WD7910/LP

ISA-Based System Controller
with Cache for 80386SX and 80286
Desktop and Portable Compatibles



TABLE OF CONTENTS

Section	Title Page
1.0	INTRODUCTION 7-1 1.1 Document Scope 7-1 1.2 Features 7-1 1.3 General Description 7-2 1.3.1 WD7710 7-2 1.3.2 WD7710LP 7-2
2.0	ARCHITECTURE 7-2 2.1 Initialization And Clocking 7-2 2.2 AT Bus 7-2 2.3 Main Processor Control 7-2 2.4 Numeric Processor Control 7-2 2.5 Data Bus 7-2 2.6 Memory and EMS Control 7-2 2.7 Power Management Control 7-2 2.8 Register File 7-5 2.8.1 Lock Status Register 7-5 2.8.2 Lock/Unlock Register 7-6 2.9 VLBI Control 7-6 2.10 Cache Control 7-6
3.0	SIGNAL DESCRIPTION
4.0	INITIALIZATION AND CLOCKING
5.0	AT BUS 7-24 5.1 Interrupt Multiplexing 7-24 5.1.1 Data Acknowledge DACK7-5, 3-0 7-24 5.1.2 Data Request DRQIN 7-24 5.1.3 Interrupt Requests 7-24 5.1.4 AT Address Bus, Data Bus, And Terminal Count (TC) Signal 7-24 5.2 Power Management Control PMCIN 7-24 5.3 Numeric Processor 7-26 5.3.1 Numeric Processor Busy, Bus Timing, And Power Down Register 7-26 5.3.2 Numeric Processor Busy (NPBUSY) Reset 7-28 5.3.3 Numeric Processor Reset (NPRST) 7-28

Section	Title					Page
	5.4	DMA C	ontrol			7-29
		5.4.1	Transfer	Modes		 7-29
		5.4.2	Transfer '	Types		 7-29
		5.4.3	Autoinitia	lize		 7-30
		5.4.4	Priority			 7-30
		5.4.5	Extended			 7-30
		5.4.6	Base and	Current Address		 7-30
		5.4.7	Base and	Current Word Count		 7-30
		5.4.8	Comman	d Register		 7-32
		5.4.9	Status Re	egister		 7-32
		5.4.10	Request			
		5.4.11	Mask Reg	gisters		 7-32
			5.4.11.1	Single Mask Register		 7-33
			5.4.11.2	Clear Mask Register		 7-33
			5.4.11.3	Mask Multiple Register		
		5.4.12	Mode Re	gister		 7-33
		5.4.13		nter Register		 7-34
		5.4.14	Master C	ear Register		 7-34
		5.4.15	DMA Mod	le Shadow Register		
	5.5	System		8259 Interrupt Controllers		7-35
		5.5.1		Sequence		 7-35
		5.5.2	Setup - In	itialization Command Words (ICW)		 7-37
			5.5.2.1	ICW1 - Initialization Command Word 1		 7-37
			5.5.2.2	ICW2 - Initialization Command Word 2	 ٠.	 7-37
			5.5.2.3	ICW3 - Initialization Command Word 3		 7-37
			5.5.2.4	ICW4 - Initialization Command Word 4		 7-38
		5.5.3 O	peration .			 7-38
			5.5.3.1	OCW1 - Operation Control Word 1		 7-38
			5.5.3.2	OCW2 - Operation Control Word 2		 7-39
			5.5.3.3	OCW3 - Operation Control Word 3		 7-39
	5.6	System	Controller	8254 Timer		 7-40
		5.6.1	Setup .			 7-41
			5.6.1.1	Mode 0 Interrupt On Terminal Count		 7-41
			5.6.1.2	Mode 1 Hardware Retriggerable One Shot .		 7-41
			5.6.1.3	Mode 2 Rate Generator		 7-41
			5.6.1.4	Mode 3 Square Wave Generator		 7-41
			5.6.1.5	Mode 4 Software Triggered Strobe		 7-41
			5.6.1.6	Mode 5 Hardware Triggered Strobe		 7-41
		5.6.2	Reading 7	The Counter		 7-42

Section	Title		Page
		5.6.3 Reading Status	7-42
		5.6.4 Page	7-42
		5.6.5 Refresh Address	7-42
	5.7	System Controller Decode	7-43
		5.7.1 Page Register Decodes	7-43
	5.8	NMI and Real-time Clock	7-44
		5.8.1 Real-Time Clock Address Register	7-44
		5.8.2 Real-Time Clock Data Register	7-44
		5.8.3 Lock Pass, Alternate A20G, And Hot Reset Register	7-44
	5.9	Parity Error and I/O Channel Check	7-45
6.0	MEM	ORY AND EMS CONTROL	7-46
	6.1	DRAM Address And Data Bus	7-46
	6.2	Memory Configuration	7-47
		6.2.1 Memory Control	7-47
		6.2.2 Memory Bank 3 Through Bank 0 Starting Address	7-49
		6.2.3 Split Starting Address	7-50
		6.2.4 RAM Shadow And Write Protect	7-52
		6.2.5 High Memory Write Protect Boundary	7-54
	6.3	Memory Timing	7-55
		6.3.1 Non-page Mode DRAM Memory Timing	7-55
		6.3.2 Page Mode	7-58
		6.3.3 Memory Address Multiplexer	7-59
	6.4	EMS	7-61
		6.4.1 EMS Control And Lower EMS Boundary	7-61
		•	7-62
		6.4.3 EMS Page Register	7-64
7.0	CACH	HE CONTROLLER	7-65
	7.1	Cache Architecture	7-65
		7.1.1 Processor Interface	7-65
		7.1.2 Tag RAM	7-65
		7.1.3 Data RAM	7-66
		7.1.4 Snoop Interface	7-66
		7.1.5 Noncacheable Control	7-67
		7.1.6 Diagnostic Control Logic	7-67
		7.1.7 LRU	7-67
		7.1.8 Flush	7-67
	7.2	Cache Control Register	7-67
		7.2.1 Cacheable Region 1 Upper Boundary	7-68
		7.2.2 Noncacheable Region 1 Lower Boundary	7-69
		7.2.3 Noncacheable Region 2 Lower Boundary	7-70
		7.2.4 Flush	7-70

Section	Title	Page
8.0	PORT CHIP SELECT AND WD7710LP REFRESH CONTROL 8.1 Refresh Control, Serial And Parallel Chip Selects 8.2 RTC, PVGA, 80287 Timing, Disk Chip Selects 8.3 Programmable Chip Select Address 8.4 I/O Port Addresses And Chip Select Assignments	7-71 7-73 7-75
9.0	9.5 PMC Inputs	7-78 7-82 7-83 7-83 7-84 7-85
		7-86 7-87 7-88 7-90 7-92 7-92 7-93 7-94
10.0	9.14 Save And Resume DIAGNOSTIC MODE 10.1 Diagnostic Register 10.2 Delay Line Diagnostic Register 10.3 Test Enable Register 10.4 Test Status Register	7-96 7-96 7-98 7-98
11.0	DC ELECTRICAL SPECIFICATIONS	7-101
12.0	AC OPERATING CHARACTERISTICS	7-105 7-105 7-125 7-129 7-132



Section	Title											Page
	12.2	AT Bus T	ning									. 7-129
		12.2.1	CPU Initiated AT Bus Cycl	es								. 7-129
		12.2.2	Entering The AT Bus									. 7-141
		12.2.3	Exiting The AT Bus									. 7-146
		12.2.4	DMA Cycles									. 7-151
		12.2.5	AT Bus Master									. 7-156
		12.2.6	AT Bus Refresh					٠.				. 7-162
	12.3	Process	r Timing									. 7-164
	12.4	Cache C	ontroller									. 7-177

LIST OF TABLES

Table	Title
2-1	Register Index
3-1	Signal/Pin Assignments
3-2	Signal Description
4-1	Clock Switch Selection
4-2	Speedup Activity
5-1	MXCTL2-0 Decoding
5-2	Bus Timing Parameters
5-3	DMA Transfer Types
5-4	DMA Controller/Channel Function Map
5-5	Interrupt Sequence
5-6	Interrupt Controller Function Map
5-7	Control Word Format
5-8	Decode Addresses
5-9	Page Register Decodes
6-1A	Typical DRAM Speeds
6-1B	Non-page Mode Timing
6-2	Page Mode Wait States
6-3	Page Mode DRAM Address Multiplexer Configuration
6-4	Non-page Non-interleave Address Configuration
6-5	Non-page 2-WAY Interleave Address Configuration
6-6	Upper Page Frame Assignments
6-7	Lower Page Frame Assignments
8-1	I/O Address and Chip Select Assignments
9-1	PMC Output Signals
9-2	PMCIN Inputs
10-1	Diagnostic Tests
11-1	DC Operating Characteristics
12-1	Timing Figure/Table Numbers
12-2	Signal Loading
12-3	80286 - Page Mode Memory Timing
12-4	80286 - Non-page Mode 00 Memory Timing
12-5	80286 - Non-page Mode 01 Memory Timing
12-6	80386SX - Page Mode Memory Timing
12-7	80386SX - Non-page Mode 00 and Mode 01 Memory Timing
12-8	CPU Initiated AT Bus Cycles
12-9	Entering the AT Bus



WD7710/WD7710LP

Table	Title	Page
12-10	Exiting the AT Bus	7-146
12-11	DMA Cycles	7-151
12-12	AT Bus Master Cycle	7-156
12-13	AT Bus Refresh Cycle, Default Timing	7-162
12-14	80286 CPU Timing	7-164
12-15	80386SX CPU Timing	7-170

LIST OF ILLUSTRATIONS

Figure	Title	Page
1-1	System Block Diagram	. 7-3
2-1	WD7710, and WD7710LP Block Diagram	. 7-7
3-1	WD7710 Pinout Diagram	. 7-11
4-1	Clock Control	. 7-20
5-1	MXCTL2-0 Multiplexing	. 7-25
6-1	Split Size	. 7-51
6-2	X_MEM = 0	
6-3	X_MEM = 1	. 7-53
7-1	Cache Controller Functional Diagram	. 7-65
7-2	Tag RAM Data Ram Structure	. 7-66
9-1	Register Access by Keyboard Controller	. 7-81
9-2	Power-down	
9-3	Power-up	. 7-95
12-1	80286 - Page Mode First Access Read/Write	. 7-120
12-2	80286 - Page Mode Read Cycle Followed by Page Hit	. 7-121
12-3	80286 - Page Mode Read After Write	
12-4	80286 - Page Mode, Page Miss Read/Write	. 7-122
12-5	80286 - Page Mode, Write Miss Following Write	. 7-123
12-6	80286 - Page Mode Read Hit Followed by a Write Hit	. 7-124
12-7	80286 - Non-page Mode 00, 1 Wait State Write (4072H = 0001)	. 7-126
12-8	80286 - Non-page Mode 00, 1 Wait State Read (4072H = 0001)	. 7-127
12-9	80286 - Non-page Mode 00, 2 Wait States Read After Write	
	(4072H = 0001)	. 7-128
12-10	80286 - Non-page Mode 01, 0 Wait State Write (4072H = 3560H)	
12-11	80286 - Non-page Mode 01, 0 Wait State Read (4072H = 3560H)	
12-12	80386SX - Page Mode, First Access Read/Write	
12-13	80386SX - Page Mode, Page Miss Read/Write	. 7-137
12-14	80386SX - Page Mode, Read Cycle Followed by a Page Hit	. 7-135
12-15	80386SX - Page Mode, Read After Write	. 7-135
12-16	80386SX - Page Mode, Read Hit Followed by a Write Hit	. 7-136
12-17	80386SX - Page Mode, Write Miss Cycle Following a Write Cycle	. 7-136
12-18	80386SX - Non-page Mode 00, 1 Wait State (Pipeline) (4072H = 0001)	. 7-138
12-19	80386SX - Non-page Mode 00, 1 Wait State Write (Pipeline) (4072H = 0001)	. 7-139
12-20	80386SX - Non-page Mode 01 / 0 Wait State Read	
	(Pipeline) (4072H = 3560H)	. 7-140
12-21	80386SX - Non-page Mode 01, 0 Wait State Read	
	(Pipeline) (4072H = 3560H)	. 7-141



igure	Title	Page
12-22	AT Bus I/O or Memory Read: 8-Bit, Default Timing	. 7-131
12-23	AT Bus I/O or Memory Read: 8-BIT, Zeroes Asserted	. 7-132
12-24	AT Bus I/O or Memory Read: 8-Bit Extra Wait State Added	. 7-133
12-25	AT Bus I/O or Memory Write: 8-Bit, Even Byte, Default Timing	. 7-134
12-26	AT Bus I/O or Memory Write: 8-Bit, Odd Byte, Default Timing	
12-27	AT BUS I/O or Memory Read: 8-Bit, Word to Byte Conversion, Default Timing	
12-28	AT Bus I/O or Memory Write: 8-Bit, Word to Byte Conversion, Default Timing	. 7-137
12-29	AT Bus I/O or Memory Read: 16-Bit, Default Timing	. 7-138
12-30	AT Bus I/O or Memory Read: 16-Bit, 0WS Asserted and Extra Wait State Added	
12-31	AT Bus I/O or Memory Write: 16-Bit, Default Timing	. 7-140
12-32	80286 CPU - Asynchronous CPUCLK to SYSCLK, BREQ Delay = 1/2 Clock	. 7-142
12-33	20006 CDLL Asymphronous CDLICLK to SVSCLK	
	BREQ Delay = 1 Clock	. 7-142
12-34	80286 CPU - Synchronous CPUCLK to SYSCLK	. 7-143
12-35	80386SX CPU - Asynchronous CPUCLK to SYSCLK, BREQ Delay = 1/2 Clock	. 7-144
12-36	80386SX CPU - Asynchronous CPUCLK to SYSCLK,	
	BREQ Delay = 1 Clock	. 7-144
12-37	80386SX CPU - Synchronous CPUCLK to SYSCLK	. 7-145
12-38	Synchronous AT Bus Cycle Completion, AT Bus Clock = CPUCLK ÷ 2	. 7-147
12-39	Synchronous AT Bus Cycle Completion, AT Bus Clock = CPUCLK ÷ 1	
12-40	Asynchronous AT Bus Cycle Completion, BAK_DEL = -1 OR -0.5 AT Bus Cycles	
12-41	Asynchronous AT Bus Cycle Completion, BAK_DEL = 0 OR +0.5 AT Bus Cycles	7 150
12-42	Basic DMA Cycle, Default Timing	
12-42	DMA Cycle, 8-Bit I/O to On-board Memory	
12-43	DMA Cycle, On-board Memory to 8-Bit I/O	
12-44	AT Bus Master, Bus Acquisition/Release	
12-45	· ·	
	AT Bus Master, Write to On-board Memory	
12-47	AT Bus Master, Read from On-board Memory	
12-48	AT Bus Refresh Cycle, Default Timing	
12-49	80286 - CPURES and NPRST During Power-up	
12-50	80286 - Coprocessor Reset (NPRST) Initiated by IOW to Port F1	. /-165
12-51	80286 - Processor Reset (CPURES) Initiated by Sources Other Than Power-up Reset	. 7-166



WD7710/WD7710LP

Figure	Title	Page
12-52	80286 - BusyCPU Asserted During Coprocessor Access	. 7-167
12-53	80286 - Latching BusyCPU When An Error Occurs And	
	Clearing It With A Write To Port F0	
12-54	80286 - Miscellaneous Timing	. 7-169
12-55	80386SX - CPURES NPRST During Power-up	. 7-172
12-56	80386SX - Coprocessor Reset (NPRST) Initiated IOW to Port F1	
12-57	80386SX - Processor Reset (CPURES) Initiated by Sources	
	Other Than Power-up ReseT	. 7-173
12-58	80386SX - BusyCPU Assertion During Coprocessor Access	
12-59	80386SX - Latching BusyCPU When An Error Occurs	
	And Clearing It With A Write To Port F0	. 7-175
12-60	80386SX - Miscellaneous Timing	. 7-176
12-61	80386SX - Input Setup And Hold Timing	. 7-176
12-62	80386SX - Output Delay Timing	. 7-176
12-63	Read Hit/Read Miss Cycle	
12-64	Write Hit/Write Miss Cycle	
12-65	DMA/Master Memory Write Hit Cycle	
12-66	DMA/Master Memory Write Miss Cycle	
12-67	Tag RAM and Data RAM Timing	

1.0 INTRODUCTION

The WD7710 is the second generation single chip AT solution based on the WD76C10A core. It is fabricated in 0.9 micron CMOS. The WD7710 provides 8 Kbytes of direct-mapped or two-way set associative lookaside caching, a page-interleaved memory controller, and enhanced power management features. Figure 1-1 shows the block diagram of the WD7710-based system.

The standard version of the WD7710 operates from 5 VDC ($\pm 10\%$) supplies. An extended low-power version, the WD7710LP, can operate with 3.3 VDC (± 0.3 V) or 5 VDC (± 0.5 V).

1.1 DOCUMENT SCOPE

This document describes the function and operation of the WD7710 and WD7710LP System Controller devices. It includes the description of external logic necessary for efficient use of these devices. In most instances the WD7710 and WD7710LP operate similarly and are referred to in this document as the System Controller. Where there are differences, the devices are identified specifically.

1.2 FEATURES

- Software and pin compatible with WD76C10A
- 8Kbyte on-chip cache for 80386SX
 - Direct map or 2 way set-associative
 - Self timed Integrated RAM arrays
 - Programmable non-cacheable regions
 - Diagnostic mode to test Tag and Data Ram
 - Flush command
 - 25 Mhz zero wait state cache hit
- ROM may be shadowed and/or cached
- Supports Static CPU for power savings in sleep mode

- Supports extra wait state for page mode
- Operates at speeds of 16 MHz, 20 MHz and 25 MHz
- Interfaces with 80286, or 80386SX CPUs.
- Supports memory in four banks with 64 Kbits, 256 Kbits, 1 Mbits or 4 Mbits DRAMs. Also supports new 512k x 8, 1M x 16 and 2M x 8 DRAM configurations.
- Page mode zero wait state access at 25 MHz with 70 ns DRAM.
- Supports up to 16 Mbyte of real memory, or 32 Mbyte of EMS memory.
- Maintains controlled propagation delay for 80386SX reset.
- Employs an internal self-tuning delay line for DRAM control.
- Self-adjusting output drivers minimize output rise/fall time variations and reduces EMI and ground noise.
- DRAM address multiplexer drives 350 pF with adjustable strength drivers.
- Main and VGA BIOS may be mapped into one physical PROM.
- Advanced 64 Kbyte and 128 Kbyte ROM shadowing allows main BIOS and video BIOS shadowing along with 320 Kbyte and 256 Kbyte remap to extended or expanded memory.
- Offers additional power saving modes:
 - Slow Refresh
 - Stop DMA Clock
- Parity generation and checking.
- 132-pin PQFP package
- 3.3V low power operation
- I/O Pin mapping for testability
- Low power 0.9 micron CMOS technology.



Additional features of WD7710LP only:

- Provides System Activity Monitor (SAM).
- Provides power control with suspend and resume.
- Provides processor stop clock.
- Features CAS before RAS slow refresh for portable applications.
- Offers automatic processor clock speed switching.
- · 3V Suspend to hard disk

1.3 GENERAL DESCRIPTION

The WD7710 is designed for use in a high performance desktop AT computer using an 80286 or 80386SX processor up to 25 MHz. The WD7710LP has the features of the WD7710 and is designed to operate in a high-performance notebook/laptop AT compatible computer using an 80286 or 80386SX processor.

1.3.1 WD7710

The WD7710 contains a high-performance memory controller with programmable modes of operation. It supports non-page, zero wait state read and write memory control. A maximum of four banks of 64 Kbit, 256 Kbit, 1 Mbit, 4 Mbit or 16 Mbit DRAM may be controlled, allowing up to 16 Mbytes of real or 32 Mbytes EMS (Expanded Memory Specification) memory. Any combination of DRAM sizes may be used. In addition, the WD7710 controls page mode DRAM or static column DRAM with page mode operation.

The on-board memory can be allocated either to extended or EMS memory in 128 Kbyte increments. Forty EMS registers support EMS 4.0 multitasking.

An internal self-tuning delay line is used for DMA and Bus Master memory cycles. Delay line information is also used to adjust the strength of the output drivers. This stabilizes the output rise and fall times, which reduces ground noise and electromagnetic interference (EMI).

EMS access to external RAM or ROM may be used to support Kanji or other extended character sets.

The WD7710 interfaces with either an 80286 or 80386SX processor. The processor type is automatically sensed at power-up. No extra logic is required to interface with the 80386SX. The variation in processor reset propagation delay is controlled to meet the strict reset timing of the 80386SX.

1.3.2 WD7710LP

In addition to supporting all the features of the WD7710, the WD7710LP also supports portable notebook/laptop computers. To provide this support, the WD7710LP makes use of Power Management Control (PMC) for powering down peripherals or the processor, which includes processor stop clock, slow clock, automatic processor clock speed switching modes and CAS before RAS slow refresh. Suspend and resume is supported when low power DRAM is refreshed while the processor and other power consuming devices are turned off. The power drain for the core logic and VGA controller is less than 5 mA in this mode. Power and clock speed may be controlled by the keyboard processor, transparently to the 80286 or 80386SX.

The System Activity Monitor (SAM) provided by WD7710LP is a transparent feature that replaces the functions previously performed by software. It determines when the system has been idle for a previously programmed period of time and determines a clean break point in which to perform powerdown activities such as suspend.



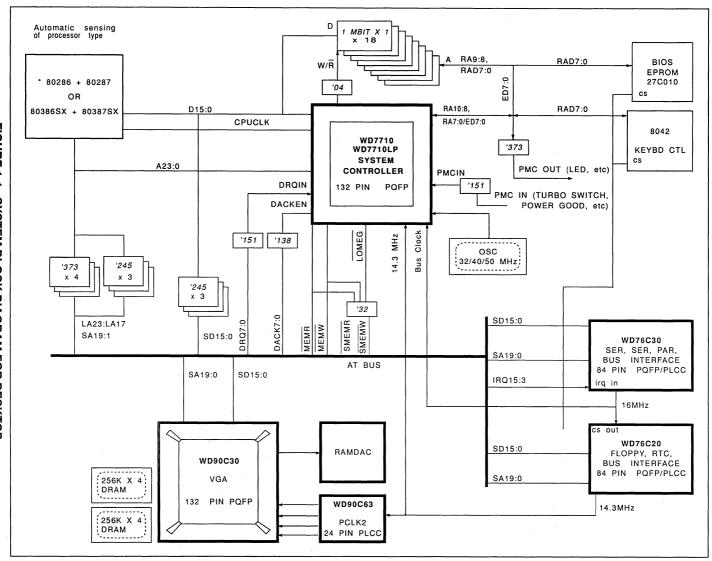


FIGURE 1-1. SYSTEM BLOCK DIAGRAM FOR DESKTOP

ADVANCED INFORMATION 11/25/91

2.0 ARCHITECTURE

All versions of the System Controller are comprised of eight major blocks:

- · Initialization and clocking
- AT bus
- 80286/80387SX processor control
- 80287/80387SX numeric processor control
- · Data bus
- · Memory and EMS control
- Power Management Control (WD7710LP only)
- Register File
- Cache control

Sections 2.1 through 2.10 provide an overview of these blocks and are described in more detail in sections 4 through 10.

2.1 INITIALIZATION AND CLOCKING

At power up, the System Controller receives the RSTIN signal, which it uses to reset the AT bus and assert CPURES and NPRST to reset the main and numeric processors. The processor and AT bus resets are held for 84 processor clocks beyond the removal of the RSTIN signal. It is at this time that the type of processor in use (80286, 80287 or 80386SX, 80387SX) is determined by examining the \$\overline{S1}[W/R#]\$ signal.

CLK14 is a 14.318 MHz clock for the 8254 compatible timers and is switched by the WD76C20 to 32 KHz during a suspend and resume operation.

BCLK2 is used to generate an 8 MHz or 10 MHz bus clock and may also be used as the source for the main processor clock, CPUCLK.

2.2 AT BUS

The AT bus provides the logic necessary to control the system clock, memory read and write access, I/O read and write cycles, data bus direction, data and interrupt requests and speaker driver.

2.3 MAIN PROCESSOR CONTROL

At the termination of reset, this block determines whether the local processor is an 80286 or 80386SX by examining the \$\overline{S1}[W/R#]\$ signal. This block also controls whether the CPUCLK is to be an input or output. While both devices have the ability to reduce the processor clock rate, only the WD7710LP has the ability to stop the clock to the processor. The WD7710LP also has the ability to power down the processor, at which time it tristates the CPUCLK, READY, HOLD, INTRQ and NMI signals.

2.4 NUMERIC PROCESSOR CONTROL

Both System Controllers support an 80287 or 80387SX processor.

2.5 DATA BUS

The Data Bus is a 16-bit (two bytes) bidirectional bus that connects to the processor's, System Controller, DRAM, and to AT data bus transceivers. The parity of each DRAM byte is indicated by DPL and DPH.

2.6 MEMORY AND EMS CONTROL

This block controls the access to 16 Mbytes of real memory or 32 Mbytes of expanded memory. Both versions of the System Controller supports non-page mode memory and independent two-way interleave page mode access to the DRAM banks.

7

2.7 POWER MANAGEMENT CONTROL

The Power Management Control (PMC) is internal logic which interfaces with external multiplexers and latches. Only the WD7710LP makes full use of the PMC. It has the ability to power down only the main processor or the main processor and peripherals, conserving power essential to portable notebook/laptop computers. When in a power down state, the WD7710LP tristates the CPUCLK, READY, HOLD, INTRQ and NMI output signals to the main processor. Also contained within this functional block are the SMI and SAM logic.

2.8 REGISTER FILE

The register file provides software control of the interface signals. The function of each register is described in the same section as the logic block which it controls. Some registers, such as the Bus Timing and Power Down Control Register at Port 1872H, serve more than one area. In this instance the register description appears only in one section but is referred to in all appropriate sections.

The registers, and the section in which they are described, are listed in Table 2-1.

In most cases, the registers are addressed by all 16 address bits, A15 through A00. Within the text, when the address is expressed as a three digit number, i.e., 092H - ALT A20 GATE and HOT RESET, only address bits A09 through A00 are used, A15 through A10 are ignored. If the address is expressed as a four digit number, all 16 address bits are used.

With the exception of the EMS Registers at port E072H and E872H and Port 70H Shadow Register at E472H, all registers located at Ports 1072H through FC72H are locked and inaccessible until unlocked by performing an eight bit I/O write of DA to the Lock/Unlock Register at Port F073H. Writing anything other than DA locks the registers. The lock/unlock status can be determined by reading the Lock/Unlock Status Register at Port FC72H twice. If the T bit (bit 15) toggles, the registers are unlocked. If the registers are locked, the read cycle is directed to the AT bus, and the data is undetermined.

2.8.1 Lock Status Register

Port Address FC72H - Read only

Bits 11 through 03 are particularly useful in laptop applications by allowing the suspend/resume software to restore correct status to on-board devices.

15	14	13	12	11	10	09	08		
Т	Not Used			DMA #2					
				СНЗ	CH2	CH1	CH0		

07	06	05	04	03	02	01	00		
	DM	A #1		P4	Not Used				
СНЗ	CH2	CH1	CH0						

Signal	Default
Name	At RSTIN

All signals None

Bit 15 - T, Toggle

Changes state after every read of this port.

Bits 14-12 - Not used, state is ignored

Bits 11-08 - DMA #2, Channel Enable

This field represents the state of the Enable Bit (Mask) for channels 3 through 0 of DMA Controller #2. For a description of the Mask Registers, refer to section 5.4.11.

- 1 = Channel enabled
- 0 = Channel disabled

Bits 07-04 - DMA #1, Channel Enable

This field represents the state of the Enable Bit (Mask) for channels 3 through 0 of DMA Controller #1. For a description of the Mask Registers, refer to section 5.4.11.

- 1 = Channel enabled
- 0 = Channel disabled

Bit 03 - P, Parallel Port Direction

The P bit represents the state of the Direction Bit (bit 5) of the parallel port Write Control Register. For a description of this bit, refer to the WD76C30 Data Book, section 4.3

Bits 02-00 - Not used, state is ignored

2.8.2 Lock/Unlock Register

Port Address F073H - Write only

15	14	13	12	11	10	09	08
Not Used							

07	06	-5	04	03	02	01	00
L/UL = DA-							

Signal Name Default At RSTIN

All signals

None

Bits 15-08 - Not used, state is ignored

Bits 07-00 - L/UL, Lock/Unlock

L/UL = DA -

11011010 unlocks the registers, allowing read and write access to the registers. Refer to Table 2-1 for the registers capable of being locked.

L/UL ≠ DA -

Anything other than 11011010 locks the registers. Any attempt to access a locked register I/O port address goes to the AT bus rather than the locked register.

2.9 Cache Control

This functional block contains the 8Kbyte integrated cache (both tag and data RAM) as well as cache control logic.

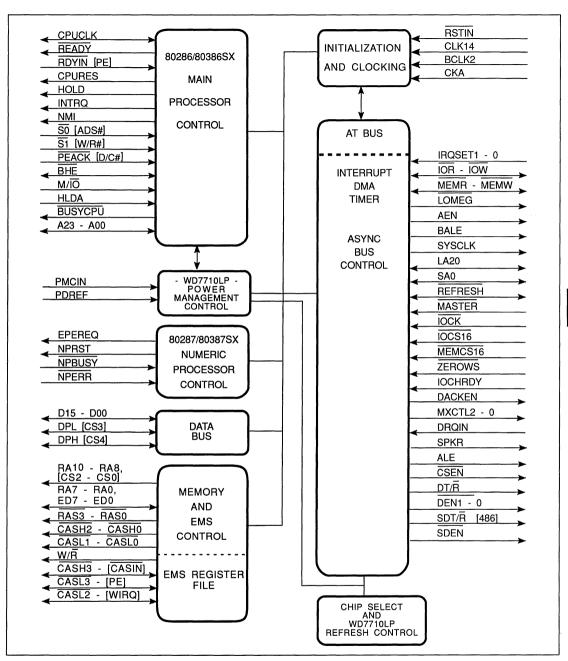


FIGURE 2-1. WD7710 AND WD7710LP BLOCK DIAGRAM

PORT ADDRESS (HEX)	REGISTER NAME	LOCK/ UNLOCK	SECTION
000 - 00F ①	DMA Control #1 (Channel 0:3)	No	5.4, 5.6,
020 - 021 ②	Interrupt Controller #1	No	5.5
040	Timer 0. Time Of Dav	No	5.7
041	Timer 1, Refresh	No	5.7
042	Timer 1, Refresh	No	5.7
043	Control Word	No	5.7
060 - 06E even	Keyboard Controller	No	8.5, Table 8-1
061 - 06F odd	Port B Parity Error And I/O Channel Check	No	5.9
070 - 07E even	Real-Time Clock Address Register	No	5.8.1
071 - 07F odd	Real-Time Clock Data Register	No	5.8.2
080 - 09F	(except 092H) DMA Page Registers	No	5.6.4
092	ALT A20 Gate and Hot Reset	No	5.8.3
0A0 - 0A1 @	Interrupt Control Slave #2	No	5.4, 5.6
0C0 - 0DE ①	DMA Control #2 (Channel 4:7)	No	5.4
00F0	Clear 287 Busy	No	5.3.2
00F1	Reset 287/387SX	No	5.3.3
1072	CPU Clock Control	Yes	4.2.4
1872	Bus Timing And Power Down Control	Yes	5.3.1
2072	Refresh Control, Serial And Parallel Chip Selects	Yes	8.1
2872	Chip Selects	Yes	8.2
3072	Programmable Chip Select Address	Yes	8.3
3872	Memory Control	Yes	6.2.1
3C72	DMA Shadow Register 1	Yes	9.14
4072 4472	Non-page Mode DRAM Memory Timing	Yes Yes	6.3.1 9.14
4472 4872	DMA Shadow Register 2	Yes Yes	9.14 6.2.2
4672 4C72	DMA Shadow Register 3	Yes	9.14
5072	Bank 3 And Bank 2 Start Address	Yes	6.2.2
5872	Split Start Address	Yes	6.2.3
5072 5C72	Reserved	165	0.2.3
6072	RAM Shadow And Write Protect	Yes	6.2.4
6472	Reserved	163	0.2.4
6872	EMS Control And Lower EMS Boundary	Yes	6.4.1
6C72	Reserved	100	0.1.1
7072	PMC Output Control 7:0	Yes	9.3
7472	Reserved	.00	0.0
7872	PMC Output Control 15:8	Yes	9.3
7C72	Reserved		
8072	PMC Timers	Yes	9.4
8872	PMC Timers	Yes	9.5
8C72	Reserved		
9072	NMI Status	Yes	9.7
9472	Reserved		
9872	Diagnostic	Yes	10.1
9C72	Reserved		
l A072	Delay Line	Yes	10.2

TABLE 2-1. REGISTER INDEX

PORT ADDRESS (HEX)	REGISTER NAME	LOCK/ UNLOCK	SECTION
A472 A872 AC72 B072 B872 C072 C872 D072 D472 D472 D872 DC72 E072 E472 E872 F072 F472 F872 F073	Reserved Test Enable Reserved Activity Monitor Control DMA Control Shadow High Memory Write Protect Boundary PMC Interrupt Enables Serial/Parallel Shadow Register Interrupt Controller Shadow Activity Monitor Mask Test Status EMS Page Register Pointer Port 70H Shadow EMS Page Register 48 MHz Oscillator Disable 48 MHz Oscillator Enable Cache Flush Lock/Unlock	Yes Yes Yes Yes Yes Yes Yes Yes No No No Yes Yes Yes Yes Yes Yos	9.11 5.4.15 6.2.5 9.6 9.8 9.9 9.12 10.4 6.4.2 9.10 6.4.3 8.5, Table 8-1 8.5, Table 8-1 8.4 2.8.1

See Table 5-4. DMA Controller/Channel Function Map
 See Table 5-6. Interrupt Controller Function Map

TABLE 2-1. REGISTER INDEX (cont.)

WD7710/WD7710LP SIGNAL DESCRIPTION

3.0 SIGNAL DESCRIPTION

The signals are listed according to their pin number in Table 3-1. The signals are grouped according to their application and described in Table 3-2.

PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME
1	RA5/ED5	34	EPEREQ	67	VSS	100	A10
2	VCC	35	NPRST	68	D11	101	VCC
3	RA4/ED4	36	LOMEG	69	VCC	102	A 9
4	RA3/ED3	37	MEMW	70	D12	103	A8
5	VSS	38	MEMR	71	D13	104	A7
6	RA2/ED2	39	ĪOW	72	D14	105	A6
7	RA1/ED1	40	IOR	73	D15	106	A 5
8	RA0/ED0	41	BHE	74	DT/R	107	A4
9	CASH2	42	NPERR	75	DEN1	108	АЗ
10	CASL2 [WIRQ]	43	PEACK [D/C]	76	DEN0	109	A2
11	RAS2	44	M/IO	77	SYSCLK	110	IRQSET1
12	CASH3 [CASIN]	45	S0 [ADS#]	78	CPURES	111	IRQSET0
13	CASL3 [PE]	46	S1 [W/R#]	79	BALE	112	MXCTL0
14	RAS3	47	READY	80	A23	113	MXCTL1
15	DPH [CS4]	48	HLDA	81	A22	114	MXCTL2
16	DPL [CS3]	49	HOLD	82	A21	115	CSEN
17	RSTIN	50	BCLK2	83	IOCK	116	DACKEN
18	DRQIN	51	RDYIN [CKA] [PE]	84	CLK14	117	PDREF
19	IOCHRDY	52	CPUCLK	85	NPBUSY	118	PMCIN
20	ZEROWS	53	BUSYCPU	86	A0 [BLE#]	119	W/R
21	IOCS16	54	NMI	87	A1	120	CASH0
22	MEMCS16	55	INTRQ	88	A20	121	CASL0
23	SPKR	56	D0	89	A19	122	RAS0
24	SA0	57	D1	90	A18	123	CASH1
25	LA20	58	D2	91	A17	124	CASL1
26	MASTER	59	D3	92	A16	125	RAS1
27	ALE	60	D4	93	A15	126	RA10 [CS2]
28	AEN	61	D5	94	A14	127	RA9 [CS1]
29	SDEN	62	D6	95	A13	128	RA8 [CS0]
30	SDT/R [486]	63	D7	96	A12	129	VSS
31	VCC	64	D8	97	A11	130	RA7/ED7
32	REFRESH	65	D9	98	VSS	131	RA6/ED6
33	VSS	66	D10	99	VSS	132	VSS

Note: Some pins are multi-functional depending upon the mode of operation. The alternate signal for these pins is enclosed in brackets.

TABLE 3-1. PIN ASSIGNMENTS

PIN	MNEMONIC	I/O	DESCRIPTION
			INITIALIZATION AND CLOCKING
84	CLK14	1	Clock 14 CLK14 is derived from a 14.318 MHz crystal and is used internally for the 8254 compatible timers. CLK14 is externally switched to 32 KHz during a suspend and resume.
17	RSTIN		System Reset In RSTIN drives a CMOS input level Schmitt Trigger and is used to reset the entire system at powerup. For a detailed description, see Section 4, Initialization and Clocking.
50	BCLK2	1	Bus Clock BCLK2 is used to generate an 8 MHz or 10 MHz expansion bus clock. For an 8 MHz bus, BCLK2 is a 16 MHz or 32 MHz input signal. For a 10 MHz bus clock, BCLK2 is a 20 or 40 MHz input signal. BCLK2 may also be used to drive the processor clock.
			AT BUS
110	IRQSET1	İ	Interrupt Request Set 1 IRQSET1, along with MXCTL2 - 0, selects one of the of the following: A20GT, IRQ1, IRQ3 - IRQ7, IRQ12. Refer to Table 5-1 and Figure 5-1.
111	IRQSET0		Interrupt Request Set 0 IRQSET0, along with MXCTL2 - 0, selects one of the following: ROM8, RESCPU, IRQ8, IRQ9 - IRQ11, IRQ14 and IRQ15. Refer to Table 5-1 and Figure 5-1.
114-112	MXCTL2:0	0	Multiplexer Control 2-0 MXCTL2 - MXCTL0, along with DRQIN, DACKEN, IRQSET1, IRQSET0 and PMCIN, control the external multiplexer for the selection of DRQs, DACKs, IRQs, ROM8, A20GT and RESCPU. Refer to Table 5-1 and Figure 5-1.
115	CSEN	0	Chip Select Enable When CSEN is asserted, DPH, DPL, and RA10-RA8 are used to generate one of 28 different chip selects. Refer to Table 8-1.
116	DACKEN	0	DACK Enable When DACKEN is asserted, MXCTL2-0 are used to generate DACK7-5, 3-0 and BUS_RST. Refer to Table 5-1 and Figure 5-1.
18	DRQIN	I	Multiplexed DRQ Inputs DRQIN, along with MXCTL2 - 0, selects one of the DRQs or CLOCK_DIR_IN. Refer to Table 5-1 and Figure 5-1
19	IOCHRDY	I/O	I/O Channel Ready Indicates extra wait states are required for the AT bus cycles.

TABLE 3-2. SIGNAL DESCRIPTION

PIN	MNEMONIC	I/O	DESCRIPTION
20	ZEROWS	1	Zero Wait States Indicates the current AT bus cycle can be finished in zero wait state.
21	IOCS16	1	16-Bit I/O Cycle Inicates the I/O device on the AT bus is a 16-bit slave.
22	MEMCS16	1	16-Bit Memory Cycle Indicates that the memory device on the AT bus is a 16-bit slave.
23	SPKR	0	Speaker SPKR drives the speaker transistor.
24	SA0	I/O	System Address 0 When not in Master Mode, SA0 is an output and is asserted by the System Controller to place address 00 on the AT Bus SA0 line. When in Master Mode, SA0 is an input and is asserted by the Bus Master to place address on A0.
25	LA20	I/O	Early Address 20 When not in Master Mode, LA20 is an output and is asserted by the System Controller to place address 20 on the AT Bus LA20 line. When in Master Mode, LA20 is an input and is asserted by the Bus Master to place address on A20.
26	MASTER	ı	Master MASTER is asserted by the Bus Master to indicate that a Bus Master cycle is occurring. This causes LA20, SA0, MEMR, MEMW, IOR, and IOW to be selected as input signals.
27	ALE	0	Address Latch Enable ALE is used to clock the SA1 - SA19 address latches.
28	AEN	0	Address Enable AEN is asserted by the System Controller while performing DMA and Refresh cycles.
29	SDEN	0	Swap Data Enable SDEN enables the data transfer between high and low bytes of the AT Bus.

TABLE 3-2. SIGNAL DESCRIPTION (Continued)

PIN	MNEMONIC	I/O	DESCRIPTION
30	SDT/R	I/O	Swap Data Transmit/Receive [80486] SDT/R controls the direction of the buffer between the low byte and high byte of the AT bus. SDT/R is tristated by a 50K pullup resistor internal to the WD7910 when RSTIN at pin 80 is low. SDT/R Mode - Output When SDT/R is high, it directs data from the low byte of the AT Bus to the high byte. When SDT/R is low, it directs data from the high byte of the AT bus to the low byte. Forcing SDT/R high while RSTIN is low selects the SDT/R mode. Holding SDT/R high as RSTIN goes high maintains the SDT/R mode. 80486 Mode - Input Selecting 80486 mode sets the SRC bit in Port 1072H to 1. This causes RDYIN at Pin 51 to be the default processor clock source input. Forcing SDT/R low while RSTIN is low selects the 80486 mode. holding SDT/R low as RSTIN goes high, maintains the 80486 mode. SDT/R pin may be forced low at reset with a 5K pulldown resistor or an open collector or tristate driver driven by RSTIN.
32	REFRESH	I/O	Refresh As an output, REFRESH is asserted by the System Controller to refresh memory on the AT Bus. As an input, REFRESH is asserted by the Bus Master in conjunction with MEMR to refresh memory on the AT Bus and DRAM controlled by the System Controller.
36	LOMEG	0	First Megabyte LOMEG is asserted when the AT bus address is below 1 Mbyte.
37	MEMW	I/O	Memory Write MEMW is an output and it is asserted by the System Controller when a memory write access to the AT bus is to take place. It is an input during Master mode.
38	MEMR	I/O	Memory Read MEMR is an output and it is asserted by the System Controller when a memory read access to the AT bus is to take place. It is an input during Master mode.
39	IOW	I/O	I/O Write IOW is an output and it is asserted by the System Controller during processor or DMA access to indicate that an I/O write operation is to take place on the AT bus. IOW is an input during Master Mode.
40	ĪŌŔ	I/O	I/O Read IOR is an output and iit s asserted by the System Controller during processor or DMA access to indicate that an I/O read operation is to take place on the AT bus. IOR is an input during Master Mode.

