
Reduces pc board area requirements


## Applications

- CAD/CAM Display Systems
- Medical Imaging Systems
- "Quick Look" Display Systems
- Image Processing Systems
- Workstations
- Monochrome or Color Display Systems


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## OUTPUT CHARACTERISTICS

## Output Voltage Range Composite

OV to $-1.064 \mathrm{~V} ; \pm 3 \%$ of Full Scale into $75 \Omega$
termination
Gray Scale
-0.064 V to $-0.707 \mathrm{~V} ; \pm 3 \%$ of Gray Scale into $75 \Omega$ termination
Recommended Load Impedance
$75 \Omega \pm 5 \%$, dc to 50 MHz
Source (Thevenin) Impedance
$75 \Omega \pm 5 \%$, dc to 50 MHz
LSB Size
2.5 mV , nominal

Rise and Fall Time
3 ns, typical, 4 ns maximum ( $10 \%$ to $90 \%$ )
Full Step Settling Time
7.5 ns typical to 1 LSB (0.4\%)

Glitch Settling Time
3 ns to <1 LSB for worst MSB transition
Glitch Area
35 pV -s typical, 70 pV -s max.
Compliance Voltage
+1.1 V to -1.1 V typical
Cable Drive Capacity
$75 \Omega$ characteristic impedance
To avoid appreciable signal loss, total length should have no more than $7.5 \Omega$ dc resistance
Composite Sync Level
-1.064 V with Standard Setup
-0.286 V ( -40 IRE Units) with respect to blanking level (back porch)
Composite Blanking Level
-0.778 V , with Standard Setup
10\% Overbright Level
0 V

## TRANSFER CHARACTERISTICS

## Resolution

8 Bits, 256 Gray Scale Levels
2.5 mV per step, nominal

Coding
Binary

## Reference White Level

11111111 produces -0.064 V absolute; +0.714 V
(100 IRE Units) relative to blanking level with Standard Set-up; + 0.643V relative to Reference Black
Reference Black Level
00000000 produces -0.707 V absolute; +0.071 V
(10 IRE Units) relative to blanking level with Stan-
dard Set-up
Differential Linearity
$\pm 1 / 2$ LSB maximum
Monotonicity
Guaranteed
Offset (dc output with 10\% Overbright Actuated)
$\pm 1 / 2$ LSB maximum, $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$

Transfer Gain (Slope) Tempco
$\pm 0.1 \%$ FSR $/{ }^{\circ} \mathrm{C}$ maximum
Propagation Delay
7 ns Typical, Strobe to output 50\% points
Control Input Speed
(Sync, Blanking, Ref. White and 10\% Overbright)
10 ns Typical to settle to $10 \%$ of final value (Refer to Timing Diagram)

## INPUT CHARACTERISTICS

Logic Levels (all inputs)
Standard TTL Levels
LOGIC $1 \geq 2.4 \mathrm{~V}$
LOGIC $2 \leq 0.4 \mathrm{~V}$
Loading

## Data and Strobe

2 unit load
Control Inputs
<2 unit load
Data
8 TTL compatible inputs
Validity
Data must be valid 2.0 ns min., prior to Strobe and remain valid for 1.5 ns after data Strobed

## Update Rate

65 MHz maximum

## Strobe Input

Data entered on positive-going edge (Timing Reference)
Pulse width
5 ns minimum
Rise and Fall Time (all inputs)
$\leq 10$ ns ( $10 \%$ to $90 \%$ )
Setup (Reference Black to Blanking)
Input open: Standard 71 mV (10 IRE Units)
Input to -5.0 V : 142 mV (20 IRE Units)
Input to Ground: 0 mV (0 IRE Units)
Composite Sync Level
Logic "0" on Sync (and Blanking) input
simultaneously resets input register to 00000000
and drives output to -1.064 V
Composite Blanking Level
Logic " 0 " on Blanking input simultaneously resets
input register and drives the output to -0.778 V
Reference White Level
Logic " 0 " on Ref. White input simultaneously sets input register to 11111111 and drives output to -0.064V
10\% Overbright Level
Logic " 0 " on input raises output level by 0.064 V .
Logic "0" on Ref. White and 10\% Overbright drives output to OV.
Glitch Adjust
Input Impedance
$7.5 \mathrm{~K} \Omega$
Control Characteristics
$50 \mathrm{pV}-\mathrm{s} / \mathrm{N}$ applied to Glitch Adjust pin

## POWER SUPPLY REQUIREMENTS

## Power Dissipation

0.95 watts typical, 1.15 watt maximum

Power Supply Required
+5.0V +5\% @ 30 mA max. 50 mV p-p ripple max.

- 5.0 V @ 200 mA maximum 5 mV p-p ripple max.
( -4.75 V to -5.5 V operating range)
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range (Ambient)
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $+40^{\circ} \mathrm{C}$
Mechanical Dimensions
0.78 " $\times 1.30 " \times 0.3$ "
(20.07 X $33.14 \times 7.82 \mathrm{~mm}$ )

24-pin double DIP
Shielding
Steel foil

## Theory of Operation

Eight bit TTL digital data presented to the AH8308T on the data inputs is latched into the input register at the rising edge of the STROBE pulse applied to the STROBE control input. The outputs of the register drive high speed switches that steer current into a summing network with an output impedance of $75 \Omega$, developing a $1 \mathrm{Vp}-\mathrm{p}$ signal directly. Due to the extremely small differential delay among the eight data channels, the code switching output glitches are invisible even on the best video monitor.
Digital control inputs for REFERENCE WHITE, SYNC, BLANKING and $10 \%$ OVERBRIGHT are provided. A logic 0 on the REF. WHITE inputs sets the registers and drives the output to -0.064 V . Logic 0 on $10 \%$ OVERBRIGHT increases the output by 0.064 V . Used in conjunction with REF. WHITE, all registers are set and the output is driven to OV. Logic 0 on the BLANKING and SYNC (plus BLANKING) inputs resets the registers and drives the output to -0.778 V and -1.064 V respectively. Combinations of BLANKING/SYNC and REF. WHITE/10\% OVERBRIGHT should be avoided. While no damage will result, active levels on both control lines may cause an indeterminate output.
The condition of the SETUP line determines the relative levels between Reference Black and the Blanking level - left open, the standard 71 mV ( 10 IRE units) is produced; tied to $-5.0 \mathrm{~V}, 142 \mathrm{mV}$ (20 IRE units) is produced; tied
to ground, 0 mV (0 IRE units) is produced. (See Chart on last page).
Please refer to the Timing Diagram, Applications Considerations and Video System Display Application sections for examples of operation.

## ENGINEER'S NOTEBOOK

## Power Supply Requirements

The AH8308T requires both $+5 \mathrm{~V} \pm 5 \%$ and $-5 \mathrm{~V}(-4.75 \mathrm{~V}$ to -5.5 V operating range) power supplies. The output amplitudes specified are nominal values based on a -5.0 V supply and will change in direct proportion to the -5 V supply voltage.
The glitch area will also vary as a function of the -5 V supply voltage. The factory trim is normally carried out at -5.0 V and may be done at another voltage if specified when ordering.
If other than -5.0 V is used with a unit trimmed for -5.0 V operation, provisions should be made on the PC board for a $10 \mathrm{~K} \Omega$ potentiometer connected to the GLITCH ADJUST terminal as shown (in Figure 2). The pot should be adjusted to reduce the glitch area to a minimum.


Figure 2. Glitch Adjust.


Figure 3. Glitch Area at Major Code Transition.

## Grounding

There are five ground pins all tied together internally and to the case of the AH8308T.

## Current Output

The AH8308T can be used as a current output device by connecting the inverting input of an op-amp to the AH8308T output and then selecting the appropriate op-amp feedback resistor for the voltage output required by the application.


Figure 4. Full Scale Step Rise Time.

## Timing

Figure 5 shows a detailed diagram depicting the timing required to generate composite video for the case of a full-scale (black to white) transition. 10\% OVERBRIGHT, BLANKING PEDESTAL and SYNC are generated after the transition to illustrate their timing.

## Cursor

To produce a cursor on a display, both 10\% OVERBRIGHT and REF. WHITE should be brought to a logic " 0 " which will drive the output to 0 V . If $10 \%$ OVERBRIGHT only is brought to logic " 0 ", the output of the AH8308T will increase +0.064 V above its prior output.

## APPLICATION CONSIDERATIONS

## Color Graphic Systems

The AH8308T is ideally suited for both monochrome composite video and RGB color applications. Normally only one channel (the green) carries the BLANKING and SYNC signals. For use in the other channels of such
systems, the BLANKING and SYNC line of the AH8308T can be disabled by tying them to logic "1".
While using a 4 - or 5 -bit DAC on each color channel may give the display system designer an acceptable color palette, the low resolution of these DACs may not be sufficient to allow anti-aliasing techniques to be employed successfully. One advantage to using an 8 -bit DAC may not be readily apparent - one that is especially important in CAD/CAM type applications where single lines are drawn on the display. When a diagonal line is drawn on the screen, "bunching" of the pixels causes a stair-stepping effect as opposed to a smooth, straight line. Increased display resolution helps to reduce the size of the "jaggies" and smooth out the line, but cannot eliminate them. Various digital-differential analysis (DDA) procedures have been used to attempt to solve this problem and minimize its effect. By using a higher Z-axis resolution ( 8 bits versus 4 or 5), further improvements in the smoothing process are realized with these DDA procedures due to the increased control over the line intensity.

## Broadcast Usage

The AH8308T is normally used in Digital Display applications. It can, however, be used for broadcast applications in which case additional circuitry is required in order to achieve full compliance with EIA Industrial Electronics Tentative Standard No. 1 (part of RS170A). This Standard details the exact waveform and timing characteristics of the broadcast composite video signal. The additional circuitry would, at a minimum, provide sinx/x correction and bandwidth filtering. In addition, the set-up on the AH8308T should be changed to 7.5 IRE units by placing a nominal $560 \Omega$ resistor between the SETUP terminal and ground.


Figure 5. Typical Timing Diagram.


Figure 6. Typical AH8308T Application.

## Video Display System Application

An example of a video display subsystem using the AH8308T is shown in block diagram form in Figure 6. Only the portion of the subsystem directly involving the AH8308T is shown. The memory and monitor circuits are not discussed in any detail, since system requirements vary. It is assumed that eight bits of digital data are available from some TTL source for use by the AH8308T and that a monitor or $\sin x / x$ filter is being driven by the AH8308T. If fewer than eight bits are used, tie the unused LSBs to logic 0. Any AH8308T control signals not required in a particular system application should be tied to logic 1 to prevent erroneous operation. The timing relationships of the various signals are shown in Figure 5.
Timing for the overall display subsystem is derived from the system Master Clock. Through a suitable divider chain, a frequency of 2.04 MHz is generated and applied to the clock input of the 3262A Sync Generator IC or equivalent (see Note*). From this clock signal, the 3262A generates the Sync and Blanking signals. The Composite Sync and Blanking Signals are applied to the corresponding control inputs on the AH8308T. The Sync and Blanking signals are also sent to the Memory System for use by the Memory Address logic if required. The 3262A also produces a timing signal which is valid during the Vertical Interval at the start of the odd Field for interlaced systems. This signal may be used to control Memory addressing.
In most systems the "setup" level is left at one particular value such as the Standard 71 mV . In rare cases where application requires, the setup level can be controlled digitally by means of a DAC with either current or voltage output. If the SETUP pin is driven as a voltage point, values from -1 to -5 V will produce 0 to 10 IRE units respectively. If a current is injected into the SETUP pin, approximately 11 mA is needed to produce 0 IRE units.

[^10]The composite video output from the AH8308T is connected directly to the ( $75 \Omega$ terminated) video input of the monitor by a length of a coax cable. The length of the cable should be limited to prevent the dc resistance of the cable run from exceeding 7.58. This is necessary to limit the amount the signal is attenuated by the cable to approximately $10 \%$ or less. If an amplifier is used between the AH8308T output and the monitor, longer lengths of cable can be allowed.

## The Video Signal

The EIA Standards RS170A and RS343A define the video signal in detail and refer to the IRE units for measuring the various components of the signal. The total peak amplitude of the standard video signal, from the maximum white level to the sync level is 140 IRE units. The standards further define the video signal as 1 Vp -p; therefore, 1 IRE unit is 7.14 mV . The maximum white level is the most positive amplitude of the video signal, the sync the most negative; this is referred to as a black-negative (as opposed to a black-positive) video signal. The illustration in Figure 7 depicts the composite video signal produced by the AH8308T.
Because the output of the AH8308T must accommodate 10\% Overbright control, Reference White, Reference Black, Blanking and Sync are shifted from their standard absolute levels by approximately -9 IRE units. The relative number of IRE units between each of these levels is compatible with the EIA Standards. As the definitions are given for the various levels in the AH8308T composite signal, it should be remembered that they differ from the standard RS170/RS343 absolute levels by 9 IRE units ( 0.064 V ).
The most positive amplitude level is the $10 \%$ Overbright. As the name applies, this level is higher than the whitest level of the picture information by $10 \%$ of the gray scale or $0.064 \mathrm{~V}(10 \%$ of 0.643 V$)$. This level is most often used to define a cursor on a display screen. By making the cursor $10 \%$ brighter than the remainder of the picture, it can be located easily. REFERENCE WHITE is the most positive amplitude of the normal picture information, while REFERENCE BLACK is the most negative. The span of signal from REFERENCE WHITE to REFERENCE BLACK is 90 IRE units of


Figure 7. The Composite Video Signal (Not to Scale).
0.643 V . This span is divided into 256 discrete levels (gray scale) due to the 8 -bit resolution of the AH8308T.
The BLANKING LEVEL is 10 IRE units below REFERENCE BLACK in a standard video signal and is the voltage level that will completely cut off the display screen. The AH8308T provides a means of varying the relative distance between the REFERENCE BLACK and BLANKING LEVEL, referred to as the setup. The SETUP pin on the AH8308T can be programmed to provide a set-up of 0 mV ., 71 mV or 142 mV ( 0 IRE, 10 IRE or 20 IRE units). Left open, the standard setup of 71 mV ( 10 IRE units) is produced; tied to $-5 \mathrm{~V}, 142 \mathrm{mV}$ (20 IRE units) is produced; tied to ground, 0 mV ( 0 IRE units is produced. The BLANKING LEVEL is also referred to as the PEDESTAL, BACK PORCH or FRONT PORCH.
The most negative amplitude of video signal is the SYNC level at - 40 IRE ( 0.286 V ) below the BLANKING LEVEL. Relative to $10 \%$ OVERBRIGHT, this level is -1.064 V . The SYNC level is used to synchronize the scanning circuits in the display system. It is this SYNC level (along with BLANKING) produced directly by the AH8308T that provides the composite video signal.
All of the above definitions apply to both monochrome and color (RED/GREEN/BLUE)
display systems. In color systems, the composite signal is produced on only one channel (usually the green). The other two DACs producing Red and Blue video have the SYNC and BLANKING lines disabled by tying them to logic 1.


## Available Options

The AH8308T is normally supplied with eight DATA INPUTS, STROBE, REFERENCE WHITE, 10\% OVERBRIGHT, BLANKING and SYNC control inputs, capable of driving a $75 \Omega$ terminated monitor. We invite inquiries on modifications such as dual monitor capability, REFERENCE BLACK CONTROL and other custom requirements.


## CONTROL SIGNALS

| SIGNAL | ACTIVE <br> LOGIC LEVEL | RESULTANT <br> OUTPUT |
| :---: | :---: | :---: |
| DATA, BIT 1-BIT 8 | 00000000 | -0.707 V (REF. BLK) |
| STROBE | 11111111 | -0.064 V (REF. WHT) |
| REF. WHITE | $\mathbf{F}$ | DATA LOADED |
| COMP. BLANK | 0 | -0.064 V |
| 10\% OVERBRIGHT | 0 | -0.778 V |
| $10 \%$ + REF. WHITE | 0 | Vout +0.064 V |
| COMP. SYNC | 0 | 0 V |
| SETUP | OPEN | -1.064 V |
|  | -5.0 V | $-142 \mathrm{mV}(10 \mathrm{mV}$ (20 IRE) |
|  | GND | $0 \mathrm{mV}(0$ IRE) |

## ORDERING GUIDE

65 MHz 8-Bit TTL Video DAC...

Specify AH8308T

150 MHz 8-Bit ECL Video DAC
(Please consult factory or representative for Data Sheet)

Specify AH3808E


## AH8308TC

## 8-Bit RGB Video DIA Converter

## Description

The AH8308TC is a third generation triple (RGB) 8 -bit video DAC that provides designers of color display systems with a complete, selfcontained, TTL-compatible RGB composite video subsystem in a 40-pin DIP. The AH8308TC features an advanced design that provides low power (3.0W maximum), high reliability, and low cost. The small size of the AH8308TC reduces the PC board area by $30 \%$ or more, and the power dissipation by up to $25 \%$ over the equivalent function implemented with single channel DACs.
Each of three video DACs within the AH8308TC accepts independent 8 -bit TTL data at an update rate of up to 100 MHz . Controls are provided for common Blanking and Strobe, and Sync (GREEN channel only). Blanking is synchronous with Strobe when activated, and asynchronous when deactivated. The video output of each channel is RS330/343 compatible, providing a $75 \Omega$ source impedance and a 1 V p-p output signal.

The AH8308TC is a cost-effective solution to the requirement for a triple 8-bit composite video DAC in applications ranging from engineering workstations to CAD/CAM systems, medical imaging, and other high-end graphics systems.

## Features

## Three 8-bit Video DACs in one

 40-pin DIP- 100 MHz Data Update Rate

TTL Compatible
Synchronous Blanking
RS330/RS343 Composite Video Output Compatible
Low Power Dissipation 2.5W

## Applications

\author{

- Color Graphic Workstations <br> CAD/CAM Systems <br> Medical Imaging Systems <br> "Quick Look" Display Systems <br> - Image Processing Systems
}


Figure 1. AH8308TC Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted.)

## OUTPUT CHARACTERISTICS (Each Channel)

## Composite Output

(GREEN Channel only)
0 V to $-1.00 \mathrm{~V}, \pm 3 \%$ of full scale into $75 \Omega$
termination
Gray Scale Output (all Channels)
0 V to $-0.643 \mathrm{~V}, \pm 3 \%$ of Gray Scale into $75 \Omega$ termination
Recommended Load Impedance
$75 \Omega, \pm 5 \%$; dc to 50 MHz
Source (Thevenin) Impedance
$75 \Omega, \pm 5 \%$; dc to 50 MHz
LSB Size
2.5 mV , nominal

Rise and Fall Time
3 ns typical, 4 ns maximum; 10\% to $90 \%$
Full Step Settling Time
7.5 ns typical to 1 LSB ( $0.4 \%$ )

Glitch Settling Time
5 ns to <1 LSB for worst-case transition
Glitch Area
$80 \mathrm{pV} \cdot \mathrm{s}$ typical
Cable Drive Capacity
$75 \Omega$ characteristic impedance; to avoid appreciable signal loss total length should have no more than $7.5 \Omega$ dc resistance
Composite Sync Level (GREEN Channel only) -1.00 V absolute, -0.286 V ( -40 IRE Units) relative to Blanking level
Composite Blanking Level

- 0.714V

TRANSFER CHARACTERISTICS
(Each Channel)

## Resolution

8 bits, 256 Gray Scale levels;
2.5 mV per step, nominal

Coding
Binary

## Reference White Level

11111111 produces OV absolute; + 0.714V (100 IRE Units) relative to Blanking level
Reference Black Level
00000000 produces -0.643 V absolute;
+0.071 V (10 IRE Units) relative to Blanking level
Differential Linearity
$\pm 1 / 2$ LSB maximum
Monotonicity
Guaranteed
Offset (Output with 11111111 Input)
$\pm 1 / 2$ LSB maximum, $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$
Propagation Delay
7 ns typical, strobe to output; $50 \%$ points

BLANKING Input Speed
7 ns typical, 10 ns maximum to settle to $10 \%$ of final value after strobe high-to-low transition
SYNC Input Speed
7 ns typical, 10 ns maximum to settle to $10 \%$ of final value
Channel-to-Channel Crosstalk
$1 / 2$ LSB maximum, dc component
100 pV • s maximum, ac component

```
INPUT CHARACTERISTICS (Each Channel)
Logic Levels (all inputs)
Standard TTL levels
Logic \(0=0 \mathrm{~V}\) to 0.4 V
Logic \(1=2.4 \mathrm{~V}\) to 5.0 V
Loading:
Data and Strobe
2 unit load
Control Inputs
<2 unit load
Data:
Validity
Data must be valid 2.0 ns prior to Strobe and remain valid for 1.5 ns after data Strobe
Update Rate
100 MHz maximum
```


## COMMON CONTROL INPUTS

Strobe Input
Data entered on negative-going edge (Timing Reference) simultaneously on all three channels

## Skew

5 ns maximum variation between channels for data latched into input registers
Pulse Width
5.0 ns minimum

Rise and Fall Time
$<10$ ns ( $10 \%$ to $90 \%$ )
Composite Blanking
Logic 1 on Blanking input simultaneously resets all input registers to 00000000 and drives all channel outputs to -0.714 V . Blanking is synchronous with falling edge of next STROBE pulse; after logic 1 to 0 transition, all channel outputs remain at the Blanking level until the next STROBE pulse, at which time data present at DAC inputs is loaded into the DAC.

## Composite Sync

Logic 1 on SYNC input (after BLANKING is activated) drives the GREEN channel output further negative to -1.00 V . SYNC must not be activated without BLANKING first being active. When SYNC is released (returned to logic 0 ), all channel outputs remain at the Blanking level until the next STROBE pulse, at which time data present at DAC inputs is loaded into the DACs (assuming BLANKING control is inactive).

## Glitch Adjust:

Input Impedance
$7.5 \mathrm{k} \Omega$
Control Characteristics
$75 \mathrm{pV} \cdot \mathrm{s} / \mathrm{V}$ applied to Glitch Adjust pin
POWER SUPPLY REQUIREMENTS
$+5 \mathrm{~V}, \pm 5 \%$
100 mA maximum; 50 mV p-p ripple maximum
$-5.0 \mathrm{~V}$
500 mA maximum; 5 mV p-p ripple maximum
( -4.75 V to -5.5 V operating range)
Power Dissipation
2.5W typical, 3.0W maximum

## ENVIRONMENTAL AND MECHANICAL

Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, noncondensing up to $+40^{\circ} \mathrm{C}$
Mechanical Dimensions
2.0 " $\times 1.0$ " $\times 0.3$ "; 40 -pin triple width DIP

## OPERATION

Each of the three DAC inputs is presented with an 8-bit data word corresponding to the intensity required for each CRT electron gun. After allowing for the data setup time, a high-to-low transition on the STROBE input causes the three 8 -bit data words to be latched into the DACs. After the DAC propagation delay, each video output produces a voltage corresponding to the data loaded in its DAC.
During the blanking interval, the BLANKING control line is activated by a logic 1. At the next STROBE pulse, the three DAC input registers are reset to 00000000 and the DAC outputs are driven to the blanking level.
When BLANKING (and SYNC) are deactivated at the end of the retrace interval, all three DAC outputs remain at the blanking level until the next STROBE pulse. Then data at the DAC inputs are latched into their respective input registers and subsequently appear at the DAC outputs after the DAC propagation delay.

## USING THE AH8308TC

## Power Supply Requirements

The AH8308TC requires both +5 V and -5 V power supplies. The specified output amplitudes are nominal values based on a -5.0 V supply and change in direct proportion to the -5.0 V supply voltage.

The glitch area also varies as a function of the -5 V supply voltage. The factory trim is normally carried out at -5.0 V and may be done at another voltage if specified when ordering.
If other than -5.0 V is used with a unit (measured directly at pin 29) trimmed for -5.0 V operation, provisions should be made on the PC board for a $10 \mathrm{k} \Omega$ potentiometer connected to the GLITCH ADJUST pin (pin 27) as shown in Figure 2. The pot should be adjusted to reduce the glitch area to a minimum.

## Grounding

There are seven (7) ground pins tied together internally via the ground plane. To reduce ground loops, each ground pin should be used for the function for which it is labelled.


Figure 2. Glitch Adjust



Figure 3. AH8308TC Typical Timing Diagram.


## ORDERING GUIDE

100 MHz , RGB 8-bit video DAC Specify AH8308TC


ANALOGO.

## AH8404TM/TC

Triple 4-Bit Video D/A Converter

## Description

The AH8404s are a significant advance in video D/A converters that provide designers of low-to-mediumcost personal computer-based color display systems with a complete, self-contained, TTL compatible, composite video subsystem in a 24 -pin DIP. The advanced design of the AH8404s provides low, 0.8 W power dissipation from a single +5 V supply, including color look-up table memory! Offered as either an RGB 4-bit D/A only, or with the integral color look-up table memory, both configurations of the AH8404s provide high reliability, small size, and low cost.
The AH8404TM color-mapped video D/A converter is designed for the color graphic system where space is at a premium. Both the functions of triple (RGB) video D/A converter and color look-up table memory are provided within a single package. Data can be written into the internal 32 word RAM (one for each color channel) such that 32 colors can be defined out of a possible 4096 at any given time. During the display (Read) interval, any of these 32 colors can be addressed from a 5 -bit bus. Separate Sync, Blanking (synchronous) and D/A Strobe control inputs are provided.


Figure 1. AH8404TM/TC Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## OUTPUT CHARACTERISTICS (Each Channel) <br> Composite Output <br> (Green Channel Only) <br> 0.00 V to $1.000 \mathrm{~V}, \pm 3 \%$ of Full Scale (assumes load is $75 \Omega, \pm 5 \%$ and +5.0 V power supply voltage; measured at load) <br> Gray Scale Output <br> 0.357 V to $1.000 \mathrm{~V}, \pm 3 \%$ of Full Scale (assumes <br> load is $75 \Omega \pm 0.5 \%$, and +5.0 V power supply <br> voltage; measured at load) <br> Recommended Load Impedance <br> $75 \Omega, \pm 5 \%$; dc to 25 MHz <br> Source (Thevenin) Impedance <br> $75 \Omega, \pm 3 \%$; dc to 25 MHz <br> LSB Size <br> 42.9 mV nominal <br> Full Scale Step Settling Time <br> 20 ns typical, 30 ns maximum to $1 / 2$ LSB after propagation delay <br> Glitch <br> Total Glitch Energy less than $300 \mathrm{pV} \cdot \mathrm{s}$ at major code transition (0111 to 1000 or vice versa) <br> Cable Drive Capability <br> $75 \Omega$ characteristic impedance; to avoid <br> appreciable signal losses total length should have <br> no more than $7.5 \Omega$ dc resistance <br> RGB Blanking Level <br> 0.286 V with 71 mV (10 IRE Unit) set-up <br> Sync Level <br> 0.000 V ; offset is 2 mV maximum, from $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$

## TRANSFER CHARACTERISTICS (Each Channel)

Resolution
4 bits, 16 Gray Scale levels; 42.9 mV per step
Reference White Level
1111 produces 1.000 V , 100 IRE Units relative to
Blanking level
Reference Black Level
0000 produces 0.357 V , 10 IRE Units relative to
Blanking level
Differential Nonlinearity
$\pm 1 / 2$ LSB, maximum
Monotonicity
Guaranteed
Transfer Gain (Slope) Tempco
$\pm 0.1 \%$ FSR/ ${ }^{\circ} \mathrm{C}$
RGB Blanking Input Delay
60 ns typical to $10 \%$ of final value.
Sync Input Delay
60 ns typical to $10 \%$ of final value

## INPUT CHARACTERISTICS

Logic Levels (all inputs)
Standard TTL levels
Logic $1>2.4 \mathrm{~V}$
Logic $0<0.4 \mathrm{~V}$

Loading:<br>Data and Strobe<br>2 Unit Load<br>Control Inputs<br>2 Unit Load<br>Address (TM Only)<br>2 Unit Load<br>Coding<br>Binary<br>Address Coding (TM Only) Binary<br>Data Update Rate<br>25.0 MHz maximum (TC), 20.0 MHz maximum (TM)<br>Memory Size (TM Only)<br>32 word by 4-bit (each RAM/channel)<br>Control Inputs<br>DAC Strobe<br>Data entered into all three DAC channels simultaneously on negative-going edge<br>Rise and Fall Time<br>$<10$ ns ( $10 \%$ to $90 \%$ )<br>DAC Propagation Delay<br>60 ns maximum, STROBE to output $10 \%$ point<br>Blanking Rise and Fall Time<br>$<10 \mathrm{~ns}$ ( $10 \%$ to $90 \%$ )

## RGB Blanking

Logic 1 on RGB Blanking input resets all DACs to 0000 at next STROBE pulse and drives the outputs of all channels to 0.286 V

## Sync

Logic 1 on RGB Blanking and Sync inputs resets all DAC inputs to 0000, drives the RED and BLUE outputs to 0.286 V and GREEN output to 0.000 V , $-0.286 \mathrm{~V}(-40$ IRE Units) relative to Blanking level

## LOOK-UP TABLE MEMORY CONTROL (AH8404TM)

## Read/Write

Logic 0 selects Read operation; logic 1 selects Write operation. DAC outputs retain previous Read value until STROBE input is applied; STROBE applied during Write operation causes Reference Black output level from all DACs

## Address - 5 bits (A0 to A4)

Determines location in memory for Read or Write operation; used as Address input to load RAM arrays in Write mode and as Look-up inputs in Read (Display) mode
Data - 4 bits (D0 to D3)
Data to be loaded into RAM array(s) by CHIP SELECT input(s) during Write operation
Chip Select - CSR, CSG, CSB
CHIP SELECT for each channel (RED, GREEN, and BLUE); logic 0 selects RAM channel for Read or Write operation; when disabled, RAM data output is all 0's to DAC inputs. DAC output of deselected channels retain last Read level if no

STROBE is applied; otherwise output falls to Reference Black level. Normally only one input at a time is enabled (selected) to write data to its corresponding RAM. All inputs are enabled to read data during display. These may be held at logic 0 throughout the read cycle

```
DYNAMIC CHARACTERISTICS
Data Setup Time
30 ns minimum (TM),0 ns min. (TC)
Data Hold Time
20 ns minimum (TM), 30 ns min. (TC)
Width of Write Pulse
25 ns minimum
Address Before Write
30 ns minimum
Address Hold Time
20 ns minimum
Address Access Time
(after valid address)
4 8 ~ n s ~ m a x i m u m
Chip Select Access
4 0 \mathrm { ns } \text { maximum}
Chip Select Disable
35 ns maximum
```

POWER REQUIREMENTS
$+5.0 \mathrm{~V}, \pm 5 \%$
120 mA maximum (TC); 160 mA maximum (TM),
50 mV p-p ripple maximum
Power Dissipation
0.5W typical; 0.6W maximum (TC)
0.6W typical; 0.8W maximum (TM)
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ ambient
Storage Temperature
$-25^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, noncondensing up to $40^{\circ} \mathrm{C}$
Dimensions
1.00 " x $1.30^{\prime \prime} \times 0.3$ "maximum
( $25 \times 33 \times 7 \mathrm{~mm}$ )
24-pin triple width DIP
Packaging
Ceramic lid epoxied to substrate
Handling
CMOS precautions required

## Operation

The AH8404TM consists of two major functional blocks (1) a memory organized as three 32 -word by 4 -bit blocks, one for each color channel, with common data, Read/Write control and address inputs, separate chip select inputs and data outputs, and (2) a triple 4-bit D/A converter with common Sync, Blanking, and Strobe control inputs. Data flow is
always from the output of the memory to the input of the D/A converter.
During a Write operation, data for the look-up table RAM is presented to the DATA inputs. The CHIP SELECT line is brought low to enable the color channel RAM that is to receive the data. The READWRITE line is pulsed, and the data is written into the RAM location defined by the five ADDRESS inputs. The CHIP SELECT line is then brought high to disable that channel. The process can be repeated for other addresses and/or color channels.
During a Read (display) cycle, all three CHIP SELECT lines are brought low to enable all channels, and the RAM address for the color to be displayed is presented to the ADDRESS inputs. After a 48 ns maximum propagation delay through the memory, the data from the addressed RAM location appears at the output of the memory. The D/A STROBE line is then pulsed to latch the data into the D/A input register. After a propagation delay through the D/A converter, the corresponding analog output voltages appear at the three D/A outputs.
The AH8404TC D/A only (and the D/A portion of the AH8404TM) accepts a 4-bit data word for each of the three video channels (RED, GREEN, and BLUE). The data is presented to the DATA inputs and held for the duration of the setup time. The STROBE is then pulsed to load the data into the three DAC registers. During the blanking interval, the BLANKING control line is activated by a logic 1 . The next STROBE pulse resets the three input registers to 0000 and drives the D/A outputs to the blanking level. When the SYNC line is activated, the next STROBE pulse drives the GREEN channel output to the sync level. At the end of the blanking/sync interval, the SYNC and BLANKING controls are released (returned to a logic 0 ). At the next STROBE to the D/A, the data at the DATA inputs to the D/A are loaded into the input registers and subsequently appear at the D/A outputs after the D/A propagation delay.

## ORDERING GUIDE

20 MHz , RGB 4-bit D/A with 32-word look-up table memory. ..Specify AH8404TM 25 MHz , RGB 4-bit D/A.........Specify AH8404TC


Figure 2. Typical Timing AH8404TM/TC.

| MECHANICAL |
| :---: |
|  |
| PINS ON $0.1^{\circ}(2.5 \mathrm{~mm})$ CENTERS |



## Description

The Analogic MP1480S is a unique 12-bit digital-to-analog current loop converter incorporating a proprietary Analogic current valve. It consists of an input register, a high-accuracy digital-to-analog converter (DAC), followed by a voltage-to-current loop conversion circuit (Fig. 1). Together, these building blocks act as a digitallycontrolled current valve, for standard 4 to 20 mA or other customerselectable current ranges. For maximum flexibility, the MP1480S offers a choice of computercompatible CMOS or low-power Schottky input registers and the option of voltage output. This high speed, accurate and versatile current transmitter has been specifically designed for application in industrial process control systems and satisfies the Instrument Society of American Standard ISA-S50.1, "Compatibility of Analog Signals for Industrial Process Control'".

## MP1480S

High Performance, 12-Bit, Current Loop D/A Converter


## Features

- User-Selectable Current Loop or Voltage Output
- Current Range: $\mathbf{4}$ to $\mathbf{2 0} \mathrm{mA}$ Standard; ranges from 0 to 50 mA available
- ISA Type 4 Transmitter, Class L and Class U Operation
- Built-in Digital Latching Register
- Overvoltage and Open-Circuit Protection in Current Loop
- Short-Circuit Protection in Voltage Output
- 12-Bit Resolution
- Multiplying Capability in Two Quadrants
- High Accuracy and Linearity: 0.021\% FSR
- Settling Time: $10 \mu$ s to $1 / 2$ LSB
- Choice of LS TTL or CMOS Inputs
- Choice of BINARY or BCD coding
- Low Profile: Metal Case


## Applications

- Industrial Control Systems
- Remote Data Acquisition Systems
- Instrumentation Systems
- Computer-Controlled Current Sources
- Automatic Relay Testing

Figure 1. MP1480S Current Loop D/A Converter Functional Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG OUTPUTS

Current loop or voltage - programmable by customer.
Current Mode - ISA type 4, non-isolated transmitter, Class L operation with $>+12 \mathrm{Vdc}$ loop supply; Class $U$ operation with $>+20 \mathrm{Vdc}$ loop supply. See Note 1
Voltage Mode - Unipolar; 0 to +5 V or 0 to +10 V ; Bipolar: $\pm 5 \mathrm{~V}$ or $\pm 10 \mathrm{~V}$; programmable by customer. See Note 2.

ACCURACY (@+25 ${ }^{\circ}$ )
Resolution
12 bits

## Relative Accuracy

0.012\% FSR (0.05\% for BCD)

Noise ( $\mathbf{1 0 ~ H z}$ to 100 kHz)
Current Mode $-<2 \mu \mathrm{Arms}$ Voltage Mode - < $0.01 \%$ FSR rms

## OUTPUT CHARACTERISTICS

Output Impedance
Current Mode - Current Source
Voltage Mode - < $0.3 \Omega$ @ dc
Load Current
Current Mode - See Note 1
Voltage Mode - 5 mA .
Short circuit IImit $=20 \mathrm{~mA}$
Receiver Voltage
Current Mode - 6V min., 33V max. See Note 1 Output Protection
Current Mode - Protected against 120 Vac @ 60 Hz . Open-circuit protected

STABILITY

## Offset Drift

Current Mode $-0.6 \mu \mathrm{~A} /{ }^{\circ} \mathrm{C}$
Voltage Mode - $10 \mathrm{ppm} / /^{\circ} \mathrm{C}$ max.
Gain Drift
Current Mode $-1.0 \mu \mathrm{~A} /{ }^{\circ} \mathrm{C}$
Voltage Mode - $20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Supply Sensitivity
10 ppm FSR/\% change in supply voltage
DIGITAL INPUTS
Logic Compatibility
Standard CMOS logic levels (C Version)
Low Power Schottky TTL (T Version)
Data Set-up Time
10 ns, minimum
Clock
Positive-edge triggered
Clear
Active low, asynchronous with clock

## SPEED

Settling time to $1 / 2$ LSB
$10 \mu \mathrm{~s}$, max. to $1 / 2$ LSB; $0.5 \mu$ s to $10 \%$
Slew Rate
Current Mode $-2 \mathrm{~mA} / \mathrm{s}$, min.
Voltage Mode - $2 \mathrm{~V} / \mu \mathrm{s}$, min.
REFERENCE VOLTAGE INPUT
Input Impedance
$20 \mathrm{k} \Omega \pm 10 \%$ and $0.01 \mu \mathrm{~F}$
Voltage
Current Mode -+2.5 V and -1.25 V See Note 3
Voltage Mode -+10 V

## MULTIPLYING MODE PERFORMANCE Quadrants <br> 2

Accuracy V.REF (+1 to $\mathbf{+ 1 0 \mathrm { V } \text { ) } ) ~}$
0.1\%

Reference Feedthrough at $1 \mathbf{k H z}$ $<1 / 2$ LSB
Output Slew Rate Referred to Reference
Current Mode - $1 \mathrm{~mA} / \mathrm{hs}^{\mathrm{s}}$
Voltage Mode - $2 \mathrm{~V} / \mu \mathrm{s}$
Output Settling Time from Reference
$10 \mu$ s to stated accuracy

## MONOTONICITY

Guaranteed over full range

## POWER SUPPLY REQUIREMENT

$\pm 15 \mathrm{Vdc} \pm 3 \%$
25 mA
+5 Vdc $\pm 5 \%$
25 mA
ENVIRONMENTAL AND MECHANICAL
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Storage Temperature
$-55^{\circ}$ to $+150^{\circ} \mathrm{C}$
Mechanical Dimensions
$2 \times 2 \times 0.39$ inches ( $50.8 \times 50.8 \times 9.9 \mathrm{~mm}$ )
Shielding
EMI: 5 sides, RFI: 6 sides

## PURCHASE OPTIONS

Input Register
Low Power Schottky or CMOS
Input Code
Binary or 3-decade BCD

Note 1: The MP1480A output does not "generate" current, but acts as a valve for an externally applied series voltage and "receiver" load. A standard 4-20 mA current is thus accepted independent of supply variation, transmission line resistance or induced noise. Inputs to the unit, at the current loop terminals, must be within the $6-33 \mathrm{~V}$ range. These terminals are protected against voltages in excess of 33 V by an HV Protect circuit.
Note 2: Voltage mode and current mode cannot be used simultaneously.
Note 3: In the current mode, the +9.95 V reference sets the span of current at 16 mA and the -4.975 V sets the baseline at 4 mA , giving a range of 4 to 20 mA . The range may be modified slightly by adjusting the reference voltage values. To alter the span, the value of the sense resistor must be changed.

## Applications Concepts

When analog signals are sent over lines characterized by unpredictable impedance and induced noise, controlled current sources often provide the most reliable transmission. The MP1480S acts as a digitally controlled valve operating in series with the customer's remote current receiver and voltage source. The unit accepts a level of current determined solely by the 12-bit digital input command and thus enables microprocessors or other digital sources to communicate with standard analog loops, including the popular 4 to 20 mA type.

## OPERATION <br> Current Loop Mode

The standard current range available in the MP1480S is $4-20 \mathrm{~mA}$. Apply supply voltages and the +9.95 V and -4.975 V reference
voltages to obtain the desired control current. A 3-terminal voltage reference and op amp circuit are recommended for the reference voltages. Make jumper connections as shown in Fig. 2. Select a current loop supply voltage, $\mathrm{V}_{\mathrm{S}}$, such that the difference between $\mathrm{V}_{\mathrm{S}}$ and the voltage drop across the external loop resistance, $R_{L}$, lies in the range $6-32 \mathrm{~V}$. The relationship between $V_{S}$ and $R_{L}$ is given by,

$$
\left(20 R_{L}+6\right) \leq V_{S} \leq\left(4 R_{L}+32\right)
$$

where, $\mathrm{R}_{\mathrm{L}}$ is in K -ohms.
It can be seen from this relationship that the maximum permitted theoretical value of $R_{L}$ is $1.625 \mathrm{k} \Omega$. The MP1480S is protected against output terminal voltages up to 120 Vac. Operation outside the 6 to 32 V range will not be within specifications. See Note 3 , under Specifications, for other current ranges.

## Unipolar and Bipolar Output Voltage Modes

Determine output range required. Apply supply voltages and +10 V reference voltage and make jumper connections(s) as shown in Fig. 3.

## CMOS Operation (MP1480S-C)

Make jumper connection between the TTLCMOS control pin and +V.DIG. terminal and connect + V.DIG. to the CMOS supply voltage ( +5 V to +15 V ).


Figure 2. MP1480S Current Output Connections and Zero and Gain Adjustments.

## TTL Operation (MP1480S-T)

No external connection is required at the TTLCMOS terminal for this mode of operation.


Figure 3. MP1480S Voltage Output Connections and Zero and Gain Adjustments.

NOTES ON VOLTAGE OUTPUT CONNECTIONS:

1. For Bipolar outputs, connect R3 OUT to NULL.
2. For 0 to +5 V , connect R2 to NULL.
3. For 0 to $+5 \mathrm{~V}, 0$ to +10 V and $\pm 5 \mathrm{~V}$ ranges, connect R1 to V.OUT
4. For $\pm 10 \mathrm{~V}$, connect R2 to V.OUT

* See "Digital Inputs" Section under Specifications
** See Notes on Voltage Output Connections


Figure 4. MP1480S Outline Drawing, Mounting Dimensions and Terminal Identifications.

## CALIBRATION

## Current Loop Mode

Make the connections shown in Fig. 2. Connect an external supply with a voltage on the order of +15 V to the current loop terminals in series with a current-limiting resistor of 47 to $100 \Omega$ and a milliammeter. Set the digital input code to zero (grounding the CLEAR terminal will accomplish this) and adjust the $50 \mathrm{k} \Omega$ trimpot for a reading of 4 mA . Set the input code to maximum as listed in Table 1 (all 1's for binary or the code corresponding to 999 for BCD) and adjust the $200 \Omega$ trimpot for a reading of 20 mA . See Note 3, under Speccifications, for other current ranges.

## Unipolar Voltage Mode

The MP1480S provides the system user with the capability of adjusting the converter to compensate for system zero offsets. Determine output range required. Make the connections shown in Fig. 3, including the desired Unipolar output connections listed under the Figure. Apply a "ZERO" input digital code (see Table 1) and adjust the 50 $k \Omega$ potentiometer for a zero voltage reading at V OUT. Set input code for maximum reading and adjust the $200 \Omega$ potentiometer for the proper output, as listed in Table 1.

## Bipolar Voltage Mode

Determine output range required. Make the connections shown in Fig. 3, including the desired Bipolar output connections listed under the Figure. Apply a "ZERO" input code and adjust the $50 \mathrm{k} \Omega$ potentiometer for full negative value at $V$ OUT. Apply a midscale input code, as listed in Table 1. Adjust $200 \Omega$ potentiometer for zero output at V OUT.

| Output Current | Code | Digital Input | Full Scale Output <br> Range 0.5V or $\pm \mathbf{5 V}$ | Full Scale Output <br> Range 0-10V or $\pm \mathbf{1 0 V}$ |
| :---: | :---: | :---: | :---: | :---: |
| 20 mA | Unipolar Binary <br> 4 mA | 111111111111 <br> Unipolar Binary | 000000000000 | +4.9988 |
| Not Used | Bipolar Offset | 111111.111111 | 0.0000 | +9.9976 |
|  | Binary | 100000000000 | 0.9976 | 0.0000 |
|  |  | 00000000000 | -5.0000 | +9.9951 |
|  |  |  | 0.0000 |  |
| 20 mA | Unipolar BCD | 100110011001 | +4.995 | -10.0000 |
| 4 mA | Unipolar BCD | 000000000000 | 0.000 | +9.990 |
| Not Used | Bipolar Offset | 100110011001 | +4.990 | 0.000 |
|  | BCD | 010100000000 | 0.000 | +9.980 |
|  |  | 000000000000 | -5.000 | 0.000 |

NOTE: Input of all zeros may be forced by grounding the CLEAR input terminal.
Table 1. MP1480S Digital Input Coding for Binary and BCD Inputs.

## ORDERING GUIDE

Specify MP1480S - $-\square-\square$
Input Logic
LS TTL - T
CMOS - C
Input Code
Binary - BIN
BCD - BCD


## ANALOGC.

## MP1814

High Performance General Purpose 14-Bit D/A Converter

## Description

The Analogic MP1814 is a premium quality digital-to-analog converter which provides genuine 14-bit resolution, linearity, and stability. Every contributing element to the MP1814 Error Budget has been designed and engineered to provide a converter that meets the requirements for economical, high-speed, accurate, and stable 14 -bit resolution in highprecision, wide-dynamic-range applications.