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

PIN	MNEMONIC	I/O	DESCRIPTION
74	DT/R	0	Data Transmit/Receive DT/ \overline{R} controls the direction of the AT Data Bus D00 through D15. When DT/ \overline{R} is high, data is directed to the AT Bus. When DT/ \overline{R} is low, data is transferred from the AT bus.
75	DEN1	0	Data Bus Enable 1 When asserted, DEN1 enables the high order byte data buffer.
76	DEN0	0	Data Bus Enable 0 When asserted, DEN0 enables the low order byte data buffer.
77	SYSCLK	0	System Clock In asynchronous bus mode, SYSCLK is equal to BCLK2 divided by two when BCLK2 is less than 28 MHz, and divided by four when BCLK2 is greater than 28 MHz. In synchronous bus mode, SYSCLK is equal to CPUCLK divided by two or four, depending on the programming.
79	BALE	0	AT Bus Address Latch Enable Address Latch Enable for the AT bus. BALE is synchronous with the Bus Clock (BCLK2).
83	IOCK	ı	I/O Channel Check When asserted, IOCK indicates a bus or memory error is on the AT bus and generates an NMI to the processor.
			MAIN PROCESSOR CONTROL
4	BHE	I/O	Bus High Enable As an input, BHE indicates a transfer of the high byte on the processor data bus. BHE is an output during DMA transfers.
43	PEACK [D/C#]	ı	Processor Extension Acknowledge [Data Control] In the 80286 mode, pin 43 is PEACK. in the 80386SX mode, pin 43 is D/C#.
44	M/IO	I	Memory or I/O Processor Memory cycle or I/O Status cycle.
45	S0 [ADS#]	ı	Processor Status 0 [Address Status] In the 80286 mode pin 45 is \$\overline{S0}\$. in the 80386SX mode, this pin 45 is ADS#.
46	S1 [W/R#]	I	Processor Status 1 [Write/Read] In the 80286 mode, pin 46 is S1. In the 80386SX mode, pin 46 is W/R#.
47	READY	0	Processor Ready READY is an output to the processor
48	HLDA	ı	Hold Acknowledge Processor hold acknowledge.

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

PIN	MNEMONIC	I/O	DESCRIPTION
49	HOLD	0	Hold Request Processor hold cycle request.
51	RDYIN/CKA/PE	ı	Processor Ready In / Alternate Clock / Parity Error The Memory Control Register at port address 3872H determines whether pin 51 is to be used as RDYIN, CKA or PE.
			RDYIN is used in a discrete cache system to indicate a hit or miss.
			CKA is used as a source for the CPU clock.
			PE indicates a parity error from an external memory controller
52	CPUCLK	I/O	Processor Clock CPUCLK speed and whether it is to be an input or output, is selected by the CPU Clock Control Register at Port Address 1072H. It is normally selected as an output to drive the processor but may be selected as an input from an external processor clock driver.
54	NMI	0	Non-maskable Interrupt Processor non-maskable interrupt cycle request.
55	INTRQ	0	Interrupt Request Processor interrupt cycle request.
78	CPURES	0	Main Processor Reset CPURES is a synchronous processor reset signal.
80 - 82 88 - 97 100 102 - 109	A23:A21 A20:A11 A10 A9:A2	I/O	Processor Address A23-A00 [Bus Low Enable] A23 through A1 are address lines from the 80286 or 80386SX. A0 is address bit A0 for the 80286, BLE# for the 80386SX. A0 is controlled by SA0 (AT bus pin 24) during Master Mode operations.
87 86	A1 A0 [BLE#]		A21, A19 through A1 are outputs during refresh and DMA cycles; they are inputs in other modes.
			A20 and A0 are outputs during refresh, DMA and Master Mode cycles; they are inputs in other modes.
		٨	IUMERIC PROCESSOR CONTROL
85	NPBUSY	1	Numeric Processor Busy Busy signal from the numeric processor 80287 or 80387SX.
34	EPERQ	0	Extend PERQ PERQ extend signal to the 80386SX for IRQ13 handling. Used only for the 80386SX.
35	NPRST	0	Numeric Processor Reset Reset to the numeric processor 80287 or 80387SX.

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

7-15

PIN	MNEMONIC	I/O	DESCRIPTION				
42	NPERR	I	Numeric Processor Error Error signal from the numeric processor 80287 or 80387SX.				
53	BUSYCPU	0	Coprocessor Busy Coprocessor Busy signal to the processor.				
	DATA BUS						
15	DPH[CS4]	I/O	Data Parity High Byte [Chip Select 4] For DRAM cycles, DPH is the high byte parity bit. For I/O cycle, CS4 is bit four of the encoded chip select bus.				
16	DPL[CS3]	I/O	Data Parity Low Byte [Chip Select 3] For DRAM cycles, DPL is the low byte parity bit. For I/O cycle, CS3 is bit three of the encoded chip select bus.				
73 - 70 68 66 - 56	D15 - D12 D11, D10 - D0	I/O	Data Bits 15 through 0 The Data Bits are connected directly to the Local and Numeric processors, DRAM data and AT Bus data transceivers.				
			MEMORY AND EMS CONTROL				
119	W/R	0	Write /Read W/ \overline{R} is high when writing to memory and low when reading from memory. W/ \overline{R} should be buffred before use.				
126 127 128	RA10/CS2 RA9/CS1 RA8/CS0	0	DRAM Address Bits 11 through 8 Chip Select Bits 2 through 0 The DRAM Address Bus is multi-functional. During DRAM cycles, RA11 through RA0 select the DRAM row and column.				
130 131 1 3 4 6 7 8	RA7/ED7 RA6/ED6 RA5/ED5 RA4/ED4 RA3/ED3 RA2/ED2 RA1/ED1 RA0/ED0	I/O	DRAM Address Bits 7 through 0 EDATA Bits 7 through 0 During I/O cycles, CS2 through CS0, along with CS4 and CS3, are decoded by external logic to one of 32 possible Chip Selects. ED7 through ED0 represents the data from such devices as the Keyboard Controller on the EDATA bus.				
14 11 125 122	RAS3 thru RAS0	0	Row Address Select Bits 3 through 0 RAS3 through RAS0 are designed to access the DRAM without the use of external drivers.				

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

PIN	MNEMONIC	I/O	DESCRIPTION				
9 123 120	CASH3 [CASIN] CASH2 CASH1 CASH0	0000	Column Address Select High 3 through 0 CASH3 [CASIN] is tristated by a 50K pullup resistor internal to the WD7710 when RSTIN at pin 17 is low. CAS Output Mode CASH3 through CASH0 operate as output signals and are designed to access the DRAM without the use of external drivers. Forcing CASH3[CASIN] high while RSTIN is low, selects the CASH3 Output Mode. Holding CASH3[CASIN] high as RSTIN goes high, maintains the CASH3 Output Mode. CAS Input Mode In this mode, pins 12, 13 and 10 function as input pins controlled by CASIN, PE and WIRQ. CASH2, CASH1, and CASH0 remain output signals. Forcing CASH3 [CASIN] low while RSTIN is low, selects the CAS Input Mode. Holding CASH3 [CASIN] low as RSTIN goes high, maintains the CAS Input Mode. The CASH3 [CASIN] pin may be forced low at reset with a 5K pulldown resistor or an open collector or tristate driver driven by RSTIN.				
13 10 124 121	CASL3 [PE] CASL2 [WIRQ] CASL1 CASL0	I/O I/O O O	Column Address Select Low 3 [Parity Error] Column Address Select Low 2 [Weitek Interrupt] Column Address Select Low 1 and 0 CAS Output Mode CASL3 through CASL0 are designed to access the DRAM without the use of external drivers. CAS Input Mode - PE When CAS Input Mode is selected by [CASIN] on pin 12, and bits 13 and 12 of Port 3872H are both 1, pin 13 becomes an input and represents a parity error. A parity error is indicated by the low to high transition of the PE signal. CAS Input Mode - WIRQ When CAS Input Mode is selected by [CASIN] on pin 12, pin 10 becomes an interrupt signal which is typically connected to IRQ13, the error signal of a Weitek coprocessor. When WIRQ goes from low to high, an IRQ 13 is generated to the system.				

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

PIN	MNEMONIC	I/O	DESCRIPTION						
	POWER MANAGEMENT CONTROL								
117	NPDREF	1	Power-down Refresh NPDREF is a 64 KHz signal from the WD7710. During power-down, NPDREF is passed internally to pin 98 (REFRESH).						
118	PMCIN	I	Power Management Control Input PMCIN is used to sample eight PMC inputs. See Table 5-1 and Figure 5-1.						
			MISCELLANEOUS						
5, 33, 67, 98, 99, 129, 132	VSS	I	Ground						
2, 31, 69, 101	VCC		+5 Volts						

TABLE 3-2. SIGNAL DESCRIPTIONS (Continued)

4.0 INITIALIZATION AND CLOCKING

This section describes the system Master Reset (RSTIN) operation, control of internal clock (CLK14), bus clock (SYSCLK) and the processor clock (CPUCLK).

4.1 POWER UP RESET

The system reset signal, NRSTIN, is generated externally at power up and is used to reset the entire system. When asserted, the System Controller outputs the CPURES signal to reset the Main Processor. At this time the System Controller also resets the AT bus by asserting DACKEN and MXCTL2-0 = 100, which are decoded externally as BUS RST (DACK4), see sections 5.1, 5.1.1. Table 5-1 and Figure 5-1. An external RC circuit can be used to extend the time that RSTIN is asserted until the power supply reaches a proper level. CPURES and the AT bus reset signals are de-asserted 84 clock pulses after RSTIN reaches its switching threshold. It is during the reset period that the type of processor is detected by examining the state of the $\overline{S1}$ signal. If $\overline{S1}$ is asserted, the System Controller enters the 80386SX mode. If \$\overline{S1}\$ is de-asserted, it enters the 80286 mode. If an 80386SX has been detected. BUSYCPU is asserted so that the processor may perform its self-test operation immediately following the power up reset.

4.2 CLOCKING

The System Controller makes use of five clocks, CLK14, BCLK2, CPUCLK, CKA and SYSCLK. Figure 4-1 shows how the clocks interact with each other and the register used to select the clock and speed.

4.2.1 Internal Clock (CLK14)

CLK14 is an input signal from a 14.318 MHz crystal and is used for the control of the 8254 compatible timers. CLK14 is switched by the WD7710 to 32 KHz during save and resume operations.

4.2.2 System Bus Clock (SYSCLK)

The AT bus is driven by the SYSCLK, which is derived from either the BCLK2 or CPUCLK, as selected by the Bus Timing Register at Port Address 1872H. SYSCLK is always one half or one fourth the value of the selected input clock (refer to Figure 4-1).

4.2.3 Processor Clock (CPUCLK)

The processor clock may be an output or input, depending on whether the System Controller generates CPUCLK or an external oscillator is used. At speeds higher than 50 MHz, CPUCLK may need to be generated by an external oscillator, making it possible to control the processor duty cycle more closely. At lower speeds, the System Controller may use BCLK2 to generate CPUCLK or, in a system without discrete cache, the System Controller may use CKA to generate CPUCLK.

During reset, CPUCLK is an output.

If the CPUCLK is initially placed in the input mode, it may be changed to the output mode by writing to the PMC Control Register at Port Address 7872H. The PMC control output 0 tristates the external clock oscillator. A processor reset (CPURES) is automatically generated during the clock switching process.

When the CPUCLK is an output, it may be stopped by SCHH or SCH (CPU Clock Control Register - bits 01 or 00, at Port Address 1072H) or divided down by CLK_SPD (bits 14-12). Only the WD7710LP supports the CPUCLK stop function. When CPUCLK is stopped, it is in phase two of the 80C286. CPUCLK is restarted by an NMI or IRQ interrupt, qualified by the normal NMI and IRQ masking circuitry or by an NMI generated PMC logic.

There are two methods for slowing the processor execution rate to provide software compatibility with programs expecting a particular CPU speed, such as game software. One method is to divide the CPUCLK by a factor of 2, 4 or 8. Dividing the clock rate may also have an effect on the CPU power consumption, so CLK_SPD also provides some choices of clock duty cycle. The other method can be used when the CPUCLK is an

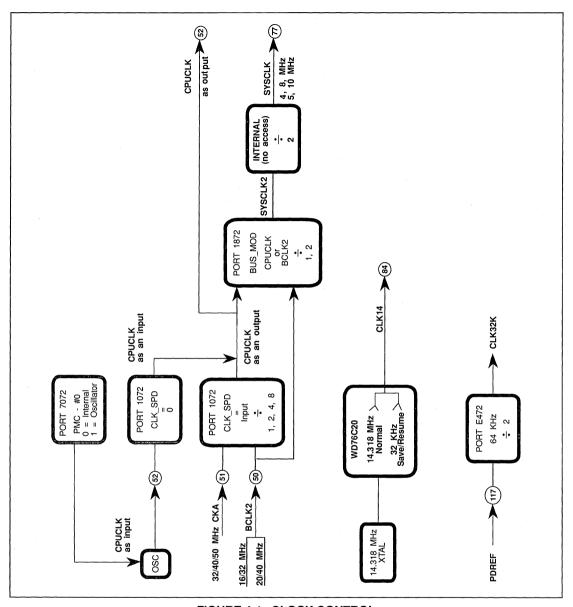


FIGURE 4-1. CLOCK CONTROL

output or input and generated by an external oscillator. In this case, EXT_HOLD is used to extend the hold request time to the processor after every refresh.

In a system without a cache or external memory controller, pin 51 can be defined as Clock A (CKA)

and used in place of the BCLK2. This choice is determined by SRC (CPU Clock Control Register bit 15 at Port Address 1072H). SRC is set automatically at power up reset, if a clock source is present at pin 51 (CKA).

4.2.4 CPU Clock (CPUCLK) Control Register

Port Address 1072H - Read and Write

15	14	13	12	11	10	09	9 08			
SRC	С	LK_SPE)	AUT_ FST	AL	T_CLK_	SPD			

07	06	05	04	03	02	01	00
	EXT_H	HOLD				SCHH	SCH

Signal Name							e <u>fault</u> t RSTIN
SRC							0/1
CLK_SPD							
AUT FST †							
ALT CLK SPD †							
EXTEND HOLD							
Bits 03, 02							
SCH †							
SCHH †							0

† Featured only in the WD7710LP

Bit 15 - SRC, CPUCLK Clock Source

When CPUCLK is selected as an output by bits 14 - 12, SRC determines whether it is to be driven by BCLK2 or CKA.

Default Value

SRC is set to 0 and BLCK2 is used as the CPUCLK clock source if CKA does not change state within 64 clocks after RSTIN is de-asserted.

SRC is set to 1 and CKA is used as the CPUCLK clock source if CKA changes state within 64 clocks after RSTIN is de-asserted, or when operating in the 80486 Mode. The 80486 Mode is selected by holding SDT/R low during RSTIN transition from low to high.

SRC = 0 -

BCK2 is the CPUCLK source.

SRC = 1 -

CKA is the CPUCLK source.

Bits 14-12 - CLK SPD, CPUCLK Clock Speed

CLK SPD determines whether CPUCLK is to be an input or output. When selecting CPUCLK as an output, CLK SPD also determines the divisor and duty cycle values. The CLK SPD *defaults to 000 or 001 at power up. Changing the CPUCLK from an input (CLK SPD = 000) to an output automatically asserts the processor reset (CPURES) and the CPUCLK Driver Enable from the PMC latch is forced low, tristating the external clock oscillator. One millesecond later. CPUCLK becomes active as an output. One millesecond and 16 CPUCLK clocks (or one millesecond) later, the CPURES is de-asserted. This method allows switching the clock source while tolerating alitches in the CPUCLK, generated due to the clock driver not being able to synchronously switch the clock. The one millesecond and 16 clocks or one millesecond selection is made through the Diagnostic Register at Port 9872H.

CLK_SPD 14 13 12

- 0 0 CPUCLK pin is an input, speed determined by external driving source (* Default value).
- 0 0 1 CPUCLK pin is an output, source divided by 1 (* Default value).
- 0 1 0 OUT, source divided by 2.
- 0 1 1 OUT, source divided by 4, 25% duty cycle.
- 1 0 0 OUT, source divided by 4, 75% duty cycle.
- 1 0 1 OUT, source divided by 8, 12% duty cycle.
- 1 1 0 OUT, source divided by 8, 88% duty cycle.
- * Based upon the value of CLOCK_DIR_IN at power up (refer to Table 5-1, Figure 5-1 and section 5.1.2).

Bit 11 - AUT_FST, Automatic Processor Clock Speed Switching Featured only in the WD7710LP

When automatic CPUCLK switching is enabled, the processor clock is switched between high and low clock speeds, depending upon activity. If the external TURBO signal is de-asserted when auto switching is enabled, the CPUCLK is normally at the alternate clock or slower rate. When speedup activity occurs, the clock speed switches to the nominal clock rate, normally the higher, for a period of time determined by Table 4-2. When no further activity occurs, the clock speed switches back down to the alternate speed. If the external TURBO signal is asserted, the clock rate is set to the nominal clock rate specified by the CLK_SPD field.

A halt state also causes the clock rate to slow, unless the SCHH or SCH field is programmed to stop the clock. The clock restarts or returns to the faster rate when any interrupt occurs.

Table 4-2 shows the activity that triggers a higher clock rate.

AUT FST = 0 -

Automatic Clock Switching is disabled. TURBO determines whether CLK_SPD or ALT_CLK_SPD is to be used as the CPU clock. Refer to Table 4-1 for the appropriate selection, as determined by TURBO.

AUT FST = 1 -

Automatic CPUCLK Switching between CLK_SPD and ALT_CLK_SPD is enabled when TURBO is de-asserted. CLK_SPD is selected when TURBO is asserted. Refer to Table 4-1. The EXT_HOLD field must be 0000 when AUT FST = 1.

TURBO	AUTO_FST	CPU CLOCK SPEED
0	0	CLK_SPD
0	1	CLK_SPD
1	0	ALT_CLK_SPD
1	1	CLK_SPD or ALT_CLK_SPD

TABLE 4-1. CLOCK SWITCH SELECTION

SPEEDUP ACTIVITY	TIME PERIOD				
Hard disk interrupt, Hard disk or numeric processor I/O, SCSI, floppy, port B I/O	1 second				
Keyboard interrupt	1 second or until next video access				
Video access or processor reset	1 millisecond				
Any NMI or IRQ interrupt, except keyboard or hard disk	1 millisecond				

TABLE 4-2. SPEEDUP ACTIVITY

Bits 10-08 - ALT_CLK_SPD, Alternate Clock Speed Featured only in the WD7710LP

> ALT_CLK_SPD 10 09 08

- 0 0 CPUCLK unchanged from CLK_SPD (Default value).
- 0 0 1 Equals source.
- 0 1 0 Equals source div by 2.
- 0 1 1 Equals source div by 4, 25% duty cycle.
- 1 0 0 Equals source div by 4, 75% duty cycle.
- 1 0 1 Equals source div by 8, 12% duty cycle.
- 1 1 0 Equals source div by 8, 88% duty cycle.

Bits 07-04 - EXT HOLD, Extend Processor Hold

Processor execution may be slowed for software compatibility by extending the processor hold request after refresh cycles. If the external TURBO signal is asserted, EXT_HOLD is forced to 0000. When the external TURBO signal is de-asserted, the EXT_HOLD returns to its programmed value, allowing an external TURBO switch to slow the processing speed.

7

EXT_HOLD 07 06 05 04

0 0 0 0 - No hold extension, (Default value).

0 0 0 1 - 1 us hold after refresh.

0 0 1 0 - 2 us hold after refresh.

0 0 1 1 - 3 μ s hold after refresh.

0 1 0 0 - 4 μs hold after refresh.

Ţ

1 1 0 1 - 13 μ s hold after refresh.

1 1 1 0 - 14 μ s hold after refresh.

1 1 1 - 15 us hold after refresh.

Bits 03-02 - Reserved for future use, must be set to zero

Bit 01 - SCHH, Stop CPUCLK at next Halt and Hold.

Featured only in the WD7710LP

SCHH is applicable only for 80C286 or Am386SXL type processors in which the clock may be stopped. This option should only be used when the clock source is the WD7710LP rather than an external oscillator

Any unmasked processor interrupt, or NMI, restarts the CPUCLK. The SCHH bit remains set and the clock will be stopped again if a halt and hold condition is detected. The refresh rate may be as programmed by the Refresh Timer at Port Address 041H, or at the slower rate selected by the Refresh Control Register at Port 2072H.

SCHH = 0 -

Normal processor clock (default value).

SCHH = 1 -

Stop processor clock at next halt and hold cycle.

Bit 00 - SCH, Stop CPUCLK at next Hold Featured only in the WD7710LP

SCH is applicable only for 80C286 or Am386SXL type processors in which the clock may be stopped. This option should only be used when the clock source is the WD7910LP instead of an external oscillator.

Any unmasked processor interrupt, or NMI, restarts the CPUCLK and sets the SCH bit to zero. DRAM refresh continues while the processor clock is stopped. The refresh rate may be as programmed by the Refresh Timer at Port Address 041H, or at the slower rate as selected by the Refresh Control Register at Port 2072H.

SCH = 0 -

Normal processor clock (Default value).

SCH = 1 -

Stop processor clock at next processor hold cycle.

5.0 AT BUS

This section describes the logic required to control the interrupts and timing between the AT bus and the System Controller.

5.1 INTERRUPT MULTIPLEXING

To reduce the number of pins required, the System Controller generates and outputs the MXCTL2-0 and DACKEN signals used by external logic to multiplex the DACKs, DRQs and IRQs down to single inputs. See Figure 5-1.

MXCTL2-0 are set to 100 during a System Reset (RSTIN) to provide a Bus Reset (BUS_RST), and to determine the ROM width (ROM8) and processor clock (CPUCLK) pin direction. See Table 5-1.

5.1.1 Data Acknowledge DACK7-5, 3-0

An external 74F138, 3 to 8 Decoder for desktop systems, or 74ACT138, 3 to 8 Decoder for laptop systems, uses MXCTL2-0 to generate the DACK7-5 and DACK3-0, which are applied to the AT bus. The unused combination develops the AT BUS_RST (bus reset). The decoder is enabled by the DACKEN signal from the System Controller.

5.1.2 Data Request DRQIN

The MXCTL2-0 signals are also used by an external 74F151, 8 to 1 Multiplexer for desktop systems, or 74ACT151, 8 to 1 Multiplexer for laptop systems, to develop the DRQIN signal received by the System Controller. The MXCLT2-0 signals are held stable during DMA transfers.

Immediately following a System Reset (RSTIN), DRQIN input 100 is sampled. If low, the processor clock (CPUCLK) pin is an output. If high, the CPUCLK starts as an output but is switched to an input shortly after RSTIN is de-asserted. See Table 5-1 and Figure 5-1. This controls the default value of CLK_SPD in the CPU Clock (CPUCLK) Control Register at Port 1072H. See section 4.2.4.

5.1.3 Interrupt Requests

The Interrupt Requests are multiplexed by the WD76C30. The multiplexing is performed as shown in Table 5-1 and Figure 5-1, and provides the System Controller with the IRQSET1 and IRQSET0 signals.

DRQIN, IRQSET1 and IRQSET0 are sampled by the System Controller at every rising edge of SYSCLK2. This allows all DMA, DRQ and IRQ lines to be sampled within 500 ns, when SYSCLK is 8 MHz.

The ROM8 input is sampled at the completion of a NRSTIN to determine ROM data width (ROM8). The RESCPU and A20GT inputs come from the 8042 keyboard controller.

5.1.4 AT Address Bus, Data Bus And Terminal Count (TC) Signal

The AT Address Bus SA19-00 and NBLE are generated from A19-00 with external latches and tristate buffers.

The AT Data Bus SD15-00 uses D15-00 and external bidirectional buffers.

The TC signal is generated by an external gate when DACKEN and CSEN are both asserted.

5.2 POWER MANAGEMENT CONTROL PMCIN

The power control signals are placed on the PMCIN input pin by way of an eight to one multiplexer, controlled by the MXCTL2-0 signals from the System Controller. In the WD7910, the TURBO signal may be connected directly to PMCIN. In the WD7710LP, the external 8:1 MUX is always used. See Figure 5-1. Bits 14 and 13 of Port 1872H (Section 5.3) control the power down of the processor and peripheral.



MXCTL 2 1 0	DRQIN	DACKEN	IRQSET0	IRQSET1	PMCIN
000 001 010 011 100	DRQ0 DRQ1 DRQ2 DRQ3 CLOCK_ DIR IN	DACK0 DACK1 DACK2 DACK3 BUS_RST	IRQ8 IRQ9 IRQ10 IRQ11 ROM8	IRQ12 IRQ1 A20GT IRQ3 IRQ4	TURBO PROC_PWR_GOOD LCL_RQ or USER DEF. USER DEF. USER DEF.
101 110 111	DRQ5 DRQ6 DRQ7	DACK5 DACK6 DACK7	RESCPU IRQ14 IRQ15	IRQ5 IRQ6 IRQ7	USER DEF. USER DEF. USER DEF.

TABLE 5-1. MXCTL2 - 0 DECODING

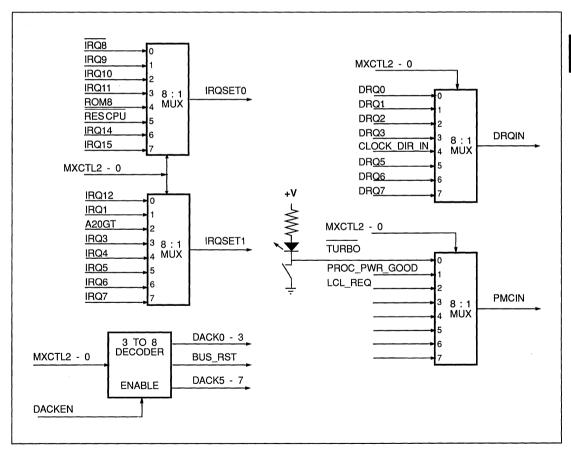


FIGURE 5-1. MXCTL2-0 MULTIPLEXING

WD7710/WD7710LP AT BUS

5.3 NUMERIC PROCESSOR

5.3.1 Numeric Processor Busy, Bus Timing, And Power Down Register

Port Address 1872H - Read and Write

15	14	13	12	11	10	09	08
NP_ BSY	PRO_ PD	FPD		BUS	_MOD	BRC	_DEL

07	06	05	04	03	02	01	00
BAR	C_DEL	WSI 16	WSM_ 16	_ WS	SI8	W	SM8

Signal Name								_	e <u>fault</u> t RSTIN
NP_BSY .									0
PRO_PD †		٠,							0
Bit 12									
FPD†									
BUS_MOD			٠.						00
BRQ_DEL									00
BAK_DEL									
WSI_16 .									
WSM_16	٠.								0
WS18									10
WSM8							•		10

† Featured only in the WD7710LP

Bit 15 - NP BSY, Numeric Processor Busy

NP_BSY must be set for systems using an 80286 CPU where the CPU runs faster than the AT bus. The causes BUSYCPU to be asserted early during any CPU write to I/O ports F8H through FFH. BUSYCPU is de-asserted at the end of the I/O write if the coprocessor has not asserted its own NPBUSY by this time. Early assertion of BUSYCPU is necessary to prevent a loss of synchronization between the 80286 and 80287. Bit 15 is ignored when an 80386SX is used.

NP BSY = 0 -

Force an early BUSYCPU for I/O writes to coprocessor addresses F8H through FFH. (Default value).

NP BSY = 1 -

Normal BUSYCPU assertion.

Bit 14 - PRO_PD, Processor Power Down Featured only in the WD7710LP

When PRO_PD has been changed from zero to one, a power down sequence for the 80286 or 80386SX processor will be initiated at the next Halt State and the expansion bus will continue to operate normally. The processor should not be powered down if DMA cycles are likely to occur. When PRO_PD is set and a halt state occurs, the processor inputs are ignored and appear to the WD7710LP to be in the passive state.

The input buffers connected to the processor signals do not consume power even if the processor signals do not reach ground. The internal pullups on inputs connecting to the processor are disabled to reduce power. PMC output 5 from Port 7072H (Processor Power Down) is set. This can be used to control the power transistor and turn off the power to the processor. All outputs going to the processor will be tristated.

When an unmasked interrupt, DRQ or NMI occurs, PMC output 5 is reset, re-powering the processor. A voltage comparator should be used to generate a Processor Power Good (PPG) signal. The PPG signal is sampled by bit 01 of the PMC Input Register at Port Address 8872H. When PPG is high, the outputs to the processor are driven and the processor is reset.

PRO PD = 0 -

Normal processor power (Default value).

PRO PD = 1 -

Start processor power down sequence.

Bit 13 - FPD, Full Powerdown

Featured only in the WD7710LP

When FPD equals one and a halt state occurs, all processor and peripheral outputs except the PMC, DRAM controls and RA/ED bus are tristated and all inputs except NRSTIN, CLK14 and PMC inputs are ignored. CAS before RAS refresh will be performed if enabled by Port 2072H. All circuitry except the PMC and refresh timer logic is stopped and PMC output 7 (Full Powerdown) from Port 7072H is set. This enables the powering down of all chips except DRAM, WD7710LP, WD76C20, WD76C30 and WD90C20. The WD76C20 provides NPDREF

(a 64 KHz refresh signal on input pin 117) during the power down mode. This signal is then gated by the System Controller to the REFRESH signal as an output on pin 32.

When a PMC interrupt occurs, PMC output 7 at Port 7072H is reset, enabling the power up sequence. A CPURES and BUS_RST (see Figure 5-1) are asserted until the PMCIN 01 PPG at Port 8872H input is high. The tristated outputs are restored and the inputs are no longer masked.

FPD remains a 1 until replaced by a 0.

FPD = 0 -

No power down (Default value).

FPD = 1 -

Full power down and in standby mode.

Bit 12 - Ignored by the System Controller, may be 0 or 1.

Bits 11, 10 - BUS MOD, Bus Mode

The System Controller defaults to mode 00 at power up. Therefore, the bus clock (SYSCLK) is controlled by BCLK2 and is asynchronous with CPUCLK (see Figure 4-1). This allows CPUCLK to be faster than SYSCLK and vary without affecting the bus timing. Normally, BCLK2 is either 16 MHz or 32 MHz. SYSCLK is divided by two regardless of the mode selected by BUS MOD, and if BCLK2 is 16 MHz at power up, it is divided by two again, providing a SYSCLK clock rate of 4 MHz until programmed to mode 01. In mode 01. the SYSCLK rate is 8 MHz for a BCLK2 of 16 MHz. Both mode 00 and 01 are asynchronous and require the appropriate synchronization delays to be established by BRQ DEL and BAK DEL of this register.

In modes 10 and 11, the SYSCLK is synchronous with the CPUCLK and synchronization delays are not needed. The bus clock mode may need to be reprogrammed when the processor clock changes.

Refer to Table 5-2 for the appropriate choices according to the CPU type and speed and AT bus speed employed.

BUS_MOD

11 10

- 0 0 Bus logic uses BCLK2 divided by 2 (Default value).
- 0 1 Bus logic uses BCLK2 divided by 1.
- 1 0 Bus logic uses CPUCLK divided by 2.
- 1 1 Bus logic uses CPUCLK divided by 1.

Bits 09, 08 - BRQ_DEL, Bus Request Delay

An asynchronous AT bus state machine requires a synchronization delay at the start of the bus cycle.

Refer to Table 5-2 for the appropriate choices according to the CPU type and speed and AT bus speed employed.

BRQ_DEL 09 08

0 0 - 1 Bus clock delay (Default value).

0 1 - .5 Bus clock delay.

1 0 - No clock delay.

1 1 - Reserved.

Bits 07, 06 - BAK DEL, Bus Acknowledge Delay

The AT bus state machine has several options available for signaling the CPU control logic that an AT bus cycle has completed. The timing of this signal determines AT bus hold time for the data and address. Proper timing is determined by the CPU speed, AT bus speed and whether they are synchronous or asynchronous. The delay settings listed here are referenced to the trailing edge of the AT command strobe.

Refer to Table 5-2 for the appropriate choices according to the CPU type and speed and AT bus speed employed.

BAK_DEL 07 06

0 0 - No delay.

0 1 - -.5 Bus clock delay.

1 0 - -1 Bus clock delay.

1 1 - +.5 Bus clock delay (Default value)

WD7710/WD7710LP AT BUS

Bit 05 - WSI16, Wait State for 16 bit I/0

WSI16 = 0 -

1 Bus clock wait state (Default value).

WSI16 = 1 -

2 Bus clock wait state

Bit 04 - WSM16, Wait State for 16 bit Memory

WSM16 = 0 -

1 Bus clock wait state (Default value).

WSM16 = 1 -

2 Bus clock wait state.

Bits 03, 02 - WSI8, Wait State for 8 bit I/O

WSI8

03 02

0 0 - 2 Bus clock wait state.

0 1 - 3 Bus clock wait state.

1 0 - 4 Bus clock wait state (Default value).

1 1 - 5 Bus clock wait state.

Bits 01, 00 - WSM8, Wait State for 8 bit Memory

WSM8

01 00

0 0 - 2 Bus clock wait state.

0 1 - 3 Bus clock wait state.

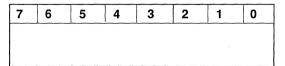
1 0 - 4 Bus clock wait state (Default value).

1 1 - 5 Bus clock wait state.

5.3.2 Numeric Processor Busy (NPBUSY) Reset

Port Address 0F0H - Write only

Writing any data to this port resets the 80287 busy signal (de-asserts NPBUSY). The data is ignored.



Signal Name								e <u>fault</u> it RSTIN
All signals								None

5.3.3 Numeric Processor Reset (NPRST)

Port Address 0F1H - Write only

Writing any data to this port asserts NPRST and resets the 80287. The main processor is wait stated for 128 clocks when writing to this port. The data is ignored.

7	6	5	4	3	2	1	0

Signal										C	e <u>fault</u>	
Name											Δ	t RSTIN
All signals												None

CPU TYPE	CPU SPEED	AT BUS SPEED	AT BUS MODE	BUS MOD	BRQ DEL	BAK DEL
80286	25 MHz	8 MHz	ASYNC	0X	00	00
	20 MHz	8 MHz	ASYNC	0X	01	01
	20 MHz	10 MHz	SYNC	10	10	10
	16 MHz	8 MHz	SYNC	10	10	10
	12.5 MHz	8 MHz	ASYNC	0X	01	10
	10 MHz	10 MHz	SYNC	11	10	10
	8 MHz	8 MHz	SYNC	11	10	10
80386SX	25 MHz	8 MHz	ASYNC	0X	01	00
	20 MHz	10 MHz	SYNC	10	10	10
	20 MHz	8 MHz	ASYNC	0X	01	00
	16 MHz	8 MHz	SYNC	10	10	10
	12.5 MHz	8 MHz	ASYNC	0X	01	10

TABLE 5-2. BUS TIMING PARAMETERS

5.4 DMA CONTROL

The System Controller contains two DMA controllers. DMA Controller 1 is in the I/O address space from 000H to 00FH and is used for 8-bit transfers. DMA Controller 2 is in the I/O space from 0C0H to 0DEH and is used for 16-bit transfers. Channel 0 of DMA Controller 2 is used to cascade DMA controller #1. Table 5-4 indentifies the Controller/Channel location and function.

AT BUS DMA CHANNEL	DMA CONTROLLER	TRANSFER TYPE
0	#1 Channel 0	8-bit
1 1	#1 Channel 1	8-bit
2	#1 Channel 2	8-bit
3	#1 Channel 3	8-bit
4	#2 Channel 0	Cascade DMA Cont. #1
5	#2 Channel 1	16-bit
6 7	#2 Channel 2 #2 Channel 3	16-bit 16-bit

TABLE 5-3. DMA TRANSFER TYPES

5.4.1 Transfer Modes

Each DMA channel may be programmed in Single Transfer Mode, Block Transfer Mode, Demand Transfer Mode or Cascade Mode.

Refer to Section 5.4.12 - Mode Register, bits 7 and 6 for programming.

Demand Mode - 00

In demand mode, a transfer continues to take place until DRQ is de-asserted or a Terminal Count (TC) is reached. If the DRQ is de-asserted, the bus will be released. If DRQ is re-asserted, the transfer will resume. The address and word count behave as in single mode.

Single Transfer Mode - 01

In single transfer mode, the channel makes one transfer for each request. The word count is decremented, and the address is incremented or decremented at the end of each transfer. When the word count goes from 0000H to FFFFH, a Terminal Count (TC) is generated. To start a transfer, the DRQ should be asserted until a DACK is received. If the DRQ is asserted through the cycle, only one transfer will take place. The DRQ must

be de-asserted and then re-asserted to start another transfer. The bus is released between transfers.

Block Transfer Mode - 10

A transfer is started in block mode by a DRQ and continues until a TC is reached. The DRQ should be held active until DACK is asserted. Block mode should be used with caution since refresh is locked out. The address and word count behave as in single mode.

Cascade Mode - 11

Cascade mode is used to cascade DMA controller #2 to DMA controller #1, and for bus master transfers. A channel in cascade mode gets the bus when a DRQ is asserted, but the word count and address are ignored. The channel holds the bus until DRQ is deasserted. The IOR, IOW, MEMR and MEMW signals must be generated by the bus master device. The addresses from the System Controller are tristated when the MASTER signal is asserted.

5.4.2 Transfer Types

There are three types of transfers: verify, write and read.

Refer to Section 5.4.12 - Mode Register, bits 3 and 2 for programming.

Verify - 00

A verify transfer is a pseudo transfer that does not generate $\overline{\text{IOR}}$, $\overline{\text{IOW}}$, $\overline{\text{MEMR}}$ or MEMW signals.

Write - 01

A write transfers data from an I/O device to memory.

Read - 10

A read transfers data from memory to an I/O device.

5.4.3 Autoinitialize

A channel may be programmed to autoinitialize for any transfer type. In this mode, when a TC is reached, the channel is loaded with the original word count and address and is ready to start another transfer.

Refer to Section 5.4.12 - Mode Register, bit 4 for programming.

5.4.4 Priority

Each DMA controller has two types of priority, fixed and rotating. For fixed priority, channel 0 has the highest priority and channel 3 has the lowest. In rotating priority, the last channel to be serviced has the lowest priority.

5.4.5 Extended Write

In normal timing, the <u>MEMR</u> or <u>IOR</u> pulse is two clock cycles and the <u>MEMW</u> or <u>IOW</u> is one clock cycle. If extended write is selected, the <u>MEMW</u> or <u>IOW</u> will be the same as the <u>MEMR</u> or <u>IOR</u>.

5.4.6 Base and Current Address

Each channel has a 16-bit base and current address register. The current address register is loaded from the base register when the base register is loaded or when in autoinitialize mode. The current address register is incremented or decremented during a transfer.

Addresses are driven to the bus while REFRESH is asserted, indicating a refresh cycle. Only address bits A23-A16 (from the page register) and bits A10-A0 (from the refresh counter) are meaningful during refresh. The address counter is incremented on the rising edge of REFRESH.

5.4.7 Base and Current Word Count

Each channel has a 16-bit base and current word count register. The current word count register is loaded from the base register when the base register is loaded or when in autoinitialize mode. The current word count is decremented during a transfer.

I/O Address Hex	Read/Write	DMA Controller	Function
000	Read/Write	1	Channel 0 Address
001	Read/Write	1	Channel 0 Word Count
002	Read/Write	1	Channel 1 Address
003	Read/Write	1	Channel 1 Word Count
004	Read/Write	1	Channel 2 Address
005	Read/Write	1	Channel 2 Word Count
006	Read/Write	1	Channel 3 Address
007	Read/Write	1	Channel 3 Word Count
008	Read	1	Status
800	Write] 1	Command Register
009	Write] 1	Request Register
00A	Write	1	Single Mask
00B	Write	1	Mode Register
00C	Write	1	Clear Pointer
00D	Write	1	Master Clear
00E	Write	1	Clear Mask
00F	Write	1	Mask All
080-09F			DMA Page Register
0C0	Read/Write	2	Channel 0 Address
0C2	Read/Write	2	Channel 0 Word Count
0C4	Read/Write	2	Channel 1 Address Channel 1 Word Count
0C6	Read/Write	2	Channel 2 Address
0C8	Read/Write	2	Channel 2 Word Count
0CA 0CC	Read/Write	2	Channel 3 Address
OCE	Read/Write Read/Write	2	Channel 3 Word Count
0D0	Read/write Read	2	Status
0D0	Write	2	Command Register
0D0 0D2	Write	2	Request Register
0D2 0D4	Write	2	Single Mask
0D4 0D6	Write	2	Mode Register
0D8	Write	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	Clear Pointer
0D8 0DA	Write	2	Master Clear
0DC	Write	2	Clear Mask
0DE	Write	2	Mask All
B872	Read	1, 2	DMA Mode Shadow
50, 5	1	.,_	

TABLE 5-4. DMA CONTROLLER/CHANNEL FUNCTION MAP

5.4.8 Command Register

Port Addresses 008H, 0D0H - Write only

The Command Register is reset by RSTIN or by writing any data to Port Address 00DH or 0DAH (see section 5.4.14).

7	6	5	4	3	2	1	0
		EX_ WR	RO_ PRI	0	CO_ DIS		

Signal Name	De <u>fault</u> At RSTIN
All signals	 . 0

Bits 7, 6 - Not used, state is ignored

Bit 5 - EX WR, Extended Write

Bit 4 - RO_PRI, Rotating Priority

Bit 3 - Must be set to 0

Bit 2 - CO DIS, Controller Disabled

Bits1, 0 - Not used, state is ignored

5.4.9 Status Register

Port Addresses 008H, 0D0H - Read only

Bits 3-0 are reset by $\overline{\text{NRSTIN}}$, writing any data to Port Address 00DH or 0DAH (see section 5.4.14) or when read by a Status Read Command.

7	6	5	4	3	2	1	0
CH3_	CH2_	CH1_	CH0_	CH3_	CH2_	CH1_	CH0
DRQ	DRQ	DRQ	DRQ	TC	TC	TC	TC

Signal Name		fault RSTIN
CH3_DRQ - CH0_DRQ		
CH3 TC - CH0 TC	 	 0

Bit 7 - CH3 DRQ, Channel 3 DRQ active

Bit 6 - CH2_DRQ, Channel 2 DRQ active

Bit 5 - CH1 DRQ, Channel 1 DRQ active

Bit 4 - CHO DRQ, Channel 0 DRQ active

Bit 3 - CH3_TC, Channel 3 has reached TC

Bit 2 - CH2 TC, Channel 2 has reached TC

Bit 1 - CH1 TC, Channel 1 has reached TC

Bit 0 - CH0 TC, Channel 0 has reached TC

5.4.10 Request Register

Port Addresses 009H, 0D2H - Write only

Each channel may be started by a software request. These requests are not affected by the Mask Register. The Request Register is reset by RSTIN or by writing any data to Port Address 00DH or 0DAH (see section 5.4.14).

7	6	5	4	3	2	1	0
					CRQ	CH	! #

Signal	De <u>fault</u>
Name	At RSTIN
All signals	0

Bits 7-3 - Not used, state is ignored

Bit 2 - CRQ, Channel Requested

Bits 1, 0 - CH#, Channel Number Requested

CH# 1 0

0 0 - Channel 0

0 1 - Channel 1

1 0 - Channel 2

1 1 - Channel 3

5.4.11 Mask Registers

Each channel has a mask bit associated with it If it is set, the channel is disabled. The bits may be set or reset by software, or set by a Terminal Count (TC) if the channel is not in autoinitialize mode. All the bits are set by a RSTIN, or by writing any data to Port Address 00DH or 0DAH (see section 5.4.14).