## Performance Achievements

The MP1814 incorporates highspeed, thermal tracking, monolithic voltage switches; precise, ultrastable, network resistors; and a reference source servoed to an aged, temperature-compensated precision reference Zener for accurate, stable operation over wide temperature ranges. The MP1814 also includes a high speed voltage amplifier that slews at $10 \mathrm{~V} / \mu \mathrm{s}$ and supports the throughput settling time of less than $15 \mu \mathrm{~s}$ for conversion to within $\pm 0.005 \%$ of a full 20 V step.
The versatile MP1814 provides the user with pin-selectable full scale ranges of $\pm 10 \mathrm{~V}, \pm 5 \mathrm{~V},+10 \mathrm{~V}$ and +5 V analog outputs for computercompatible binary or offset binary input data codes.


Figure 1. MP1814 Functional Block Diagram.

The MP1814 small size (2" $\times 2^{\prime \prime}$ ), low profile ( 0.375 "), metal case provides RFI and EMI shielding, and encloses a repairable assembly that includes high-quality power supply by-pass capacitors to prevent power supply transients from interfering with conversion performance.

## Features

## ■ True 14-bit Accuracy and

 Linearity- Maximum Interface Compatibility
Selectable $\pm 10 \mathrm{~V}, \pm 5 \mathrm{~V},+5 \mathrm{~V}$, +10 V Output Voltage
Positive True Logic Input Coding (TTL Compatible)
- High Speed
$15 \mu \mathrm{~s}$ max. to $0.005 \%$ of 20 V step
- Separate Digital and Analog Grounds
Up to 250 mV potential difference
■ Guaranteed Monotonicity Differential Linearity with 0.003\%

Tempco of Differential Linearity $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ.

## - Low Profile

0.375 " high metal shielding case

## Applications

- Wide Dynamic Range, Computer Controlled, Industrial Processes
- High Precision CRT Display Systems
- Automated Test Instrumentation
- Waveform Synthesis and Recovery
- High Resolution Information Translation Systems
- Programmable Control Instrumentation (Gain, Offset, etc.)
- High Resolution Oscillographic Recordings


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## DIGITAL INPUTS

## Number of Bits

14
Coding
Binary, Offset Binary Positive "TRUE" Logic Compatibility
1 TTLBits 2-14; 2 TTLMSB-1

## ANALOG OUTPUT

Full Scale Ranges
$\pm 5 \mathrm{~V}, \pm 10 \mathrm{~V},+5 \mathrm{~V},+10 \mathrm{~V}$
Impedance
$<0.1 \Omega$ (dc)
Maximum Load
$2 \mathrm{~K} \Omega 1000 \mathrm{pF}$ for rated settling time

## INPUT REFERENCE OUTPUT

Voltage
$+10 \mathrm{~V},+5 \mathrm{~V}$
Impedance
$<0.1 \Omega$

## SPEED

Settling Time
$10 \mu$ s typ., $15 \mu \mathrm{~s}$ max. for 20 V step to $0.005 \%$
Slew Rate
$10 \mathrm{~V} / \mu \mathrm{s}$

## ACCURACY

Absolute Accuracy
$\pm 0.006 \%$ FSR*
Linearity
$\pm 1 / 2$ LSB ( $\pm 0.003 \%$ FSR)

## Differential Linearity

$\pm 1 / 2$ LSB ( $\pm 0.003 \%$ FSR)

## Zero Offset

Adjustable to Zero
*Adjustable to $\pm 0.003 \%$ with proper adjustment of external trim pots.

## STABILITY

Diff. Linearity Tempco
$1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $3.0 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Range (Gain) Tempco
$7 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Zero Offset Tempco
Unipolar
$5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $7.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Bipolar
$7 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.

## Noise

$\pm 0.005 \%$ FSR p-p (3o)
Power Supply Sensitivity
$\pm 0.0005 \% / \%$ P.S. Change, nominal
Warm Up Time
5 minutes

## POWER SUPPLY GROUNDS

Separate Analog and digital Grounds; 250 mV max. allowable difference of potential

```
POWER REQUIREMENTS
+15V \pm3%
34 mA max. + Load
-15V \pm3%
30 mA max. + Load
+5V \pm5%
35 mA max. + Load
```

ENVIRONMENTAL AND PACKAGING
Operating Temperature
$0^{\circ}$ to $70^{\circ} \mathrm{C}$
Relative Humidity (Non-Condensing)
5\% to $95 \%$
Size
2" x 2" x 0.375 "
Shielding
RFI 6 sides, EMI 5 sides
Storage Temp.
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

## APPLICATION DATA

## Calibration

Linearity and relative accuracy for 14 -bit performance are designed in. Absolute accuracy calibration may be set externally as shown in Figure 2 and described below.


Figure 2. Connecting External Adjustments Potentiometers for MP1814 OFFSET and RANGE.

## Offset Adjustment

The analog output is adjusted for zero, or other desired offset, by connecting R1 (10-turn $20 \mathrm{k} \Omega$ potentiometer) and R3 (2 M 2 ) as shown in Figure 2. Use thermally stable components of $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or better, and keep the connection leads as short as possible to maintain the MP1814 performance.
After making the required connections, (Table 1) apply the appropriate "ZERO" code (See Table 2), and adjust R1 for 0.0000 volts output.

| FOR <br> FSR <br> $\downarrow$ | CONNECT |  |  |
| :---: | :---: | :---: | :---: |
|  | RANGE MODE | RANGE 1 | RANGE 2 |
| 10 V | REF SW | TO $\downarrow$ | TO $\downarrow$ |
| 5 V | REF SW | $+5 V$ REF | ANA RTN |
| +10 V | ANA RTN | ANA RTN | $V_{\text {OUT }}$ |
| +5 V | ANA RTN | $V_{\text {OUT }}$ | $V_{\text {OUT }}$ |

Table 1. Connection Matrix for Full Scale Outputs.

ORDERING GUIDE
Specify MP1814

## Range Adjustment

The MP1814 analog output may be calibrated for the desired full scale range by connecting R2 (10-turn $20 \mathrm{k} \Omega$ potentiometer) and R4 (1 MS) as shown in Figure 2. (See stability and lead length requirements described above.) Apply the full scale code as indicated in Table 1, and adjust R2 for the appropriate full scale voltage output.

| CODE | UNIPOLAR (Binary) |  | BIPOLAR (Offset Binary) |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0 to +10 V | 0 to +5 V | $\pm 10 \mathrm{~V}$ | +5V |
| 11111111111111 | 9.9994 | 4.9997 | 9.9988 | 4.9994 |
| 10000000000000 | 5.0000 | 2.5000 | 0.0000 | 0.0000 |
| 00000000000001 | 0.0006 | 0.0003 | -9.9988 | -4.9994 |
| 00000000000000 | 0.0000 | 0.0000 | -10.0000 | $-5.0000$ |

Table 2. MP1814 Coding Translation Table.


Figure 3. Strobe and Data Input Timing.


Figure 4. MP1814 Outline Dimensions.


## ANALOGIC.

MP1900A SERIES<br>High Speed, High<br>Stability<br>13, 14, 15 and 16-Bit D/A<br>Converters

## Description

The MP1900A Series are thermally stabilized, precision digital-toanalog (D/A) converters that provide exceptional linearity, and stability over both time and temperature. Employing unique offset and gain stabilizing circuitry, each model in the Series offers true accuracy commensurate with its resolution at throughput rates in excess of 100 kHz . Linearity of $0.001 \%$ FSR, absolute accuracy of $0.002 \%$ FSR, and a differential linearity tempco of $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ are achieved to meet the most demanding industrial and instrumentation requirements, where stability over time and temperature and high reliability are critical.
Both unipolar and bipolar current and voltage output modes are provided to allow maximum flexibility in implementing a design using the MP1900A Series. Settling times to within 1 LSB of a full scale input step of $1.5 \mu \mathrm{~s}$ in the current mode, or $10 \mu \mathrm{~s}$ in the voltage mode (using the internal output amplifier) are obtainable. Additional features such as data input latches, internal gain and offset adjustment potentiometers, internal reference supply and pin-selectable operating mode, combine to make system integration of the MP1900A Series of high accuracy, high stability D/A converters very straight-forward.

Completely self-contained, each model in the MP1900A Series is packaged in a fully shielded $2 \times 4 \times$ 0.375 " metal can. The locations of the various functlonal pins is standardized, allowing or direct interchangeability among the four converters in the Series.

## Features

- Up to 16-bit Resolution
- 0.001\% FSR Integral Linearity
- 0.002\% FSR Absolute Accuracy
- Settling Times to $1.5 \mu \mathrm{~s}$
- Pin-Selectable Output Mode

Unipolar or bipolar
Current or voltage

- Thermally Stabilized Gain and Offset


## Applications

- Precision Incremental CRT Displays
- Digital Control of Power Supplies
- Automated Component Testing

Waveform Synthesis
Automated Phototypesetting


Figure 1. MP1916A Functional Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## PARAMETER

## DIGITAL INPUT

## Enable

32 loads
DTLITTL Compatible
2 loads

## Resolution

16 - MP1916A, 15 - MP1915A, 14 -
MP1914A, 13 - MP1913A
Input Codes
Binary, 2's complement (pin selectable)

## ANALOG OUTPUT

Current Mode
Full Scale Range
-2 mA to +2 mA , bipolar, 0 to -4 mA , unipolar
Impedance
1.25 k $\Omega$, bipolar, 2 k $\Omega$, unipolar

Voltage Compliance
$\pm 1 \mathrm{~V}$ max.

## Voltage Mode

Full Scale Range
$\pm 10 \mathrm{~V}, \pm 5 \mathrm{~V}, 0$ to $+10 \mathrm{~V}, 0$ to +5 V (pin
selectable)
Impedance
$0.1 \Omega$ @ dc
Load Current
$\pm 5 \mathrm{~mA}$ (includes feedback current)

## INTERNAL REFERENCE OUTPUT

## Voltage

$6.5 \mathrm{~V} \pm 0.3 \%$ (proportional to range control)
Output Impedance
$0.1 \Omega$
Current Load
1 mA max.

## SPEED

## Current Mode

Settling Time to 1 LSB
$1.0 \mu \mathrm{~s}$ typ. - MP1916A, $0.8{ }_{\lambda} \mathrm{s}$ typ. - MP1915A, $0.6 \mu$ s typ. - MP1914A \& MP1913A
(Full Scale Step)
$1.5 \mu \mathrm{~s}$ max. - MP1916A, $1.2 \mu \mathrm{~s}$ max. -
MP1915A, $1.0 \mu \mathrm{~s}$ max. - MP1914A \& MP1913A
Voltage Mode (Internal Amp) Settling Time to 1 LSB
$10 \mu$ s typ., $20 \mu$ s max. - MP1916A
$10 \mu$ s typ., $17 \mu$ s max. - MP1915A
$10 \mu$ s typ., $15 \mu$ s max. - MP1914A \& MP1913A
Slew Rate
$2 \mathrm{~V} / \mu \mathrm{s}$

## ACCURACY

Linearity
0.001\% FSR - MP1916A, 0.0015\% FSR -

MP1915A, 0.003\% FSR - MP1914A, 0.006\% FSR - MP1913A
Absolute Accuracy
0.002\% FSR - MP1916A, 0.004\% FSR -

MP1915A, 0.006\% FSR - MP1914A, 0.01 \% FSR - MP1913A

## STABILITY

## Current and Voltage Modes

Tempco of Reference
$2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. - MP1916A, MP1915A \& MP1914A
$3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. - MP1913A
Tempco of Linearity
$1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $2 \mathrm{ppm} /{ }^{\circ} \mathrm{C} \max$.
Tempco of Gain
$2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. - MP1916A, MP1915A \& MP1914A
$3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $6 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. - MP1913A
Power Supply Sensitivity
5 ppm FSR/\% change in dc voltage

## Current Mode

Tempco of Offset
$1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., unipolar; $2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., bipolar - MP1916A, MP1915A \& MP1914A
$1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., unipolar; $3 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., bipolar

- MP1913A


## Voltage Mode

Tempco of Offset
$2 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., unipolar - MP1916A, MP1915A \& MP1914A
$6 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max., unipolar - MP1913A

## NOISE (3o)

dc to 1 MHz
0.0015\% FSR p-p - MP1916A, MP1915A \&

MP1914A
0.0030\% FSR p-p - MP1913A
dc to $\mathbf{6 0 ~ H z}$
$50 \mu \mathrm{~V}$ p-p ( $0.00025 \%$ FSR)

## DIGITAL CONTROL*

## Enable Input

TTL compatible (high $=$ enable)
Loading
32 loads
*See Timing Diagram

## POWER SUPPLY

$+15 \mathrm{~V} \pm 3 \%$
35 mA typ. + load current
$-15 \mathrm{~V} \pm 3 \%$
35 mA typ. + load current
$+5 \mathrm{~V} \pm 5 \%$
180 mA typ.

## ENVIRONMENTAL \& PACKAGING <br> Storage \& Operating Temperature <br> $0^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$

Relative Humidity
$5 \%$ to $95 \%$, non-condensing
Warmup Time
5 min. to spec. accuracy
Fault Protection
Output may be shorted to ground indefinitely
without damage
Size
$4 \times 2 \times 0.375^{\prime \prime}(101.6 \times 50.8 \times 9.5 \mathrm{~mm})$
Shielding
RFI 6 sides; EMI 5 sides

## Using the MP1900A Series

The 1900A Series of 13- to 16 -bit D/A Converters is factory equipped to permit user selection of any of the standard performance options. These selections are accomplished by making appropriate pin connections externally at the module pins.
Operation for binary, offset binary, or two's complement input code, voltage or current output mode, and the full-scale output range are determined by making the pin connections specified in Figure 2.
When using the current output mode, the built-in voltage amplifier is available for other system applications. However, if not used, the amplifier voltage output should be conected to AMP IN, to prevent possible noload amplifier oscillations from coupling to the current output signal.

| OUTPUT AND <br> CODING REQUIRED | JUMPERS |
| :---: | :---: |
|  | PIN JUMPERS ON MODULE |

Figure 2. Mode and Full-Scale Range Jumper Connections.

## Adjustments

Built-in potentiometers may be adjusted to customize the MP1900TC Series D/A converters to system aplications requiring trimming of Range (Gain) and/or Offset (Zero). The RANGE and OFFSET potentiometers are identified and located on the label, and access to them is made at the top of the Modupac.

| MP1916A DIGITAL INPUT DATA CODING |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FORMAT | MSB | INPU <br> (for 1 | $\begin{aligned} & \text { T COD } \\ & 6 \text { bits)* } \end{aligned}$ | LSB | 1913 | $\begin{aligned} & \text { IOUT M } \\ & 1914 \end{aligned}$ | $\begin{gathered} \text { iamperes* } \\ 1915 \end{gathered}$ | 1916 |
| Unipolar Binary | $\begin{aligned} & 1111 \\ & 0000 \end{aligned}$ | $\begin{aligned} & 1111 \\ & 0000 \end{aligned}$ | $\begin{aligned} & 1111 \\ & 0000 \end{aligned}$ | $\begin{aligned} & 1111 \\ & 0000 \end{aligned}$ | $\begin{array}{r} -3.99950 \\ 0.00000 \end{array}$ | $\begin{array}{r} -3.99975 \\ 0.00000 \end{array}$ | $\begin{array}{r} -3.99988 \\ 0.00000 \end{array}$ | $\begin{array}{r} -3.99994 \\ 0.00000 \end{array}$ |
| Offset <br> Binary | 1111 <br> 1000 <br> 0000 | $\begin{aligned} & 1111 \\ & 0000 \\ & 0000 \\ & \hline \end{aligned}$ | 1111 <br> 0000 <br> 0000 | 1111 <br> 0000 <br> 0000 | $\begin{array}{r} -1.99950 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ | $\begin{array}{r} -1.99975 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ | $\begin{array}{r} -1.99988 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ | $\begin{array}{r} -1.99994 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ |
| Two's Complement | 0111 <br> 0000 <br> 1000 | $\begin{aligned} & 1111 \\ & 0000 \\ & 0000 \\ & \hline \end{aligned}$ | 1111 0000 0000 | 1111 <br> 0000 <br> 0000 | $\begin{array}{r} -1.99950 \\ 0.00000 \\ +2.00000 \end{array}$ | $\begin{array}{r} -1.99975 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ | $\begin{array}{r} -1.99988 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ | $\begin{array}{r} -1.99994 \\ 0.00000 \\ +2.00000 \\ \hline \end{array}$ |
| *For Voltage Amplifier, $\mathrm{V}_{\text {OUT }}$ is defined by Selected Feedback Resistor, $\mathrm{R}_{\text {FB }} ; \mathrm{V}_{\text {OUT }}=$ $-I_{\text {OUT }} \times$ R $_{\text {FB. }}$. <br> **For lesser bits, delete less significant bits. |  |  |  |  |  |  |  |  |

To trim any offsets to zero, apply the coded input for zero signal, and trim OFFSET for a zero analog current or voltage output.
To adjust the range, apply a full-scale coded input and trim RANGE for the correct analog current or voltage output.


Typical Timing Diagram For Any Bit.
Data present at the latch input is transferred to the DAC input when the enable line goes high, and follows the data as long as the enable line remains high. When the enable goes low, the information that was present just prior to the time the transition occurred is retained.

Figure 3. Typical Timing, MP1900A Series.


Figure 4. MP19XXA Outline Drawing and Pin Locations.

## ORDERING GUIDE

For Specify
13-Bit D/A MP1913A
14-Bit D/A MP1914A
15-Bit D/A MP1915A 16-Bit D/A MP1916A

## Description

The MP1900TC Series are thermally stabilized, precision digital-toanalog (D/A) converters that provide exceptional linearity and stability over both time and temperature. Employing unique temperature stabilizing circuitry, each model in the Series offers true accuracy commensurate with its resolution at throughput rates in excess of 100 kHz . Linearity of $0.001 \%$ FSR, absolute accuracy of $0.002 \%$ FSR, and combined Reference, Gain, Linearity and Offset tempco of $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ are achieved to meet the most demanding industrial and instrumentation requirements, where stability over time and temperature and high reliability are critical.
Both unipolar and bipolar current and voltage output modes are provided to allow maximum flexibility in implementing a design using the MP1900TC Series. Settling times to within 1 LSB of a full scale input step of $1.5 \mu \mathrm{~s}$ in the current mode, or $10 \mu \mathrm{~s}$ in the voltage mode (using the internal output amplifier) are

## MP1900TC SERIES

High Speed, Ultra-Stable 14-, 15-, and 16-Bit D/A Converters


Figure 1. Functional Block Diagram of MP1916TC.
obtainable. Additional features such as data input latches, internal gain and offset adjustment potentiometers, internal reference supply and pin-selectable operating mode, combine to make system integration of the MP1900TC Series of high accuracy, high stability D/A converters very straight-forward.
Completely self-contained, each model in the MP1900TC Series is packaged in a fully shielded $2 \times 4 \times$ 0.44 " metal can. The locations of the various functional pins is standardized, allowing for direct interchangeability among the four converters in the Series.

## Features

- Up to 16-bit Resolution
0.001\% FSR Integral Linearity
- 0.002\% FSR Absolute Accuracy
- Settling Times to $1.5 \mu \mathrm{~s}$
- Pin-Selectable Output Mode

Unipolar of bipolar
Current or voltage

- Thermally Stabilized


## Applications

## Precision Incremental CRT Displays <br> - Digital Control of Power Supplies <br> - Automated Component Testing <br> - Waveform Synthesis <br> - Automated Phototypesetting

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise notedi)

## PARAMETER

ANALOG OUTPUT
Current Mode
Full Scale Range
-2 mA to +2 mA , bipolar; 0 to -4 mA , unipolar
Impedance
$1.25 \mathrm{k} \Omega$, bipolar; $2 \mathrm{k} \Omega$, unipolar
Voltage Compliance
$\pm 1 \mathrm{~V}$ maximum
Voltage Mode
Full Scale Range
$\pm 10 \mathrm{~V}, \pm 5 \mathrm{~V}, 0$ to $+10 \mathrm{~V}, 0$ to +5 V (pin
selectable)
Impedance
$<0.1 \Omega$ @ dc
Load Current
$\pm 5 \mathrm{~mA}$ max. (includes feedback current)

## DIGITAL INPUT

DTL/TTL Compatible
2 loads
Number of Bits
16 - MP1916TC, 15 - MP1915TC, 14 -
MP1914TC
Input Codes
Binary, 2's complement (pin selectable)

## Enable

32 TTL Loads

## INTERNAL REFERENCE OUTPUT

Voltage
$6.5 \mathrm{~V} \pm 0.15 \%$ (proportional to range control)
Output Impedance
$<0.1 \Omega$
Current Load
1 mA maximum

## SPEED

## Current Mode

Settling Time to 1 LSB
$1 \mu$ s typ. - MP1916TC, $0.8 \mu$ s typ. -
MP1915TC, $0.6 \mu$ s typ. - MP1914TC
(Full Scale Step)
$1.5 \mu$ s max. - MP1916TC, $1.2 \mu$ s max. -
MP1915TC, $1.0 \mu$ s max. - MP1914TC
Voltage Mode (Internal Amp)
Settling Time to 1 LSB
$10 \mu \mathrm{~s}$ typ., $20 \mu \mathrm{~s}$ max. - MP1916TC
$10 \mu$ s typ., $17 \mu \mathrm{~s}$ max. - MP1915TC
$10 \mu$ s typ., $15 \mu$ s max. - MP1914TC
Slew Rate
$2 \mathrm{~V} / \mu \mathrm{s}$

ACCURACY (@ $+15^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$ )
Relative Accuracy (Linearity)
0.001\% FSR max. - MP1916TC, 0.0015\% FSR max. - MP1915TC, 0.003\% FSR - MP1914TC
Absolute Accuracy (NBS Traceability) 0.002\% FSR max. - MP1916TC, 0.004\% FSR max. - MP1915TC, $0.006 \%$ FSR - MP1914TC

STABILITY (@ $+15^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$ )
Current and Voltage Modes
Total Combined Tempco's of Reference, Linearity, Gain and Offset
$1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
For 0 to $+15^{\circ} \mathrm{C}$ and $+35^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$ without Temperature Control $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Power Supply Sensitivity
$5 \mathrm{ppm} \mathrm{FS} / \%$ change in dc voltage

## POWER REQUIREMENTS

$+15 \pm 0.5 \mathrm{Vdc}$
DAC: 35 mA typ. + load current
Temperature Controller: 150 mA initial, 60 mA typ. after warmup @ $25^{\circ} \mathrm{C}$
$-15 \pm 0.5$ Vdc
35 mA typ. + load current
$+5 \pm 0.25 \mathrm{Vdc}$
180 mA typ.