5.4.11.1 Single Mask Register

Port Addresses 00AH, 0D4H - Write only

7	6	5	4	3	2	1	0
					SE_ MA	C⊦	l#

Signal	De <u>fault</u>
Name	At RSTIN
All signals	1

Bits 7-3 - Not used, state is ignored

Bit 2 - SE_MA, Set Mask

SE_MA = 0 -Clear Mask

SE_MA = 1 -Set Mask

Bits 1, 0 - CH#, Channel Number Requested

CH# 1 0

0 0 - Channel 0

0 1 - Channel 1

1 0 - Channel 2

1 1 - Channel 3

5.4.11.2 Clear Mask Register

Port Addresses 00EH, 0DCH - Write only

Writing any data to this register resets all Masks. The data is ignored.

7	6	5	4	3	2	1	0
	·				·		

Signal Name								_	e <u>fault</u> it RSTIN
All signals									None

Bits 7-0 - Not used, state is ignored

5.4.11.3 Mask Multiple Register

Port Addresses 00FH, 0DEH - Write only

7	6	5	4	3	2	1	0
				CH3_ MA	CH2_ MA	CH1_ MA	CH0_ MA

Signal Name								_	e <u>fault</u> t RSTIN
All signals									1

Bits 7-4 - Not used, state is ignored

Bit 3 - CH3 MA, Channel 3 Mask

Bit 2 - CH2_MA, Channel 2 Mask

Bit 1 - CH1_MA, Channel 1 Mask

Bit 0 - CH0 MA, Channel 0 Mask

5.4.12 Mode Register

Port Addresses 00BH, 0D6H - Write only

This register selects the mode and type of transfer for each channel. Refer to sections 5.4.1 through 5.4.1.4 for a description of the Transfer Modes, sections 5.4.2 through 5.4.2.3 for a description of the Transfer Types and section 5.4.3 for a description of Autoinitialize.

7	6	5	4	3	2	1	0
TR. MC	A_ DD	AD_ DEC	AUTO	TR TY		CH SE	IA# L

Signal	De <u>fault</u>
Name	At RSTIN
All eignale	None

Bits 7, 6 - TRA_MOD, Transfer Mode

TRA_MOD

7 6

0 0 - Demand

0 1 - Single

1 0 - Block

1 - Cascade

Bit 5 - AD DEC, Address Decrement

AD DEC = 0

Address is incremented.

AD DEC = 1

Address is decremented after each DMA cycle.

Bit 4 - AUTO. Autoinitialize

AUTO = 0

Autoinitialization is disabled.

AUTO = 1

Autoinitialization is enabled.

Bits 3, 2 - TRA_TYP, Transfer Type

TRA_TYP

 $\overline{3}$ 2

0 0 - Verify

0 1 - Write

1 0 - Read

1 - Not used

Bits 1, 0 - CHA# SEL, Channel Select

CHA# SEL

1 0

0 0 - Channel 0

0 1 - Channel 1

1 0 - Channel 2

1 1 - Channel 3

5.4.13 Clear Pointer Register

Port Addresses 00CH, 0D8H - Write only

Each DMA controller has a pointer flip-flop that indicates which half of the word count or address is being accessed. Each time a word count or address is written or read, the pointer changes state. When the flip-flop is reset, bits 7-0 are accessed, and when it is set, bits 15-8 are accessed. The pointer is reset by writing any data to the Clear Pointer Register, or to Port Address 00DH or 0DAH (see section 5.4.14). In either case, the data is ignored.

7	6	5	4	3	2	1	0

Signal Name								De <u>fault</u> At RSTIN
All signals					_			None

Bits 7-0 - Not used, state is ignored

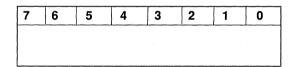
5.4.14 Master Clear Rgister

Port Addresses 00DH, 0DAH - Write only

Writing any data to the Master Clear Register will:

- 1. Clear the Command Register
- 2. Clear the Status Register
- 3. Clear the Request Register
- 4. Set the Mask Register
- 5. Clear the Pointer Flip-Flop

All data is ignored.



Signal Name									De <u>fault</u> At RSTIN
Name								•	M HOIM
All signals									None

Bits 7-0 - Not used, state is ignored

5.4.15 DMA Mode Shadow Register

Port Address B872H - Read only

This register is particularly useful in laptop applications by allowing the suspend/resume software to restore correct status to on-board devices.

15	14	13	12	11	10	09	08				
DMA1 MODE											

07	06	05	04	03	02	01	00
			DMA2	MODE			

Signal Name	De <u>fault</u> At RSTIN
DMA1 MODE	 0
DMA 2 MODE	0

Bits 15-08 - DMA1 MODE

DMA 1 MODE contains a copy of the data written into the DMA1 Mode Register located at I/O address 00BH (see Table 5-4).

Bits 07-00 - DMA 2 MODE

DMA 2 MODE contains a copy of the data written into the DMA2 Mode Register located at I/O address 0D6H (see Table 5-4).

5.5 SYSTEM CONTROLLER 8259 INTER-RUPT CONTROLLERS

The System Controller contains two interrupt controllers. Interrupt Controller 1 is in the I/O space of 020H to 021H and Interrupt Controller 2 is in the I/O space of 0A0H to 0A1H. Interrupt 2 of Interrupt Controller 1 is used to cascade Interrupt Controller 2.

5.5.1 Interrupt Sequence

 When an interrupt arrives from a peripheral device, the interrupt may only be programmed to be edge sensitive. In this mode, the interrupt must go low and high for each interrupt. The interrupt sets the appropriate bit in the Interrupt Request Register (IRR).

System interrupt	Interrupt Controller	Use
0	#1 Level 0	Timer
1	#1 Level 1	Keyboard
2	#1 Level 2	Cascade
3-7	#1 Level 3 - 7	AT Bus
8	#2 Level 0	RTC
9-12	#2 Level 1-4	AT Bus
13	#2 Level 5	Co-Processor
14-15	#2 Level 6-7	AT Bus

TABLE 5-5. INTERRUPT SEQUENCE

If the interrupt has not been masked off, it is passed to the priority circuit. There are three types of priority.

Fixed

In fixed priority, interrupt 0 has the highest priority and interrupt 7 has the lowest.

Automatic Rotation

In automatic rotation, the last interrupt serviced has the lowest priority.

Specific Rotation

In this mode, the lowest priority interrupt can be set by software. The next interrupt will have the highest priority. For example if interrupt 4 is set to the lowest level, the priority will be 5, 6, 7, 0, 1, 2, 3 and 4.

- 3. The interrupt controller sends an IRQ to the CPU.
- 4. The CPU responds with an INTA cycle that freezes priority.
- 5. The CPU sends another INTA, causing the interrupt controller to send a vector to the CPU, set the appropriate bit in the Interrupt Service Register (ISR) and clear the corresponding bit in the IRR, if it is in the edge triggered mode. As long as the bit in the ISR is set, all interrupts at the same level or lower are inhibited unless programmed for special mask mode.

6. An EOI is issued to end the interrupt. This clears the appropriate bit in the Interrupt Service Register. For the slave adapter (interrupt controller #2), two EOI's must be issued. There are three types of EOI's, Specific, Nonspecific and Automatic.

Specific

An EOI is issued by software for a specific interrupt.

Non-Specific

A non-specific EOI is also issued by software. The hardware generates an EOI for the highest level active interrupt.

Automatic

An automatic EOI is a non-specific EOI that is caused by the second INTA.

The interrupt controllers may also be operated in a polled mode. In this mode, the CPU is set to disable the interrupt input. In this case, software must issue a poll command. This takes the place of an INTA, and the software can then read the interrupt level to determine the interrupt to be serviced.

When cascading is used and the slave has issued an interrupt, other interrupts from the slave are locked out. If it is desired to preserve priority in the slave (i.e., allow higher interrupts to occur when a lower interrupt is being serviced), Special Fully Nested Mode should be programmed in the master. After a non-specific EOI has been sent to the slave, the ISR should be checked to see whether any other interrupts are active. If there are no interrupts active, a non-specific EOI should be sent to the master.

Interrupt Controller	Address Hex	Function	Read/write
Oomioner			
1	020	ICW1	Write
1	021	ICW2	Write
1	021	ICW3	Write
1	021	ICW4	Write
1	021	OCW1	Write
1	020	OCW2	Write
1	020	OCW3	Write
1	020	IRR	Read
1	020	ISR	Read
1	021	Mask	Read
1	020, 021	Interrupt Level	Read
2	0 A 0	ICW1	Write
2	0A1	ICW2	Write
2 2 2	0A1	ICW3	Write
2	0A1	ICW4	Write
2 2	0A1	OCW1	Write
2	0 A 0	OCW2	Write
2 2	0 A 0	OCW3	Write
2	0 A 0	IRR	Read
2	0 A 0	ISR	Read
2	0A1	Mask	Read
2 2	0A0, 0A1	Interrupt Level	Read

TABLE 5-6. INTERRUPT CONTROLLER FUNCTION MAP

Z

5.5.2 Setup - Initialization Command Words (ICW)

The interrupt controllers are set up by writing a series of Initialization Command Words (ICW). The sequence is started by writing a one to bit 4 of ICW1. If ICW4 is to be included in the sequence, a one must also be written to bit 0 of the ICW1.

5.5.2.1 ICW1 - Initialization Command Word 1

Port Addresses 020H, 0A0H - Write only

Bit 4 of this register must be set to 1 or it will be interrpreted as OCW2 or OCW3.

7	6	5	4	3	2	1	0
			S_S	L_T		N C_M	ICW 4

Signal Name								_	e <u>fault</u> t RSTIN
All signals									None

Bit 7-5 - Not used, state is ignored

Bit 4 - S S, Start Sequence

S S Must be set to 1

Bit 3 - L T, Level Trigger

The Interrupt Controller may be programmed to support Level Sensitive Mode for diagnostic adapters which may need to test this capability.

 $L_T = 0 -$

Edge Triggered Mode is selected.

 $L_T = 1 -$

Level Triggered Mode is selected. EN_LVL (bit 00) in Port A872H must first be set to 1.

Bit 2 - Not Used, state is ignored

Bit 1 - N C M, Not Cascade Mode

NCM=0

Cascade Mode selected

NC M = 1 -

Single Mode selected

Bit 0 - ICW4. Initialization Control Word 4

ICW4 = 0 -

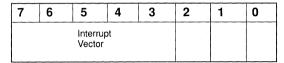
ICW4 not included in sequence

ICW4 = 1 -

ICW4 is included in sequence

5.5.2.2 ICW2 - Initialization Command Word 2

Port Addresses 021H, 0A1H - Write only



Signal	De <u>fault</u>
Name	At RSTIN
All eignale	None

Bits 7-3 - Interrupt Vector

Bits 2-0 - Not used, state is ignored

5.5.2.3 ICW3 - Initialization Command Word 3

Port Addresses 021H - Write only

This address accesses only Interrupt Controller 1.

7	6	5	4	3	2	1	0
0	0	0	0	0	12 H_L	0	0

Signal								D	efault_
Name								Α	t RSTIN
All signals									None

Bits 7-3 - Not used, must be set to 0

Bit 2 - I2 H L, Interrupt 2 Has Slave

12 H L = 0 -

Interrupt 2 does not have the Slave

12 H L = 1 -

Interrupt 2 has the Slave

Bits 1-0 - Not used, must be set to 0

WD7710/WD7710LP AT BUS

Port Addresses 0A1H - Write only

This address accesses only Interrupt Controller 2.

7	6	5	4	3	2	1	0
0	0	0	0	0	s	lave ID	

Signal Name								e <u>fault</u> it RSTII	ī
All signals								None	

Bits 7-3 - Not used, must be set to 0

Bits 2-0 - Slave ID

5.5.2.4 ICW4 - Initialization Command Word 4

Port Addresses 021H, 0A1H - Write only

A Slave does not have ICW4.

7	6	5	4	3	2	1	0
0	0	0	S F N M	0	0	AUT EOI	1

Signal Name								 e <u>fault</u> t RSTIN
All signals								None

Bits 7-5 - Not used, must be set to 0

Bit 4 - S F N M, Special Fully Nested Mode

S F N M = 0 -Not Special Fully Nested Mode

S F N M = 1 -Special Fully Nested Mode

Bits 3-2 - Not used, must be set to 0

Bit 1 - AUT_EOI, Auto End Of Interrupt

AUT_EOI = 0 Normal End Of Interrupt

AUT_EOI = 1 Automatic End Of Interrupt

Bit 0 - Not used, must be set to 1

5.5.3 Operation

Once the interrupt controllers are set up, they may be programmed by Operation Control Words One through Three (OCW1:3).

5.5.3.1 OCW1 - Operation Control Word 1

Port Address 021H, 0A1H - Write only

7	6	5	4	3	2	1	0
INT	INT	INT	INT	INT	INT	INT	INT
7_M	6_M	5_M	4_M	3_M	2_M	1_M	0_M

Signal		Default
Name		At RSTIN
All signals	 	None

Bit 7 - Interrupt 7 Mask

Bit 6 - Interrupt 6 Mask

Bit 5 - Interrupt 5 Mask

Bit 4 - Interrupt 4 Mask

Bit 3 - Interrupt 3 Mask

Bit 2 - Interrupt 2 Mask

Bit 1 - Interrupt 1 Mask

Bit 0 - Interrupt 0 Mask

5.5.3.2 OCW2 - Operation Control Word 2

Port Address 020H, 0A0H - Write only

7	6	5	4	3	2	1	C
E	EOI_CC	TN	0	0		INT_LE	ΞV

_	_	^	•	_	^1	พว
-	-		3	- ()	1	m i

Port Address 020H, 0A0H - Write only

7	6	5	4	3	2	1	0
0	s	MM	0	1	P_C	IRR_	_ISR

Signal Name								Default At RSTIN
All signals								. None

Bits 7-5 - EOI CONT, End Of Interrupt

EOI CONT 7 0 0 0 - Clear Botate On Automatic EOI 0 0 1 - Non-specific EOI 0 1 0 - Not used 0 1 1 - Specific EOI 1 0 0 - Set Rotate on Automatic EOI 0 1 - Rotate on Non-1 Specific EOI 1 1 0 - Set Priority 1 - Rotate on Specific EOI

Bits 4, 3 - Must be set to 0

Bits 2-0 - INT LEV, Interrupt Level

To enable the setting of the interrupt level (INT_LEV), EOI_CONT must be set to 1 1 0 (Set Priority).

Default Signal Name At RSTIN All signals . None

Bit 7 - Must be set to 0

Bits 6, 5 - SMM, Special Mask Mode

SMM 5 6 0 n Not used Not used 0 1 Reset Special Mask Mode

Bit 4 - Must be set to 0

Bit 3 - Must be set to 1

Bit 2 - P C, Poll Command

PC=0-No Poll Command

PC=1-Poll Command

Bits 1-0 - IRR ISR, Interrupt Request Register and Interrupt Service Register

Set Special Mask Mode

IRR ISR 1 0 0 - Not used 0 1 - Not used 1 0 - Read Interrupt Request Register 1 1 - Read Interrupt Service Register

5.6 SYSTEM CONTROLLER 8254 TIMER

The System Controller contains an 8254 equivalent timer containing three independent counters. All the timers run off of a 1.19 MHz clock derived from the 14.318 MHz clock input. The GATE0 and GATE1 signals are tied high. The GATE2 signal is tied to register 61H, bit 0. The counters decrement when counting. The largest possible count is 0.

Each counter may be programmed for different counting modes and the count may be read back. To initialize a counter, the Control Word must be written, followed by one or two bytes of count if needed. Refer to Table 5-7 for the correct Control Word Format. Each counter may be programmed to count in BCD or binary.

I/O ADDRESS	USE	READ/ WRITE
040H	Timer 0 Count/Status	Read/Write
041H	Timer 1 Count/Status	Read/Write
042H	Timer 2 Count/Status	Read/Write
043H	Control Word	Write

TIMER CHANNEL	USE
0	Time of Day (Interrupt)
1	Refresh Request
2	Speaker

CONTROL V	VORD (FORMAT	1) - I/O Address 043H - Counter Latch Command
0	BCD	
1-3	Mode	000 Mode 0 001 Mode 1 X10 Mode 2 X11 Mode 3 100 Mode 4
4-5	Function	 101 Mode 5 00 Counter Latch Command 01 Read/Write Low Byte 10 Read/Write High Byte 11 Read/Write Low Byte then High Byte
6-7	Counter	OO Counter 0 O1 Counter 1 10 Counter 2
CONTROL V	VORD (FORMAT	2) - I/O Address 043H - Read Back Command
0 1 2 3 4 5 6-7		0 Select Counter 0 Select Counter 1 Select Counter 2 Latch Status Latch Count

TABLE 5-7. CONTROL WORD FORMAT

5.6.1 Setup

Each counter may be set in one of six modes by writing a Control Word (format 1). The Control Word must specify the counter and the number of count bytes to be written. A new count may be written at any time.

5.6.1.1 Mode 0 Interrupt on Terminal Count

The counter starts when the count is loaded. When the count = 0, the counter continues counting from FFFFH in binary mode or 9999 in BCD mode. GATE = 1 enables counting. GATE = 0 disables counting.

OUT goes low when the counter starts. It goes high when the count = 0, and stays high until a new count or mode is written.

If a new count is written while the counter is counting, it will be loaded on the next clock pulse.

5.6.1.2 Mode 1 Hardware Retriggerable One Shot

The counter starts when GATE goes from low to high. When the count = 0, the counter continues counting from FFFFH in binary mode or 9999 in BCD mode.

Any time GATE goes from low to high, the counter is reloaded with the original count and the counter started.

OUT goes low when GATE goes from low to high. It goes high when the count = 0. If a new count is written while the counter is counting, it will be loaded the next time GATE goes from low to high.

5.6.1.3 Mode 2 Rate Generator

The counter starts when the count is loaded. When the count = 0, the counter is reloaded and the counter is started again. GATE = 1 enables counting. GATE = 0 disables counting. If GATE goes from low to high, the counter is reloaded.

OUT is initially high. When the count = 1, OUT goes low for one clock.

If a new count is written while the counter is counting, it will be loaded the next time the count = 0 or when GATE goes from low to high.

5.6.1.4 Mode 3 Square Wave Generator

The counter starts when the count is loaded. When the count = 0, the counter is reloaded and the counter started again. GATE = 1 enables counting. GATE = 0 disables counting. If GATE goes from low to high, the counter is reloaded.

When the counter starts, OUT is high. When the count is half done, OUT goes low. If GATE goes low then OUT will go high.

If a new count is written while the counter is counting, it will be loaded the next time the count = 0 or when GATE goes from low to high.

5.6.1.5 Mode 4 Software Triggered Strobe

The counter starts when the count is loaded. When the count = 0, the counter continues counting from FFFFH in binary mode or 9999 in BCD mode. GATE = 1 enables counting. GATE = 0 disables counting. OUT is initially high. When the count = 0, OUT goes low for one clock.

If a new count is written while the counter is counting, it will be loaded on the next clock pulse.

5.6.1.6 Mode 5 Hardware Triggered Strobe

The counter starts when the count is loaded. When the count = 0, the counter continues counting from FFFFH in binary mode or 9999 in BCD mode. GATE = 1 enables counting. GATE = 0 disables counting. If GATE goes from low to high, the counter is reloaded. OUT is high when the counter starts. When count = 0, OUT goes low for one clock. If a new count is written while the counter is counting, it will be loaded the next time the count = 0 or when GATE goes from low to high.



5.6.2 Reading The Counter

There are three ways of reading the counters:

- The count is read directly. This mode can cause false readings due to the fact that the counter may be changing while it is read.
- The count may be read via a Counter Latch Command. (See Control Word format 1). This command latches the count so that it may be read without changing.
- The count may be read via a Read Back Command. (See Control Word format 2). This command is the equivalent of multiple Counter Latch Commands.

5.6.3 Reading Status

The status of a counter may be read by issuing a Read Back Command with data bit 4 = 0. (See Control Word format 2). Bits 0-5 are the same as the command word for the counter. Bit 6 tells whether the last count that was written has been loaded into the counter. Bit 7 reflects the state of the OUT pin.

STATUS WORD	
0	BCD
1-3	Mode
4-5	Function
6	New Count Written
7	Out Status

5.6.4 Page

The page register is an 8-bit by 16-byte dual-ported RAM. It is used during refresh cycles and to generate address bits 16 to 23 for 8-bit DMA transfers and address bits 17 to 23 for 16-bit DMA transfers. One port of the RAM is a read-only port for DMA or refresh cycles and the other is a read/write port for the 80286 CPU.

5.6.5 Refresh Address

This block contains an 11-bit counter that is used for the address during a refresh.



5.7 SYSTEM CONTROLLER DECODE

ADDRESS										DECODES	HEX
9	8	7	6	5	4	3	2	1	0		
0 0 0 0 0 0 0 0	0	0 0 0	1 1 1	1 1 1 0	X X 0 1 1 X 1 X	XXXXXXXXX	X X X X 0	X X X X X X X X X X X X X X X X X X X	X	DMA Controller 1 (Ch 0-3) Interrupt Controller Master Timer Port B (PIO) Real-Time Clock (Address) Real-Time Clock (Data) Page Register (except 092H) ALT 20 GATE, Hot Reset Interrupt Controller Slave DMA Controller 2 (Ch 4-7)	000-00F 020-03F 040-05F 061-06F (odd) 070-07E (even) 071-07F (odd) 080-09F 092 0A0-0BF 0C0-0DF

TABLE 5-8. DECODE ADDRESSES

5.7.1 Page Register Decodes

Address	Decode
0087H	DMA Channel 0
0083H	DMA Channel 1
0081H	DMA Channel 2
0082H	DMA Channel 3
008BH	DMA Channel 5
0089H	DMA Channel 6
008AH	DMA Channel 7
008FH	Refresh

TABLE 5-9. PAGE REGISTER DECODES

NOTE

Page register data appears on address bits A23-A16 during refresh and 8-bit DMA cycles. For 16-bit DMA cycles (channels 5-7), the LSB of the page register does not appear.

5.8 NMI AND REAL TIME CLOCK

5.8.1 Real Time Clock Address Register

Port Address 070H-07EH even - Write only

There is only one RTC Address Register. All even number addresses from 070H through 07EH access this register.

7	6	5	4	3	2	1	0
	RTC						
	A6	A5	A4	A3	A2	A1	A0

Signal Name	De <u>fault</u> At RSTIN			
D_NMI			1	
RTC6 - RTC0				

Bit 7 - D NMI, Disable Non-Maskable Interrupt

D NMI = 0 -

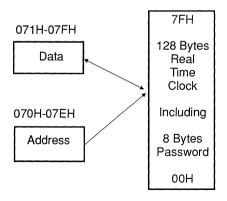
Non-Maskable Interrupt enabled

D NMI = 1 -

Non-Maskable Interrupt disabled (Default value)

Bits 6-0 - RTCA6 through RTCA0, Real-Time Clock Address

RTCA6 through RTCA0 provide the 128 addresses of the Real-Time Clock area. The data selected by this address is available by reading the RTC Data Register at the odd numbered locations, 071H-07FH.



5.8.2 Real-Time Clock Data Register

Port Address 071H-07FH odd - Read and Write

There is only one RTC Data Register. All odd number addresses from 071H through 07FH access this register.

Data is transferred between this register and the memory location selected by the RTC Address Register. The data bus used is selected by bit 15 of the register at Port Address 2872H (refer to section 7.2).

7	6	5	4	3	2	1	0						
	Real-Time Clock Data												

5.8.3 Lock Pass, Alternate A20G And Hot Reset

Port Address 092H - Read and Write

7	6	5	4	3	2	1	0		
				LOCK_ PASS		ALT_ A20G	HOT_ RST		

Signal Name								De <u>fault</u> At RSTIN			
Bits 7-4, 2											None
LOCK_PASS											0.
ALT_A20G .			٠.								0
HOT_RST .											0

Bit 3 - LOCK PASS

LOCK_PASS is used to prevent access to the eight byte password located in the Real-Time Clock area. The protected addresses are 38H through 3FH. Before LOCK_PASS can be set, bit 02 of the register at Port Address 2872H must be set to 0. Once LOCK_PASS is set, it can only be reset by NRSTIN.

LOCK PASS = 0 -

The eight byte password area is accessible.

LOCK PASS = 1 -

The eight byte password area is not accessible.

Bit 1 - ALT A20G. Alternate A20 Gate

Normally, the state of ALT_A20G is ORed with the external A20GT signal. If either ALT_A20G or A20GT is high, the A20 line is ungated. If both ALT-A20G and A20GT are low, A20 will be gated low.

As an option, ALT_A20G may be programmed by the Diagnostic Register at Port Address 9872H to automatically change state to match that of the Keyboard's A20GATE.

Bit 0 - HOT RST, Hot Reset

A processor reset (CPURES) is generated 128 CPUCLKs after the HOT_RST changes from a 0 to 1. The CPURES is 16 clock pulses wide.

5.9 PARITY ERROR AND I/O CHANNEL CHECK

Port Address 061H- 06FH odd Bits 7-4 - Read only, Bits 3-0 - Read and Write

Odd numbered Port Addresses 061H through 06FH provide access to parity error and I/O Channel Check of the expansion bus.

7	6	5	4	3	2	1	0
PE	IOCK	OUT 2	REF DT	D_ IOC	D_ PE	ENS PK	TMR 2G

Signal Name									_	e <u>fault</u> t RSTIN
PE										0
IOCK										0
OUT2										NA
REFDT										1
D_IOC										0
D_PE										0
ENSPK										0
TMR2G										0

Bit 7 - PE, Parity Error (read only)

PE = 0 -

No Parity Error

PE = 1 -

Parity Error

Bit 6 - IOCK, I/O Channel Check from the expansion bus (read only)

IOCK = 0 -

No I/O Channel Check Error

IOCK = 1 -

I/O Channel Check Error

Bit 5 - OUT2, from timer channel 2 (read only)

OUT2 represents the state of the Timer 2 output.

Bit 4 - REFDT, changes state on each refresh (read only)

Bit 3 - D_IOC, Disable I/O Channel Check (read and write)

D IOC = 0 -

I/O channel check from the expansion bus is not disabled.

D IOC = 1 -

I/O channel check from the expansion bus is disabled.

Bit 2 - D_PE, Disable Parity Error Check (read and write)

DPE = 0

Parity error checking not disabled. This may be overridden by Port Address register 6072H, bit 10 for systems without parity RAM.

D PE = 1 -

Parity error checking disabled

Bit 1 - ENSPK, Enable Speaker

ENSPK = 0 -

Speaker is not enabled

ENSPK = 1 -

Speaker is enabled

Bit 0 - TMR2G, Gate for Timer Channel 2

TMR2G = 0 -

Timer Channel 2 gated low

TMR2G = 1 -

Timer Channel 2 output enabled

6.0 MEMORY AND EMS CONTROL

This section describes the DRAM address bus and the EMS memory configuration and control registers.

6.1 DRAM ADDRESS AND DATA BUS

The memory address bus is multi-functional. During DRAM cycles, the DRAM row and column addresses are present on RA11 through RA0. During I/O cycles, RA11 through RA08 (CS3-CS0) are used to decode 16 possible Chip Selects. Also, during I/O cycles to devices such as the Keyboard Controller, RA7 through RA0 become the Data Bus bits ED7 through ED0.

The RAS and CAS lines are designed to drive the DRAM array directly without the use of external drivers. RA10 through RA0 are capable of driving 350 pF, the equivalent load of two banks of one bit wide RAM, plus two banks of four bit wide RAM (48 DRAMs).

The W/R signal at pin 119 should be buffered before use. Write protection is accomplished by not asserting CAS to the local DRAM while MEMW at pin 37 is asserted.

The on-board DRAM may be disabled so that external cards such as EMS may provide memory. The DRAM may be disabled in three stages, from 128 Kbyte to 640 Kbyte, 256 Kbyte to 640 Kbyte and 512 Kbyte to 640 Kbyte.

When disabling any on-board DRAM, the register at Port Address 6872H must not be programmed to enable the on-board Lower EMS Page Frame.

The WD7710 and WD7710LP provide support for DRAM banks to be independent or two-way page interleaved. DRAM banks that are interleaved must be of the same DRAM size.



6.2 MEMORY CONFIGURATION

6.2.1 Memory Control

Port Address 3872H - Read and Write

15	1	4	13	12	11	10	09	08
PG_ CAS			CA		PG		ILV	

07	06	05	04	03	02	01	00
SIZ BNI		SIZI BNł		SIZI		SIZE BNK	

Signal Name	De <u>fault</u> At RSTIN
PG_CAS	. 0
CA	. 00
PG	. 0
ILV	. 00
SIZE_BNK3	. 00
SIZE_BNK2	. 00
SIZE_BNK1	. 00
SIZE BNK0	. 00

Bit 15 - PG CAS, Page Mode CAS Width

PG_CAS = 0 - Read CAS pulse width is 2.5 CPUCLK clocks (Default value).

PG_CAS = 1 - Read CAS pulse width is 2 CPUCLK clocks. This is required for 80386SX Pipeline mode.

Bit 14 - Reserved for future use, should be set to 0.

Bits 13, 12 - CA, Cache Mode

Enabling the Cache Mode adds an additional wait state to the beginning of on-board read cycles. On-board read cycles occur only for cache misses. If the RDYIN signal indicates that the external cache has experienced a zero wait state read hit, the DRAM read cycle is aborted.

Pin 51 of the System Controller serves one of three functions, depending upon the mode selected by CA. Pin 51 may represent the RDYIN (Ready In), CKA (Alternate Clock) or PE (Parity Error).

When CA is changed, a hold acknowledge cycle is required before the change goes into effect.

CA 13 12

- 0 0 Cache Mode not enabled. Pin 51 may be used as the alternate clock CKA. (Default value)
- 0 1 Cache Mode enabled.
- 1 0 External Memory Controller. Pin 51 becomes PE and is connected to the parity error line of the external memory controller.
- 1 1 Pin 51 may be used as the alternate clock CKA. When CAS Input Mode is enabled, PE on pin 111 becomes an input and represents an error. (See pin 12 description in Table 3-2 on selecting CAS Mode.)

Bit 11 - PG, Page Mode

PG = 0 - Non-page mode (Default value)
Word interleaving is employed when bank interleaving is enabled by ILV.
Non-page mode *is not supported* in 1Mbit x 16 chips and 2Mbits x 16 configurations.

PG = 1 - Page mode

Page mode interleaving is performed
when bank interleaving is enabled by ILV.

Bits 10-08 - ILV. Interleave

In Non-page Mode (PG = 0), word interleaving is employed. In Page Mode (PG = 1), Page Mode interleaving is used. Four-way interleave is only supported in Page Mode when four banks are installed using one of the following DRAM configurations: 4 Mbits x 16; 512Kbits x 16; 1Mbit x 16 chips; or 2Mbits x 16. Interleave of 64 Kbits x 16 DRAM is not supported by any of the System Controllers.

DRAM banks must be of the same size and assigned the same starting address when they are interleaved together.

ILV 10 09 08

- 0 0 No interleaving performed
- 0 0 1 Banks 0 and 1 are interleaved Banks 2 and 3 are not interleaved Banks 0 and 1 must be the same size
- 0 1 0 Banks 0 and 1 are not interleaved

Banks 2 and 3 are interleaved 0 1 1 - Banks 0 and 1 are interleaved Banks 2 and 3 are interleaved

(Each pair must be the same size. Banks 0 and 1 may be a different size from Banks 2 and 3.)

1 0. 0 - Page Mode four-way interleave (Banks 0, 1, 2 and 3 must have one of the following DRAM configurations installed: 4 Mbits x 16; 512 Kbits x 16; 2Mbits x 16; or 1 Mbit x 16 chips.)

DRAM Banks 3 through 0

The WD7710 and WD7710LP support all DRAM sizes. The DRAM sizes may be mixed.

Bits 07, 06 - SIZE BNK3, Size of Bank 3

PORT 7472	POR1	3872	BANK 3 SIZE
BIT 15	BIT 7	BIT 6	
0	0	0	64Kbits x 16
0	0	1	256Kbits x 16
0	1	0	1Mbits x 16
0	1	1	4Mbits x 16
1	0	0	512Kbits x 16
1	0	1	1 Mbits x 16 chip
1	1	0	2 Mbits x 16
1	1	1	Reserved

Bits 05, 04 - SIZE_BNK2, Size of Bank 2

PORT 7472	PORT 3872		BANK 2 SIZE
BIT 14	BIT 5	BIT 4	
0	0	0	64Kbits x 16
0	0	1	256Kbits x 16
0	1	0	1Mbits x 16
0	1	1	4Mbits x 16
1	0	0	512Kbits x 16
1	0	1	1 Mbits x 16 chip
1	1	0	2 Mbits x 16
1	1	1	Reserved

Bits 03, 02 - SIZE_BNK1, Size of Bank 1

PORT 7472	PORT 3872		BANK 1 SIZE
BIT 13	BIT 3	BIT 2	
0	0	0	64Kbits x 16
0	0	1	256Kbits x 16
0	1 .	0	1Mbits x 16
0	1	1	4Mbits x 16
1	0	0	512Kbits x 16
1	0	1	1 Mbits x 16 chip
1	1	0	2 Mbits x 16
1	1	1	Reserved

Bits 01, 00 - SIZE_BNK0, Size of Bank 0

PORT 7472	PORT 3872		BANK 0 SIZE
BIT 12	BIT 1	BIT 0	
0	0	0	64Kbits x 16
0	0	1	256Kbits x 16
0	1	0	1Mbits x 16
0	1	1	4Mbits x 16
1	0	0	512Kbits x 16
1	0	1	1 Mbits x 16 chip
1	1	0	2 Mbits x 16
1	1	1	Reserved

6.2.2 Memory Bank 3 Through Bank 0 Starting Address

Port Address 4872H - Read and Write

15	14	13	12	11	10	09	08
A24	A23			A20 address		A18	A17

07	06	05	04	03	02	01	00
A24	A23	A22 Bank		A20 address	A19	A18	A17

Port Address 5072H - Read and Write

15	14	13	12	11	10	09	08
A24	A23			A20 address		A18	A17

07	06	05	04	03	02	01	00
A24	A23			A20 address		A18	A17

The starting address of the bank must be programmed on boundaries corresponding to the bank size. Smaller banks must be placed at a higher starting address than larger banks. The size of the bank is automatically set by the type and size of the RAM. When banks are interleaved, in either page or non-page mode, the interleaved banks should be enabled and programmed to the same starting address.

The bank size is doubled for two-way interleave and quadrupled for four-way interleave. For example, if bank 0 has 256 Kbit DRAMs and banks 2 and 3 have 1 Mbit DRAMs, the starting address for banks 2 and 3 should be zero. Both banks should be enabled. The size of the combined banks is 4 Mbytes, double the size of the individual banks. The starting address for bank 0 should then be at 4 Mbytes. For three banks of the same size, in which two are interleaved, the two interleaved banks must be placed at a lower starting address than the third bank.

RAM SIZE	PAGE SIZE	BANK SIZE
64Kbits x 16	512 Bytes	128 Kbytes
256 Kbits x 16	1024 Bytes	512 Kbytes
1 Mbits x 16	2048 Bytes	2048 Kbytes
4 Mbits x 16	4096 Bytes	8192 Kbytes
512 Kbits x 16	1024 Bytes	1024 Kbytes
1 Mbit x 16 chips	512 Bytes	2048 Kbytes
2 Mbits x 16	1024 Bytes	4096 Kbytes

6.2.3 Split Starting Address

Port Address 5872H - Read and Write

15	14	13	12	11	10	09	08
EN_ BK3	EN_ BK2	EN_ BK1	EN_ BK0	DRA DRV	M_	SPI SIZE	

07	06	05	04	03	02	01	00
A24	A23	A22	A21	A20	A19		

Signal Name								e <u>fault</u> t RSTIN
EN_BK3								0
EN_BK2								0
EN_BK1								0
EN_BKO								0
DRAM_DRV								
SPLIT_SIZE								00
Bits 01, 00 .				_				None

Bit 15 - EN BK3, Enable Bank 3

EN BK3 = 0 -

Bank 3 is disabled (Default value)

EN BK3 = 1 -

Bank 3 is enabled

Bit 14 - EN_BK2, Enable Bank 2

EN BK2 = 0 -

Bank 2 is disabled (Default value)

EN BK2 = 1 -

Bank 2 is enabled

Bit 13 - EN BK1, Enable Bank 1

EN BK1 = 0 -

Bank 1 is disabled (Default value)

EN BK1 = 1 -

Bank 1 is enabled

Bit 12 - EN BKO, Enable Bank 0

EN BK0 = 0

Bank 0 is disabled (Default value)

EN BK0 = 1 -

Bank 0 is enabled

Bits 11, 10 - DRAM DRV, DRAM Driver Strength

The DRAM address driver strength may be adjusted for capacitive load. When adjusted properly, output overshoot and undershoot is minimized while still meeting worst case

DRAM timing. The DRAM RAS, CAS and address buffers also automatically compensate for variations in temperature, voltage and manufacturing process.

DRAM_DRV

11 10

0 0 - Full strength DRAM address drive, up to 350 pF (Default value)

- 1 Low strength DRAM address drive, up to 100 pF
- 1 0 Medium strength DRAM address drive, up to 180 pF
- 1 1 High strength DRAM address drive, up to 260 pF

Bits 09, 08 - SP SIZE, Split Size

The split is implemented by moving the block of memory between 0A0000H through 0FFFFFH to another area. The destination area must start on a 512 Kbyte boundary. If BIOS is to be shadowed, the split size must be 320 Kbyte for a 64 Kbyte shadow or 256 Kbyte for a 128 Kbyte shadow, and the RAM Shadow And Write Protect Register (Port 6072H) must also be programmed.

Figure 6-1 illustrates that the memory from 0A0000H (640 Kbyte) to 100000H (1024 Kbyte) is available for remapping. The remapping may start at 100000H, providing 384 Kbyte of extended memory, or may start at 0F0000H to allow BIOS shadowing, with 320 Kbyte of extended memory. Only a single bank may be split. The bank to be split must be at least 512 Kbyte or larger.

SPLIT SIZE

09 08

0 0 - No split (Default value)

- 0 1 256 Kbyte split, memory moved from 0A0000H to 0DFFFFH
- 1 0 320 Kbyte split, memory moved from 0A0000H to 0EFFFFH
- 1 1 384 Kbyte split, memory moved from 0A0000H to 0FFFFH

Bits 07-02 - A24-A19, Split Starting Address

Bits 01, 00 - Not used, state is ignored

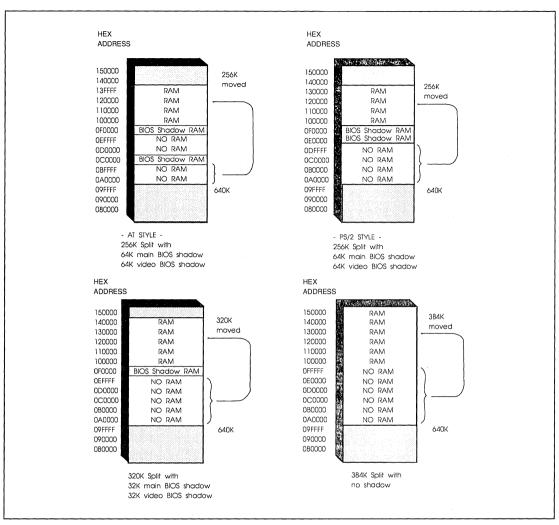


FIGURE 6-1. SPLIT SIZE

6.2.4 RAM Shadow And Write Protect

Port Address 6072H - Read and Write

	15	14	13	12	11	10	09	08
C	DIS_N	1EM	HM_ WP	WP	INV_ PAR	PAR_ DIS	SHE)

07	06	05	04	03	02	01	00
X_ MEM		VB_S	SIZ	RC TY		BL_M	IOU

Signal Name									_	e <u>fault</u> t RSTIN
DIS_MEM	:									00
HM_WP .										0
WP										0
INV_PAR										0
PAR_DIS										0
SHD										00
X_MEM .										0
										None
VB_SIZ .										00
ROM_TYP					•					00
BL_MOU †										00

→ Featured only in the WD7710LP

Bit 15, 14 - DIS MEM, Disable On-board Memory

DIS_MEM 15 14

- 0 0 On-board memory from 128 KB to 640 KB not disabled (Default value).
- 0 1 On-board memory from 512 KB to 640 KB disabled.
- 1 0 On-board memory from 256 KB to 640 KB disabled.
- 1 1 On-board memory from 128 KB to 640 KB disabled.

Bit 13 - HM_WP, High Memory Write Protect Enable

This bit enables the write protection for the memory boundary established by the register at Port C072H.

HM WP = 0 -

High memory write protect not enabled (Default value).

 $HM_WP = 1 -$

High memory write protect enabled.

Bit 12 - WP, Shadowed BIOS Write Protect Enable

WP = 0 -

Write protect for shadowed BIOS not enabled (Default value).

WP = 1 -

Write protect for shadowed BIOS enabled.

Bit 11 - INV PAR, Invert Parity

INV PAR = 0 -

Normal parity when writing to on-board DRAM (Default value).

INV PAR = 1 -

Invert parity when writing to on-board DRAM.

Bit 10 - PAR DIS, Parity Checking Disabled

Parity checking is normally enabled or disabled by Port 061H. Setting PAR_DIS overrides the Port 061H setting and disables parity checking. This ability is provided for systems without parity RAM.

PAR DIS = 0 -

Parity checking as selected by Port 061H (Default value).

PAR DIS = 1 -

Parity checking disabled.

Bits 09, 08 - SHD, Shadow BIOS

Before the BIOS can be shadowed, the SPLIT_SIZE field in the Split Starting Address Register at Port 5872H must be programmed to non-zero.

ROM at FE0000H through FFFFFFH, the top of 16 MByte address space is never shadowed.

Option SHD 11 should be used when Video Remap Function is desired (i.e. Video BIOS in the lower half of EPROM shows up at C0000H).

64 Kbyte of system BIOS at 0F0000H through 0FFFFFH, and up to 64 Kbyte of video BIOS at 0C0000H through 0CFFFFH, may be shadowed. This type of shadowing is accomplished by setting SHD = 10 and then writing the system and video BIOS into 0E0000H through 0FFFFFH. When SHD is set to 11, the video BIOS appears at 0C0000H through 0CFFFFH rather than 0E0000H through 0EFFFFH.



The video shadow size at 0C0000H - 0CFFFFH is determined by VB_SIZ, the video BIOS size field

SHD

09 08

- † 0 0 No BIOS shadowing, allows 384 KB remap (Default value).
 - 0 1 64 KB system BIOS shadow, 0F0000H - 0FFFFFH, allows 320 KB remap.
 - 1 0 128 KB system BIOS shadow, 0E0000H - 0FFFFFH, allows 256 KB remap.
- † 1 1 64 KB system BIOS shadow, 0F0000 - 0FFFFF and video BIOS shadow, allows 256 KB remap.

† See note following bits 01, 00.

Bit 07 - X_MEM, Shadow BIOS for Read/Write Memory

When SHD (bits 09 and 08) equals 11, X_MEM provides the means of using RAM from E8000H through EFFFFH not being used for video BIOS shadowing, to be used as read/write memory.

$$X_MEM = 0$$
 - SHD = 11
ROM TYP = 10 - VB SIZ = 01

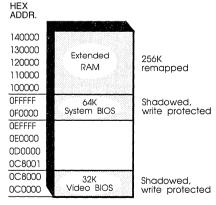
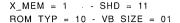


FIGURE 6-2. X MEM = 0



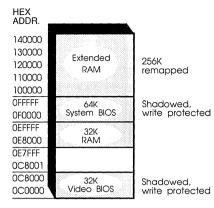


FIGURE 6-3. X MEM = 1

Bit 06 - Not used, state is ignored

Bits 05, 04 - VB SIZ, Video BIOS Size

VB_SIZ †

0 0 - 16 KB video BIOS (Default value)

0 1 - 32 KB video BIOS

1 0 - 48 KB video BIOS

1 1 - 64 KB video BIOS

† See note following bits 01, 00.

Bits 03, 02 - ROM TYP, ROM Type

For ROM type 00, CSPROM is asserted when the address is 0E0000H - 0FFFFFH or FE0000H - FFFFFFH.

For ROM type 10, CSPROM is asserted when the address is 0F0000H - 0FFFFFH, FF0000H - FFFFFFH or 0C0000H - 0CXFFFH where X is determined by VB_SIZ. This allows either a 128 Kbyte BIOS with a 64 Kbyte system BIOS and a 64 Kbyte video BIOS, or a 64 Kbyte BIOS with a 32 Kbyte system BIOS and a 32 Kbyte video BIOS. The 32 Kbyte video BIOS portion must be in the bottom half of the EPROM and is accessed both at C0000H - CX000H and F0000H - FX000H.

64 Kbyte EPROM needs addresses SA15 - SA0. A 128 Kbyte EPROM needs addresses SA16 - SA0. Neither EPROM needs translated addresses.

CSPROM is CS4 through CS0, decoded as the value of 00.

ROM_TYP 03 02

- 0 0 128 KB system BIOS, located at E0000H FFFFFH
- 0 1 64 KB system BIOS, located at F0000H FFFFFH (Default value)
- † 1 0 64 KB or 128 KB shared BIOS System BIOS located at F0000H - FFFFFH, video BIOS located at C0000H - CX000H
 - 1 1 Reserved

† See note following bits 01, 00.

Bits 01, 00 - BL_MOU, Backlight Mouse Control Featured only in the WD7710LP

Enabling the Backlight Mouse Control increases the CPU speed for one second if Auto Clock Switching is on. The AUT_FST bit is located at Port 1072H bit 11. Enabling the Backlight Mouse Control also affects the Back/light and LCD timers in the PMC Timer Register at Port Address 8072H.

BL_MOU 01 00

0 0 - No mouse control (Default value)

0 1 - INT12 mouse

1 0 - INT4 mouse

1 1 - INT3 mouse

† NOTE

When SHD = 11 and X_MEM = 0, or SHD = 00 and ROM_TYP = 10, the portion of 0E0000H DRAM memory that is not mapped to 0C0000H (as determined by VB_SIZ) is not accessible. Once a portion of 0E0000H segment is mapped to 0C0000H, all 0E0000H accesses go to the expansion bus without generation of CSPROM. This allows AT bus plug-in boards and/or drivers to access the E0000H segment.

6.2.5 High Memory Write Protect Boundary

Port Address C072H - Read and Write

15	14	13	12	11	10	09	08

00	01	02	03	04	05	06	07
A17	A18	A19	A20	A21	A22	A23	A24
	A18	A19	A20	A21	A22	A23	A24

Signal Name								e <u>fault</u> At RSTIN
Bits 15-08								None

Bits 15-08 - Not used, state is ignored

Bits 07-00 - A24-A17, Boundary Address

Memory above the high memory write protect boundary is write protected when enabled by the HM_WP, bit 13 of the RAM Shadow And Write Protect Register at Port 6072H. This provides an additional write protect region for disk caching.

6.3 MEMORY TIMING

The DRAM timing is determined by an internal delay line for DMA and Master Mode transfers. The RAS leading edge becomes active from the active level of MEMR and MEMW. The delay line is automatically tuned to fixed delays, using the 14.318 MHz clock CLK14 as reference.

When writing to the DRAM memory timing register at Port 4072H, the memory timing mode changes immediately. The code that programs this register should be in ROM and not shadowed in RAM.

6.3.1 Non-page Mode DRAM Memory Timing

Port Address 4072H - Read and Write

15	14	13	12	11	10	09	08
	NP_M	ODE	NP_ RAW	NP_	WCAS	_NP_I	RCAS

07	06	05	04	03	02	01	00
	NP_I HLD	RAS_	N	P_PWE		NP ₋	_ws

Signal Name							_	e <u>fault</u> t RSTIN
Bits 15, 07								None
NP_MODE .								00
NP_RAW								0
NP_WCAS .								00
NP_RCAS								00
NP_RAS_HLD								00
NP_PWE								000
NP_WS								00

Bit 15 - Not used, state is ignored

Bits 14, 13 - NP_MODE, Non-Page Mode

There are two non-page modes available, Mode-00 and Mode-01. Mode-00 provides one processor clock of row address hold time and is used for 1, 2 or 3 wait state memory cycles. Mode-01 provides a half processor clock of row address hold time and is used for 0 wait state memory cycles. Because the memory timing may be adjusted in increments of half a processor clock, Mode-00 is suited for all DRAM and processor speeds.

Mode-01 provides a half processor clock row address hold time, which is usually sufficient for system speeds of 12.5 MHz and slower. This compressed timing allows zero wait state operation.

Table 6-1A shows typically required DRAM speeds and register programming values for various processor speeds. Because DRAM timing varies among manufacturers, the required DRAM speed may differ from those listed in the table.

NP_MODE 14 13

- 0 0 Minimum 1 wait state.
- 0 1 Minimum 0 wait state.

PROCESSOR SPEED	NP_ MODE	DRAM SPEED	WAIT STATES	REGISTER 4072H
12.5 MHz	01	80 ns	0	3560H
16 MHz	01	53 ns	0	3560H
16 MHz	00	80 ns	1	1025H
20 MHz	00	80 ns	1	1025H
20 MHz	00	100 ns	2	107AH

TABLE 6-1A. TYPICAL DRAM SPEEDS

Bit 12 - NP_RAW, Non-page disable Read After Write

EMS accesses and interleave miss cycles (I/O cycle to device on RAD) may add one additional wait state.

NP RAW = 0 -

Memory read cycles immediately following a write cycle causes an automatic wait state to be added before initiating the read cycle.

NP RAW = 1 -

Read after write cycles do not have additional wait states.

Bit 11, 10 - NP_WCAS, Non-page Write CAS Delay

NP_WCAS 11 10

0 0 - CAS write delay 1.0 CLK2

0 1 - CAS write delay 1.5 CLK2

1 0 - CAS write delay 2.0 CLK2

1 1 - CAS write delay 2.5 CLK2

Bit 09, 08 - NP_RCAS, Non-page Read CAS Delay

NP_RCAS 11 10

0 0 - CAS read delay 1.0 CLK2

0 1 - CAS read delay 1.5 CLK21 0 - CAS read delay 2.0 CLK2

1 1 - CAS read delay 2.5 CLK2

Bit 07 - Not used, state is ignored

Bits 06, 05 - NP_RAS_HLD, Non-page CAS to RAS Hold Time

The RAS active delay is reduced by half a clock during writes if NP_WCAS is set to 1X, or during reads if NP_RCAS is set to 1X.

NP_RAS_HLD 06 05

- 0 0 RAS active until 1.0 clock after CAS.
- 0 1 RAS active until 1.5 clock after CAS.
- 1 0 RAS active until 2.0 clock after CAS.
- 1 RAS active until 2.5 clock after CAS.

Bits 04-02 - NP_PWE, Non-page CAS Pulse Width Extension

The pulse width is reduced by half a clock during writes if NP_WCAS is set to X1, or during reads if NP RCAS is set to 1X.

NP_PWE 04 03 02

0 0 - No extension (2 CLK2 normal)

0 0 1 - Extended by 0.5 CLK2

0 1 0 - Extended by 1.0 CLK2

0 1 1 - Extended by 1.5 CLK2

1 0 0 - Extended by 2.0 CLK2

1 0 1 - Extended by 2.5 CLK2

1 1 0 - Extended by 3.0 CLK2

1 1 1 - Extended by 3.5 CLK2

Bits 01, 00 - NP_WS, Non-page Wait States

NP_WS makes it possible to unconditionally add wait states to all DRAM cycles. Condional wait states may be added to read after write cycles, EMS accesses and interleave miss cycles, with NP_RAW (bit 12).

NP_WS 01 00

0 0 - No wait states added

0 1 - 1 Wait state added

1 0 - 2 Wait states added

1 1 - 3 Wait states added

NPHB = Bit 05

NPWF = Bit 10

NPCAS = Bits 04, 03

TIMING	NUMBER OF CLK2'S						
	MODE-00	MODE-01					
Row address to RAS	2	2					
RAS width	3 + NPH + NPHB / 2	1 + NPH + NPHB / 2					
Row address hold	1	0.5					
Column address setup (read)	1 + NPRF / 2	0.5 + NPRF / 2					
Column address setup (write)	1 + NPWF / 2	1 + NPWF / 2					
RAS hold (read from CAS)	1 + NPHB / 2 - NPRF / 2 + NPH	0.5 - NPRF / 2 + NPH					
RAS hold (write)	1 + NPHB / 2 - NPWF / 2 + NPH	0.5 - NPWF / 2 + NPH					
CAS width (read)	① + NPCAS + NPCB / 2 - NPRF / 2	① + NPCAS + NPCB / 2 - NPRF / 2					
CAS width (write)	① + NPCAS + NPCB / 2 - NPWF / 2	① + NPCAS + NPCB / 2 - NPWF / 2					
RAS precharge	2 × (2 + NP_WS) - RAS width	2 × (2 + NP_WS) - RAS width					
Column address hold	1 - NPCB / 2	1 - NPCB / 2					

TABLE 6-1B. NON-PAGE MODE TIMING

NPH = Bit 06

NP_WS = Bits 01, 00

NPRF = Bit 08

NPCB = Bit 02

6.3.2 Page Mode

Table 6-2. identifies the type of DRAM cycle and number of wait states for the 80286 and 80386SX processors.

	PAGE MODE DRAM CYCLE	WAIT STATES
80286	Write page hit Write page first access † Write page miss Read page hit Read after write page hit Read page first access † Read page miss	0 1 2 0 1 2 3
80286 With Discrete Cache	Write page hit Write page first access † Write page miss Read cache hit Read cache miss, page hit Read cache miss, page first access † Read cache miss, page miss	0 1 2 0 1 3 4
80386SX	Write page hit, pipeline mode Write page hit, non-pipeline mode Write page first access, pipline mode † Write page miss, pipeline mode Write page miss, non-pipeline mode Read page hit, pipeline mode Read page hit, non-pipeline mode Read after write page hit, pipeline mode † Read page first access non-pipeline mode † Read page miss, pipeline mode Read page miss, non-pipeline mode	0 1 1 2 3 0 1 1 3 3 4
80386SX With Discrete Cache, Non-pipe	Write page hit Write page first access † Write page miss Read cache hit Read cache miss, page hit Read cache miss, page first access † Read cache miss, page miss	0 1 2 0 1 3 4

† Equal Bank sizes, non-EMS cycle

First access is a page mode memory cycle which immediately follows a refresh, DMA or master cycle. It is not necessary for the DRAMs to be precharged for a first access cycle, since all RAS signals have been high in the previous cycle. This shortens a first access page mode cycle by one wait state. For example, a read page miss, non-pipeline mode in 80386SX mode is four wait states. A read page miss, non-pipeline mode, first access in 80386SX mode is three wait states. All installed DRAMs must be the same size and configuration and the memory cycle cannot be an EMS cycle for a first access to occur.

TABLE 6-2. PAGE MODE WAIT STATES

6.3.3 Memory Address Multiplexer

The memory address multiplexer generates the DRAM row and column address. The DRAM address multiplexer is designed so that the same type socket may be used for 64 Kbyte, 256 Kbyte, 1 Mbyte or 4 Mbyte SIMM memory modules.

	RA11	RA10	RA9	RA8	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	
					64 KBI	TS NON	I-INTER	LEAVE					
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A12 A4	A11 A3	A10 A2	A9 A1	
	64 KBITS 2-WAY INTERLEAVE OR 256K NON-INTERLEAVE A13 A22 A20 A18 A16 A15 A14 A13 A12 A11 A10 A												
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A12 A4	A11 A3	A10 A2	A17 A1	
	64 KI	BITS 4-V	VAY INT			K 2-WAY				S NON-	NTERL	EAVE	
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A12 A4	A11 A3	A19 A2	A17 A1	
	256 KBITS 4-WAY INTERLEAVE, 1 MBITS 2-WAY INTERLEAVE, 4 MBITS NON-INTERLEAVE OR 512 KBITS X 8 4-WAY INTERLEAVE												
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A12 A4	A21 A3	A19 A2	A17 A1	
			1	MBITS 4	1-WAY C	OR 4 MB	ITS 2-W	/AY INT	ERLEA\	/E			
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A23 A4	A21 A3	A19 A2	A17 A1	
					4 MBIT	S 4-WA	/ INTER	LEAVE					
ROW COL	A13 A13	A22 A11	A20 A10	A18 A9	A16 A8	A15 A7	A14 A6	A24 A5	A23 A4	A21 A3	A19 A2	A17 A1	
				512	K X 8 D	RAM: 1	NON-IN	TERLEA	VE				
ROW COL	A13 A13	A22 A11	A19 A10	A18 A9	A16 A8	A15 A7	A14 A6	A13 A5	A12 A4	A11 A3	A10 A2	A17 A1	
				1 N	1 X 16 D	RAM: N	ON-INT	ERLEA'	٧E				
ROW COL	A13 A13	A9 A11	A19 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A11 A3	A10 A2	A17 A1	
}				1 M	X 16 DF	RAM: 2-	WAY IN	TERLEA	VE			l	
ROW COL	A13 A13	A10 A11	A21 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A11 A3	A19 A2	A17 A1	
				1 M	X 16 DF	RAM: 4-	WAY IN	TERLEA	VE				
ROW COL	A13 A13	A22 A11	A21 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A11 A3	A19 A2	A17 A1	

TABLE 6-3. PAGE MODE DRAM ADDRESS MULTIPLEXER CONFIGURATION

	RA11	RA10	RA9	RA8	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	
	2M X 8 DRAM: NON-INTERLEAVE												
ROW COL	A13 A13	A21 A11	A19 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A11 A3	A10 A2	A17 A1	
		2M X 8 DRAM: 2-WAY INTERLEAVE											
ROW COL	A13 A13	A21 A11	A19 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A11 A3	A22 A2	A17 A1	
				2N	1 X 8 DF	RAM: 4-\	VAY INT	ERLEA	VE				
ROW COL	A13 A13	A21 A11	A19 A10	A18 A9	A16 A8	A15 A7	A14 A6	A20 A5	A12 A4	A23 A3	A22 A2	A17 A1	
					RE	FRESH	ADDRE	SS					
ROW		A10	A 9	A8	A7	A6	A5	A4	А3	A2	A1	A0	

TABLE 6-3. PAGE MODE DRAM ADDRESS MULTIPLEXER (Continued)

	RA11	RA10	RA9	RA8	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	
ROW	A13	A11	A10	A9	A8	A7	A6	A5	A4	A3	A2	A1	ALL
COL	A13	A22	A20	A18	A16	A15	A14	A13	A12	A11	A10	A9	64 Kb
COL	A13	A22	A20	A18	A16	A15	A14	A13	A12	A11	A10	A17	256 Kb
COL	A13	A22	A20	A18	A16	A15	A14	A13	A12	A11	A19	A17	1 Mb or 512 Kb x 8
COL	A13	A22	A20	A18	A16	A15	A14	A13	A12	A21	A19	A17	4 Mb

TABLE 6-4. NON-PAGE, NON-INTERLEAVE ADDRESS CONFIGURATION

	RA11	RA10	RA9	RA8	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	
ROW	A13	A11	A10	A9	A8	A7	A6	A5	A 4	A3	A2	A13	ALL
COL	A13	A22	A20	A18	A16	A15	A14	A17	A12	A11	A10	A9	64 Kb
COL	A13	A22	A20	A18	A16	A15	A14	A19	A12	A11	A10	A17	256 Kb
COL	A13	A22	A20	A18	A16	A15	A14	A21	A12	A11	A19	A17	1 Mb or 512 Kb x 8
COL	A13	A22	A20	A18	A16	A15	A14	A12	A23	A21	A19	A17	4 Mb

TABLE 6-5. NON-PAGE, NON-INTERLEAVE ADDRESS CONFIGURATION

An external latch is required to generate RA $\frac{11}{1}$ for $\frac{1}{1}$ M x 16 and 2M x 16 type DRAMs. It latches A13 from the processor address bus with the inverted READY signal from the WD7710.

7

6.4 EMS

6.4.1 EMS Control And Lower EMS Boundary

Port Address 6872H - Read and Write

15	14	13	12	11	10	09	08
INC	PF_L	.00		EM	S_EN		

07	06	05	04	03	02	01	00
EN_ RES	A23	A22 LO		A20 MS_BOL		A18	A17

Signai Name							etauit t RSTIN
INC							0
PF_LOC							00
Bits 12, 09, 08							None
EMS_EN							00
EN_RES							0
A23-A17							0

Bit 15 - INC, Increment EMS Pointer

The INC bit controls whether or not the EMS Pointer at Port E072H is to be incremented after each read or write of the EMS Page Register at Port E872H.

INC = 0 -

The EMS pointer does not increment (Default value).

INC = 1 -

EMS pointer increments after access to EMS Page Register.

Bits 14-13 - PF_LOC, Upper Page Frame Location

PF_LOC determines the starting location of a block eight frames. See Table 6-6 for the upper page frame assignments.

PF_LOC 14 13

- 0 0 Upper page frame starts at C4000H (Default value)
- 0 1 Upper page frame starts at C8000H
- 1 0 Upper page frame starts at CC000H
- 1 1 Upper page frame starts at D0000H

Bit 12 - Not used, state is ignored

Bits 11, 10 - EMS_EN, EMS Enable

EMS_EN determines whether all EMS frames are to be enabled, only the upper page frames or no page frames. Tables 6-6 and 6-7 show the upper and lower page frame assignments.

EMS_EN 11 10

- 0 0 Disable EMS (Default value)
- 1 Enable EMS Register
 programming without having to
 enable a Page Frame. This is
 useful for initializing the lower
 Page Frame.
- 1 0 Enable upper Page Frame assignments and EMS register programming.
- 1 1 Enable upper and lower Page Frame assignments and EMS register programming.

Bits 09, 08 - Not used, state is ignored

Bits 07 - EN_RES, Enable Lower Boundary

EN_RES determines whether A23 through A17 (bits 06 through 00 of this register) are to be used as the lower EMS boundary or ignored.

When the LOWER_EMS_BOUNDARY is enabled, the memory above the boundary is removed from the extended memory and reserved for EMS.

EN RES = 0 -

Ignore LOWER_EMS_BOUNDARY (Default value)

 $EN_RES = 1 -$

Enable LOWER EMS_BOUNDARY

Bits 06-00 - A23-A17.

LOWER EMS BOUNDARY

The lower_EMS_boundary provides address bits A23 through A17 and determines the starting address.

This address must be set to 128 Kbyte below the actual start address. For example, to start EMS at the 1 Mbyte boundary, this field should be set to 07H.

6.4.2 EMS Page Register Pointer

Port Address E072H -Bits 15-06 Read only, Bits 05-00 Read and Write

15	14	13	12	11	10	09	08
				DLT			
16	15	15	13	12	11	10	9

07	06	05	04	03	02	01	00
DL	.T			POIN	TER		
8	7						
1		-					

Signal Name								e <u>fault</u> t RSTIN
DLT POINTER								

The EMS Page Register Pointer is used as an indirect address register. It is loaded with the EMS Page Register Number, ranging from 00 to 39 decimal. If the INC bit is set in Port 6872H, the EMS Page Register Pointer is incremented after each read or write of the EMS Page Register at Port E872H. Tables 6-6 and 6-7 shows the EMS Page Register Pointer value and the page frame assignments.

Bits 15-06 - DLT, Delay Line Test

In the Delay Line Test Mode, these bits represent the state of internal Delay Line signals.

The Delay Line Test is initiated by bit 8 (TDL) in the Test Enable Register at Port Address A872H.

Blts 05-00 - POINTER, EMS Page Register Number

Decimal number, 00 through 39. When programming this field, the hex equivalent 00 through 27H should be used.

EMS REG NUM	PF_LOC = 00	EMS REG NUM	PF_LOC = 01	EMS REG NUM	PF_LOC = 10	EMS REG NUM	PF_LOC = 11
32	E0000-E3FFF	33	E4000-E7FFF	34	E8000-EBFFF	35	EC000-EFFFF
39	DC000-DFFFF	32	E0000-E3FFF	33	E4000-E7FFF	34	E8000-EBFFF
38	D8000-DBFFF	39	DC000-DFFFF	32	E0000-E3FFF	33	E4000-E7FFF
37	D4000-D7FFF	38	D8000-DBFFF	39	DC000-DFFFF	32	E0000-E3FFF
36	D0000-D3FFF	37	D4000-D7FFF	38	D8000-DBFFF	39	DC000-DFFFF
35	CC000-CFFFF	36	D0000-D3FFF	37	D4000-D7FFF	38	D8000-DBFFF
34	C8000-CBFFF	35	CC000-CFFFF	36	D0000-D3FFF	37	D4000-D7FFF
33	C4000-C7FFF	34	C8000-CBFFF	35	CC000-CFFFF	36	D0000-D3FFF

EMS registers 32 through 39 (decimal) can be individually enabled or disabled by the EN (bit 15) of the EMS Page Register. See Port E872H description.

TABLE 6-6. UPPER PAGE FRAME ASSIGNMENTS

EMS REG NUM	HEX	DEC	EMS REG NUM	HEX	DEC
23	5C000-5FFFF	368K-384K	7	9C000-9FFFF	624K-640K
22	58000-5BFFF	352K-368K	6	98000-9BFFF	608K-624K
21	54000-57FFF	336K-352K	5	94000-97FFF	592K-608K
20	50000-53FFF	320K-336K	4	90000-93FFF	576K-592K
19	4C000-4FFFF	304K-320K	3	8C000-8FFFF	560K-576K
18	48000-4BFFF	288K-304K	2	88000-8BFFF	544K-560K
17	44000- 47FFF	272K-288K	1	84000-87FFF	528K-544K
16	40000-43FFF	256K-272K	0	80000-83FFF	512K-528K
15	3C000-3FFFF	240K-256K	31	7C000-7FFFF	496K-512K
14	38000-3BFFF	224K-240K	30	78000-7BFFF	480K-496K
13	34000-37FFF	208K-224K	29	74000-77FFF	464K-480K
12	30000-33FFF	192K-208K	28	70000-73FFF	448K-464K
11	2C000-2FFFF	176K-192K	27	6C000-6FFFF	4320-448K
10	28000-2BFFF	160K-176K	26	68000-6BFFF	416K-432K
9	24000-27FFF	144K-160K	25	64000-67FFF	400K-416K
8	20000-23FFF	128K-144K	24	60000-63FFF	384K-400K

EMS registers 0 through 31 (decimal) are enabled or disabled as a block. If the EMS_EN field of Port 6872H is 11, the EMS registers 0 through 31 are enabled and the EN (bit 15) of the EMS Page Register is treated as a one. See Port E872H description.

TABLE 6-7. LOWER PAGE FRAME ASSIGNMENTS

6.4.3 EMS Page Register

Port Address E872H - Bits 14-12 Read only, Bits 15, 11-00 Read and Write

There are 40 EMS Page Registers accessible through Port E872H. Only EMS registers 32 through 39 are initialized to zero. EMS registers 0 through 31 are not initialized. The EMS Page Register Pointer at Port E072H provides the offset location for Port E872H.

15	14	13	12	11	10	09	08
EN	0	0	0	P11	P10	P9	P8

07	06	05	04	03	02	01	00
P7	P6	P5	P4	P3	P2	P1	P0

Signal Name	De <u>fault</u> At RSTIN
EN	 . 0
Bits 14-12	 . 0
P11-P0	 . 0

Bit 15 - EN, Enable EMS Page Register

EMS Page Registers 32 through 39 can be individually enabled or disabled by the EN bit. EMS Page Registers 0 through 31 are enabled or disabled as a block by the setting of the EMS_EN field in the EMS Control Register at Port 6872H. When EMS_EN equals 11, the EN bit in this register is treated as a one for the lower Page Frame.

EN = 0 -

This EMS Page Register is disabled

EN = 1 -

This EMS Page Register is enabled

Bits 14-12 - Read only, not used by the System Controller

Bits 11-00 - P11 through P00, EMS Page Number

EMS page numbers 8 through 39 and 64 through 2047 are supported for on-board memory, equal to 31.5 MBytes of EMS memory. The memory address is generated by reading the EMS page number from the System Controller and multiplying it by 16 Kbytes, then adding the lower 14 bits of the processor address to the product. This results in EMS page numbers zero through seven being mapped to the lower 128 Kbytes of memory and On-board extended memory being able to be accessed in real mode via the EMS logic.

EMS page numbers 2048 through 2303, equal to 4 MBytes, are used for external EMS memory, providing a method of accessing plug-in RAM or ROM cards. If P11 is 1 when an external EMS access occurs, EMS page number bits P7 through P0 are output on RA0-7/ED0-7 and the EMS chip select is asserted. The RAM/ROM card should access data on the expansion data bus, using MEMR, MEMW, MEMCS16 and IOCHRDY to make the transfer.

NOTE

When using external EMS memory with P11 = 1, EN (bit 15) must be 0.

7.0 CACHE CONTROLLER

The Cache Controller provides an effective way to increase the memory bandwidth by storing the most frequently used data in the internal Cache DATA RAM. The WD7710 provides both software and hardware mechanisms to assure coherency of the data between CPU, DMA and Bus Master cycles. During DMA/Master write cycles, the controller will compare the system address and the tag contents. If the address matches, the data will be written into the data RAM. The cache can also be flushed by writing to the flush register.

7.1 CACHE ARCHITECTURE

The cache controller contains of eight functional blocks.

- Processor Interface
- TAG RAM
- DATA RAM
- SNOOP Interface
- Non-cacheable Control
- Diagnostic Control Logic
- LRU
- Flush

Figure 7-1 shows a block diagram of the cache.

7.1.1 Processor Interface

The processor interface supports the 80386SX in both pipeline and non-pipeline mode. It keeps track of the 80386SX processor states a generates READY for read hit cycles. It ignores all the I/O and co-processor cycles.

7.1.2 TAG RAM

BIST (Built-In-Self-Test)logic is included in the TAG RAM to reduce test time.

The internal TAG RAM is organized as two sets of 256 x 21 self-timed synchronous static RAM. Twelve bits are used to store A12:23 from the processor; 8 bits are used to store the demultiplexed A1:3 as line valid, and 1 bit is used as block valid. The block valid bit can be cleared by

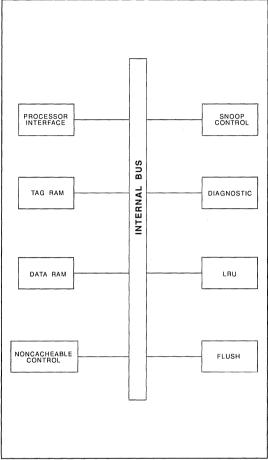


FIGURE 7-1. CACHE CONTROLLER FUNCTIONAL DIAGRAM

the FLUSH function which flushes the cache contents and causes block miss for all the subsequent cycles.

A4 through A11 from the 80386SX selects one of the entries from each set. The output from the TAG RAM is compared against the address (A12:23,A1:A3) from the processor. If the address is the same and the corresponding line valid and block valid bits are set, a cache hit cycle is activated. If an address match occurs when the block valid bit is set, and the line valid is clear, it is a line miss. On the other hand, if the address does not compare or the block valid bit is clear, it is a block miss cycle.

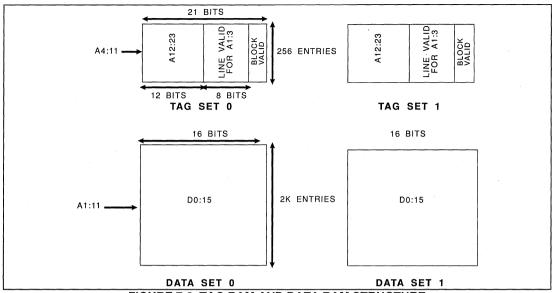


FIGURE 7-2. TAG RAM AND DATA RAM STRUCTURE

During the read block miss cycle, the address is written into the TAG RAM, the block valid bit is set, and the corresponding line valid bit is set.

During the read line miss cycle, the corresponding line valid bit is set, and all other bits are not altered.

Address Compare	Line Valid	Block Valid	
Χ	Х	0	Block Miss
0	Χ	1	Block Miss
1	0	1	Line Miss
1	1	1	Hit

During a memory write cycle, the contents of the TAG RAM is not affected. The Block size of the TAG RAM is eight lines and each line is 2 bytes. The TAG RAM enters low power mode during Full Power Down to conserve power.

7.1.3 Data RAM

The internal DATA RAM is organized as 2 sets of $2K \times 16$. During a read hit cycle, the data is provided by one of the sets of DATA RAM to the processor. During a read miss cycle, the data is

provided by the DRAM to the processor and is written into the DATA RAM. If the read cycle is a page hit, it will be a one wait state cycle. If it is a page miss, it will be a four wait states cycle. See Section 12.4, Cache Controller Timing.

During a write hit cycle, the data from the processor is written into the DATA RAM to maintain data coherency. In a write miss cycle, either block miss or line miss, no action is taken and DATA RAM contents are not affected. See Section 12.4, Cache Controller Timing.

The DATA RAM enters low power mode during Full Power Down to conserve power. BIST logic is included in the DATA RAM to reduce test time.

7.1.4 Snoop Interface

The Snoop interface maintains the data coherency when DMA or Master cycles take place. When a DMA or Bus Master write cycle occurs, the Snoop logic will update the data in the DATA RAM if the address from DMA or the Bus Master is the same as the corresponding TAG address(Hit cycle). If no match is indicated (Miss cycle), the DATA RAM will not be updated. See Section 12.4, Cache Controller Timing.

7.1.5 Non-cacheable Control

Two user definable and twelve standard non-cacheable regions are provided. Ten of the twelve standard regions are 16KB increments from C8000H - EFFFFH. These regions can be used as EMS memory or for DOS 5.0 Upper Memory Blocks and can be enabled or disabled individually. The other two standard non-cacheable regions are the video BIOS area (C0000-CXFFF or E0000-EFFFF) and the system BIOS area (F0000-FFFFF). The Non-cacheable control logic allows cacheing of these regions to be enabled or disabled individually.

The two user definable non-cacheable regions can also be enabled individually. The non-cacheable regions are set by the upper and lower limit registers. These regions are assigned on 4Kbyte boundaries anywhere in the 16MB physical address space of the 80386SX.

The typical applications of these user defined noncacheable areas are the memory between 512KB and 640KB, and the memory accessed on the AT bus. When powered up, the WD7910 assumes all the memory from 0KB to 640KB and 1M to 16MB are cacheable. It is necessary to have the BIOS to program the noncacheable region registers.

7.1.6 Diagnostic Control Logic

The function of the diagnostic control logic, when enabled, is to map the internal TAG RAM and LRU RAM to address 20000H and DATA RAM to address 40000H. In this mode, memory accesses to these address ranges are diverted to the internal TAG RAM and DATA RAM. This permits the system BIOS to test the internal DATA RAM and TAG RAM.

During Diagnostic Access, the 21-bit TAG RAM (D20:0) and the 2-bit LRU RAM (L1:0) are concatenated to 23 bits and mapped into the Address Space by using A1 to determine whether the data presented is TAG RAM bits D20-D9 (A1 Low) or TAG RAM bits {L1:0,D8:0} (A1 high). Since the LRU RAM has 128 entries (See Section 3.1.7) whereas the TAG RAM has 256 entries, so address A4 has no effect on the selection of the LRU RAM.

7.1.7 LRU

The LRU section has 128 entries and each entry has 2 bits. Addresses 11:5 are used to select one of the entries and Address 4 is used to select one of the two bits. In the event of a read miss, either group can be updated with new data. The LRU bit of the corresponding entry flags the candidate for replacement. Once the replacement is done, LRU bit of the corresponding entry is changed and pointed to the other set. In the event of read hit, the LRU bit of the corresponding entry points to the other set. During a write hit cycle, the corresponding LRU bit is changed and pointed to the other set. The LRU bit is not changed for write miss cycles. All the entries are reset to zero by NRESIN.

7.1.8 Flush

Flush is used to clear all the block valid bits in the TAG RAM and to clear all the LRU bits. This force the cache controller to rebuild the cache contents and force all the subsequent fetch to the DRAM. This is used after an EMS page change.

7.2 CACHE CONTROL REGISTER

Port Address C472 Read / Write

15	14	13	12	11	10	09	08
C_ ENBL	C_ SSB	C_ DIAG	C_ SVB	MFR	C_M	HI_ME M9	HI_ME M8

07	06	05	04	03	02	01	00
HI_ME	HI_ME	HI_ME	HI_ME	HI_ME	HI_ME	HI_ME	HI_ME
M7	M6	M5	M4	M3	M2	M1	M0

Bit 15 - C ENBL, Cache Enable

This bit is used to enable the cache controller. Before writing to this bit, the memory controller must be programmed to support the cache mode. This can be done by writing (01) to bit 13 and 12 of register 3872. When this bit is changed, a hold acknowledge cycle is required before the change goes into effect.

C ENBL= 1 Cache Enable

C ENBL= 0 Cache Disable (Default)



Bit 14 - C SSB. Cache Shadowed System BIOS at F0000H through FFFFFH

When the System BIOS is shadowed, it can also be cached to increase the system BIOS performance. When this bit is changed, a hold acknowledge cycle is required before the change goes into effect.

C SSB = 1 Enable caching of shadow RAM. When Custom mode is enabled, the address from 0F0000H - 0F0FFFH is not cached.

C SSB = 0 Disable caching of shadow RAM (Default)

Bit 13 - C DIAG, Cache Diagnostic Mode

Enabling the cache and this bit puts the cache into diagnostic mode as described in section 7.1.6. When this bit is changed, a hold acknowledge cycle is required before the change goes into effect.

C DIAG = 1 Cache is in diagnostic mode

C DIAG = 0 Standard cache mode (Default)

Bit 12 - C SVB, Cache Shadowed Video BIOS at E0000H through EFFFFH or C0000H through CXXXXH

When the Video BIOS is shadowed, it can also be cached to increase the Video BIOS performance. When this bit is changed, a hold acknowledge cycle is required before the change goes into effect.

C_SVB = 1 Enable Cacheing Video BIOS

C SVB = 0 Disable Cacheing Video BIOS (Default)

Bit 11 - C MFR, Manufacturing Test Bit

Bit 10 - C, Cache Mode

BIT 9

C = 1 2-way set associative

C = 0 Direct-mapped (Default)

Bits 9:0 - HI-MEM, High memory region caching control. Setting these bits enables the caching of the HI-MEM region. Default after reset is 0.

EC000H - EFFFFH BIT 8 E8000H - EBFFFH BIT 7 E4000H - E7FFFH BIT 6 E0000H - E3FFFH BIT 5 DC000H - DFFFFH BIT 4 D8000H - DBFFFH

BIT 3 D4000H - D7FFFH

BIT 2 D0000H - D3FFFH BIT 1 CC000H - CFFFFH

BIT 0 C8000H - CBFFFH

Bits 9:0 = 1. Enable caching Bits 9:0 = 0. Disable caching

Noncacheable Region 1 Upper 7.2.1 **Boundary**

Port Address BC72. Read/Write

15	14	13	12	11	10	09	08
A23	A22	A21	A20	A19	A18	A17	A16
07	06	05	04	03	02	01	00
A15	A14	A13	A12	S_ REF	INT_ DIS	INT_ ST	S_ IO RDY

This register determines the upper address boundary of the user defineable noncacheable region 1. Default after reset is zero.

Bits 15:4. = A23: 12 of the upper address boundary

Bit 3, Slow Refresh

When this bit is set, the DRAM refresh rate is slowed down to 120us. This bit does not affect the refresh toggle bit in Port 61.

Bit 3 = 1, Enable Slow Refresh

Bit 3 = 0, Disable Slow Refresh (Default)

Bit 2, Interrupt Disable

When this bit is set, the interrupt from the interrupt controller is disabled. The command will not take effect immediately if the interrupt request signal from the interrupt controller is active. The command will take effect immediately if the interrupt request signal is inactive. This allows control of the interrupt regardless of the Operating system privilege level.

Bit 2 = 1, Disable the hardware interrupt from the interrupt Controller

Bit 2 = 0, Enable hardware interrupt.

Bit 1, Interrupt Disable Status (Read Only)

This enables reading of Interrupt Status regardless of Operating System privilege level.

Bit 1 = 1, Indicates the Interrupt Disable command is pending

Bit 1= 0, Indicates the Interrupt Disable command is processed

Bit 0, SNOOP with IOCHRDY active

During periods when the CPU Clock is slower than the AT BUS clock (slowed for power savings), the Snoop Logic may be unable to properly track the memory cycle during DMA or BUS Master Cycles. Setting this bit enables the WD7710 to use the IOCHRDY signal to lengthen the cycle.

Bit 0 = 1, Enable IOCHRDY for DMA/Master cycle

Bit 0 = 0, Disable IOCHRDY for DMA/Master cycle (Default)

7.2.2 Noncacheable Region 1 Lower Boundary

Port Address B472. Read/Write

15	14	13	12	11	10	09	08
A23	A22	A21	A20	A19	A18	A17	A16

07	06	05	04	03	02	01	00
A15	A14	A13	A12	S DMA_ CLK	X_ WS	S_ BIST	BIST _S

This register determines the lower address boundary of the user defineable noncacheable region 1. Noncacheable region 1 is disabled when the upper boundary is set below the lower boundary. Default after reset is zero.

Bits 15:4, A23: 12 of the lower address boundary.

Bit 3, Stop DMA Clock

Setting this bit causes the DMA clock to stop while there is no DMA activity. Upon any DMA request (DRQn), the DMA clock starts up again and continues to run until 16 DMA clocks after the end of the DMA Acknowledge (DACKn).

Bit 3 = 1, Enable Stop DMA Clock

Bit 3 = 0, Disable Stop DMA Clock (Default)

Bit 2, Extra Wait State for Page Mode

If this bit is active, it adds an extra wait state to all the memory cycles. With this featury system manufacturer can use slower DRAM for WD7710 system without loss of huge performance and achieve saving since the majority of the memory access are directly to the internal cache.

Bits 1, Start BIST

Setting bit 1 forces the BIST to check the TAG RAM and DATA RAM. The result can be checked by reading BIT 0. Bit 0 is a read only register.

Bit 0, BIST Status

Bit 0 = 1, RAM error.

Bit 0 = 0. No error found.

7.2.3 Noncacheable Region 2 Lower Boundary

Port Address CC72 Read/Write

15	14	13	12	11	10	09	08
A23	A22	A21	A20	A19	A18	A17	A16

07	06	05	04	03	02	01	00
A15	A14	A13	A12				NR 2C

This is used to determine the lower address boundary of the user defineable noncacheable region 2. Any address above or equal to this address is considered non-cacheable. Default after reset is zero.

Bits 15:4, A23: 12 of the lower address boundary

Bits 3:1, Test Register

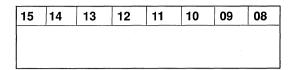
For Factory use only.

Bit 0, Non-cacheable Region 2

Bit 0 = 1, enables non-cacheable Region 2 Bit 0 = 0, disables non-cacheable Region 2 (default)

7.2.4 Flush

Port Address F872H Write Only



07	06	05	04	03	02	01	00
					,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		

Signal Name								e <u>fault</u> t RSTIN
All signals								None

Writing to this I/O port with any data will clear all the valid bits in the TAG RAM. This is ordinarily used to clear the cache when there is a change to the EMS page register and also causes the WD7710 to output Chip Select number 13H.

8.0 PORT CHIP SELECT AND WD7710LP REFRESH

This section describes refresh control logic peculiar to the WD7710LP and used by the power down feature. This section also describes the registers used to control the following functions:

- · Port chip select and control
- · High speed hard disk access
- AT hard disk IDE mode
- 8/16 bit 80287 bus timing
- · Real-Time Clock bus location
- · Access to the CMOS RAM password

Table 8-1 identifies the ports, their Chip Select number, I/O address and function.

8.1 REFRESH CONTROL, SERIAL AND PARALLEL CHIP SELECTS

Port Address 2072H - Read and Write

15	14	13	12	11	10	09	08
M_ REF	V_ REF	CBR_ REF	CBR_ SR	SCSI	PA	λR	PAR_ L

07	06	05	04	03	02	01	00
	SER_A		SER_ AL		SER_	В	SER_ BL

Signal Name									e <u>fault</u> t RSTIN
M_REF †									0
V_REF †									0
CBR_REI	F†								0
CBR_SR									0
SCSI									0
PAR									00
PAR_L .									0
SER_A									000
SER_AL									0
SER_B									000
SER BL									0

† Featured only in the WD7710LP

Bit 15 - M_REF, Memory Refresh Power Down Mode

Featured only in the WD7710LP

The refresh period may be lengthened for extended refresh DRAM while maintaining bus compatibility. When slow refresh is selected, main on-board memory is refreshed at one eighth the normal rate. In the Full Power Down mode, selected by the FPD bit in the register at Port 1872H, and M_REF = 1, the on-board DRAM is refreshed with every eighth NPDREF. NPDREF is a 64 KHz input signal supplied by the WD76C20.

MREF = 0

Normal refresh period for main onboard memory (Default value).

M REF = 1 -

Slow refresh main on-board memory.

Bit 14 - V_REF, Video Refresh Power Down Mode Featured only in the WD7710LP

The refresh period may be lengthened for extended refresh DRAM while maintaining bus compatibility. When slow refresh is selected, main on-board memory is refreshed at one eighth the normal rate. In the Full Power Down mode, selected by the FPD bit in the register at Port 1872H, and V_REF = 1, the on-board DRAM is refreshed with every eighth NPDREF. NPDREF is a 64 KHz input signal supplied by the WD76C20.

V REF = 0 -

Normal refresh period for video memory (Default value)

V REF = 1 -

Slow refresh video memory

Bit 13 - CBR_REF, CAS Before RAS Refresh For On-board DRAM

Featured only in the WD7710LP

Most standard DRAMs support this type of CAS before RAS refresh, while special DRAMs do not.

CBR REF = 0 -

Normal refresh for on-board DRAM (Default value)

CBR REF = 1 -

CAS before RAS refresh

Bit 12 - CBR SR, CAS Before RAS Self Refresh

CAS before RAS self refresh is supported only by special DRAMs.

CBR SR = 0 -

No CAS before RAS self refresh (Default value)

CBR SR = 1 -

CAS before RAS self refresh of DRAM is supported during suspend and resume, where CAS is held low continuously while in suspend.

Bit 11 - SCSI, Small Computer System Interface Chip Select

The SCSI is selected by chip select number 12. See Table 8-1.

SCSI = 0 -

SCSI chip select disabled (Default value)

SCSI = 1 -

SCSI chip select at I/O port 353XH

Bits 10, 09 - PAR, Parallel Port Chip Select

The parallel port is selected by chip select number 0FH and may be located at I/O address 278H through 27FH, 378H through 37FH, or 3BCH through 3BFH. Bits 10 and 09 may disable the chip select or locate it at one of three areas. See Table 8-1.