ENVIRONMENTAL \& MECHANICAL
Controlled Operating Temperature Range ${ }^{2}$
$+15^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$
Storage Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
$5 \%$ to $95 \%$, non-condensing
Warmup Time
10 min. to spec. accuracy
Fault Protection
Output may be shorted to ground indefinitely without damage
Dimensions
$4 \times 2 \times 0.44$ " ( $101.6 \times 50.8 \times 11.2 \mathrm{~mm}$ )
Shielding
RFI 6 sides, EMI 5 sides

1. Stabilities and temperatures given are for a normally specified DAC operation of $+15^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$. For other temperature ranges, data may be shifted accordingly. See Note 2.
2. Any $20^{\circ} \mathrm{C}$ span between $0^{\circ} \mathrm{C}$ and $+60^{\circ} \mathrm{C}$ may be user-specified.

## Principles of Operation

As shown in Figure 1, binary data is loaded in parallel into the internal latches by a high logic level at the ENABLE input. The latched outputs of the eight more significant bits drive quad switches that steer precision current sources either to the CURRENT OUTPUT or to ground. Exact current values are determined by the binary-weighted, precision, thermally tracking resistor network. This network converts the precision internal reference voltage into 16 precision currents which are gated to the output by the current steering switches. The eight less significant bits are provided by a monolithic digital-to-analog converter.
The entire package described above plus the gain-setting resistors associated with the output voltage amplifier are enclosed in a proportional temperature controller which, in turn, includes a thermistor, an operational amplifier, and a heating element. Temperature determines the thermistor output. When the exterior temperature ambient drops, the thermistor resistance increases. This action causes an increased amplifier output that forces more current through the heating element. Conversely, when the exterior temperature rises, less current flows through the heating element. Thus, a constant temperature, well within $1^{\circ} \mathrm{C}$, is maintained for an exterior $20^{\circ} \mathrm{C}$ ambient span. Wider temperature ranges or different ambient spans can be specified at time of ordering.

## Using the MP1900TC Series

The MP1900TC 14- to 16-bit D/A Converters are factory equipped to permit users to select any of the standard performance options. These selections are accomplished by making appropriate connections externally at the module pins.
Operation for binary, offset binary, or two's complement input code, voltage or current output mode, and the full-scale output range are determined by making the pin connections specified in Figure 2.
When using the current output mode, the built-in voltage amplifier is available for other system applications. However, if not used, the amplifier voltage output should be connected to AMP IN to prevent possible no-load amplifier oscillations from feedback coupling to the current output signal.

| OUTPUT AND <br> CODING REQUIRED | JUMPERS |
| :---: | :---: | :--- |
|  | PIN JUMPERS ON MODULE |

NOTE: The $+\mathbb{I N}^{*}$ terminal of the external op. amp should be connected to the ANA RTN Pin of the MP1916 via a resistor ( $1.2 \mathrm{k} \Omega$ ). *Connection on external op. Amp.

Figure 2. Mode and Full-Scale Range Jumper Connections.

## Adjustments

Built-in potentiometers may be adjusted to customize the MP1900TC Series D/A converters to system aplications requiring trimming of Range (Gain) and/or Offset (Zero). The RANGE and OFFSET potentiometers are identified and located on the label, and access to them is made at the top of the Modupac.
To trim any offsets to zero, apply the coded input for zero signal, and trim OFFSET for a zero analog current or voltage output.
To adjust the range, apply a full-scale coded input, and trim RANGE for the correct analog current or voltage output.

| DIGITAL INPUT DATA CODING |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FORMAT | INPUT CODE(MSB) (for 16 bits)** (LSB) |  |  |  | lour Milliamperes* |  |  |
|  |  |  |  |  | 1914TC | 1915TC | 1916TC |
| Unipolar Binary | $\begin{aligned} & 1111 \\ & 0000 \end{aligned}$ | 1111 | 1111 | 1111 | -3.99975 | -3.99988 | -3.99994 |
|  |  | 0000 | 0000 | 0000 | 0.00000 | 0.00000 | 0.00000 |
| Offset Binary | $\begin{aligned} & 1111 \\ & 1000 \\ & 0000 \end{aligned}$ | 1111 | 1111 | 1111 | -1.99975 | -1.99988 | -1.99994 |
|  |  | 0000 | 0000 | 0000 | 0.00000 | 0.00000 | 0.00000 |
|  |  | 0000 | 0000 | 0000 | +2.00000 | +2.00000 | +2.00000 |
| Two's Complement | $\begin{aligned} & 0111 \\ & 0000 \\ & 1000 \end{aligned}$ | 1111 | 1111 | 1111 | -1.99975 | -1.99988 | -1.99994 |
|  |  | 0000 | 0000 | 0000 | 0.00000 | 0.00000 | 0.00000 |
|  |  | 0000 | 0000 | 0000 | +2.00000 | +2.00000 | +2.00000 |
| *For Voltaqe Amplifier, V OUT is defined by Selected Feedback Resistor, RFB; <br> $V_{\text {OUT }}=-$ IOUT $\times$ RFB . <br> **For fewer bits, delete less significant bits |  |  |  |  |  |  |  |



Figure 3. MP1900TC Outline Drawing and Pin Locations.

## ORDERING GUIDE

## Specify

## 14-Bit D/A Converter MP1914TC 15-Bit D/A Converter MP1915TC 16-Bit D/A Converter MP1916TC

If stabilization over $20^{\circ} \mathrm{C}$ span other than $+15^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$ is required, please specify temperature span when ordering.

## Description

The MP1926 is an ultra-linear, high speed, 16 -bit digital-to-analog converter module designed specifically for reconstructing dynamic complex waveforms from digital data, particularly audio or acoustic signals, sonar, and other signals that have a substantial amount of the information content in the vicinity of "zero volts" (midrange). In such systems, power occasionally peaks well above the rms power level, as in speech or music. Thus, accurately recreating such information from digital data requires exceptional small signal performance to handle the information near zero level without crossover distortion, yet there must be a very large dynamic range to handle the bursts of higher amplitudes, together with the ability to handle the wide range of frequency interest.
The MP1926 meets these requirements with an internal sign/magnitude architecture that gives 18 bits of linearity for signals near zero volts and a $3 \mu \mathrm{~s}$ settling time - at a price less than that of other, low speed, 16-bit DACs which typically offer, at best, 14-bit accuracy at midrange.
Accepting standard input binary codes, including offset binary and 2's complement. Analogic's pro-


Figure 1. MP1926 Functional Block Diagram.
prietary (pat. pending) sign/ magnitude internal architecture provides performance that actually improves as the signal approaches zero from either direction (error proportional to the signal's absolute value, or magnitude). With the commonly used "offset binary" architecture, which produces a bipolar output by offsetting an internal unipolar signal by one half full scale, even a small error in the
(continued)

## Features

- Low Harmonic Distortion 0.005\% (0.0005 dB!)
- Wide Dynamic Range 16 bits
- Ultra-High Linearity Over the Full Scale Range $\pm 1 / 4$ LSB, max. mid-range non-linearity
- High speed settling time $<3 \mu \mathrm{~s}$ (MP1926A)
- Low Tempco's total drift from all sources $<1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ (MP1926S)
- Low Power 250 mW
- Built-In Code Conversion uses standard codes
- Low Cost
- Flexible
$\pm 8 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$ power supply TTL or CMOS inputs Offset Binary, 2's Complement, or
Sign/Magnitude codes
Operates $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$


## Applications

- Professional Audio Systems Low Total Harmonic Distortion
- Telecommunications Digitizing - High Noise Power Ratio
- High Resolution Information Translation Systems
- High Speed, High Precision, Automated Test Instrumentation
- Wide Dynamic Range, Computer Controlled, Industrial Processes
- Waveform Synthesis and Recovery


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## BIPOLAR OUTPUT

Full Scale Voltage Ranges (FSR) ${ }^{1}$
$\pm 5 \mathrm{~V}$ or $\pm 10 \mathrm{~V}$
dc Output Impedance
$0.1 \Omega$ max.
Load Current
5 mA max.

```
ACCURACY @ 25*
For Mid-Range Outputs Centered about Zero
Volts (1/4 FSR)}\mp@subsup{}{}{2
\pm4 ppm FSR max.
Over the Full Scale Range }\mp@subsup{}{}{3
\pm15 ppm FSR max.
Absolute Range Accuracy }\mp@subsup{}{}{4
MP1926A - }\pm0.1% FS
MP1926S - }\pm0.01% FS
Offset Voltage }\mp@subsup{}{}{4
MP1926A - \pm1 mV
MP1926S - }\pm0.1\textrm{mV
Zero Code, 0}\mp@subsup{0}{}{\circ}\mathrm{ to }7\mp@subsup{0}{}{\circ}\textrm{C
Continuous and monotonic through zero
```


## STABILITY

Tempco of Differential Nonlinearity for MidRange Outputs Centered about Zero Volt ( $1 / 4$ FSR)
$\pm 0.25$ typ., $\pm 1$ max. ppm FSR/ $/{ }^{\circ} \mathrm{C}$
Over the FSR
$\pm 0.5$ typ., $\pm 2$ max. ppm FSR $/{ }^{\circ} \mathrm{C}$
Tempco of Gain (Includes Reference) ${ }^{5}$
MP1926A - $\pm 10 \mathrm{ppm}$ of READING $/{ }^{\circ} \mathrm{C}$ typ., $\pm 30 \mathrm{ppm}$ of READING $/{ }^{\circ} \mathrm{C}$ max.
MP1926S - $\pm 2 \mathrm{ppm}$ of READING $/{ }^{\circ} \mathrm{C}$ typ., $\pm 5$
ppm of READING ${ }^{\circ} \mathrm{C}$ max.
Tempco of Offset Voltage ${ }^{6}$
MP1926A - $\pm 5 \mathrm{ppm} \operatorname{FSR} /^{\circ} \mathrm{C}$ max.
MP1926S - $\pm 0.5 \mathrm{ppm} \mathrm{FSR} /{ }^{\circ} \mathrm{C}$ max.
Power Supply Sensitivity

## Gain

20 ppm FSR/V
Offset
$20 \mu \mathrm{~V} / \mathrm{V}$
Recommended Recalibration Interval
MP1926A - N/A
MP1926S - See Note 4
Warm Up Time to Specified Accuracy
5 minutes max.
Settling Time for 5V step
to $0.01 \%$
MP1926A - $3 \mu \mathrm{~S}$ max.
MP1926S - $40 \mu \mathrm{~s}$ max.
to 1 LSB
MP1926A - $5 \mu$ s max.
MP1926S - $50 \mu \mathrm{~s}$ max.

## Slew Rate

MP1926A - $7.5 \mathrm{~V} / \mu \mathrm{s}$ min.
MP1926S - $0.15 \mathrm{~V} / \mu \mathrm{s}$ min.
Noise ( $\mathbf{1 0 ~ H z ~ t o ~} 100 \mathrm{kHz}$ )
$35 \mu \mathrm{~V}$ rms
Output Fault Protection
Indefinite short to ground

## MAGNITUDE OUTPUT (Auxiliary Output)

Voltage Range
0 to -5 V
Offset Voltage
$20 \mu \mathrm{~V}$ typ.
Tempco of Offset Voltage
$1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ max.
Output Fault Protection
Indefinite short to ground

## INTERNAL REFERENCE OUTPUT

Nominal Voltage
+5 V (proportional to Range Control)
dc Output Impedance
$0.1 \Omega$ max.
Load Current
1 mA max.

## DIGITAL INPUTS

## Resolution

## 16 bits

## Format (Pin Programmable)

See Tables 1 \& 2
Logic Compatibility ${ }^{7}$
CMOS, TTL
Low (FALSE) Level/High (TRUE) Level
$0.4 \mathrm{~V} \pm 0.6 \mathrm{~V} / 4.6 \mathrm{~V} \pm 0.6 \mathrm{~V}$
Input Impedance
$1 \mathrm{M} \Omega \mathrm{min}$.

## POWER REQUIREMENTS ${ }^{8}$

Nominal Voltage ${ }^{1}$
$\pm 8 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$
Absolute Max.
$\pm 16 \mathrm{~V}$
Current, Exclusive of Load $\pm 16 \mathrm{~mA}$
Dissipation @ $\pm 8 \mathrm{~V}$, exclusive of load 250 mW max.
Dissipation @ $\pm 15 \mathrm{~V}$, exclusive of load 500 mW max.

## ENVIRONMENT

Rated Performance
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Operating Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage Temperature Range
$-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$

## PACKAGING

Dimensions, inches ( mm rounded)
$2 \times 4 \times 0.44$ inches ( $50.8 \times 101.6 \times 11.2 \mathrm{~mm}$ )
Electromagnetic Shielding
5 sides
Electrostatic Shielding
6 sides

## Notes

1. FSR is pin programmable. 20 V FSR requires $\pm 15 \mathrm{~V}$ power supply.
2. Deviation from best straight line.
3. Deviation from best straight line.
4. Range accuracy (gain) and offset voltage each adjustable via externally accessible potentiometers. Specifications given are factory setting, using $\pm 8 \mathrm{~V}$ supplied. Recommended recalibration interval is three months in an instrumentation application (MP1926S).
5. For bipolar signals, $X$ ppm of READING is less than or equal to $\mathrm{X} / 2 \mathrm{ppm}$ of FSR, e.g., 2 ppm of READING $\leq 1 \mathrm{ppm}$ FSR.
6. Total at 0 V , not affected by reference drift.
7. Unit does not include pull-up resistors, which may be required for TTL.
8. Analog Return, Output Return, and case are tied internally.

## Description (cont.)

offsetting resistor can frequently cause large output errors near zero volts. Therefore, the MP1926 is the only high speed, 16-bit digital-to-analog converter to offer linearity near zero volts better than $\pm 1 / 4$ LSB (4 ppm) and total full range harmonic distortion (measured with an output deglitch amplifier) better than $0.005 \%$ ( 0.0005 dB !).
Moreover, this performance is preserved over a wide temperature range. The MP1926S, a version optimized for use in reference-type applications, offers voltage offset, linearity, and gain drifts so low that the worst-case total (algebraic sum) of their effects for signals near zero volts is typically less than $1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ from $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$. Even the very fast MP1926A version offers better stability than provided by many higher-priced 16-bit DACs. Both versions have an auxiliary unipolar output that is proportional to the magnitude of the bipolar output and which offers zero voltage offset stability of $1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ !
Besides offering such linear and stable performance, the MP1926 offers versatility. It directly accepts offset binary and two's complement codes as well as sign/magnitude codes, without added circuitry, from CMOS or TTL logic, so that it can be interfaced easily with most
computer-based systems. It operates from a single bipolar power supply (no separate +5 V supply is required), and its low power consumption of 250 mW and metal case qualify it for use in a variety of environments. Thus the benefits of exceptionally good small-signal performance, high speed, and very wide dynamic range, coupled with low cost, make the MP1926 the ideal choice for a large variety of applications.

## Performance Features

An internal sign/magnitude architecture provides optimum bipolar performance, particularly when compared to the commonly used offset binary architectures. Several key features of the MP1926 make this dramatic improvement in performance easy to use in many applications. Those features include low gain, linearity, offset errors: onboard decoding of several popular digital codes (converting to the sign/magnitude code used internally; and hard-wired range selection.

## Bipolar Performance

An internal sign/magnitude architecture provides optimum bipolar performance because step size error decreases as the signal magnitude decreases, rather than being proportional to major bit weight contributions as in an offset binary architecture. The MP1926 employs a unique internal implementation of the sign/magnitude algorithm. Figure 1 shows that the 15 LSBs of a decoded (code converted) digital word control a resistor network that provides a scaled current to a chopper stabilized Magnitude Amplifier, which in turn converts this current to a unipolar ( 0 V to -5 V ) voltage. The bipolar output is generated by using the MSB to configure the Output Amplifier as either an inverter or a follower. Figure 2 shows the resulting performance for a typical MP1926 - note that the error decreases as the output approaches zero from either direction, that the performance is symmetric above and below 0 V , and that the output crosses through zero continuously.
As shown, for midrange outputs the nonlinearity is typically much less than 4 ppm FSR. Thus the MP1926 provides a full 96 dB of useable dynamic range ( $2^{16}$ voltage steps). Most other 16 -bit converters have a much smaller effective dynamic range because they exhibit relatively large errors


Figure 2. Error Plot of an MP1926. Error measured at zero volts and at 256 other points across the full scale range. These included the 128 most major bit transition points, plus a point 1 LSB away from each. Over the FSR the largest total error (non-linearity, gain and offset) is less than 10 ppm. Over the midrange centered around zero volts, the non-linearity error is less than 2 ppm.
for small output signals. The following paragraphs show why the MP1926 approach is superior to offset binary approaches and to earlier sign/magnitude approaches in most bipolar applications.
Figure 3 compares performance around zero of offset binary and sign/magnitude architectures, showing dramatically the lower gain error sensitivity of a sign/magnitude approach. Further, an offset binary converter requires a precise match (much better than $1 / 2$ LSB) between the MSB resistor and the offsetting resistor. For outputs near OV the MSB is switched on and all other bits are switched off (or MSB off, all other bits on), so small imbalances and drifts with time can easily cause a discontinuity at 0 V which is proportional to the MSB weighting - i.e., an error proportional to one half of the full scale even for small signals.
On the other hand, in a converter using an internal sign/magnitude approach, the most significantly weighted resistors do not affect the current summing for outputs near OV, so linearity is inherently superior when using the same quality resistors, both initially and over time. (Dynamic accuracy at
zero is also superior because a zero cross ing is not a major current switching point.)

## Initial Linearity

For midrange outputs centered around 0 V , the MP1926's linearity is better than $\pm 1 / 4$ LSB ( 4 ppm FSR). For outputs beyond midrange, the increment between codes equals the LSB step size of 15 ppm plus a differential nonlinearity of $+13 /-9 \mathrm{ppm}$ FSR, even at the major carries. This ensures both monotonicity and no missing steps over the entire output range.

## Long Term Stability

Most resistors, except for laboratory standard wire-wound types, exhibit tracking ratios worse than $15 \mathrm{ppm} / \mathrm{year}$. In offset binary converters such resistor drift frequently results in significant linearity drift for signals near 0 V ; a converter using an internal sign/magnitude approach can be expected to be four or five times less sensitive to resistor drift. For signals centered around OV ( $1 / 4 \mathrm{FSR}$ ), long-term linearity stability of the MP1926 is predicted to be much better than $1 / 2$ LSB per year.


Figure 3. Comparison of Performance Near Zero. The transfer function of an offset binary converter originates at - FS (all current switches off). Thus OV is usually $1 / 2$ of FSR, and any gain drift will shift the OV output as shown. With an internal sign/magnitude approach the transfer function originates at 0 V (all current switches off), so the 0 V output is not affected by gain drift.

The classical problem of attaining both low offset drift and high speed simultaneously when using a sign/magnitude approach has been solved by using the unique Magnitude Amplifier. (An offset error in the Magnitude signal would cause a discontinuity whenever the sign switches at a zero crossing, and would cause the output to be asymmetric about 0V). Earlier sign/magnitude approaches have met this low offset requirement by using slow amplifiers, limiting their applicability. The MP1926's Magnitude Amplifier is both chopper stabilized and
fast. Its offset drift is an extremely low 1 $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$, yet the MP1926A settles to 1 LSB in only $5 \mu \mathrm{~s}$. The converter has no offsetting resistor, so the only other contributor to offset drift is the output amplifier, resulting in less than $0.5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ drift for the MP1926S. Therefore, the module's performance is symmetric about zero yet fast enough for a wide variety of applications.
In summary, the Analogic MP1926 sign/magnitude approach inherently provides better bipolar performance than would any offset binary approach using equal quality resistors and amplifiers. Furthermore, the precision chopper stabilized design of the MP1926 is the optimum internal implementation of the sign/magnitude approach. The resulting total improvement for a typical application (e.g., rms signal $\pm 10 \%$ of the peak signal) can be on the order of 20 dB !

## Input Decoding

The MP1926 may be connected to accept either of four input code types: offset

| CODE | MODULE CONNECTIONS |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{gathered} \text { SIGN } \\ \text { to } \end{gathered}$ | CONT to | $\begin{aligned} & \text { B1 CONT } \\ & \text { to } \end{aligned}$ | $\begin{gathered} \text { CODE SET } \\ \text { to } \end{gathered}$ |
| Offset Binary | SIGN OUT | SIGN OUT | REF OUT | REF OUT |
| 2's Complement | SIGN OUT | SIGN OUT | OUT RET | REF OUT |
| Sign/Magnitude* | SIGN OUT | OUT RTN | REF OUT | OUT RTN |
| Modified Sign/Magnitude* | SIGN OUT | OUT RTN | OUT RET | OUT RTN |

Table 1. Code Selection.
binary, 2's complement, sign/magnitude, or modified sign/magnitude. Neither external decoding control nor an MSB input are required, because interconnecting the module per Table 1 automatically provides conversion to the sign/magnitude code used internally. Each code bit is supplied to one of 16 CMOS EXCLUSIVE OR gates. Each gate either follows or inverts the bit, depending on the state of the CONTrol signal connected to its second input.*

[^11]
## Output Range Selection

Outputs from the module have a low impedance and can drive up to 5 mA . The user may select the desired output voltage range by setting the gain of the Output Amplifier via the RANGE SET input. To select an output range of $\pm 5 \mathrm{~V}$ (10V FSR), connect RANGE SET to the bipolar OUTPUT. To select $\pm 10 \mathrm{~V}$ output range ( 20 V FSR), connect RANGE SET to OUTPUT RETURN, and use $\pm 15 \mathrm{~V}$ power supplies.

## Calibration

For audio and telecommunication applications, offset and range recalibration will rarely, if ever, be required. However, the module should be recalibrated whenever the full scale range is changed.

## Comments

1. Interconnect the MP1926 per the application. Apply power and allow 5 minutes for warm-up.
2. Readjust the OFFSET control before readjusting the GAIN (range) control.
3. Refer to Table 2 for the corresponding codes and voltages.

## Bipolar Zero Offset Adjustment Procedure

1. If supplying Offset Binary or 2's Complement input code, apply the code corresponding to zero while adjusting the OFFSET control so that the output is $0 \mathrm{~V} \pm$ the tolerance required for the application.
2. If supplying Sign/Magnitude or Modified Sign/Magnitude code:
a. Alternately apply the codes corresponding to +0 V and - OV;
b. While so doing, adjust the OFFSET control so that the average value of these two outputs if 0 V . (these two outputs will typically differ by less than 2 ppm .)

## Range Adjustment Procedure

1. Apply a code corresponding to the largest voltage for which the absolute value is critical.
2. Adjust the GAIN control so that the output equals the corresponding voltage to within the application tolerance.