PAR

10 09

- 0 0 PAR chip select disabled (Default value)
- 0 1 PAR chip select at I/O port 3BCH 3BFH
- 1 0 PAR chip select at I/O port 378H 37FH
- 1 1 PAR chip select at I/O port 278H - 27FH

Bit 08 - PAR L, Parallel Port Bus Location

PAR L = 0 -

Parallel port is located on the RA0-7/ED0-7 bus. This is typical when the WD76C30 is used.

$PAR_L = 1 -$

Parallel port is located on the expansion data bus.

Bits 07, 06, 05 - SER A, Serial Port A Chip Select

The serial port A is selected by chip select number 0EH and may be located at I/O address 2E8H through 2EFH, 2F8H through 2FFH, 3E8H through 3EFH or 3F8H through 3FFH. Bits 07, 06, and 05 may disable the chip select or locate it at one of the four areas. See Table 8-1.

It is possible to select the same I/O port address for serial port A and serial port B. Selecting the same address for both ports results in an unpredictable response and should not be done.

SER A

07 06 05

- 0 0 Serial port A chip select disabled (Default value)
- 0 0 1 Serial port A chip select at I/O port 3F8H 3FFH
- 0 1 0 Serial port A chip select at I/O port 2F8H 2FFH
- 0 1 1 Serial port A chip select at I/O port 3E8H 3EFH
- 1 0 0 Serial port A chip select at I/O port 2E8H 2EFH

Bit 04 - SER AL, Serial A Port Bus Location

SER AL = 0 -

Serial port A is located on the RA0-7/ED0-7 bus. This is typical when the WD76C30 is used.

SER AL = 1 -

Serial port A is located on the expansion data bus.

Bits 03, 02, 01 - SER B Serial Port B Chip Select

The serial port B is selected by chip select number 10 and may be located at I/O address 2E8H through 2EFH, 2F8H through 2FFH, 3E8H through 3FFH or 3F8H through 3FFH. Bits 03, 02 and 01 may disable the chip select or locate it at one of the four areas. See Table 8-1.

It is possible to select the same I/O port address for serial port B and serial port A. Selecting the same address for both ports results in an unpredictable response and should not be done.

SER_B 03 02 01

0 0 - Serial port B chip select disabled (Default value)

0 0 1 - Serial port B chip select at I/O port 3F8H - 3FFH

0 1 0 - Serial port B chip select at I/O port 2F8H - 2FFH

0 1 1 - Serial port B chip select at I/O port 3E8H - 3EFH

1 0 0 - Serial port B chip select at I/O port 2E8H - 2EFH

Bit 00 - SER_BL, Serial B Port Bus Location

SER BL = 0 -

Serial port B is located on the RA0-7/ED0-7 bus. This is typical when the WD76C30 is used.

SER BL = 1 -

Serial port B is located on the expansion data bus

8.2 RTC, PVGA, 80287 TIMING, AND DISK CHIP SELECTS

Port Address 2872H - Read and Write

Bits 12 through 07 and Port Address 3072H control the use and location of the Programmable Chip Select.

15	14	13	12	11	10	09	08
RTC_ L	FST_ VGA	FST_ SCSI	EN_ PCS1	U_ MSK1		L_MSI	< 1

07	06	05	04	03	02	01	00
PRG_ L	HS_ HD		P/S	HS_ 287	LK_ PSW	DS_ HD	DS FLP

Signal Name	De <u>fault</u> At RSTIN
RTC_L .	 0
FST_SCSI	 0
-	
	 00
PRG L	 0
EN_PCS . U_MSK1 .	 0 00 00

HS HD									000
P/S									000
HS 287									0
LK PSW									0
DS HD									0
DS FLP									Ω

Bit 15 - RTC L, Real-Time Clock

The Real-Time Clock is normally on the RA0-7/ED0-7 bus but may be placed on the expansion data bus.

RTC L=0-

Real-Time Clock is on the RA0-7/ED0-7 bus (Default value).

RTC L=1-

Real-Time Clock is on the expansion data bus. This is the required setting when the WD76C20 is used.

Bit 14 - FST VGA, Fast VGA Video

The performance of Western Digital Imaging PVGA display controllers may be enhanced by reducing wait states for access to video I/O. This feature should only be used with Western Digital Imaging PVGA1A, WD90C90, WD90C30, WD90C20, WD90C11 and WD90C10 devices. I/O cycles to eightbit ports 3C0H - 1H, 3C4H - 5H and 3CEH - FH are made with one wait state cycles.

FST VGA = 0 -

Normal PVGA control (Default value)

FST VGA = 1 -

One wait state I/O cycle to PVGA

Bit 13 - FST SCSI, Fast SCSI

The performance of the WD33C93 SCSI Contoller is enhanced by performing eight-bit accesses with one wait state rather than four wait states.

FST SCSI = 0 -

Four Wait States (Default value)

FST_SCSI = 1 -

One Wait State

Bit 12 - EN_PCS1, Enable Programmable Chip Select 1

The Programmable Chip Select logic is selected with chip select 11 and may be disabled or enabled. See Table 8-1.

EN PCS = 0 -

Disable Programmable Chip Select (Default value)

EN PCS = 1 -

Enable Programmable Chip Select

Bit 11 - U_MSK1, Upper Address Bits Masked

U_MSKI determines whether or not the upper address bits A15 through A10 are to be used as designated in the Programmable Chip Select Address Register at Port 3072H.

U MSKI = 0 -

A15 through A10 are ignored (Default value).

U MSKI = 1 -

A15 through A10 are included in the address.

Bits 10, 09, 08 - L_MSK1, Lower Address Bits Masked

L_MSK1 determines whether the lower four address bits A03 through A00 are to be used as designated in the Programmable Chip Select Address Register at Port 3072H.

L_MSK1

10 09 08

0 0 - A09 through A00 are included in the address (Default value).

0 0 1 - A00 is ignored.

0 1 0 - A00, A01 are ignored.

0 1 1 - A00, A01, A02 are ignored.

1 0 0 - A00, A02, A03 are ignored, A01 is not ignored, ver. A-F. A00, A01, A02 A03 are ignored, WD76C10A and newer.

Bit 07 - PRG_L, Programmable Chip Select Bus Location

PRG L=0-

Programmable Chip Select is on the RA0-7/ED0-7 bus (Default value).

PRG L = 1 -

Programmable Chip Select is on the expansion bus.

Bit 06 - HS_HD, High Speed Hard Disk Data Transfer Rate

Enabling the high speed data transfers results in hard disk, 16-bit data transfers to be performed at a compressed timing rate rather than at the compatible bus rate. When operating in the high speed mode, the first data transfer is made at the compatible bus rate. Subsequent accesses to the hard disk port are made at high speed, with IOCS16 ignored and the WD76C20 hard disk chip select remaining stable.

NOTE

This feature requires the use of the WD76C20 and should only be used with Western Digital IDE drives WD-AC280, WD-AC140, WD-AC160, WD-AC2120, WD-AP4200, WD-AB130 and WD-AH260.

HS HD = 0 -

Compatible bus timing enabled (Default value).

 $HS_HD = 1 -$

High speed hard disk accesses enabled.

Bit 05 - Not used, the state is ignored

Bit 04 - P/S, Primary Or Secondary Disk

The P/S bit is only used to select the floppy disk chip select address in the IDE mode. See Table 8-1, chip select numbers 08H through 0BH.

P/S = 0 -

Primary hard disk and Floppy address selected (Default value).

P/S = 1 -

Secondary hard disk and Floppy address selected.

Bit 03 - HS_287, Co-processor 80287 High Speed Timing

Normal I/O read and write access to the 80287 is made with eight bit bus timing. Setting HS_287 results in 16-bit bus timing.

HS 287 = 0 -

Normal 80287 timing (Default value).

HS 287 = 1 -

Fast 80287 timing.

Bit 02 - LK_PSW, Prevent Locking Password

Port 092H bit 3 (Lock_Pass) is used to prevent access to the CMOS RAM password area located at 38H through 3FH. Setting LK_PSW before attempting to set Lock_Pass, inhibits the setting of Lock_Pass. In this instance, it is possible to access the CMOS RAM password area. If Lock_Pass is set before LK_PSW, LK_PSW will have no effect.

LK PSW = 0 -

Port 092H bit 3, Lock_Pass can be set (Default value).

LK PSW = 1 -

Port 092H bit 3, Lock_Pass can not be set.

Bit 01 - DS_HD, Hard Disk Chip Select 0CH, 0DH

DS HD = 0.

Hard disk chip select is enabled (Default value).

 $DS_HD = 1 -$

Hard disk chip select is not generated.

Bit 00 - DS_FLP, Floppy Disk Chip Select 08H, 09H, 0AH, 0BH

DS FLP = 0 -

Floppy disk chip select is enabled (Default value).

DS FLP = 1 -

Floppy disk chip select is not generated.

8.3 PROGRAMMABLE CHIP SELECT ADDRESS

Port Address 3072H - Read and Write

15	14	13	12	11	10	09	08
A15	A14	A13	A12	A11	A10	A09	A08
j.				l			

07	06	05	04	03	02	01	00
A07	A06	A05	A04	A03	A02	A01	A00
		}	ł				
1	}	Į		ļ	ļ		1

Signal	De <u>fault</u>
Name	At RSTIN
All signals	None

7

8.4 I/O PORT ADDRESSES

Table 8-1 lists the I/O addresses and chip selects generated for each fixed port type. Address bits A15 through A10 are ignored for the I/O addresses listed with three digits. The ports are listed in the sequence of the chip select value.

PORT	I/O ADDRESS (HEX)	CHIP SELECT NUMBER (HEX)	FUNCTION
ROM Chip Select	N/A	00	Chip select for BIOS ROM
Keyboard Control	060 - 06E even	01	Chip select for 8042
80287	00E0 - 00FF	02	Chip select for numeric processor
Power Control	7072	03	PMC Write Strobe 0
Reserved		04	Reserved
Real-time Clock	070	05	RTC ALE
Real-time Clock	071	06	RTC Write Strobe
Real-time Clock	071	07	RTC Read Strobe
Floppy Operation Chip Select	3F2 372	08	Primary address Secondary address
Floppy Chip Select	3F4, 3F5 374, 375	09	Primary address Secondary address
Floppy Control Chip Select	3F7 377	0A	Primary address Secondary address (Floppy enabled, HD disabled)
Floppy and HD Control Chip Select	3F7 377	0B	Primary address Secondary address (Floppy enabled, HD enabled)
Hard Disk Chip Select	1F0, 1F1 - 1F7 170, 171 - 177	0C	Primary address Secondary address
Hard Disk Chip Select	3F6 3F7 † 376 377 †	OD	Primary Address Secondary address
Serial Port A Chip Select	2E8 - 2EF 2F8 - 2FF 3E8 - 3EF 3F8 - 3FF	0E ††	
Parallel Port 0 Chip Select	278 - 27F 378 - 37F 3BC - 3BF	0F	

TABLE 8-1. I/O PORT ADDRESSES AND CHIP SELECT ASSIGNMENTS

PORT	I/O ADDRESS (HEX)	CHIP SELECT NUMBER (HEX)	FUNCTION
Serial Port B Chip Select	2E8 - 2EF 2F8 - 2FF 3E8 - 3EF 3F8 - 3FF	10 ††	
Program Chip Select 1	PROG 1	11	
SCSI	3530 - 353X	12	
Cache Flush	F872	13	
EMS	F072 F472	14 15 16	External EMS 48 MHz Clock Disabled 48 MHz Clock Enabled
Power Control	7872	17	PMC Write Strobe 1
Floppy Chip Select	3F0 - 3F1 370 - 371	18	Primary address Secondary address
Floppy Chip Select	3F3 373	19	Primary address Secondary address
Program Chip Select2	PROG 2	1A	
Program Chip Select 3	PROG 3	1B	
Reserved		1E	Reserved
Reserved		1F	Reserved

[†] IDE Hard disk enabled, floppy disabled

TABLE 8-1. I/O PORT ADDRESSES (Continued)

^{††} The Chip Select Number is the decoded value of CS4 - CS0. If the Programmed Chip Select corresponds to any other decode, the Programmed Chip Select is suppressed. If Serial Port A and B are programmed for the same address, Serial Port B Chip Select is suppressed.

9.0 POWER MANAGEMENT CONTROL

The WD7710LP supports all PMC inputs, output and interrupt functions.

9.1 SYSTEM ACTIVITY MONITOR (SAM)

The System Activity Monitor (SAM) found in the WD7710LP is a hardware solution to monitoring system activity. SAM was conceived to solve the problems associated with system activity detection in various operating environments such as DOS, Windows, OS/2 and VCPI.

With the WD7710LP a software approach was employed to determine system activity. This software approach was accomplished using a watchdog timer. As a part of the watchdog timer service, the sources of activity are checked and a determination is then made on the state of system activity. This approach does not consider the state of the system activity between watchdog timer interrupts. However, with SAM, the system activity state is continuously monitored through hardware, thus providing a more universal approach to activity detection.

With the help of SAM it is now possible to:

- Provide a trigger when a pre-programmed period of system inactivity time elapses.
- Enable/disable the sources that constitute system activity.
- Select either coarse or fine timeout values for system inactivity period.

System Activity

System activity denotes periods of time in which the system performs useful tasks. The sources Of System Activity are:

- Unmasked pending interrupts.
- Unmasked interrupts in service.
- Access to hard disk data port.
- I/O Access to programmable chip select port.
- · DMA transfers.
- Coprocessor cycles.
- A programmable PCU input.
- NMI.

SAM allows for excluding the following interrupt sources from contributing to system activity:

- IRQ 0, used by DOS to keep track of the system time.
- IRQ7, used for spurious interrupts and parallel port interrupts.
- IRQ 8, used by Windows, OS/2 and other multitasking environments to keep the scheduler running.
- A progammable interrupt level used as a power management interrupt.

SAM also takes into account programs such as MOUSE.COM which, in an attempt to locate a mouse on a communication port, generates interrupts on interrupt levels 3 and 4, and leaves them pending. To overcome this problem, SAM allows only the unmasked pending interrupts on 3 and 4 to constitute system activity.

Using SAM for System Power Management:

a) System Timeout Capability

SAM can be programmed to determine coarse periods of inactivity, with the minimum period as one minute, four seconds, up to a maximum period of 16 minutes. It is also possible to extend the maximum limit to any value by reading the Activity Before bit (ACTBEF) in the Activity Monitor Control Register at Port Address B072H.

On reaching the programmed period, SAM generates a Local Attention signal. Typically, the Local Attention is tied to a power management interrupt. In response to Local Attention, the power management interrupt handler makes it possible to prepare the system for a Suspend operation.

b) Responding to a Suspend Request

SAM can be programmed to determine a clean breakpoint for suspending the system upon receiving the Suspend request. At the time the Suspend request is received, it is possible that the system is busy performing an indivisible operation, and it is necessary to wait for the system to finish this indivisible operation before initiating suspend. In order to do this, control to the CPU must be relin-

quished for just enough time for the CPU to complete the operation. This is referred as Suspend arbitration.

In addition to performing Suspend arbitration, SAM is also responsible for determining the earliest opportunity to initiate the Suspend sequence. For instance, if a Suspend request is caused by a low battery condition, it is imperative that the system be placed in the suspend state as soon as possible. Here the fine granularity of SAM may be used to determine brief periods of inactivity from as low as 7.8 milliseconds to as high as 117.2 milliseconds, and establish a clean breakpoint for Suspending the system.

Advantages of SAM:

- 1. SAM is a reliable and consistent approach to detecting system activity.
- 2. SAM is hardware based making it truly non-obtrusive
- SAM is independent of the operating environment and the execution mode of the processor.
- 4. SAM can perform in two modes:
- Detection of system activity for extended periods of time, for the purposes of system timeout.
- Detection of brief periods of inactivity for initiating Suspend.
- Programmability allows for the control of sources of system activity and setting up coarse and fine timeout values.
- SAM generates a signal called Local Attention (LCL_ATN) on reaching programmed periods of timeout. This signal is generally tied to an unused IRQ level to invoke the Power Management program.
- SAM also carries information on DMA activity state. This is used for determining whether it is appropriate to place the processor in the Sleep Mode.

 SAM makes it possible to read the state of the interrupt controllers and, if needed, reprogram them on Resume.
 This is provided to handle the spurious interrupts that are generated by devices at powerup time on Resume.

NOTE

SAM cannot be used for determining when the processor should be placed in the Sleep Mode. This determination is intimately tied to the operating environment and is handled by Western Digital's Power Management drivers DOS/VCPI, Windows and OS/2.

9.2 PROCESSOR POWER DOWN MODE

The Processor Power Down Mode is initiated by setting bit 13 of the register at Port Address 1872H to one. The CPURES signal is asserted, then tristated. An internal 200K pullup resistor holds the CPURES active. The Processor Power Down (PMC # 5) signal from the PMC Control Register is used to control the power converter from the processor. The WD7710LP holds CPUCLK, READY, HOLD, INTRQ and NMI low to the processor.

The same conditions used to restart a stopped clock also initiate the Power Up Mode. The Power Up Mode is entered by an unmasked DRQ, unmasked IRQ interrupt or a PMC input change, resulting in an unmasked NMI to Port 9072H. A Processor Power Good signal is then input on the PMCIN pin. After 1 ms., PMC Processor Power Good signal is checked for a logic 1 state. At this time, CPURES is driven high and the CPUCLK, READY, HOLD, INTRQ and NMI signals are driven to their correct states. CPURES remains asserted for 64 additional CPUCLKs.

The PMC unit is composed of two external chips, 74HCT273 octal latch used for the eight PMC outputs from data bus ED0 - ED7 and a 74HCT151 8:1 multiplexer used for the PMCIN signal. The PMC output latches are cleared at power up (see Figure 5-1).

The keyboard processor may access the WD7710LP's internal registers by way of the PMC logic. The keyboard processor starts a local ac-

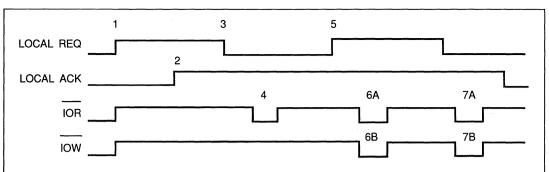
cess by asserting LCL_REQ, which causes PMCIN 2 to be asserted and written in the PMC input register at Port 8872H (see Figure 5-1 and Table 9-2). The WD7710LP arbitrates with refresh, DMA and master for a hold cycle from the processor. When the processor returns a hold acknowledge (HLDA), the WD7710LP asserts LCL_ACK (PMC output 3 from Port 7072H) on the ED0 - ED7 data bus. The keyboard processor then passes the opcode/address byte to the WD7710LP on the data bus and drops the LCL_REQ. The WD7710LP responds by de-asserting LCL ACK.

If the opcode specified a register write, data high (D15 through D08) and data low (D07 through D00), bytes are passed to the WD7710LP. If the opcode specified an I/O read, the data high and data low bytes are sent from the WD7710LP to the keyboard processor.

All special operation registers within the WD7710LP may be accessed in this manner without first unlocking the register. See section 2.8.2, Port Address F073H, for Lock/Unlock Register. This method allows the keyboard processor to control speed switching and other parameters without host processor intervention.

Figure 9-1 shows the handshake procedure, followed by the keyboard controller and the WD7710LP.

Figures 9-2 and 9-3 represents the powerdown and powerup sequence and control.



- 1 8042 Requests local data transfer
- 2 WD7710LP returns LOCAL_ACK after receiving HLDA from the host processor
- 3 8042 loads address and OPCODE into data register, then drops LOCAL_REQ
- 4 WD7710LP reads address and OPCODE
- 5 8042 Reloads data register with high byte, then asserts LOCAL_REQ
- 6A WD7710LP Reads high byte

7A WD7710LP Read low byte, writes to internal register

FOR READ CYCLE OF WD7710LP INTERNAL REGISTER:

6B WD7710LP Writes high byte to 8042

7B WD7710LP writes low byte to 8042

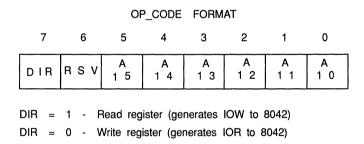


FIGURE 9-1. REGISTER ACCESS BY KEYBOARD CONTROLLER

9.3 PMC OUTPUT CONTROL REGISTERS

Port Address 7072H - Bits 07-00 are Read only

15	14	13	12	11	10	09	08

Port Address 7872H - Bits 07-00 are Read and Write

15	14	13	12	11	10	09	08

07	06	05	04	03	02	01	00
OUT	OUT	OUT	OUT	OUT	OUT	OUT	OUT
7	6	5	4	3	2	1	0

Signal Name								_	efault STIN
All signals									None

PMC Output Control Bits 7:0

Featured only in the WD7710LP

07	06	05	04	03	02	01	00
OUT F	OUT E	OUT D	OUT C	OUT B	OUT	OUT 9	OUT 8

Signal Name						*		Defau RSTIN	
All signals								. Non	е

PMC Output Control Bits 15:08

Featured only in the WD7710LP

PMC	PMC OUTPUT SIGNAL PORT 7072H	PMC	PMC OUTPUT SIGNAL PORT 7872H
он	CPU Clock Driver Enable	8H	User Defined
1H	LCD Enable	9H	User Defined
2H	Backlight Enabled	AH	User Defined
ЗН	LCL_ACK	ВН	User Defined
4H	LCL_ATN	СН	User Defined
5H	Processor powerdown	DH	User Defined
6H	Gate A20	EH	User Defined
7H	Full Powerdown	FH	User Defined

TABLE 9-1. PMC OUTPUT SIGNALS

9.4 PMC TIMERS

Port Address 8072H - Read and Write

When no keyboard or Mouse interrupts have occurred for the time specified by BL_TIMEOUT or LCD_TIMEOUT, PMC Output 1 or 2 is written to the PMC OUTPUT CONTROL 7:0 register at Port Address 7072H (see Table 9-1) to disable the LCD or Backlight. The timer is reset and the Backlight and LCD control re-enabled at the refresh cycle following a Keyboard or Mouse interrupt. The Mouse Interrupts are programmed by bits 01 and 00 (BL_MOU) in the RAM Shadow And Write Protect Register at Port Address 6072H. The same timer is used for the Backlight and LCD timeout.

The timeout delay may be programmed in increments of five seconds, to a maximum of 1,270 seconds, or 21 minutes and 10 seconds.

15	14	13	12	11	10	09	08
			BL_TI	MEOUT			

07	06	05	04	03	02	01	00
			LCD_T	IMEOUT	•		

Signal						_	<u>efaul</u> t
Name						R	STIN
BL_TIMEOUT † .							0
LCD_TIMEOUT †							0

† Featured only in the WD7710LP

Bits 15-08 - BL_TIMEOUT, Backlight Time Out

00H - Backlight always disabled 01H - Enabled for 5 seconds

02H - Enabled for 10 seconds

1

FEH - enabled for 254 x 5 seconds

FFH - Backlight enabled

Bits 07-00 - LCD TIMEOUT, LCD Time Out

00H - LCD always disabled

01H - Enabled for 5 seconds

02H - Enabled for 10 seconds

1

FEH - enabled for 254 x 5 seconds

FFH - LCD enabled

9.5 PMC INPUTS

Port Address 8872H - Read and Write

15	14	13	12	11	10	09	08
PMC_	EN_	AF	AF	AF	AF	AF	AF
UPD	LCL	7	6	5	4	3	2

07	06	05	04	03	02	01	00
IN 7	IN 6	IN 5	IN	IN	IN	IN	IN
7	6	5	4	3	2	1	0

Signal Name								efault it RSTIN
PMC UPD								0
EN_LCL †								0
AF7-AF2 †								0
IN7-IN0								None

† Featured only in the WD7710LP

Bit 15 - PMC UPD, Enable PMC Update

PMC UPD = 0 -

No update cycles occur.

PMC UPD = 1 -

A change of state of PMC outputs 7 through 0 (Port Address 7072H) or the internal A20 GATE, causes an update cycle of the PMC 7:0 output latch.

Bit 14 - EN_LCL, Enable Local Request - Featured only in the WD7710LP

EN_LCL enables the PMCIN 2 to initiate a local access of the WD7710LP internal registers from the keyboard controller.

EN_LCL = 0 -

PMCIN 2 is user defined.

EN LCL = 1 -

PMCIN 2 is LOCAL REQ.

Bits 13-08 - AF7-AF2, Local Attention Flags Featured only in the WD7710LP

Local attention flags AF7 through AF2 are set to indicate which PMC input(s) have caused LCL_ATN in PMC Interrupt Enable Register at Port C872H to be asserted. To clear the flag and corresponding IN bit in the PMC Inputs Register, it is necessary to clear the corresponding EA bit in PMC Interrupt Enable Register. If both an EA bit and EI bit in the PMC Interrupt Enable Register are set, both must be reset to clear the corresponding IN status and AF flag.

AF7 - AF2 = 0 -

This PMC input did not cause LCL_ATN to be asserted.

AF7 - AF2 = 1 -

This PMC input caused LCL_ATN to be asserted.

Bits 07-00 - IN7-IN0, PMC Inputs 7-0

The Activity Monitor Mask Register at Port Address D872H may be used to select one of the PMC inputs IN7 through IN2 as a source of activity for power management purposes.

IN7 through IN0 are status flags which provide information about the corresponding PMC input IN7 through IN0. IN1 and IN0 represent the current state of the input, while IN7 through IN2 represent either the current state or a latched transition. An IN7 through IN2 status is unlatched when both the corresponding EI and EA bits in the PMC Interrupt Enable Register at Port C872H are reset. It becomes a latched status when either the corresponding EI or EA bit is set. See Table 9-2.

9.6 PMC INTERRUPT ENABLE

Port Address C872H - Read and Write

15	14	13	12	11	10	09	08
EI7	EI6 Non-ma	EI5 askable	EI4 Interrupt	EI3 Enable	El2		

07	06	05	04	03	02	01	00
EA7			EA4 ntion Ena		EA2		

Signal Name								e <u>fault</u> At RSTIN
EI7-EI2 † .								
EA7-EA2 †								0

† Featured only in the WD7710LP

Bits 15-10 - EI7-EI2, Non-maskable Interrupt Enable 7 through 2 - Featured only in the WD7710LP

EI7 through EI2 enable the generation of an NMI when the corresponding PMC inputs IN_7 through IN_2 in Port 8872H change state. For example, when EI7 is a 1 and IN_7 changes from a 0 to 1 an NMI will be generated.

E17-E12 = 0 -

Non-maskable Interrupt not enabled

E17-E12 = 1 -

Non-maskable Interrupt is enabled

Bits 09, 08 - Not used, state is ignored

Bits 07-02 - EA7-EA2, Local Attention Enable Featured only in the WD7710LP

EA7 through EA2 enable the assertion of LCL_ATN by the corresponding IN_7 through IN_2. LCL_ATN is PMC output number 4.

EA7-EA2 = 0 -

LCL ATN is not enabled

EA7-EA2 = 1 -

LCL ATN is enabled

Bits 01, 00 - Not used, state is ignored

Ę

9.7 NMI STATUS

Port Address 9072H - Read and Write

15	14	13	12	11	10	09	08
0	0	0	0	0	0	0	0
1							

07	06	05	04	03	02	01	00
IF7	IF6 Non-ma	IF5 iskable	IF4 Interrupt	IF3 Flags	IF2	0	0

Signal Name Default At RSTIN

IF7-IF2 † 0-

† Featured only in the WD7710LP **Bits 15-08** - Not used, must be 0 Bits 07-02 - IF7-IF2, Non-maskable Interrupt Flags 7 through 2 - Featured only in the WD7710LP

NMI interrupt flags IF7 through IF2 are set to indicate which PMC input(s), if any, have caused NMI to be asserted. To reset the flag and corresponding IN status bit in the PMC Input Register at Port 8872H, it is necessary to reset the corresponding bit in the PMC Interrupt Enable Register at Port C872H. If both an EA bit and EI bit in the PMC Interrupt Enable Register are set, both must be reset to clear the corresponding IN status and IF flag.

Bits 01, 00 - Not used, must be 0

PMC INPUT NUMBER ¹	PMC INPUT NAME	INTERRUPT ON	SETS FLAG NUMBER ²
00H	TURBO		
01H	PROC_PWR_GOOD		
02H	LCL_REQ or User Defined	Transistion	IF2 or AF2
03H	User Defined	Transistion	IF3 or AF3
04H	User Defined	Transistion	IF4 or AF4
05H	User Defined	Transistion	IF5 or AF5
06H	User Defined	Transistion	IF6 or AF6
07H	User Defined	Active Edge	IF7 or AF7

Port Address 8872H, section 9.5
 Port Address 9072H, section 9.7
 Port Address 8872H, section 9.5

TABLE 9-2. PMCIN INPUTS



9.8 SERIAL/PARALLEL SHADOW REGISTER

Port Address D072H - Read only

The Shadow Register is particularly useful in laptop applications by allowing the suspend/resume software to restore correct status to on-board serial and parallel devices.

15	14	13	12	11	10	09	08
SP_	Α	SP_B			PP_	2	

07	06	05 04 03 02					00					
			PP_	0								
l												

Signal Name								_	e <u>fault</u> t RSTIN
All signals									None

Bits 15, 14 - SP_A, Serial Port A Register 2

This field represents bits 7 and 6 of Serial Port A Register 2.

Bits 13, 12 - SP_B, Serial Port B Register 2

This field represents bits 7 and 6 of Serial Port B Register 2.

Bits 11-08 - PP 2. Parallel Port Register 2

This field represents bits 3-0 of Parallel Port Register 2

Bits 07-00 - PP 0, Parallel Port Register 0

This field represents bits 7-0 of Parallel Port Register 0.

9.9 INTERRUPT CONTROLLER SHADOW REGISTER

Port Address D472H - Read only

When performing a resume operation, it may be advantageous to reset and reinitialize the interrupt controllers in the WD7710. Since many of the interrupt control registers are write only, it is impossible to determine the state of the interrupt controllers at suspend time. This register makes it possible to determine the state of selected signals internal to the master and slave interrupt controllers. With this information, when the interrupt control registers are reinitialized during resume, they can be returned to the state in which they were before suspend.

ICW2, ICW4, OCW2 and OCW3 referred to in this text is further defined in sections 5.5.2.2, 5.5.2.4, 5.5.3.2 and 5.5.3.3.

15	14	13	12	11	10	09	08
AMT OUT	DEV	,	TM7	TS7	S F N M	AUT_ EOI	RA_ EOI

07	06	05	04	03	02	01	00
PLM2	PLM1	PLM0	PLS2	PLS1	PLS0	SMM	SMM
Priorit	y Level	Master	Priority	Level	Slave	M	S

Signal Name		e <u>fault</u> At RSTIN
Bits 15, 12-00		None
Bits 14, 13		00

Bit 15 - AMTOUT, Activity Monitor Timeout

AMTOUT represents the current state of the timeout comparator in the activity monitor. It is for test purposes only

Bit 14, 13 - DEV, Device

DEV identifies the device as WD7910 or WD7710 and is used in conjunction with VER at Port Address 9872H and SVER at Port Address A872H. DEV, VER and SVER are defined in Table 10.1.

Bit 12 - TM7, Master Interrupt Vector Bit 7

TM7 represents bit 7 of the Interrupt Vector in the Master Interrupt Controller as set by ICW2. Bits 6 through 3 of the Interrupt Vector may be read from D6 through D3 by a Poll Command to the Master Interrupt Controller. The Poll Command is implemented by P_C = 1 (bit 2 of OCW3).

Bit 11 - TS7, Slave Interrupt Vector Bit 7

TS7 represents bit 7 of the Interrupt Vector in the Slave Interrupt Controller as set by ICW2. Bits 6 through 3 of the Interrupt Vector may be read from D6 through D3 by a Poll Command to the Slave Interrupt Controller. The Poll Command is implemented by $P_C = 1$ (bit 2 of OCW3).

Bit 10 - SFNM, Special Fully Nested Mode

SFNM represents the state of ICW4 - bit 4 in the Master Interrupt Controller. The WD7710 does not require SFNM for the slave interrupt controller and ignores its state.

Bit 09 - AUT_EOI, Auto End Of Interrupt

AUT_EOI represents the state of ICW4 - bit 1 in the Master Interrupt Controller. The WD7710 does not require AUT_EOI for the slave interrupt controller and ignores its state.

Bit 08 - RA EOI, Rotate Auto End Of Interrupt

RA_EOI indicates whether or not Rotate On Automatic End Of Interrupt has been selected in the Master Interrupt Controller by EOI_CONT (bits 7 through 5 of OCW2). The WD7710 does not require Rotate On End Of Interrupt for the slave interrupt controller and ignores its state.

RA EOI = 0 -

Rotate On Auto End Of Interrupt has not been selected.

RA_EOI = 1-

Rotate On Auto End Of Interrupt has been selected.

Bits 07-05 - PLM2-PLM0, Priority Level Master

PLM2-PLM0 represent the bottom priority level programmed into the Master Interrupt Controller by INT_LEV (OCW2 bits 2 through 0).

Bits 04-02 - PLS2-PLS0, Priority Level Slave

PLS2-PLS0 represent the bottom priority level programmed into the Slave Interrupt Controller by INT_LEV (OCW2 bits 2 through 0).

Bit 01 - SMMM, Special Mask Mode Master

SMMM indicates whether Special Mask Mode has been set in the Master Interrupt Controller by a write to SMM in OCW3.

SMMM = 0 -

Special Mask Mode is not enabled.

SMMM = 1 -

Special Mask Mode is enabled.

Bit 00 - SMMS. Special Mask Mode Slave

SMMS indicates whether Special Mask Mode has been set in the Slave Interrupt Controller by a write to SMM in OCW3.

SMMS = 0 -

Special Mask Mode is not enabled.

SMMS = 1 -

Special Mask Mode is enabled.

9.10 PORT 70 SHADOW REGISTER

Port Address E472

15	14	13	12	11	10	09	08
CLK	REF	INTR	NOD	TOD	RSVD	RSVD	RSVD
32K	DET		MA	UN			

07	06	05	04	03	02	01	00
NMI	RTC						
MSK	IR6	IR5	IR4	IR3	IR2	IR1	IR0

This register provides read-only information on the status of interrupts and DMA which is useful for determining when the processor may be put to sleep. Two bits are also provided for generating software delays without incurring the operating system traps that would result from accessing I/O port 0061 in virtual 86 mode. This register also contains a shadow of the real time clock address register, a write only I/O port. It is necessary to access the real-time clock CMOS RAM during Suspend/Resume operations. This shadow of Port 0070 allows it to be restored to the same state it was in at suspend time.

This register can be read without first unlocking the WD7710. This is important since the CLK32K, REFDET, and TODUN bits may need to be read frequently.

Bit 15 - CLK32K

This read-only bit is a divide by 2 of the PDREF input. It can be read to provide a stable timing reference, not subject to reprogramming of the refresh rate. CLK32K has a 30.5 microsecond period with a 50% duty cycle.

Bit 14 - REFDET

This read-only bit is a copy of the REFDET bit available from I/O Port 0061, Bit 4.

Bit 13 - INTR

This read-only bit gives the state of the INTR output pin to the CPU.

Bit 12 - NODMA, No DMA

This read-only bit is set whenever it has been at least 30.5 microseconds since the last DMA or bus master cycle occurred.

Bit 11 - TODUN, Time of Day Update Needed (R/W)

This is a general purpose storage bit which can be written and read but has no effect on internal logic. Its purpose is to allow an SMI handler to signal the operating system that the time of day has been corrupted. This bit is checked by the Timer 0 Interrupt Handler. Note that although this bit is readable without unlocking the WD7710, it cannot be written unless the WD7710 is unlocked.

Bits 10:8 - RSVD

These read-only bits are reserved for future use. They currently are read back as a 0.

Bit 7 - NMIMSK, NMI Mask

This read-only bit gives the state of the NMI mask bit as it was set the last time I/O port 0070 was written.

Bits 6:0 - RTCIR6-0

These read-only bits give the state of the real time clock address register as it was set the last time I/O port 0070 was written.

9.11 ACTIVITY MONITOR CONTROL REGISTER

Port Address B072H - Bits 15, 13-11, 08-00 Read and Write Bits 14, 10, 09 Read only

For an overview of the Activity Monitor Register, see the general description of the Activity Monitor Mask Register in section 9.12.

15	14	13	12	11	10	09	08
IRR AE	CB12			IND ET		ACT BEF	AM EN

07	06	05	04	03	02	01	00	
		eout Cou		Fine Timeout Count AMC3 AMC2 AMC1 AMC0				
AMC	AIVIC	AMCS	AMC4	AIVIC3	AIVIC2	AMCT	AMCU	

Signal Name	Default At RSTIN
IRRAE	 . 0
CB12	 . None
AMTM	 . 0
ACTLCH	 . None
INDET	 . None
ACTAFT	 . None
ACTBEF	 . None
AMEN	 . 0
AMC7-AMC0	 . 0-0

Bit 15 - IRRAE, Interrupt Request Register Activity Enable

IRRAE controls whether or not the IRR (Interrupt Request Register) bits from the Interrupt Controller at Port Address 020H, 0A0H may be a source of activity (refer to section 5.5).

IRRAF = 0 -

No IRR bits can be used as an activity source.

IRRAE = 1 -

IRR bits can be a source of activity. IRR8, IRR7 and IRR0 may still be masked by Port Address D872H.

Bit 14 - CB12, Counter Bit 12

For factory use only.

The activity monitor circuitry contains a 17-bit timeout counter for generating long timeouts. For test purposes, CB12 represents the twelfth bit of that counter.

Bit 13 - AMTM, Activity Monitor Test Mode

AMTM = 0 -

Activity Monitor functions normally.

AMTM = 1 -

Activity Monitor is in Test Mode. Activity Monitor State Machine is clocked faster than normal and nine stages of the 17-bit timeout counter are bypassed.

Bit 12 - ACTLCH, Activity Latch

This latch is always enabled, regardless of other enable bit settings. Writing a 1 to ACTLCH has no effect.

ACTLCH = 0 -

The Activity Latch is reset by writing 0 to ACTLCH.

ACTLCH = 1 -

Activity by an unmasked source has occurred.

Bit 11 - INDET, Inactivity Detect

Writing a 1 to INDET has no effect.

INDET = 0 -

Writing 0 to INDET, or placing the Activity Monitor in the idle state by writing 0 to AMEN (bit 8), resets INDET, ACTAFT and ACTBEF

INDET = 1 -

System is idle and the Activity Monitor has requested the local attention output be set. This occurs when there has been no unmasked activity, allowing the predetermined timeout (bits 07-00) to be reached.

NOTE

PMCIN transitions may also cause the local attention (LCL_ATN PMC 4) output to be set.

Bit 10 - ACTAFT, Activity After INDET

ACTAFT is a read only bit and its state is ignored during writes.

ACTAFT = 0 -

Writing 0 to INDET, or placing the Activity Monitor in the idle state by writing 0 to AMEN (bit 8), resets INDET, ACTAFT and ACTBEF.

ACTAFT = 1 -

Activity has occurred after INDET had been set. This would happen when ac-

tivity occurs during the time it takes to reach the interrupt service routine invoked by the local attention output request.

Bit 09 - ACTBEF, Activity Before INDET

ACTBEF is a read only bit and its state is ignored during writes.

ACTBEF = 0 -

Writing 0 to INDET, or placing the Activity Monitor in the idle state by writing 0 to AMEN (bit 8), resets INDET, ACTAFT and ACTBEF.

ACTBEF = 1 -

Activity did occur and reset the timeout counter before INDET was set. This is important if consecutive timeout periods are being counted in a service routine to obtain a system timeout period other than that available using AMC7-AMC0 (bits 07-00). It would be necessary for the routine to clear the software counter if ACTBEF were set, since there would have been no activity only for the period of time programmed in AMC7-AMC0.

Bit 08 - AMEN, Activity Monitor Enable

This is the master enable for the Activity Monitor.

AMEN = 0 -

Writing 0 to AMEN places the Activity Monitor in the idle state.

AMEN = 1 -

Writing 1 to AMEN causes the Activity Monitor to start clocking the timeout counter. Each time an unmasked source of activity is detected, the counter is cleared. If no unmasked source of activity is detected before the timeout counter reaches the value programmed by ACM7 through ACM0, INDET and the local attention output are set. The timeout counter is then cleared and a new timeout sequence begins.

Bits 07-04 - AMC7-AMC4, Activity Monitor Counter Coarse

AMC7-AMC4 establish the timeout values from 64 seconds to 16 minutes in 64-second increments. These bits must only be written when the Activity Monitor is disabled (AMEN = 0). They may be read at any time.

AMC7	AMC6	AMC5	AMC4	
0	0	0	0	0 seconds
0	0	0	1	1 min., 4s
0	0	1	0	2 min., 8s
0	0	1	1	3 min., 12s
0	1	0	0	4 min., 16s
0	1	0	1	5 min., 20s
0	1	1	0	6 min., 24s
0	1	1	1	7 min., 28s
1	0	0	0	8 min., 32s
1	0	0	1	9 min., 36s
1	0	1	0	10 min., 40s
1	0	1	1	11 min., 44s
1	1	0	0	12 min., 48s
1	1	0	1	13 min., 52s
1	1	1	0	14 min., 56s
1	1	1	1	16 min., 0s

Bits 03-00 - AMC3-AMC0, Activity Monitor Counter Fine

AMC3-AMC0 establish the timeout values from 7.8 milliseconds to 117.2 milliseconds in 7.8 millisecond increments. Tolerance on time delays is -0, +3.9 milliseconds. These bits must only be written when the Activity Monitor is disabled (AMEN = 0). They may be read at any time.

АМСЗ	AMC2	AMC1	AMC0	
0	0	0	0	0 ms
0	0	0	1	7.8 ms
0	0	1	0	15.6 ms
0	0	1	1	23.4 ms
0	1	0	0	31.3 ms
0	1	0	1	39.1 ms
0	1	1	0	46.9 ms
0	1	1	1	54.7 ms
1	0	0	0	62.5 ms
1	0	0	1	70.3 ms
1	0	1	0	78.1 ms
1	0	1	1	85.9 ms
1	1	0	0	93.8 ms
1	1	0	1	101.6 ms
1	1	1	0	109.4 ms
1	1	1	1	117.2 ms

NOTE

The fine timeout delay (AMC3 through AMC0) is added to the coarse timeout delay (AMC7 through AMC4) to obtain the total timeout delay.

9.12 ACTIVITY MONITOR MASK REGISTER

Port Address D872H - Read and Write

The activity monitor provides a hardware solution for determining inactivity in a system. Knowing when a system is inactive is key to performing such power reduction activities as suspend. When the Activity Monitor is enabled by the Activity Monitor Control Register at Port Address B072H. the Activity Monitor clocks a counter and invokes a service routine using local attention when the counter reaches a programmed timeout value. However, while the counter is being clocked, the Activity Monitor continuously monitors for any of several events that would indicate that the system is active. If any of these events occur, the counter is reset and the timeout starts over. Thus the service routine is only invoked when the system has been inactive for a programmed period of time.

To provide a high degree of flexibility in determining what is active and what is not, many sources are routed to the Activity Monitor. These include the IRR (Interrupt Request Register) and ISR (In Service Register) bits from the Interrupt Controller, the PMC inputs, NMI output, DMA (or AT Master) cycles and I/O accesses to either the numeric coprocessor, hard disk data port or programmable chip select. All of these sources are considered activity unless masked.

The interrupt input masks are controlled in the lower byte. All ISR and IRR bits are detected as activity except those specifically masked. Note, however, that ISR2 and IRR2 are not examined since they are cascade interrupts only. Also, IRR3 and IRR4 are qualified by the Mask Register in the Interrupt Controller before being passed to the Activity Monitor. The master mask for all IRR bits is the IRRAE bit in the register at Port Address B072H.

15	14	13	12	11	10	09	08
PCS	PMC	PMC	PMC	PMC	NMI	HDD	COP
M	ILS	IS2	IS1	IS0	M	M	M

07	06	05	04	03	02	01	00
IMS1	IMS0	IRR8 M	IRR7 M	IRR0 M	ISR8 M	ISR7 M	ISR0 M

Signal Name	<u>Defaul</u> t RSTIN
All signals	 0

Bit 15 - PCSM, Programmable Chip Select Mask

PCSM = 0 -

Read or write I/O accesses to the ports defined by the programmable chip select in the WD7710LP are considered activity.

PCSM = 1 -

Read or write I/O accesses to the ports defined by the programmable chip select in the WD7710LP are ignored.

Bit 14 - PMCILS, Power Management Control Input Level Select

PMCILS determines which logic level on the selected PMC input is to be considered active. (See bits 13-11, PMCIS2-0.)

PMCILS = 0 -

PMCIN is active low.

PMCILS = 1 -

PMCIN is active high.

Bits 13-11 - PMCIS2-PMCIS0, Power Management Control Input Select

One of the PMC inputs IN7 through IN2 at Port Address 8872H may be selected for detection as a source of activity.

NOTE

The EI and EA bits at Port Address C872H, corresponding to the selected IN signal, should be cleared to prevent the IN signal from being latched internally.

PMCIS 2 1 0

0 0 - PMC input 2 selected

0 0 1 - PMC input 3 selected

0 1 0 - PMC input 4 selected

0 1 1 - PMC input 5 selected

1 0 0 - PMC input 6 selected

1 0 1 - PMC input 7 selected

1 1 0 - Reserved

1 1 1 - Disabled, no PMC inputs checked

Bit 10 - NMIM, Non-maskable Interrupt Mask

NMIM = 0 -

The NMI output is used as a source of activity.

NMIM = 1 -

The NMI output is ignored.

Bit 9 - HDDM, Hard Disk Data Port Mask

HDDM = 0 -

If the hard disk chip select has been enabled by bit 01 at Port Address 2872H, I/O read and write operations to the 16-bit hard disk data port are allowed as a source of activity.

HDDM = 1 -

The hard disk data port I/O is ignored.

Bit 8 - COPM, Coprocessor Mask

COPM = 0 -

I/O cycles to the coprocessor are treated as a source of activity. For an 80286 system, this is I/O address range 00F8H through 00FFH. For an 80386SX system, this is when A23 is high and M/\overline{O} is low.

COPM = 1 -

I/O to the coprocessor is ignored.

Bits 07, 06 - IMS1-0, Interrupt Mask Select

The local attention generated by the Activity Monitor will be routed to an available interrupt input to invoke a service routine. That interrupt is not to be detected as a source of activity. IMS1 through 0 provide a selection of four possible inputs to be used for this function and masks the corresponding IRR and ISR bits as sources of activity.

IMS 1 C

0 0 - IRQ5 masked

0 1 - IRQ10 masked

1 0 - IRQ11 masked

1 1 - IRQ15 masked

Bit 05 - IRR8M, Interrupt Request Register 8 Mask

IRR8M = 0 -

Real-Time Clock Interrupt (IRR8) may be detected as a source of activity. Bit 15 in the Activity Monitor Control Register at Port Address B072H must also be set.

IRR8M = 1 -

Real-Time Clock Interrupt (IRR8) is ignored.

NOTE

See Test Enable Register (A872), Section 11.3 for information about IRQ9 enable control.

Bit 04 - IRR7M, Interrupt Request Register 7 Mask

IRR7M = 0 -

Parallel Port or Spurious Interrupt (IRR7) may be detected as a source of activity. Bit 15 in the Activity Monitor Control Register at Port Address B072H must also be set.

IRR7M = 1 -

Parallel Port or Spurious Interrupt (IRR7) is ignored.

Bit 03 - IRROM, Interrupt Request Register 0 Mask

IRROM = 0 -

Time Of Day Interrupt (IRR0) may be detected as a source of activity. Bit 15 in the Activity Monitor Control Register at Port Address B072H must also be set.

IRROM = 1 -

Time Of Day Interrupt (IRR0) is ignored.

Bit 02 - ISR8M, Interrupt Service Register 8 Mask

ISR8M = 0 -

Real-Time Clock Interrupt (ISR8) may be detected as a source of activity.

ISR8M = 1 -

Real-Time Clock Interrupt (ISR8) is ignored.

Bit 01 - ISR7M, Interrupt Service Register 7 Mask

ISR7M = 0 -

Parallel Port or Spurious Interrupt (ISR7) may be detected as a source of activity.

ISR7M = 1 -

Parallel Port or Spurious Interrupt (ISR7) is ignored.

Bit 00 - ISR0M, Interrupt Service Register 0 Mask

ISROM = 0 -

Time of Day Interrupt (ISR0) may be detected as a source of activity.

ISROM = 1 -

Time Of Day Interrupt (ISR0) is ignored.

9.13 3V Suspend Shadow Registers

The 3V suspend mode provides maximum power savings for the system. The contents of the DRAM, chip set registers, CPU registers and video RAM are all written to the hard disk and then all voltages are shut down, including the power supply. The only logic left on in this mode is the real-time clock and a 3V suspend controller. The real-time clock and the 3V suspend controller run off of the real-time clock battery. When the resume request is sampled by the suspend controller, the suspend controller enables the power supply and resumes the system.

To maintain compatibility with the IBM AT, the timer and DMA registers cannot be read back. To overcome this, these registers are shadowed and read back through other registers. (See descriptions for registers 3C72, 4472 and 4C72.)

9.13.1 DMA Shadow Register 1

Port Address 3C72H (R)

15	14	13	12	11	10	09	08
AD_ DEC	AUTO	TRA_ TYP	TRA_ TYP	TRA_ MOD	TRA_ MOD		AUTO
07	06	05	04	03	02	01	00
TRA_ TYP	TRA_ TYP	TRA_ MOD	TRA_ MOD	AD_ DEC	AUTO	TRA_ TYP	TRA_ TYP

Bit 15, the AD_DEC bit of register 0B for DMA channel 2.

Bit 14, the AUTO bit of register 0B for DMA channel 2.

Bits 13:12, the TRA_TYP bits of registers 0B for DMA channel 1.

Bits 11:10, the TRA_MOD bits of register 0B for DMA channel 1.

Bit 9, the AD_DEC bit of register 0B for DMA channel 1.

Bit 8, the AUTO bit of register 0B for DMA channel 1.

Bits 7:6, the TRA_TYP bits of register 0B for DMA channel 1.

Bits 5:4, the TRA_MOD bits of register 0B for DMA channel 0.

Bit 3, the AD_DEC bit or register 0B for DMA channel 0.

Bit 2, the AUTO bit of register 0B for DMA channel 0.

Bits 1:0, the TRA_TYP bits of register 0B for DMA channel 0.

9.13.2 DMA Shadow Register 2

Port Address 4472H (R)

15	14	13	12	11	10	09	08
TRA_ TYP	TRA_ TYP	TRA_ MOD	TRA_ MOD	AD_ DEC	AUTO	TRA_ TYP	TRA_ TYP
07	06	05	04	03	02	01	00
0,	00	05	04	US	02	UI	00

Bits 15:14, the TR_TYP bits of register 0D6 for channel 6.

Bits 13:12, the TRA_MOD bits of register 0D6 for channel 5.

Bit 11, the AD_DEC bit of register 0D6 for channel 5.

Bit 10, the AUTO bit of register 0D6 for channel 5.

Bits 9:8, the TRA_TYP bits of register 0D6 for channel 5.

Bits 7:6, the TRA_MOD bits of register 0B for channel 3.

Bit 5, the AD_DEC bit of register 0B for channel 3.

Bit 4, the AUTO bit of register 0B for channel 3.

Bit 3:2, the TRA_TYP bits of register 0B for channel 3.

Bits 1:0, the TRA_MOD bits of register 0B for channel 2

9.13.3 DMA Shadow Register 3

Port Address 4C72H (Read only for bits 14:0)

							•
15	14	13	12	11	10	09	08
SCB		EX_ WR	RO_ PRI		CO_ DIS	TRA_ MOD	TRA_ MOD
07	06	0E	04	00	00	04	-00
07	UO	05	04	03	02	01	00

Bit 15, Shadow Control BIT (SCB)

Bit 14, Reserved

Bit 13, When SCB is low, this bit represents the EX_WR bit of register 08. When SCB is high, this bit represents the EX_WR bit of register of register 0D0.

Bit 12, When SCB is low, this bit represents the RO_PRI bit of register 08. When SCB is high, this bit represents the RO_PRI bit of register 0D0.

Bit 11, Reserved.

Bit 10, When SCB is low, this bit represents the CO_DIS bit of register 08. When SCB is high, this bit represents the CO_DIS bit of register 0D0.

Bits 9:8, These bits represent the TRA_MOD bits of register 0D6 for channel 7.

Bit 7. AD DEC bit of register 0D6 for channel 7.

Bit 6, AUTO bit of register 0D6 for channel 7.

Bits 5:4, the TRA_TYP bits of register 0D6 for channel 7.

Bits 3:2, the TRA_MOD bits of register 0D6 for channel 6.

Bit 1, the AD_DEC bit of register 0D6 for channel 6

Bit 0, the AUTO bit of register 0D6 for channel 6

9.13.4 DMA Base Address and Count Register

When the SCB is high, the DMA base aaddress and base count can be read back from register 0 to 7. When SCB is low, register 0 to 7 represents the current address and current count.

9.13.5 Timer Count

When SCB is high, the timer base count can be read back from register 40:43. When SCB is low, the register 40:43 represents the timer current count.



9.14 SAVE AND RESUME

When the WD7710LP is in the Save And Resume Mode, it typically draws less than 500 μ A. Figures 9-2 and 9-3 illustrate the steps that the WD7710LP goes through during power down and power up.

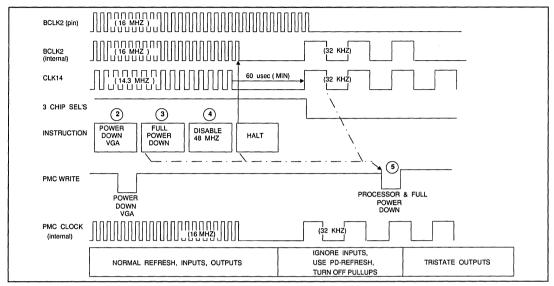


FIGURE 9-2. POWER DOWN

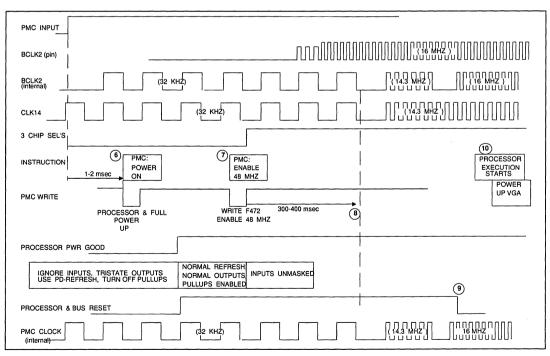


FIGURE 9-3. POWER UP

10.0 DIAGNOSTIC MODE

Simultaneously asserting MASTER, MEMR and MEMW while RSTIN is asserted, causes all output pins to become tristated. The outputs remain tristated if RSTIN is de-asserted while MASTER, MEMR and MEMW are asserted. The outputs become active drivers when RSTIN is asserted and any of the MASTER, MEMR or MEMW are not asserted. The output tristate mode allows an incircuit board tester to drive the WD7710's output pins.

I/O Pin Mapping Mode

The I/O Pin Mapping Mode provides the in-circuit tester for evaluating the connectivity of the WD7710 to the printed circuit board. Simultaneously asserting MASTER, MEMR, MEMW when A1 is high, A2 is low, and RSTIN is asserted, causes the WD7710 to switch to I/O Mapping Mode. The WD7710 stays in this mode if RSTIN is deasserted while MASTER, MEMR, and MEMW are asserted.

Full Tristate Mode

Simultaneously asserting MASTER, MEMR, and MEMW with A1 low and A2 high while RSTIN is asserted, causes all the output pins of the WD7710 to tristate and disablesall the pullup and pulldown register. The WD7710 stays in this mode if RSTIN is deasserted while MASTER, MEMR and MEMW are asserted. The outputs become active drivers when RSTIN is asserted with any of the MASTER, MEMR or MEMW is deasserted. This allows the tester to test for leakage current of the device.

Pullup and Pulldown Test Mode

Simultaneously asserting MASTER, MEMR, MEMW with A1 and A2 high while RSTIN is asserted, causes all the output pins of the WD7710 to become tristated and enables all the pullup and pulldown resistors. The WD7710 stays in this mode if RSTIN is deasserted while MASTER, MEMR and MEMW are asserted. The outputs become active drivers when RSTIN is asserted with any of the MASTER, MEMR or MEMW is deasserted. This allows the tester to test the pullup and pulldown resistors of the device.

10.1 DIAGNOSTIC REGISTER

Port Address 9872H - Read and Write

15	14	13	12	11	10	09	08
	RSVD		CLK_ TST	REF_ MAS	AUT_ A20		CLK SW

07	06	05	04	03	02	01	00						
sx	DS	DIAG											

Signal Name									<u>Defaul</u> t RSTIN				
VER													VER#
CLK_TST						٠.							0
REF_MAS													0
AUT_A20													0
Bit 09													None
CLK_SW													0
SX									٠.				None
DS	•												0
DIAG													0-0

Bit 12 - CLK TST, Clock Test

Diagnostics for factory use only.

Bit 11 - REF MAS. Bus Master Refresh

Additional external logic may be required to support the bus master initiated refresh.

REF MAS = 0 -

Does not support bus master initiated refresh (Default value).

 $REF_MAS = 1 -$

Supports bus master initiated refresh.

Bit 10 - AUT A20, Automatic Gate A20

Normally, the Alternate Gate A20 signal from Port 092H is OR'ed with the 8042 Gate A20.

When the AUT_A20 bit is set, the Alternate Gate A20 control bit automatically changes state to match the keyboard's Gate A20. Bit 1 (ALT_A20G) of Port 092H is set or reset according to the way 8042 is programmed. When the keyboard data port is read using the D1 keyboard controller command, the state of the Gate A20 status bit is replaced by that of AUT_A20.

The state of the A20 gating signal is available on PMC output 6 by reading Port 7072H (see Table 9-1).

AUT A20 = 0 -

Normal Alternate Gate A20 (Default value).

AUT A20 = 1 -

Automatic Gate A20

Bit 09 - Not used, state is ignored.

Bit 08 - CLK_SW, Clock Switch

The short clock switch reset pulse width is 1 µs plus 16 CPUCLKs. The 80486 processor requires a 1 ms clock switch.

CLK SW = 0 -

Short clock switch reset width (Default value)

CLK SW = 1 -

1 ms clock switch reset width

Bit 07 - SX, 80386SX Processor

At power up the System Controller samples the type of processor in the system.

SX = 0 -

80286 processor was detected.

SX = 1 -

80386SX processor was detected.

Bit 06 - DS, Diagnostic Signal

DS represents the state of the diagnostic signal selected by DIAG (bits 05 through 00).

Bits 05-00 - DIAG, Diagnostic Function

DIAG selects the diagnostic function to be performed. The DS bit represents the state of the signal selected. Table 10-1. lists the tests available.

DIAG = 00000 - Diagnostic output disabled, speaker normal.

DIAG = 00001 - Diagnostic output disabled, speaker disabled.

DIAG	FUNCTION	DIAG	FUNCTION
00000	Normal Speaker	10000	Reserved
00001	Speaker Disabled	10001	Reserved
00010	Reserved	10010	Reserved
00011	Reserved	10011	Reserved
00100	Reserved	10100	Reserved
00101	Reserved	10101	Reserved
00110	Reserved	10110	Reserved
00111	Reserved	10111	Reserved
01000	Reserved	11000	Reserved
01001	Reserved	11001	Reserved
01010	Reserved	11010	Reserved
01011	Reserved	11011	Reserved
01100	Reserved	11100	Reserved
01101	Reserved	11101	Reserved
01110	Reserved	11110	Reserved
01111	Reserved	11111	Reserved

TABLE 10-1. DIAGNOSTIC TESTS

10.2 DELAY LINE DIAGNOSTIC REGISTER

Port Address A072H - Read and Write

15	14	13	12	11	10	09	08

07	06	05	04	03	02	01	00			
LAT	DL			DELAY						

Signal Name								-	efault RSTIN
Bits 15-08									None
LAT									0
DL									0
DELAY .									None

Bit 07 - LAT, Latch Output Strength

The delay line count value (bits 05-00) is used to control the output buffer strength. The output buffer strength is normally adjusted every time the delay count changes. LAT may be used to lock the buffer strength at its present value.

LAT = 0 -

The output buffer strength is adjusted when the delay count changes.

LAT = 1 -

The output buffer strength is locked at its present value.

Bit 06 - DL, Delay Freeze

The internal self tuning delay line normally is updated by one delay element during every refresh cycle. For test purposes, the delay may be forced to stop generating calibration cycles. When delay line updates are frozen, the tester may write different delay line counter values in bits 05-00.

DL = 0 -

Normal delay line operation (Default value)

DL = 1 -

Freeze delay line

Bits 05-00 - DELAY, Delay Counter Value

The delay line counter value is used to control the output buffer strength.

This register may be written to when DL is set to one.

10.3 TEST ENABLE REGISTER

Port Address A872H - Bits 15-10 Read only Bits 09-00 Read and Write

The test function bits 07-03 are for factory use only.

15	14	13	12	11	10	09	08
	SVE	3		BF40	BC40	IRQ9 EN	TDL

07	06	05	04	03	02	01	00
OLD	BFC	BIST	BFC	BIST	EN_	DISFA	EN_
IHLD	3	3	40	40	PLD		LVL

Signal							De <u>fault</u>
Name							At RSTIN
All signals							0-0

Bits 15-12 - SVER, Secondary Version Number.

See VER at Port Address 9872H.

	4721	ADDRESS I DEVICE - s 14, 13	PORT ADDRESS A872H SECONDARY VERSION - Bits 15-12									
14	13	Device	15	14	13	12	Rev					
0	0	WD76C10	0	0	0	0	Α					
0	1	WD7710/7910	0	0	0	1	В					
1	0	Reserved	0	0	1	0	С					
1	1	Reserved	-	-	-	-	-					
			1	1	1	1	Р					

Bit 11 - BF40, EMS Register Self Test Status

Bit 10 - BC40, EMS Register Self Test Status

Bit 09 - IRQ9EN = 0, Masks IRR9 and ISR9 so that the System Activity Monitor does not detect these signals. This prevents vertical retrace from being a source of activity for SAM.

IRQ9EN = 0.

Masking of IRR9 and ISR9 enabled

IRQ9EN = 1.

Masking disabled

Bit 08 - TDL, Test Delay Line.

Bit 07 - OLD IHLD,

 $OLD_IHLD = 0 -$

SX test not enabled

OLD_IHLD = 1 -

SX test enabled

Bit 06 - BFC3,

BFC3 = 0 -

DMA register file test

BFC3 = 1 -

DMA register file test

Bit 05 - BIST3,

BIST3 = 0 -

DMA register file test

BIST3 = 1 -

DMA register file test

Bit 04 - BFC40.

BFC40 = 0 -EMS mapping RAM

BFC40 = 1 -EMS mapping RAM

Bit 03 - BIST40,

BIST40 = 0 -

EMS mapping RAM

BIST40 = 1 -

EMS mapping RAM

Bit 02 - EN PLD, Enable Pulldown

EN PLD = 0 -

Pulldown resistors are not enabled.

EN PLD = 1 -

40K to 100K internal pulldown resistors will be enabled during processor power down or full power down on processor address lines A23 through A00, and on processor data lines D15 through D00.

Bit 01 - DISFA. Disable First Access

DISFA = 0 -

First access Page Mode cycles are not disabled

DISFA = 1 -

First access Page Mode cycles are disabled. Page Miss cycles occur instead.

Bit 00 - EN LVL, Enable Level

The Interrupt Controller may be programmed to support Level Sensitive Mode for diagnostic adapters which may need to test this capability.

EN LVL = 0 -

Level Sensitive Interrupt Mode in the 8259 Interrupt Controller is not supported. L_T (bit 3) at Port 020H has no effect.

EN LVL = 1 -

Level Sensitive Interrupt Mode in the 8259 Interrupt Controller is supported. L_T (BIT 3) at Port 020H now controls the selection of edge-sensed or level-sensed interrupts.

10.4 TEST STATUS REGISTER

Port Address DC72H - Read only

For factory use only.

15	14	13	12	11	10	09	08
	ay Line MED		DLT6	DLT5	DLT4	DLT3	DLT2

07	06	05	04	03	02	01	00
DLT1	DLT0	BF34	BF33	BF32	BF31	BF30	вс

Signal Name								-	efault RSTIN
All signals									None

Bit 15 - CAL, Calibration

CAL = 0 -

Internal delay line has not completed initial calibration.

CAL = 1 -

Internal delay line has completed initial calibration.

Bits 14, 13 - MED, SLOW, Medium and Slow

These bits provide information regarding the output buffer strength.

MEDIUM	SLOW	
0	0	Output buffers are set to low strength (fast WD7710/7710LP).
0	1	Invalid
1	0	Output buffers are set to medium strength (medium speed WD7710/7710LP).
1	1	Output buffers are set to full strength (slow WD7710/7710LP).

Bits 12-06 - DLT6-DLT0,

These bits provide information about internal nodes and are for test purposes only. Their state is dependent upon the test mode selected and the speed of the WD7710/7710LP.

Bits 05-01 - BF34-BF30,

These bits provide information about internal nodes and are for test purposes only. Their state is dependent upon the test mode selected and the speed of the WD7710/7710LP.

Bit 00 - BC

This bit provides information about internal nodes and are for test purposes only. Its state is dependent upon the test mode selected and the speed of the WD7710/7710LP.

11.0 DC ELECTRICAL SPECIFICATIONS

11.1 MAXIMUM RATINGS

Supply Voltage (Vcc) with respect to Vss (ground)	Vcc - Vss ≤ 7.0 Volts	
Voltage on any pin with respect to Vss (ground) .	Vss -0.3 Volts to Vdd +0.3 Volts	s
Operating Temperature	0°C (32°F) to 70°C (158°F)	
Storage Temperature	40°C (-40°F) to 125°C (257°F)	
Power Dissipation	600 mW	

NOTE

Maximum limits indicate where permanent device damage occurs. Continuous operation at these limits is not intended and should be limited to those conditions specified in the DC Operating Characteristics.

11.2 DC OPERATING CHARACTERISTICS

TA = 0° C (32°F) to 70°C (158°F) Vcc = +5V ±.25V (5%) for WD7910 and WD7910LP

SYMBOL	CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
IIL IOZ	Input Leakage Tristate And Open Drain Output Leakage	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			
VIH	Input High Voltage	2.0		V	
VIL	Input Low Voltage	1	.8	V	
VIHC	CPUCLK Input High	3.6		V	
VIL	CPUCLK Input Low		.6	V	
ICC	Supply Current		200 150	mA mA	Inputs at 2.0V Inputs at 5.0V Outputs Open, CPUCLK = 32 MHz
ICCSB	Typical Supply Current, Power Down Mode For WD7910LP	.5		mA	Typical, CPUCLK Off, CLK14 = 32 KHz

TABLE 11-1. DC OPERATING CHARACTERISTICS

FOR PINS WITH INTERNAL PULLUPS:

MASTER, IOCK, IOCS16, MEMCS16, ZEROWS, IOCHRDY, RDYIN, PDREF

SYMBOL	CHARACTERISTIC	TIC MIN MAX UNIT CONDITIONS		CONDITIONS	
IIL	Input Pullup Current	-30	-110	μА	Not suspend and resume mode

TABLE 11-1, DC OPERATING CHARACTERISTICS cont.

M/IO, PEACK, NPERR, NPBUSY, S0, S1, NPRST, CPURES, DPH, DPL

SYMBOL CHARACTERISTIC		MIN	MAX	UNIT	CONDITIONS
IIL	Input Pullup Current	-30	-110	μА	Not processor down or suspend mode

TABLE 11-1, DC OPERATING CHARACTERISTICS cont.

PMCIN, IOCHRDY, ZEROWS, IOCS16, MEMCS16, MASTER, PDREF, REFRESH, BHE, IOR, IOW, MEMR, MEMW

SYMBOL	BOL CHARACTERISTIC		MAX	UNIT	CONDITIONS
IIL	Input Pullup Current	-30	-110	μА	Not suspend mode

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

CASL3, CASL2, CASH3, SDT/R

SYMBOL	CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
IIL	Input Pullup Current	-30	-110	μА	RESET IN = 0

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

FOR PINS WITH INTERNAL PULLDOWNS:

A23-A0, D15-D0

SYMBOL	MBOL CHARACTERISTIC		MAX	UNIT	CONDITIONS
IIL	Input Pulldown Current	-30	-110	μА	Processor power down or suspend mode

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

FOR OUTPUTS:

DACK2-0, DACKEN, D15-D0, READY, CPURES, HOLD, INTRQ, A23-A0, NMI, DPH, DPL, RA10-RA8, RA7/ED7-RA0/ED0, BHE, RAS3-RAS0, CASL3-CSL0, CASH3-CASH0, W/R, DT/R, DEN1, DEN0, SDT/R, SDEN, CSEN, LOMEG

SYMBOL	CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
VOH	Output High Voltage	Vcc8		V	IOUT = -100 μA
VOH	Output High Voltage	2.4		V	IOUT = -2 mA
VOL	Output Low Voltage		.4	V	IOUT = 2 mA
		1	ł	1	

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

FOR OUTPUTS:

MXCTL2-0

CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
Output High Voltage	Vcc8		٧	IOUT = -200 μA
Output High Voltage	2.4		V	IOUT = -4 mA
Output Low Voltage		.4	V	IOUT = 4 mA
	Output High Voltage Output High Voltage	Output High Voltage Vcc8 Output High Voltage 2.4	Output High Voltage Vcc8 Output High Voltage 2.4	Output High Voltage Vcc8 V Output High Voltage 2.4 V

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

FOR OUTPUTS:

IOR, IOW, MEMR, MEMW, AEN, SYSCLK, BALE, LA20, SA0

SYMBOL	CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
VOH VOL	Output High Voltage Output Low Voltage	2.4	.5	V	IOUT = -3 mA IOUT = 24 mA

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

FOR OUTPUT:

REFRESH

SYMBOL	CHARACTERISTIC	MIN	MAX	UNIT	CONDITIONS
VOL	Output Low Voltage		.5	V	IOUT = 24 mA

TABLE 11-1. DC OPERATING CHARACTERISTICS cont.

12.0 AC OPERATING CHARACTERISTICS

The AC Operating Characteristics are divided into three major categories: Memory Timing Section 12.1, AT Bus Timing Section 12.2, Processor Timing Section 12.3, and Cache Controller Timing (Section 12.4).

Table 12-1 lists the timing tables and figures, and their section location.

TABLE NUMBER	FIGURE NUMBER	TITLE	SECTION
12-3		80286 - Page Mode Memory Timing	12.1.1
	12-1	80286 - Page Mode First Access Read/Write	12.1.1
	12-6	80286 - Page Mode Read Hit Followed By Write Hit	12.1.1
12-4		80286 - Non-Page Mode 00 Memory Timing	12.1.2
	12-7	80286 - Non-Page Mode 00 1 Wait State Write	12.1.2
	12-8	80286 - Non-Page Mode 00 1 Wait State Read	12.1.2
	12-9	80286 - Non-Page Mode 00 2 Wait States Read After Write	12.1.2
12-5		80286 - Non-Page Mode 01 Memory Timing	12.1.3
	12-10	80286 - Non-Page Mode 01 0 Wait State Write	12.1.3
	12-11	80286 - Non-Page Mode 01 0 Wait State Read	12.1.3
12-6		80386SX - Page Mode Memory Timing	12.1.4
	12-12 ↑	80386SX - Page Mode, First Access Read/Write	12.1.4
	12-17	80386SX - Page Mode, Write Miss Following A Write	12.1.4
12-7		80386SX - Non-Page Mode 00 And Mode 01	12.1.5
	12-18	80386SX - Non-Page Mode 00 1 Wait State Read	12.1.5
	↓ 12-21	80386SX - Non-Page Mode 00 1 Wait State Read	12.1.5
12-8		CPU Initiated AT Bus Cycles	12.2.1
	12-22 ↑	AT Bus I/O Or Memory Read: 8-Bit, Default Timing	12.2.1
	12-31	AT Bus I/O Or Memory Write: 16-Bit, Default Timing	12.2.1
12-9	120.	Entering The AT Bus	12.2.2
	12-32	80286 CPU - Asysnchronous CPUCLK To SYSCLK, BREQ Delay = 1/2 Clock	12.2.2
	\$	5.124 5014 1/2 5155K	'
	12-37	80386SX CPU - Synchronous CPUCLK To SYSCLK	12.2.2
12-10		Exiting The AT Bus	12.2.3
	12-38	Synchronous AT Bus Cycle Completion, AT Bus Clock = 1/2 CPUCLK	12.2.3
	↑ 12-41	Asynchronous AT Bus Cycle Completion,	12.2.3
	12-41	BAK DEL = 0 Or +0.5 AT Bus Cycles	12.2.3
12-11		DMA Entering And Exiting The AT Bus	12.2.4
'- ''	12-42	Basic DMA Cycle, Default Timing	12.2.4
	12-43	DMA Cycle, 8-Bit I/O To On-board Memory	12.2.4
'	12-44	DMA Cycle, On-board Memory To 8-Bit I/O	12.2.4
12-12	.=	AT Bus Master Cycle	12.2.5
	12-45	AT Bus Master, Bus Acquisition/Release	12.2.5
	12-46	AT Bus Master, Write To On-board Memory	12.2.5
	12-47	AT Bus Master, Read From On-board Memory	12.2.5
12-13		AT Bus Refresh Cycle, Default Timing	12.2.5
	12-48	AT Bus Refresh Cycle, Default Timing	12.2.5

TABLE 12-1. TIMING FIGURE/TABLE NUMBERS

TABLE NUMBER	FIGURE NUMBER	TITLE	SECTION
12-14		80286 CPU TIMING	12.3
	12-49 ‡	80286 - CPURES AND NPRST DURING POWER UP	12.3
	12-54	80286 - MISCELLANEOUS TIMING	12.3
12-15		80386SX CPU TIMING	12.3
	12-55	80386SX - CPURES AND NPRST DURING POWER UP	12.3
	12-62	80386SX - OUTPUT DELAY TIMING	12.3

TABLE 12-1. TIMING FIGURE/TABLE NUMBERS cont.

SIGNAL	LOAD	SIGNAL	LOAD	SIGNAL	LOAD
CPURES W/R SDEN MXCTL2 - 0 LOMEG HOLD BUSYCPU CPUCLK CASL3 - 0 DPL IOR LA20 BALE	50 pF 50 pF 50 pF 50 pF 50 pF 50 pF 70 pF 75 pF 100 pF 200 pF 200 pF	NPRST ALE DT/R DACKEN SPKR INTRQ EPEREQ SYSCLK D15 - D0 RAS3 - RAS0 MEMW SA0 REFRESH	50 pF 50 pF 50 pF 50 pF 50 pF 50 pF 75 pF 100 pF 150 pF 200 pF 200 pF	BHE DEN1, DEN0 SDT/R CSEN READY NMI A23 - A0 CASH3 - Ō DPH IOW MEMR AEN RA10 - RA0	50 pF 50 pF 50 pF 50 pF 50 pF 50 pF 60 pF 75 pF 100 pF 200 pF 200 pF 200 pF 350 pF

TABLE 12-2. SIGNAL LOADING

12.1 MEMORY TIMING

Sections 12.1.1 through 12.1.5 present the memory timing for Page Mode and Non-Page Mode, for the 80286 and 80386SX processors.

Categories are grouped as follows:

80286

Page Mode Non-Page Mode 00 Non-Page Mode 01 80386SX

Page Mode

Non-Page Mode 00 and 01

Mnemonics used in the timing diagrams and tables are defined as:

TC - Command Cycle
TW - Wait State Cycle

TS - Status Cycle

WNRDRAM - Write Not Read DRAM (W/ \overline{R}

pin 119).

12.1.1 80286 Page Mode Timing

SYMBOL	CHARACTERISTIC	MAX 12.5 MHz	MAX 20 MHz
T220 T221	Processor address to RAM address valid, Page Hit CPUCLK fall to CAS fall, 2.5 CLK CAS	32 36	30 34
T222	CPUCLK rise to CAS rise	29	27
T223	CPUCLK rise to CAS fall, 2.0 CLK CAS	30	26
T224	Processor data to parity valid	25	22
T225 T226	CPUCLK fall to RAM address valid, Page Miss CPUCLK fall to WNRDRAM rise	39 34	36 31
T227	CPUCLK rise to RAS fall, first access	28	26
T228	CPUCLK fall to column address valid	44	41
T229	CPUCLK fall to WNRDRAM fall	34	31
T232	CPUCLK fall to RAS rise, Page Miss	29	27
T233	CPUCLK rise to RAS fall, Page Miss	28	26
T234 T235	CPUCLK rise to READY rise CPUCLK rise to READY fall	24 24	22
1233	OF OOLK 1186 to FILAD FIGH	27	_ ~~

TABLE 12-3. 80286 - PAGE MODE MEMORY TIMING

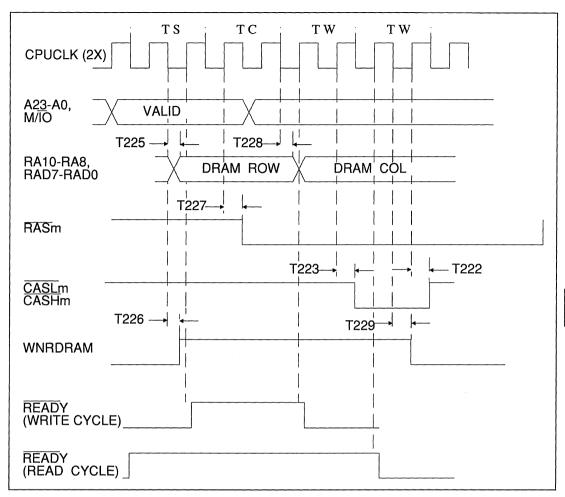


FIGURE 12-1. 80286 - PAGE MODE FIRST ACCESS READ/WRITE

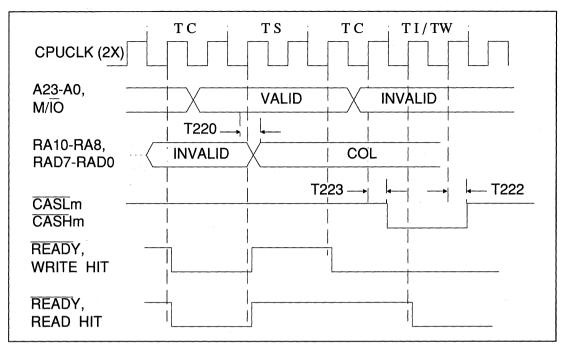


FIGURE 12-2, 80286 - PAGE MODE READ CYCLE AND PAGE HIT

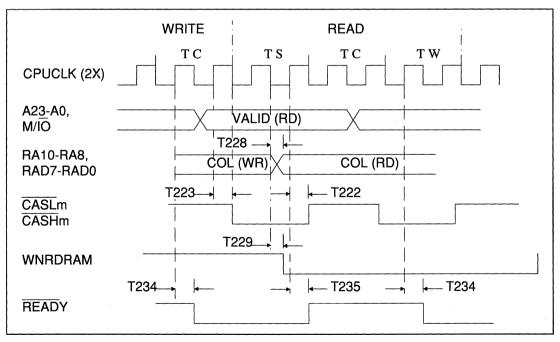


FIGURE 12-3. 80286 - PAGE MODE READ AFTER WRITE

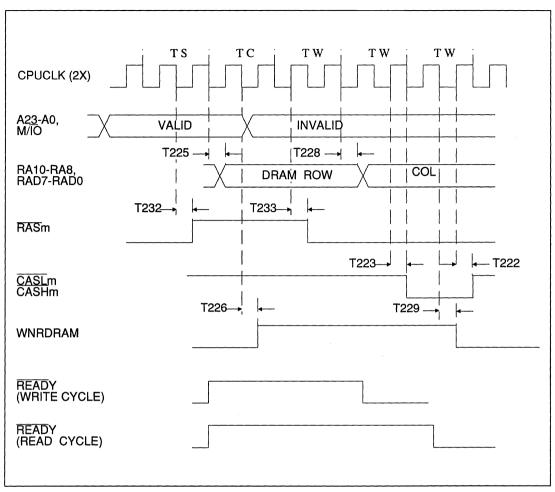


FIGURE 12-4. 80286 - PAGE MODE, PAGE MISS READ/WRITE

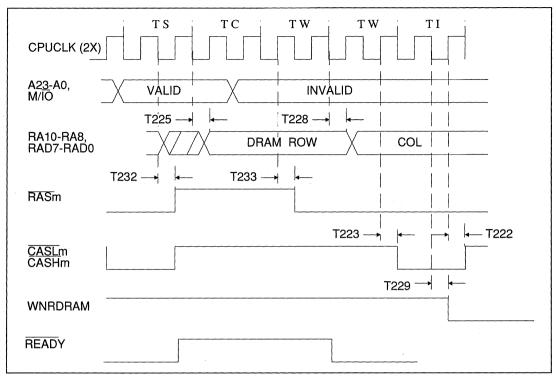


FIGURE 12-5. 80286 - PAGE MODE, WRITE MISS AFTER WRITE

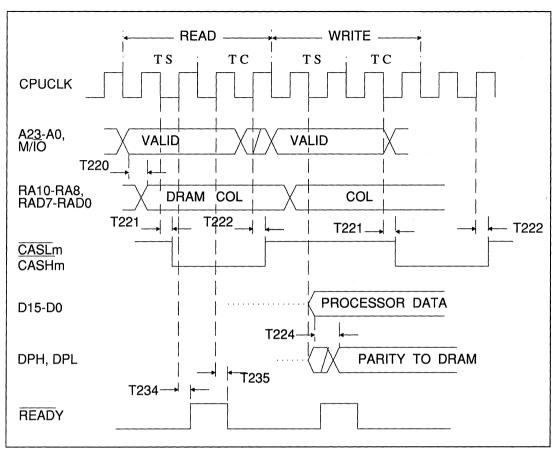


FIGURE 12-6, 80286 - PAGE MODE READ HIT AND WRITE HIT

12.1.2 80286 Non-Page Mode 00 Timing

SYMBOL	CHARACTERISTIC	MAX 12.5 MHz	MAX 20 MHz
T234 T235	See Table 13-3 See Table 13-3		
T252	CPUCLK fall to CAS rise	33	30
T255	CPUCLK fall to RAS fall	35	32
T270 T271	CPUCLK fall to <u>ROW</u> address CPUCLK fall to CAS fall	46 37	42 34
T273 T274	CPUCLK fall to WNRDRAM fall CPUCLK fall to WNRDRAM rise	33 33	31 31
T275 T276 T277	Data holding tristate. ① Clock fall to parity valid CPUCLK fall to RAS rise	12 30 30	12 27 28
T278 T279	CPUCLK fall to COLUMN address valid Processor address to ROW address	41 32	38 30
	Processor address to ROW address imes are not tested. Timing specifications are derived from sim		30

TABLE 12-4. 80286 - NON-PAGE MODE 00 MEMORY TIMING

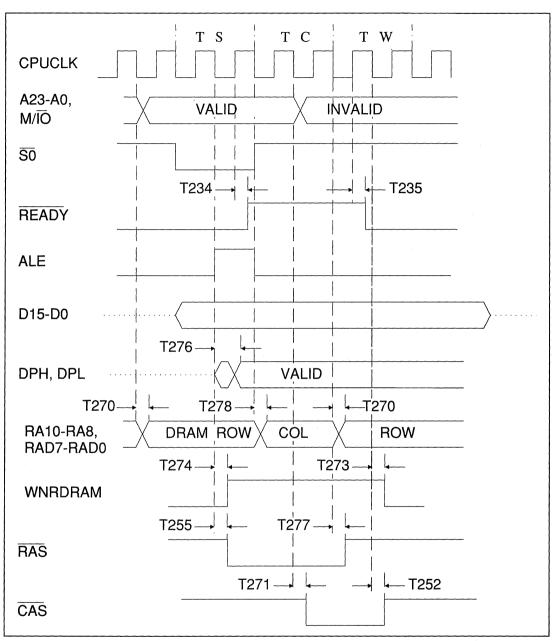


FIGURE 12-7. 80286 - NON-PAGE MODE 00, 1 WAIT STATE WRITE (4072H = 0001)

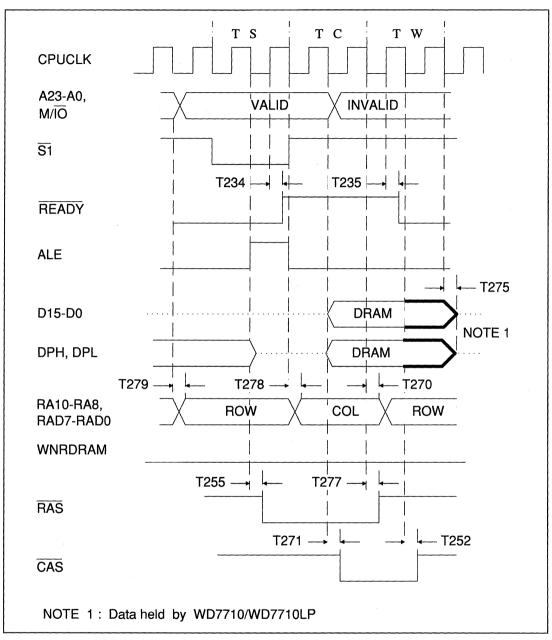


FIGURE 12-8. 80286 - NON-PAGE MODE 00, 1 WAIT STATE READ (4072H = 0001)

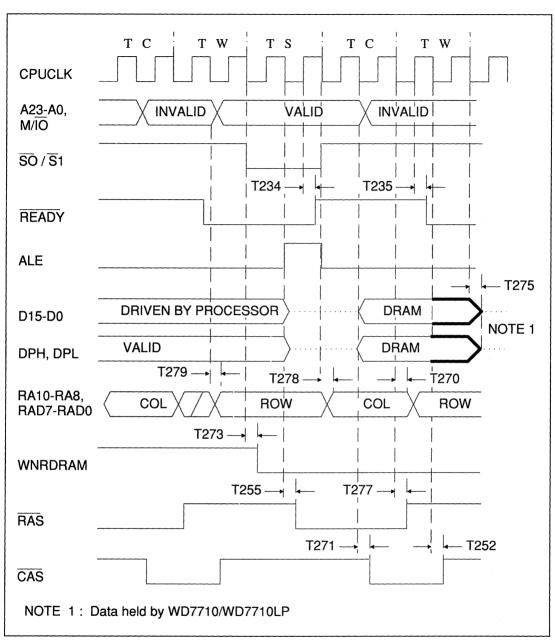


FIGURE 12-9. 80286 - NON-PAGE MODE MODE 00, 2 WAIT STATES READ AFTER WRITE (4072H = 0001)