## TYPICAL APPLICATIONS

## Professional Audio Systems

Figure 4 illustrates the highest performance, yet lowest cost solution available to the problem of simultaneously updating a stereo pair of analog outputs at rates up to 55 kHz from 16-bit resolution data. A conventional implementation would require two D/A converters, with digital double buffering for simultaneous update, feeding two output deglitch amplifiers. The MP1926A, with a voltage settling time of only $5 \mu \mathrm{~s}$, allows two channels to be updated from a single D/A converter within the $18 \mu \mathrm{~s}$ available. The only buffering required for

| $\begin{gathered} \text { Offset Binary } \\ \mathrm{B} 1, \mathrm{~B} 2, \ldots, \quad \mathrm{~B} 15, \mathrm{~B} 16 \end{gathered}$ | Bipolar Output |
| :---: | :---: |
|  | +4.999847V |
| 1000000000000000 | 0.000000 V |
| 0000000000000000 | -5.000000V |
| $\begin{array}{cc}  & \text { Two's Complement } \\ \mathrm{B} 1, \mathrm{~B} 2, \ldots, & \mathrm{~B} 15, \mathrm{~B} 16 \end{array}$ | Bipolar Output |
| $\begin{array}{llllll}0 & 111 & 111 & 111 & 111 & 111\end{array}$ | + 4.999847V |
| 0000000000000000 | 0.000000 V |
| 1000000000000000 | $-5.000000 \mathrm{~V}$ |
|  Sign/Magnitude <br> $\mathrm{B} 1, \mathrm{~B} 2, \ldots$, $\mathrm{B} 15, \mathrm{~B} 16$ | Bipolar Output |
| $\begin{array}{llllllll}1 & 111 & 111 & 111 & 111 & 111\end{array}$ | +4.999847V |
| 1000000000000000 | $+0.000000 \mathrm{~V}$ |
| 0000000000000000 | -0.000000V |
|  | -4.999847V |
| Modified Sign/Magnitude |  |
| B1, B2,.. , B15, B16 | Bipolar Output |
| $\begin{array}{lllllll}0 & 111 & 111 & 111 & 111 & 111\end{array}$ | + 4.999847V |
| 0000000000000000 | $+0.000000 \mathrm{~V}$ |
| 1000000000000000 | -0.000000V |
| 1111111111111111 | -4.999847V |
| Notes <br> For $\pm 5 \mathrm{~V}$ FSR, 1 LSB $=153 \mu \mathrm{~V}$ <br> For $\pm 10 \mathrm{~V}$ FSR, multiply above voltages |  |

Table 2. Input Coding.
simultaneous updating can be provided by an AH201-1 Distortion Suppressor ( Z 1 in Figure 4.) The very low feedthrough ( -100 dB) of the AH201-1 allows Channel 1 to be held while the MP1926A outputs Channel 2 data with negligible effect on Channel 1.
A deglitcher is always required at the output of D/A converter in audio aplications to minimize harmonic distortion. The AH201 is a deglitch amplifier designed specifically for use with the MP1926A in these applications. The Channel 2 AH201-2 deglitches by momentarily holding its output at ground during the time that the MP1926A is updating Channel 2. The Channel 1 AH201-2 holds its output at ground during the time that the AH201-1 is switching (see timing diagram). The response of the AH2O1 is time constant controlled ( $\mathrm{RC}=2 \mu \mathrm{~s}$ ) to pass full power 20 kHz sine waves without output slew rate limiting (and subsequent distortion). The overall harmonic distortion of this configuration has been measured to be less than $0.005 \%$ ( 0.0005 dB !) over the frequency range of 20 Hz to 20 kHz .
For applications in which sequential updating of the outputs is acceptable, the AH201-1 shown in Figure 4 may be ommitted. Each half of the AH201-2 would be sequentially updated, coincident wih the D/A update of its channel data. Also, depending on the application, units may be driven from a single MP1926A.


Figure 4. Simultaneous Updating of Stereo Audio Channels.


Figure 5. Typical Timing for Figure 4.


Figure 6. Mechanical \& Pinout.

## ORDERING GUIDE

For $3 \mu$ s settling time: Specify MP1926A
For 2 ppm of READING/ ${ }^{\circ} \mathrm{C}$ gain stability: Specify MP1926S


## ANALOGIO

## MP1936

Ultra-Low Harmonic
Distortion
Multi-Year Stable, Low Cost
16-Bit D/A Converter with Distortion Suppressor

## Description

The MP1936 combines an ultralinear, bi-polar digital-to-analog conversion circuit with a controlled time constant distortion suppressor, providing in one low-cost module complete capability for restoring digitized signals to analog form with less than $0.005 \%$ harmonic distortion (less than -86 dB , worst case). A complete, fully-tested subsystem needing no external parts or adjustments, this module requires less total component and assembly expense, pc board area, and power than do subsystems based on integrated circuit DAC's. Nevertheless, it provides superior low-level performance essential to quality telecommunications, satellite program distribution, and other ac-coupled applications requiring wide dynamic range. As an example, for a 1 kHz tone at the commonly measured level of -41 dB down from full scale, peak line distortion is down by $-50 \mathrm{~dB}(-91 \mathrm{~dB}$ relative to full scale)!
The D/A and distortion suppression circuits are based on the Analogic professional audio DAC and professional audio distortion suppressor (MP1926A* and MP201A*, respectively), but are optimized within a single shielded and tested module
(continued)


Figure 1. MP1936 Functional Block Diagram

## Features

- Ultra-Low Harmonic Distortion

For full scale signals:
-86 dB worst case 20 Hz to 20 kHz
For low level signals:
-50 dB max. for a 1 kHz tone
@ -41 dB below peak

- High Speed

Up to 128,000 updates/sec Wide bandwidth for multiple high
fidelity or voice grade channels
$\square$ Ultra Low Noise
-110 dB (less than 1 LSB )

- Low Cost

No external components
Minimized board space
Adjustment-free operation

- Ultra Stable

3-year, no-adjustment differential linearity of $\pm 25 \mathrm{ppm}$ FSR, better than the 3-month performance of higher-priced converters
Differential linearity tempco of $\pm 0.25 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$

- Environmentally Rugged

128,700 hour MTBF ( $>14$ years)
Operates $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C} \mathrm{EMI}$
\& RFI shielded

- Low Power
$<430 \mathrm{~mW}$
- Flexible
$\pm 9 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$ power supply
TTL or CMOS inputs
Offset binary, 2's complement, or sign/magnitude input codes
- Easy to Use

DAC updates upon code change
Deglitcher controlled by single line
Compatible with industry standard MP1926A professional audio DAC

## Applications

- Telecommunications Decoding

Satellite Earth Stations
Terrestrial Channel Bank
Equipment
Studio Transmission Links
(STL's)
Terrestrial Audio PCM Systems

- High Accuracy Bipolar Data Translating
Waveform Synthesizers
Testers for Consumer Grade
Digital Audio Systems

```
BIPOLAR OUTPUT
Full Scale Voltage Range (FSR)
\pm5V nom.
Load Current
\pm5 mA max., (DAC w/Distortion Suppressor }\mp@subsup{}{}{1}\mathrm{ -
\pm20 mA max.)
Output Impedance @ dc
0.1\Omega max.
Output Fault Protection
Indefinite short to ground
```

ACCURACY @ $25^{\circ} \mathrm{C}$, nom.
Peak Line Harmonic Distortion ${ }^{2}$
Fundamental @ $\pm \mathbf{5 V}$; 20 Hz through 20 kHz N/A, (DAC w/Distortion Suppressor ${ }^{1}$ - Down from fundamental by at least -86 dB )
Fundamental $\mathbf{- 4 1} \mathrm{dB}$ down @ 1 kHz N/A, (DAC w/Distortion Suppressor' - Down from fundamental by at least -50 dB )
Total Non-Linearity ${ }^{3}$
For Midrange Outputs Centered About Zero Volts
( $1 / 4$ FSR):
Initially
$\pm 4 \mathrm{ppm}$ FSR max., ( $\pm 2 \mathrm{ppm}$ FSR typ.)
After 3 years (calculated)
$\pm 25 \mathrm{ppm}$ FSR max.
Over the Full Scale Range
$\pm 15 \mathrm{ppm}$ FSR max., (DAC w/Distortion Suppressor' $- \pm 25 \mathrm{ppm}$ FSR max.)
Absolute Range (Gain) Accuracy
$\pm 0.01 \mathrm{~dB}( \pm 0.1 \%)$, (DAC w/Distortion
Suppressor ${ }^{1}- \pm 0.2 \mathrm{~dB}( \pm 2 \%)$
Offset Voltage
$\pm 20 \mathrm{mV}$ max., (DAC w/Distortion Suppressor ${ }^{1}$ $\pm 30 \mathrm{mV}$ max.)
Zero Code $\mathbf{0}^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Continuous and monotonic through zero
Noise ${ }^{4}$ (referenced to rms full scale)

- 113 dB rms, (DAC w/Distortion Suppressor ${ }^{1}$ -
-110 dB rms)


## STABILITY

Tempco of Differential Non-Linearity
For Midrange Outputs Centered About Zero Volts ( $1 / 4$ FSR)
$\pm 1 \mathrm{ppm}$ FSR/ ${ }^{\circ} \mathrm{C}$ max.
( $\pm 0.25 \mathrm{ppm}$ FSR/ $/{ }^{\circ} \mathrm{C}$ typ.)
Over the Full Scale Range
$\pm 2 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ max., ( $\pm 0.5 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ typ.)
Tempco of Gain $\left(0^{\circ} \mathrm{C}\right.$ to $70^{\circ} \mathrm{C}$ average; includes
reference) ${ }^{5}$
$\pm 30 \mathrm{ppm}$ of READING $/{ }^{\circ} \mathrm{C}$ max., ( $\pm 10 \mathrm{ppm}$ of
READING/ ${ }^{\circ} \mathrm{C}$ typ.), (DAC w/Distortion Suppressor ${ }^{1}$
$- \pm 50 \mathrm{ppm}$ of READING $/{ }^{\circ} \mathrm{C}$ max., ( $\pm 20 \mathrm{ppm}$ of
READING $/{ }^{\circ} \mathrm{C}$ typ.))
Tempco of Offset Voltage ${ }^{6}$
$\pm 5 \mathrm{ppm}$ FSR/ ${ }^{\circ} \mathrm{C}$ max., (DAC w/Distortion
Suppressor' $- \pm 7 \mathrm{ppm}$ FSR $/{ }^{\circ} \mathrm{C}$ max.)

Power Supply Sensitivity
Range (Gain)
20 ppm FSR/
Offset
$35 \mu \mathrm{~V} / \mathrm{V}$
Time Stability
see Non-Linearity spec
Warm-Up Time to Specified Accuracy
3 minutes max.

TRANSFER CHARACTERISTICS
Frequency Response ${ }^{7}$
N/A, ((DAC w/Distortion Suppressor' - See
Theory of Operation)
Settling Time for 5 Volt Step
To 0.01\%
$3.5 \mu \mathrm{~s}$, (DAC w/Distortion Suppressor ${ }^{1}$ - N/A)
To 1 LSB
$6 \mu \mathrm{~s}$, (DAC w/Distortion Suppressor ${ }^{1}$ - N/A)
To Desired Gain Accuracy
N/A, (DAC w/Distortion Suppressor ${ }^{1}$ -
Determined by time constant ( $\tau$ ) and system
timing ( $3.4 \mu \mathrm{~s} \tau$ std.; consult factory for other $\tau$ 's))
Slew Rate
7.5 V/ $/ \mathrm{S}$ min., (DAC w/Distortion Suppressor ${ }^{1}$ Time constant limited response)

## INTERNAL REFERENCE

## Nominal Voltage

$+5 \mathrm{~V}$
DC Output Impedance
$0.1 \Omega$ max.
Load Current
1 mA max.

## DIGITAL INPUTS <br> Definition

16 data bits per Decoding Table, (Distortion Sup-
pressor - 1 Mode Control signal
Logic Compatibility
CMOS
5 V only, (Distortion Suppressor - N/A)
TTL
With external pull-up to +5 V supply, (Distortion
Suppressor - TTL)
Low Level
0 V to +1 V (FALSE), (Distortion Suppressor - OV
to $+0.5 \mathrm{~V}(\mathrm{ON}))$
High Level
+4 V to +5 V (TRUE), (Distortion Suppressor +3 V to +5 V (OFF))
Required Rise and Fall Time N/A, (Distortion Suppressor - 5 ns max.)

## POWER REQUIREMENT ${ }^{8}$

Nominal Voltage
$\pm 9 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$
Absolute Max. $\pm 16 \mathrm{~V}$
Current, Exclusive of Load $\pm 23 \mathrm{~mA}$ typ.
Dissipation @ $\pm 9 \mathrm{~V}$, Exclusive of Load 430 mW max.

Dissipation @ $\pm 15 \mathrm{~V}$, Exclusive of Load 750 mW max.

## ENVIRONMENT

Rated Performance
$0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$
Operating Temperature Range
$-25^{\circ} \mathrm{C}$ to $+85^{\circ}$

## Storage Temperature Range

$-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing, up to $40^{\circ} \mathrm{C}$

PACKAGING (Modupac ${ }^{\text {TM }}$ )
Dimensions, Inches ( $\mathbf{m m}$ rounded)
2" X 4" x 0.44 "
( $50.8 \mathrm{~mm} \times 101.6 \mathrm{~mm} \times 11.2 \mathrm{~mm}$ )
Electromagnetic Shielding
5 sides
Electrostatic Shielding
6 sides

## NOTES

1. These specifications apply when the distortion suppressor and the DAC are used in combination per Figure 1. For distortion suppressor-only specifications, consult factory.
2. Peak line harmonic distortion as measured by spectrum analyzer with 100 Hz bandwidth @ $25^{\circ} \mathrm{C}$ nominal; specification assumes that interconnections and timing for DAC and distortion suppressor are per recommendations.
3. Deviation from best straight line.
4. 20 kHz bandwidth, measured with a distortion suppressor duty cycle of $50 \%$ and 50 kHz sampling frequency. Noise in OFF mode is 3 dB greater than in ON mode.
5. For bipolar signals, $X$ ppm of READING is less than or equal to $\mathrm{X} / 2 \mathrm{ppm}$ of FSR, e.g., 2 ppm of READING $\leq 1 \mathrm{ppm}$ FSR.
6. Total at OV, not affected by reference drift.
7. For flat system frequency response, post filtering that follows the distortion suppressor should include a zero at 46 kHz to cancel the pole that exists at 46 kHz in the distortion suppressor. It should also compensate for the $(\sin x) / x$ attenuation that is introduced by any sampled data process. For related information, see the Analogic Data Conversion Systems Digest, Ed. 4, esp. pp. 160-162, 215-217, 223 and 224.
8. Analog Return, Output Return, and Case are tied internally.

## Description (cont.)

for low cost systems that require long term stability exceeding several years. Accepting a variety of standard input codes, the DAC circuit employs a proprietary (pat. pending) internal sign/magnitude architecture that provides better than 18 -bit linearity for signals in the critical zero crossover region ( $\pm 1 / 8$ full scale range), yet offers $3.5 \mu \mathrm{~s}$ settling time to $0.01 \%$ of a 5 V step - a speed sufficient for multiple broadcast-grade channels. In this internal architecture, the most significant bit weighting resistances make no contribution to small signals. This contrasts dramatically with the commonly-used offset binary architecture, in which a heavily weighted resistor predominates at midrange, enabling even small resistor errors and drifts to degrade midrange linearity by the equivalent of several bits and to cause large zero crossover distortions. Low sensitivity to resistor error, combined with high-quality stabilized resistors, renders the differential linearity of the MP1936 for signals more than 18 dB down virtually immune to temperature changes (typically less than 1 LSB of drift over a $60^{\circ} \mathrm{C}$ span) and yields a three-year no adjustment differential linearity drift of less than $\pm 25 \mathrm{ppm}$, meeting the critical long-term fidelity criteria and economic goals established for many unattended remote communication stations.
The distortion suppressor - used to sample the DAC's output value and then hold it while the DAC is being switched to a new value suppresses the DAC's code-dependent switching glitches.* Its $3.4 \mu \mathrm{~s}$ output time constant prevents slew-rate-limiting output distortions, yet provides full power response for signals up to 46 kHz in the sampling mode. This unique amplifier has been specifically developed for low-distortion applications, because conventional sample and hold circuits commonly used as deglitchers have been found to distort high-frequency or high-amplitude signals.
High speed, low noise and low distortion over the dynamic range from peak power to studio quiet, ease of use including CMOS and TTL logic compatibility, and wide environmental latitude qualify the MP1936 for many of the most demanding digital communication applications.

[^12]
## SYSTEM PERFORMANCE FEATURES

An internal sign/magnitude architecture provides accurate large signal performance and superior low level performance, particularly when compared to the commonly used offset binary internal architecture. A complete modular subsystem based on this approach, the MP1936 conserves pc board area, power, and design \& production expense when compared to circuits based on offset binary IC converters, making it easy to use in many applications.

## Optimized for Audio Applications

Analogic instrumentation grade converters have served the needs of digital audio system designers for over a decade. In the late 1970's, to meet their expressed needs for lower-cost, optimized converters, a high-speed sign/ magnitude architecture was developed. This architecture is particularly suited to reconstructing dynamic complex waveforms, such as speech or music, that: 1) have a substantial amount of their information content in the vicinity of "zero volts" (midrange on a bipolar scale), and 2) may occasionally peak well above the rms level.
Differential linearity in the region near zero has been identified as the critical parameter for such signals. With the commonly used offset binary architecture, which produces a bipolar output by offsetting an internal unipolar signal by one half full scale,


NOTE: A time-constant limited response affects all input voltage changes in the same proportion as long as the settling time allowed is constant. For this example, the ON time of $16.5 \mu \mathrm{~s}$ (approximately 5 time constants) results in a gain error of 0.1 dB . If required, this gain reduction can be corrected by the system's gain adjustment.
even a small error in the offsetting resistor can frequently cause relatively large differential linearity errors near zero volts. Further, for a zero crossing, all bit-weighting resistors are switched, further degrading differential linearity and increasing susceptibility to harmonic distortion, granularity noise, and similar audio artifacts. These effects are often magnified by the $\pm 15$ $\mathrm{ppm} / \mathrm{year}$ to $\pm 100 \mathrm{ppm} /$ year tracking ratio drift of many commonly used bit-weighting resistors. Thus, all offset binary converters are virtually useless in the critical audio region after a short time in the field.
In contrast, with a sign/magnitude internal architecture, step size error decreases as the signal approaches zero volts from either direction, and no current-weighting resistors are switched for a zero crossing.* In the MP1936, the six most significant current-weighting resistors make no contribution to signals that are down by -41 dB or more from peak full scale, ensuring ultra-linear performance in the most critical audio range. This basic architectural advantage, coupled with over a decade of experience in the manufacture of precision data converters, makes this module optimum for high quality, low cost communication applications. Even for outputs larger than - 18 dB , the increment between codes equals the LSB step size of 15 ppm FSR plus a differential nonlinearity of only $+13 /-9 \mathrm{ppm}$ FSR, ensuring both monotonicity and no missing steps over the entire output range.

## A Complete Modular Subsystem

Traditionally, designers and manufacturers of telecommunications systems have been required to select separate DAC and deglitch circuits, test each one, then mate them and test the combination. Further, most high resolution integrated circuit DAC's commonly available in the audio speed range require an external reference supply, multiple external operational amplifiers, power supply decoupling capacitors, and trimming potentiometers consuming equal or more printed circuit board area than does the MP1936. In addition, they frequently require tedious and expensive offset zeroing operations via the external potentiometers, with questionable stability and reliability.

[^13]The MP1936, on the other hand, requires no external potentiometers. Its stability obviates the need for routine linearity, gain, or offset adjustments, increasing reliability and decreasing field support cost. As a completely engineered subsystem, the MP1936 conserves user design time significantly; as a fully assembled and tested subsystem, it conserves production labor cost as well as component cost when compared to the total cost of an IC-based equivalent subsystem.

## Using the MP1936

The MP1936 provides decoding and interconnect flexibility as well as control simplicity, facilitating use in a variety of applications.
Input Decoding The MP1936's digital-toanalog converter may be connected to accept any one of four input code types: offset binary, two's complement, sign/magnitude, or modified sign/magnitude. The input data is automatically converted, if necessary, to the sign/magnitude code used internally-the user need only interconnect the module per the Code Selection Table.
Note that the Input Decoding Table defines the transfer function of the DAC only; the distortion suppressor inverts the DAC's output. (The table is presented on a DAC-only basis for consistency among applications, independent of the number and type of postDAC processing channels.)
Control Only the input data and one control line are needed to operate the MP1936. The DAC updates upon receipt of each new code word-no separate selection or enable signals are required. Per the Typical Timing Diagram, the control line is used to select the distortion suppressor's mode: a logical zero places this amplifier in the ON (input connected) mode; a logical one places it in the OFF (input disconnected) mode. Recommended switching rates are from 5 kHz to 128 kHz .
Interconnect Flexibility The DAC's output and the distortion suppressor's input are both available to the user on external pins, providing for special purpose processing and multiple-channel hookups (see Typical Applications). It is recommended that MP201A Distortion Suppressors be used to deglitch any additional channels that use the same DAC. The primary circuit in that module is essentially identical to the MP1936's distortion suppressor, ensuring identical performance in all channels.

Logic Compatibility The digital data may be supplied via either CMOS or TTL devices. However, if TTL is used, an external pull up resistor to +5 V is needed on each data input line. The distortion suppressor's mode control input must be TTL.
Power Supply The MP1936 operates from a bipolar supply at any voltage from $\pm 9 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$. Thus the module may be isolated from the system's $\pm 15 \mathrm{~V}$ supplies via simple regulators.
Interchangeability The mechanical dimensions of the MP1936 are identical to those of the industry standard professional audio DAC, the MP1926A, and the pinouts are nearly identical. MP1926A users who wish to convert to the MP1936 may do so with a minimum of external jumpers. For related information, consult your Analogic Representative.

## THEORY OF OPERATION

## D/A Converter

Figure 2 shows the theoretical transfer function of a sign/magnitude digital-to-analog converter (DAC). Per Figure 1, this is implemented by first decoding the digital input word (converting it to the sign/magnitude code used internally), then: 1) applying the 15 LSB's to a magnitude DAC and 2) applying the MSB (sign bit) to configure an amplifier that either follows or inverts the magnitude signal.
The classical problem of attaining both low offset drift and high speed simultaneously from a sign/magnitude circuit has been solved by using a unique amplifier in the Magnitude DAC. (An offset error in the magnitude signal would cause a discontinuity whenever the sign switches at a zero crossing, and would cause the output to be asymmetric about OV.) Earlier sign/magnitude approaches have met this low offset requirement by using slow amplifiers, limiting their applicability. The MP1936's magnitude amplifier is both chopper stabilized and fast. Offset drift of this amplifier is an extremely low $1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$, yet settling time to 1 LSB , including the sign switching amplifier, is only $6 \mu \mathrm{~s}$. The MP1936's performance is, therefore, symmetric about zero yet fast enough for quality audio applications.

## Distortion Suppressor

All digital-to-analog converters, including the MP1936's Magnitude DAC, generate some dynamic distortion while they are being updated from one "steady-state" value to
another. This distortion results primarily from code-dependent switching glitches associated with the DAC's current-weighting network. To reject these glitches, the distortion suppressor uses a holding capacitor and a pair of high-quality analog switches in addition to an inverting amplifier (Figure 1). The switches select one of two modes, as follows:
When the DAC output has settled to some desired value, the distortion suppressor is commanded to the ON mode: shunt switch " $A$ " opens and series switch " $B$ " closes, connecting the settled DAC output to the distortion suppressor's output. In this mode the distortion suppressor's output response is exponential, with the $3.4 \mu \mathrm{~s}$ time constant provided by the holding capacitor and feedback resistor being sufficient to avoid slew rate limiting effects for up to $\pm 5 \mathrm{~V}$ signals.*
When the DAC is updating to a new value, the distortion suppressor is commanded into the OFF mode: the switch positions reverse, shunting the changing DAC output signal to ground and allowing the previous DAC output level, now stored on the holding capacitor, to continue as the distortion suppressor's out-
put. In this mode, its output is isolated from the DAC's transients. (Feedthrough of a $\pm 5 \mathrm{~V}$ sine wave injected at the distortion suppressor's input pin during this mode is typically down -90 dB !)
When the distortion suppressor is switched between its two modes, it will pass signals up to 20 kHz without introducing noticeable distortion. For example, the peak line distortion for a full amplitude sine wave at 20 kHz (switching rate $=50 \mathrm{kHz}$ ) is -86 dB with respect to the $\pm 5 \mathrm{~V}$ level! Clearly, the transfer function of this circuit is related to both the ON time ( $\mathrm{t}_{0}$ ) and the sampling period ( T ) chosen for operation. The theoretical relative frequency response can be obtained by taking the convolution of the transfer functions of the two circuit configurations shown at the bottom of the Typical Timing Diagram. At dc, the distortion suppressor's gain is -1 . The transfer function is included in an application note available from your Analogic Representative.

[^14]

Figure 2. Comparison of Performance Near Zero The transfer function of a converter using an internal sign/magnitude approach originates at 0 V (all current switches off), so the OV output is not affected by linearity or
gain drifts. With an offset binary approach, the transfer function originates at $-1 / 2$ FSR (all current switches off), and any linearity or gain drift will shift the OV output as shown.

## TYPICAL APPLICATIONS

## Stereo Broadcast Link

Figure 3 illustrates a high performance, yet low cost method for simultaneously updating a stereo pair of analog outputs, at rates up to 55 kHz , from 16 -bit resolution data ( 98 dB dynamic range). A conventional implementation would require two DAC's plus digital buffering to achieve simultaneous updating. The MP1936, with a voltage settling time of only $6 \mu \mathrm{~s}$ to 1 LSB for a large step, allows both channels to be updated from a single DAC within the $18 \mu \mathrm{~s}$ available. The only buffering required for simultaneous updating can be provided by an additional, external distortion suppressor such as the Analogic AH201-1.
The timing diagram shows that the $\mathrm{S} / \mathrm{H}$ samples the DAC's output during a time slot assigned to Channel 1. It then holds this new Channel 1 level while the DAC output settles to a new Channel 2 level. Due to the AH201's


Figure 3. Simultaneous Updating of Stereo Audio Channels with a single D/A @ 55 kHz sampling rate per channel and 16-bit resolution.
low feedthrough in the HOLD mode, the Channel 2 information and glitches will have negligible effect on Channel 1. When the inputs to the distortion suppressor and the first AH201 contain stable new data, both of these circuits are switched ON, causing both channels to be updated simultaneously.*
*For more complete implementation information, consult your Analogic Representative.


Figure 4. Non-Simultaneous Updating of Multiple Audio Channels with a single D/A @ 15 kHz bandwidth per channel (16-bits of resolution).

## Satellite Downlink

The MP1936 also provides an economical method for restoring channels sequentially. For example, a satellite ground station used in a program channel distribution service would be required to update multiple audio outputs, but not necessarily simultaneously. Figure 4 illustrates one possible implementation using a single DAC to sequentially update four, 15 kHz bandwidth, audio channels. A nominal 32 kHz sampling rate per channel is assumed. This means that the DAC must update four channels every $31.2 \mu \mathrm{~s}$ or one channel every $7.8 \mu \mathrm{~s}$, which is well within the settling capability of the MP1936. The distortion suppressor in each channel is simply turned on for the last $4.3 \mu \mathrm{~s}$ of the corresponding MP1936 update period.

## Performance In An Audio Sampled Data System

A complete digital audio system - using an Analogic SHAD-2 A/D conversionsystem* for digitally encoding analog input signals and an MP1936 for decoding the digital data to recover them - has been evaluated. The spectral analyses presented here indicate that end-to-end performance of the total system is well within the fidelity criteria of studio transmission links for both low level and high level signals.
The peak harmonic distortion measured for high frequency, full scale signal was only $-89 \mathrm{~dB}(-101 \mathrm{~dB}$ referenced to full scale). These measurements show the accumulated effects of distortion produced by all of the components in the audio sampled data system as well as by the input signal generator used. Thus it is reasonable to conclude that the performance of the MP1936 alone during these test runs was signficantly better than the -89 dB and -60 dB measured for the total system!
On the basis of these tests, MP1936 performance exceeded the specifications ( -86 dB and -50 dB ) notably, a characteristic not uncommon with Analogic products. The unit tested was selected from a production prototype lot. As the MP1936 has no external adjustments, no special tweaking was performed for these tests; the results shown here may be considered representative of typical, adjustment-free audio fidelity.


Spectrum Analyzer Recordings ( 100 Hz bandwidth) for Reconstructed Sine Wave Signals. For a high frequency, full scale test tone, the largest harmonic measured in the 20 Hz to 20 kHz band was -89.0 dB ; for a low-level tone, the largest harmonic in this band was -60.8 dB . Filtering was not used in this test. In most applications, output filtering would remove the components above 20 kHz , including those which result from foldback on the sampling frequency, $\mathrm{f}_{\mathrm{s}}$.

[^15]
## Telephone Group Set PCM/FDM Conversion

The output frequency band in a pulse code modulation (PCM)/frequency division multiplexed (FDM) telephone baseband group is 60 kHz to 108 kHz , with a data update rate of 112 kHz . To minimize the amount of $(\sin x) / x$ correction required and to reduce the energy present at the sampling frequency, the distortion suppressor may be modified (consult the factory) to switch its input between ground and the newly settled DAC output, rather than between a stored level and the newly settled DAC output. Switching to ground is coincident with the update of the DAC; typically $t_{o}$
may be $1 / 4$ to $1 / 2$ of $T$. The large dynamic range and low distortion of the MP1936 result in negligibly low crosstalk. Measured under standard telephone conditions, the noise power ratio (NPR) is better than 64 dB when tested in a loop back system.


PCM/FDM Telephone Application


## Offset Binary

| B1, B2, $, \ldots, \quad$ B15, B16 | Bipolar Output |
| ---: | ---: |
| 1111111111111111 | +4.999847 V |
| 1000000000000000 | 0.000000 V |
| 0000000000000000 | -5.000000 V |

## Two's Complement

| B1, B2, $\ldots, \quad$ B15, B16 | Bipolar Output |
| :---: | ---: |
| 011111111111111 | +4.999847 V |
| 000000000000000 | 0.000000 V |
| 1000000000000000 | -5.000000 V |
| Sign/Magnitude |  |


| B1, B2, $\ldots, \quad$ B15, B16 | Bipolar Output |
| ---: | ---: |
| 111111111111111 | +4.999847 V |
| 1000000000000000 | +0.000000 V |
| 0000000000000000 | -0.000000 V |
| 0111111111111111 | -4.999847 V |

## Modified Sign/Magnitude

| B1, B2, $\ldots, \quad$ B15, B16 | Bipolar Output |
| ---: | ---: |
| 0111111111111111 | +4.999847 V |
| 0000000000000000 | +0.000000 V |
| 1000000000000000 | -0.000000 V |
| 1111111111111111 | -4.999847 V |

## DIA Converter Input Decoding*

*This table defines the transfer function of the sign/magnitude D/A conversion circuit only. Note that the distortion suppressor circuit inverts the polarity of the D/A OUT signal.

|  | MODULE CONNECTIONS |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| CODE | $\begin{gathered} \text { SIGN } \\ \text { to } \end{gathered}$ | $\begin{gathered} \text { CONTROL } \\ \text { to } \end{gathered}$ | $\begin{aligned} & \text { B1 CONTROL } \\ & \text { to } \end{aligned}$ | $\begin{gathered} \text { CODE SET } \\ \text { to } \end{gathered}$ |
| Offset Binary | SIGN OUT | SIGN OUT | REF OUT | REF OUT |
| 2's Complement | SIGN OUT | SIGN OUT | OUT RET | REF OUT |
| Sign/Magnitude* | SIGN OUT | OUT RTN | REF OUT | OUT RTN |
| Modified Sign/Magnitude* | SIGN OUT | OUT RTN | OUT RET | OUT RTN |

## ORDERING GUIDE

For digital-to-analog decoding with low distortion over a 98 dB dynamic range, Specify $\square$ MP1936

For a complete family of digital audio data conversion/ translation building blocks, consult your Analogic representative.


ANALDG옾
MP8116
16-Bit D/A Converter

## Description

The MP8116 is the ultimate in precision, high stability, 16 -bit digital-toanalog converters. Originally developed for nuclear physics experimentation applications, the MP8116 is ideally suited for any application where differential linearity, accuracy and stability over time and temperature are critical.
The MP8116 features both Relative Accuracy and Differential NonLinearity of better than 0.25 LSB. Tempco of Differential Non-Linearity is an outstanding $0.25 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum, giving the MP8116 solid 16 -bit accuracy over a full $30^{\circ} \mathrm{C}$ temperature range. All other parameters are commensurate with this level of performance, thus making the MP8116 the ultimate in precision and stability.

## Features

- True 16-bit accuracy $\pm 0.25$ LSB maximum Relative Accuracy $\pm 0.25$ LSB maximum Differential Non-Linearity
- Exceptional Temperature Stability
0.25 ppm $/{ }^{\circ} \mathrm{C}$ Differential NonLinearity Tempco
- Separate Analog and Digital Grounds
■ Dual-Feedback Load Sensing
- Low Power Dissipation


## Applications

- Automatic Test Equipment
- Calibration Standards
- Laser-trimming and Scribing Systems
- Profilers
- Phototypesetting
- Digitally controlled Power Supplies
- Precision Function Generation


Figure 1. MP8116 Block Diagram.

## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG OUTPUTS

## Fault Protection

Outputs may be short-circuited to ground indefinitely

## VOLTAGE MODE

Full-Scale Ranges
$\pm 10.00000 \mathrm{~V}, \pm 5.00000 \mathrm{~V}$ and OV to
+10.00000 V ; determined at time of order
Output Impedance
$<0.1 \Omega$ at dc

## Output Configuration

Balanced 4-wire for remote sensing
Load Current
2 mA maximum
Settling Time
$25 \mu \mathrm{~s}$ maximum to $1 / 2$ LSB for full scale step

## Slew Rate

$18 \mathrm{~V} / \mu \mathrm{s}$ minimum

## CURRENT MODE

Full Scale Range
-1.00000 mA to +1.00000 mA (Bipolar);
0.00000 mA to -2.0000 mA (Unipolar)

Output Impedance
$3.33 \mathrm{k} \Omega$ bipolar
$5 \mathrm{k} \Omega$ unipolar
Voltage Compliance
$\pm 0.5 \mathrm{~V}$ maximum
Settling Time
$10 \mu \mathrm{~s}$ maximum to $1 / 2$ LSB for full scale step

## INTERNAL REFERENCE

Voltage Output
+10V nominal
Output Impedance
$0.1 \Omega$ nominal
Output Load Current
1 mA maximum

## ACCURACY

Absolute Accuracy
Relative Accuracy $\pm 2$ ppm NBS traceable
Relative Accuracy
$\pm 0.00022 \%$ FSR typical,
$\pm 0.00037 \%$ FSR maximum
Differential Non-Linearity
$\pm 0.00012 \%$ FSR typical,
$\pm 0.00037 \%$ FSR maximum
Noise
<1.5 ppm FSR rms typical, 3 ppm FSR rms maximum over 20 Hz to 100 kHz ;
$<1$ ppm FSR, p-p typical, 2 ppm FSR p-p maximum from dc to 100 Hz

## STABILITY (Tempco)

Differential Nonlinearity
$\pm 0.07 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typical, $\pm 0.25 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Gain
$\pm 0.23 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typical
$\pm 0.44 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum
Offset
$\pm 2.3 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ typical,
$\pm 5.6 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ maximum
Power Supply Sensitivity

## Offset

$20 \mu \mathrm{~V} / \mathrm{V}$ maximum
Gain
$20 \mathrm{ppm} / \mathrm{V}$ maximum
Recommended Recalibration Interval 3 months

## DIGITAL INPUTS

## General

TTL compatible, one unit load Positive true

## Coding

Binary or two's complement (specify when ordering)

## ENABLE

Logic "1", output follows input data; logic "1" to " 0 " transition latches input data into registers

## POWER REQUIREMENTS

$+15 \mathrm{~V}, \pm 3 \%$
20 mA maximum
$-15 \mathrm{~V}, \pm 3 \%$
50 mA maximum
$+5 \mathrm{~V}, \pm 5 \%$
75 mA maximum

## ENVIRONMENTAL AND MECHANICAL

Storage Temperature
$-10^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Operating Temperature
$+5^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Temperature Range for Rated Temperature
Coefficients
$+20^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$
Relative Humidity
5\% to 90\% non-condensing
Warm-up Time to Specified Performance
20 minutes
Dimensions
$3.875^{\prime \prime} \times 7.09^{\prime \prime} \times 0.5^{\prime \prime}$ nominal
( $98.4 \times 180.2 \times 12.7 \mathrm{~mm}$ )
Mating Connector
30 pin, 0.156 " spacing;
Viking 2V K 15D/1-2 or equivalent
Two Analogic 15-300004 supplied

## USING THE MP8116

## General

Integration of the MP8116 in a system is relatively straight-forward. The separation of analog and digital grounds, the fourwire output load sensing, and both current and voltage output modes combine to allow maximum flexibility in implementation.

## Digital Control

The digital input latches are 74L75 registers. When the ENABLE line is high, the output of the MP8116 will follow the data present at the inputs. When the ENABLE line is brought low, the data present at the inputs at the transition will be latched into the registers.

## Digital Data

The coding of the digital data is selected at the time of ordering and cannot be changed by the user. Binary and two's complement coding can be accommodated.

## Grounding

The Analog and Digital grounds in the MP8116 are totally separate. Depending on the application, the grounds can be maintained separated, or can be tied together at the MP8116 connector.

## Current Output

The current output full scale range is determined at the time of manufacture and is not user selectable. The MP8116 can be used in the current mode, even if a voltage mode version has been ordered. In this case, the current range will correspond to the voltage range, i.e. a unipolar current with a unipolar voltage range model, and a bipolar current output with a bipolar voltage range model.

## Voltage Output

The voltage output full scale range must be determined at the time of ordering and is not user selectable. Full scale output ranges of 0 V to $+10 \mathrm{~V}, \pm 10 \mathrm{~V}$ and $\pm 5 \mathrm{~V}$ are accommodated.
Remote sensing capability of the load voltage is provided. Connect the load as shown in Figure 2.

## TYPICAL APPLICATIONS

Figure 3 shows the MP8116 used as part of a function generator, the application for which it was originally developed. In this application, the DAC is used to program the current


Figure 2. Voltage Output Circuit.


Figure 3. Function Generation.
in the magnets of a particle accelerator. Open-loop programming of the DAC would cause small but intolerable "steps" in the generated current-time function, $\mathrm{f}(\mathrm{t})$, as shown in the insert. The circuit shown* achieves virtually perfect smoothing of the function, at high speeds, without introducing significant error.
In operation, the computer presets a 16 -stage counter to the $Y_{0}$ intercept of the desired function, and also programs a rate multiplier to control the clock pulses that advance the counter. The counter state is the input code to the MP8116, so that the rate-multiplier coefficient actually establishes the slope of the function at any time. The output of the MP8116 is, then, the quantized value of $f(t)$. A comparator then compares this quantized value with the smoothed value, which is derived from the output of an integrator. The input of the integrator is the output of the same MP8116 DAC, whose input code is generated

[^16]by the state of a presettable up-down counter. This up-down counter stores counts generated by logic driven by the output of the comparator. Thus, if the sensitivity of the comparator is of the order of $1 / 2$ LSB (8 ppm of full scale), the integrator output will not be more than 1 LSB different from the quantized $f(t)$, but the output $f(t)$ is smoothed by the integration.

## Testing Converters and Precision DVM's (Figure 4)

The MP8116 is the ideal device for testing and calibrating high-resolution D/A converters, A/D converters, and DVM's up to $51 / 2$ decimal digits, because of its high absolute accuracy and linearity. In figure 4 we show a digital programming source that might be anything from a set of 16 switches (for manual testing) to a digital computer, including test-program RAM, ROM, digital controllers, etc. The analog output of the MP8116 is then used as the input to the A/D Converter or DVM under test, and its output is then compared with the programmed input to the MP8116. (To test D/A converters, the digital code is fed to both the MP8116 and the DAC under test, and their analog outputs are compared in a null detector of adequate sensitivity.)


## Computer-Programmable Voltage/Current Source for Precision ATE Systems (Figure 5)

In Figure 5, we see one of the most important applications of the MP8116: its use as a computer-programmable voltage or current source in high-speed automatic test equipment (ATE). Here again, the high accuracy and linearity of the MP8116, and its relatively fast settling time, provide measurement capability and confidence levels not previously available for less than 3-5 times the cost of the MP8116. Note the use of optical couplers at the digital input, for full floating analog output, and the use of load-sensing in the voltage mode. The low-cost Analogic MP3020 dc/dc converter power supply shown will preserve the isolation of the output, and eliminate consideration of common-mode noise errors.


Figure 5. Precision ATE Voltage/Current Source.

Figure 4. Testing Converters or DVM's.

| FORMAT | INPUT CODE | OUTPUT |
| :---: | :---: | :---: |
| Monopolar | 0000000000000000 | 0.000000 Volts |
| 10 V Span | 1111111111111111 | 9.999847 Volts |
| Bipolar | 0000000000000000 | -5.000000 Volts |
| 10 V Span | 1000000000000000 | 0.000000 Volts |
|  | 1111111111111111 | 4.999847 Volts |
|  | 0000000000000000 | -10.000000 Volts |
| 20 V Span | 1000000000000000 | 0.000000 Volts |
|  | 1111111111111111 | 9.999695 Volts |
| Two's | 100000000000000 | -10.000000 Volts |
| Complement | 0000000000000000 | 0.000000 Volts |
| 20V Span | 0111111111111111 | 9.999695 Volts |
| Monopolar | 0000000000000000 | 0.000000 mA |
| Current 2 mA Span | 1111111111111111 | - 1.999969 mA |
| Bipolar | 0000000000000000 | 1.000000 mA |
| Current | 1000000000000000 | 0.000000 mA |
| 2 mA Span | 1111111111111111 | -. 999969 mA |

Table 1 Digital Input Data Coding


## ORDERING GUIDE



## Description

The Analogic MP8308 and MP8318 are fast, low cost, functionally complete digital-to-analog converter subsystems designed for video and graphic display applications.
The MP8318 accepts 8 data bits, at rates up to 100 MHz , into a set of strobed latches and converts the data into a very fast rise time (3 ns) analog output. The output drives a terminated $75 \Omega$ coaxial cable directly, producing a 1V output. This module provides output steps so clean that deglitching is not required (see oscillo-photos). If the 8 -bit video input represents a digitized composite video signal, the MP8318 will produce a composite video output.
The MP8308 retains all of the features offered by the MP8318 and produces a composite video output signal with 256 gray levels, including setup, blanking and sync, all derived from separate digital inputs. The output is in general conformance with EIA Standards RS170 and RS343A, and will directly drive the composite video input of high-resolution TV monitors. Both units are available with TTL or ECL logic interfaces, and operate from +5 V and -5 V (or -5.2 V supplies. They are packaged in fully shielded $2 \times 3 \times 0.35$-inch metal cases, thus allowing $1 / 2$-inch board spacing.

## Features

- 100 MHz Update Rate, ECL
- 40 MHz Update Rate, TTL
- $<3$ ns Rise and Fall Times
- Direct Drive to 75 R Coaxial Cable or TV Monitor
- No Deglitching Required
- Strobed Input Data Register
- Low Cost

■ + 5V, - 5V Supplies

- Low Profile, 9 mm (.350') Shielded Case


## MP8308 ONLY

- RS343A Compatible Signal
- Composite Blanking
- Composite Sync
- Adjustable Setup

■ 8-Bit Gray Scale/256 Levels

## Applications

## - Raster-Scan High Resolution Monochrome Video <br> - Raster-Scan High Resolution Color Video <br> - Graphic Display Systems <br> - Function Generation <br> - Time Base Correction



Figure 1. MP8308 Functional Block Diagram.

## SPECIFICATIONS

## OUTPUT CHARACTERISTICS

Output Voltage Range
OV to $-1 \mathrm{~V} \pm 5 \%$ into $75 \Omega$ termination
Output Current
$-13.3 \mathrm{~mA}$
Recommended Load Impedance
$75 \Omega \pm 5 \%$, dc to $>10 \mathrm{MHz}$
Source (Thevenin) Impedance
$75 \Omega \pm 5 \%$, dc to 50 MHz
Output Bandwidth
$>100 \mathrm{MHz}$ @ -3 dB

## LSB Size

3.9 mV nominal, MP8318
2.5 mV nominal, MP8308

Rise and Fall Time
3 ns typ., 4 ns max. ( $10 \%$ to $90 \%$ )
Full Step Settling Time
7.5 ns typ. to 1 LSB ( $0.4 \%$ )

Glitch Settling Time
5 ns to <1 LSB, for worst (MSB) transition Glitch Area
Equivalent to 1 LSB step @ 50 MHz update rate, typical
For MP8308, worst case area $=70 \mathrm{pV} / \mathrm{s}$ max., $50 \mathrm{pV} / \mathrm{s}$ typ.

## TRANSFER CHARACTERISTICS

## Resolution

8 bits, 256 levels
Coding
Binary. An input code of 11111111 (All High) produces OV out. Input $=00000000$ produces -1 V
out, (MP8318), or -0.643 V out, (MP8308)
See "Video Characteristics"
Differential Linearity
$\pm 1 / 2$ LSB max. @ $25^{\circ} \mathrm{C}$
Monotonicity
Guaranteed, $10^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$
Offset (dc output with 11111111 input)
$\pm 1 / 2$ LSB max., $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$
Transfer Gain (Slope) Tempco
$\pm 0.02 \% /{ }^{\circ} \mathrm{C}$ max.
Propagation Delay
ECL Version: 7 ns, typ., strobe to output, 50\% points
TTL Version: 10 ns, typ., strobe to output, 50\% points

## INPUT CHARACTERISTICS

## Update Rate

ECL: 100 MHz
TTL: 40 MHz

## Input Register

8 ECL Type D Flip-Flops in all versions. TTL version also includes built-in TTL to ECL translators in data input lines and strobe

## Strobe Input

Data entered on positive-going edge (timing reference)

## Setup

ECL: 2.5 ns min. before strobe
TTL: 7.0 ns min . before strobe
Hold
ECL: 1.5 ns min.
TTL: 6.0 ns min.