12.1.3 80286 Non-Page Mode 01 Timing

SYMBOL	CHARACTERISTIC	MAX 12.5 MHz	MAX 20 MHz
T224	See Table 12-3		
T234 T235	See Table 12-3 See Table 12-3		
T252 T253 T254 T255	See Table 12-4 CPUCLK fall to WNRDRAM fall CPUCLK fall to WNRDRAM rise See Table 12-4	34 34	31 31
T257 T258	CPUCLK rise to RAS rise CPUCLK rise to COLUMN address valid	35 44	32 40
T276	See Table 12-4		

TABLE 12-5. 80286 - NON-PAGE MODE 01 MEMORY TIMING

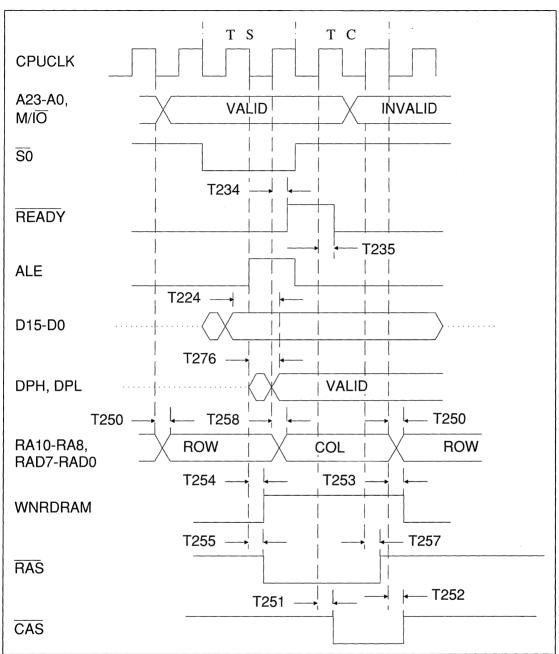


FIGURE 12-10. 80286 - NON-PAGE MODE 01, 0 WAIT STATE WRITE (4072H = 3560H)

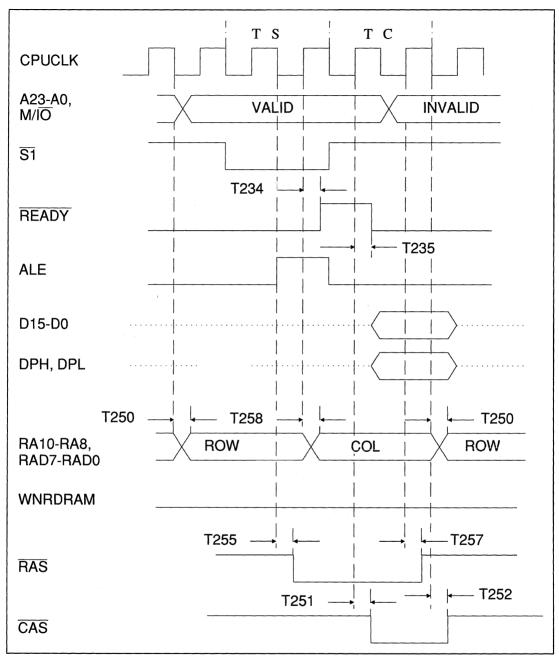


FIGURE 12-11. 80286 - NON-PAGE MODE 01, 0 WAIT STATE READ (4072H = 3560H)

12.1.4 80386SX Page Mode Timing

SYMBOL	CHARACTERISTIC	MAX 12.5 MHz	MAX 20 MHz	MAX 25 MHz
T200	Processor ADDRESS to RAM address valid, Page Hit		34	27
T201	CPUCLK rise to <u>CAS</u> fall, 2.5 CLK CAS		31	25
T202	CPUCLK fall to <u>CAS</u> rise		24	21
T203	CPUCLK fall to CAS fall, 2.0 CLK CAS		27	22
T204	Processor data to parity valid	1	25	20
T205	CPUCLK rise to RAM address valid, Page Miss	1	48	43
T206	CPUCLK rise to WNRDRAM rise		31	28
T207	CPUCLK fall to RAS fall, first access		27	21
T208	CPUCLK rise to COLUMN address valid		49	33
T209	CPUCLK rise to WNRDRAM fall		31	28
T212	CPUCLK rise to RAS rise, Page Miss		27	24
T213	CPUCLK fall to RAS fall, Page Miss		27	24
T214	CPUCLK rise to READY fall		19	18
T215	CPUCLK rise to READY rise	•	19	18

TABLE 12-6. 80386SX - PAGE MODE MEMORY TIMING

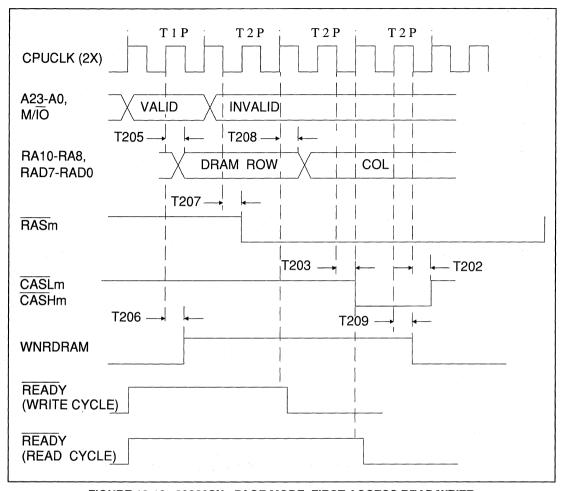


FIGURE 12-12. 80386SX - PAGE MODE, FIRST ACCESS READ/WRITE

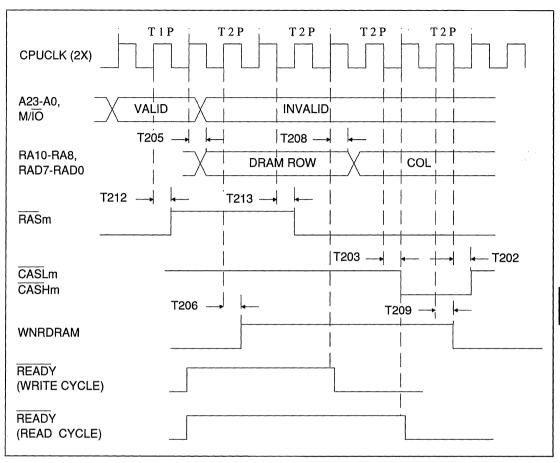


FIGURE 12-13. 80386SX - PAGE MODE, PAGE MISS READ/WRITE

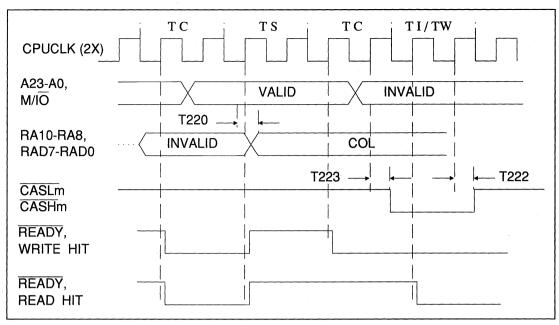


FIGURE 12-14. 80386SX - PAGE MODE, RAD CYCLE FOLLOWED BY A PAGE HIT

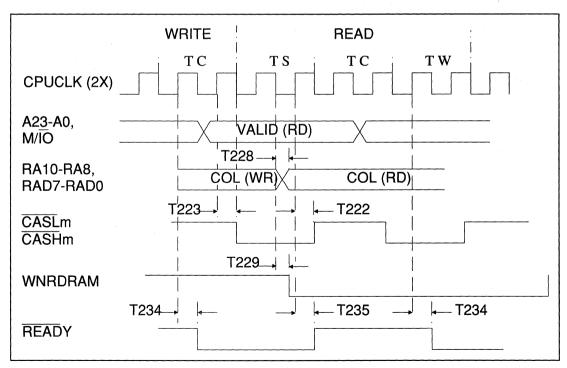


FIGURE 12-15. 80386SX - PAGE MODE, READ AFTER WRITE

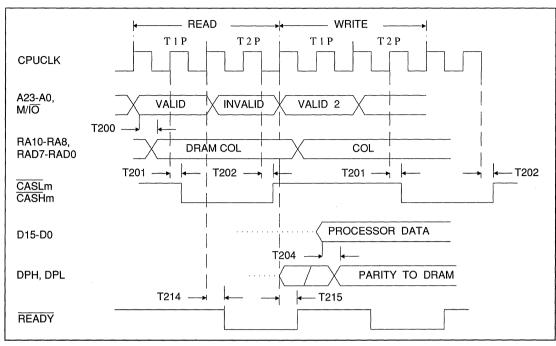


FIGURE 12-16. 80386SX - PAGE MODE, READ HIT FOLLOWED BY A WRITE HIT

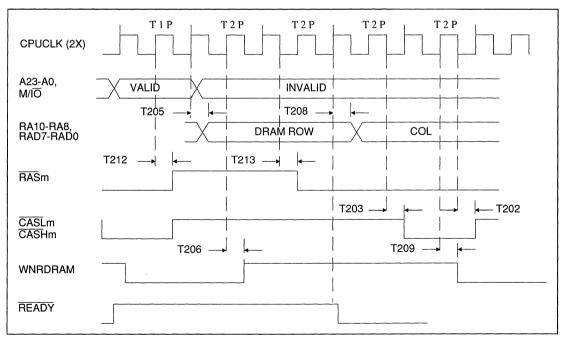


FIGURE 12-17. 80386SX - PAGE MODE, WRITE MISS CYCLE FOLLOWING A WRITE CYCLE

12.1.5 80386SX Non-Page Mode 00 and Mode 01 Timing

SYMBOL	CHARACTERISTIC	MAX 12.5 MHz	MAX 20 MHz	MAX 25 MHz
T204	See Table 12-6			
T214	See Table 12-6			
T215	See Table 12-6			
T240	CPUCLK rise to ROW address valid		42	42
T241	CPUCLK fall to CAS fall		27	27
T242	CPUCLK rise to CAS rise	1	28	24
T243	CPUCLK rise to WNRDRAM fall		28	28
T244	CPUCLK rise to WNRDRAM rise	1	28	28
T245	CPUCLK rise to RAS fall	1	25	23
T246	CPUCLK rise to RAS rise		25	23
T247	CPUCLK fall to RAS rise	1	29	29
T248	CPUCLK fall to COLUMN address valid		44	44
T249	CPUCLK rise to CAS fall		29	29
T260	CPUCLK rise to COLUMN address		43	41

TABLE 12-7. 80386SX - NON-PAGE MODE 00 & 01 MEMORY TIMING

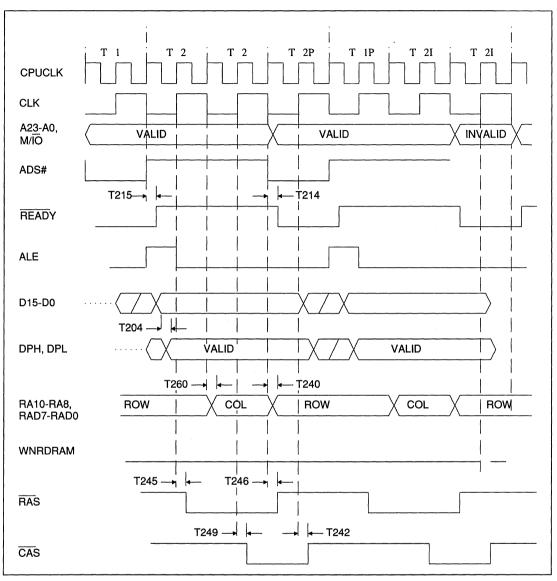


FIGURE 12-18. 80386SX - NON-PAGE MODE 00, 1 WAIT STATE READ (PIPELINE) (4072H = 0001)

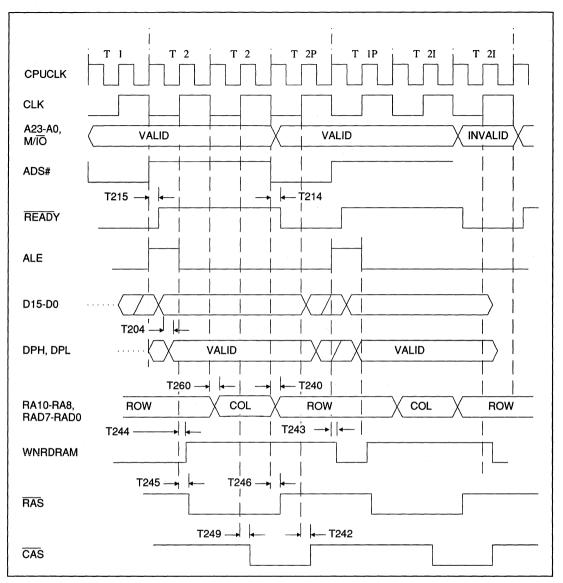


FIGURE 12-19. 80386SX - NON-PAGE MODE 00, 1 WAIT STATE WRITE (PIPELINE) (4072H = 0001)

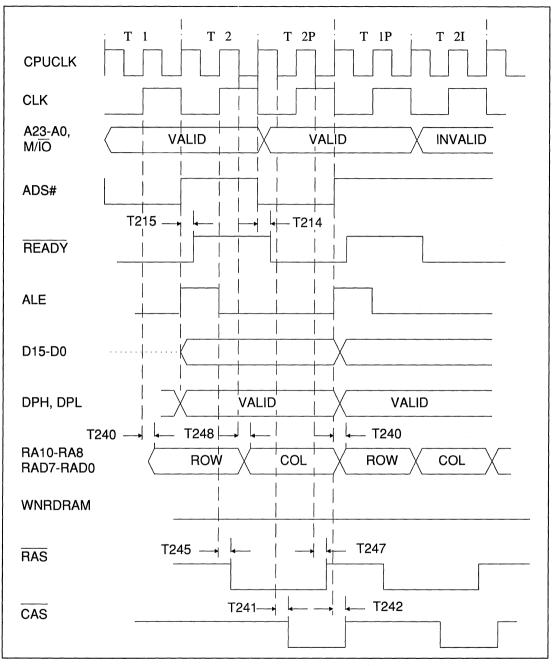


FIGURE 12-20. 80386SX - NON-PAGE MODE 01, 0 WAIT STATE READ (PIPELINE) (4072H = 3560H)

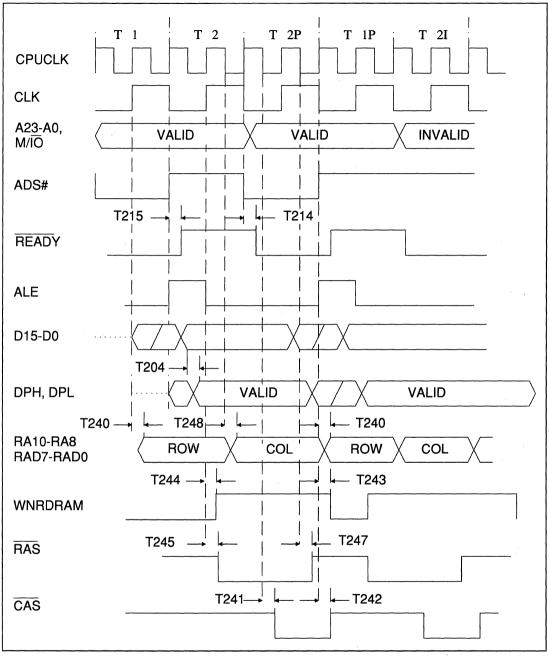


FIGURE 12-21. 80386SX - NON-PAGE MODE 01, 0 WAIT STATE READ (PIPELINE) (4072H = 3560H)

12.2 AT BUS TIMING

The AT Bus timing is divided into six major categories:

- 1. CPU initiated AT Bus cycles.
- 2. Entering the AT Bus.
- 3. Exiting the AT Bus.
- 4. DMA cycles.

- 5. AT Bus Master cycles.
- 6. AT Bus refresh cycle

Some figures in this section are included only to show the sequence of the signals during certain operations. In these figures, no timing parameters are provided.

12.2.1 CPU Initiated AT Bus Cycles

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T00	SYSCLK Cycle Time	100		ns	
T01	SYSCLK fall to BALE rise		12	ns	
T02	SYSCLK rise to BALE fall		9	ns	
Т03	SYSCLK fall to MEMR fall		9	ns	8-bit cycle
T04	SYSCLK rise to MEMR rise		6	ns	
T05	SYSCLK fall to IOR fall		10	ns	
T06	SYSCLK rise to IOR rise		7	ns	
Т07	SYSCLK rise to DEN0 fall		7	ns	Read Cycle
T08	SYSCLK rise to DEN0 rise		. 11	ns	Read Cycle
T09	SYSCLK rise to DEN1 fall		7	ns	Read Cycle
T10	SYSCLK rise to DEN1 rise		9	ns	Read Cycle
T11	SYSCLK fall to DTR fall	!	19	ns	Delay is number given plus $(T00 \times 0.25)$
T12	SYSCLK rise to DTR rise		14	ns	Delay is number given plus $(T00 \times 0.25)$
T13	SYSCLK fall to SDEN fall	i	10	ns	·
T14	SYSCLK rise to SDEN rise		8	ns	
T15	SYSCLK fall to SDTR rise	÷	14	ns	Delay is number given plus $(T00 \times 0.25)$
T16	SYSCLK rise to SDTR fall		11	ns	Delay is number given plus (T00 × 0.25)
T17	MEMCS16 setup time to SYSCLK rise	25	-	ns	
T18	MEMCS16 hold time from SYSCLK rise	0		ns	
T19	IOCS16 setup time to SYSCLK fall	23	·	ns	
T20	IOCS16 hold time from SYSCLK fall	0		ns	8-bit cycle

TABLE 12-8. CPU INITIATED AT BUS CYCLES

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T21	IOCHRDY setup time to SYSCLK rise	22		ns	
T22	IOCHRDY hold time from SYSCLK rise	0		ns	
T23	ZEROWS setup time to SYSCLK fall	24		ns	
T24	ZEROWS hold time from SYSCLK fall	0		ns	
T25	AT Bus data setup time to SYSCLK rise	22		ns	Total setup time is number given plus delay through AT Bus data buffers.
T26	AT Bus data hold time from SYSCLK rise	0		ns	
T27	SYSCLK fall to MEMW fall		9	ns	
T28	SYSCLK rise to MEMW rise		5	ns	
T29	SYSCLK fall to IOW fall		10	ns	
T30	SYSCLK rise to IOW rise		8	ns	l e
T31	SYSCLK fall to DEN0 fall		10	ns	Write cycle
T32	SYSCLK fall to DEN0 rise		9	ns	Write cycle
T33	SYSCLK fall to DEN1 fall		10	ns	Write cycle
T34	SYSCLK fall to DEN1 rise		9	ns	Write cycle
T35	SYSCLK fall to SDEN rise		11	ns	
T36	SYSCLK fall to SA0 rise		. 16	ns	Word to byte conversion cycle
T37	SYSCLK rise to MEMR fall		. 6	ns	16-bit cycle
T38	IOCS16 hold time from SYSCLK rise	0		ns	16-bit cycle
T39	SYSCLK high time	-4	0	ns	(T00 ÷ 2) plus number given

TABLE 12-8. CPU INITIATED BUS CYCLES cont.

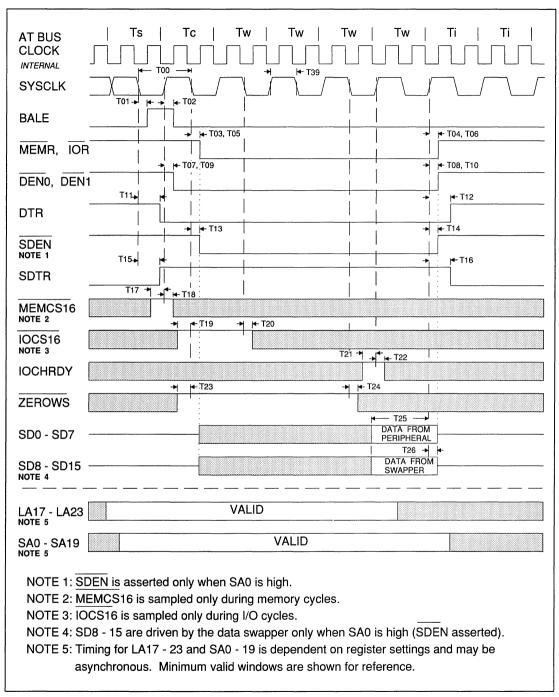


FIGURE 12-22. AT BUS I/O OR MEMORY READ: 8-BIT, DEFAULT TIMING

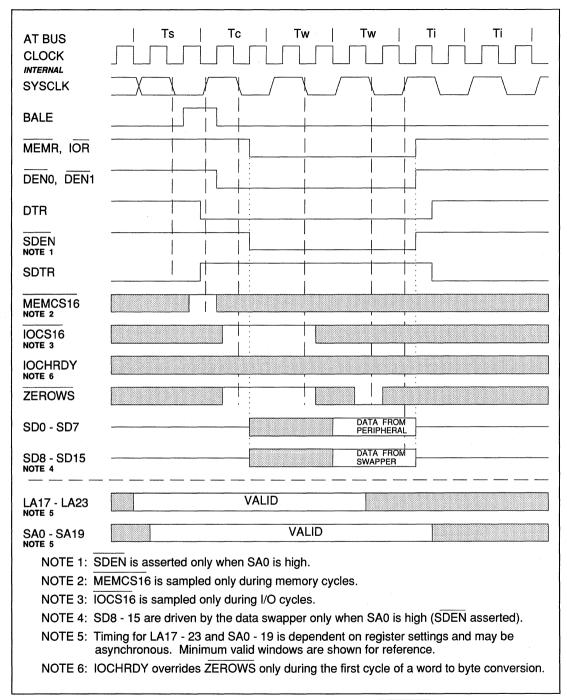


FIGURE 12-23. AT BUS I/O OR MEMORY READ: 8-BIT, ZEROWS ASSERTED

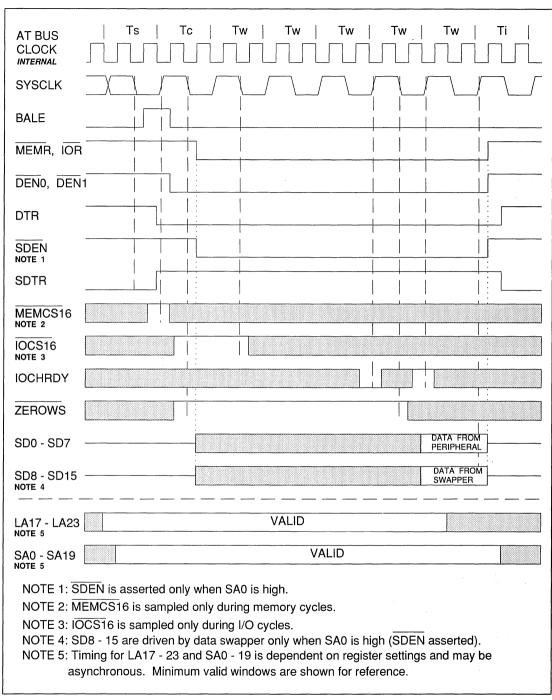


FIGURE 12-24. AT BUS I/O OR MEMORY READ: 8-BIT, EXTRA WAIT STATE ADDED

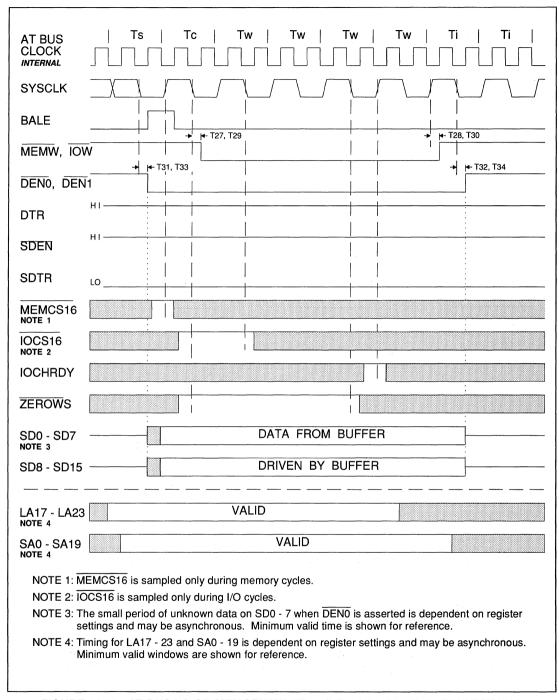


FIGURE 12-25. AT BUS I/O OR MEMORY WRITE: 8-BIT, EVEN BYTE, DEFAULT TIMING

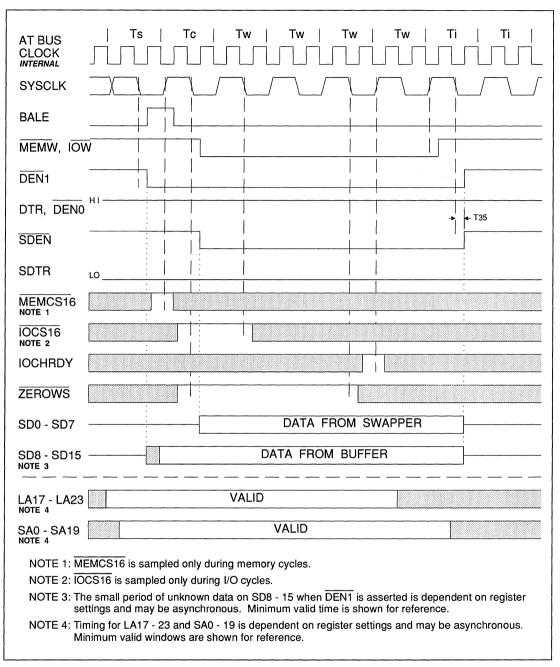


FIGURE 12-26. AT BUS I/O OR MEMORY WRITE: 8-BIT, ODD BYTE, DEFAULT TIMING

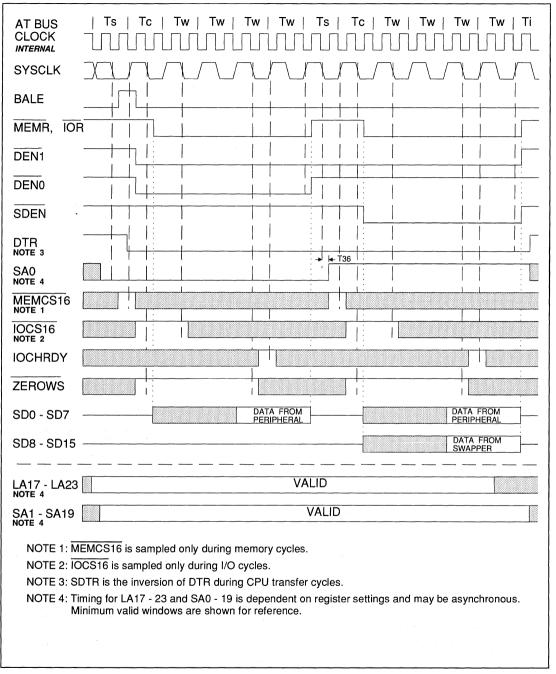


FIGURE 12-27. AT BUS I/O OR MEMORY READ: 8-BIT, WORD TO BYTE CONVERSION, DEFAULT TIMING

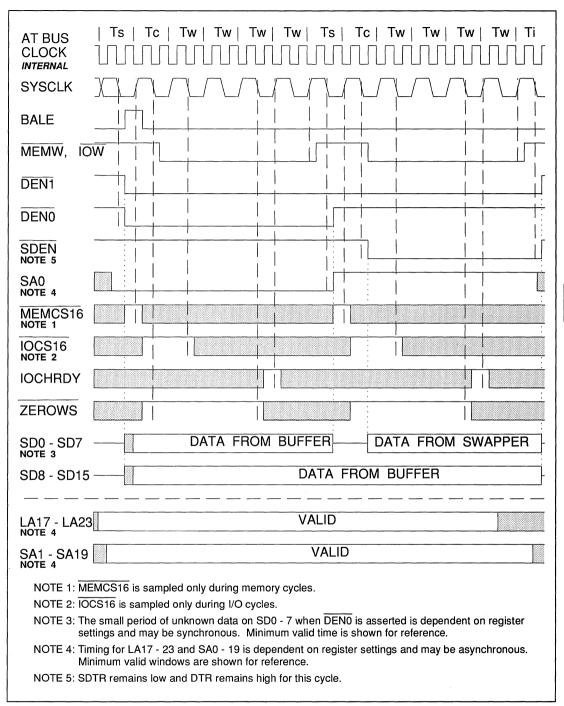


FIGURE 12-28. AT BUS I/O OR MEMORY WRITE: 8-BIT, WORD TO BYTE CONVERSION, DEFAULT TIMING

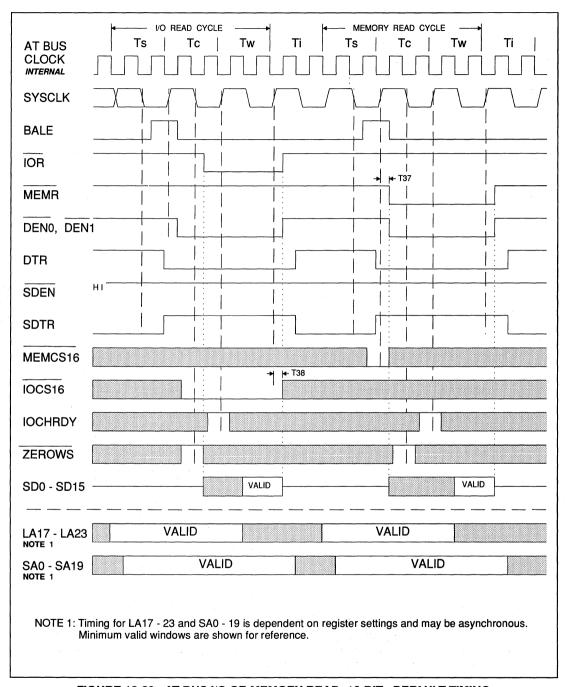


FIGURE 12-29. AT BUS I/O OR MEMORY READ: 16-BIT, DEFAULT TIMING

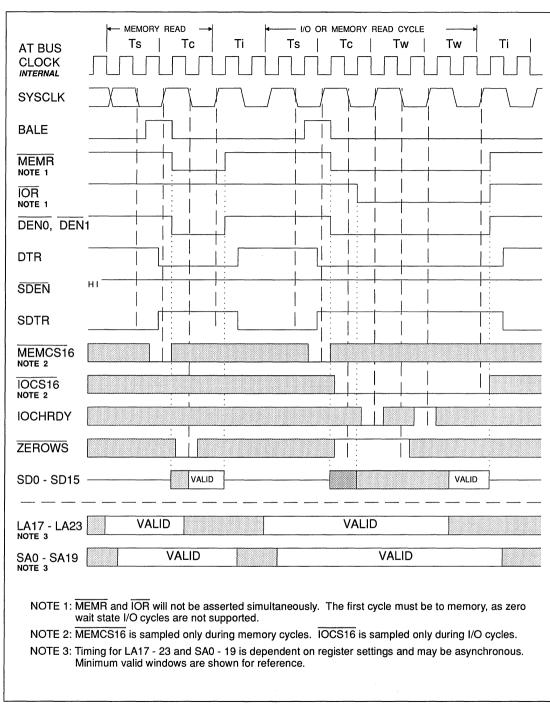


FIGURE 12-30. AT BUS I/O OR MEMORY READ: 16-BIT, 0WS ASSERTED AND EXTRA WAIT STATE ADDED

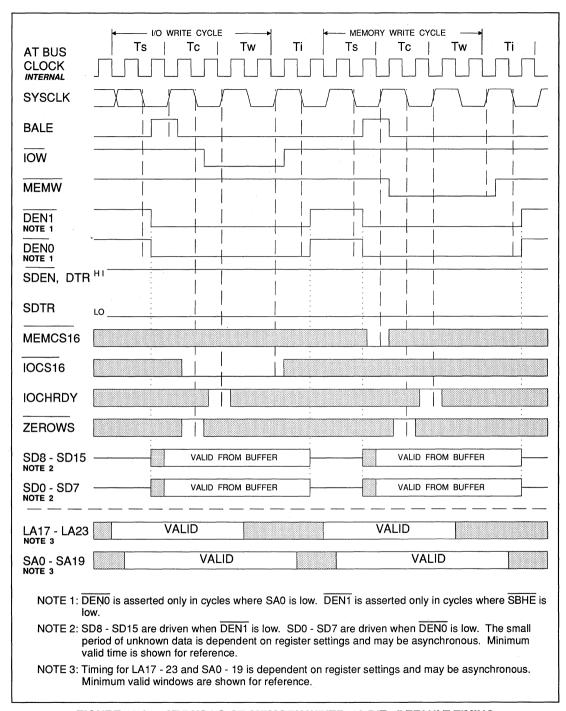


FIGURE 12-31. AT BUS I/O OR MEMORY WRITE: 16-BIT, DEFAULT TIMING

12.2.2 Entering the AT Bus

The timing in this section is presented in the following sequence:

80286 CPU

Asysnchronous CPUCLK to SYSCLK Synchronous CPUCLK to SYSCLK

80386SX CPU

Asysnchronous CPUCLK to SYSCLK Synchronous CPUCLK to SYSCLK

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T40	CPUCLK fall to SYSCLK fall 80286 CPU mode. CPUCLK rise to SYSCLK fall 80386SX CPU mode.	4		ns	Register 1872H: BRQ_DEL = 01 BUS_MOD = 0X Delay is number given plus (T00 × 0.25)
T41	CPUCLK fall to SYSCLK fall 80286 CPU mode. CPUCLK rise to SYSCLK fall 80386SX CPU mode.	9		ns	Register 1872H: BRQ_DEL = 00 BUS_MOD = 0X Delay is number given plus (T00 × 0.5)
T42	CPUCLK fall to SYSCLK fall 80386SX CPU mode.		29	ns	Register 1872H: BRQ_DEL = 10 BUS_MOD = 11
T43	CPUCLK rise to SYSCLK fall 80386SX CPU mode.		35	ns	Register 1872H: BRQ_DEL = 10 BUS_MOD = 10
T44	CPUCLK rise to SYSCLK fall 80286 CPU mode.		29	ns	Register 1872H: BRQ_DEL = 10 BUS_MOD = 11
T45	CPUCLK fall to SYSCLK fall 80286 CPU mode.		36	ns	Register 1872H: BRQ_DEL = 10 BUS_MOD = 10
T140	CPUCLK fall to ALE rise 80286 CPU mode. CPUCLK rise to ALE rise 80386SX CPU mode.		20	ns	
T141	CPUCLK fall to ALE fall 80286 CPU mode. CPUCLK rise to ALE fall 80386SX CPU mode.		20	ns	
T214	See TABLE 13-6				
T215	See TABLE 13-6				
T234 T235	See TABLE 13-3 See TABLE 13-3				

TABLE 12-9. ENTERING THE AT BUS

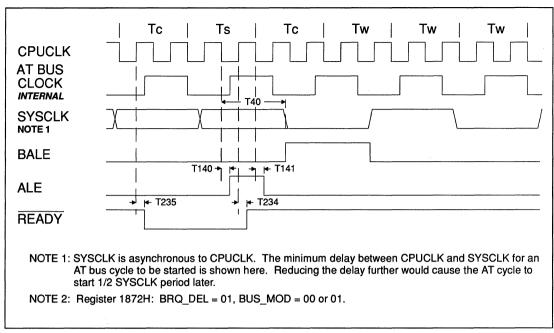


FIGURE 12-32. 80286 CPU - ASYNCHRONOUS CPUCLK TO SYSCLK, BREQ DELAY = 1/2 CLOCK

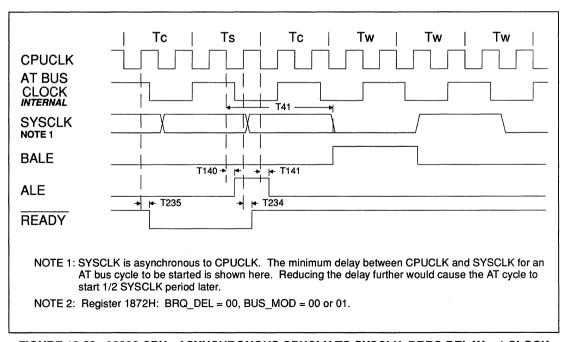


FIGURE 12-33. 80286 CPU - ASYNCHRONOUS CPUCLK TO SYSCLK, BREQ DELAY = 1 CLOCK

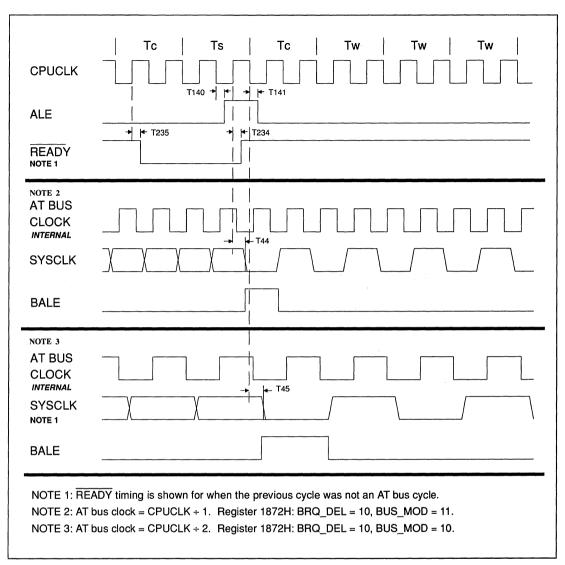


FIGURE 12-34. 80286 CPU - SYCNHRONOUS CPUCLK TO SYSCLK

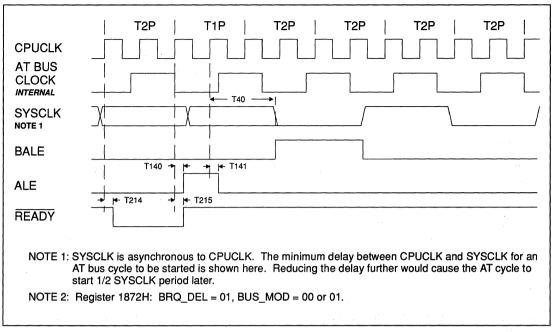


FIGURE 12-35. 80386SX CPU - BREQ DELAY = 1/2 CLOCK

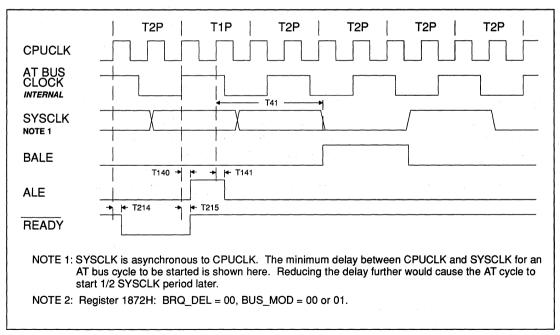


FIGURE 12-36, 80386SX - BREQ DELAY = 1 CLOCK

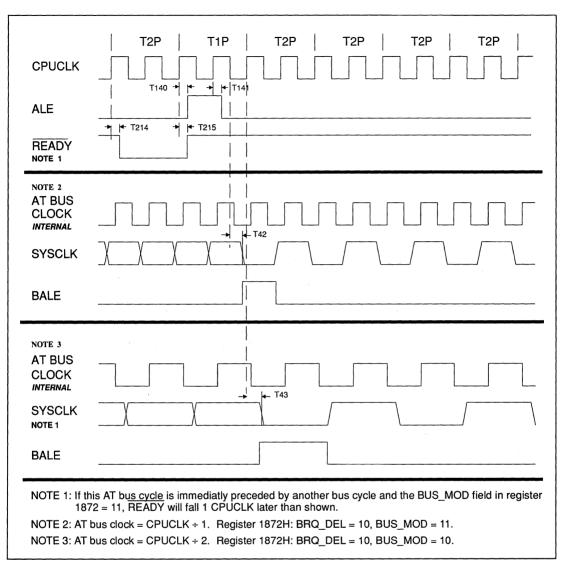


FIGURE 12-37. 80386SX CPU - SYCNHRONOUS CPUCLK TO SYSCLK

12.2.3 Exiting The AT Bus

Exiting a synchronous AT bus is covered first, followed by the asynchronous bus.