## Logic Levels

TTL version: standard 7400 TTL Levels
ECL version: 10,000 series ECL on Data and
Strobe inputs only; TTL levels on control logic
Data Input Loading
ECL: 5 pF and $50 \mathrm{k} \Omega$ (to -5 V )
(Each of 8 Inputs)
TTL: two-unit load
Strobe Input Loading
ECL: 40 pF and $6 \mathrm{k} \Omega$ (to -5 V )
TTL: two-unit load
Control Input Loading (MP8308: Blanking, Sync, and Ref. White, MP8318: Set and Reset)
All versions, TTL levels; <2 units each line

## POWER SUPPLY REQUIREMENTS

## Supply Volgage

Two supplies for all units, +5 V and -5 V , nominal
Positive Supply
$5.0 \mathrm{~V} \pm 5 \%$ @ 25 mA for MP83XX ECL; @ 50 mA for MP83XX TTL
Negative Supply
-4.75 V to $-5.5 \mathrm{~V} @ 340 \mathrm{~mA}$ for MP83XX ECL; at 450 mA for MP83XX

## Supply Regulation

Negative supply should not have more than
5 mV p-p ripple

## Supply Common

Digital Return is the common for the +5 V and -5 V supplies

## ENVIRONMENTAL AND PACKAGING <br> Operating Temperature Range <br> $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$

## Storage Temperature

$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
0 to $85 \%$, non-condensing up to $40^{\circ} \mathrm{C}$
Mechanical Dimensions
2" $\times 3$ " x 0.35 "
( $50 \times 75 \times 9 \mathrm{~mm}$ )
Shielding
Steel case with electromagnetic shielding 5 sides, electrostatic shielding 6 sides

## System Performance

The MP8308 provides three circuit functions: an input data register, eight equi-delay switches, and a high-speed summation network. The register flip-flops are ultra-high speed ECL units that are selected for minimum differential delay. The flip-flops drive high-speed switches that steer current into a summing network.The network has a Thevenin impedance of $75 \Omega$; the input current develops a $1 \mathrm{Vp}-\mathrm{p}$ signal directly into a $75 \Omega$ load. Due to the unusually small differential delay among the eight data channels, the glitches introduced by code switching are invisible, even on the best monitors. In addition, because the network directly generates the required output voltage, no amplifier or buffer is needed, which results in an unusually clean transition at the output with an extremely fast rise time.

## The MP8308 Composite Video DAC

The MP8308 has two additional current switches in the equi-delay bank: one to inject the Blanking level and one for the Sync level, as required to generate a composite video signal. The MP8308 therefore provides higher resolution than other video DAC designs, since none of the 8 -bit video gray scale levels are used in generating the Sync signal levels. In addition to preserving full resolution, this approach permits direct control of the amount of Setup. In critical applications, such as computerized tomography (CT), varying the picture brightness is helpful in delineating suspected areas. Heretofore, this was accomplished by manually adjusting the brightness control on the TV monitor. The problem, however, is to restore the picture to its original brightness; this is especially important in the case of color.

The Setup control provides a means for varying brightness in reproducible steps. TV monitors cut off the picture tube in response to the Blanking level, producing the blackest possible visual picture. The Setup control varies the offset between Reference Black level and Blanking level which produces an apparent shift in the "brightness" of Reference Black.
The MP8308 has additional user flexibility, achieved by the addition of a Reference White control. Assertion of this input drives the output to its most positive voltage; the Reference White level.

Reference White sets the input register, which turns OFF the eight gray scale current switches. The Sync or Blanking inputs reset the input register, producing full scale output from the gray scale current switches; the output of the Sync or Blanking current switches is added to the full scale output. Obviously Reference White should not be activated during the Sync or Blanking intervals.


Figure 2. MP8308 Block Diagram.

## The MP8318 High Speed DAC

The MP8318 scale output of 1V peak is fully controlled by the 8 -bit data word. The MP8318 may be connected to the output of a video ADC, to regenerate a TV image on a monitor. In this example, it is assumed that the input digital data of 8 -bits includes the Sync tips.
The Set and Reset inputs of the input register are available on terminals, as shown in Fig. 3; they produce zero or fullscale outputs, respectively, when activated. The MP8318 is ideally suited for time base correction and function generation applications.


Figure 3. MP8318 Block Diagram.

## Operation with other than a - 5.0V supply

The MP8308 and MP8318 series are capable of operation from a negative supply voltage between -4.75 V to -5.5 V . The output amplitudes specified are nominal values based upon a -5.0 V supply, and will change in direct proportion to the negative supply voltage.
Additionally, the glitch area will vary as a function of the negative supply voltage. The factory trim is carried out at -5.0 V . If other than -5.0 V is used, connect a $10 \mathrm{k} \Omega$ potentiometer as shown, to the Glitch Adjust Terminal. Adjust this pot for minimum glitch area at the major carry transition. If -5.0 V is used, this pot may be omitted and the Glitch Adjust Terminal left open.


Figure 4. Glitch Adjustment.

## Broadcast Usage

EIA Industrial Electronics Tentative Standard No. 1 which will, in the future, become a part of RS170-A, details the exact waveform and timing characteristics of the composite video signal at the output of a color television studio.
The products described in this data sheet are in general conformance with such needs. Exact compliance requires additional circuitry which would, at a minimum, provide Sin XIX correction and bandwidth filtering. In addition, the Setup on the MP8308 should be changed to 7.5 IRE units, by placing a resistor of about 560 ? between the Setup terminal and ground.

## APPLICATION INFORMATION

## Bandwidth

The output bandwidth may be reduced, if desired, by adding a small capacitor across the DAC output. This will result in slower rise times. The absolute glitch amplitude will decrease, but the energy (or net area) of the glitch will be unchanged.

## ECL Terminators

The MP8308ECL and MP8318ECL units do not include ECL terminating resistors. If the source of the video data and strobe is more than a few inches away from these units, ECL terminators should be connected in close proximity to the inputs of the DACs.

## Grounds

The DIG RTN, ANA RTN and STROBE RTN terminals are all tied together internally. The +5 V and -5 V supply common should be connected to DIG RTN. If a long printed circuit wiring connection is required for integration of the DAC into a video system, stripline wiring techniques may be implemented by taking advantage of the physical arrangement of the output terminals i.e., the ANA RTN terminals are located on each side of the VIDEO OUT terminal. ANA RTN normally connects to the shield of an external $75 \Omega$ coaxial cable. STROBE RTN is included as a convenience and may be used optionally to facilitate connection.

## 3262A TV Timing Generator

The sync and blanking outputs of this device may not be capable of driving the MP8308 series, under worst case conditions, without the use of a logic driver.

## Data Input Timing

All timing is referenced to the positive edge of the strobe. On ECL units, a Setup of 2.5 ns minimum and a Hold of 1.5 ns minimum, from strobe, are required. On TTL units, 7.0 ns and 6.0 ns are required, respectively, for Setup and Hold.

This example underscores the simplicity achieved when using the MP8308 in a display system. Digital video data, digital sync and digital blanking are converted directly to a composite monitor input. Analog mixing and/or generation of the sync/blanking is not required, nor is a separate high power driver amplifier required ahead of the monitor. Input video data need not be "aligned" to achieve low glitch performance. In fact, a "deglitcher" is not needed, or even built into the MP8308/MP8318 series; the design is inherently low glitch.


Figure 5. Typical Application of MP8308 in Small Display System.


Figure 6. Typical Glitch at Major Carry (worst case transition). Glitch is approximately 40 mV -ns.

Figure 7. Typical MP8308/MP8318 Output for Full Scale Step.


Figure 8. Composite Video Output (not to scale).

## VIDEO CHARACTERISTICS (MP8308 ONLY)

```
Composite Video Signal
Consists of 256 gray levels plus blanking level
and sync level
Gray Scale Range
0.643 Vp-p
Step Size
2.5 mV step
Reference White Level
OV, absolute; +0.714 V (100 IRE Units) relative
to blanking level with standard Setup; +0.643 V
relative to Reference Black
Input Code for White Level
11111111
Reference White Control
Logic " 0 " (TTL) on Ref. White line overrides
video input data and drives the output to 0 V
Reference Black Level
-0.643 V , absolute; +71 mV (10 IRE Units)
relative to blanking level with standard Setup
Input Code for Reference Black Level
0000000
Composite Blanking Level
Composite Video Signal
Consists of 256 gray levels plus blanking level and sync level
Gray Scale Range
0.643 Vp-p
Step Size
2.5 mV step
Reference White Level
to blanking level with standard Setup; +0.643 V
relative to Reference Black
Input Code for White Level
11111111
Reference White Control
Logic " 0 " (TTL) on Ref. White line overrides drives the output to \(0 V\)
Relerence Black Level
relative to blanking level with standard Setup
Input Code for Reference Black Level
0000000
```

-0.714 V , absolute, with standard Setup
-0.714 V , absolute, with standard Setup

Input Command for Blanking/Pedestal Level
Logic " 0 " (TTL) on "Blanking" line
simultaneously resets input register to
00000000
Composite Sync Level
-1.0 V absolute with standard Setup; - 0.286 V
( -40 IRE Units) with respect to blanking level
(back porch)
Input Command for Sync Level
Logic " 0 " (TTL) on "Sync" line simultaneously
resets input register to 00000000
Sync and Blanking Rise and Fall Times
$<100$ ns
Sync and Blanking Overshoot
$<2 \%$
Setup (Reference Black-to-Blanking)
Externally programmable from 0 mV (0 IRE Units) to 142 mV (20 IRE Units)
Setup Control Line
Input Open: Standard 71 mV (10 IRE Units)
Setup. Input tied to -5 V : 142 mV (20 IRE Units).
Input tied to gnd: 0 mV (0 IRE Units)

## GLOSSARY OF VIDEO TERMS

## Composite Video Signal

The combined video signal, with or without Setup, plus the Sync signal.

## Video Signal

The visually perceived portion of the composite video signal which varies in gray scale levels from Reference White to Reference Black. Also known as the picture signal.

## Sync or Composite Sync Signal

That portion of the composite video signal which synchronizes the scanning process.

## Sync Level

The level of the peak of the Sync signal.
Setup
The difference in level between the Reference Black level and the Blanking level. Not to be confused with setup as used in conjunction with digital logic.

## Blanking Level

The level which separates the Sync portion from the video signal, with or without Setup. This level is sometimes also called the pedestal, back porch or front porch. It usually refers to the level which will cut off the TV tube, producing the blackest possible visual picture.

## Reference Black Level

The maximum negative polarity amplitude of the video signal.

## Reference White Level

The maximum positive polarity amplitude of the video signal.

## Gray Scale

The discrete levels of the video signal between Reference White and Reference Black levels.

## Raster-Scan

The basic method of sweeping across a CRT, a line at a time, to generate and display pictures such as used in commercial TV in the USA.

## Monochrome Video

Conventional black-and-white television video in which the Z-axis, or intensity, of the beam is modified during scanning to shade and/or outline images.

## Color Video (RGB)

As used herein, this refers to the method of generating color images by combining the three primary colors of red-green-blue (RGB). The associated monitor would be identified as an "RGB" monitor. Three MP8308 series D/A converters are required to drive such a monitor, one each for red, green and blue.


Figure 9. MP8308/MP8318 Outline Dimensions.

ORDERING GUIDE
For 100 MHz ECL Input 8 -bit D/A: Specify MP8318 ECL.
For 40 MHz TTL Input 8 -bit D/A: Specify MP8318.
For 100 MHz ECL Composite Video D/A: Specify MP8308 ECL.
For 40 MHz TTL Composite Video D/A: Specify MP8308.

Selection Guide
.7-2
Glossary. ..... 7-3
MP3015 + 5V In, $\pm 15 \mathrm{~V}$ @ 100 mA Out, DC/DC Converter ..... 7-5
MP3020 +5 V In, $\pm 15 \mathrm{~V} @ 150 \mathrm{~mA}$ Out, DC/DC Converter ..... 7-9
MP3024 +5 V In, $\pm 15 \mathrm{~V} @ 75 \mathrm{~mA}$ Out, DC/DC Converter ..... 7-13
MP3026 +5 V In, $\pm 15 \mathrm{~V} @ 150 \mathrm{~mA}$ Out, DC/DC Converter ..... 7-13
MP3035 + 5V In, $\pm 15 \mathrm{~V} @ 165 \mathrm{~mA} \&+5 \mathrm{~V}$ @750 mA Out DC/DC Converter.7-17

## ANALDGㅗㅛ

## SECTION 7 <br> DC/DC Converters

SELECTION GUIDE

| MAJOR CHARACTERISTIC OR APPLICATION REQ'MT | PRIMARY PARAMETER | SECONDARY PARAMETER | RECOMMENDED MODEL NO. | DATA SHEET ON PAGE |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \pm 15 \mathrm{~V} \text { Output } \\ & @ 75 \mathrm{~mA} \end{aligned}$ | Load Regulation $\pm 0.75 \%$ for NL-FL | Line <br> Regulation $\pm 1 \%$ for $\pm 5 \%$ change | MP3024 | 7-13 |
| $\pm 15 \mathrm{~V}$ Output <br> @ 100 mA | Load Regulation $\pm 0.01 \%$ for 10 mA change | Line Regulation $0.1 \%$ for 4.5-5.5V change | MP3015 | 7-5 |
| $\pm 15 \mathrm{~V}$ Output <br> @ 150 mA | Load Regulation $\pm 0.1 \%$ for NL-FL | Line Regulation $\pm 0.1 \%$ for $\pm 5 \%$ input change | MP3020 | 7-9 |
|  | Load Regulation $\pm 0.2 \%$ for NL-FL | Line <br> Regulation $\pm 0.2 \%$ max. $\pm 5 \%$ change | MP3026 | 7-13 |
| $\pm 15 \mathrm{~V}$ Output <br> @ 165 mA <br> $\pm 5 \mathrm{~V}$ Output <br> @ 750 mA | Load Regulation 0.1\% max. ( $\pm 15 \mathrm{~V}$ ) 1\% max. NL-FL (5V) | Line <br> Regulation <br> 0.1\% max. <br> $( \pm 15 \mathrm{~V})$ <br> 1\% max. <br> for 4.5-5.5V | MP3035 | 7-17 |

## GLOSSARY OF TERMS

## DC-TO-DC CONVERTERS

DC-TO-DC CONVERTER A circuit that converts +5 V power to highly stable, highly regulated $\pm 15 \mathrm{~V}$ power for bipolar analog circuitry. In addition to stability and regulation, DC-to-DC converter requirements include higher isolation, higher efficiency, EMI and RFI shielding, and short circuit protection. See Figure 1.
EFFICIENCY A ratio, expressed in percentage, of output power at full load divided by input power.
ISOLATION Breakdown voltage between the input and the output.
KICKBACK Noise fed back to the input of the converter as a result of inductive switching.

LINE REGULATION A measure of the ability of the converter to maintain its output voltage when the input voltage changes, e.g., $\pm 0.1 \%$ for $\pm 5 \%$ input change.

LOAD REGULTATION A measure of the ability of the converter to maintain its output voltage when the load changes, e.g., $\pm 0.1 \%$ for no load to full load.

LOAD TRANSIENT RECOVERY The time it takes the output to settle to its rated value after a specified step change in the load, e.g., $100 \mu \mathrm{~s}$ to settle to rated output with change from $1 / 2$ load to full load.

PEAK TRANSIENT The maximum noise level, in a given bandwidth, at the output of a converter, as a result of a specified step change in the load, e.g., 50 mV typical for full load change.


Figure 1. Functional Block Diagram of a DC- to-DC Converter.


## ANMLOCB.

MP3015
Stable, Dual Output $\pm 15 \mathrm{~V}$ out/ +5 V in dc/dc Converter

## Description

The MP3015 is a highly regulated, dual-tracking and very stable dc-todc converter, operating from a +5 V supply. It provides an output current of 200 mA maximum from both +15 V and -15 V outputs, with each output limited to 100 mA . It has the ability to sense and correct output voltages at local or remote loads.
Without remote sensing, the load regulation provided by the MP3015 is $\pm 0.1 \%$ maximum, for a $\pm 10 \%$ change in load. When the 3 -wire remote sensing capability is utilized, load regulation improves to $0.01 \%$ for the same change in load.
The excellent line regulation of the MP3015 maintains the $\pm 15 \mathrm{~V}$ output to $\pm 0.1 \%$ with variations up to $10 \%$ in the +5 V input supply voltage.
Short circuit protection is provided by fold-back-type output current limiting. In addition, the +5 V supply input is protected from transient loading by an integral LC filter network. Typical output noise is below 1 mV rms , or 20 mV peak, in a 10 MHz bandwidth.

Low current density connections to the MP3015 have been realized through the use of multiple parallelwired pins for each input and output terminal. The unit is packaged in a $2 \times 2 \times 0.44$ inch module. Gold-plated 0.025 in. diameter pins, with standard 0.1 in . spacing, allow mounting of the module on standard circuit boards designed for 16-pin IC packages.
The use of a metal case guarantees stable operation under all ambient electrostatic and electromagnetic conditions and permits freedom of physical positioning without any risk of mutual interference.

## Features

■ $\pm 15 \mathrm{~V}$ Output @up to 200 mA Total Current

- Operates from +5V Source
- Voltage Correction with Remote Sensing Feature
$\square \pm 0.01 \%$ Line Regulation
- Output Impedance Less Than $0.1 \Omega$
- 1 mV rms Maximum Noise

■ Short Circuit Protected

- Fast Load Transient Recovery
- Metal Construction

Combines Heat Sink with
Superior Shielding

- Compact:
2.0 " $\times 2.0^{\prime \prime} \times 0.44$ "
( $51 \times 51 \times 11 \mathrm{~mm}$ )


## Applications

- Circuits requiring monitoring of load voltages, for critical $\pm 15 \mathrm{~V}$ stability and correction
- Circuits requiring good load regulation for large changes in load

Figure 1. MP3015 Functional Block Diagram.

## SPECIFICATIONS

## ELECTRICAL PERFORMANCE <br> Temperature Coefficient <br> 200 ppm $/{ }^{\circ} \mathrm{C}$ <br> Noise <br> Less than 1 mV rms ( 20 mV peak) with 10 MHz bandwidth <br> Line Regulation <br> $\pm 0.1 \%$ max. change in output voltage for $\pm 10 \%$ change in input supply voltage <br> Load Voltage Sensing Capability <br> Local or Remote <br> Load Regulation <br> Without remote sensing: $\pm 0.1 \%$ change in output voltage from 10\% change in load. <br> Remote sensing: $\approx \pm 0.01 \%$ change in output voltage for $10 \%$ change in load <br> Transient Recovery <br> $100 \mu \mathrm{~s}$ to settle to rated output with change from $1 / 2$ load to full load <br> Warm-Up Time <br> Essentially zero <br> Shielding <br> Electrostatic all sides; electromagnetic all sides except bottom <br> Output Short Circuit Protection <br> Either side to ground: indefinitely. Both sides to ground: 5 min. max. Short circuit (foldback current: 40 mA max.

## ELECTRICAL INTERFACE

## Output Voltage

+15 V and $-15 \mathrm{~V} \pm 0.7 \%$
Output Current
@ $0^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$ : 200 mA max. Total from both +15 V and -15 V outputs, but not more than 100 mA from either output
$@+35^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ : 150 mA max. total from both +15 V and -15 V outputs, but not more than 100 mA from either output dc Output Impedance

## $<0.1 \Omega$

Maximum Voltage Between Input and Output Returns
50V
External Load Capacitance
No maximum
Input Power Requirements
$+5 \mathrm{Vdc} \pm 10 \%$ @ 1.1 amp , full load; no-load input current $=180 \mathrm{~mA}$

## PHYSICAL

## Size

$2.0 \times 2.0 \times 044^{\prime \prime}$
$(51 \times 51 \times 11 \mathrm{~mm})$
Metal encased module
Pin Configuration
0.025 inch diameter gold-plated pins arranged for 16 pin DIP sockets or P.C. mounting Repairability
Factory repairable

## ENVIRONMENTAL

Temperature Range
Operating: $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$. Non-operating $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Case Temperature $25^{\circ} \mathrm{C}$ max. above ambient (case may be connected to heat sink if desired)

## Application Data

## Remote Sensing:

To utilize the remote sensing capability of the MP3015, sever the three printed circuit foil connections between the three pairs of adjacent pins, as indicated by the asterisks in Figure 3, and connect separate sensing lines between the $+15 \mathrm{~V},-15 \mathrm{~V}$, and OUT RTN terminals of the load circuit and the corresponding sense terminals of the Converter. In Figure 3, the supply buses are indicated by bold lines, with sensing lines shown lighter.


Figure 2. Outline and Mounting Dimensions.


Figure 3. Connections for Remote Sensing.

Specify MP3015.


## ANALOGC.

## MP3020

Ultra-Isolated
$+5 \mathrm{~V} \operatorname{In} / \pm 15 \mathrm{~V}$ Out dc Power Converter

## Description

The MP3020 is a tightly regulated, highly isolated, and very stable dc-todc converter. It is ideal for driving analog circuitry from digital logic power sources where exceptional efficiency and an extra margin of power are needed. Excellent regulation circuits end spiking problems and limit output voltage variations to 0.1 percent with either an input voltage change of 10 percent or an output change from no load to full load. Typical noise is $700 \mu \mathrm{~V} \mathrm{rms}$ or 11 mV p-p across a 20 MHz bandwidth. Positive and negative output circuits can deliver 150 mA individually or 300 mA combined. At maximum load ( 4.5 W ), this converter is 65 percent efficient. It draws only 1.4A from a 5 V supply, minimizing heat dissipation, and it requires no added heat sinking, as do many other converters, to operate without derating. Noise coupling, either back to the digital supply source or forward to the analog circuitry, is minimized, making the MP3020 ideal for noise-sensitive computerconverter environments.
Sophisticated multiple shielding minimizes the threat of interference, enabling the designer to position


Figure 1. Functional Block Diagram.
this converter in nearly any desired location. A phenolic board protecting the base prevents the possibility of etch run shorts.
Internal limiting of the individual output current to 225 mA protects the MP3020 against short circuits, and an integral filter network protects input circuitry against transients on the source lines.

## Features

- Offers unmatched isolation: $80 \mathrm{pF}, 10^{12} \Omega, 1000 \mathrm{~V}$
- Delivers 4.5 watts of usable power at 65 percent efficiency
- Operates reliably without heatsinking over full load and temperature ranges
- Only 0.375 inches high for plugin or PC mounting with 0.5 -inch card cage spacing
- Recovers from full-load transients in $25 \mu \mathrm{~s}$


## Applications

- Driving floating front ends in AID and D/A conversion systems
- Driving floating operational amplifier, permitting it to operate with high common mode voltages
- Driving strain gauges and load cells


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## ANALOG OUTPUTS

Voltage
+15 Vdc and $-15 \mathrm{Vdc}, \pm 0.5 \%$ max. (tracking)

## Current

150 mA max. each side, 300 mA max. total
Current Limit (Internal)
$225 \pm 50 \mathrm{~mA}$ at $25^{\circ} \mathrm{C}$
Output Capacitance
$10 \mu \mathrm{~F}$
Load Capacitance
Virtually no limit

## Load Regulation

$\pm 0.1 \%$ max. for no-load to full-load change

## Line Regulation

$\pm 0.1 \%$ max. for $a+5$ to $-5 \%$ change or a - 5
to $+5 \%$ change in the input voltage
Load Transient Recovery
$20 \mu$ s typical, $50 \mu \mathrm{~s}$ max. to $0.1 \%$ after a full-

## load change

Peak Transient
50 mV typical for full-load change, 25 mV typical for a half-load change, both at 10 MHz bandwidth
Temperature Coefficient $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ., $\pm 100 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max.
Noise
1 mV rms typ., 40 mV p-p max., both at 20 MHz bandwidth
Short-Circuit Protection
Current limited on both sides, without foldback, to $225 \pm 50 \mathrm{~mA}$

## ANALOG INPUTS

Voltage
$5.0 \pm 0.25 \mathrm{~V}$

## Current

1.75 mA typ., 200 mA max. at no load, 1.45 amp . max. at full load

## Reflected Input Ripple Current

$25 \mathrm{~mA} p-\mathrm{p}$ typ., 50 mA p-p max., with full load change

## CHOPPER FREQUENCY <br> 25 kHz nominal

## EFFICIENCY

$65 \%$ typical at 5.0 V input voltage and full load

## ISOLATION

Resistive Coupling
$10^{12} \Omega$ typical, $10^{10}$ minimum
Capacitive Coupling
80 pF typical, 100 pF maximum
Breakdown Voltage
1000 V typical, 500 V minimum

## Shielding

Electromagnetic, 5 sides

## PHYSICAL

## Size

$2.0 \times 2.0 \times 0.375$ inches ( $50.8 \times 50.8 \times 9.6 \mathrm{~mm}$ )

## Weight

3.5 oz. max. (99.23g)

## Pin Size

0.040 by 0.35 inches ( $1.0 \times 8.9 \mathrm{~mm}$ ), hardened brass

## ENVIRONMENTAL

Operating
$-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Non-Operating
$-40^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Case Temperature Rise
$31^{\circ} \mathrm{C}$ max. (after 30 minutes), $10^{\circ} \mathrm{C} /$ watt dissipated in package (i.e., at full load, 3.5 watts are dissipated in package)


Figure 2. Outline and Mounting Dimensions.

## ORDERING GUIDE

## Description

The MP3024 and MP3026 are dc/dc converters specifically designed for powering and floating analog circuits from +5 V logic-level power supplied without inducing "kickback" errors onto the logic circuits that share the same +5 V source. Two mdoels are available, each providing a +15 V output and a slaved -15 V output; the MP3024 provides a total of 2.25 W of output power, and the MP3026 provides 4.5W for higher power applications.

Besides a high efficiency of approximately $60 \%$ and good regulation, both supplies offer other electrical and mechanical features making them suited to numerous real-world applications. Up to 500 V of isolation is provided between the input and the outputs, so that analog circuits powered by these supplies reject the error effects of high common mode voltages arising in many real-world environments. This isolation also prevents such voltages from being coupled back to, and damaging, the host digital system.
As a result of the high efficiency design, very little heat is dissipated so that rated performance may be
(continued)


Figure 1. MP3024/MP3026 Functional Block Diagram.

## Features

- Low Cost
- High Isolation

500 Vdc min. breakdown voltage

- Choice of Power Ratings

Up to 75 mA min. output at +15 V and at $-15 \mathrm{~V}(150 \mathrm{~mA}$ min. total, MP3024)
Up to 150 mA , min. output at +15 V and at $-15 \mathrm{~V}(300 \mathrm{~mA}$ min. total, MP3026)

- Integral Pi Filtering Low kickback without external circuitry - less than 50 mA p-p @ 35 kHz (MP3024)
- High Efficiency

60\% full load efficiency (MP3024)
Operation without heat-sinking

- Good Regulation
0.2\% load regulation

200 mV p-p load transient response
0.2\% line regulation (MP3026)

- Low Profile Metal Case $0.375^{\prime \prime}$ height - compatible with 0.5 " - centers ( 12.70 cm ) board mounting Electromagnetic and electrostatic sheilding
- High Temperature Operation Up to $70^{\circ} \mathrm{C}$ without derating (MP3026)
- Fully Specified Performance Fully tested and burned-in (with temperature/load cycling) to ensure dependability


## Applications

- Powering bipolar analog circuits from a +5 V supply
- Powering floating operational amplifiers in high common-mode-voltage environments
- Powering floating front ends in A/D and D/A conversion systems
- Exciting strain gauges and load cells
- Powering simultaneouslysampling medical instrumentation front-ends


## SPECIFICATIONS

(All specifications guaranteed at $25^{\circ} \mathrm{C}$ unless otherwise noted)

## OUTPUTS

## Voltage

+15 Vdc and $-15 \mathrm{Vdc} \pm 5 \%$ max.

## Current

MP3024 - 75 mA min. at +15 Vdc and 75 mA
min . at -15 Vdc ( 150 mA min. total)
MP3026 - 150 mA min. at +15 Vdc and 150
mA min. at -15 Vdc ( 300 mA min. total)

## Power

MP3024-2.25W, min.
MP3026-4.5W, min.
Output Capacitance
$6.8 \mu \mathrm{~F}$ nom.
Load Capacitance
Unlimited
Line Regulation
MP3024 - $\pm 1.0 \%$ max. ( $\pm 0.5 \%$ typ.) for a $\pm 5.0 \%$ change in the input voltage
MP3026 - $\pm 0.2 \%$ max. for a $\pm 5.0 \%$ change in the input voltage
Load Regulation
MP3024 - $\pm 0.75 \%$ max. ( $\pm 0.2 \%$ typ.) for noload to full load change
MP3026 - $\pm 0.2 \%$ max. for no-load to full-load change
Temperature Coefficient $\pm 0.03 \%{ }^{\circ} \mathrm{C}$ max.

## Transient Response

(for an instantaneous change from 50\% load to full load on either or both outputs)
200 mV p-p output transient, max. ( 10 MHz bandwidth), settling to within specified load regulation tolerance in $50 \mu \mathrm{~s}$

## Noise \& Ripple

75 mV p-p and 3 mV rms max. ( 10 MHz bandwidth)
Short Circuit Protection without damage
Both outputs to each other, or either output to ground
Current Limit (internal)
MP3024-300 mA max. at + 15 Vdc; 300 mA max. at -15 Vdc
MP3026 - 600 mA max. at $+15 \mathrm{Vdc} ; 600 \mathrm{~mA}$
max. at -15 Vdc

## INPUT

Voltage
$+5.00 \mathrm{~V} \pm 0.25 \mathrm{~V}$
Current
MP3024 - 0.75A, max., @ full load \& nominal voltage
MP3026 - 1.55A, max., @ full load \& nominal voltage

## Power

MP3024 - 3.75W
MP3026 - 7.25W

## Reflected Input Ripple Current

MP3024 - 50 mA p-p max., at 35 kHz MP3026 - 75 mA p-p max., at 35 kHz

## Input Protection

Reverse polarity, indefinite without damage

## CONVERSION \& ISOLATION

## Efficiency

MP3024-60\% min., at nominal +5 V input and 150 mA output
MP3026-58\% min., at nominal +5 V input and 300 mA output
Resistive Coupling (input to output) $10^{9} \Omega$ typ.
Capacitive Coupling (input to output) 50 pF typ.
Breakdown Voltage (input to output)
500 Vdc min.
Shielding
Electromagnetic, 5 sides; Electrostatic, 6 sides
Chopper Frequency
35 kHz

## ENVIRONMENTAL \& MECHANICAL

Operating Temperature
MP3024- $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ in free air (derated to $\pm 50 \mathrm{~mA}$ output at $70^{\circ} \mathrm{C}$ )
MP3026- $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ in free air (no derating)

## Case Temperature Rise

MP3024-30 ${ }^{\circ} \mathrm{C}$ max. above ambient
MP3026-35 ${ }^{\circ} \mathrm{C}$ max. above ambient

## Non-Operating Temperature

$-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Relative Humidity
$5 \%$ to $95 \%$, non-condensing, to $+40^{\circ} \mathrm{C}$
Size
MP3024-1.000 x $2.000 \times 0.375^{\prime \prime}(25.4 \times 50.8 \times$
9.5 mm )

MP3026-2.000 x $2.000 \times 0.375$ " ( $50.8 \times 50.8 \times$
9.5 mm )

Weight
MP3024 - 1 oz. max. ( 28.4 gm )
MP3026-2 oz. max. ( 56.7 gm )
Case Potential
Tied to Output Return

## Description (cont.)

obtained without heat-sinking. A metal case is standard, providing RFI shielding on six sides, and EMI shielding on five. The case's low profile ( 0.375 ') allows printed circuit board spacing of only 0.5 " ( 12.70 mm ) on centers.
These supplies are reliable in a variety of usage situations, incorporating protection for both the inputs and the outputs. Each unit is exhaustively tested and burned-in with on/off cycling, load variations, and temperature cycling to ensure reliable operation under all operating conditions. Further, the MP3026 affords operation up to $70^{\circ} \mathrm{C}$ without derating.
The reliability, high performance, and low cost of these converters qualify them for driving operational amplifiers, strain gauges, and many other circuits for which precision and dependability must be achieved at low cost.

MOUNTING DIMENSIONS \& PINOUTS


ORDERING GUIDE

| For | Specify |
| :--- | ---: |
| 2.25W output | MP3024 |
| 4.5W output | MP3026 |



## ANMLOGBO

MP3035
+5 V In
Isolated +5 V Out \& Isolated $\pm 15 \mathrm{~V}$ Out DC Power Converter

## Description

Analogic's MP3035 is a compact dc-to-dc power converter that provides exceptionally high levels of efficiency, isolation, and reliability, with a full 9 watts of output... enough to power a complete A/D or D/A data system. It provides a very high degree of isolation, both from input to output and between the analog ( $\pm 15 \mathrm{~V}$ ) and digital ( 5 V ) grounds. Noise, ripple, and heat dissipation are all minimized in this systemoriented design.
The positive and negative analog outputs can deliver 165 mA each, and the +5 V output is rated at 750 mA . Load and line regulation are typically $0.02 \%$ on the $\pm 15 \mathrm{~V}$ outputs and $0.1 \%$ and $0.01 \%$ on the +5 V output.
The isolated grounds suppress digital interference in the analog section, and eliminate system ground-loop problems. Commonmode voltages may be as high as 500 V .
In addition to positive, non-foldback constant-current limiting of all three outputs, each is provided with a thermal-shutdown feature that protects semiconductor junctions. In the Fault Mode, any output shorted to its respective common will survive eight hours, at a $\mathrm{T}_{\mathrm{A}}$ of $+71^{\circ} \mathrm{C}-\mathrm{a}$ period generally adequate to locate a system short.
Only derated computer-grade components are used in the MP3035, and each unit is subjected to 100 -hour burn-in after assembly, to assure the highest reliability. Thermal resis-

## Features

■ Excellent Isolation - 75 pF , $10^{\circ} \Omega, 500 \mathrm{~V}$. Separate analog and digital grounds

- Complete EMI/RFI Shielding continuous six-sided package shield, $\pi$-type input filter, multiple transformer shielding
- Double Protection - special constant-current limiting (no latchdown); thermal shutdown for long-term fault protection
- Low surface temperature rise $5^{\circ} \mathrm{C}$ per package watt dissipated
■ High reliability - 100\% burn-in, components derated, operates without heat sinking over full load and temperature range
- Fast full-load transient-recovery time - $25 \mu$ s maximum
- Separate Analog and Digital Grounds - System ground loops eliminated, low digital noise interference
- Low Noise - Minimizes openboard noise and shielding problems


## Applications

- A/D \& DIA Converters and Data Acquisition Systems - linear, digital circuitry, CMOS, DTLTTL, Function Modules, LSI Memory Standby Power Source (from batteries)
■ Portable Data Systems mobile instrumentation
- Transducer Excitation - driving strain gauges and load cells (continued)


Figure 1. MP3035 Functional Schematic Diagram.

## SPECIFICATIONS

## OUTPUTS

Voltage, E1 \& E2
+15 Vdc and $-15 \mathrm{Vdc}, \pm 0.2 \%$ typ. $\pm 1 \%$ max. (tracking)

## E3

$+5 \mathrm{Vdc} \pm 4 \%$ max.
Voltage Balance, E1 to E2
$\pm 0.5 \% \pm 1 \%$ max.
Rated Current
E1 \& E2
$\pm 165 \mathrm{~mA}$
E3
$\pm 750 \mathrm{~mA}$
(all three outputs may be fully loaded simultaneously)
Constant Current Limiting, E1 \& E2
I thresh = 250 mA ; Issg $=300 \mathrm{~mA}$
E3
I peak $=2.2 \mathrm{~A}$; $\mathrm{Issg}=750 \mathrm{~mA}$
Voltage Limiting (O.V.P.), E3
6.8V

Load Regulation (NL-FL), E1 \& E2
$\pm 0.02 \%$ typ., $\pm 0.1 \%$ max.
E3
$\pm 0.1 \%$ typ., $\pm 1 \%$ max.
Line Regulation (full range),
E1 \& E2
$\pm 0.02 \%$ typ., $\pm 0.1 \%$ max.
E3
$\pm 0.1 \%$ typ., $\pm 1 \%$ max.
Average Voltage Temperature Coefficient, E1 \& E2
$\pm 0.003 \%$ typ., $\pm 0.015 \%$ max.
E3
$\pm 0.02 \%$ typ., $\pm 0.05 \%$ max.
Voltage Stability after Initial Warmup, E1 \& E2
$\pm 0.01 \%$ max. $/ 1 \mathrm{hr} . \pm 0.05 \% / 24 \mathrm{hr}$.
E3
$\pm 0.05 \%$ max. $/ 1 \mathrm{hr} . \pm 0.2 \% / 24 \mathrm{hr}$.
Initial Voltage Warmup Drift, E1 \& E2
$\pm 20 \mathrm{mV}$ typ., $\pm 90 \mathrm{mV}$ max.
E3
$\pm 40 \mathrm{mV}$ typ., $\pm 90 \mathrm{mV}$ max.
Initial Warmup Time ( $\pm \mathrm{FL}$ )
60 minutes
Load Transient Recovery (NL-FL; error band $\pm 0.1 \%$ )
$25 \mu$ s typ., $50 \mu \mathrm{~s}$ max.
Noise, Bandwidth $=20 \mathrm{MHz}( \pm F L)$, E1 \& E2
1 mV max. rms, 15 mV p-p typ., 40 mV p-p max.
E3
1.2 mV max. rms, 20 mV p-p typ., 40 mV p-p max.

## Short Protection

Any output to its respective common will survive 8 hr . at $\mathrm{T}_{\mathrm{A}}$ of $+71^{\circ} \mathrm{C}$

Output Power
8.7 watts

## INPUTS

## Voltage Range

$\pm 5.00 \mathrm{Vdc} \pm 0.500 \mathrm{Vdc}$

## Current

3.48A (FL), 0.50A (NL)

## Power Interruption

Restarts in Fault Mode. Restarts with reverse current injected into output.

## Converter Start-up

$\mathrm{E}_{\mathrm{IN}}<1 \mathrm{Vdc}$
Converter Switching Frequency
$>20 \mathrm{kHz}$ (inaudible)
Power Efficiency
50\%
Reflected Input Ripple Current
$2 \%, 3.5 \%$ p-p max. of $I_{I N}$
(Bandwidth $=20 \mathrm{MHz}, \pm \mathrm{FL}, \mathrm{R}_{\mathrm{S}}=0.25$ terminated)
70 mA p-p
Input Fault Mode Current
7A (worst case)

## ISOLATION

Input to Output
Effective "C", E1 \& E2
150 pF
E3
75 pF
Effective "R"
$10^{\circ} \Omega \mathrm{min}$.
E1, E2 to E3 Output
Effective "C"
110 pF
Effective "R"
$10^{9} \Omega$ min.
Breakdown Voltages
500 Vdc min.
COMMON MODE NOISE CURRENT
$\left(\mathrm{CM}_{\mathrm{IN}}\right)$ Bandwidth $=20 \mathrm{MHz}( \pm \mathrm{FL})$,
RS $=50$ R $\mathrm{E} 1 \& \mathrm{E} 2$
$500 \mu \mathrm{~A}$ p-p
E3
$700 \mu \mathrm{~A}$ p-p

## EMI/RFI SHIELDING

Transformer
Mulitple Shielding
Internal Input Filter
$\pi$-type
Package
6 sides, continuous

## PHYSICAL

## Size

3.00 " $\times 2.56 " \times 0.75^{\prime \prime}$
$(76.2 \times 65.0 \times 19.1 \mathrm{~mm})$

## Weight

12 oz. (340.2g)
Pin Size
0.040 " dia. x 0.25 "
( 1.02 dia. $\times 6.35 \mathrm{~mm}$ )

## ENVIRONMENTAL

Operating Temperature Range
$-25^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$
Storage Temperature Range
$-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Case Temperature Rise
$5^{\circ} \mathrm{C} /$ Package watt dissipated

## Description (cont.)

tance paths $\left(\theta_{\mathrm{J}-\mathrm{C}}\right)$ are of the order of $50 \%$ less than in comparable power-supply modules. Surface temperature rise is only $5^{\circ} \mathrm{C}$ per package watt dissipated and, at maximum load, the MP3035 is $50 \%$ efficient.
Sophisticated multiple shielding of transformer and case, including an internal $\pi$ type input filter, effectively minimizes interference. The converter may thus be positioned in nearly any desired location.

## DIMENSIONS \& PIN CONNECTIONS



ANALOGIC CORPORATION (Factory)
Data Conversion Products Group
360 Audubon Road Wakefield, MA 01880
(617) 246-0300

Easylink 466069 +
Answerback ANALOGIC WKFL
Sales Assistance: Ext. 2115
Technical Assistance: Ext. 2368
Ext. 2168
ANALOGIC CORPORATION 4300 Stevens Creek Blvd.
Suite 284
San Jose, CA 95129
(408) 247-6401

Telex 910-338-0568

ANALOGIC CORPORATION 9898 Bissonnet Houston, TX 77036 (713) 541-5331

Telex 33-26-44
ANALOGIC CORPORATION Executive Club West 21330 Center Ridge Road Rocky River, OH 44116 (216) 331-1990

## ANALOGIC CORPORATION SUBSIDIARIES

ANALOGIC LIMITED<br>68 High Street<br>Weybridge<br>Surrey, KT13 8BN<br>England (UK)<br>(44) 0932-56011<br>Telex 851-928030<br>ANALOGIC GMBH<br>Daimlerring 2<br>6200 Wiesbaden—Nordenstadt<br>F.R. West Germany<br>(49) 6122-4071/74<br>Telex 841-4182587

## ANALOGO.


[^0]:    *Note: At Gain $<20$, inputs must be $< \pm 0.5 \mathrm{~V}$.

[^1]:    Input Offset Voltage
    $<6.0 \mathrm{mV}$, (MP261 - <2.0 mV)

[^2]:    * Doubles approximately every $10^{\circ} \mathrm{C}$

[^3]:    *For further discussion, please refer to The Analogic DataConversion Systems Digest, "Some Considerations in the Design of Wide Dynamic Range Audio Digitizing Systems," by Robert Talambiras.

[^4]:    1. Full scale ranges (FSR's) specified with $500 \Omega$ nominal between gain adjust terminals @ $25^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$. A resistance change of 0 to $1 \mathrm{k} \Omega$ between gain adjust terminals results in a nominal gain change of $9 \%$
    2. " 0 " denotes this pin connected to the V - isolated output.
    " 1 " denotes this pin connected to the $\mathrm{V}+$ isolated output through a resistor.
    3. Input Gain; see Figure 2 and Input Connections.
[^5]:    **To change to offset binary, use B1 instead of $\overline{B 1}$.
    For 5 V units, divide input voltage by 2.

[^6]:    *Other values of Input Full Scale Range, Conversion Rate, or Integration Time are available on special order. Consult Factory.

[^7]:    ENVIRONMENTAL \& MECHANICAL
    Operating Temperature
    $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
    Storage Temperature
    $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
    Relative Humidity
    $5 \%$ to $85 \%$ non-condensing to $40^{\circ} \mathrm{C}$
    Shielding
    Electrostatic and electromagnetic
    Package Size
    $4.6^{\prime \prime} \times 3.9^{\prime \prime} \times 0.375^{\prime \prime}(116.8 \times 76.2 \times 9.7 \mathrm{~mm})$

[^8]:    - Multitrack PCM for Professional Audio Recording
    - Self-Contained Record and Playback
    - Vibration Analysis

    Spectrum Analysis

    - Seismic Exploration
    - Sonar Systems
    - Instrumentation

[^9]:    * For more information on Analogic's audio system, please send for data sheets on the MP282A, MP2735, MP1926A, MP1936, MP201A and AH201.

[^10]:    *PLEASE NOTE
    Comparable IC's providing similar functions to the 3262A are available from several manufacturers. The Fairchild part number 3262A is used by way of example, and no endorsement by Analogic of this part is intended or implied. Also, Analogic is not responsible for the accuracy of technical information supplied by other manufacturers.

[^11]:    *For offset binary and two's complement operation, the CODE SET input connects a voltage available on the module to the 16th resistor in the network, offsetting the output by $1 / 2$ LSB and thus avoiding the " +0 V " and " -0 V " codes implicit in sign/magnitude operation. The MP1926's offset control is factory adjusted to make this 17 th bit offsetting transparent to the user who is supplying offset binary or 2's complement codes. To set up for sign/magnitude input coding, see the calibration procedure.

[^12]:    *In general, applications will incorporate a recovery filter to compensate for both the $(\sin x) / x$ attenuation introduced by the sampling process and the frequencydependent attenuation (rolloff) introduced by the distortion suppressor's time constant limited response.

[^13]:    *For more details on the applicability of the sign/magnitude architecture to audio systems, consult your Analogic Representative.

[^14]:    *Other time constants available - consult factory.

[^15]:    *The SHAD-2 provides 98 dB (16-bit) dynamic range at low cost via an MP282A Dual Channel Sample and Hold (with 1-bit automatic gain ranging) and an MP2735-2 Low Distortion 15-Bit Analog-to-Digital Converter. It incorporates these two modules, plus control logic for simultaneously updating two channels, within a compact $4.62^{\prime \prime} \times 5.78^{\prime \prime}$ ( $117 \mathrm{~mm} \times 147 \mathrm{~mm}$ ) printed circuit board. For more information on Analogic audio PCM products, consult your Analogic Representative; for a detailed summary of end-to-end system tests that used the MP1936's decoding architecture, ask for a reprint of "A New, Ultra Linear 16-Bit Digital-to-Analog Conversion System for Professional Audio," by Albert A. Sanchez.

[^16]:    *This function generating technique is due to Dr. J. Bosser, (at CERN Geneva) whose cooperation we wish to acknowledge.