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T46	SYSCLK fall to CPUCLK	-5		ns	Register 1872H: BAK_DEL = 10 BUS_MOD = 0X
T47	SYSCLK fall to CPUCLK	-15		ns	Register 1872H: BAK_DEL = 01 BUS_MOD = 0X Delay is number given plus (T00 × 0.25)
T48	SYSCLK rise to CPUCLK	-10		ns	Register 1872H: BAK_DEL = 00 BUS_MOD = 0X
T49	SYSCLK rise to CPUCLK	-15		ns	Register 1872H: BAK_DEL = 11 BUS_MOD = 0X Delay is number given plus (T00 × 0.25)
T144	CPUCLK fall to READY fall, 80286 CPU mode.		24	ns	Register 1872H: BUS_MOD = 11 AT cycles only
T145	CPUCLK fall to READY rise, 80286 CPU mode.	·	26	ns	Register 1872H: BUS_MOD = 11 AT cycles only
T214	See TABLE 12-6				
T215	See TABLE 12-6				
T234	See TABLE 12-3				
T235	See TABLE 12-3				

TABLE 12-10. EXITING THE AT BUS

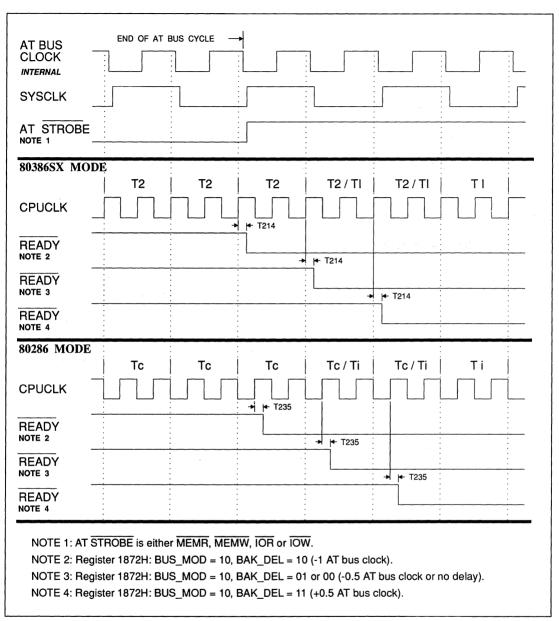


FIGURE 12-38. SYNCHRONOUS AT BUS CYCLE COMPLETION, AT BUS CLOCK = CPUCLK \div 2

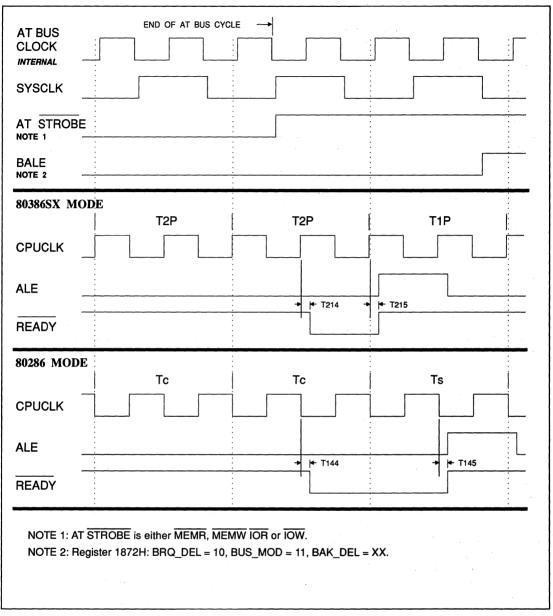


FIGURE 12-39. SYNCHRONOUS AT BUS CYCLE COMPLETION, AT BUS CLOCK = CPUCLK \div 1

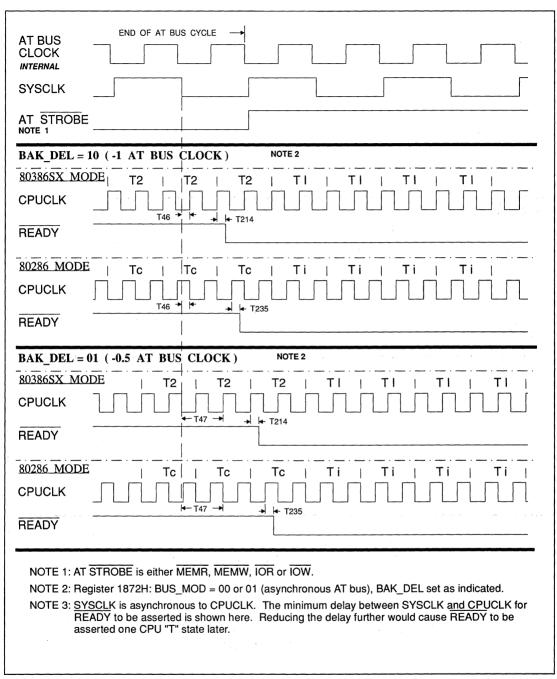


FIGURE 12-40. ASYNCHRONOUS AT BUS CYCLE COMPLETION, BAK DEL = -1 OR -0.5 AT BUS CLOCKS

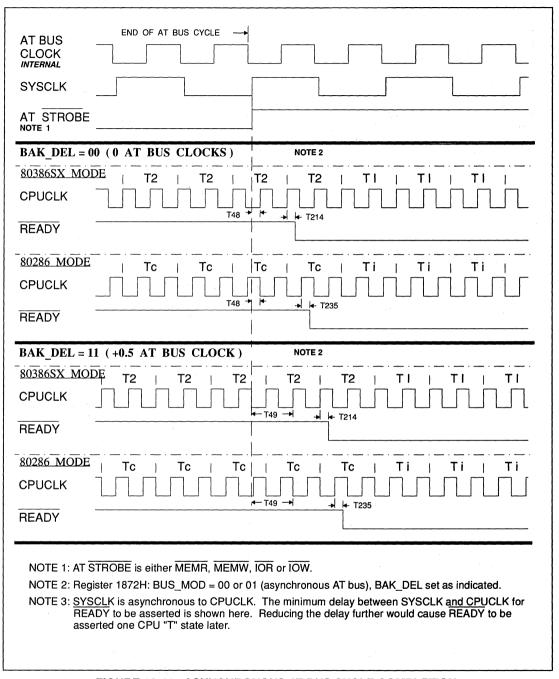


FIGURE 12-41. ASYNCHRONOUS AT BUS CYCLE COMPLETION, BAK_DEL = 0 OR +0.5 AT BUS CLOCKS

12.2.4 DMA Cycles

Basic default timing is covered first, followed by 8-bit I/O to onboard memory, then onboard memory to 8-bit I/O.

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T50	SYSCLK rise to ALE valid high		15	ns	
T51	SYSCLK rise to BALE valid high		15	ns	
T52	SYSCLK rise to AEN valid high		15	ns	
T53	SYSCLK rise to Address driven	0		ns	•
T54	SYSCLK rise to Address valid		60	ns	
T55	Address hold from SYSCLK rise	0		ns	:
T56	SYSCLK rise to LA20 valid		49	ns	
T57	LA20 hold from SYSCLK rise	0		ns	
T58	SYSCLK rise to SA0 valid		40	ns	
T59	SA0 hold from SYSCLK rise	0		ns	
T60	SYSCLK rise to BHE driven	0		ns	
T61	SYSCLK rise to BHE valid		36	ns	
T62	BHE hold from SYSCLK rise	0		ns	
T63	SYSCLK fall to MXCTL valid		2	ns	
T64	SYSCLK rise to DACKEN rise		28	ns	·
T65	SYSCLK rise to DACKEN fall		31	ns	
T66	SYSCLK rise to CSEN fall		32	ns	
T67	SYSCLK rise to CSEN rise		33	ns	
T68	IOCHRDY setup to SYSCLK rise	12		ns	
T69	IOCHRDY hold from SYSCLK rise	0		ns	
T70	SYSCLK rise to \overline{IOR} fall		28	ns	
T71	SYSCLK rise to IOR rise		35	ns	
T72	SYSCLK rise to MEMW fall		47	ns	
T73	SYSCLK rise to MEMW rise		35	ns	
T74	SYSCLK rise to DEN1 fall		32	ns	I/O to memory
T75	SYSCLK rise to DEN1 rise		42	ns	I/O to memory
T76	SYSCLK rise to DEN0 fall		32	ns	I/O to memory
T77	SYSCLK rise to DEN0 rise		42	ns	I/O to memory
T78	SYSCLK rise to SDEN fall		21	ns	
T79	SYSCLK rise to SDEN rise		37	ns	I/O to memory

TABLE 12-11. DMA CYCLES

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T80	SYSCLK rise to SDTR rise		30	ns	
T81	SYSCLK rise to SDTR fall		20	ns	
T82	SYSCLK rise to IOW fall		53	ns	
T83	SYSCLK rise to IOW rise		37	ns	
T84	SYSCLK rise to MEMR fall		17	ns	
T85	SYSCLK rise to MEMR rise		38	ns	
T86	SYSCLK rise to DEN1 fall	1	22	ns	Memory to I/O
T87	SYSCLK rise to DEN1 rise		116	ns	Memory to I/O
T88	SYSCLK rise to DEN0 fall		22	ns	Memory to I/O
T89	SYSCLK rise to DEN0 rise		116	ns	Memory to I/O
T90	SYSCLK rise to SDEN rise		116	ns	Memory to I/O
T91	SYSCLK rise to DTR rise		31	ns	
T92	SYSCLK rise to DTR fall		22	ns	
T100	MEMW fall to RASn fall		27	ns	
T101	MEMW rise to RASn rise		29	ns	
T102	MEMW fall to CASn fall		108	ns	and the second second
T103	MEMW rise to CASn rise		30	ns	
T105	MEMW fall to RA10 - RA0 valid		100	ns	
T107	MEMW fall to W/R high		29	ns	
T108	MEMW rise to W/R low	10		ns	
T120	MEMR fall to RASn fall		28	ns	
T121	MEMR rise to RAS rise		29	ns	
T122	MEMR fall to CASn fall		110	ns	
T123	MEMR rise to CAS rise	1	31	ns	
T125	MEMR fall to RA10 - RA0 valid		100	ns	
T126	MEMR fall to DPH, DPL float	1	25	113	
T127	MEMR rise to DPH, DPL	35	20	1000	Land of the Alexander
112/	driven				
Т303	D15 - D0 valid to DPH, DPL valid		27	ns	
T305	D15 - D0 setup to MEMR rise	18		ns	
T305	DPH, DPL setup to MEMR rise	10	1 2 2 2	ns	
1300	DI FI, DEL SEIUP IO MIEMIN TISE	10		119	

TABLE 12-11. DMA CYCLES cont.

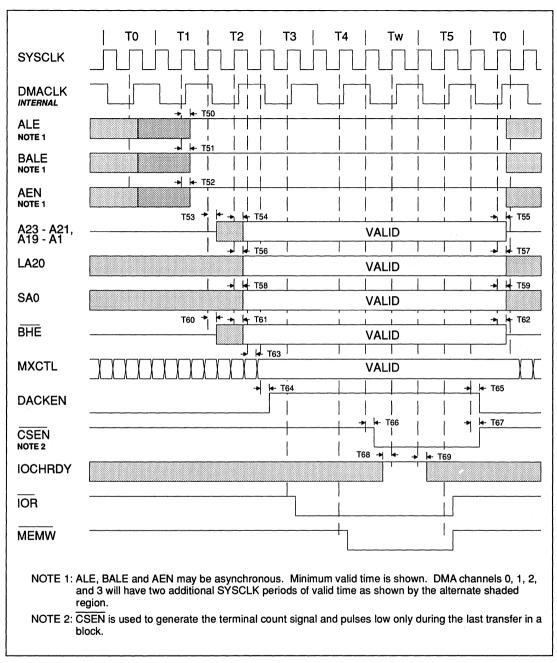


FIGURE 12-42. BASIC DMA CYCLE, DEFAULT TIMING

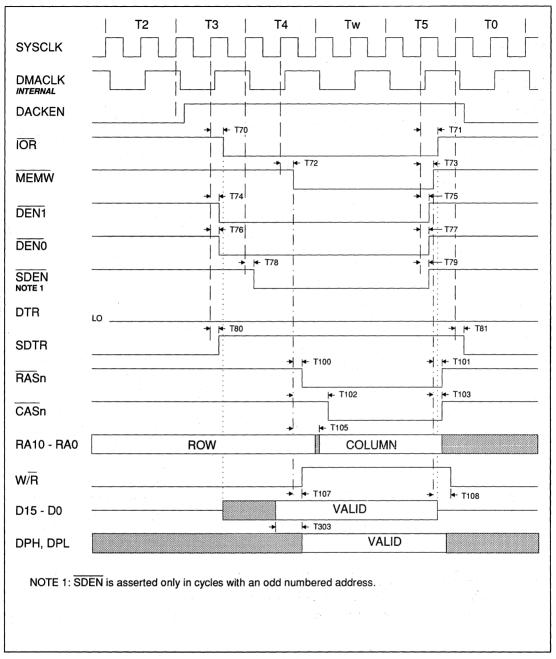


FIGURE 12-43. DMA CYCLE, 8-BIT I/O TO ON-BOARD MEMORY

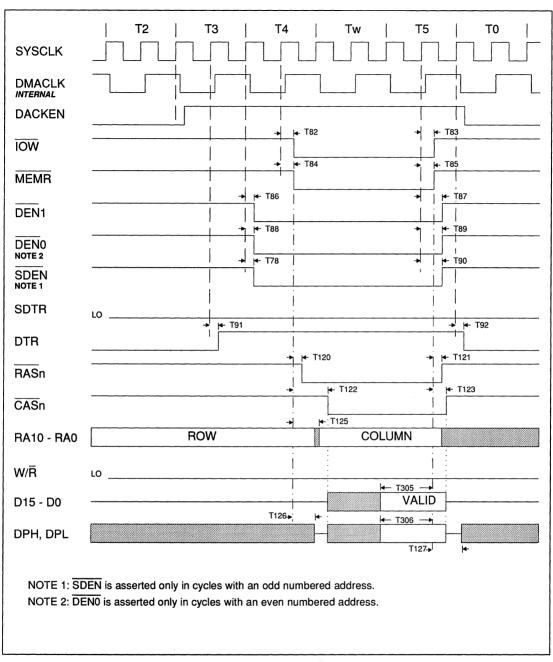


FIGURE 12-44. DMA CYCLE, ON-BOARD MEMORY TO 8-BIT I/O

12.2.5 AT Bus Master

The AT bus master timing is covered in the following sequence:

- Bus acquisition and release
- Writing to the onboard memoryReading from the onboard memory

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T50	SYSCLK rise to ALE valid high		15	ns	
T51	SYSCLK rise to BALE valid high		15	ns	
T52	SYSCLK rise to AEN valid high		15	ns	
T53	SYSCLK rise to Address driven	0		ns	
T55	Address hold from SYSCLK rise	0		ns	
T60	SYSCLK rise to BHE driven	0		ns	
T61	SYSCLK rise to BHE valid		36	ns	
T62	BHE hold from SYSCLK rise	0		ns	
T63	SYSCLK fall to MXCTL valid		2	ns	
T64	SYSCLK rise to DACKEN rise		28	ns	
T65	SYSCLK rise to DACKEN fall		31	ns	
T150	MASTER fall to AEN fall	·	30	ns	
T151	MASTER rise to AEN rise		30	ns	
T152	MASTER fall to A23 - A21, A19 - A1 float		30	ns	
T153	MASTER rise to A23 - A21, A19 - A1 driven	15		ns	
T154	MASTER fall to LA20 float		23	ns	
T155	MASTER rise to LA20 driven	10		ns	
T156	MASTER fall to SA0 float		24	ns	
T157	MASTER rise to SA0 driven	10		ns	·
T158	MASTER fall to BHE float		30	ns	
T159	MASTER rise to BHE driven	10		ns	
T160	MASTER fall to CSEN fall		32	ns	
T161	MASTER rise to CSEN rise		35	ns	
T162	MASTER fall to MEMR float		24	ns	
T163	MASTER rise to MEMR driven	10		ns	and the second s
T164	MASTER fall to MEMW, IOR, IOW, float		23	ns	
T165	MASTER rise to MEMW, IOR, IOW driven	10	Padral -	ns	

TABLE 12-12. AT BUS MASTER CYCLE

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T166	A2 <u>3 - A21, A19 - A</u> 1 setup to MEMR, MEMW	45		ns	
T167	LA20 setup to MEMR, MEMW	50		ns	
T168	BHE setup to MEMR, MEMW	0		ns	
T169	SA0 setup to MEMR, MEMW	0		ns	
T170	<u>A23 - A21, A19</u> - A1 hold from MEMR, MEMW	15		ns	
T171	LA20 hold from MEMR, MEMW	15		ns	
T172	BHE hold from MEMR, MEMW	15		ns	
T173	SA0 hold from MEMR, MEMW	15		ns	
T174	SA0 in to A0 out delay	1	45	ns	·
T175	MEMW fall to DEN1 fall	1	30	ns	
T176	MEMW fall to DEN0 fall	ł	30	ns	
T177	MEMW rise to DEN1 rise		83	ns	
T178	MEMW rise to DEN0 rise		83	ns	
T179	MEMR fall to DEN1 fall		85	ns	
T180	MEMR fall to DEN0 fall		85	ns	
T181	MEMR rise to DEN1 rise		32	ns	
T182	MEMR rise to DEN0 rise		32	ns	
T183	MEMR fall to DTR rise		29	ns	
T184	MEMR rise to DTR fall		82	ns	
T190	MEMR, MEMW fall to RASn fall		83	ns	
T191	MEMR, MEMW rise to RASn rise		33	ns	
T192	MEMR, MEMW fall to CASn fall		126	ns	
T193	MEMR, MEMW rise to CASn rise		33	ns	
T194	MEMR, MEMW fall to RA10 - RA0 column address valid		120	ns	
T196	MEMR, MEMW fall to RA10 - RA0 row address valid		42	ns	
T197	RA10 - R <u>A0 column addre</u> ss hold from MEMR, MEMW rise	5		ns	

TABLE 12-12. AT BUS MASTER CYCLE cont.

SYMBOL	CHARACTERISTIC	MIN	мах	UNITS	TEST CONDITIONS
T300	MEMW fall to W/R rise		33	ns	
T301	MEMW rise to W/R fall	10		ns	The second secon
T302	MEMW fall to DPH, DPL valid		32	ns	
T303	D15 - D0 valid to DPH, DPL valid		27	ns	
T304	DPH, DPL hold from MEMW rise	5		ns	
T305	D15 - D0 setup to MEMR rise	18		ns	
T306	DPH, DPL setup to MEMR rise	10		ns	
T307	MEMR fall to DPH, DPL float		35	ns	
T308	MEMR rise to DPH, DPL driven	58		ns	Asserting the second second

TABLE 12-12. AT BUS MASTER CYCLE cont.

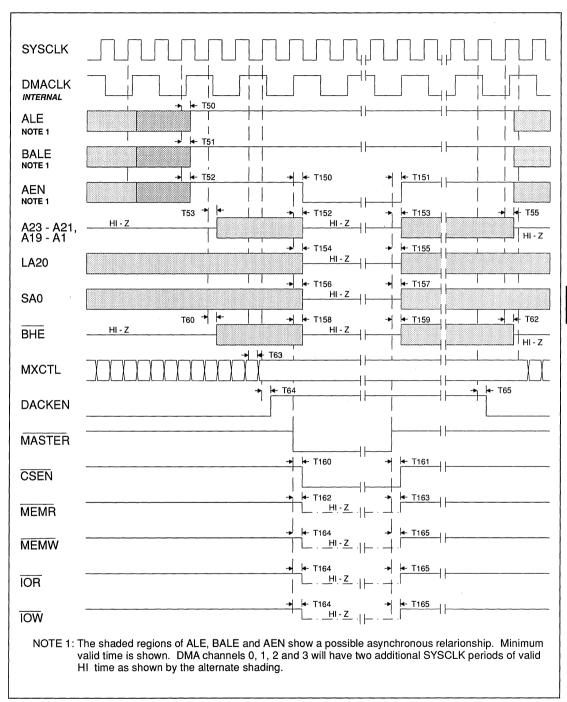


FIGURE 12-45. AT BUS MASTER, BUS ACQUISITION/RELEASE

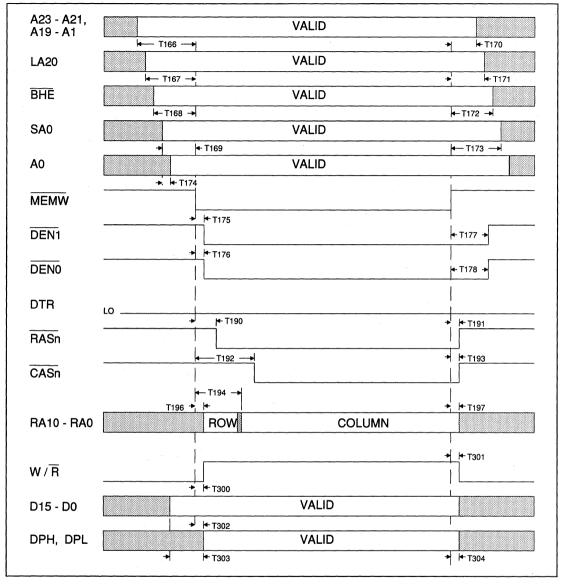


FIGURE 12-46. AT BUS MASTER, WRITE TO ON-BOARD MEMORY

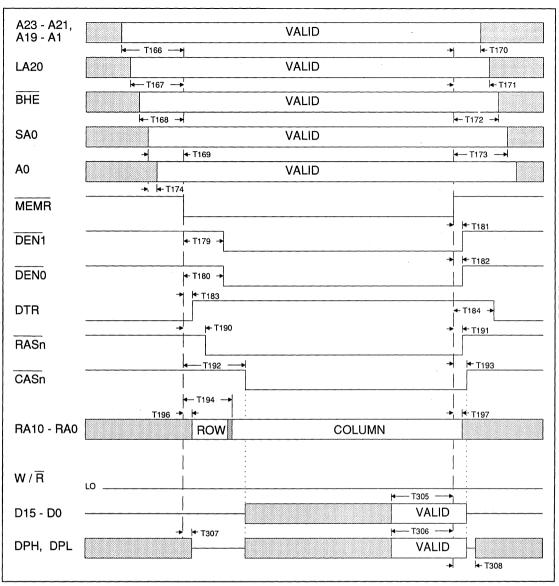


FIGURE 12-47. AT BUS MASTER, READ FROM ON-BOARD MEMORY

12.2.6 AT Bus Refresh

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T320	REFRESH low before SYSCLK rise	4		ns	REFRESH setup is number given plus (T00 × 0.25)
T321	SYSCLK fall to REFRESH rise		16	ns	
T325	SYSCLK rise to A23 - A21, A19 - A16 and A7 - A1 valid		35	ns	
T326	SYSCLK fall to A23 - A21, A19 - A16 and A7 - A1 invalid	2		ns	
T327	SYSCLK rise to A20, A15 - A8 valid		45	ns	
T328	SYSCLK fall to A20, A15 - A8 invalid	2		ns	
T329	SYSCLK rise to LA20 valid		30	ns	
T330	SYSCLK fall to LA20 invalid	2		ns	
T331	SYSCLK rise to SA0 valid		30	ns	
T332	SYSCLK fall to SA0 invalid	2		ns	
T333	SYSCLK rise to MEMR low		8	ns	
T334	SYSCLK rise to MEMR high		7	ns	
T335	IOCHRDY setup to SYSCLK rise	23		ns	
T336	IOCHRDY hold time from SYSCLK rise	0		ns	

TABLE 12-13. AT BUS REFRESH CYCLE, DEFAULT TIMING

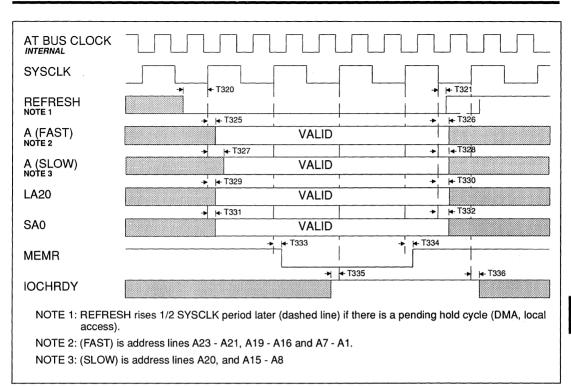


FIGURE 12-48. AT BUS REFRESH CYCLE, DEFAULT TIMING

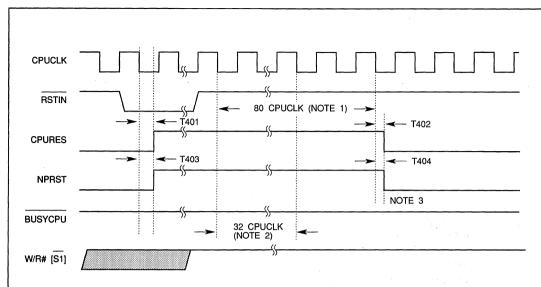
12.3 PROCESSOR TIMING

This section covers the 80286 CPU timing, followed by the 80386SX.

SYMBOL	CHARACTERISTIC	MIN	MAX	UNITS	TEST CONDITIONS
T140	See Table 12-9				
T141	See Table 12-9	}			
T143	See Table 12-9				
T401	CPUCLK fall to CPURES rise delay		14	ns	
T402	CPUCLK fall to CPURES fall delay		13	ns	
T403	CPUCLK fall to NPRST rise delay		14	ns	
T404	CPUCLK fall to NPRST fall delay		13	ns	
T405	CPUCLK fall to BUSYCPU fall delay		35	ns	•
T406	NPBUSY rise to BUSYCPU rise delay		35	ns	•
T408	SO, S1 setup time to CPUCLK	9		ns	
T409	SO, S1 hold time to CPUCLK	1		ns	
T410	M/IO setup time to CPUCLK	26		ns	
T411	M/IO hold time to CPUCLK	1		ns	
T412	Address setup time to CPUCLK	26		ns	• '
T413	Address hold time to CPUCLK	1		ns	
T414	PEACK setup time to CPUCLK	7		ns	
T415	PEACK hold time to CPUCLK	1		ns	
T416	DPH, DPL setup time to CPUCLK fall	5		ns	
T417	DPH, DPL hold time from CPUCLK fall	19		ns	
T418	D15 - D0 setup time to CPUCLK fall	5		ns	
T419	D15 - D0 hold time from CPUCLK fall	19		ns	

① T405 and T406 are for reference only since BUSYCPU is an asynchronous signal to the 80286. These two parameters are guaranteed by design and will not be tested.

TABLE 12-14. 80286 CPU TIMING



NOTE 1: Minimum of 80 CPUCLKs are asserted before the removal of CPURES.

NOTE 2: W/R# [S1] is sampled 32 CPUCLKs after RSTIN is de-asserted to determine the processor type.

NOTE 3: If, by sampling W/R# [S1], the processor type detected is an 80386SX, BUSYCPU is asserted for a minimum of 10 CPUCLKs before and after the trailing edge of CPURES to perform 80386SX self test.

FIGURE 12-49. 80286 - CPURES AND NPRST DURING POWER UP

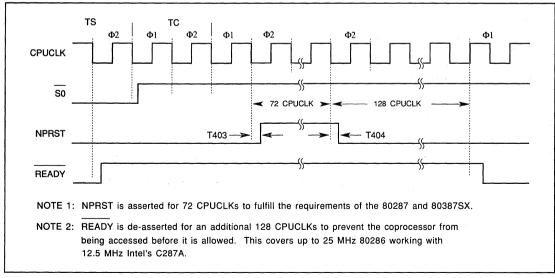


FIGURE 12-50. 80286 - COPROCESSOR RESET (NPRST)
INITIATED BY IOW TO PORT F1

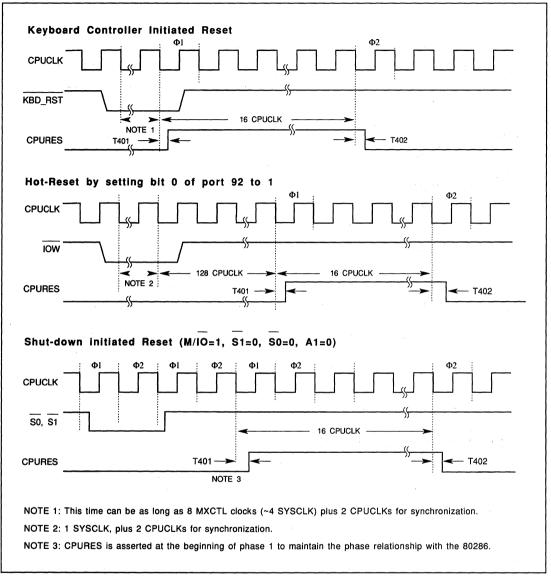


FIGURE 12-51. 80286 - PROCESSOR RESET (CPURES) INITIATED BY SOURCES OTHER THAN POWER UP RESET

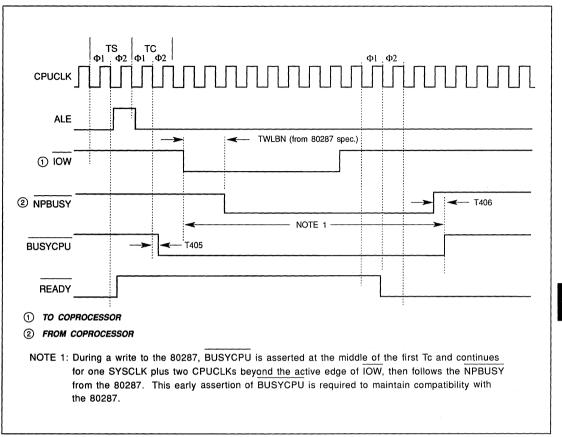


FIGURE 12-52. 80286 - BUSYCPU ASSERTED DURING COPROCESSOR ACCESS

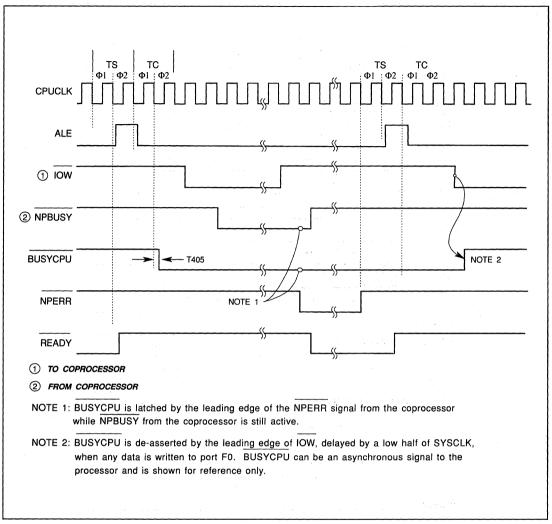


FIGURE 12-53. 80286 - LATCHING BUSYCPU WHEN AN ERROR OCCURS AND CLEARING IT WITH A WRITE TO PORT FO

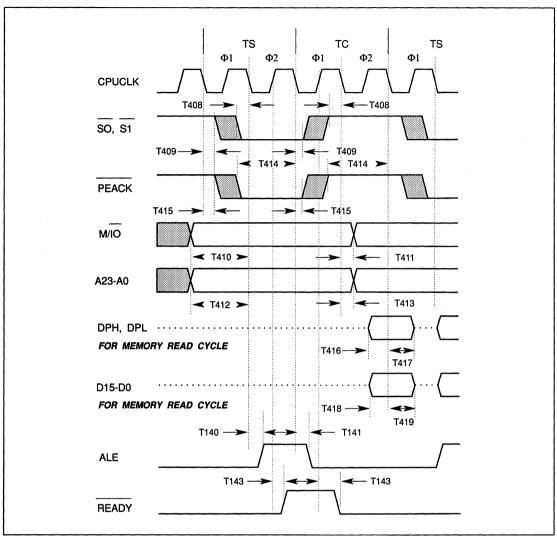


FIGURE 12-54. 80286 - MISCELLANEOUS TIMING

SYMBOL	CHARACTERISTIC	20 MHz		25 MHz		LIMITO	
		MIN	MAX	MIN	MAX	UNITS	
T140	See Table 12-9						
T141	See Table 12-9						
T204	See Table 12-6				1		
T214	See Table 12-6	İ					
T215	See Table 12-6						
T451	CPUCLK rise to CPURES rise delay		14		10	, ns	
T452	CPUCLK rise to CPURES fall delay		13		10	ns	
T453	CPUCLK rise to NPRST rise delay		14		10	ns	
T454	CPUCLK rise to NPRST fall delay		13		10	ns	
T455	CPUCLK rise to BUSYCPU fall delay		35		35	ns	
T456	CPUCLK rise to BUSYCPU rise delay		35		30	ns	
T457	NPBUSY fall to BUSYCPU fall delay		30		30	ns	
T458	NPBUSY rise to BUSYCPU rise delay	and the	35		35	ns	
T460	NPERR fall to EPEREQ rise delay		30		30	ns	
T462	ADS# setup time to CPUCLK rise	14		10		ns	
T463	ADS# hold time from CPUCLK rise	5		4		ns	
T464	W/R# setup time to CPUCLK rise	14		8		ns	
T465	W/R# hold time from CPUCLK rise	5		4		ns	
T466	D/C# setup time to CPUCLK rise	14		6		ns	
T467	D/C# hold time from CPUCLK rise	5		4	}	ns	
T468	M/IO setup time to CPUCLK rise	17		15		ns	
T469	M/IO hold time from CPUCLK rise	5		4	į	ns	
T470	BHE setup time to CPUCLK rise	17		15		ns	
T471	BHE hold time from CPUCLK rise	3		4		ns	
				L	<u> </u>		

TABLE 12-15. 80386SX CPU TIMING

SYMBOL	CHARACTERISTIC	20 MHz MIN MAX		25 MHz MIN MAX		UNITS	
T472	HLDA setup time to CPUCLK rise	10		6		ns	
T473	HLDA hold time from CPUCLK rise	3		4		ns	
T474	HOLD valid delay from CPUCLK rise		26		20	ns	
T475	DPH setup time to CPUCLK rise	5		5		ns	
T476	DPH hold time from CPUCLK rise	19		19		ns	
T477	D15-D0 setup time to CPUCLK rise	5		5		ns	
T478	D15-D0 hold time from CPUCLK rise	19		19		ns	
T479	A23-A1, BLE# setup time to CPUCLK rise	40		38		ns	
T480	A23-A1, BLE# hold time from CPUCLK rise	3		4		ns	

TABLE 12-15. 80386SX CPU TIMING cont.

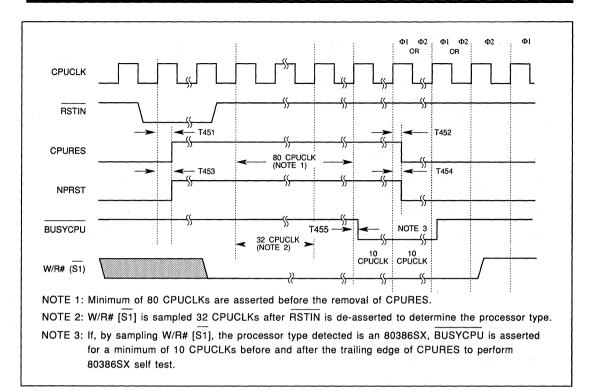


FIGURE 12-55. 80386SX - CPURES AND NPRST DURING POWER UP

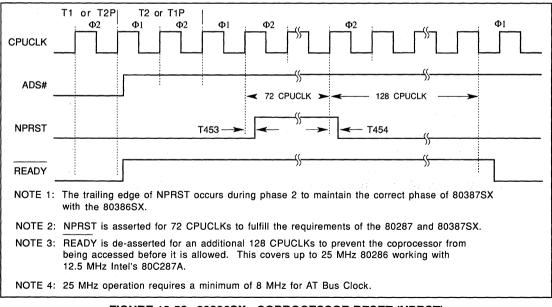


FIGURE 12-56. 80386SX - COPROCESSOR RESET (NPRST)
INITIATED BY IOW TO PORT F1

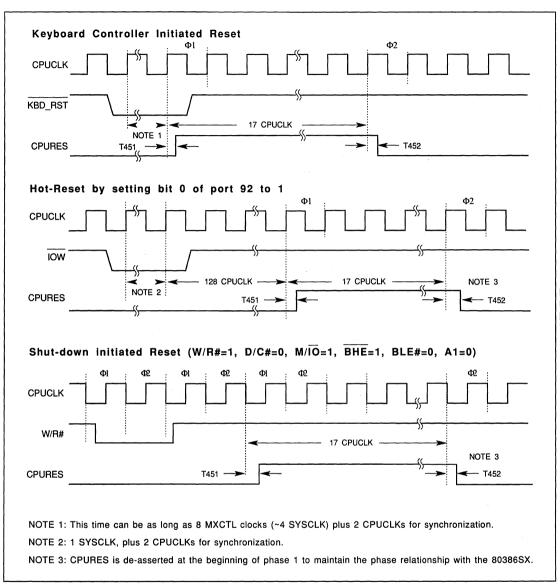


FIGURE 12-57. 80386SX - PROCESSOR RESET (CPURES) INITIATED BY SOURCES OTHER THAN POWER UP RESET

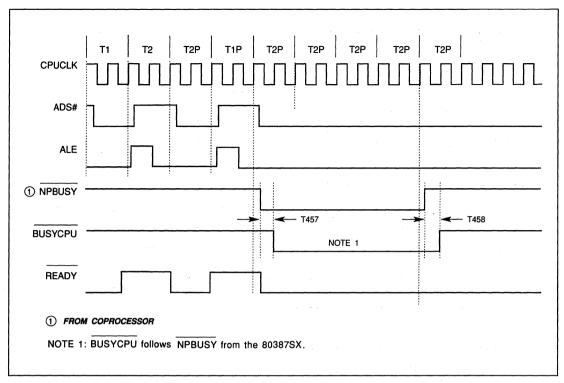


FIGURE 12-58, BUSYCPU ASSERTION DURING COPROCESSOR ACCESS

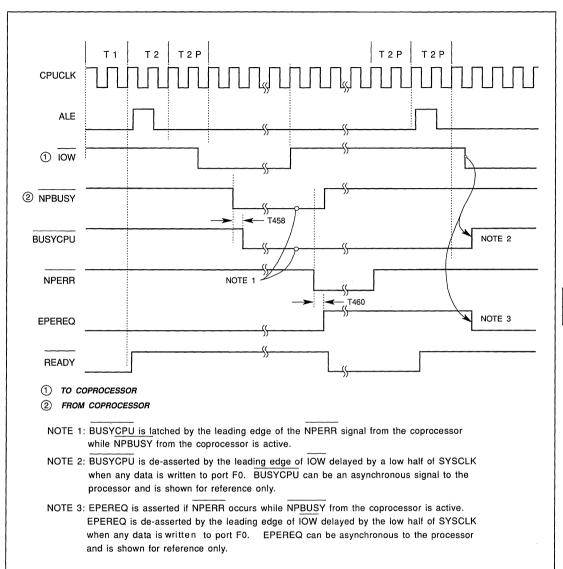


FIGURE 12-59. 80386SX - LATCHING BUSYCPU WHEN AN ERROR OCCURS AND CLEARING IT WITH A WRITE TO PORT F0

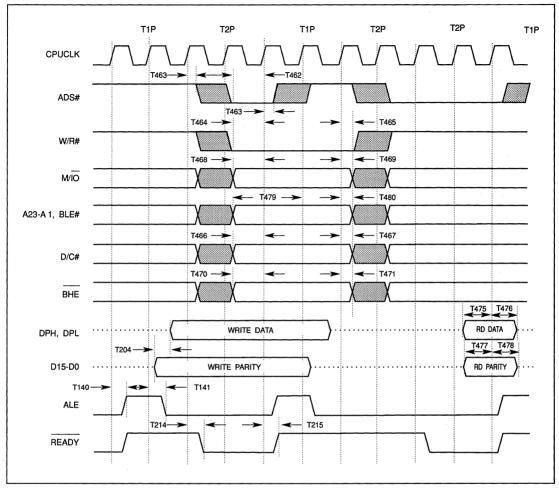


FIGURE 12-60. 80386SX - MISCELLANEOUS TIMING

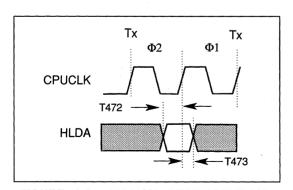


FIGURE 12-61. 80386SX - INPUT SETUP AND HOLD TIMING

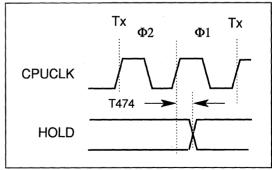


FIGURE 12-62. 80386SX - OUTPUT DELAY TIMING

12.4 CACHE CONTROLLER TIMING

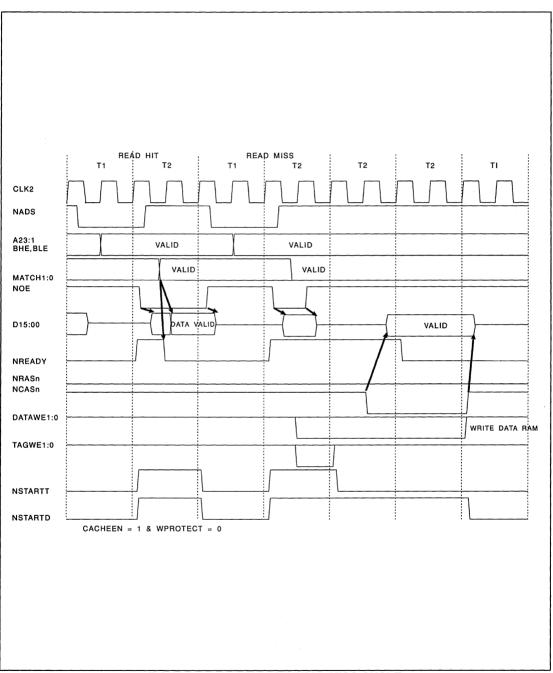


FIGURE 12-63, READ HIT/READ MISS CYCLE

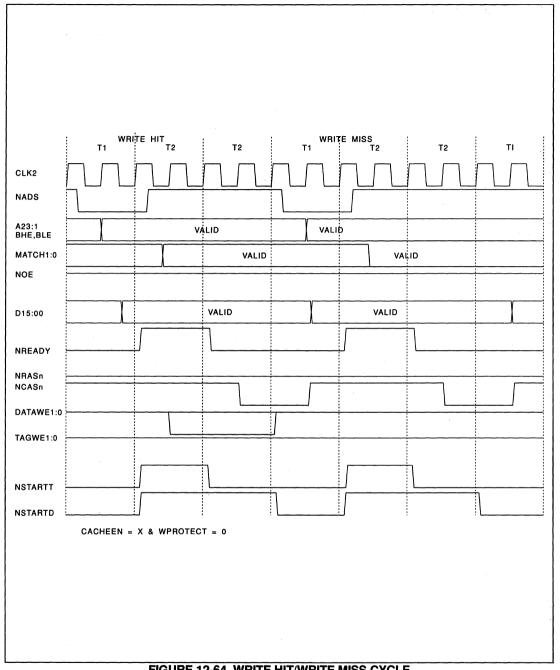


FIGURE 12-64. WRITE HIT/WRITE MISS CYCLE

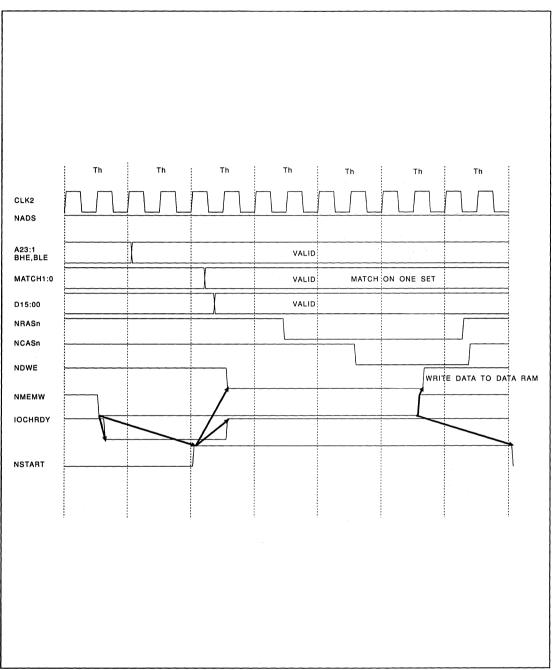


FIGURE 12-65. DMA/MASTERMEMORY WRITE HIT CYCLE

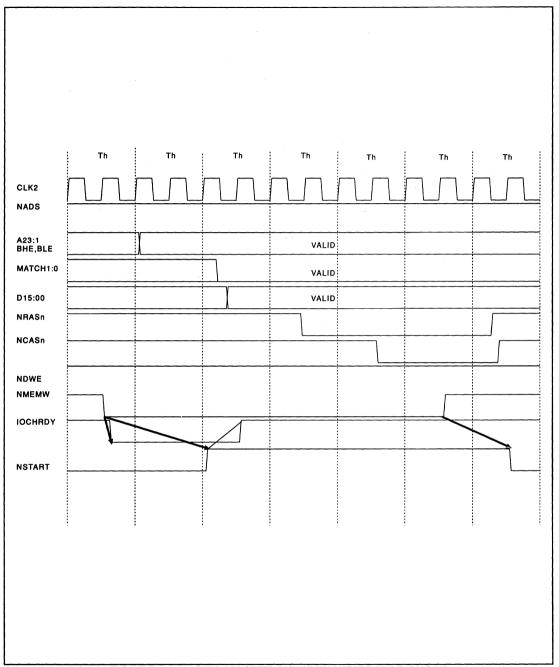


FIGURE 12-66. DMA/MASTER MEMORY WRITE MISS CYCLE

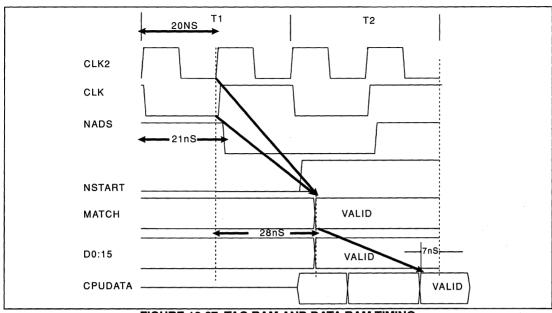


FIGURE 12-67. TAG RAM AND DATA RAM TIMING